General Information

Mission Information

Project name	211105_B_5060420_nad2011_FINAL
Processing date	2021-11-10 21:12:00
Mission date	2021-11-05 21:17:16
Mission duration	02:41:10.000
Processing mode	IN-Fusion PP-RTX

Rover Hardware Information

Product	POS AV 610 VER6 HW2.5-12
Serial number	S/N9825
IMU type	57
Receiver type	BD982
Antenna type	Unknown External

Project File List

Rover Data Files

File name	File type
survey3.pos	POS Data

Input Files

File Name	File Type
Ephm3090.21g	GLONASS Broadcast Ephemeris
Ephm3090.21n	GPS Broadcast Ephemeris
Ephm3100.21g	GLONASS Broadcast Ephemeris
Ephm3100.21n	GPS Broadcast Ephemeris

Output Files

Filename	File type
sbet_211105_B_5060420_nad2011_FINAL.out	SBET Trajectory File

Rover Data Summary

First raw data file	survey3.pos		
Last raw data file	survey3.pos		
Start GPS week	2182		
Start time	508635.897 (11/5/2021 9:17:15 PM)		
End time	518306.482 (11/5/2021 11:58:26 PM)		
Start of fine alignment	509000.954 (11/5/2021 9:23:20 PM)		
Available subsystems	Primary GNSS, IMU		
POS Event Input	None		
Correction data	None		
IMU Installation Lever Arms & Mounting Angles			
Reference to IMU lever arm (m)	0.000	0.000	0.000
Reference to IMU mounting angles (deg)	0.000	0.000	90.000
Reference to Primary GNSS lever arm (m)	-0.497	-0.045	-1.199
Reference to Primary GNSS lever arm std dev (m)	-1.000		
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

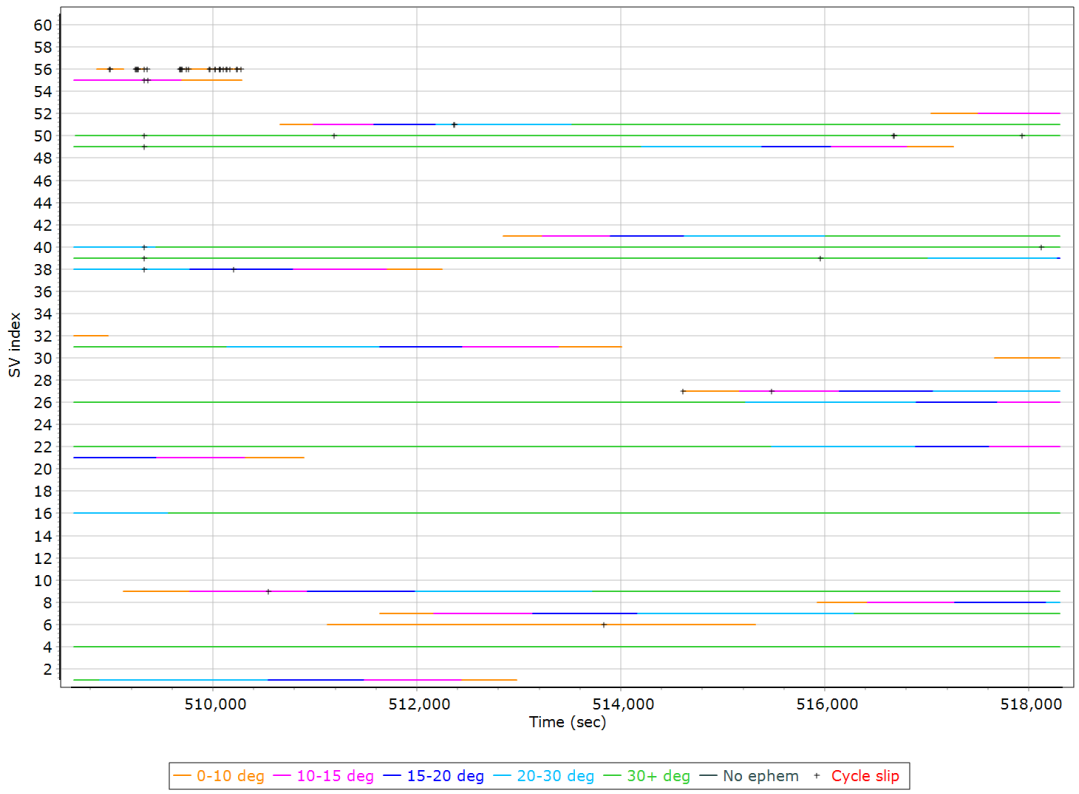
Rover Data QC

Raw IMU Import QC Summary

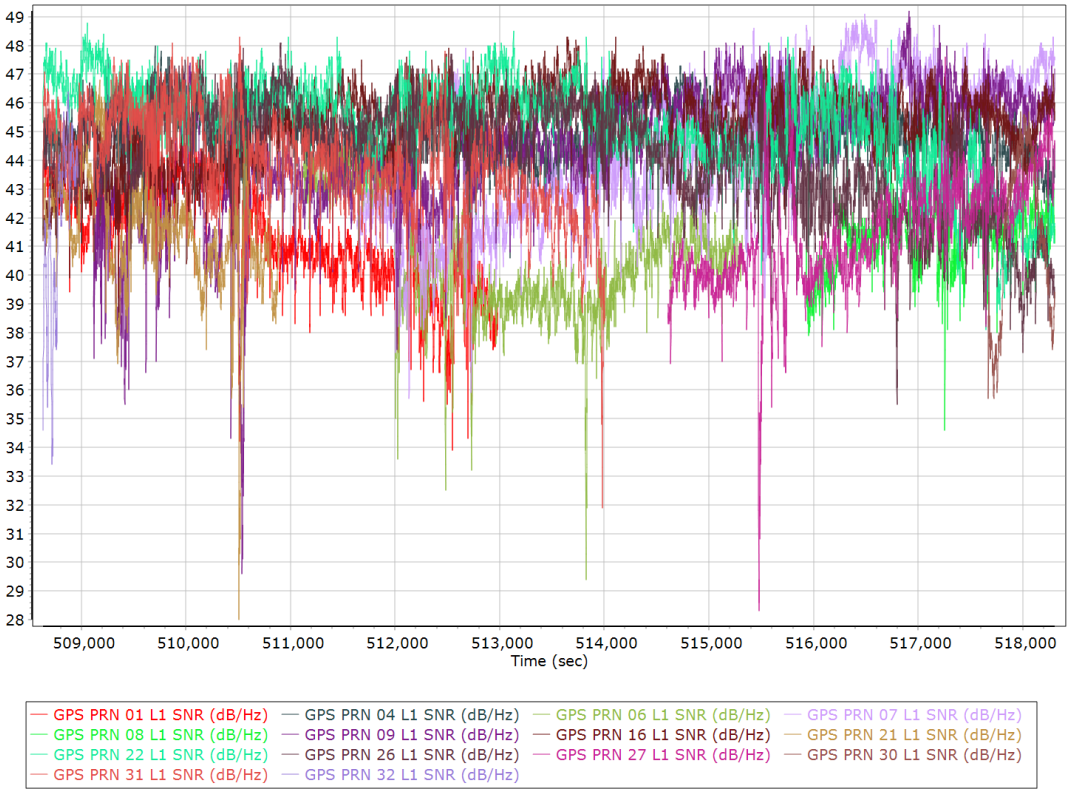
IMU data input file	imu_Mission 1.dat
IMU data check log file	imudt_211105_B_5060420_nad2011_FINAL.log
IMU Records Processed	1933697
Termination Status	Normal
IMU Anomalies	0

Primary Observables & Satellite Data

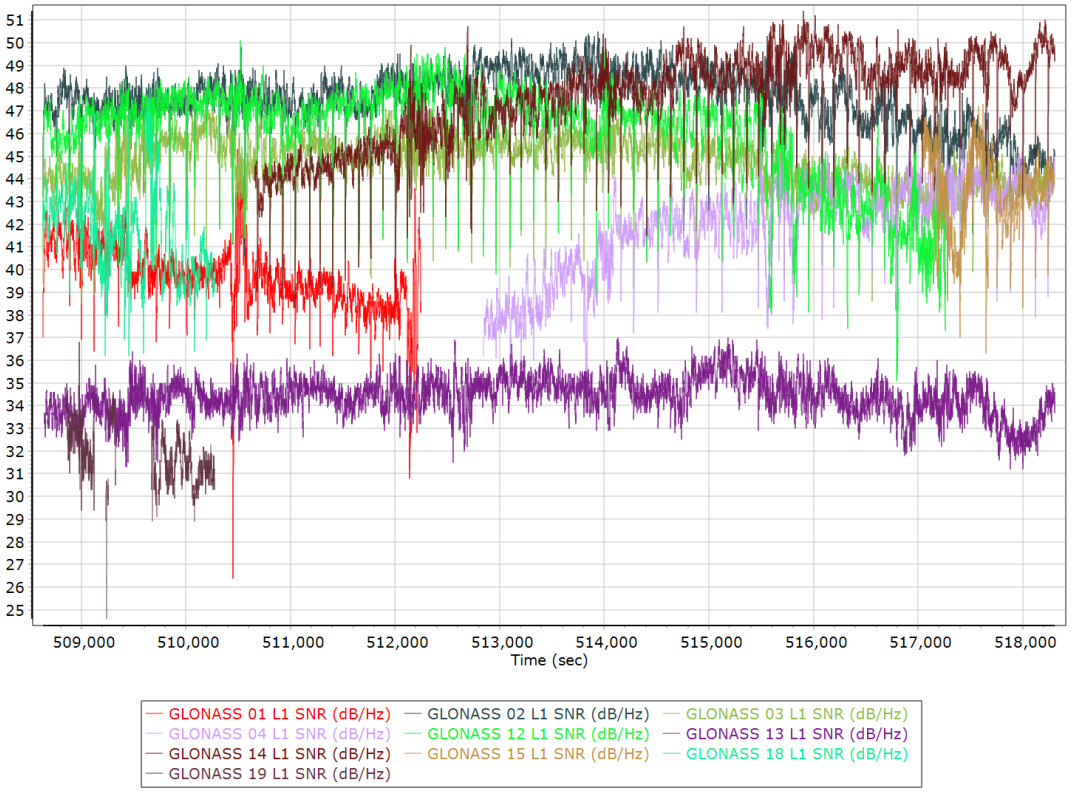
GPS/GLONASS L1 Satellite Lock/Elevation



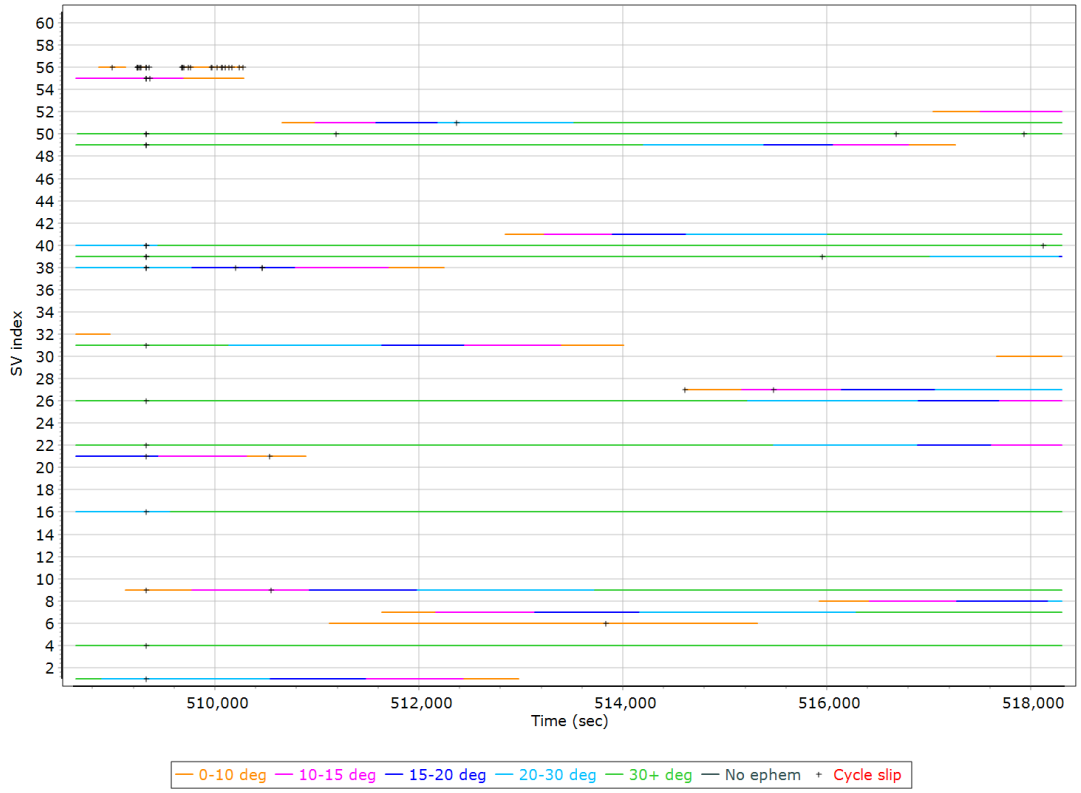
GPS L1 SNR



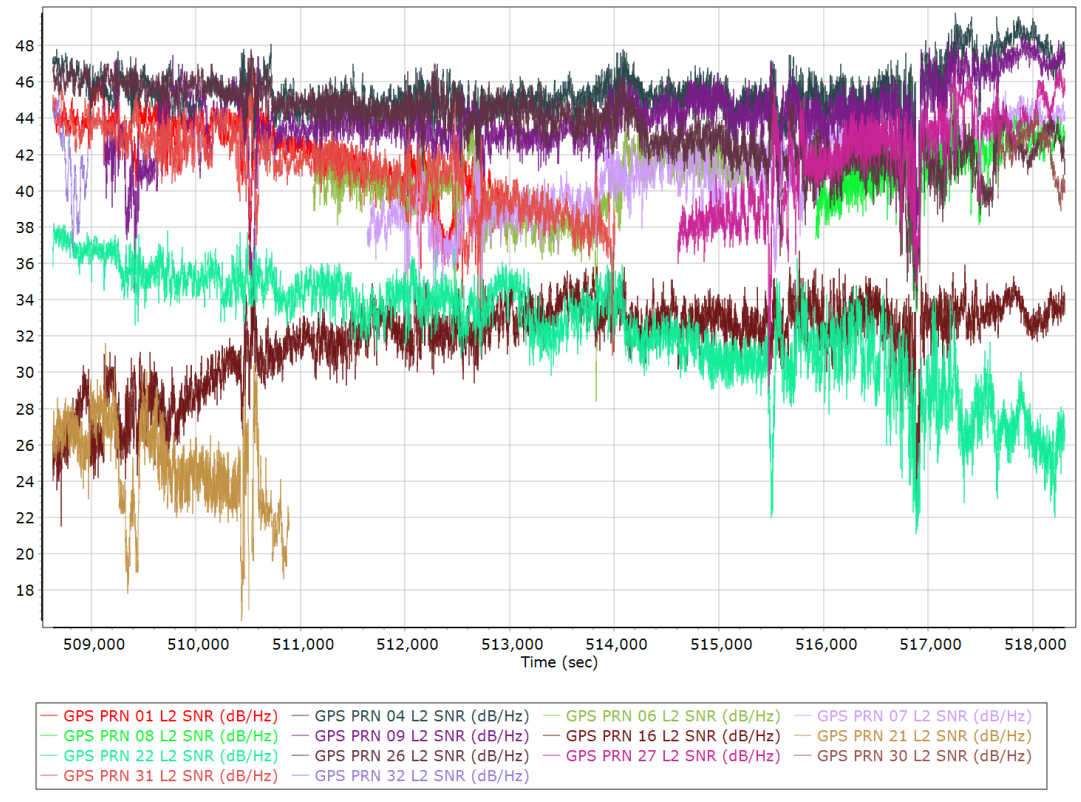
GLONASS L1 SNR



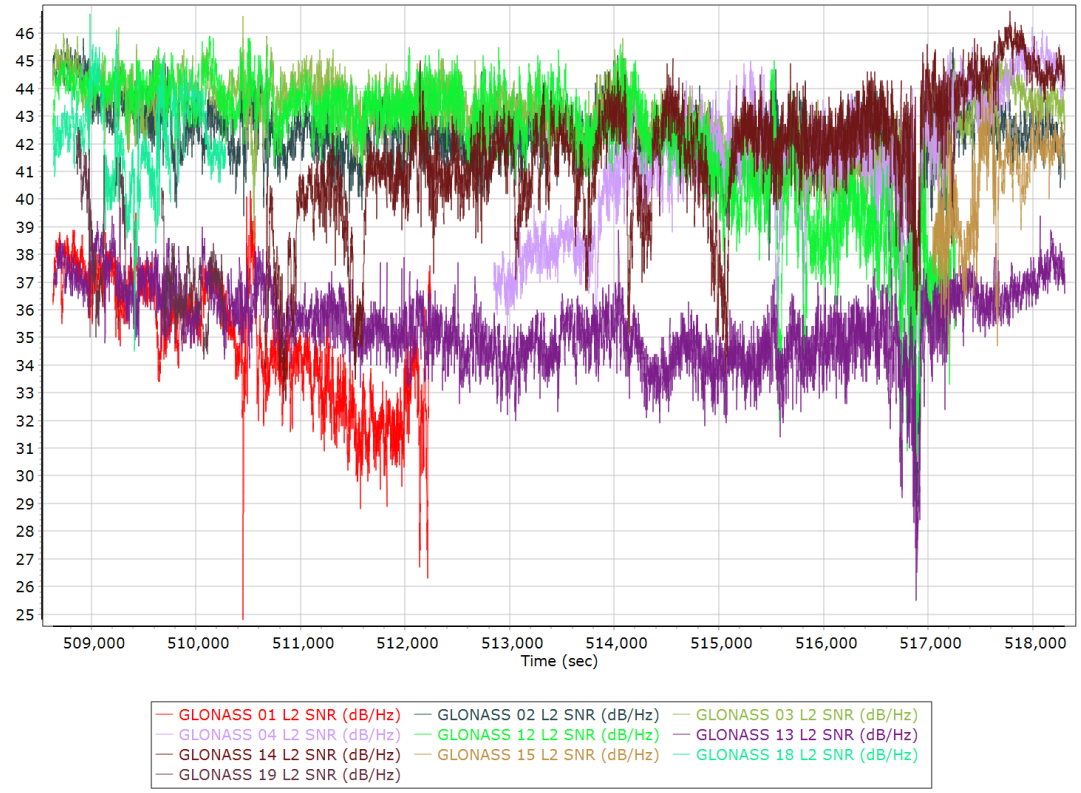
GPS/GLONASS L2 Satellite Lock/Elevation



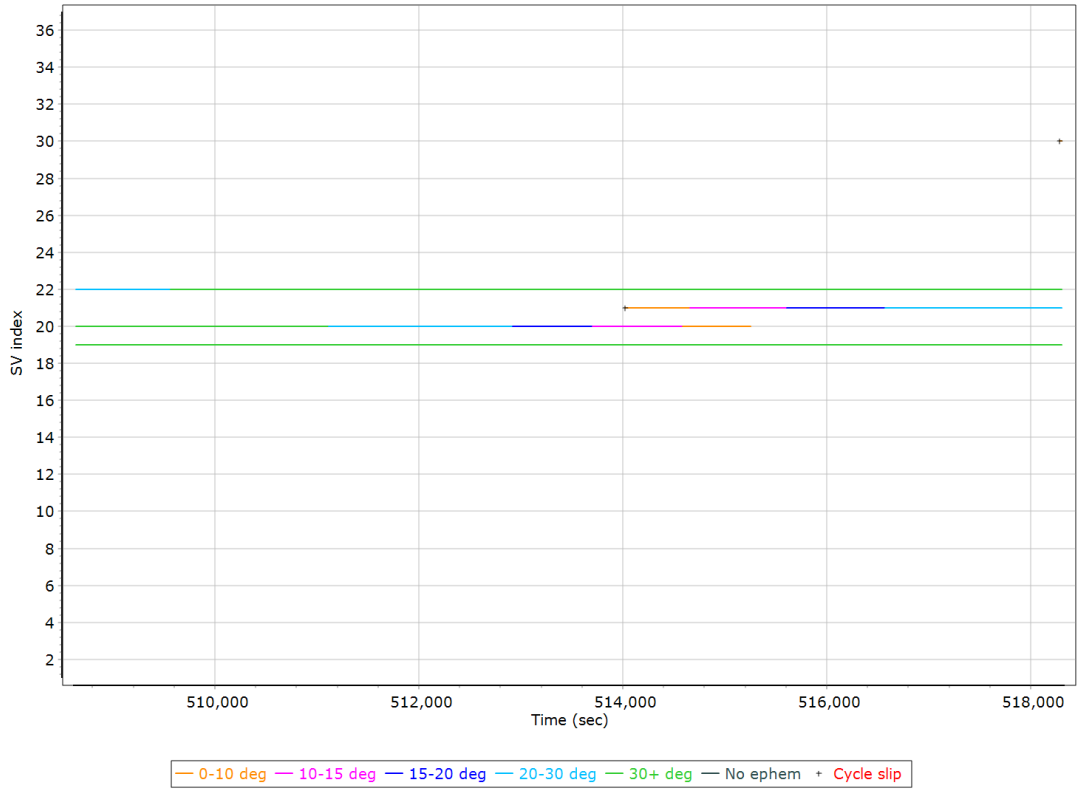
GPS L2 SNR



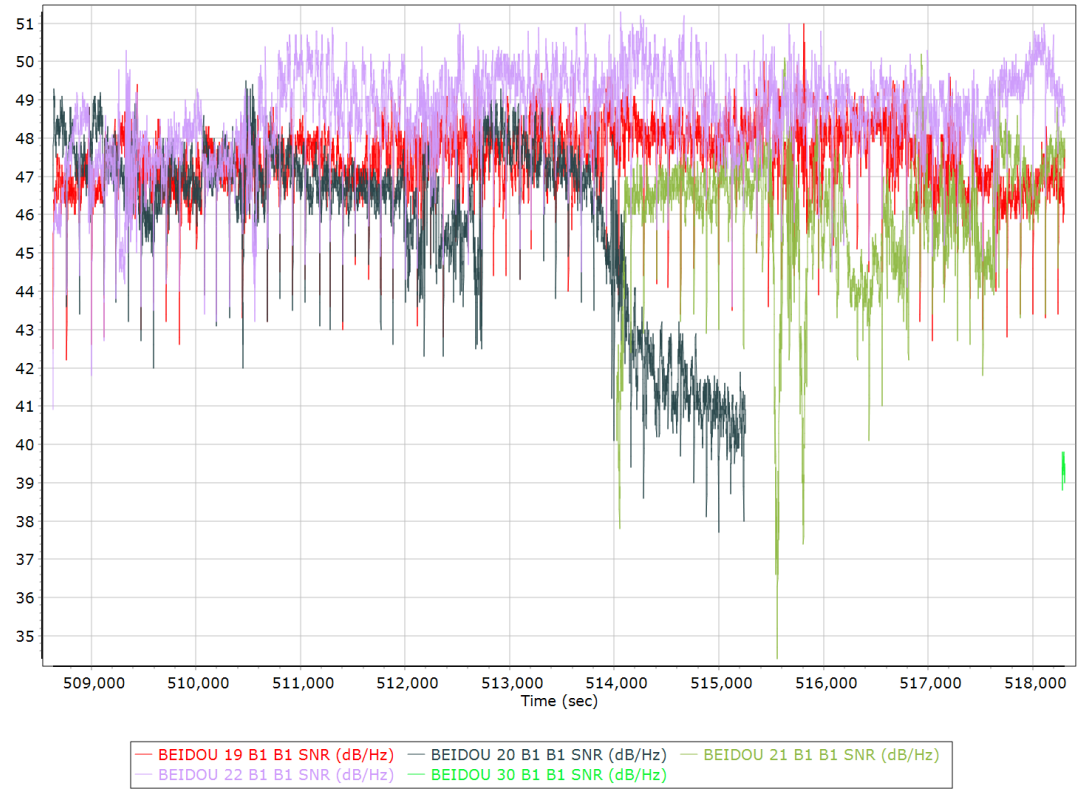
GLONASS L2 SNR



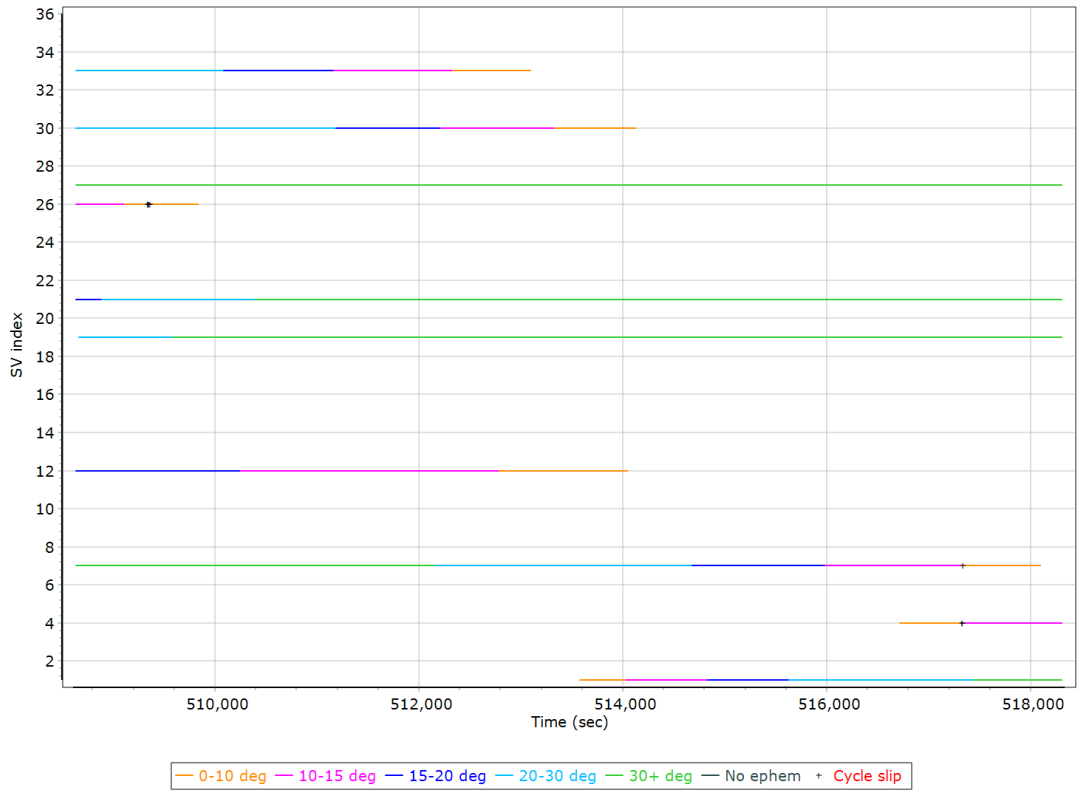
BEIDOU Satellite Lock/Elevation



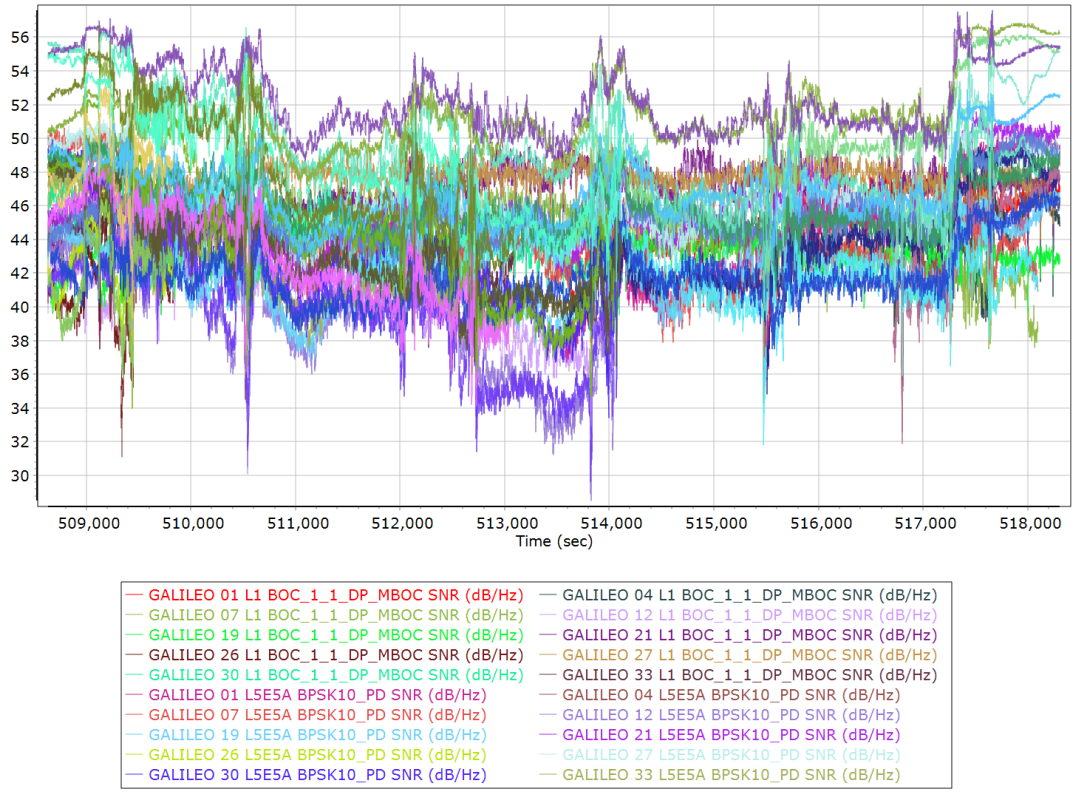
BEIDOU SNR



GALILEO Satellite Lock/Elevation



GALILEO SNR


56
54
52
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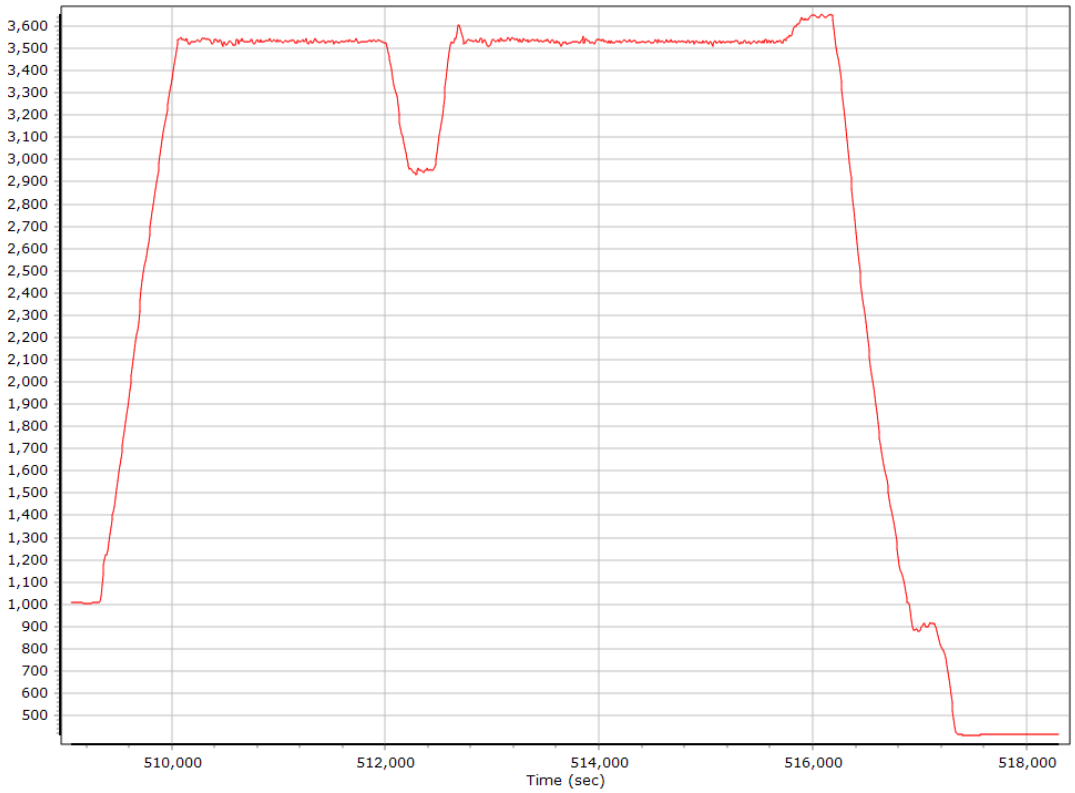
48
46
44
42
40
38
36
34
32
30
509,000
510,000
511,000
512,000
513,000
514,000
515,000
516,000
517,000
518,000
Time (sec)
GALILEO 01 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
GALILEO 04 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
GALILEO 07 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
GALILEO 12 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
GALILEO 19 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
GALILEO 21 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
GALILEO 26 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
GALILEO 27 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
GALILEO 30 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
GALILEO 33 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
GALILEO 01 L5E5A BPSK10_PD SNR (dB/Hz)
GALILEO 04 L5E5A BPSK10_PD SNR (dB/Hz)
GALILEO 07 L5E5A BPSK10_PD SNR (dB/Hz)
GALILEO 12 L5E5A BPSK10_PD SNR (dB/Hz)
GALILEO 19 L5E5A BPSK10_PD SNR (dB/Hz)
GALILEO 21 L5E5A BPSK10_PD SNR (dB/Hz)
GALILEO 26 L5E5A BPSK10_PD SNR (dB/Hz)
GALILEO 27 L5E5A BPSK10_PD SNR (dB/Hz)
GALILEO 30 L5E5A BPSK10_PD SNR (dB/Hz)
GALILEO 33 L5E5A BPSK10_PD SNR (dB/Hz)

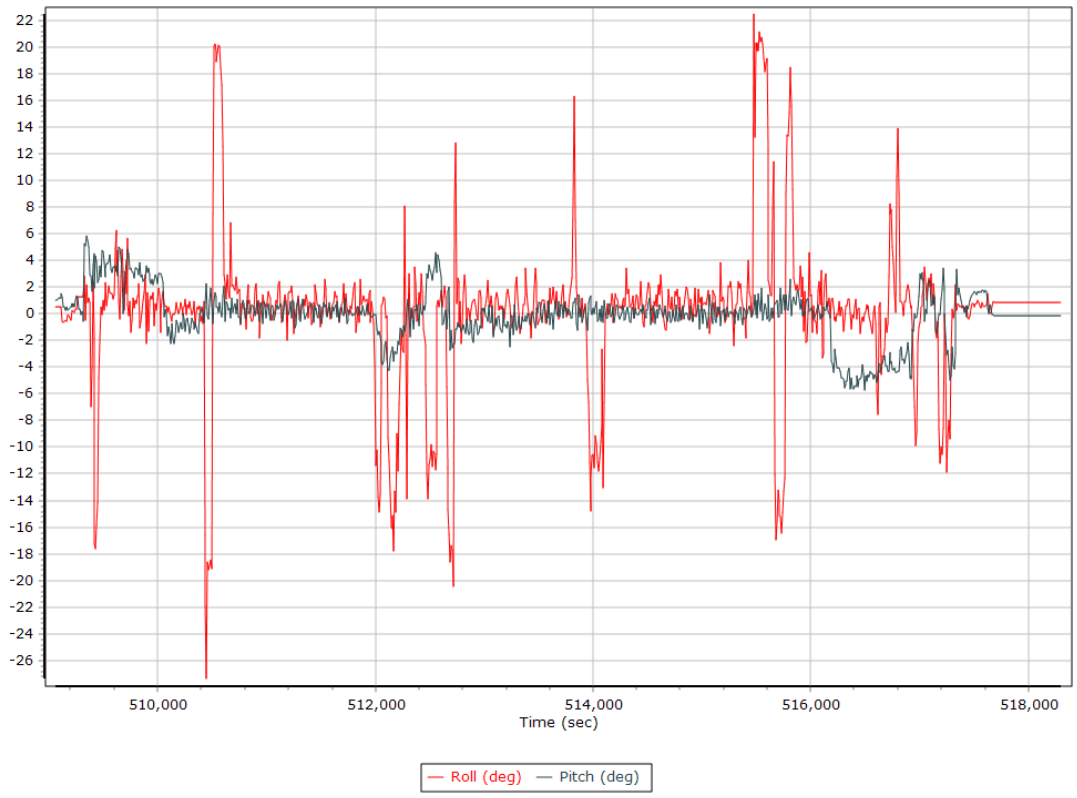
Smoothed Trajectory Information

Top View

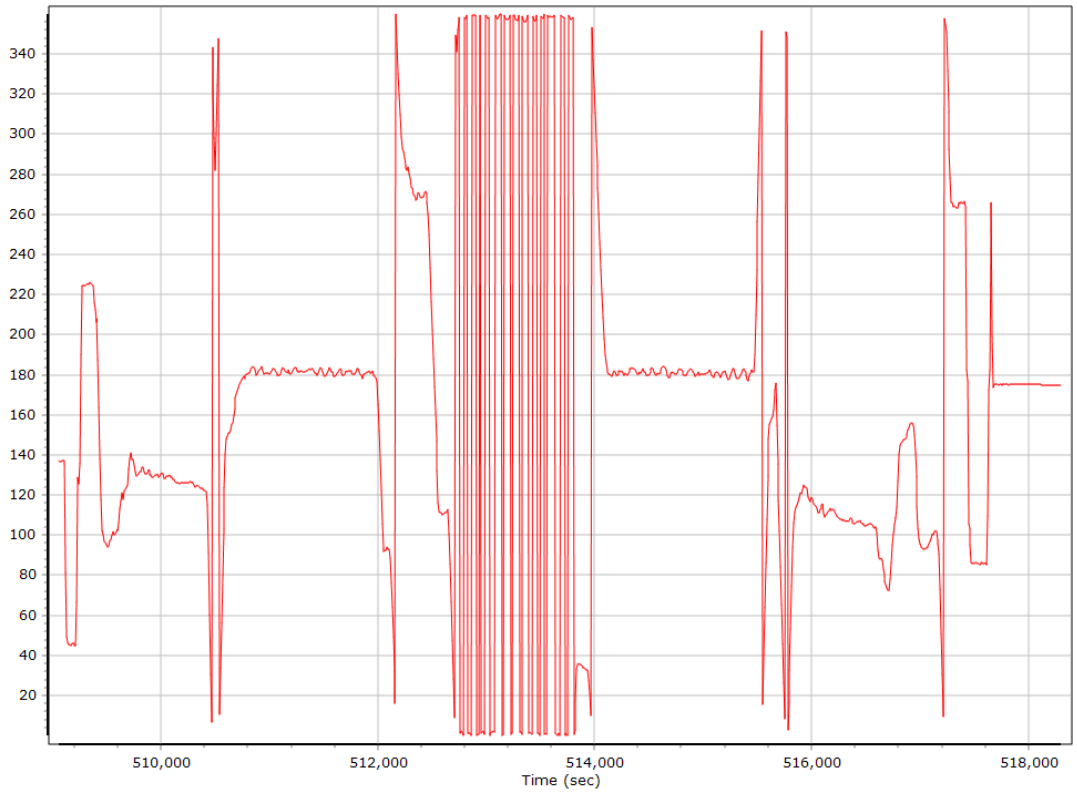
Altitude



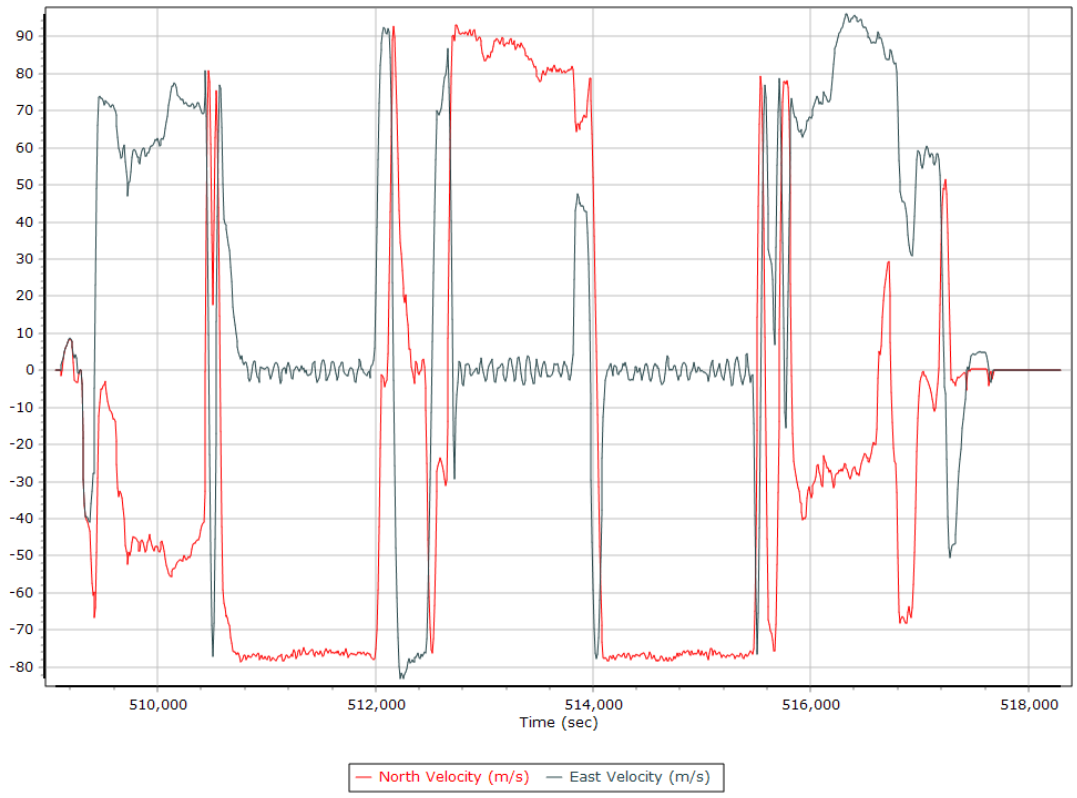
Roll/Pitch



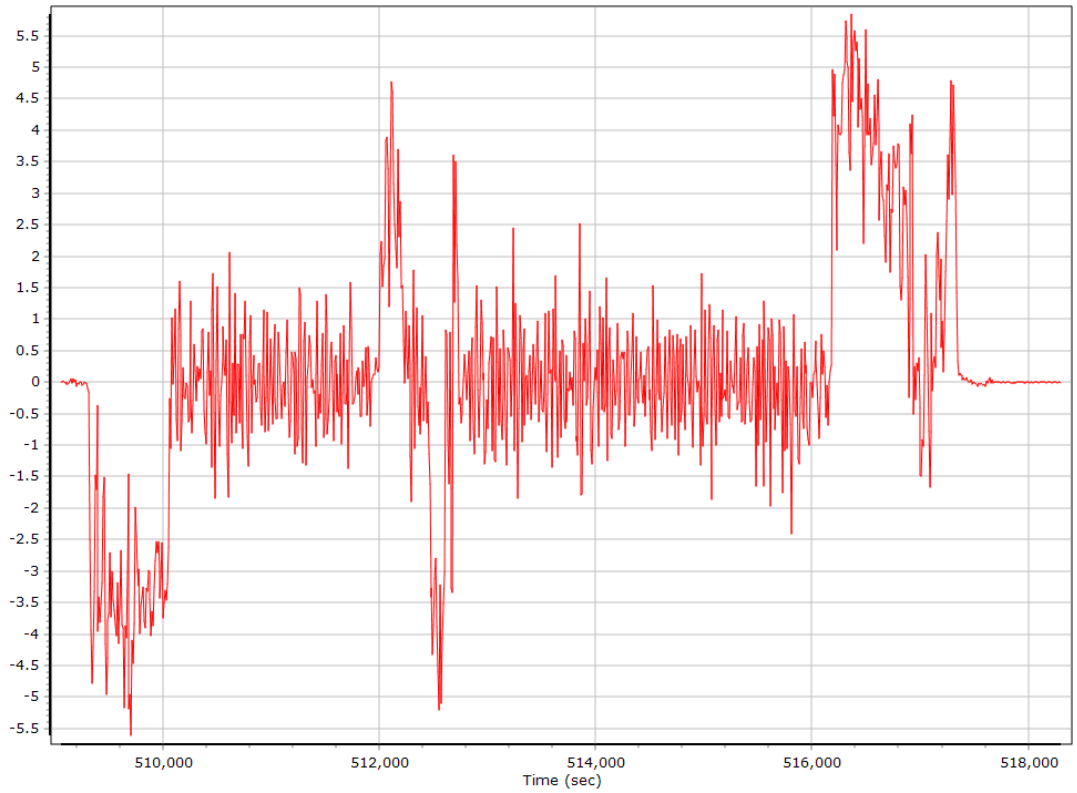
Heading



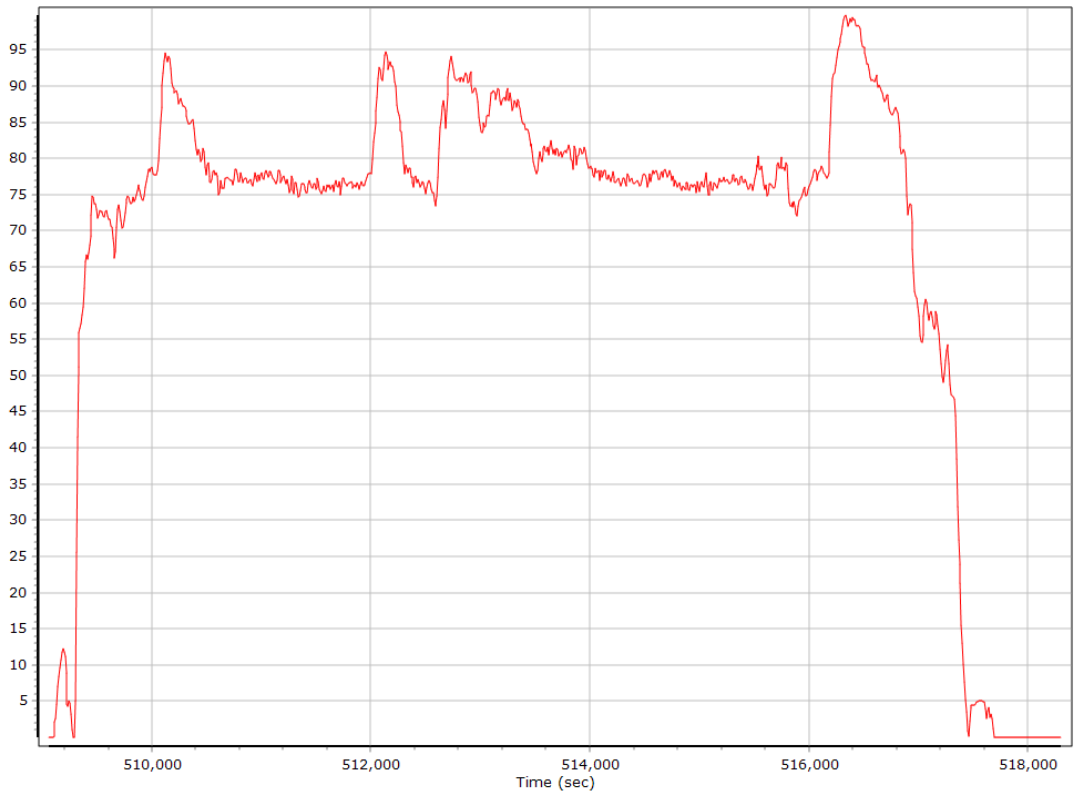
North/East Velocity



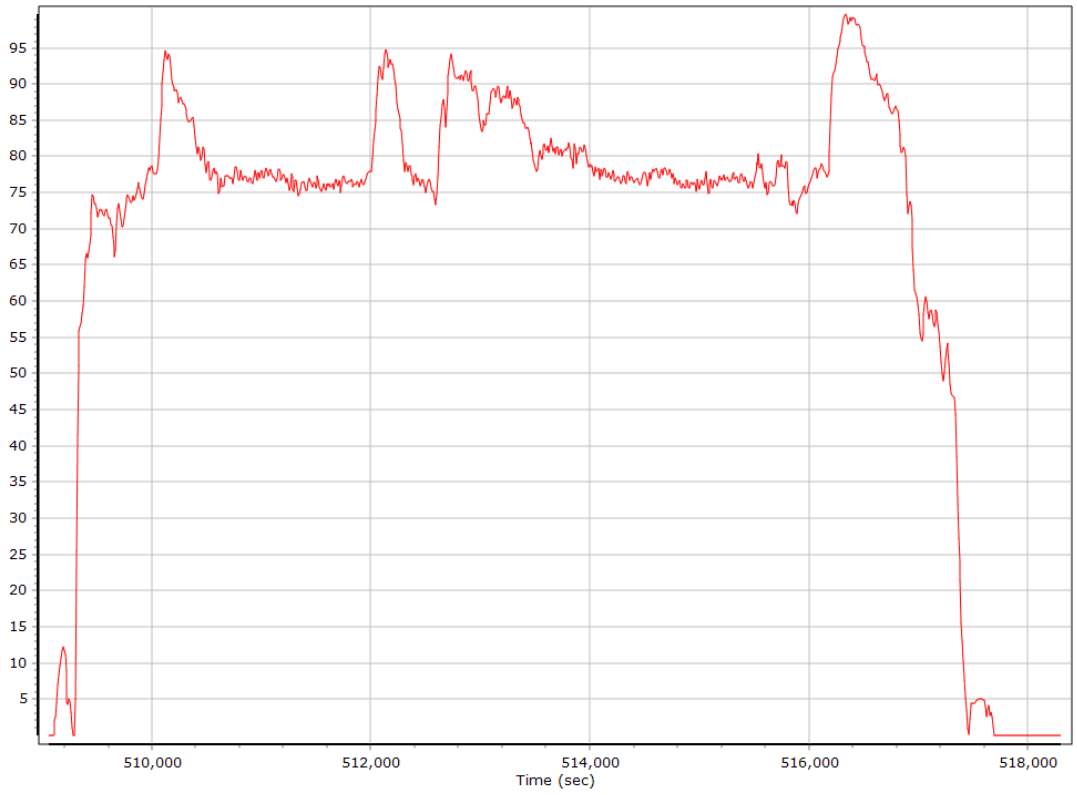
Down Velocity



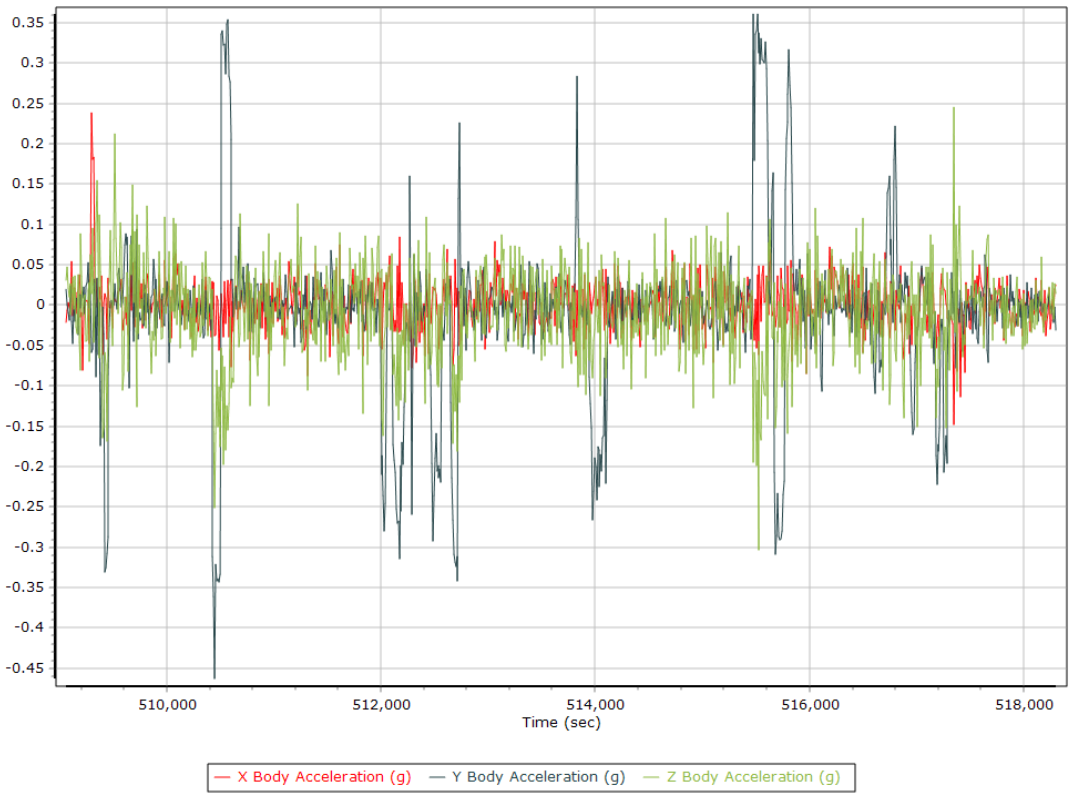
Total Speed



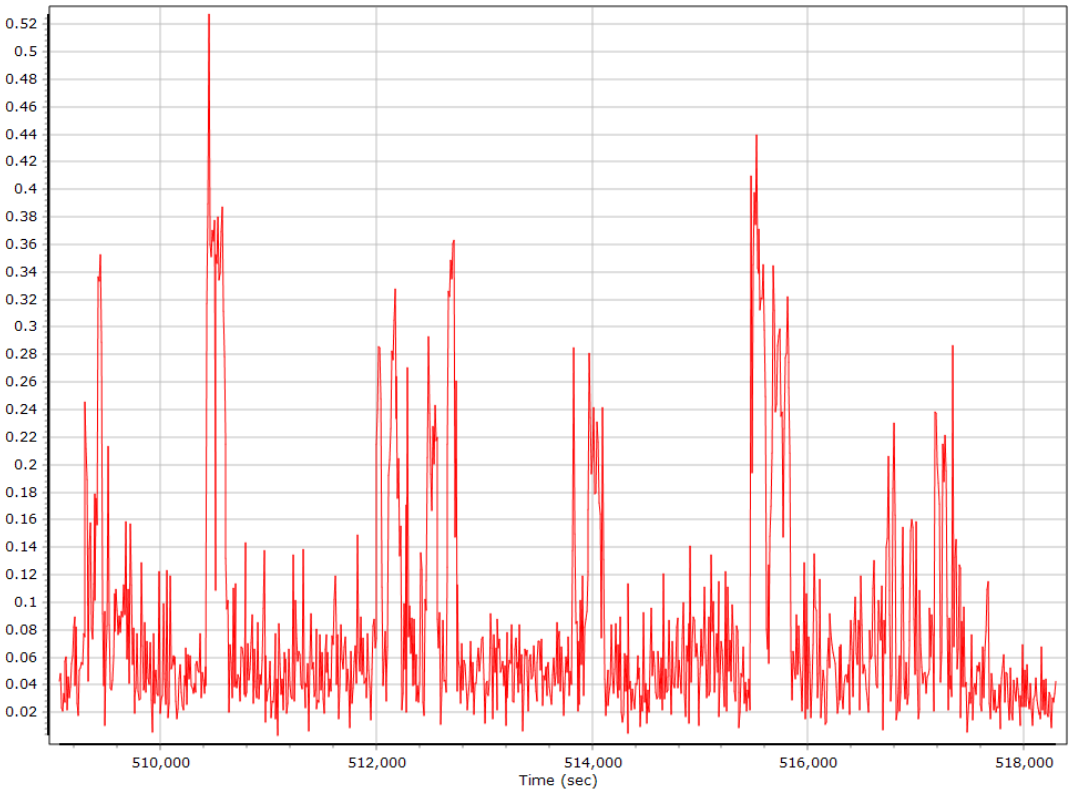
Ground Speed



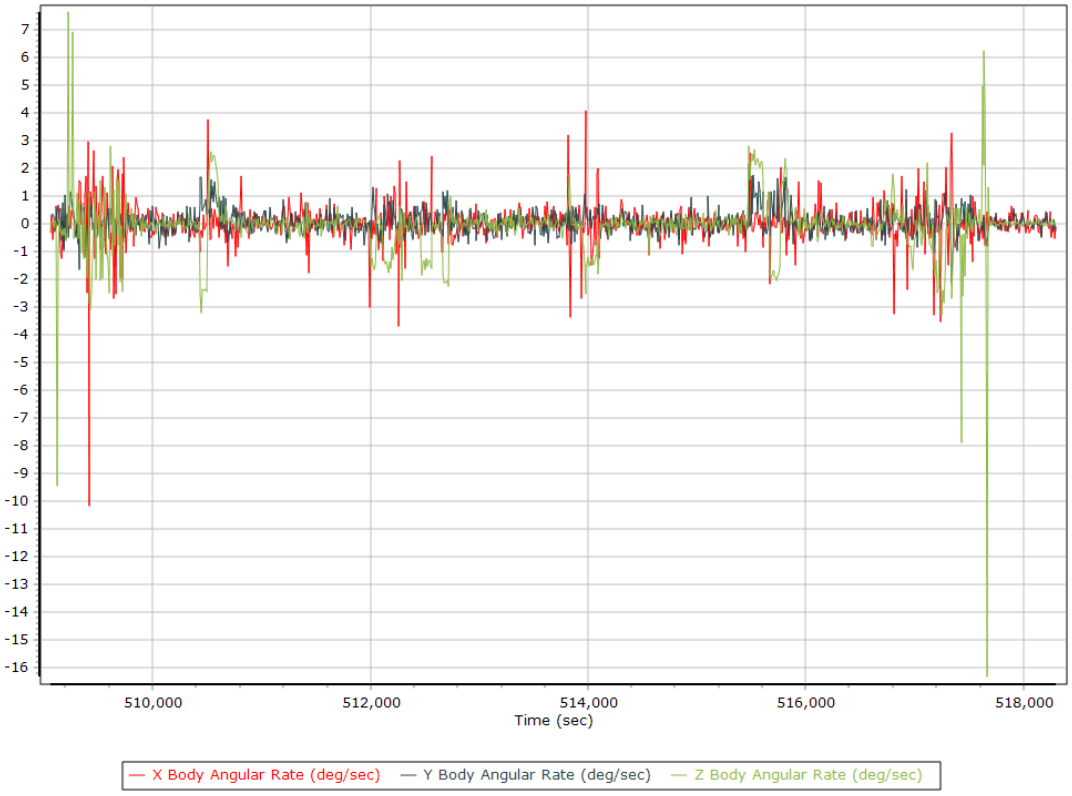
Body Acceleration



Total Body Acceleration



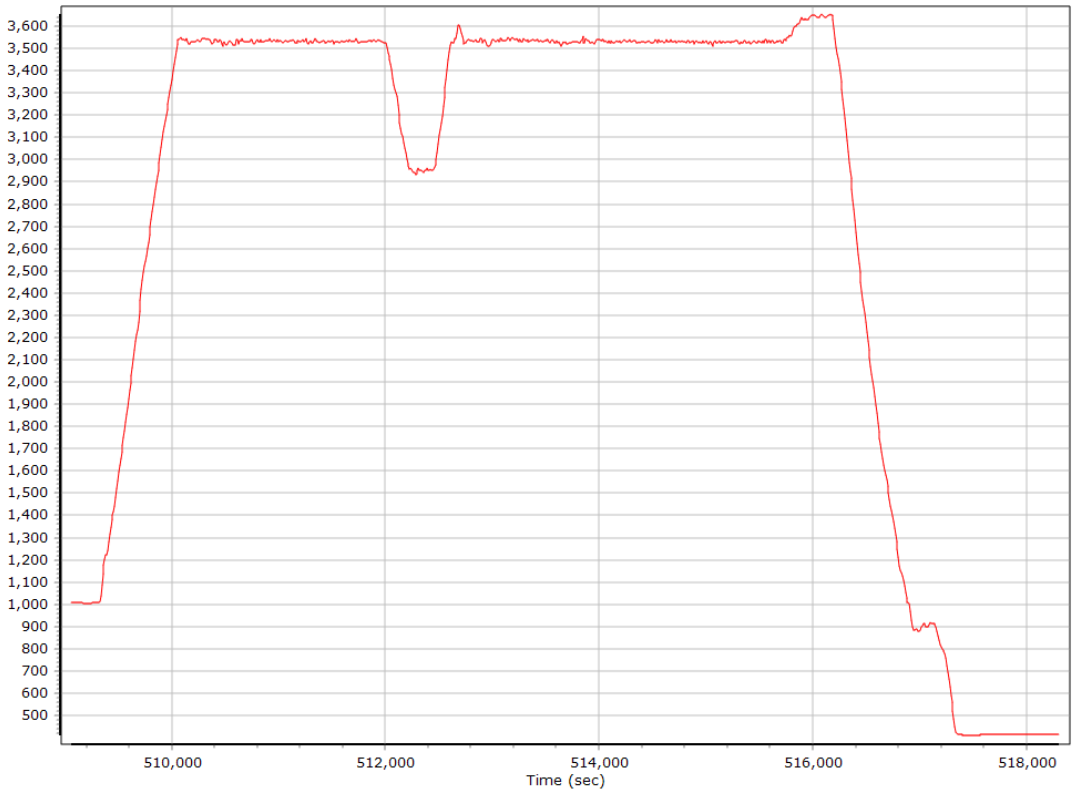
Body Angular Rate



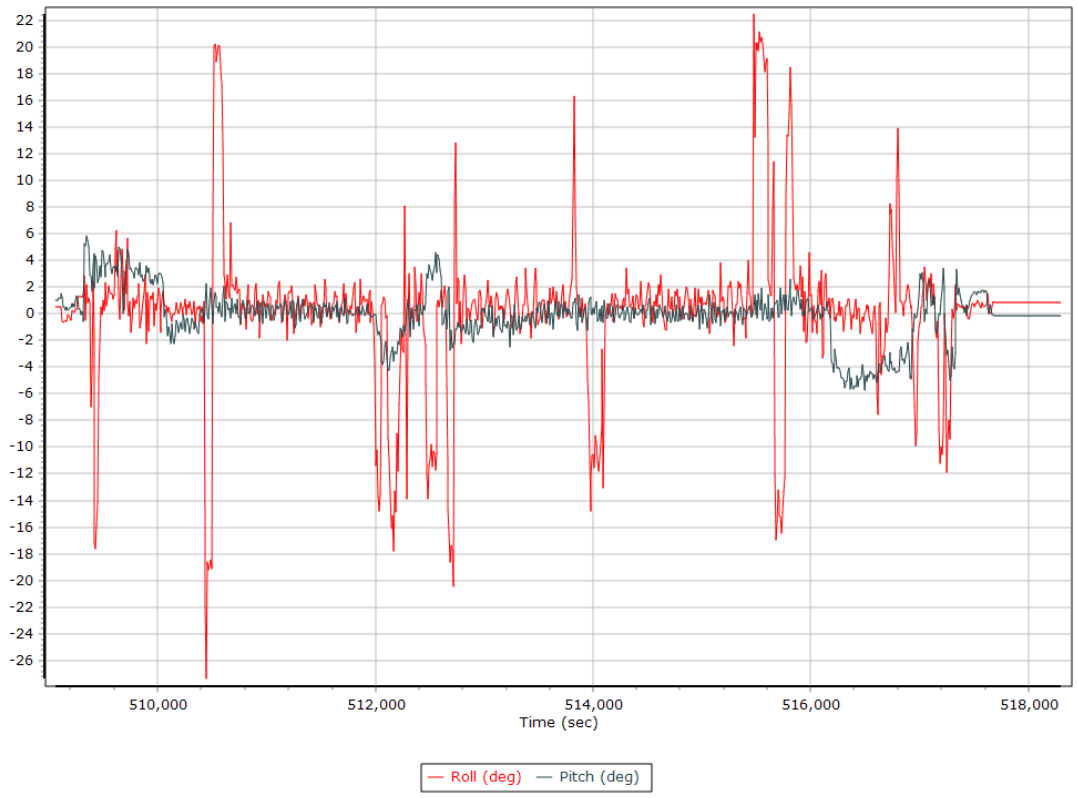
Forward Processed Trajectory Information

Top View

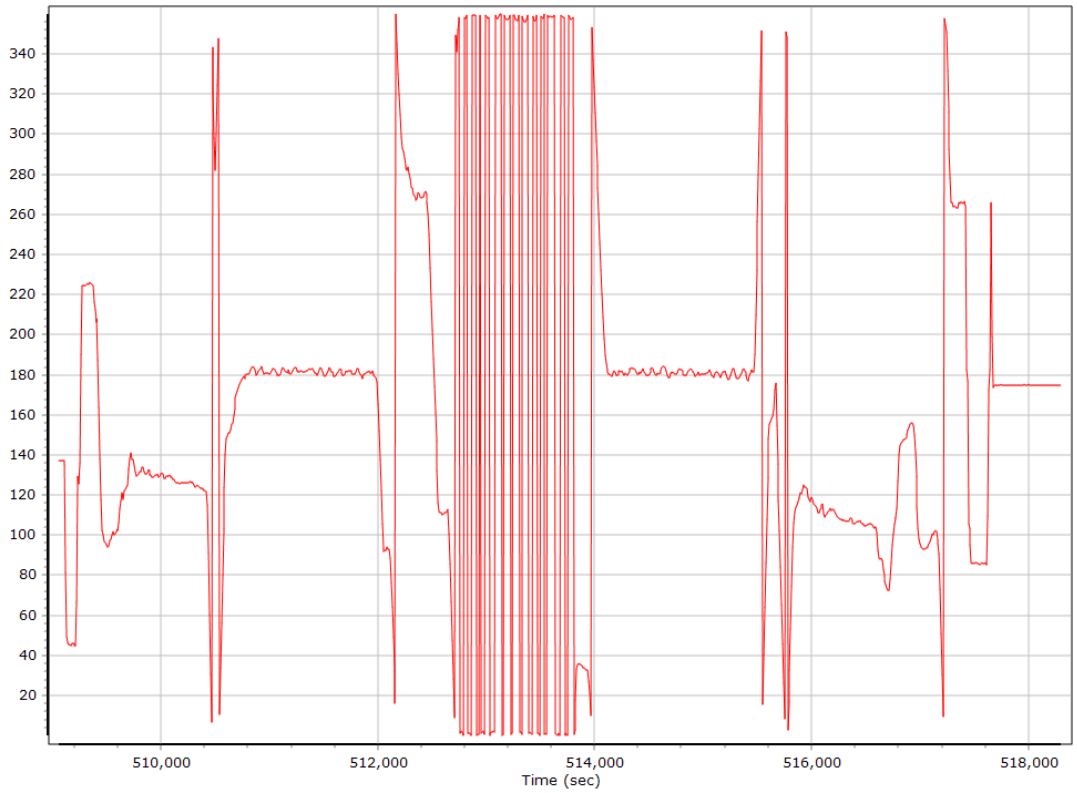
Altitude



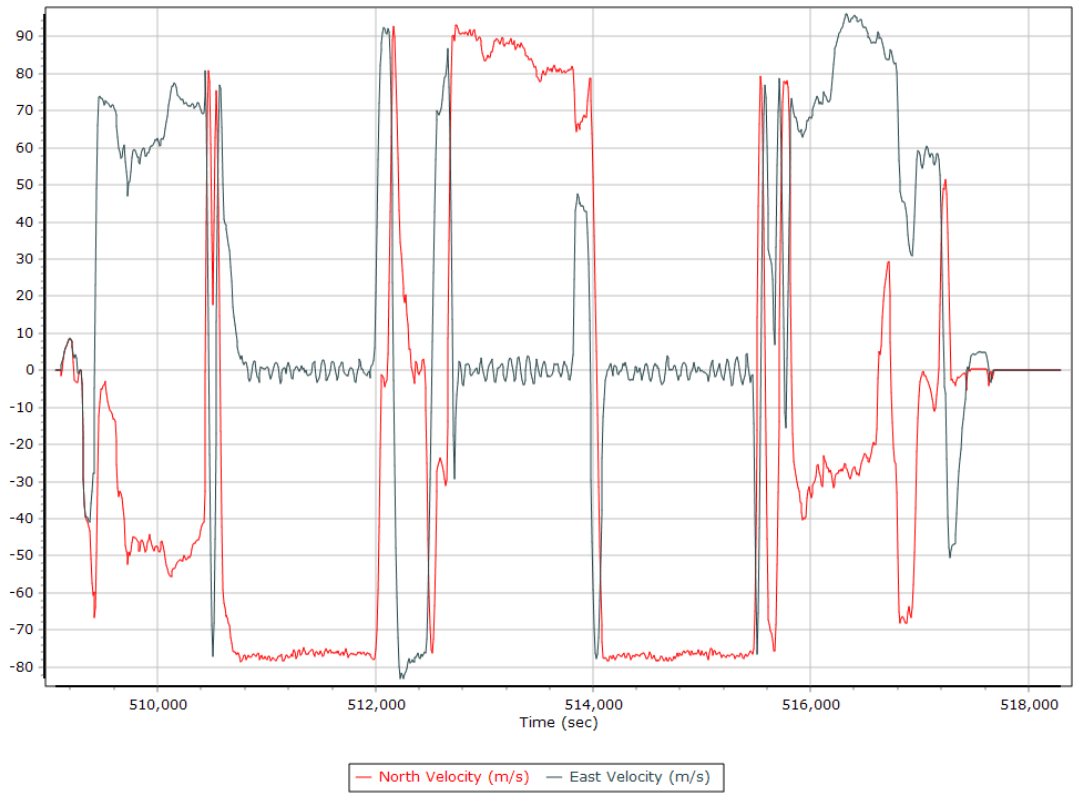
Roll/Pitch



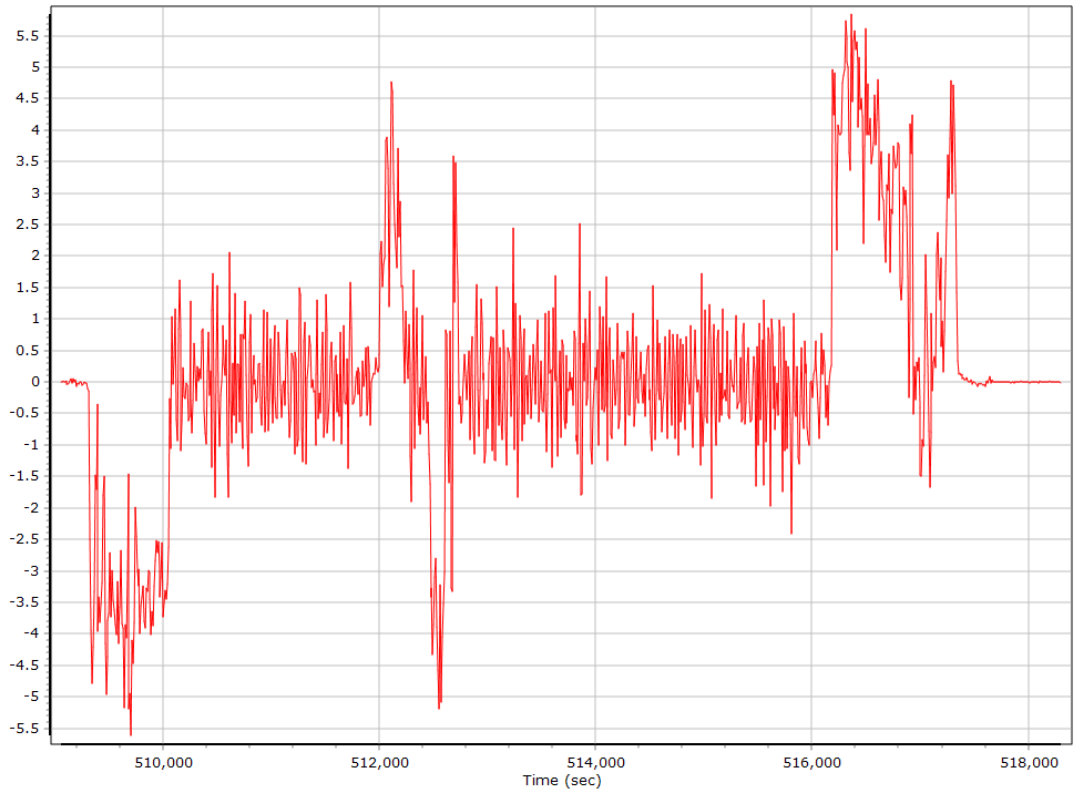
Heading



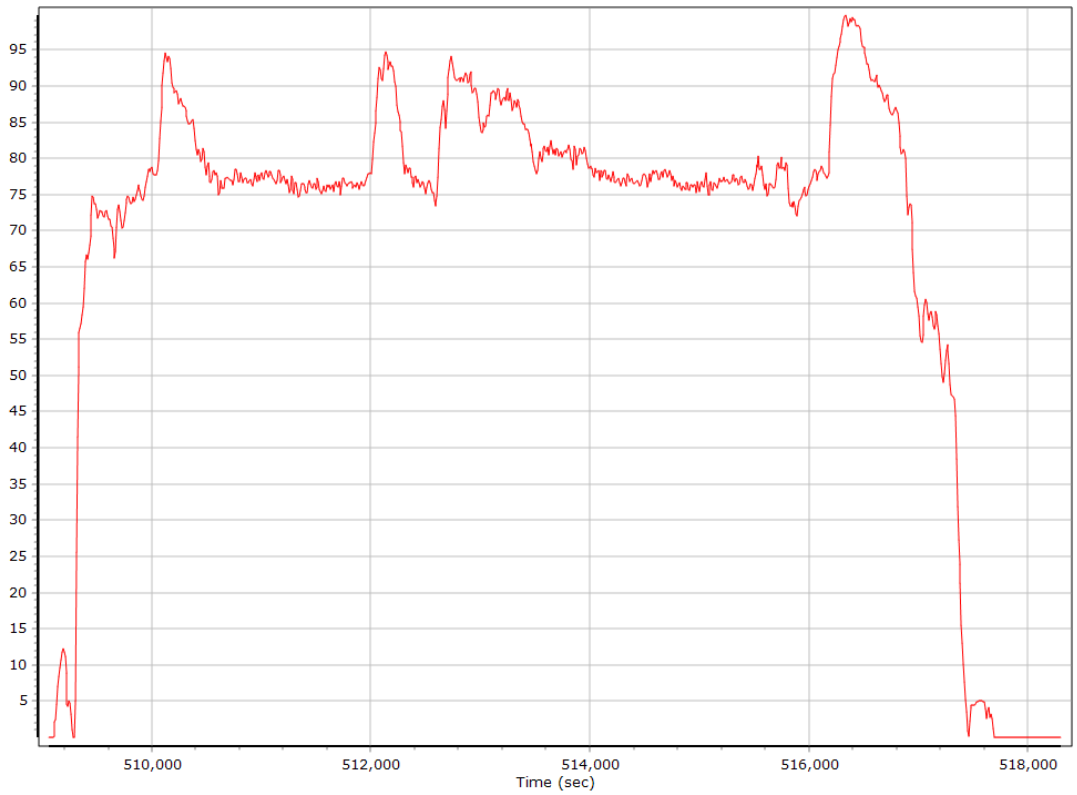
North/East Velocity



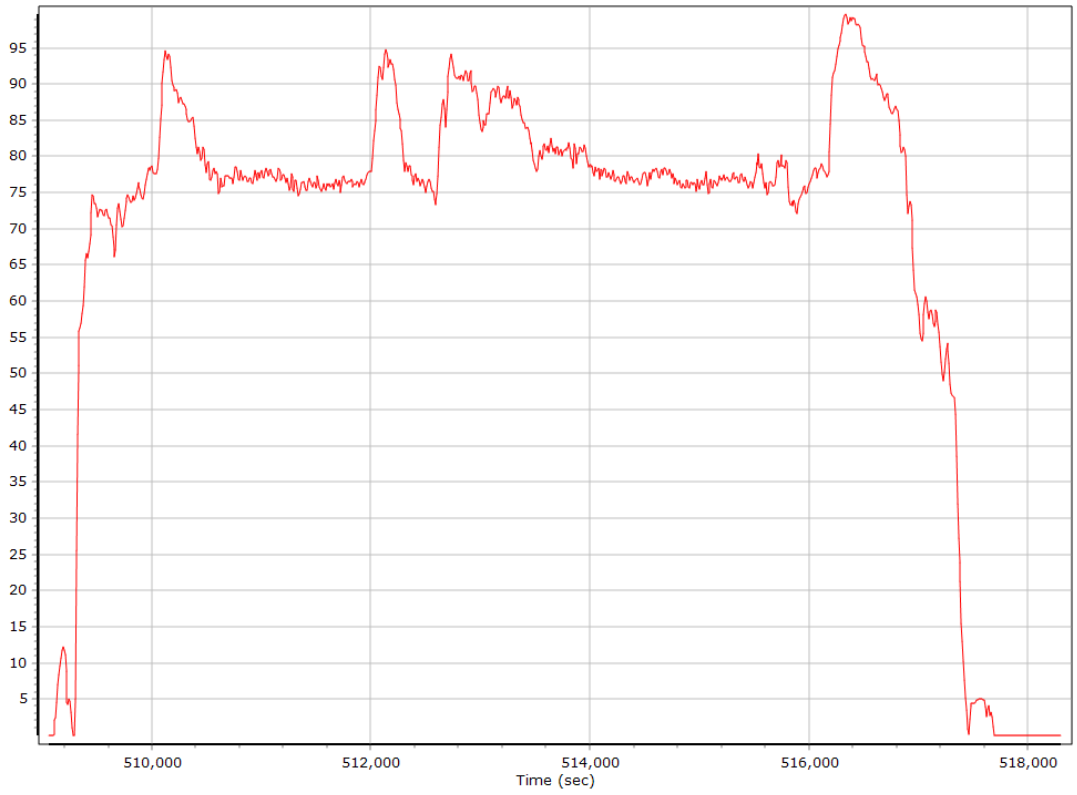
Down Velocity



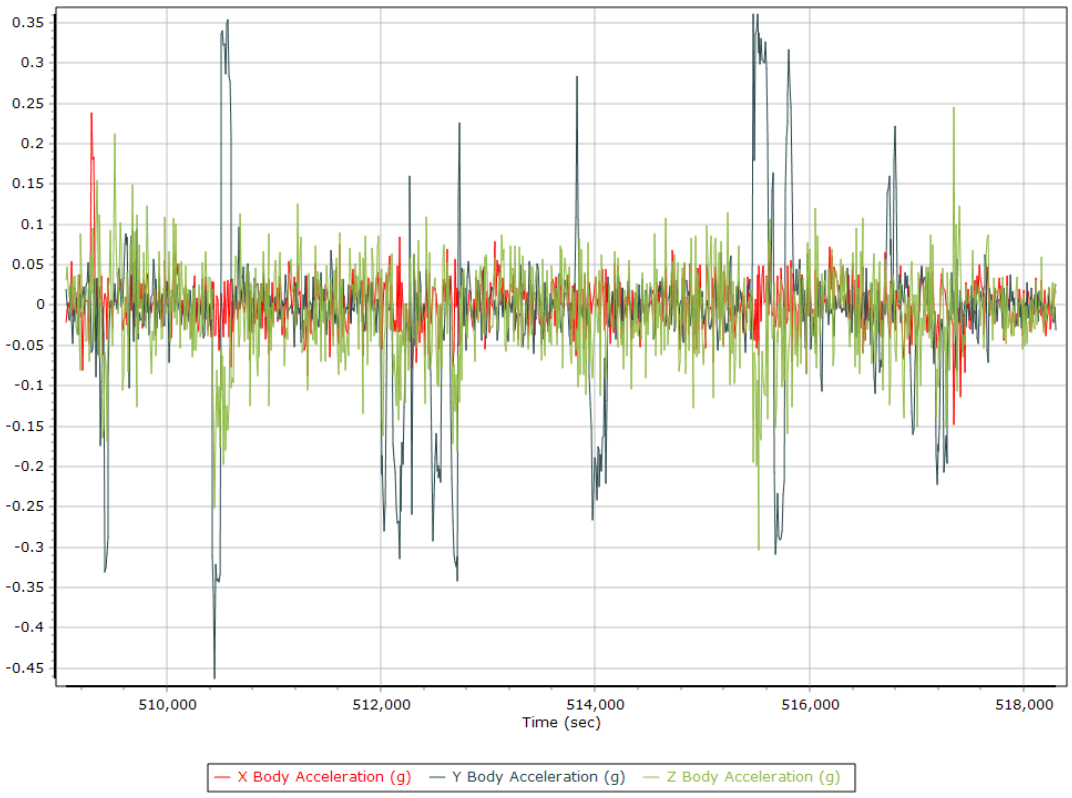
Total Speed



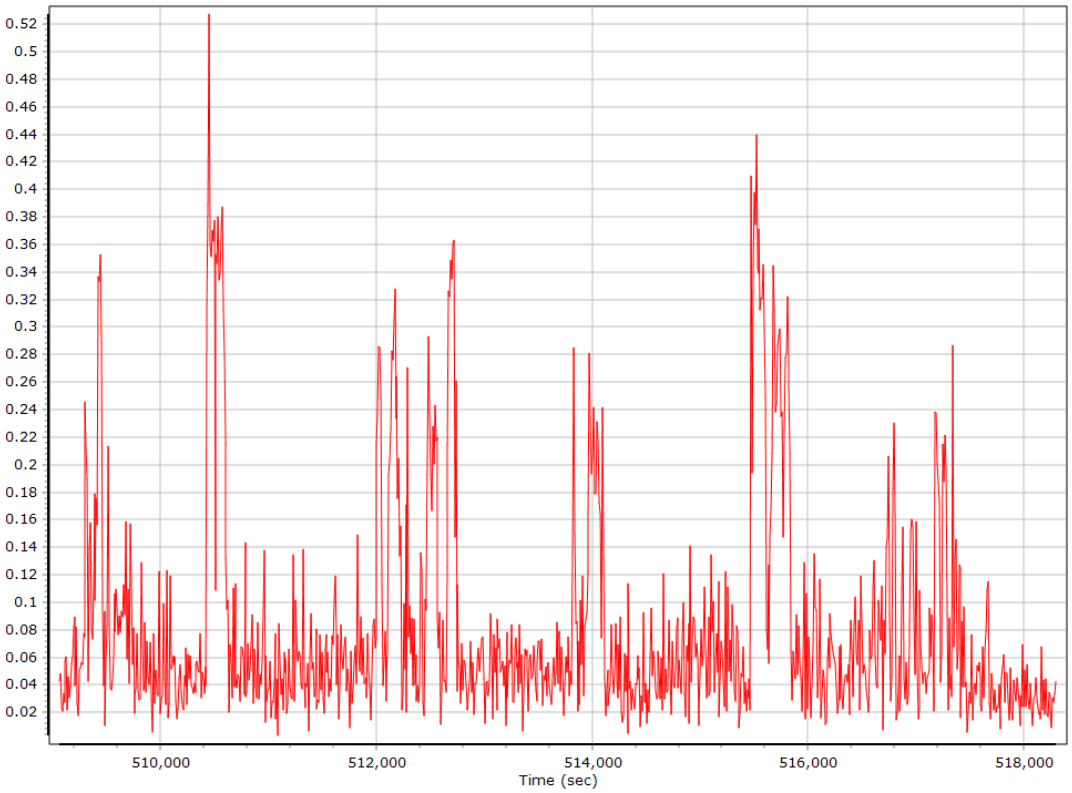
Ground Speed



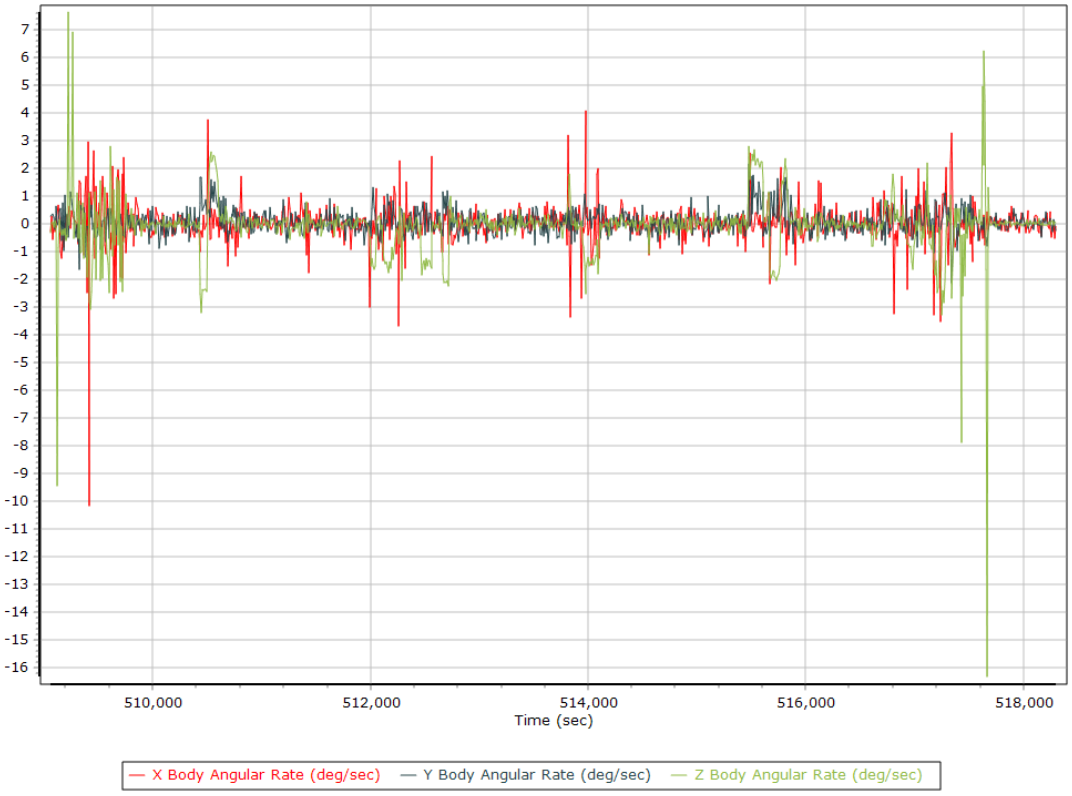
Body Acceleration



Total Body Acceleration



Body Angular Rate

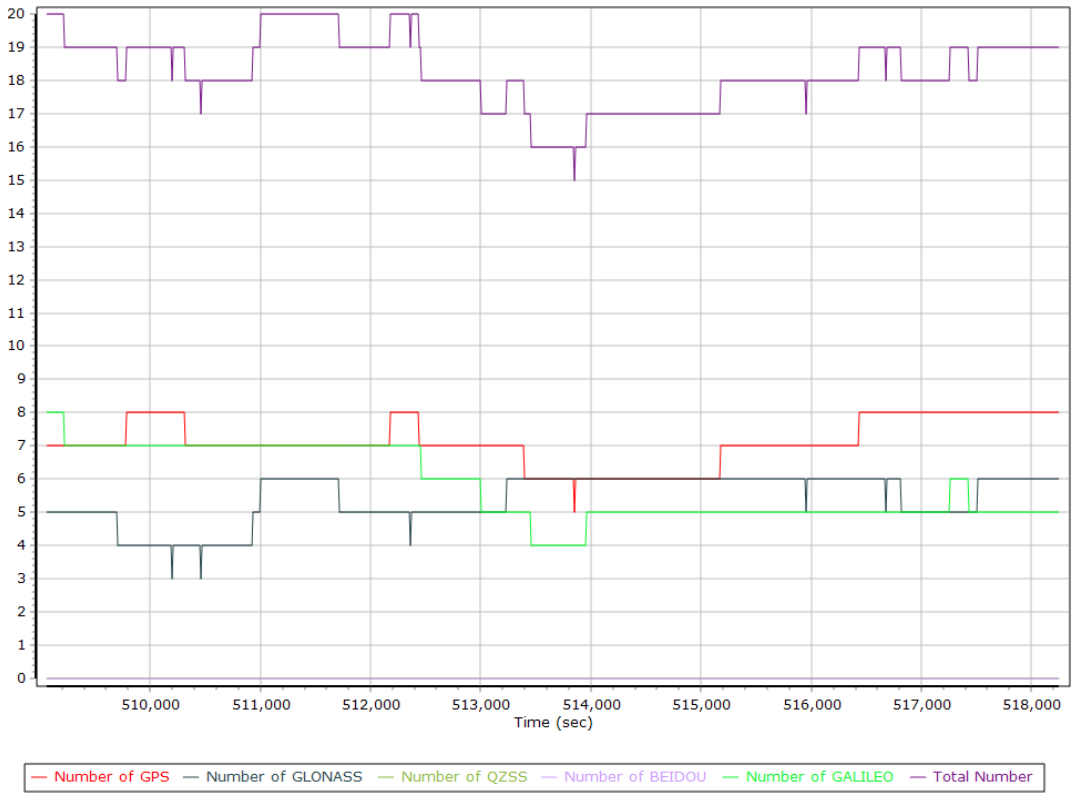


GNSS QC

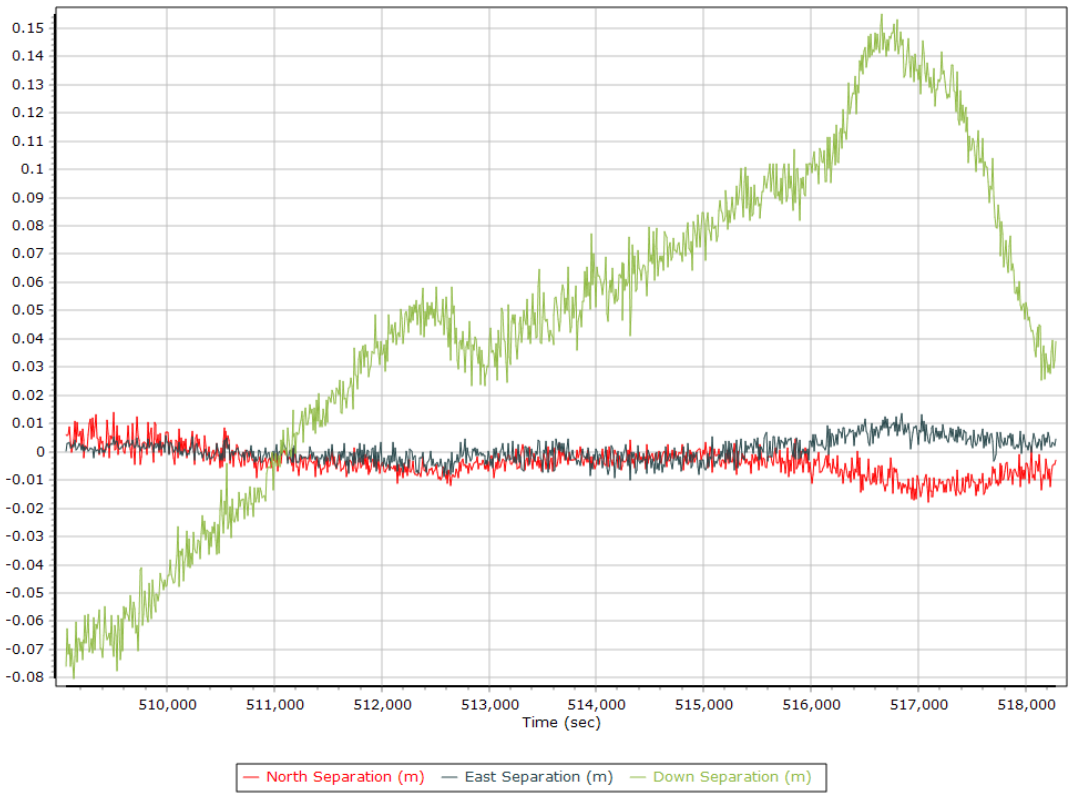
GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	4	8	7
Number of GLONASS SV	0	6	5
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	0	0
Number of GALILEO SV	3	8	6
Total number of SV	11	20	18
PDOP	1.09	3.46	1.26
QC Solution Gaps	1.00	1.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	9609.00	0.00	8.00
Percentage	99.92	0.00	0.08

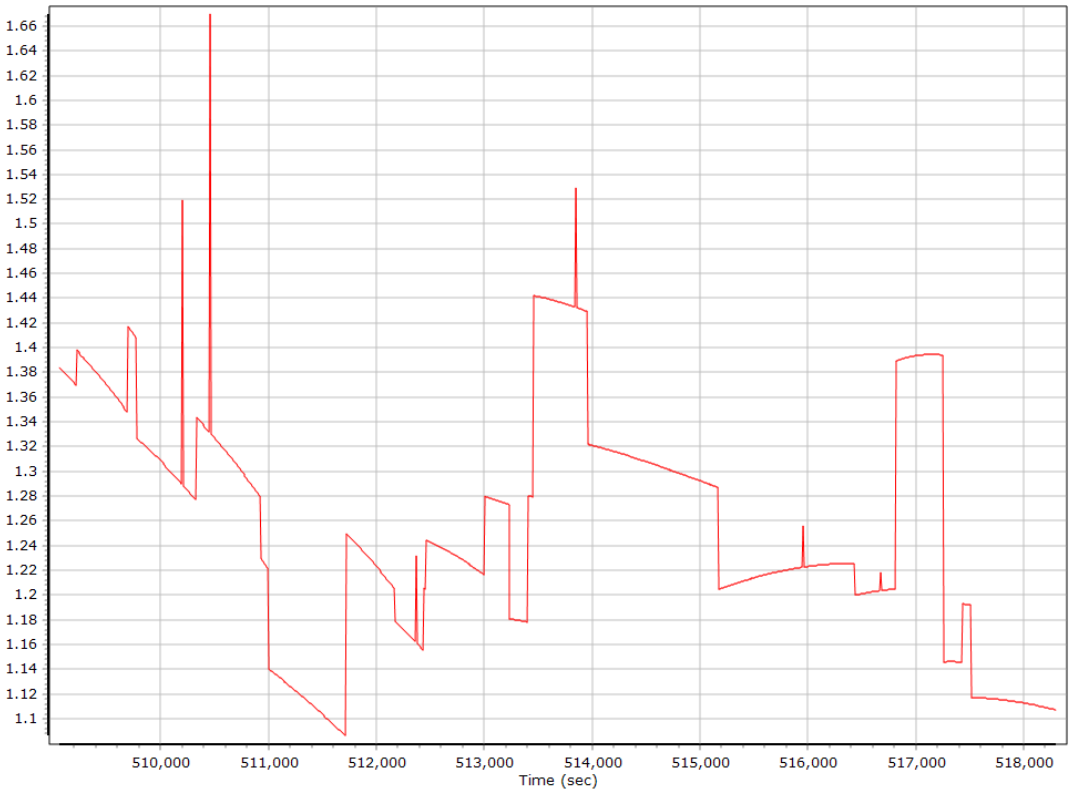
Num SVs in solution



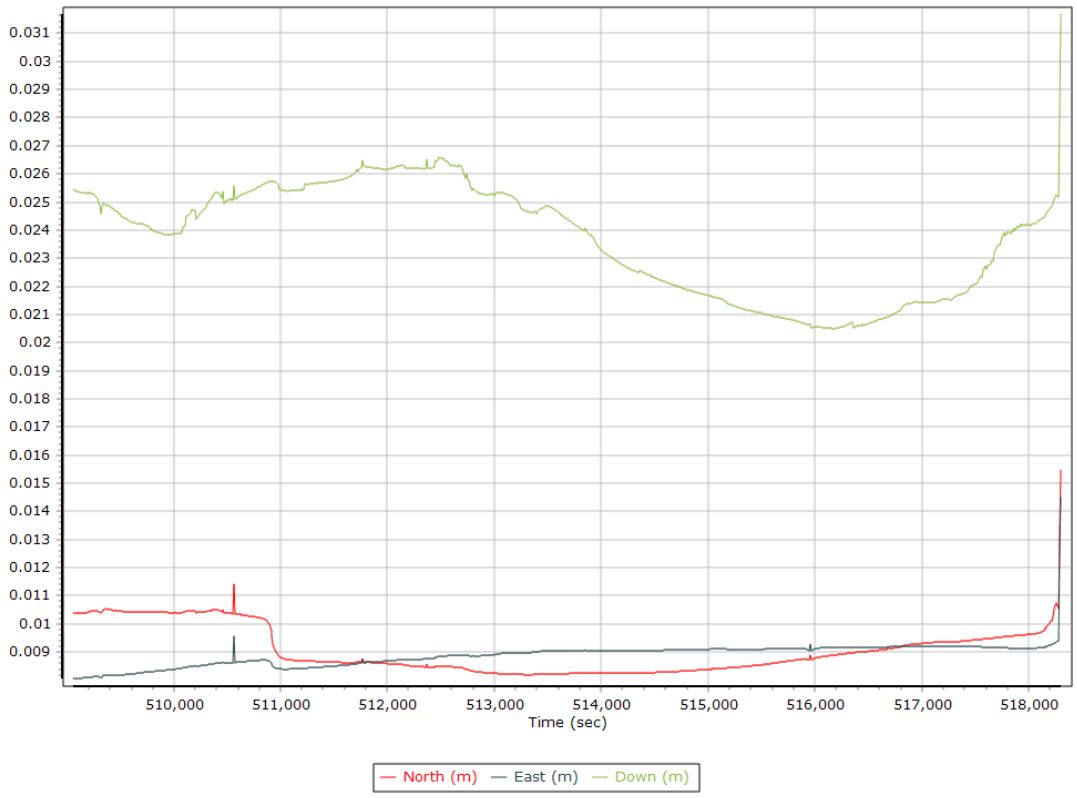
Forward/Reverse Separation



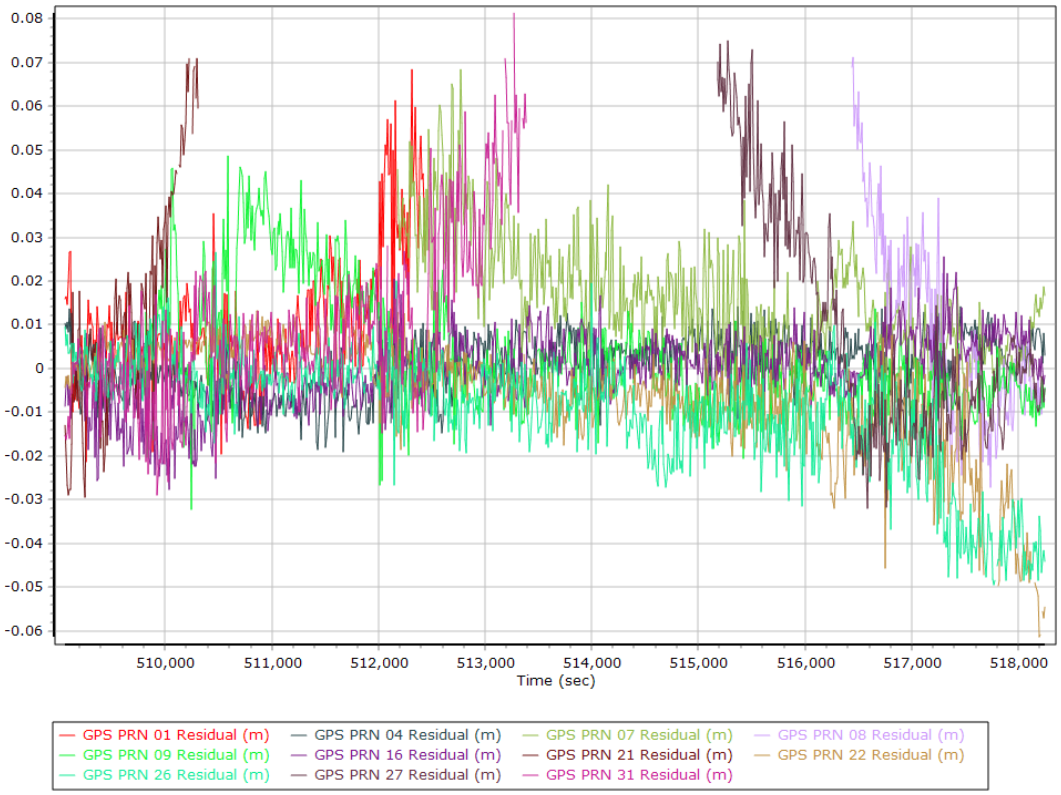
PDOP



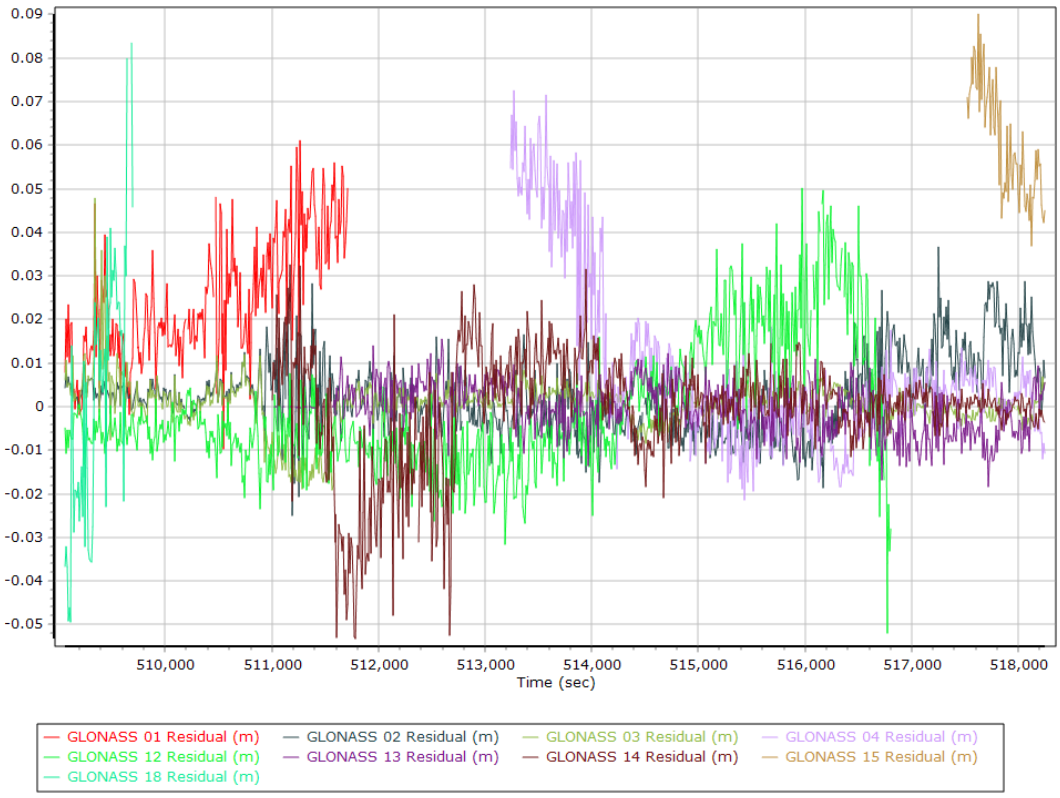
Estimated Position Accuracy



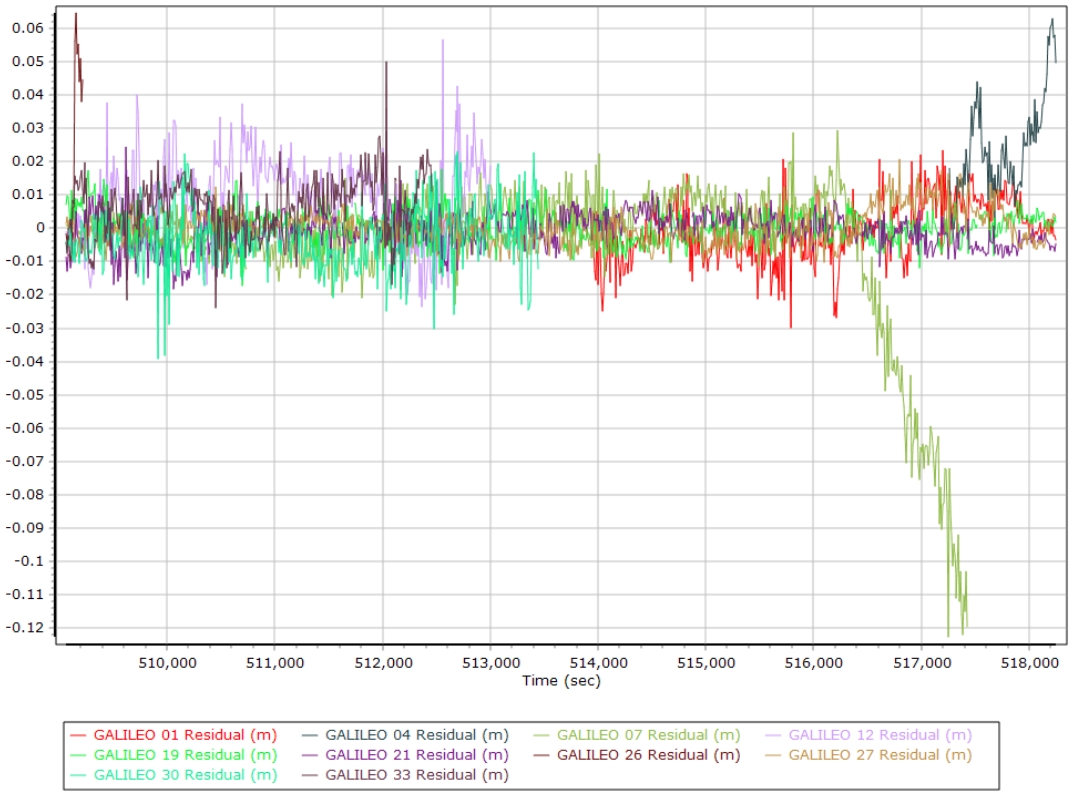
GPS Residuals



GLONASS Residuals



GALILEO Residuals



GNSS-Inertial Processor Configuration

Processing mode	IN-Fusion PP-RTX		
Stabilized mount	False		
Processing start time	508636.000 (11/5/2021 9:17:16 PM)		
Processing end time	518306.000 (11/5/2021 11:58:26 PM)		
Initial attitude source	Real-Time VNAV/RNAV Attitude		
IMU Sensor Context	Processing with Onboard IMU		
Reference to IMU lever arm (m)	0.000	0.000	0.000
Reference to IMU mounting angles (deg)	0.000	0.000	90.000
Reference to Primary GNSS lever arm (m)	-0.503	-0.047	-1.205
Reference to Primary GNSS lever arm std dev (m)	0.030	0.030	0.030
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

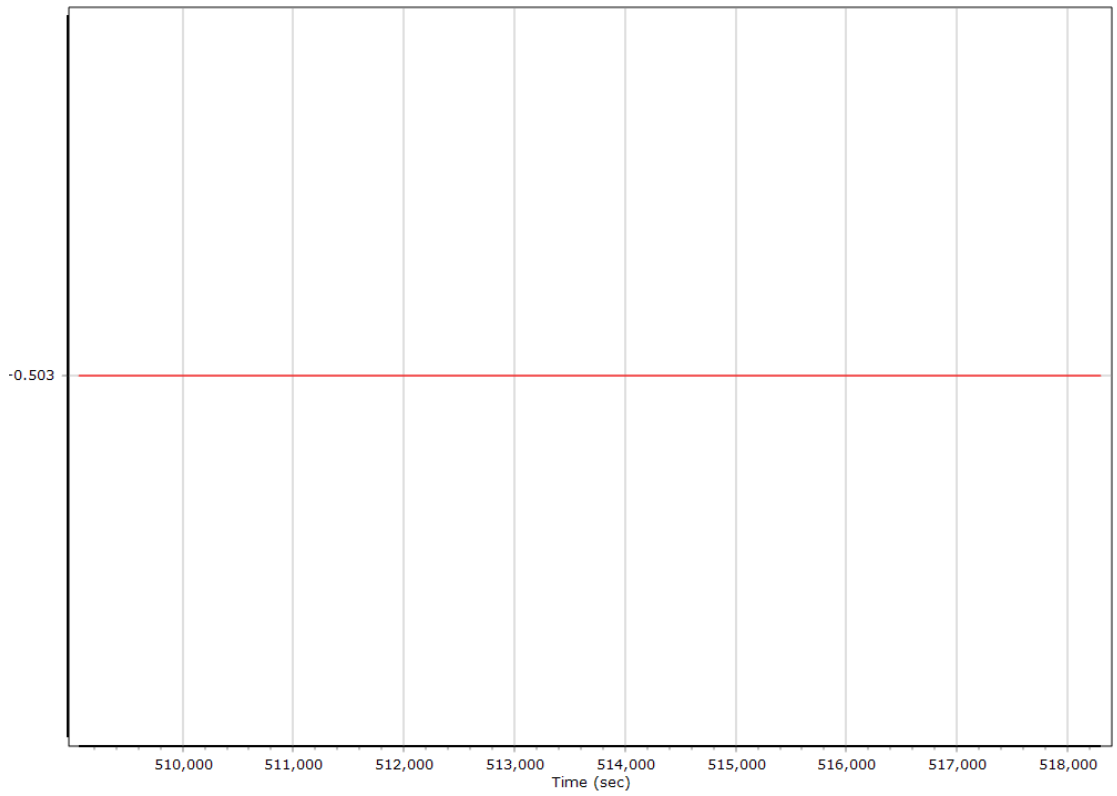
Calibrated Installation Parameters

Reference-Primary GNSS Lever Arm (m)

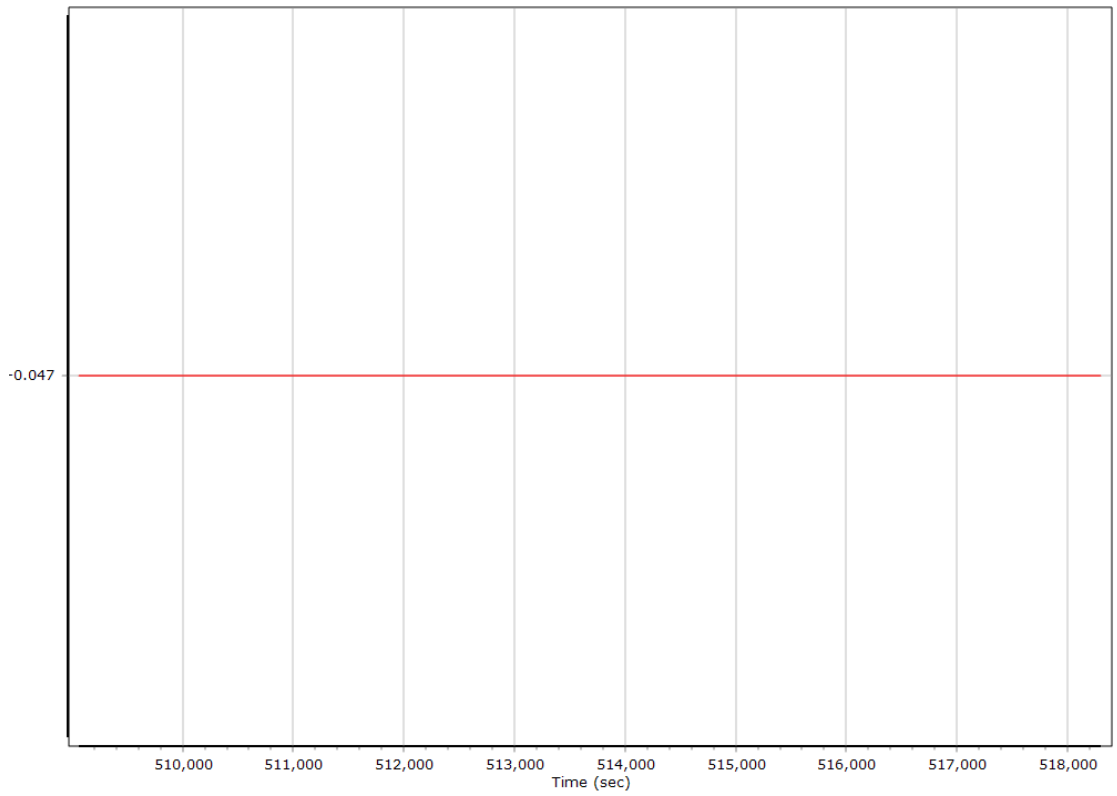
Reference-Primary GNSS Lever Arm Automatic Calibration Results

Original Reference to Primary GNSS lever arm (m)	-0.497	-0.045	-1.199
Iteration 1 Reference to Primary GNSS lever arm (m)	-0.503	-0.047	-1.205
Iteration 2 Reference to Primary GNSS lever arm (m)	-0.503	-0.047	-1.205
Primary GNSS Lever Arm In use	Iteration 2		

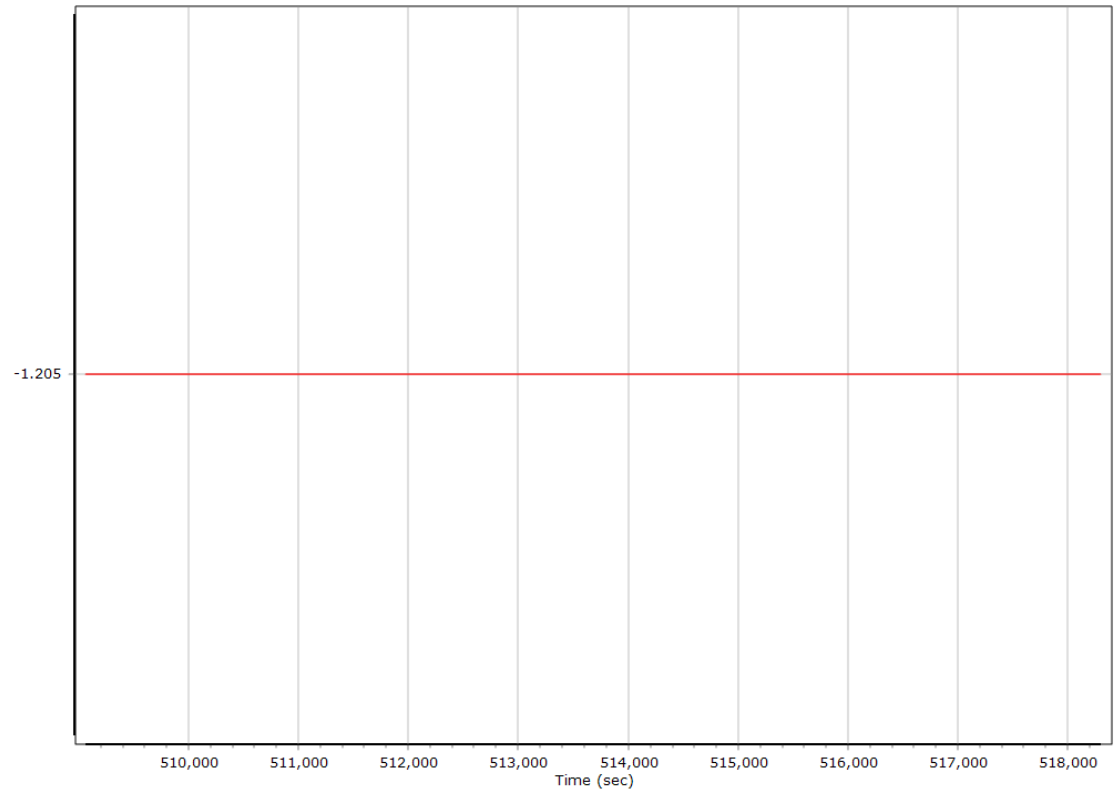
X Reference-Primary GNSS Lever Arm (m)



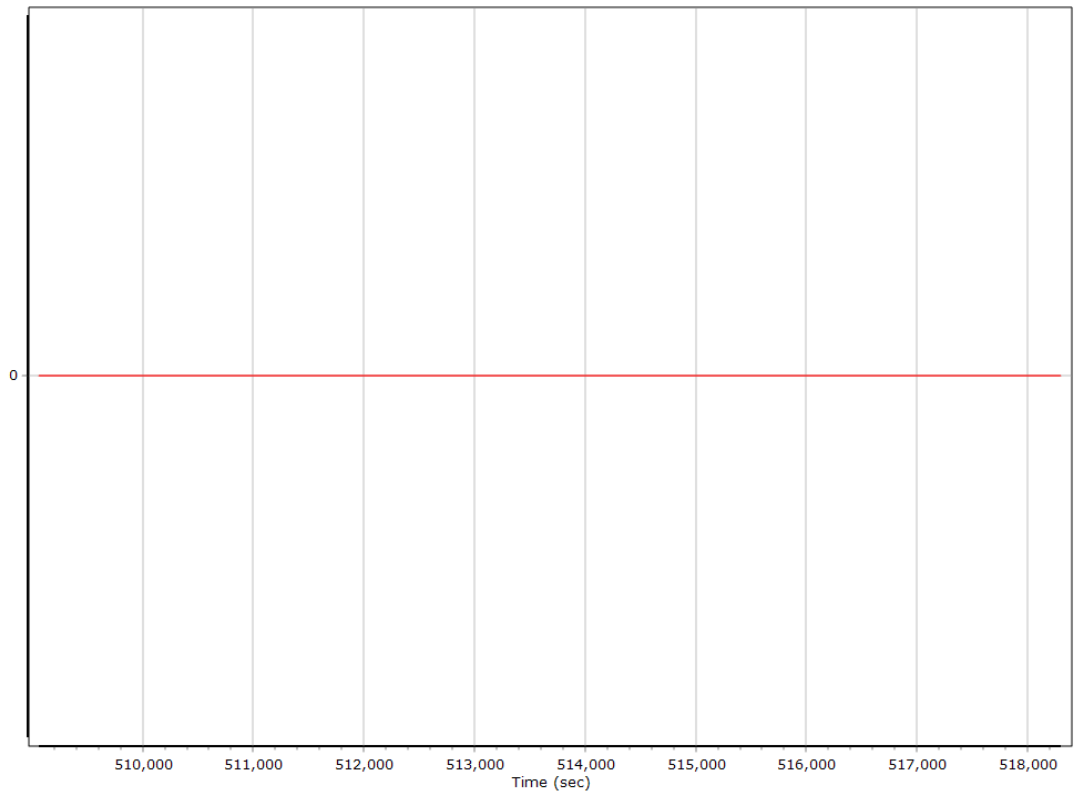
Y Reference-Primary GNSS Lever Arm (m)



Z Reference-Primary GNSS Lever Arm (m)



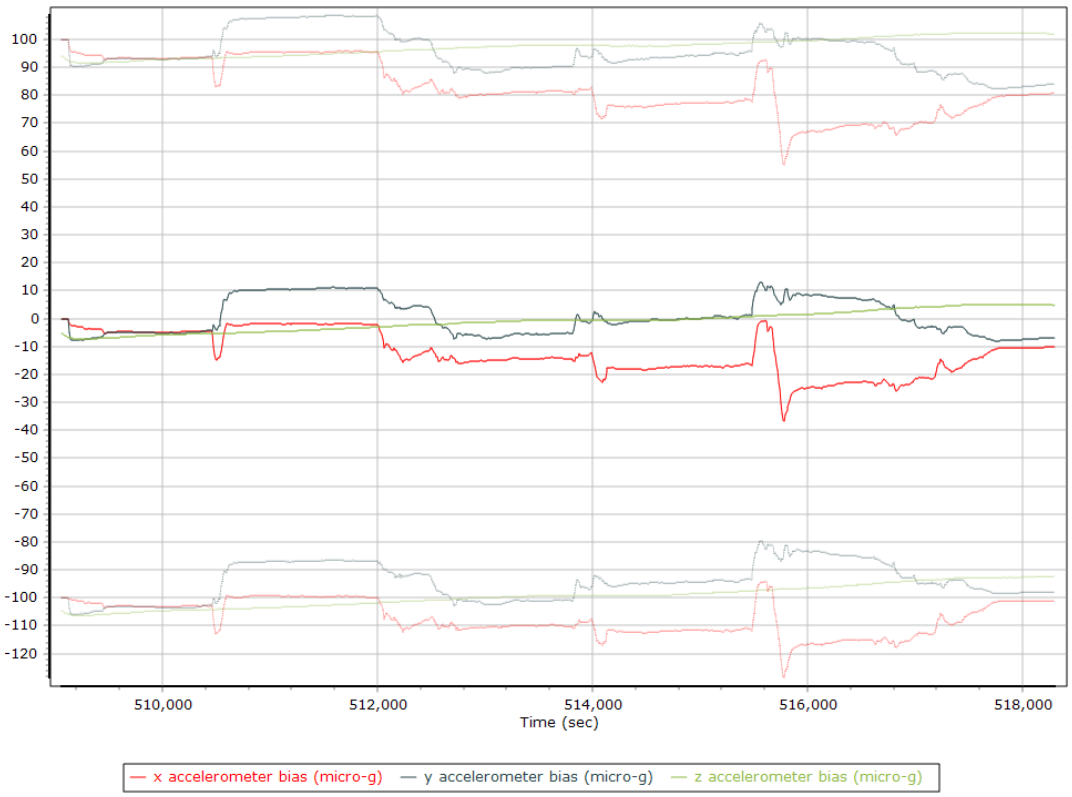
Reference-Primary GNSS Lever Arm Figure of Merit



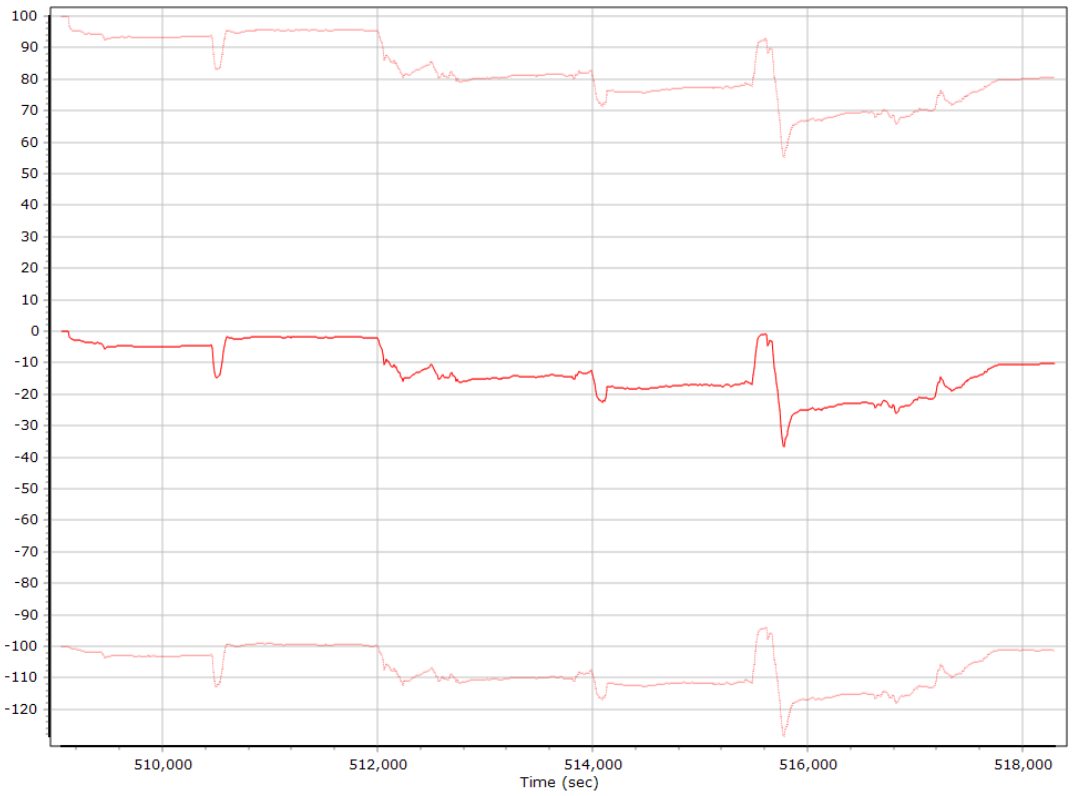
IN-Fusion QC

Forward Processed Estimated Errors, Reference Frame

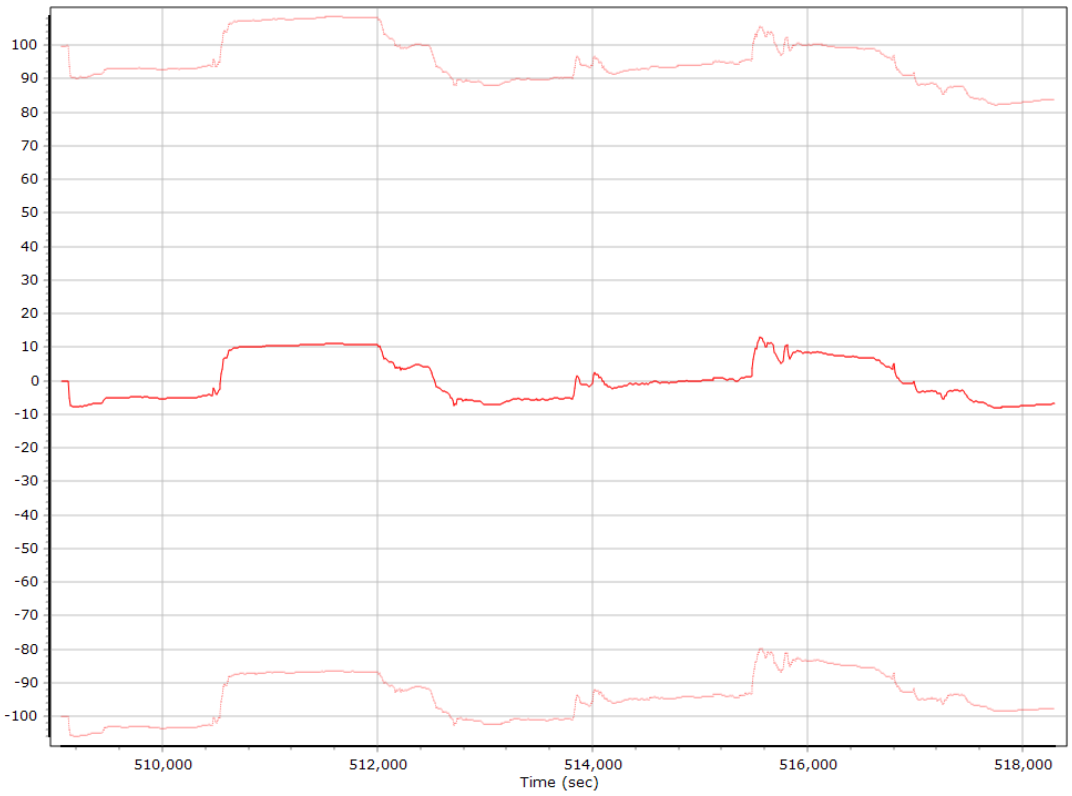
Accelerometer Bias (micro-g)



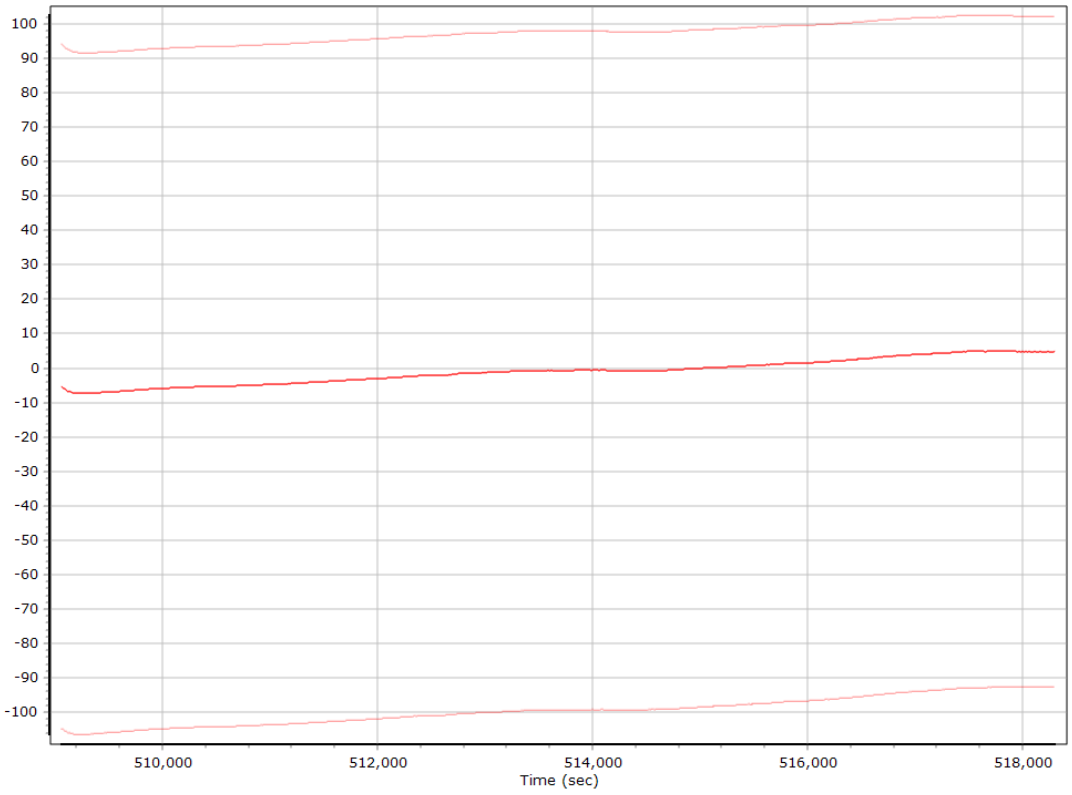
X Accelerometer Bias (micro-g)



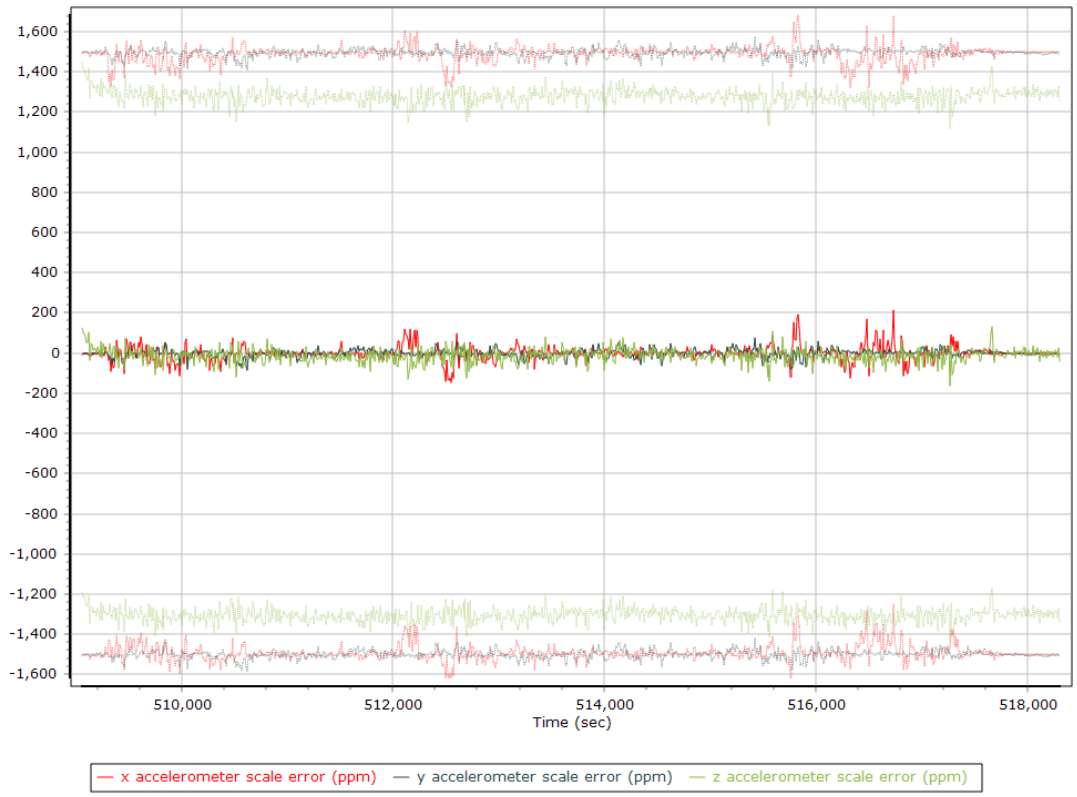
Y Accelerometer Bias (micro-g)



Z Accelerometer Bias (micro-g)



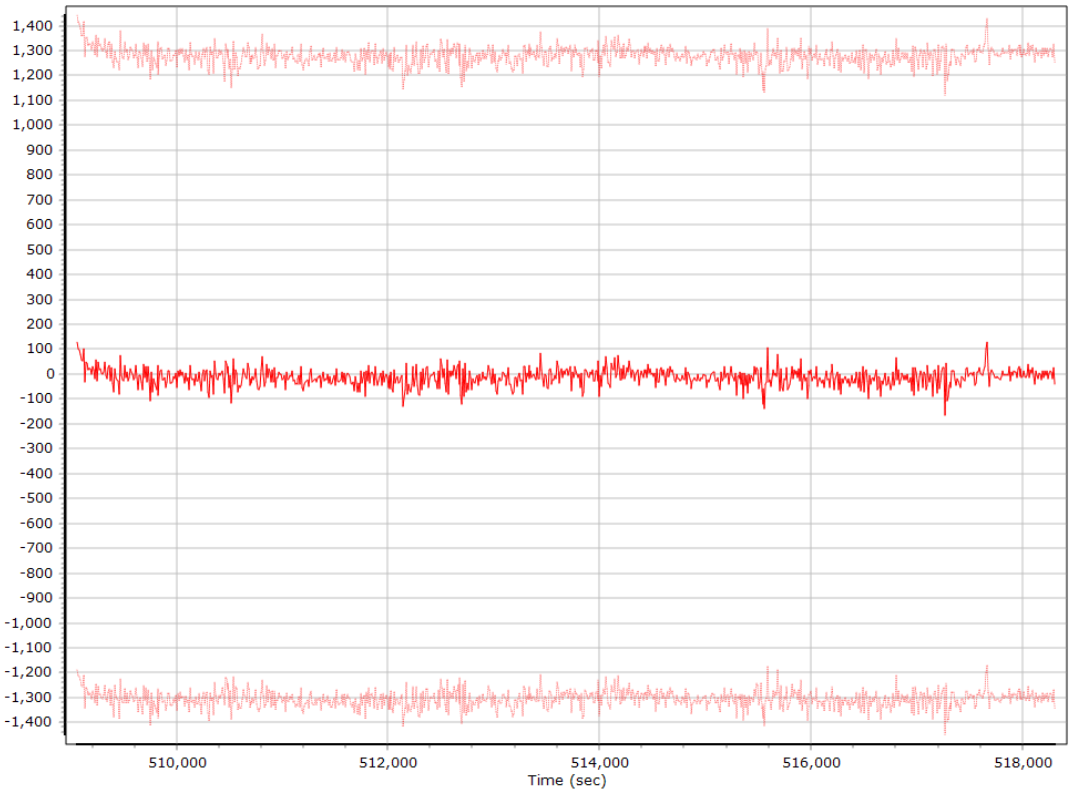
Accelerometer Scale Error (ppm)



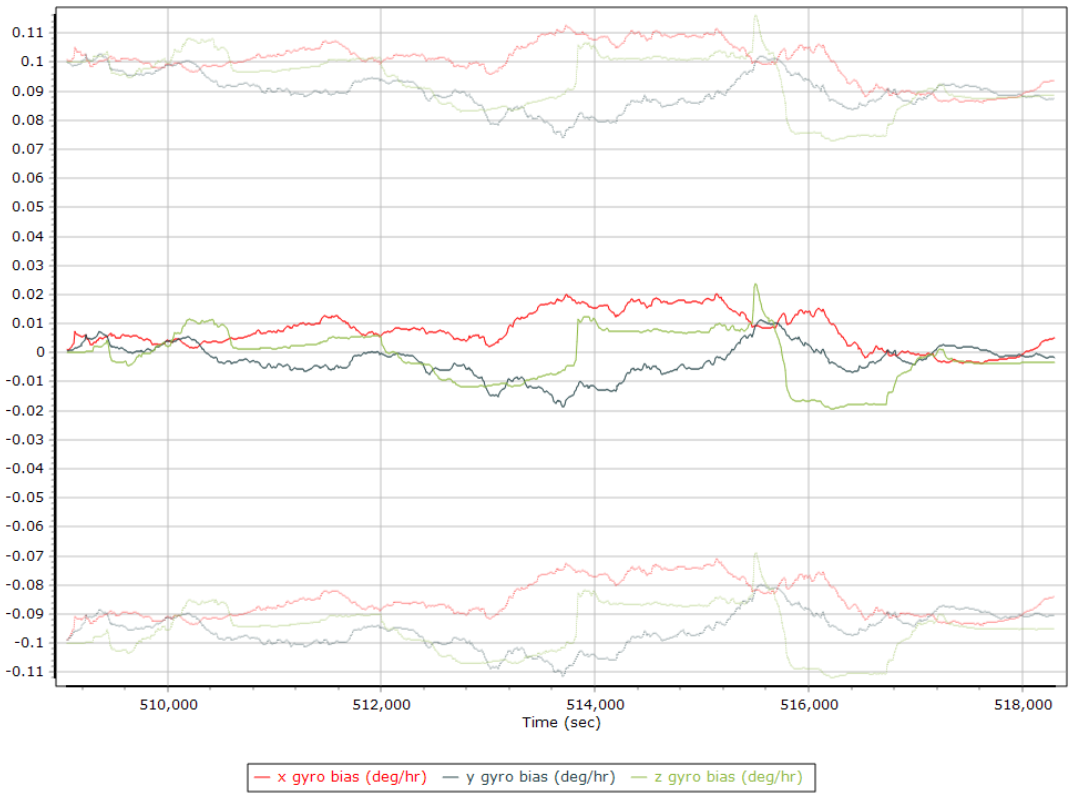
X Accelerometer Scale Error (ppm)

Y Accelerometer Scale Error (ppm)

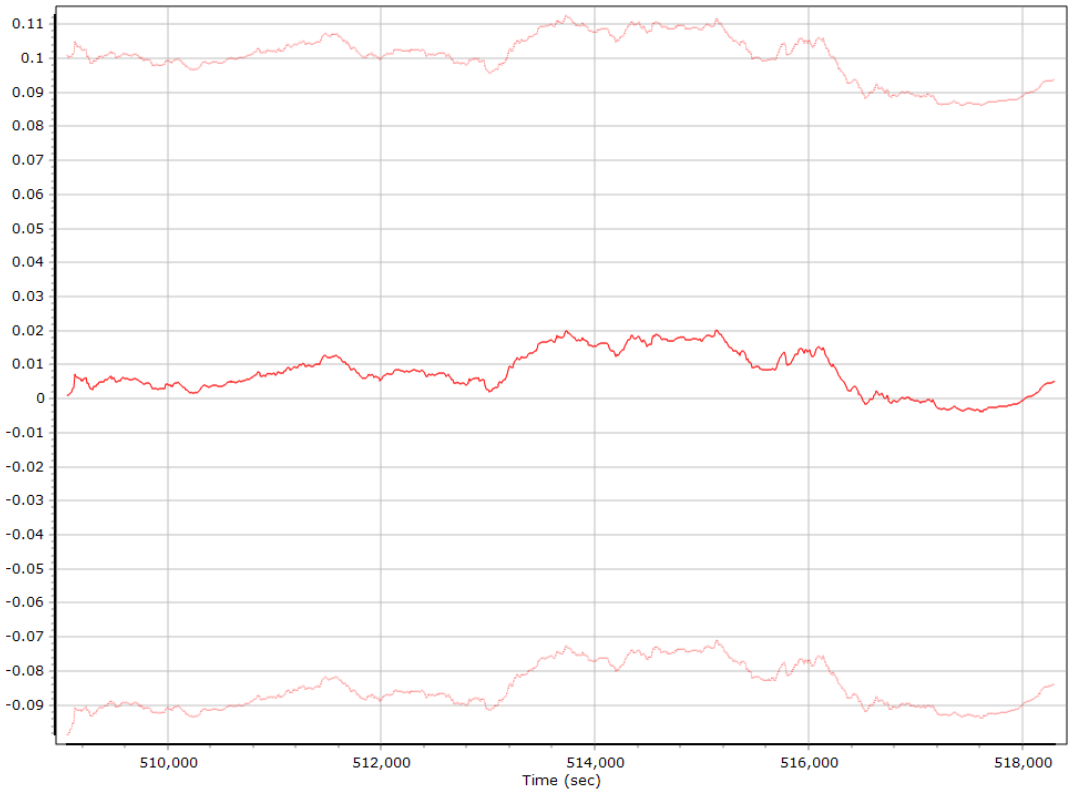
Z Accelerometer Scale Error (ppm)



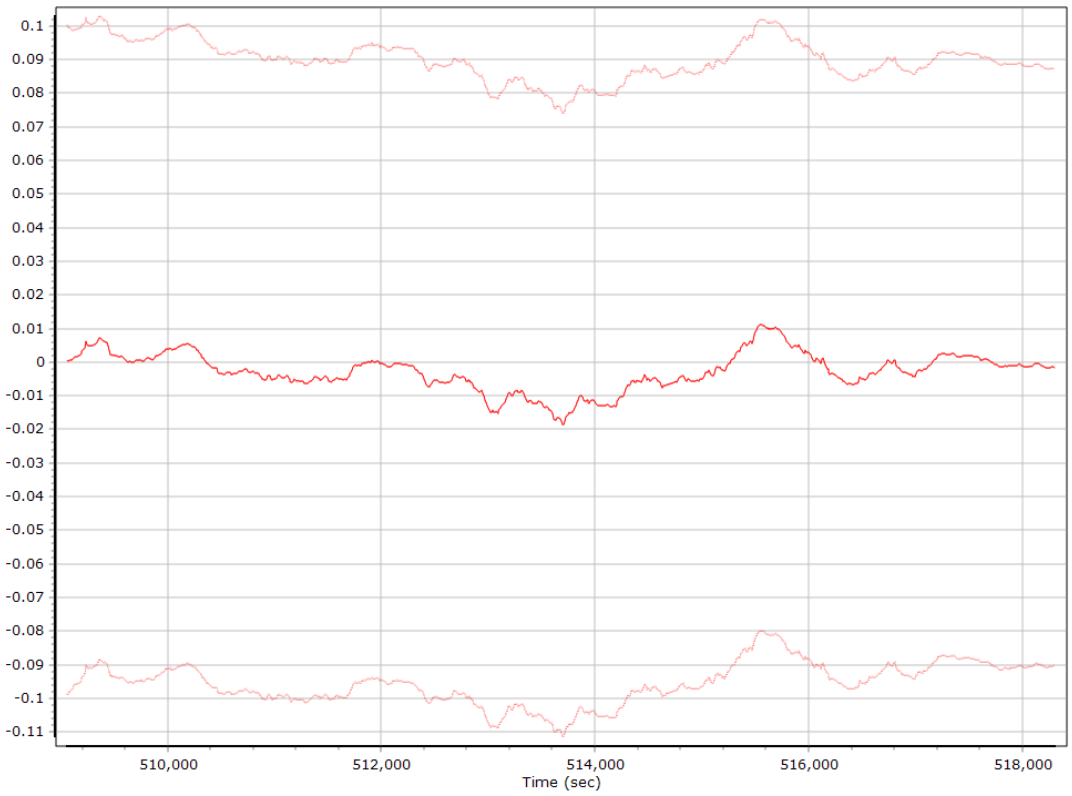
Gyro Bias (deg/h)



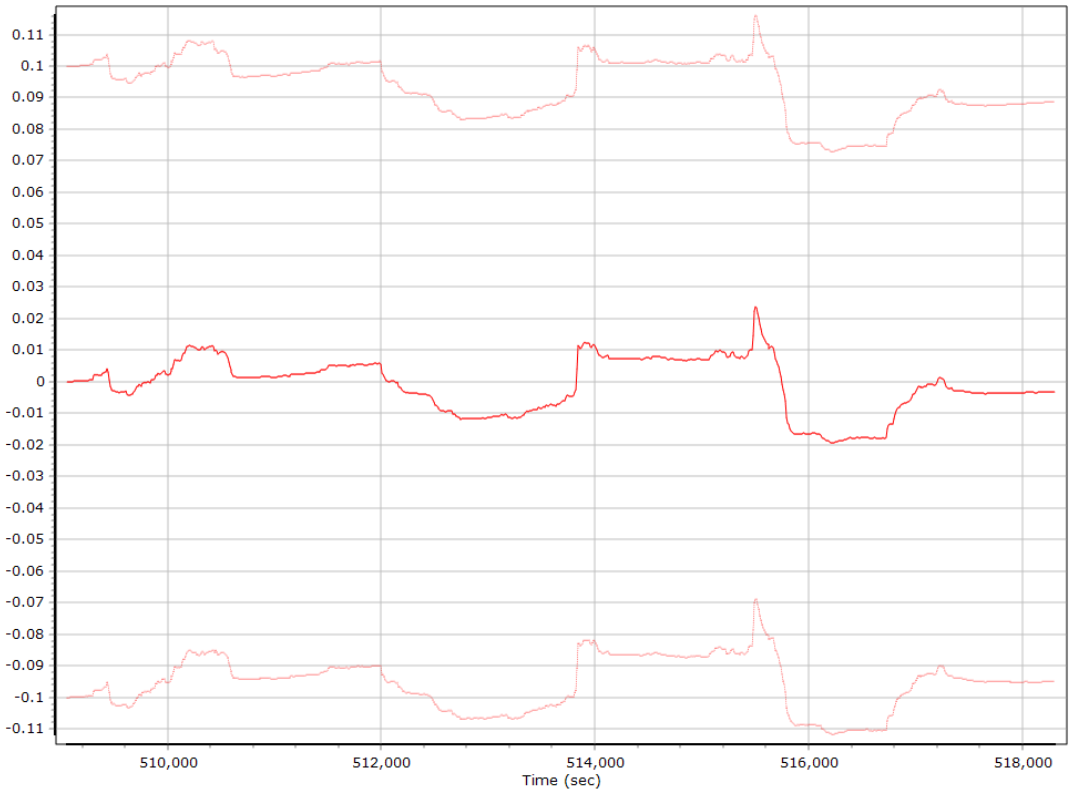
X Gyro Bias (deg/h)



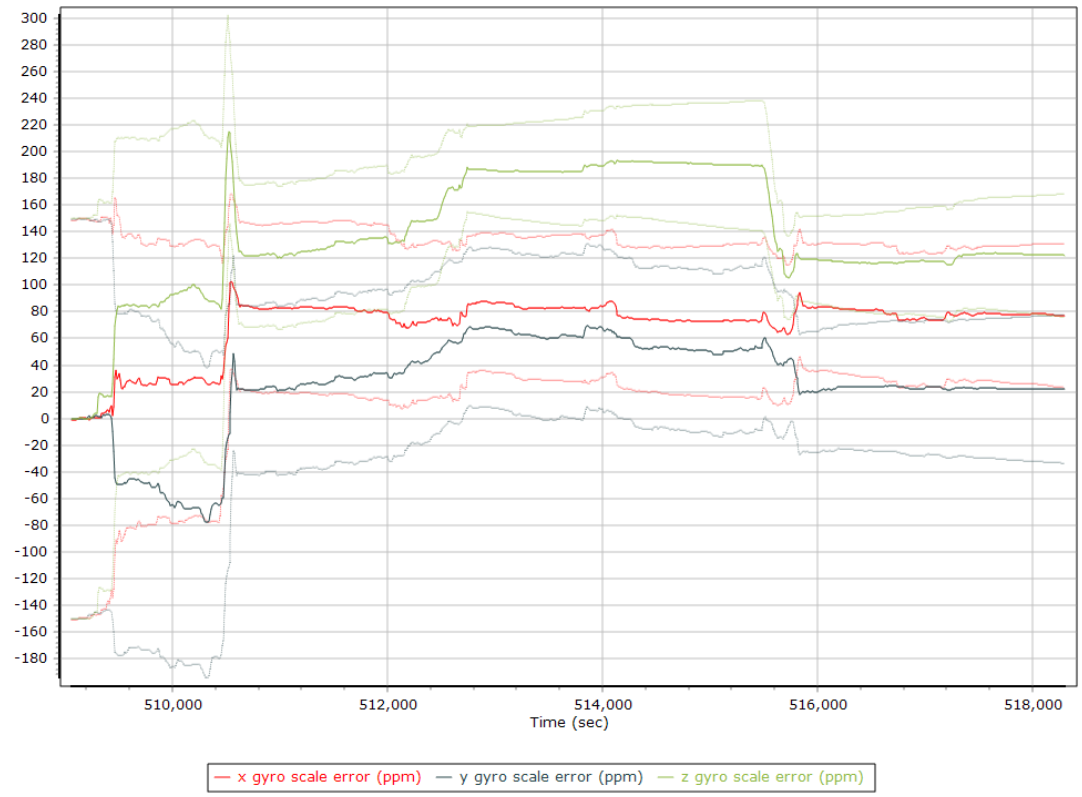
Y Gyro Bias (deg/h)



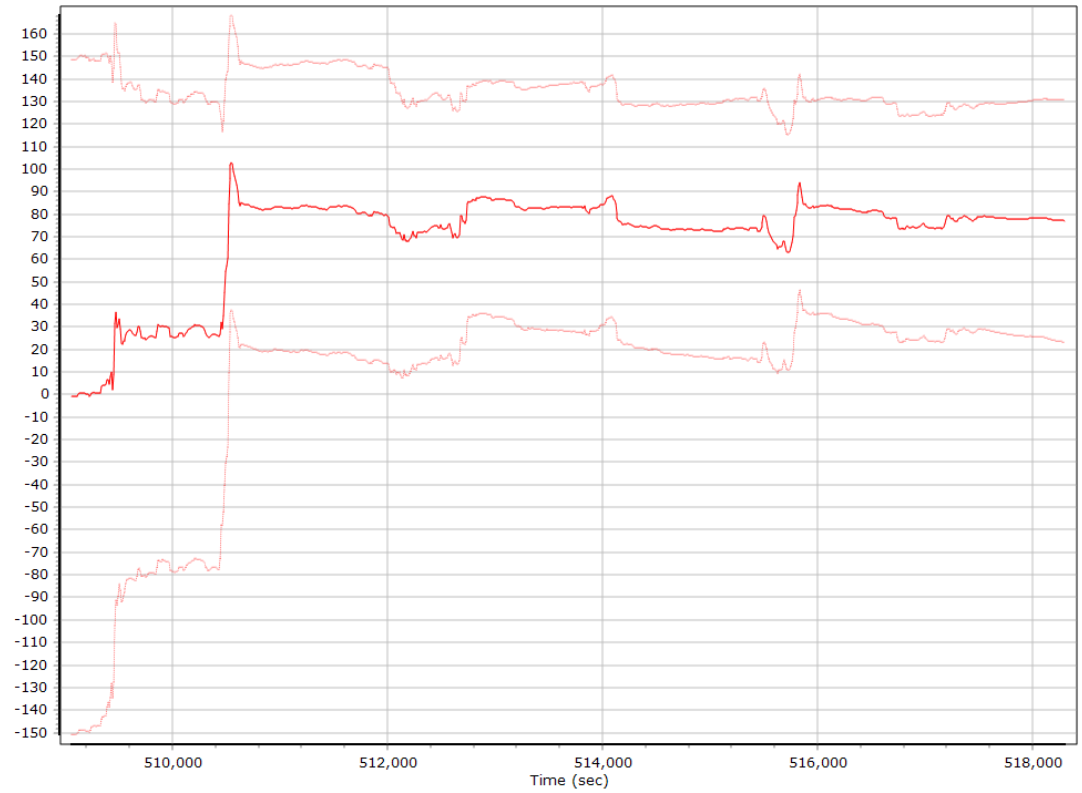
Z Gyro Bias (deg/h)



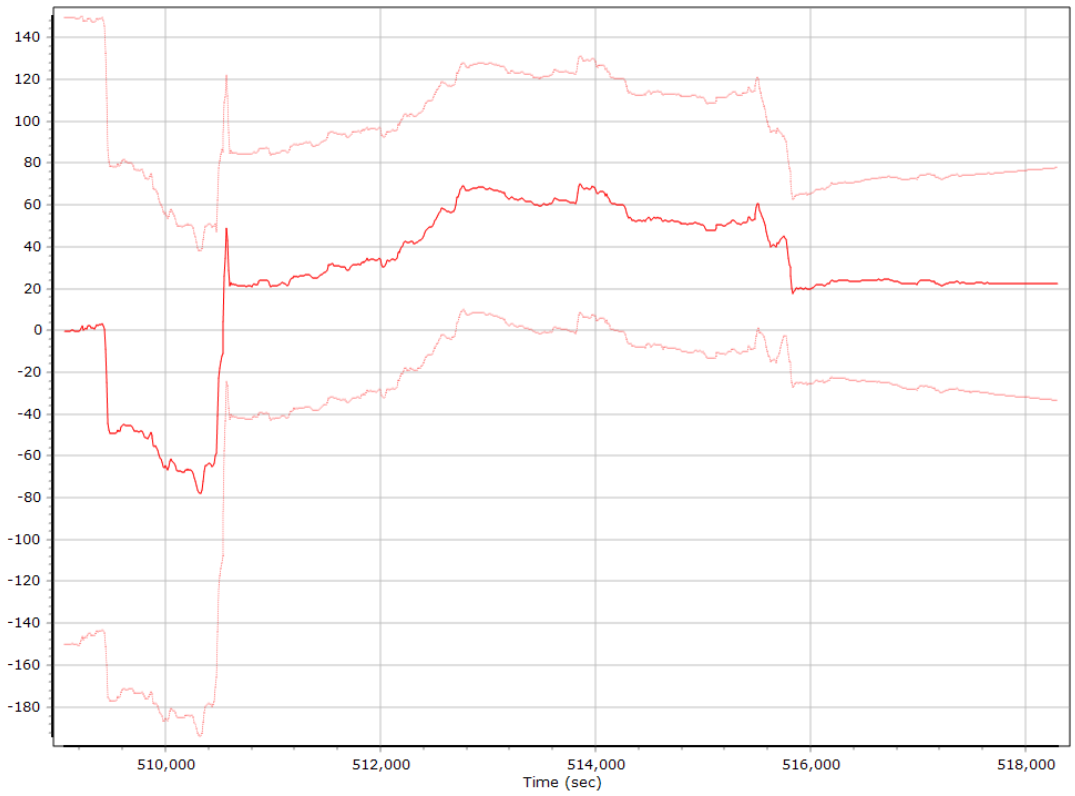
Gyro Scale Error (ppm)



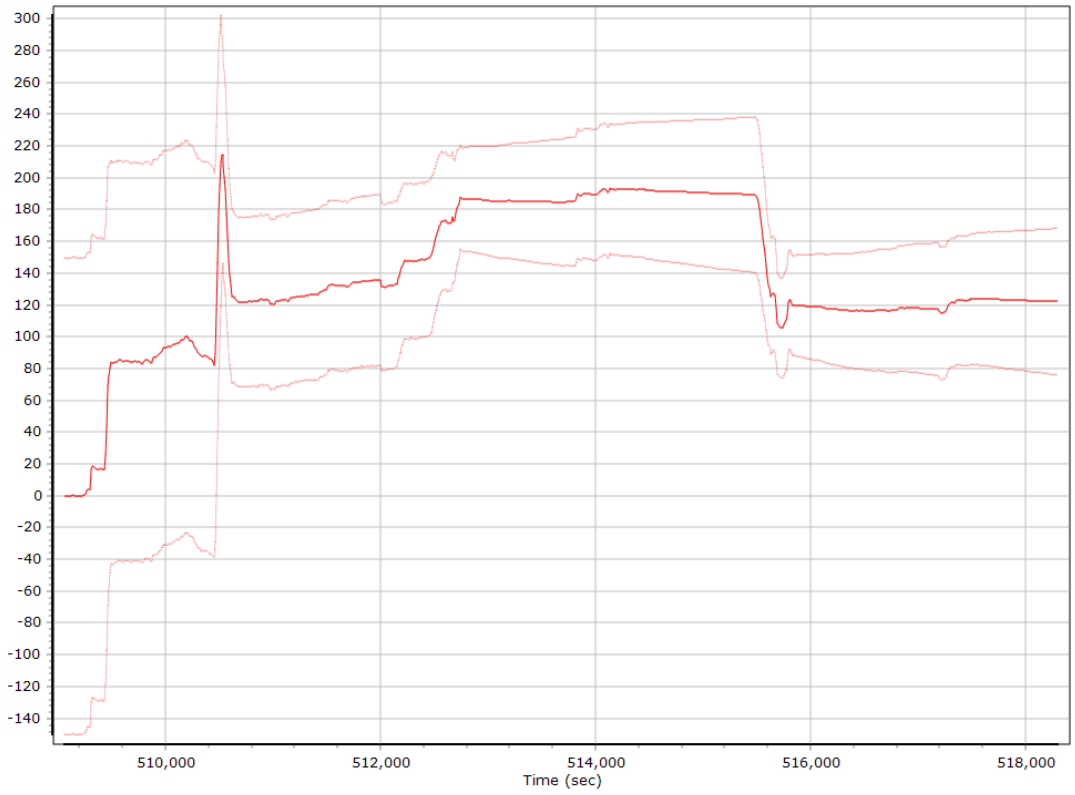
X Gyro Scale Error (ppm)



Y Gyro Scale Error (ppm)

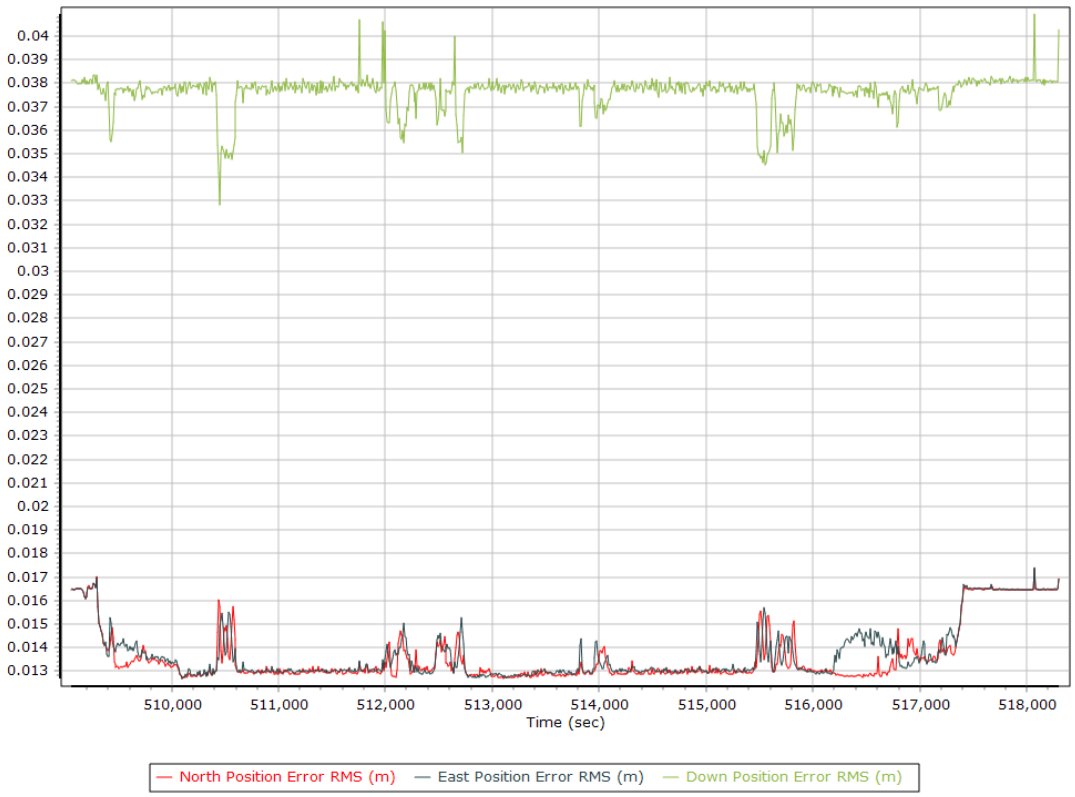


Z Gyro Scale Error (ppm)

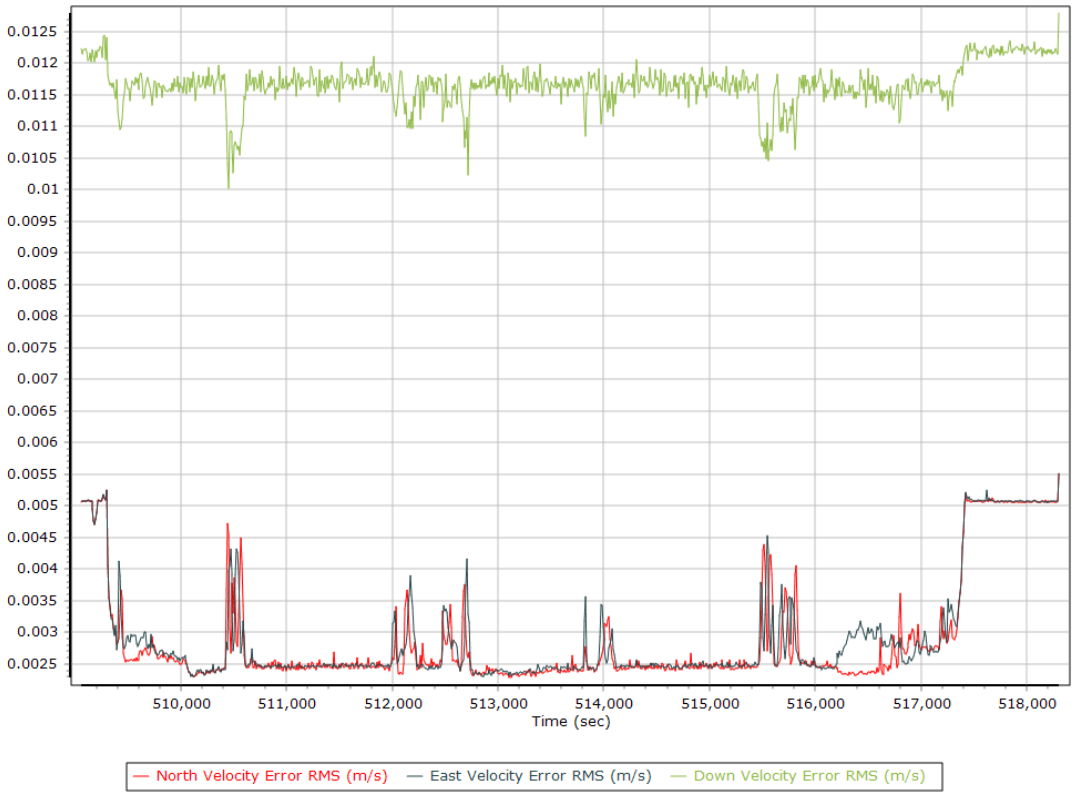


Smoothed Performance Metrics

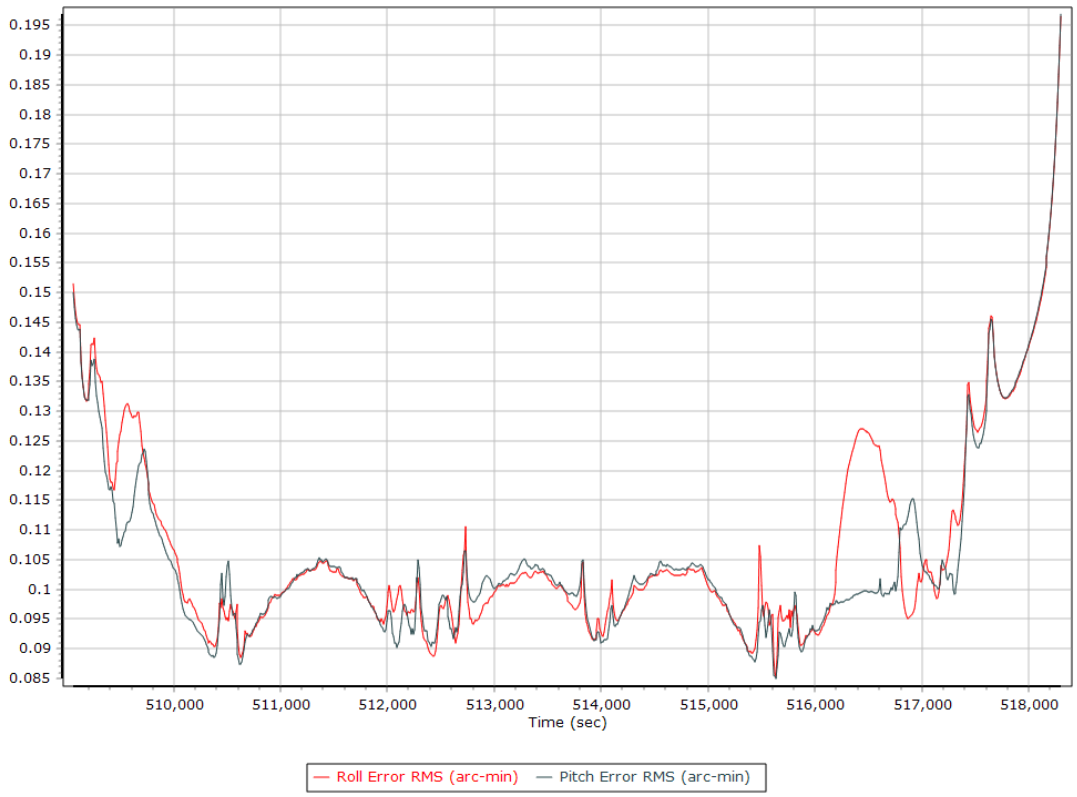
Position Error RMS (m)



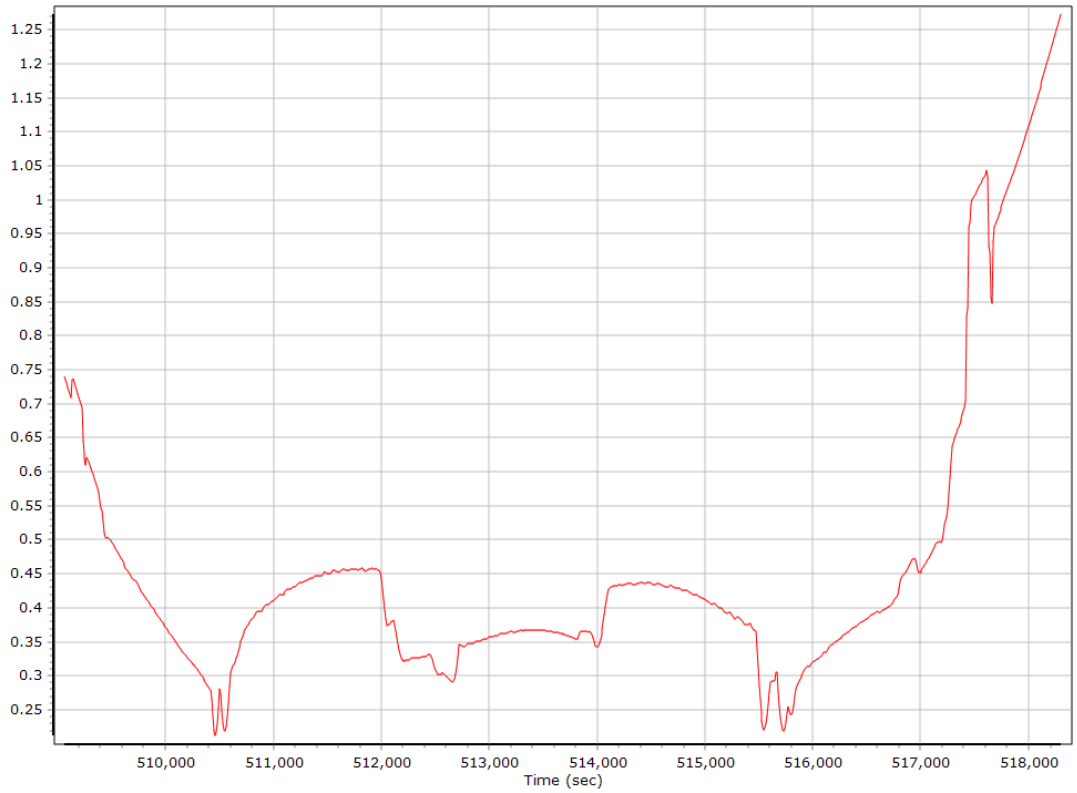
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

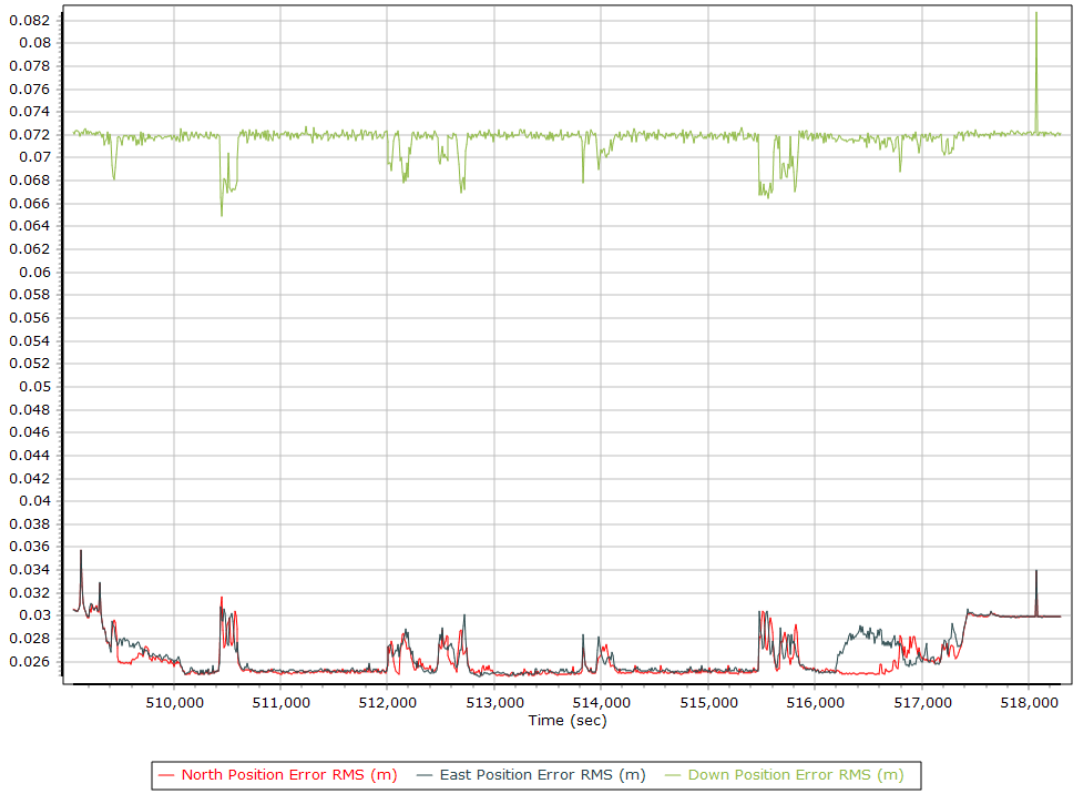


Heading Error RMS (arc-min)

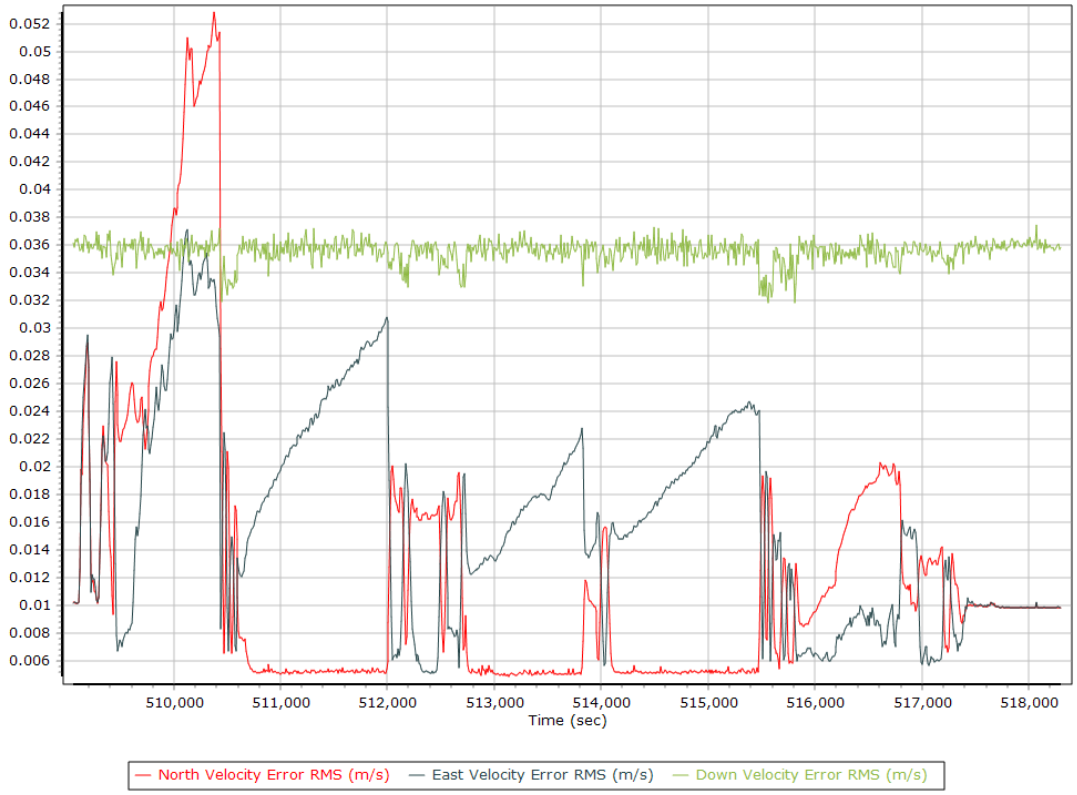


Forward Processed Performance Metrics

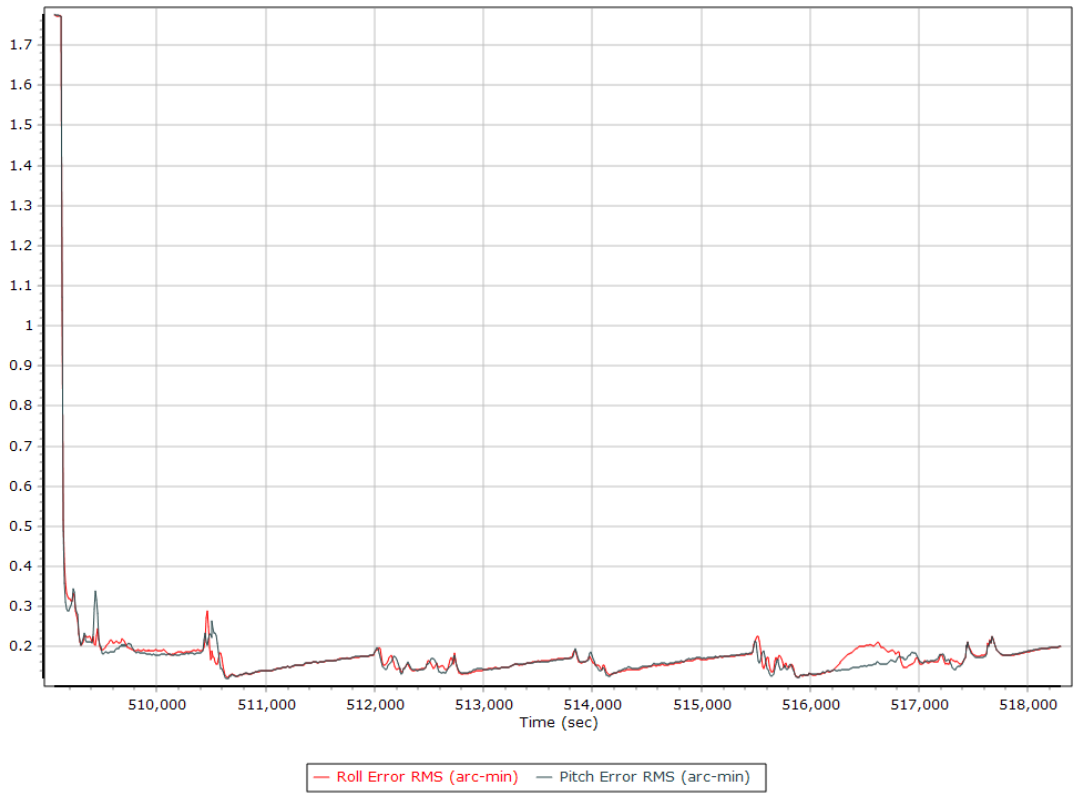
Position Error RMS (m)



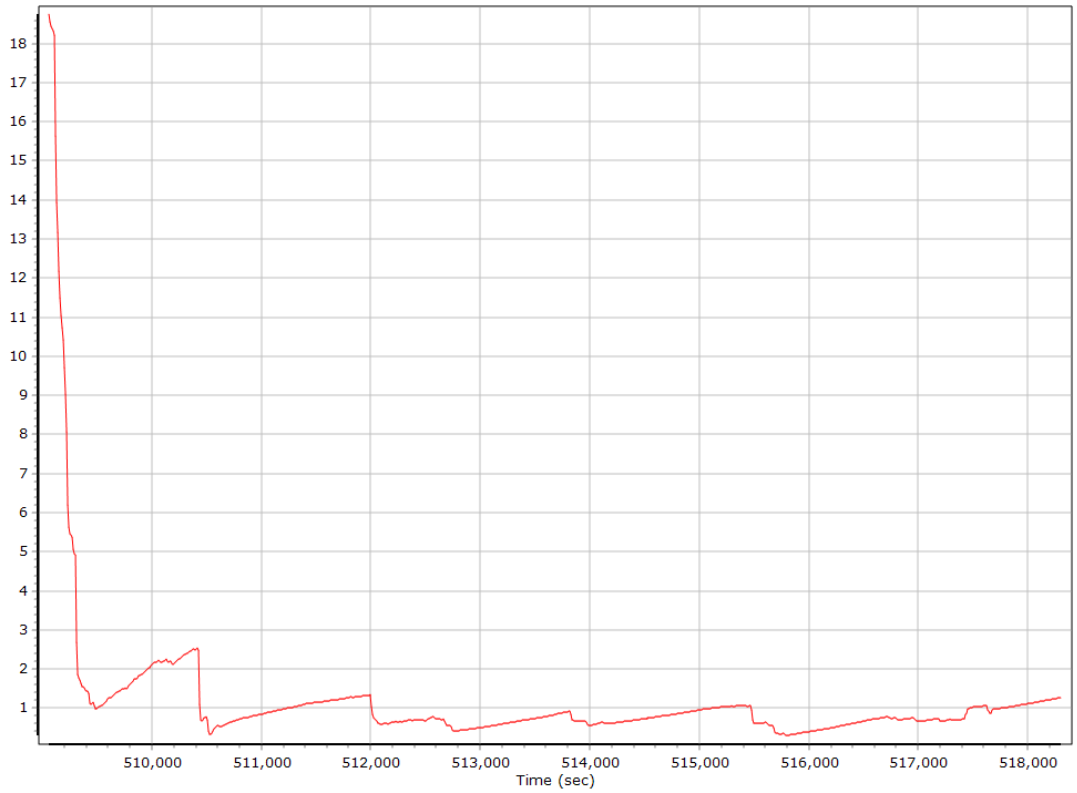
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

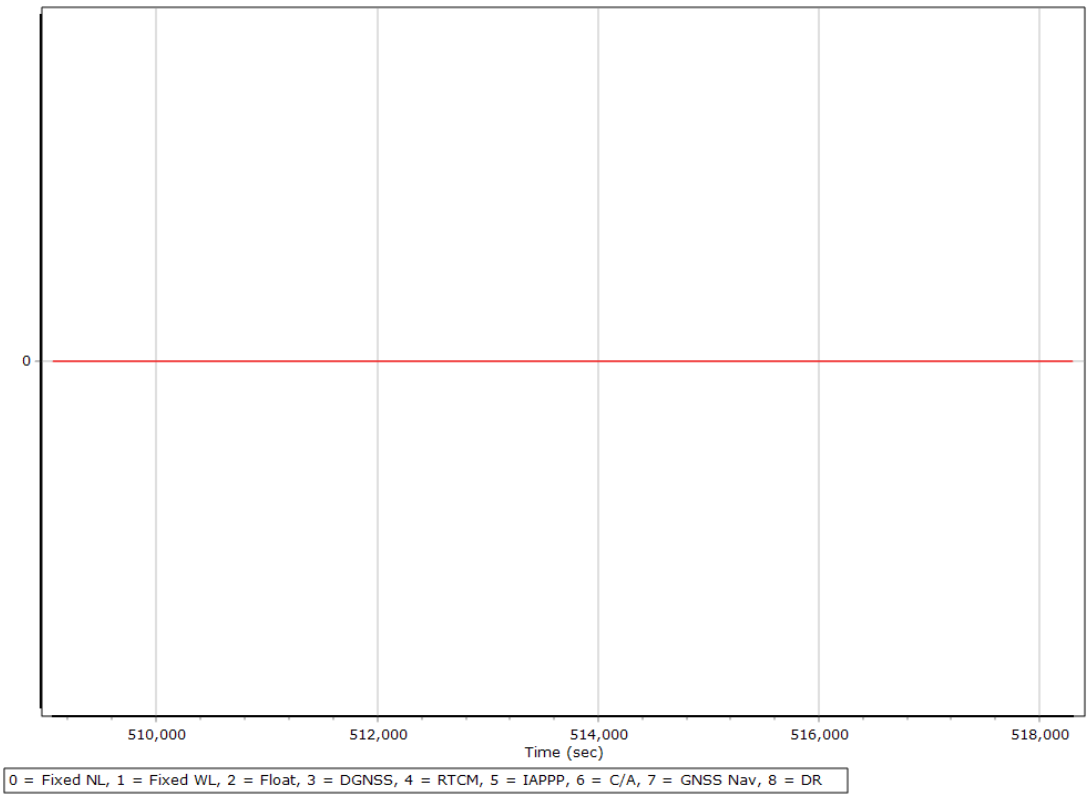


Heading Error RMS (arc-min)

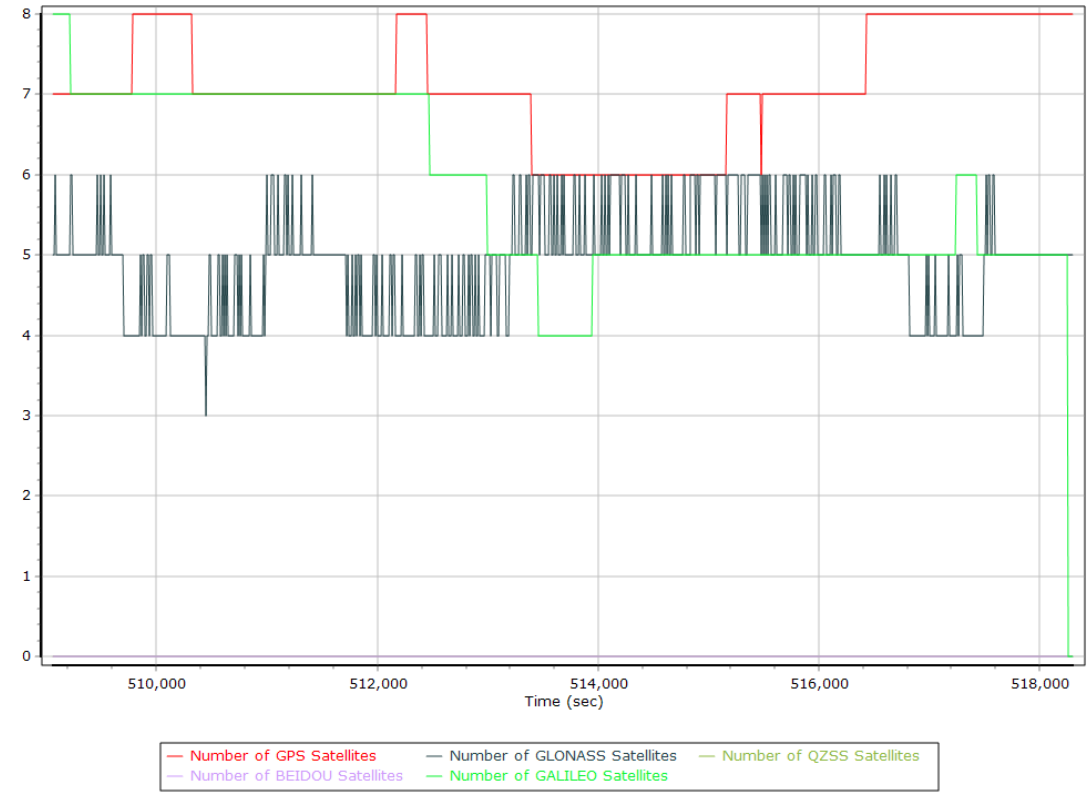


Forward Processed Solution Status

Processing Mode



Number of Satellites



Baseline Length