

General Information

Mission Information

Project name	211022_A_5060428_nad2011_FINAL
Processing date	2021-11-04 14:58:40
Mission date	2021-10-22 14:43:33
Mission duration	03:27:24.000
Processing mode	IN-Fusion PP-RTX

Rover Hardware Information

Product	POS AV 610 VER6 HW2.5-12
Serial number	S/N10633
IMU type	57
Receiver type	BD982
Antenna type	AV39

Project File List

Rover Data Files

File name	File type
survey1.pos	POS Data

Input Files

File Name	File Type
Ephm2950.21g	GLONASS Broadcast Ephemeris
Ephm2950.21n	GPS Broadcast Ephemeris

Output Files

Filename	File type
sbet_211022_A_5060428_nad2011_FINAL.out	SBET Trajectory File

Rover Data Summary

First raw data file	survey1.pos		
Last raw data file	survey1.pos		
Start GPS week	2180		
Start time	485012.106 (10/22/2021 14:43:32)		
End time	497457.006 (10/22/2021 18:10:57)		
Start of fine alignment	485346.556 (10/22/2021 14:49:06)		
Available subsystems	Primary GNSS, IMU		
POS Event Input	None		
Correction data	None		
IMU Installation Lever Arms & Mounting Angles			
Reference to IMU lever arm (m)	0.000	0.000	0.000
Reference to IMU mounting angles (deg)	0.000	0.000	-90.000
Reference to Primary GNSS lever arm (m)	0.534	0.060	-1.199
Reference to Primary GNSS lever arm std dev (m)	-1.000		
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

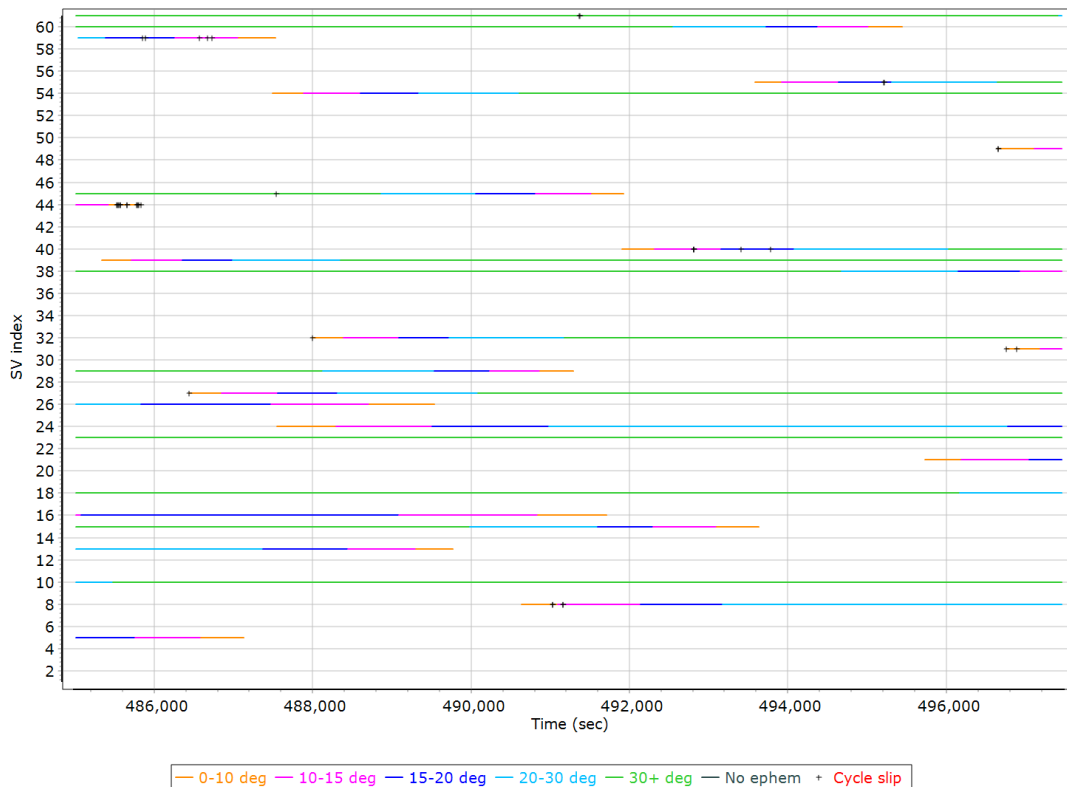
Rover Data QC

Raw IMU Import QC Summary

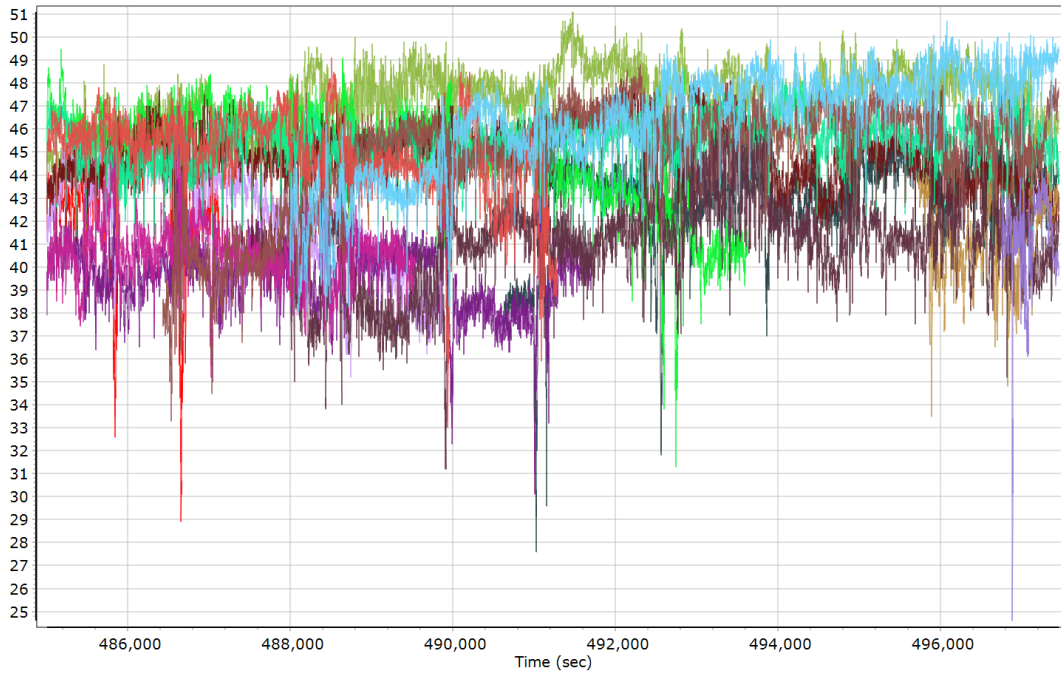
IMU data input file	imu_211022_A_5060428_nad2011_FINAL.dat
IMU data check log file	imudt_211022_A_5060428_nad2011_FINAL.log
IMU Records Processed	2488581
Termination Status	Normal
IMU Anomalies	0

Primary Observables & Satellite Data

GPS/GLONASS L1 Satellite Lock/Elevation

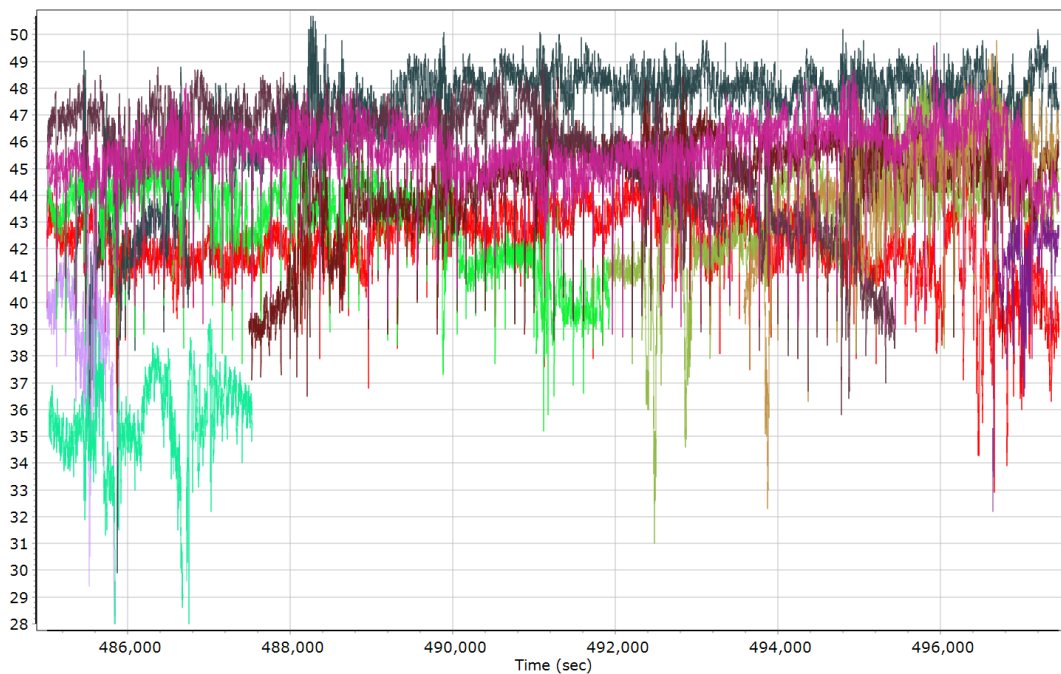


GPS L1 SNR



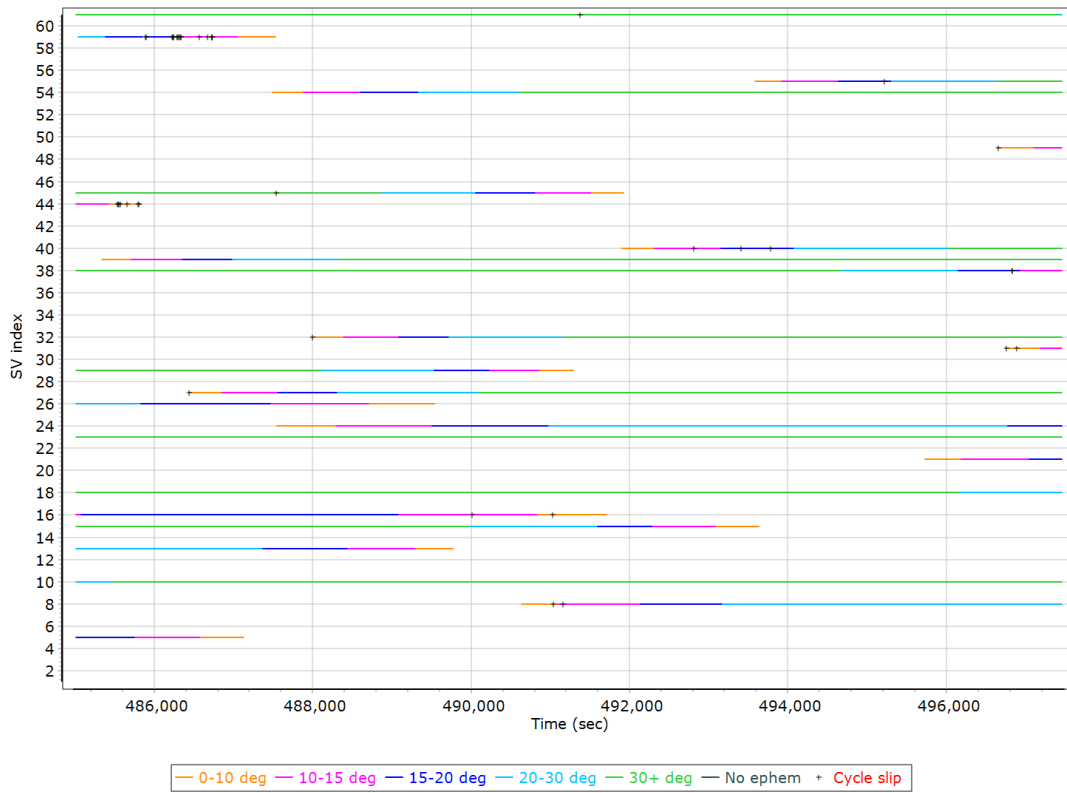
- | | | | |
|---------------------------|---------------------------|---------------------------|---------------------------|
| GPS PRN 05 L1 SNR (dB/Hz) | GPS PRN 08 L1 SNR (dB/Hz) | GPS PRN 10 L1 SNR (dB/Hz) | GPS PRN 13 L1 SNR (dB/Hz) |
| GPS PRN 15 L1 SNR (dB/Hz) | GPS PRN 16 L1 SNR (dB/Hz) | GPS PRN 18 L1 SNR (dB/Hz) | GPS PRN 21 L1 SNR (dB/Hz) |
| GPS PRN 23 L1 SNR (dB/Hz) | GPS PRN 24 L1 SNR (dB/Hz) | GPS PRN 26 L1 SNR (dB/Hz) | GPS PRN 27 L1 SNR (dB/Hz) |
| GPS PRN 29 L1 SNR (dB/Hz) | GPS PRN 31 L1 SNR (dB/Hz) | GPS PRN 32 L1 SNR (dB/Hz) | |

GLONASS L1 SNR

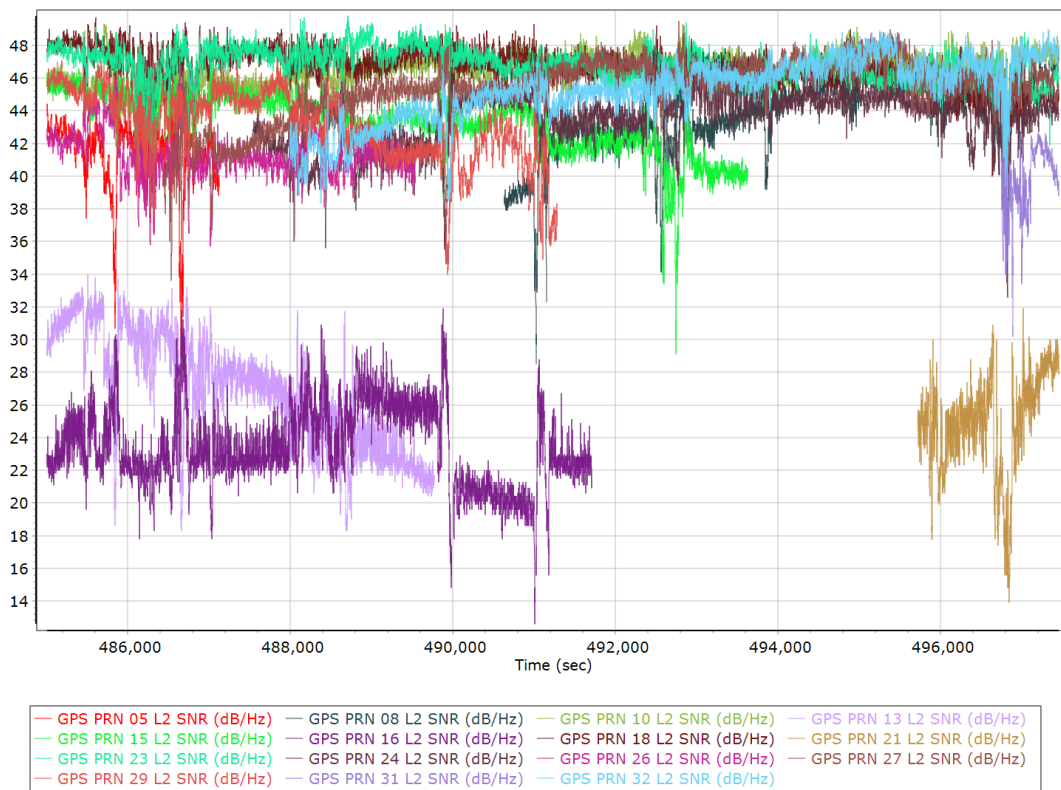


- | | | |
|---------------------------|---------------------------|---------------------------|
| GLONASS 01 L1 SNR (dB/Hz) | GLONASS 02 L1 SNR (dB/Hz) | GLONASS 03 L1 SNR (dB/Hz) |
| GLONASS 07 L1 SNR (dB/Hz) | GLONASS 08 L1 SNR (dB/Hz) | GLONASS 12 L1 SNR (dB/Hz) |
| GLONASS 17 L1 SNR (dB/Hz) | GLONASS 18 L1 SNR (dB/Hz) | GLONASS 22 L1 SNR (dB/Hz) |
| GLONASS 23 L1 SNR (dB/Hz) | GLONASS 24 L1 SNR (dB/Hz) | |

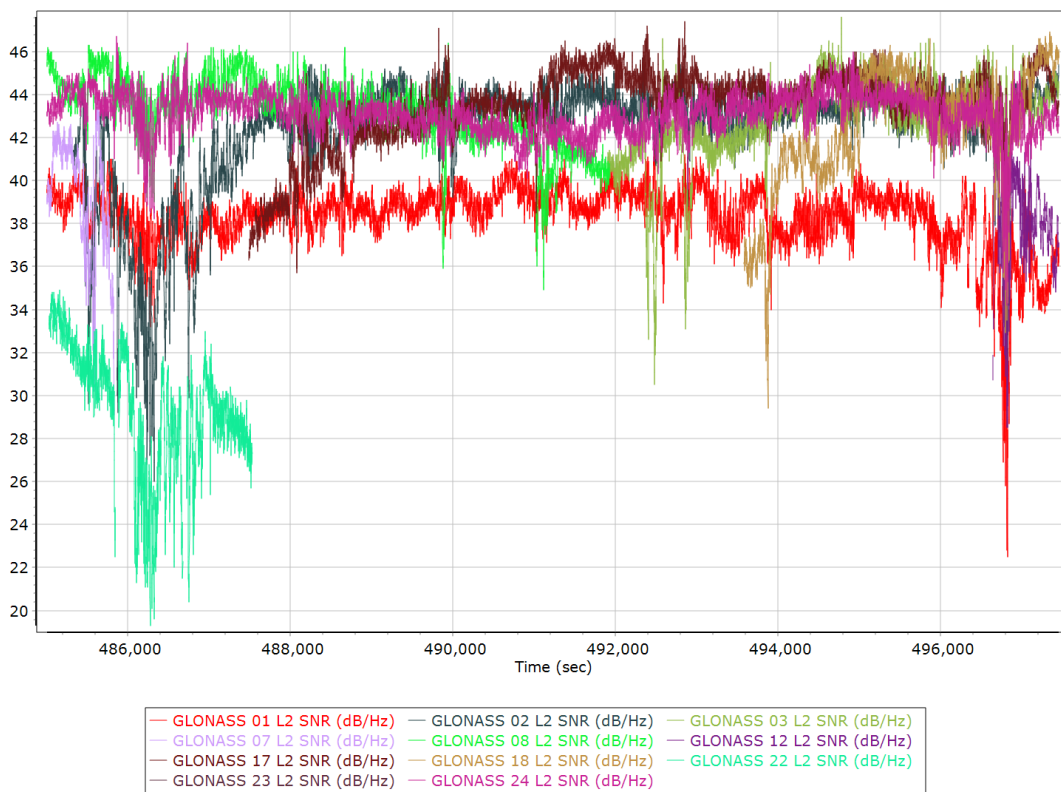
GPS/GLONASS L2 Satellite Lock/Elevation



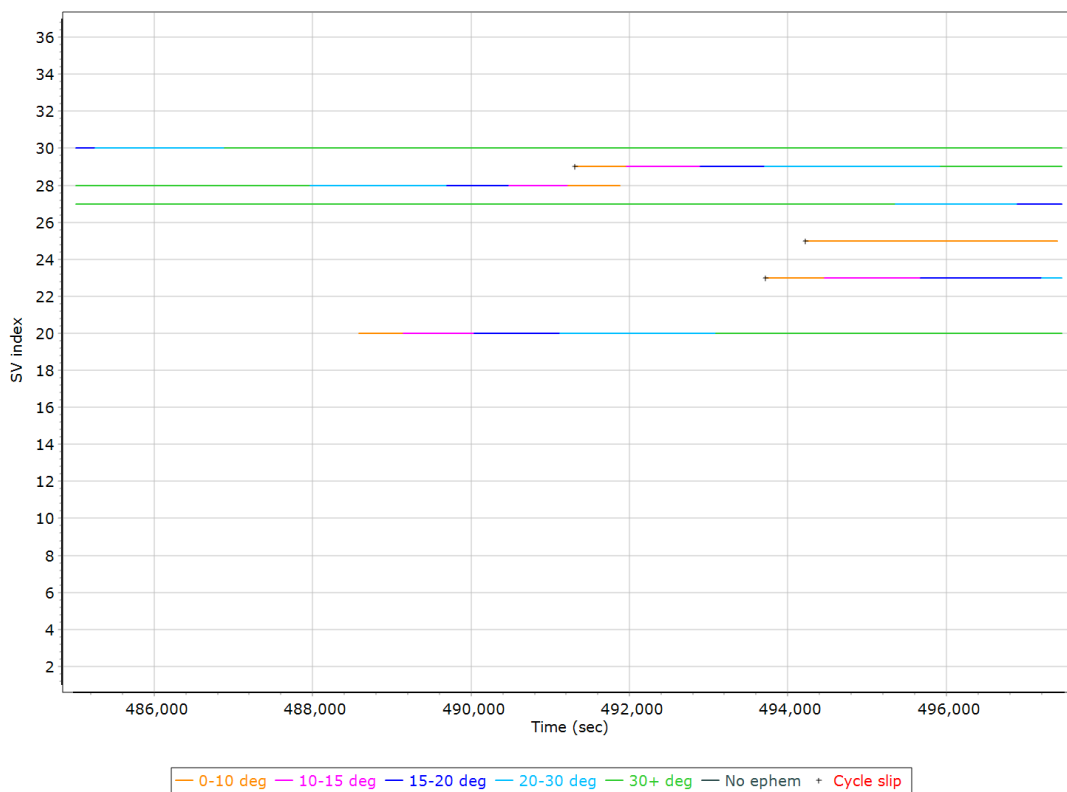
GPS L2 SNR



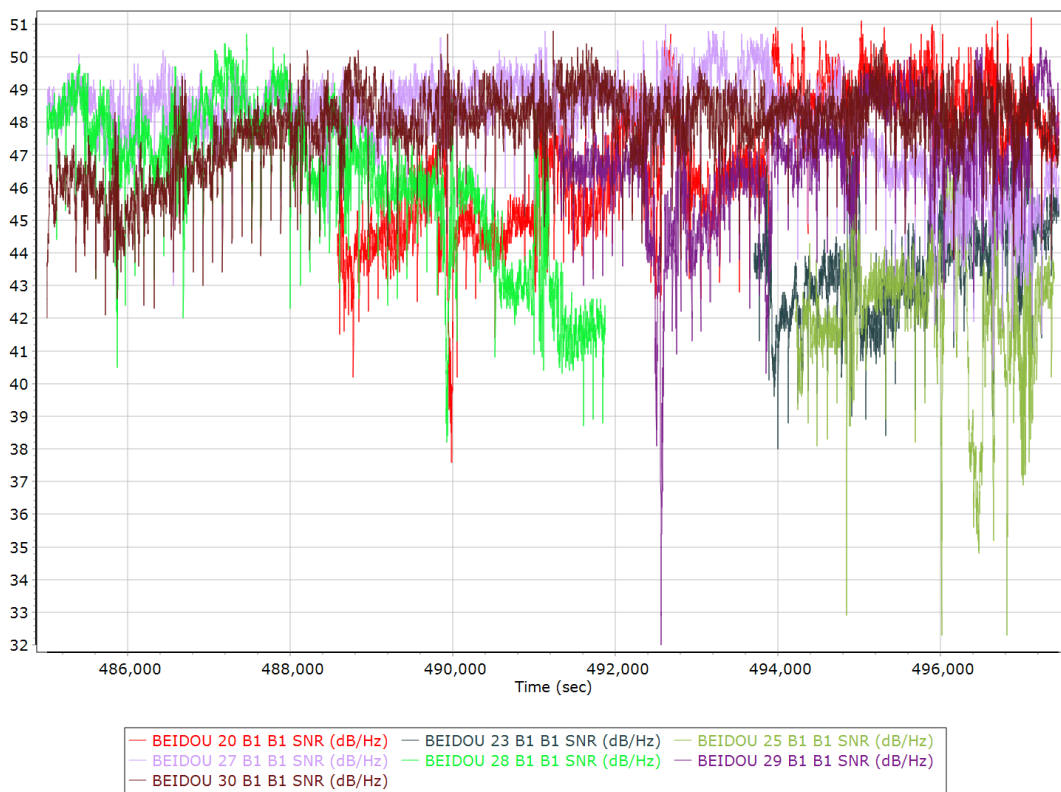
GLONASS L2 SNR



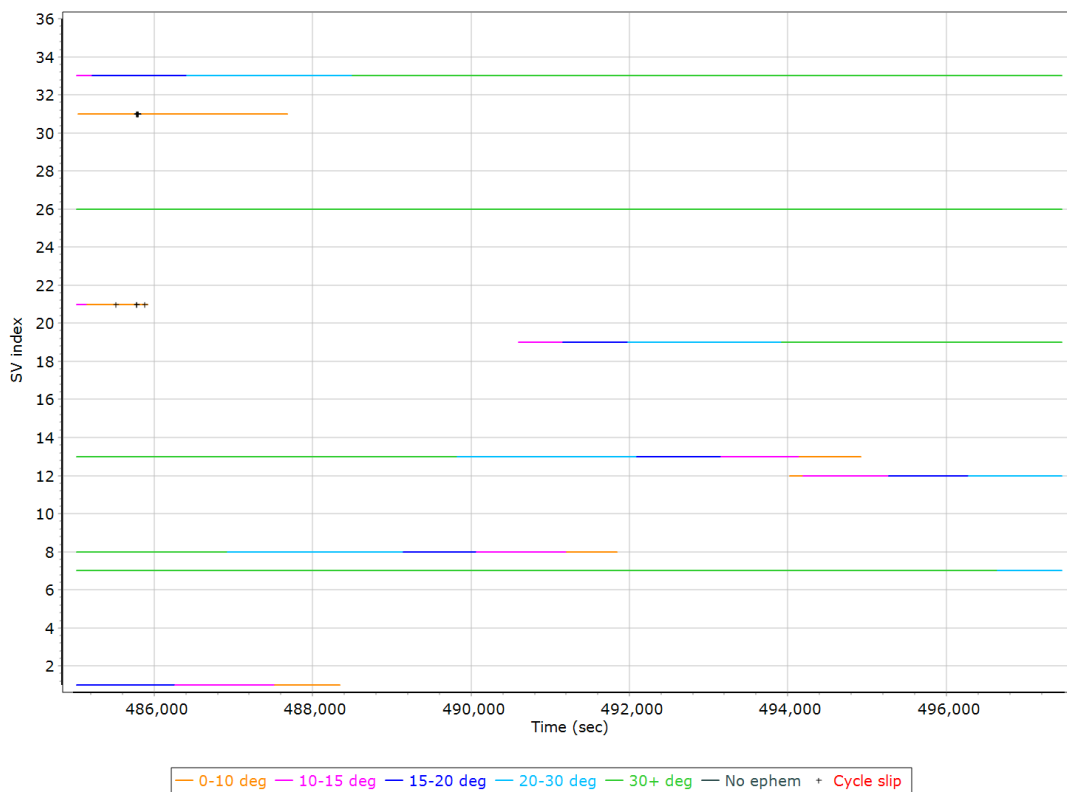
BEIDOU Satellite Lock/Elevation



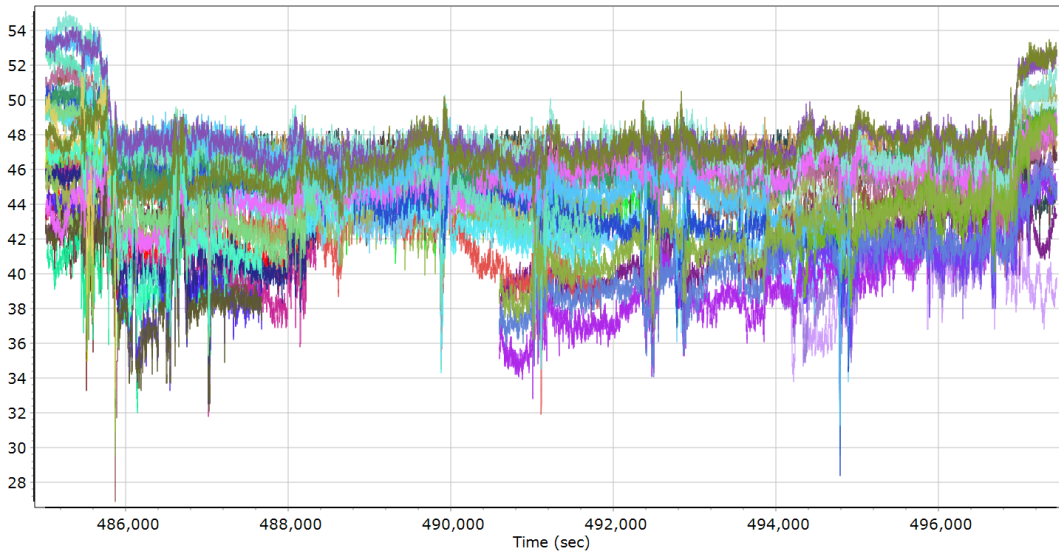
BEIDOU SNR



GALILEO Satellite Lock/Elevation



GALILEO SNR



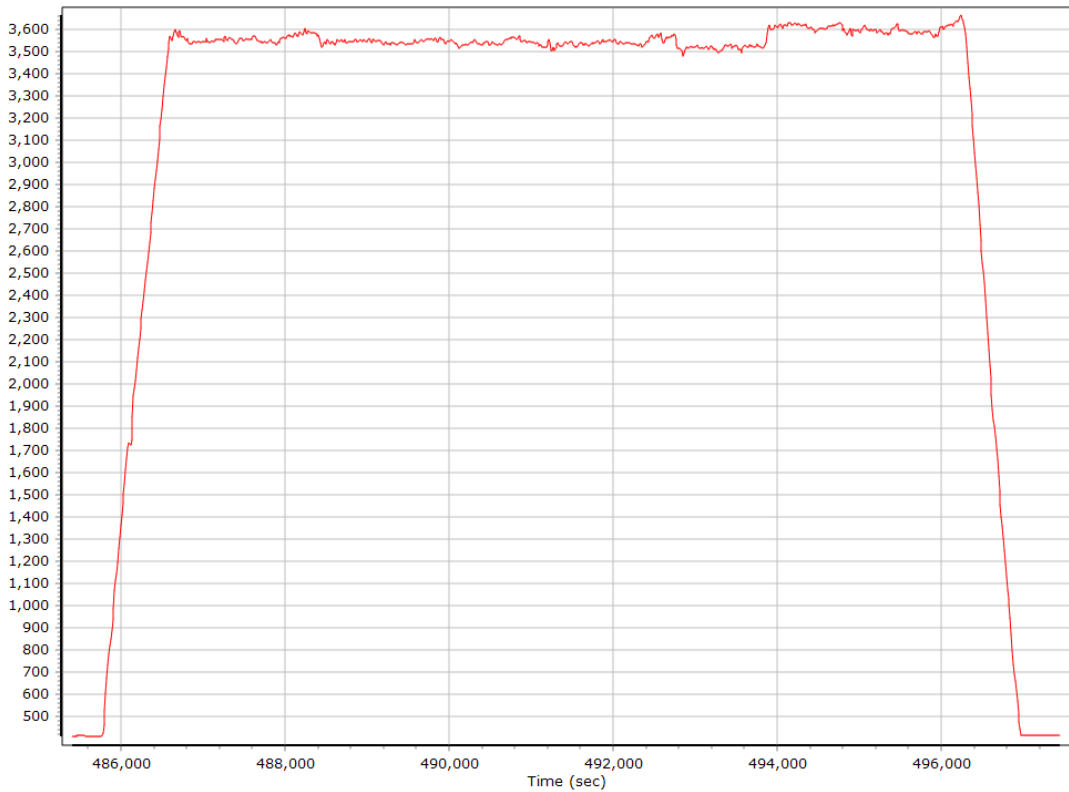
— GALILEO 01 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 07 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 08 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 12 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 13 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 19 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 21 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 26 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 31 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 33 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 01 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 07 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 08 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 12 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 13 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 19 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 21 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 26 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 31 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 33 L5E5A BPSK10_PD SNR (dB/Hz)

Smoothed Trajectory Information

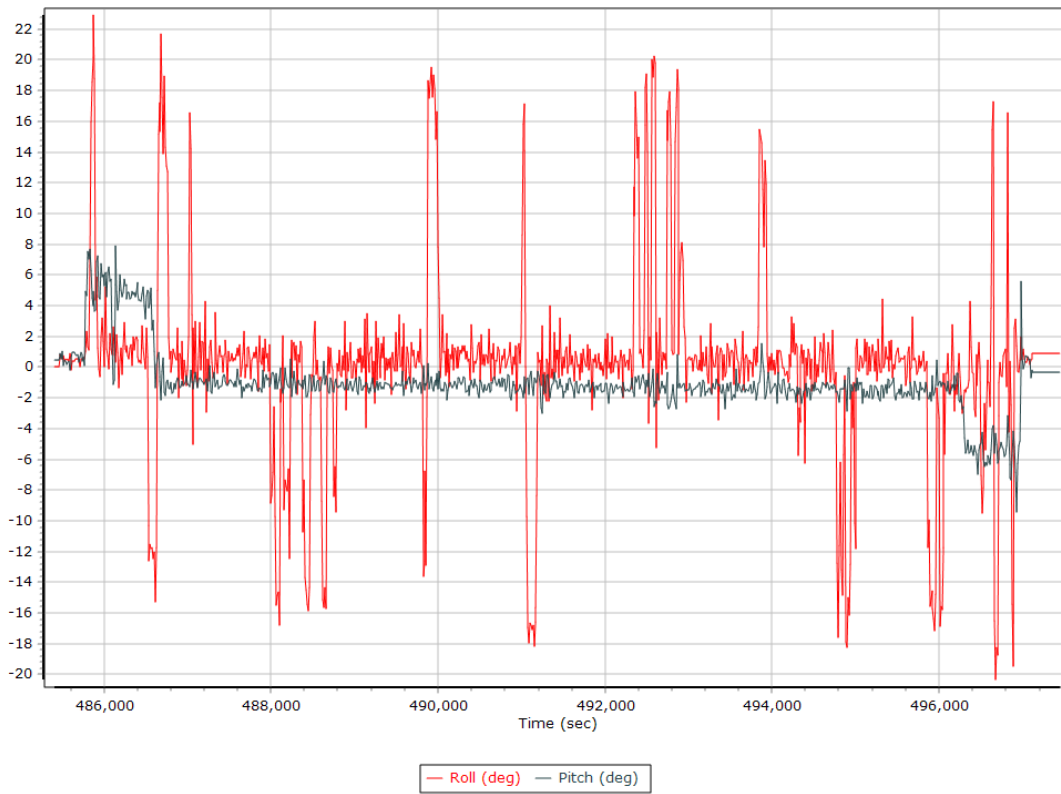
Top View



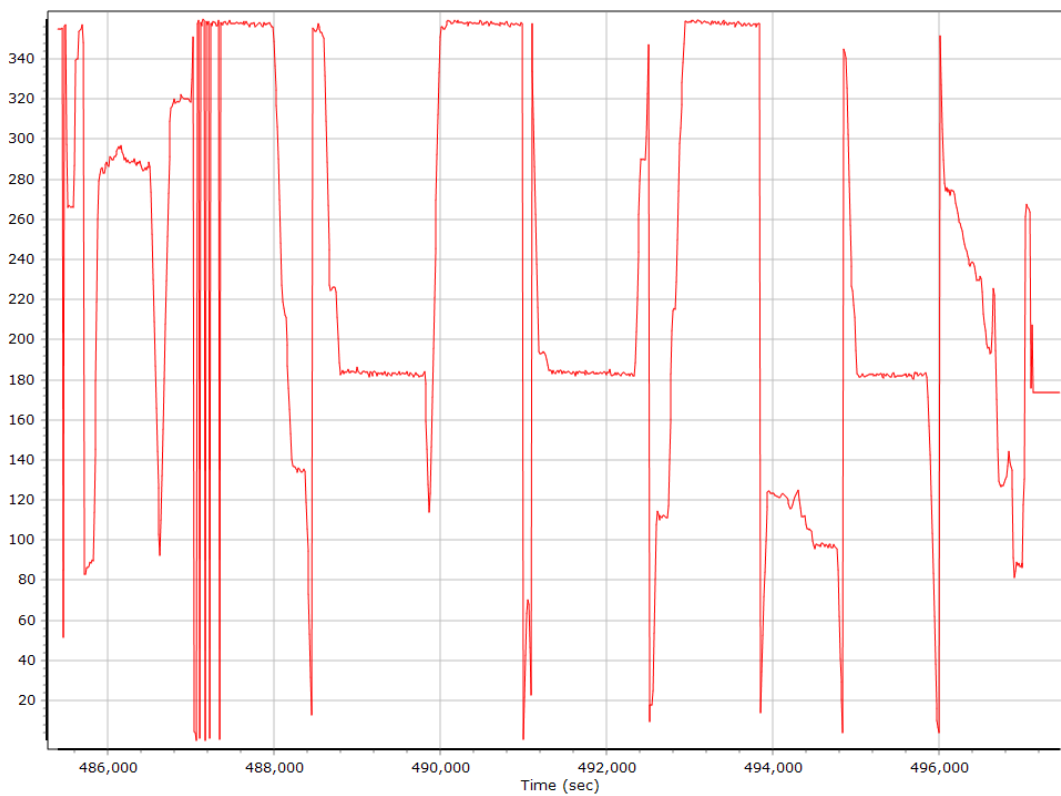
Altitude



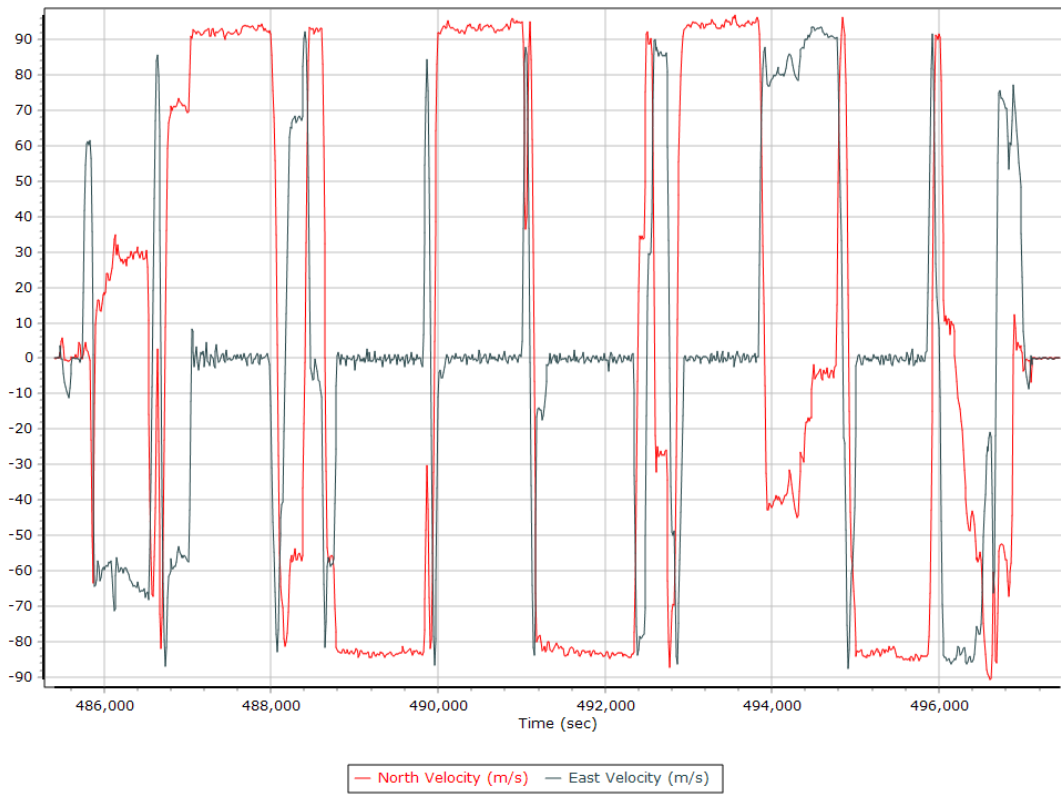
Roll/Pitch



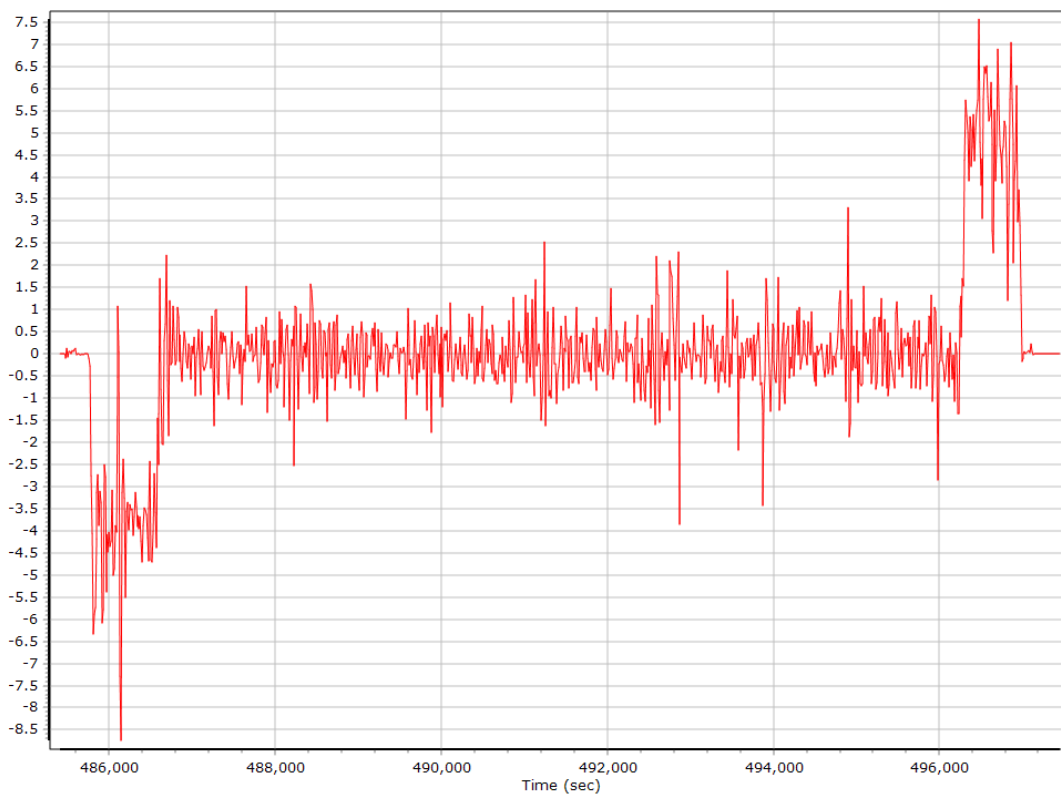
Heading



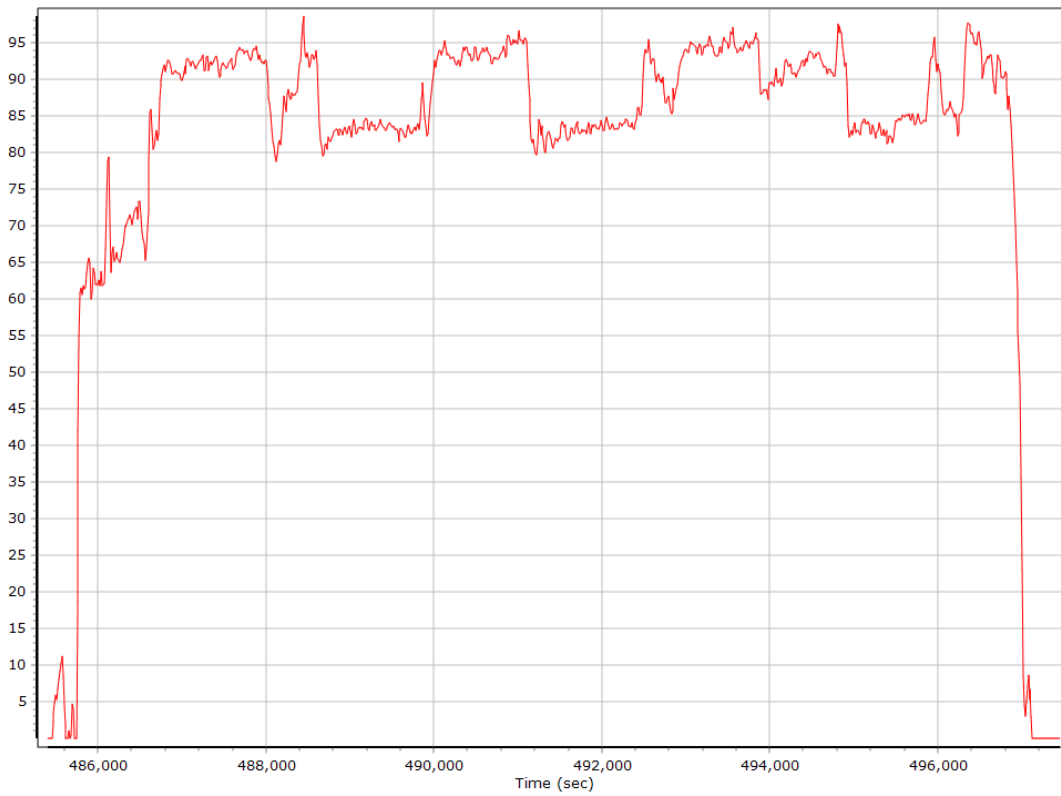
North/East Velocity



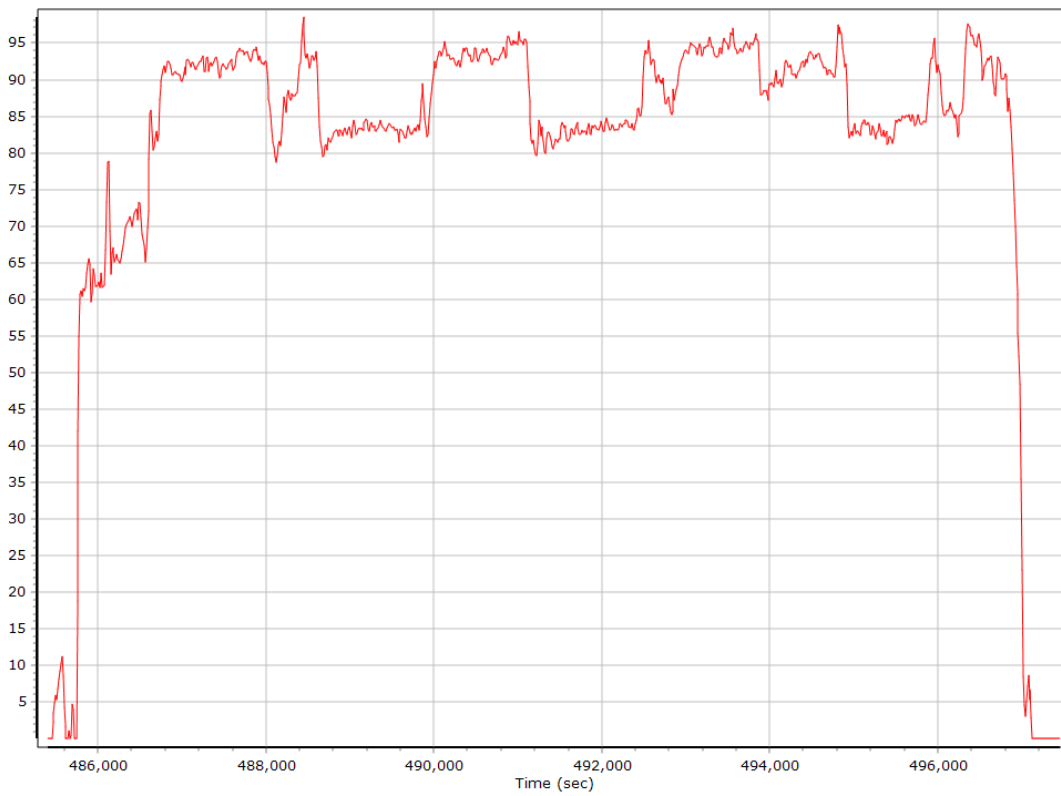
Down Velocity



Total Speed



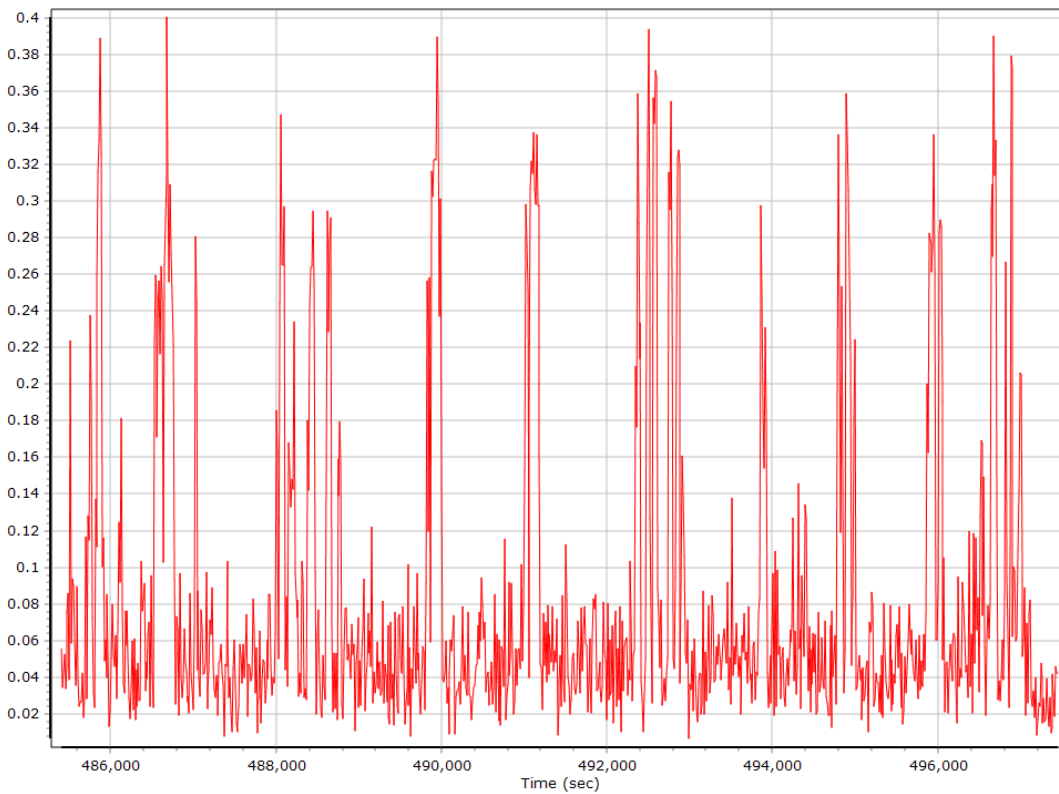
Ground Speed



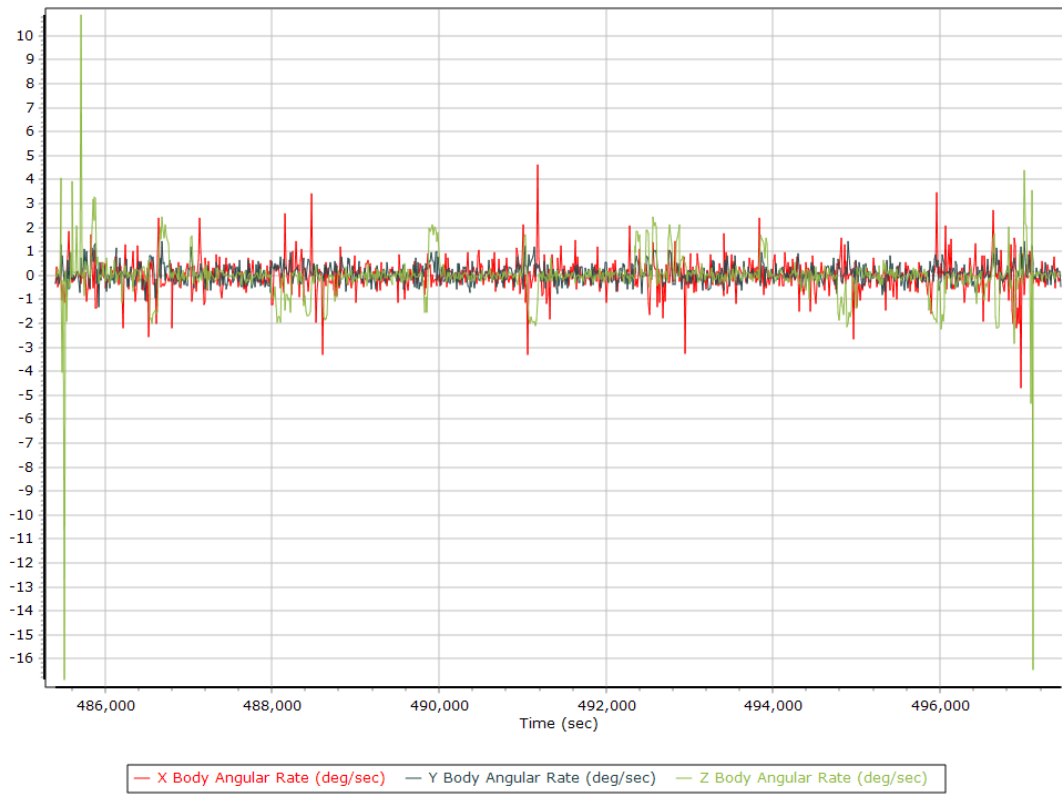
Body Acceleration



Total Body Acceleration

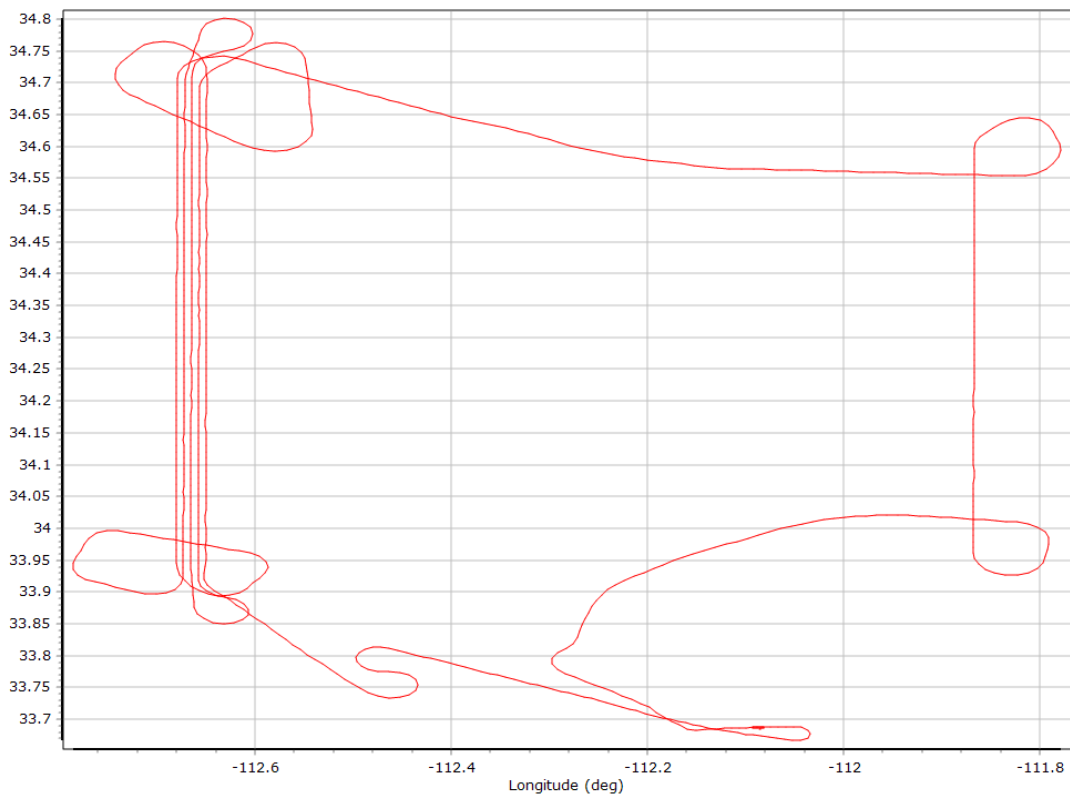


Body Angular Rate

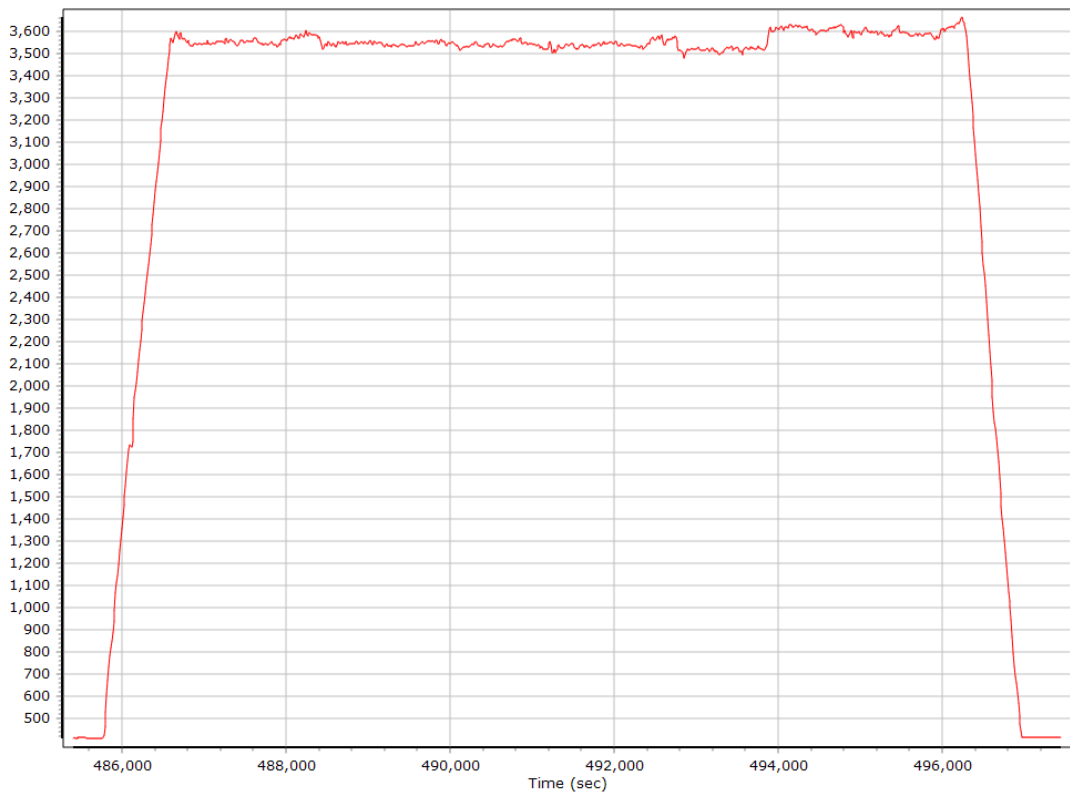


Forward Processed Trajectory Information

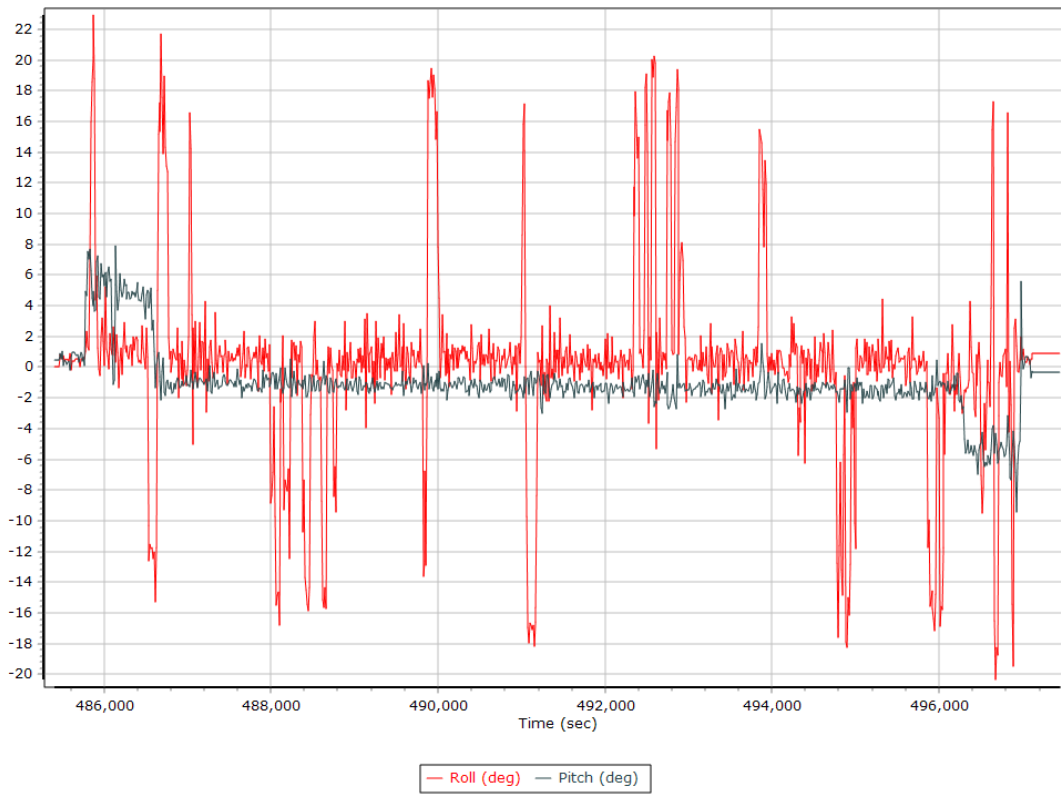
Top View



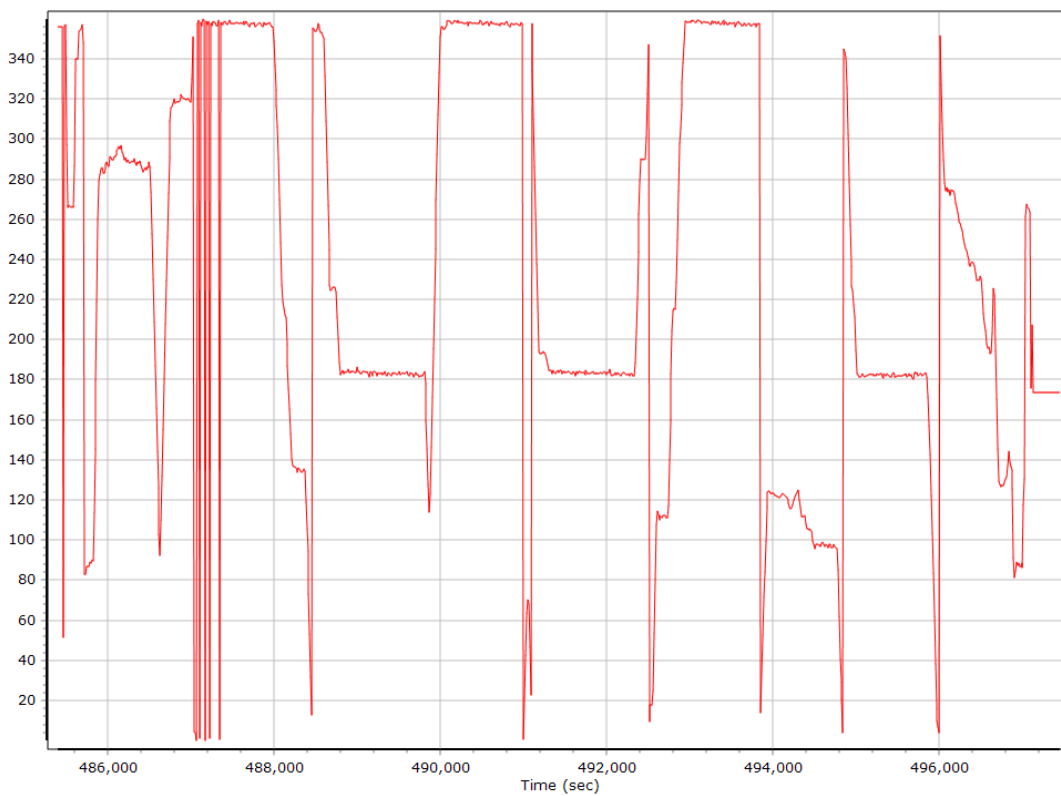
Altitude



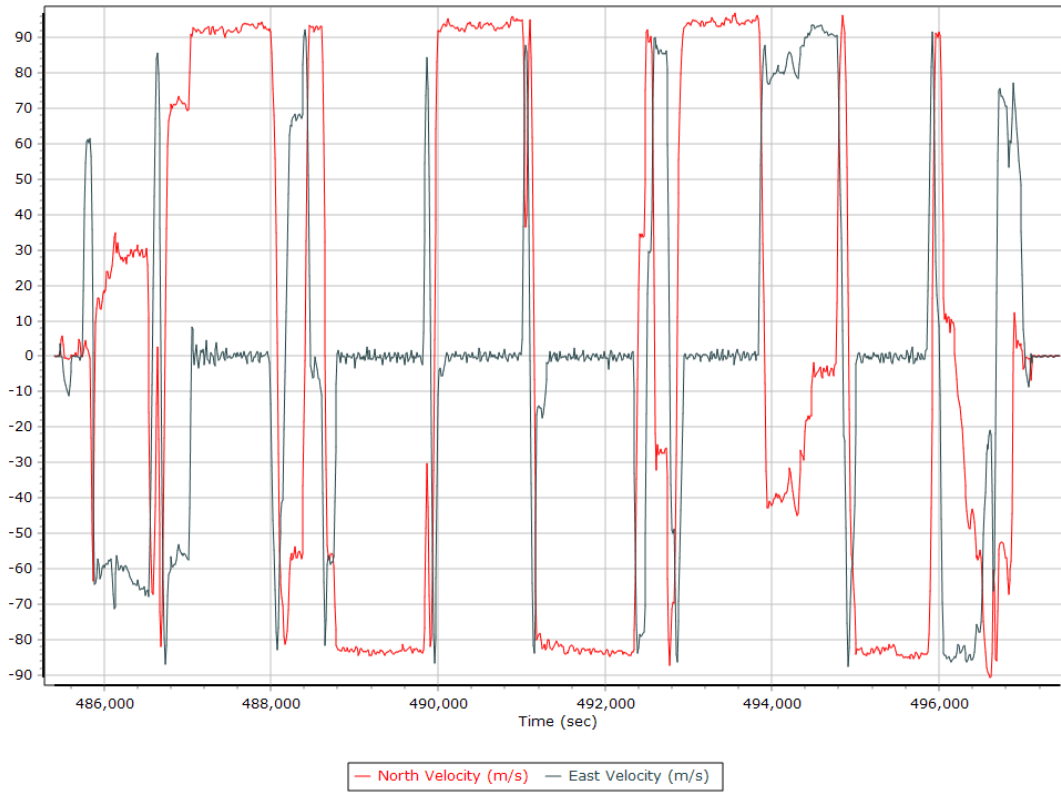
Roll/Pitch



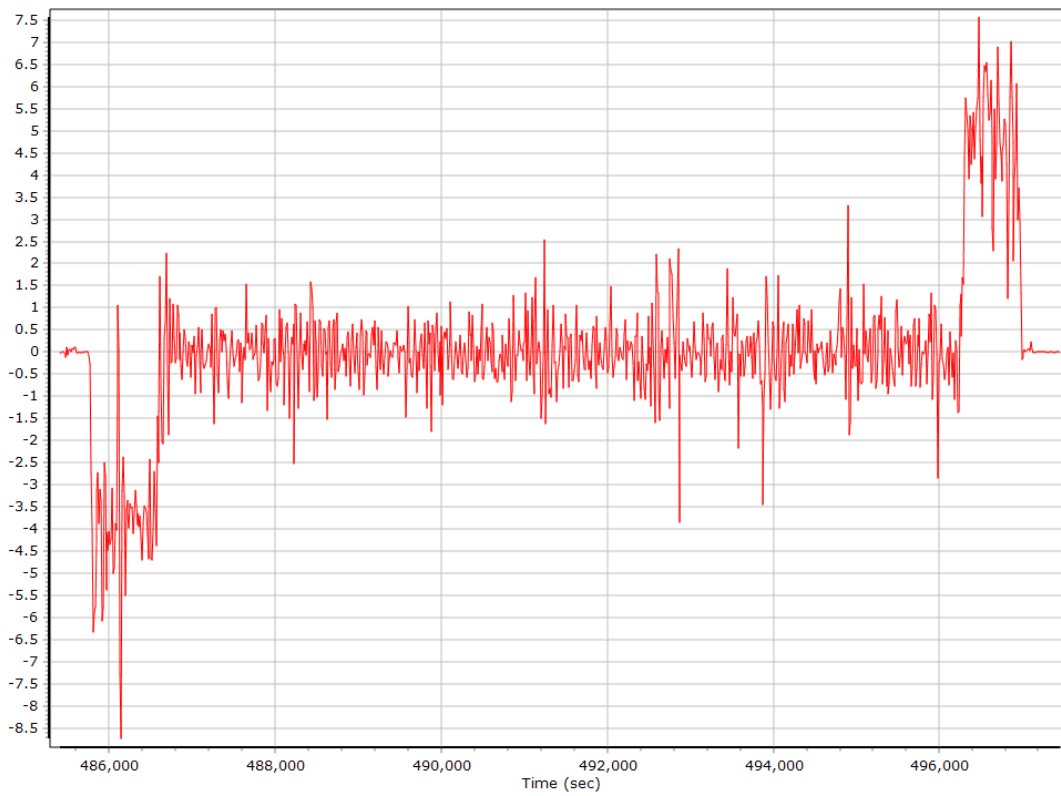
Heading



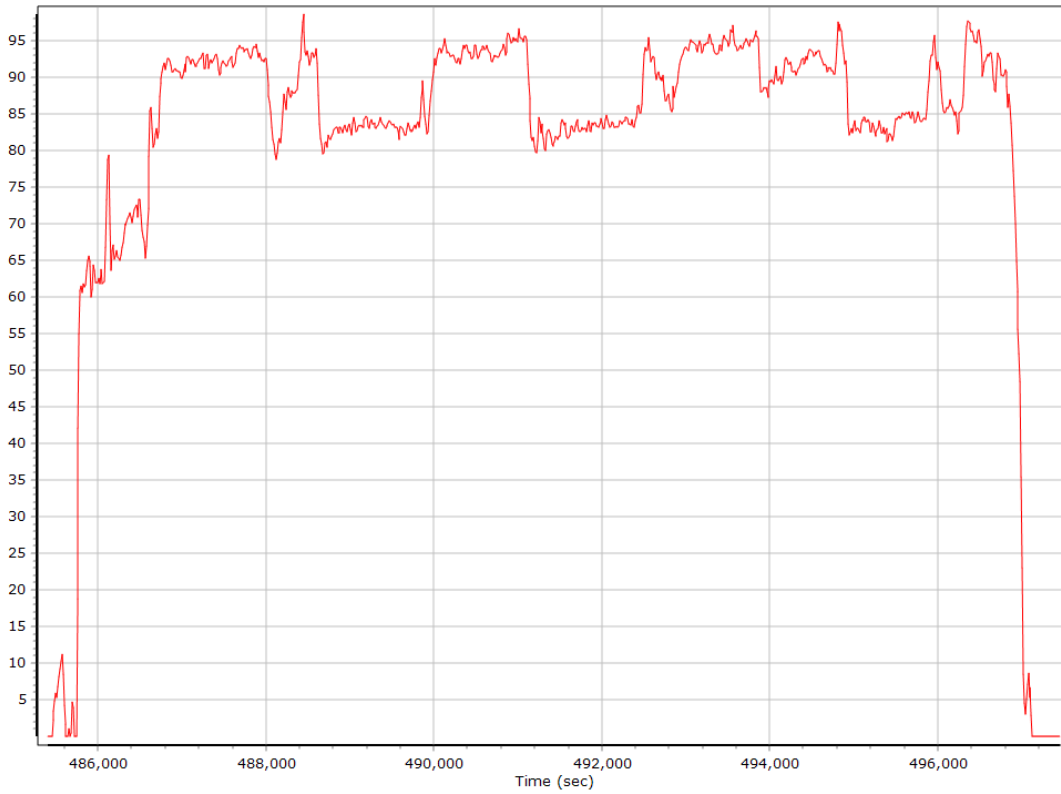
North/East Velocity



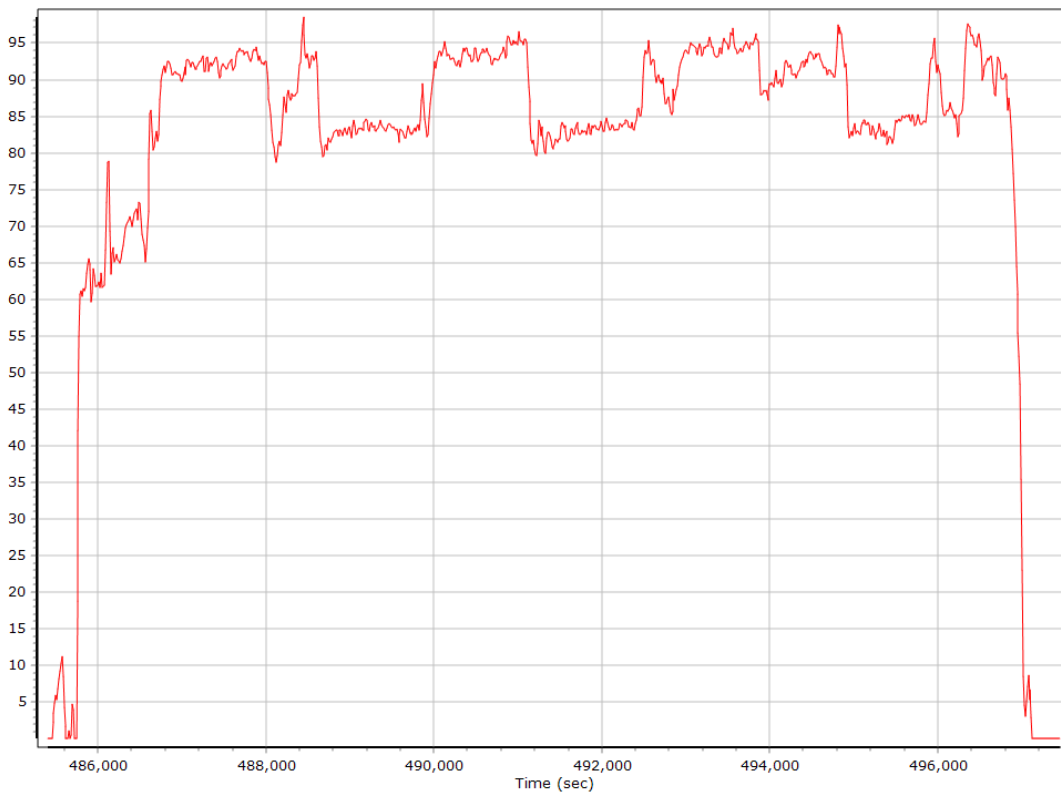
Down Velocity



Total Speed



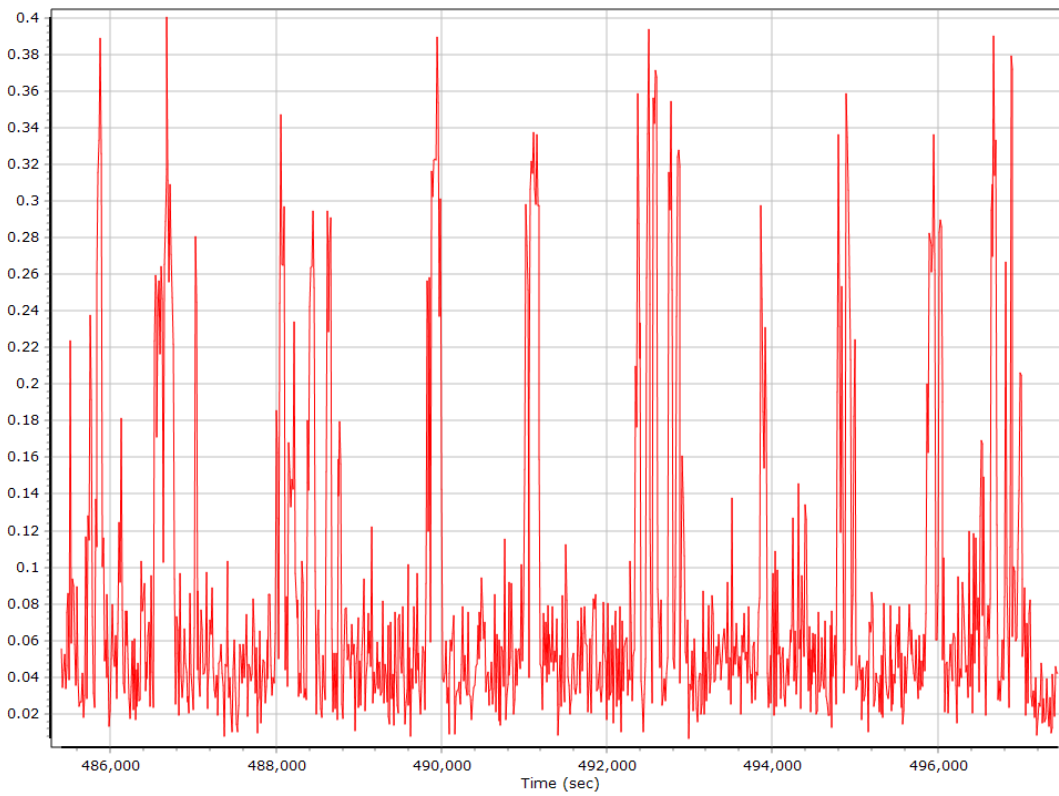
Ground Speed



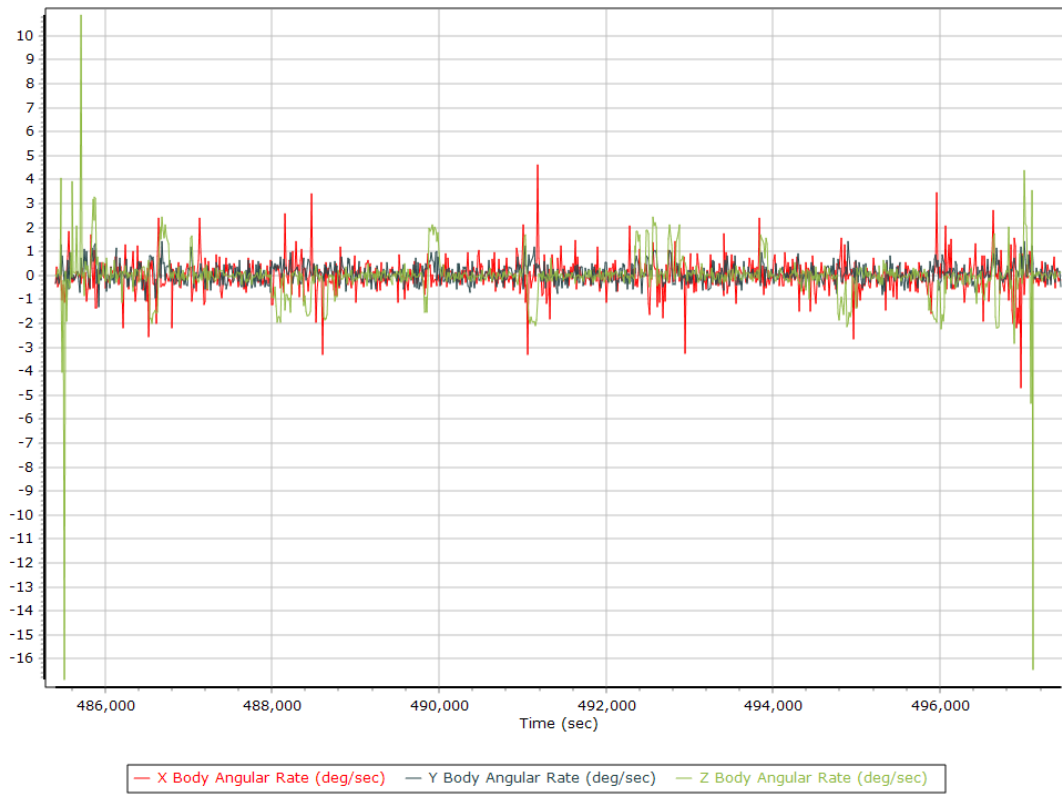
Body Acceleration



Total Body Acceleration



Body Angular Rate

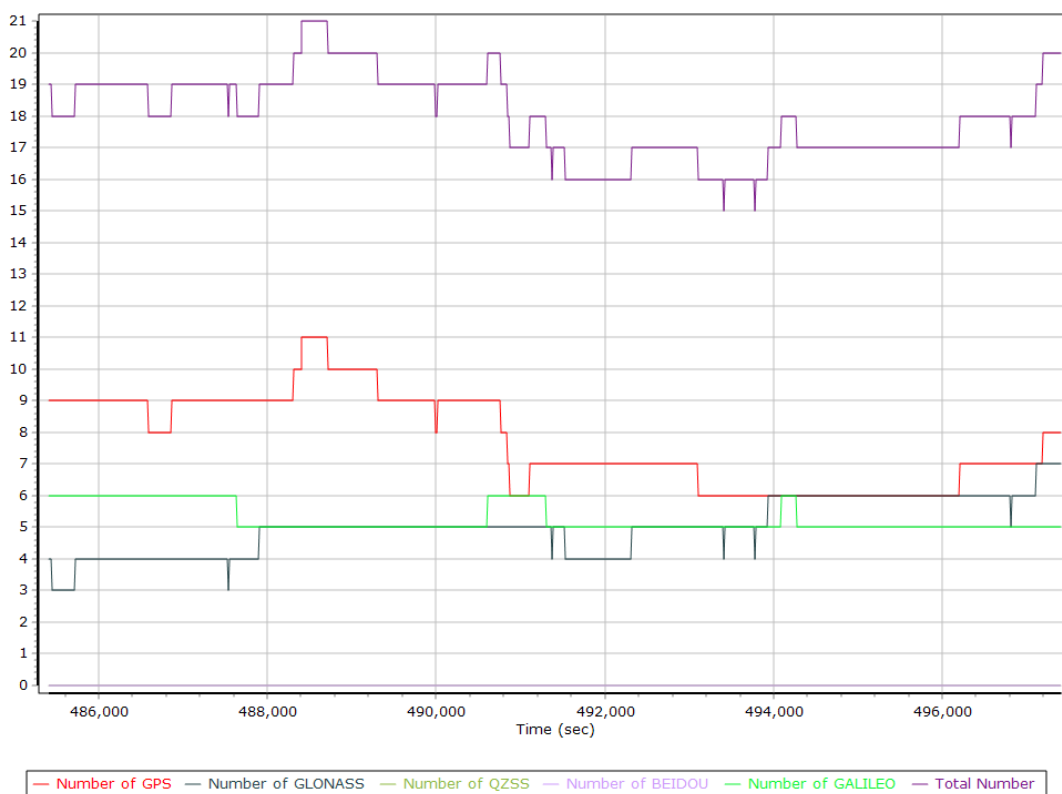


GNSS QC

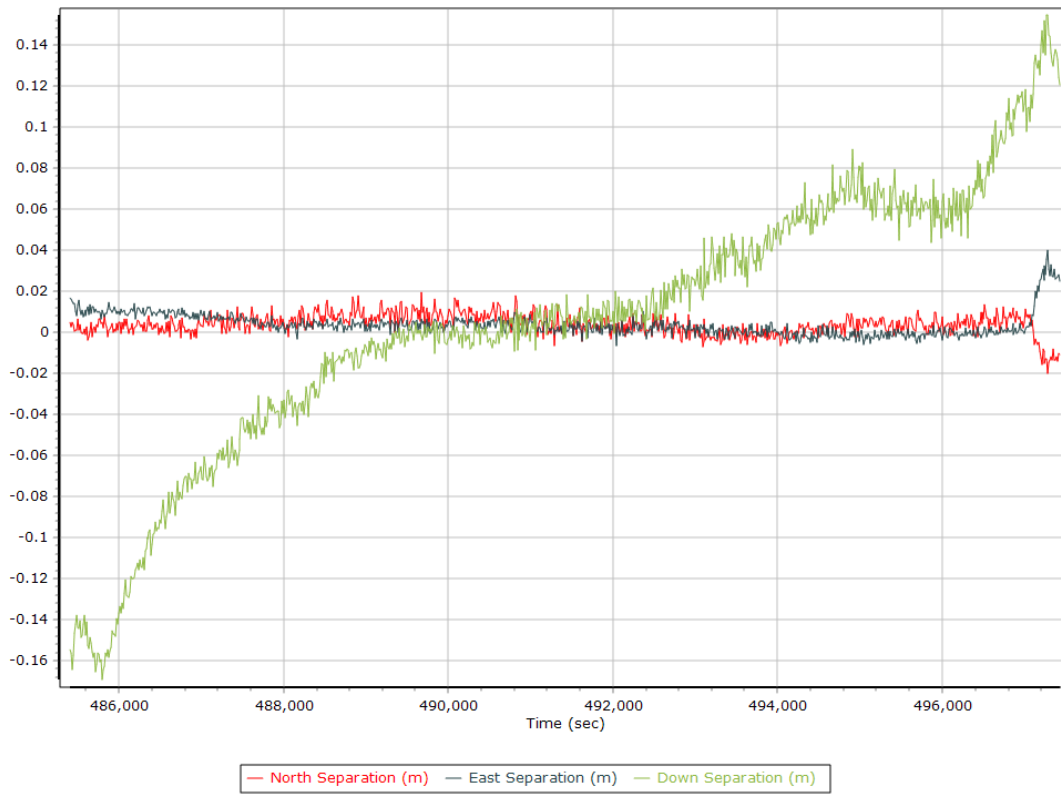
GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	6	11	8
Number of GLONASS SV	3	7	5
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	0	0
Number of GALILEO SV	0	7	5
Total number of SV	13	21	18
PDOP	1.02	1.72	1.26
QC Solution Gaps	0.00	0.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	12396.00	0.00	0.00
Percentage	100.00	0.00	0.00

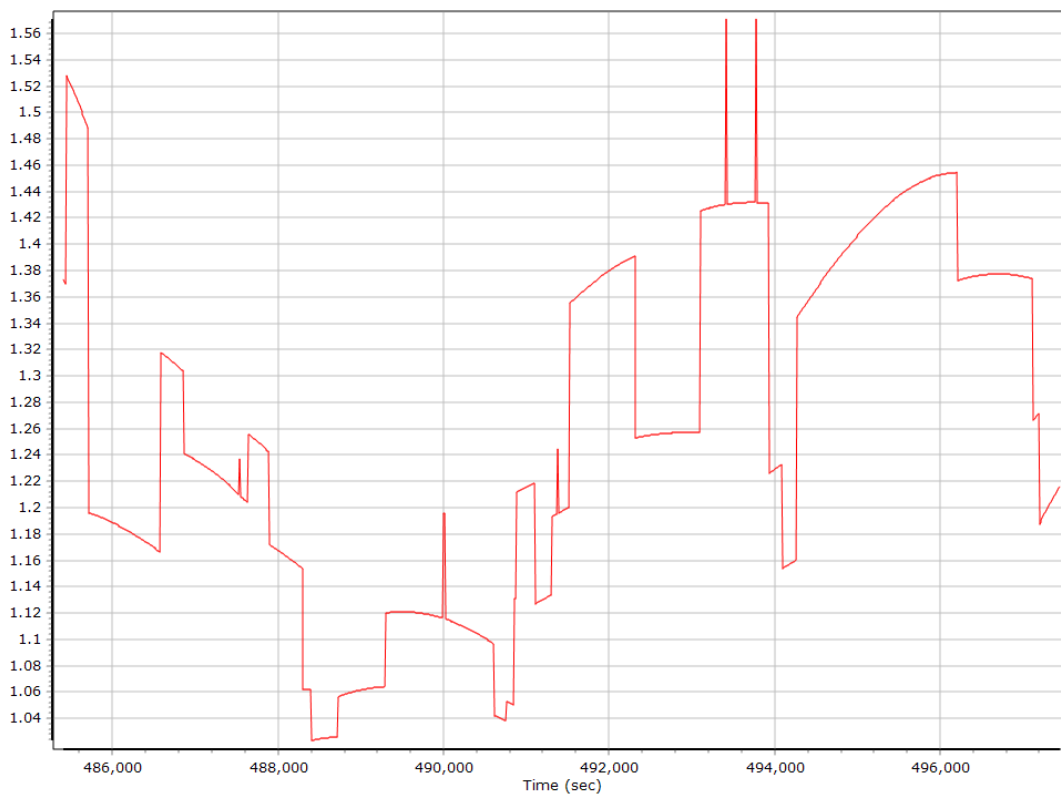
Num SVs in solution



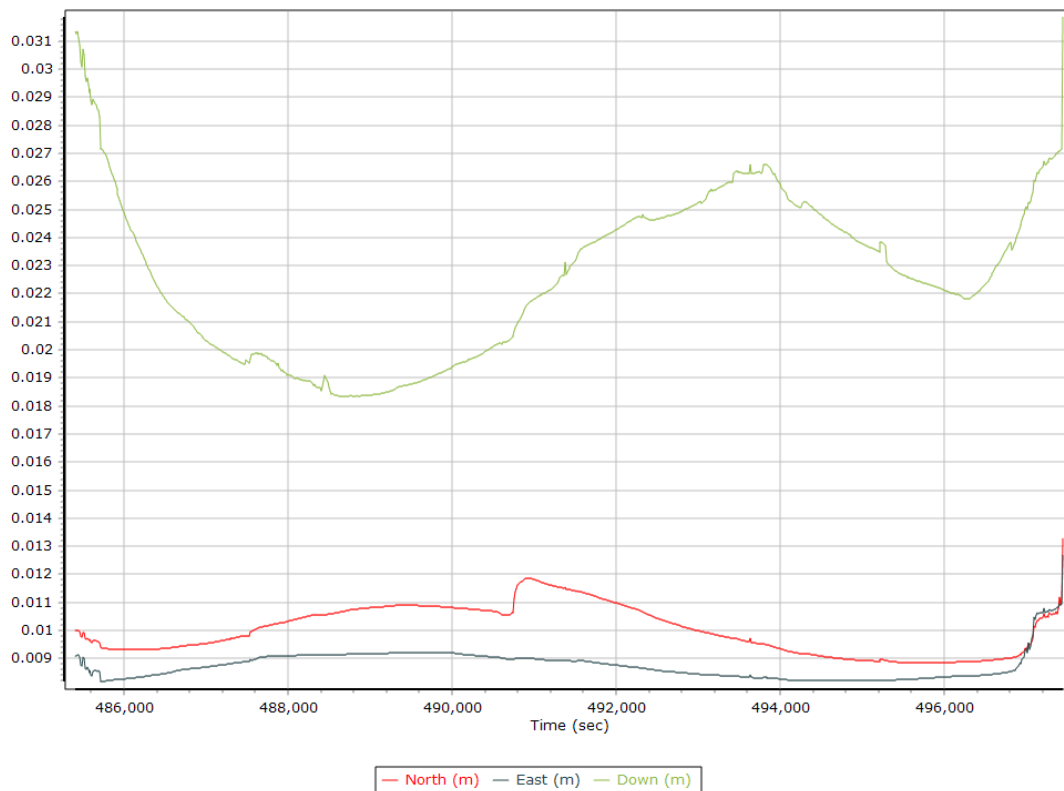
Forward/Reverse Separation



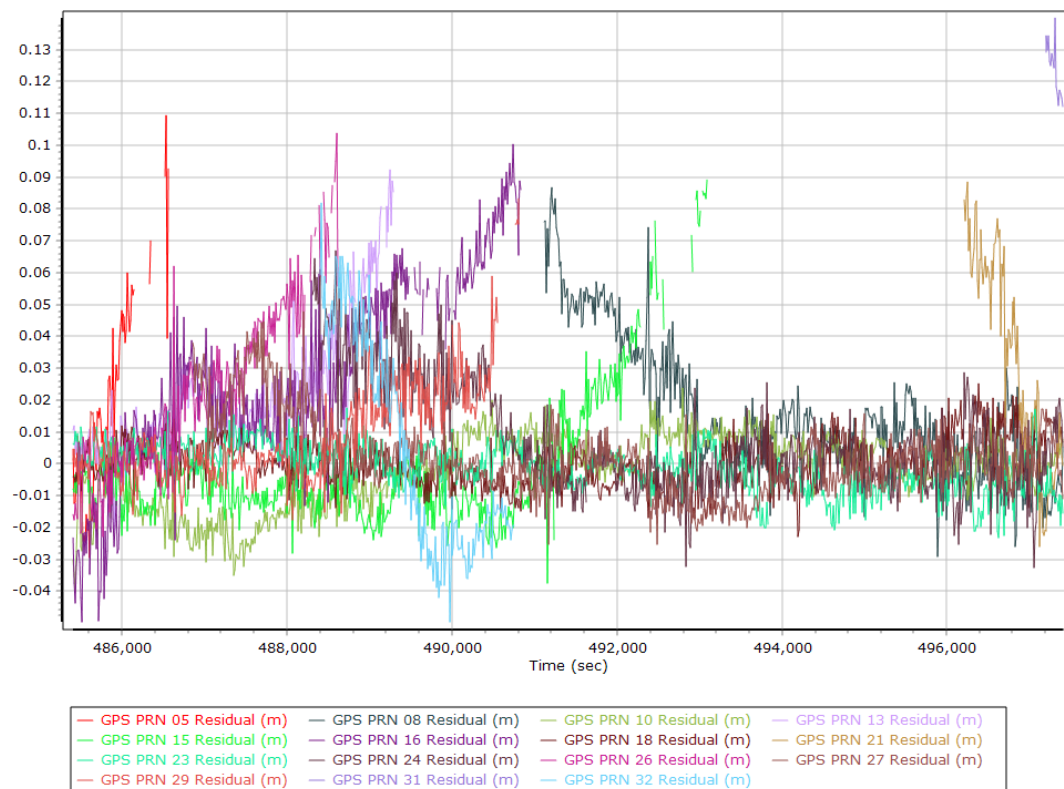
PDOP



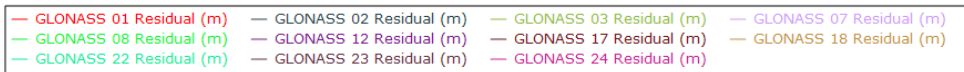
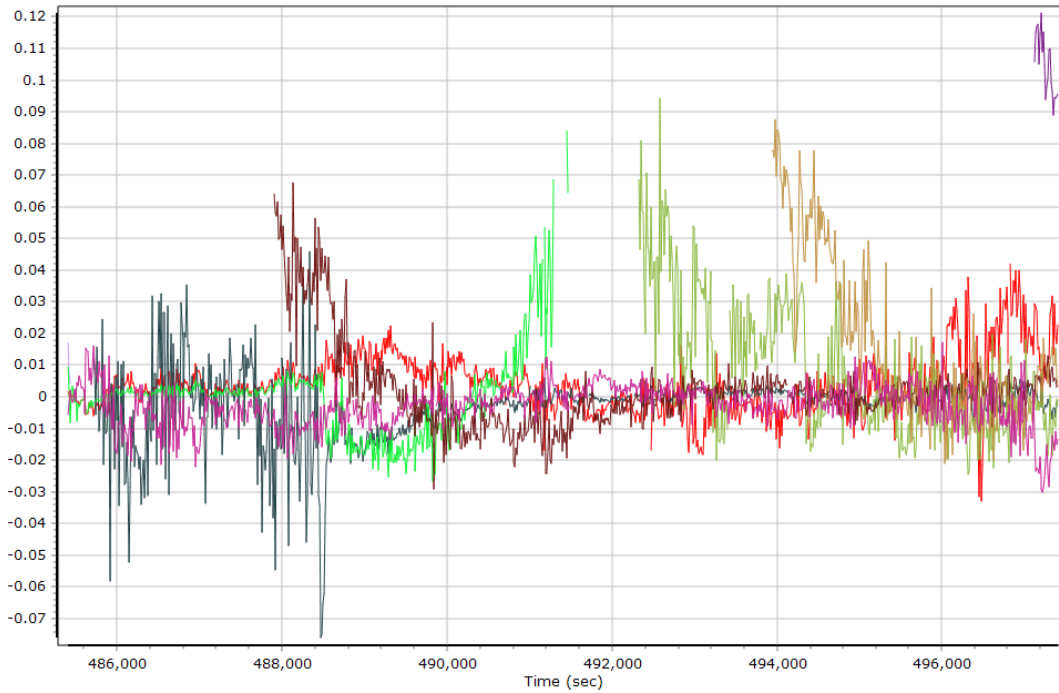
Estimated Position Accuracy



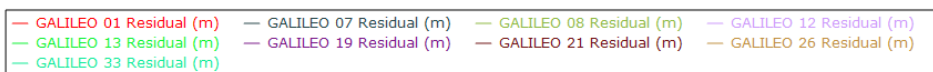
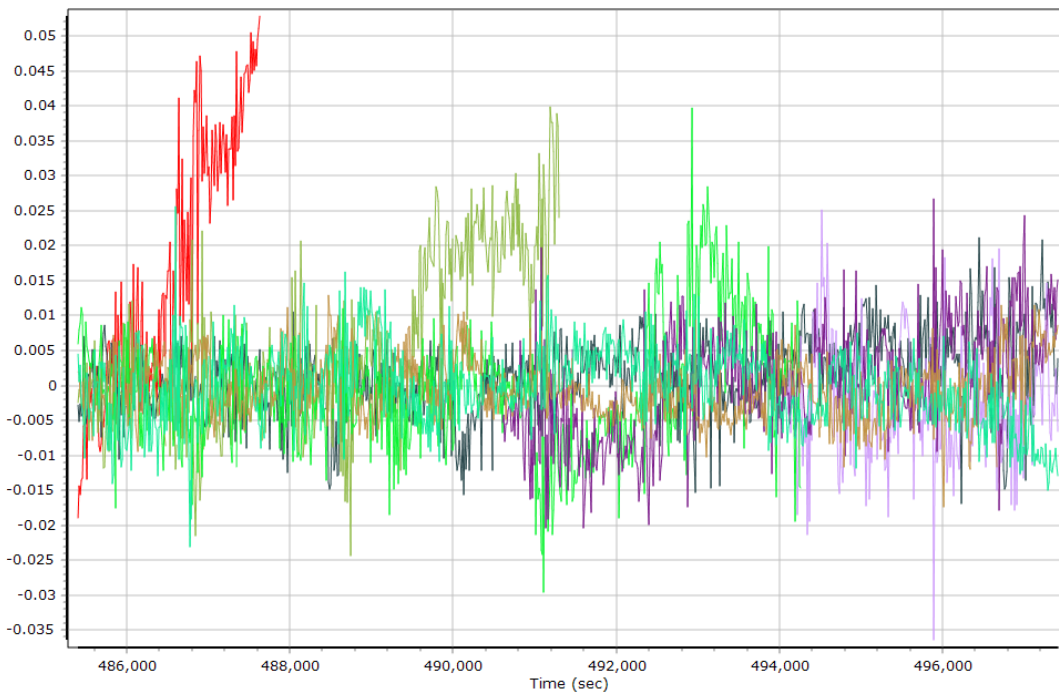
GPS Residuals



GLONASS Residuals



GALILEO Residuals



GNSS-Inertial Processor Configuration

Processing mode	IN-Fusion PP-RTX		
Stabilized mount	False		
Processing start time	485013.000 (10/22/2021 14:43:33)		
Processing end time	497457.000 (10/22/2021 18:10:57)		
Initial attitude source	Real-Time VNAV/RNAV Attitude		
IMU Sensor Context	Processing with Onboard IMU		
Reference to IMU lever arm (m)	0.000	0.000	0.000
Reference to IMU mounting angles (deg)	0.000	0.000	-90.000
Reference to Primary GNSS lever arm (m)	0.527	0.042	-1.185
Reference to Primary GNSS lever arm std dev (m)	0.030	0.030	0.030
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

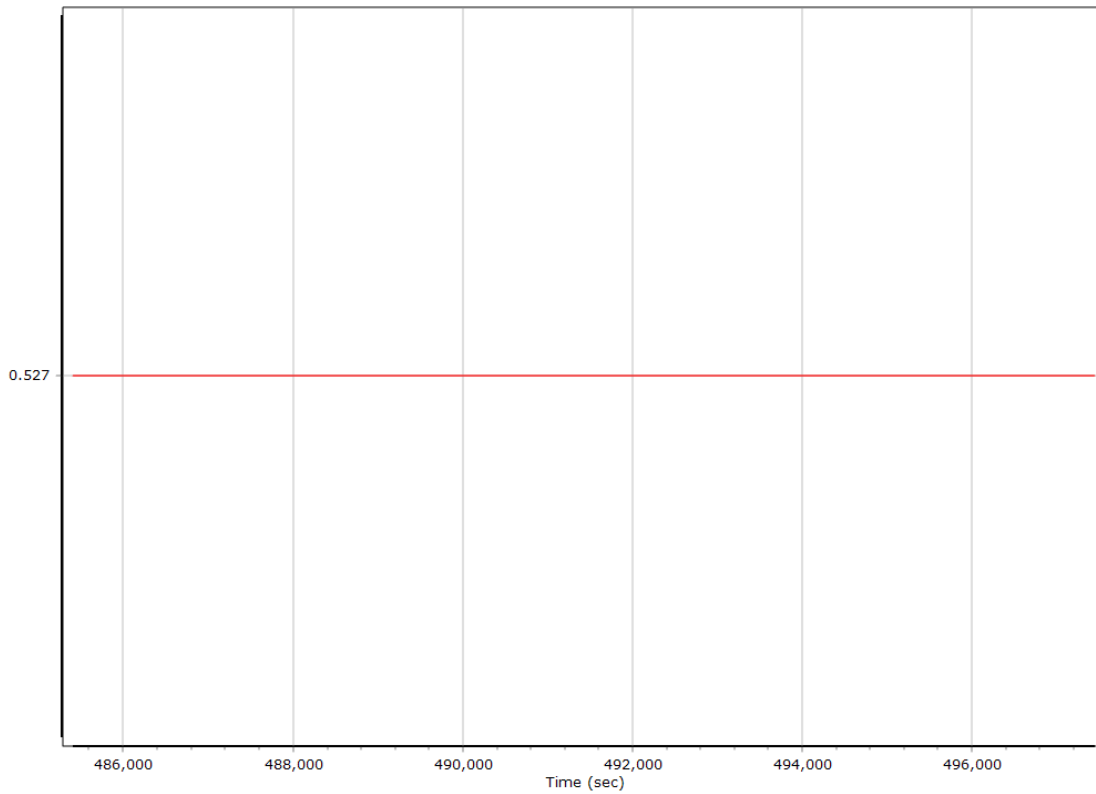
Calibrated Installation Parameters

Reference-Primary GNSS Lever Arm (m)

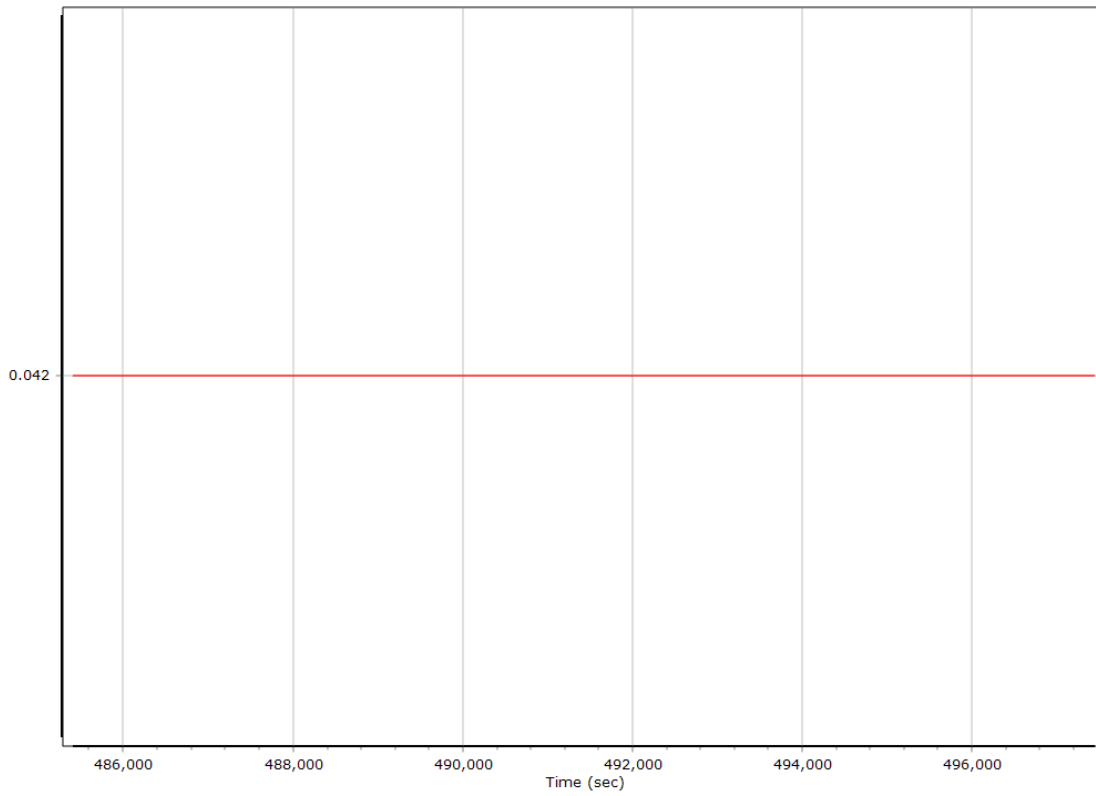
Reference-Primary GNSS Lever Arm Automatic Calibration Results

Original Reference to Primary GNSS lever arm (m)	0.534	0.060	-1.199
Iteration 1 Reference to Primary GNSS lever arm (m)	0.527	0.042	-1.186
Iteration 2 Reference to Primary GNSS lever arm (m)	0.527	0.042	-1.185
Primary GNSS Lever Arm In use	Iteration 2		

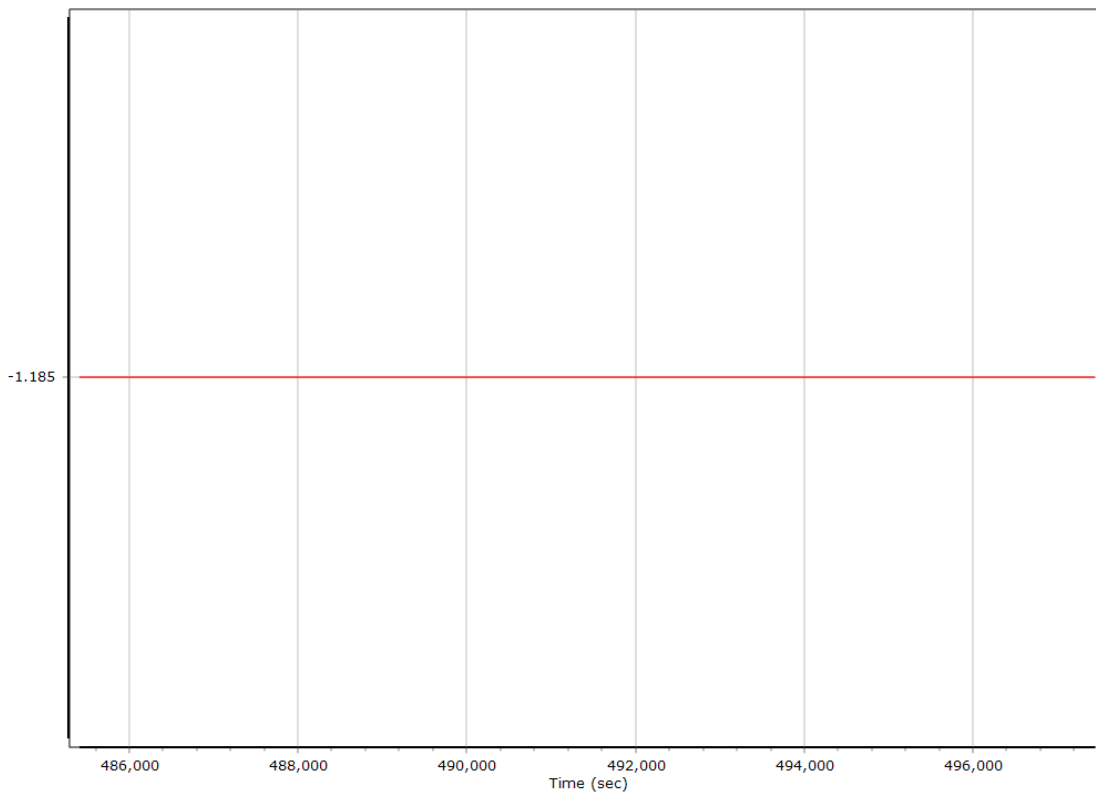
X Reference-Primary GNSS Lever Arm (m)



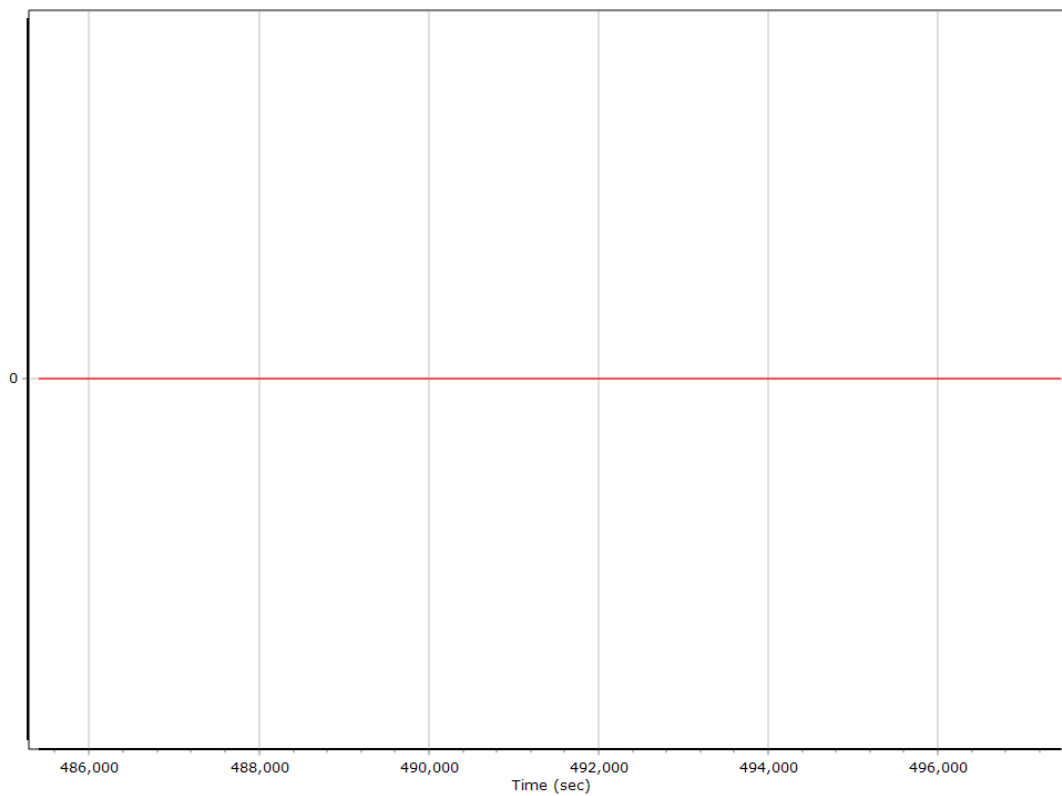
Y Reference-Primary GNSS Lever Arm (m)



Z Reference-Primary GNSS Lever Arm (m)



Reference-Primary GNSS Lever Arm Figure of Merit



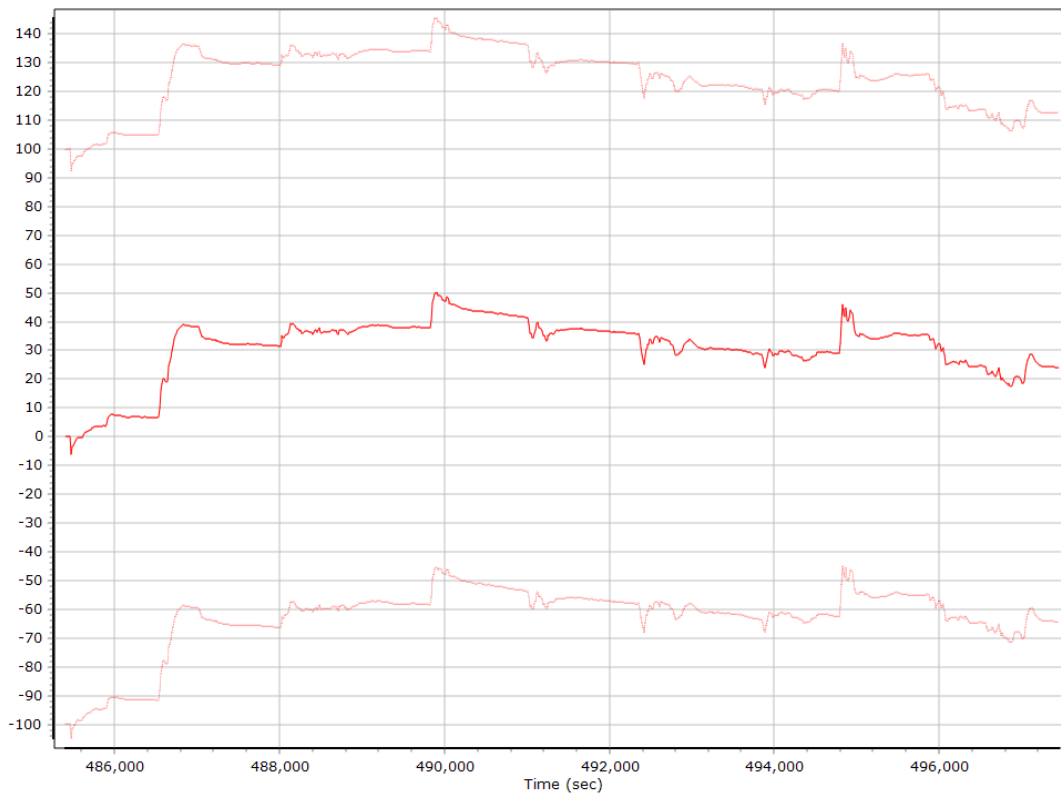
IN-Fusion QC

Forward Processed Estimated Errors, Reference Frame

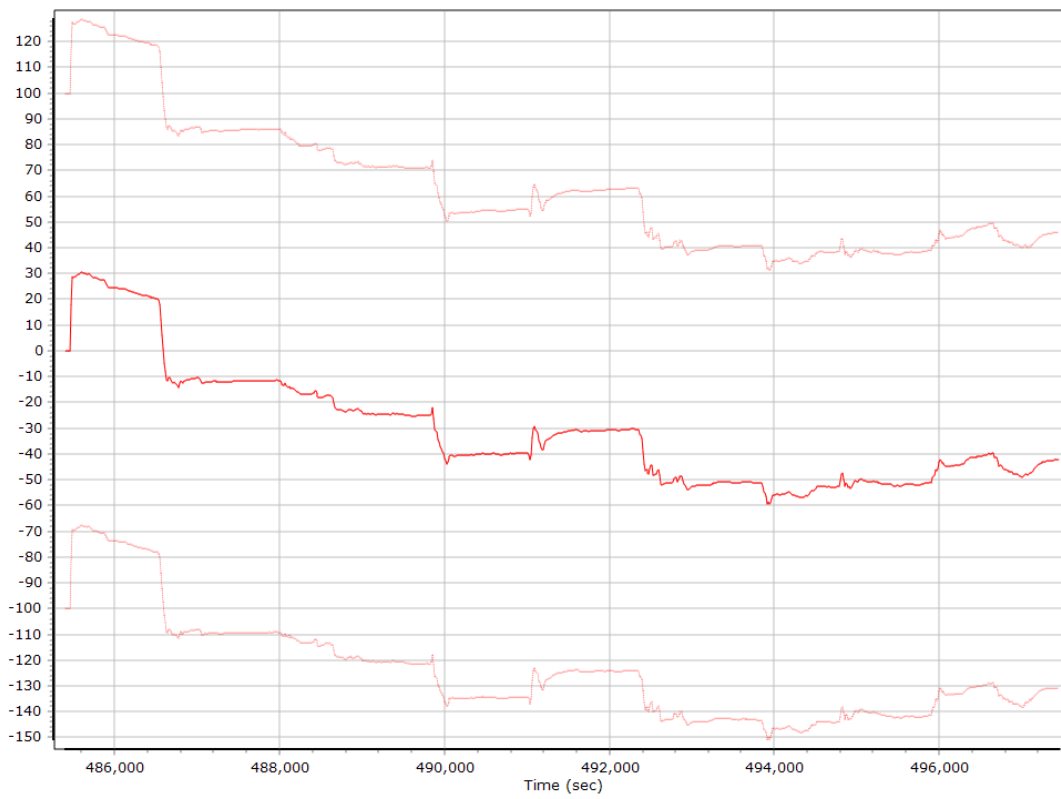
Accelerometer Bias (micro-g)



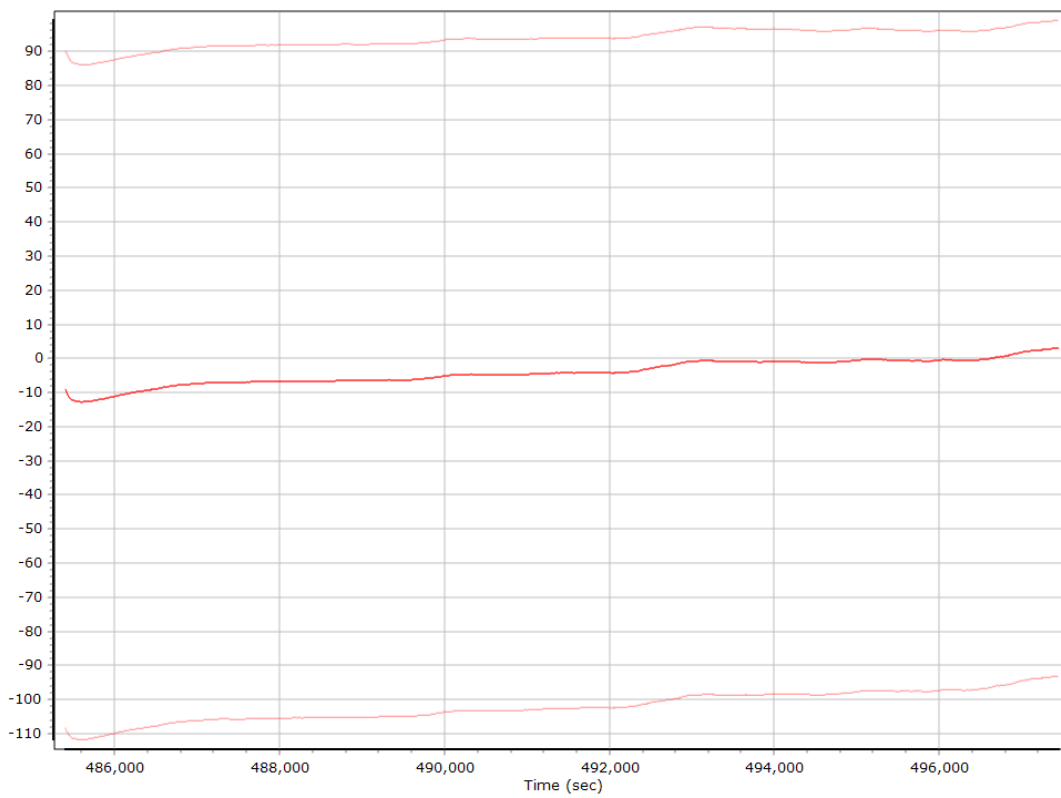
X Accelerometer Bias (micro-g)



Y Accelerometer Bias (micro-g)



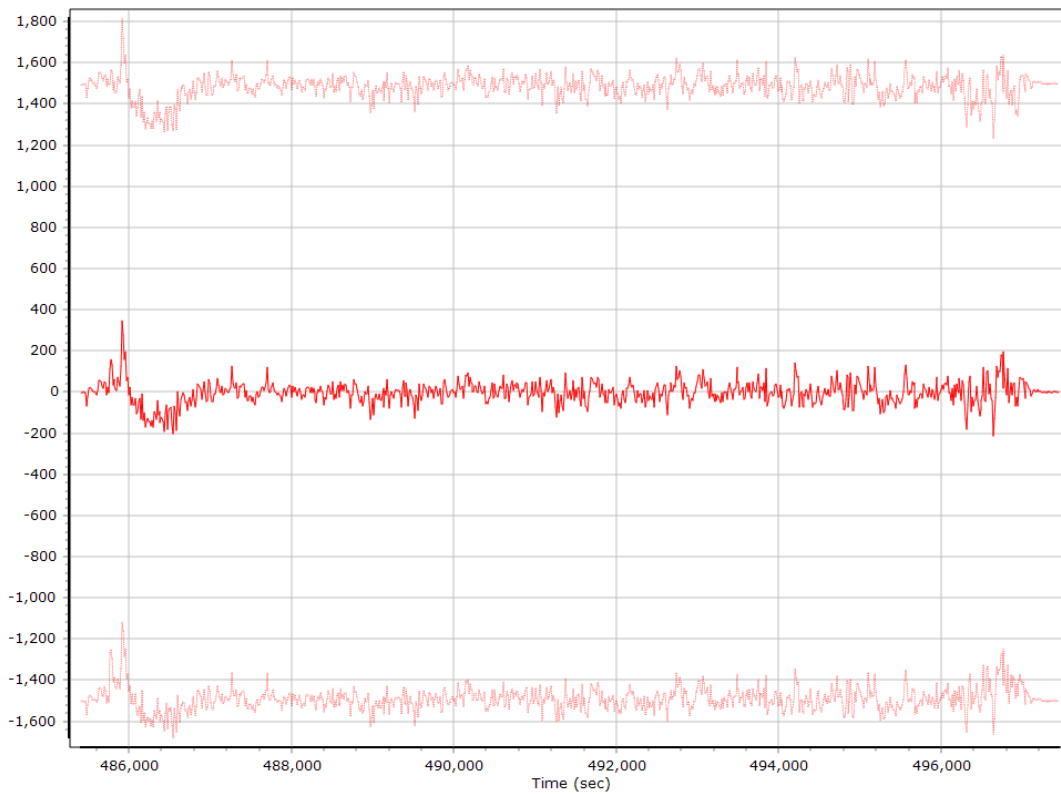
Z Accelerometer Bias (micro-g)



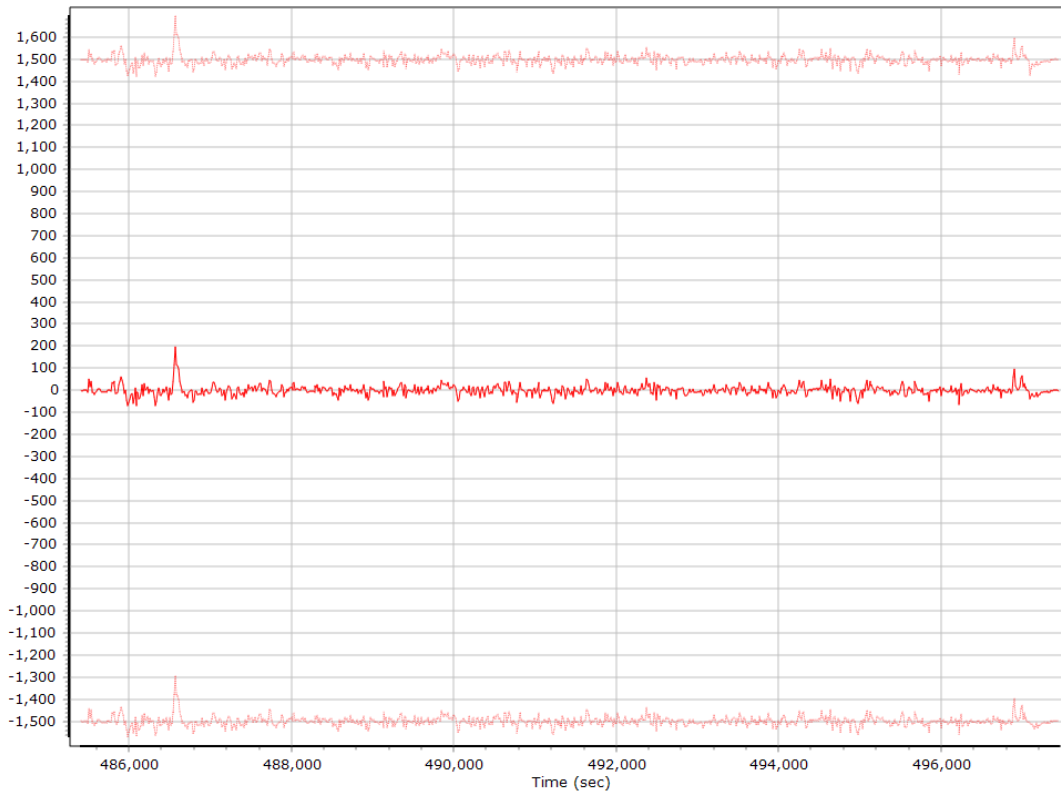
Accelerometer Scale Error (ppm)



X Accelerometer Scale Error (ppm)



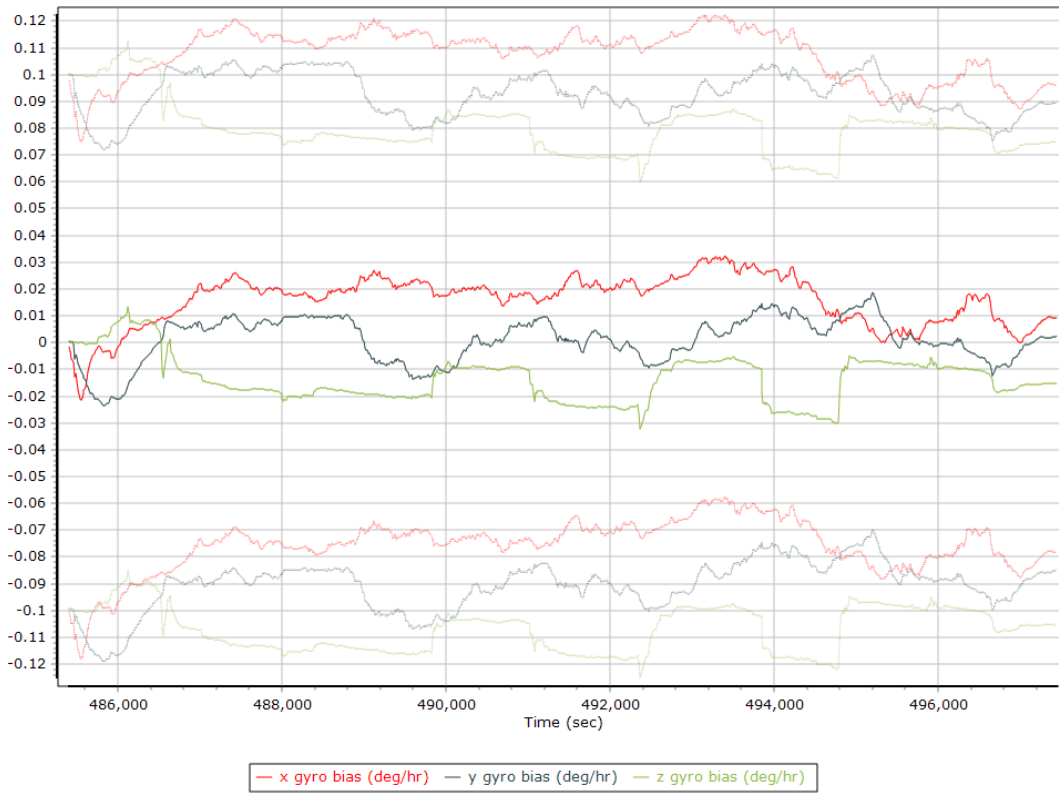
Y Accelerometer Scale Error (ppm)



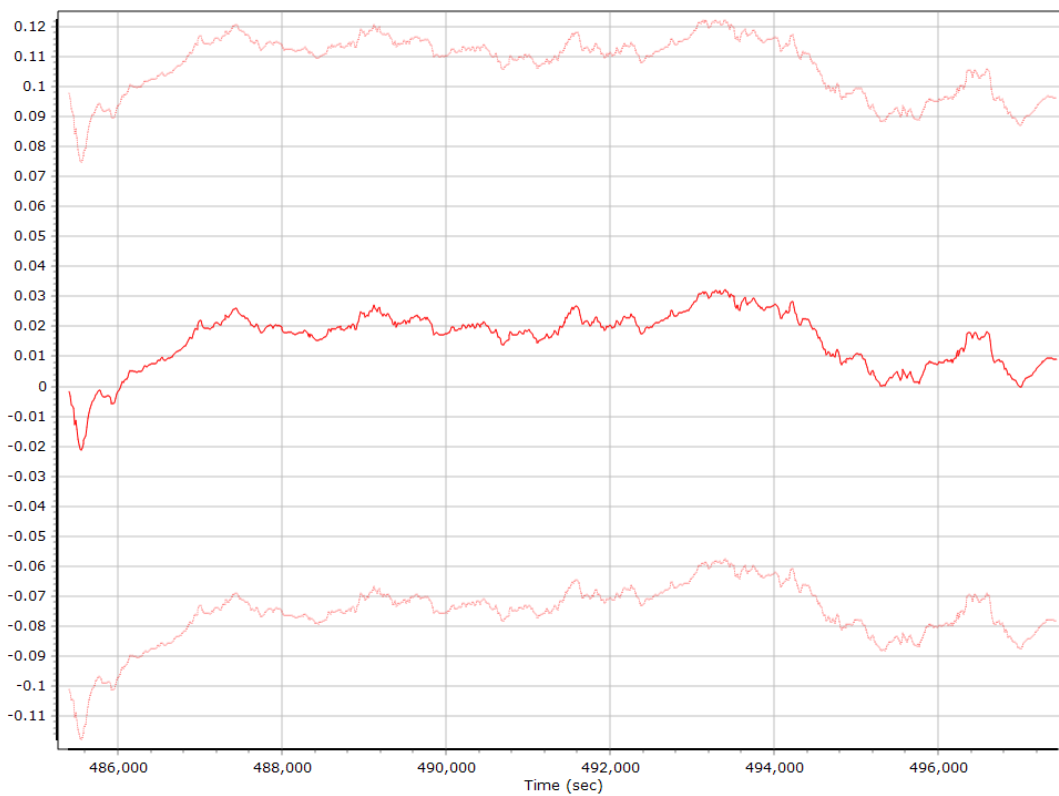
Z Accelerometer Scale Error (ppm)



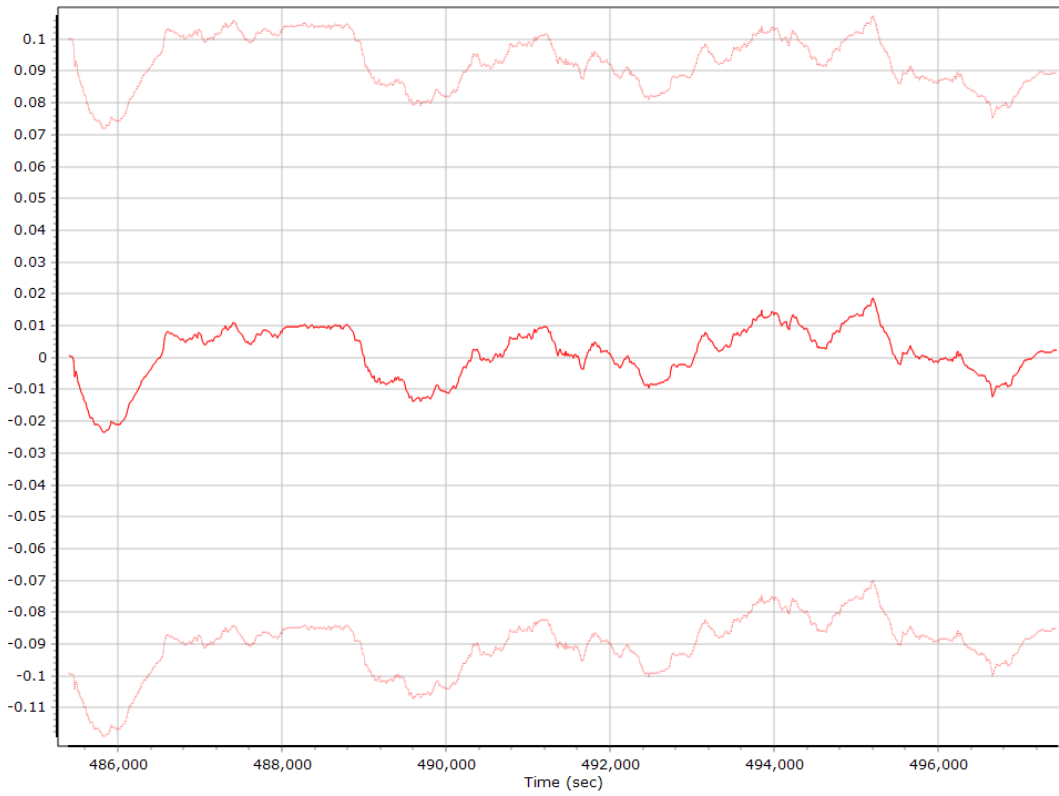
Gyro Bias (deg/h)



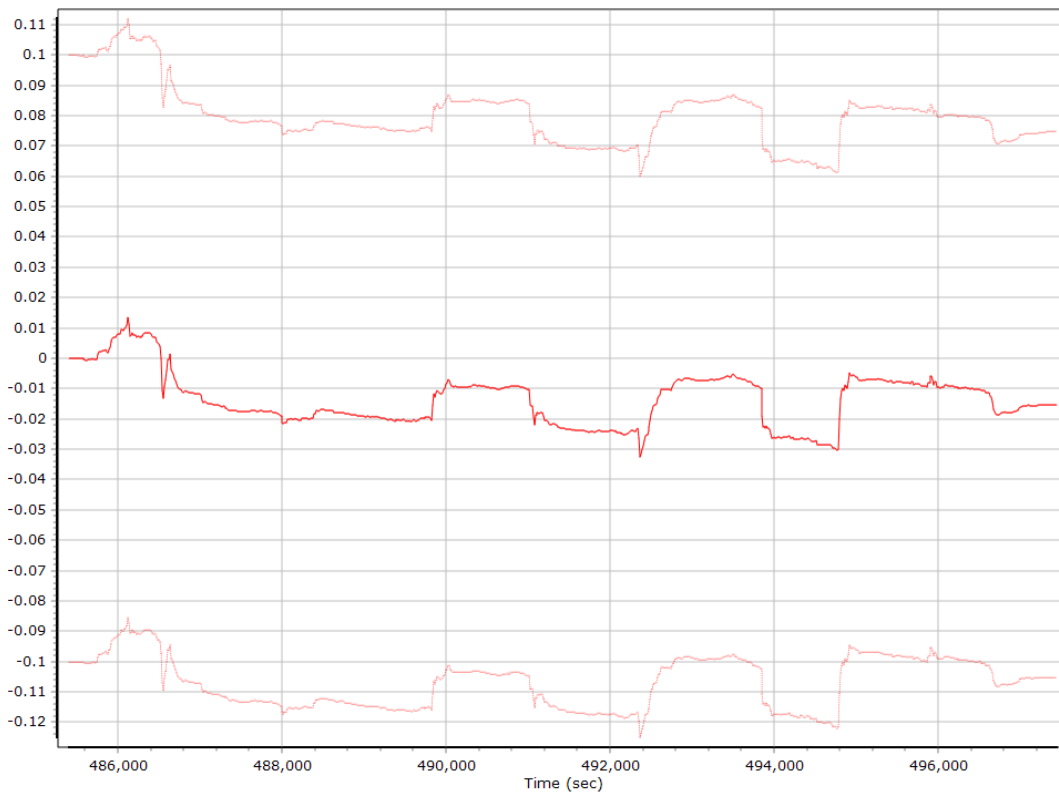
X Gyro Bias (deg/h)



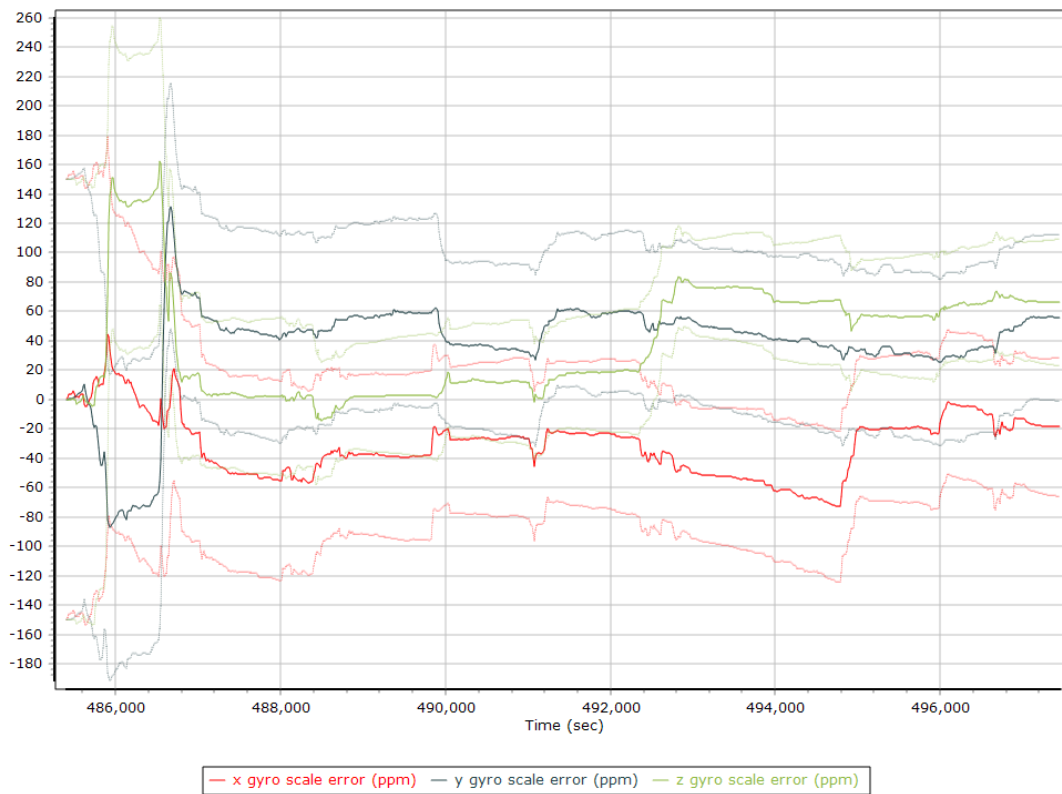
Y Gyro Bias (deg/h)



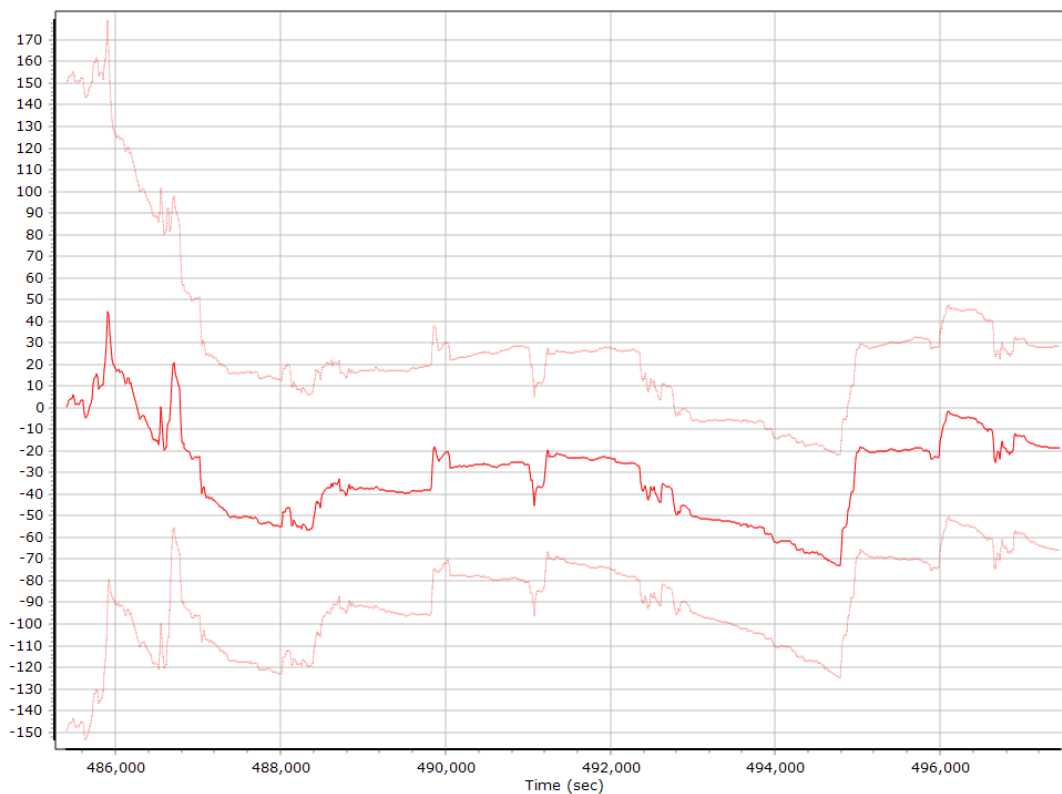
Z Gyro Bias (deg/h)



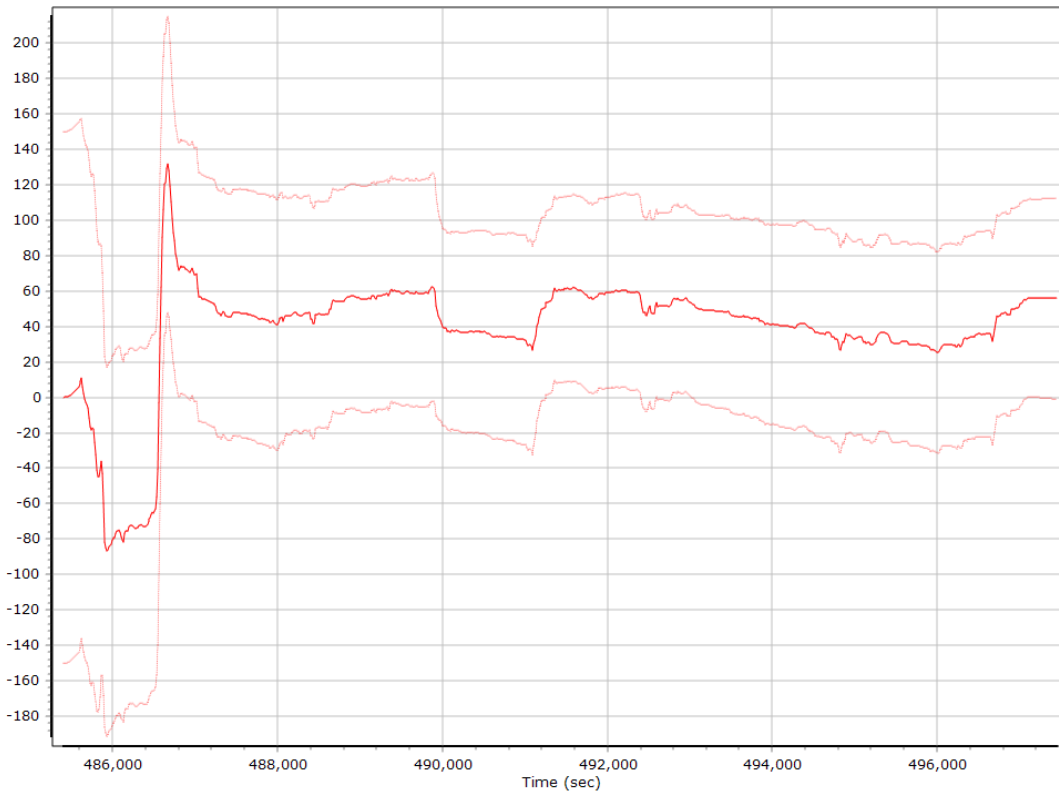
Gyro Scale Error (ppm)



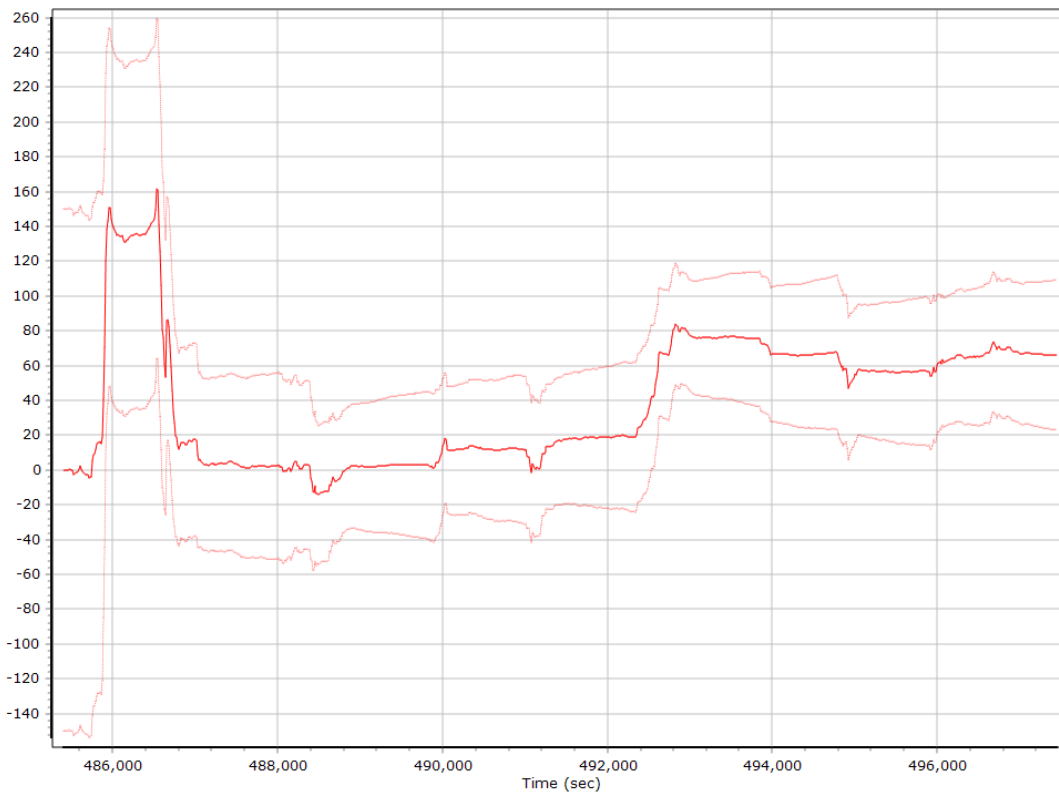
X Gyro Scale Error (ppm)



Y Gyro Scale Error (ppm)



Z Gyro Scale Error (ppm)

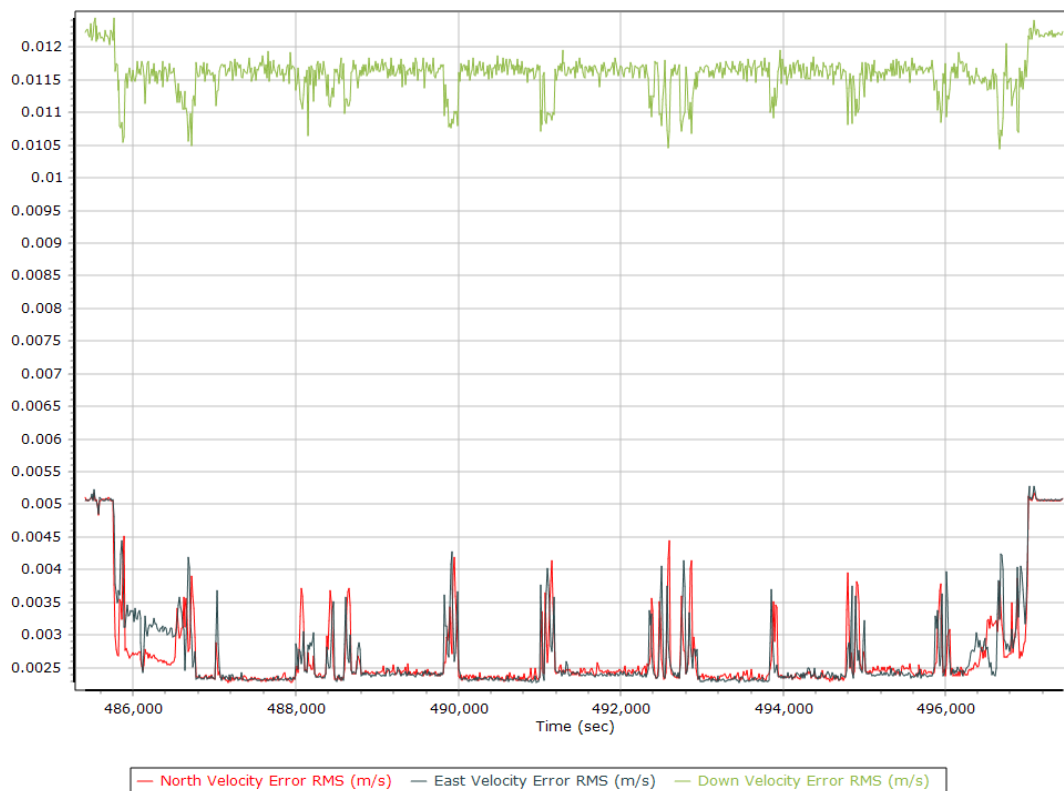


Smoothed Performance Metrics

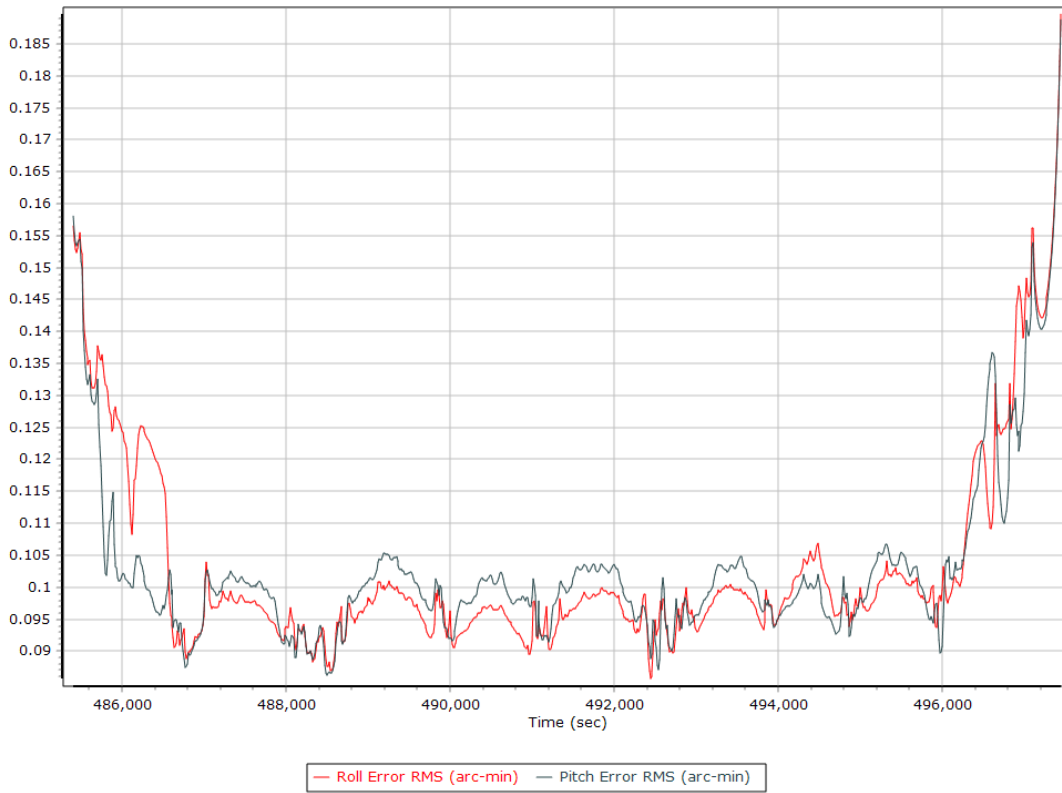
Position Error RMS (m)



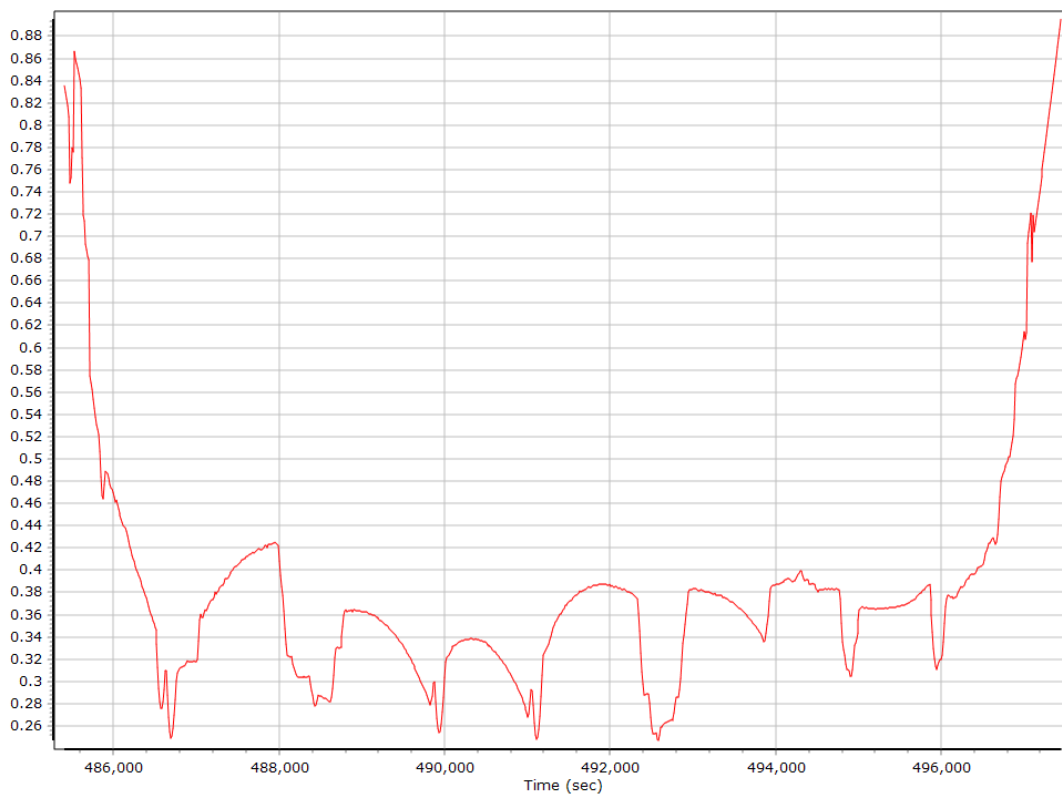
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

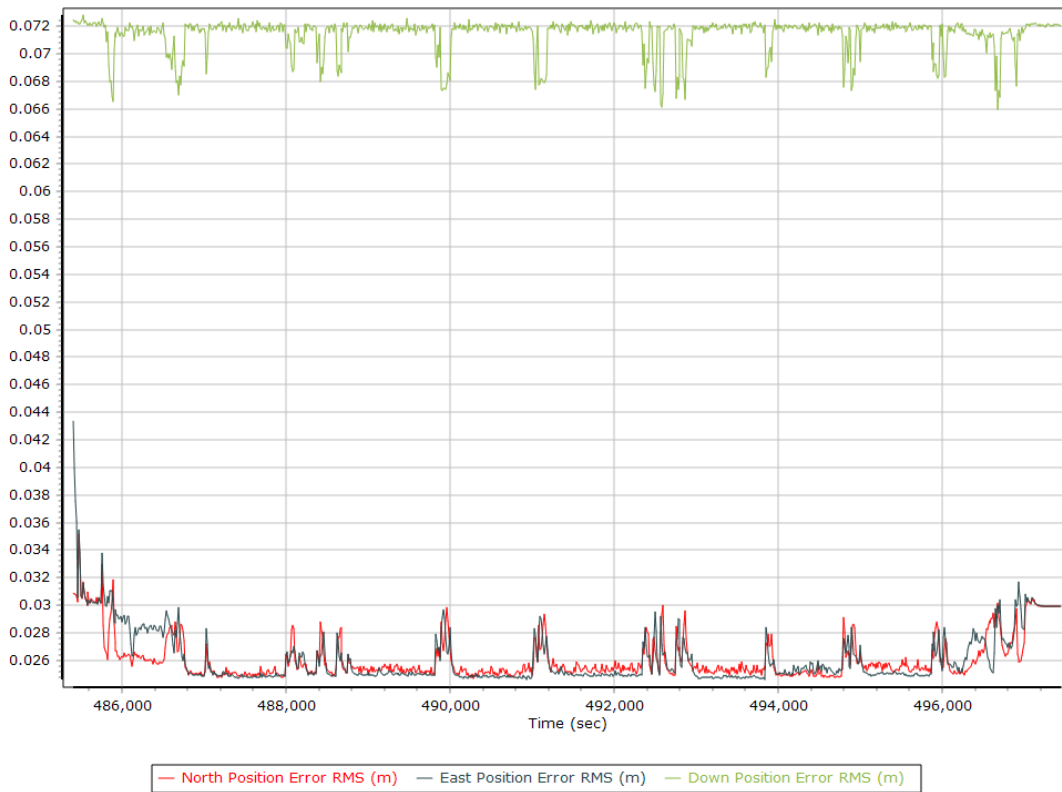


Heading Error RMS (arc-min)

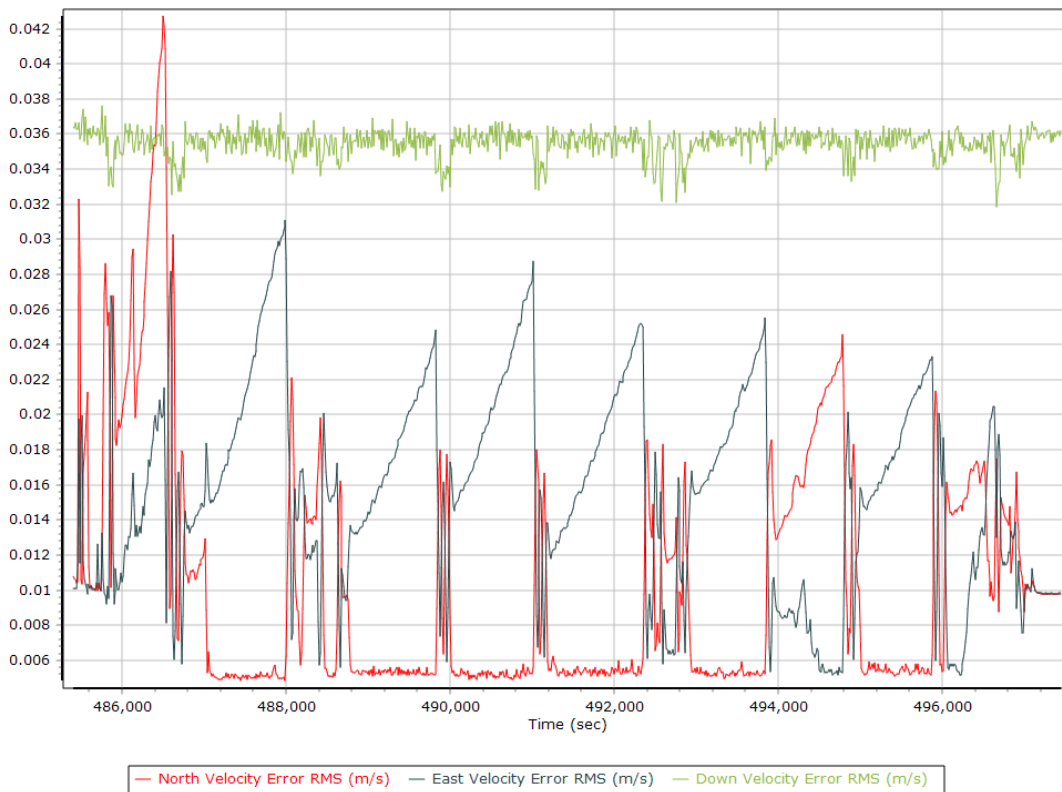


Forward Processed Performance Metrics

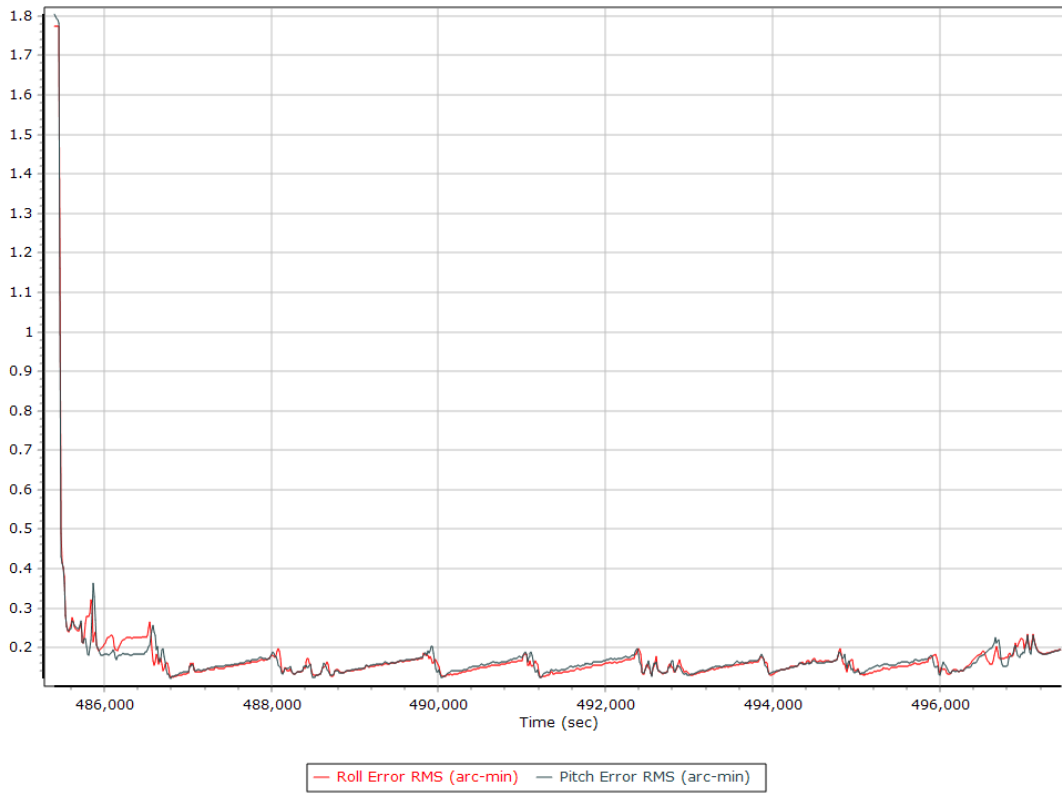
Position Error RMS (m)



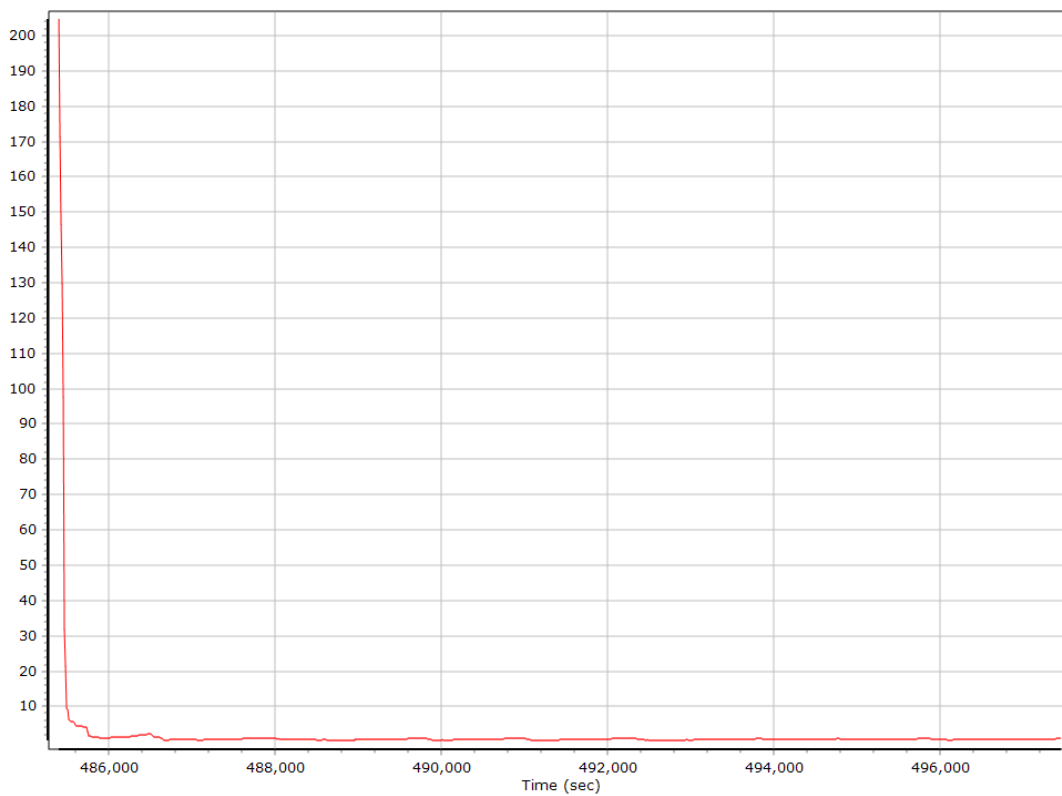
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

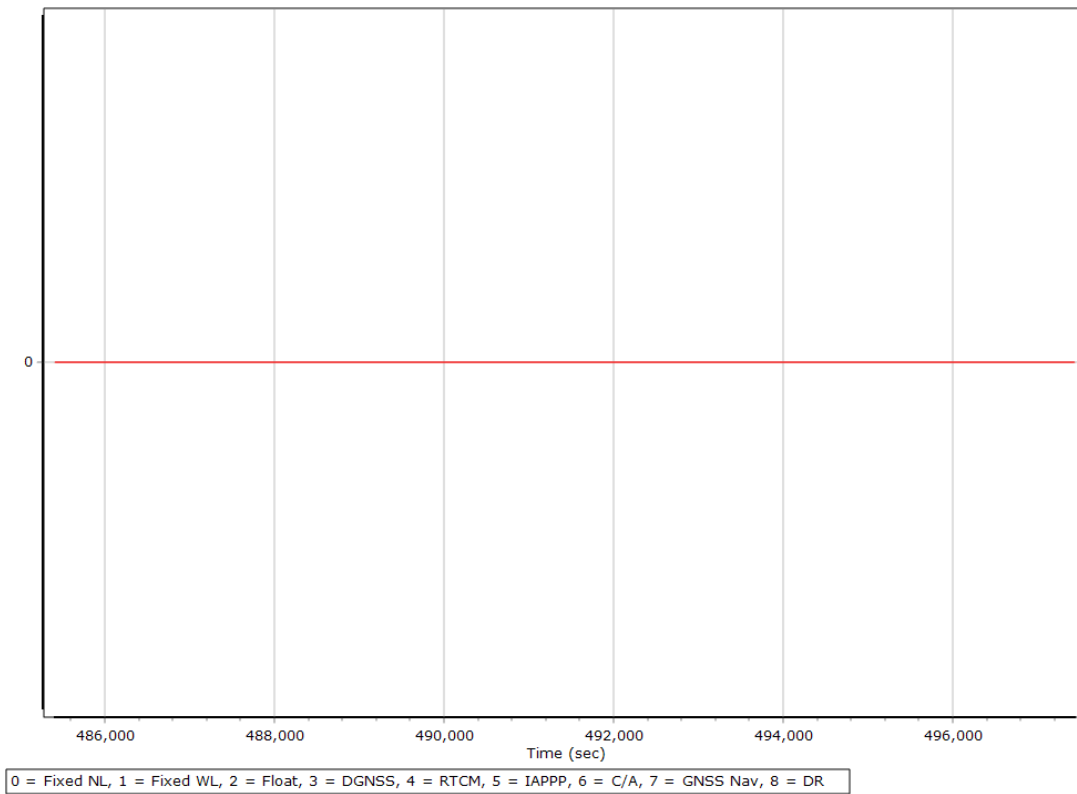


Heading Error RMS (arc-min)

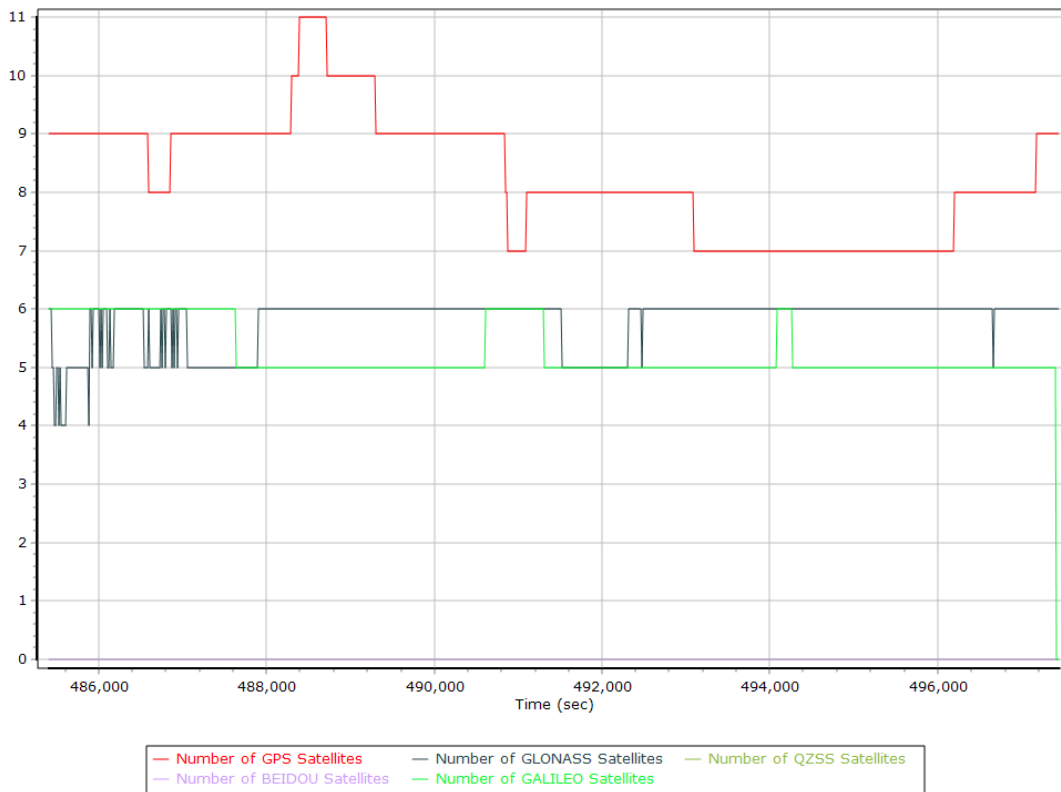


Forward Processed Solution Status

Processing Mode



Number of Satellites



Baseline Length

