

## General Information

### Mission Information

Project name	211020_A_5060420_nad2011_FINAL
Processing date	2021-10-27 16:57:07
Mission date	2021-10-20 18:28:24
Mission duration	02:45:16.801
Processing mode	IN-Fusion PP-RTX

### Rover Hardware Information

Product	POS AV 610 VER6 HW2.5-12
Serial number	S/N9825
IMU type	57
Receiver type	BD982
Antenna type	AV39

## Project File List

### Rover Data Files

File name	File type
survey3.pos	POS Data

### Input Files

File Name	File Type
Ephm2930.21g	GLONASS Broadcast Ephemeris
Ephm2930.21n	GPS Broadcast Ephemeris

### Output Files

Filename	File type
sbet_211020_A_5060420_nad2011_FINAL.out	SBET Trajectory File

## Rover Data Summary

First raw data file	survey3.pos		
Last raw data file	survey3.pos		
Start GPS week	2180		
Start time	325703.430 (10/20/2021 18:28:23)		
End time	339511.665 (10/20/2021 22:18:31)		
Start of fine alignment	326889.681 (10/20/2021 18:48:09)		
Available subsystems	Primary GNSS, IMU		
POS Event Input	None		
Correction data	None		
<b>IMU Installation Lever Arms &amp; Mounting Angles</b>			
Reference to IMU lever arm (m)	0.000	0.000	0.000
Reference to IMU mounting angles (deg)	0.000	0.000	90.000
Reference to Primary GNSS lever arm (m)	-0.497	-0.045	-1.199
Reference to Primary GNSS lever arm std dev (m)	-1.000		
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

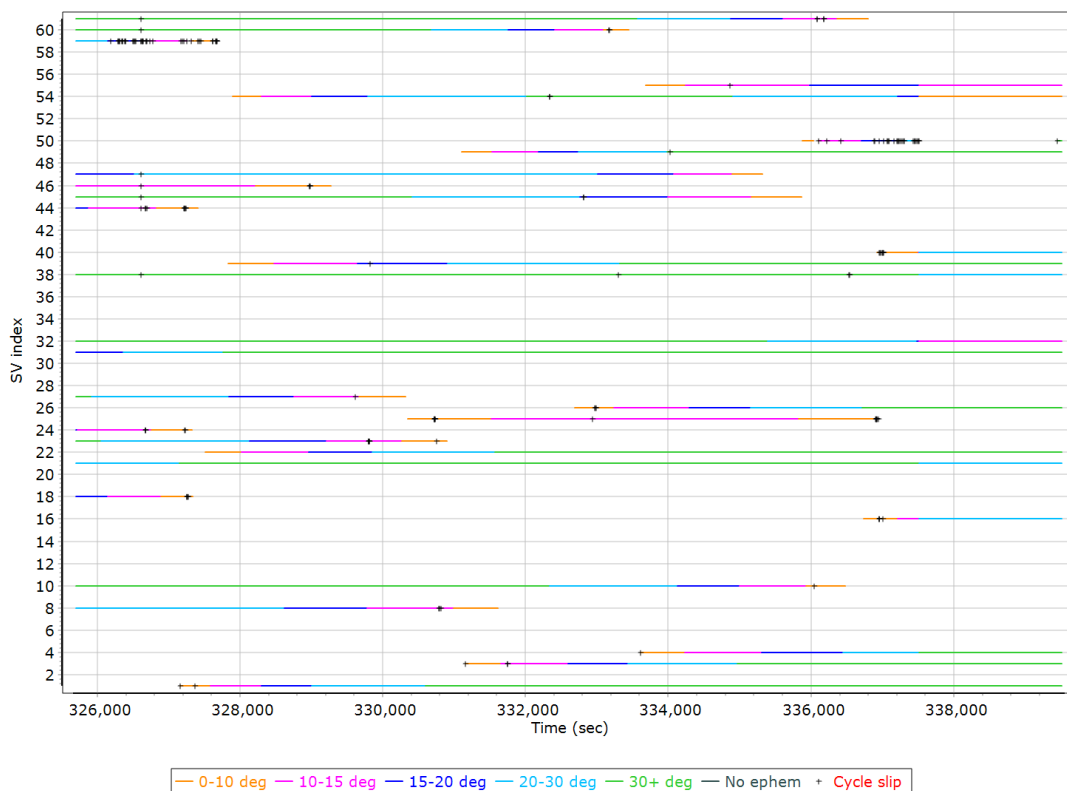
## Rover Data QC

### Raw IMU Import QC Summary

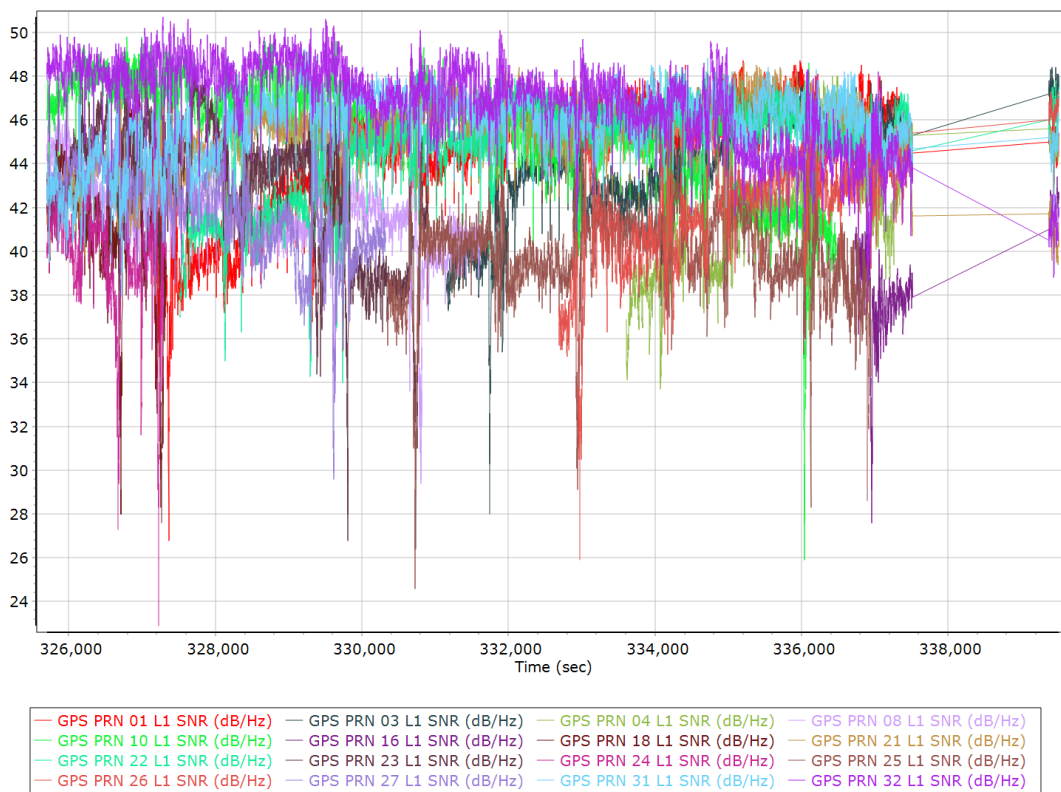
IMU data input file	imu_211020_A_5060420_nad2011_FINAL.dat
IMU data check log file	imudt_211020_A_5060420_nad2011_FINAL.log
IMU Records Processed	2389294
Termination Status	Warnings
IMU Anomalies	1
<b>IMU Failure Messages</b>	
339377.038 : WARNING : Gap of 1859.6355 seconds in CHECKDT input data	

## Primary Observables & Satellite Data

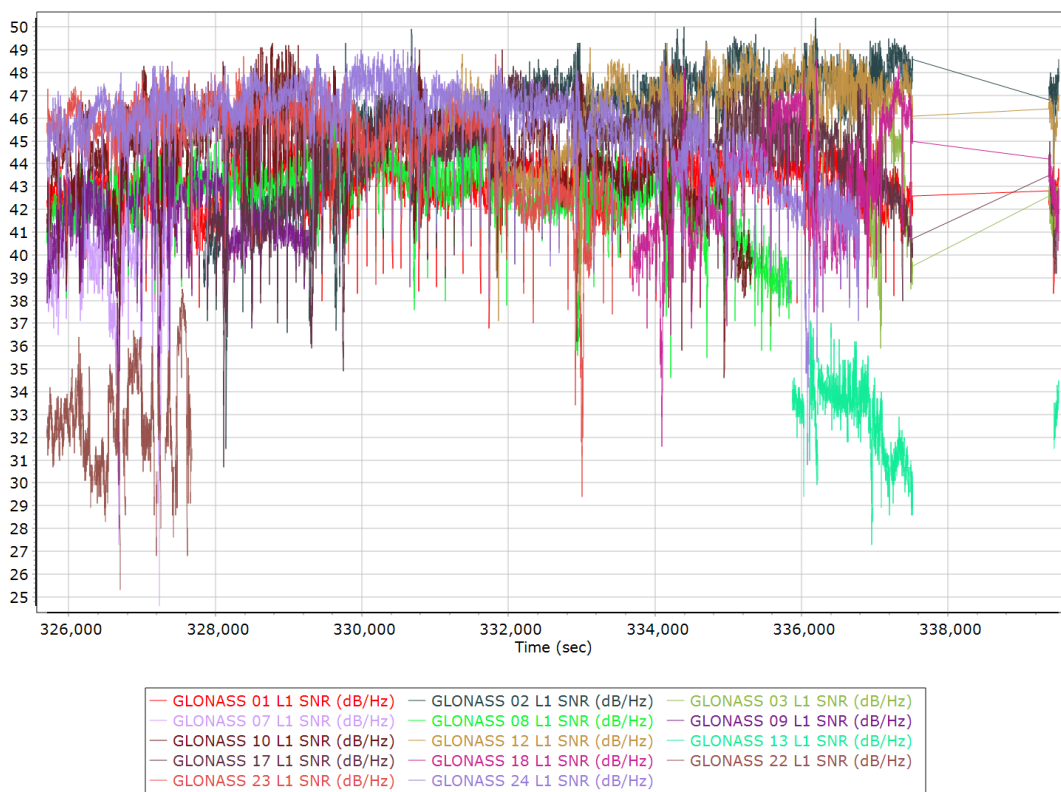
### GPS/GLONASS L1 Satellite Lock/Elevation



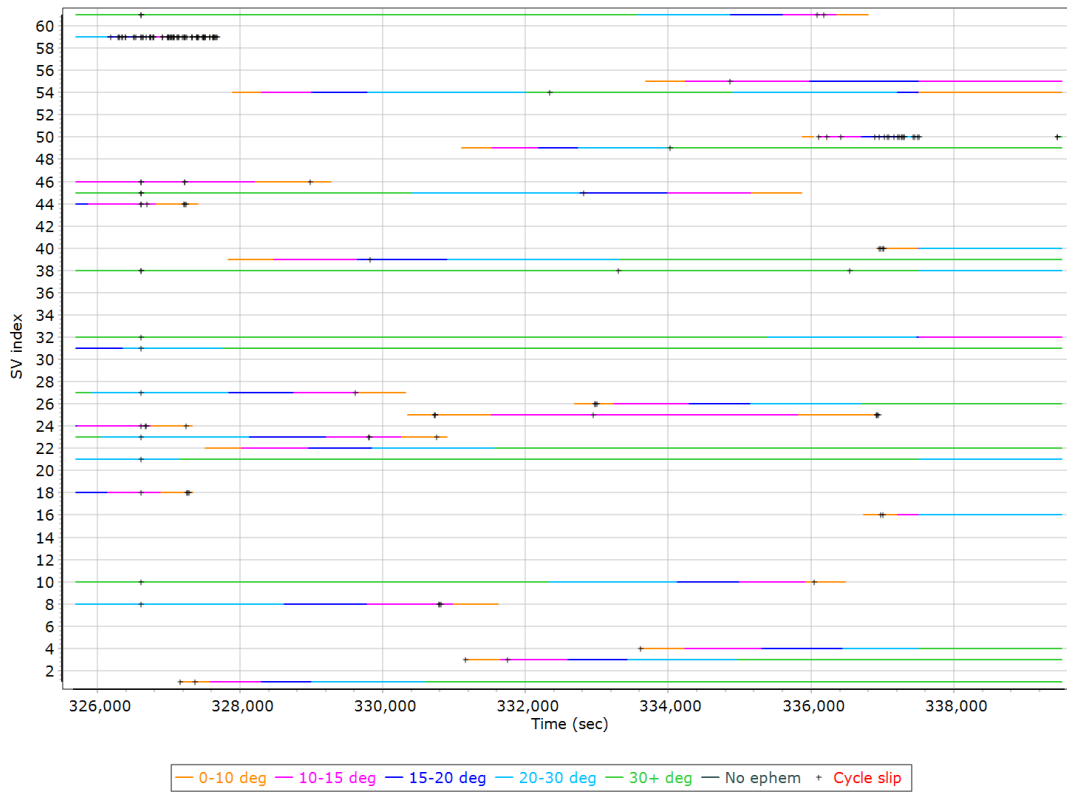
### GPS L1 SNR



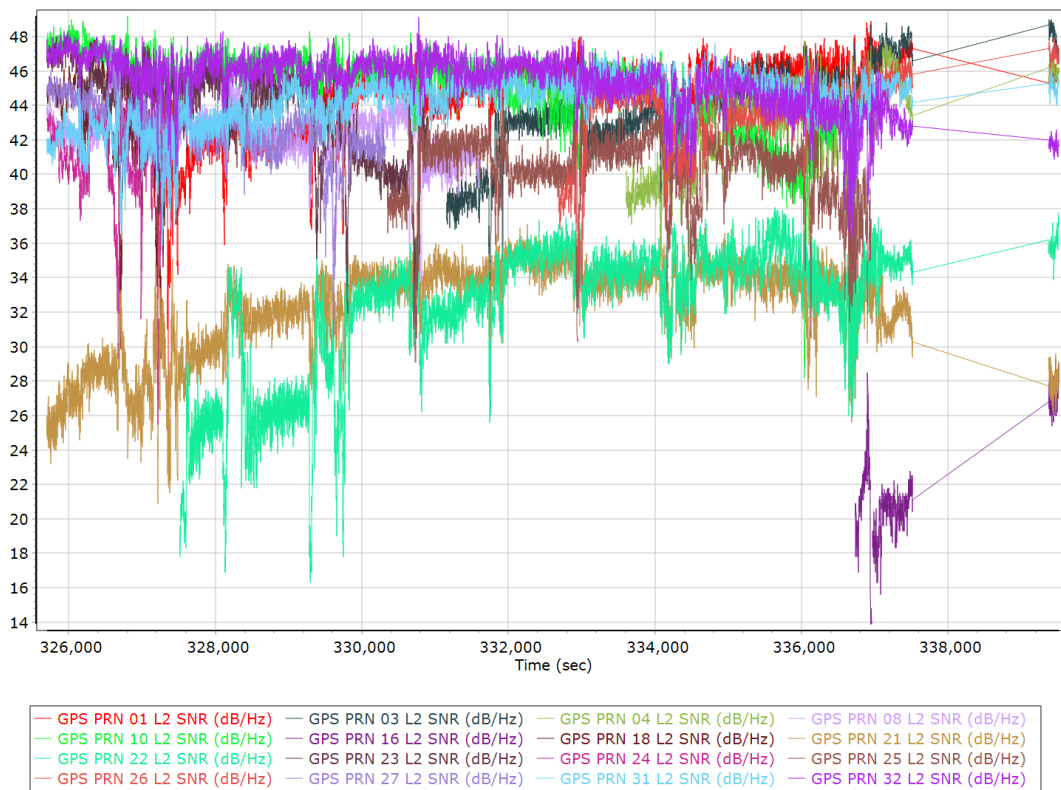
### GLONASS L1 SNR



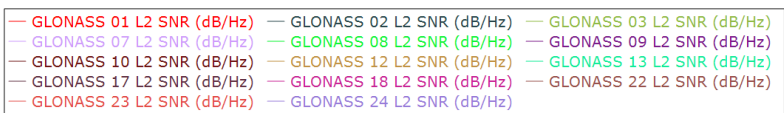
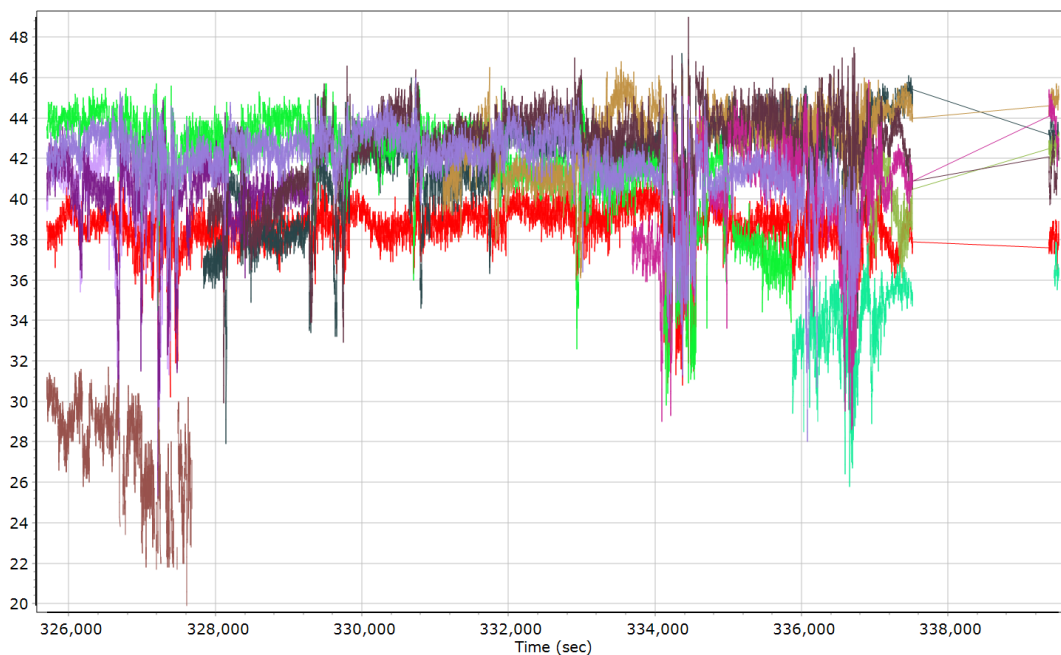
### GPS/GLONASS L2 Satellite Lock/Elevation



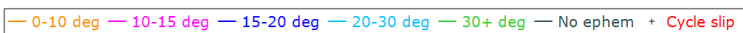
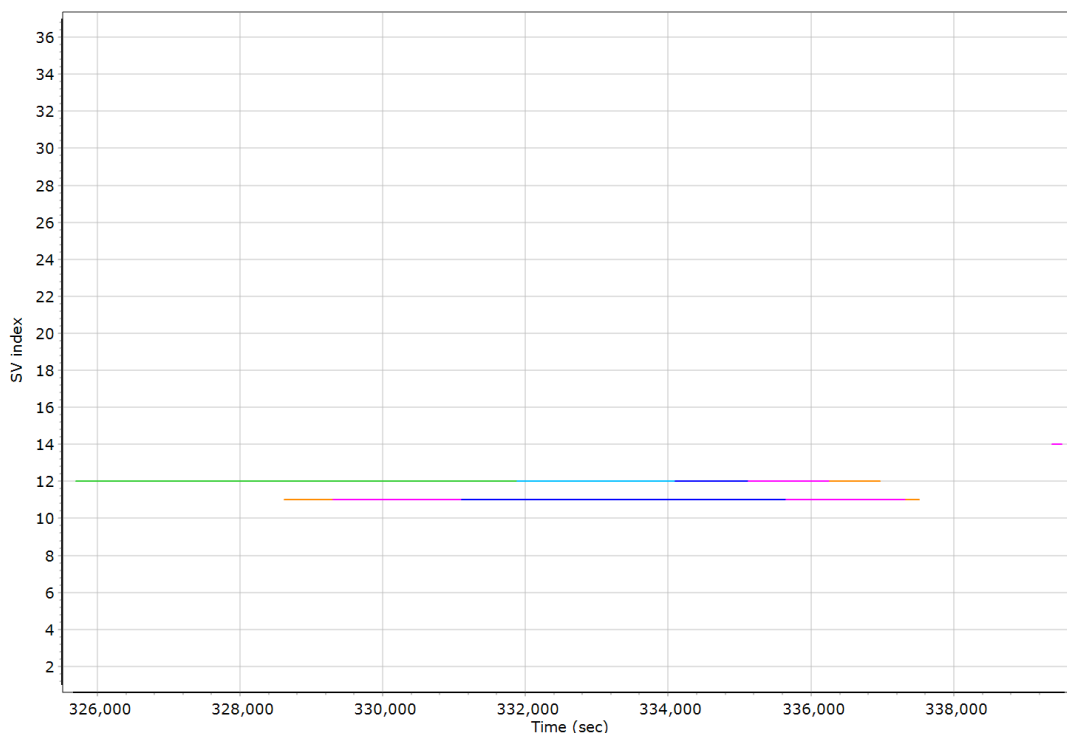
### GPS L2 SNR



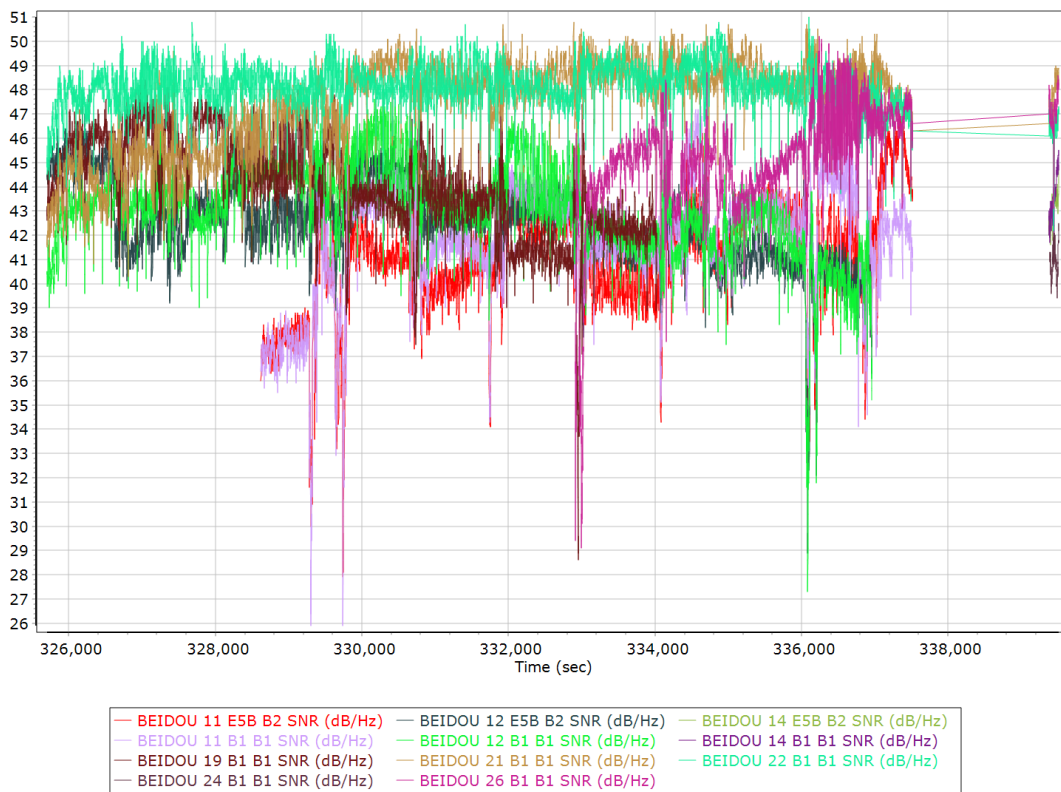
### GLONASS L2 SNR



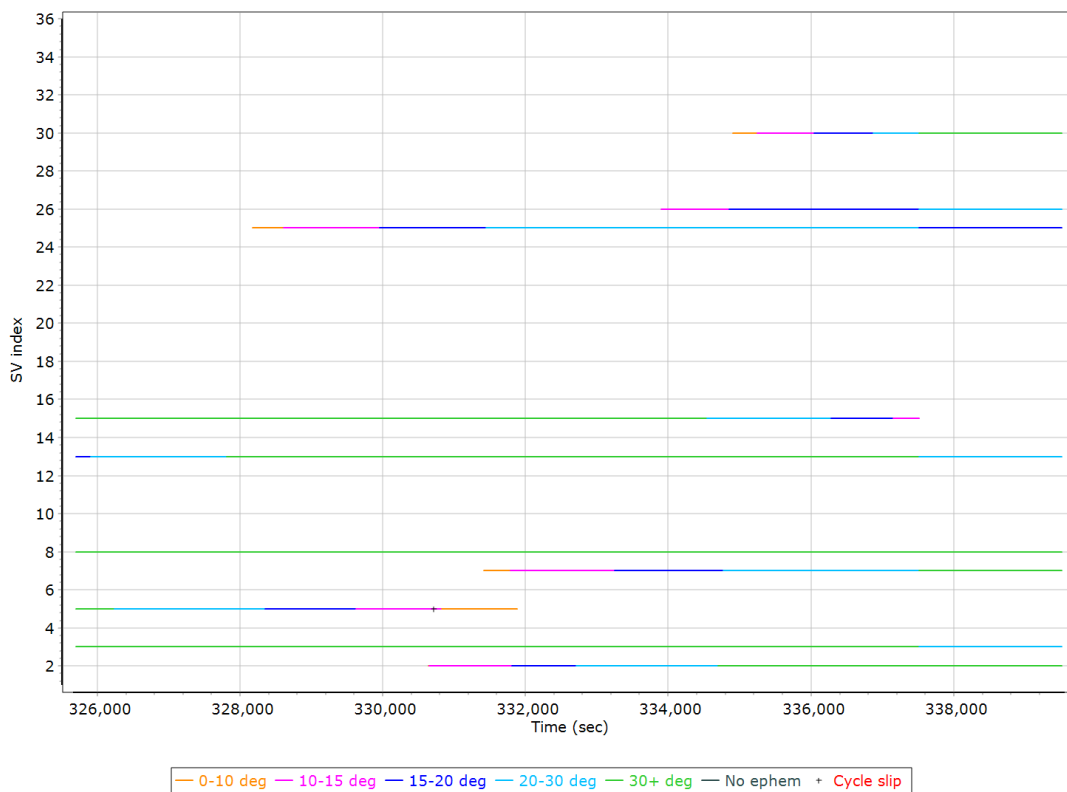
### BEIDOU Satellite Lock/Elevation



### BEIDOU SNR

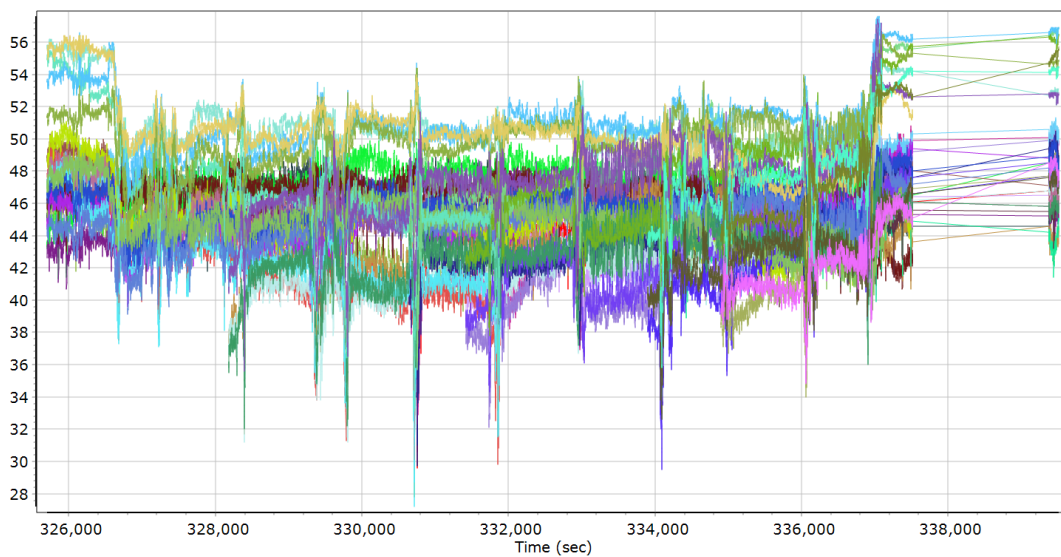


### GALILEO Satellite Lock/Elevation





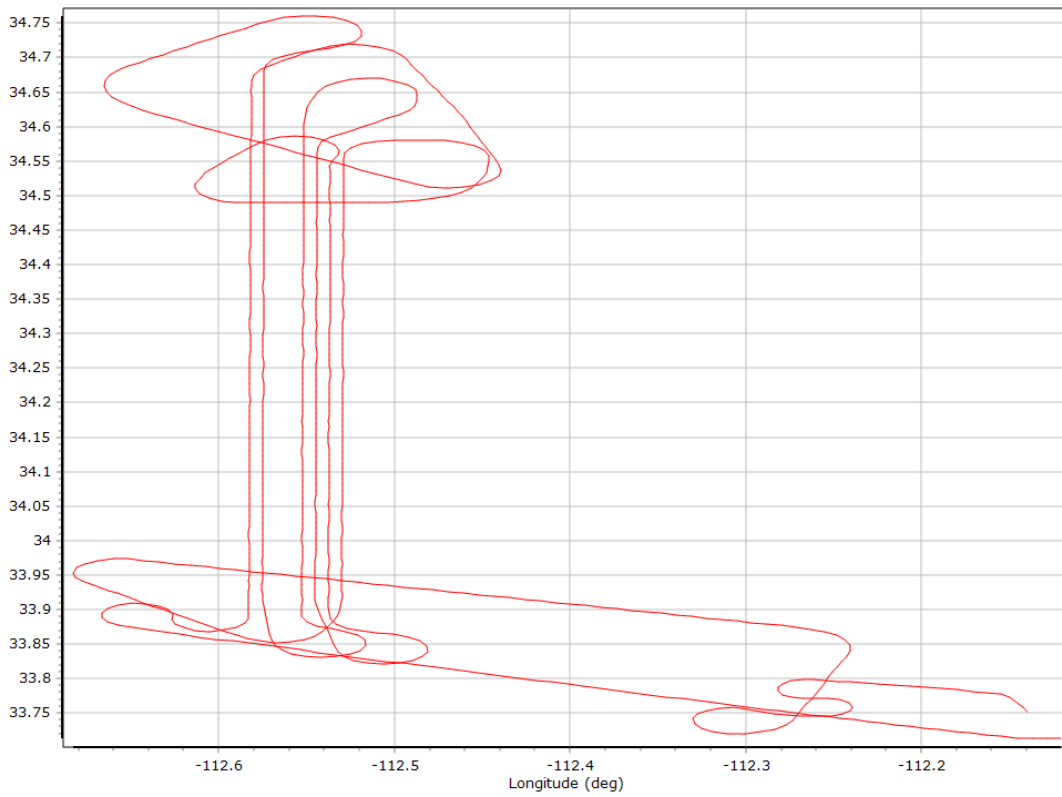
## GALILEO SNR



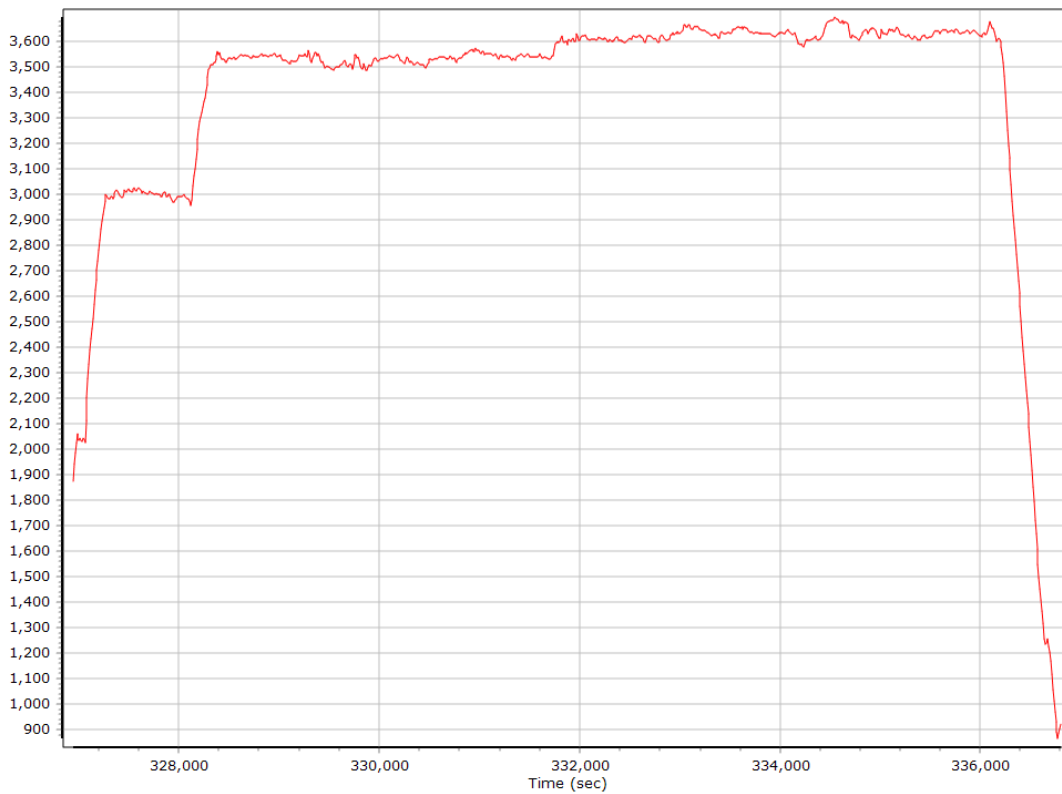
— GALILEO 02 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 03 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 05 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 07 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 08 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 13 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 15 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 25 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 26 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 30 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 02 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 03 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 05 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 07 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 08 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 13 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 15 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 25 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 26 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 30 L5E5A BPSK10_PD SNR (dB/Hz)

## Smoothed Trajectory Information

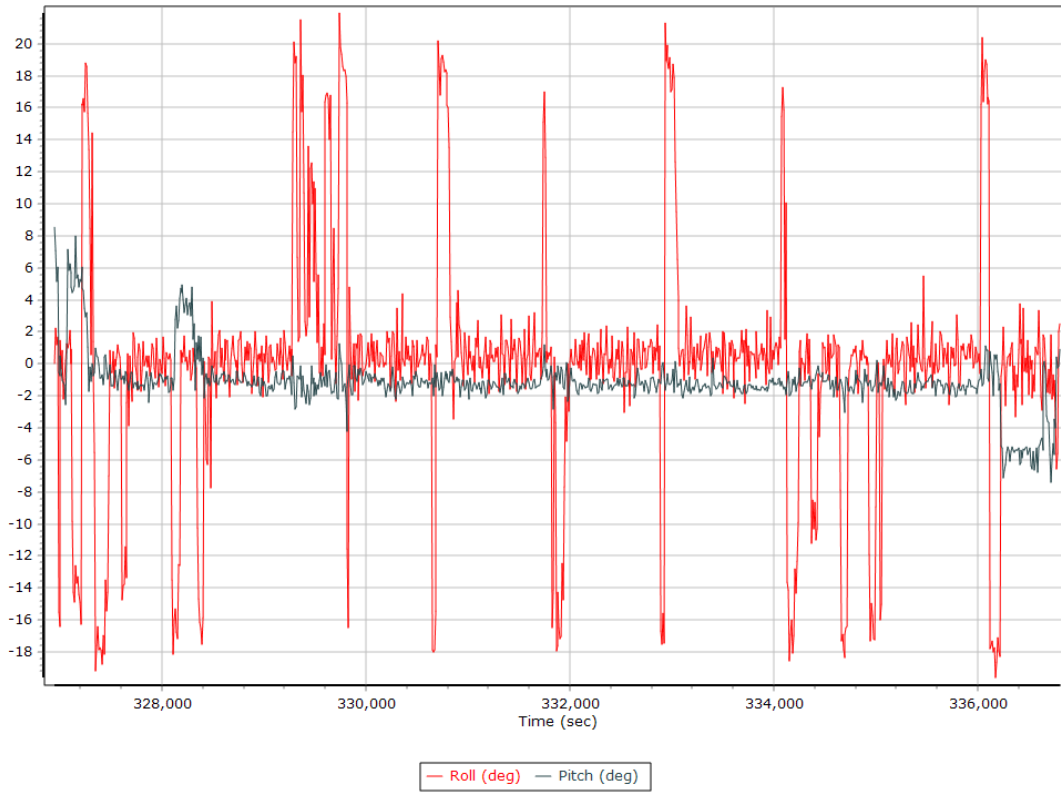
### Top View



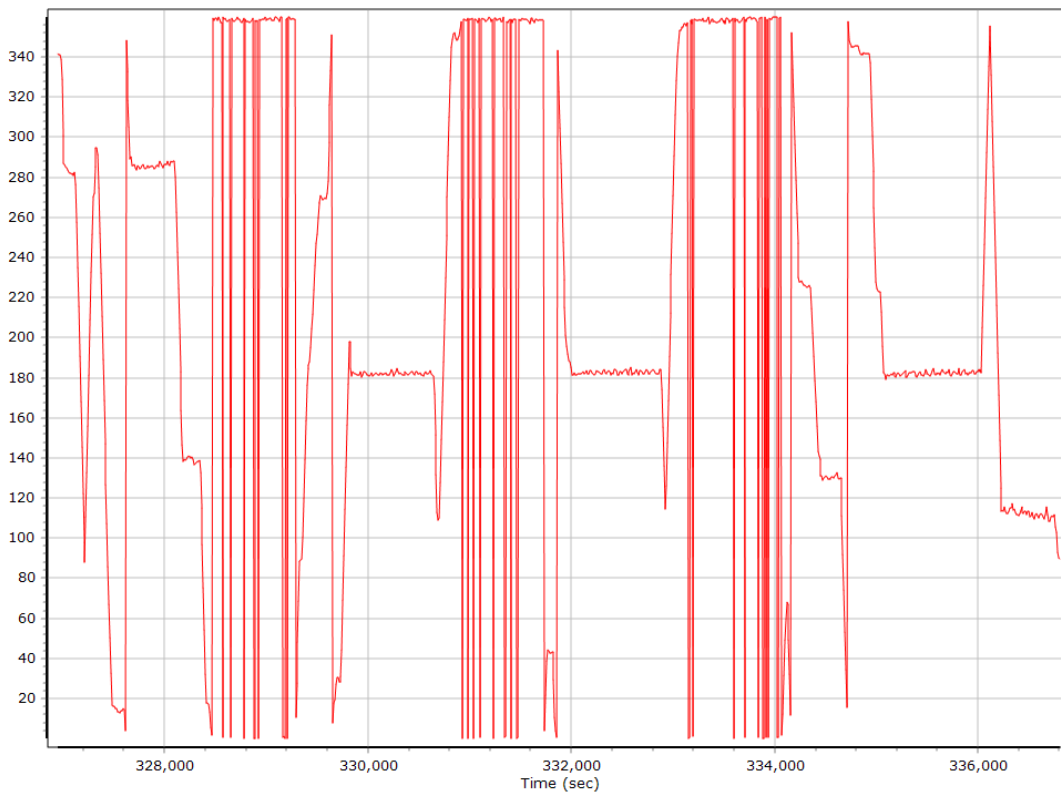
### Altitude



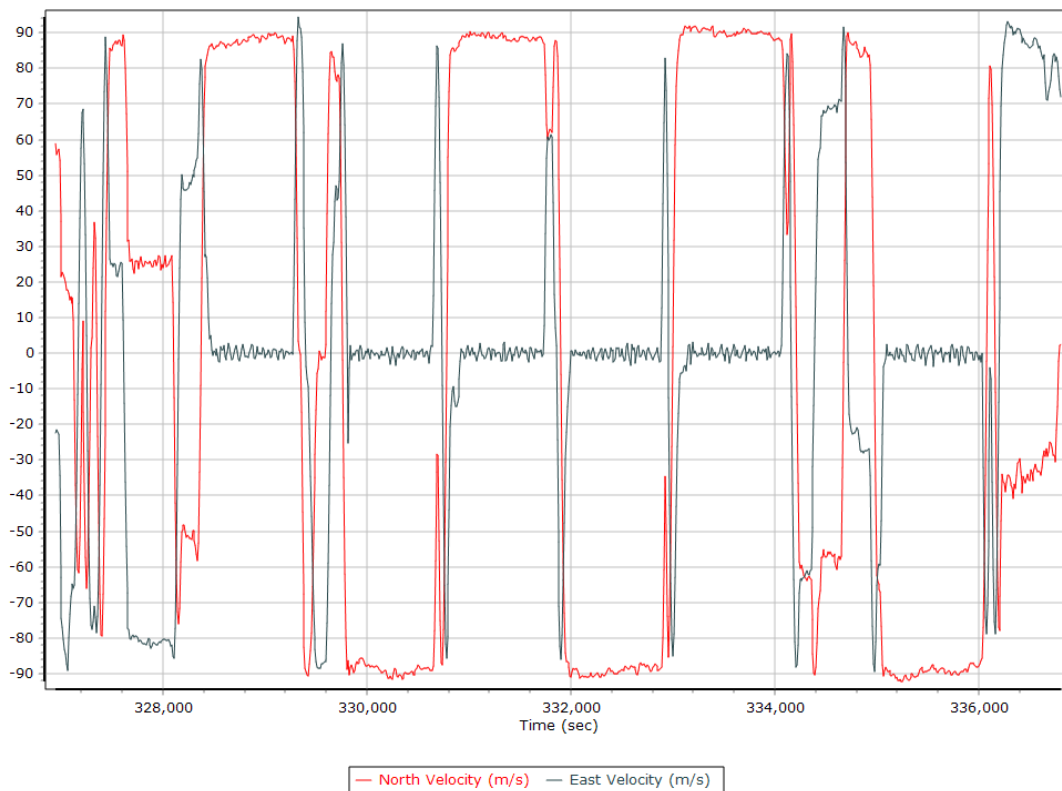
## Roll/Pitch



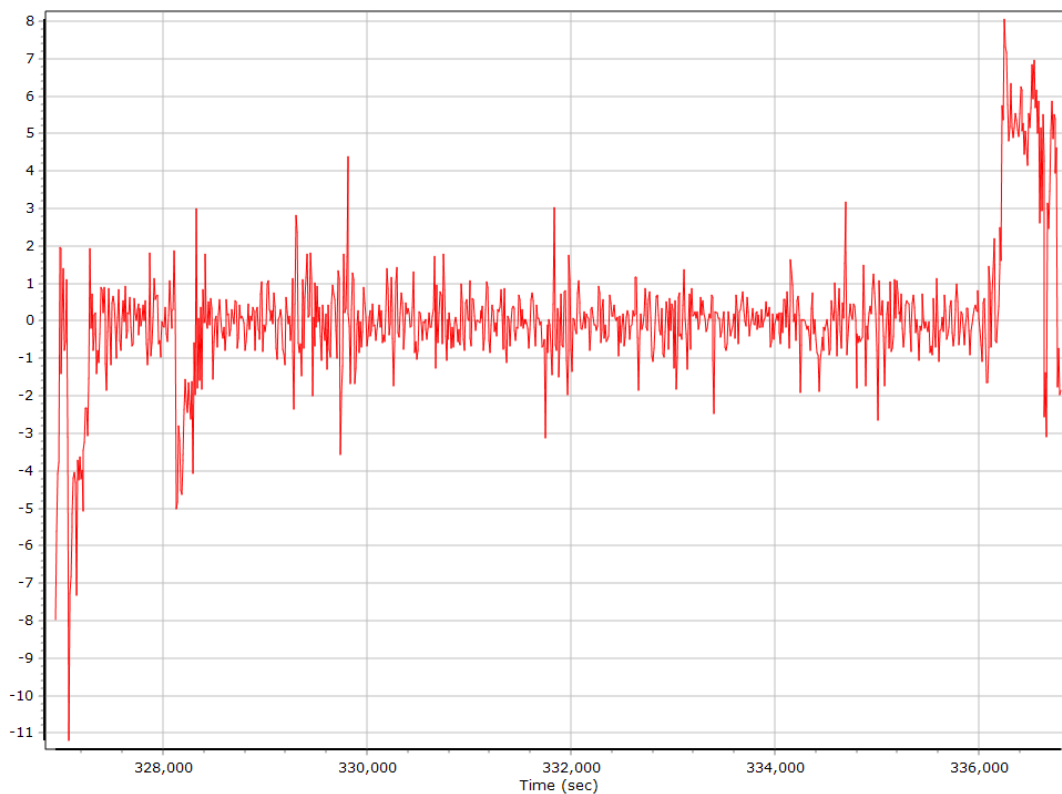
## Heading



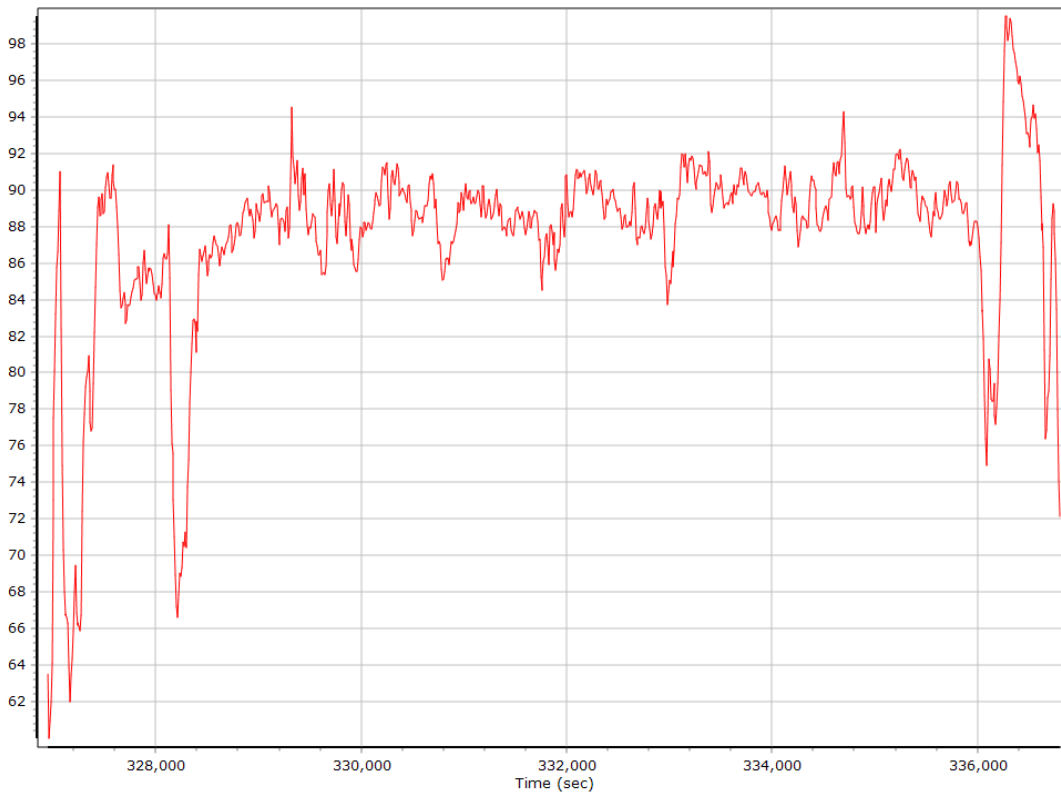
### North/East Velocity



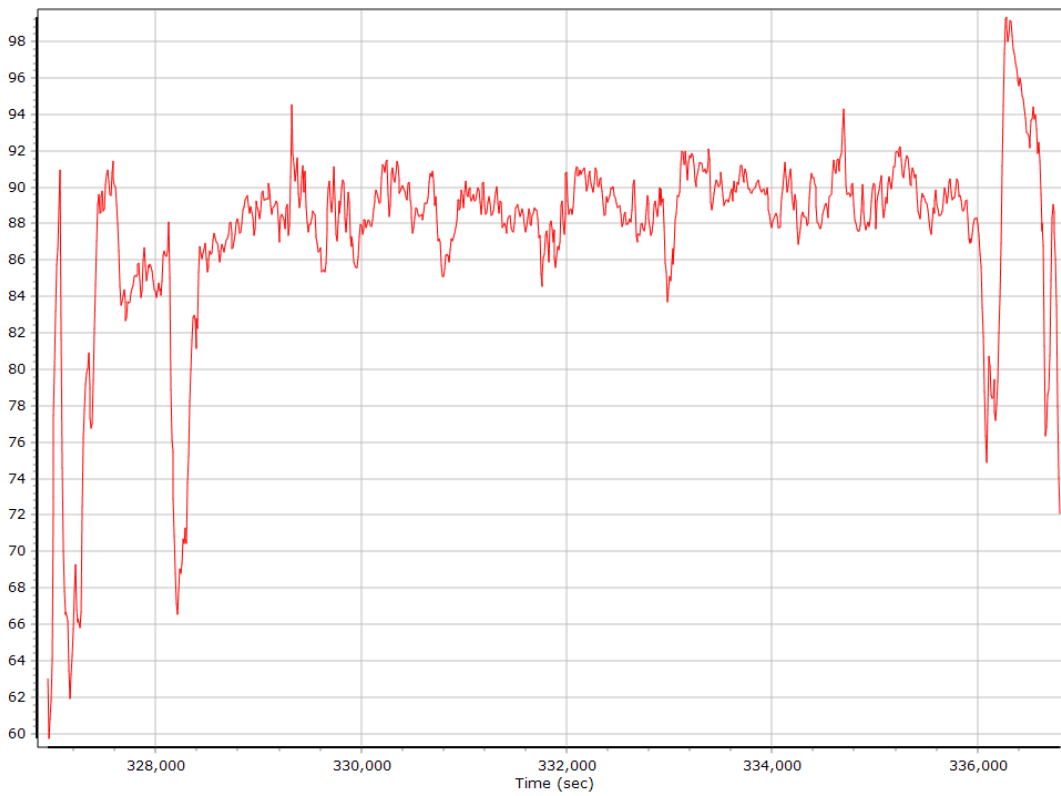
### Down Velocity



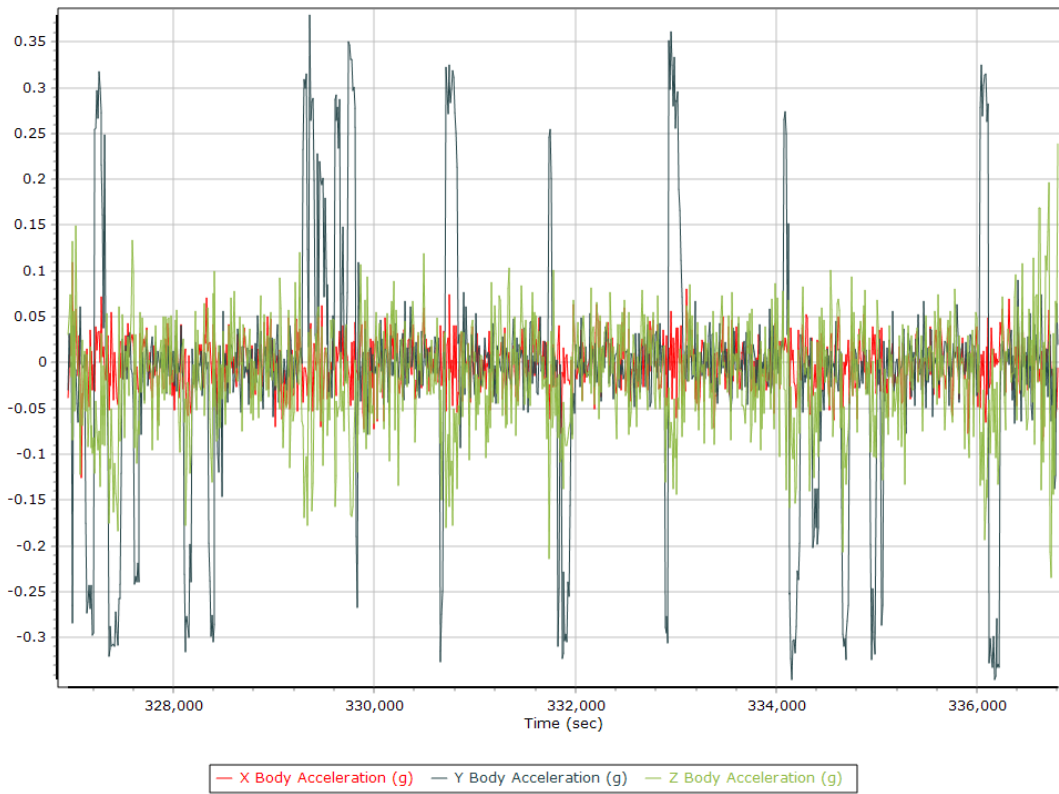
## Total Speed



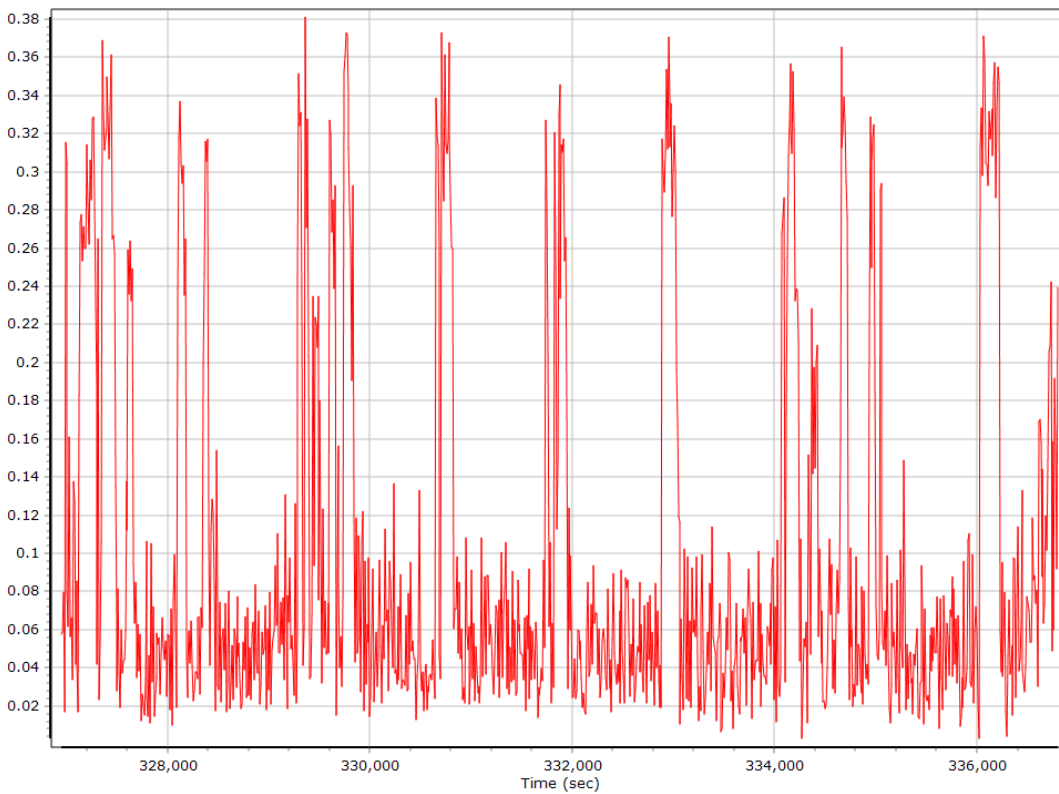
## Ground Speed



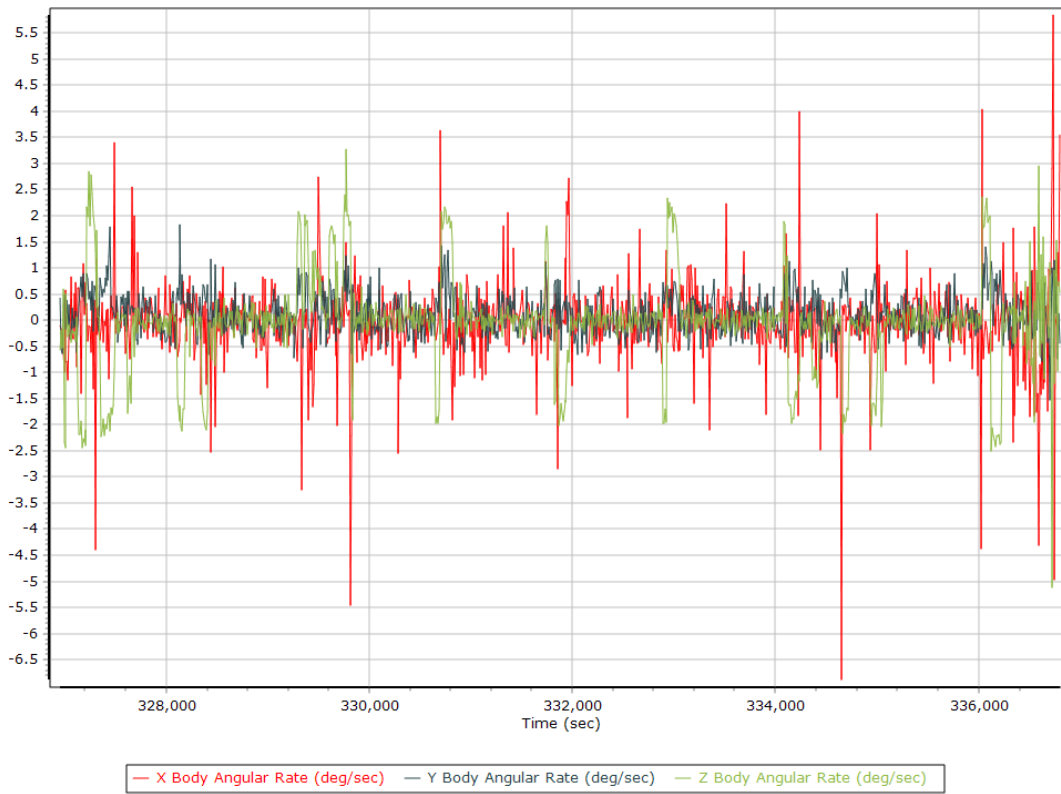
## Body Acceleration



## Total Body Acceleration

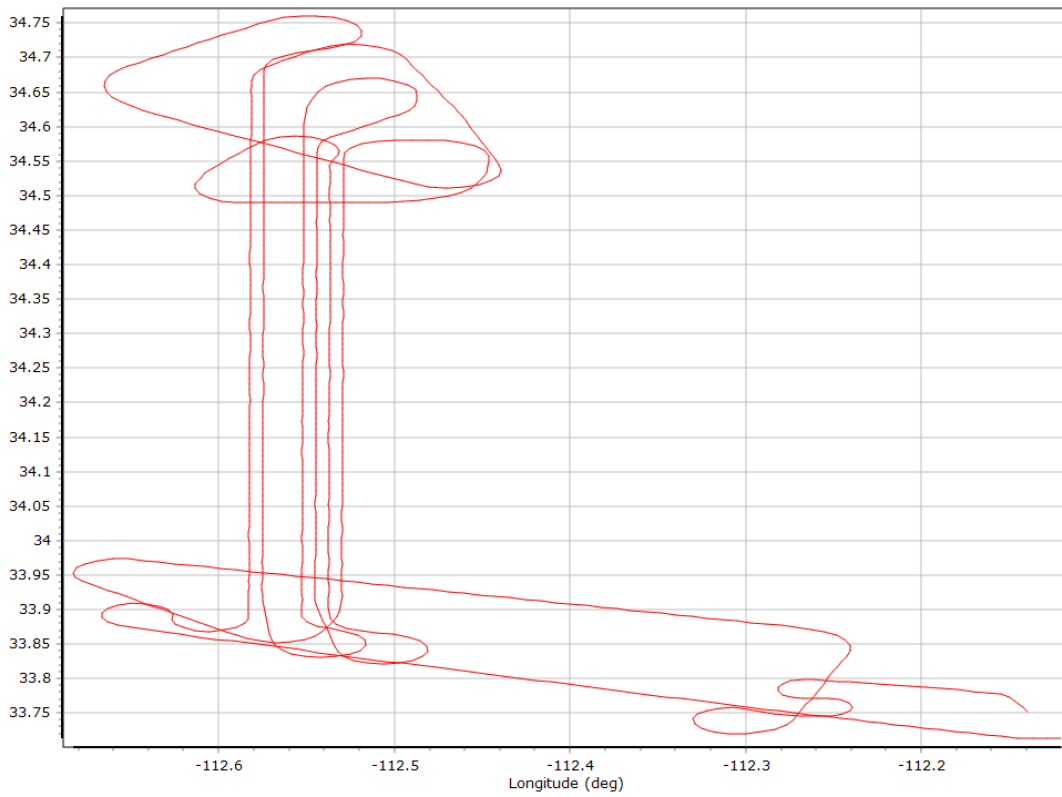


## Body Angular Rate

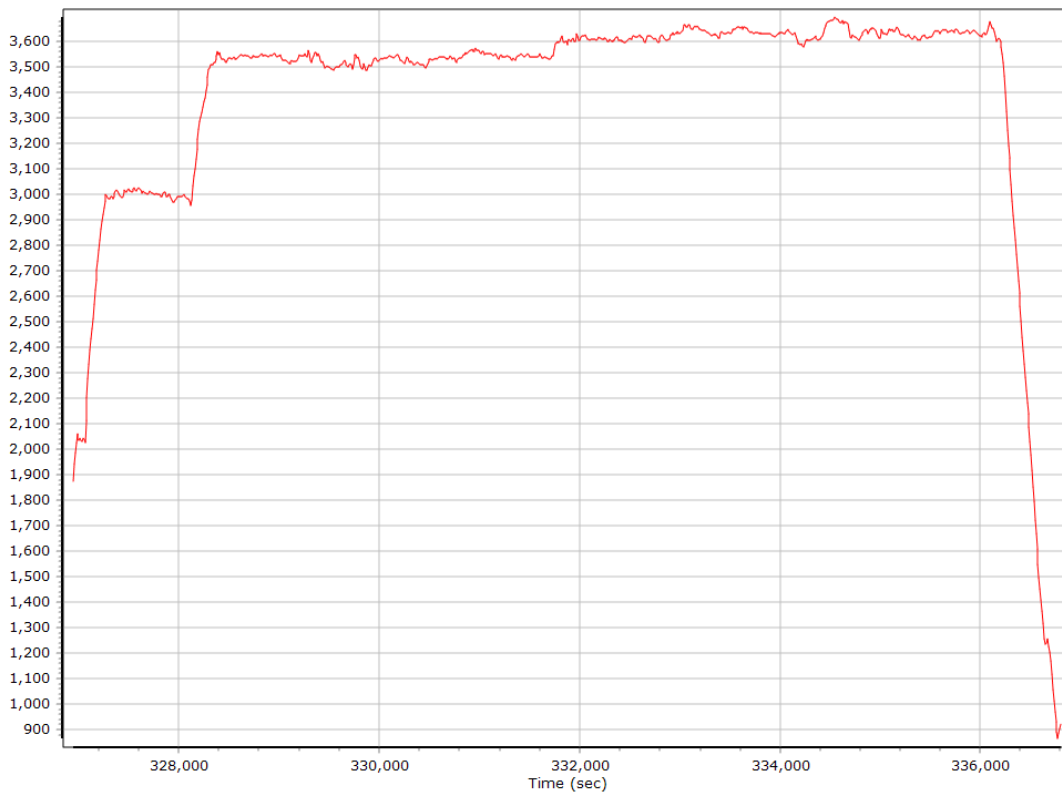


## Forward Processed Trajectory Information

### Top View

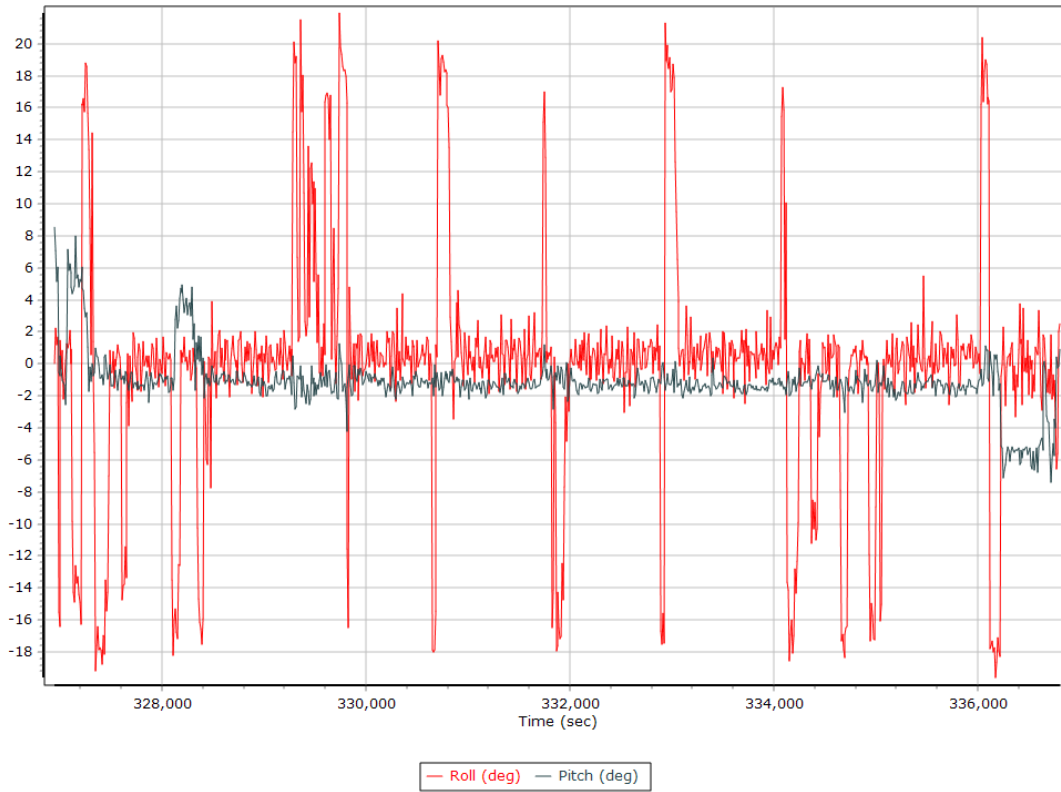


### Altitude

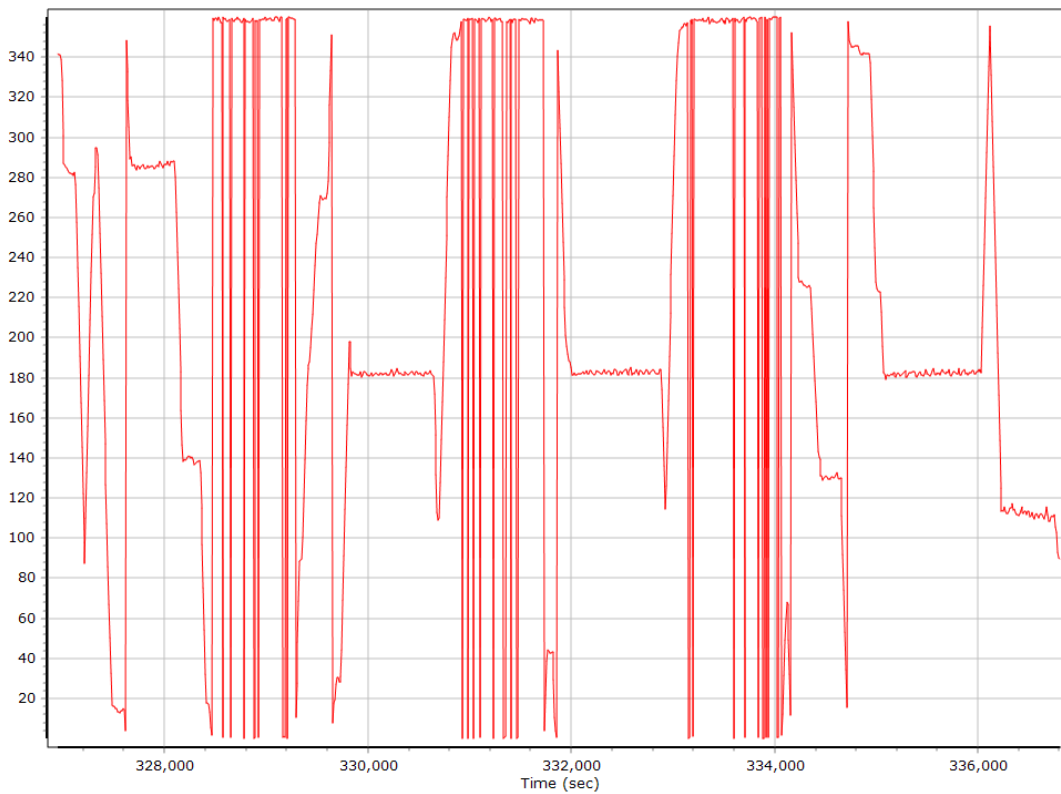




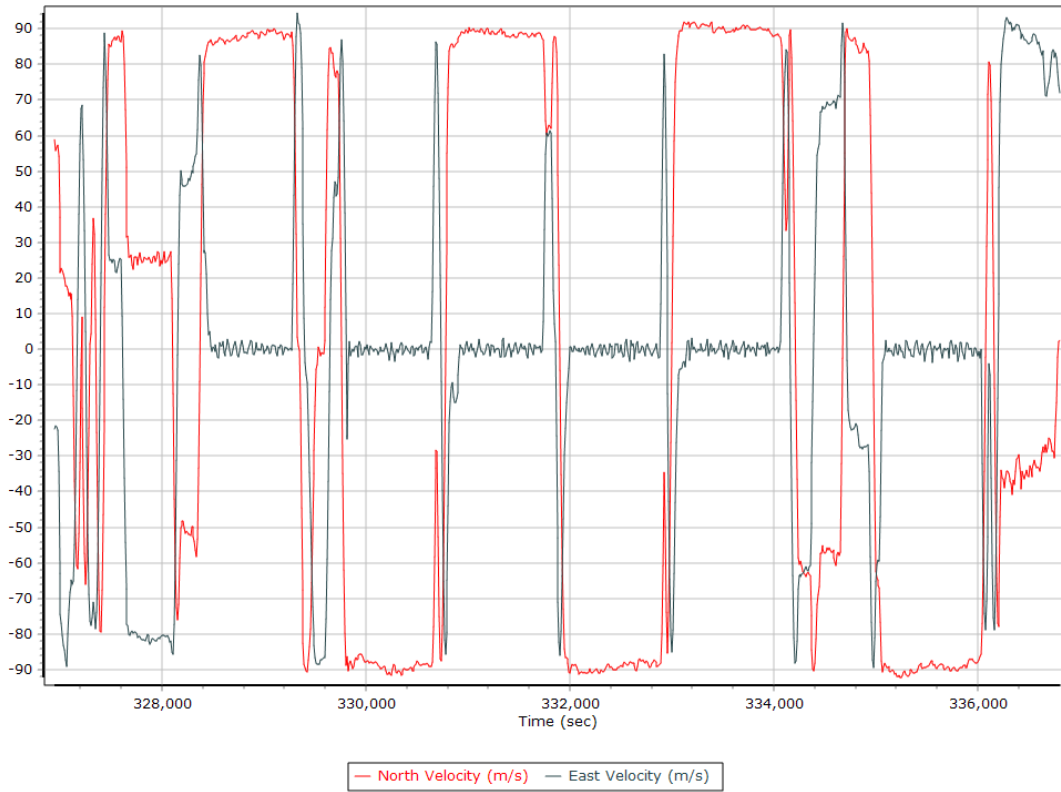
## Roll/Pitch



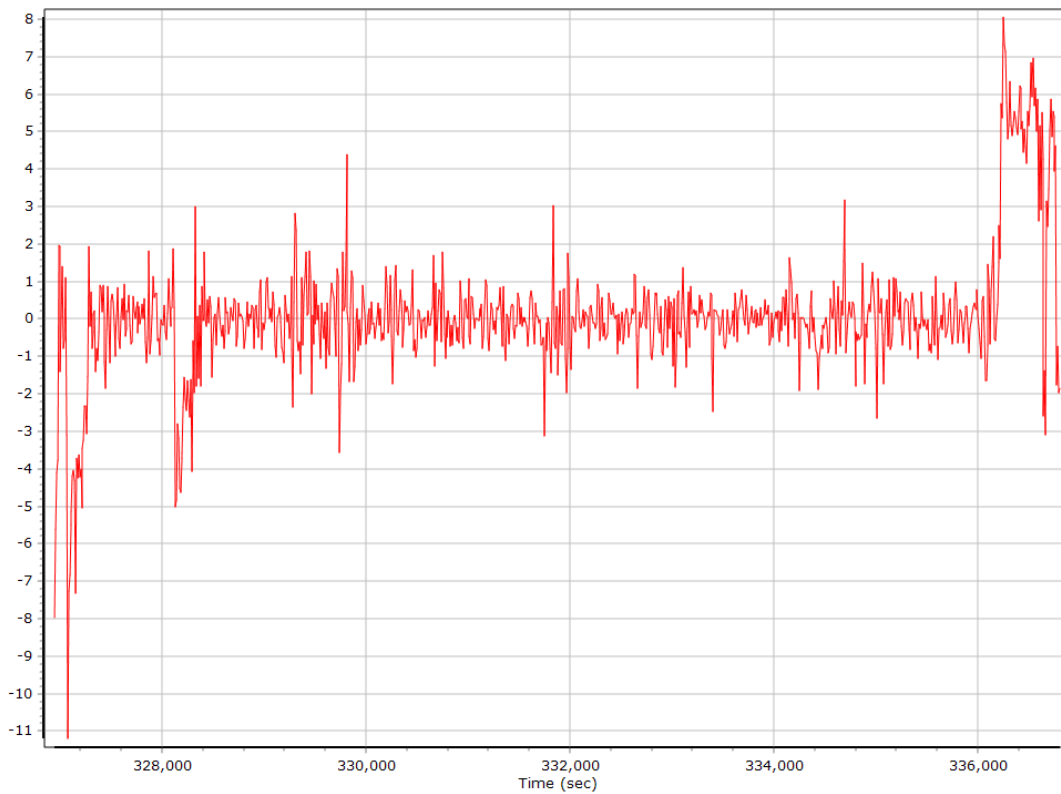
## Heading



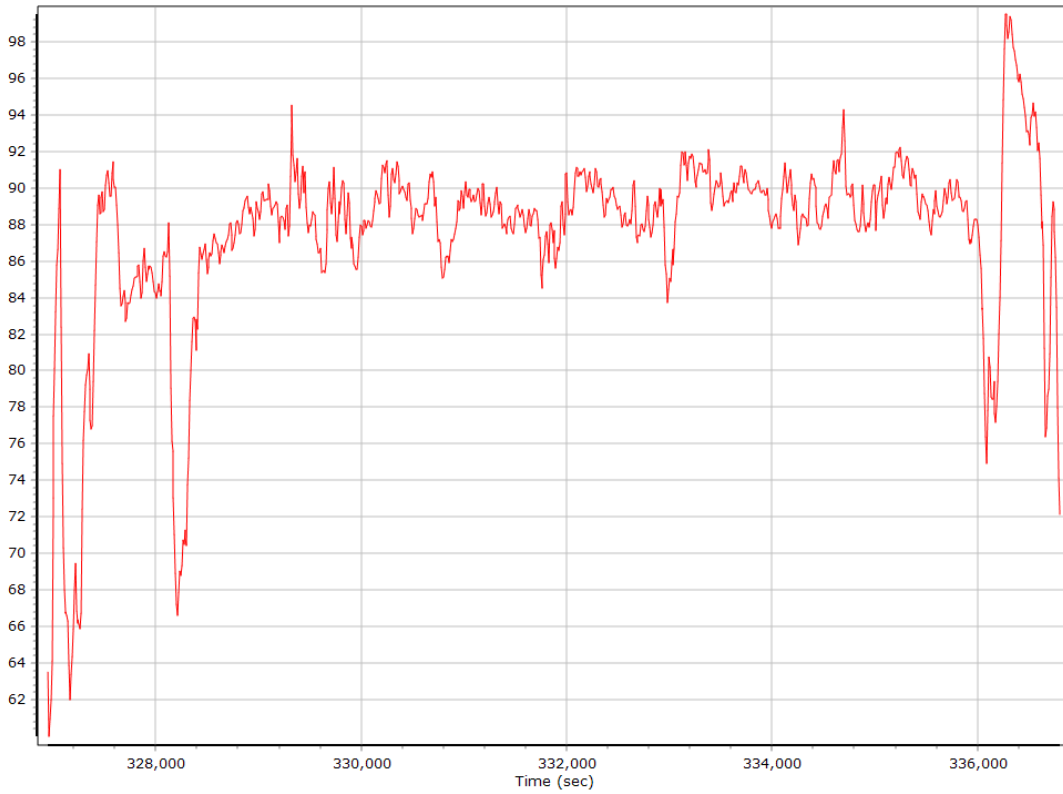
## North/East Velocity



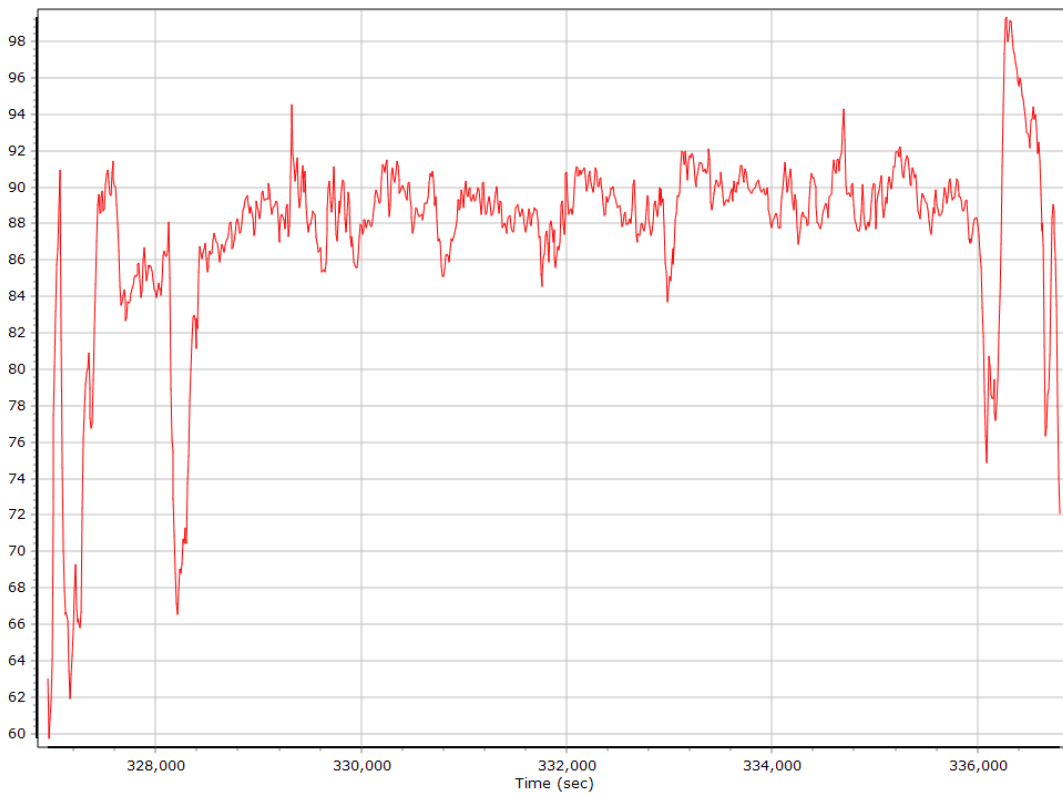
## Down Velocity



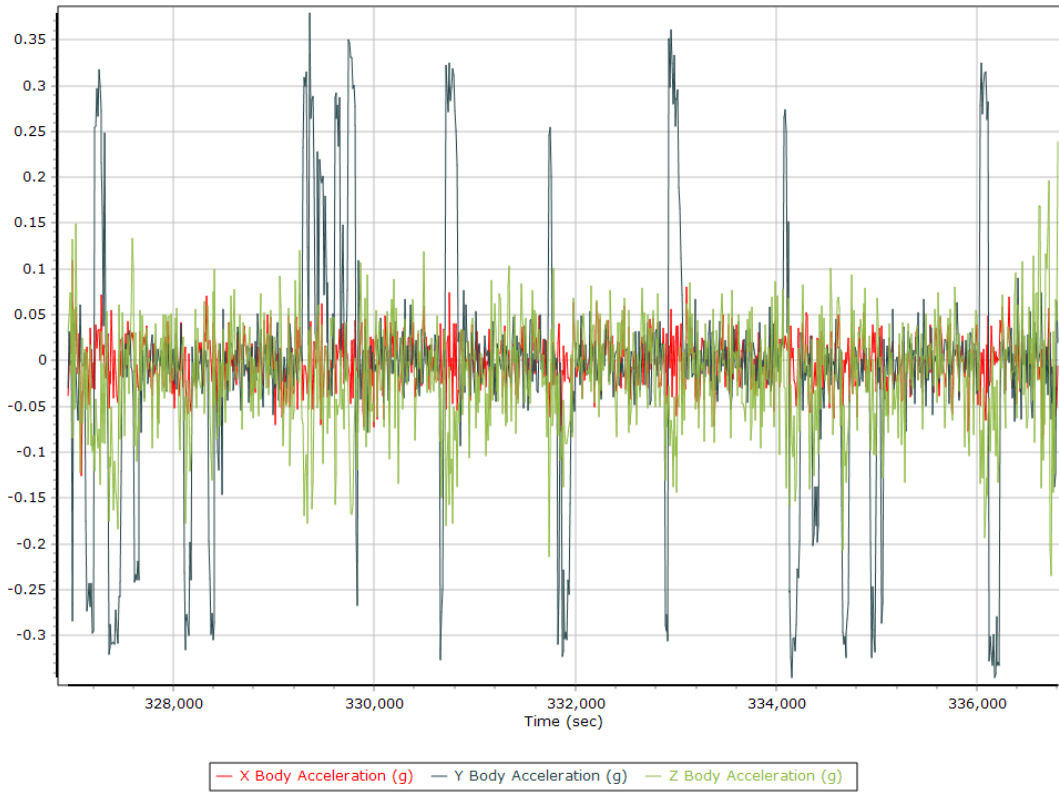
## Total Speed



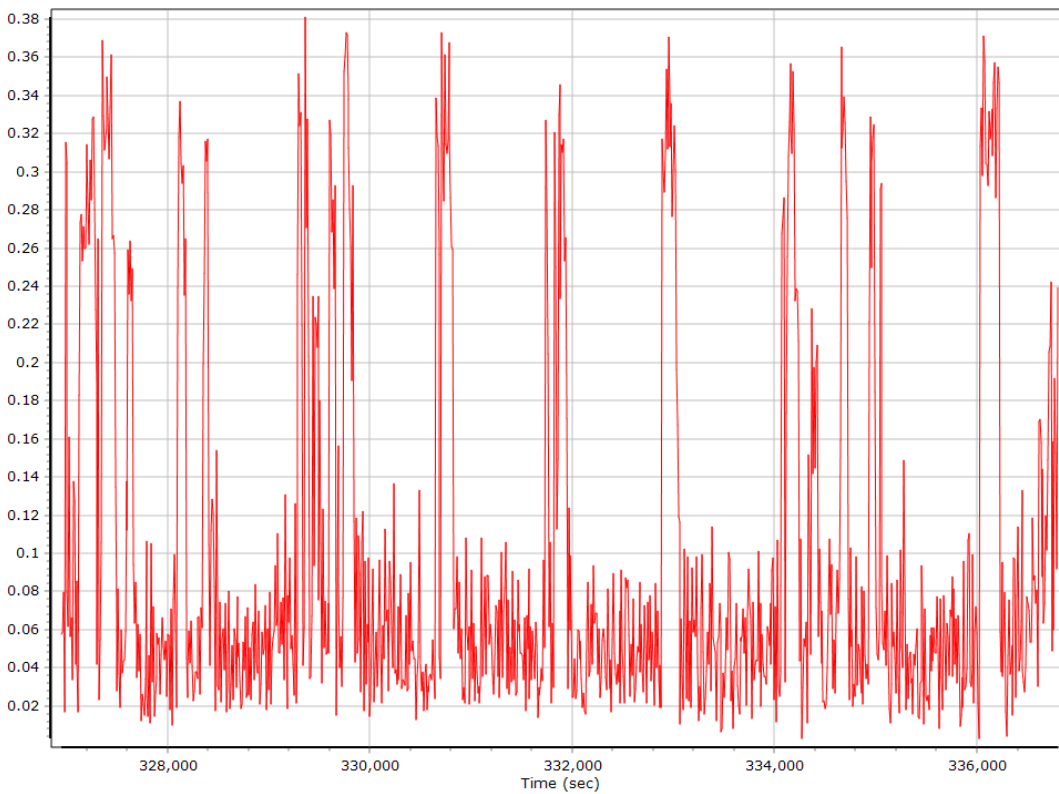
## Ground Speed



## Body Acceleration



## Total Body Acceleration



## Body Angular Rate

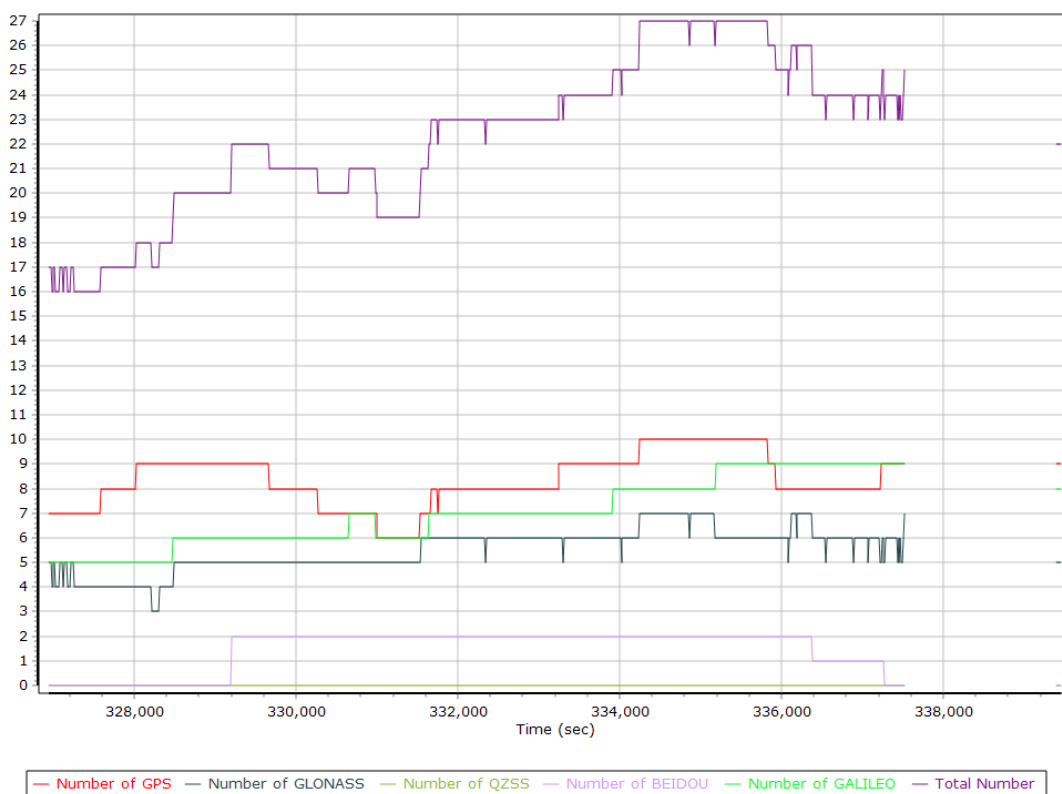


## GNSS QC

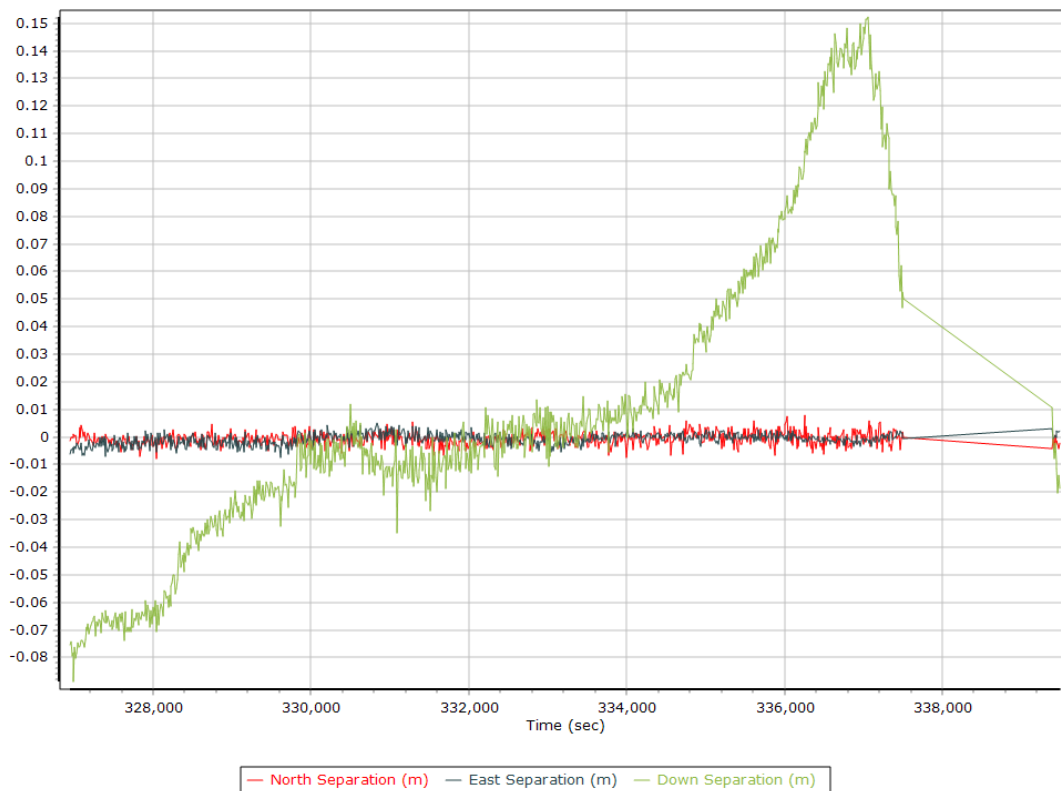
### GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	4	10	8
Number of GLONASS SV	0	7	6
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	2	1
Number of GALILEO SV	4	9	7
Total number of SV	12	27	22
PDOP	1.04	2.52	1.20
QC Solution Gaps	1.00	1866.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	11878.00	0.00	1869.00
Percentage	86.40	0.00	13.60

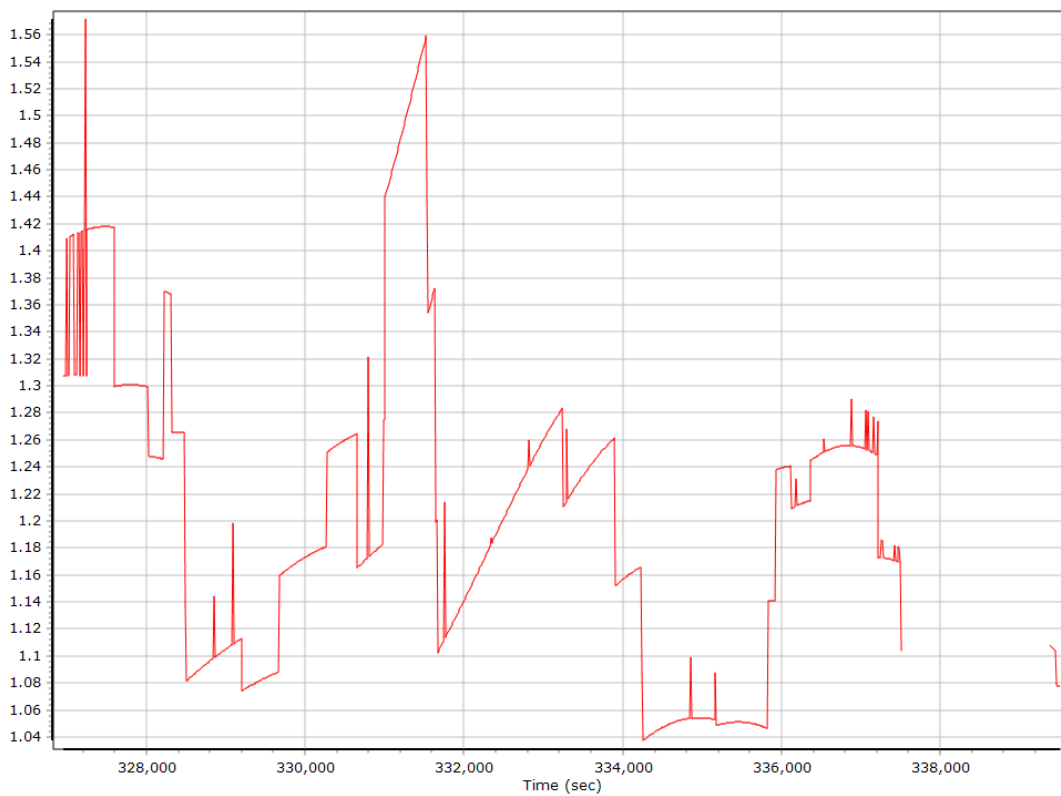
### Num SVs in solution



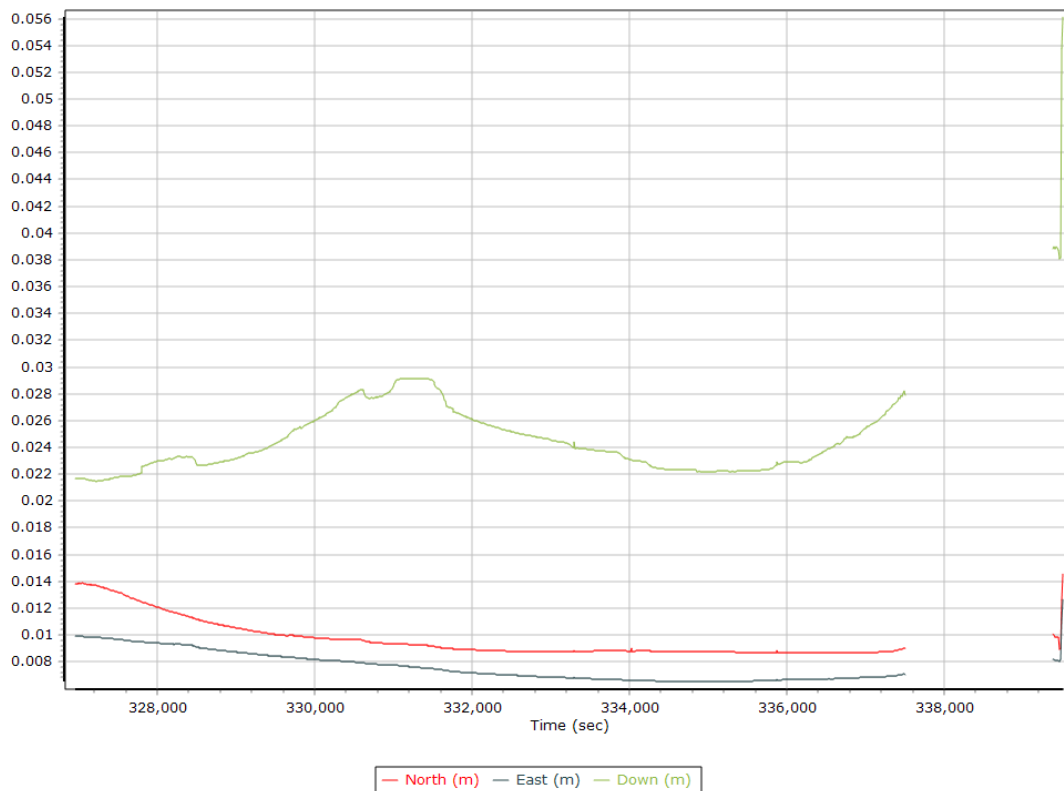
### Forward/Reverse Separation



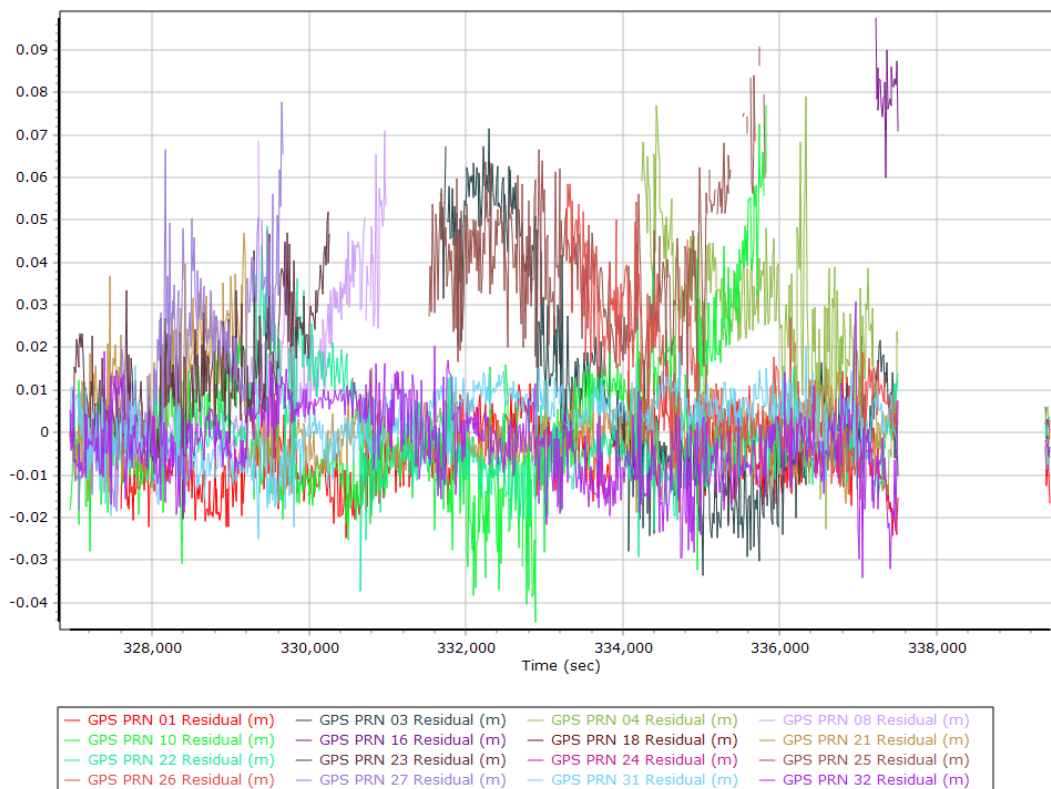
### PDOP



## Estimated Position Accuracy

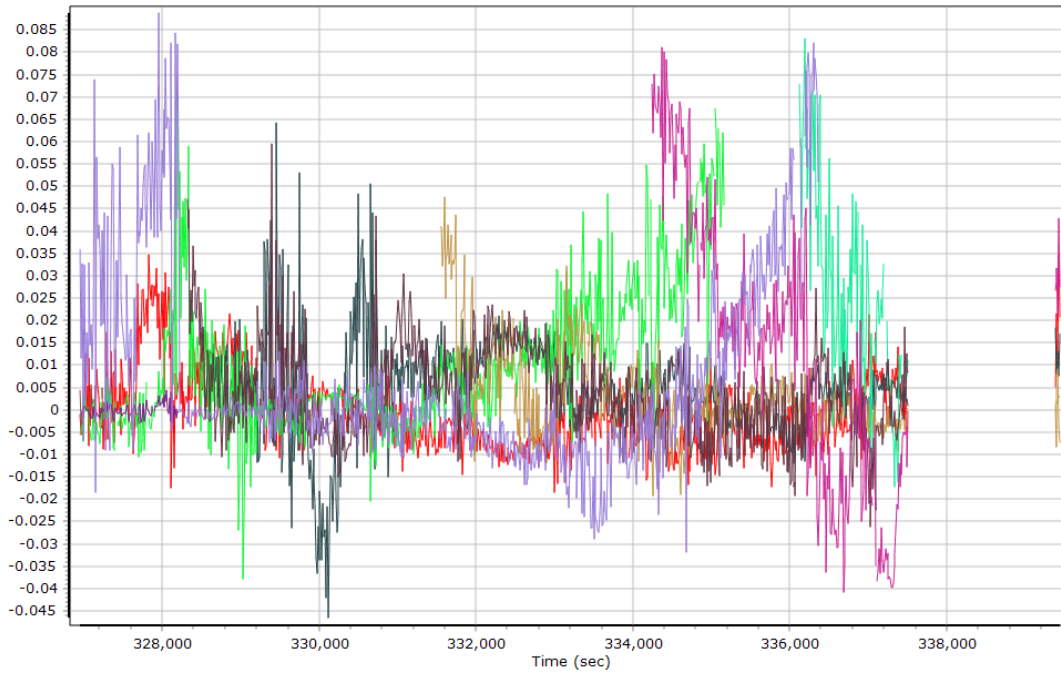


## GPS Residuals



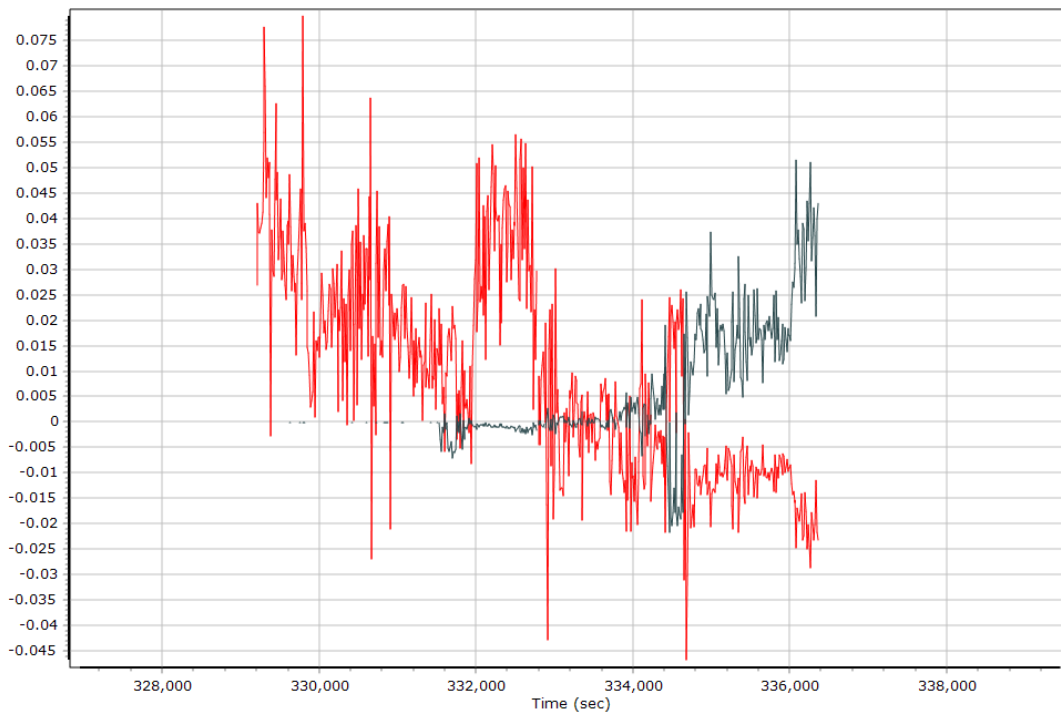


## GLONASS Residuals



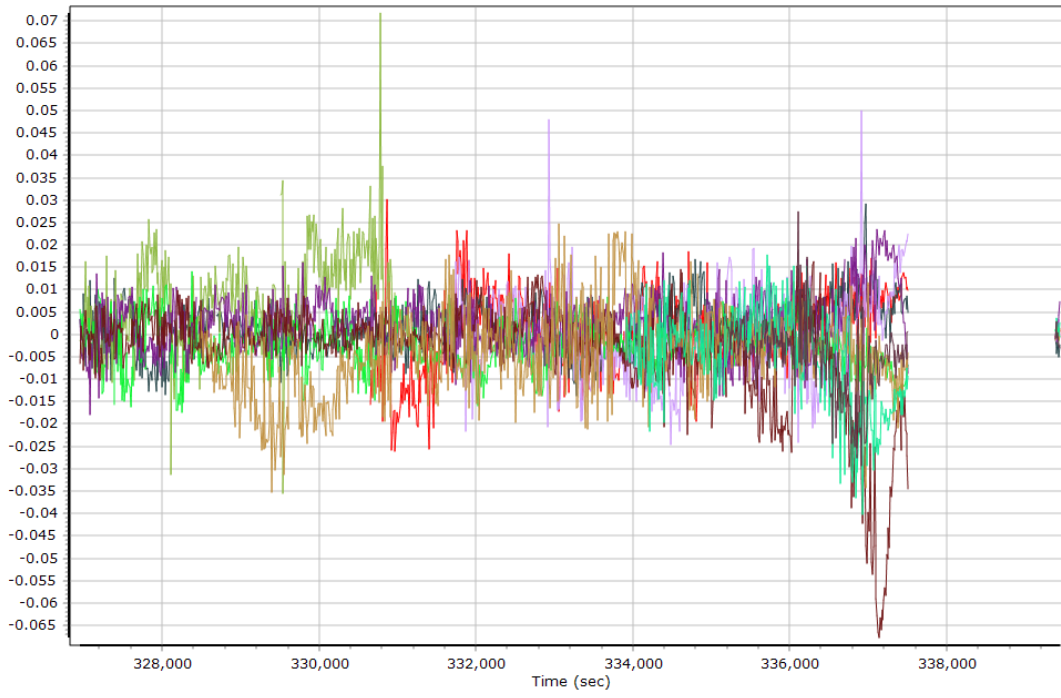
- GLONASS 01 Residual (m)
- GLONASS 02 Residual (m)
- GLONASS 03 Residual (m)
- GLONASS 07 Residual (m)
- GLONASS 08 Residual (m)
- GLONASS 09 Residual (m)
- GLONASS 10 Residual (m)
- GLONASS 12 Residual (m)
- GLONASS 13 Residual (m)
- GLONASS 17 Residual (m)
- GLONASS 18 Residual (m)
- GLONASS 22 Residual (m)
- GLONASS 23 Residual (m)
- GLONASS 24 Residual (m)

## BEIDOU Residuals



- BEIDOU 11 Residual (m)
- BEIDOU 12 Residual (m)
- BEIDOU 19 Residual (m)
- BEIDOU 21 Residual (m)
- BEIDOU 22 Residual (m)
- BEIDOU 26 Residual (m)

## GALILEO Residuals



- |                         |                         |                         |                         |
|-------------------------|-------------------------|-------------------------|-------------------------|
| GALILEO 02 Residual (m) | GALILEO 03 Residual (m) | GALILEO 05 Residual (m) | GALILEO 07 Residual (m) |
| GALILEO 08 Residual (m) | GALILEO 13 Residual (m) | GALILEO 15 Residual (m) | GALILEO 25 Residual (m) |
| GALILEO 26 Residual (m) | GALILEO 30 Residual (m) |                         |                         |

## GNSS-Inertial Processor Configuration

Processing mode	IN-Fusion PP-RTX		
Stabilized mount	False		
Processing start time	326889.015 (10/20/2021 18:48:09)		
Processing end time	336805.816 (10/20/2021 21:33:25)		
Initial attitude source	Real-Time VNAV/RNAV Attitude		
IMU Sensor Context	Processing with Onboard IMU		
Reference to IMU lever arm (m)	0.000	0.000	0.000
Reference to IMU mounting angles (deg)	0.000	0.000	90.000
Reference to Primary GNSS lever arm (m)	-0.574	-0.062	-1.205
Reference to Primary GNSS lever arm std dev (m)	0.030	0.030	0.030
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

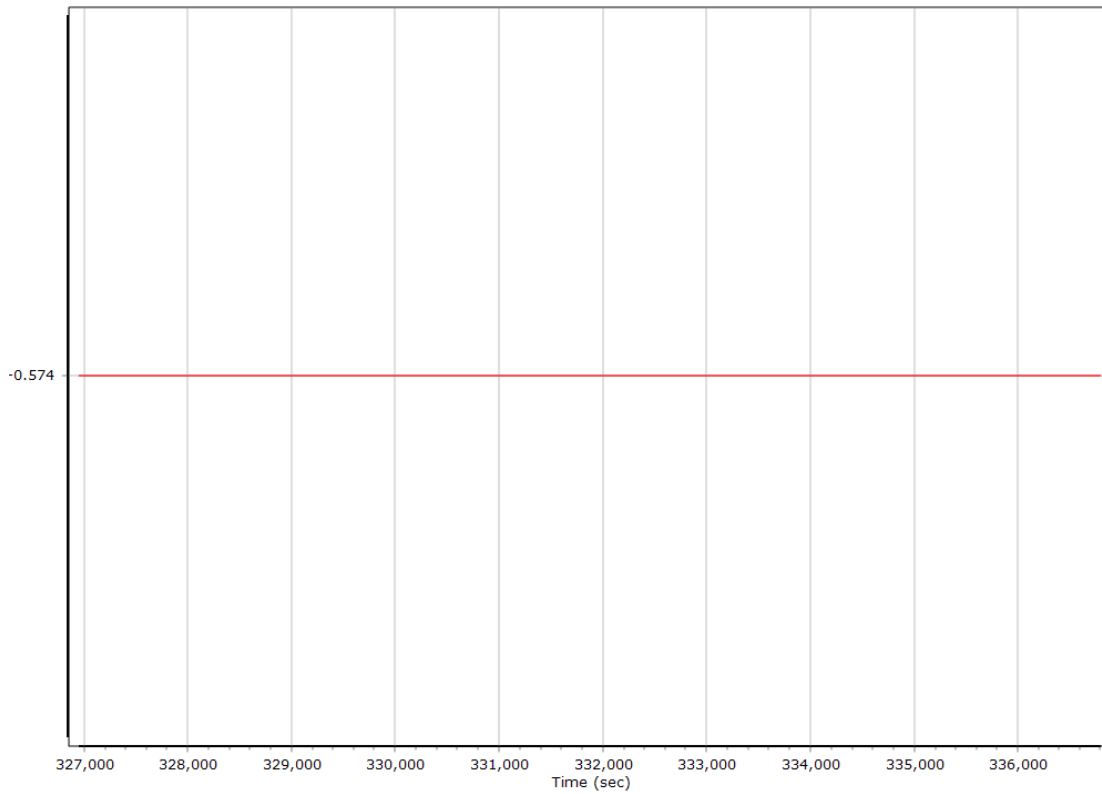
## Calibrated Installation Parameters

### Reference-Primary GNSS Lever Arm (m)

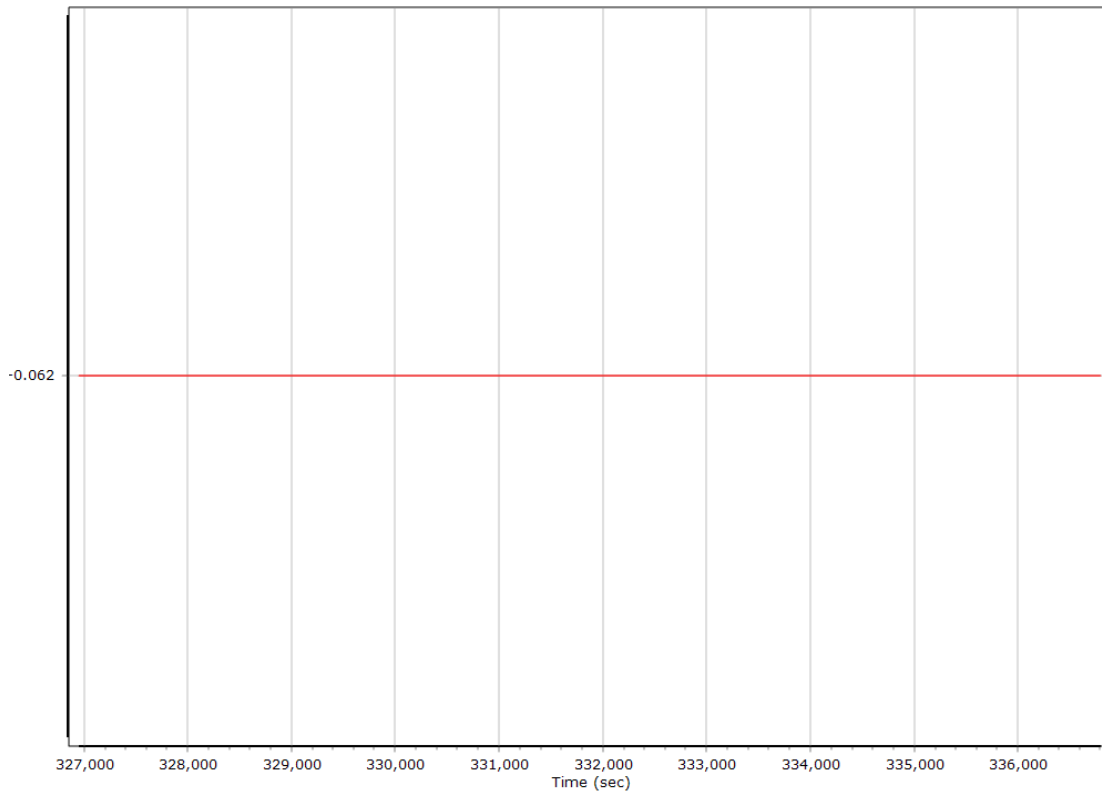
#### Reference-Primary GNSS Lever Arm Automatic Calibration Results

Original Reference to Primary GNSS lever arm (m)	-0.497	-0.045	-1.199
Iteration 1 Reference to Primary GNSS lever arm (m)	-0.567	-0.061	-1.206
Iteration 2 Reference to Primary GNSS lever arm (m)	-0.574	-0.062	-1.205
Primary GNSS Lever Arm In use	Iteration 2		

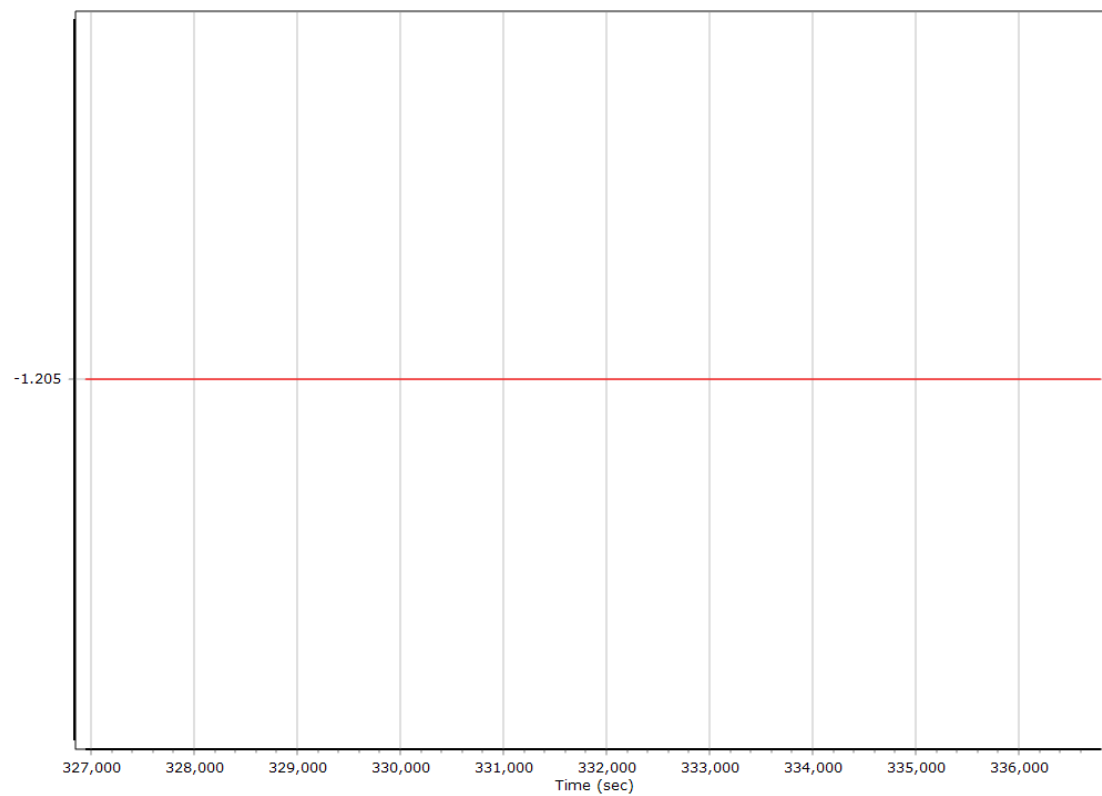
### X Reference-Primary GNSS Lever Arm (m)



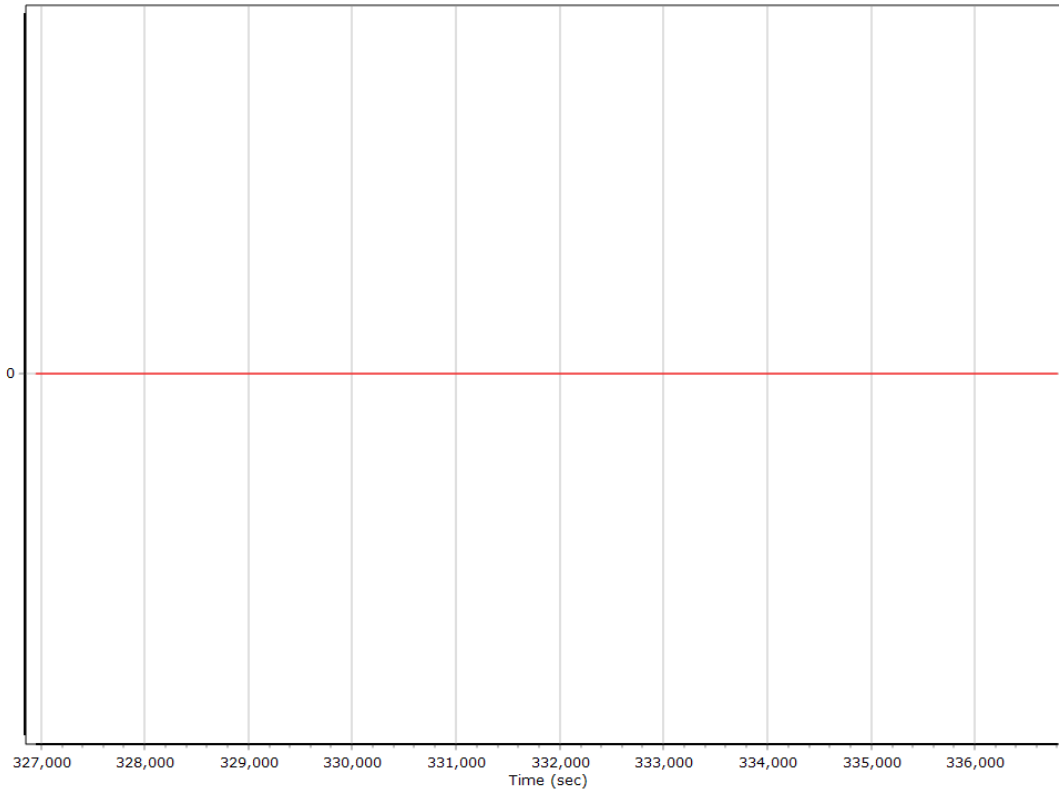
### Y Reference-Primary GNSS Lever Arm (m)



### Z Reference-Primary GNSS Lever Arm (m)



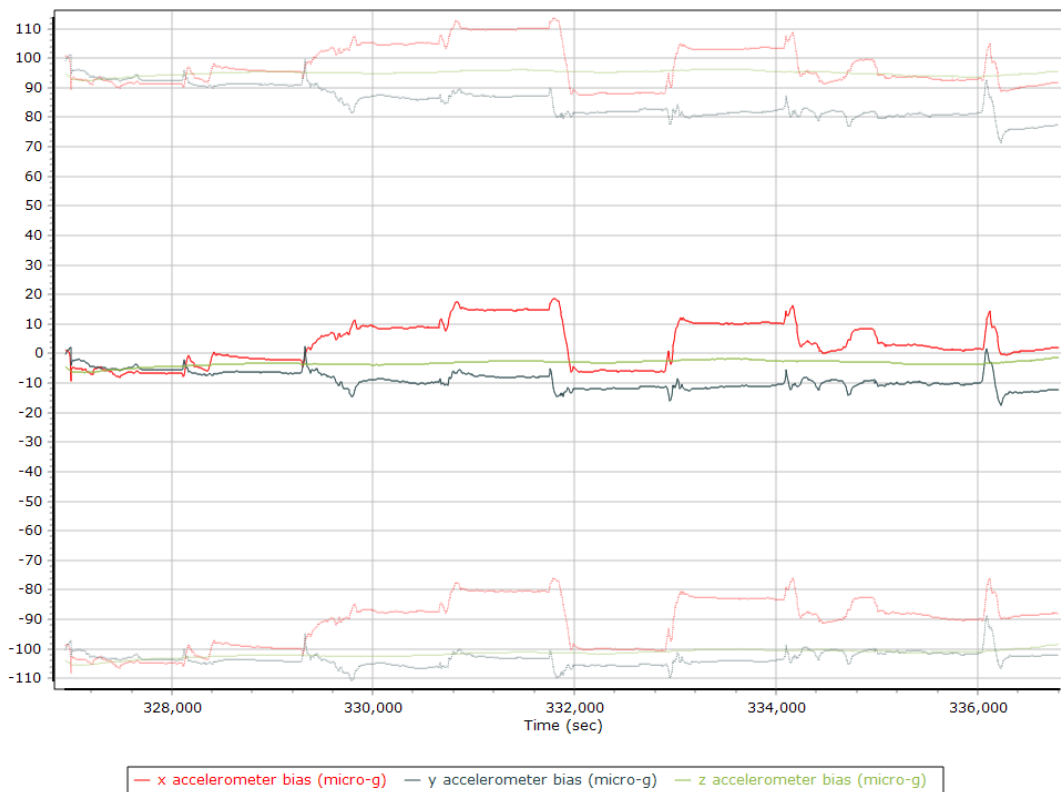
### Reference-Primary GNSS Lever Arm Figure of Merit



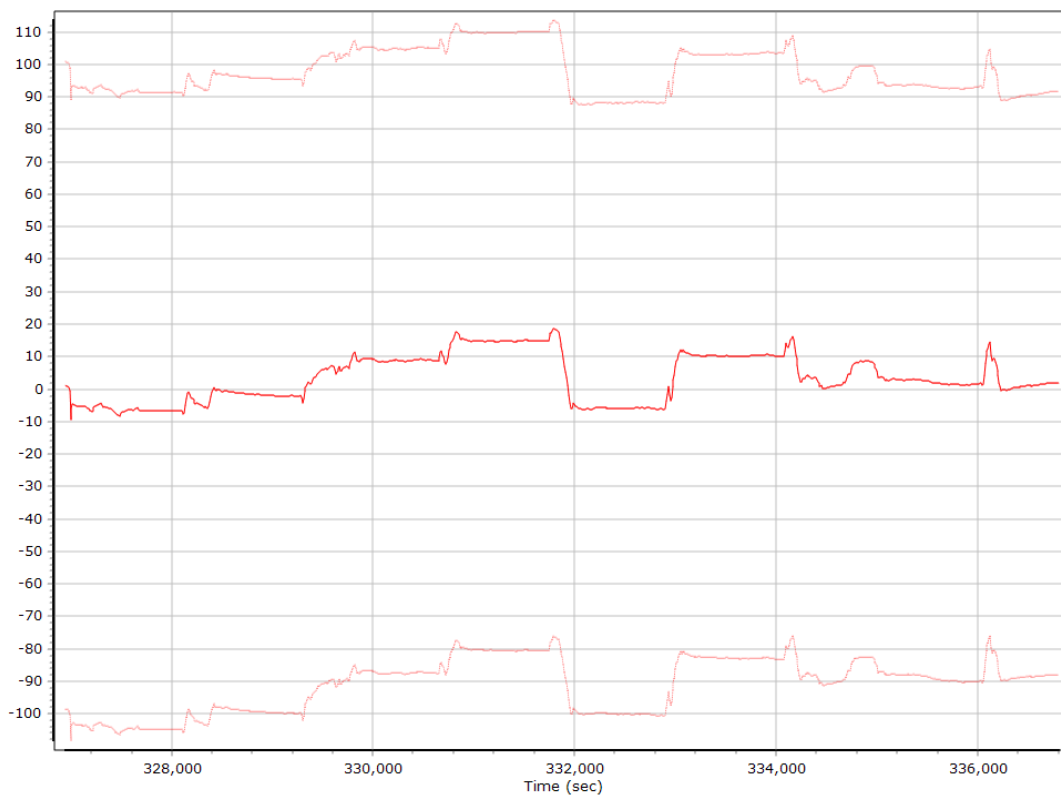
## IN-Fusion QC

### Forward Processed Estimated Errors, Reference Frame

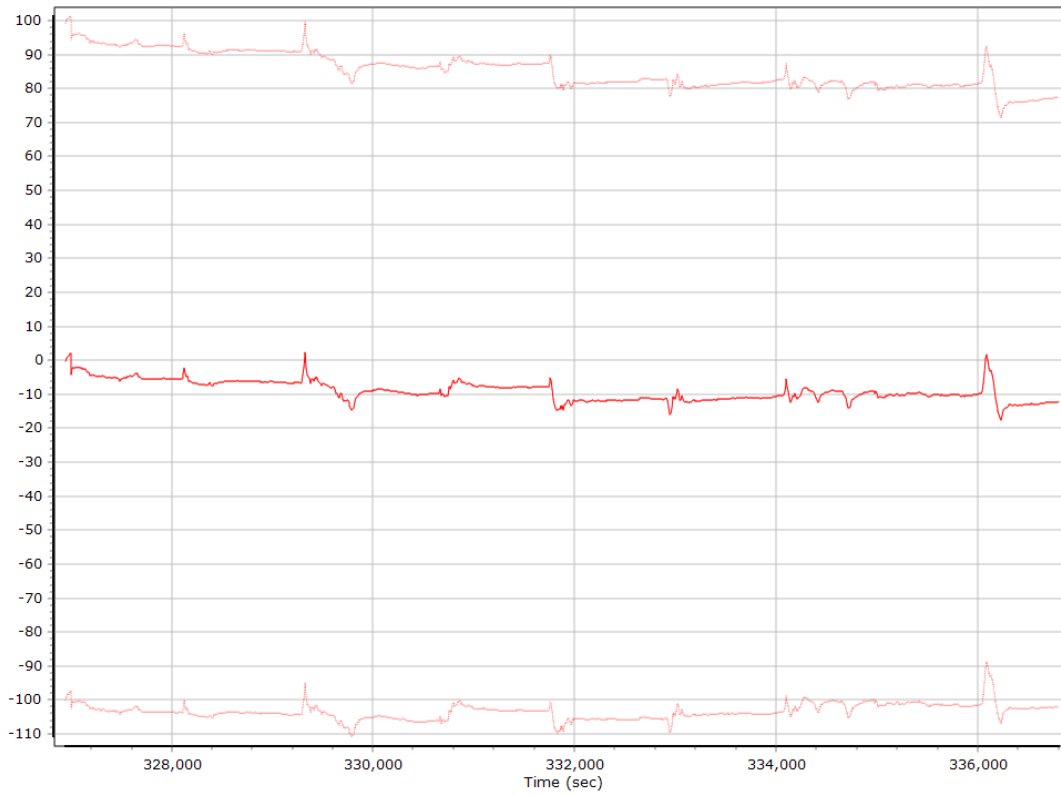
#### Accelerometer Bias (micro-g)



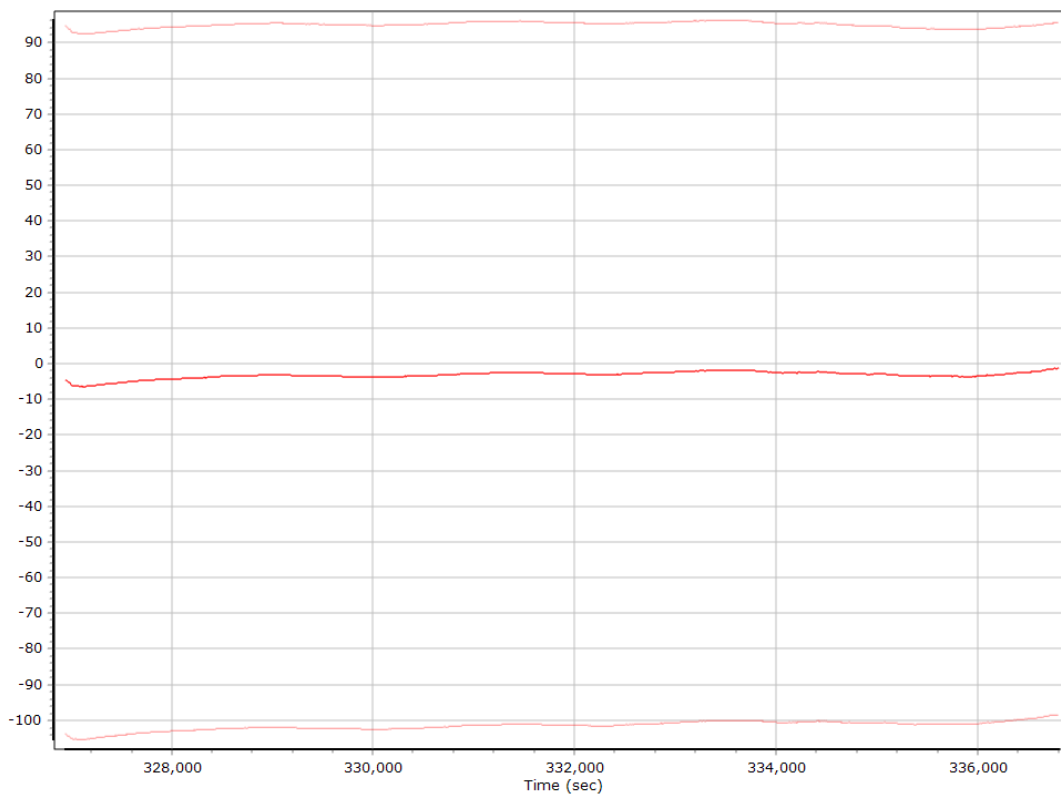
#### X Accelerometer Bias (micro-g)



### Y Accelerometer Bias (micro-g)



### Z Accelerometer Bias (micro-g)





### Accelerometer Scale Error (ppm)



### X Accelerometer Scale Error (ppm)



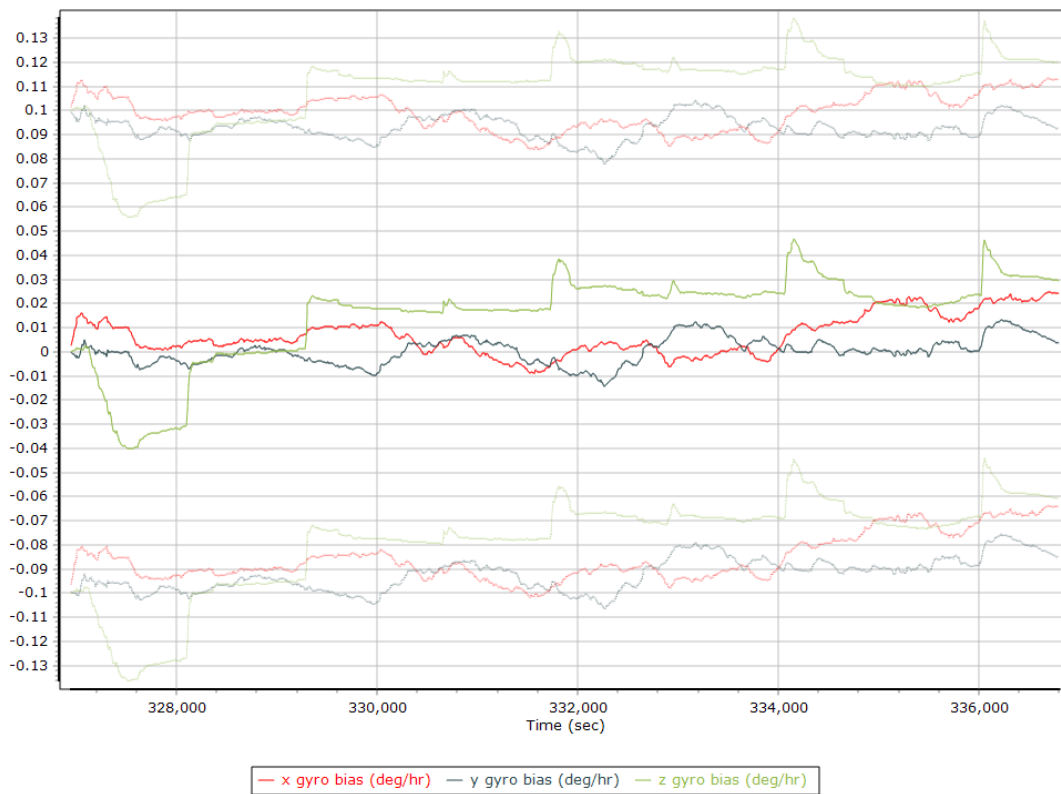
### Y Accelerometer Scale Error (ppm)



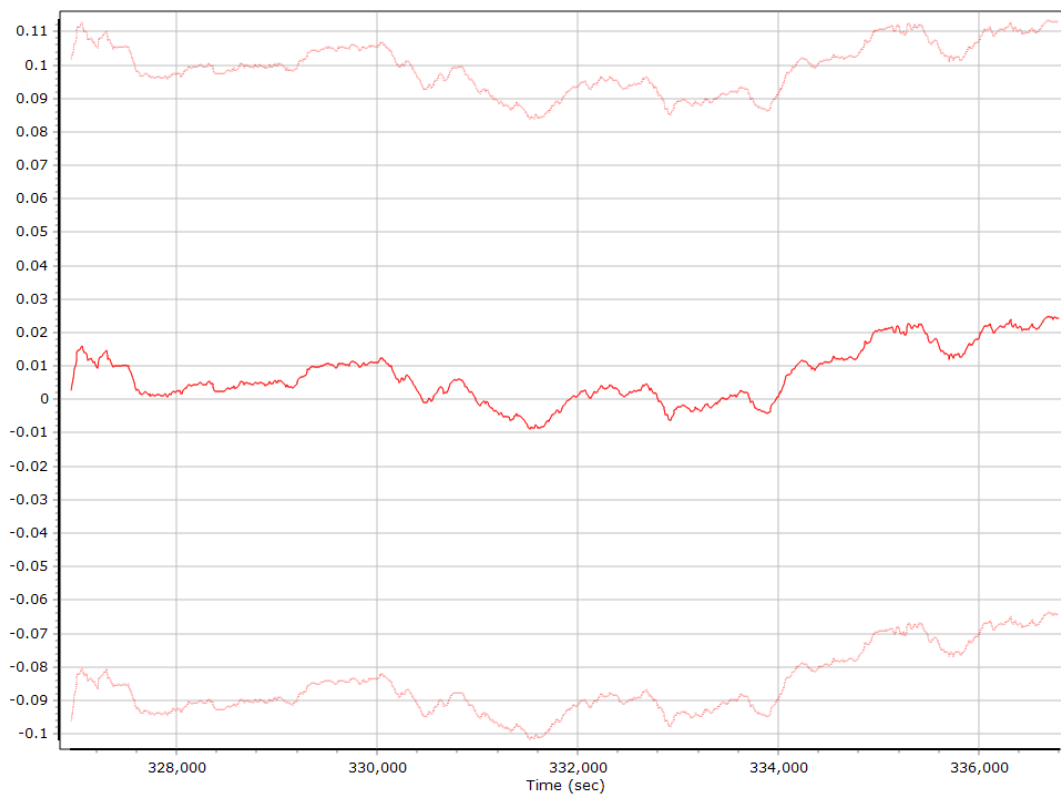
### Z Accelerometer Scale Error (ppm)



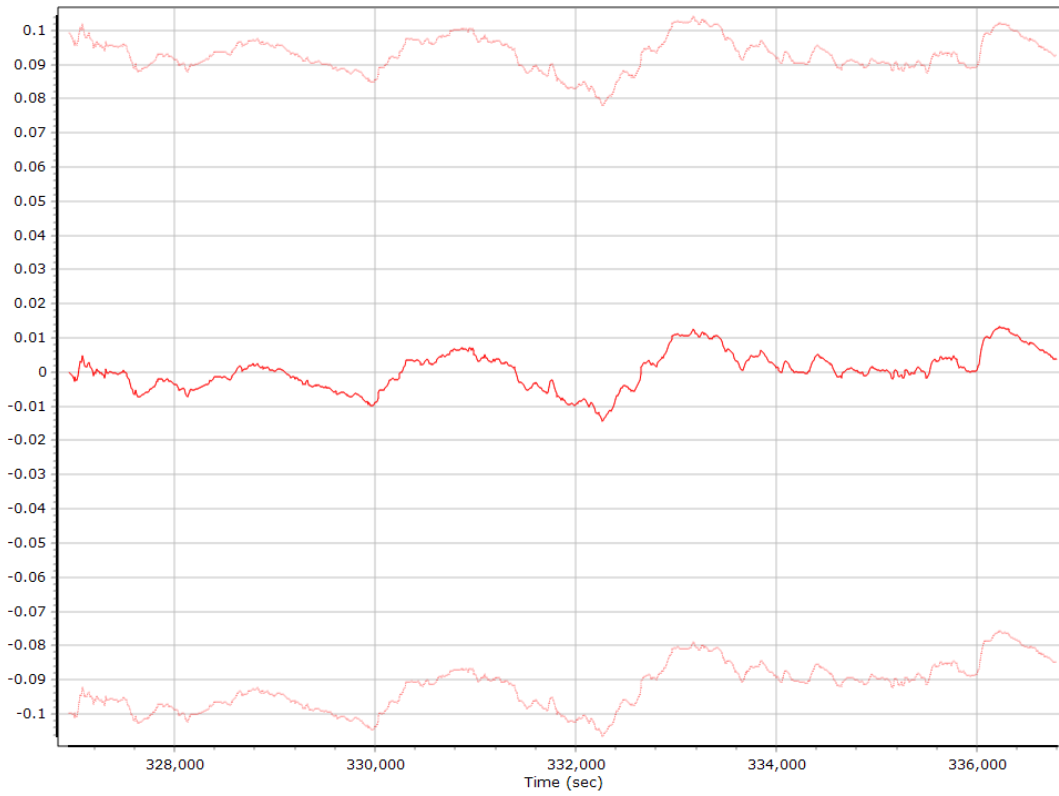
### Gyro Bias (deg/h)



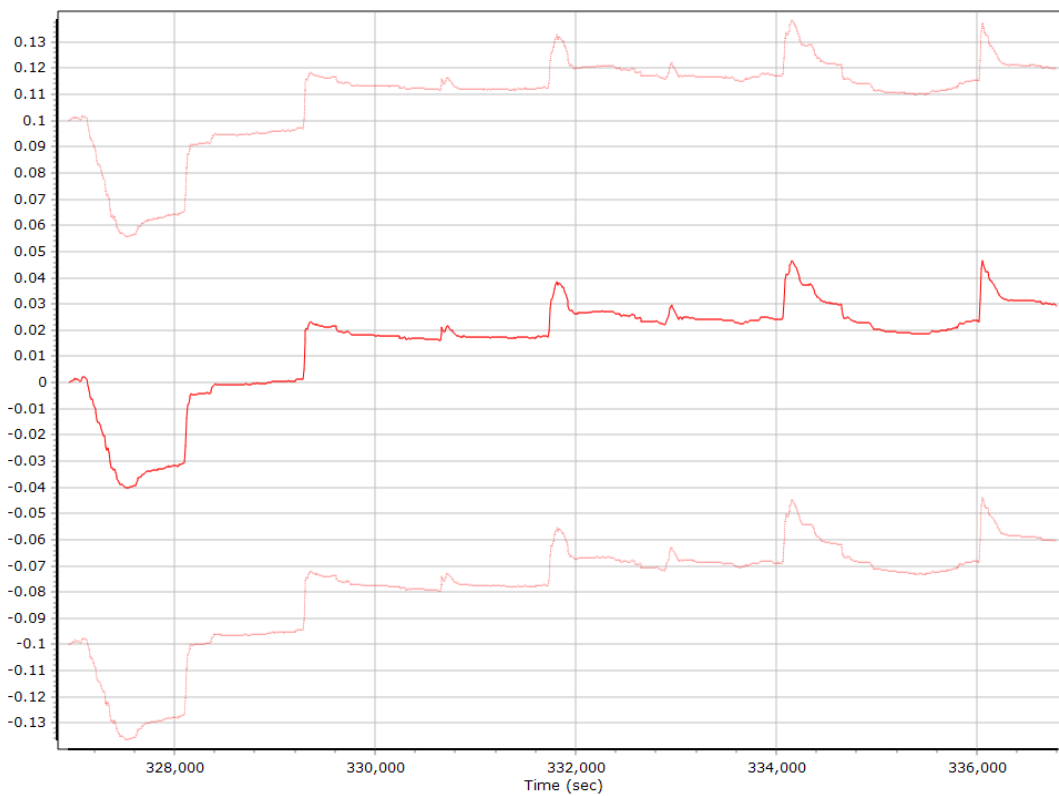
### X Gyro Bias (deg/h)



### Y Gyro Bias (deg/h)



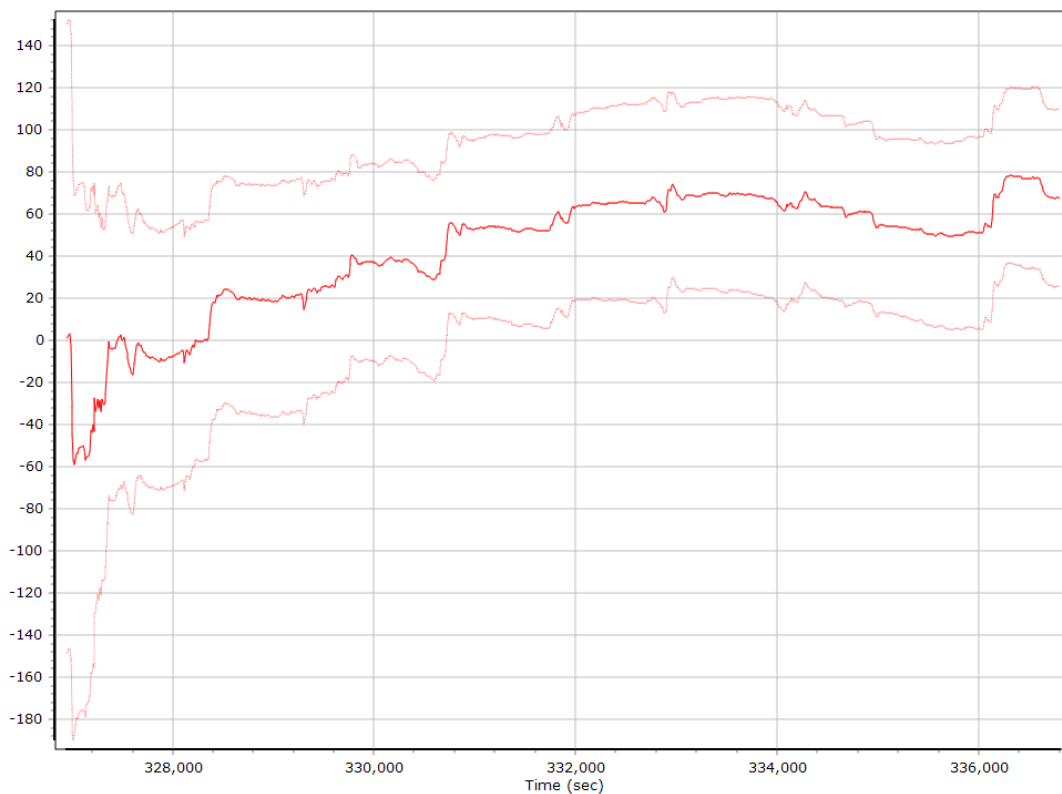
### Z Gyro Bias (deg/h)



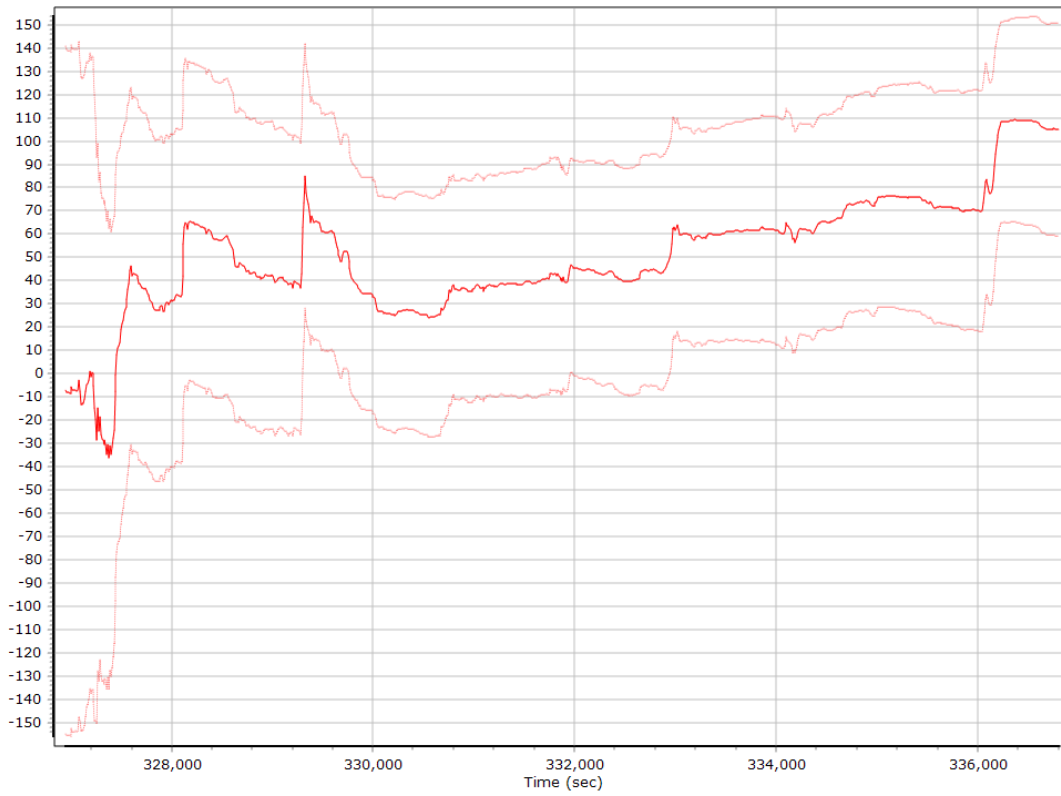
### Gyro Scale Error (ppm)



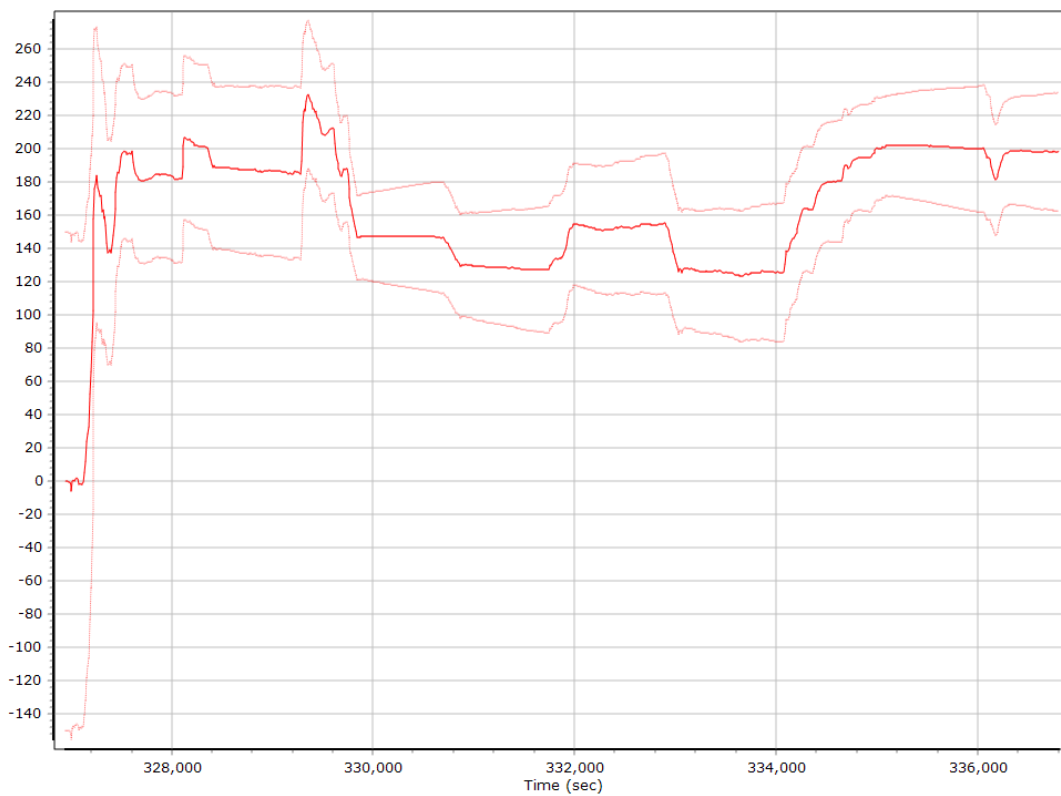
### X Gyro Scale Error (ppm)



### Y Gyro Scale Error (ppm)

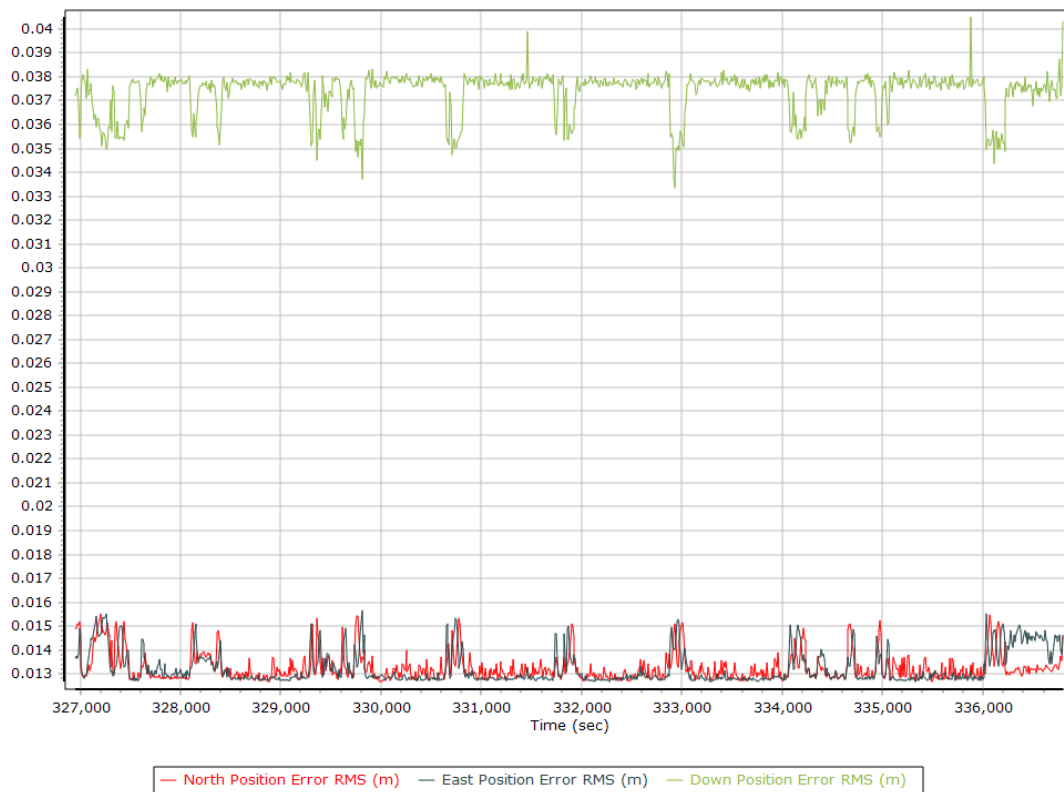


### Z Gyro Scale Error (ppm)

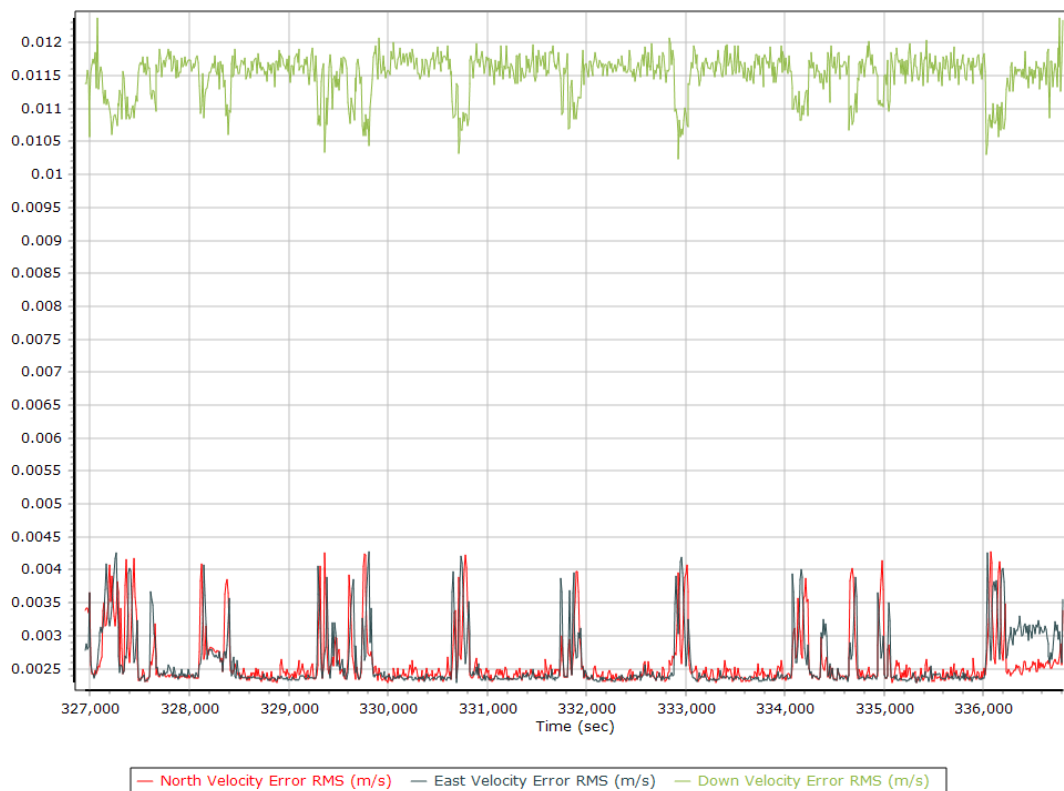


## Smoothed Performance Metrics

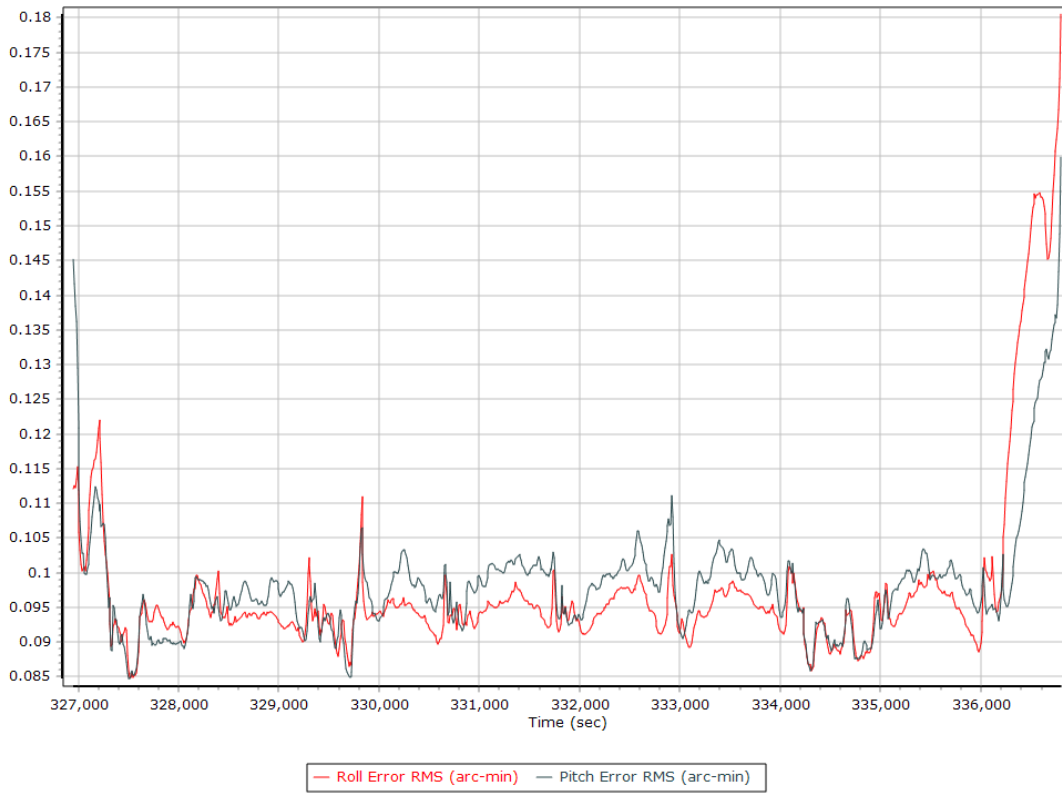
### Position Error RMS (m)



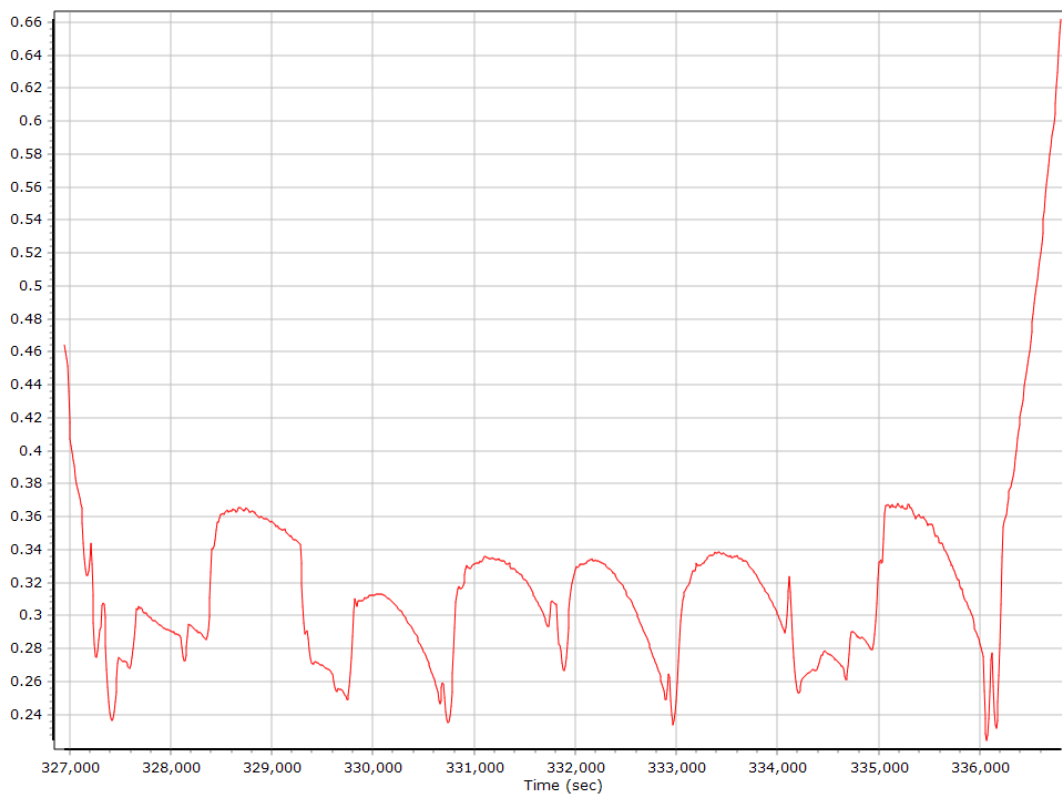
### Velocity Error RMS (m/s)



### Roll/Pitch Error RMS (arc-min)



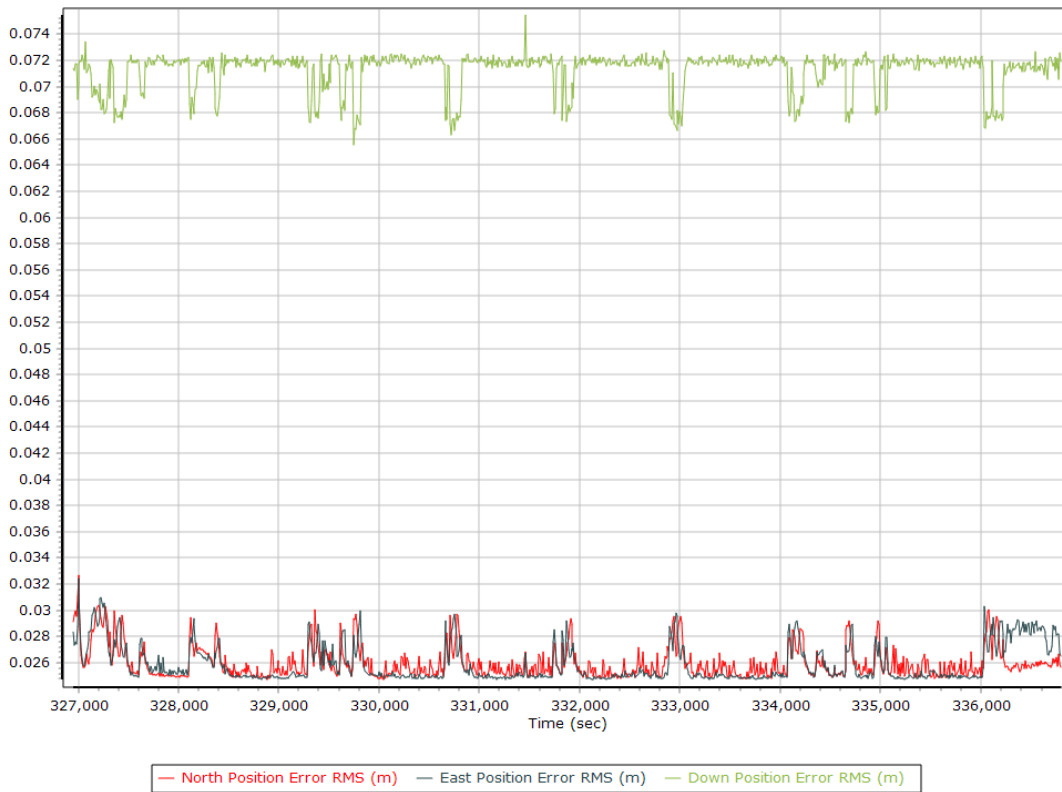
### Heading Error RMS (arc-min)



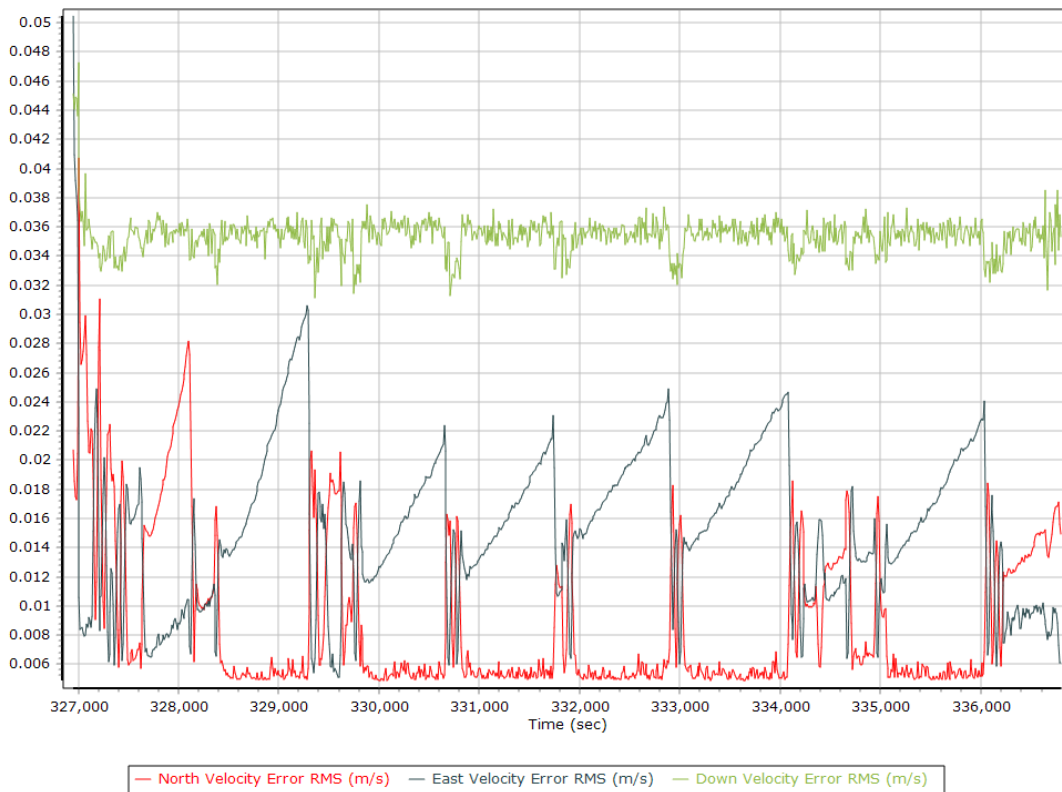


## Forward Processed Performance Metrics

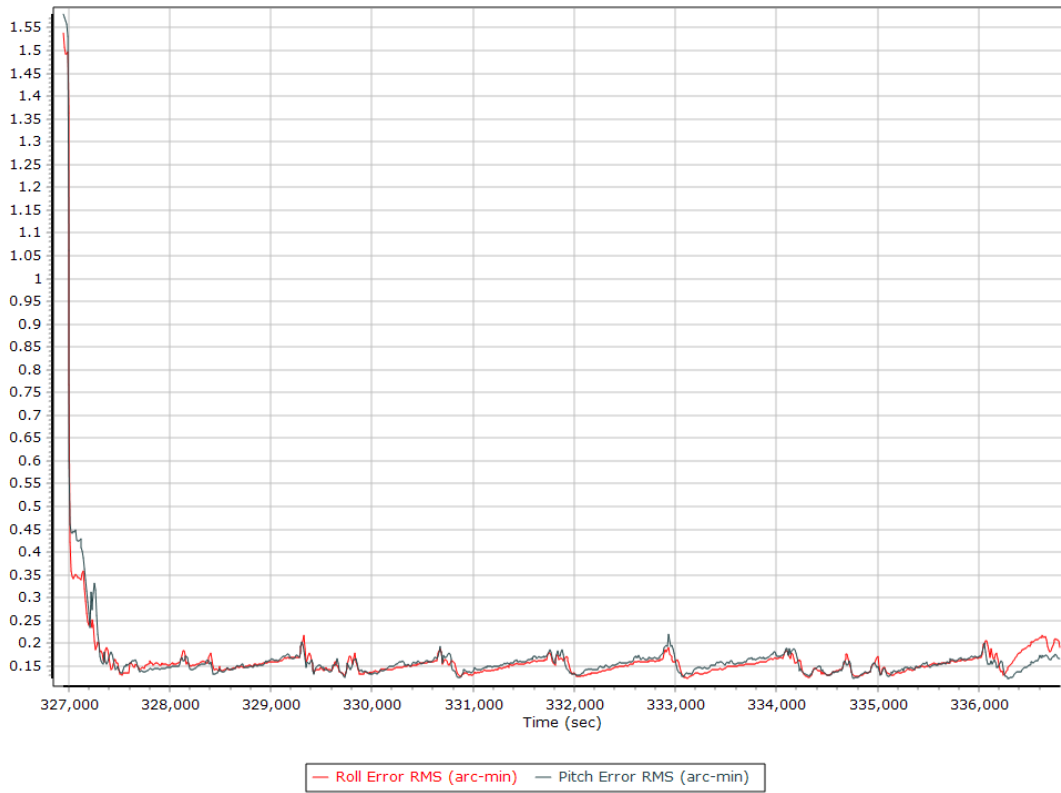
### Position Error RMS (m)



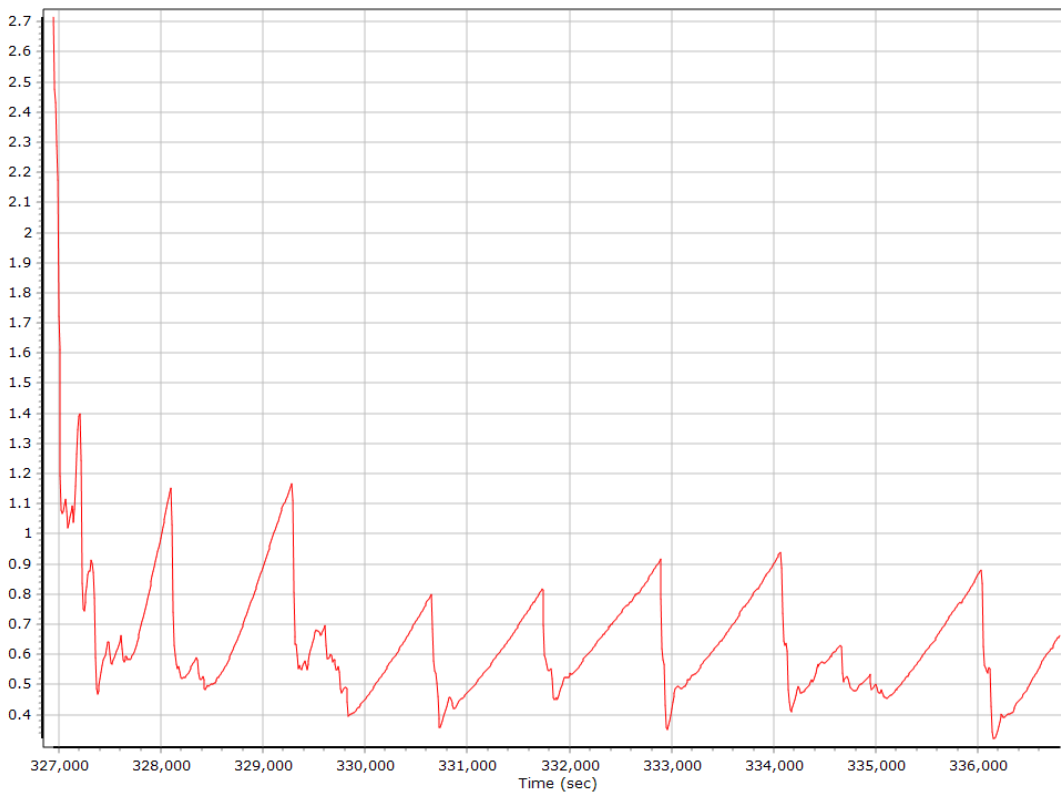
### Velocity Error RMS (m/s)



### Roll/Pitch Error RMS (arc-min)

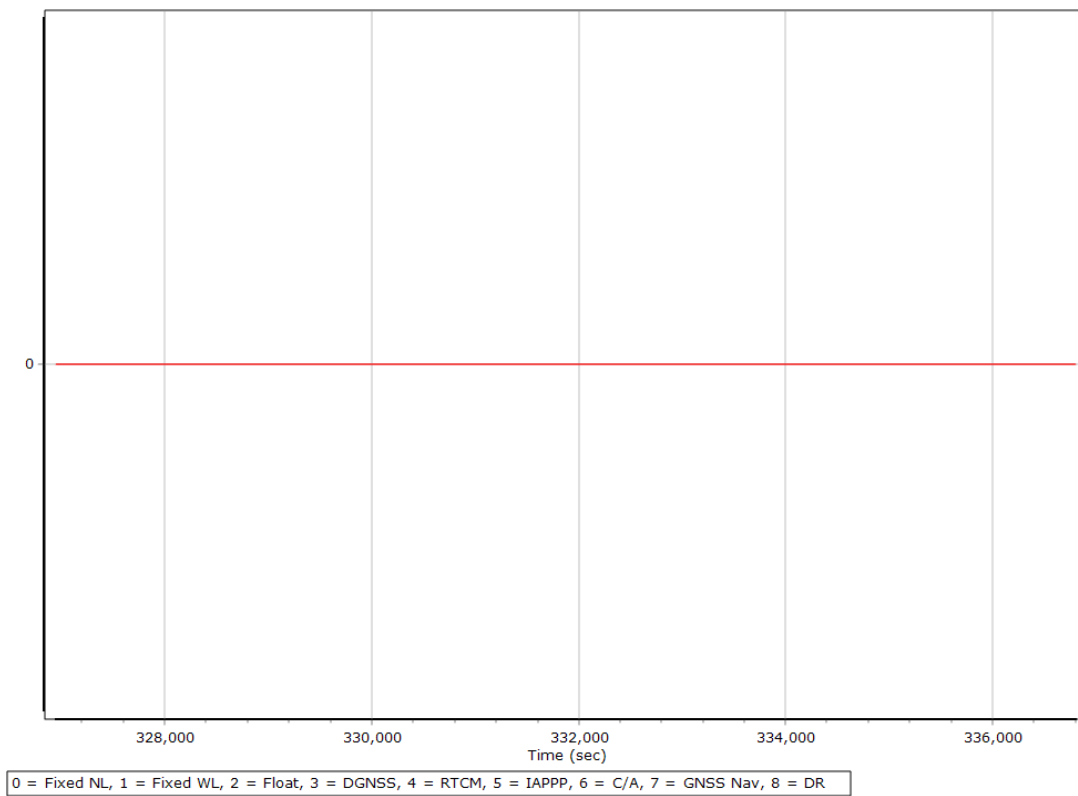


### Heading Error RMS (arc-min)

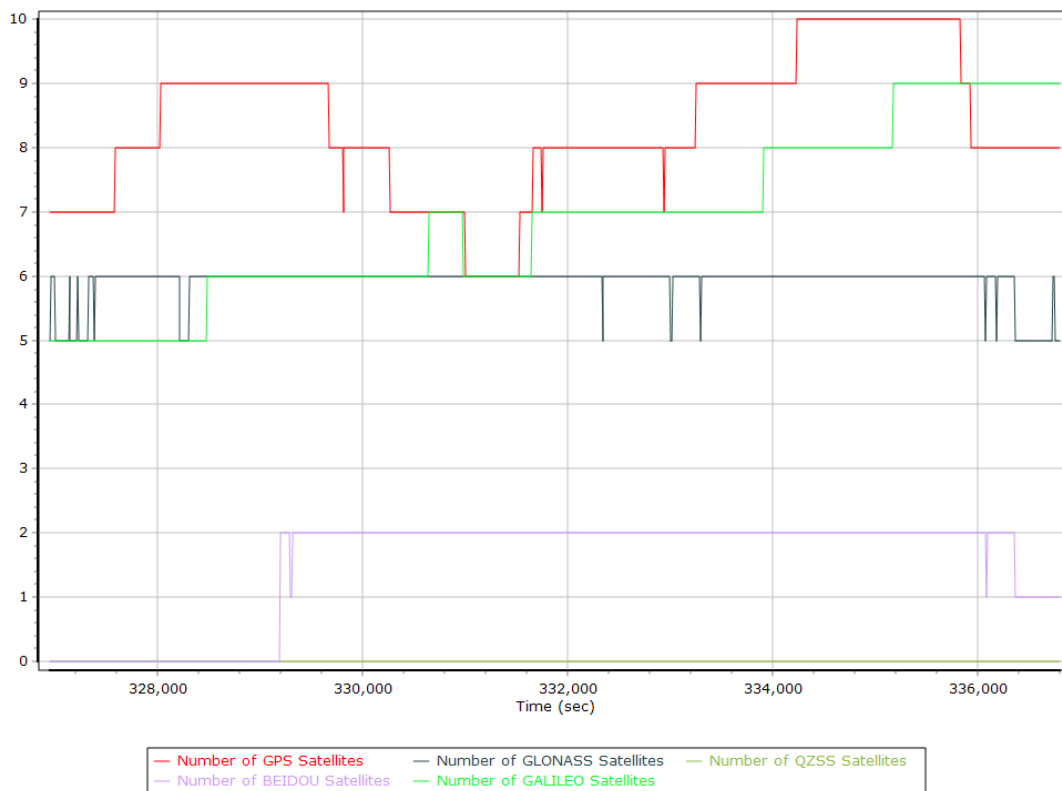


## Forward Processed Solution Status

### Processing Mode



### Number of Satellites



## Baseline Length

