

General Information

Mission Information

Project name	20211126_F1_Basestation
Processing date	2021-12-07 18:58:56
Mission date	2021-11-26 15:55:48
Mission duration	04:22:56.000
Processing mode	IN-Fusion Single Base
GPS Station	DHLG Durmid Hill

Rover Hardware Information

Product	POS AV 610 VER6 HW2.5-12
Serial number	S/N12299
IMU type	57
Receiver type	BD982
Antenna type	AV39

Project File List

Rover Data Files

File name	File type
VQ1560.189	POS Data
VQ1560.190	POS Data
VQ1560.191	POS Data
VQ1560.192	POS Data
VQ1560.193	POS Data
VQ1560.194	POS Data
VQ1560.195	POS Data
VQ1560.196	POS Data
VQ1560.197	POS Data
VQ1560.198	POS Data
VQ1560.199	POS Data
VQ1560.200	POS Data
VQ1560.201	POS Data
VQ1560.202	POS Data
VQ1560.203	POS Data
VQ1560.204	POS Data
VQ1560.205	POS Data
VQ1560.206	POS Data
VQ1560.207	POS Data
VQ1560.208	POS Data
VQ1560.209	POS Data
VQ1560.210	POS Data
VQ1560.211	POS Data
VQ1560.212	POS Data
VQ1560.213	POS Data
VQ1560.214	POS Data
VQ1560.215	POS Data
VQ1560.216	POS Data
VQ1560.217	POS Data
VQ1560.218	POS Data
VQ1560.219	POS Data
VQ1560.220	POS Data
VQ1560.221	POS Data
VQ1560.222	POS Data
VQ1560.223	POS Data
VQ1560.224	POS Data
VQ1560.225	POS Data

Input Files

File Name	File type
Ephm3300.21g	GLONASS Broadcast Ephemeris
Ephm3300.21n	GPS Broadcast Ephemeris
dhlg3300.21o	GNSS SingleBase

Output Files

Filename	File type
sbet_20211126_F1_Basestation.out	SBET Trajectory File
export_20211126_F1_Basestation_NAD83_2011.	Custom Smoothed BET Export Output

Rover Data Summary

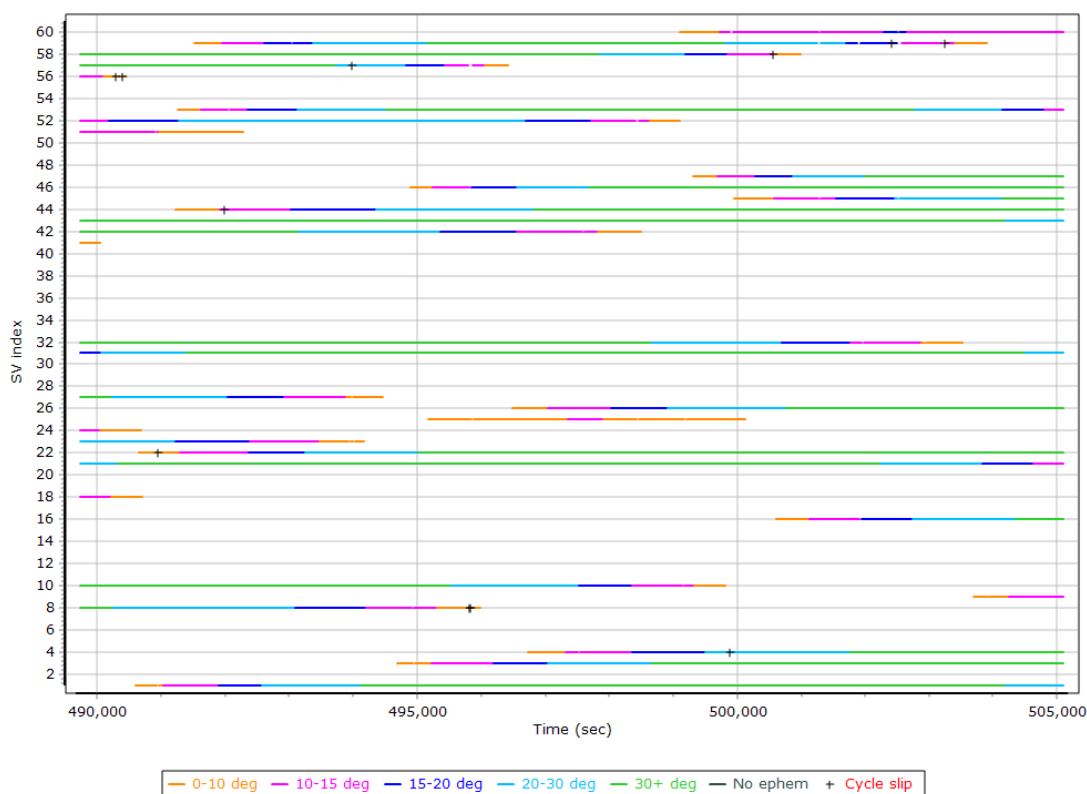
First raw data file	VQ1560.189		
Last raw data file	VQ1560.225		
Start GPS week	2185		
Start time	489341.874 (11/26/2021 15:55:41)		
End time	505106.688 (11/26/2021 20:18:26)		
Start of fine alignment	489678.801 (11/26/2021 16:01:18)		
Available subsystems	Primary GNSS, IMU		
POS Event Input	None		
Correction data	None		
IMU Installation Lever Arms & Mounting Angles			
Reference to IMU lever arm [m]	0.018	-0.010	-0.464
Reference to IMU mounting angles [deg]	0.000	0.000	0.000
Reference to Primary GNSS lever arm [m]	0.000	0.000	-1.000
Reference to Primary GNSS lever arm std dev [m]	-1.000		
Aircraft to Reference mounting angles [deg]	0.000	0.000	0.000

Raw Data QC

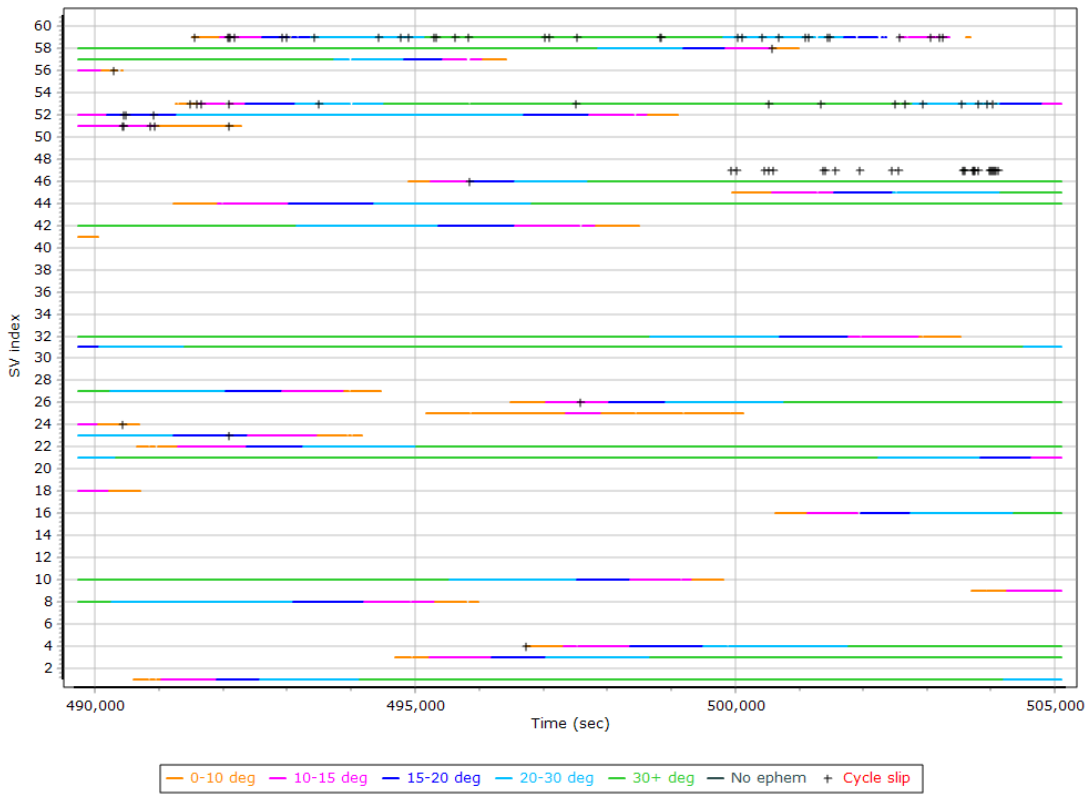
Raw IMU Import QC Summary

IMU data input file	imu_20211126_F1_Basestation.dat
IMU data check log file	imudt_20211126_F1_Basestation.log
IMU Records Processed	3154697
Termination Status	Warnings
IMU Anomalies	1
IMU Failure Messages	
489341.684 : WARNING : Gap of 489329.7225 seconds in CHECKDT input data	

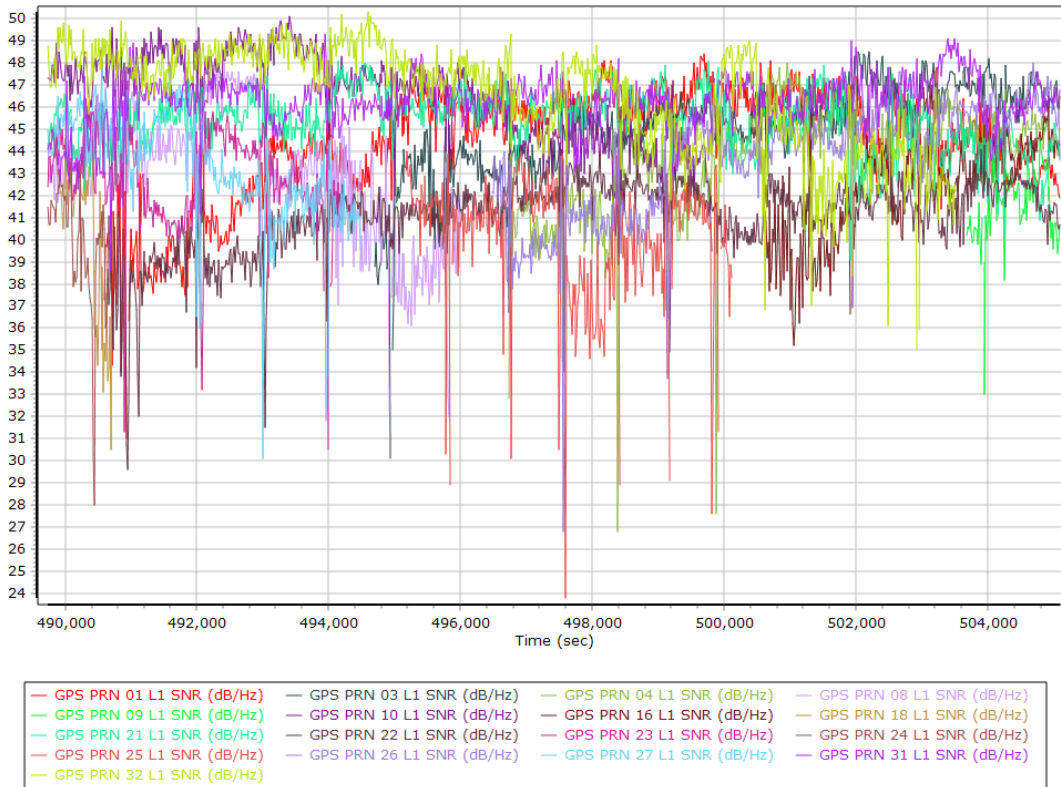
L1 Satellite Lock/Elevation



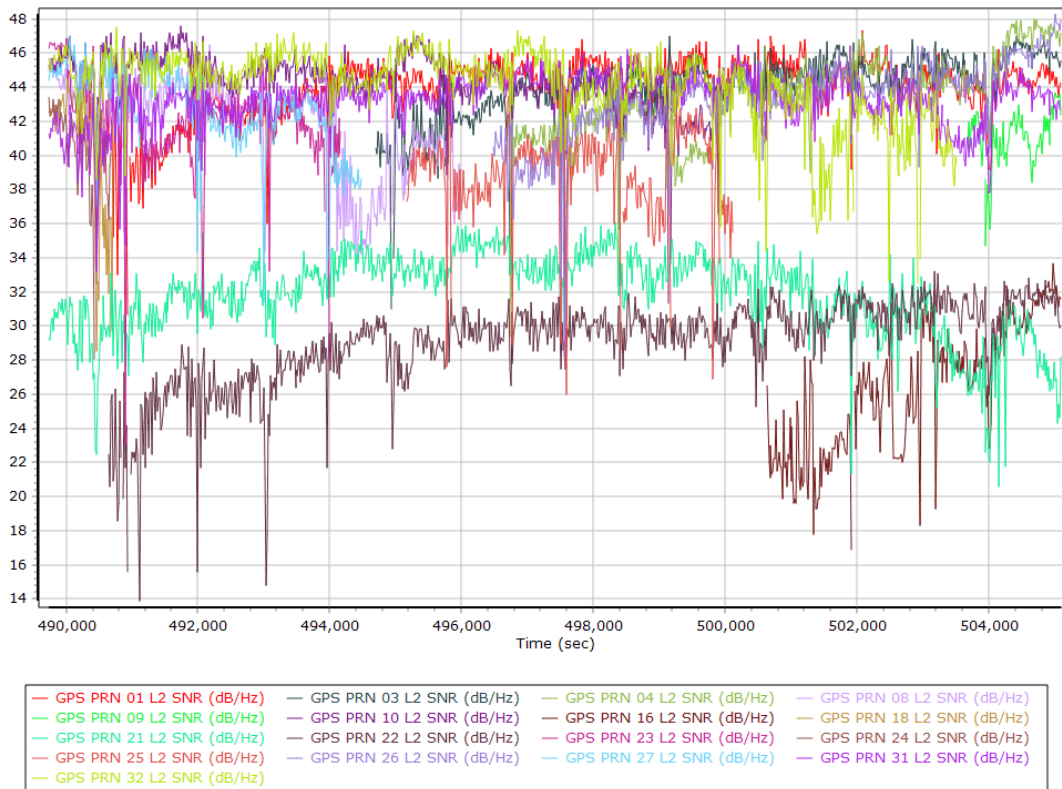
L2 Satellite Lock/Elevation



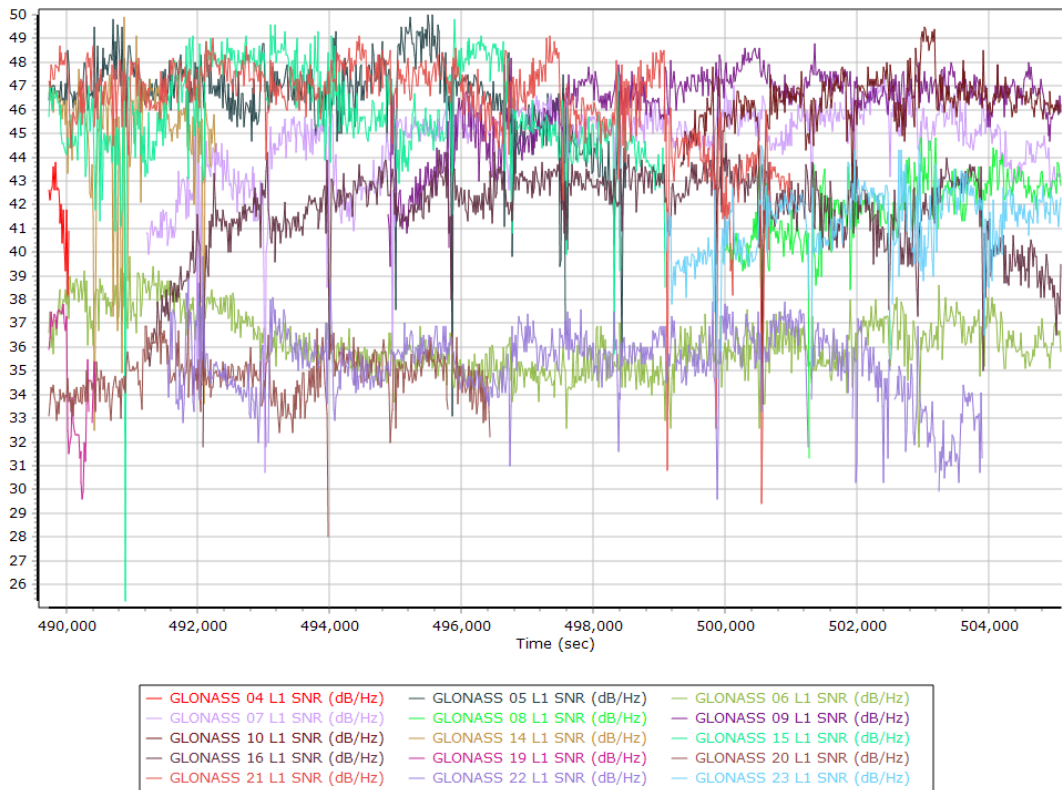
GPS L1 SNR



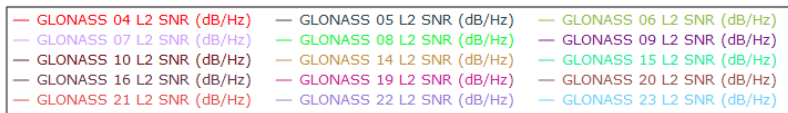
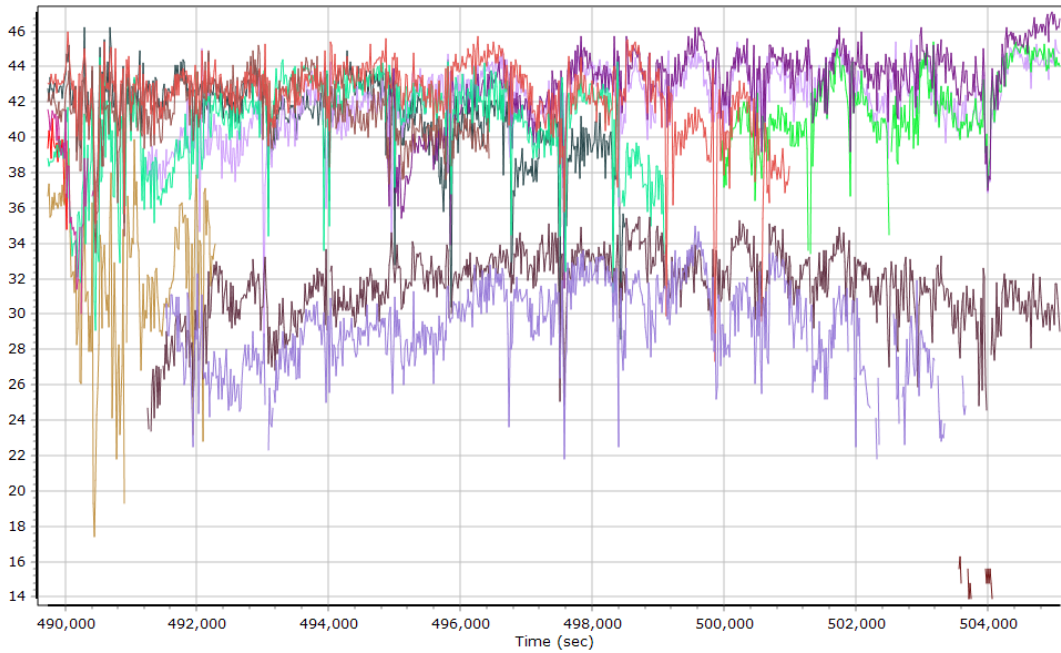
GPS L2 SNR



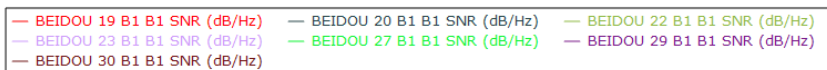
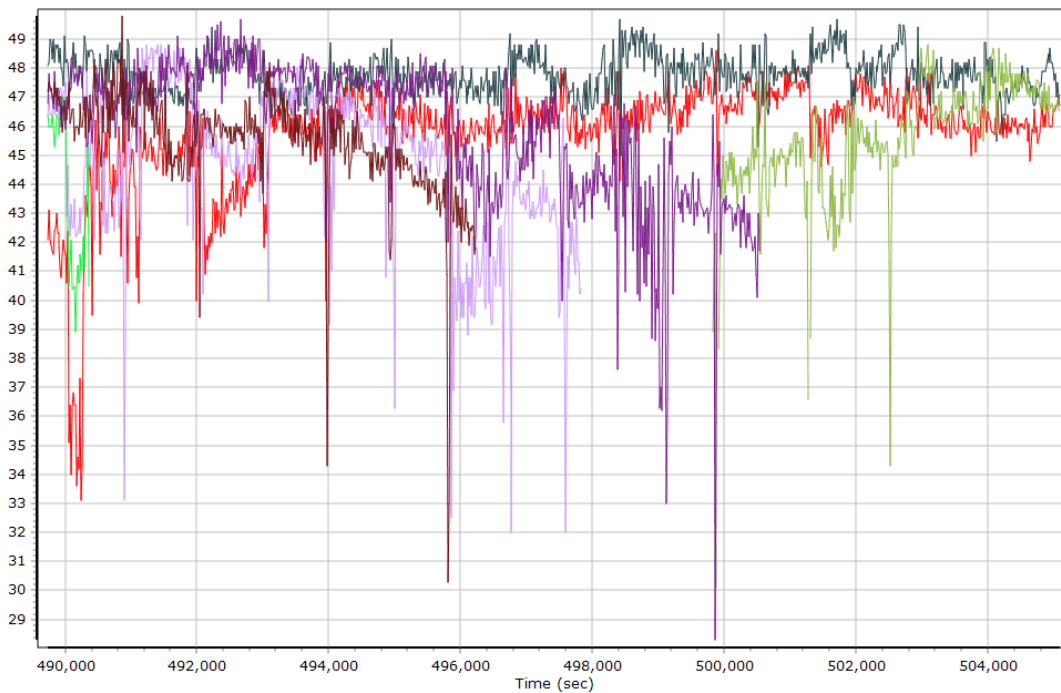
GLONASS L1 SNR



GLONASS L2 SNR

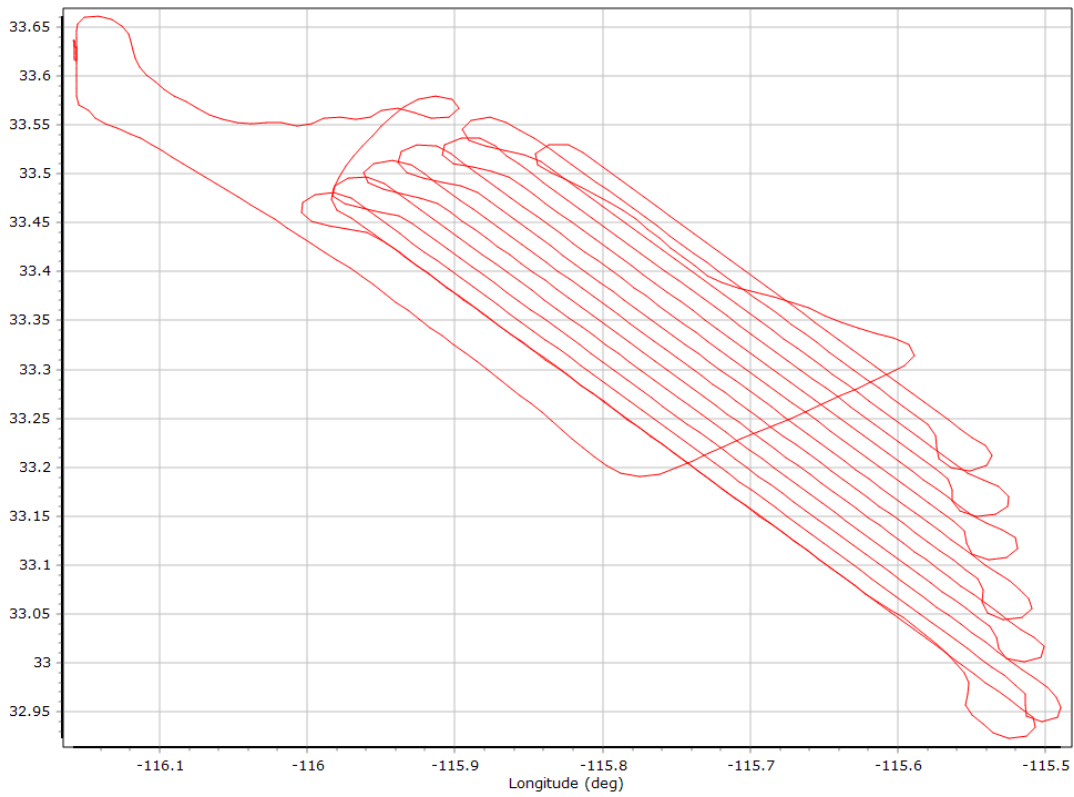


BEIDOU SNR

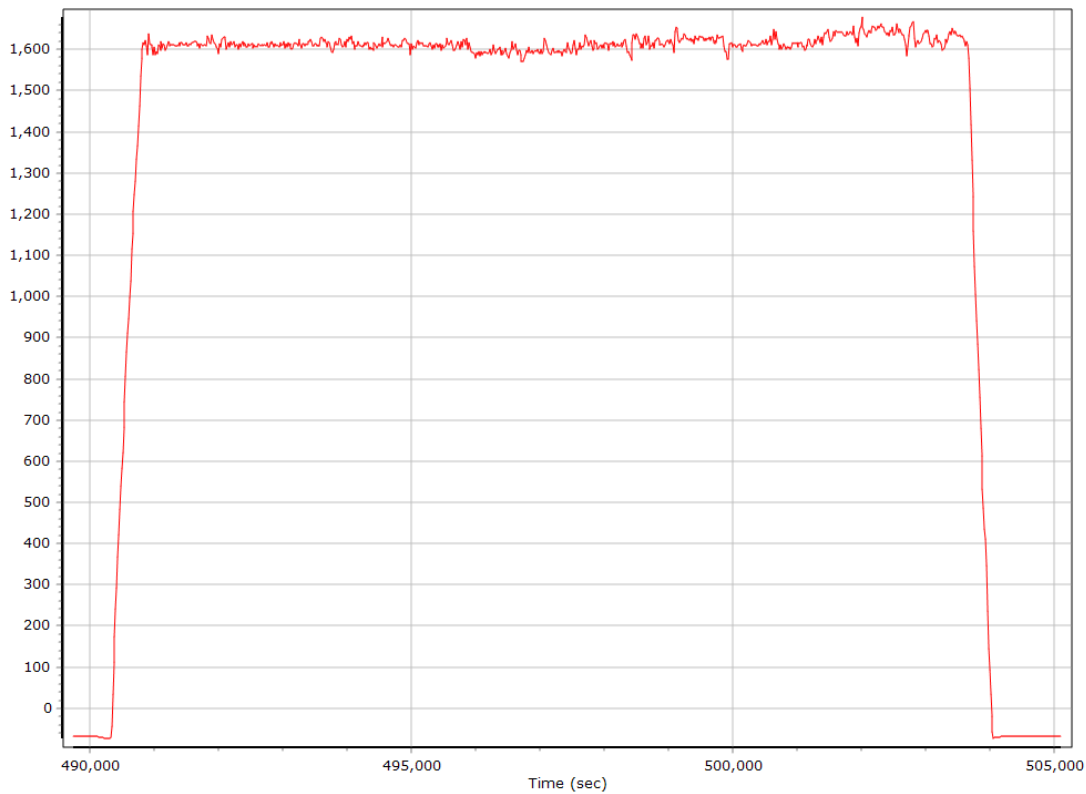


Trajectory Information

Top View



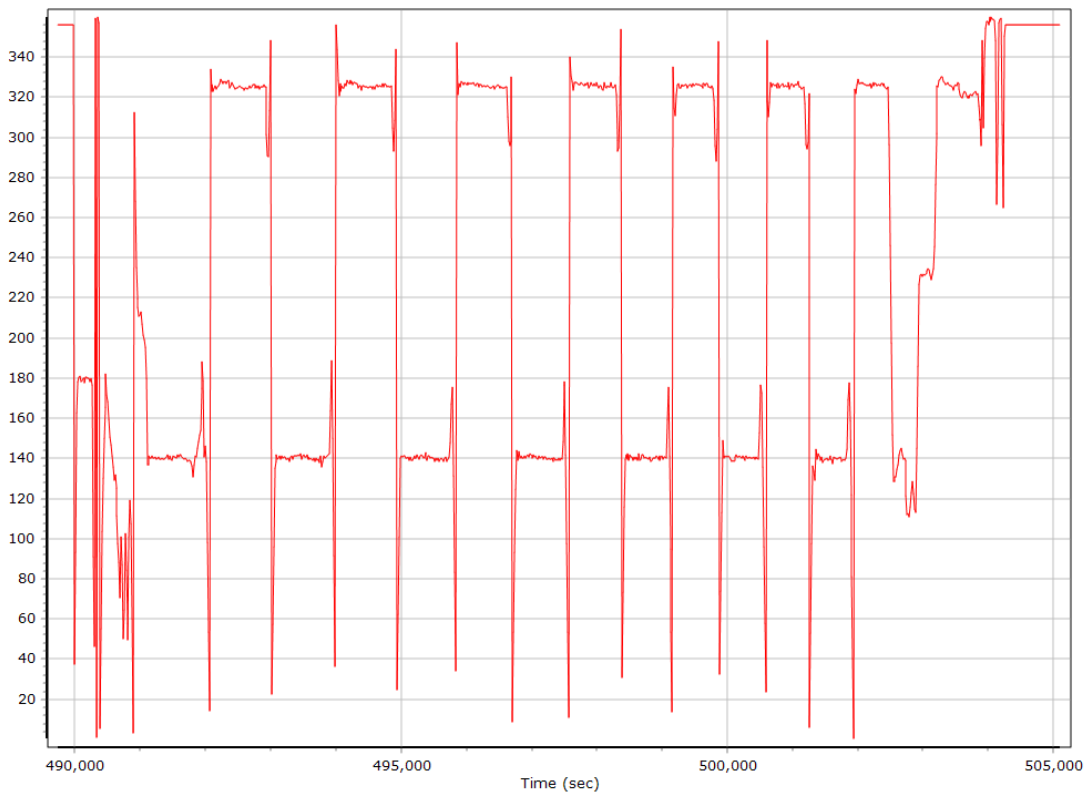
Altitude



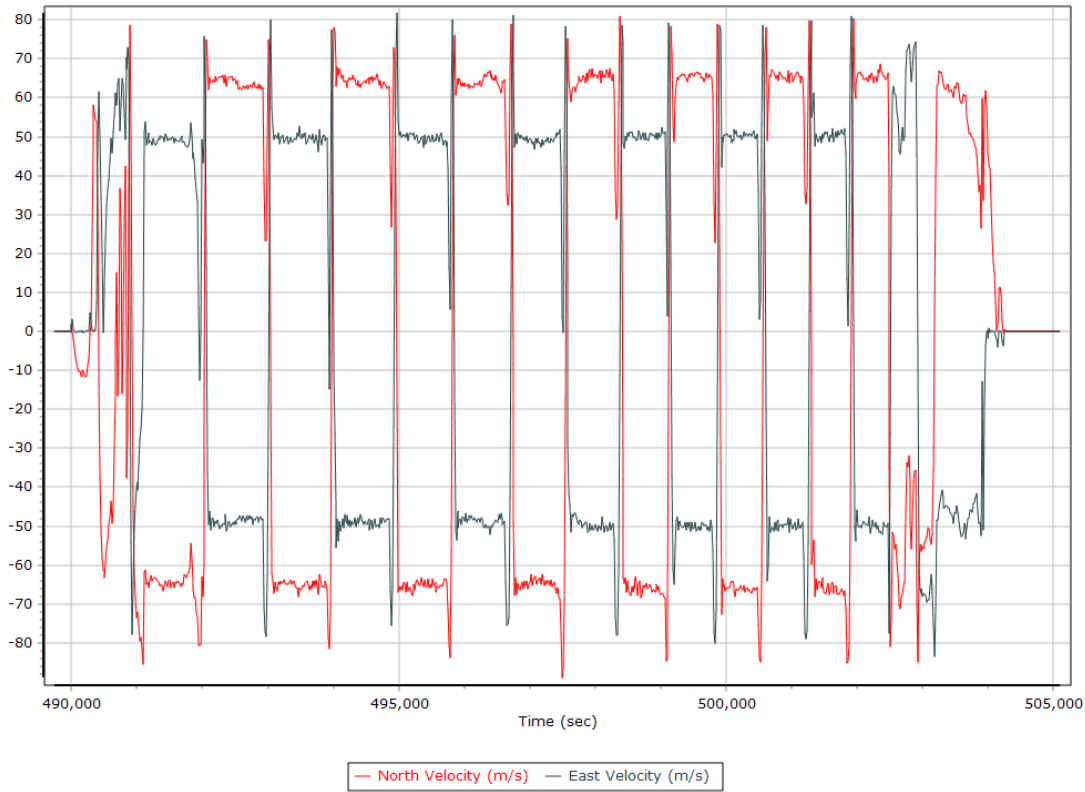
Roll/Pitch



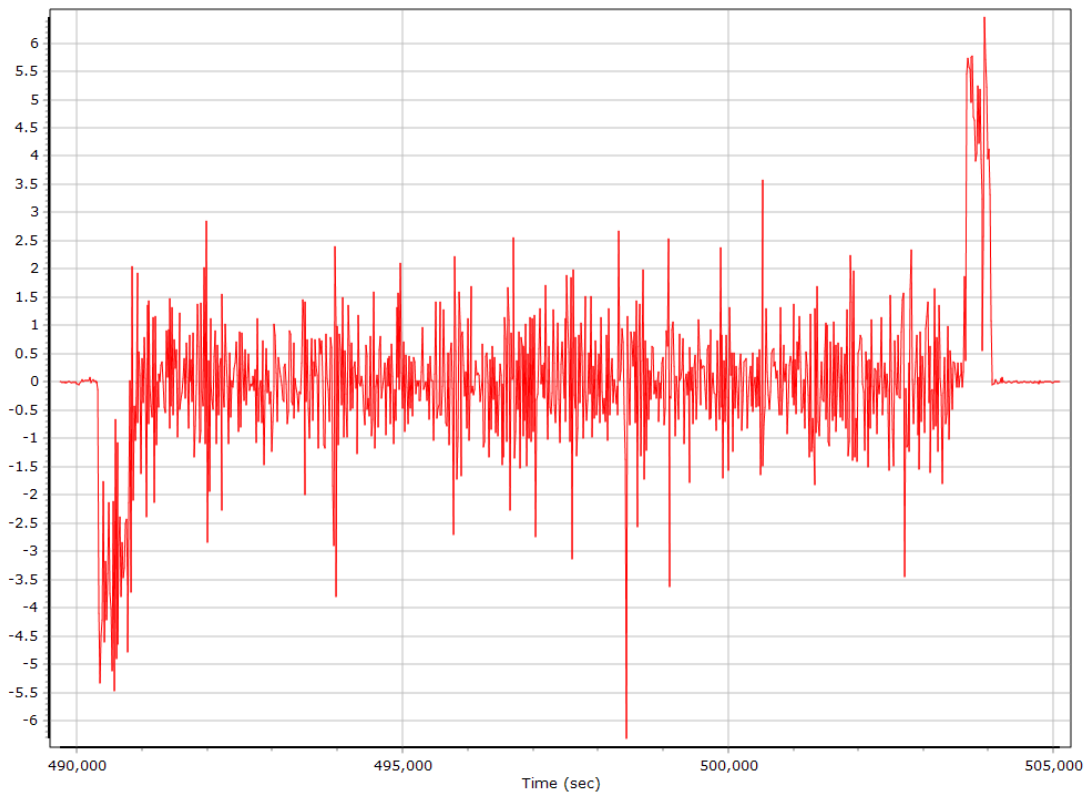
Heading



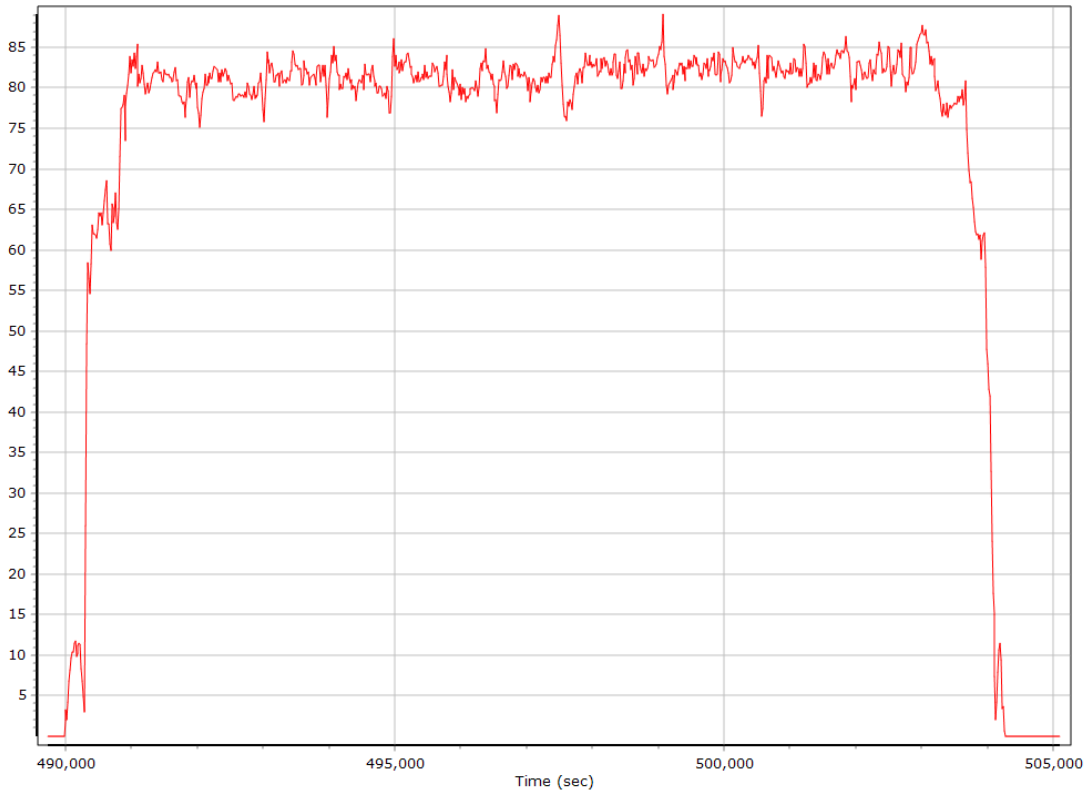
North/East Velocity



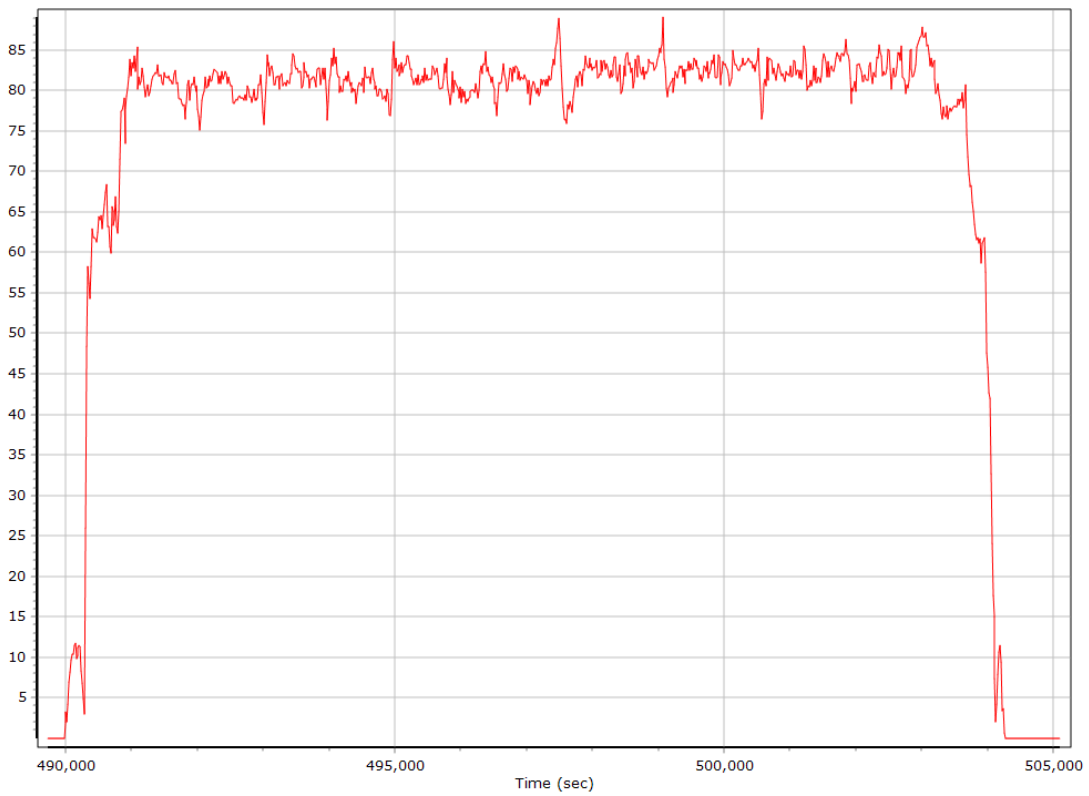
Down Velocity



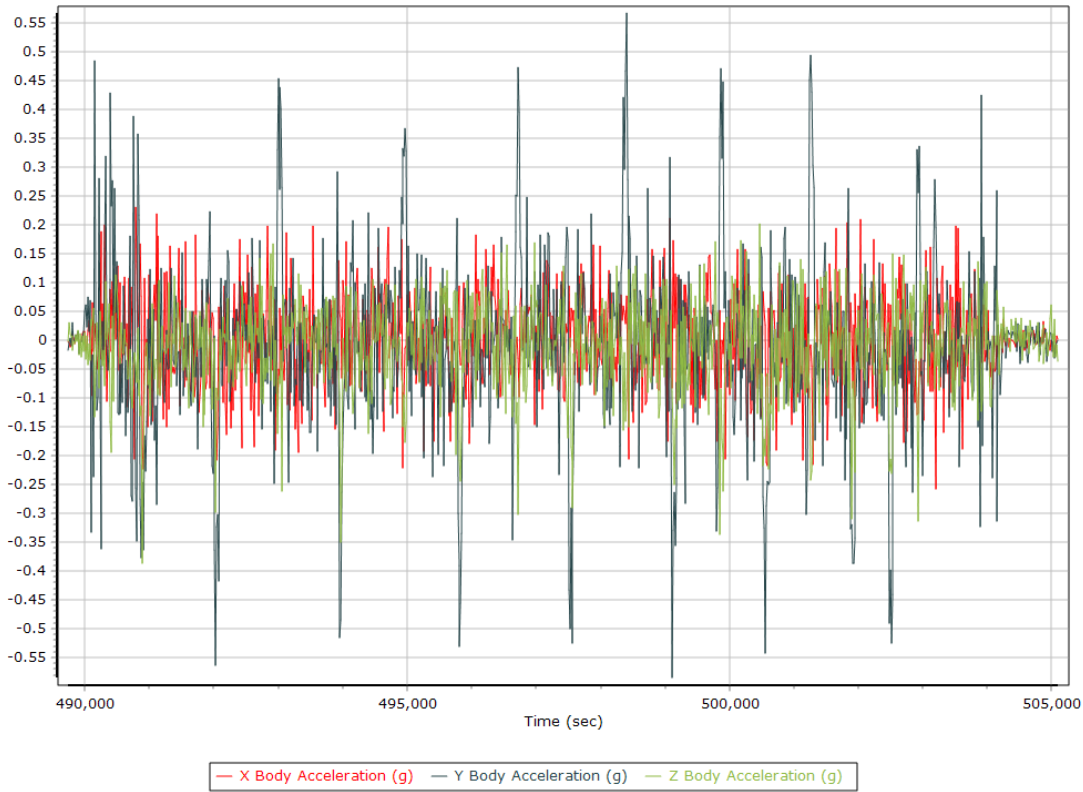
Total Speed



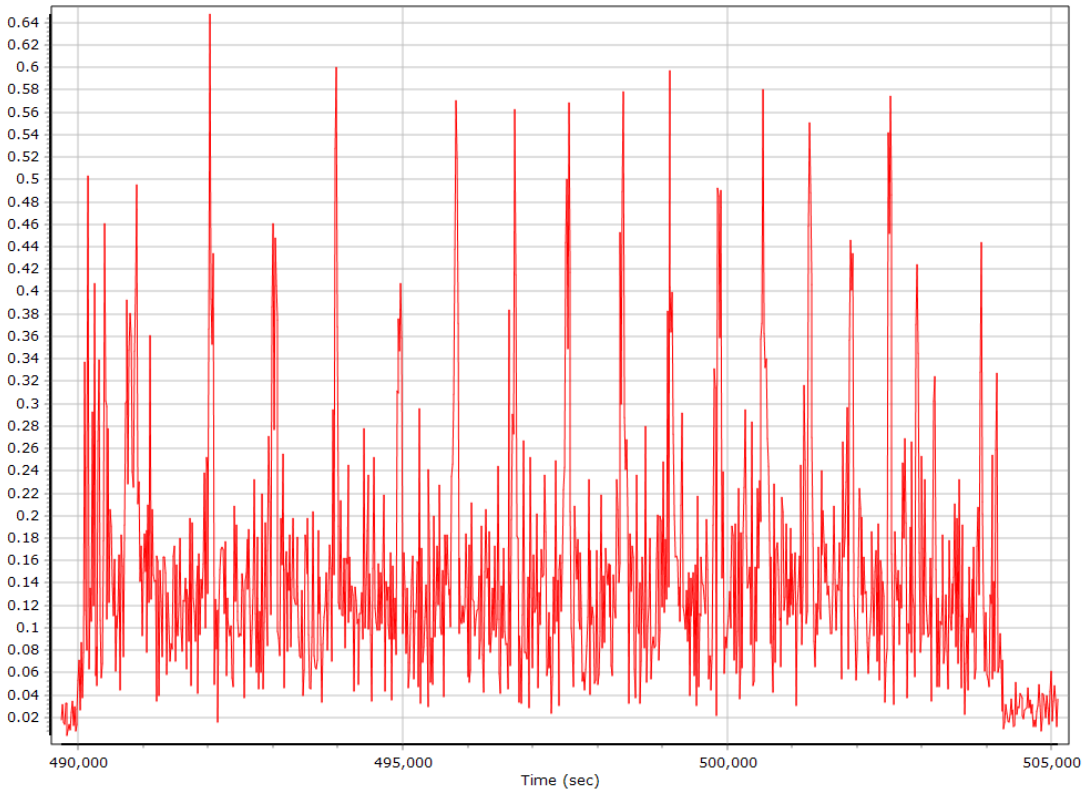
Ground Speed



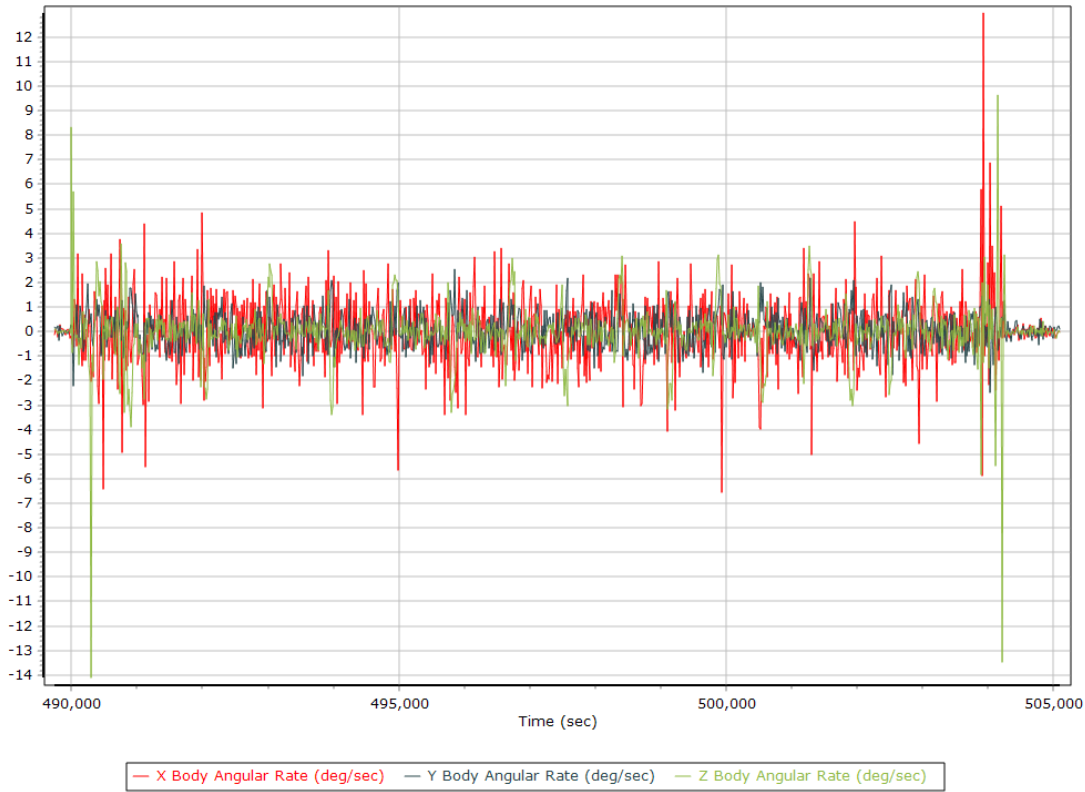
Body Acceleration



Total Body Acceleration



Body Angular Rate



Base Station Information

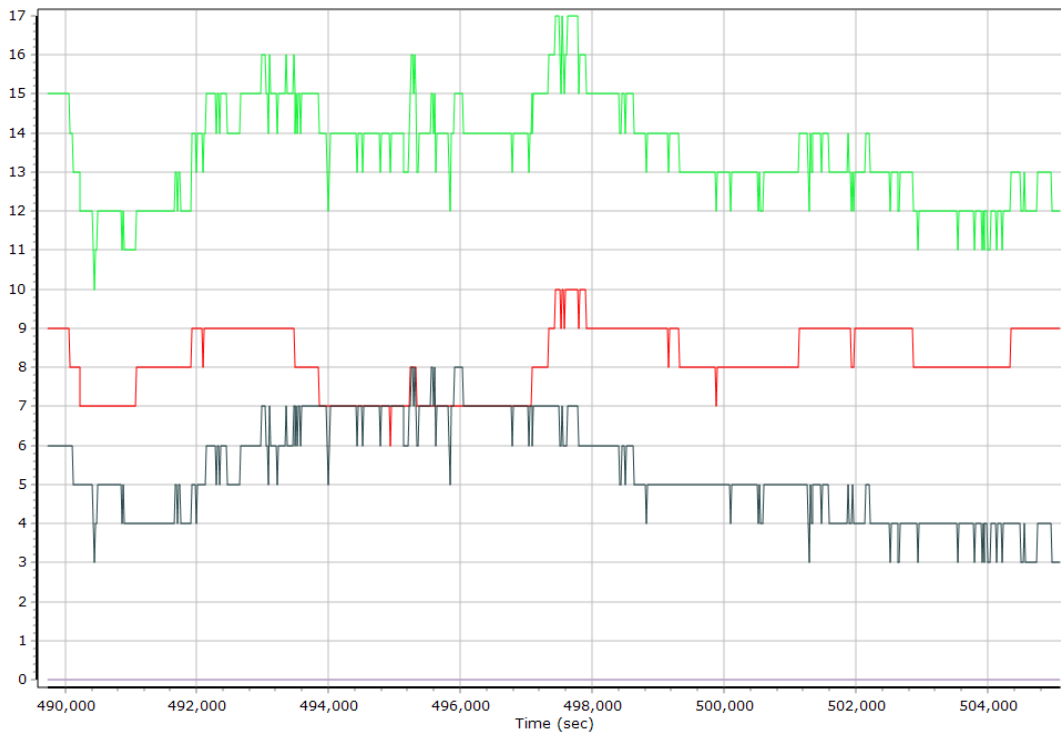
Station ID	DHLG Durmid Hill		
Filename	dhlg3300.21o		
Start date	11/26/2021 00:00:00		
End date	11/26/2021 23:59:59		
Duration	23:59:59.000		
Data type	GNSS		
Receiver manufacturer, model, serial no.	Topcon	NET-G3A	618-01037
Antenna manufacturer, model	Topcon	TPS CR.G3 w/SCIS	
Antenna height [m]	0.122		
Antenna measurement method	Bottom of antenna mount		
Offset from measured point to APC [m]	0.08417		
Latitude	N33°23'23.28790"		
Longitude	W115°47'16.85576"		
Ellipsoidal height [m]	-82.15100		
Frame	NAD83_2011		
Epoch	2010		
Ellipsoid	GRS_1980		
Velocity North [mm/y]	36.2		
Velocity East [mm/y]	-29.88		
Velocity Up [mm/y]	-1.08		

GNSS QC

GNSS QC Statistics

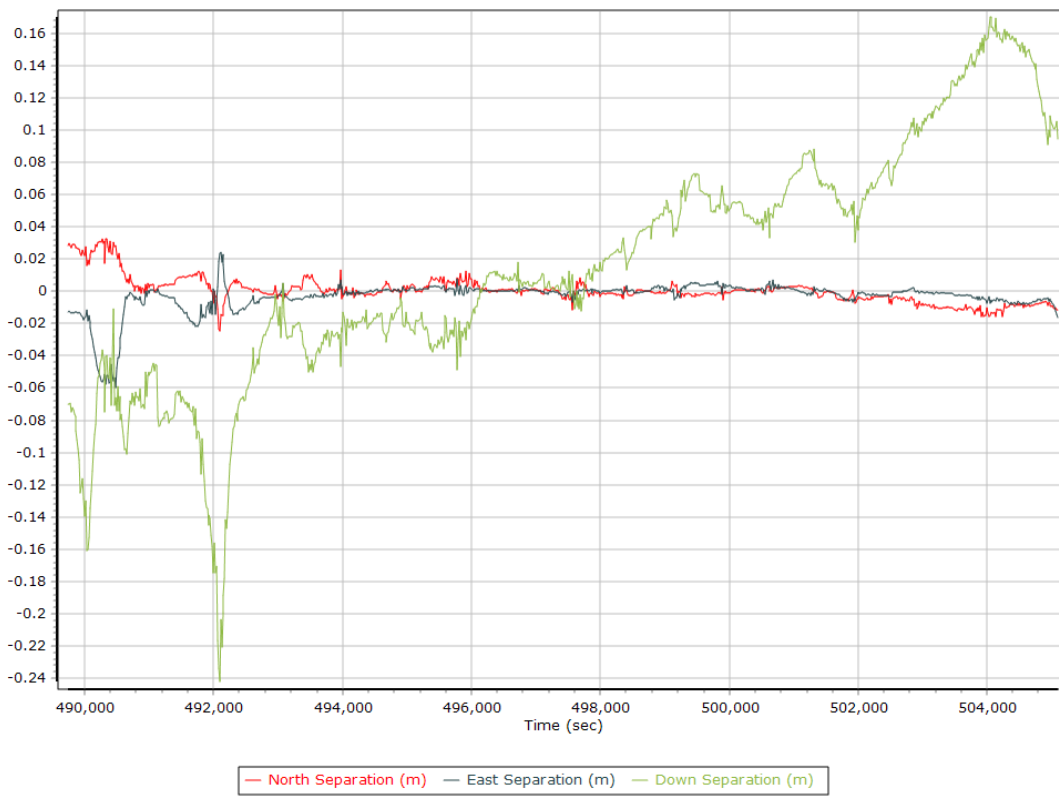
Statistics	Min	Max	Mean
Baseline length [km]	1.72	57.57	
Number of GPS SV	6	10	8
Number of GLONASS SV	0	8	5
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	0	0
Total number of SV	6	17	14
PDOP	1.25	3.91	1.57
QC Solution Gaps	0.00	0.00	
Solution Type	Fixed	Float	No solution
Epoch (s)	15757.00	0.00	0.00
Percentage	100.00	0.00	0.00

Num SVs in solution

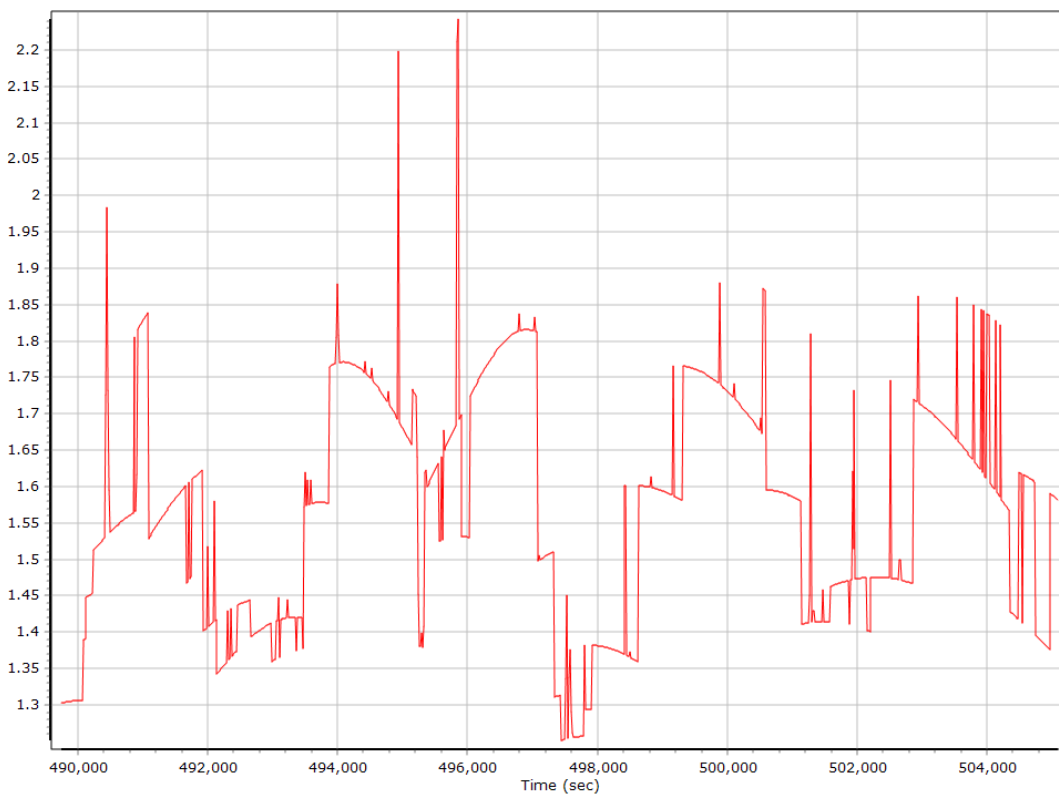


— Number of GPS — Number of GLONASS — Number of QZSS — Number of BEIDOU — Total Number

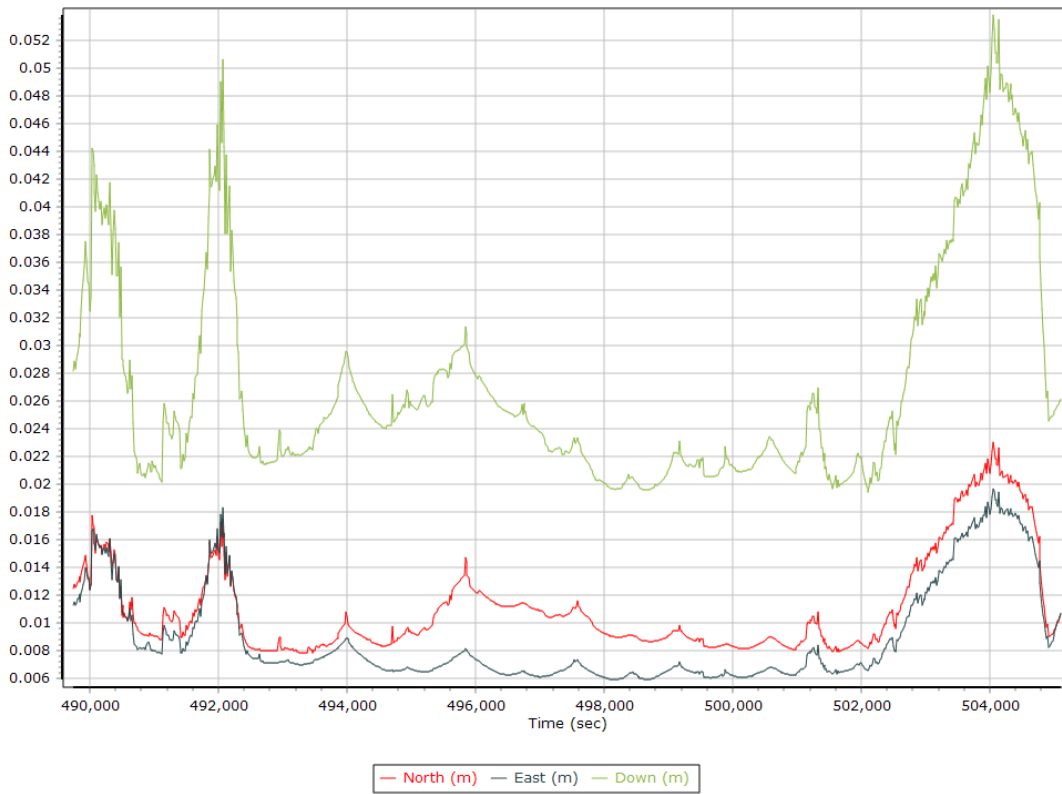
Forward/Reverse Separation



PDOP



Estimated Position Accuracy



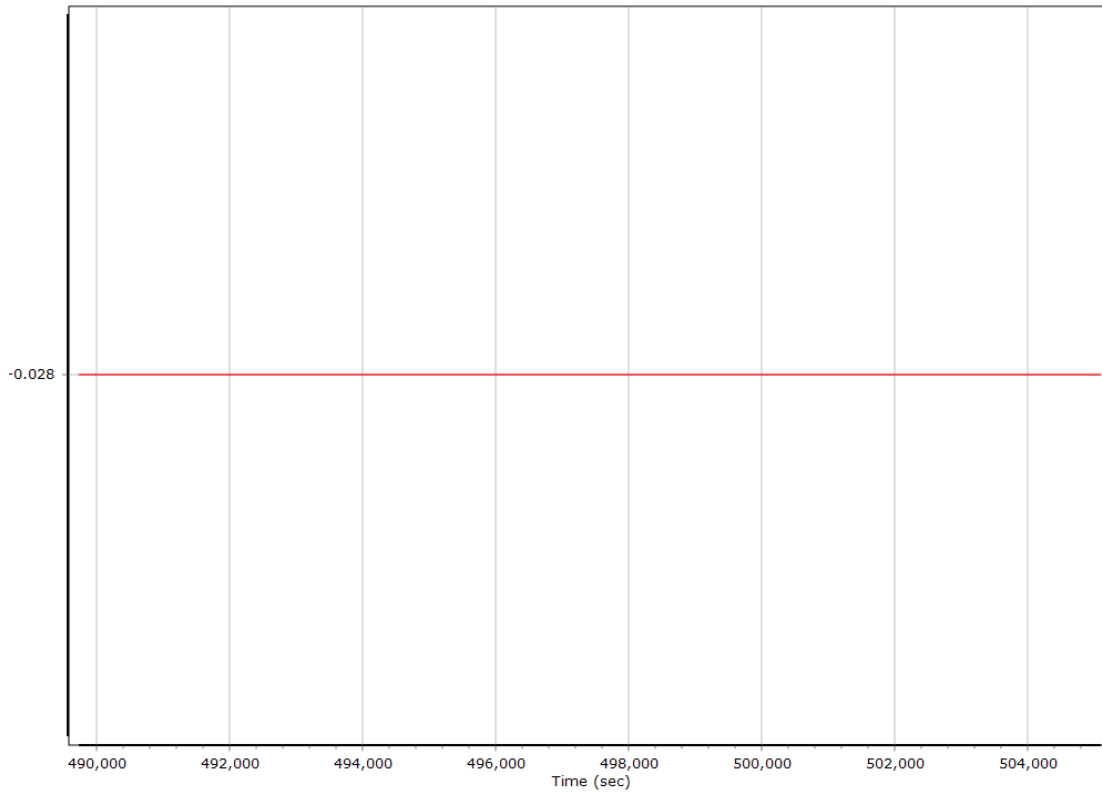
GNSS-Inertial Processor Configuration

Processing mode	IN-Fusion Single Base		
Stabilized mount	False		
Base station	DHLG Durmid Hill		
Processing start time	489330.000 (11/26/2021 15:55:30)		
Processing end time	505106.000 (11/26/2021 20:18:26)		
Initial attitude source	Real-Time VNAV/RNAV Attitude		
IMU Sensor Context	Processing with Onboard IMU		
Reference to IMU lever arm [m]	0.000	0.000	0.000
Reference to IMU mounting angles [deg]	0.000	0.000	0.000
Reference to Primary GNSS lever arm [m]	-0.028	-0.054	-0.948
Reference to Primary GNSS lever arm std dev [m]	0.030	0.030	0.030
Aircraft to Reference mounting angles [deg]	0.000	0.000	0.000

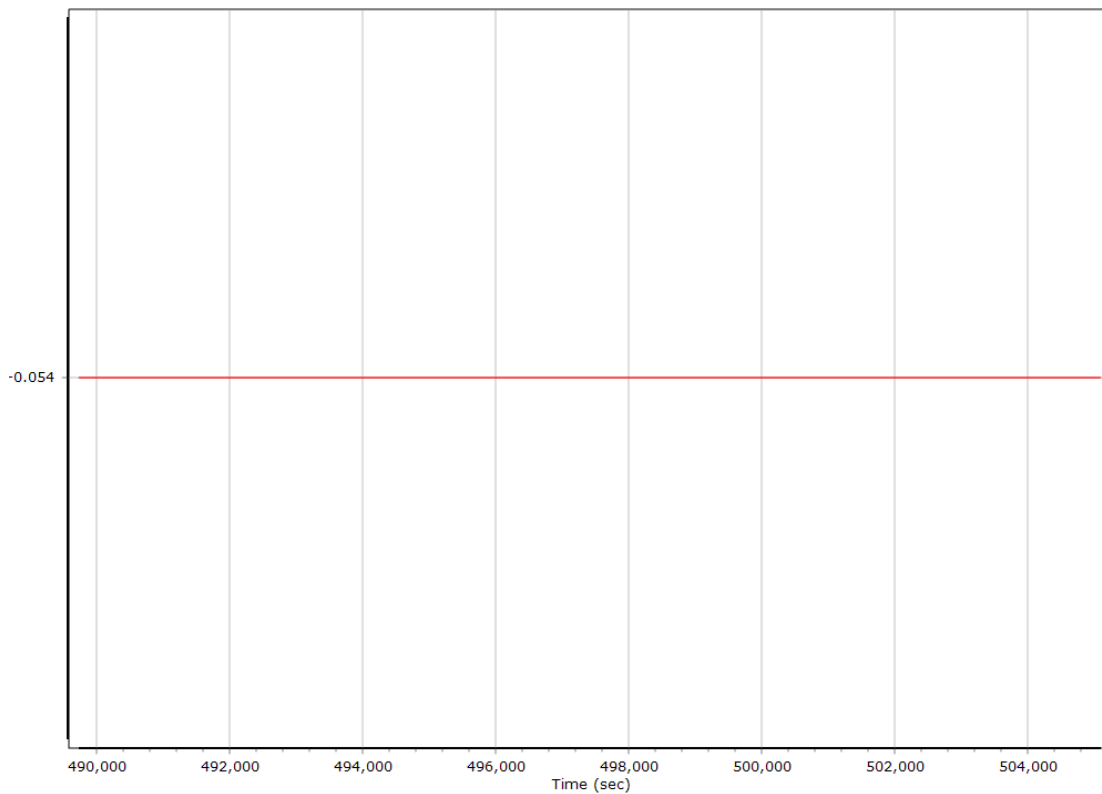
Calibrated Installation Parameters

Reference-Primary GNSS Lever Arm

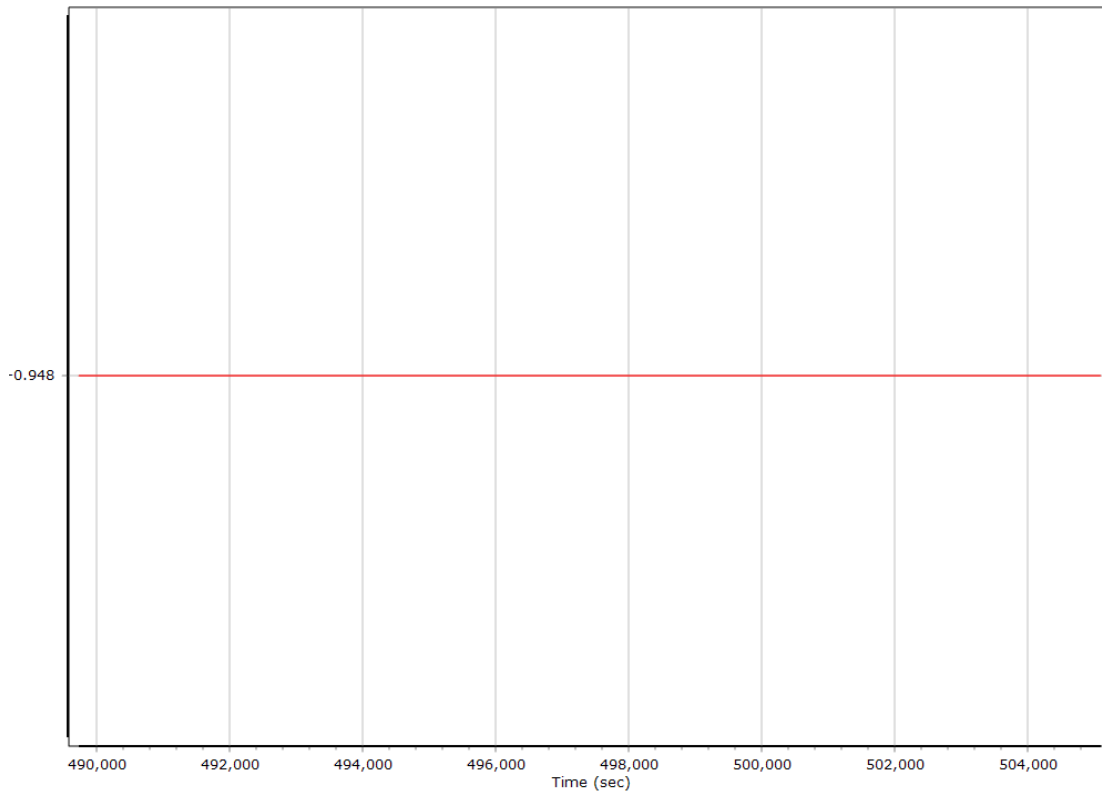
X Reference-Primary GNSS Lever Arm (m)



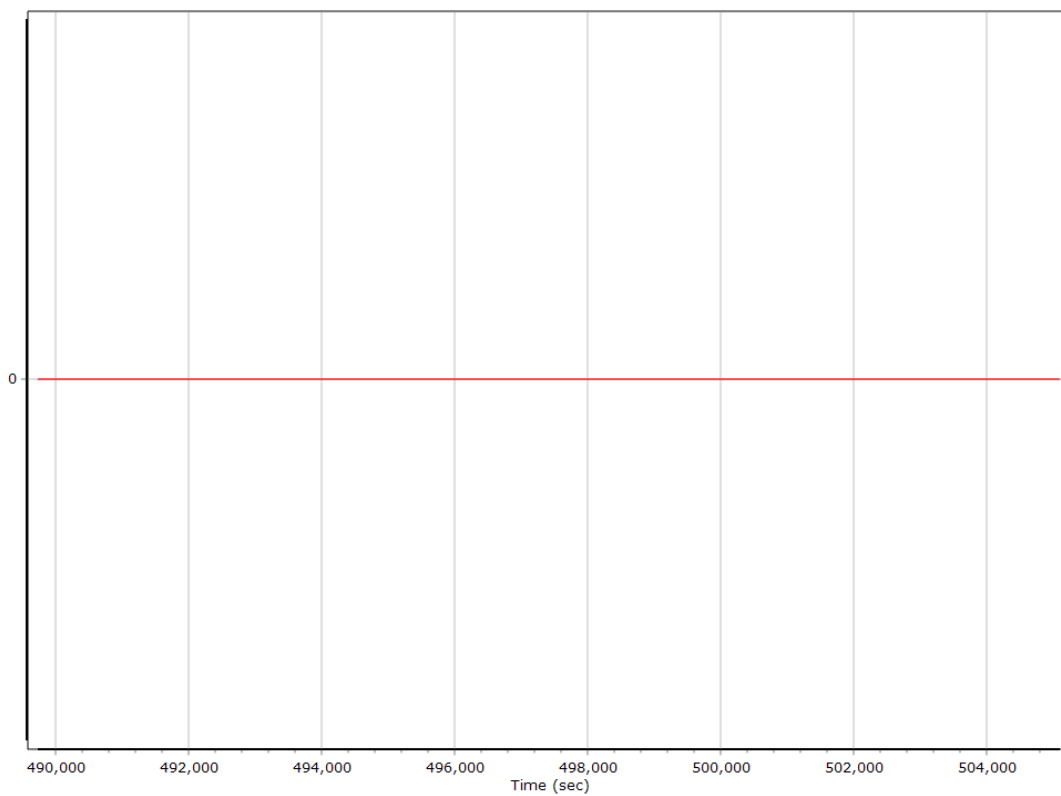
Y Reference-Primary GNSS Lever Arm (m)



Z Reference-Primary GNSS Lever Arm (m)



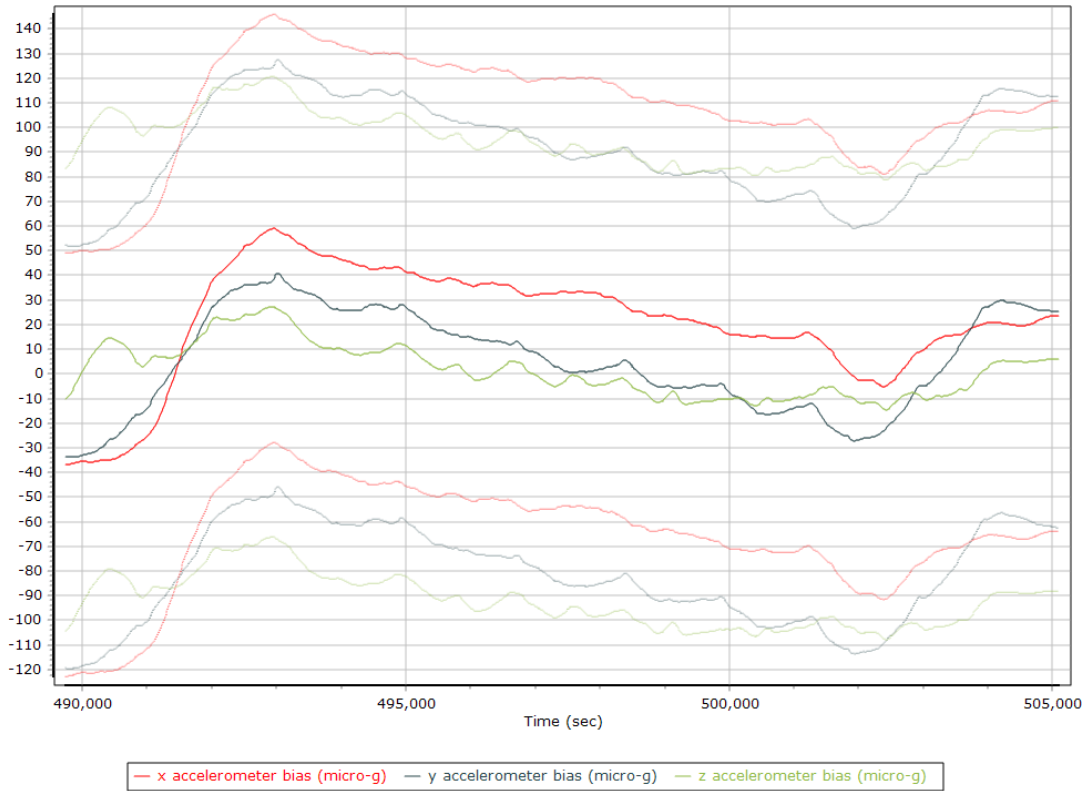
Reference-Primary GNSS Lever Arm Figure of Merit



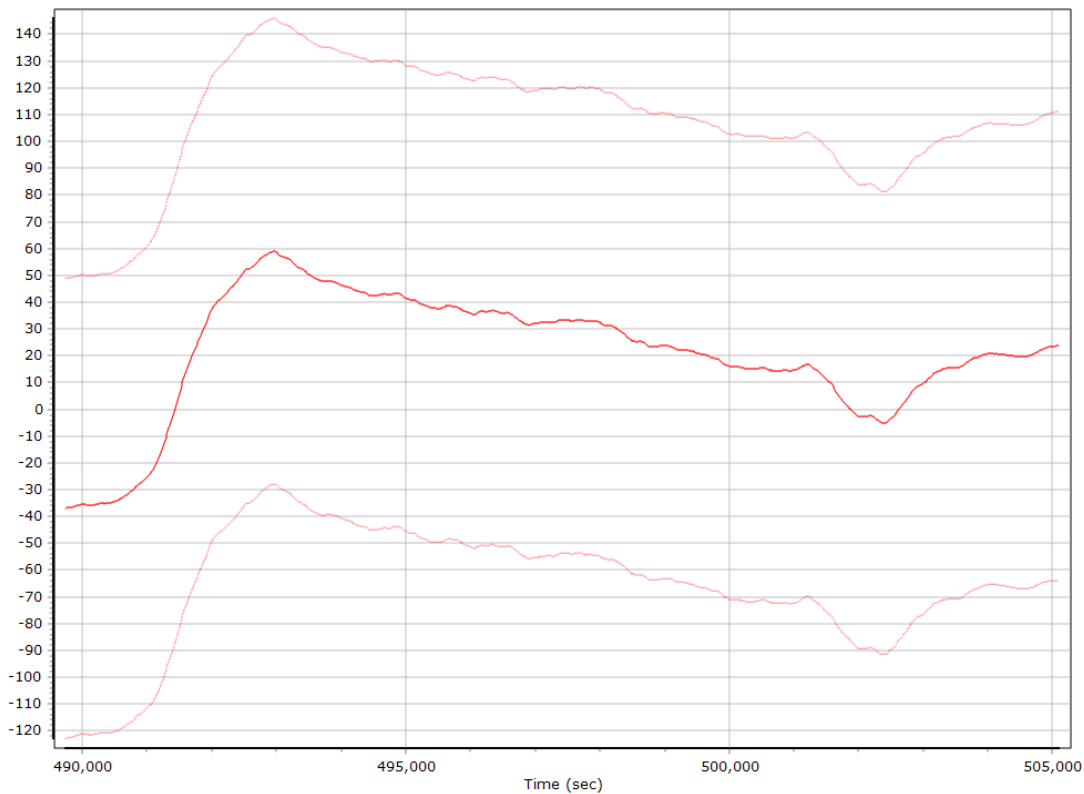
Smoothed IN-Fusion QC

Smoothed Estimated Errors, Reference Frame

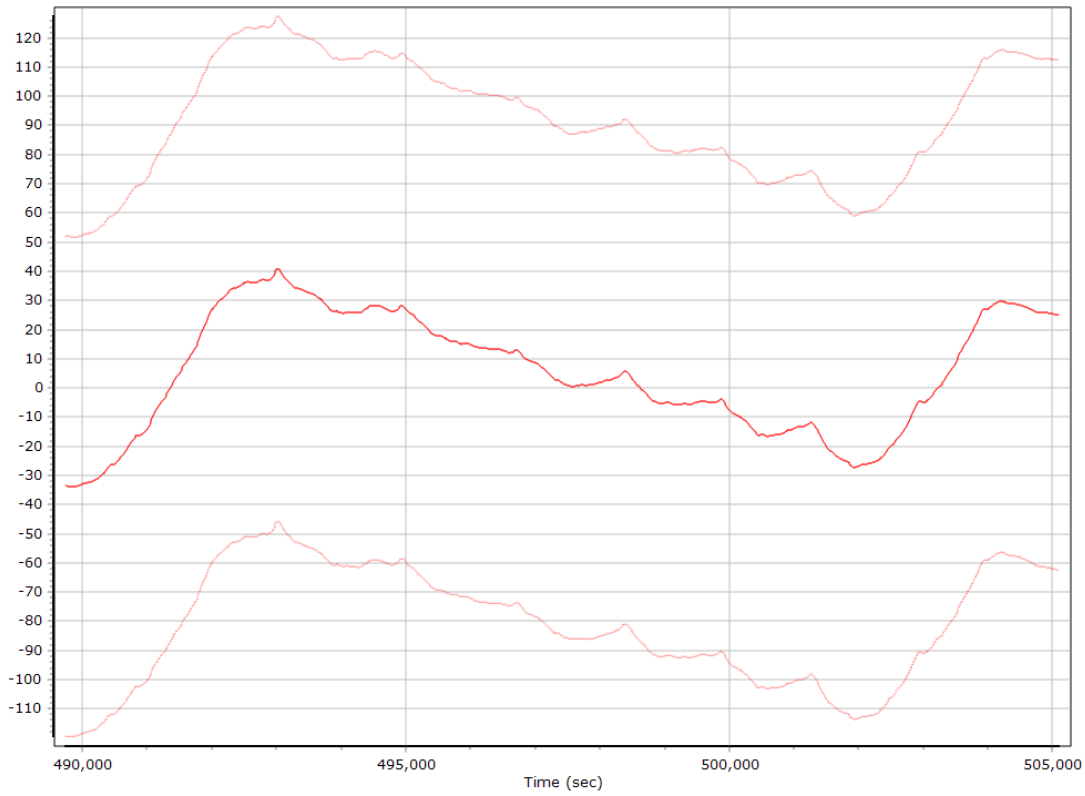
Accelerometer Bias (micro-g)



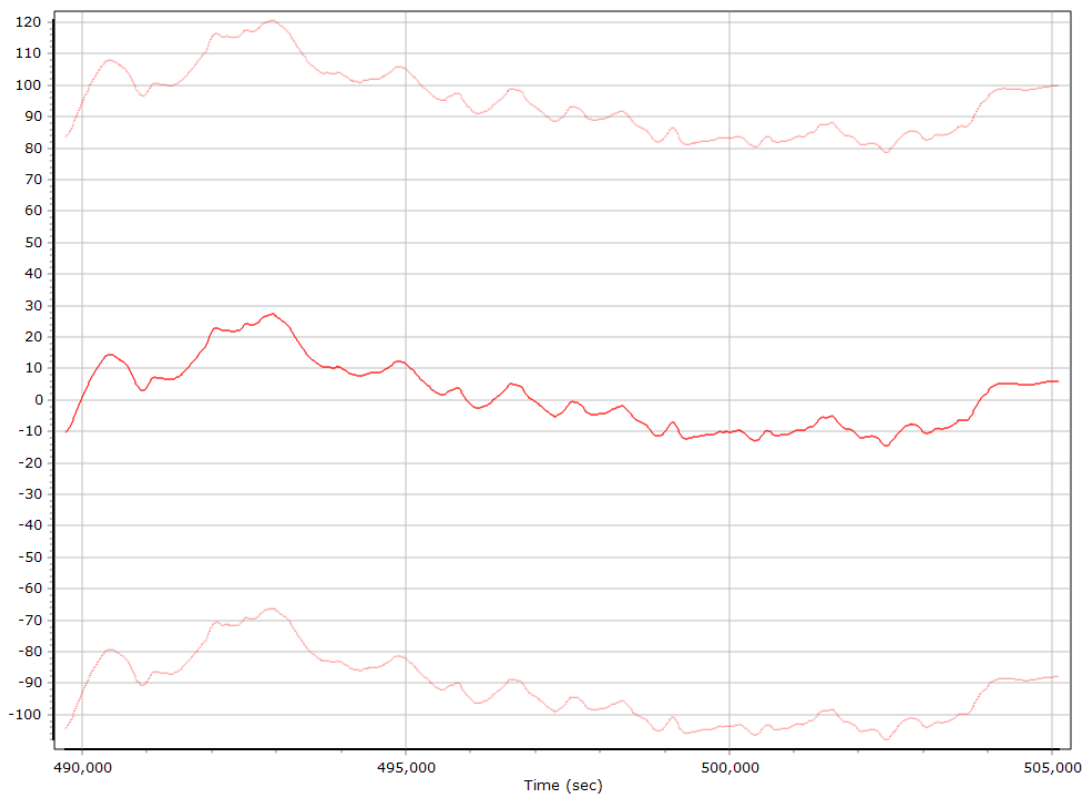
X Accelerometer Bias (micro-g)



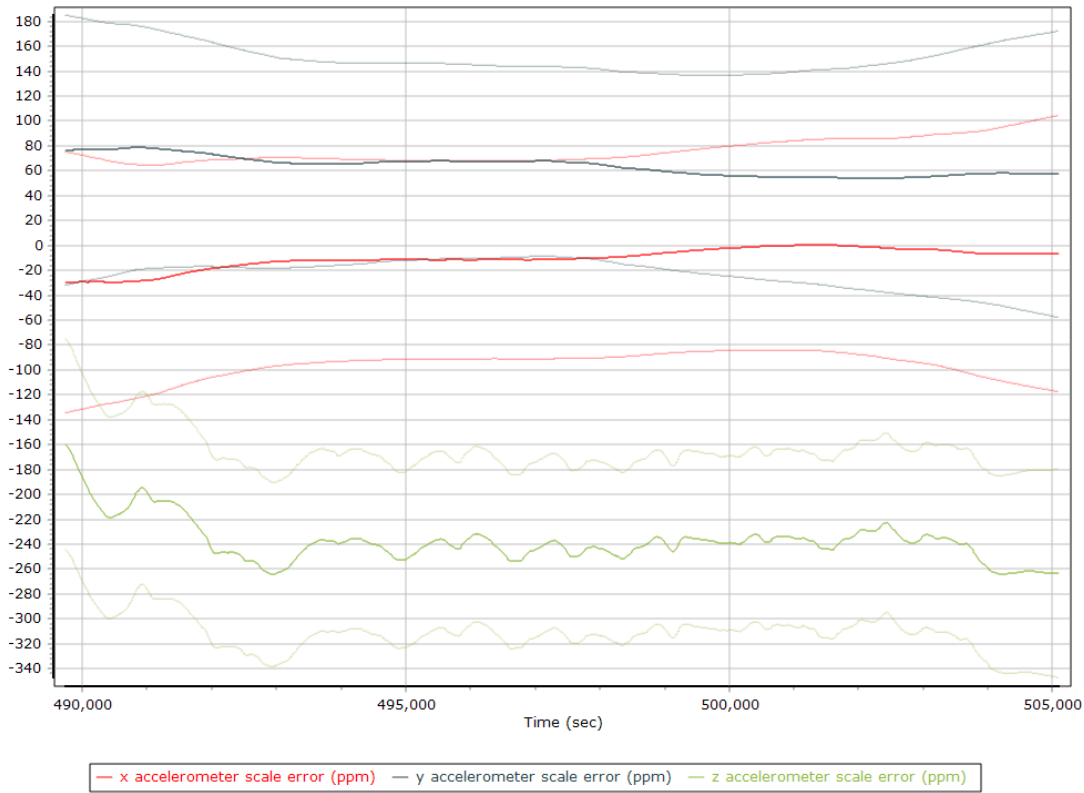
Y Accelerometer Bias (micro-g)



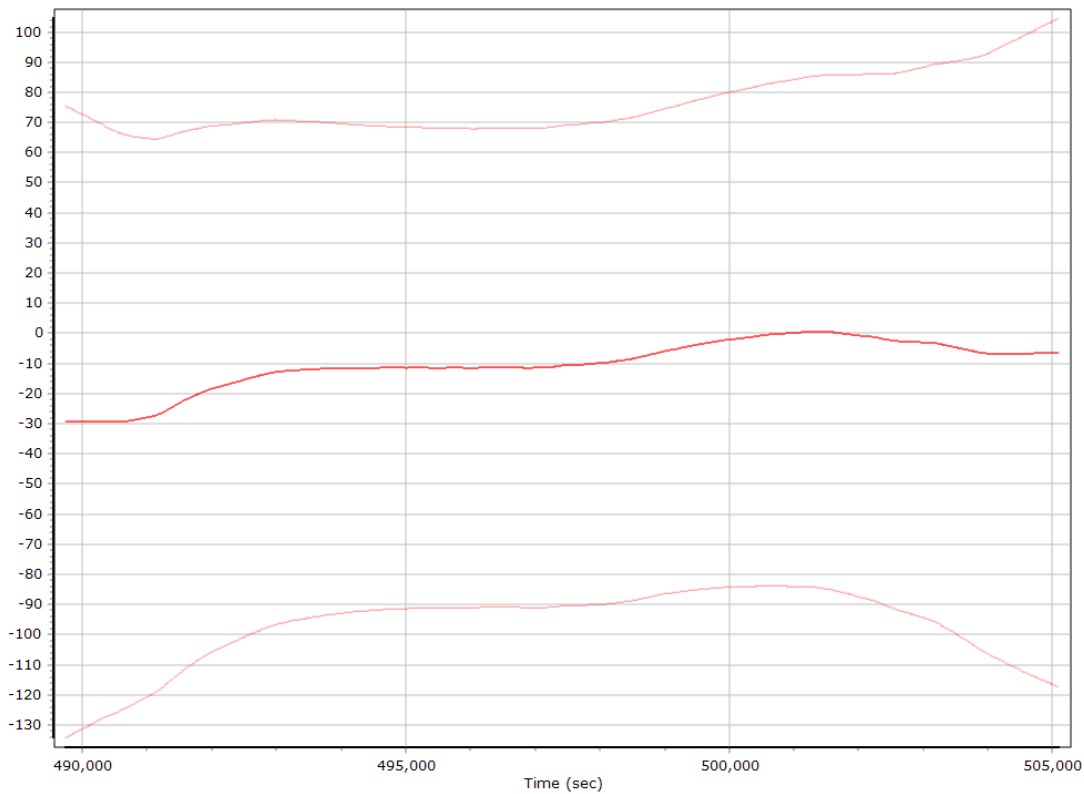
Z Accelerometer Bias (micro-g)



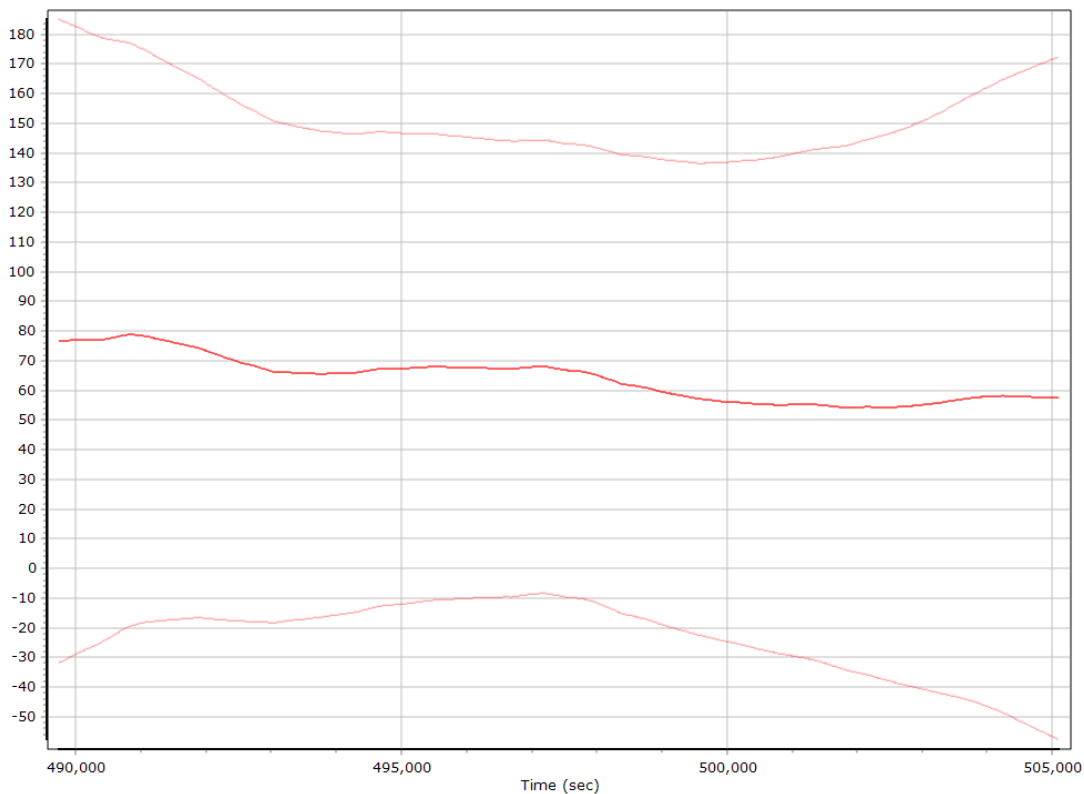
Accelerometer Scale Error (ppm)



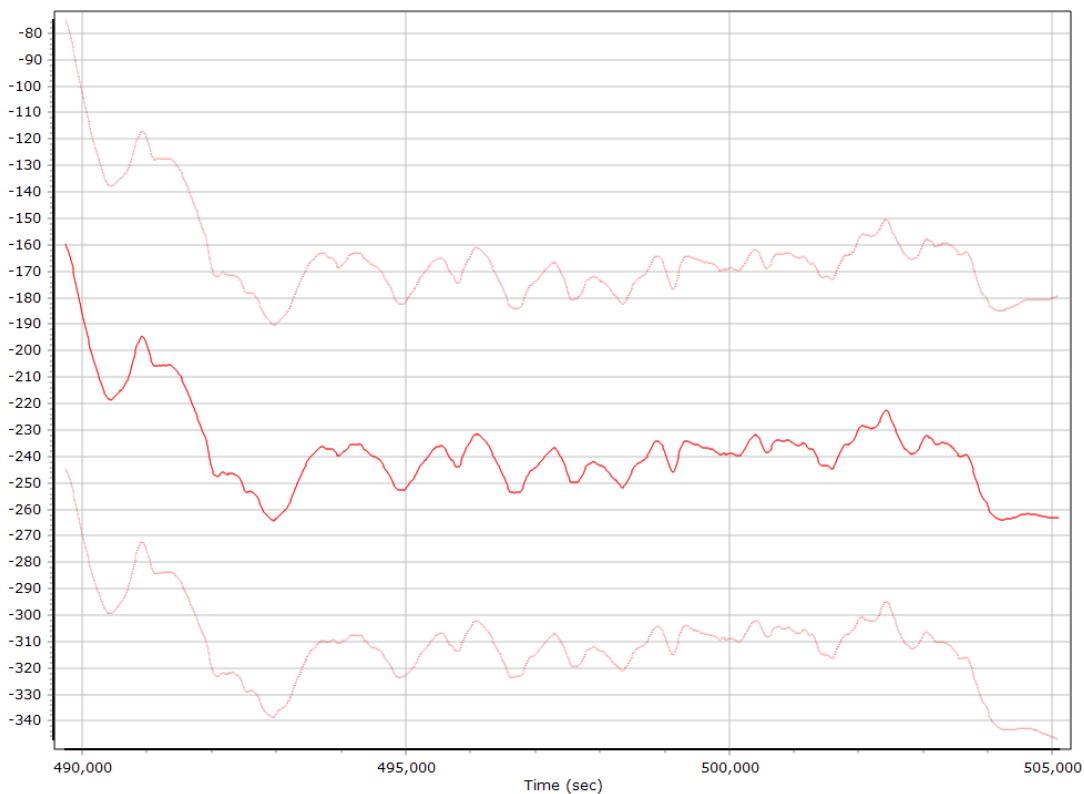
X Accelerometer Scale Error (ppm)



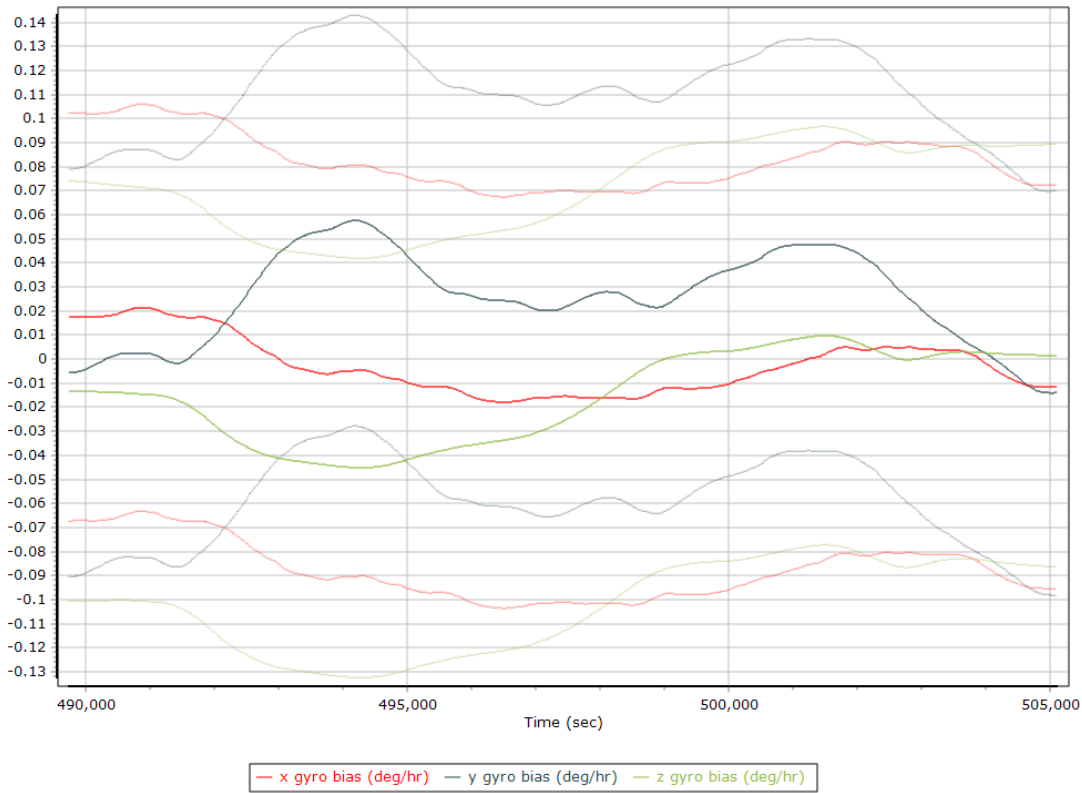
Y Accelerometer Scale Error (ppm)



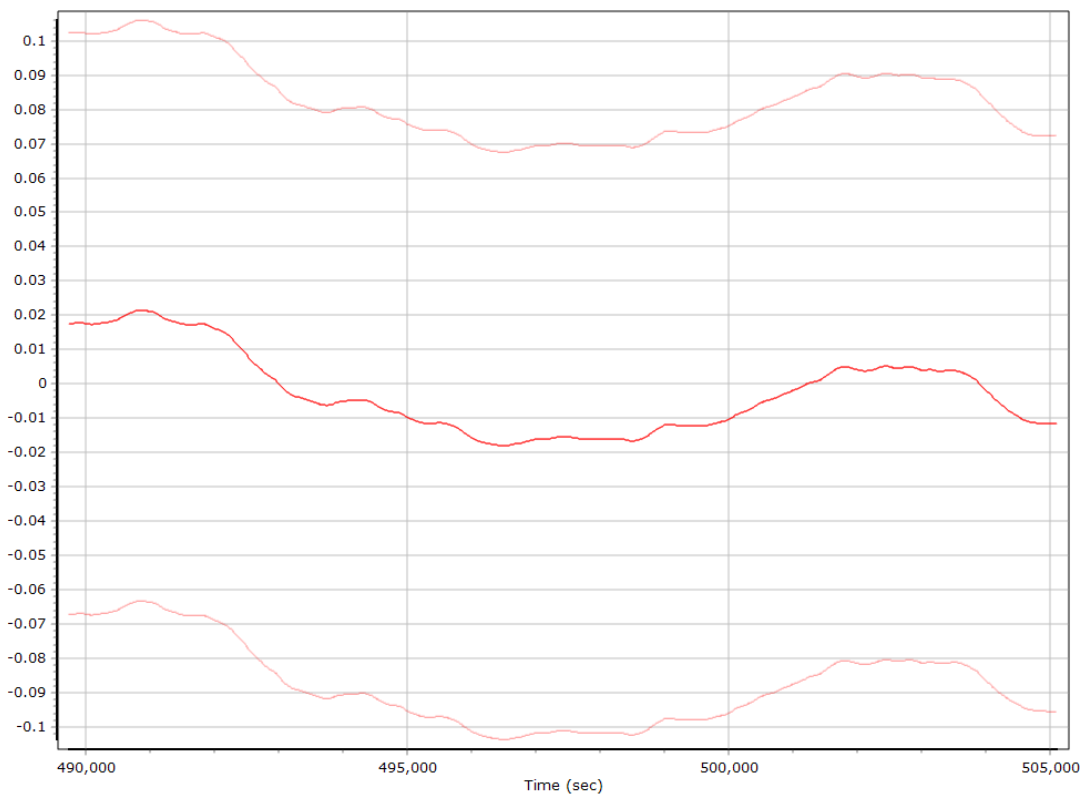
Z Accelerometer Scale Error (ppm)



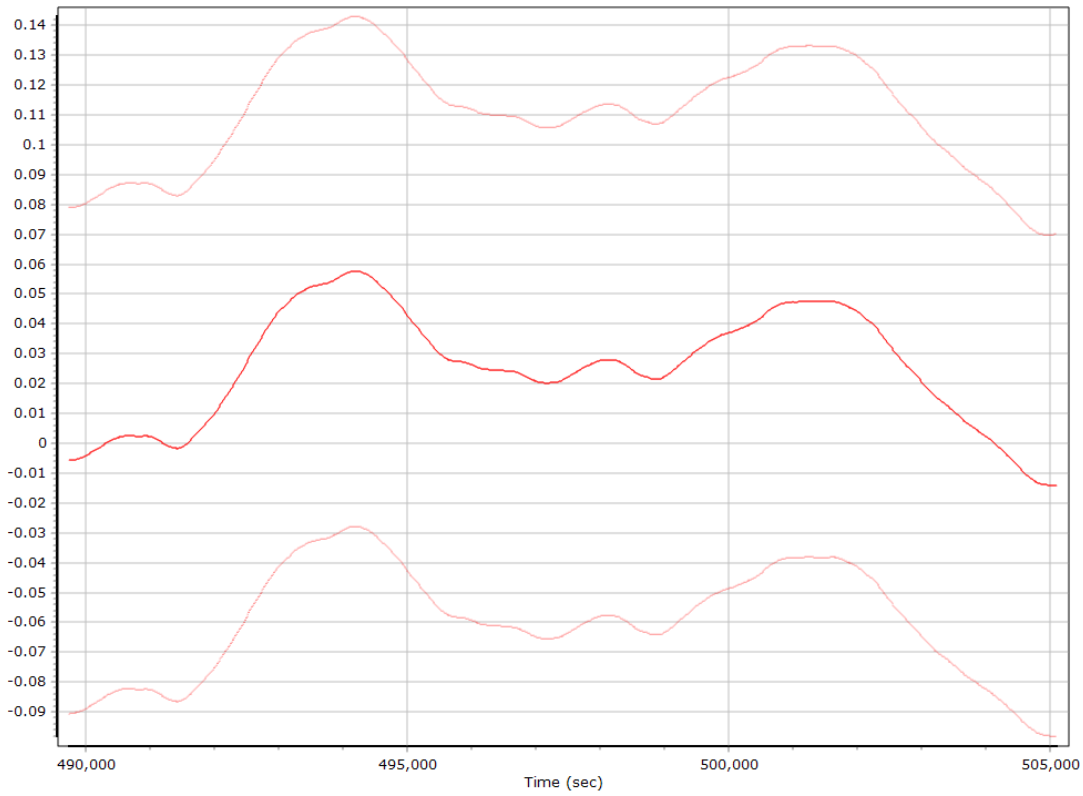
Gyro Bias (deg/h)



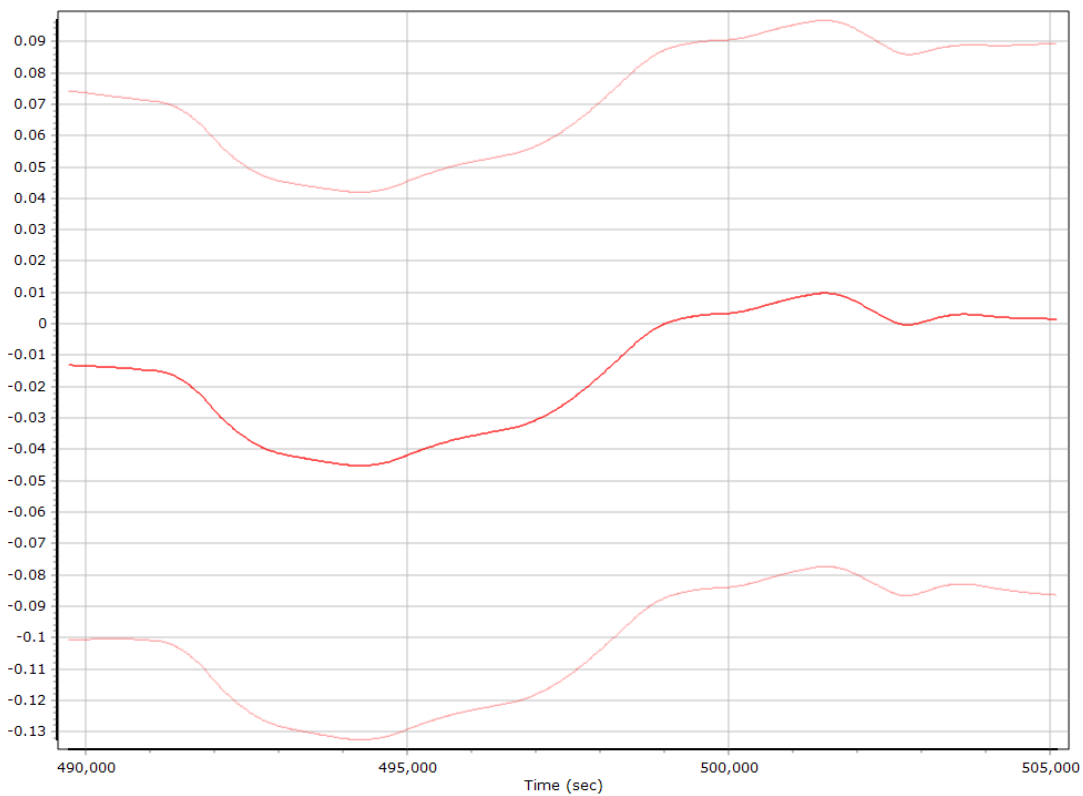
X Gyro Bias (deg/h)



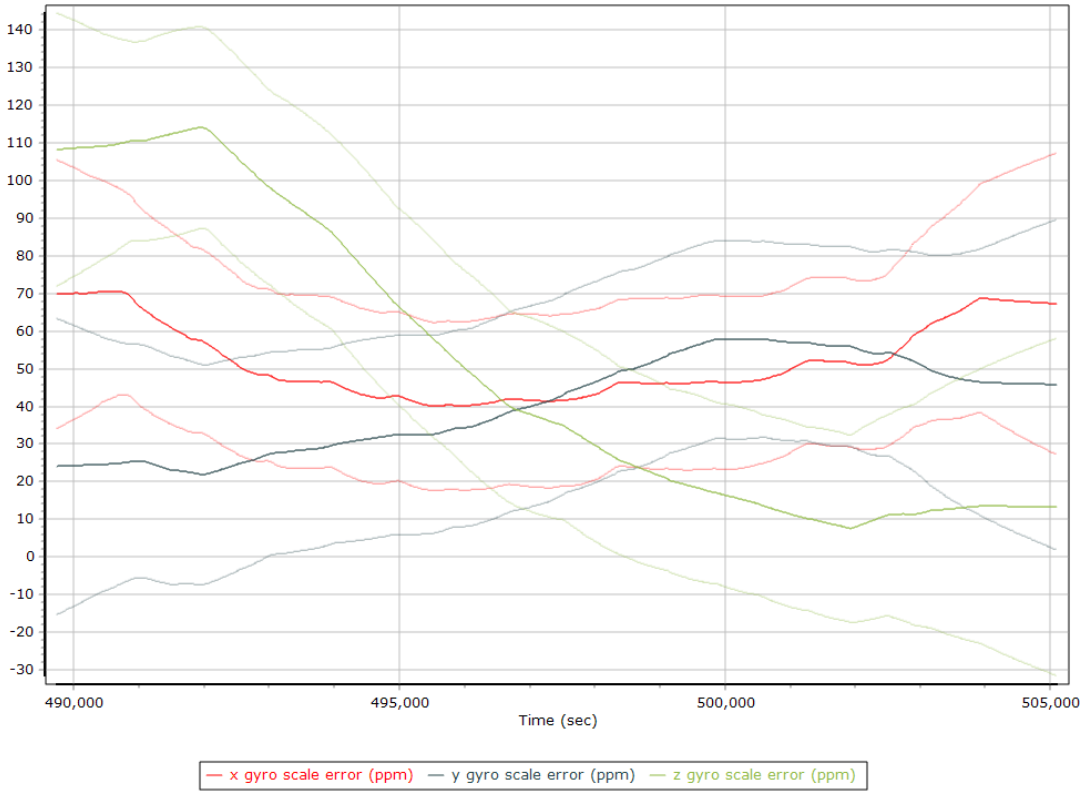
Y Gyro Bias (deg/h)



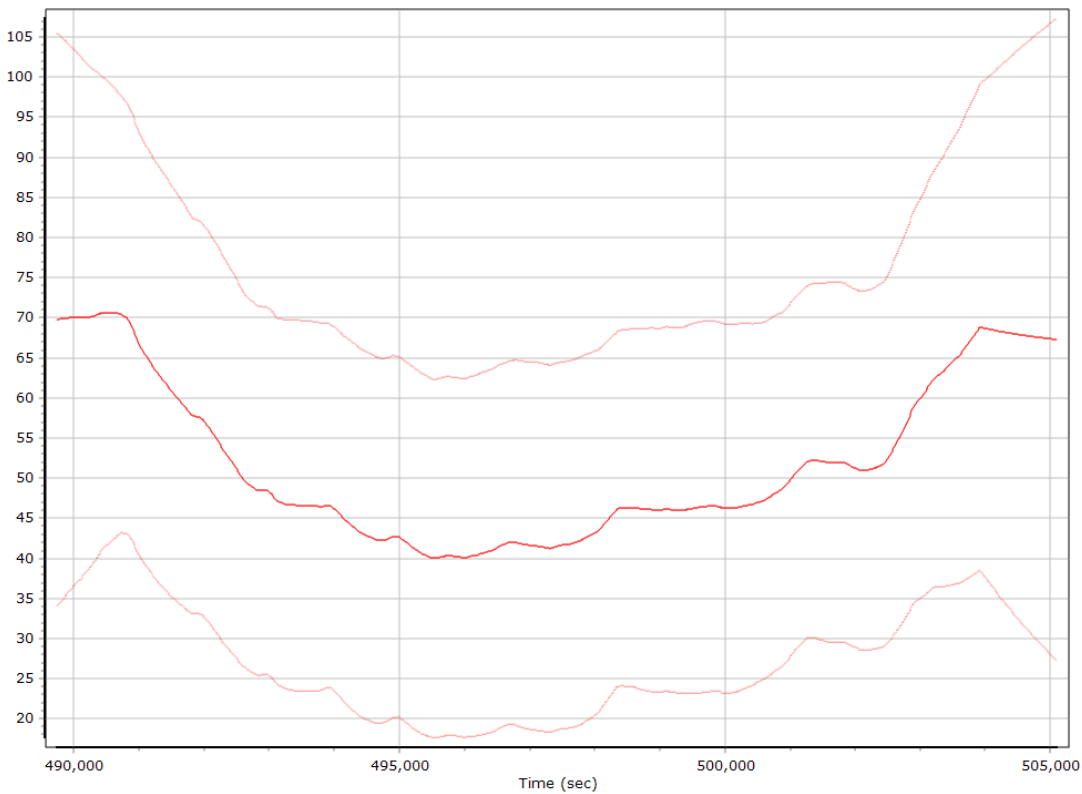
Z Gyro Bias (deg/h)



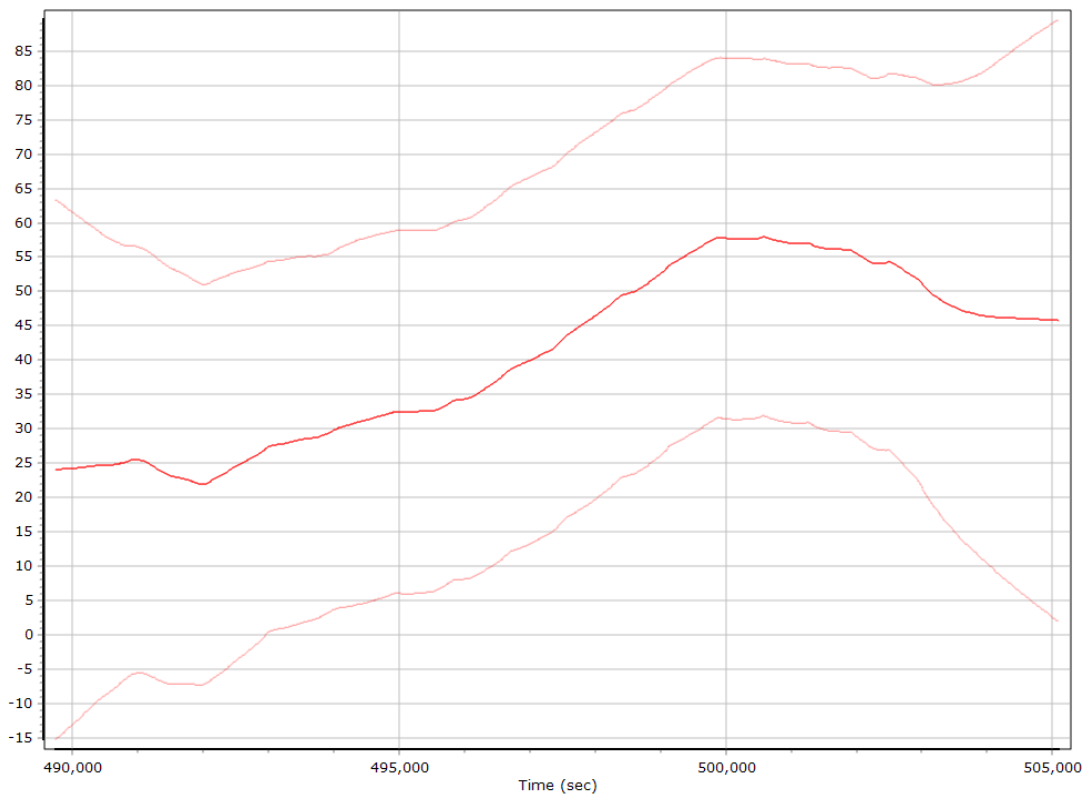
Gyro Scale Error (ppm)



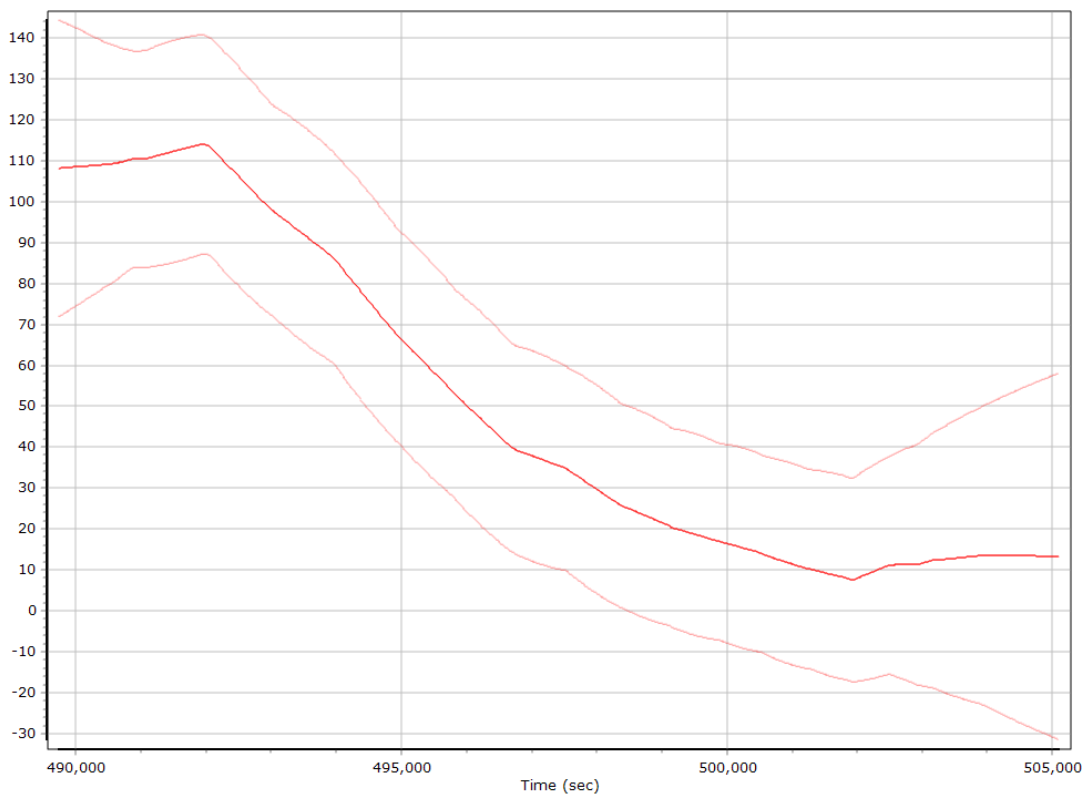
X Gyro Scale Error (ppm)



Y Gyro Scale Error (ppm)

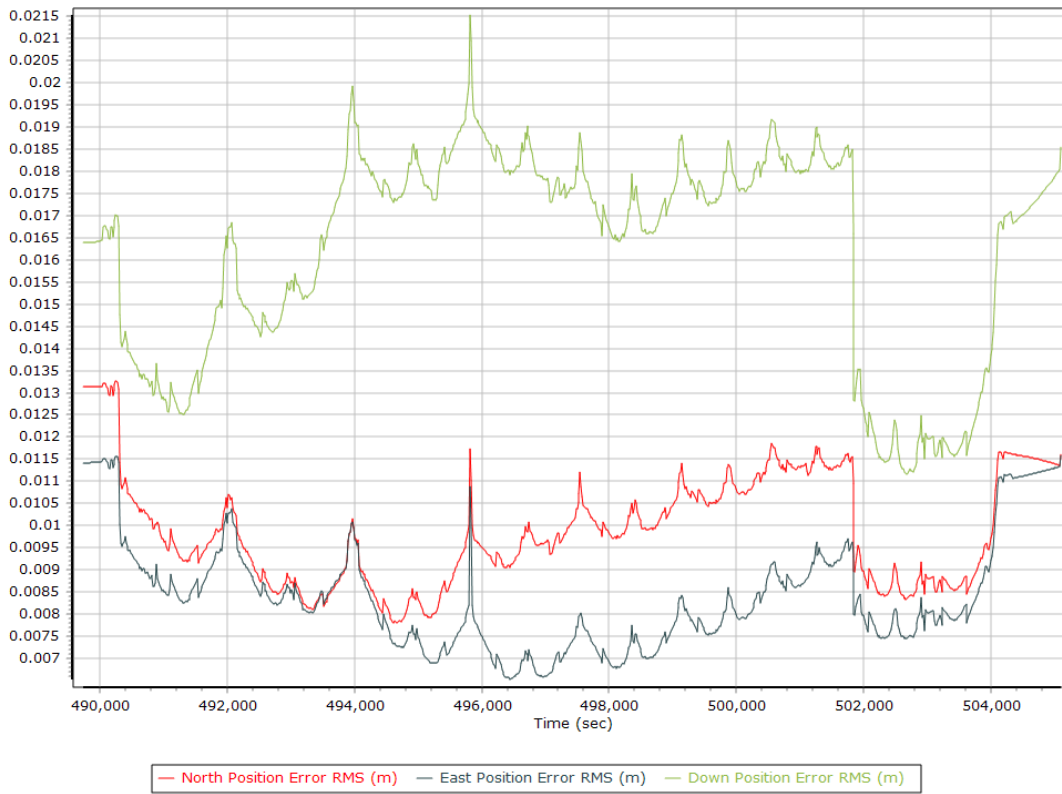


Z Gyro Scale Error (ppm)

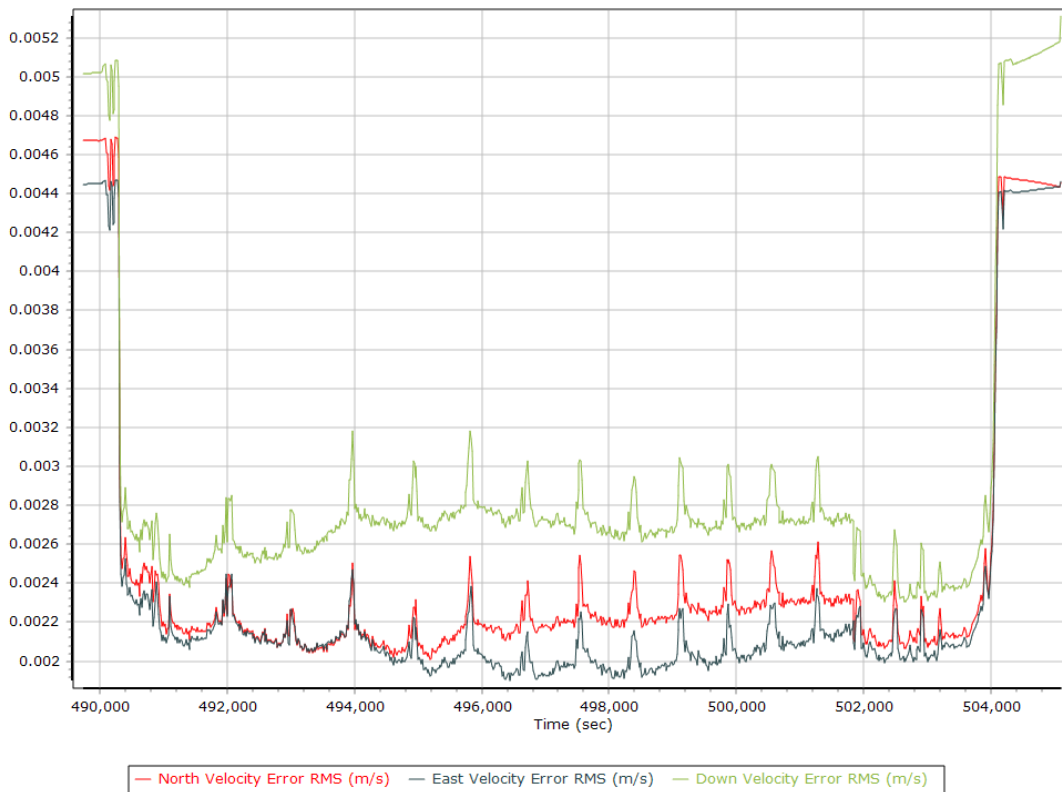


Smoothed Performance Metrics

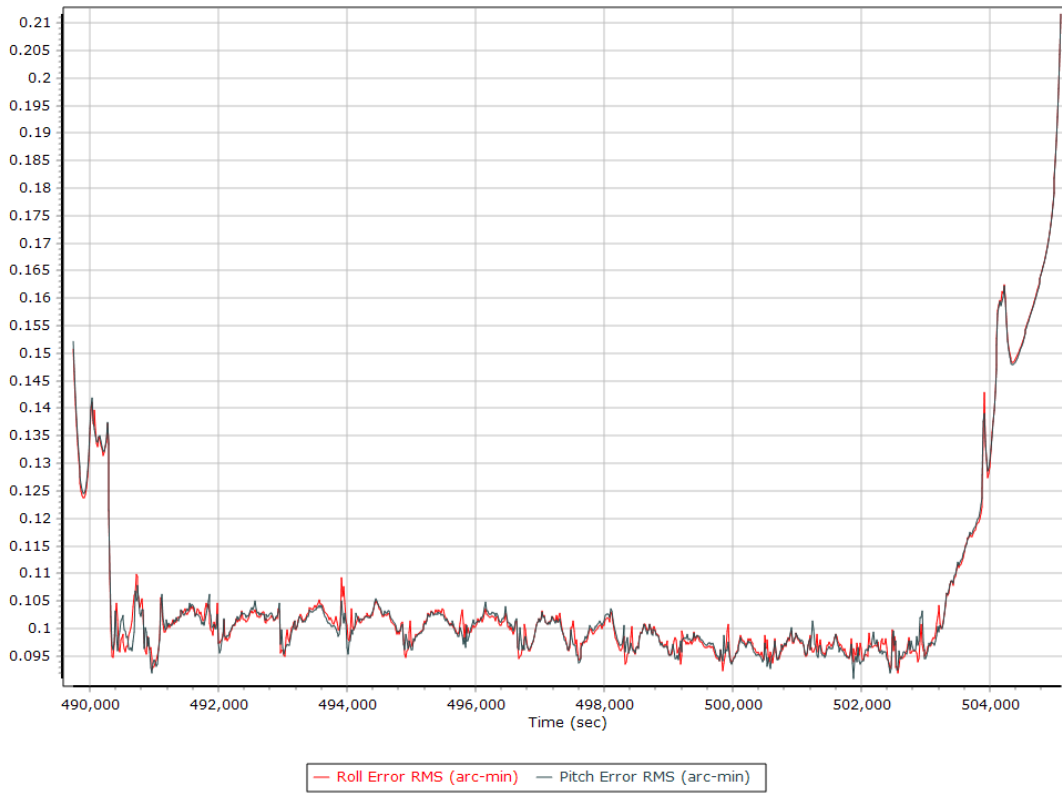
Position Error RMS (m)



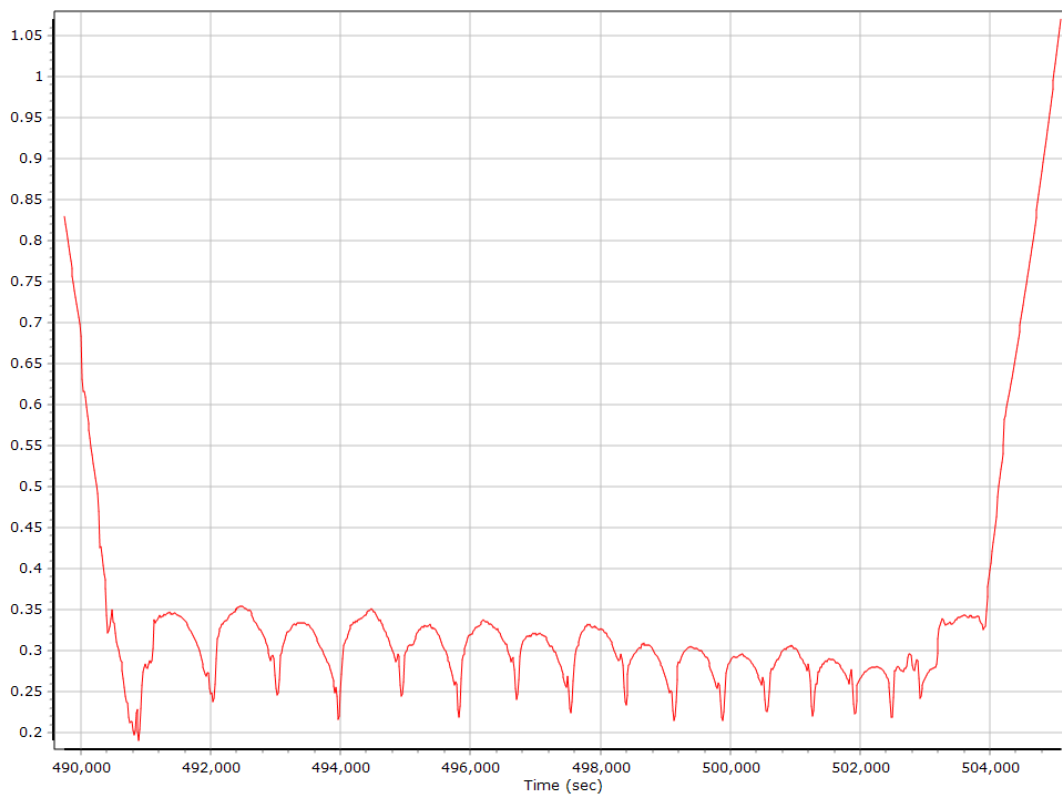
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

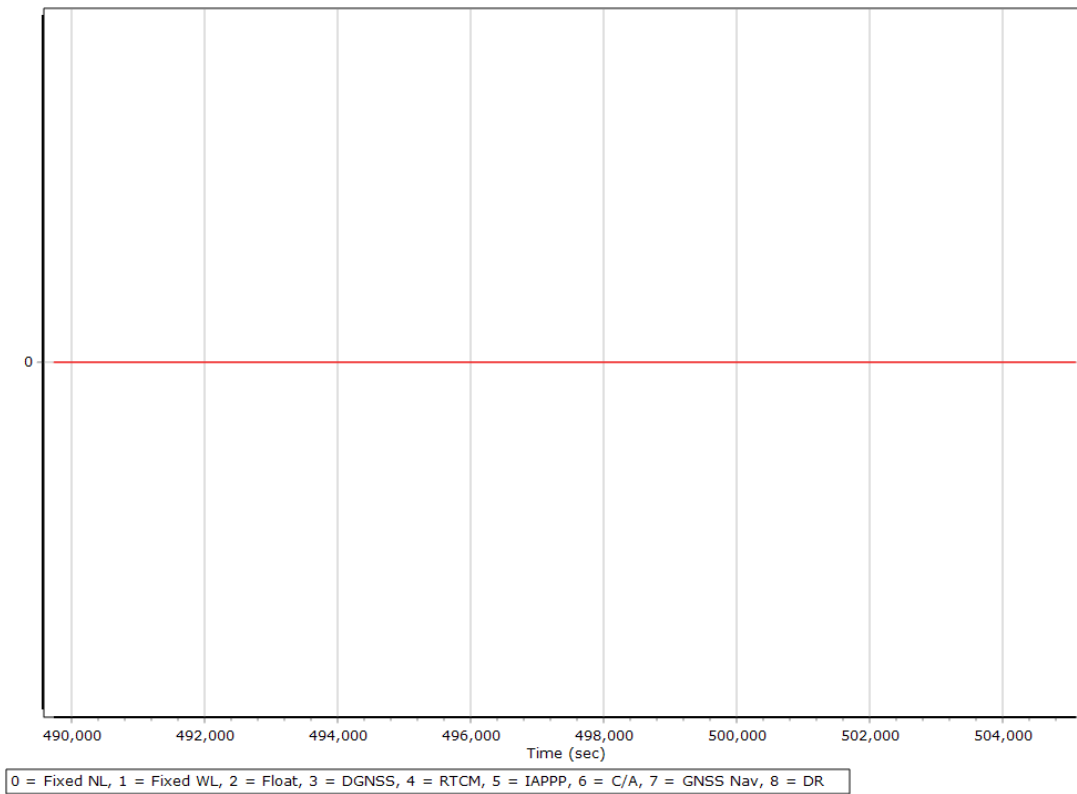


Heading Error RMS (arc-min)

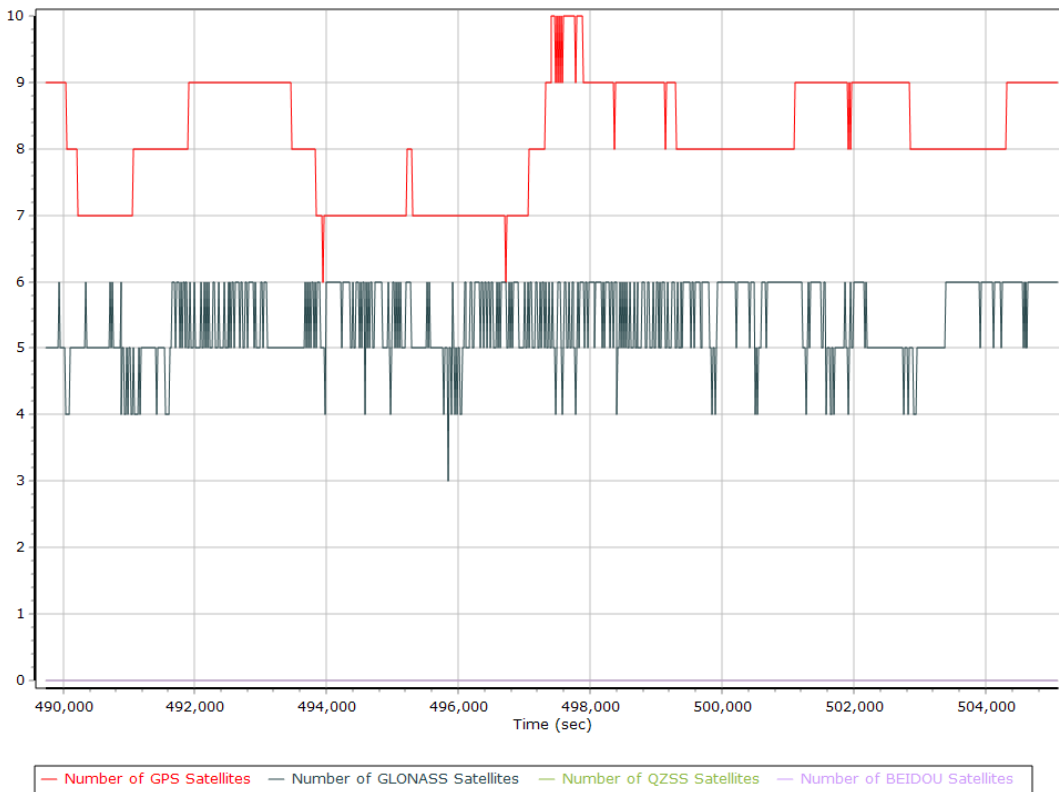


Smoothed Solution Status

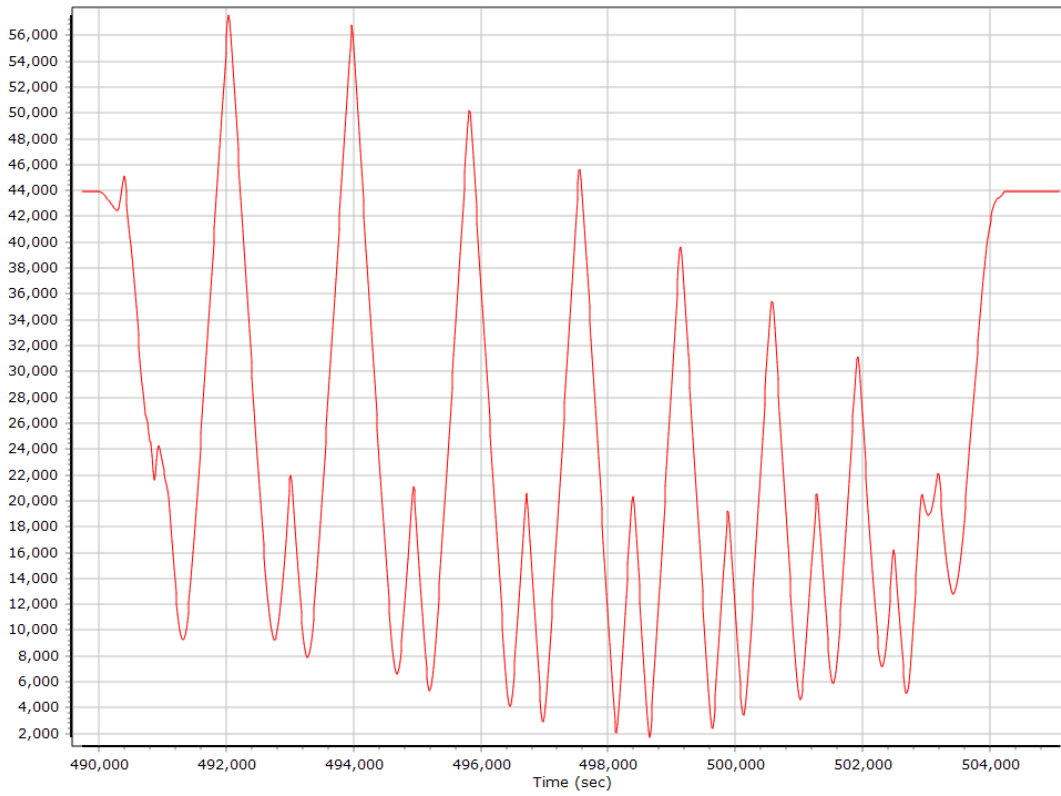
Processing Mode



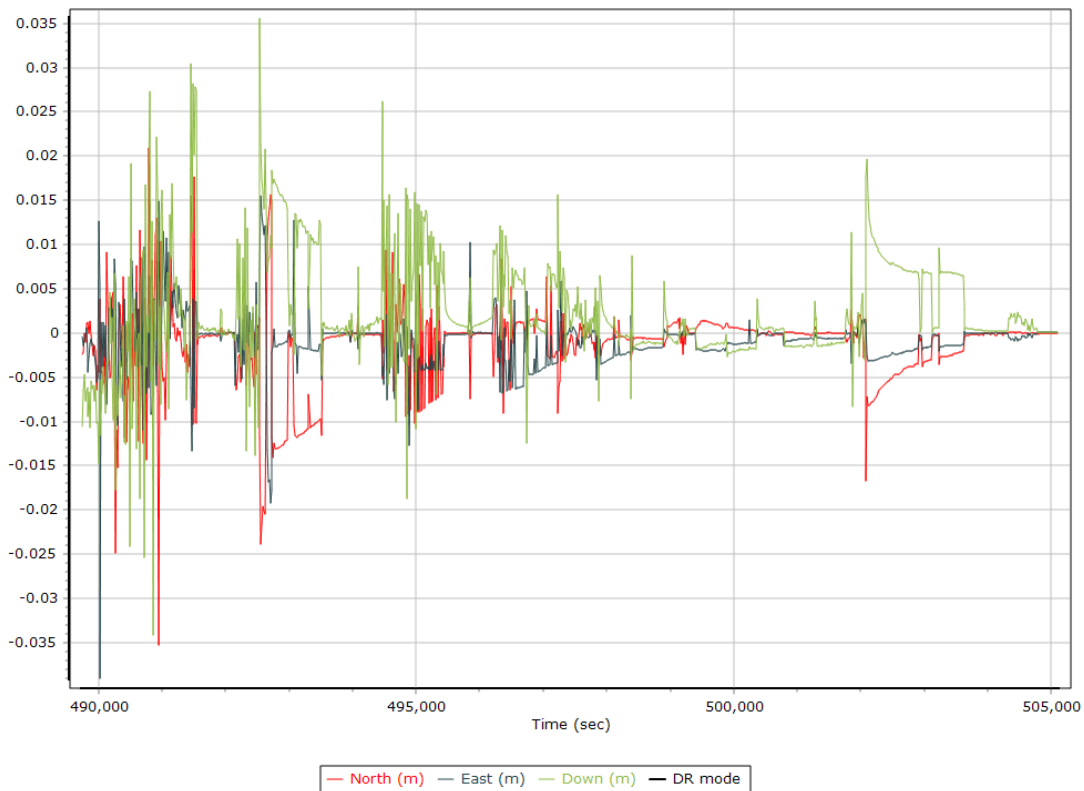
Number of Satellites



Baseline Length



SBET IAkar Separation



Export Summary

Export file	export_20211126_F1_Basestation_NAD83_2011.out		
Export format	Custom Smoothed BET		
Solution in use	Post-processed		
Output rate	All Records		
Reference to Output lever arm [m]	0.000	0.000	0.000
Reference mounting angles [deg]	0.000	0.000	0.000
Output units (Coordinate / Lat & Lon)	Meter	Deg Decimal	
Export start time	489680.001 (11/26/2021 16:01:20)		
Export end time	505106.003 (11/26/2021 20:18:26)		
Height option	Ellipsoid Height		
WGS84 height flag	False		
Grid	Universal Transverse Mercator		
Zone	UTM North 11 (120W to 114W)		
Datum	NAD83 (2011)		
Ellipsoid	GRS 1980		
Local Transformation	NONE		
Target Epoch	2010		

EO Summary

EO file			
EO format			
Lever arm [m]	0.000	0.000	0.000
Boresight angles [arcmin]	0.000	0.000	0.000
Output rate	All Records		
Rotation sequence	x omega	y phi	z kappa
Local shift [m]	0.000	0.000	0.000
Output units (coordinate / angle / lat & lon)	Meter	Degree	Deg Decimal
Height option	Ellipsoid Height		
WGS84 height flag	False		
Scale height option	False		
Kappa cardinal rotation [deg]	0		
Solution in use	Post-processed		
EO start time	489680.001 (11/26/2021 16:01:20)		
EO end time	505106.003 (11/26/2021 20:18:26)		
Grid	Universal Transverse Mercator		
Zone	UTM North 11 (120W to 114W)		
Datum	WGS84		
Ellipsoid	WGS84		
Local Transformation	NONE		
Target Epoch	2021.90137		