

General Information

Mission Information

Project name	201110_A_5060416_nad2011_FINAL
Processing date	2020-11-17 12:32:06
Mission date	2020-11-10 02:27:43
Mission duration	01:16:22.000
Processing mode	IN-Fusion PP-RTX

Rover Hardware Information

Product	POS AV 610 VER6 HW2.5-12
Serial number	S/N9724
IMU type	57
Receiver type	BD982
Antenna type	AV39

Project File List

Rover Data Files

File name	File type
survey2.pos	POS Data

Input Files

File Name	File Type
Ephm3150.20g	GLONASS Broadcast Ephemeris
Ephm3150.20n	GPS Broadcast Ephemeris

Output Files

Filename	File type
sbet_201110_A_5060416_nad2011_FINAL.out	SBET Trajectory File

Rover Data Summary

First raw data file	survey2.pos		
Last raw data file	survey2.pos		
Start GPS week	2131		
Start time	181662.930 (11/10/2020 2:27:42 AM)		
End time	186245.831 (11/10/2020 3:44:05 AM)		
Start of fine alignment	181982.461 (11/10/2020 2:33:02 AM)		
Available subsystems	Primary GNSS, IMU		
POS Event Input	None		
Correction data	None		
IMU Installation Lever Arms & Mounting Angles			
Reference to IMU lever arm (m)	0.000	0.000	0.000
Reference to IMU mounting angles (deg)	0.000	0.000	90.000
Reference to Primary GNSS lever arm (m)	-0.526	0.128	-1.201
Reference to Primary GNSS lever arm std dev (m)	-1.000		
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

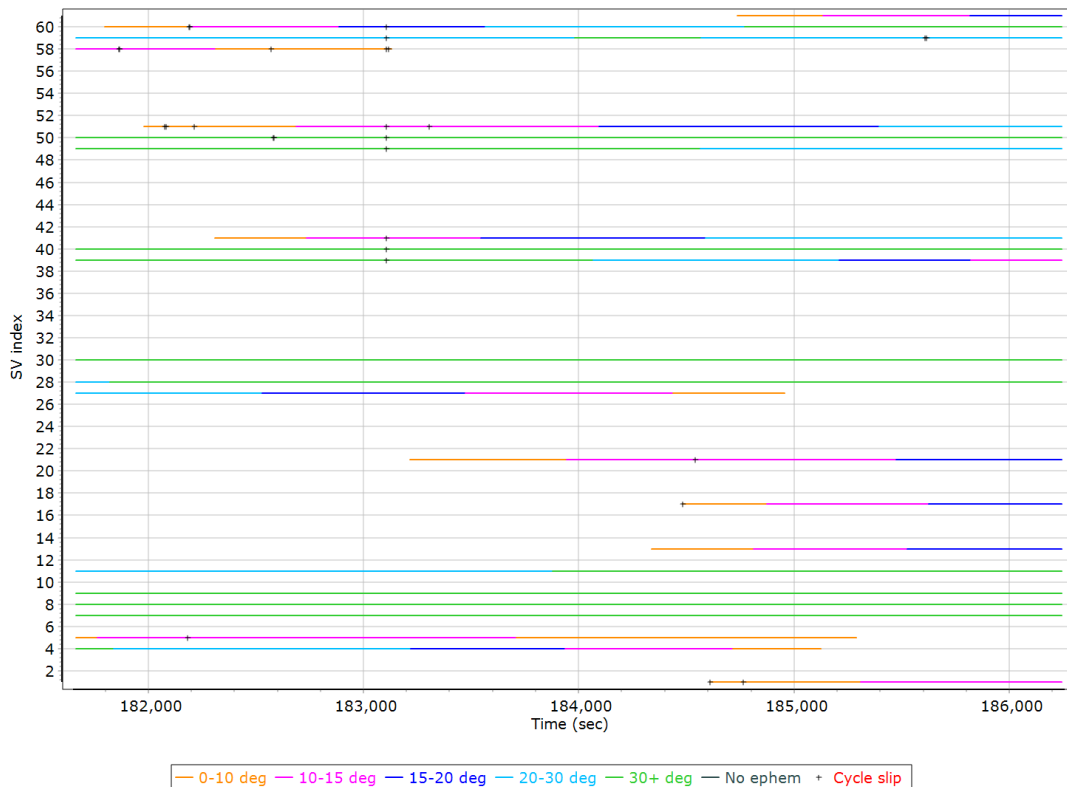
Rover Data QC

Raw IMU Import QC Summary

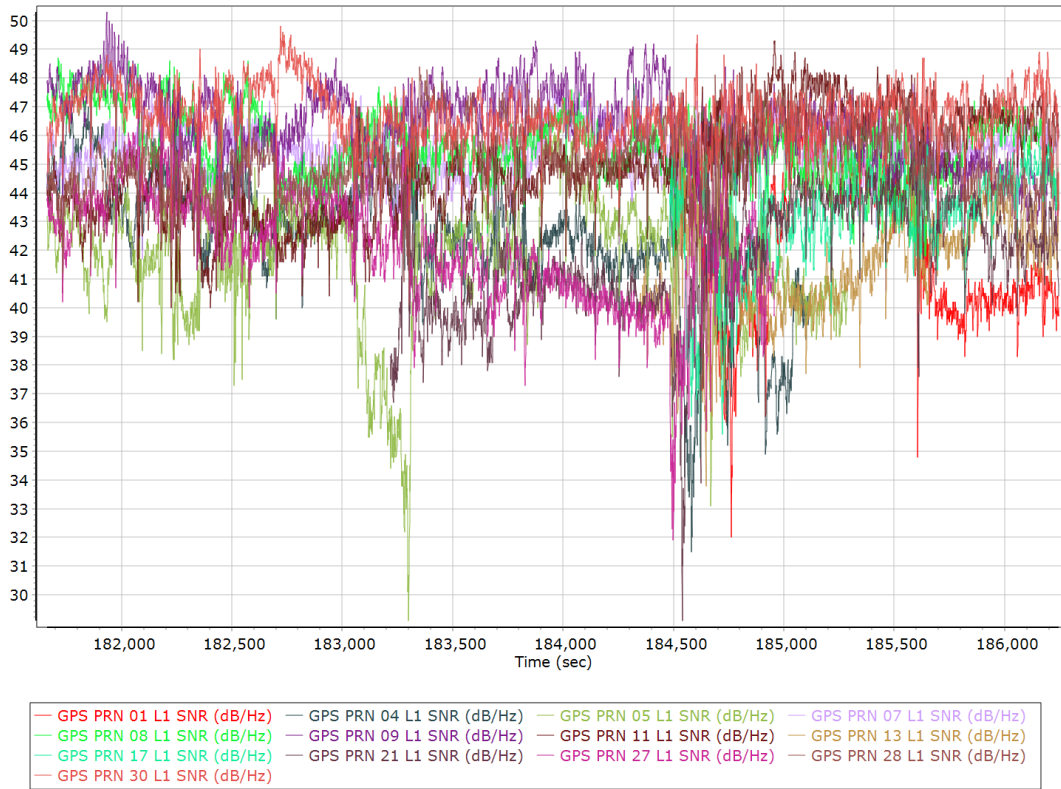
IMU data input file	imu_201110_A_5060416_nad2011_FINAL.dat
IMU data check log file	imudt_201110_A_5060416_nad2011_FINAL.log
IMU Records Processed	916458
Termination Status	Normal
IMU Anomalies	0

Primary Observables & Satellite Data

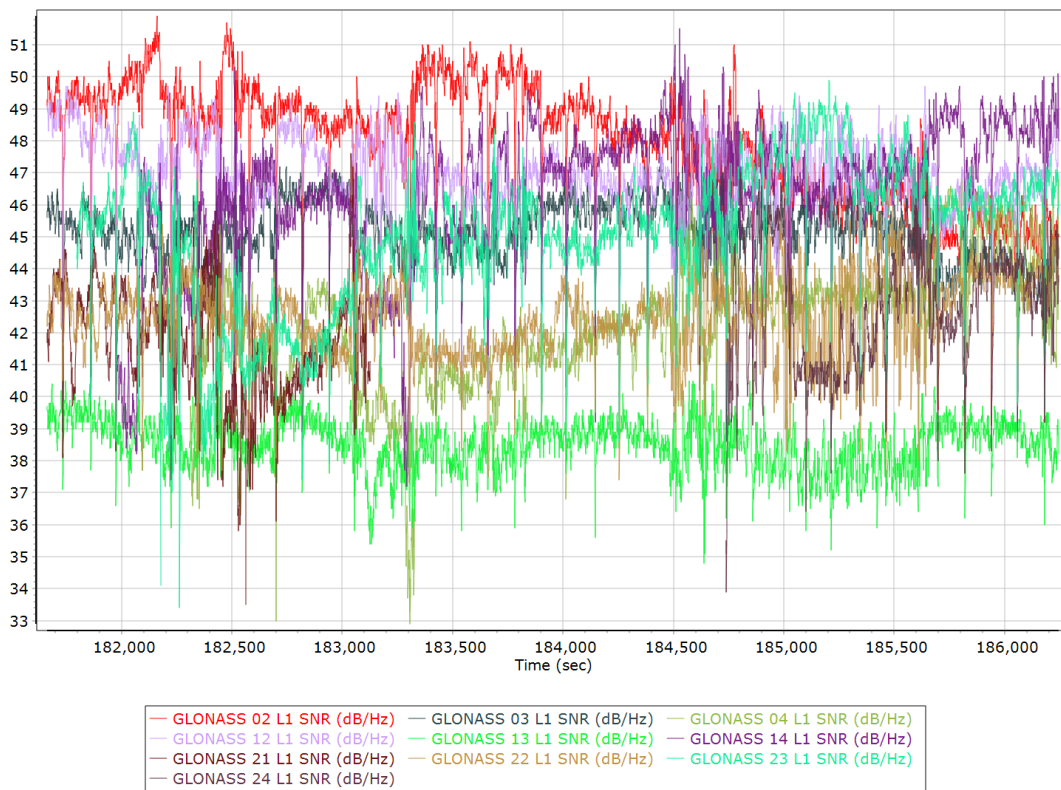
GPS/GLONASS L1 Satellite Lock/Elevation



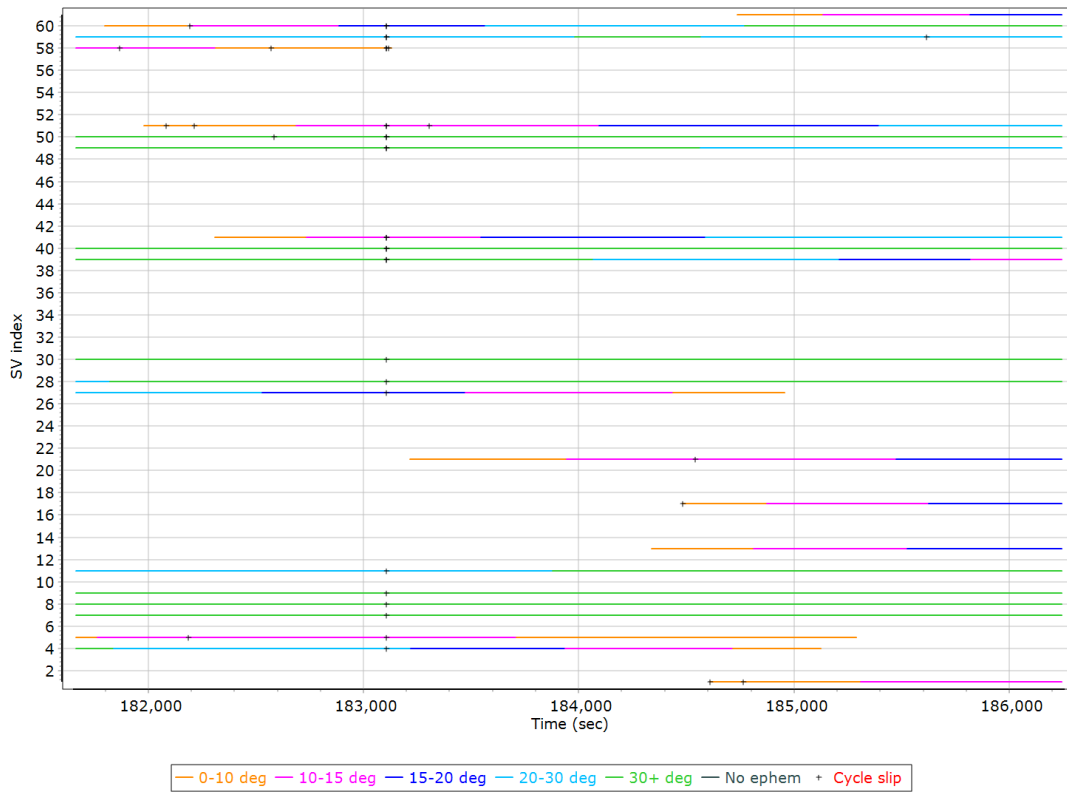
GPS L1 SNR



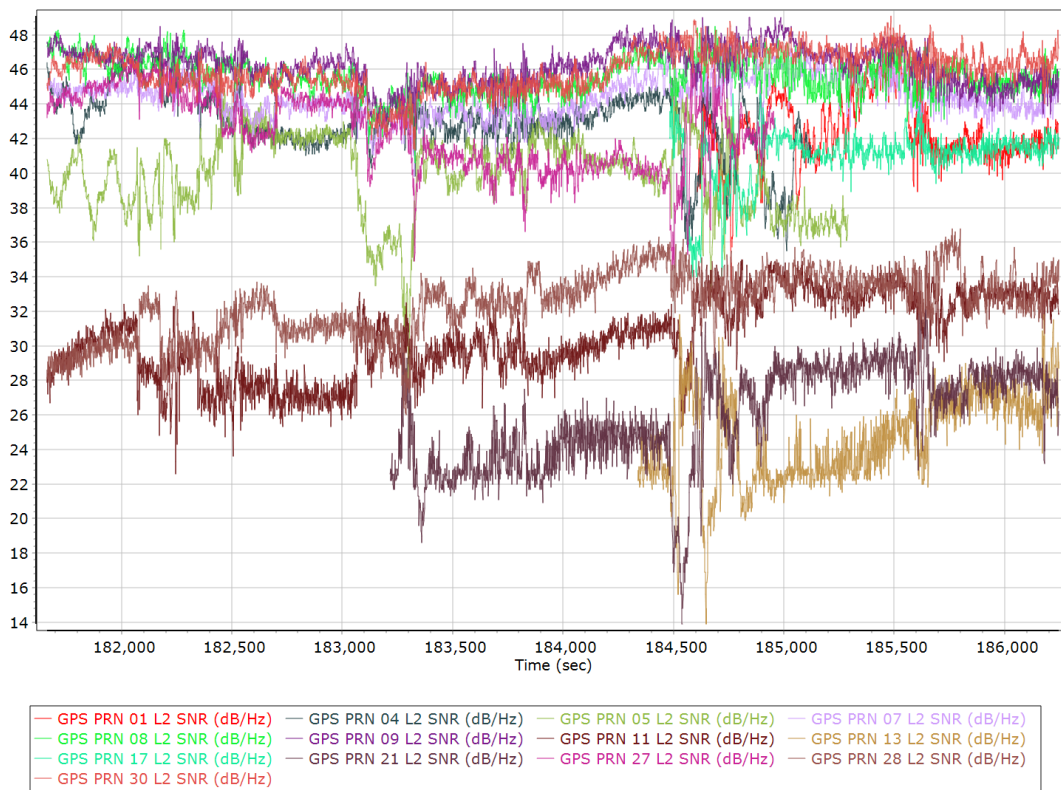
GLONASS L1 SNR



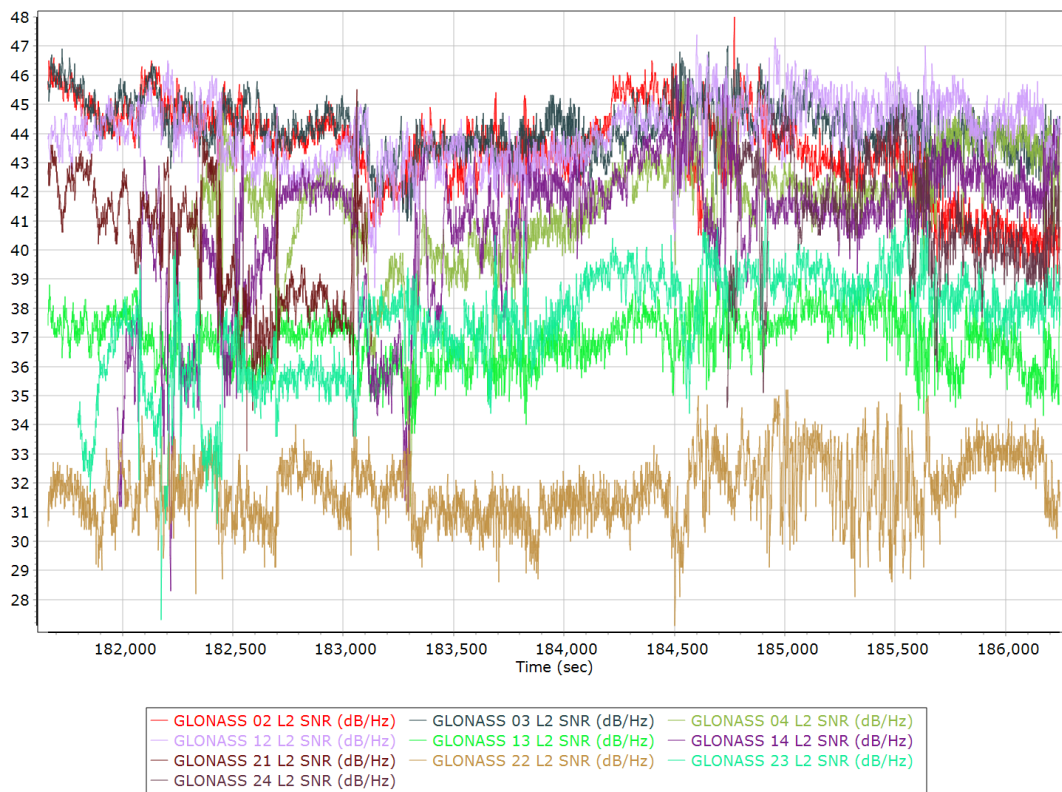
GPS/GLONASS L2 Satellite Lock/Elevation



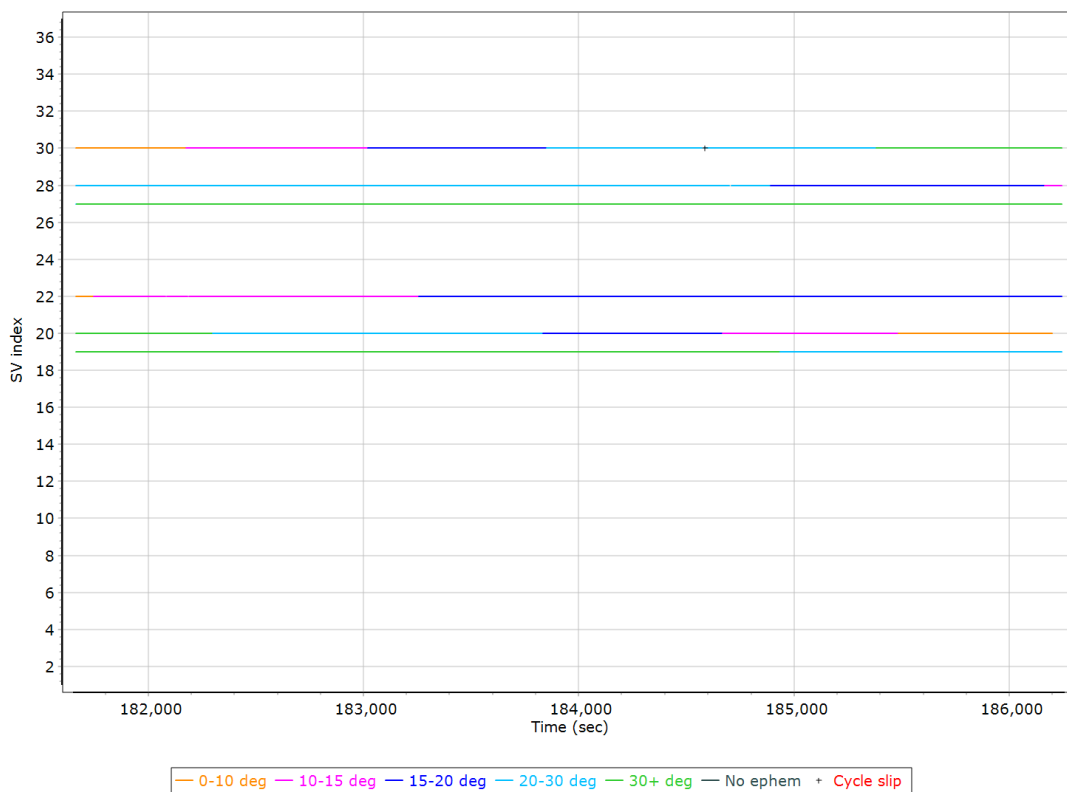
GPS L2 SNR



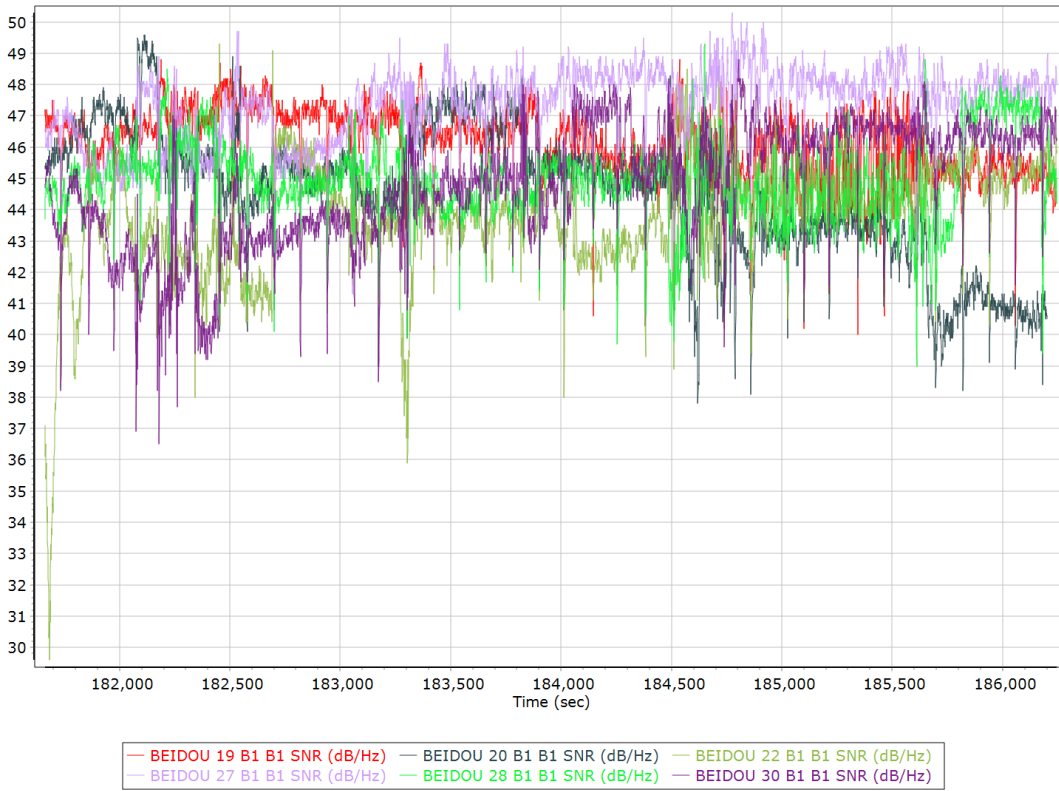
GLONASS L2 SNR



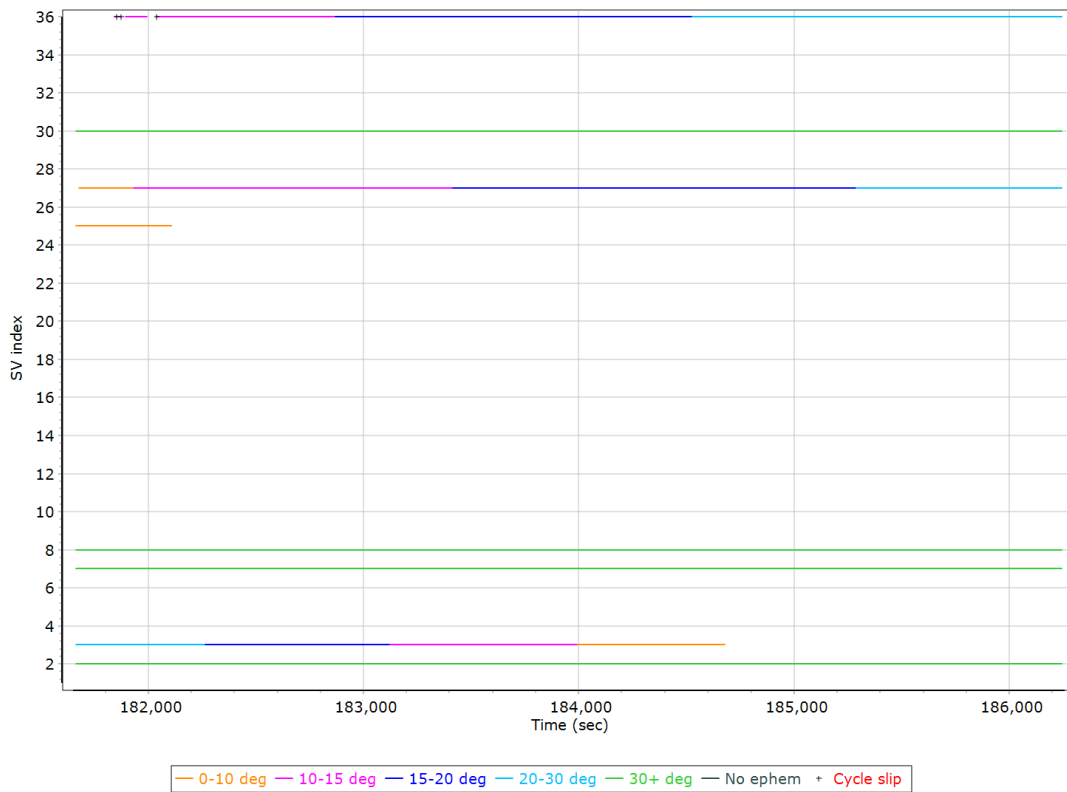
BEIDOU Satellite Lock/Elevation



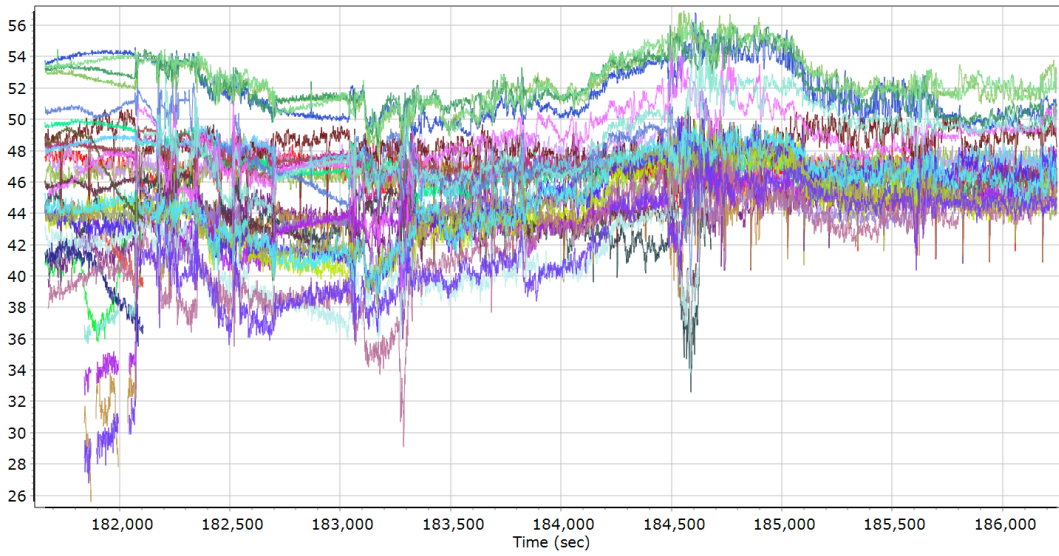
BEIDOU SNR



GALILEO Satellite Lock/Elevation



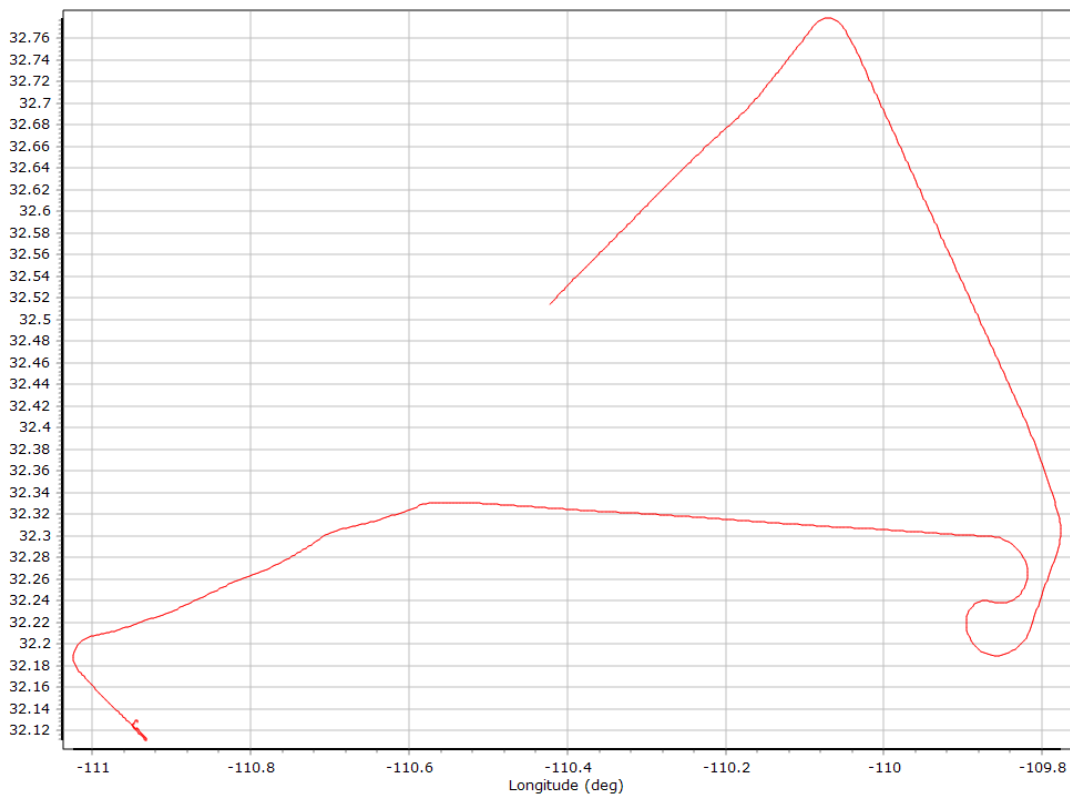
GALILEO SNR



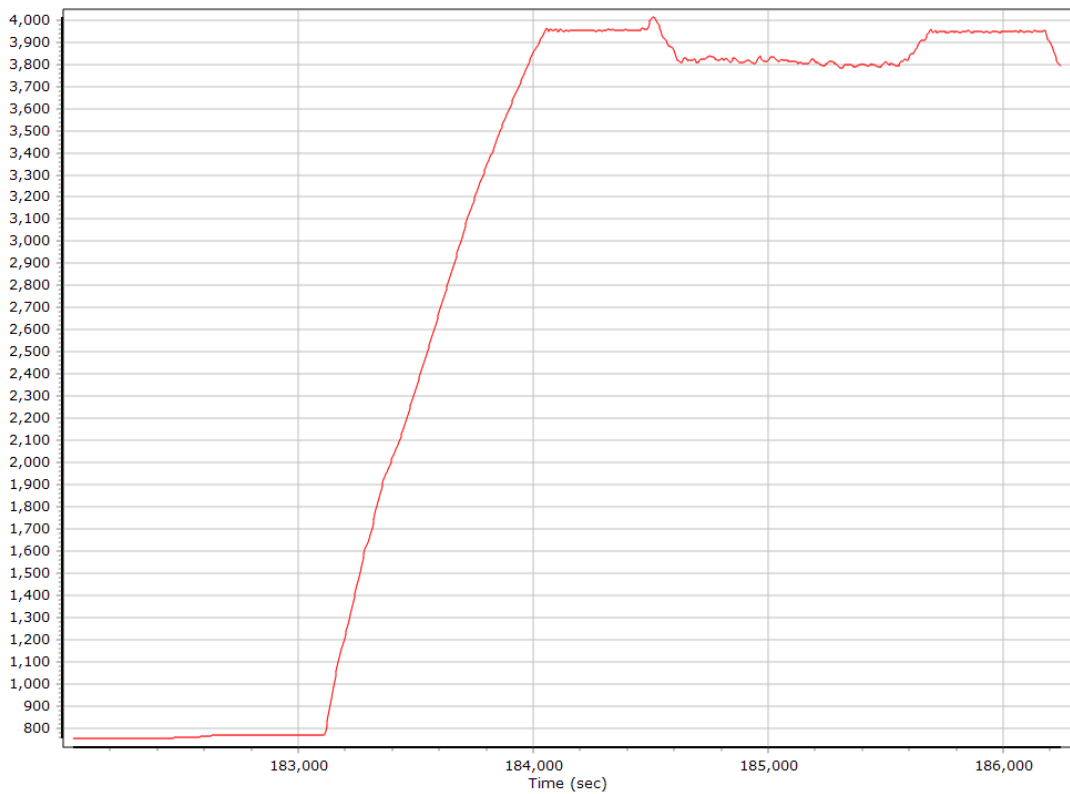
— GALILEO 02 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 03 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 07 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 08 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 25 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 27 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 30 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 36 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 02 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 03 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 07 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 08 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 25 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 27 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 30 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 36 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 02 E5B BPSK10_PD SNR (dB/Hz)	— GALILEO 03 E5B BPSK10_PD SNR (dB/Hz)
— GALILEO 07 E5B BPSK10_PD SNR (dB/Hz)	— GALILEO 08 E5B BPSK10_PD SNR (dB/Hz)

Smoothed Trajectory Information

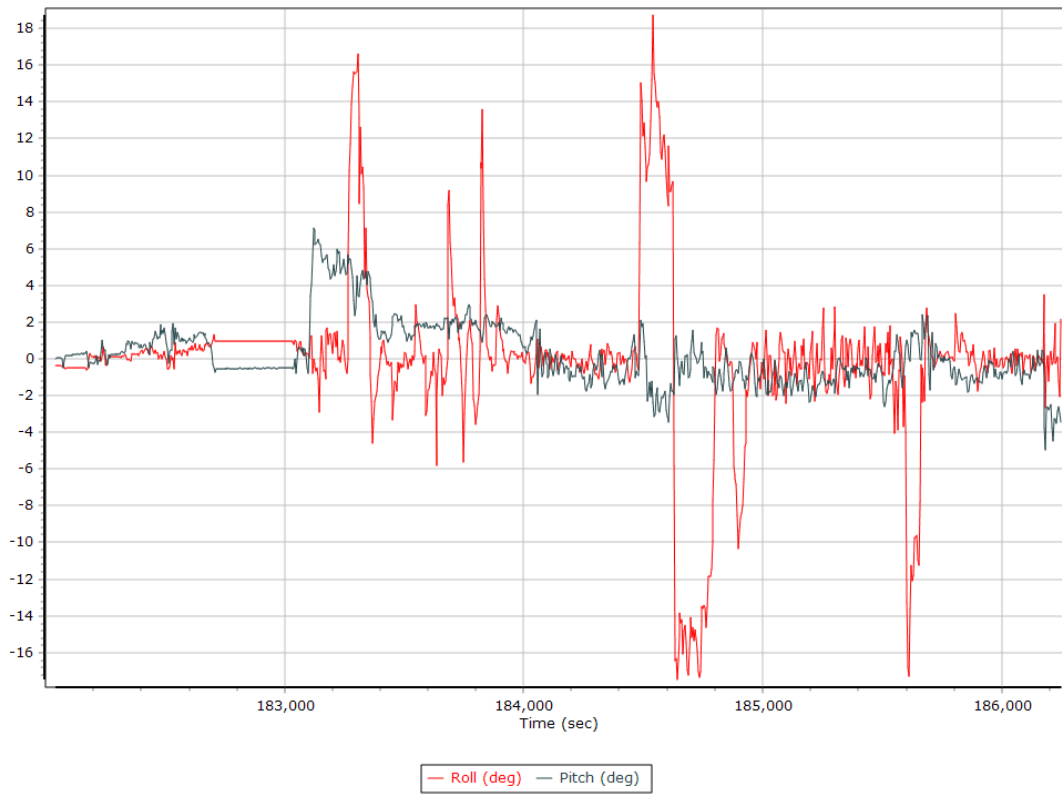
Top View



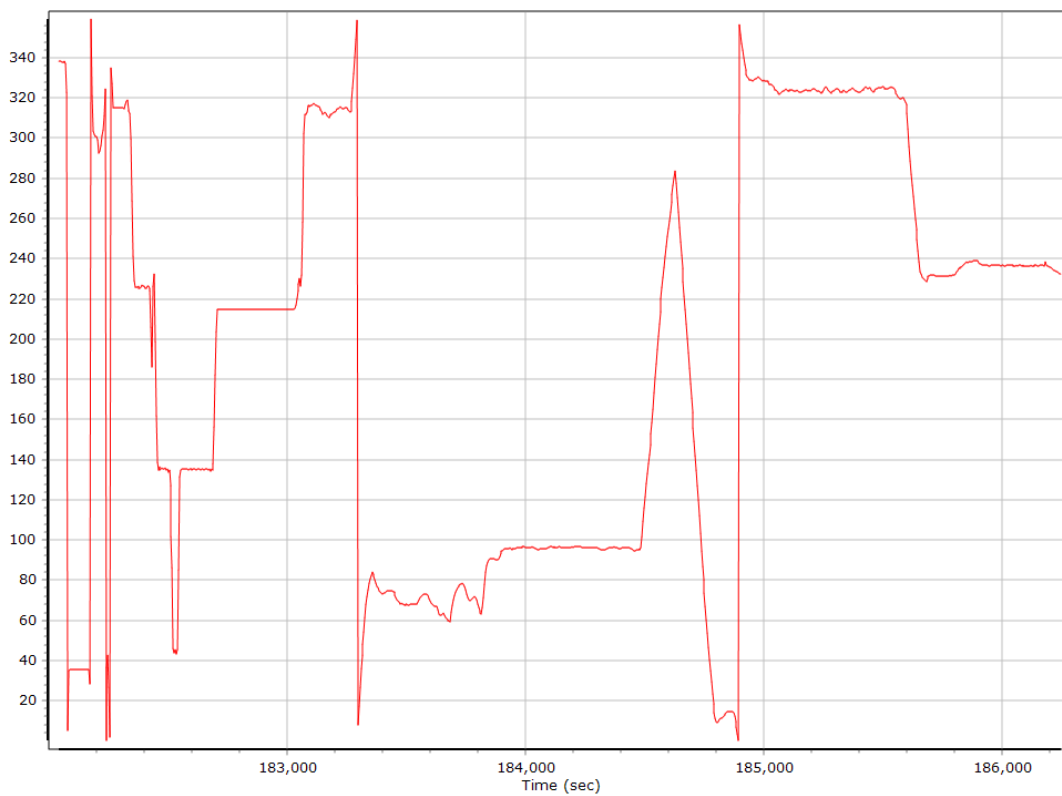
Altitude



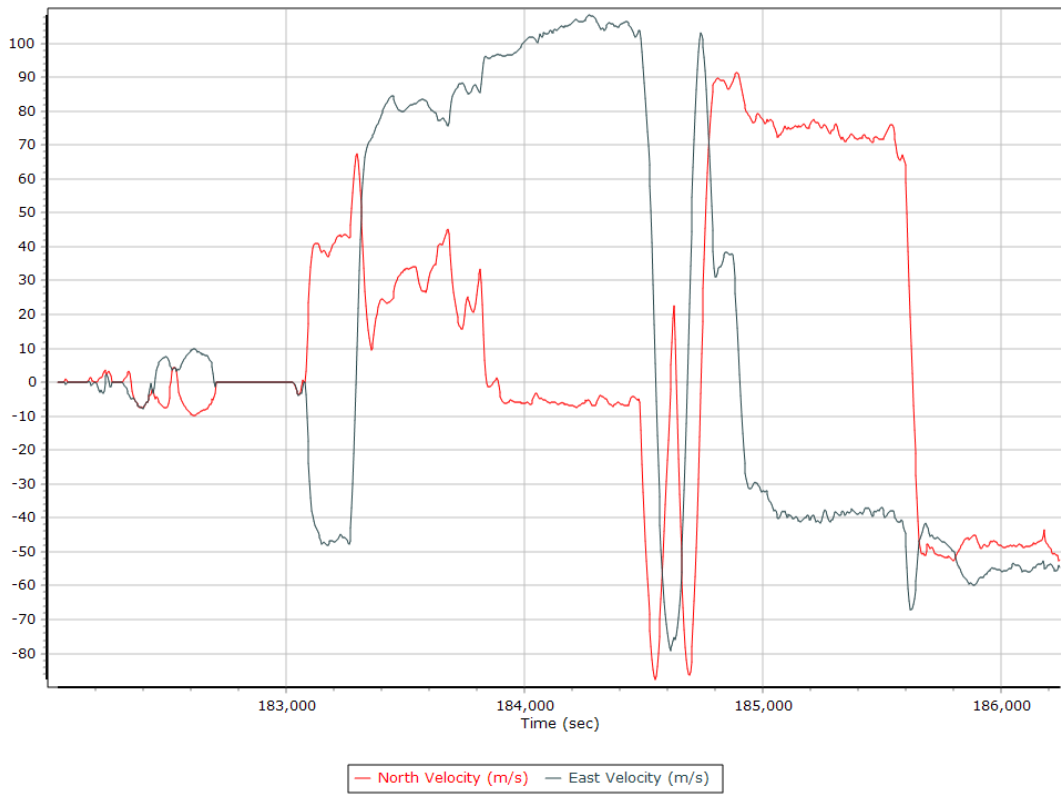
Roll/Pitch



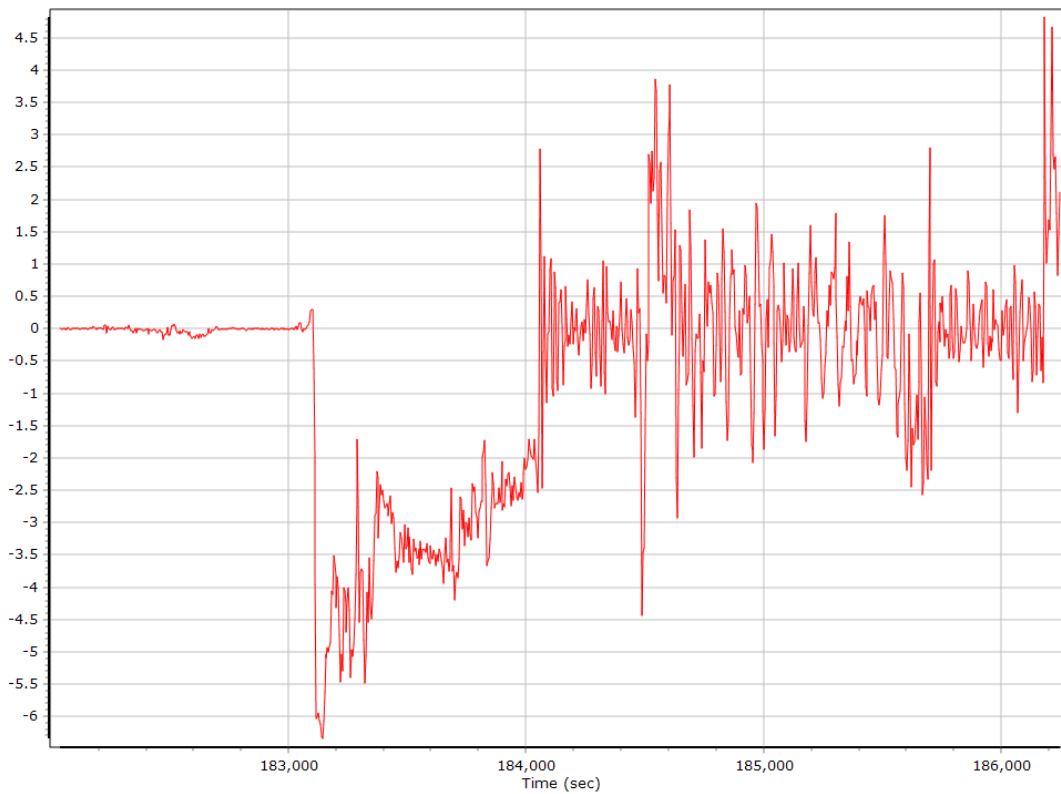
Heading



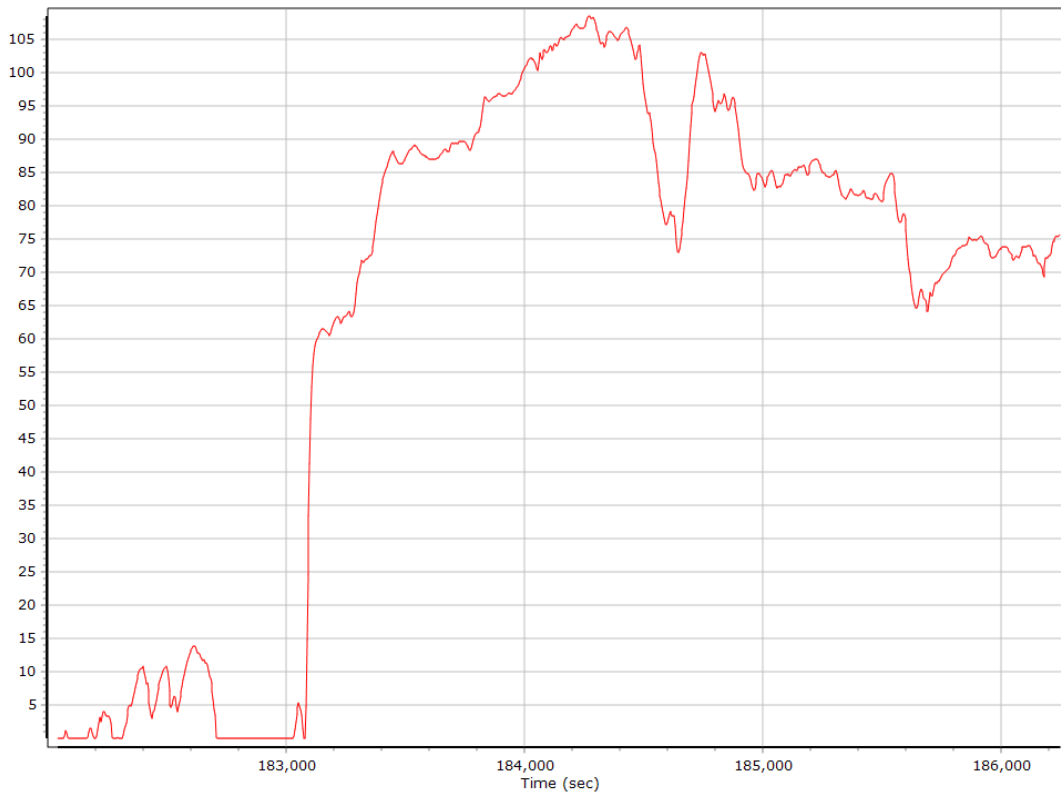
North/East Velocity



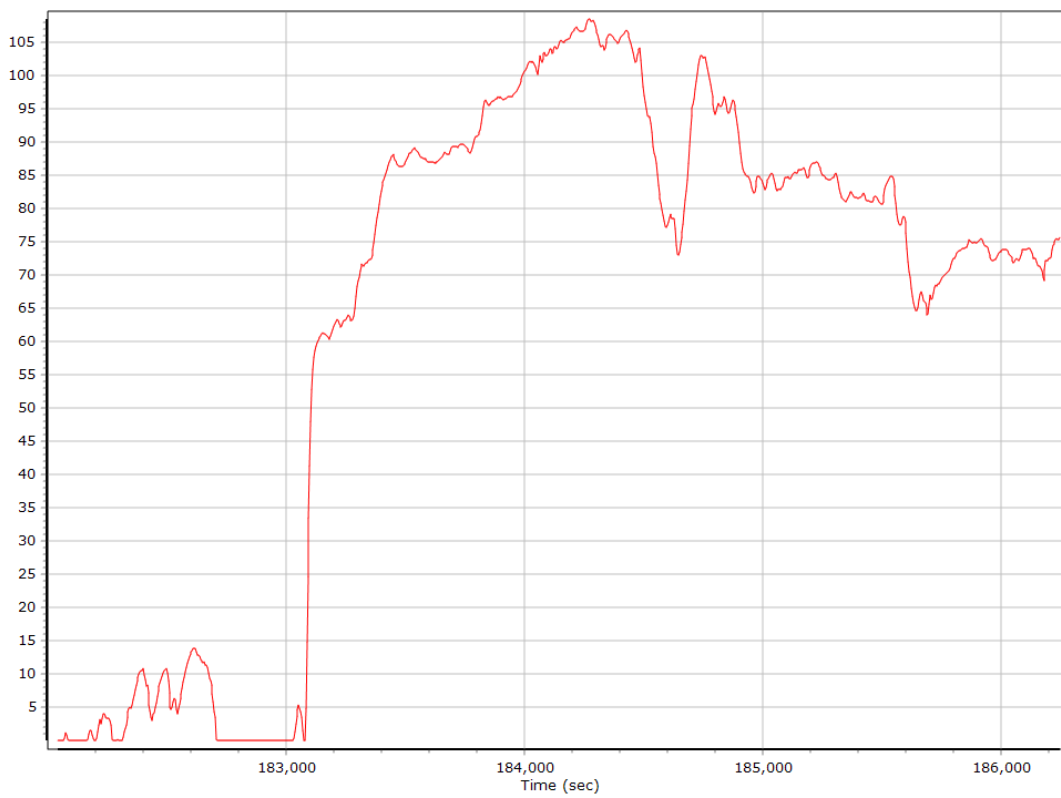
Down Velocity



Total Speed



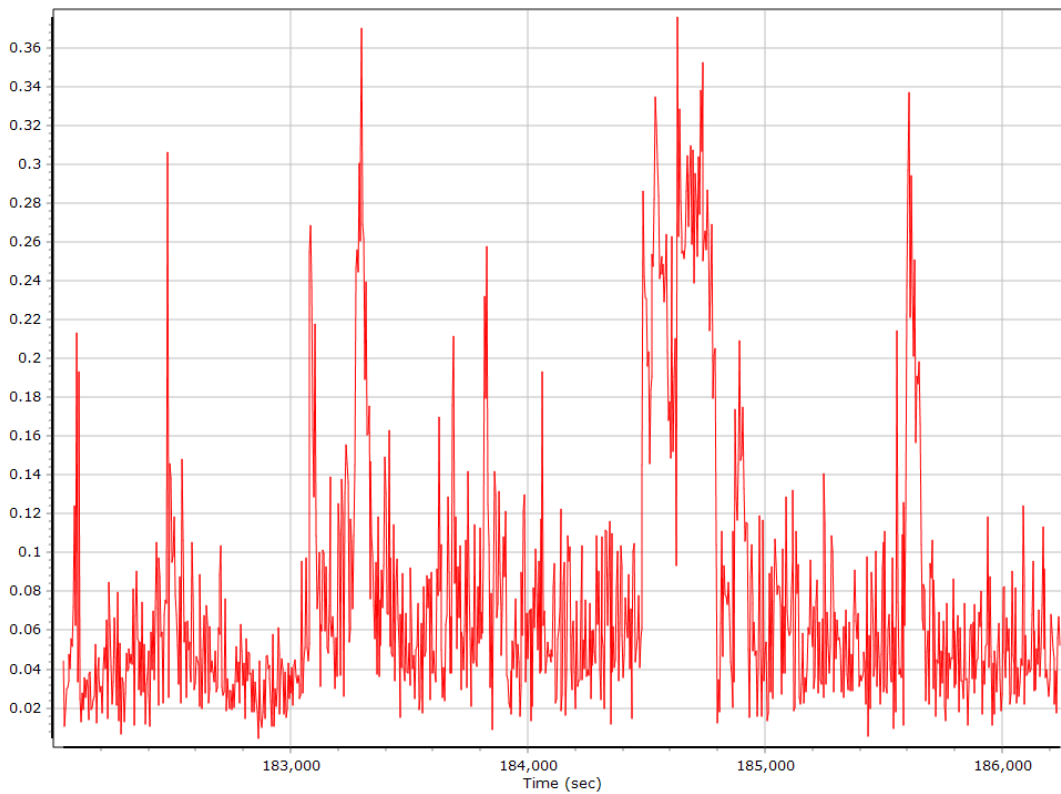
Ground Speed



Body Acceleration



Total Body Acceleration

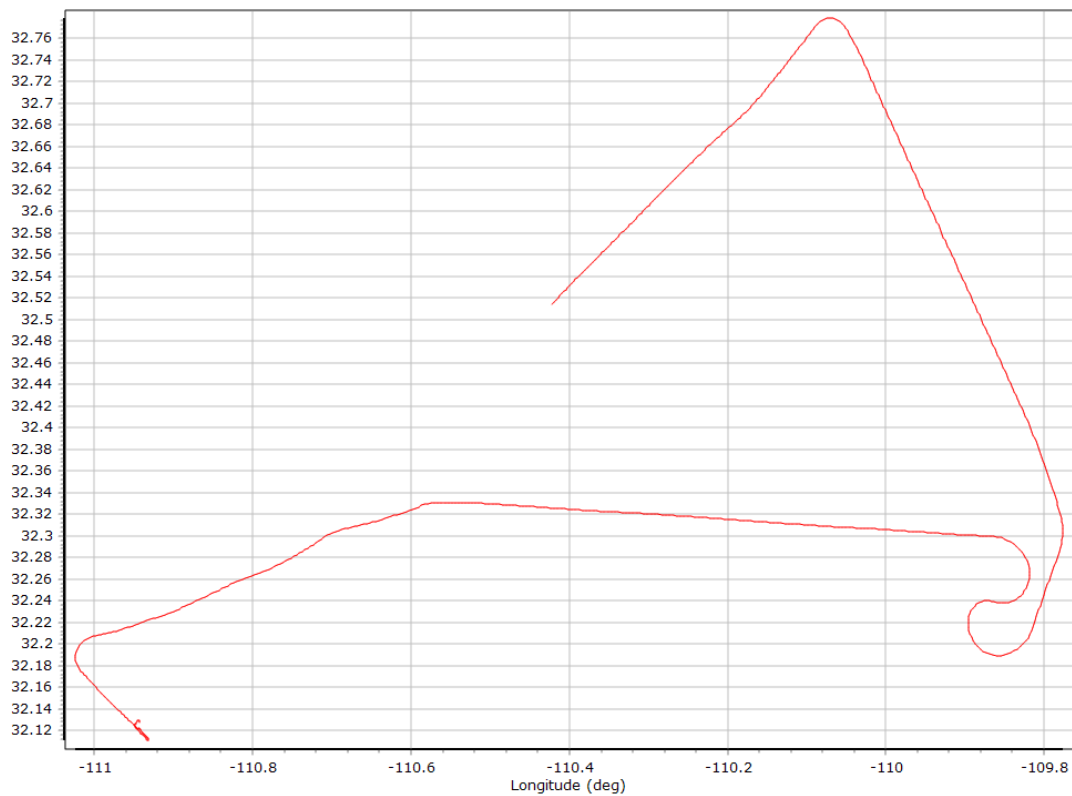


Body Angular Rate

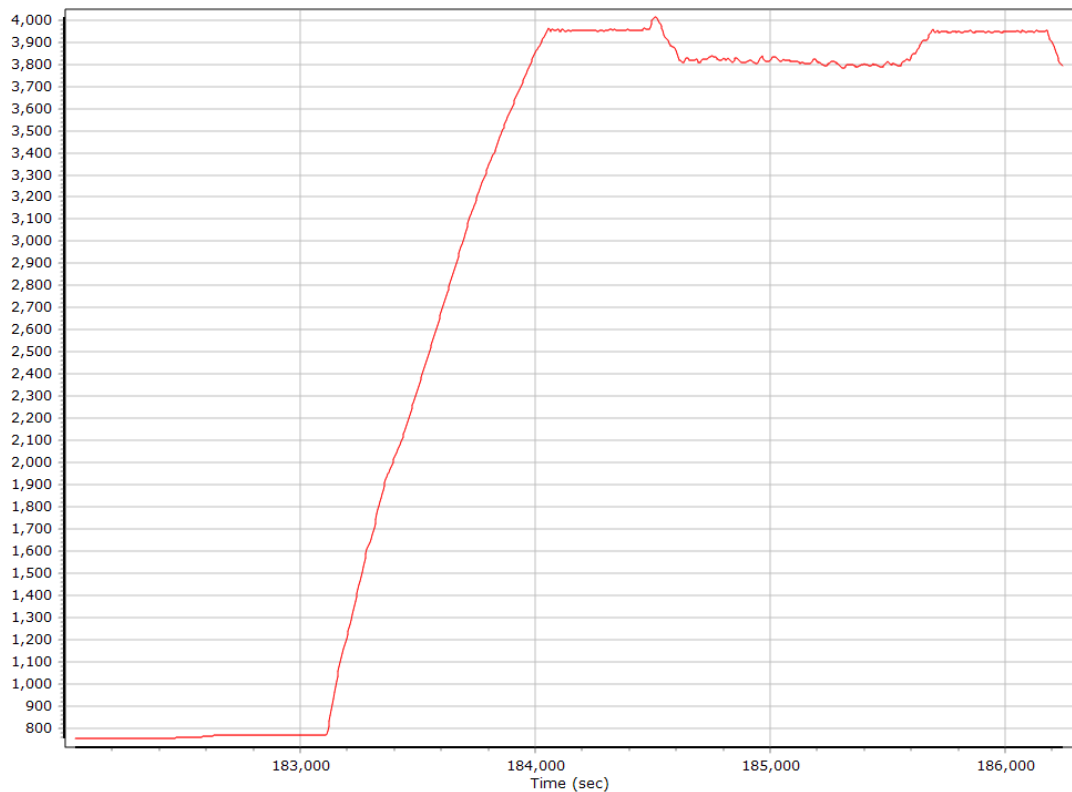


Forward Processed Trajectory Information

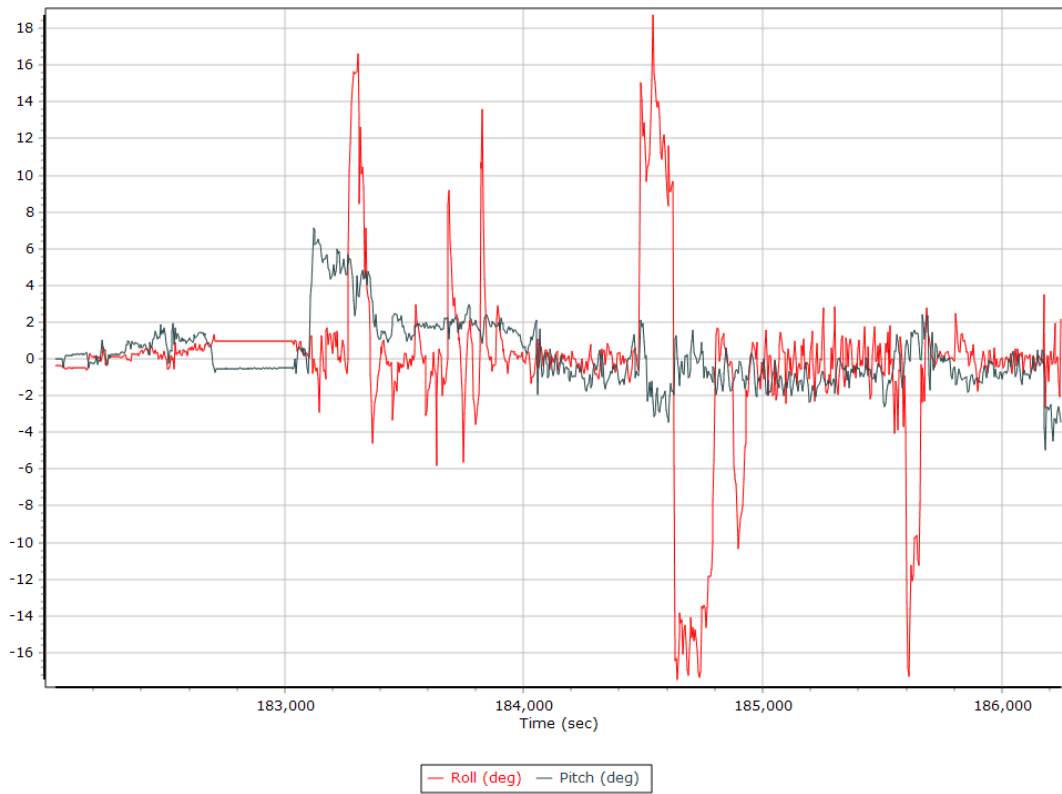
Top View



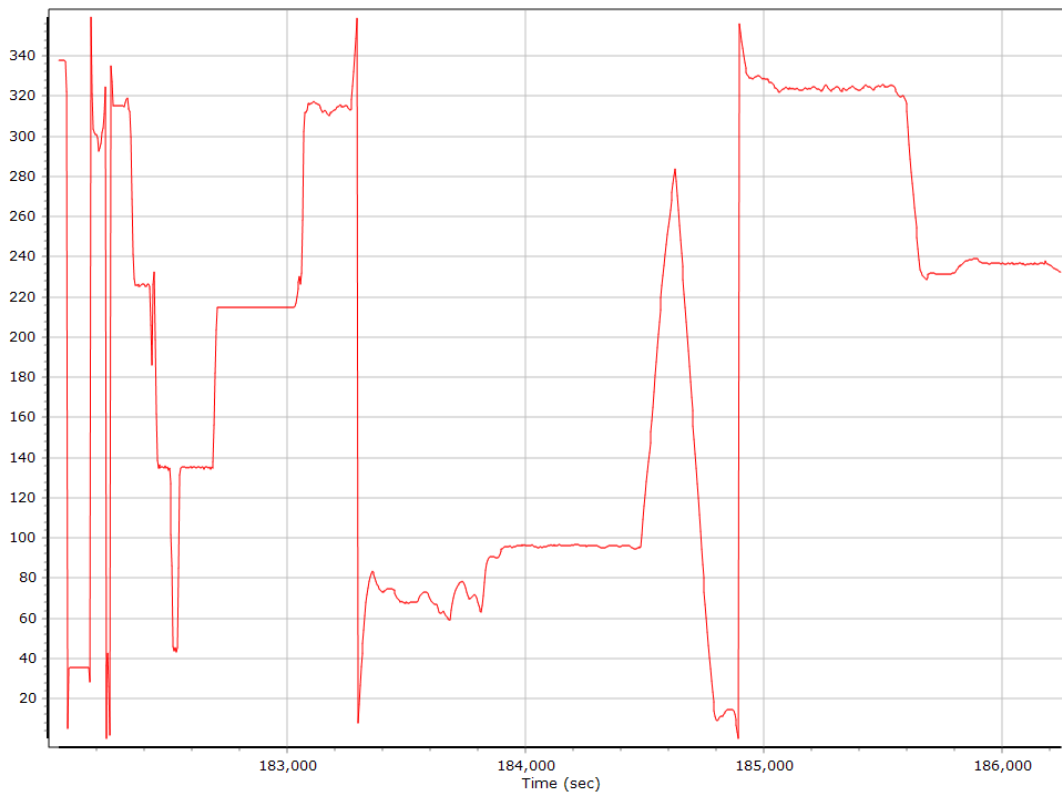
Altitude



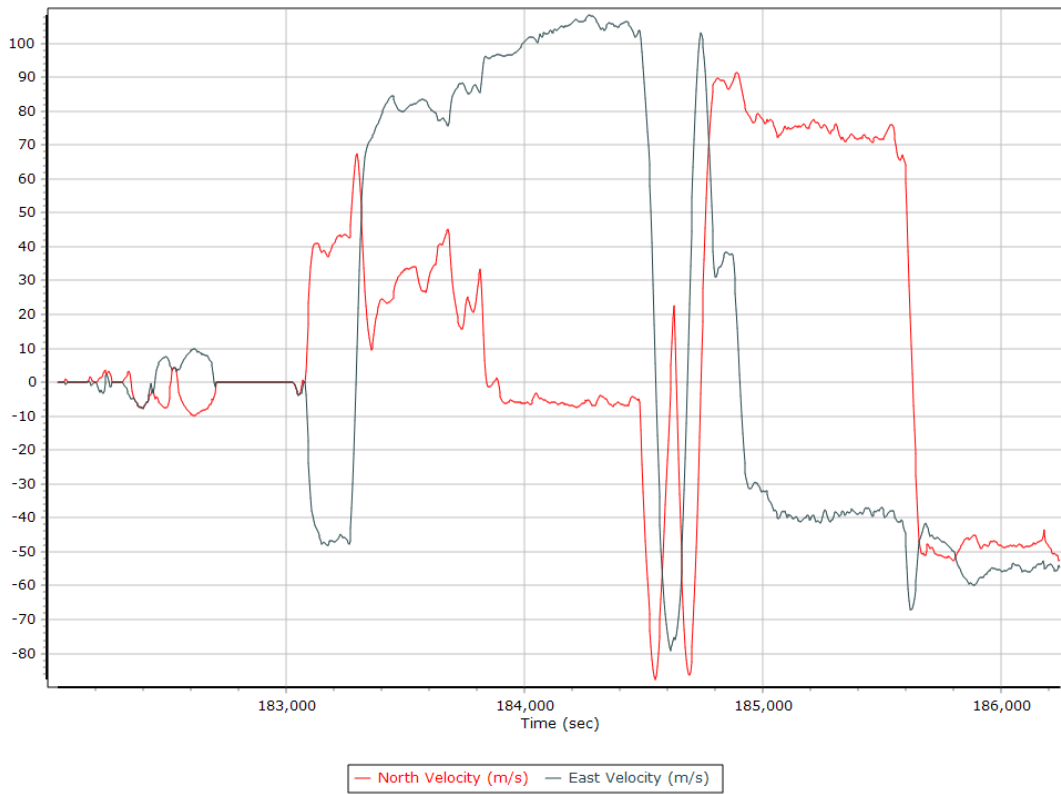
Roll/Pitch



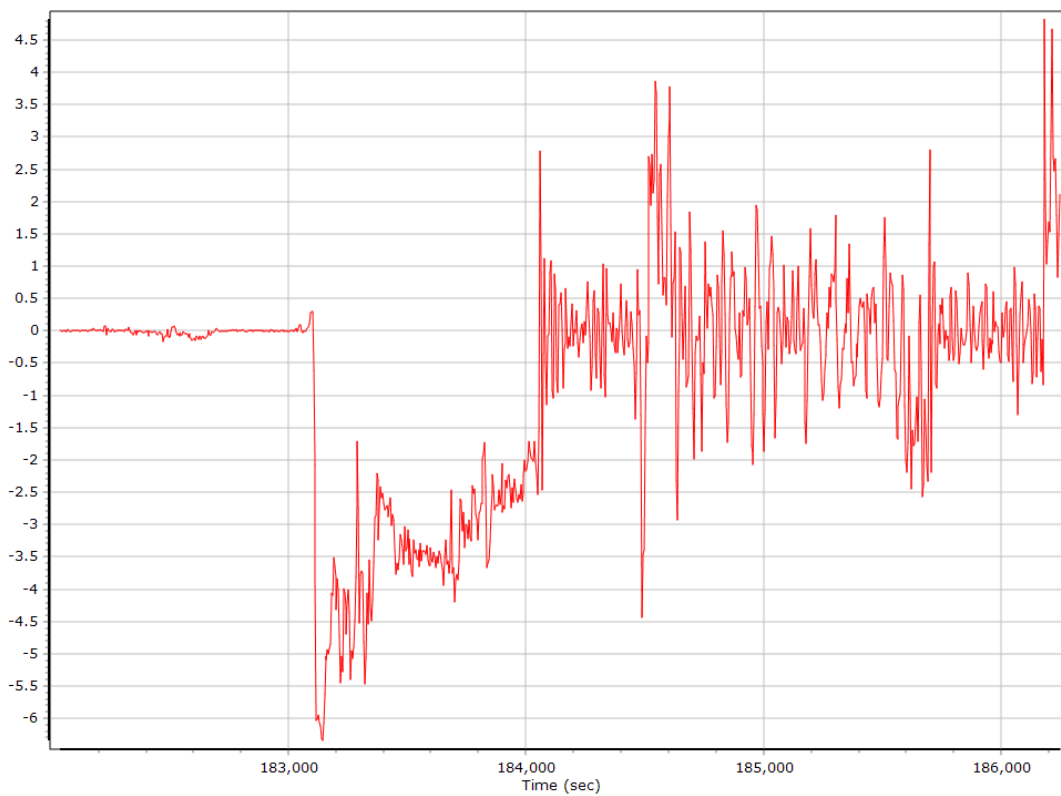
Heading



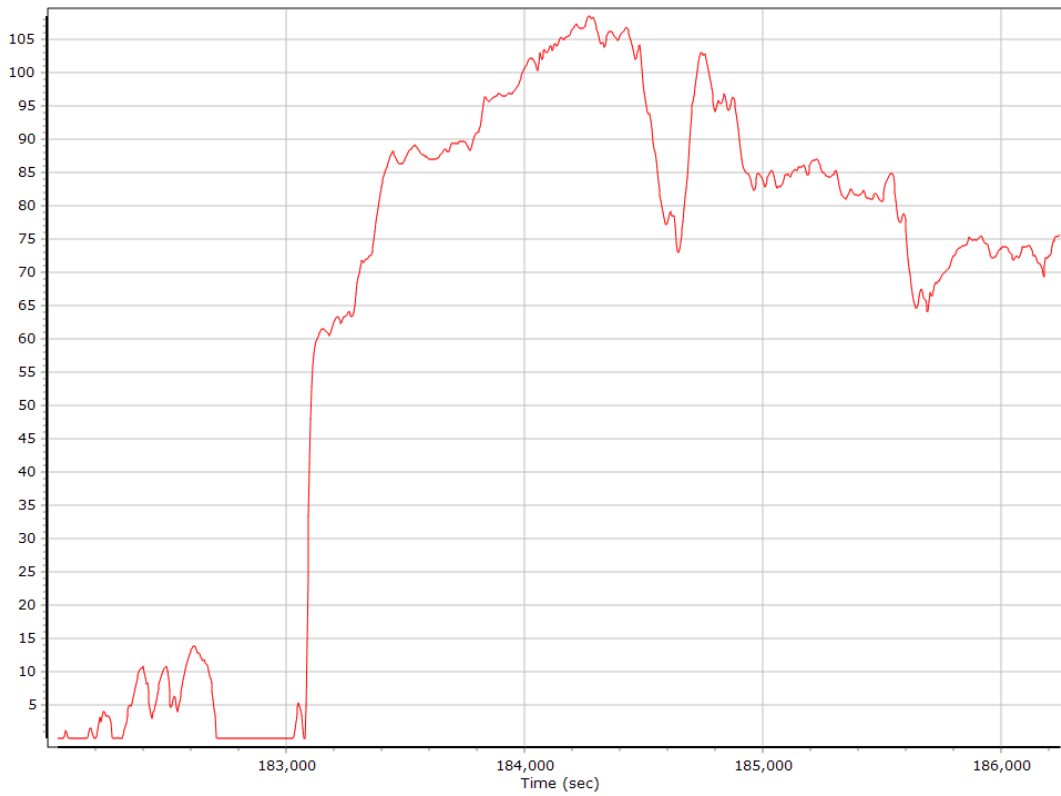
North/East Velocity



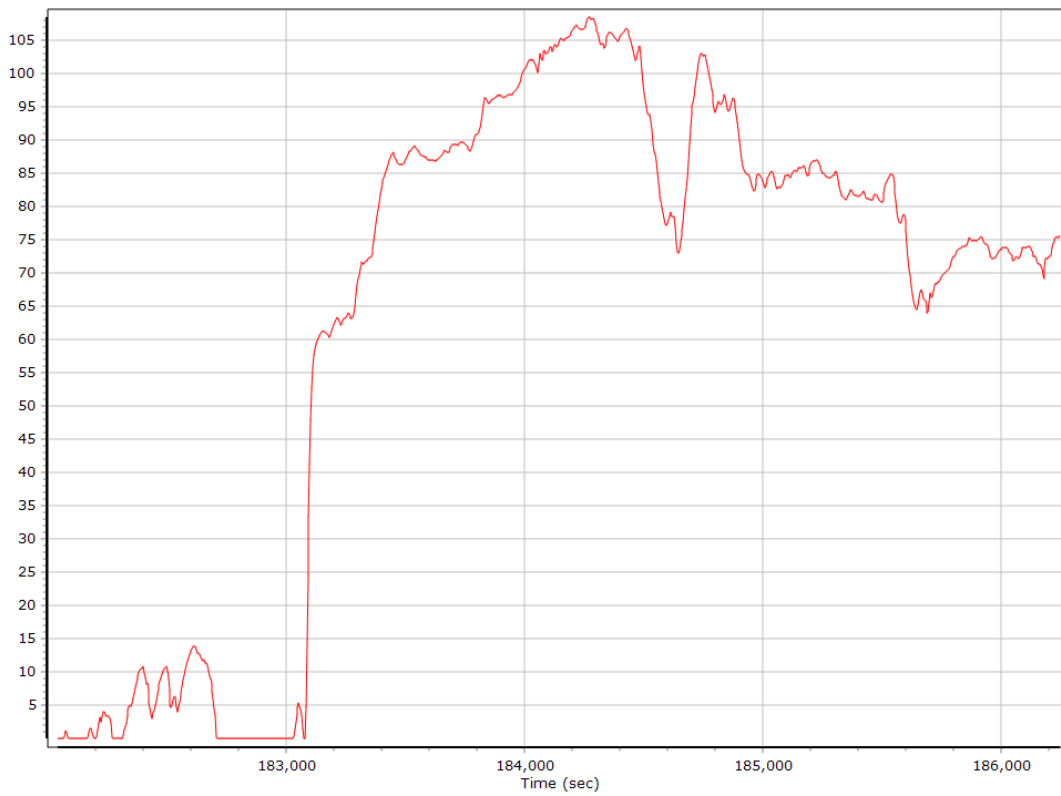
Down Velocity



Total Speed



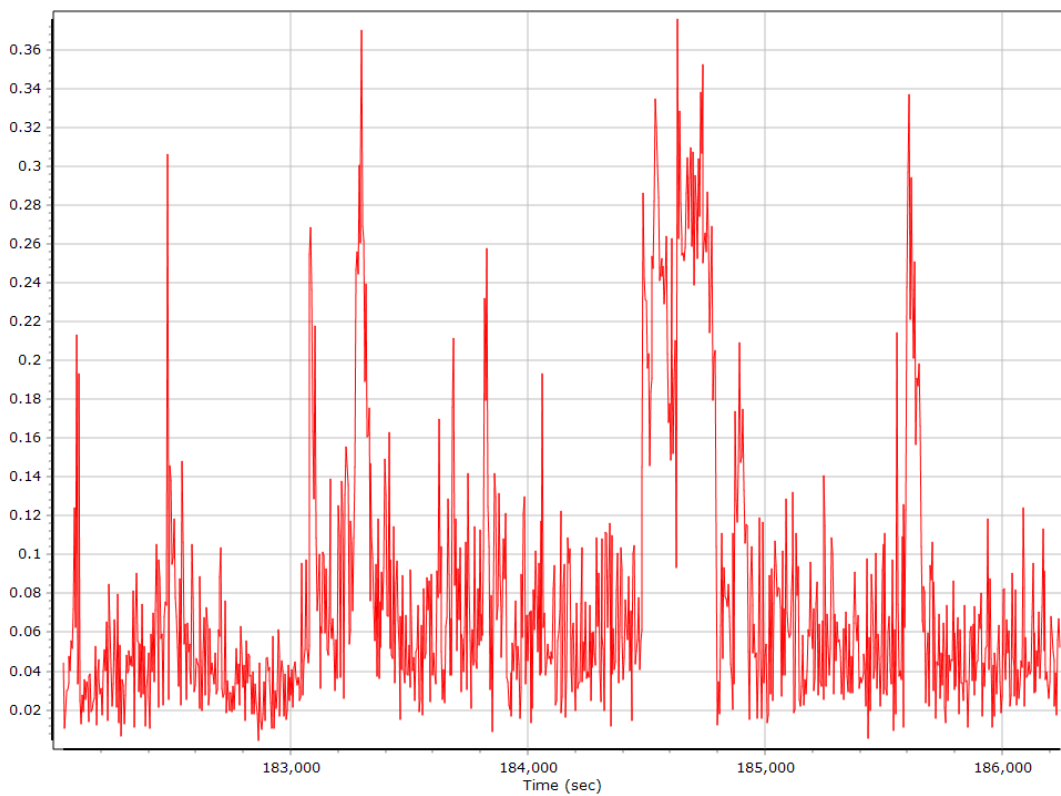
Ground Speed



Body Acceleration



Total Body Acceleration



Body Angular Rate

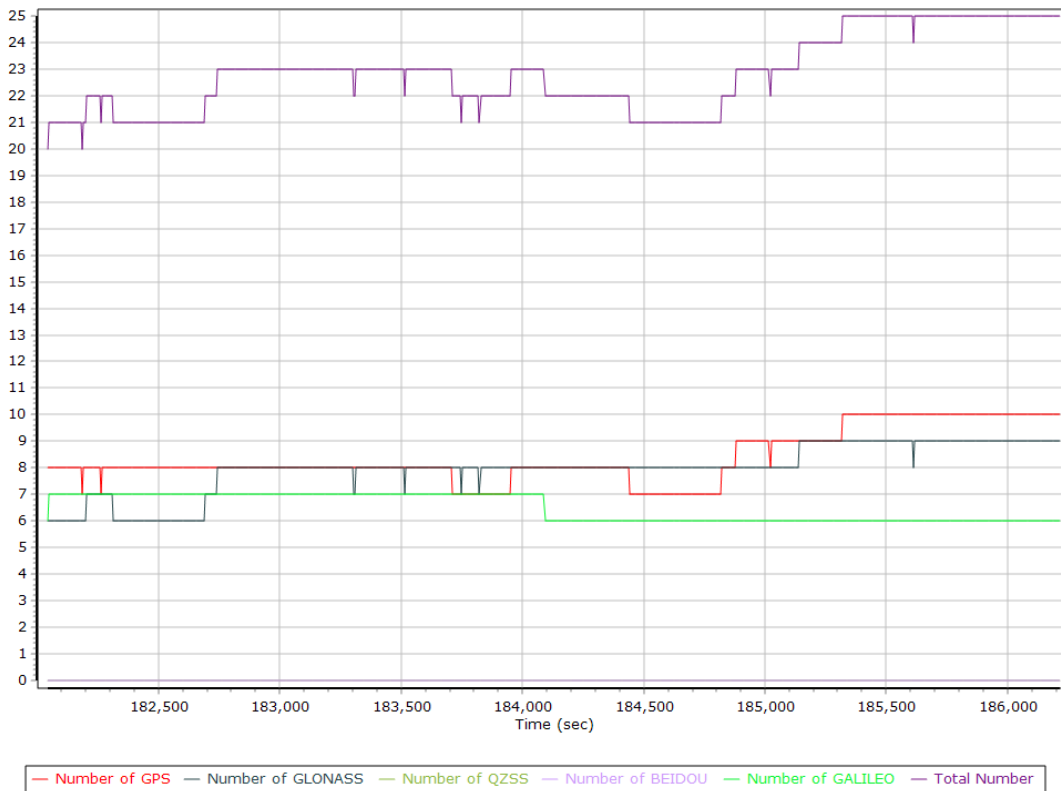


GNSS QC

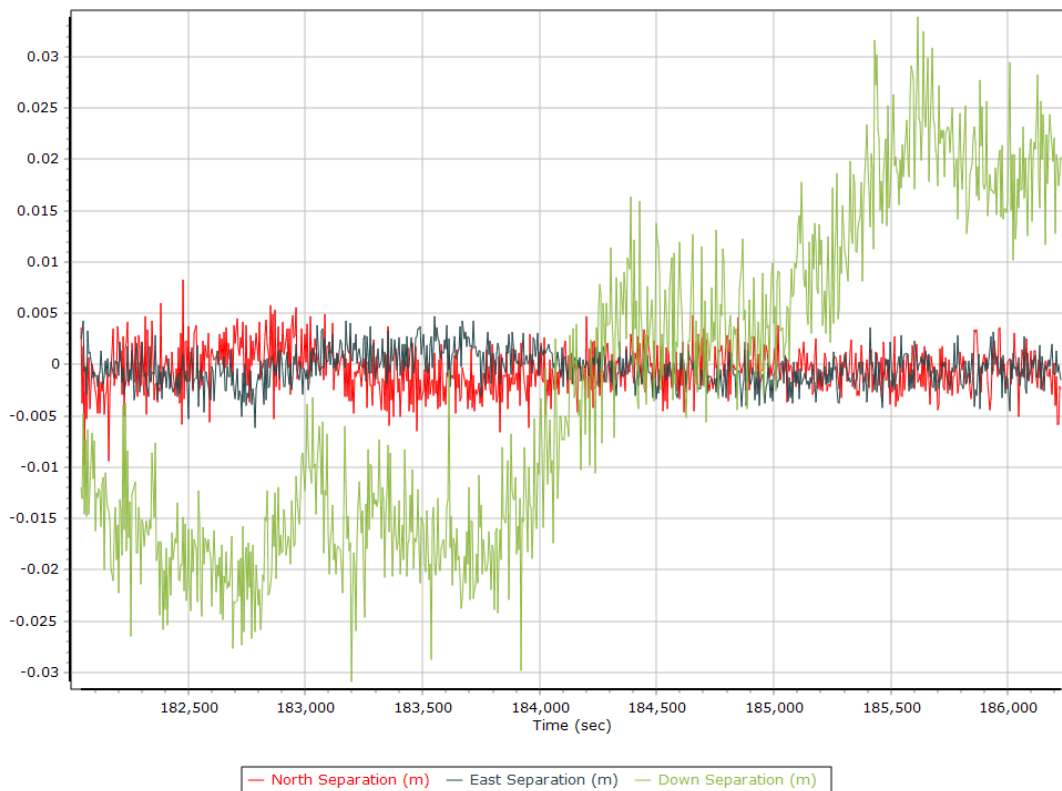
GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	6	10	8
Number of GLONASS SV	0	9	8
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	0	0
Number of GALILEO SV	5	7	6
Total number of SV	15	25	23
PDOP	1.01	1.53	1.15
QC Solution Gaps	1.00	1.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	4546.00	0.00	3.00
Percentage	99.93	0.00	0.07

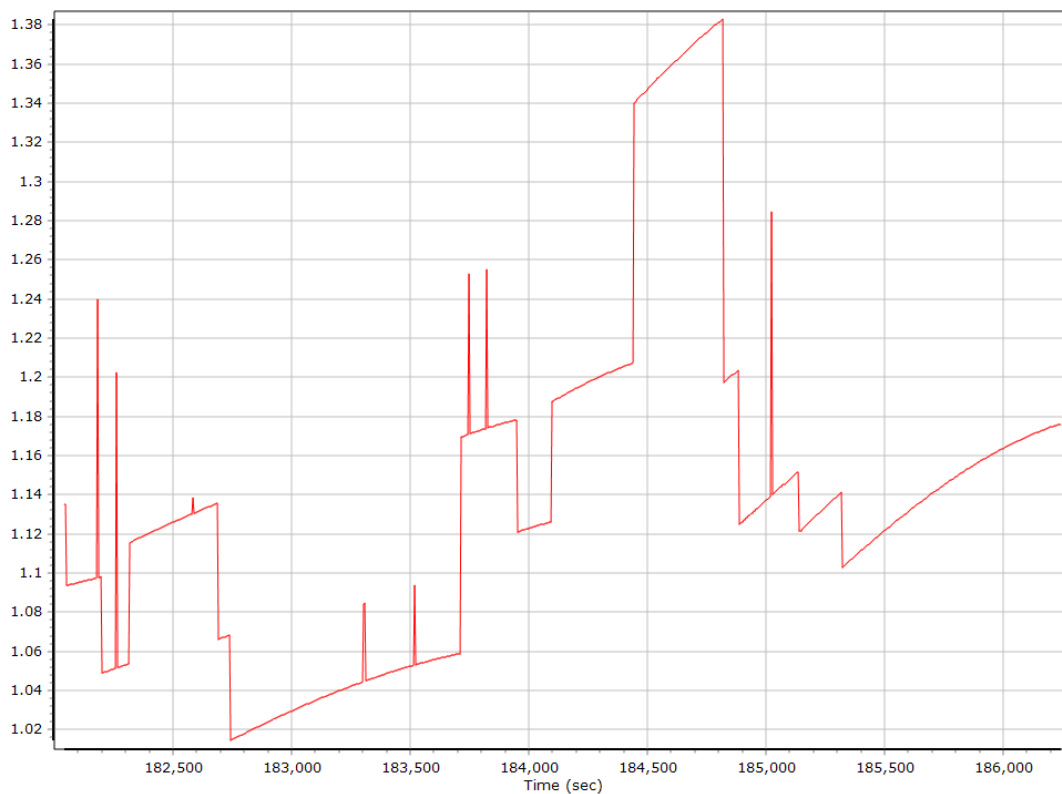
Num SVs in solution



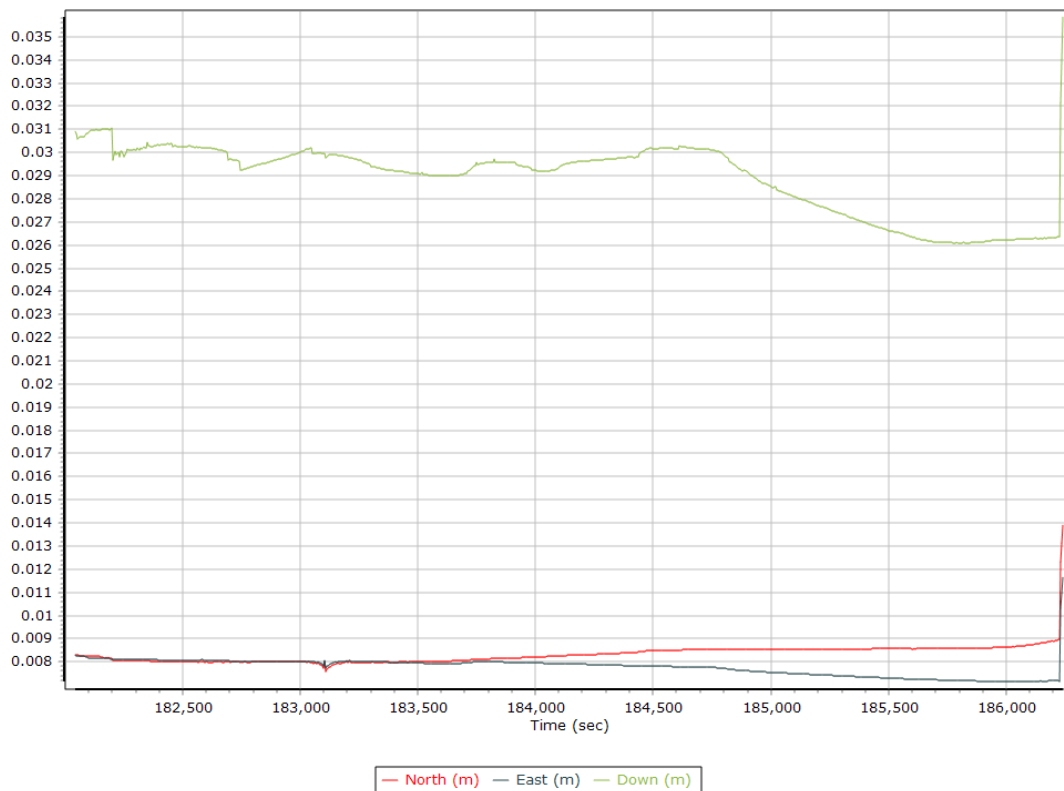
Forward/Reverse Separation



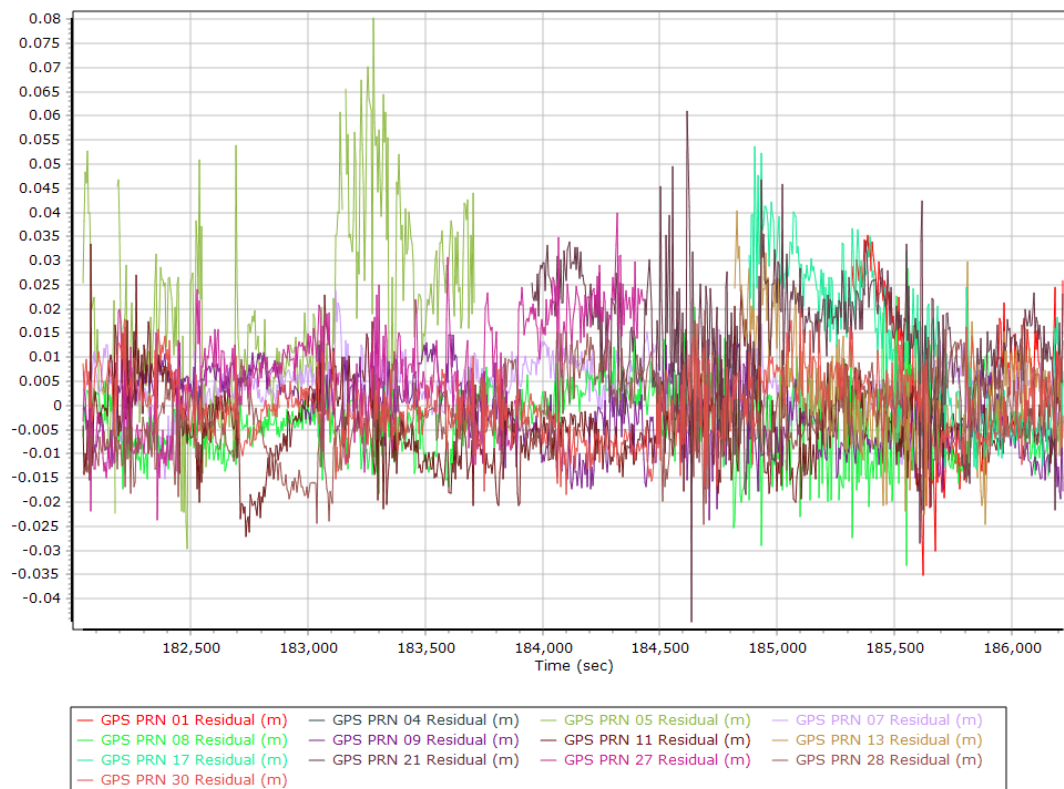
PDOP



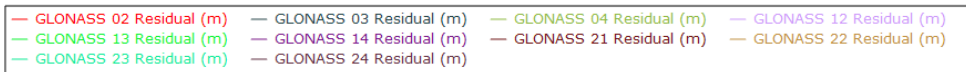
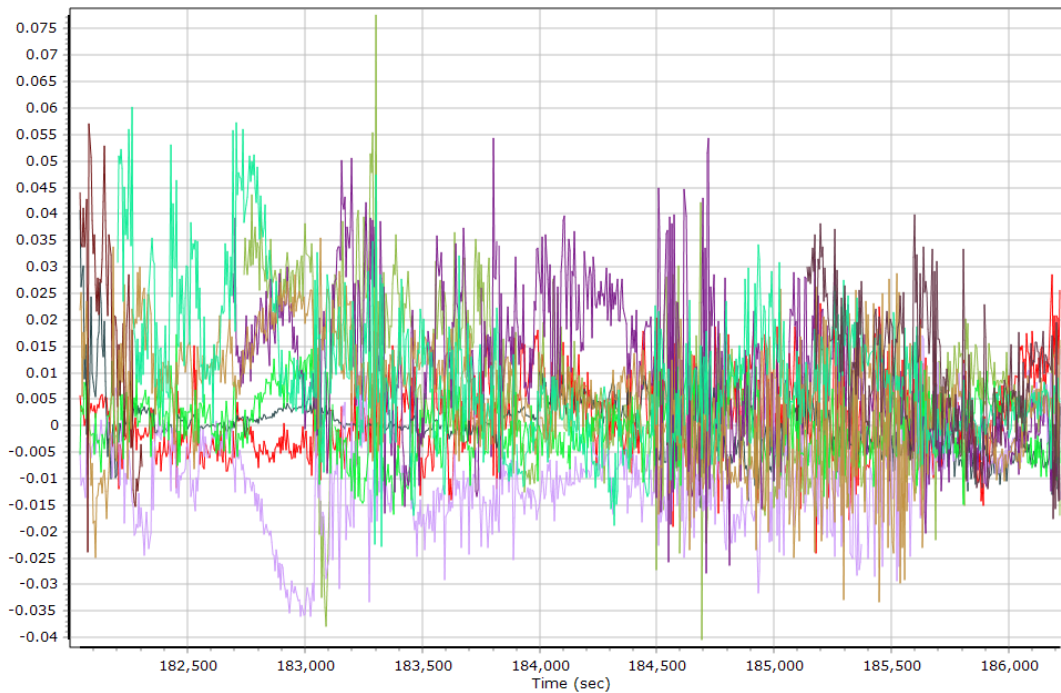
Estimated Position Accuracy



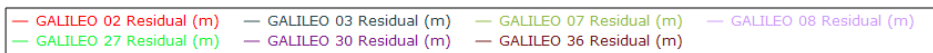
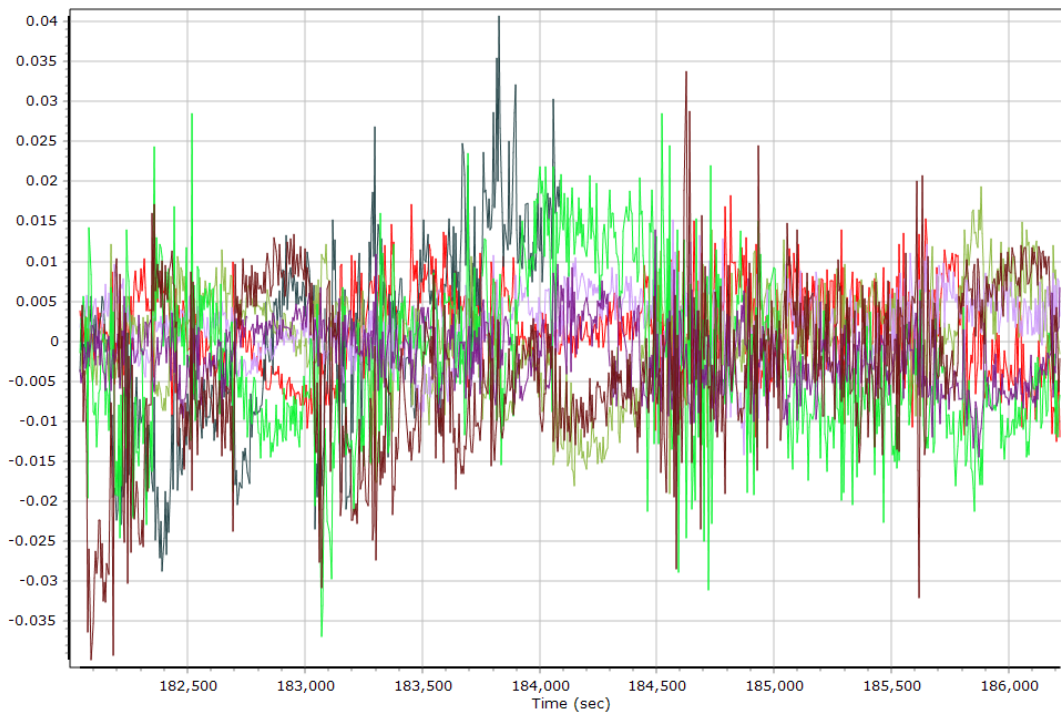
GPS Residuals



GLONASS Residuals



GALILEO Residuals



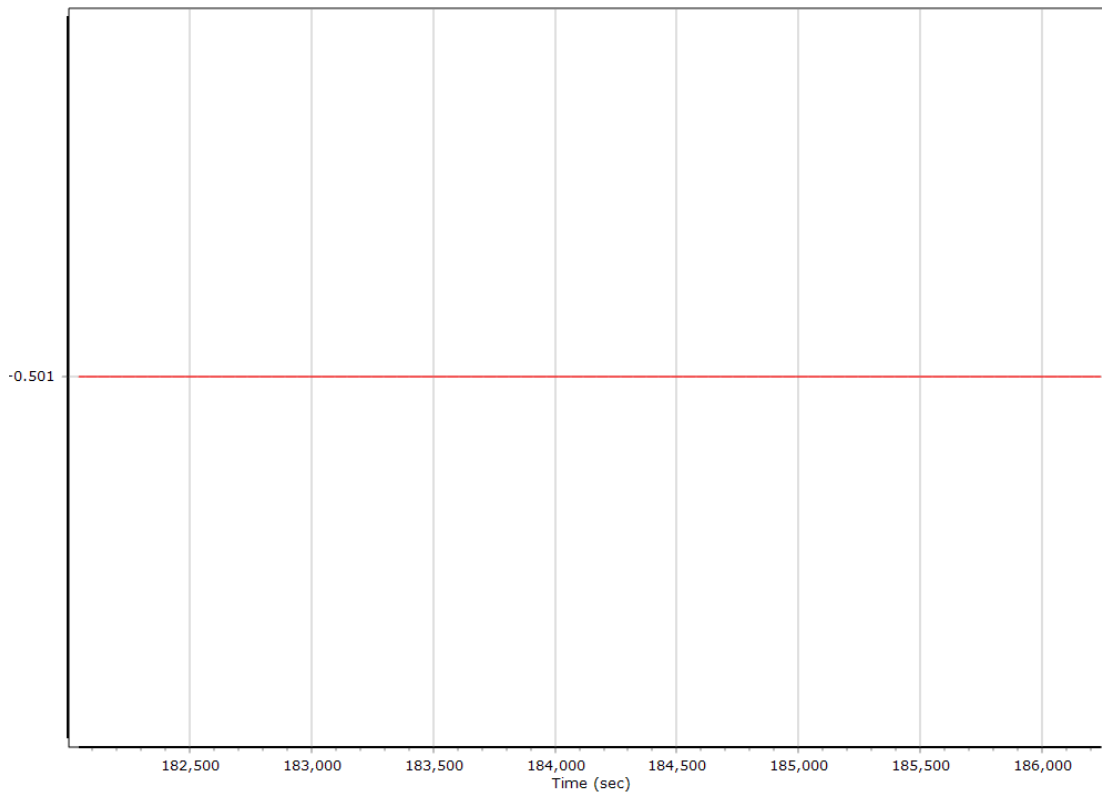
GNSS-Inertial Processor Configuration

Processing mode	IN-Fusion PP-RTX		
Stabilized mount	False		
Processing start time	181663.000 (11/10/2020 2:27:43 AM)		
Processing end time	186245.000 (11/10/2020 3:44:05 AM)		
Initial attitude source	Real-Time VNAV/RNAV Attitude		
IMU Sensor Context	Processing with Onboard IMU		
Reference to IMU lever arm (m)	0.000	0.000	0.000
Reference to IMU mounting angles (deg)	0.000	0.000	90.000
Reference to Primary GNSS lever arm (m)	-0.501	0.125	-1.223
Reference to Primary GNSS lever arm std dev (m)	0.030	0.030	0.030
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

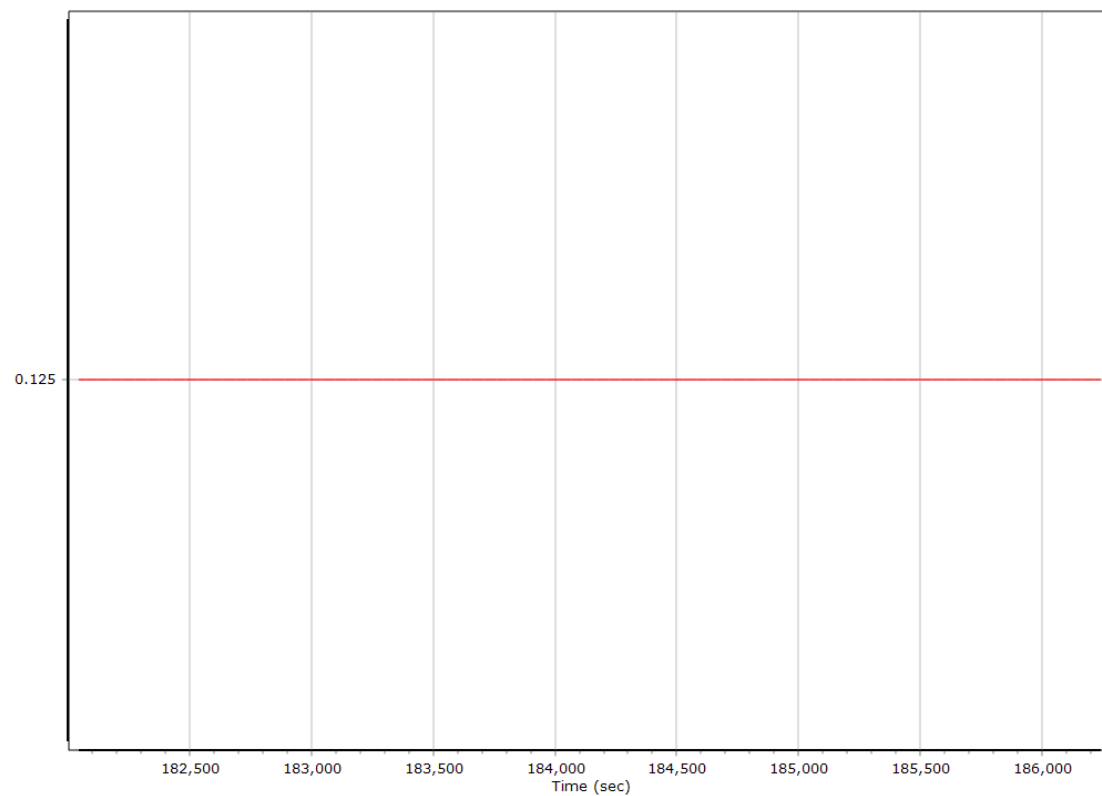
Calibrated Installation Parameters

Reference-Primary GNSS Lever Arm (m)

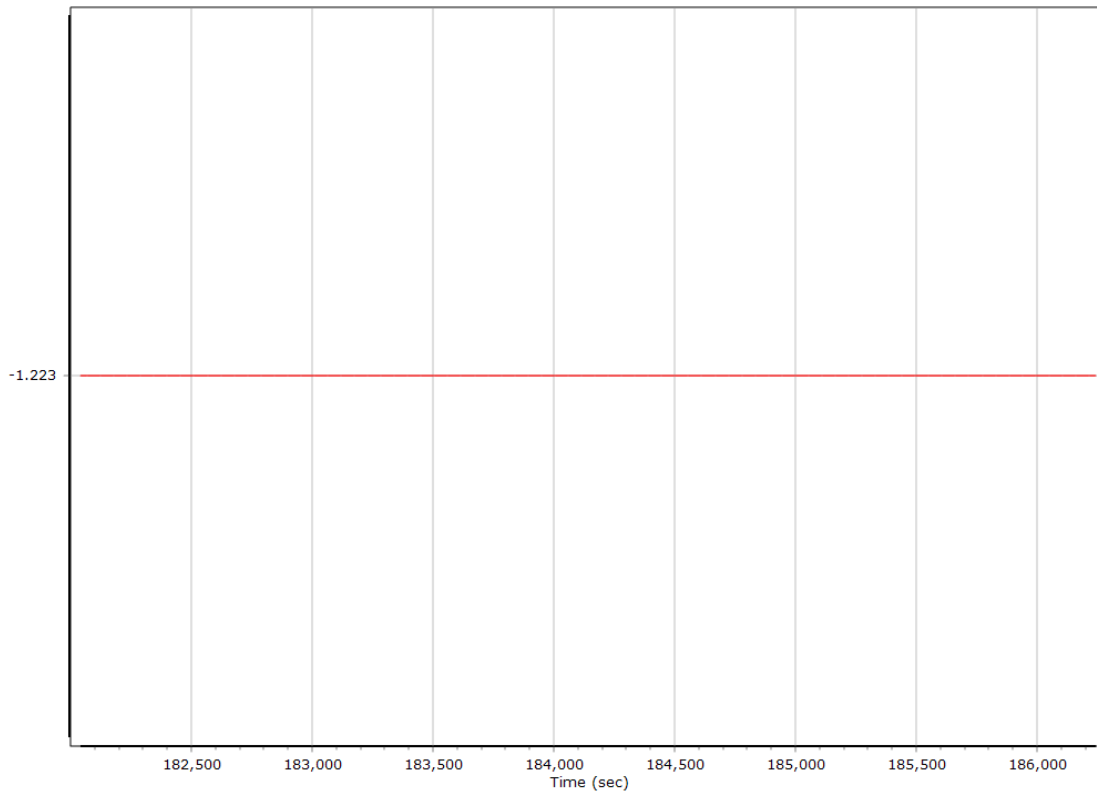
X Reference-Primary GNSS Lever Arm (m)



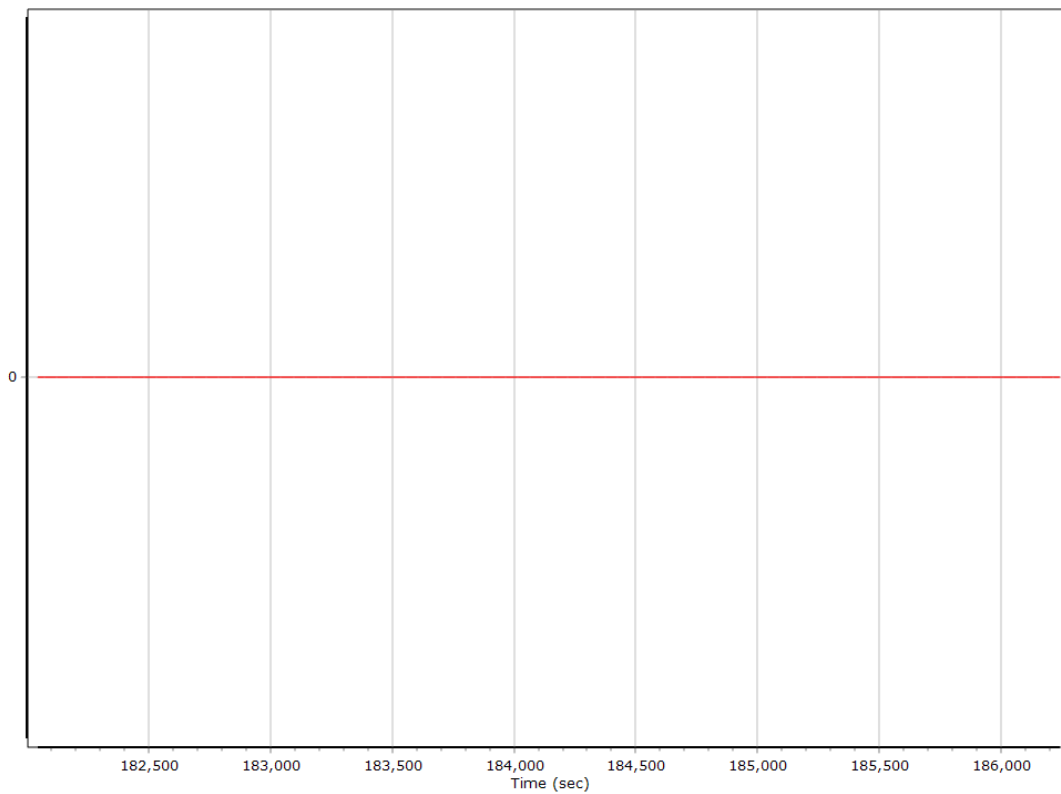
Y Reference-Primary GNSS Lever Arm (m)



Z Reference-Primary GNSS Lever Arm (m)



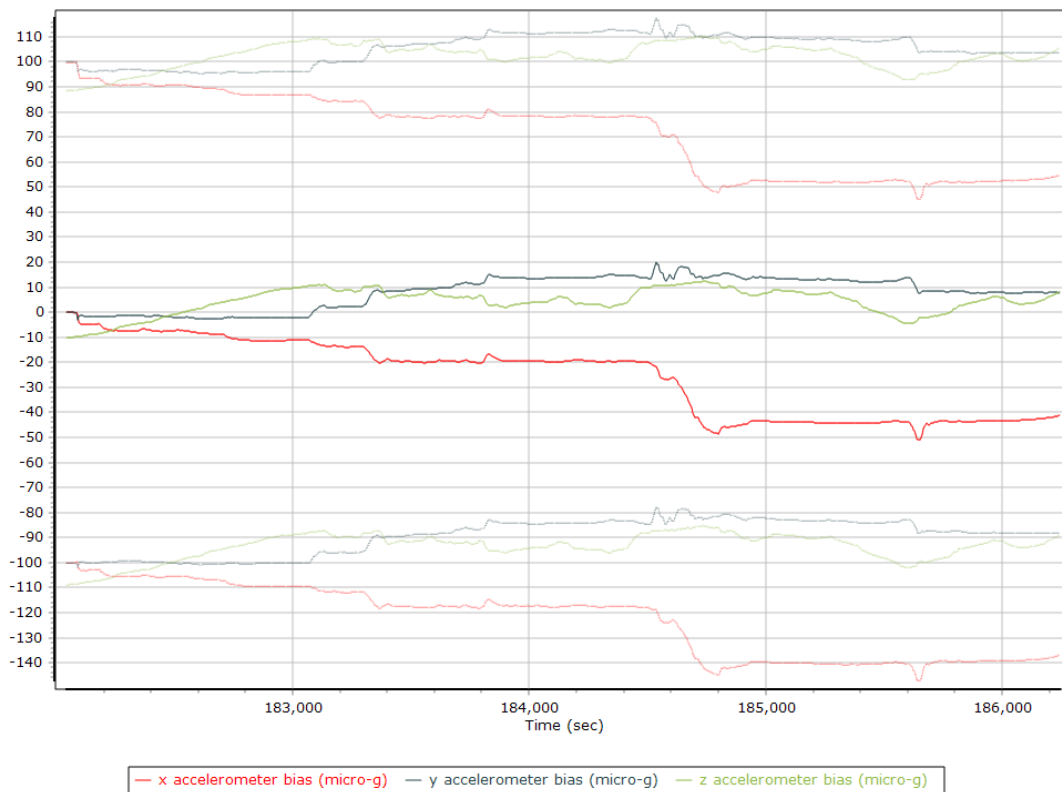
Reference-Primary GNSS Lever Arm Figure of Merit



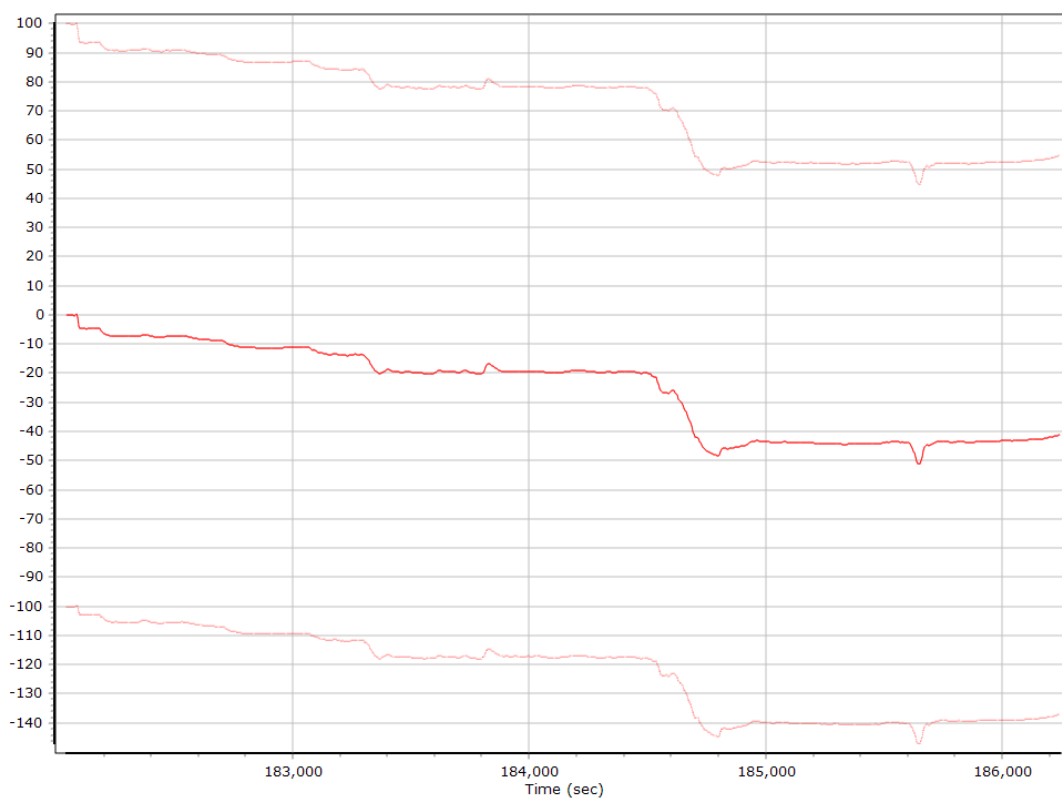
IN-Fusion QC

Forward Processed Estimated Errors, Reference Frame

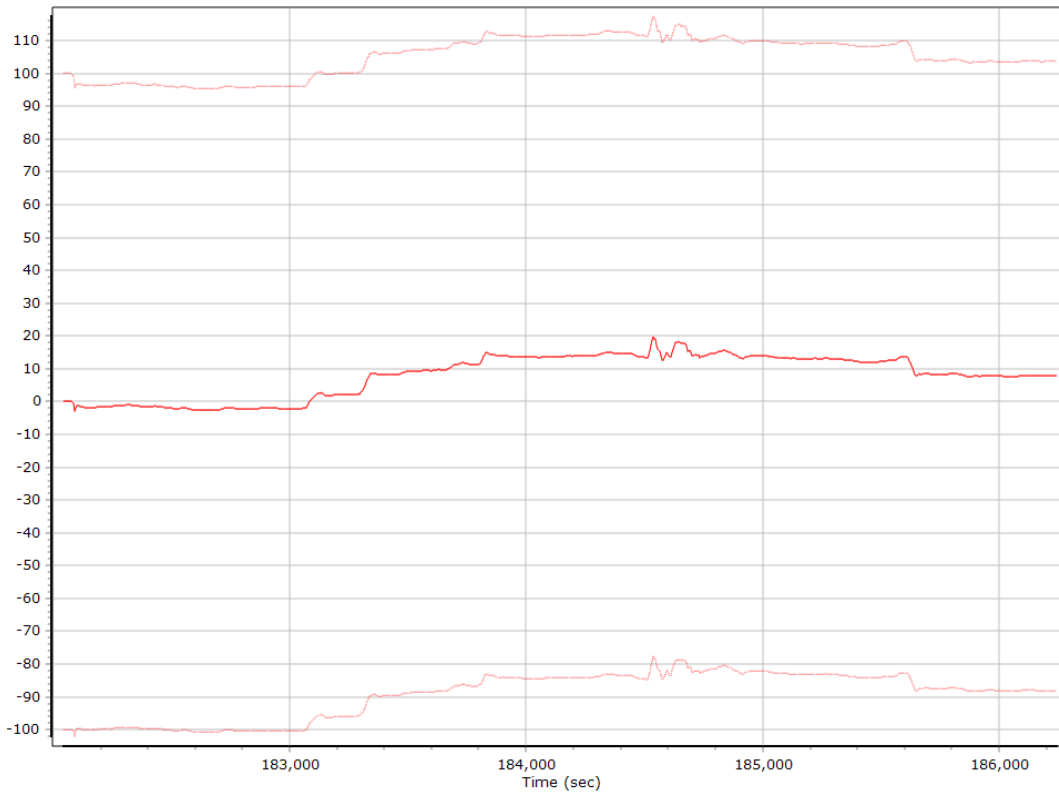
Accelerometer Bias (micro-g)



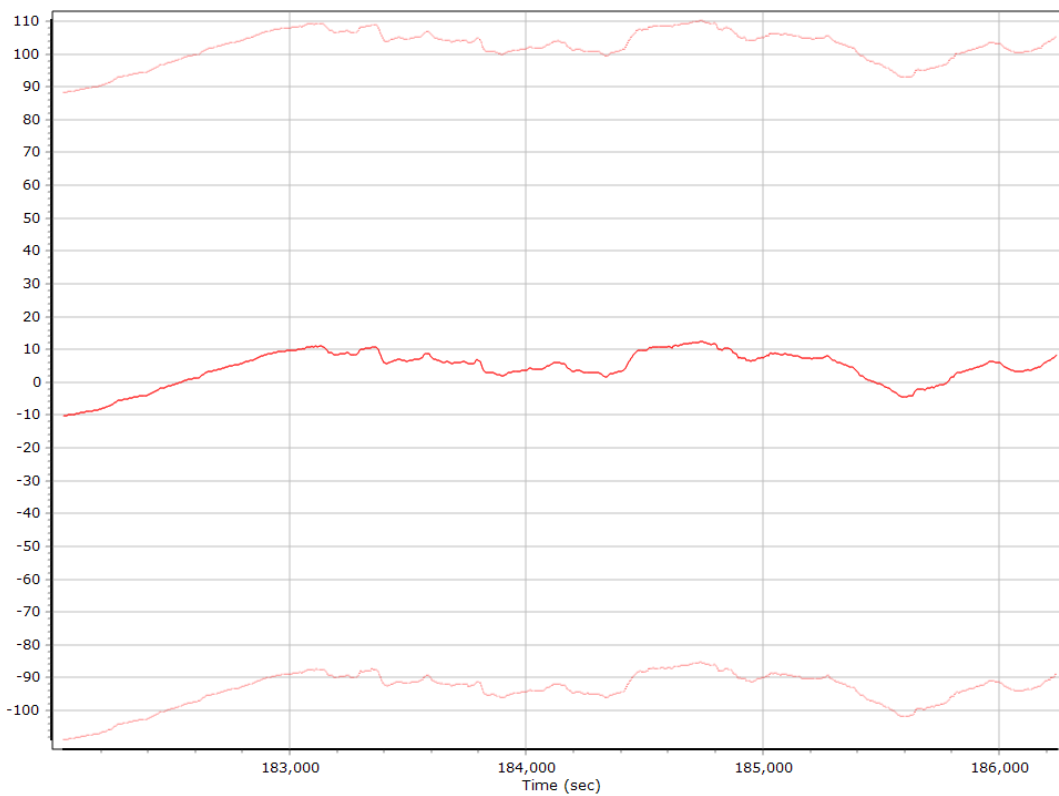
X Accelerometer Bias (micro-g)



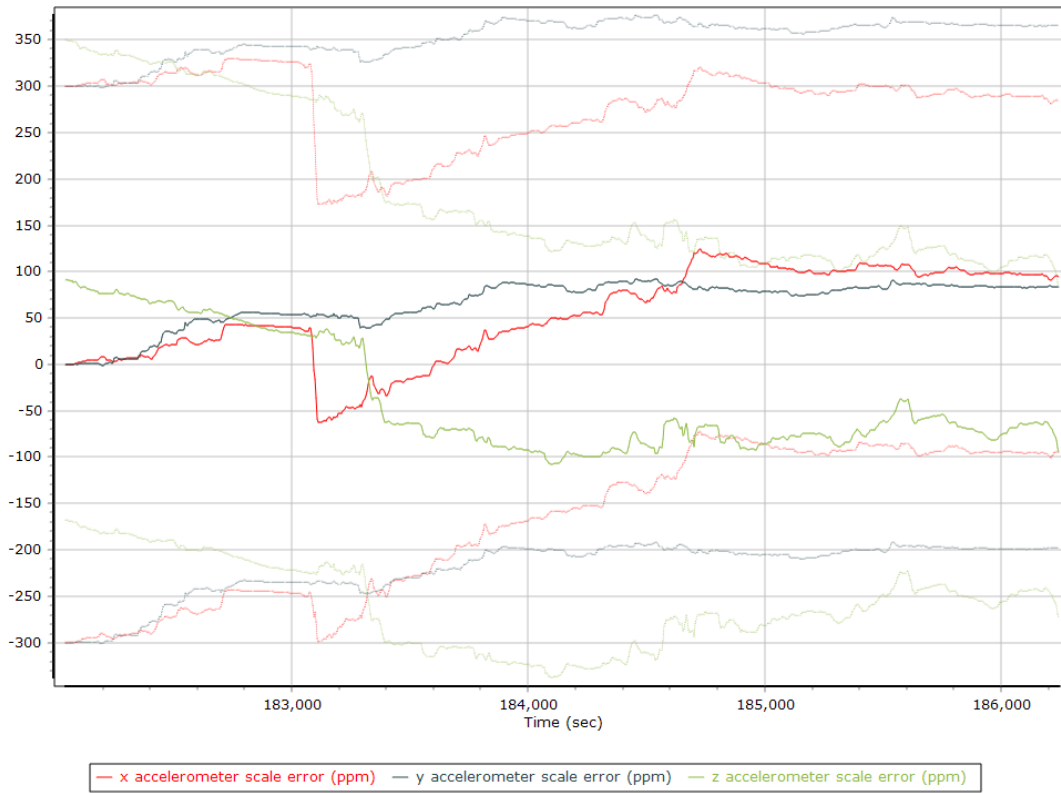
Y Accelerometer Bias (micro-g)



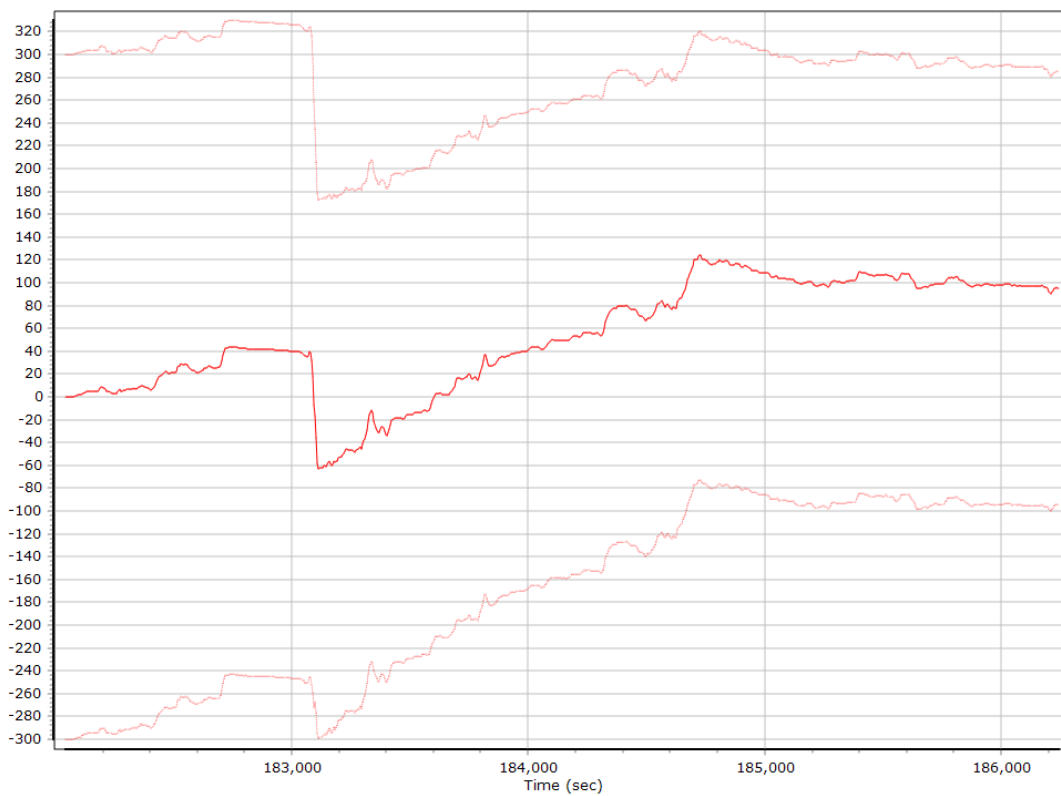
Z Accelerometer Bias (micro-g)



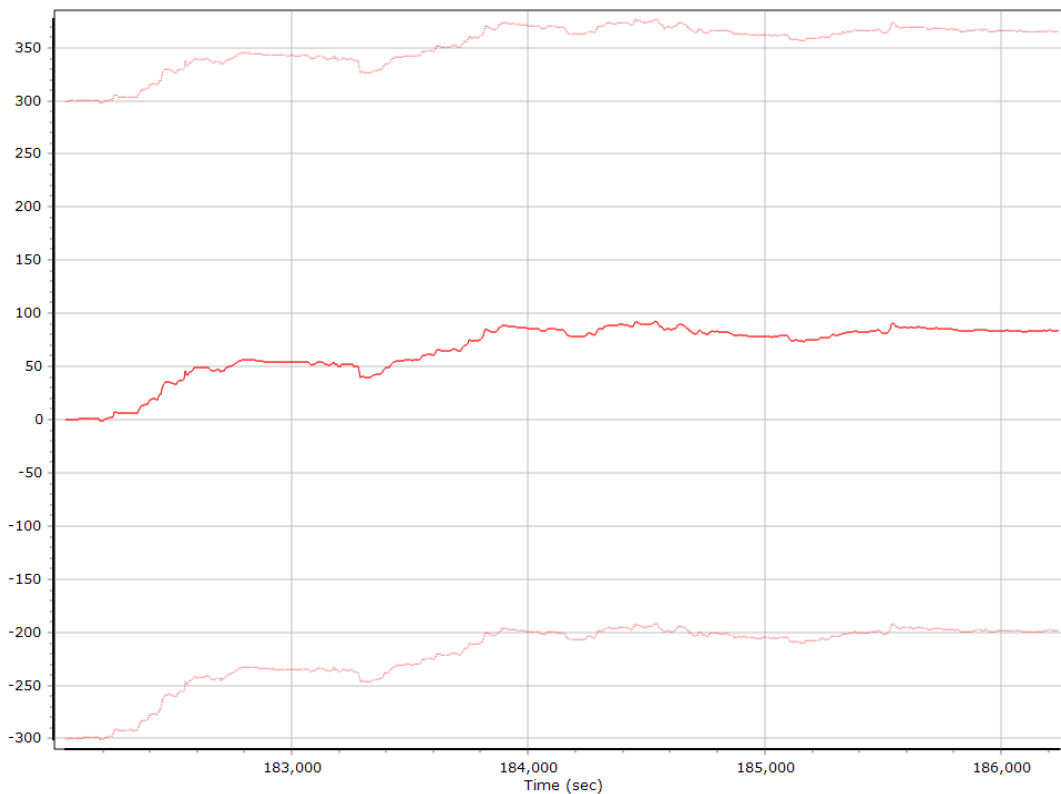
Accelerometer Scale Error (ppm)



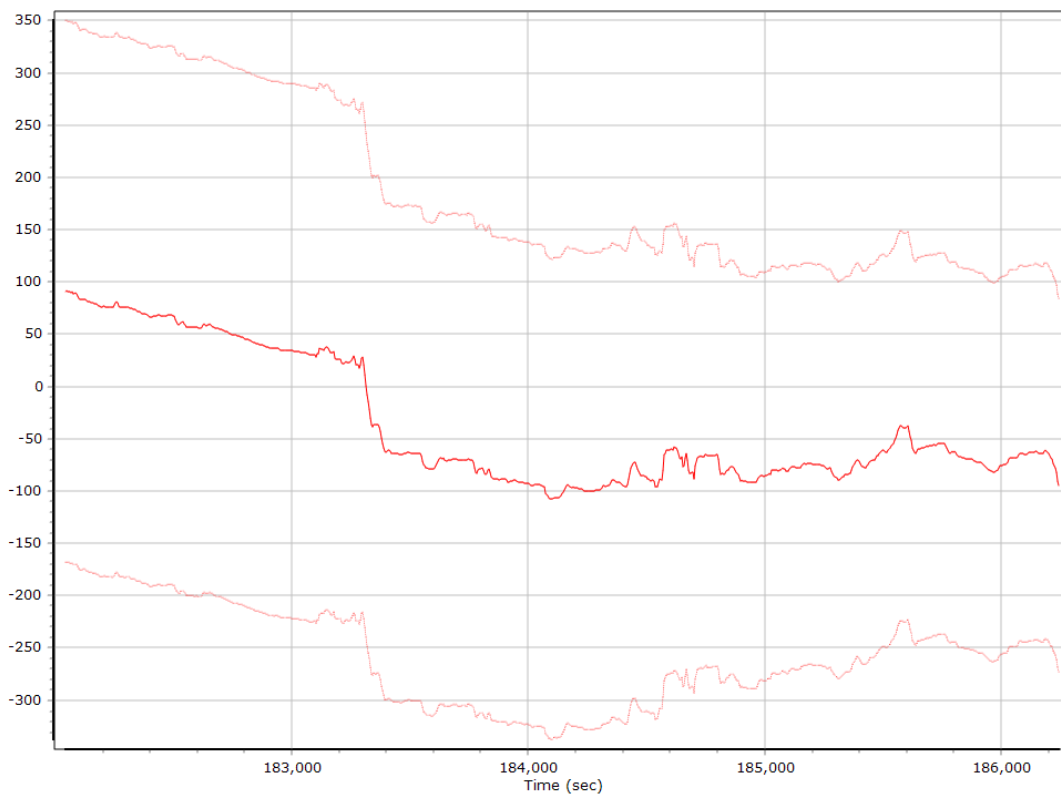
X Accelerometer Scale Error (ppm)



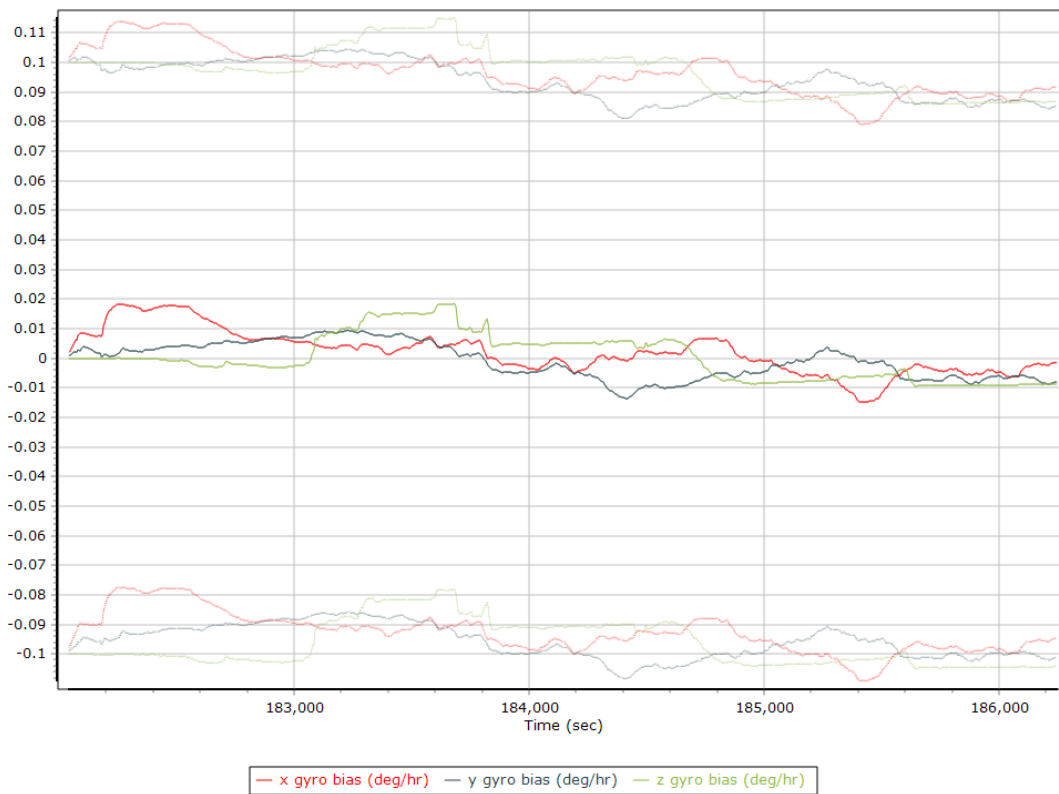
Y Accelerometer Scale Error (ppm)



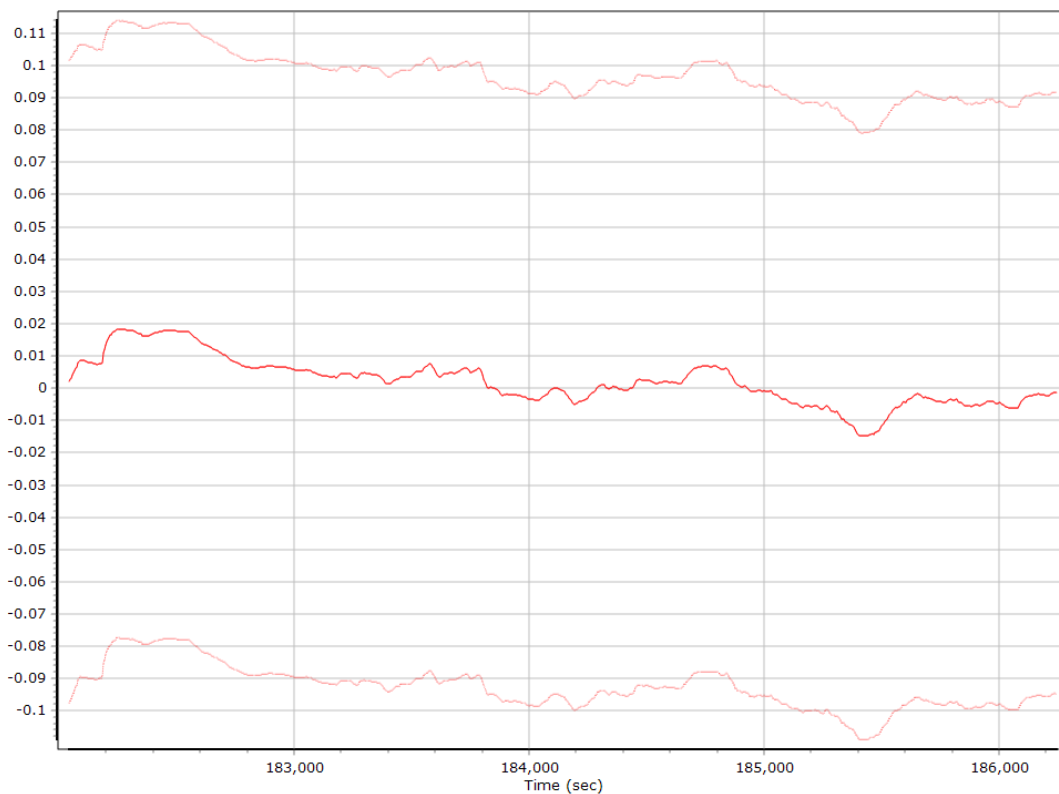
Z Accelerometer Scale Error (ppm)



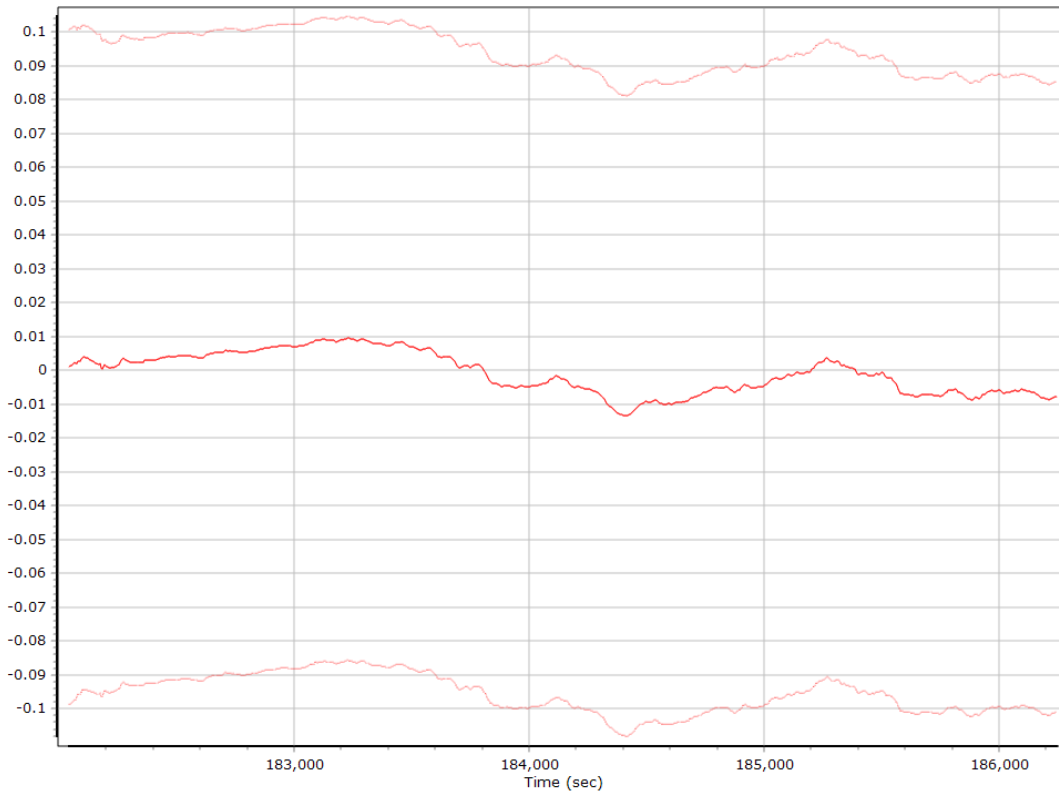
Gyro Bias (deg/h)



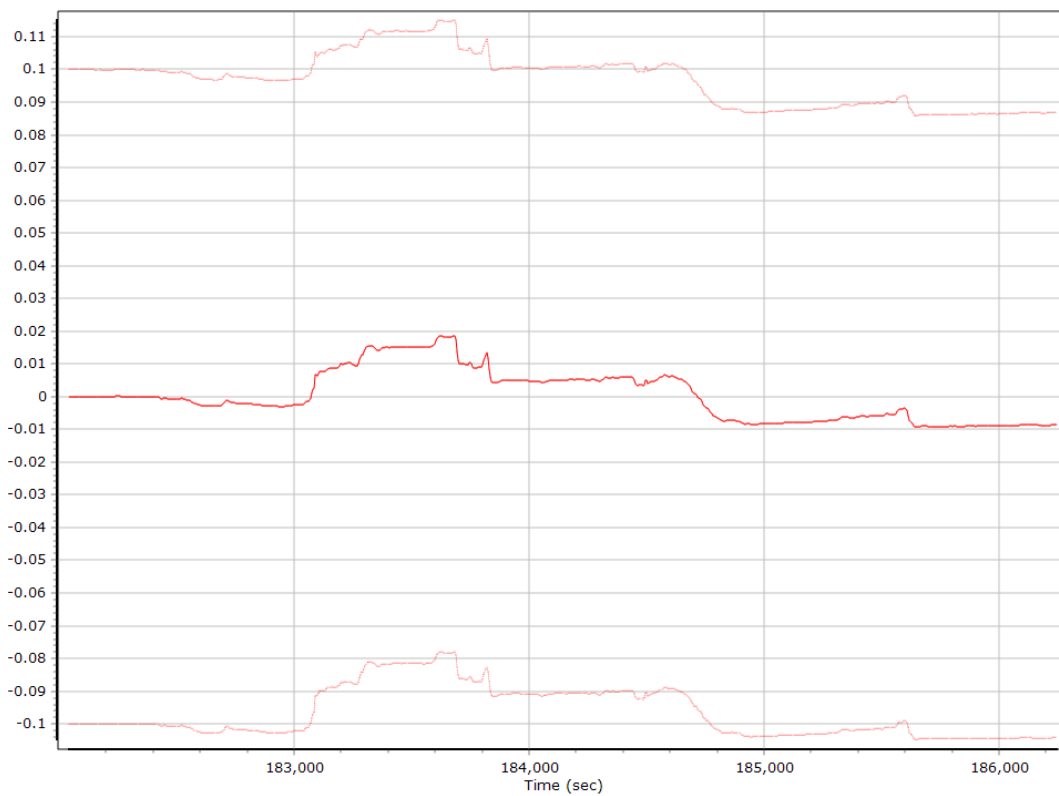
X Gyro Bias (deg/h)



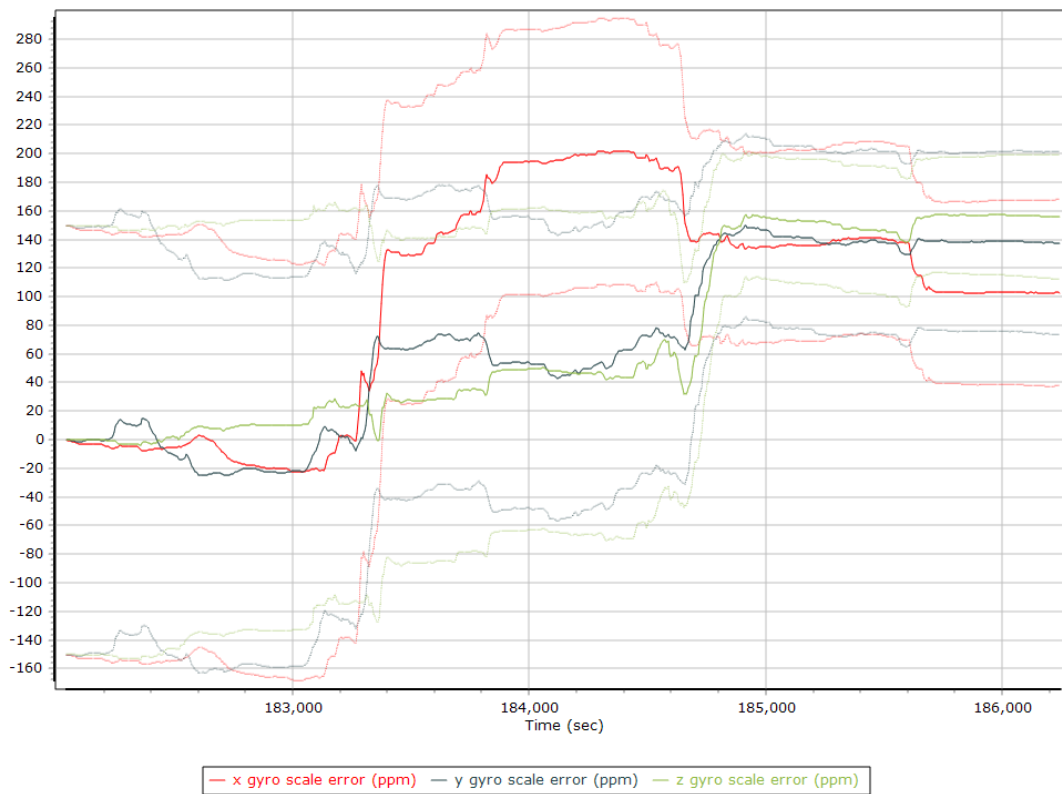
Y Gyro Bias (deg/h)



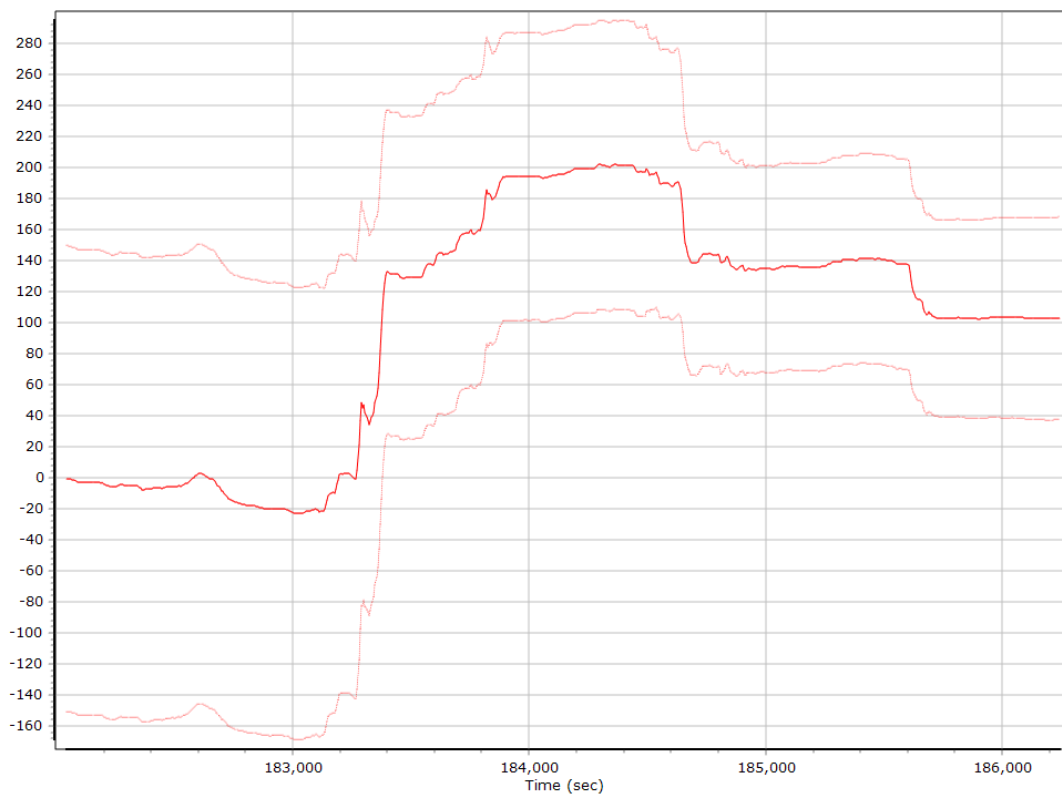
Z Gyro Bias (deg/h)



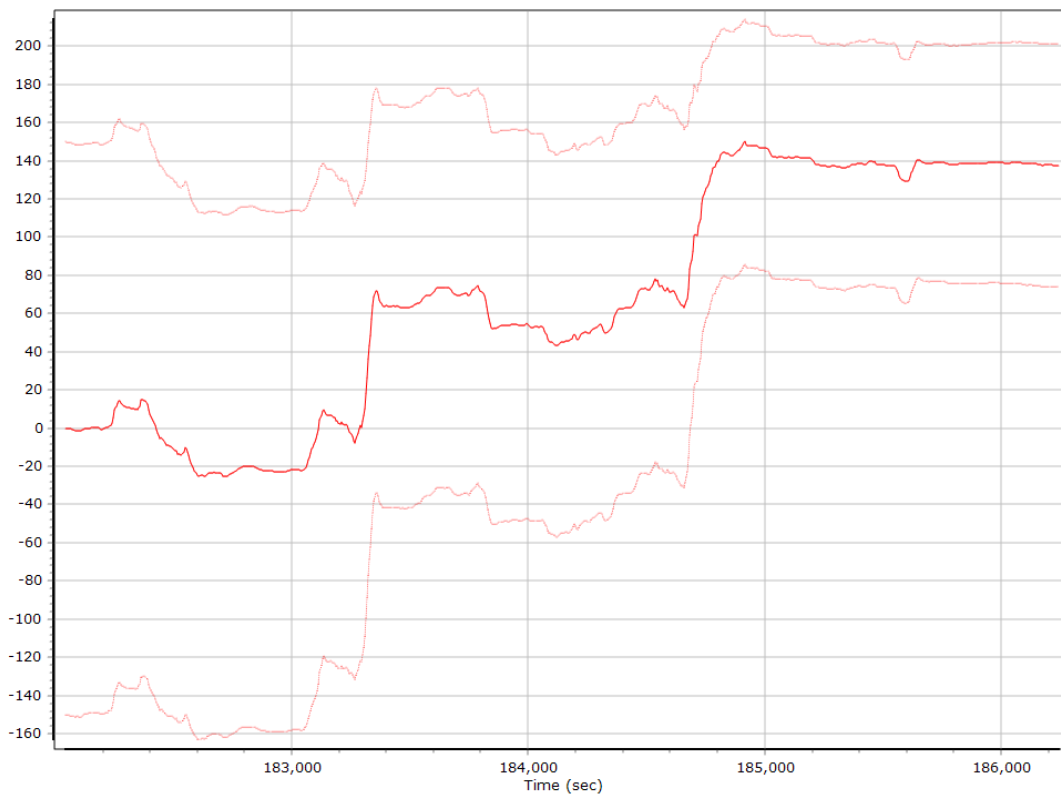
Gyro Scale Error (ppm)



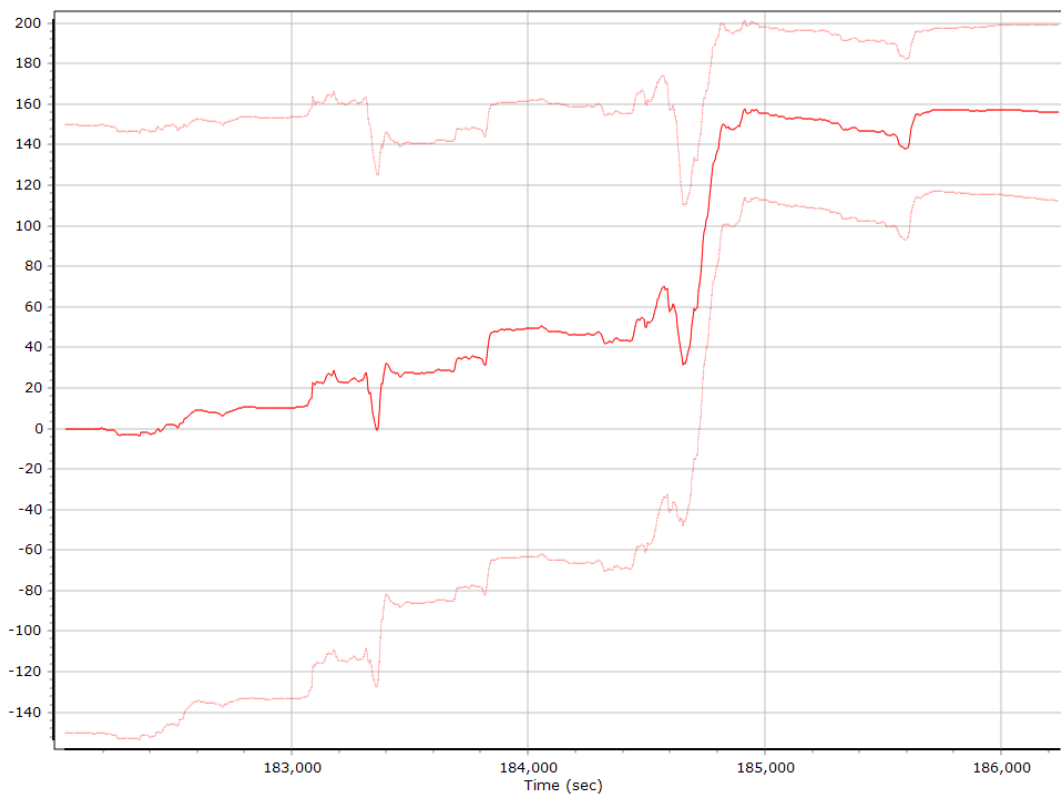
X Gyro Scale Error (ppm)



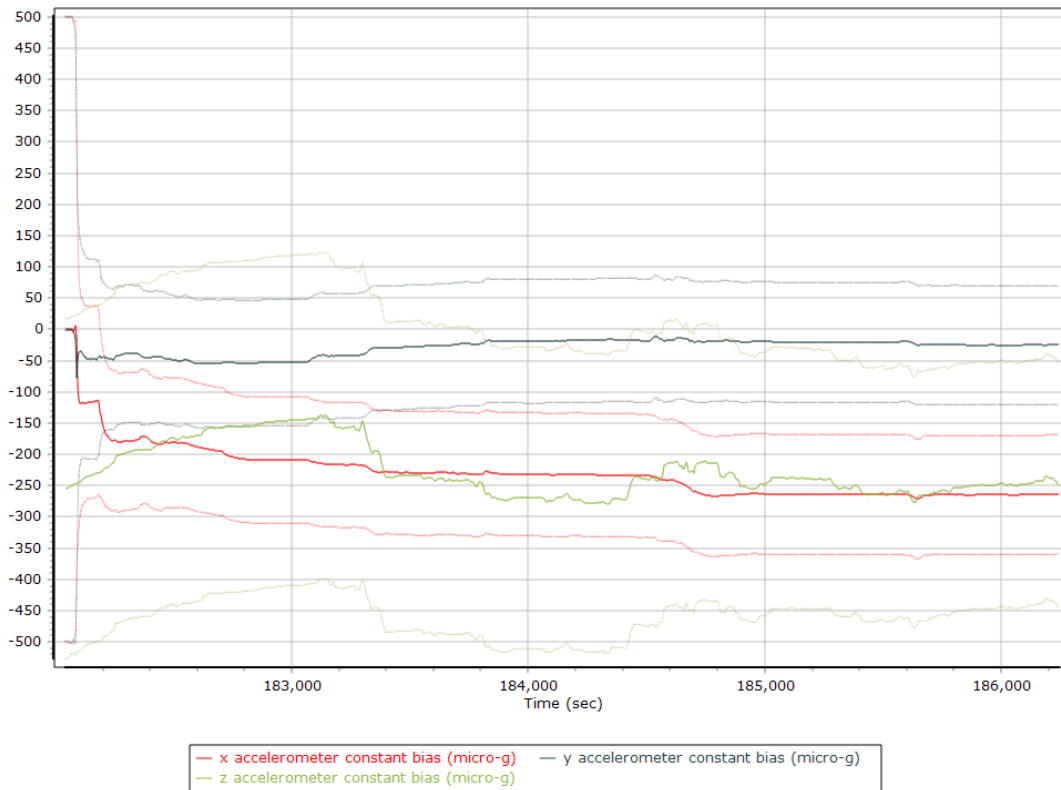
Y Gyro Scale Error (ppm)



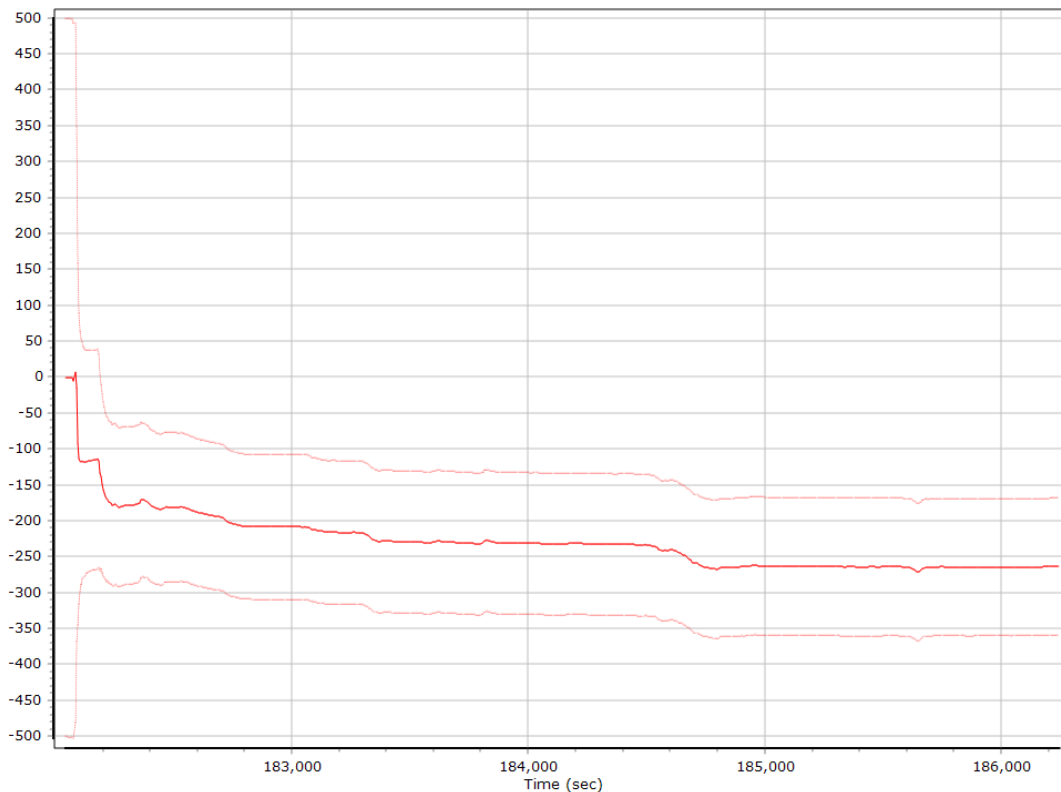
Z Gyro Scale Error (ppm)



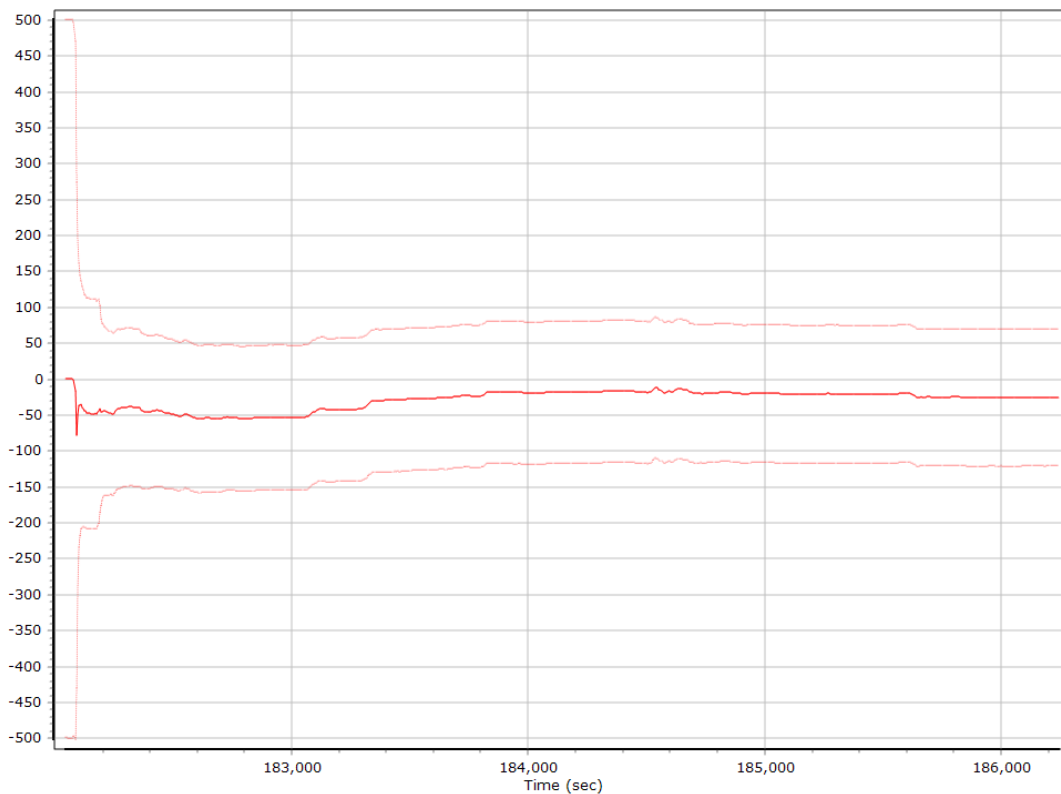
Forward Processed Estimated Constant Errors, Reference Frame Accelerometer Bias (micro-g)



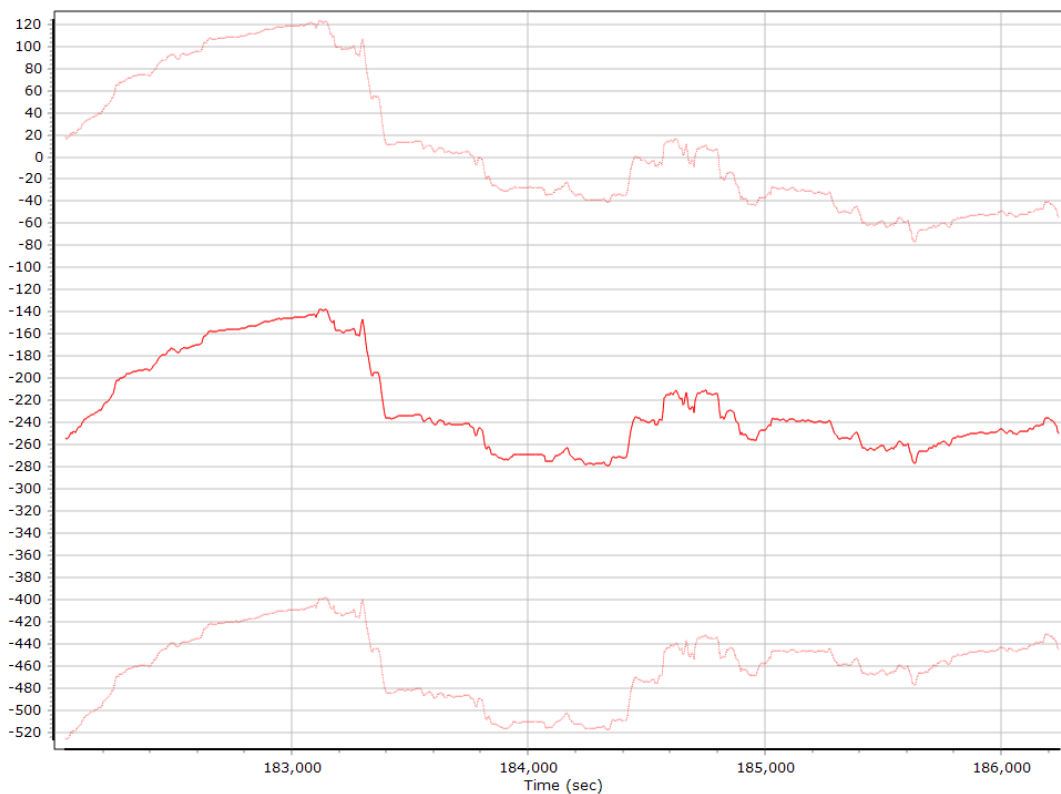
X Accelerometer Bias (micro-g)



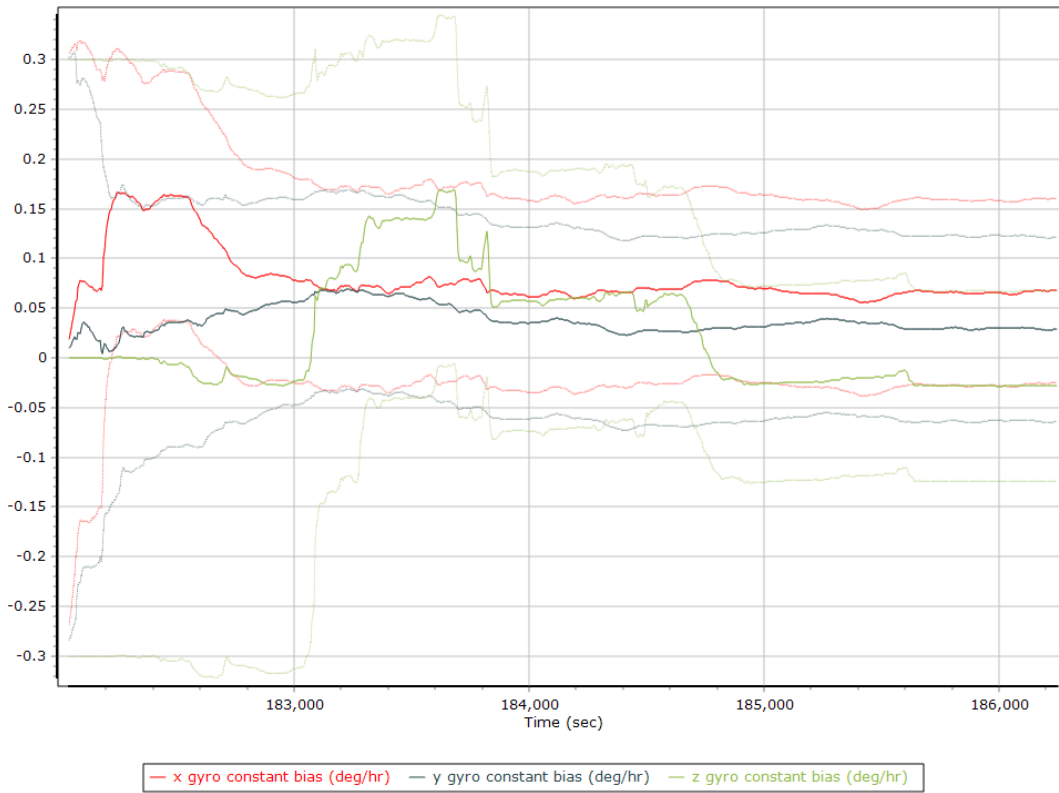
Y Accelerometer Bias (micro-g)



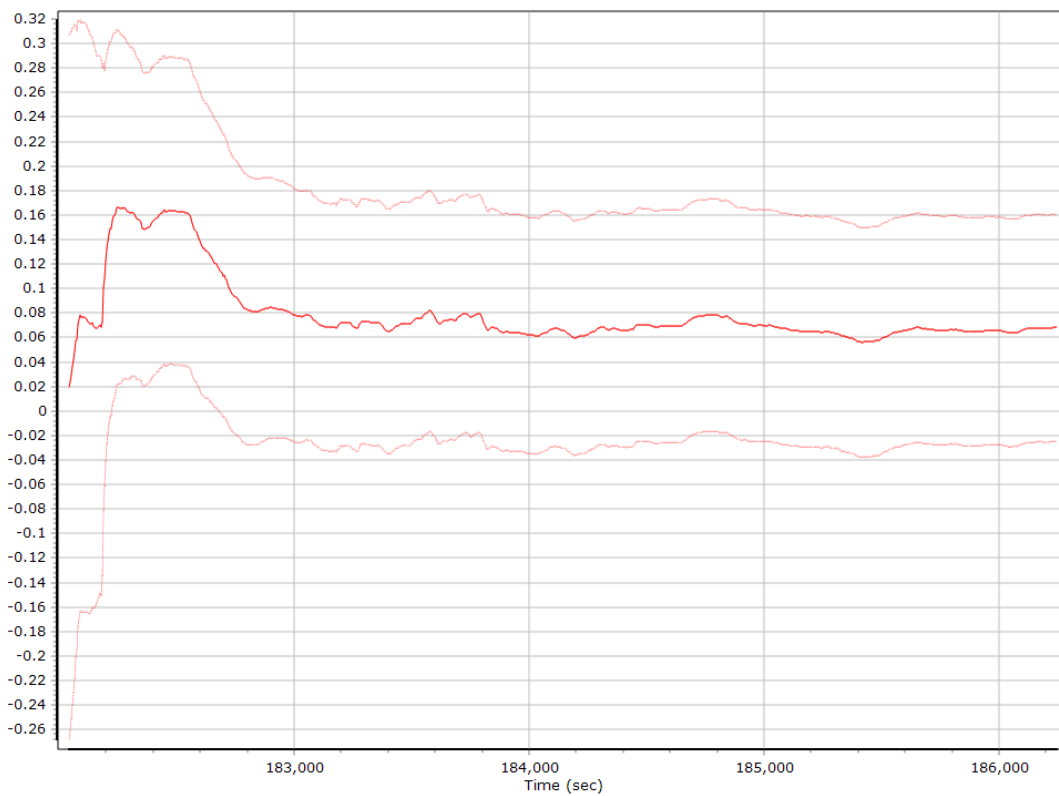
Z Accelerometer Bias (micro-g)



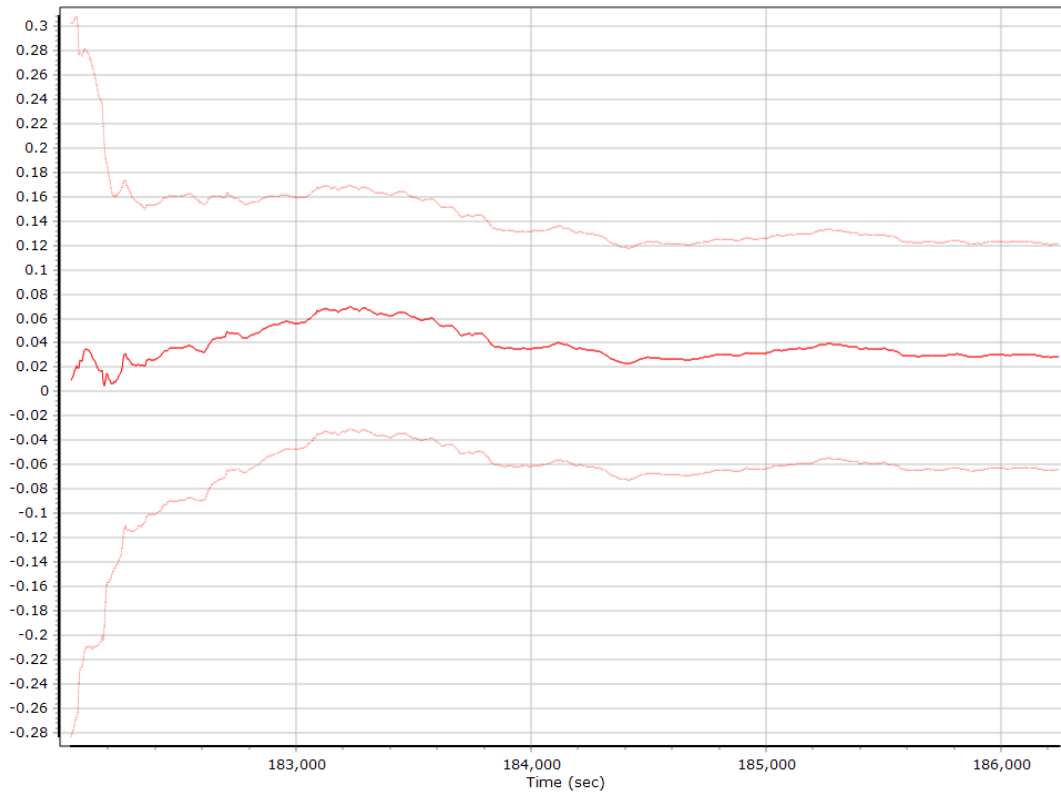
Gyro Bias (deg/h)



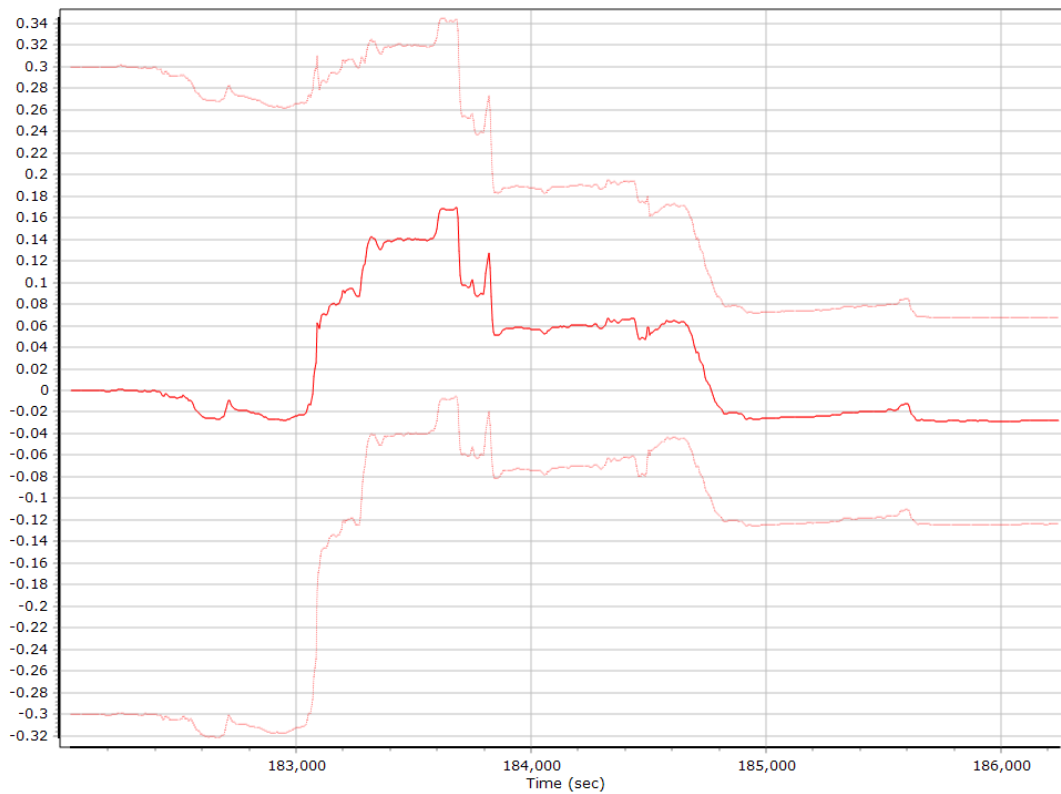
X Gyro Bias (deg/h)



Y Gyro Bias (deg/h)

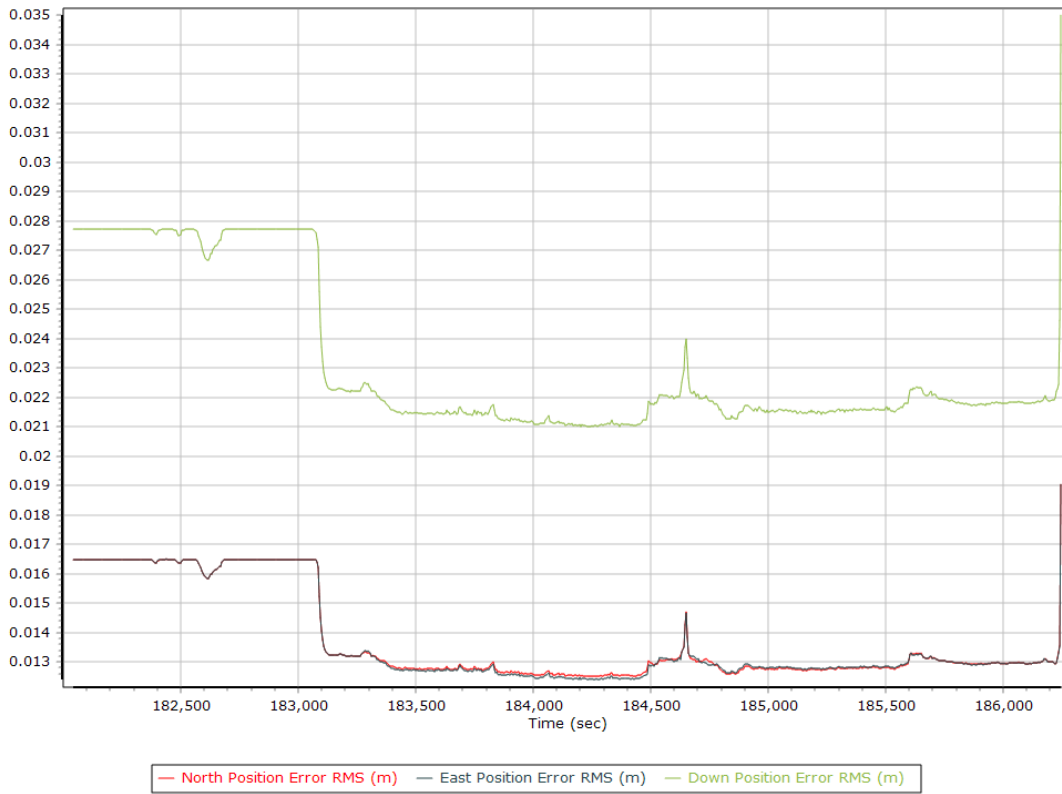


Z Gyro Bias (deg/h)

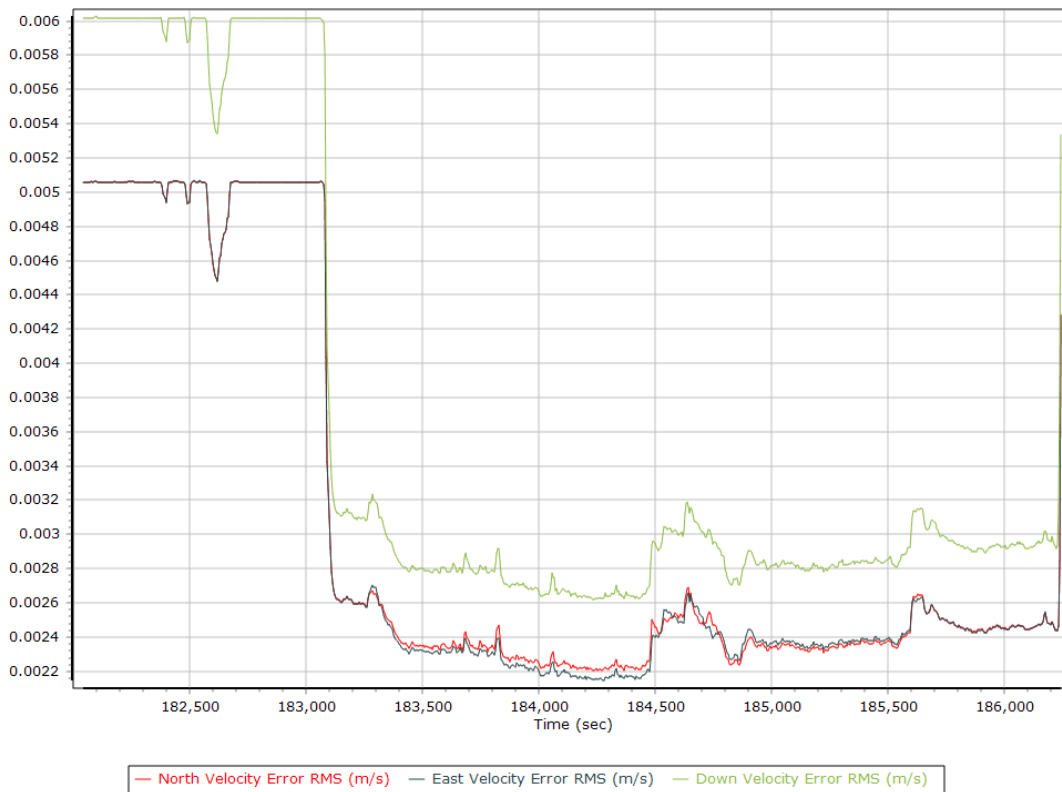


Smoothed Performance Metrics

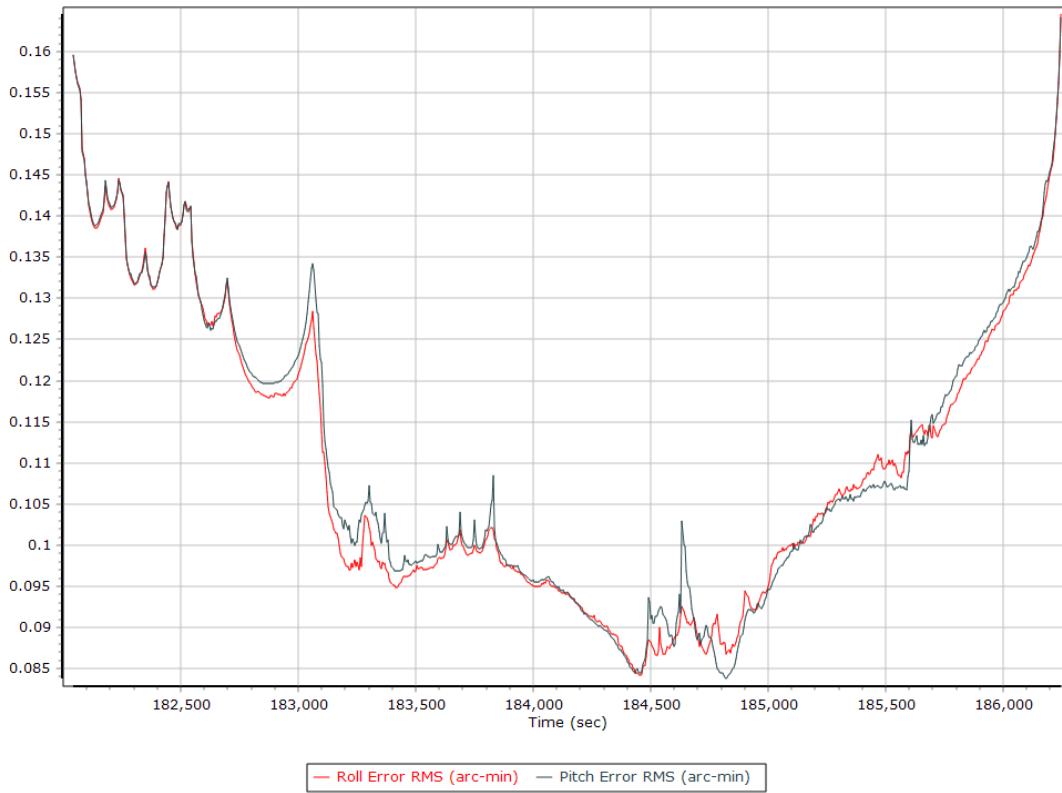
Position Error RMS (m)



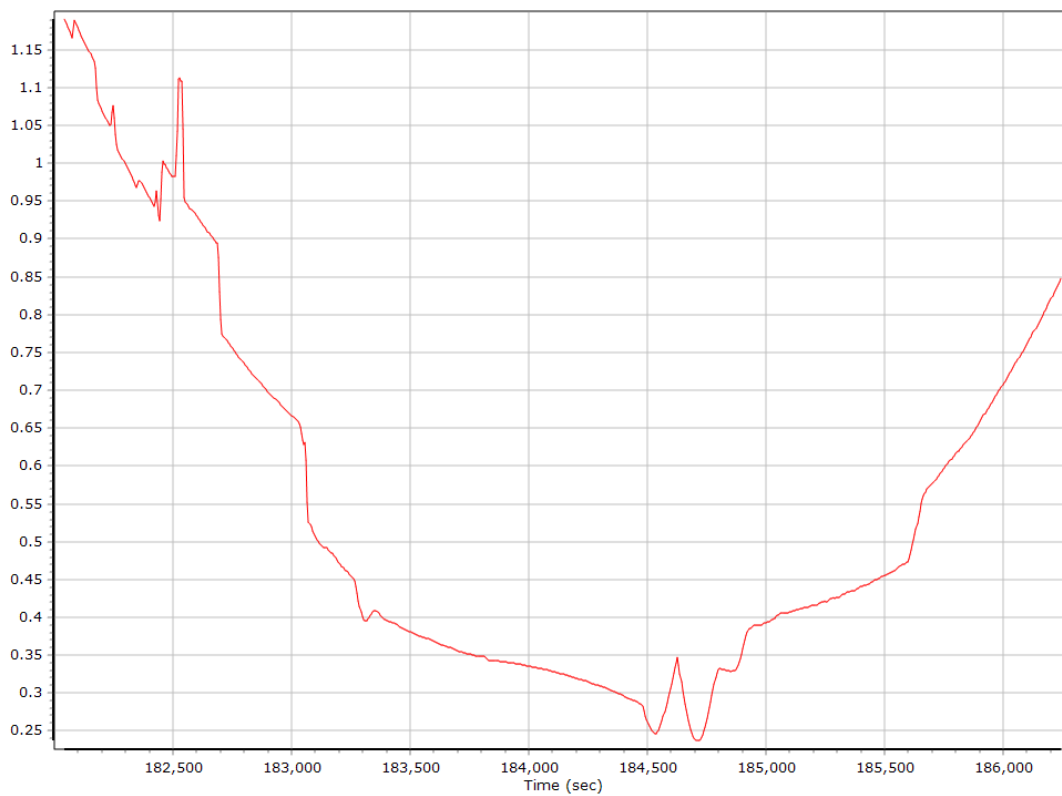
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

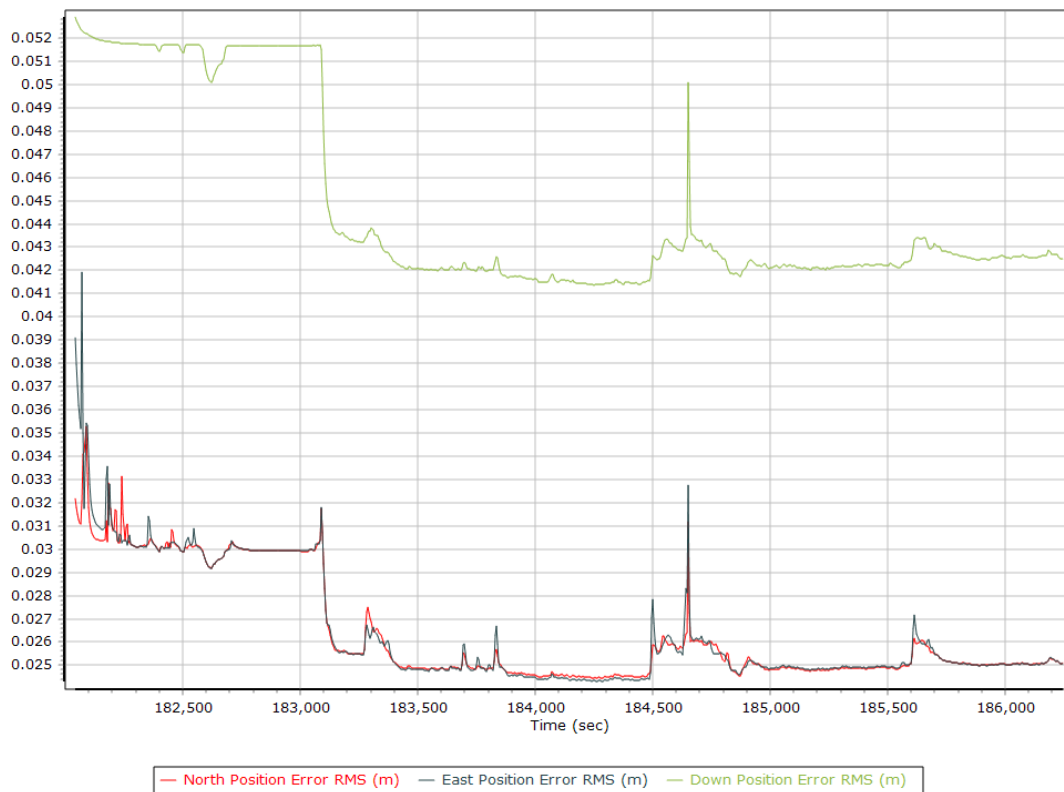


Heading Error RMS (arc-min)

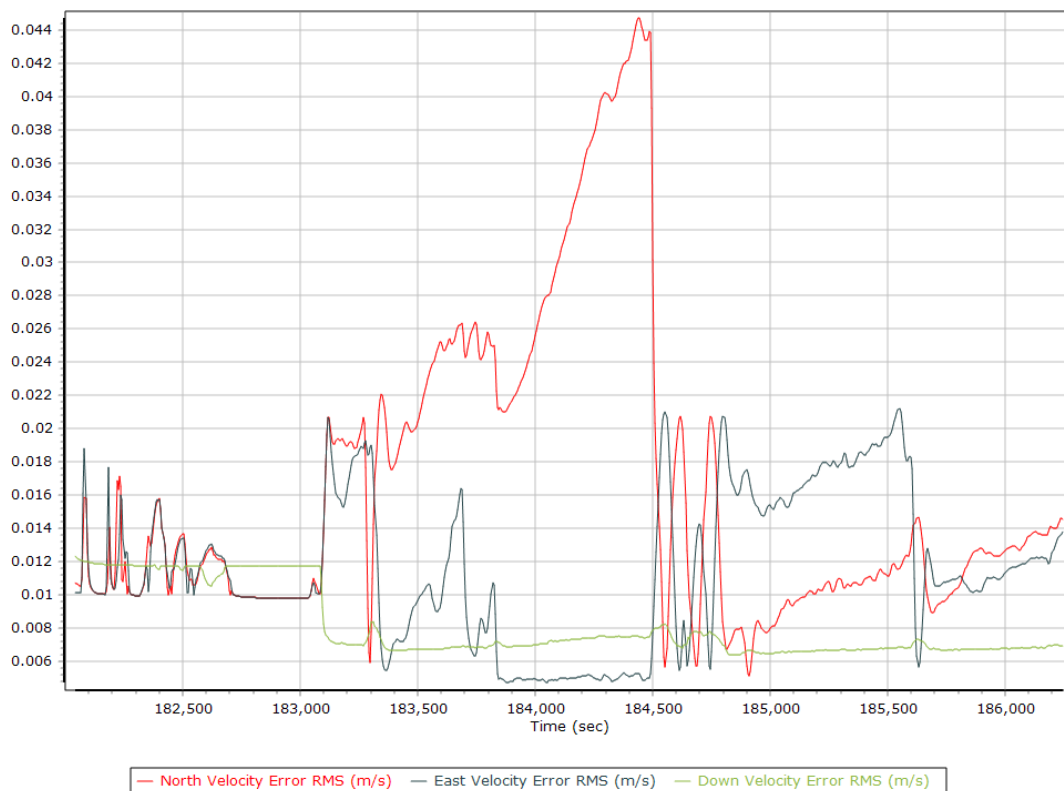


Forward Processed Performance Metrics

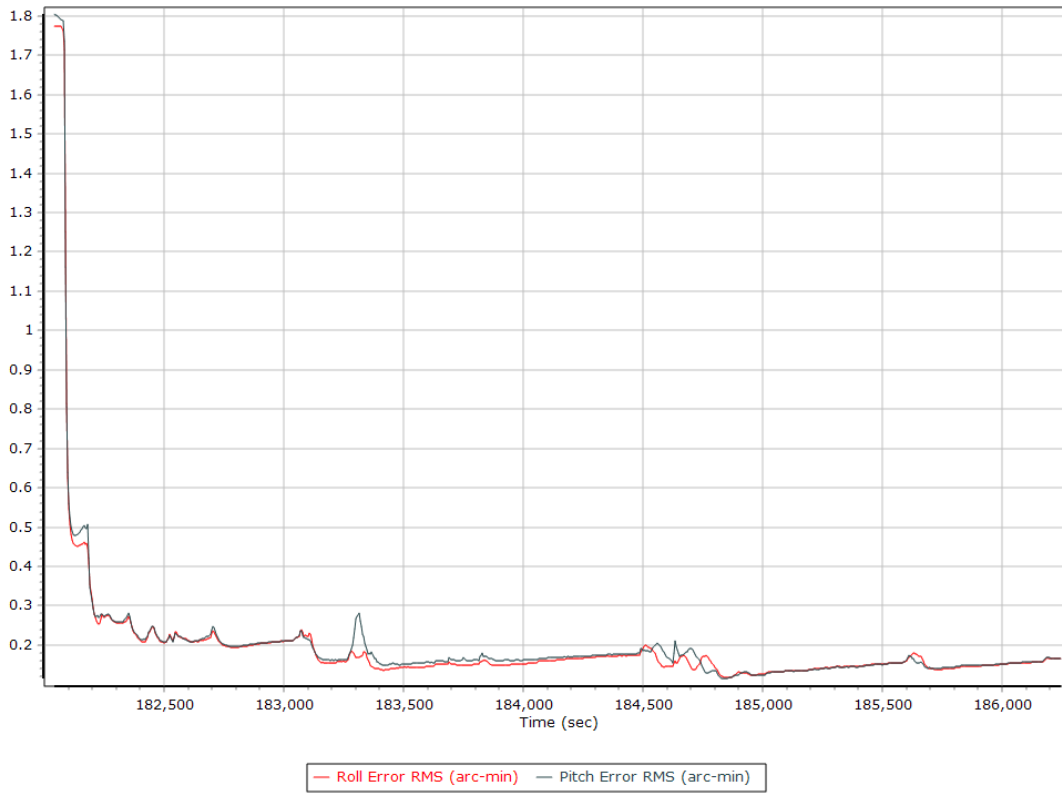
Position Error RMS (m)



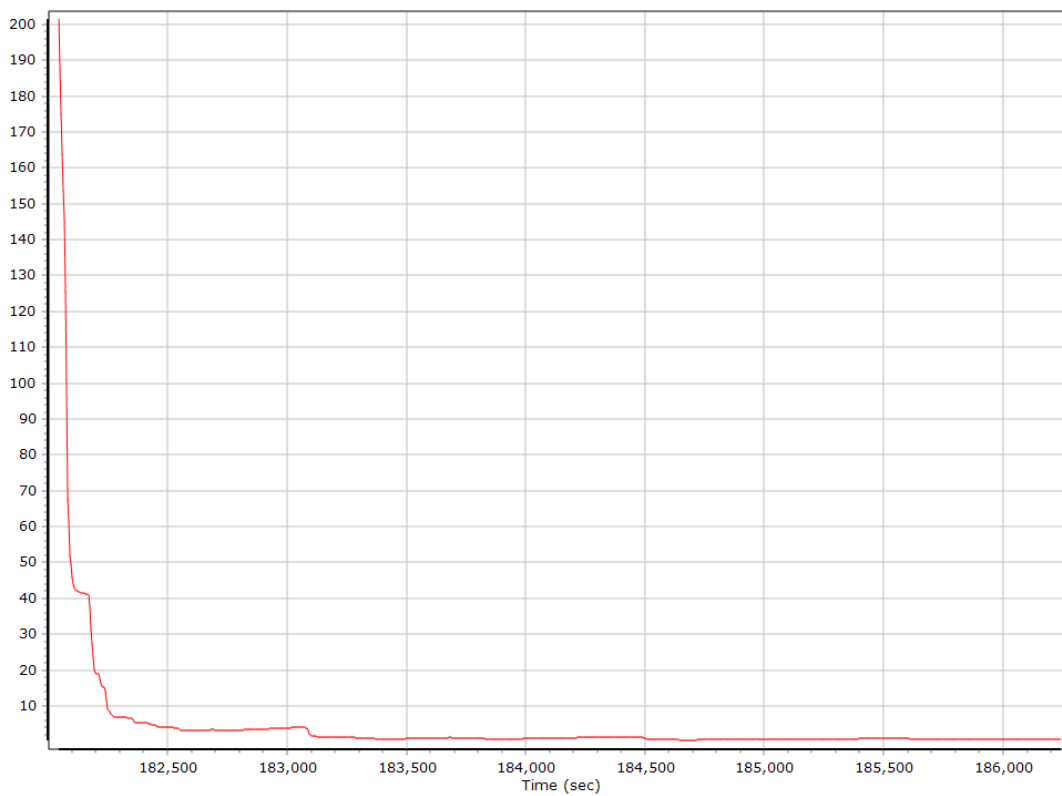
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

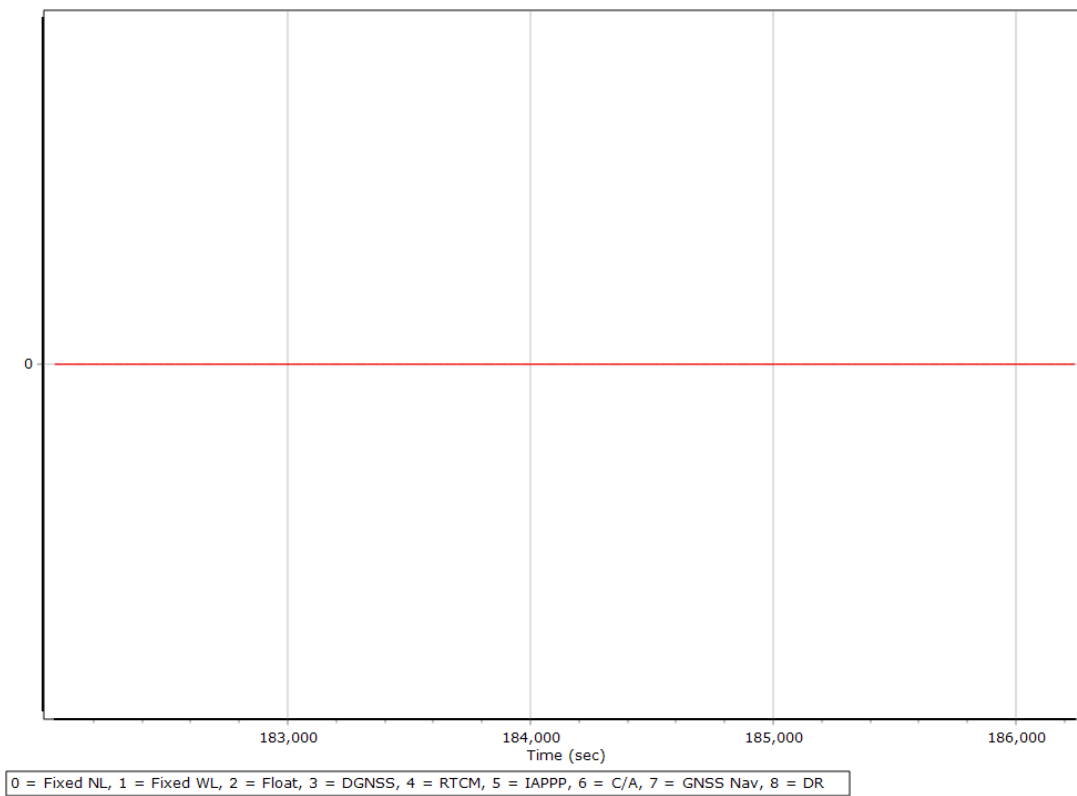


Heading Error RMS (arc-min)

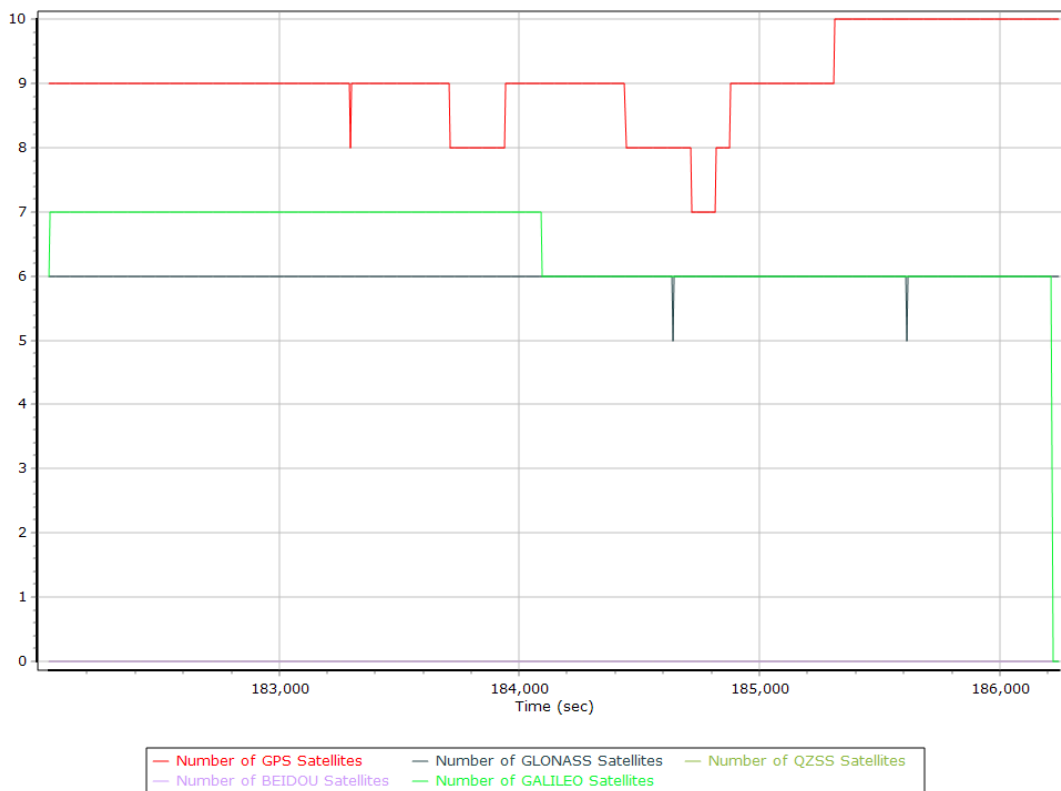


Forward Processed Solution Status

Processing Mode



Number of Satellites



Baseline Length

