

## General Information

### Mission Information

Project name	200929_B_5060420_nad2011_FINAL
Processing date	2020-10-07 13:23:54
Mission date	2020-09-29 14:22:23
Mission duration	05:35:11.000
Processing mode	IN-Fusion PP-RTX

### Rover Hardware Information

Product	POS AV 610 VER6 HW2.5-12
Serial number	S/N9825
IMU type	57
Receiver type	BD982
Antenna type	AV39

## Project File List

### Rover Data Files

File name	File type
survey3.pos	POS Data

### Input Files

File Name	File Type
Ephm2730.20g	GLONASS Broadcast Ephemeris
Ephm2730.20n	GPS Broadcast Ephemeris

### Output Files

Filename	File type
sbt_200929_B_5060420_nad2011_FINAL.out	SBET Trajectory File

## Rover Data Summary

First raw data file	survey3.pos		
Last raw data file	survey3.pos		
Start GPS week	2125		
Start time	224543.043 (9/29/2020 2:22:23 PM)		
End time	244647.922 (9/29/2020 7:57:27 PM)		
Start of fine alignment	224902.097 (9/29/2020 2:28:22 PM)		
Available subsystems	Primary GNSS, IMU		
POS Event Input	None		
Correction data	None		
<b>IMU Installation Lever Arms &amp; Mounting Angles</b>			
Reference to IMU lever arm (m)	0.000	0.000	0.000
Reference to IMU mounting angles (deg)	0.000	0.000	-90.000
Reference to Primary GNSS lever arm (m)	0.527	0.205	-1.192
Reference to Primary GNSS lever arm std dev (m)	-1.000		
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

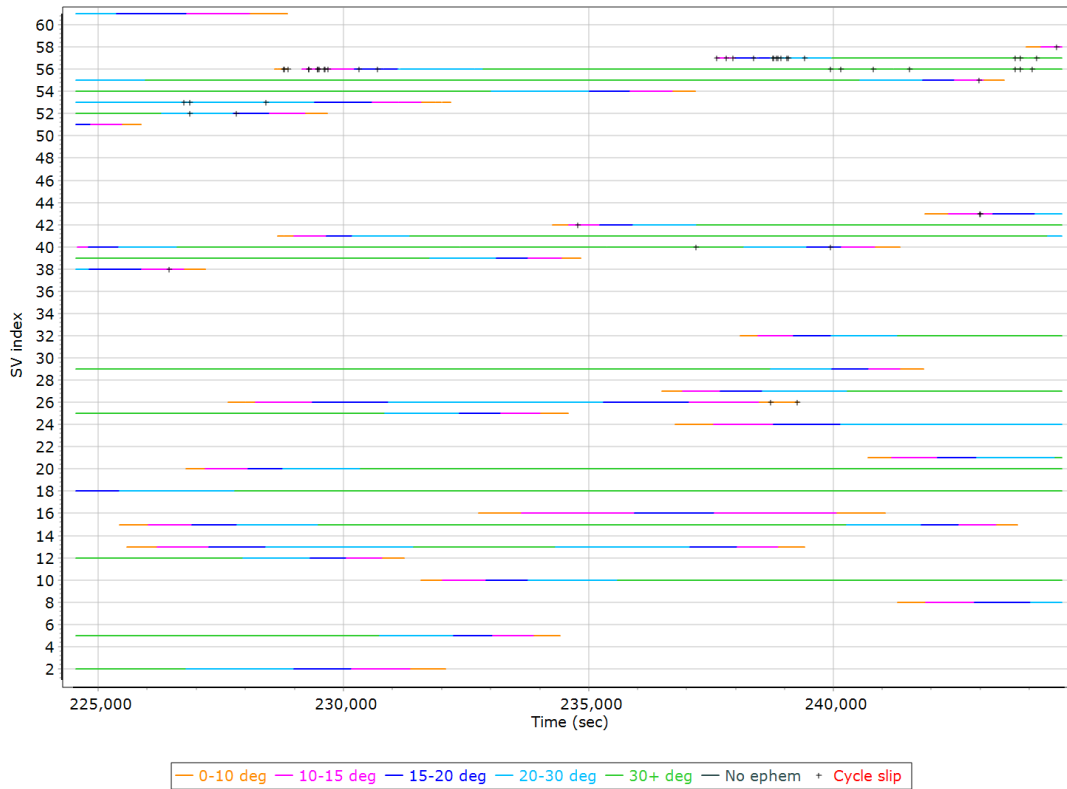
## Rover Data QC

### Raw IMU Import QC Summary

IMU data input file	imu_200929_B_5060420_nad2011_FINAL.dat
IMU data check log file	imudt_200929_B_5060420_nad2011_FINAL.log
IMU Records Processed	4021435
Termination Status	Normal
IMU Anomalies	0

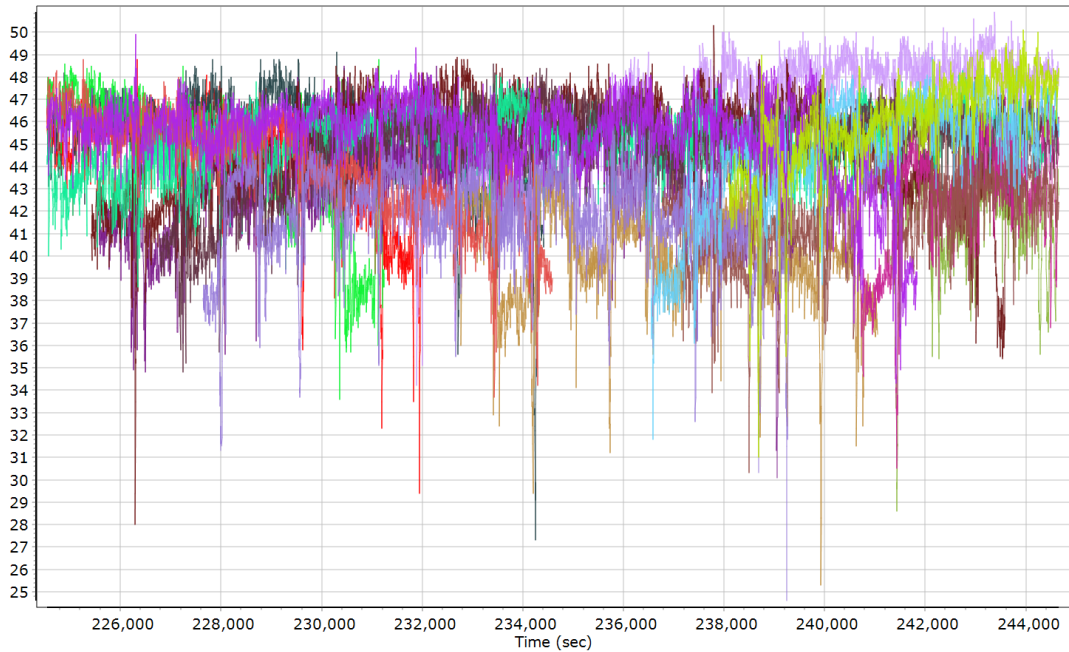
## Primary Observables & Satellite Data

### GPS/GLONASS L1 Satellite Lock/Elevation



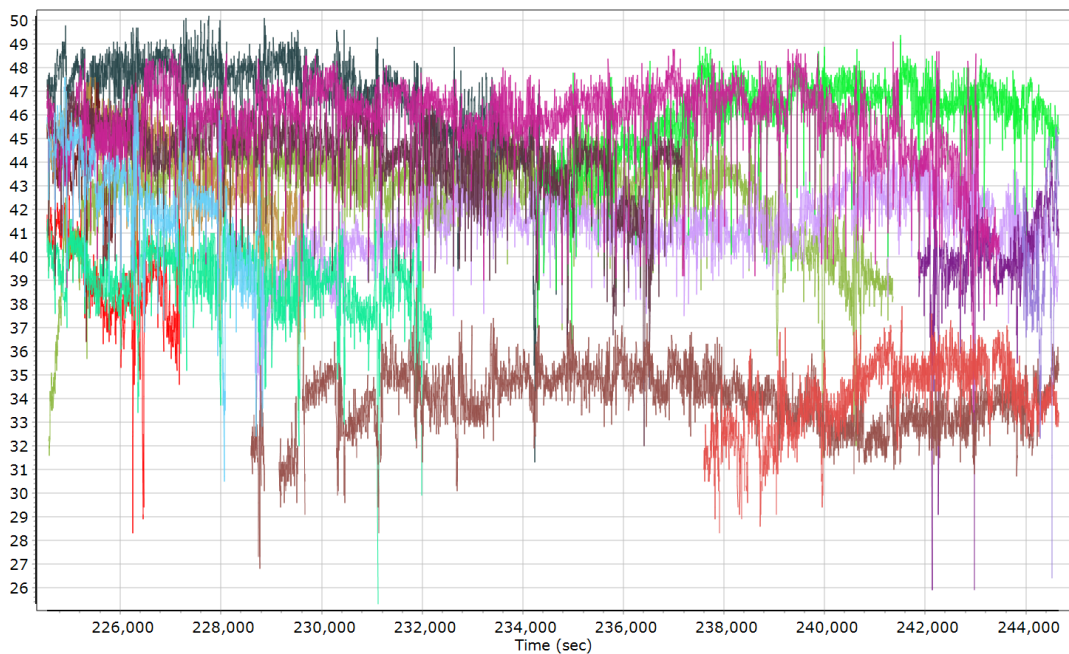


### GPS L1 SNR



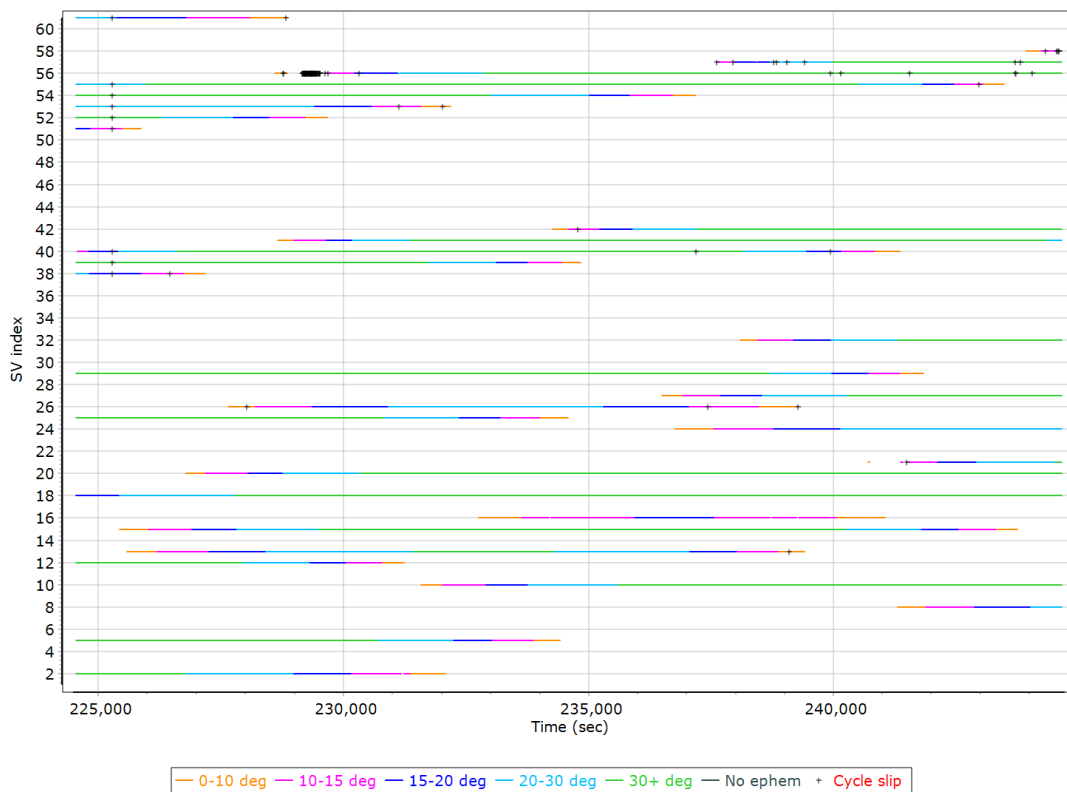
- |                           |                           |                           |                           |
|---------------------------|---------------------------|---------------------------|---------------------------|
| GPS PRN 02 L1 SNR (dB/Hz) | GPS PRN 05 L1 SNR (dB/Hz) | GPS PRN 08 L1 SNR (dB/Hz) | GPS PRN 10 L1 SNR (dB/Hz) |
| GPS PRN 12 L1 SNR (dB/Hz) | GPS PRN 13 L1 SNR (dB/Hz) | GPS PRN 15 L1 SNR (dB/Hz) | GPS PRN 16 L1 SNR (dB/Hz) |
| GPS PRN 18 L1 SNR (dB/Hz) | GPS PRN 20 L1 SNR (dB/Hz) | GPS PRN 21 L1 SNR (dB/Hz) | GPS PRN 24 L1 SNR (dB/Hz) |
| GPS PRN 25 L1 SNR (dB/Hz) | GPS PRN 26 L1 SNR (dB/Hz) | GPS PRN 27 L1 SNR (dB/Hz) | GPS PRN 29 L1 SNR (dB/Hz) |
| GPS PRN 32 L1 SNR (dB/Hz) |                           |                           |                           |

### GLONASS L1 SNR

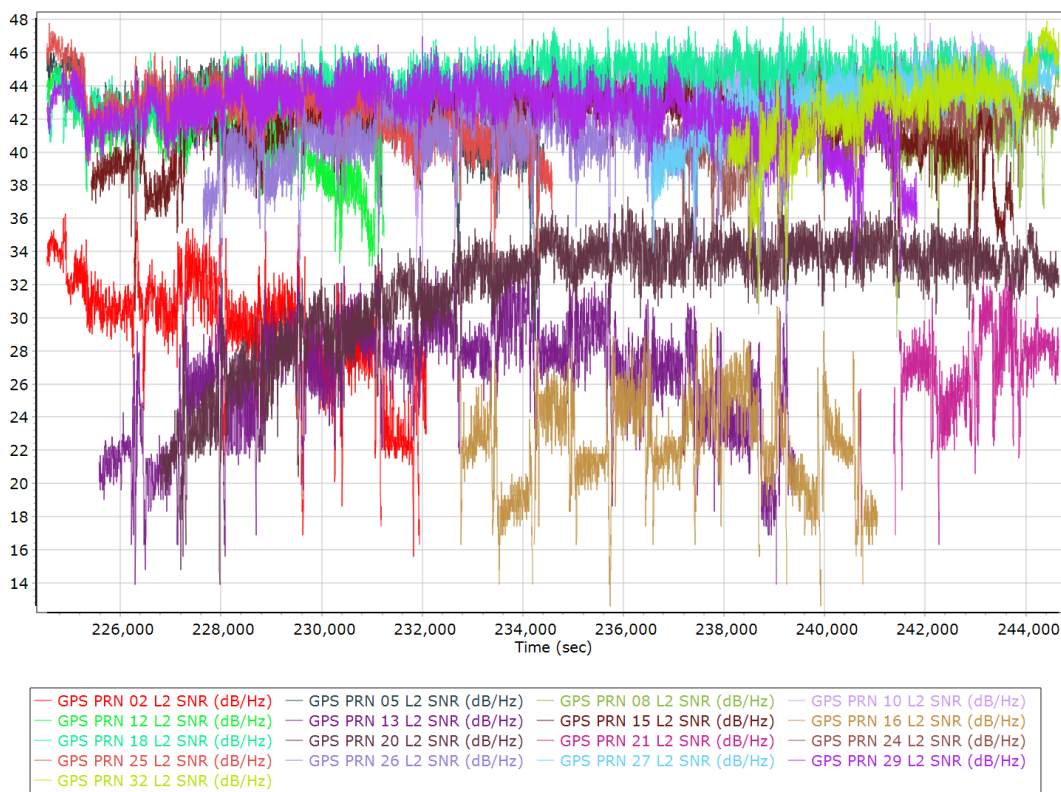


- |                           |                           |                           |
|---------------------------|---------------------------|---------------------------|
| GLONASS 01 L1 SNR (dB/Hz) | GLONASS 02 L1 SNR (dB/Hz) | GLONASS 03 L1 SNR (dB/Hz) |
| GLONASS 04 L1 SNR (dB/Hz) | GLONASS 05 L1 SNR (dB/Hz) | GLONASS 06 L1 SNR (dB/Hz) |
| GLONASS 14 L1 SNR (dB/Hz) | GLONASS 15 L1 SNR (dB/Hz) | GLONASS 16 L1 SNR (dB/Hz) |
| GLONASS 17 L1 SNR (dB/Hz) | GLONASS 18 L1 SNR (dB/Hz) | GLONASS 19 L1 SNR (dB/Hz) |
| GLONASS 20 L1 SNR (dB/Hz) | GLONASS 21 L1 SNR (dB/Hz) | GLONASS 24 L1 SNR (dB/Hz) |

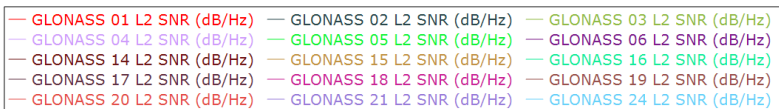
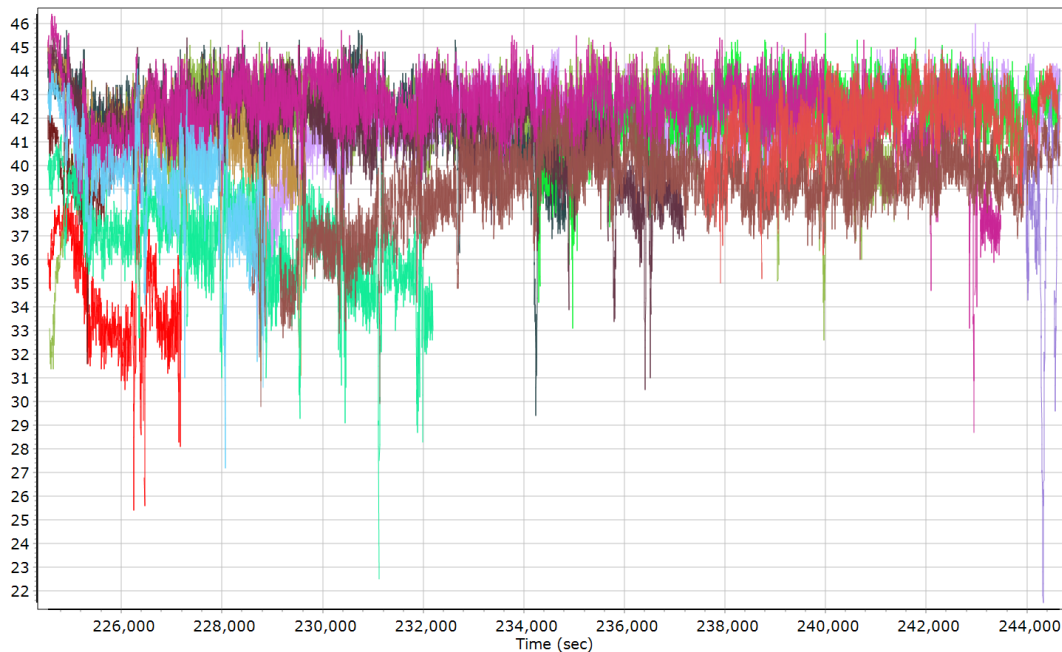
### GPS/GLONASS L2 Satellite Lock/Elevation



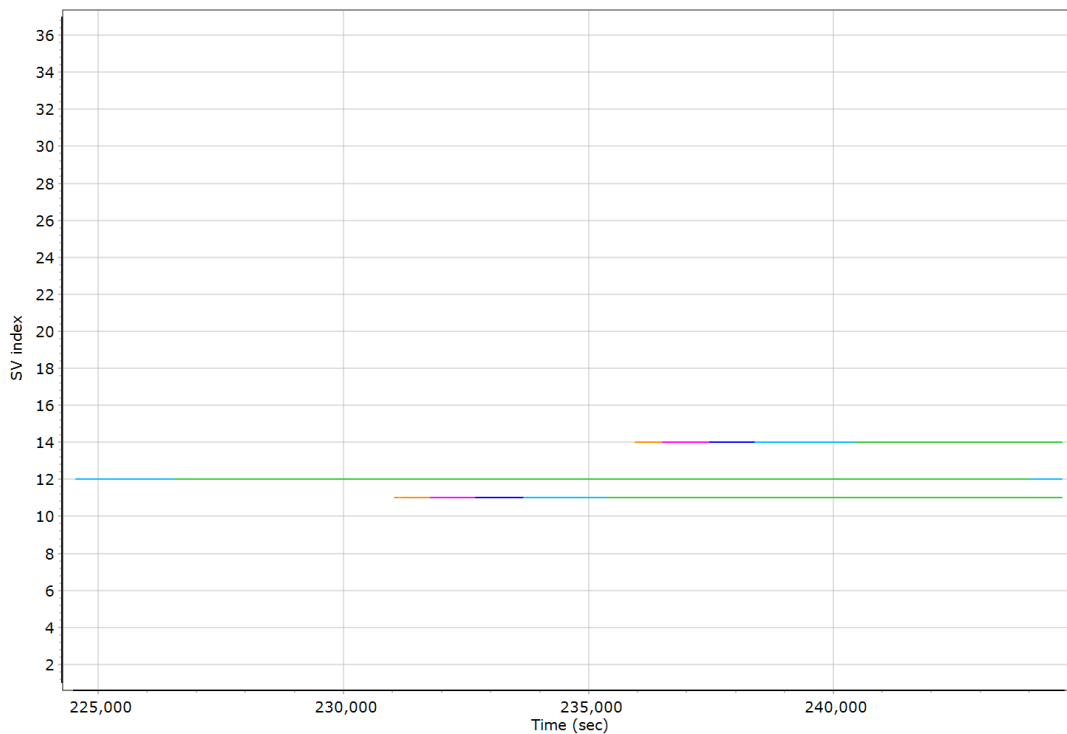
### GPS L2 SNR



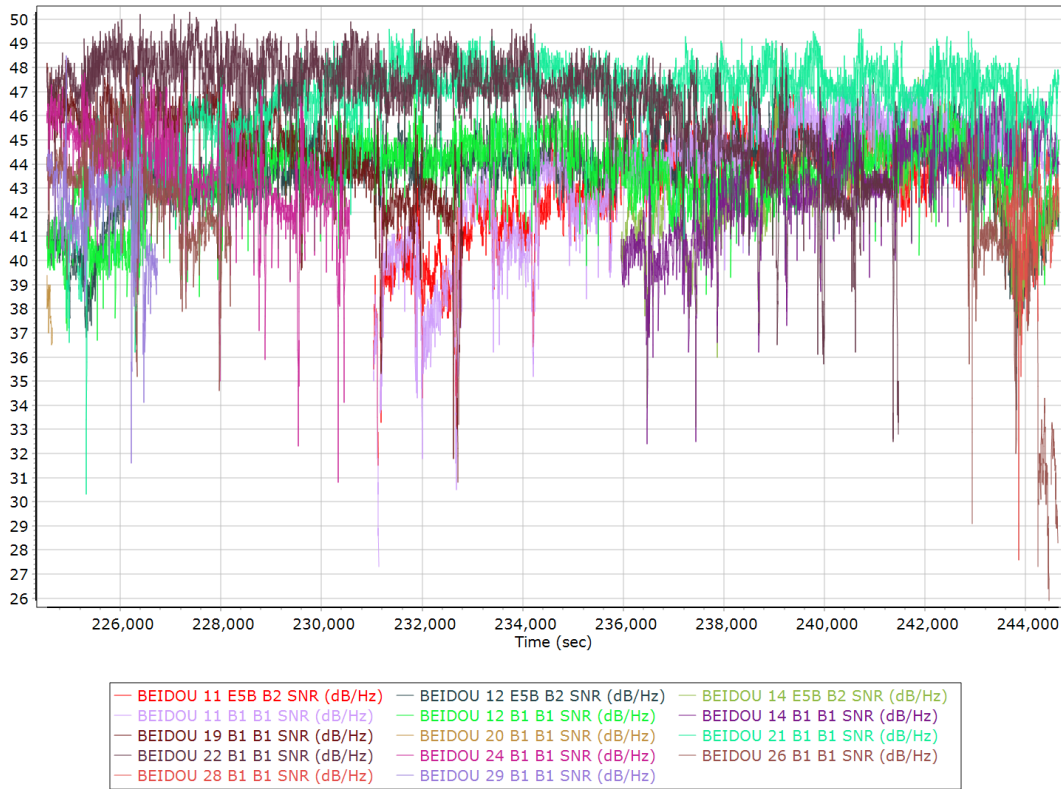
### GLONASS L2 SNR



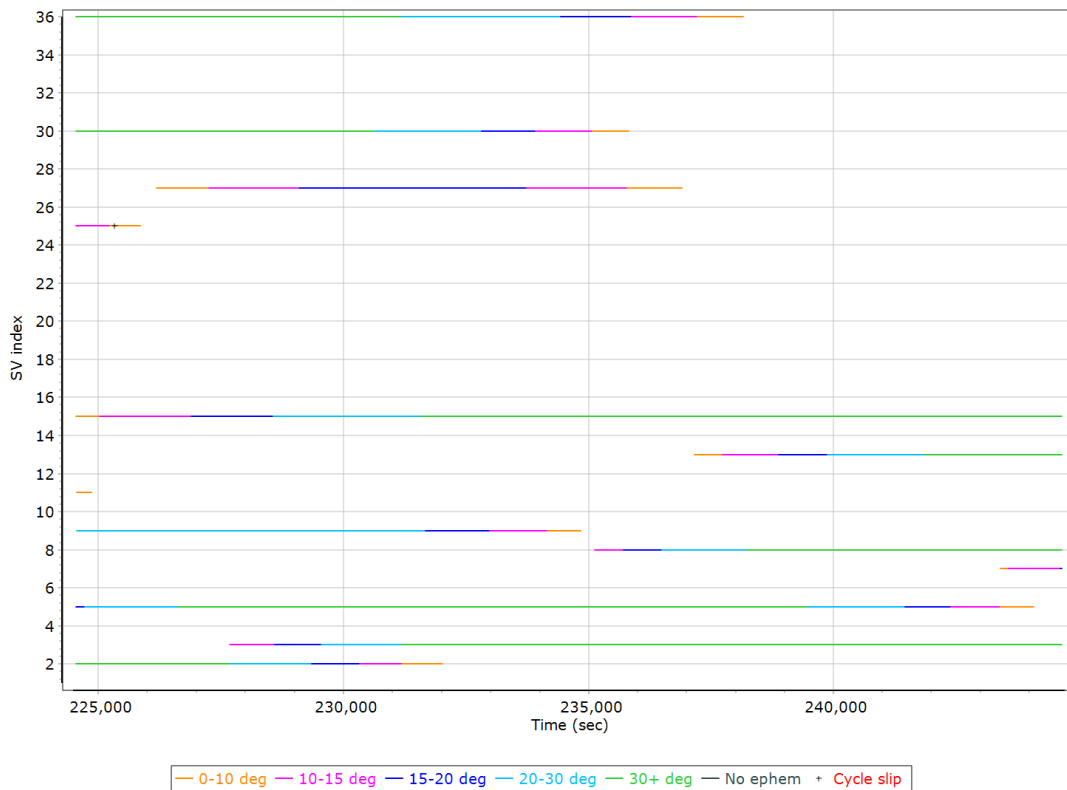
### BEIDOU Satellite Lock/Elevation



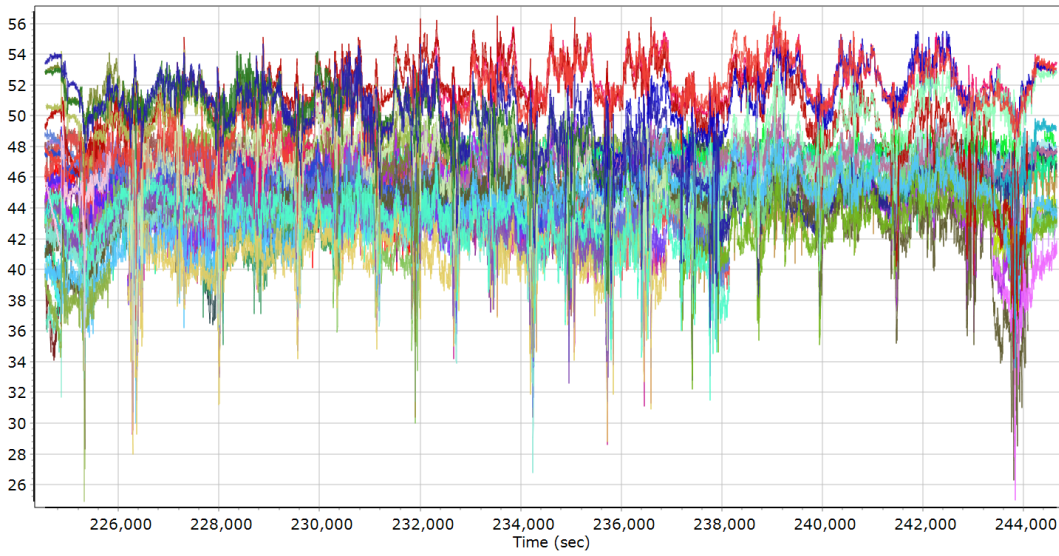
### BEIDOU SNR



### GALILEO Satellite Lock/Elevation



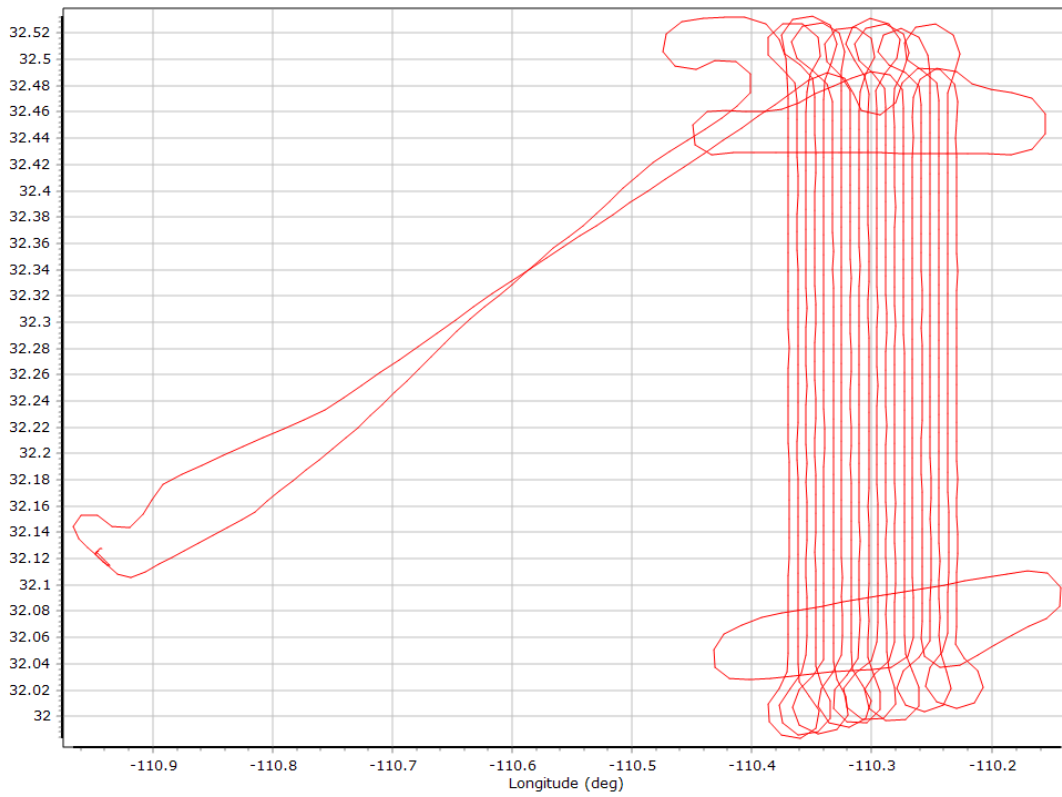
## GALILEO SNR



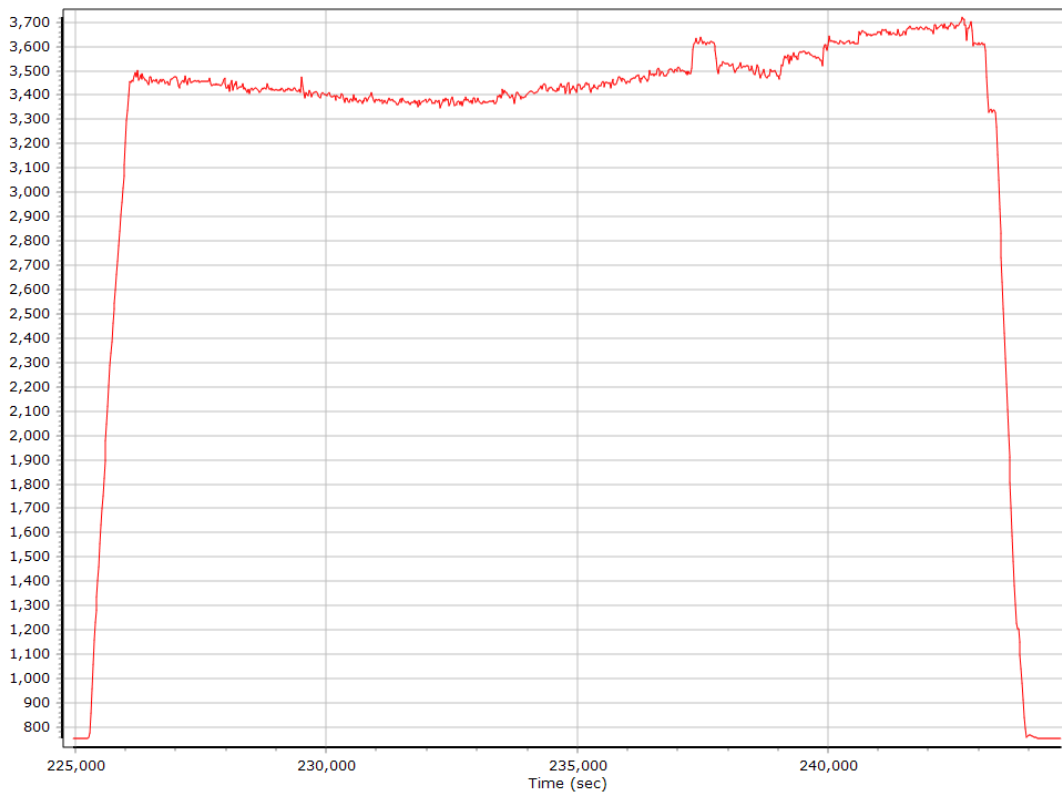
- |   |   |
|---|---|
| — GALILEO 02 L1 BOC_1_1_DP_MBOC SNR (dB/Hz) | — GALILEO 03 L1 BOC_1_1_DP_MBOC SNR (dB/Hz) |
| — GALILEO 05 L1 BOC_1_1_DP_MBOC SNR (dB/Hz) | — GALILEO 07 L1 BOC_1_1_DP_MBOC SNR (dB/Hz) |
| — GALILEO 08 L1 BOC_1_1_DP_MBOC SNR (dB/Hz) | — GALILEO 09 L1 BOC_1_1_DP_MBOC SNR (dB/Hz) |
| — GALILEO 11 L1 BOC_1_1_DP_MBOC SNR (dB/Hz) | — GALILEO 13 L1 BOC_1_1_DP_MBOC SNR (dB/Hz) |
| — GALILEO 15 L1 BOC_1_1_DP_MBOC SNR (dB/Hz) | — GALILEO 25 L1 BOC_1_1_DP_MBOC SNR (dB/Hz) |
| — GALILEO 27 L1 BOC_1_1_DP_MBOC SNR (dB/Hz) | — GALILEO 30 L1 BOC_1_1_DP_MBOC SNR (dB/Hz) |
| — GALILEO 36 L1 BOC_1_1_DP_MBOC SNR (dB/Hz) | — GALILEO 02 L5E5A BPSK10_PD SNR (dB/Hz)    |
| — GALILEO 03 L5E5A BPSK10_PD SNR (dB/Hz)    | — GALILEO 05 L5E5A BPSK10_PD SNR (dB/Hz)    |
| — GALILEO 07 L5E5A BPSK10_PD SNR (dB/Hz)    | — GALILEO 08 L5E5A BPSK10_PD SNR (dB/Hz)    |
| — GALILEO 09 L5E5A BPSK10_PD SNR (dB/Hz)    | — GALILEO 11 L5E5A BPSK10_PD SNR (dB/Hz)    |

## Smoothed Trajectory Information

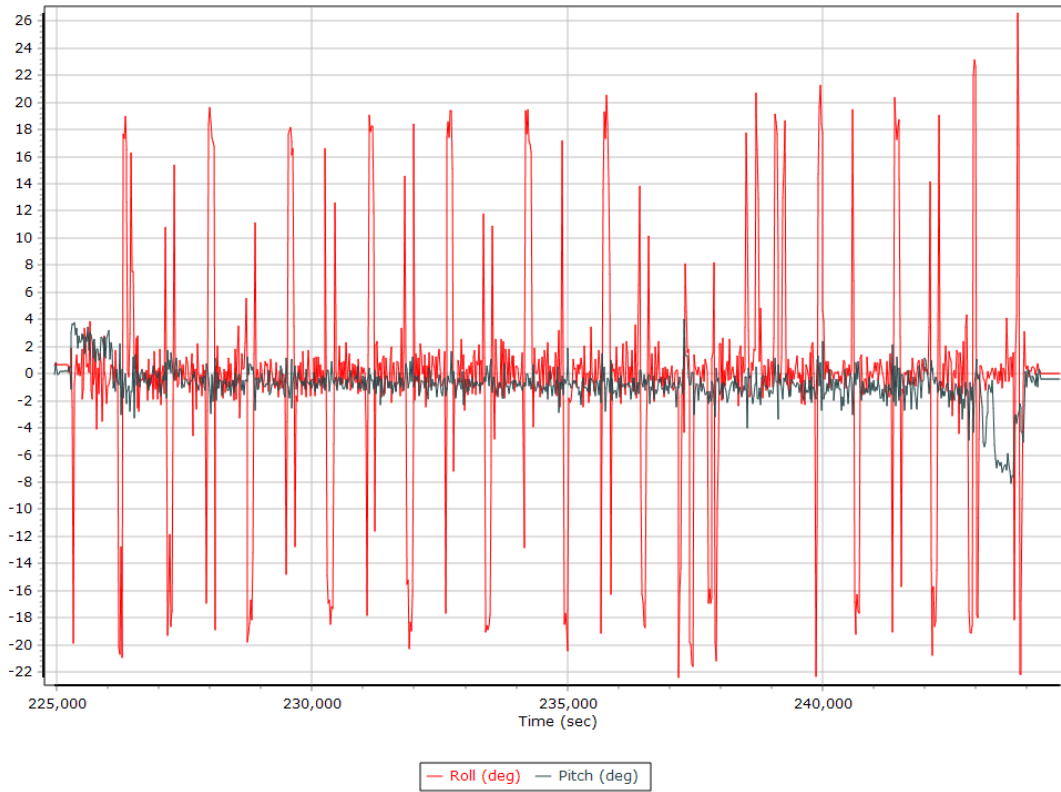
### Top View



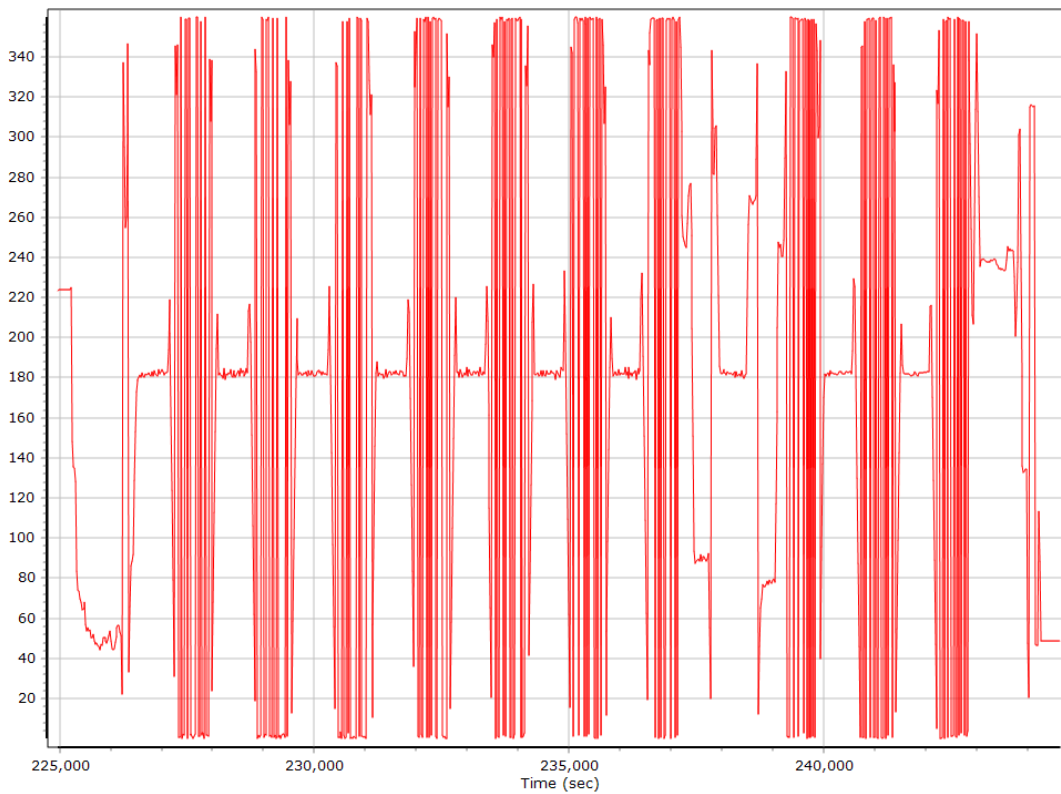
### Altitude



## Roll/Pitch

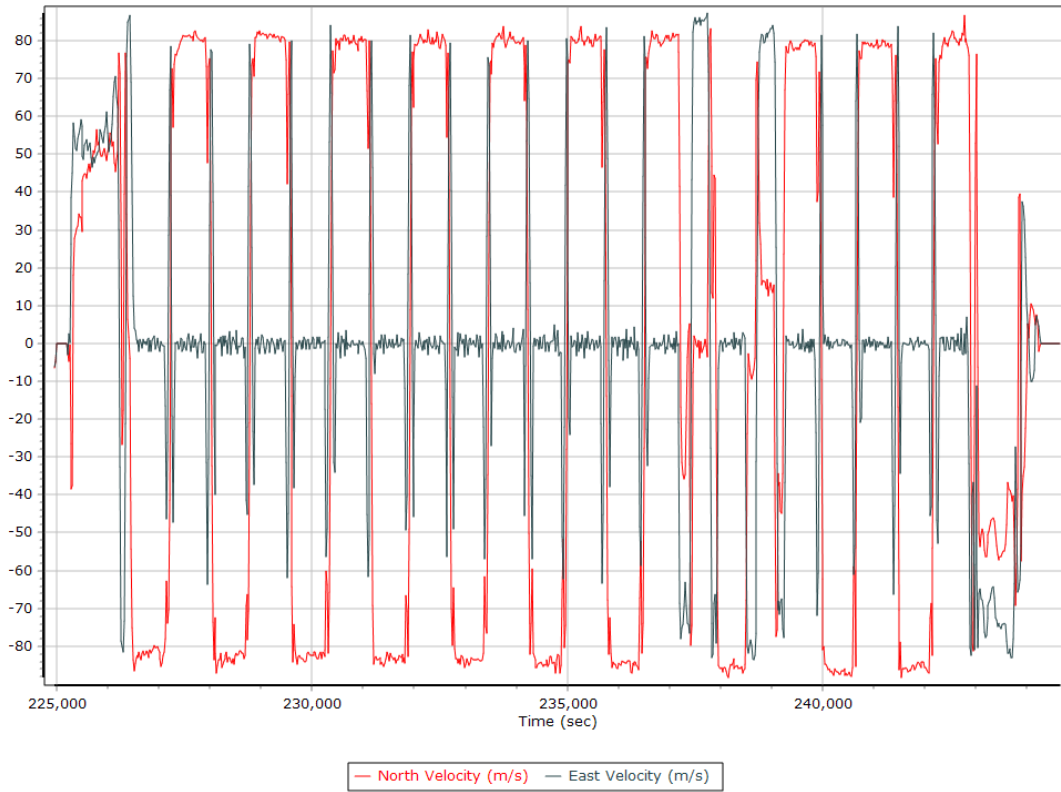


## Heading

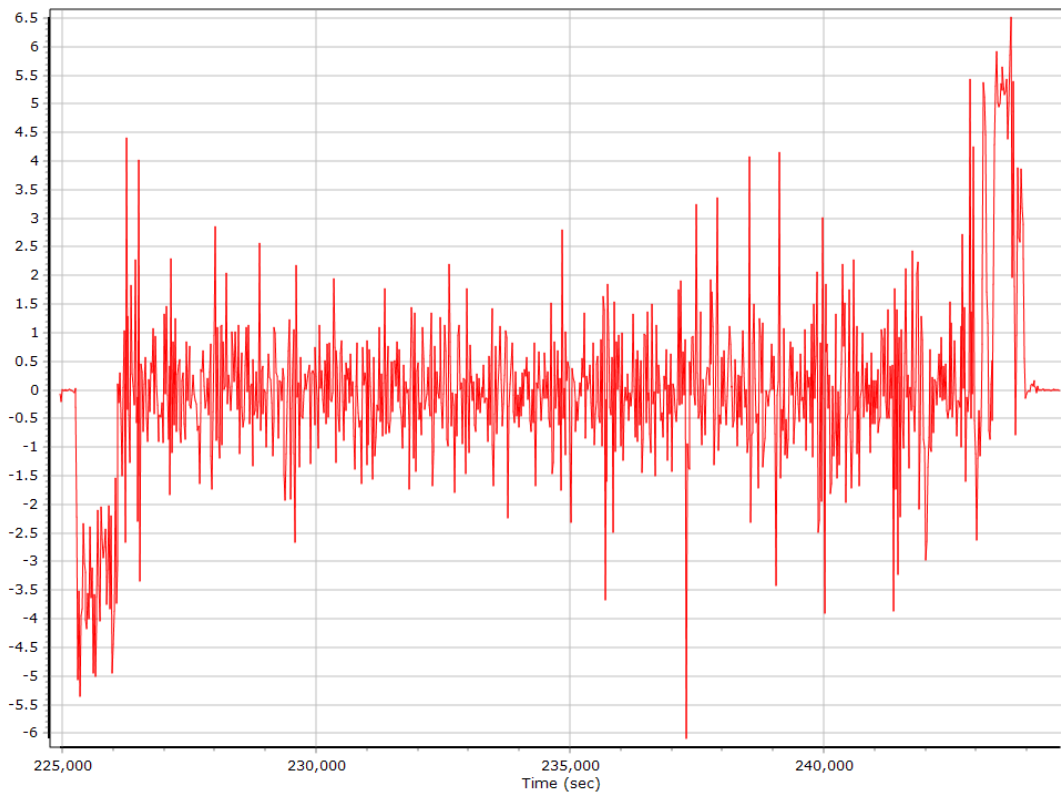




## North/East Velocity

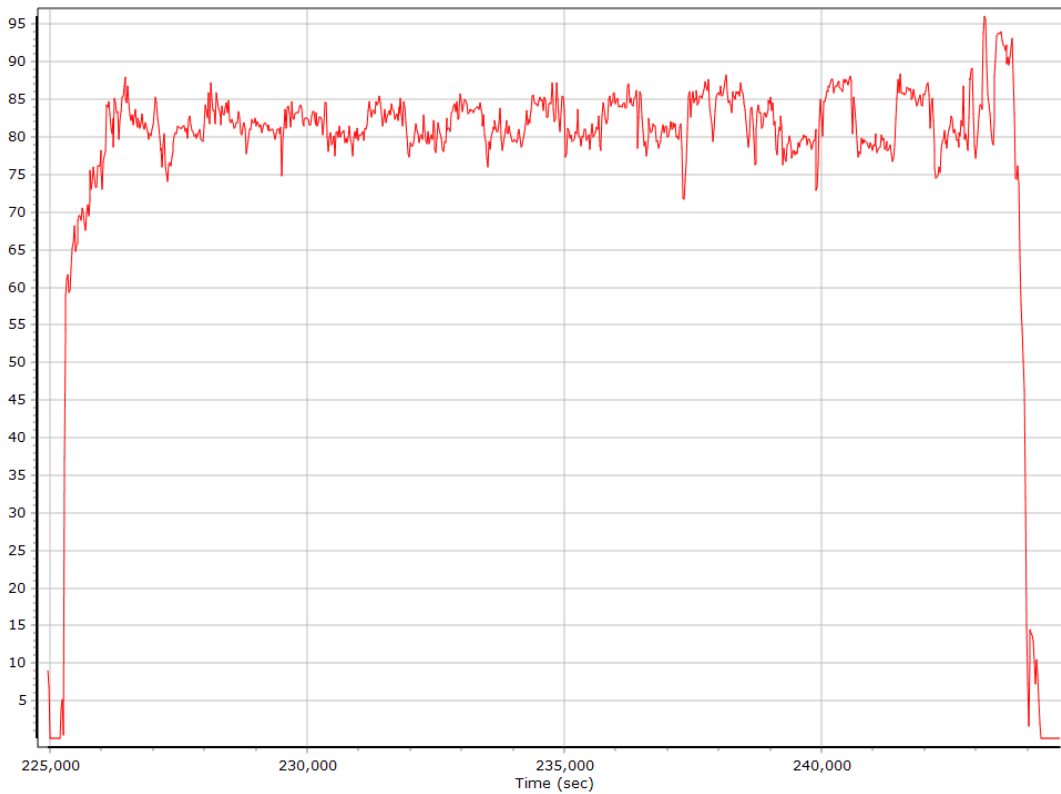


## Down Velocity

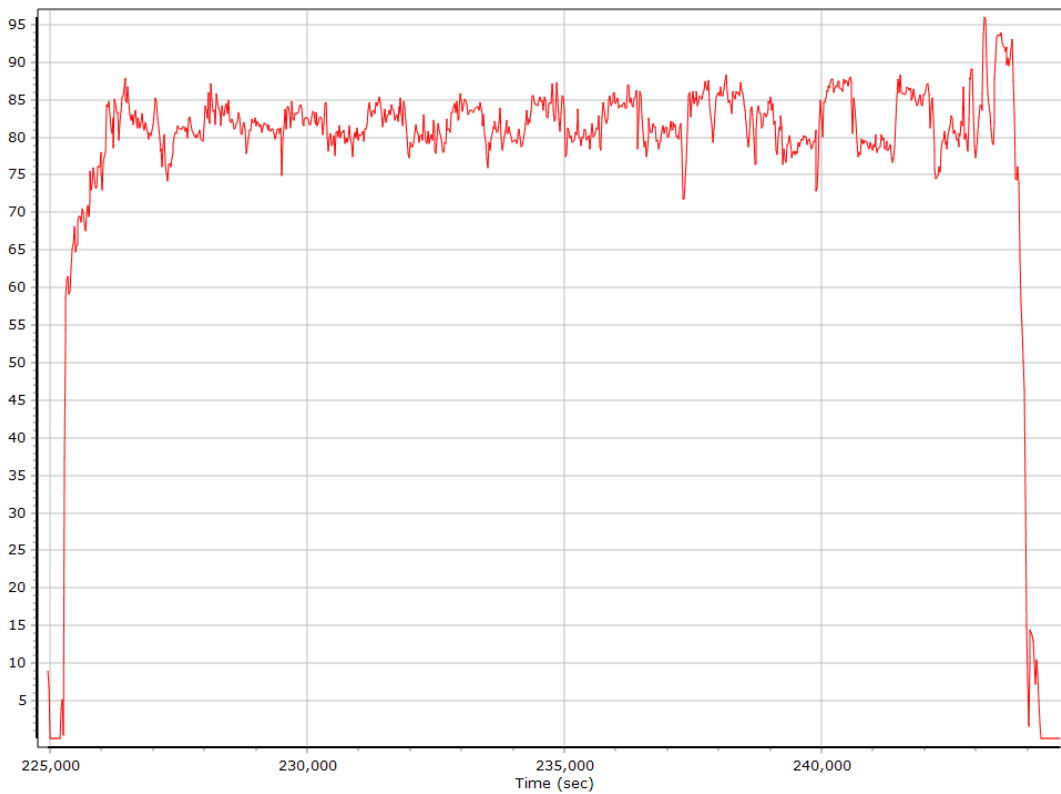




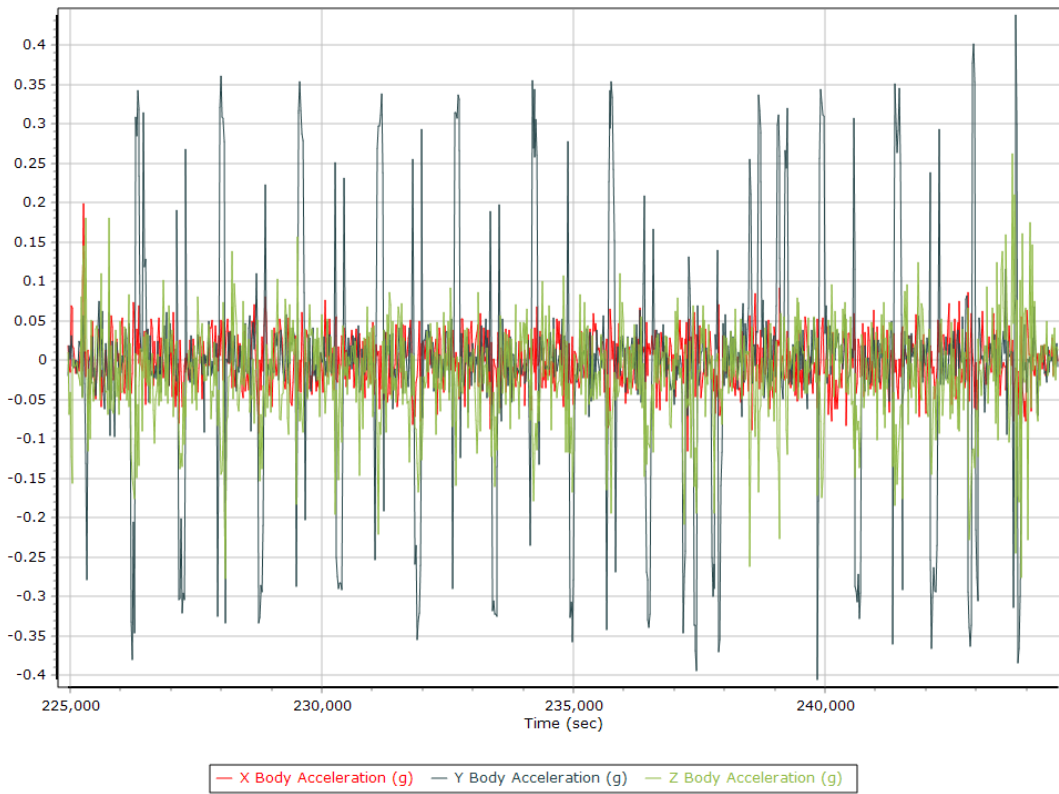
## Total Speed



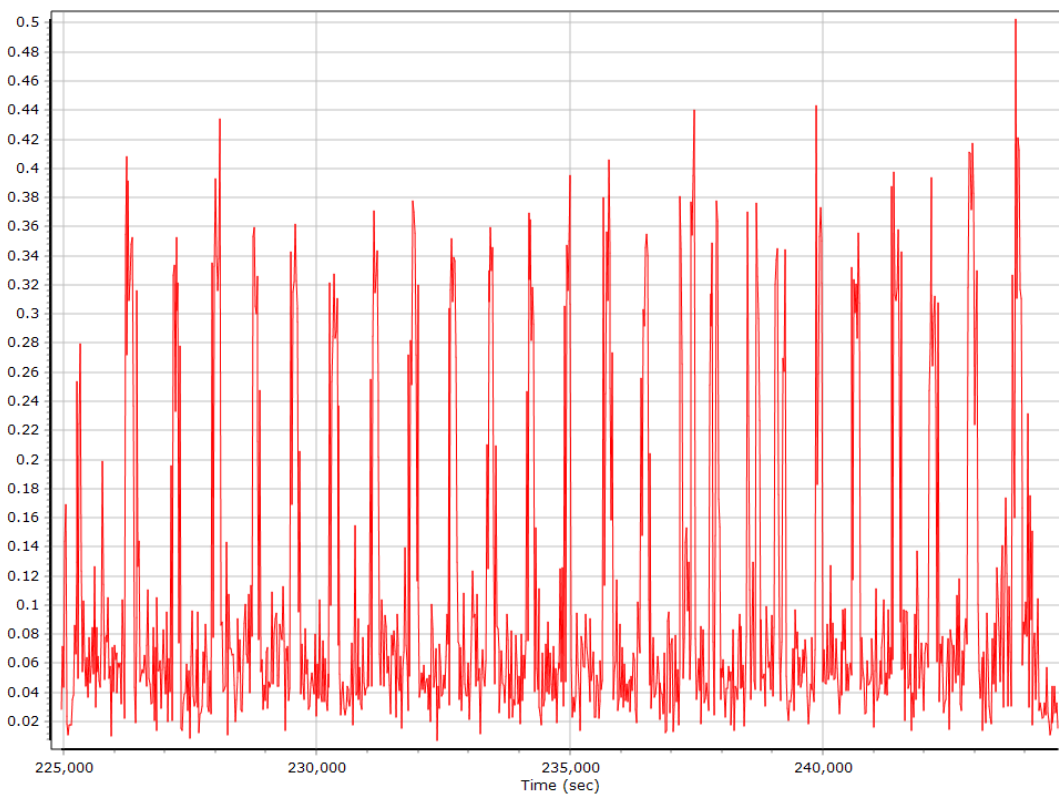
## Ground Speed



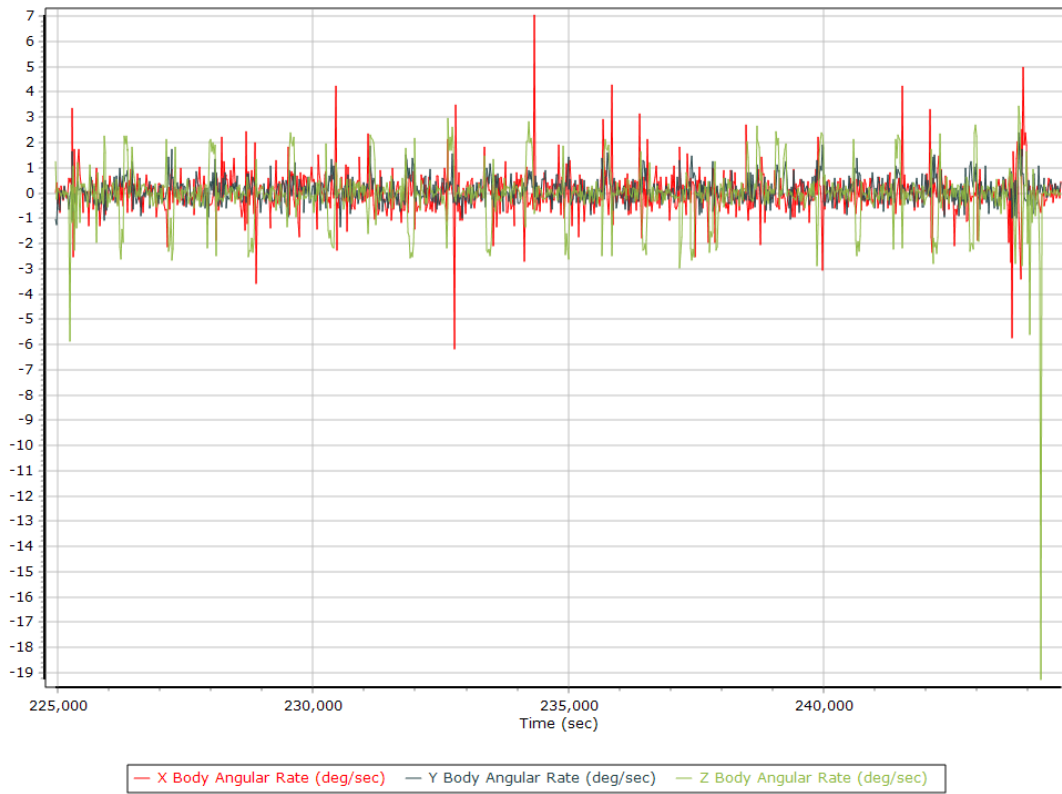
## Body Acceleration



## Total Body Acceleration

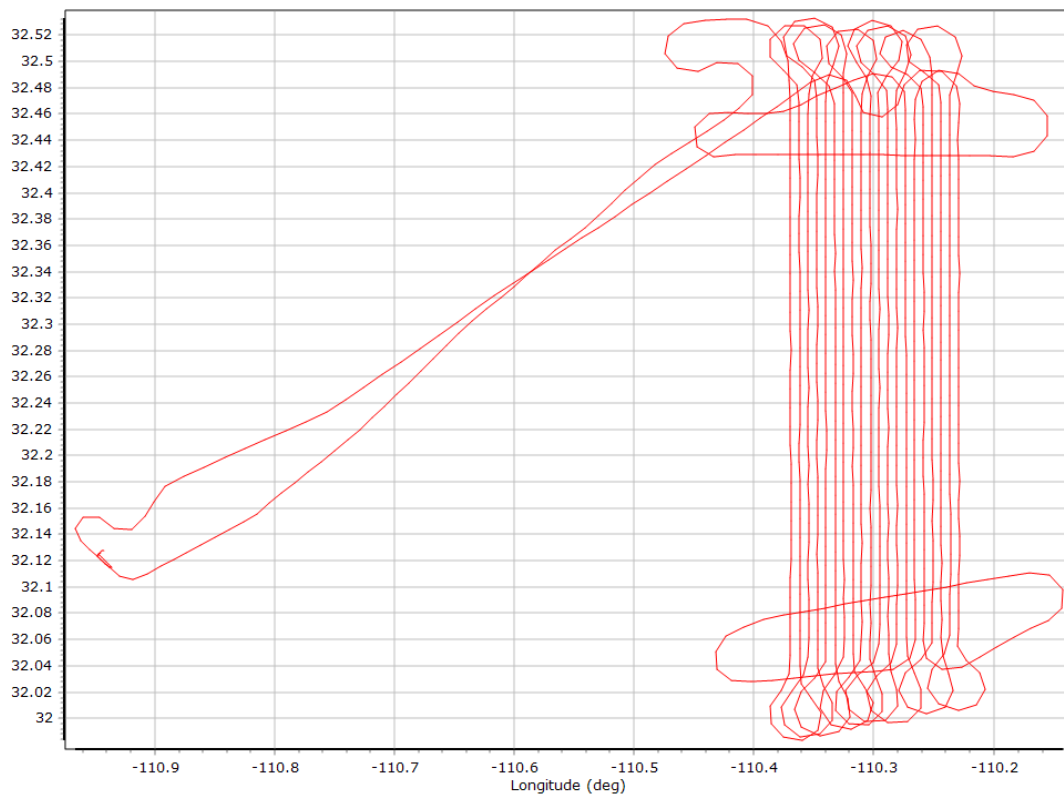


## Body Angular Rate

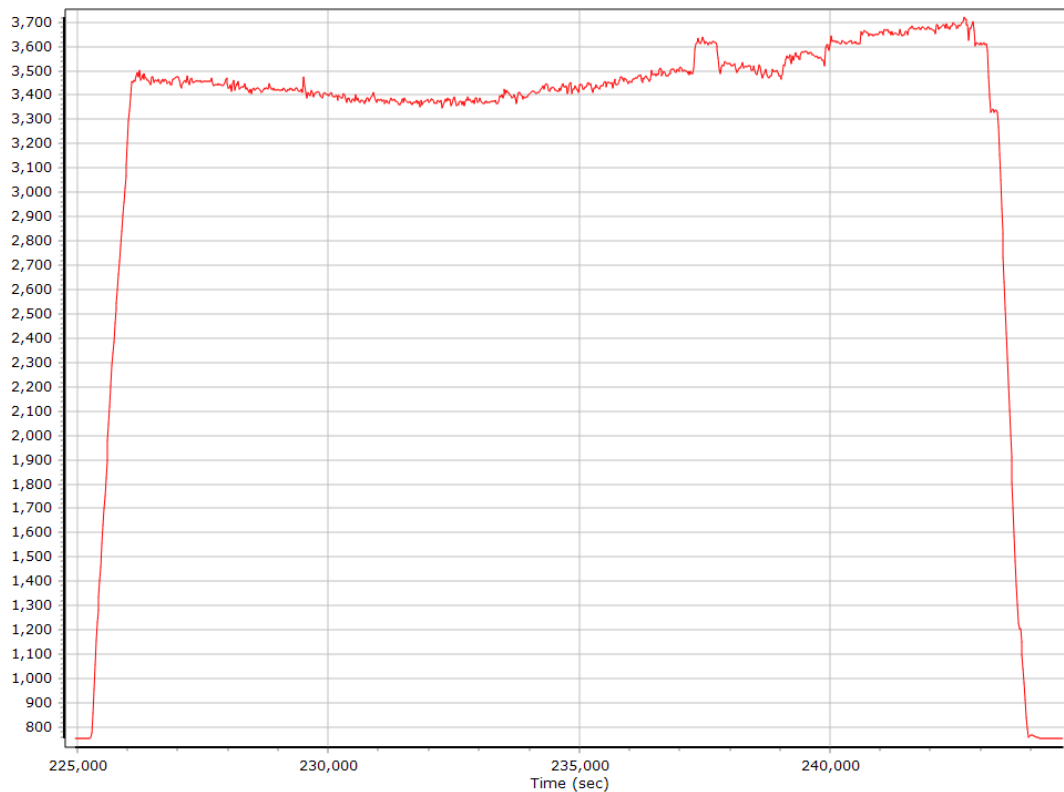


## Forward Processed Trajectory Information

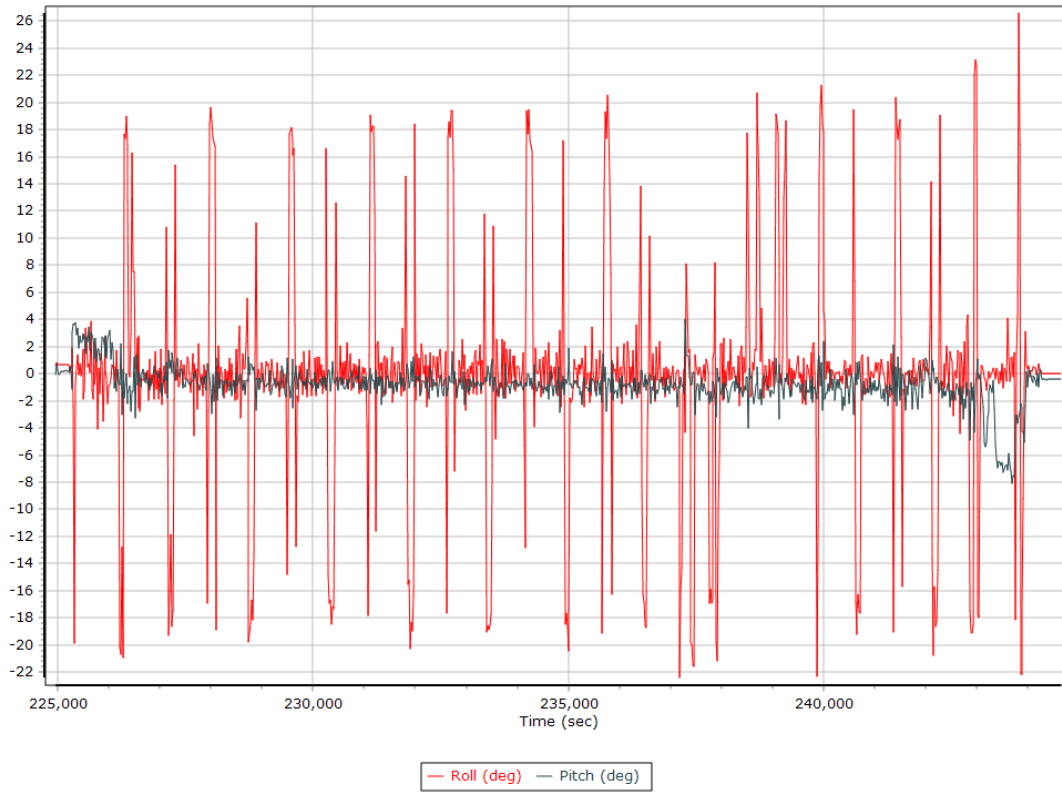
### Top View



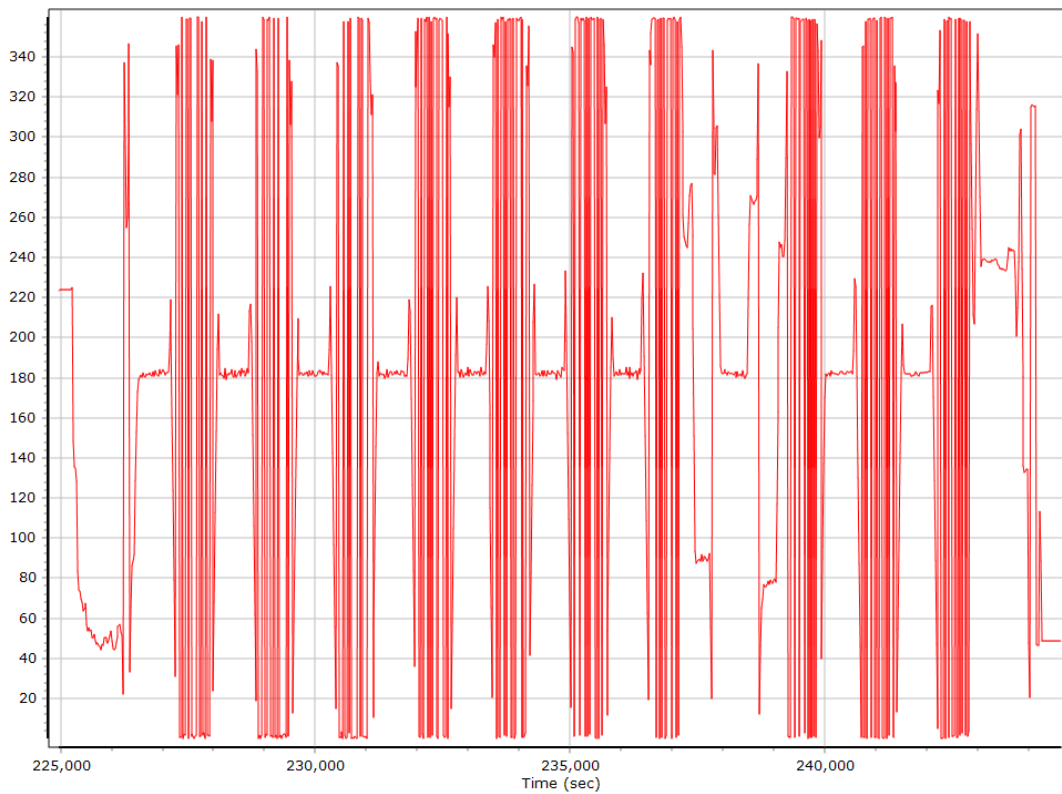
### Altitude



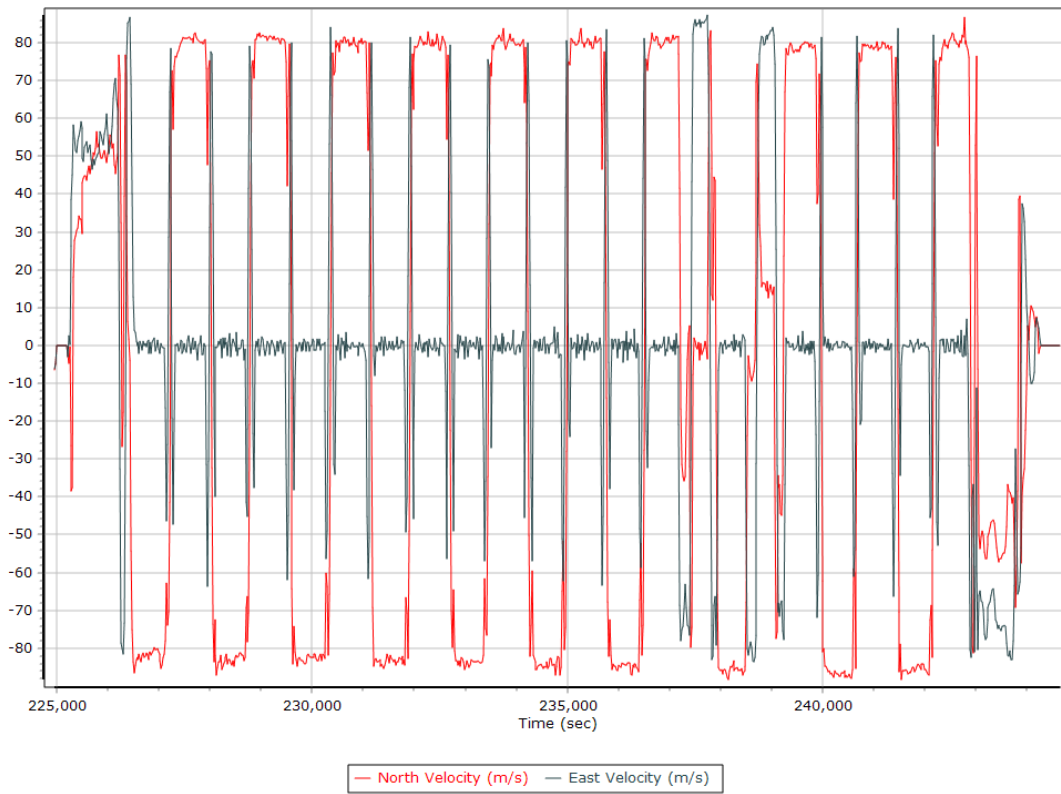
## Roll/Pitch



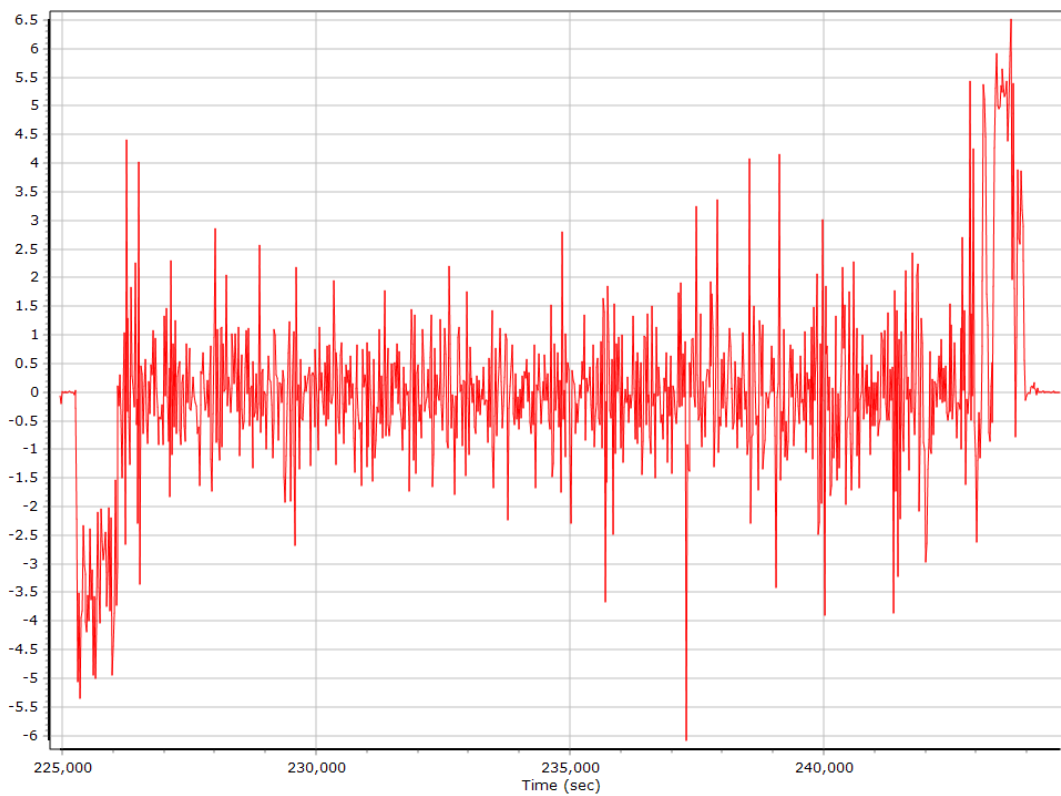
## Heading



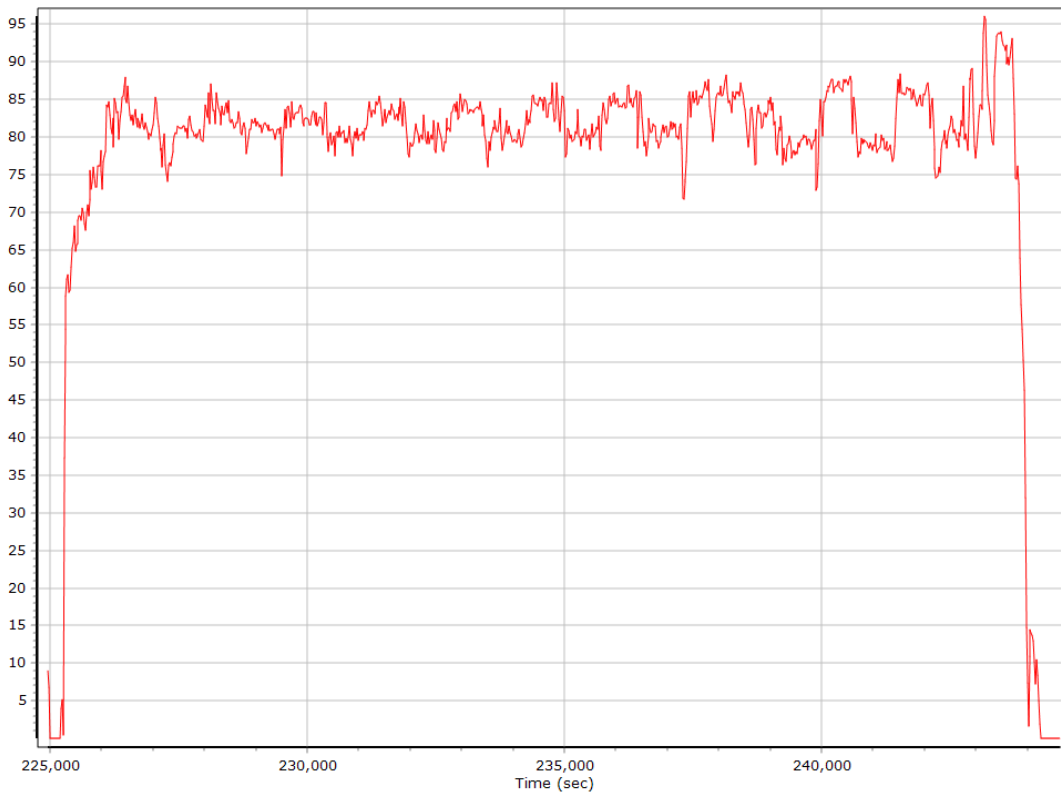
## North/East Velocity



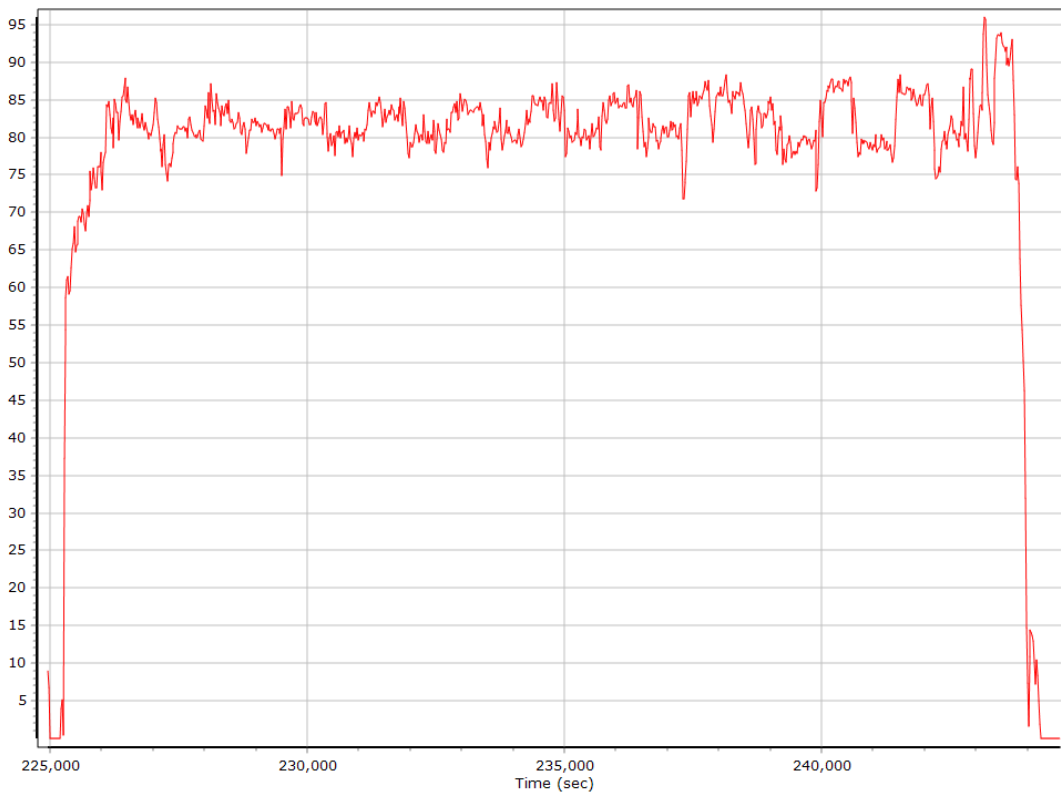
## Down Velocity



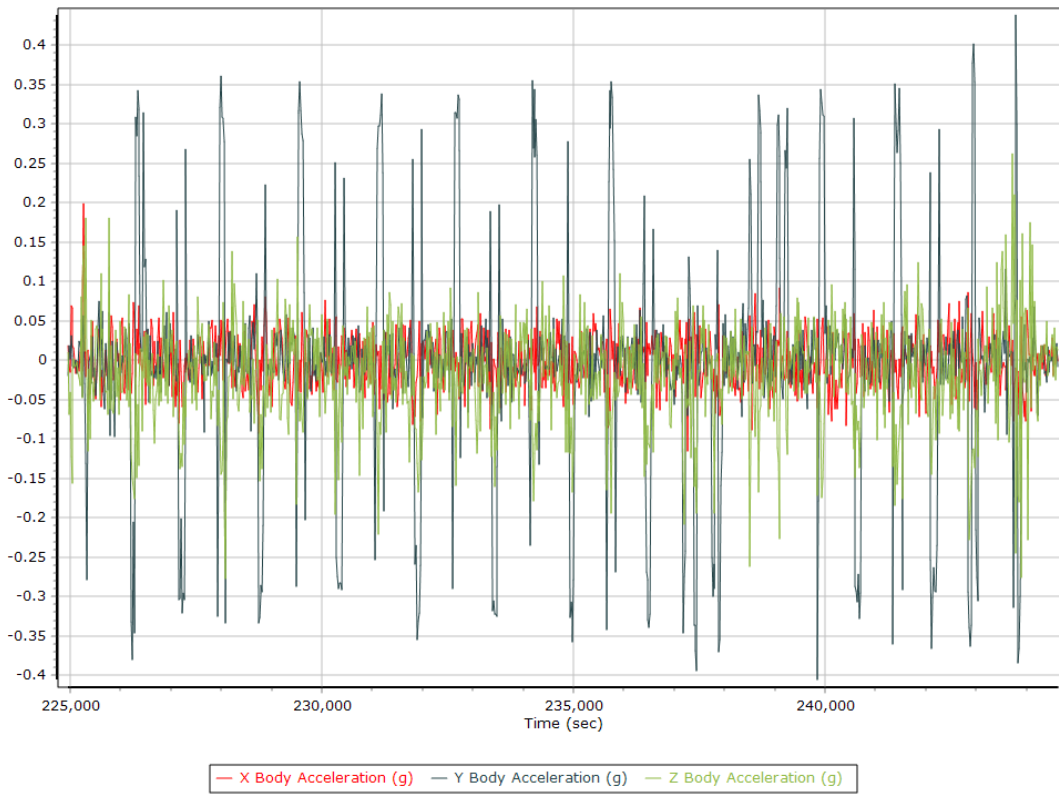
## Total Speed



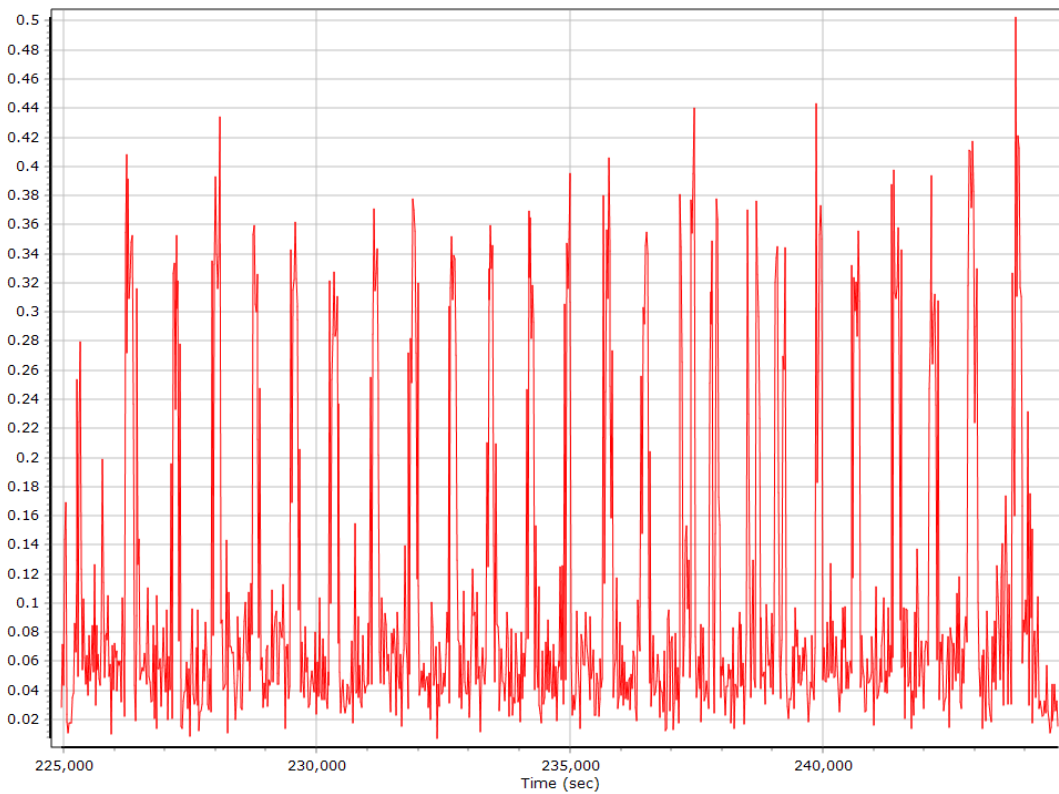
## Ground Speed



## Body Acceleration

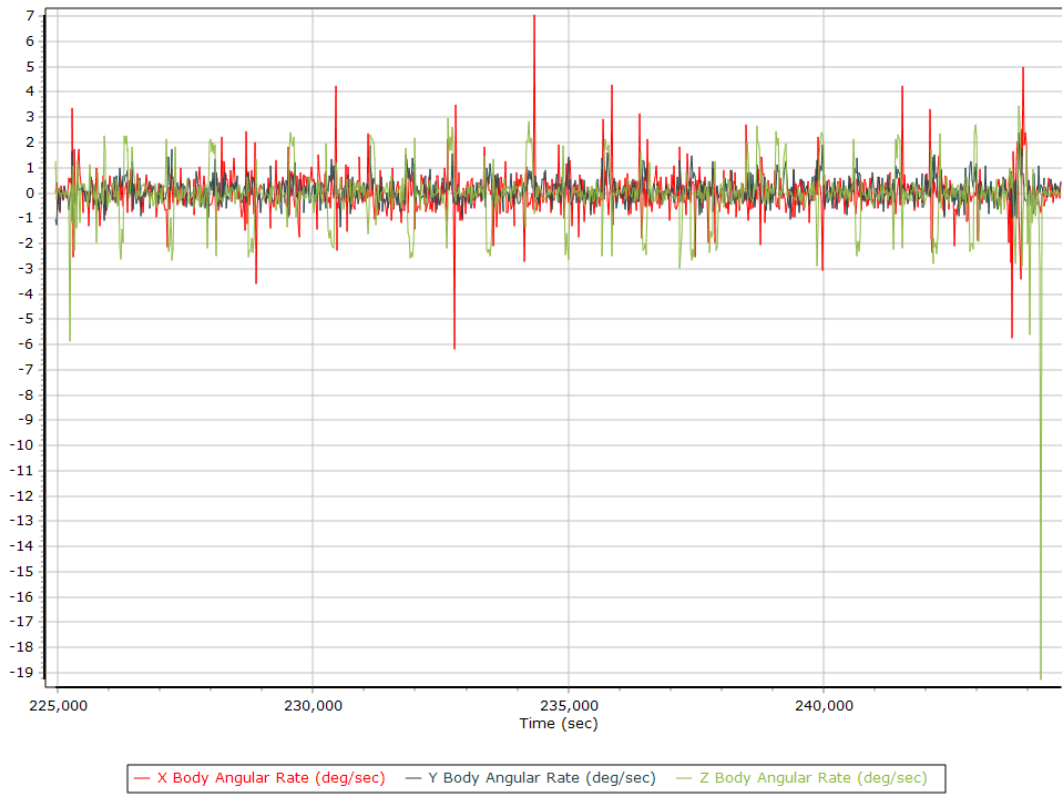


## Total Body Acceleration





## Body Angular Rate

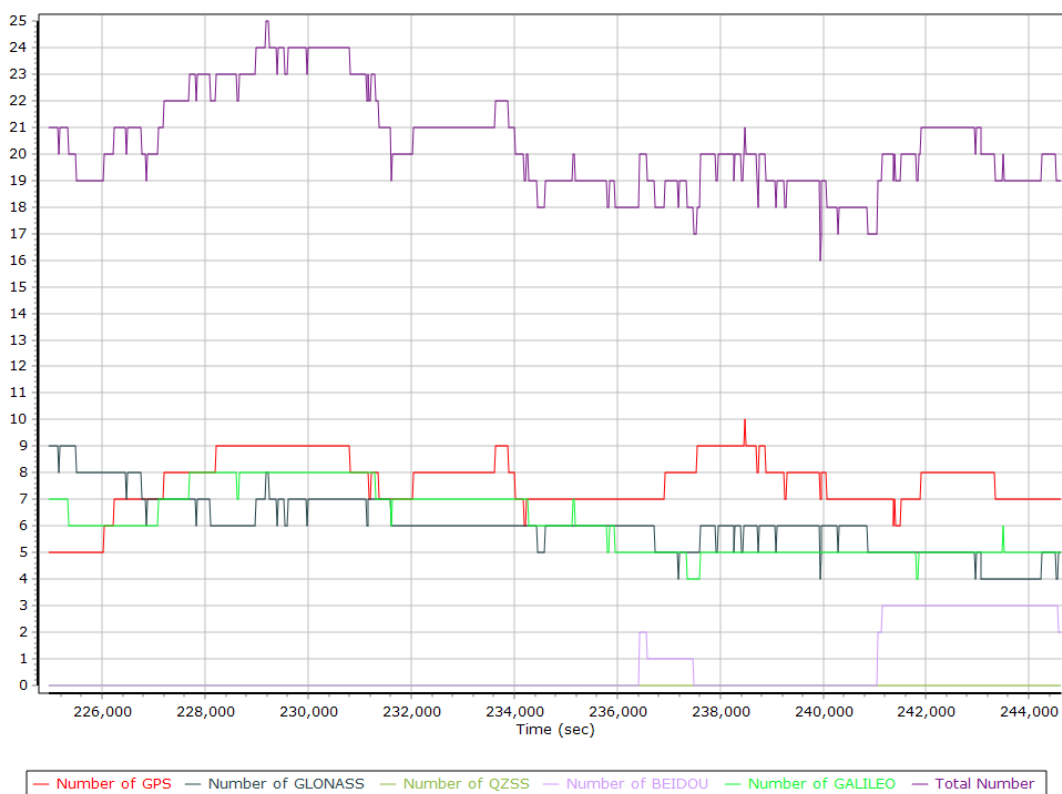


## GNSS QC

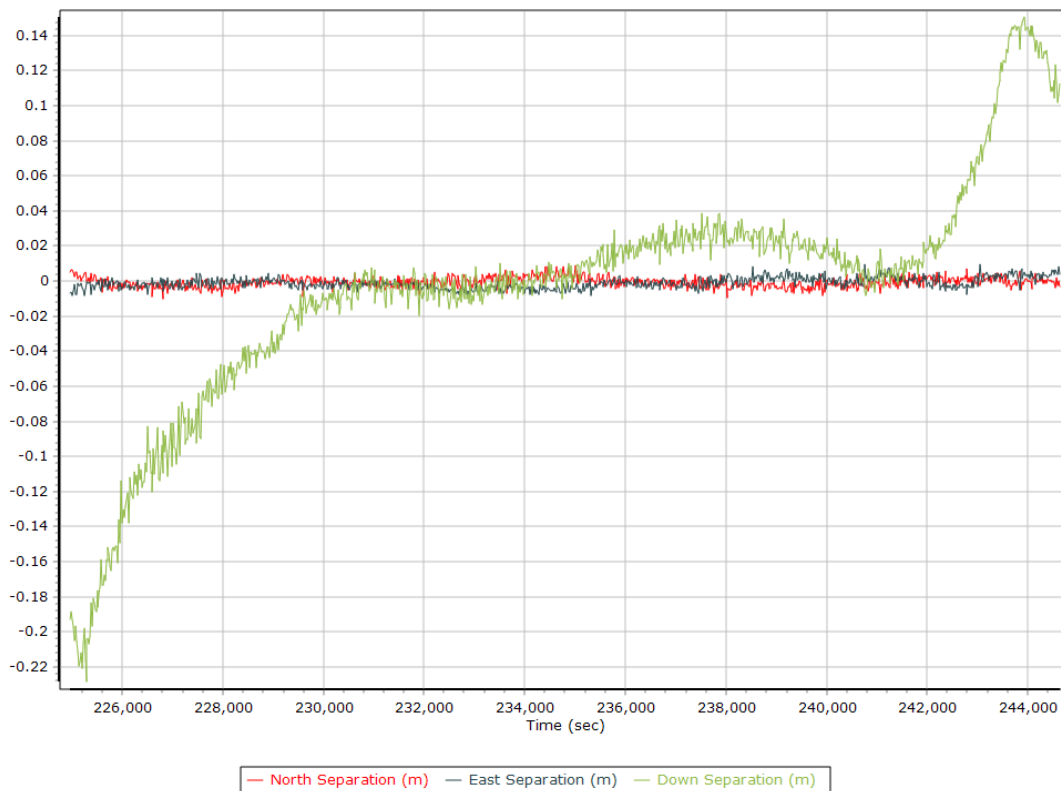
### GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	5	10	8
Number of GLONASS SV	0	9	6
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	3	1
Number of GALILEO SV	4	8	6
Total number of SV	12	25	20
PDOP	1.05	1.80	1.25
QC Solution Gaps	1.00	1.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	20019.00	0.00	53.00
Percentage	99.74	0.00	0.26

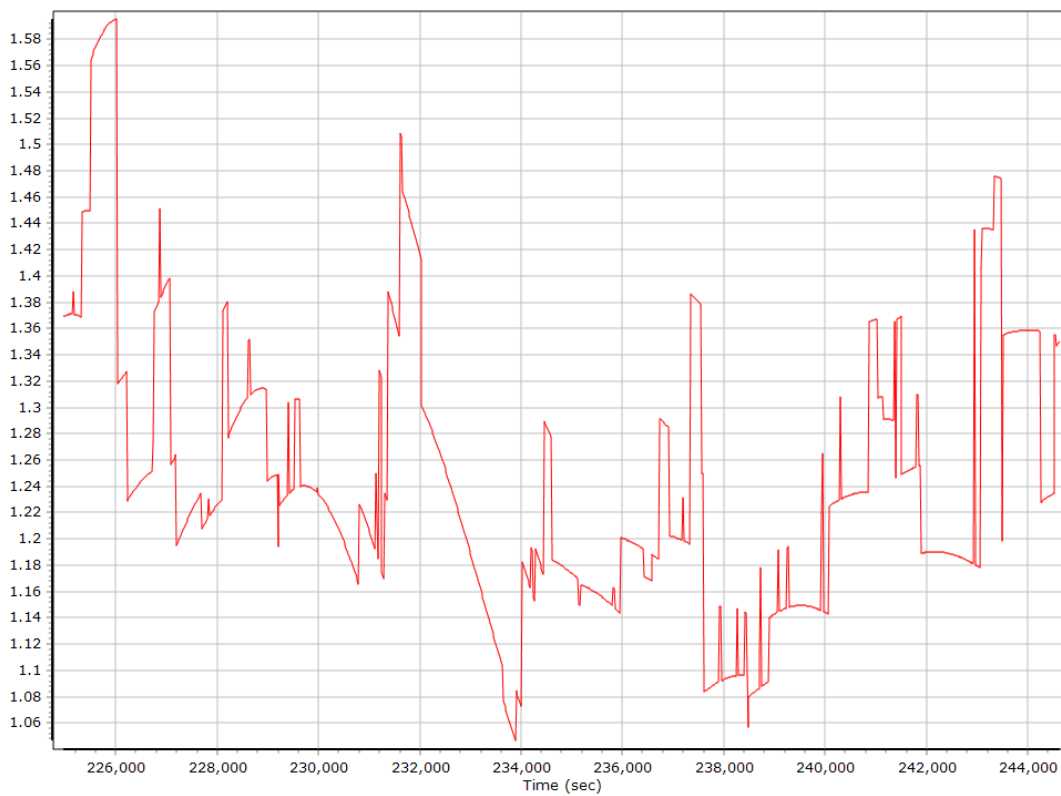
### Num SVs in solution



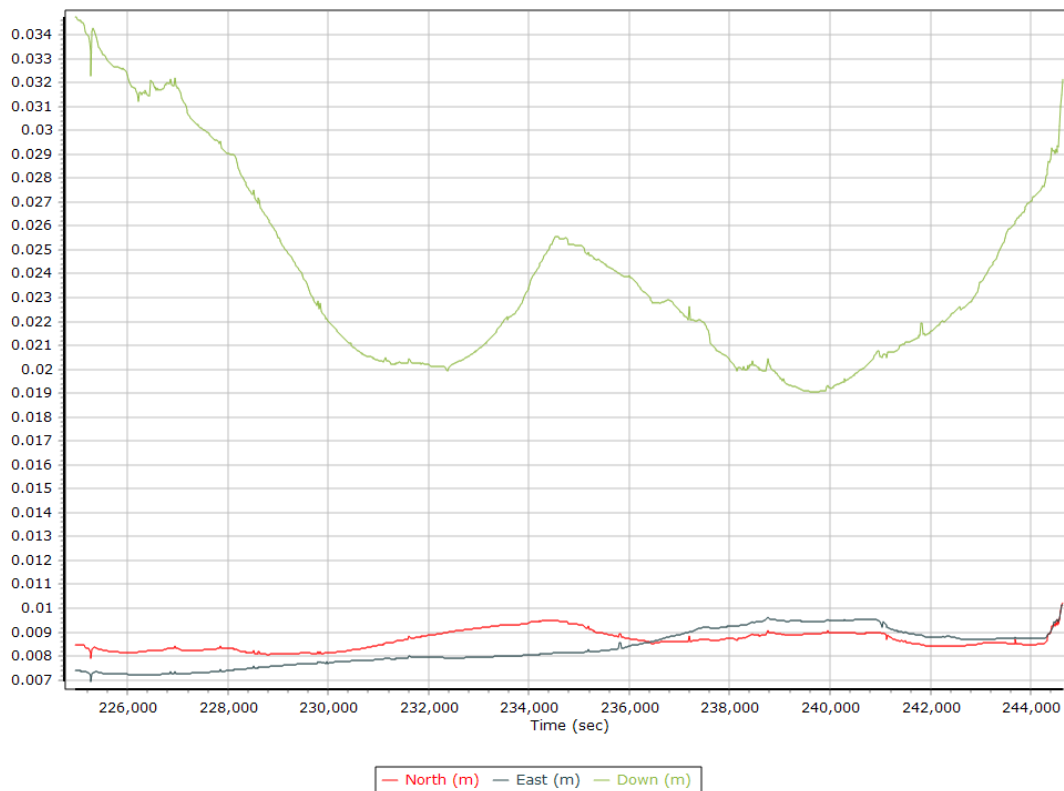
### Forward/Reverse Separation



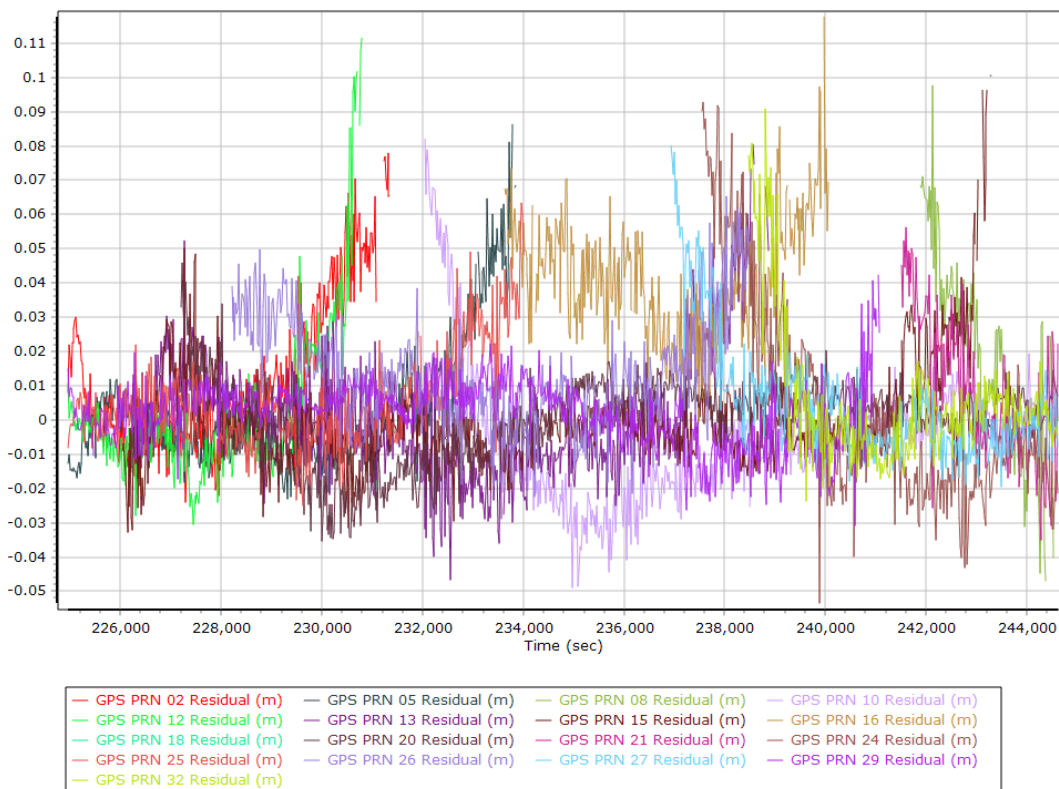
### PDOP



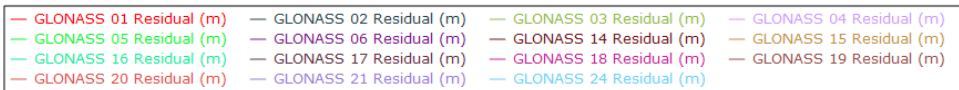
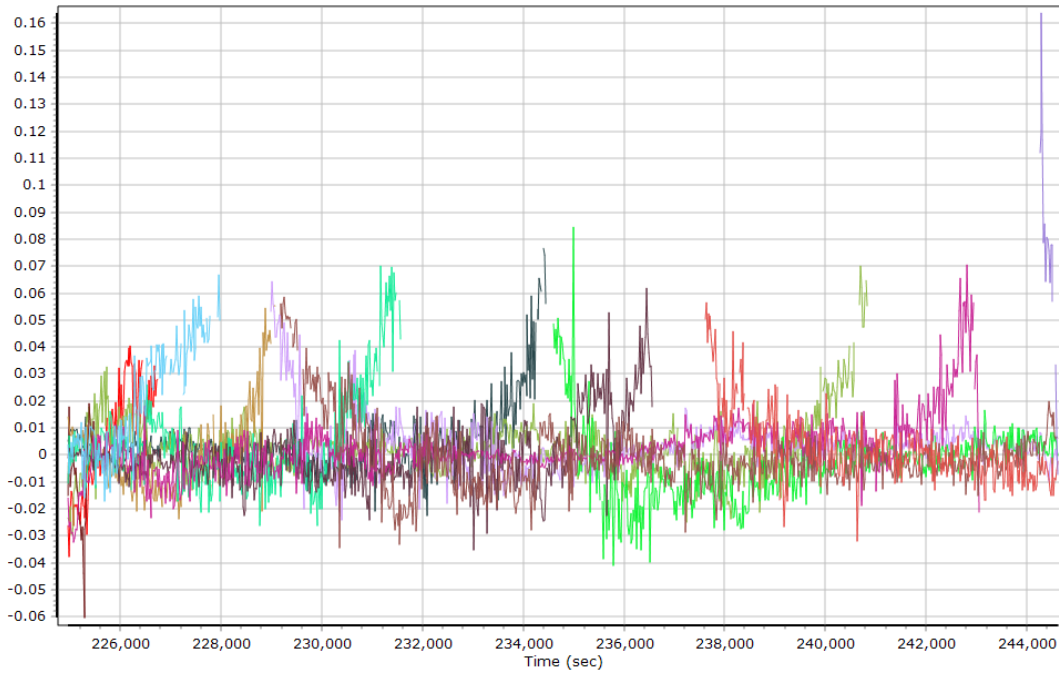
## Estimated Position Accuracy



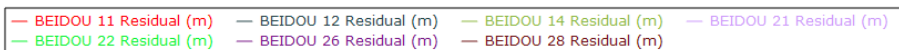
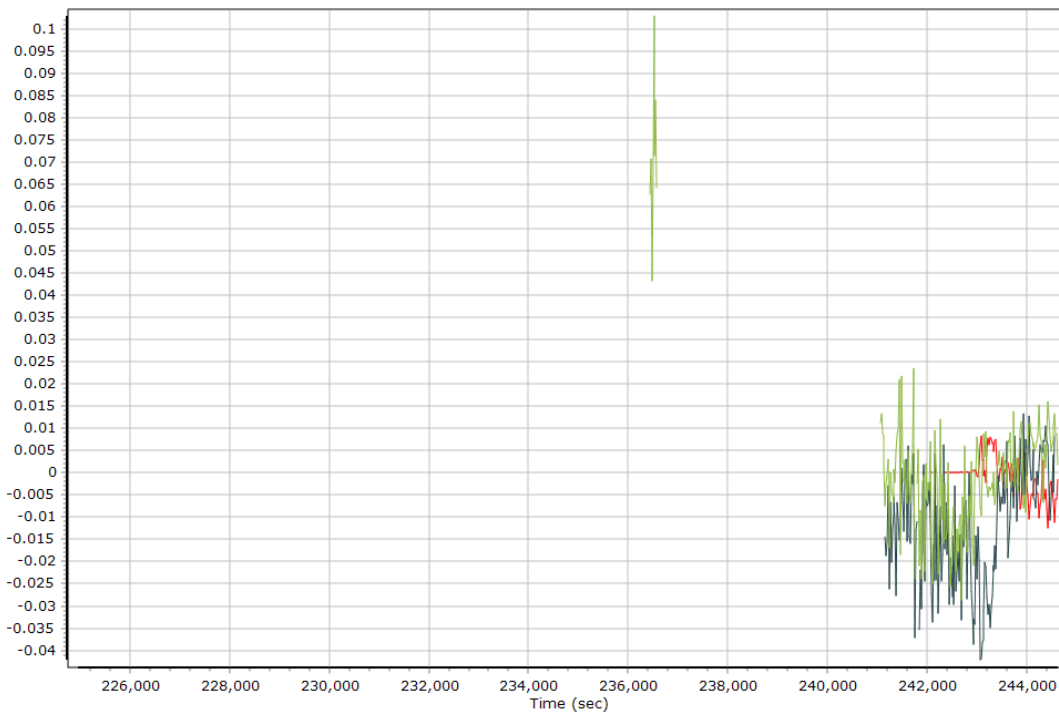
## GPS Residuals



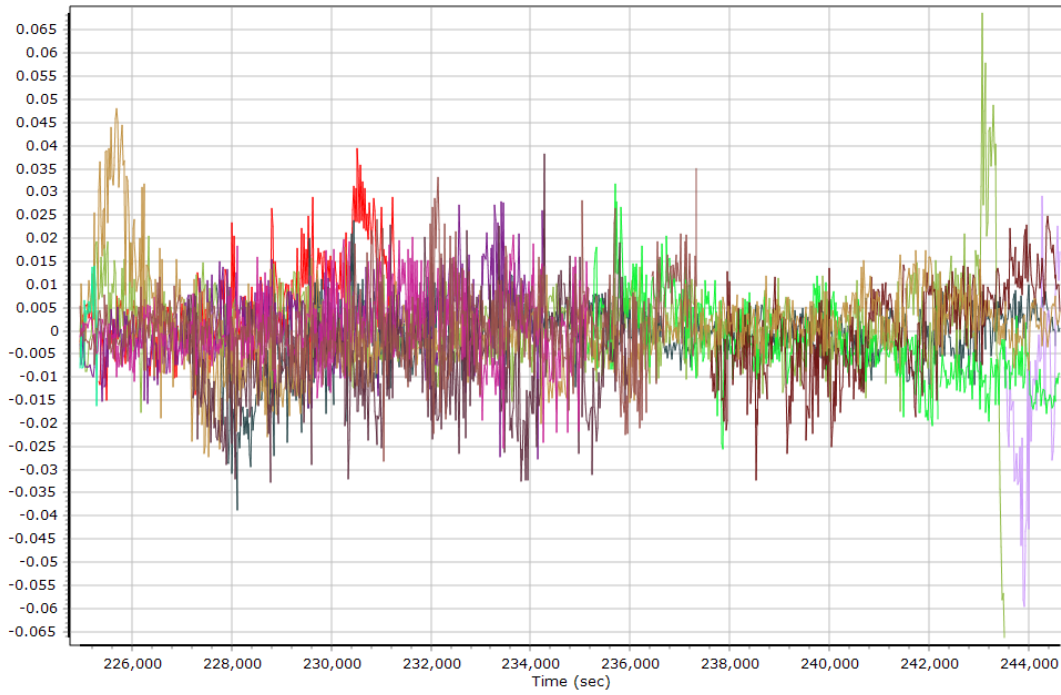
## GLONASS Residuals



## BEIDOU Residuals



## GALILEO Residuals



- |                         |                         |                         |                         |
|-------------------------|-------------------------|-------------------------|-------------------------|
| GALILEO 02 Residual (m) | GALILEO 03 Residual (m) | GALILEO 05 Residual (m) | GALILEO 07 Residual (m) |
| GALILEO 08 Residual (m) | GALILEO 09 Residual (m) | GALILEO 13 Residual (m) | GALILEO 15 Residual (m) |
| GALILEO 25 Residual (m) | GALILEO 27 Residual (m) | GALILEO 30 Residual (m) | GALILEO 36 Residual (m) |

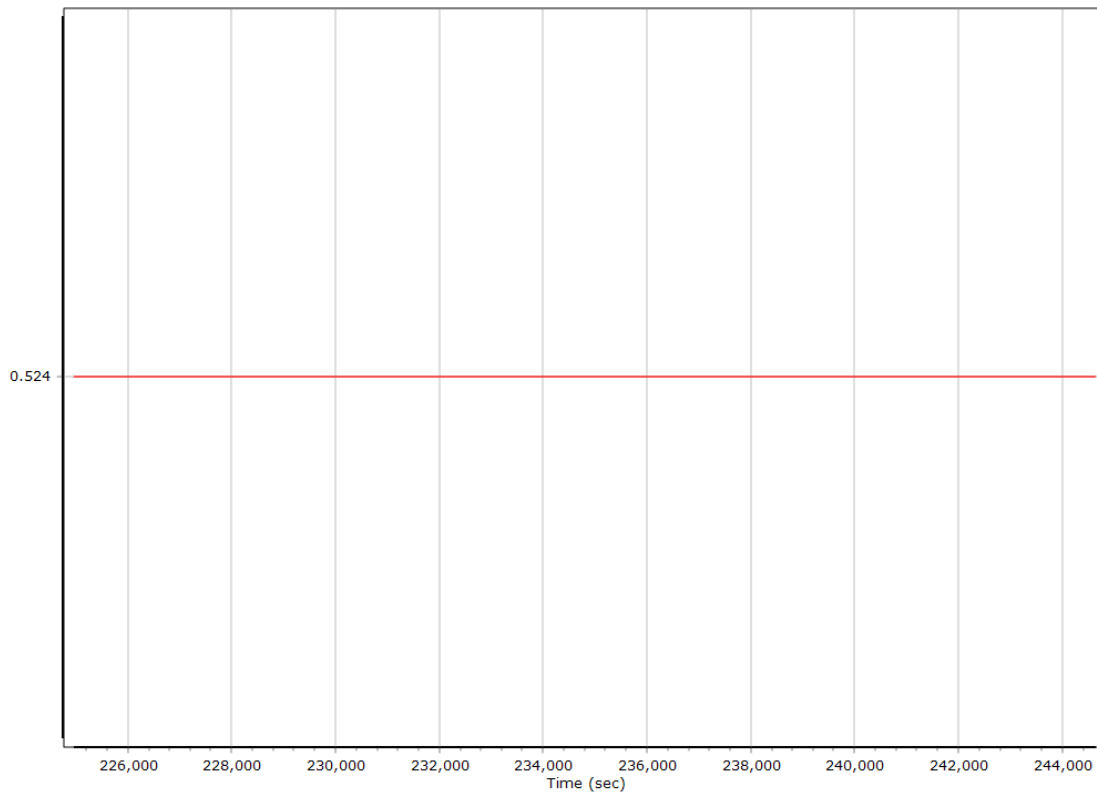
## GNSS-Inertial Processor Configuration

Processing mode	IN-Fusion PP-RTX		
Stabilized mount	False		
Processing start time	224543.000 (9/29/2020 2:22:23 PM)		
Processing end time	244654.000 (9/29/2020 7:57:34 PM)		
Initial attitude source	Real-Time VNAV/RNAV Attitude		
IMU Sensor Context	Processing with Onboard IMU		
Reference to IMU lever arm (m)	0.000	0.000	0.000
Reference to IMU mounting angles (deg)	0.000	0.000	-90.000
Reference to Primary GNSS lever arm (m)	0.524	0.220	-1.195
Reference to Primary GNSS lever arm std dev (m)	0.030	0.030	0.030
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

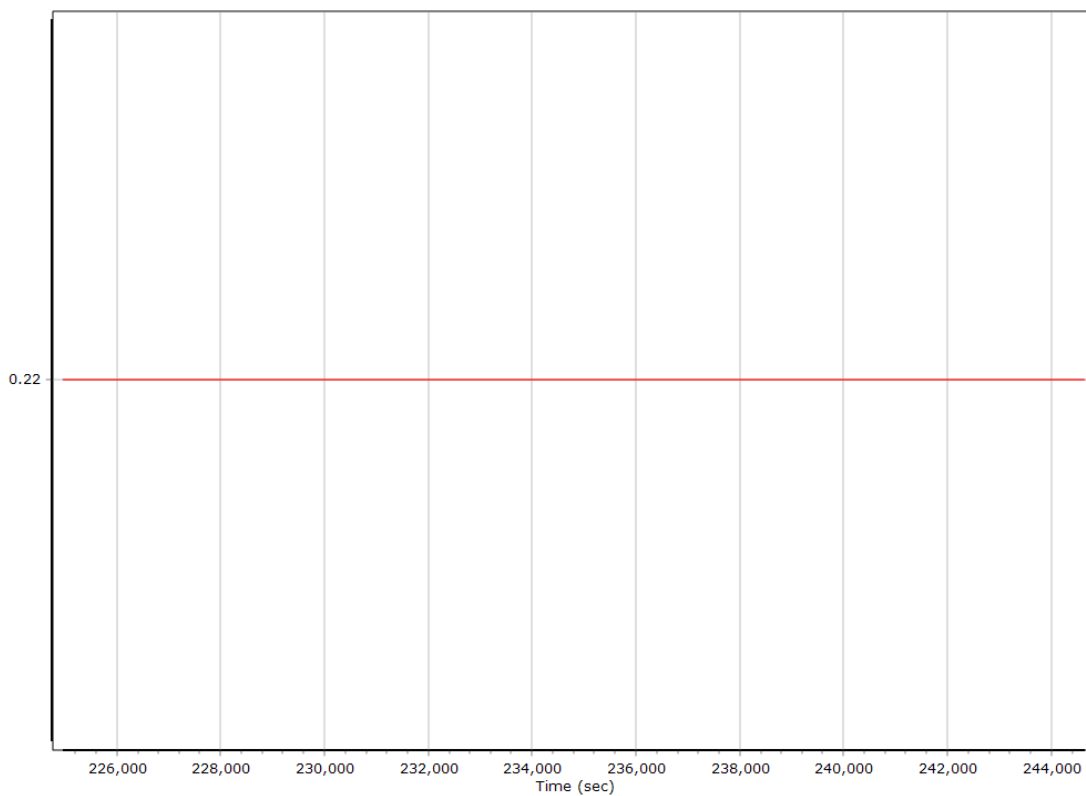
## Calibrated Installation Parameters

### Reference-Primary GNSS Lever Arm (m)

#### X Reference-Primary GNSS Lever Arm (m)

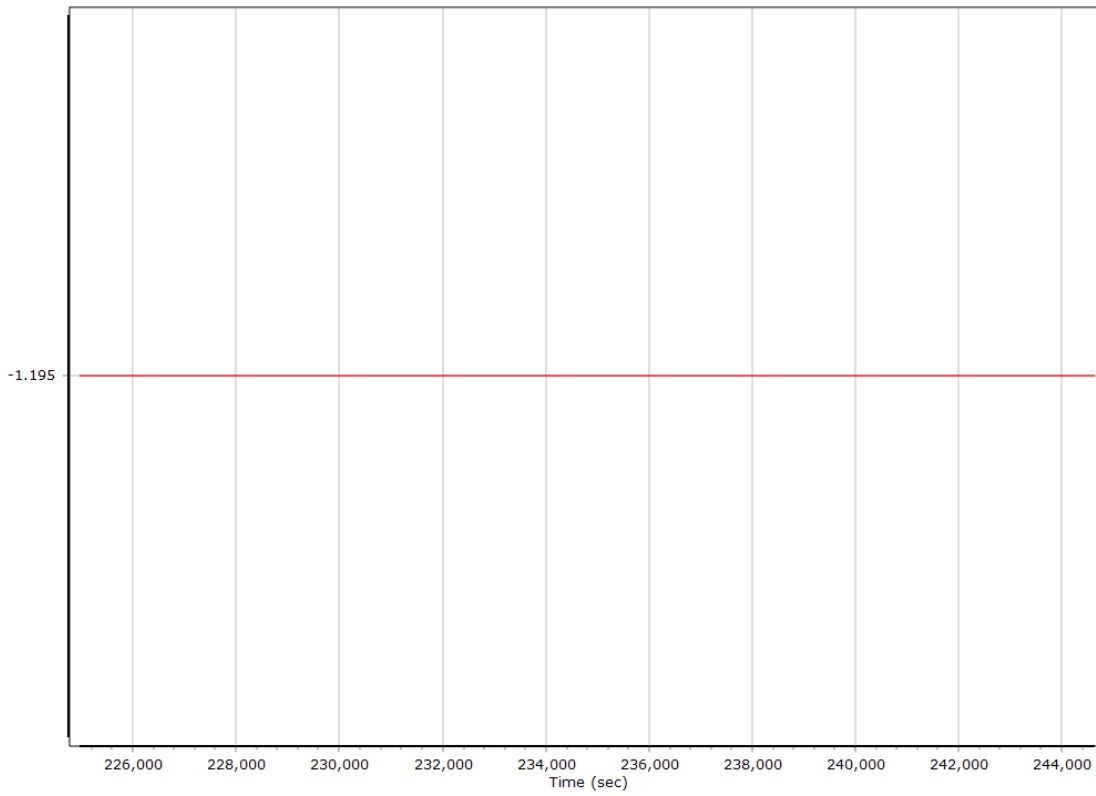


#### Y Reference-Primary GNSS Lever Arm (m)

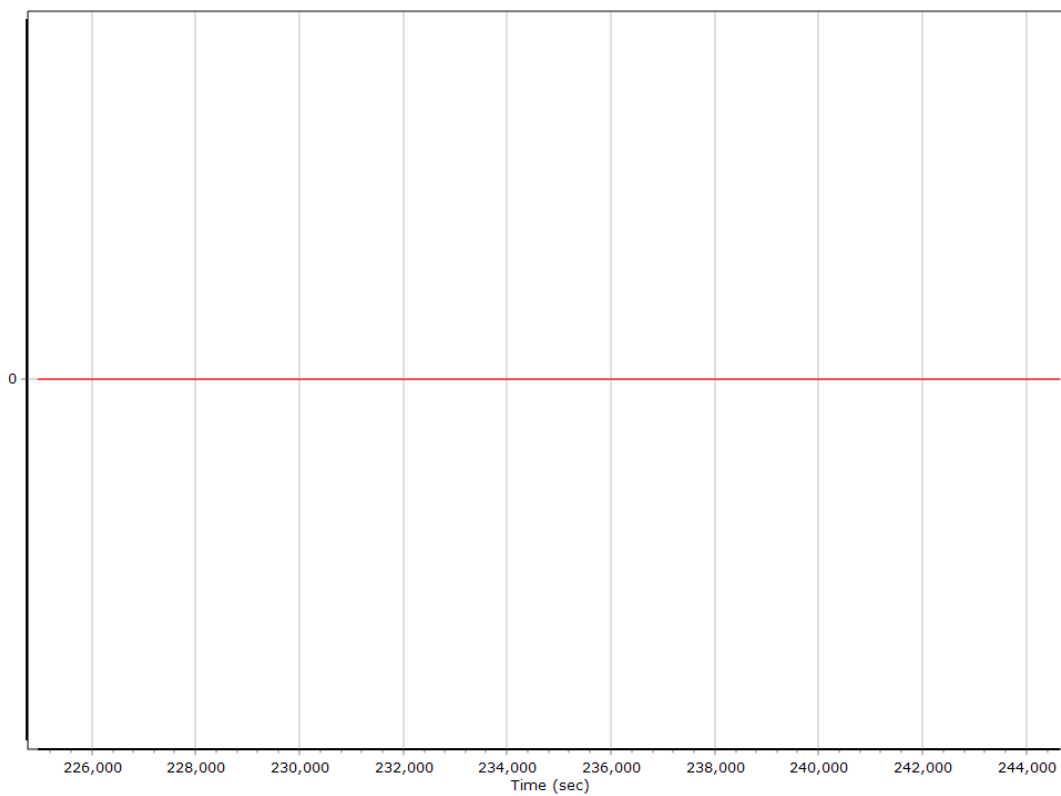




### Z Reference-Primary GNSS Lever Arm (m)



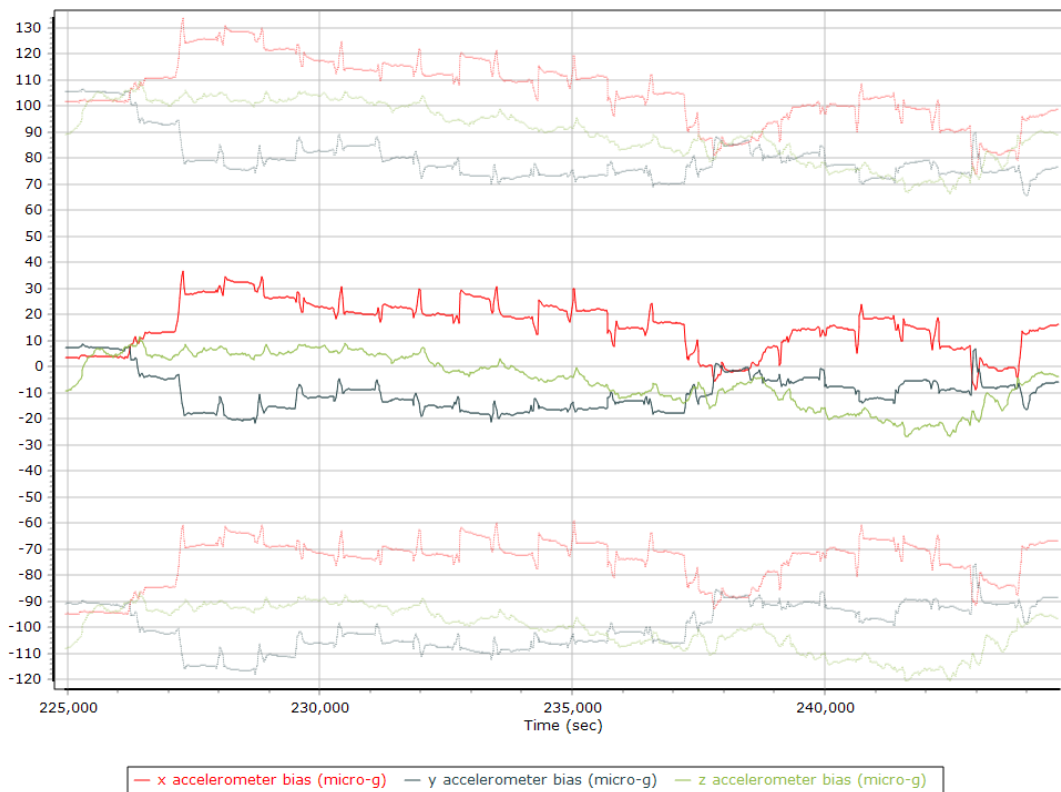
### Reference-Primary GNSS Lever Arm Figure of Merit



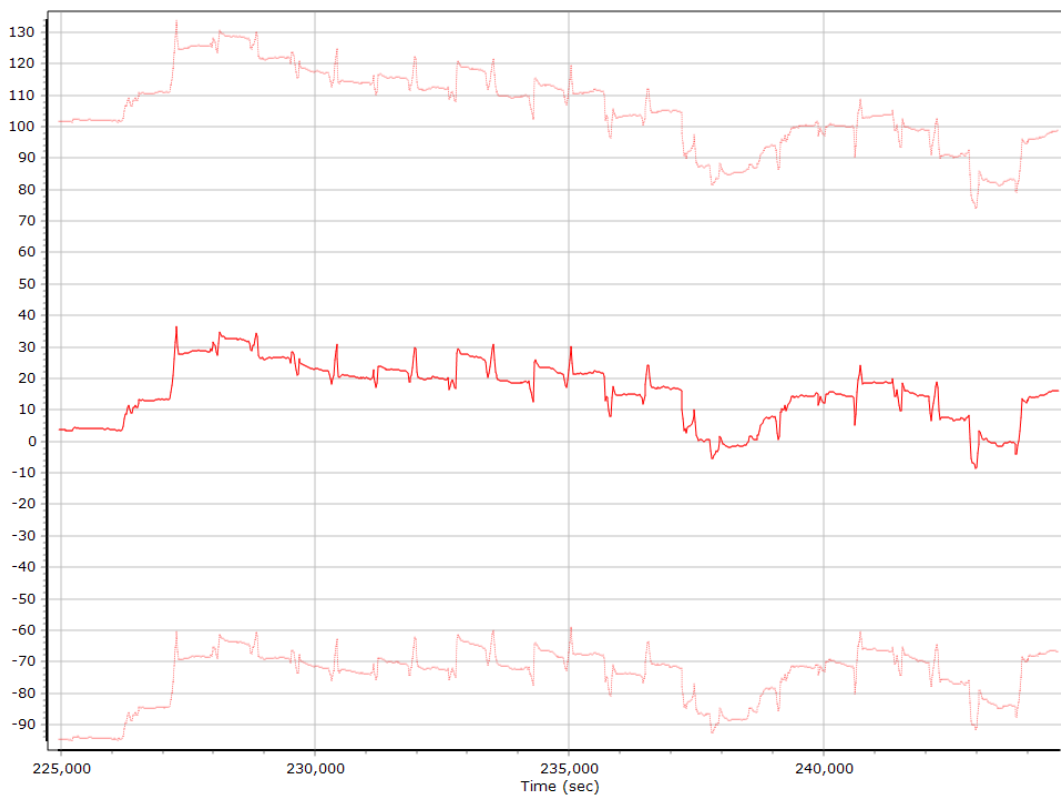
## IN-Fusion QC

### Forward Processed Estimated Errors, Reference Frame

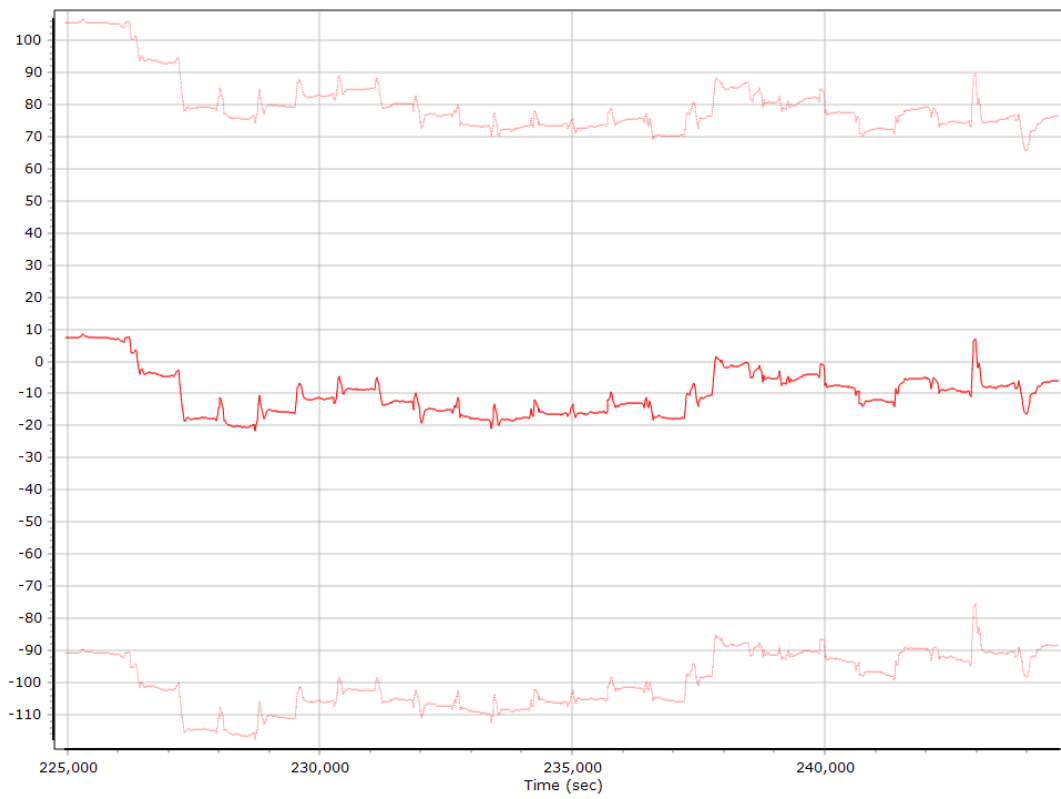
#### Accelerometer Bias (micro-g)



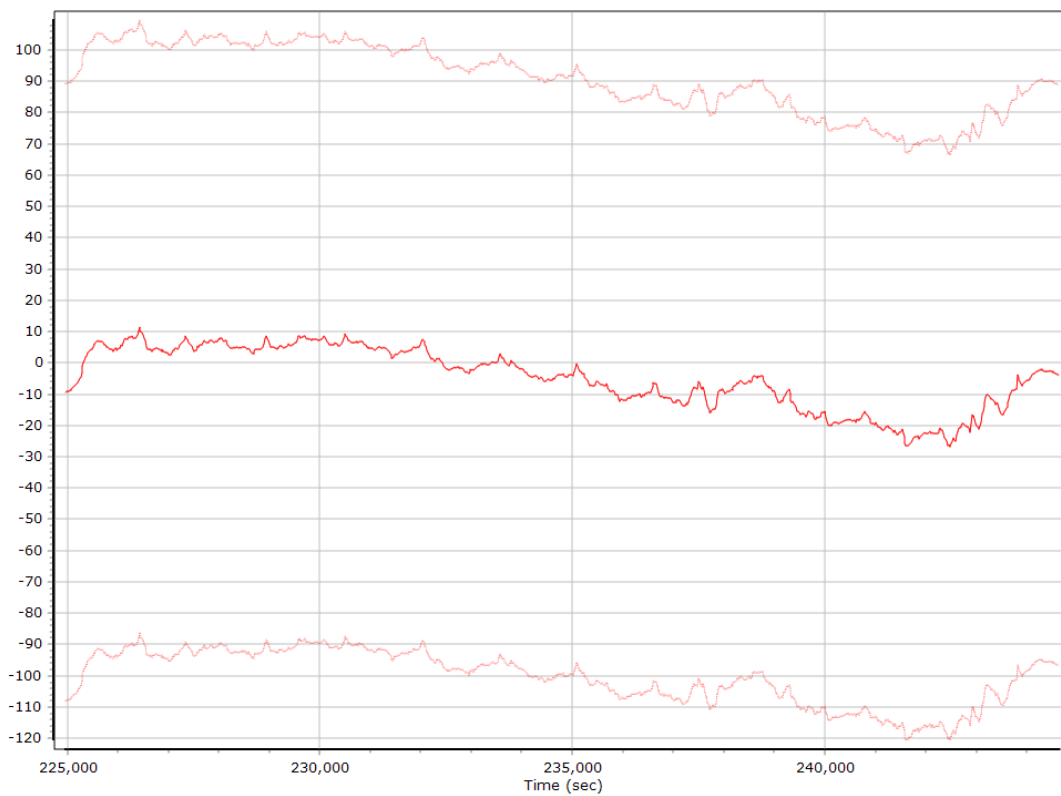
#### X Accelerometer Bias (micro-g)



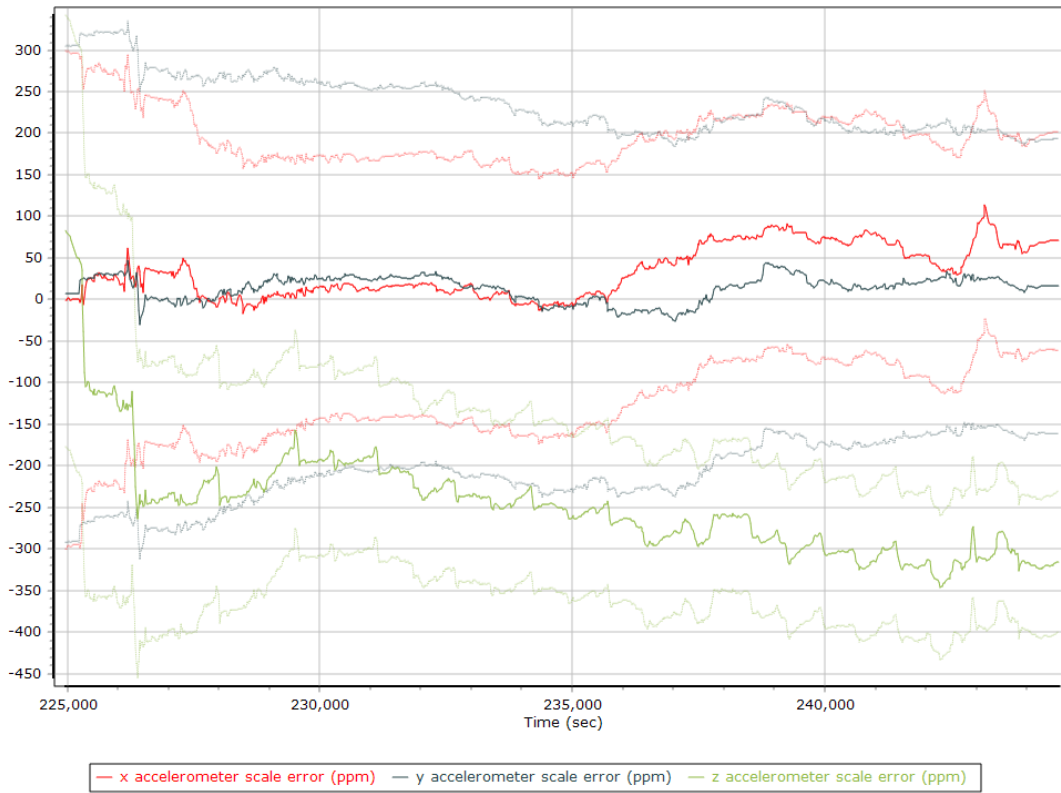
### Y Accelerometer Bias (micro-g)



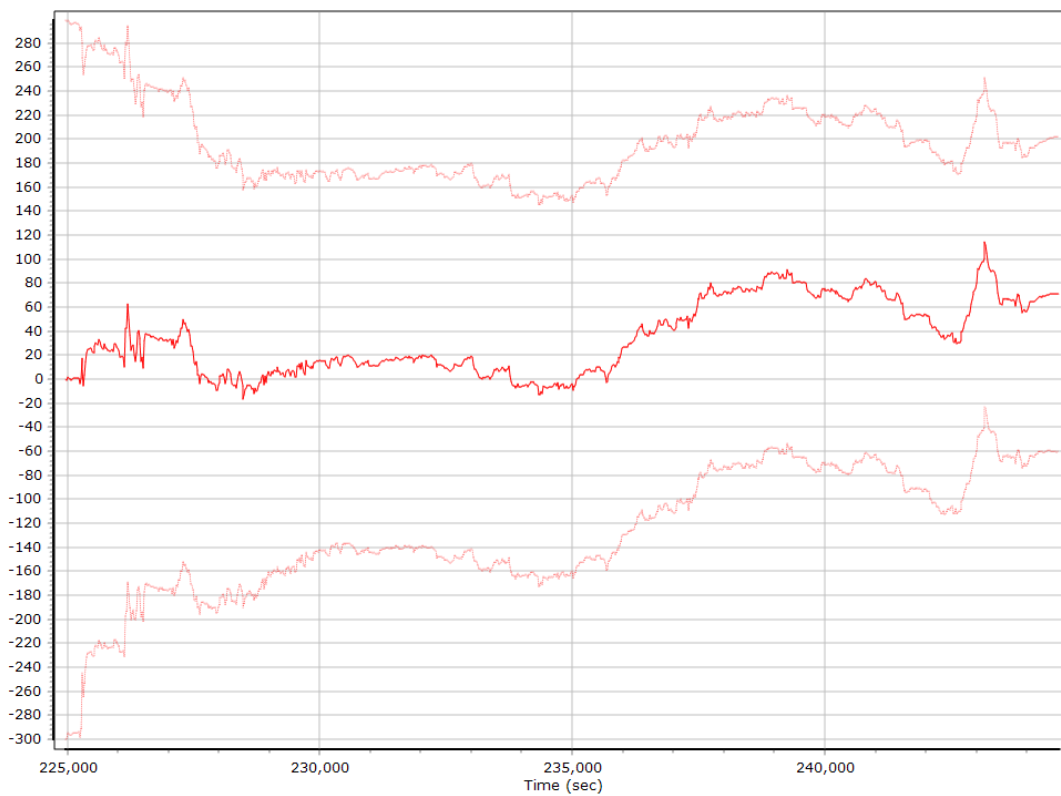
### Z Accelerometer Bias (micro-g)



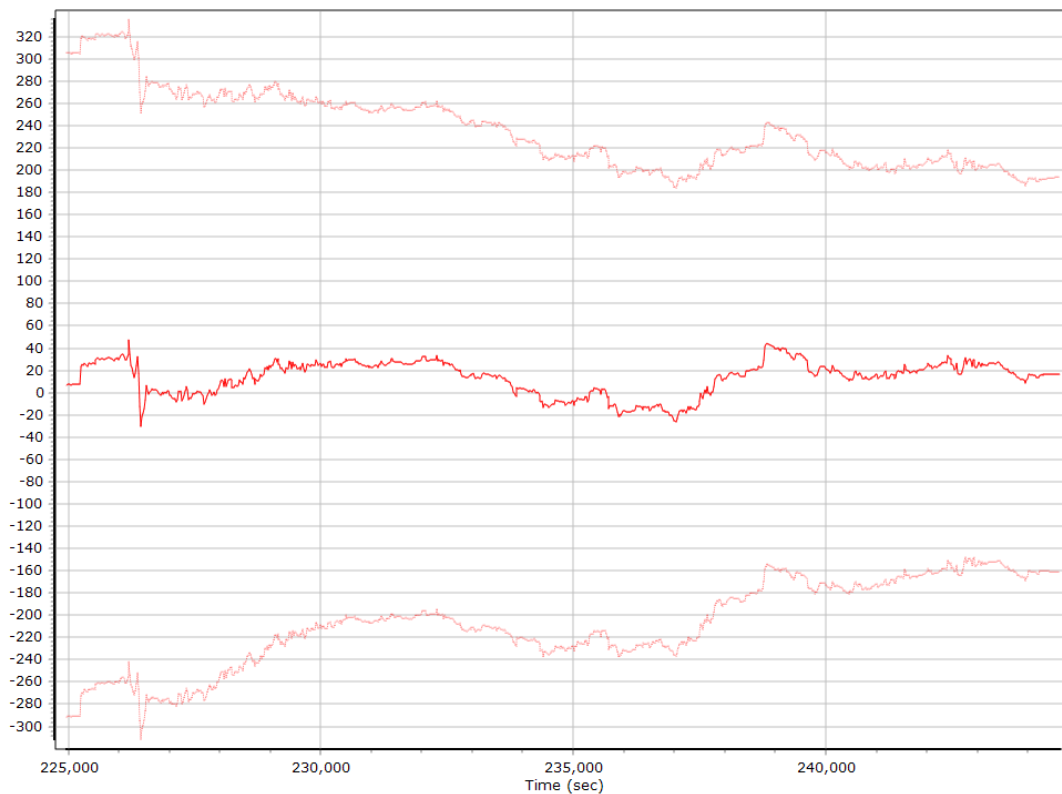
### Accelerometer Scale Error (ppm)



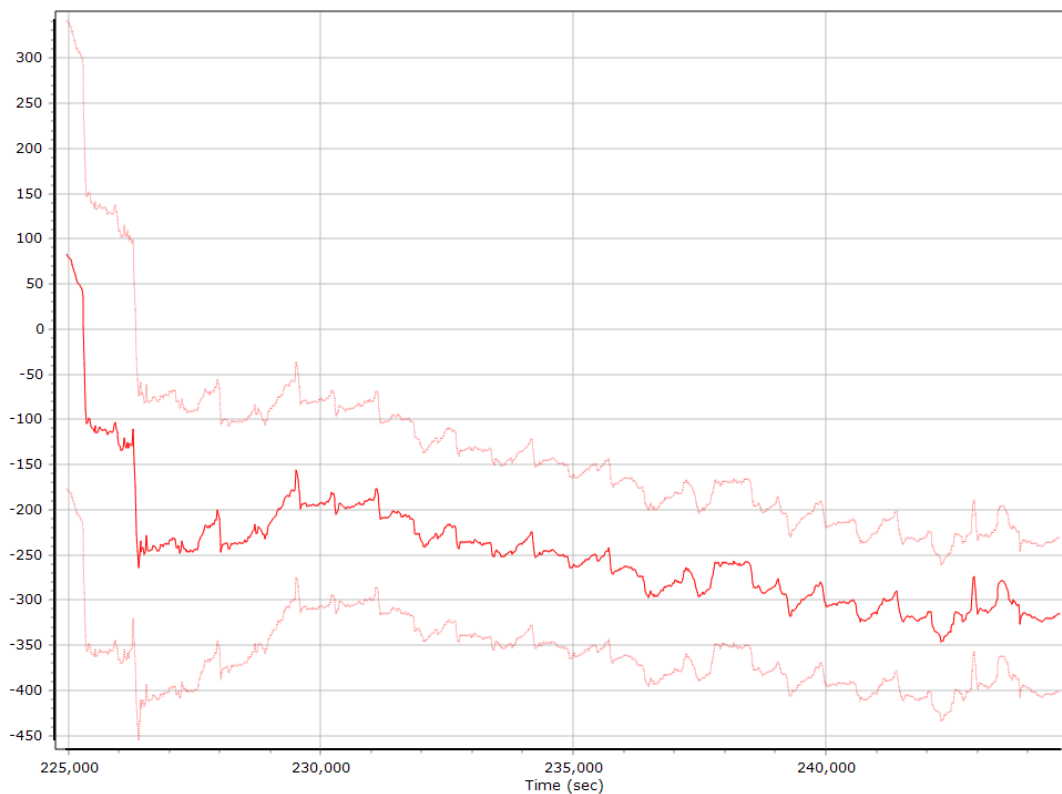
### X Accelerometer Scale Error (ppm)



### Y Accelerometer Scale Error (ppm)



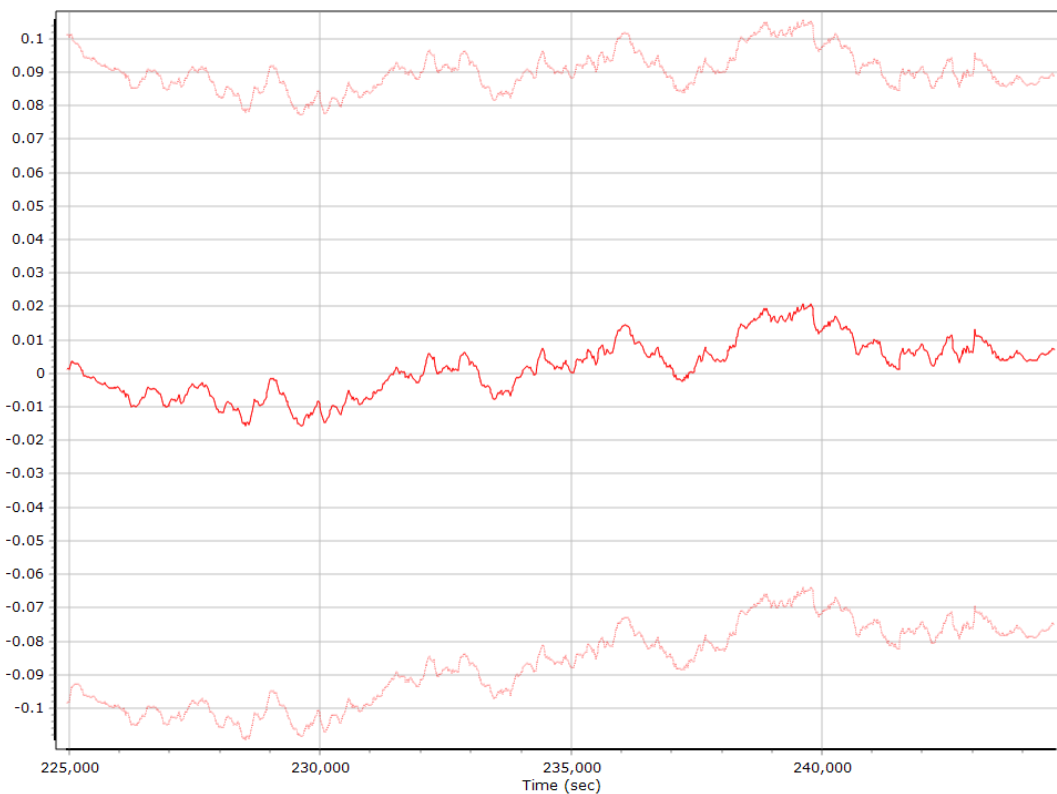
### Z Accelerometer Scale Error (ppm)



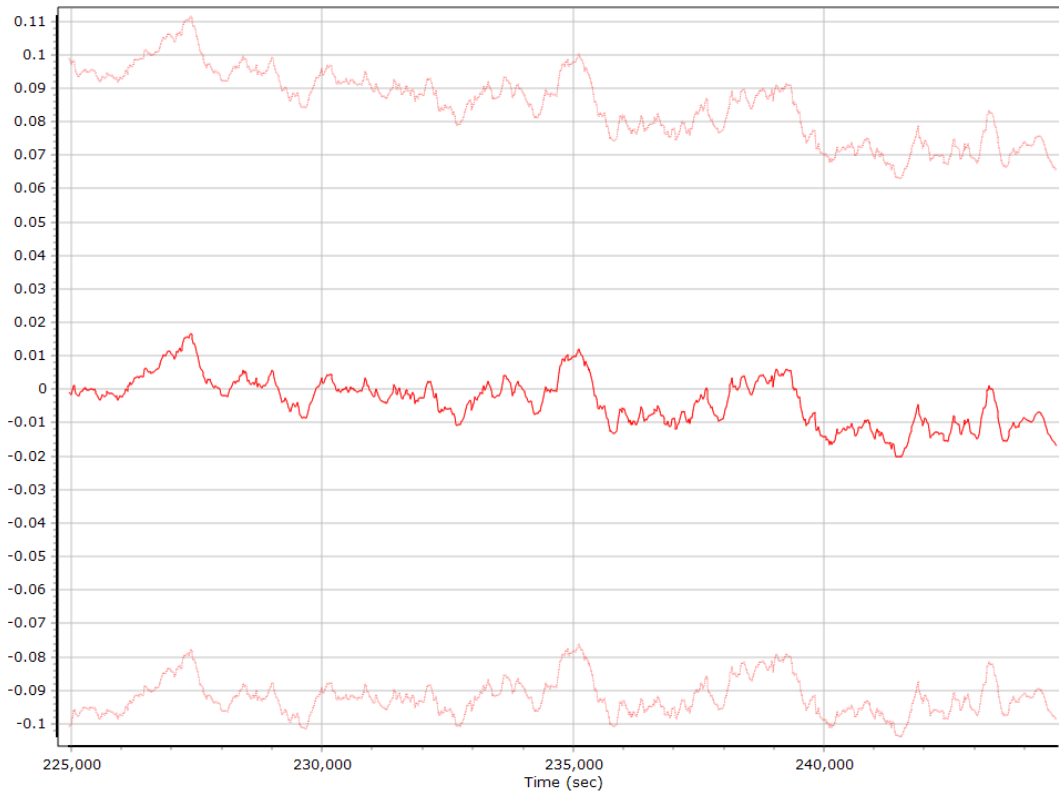
### Gyro Bias (deg/h)



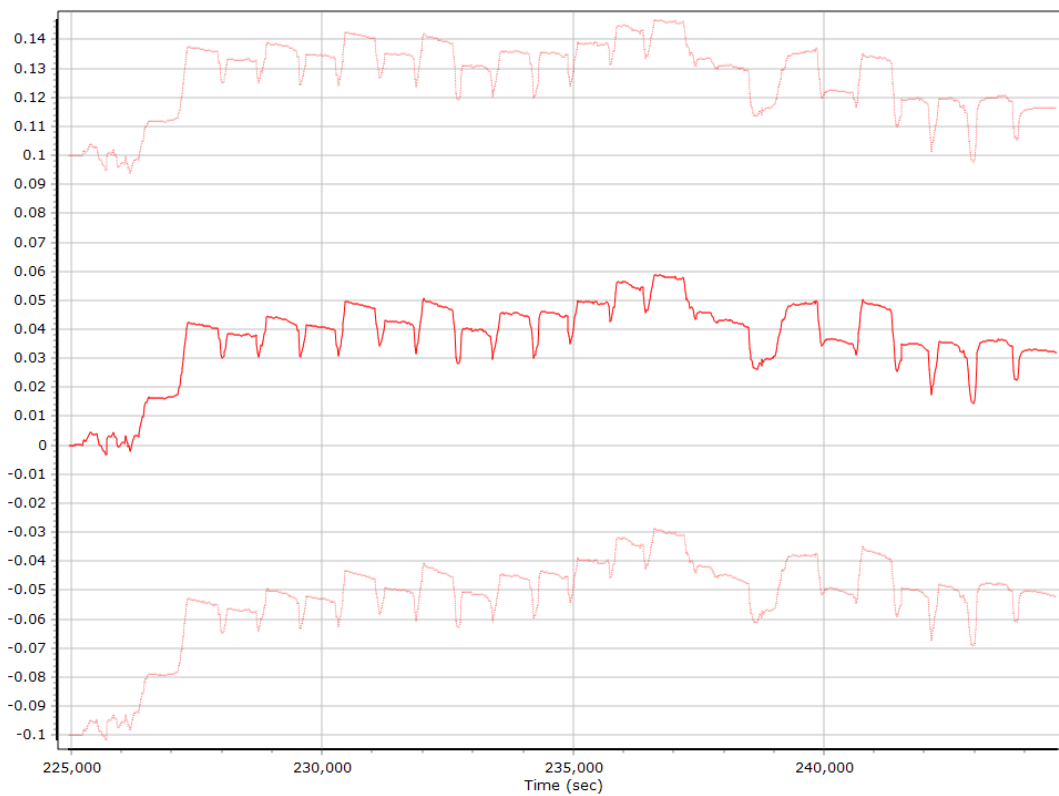
### X Gyro Bias (deg/h)



### Y Gyro Bias (deg/h)



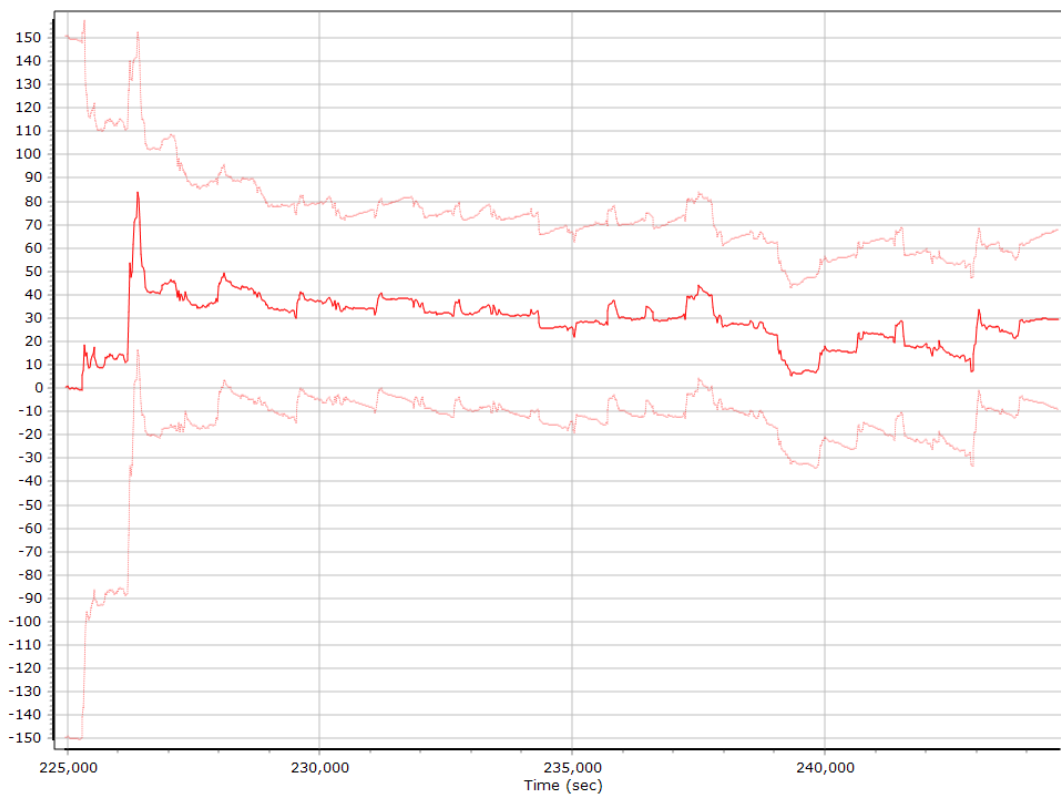
### Z Gyro Bias (deg/h)



### Gyro Scale Error (ppm)

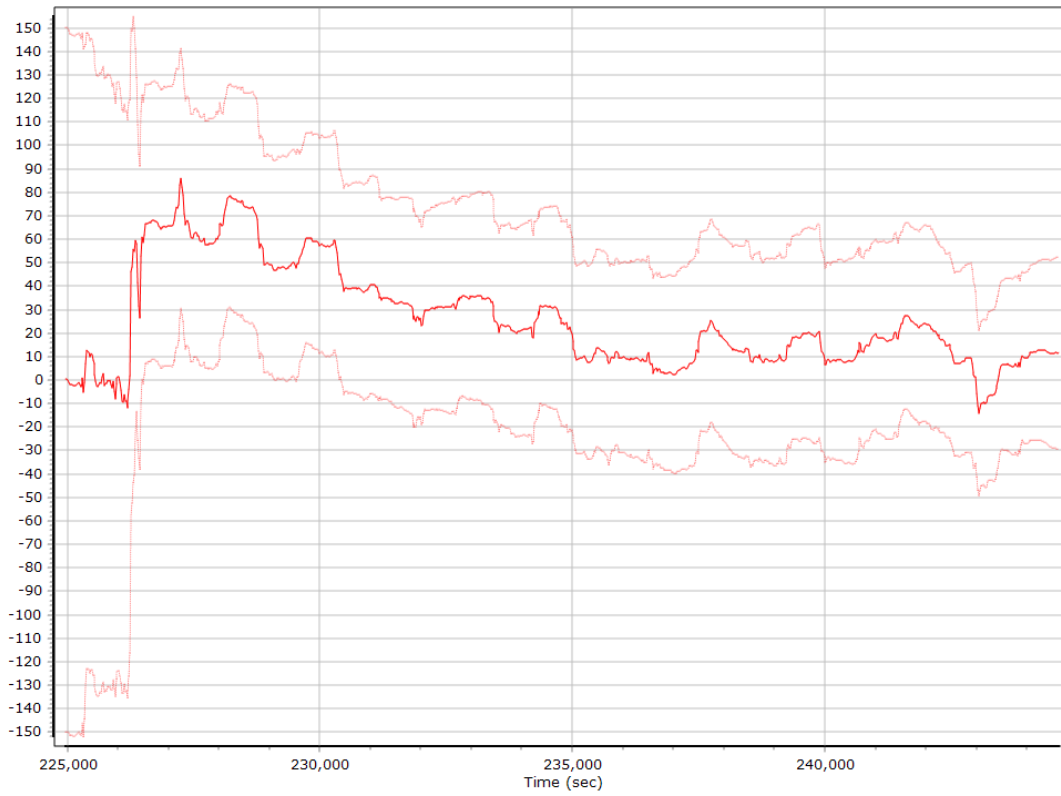


### X Gyro Scale Error (ppm)

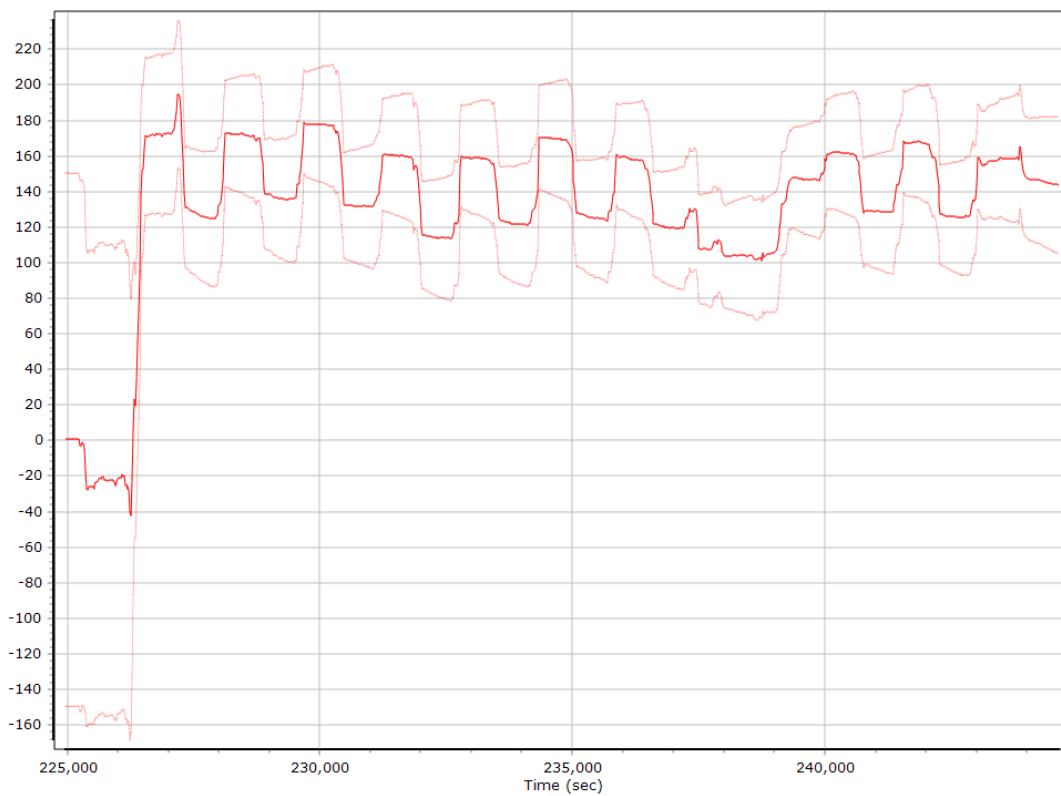




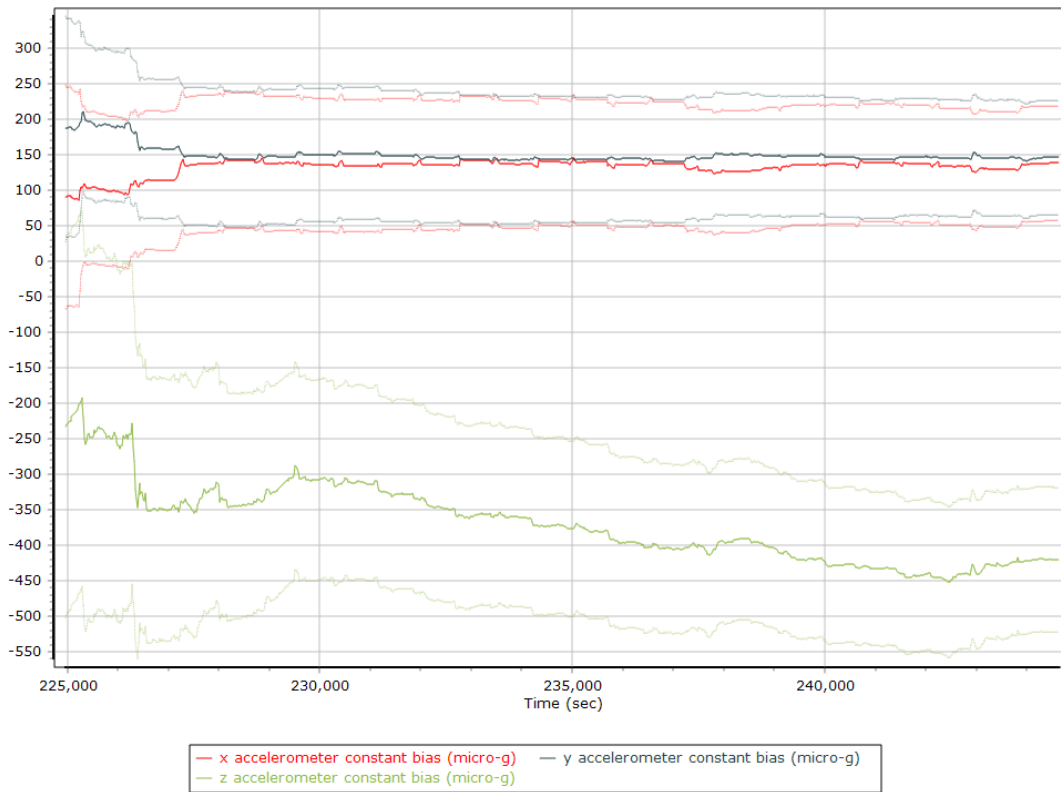
### Y Gyro Scale Error (ppm)



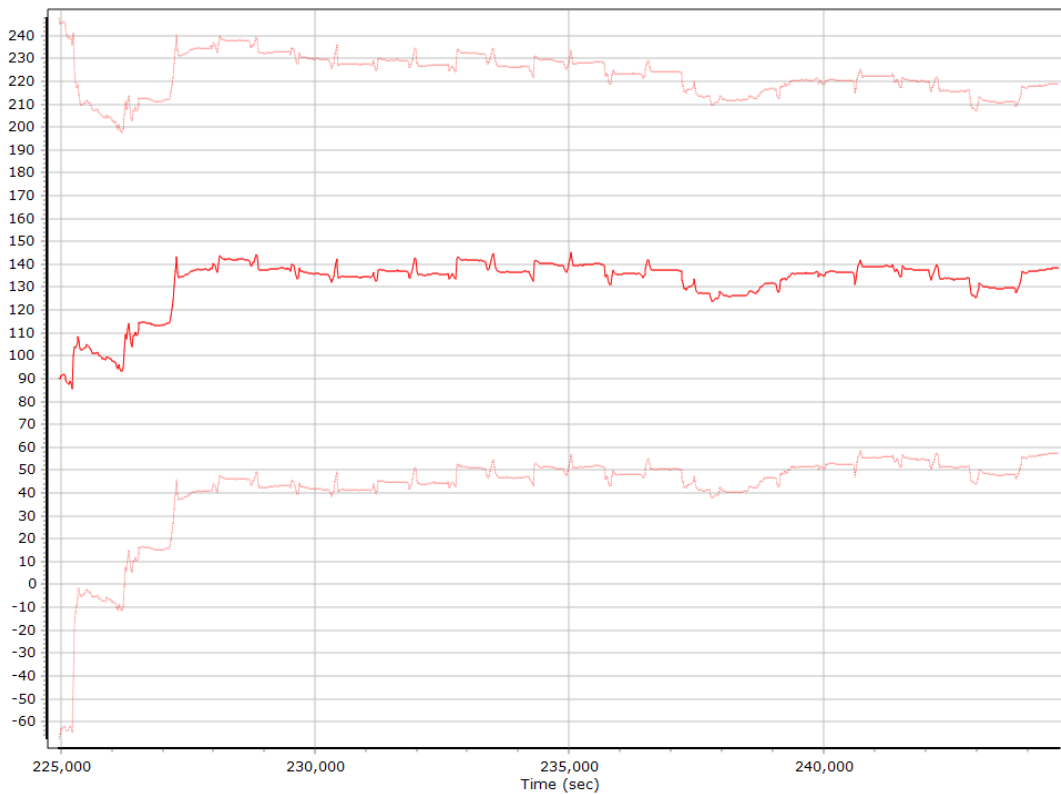
### Z Gyro Scale Error (ppm)



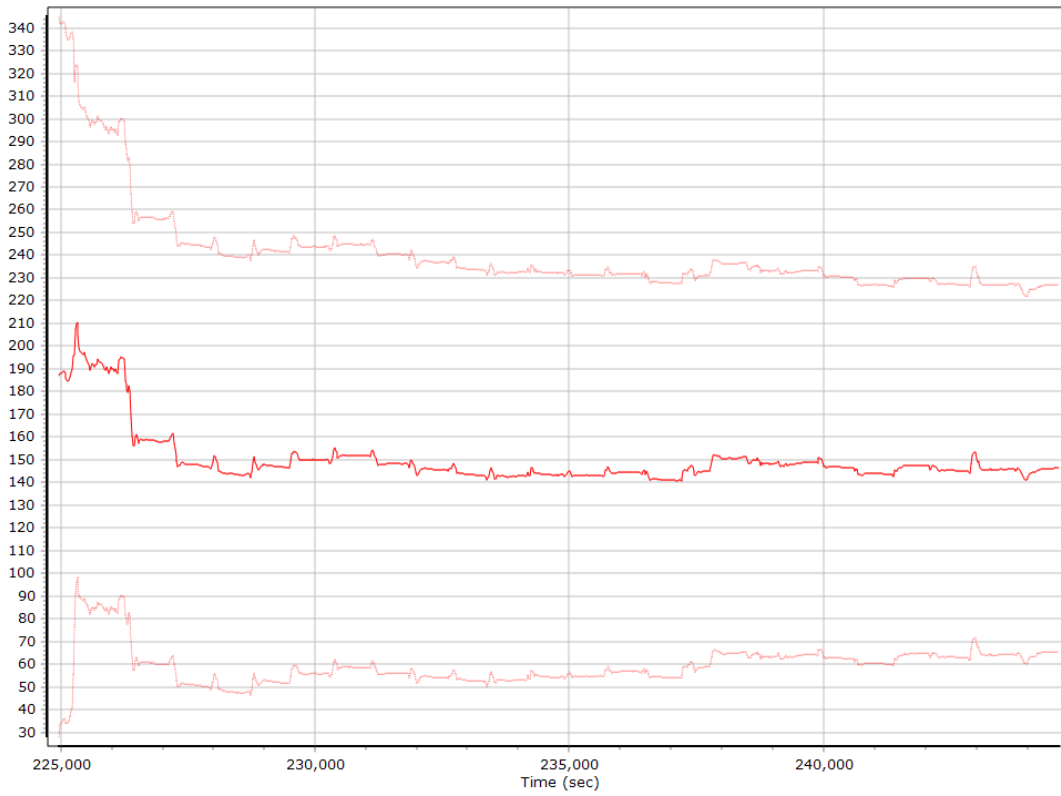
## Forward Processed Estimated Constant Errors, Reference Frame Accelerometer Bias (micro-g)



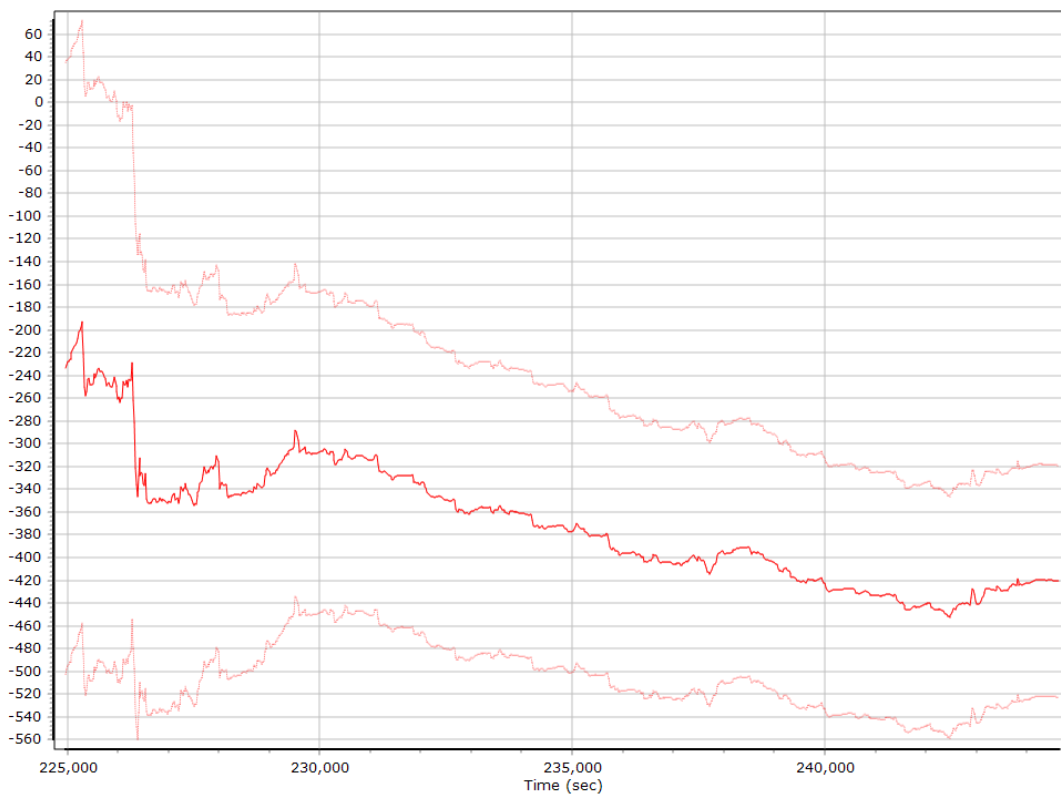
## X Accelerometer Bias (micro-g)



### Y Accelerometer Bias (micro-g)



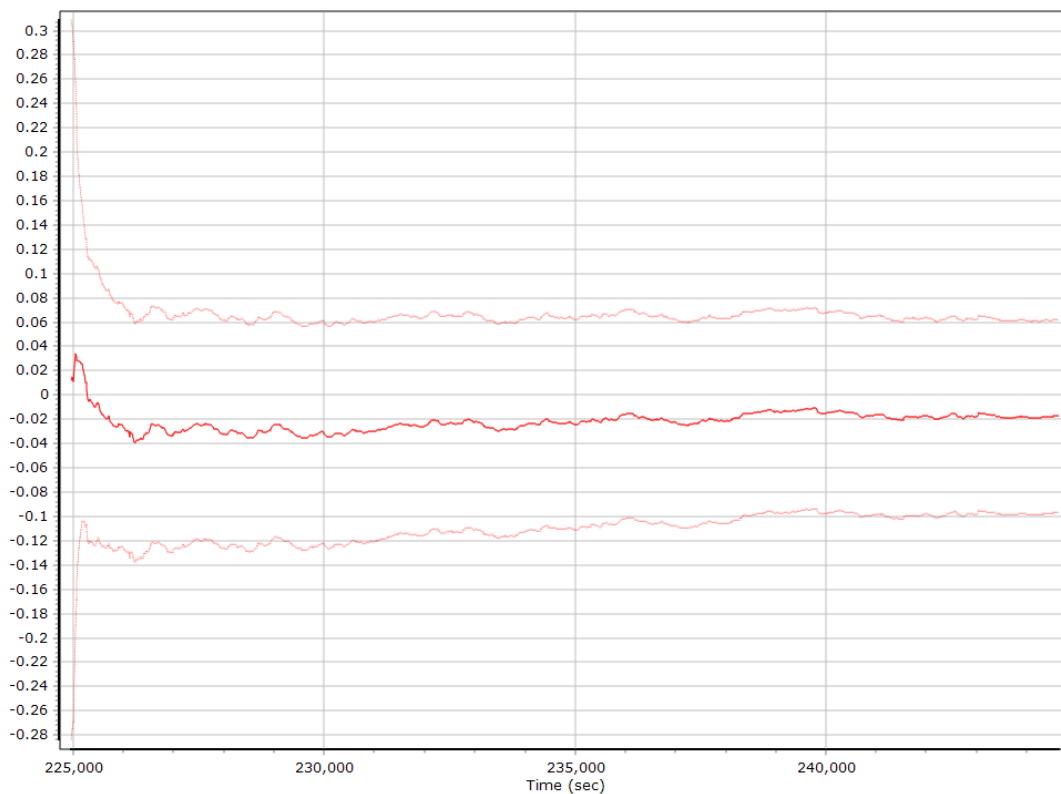
### Z Accelerometer Bias (micro-g)



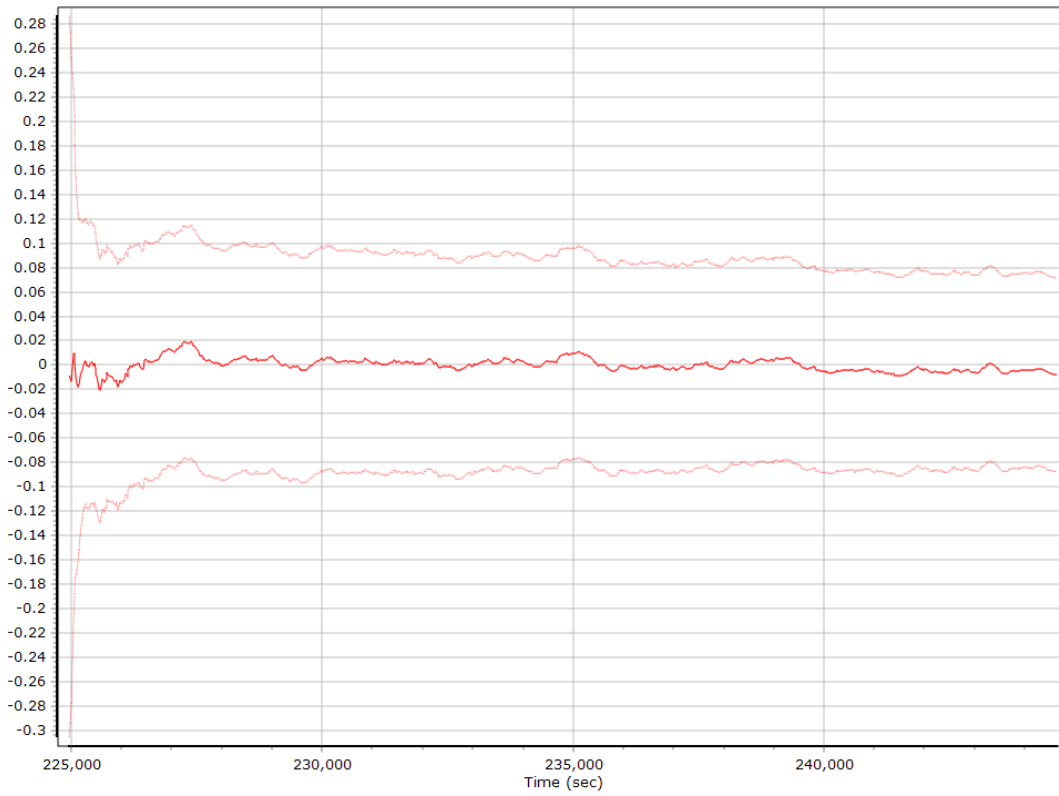
### Gyro Bias (deg/h)



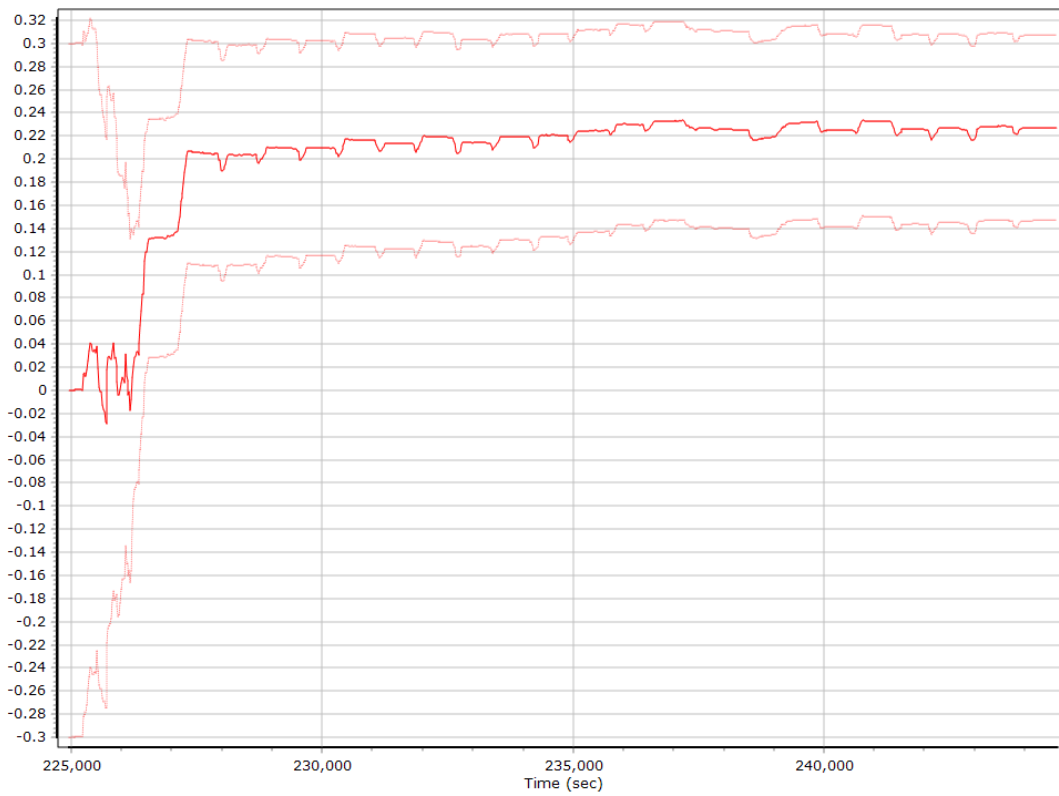
### X Gyro Bias (deg/h)



### Y Gyro Bias (deg/h)

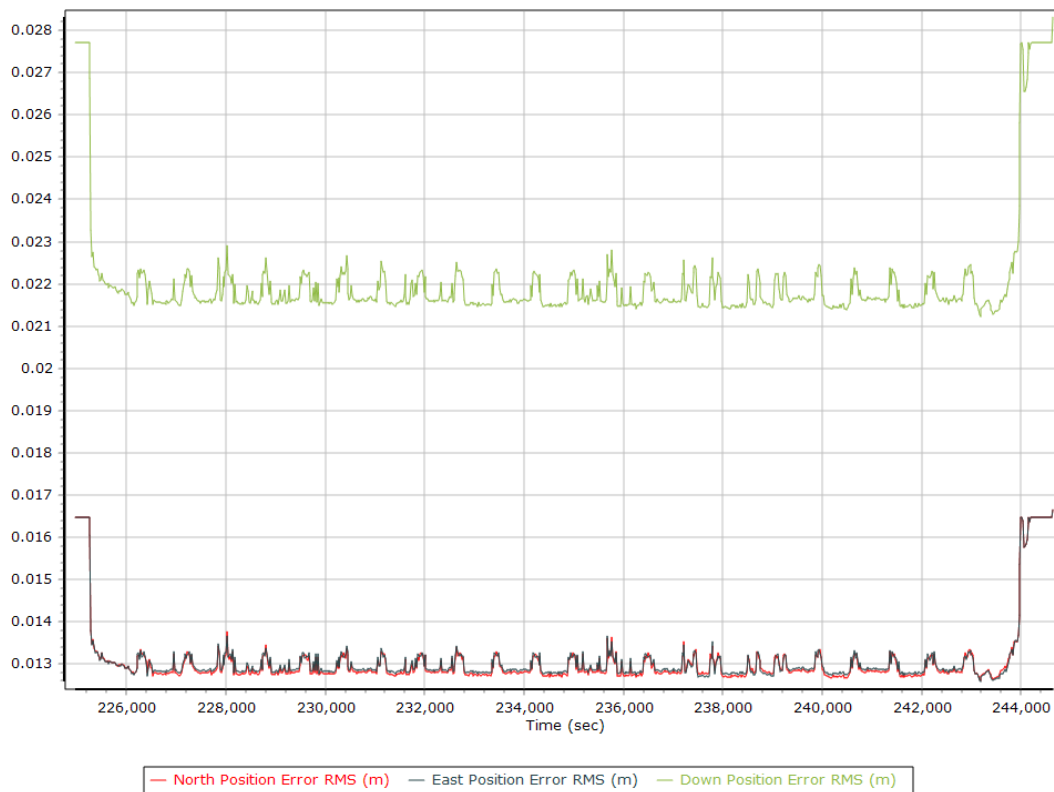


### Z Gyro Bias (deg/h)

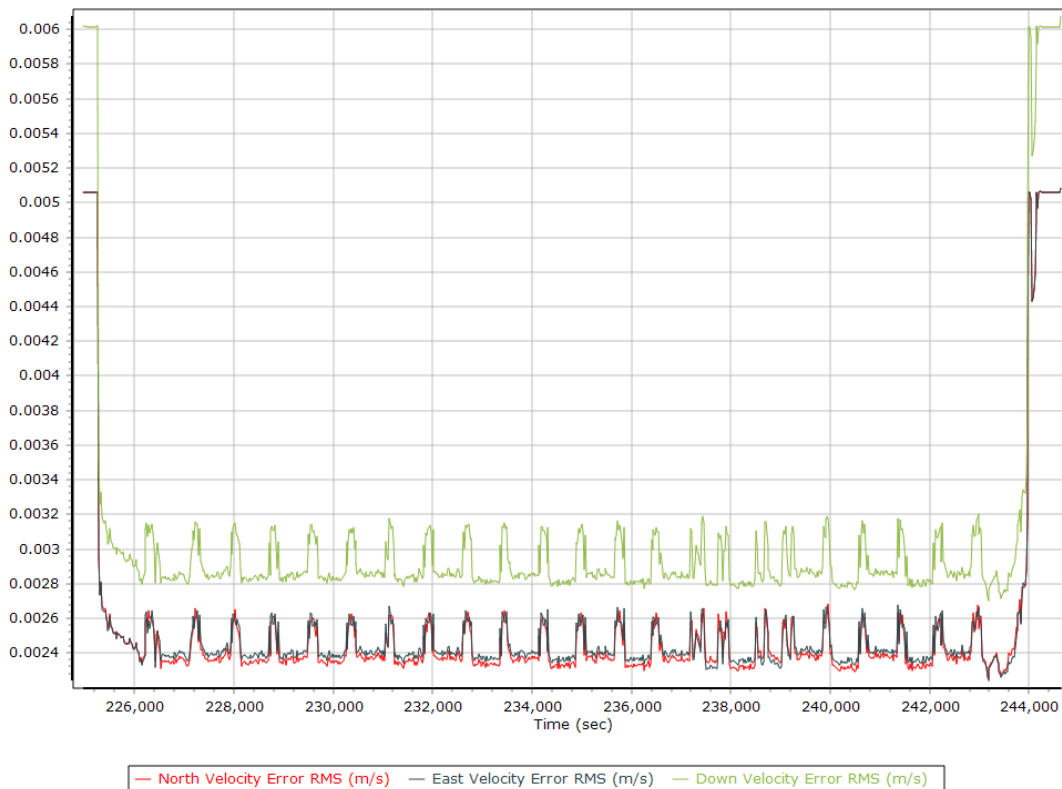


## Smoothed Performance Metrics

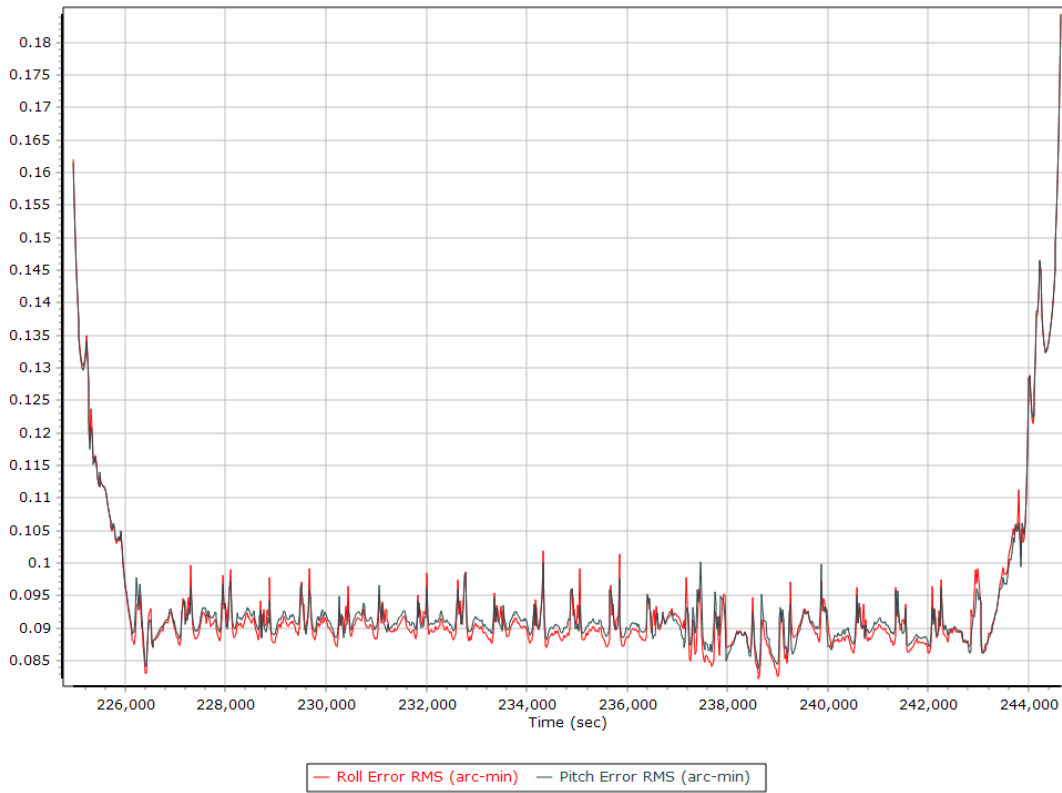
### Position Error RMS (m)



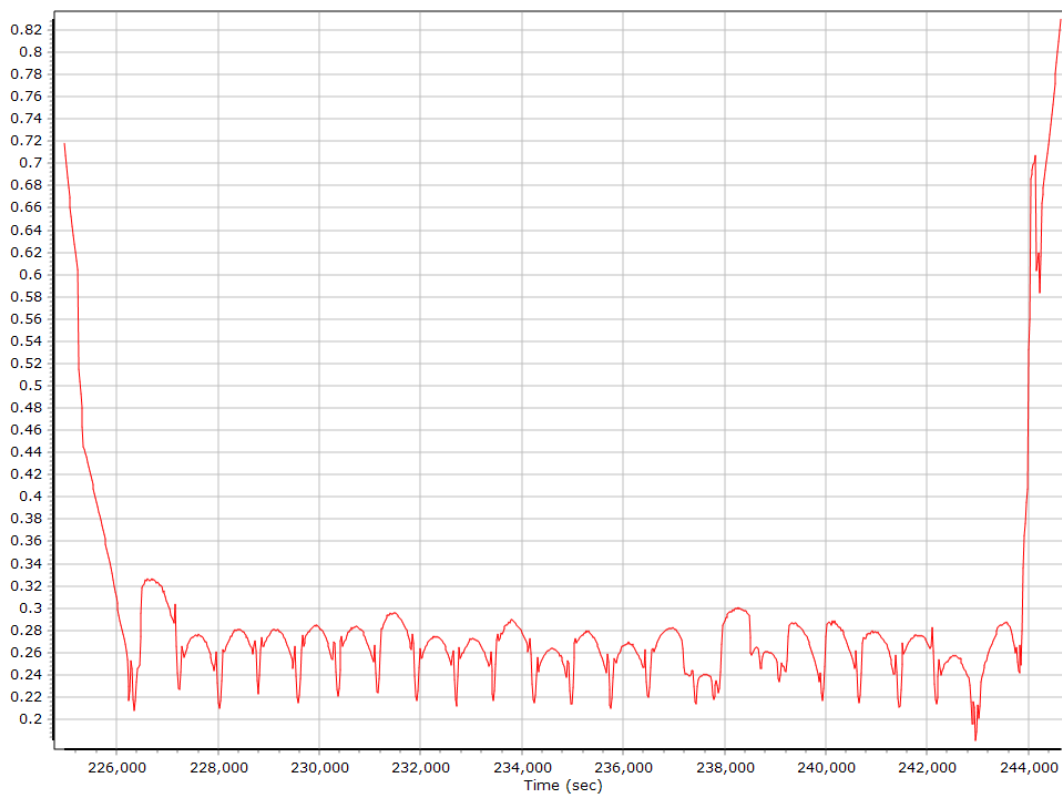
### Velocity Error RMS (m/s)



### Roll/Pitch Error RMS (arc-min)



### Heading Error RMS (arc-min)

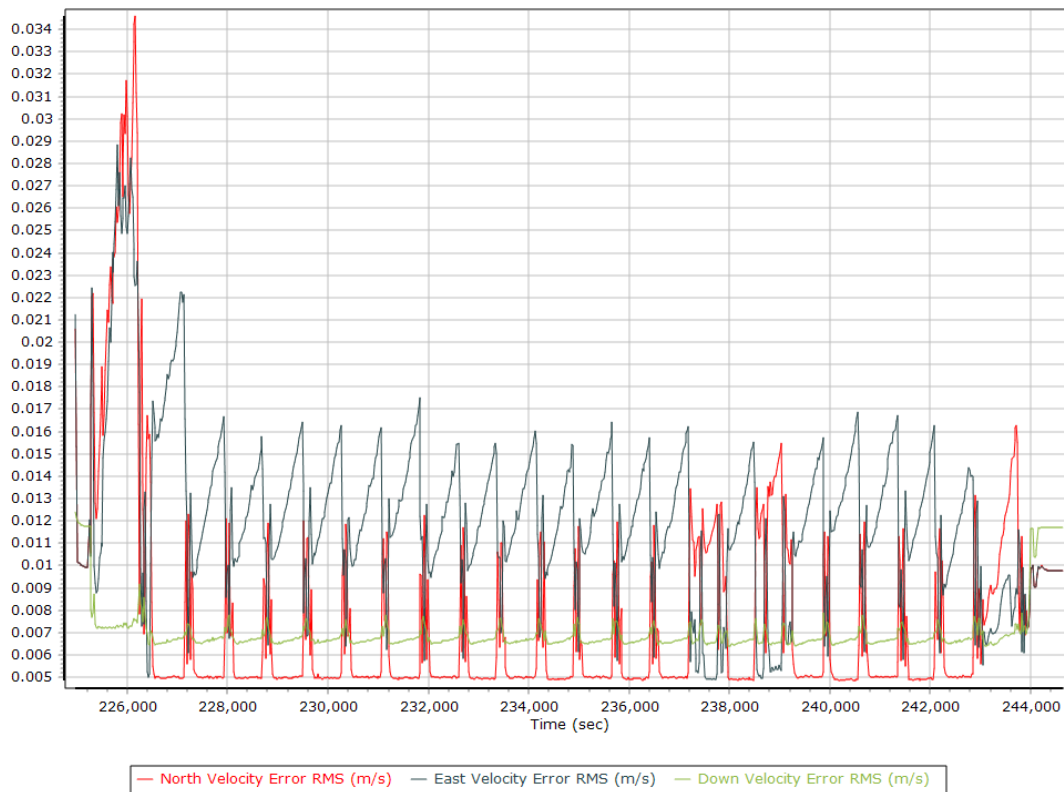


## Forward Processed Performance Metrics

### Position Error RMS (m)

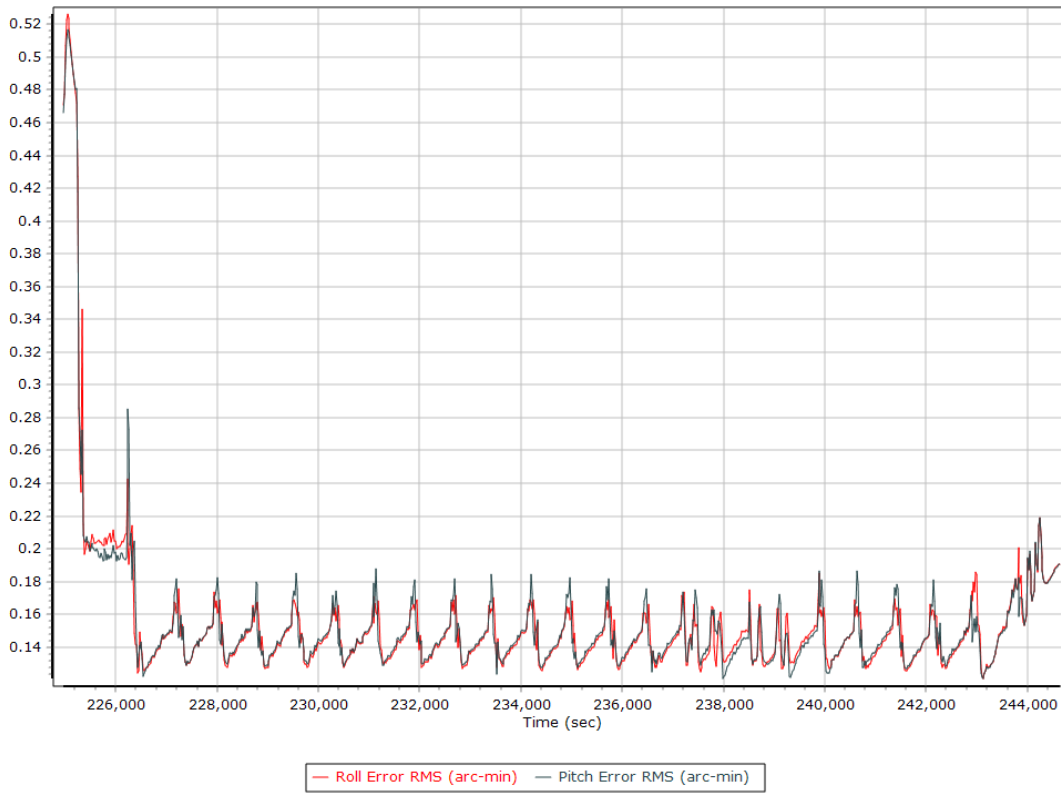


### Velocity Error RMS (m/s)

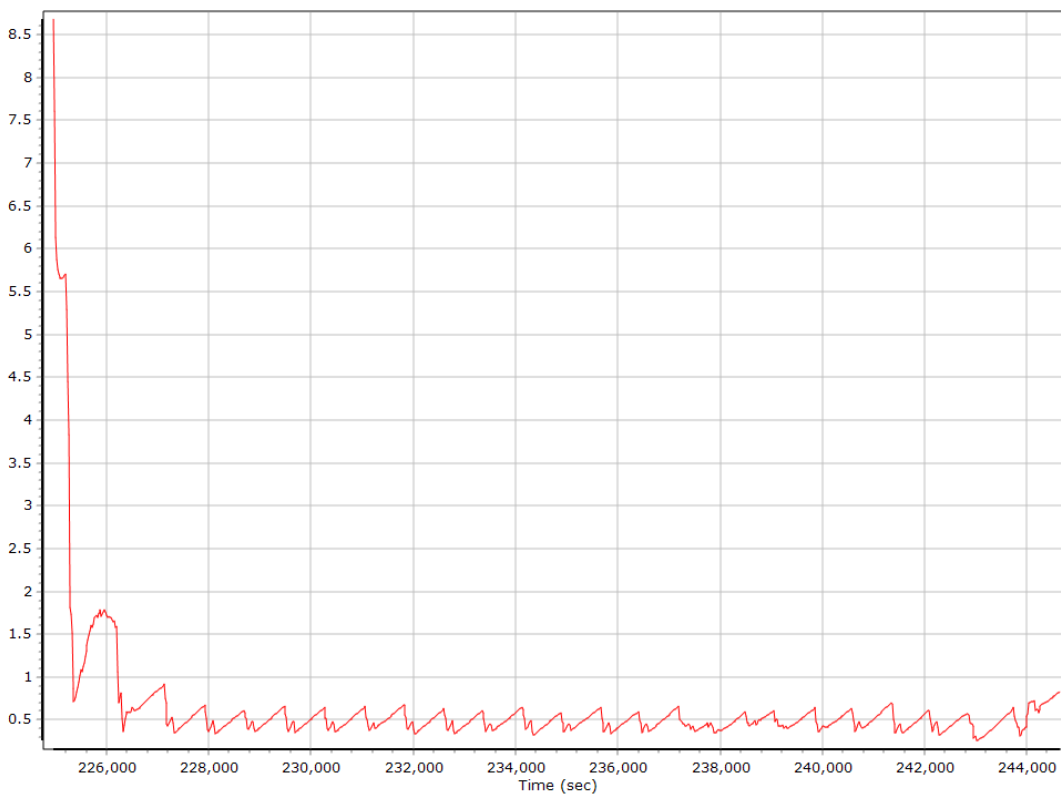




### Roll/Pitch Error RMS (arc-min)

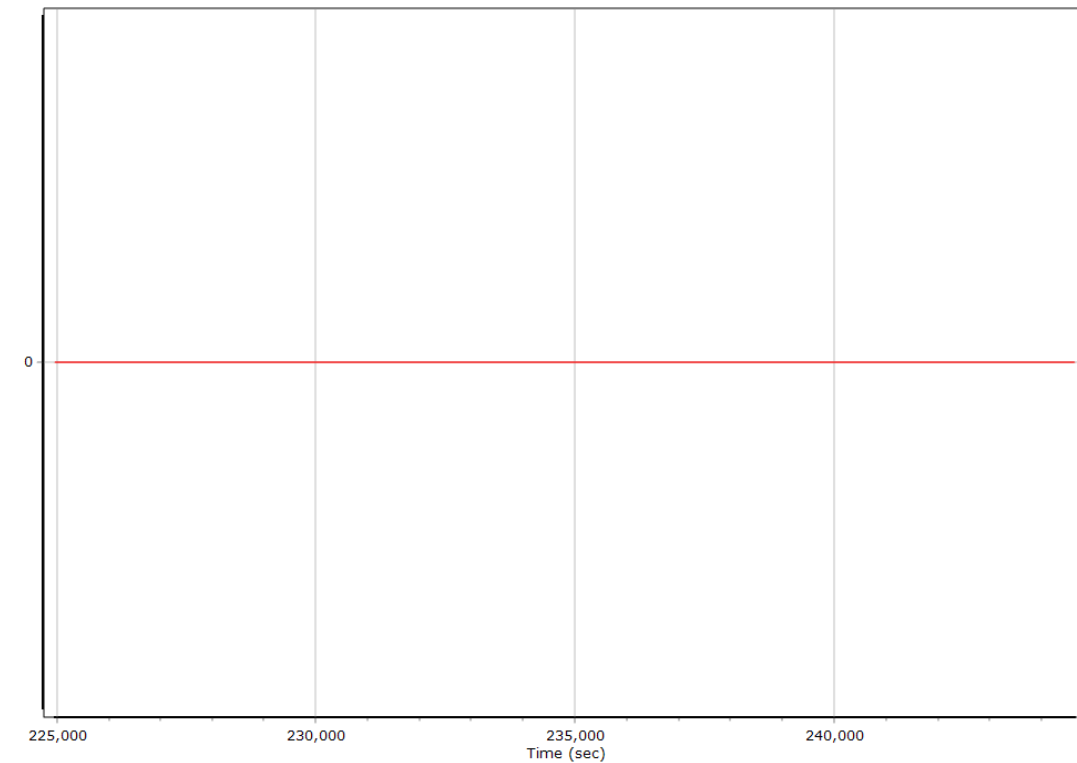


### Heading Error RMS (arc-min)



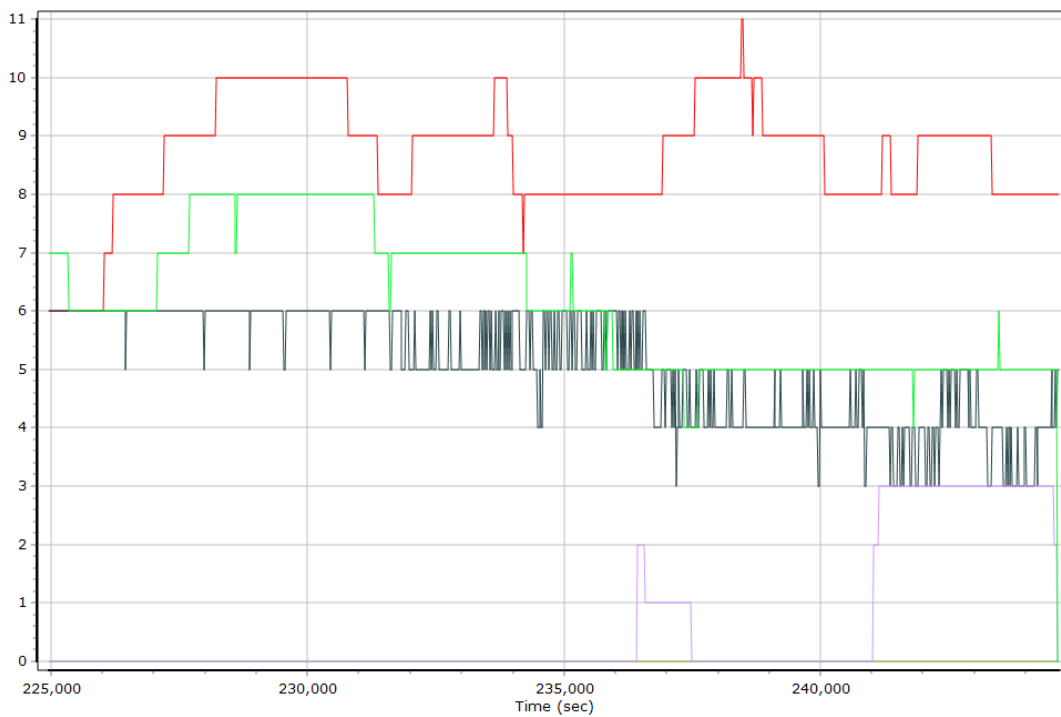
## Forward Processed Solution Status

### Processing Mode



0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = C/A, 7 = GNSS Nav, 8 = DR

### Number of Satellites



— Number of GPS Satellites    — Number of GLONASS Satellites    — Number of QZSS Satellites  
 — Number of BEIDOU Satellites    — Number of GALILEO Satellites

## Baseline Length

