

General Information

Mission Information

Project name	201105_A_5060420_nad2011_FINAL
Processing date	2020-11-11 15:29:08
Mission date	2020-11-05 01:35:16
Mission duration	04:10:30.000
Processing mode	IN-Fusion PP-RTX

Rover Hardware Information

Product	POS AV 610 VER6 HW2.5-12
Serial number	S/N9825
IMU type	57
Receiver type	BD982
Antenna type	AV39

Project File List

Rover Data Files

File name	File type
survey1.pos	POS Data

Input Files

File Name	File Type
Ephm3100.20g	GLONASS Broadcast Ephemeris
Ephm3100.20n	GPS Broadcast Ephemeris

Output Files

Filename	File type
sbet_201105_A_5060420_nad2011_FINAL.out	SBET Trajectory File

Rover Data Summary

First raw data file	survey1.pos		
Last raw data file	survey1.pos		
Start GPS week	2130		
Start time	351315.581 (11/5/2020 1:35:15 AM)		
End time	366346.209 (11/5/2020 5:45:46 AM)		
Start of fine alignment	351632.623 (11/5/2020 1:40:32 AM)		
Available subsystems	Primary GNSS, IMU		
POS Event Input	None		
Correction data	None		
IMU Installation Lever Arms & Mounting Angles			
Reference to IMU lever arm (m)	0.000	0.000	0.000
Reference to IMU mounting angles (deg)	0.000	0.000	-90.000
Reference to Primary GNSS lever arm (m)	0.527	0.205	-1.192
Reference to Primary GNSS lever arm std dev (m)	-1.000		
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

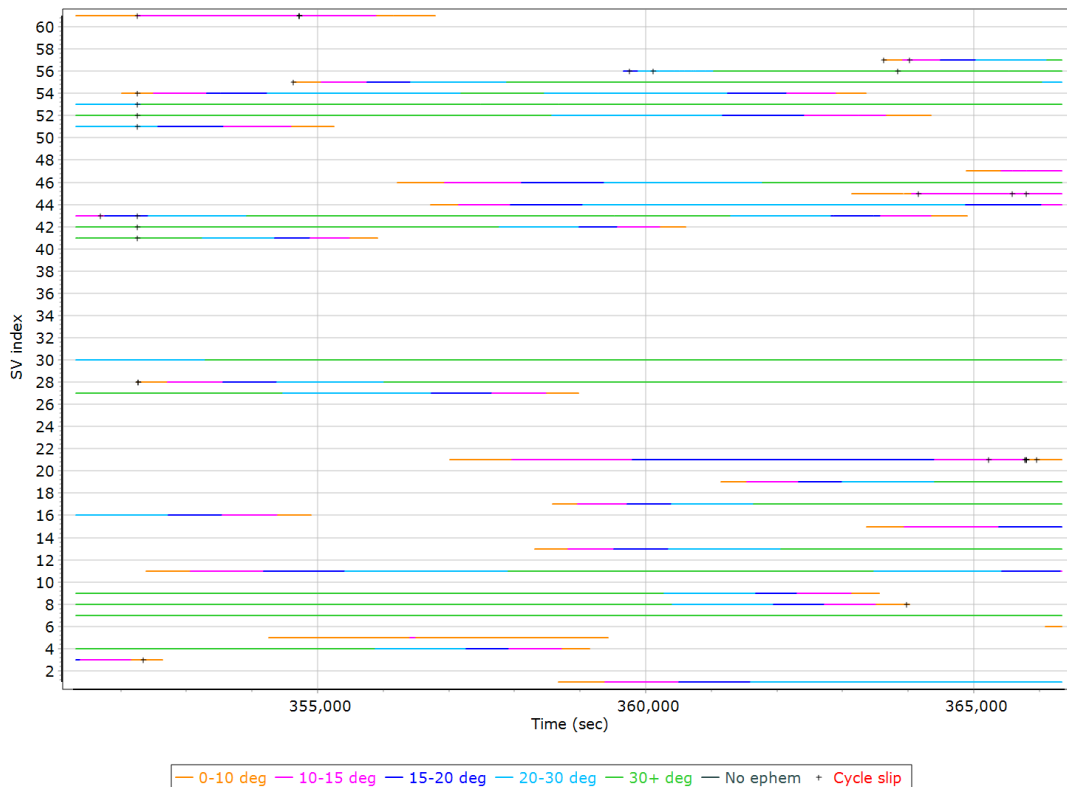
Rover Data QC

Raw IMU Import QC Summary

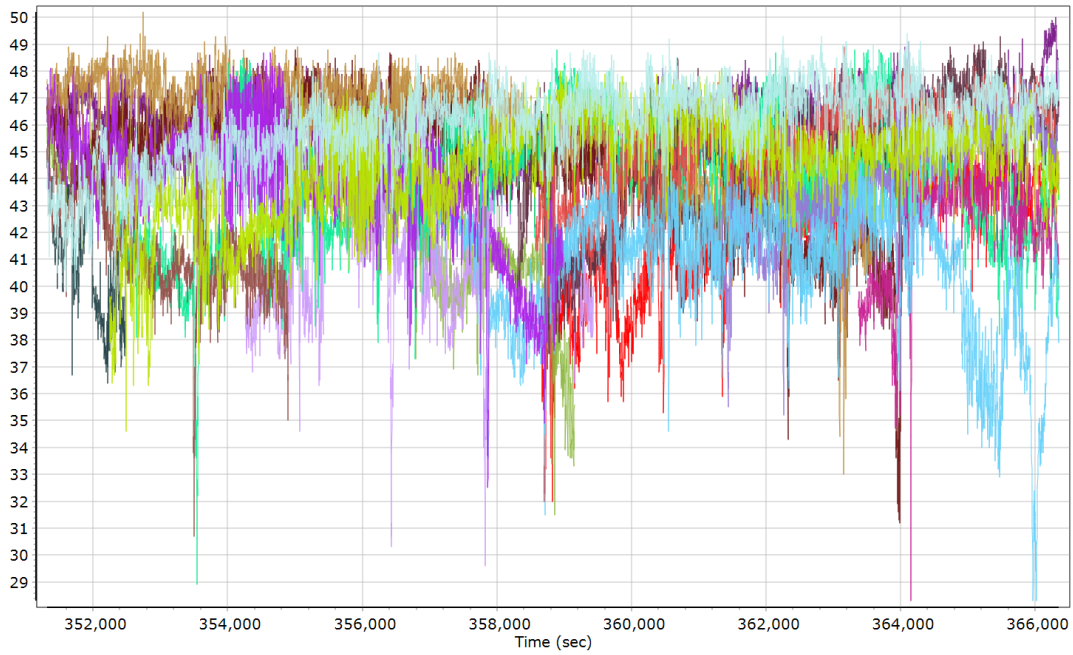
IMU data input file	imu_201105_A_5060420_nad2011_FINAL.dat
IMU data check log file	imudt_201105_A_5060420_nad2011_FINAL.log
IMU Records Processed	3005563
Termination Status	Normal
IMU Anomalies	0

Primary Observables & Satellite Data

GPS/GLONASS L1 Satellite Lock/Elevation

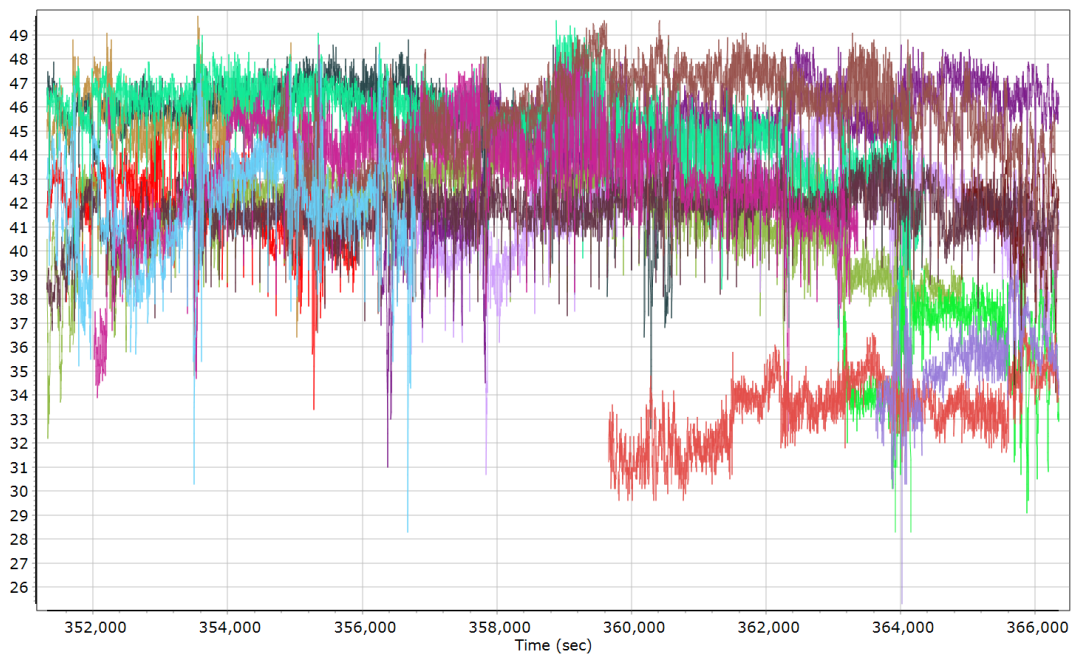


GPS L1 SNR



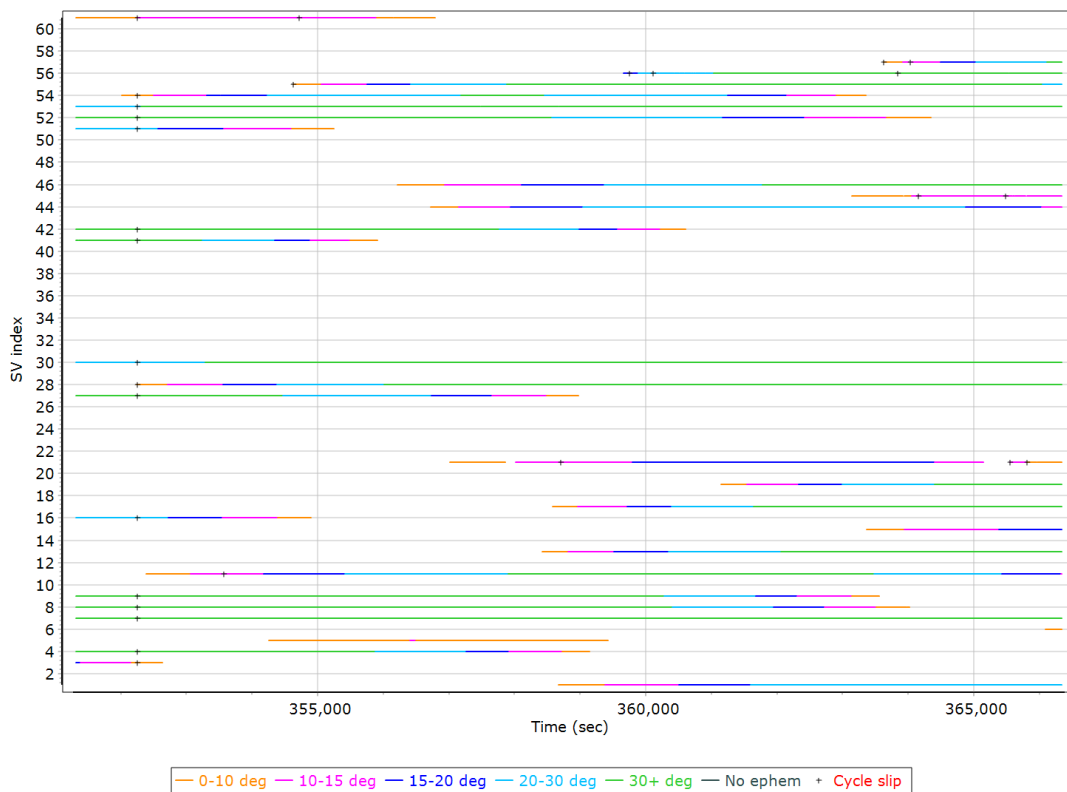
- | | | | |
|---------------------------|---------------------------|---------------------------|---------------------------|
| GPS PRN 01 L1 SNR (dB/Hz) | GPS PRN 03 L1 SNR (dB/Hz) | GPS PRN 04 L1 SNR (dB/Hz) | GPS PRN 05 L1 SNR (dB/Hz) |
| GPS PRN 06 L1 SNR (dB/Hz) | GPS PRN 07 L1 SNR (dB/Hz) | GPS PRN 08 L1 SNR (dB/Hz) | GPS PRN 09 L1 SNR (dB/Hz) |
| GPS PRN 11 L1 SNR (dB/Hz) | GPS PRN 13 L1 SNR (dB/Hz) | GPS PRN 15 L1 SNR (dB/Hz) | GPS PRN 16 L1 SNR (dB/Hz) |
| GPS PRN 17 L1 SNR (dB/Hz) | GPS PRN 19 L1 SNR (dB/Hz) | GPS PRN 21 L1 SNR (dB/Hz) | GPS PRN 27 L1 SNR (dB/Hz) |
| GPS PRN 28 L1 SNR (dB/Hz) | GPS PRN 30 L1 SNR (dB/Hz) | | |

GLONASS L1 SNR

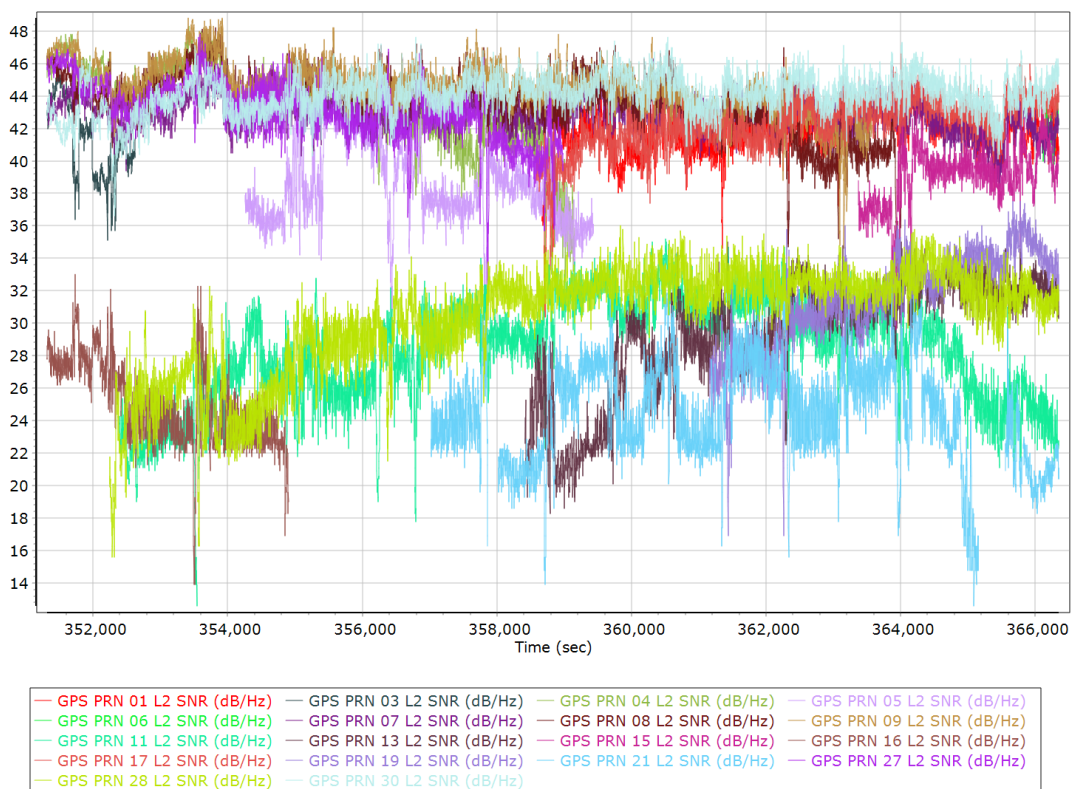


- | | | |
|---------------------------|---------------------------|---------------------------|
| GLONASS 04 L1 SNR (dB/Hz) | GLONASS 05 L1 SNR (dB/Hz) | GLONASS 06 L1 SNR (dB/Hz) |
| GLONASS 07 L1 SNR (dB/Hz) | GLONASS 08 L1 SNR (dB/Hz) | GLONASS 09 L1 SNR (dB/Hz) |
| GLONASS 10 L1 SNR (dB/Hz) | GLONASS 14 L1 SNR (dB/Hz) | GLONASS 15 L1 SNR (dB/Hz) |
| GLONASS 16 L1 SNR (dB/Hz) | GLONASS 17 L1 SNR (dB/Hz) | GLONASS 18 L1 SNR (dB/Hz) |
| GLONASS 19 L1 SNR (dB/Hz) | GLONASS 20 L1 SNR (dB/Hz) | GLONASS 24 L1 SNR (dB/Hz) |

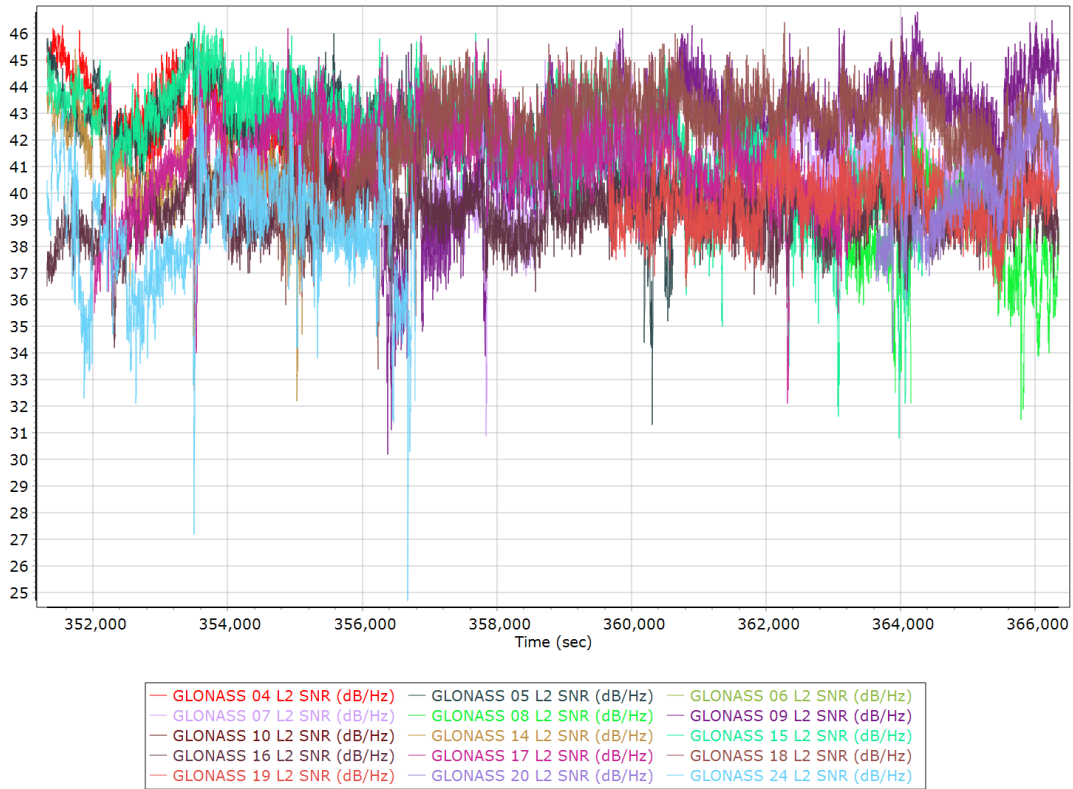
GPS/GLONASS L2 Satellite Lock/Elevation



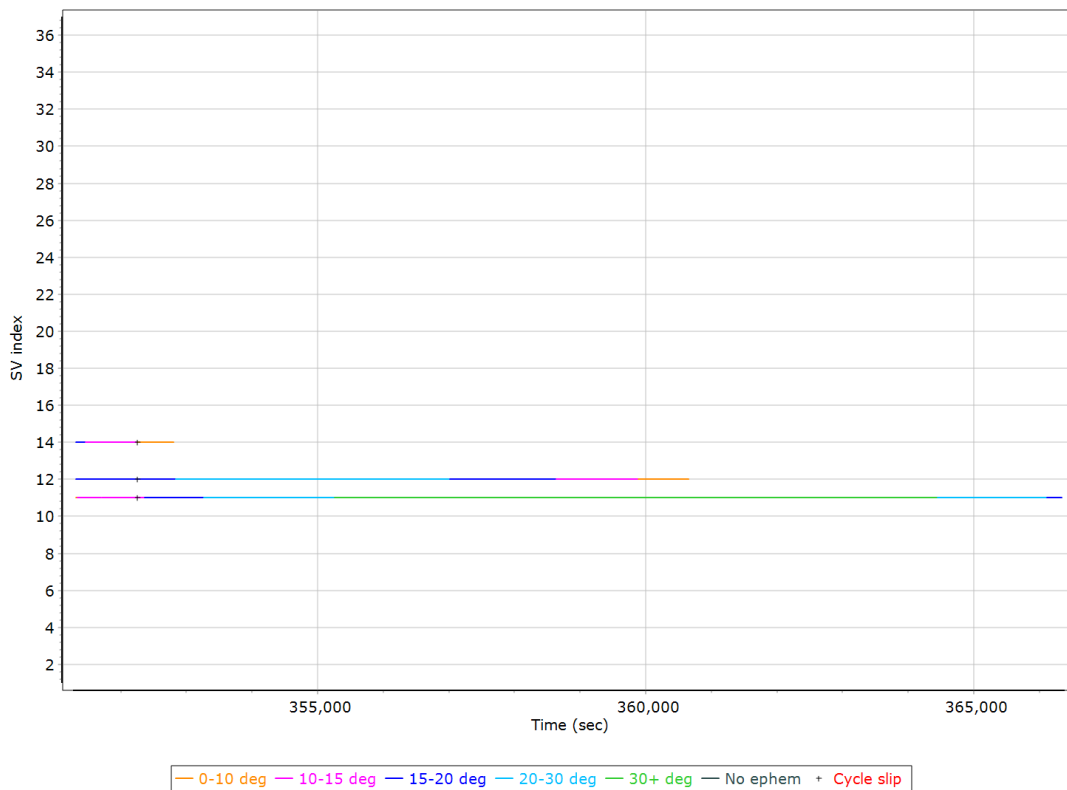
GPS L2 SNR



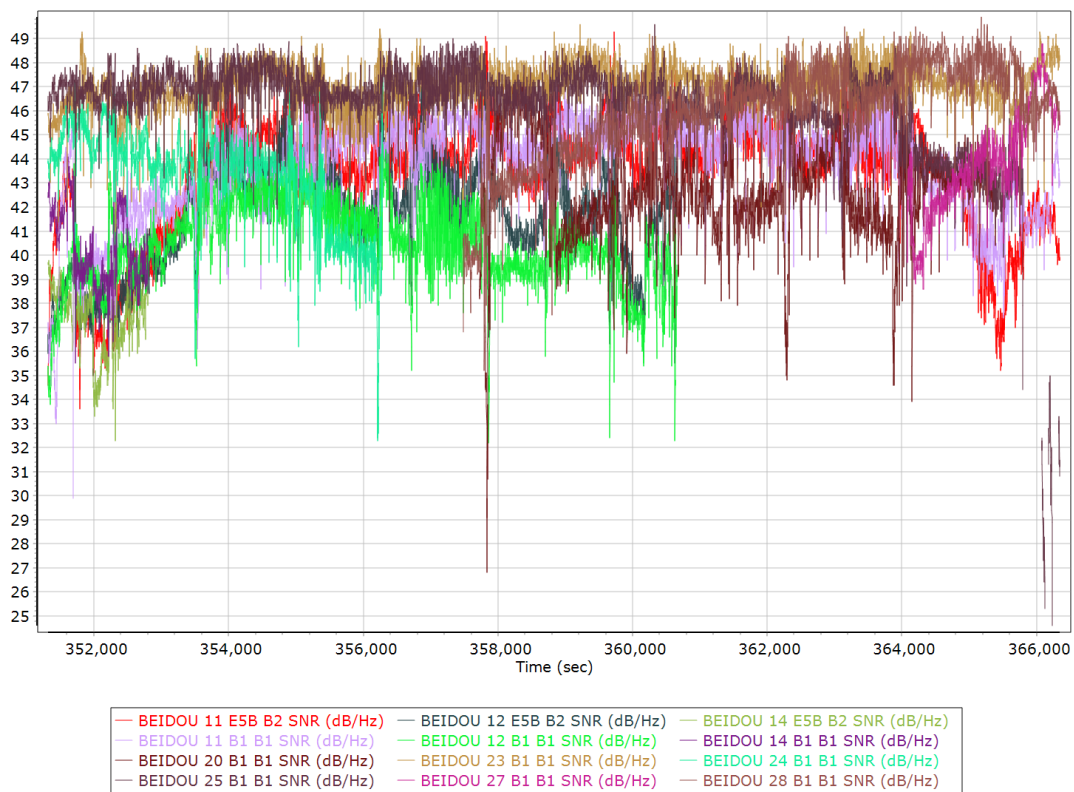
GLONASS L2 SNR



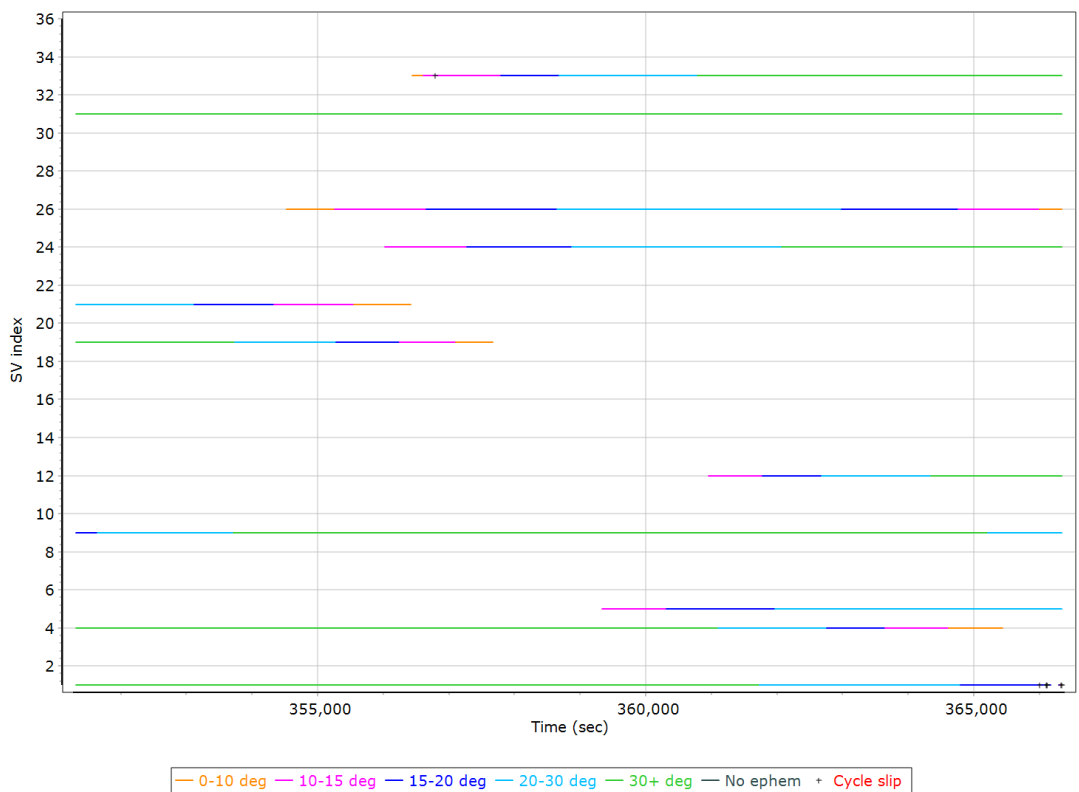
BEIDOU Satellite Lock/Elevation



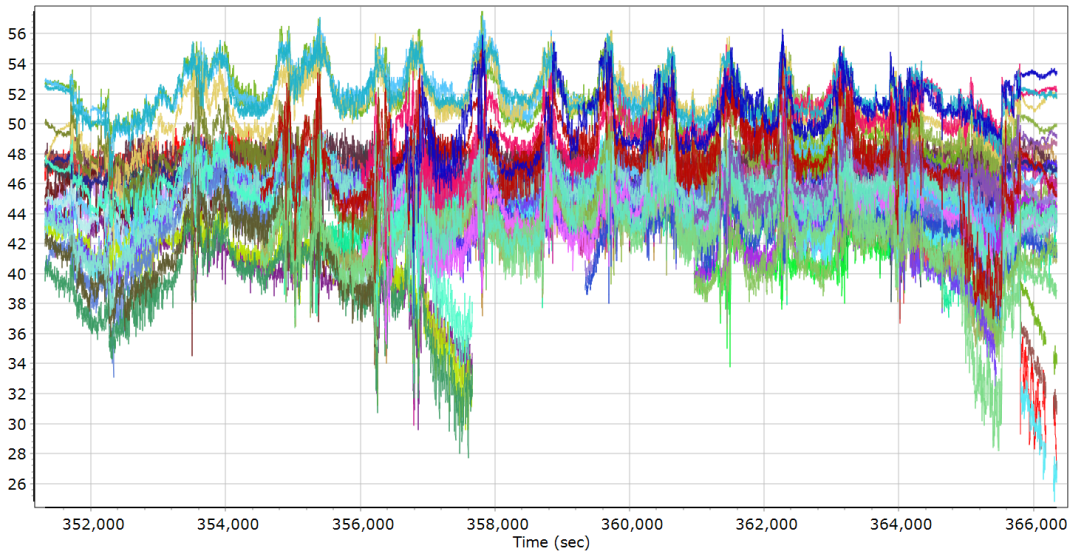
BEIDOU SNR



GALILEO Satellite Lock/Elevation



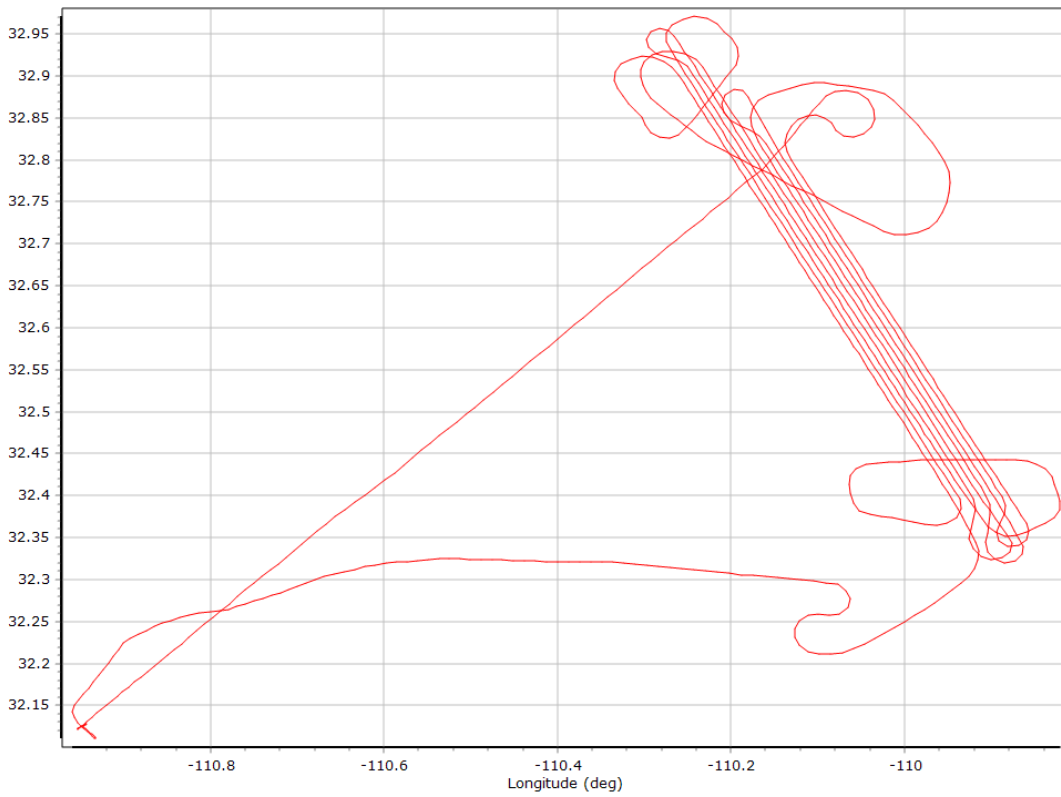
GALILEO SNR



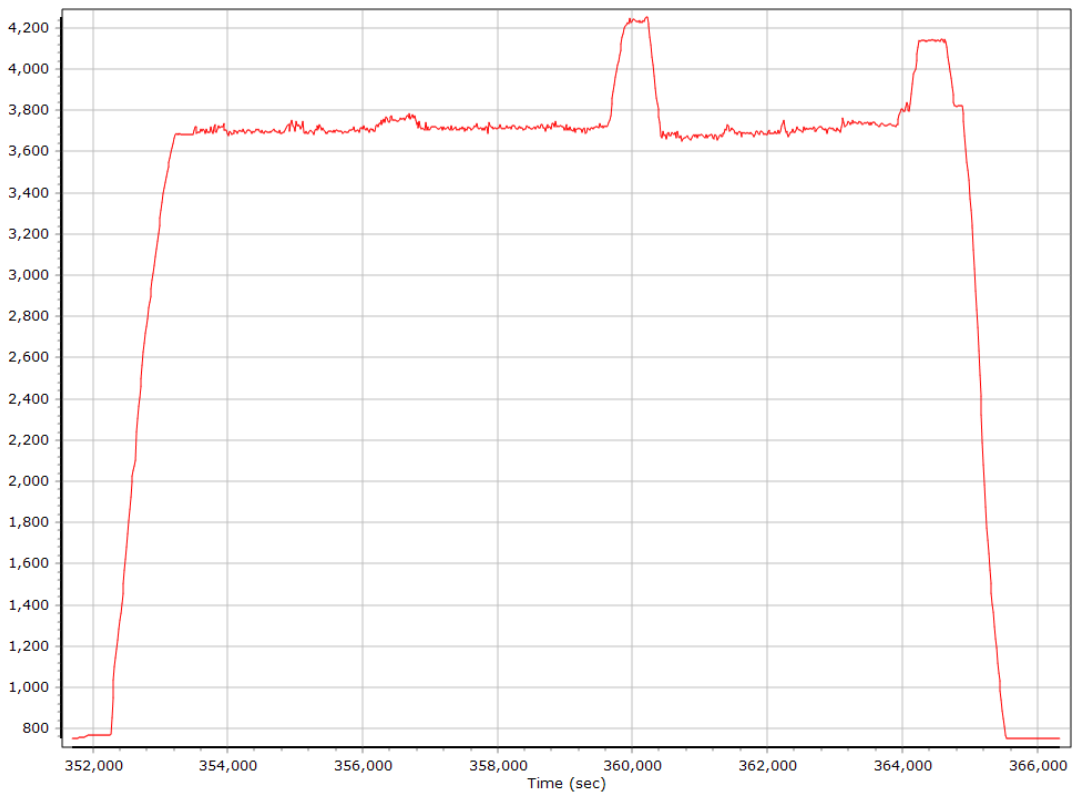
— GALILEO 01 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 04 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 05 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 09 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 12 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 19 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 21 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 24 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 26 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 31 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 33 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 01 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 04 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 05 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 09 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 12 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 19 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 21 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 24 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 26 L5E5A BPSK10_PD SNR (dB/Hz)

Smoothed Trajectory Information

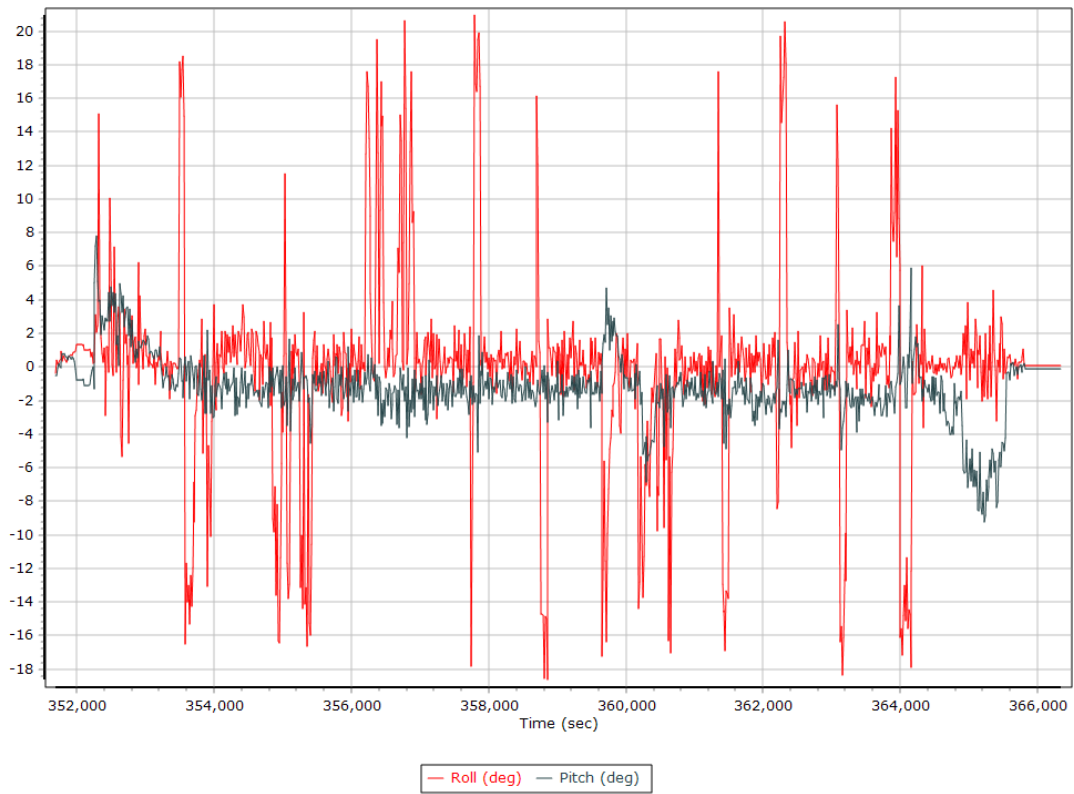
Top View



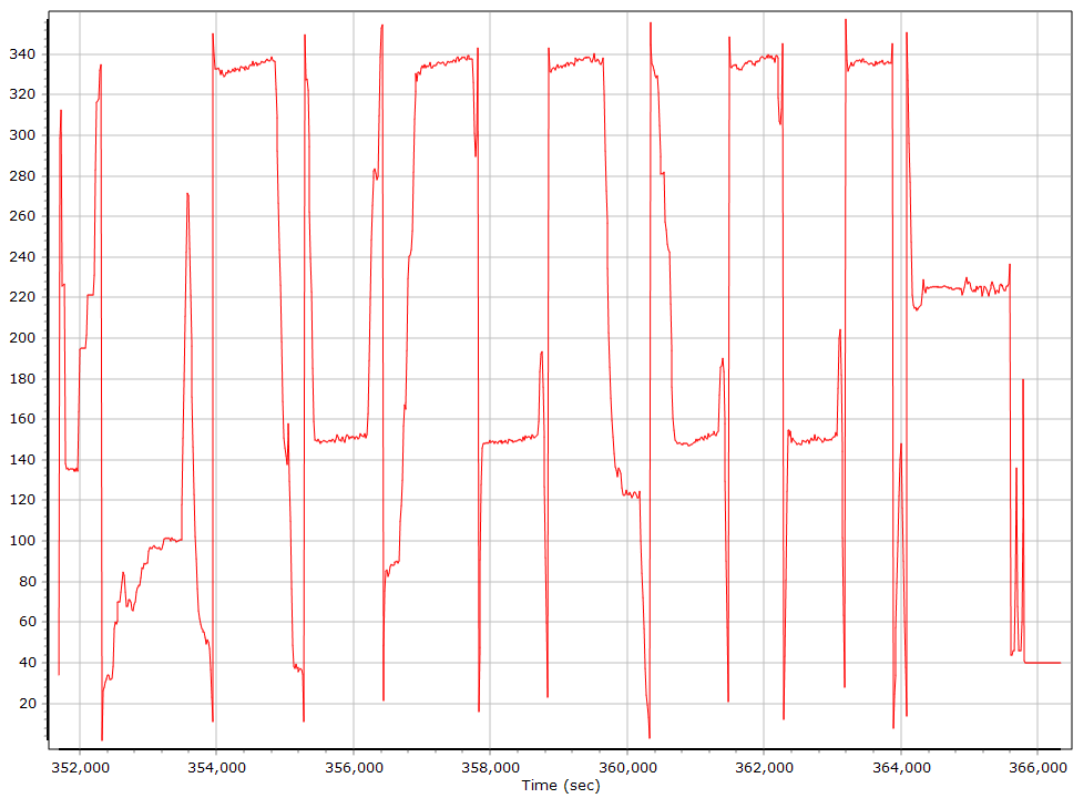
Altitude



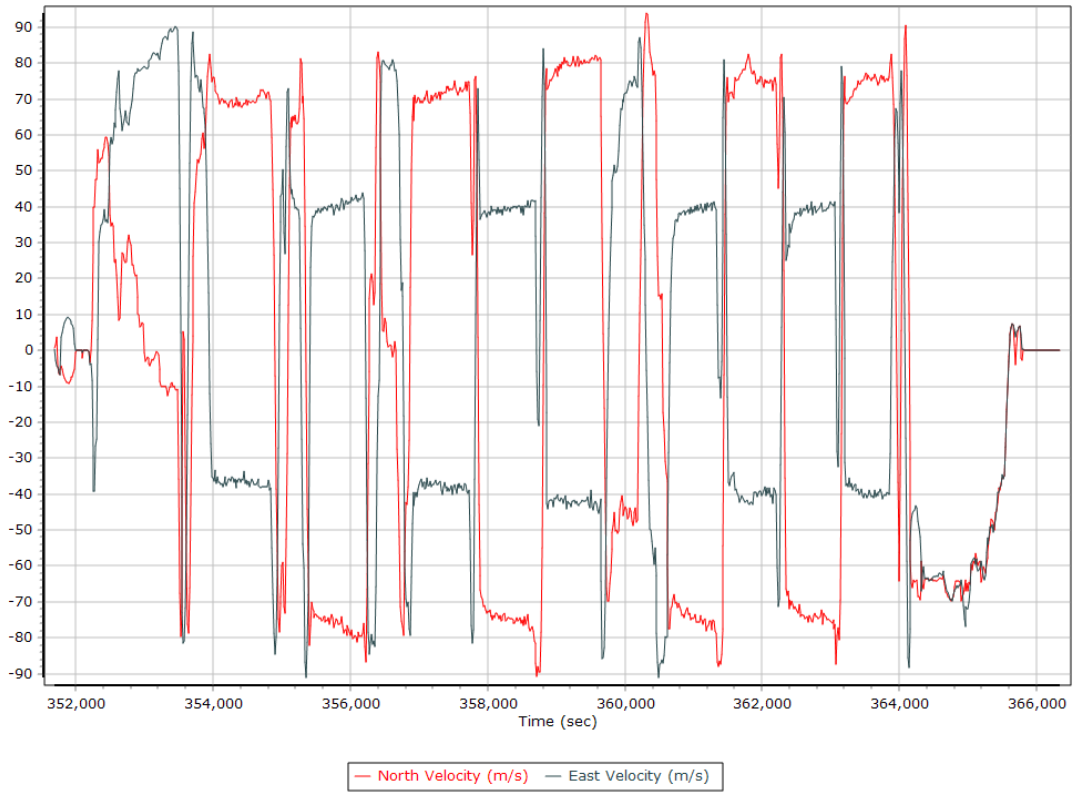
Roll/Pitch



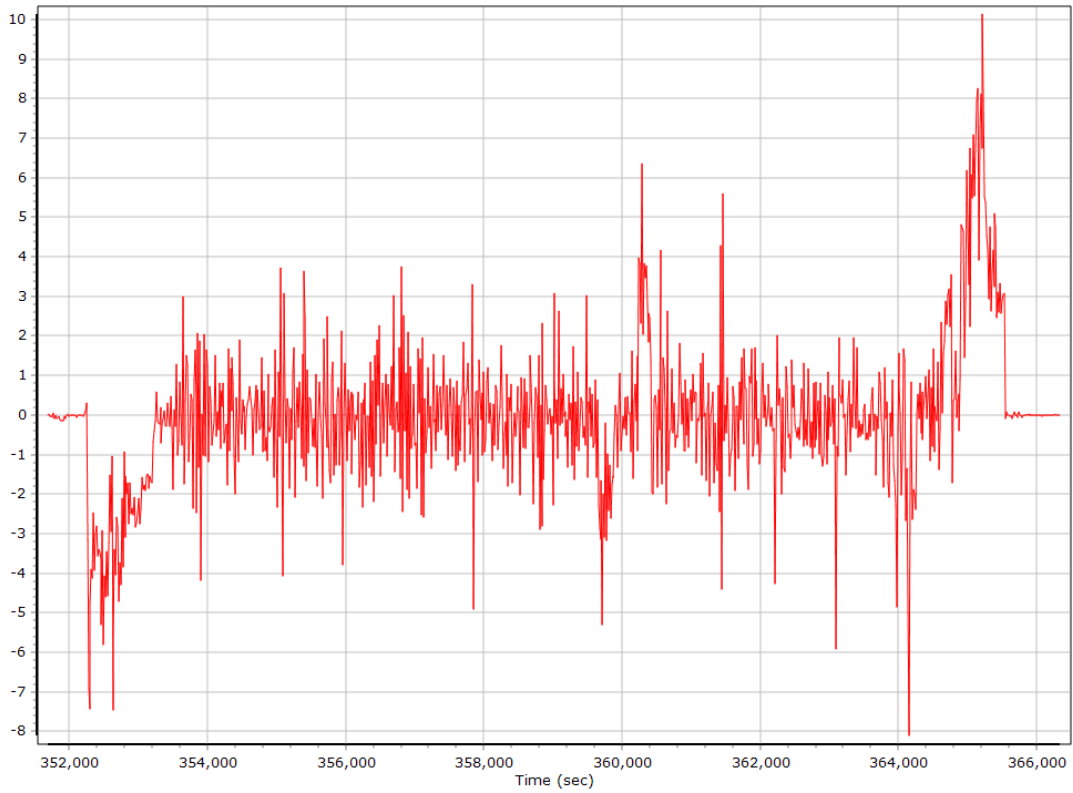
Heading



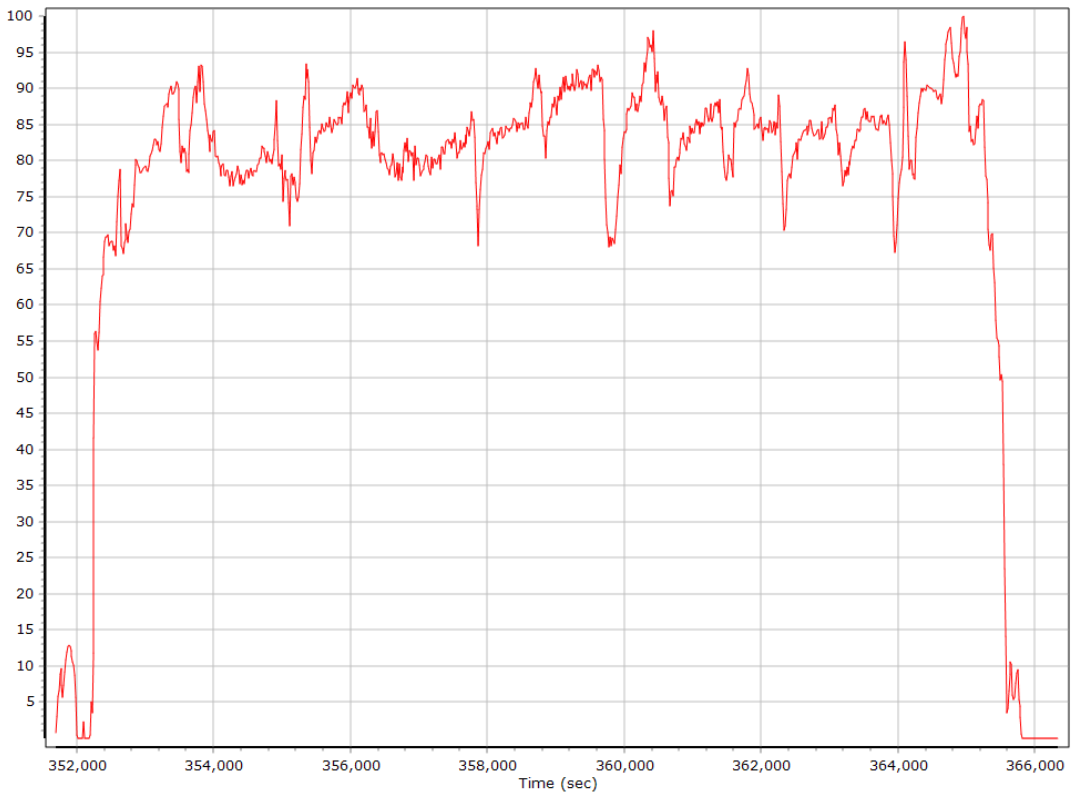
North/East Velocity



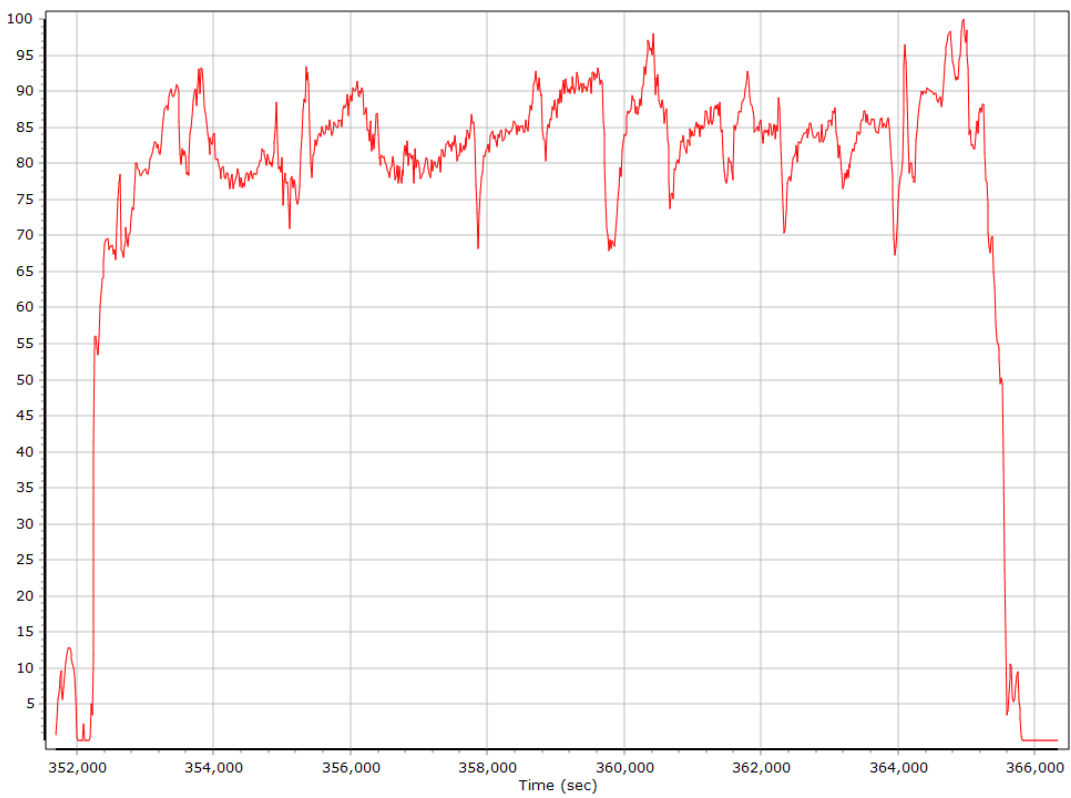
Down Velocity



Total Speed



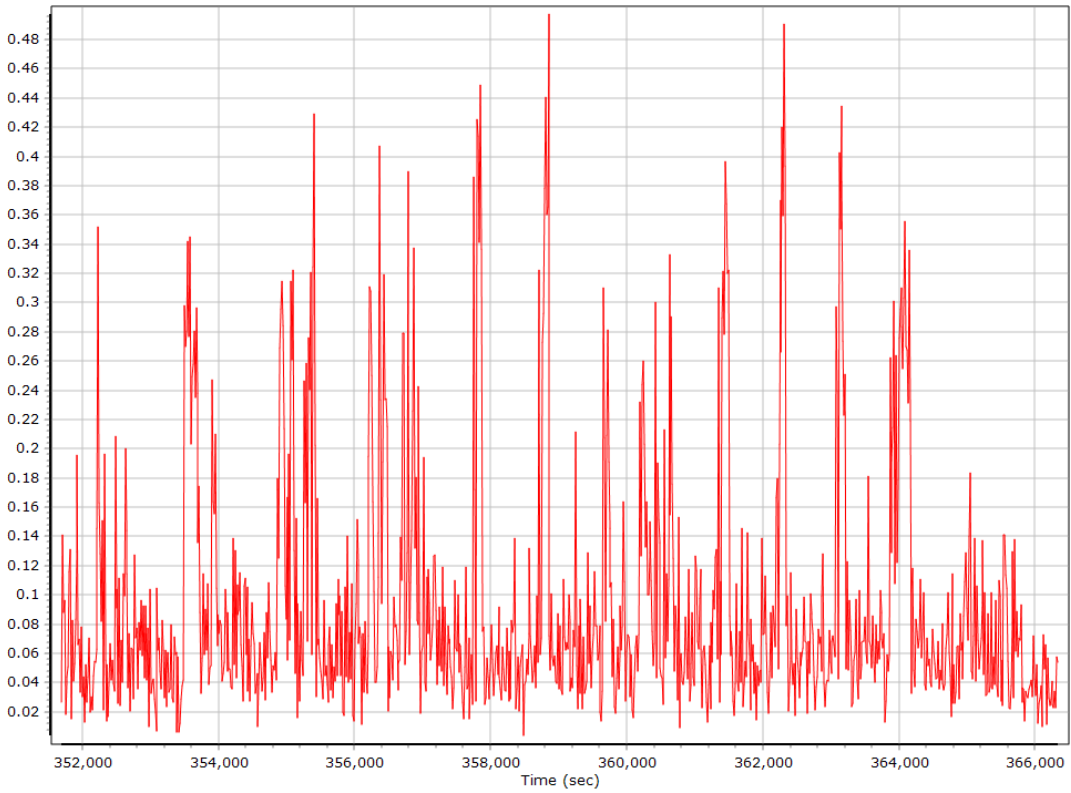
Ground Speed



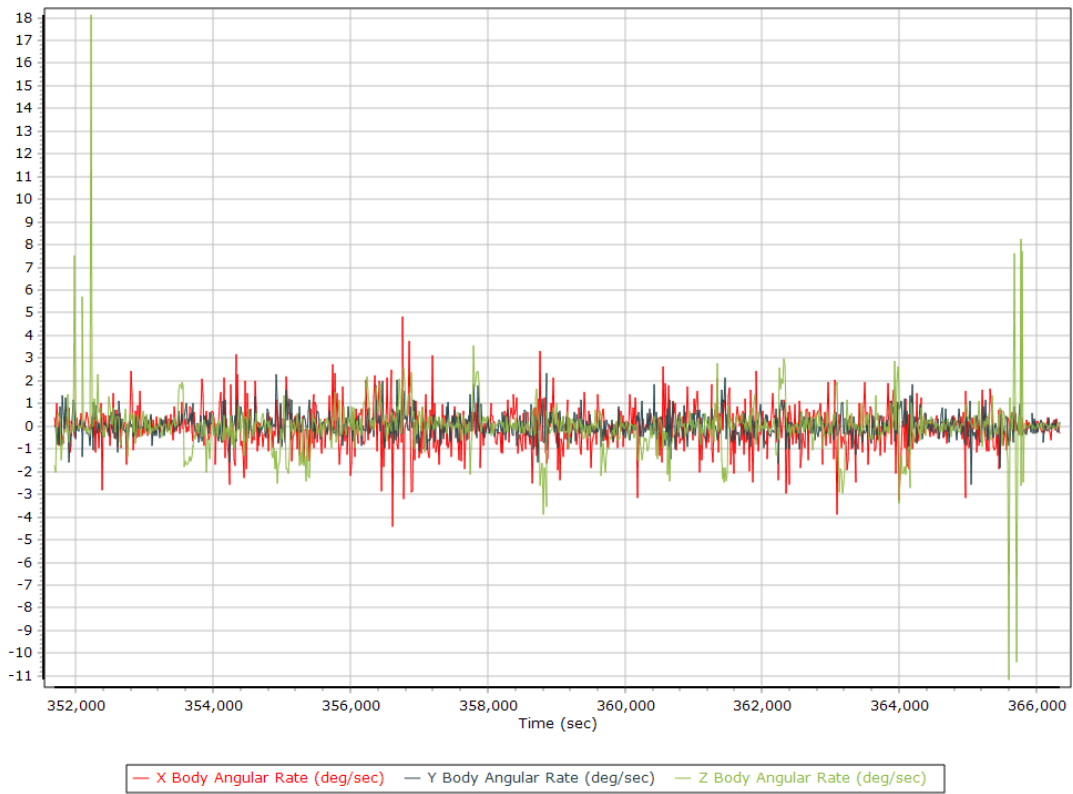
Body Acceleration



Total Body Acceleration

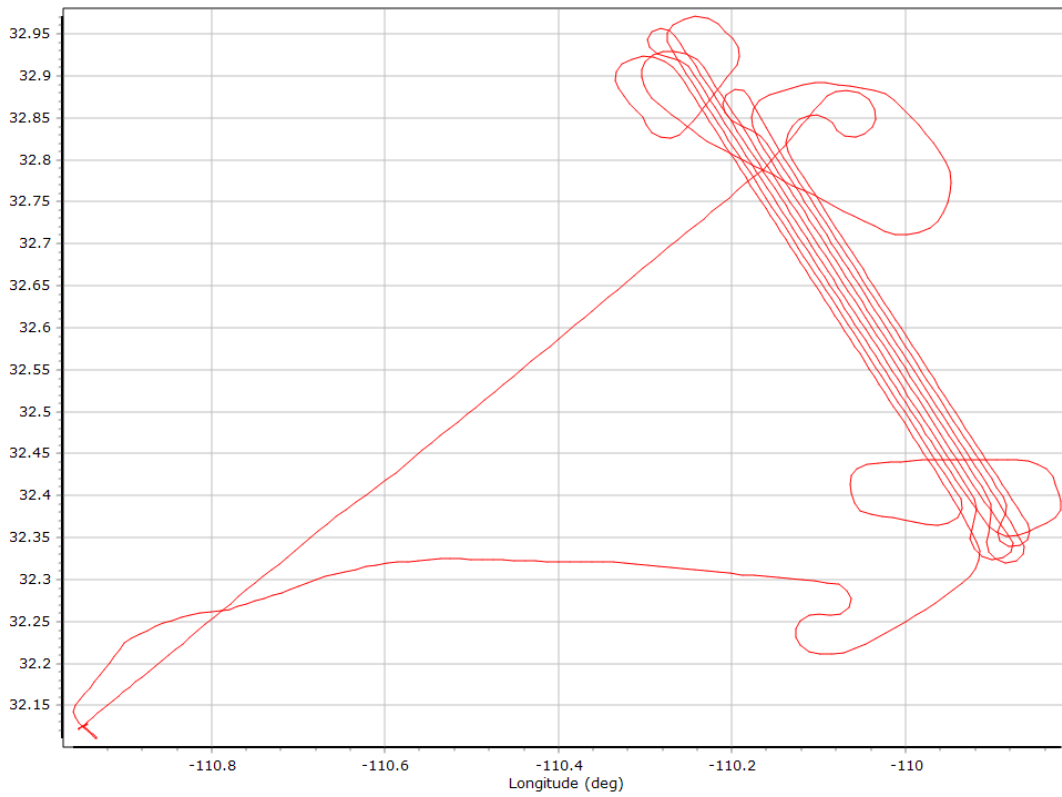


Body Angular Rate

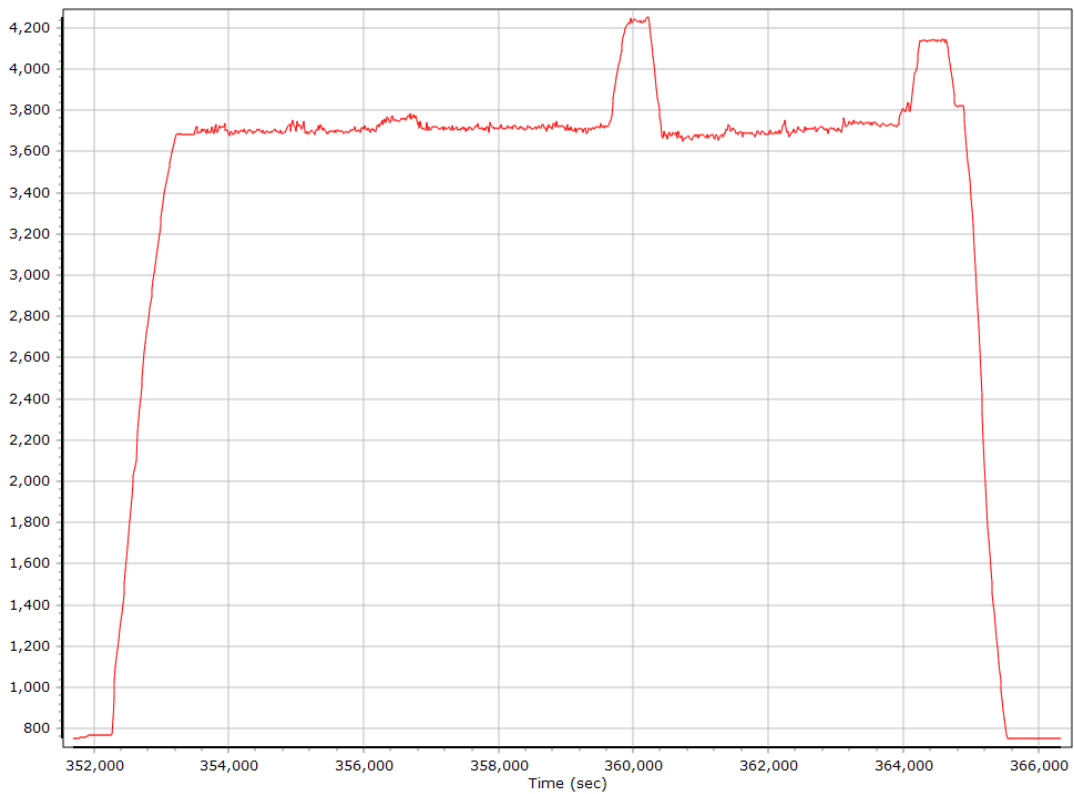


Forward Processed Trajectory Information

Top View



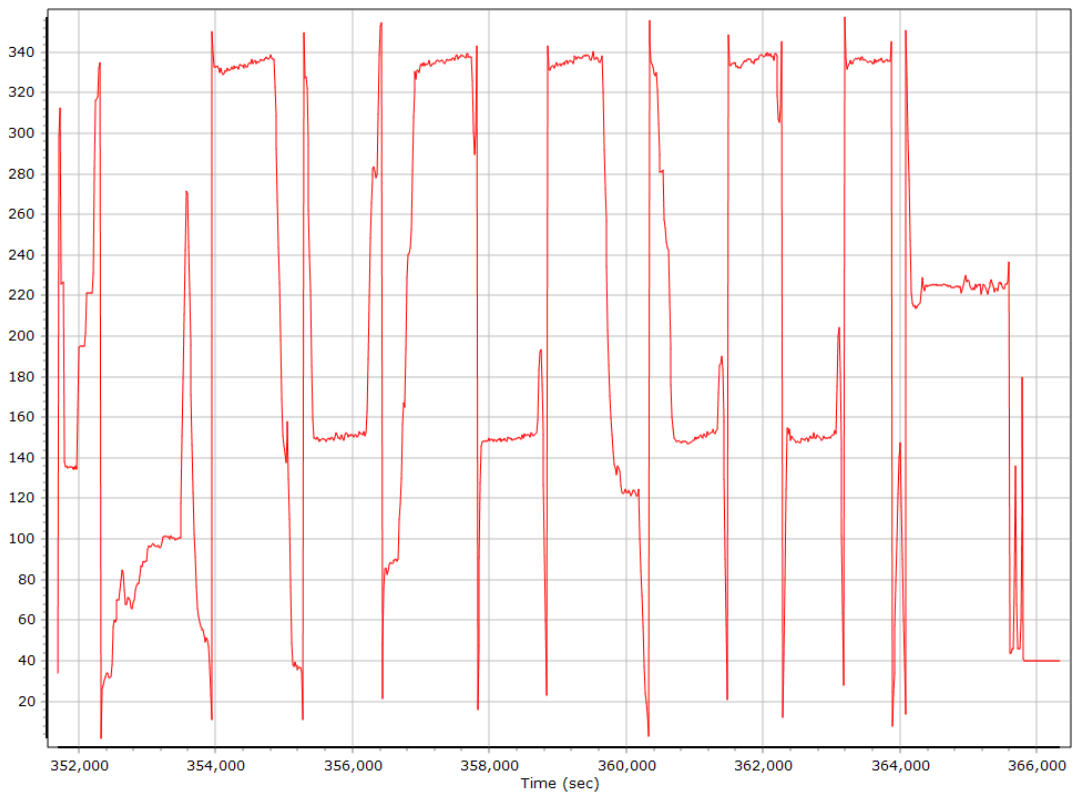
Altitude



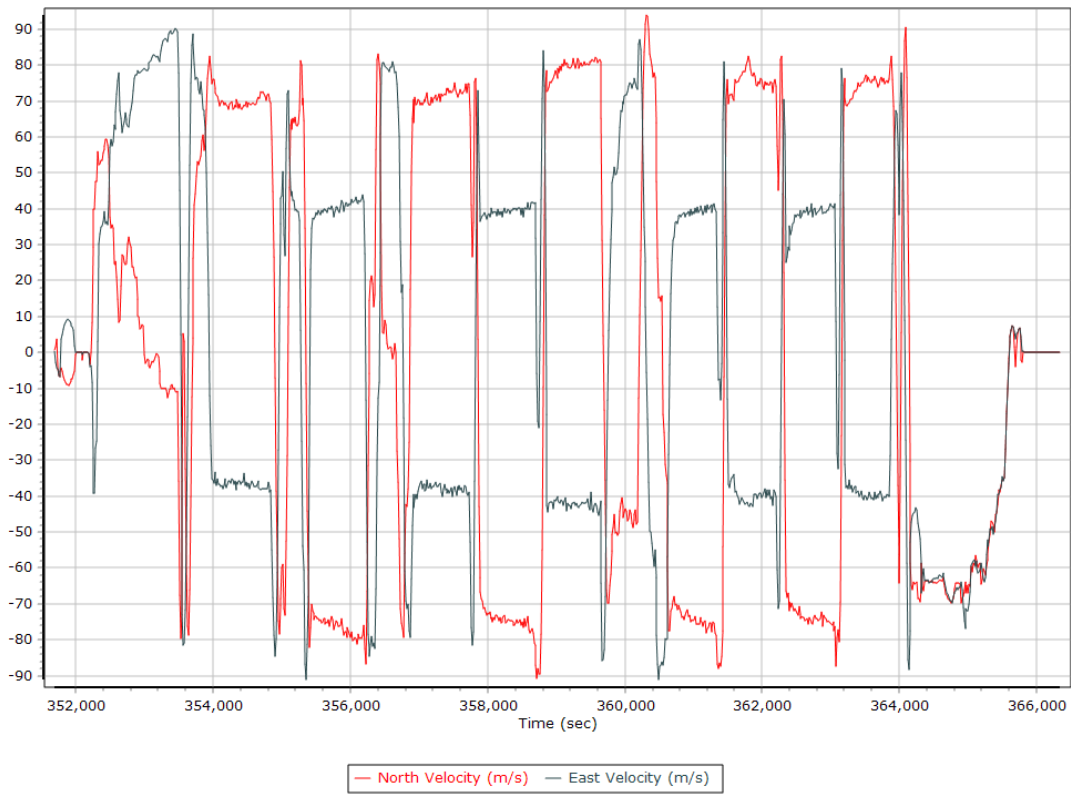
Roll/Pitch



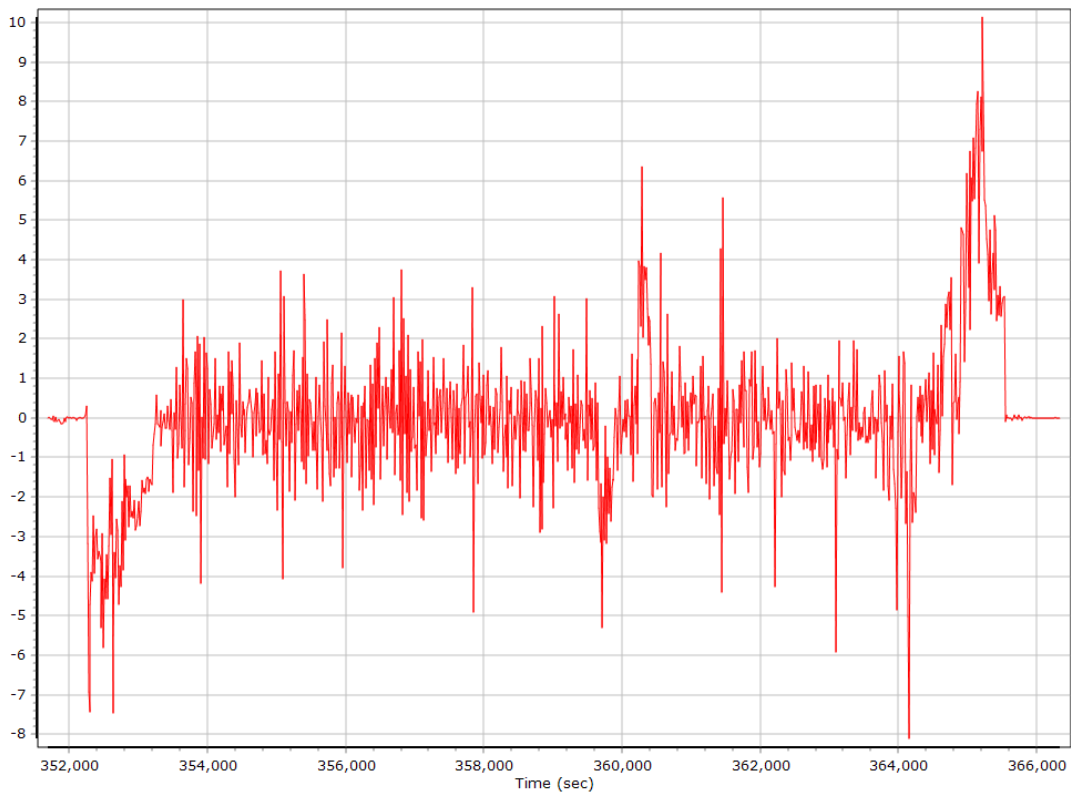
Heading



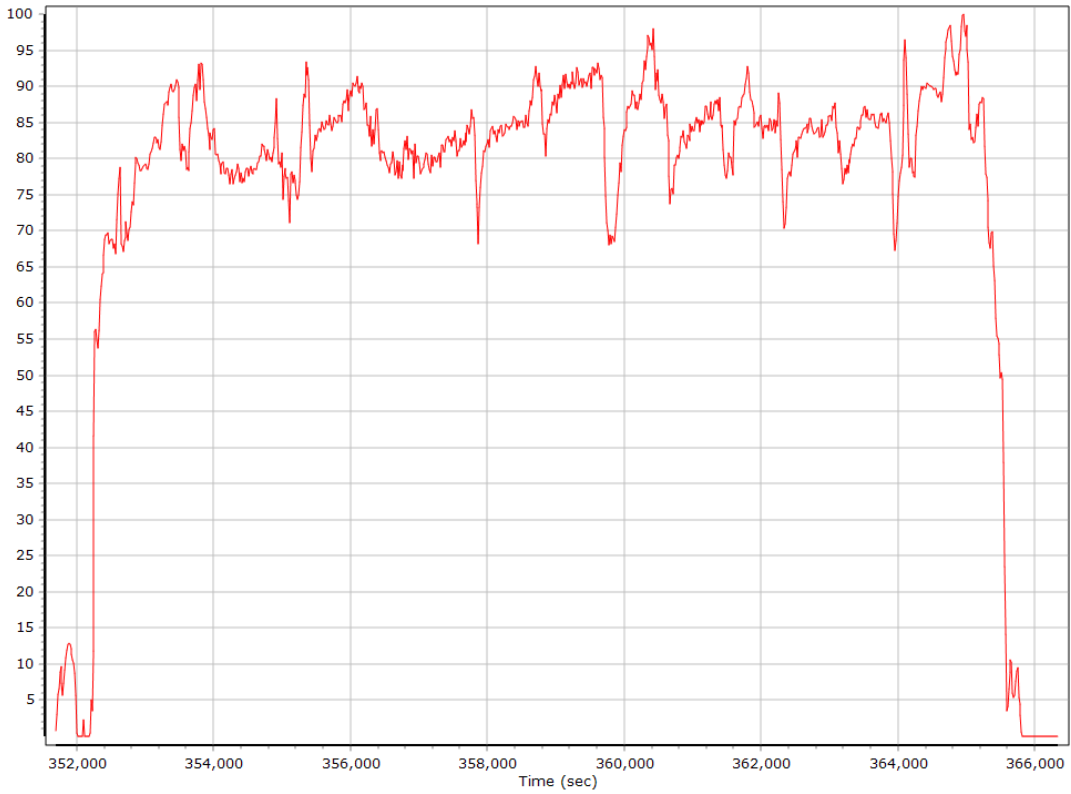
North/East Velocity



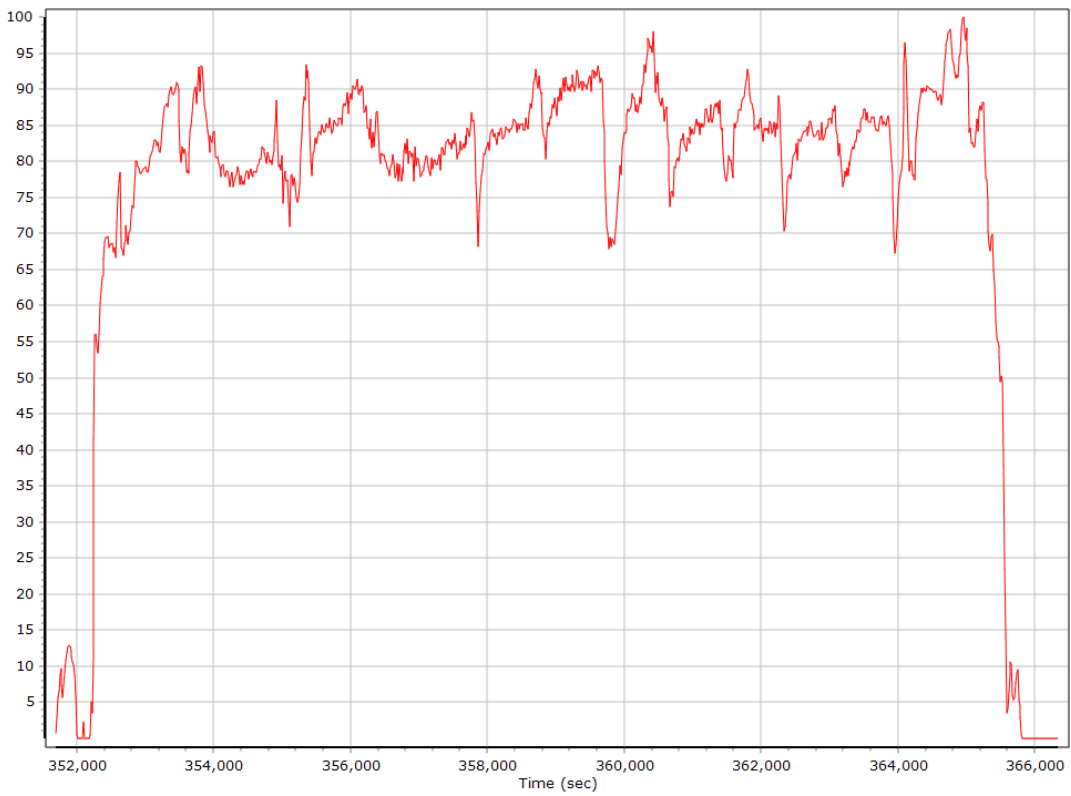
Down Velocity



Total Speed



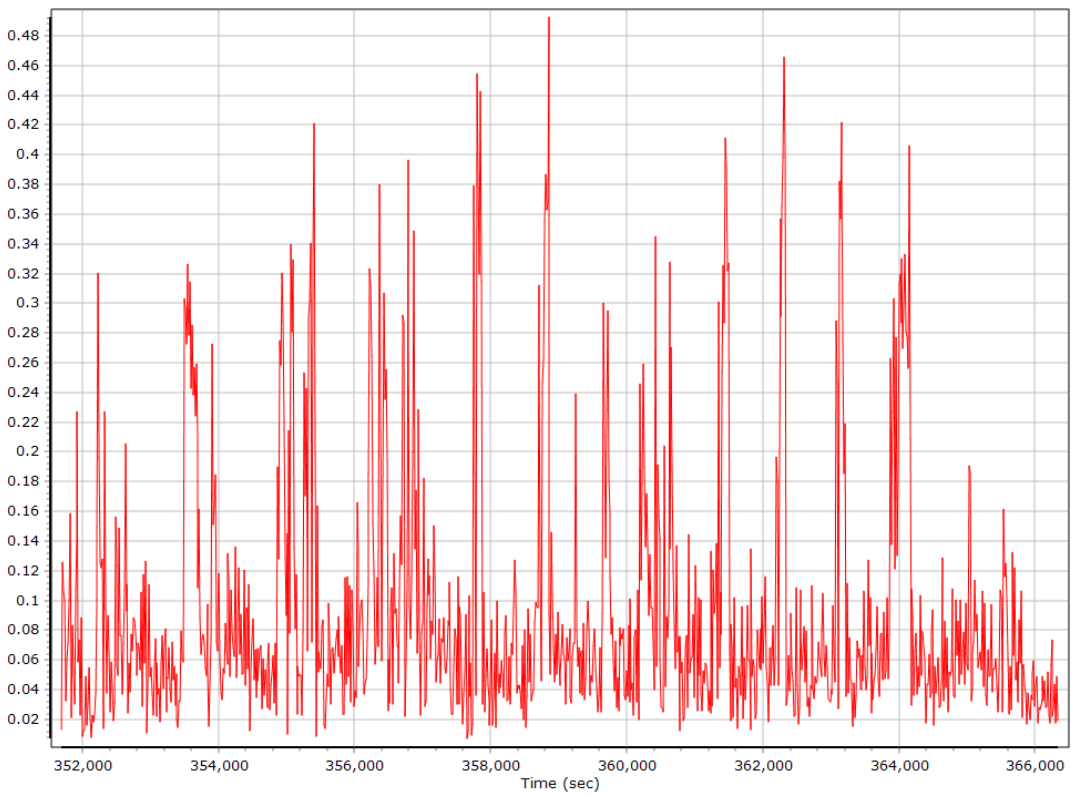
Ground Speed



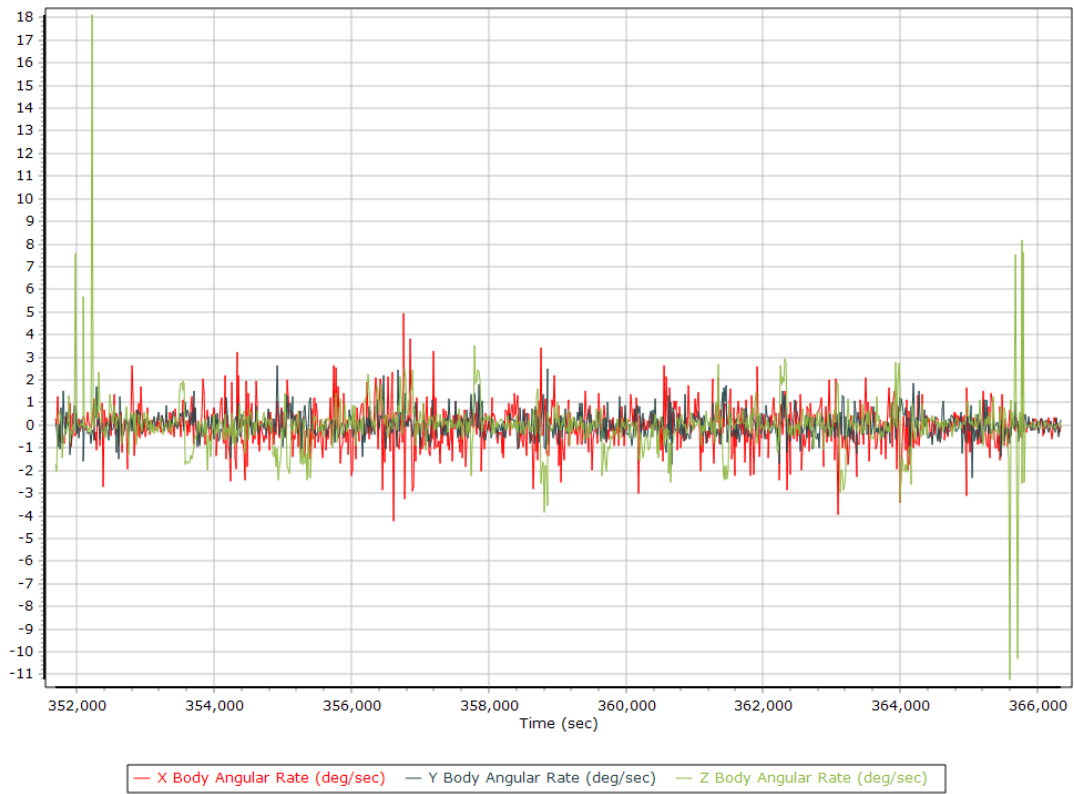
Body Acceleration



Total Body Acceleration



Body Angular Rate

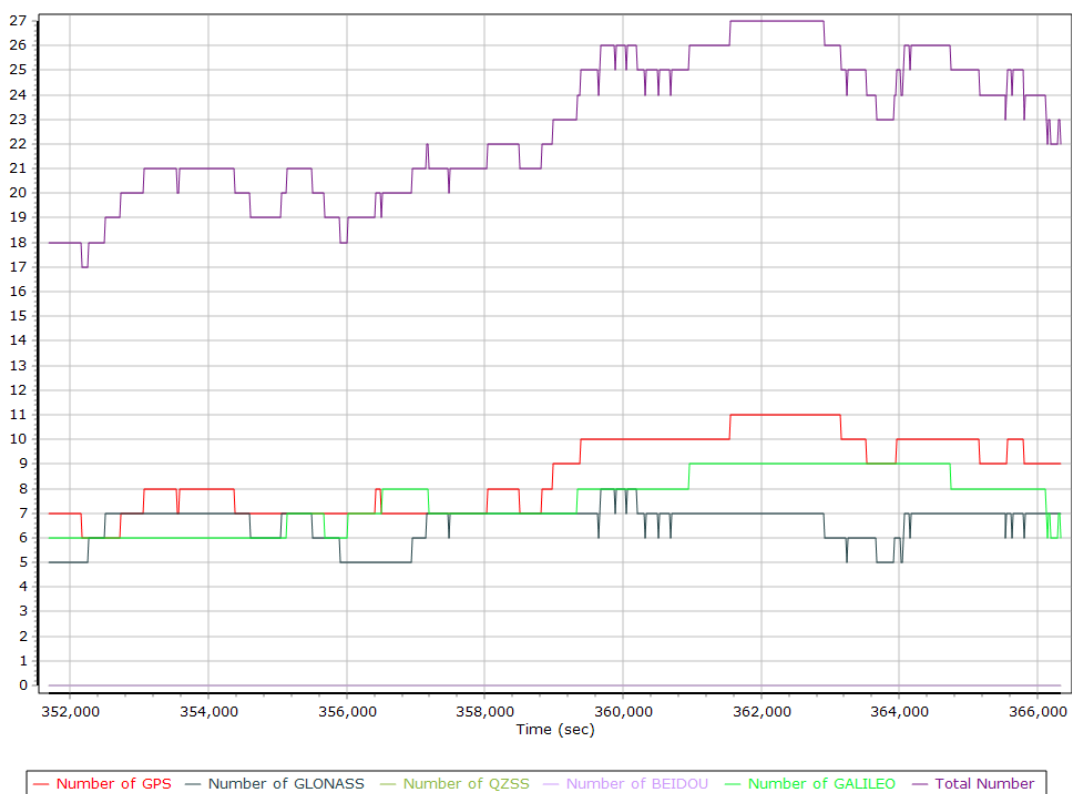


GNSS QC

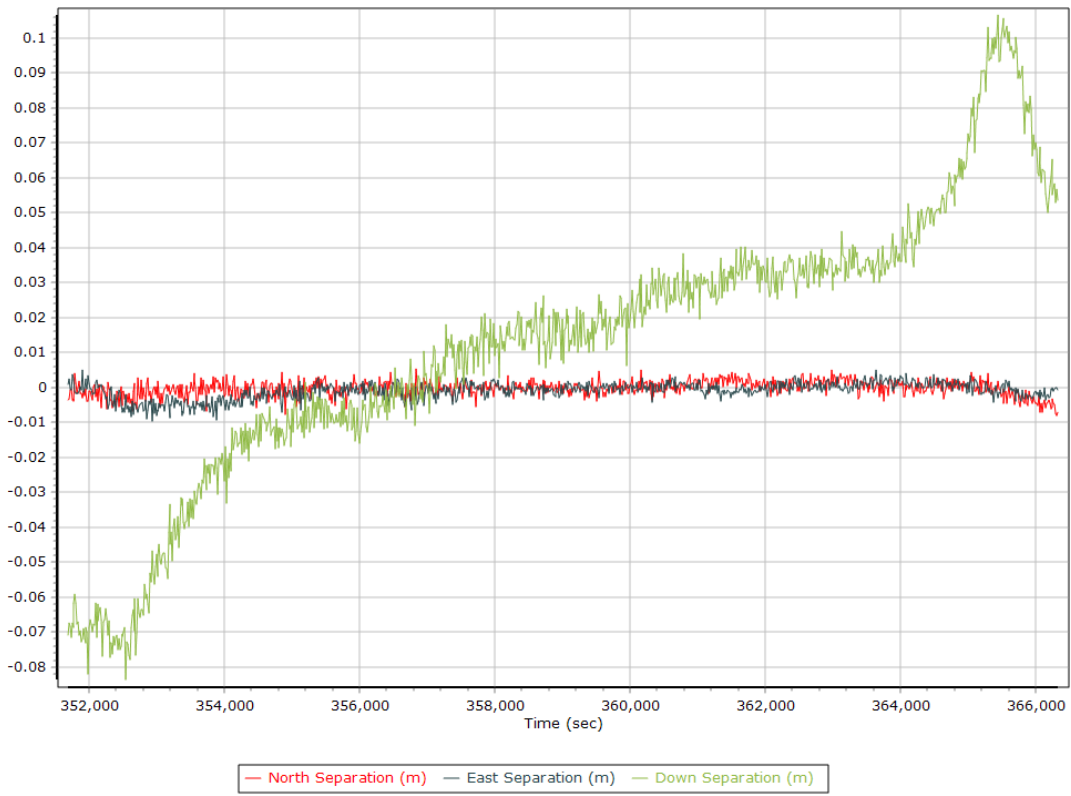
GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	6	11	9
Number of GLONASS SV	0	8	7
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	0	0
Number of GALILEO SV	6	9	7
Total number of SV	12	27	23
PDOP	1.00	1.71	1.17
QC Solution Gaps	1.00	1.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	15013.00	0.00	5.00
Percentage	99.97	0.00	0.03

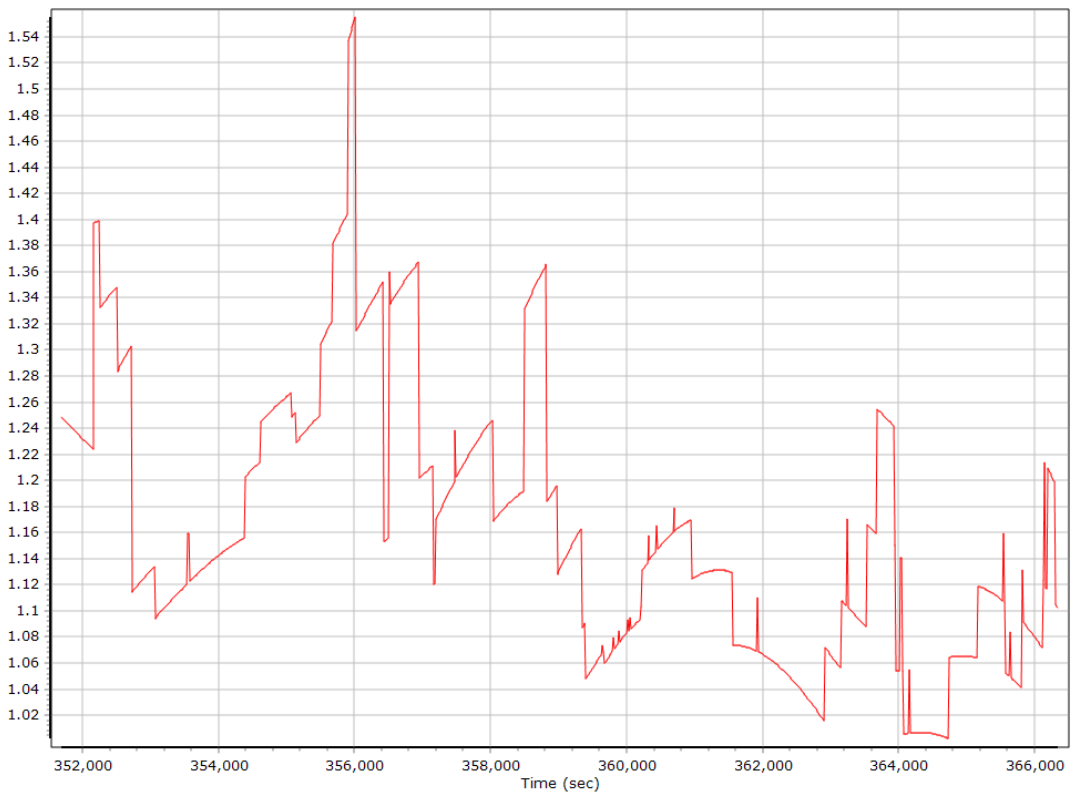
Num SVs in solution



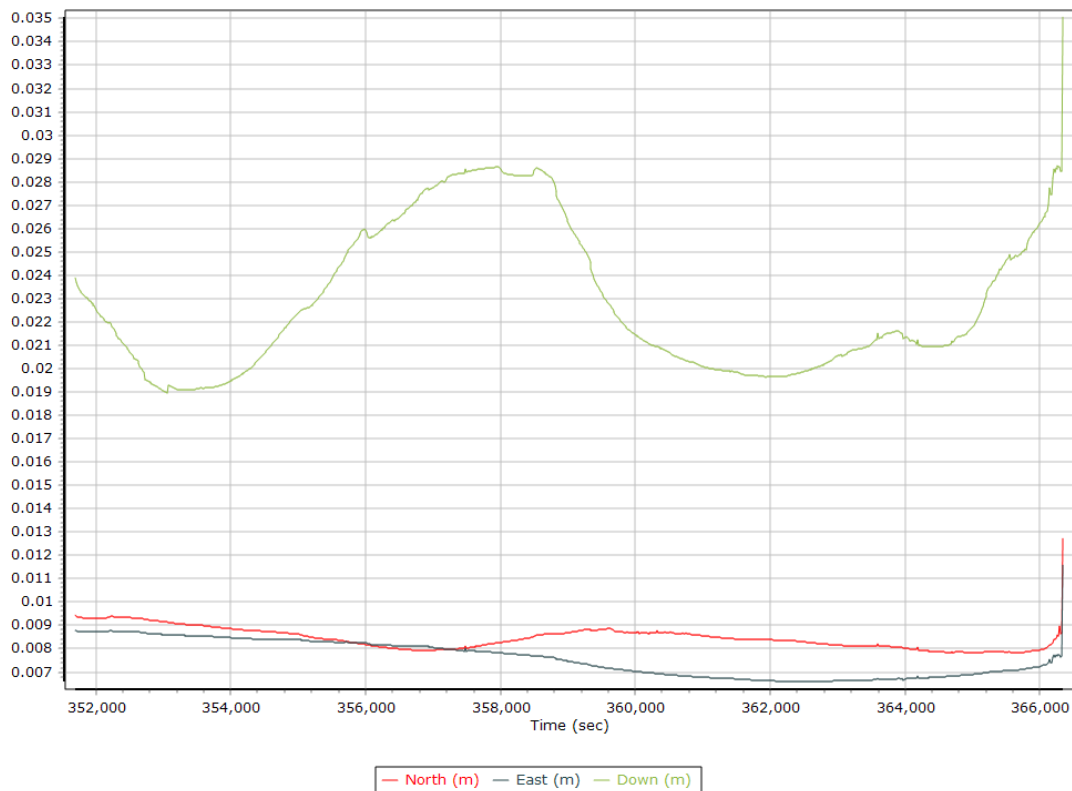
Forward/Reverse Separation



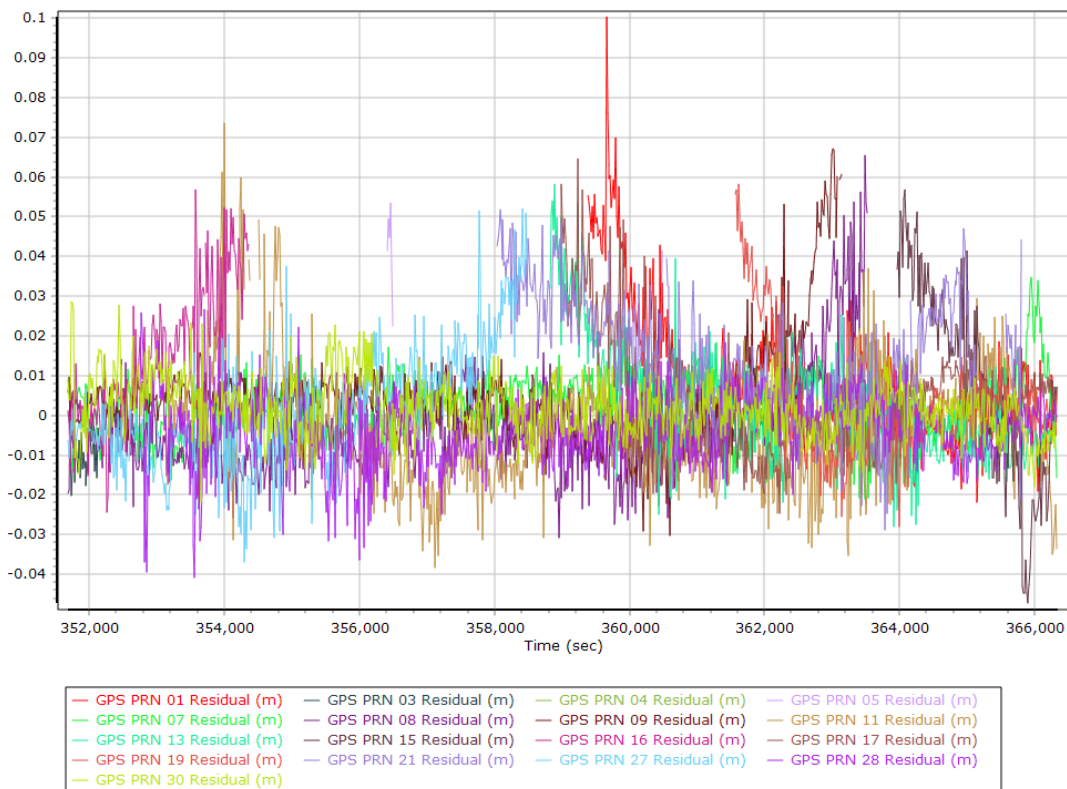
PDOP



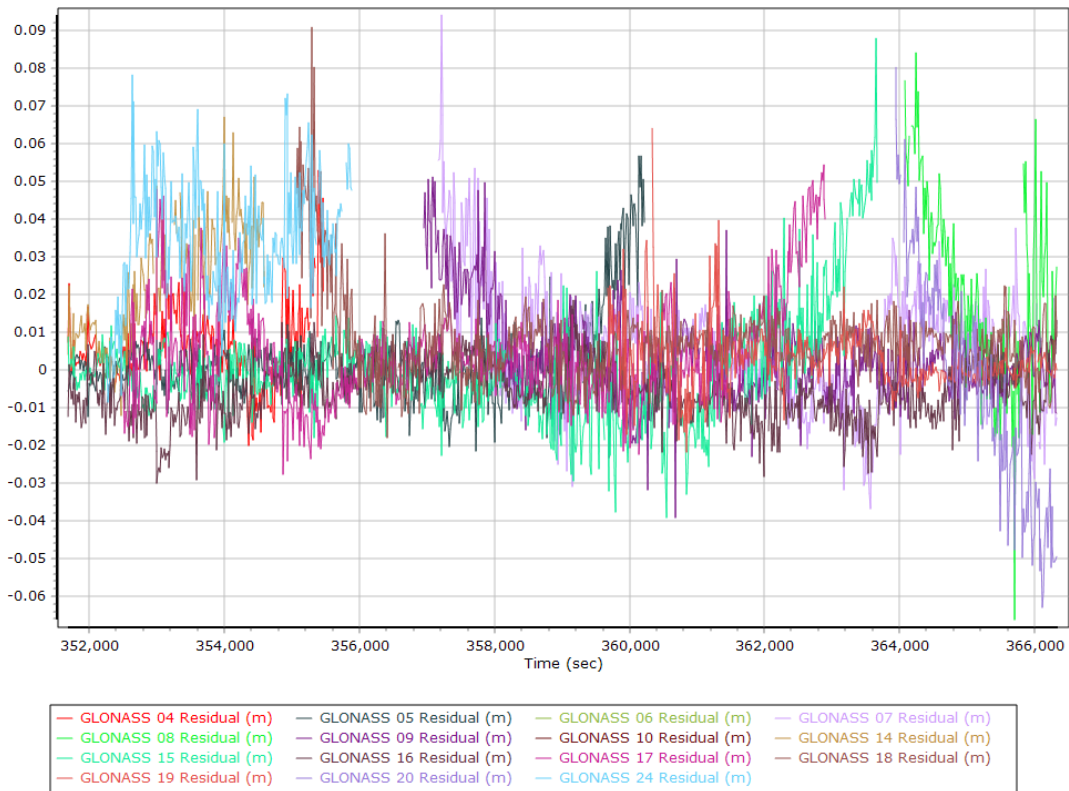
Estimated Position Accuracy



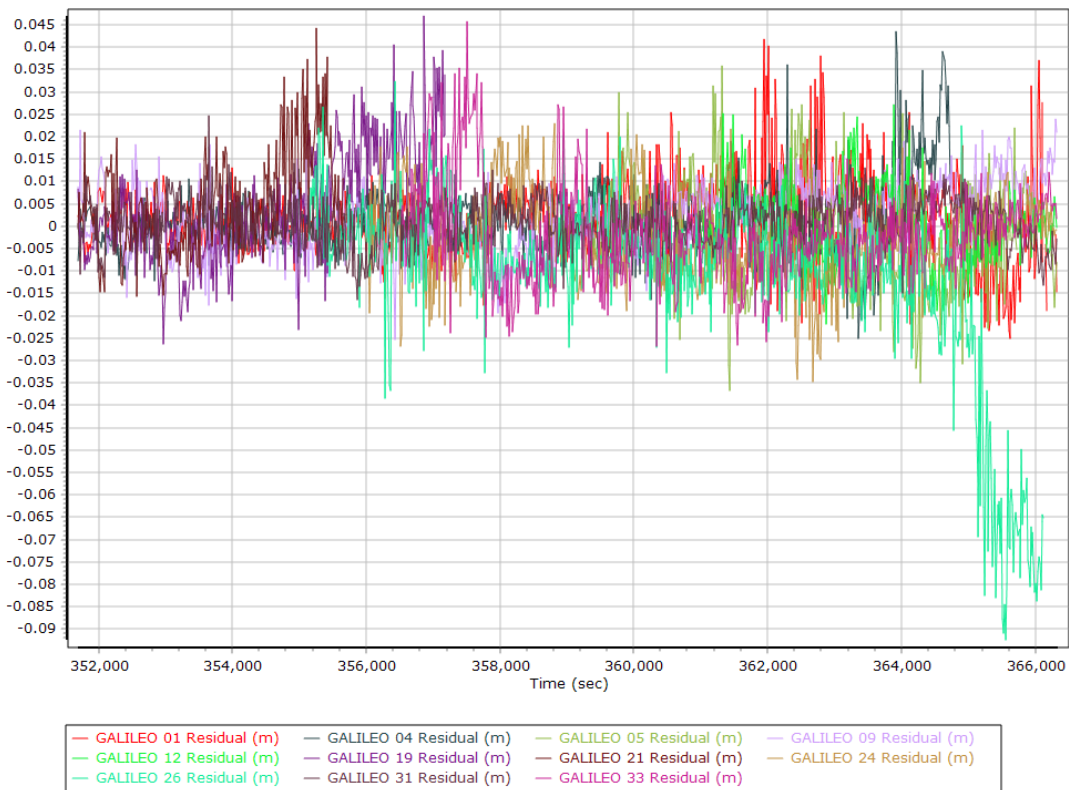
GPS Residuals



GLONASS Residuals



GALILEO Residuals



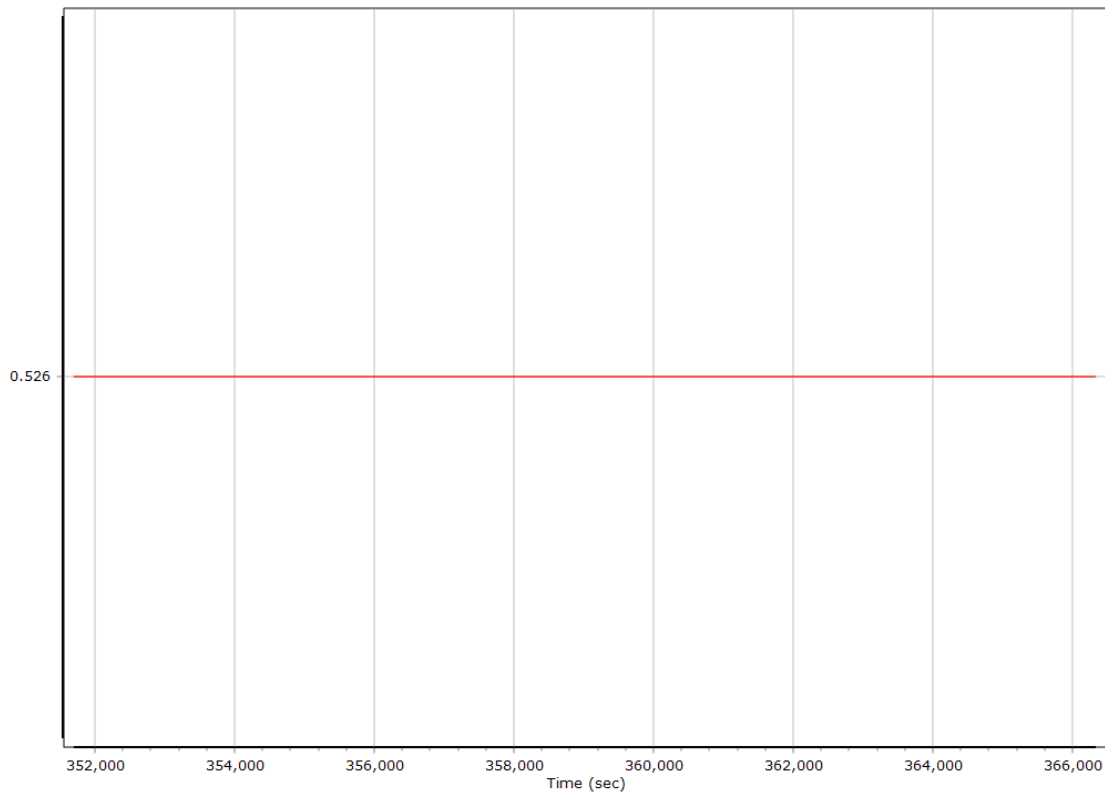
GNSS-Inertial Processor Configuration

Processing mode	IN-Fusion PP-RTX		
Stabilized mount	False		
Processing start time	351316.000 (11/5/2020 1:35:16 AM)		
Processing end time	366346.000 (11/5/2020 5:45:46 AM)		
Initial attitude source	Real-Time VNAV/RNAV Attitude		
IMU Sensor Context	Processing with Onboard IMU		
Reference to IMU lever arm (m)	0.000	0.000	0.000
Reference to IMU mounting angles (deg)	0.000	0.000	-90.000
Reference to Primary GNSS lever arm (m)	0.526	0.199	-1.199
Reference to Primary GNSS lever arm std dev (m)	0.030	0.030	0.030
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

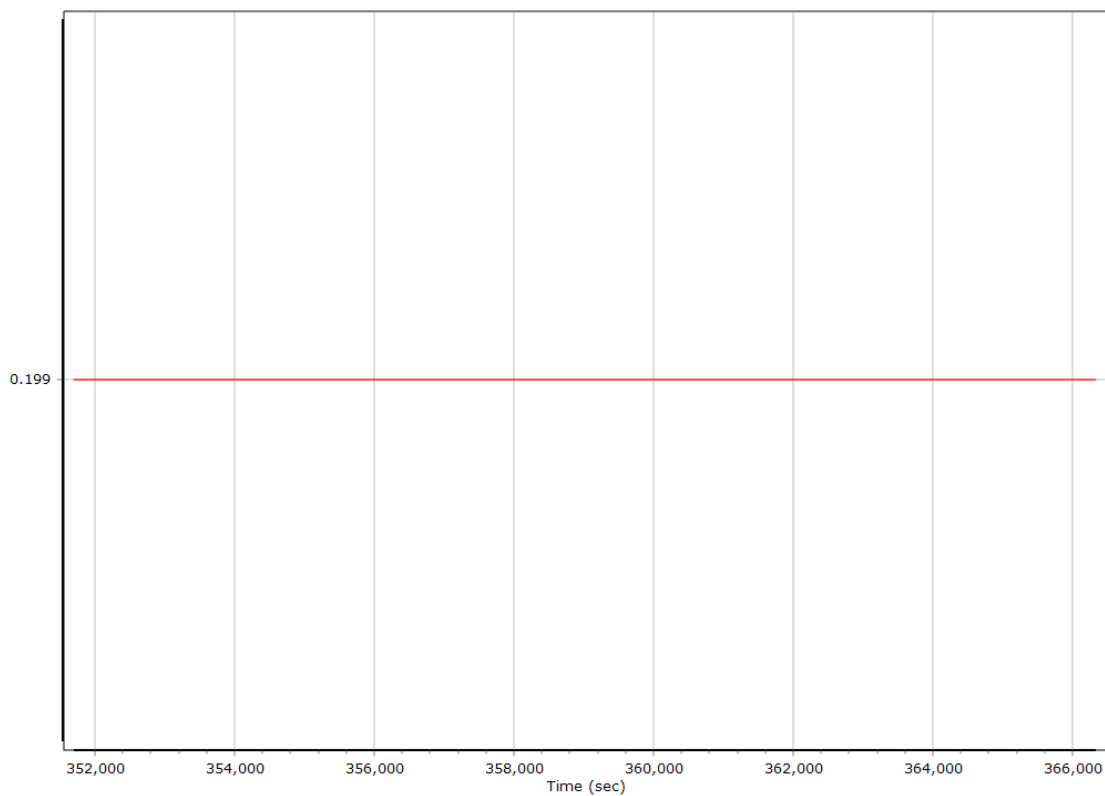
Calibrated Installation Parameters

Reference-Primary GNSS Lever Arm (m)

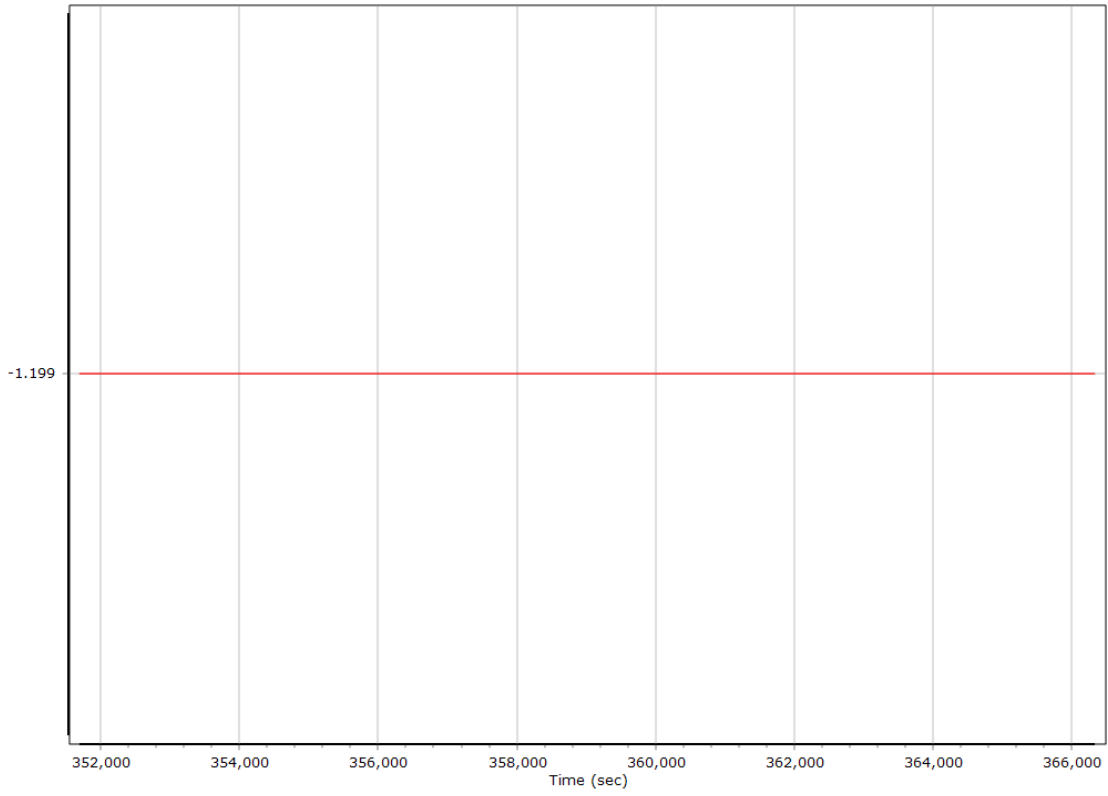
X Reference-Primary GNSS Lever Arm (m)



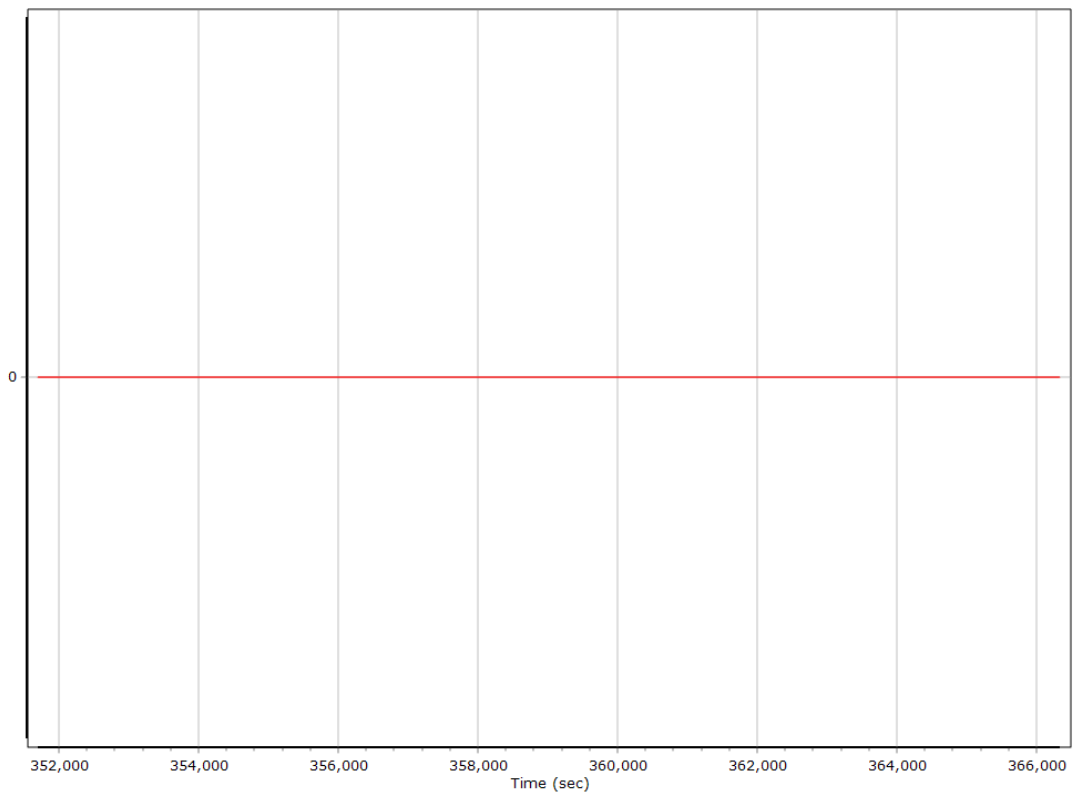
Y Reference-Primary GNSS Lever Arm (m)



Z Reference-Primary GNSS Lever Arm (m)



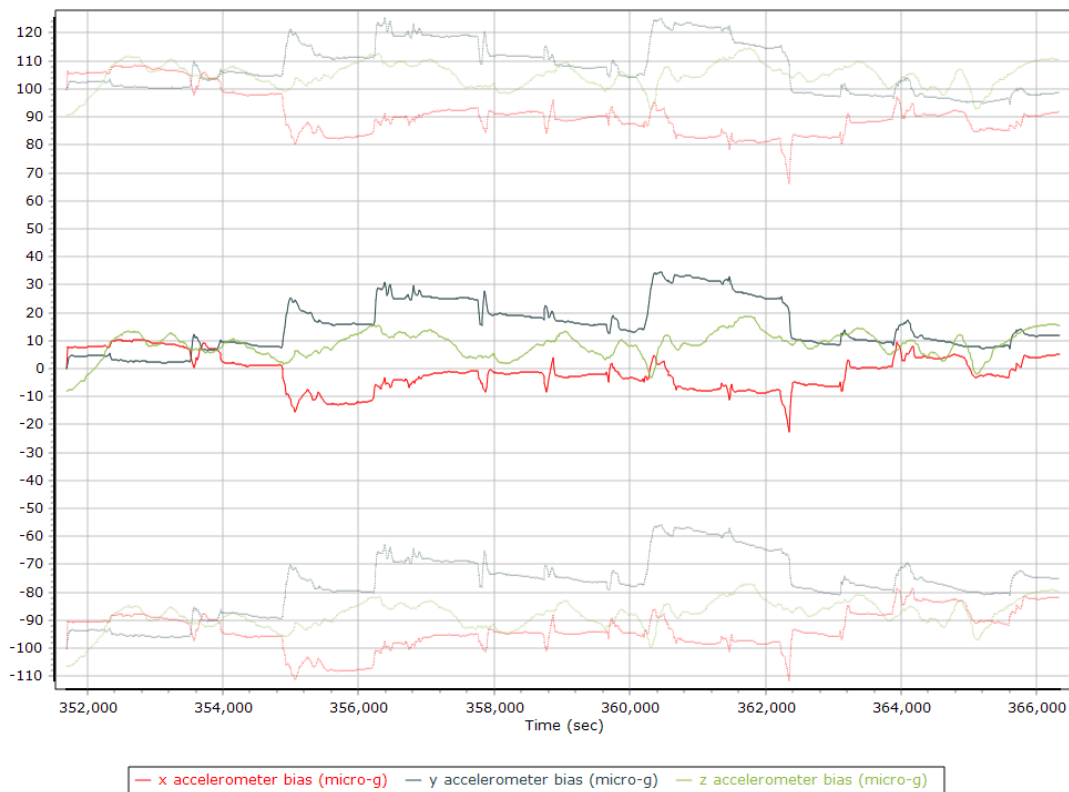
Reference-Primary GNSS Lever Arm Figure of Merit



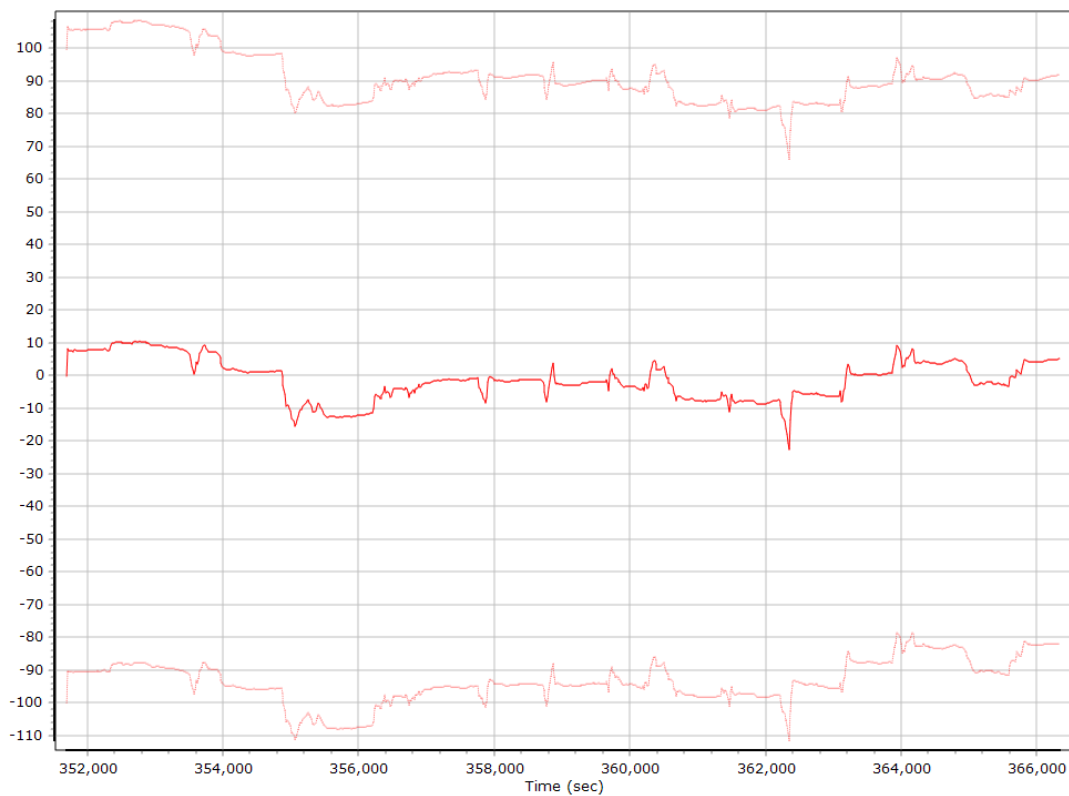
IN-Fusion QC

Forward Processed Estimated Errors, Reference Frame

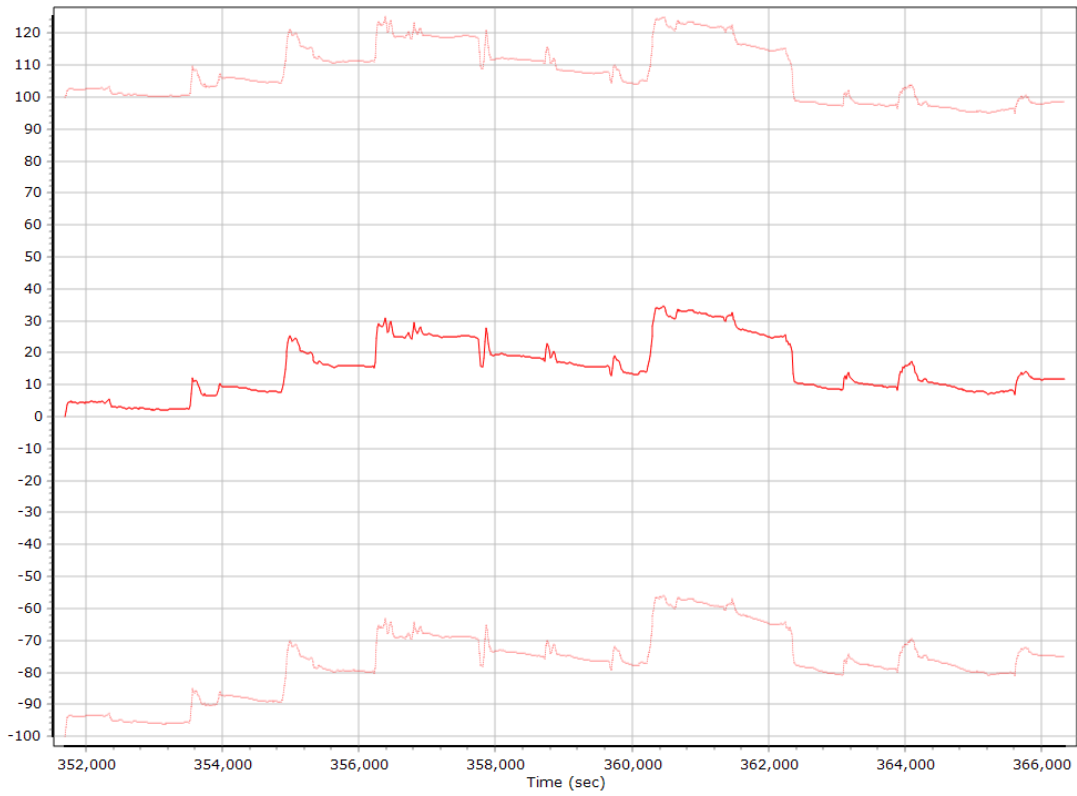
Accelerometer Bias (micro-g)



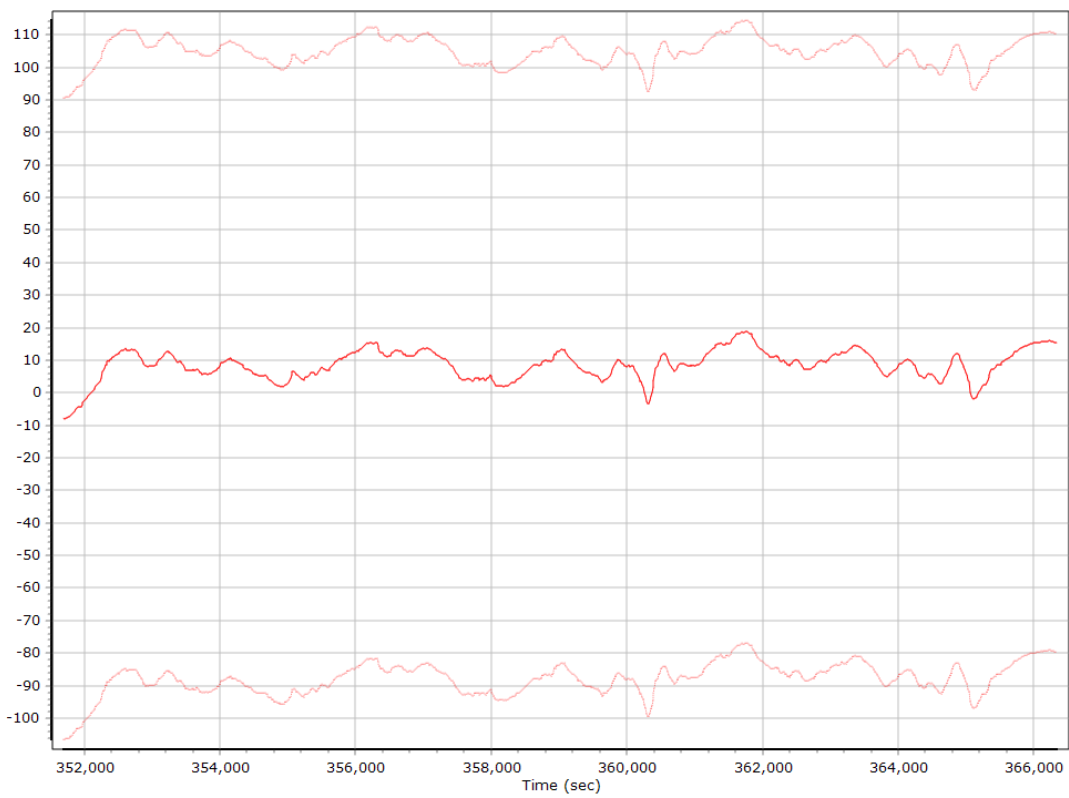
X Accelerometer Bias (micro-g)



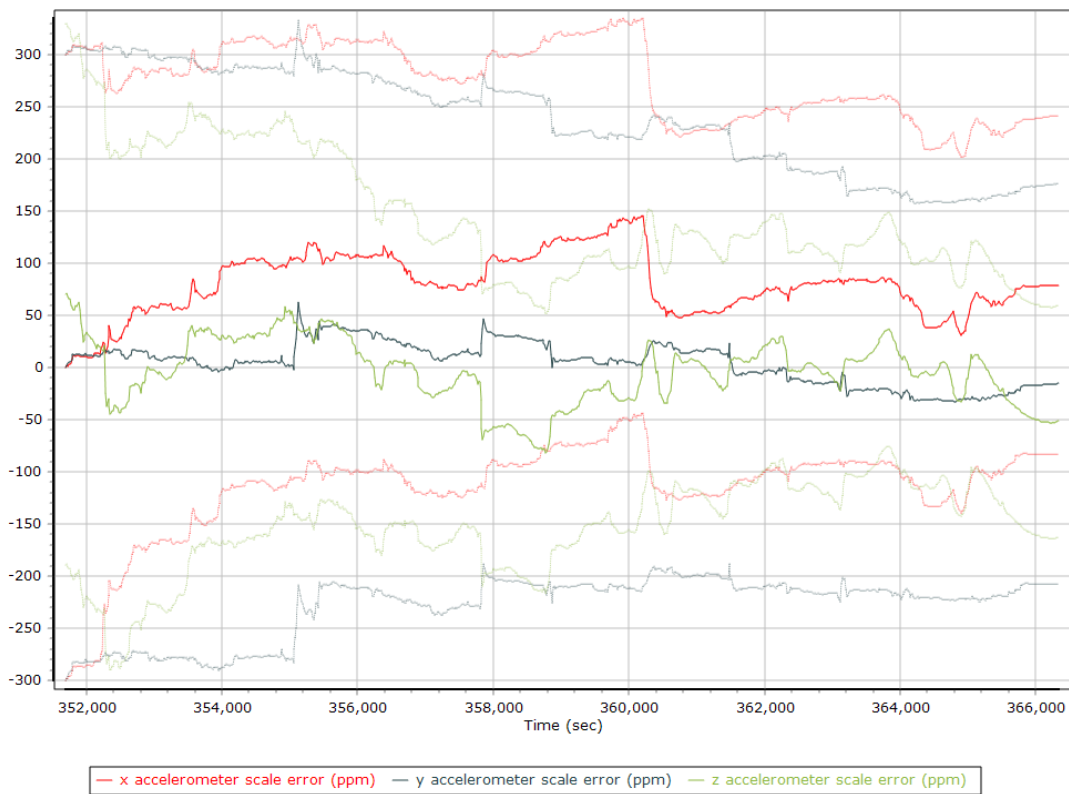
Y Accelerometer Bias (micro-g)



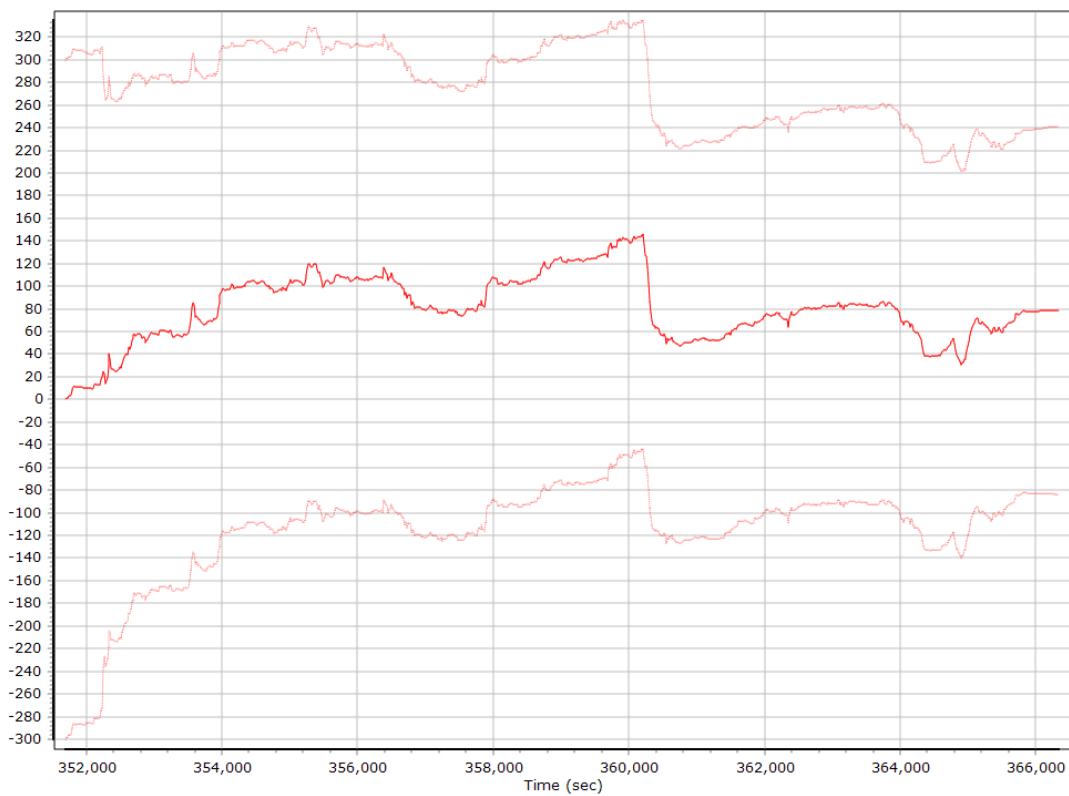
Z Accelerometer Bias (micro-g)



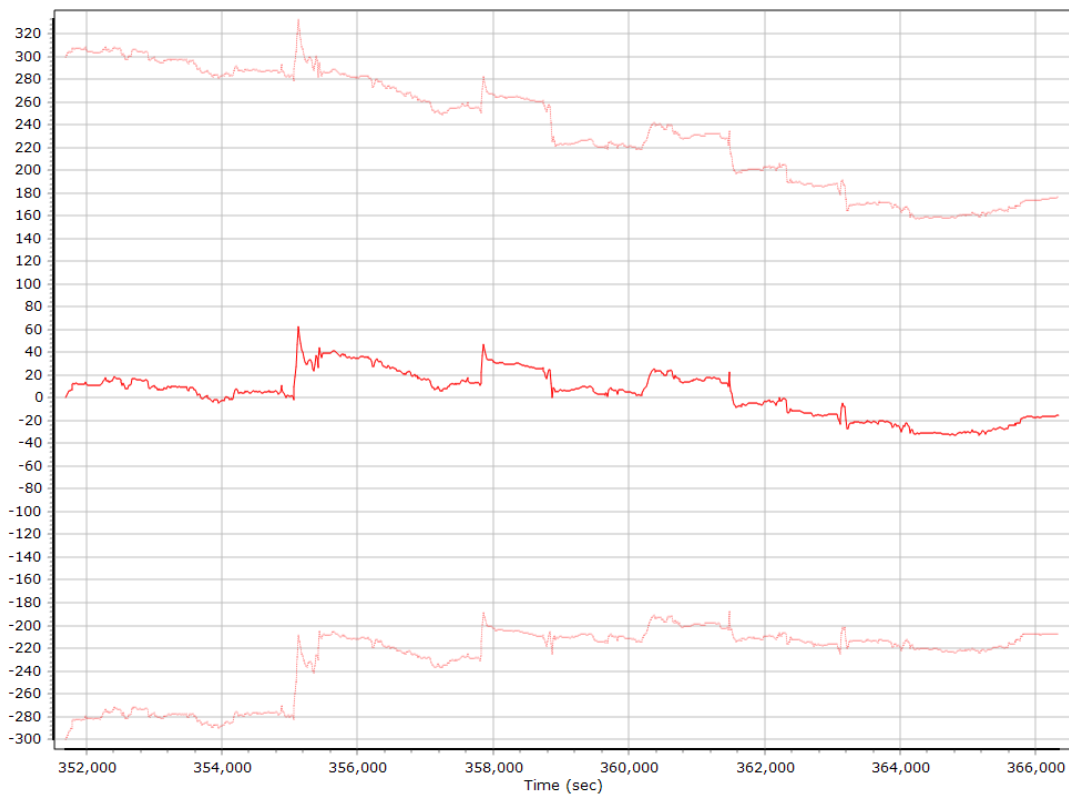
Accelerometer Scale Error (ppm)



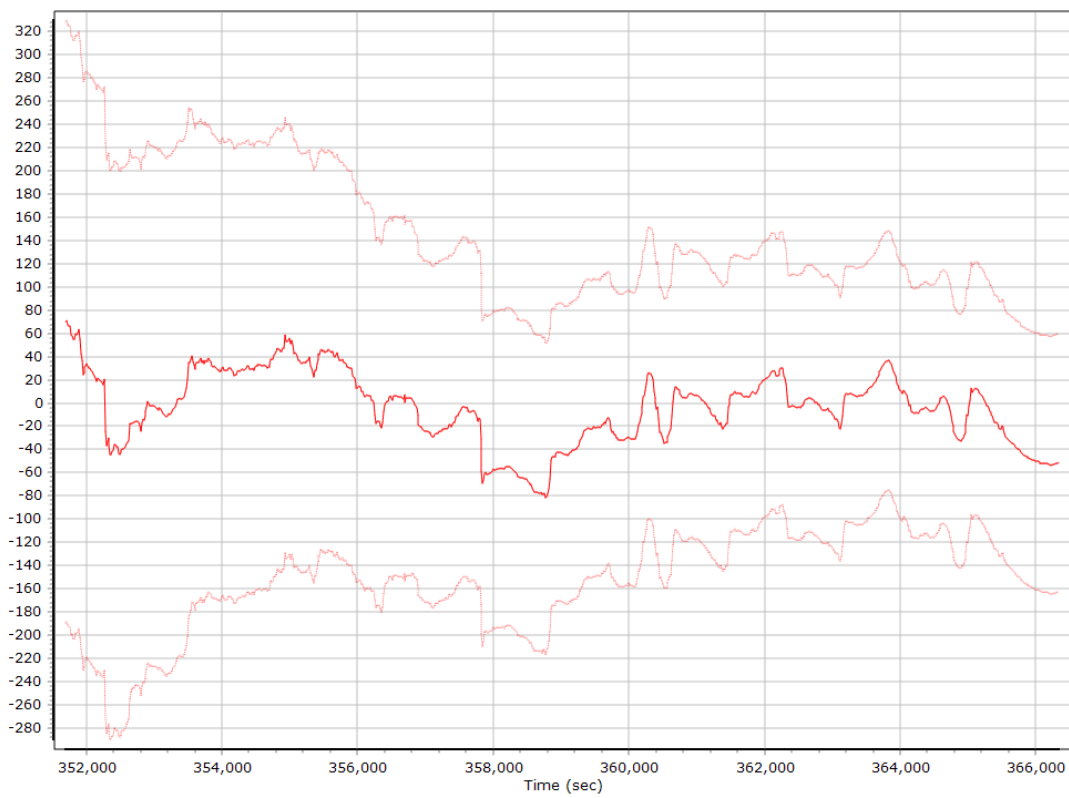
X Accelerometer Scale Error (ppm)



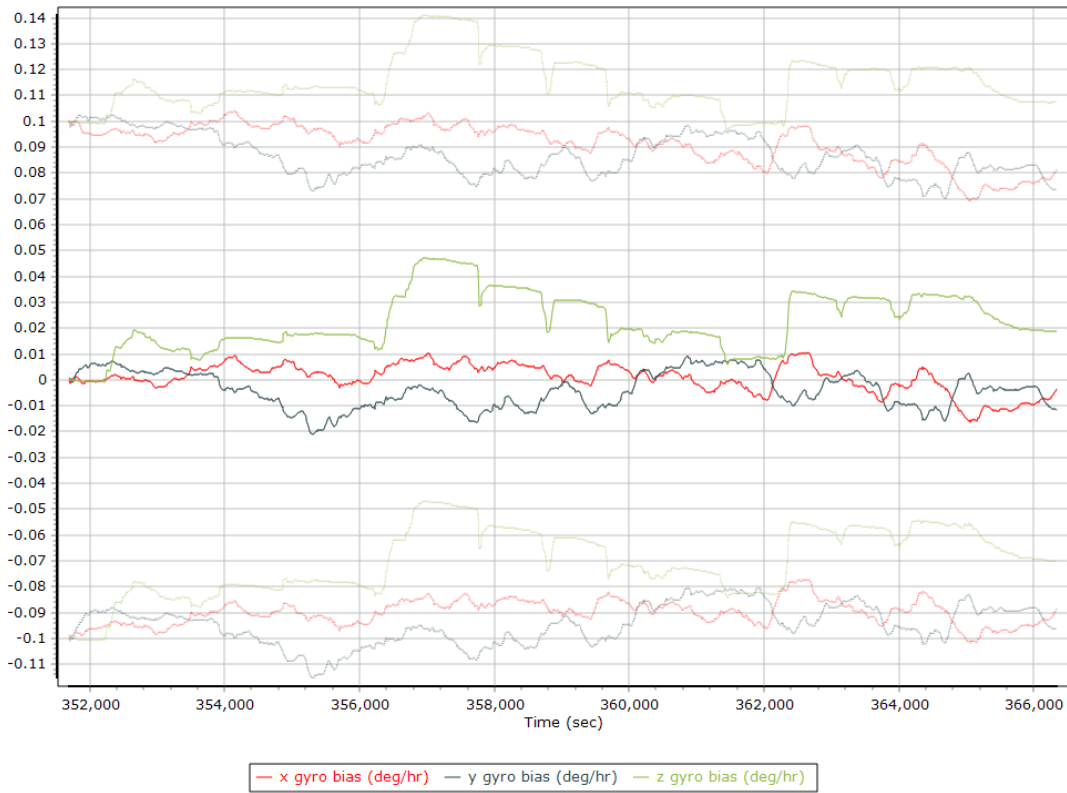
Y Accelerometer Scale Error (ppm)



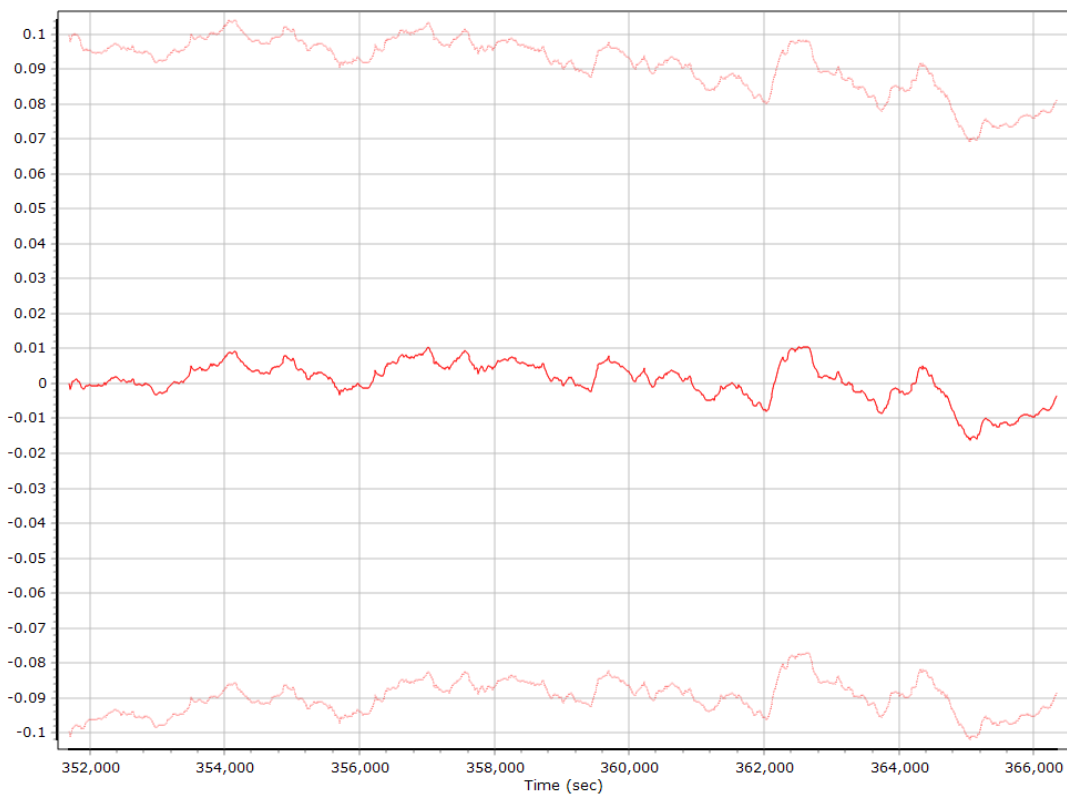
Z Accelerometer Scale Error (ppm)



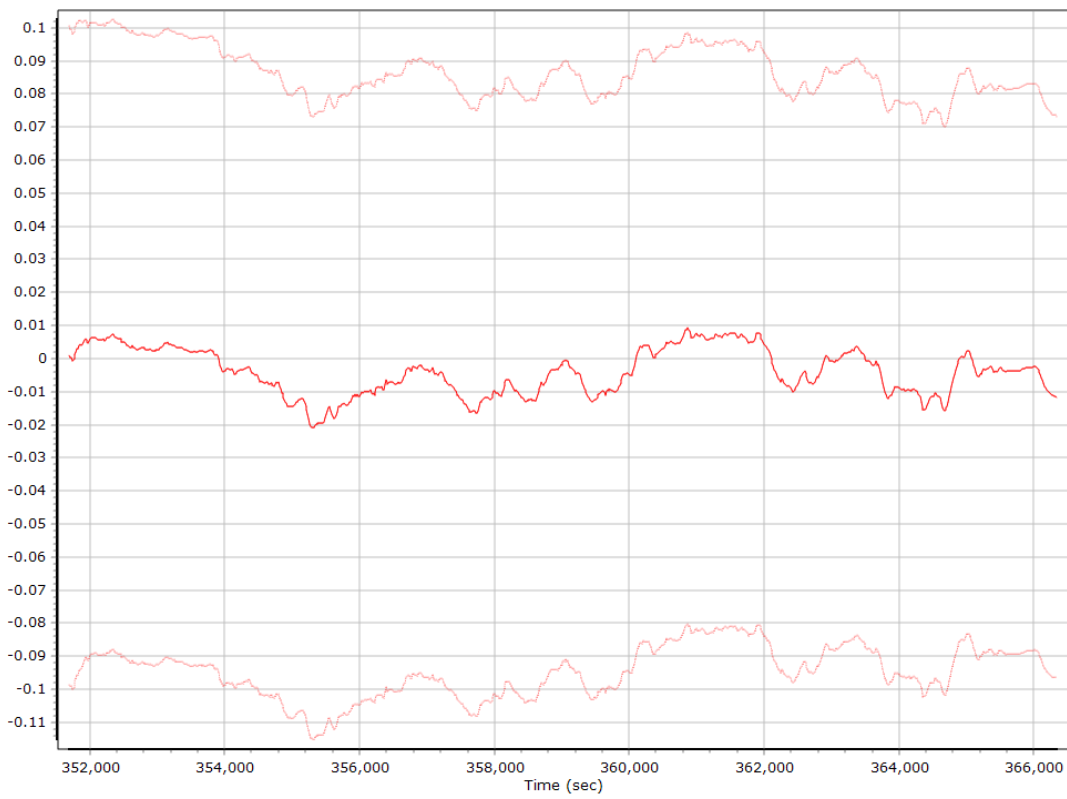
Gyro Bias (deg/h)



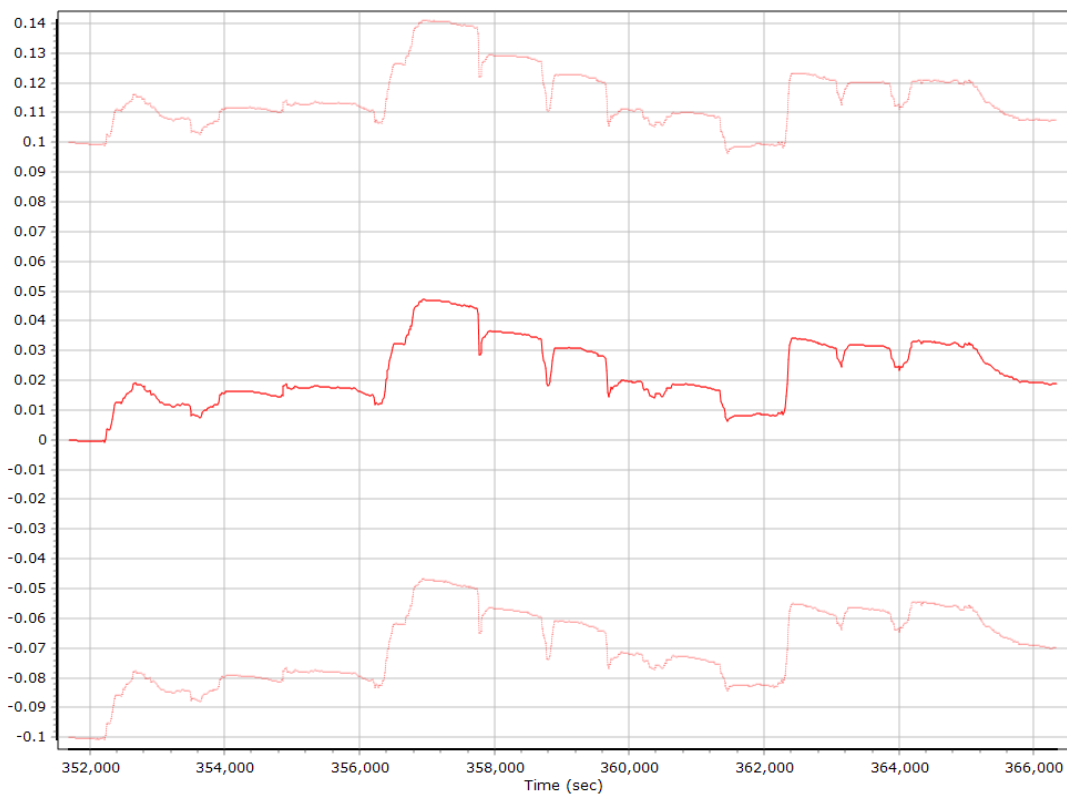
X Gyro Bias (deg/h)



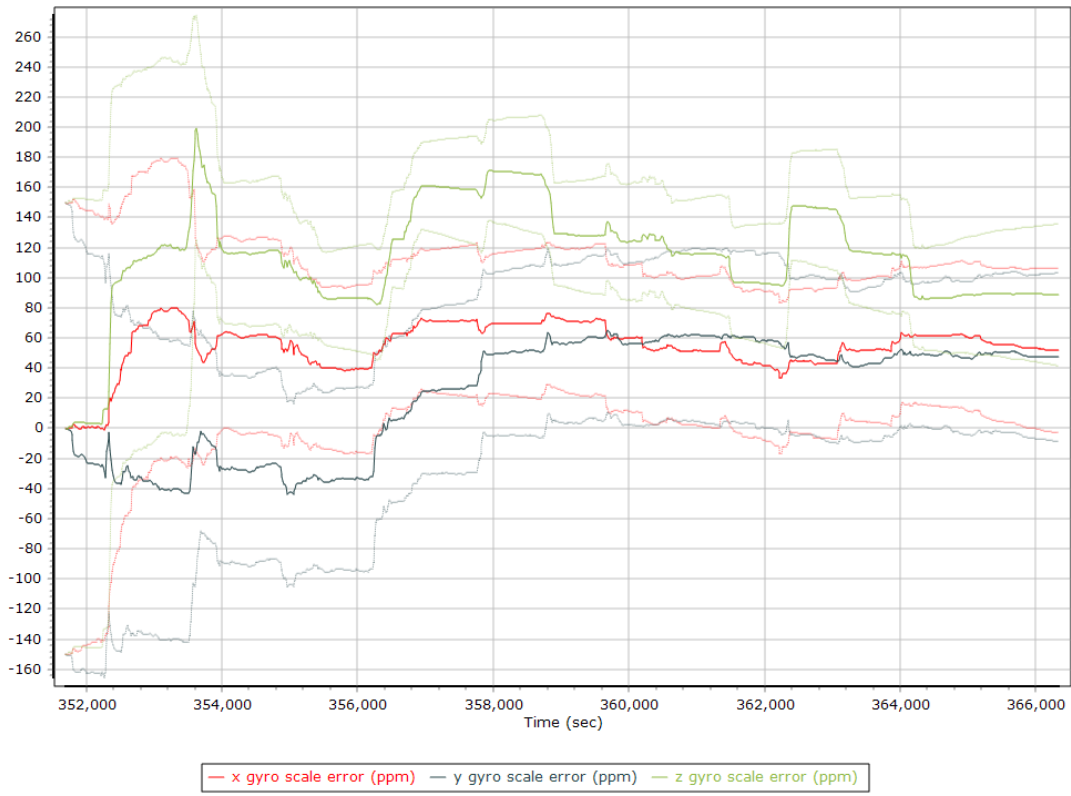
Y Gyro Bias (deg/h)



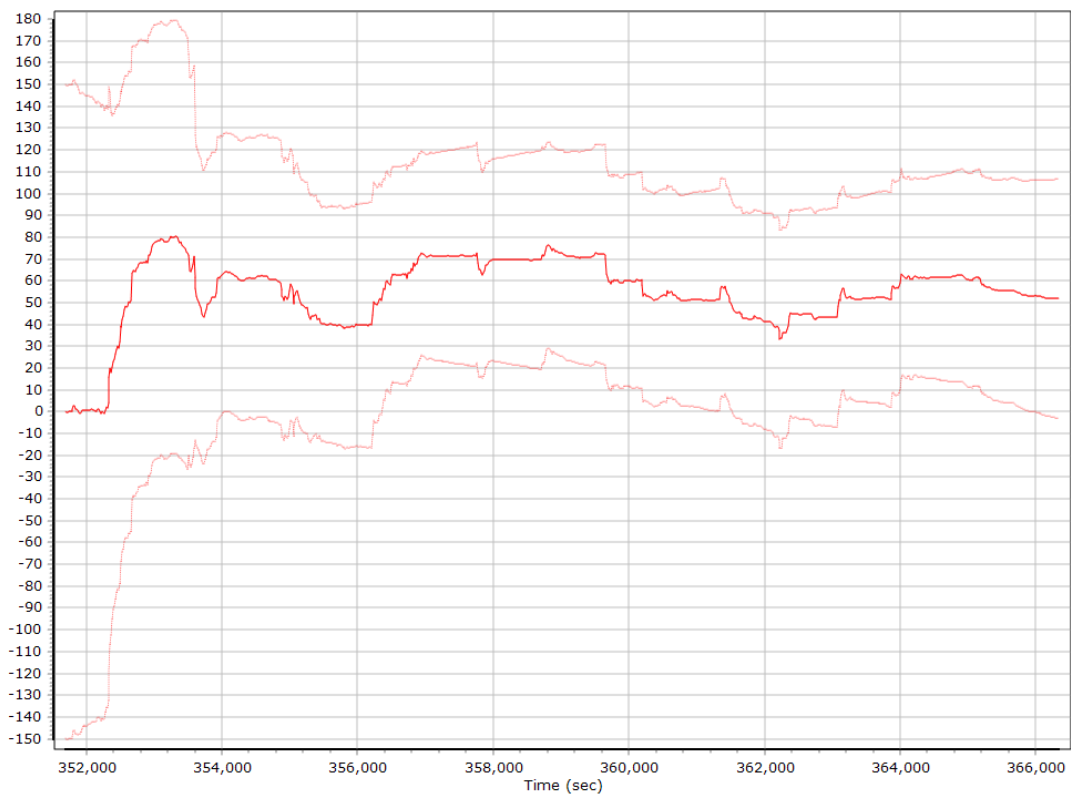
Z Gyro Bias (deg/h)



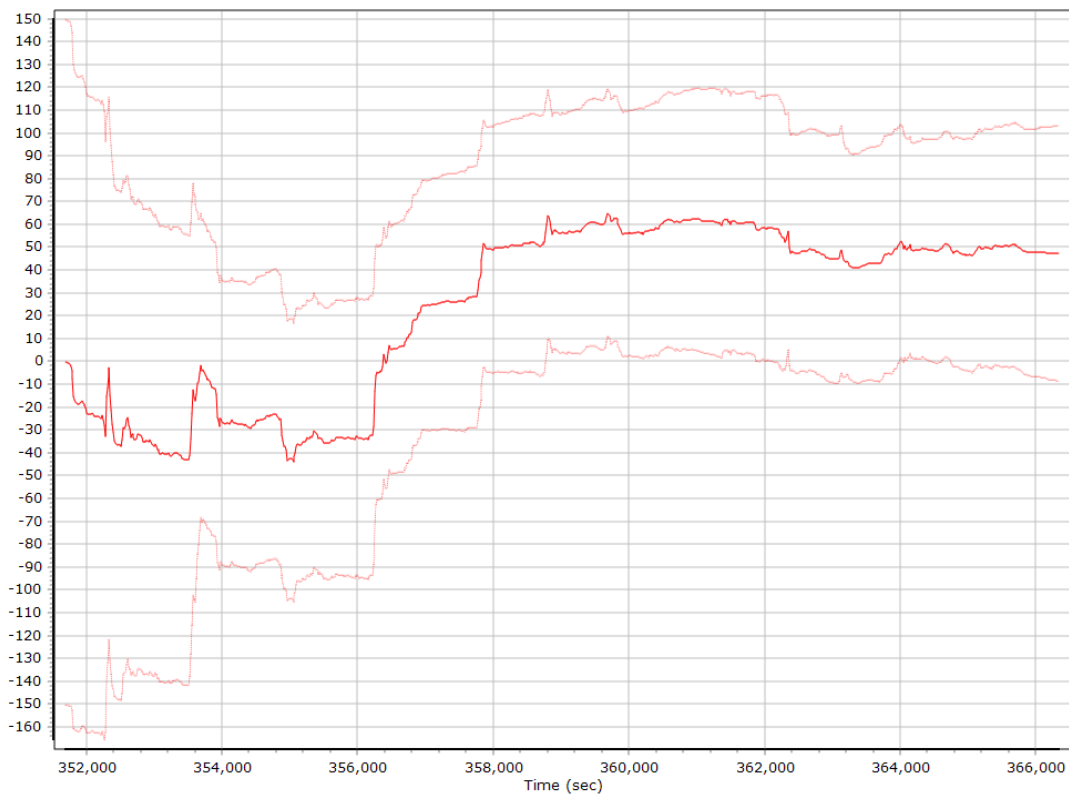
Gyro Scale Error (ppm)



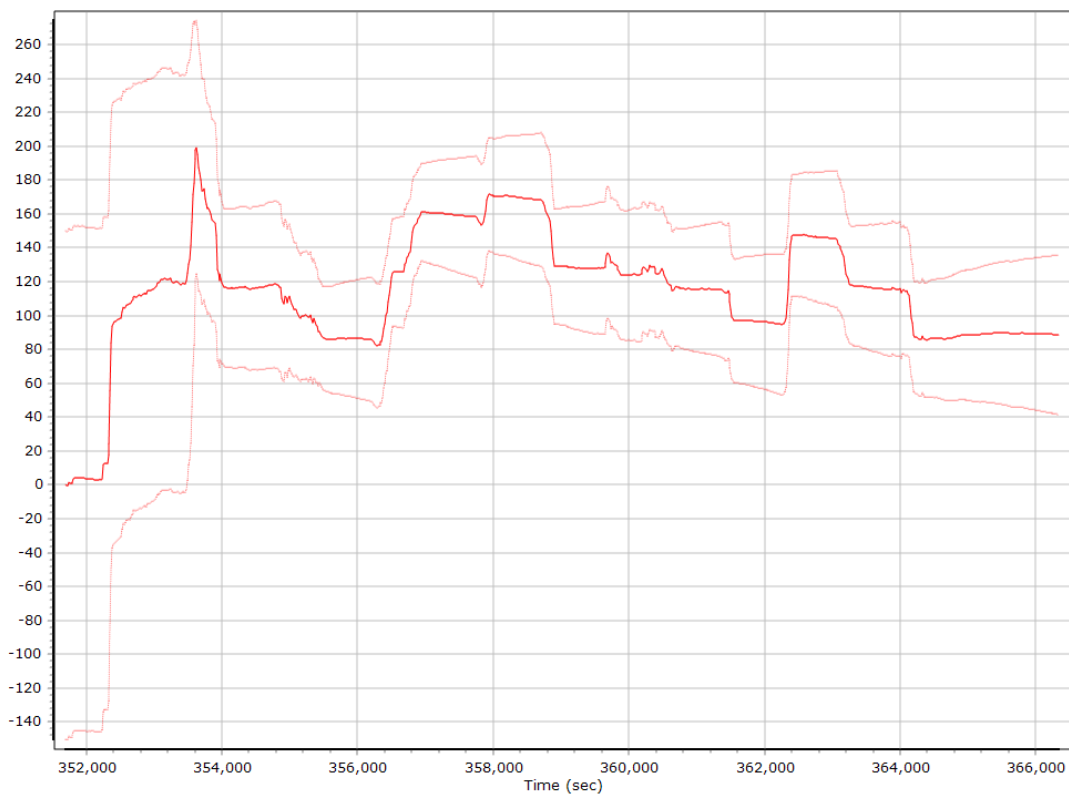
X Gyro Scale Error (ppm)



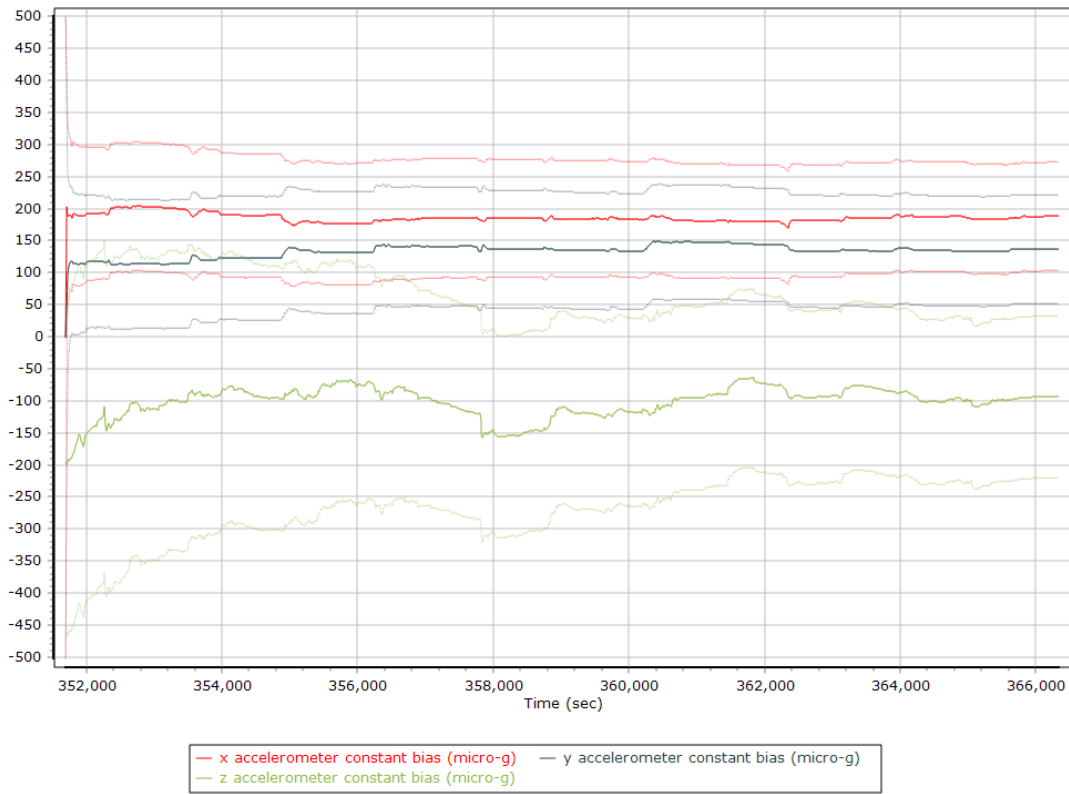
Y Gyro Scale Error (ppm)



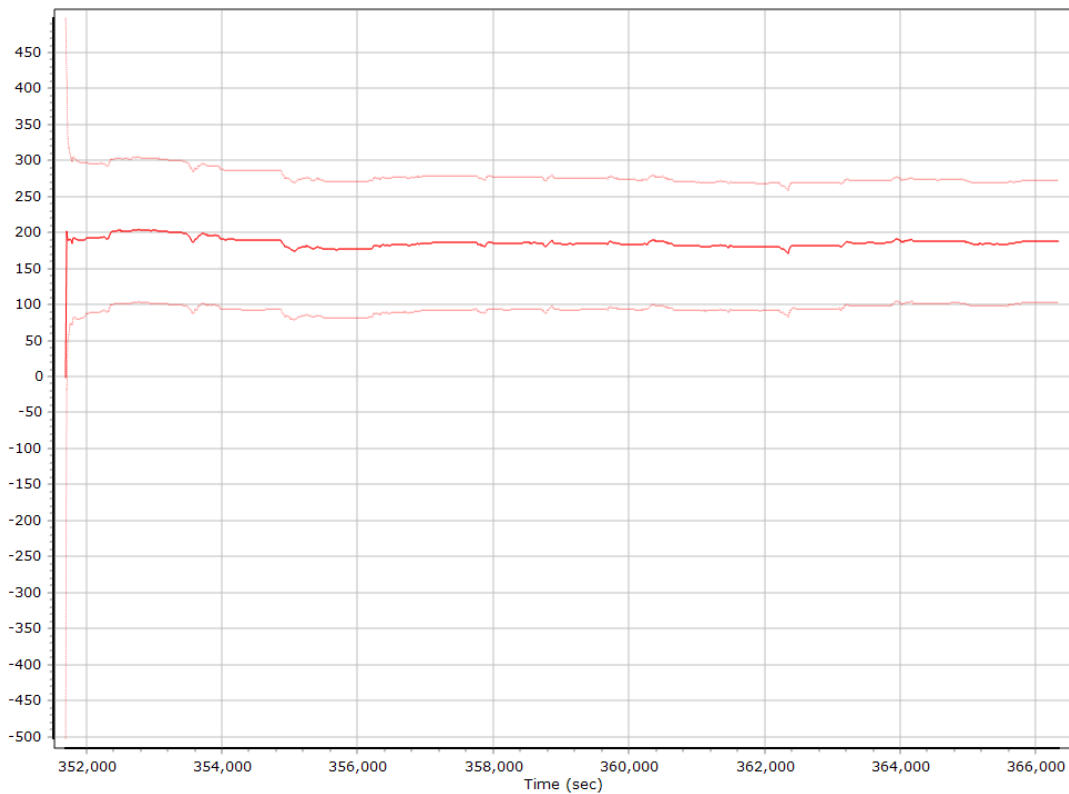
Z Gyro Scale Error (ppm)



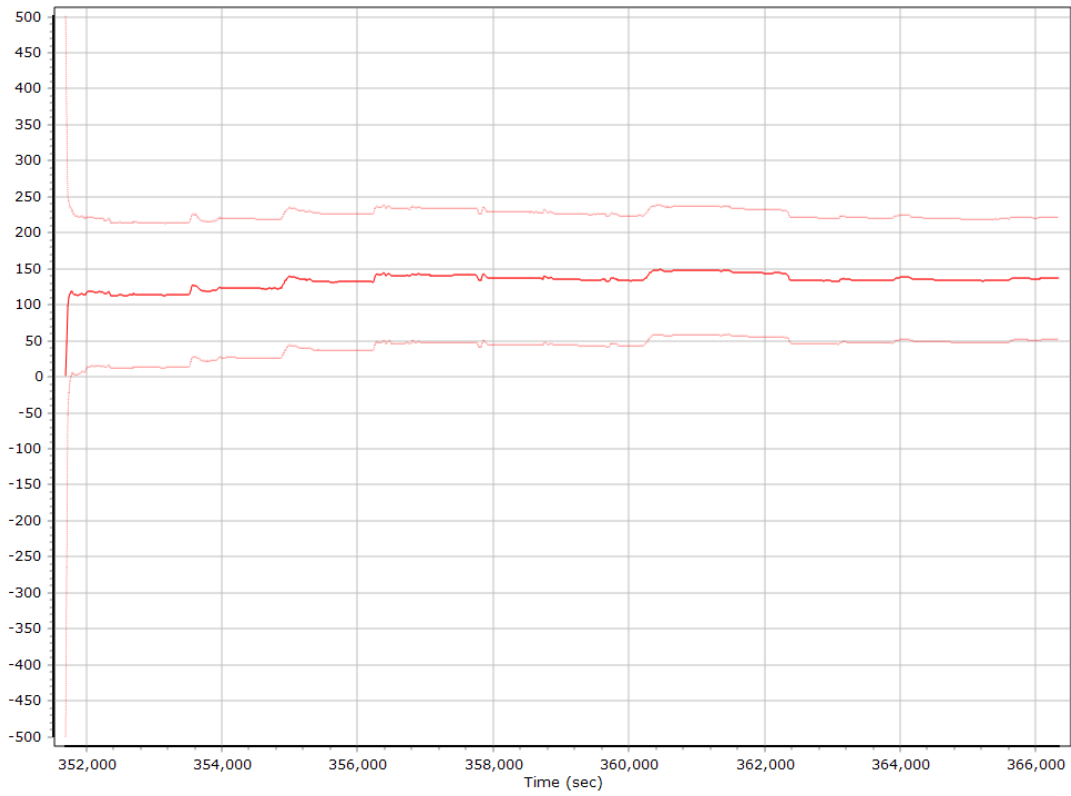
Forward Processed Estimated Constant Errors, Reference Frame Accelerometer Bias (micro-g)



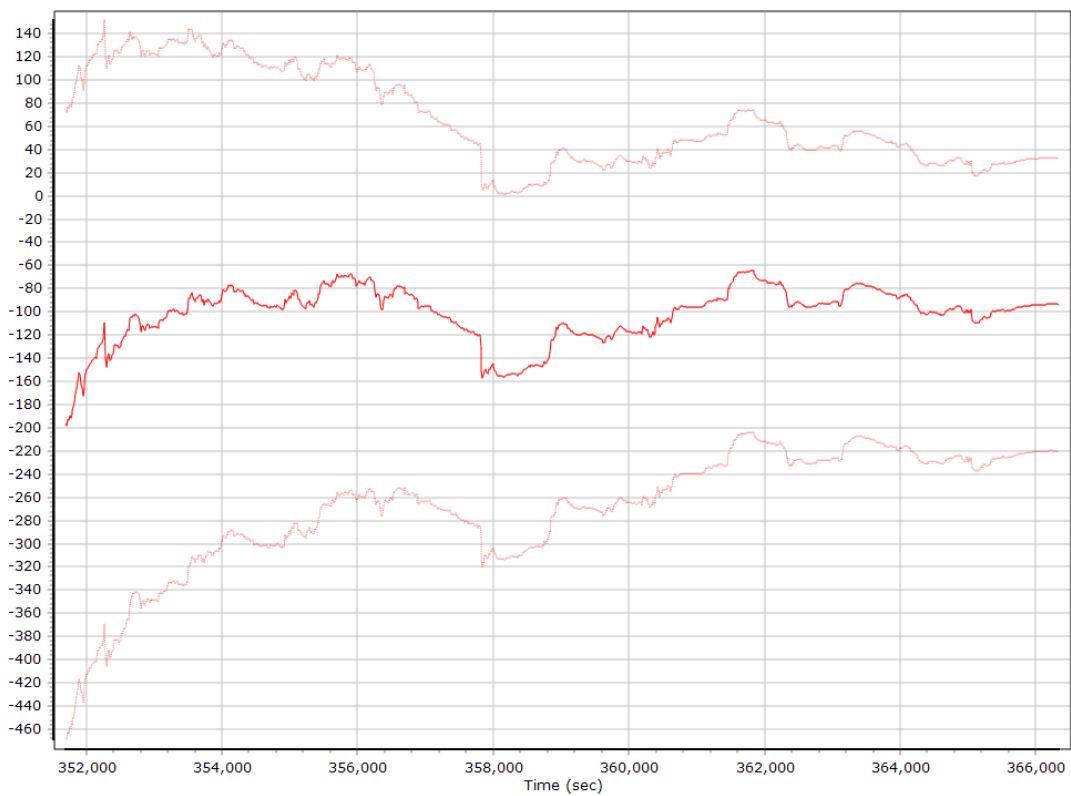
X Accelerometer Bias (micro-g)



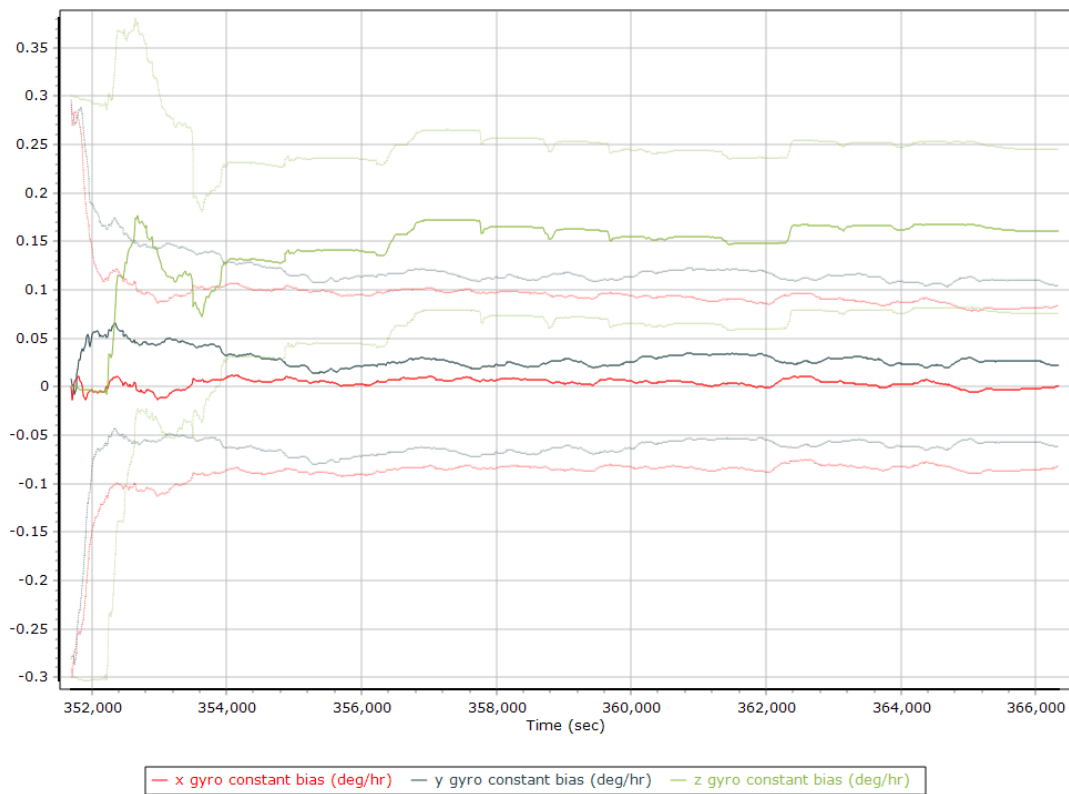
Y Accelerometer Bias (micro-g)



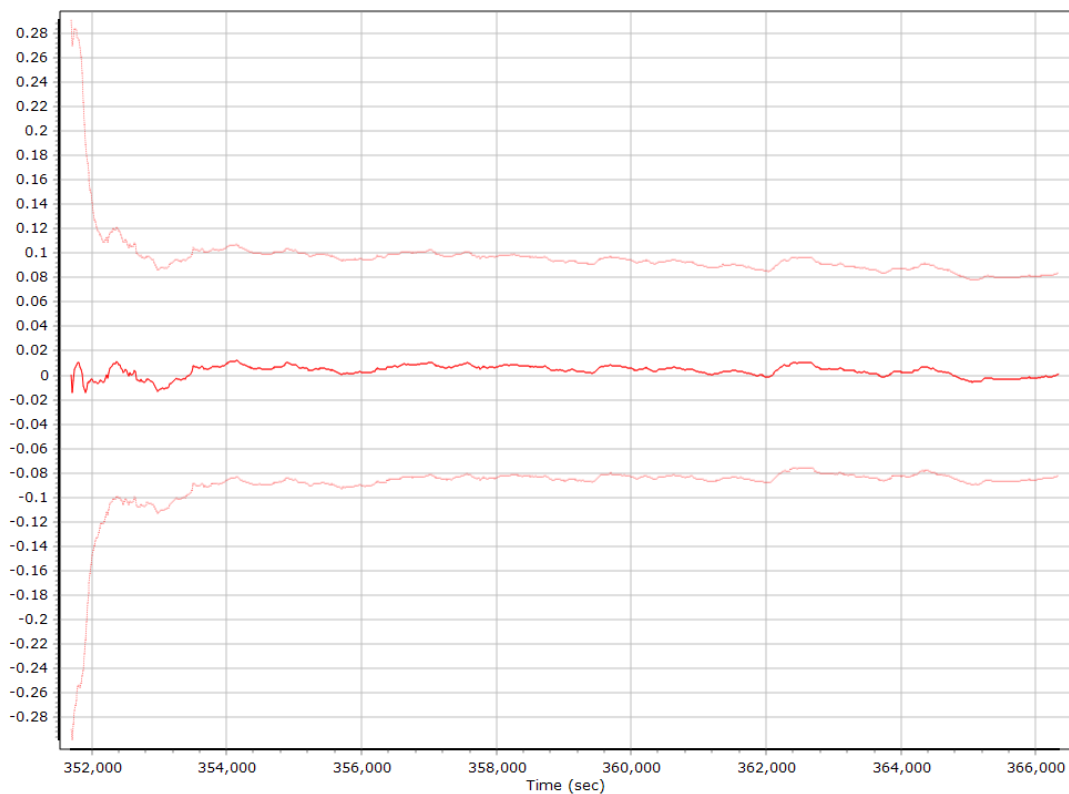
Z Accelerometer Bias (micro-g)



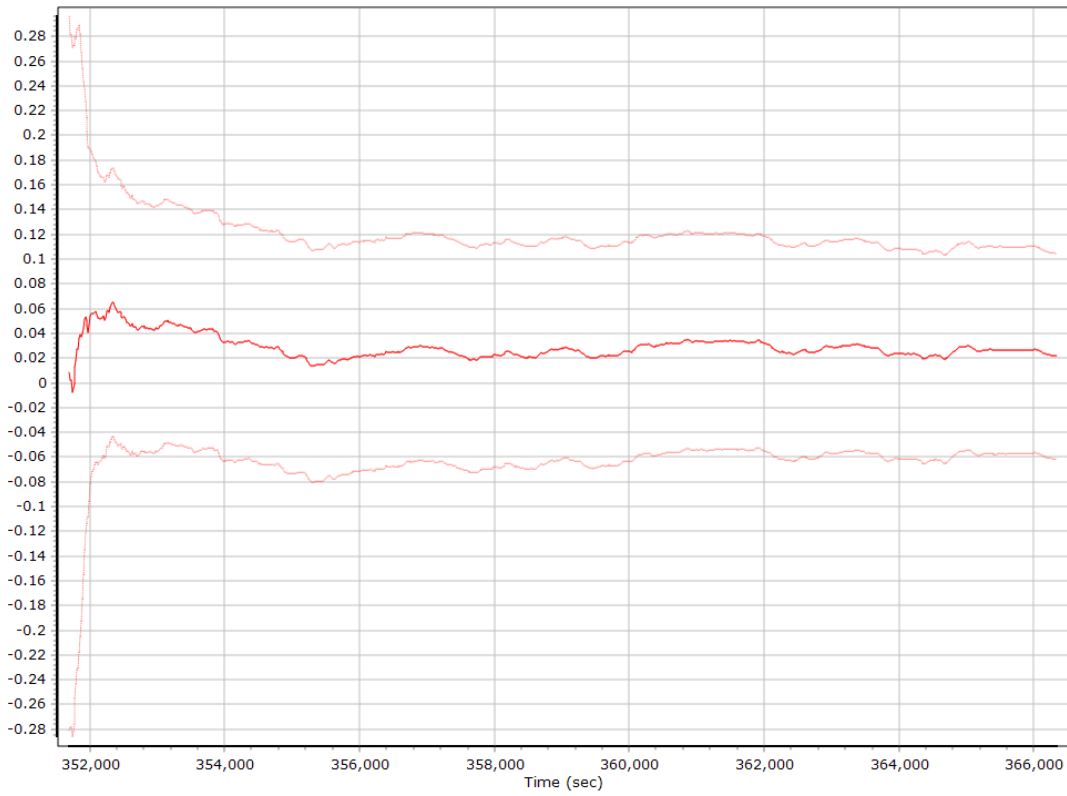
Gyro Bias (deg/h)



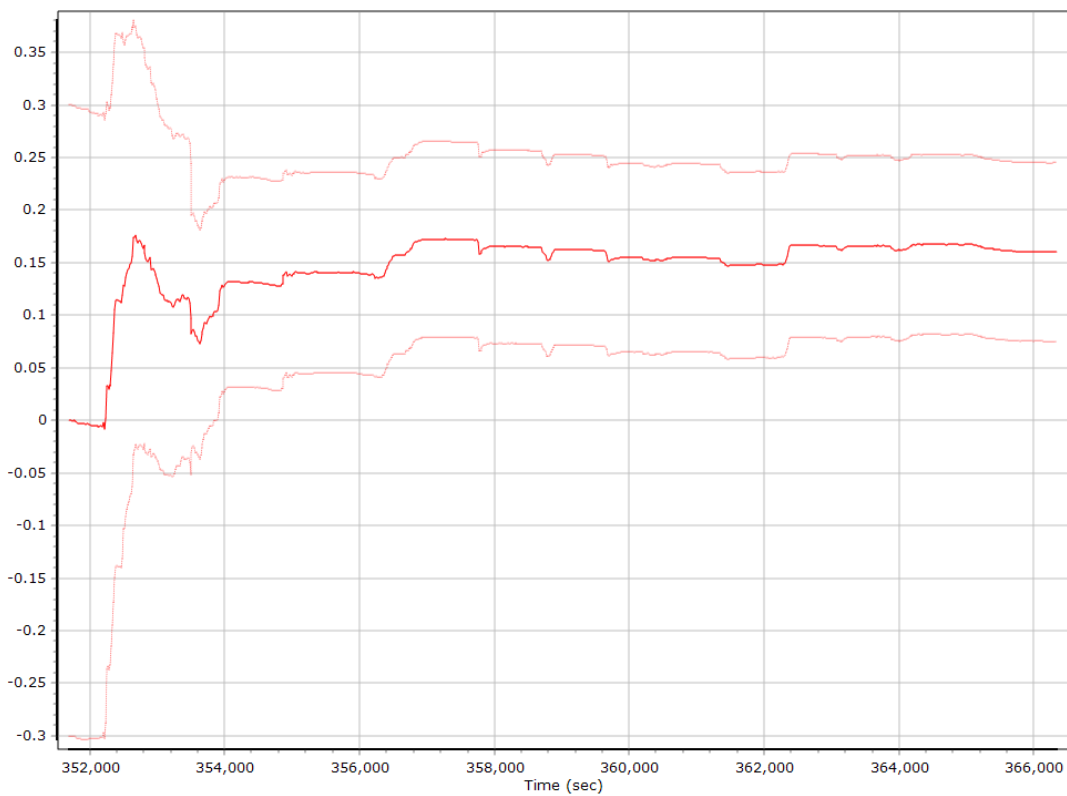
X Gyro Bias (deg/h)



Y Gyro Bias (deg/h)

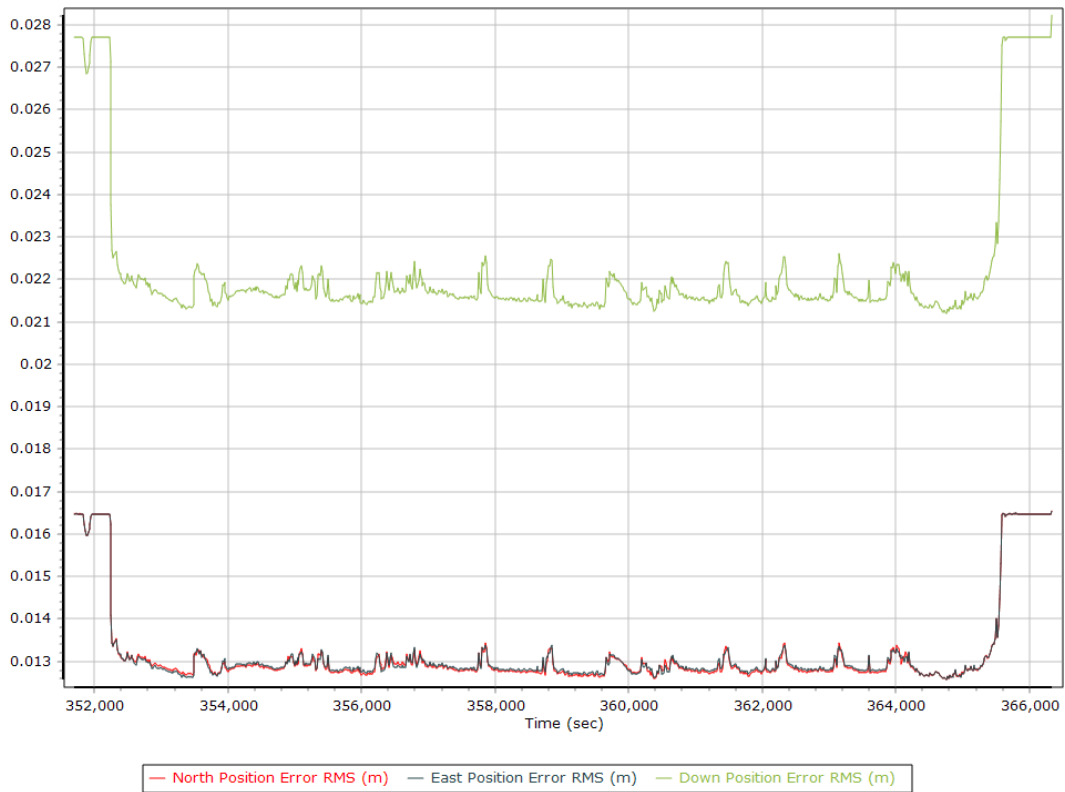


Z Gyro Bias (deg/h)

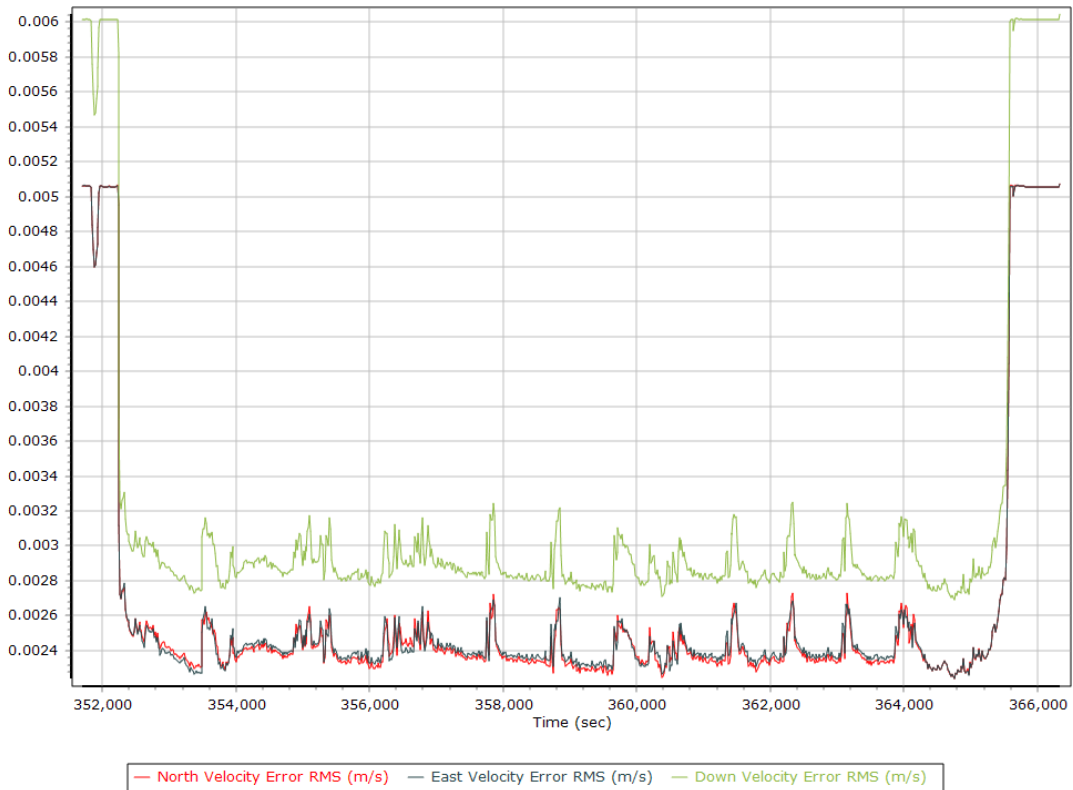


Smoothed Performance Metrics

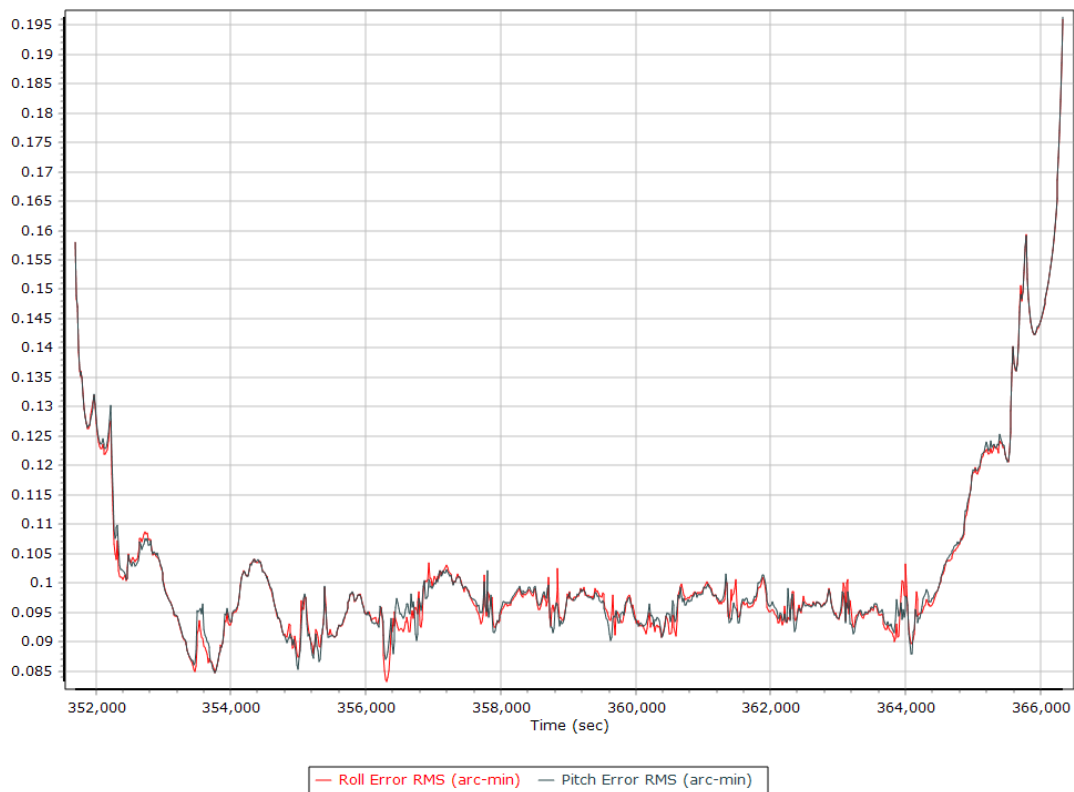
Position Error RMS (m)



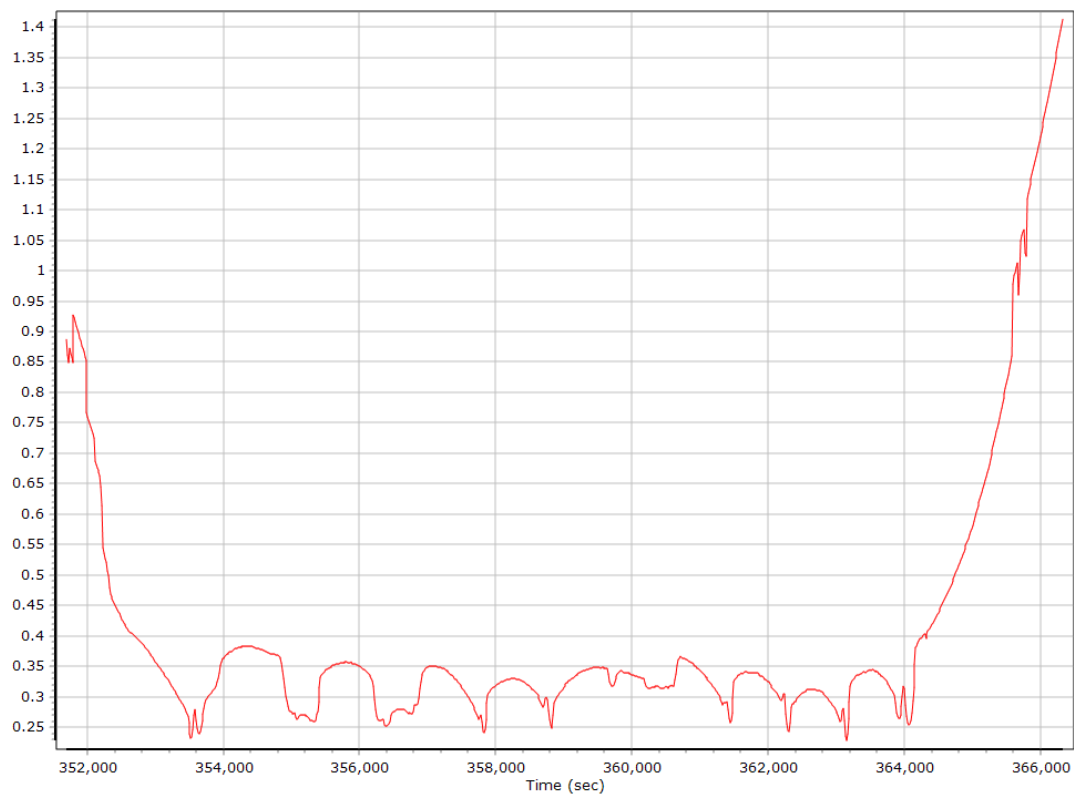
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

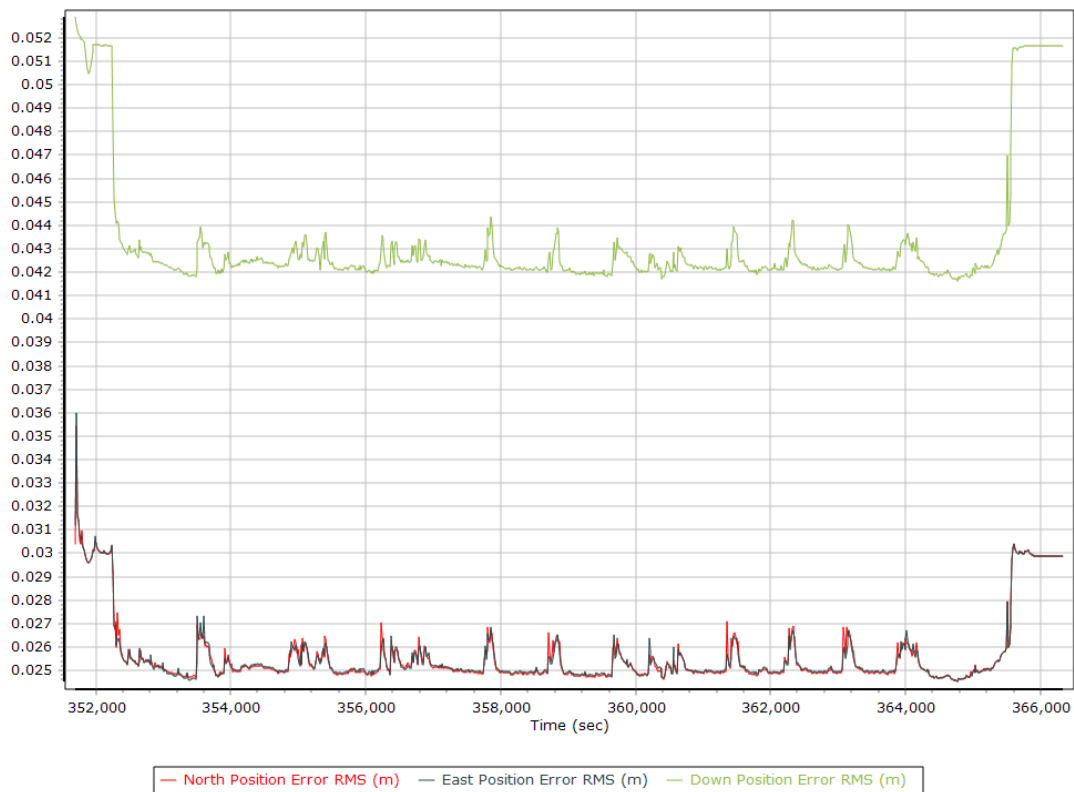


Heading Error RMS (arc-min)

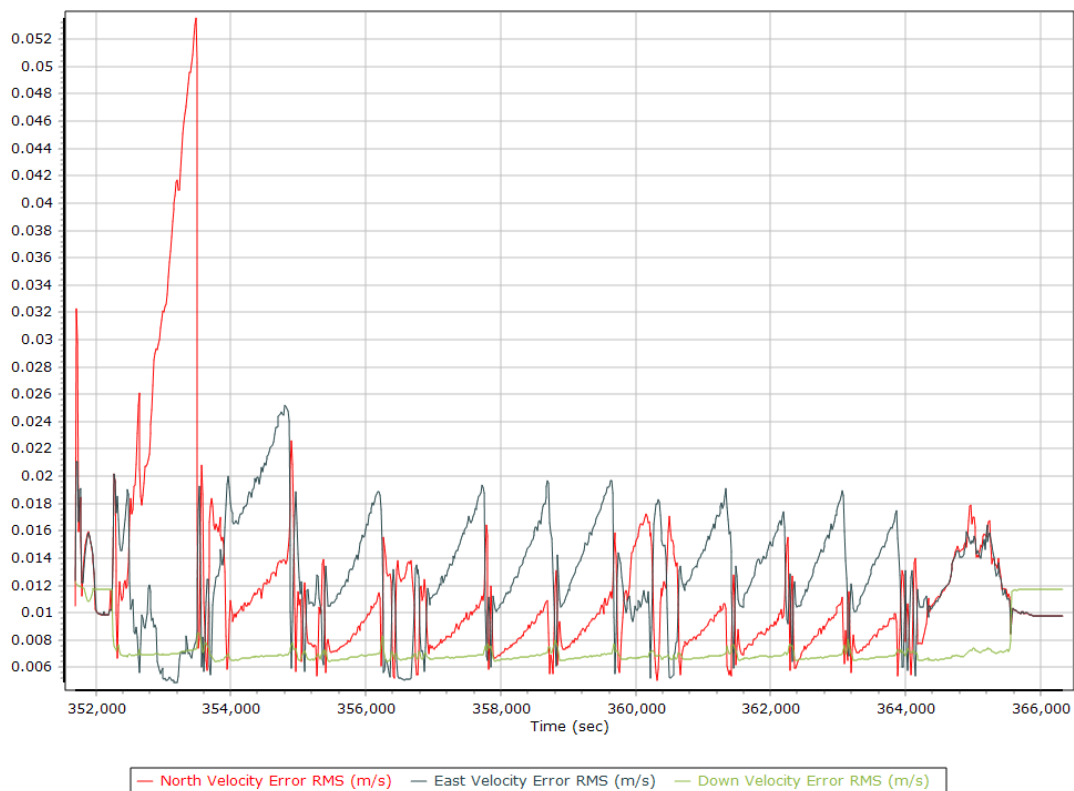


Forward Processed Performance Metrics

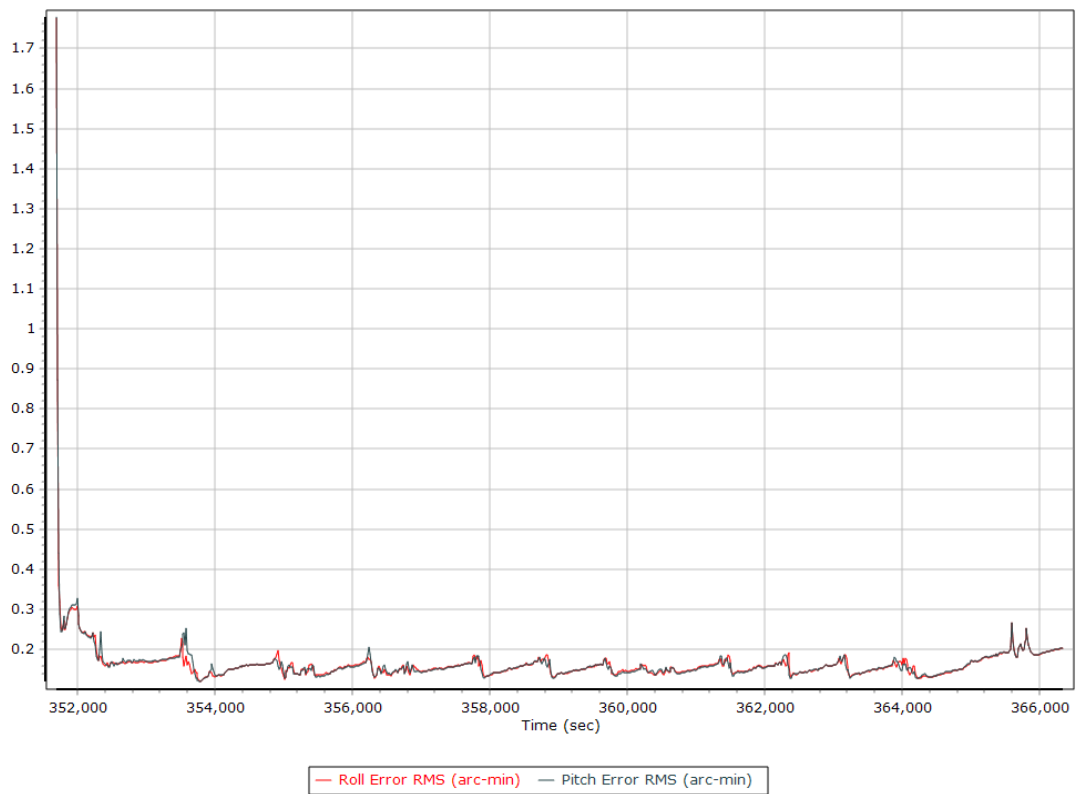
Position Error RMS (m)



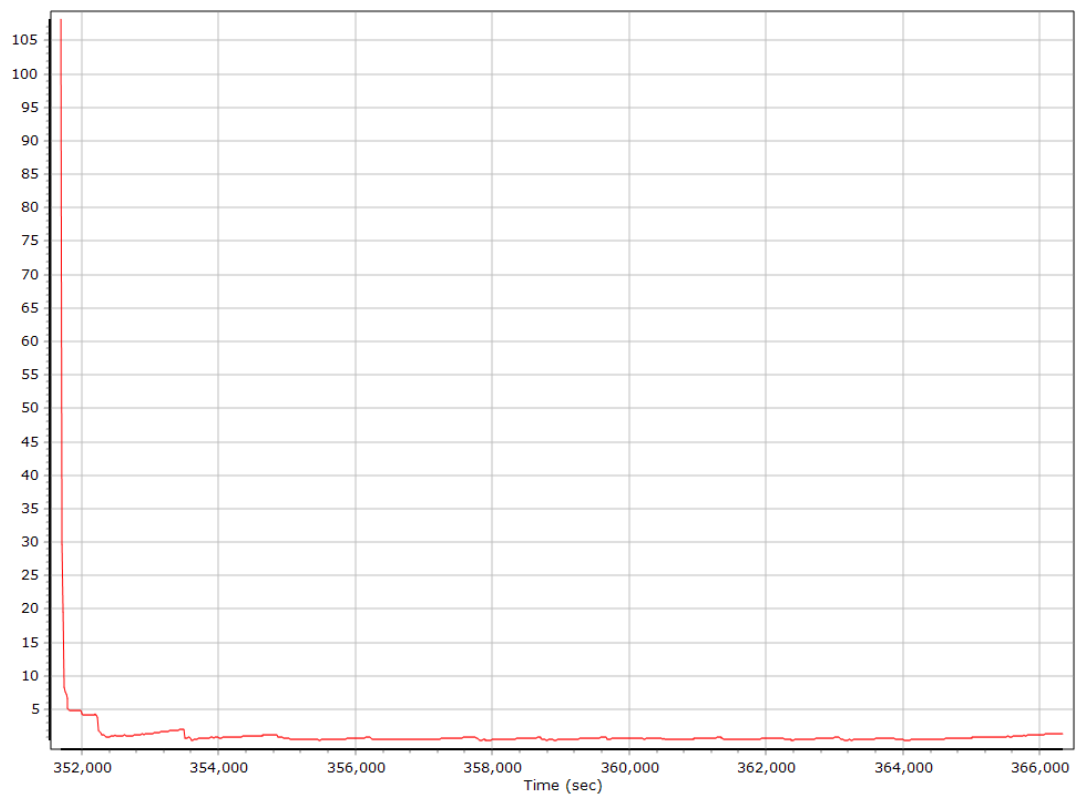
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

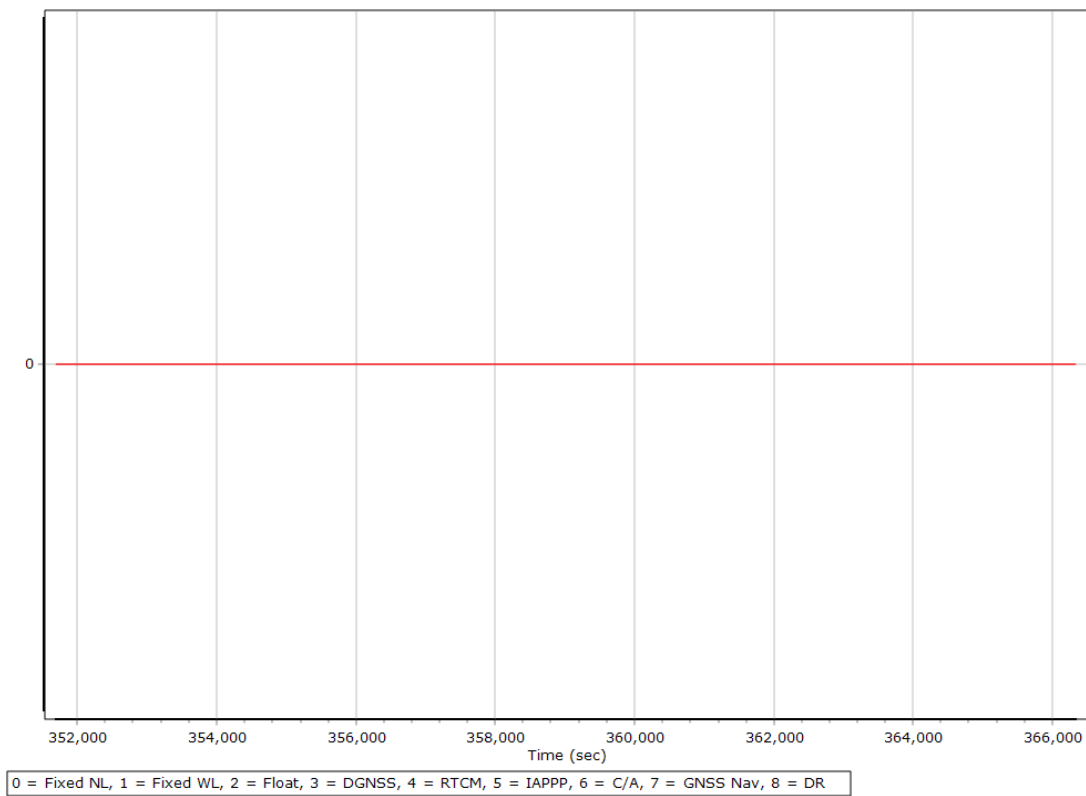


Heading Error RMS (arc-min)

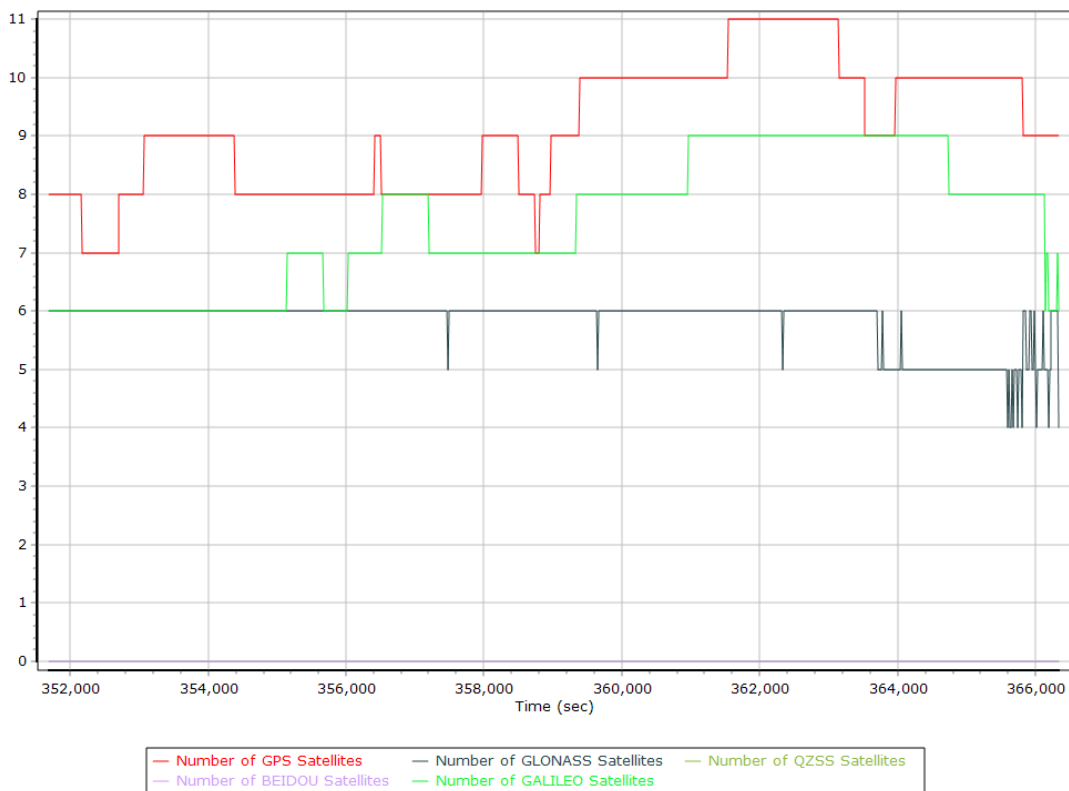


Forward Processed Solution Status

Processing Mode



Number of Satellites



Baseline Length

