

General Information

Mission Information

Project name	211111_A_5060484_nad2011_FINAL
Processing date	2021-11-12 15:22:04
Mission date	2021-11-11 16:33:07
Mission duration	05:14:51.000
Processing mode	IN-Fusion PP-RTX

Rover Hardware Information

Product	POS AV 610 VER6 HW2.5-12
Serial number	S/N12118
IMU type	57
Receiver type	BD982
Antenna type	AV39

Project File List

Rover Data Files

File name	File type
211111a.000	POS Data
211111a.001	POS Data
211111a.002	POS Data
211111a.003	POS Data
211111a.004	POS Data
211111a.005	POS Data
211111a.006	POS Data
211111a.007	POS Data
211111a.008	POS Data
211111a.009	POS Data
211111a.010	POS Data
211111a.011	POS Data
211111a.012	POS Data
211111a.013	POS Data
211111a.014	POS Data
211111a.015	POS Data
211111a.016	POS Data
211111a.017	POS Data
211111a.018	POS Data
211111a.019	POS Data
211111a.020	POS Data
211111a.021	POS Data
211111a.022	POS Data
211111a.023	POS Data
211111a.024	POS Data
211111a.025	POS Data
211111a.026	POS Data
211111a.027	POS Data
211111a.028	POS Data
211111a.029	POS Data
211111a.030	POS Data
211111a.031	POS Data
211111a.032	POS Data
211111a.033	POS Data
211111a.034	POS Data
211111a.035	POS Data
211111a.036	POS Data
211111a.037	POS Data
211111a.038	POS Data
211111a.039	POS Data
211111a.040	POS Data
211111a.041	POS Data

Input Files

File Name	File Type
Ephm3150.21g	GLONASS Broadcast Ephemeris
Ephm3150.21n	GPS Broadcast Ephemeris

Output Files

Filename	File type
sbet_211111_A_5060484_nad2011_FINAL.out	SBET Trajectory File

Rover Data Summary

First raw data file	211111a.000		
Last raw data file	211111a.041		
Start GPS week	2183		
Start time	405187.024 (11/11/2021 4:33:07 PM)		
End time	424070.501 (11/11/2021 9:47:50 PM)		
Start of fine alignment	405382.214 (11/11/2021 4:36:22 PM)		
Available subsystems	Primary GNSS, IMU		
POS Event Input	None		
Correction data	None		
IMU Installation Lever Arms & Mounting Angles			
Reference to IMU lever arm (m)	0.000	0.000	0.000
Reference to IMU mounting angles (deg)	0.000	0.000	180.000
Reference to Primary GNSS lever arm (m)	0.683	-0.546	-1.101
Reference to Primary GNSS lever arm std dev (m)	-1.000		
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

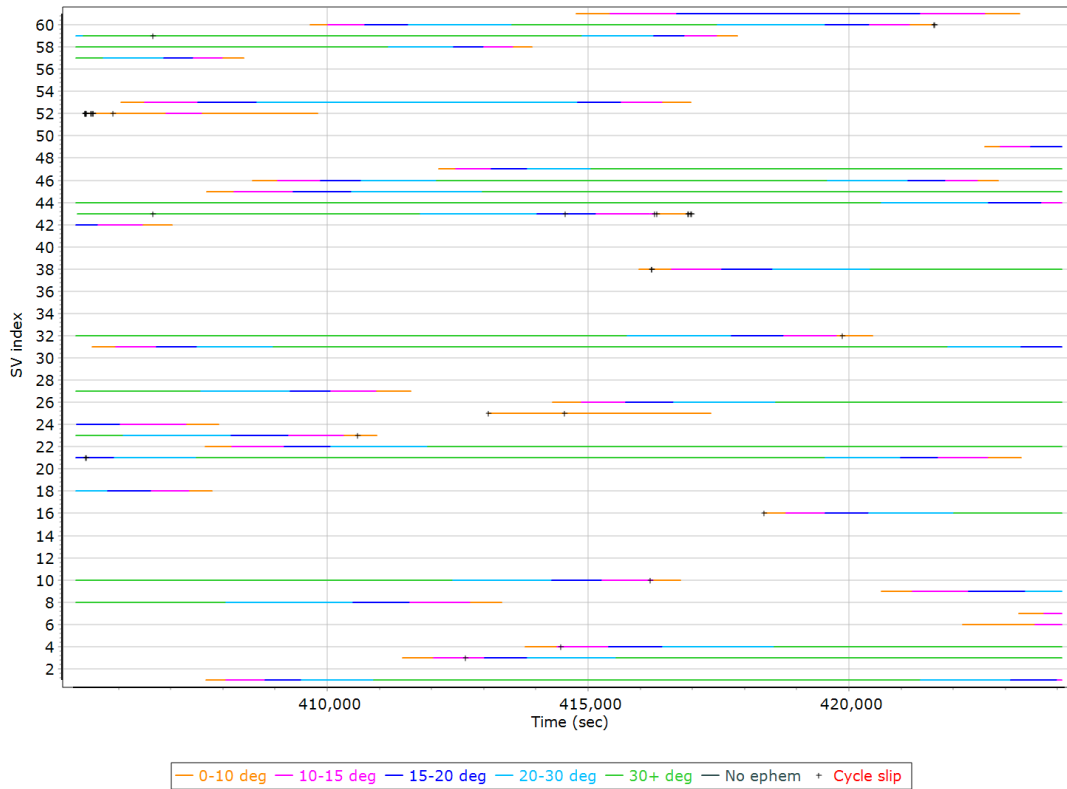
Rover Data QC

Raw IMU Import QC Summary

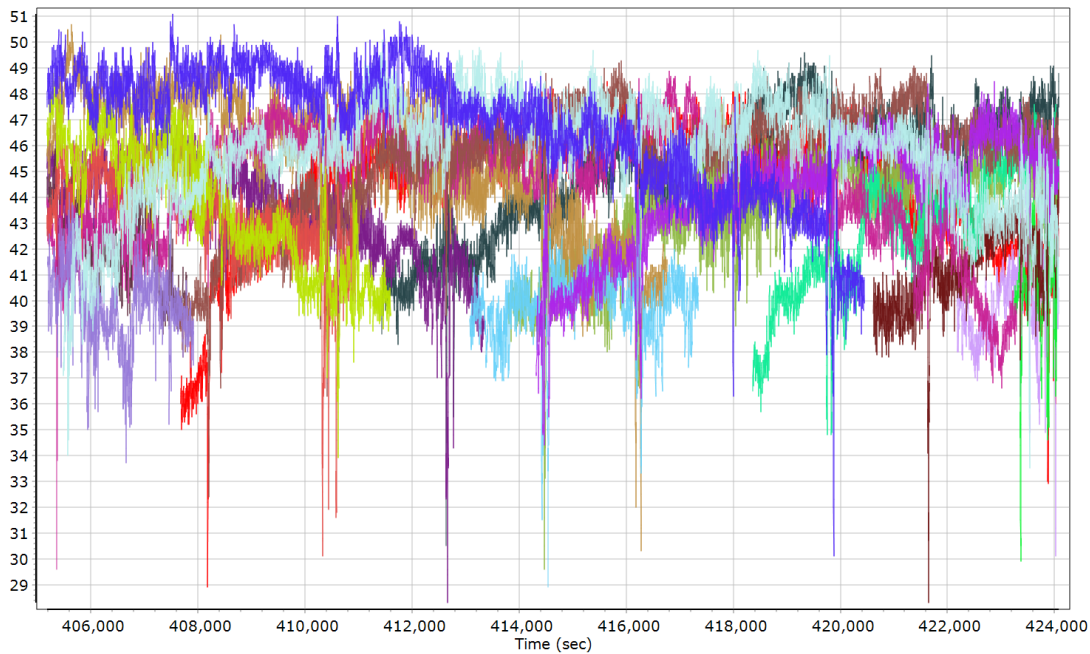
IMU data input file	imu_211111_A_5060484_nad2011_FINAL.dat
IMU data check log file	imudt_211111_A_5060484_nad2011_FINAL.log
IMU Records Processed	3777646
Termination Status	Normal
IMU Anomalies	0

Primary Observables & Satellite Data

GPS/GLONASS L1 Satellite Lock/Elevation

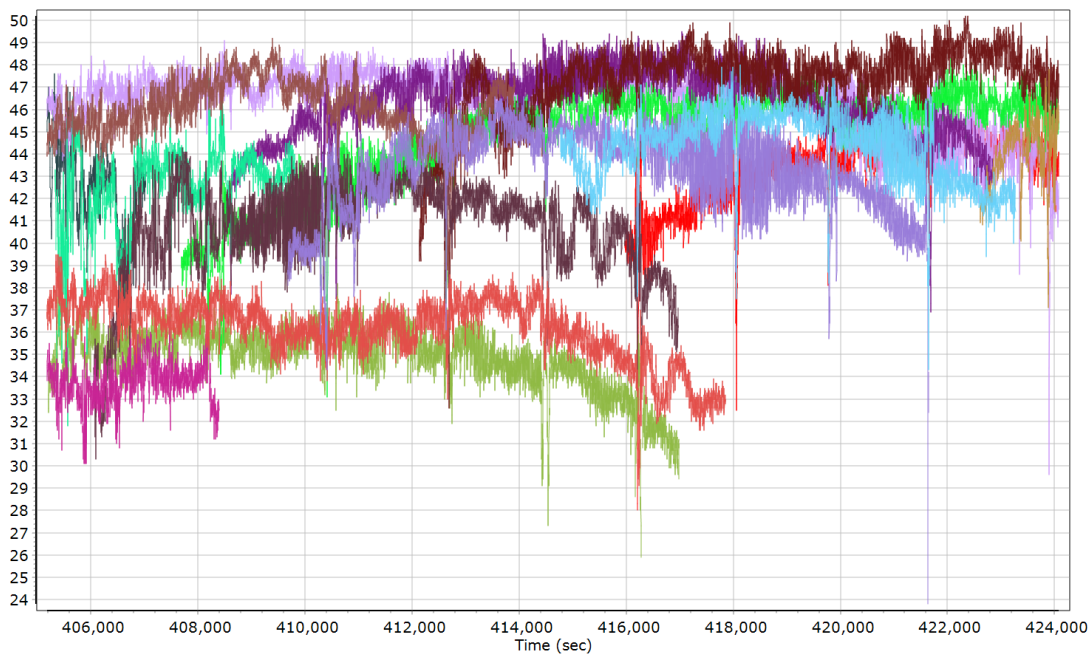


GPS L1 SNR



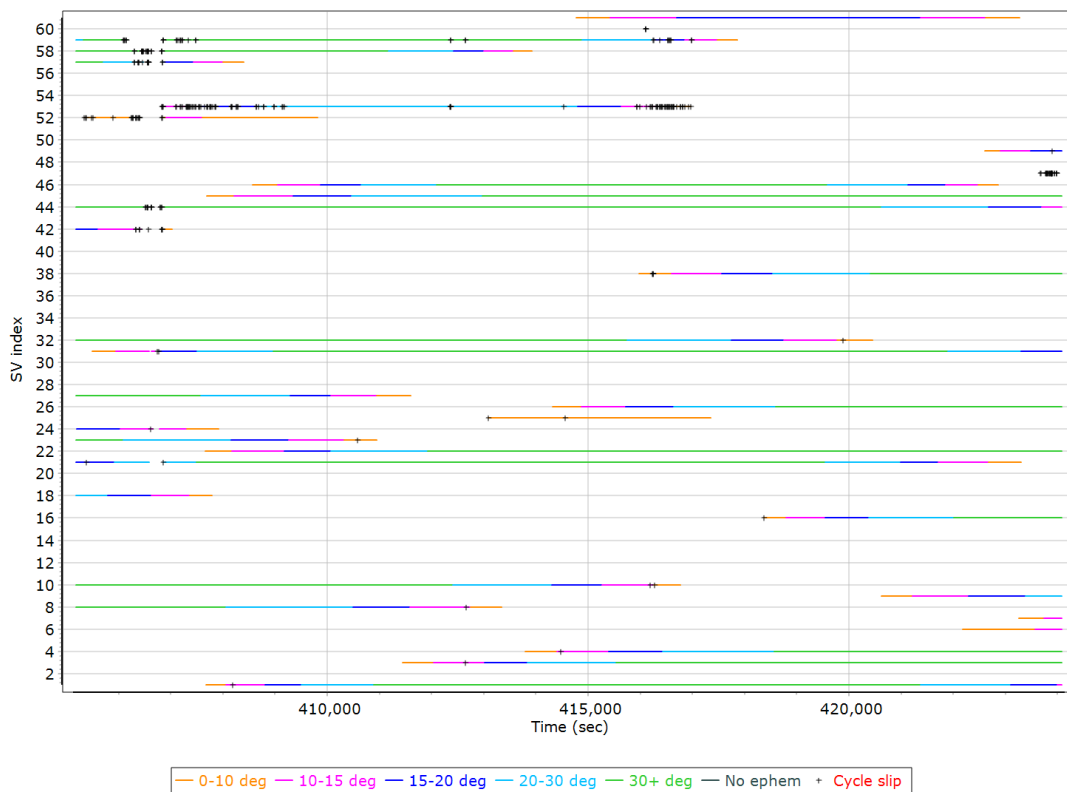
- | | | | |
|---------------------------|---------------------------|---------------------------|---------------------------|
| GPS PRN 01 L1 SNR (dB/Hz) | GPS PRN 03 L1 SNR (dB/Hz) | GPS PRN 04 L1 SNR (dB/Hz) | GPS PRN 06 L1 SNR (dB/Hz) |
| GPS PRN 07 L1 SNR (dB/Hz) | GPS PRN 08 L1 SNR (dB/Hz) | GPS PRN 09 L1 SNR (dB/Hz) | GPS PRN 10 L1 SNR (dB/Hz) |
| GPS PRN 16 L1 SNR (dB/Hz) | GPS PRN 18 L1 SNR (dB/Hz) | GPS PRN 21 L1 SNR (dB/Hz) | GPS PRN 22 L1 SNR (dB/Hz) |
| GPS PRN 23 L1 SNR (dB/Hz) | GPS PRN 24 L1 SNR (dB/Hz) | GPS PRN 25 L1 SNR (dB/Hz) | GPS PRN 26 L1 SNR (dB/Hz) |
| GPS PRN 27 L1 SNR (dB/Hz) | GPS PRN 31 L1 SNR (dB/Hz) | GPS PRN 32 L1 SNR (dB/Hz) | |

GLONASS L1 SNR

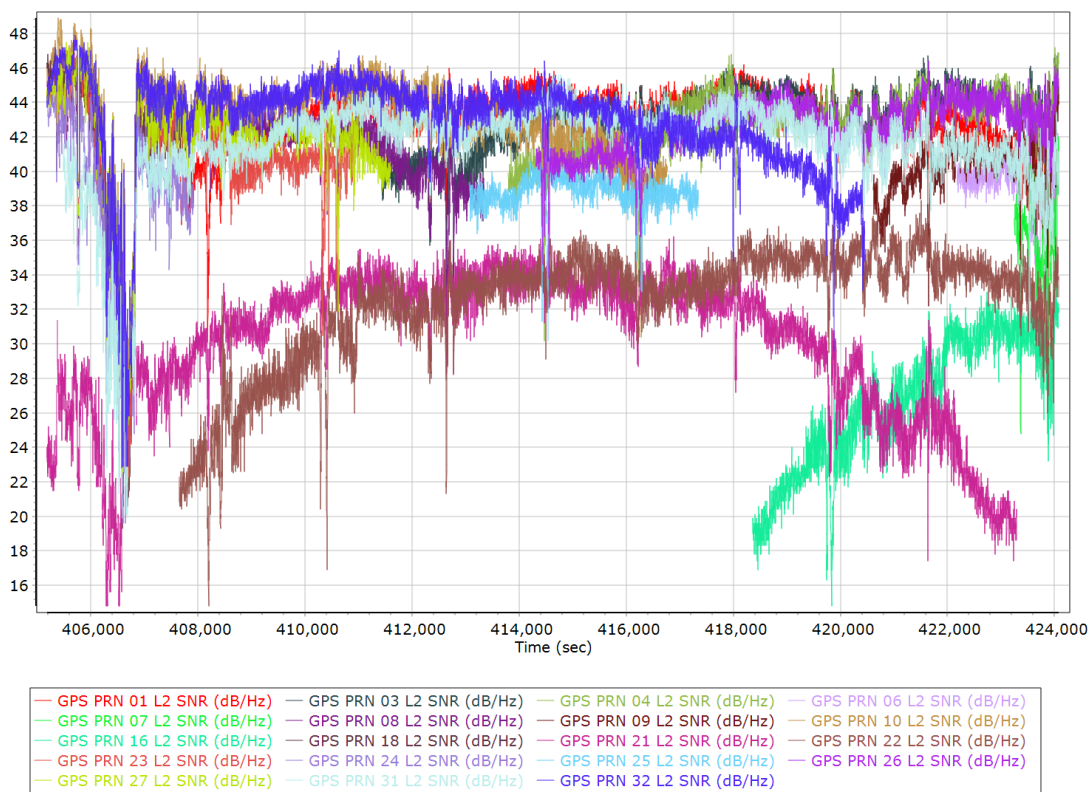


- | | | |
|---------------------------|---------------------------|---------------------------|
| GLONASS 01 L1 SNR (dB/Hz) | GLONASS 05 L1 SNR (dB/Hz) | GLONASS 06 L1 SNR (dB/Hz) |
| GLONASS 07 L1 SNR (dB/Hz) | GLONASS 08 L1 SNR (dB/Hz) | GLONASS 09 L1 SNR (dB/Hz) |
| GLONASS 10 L1 SNR (dB/Hz) | GLONASS 12 L1 SNR (dB/Hz) | GLONASS 15 L1 SNR (dB/Hz) |
| GLONASS 16 L1 SNR (dB/Hz) | GLONASS 20 L1 SNR (dB/Hz) | GLONASS 21 L1 SNR (dB/Hz) |
| GLONASS 22 L1 SNR (dB/Hz) | GLONASS 23 L1 SNR (dB/Hz) | GLONASS 24 L1 SNR (dB/Hz) |

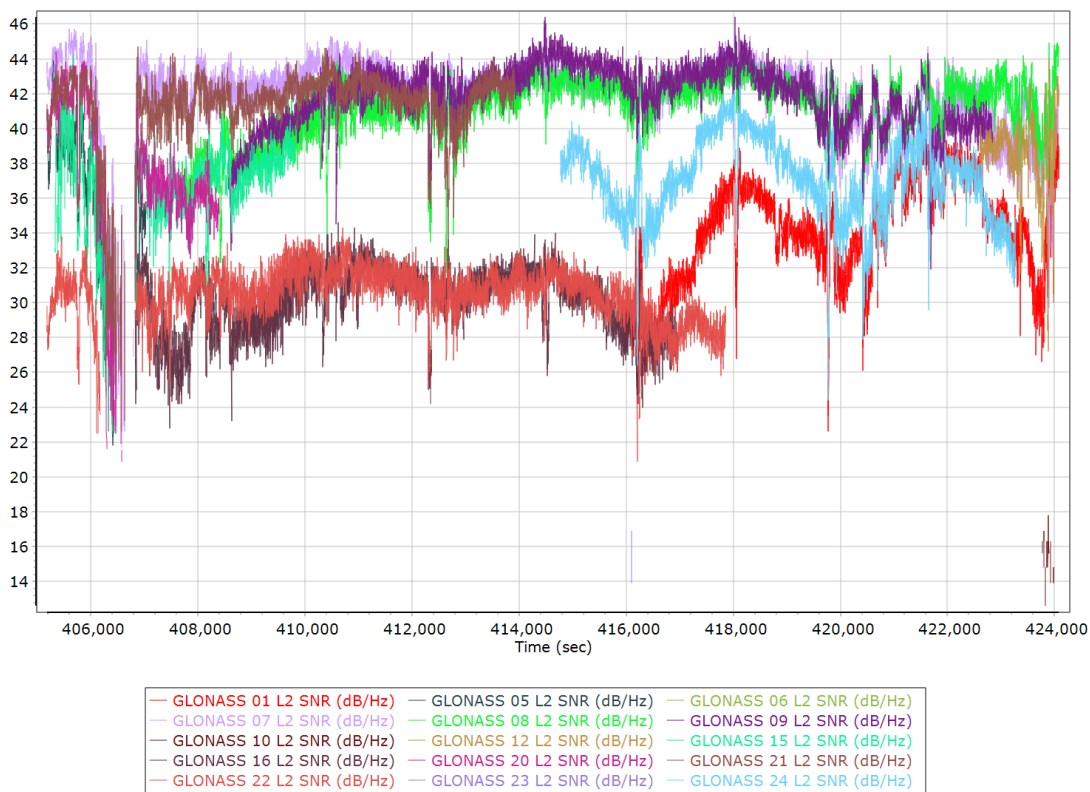
GPS/GLONASS L2 Satellite Lock/Elevation



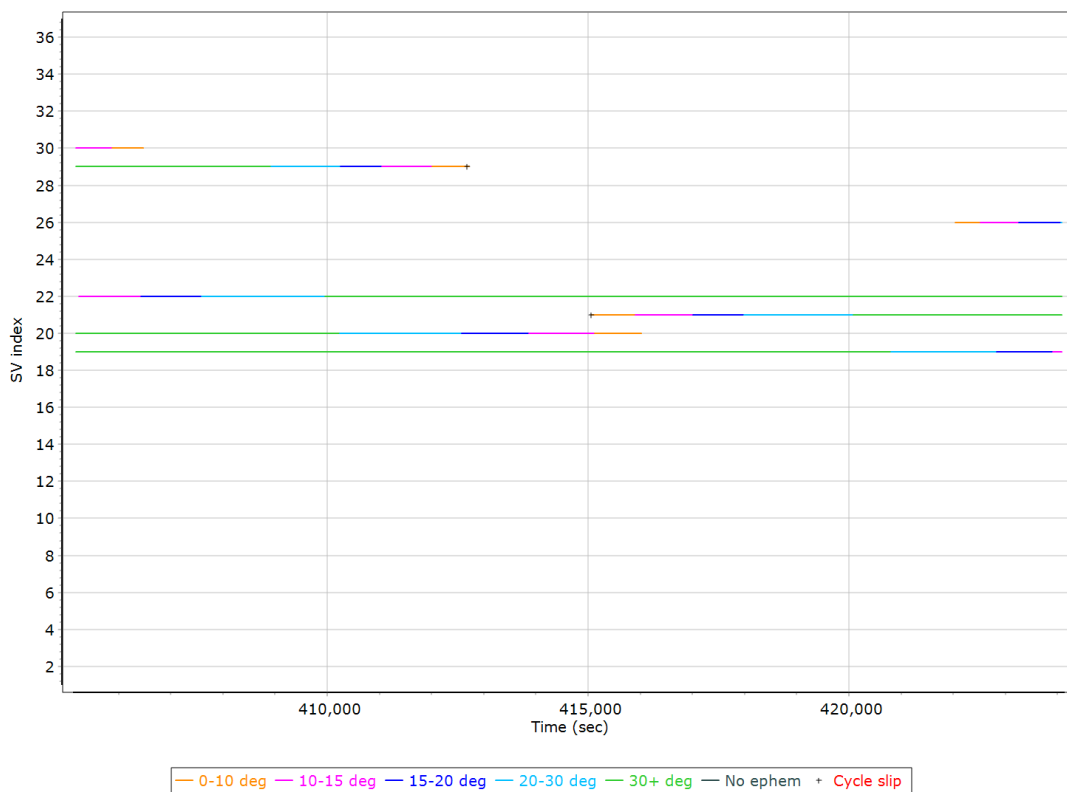
GPS L2 SNR



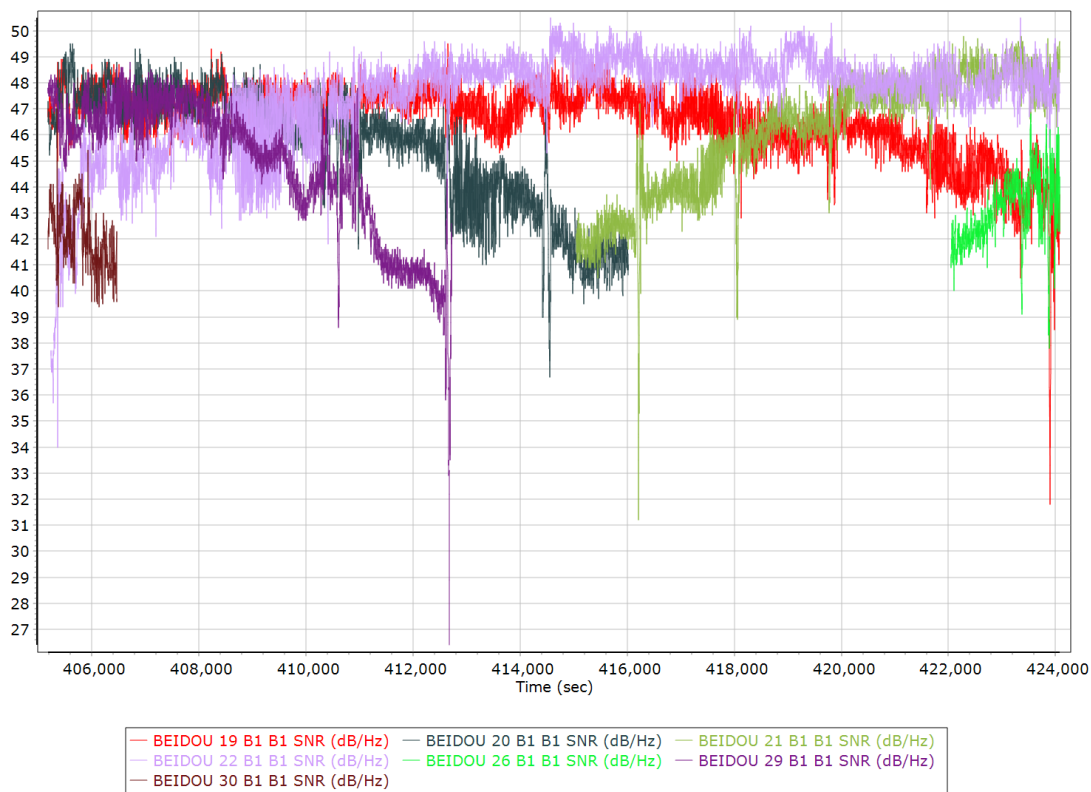
GLONASS L2 SNR



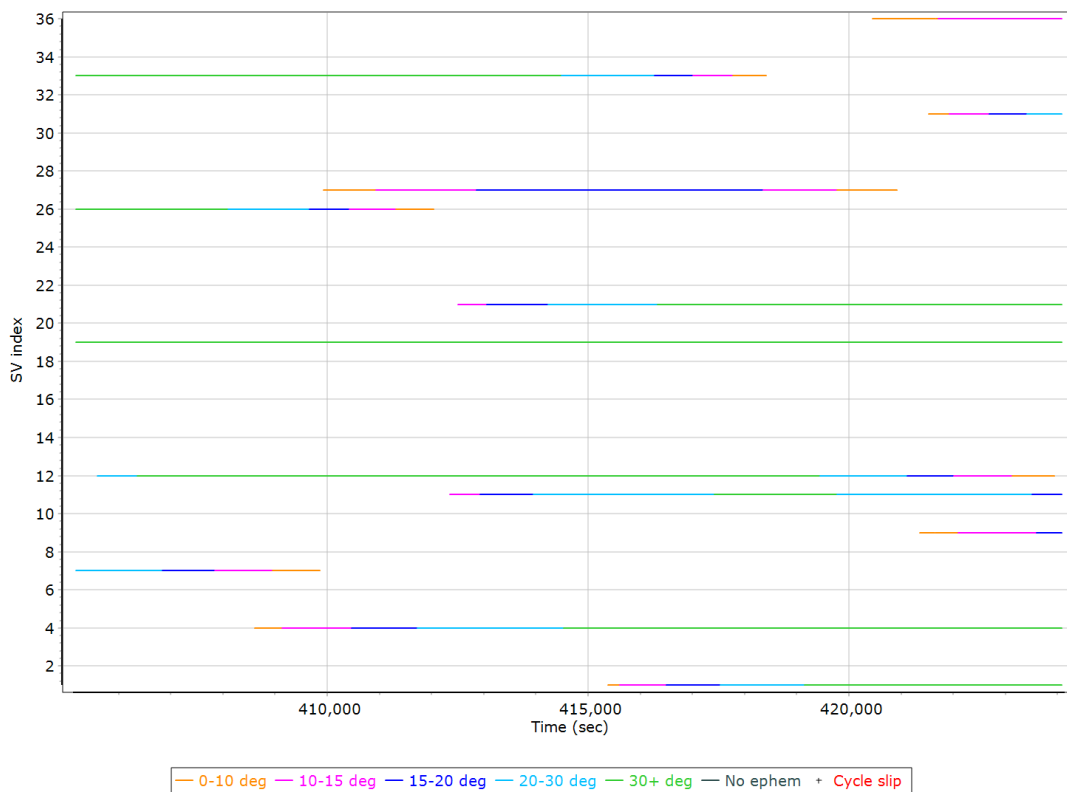
BEIDOU Satellite Lock/Elevation



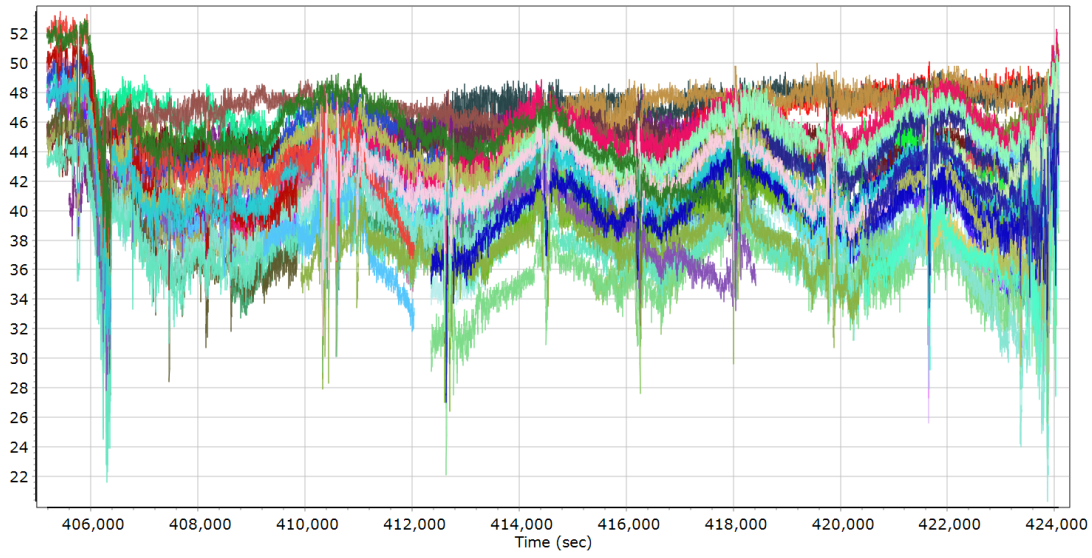
BEIDOU SNR



GALILEO Satellite Lock/Elevation



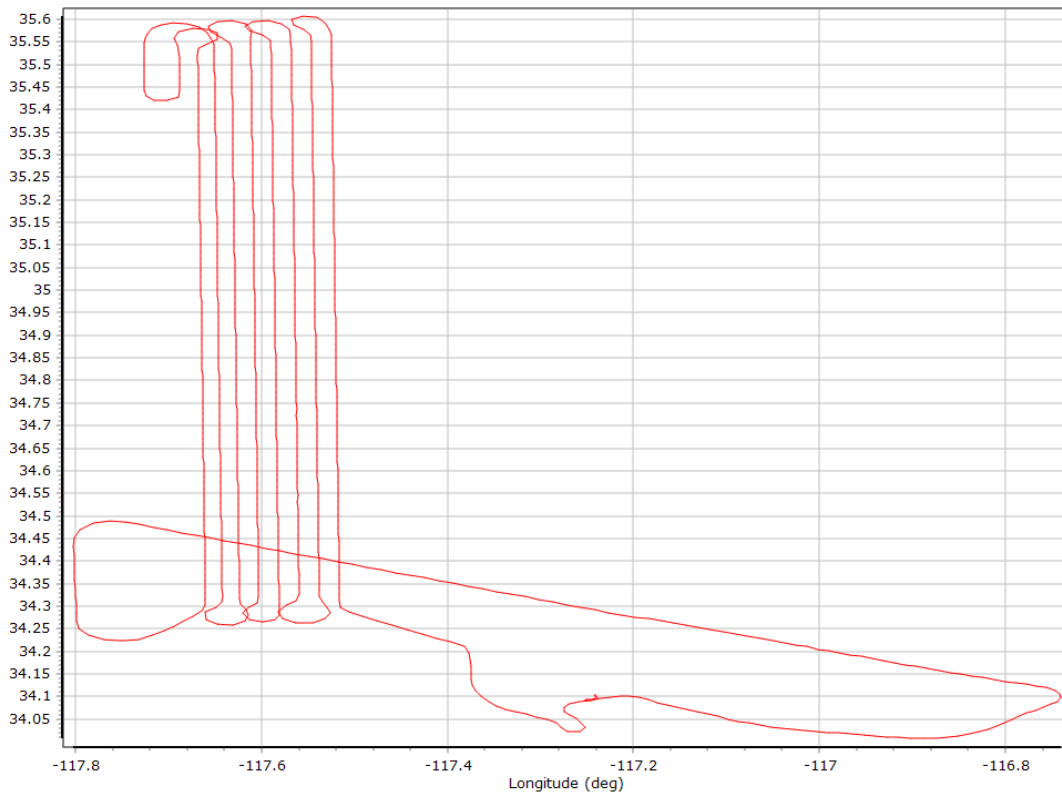
GALILEO SNR



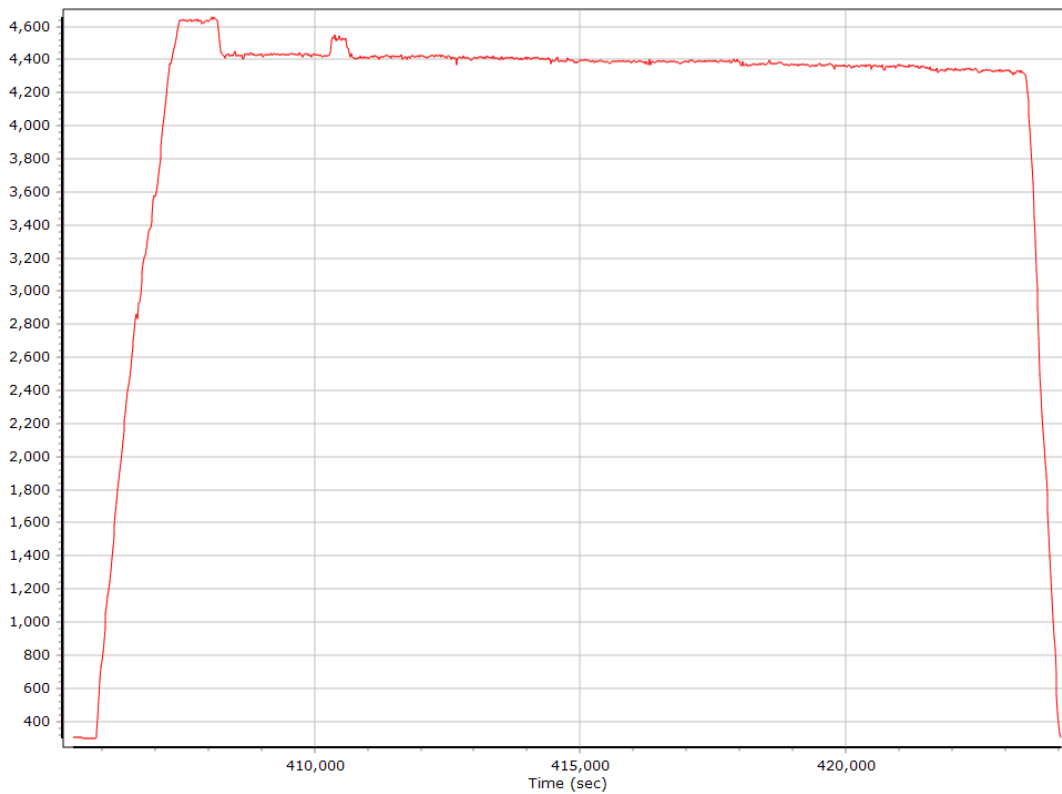
— GALILEO 01 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 04 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 07 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 09 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 11 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 12 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 19 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 21 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 26 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 27 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 31 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 33 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 36 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 01 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 04 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 07 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 09 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 11 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 12 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 19 L5E5A BPSK10_PD SNR (dB/Hz)

Smoothed Trajectory Information

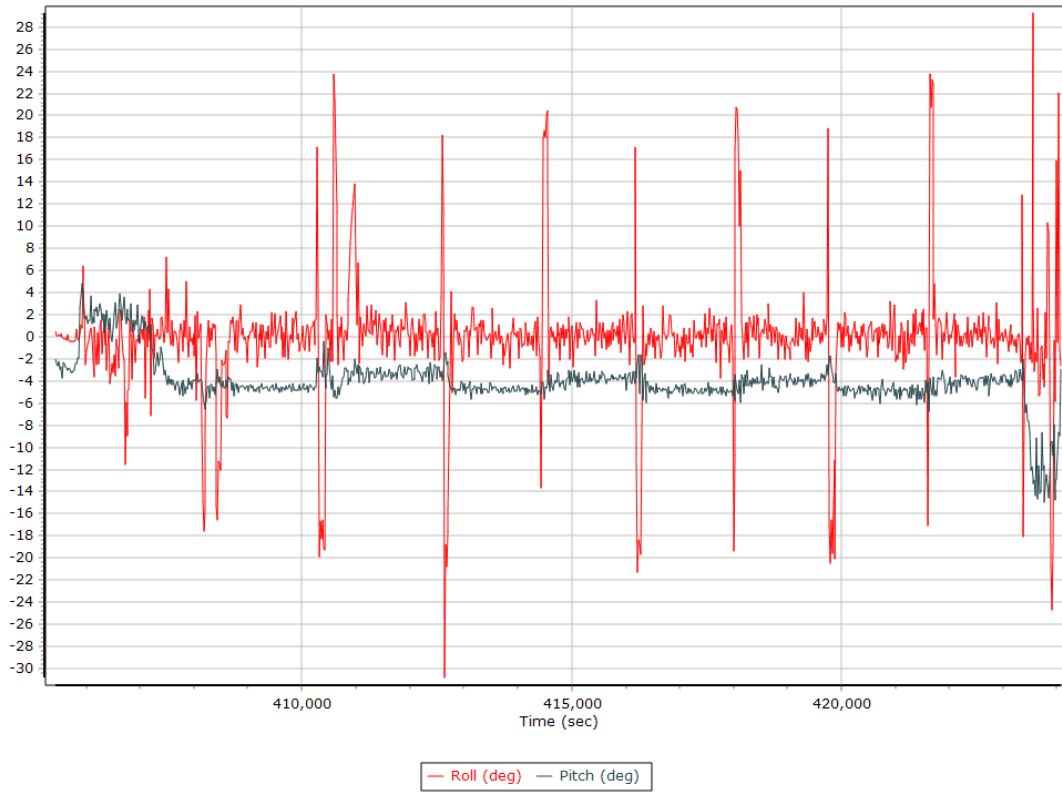
Top View



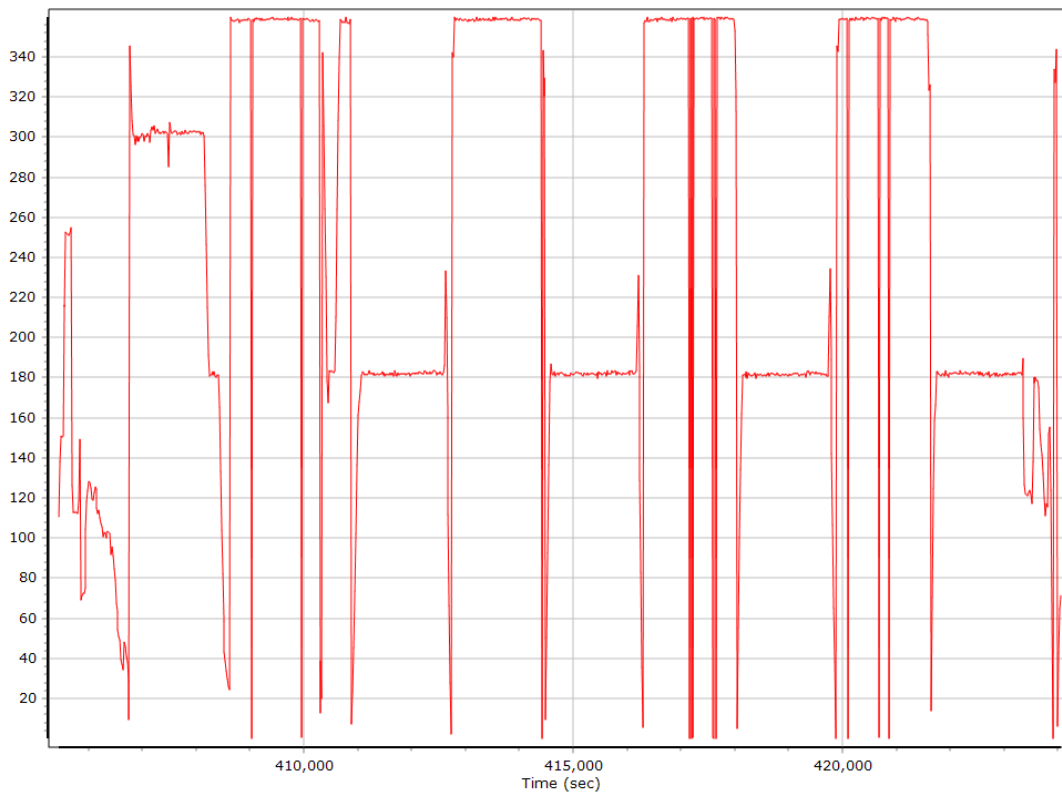
Altitude



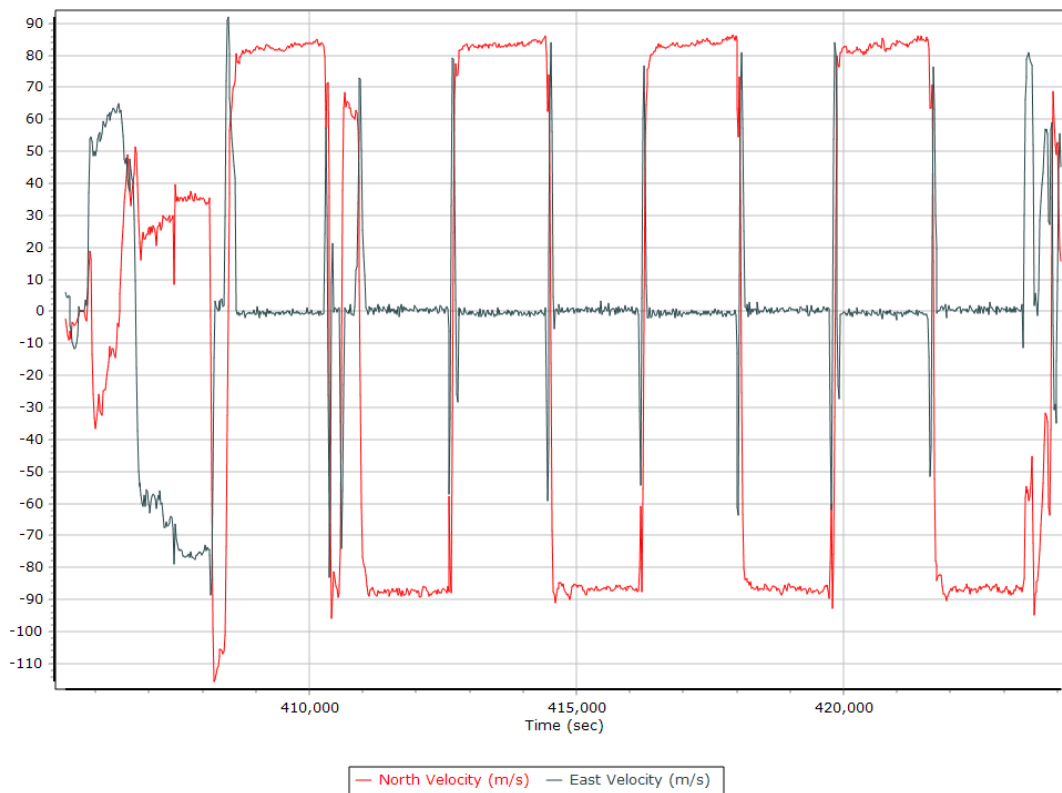
Roll/Pitch



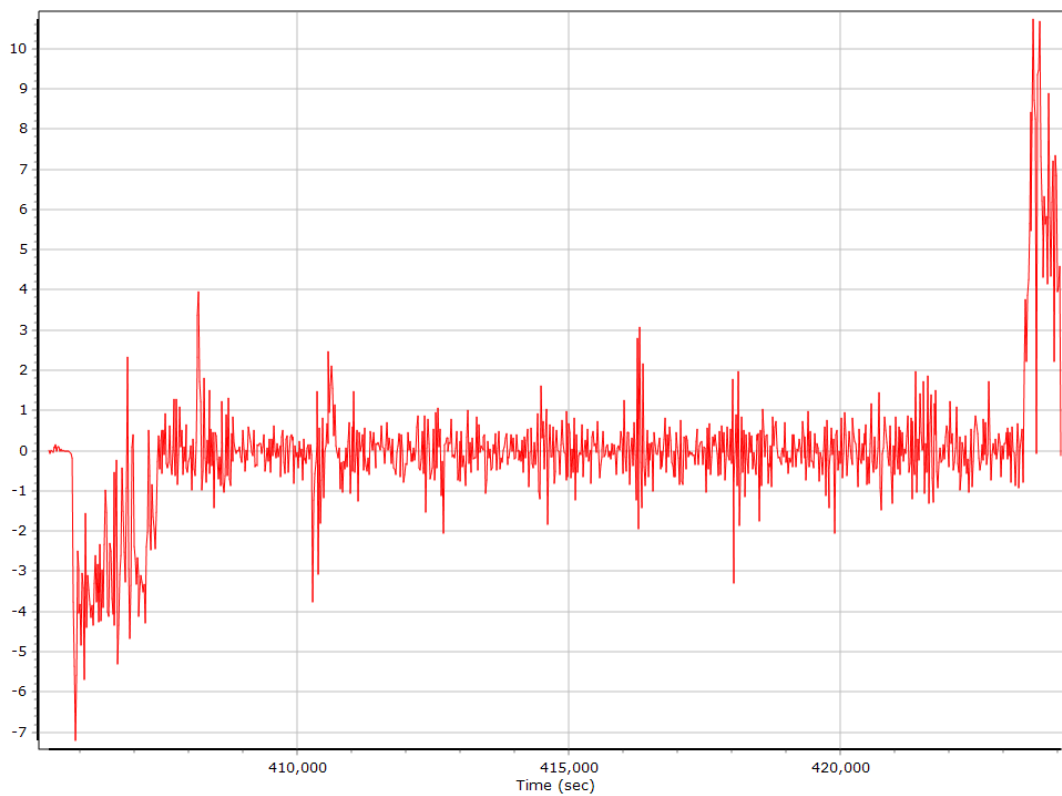
Heading



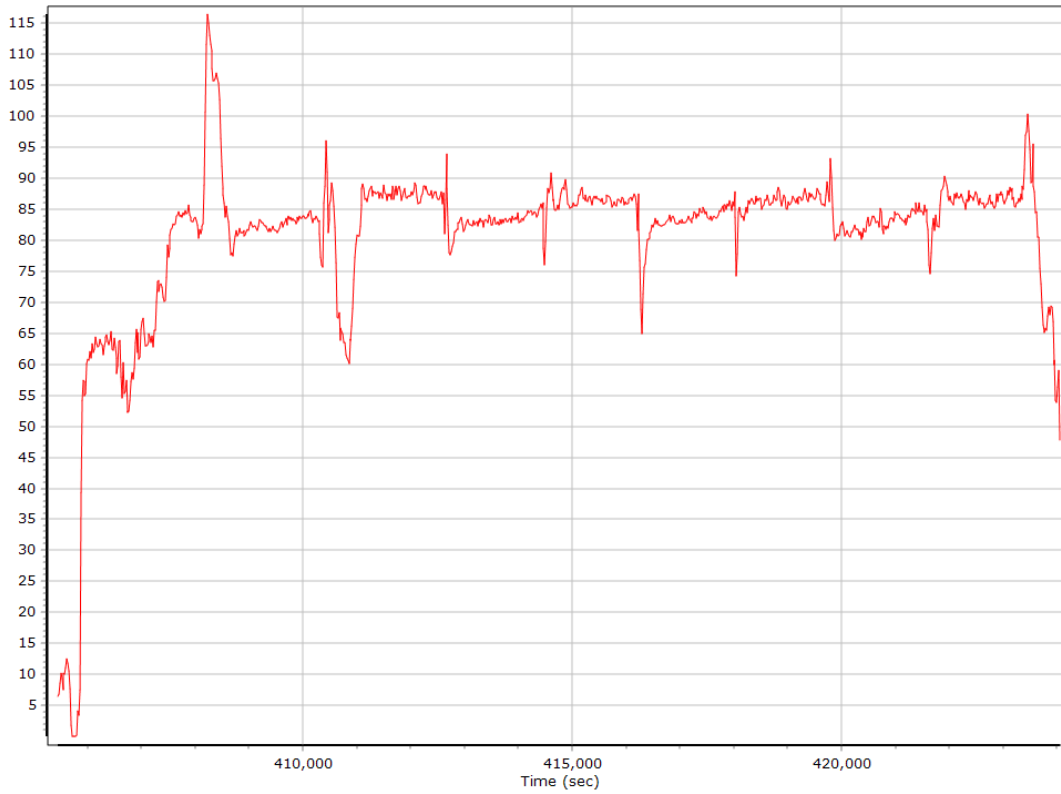
North/East Velocity



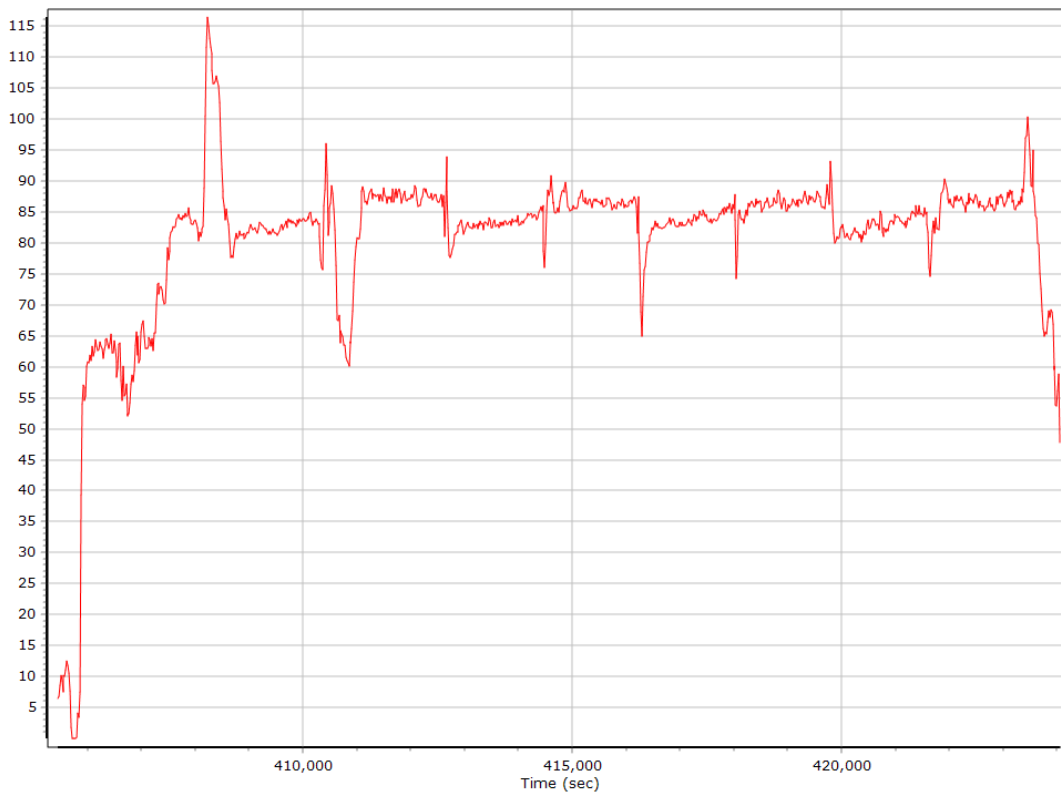
Down Velocity



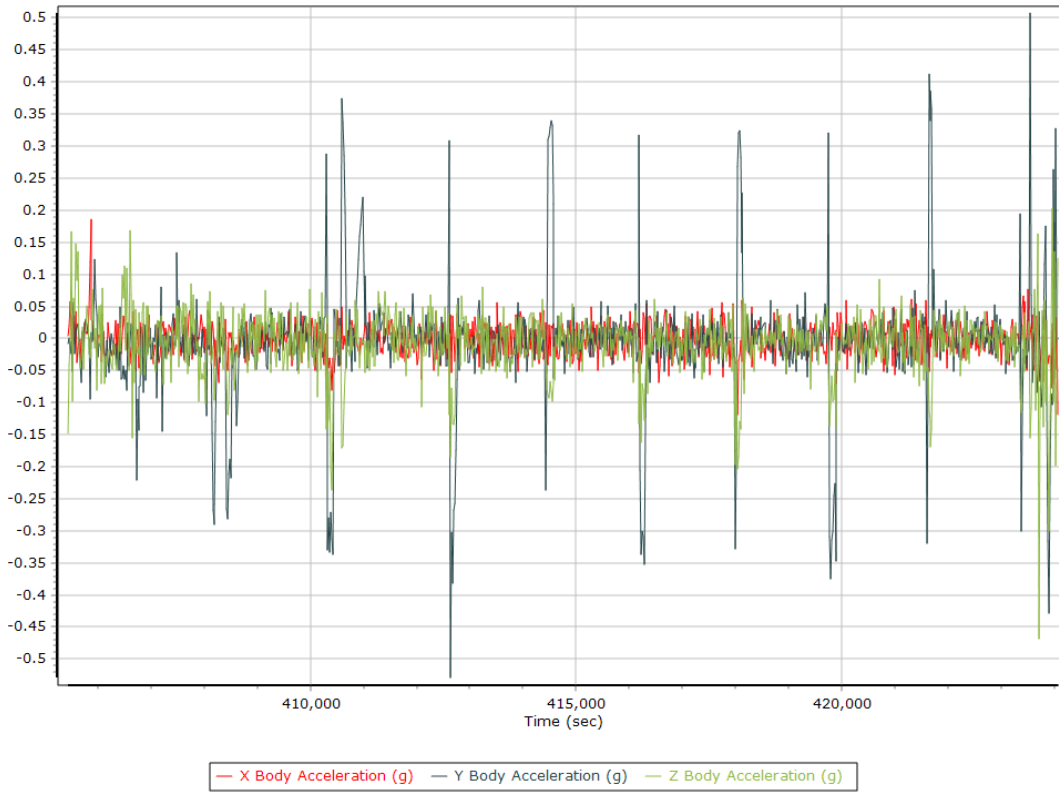
Total Speed



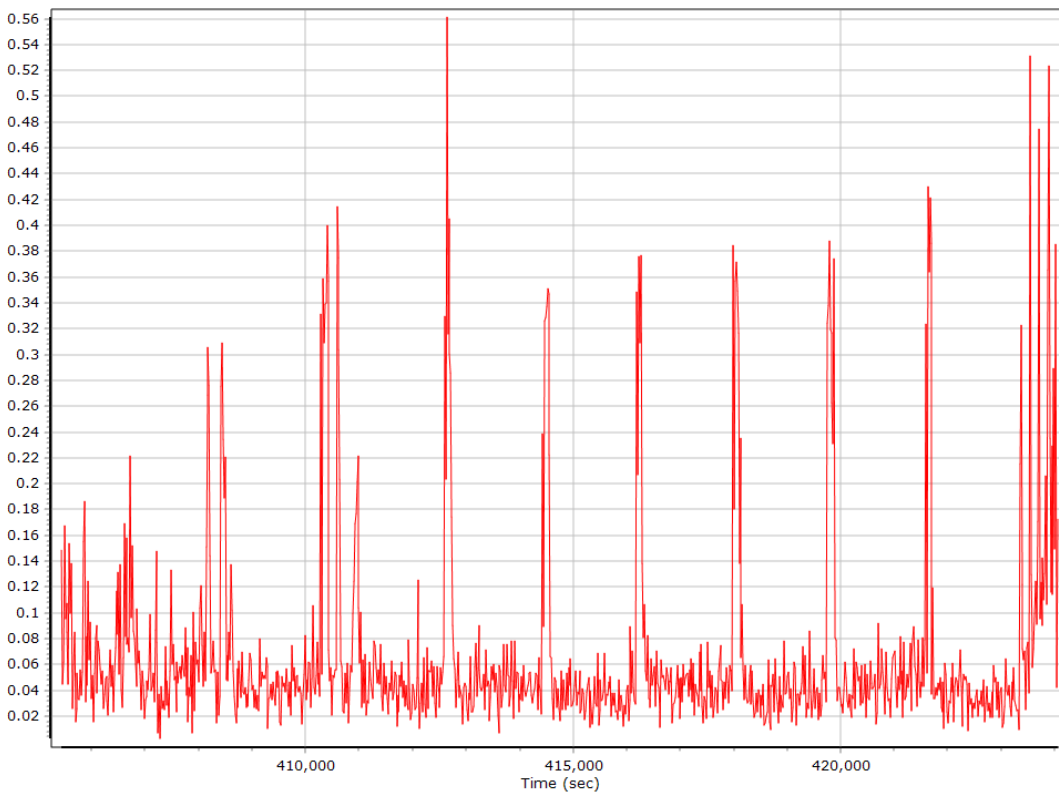
Ground Speed



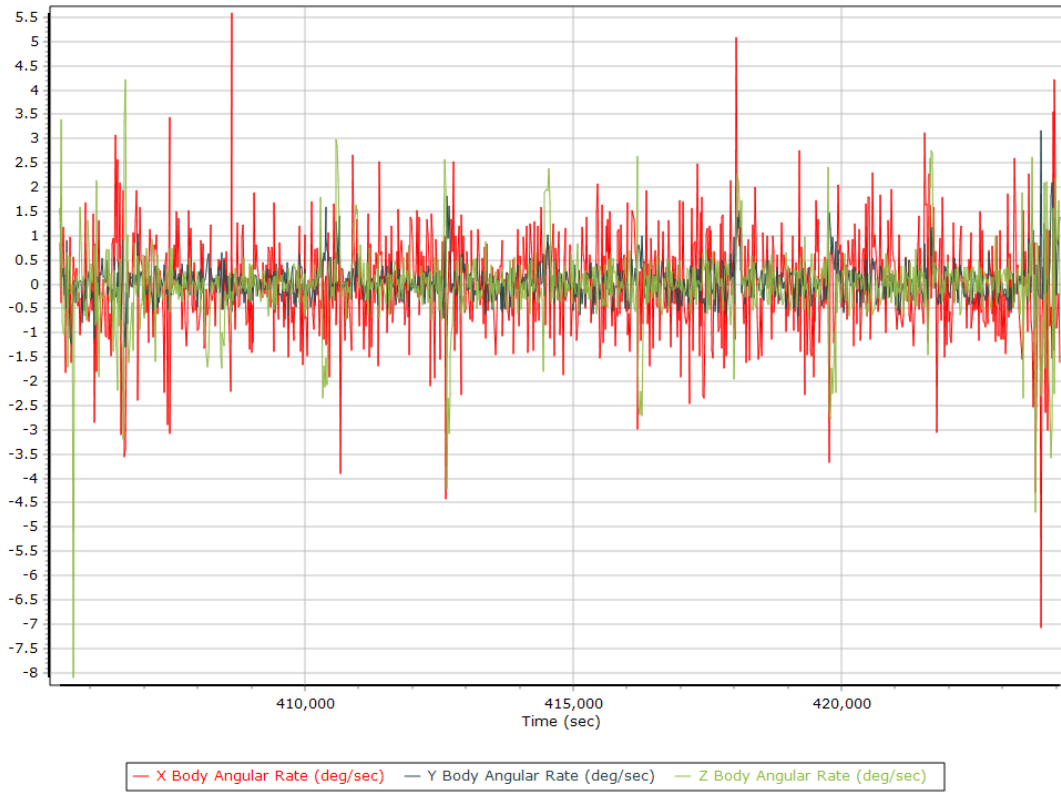
Body Acceleration



Total Body Acceleration

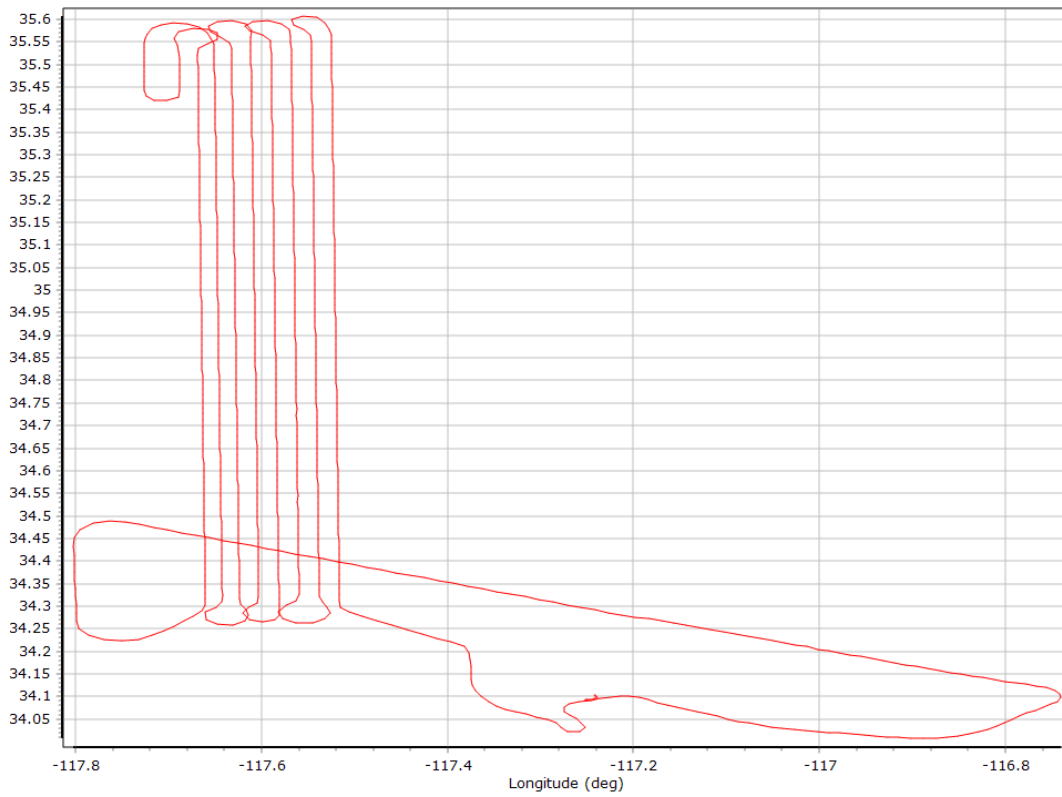


Body Angular Rate

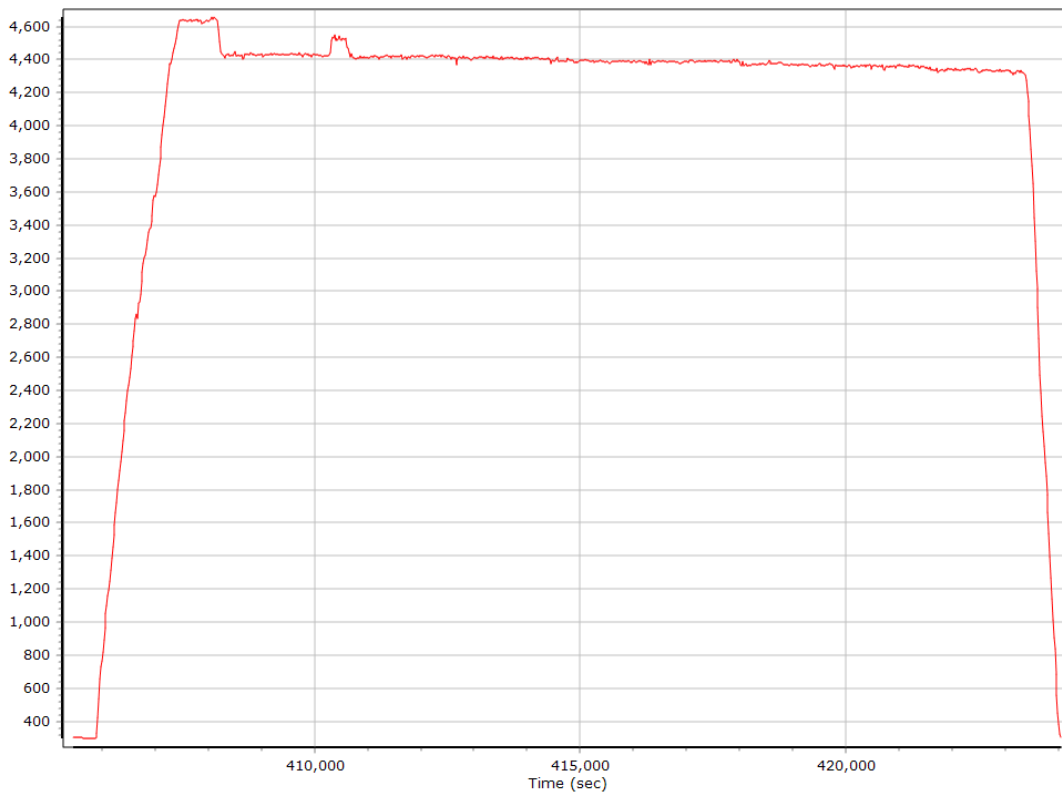


Forward Processed Trajectory Information

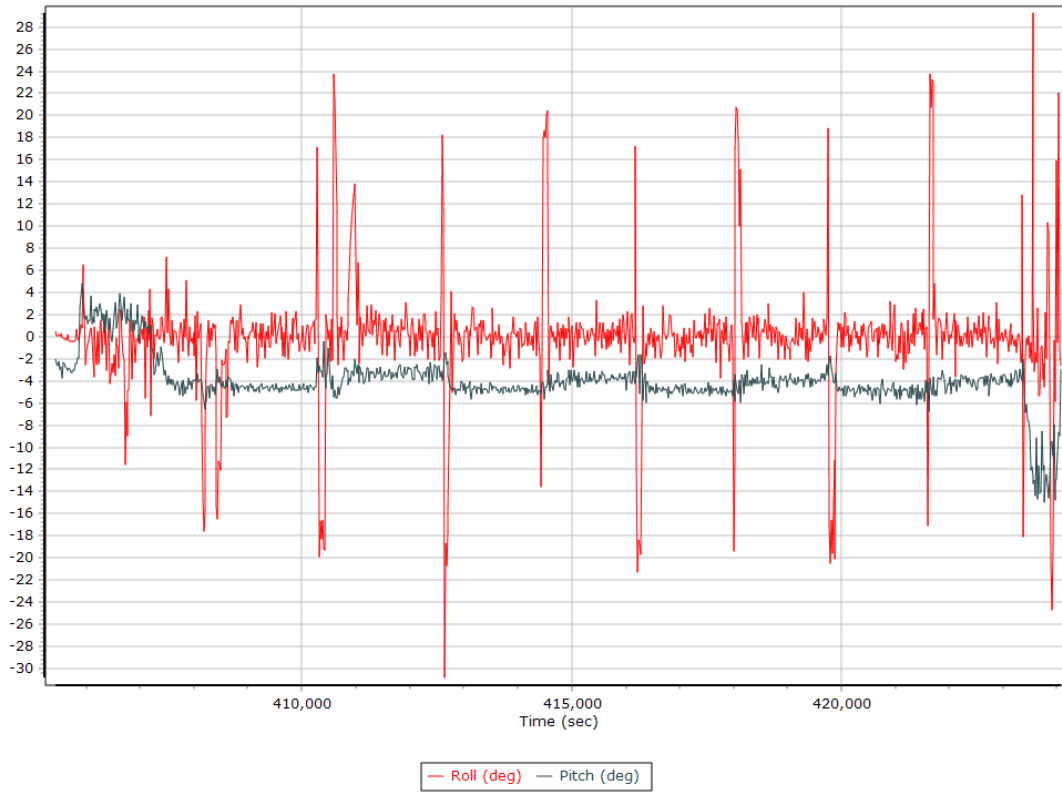
Top View



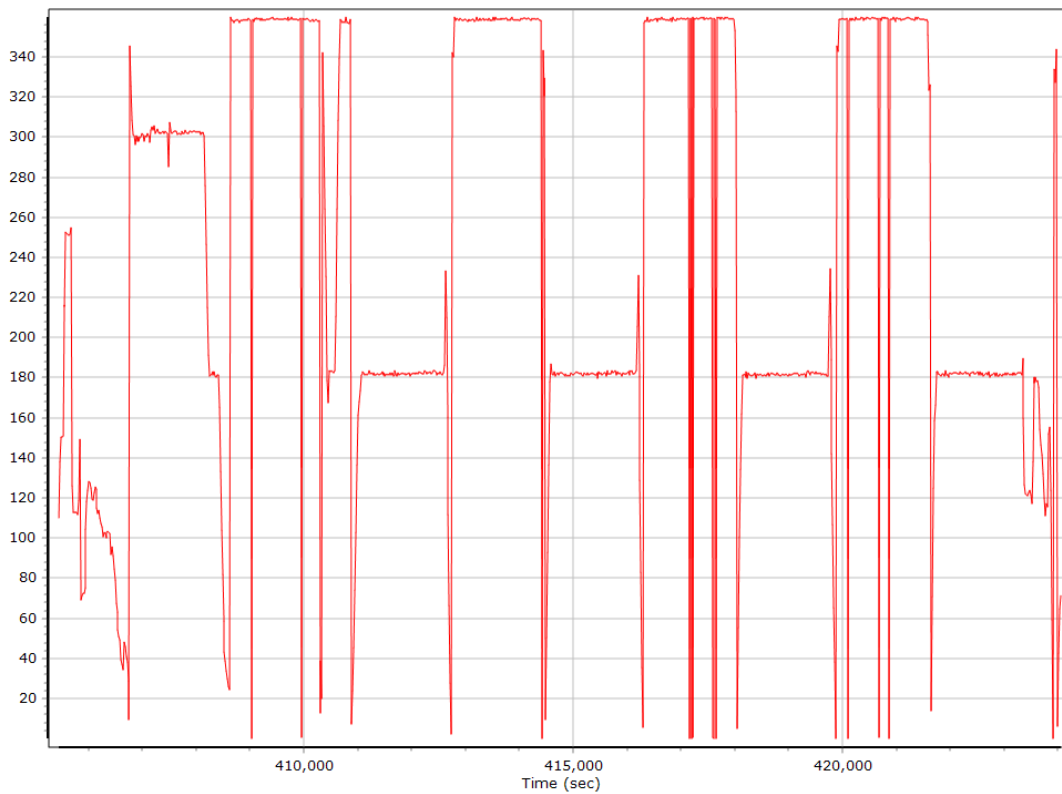
Altitude



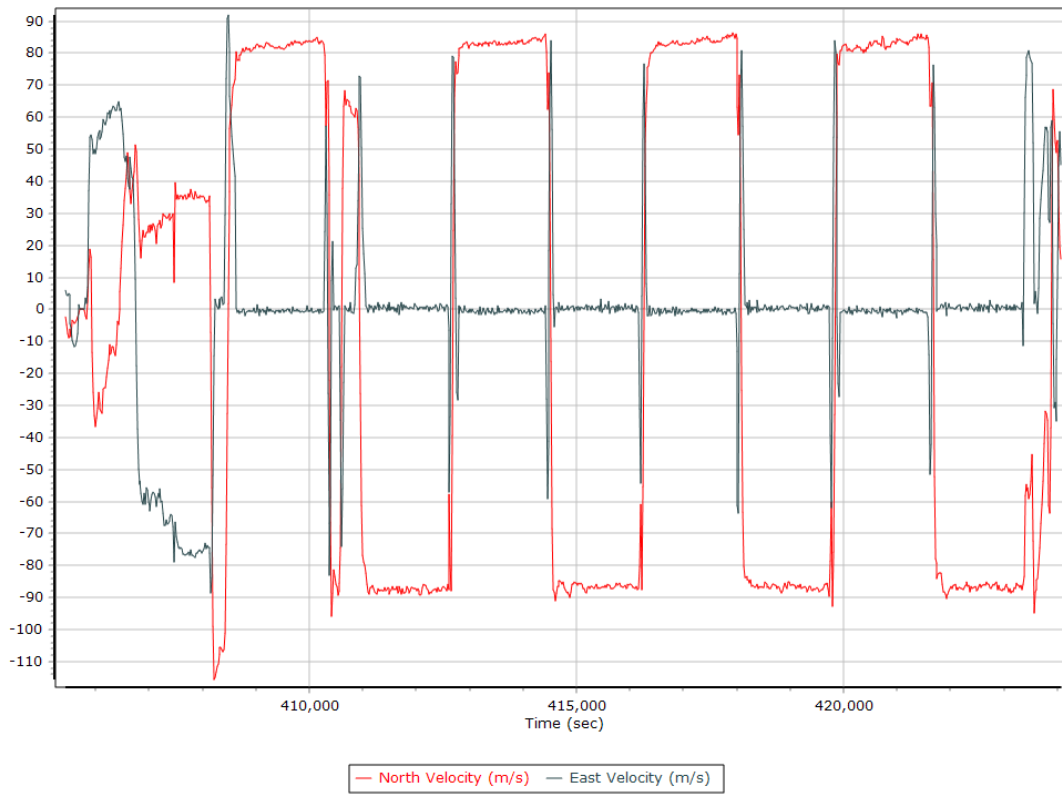
Roll/Pitch



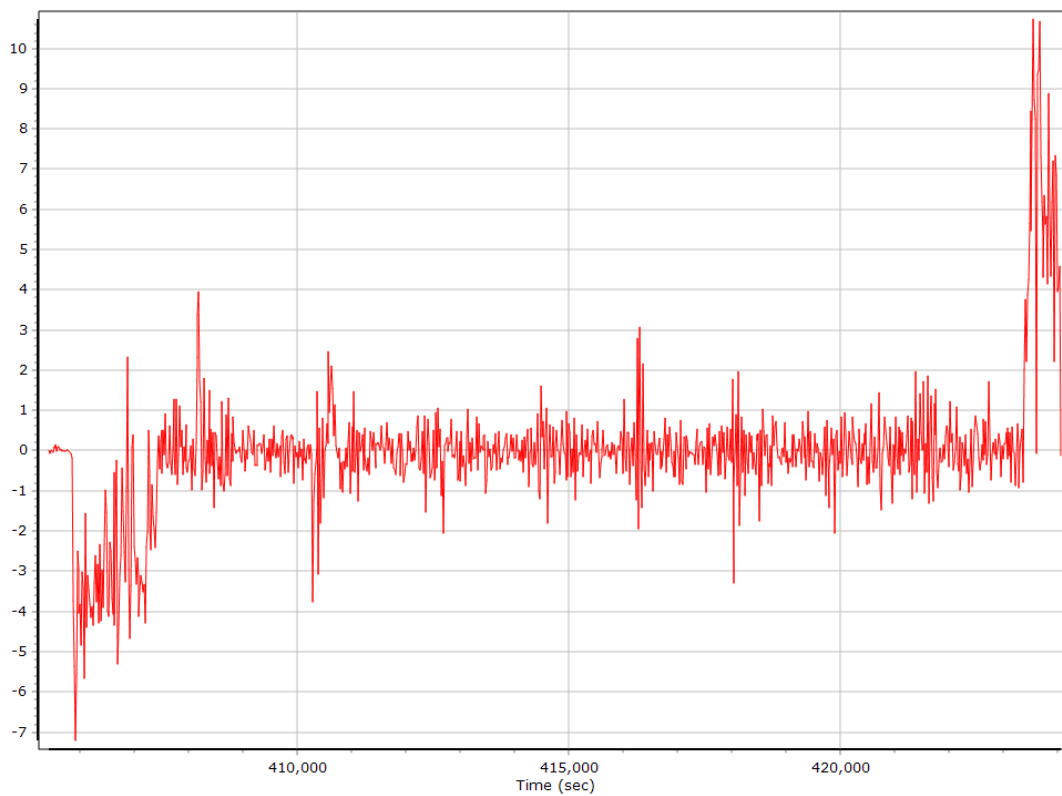
Heading



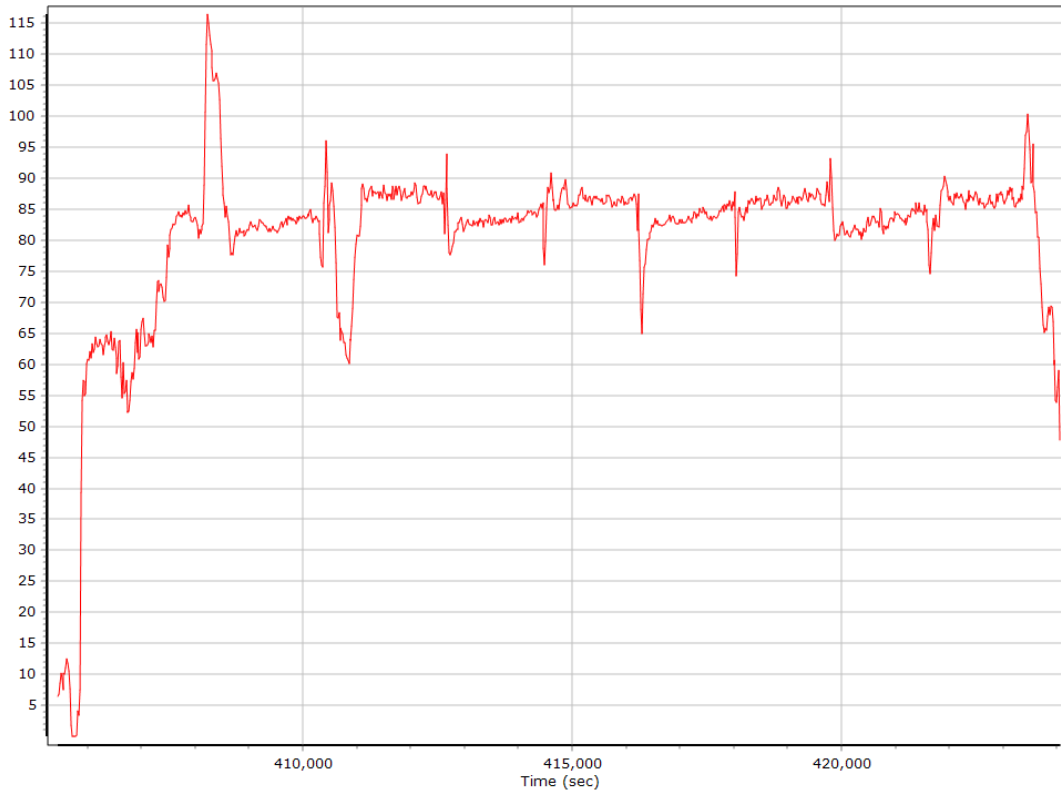
North/East Velocity



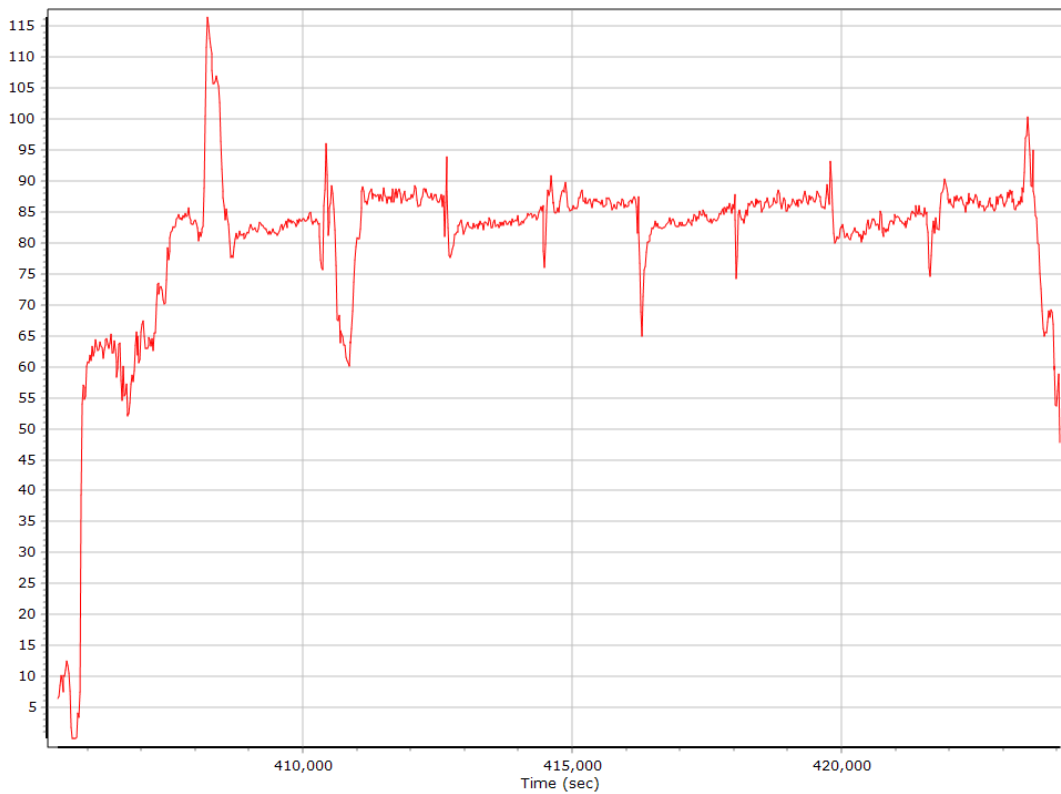
Down Velocity



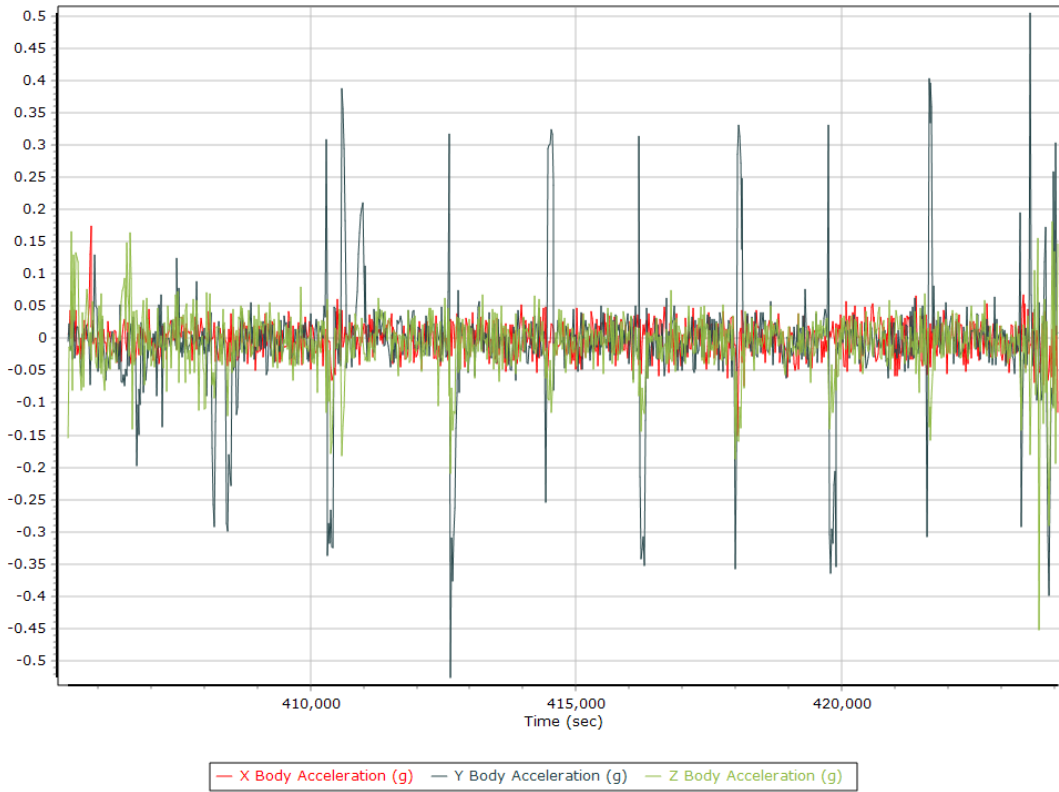
Total Speed



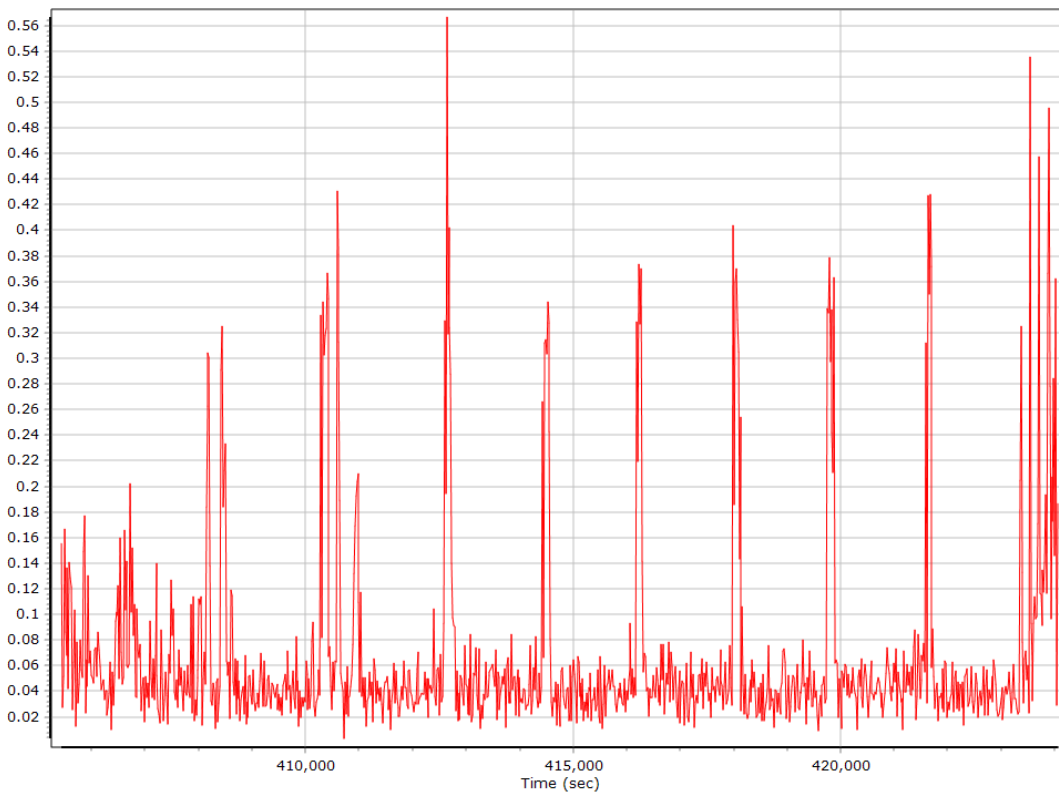
Ground Speed



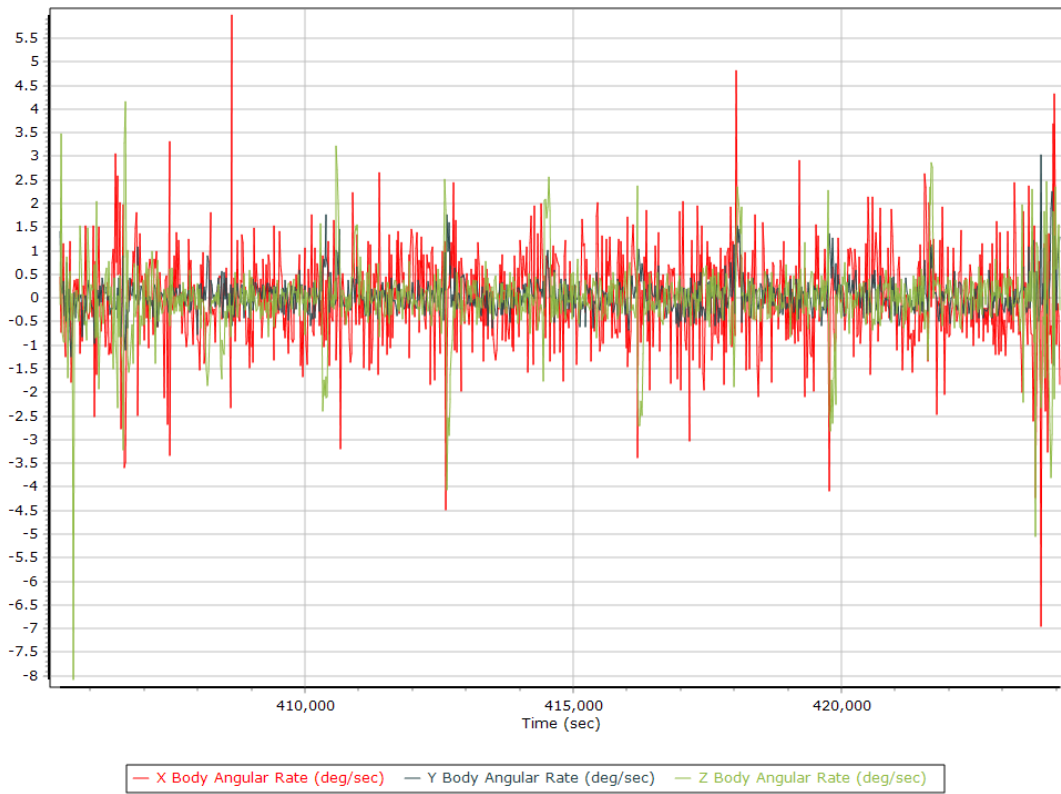
Body Acceleration



Total Body Acceleration



Body Angular Rate

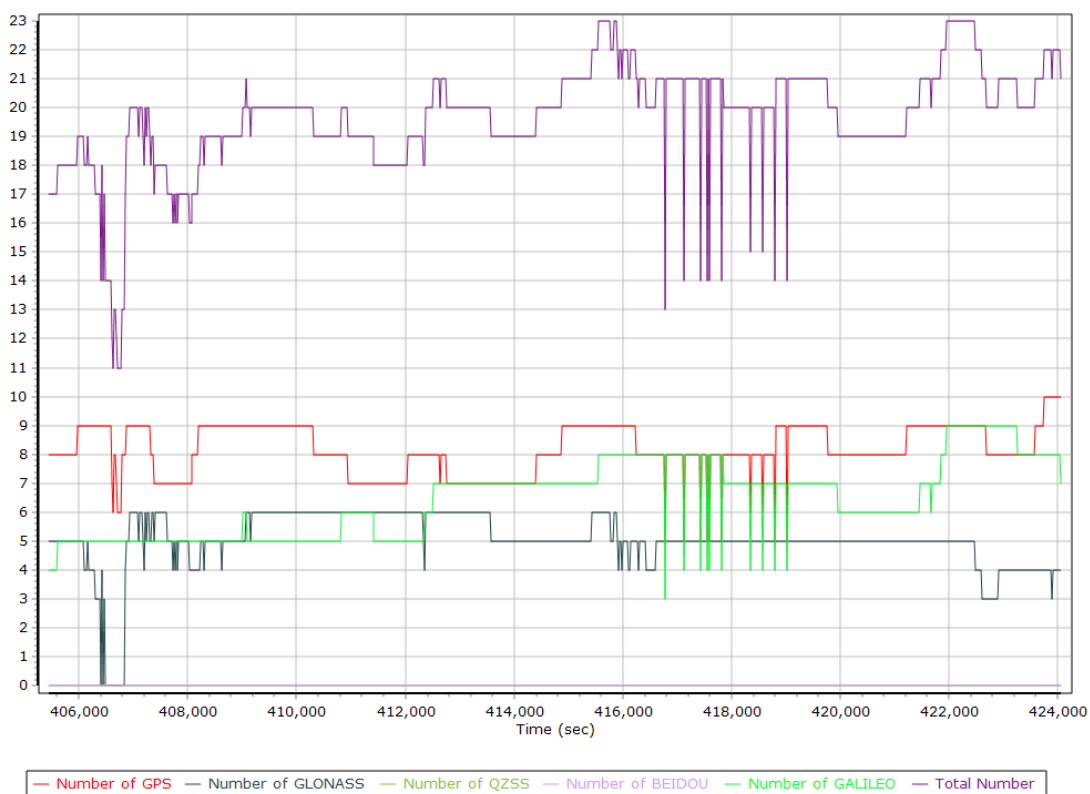


GNSS QC

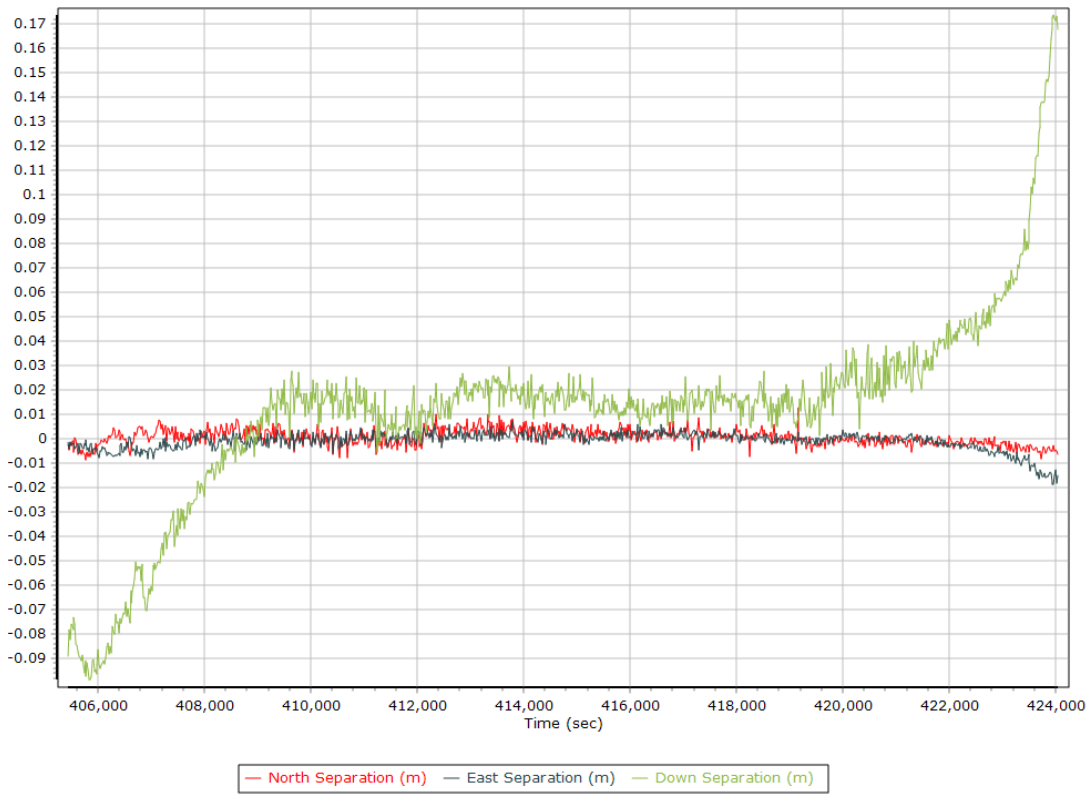
GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	5	10	8
Number of GLONASS SV	0	6	5
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	0	0
Number of GALILEO SV	3	9	6
Total number of SV	11	23	20
PDOP	1.01	2.46	1.27
QC Solution Gaps	0.00	0.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	18882.00	0.00	0.00
Percentage	100.00	0.00	0.00

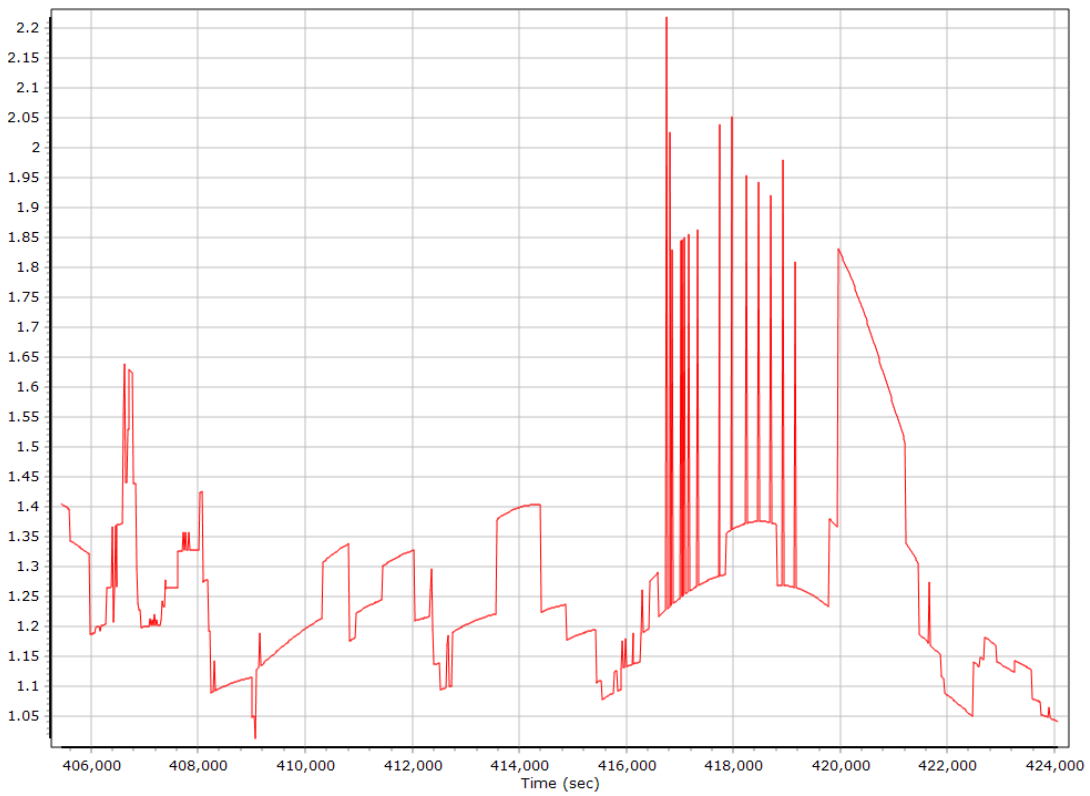
Num SVs in solution



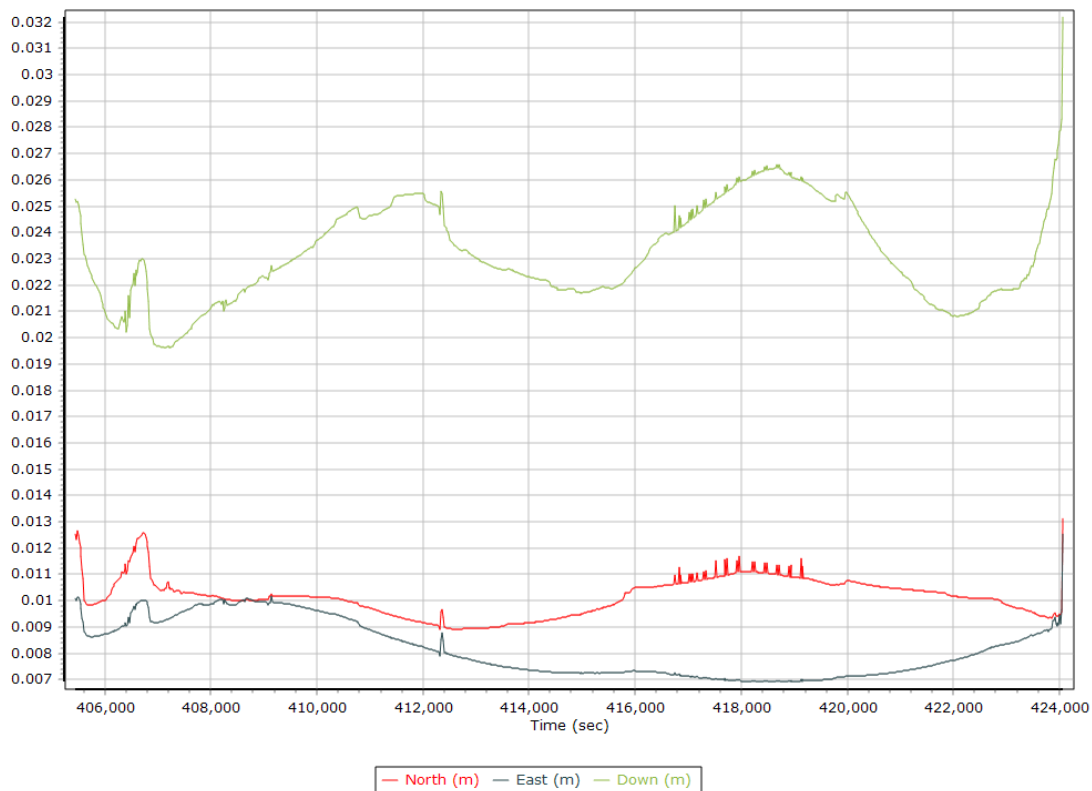
Forward/Reverse Separation



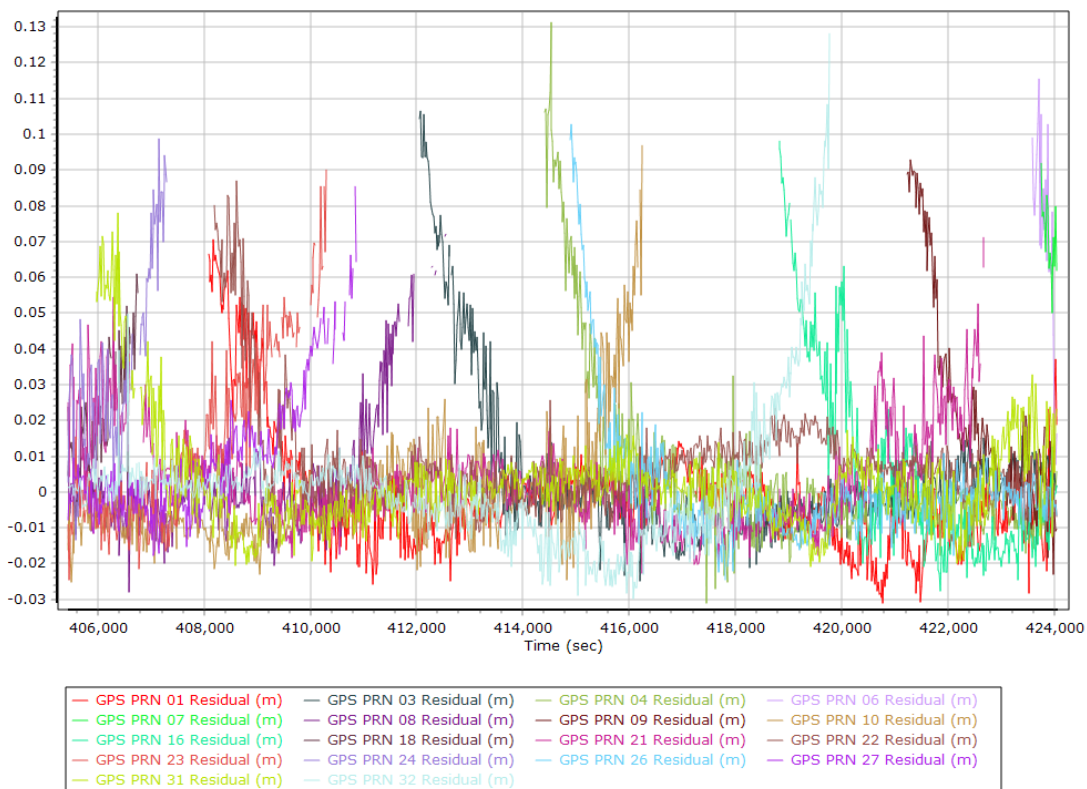
PDOP



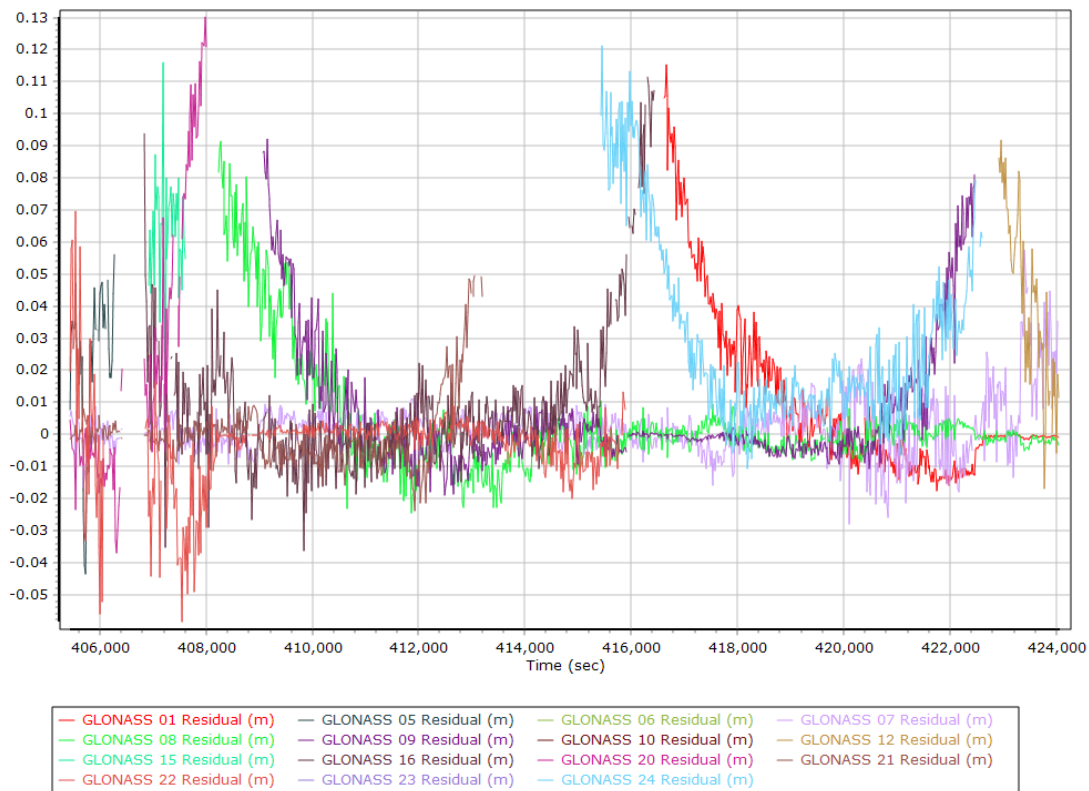
Estimated Position Accuracy



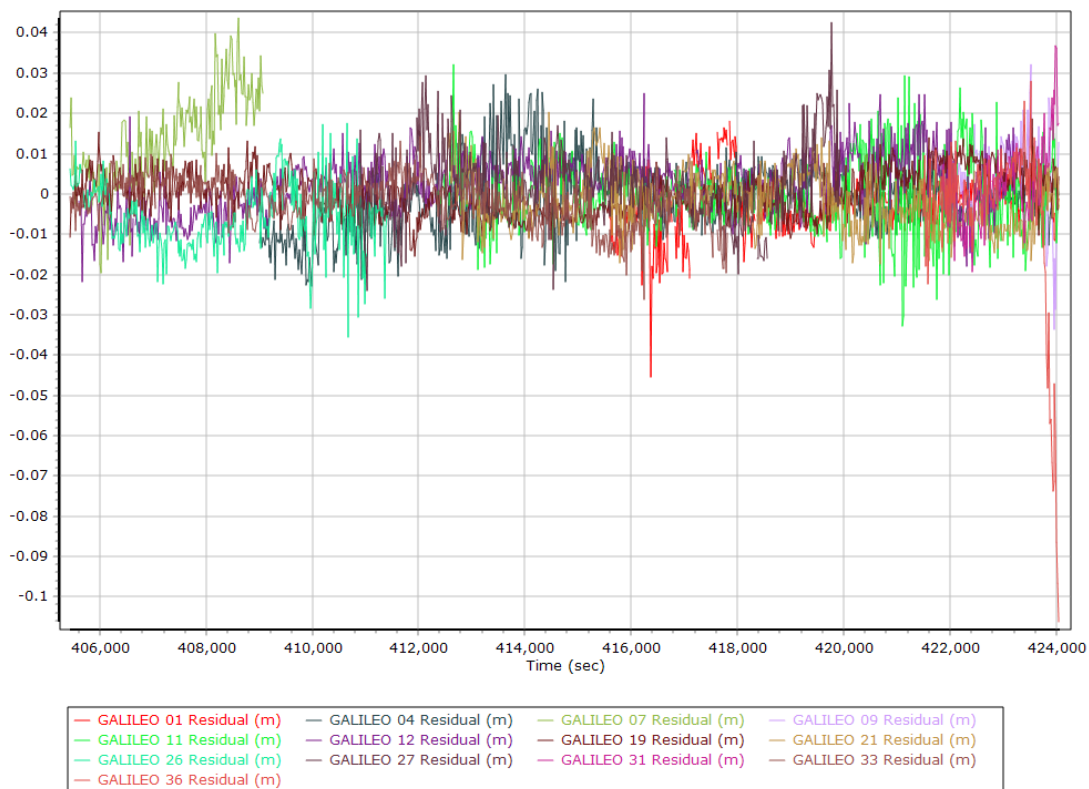
GPS Residuals



GLONASS Residuals



GALILEO Residuals



GNSS-Inertial Processor Configuration

Processing mode	IN-Fusion PP-RTX		
Stabilized mount	False		
Processing start time	405187.000 (11/11/2021 4:33:07 PM)		
Processing end time	424078.000 (11/11/2021 9:47:58 PM)		
Initial attitude source	Real-Time VNAV/RNAV Attitude		
IMU Sensor Context	Processing with Onboard IMU		
Reference to IMU lever arm (m)	0.000	0.000	0.000
Reference to IMU mounting angles (deg)	0.000	0.000	180.000
Reference to Primary GNSS lever arm (m)	0.382	-0.427	-1.083
Reference to Primary GNSS lever arm std dev (m)	0.030	0.030	0.030
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

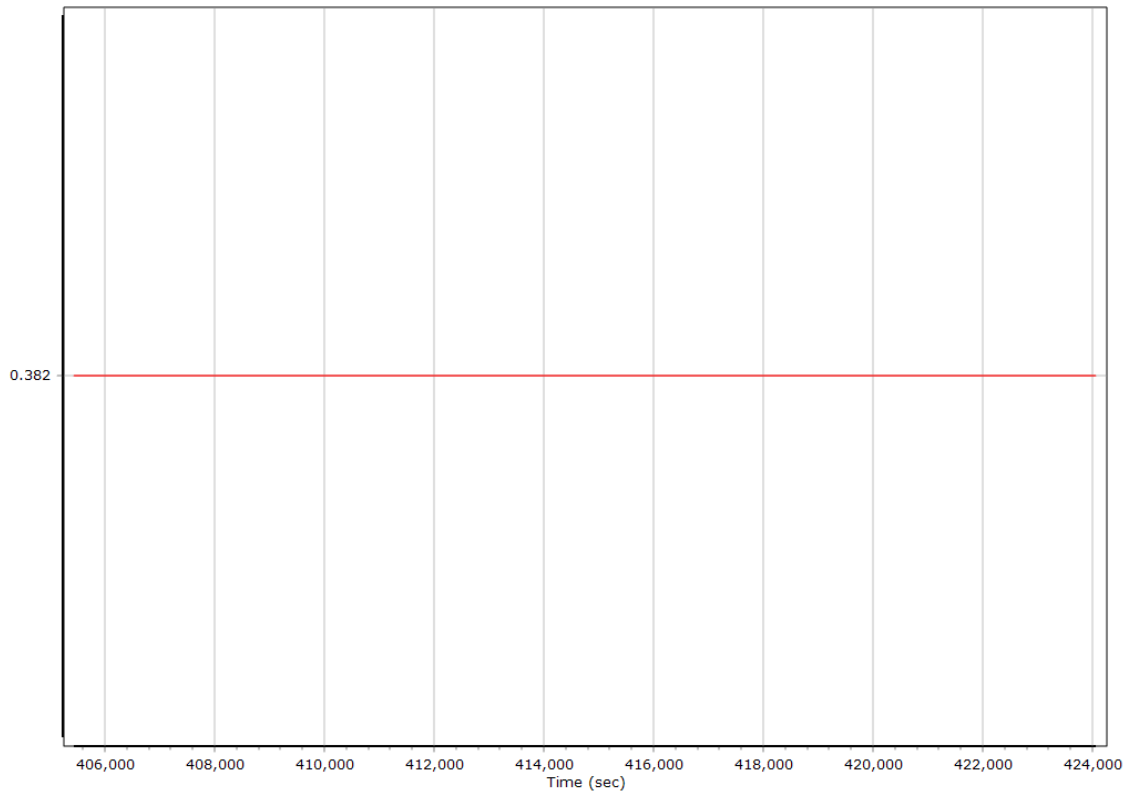
Calibrated Installation Parameters

Reference-Primary GNSS Lever Arm (m)

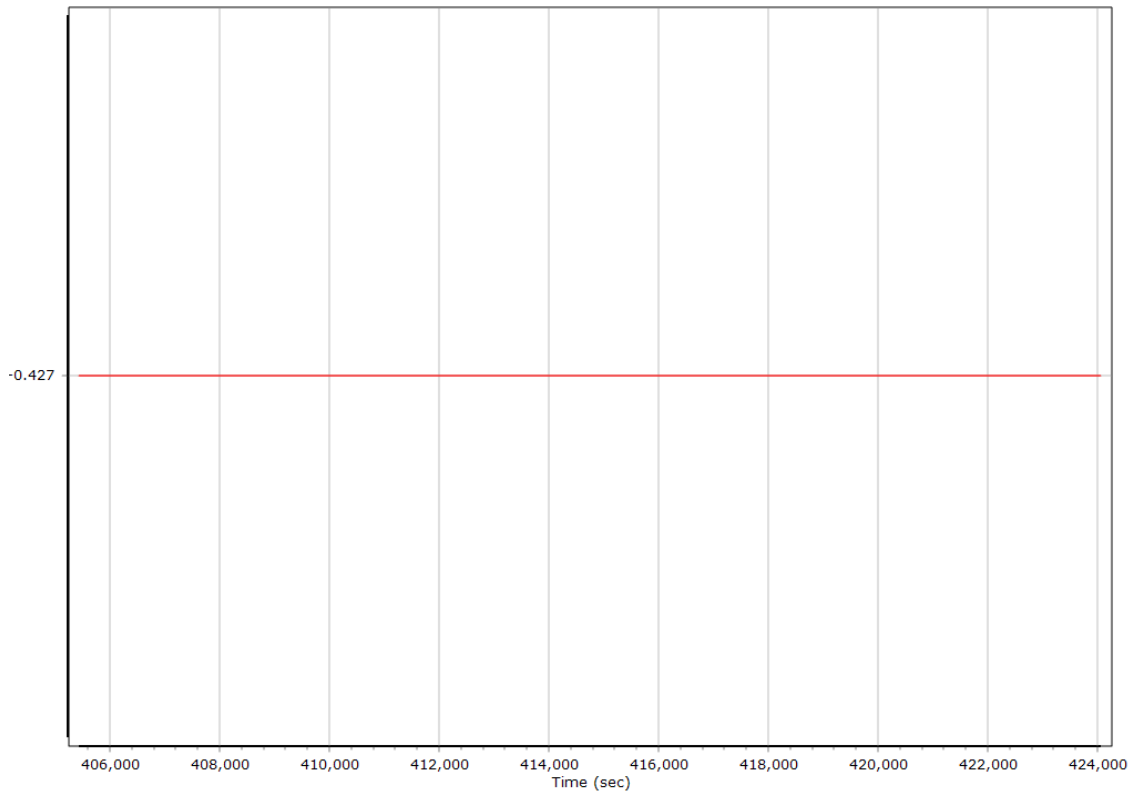
Reference-Primary GNSS Lever Arm Automatic Calibration Results

Original Reference to Primary GNSS lever arm (m)	0.388	-0.417	-1.086
Iteration 1 Reference to Primary GNSS lever arm (m)	0.382	-0.426	-1.083
Iteration 2 Reference to Primary GNSS lever arm (m)	0.382	-0.427	-1.083
Primary GNSS Lever Arm In use	Iteration 2		

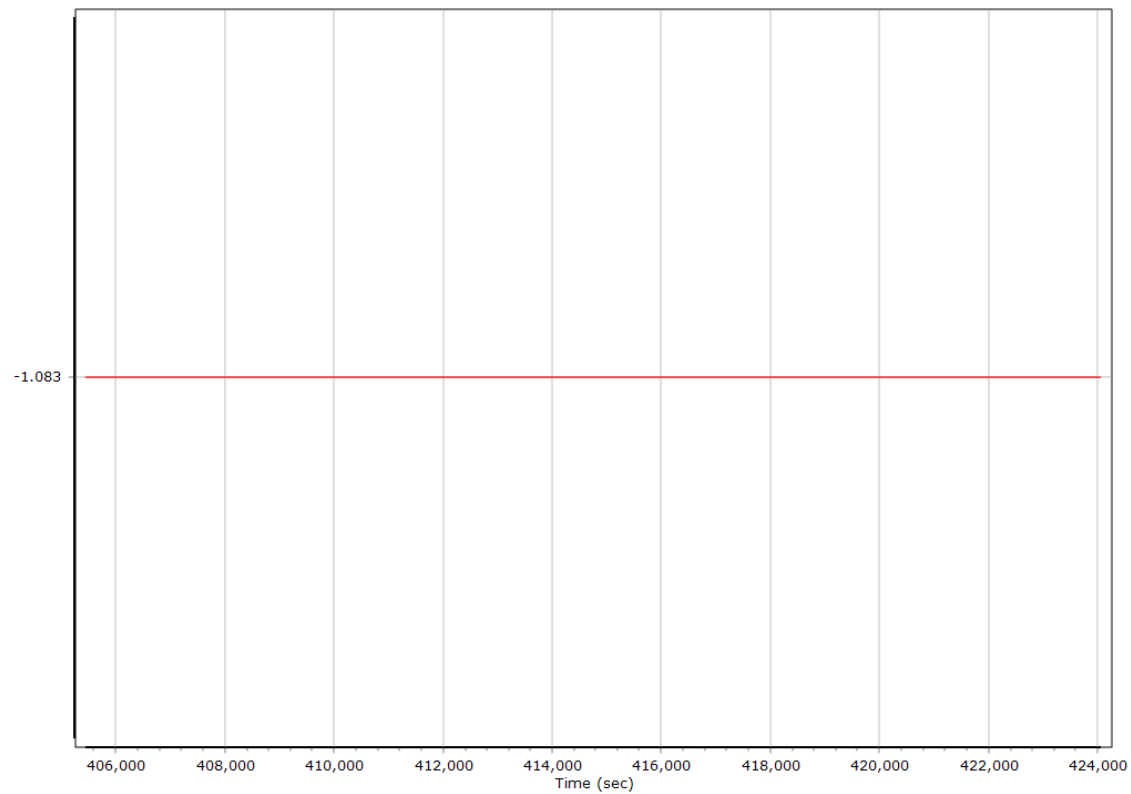
X Reference-Primary GNSS Lever Arm (m)



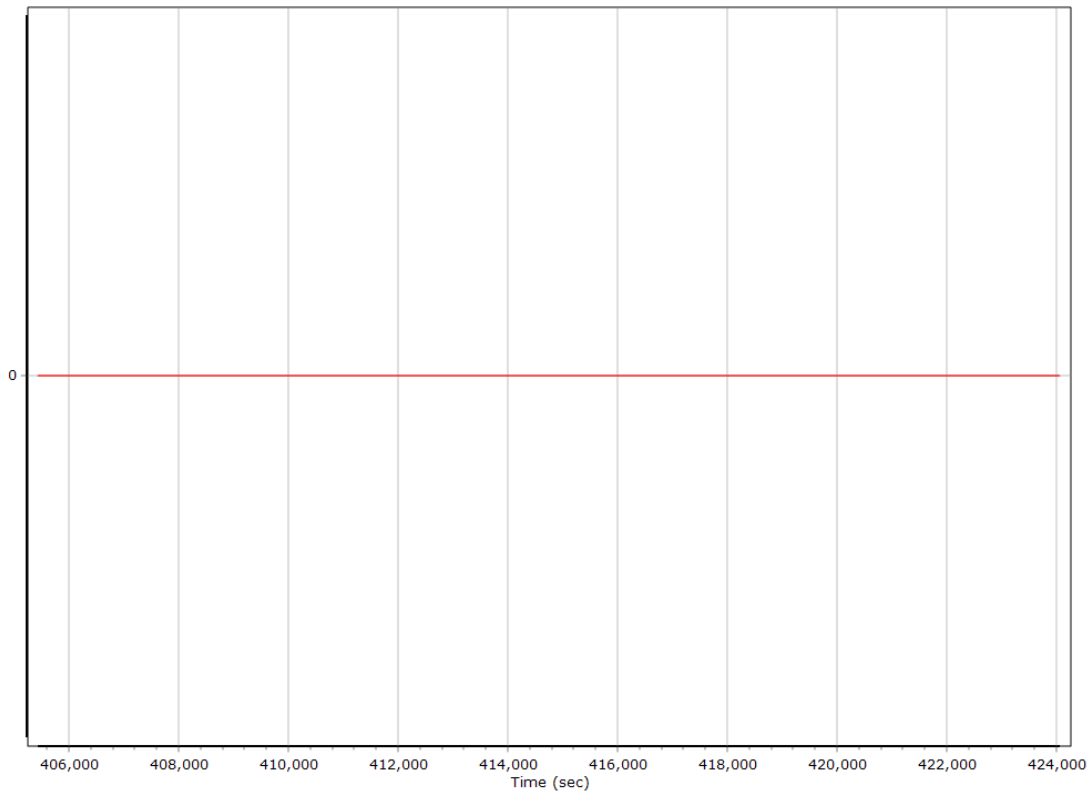
Y Reference-Primary GNSS Lever Arm (m)



Z Reference-Primary GNSS Lever Arm (m)



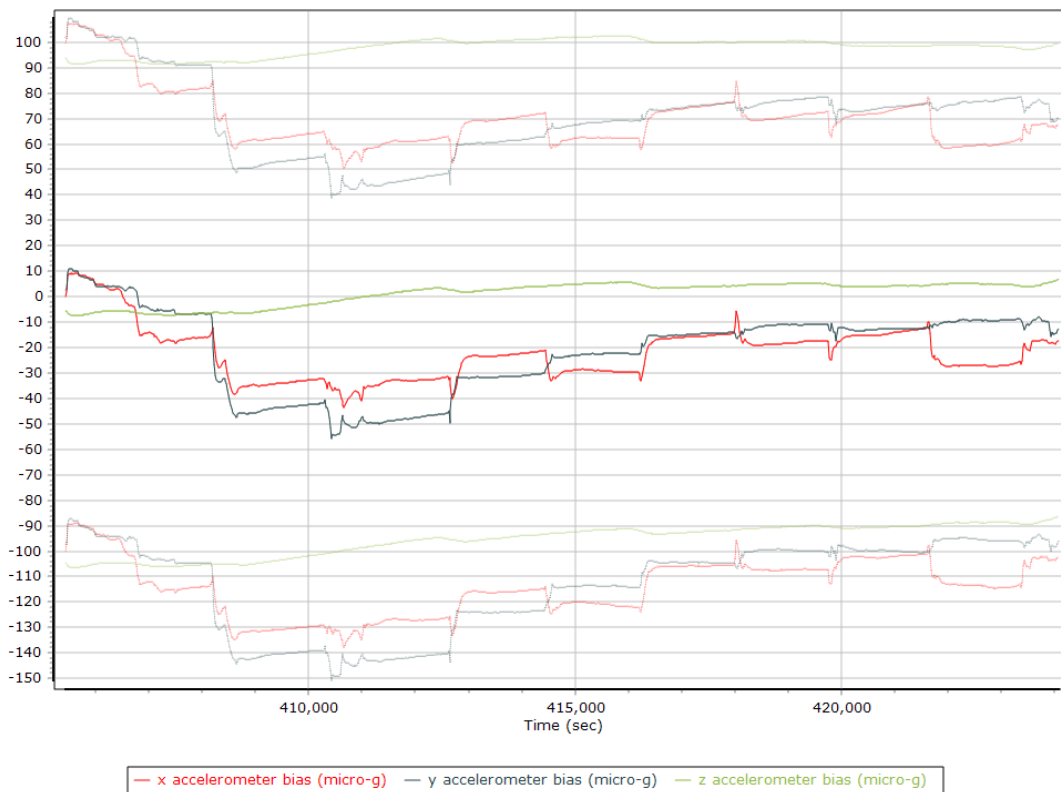
Reference-Primary GNSS Lever Arm Figure of Merit



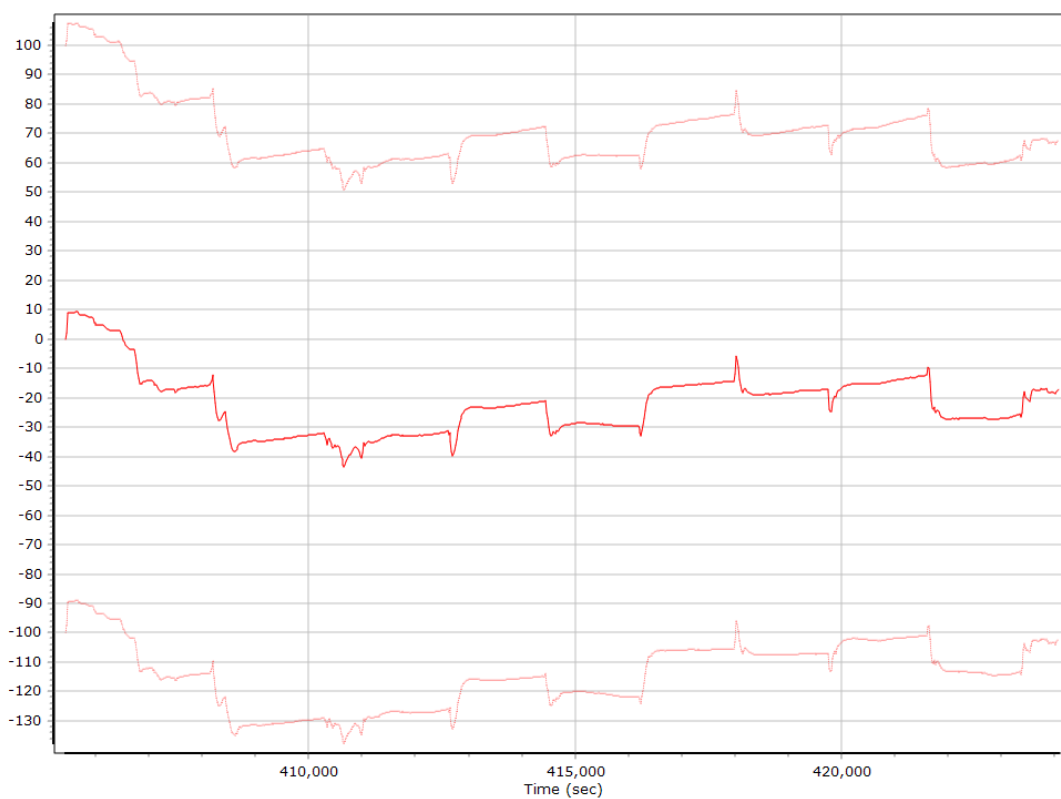
IN-Fusion QC

Forward Processed Estimated Errors, Reference Frame

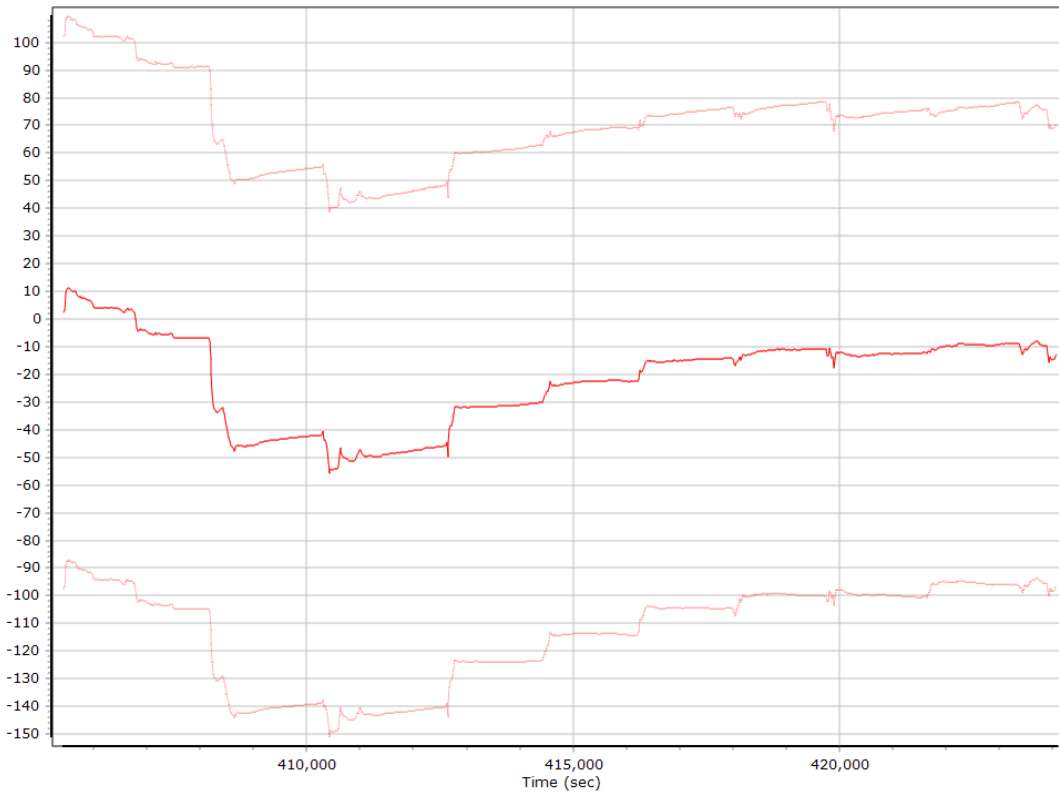
Accelerometer Bias (micro-g)



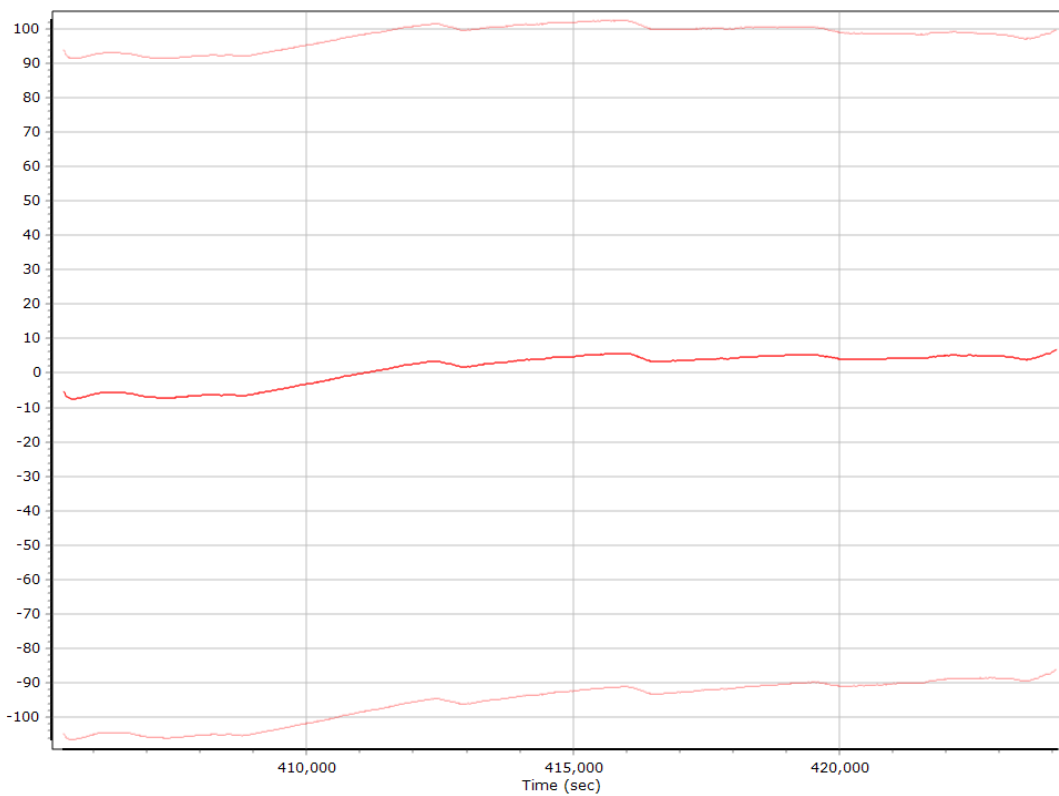
X Accelerometer Bias (micro-g)



Y Accelerometer Bias (micro-g)



Z Accelerometer Bias (micro-g)



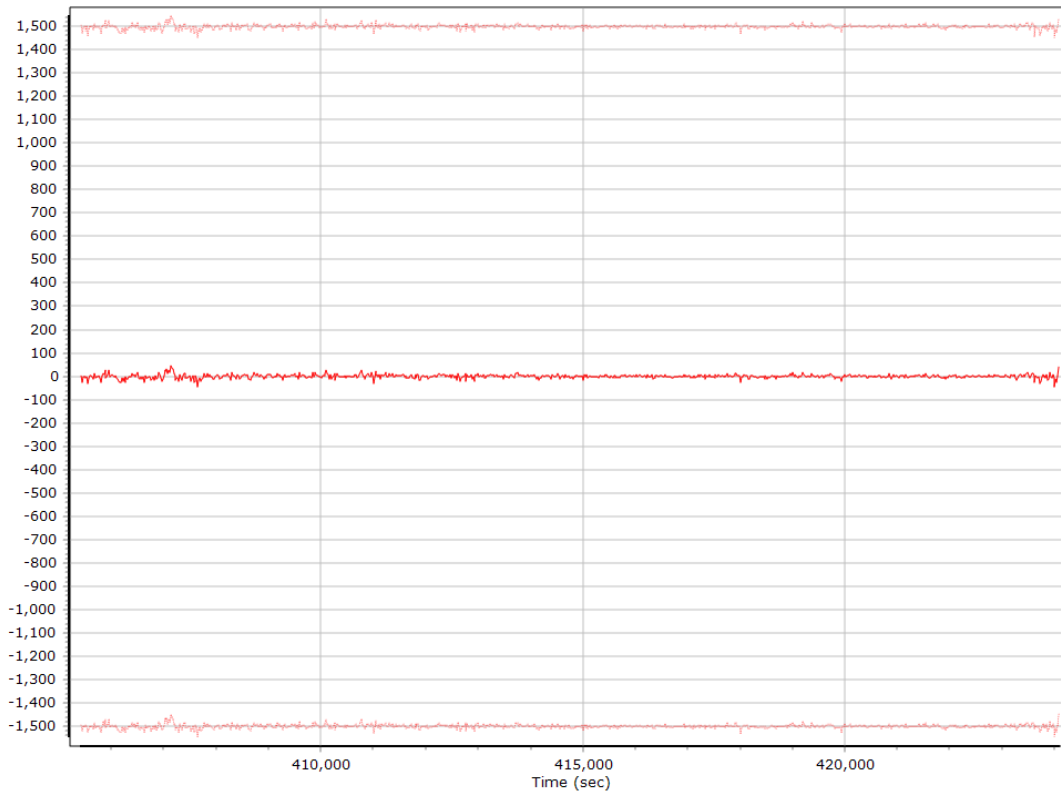
Accelerometer Scale Error (ppm)



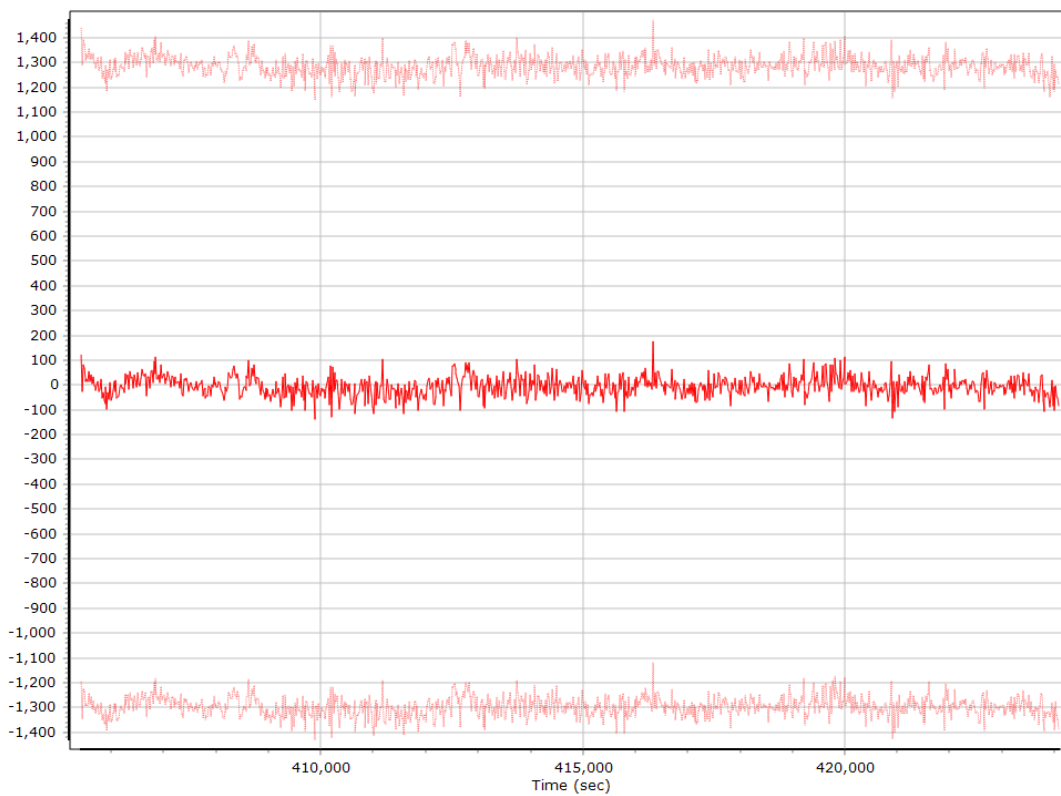
X Accelerometer Scale Error (ppm)



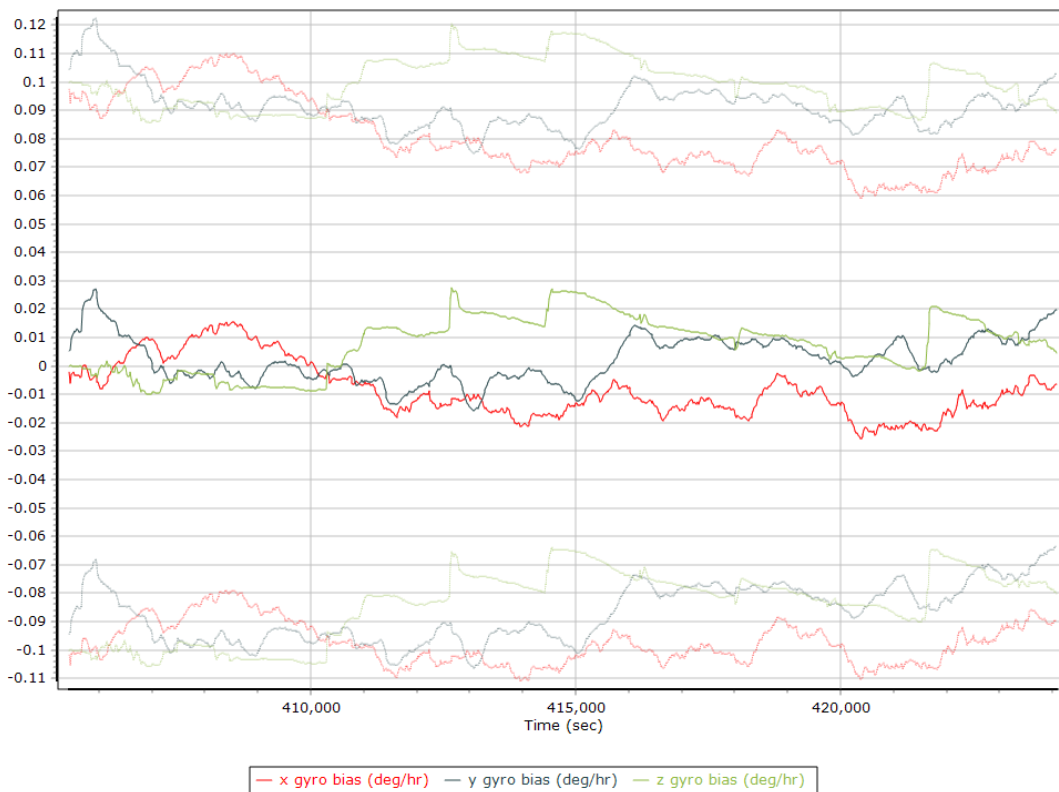
Y Accelerometer Scale Error (ppm)



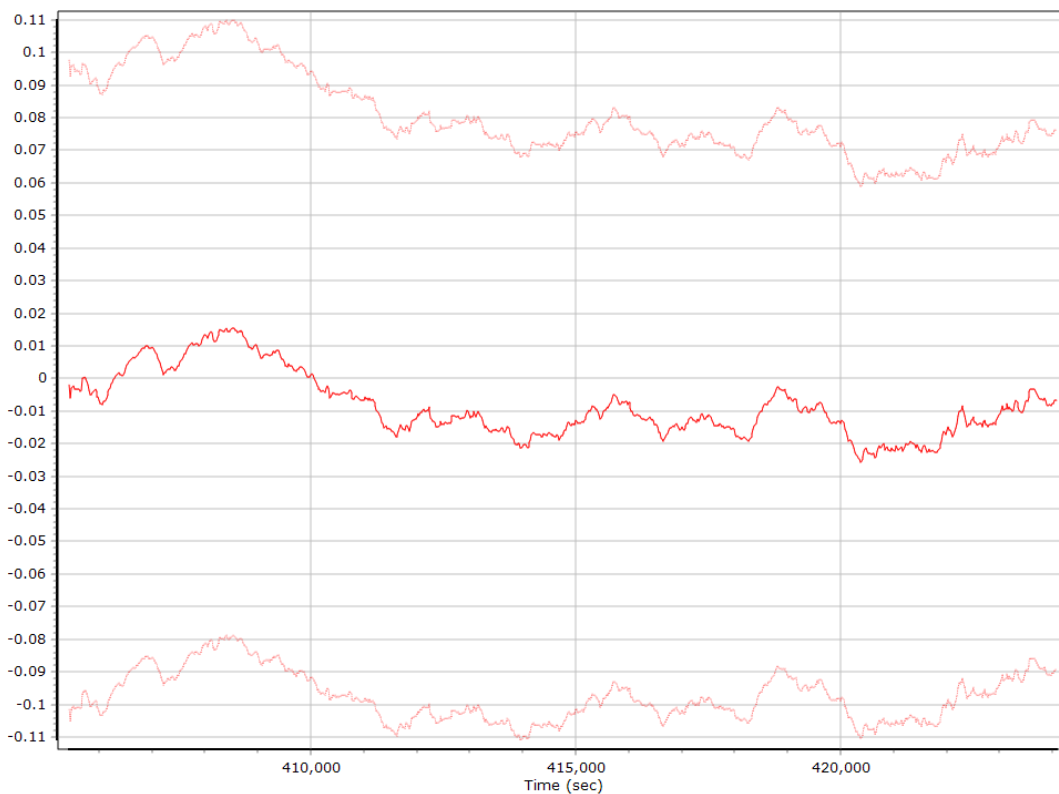
Z Accelerometer Scale Error (ppm)



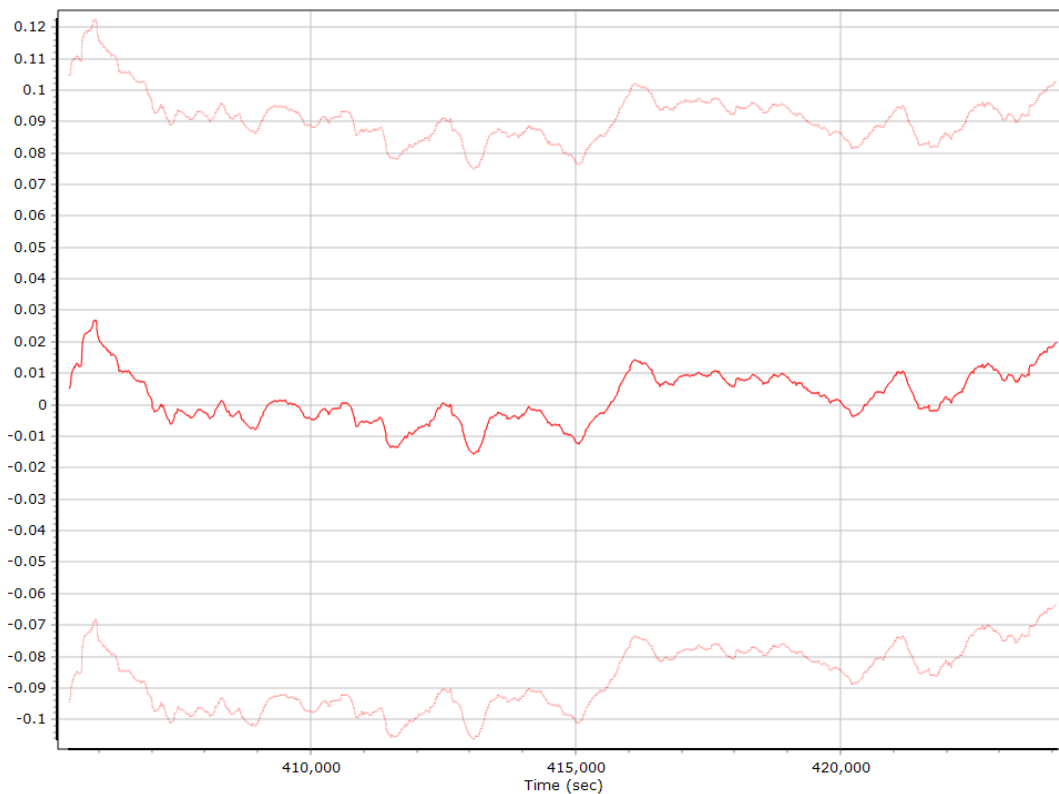
Gyro Bias (deg/h)



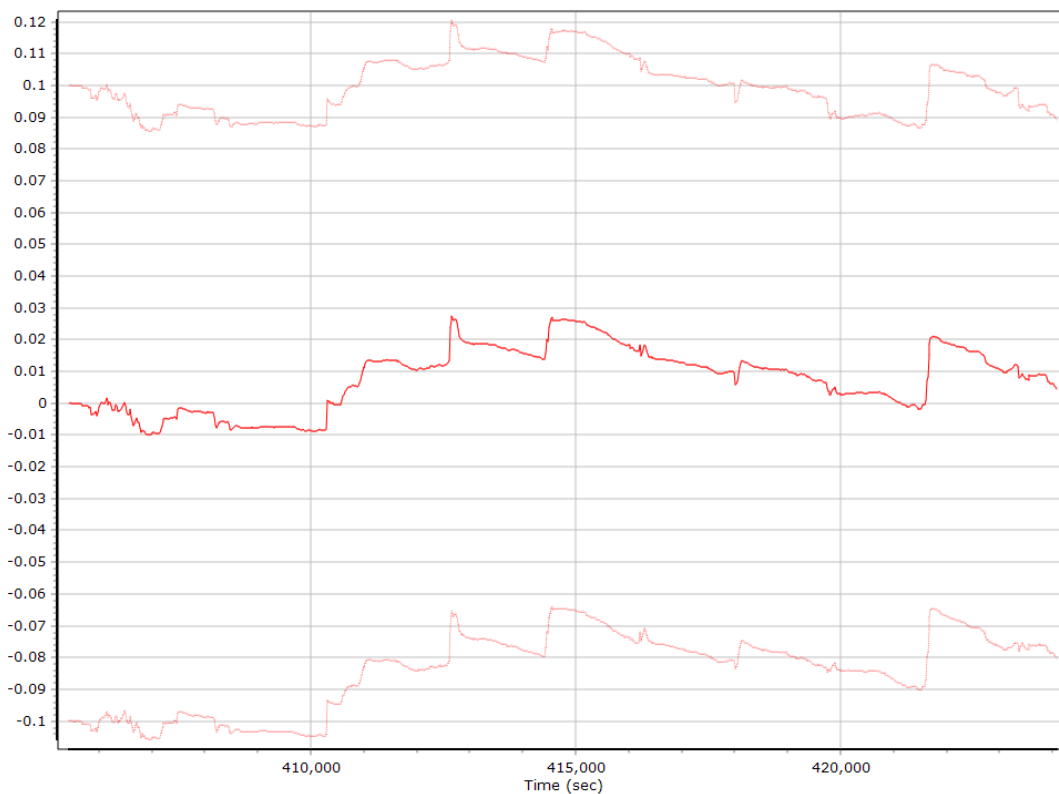
X Gyro Bias (deg/h)



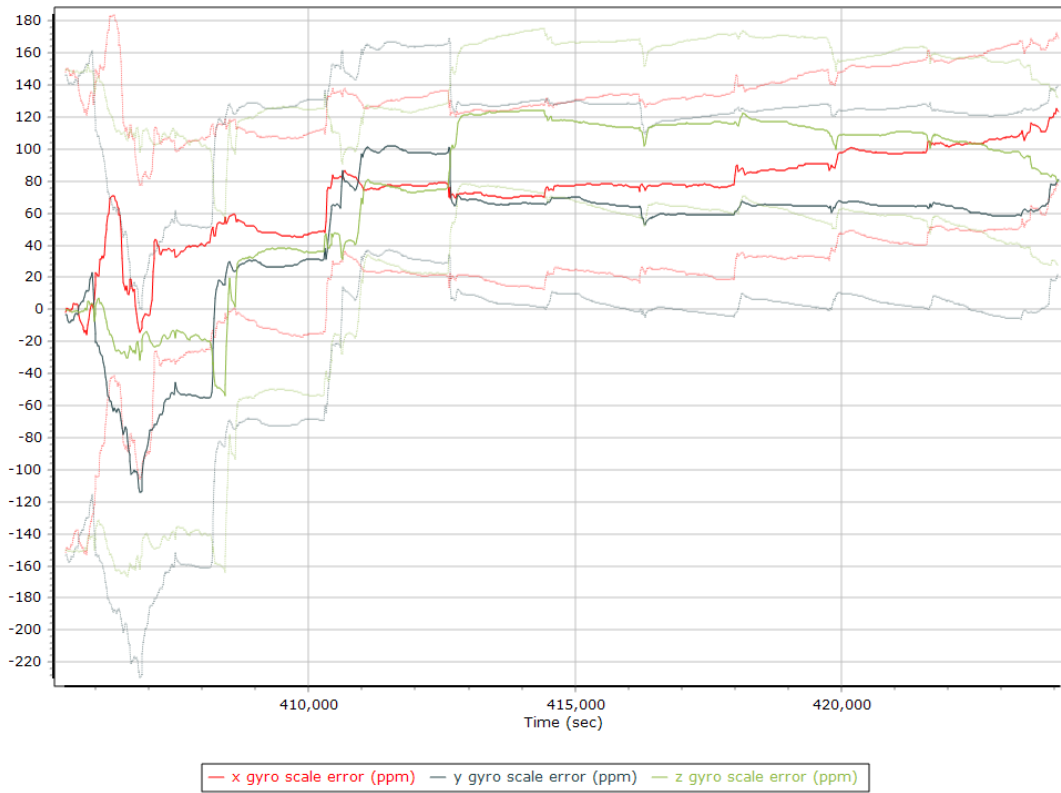
Y Gyro Bias (deg/h)



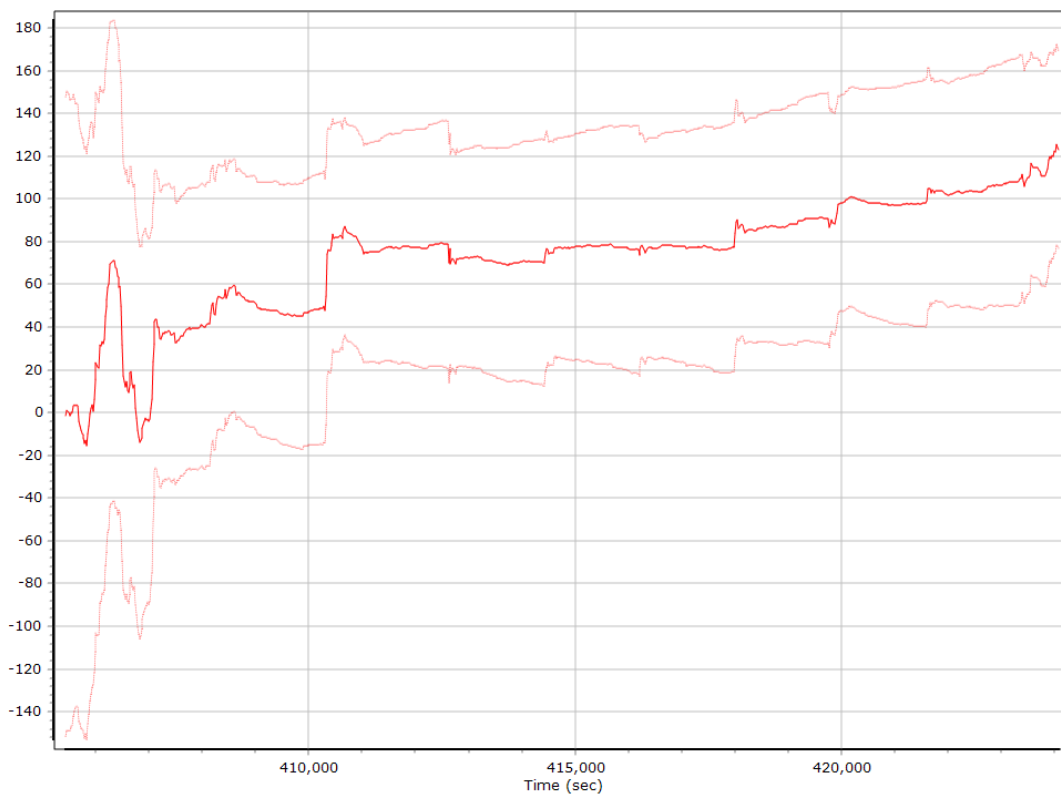
Z Gyro Bias (deg/h)



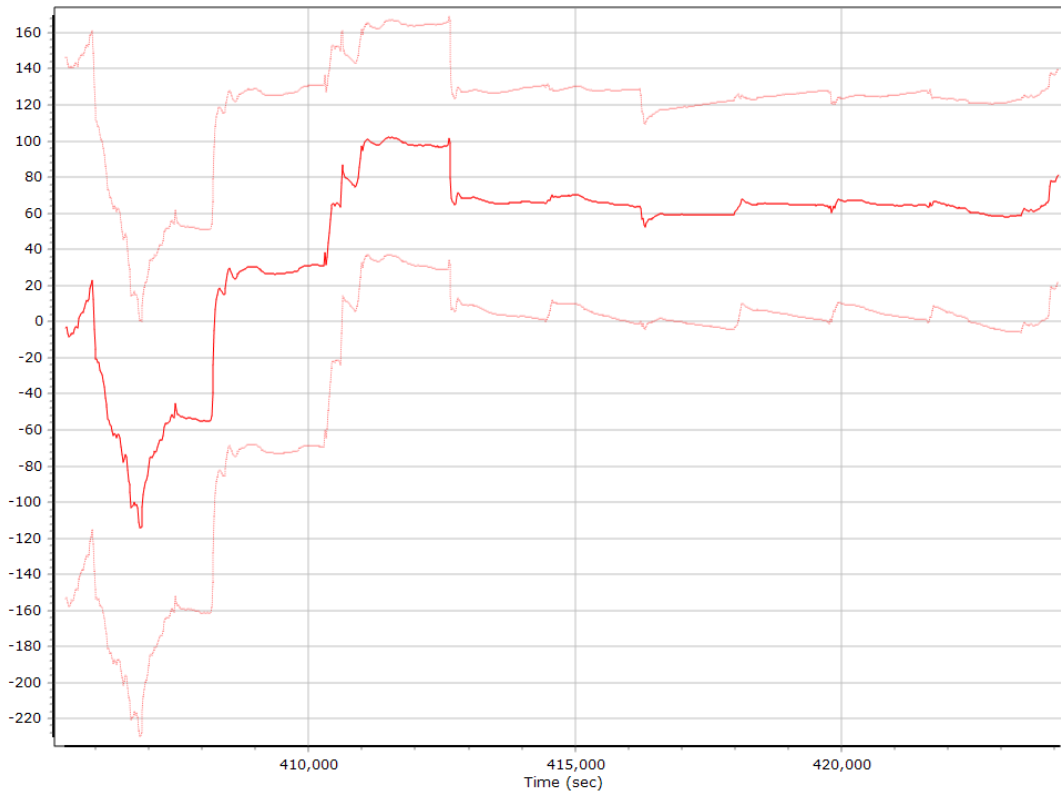
Gyro Scale Error (ppm)



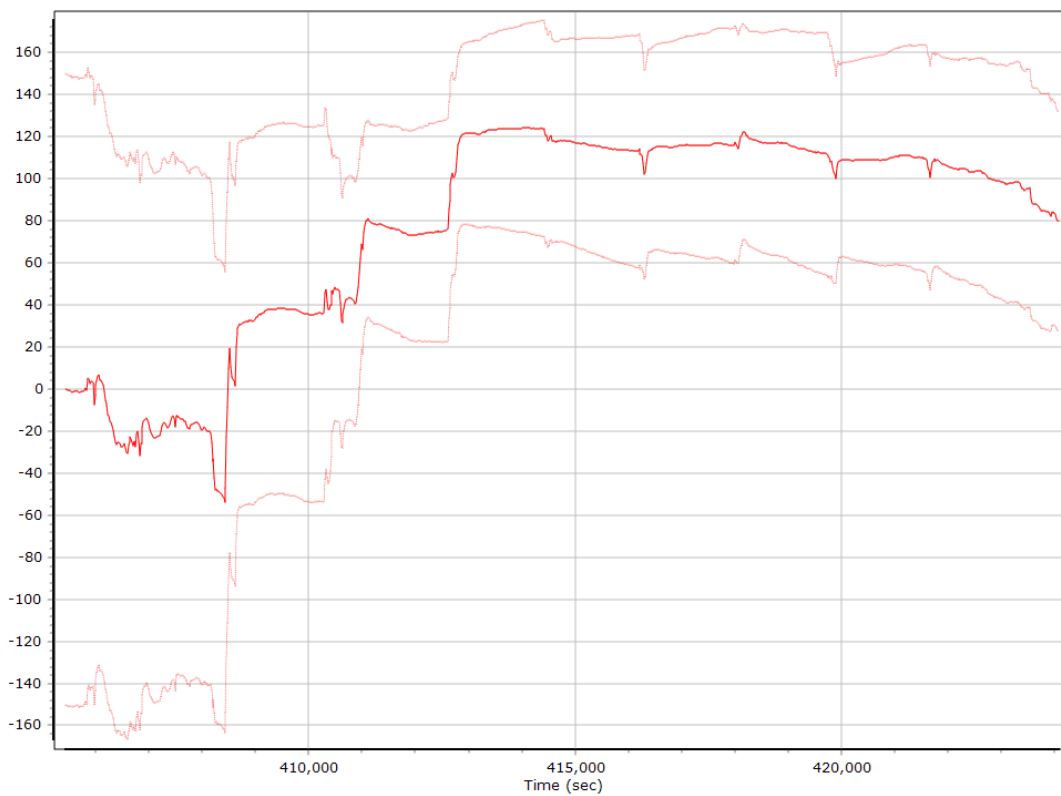
X Gyro Scale Error (ppm)



Y Gyro Scale Error (ppm)

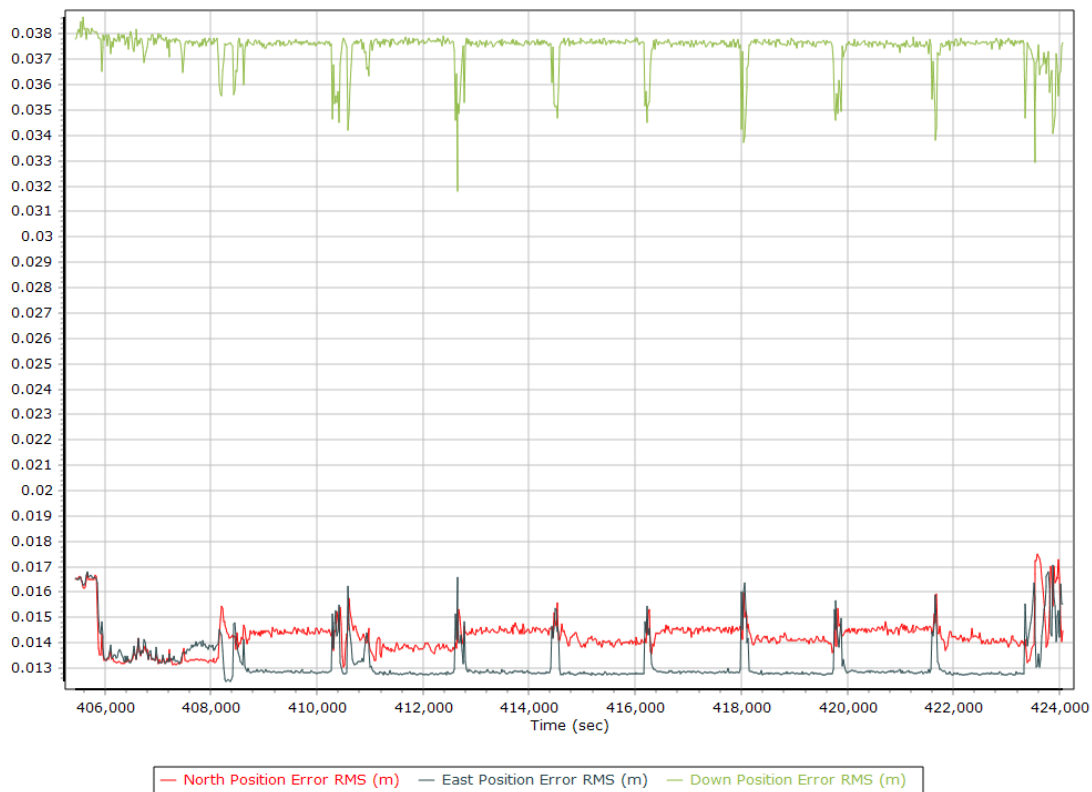


Z Gyro Scale Error (ppm)

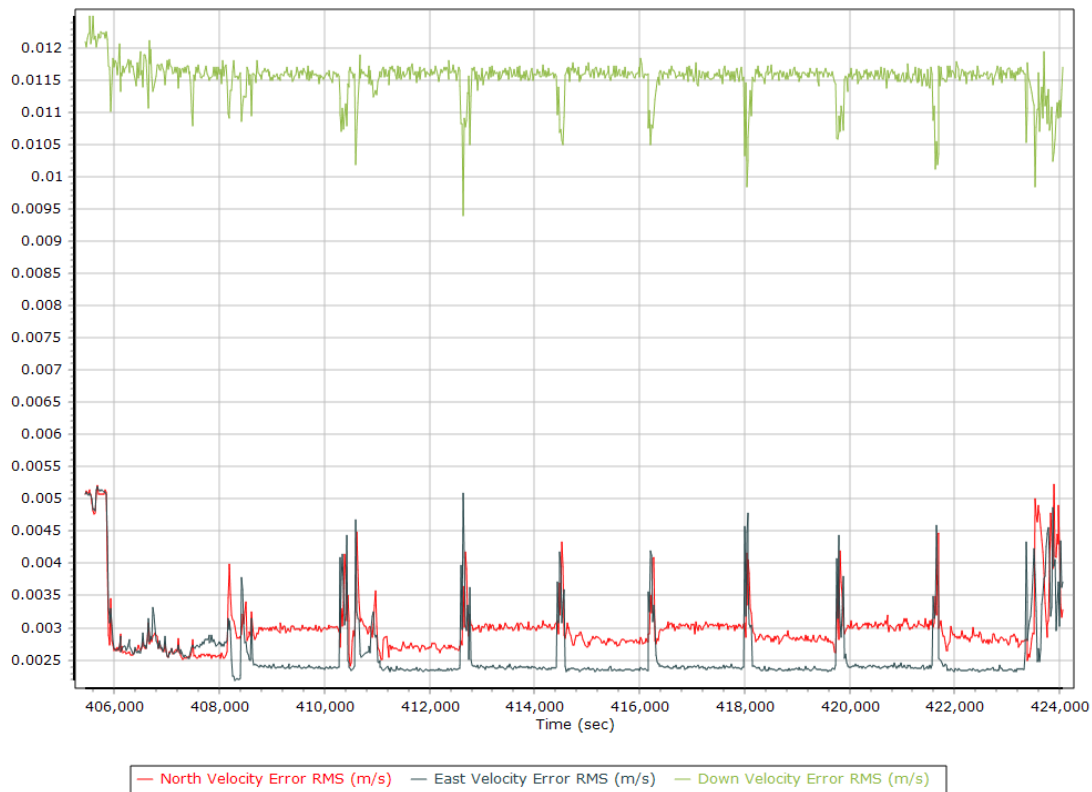


Smoothed Performance Metrics

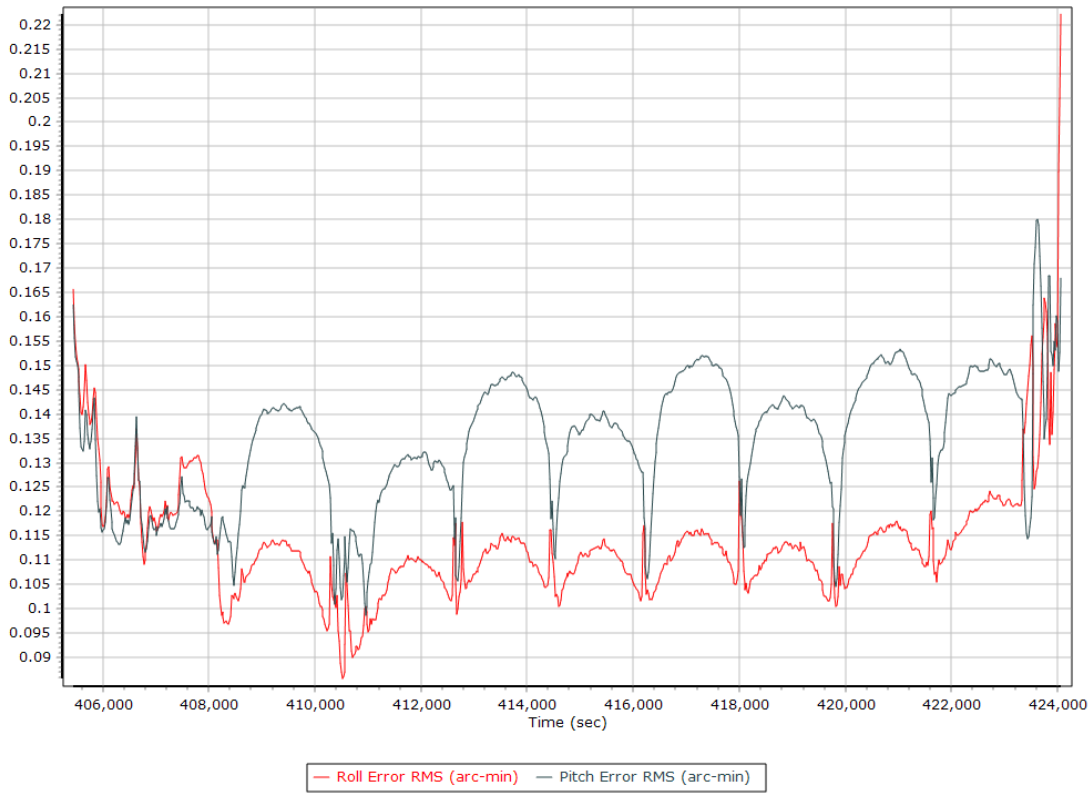
Position Error RMS (m)



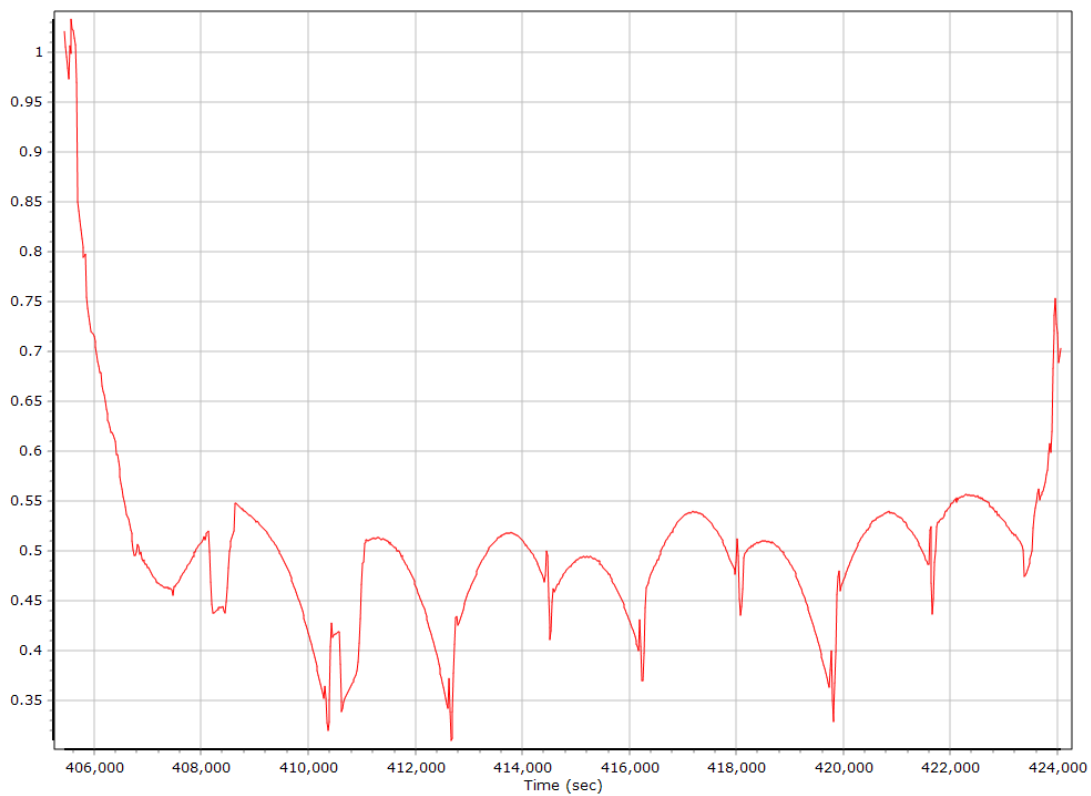
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

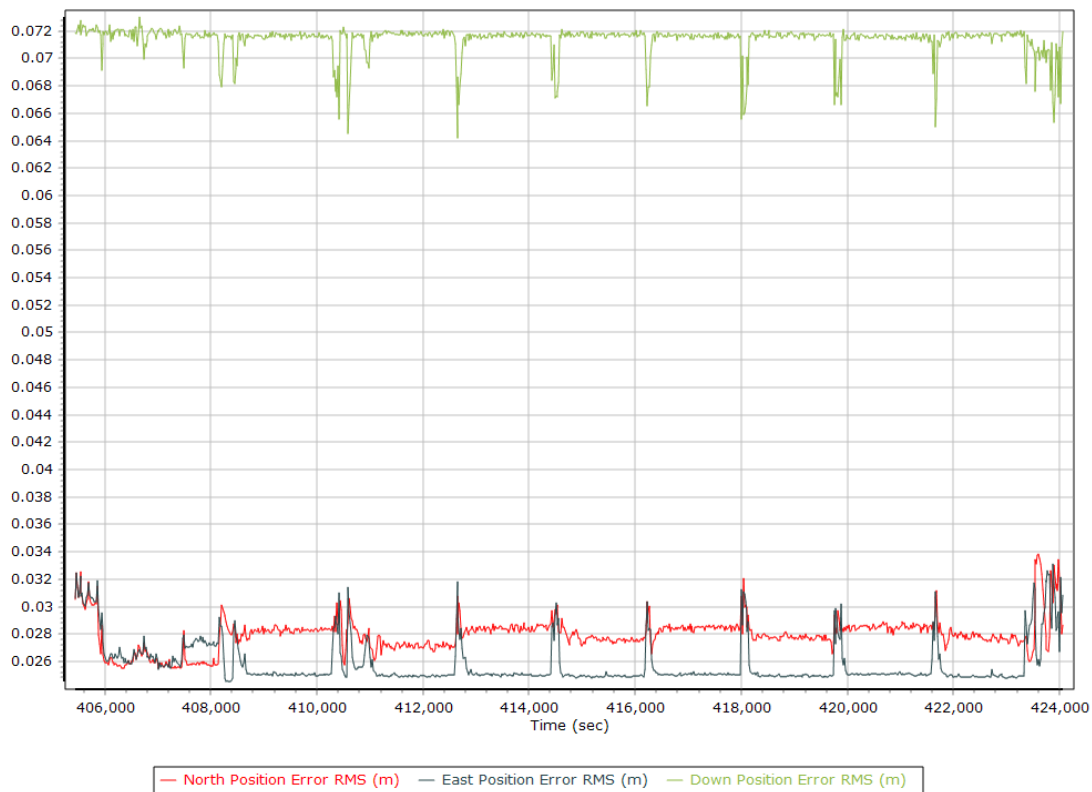


Heading Error RMS (arc-min)

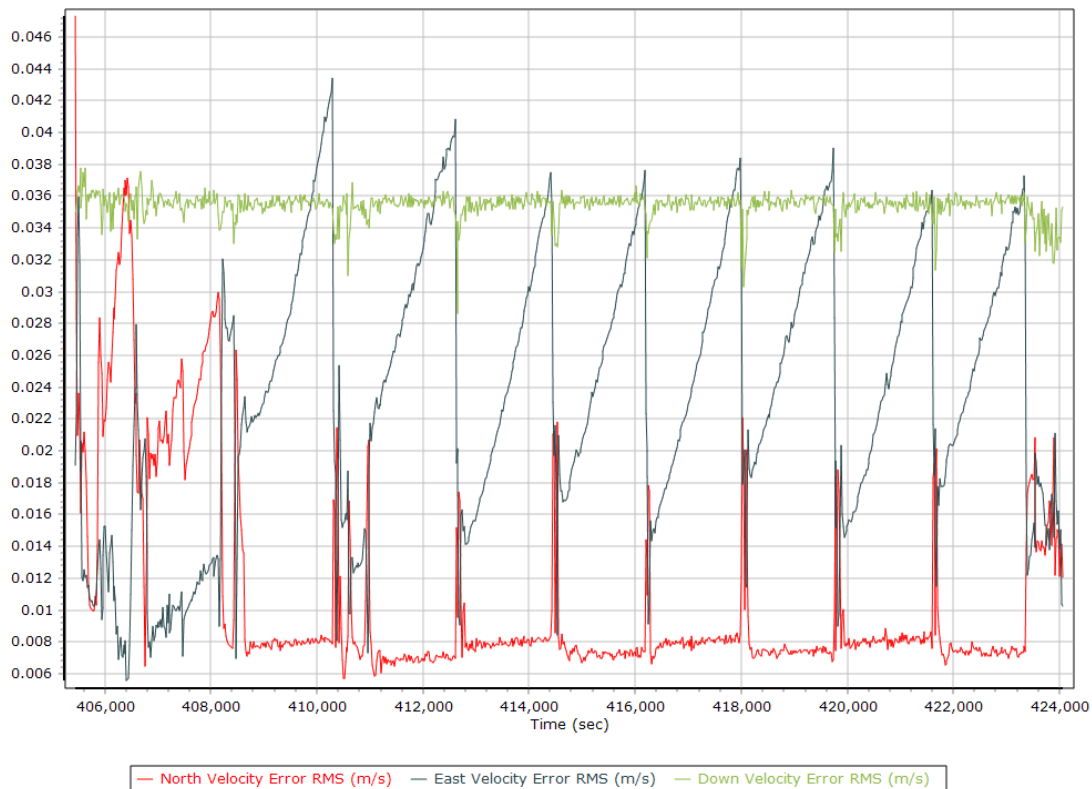


Forward Processed Performance Metrics

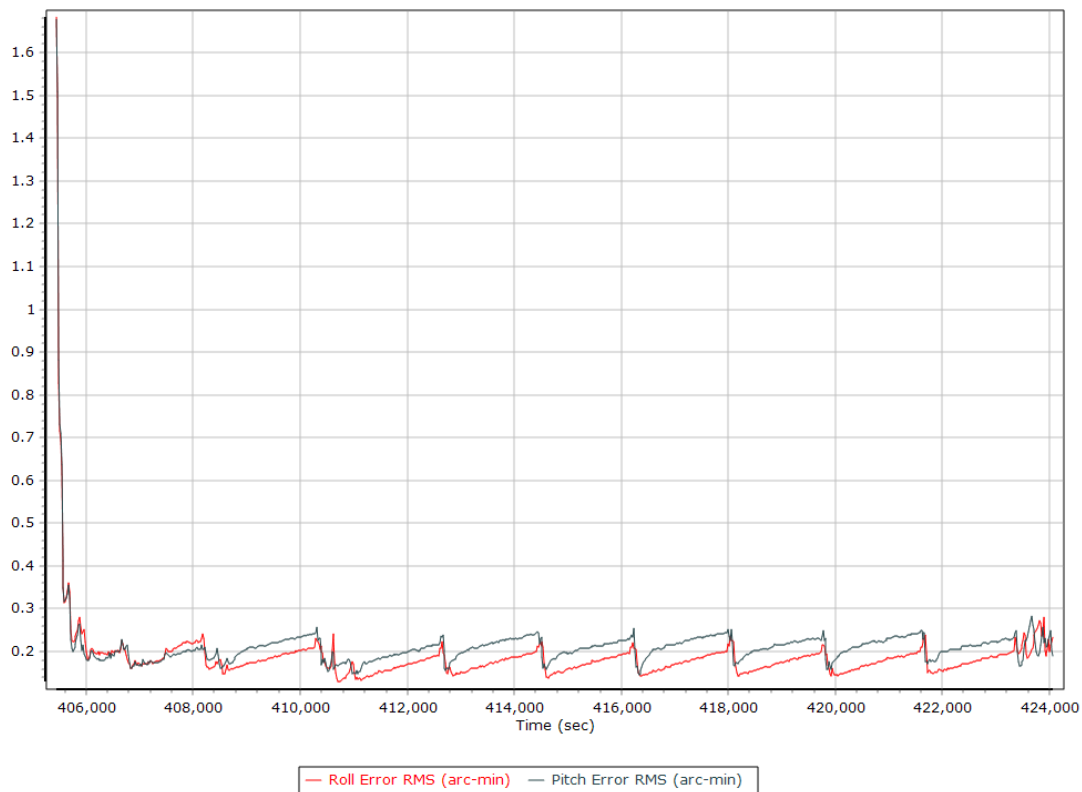
Position Error RMS (m)



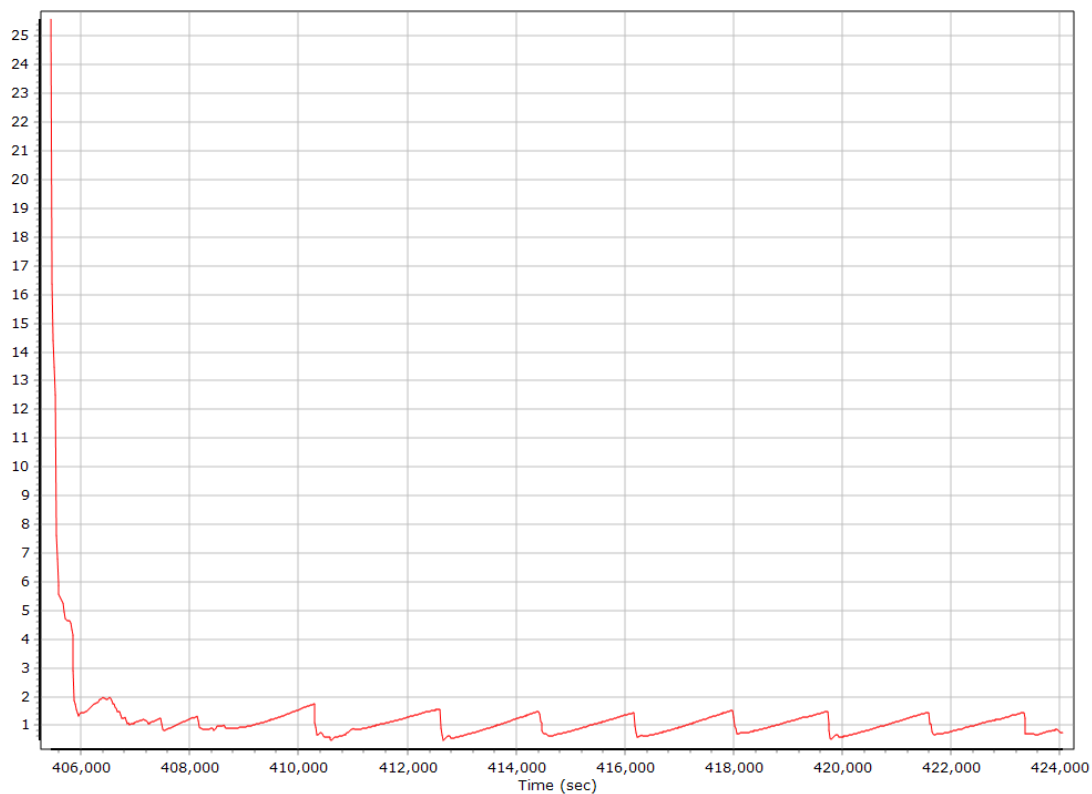
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

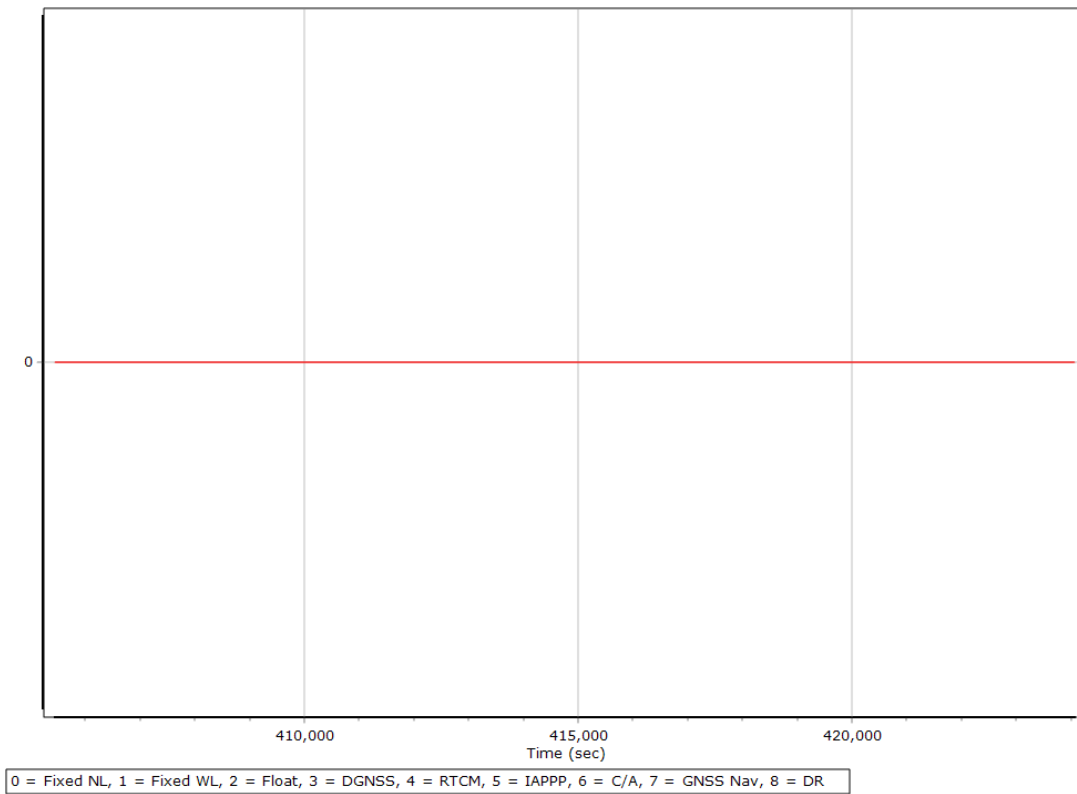


Heading Error RMS (arc-min)

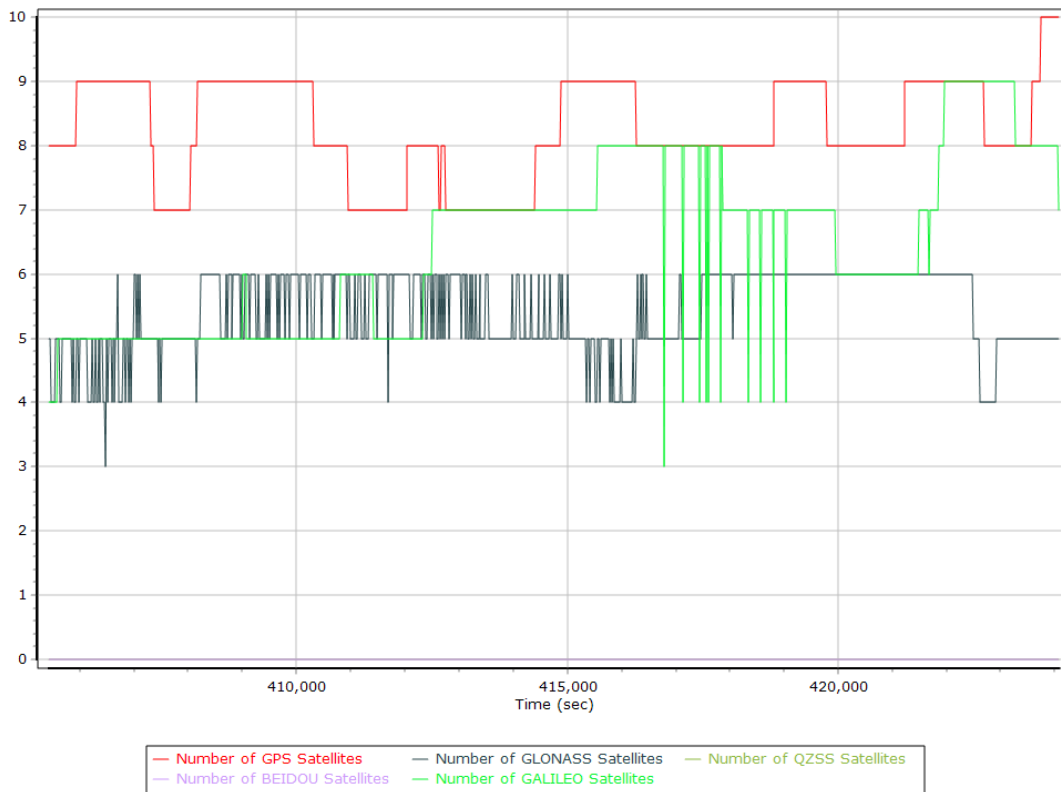


Forward Processed Solution Status

Processing Mode



Number of Satellites



Baseline Length

