

General Information

Mission Information

Project name	201208_A_5060420_nad2011_FINAL
Processing date	2020-12-11 13:16:50
Mission date	2020-12-08 14:51:20
Mission duration	02:29:55.000
Processing mode	IN-Fusion PP-RTX

Rover Hardware Information

Product	POS AV 610 VER6 HW2.5-12
Serial number	S/N9825
IMU type	57
Receiver type	BD982
Antenna type	AV39

Project File List

Rover Data Files

File name	File type
survey92.pos	POS Data

Input Files

File Name	File Type
Ephm3430.20g	GLONASS Broadcast Ephemeris
Ephm3430.20n	GPS Broadcast Ephemeris

Output Files

Filename	File type
sbet_201208_A_5060420_nad2011_FINAL.out	SBET Trajectory File

Rover Data Summary

First raw data file	survey92.pos		
Last raw data file	survey92.pos		
Start GPS week	2135		
Start time	226279.416 (12/8/2020 2:51:19 PM)		
End time	235275.530 (12/8/2020 5:21:15 PM)		
Start of fine alignment	226595.754 (12/8/2020 2:56:35 PM)		
Available subsystems	Primary GNSS, IMU		
POS Event Input	None		
Correction data	None		
IMU Installation Lever Arms & Mounting Angles			
Reference to IMU lever arm (m)	0.000	0.000	0.000
Reference to IMU mounting angles (deg)	0.000	0.000	-90.000
Reference to Primary GNSS lever arm (m)	0.527	0.205	-1.192
Reference to Primary GNSS lever arm std dev (m)	-1.000		
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

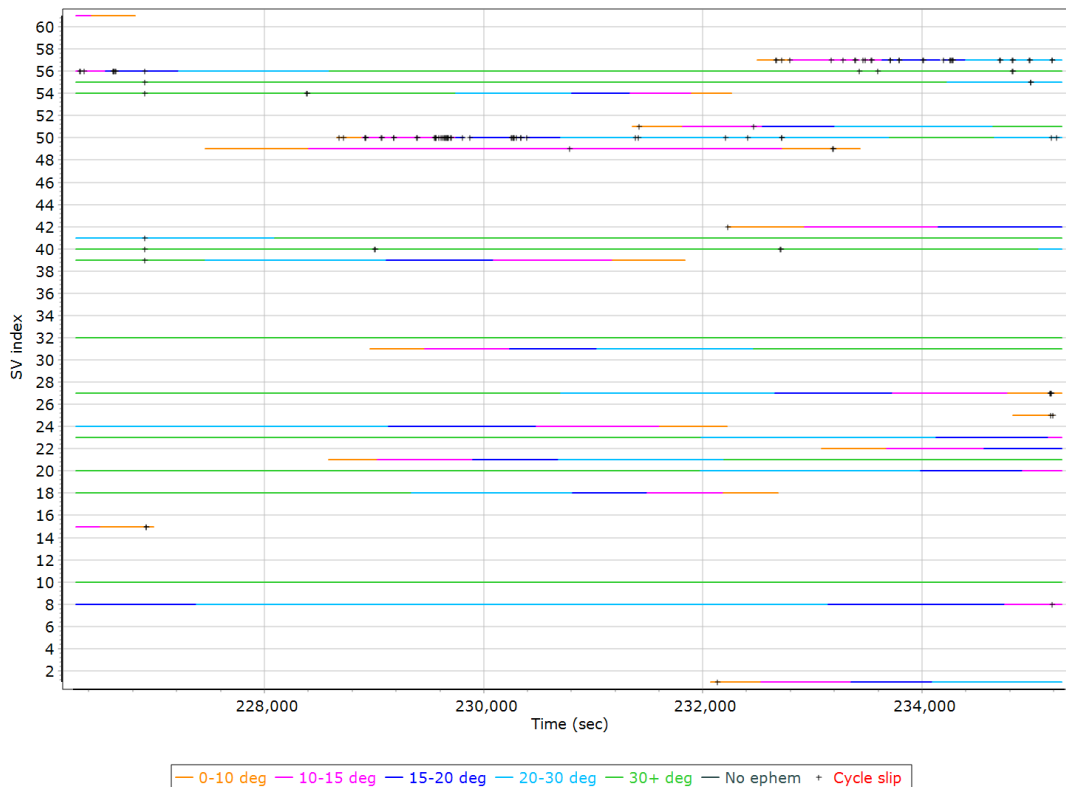
Rover Data QC

Raw IMU Import QC Summary

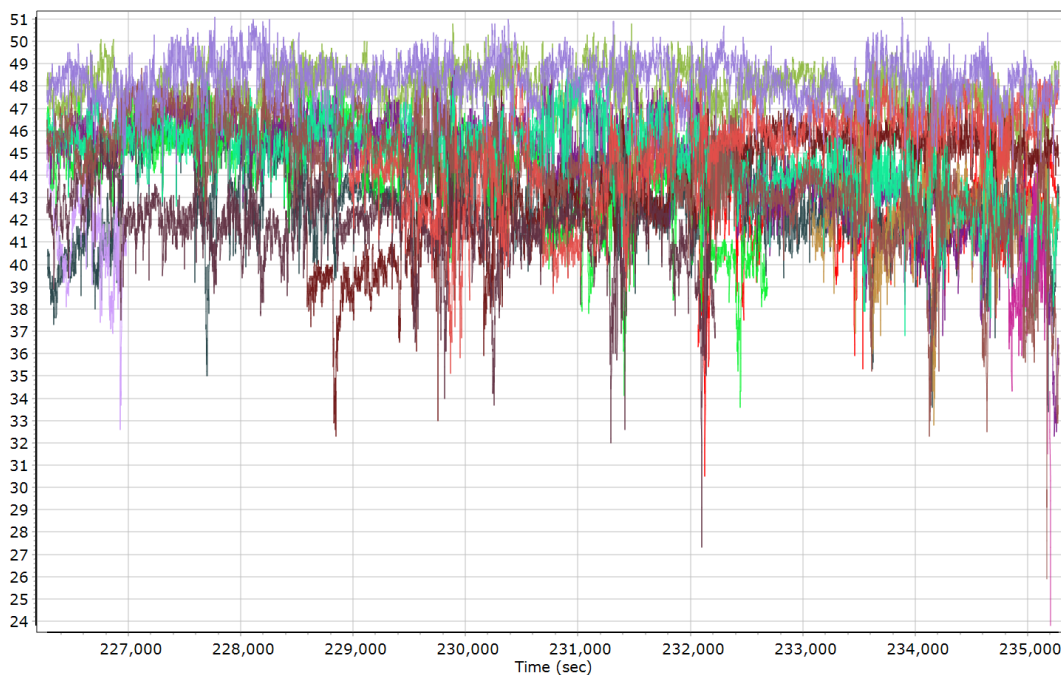
IMU data input file	imu_201208_A_5060420_nad2011_FINAL.dat
IMU data check log file	imudt_201208_A_5060420_nad2011_FINAL.log
IMU Records Processed	1798946
Termination Status	Normal
IMU Anomalies	0

Primary Observables & Satellite Data

GPS/GLONASS L1 Satellite Lock/Elevation

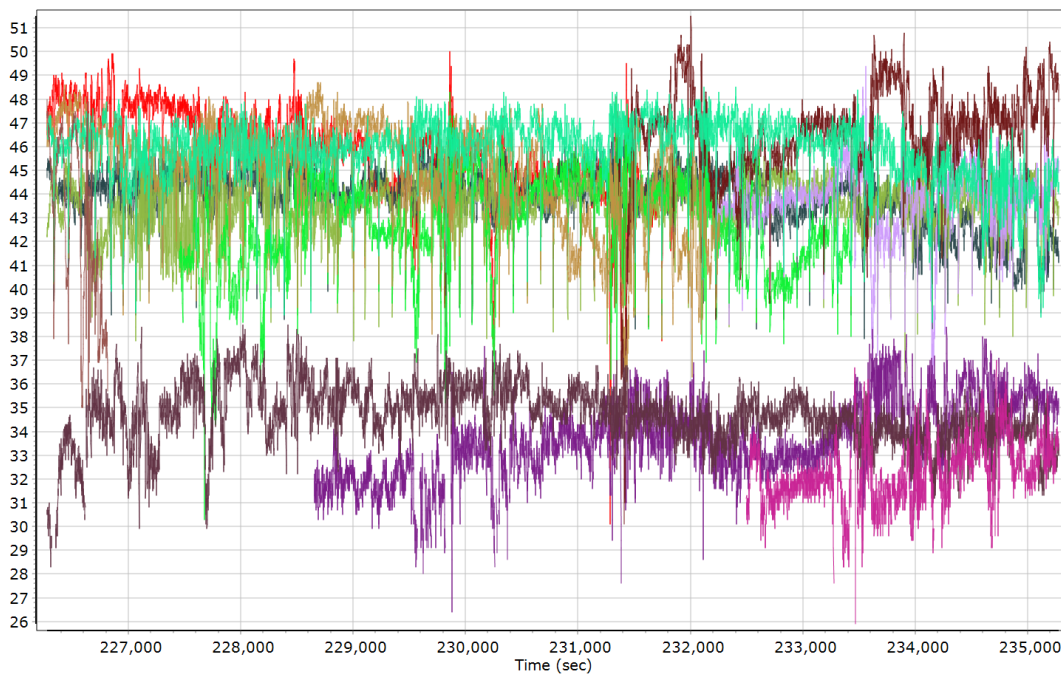


GPS L1 SNR



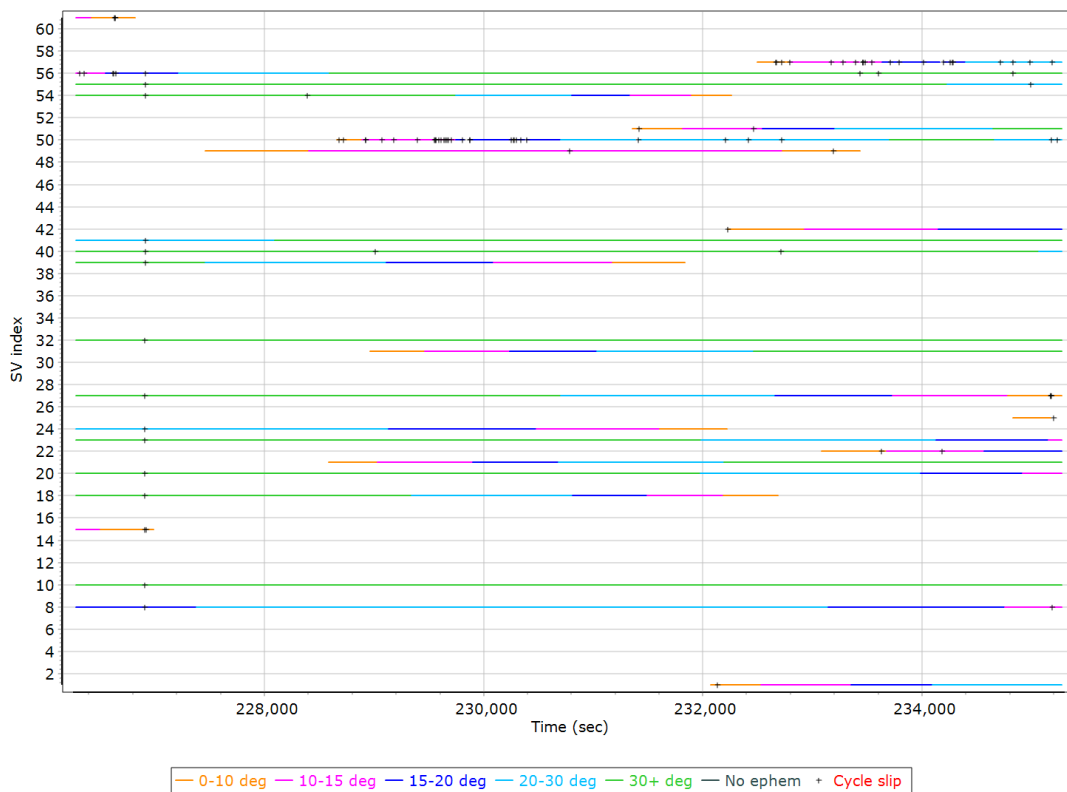
- | | | | |
|---------------------------|---------------------------|---------------------------|---------------------------|
| GPS PRN 01 L1 SNR (dB/Hz) | GPS PRN 08 L1 SNR (dB/Hz) | GPS PRN 10 L1 SNR (dB/Hz) | GPS PRN 15 L1 SNR (dB/Hz) |
| GPS PRN 18 L1 SNR (dB/Hz) | GPS PRN 20 L1 SNR (dB/Hz) | GPS PRN 21 L1 SNR (dB/Hz) | GPS PRN 22 L1 SNR (dB/Hz) |
| GPS PRN 23 L1 SNR (dB/Hz) | GPS PRN 24 L1 SNR (dB/Hz) | GPS PRN 25 L1 SNR (dB/Hz) | GPS PRN 27 L1 SNR (dB/Hz) |
| GPS PRN 31 L1 SNR (dB/Hz) | GPS PRN 32 L1 SNR (dB/Hz) | | |

GLONASS L1 SNR

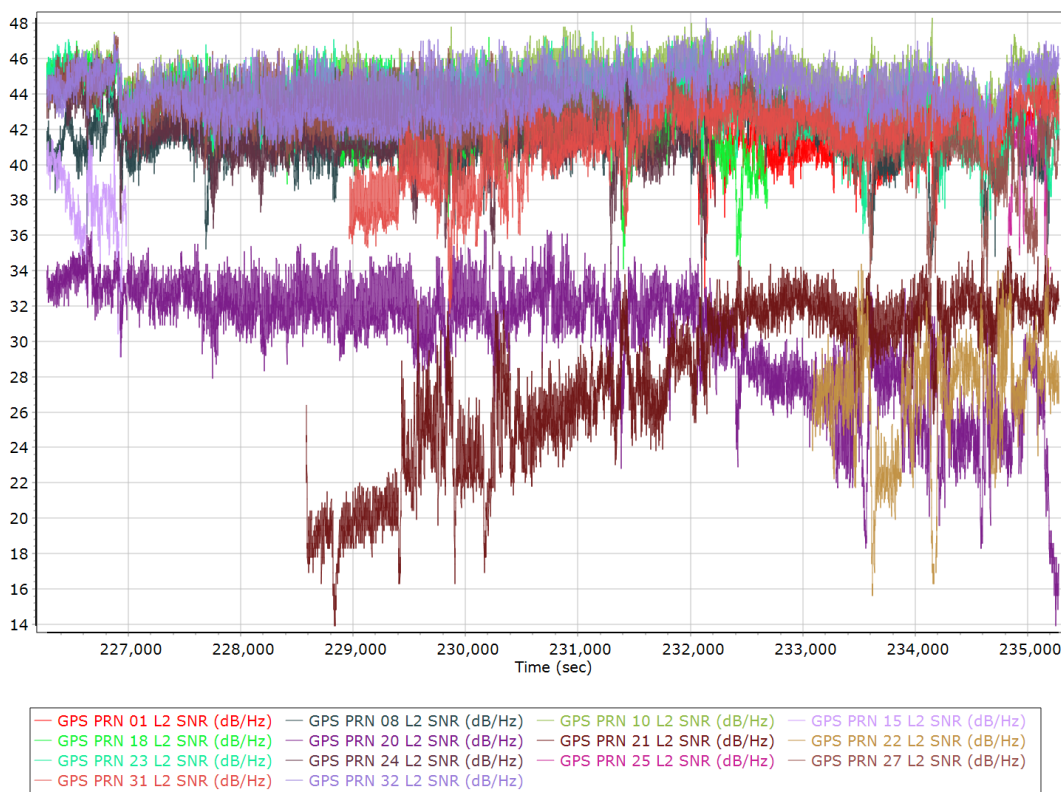


- | | | |
|---------------------------|---------------------------|---------------------------|
| GLONASS 02 L1 SNR (dB/Hz) | GLONASS 03 L1 SNR (dB/Hz) | GLONASS 04 L1 SNR (dB/Hz) |
| GLONASS 05 L1 SNR (dB/Hz) | GLONASS 12 L1 SNR (dB/Hz) | GLONASS 13 L1 SNR (dB/Hz) |
| GLONASS 14 L1 SNR (dB/Hz) | GLONASS 17 L1 SNR (dB/Hz) | GLONASS 18 L1 SNR (dB/Hz) |
| GLONASS 19 L1 SNR (dB/Hz) | GLONASS 20 L1 SNR (dB/Hz) | GLONASS 24 L1 SNR (dB/Hz) |

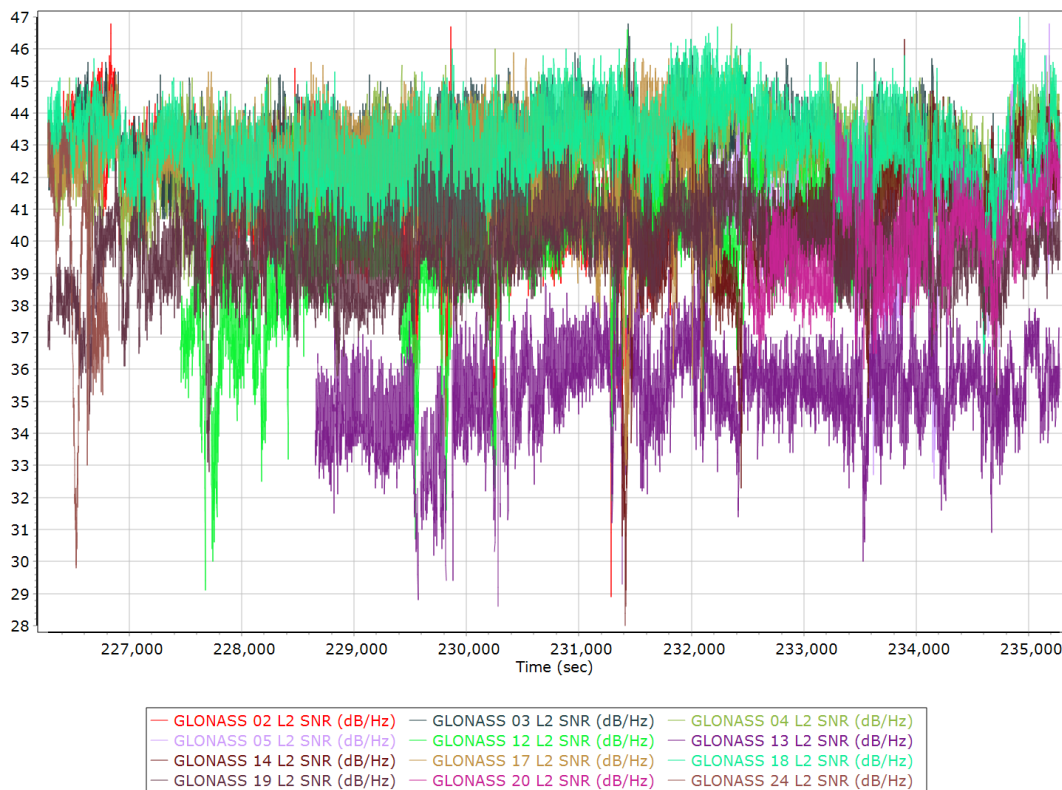
GPS/GLONASS L2 Satellite Lock/Elevation



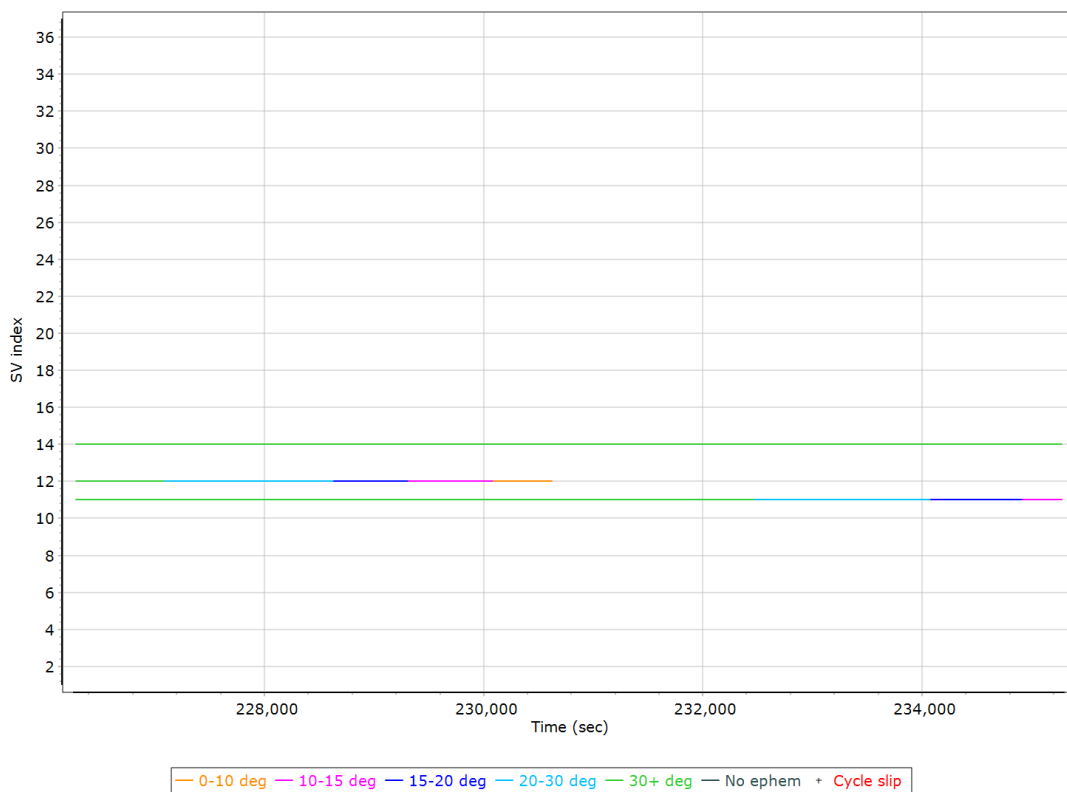
GPS L2 SNR



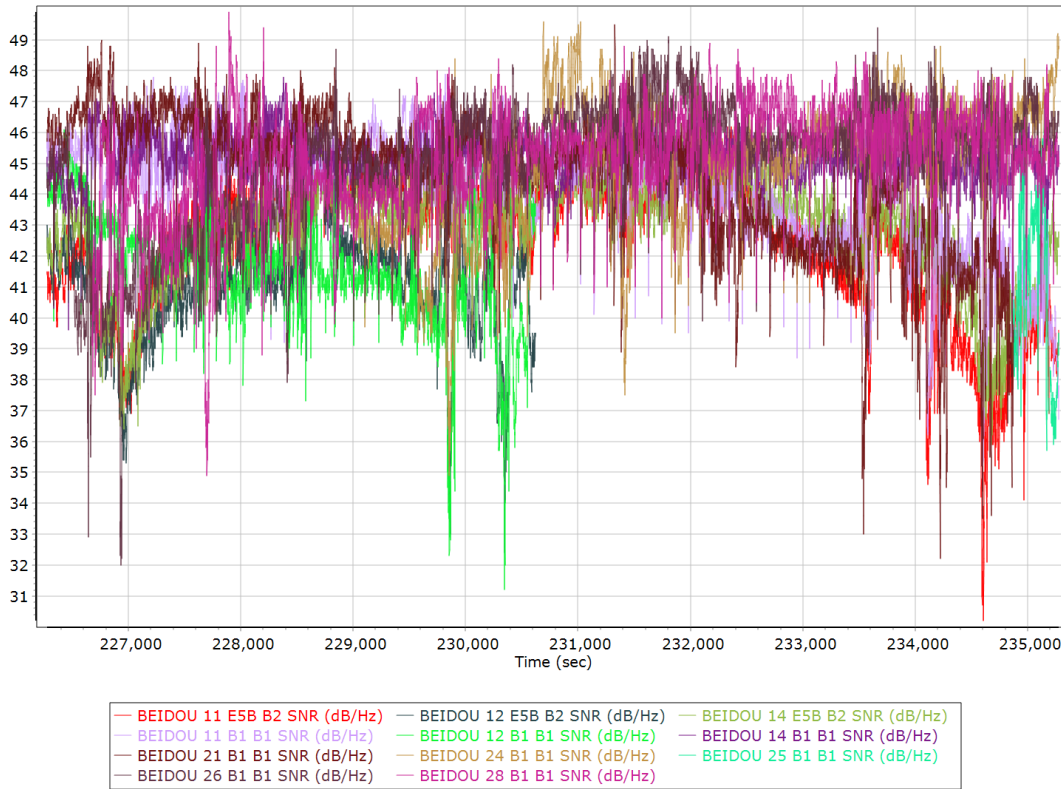
GLONASS L2 SNR



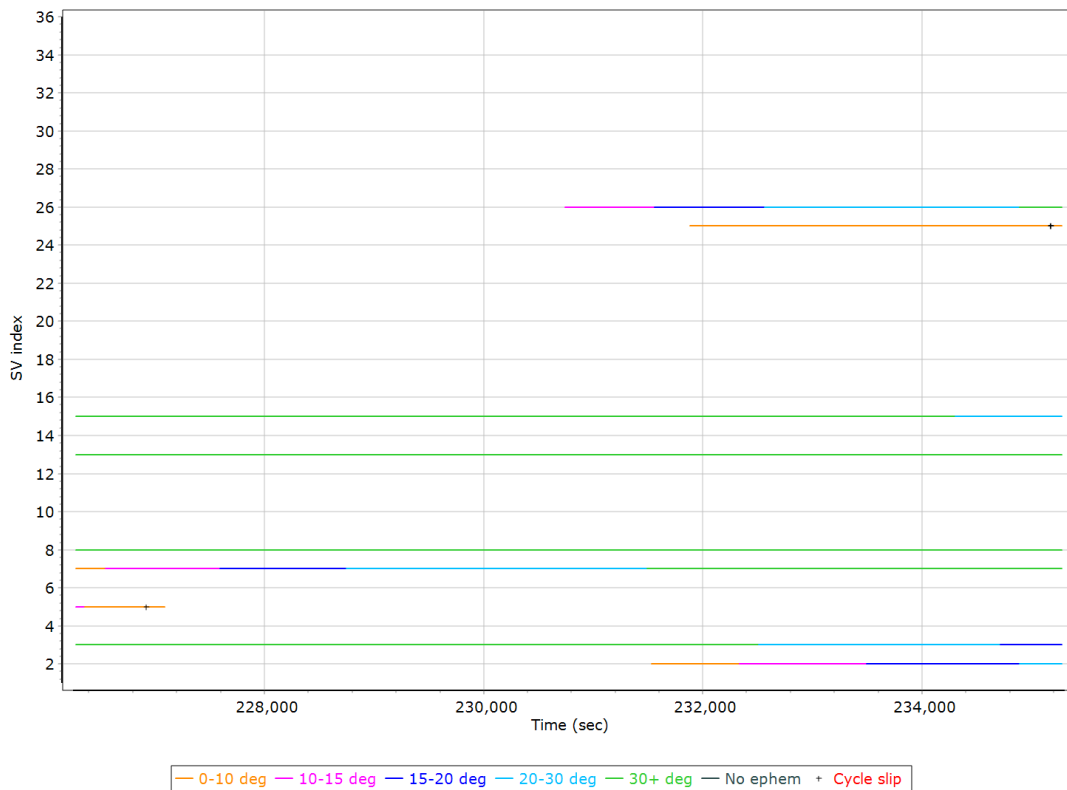
BEIDOU Satellite Lock/Elevation



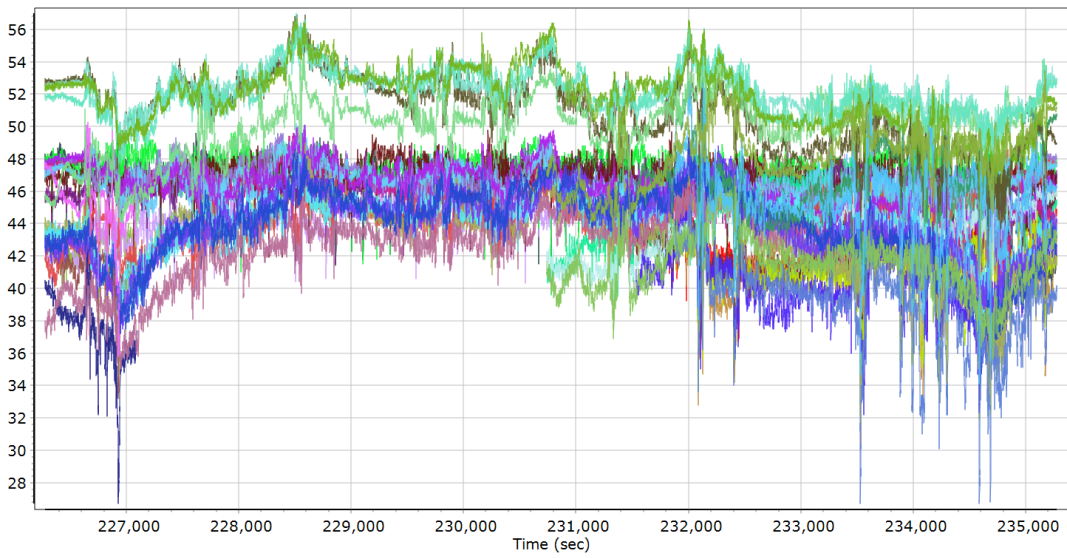
BEIDOU SNR



GALILEO Satellite Lock/Elevation



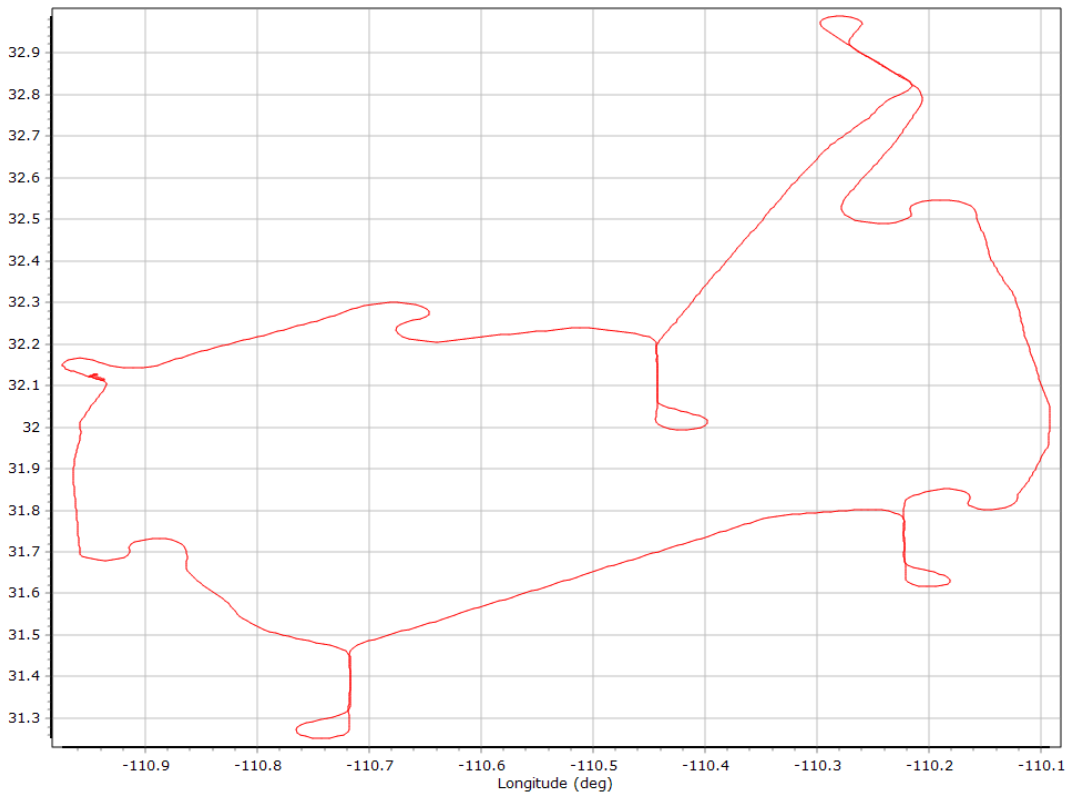
GALILEO SNR



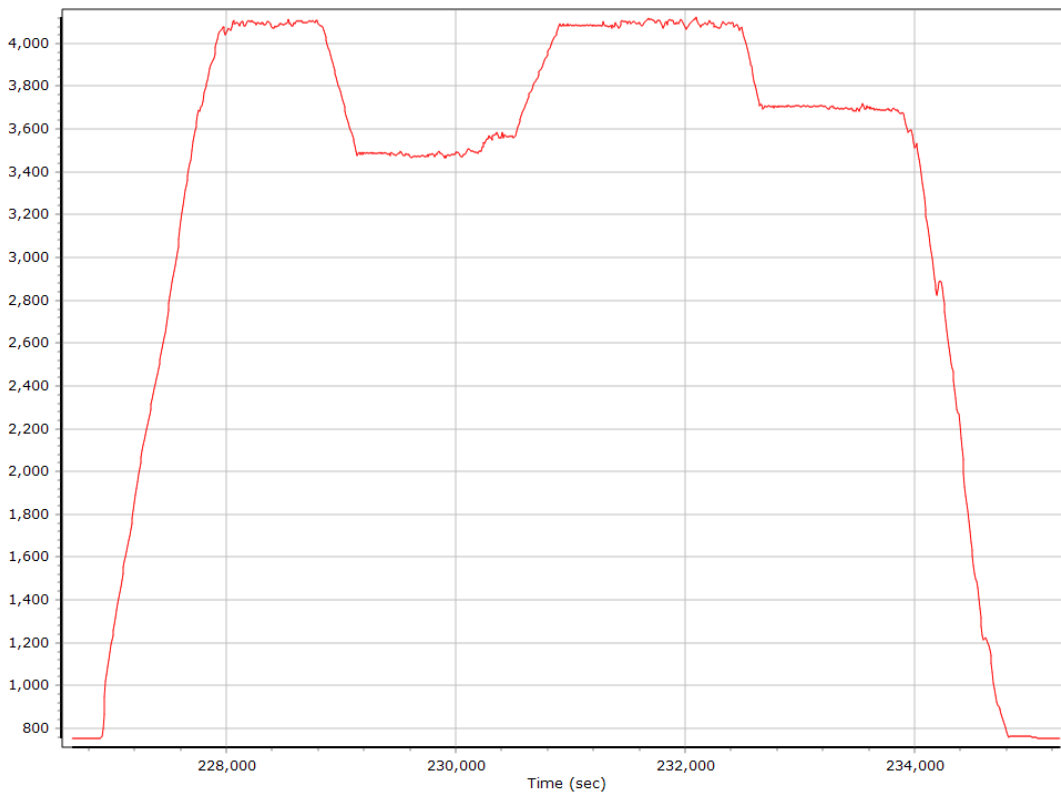
— GALILEO 02 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 03 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 05 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 07 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 08 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 13 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 15 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 25 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 26 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 02 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 03 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 05 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 07 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 08 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 13 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 15 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 25 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 26 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 02 E5B BPSK10_PD SNR (dB/Hz)	— GALILEO 03 E5B BPSK10_PD SNR (dB/Hz)

Smoothed Trajectory Information

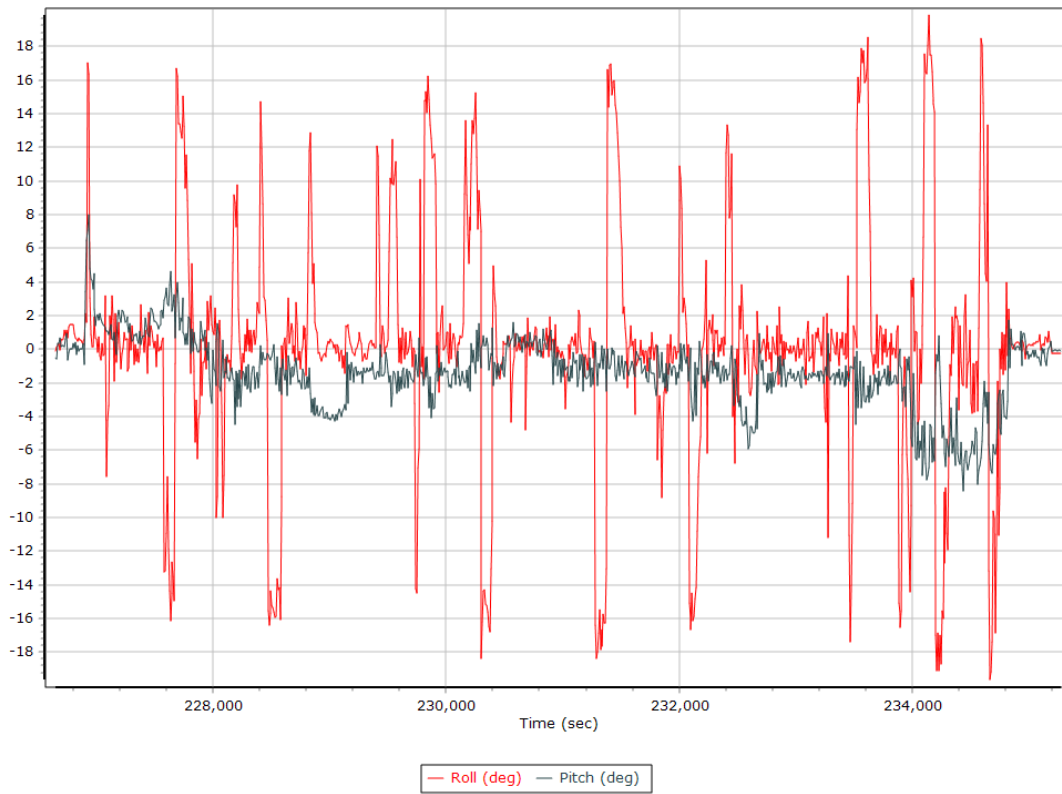
Top View



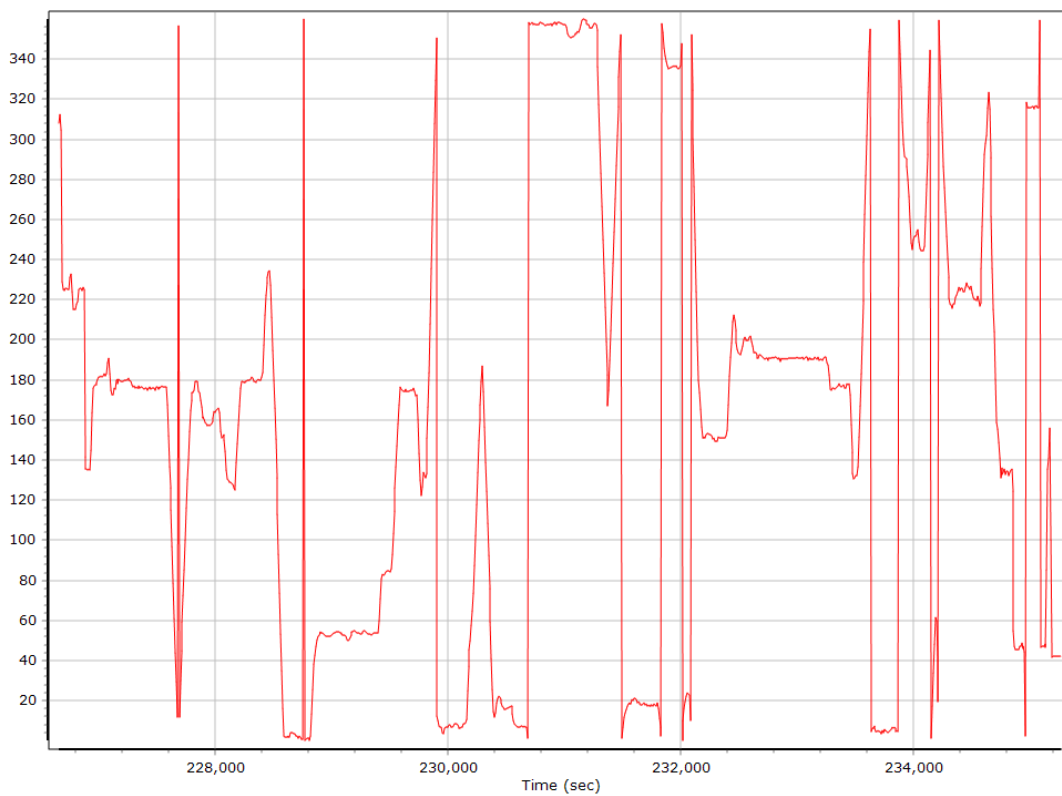
Altitude



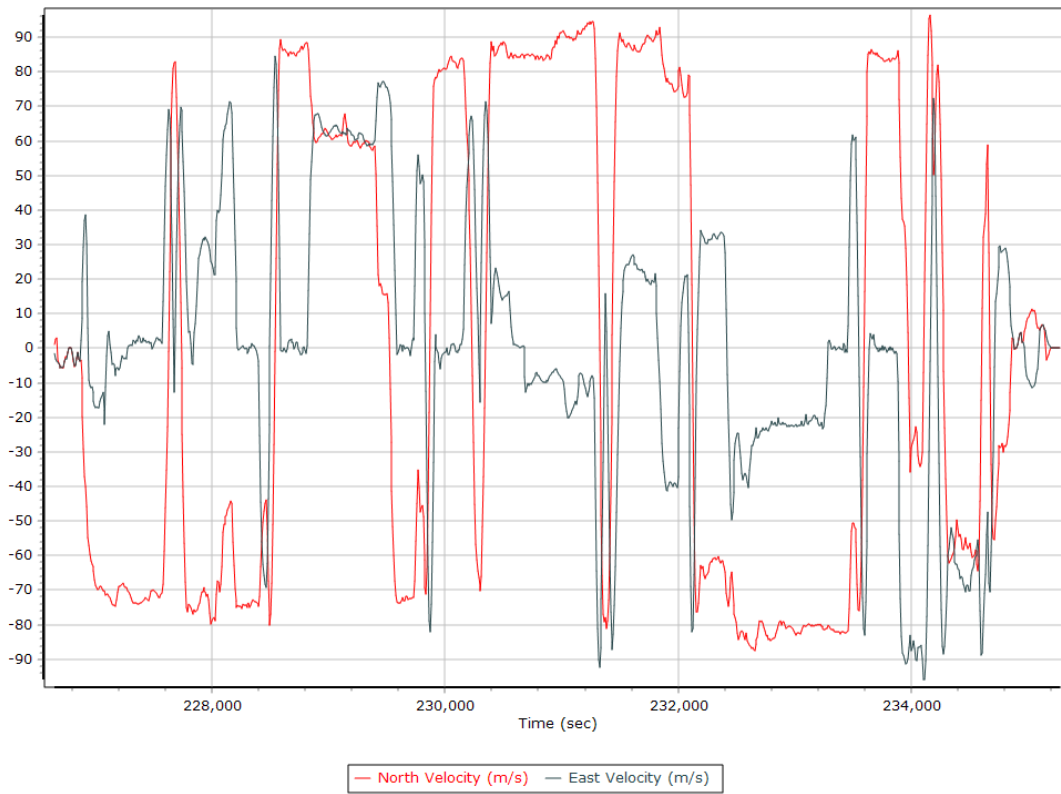
Roll/Pitch



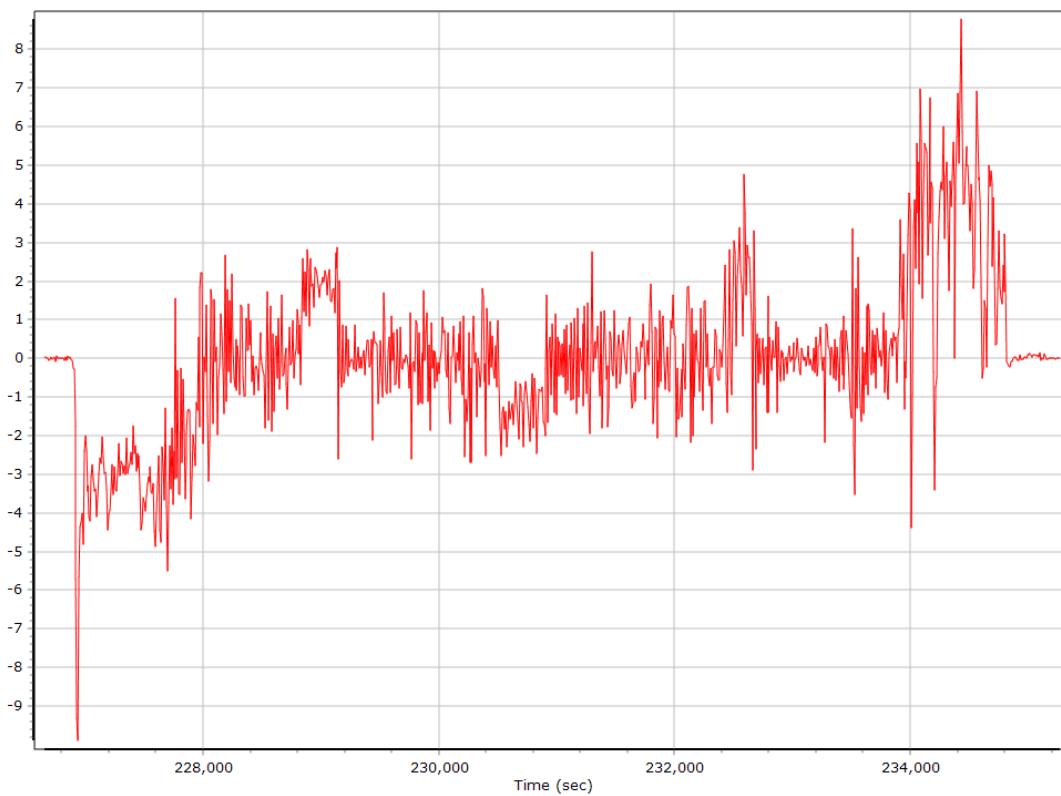
Heading



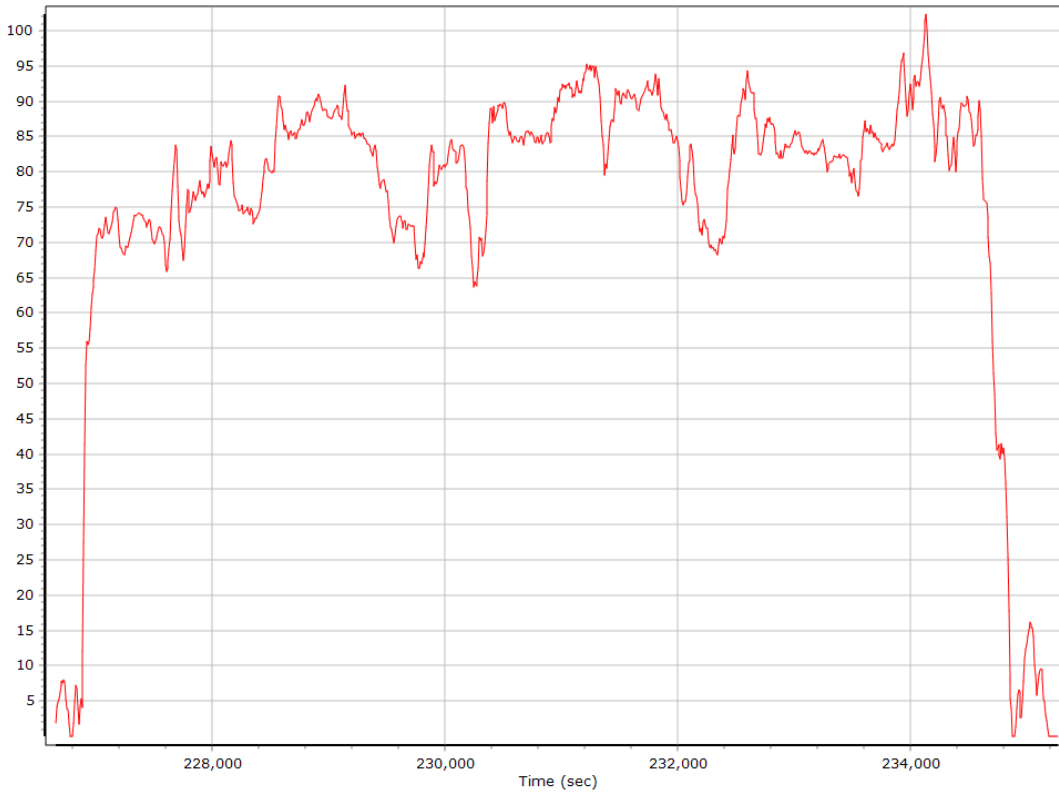
North/East Velocity



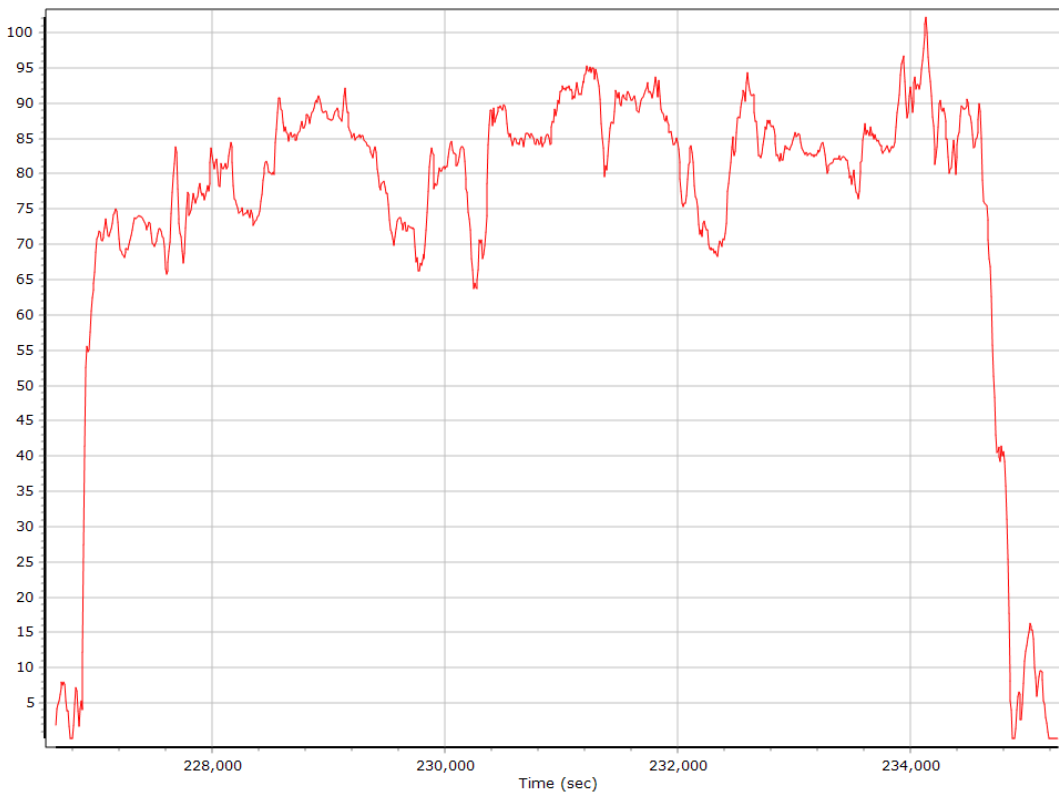
Down Velocity



Total Speed



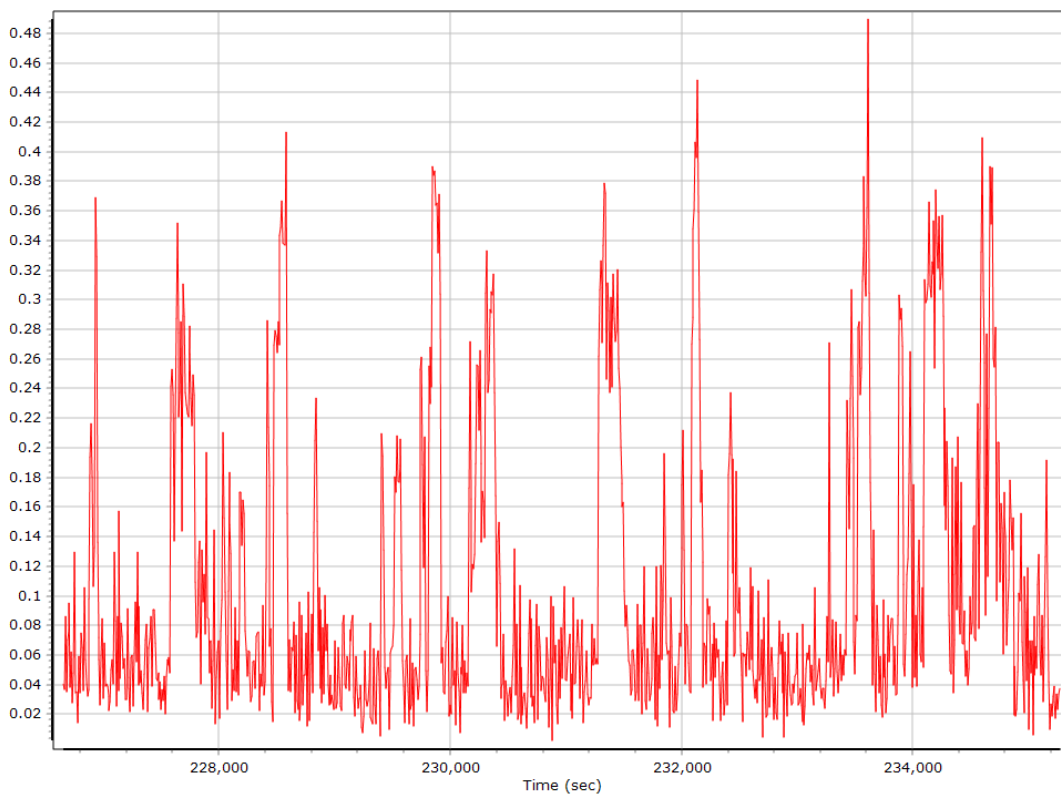
Ground Speed



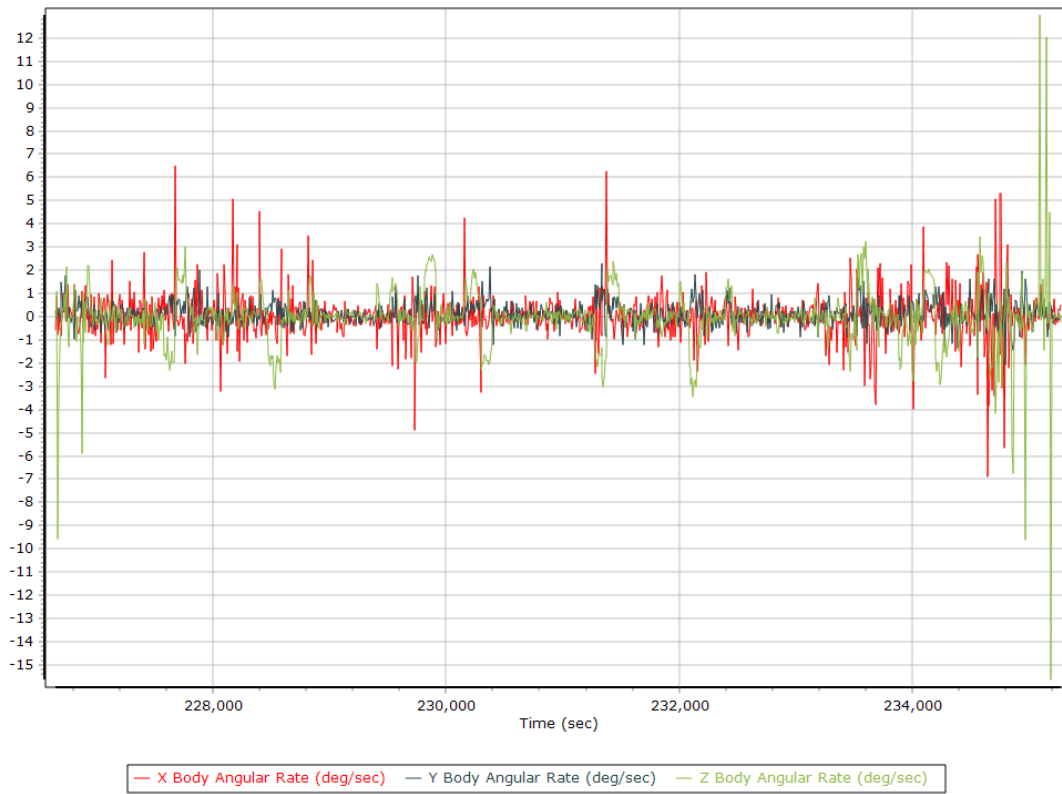
Body Acceleration



Total Body Acceleration



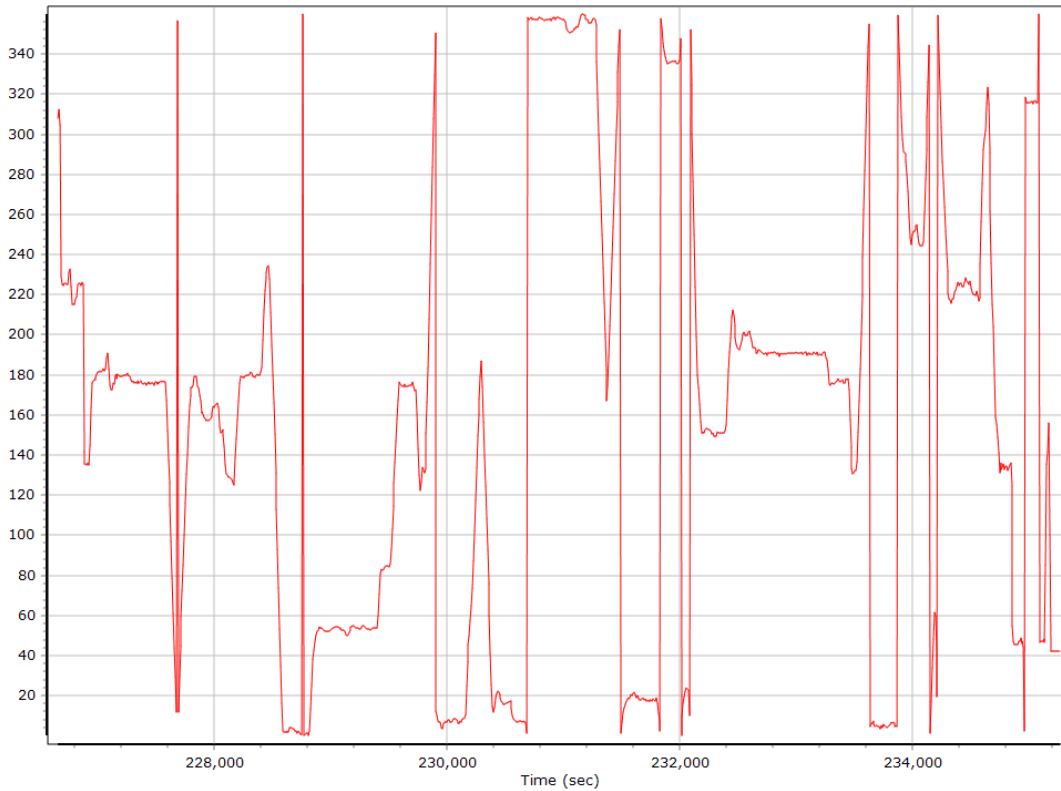
Body Angular Rate



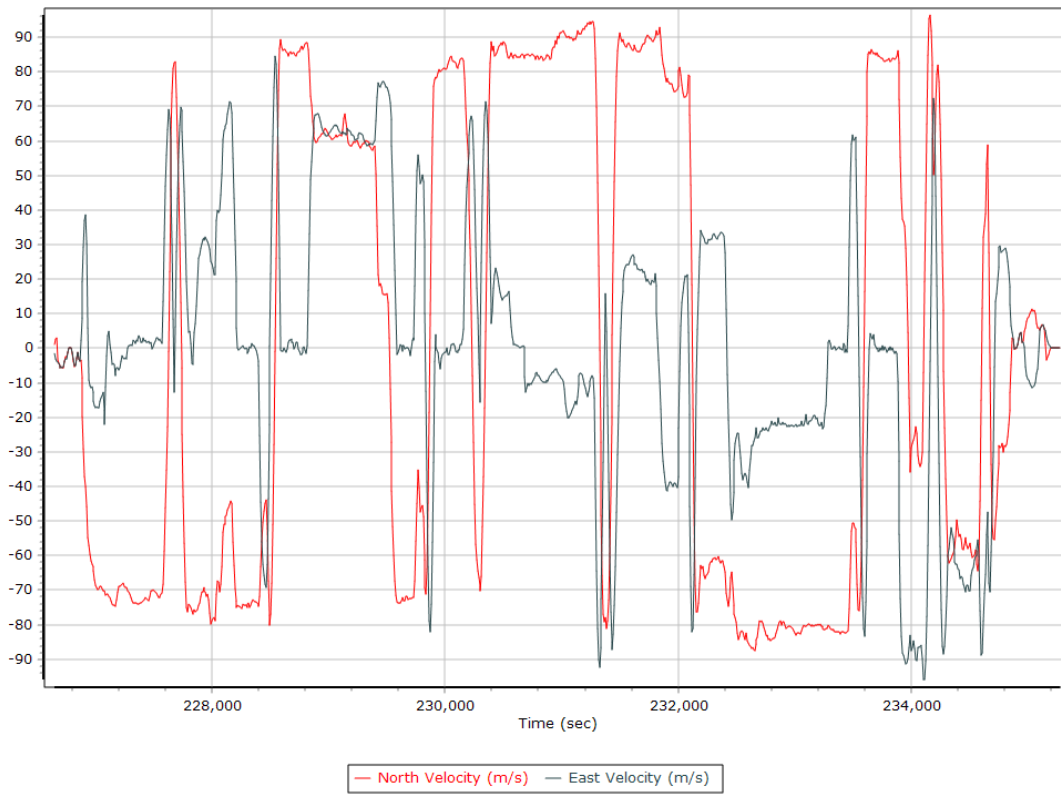
Roll/Pitch



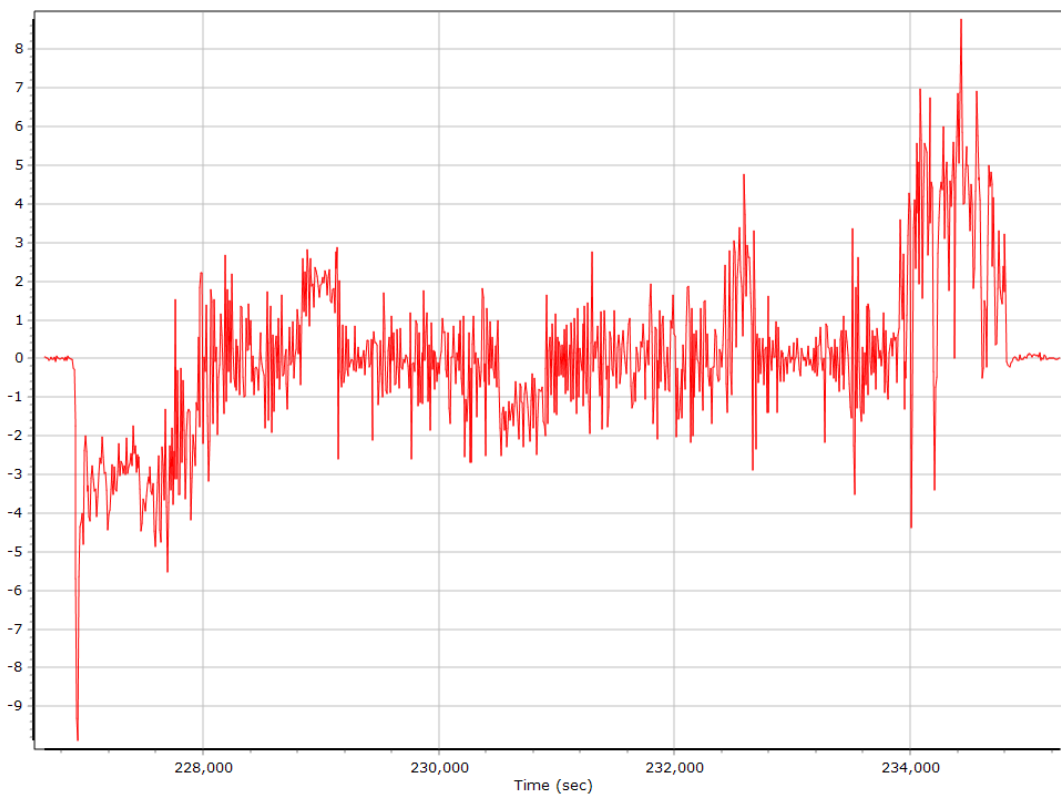
Heading



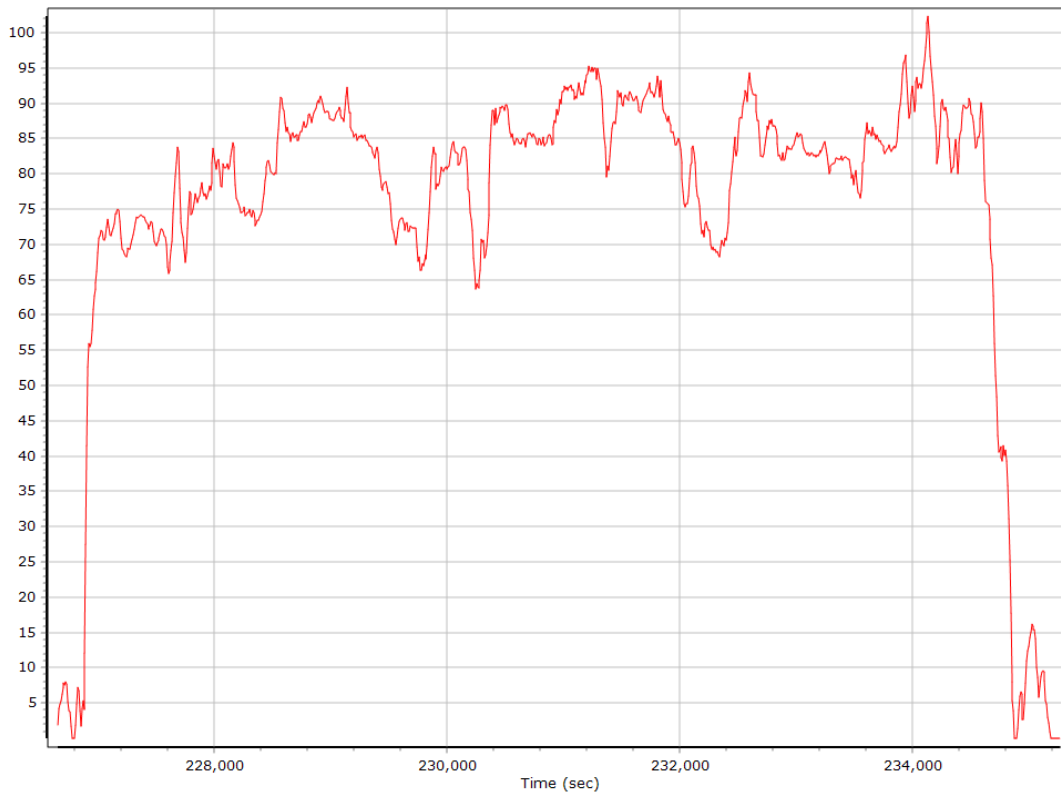
North/East Velocity



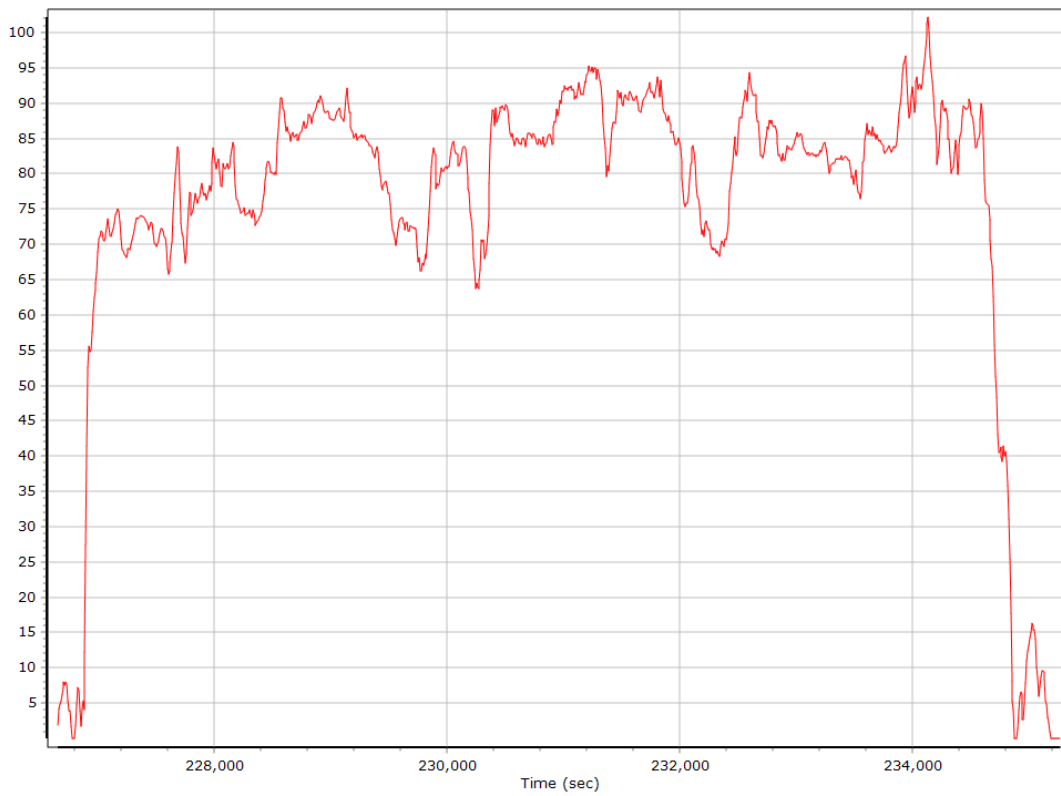
Down Velocity



Total Speed



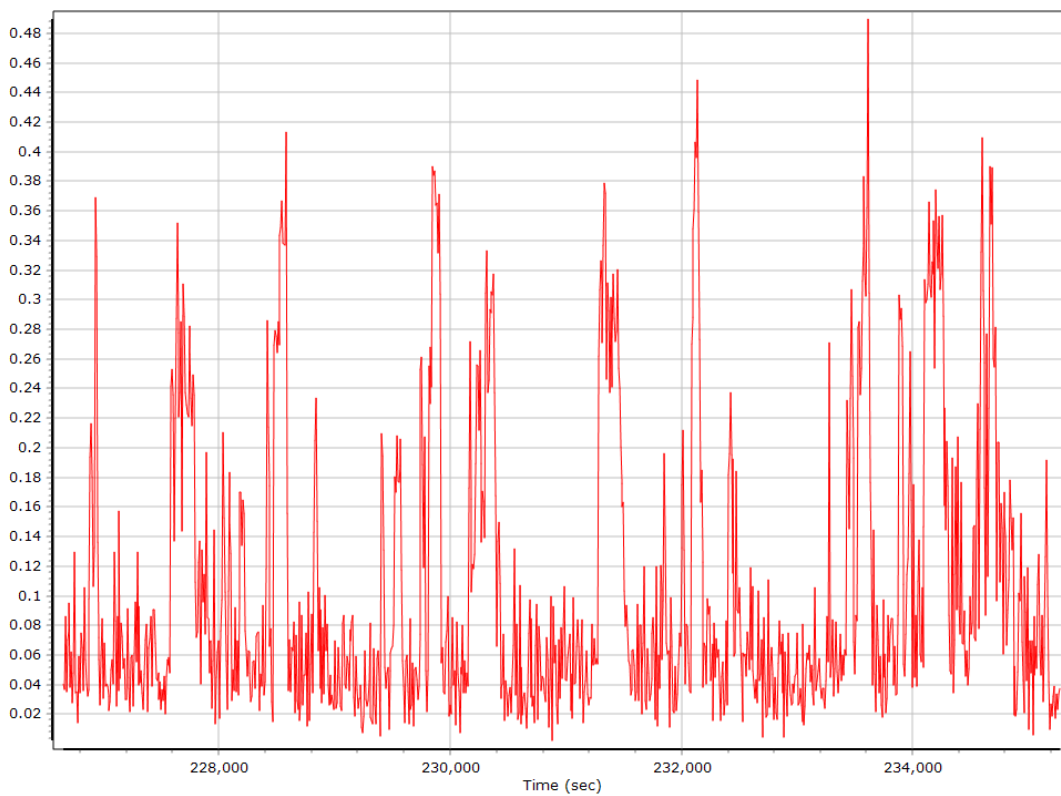
Ground Speed



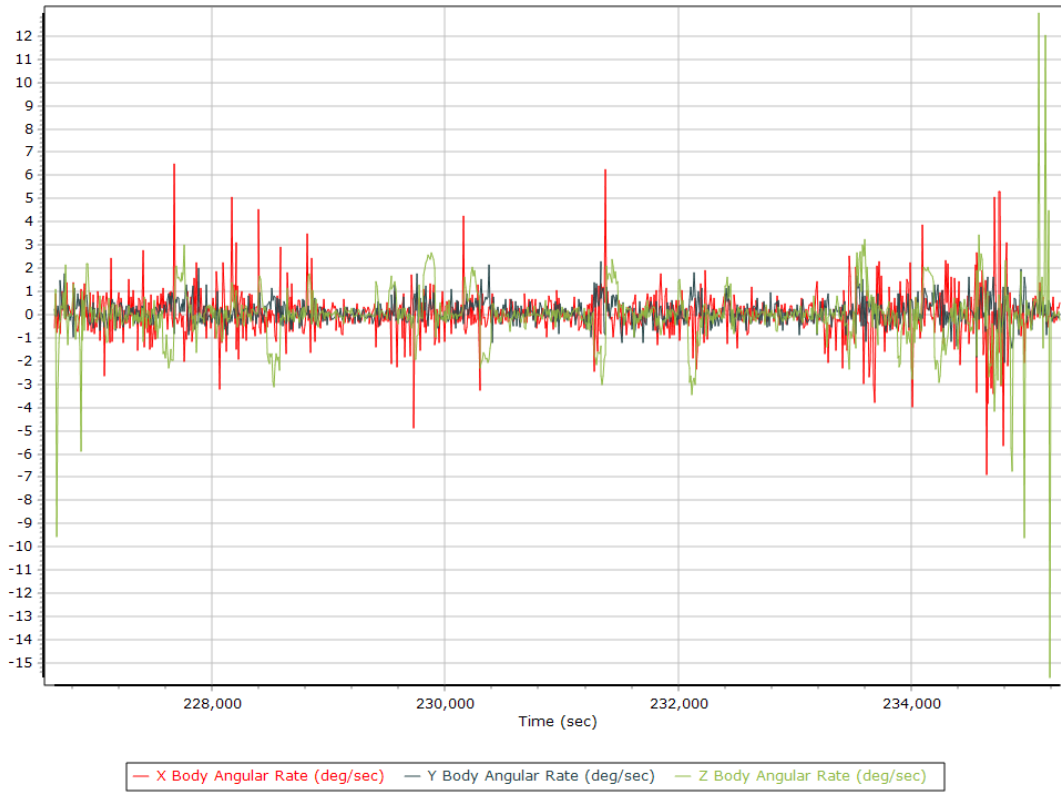
Body Acceleration



Total Body Acceleration



Body Angular Rate

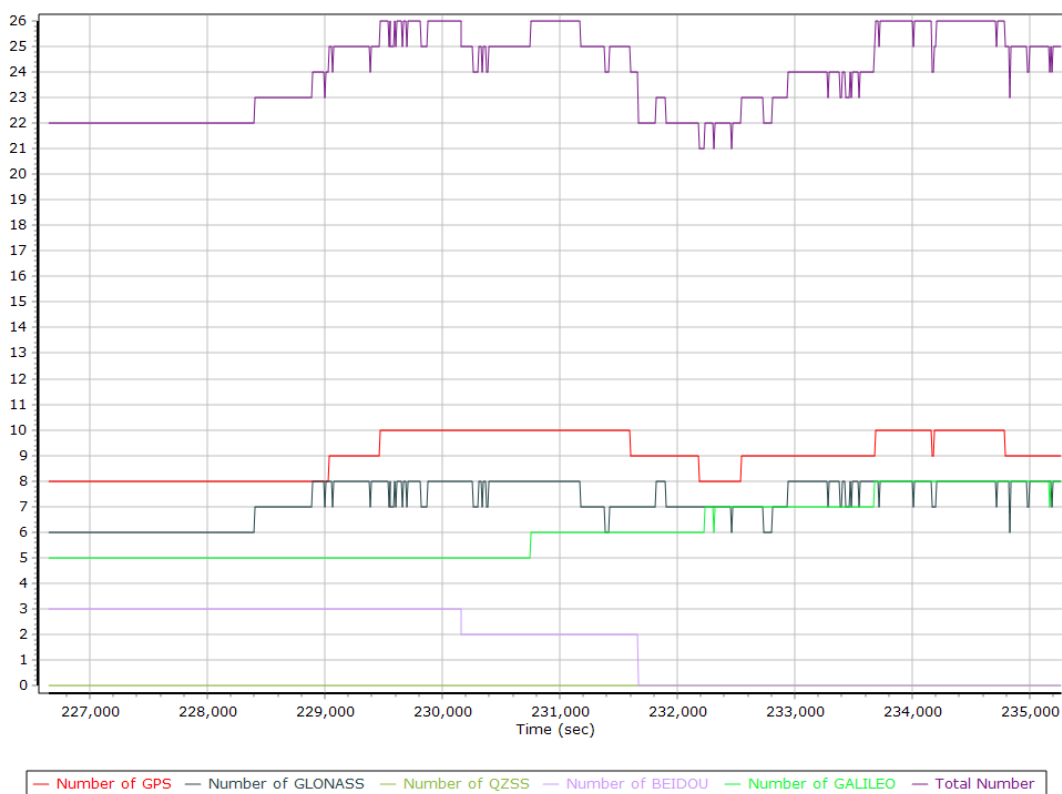


GNSS QC

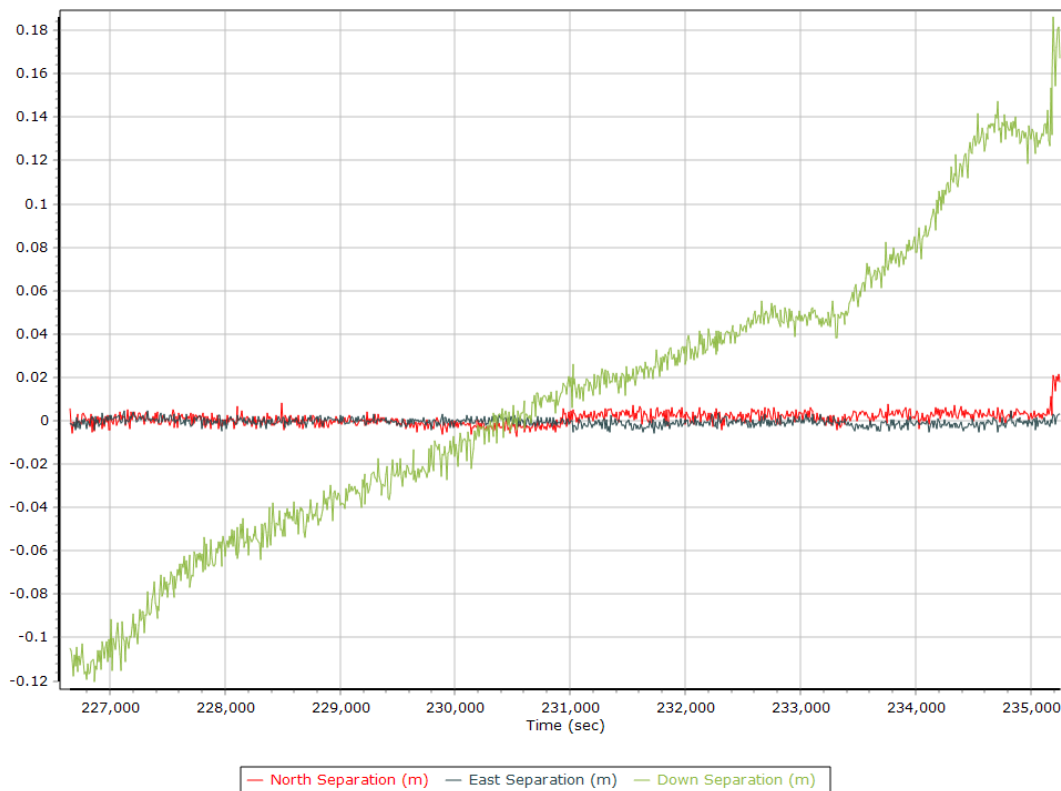
GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	8	10	9
Number of GLONASS SV	0	8	7
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	3	2
Number of GALILEO SV	5	8	6
Total number of SV	13	26	24
PDOP	1.00	1.59	1.11
QC Solution Gaps	0.00	0.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	8983.00	0.00	0.00
Percentage	100.00	0.00	0.00

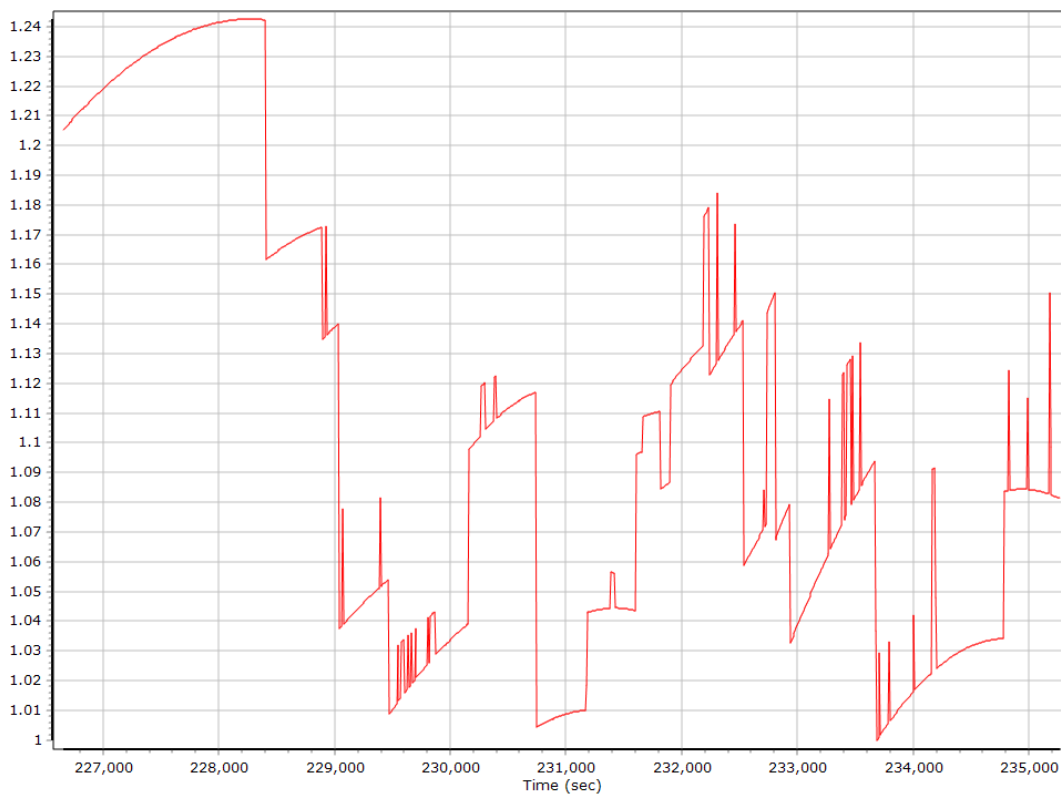
Num SVs in solution



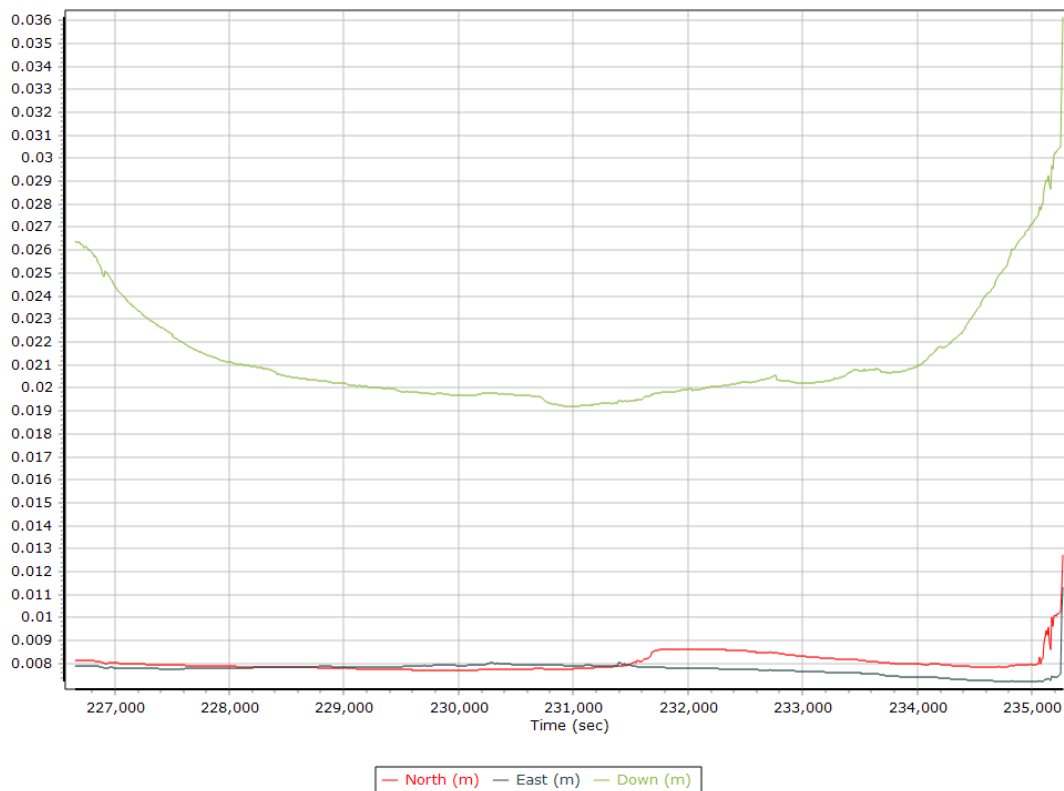
Forward/Reverse Separation



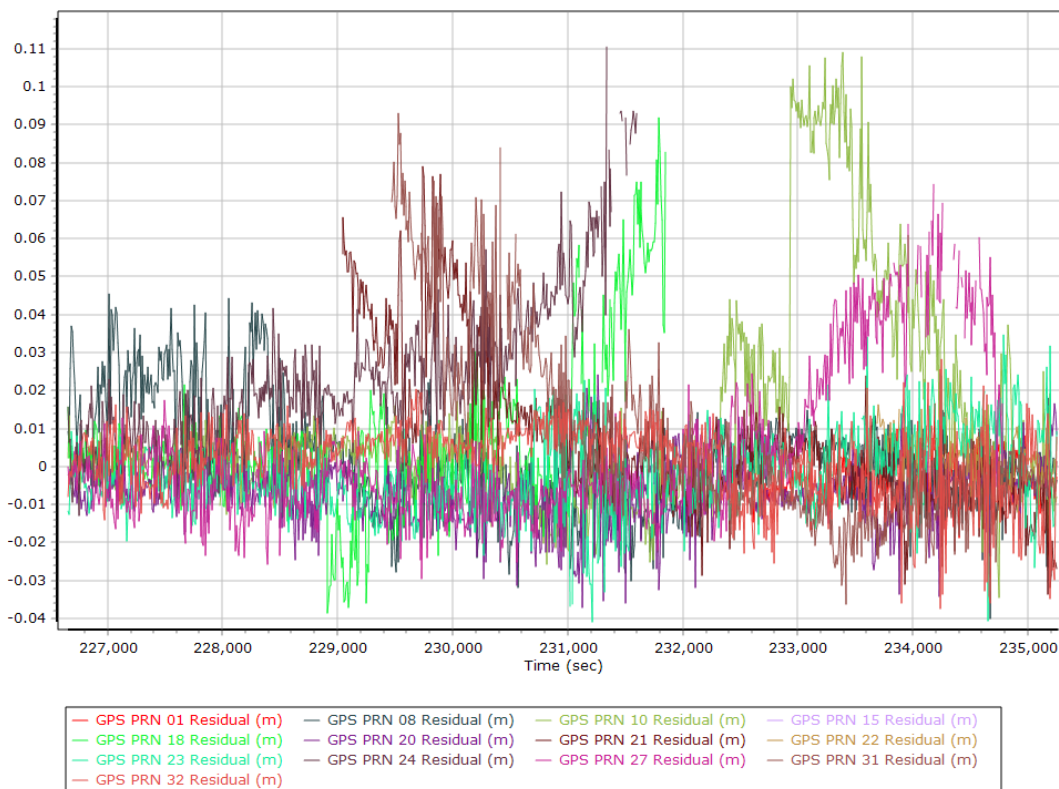
PDOP



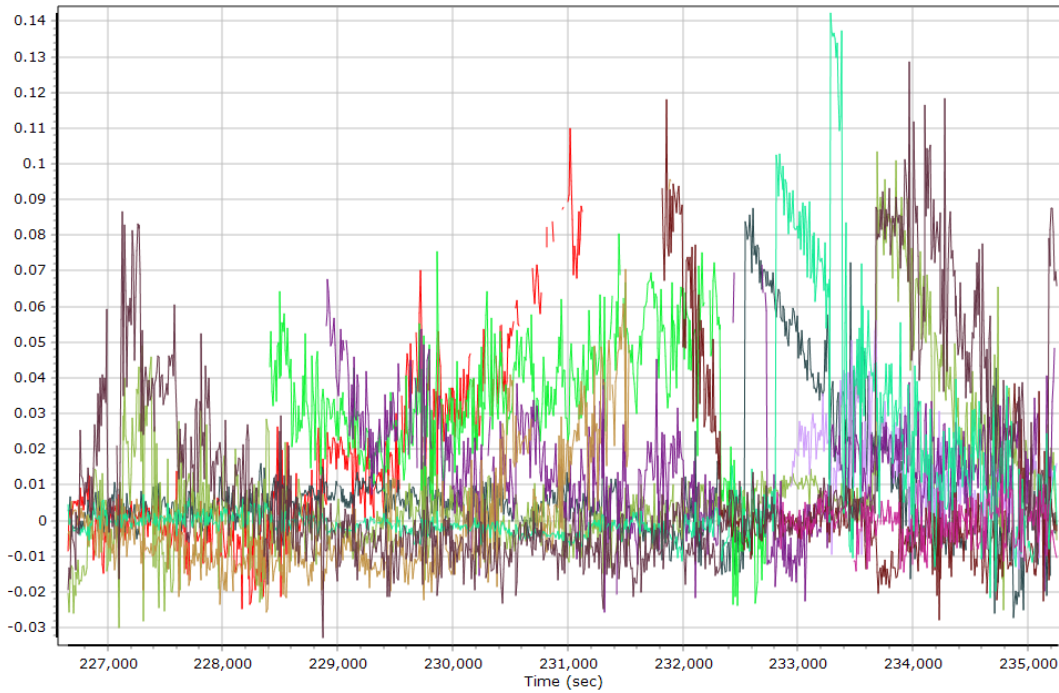
Estimated Position Accuracy



GPS Residuals

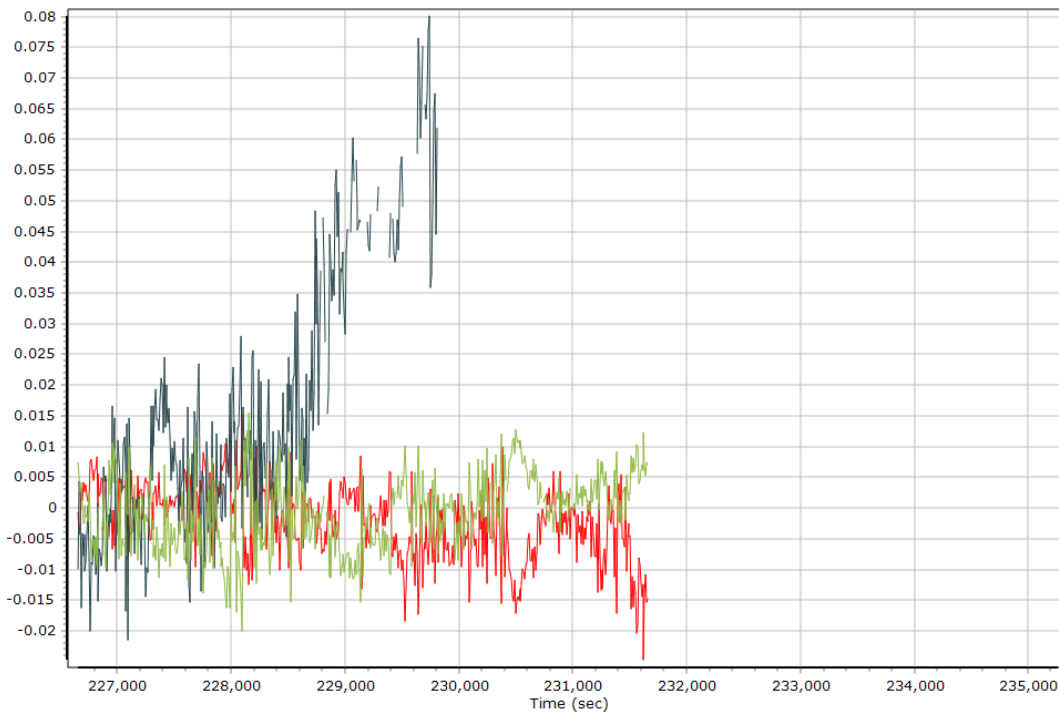


GLONASS Residuals



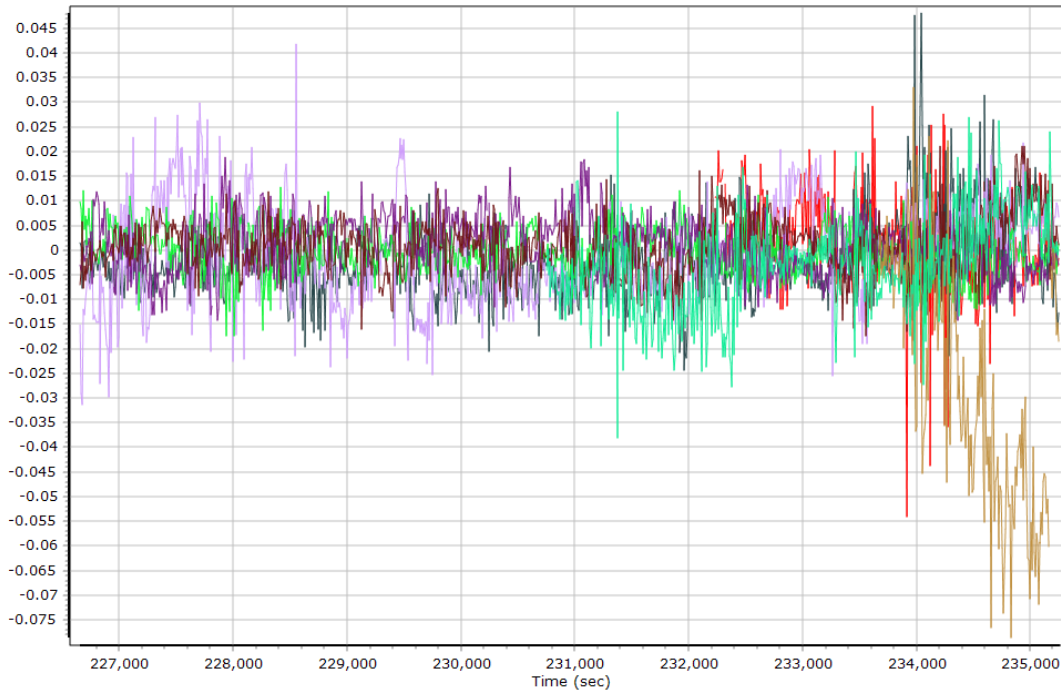
- | | | | |
|-------------------------|-------------------------|-------------------------|-------------------------|
| GLONASS 02 Residual (m) | GLONASS 03 Residual (m) | GLONASS 04 Residual (m) | GLONASS 05 Residual (m) |
| GLONASS 12 Residual (m) | GLONASS 13 Residual (m) | GLONASS 14 Residual (m) | GLONASS 17 Residual (m) |
| GLONASS 18 Residual (m) | GLONASS 19 Residual (m) | GLONASS 20 Residual (m) | GLONASS 24 Residual (m) |

BEIDOU Residuals



- | | | | |
|------------------------|------------------------|------------------------|------------------------|
| BEIDOU 11 Residual (m) | BEIDOU 12 Residual (m) | BEIDOU 14 Residual (m) | BEIDOU 21 Residual (m) |
| BEIDOU 24 Residual (m) | BEIDOU 26 Residual (m) | BEIDOU 28 Residual (m) | |

GALILEO Residuals



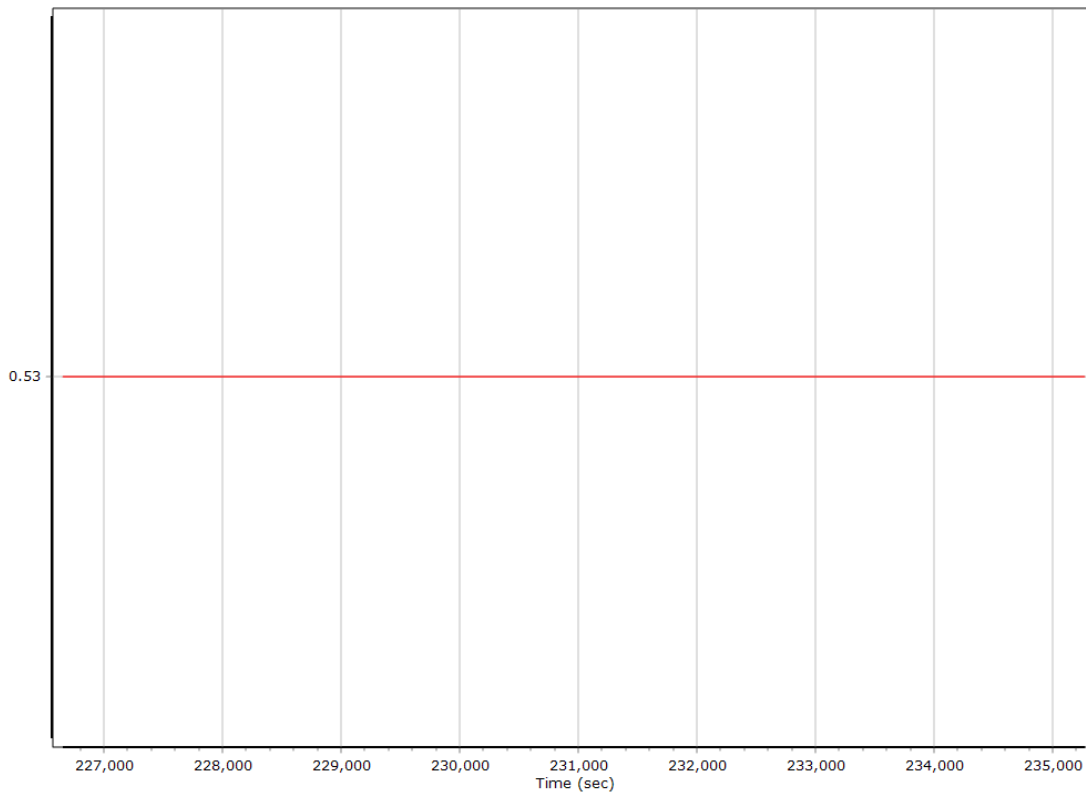
GNSS-Inertial Processor Configuration

Processing mode	IN-Fusion PP-RTX		
Stabilized mount	False		
Processing start time	226280.000 (12/8/2020 2:51:20 PM)		
Processing end time	235275.000 (12/8/2020 5:21:15 PM)		
Initial attitude source	Real-Time VNAV/RNAV Attitude		
IMU Sensor Context	Processing with Onboard IMU		
Reference to IMU lever arm (m)	0.000	0.000	0.000
Reference to IMU mounting angles (deg)	0.000	0.000	-90.000
Reference to Primary GNSS lever arm (m)	0.530	0.205	-1.197
Reference to Primary GNSS lever arm std dev (m)	0.030	0.030	0.030
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

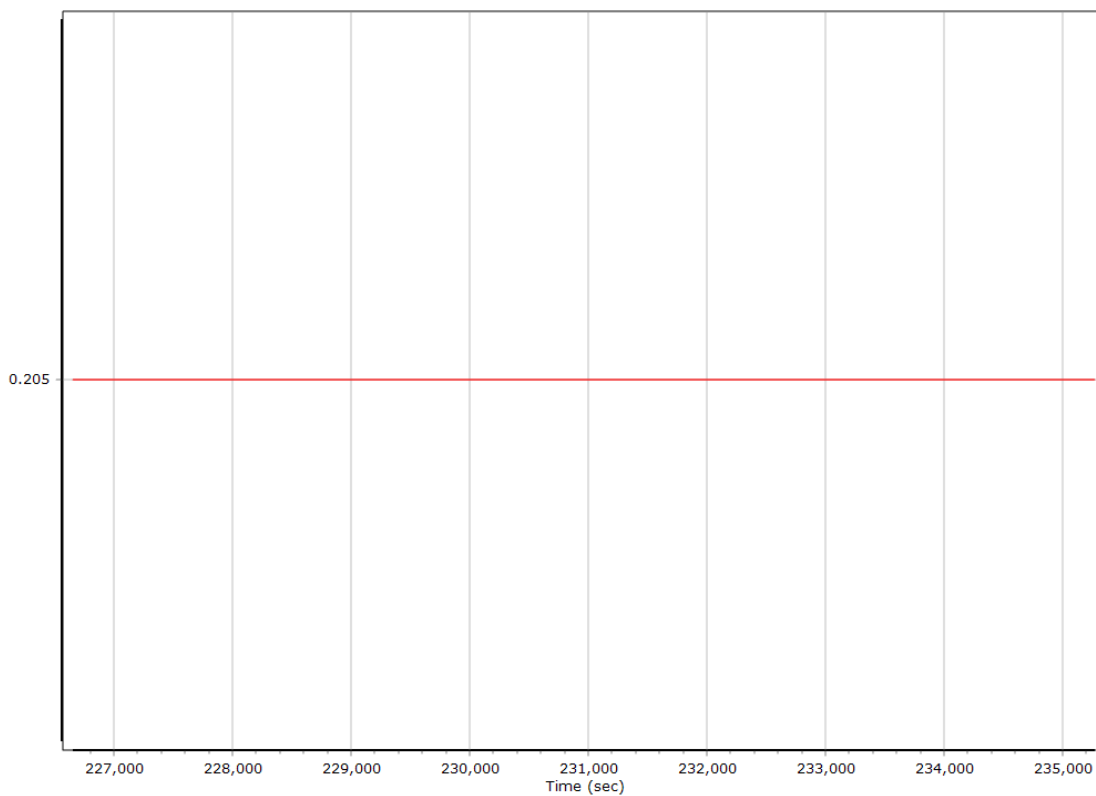
Calibrated Installation Parameters

Reference-Primary GNSS Lever Arm (m)

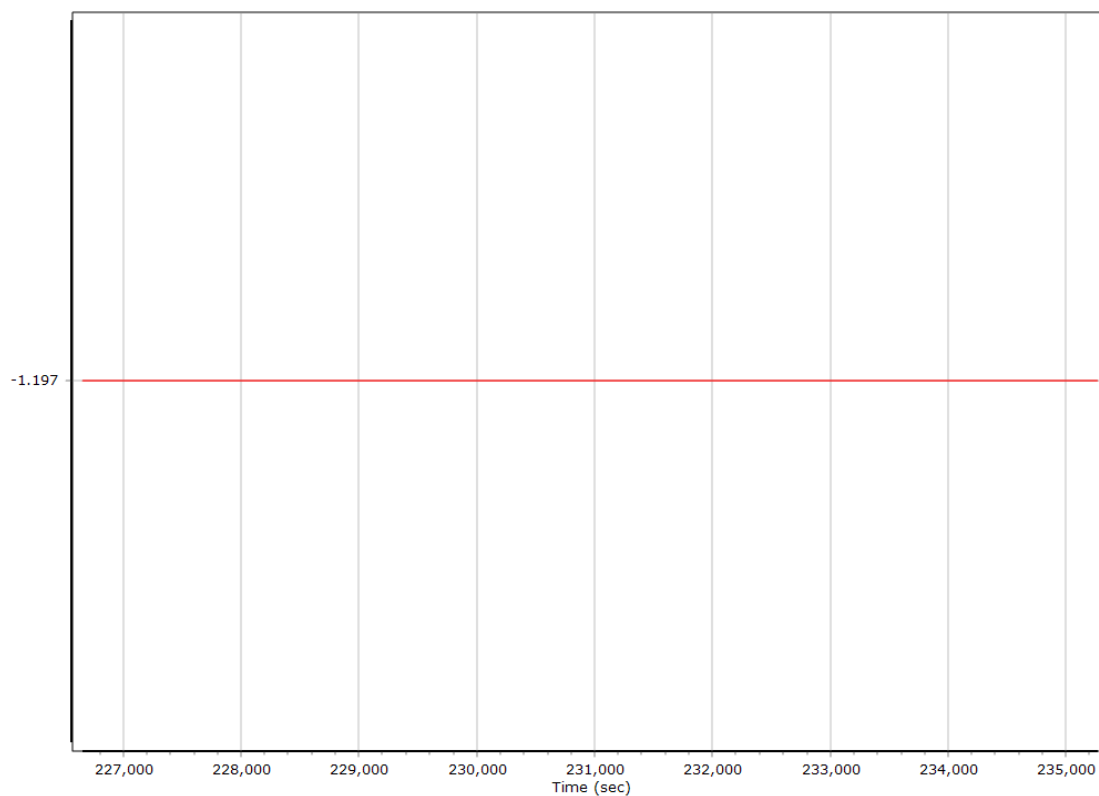
X Reference-Primary GNSS Lever Arm (m)



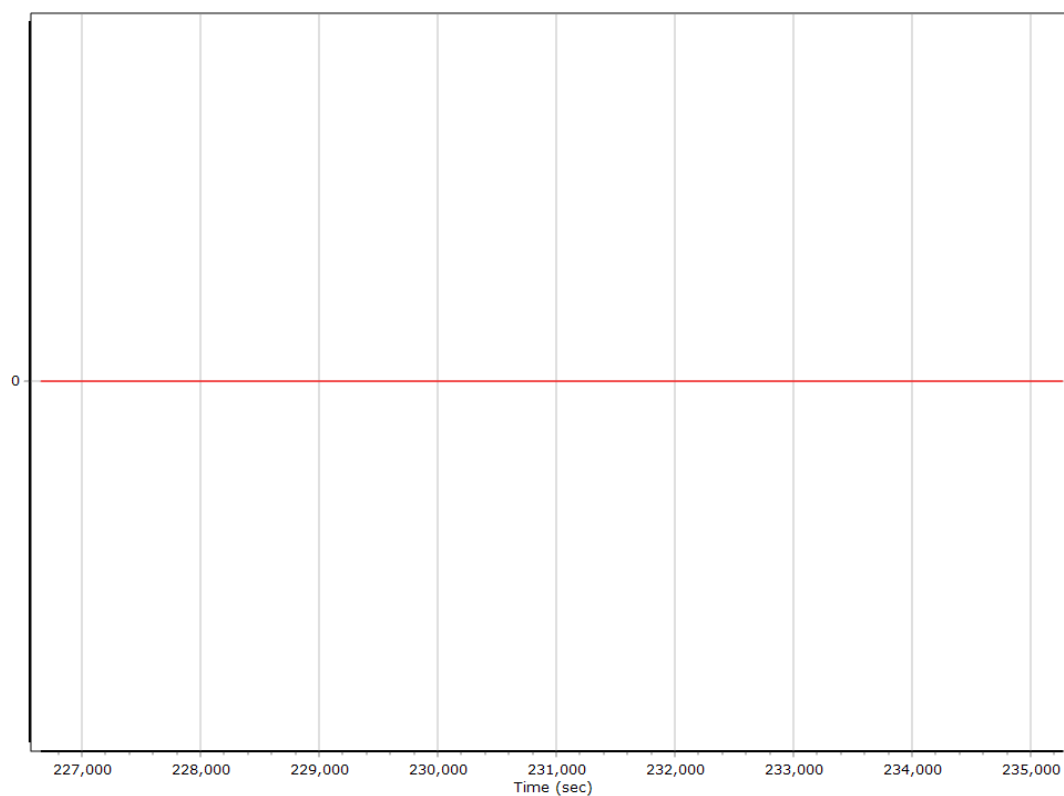
Y Reference-Primary GNSS Lever Arm (m)



Z Reference-Primary GNSS Lever Arm (m)



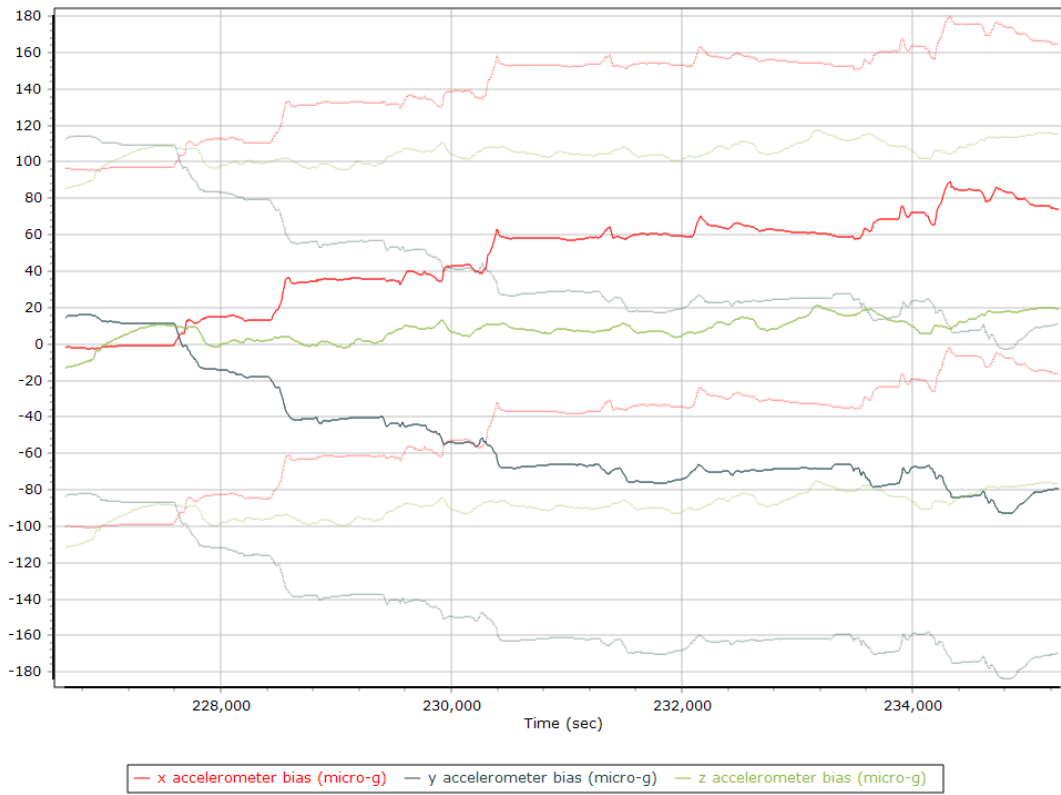
Reference-Primary GNSS Lever Arm Figure of Merit



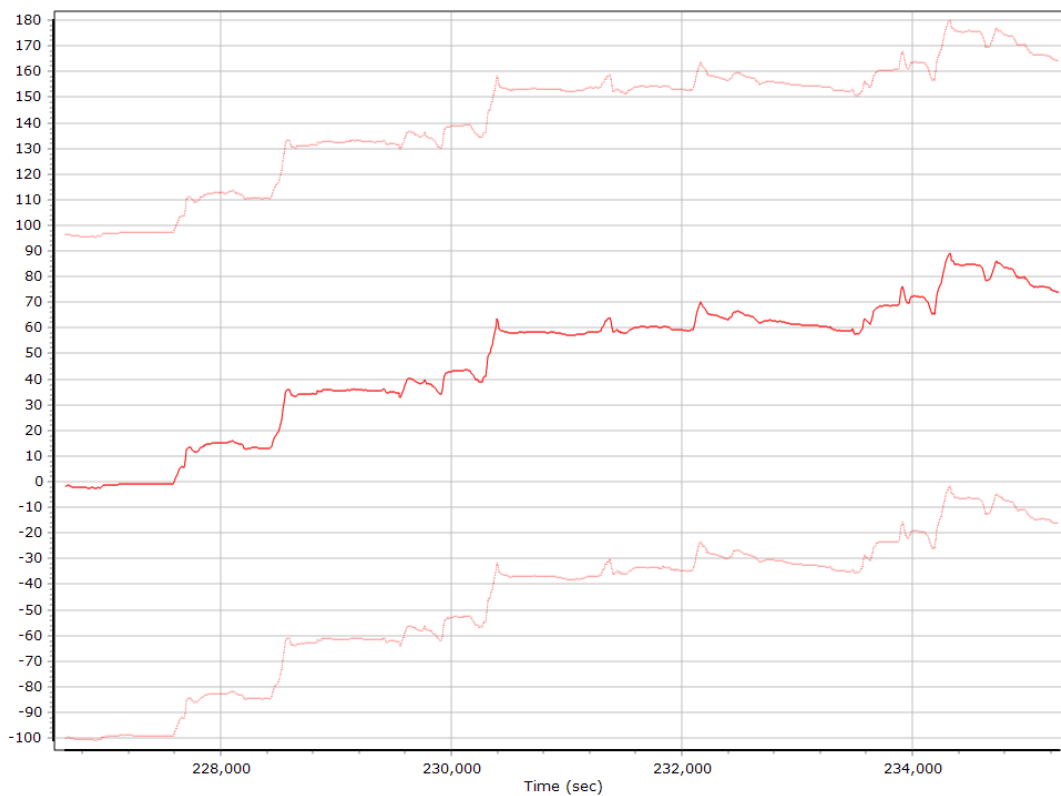
IN-Fusion QC

Forward Processed Estimated Errors, Reference Frame

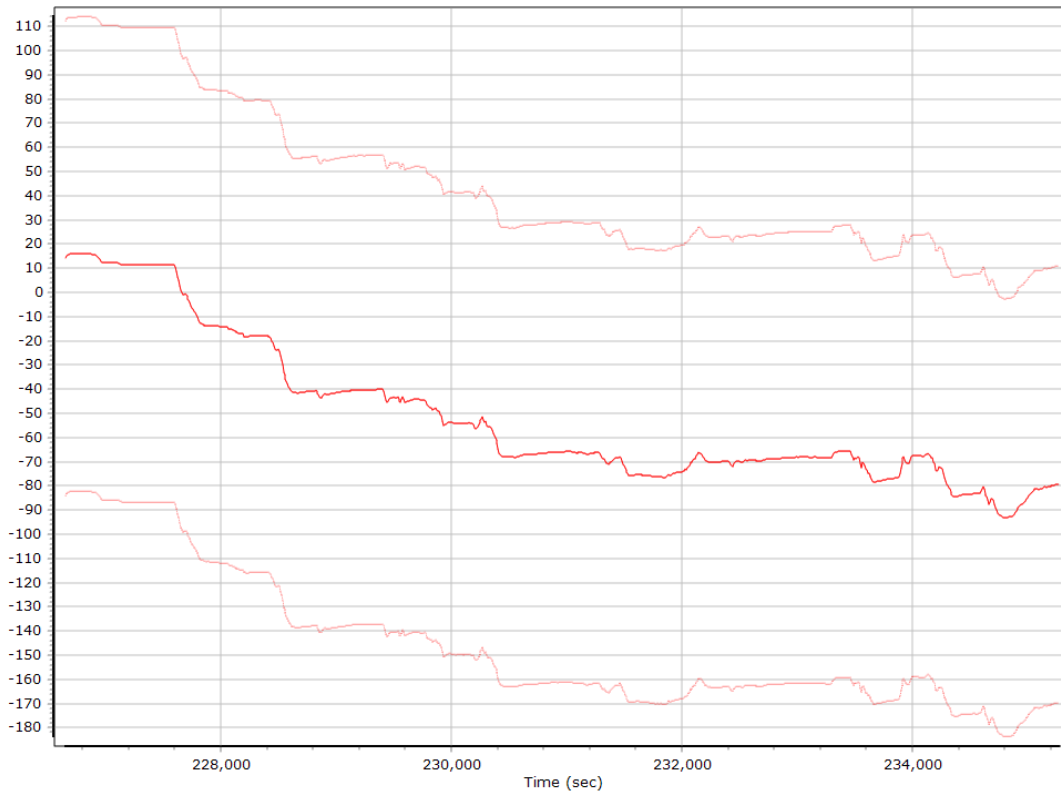
Accelerometer Bias (micro-g)



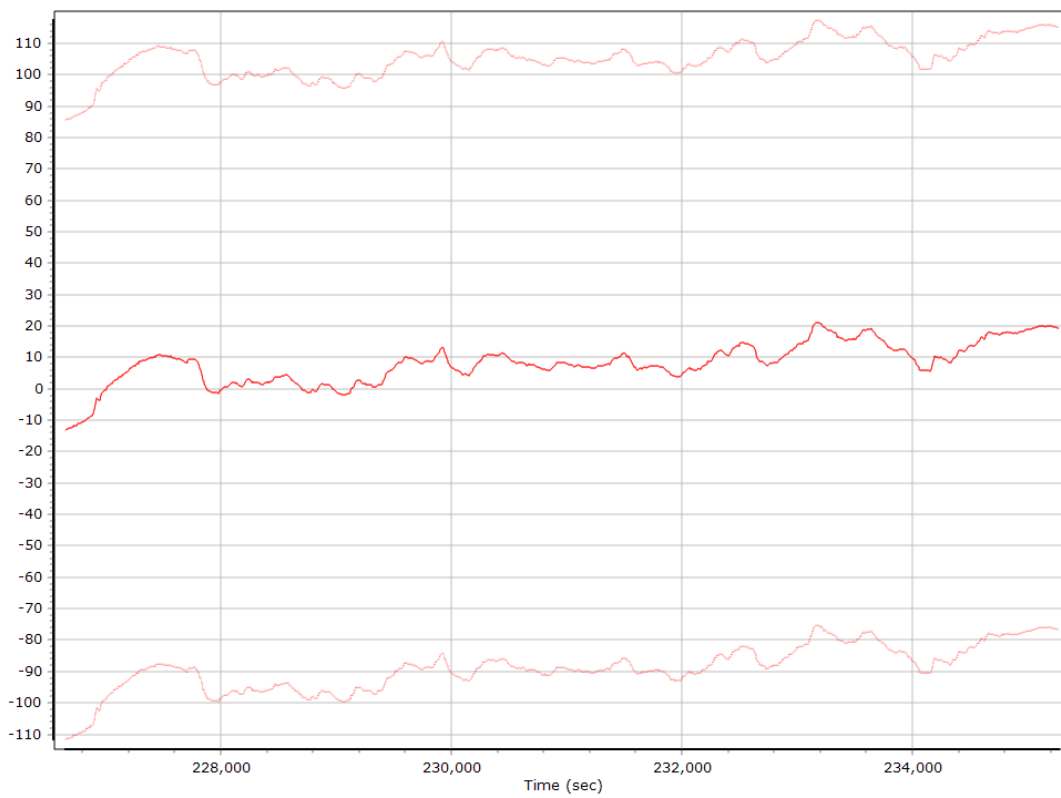
X Accelerometer Bias (micro-g)



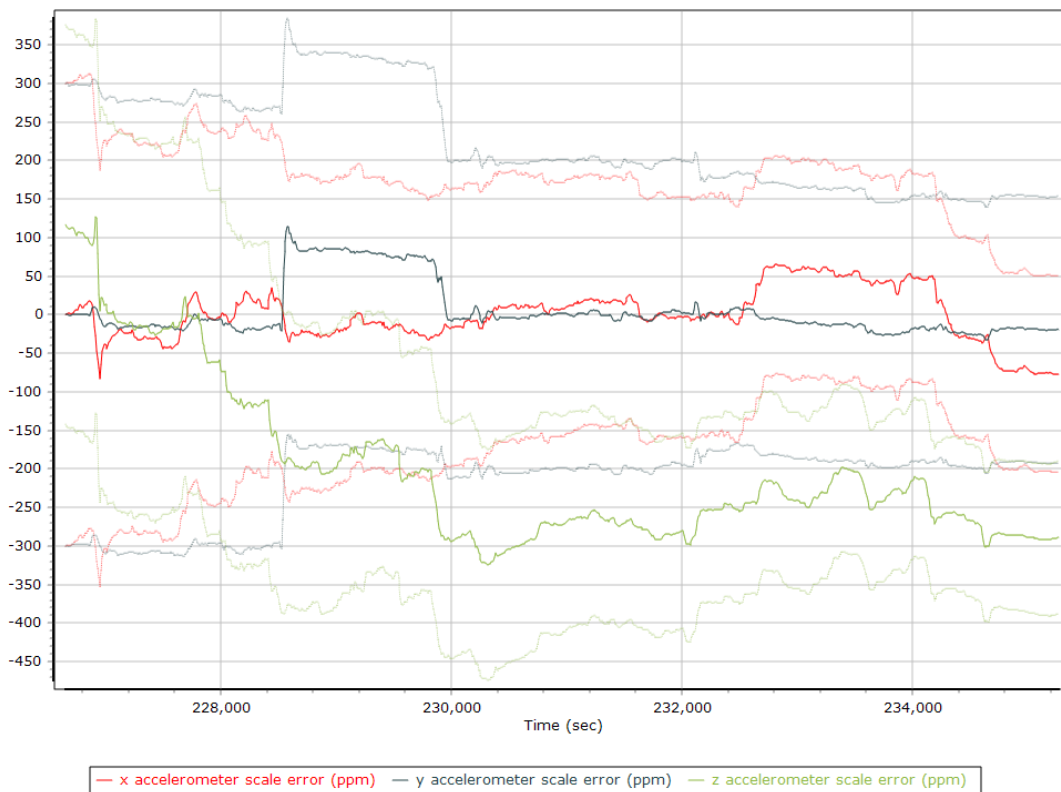
Y Accelerometer Bias (micro-g)



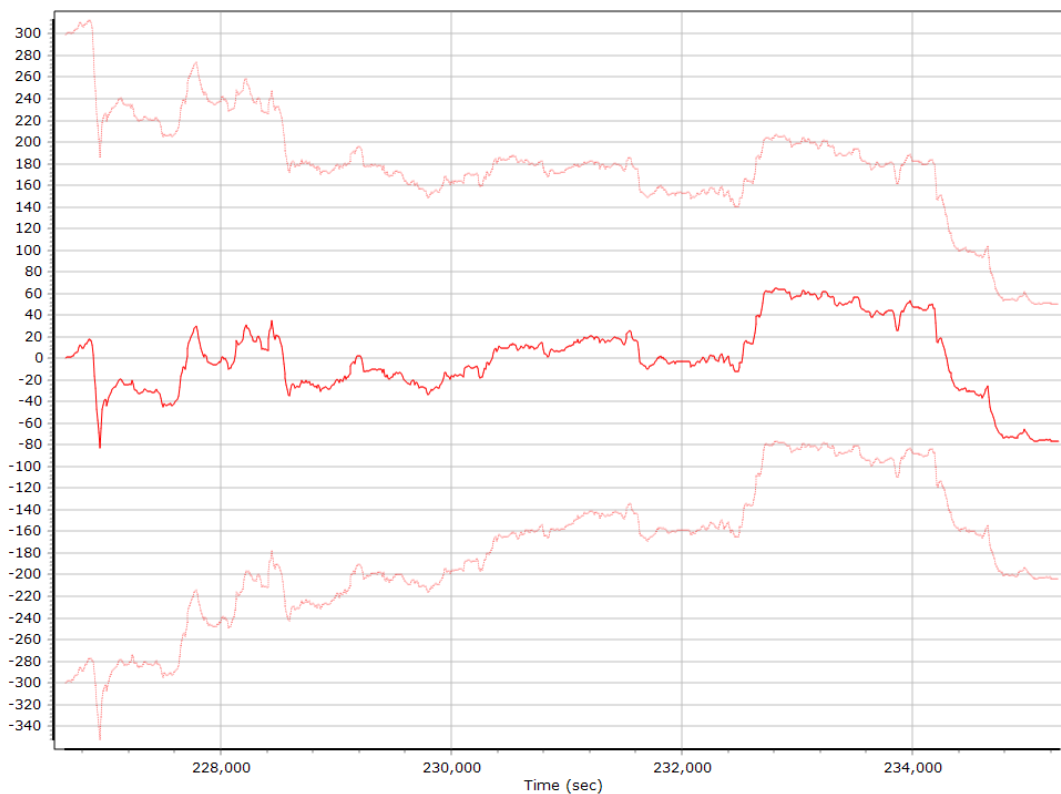
Z Accelerometer Bias (micro-g)



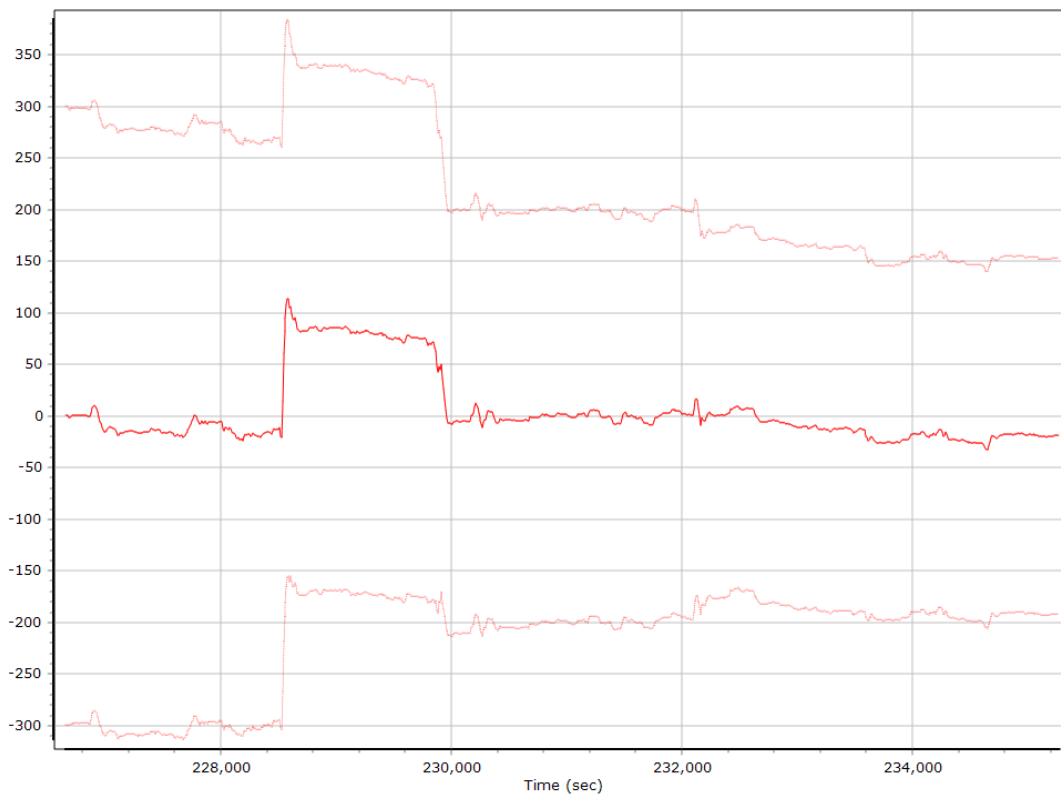
Accelerometer Scale Error (ppm)



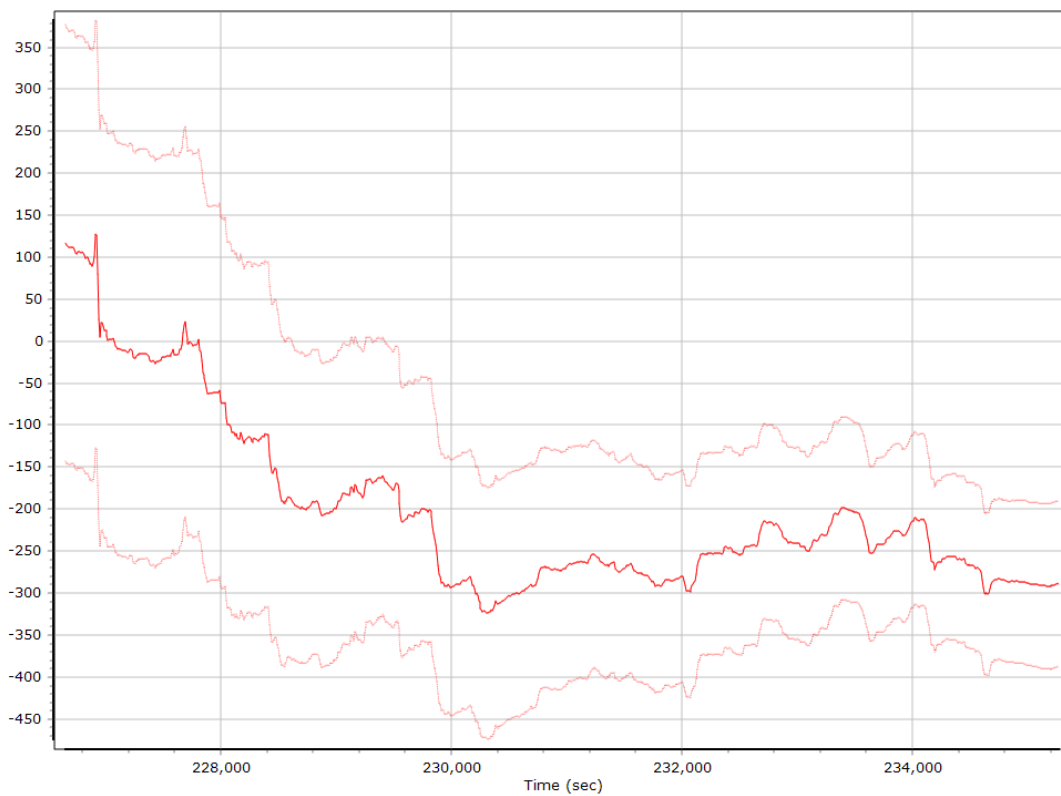
X Accelerometer Scale Error (ppm)



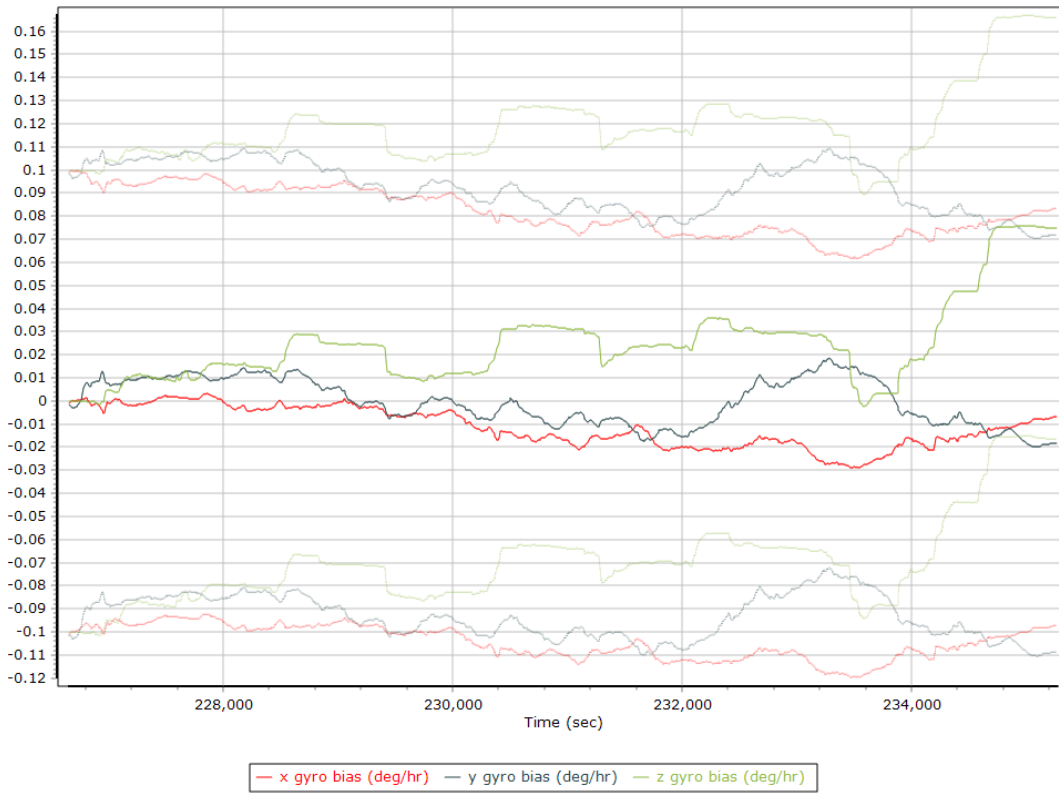
Y Accelerometer Scale Error (ppm)



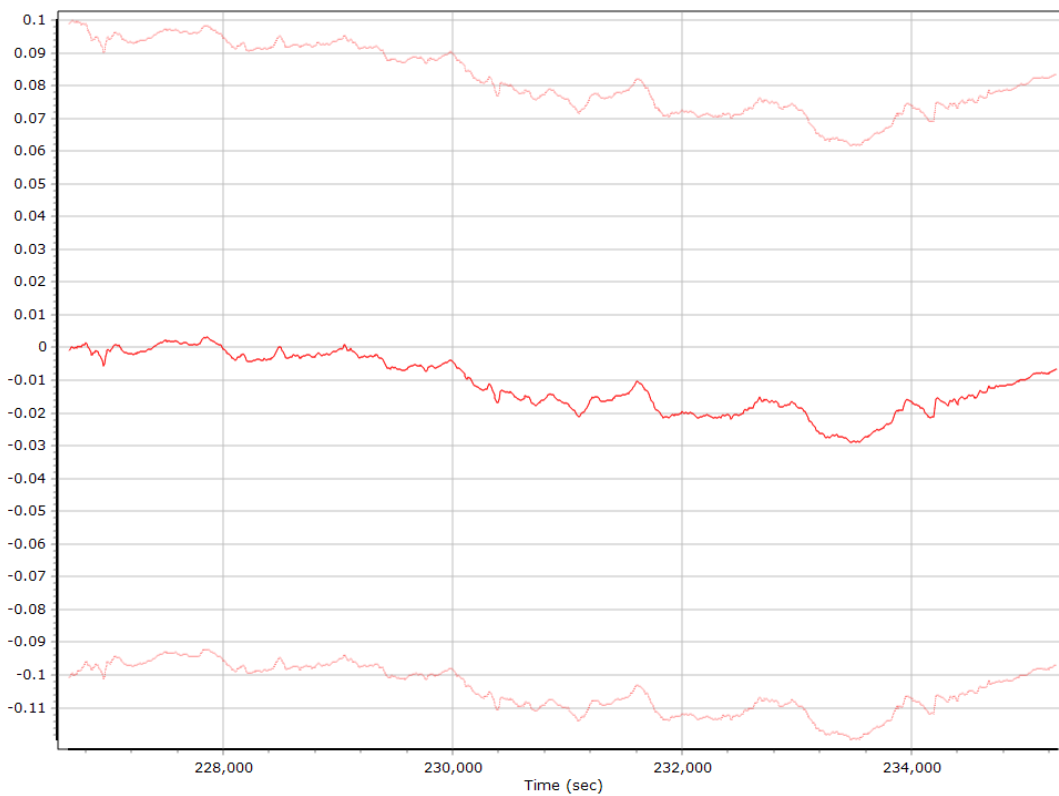
Z Accelerometer Scale Error (ppm)



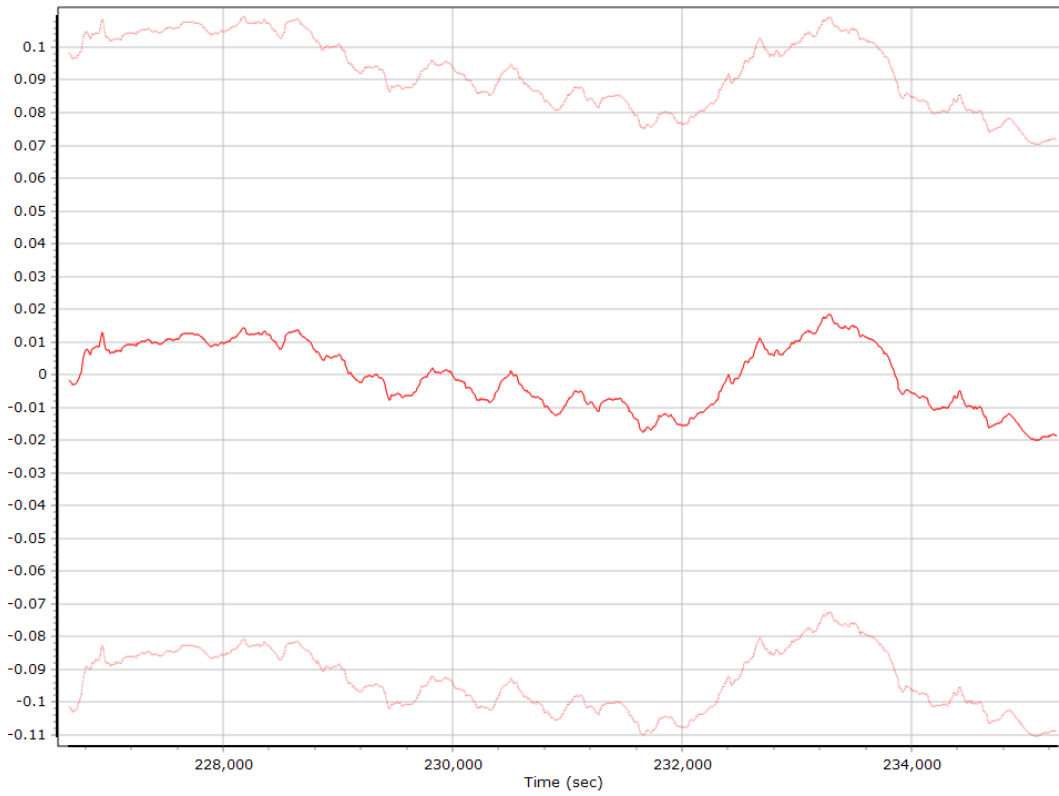
Gyro Bias (deg/h)



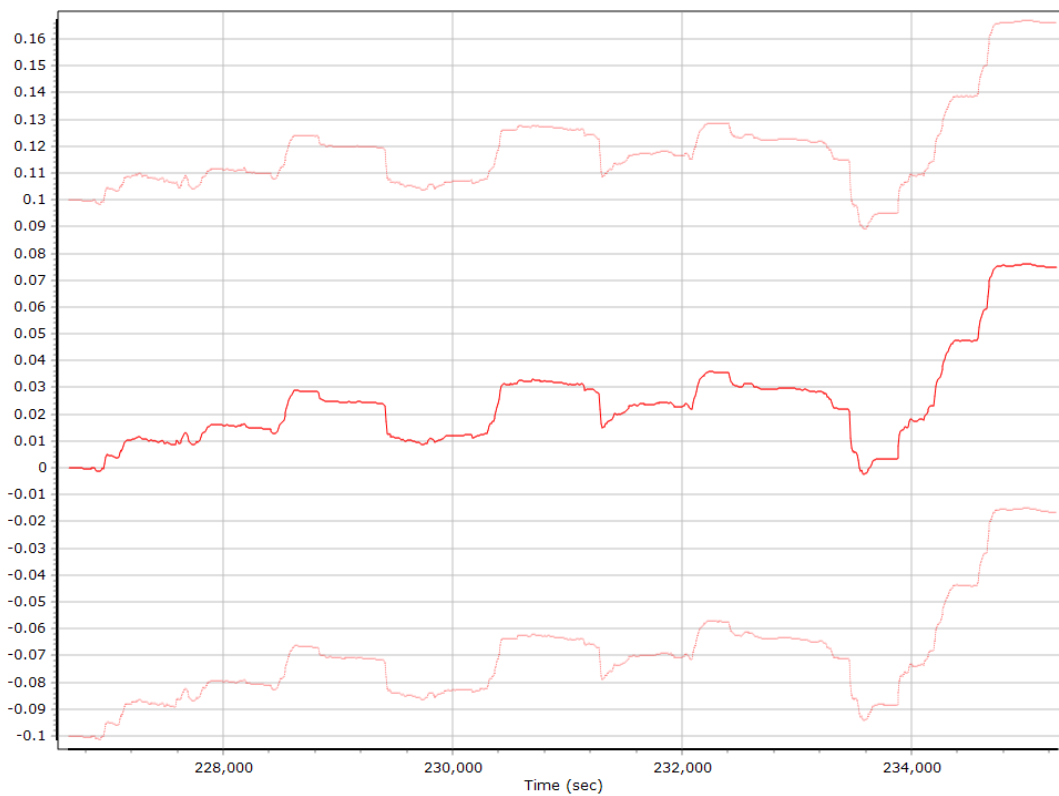
X Gyro Bias (deg/h)



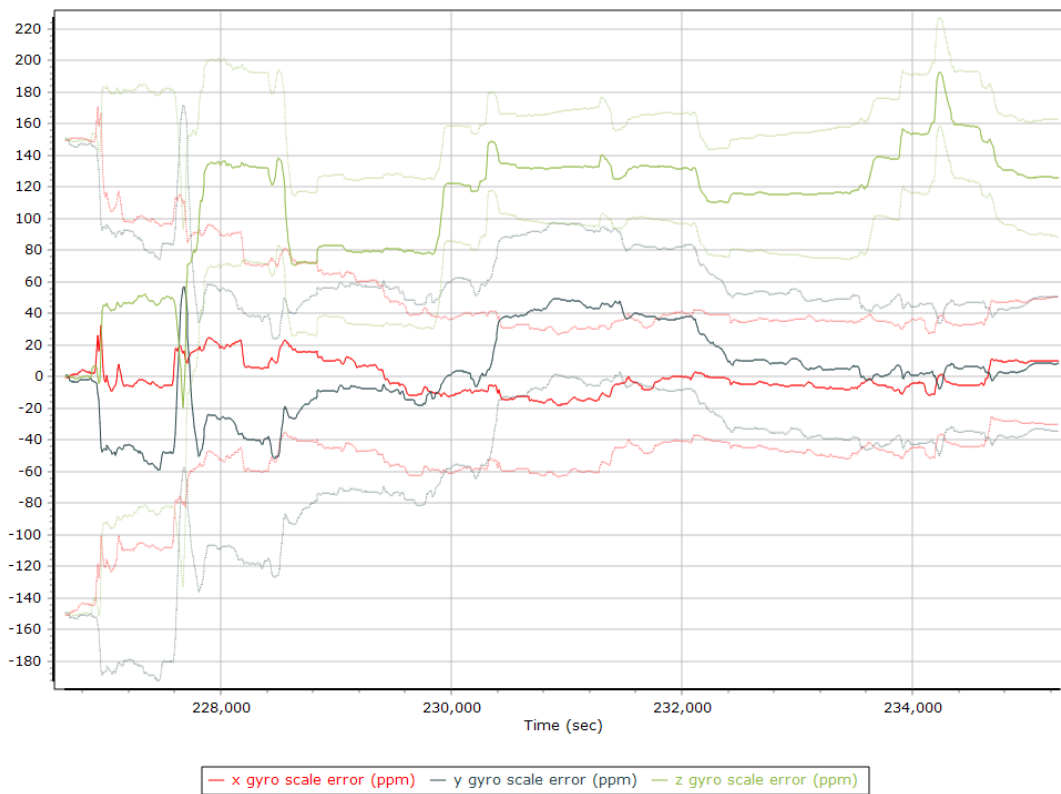
Y Gyro Bias (deg/h)



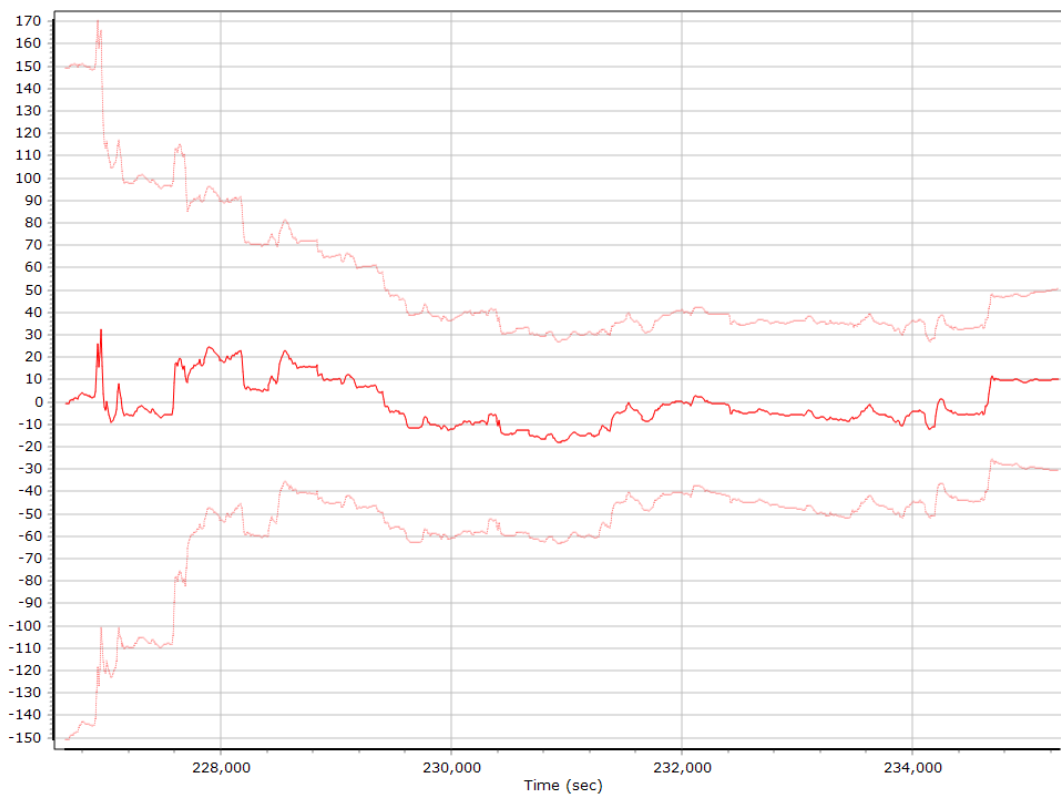
Z Gyro Bias (deg/h)



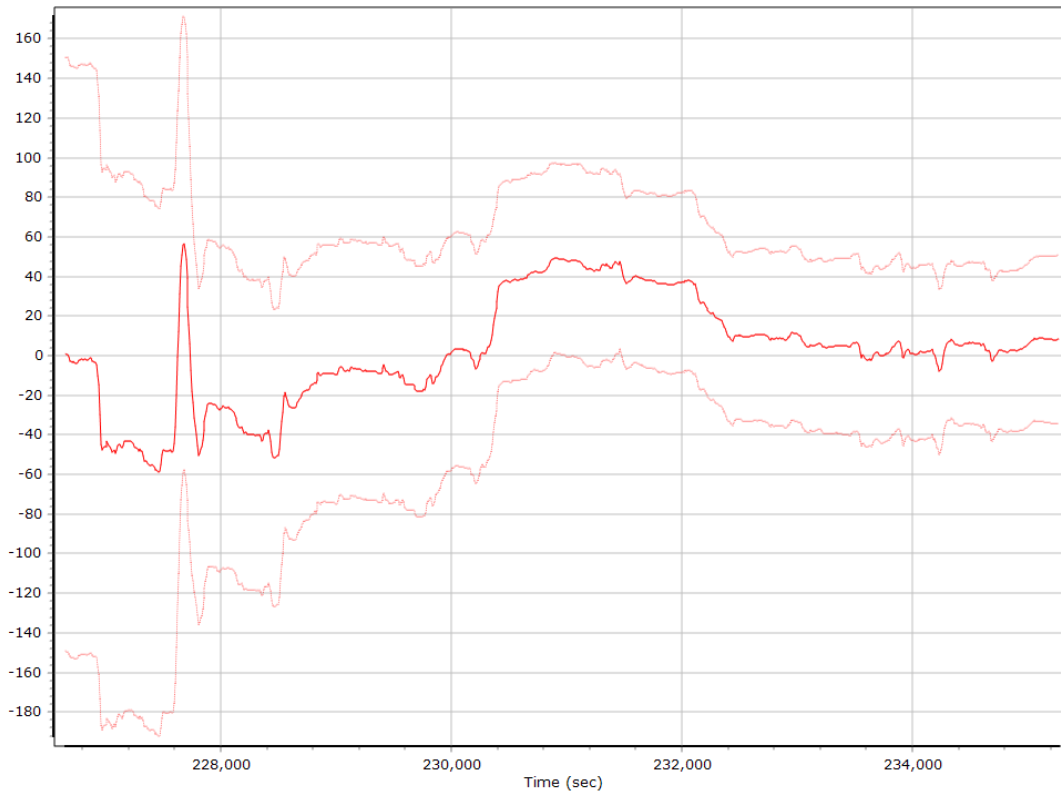
Gyro Scale Error (ppm)



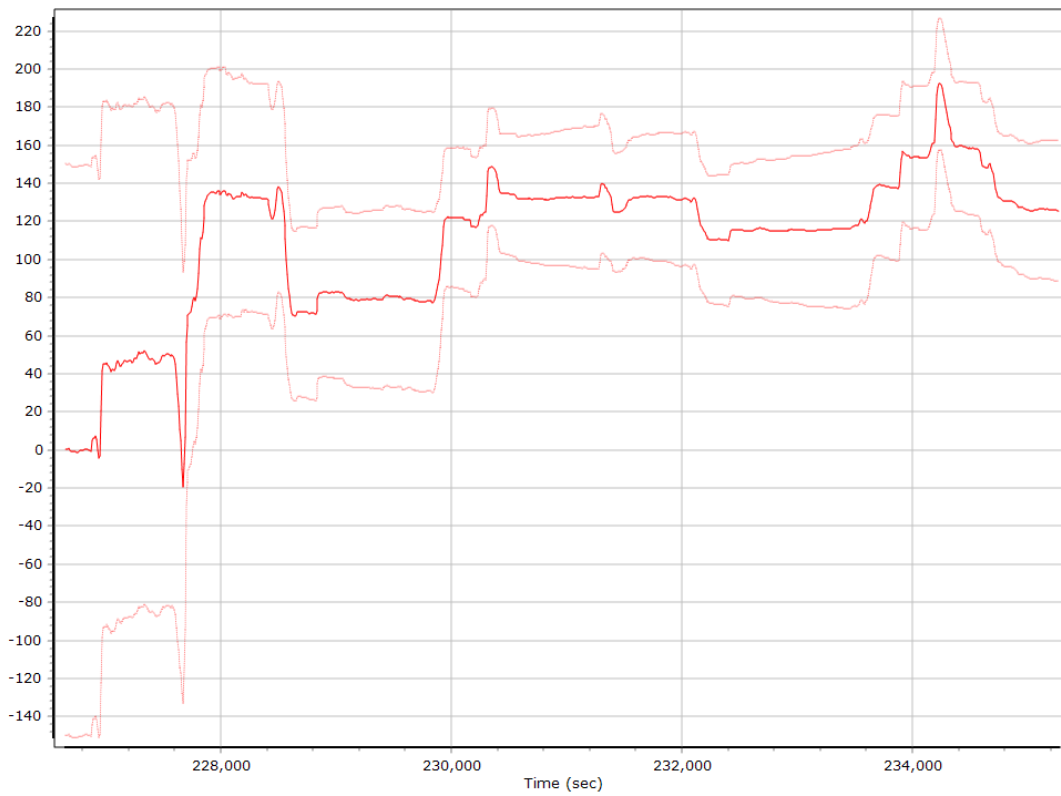
X Gyro Scale Error (ppm)



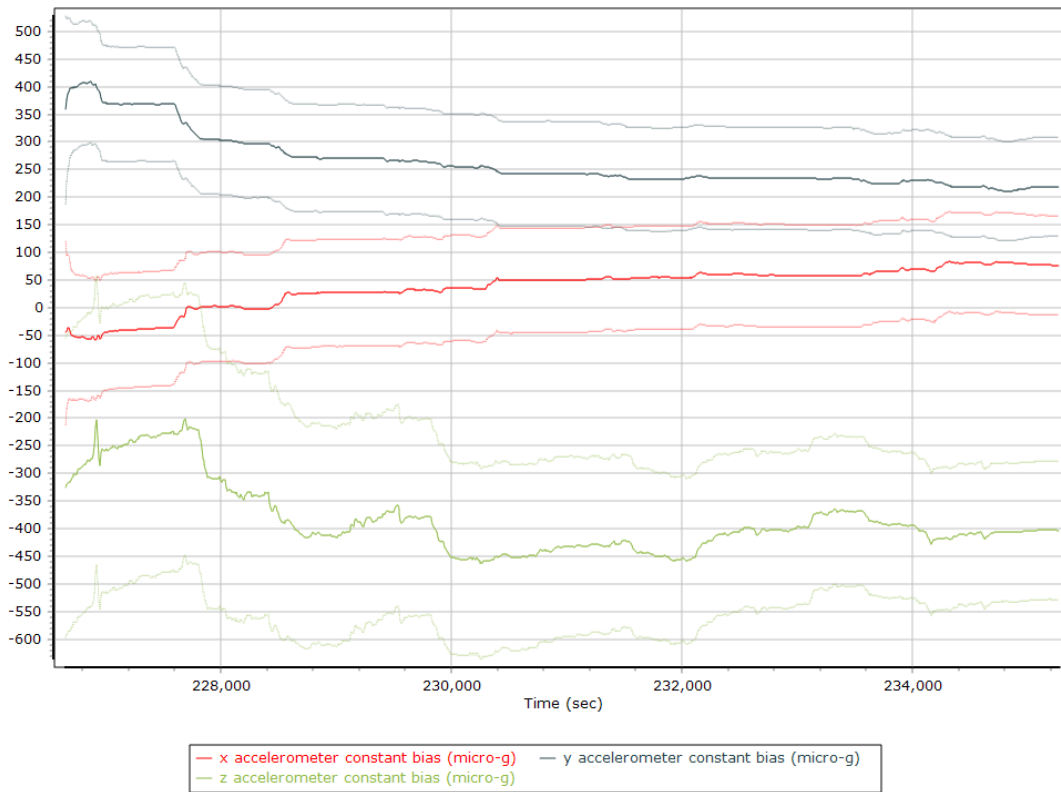
Y Gyro Scale Error (ppm)



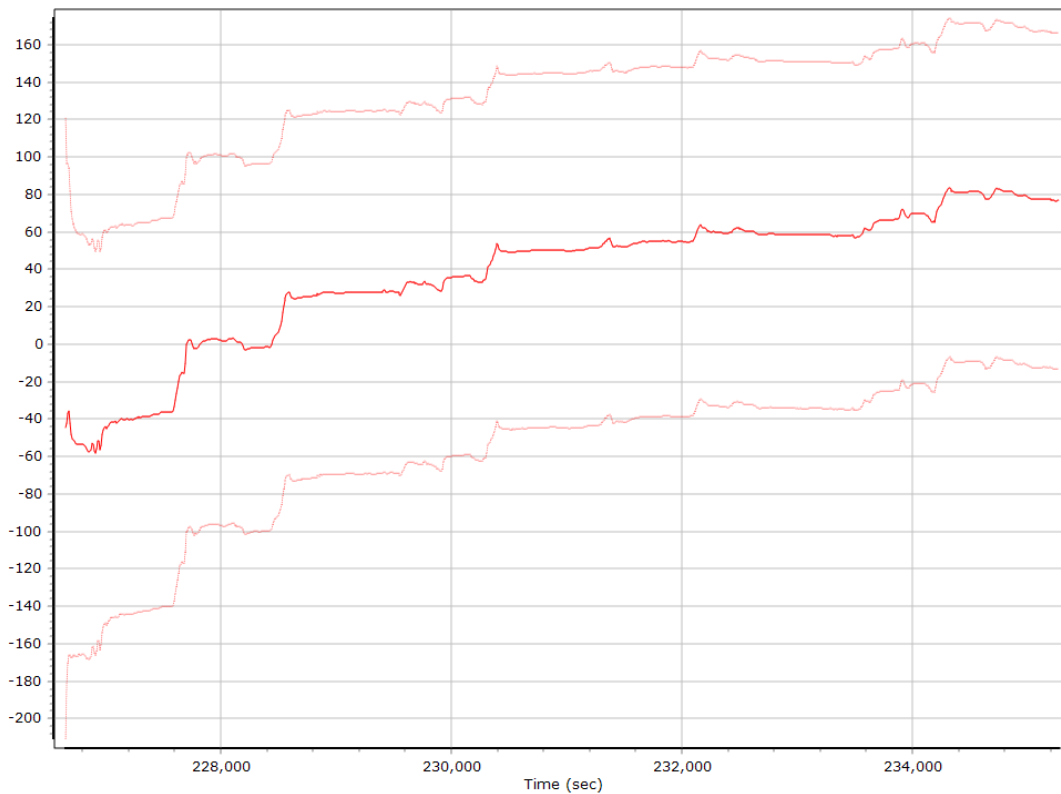
Z Gyro Scale Error (ppm)



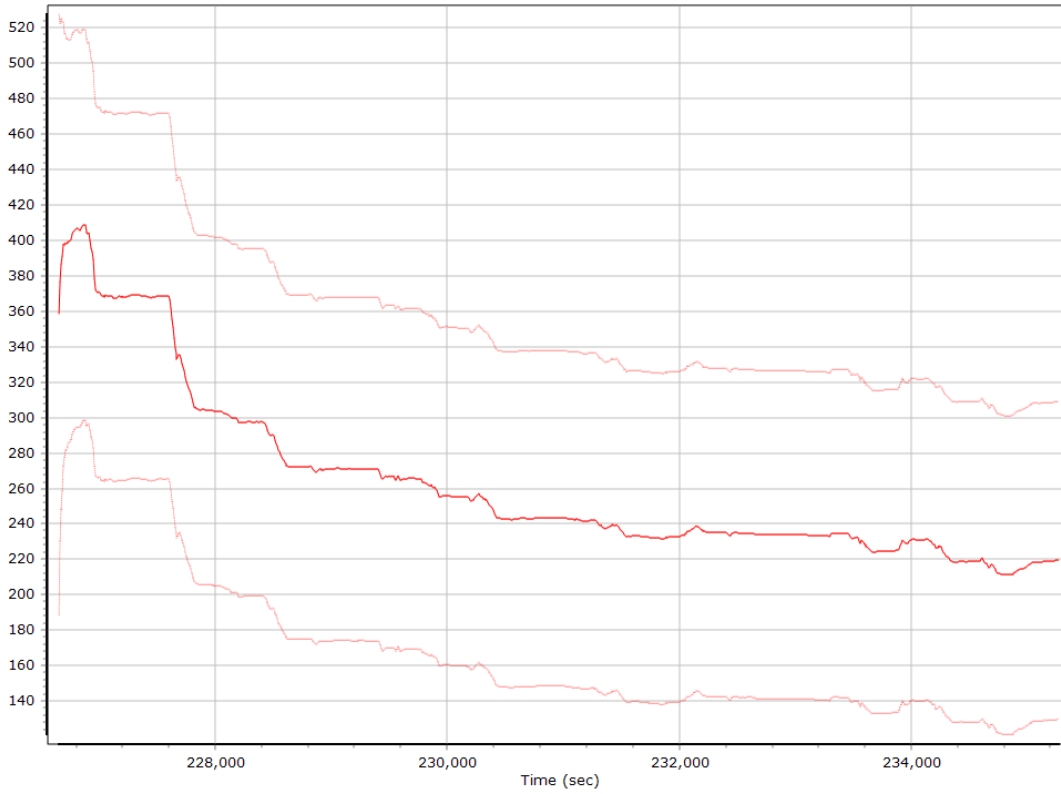
Forward Processed Estimated Constant Errors, Reference Frame Accelerometer Bias (micro-g)



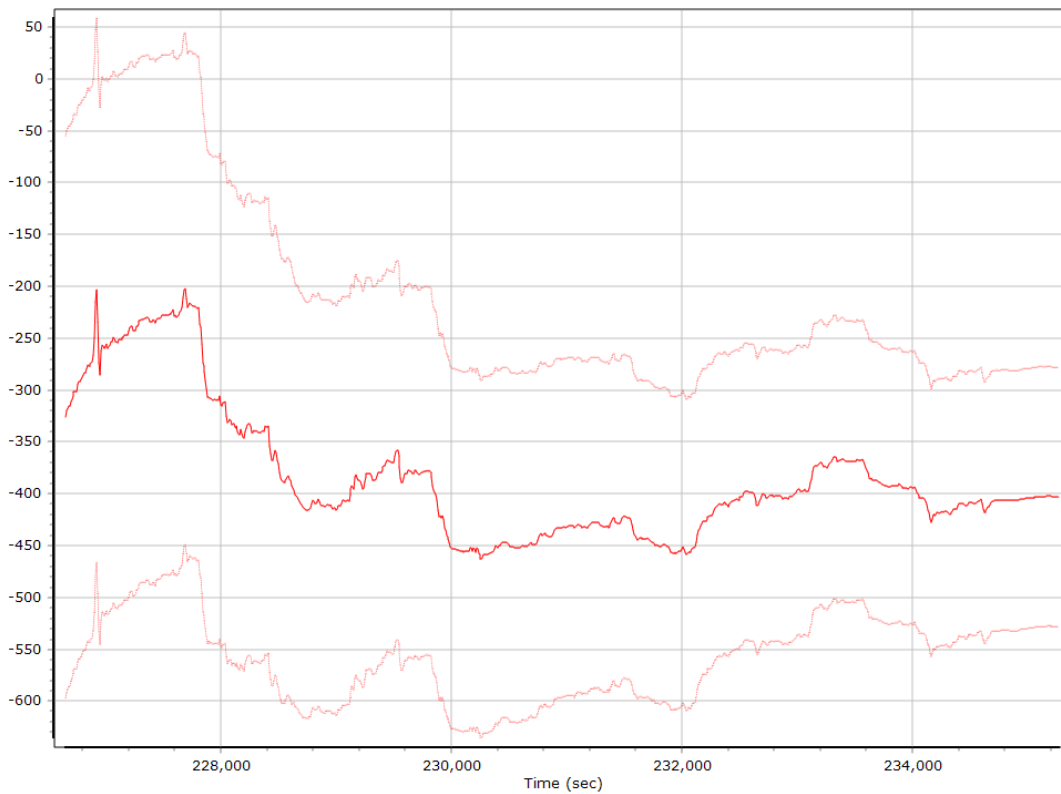
X Accelerometer Bias (micro-g)



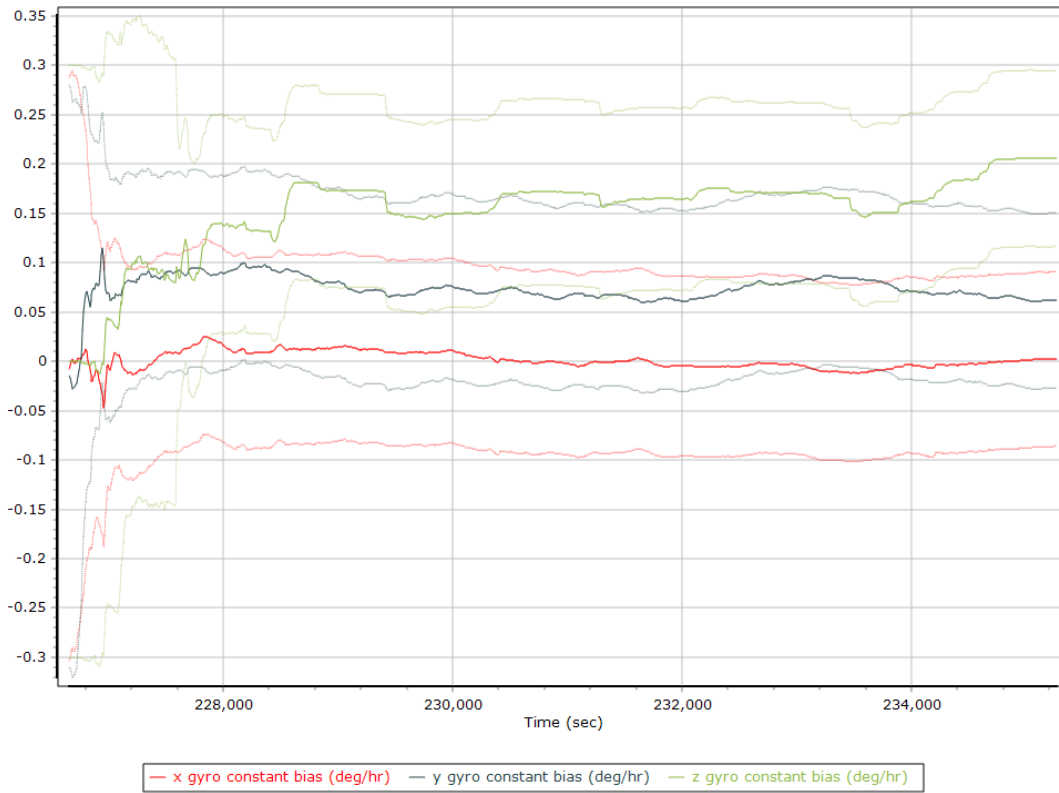
Y Accelerometer Bias (micro-g)



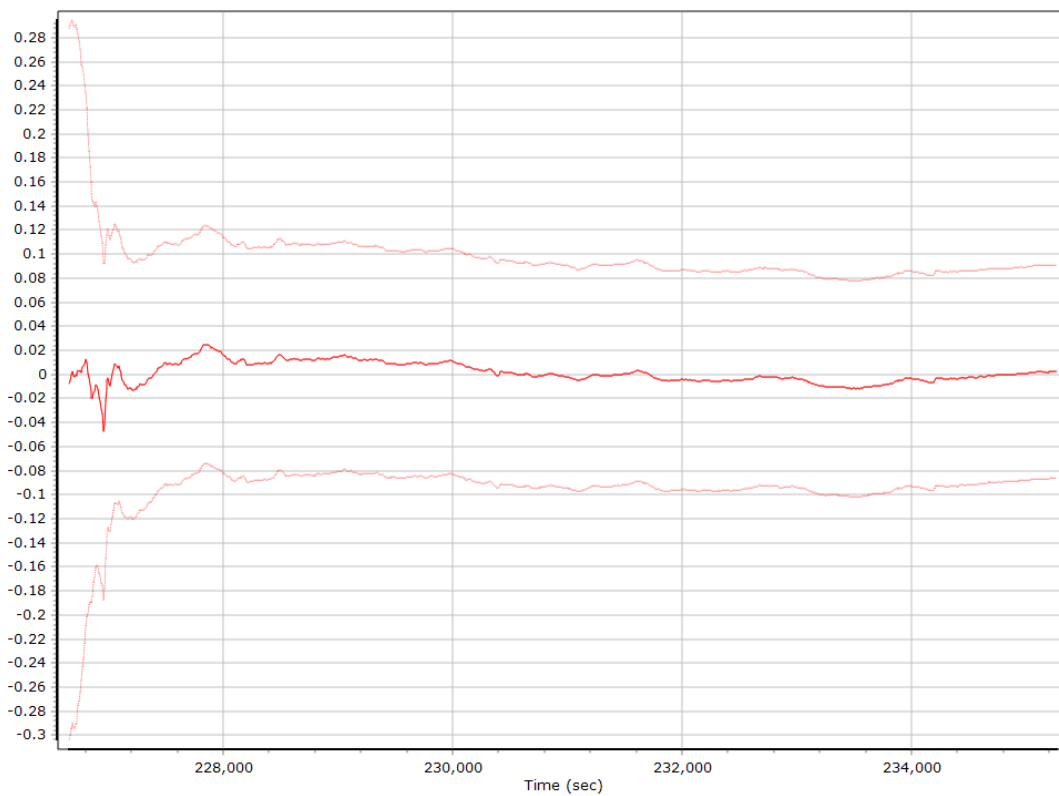
Z Accelerometer Bias (micro-g)



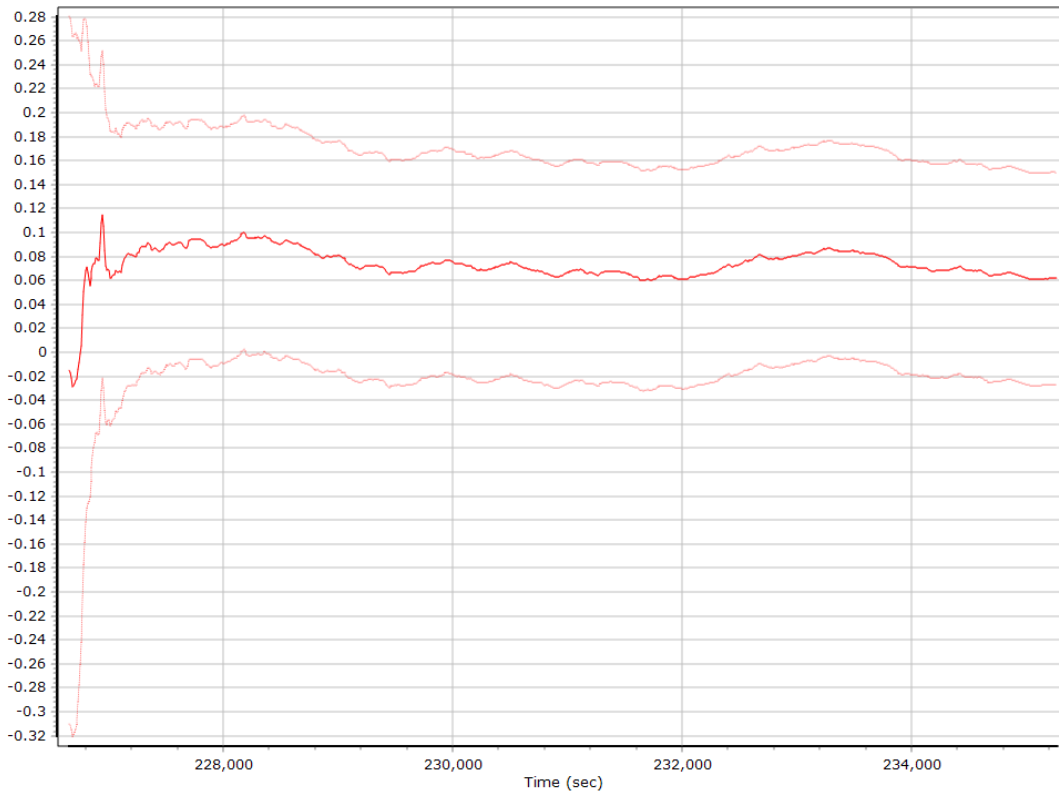
Gyro Bias (deg/h)



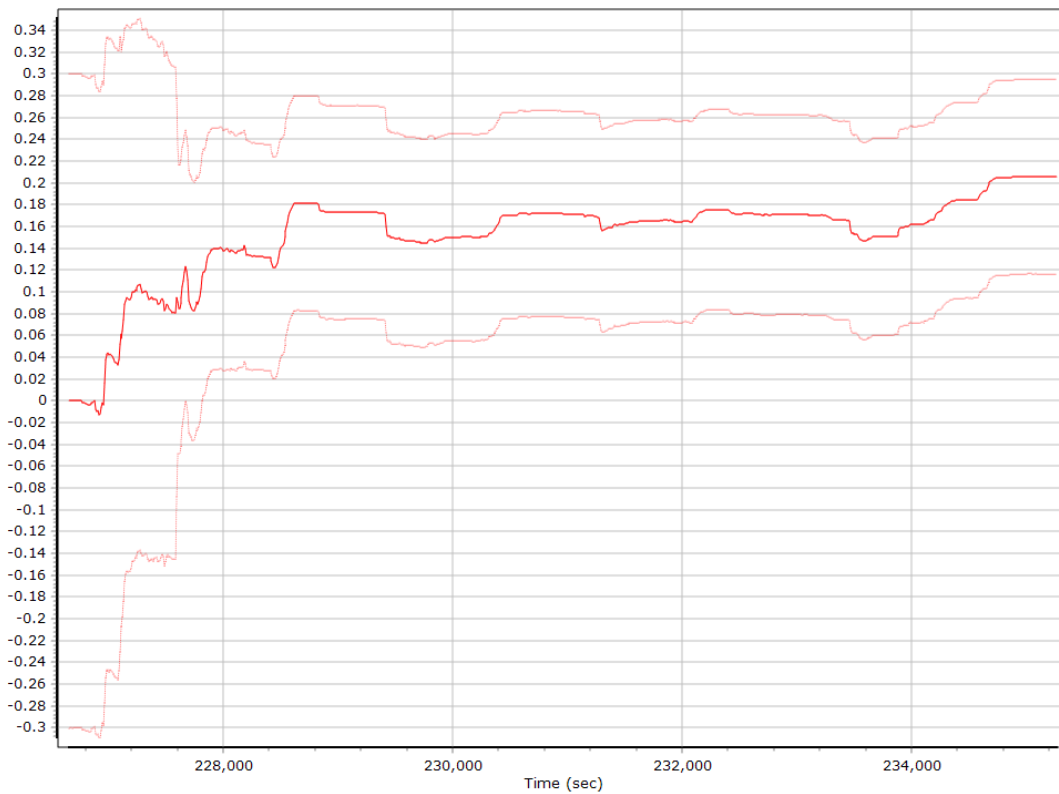
X Gyro Bias (deg/h)



Y Gyro Bias (deg/h)

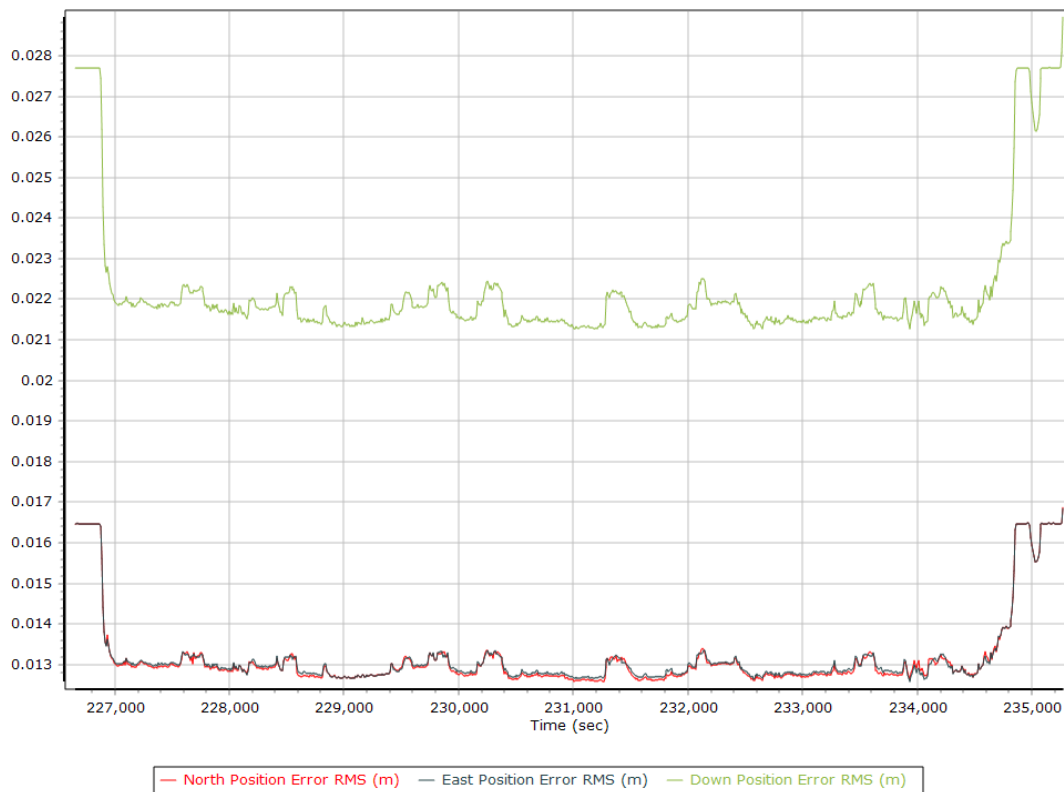


Z Gyro Bias (deg/h)

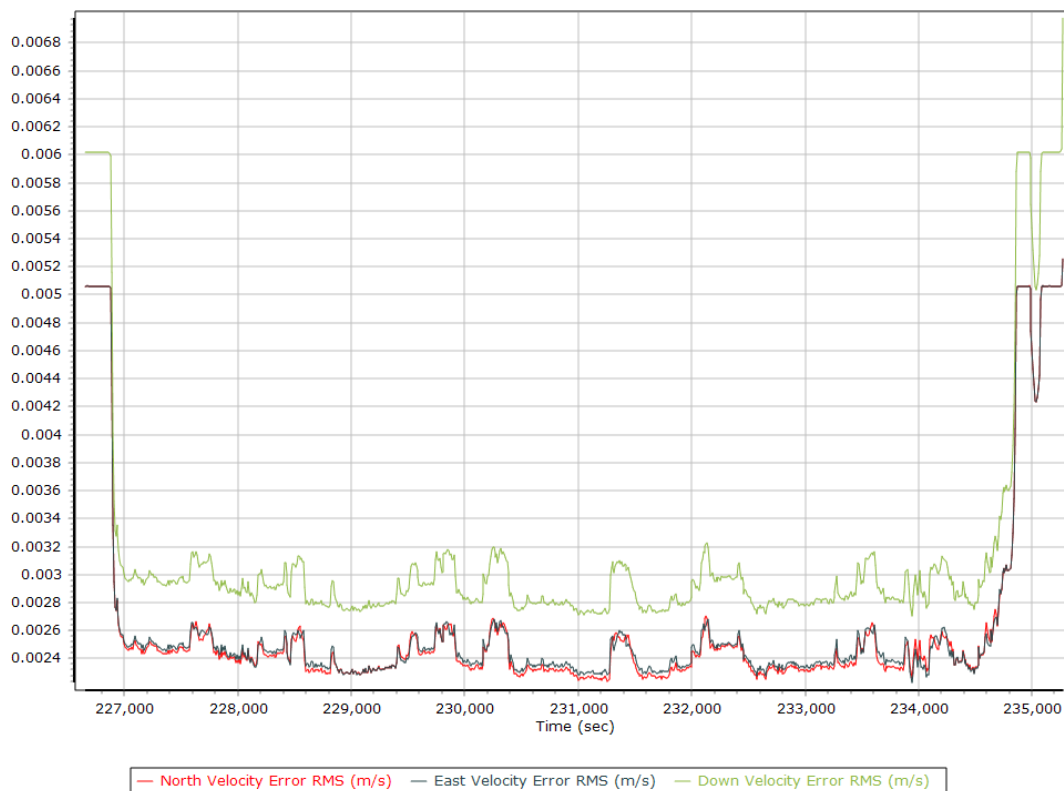


Smoothed Performance Metrics

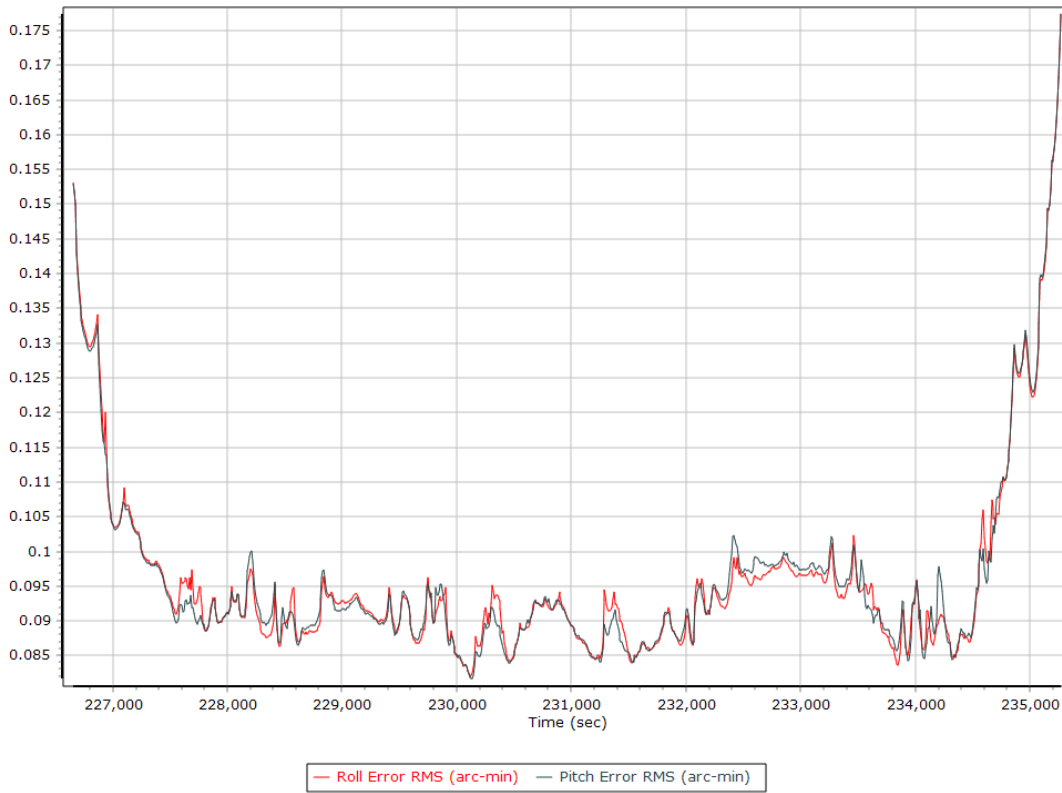
Position Error RMS (m)



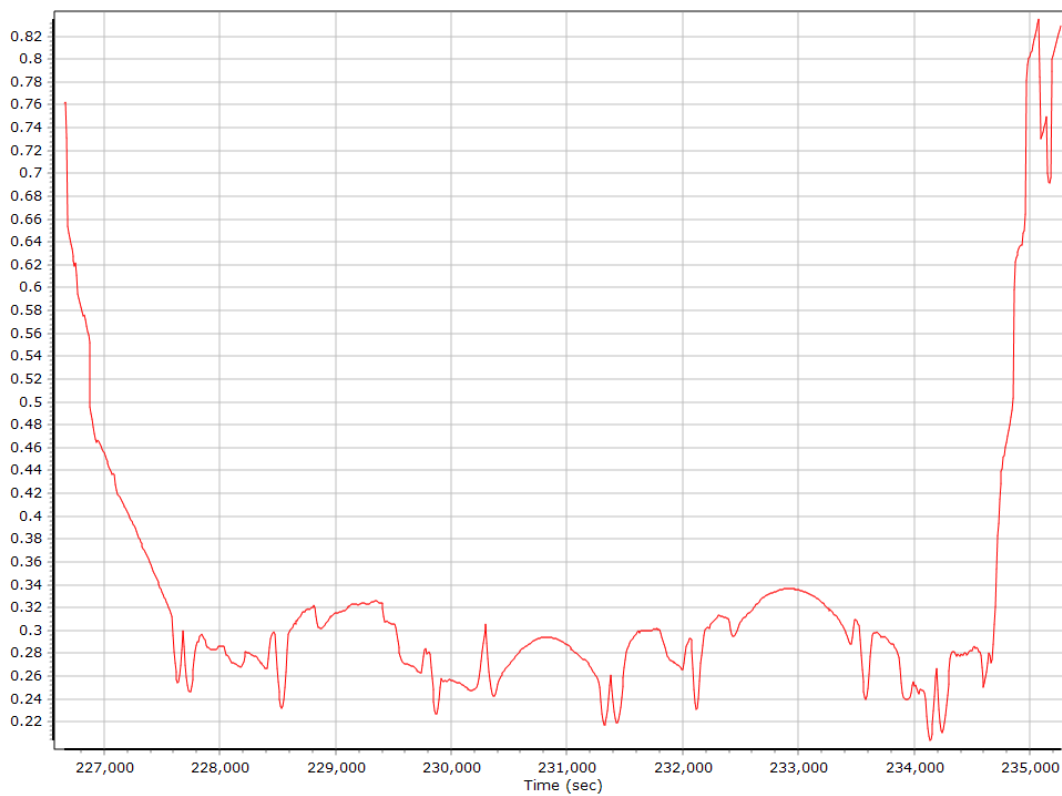
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

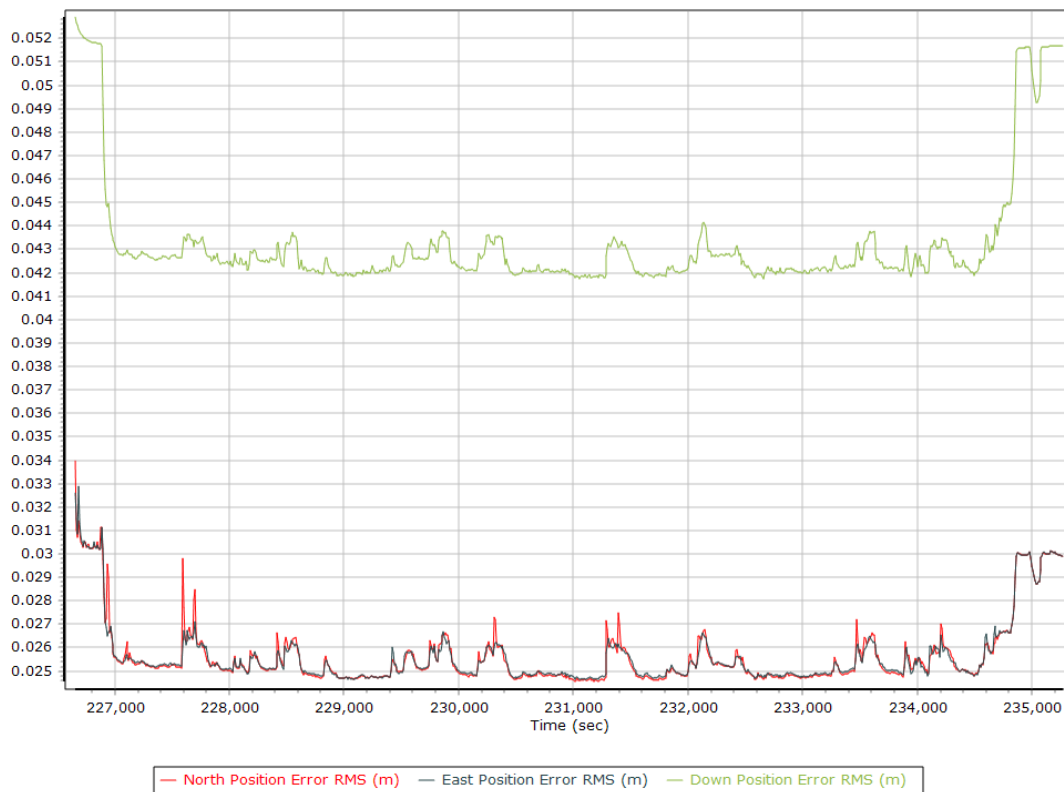


Heading Error RMS (arc-min)

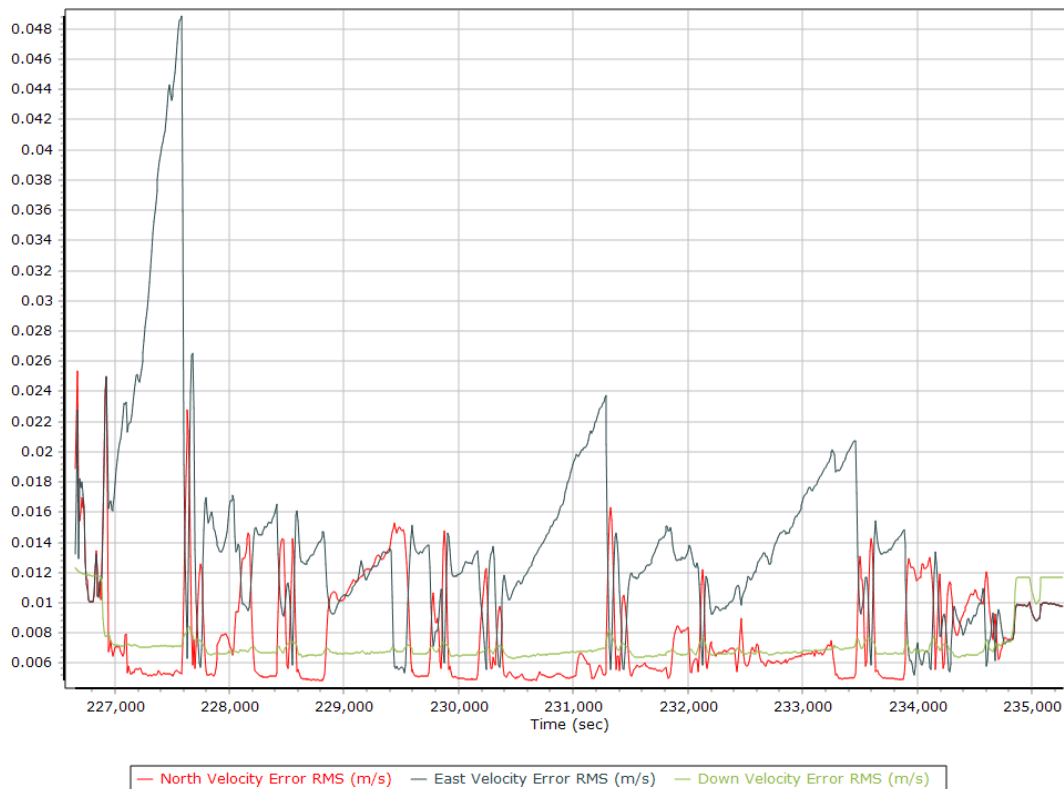


Forward Processed Performance Metrics

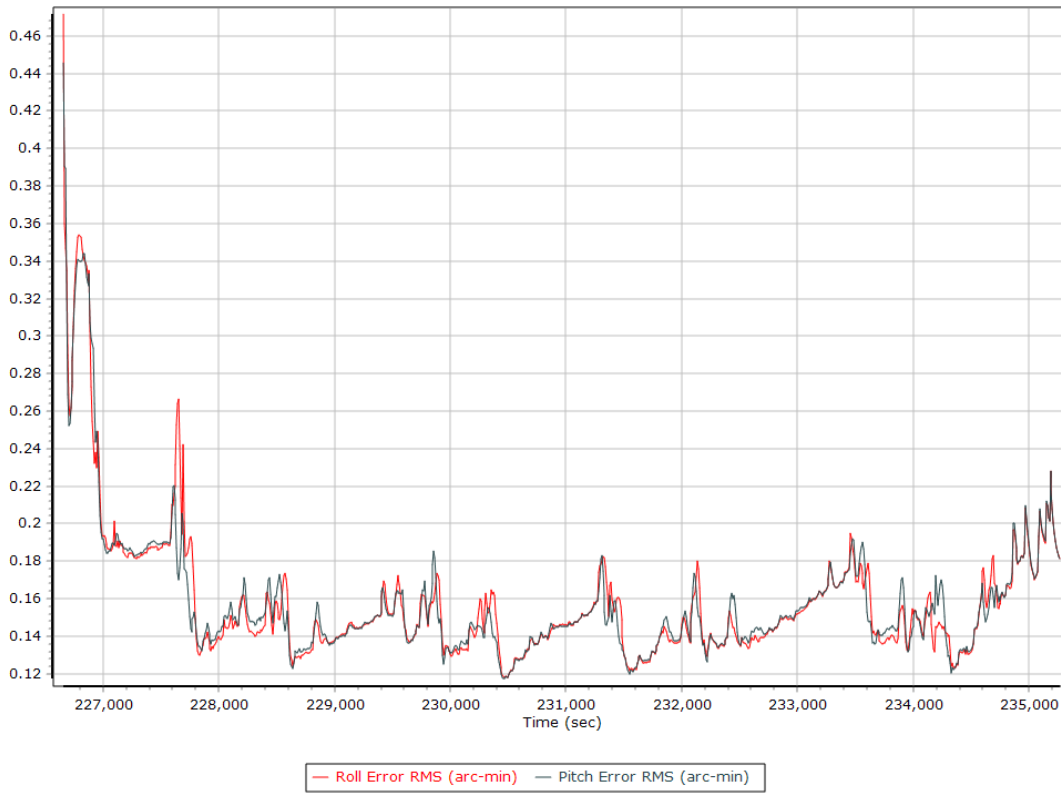
Position Error RMS (m)



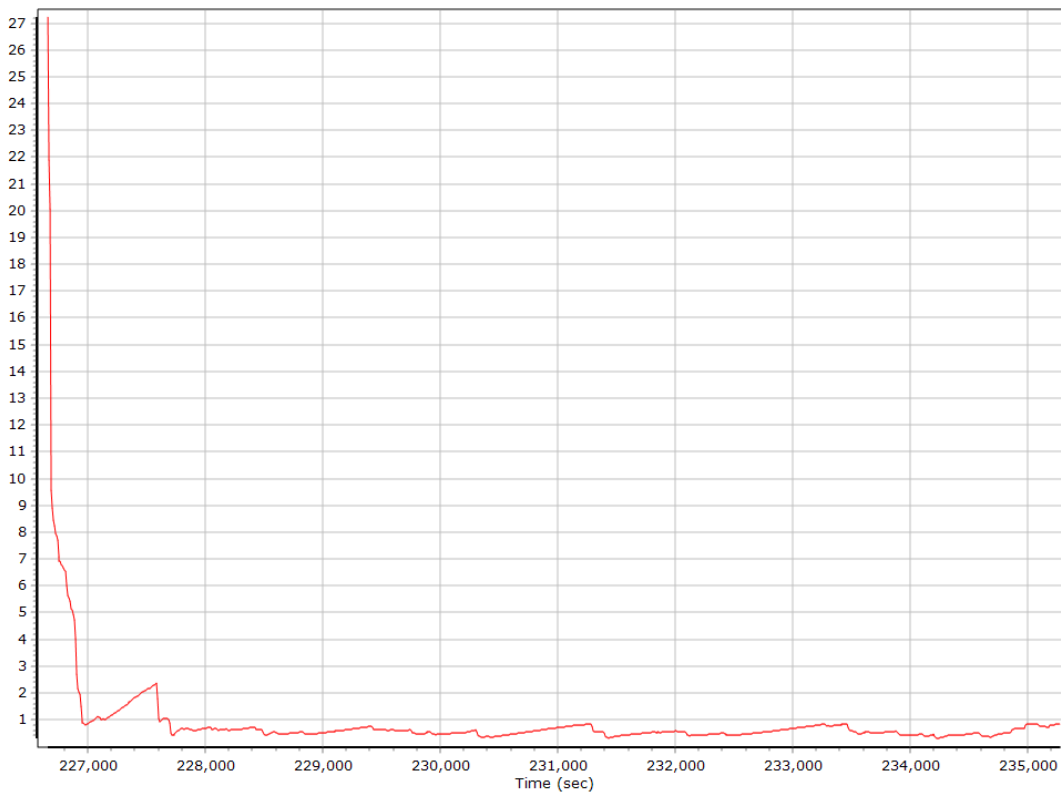
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

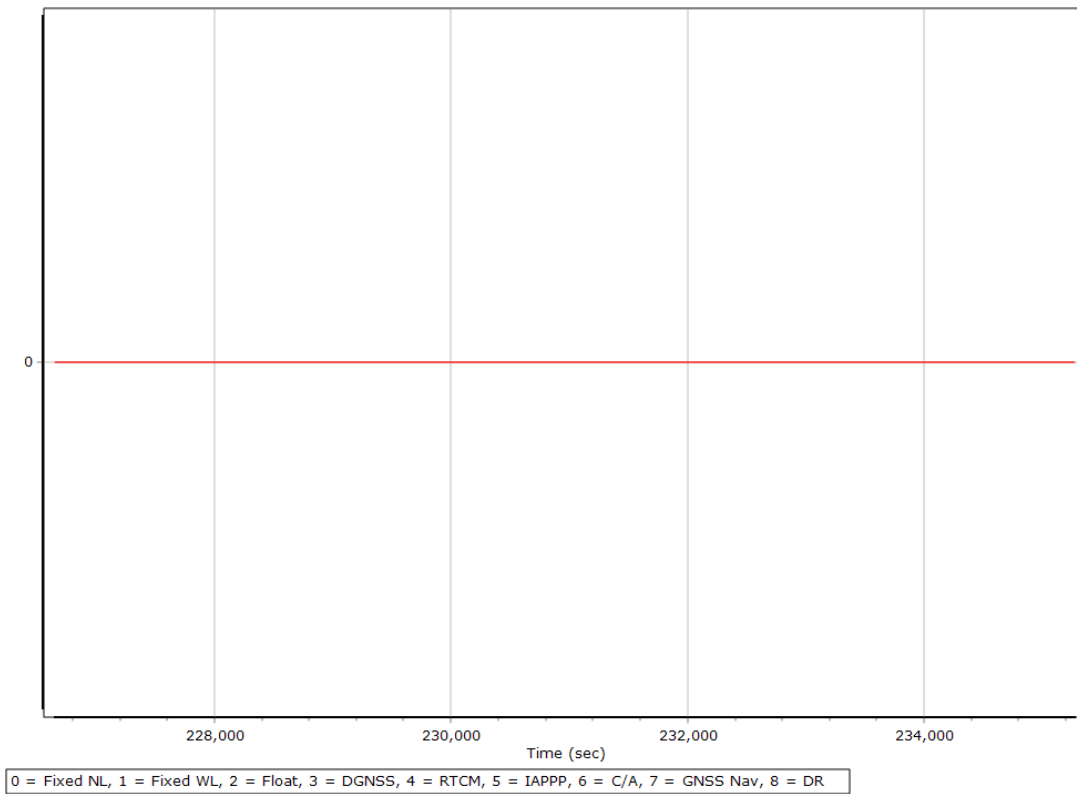


Heading Error RMS (arc-min)

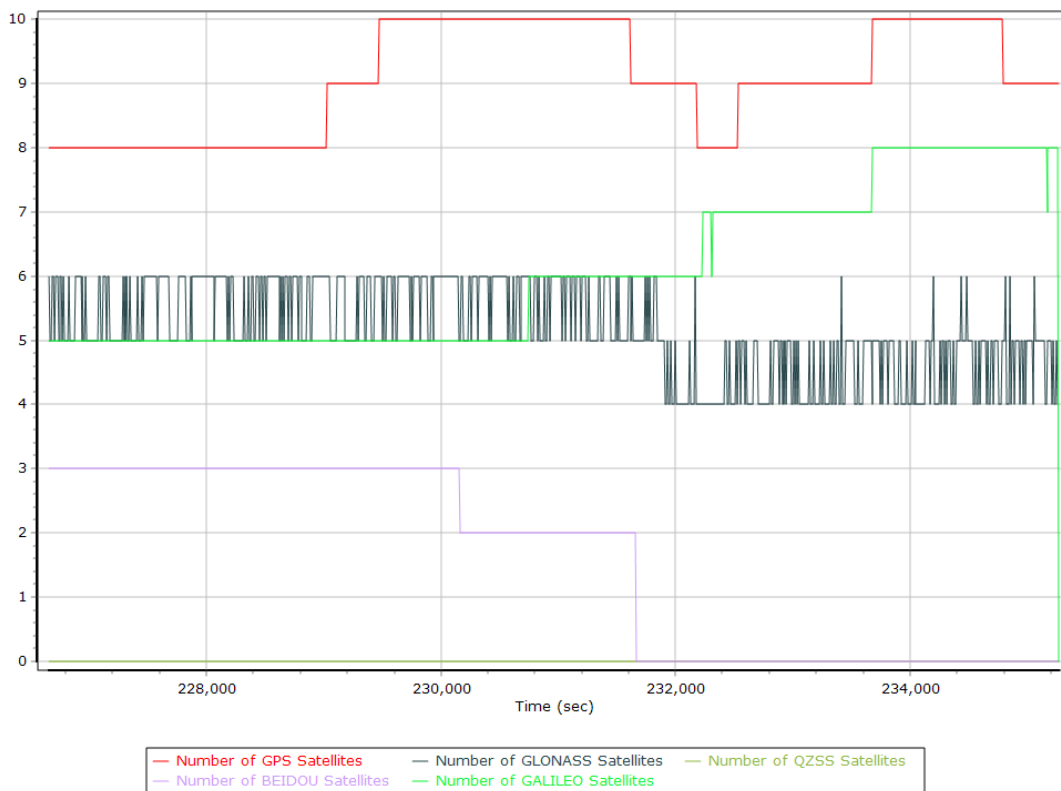


Forward Processed Solution Status

Processing Mode



Number of Satellites



Baseline Length

