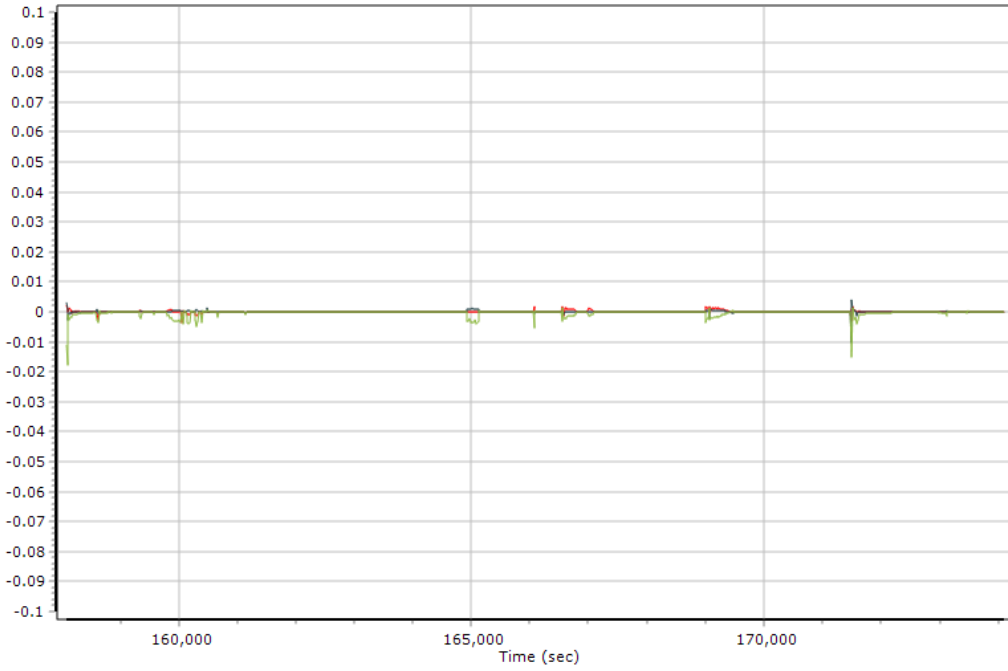


1 Appendix B - GPS and IMU Processing Reports for Each Mission

MISSION: 2SU18351A

Timing

Start	<input type="text" value="158062.389"/>	Data	Incr. (sec)	^
End	<input type="text" value="174126.108"/>	Output Record	0.005000	
<input type="checkbox"/> Entire time interval		IMU	0.005000	
<input checked="" type="checkbox"/> Seconds of start week		Primary GNSS	1.000000	v
UTC Offset	<input type="text" value="18.000"/>			



— North (m) — East (m) — Down (m) — DR mode

Disable Satellites

GPS | GLONASS | BEIDOU | QZSS

<input type="checkbox"/> PRN 1	<input type="checkbox"/> PRN 10	<input type="checkbox"/> PRN 19	<input type="checkbox"/> PRN 28
<input type="checkbox"/> PRN 2	<input type="checkbox"/> PRN 11	<input type="checkbox"/> PRN 20	<input type="checkbox"/> PRN 29
<input type="checkbox"/> PRN 3	<input type="checkbox"/> PRN 12	<input type="checkbox"/> PRN 21	<input type="checkbox"/> PRN 30
<input type="checkbox"/> PRN 4	<input type="checkbox"/> PRN 13	<input type="checkbox"/> PRN 22	<input type="checkbox"/> PRN 31
<input type="checkbox"/> PRN 5	<input type="checkbox"/> PRN 14	<input type="checkbox"/> PRN 23	<input type="checkbox"/> PRN 32
<input type="checkbox"/> PRN 6	<input type="checkbox"/> PRN 15	<input type="checkbox"/> PRN 24	
<input type="checkbox"/> PRN 7	<input type="checkbox"/> PRN 16	<input type="checkbox"/> PRN 25	
<input type="checkbox"/> PRN 8	<input type="checkbox"/> PRN 17	<input type="checkbox"/> PRN 26	
<input type="checkbox"/> PRN 9	<input type="checkbox"/> PRN 18	<input type="checkbox"/> PRN 27	

< [Progress Bar] >

Elevation Mask Angle

Force GPS Only

Disable Satellites

GPS

GLONASS

BEIDOU

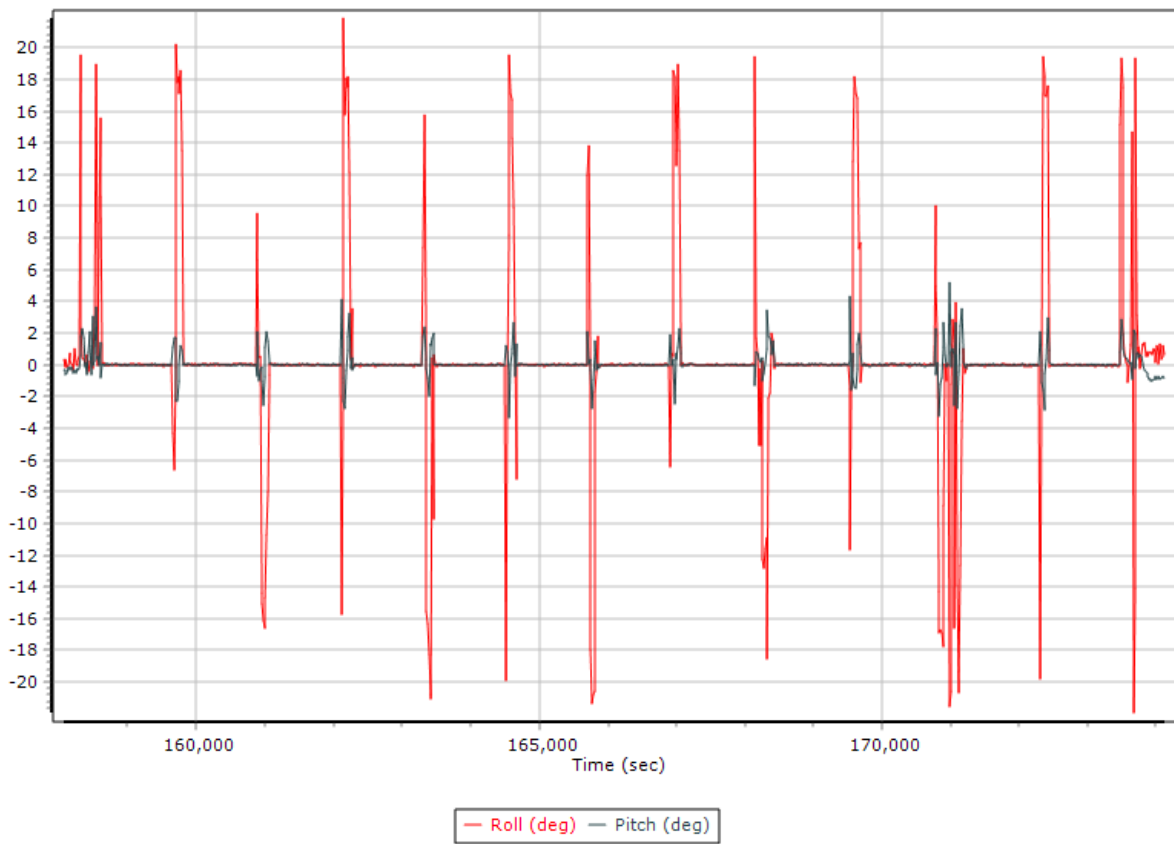
QZSS

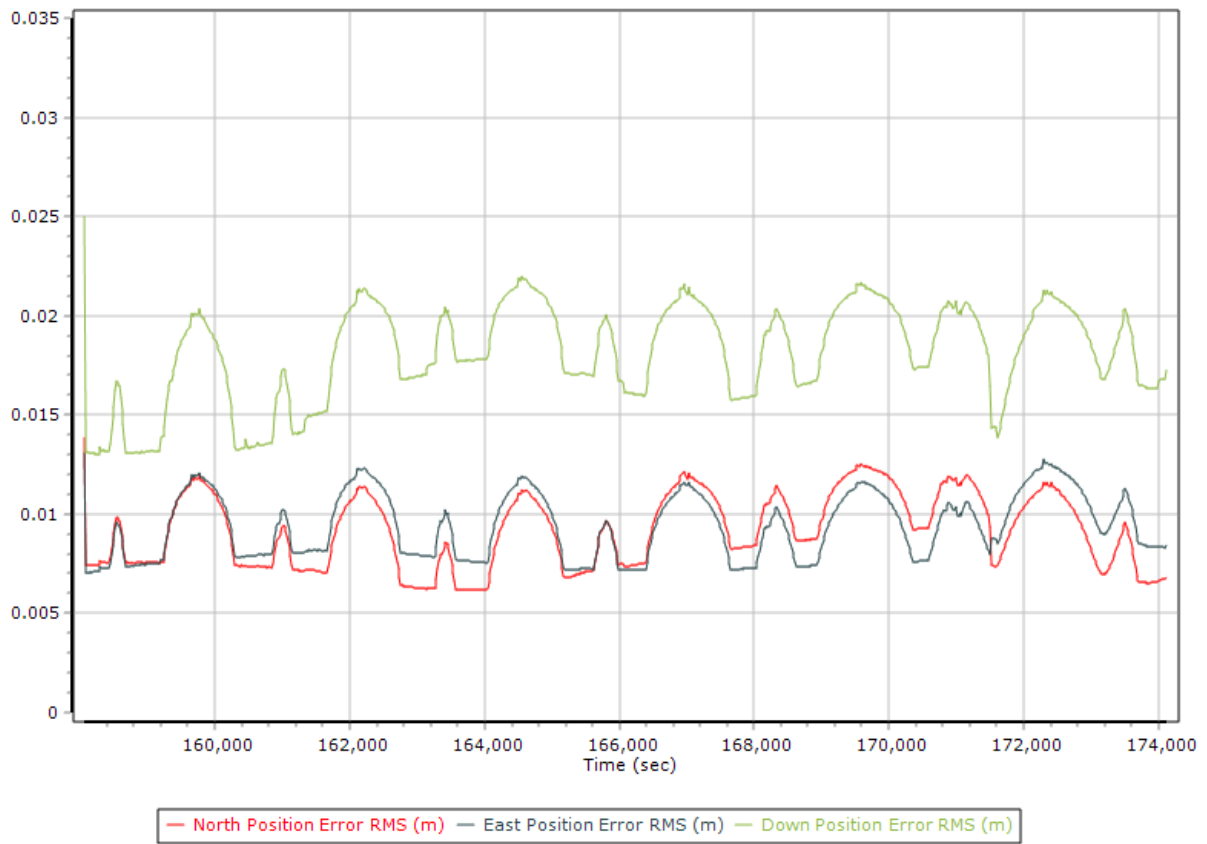
- | | | |
|---------------------------------|----------------------------------|----------------------------------|
| <input type="checkbox"/> SLOT 1 | <input type="checkbox"/> SLOT 10 | <input type="checkbox"/> SLOT 19 |
| <input type="checkbox"/> SLOT 2 | <input type="checkbox"/> SLOT 11 | <input type="checkbox"/> SLOT 20 |
| <input type="checkbox"/> SLOT 3 | <input type="checkbox"/> SLOT 12 | <input type="checkbox"/> SLOT 21 |
| <input type="checkbox"/> SLOT 4 | <input type="checkbox"/> SLOT 13 | <input type="checkbox"/> SLOT 22 |
| <input type="checkbox"/> SLOT 5 | <input type="checkbox"/> SLOT 14 | <input type="checkbox"/> SLOT 23 |
| <input type="checkbox"/> SLOT 6 | <input type="checkbox"/> SLOT 15 | <input type="checkbox"/> SLOT 24 |
| <input type="checkbox"/> SLOT 7 | <input type="checkbox"/> SLOT 16 | |
| <input type="checkbox"/> SLOT 8 | <input type="checkbox"/> SLOT 17 | |
| <input type="checkbox"/> SLOT 9 | <input type="checkbox"/> SLOT 18 | |

Elevation Mask Angle

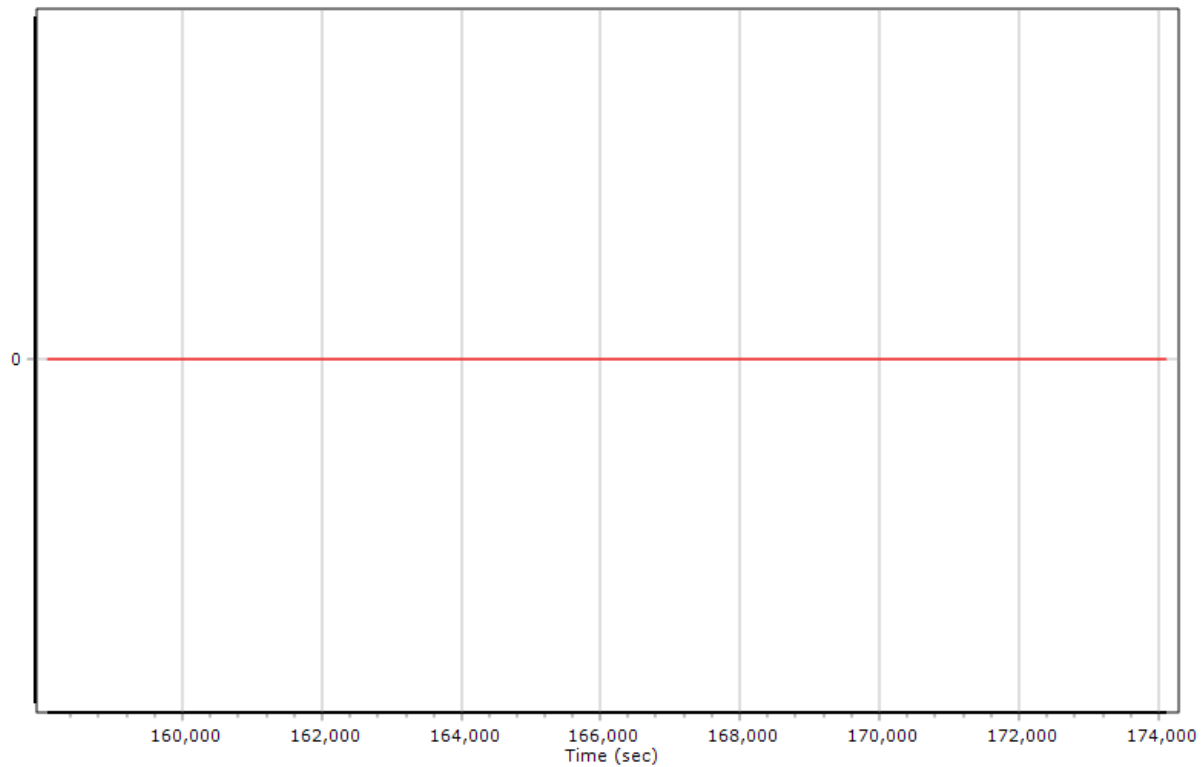
10.000 deg

Force GPS Only



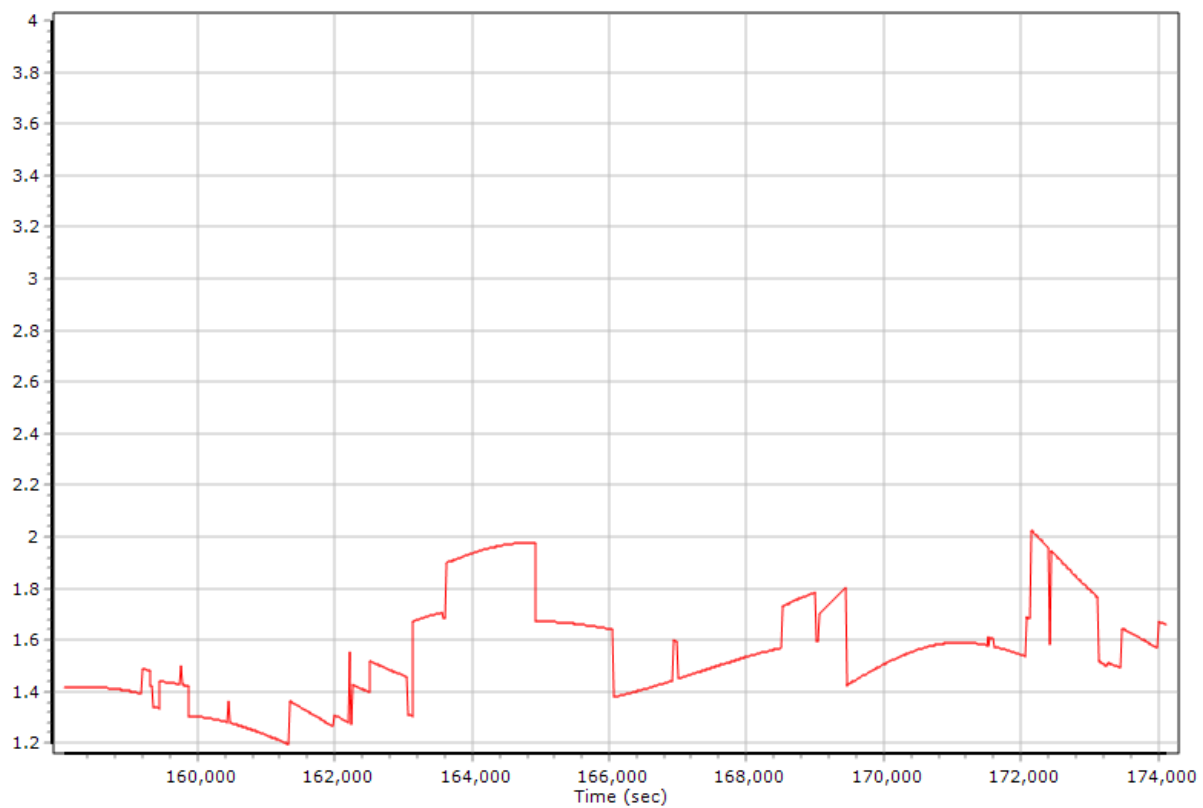


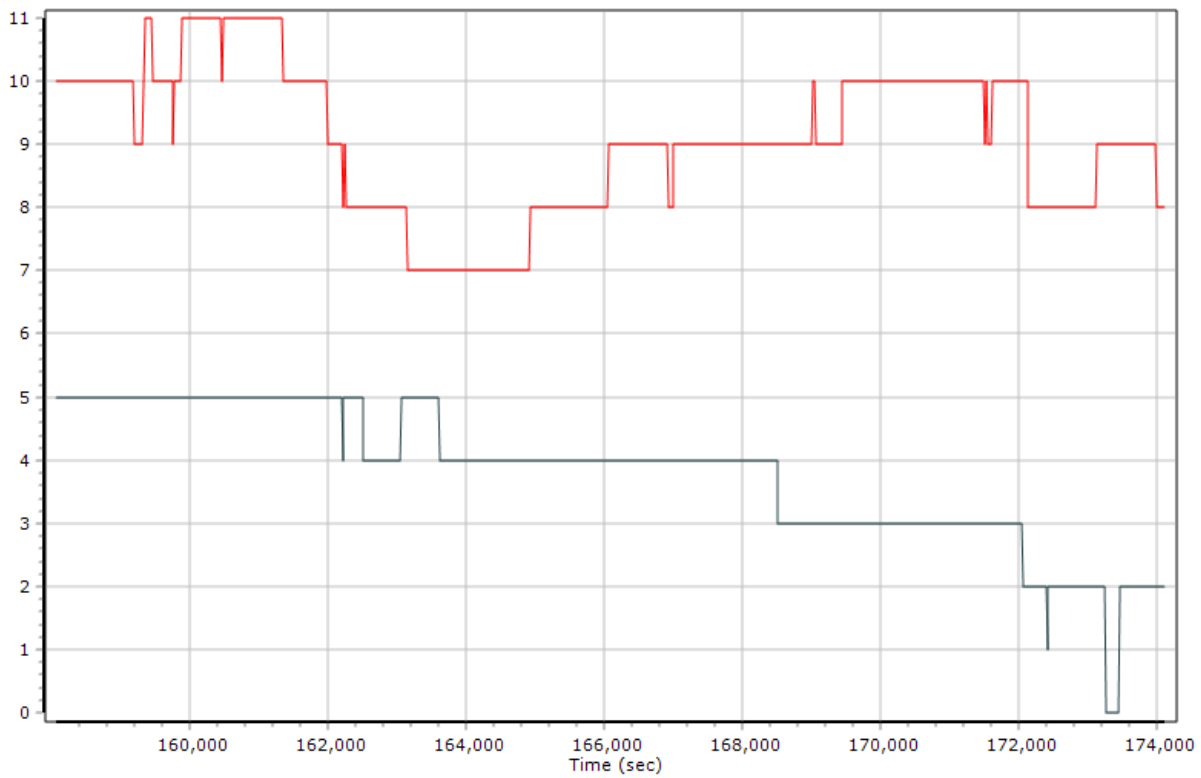
Processing Mode



0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = C/A, 7 = GNSS Nav, 8 = DR

PDOP





— Number of GPS Satellites — Number of GLONASS Satellites

Stabilized Mount to IMU Lever Arm

X
Y
Z

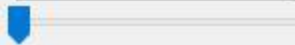
Stabilized Mount to IMU Mounting Angles

X
Y
Z

Stabilized Mount to Primary GNSS Lever Arm

X
Y
Z

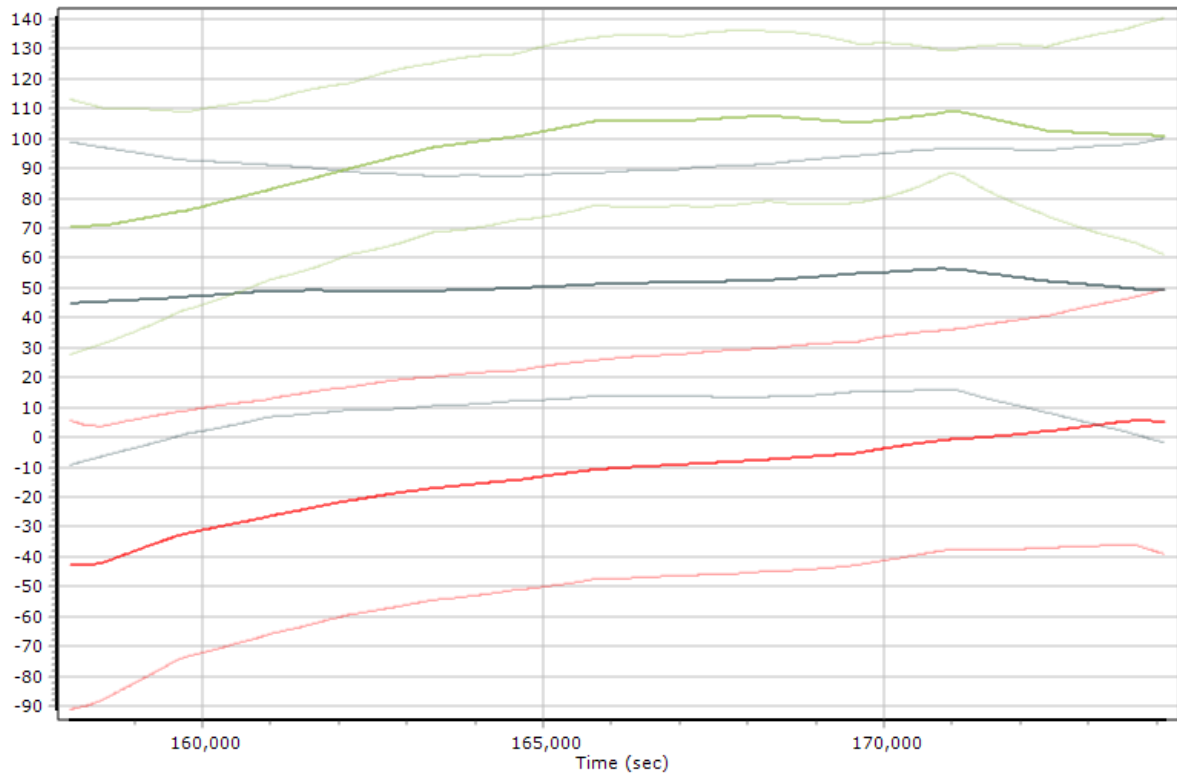
Standard Deviation


<3cm 10cm 50cm 1m 10m

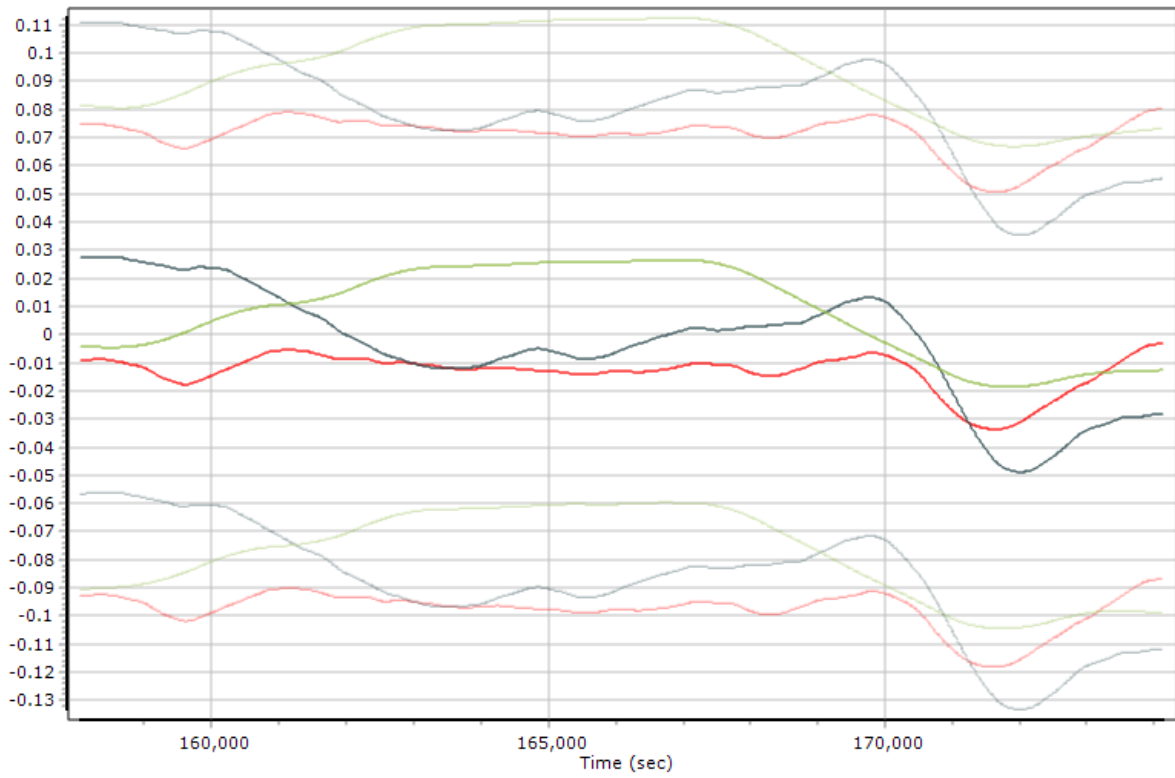
Aircraft to Stabilized Mount Mounting Angles

X
Y
Z

Measurements are to the stabilized platform's center of rotation with the Gimbal in the rest position.

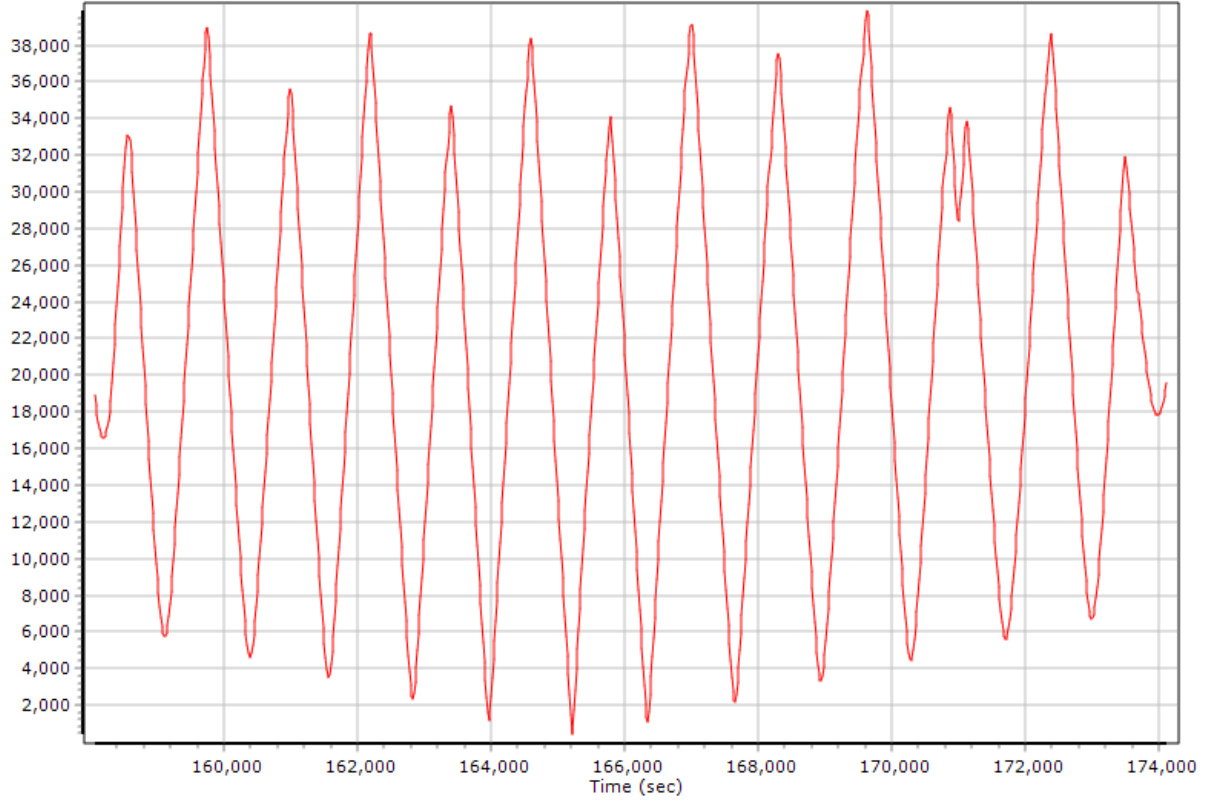


— x gyro scale error (ppm) — y gyro scale error (ppm) — z gyro scale error (ppm)

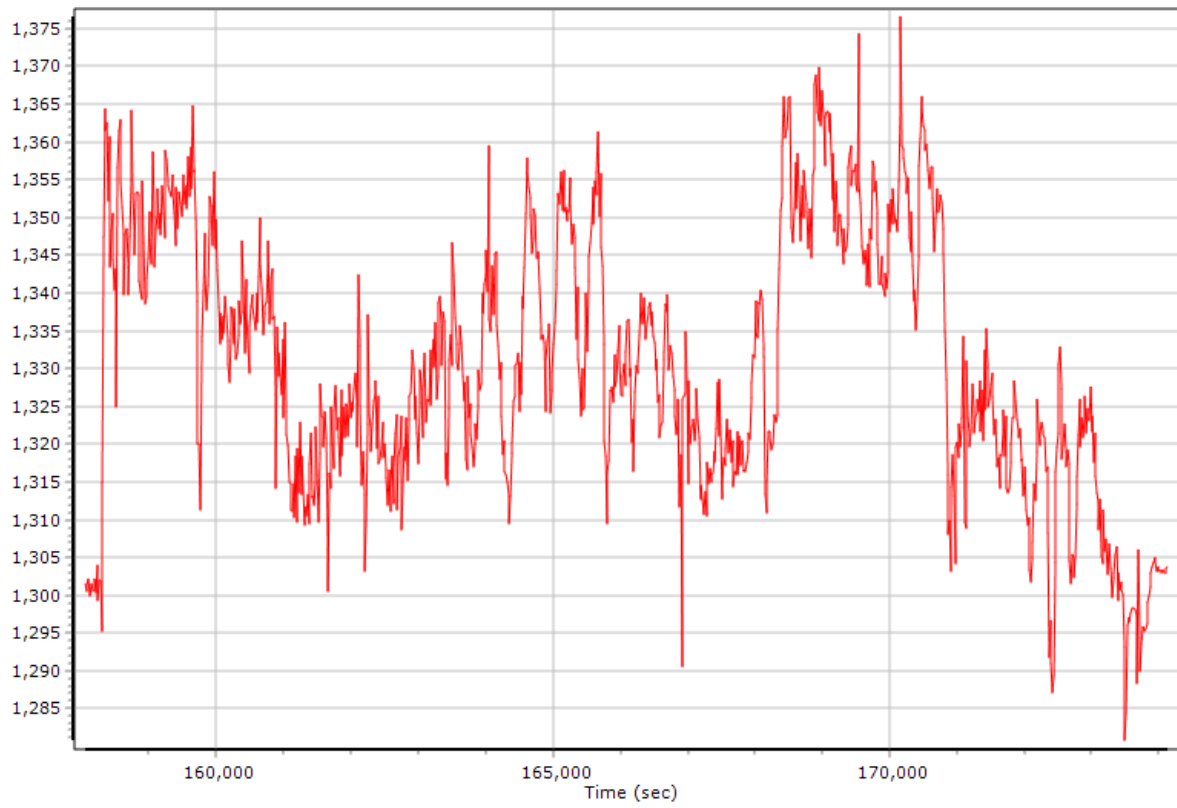


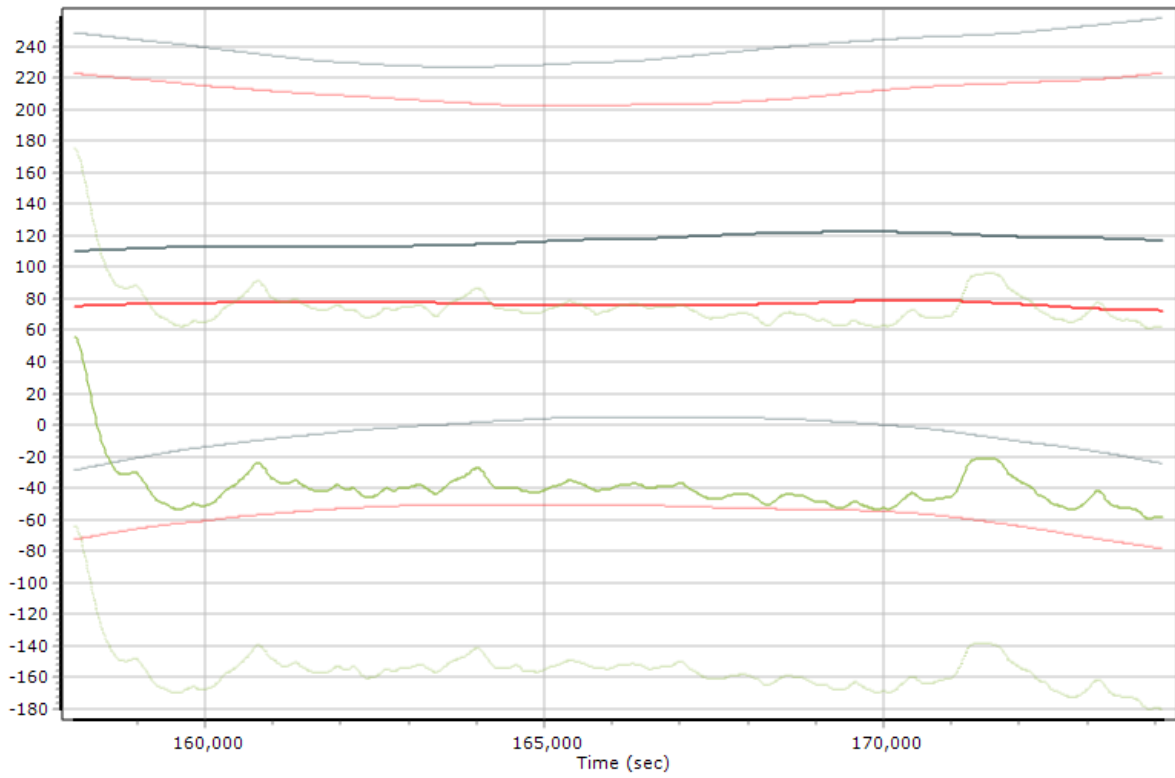
— x gyro bias (deg/hr) — y gyro bias (deg/hr) — z gyro bias (deg/hr)

Baseline Length(m)

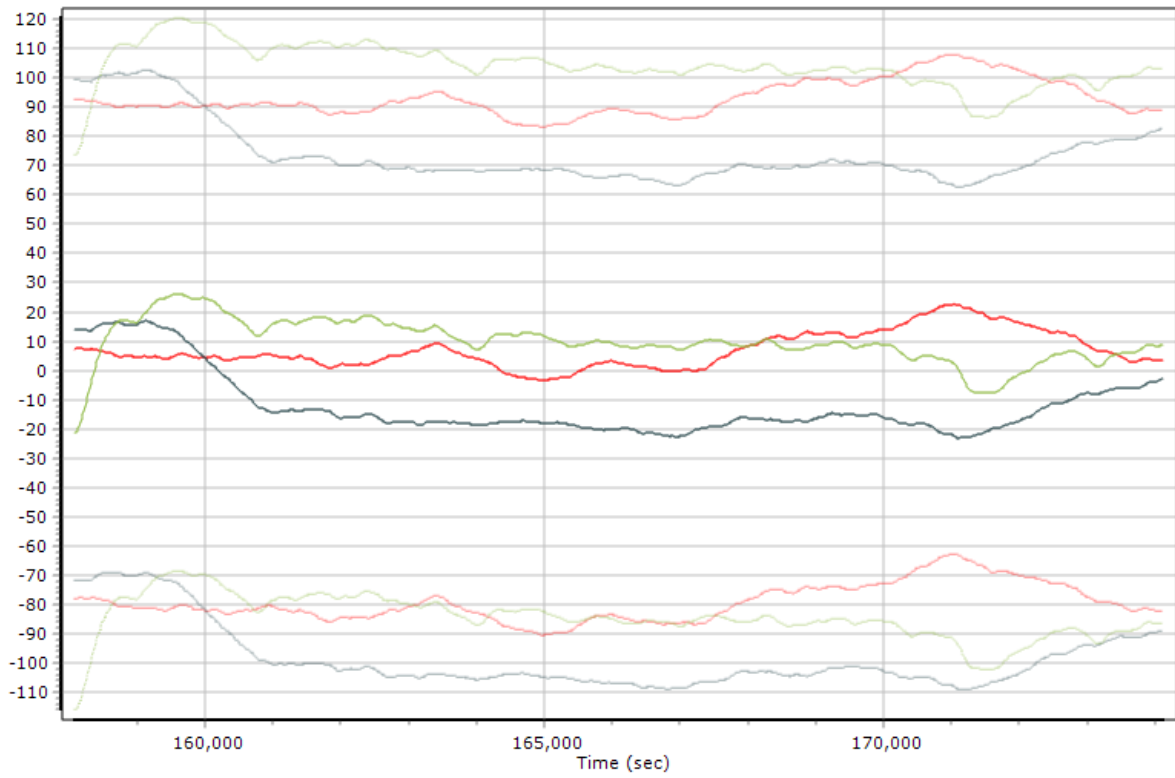


Altitude (m)

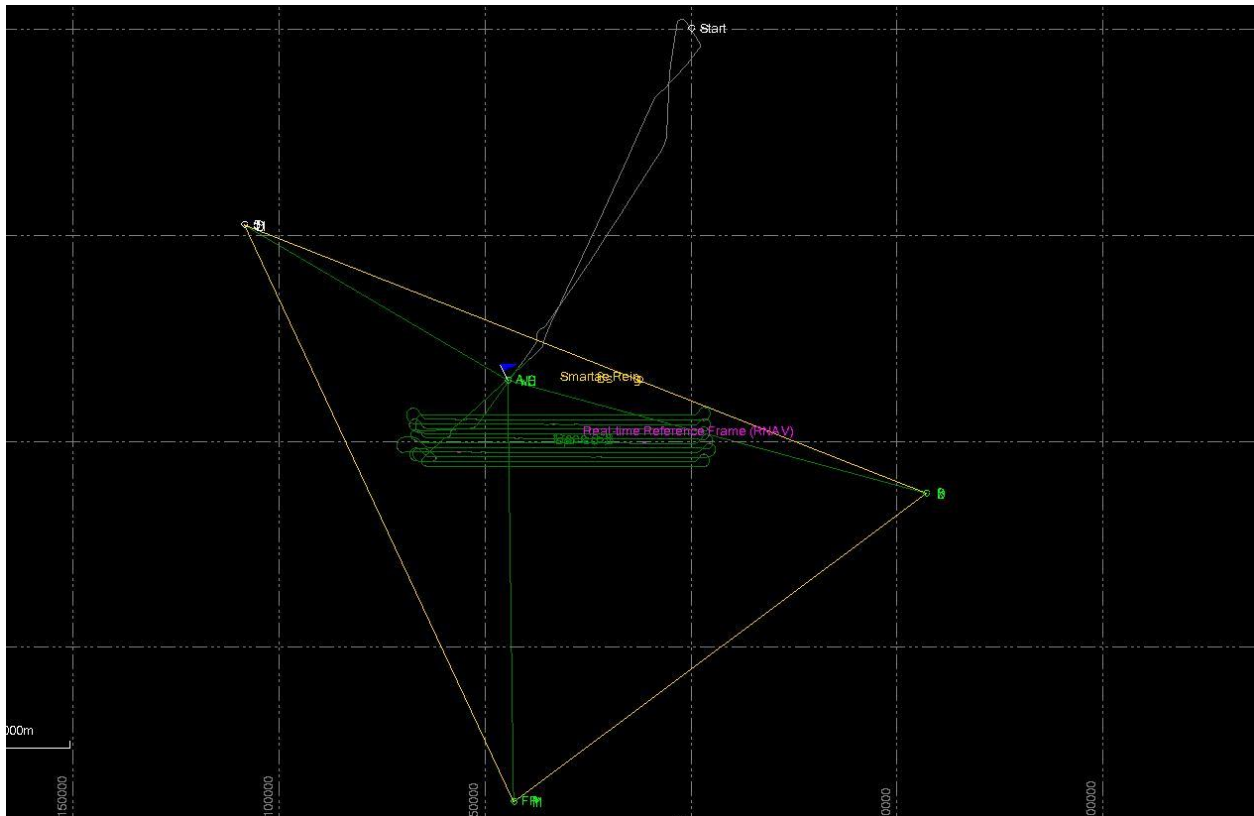




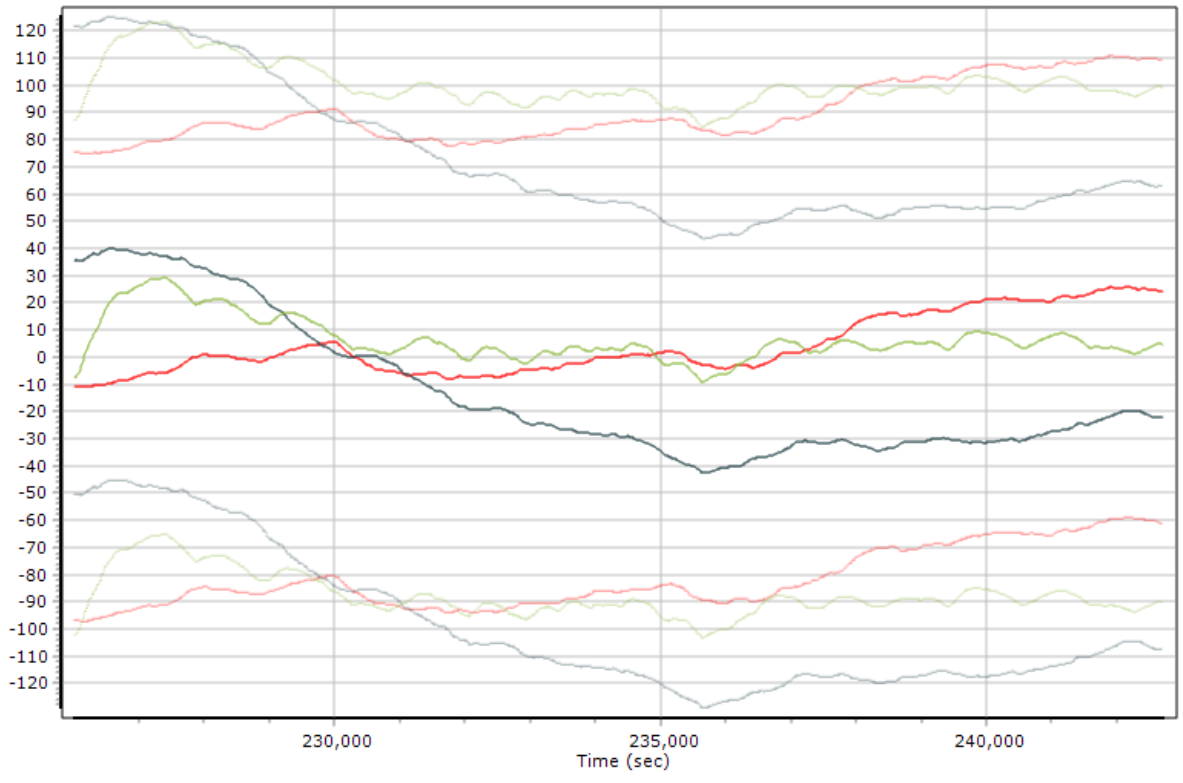
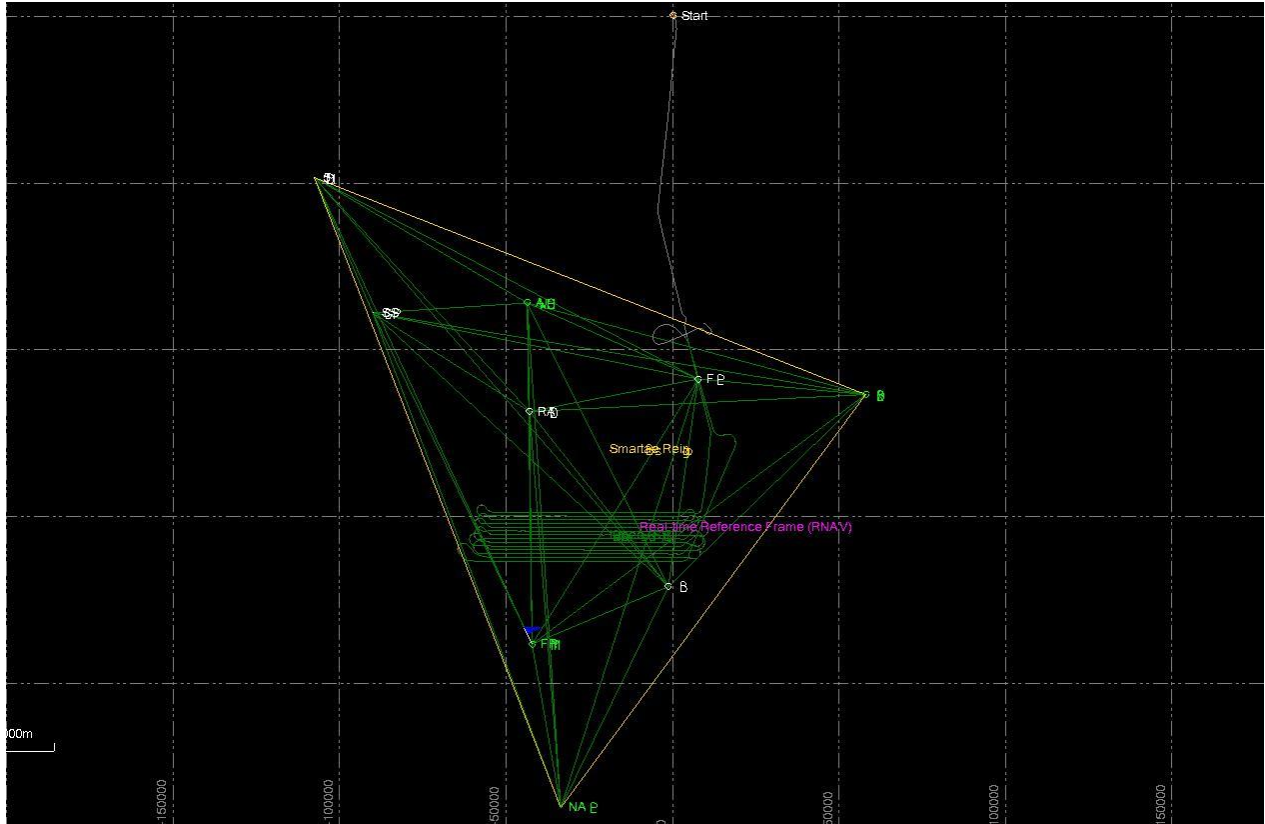
— x accelerometer scale error (ppm) — y accelerometer scale error (ppm) — z accelerometer scale error (ppm)



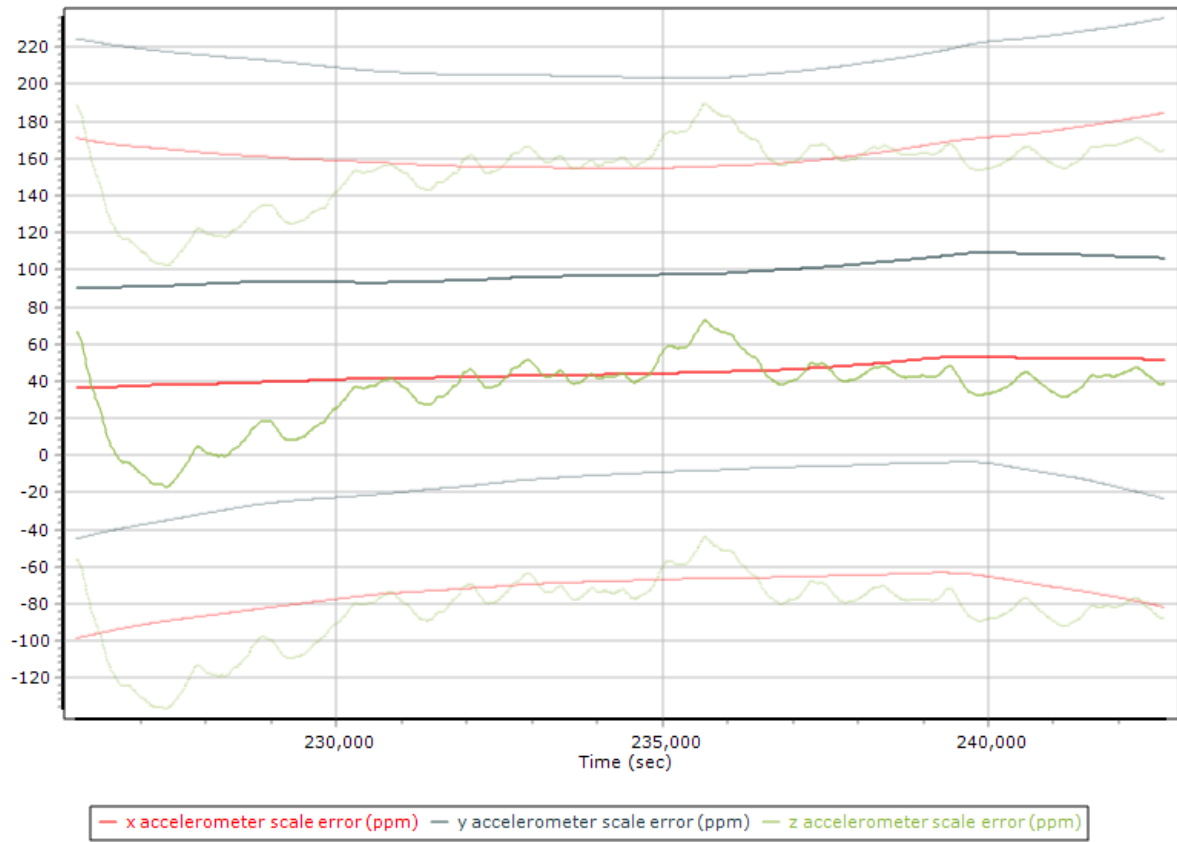
— x accelerometer bias (micro-g) — y accelerometer bias (micro-g) — z accelerometer bias (micro-g)



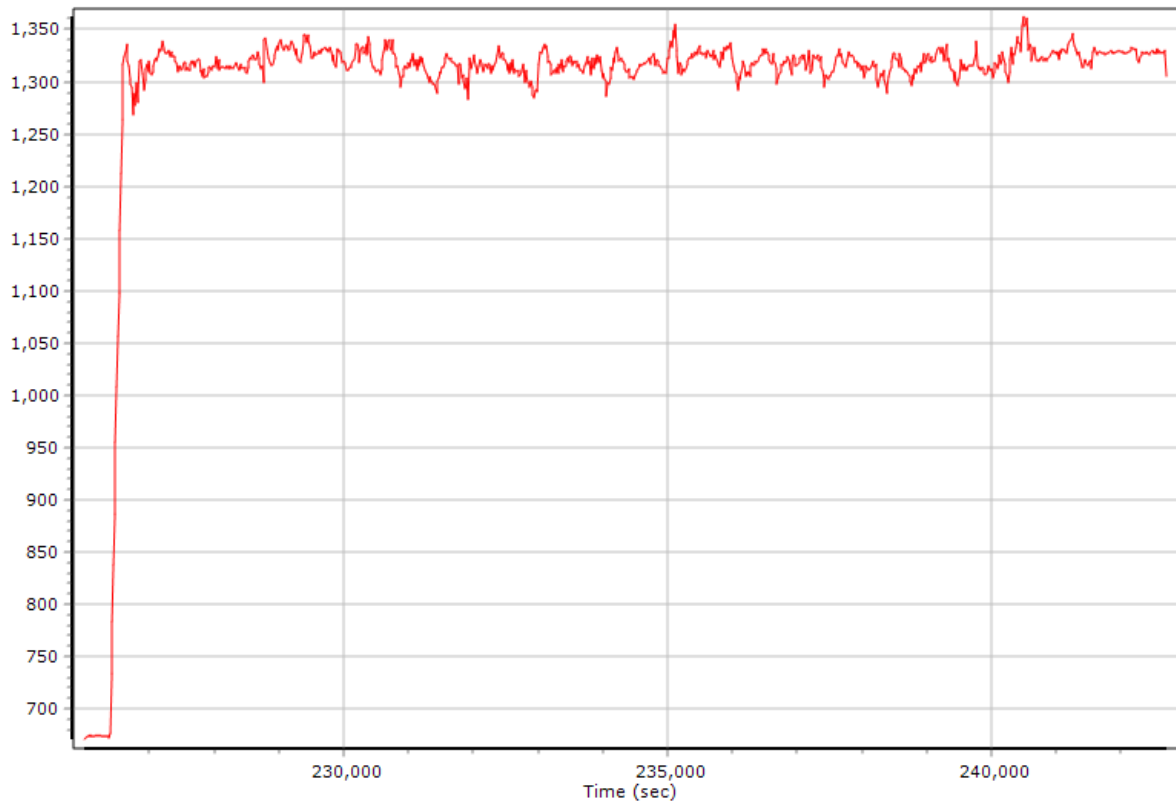
MISSION: 2SU18352A



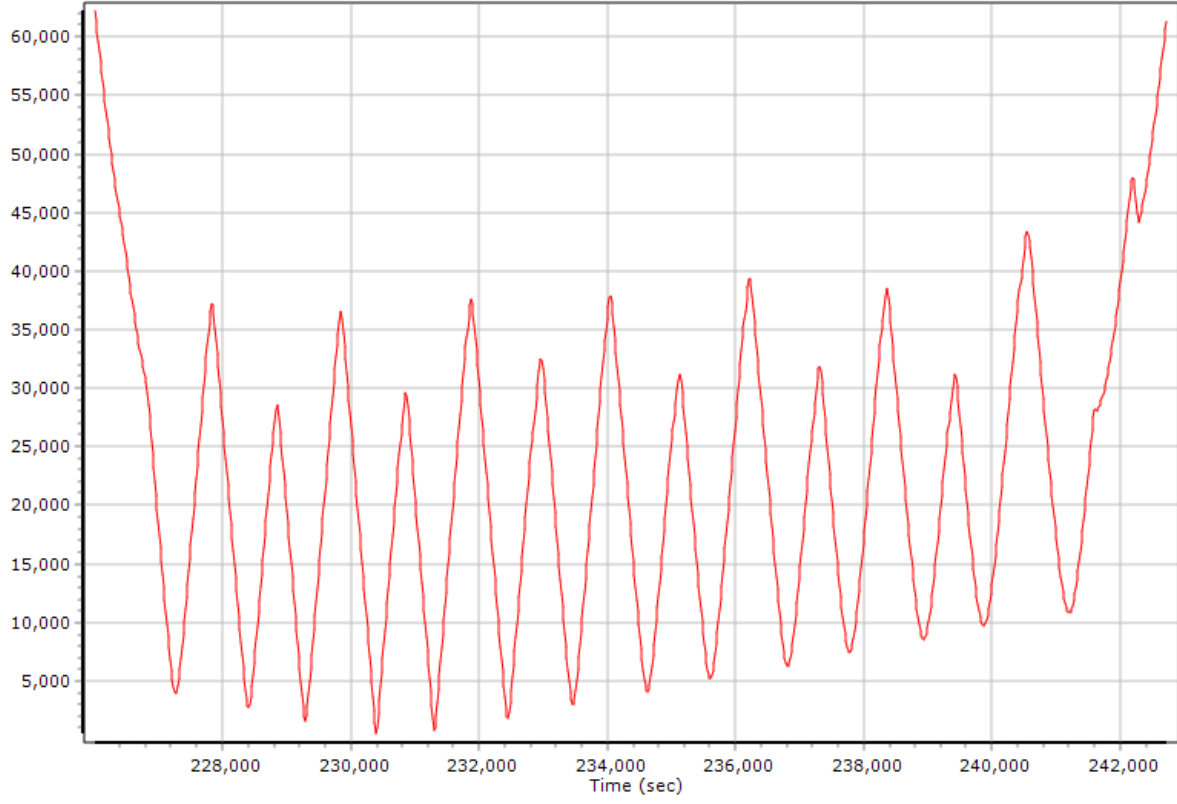
— x accelerometer bias (micro-g) — y accelerometer bias (micro-g) — z accelerometer bias (micro-g)

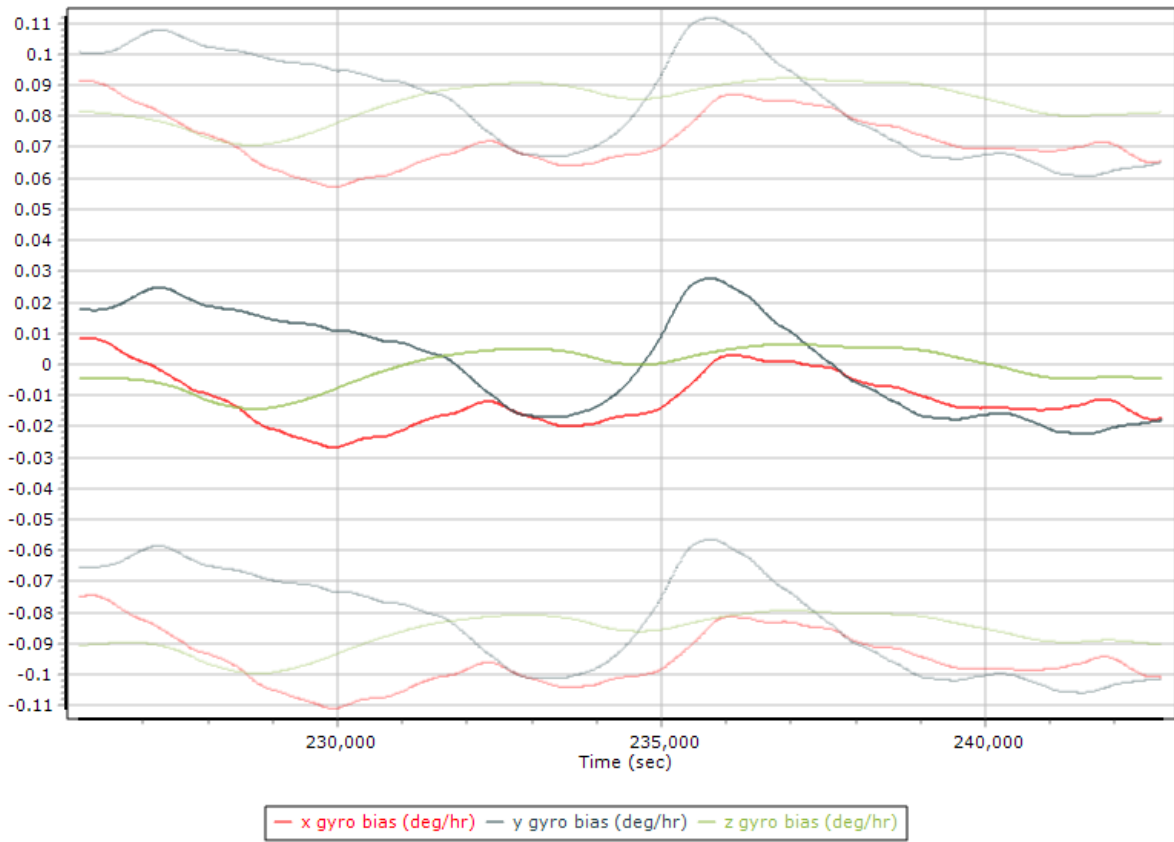


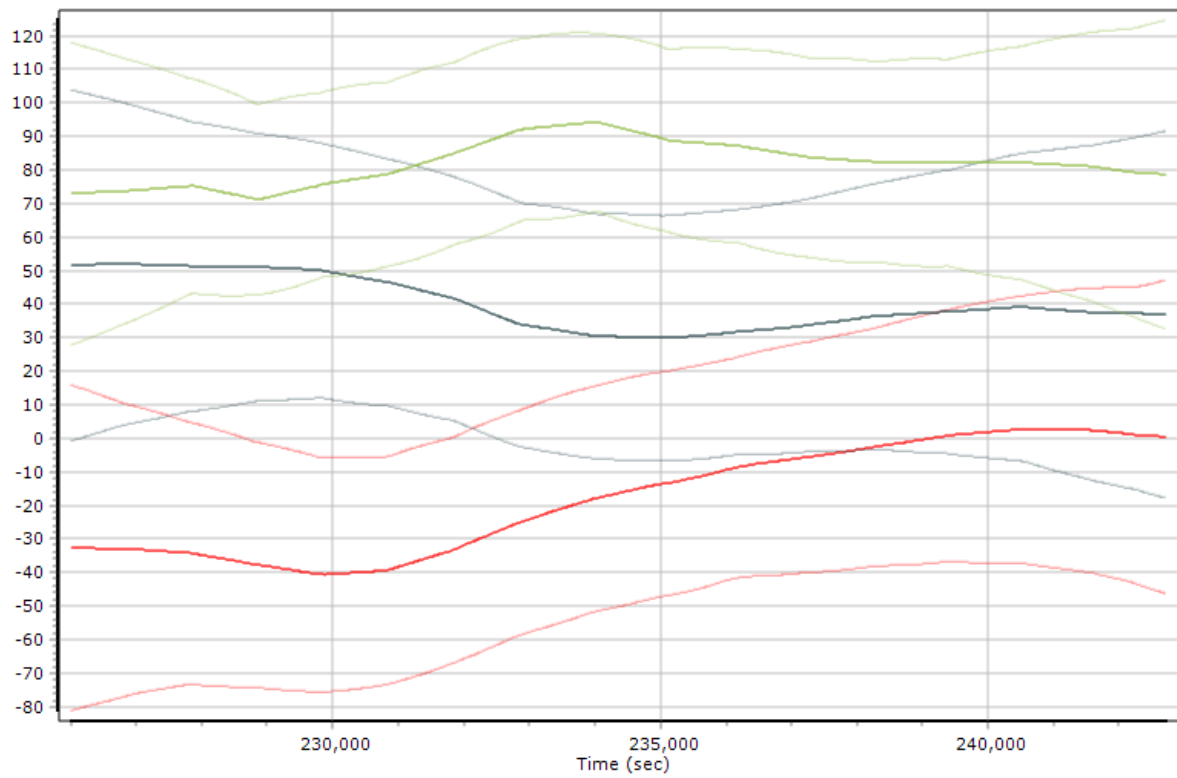
Altitude (m)



Baseline Length(m)







— x gyro scale error (ppm) — y gyro scale error (ppm) — z gyro scale error (ppm)

Stabilized Mount to IMU Lever Arm

X
Y
Z

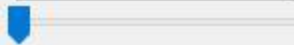
Stabilized Mount to IMU Mounting Angles

X
Y
Z

Stabilized Mount to Primary GNSS Lever Arm

X
Y
Z

Standard Deviation

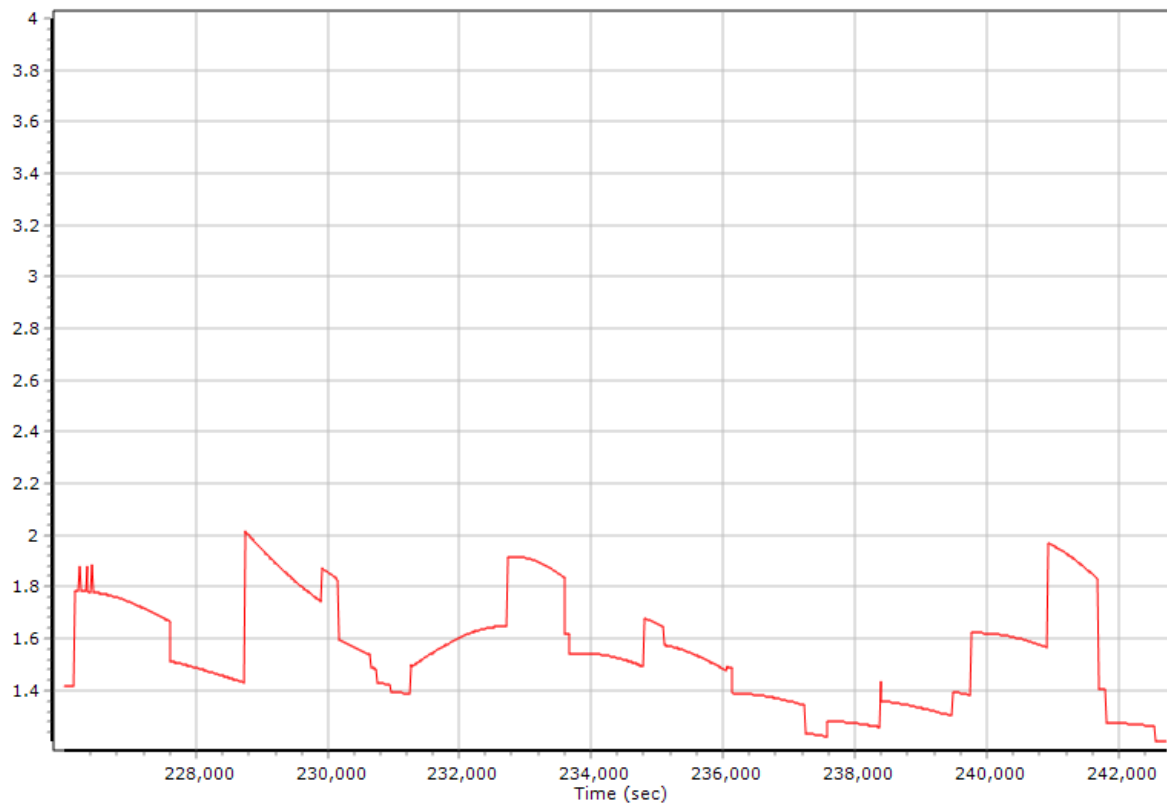

<3cm 10cm 50cm 1m 10m

Aircraft to Stabilized Mount Mounting Angles

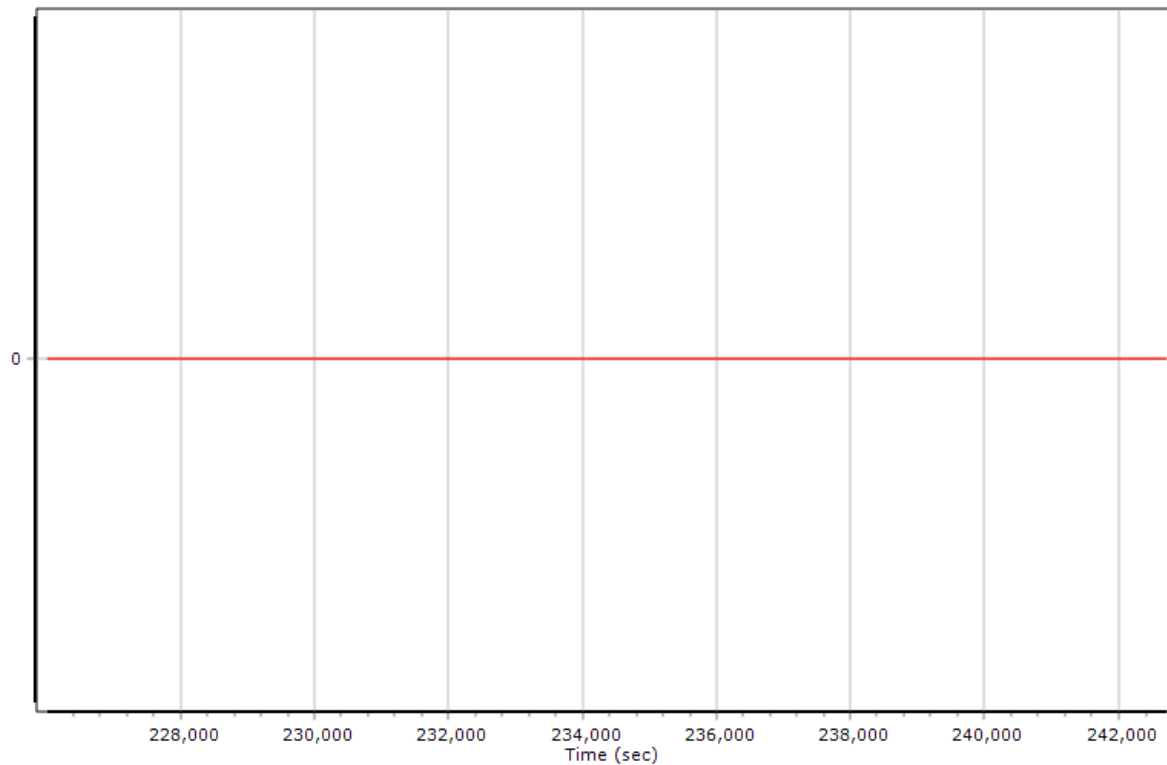
X
Y
Z

Measurements are to the stabilized platform's center of rotation with the Gimbal in the rest position.

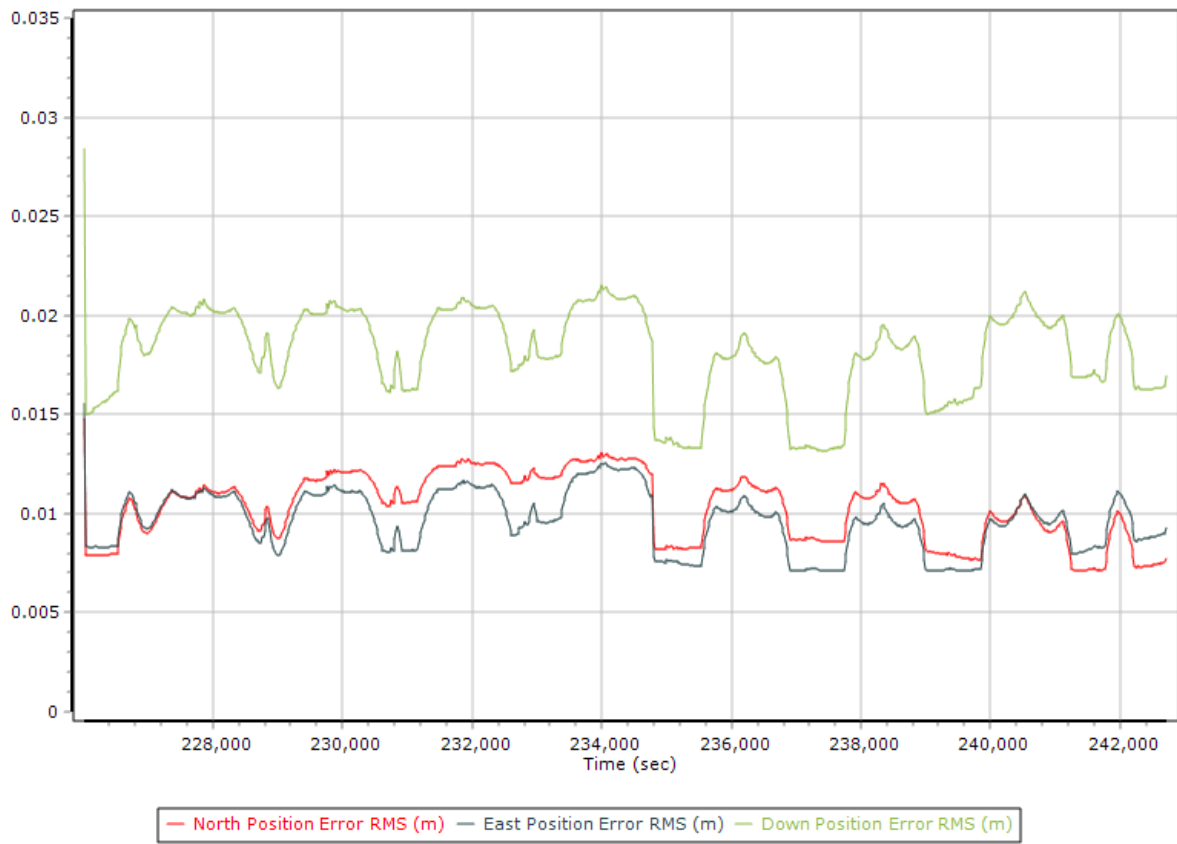
PDOP

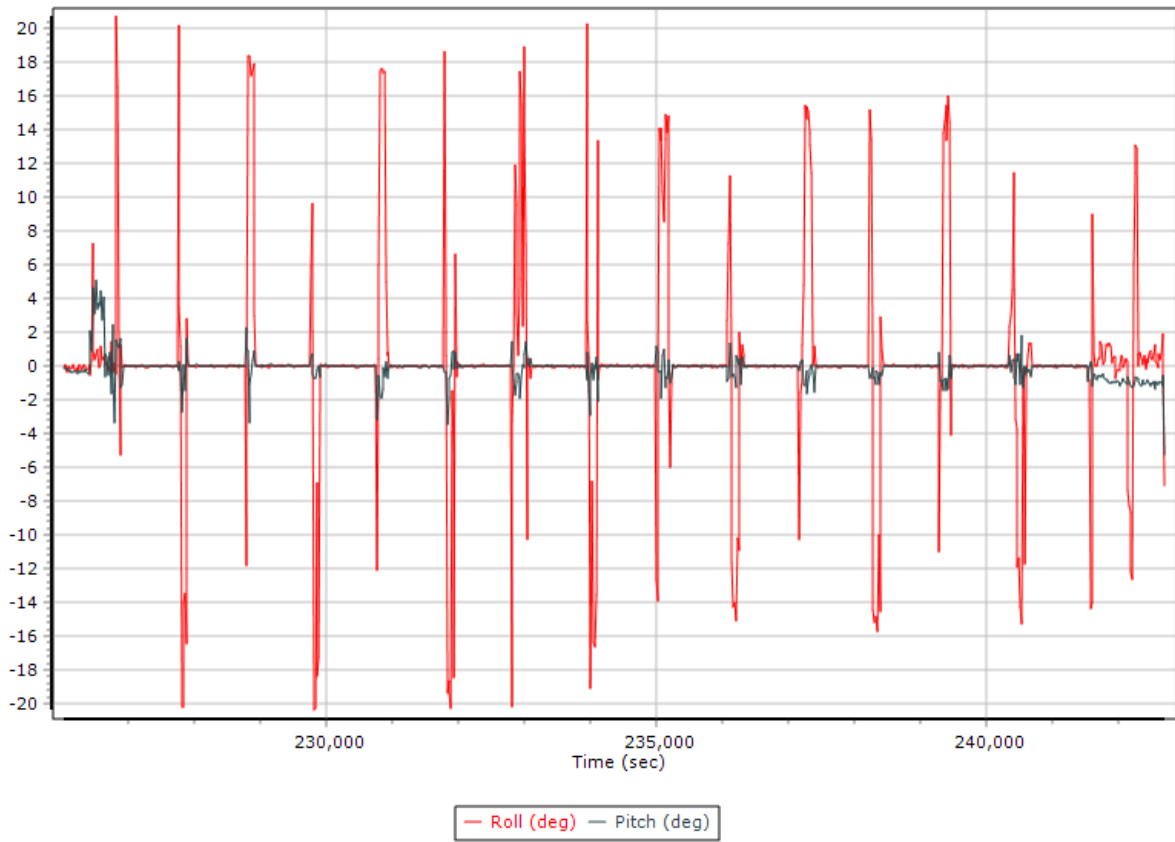


Processing Mode



0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = C/A, 7 = GNSS Nav, 8 = DR





Output Format

 Shapefile 

PointZ PolylineZ

Reference to Output
Lever Arm

X	0.000 m
Y	0.000 m
Z	0.000 m

Output w.r.t. Reference
Mounting Angles

X	0.000 deg
Y	0.000 deg
Z	0.000 deg

Output Rate

All Records

Height Options

Ellipsoid Geoid Model

Orthometric EGM96

WGS84

Output Units

Coordinate Meter

Lat & Lon Deg Decimal

Solution In Use Post-processed

Timing

Start 226007.003 Entire time interval

End 242728.698 Seconds of start week

Default Mapping Frame

Mapping Frame

WGS84 Universal Transverse Mercator UTM North 17 (84W to 78W) NONE 2018.962

Output Format

 Shapefile 

PointZ PolylineZ

Reference to Output
Lever Arm

X	0.000 m
Y	0.000 m
Z	0.000 m

Output w.r.t. Reference
Mounting Angles

X	0.000 deg
Y	0.000 deg
Z	0.000 deg

Output Rate

All Records

Height Options

Ellipsoid Geoid Model

Orthometric EGM96

WGS84

Output Units

Coordinate Meter

Lat & Lon Deg Decimal

Solution In Use Post-processed

Timing

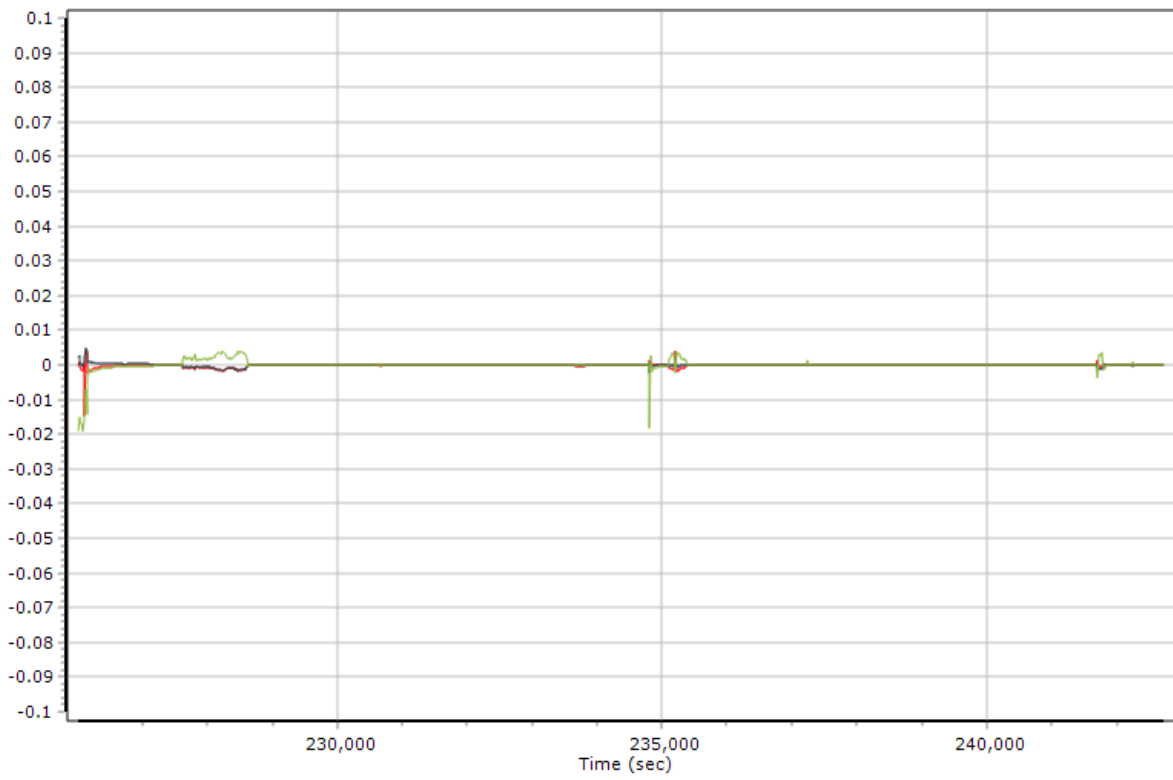
Start 226007.003 Entire time interval

End 242728.698 Seconds of start week

Default Mapping Frame

Mapping Frame

WGS84 Universal Transverse Mercator UTM North 17 (84W to 78W) NONE 2018.962



— North (m) — East (m) — Down (m) — DR mode

Timing

Start

End

Entire time interval

Seconds of start week

UTC Offset

Data	Incr. (sec)
Output Record	0.005000
IMU	0.005000
Primary GNSS	1.000000



MISSION: 2SU18352B

Timing

Start: 248935.308

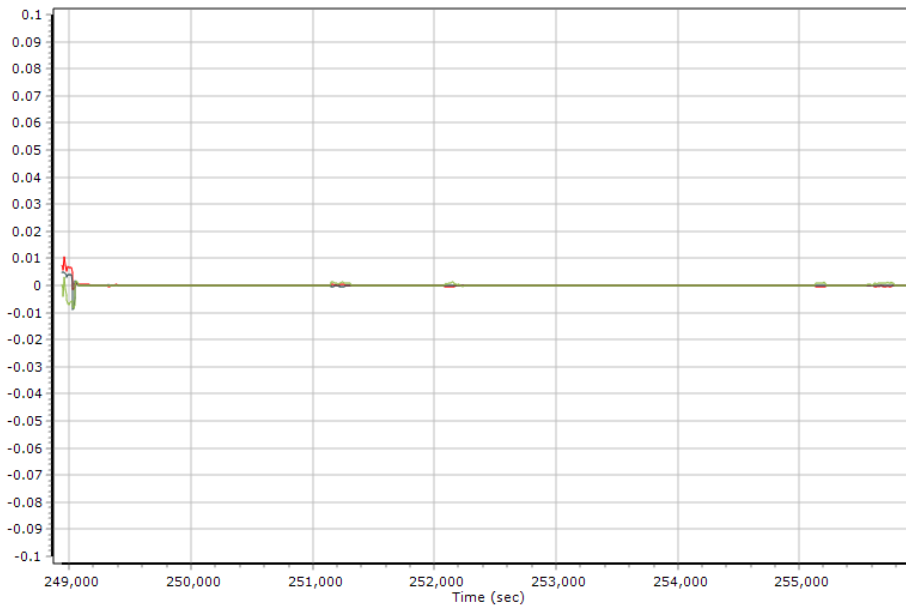
End: 255895.929

Entire time interval

Seconds of start week

UTC Offset: 18.000

Data	Incr. (sec)
Output Record	0.005000
IMU	0.005000
Primary GNSS	1.000000



Disable Satellites

GPS GLONASS BEIDOU QZSS

- | | | | |
|--------------------------------|---------------------------------|---------------------------------|---------------------------------|
| <input type="checkbox"/> PRN 1 | <input type="checkbox"/> PRN 10 | <input type="checkbox"/> PRN 19 | <input type="checkbox"/> PRN 28 |
| <input type="checkbox"/> PRN 2 | <input type="checkbox"/> PRN 11 | <input type="checkbox"/> PRN 20 | <input type="checkbox"/> PRN 29 |
| <input type="checkbox"/> PRN 3 | <input type="checkbox"/> PRN 12 | <input type="checkbox"/> PRN 21 | <input type="checkbox"/> PRN 30 |
| <input type="checkbox"/> PRN 4 | <input type="checkbox"/> PRN 13 | <input type="checkbox"/> PRN 22 | <input type="checkbox"/> PRN 31 |
| <input type="checkbox"/> PRN 5 | <input type="checkbox"/> PRN 14 | <input type="checkbox"/> PRN 23 | <input type="checkbox"/> PRN 32 |
| <input type="checkbox"/> PRN 6 | <input type="checkbox"/> PRN 15 | <input type="checkbox"/> PRN 24 | |
| <input type="checkbox"/> PRN 7 | <input type="checkbox"/> PRN 16 | <input type="checkbox"/> PRN 25 | |
| <input type="checkbox"/> PRN 8 | <input type="checkbox"/> PRN 17 | <input type="checkbox"/> PRN 26 | |
| <input type="checkbox"/> PRN 9 | <input type="checkbox"/> PRN 18 | <input type="checkbox"/> PRN 27 | |



Elevation Mask Angle

Force GPS Only

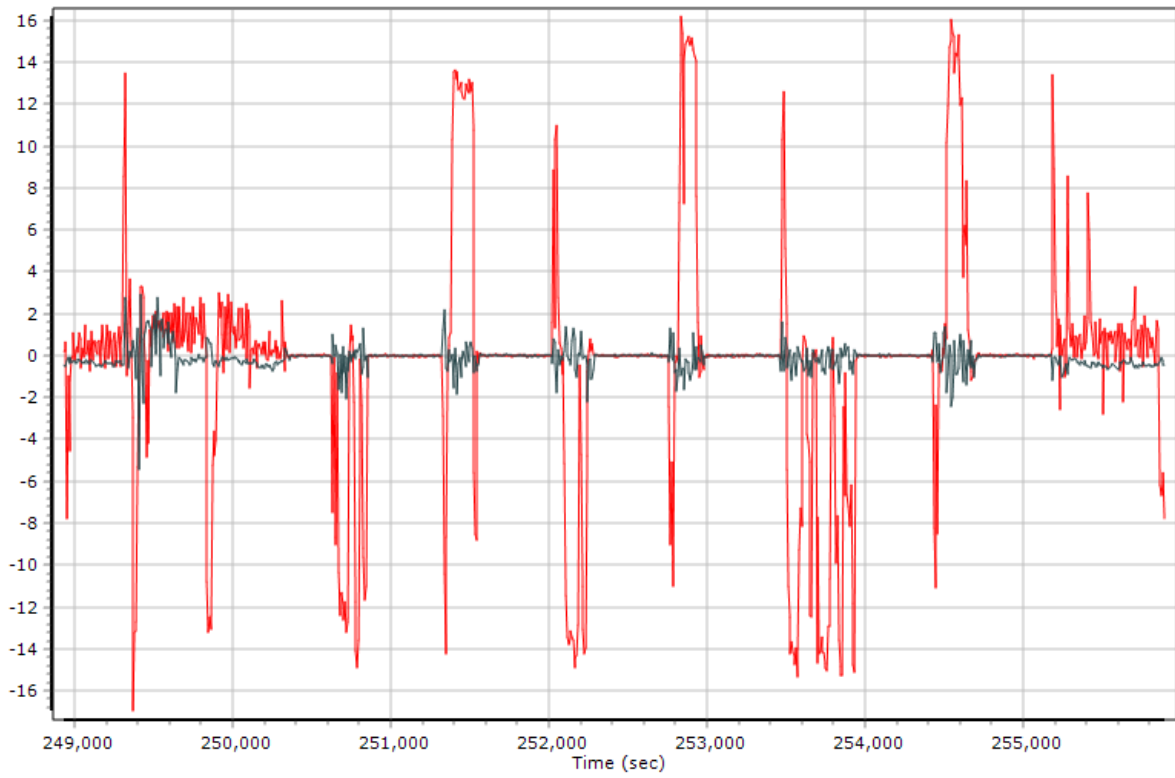
Disable Satellites

GPS GLONASS BEIDOU QZSS

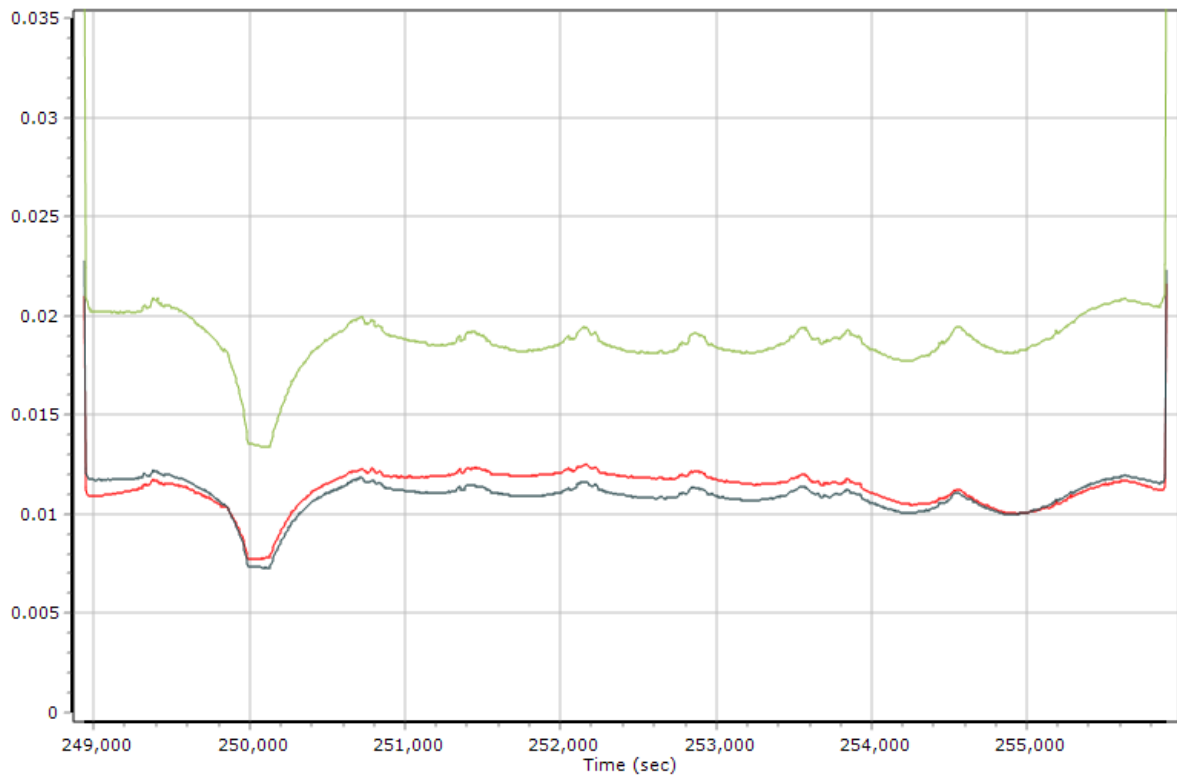
- | | | |
|---------------------------------|----------------------------------|----------------------------------|
| <input type="checkbox"/> SLOT 1 | <input type="checkbox"/> SLOT 10 | <input type="checkbox"/> SLOT 19 |
| <input type="checkbox"/> SLOT 2 | <input type="checkbox"/> SLOT 11 | <input type="checkbox"/> SLOT 20 |
| <input type="checkbox"/> SLOT 3 | <input type="checkbox"/> SLOT 12 | <input type="checkbox"/> SLOT 21 |
| <input type="checkbox"/> SLOT 4 | <input type="checkbox"/> SLOT 13 | <input type="checkbox"/> SLOT 22 |
| <input type="checkbox"/> SLOT 5 | <input type="checkbox"/> SLOT 14 | <input type="checkbox"/> SLOT 23 |
| <input type="checkbox"/> SLOT 6 | <input type="checkbox"/> SLOT 15 | <input type="checkbox"/> SLOT 24 |
| <input type="checkbox"/> SLOT 7 | <input type="checkbox"/> SLOT 16 | |
| <input type="checkbox"/> SLOT 8 | <input type="checkbox"/> SLOT 17 | |
| <input type="checkbox"/> SLOT 9 | <input type="checkbox"/> SLOT 18 | |

Elevation Mask Angle

Force GPS Only

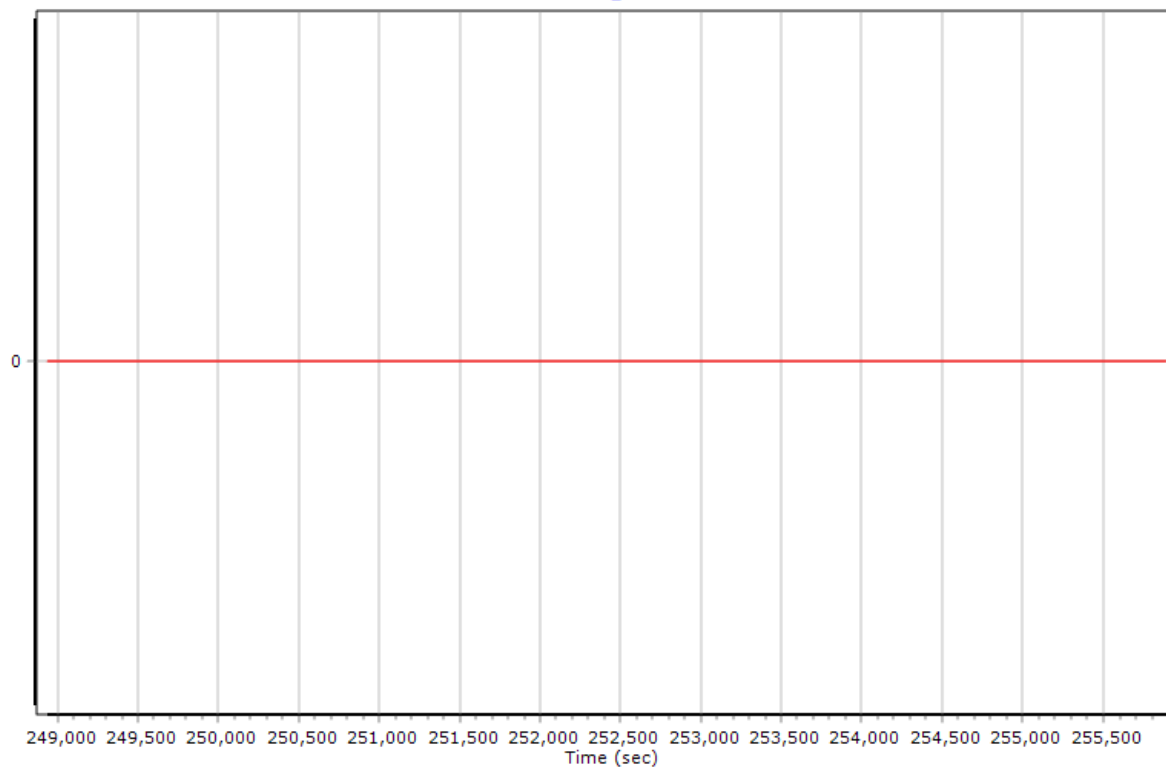


— Roll (deg) — Pitch (deg)



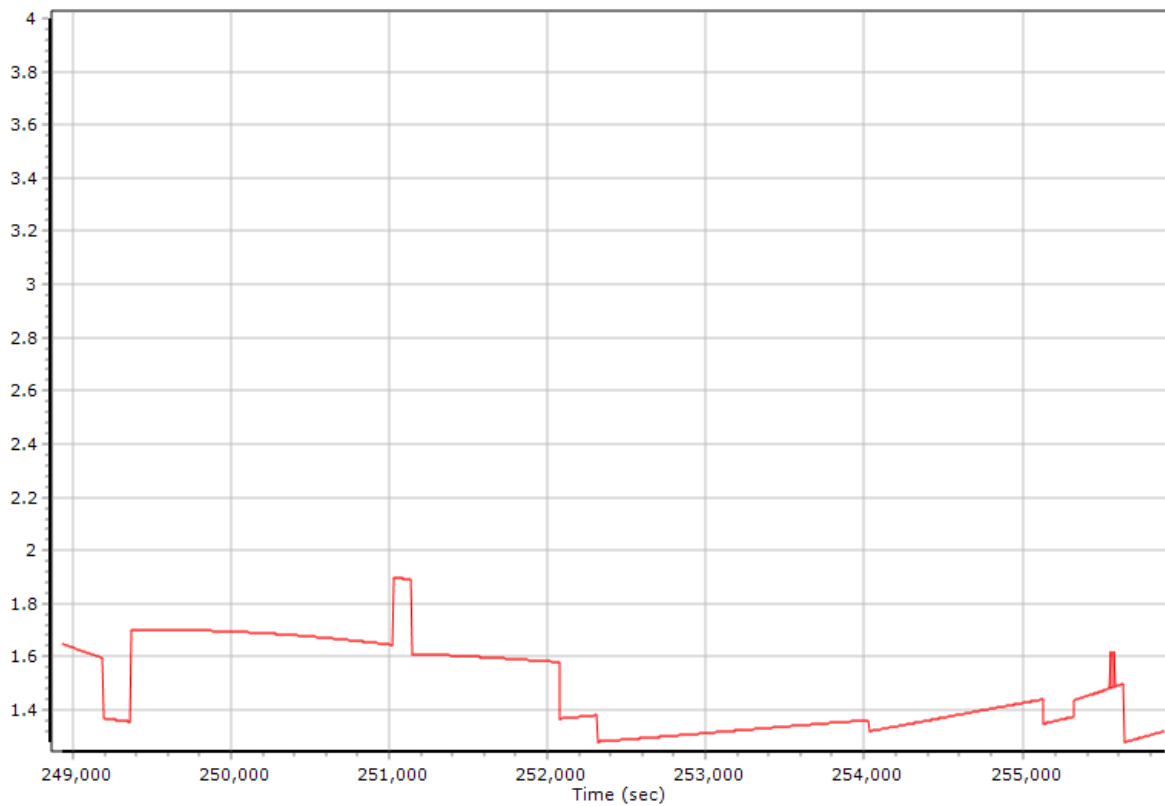
— North Position Error RMS (m) — East Position Error RMS (m) — Down Position Error RMS (m)

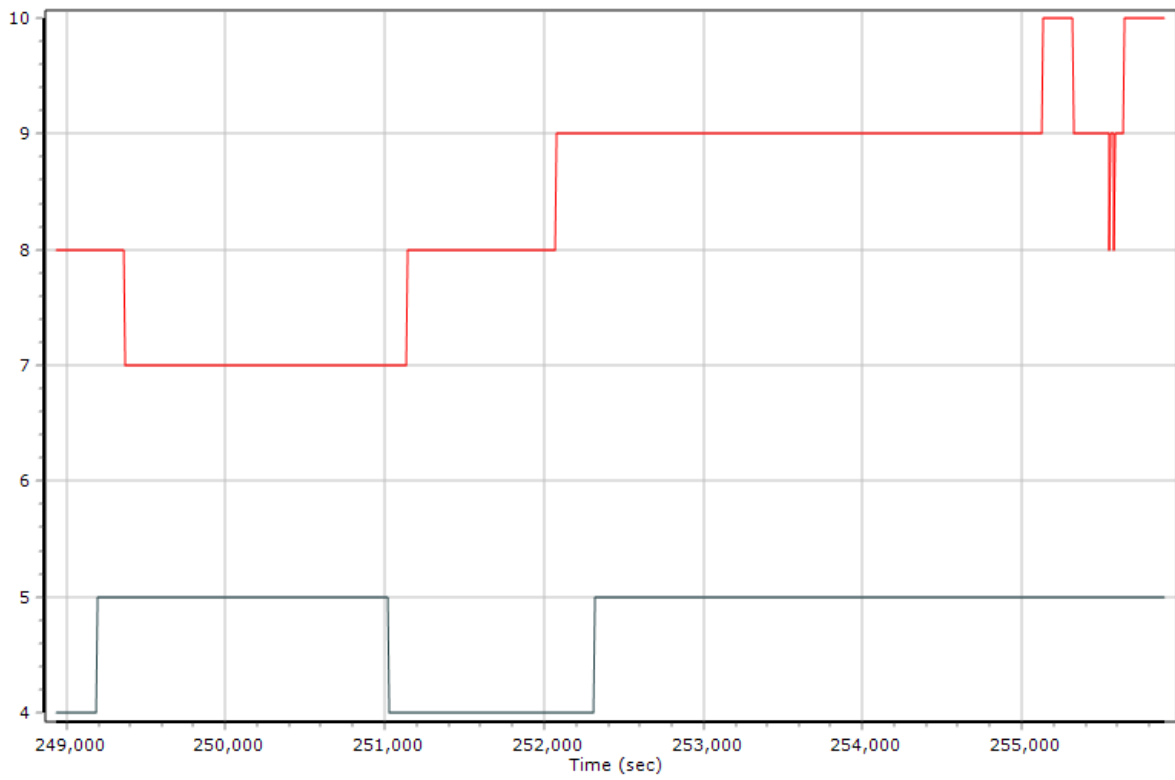
Processing Mode



0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = C/A, 7 = GNSS Nav, 8 = DR

PDOP





— Number of GPS Satellites — Number of GLONASS Satellites

Stabilized Mount to IMU Lever Arm

X
Y
Z

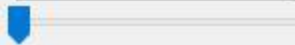
Stabilized Mount to IMU Mounting Angles

X
Y
Z

Stabilized Mount to Primary GNSS Lever Arm

X
Y
Z

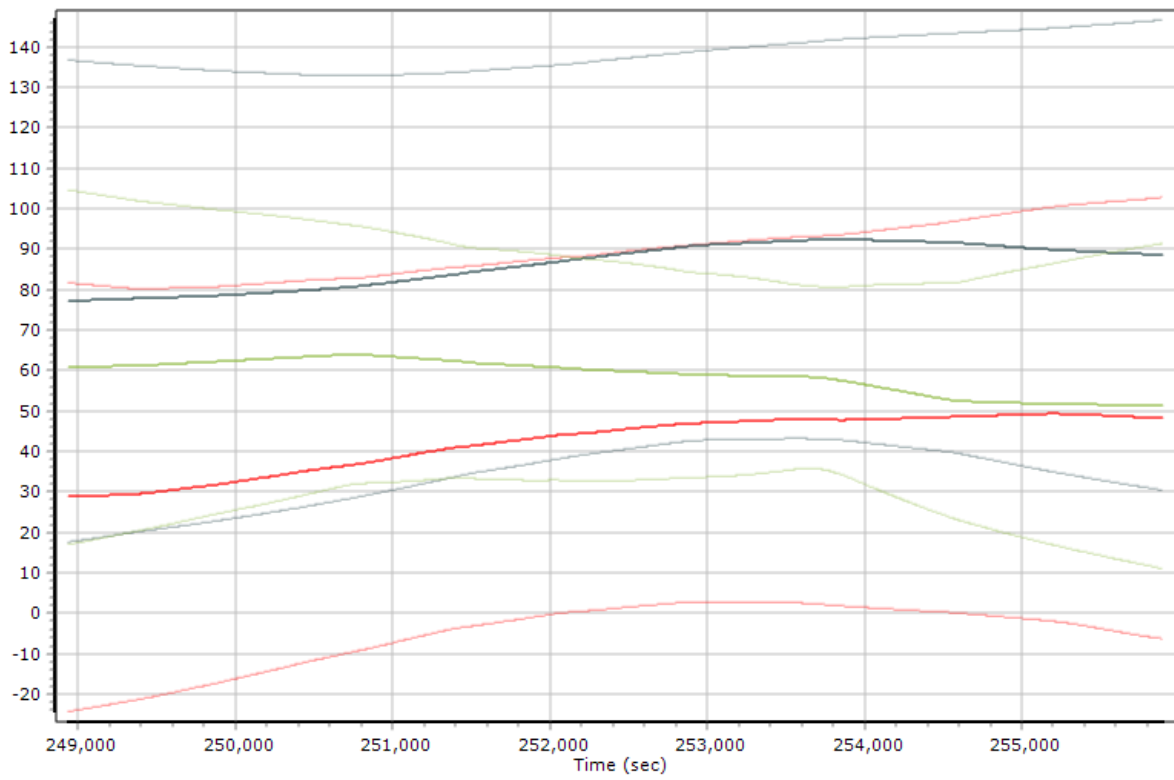
Standard Deviation


<3cm 10cm 50cm 1m 10m

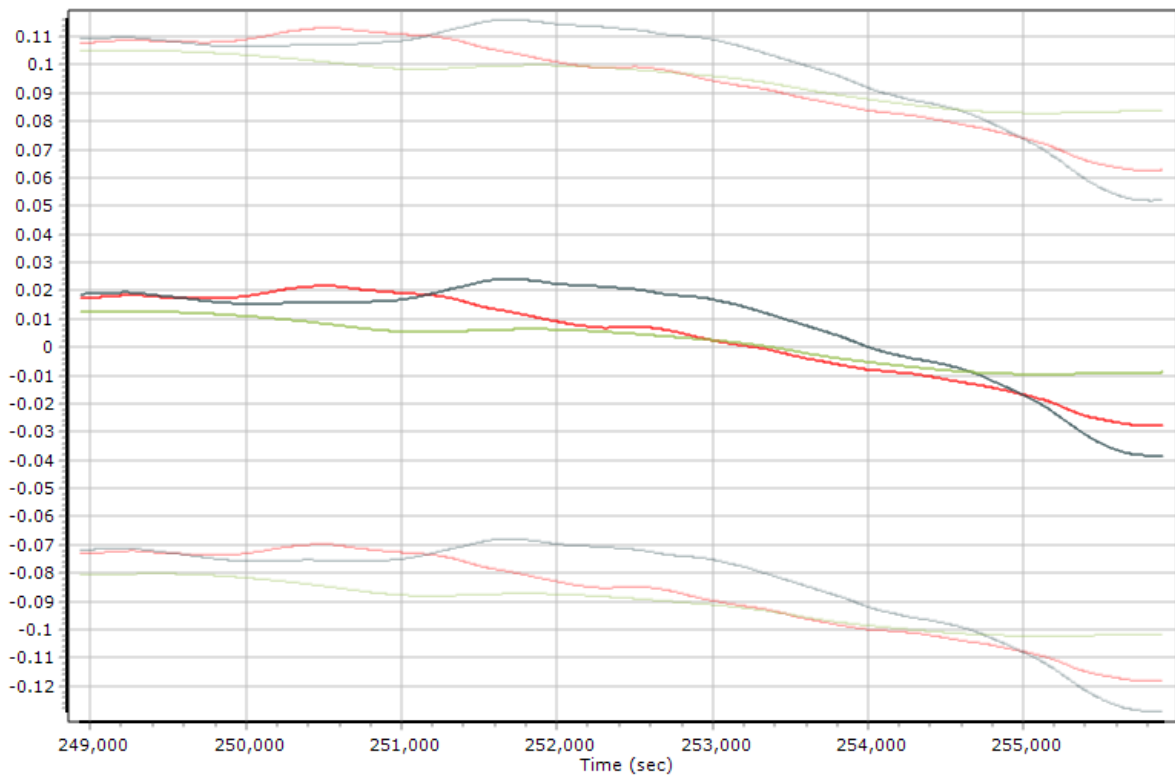
Aircraft to Stabilized Mount Mounting Angles

X
Y
Z

Measurements are to the stabilized platform's center of rotation with the Gimbal in the rest position.

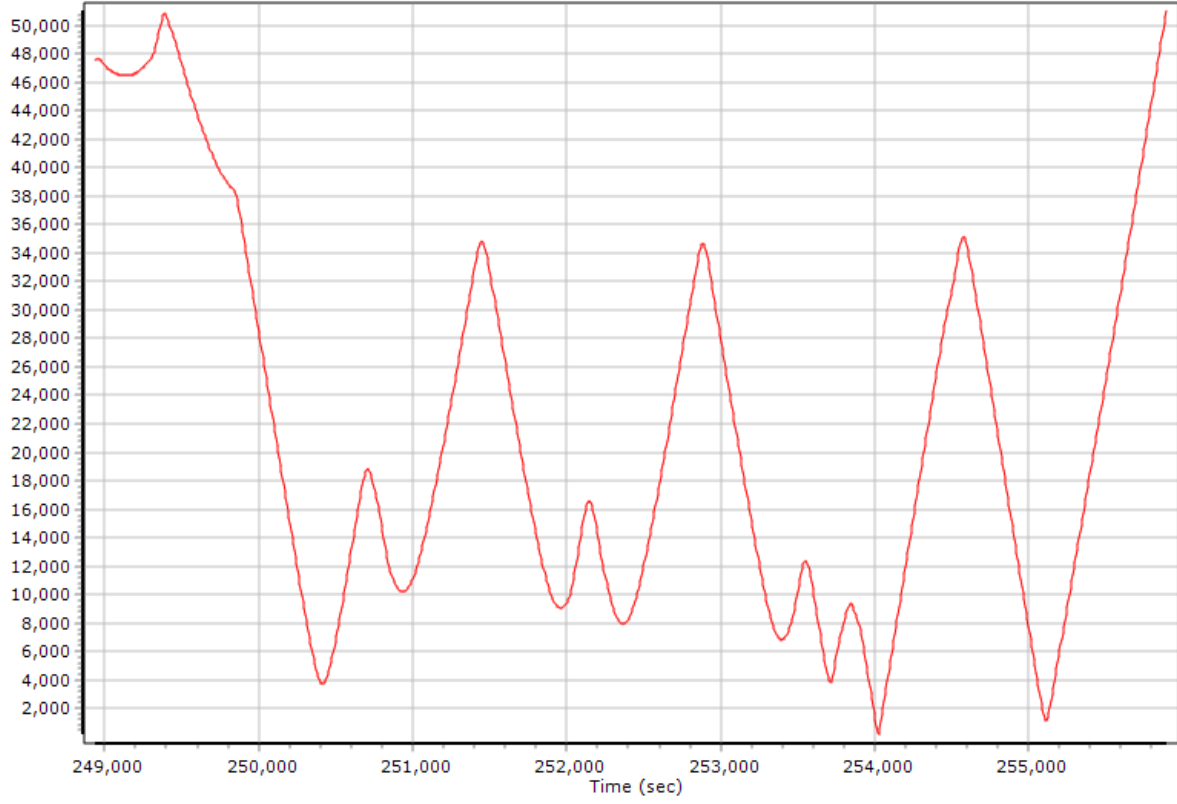


— x gyro scale error (ppm) — y gyro scale error (ppm) — z gyro scale error (ppm)

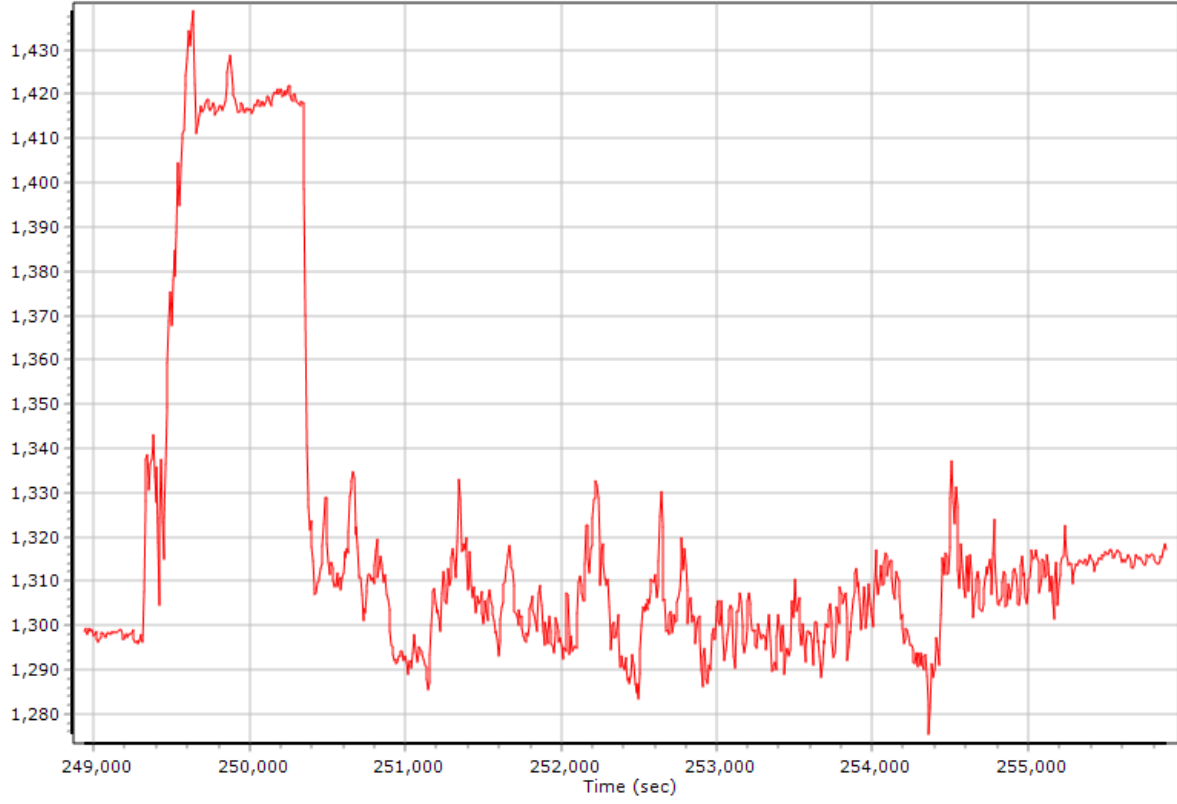


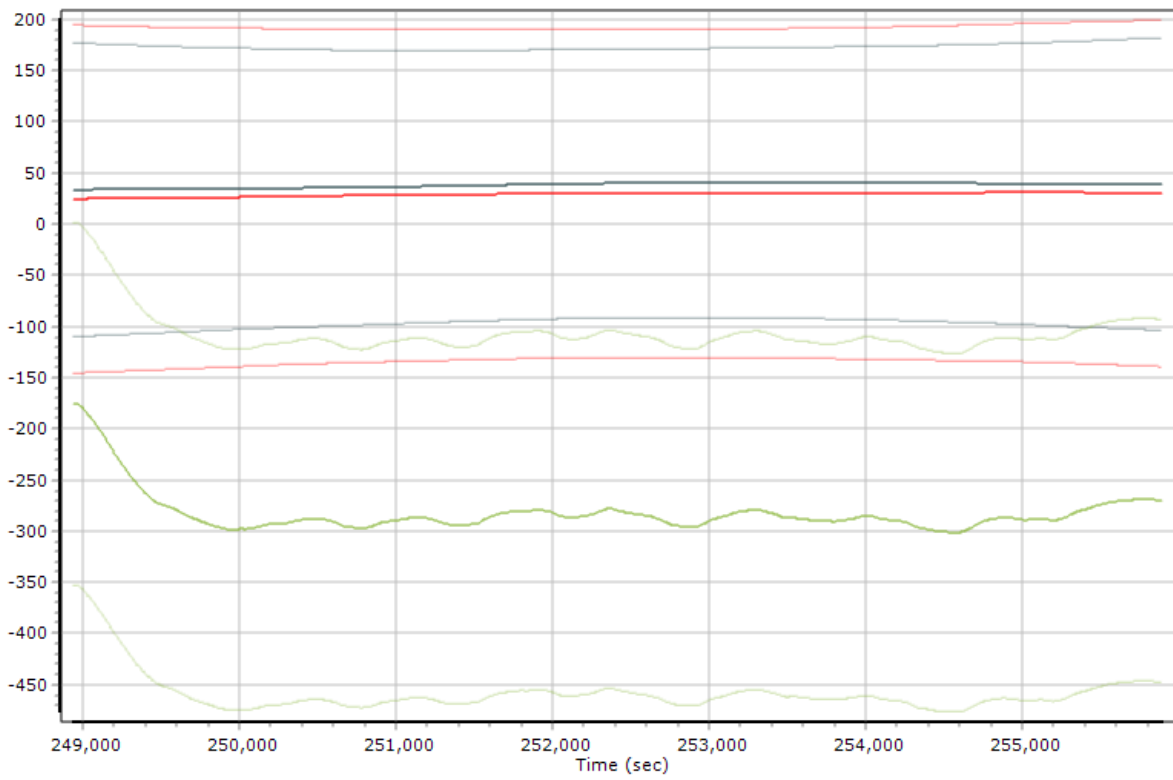
— x gyro bias (deg/hr) — y gyro bias (deg/hr) — z gyro bias (deg/hr)

Baseline Length(m)

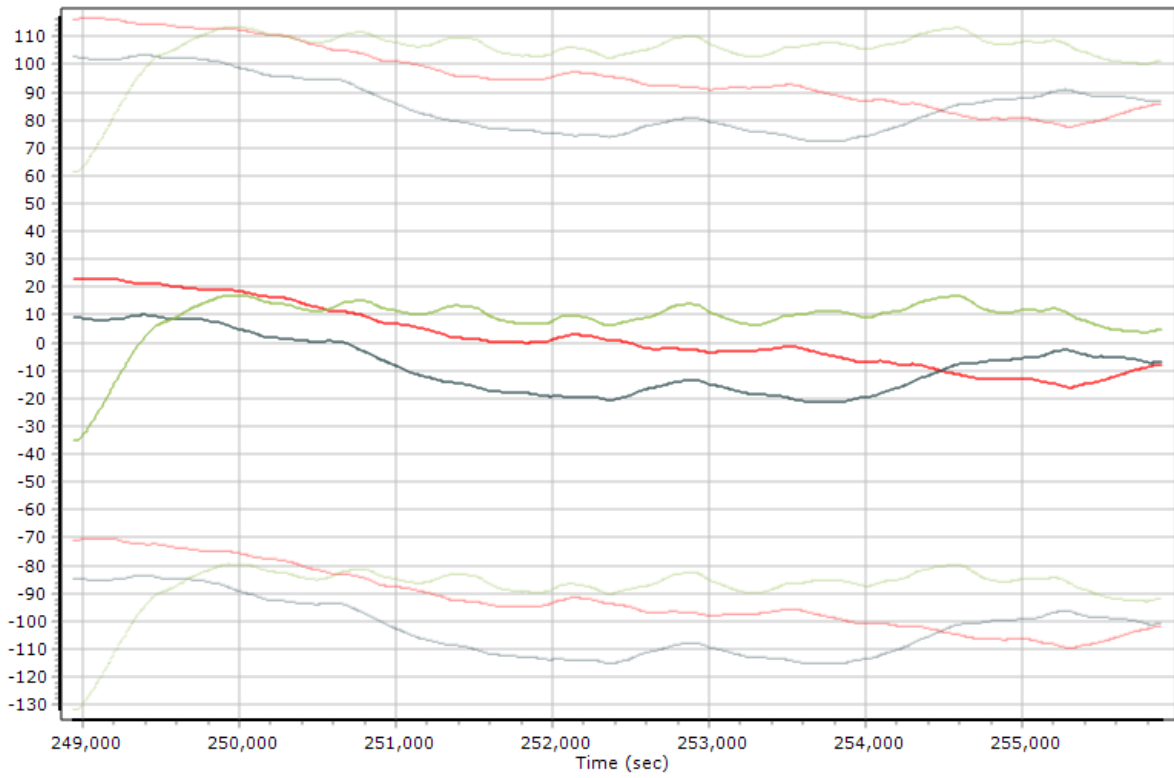


Altitude (m)

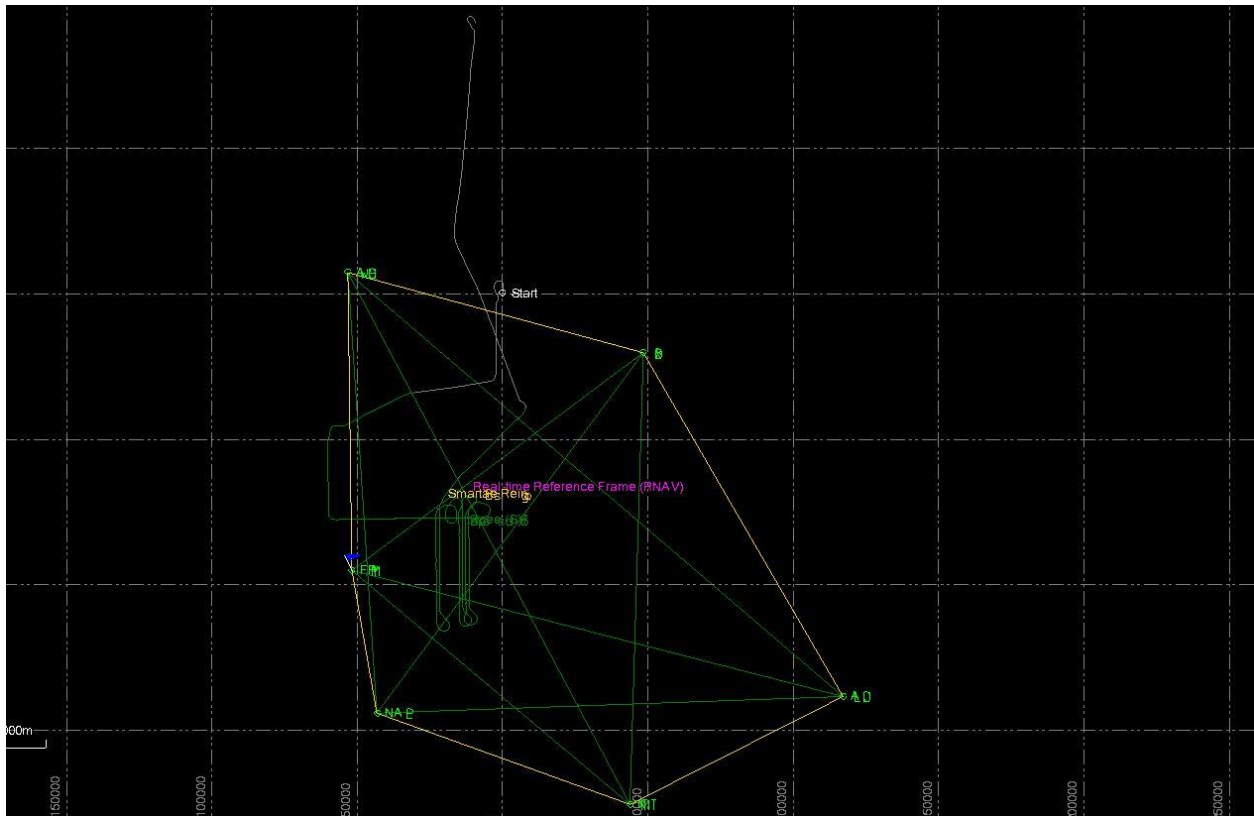




— x accelerometer scale error (ppm) — y accelerometer scale error (ppm) — z accelerometer scale error (ppm)



— x accelerometer bias (micro-g) — y accelerometer bias (micro-g) — z accelerometer bias (micro-g)



MISSION: 2SU18353A1

Timing

Start

End

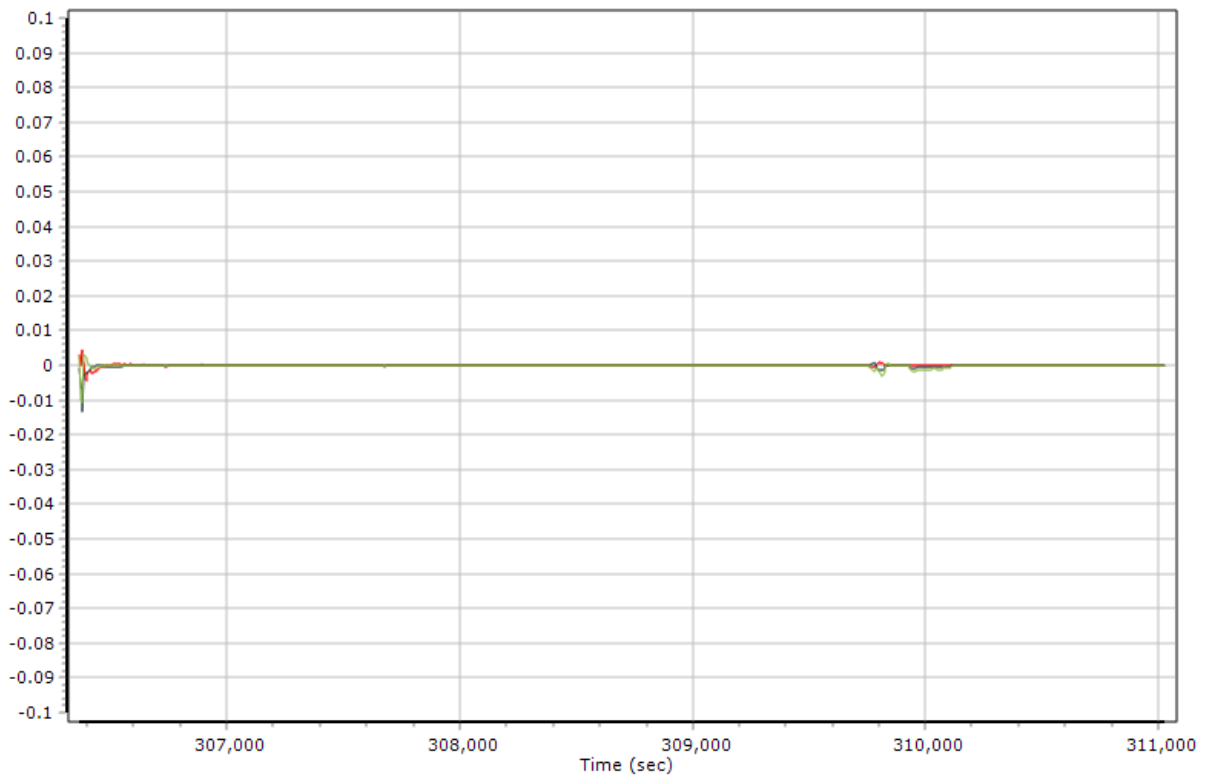
Entire time interval

Seconds of start week

UTC Offset

Data	Incr. (sec)
Output Record	0.005000
IMU	0.005000
Primary GNSS	1.000000





— North (m) — East (m) — Down (m) — DR mode

Disable Satellites

GPS | GLONASS | BEIDOU | QZSS

- | | | | |
|--------------------------------|---------------------------------|---------------------------------|---------------------------------|
| <input type="checkbox"/> PRN 1 | <input type="checkbox"/> PRN 10 | <input type="checkbox"/> PRN 19 | <input type="checkbox"/> PRN 28 |
| <input type="checkbox"/> PRN 2 | <input type="checkbox"/> PRN 11 | <input type="checkbox"/> PRN 20 | <input type="checkbox"/> PRN 29 |
| <input type="checkbox"/> PRN 3 | <input type="checkbox"/> PRN 12 | <input type="checkbox"/> PRN 21 | <input type="checkbox"/> PRN 30 |
| <input type="checkbox"/> PRN 4 | <input type="checkbox"/> PRN 13 | <input type="checkbox"/> PRN 22 | <input type="checkbox"/> PRN 31 |
| <input type="checkbox"/> PRN 5 | <input type="checkbox"/> PRN 14 | <input type="checkbox"/> PRN 23 | <input type="checkbox"/> PRN 32 |
| <input type="checkbox"/> PRN 6 | <input type="checkbox"/> PRN 15 | <input type="checkbox"/> PRN 24 | |
| <input type="checkbox"/> PRN 7 | <input type="checkbox"/> PRN 16 | <input type="checkbox"/> PRN 25 | |
| <input type="checkbox"/> PRN 8 | <input type="checkbox"/> PRN 17 | <input type="checkbox"/> PRN 26 | |
| <input type="checkbox"/> PRN 9 | <input type="checkbox"/> PRN 18 | <input type="checkbox"/> PRN 27 | |



Elevation Mask Angle

Force GPS Only

Disable Satellites

GPS

GLONASS

BEIDOU

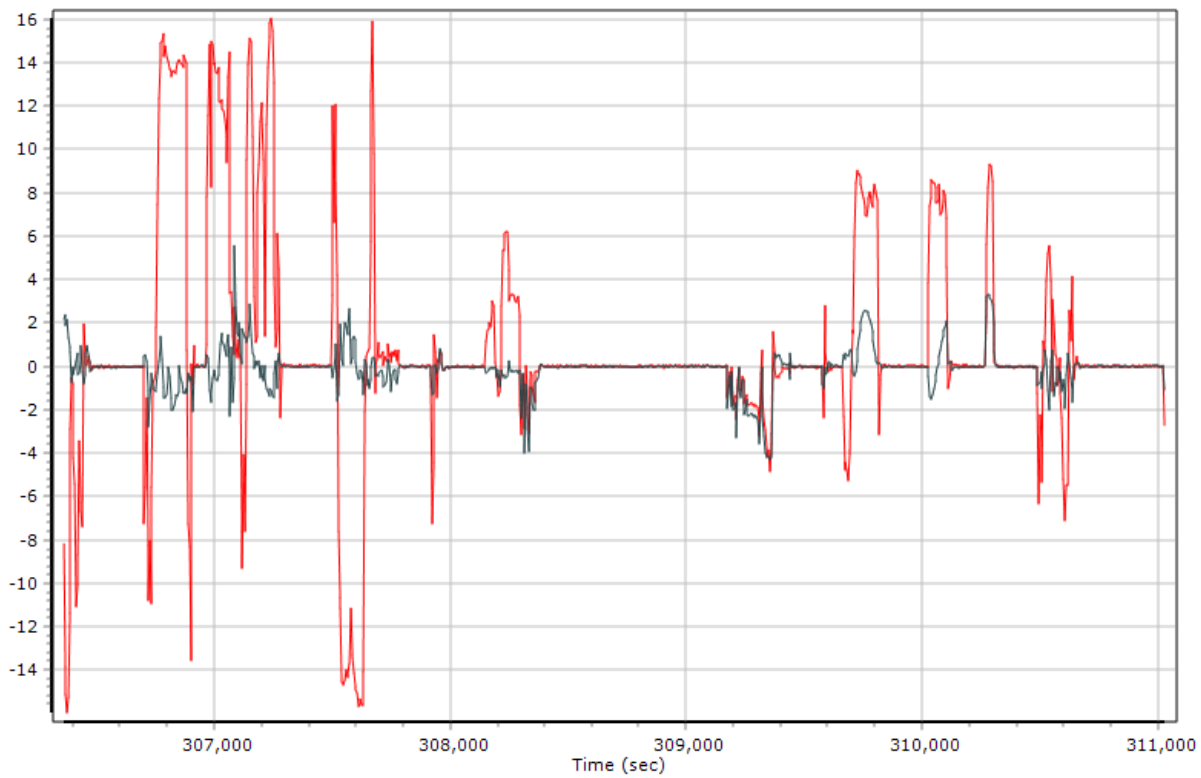
QZSS

- | | | |
|---------------------------------|----------------------------------|----------------------------------|
| <input type="checkbox"/> SLOT 1 | <input type="checkbox"/> SLOT 10 | <input type="checkbox"/> SLOT 19 |
| <input type="checkbox"/> SLOT 2 | <input type="checkbox"/> SLOT 11 | <input type="checkbox"/> SLOT 20 |
| <input type="checkbox"/> SLOT 3 | <input type="checkbox"/> SLOT 12 | <input type="checkbox"/> SLOT 21 |
| <input type="checkbox"/> SLOT 4 | <input type="checkbox"/> SLOT 13 | <input type="checkbox"/> SLOT 22 |
| <input type="checkbox"/> SLOT 5 | <input type="checkbox"/> SLOT 14 | <input type="checkbox"/> SLOT 23 |
| <input type="checkbox"/> SLOT 6 | <input type="checkbox"/> SLOT 15 | <input type="checkbox"/> SLOT 24 |
| <input type="checkbox"/> SLOT 7 | <input type="checkbox"/> SLOT 16 | |
| <input type="checkbox"/> SLOT 8 | <input type="checkbox"/> SLOT 17 | |
| <input type="checkbox"/> SLOT 9 | <input type="checkbox"/> SLOT 18 | |

Elevation Mask Angle

10.000 deg

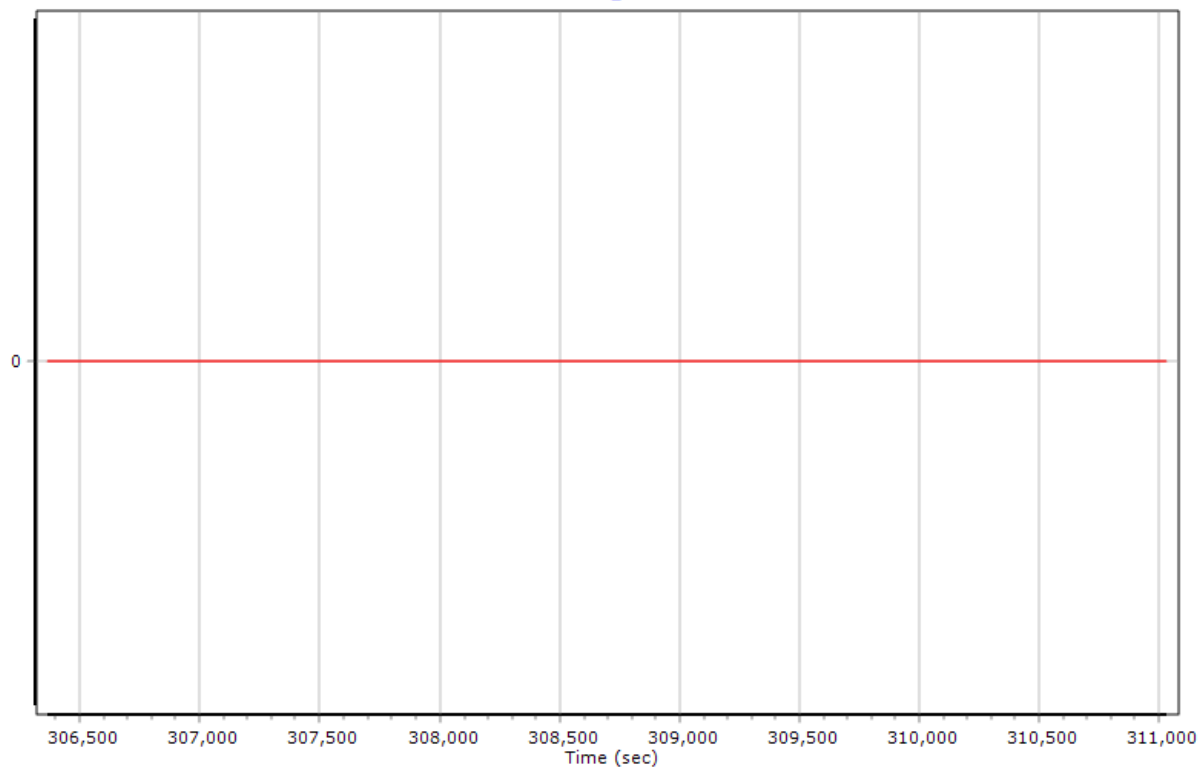
Force GPS Only



— Roll (deg) — Pitch (deg)

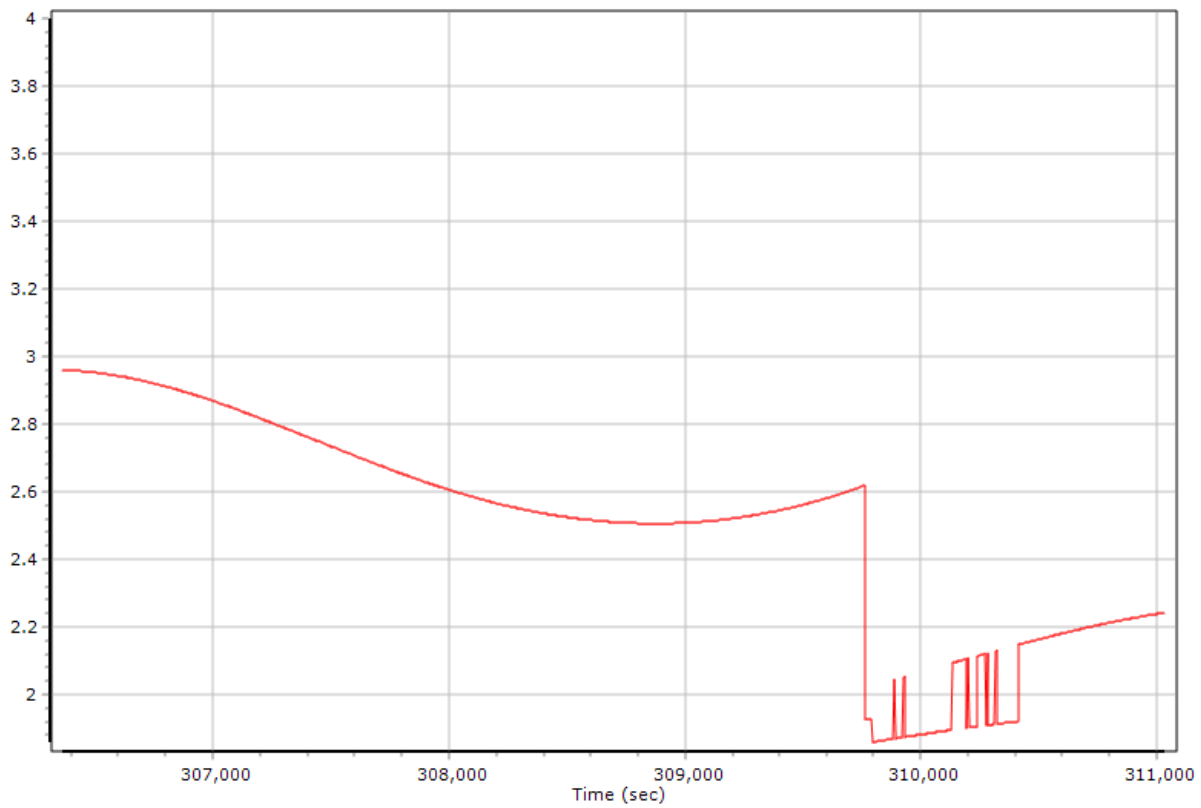


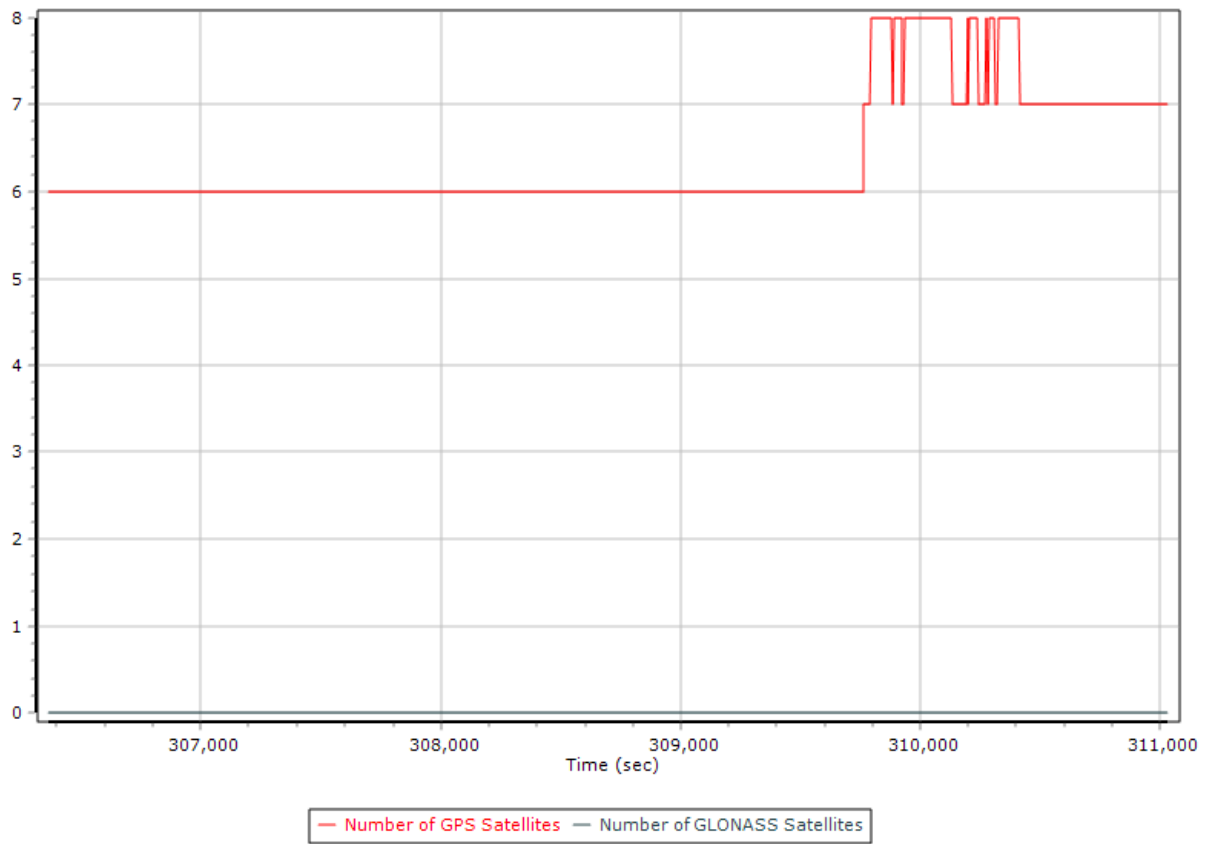
Processing Mode



0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = C/A, 7 = GNSS Nav, 8 = DR

PDOP





Stabilized Mount to IMU Lever Arm

X
Y
Z

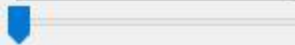
Stabilized Mount to IMU Mounting Angles

X
Y
Z

Stabilized Mount to Primary GNSS Lever Arm

X
Y
Z

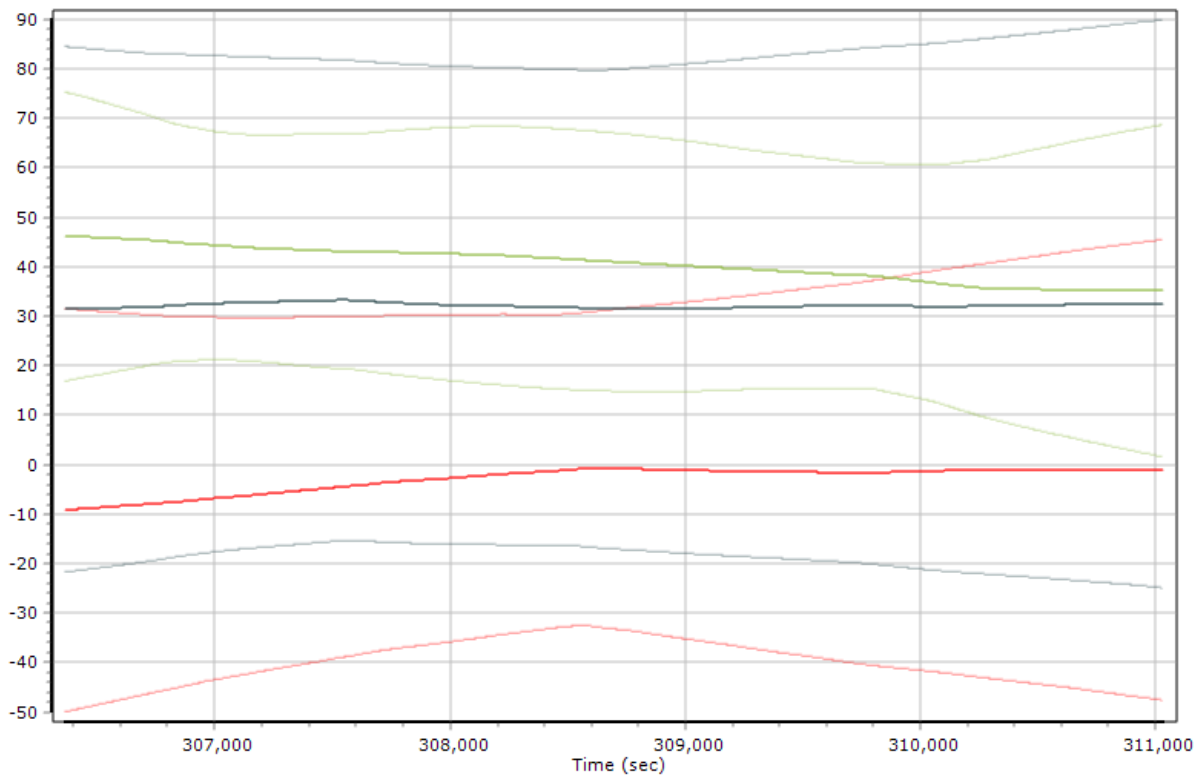
Standard Deviation


<3cm 10cm 50cm 1m 10m

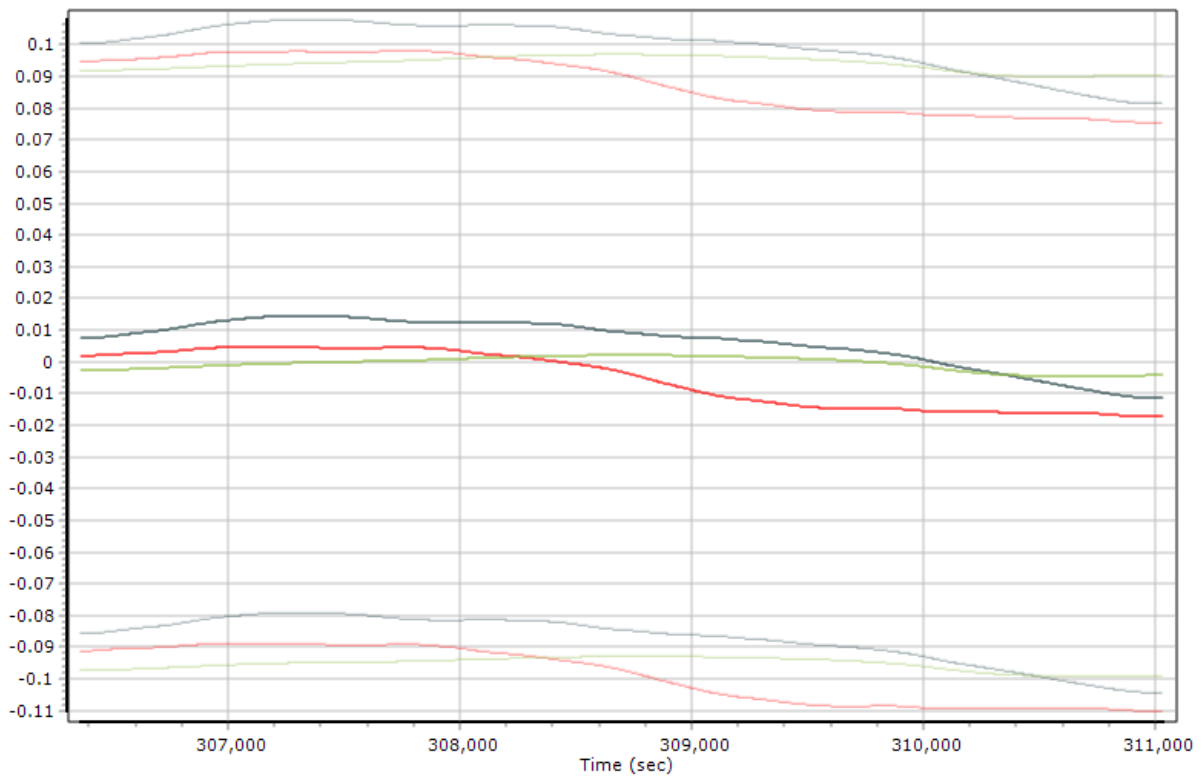
Aircraft to Stabilized Mount Mounting Angles

X
Y
Z

Measurements are to the stabilized platform's center of rotation with the Gimbal in the rest position.

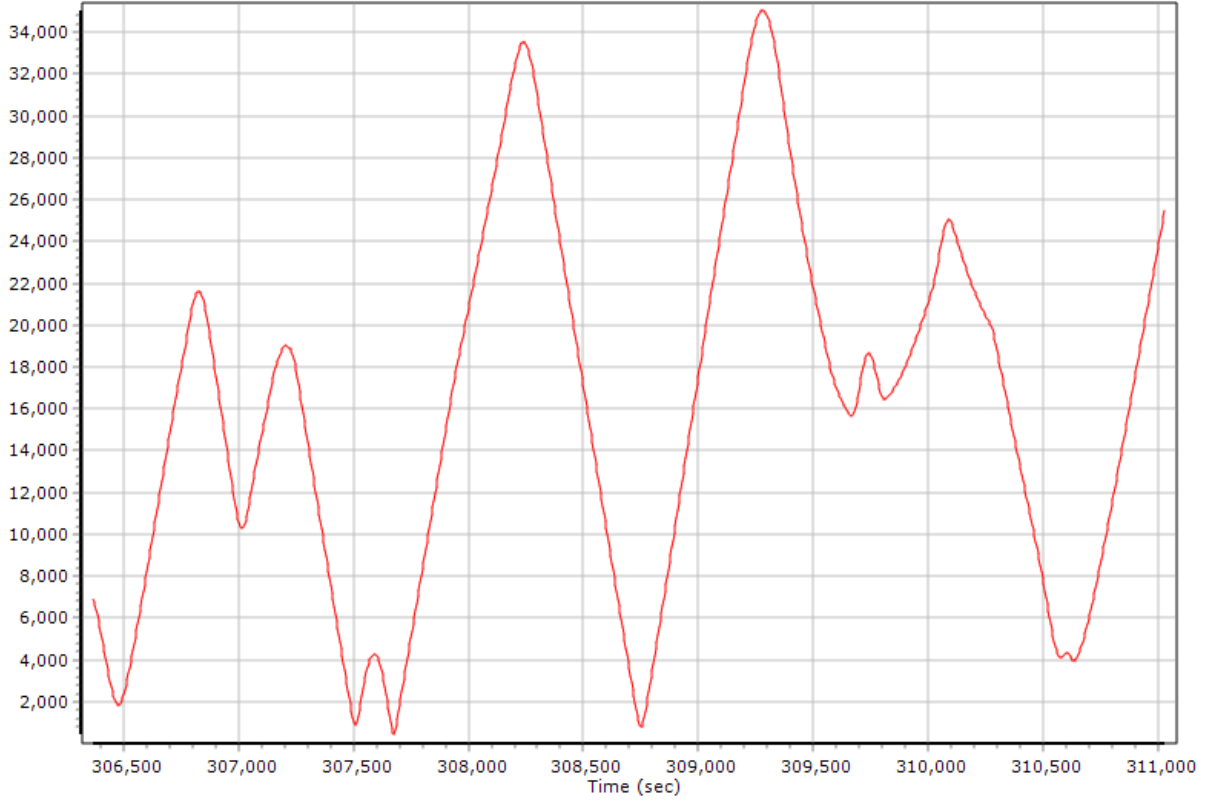


— x gyro scale error (ppm) — y gyro scale error (ppm) — z gyro scale error (ppm)

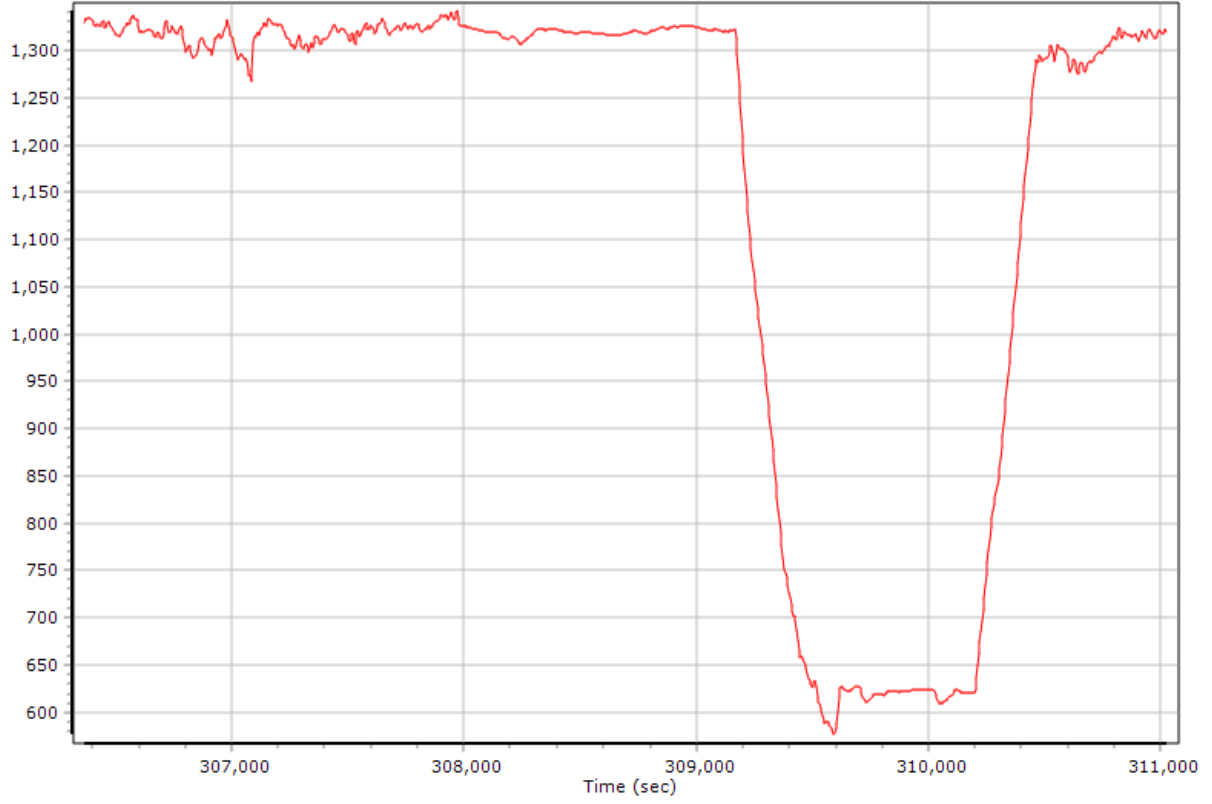


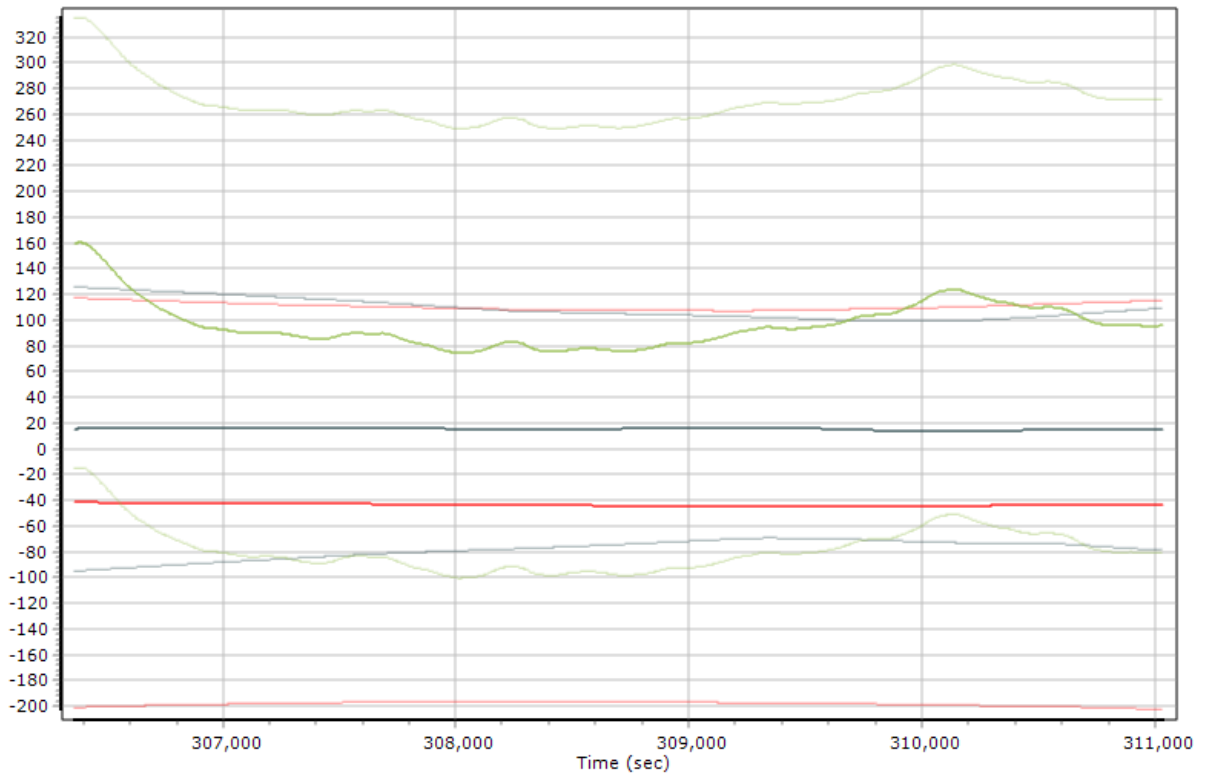
— x gyro bias (deg/hr) — y gyro bias (deg/hr) — z gyro bias (deg/hr)

Baseline Length(m)



Altitude (m)

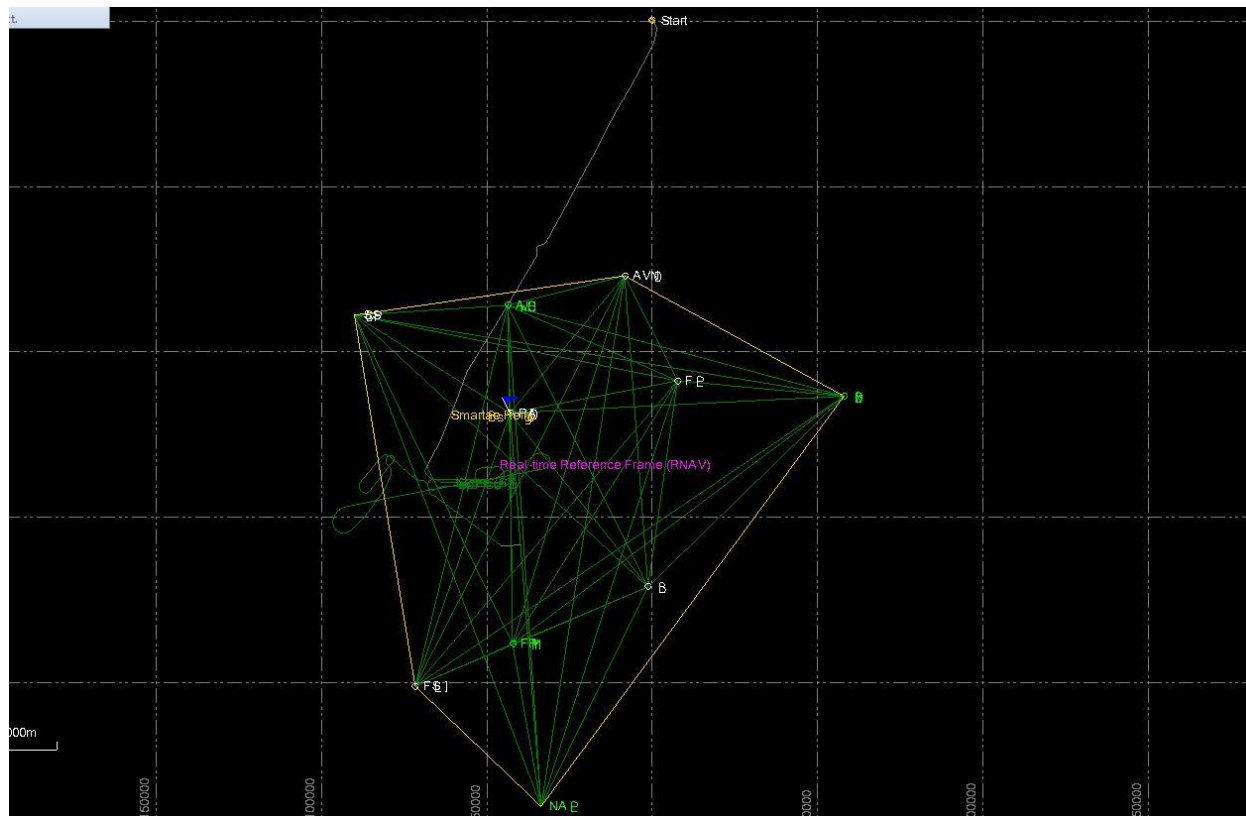




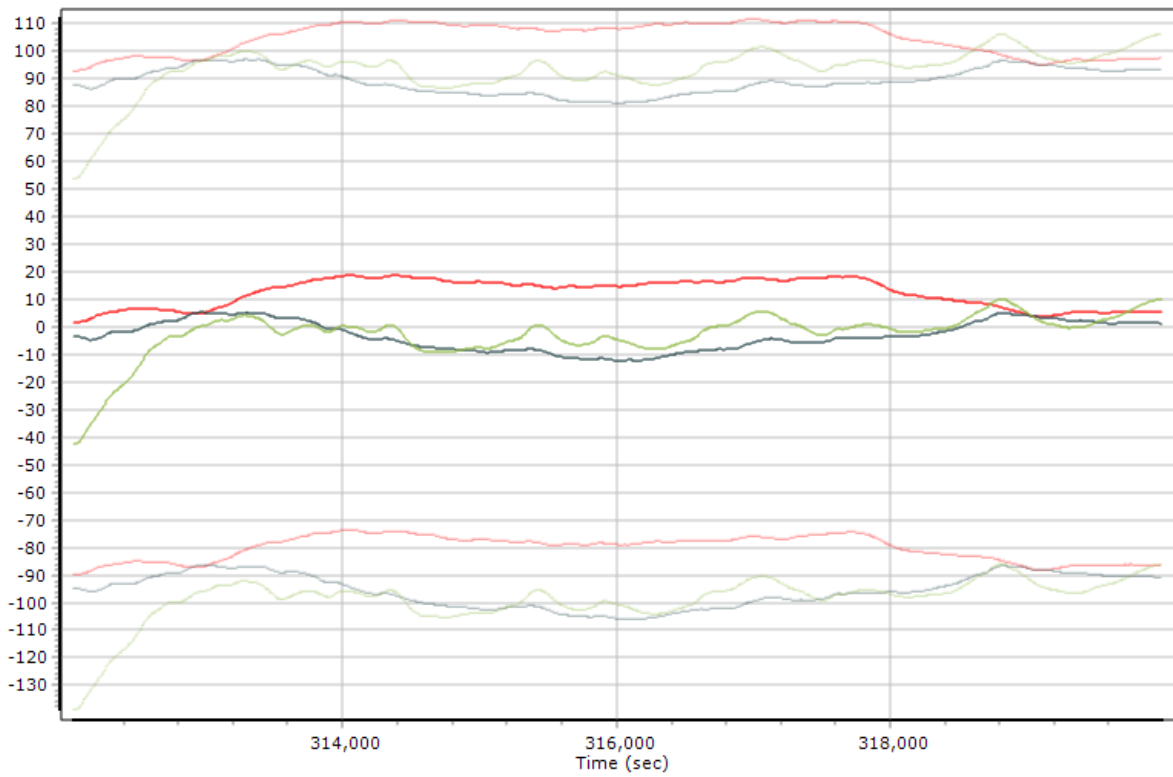
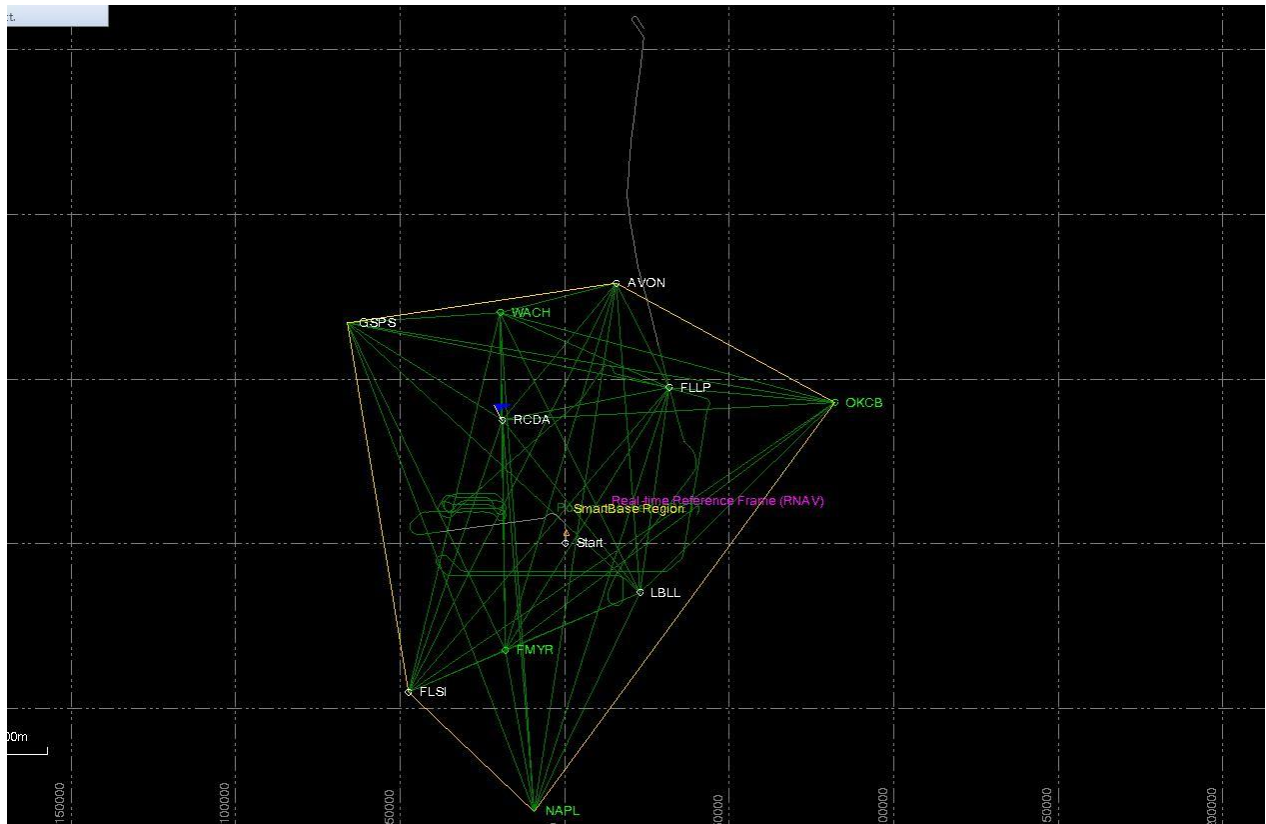
— x accelerometer scale error (ppm) — y accelerometer scale error (ppm) — z accelerometer scale error (ppm)



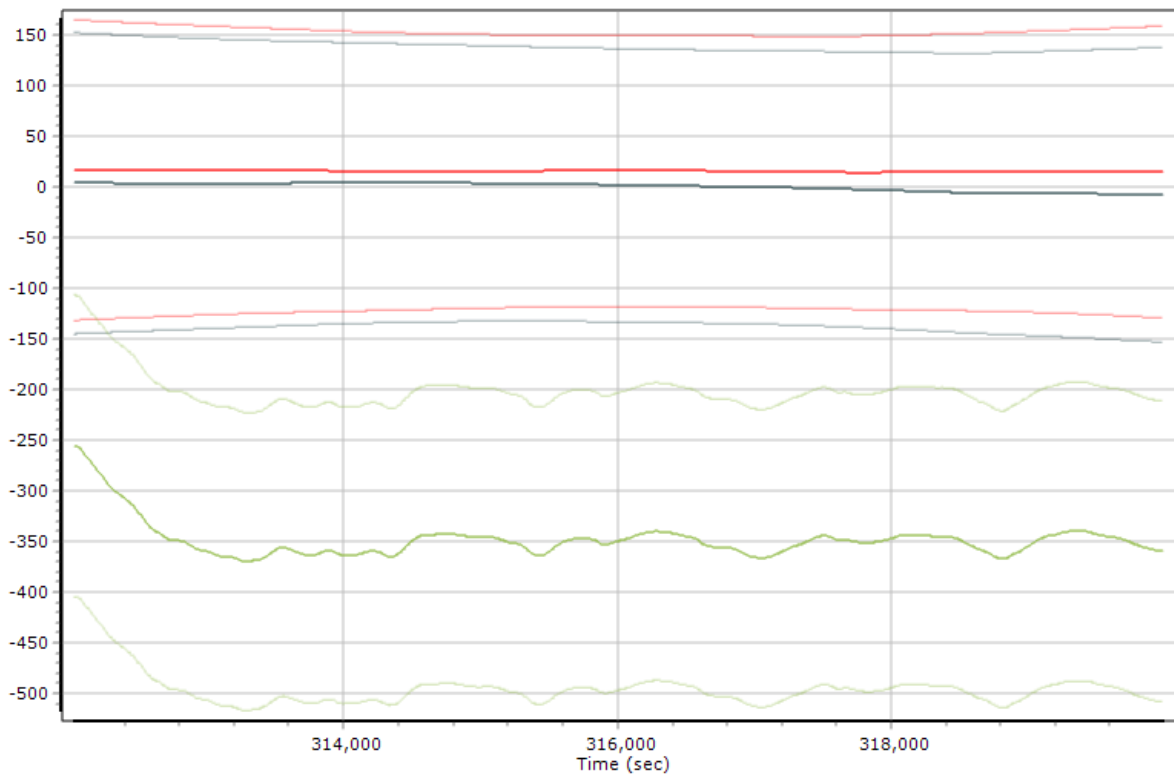
— x accelerometer bias (micro-g) — y accelerometer bias (micro-g) — z accelerometer bias (micro-g)



MISSION: 2SU18353A2

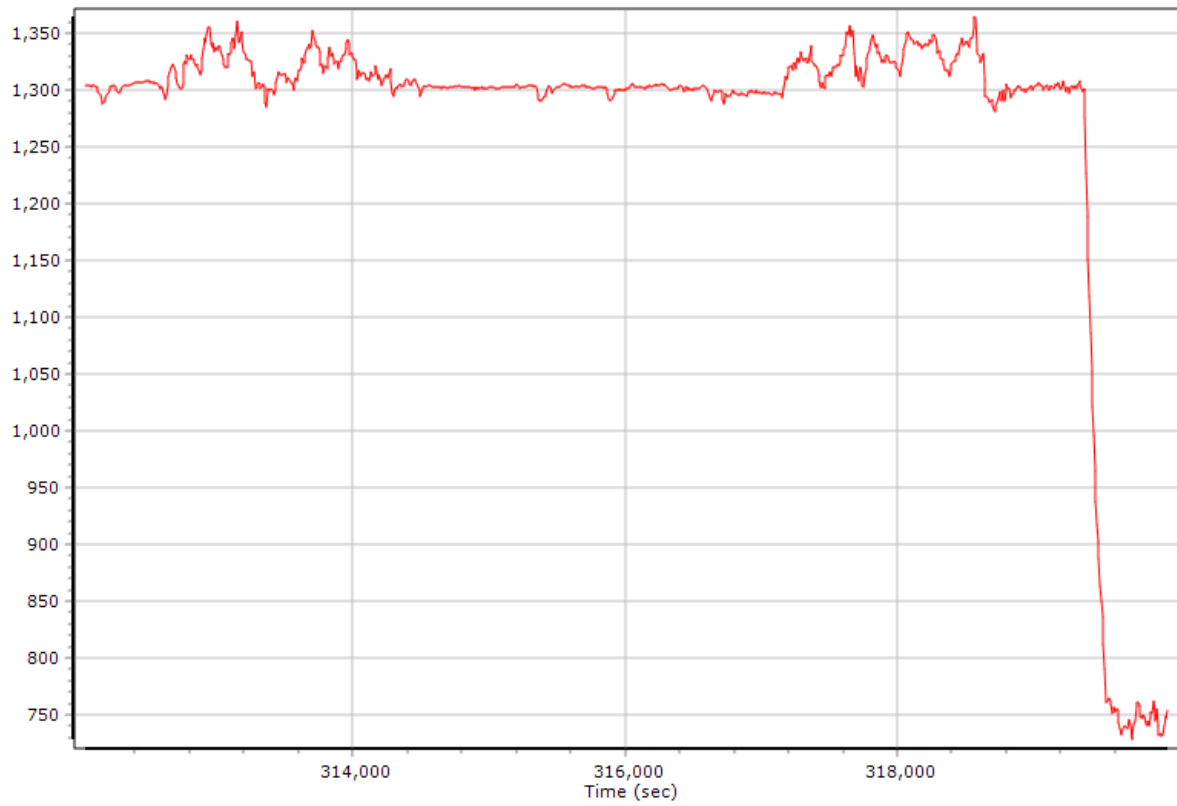


— x accelerometer bias (micro-g) — y accelerometer bias (micro-g) — z accelerometer bias (micro-g)

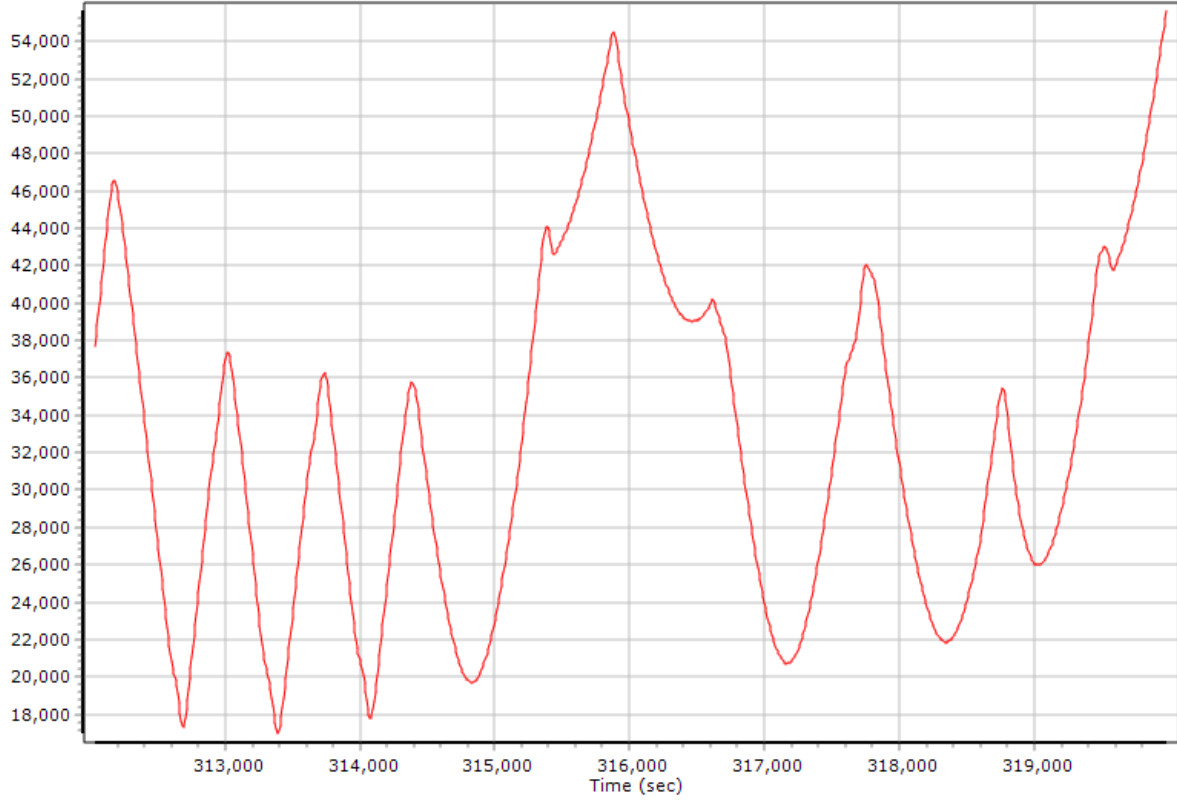


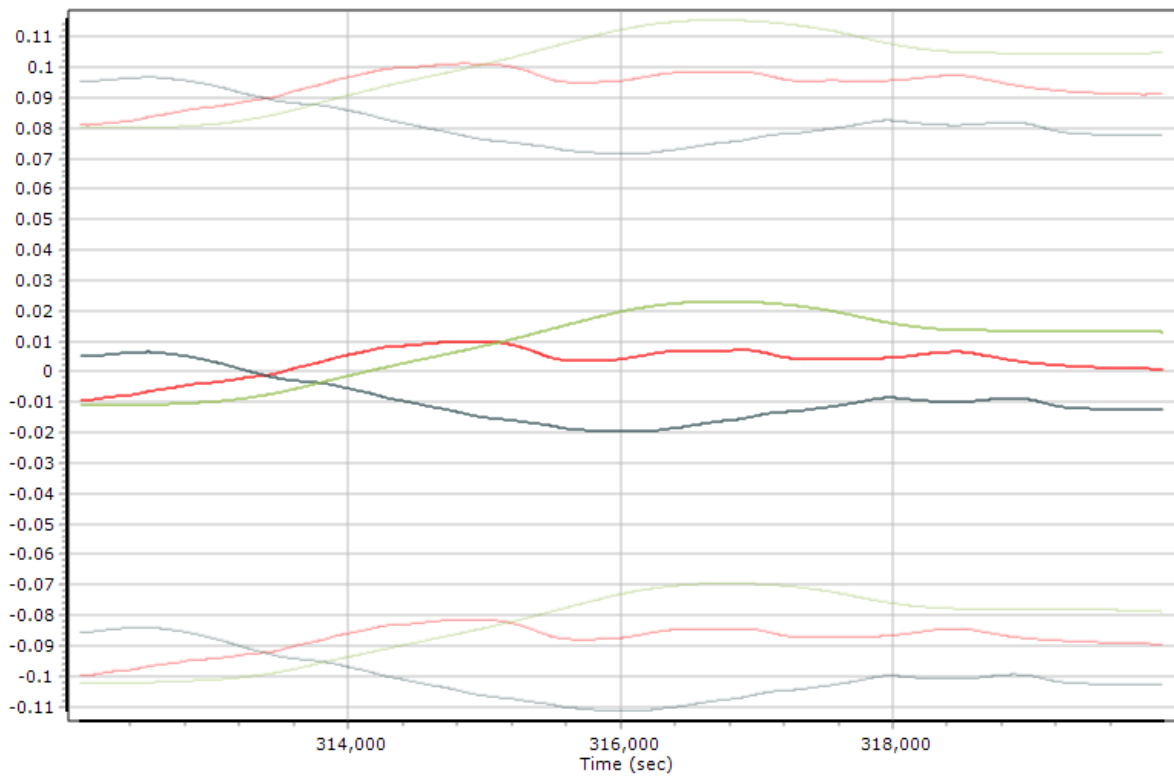
— x accelerometer scale error (ppm) — y accelerometer scale error (ppm) — z accelerometer scale error (ppm)

Altitude (m)

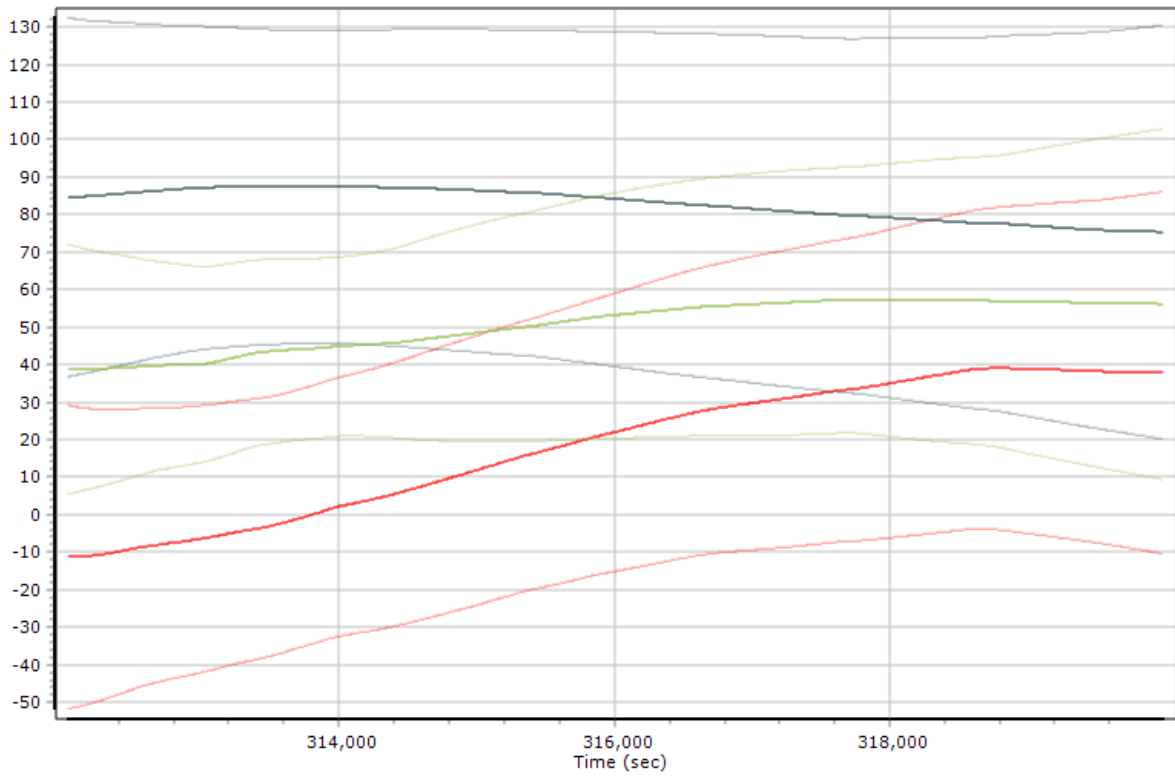


Baseline Length(m)





— x gyro bias (deg/hr) — y gyro bias (deg/hr) — z gyro bias (deg/hr)



— x gyro scale error (ppm) — y gyro scale error (ppm) — z gyro scale error (ppm)

Stabilized Mount to IMU Lever Arm

X
Y
Z

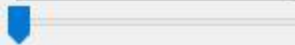
Stabilized Mount to IMU Mounting Angles

X
Y
Z

Stabilized Mount to Primary GNSS Lever Arm

X
Y
Z

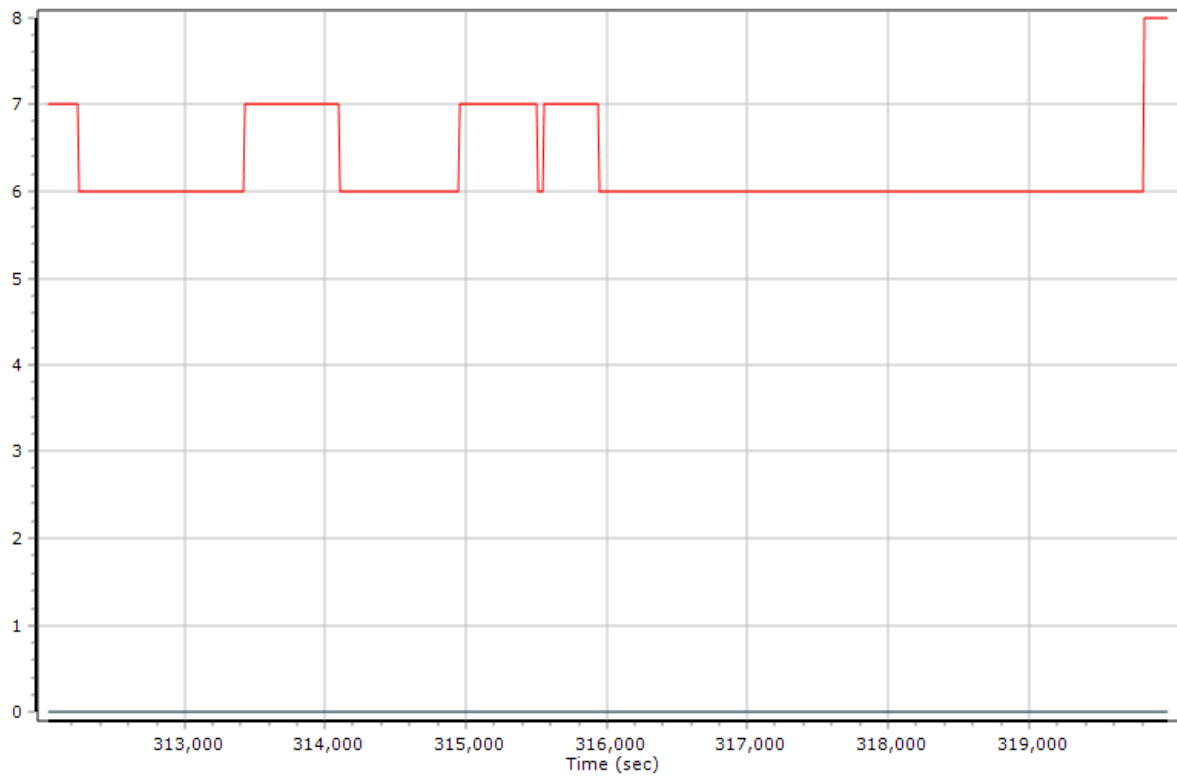
Standard Deviation


<3cm 10cm 50cm 1m 10m

Aircraft to Stabilized Mount Mounting Angles

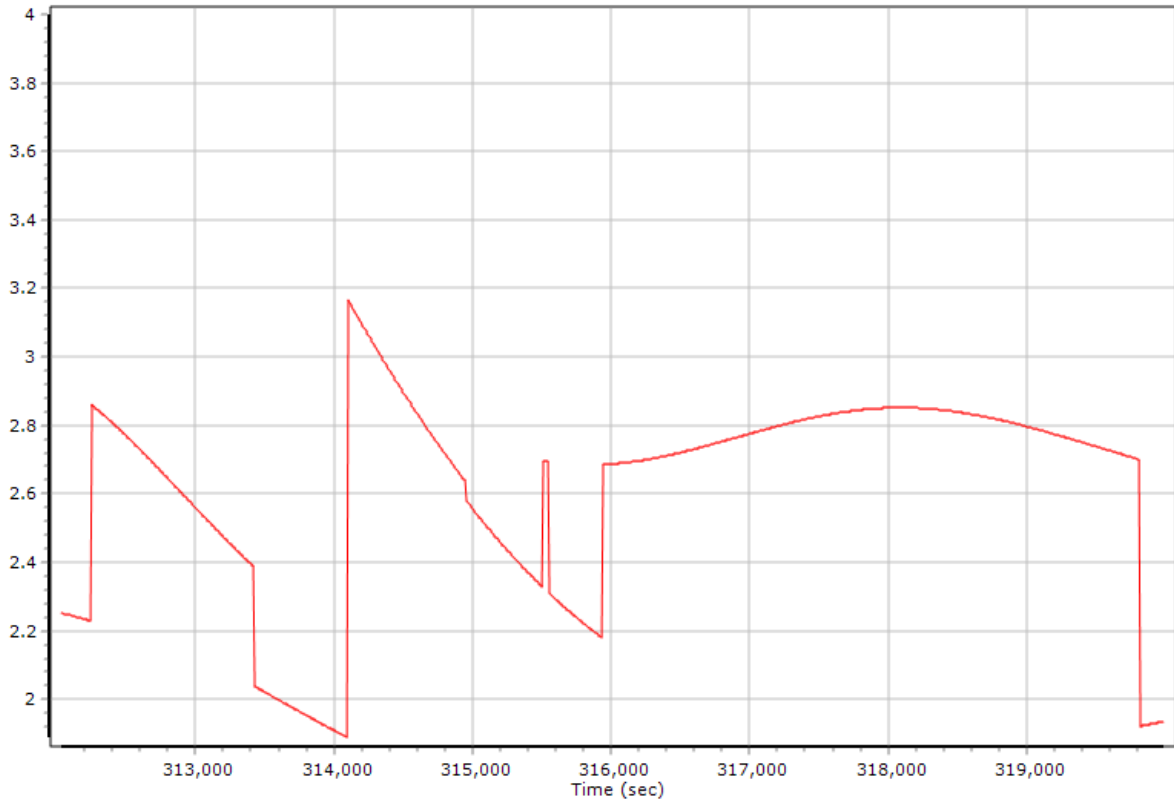
X
Y
Z

Measurements are to the stabilized platform's center of rotation with the Gimbal in the rest position.

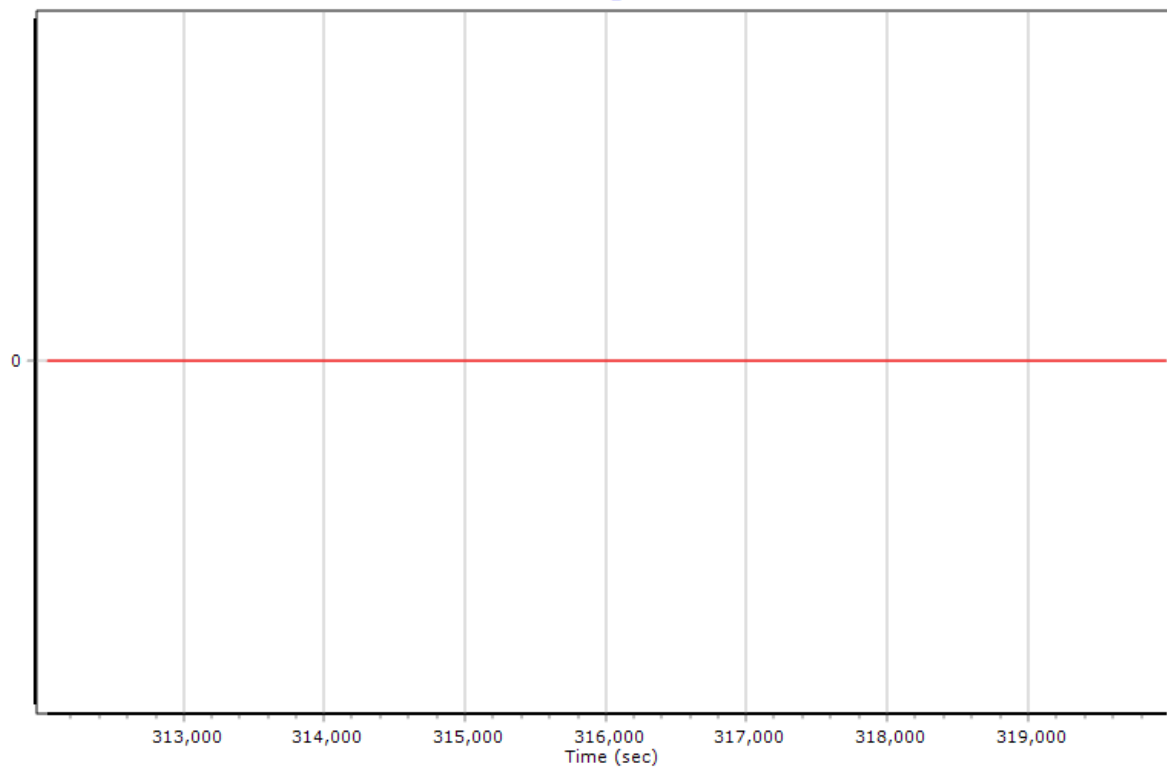


— Number of GPS Satellites — Number of GLONASS Satellites

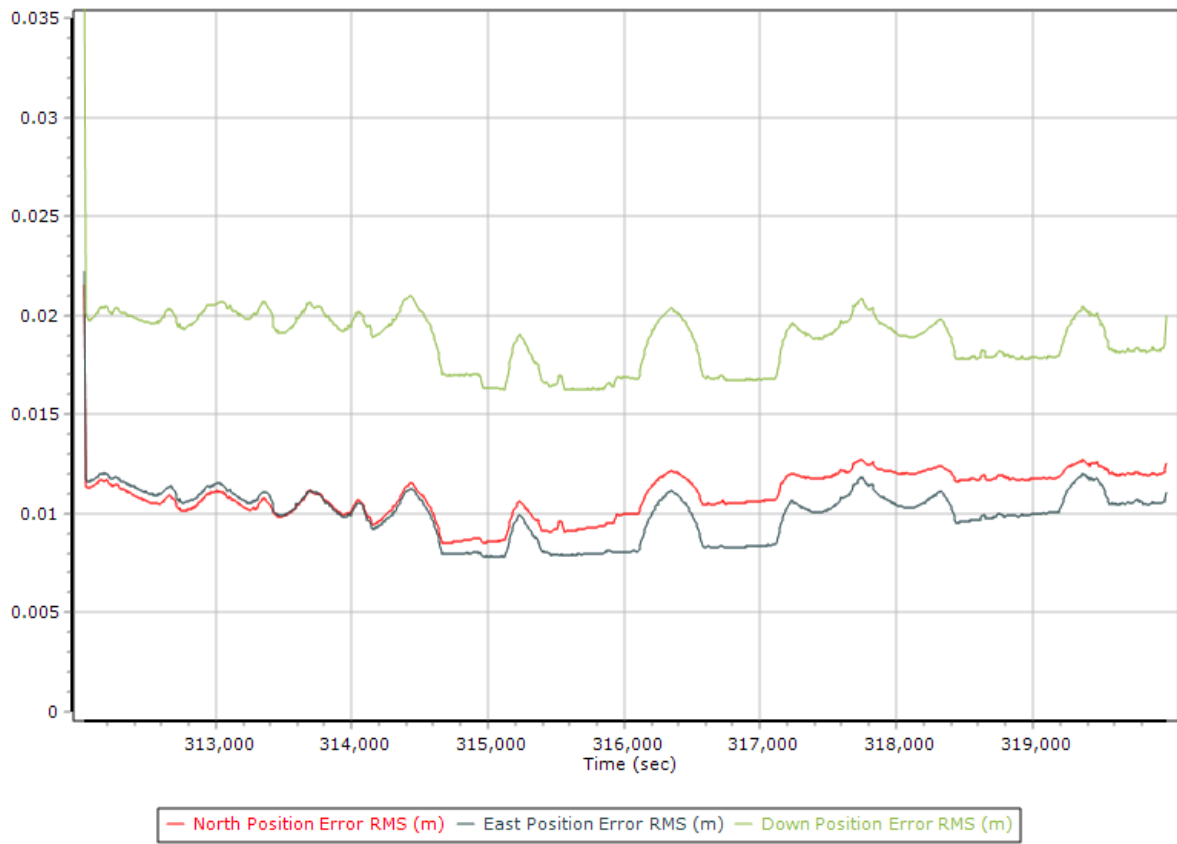
PDOP

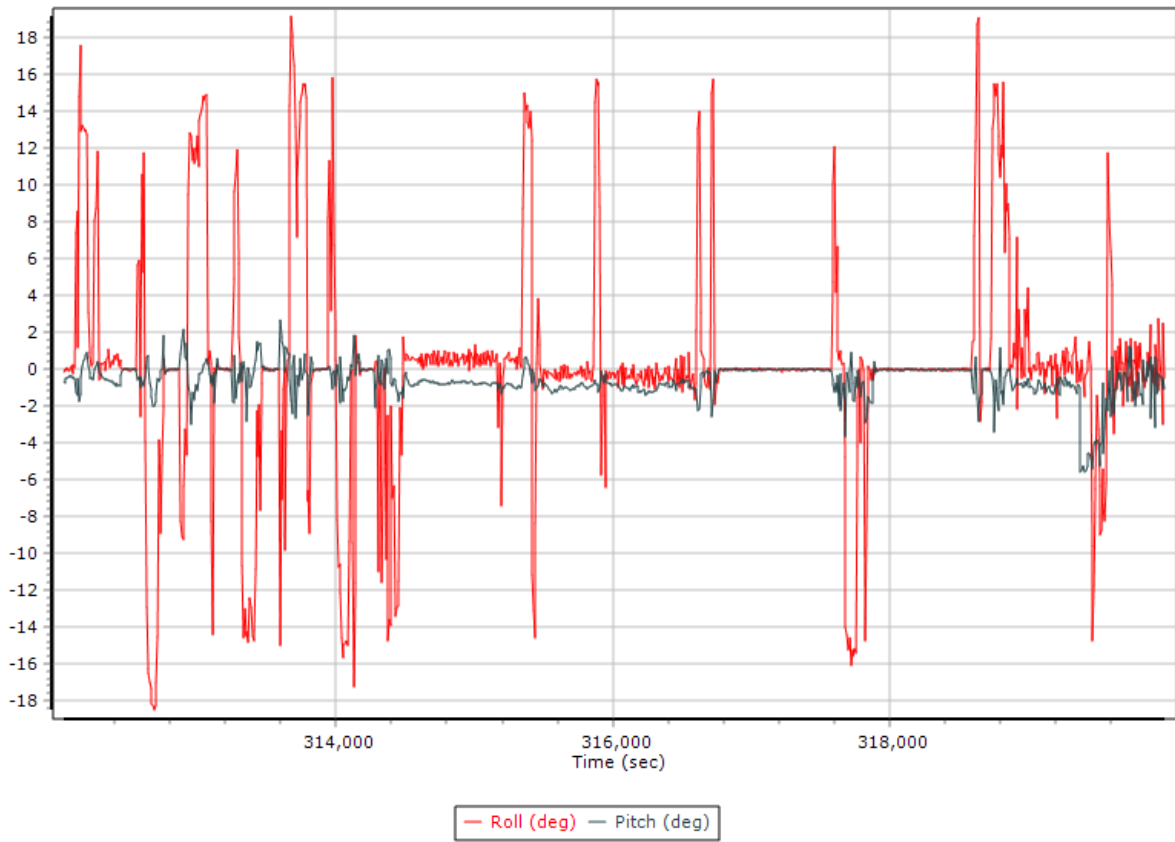


Processing Mode



0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = C/A, 7 = GNSS Nav, 8 = DR





Disable Satellites

GPS GLONASS BEIDOU QZSS

- | | | |
|---------------------------------|----------------------------------|----------------------------------|
| <input type="checkbox"/> SLOT 1 | <input type="checkbox"/> SLOT 10 | <input type="checkbox"/> SLOT 19 |
| <input type="checkbox"/> SLOT 2 | <input type="checkbox"/> SLOT 11 | <input type="checkbox"/> SLOT 20 |
| <input type="checkbox"/> SLOT 3 | <input type="checkbox"/> SLOT 12 | <input type="checkbox"/> SLOT 21 |
| <input type="checkbox"/> SLOT 4 | <input type="checkbox"/> SLOT 13 | <input type="checkbox"/> SLOT 22 |
| <input type="checkbox"/> SLOT 5 | <input type="checkbox"/> SLOT 14 | <input type="checkbox"/> SLOT 23 |
| <input type="checkbox"/> SLOT 6 | <input type="checkbox"/> SLOT 15 | <input type="checkbox"/> SLOT 24 |
| <input type="checkbox"/> SLOT 7 | <input type="checkbox"/> SLOT 16 | |
| <input type="checkbox"/> SLOT 8 | <input type="checkbox"/> SLOT 17 | |
| <input type="checkbox"/> SLOT 9 | <input type="checkbox"/> SLOT 18 | |

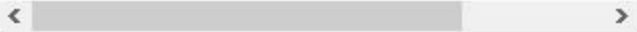
Elevation Mask Angle

Force GPS Only

Disable Satellites

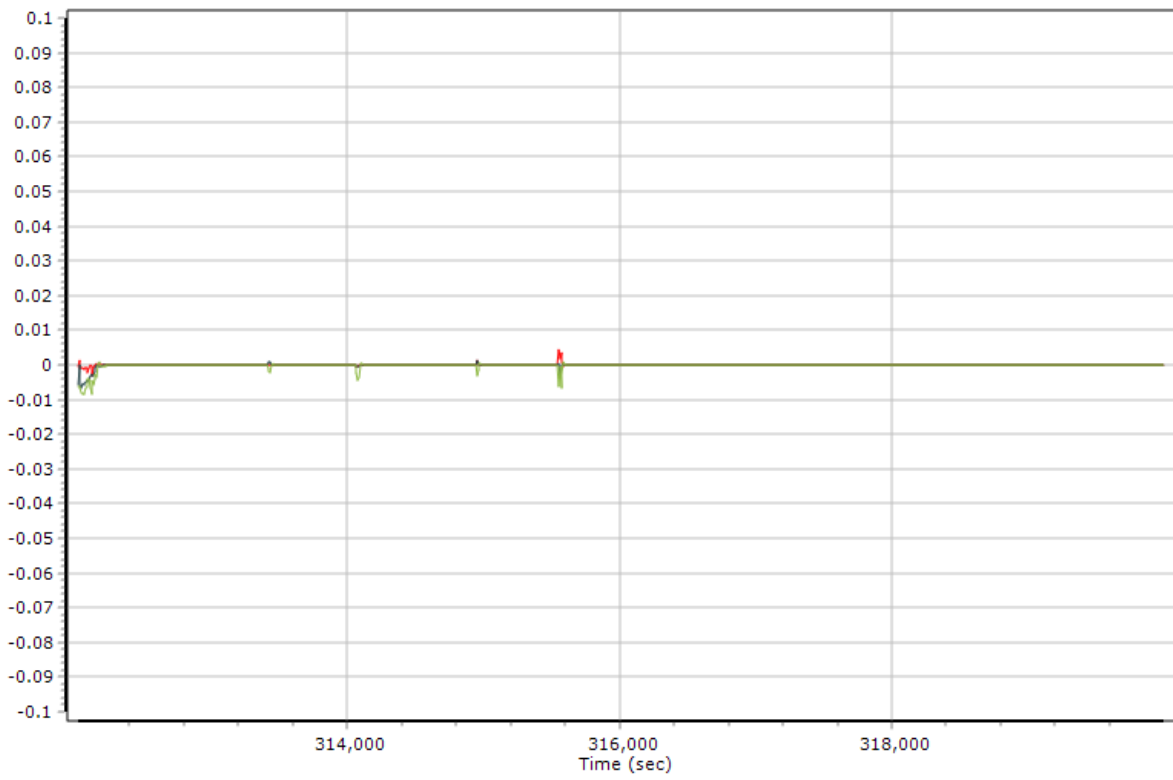
GPS GLONASS BEIDOU QZSS

- | | | | |
|--------------------------------|---------------------------------|---------------------------------|---------------------------------|
| <input type="checkbox"/> PRN 1 | <input type="checkbox"/> PRN 10 | <input type="checkbox"/> PRN 19 | <input type="checkbox"/> PRN 28 |
| <input type="checkbox"/> PRN 2 | <input type="checkbox"/> PRN 11 | <input type="checkbox"/> PRN 20 | <input type="checkbox"/> PRN 29 |
| <input type="checkbox"/> PRN 3 | <input type="checkbox"/> PRN 12 | <input type="checkbox"/> PRN 21 | <input type="checkbox"/> PRN 30 |
| <input type="checkbox"/> PRN 4 | <input type="checkbox"/> PRN 13 | <input type="checkbox"/> PRN 22 | <input type="checkbox"/> PRN 31 |
| <input type="checkbox"/> PRN 5 | <input type="checkbox"/> PRN 14 | <input type="checkbox"/> PRN 23 | <input type="checkbox"/> PRN 32 |
| <input type="checkbox"/> PRN 6 | <input type="checkbox"/> PRN 15 | <input type="checkbox"/> PRN 24 | |
| <input type="checkbox"/> PRN 7 | <input type="checkbox"/> PRN 16 | <input type="checkbox"/> PRN 25 | |
| <input type="checkbox"/> PRN 8 | <input type="checkbox"/> PRN 17 | <input type="checkbox"/> PRN 26 | |
| <input type="checkbox"/> PRN 9 | <input type="checkbox"/> PRN 18 | <input type="checkbox"/> PRN 27 | |



Elevation Mask Angle

Force GPS Only



— North (m) — East (m) — Down (m) — DR mode

Timing

Start 312030.631

End 319992.474

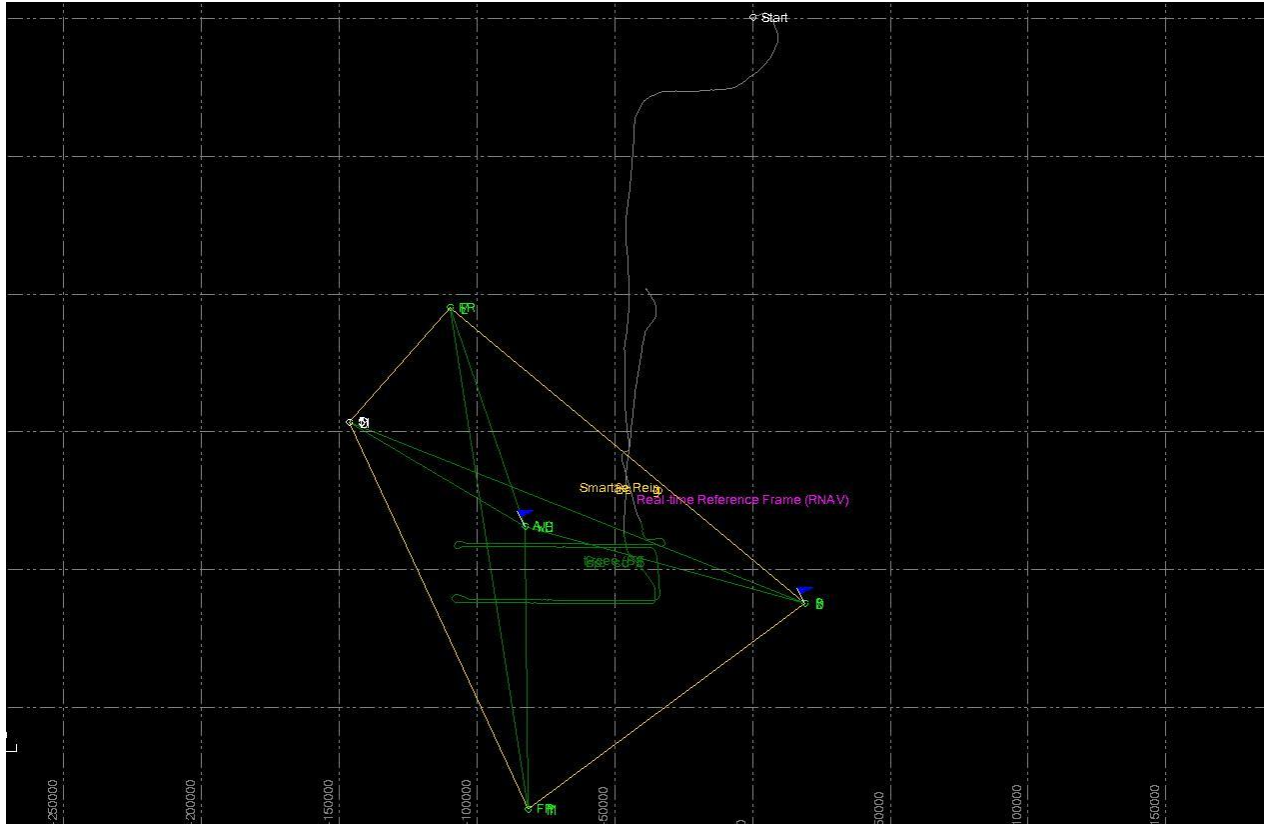
Entire time interval

Seconds of start week

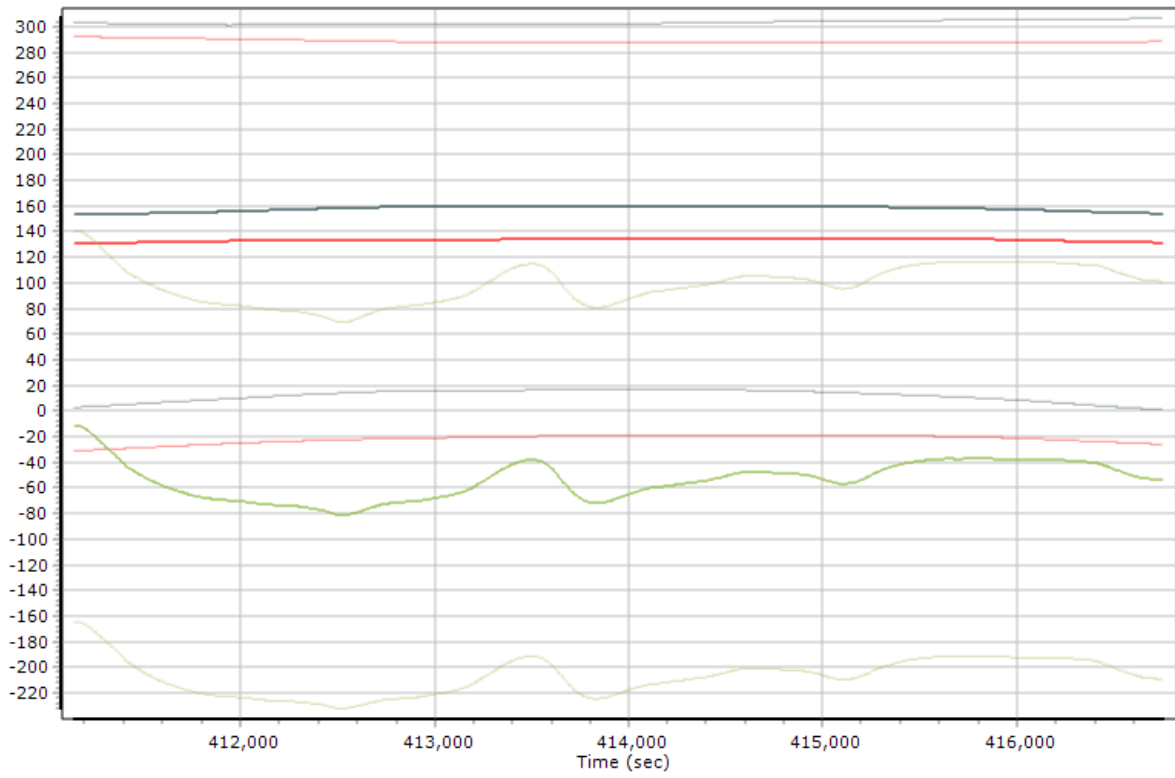
UTC Offset 18.000

Data	Incr. (sec)
Output Record	0.005000
IMU	0.005000
Primary GNSS	1.000000

MISSION: 45A18340A

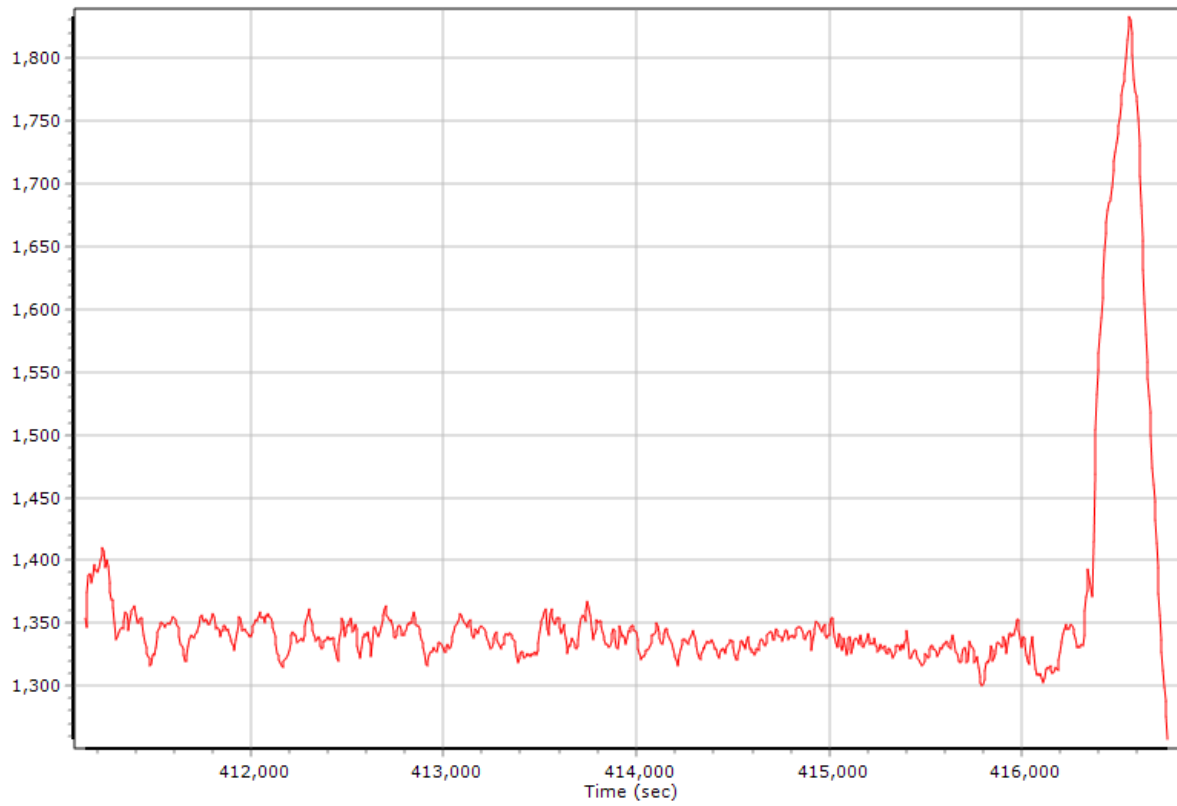


— x accelerometer bias (micro-g) — y accelerometer bias (micro-g) — z accelerometer bias (micro-g)

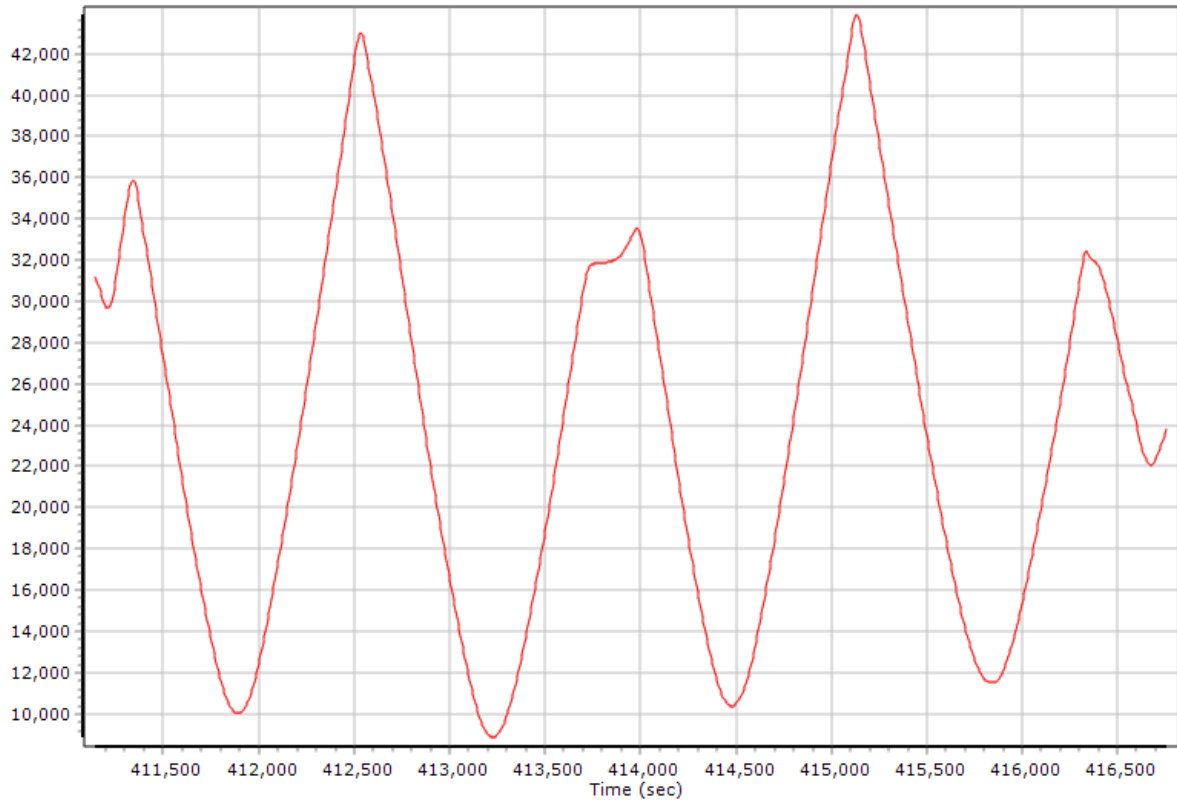


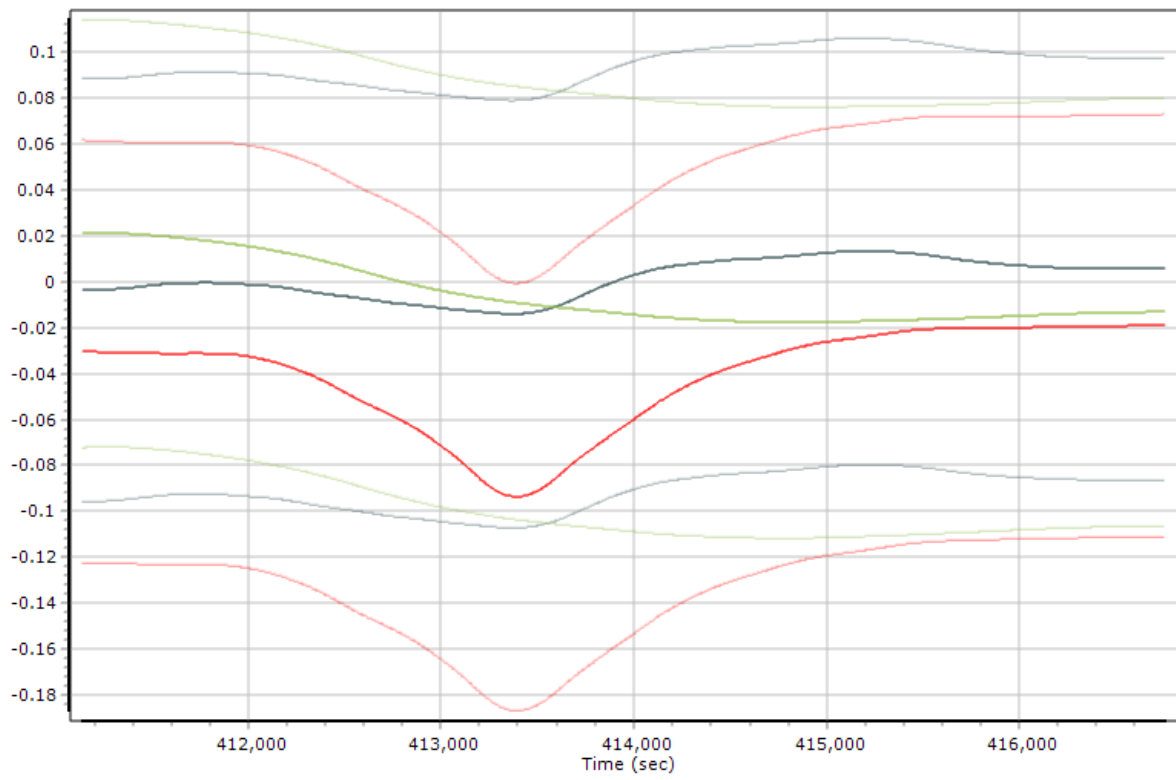
— x accelerometer scale error (ppm) — y accelerometer scale error (ppm) — z accelerometer scale error (ppm)

Altitude (m)

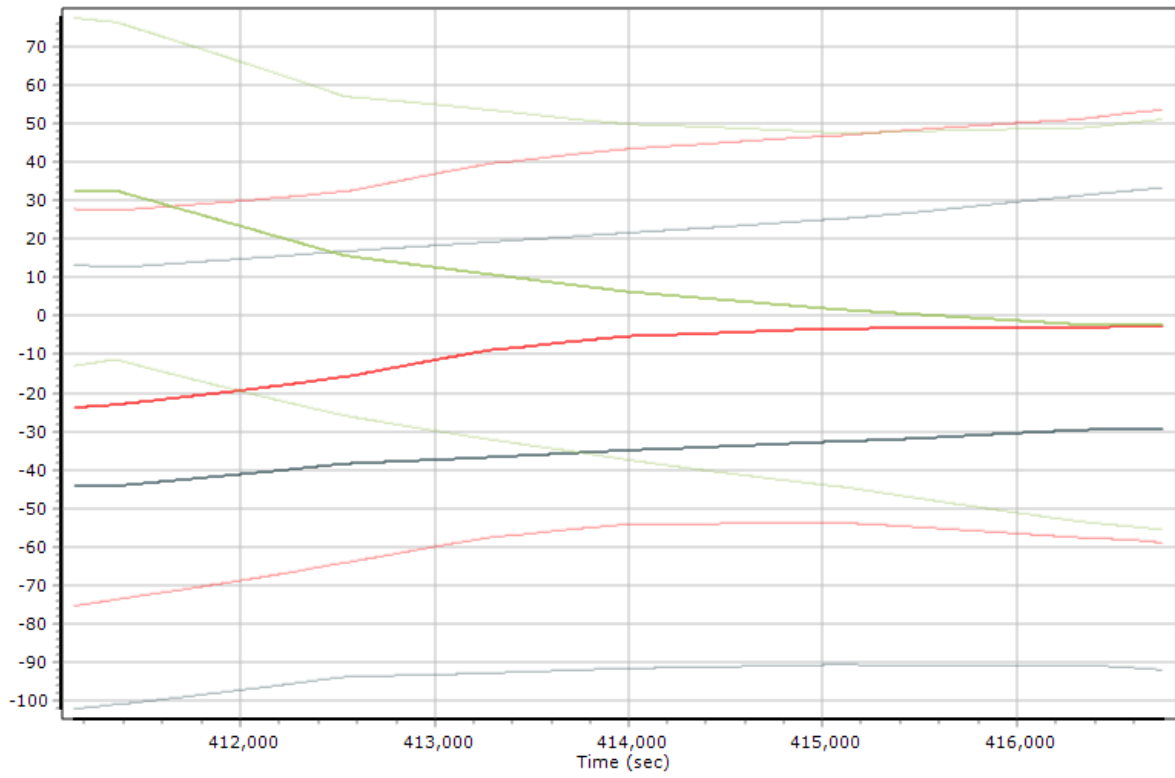


Baseline Length(m)





— x gyro bias (deg/hr) — y gyro bias (deg/hr) — z gyro bias (deg/hr)



— x gyro scale error (ppm) — y gyro scale error (ppm) — z gyro scale error (ppm)

Stabilized Mount to IMU Lever Arm

X
Y
Z

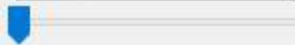
Stabilized Mount to IMU Mounting Angles

X
Y
Z

Stabilized Mount to Primary GNSS Lever Arm

X
Y
Z

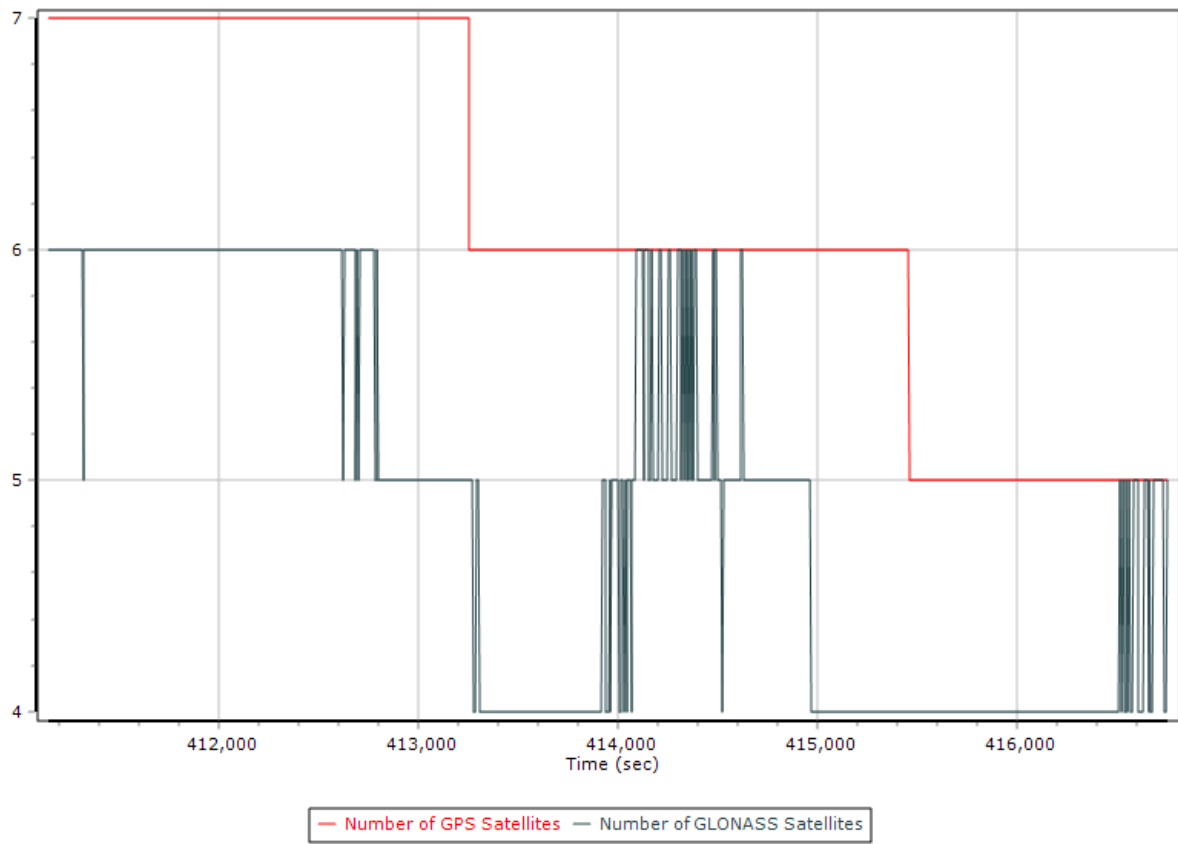
Standard Deviation


<3cm 10cm 50cm 1m 10m

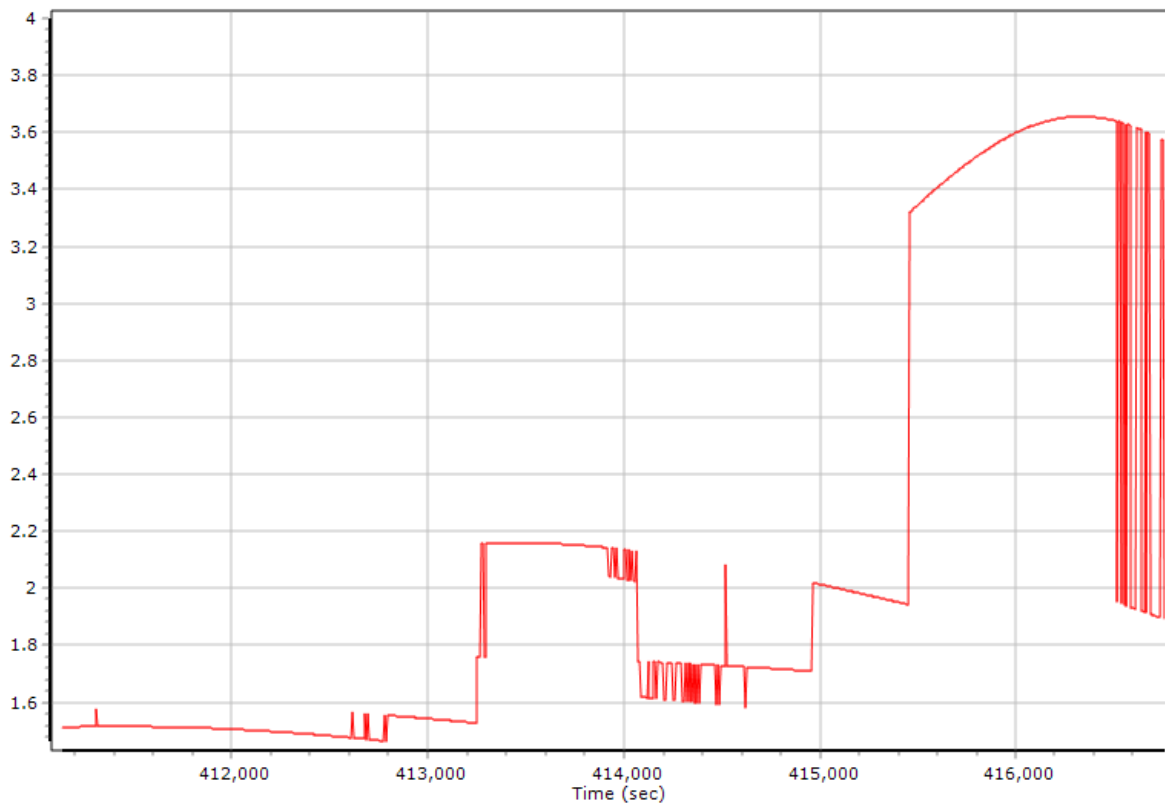
Aircraft to Stabilized Mount Mounting Angles

X
Y
Z

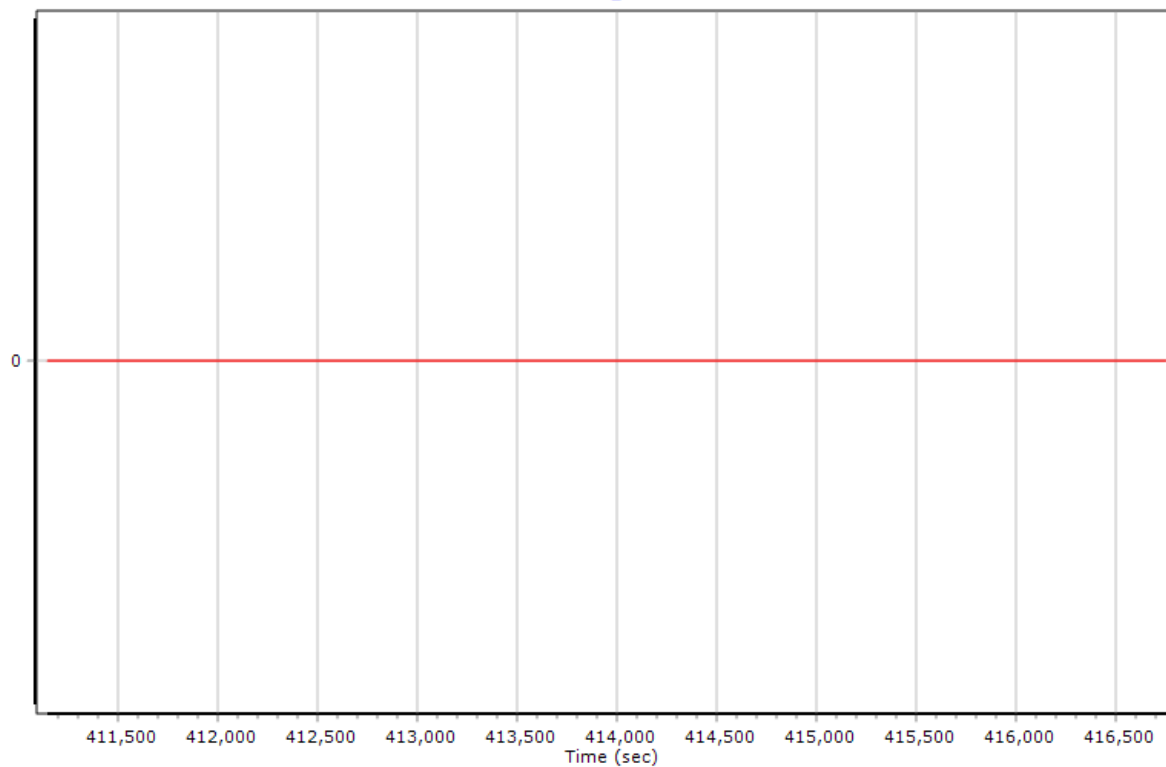
Measurements are to the stabilized platform's center of rotation with the Gimbal in the rest position.



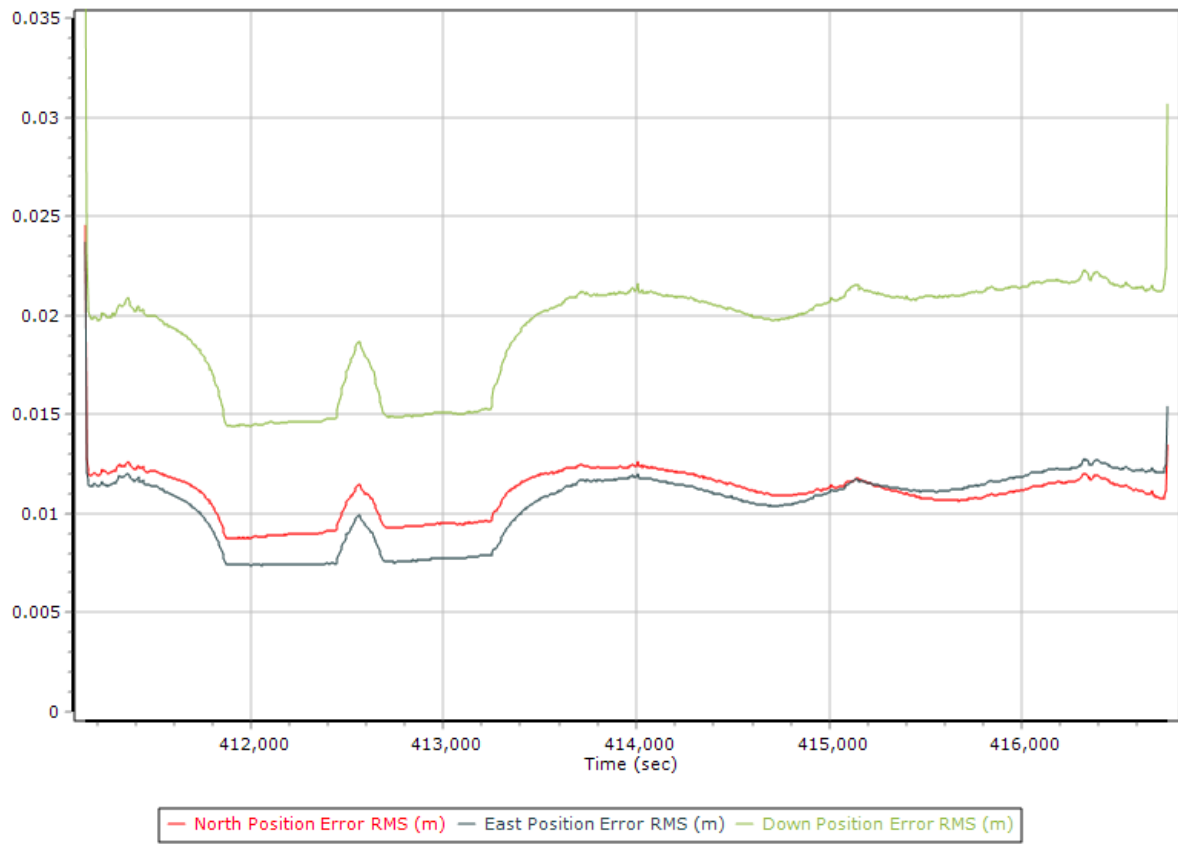
PDOP

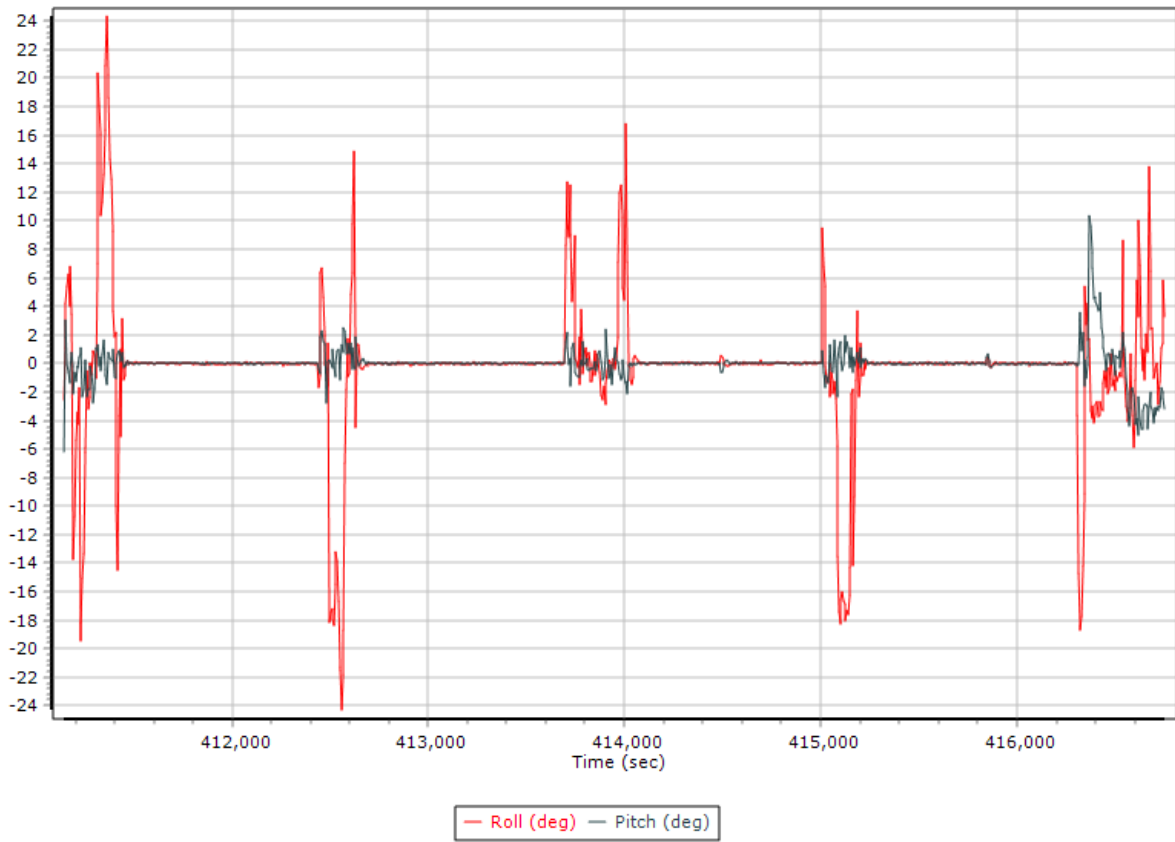


Processing Mode



0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = C/A, 7 = GNSS Nav, 8 = DR





Disable Satellites

GPS GLONASS BEIDOU QZSS

- | | | |
|---------------------------------|----------------------------------|----------------------------------|
| <input type="checkbox"/> SLOT 1 | <input type="checkbox"/> SLOT 10 | <input type="checkbox"/> SLOT 19 |
| <input type="checkbox"/> SLOT 2 | <input type="checkbox"/> SLOT 11 | <input type="checkbox"/> SLOT 20 |
| <input type="checkbox"/> SLOT 3 | <input type="checkbox"/> SLOT 12 | <input type="checkbox"/> SLOT 21 |
| <input type="checkbox"/> SLOT 4 | <input type="checkbox"/> SLOT 13 | <input type="checkbox"/> SLOT 22 |
| <input type="checkbox"/> SLOT 5 | <input type="checkbox"/> SLOT 14 | <input type="checkbox"/> SLOT 23 |
| <input type="checkbox"/> SLOT 6 | <input type="checkbox"/> SLOT 15 | <input type="checkbox"/> SLOT 24 |
| <input type="checkbox"/> SLOT 7 | <input type="checkbox"/> SLOT 16 | |
| <input type="checkbox"/> SLOT 8 | <input type="checkbox"/> SLOT 17 | |
| <input type="checkbox"/> SLOT 9 | <input type="checkbox"/> SLOT 18 | |

Elevation Mask Angle

Force GPS Only

Disable Satellites

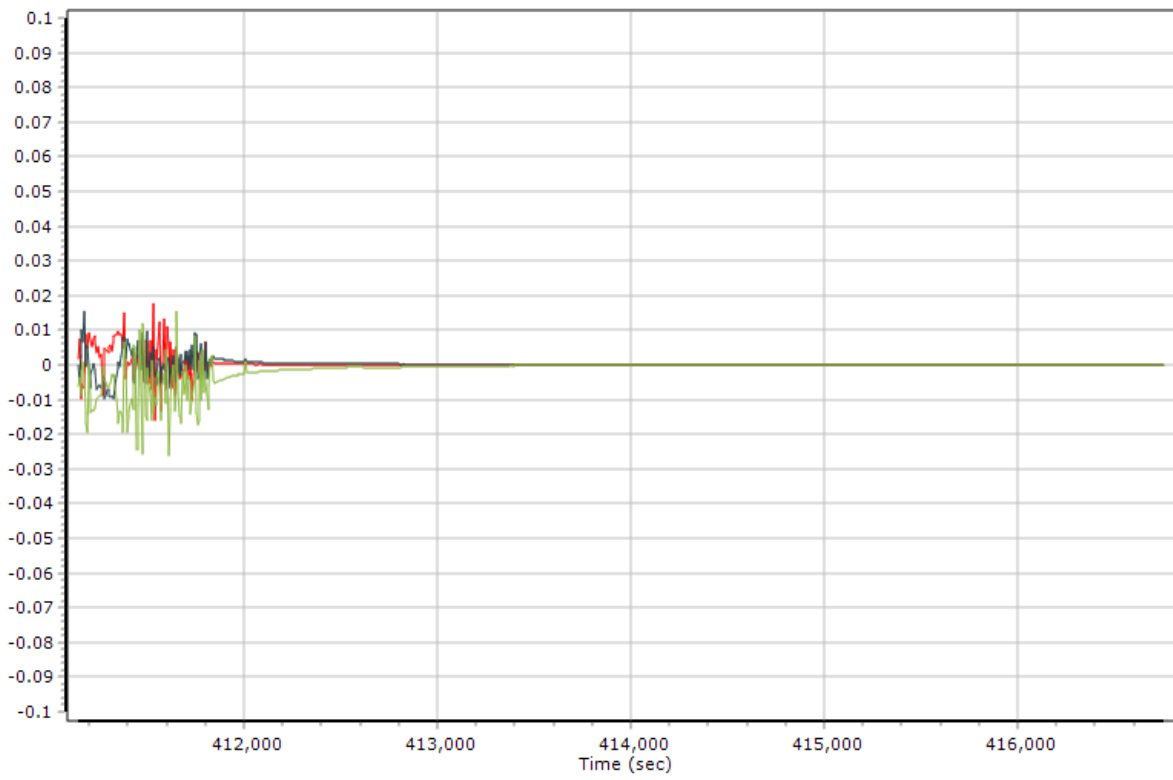
GPS | GLONASS | BEIDOU | QZSS

- | | | | |
|--------------------------------|--|--|--|
| <input type="checkbox"/> PRN 1 | <input type="checkbox"/> PRN 10 | <input type="checkbox"/> PRN 19 | <input type="checkbox"/> PRN 28 |
| <input type="checkbox"/> PRN 2 | <input type="checkbox"/> PRN 11 | <input type="checkbox"/> PRN 20 | <input type="checkbox"/> PRN 29 |
| <input type="checkbox"/> PRN 3 | <input checked="" type="checkbox"/> PRN 12 | <input type="checkbox"/> PRN 21 | <input type="checkbox"/> PRN 30 |
| <input type="checkbox"/> PRN 4 | <input type="checkbox"/> PRN 13 | <input type="checkbox"/> PRN 22 | <input checked="" type="checkbox"/> PRN 31 |
| <input type="checkbox"/> PRN 5 | <input type="checkbox"/> PRN 14 | <input type="checkbox"/> PRN 23 | <input type="checkbox"/> PRN 32 |
| <input type="checkbox"/> PRN 6 | <input type="checkbox"/> PRN 15 | <input type="checkbox"/> PRN 24 | |
| <input type="checkbox"/> PRN 7 | <input type="checkbox"/> PRN 16 | <input type="checkbox"/> PRN 25 | |
| <input type="checkbox"/> PRN 8 | <input type="checkbox"/> PRN 17 | <input checked="" type="checkbox"/> PRN 26 | |
| <input type="checkbox"/> PRN 9 | <input type="checkbox"/> PRN 18 | <input checked="" type="checkbox"/> PRN 27 | |



Elevation Mask Angle

Force GPS Only



— North (m) — East (m) — Down (m) — DR mode

Timing

Start 411142.005

End 416757.077

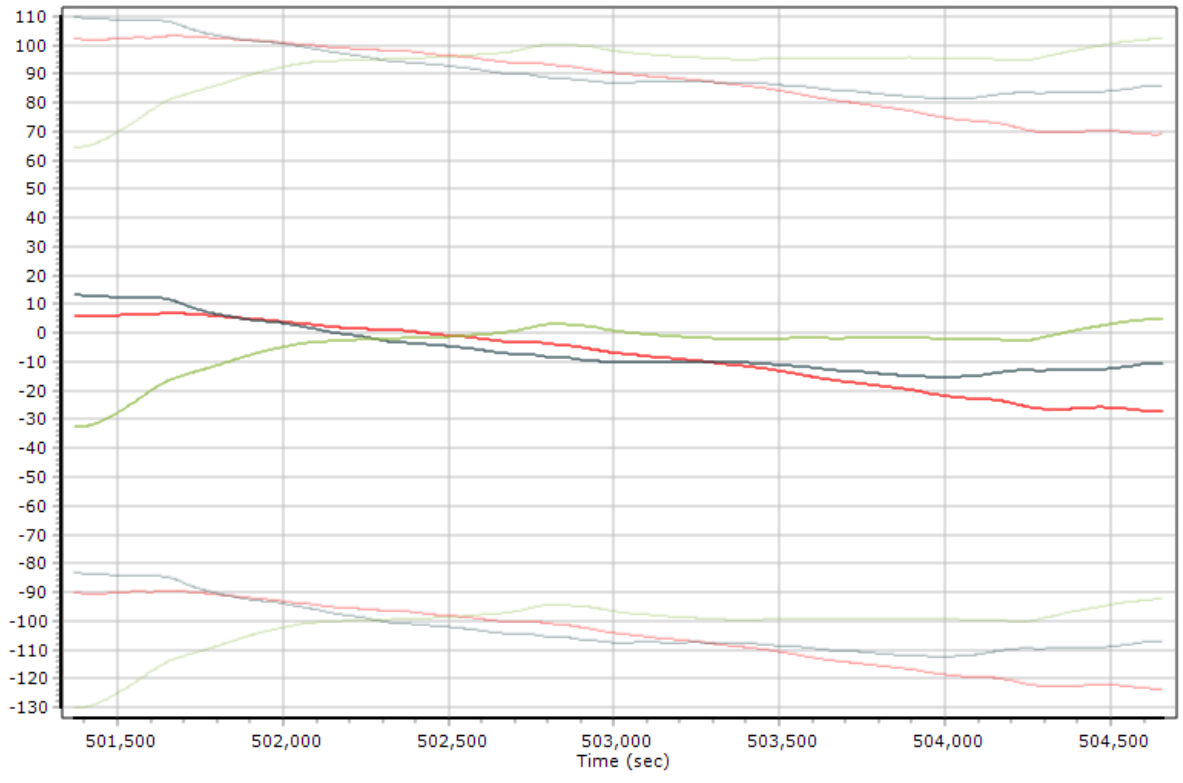
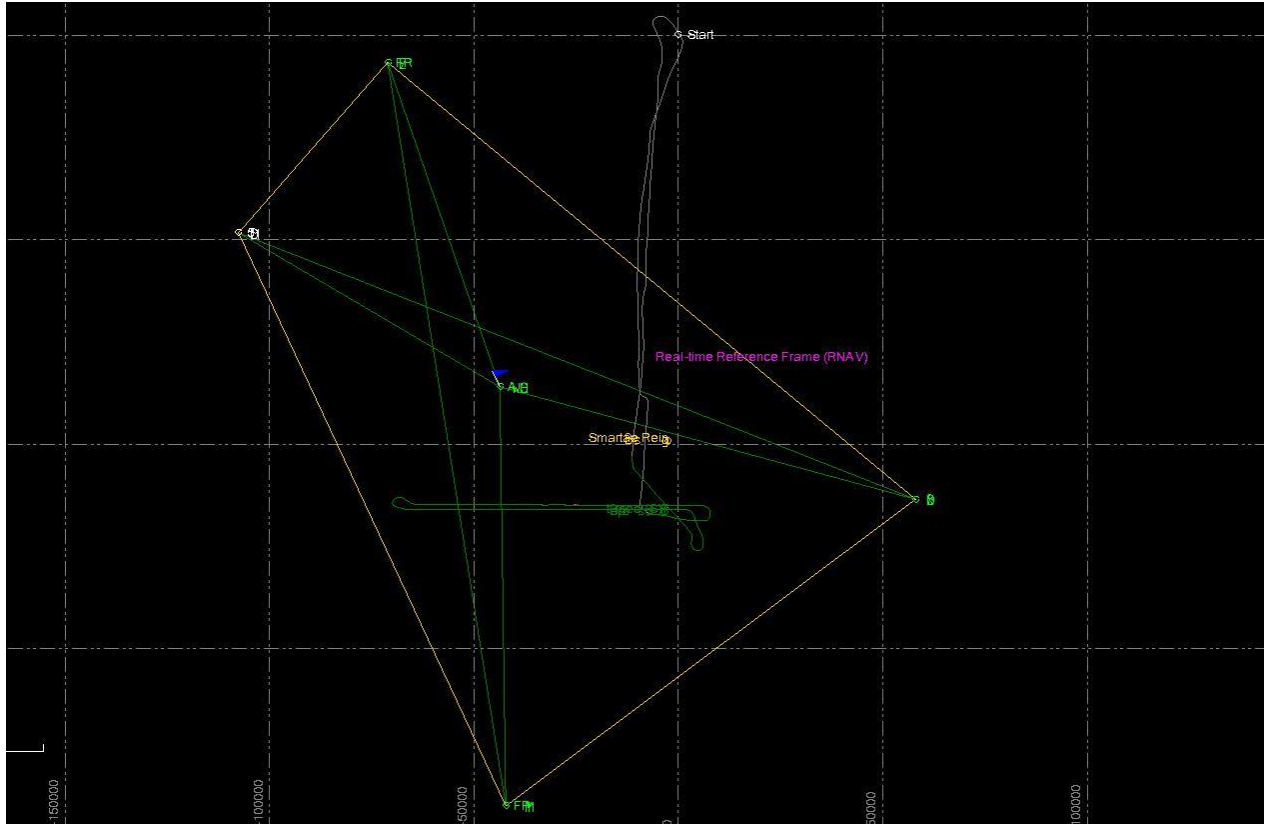
Entire time interval

Seconds of start week

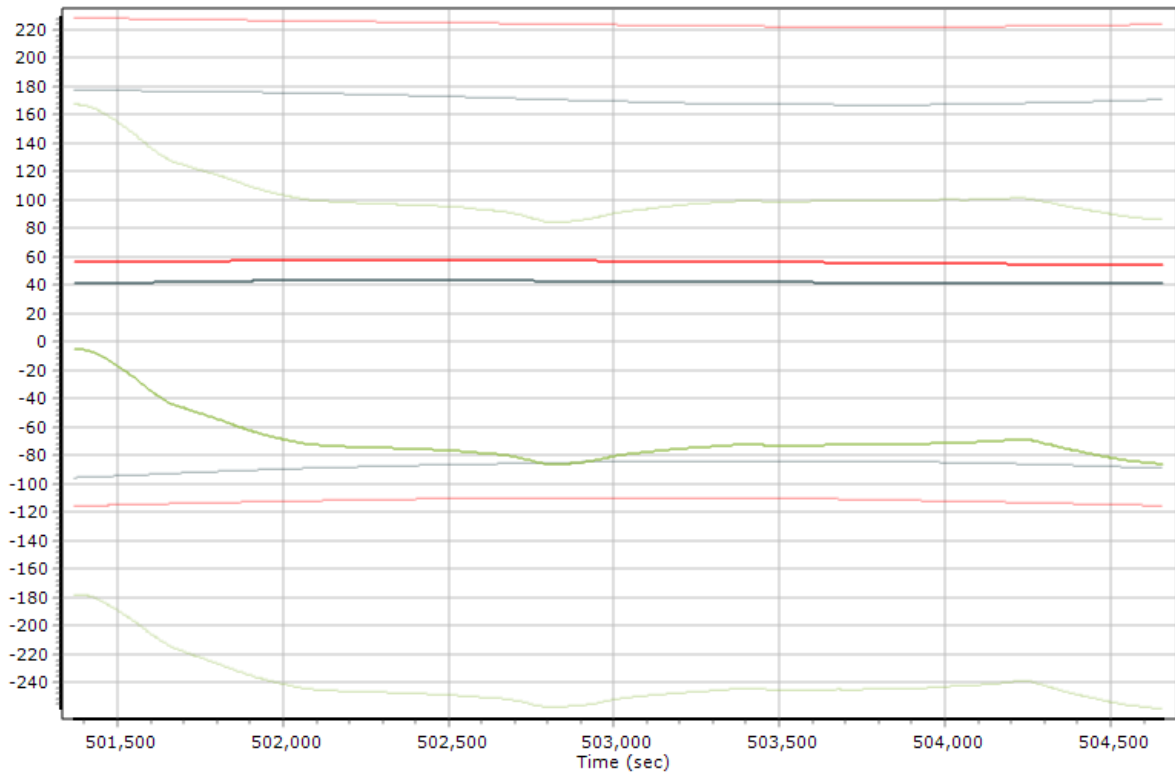
UTC Offset 18.000

Data	Incr. (sec)
Output Record	0.005000
IMU	0.005000
Primary GNSS	1.000000

MISSION: 45A18341A

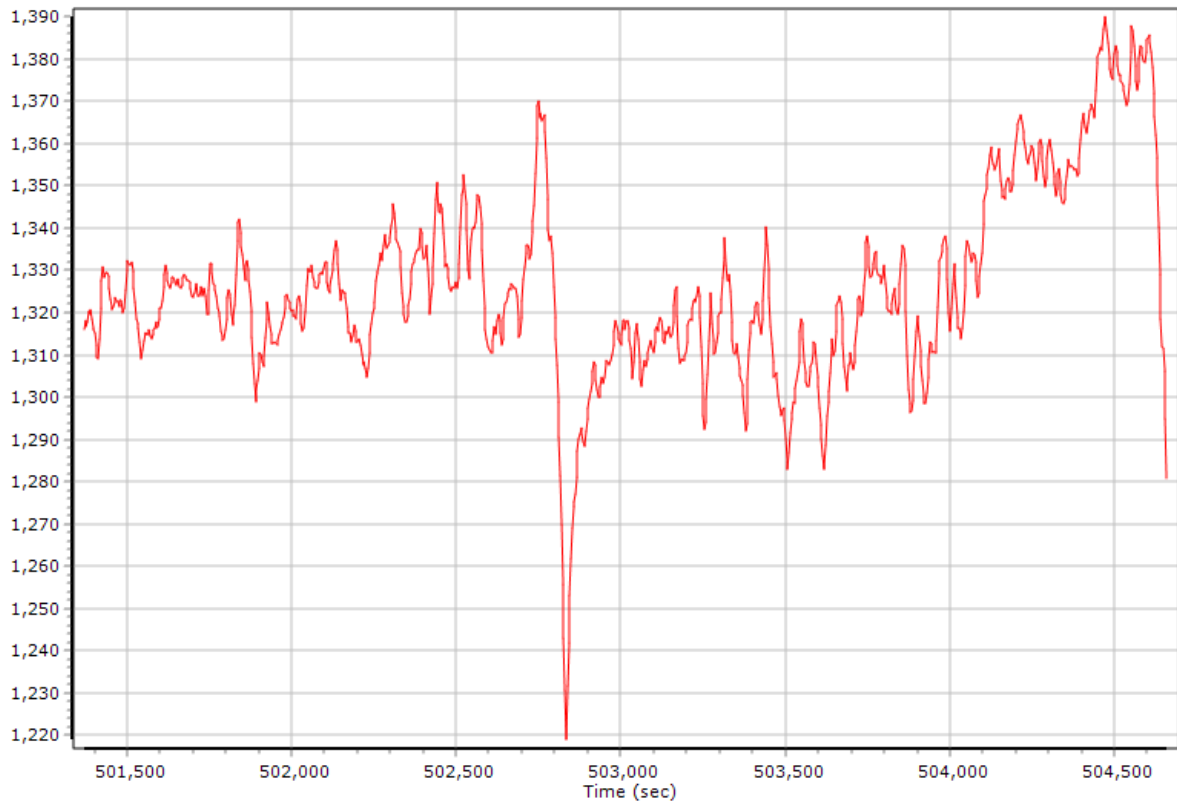


— x accelerometer bias (micro-g) — y accelerometer bias (micro-g) — z accelerometer bias (micro-g)

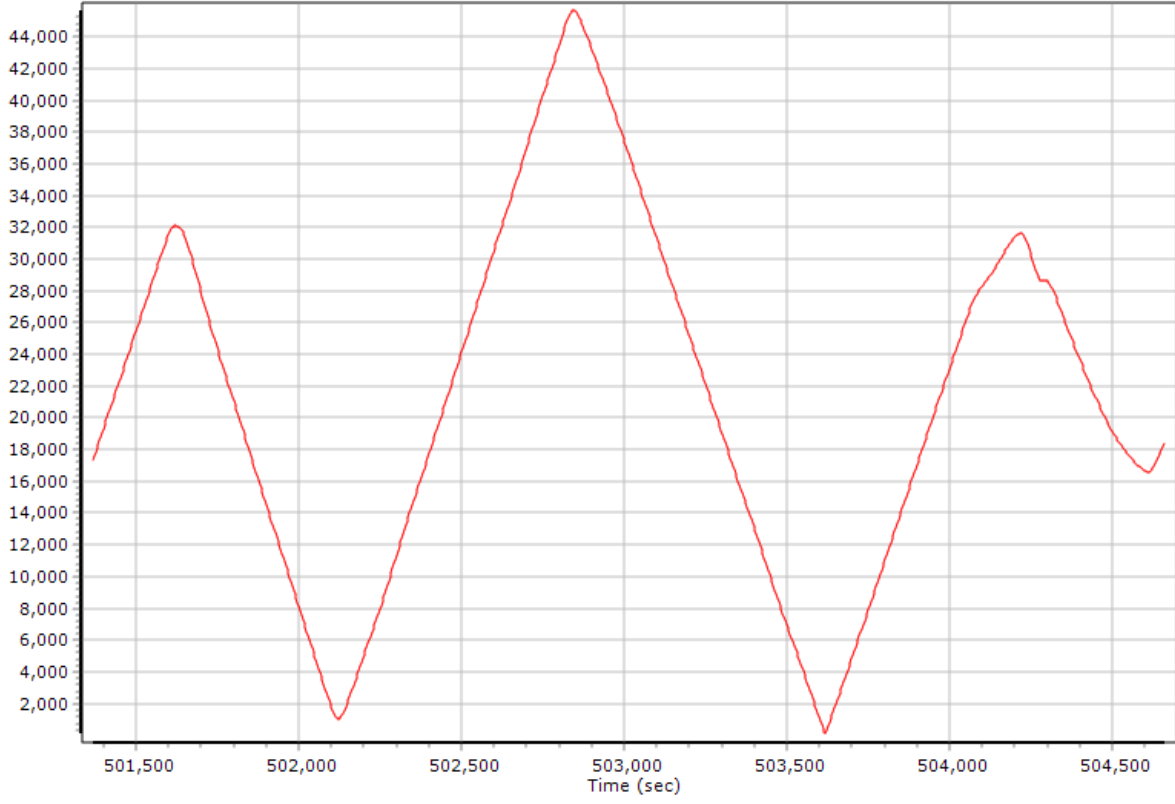


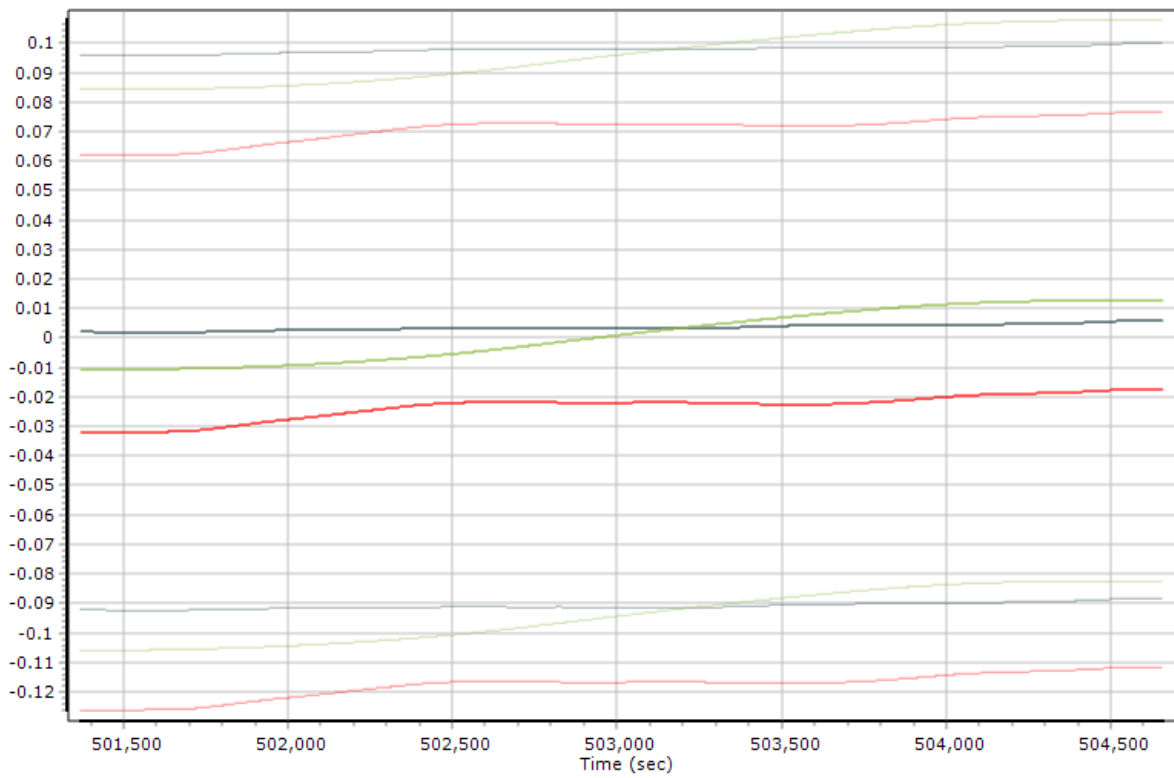
— x accelerometer scale error (ppm) — y accelerometer scale error (ppm) — z accelerometer scale error (ppm)

Altitude (m)

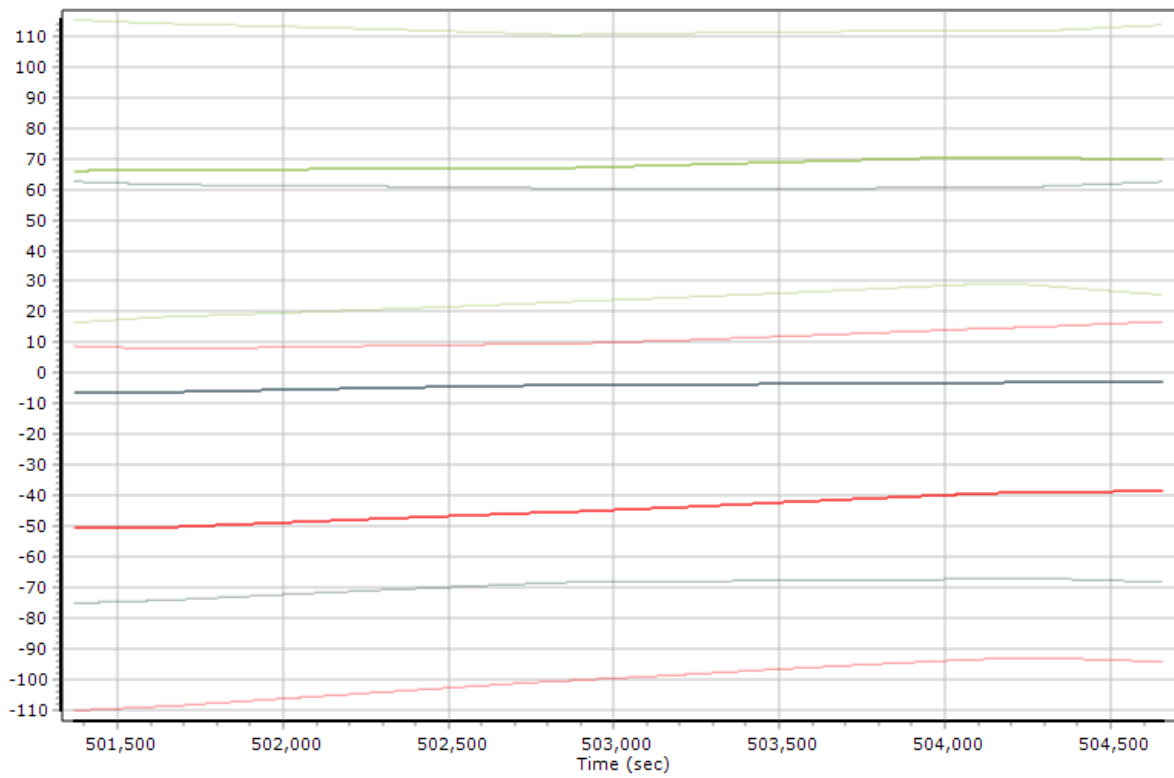


Baseline Length(m)





— x gyro bias (deg/hr) — y gyro bias (deg/hr) — z gyro bias (deg/hr)



— x gyro scale error (ppm) — y gyro scale error (ppm) — z gyro scale error (ppm)

Stabilized Mount to IMU Lever Arm

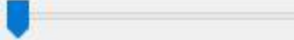
X
Y
Z

Stabilized Mount to IMU Mounting Angles

X
Y
Z

Stabilized Mount to Primary GNSS Lever Arm

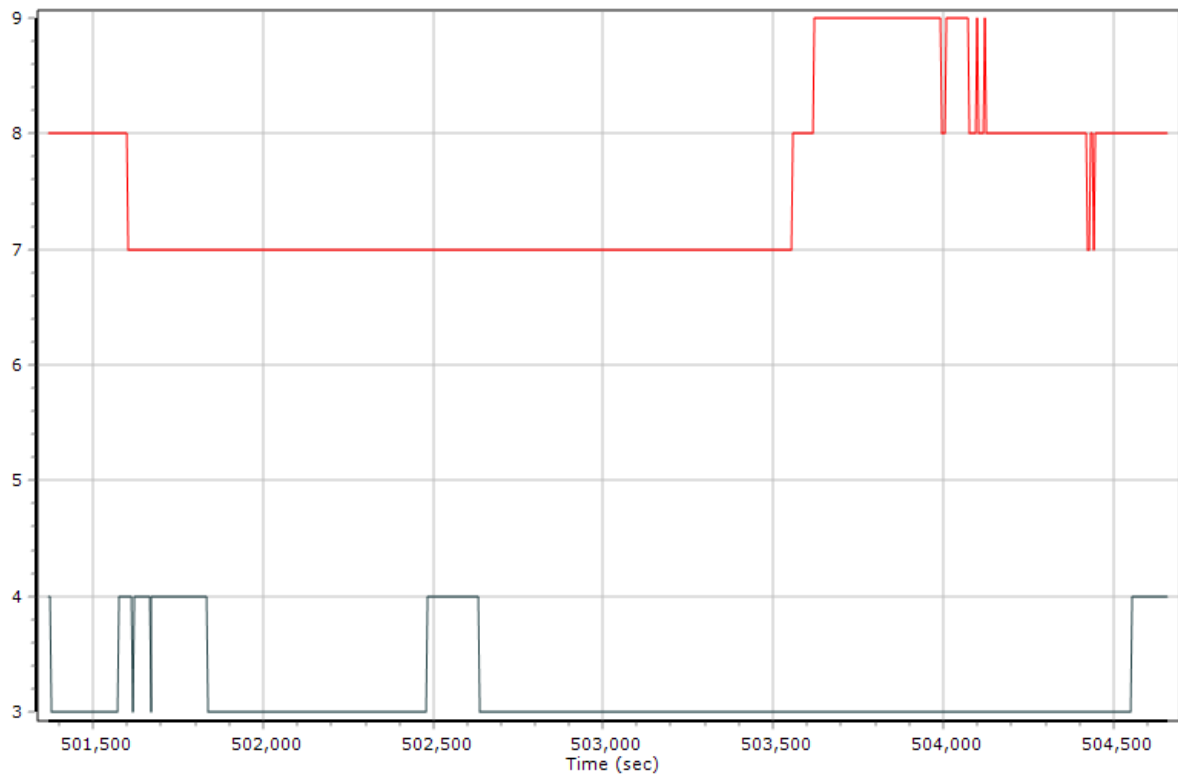
X
Y
Z

Standard Deviation 
<3cm 10cm 50cm 1m 10m

Aircraft to Stabilized Mount Mounting Angles

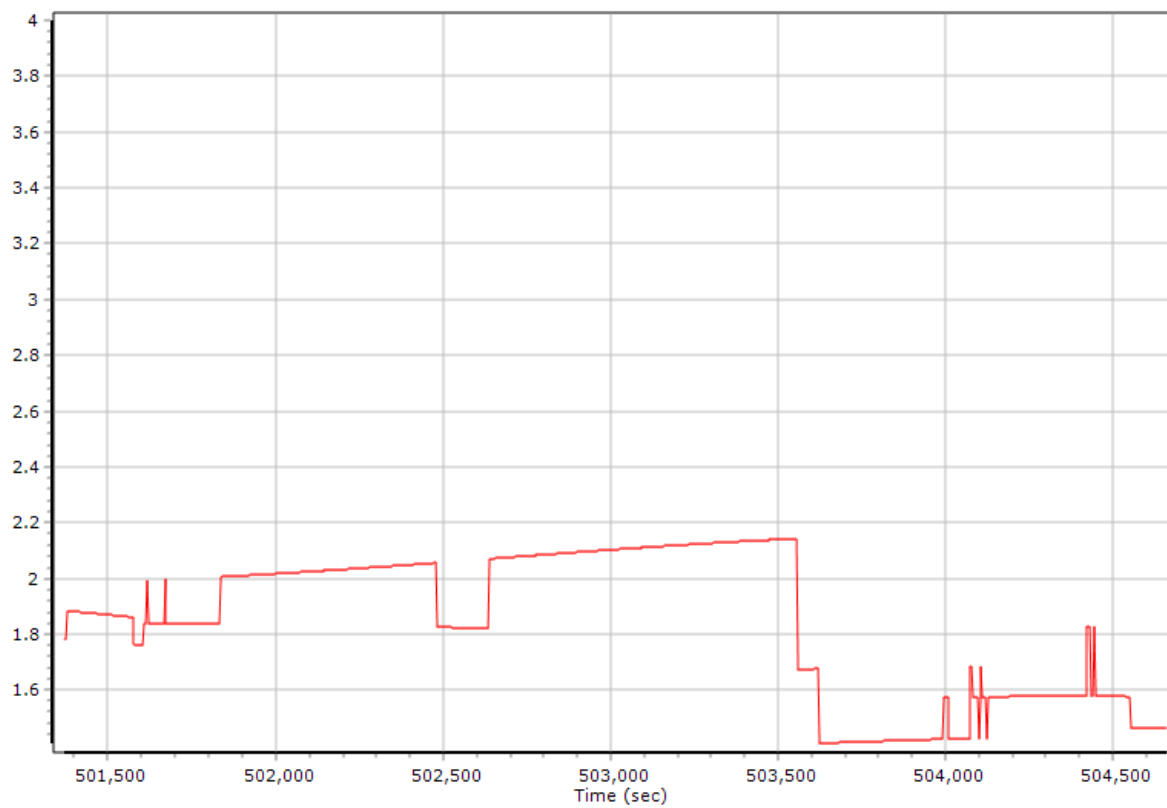
X
Y
Z

Measurements are to the stabilized platform's center of rotation with the Gimbal in the rest position.



— Number of GPS Satellites — Number of GLONASS Satellites

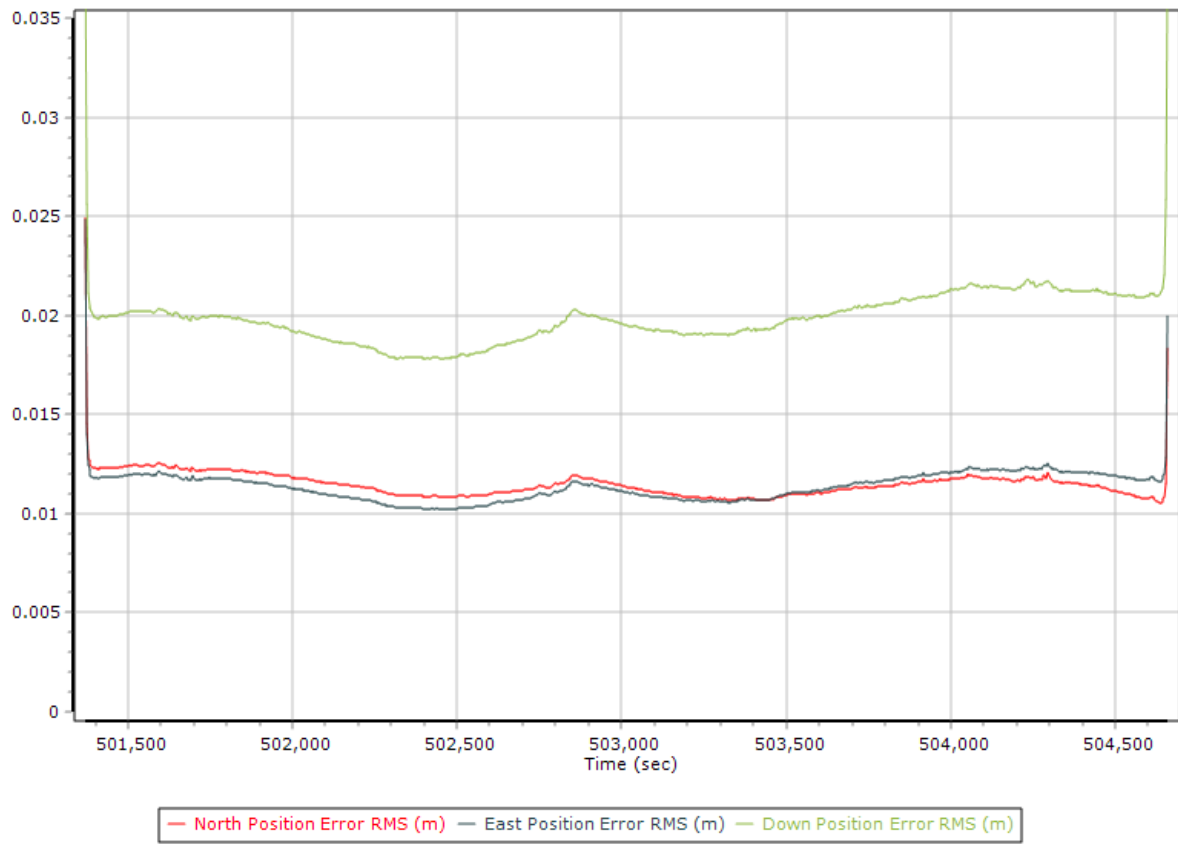
PDOP

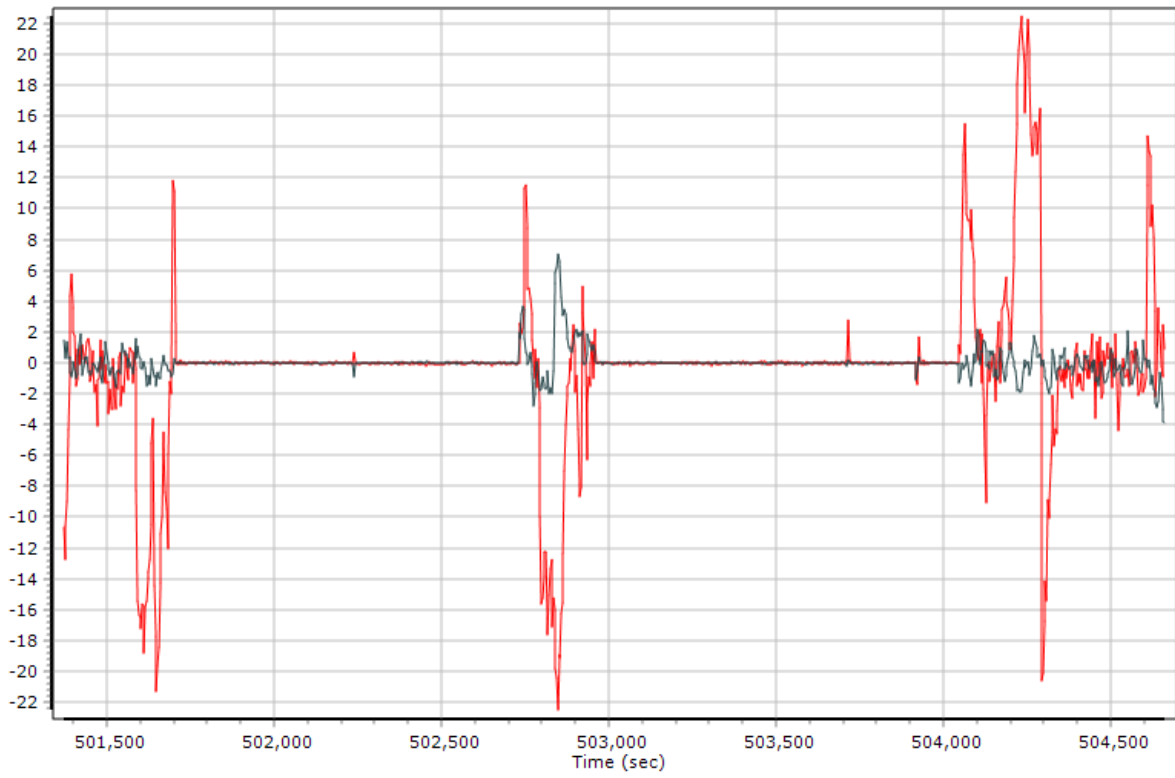


Processing Mode



0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = C/A, 7 = GNSS Nav, 8 = DR





— Roll (deg) — Pitch (deg)

Disable Satellites

GPS GLONASS BEIDOU QZSS

- | | | |
|---------------------------------|----------------------------------|----------------------------------|
| <input type="checkbox"/> SLOT 1 | <input type="checkbox"/> SLOT 10 | <input type="checkbox"/> SLOT 19 |
| <input type="checkbox"/> SLOT 2 | <input type="checkbox"/> SLOT 11 | <input type="checkbox"/> SLOT 20 |
| <input type="checkbox"/> SLOT 3 | <input type="checkbox"/> SLOT 12 | <input type="checkbox"/> SLOT 21 |
| <input type="checkbox"/> SLOT 4 | <input type="checkbox"/> SLOT 13 | <input type="checkbox"/> SLOT 22 |
| <input type="checkbox"/> SLOT 5 | <input type="checkbox"/> SLOT 14 | <input type="checkbox"/> SLOT 23 |
| <input type="checkbox"/> SLOT 6 | <input type="checkbox"/> SLOT 15 | <input type="checkbox"/> SLOT 24 |
| <input type="checkbox"/> SLOT 7 | <input type="checkbox"/> SLOT 16 | |
| <input type="checkbox"/> SLOT 8 | <input type="checkbox"/> SLOT 17 | |
| <input type="checkbox"/> SLOT 9 | <input type="checkbox"/> SLOT 18 | |

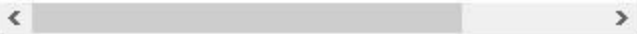
Elevation Mask Angle

Force GPS Only

Disable Satellites

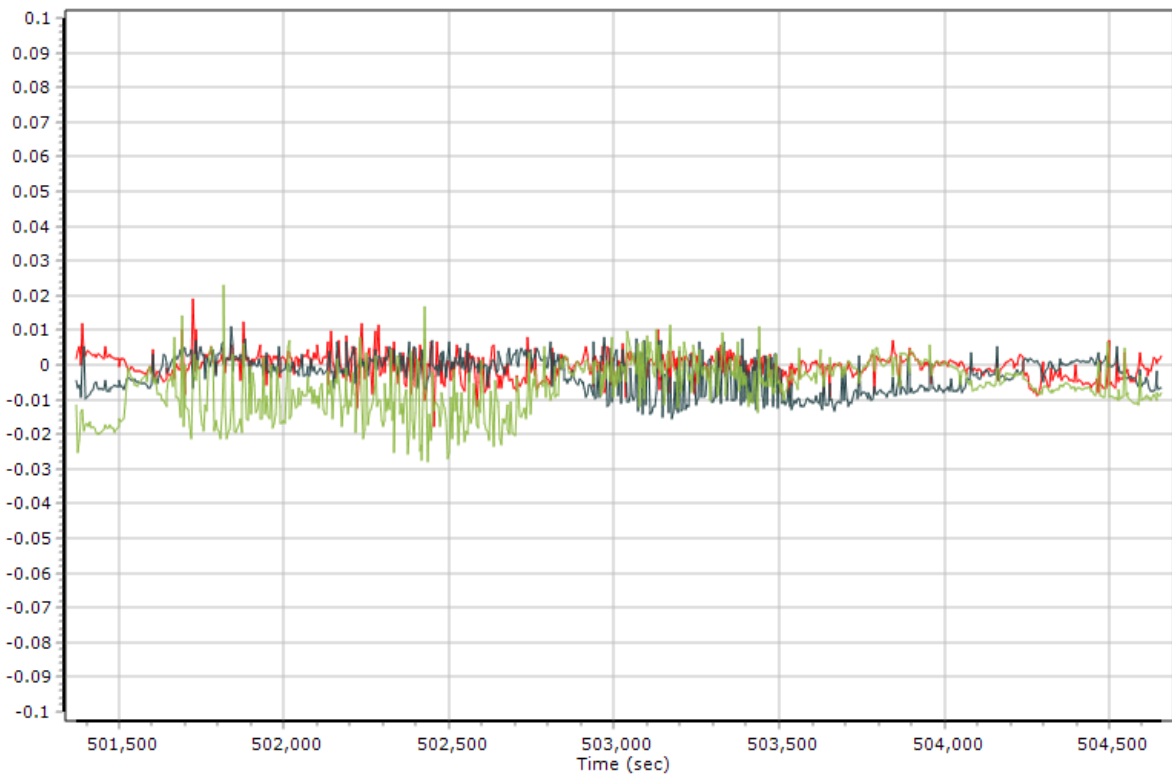
GPS GLONASS BEIDOU QZSS

- | | | | |
|--------------------------------|---------------------------------|---------------------------------|---------------------------------|
| <input type="checkbox"/> PRN 1 | <input type="checkbox"/> PRN 10 | <input type="checkbox"/> PRN 19 | <input type="checkbox"/> PRN 28 |
| <input type="checkbox"/> PRN 2 | <input type="checkbox"/> PRN 11 | <input type="checkbox"/> PRN 20 | <input type="checkbox"/> PRN 29 |
| <input type="checkbox"/> PRN 3 | <input type="checkbox"/> PRN 12 | <input type="checkbox"/> PRN 21 | <input type="checkbox"/> PRN 30 |
| <input type="checkbox"/> PRN 4 | <input type="checkbox"/> PRN 13 | <input type="checkbox"/> PRN 22 | <input type="checkbox"/> PRN 31 |
| <input type="checkbox"/> PRN 5 | <input type="checkbox"/> PRN 14 | <input type="checkbox"/> PRN 23 | <input type="checkbox"/> PRN 32 |
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| <input type="checkbox"/> PRN 7 | <input type="checkbox"/> PRN 16 | <input type="checkbox"/> PRN 25 | |
| <input type="checkbox"/> PRN 8 | <input type="checkbox"/> PRN 17 | <input type="checkbox"/> PRN 26 | |
| <input type="checkbox"/> PRN 9 | <input type="checkbox"/> PRN 18 | <input type="checkbox"/> PRN 27 | |



Elevation Mask Angle

Force GPS Only



— North (m) — East (m) — Down (m) — DR mode

Timing

Start

End

Entire time interval

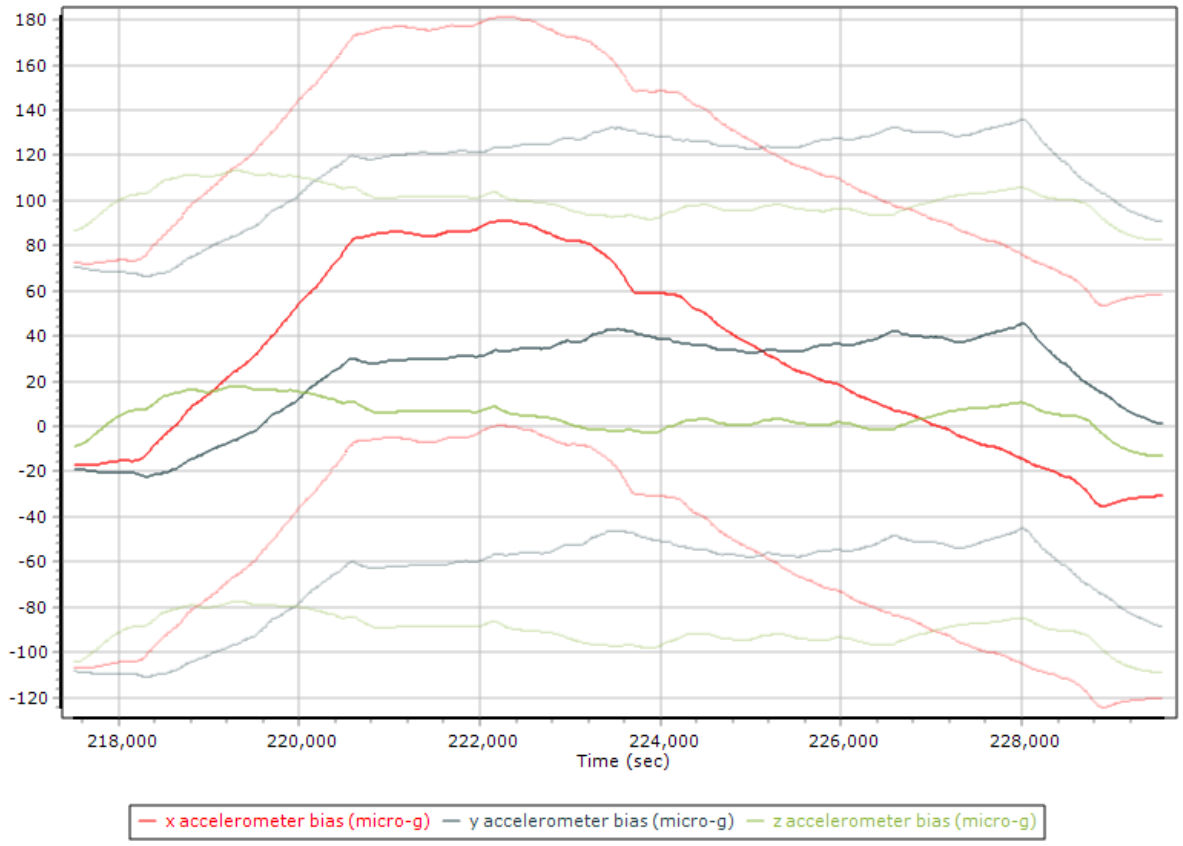
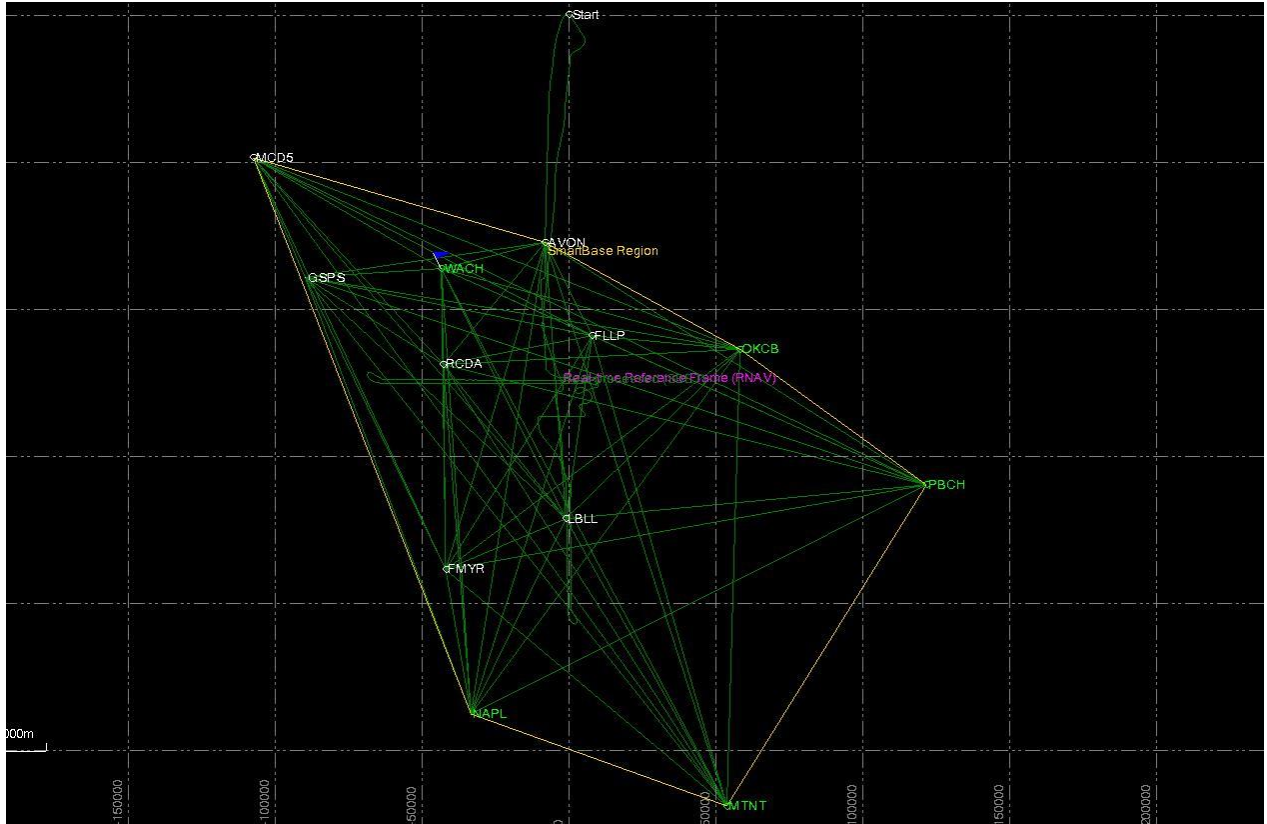
Seconds of start week

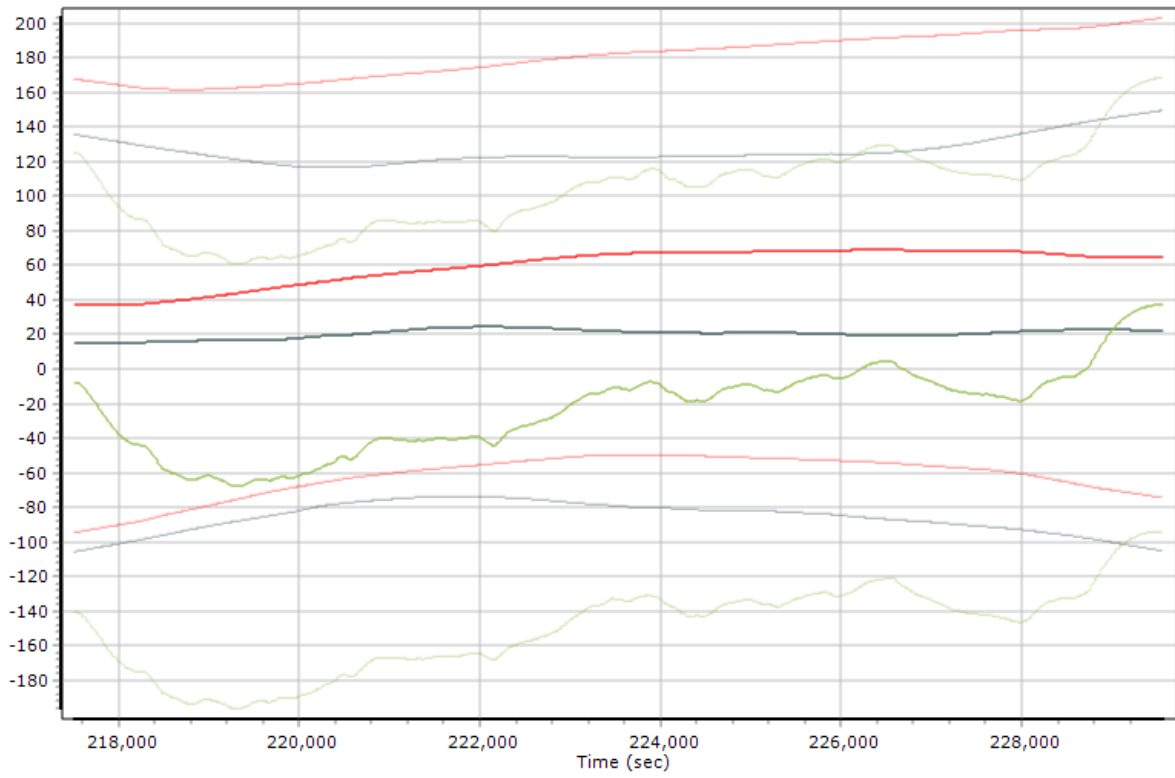
UTC Offset

Data	Incr. (sec)
Output Record	0.005000
IMU	0.005000
Primary GNSS	1.000000



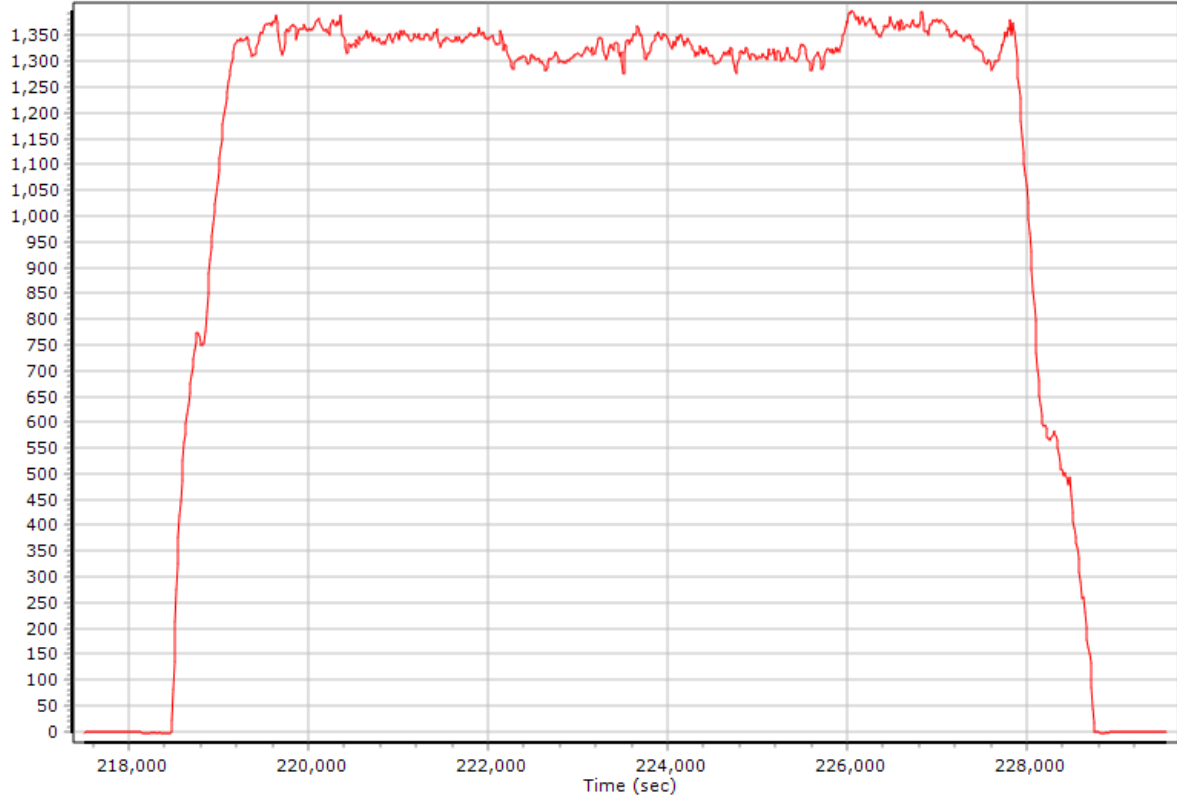
MISSION: 45A18345A



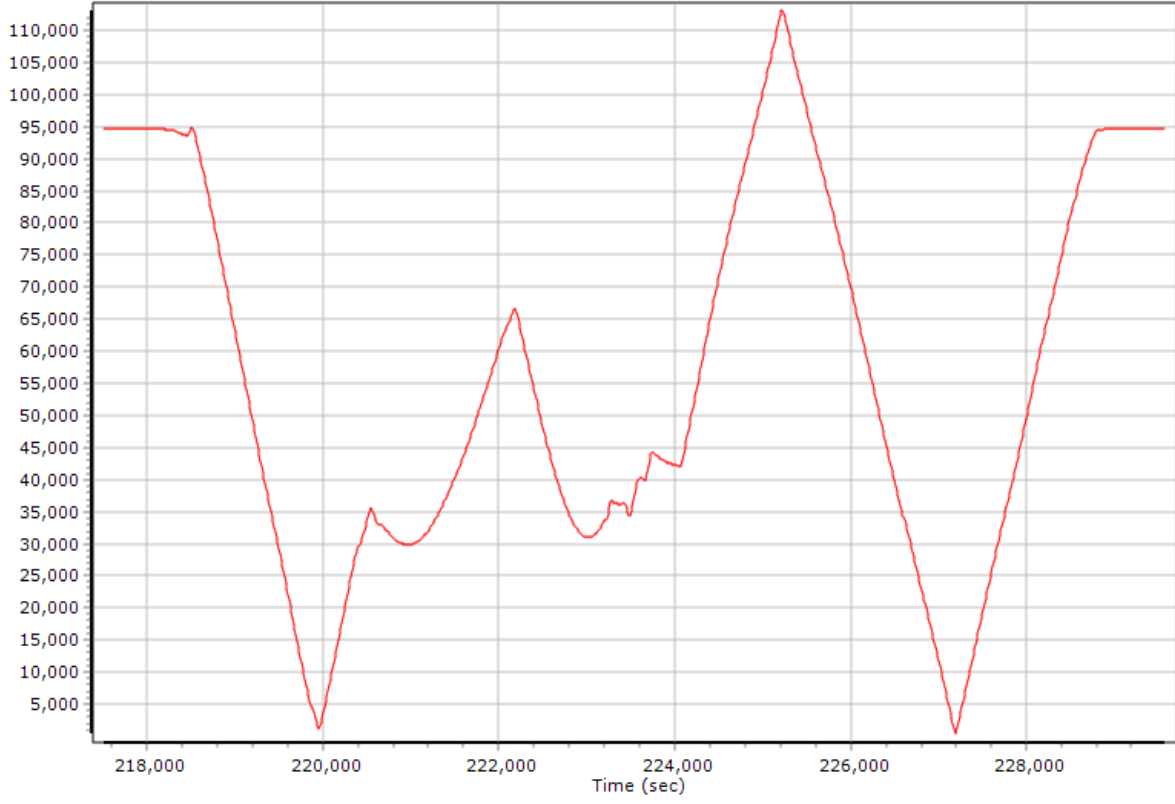


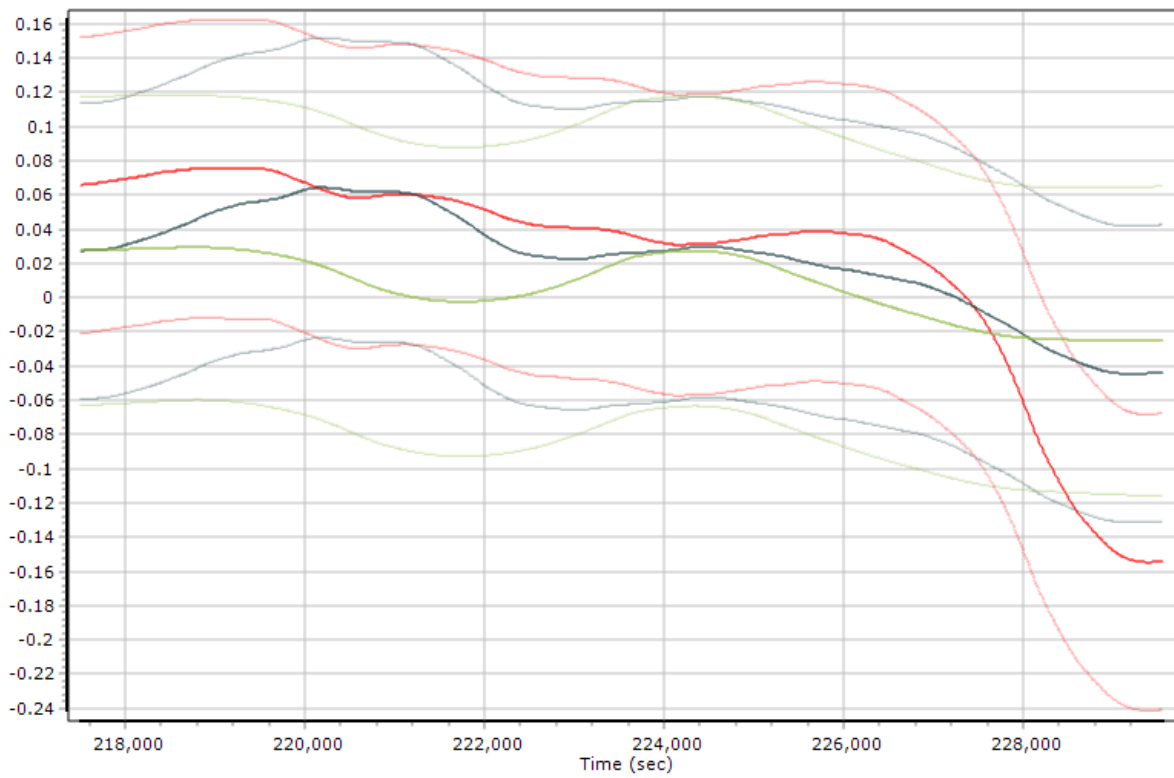
— x accelerometer scale error (ppm) — y accelerometer scale error (ppm) — z accelerometer scale error (ppm)

Altitude (m)

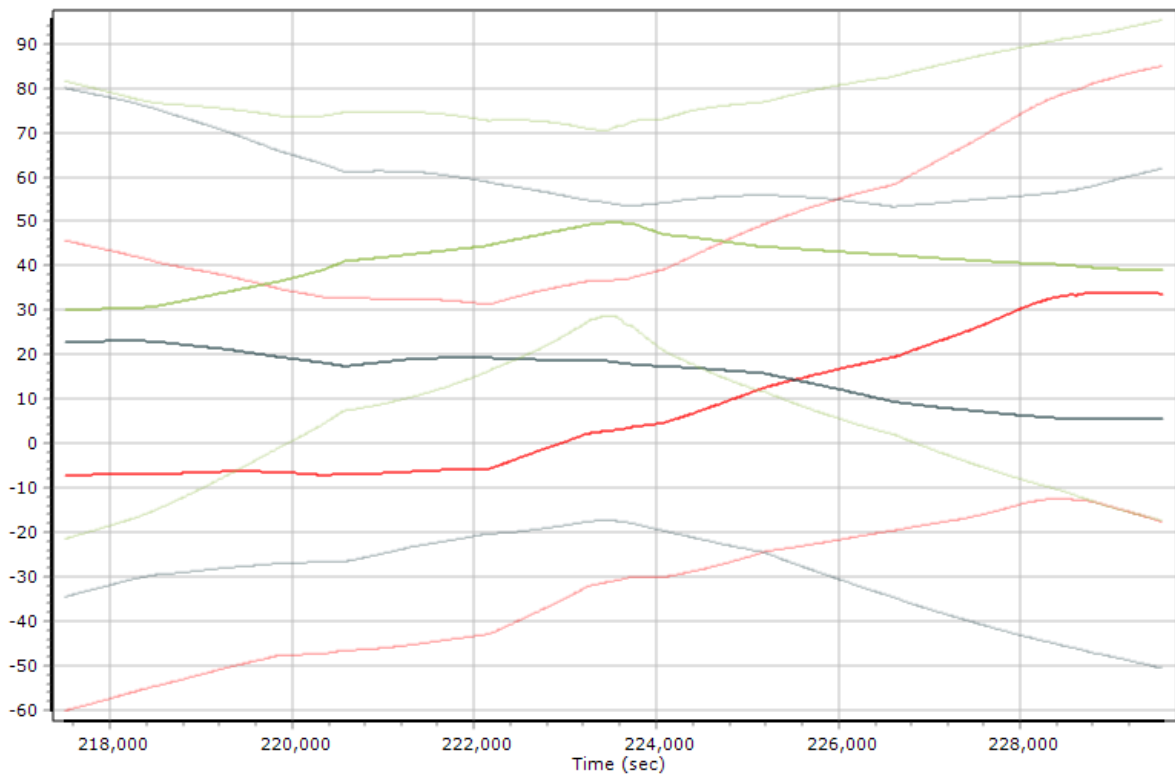


Baseline Length(m)





— x gyro bias (deg/hr) — y gyro bias (deg/hr) — z gyro bias (deg/hr)



— x gyro scale error (ppm) — y gyro scale error (ppm) — z gyro scale error (ppm)

Stabilized Mount to IMU Lever Arm

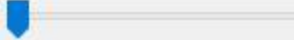
X
Y
Z

Stabilized Mount to IMU Mounting Angles

X
Y
Z

Stabilized Mount to Primary GNSS Lever Arm

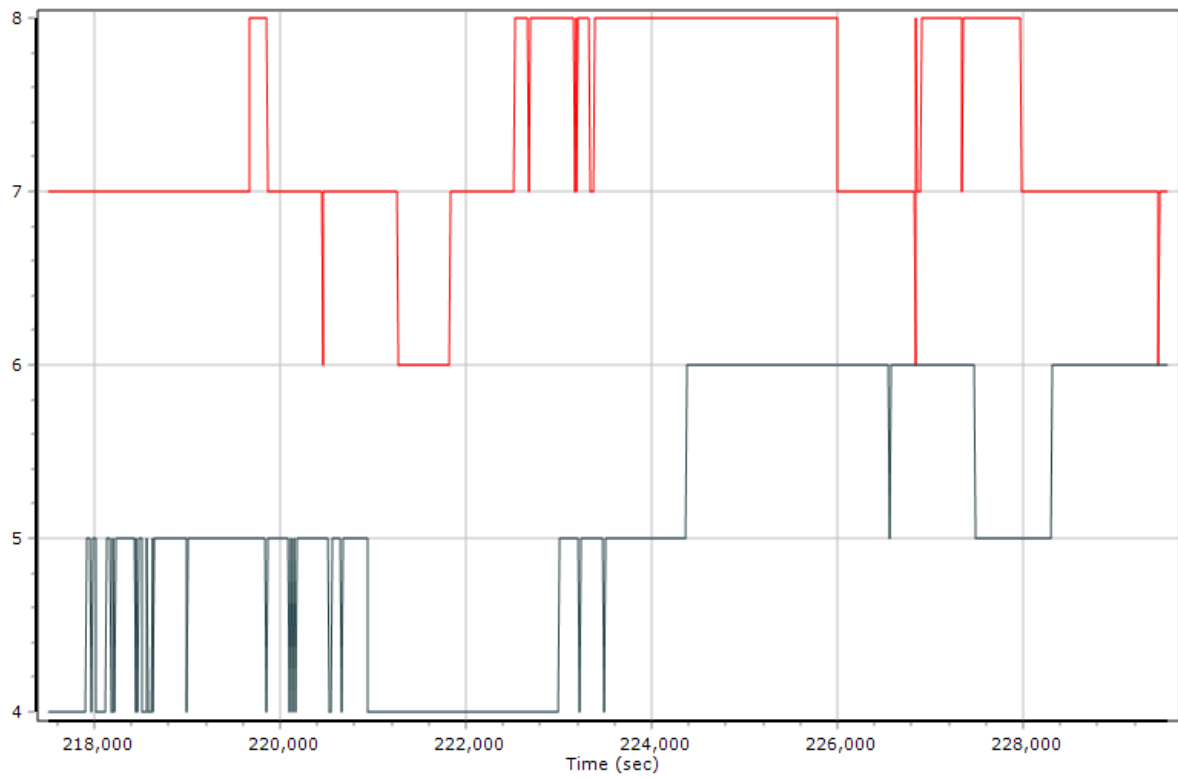
X
Y
Z

Standard Deviation 
<3cm 10cm 50cm 1m 10m

Aircraft to Stabilized Mount Mounting Angles

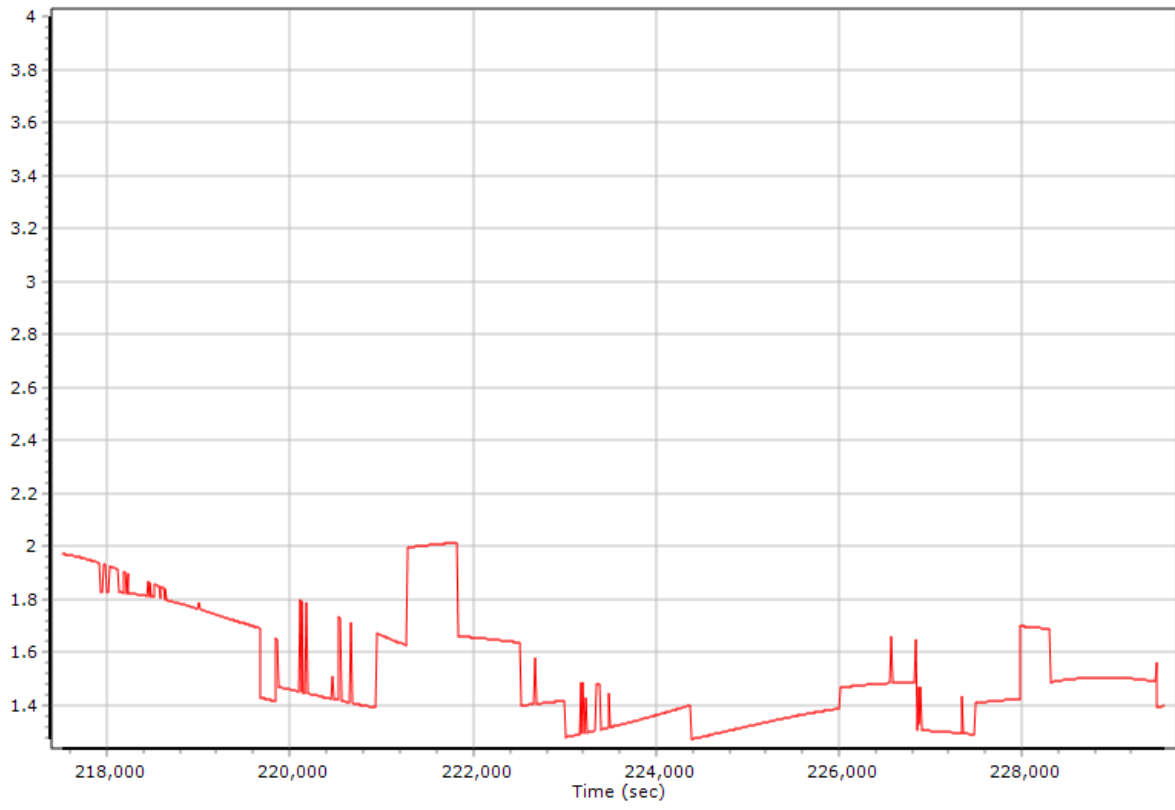
X
Y
Z

Measurements are to the stabilized platform's center of rotation with the Gimbal in the rest position.

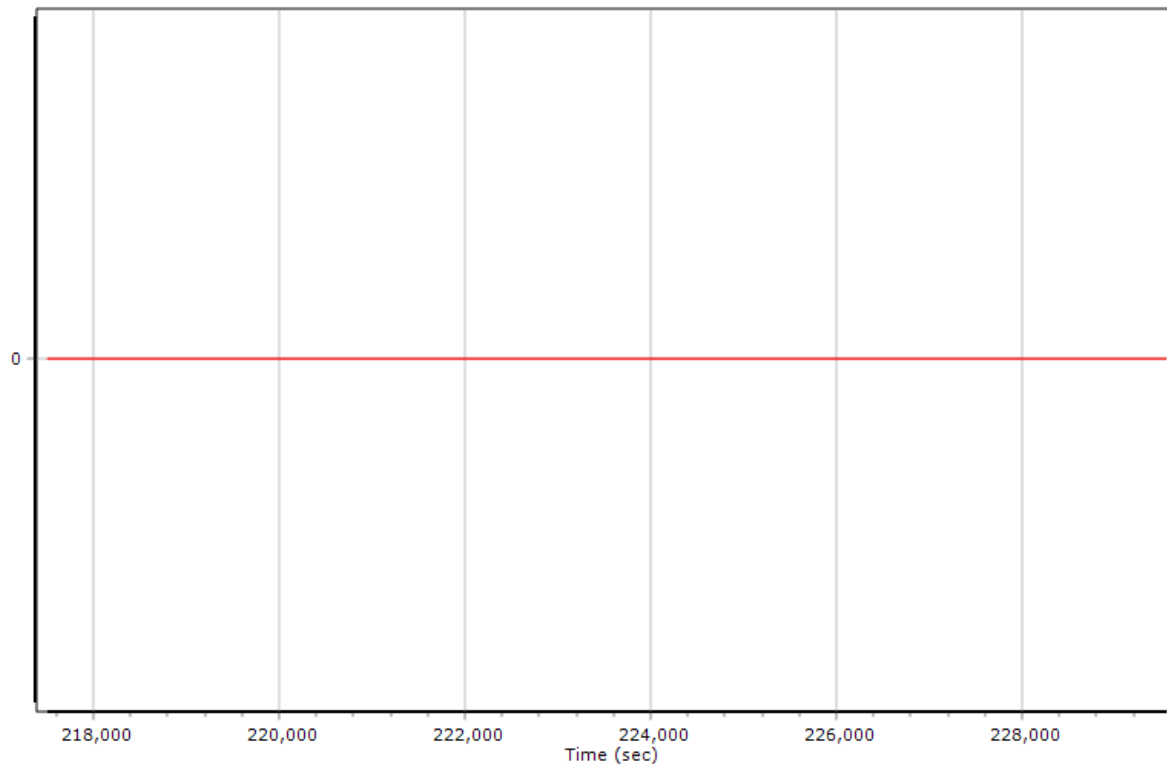


— Number of GPS Satellites — Number of GLONASS Satellites

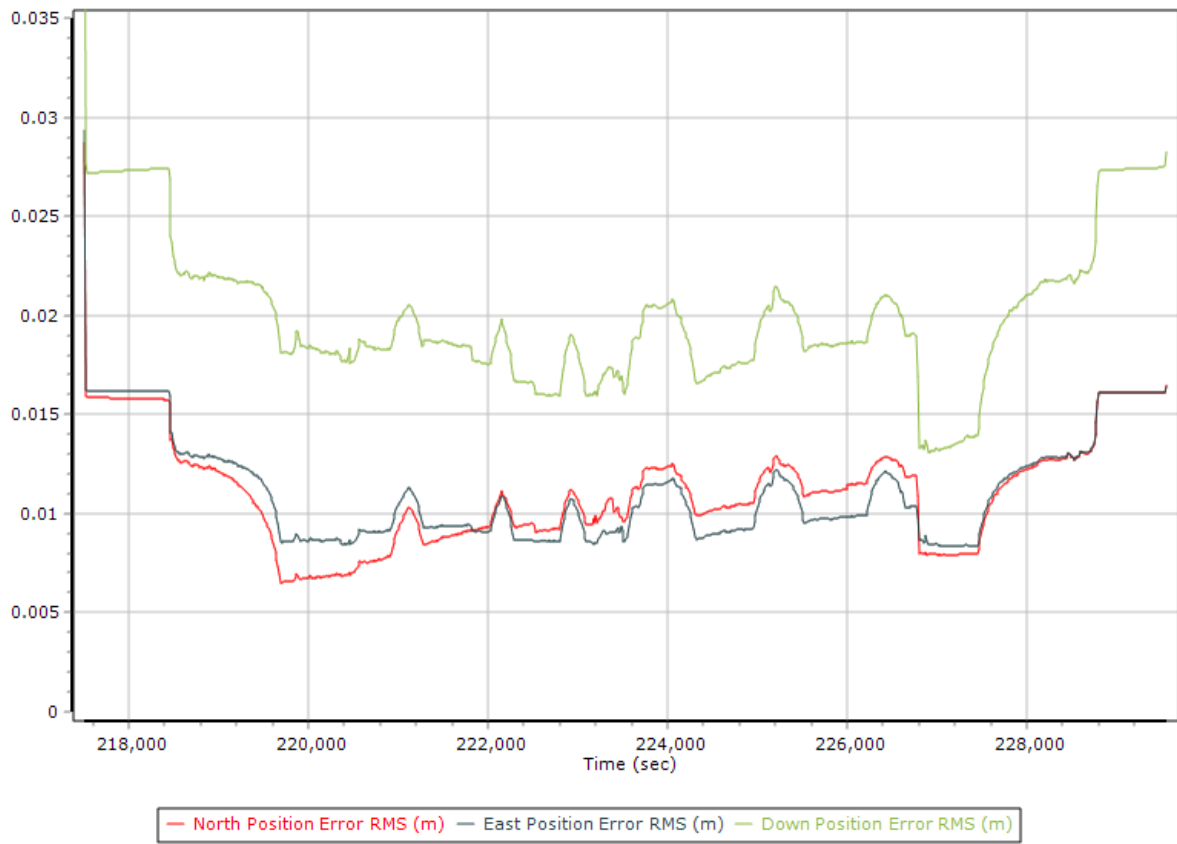
PDOP

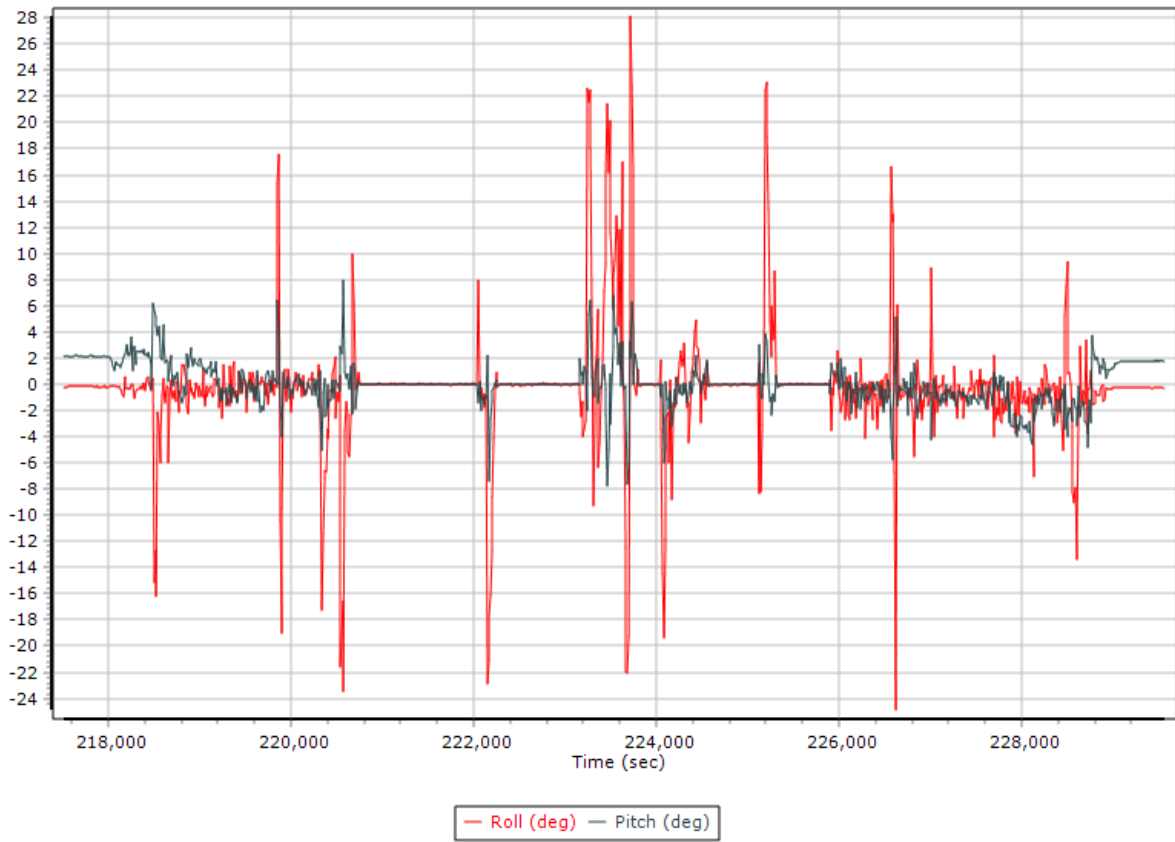


Processing Mode



0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = C/A, 7 = GNSS Nav, 8 = DR





Disable Satellites

GPS GLONASS BEIDOU QZSS

- | | | |
|---------------------------------|----------------------------------|----------------------------------|
| <input type="checkbox"/> SLOT 1 | <input type="checkbox"/> SLOT 10 | <input type="checkbox"/> SLOT 19 |
| <input type="checkbox"/> SLOT 2 | <input type="checkbox"/> SLOT 11 | <input type="checkbox"/> SLOT 20 |
| <input type="checkbox"/> SLOT 3 | <input type="checkbox"/> SLOT 12 | <input type="checkbox"/> SLOT 21 |
| <input type="checkbox"/> SLOT 4 | <input type="checkbox"/> SLOT 13 | <input type="checkbox"/> SLOT 22 |
| <input type="checkbox"/> SLOT 5 | <input type="checkbox"/> SLOT 14 | <input type="checkbox"/> SLOT 23 |
| <input type="checkbox"/> SLOT 6 | <input type="checkbox"/> SLOT 15 | <input type="checkbox"/> SLOT 24 |
| <input type="checkbox"/> SLOT 7 | <input type="checkbox"/> SLOT 16 | |
| <input type="checkbox"/> SLOT 8 | <input type="checkbox"/> SLOT 17 | |
| <input type="checkbox"/> SLOT 9 | <input type="checkbox"/> SLOT 18 | |

Elevation Mask Angle

Force GPS Only

Disable Satellites

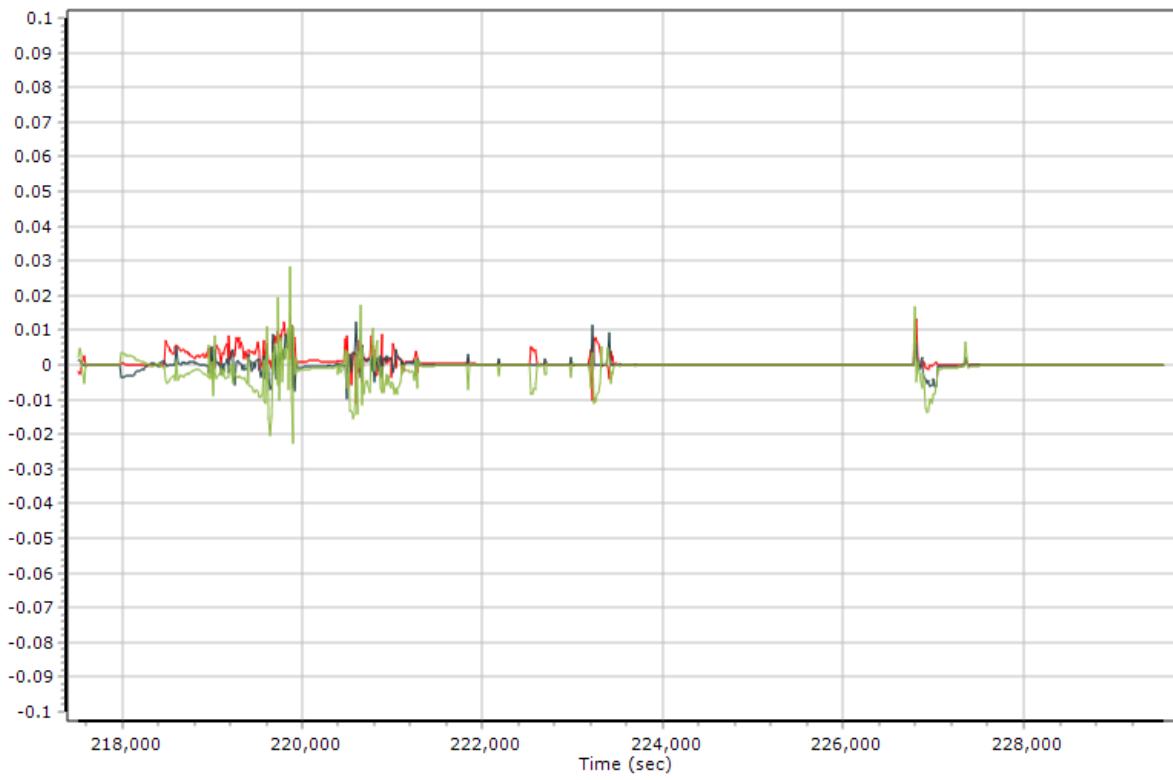
GPS GLONASS BEIDOU QZSS

- | | | | |
|--------------------------------|---------------------------------|---------------------------------|---------------------------------|
| <input type="checkbox"/> PRN 1 | <input type="checkbox"/> PRN 10 | <input type="checkbox"/> PRN 19 | <input type="checkbox"/> PRN 28 |
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| <input type="checkbox"/> PRN 3 | <input type="checkbox"/> PRN 12 | <input type="checkbox"/> PRN 21 | <input type="checkbox"/> PRN 30 |
| <input type="checkbox"/> PRN 4 | <input type="checkbox"/> PRN 13 | <input type="checkbox"/> PRN 22 | <input type="checkbox"/> PRN 31 |
| <input type="checkbox"/> PRN 5 | <input type="checkbox"/> PRN 14 | <input type="checkbox"/> PRN 23 | <input type="checkbox"/> PRN 32 |
| <input type="checkbox"/> PRN 6 | <input type="checkbox"/> PRN 15 | <input type="checkbox"/> PRN 24 | |
| <input type="checkbox"/> PRN 7 | <input type="checkbox"/> PRN 16 | <input type="checkbox"/> PRN 25 | |
| <input type="checkbox"/> PRN 8 | <input type="checkbox"/> PRN 17 | <input type="checkbox"/> PRN 26 | |
| <input type="checkbox"/> PRN 9 | <input type="checkbox"/> PRN 18 | <input type="checkbox"/> PRN 27 | |



Elevation Mask Angle

Force GPS Only



— North (m) — East (m) — Down (m) — DR mode

Timing

Start

End

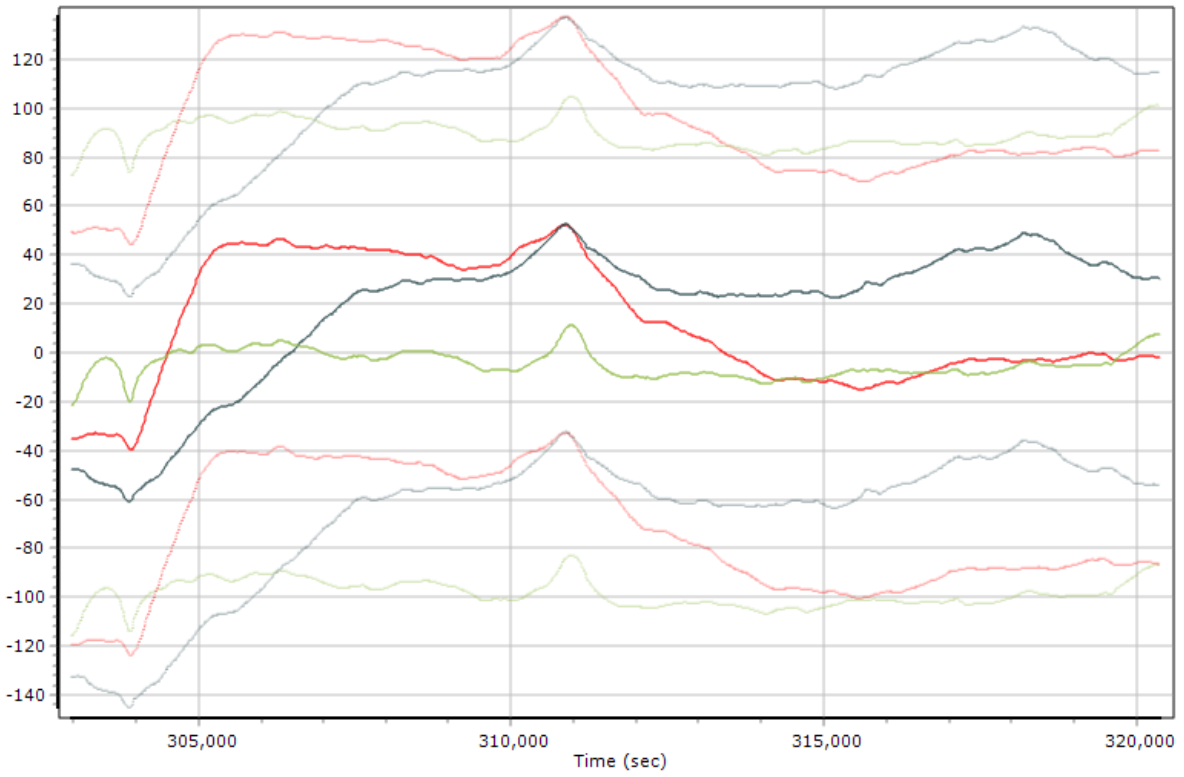
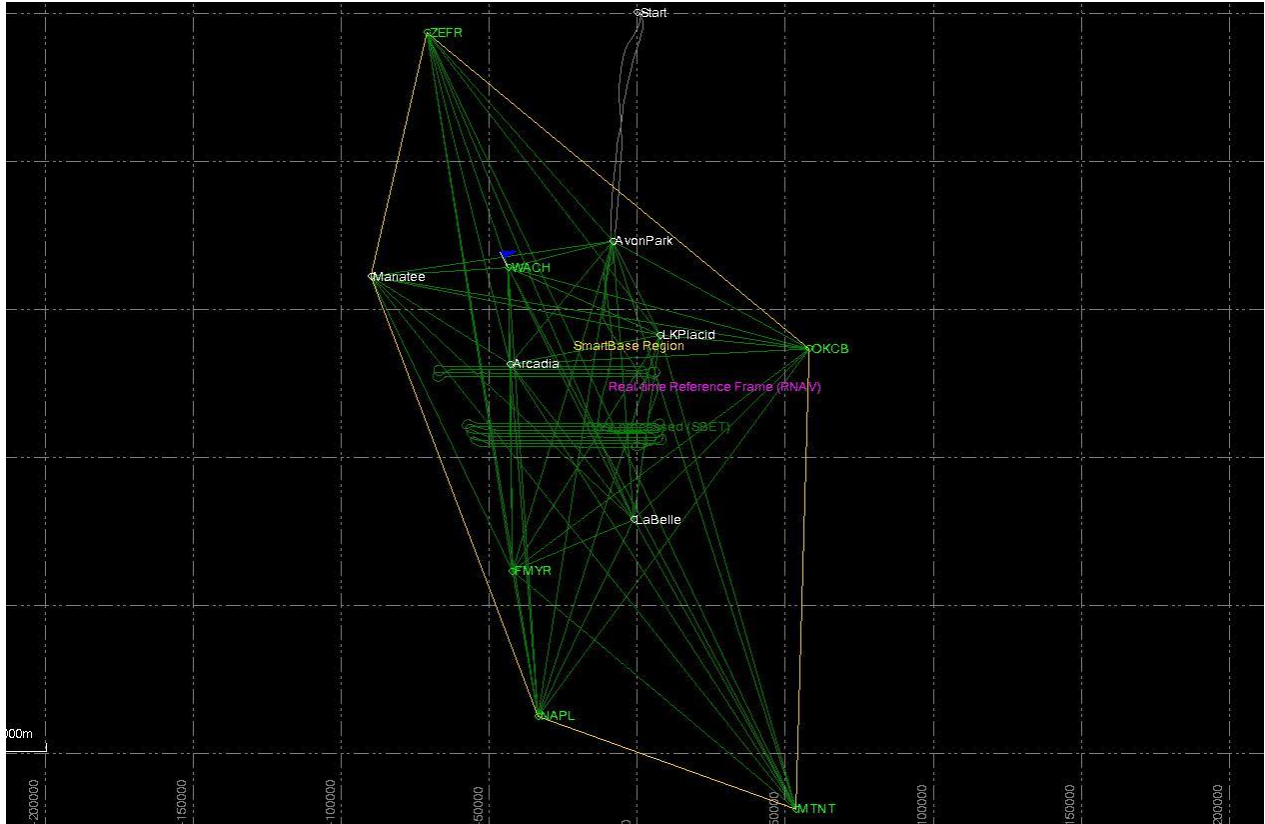
Entire time interval

Seconds of start week

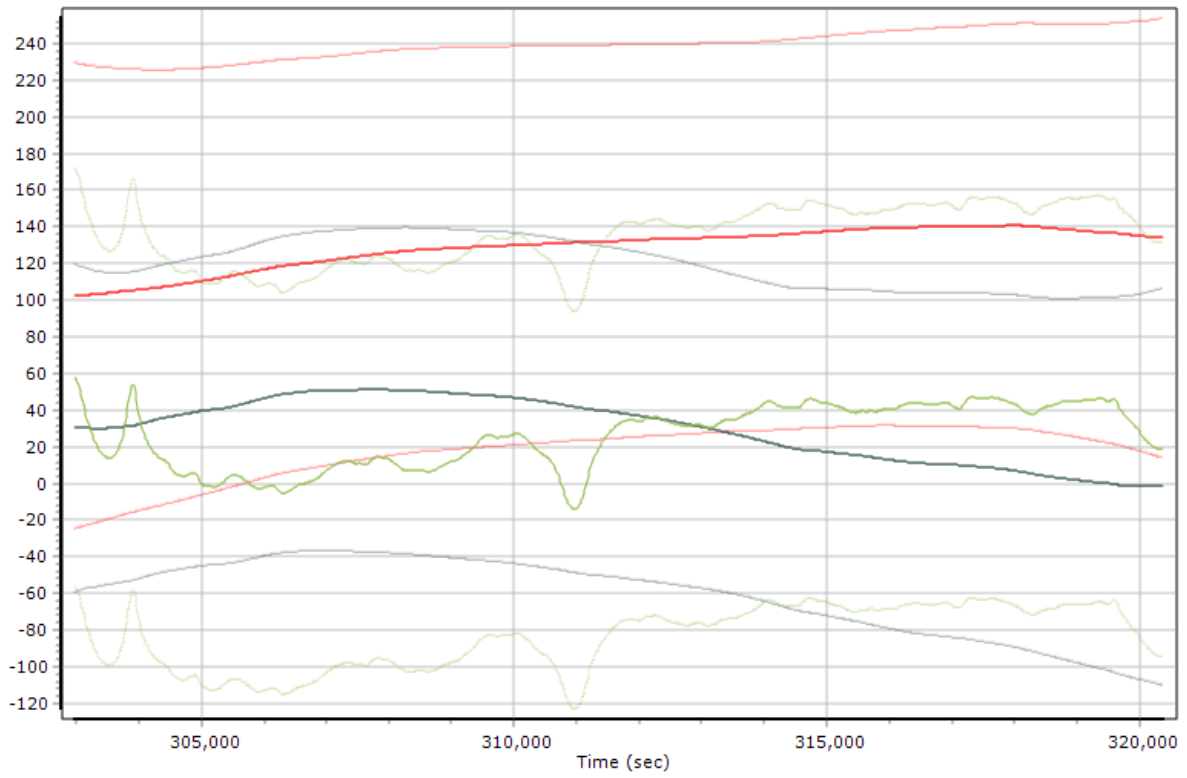
UTC Offset

Data	Incr. (sec)
Output Record	0.005000
IMU	0.005000
Primary GNSS	1.000000

MISSION: 45A18346A

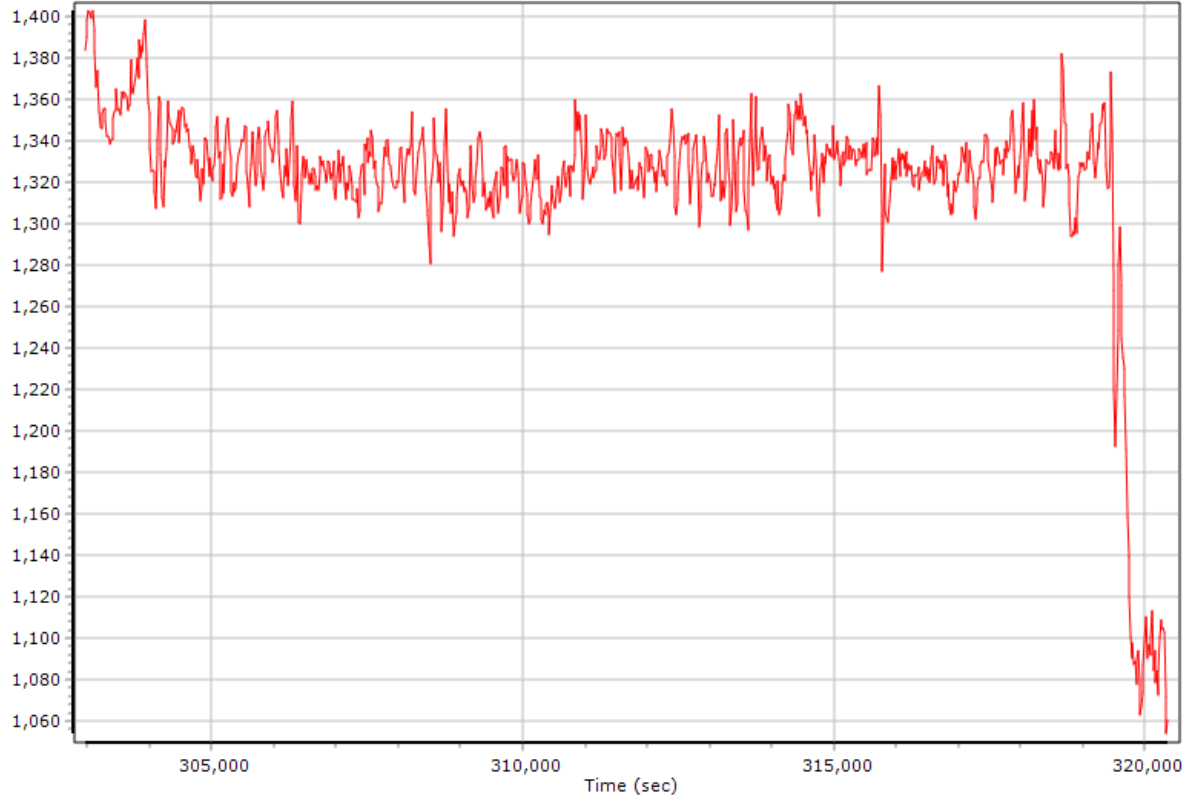


— x accelerometer bias (micro-g) — y accelerometer bias (micro-g) — z accelerometer bias (micro-g)

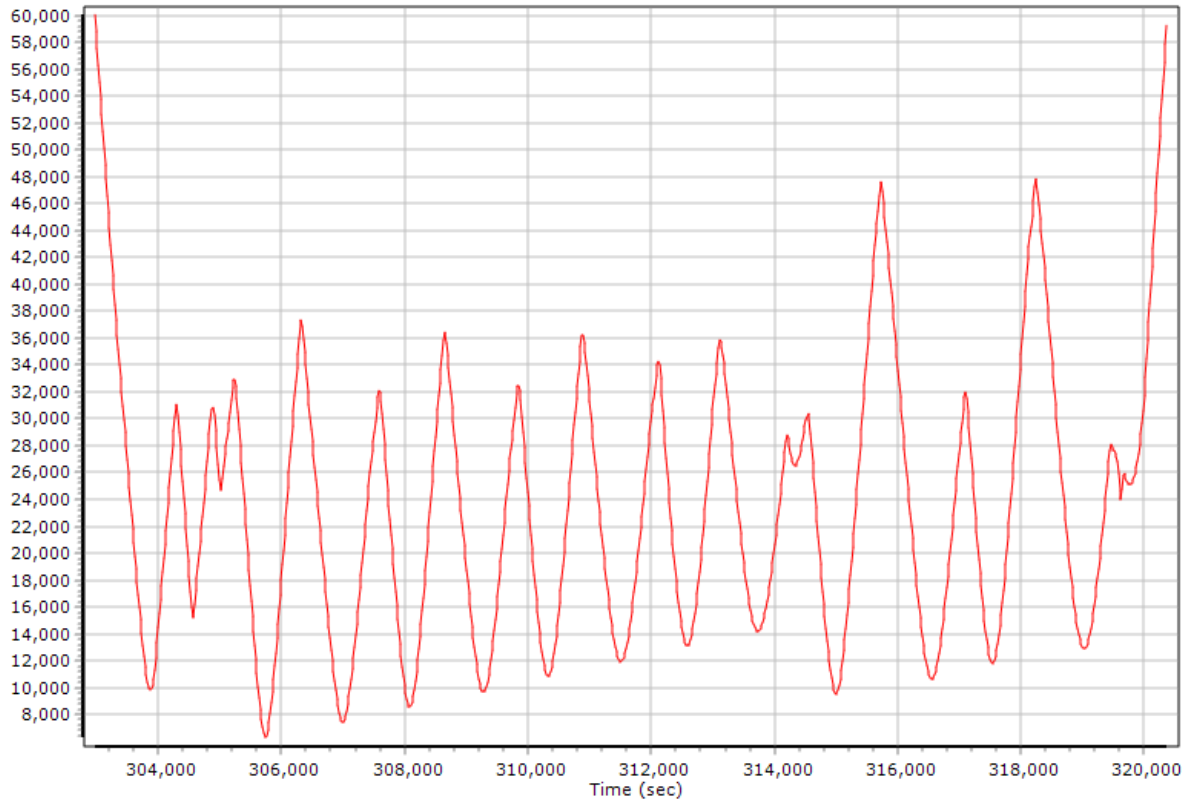


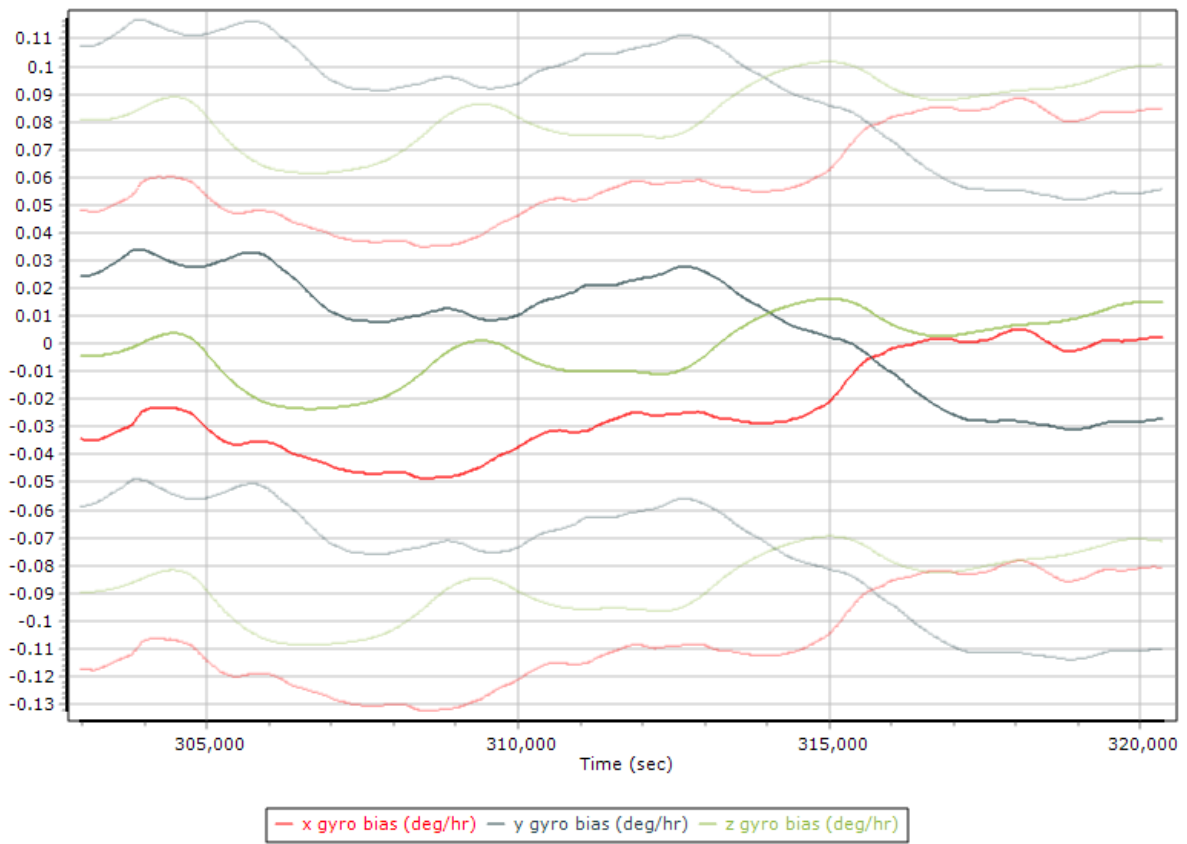
— x accelerometer scale error (ppm) — y accelerometer scale error (ppm) — z accelerometer scale error (ppm)

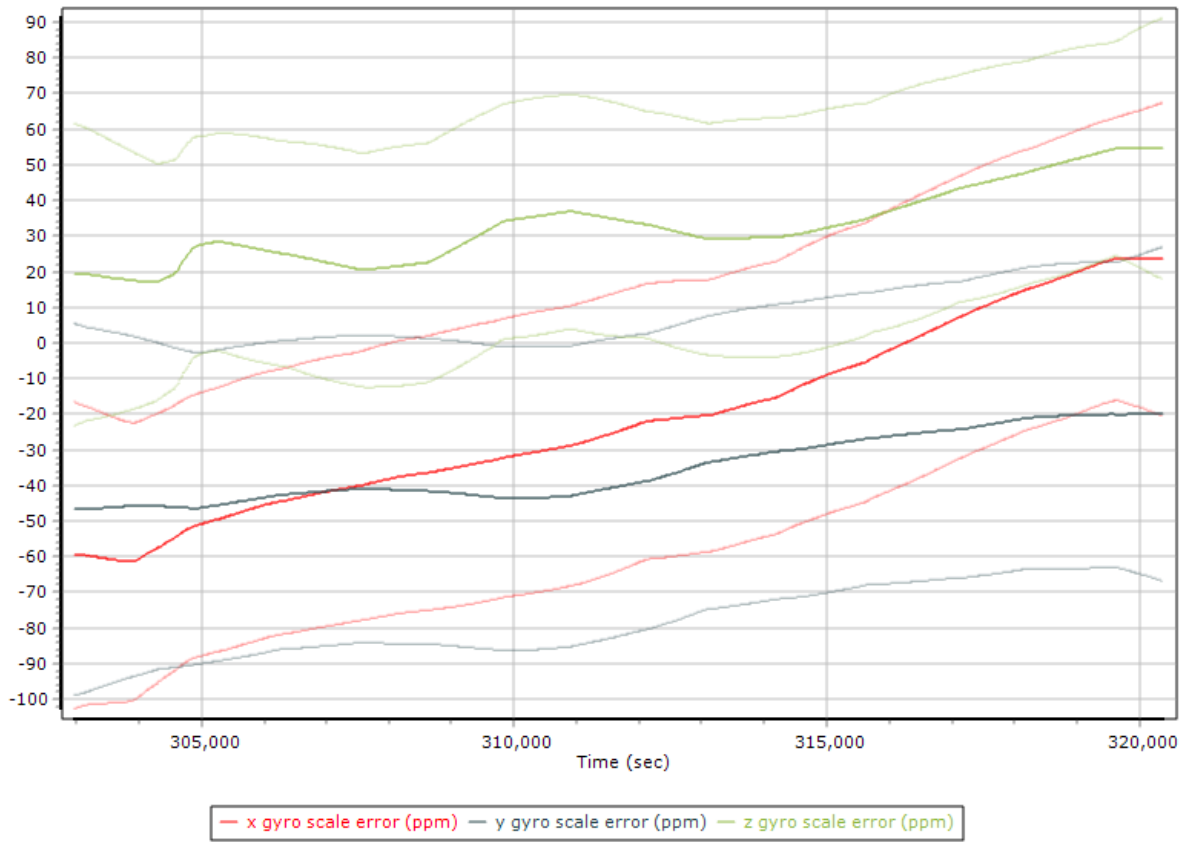
Altitude (m)



Baseline Length(m)







Stabilized Mount to IMU Lever Arm

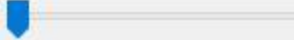
X
Y
Z

Stabilized Mount to IMU Mounting Angles

X
Y
Z

Stabilized Mount to Primary GNSS Lever Arm

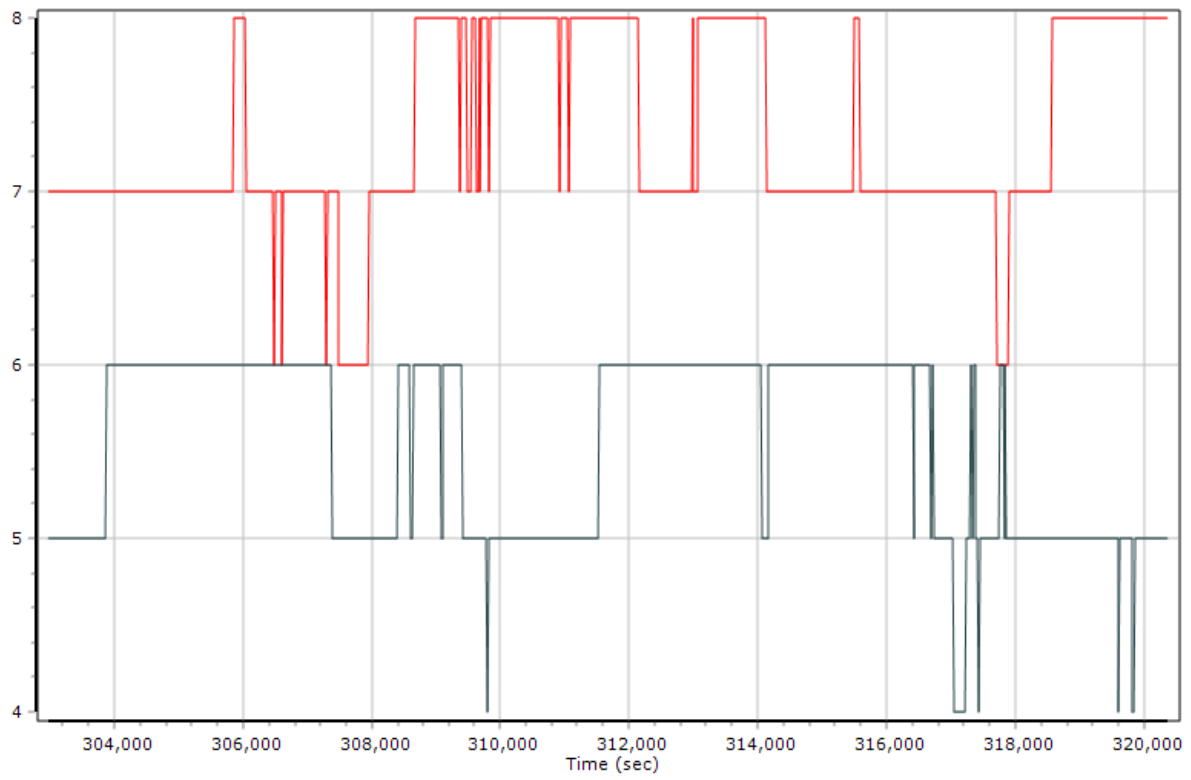
X
Y
Z

Standard Deviation 
<3cm 10cm 50cm 1m 10m

Aircraft to Stabilized Mount Mounting Angles

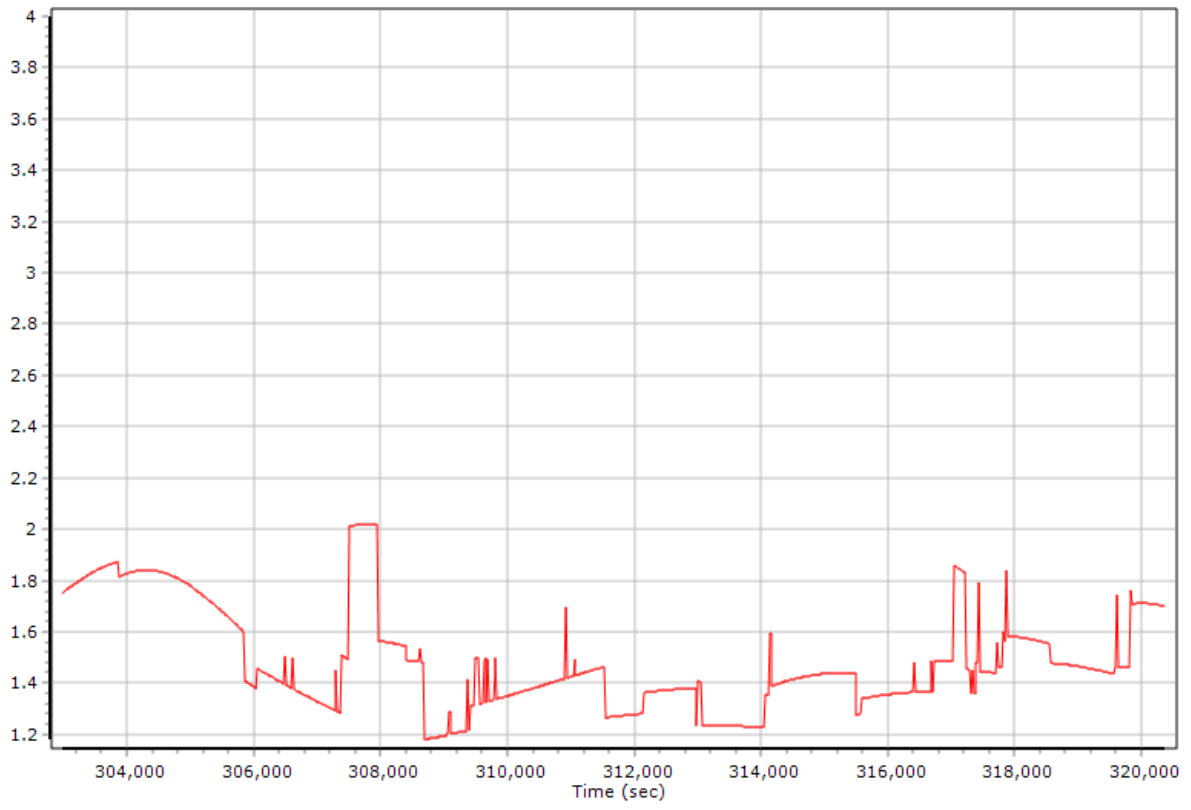
X
Y
Z

Measurements are to the stabilized platform's center of rotation with the Gimbal in the rest position.

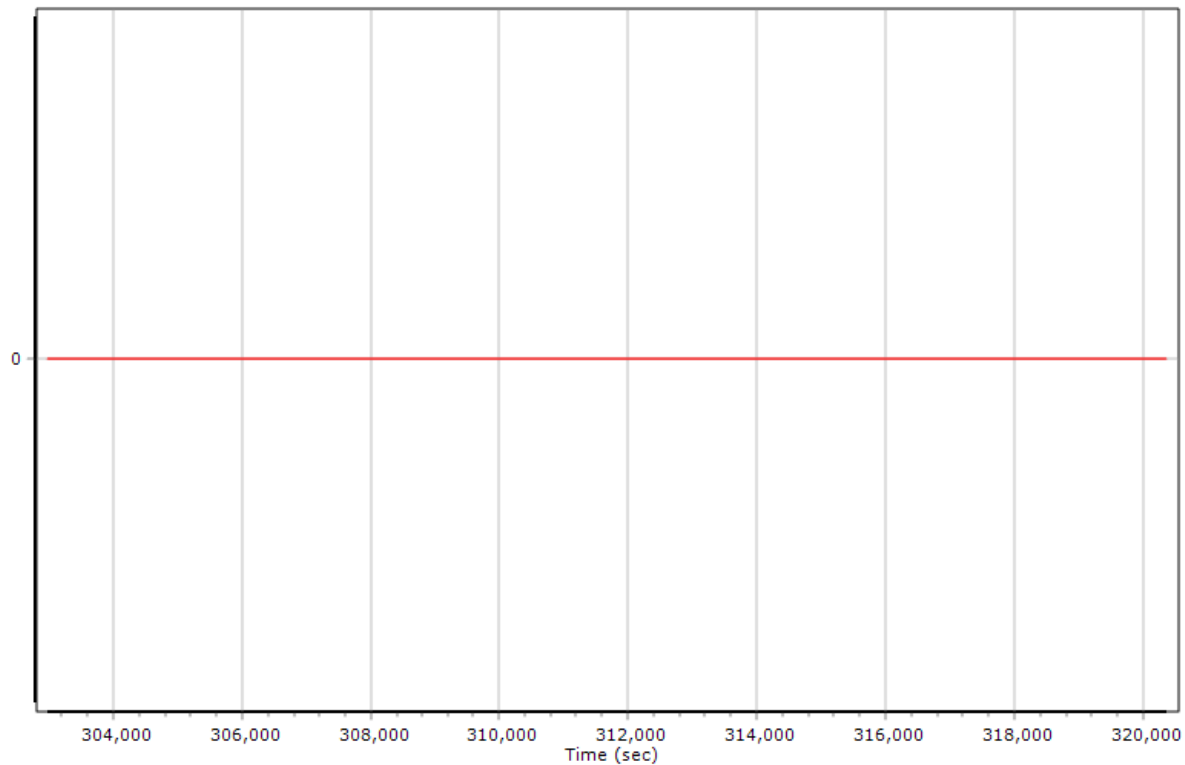


— Number of GPS Satellites — Number of GLONASS Satellites

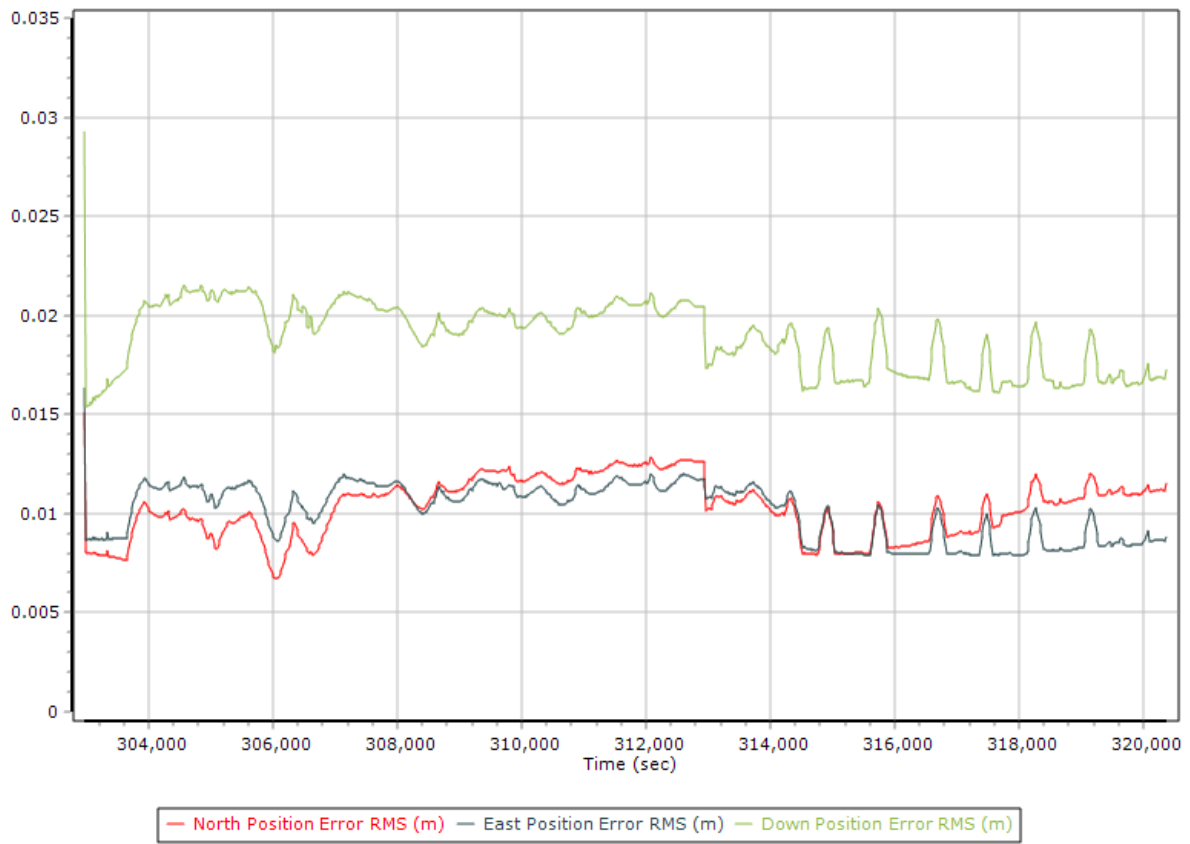
PDOP

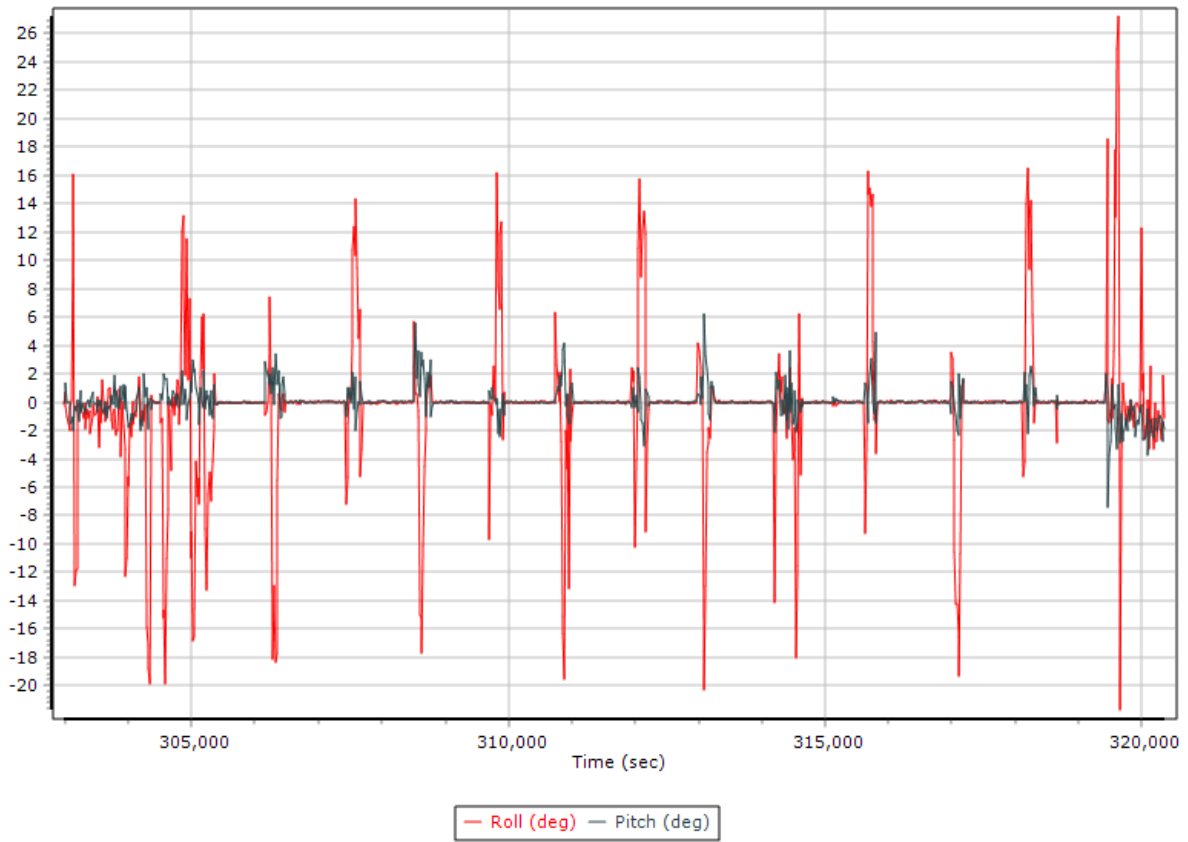


Processing Mode



0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = C/A, 7 = GNSS Nav, 8 = DR





Disable Satellites

GPS GLONASS BEIDOU QZSS

- | | | |
|---------------------------------|----------------------------------|----------------------------------|
| <input type="checkbox"/> SLOT 1 | <input type="checkbox"/> SLOT 10 | <input type="checkbox"/> SLOT 19 |
| <input type="checkbox"/> SLOT 2 | <input type="checkbox"/> SLOT 11 | <input type="checkbox"/> SLOT 20 |
| <input type="checkbox"/> SLOT 3 | <input type="checkbox"/> SLOT 12 | <input type="checkbox"/> SLOT 21 |
| <input type="checkbox"/> SLOT 4 | <input type="checkbox"/> SLOT 13 | <input type="checkbox"/> SLOT 22 |
| <input type="checkbox"/> SLOT 5 | <input type="checkbox"/> SLOT 14 | <input type="checkbox"/> SLOT 23 |
| <input type="checkbox"/> SLOT 6 | <input type="checkbox"/> SLOT 15 | <input type="checkbox"/> SLOT 24 |
| <input type="checkbox"/> SLOT 7 | <input type="checkbox"/> SLOT 16 | |
| <input type="checkbox"/> SLOT 8 | <input type="checkbox"/> SLOT 17 | |
| <input type="checkbox"/> SLOT 9 | <input type="checkbox"/> SLOT 18 | |

Elevation Mask Angle

Force GPS Only

Disable Satellites

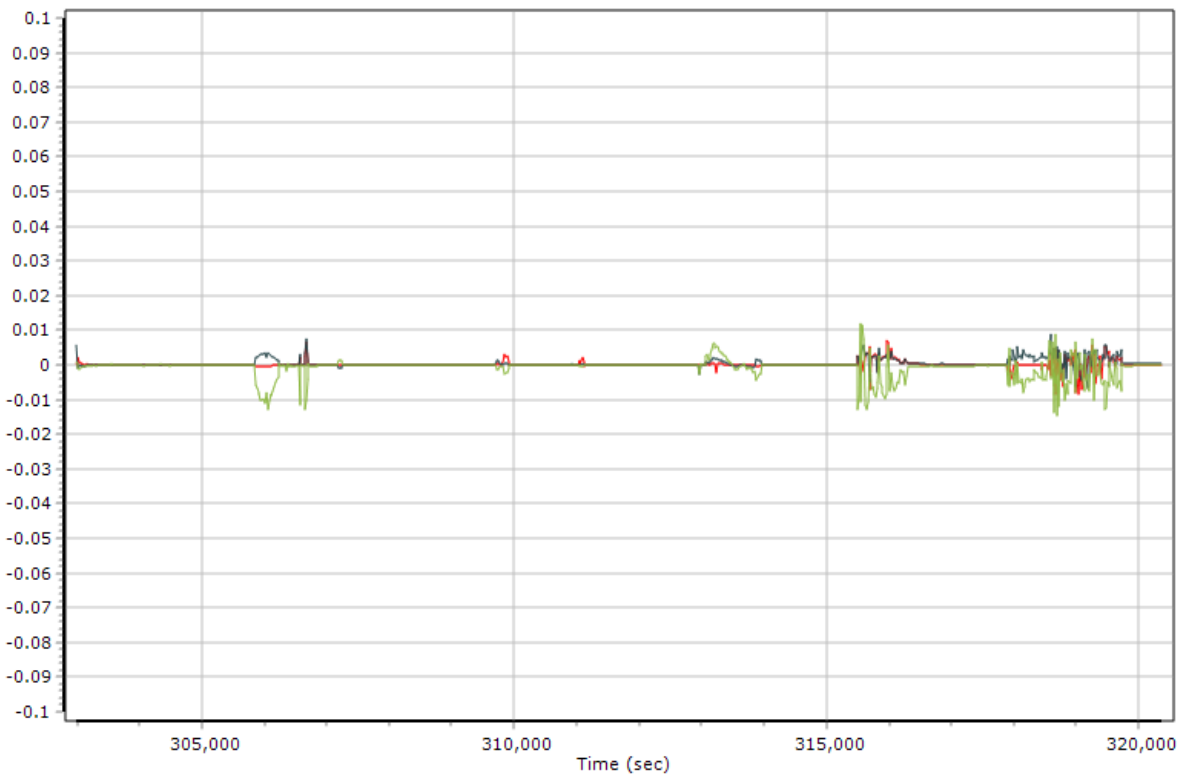
GPS GLONASS BEIDOU QZSS

- | | | | |
|--------------------------------|---------------------------------|---------------------------------|---------------------------------|
| <input type="checkbox"/> PRN 1 | <input type="checkbox"/> PRN 10 | <input type="checkbox"/> PRN 19 | <input type="checkbox"/> PRN 28 |
| <input type="checkbox"/> PRN 2 | <input type="checkbox"/> PRN 11 | <input type="checkbox"/> PRN 20 | <input type="checkbox"/> PRN 29 |
| <input type="checkbox"/> PRN 3 | <input type="checkbox"/> PRN 12 | <input type="checkbox"/> PRN 21 | <input type="checkbox"/> PRN 30 |
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| <input type="checkbox"/> PRN 5 | <input type="checkbox"/> PRN 14 | <input type="checkbox"/> PRN 23 | <input type="checkbox"/> PRN 32 |
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| <input type="checkbox"/> PRN 7 | <input type="checkbox"/> PRN 16 | <input type="checkbox"/> PRN 25 | |
| <input type="checkbox"/> PRN 8 | <input type="checkbox"/> PRN 17 | <input type="checkbox"/> PRN 26 | |
| <input type="checkbox"/> PRN 9 | <input type="checkbox"/> PRN 18 | <input type="checkbox"/> PRN 27 | |



Elevation Mask Angle

Force GPS Only



— North (m) — East (m) — Down (m) — DR mode

Timing

Start

End

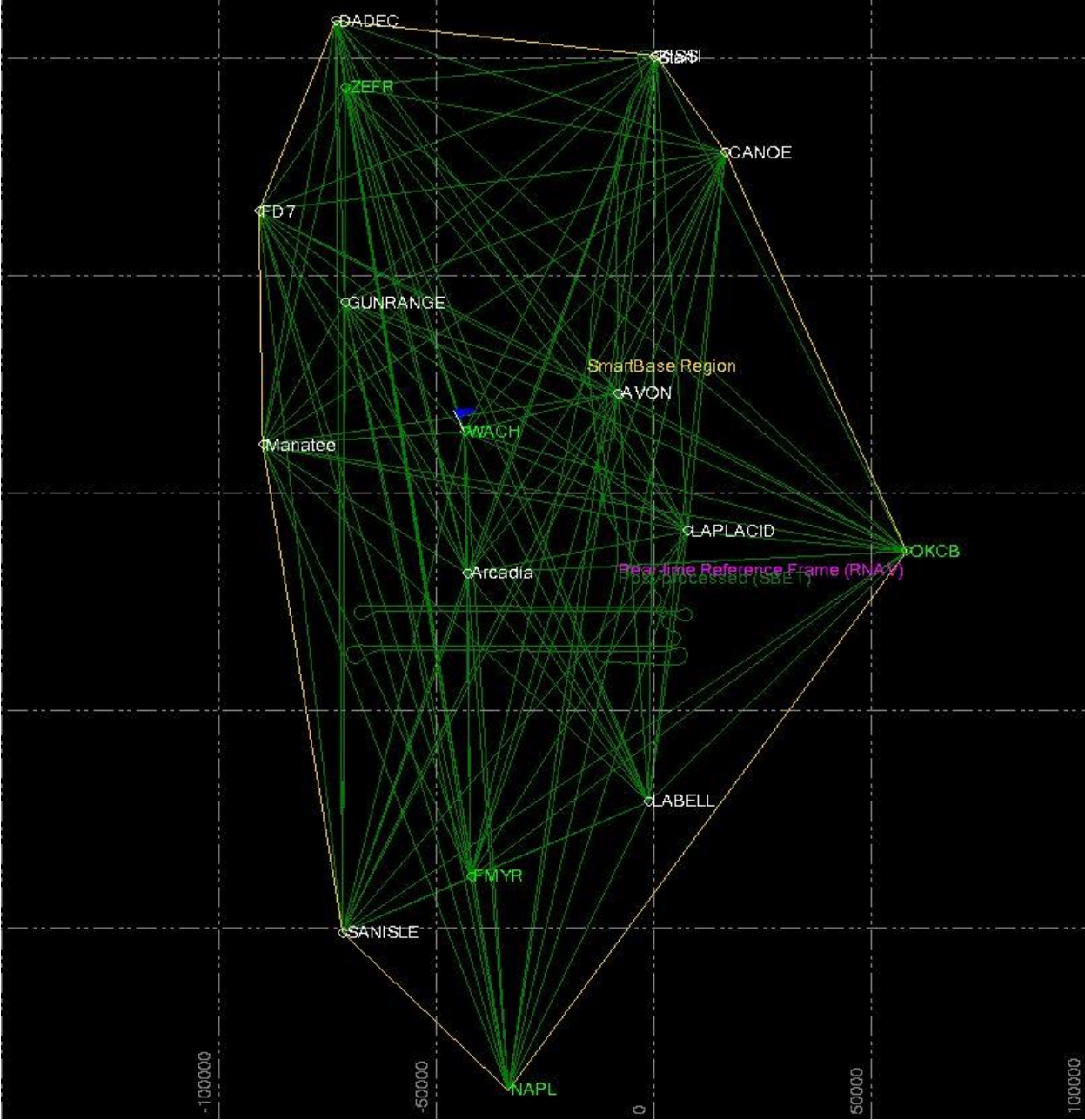
Entire time interval

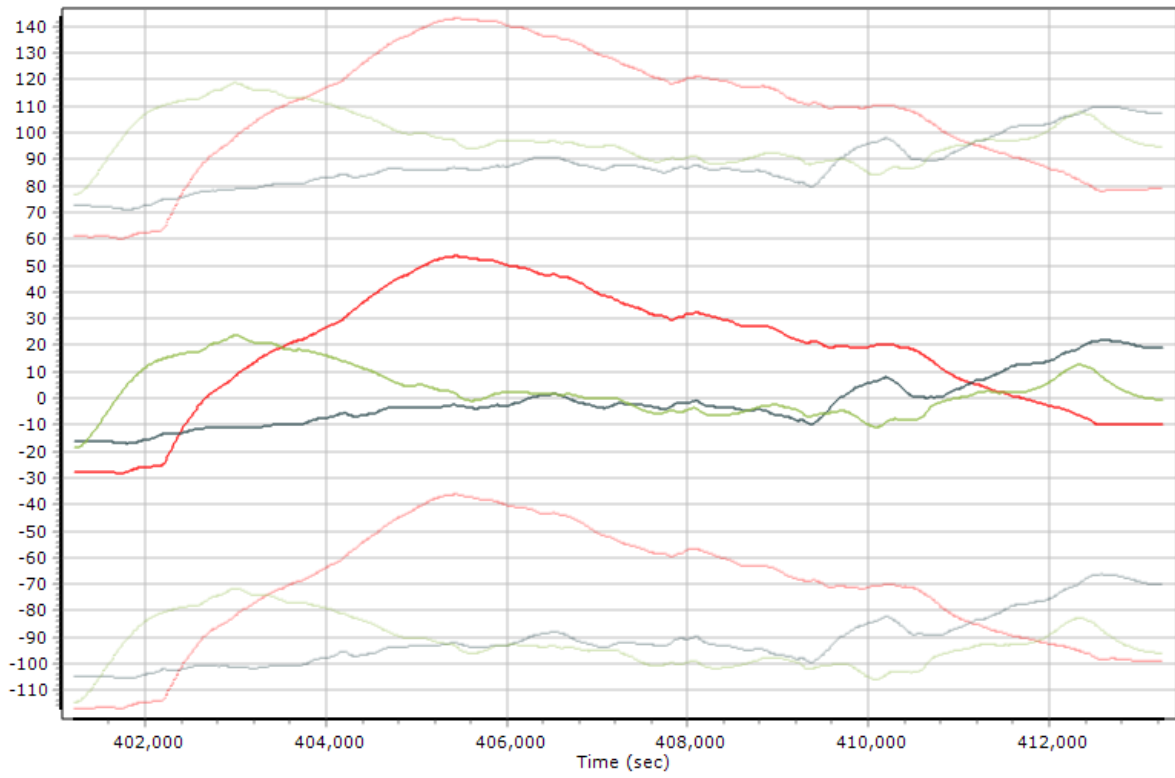
Seconds of start week

UTC Offset

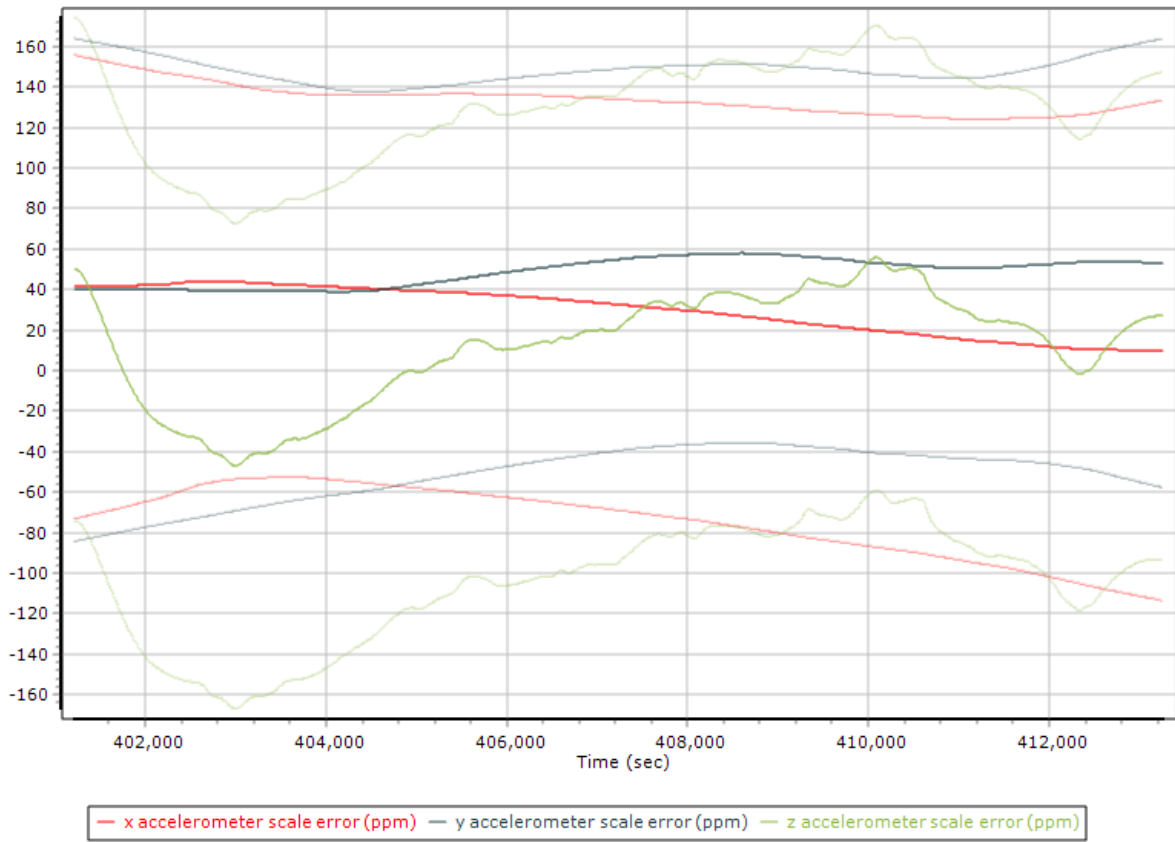
Data	Incr. (sec)
Output Record	0.005000
IMU	0.005000
Primary GNSS	1.000000

MISSION: 45A18347A

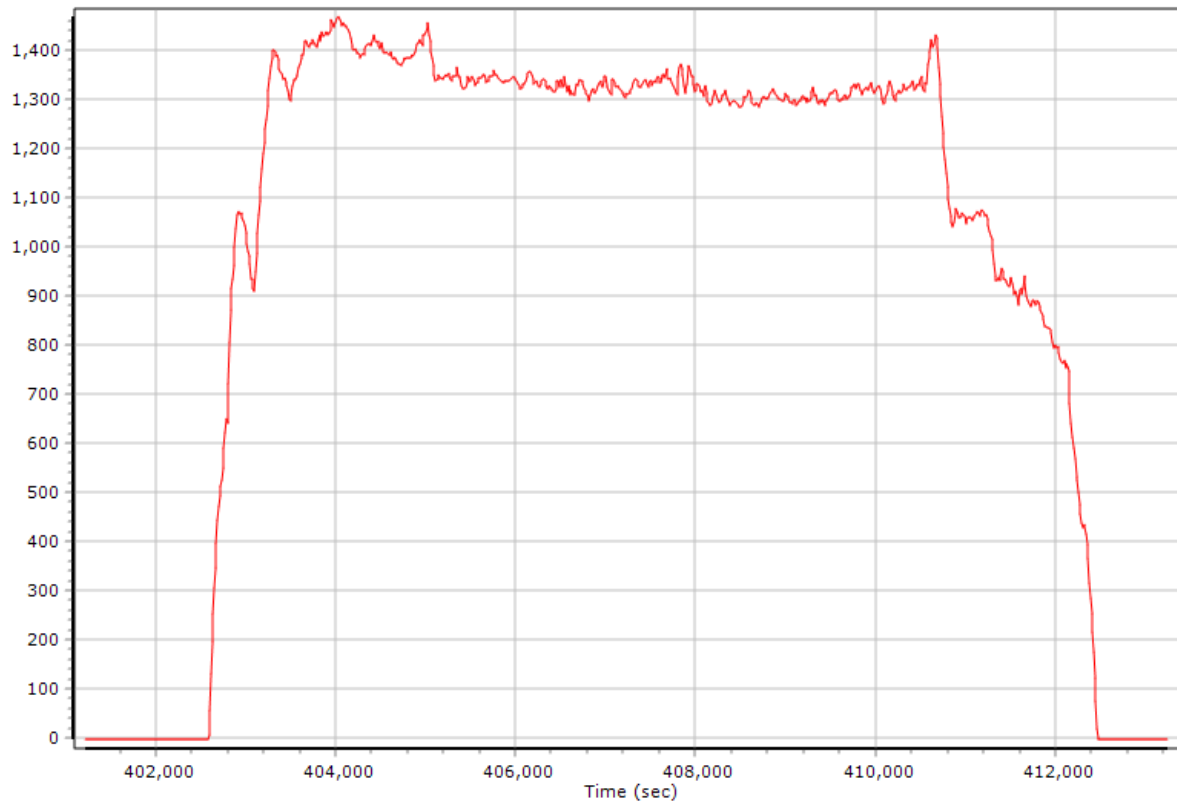




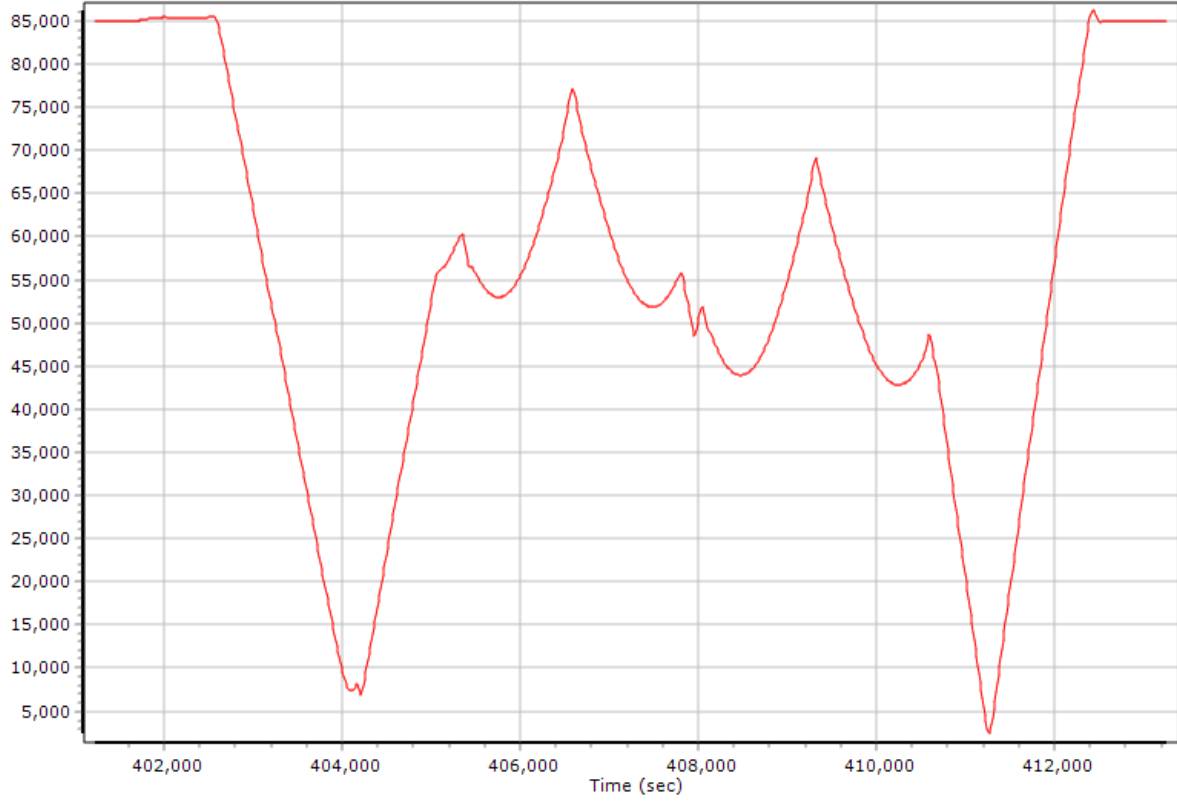
— x accelerometer bias (micro-g) — y accelerometer bias (micro-g) — z accelerometer bias (micro-g)

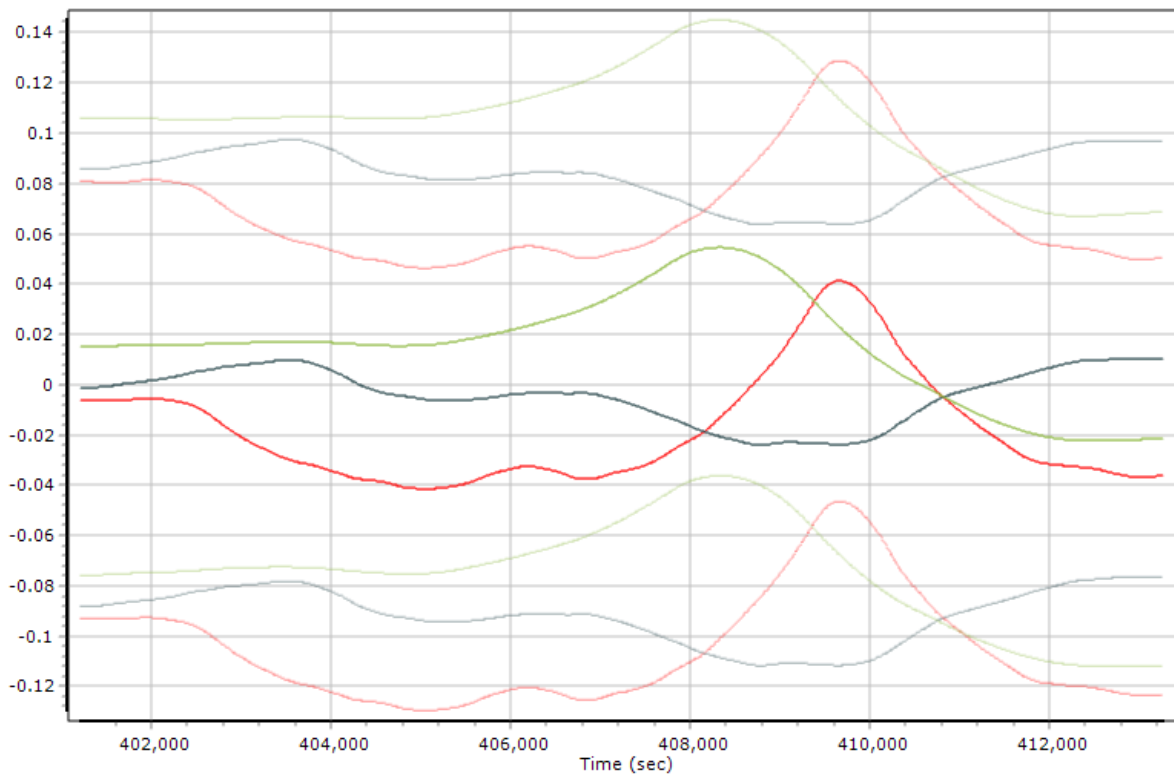


Altitude (m)

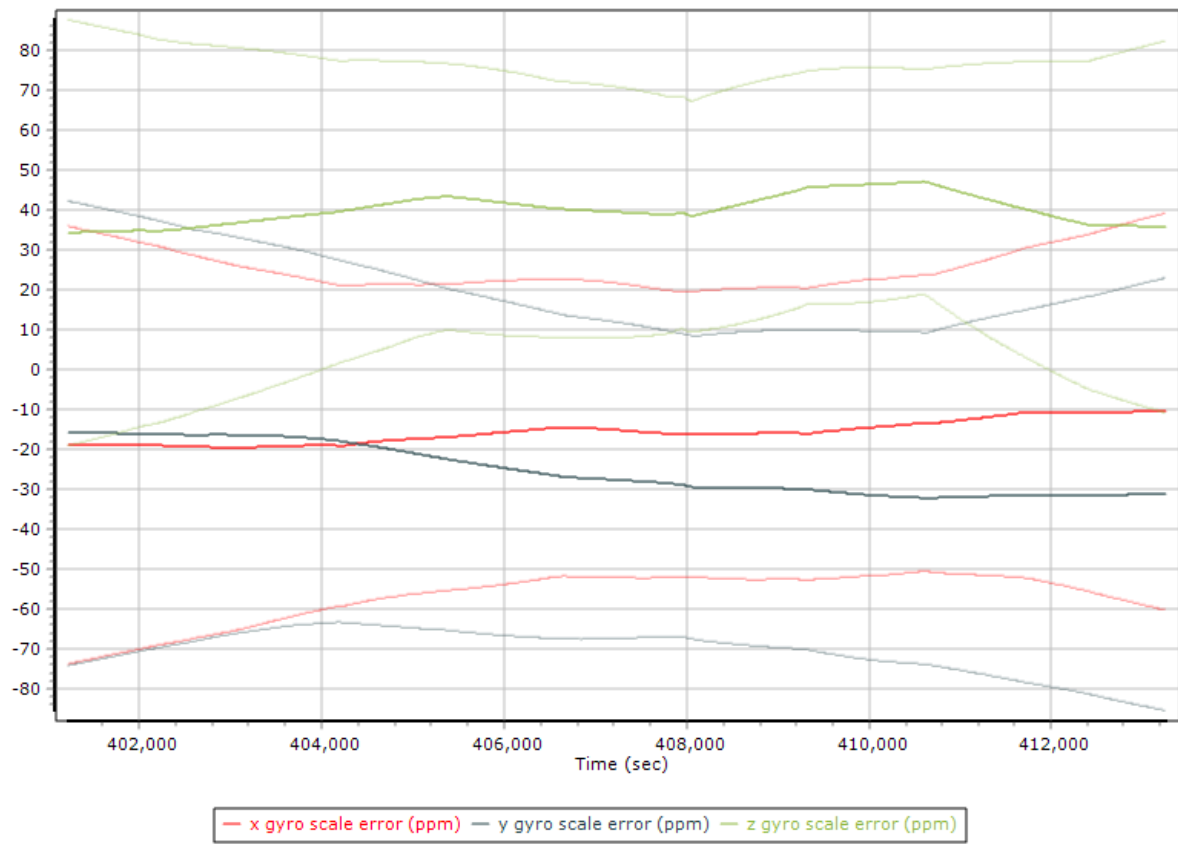


Baseline Length(m)





— x gyro bias (deg/hr) — y gyro bias (deg/hr) — z gyro bias (deg/hr)



Stabilized Mount to IMU Lever Arm

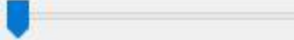
X
Y
Z

Stabilized Mount to IMU Mounting Angles

X
Y
Z

Stabilized Mount to Primary GNSS Lever Arm

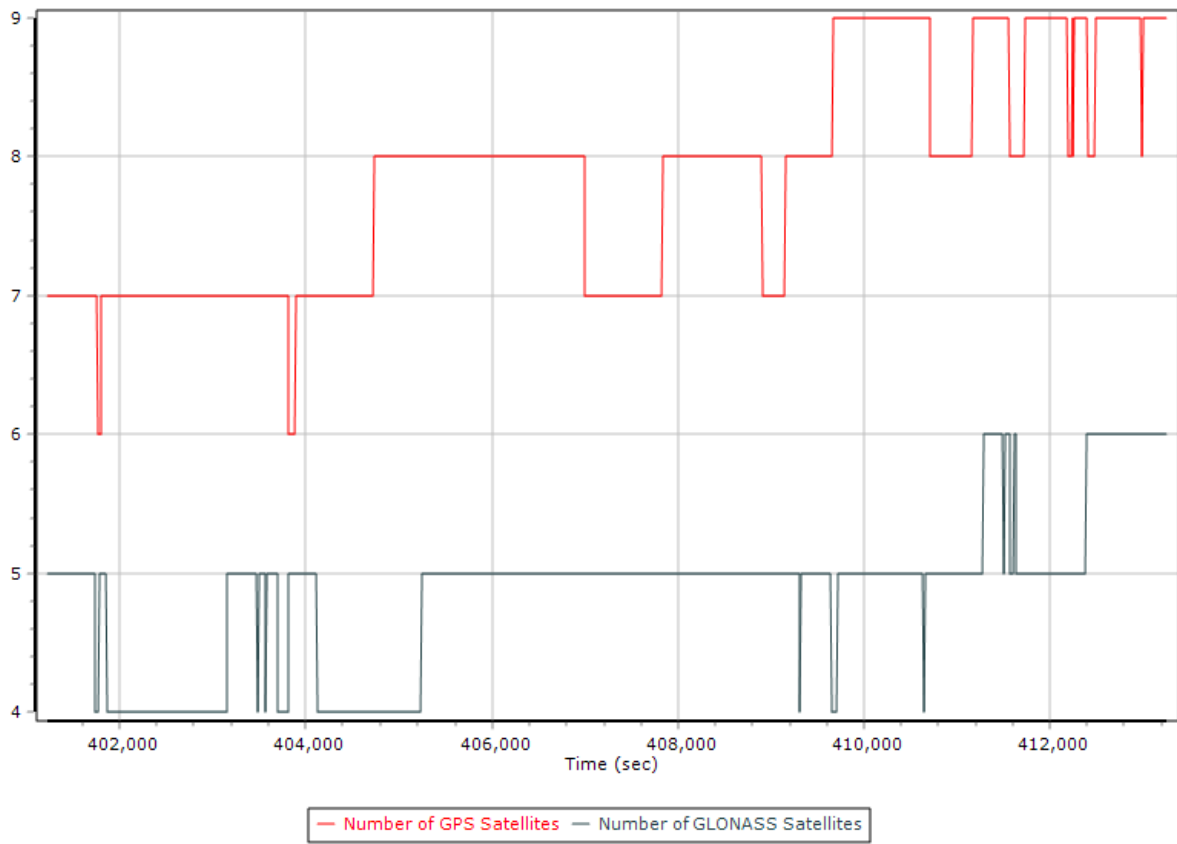
X
Y
Z

Standard Deviation 
<3cm 10cm 50cm 1m 10m

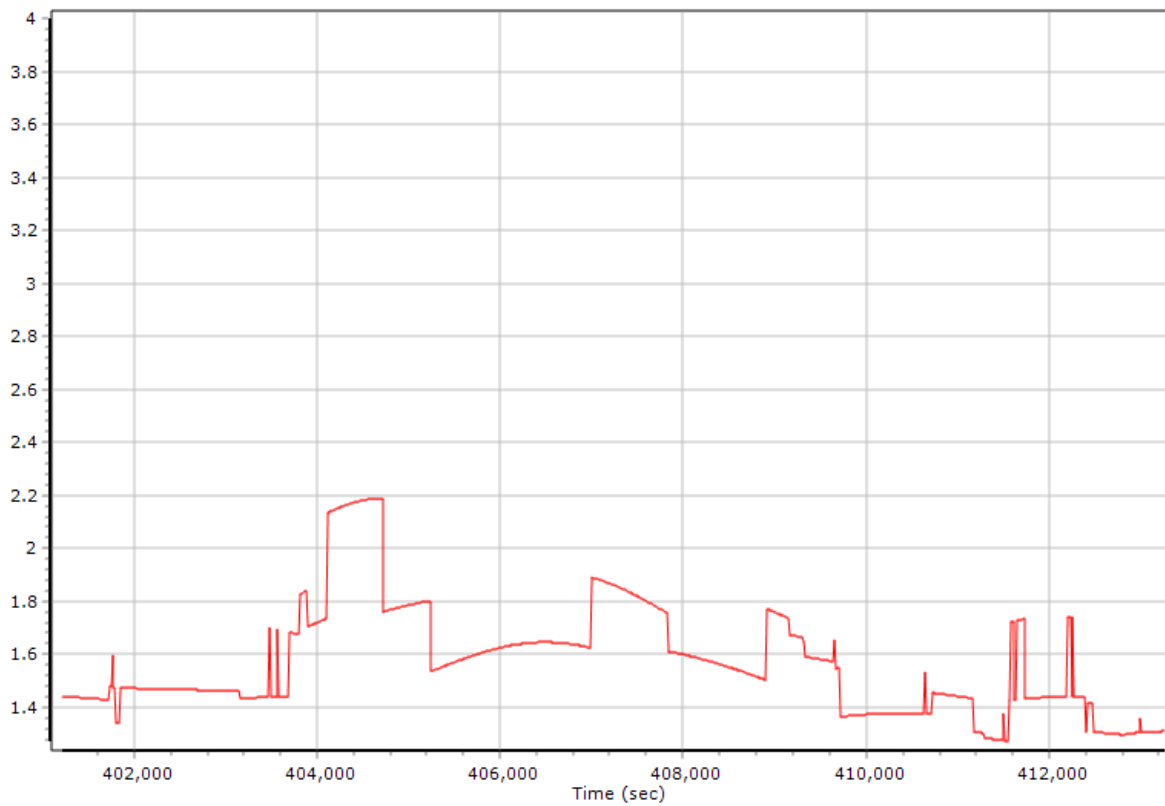
Aircraft to Stabilized Mount Mounting Angles

X
Y
Z

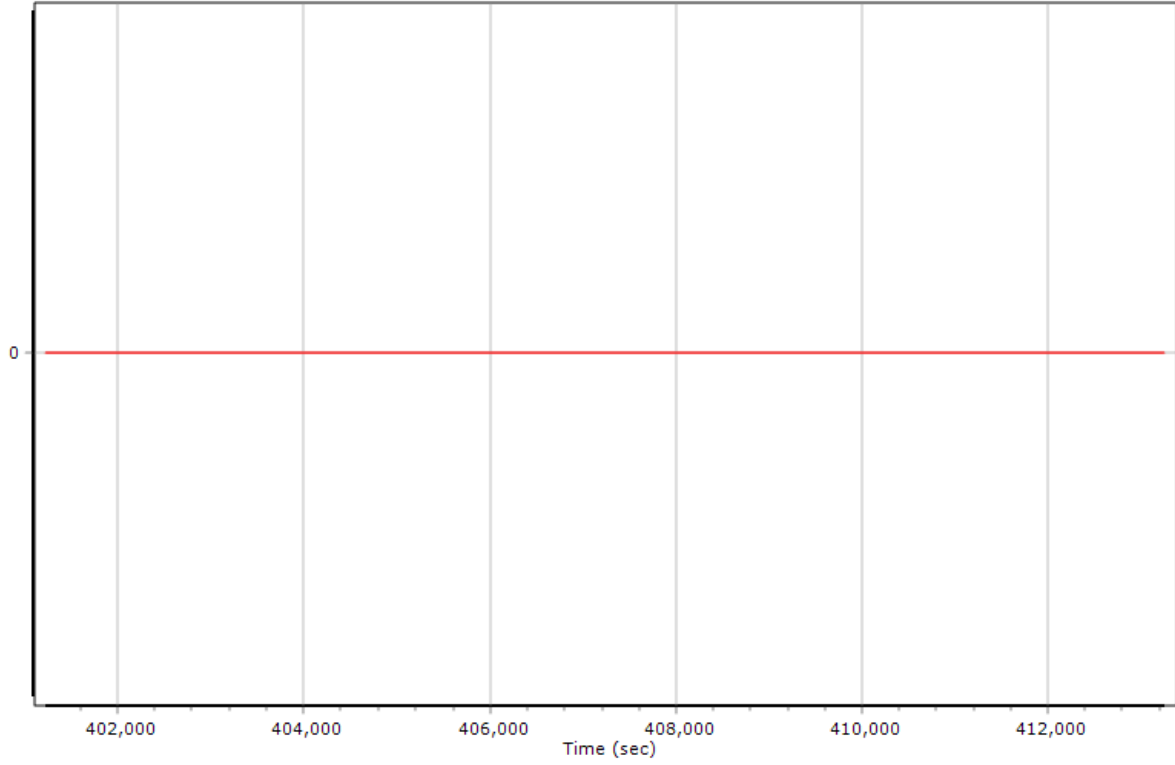
Measurements are to the stabilized platform's center of rotation with the Gimbal in the rest position.



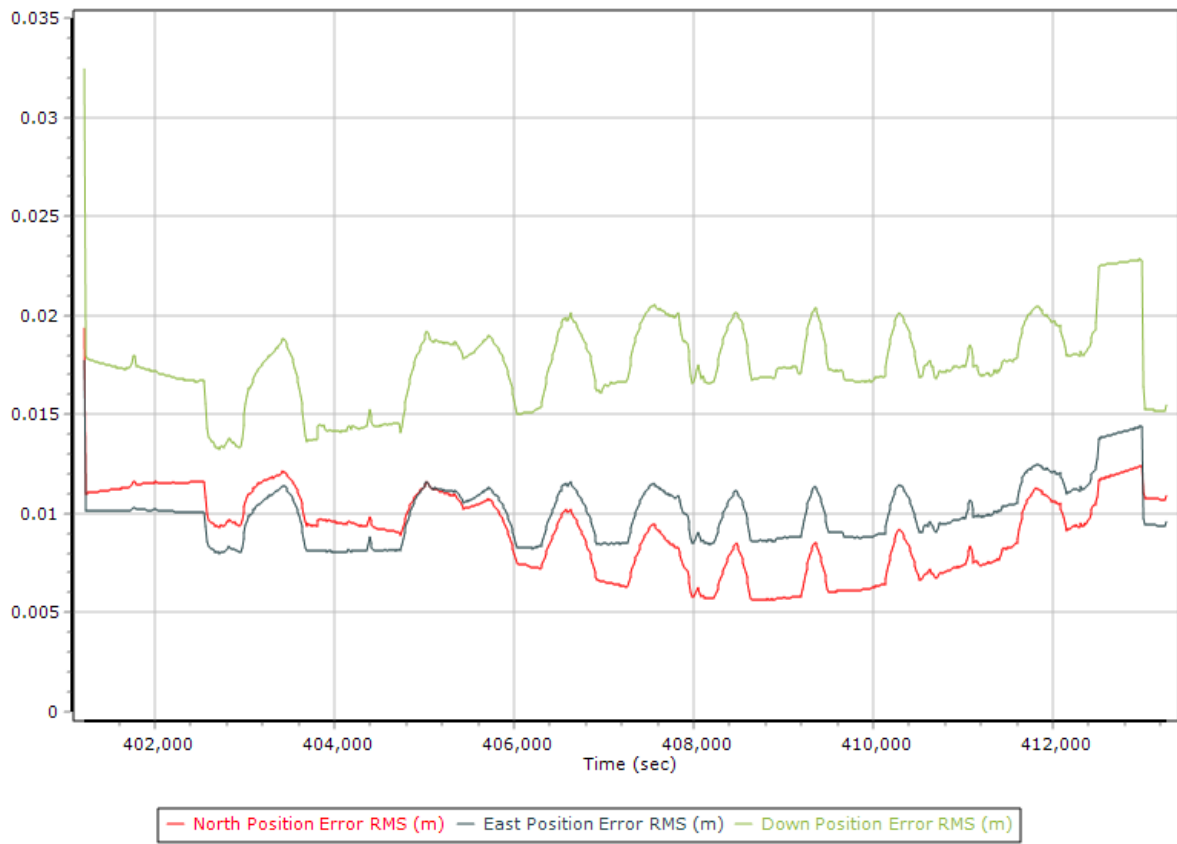
PDOP

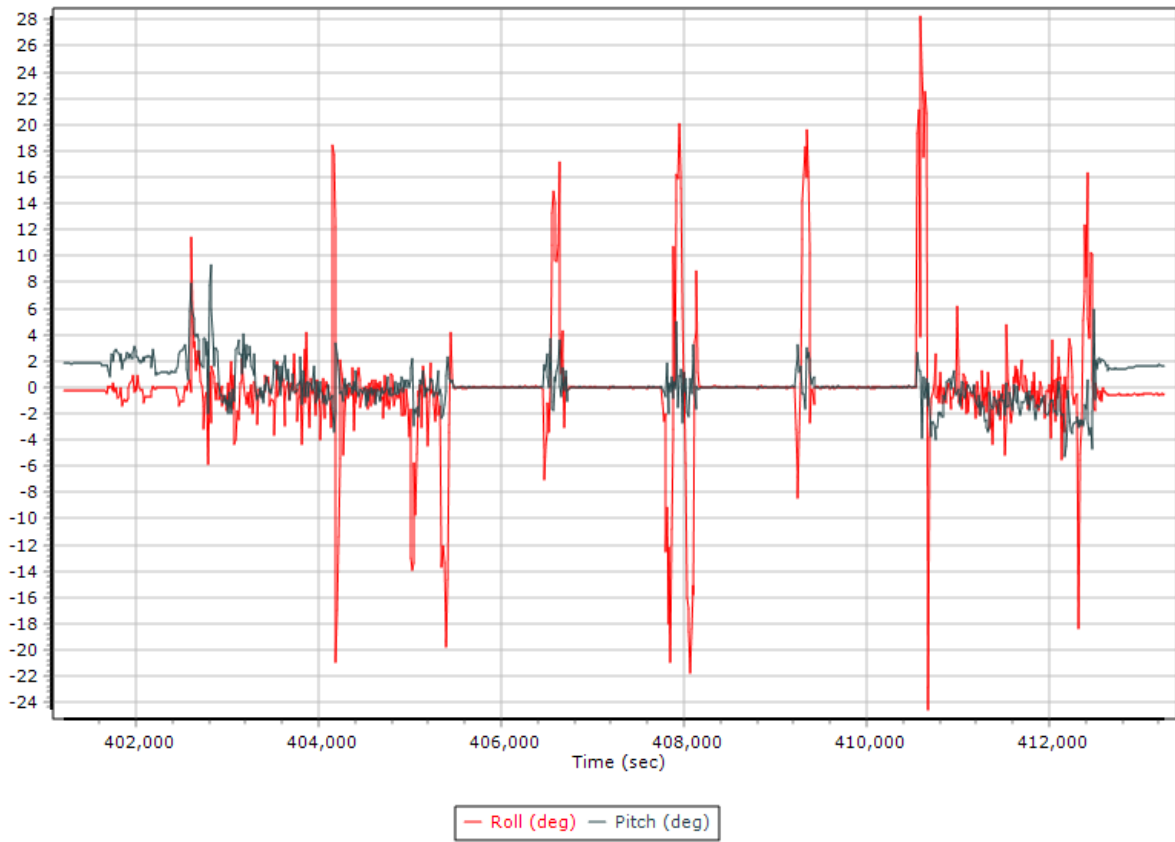


Processing Mode



0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = C/A, 7 = GNSS Nav, 8 = DR





Disable Satellites

GPS GLONASS BEIDOU QZSS

- | | | |
|---------------------------------|----------------------------------|----------------------------------|
| <input type="checkbox"/> SLOT 1 | <input type="checkbox"/> SLOT 10 | <input type="checkbox"/> SLOT 19 |
| <input type="checkbox"/> SLOT 2 | <input type="checkbox"/> SLOT 11 | <input type="checkbox"/> SLOT 20 |
| <input type="checkbox"/> SLOT 3 | <input type="checkbox"/> SLOT 12 | <input type="checkbox"/> SLOT 21 |
| <input type="checkbox"/> SLOT 4 | <input type="checkbox"/> SLOT 13 | <input type="checkbox"/> SLOT 22 |
| <input type="checkbox"/> SLOT 5 | <input type="checkbox"/> SLOT 14 | <input type="checkbox"/> SLOT 23 |
| <input type="checkbox"/> SLOT 6 | <input type="checkbox"/> SLOT 15 | <input type="checkbox"/> SLOT 24 |
| <input type="checkbox"/> SLOT 7 | <input type="checkbox"/> SLOT 16 | |
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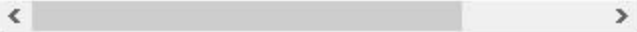
Elevation Mask Angle

Force GPS Only

Disable Satellites

GPS GLONASS BEIDOU QZSS

- | | | | |
|--------------------------------|---------------------------------|---------------------------------|---------------------------------|
| <input type="checkbox"/> PRN 1 | <input type="checkbox"/> PRN 10 | <input type="checkbox"/> PRN 19 | <input type="checkbox"/> PRN 28 |
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| <input type="checkbox"/> PRN 8 | <input type="checkbox"/> PRN 17 | <input type="checkbox"/> PRN 26 | |
| <input type="checkbox"/> PRN 9 | <input type="checkbox"/> PRN 18 | <input type="checkbox"/> PRN 27 | |



Elevation Mask Angle

Force GPS Only



Timing

Start

End

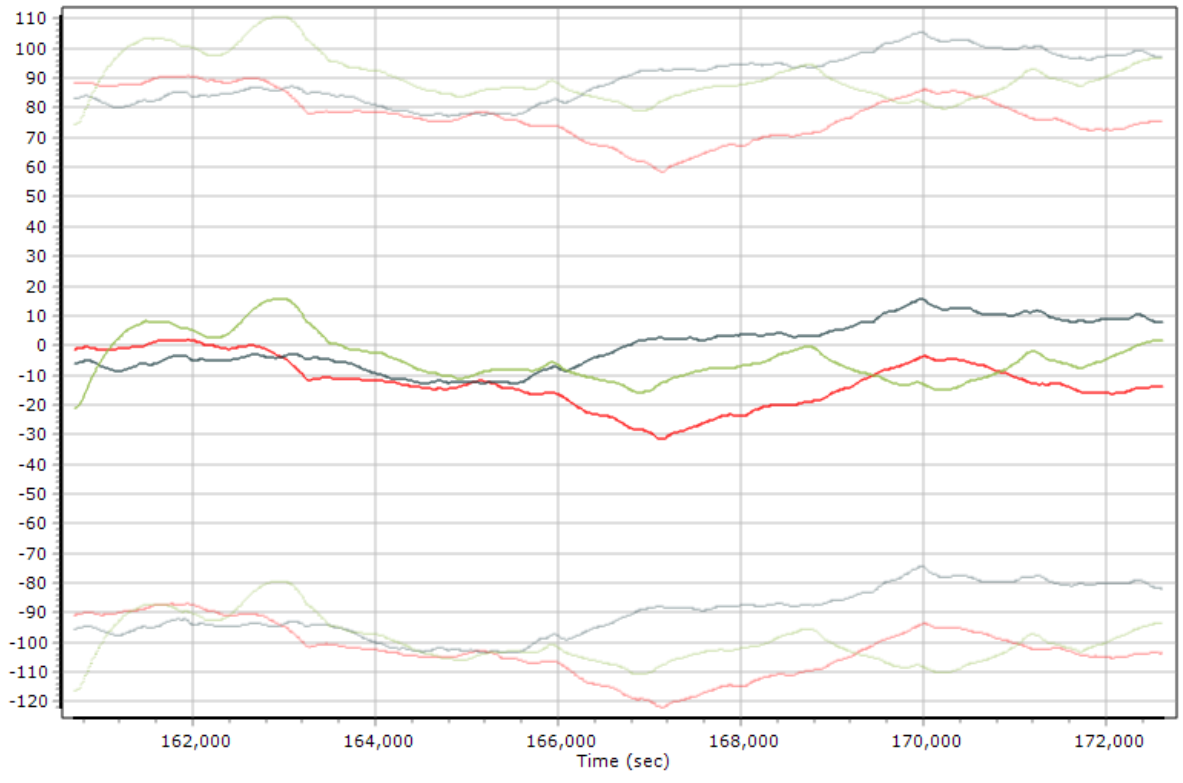
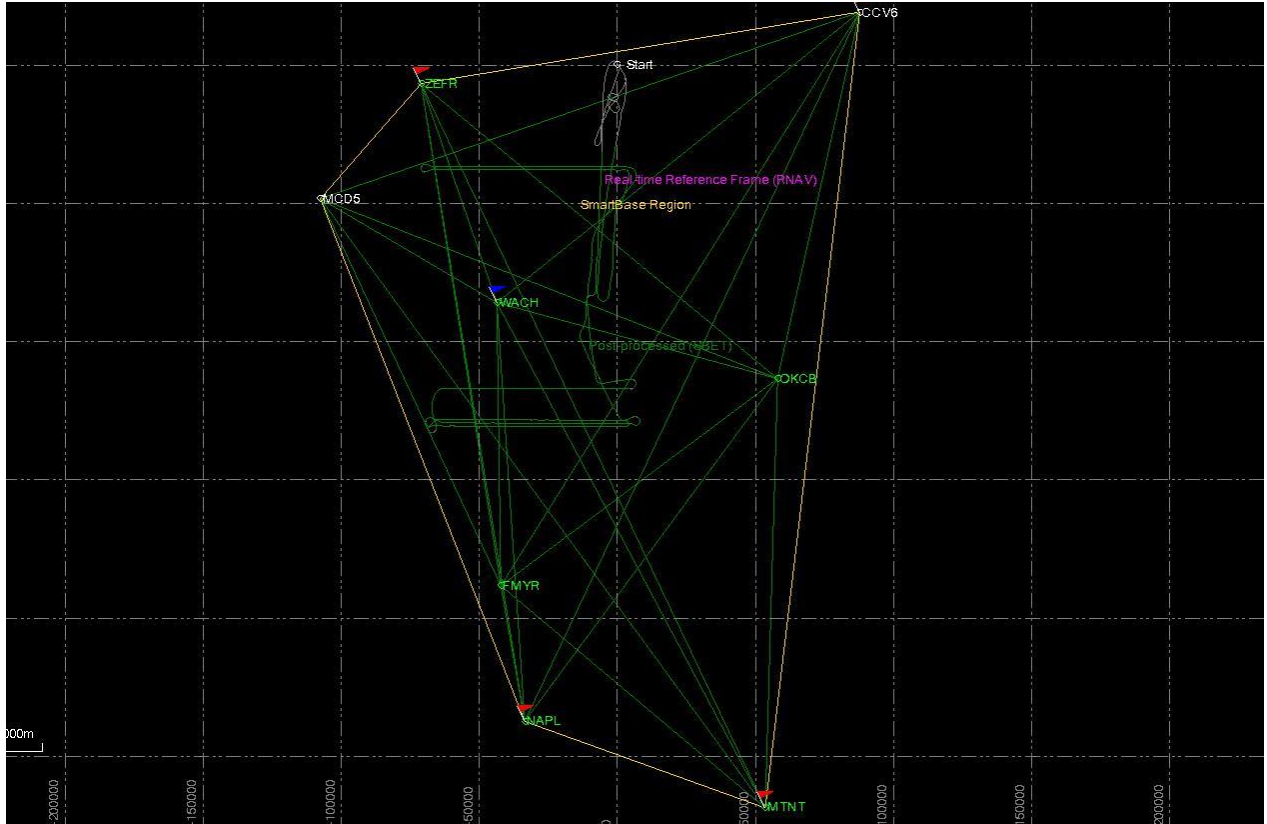
Entire time interval

Seconds of start week

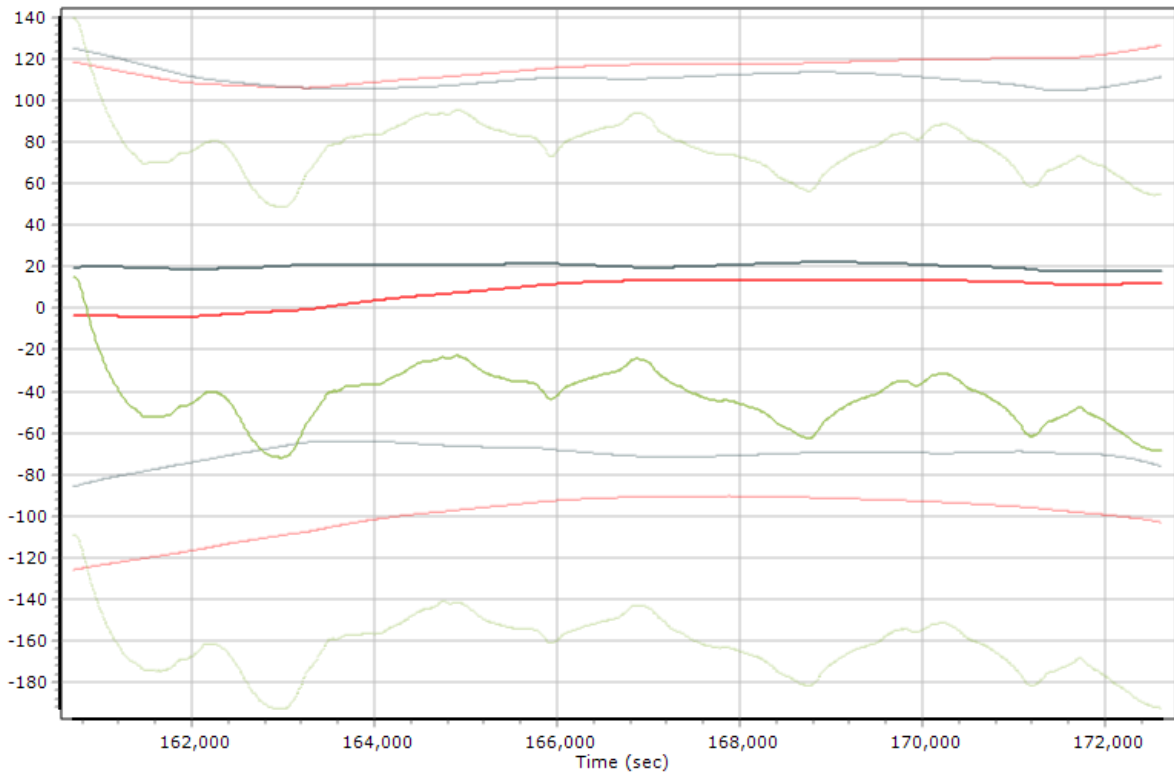
UTC Offset

Data	Incr. (sec)
Output Record	0.005000
IMU	0.005000
Primary GNSS	1.000000

MISSION: 45A18351A

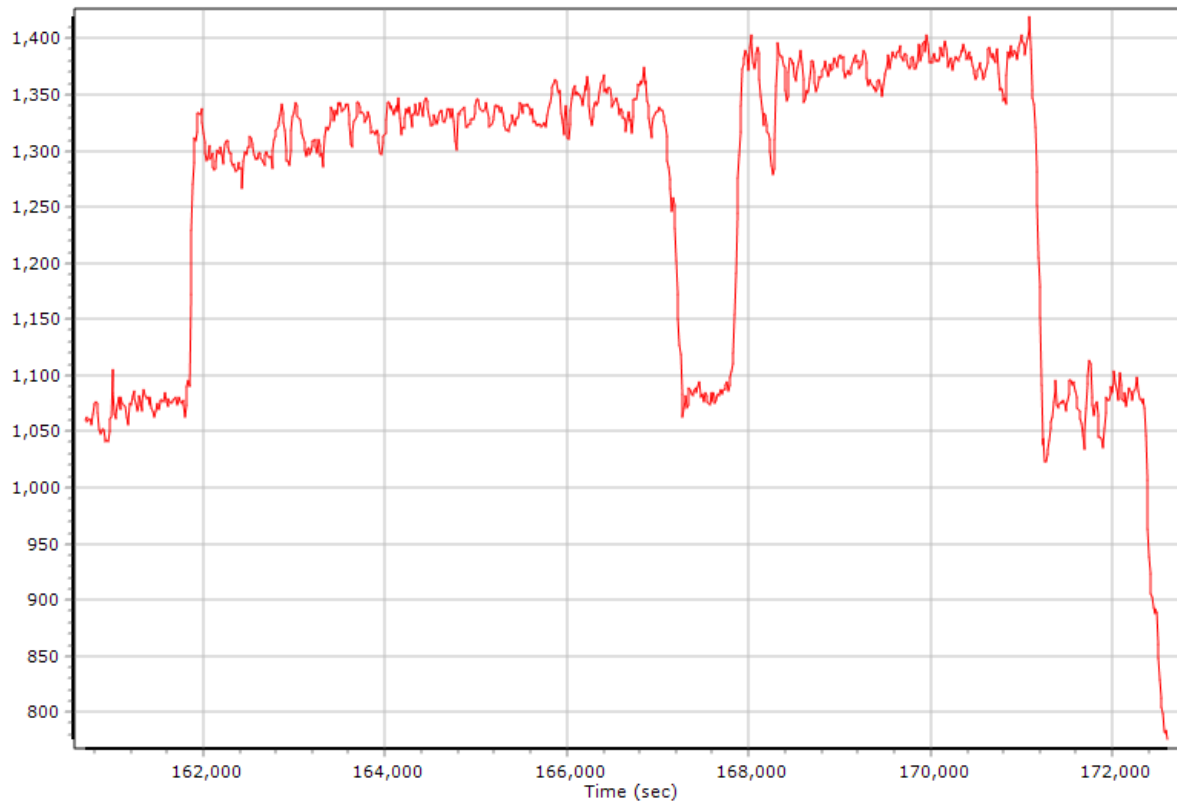


— x accelerometer bias (micro-g) — y accelerometer bias (micro-g) — z accelerometer bias (micro-g)

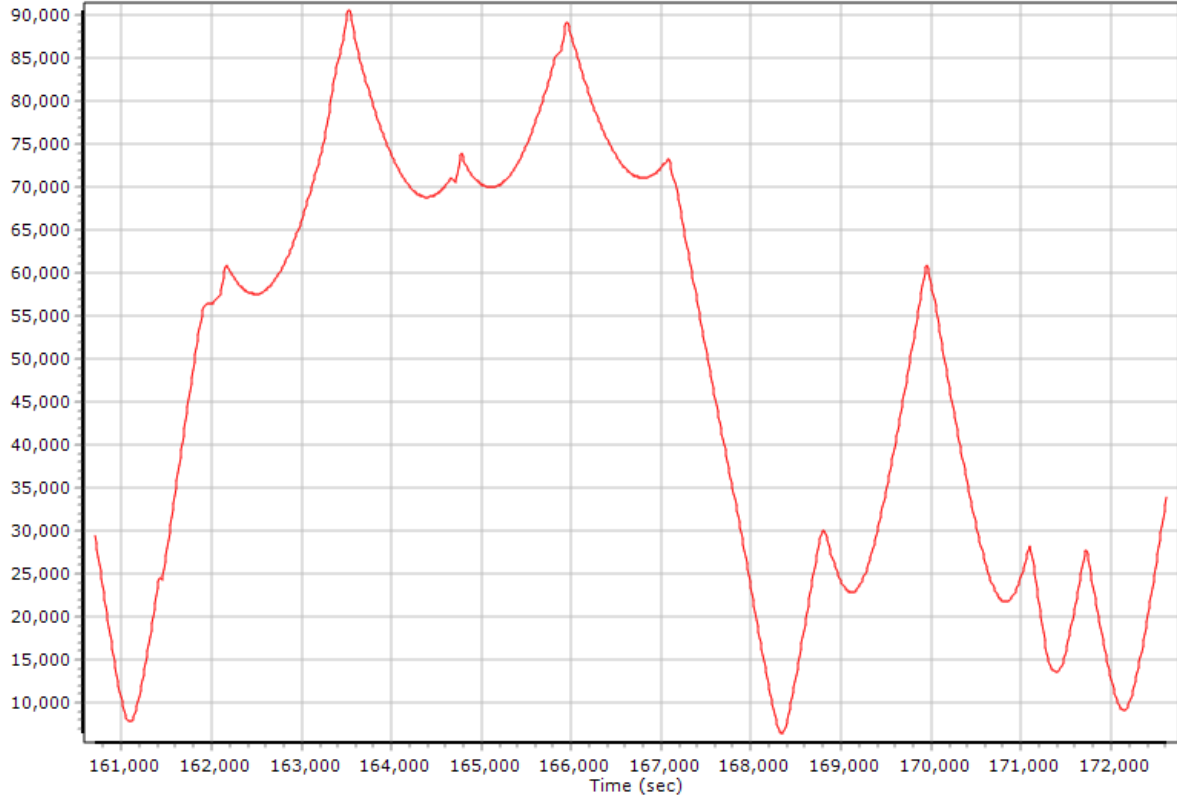


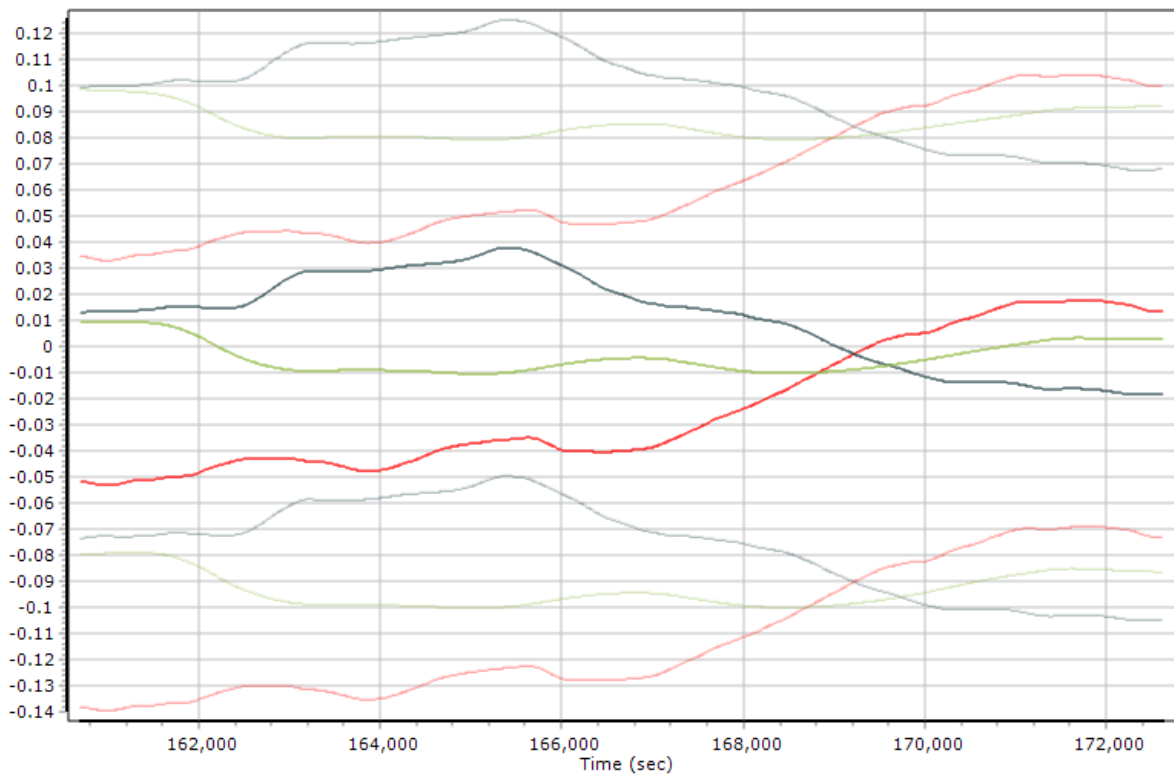
— x accelerometer scale error (ppm) — y accelerometer scale error (ppm) — z accelerometer scale error (ppm)

Altitude (m)

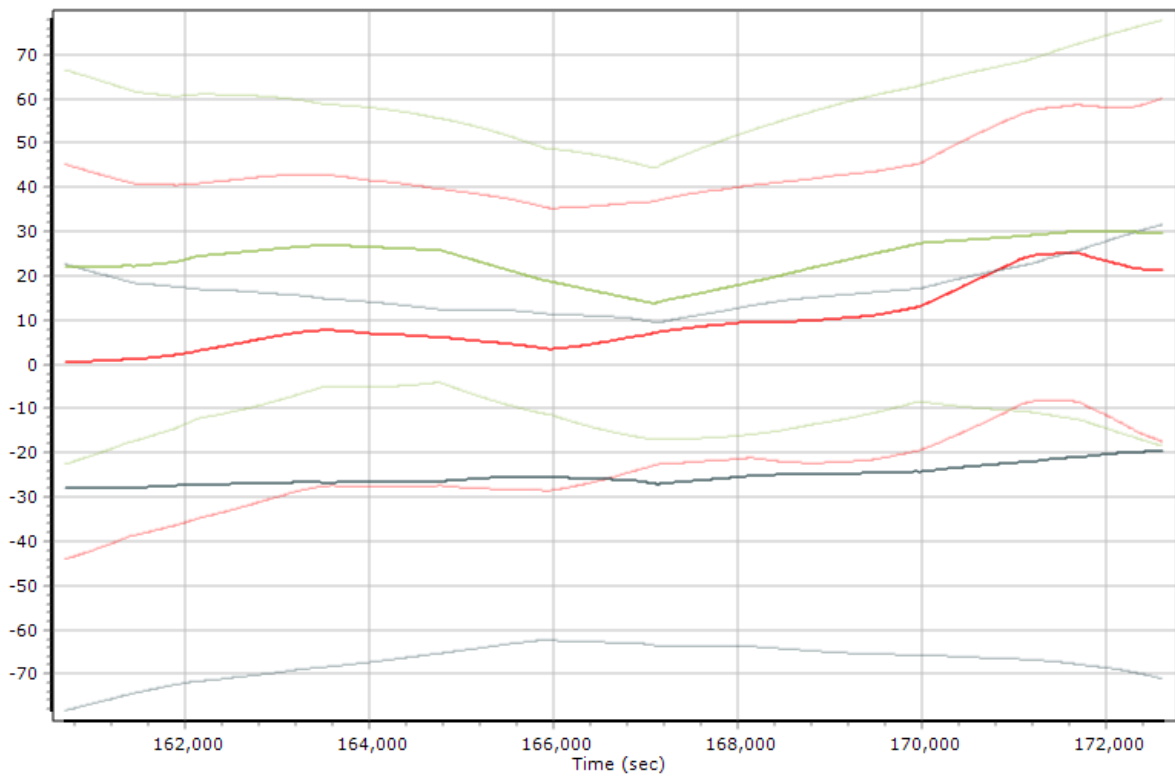


Baseline Length(m)





— x gyro bias (deg/hr) — y gyro bias (deg/hr) — z gyro bias (deg/hr)



x gyro scale error (ppm) y gyro scale error (ppm) z gyro scale error (ppm)

Stabilized Mount to IMU Lever Arm

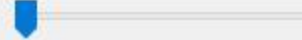
X
Y
Z

Stabilized Mount to IMU Mounting Angles

X
Y
Z

Stabilized Mount to Primary GNSS Lever Arm

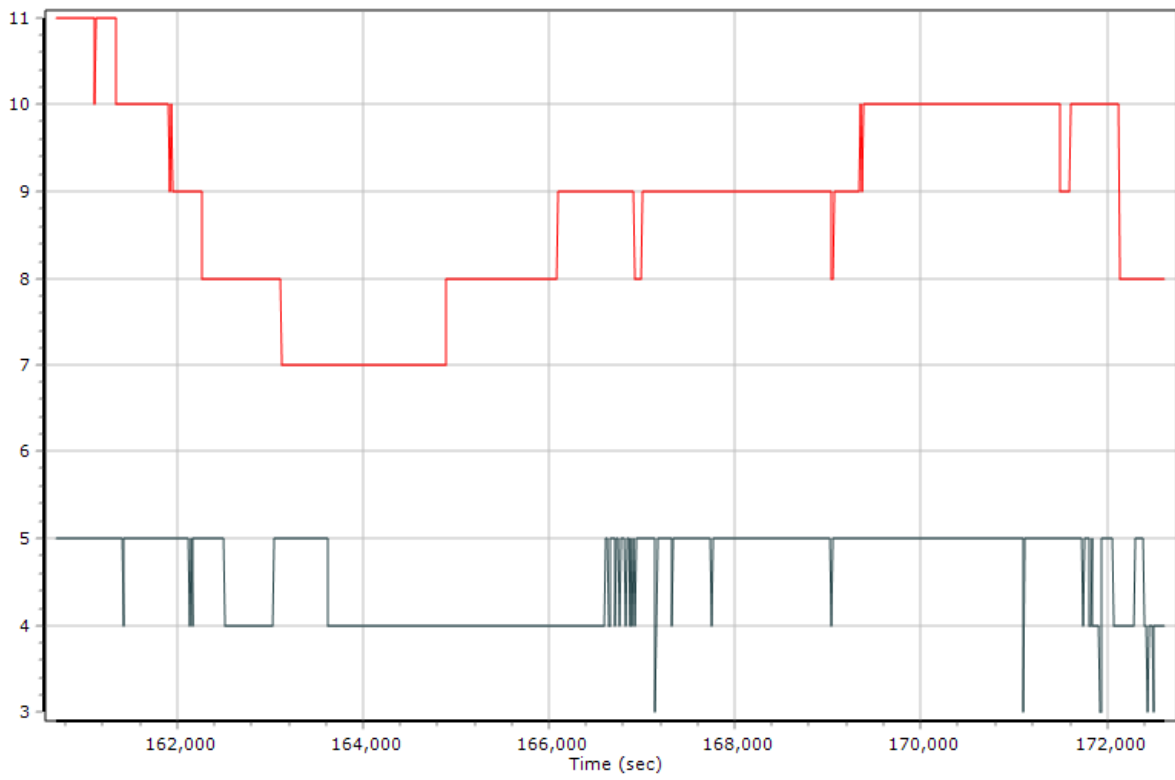
X
Y
Z

Standard Deviation 
<3cm 10cm 50cm 1m 10m

Aircraft to Stabilized Mount Mounting Angles

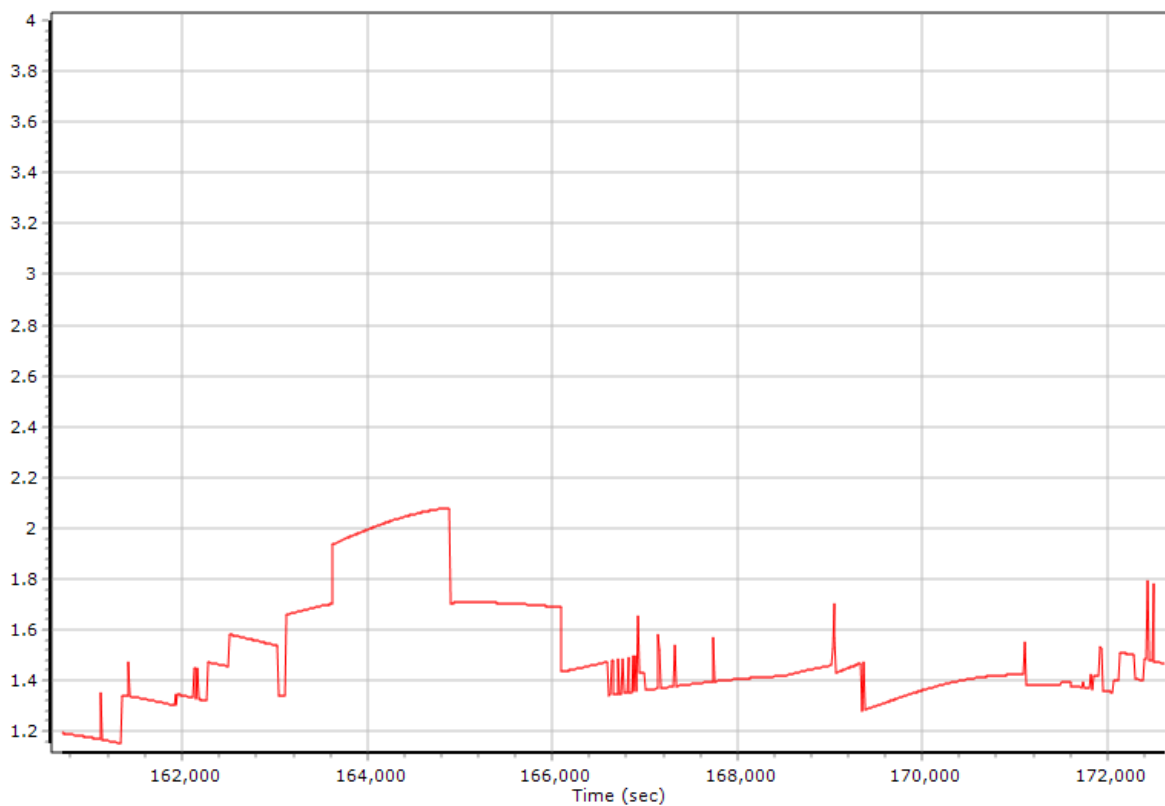
X
Y
Z

Measurements are to the stabilized platform's center of rotation with the Gimbal in the rest position.

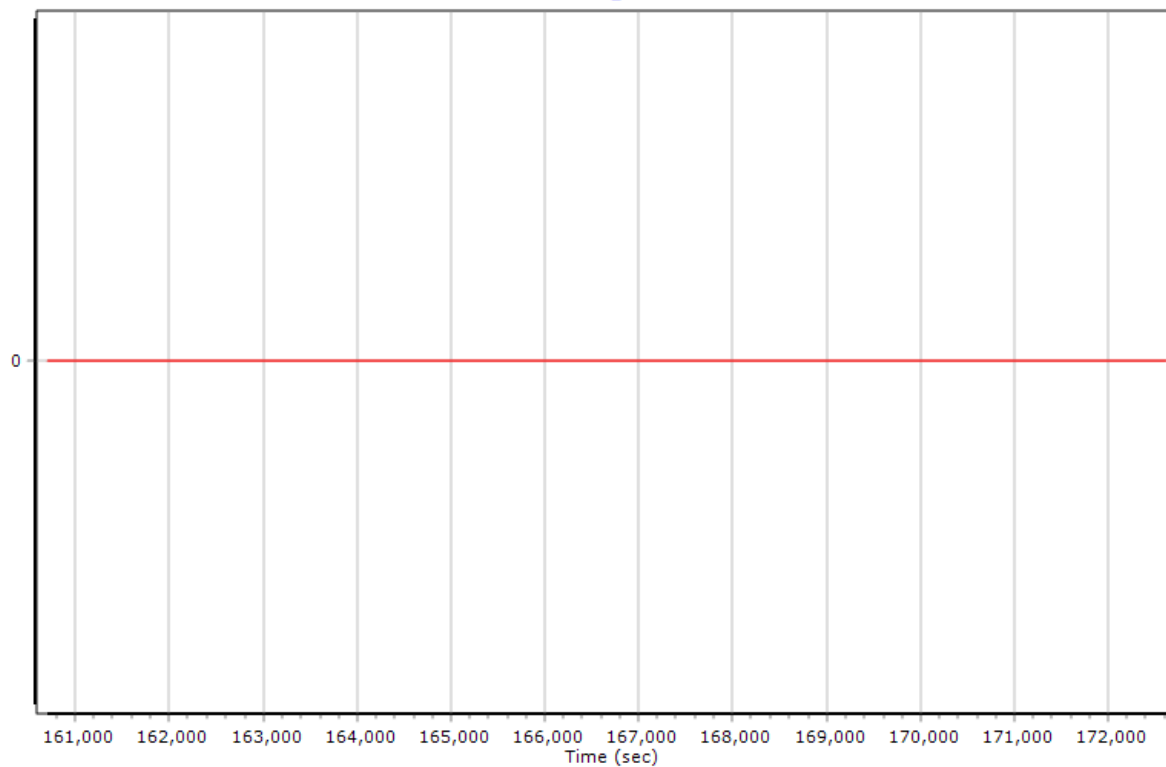


— Number of GPS Satellites — Number of GLONASS Satellites

PDOP

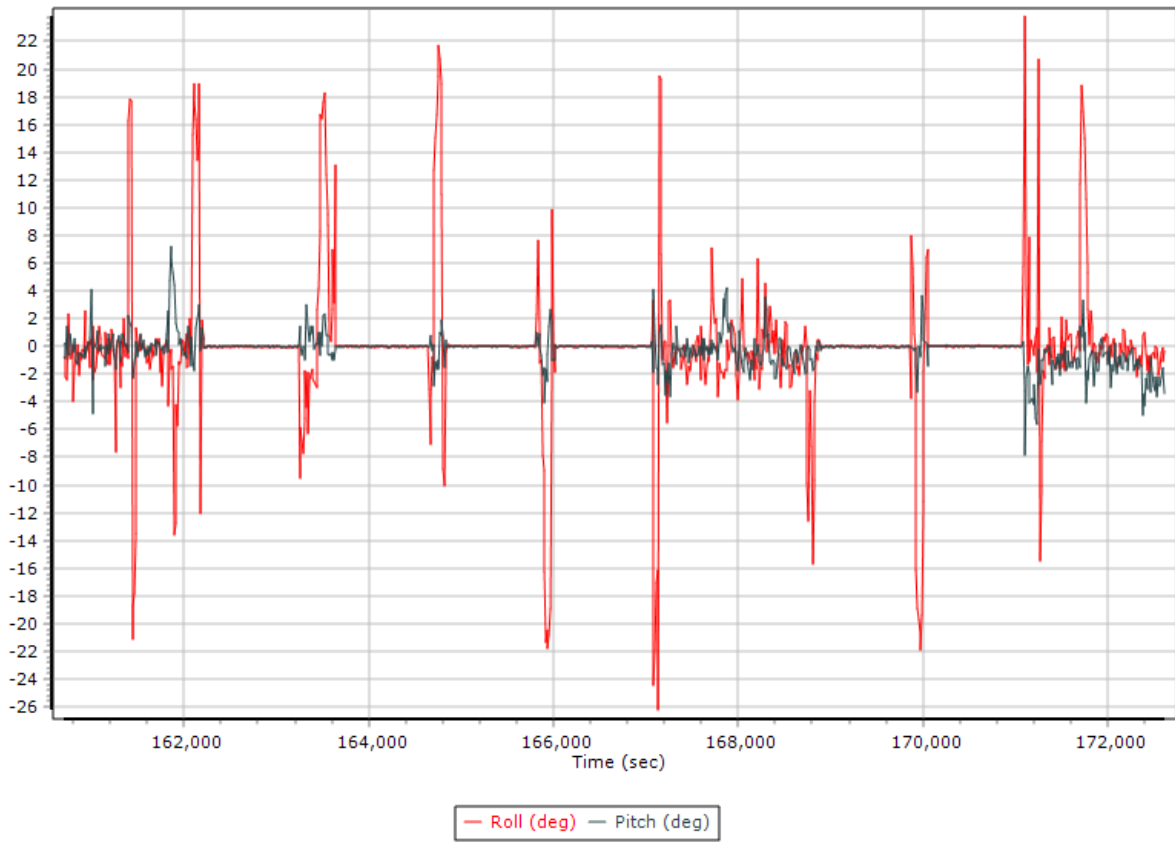


Processing Mode



0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = C/A, 7 = GNSS Nav, 8 = DR





Disable Satellites

GPS GLONASS BEIDOU QZSS

- | | | |
|---------------------------------|----------------------------------|----------------------------------|
| <input type="checkbox"/> SLOT 1 | <input type="checkbox"/> SLOT 10 | <input type="checkbox"/> SLOT 19 |
| <input type="checkbox"/> SLOT 2 | <input type="checkbox"/> SLOT 11 | <input type="checkbox"/> SLOT 20 |
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| <input type="checkbox"/> SLOT 4 | <input type="checkbox"/> SLOT 13 | <input type="checkbox"/> SLOT 22 |
| <input type="checkbox"/> SLOT 5 | <input type="checkbox"/> SLOT 14 | <input type="checkbox"/> SLOT 23 |
| <input type="checkbox"/> SLOT 6 | <input type="checkbox"/> SLOT 15 | <input type="checkbox"/> SLOT 24 |
| <input type="checkbox"/> SLOT 7 | <input type="checkbox"/> SLOT 16 | |
| <input type="checkbox"/> SLOT 8 | <input type="checkbox"/> SLOT 17 | |
| <input type="checkbox"/> SLOT 9 | <input type="checkbox"/> SLOT 18 | |

Elevation Mask Angle

Force GPS Only

Disable Satellites

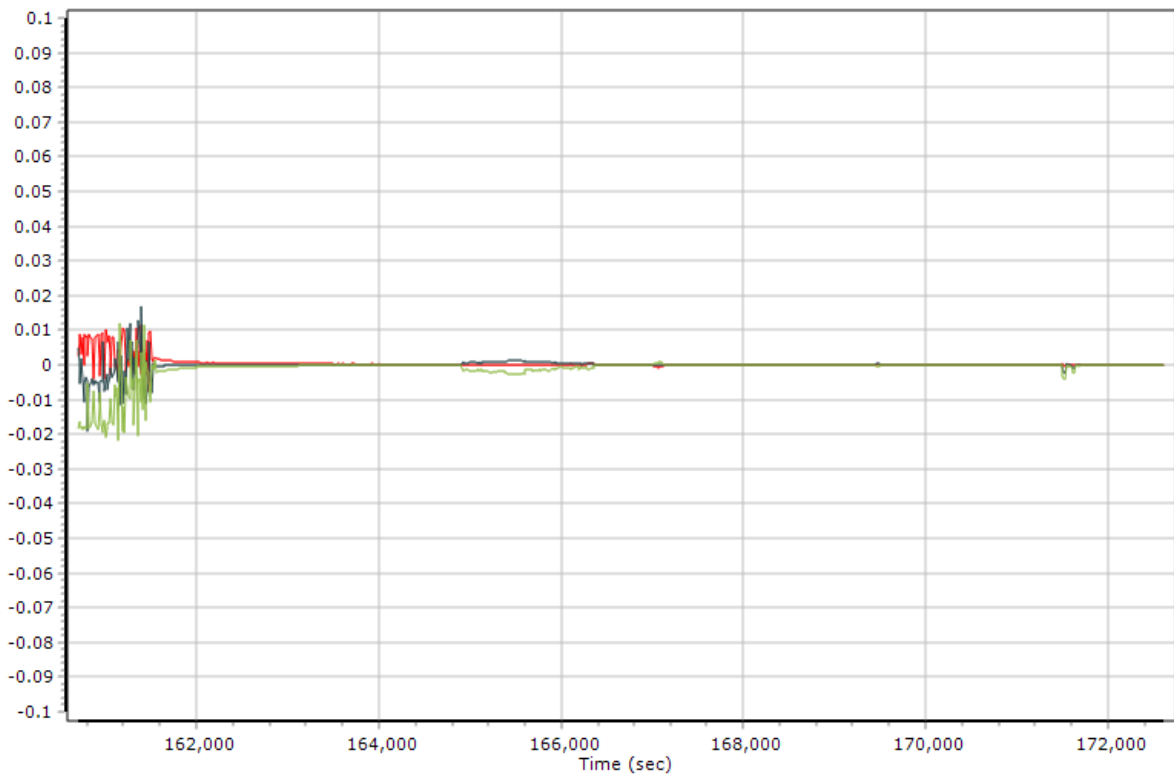
GPS GLONASS BEIDOU QZSS

- | | | | |
|--------------------------------|---------------------------------|---------------------------------|---------------------------------|
| <input type="checkbox"/> PRN 1 | <input type="checkbox"/> PRN 10 | <input type="checkbox"/> PRN 19 | <input type="checkbox"/> PRN 28 |
| <input type="checkbox"/> PRN 2 | <input type="checkbox"/> PRN 11 | <input type="checkbox"/> PRN 20 | <input type="checkbox"/> PRN 29 |
| <input type="checkbox"/> PRN 3 | <input type="checkbox"/> PRN 12 | <input type="checkbox"/> PRN 21 | <input type="checkbox"/> PRN 30 |
| <input type="checkbox"/> PRN 4 | <input type="checkbox"/> PRN 13 | <input type="checkbox"/> PRN 22 | <input type="checkbox"/> PRN 31 |
| <input type="checkbox"/> PRN 5 | <input type="checkbox"/> PRN 14 | <input type="checkbox"/> PRN 23 | <input type="checkbox"/> PRN 32 |
| <input type="checkbox"/> PRN 6 | <input type="checkbox"/> PRN 15 | <input type="checkbox"/> PRN 24 | |
| <input type="checkbox"/> PRN 7 | <input type="checkbox"/> PRN 16 | <input type="checkbox"/> PRN 25 | |
| <input type="checkbox"/> PRN 8 | <input type="checkbox"/> PRN 17 | <input type="checkbox"/> PRN 26 | |
| <input type="checkbox"/> PRN 9 | <input type="checkbox"/> PRN 18 | <input type="checkbox"/> PRN 27 | |



Elevation Mask Angle

Force GPS Only



— North (m) — East (m) — Down (m) — DR mode

Timing

Start

End

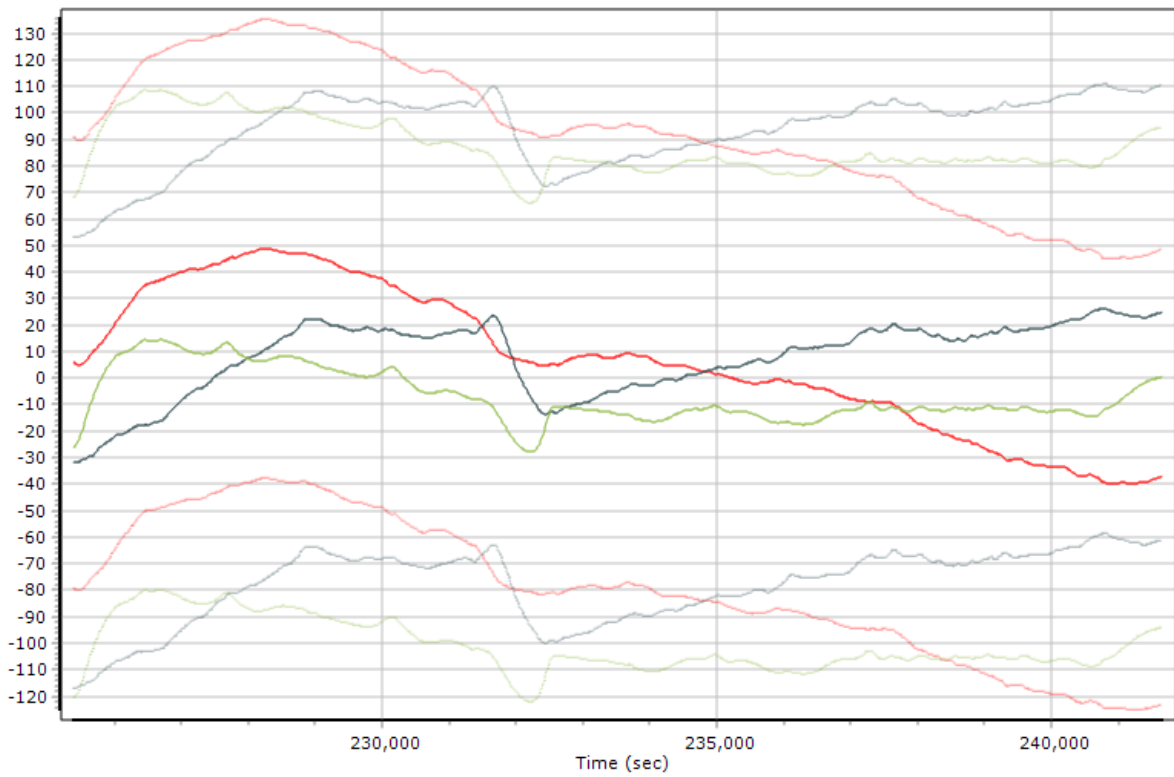
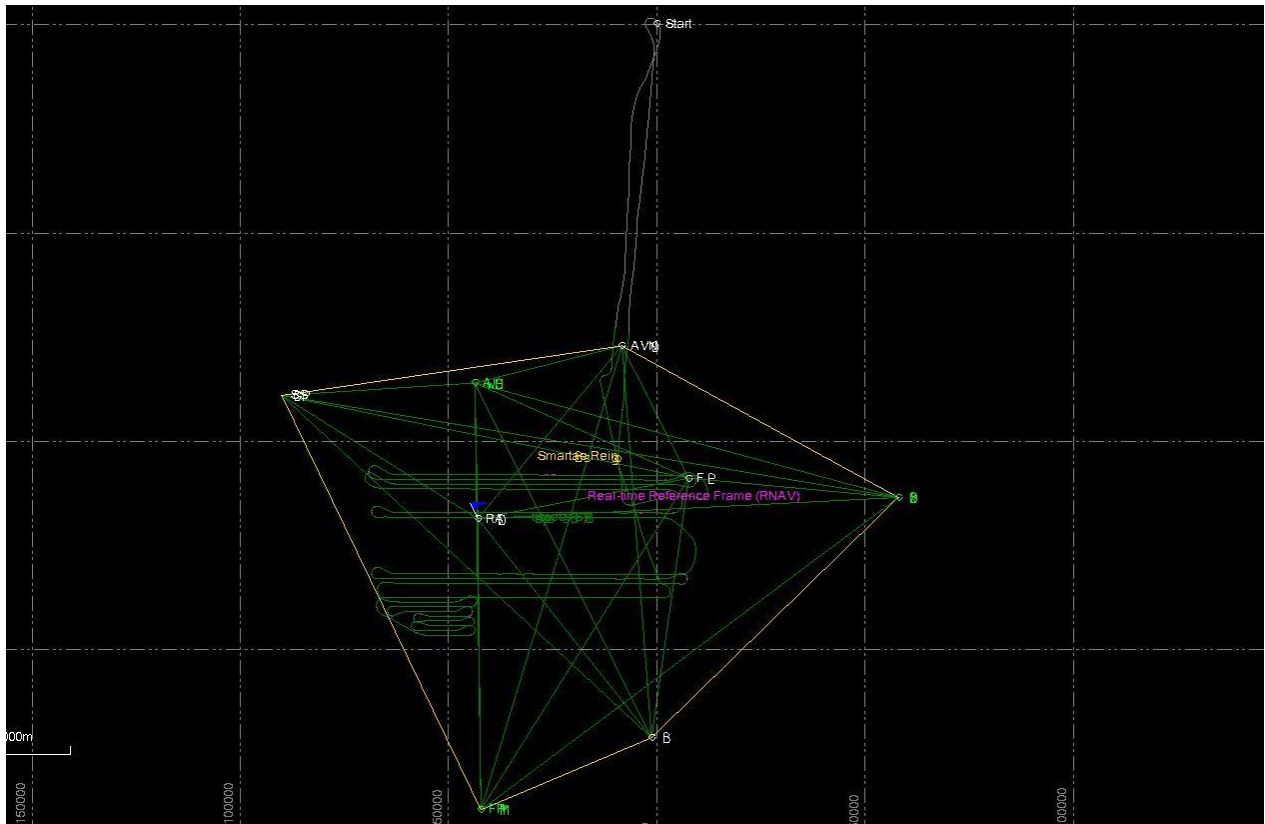
Entire time interval

Seconds of start week

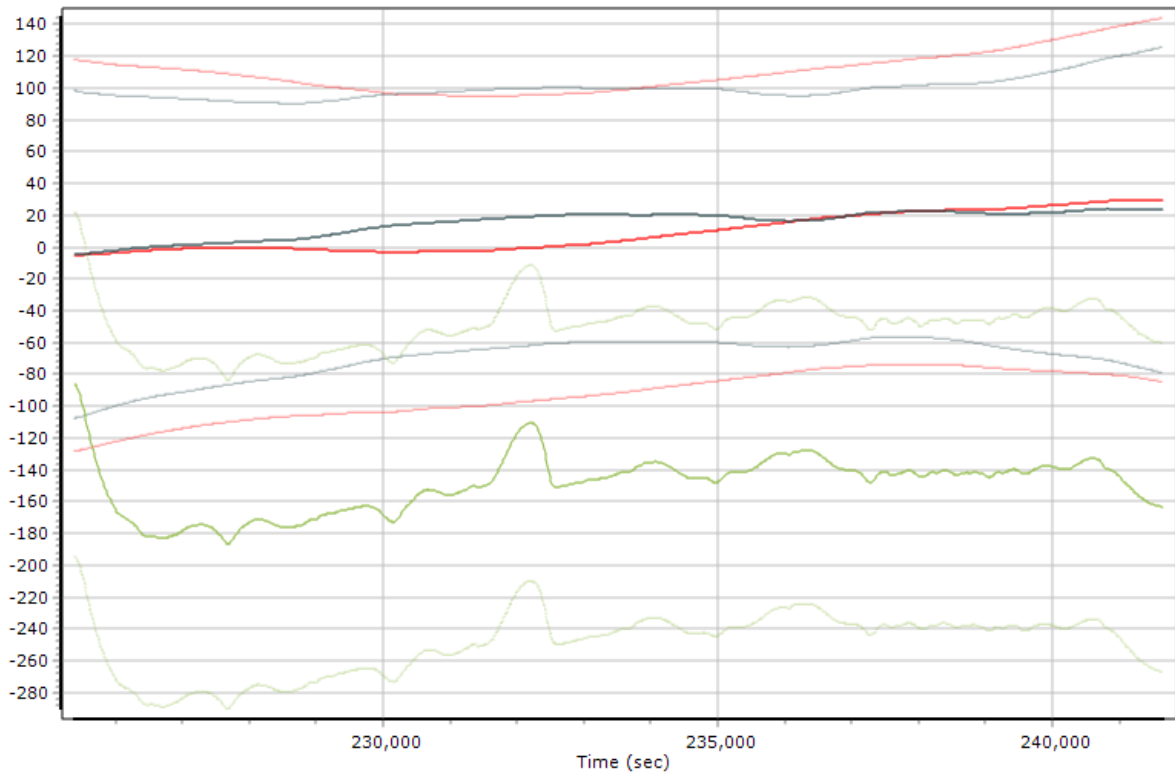
UTC Offset

Data	Incr. (sec)
Output Record	0.005000
IMU	0.005000
Primary GNSS	1.000000

MISSION: 45A18352A

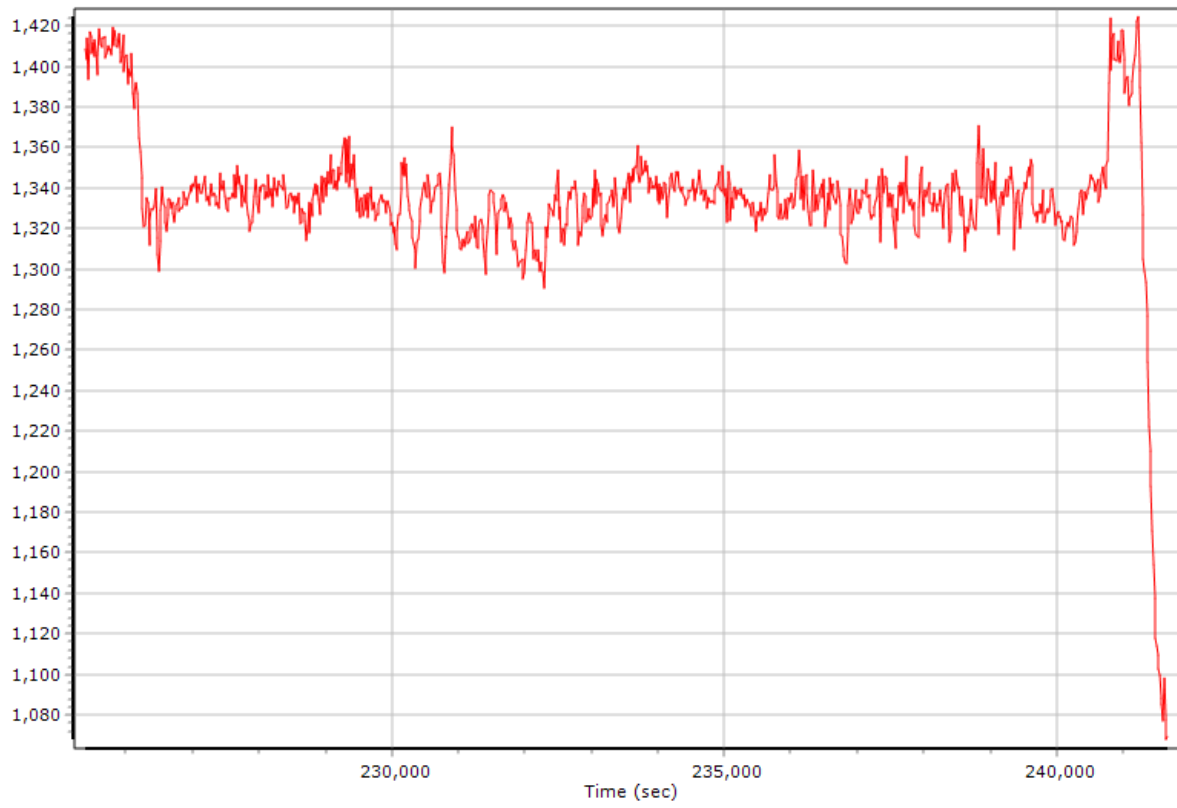


— x accelerometer bias (micro-g) — y accelerometer bias (micro-g) — z accelerometer bias (micro-g)

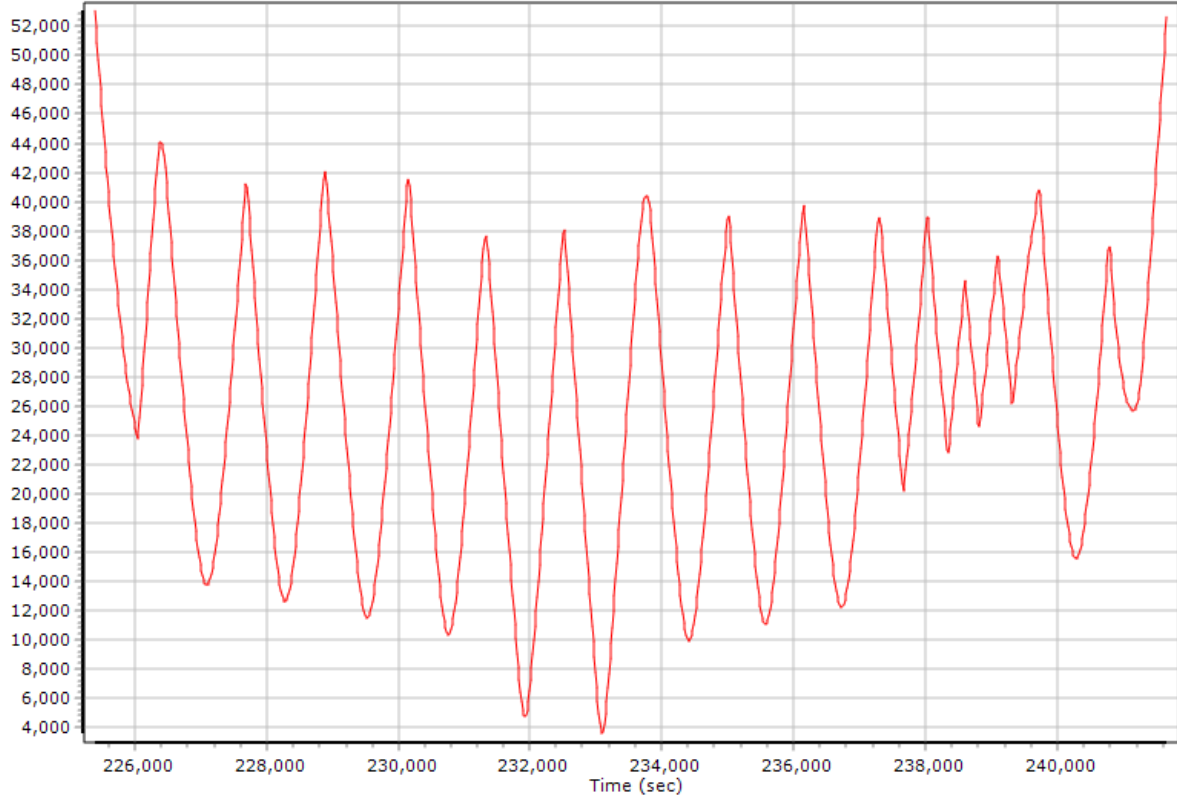


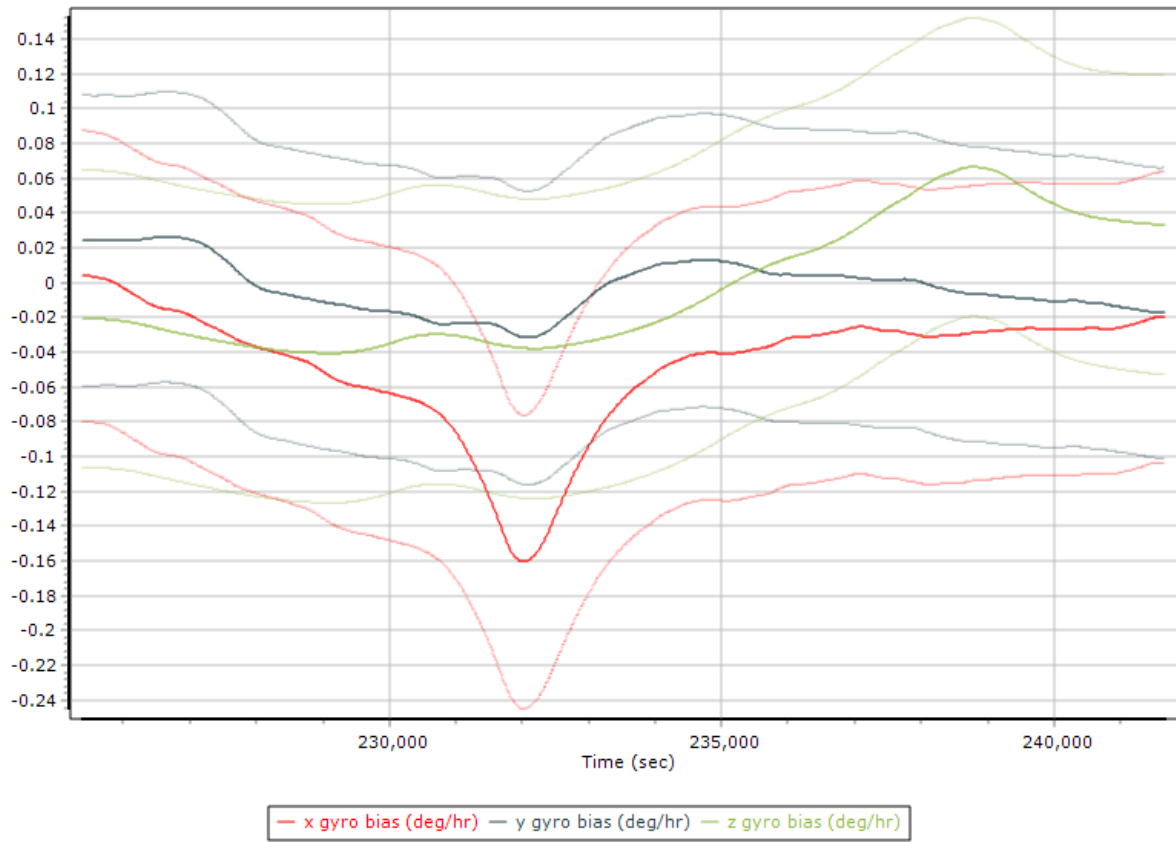
— x accelerometer scale error (ppm) — y accelerometer scale error (ppm) — z accelerometer scale error (ppm)

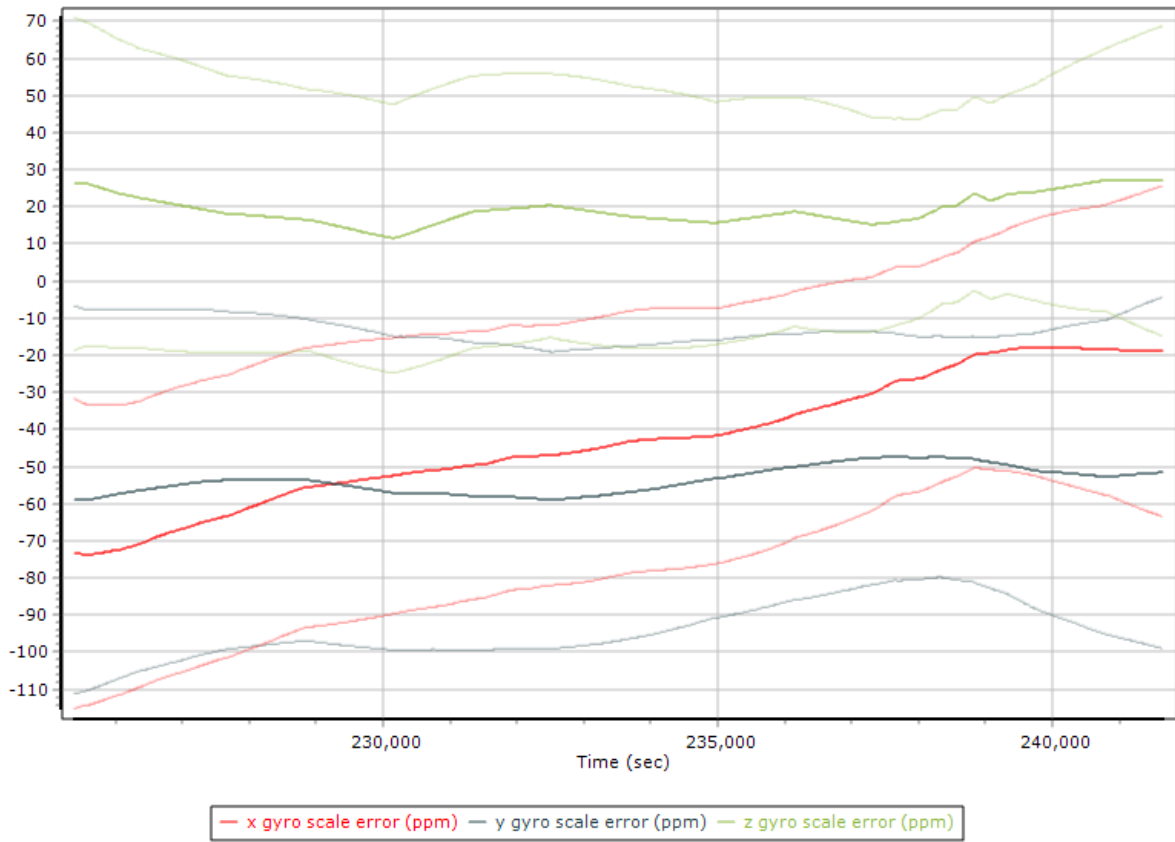
Altitude (m)



Baseline Length(m)







Stabilized Mount to IMU Lever Arm

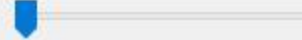
X
Y
Z

Stabilized Mount to IMU Mounting Angles

X
Y
Z

Stabilized Mount to Primary GNSS Lever Arm

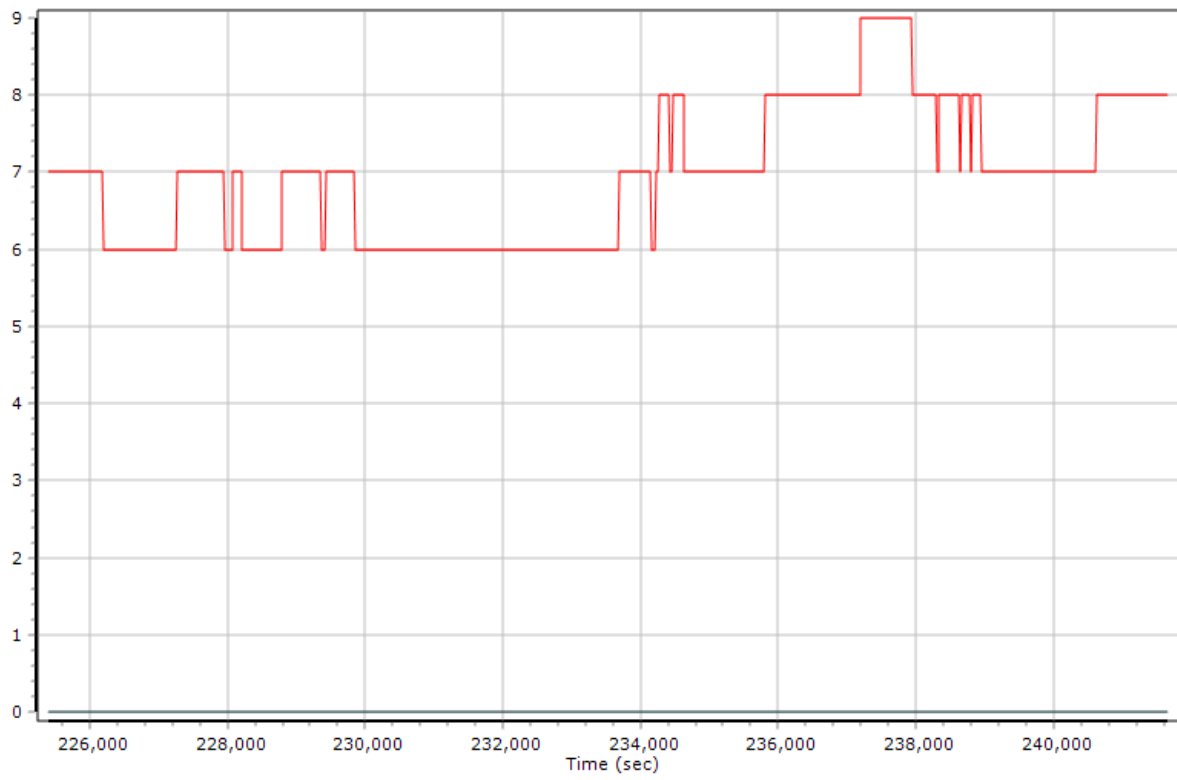
X
Y
Z

Standard Deviation 
<3cm 10cm 50cm 1m 10m

Aircraft to Stabilized Mount Mounting Angles

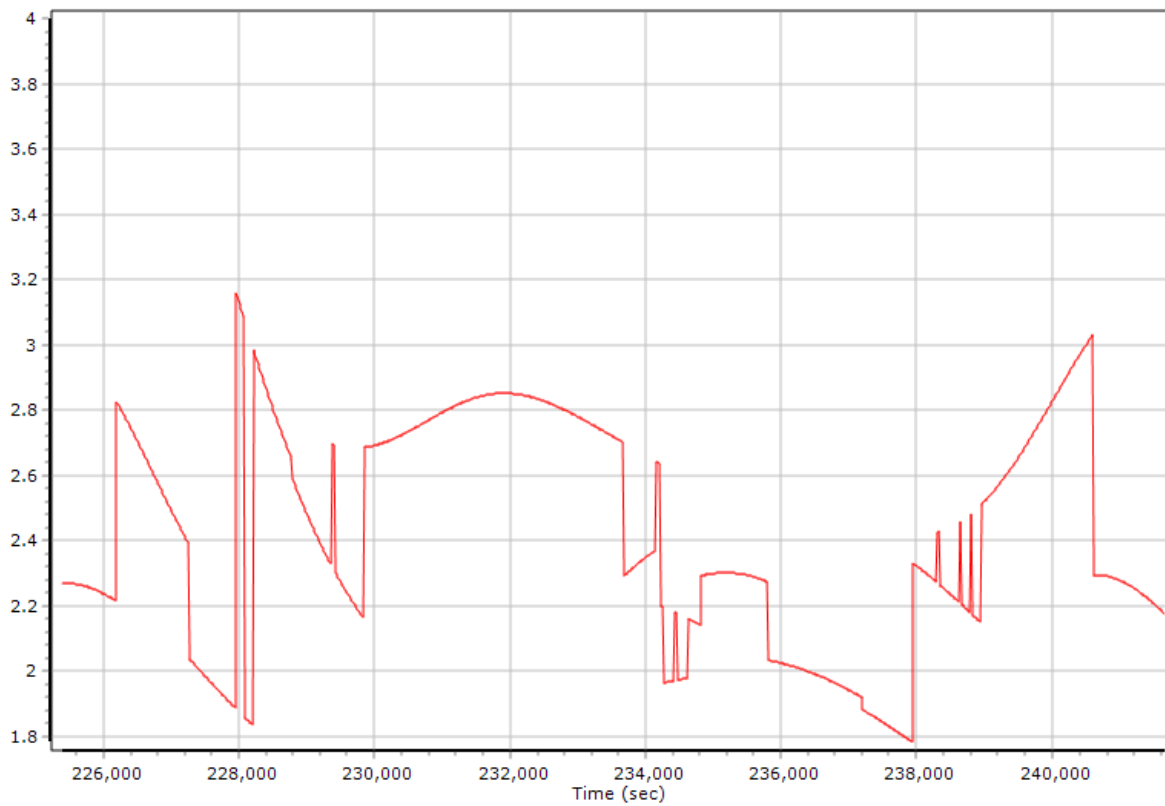
X
Y
Z

Measurements are to the stabilized platform's center of rotation with the Gimbal in the rest position.

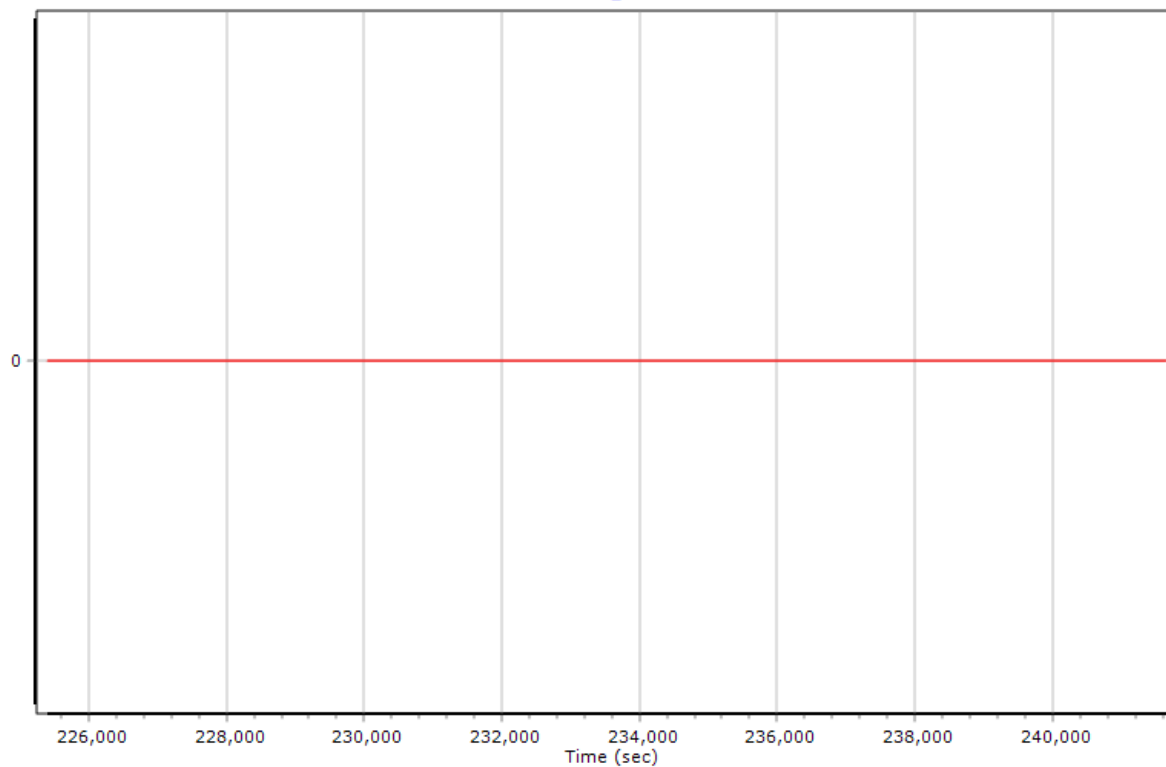


— Number of GPS Satellites — Number of GLONASS Satellites

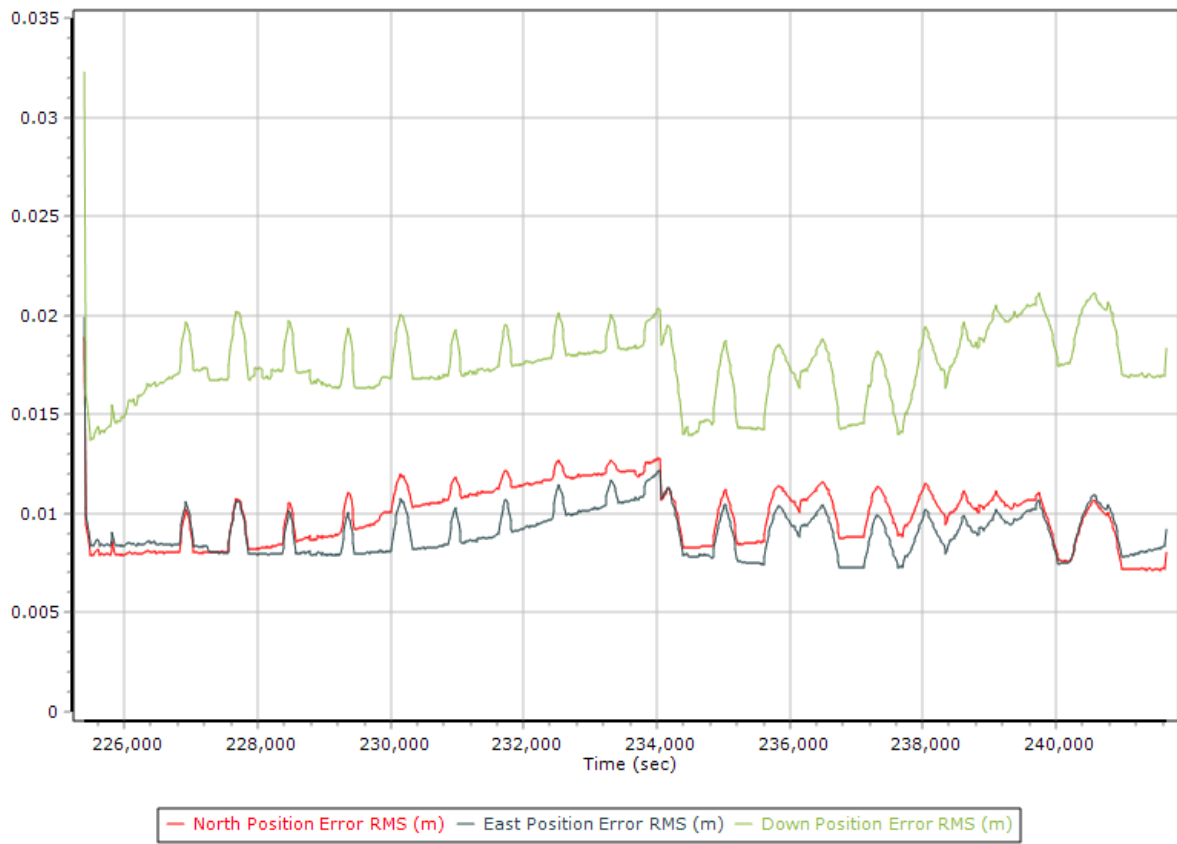
PDOP

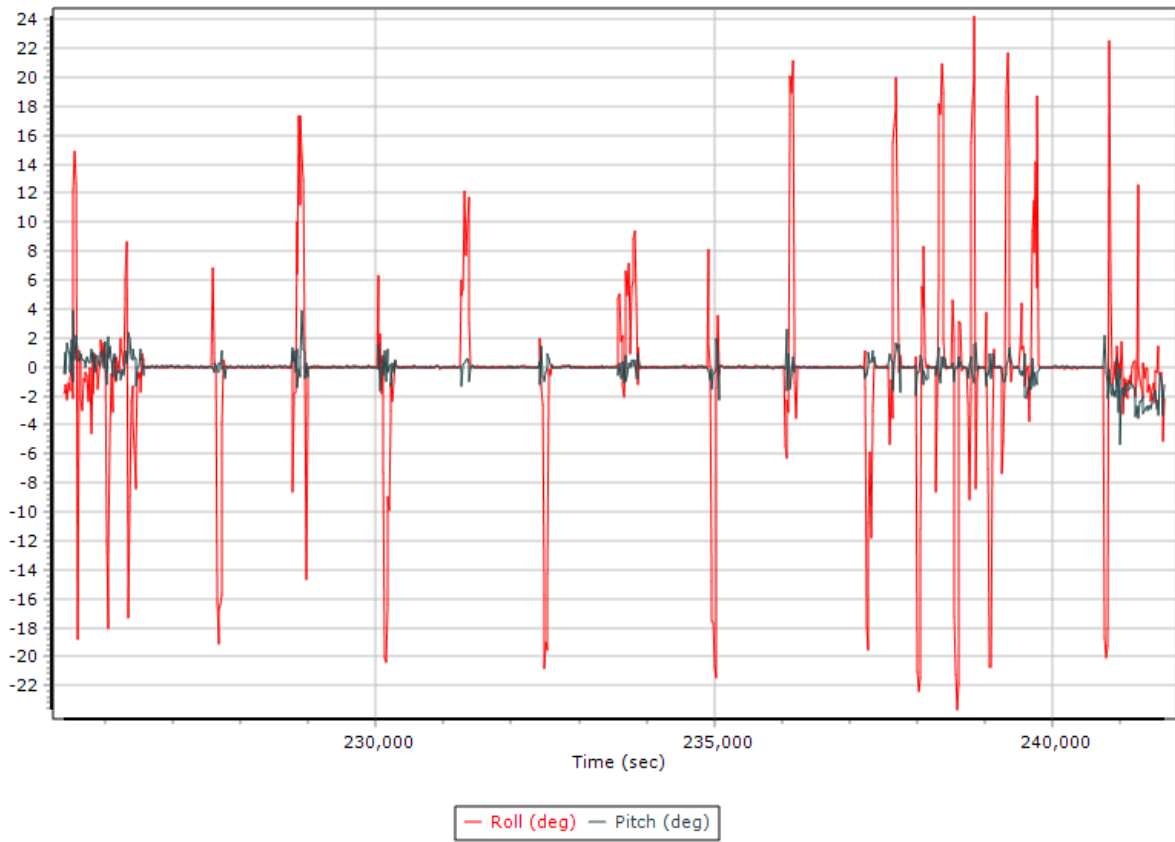


Processing Mode



0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = C/A, 7 = GNSS Nav, 8 = DR





Disable Satellites

GPS GLONASS BEIDOU QZSS

- | | | |
|---------------------------------|----------------------------------|----------------------------------|
| <input type="checkbox"/> SLOT 1 | <input type="checkbox"/> SLOT 10 | <input type="checkbox"/> SLOT 19 |
| <input type="checkbox"/> SLOT 2 | <input type="checkbox"/> SLOT 11 | <input type="checkbox"/> SLOT 20 |
| <input type="checkbox"/> SLOT 3 | <input type="checkbox"/> SLOT 12 | <input type="checkbox"/> SLOT 21 |
| <input type="checkbox"/> SLOT 4 | <input type="checkbox"/> SLOT 13 | <input type="checkbox"/> SLOT 22 |
| <input type="checkbox"/> SLOT 5 | <input type="checkbox"/> SLOT 14 | <input type="checkbox"/> SLOT 23 |
| <input type="checkbox"/> SLOT 6 | <input type="checkbox"/> SLOT 15 | <input type="checkbox"/> SLOT 24 |
| <input type="checkbox"/> SLOT 7 | <input type="checkbox"/> SLOT 16 | |
| <input type="checkbox"/> SLOT 8 | <input type="checkbox"/> SLOT 17 | |
| <input type="checkbox"/> SLOT 9 | <input type="checkbox"/> SLOT 18 | |

Elevation Mask Angle

Force GPS Only

Disable Satellites

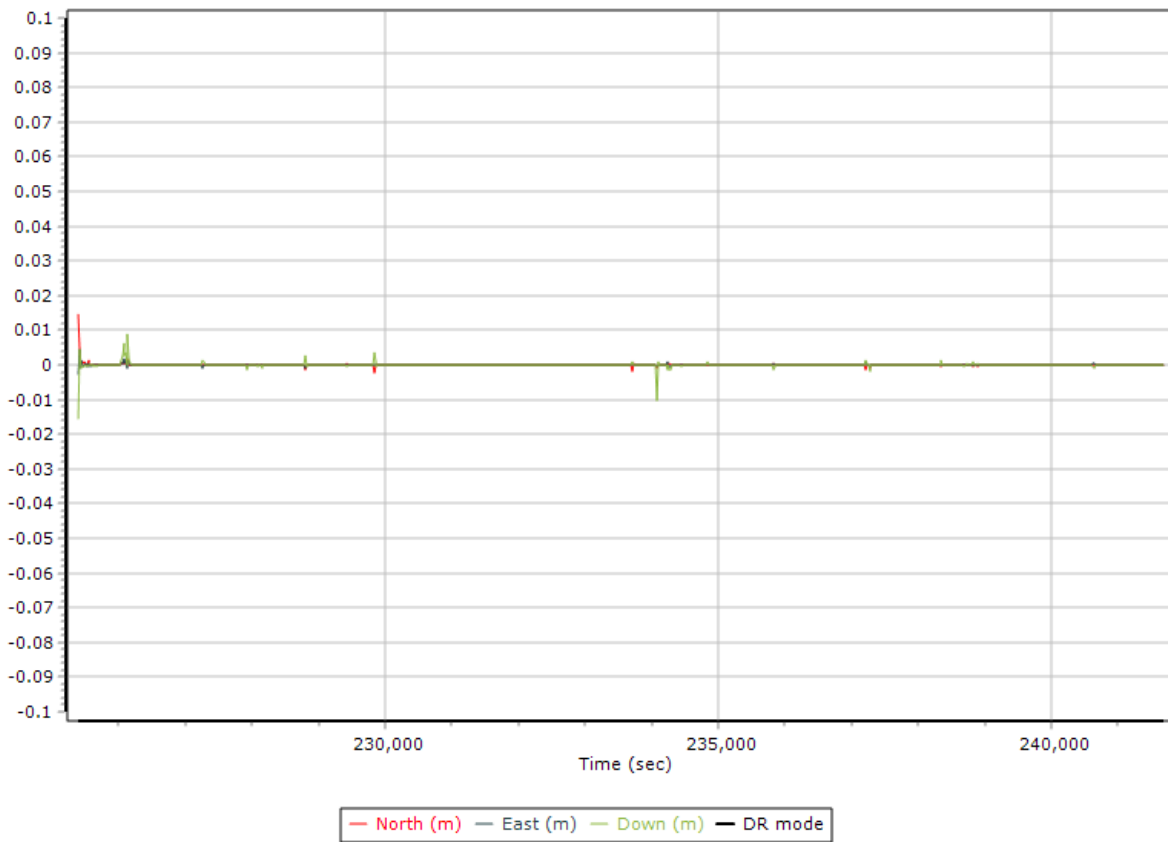
GPS GLONASS BEIDOU QZSS

- | | | | |
|--------------------------------|---------------------------------|---------------------------------|---------------------------------|
| <input type="checkbox"/> PRN 1 | <input type="checkbox"/> PRN 10 | <input type="checkbox"/> PRN 19 | <input type="checkbox"/> PRN 28 |
| <input type="checkbox"/> PRN 2 | <input type="checkbox"/> PRN 11 | <input type="checkbox"/> PRN 20 | <input type="checkbox"/> PRN 29 |
| <input type="checkbox"/> PRN 3 | <input type="checkbox"/> PRN 12 | <input type="checkbox"/> PRN 21 | <input type="checkbox"/> PRN 30 |
| <input type="checkbox"/> PRN 4 | <input type="checkbox"/> PRN 13 | <input type="checkbox"/> PRN 22 | <input type="checkbox"/> PRN 31 |
| <input type="checkbox"/> PRN 5 | <input type="checkbox"/> PRN 14 | <input type="checkbox"/> PRN 23 | <input type="checkbox"/> PRN 32 |
| <input type="checkbox"/> PRN 6 | <input type="checkbox"/> PRN 15 | <input type="checkbox"/> PRN 24 | |
| <input type="checkbox"/> PRN 7 | <input type="checkbox"/> PRN 16 | <input type="checkbox"/> PRN 25 | |
| <input type="checkbox"/> PRN 8 | <input type="checkbox"/> PRN 17 | <input type="checkbox"/> PRN 26 | |
| <input type="checkbox"/> PRN 9 | <input type="checkbox"/> PRN 18 | <input type="checkbox"/> PRN 27 | |



Elevation Mask Angle

Force GPS Only



Timing

Start

End

Entire time interval

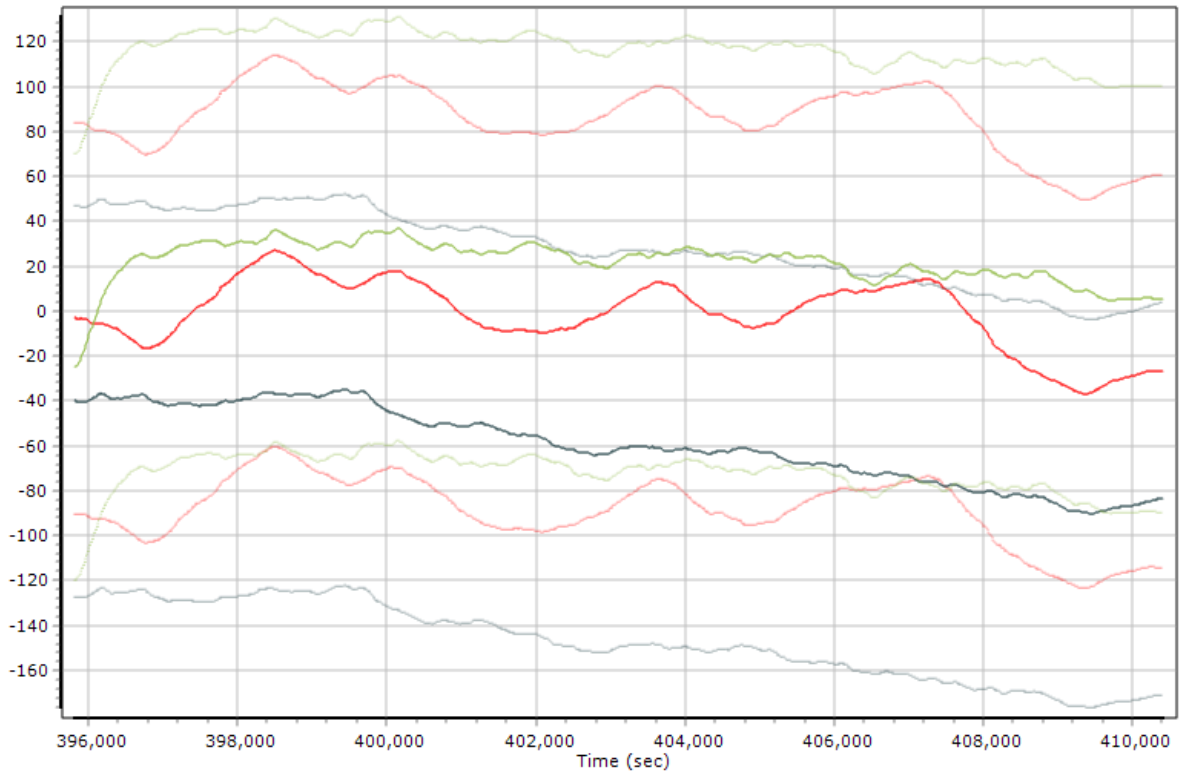
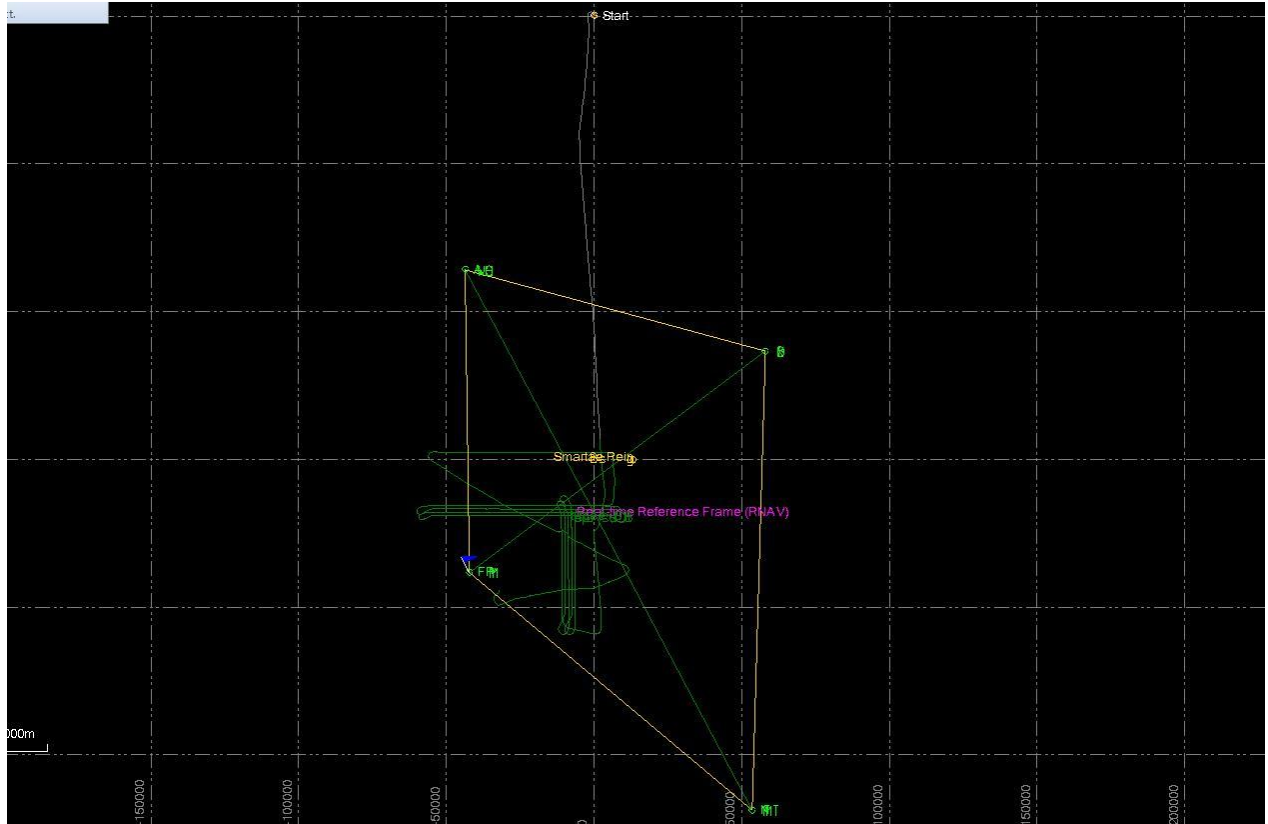
Seconds of start week

UTC Offset

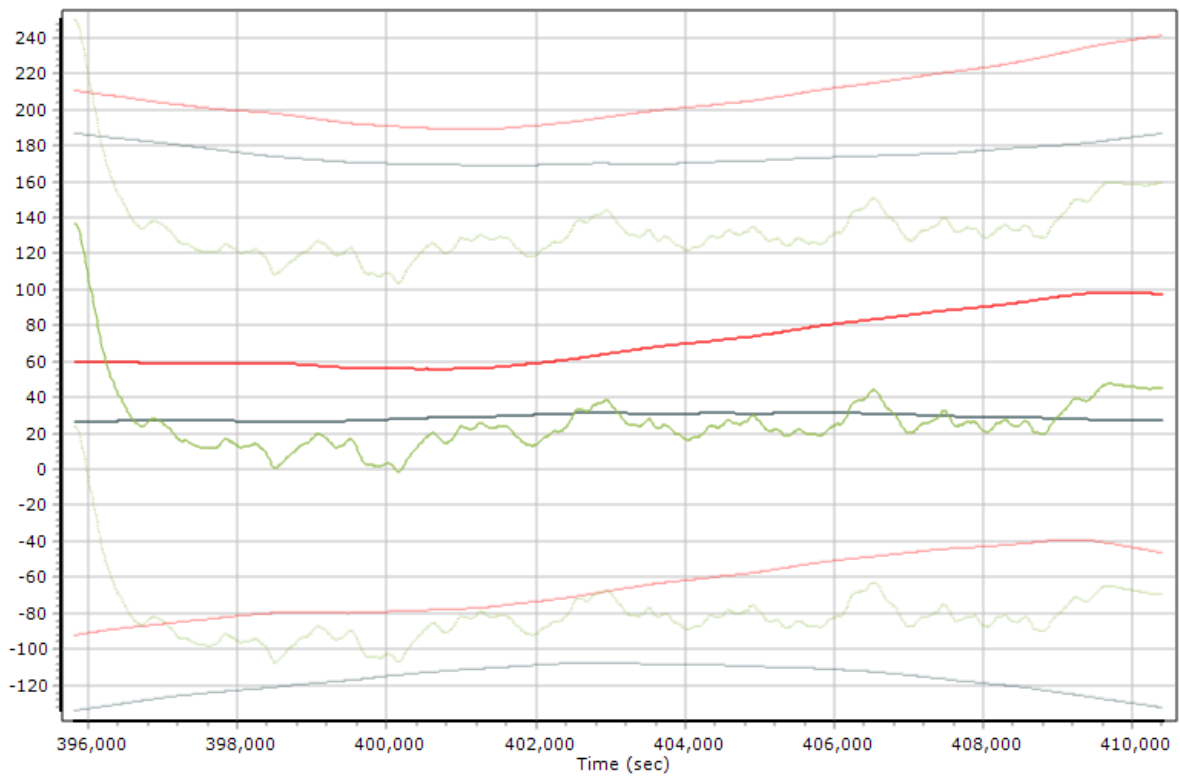
Data	Incr. (sec)
Output Record	0.005000
IMU	0.005000
Primary GNSS	1.000000



MISSION: PTG19010A

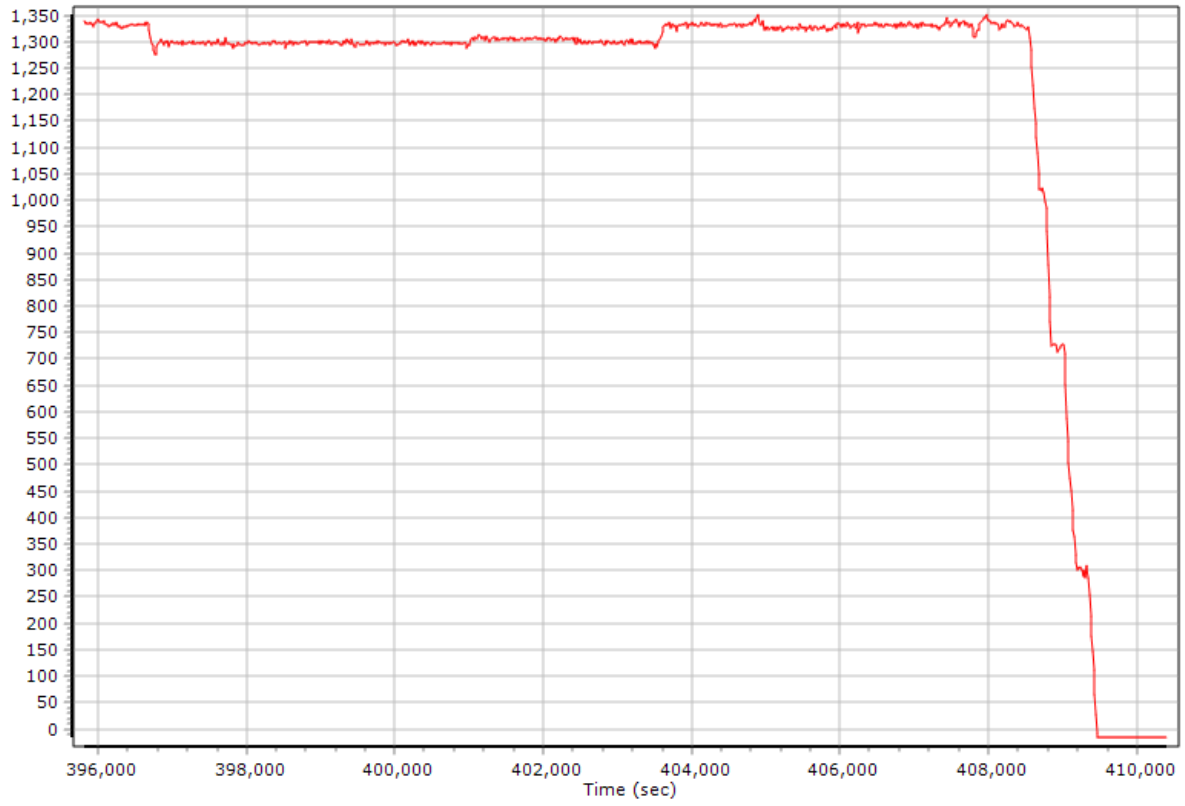


— x accelerometer bias (micro-g) — y accelerometer bias (micro-g) — z accelerometer bias (micro-g)

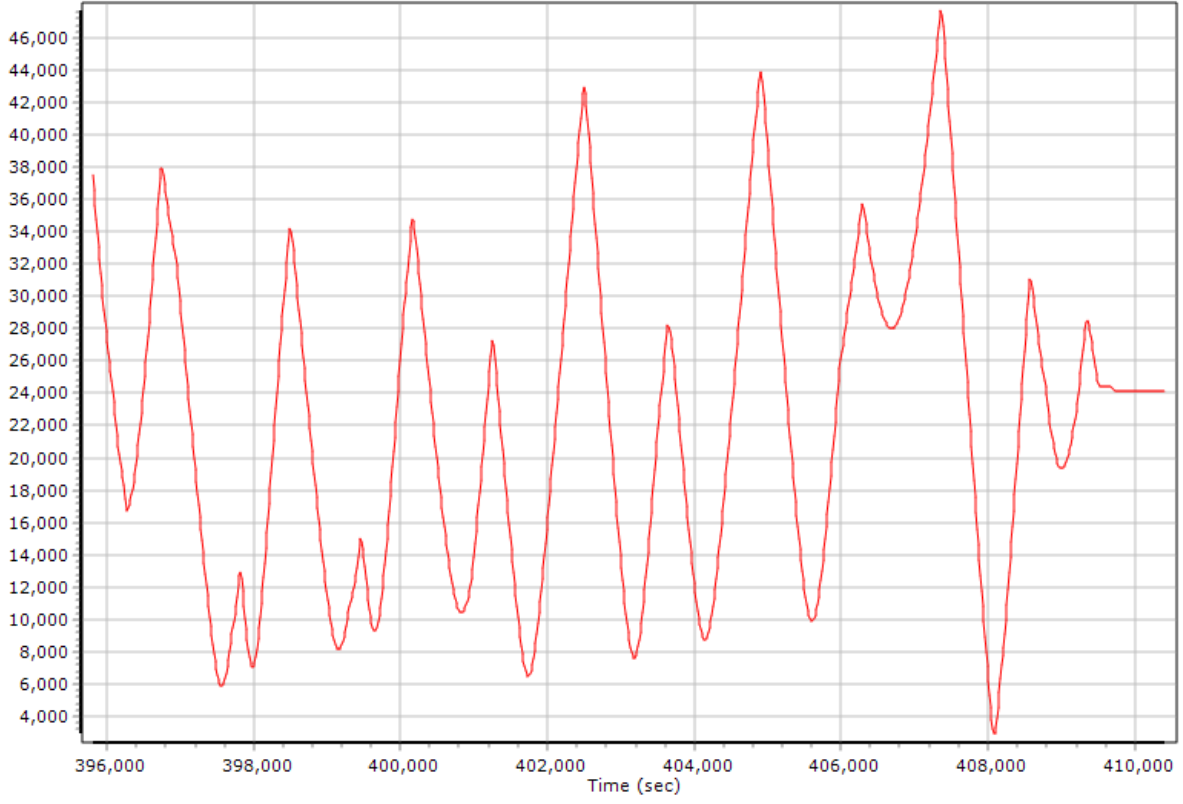


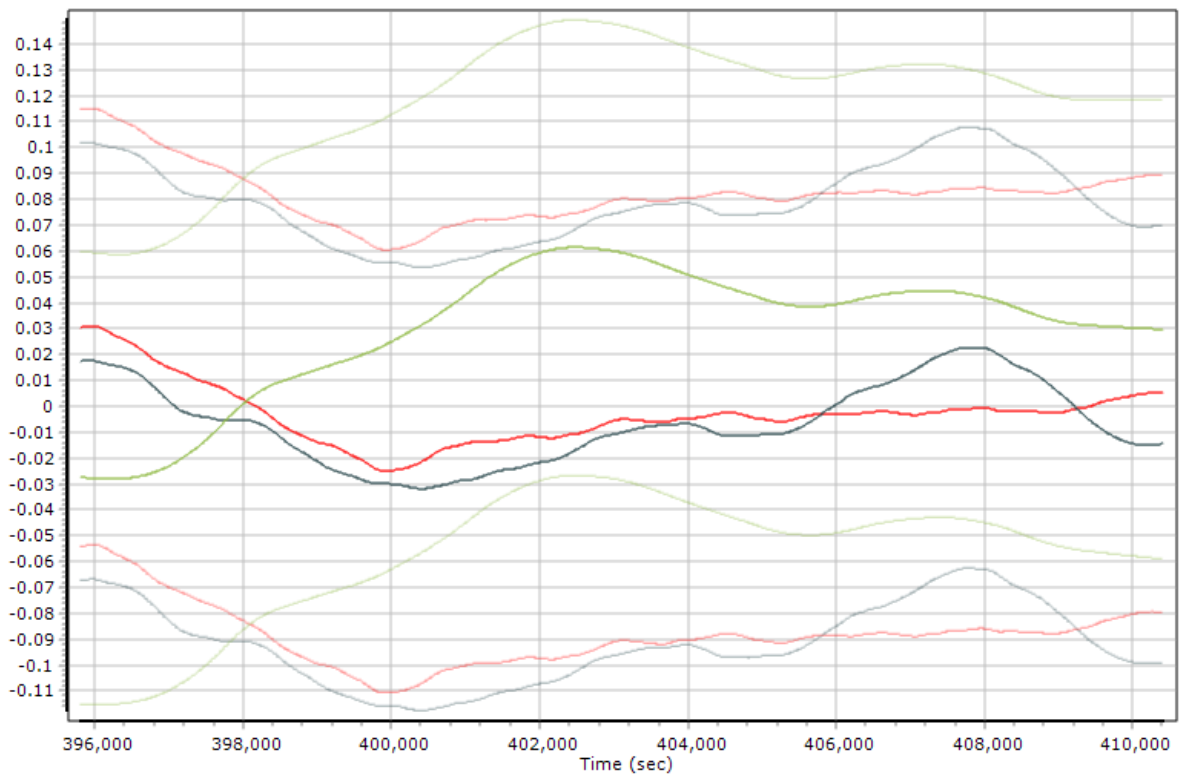
— x accelerometer scale error (ppm) — y accelerometer scale error (ppm) — z accelerometer scale error (ppm)

Altitude (m)

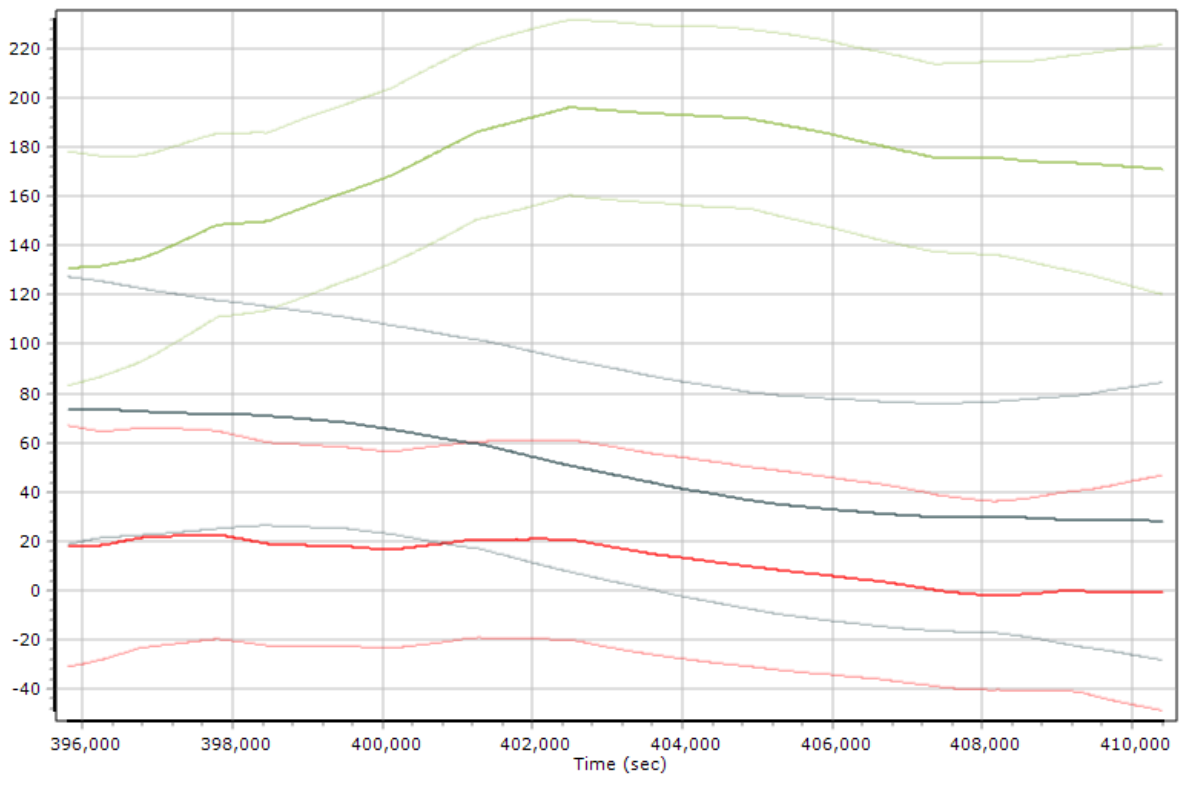


Baseline Length(m)





— x gyro bias (deg/hr) — y gyro bias (deg/hr) — z gyro bias (deg/hr)



— x gyro scale error (ppm) — y gyro scale error (ppm) — z gyro scale error (ppm)

Stabilized Mount to IMU Lever Arm

X
Y
Z

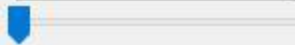
Stabilized Mount to IMU Mounting Angles

X
Y
Z

Stabilized Mount to Primary GNSS Lever Arm

X
Y
Z

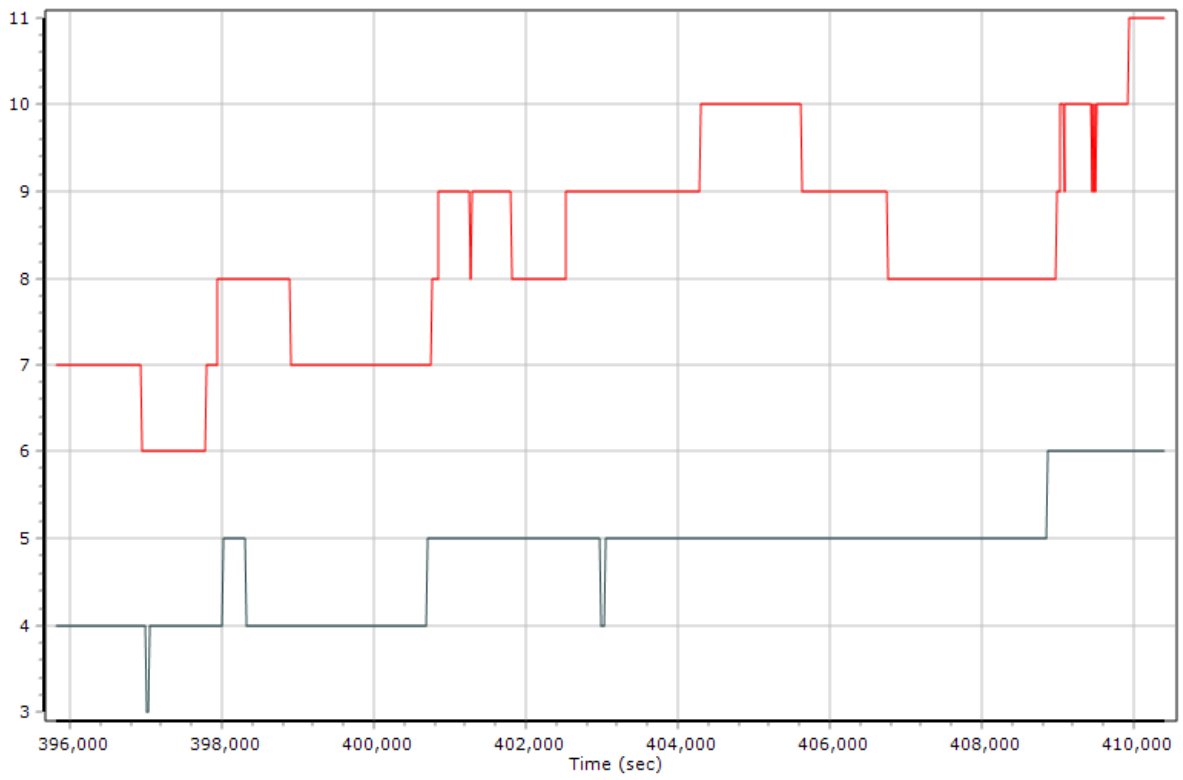
Standard Deviation


<3cm 10cm 50cm 1m 10m

Aircraft to Stabilized Mount Mounting Angles

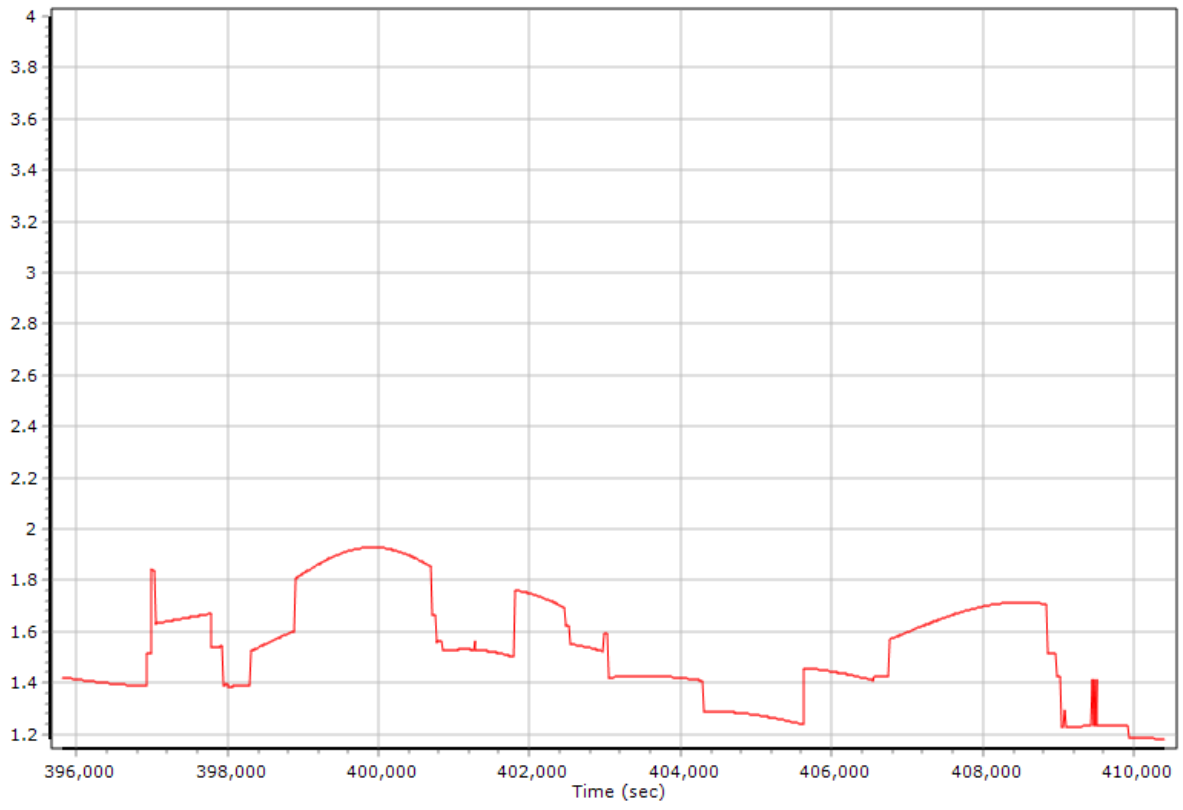
X
Y
Z

Measurements are to the stabilized platform's center of rotation with the Gimbal in the rest position.

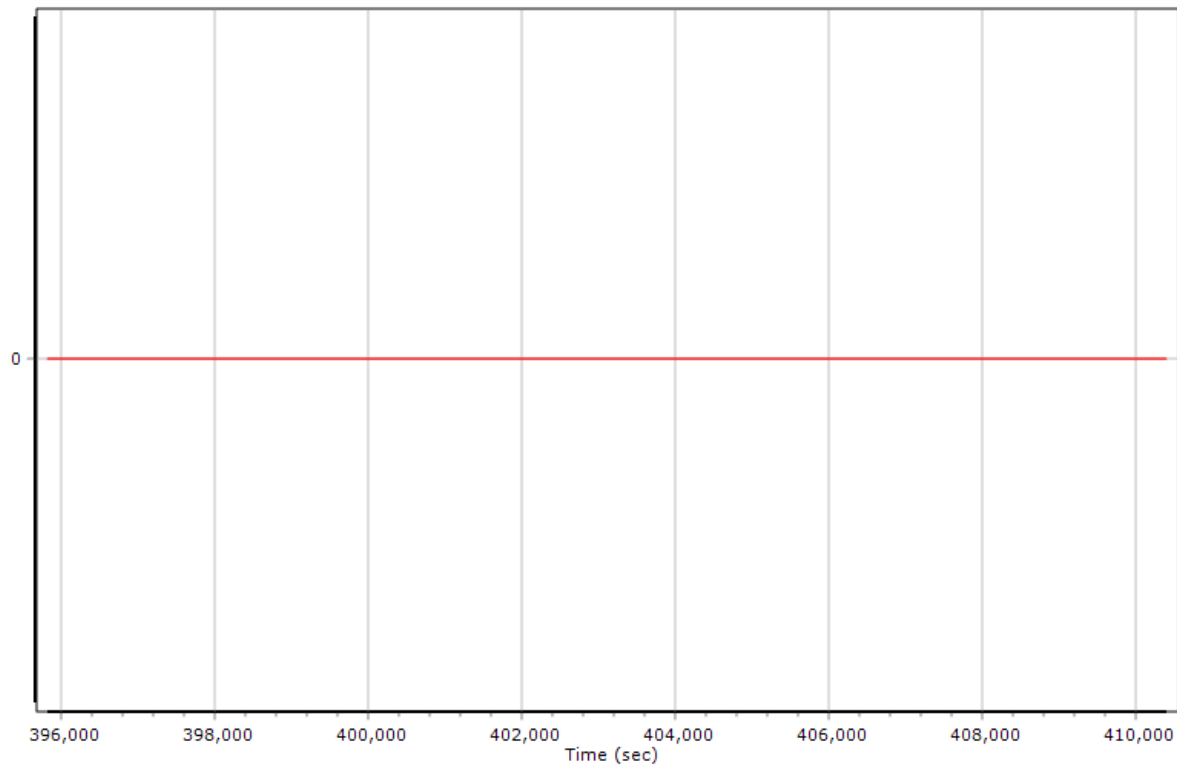


— Number of GPS Satellites — Number of GLONASS Satellites

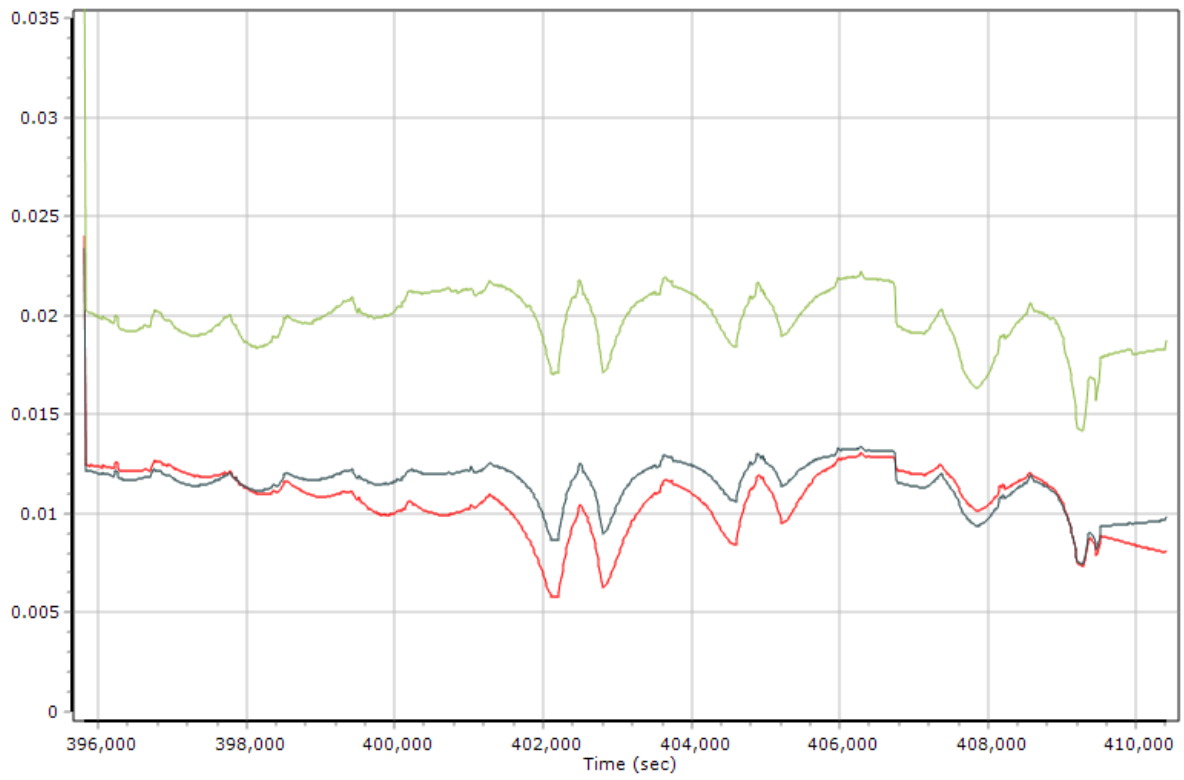
PDOP



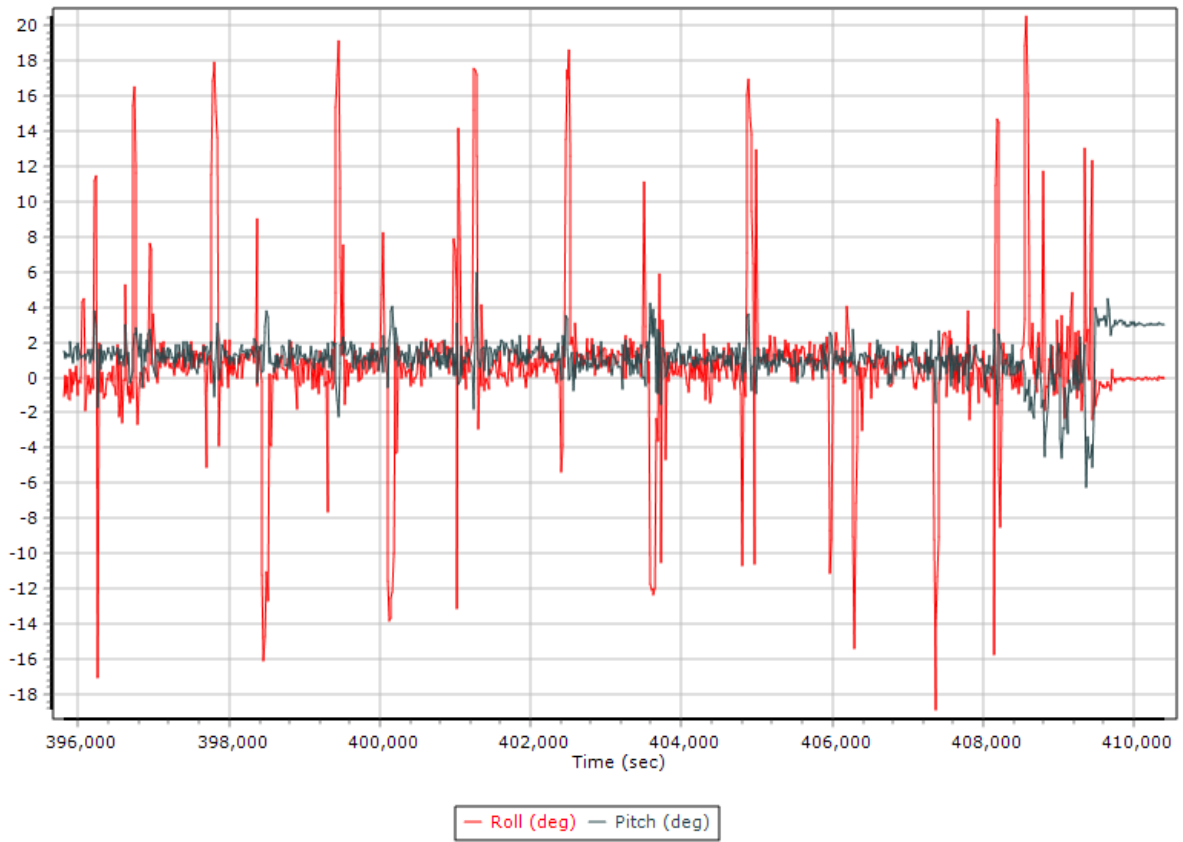
Processing Mode



0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = C/A, 7 = GNSS Nav, 8 = DR



— North Position Error RMS (m) — East Position Error RMS (m) — Down Position Error RMS (m)



Disable Satellites

GPS GLONASS BEIDOU QZSS

- | | | |
|---------------------------------|----------------------------------|----------------------------------|
| <input type="checkbox"/> SLOT 1 | <input type="checkbox"/> SLOT 10 | <input type="checkbox"/> SLOT 19 |
| <input type="checkbox"/> SLOT 2 | <input type="checkbox"/> SLOT 11 | <input type="checkbox"/> SLOT 20 |
| <input type="checkbox"/> SLOT 3 | <input type="checkbox"/> SLOT 12 | <input type="checkbox"/> SLOT 21 |
| <input type="checkbox"/> SLOT 4 | <input type="checkbox"/> SLOT 13 | <input type="checkbox"/> SLOT 22 |
| <input type="checkbox"/> SLOT 5 | <input type="checkbox"/> SLOT 14 | <input type="checkbox"/> SLOT 23 |
| <input type="checkbox"/> SLOT 6 | <input type="checkbox"/> SLOT 15 | <input type="checkbox"/> SLOT 24 |
| <input type="checkbox"/> SLOT 7 | <input type="checkbox"/> SLOT 16 | |
| <input type="checkbox"/> SLOT 8 | <input type="checkbox"/> SLOT 17 | |
| <input type="checkbox"/> SLOT 9 | <input type="checkbox"/> SLOT 18 | |

Elevation Mask Angle

Force GPS Only

Disable Satellites

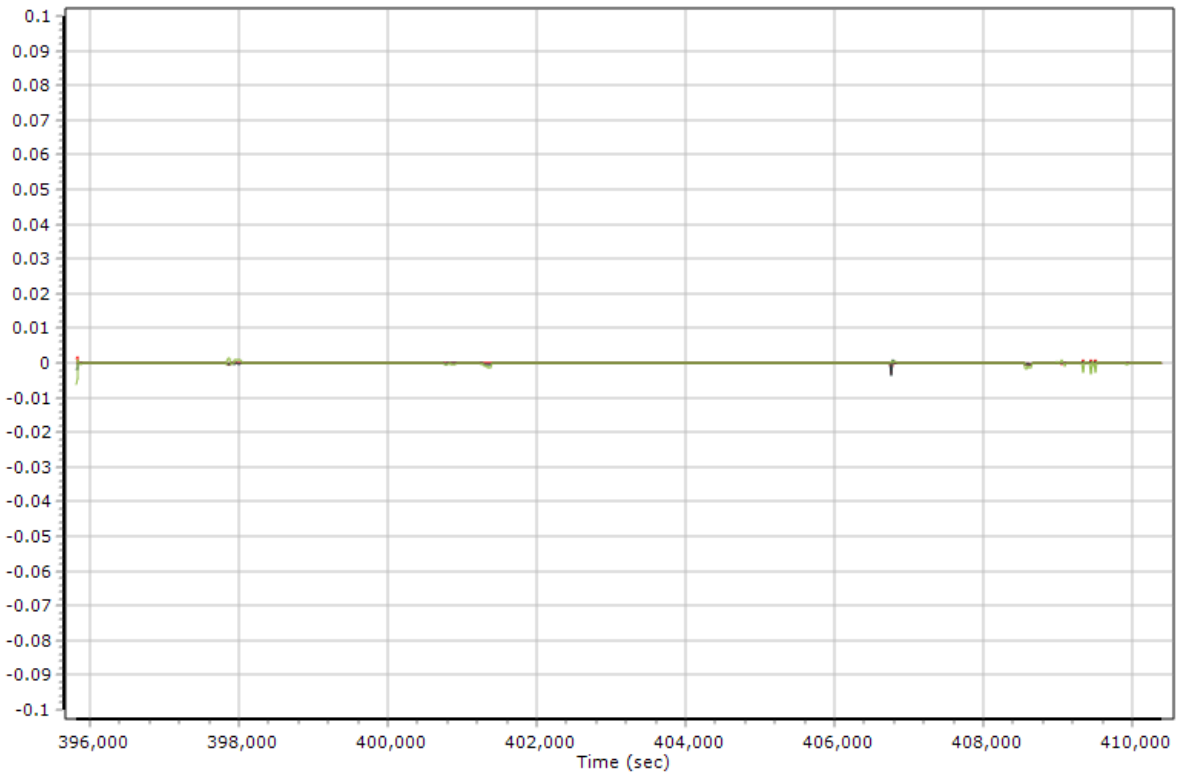
GPS GLONASS BEIDOU QZSS

- | | | | |
|--------------------------------|---------------------------------|---------------------------------|---------------------------------|
| <input type="checkbox"/> PRN 1 | <input type="checkbox"/> PRN 10 | <input type="checkbox"/> PRN 19 | <input type="checkbox"/> PRN 28 |
| <input type="checkbox"/> PRN 2 | <input type="checkbox"/> PRN 11 | <input type="checkbox"/> PRN 20 | <input type="checkbox"/> PRN 29 |
| <input type="checkbox"/> PRN 3 | <input type="checkbox"/> PRN 12 | <input type="checkbox"/> PRN 21 | <input type="checkbox"/> PRN 30 |
| <input type="checkbox"/> PRN 4 | <input type="checkbox"/> PRN 13 | <input type="checkbox"/> PRN 22 | <input type="checkbox"/> PRN 31 |
| <input type="checkbox"/> PRN 5 | <input type="checkbox"/> PRN 14 | <input type="checkbox"/> PRN 23 | <input type="checkbox"/> PRN 32 |
| <input type="checkbox"/> PRN 6 | <input type="checkbox"/> PRN 15 | <input type="checkbox"/> PRN 24 | |
| <input type="checkbox"/> PRN 7 | <input type="checkbox"/> PRN 16 | <input type="checkbox"/> PRN 25 | |
| <input type="checkbox"/> PRN 8 | <input type="checkbox"/> PRN 17 | <input type="checkbox"/> PRN 26 | |
| <input type="checkbox"/> PRN 9 | <input type="checkbox"/> PRN 18 | <input type="checkbox"/> PRN 27 | |



Elevation Mask Angle

Force GPS Only



— North (m) — East (m) — Down (m) — DR mode

Timing

Start

End

Entire time interval

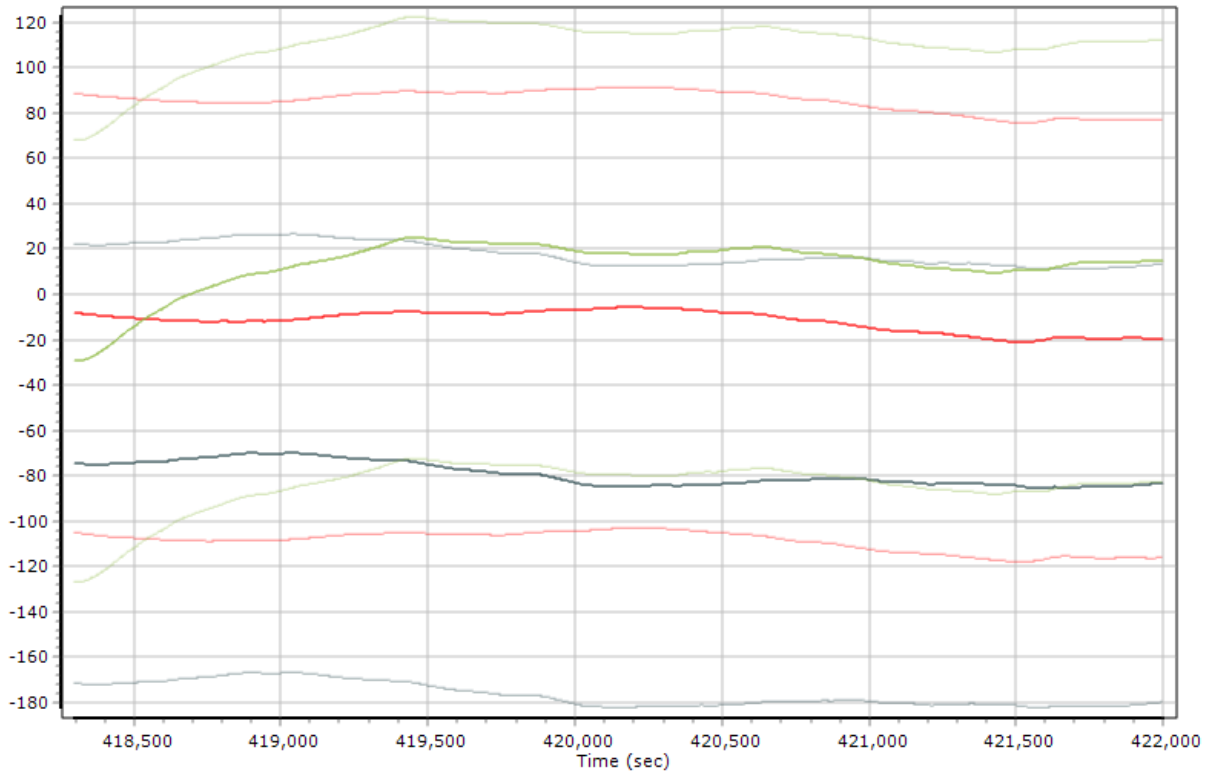
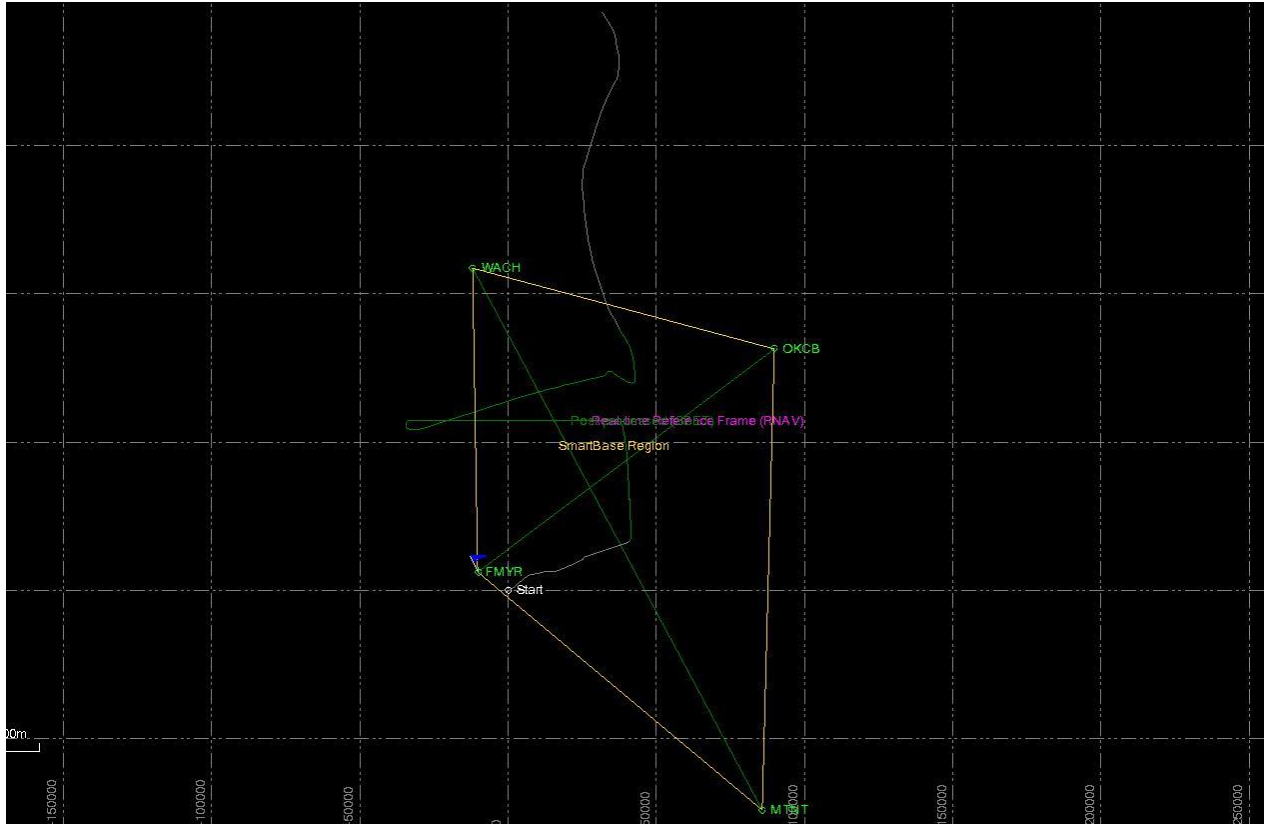
Seconds of start week

UTC Offset

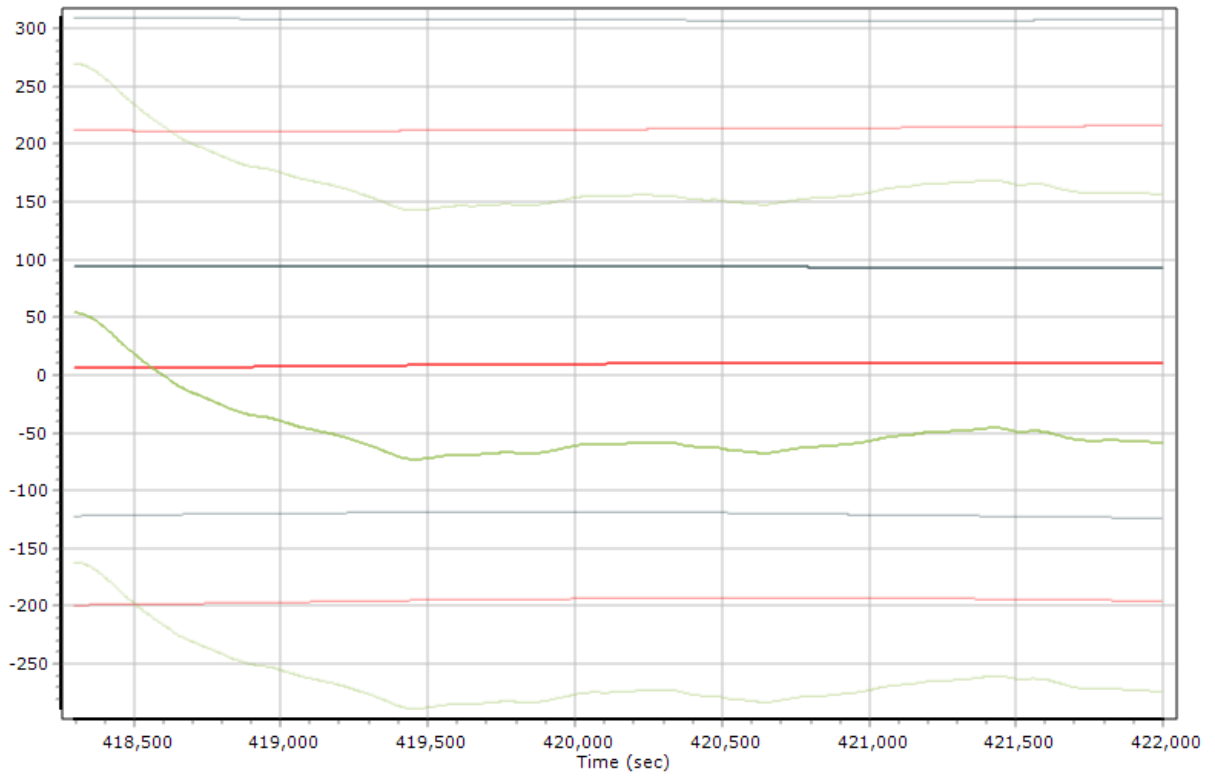
Data	Incr. (sec)
Output Record	0.005000
IMU	0.005000
Primary GNSS	1.000000



MISSION: PTG19010B

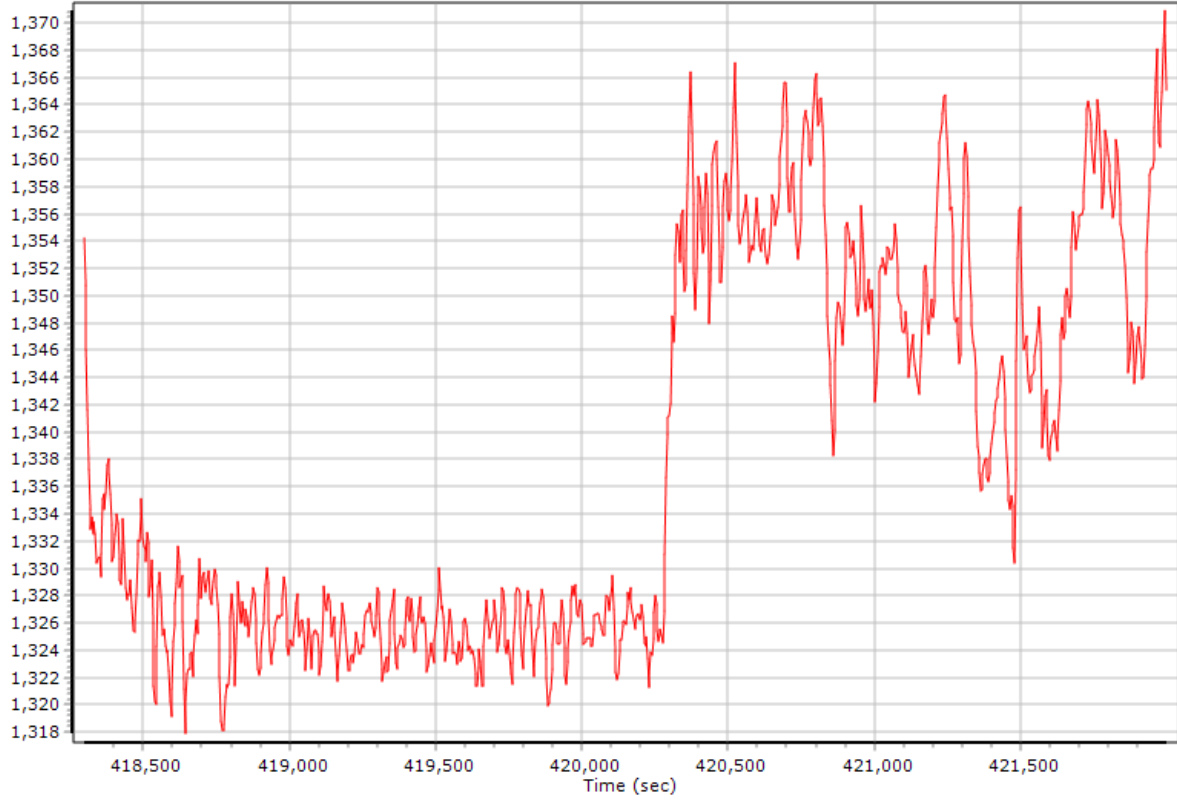


— x accelerometer bias (micro-g) — y accelerometer bias (micro-g) — z accelerometer bias (micro-g)

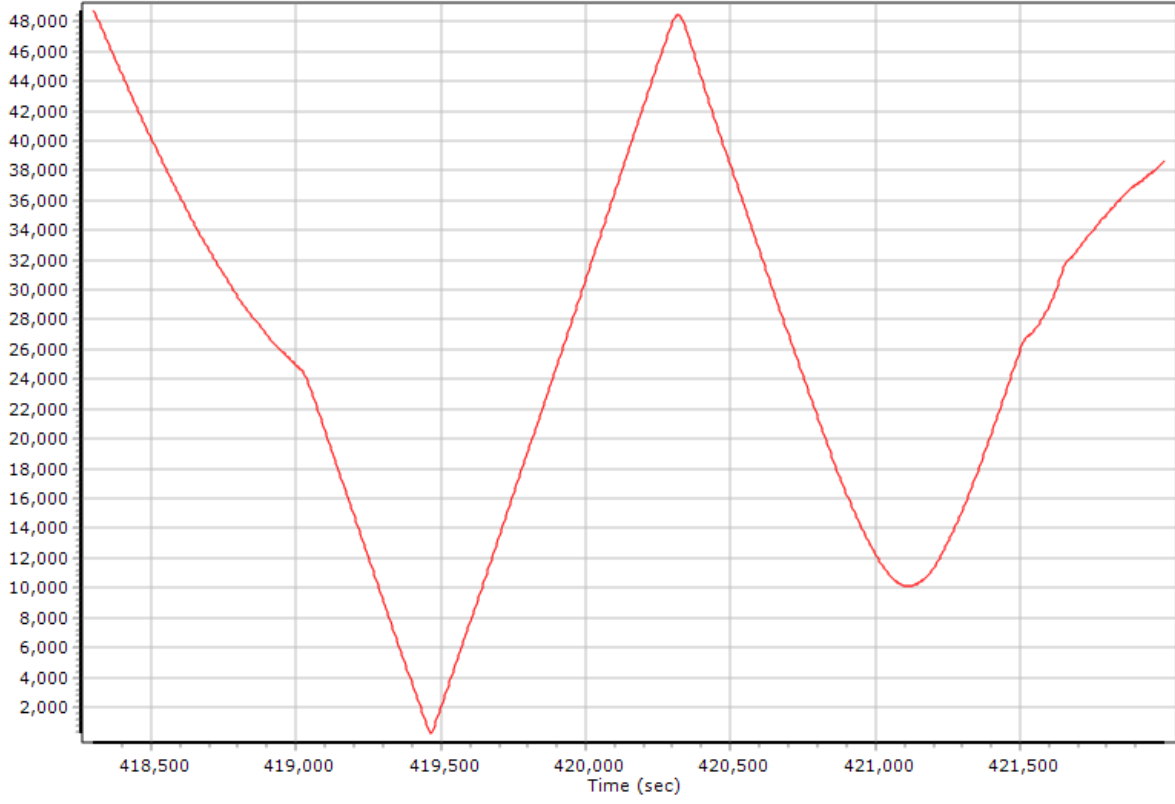


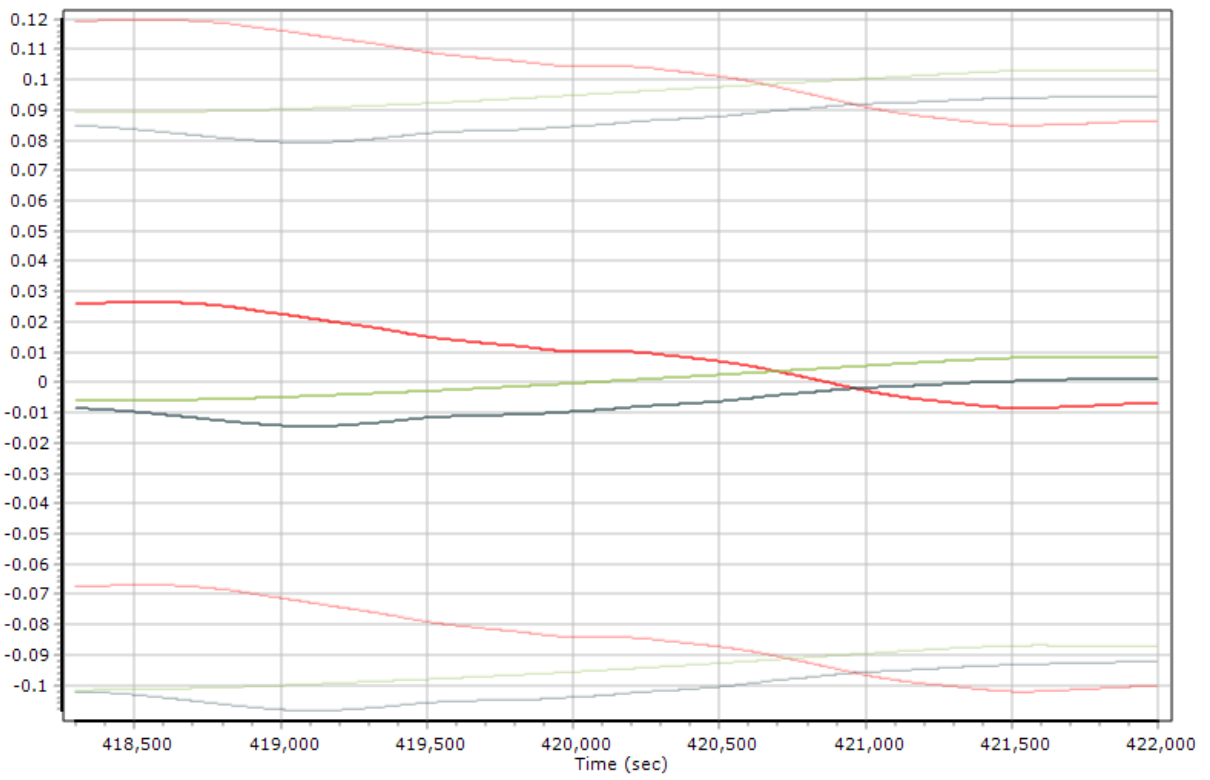
— x accelerometer scale error (ppm) — y accelerometer scale error (ppm) — z accelerometer scale error (ppm)

Altitude (m)

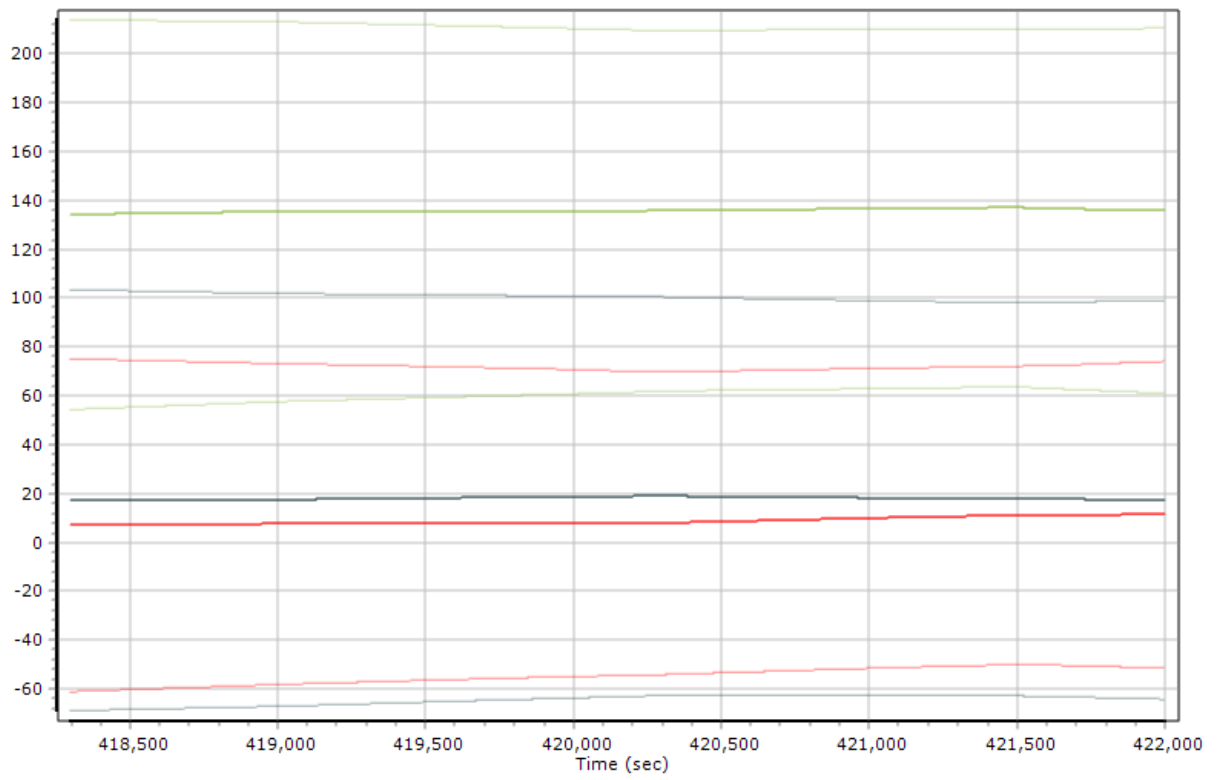


Baseline Length(m)





— x gyro bias (deg/hr) — y gyro bias (deg/hr) — z gyro bias (deg/hr)



— x gyro scale error (ppm) — y gyro scale error (ppm) — z gyro scale error (ppm)

Stabilized Mount to IMU Lever Arm

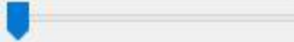
X
Y
Z

Stabilized Mount to IMU Mounting Angles

X
Y
Z

Stabilized Mount to Primary GNSS Lever Arm

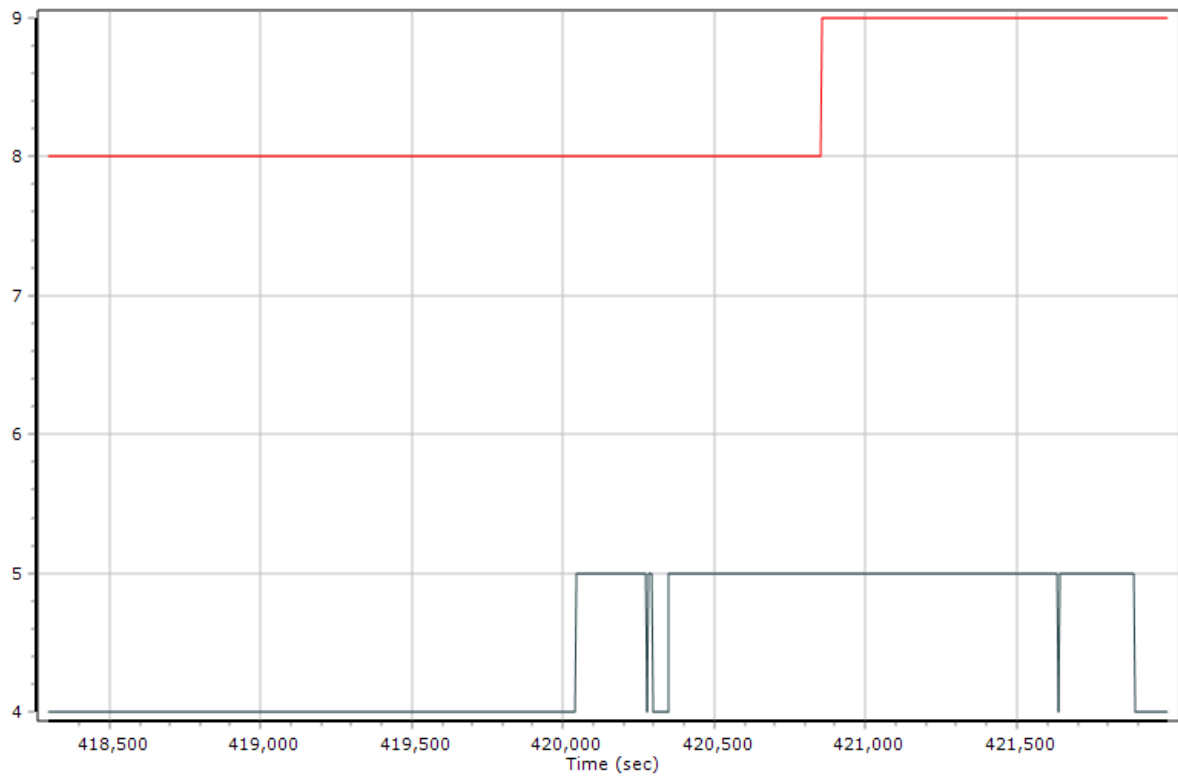
X
Y
Z

Standard Deviation 
<3cm 10cm 50cm 1m 10m

Aircraft to Stabilized Mount Mounting Angles

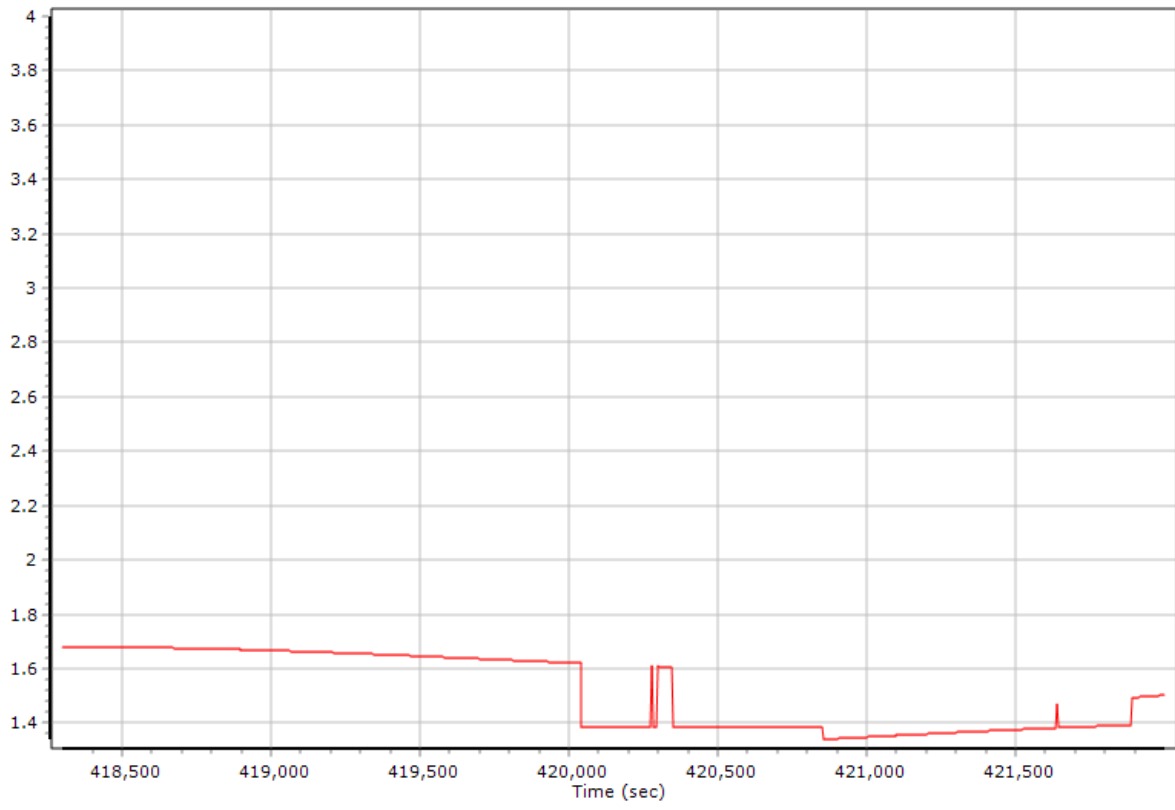
X
Y
Z

Measurements are to the stabilized platform's center of rotation with the Gimbal in the rest position.

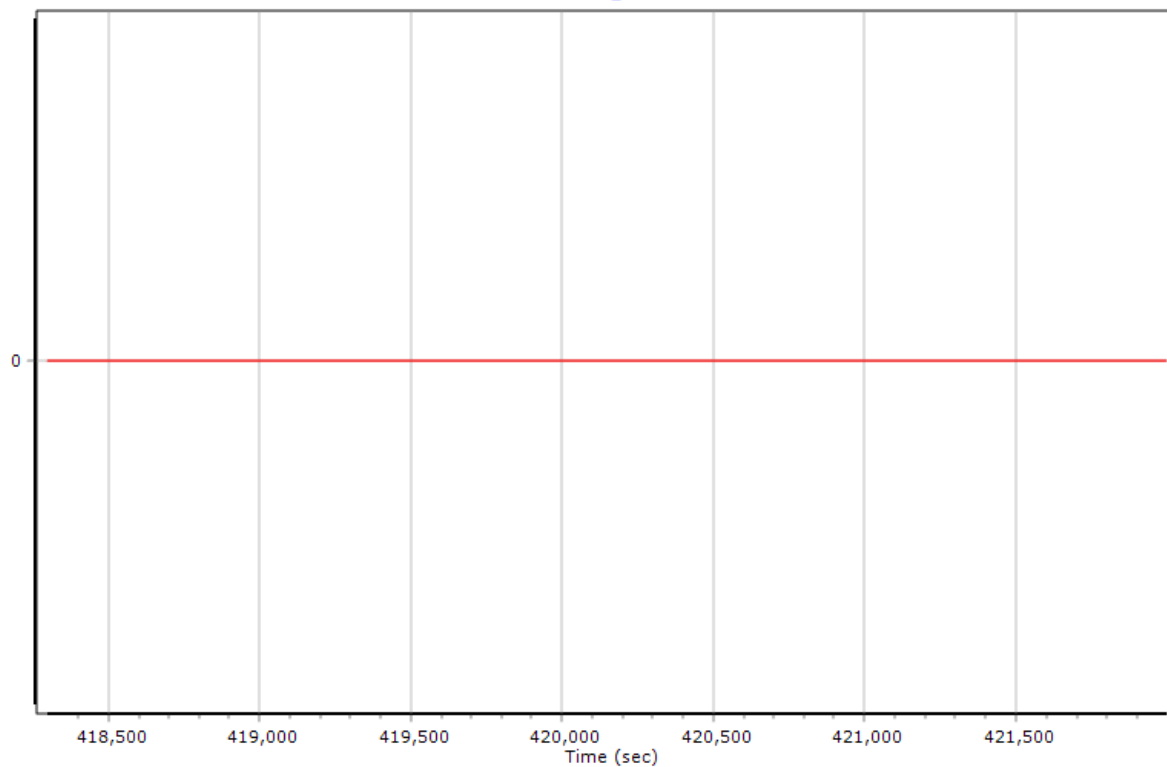


— Number of GPS Satellites — Number of GLONASS Satellites

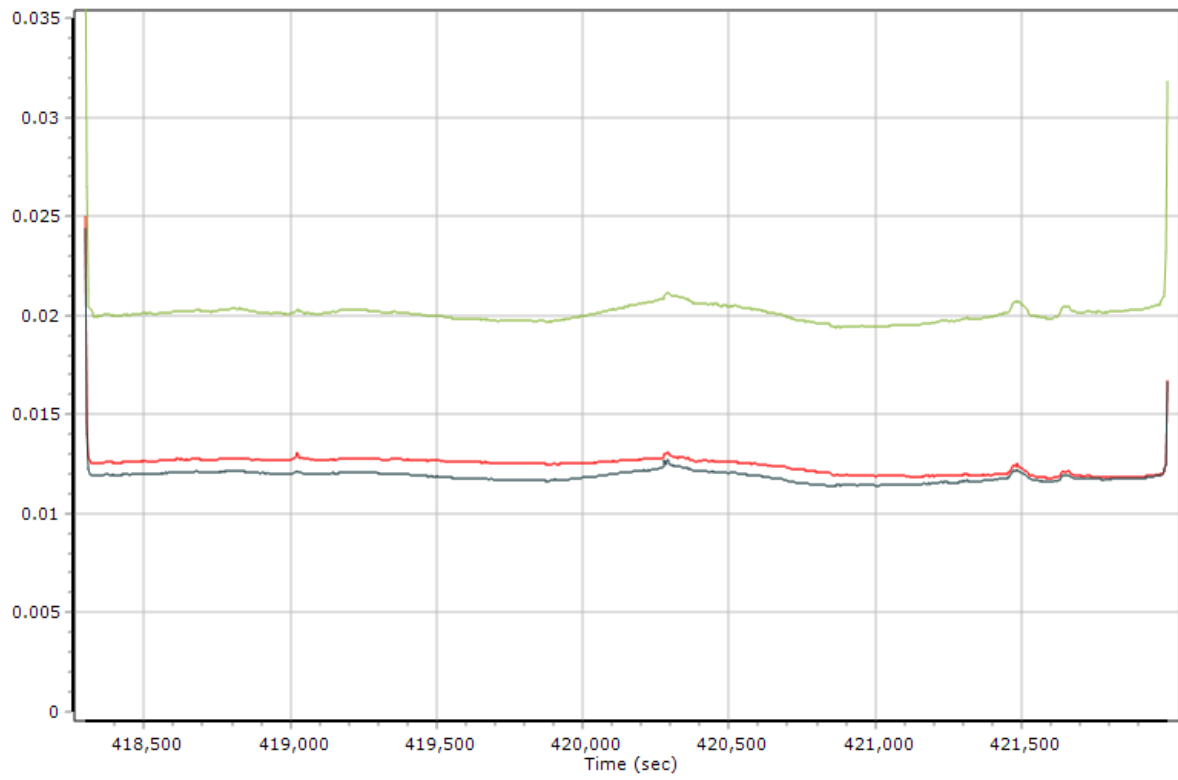
PDOP



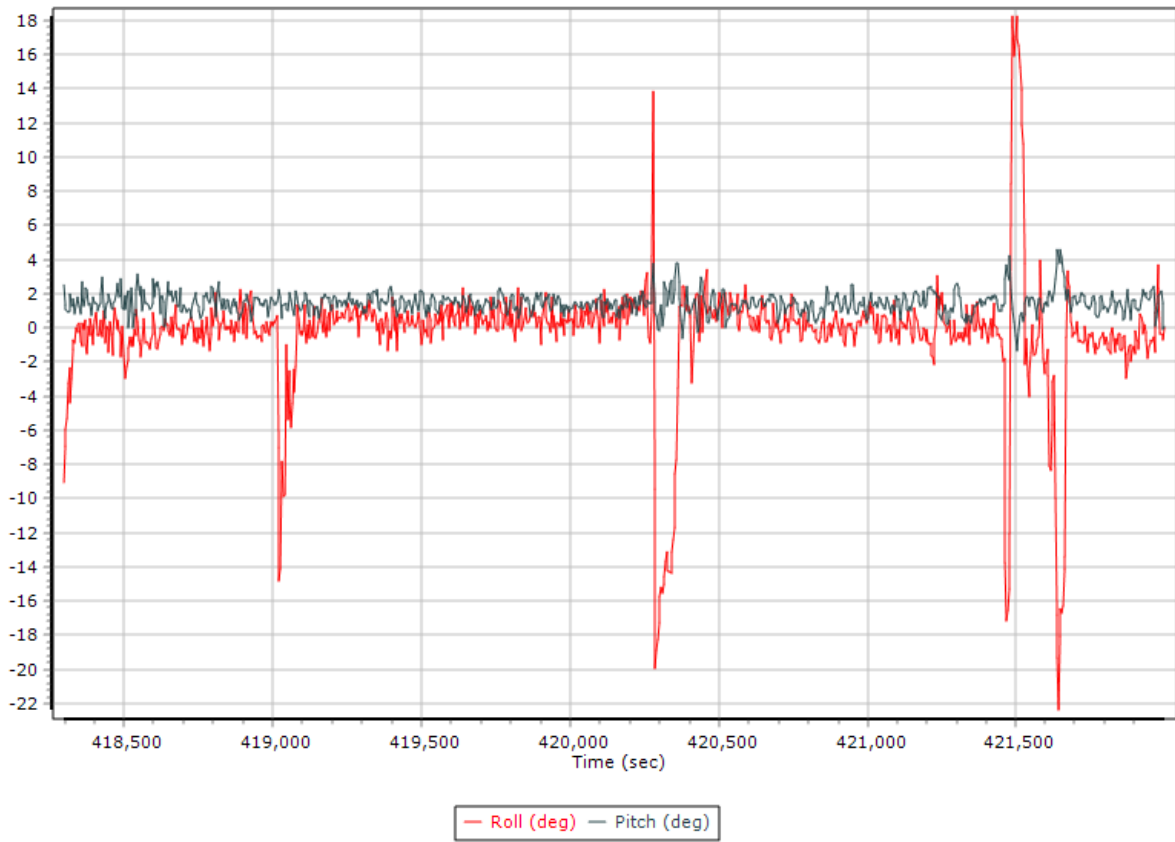
Processing Mode



0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = C/A, 7 = GNSS Nav, 8 = DR



— North Position Error RMS (m) — East Position Error RMS (m) — Down Position Error RMS (m)



Disable Satellites

GPS GLONASS BEIDOU QZSS

- | | | |
|---------------------------------|----------------------------------|----------------------------------|
| <input type="checkbox"/> SLOT 1 | <input type="checkbox"/> SLOT 10 | <input type="checkbox"/> SLOT 19 |
| <input type="checkbox"/> SLOT 2 | <input type="checkbox"/> SLOT 11 | <input type="checkbox"/> SLOT 20 |
| <input type="checkbox"/> SLOT 3 | <input type="checkbox"/> SLOT 12 | <input type="checkbox"/> SLOT 21 |
| <input type="checkbox"/> SLOT 4 | <input type="checkbox"/> SLOT 13 | <input type="checkbox"/> SLOT 22 |
| <input type="checkbox"/> SLOT 5 | <input type="checkbox"/> SLOT 14 | <input type="checkbox"/> SLOT 23 |
| <input type="checkbox"/> SLOT 6 | <input type="checkbox"/> SLOT 15 | <input type="checkbox"/> SLOT 24 |
| <input type="checkbox"/> SLOT 7 | <input type="checkbox"/> SLOT 16 | |
| <input type="checkbox"/> SLOT 8 | <input type="checkbox"/> SLOT 17 | |
| <input type="checkbox"/> SLOT 9 | <input type="checkbox"/> SLOT 18 | |

Elevation Mask Angle

Force GPS Only

Disable Satellites

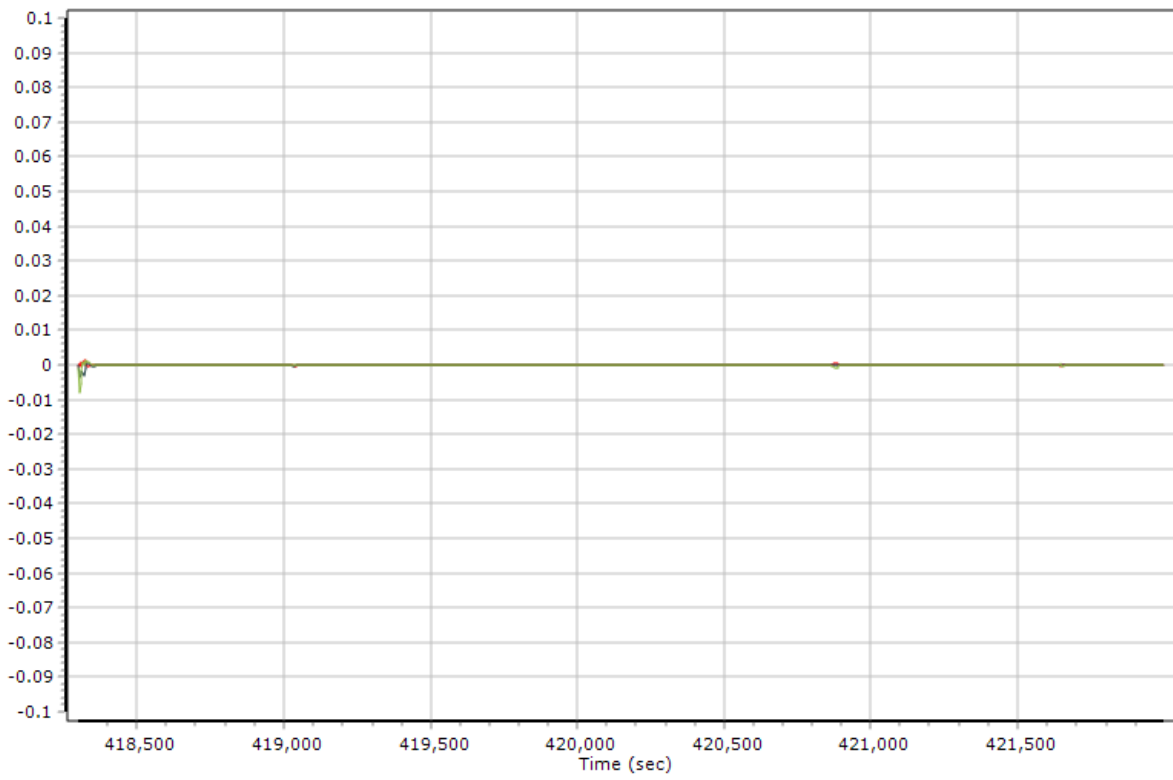
GPS GLONASS BEIDOU QZSS

- | | | | |
|--------------------------------|---------------------------------|---------------------------------|---------------------------------|
| <input type="checkbox"/> PRN 1 | <input type="checkbox"/> PRN 10 | <input type="checkbox"/> PRN 19 | <input type="checkbox"/> PRN 28 |
| <input type="checkbox"/> PRN 2 | <input type="checkbox"/> PRN 11 | <input type="checkbox"/> PRN 20 | <input type="checkbox"/> PRN 29 |
| <input type="checkbox"/> PRN 3 | <input type="checkbox"/> PRN 12 | <input type="checkbox"/> PRN 21 | <input type="checkbox"/> PRN 30 |
| <input type="checkbox"/> PRN 4 | <input type="checkbox"/> PRN 13 | <input type="checkbox"/> PRN 22 | <input type="checkbox"/> PRN 31 |
| <input type="checkbox"/> PRN 5 | <input type="checkbox"/> PRN 14 | <input type="checkbox"/> PRN 23 | <input type="checkbox"/> PRN 32 |
| <input type="checkbox"/> PRN 6 | <input type="checkbox"/> PRN 15 | <input type="checkbox"/> PRN 24 | |
| <input type="checkbox"/> PRN 7 | <input type="checkbox"/> PRN 16 | <input type="checkbox"/> PRN 25 | |
| <input type="checkbox"/> PRN 8 | <input type="checkbox"/> PRN 17 | <input type="checkbox"/> PRN 26 | |
| <input type="checkbox"/> PRN 9 | <input type="checkbox"/> PRN 18 | <input type="checkbox"/> PRN 27 | |



Elevation Mask Angle

Force GPS Only



— North (m) — East (m) — Down (m) — DR mode

Timing

Start

End

Entire time interval

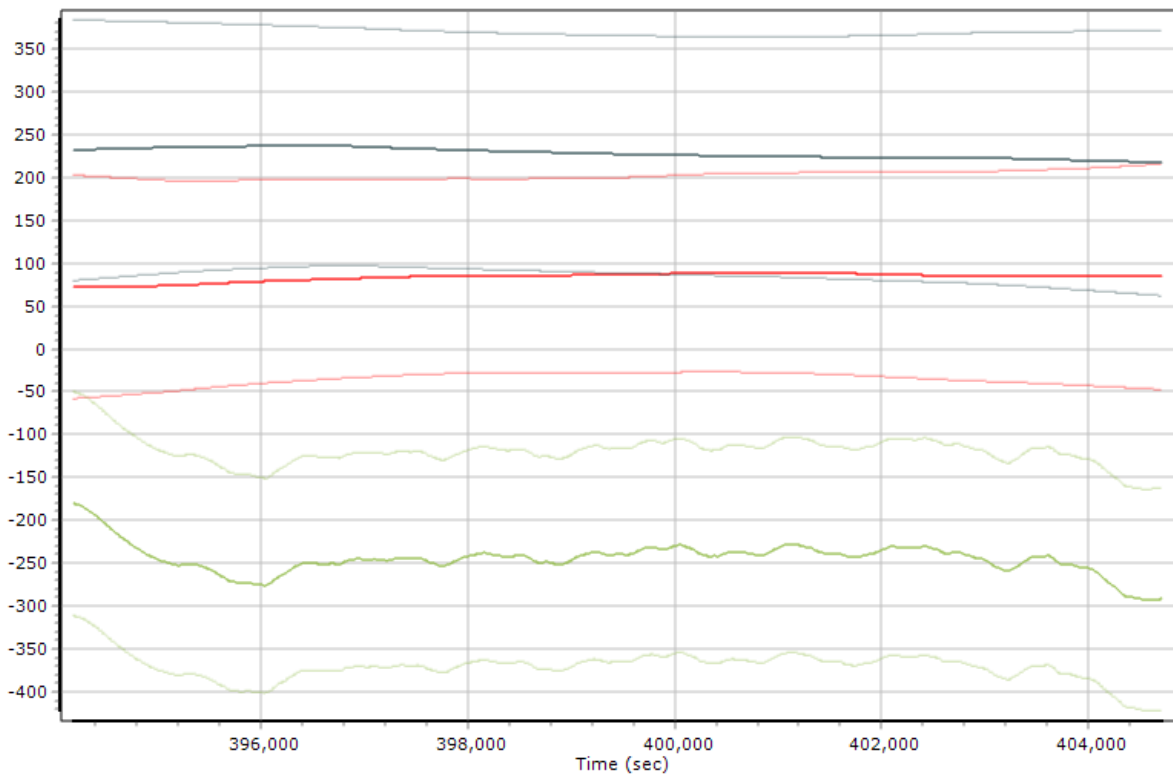
Seconds of start week

UTC Offset

Data	Incr. (sec)
Output Record	0.005000
IMU	0.005000
Primary GNSS	1.000000

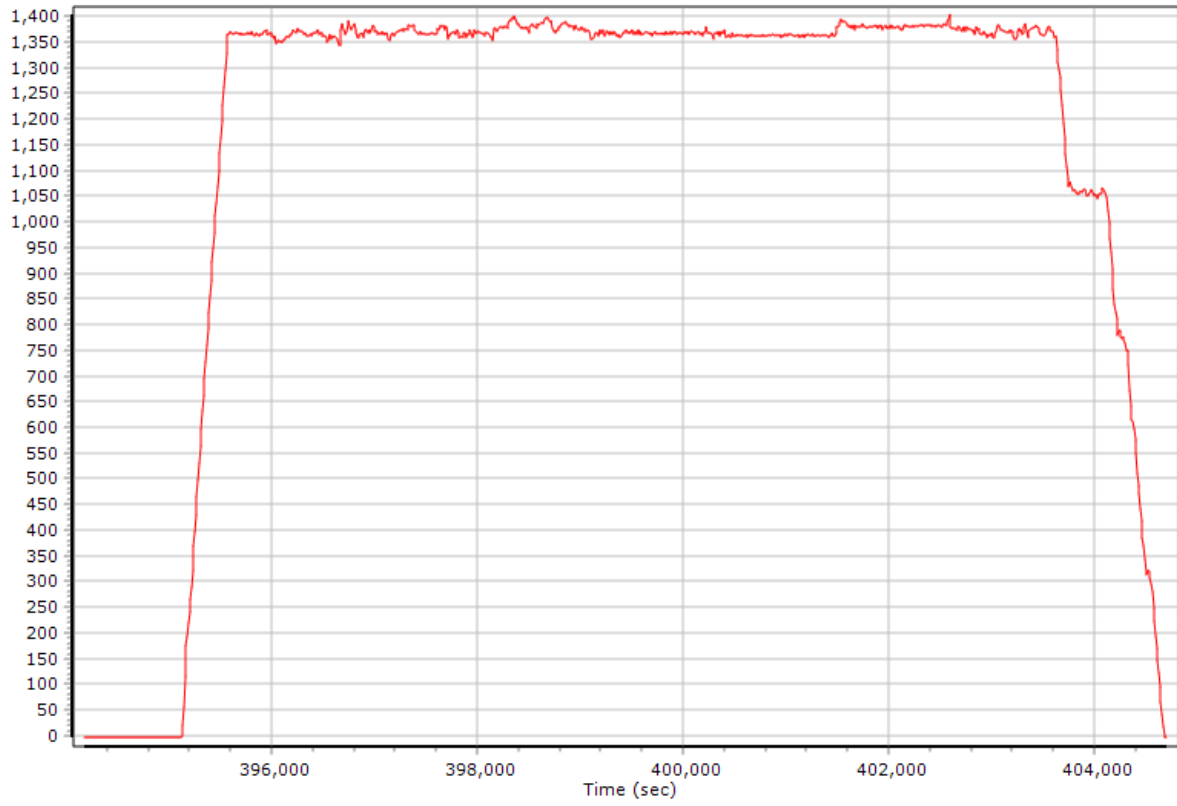


MISSION: PTG19094A

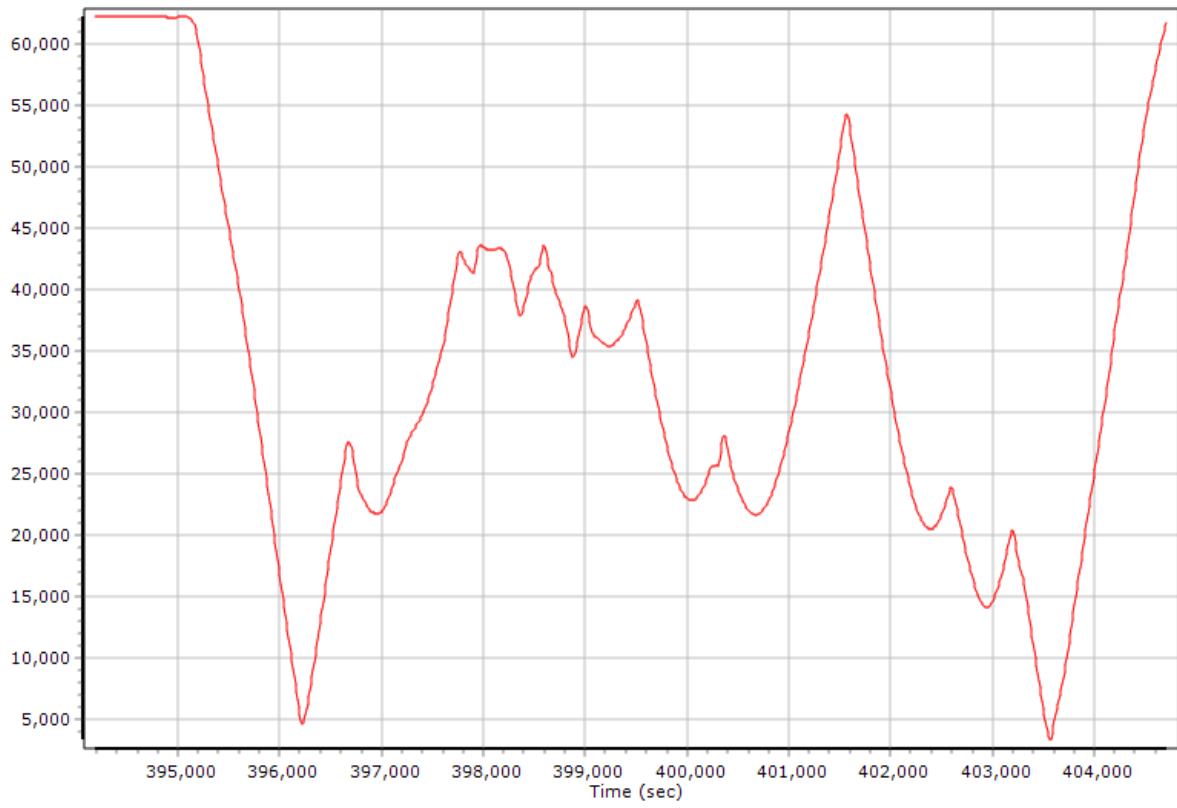


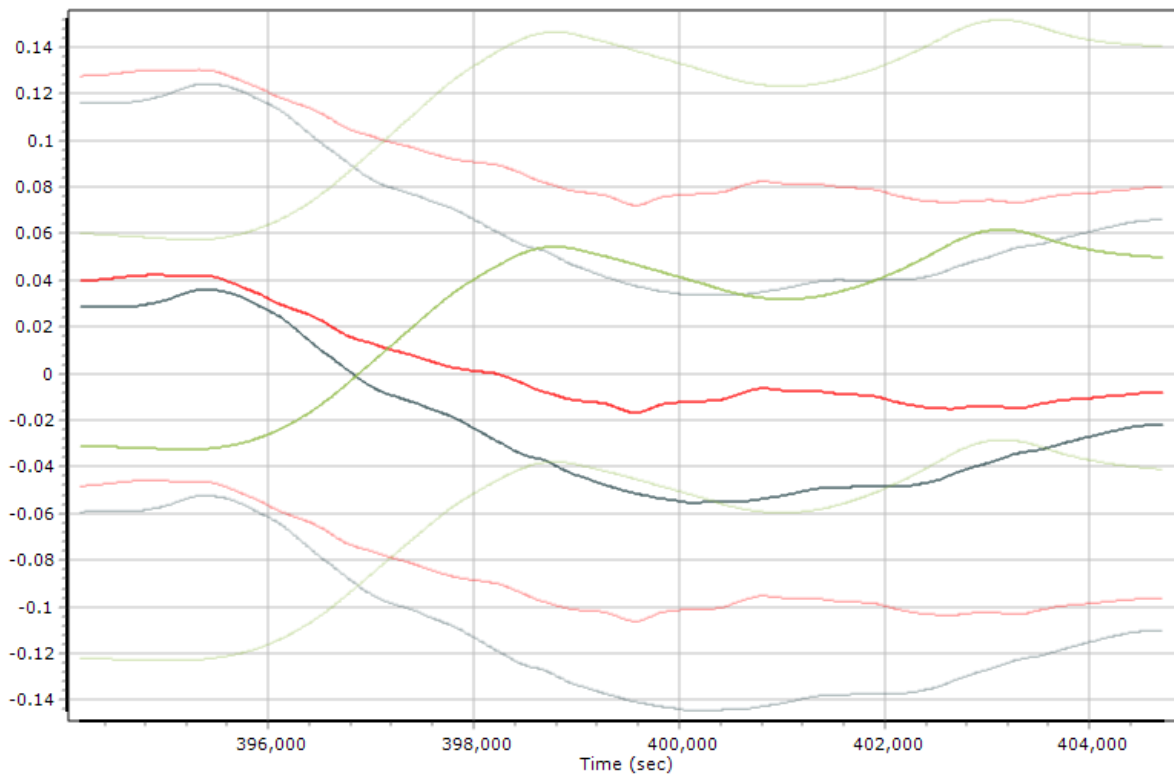
— x accelerometer scale error (ppm) — y accelerometer scale error (ppm) — z accelerometer scale error (ppm)

Altitude (m)

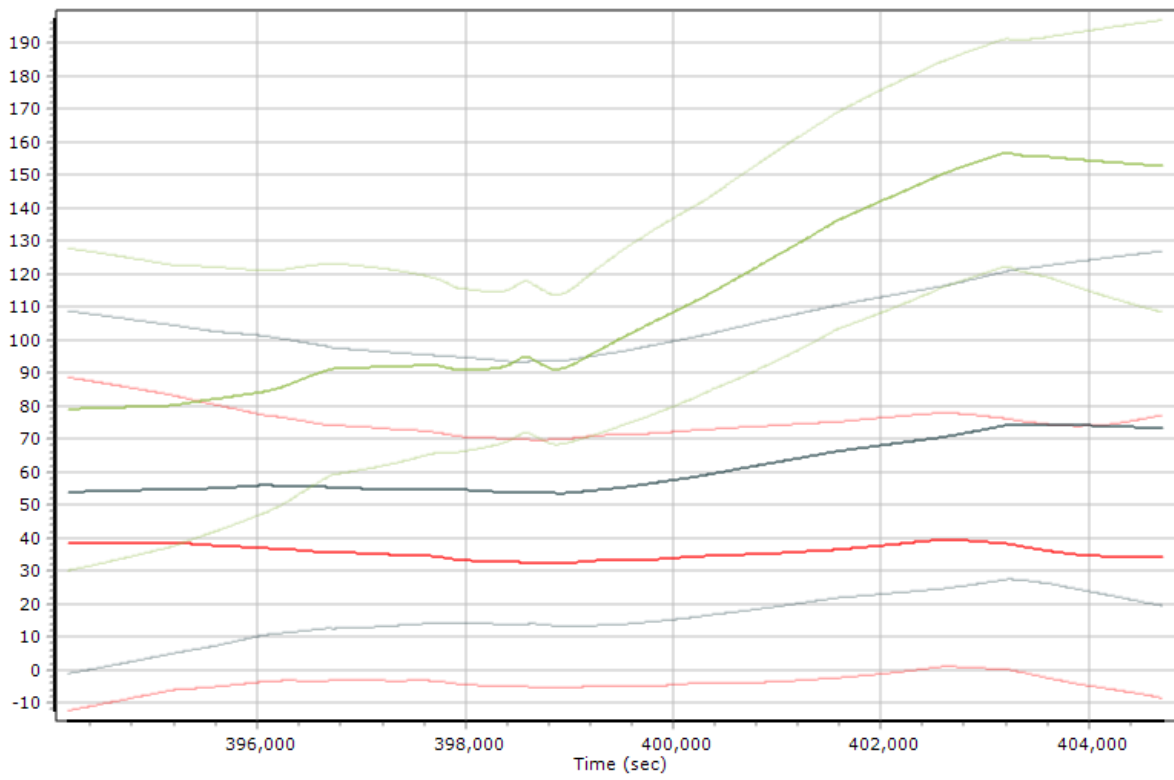


Baseline Length(m)





— x gyro bias (deg/hr) — y gyro bias (deg/hr) — z gyro bias (deg/hr)



— x gyro scale error (ppm) — y gyro scale error (ppm) — z gyro scale error (ppm)

Stabilized Mount to IMU Lever Arm

X
Y
Z

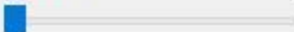
Stabilized Mount to IMU Mounting Angles

X
Y
Z

Stabilized Mount to Primary GNSS Lever Arm

X
Y
Z

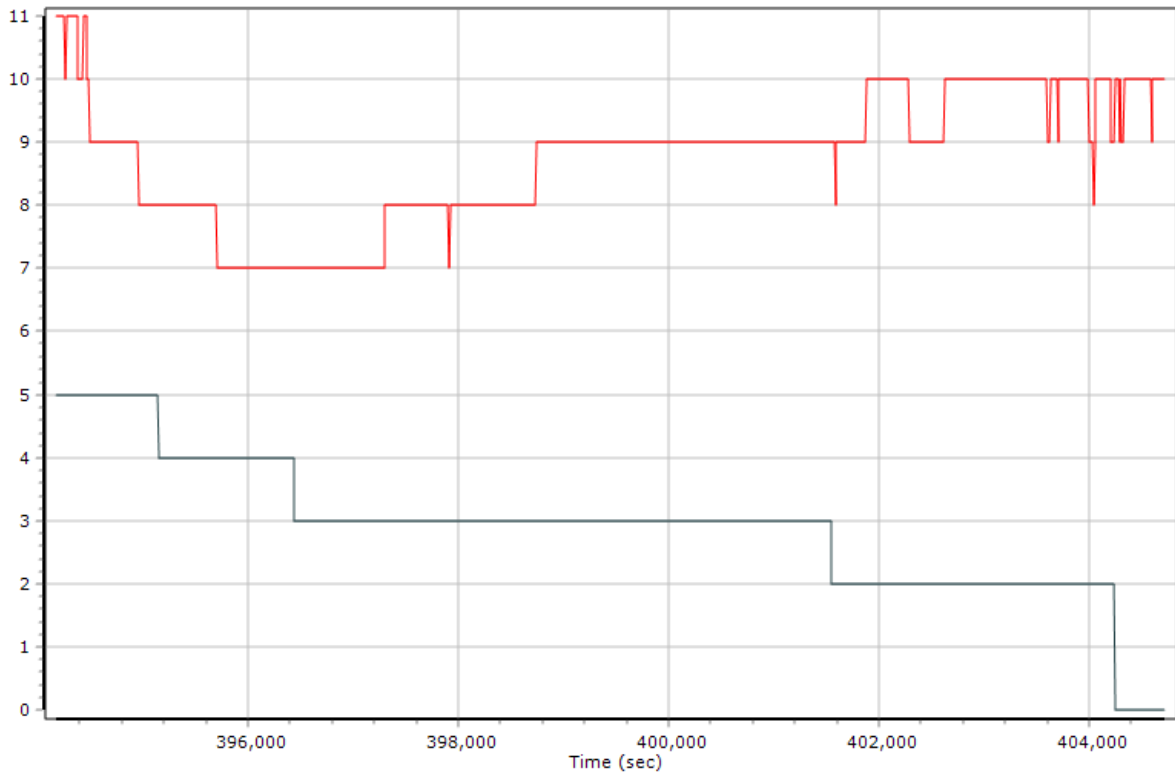
Standard Deviation


<3cm 10cm 50cm 1m 10m

Aircraft to Stabilized Mount Mounting Angles

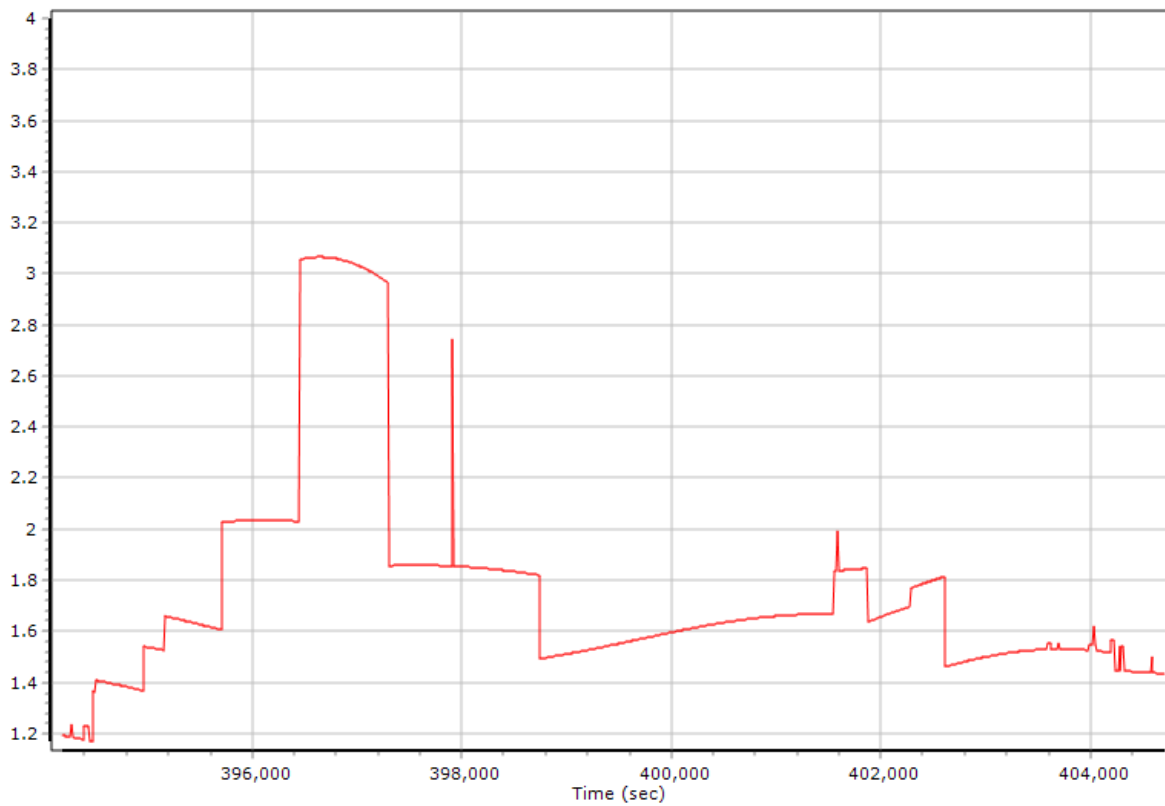
X
Y
Z

Measurements are to the stabilized platform's center of rotation with the Gimbal in the rest position.

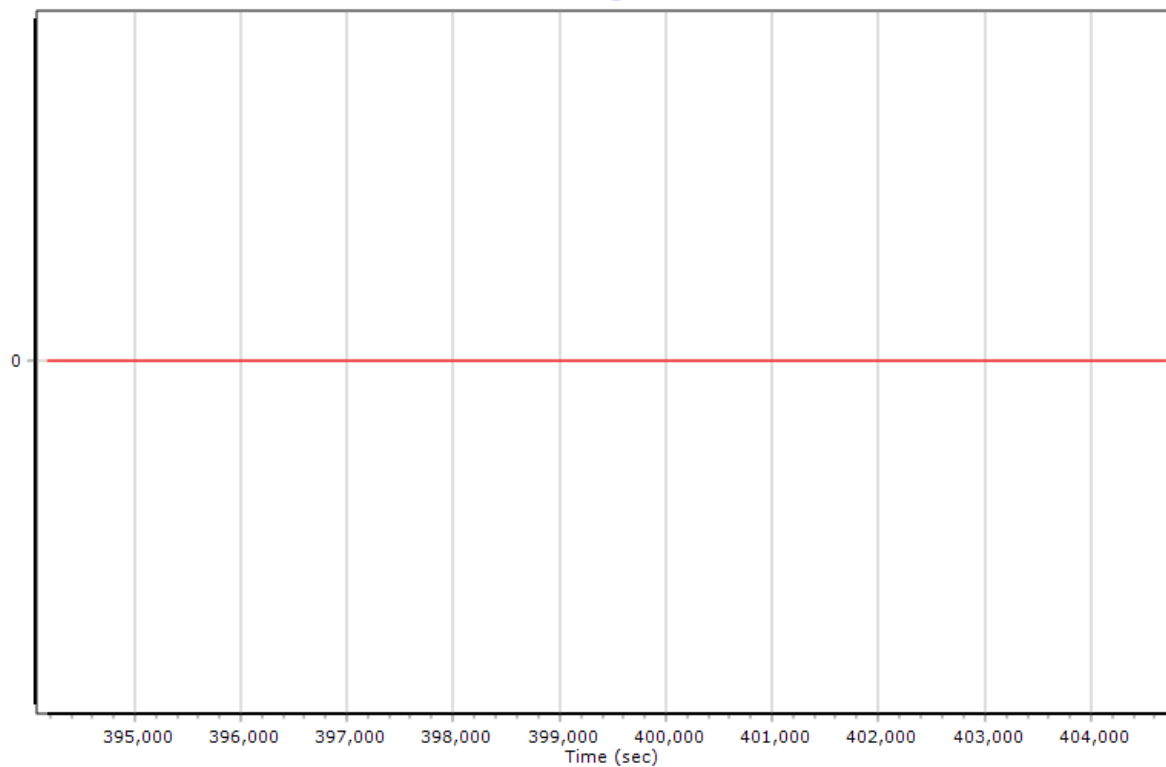


— Number of GPS Satellites — Number of GLONASS Satellites

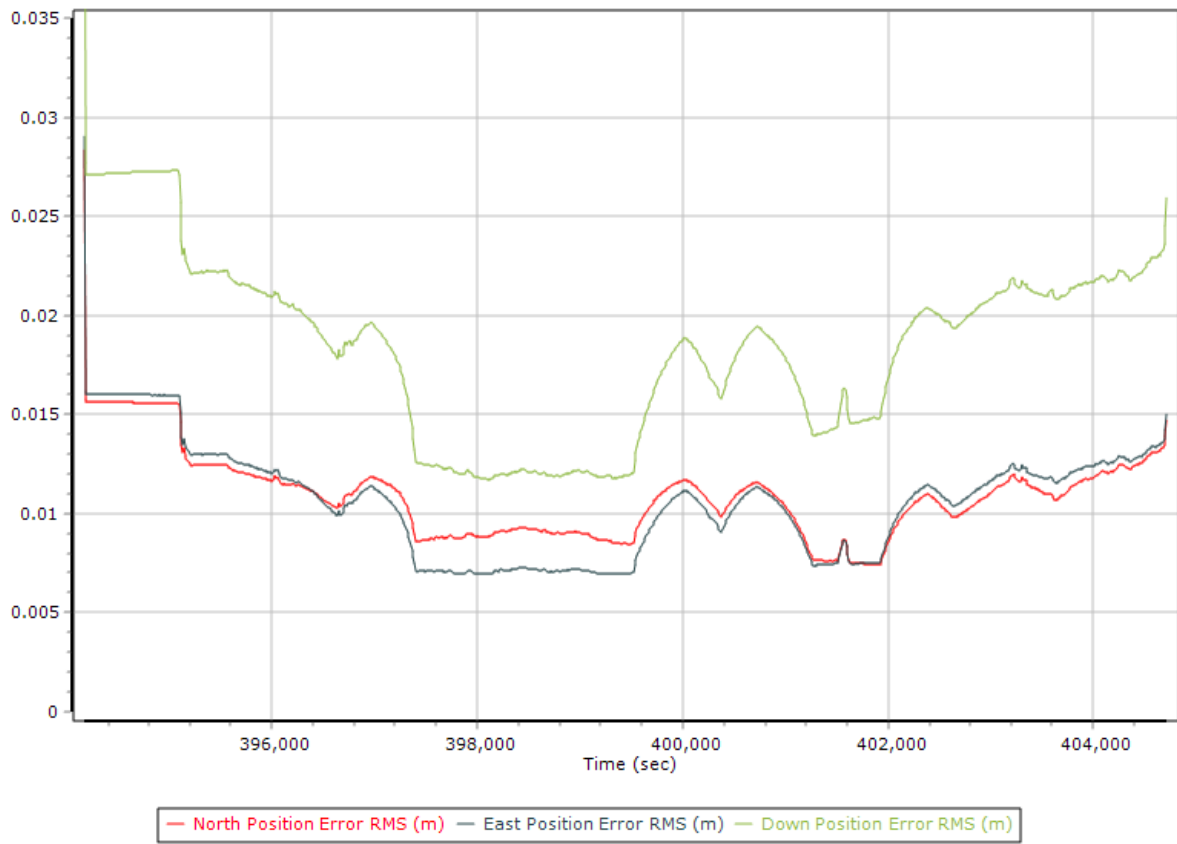
PDOP

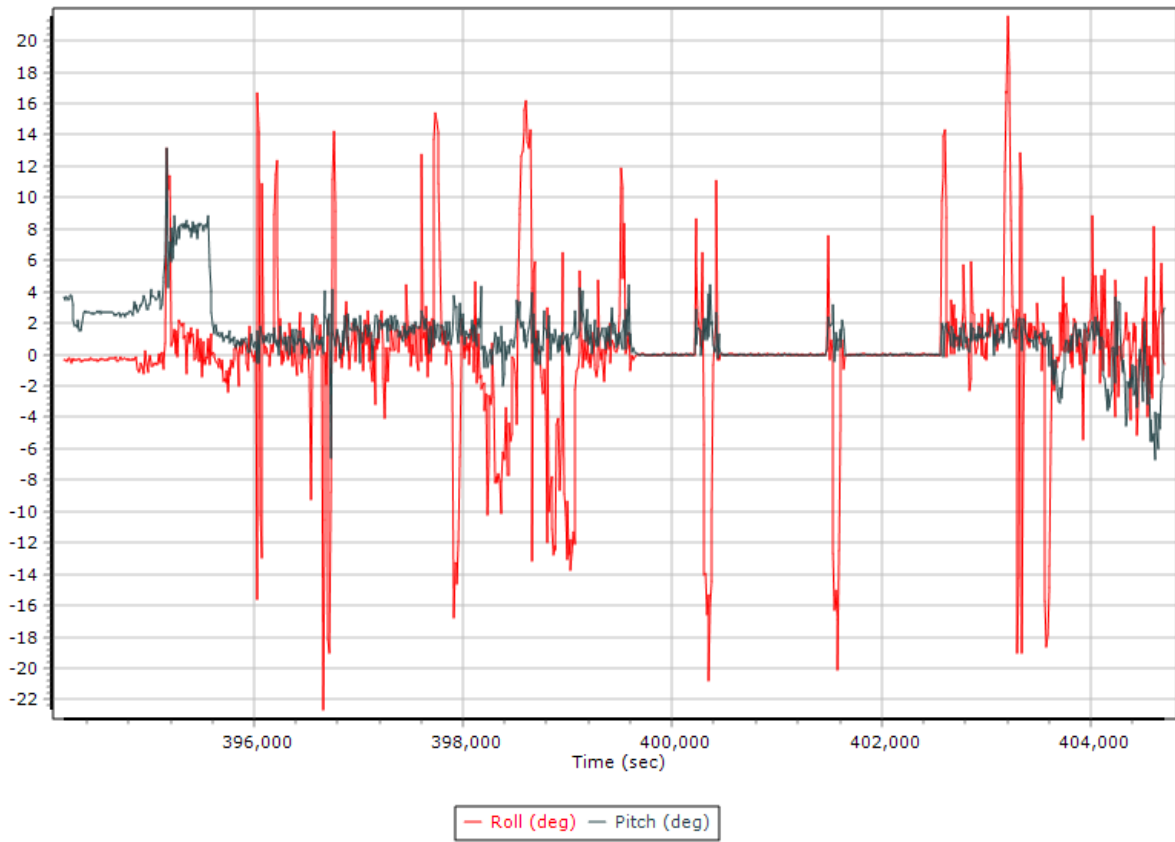


Processing Mode



0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = C/A, 7 = GNSS Nav, 8 = DR





Disable Satellites

GPS GLONASS BEIDOU QZSS

- | | | |
|---------------------------------|----------------------------------|----------------------------------|
| <input type="checkbox"/> SLOT 1 | <input type="checkbox"/> SLOT 10 | <input type="checkbox"/> SLOT 19 |
| <input type="checkbox"/> SLOT 2 | <input type="checkbox"/> SLOT 11 | <input type="checkbox"/> SLOT 20 |
| <input type="checkbox"/> SLOT 3 | <input type="checkbox"/> SLOT 12 | <input type="checkbox"/> SLOT 21 |
| <input type="checkbox"/> SLOT 4 | <input type="checkbox"/> SLOT 13 | <input type="checkbox"/> SLOT 22 |
| <input type="checkbox"/> SLOT 5 | <input type="checkbox"/> SLOT 14 | <input type="checkbox"/> SLOT 23 |
| <input type="checkbox"/> SLOT 6 | <input type="checkbox"/> SLOT 15 | <input type="checkbox"/> SLOT 24 |
| <input type="checkbox"/> SLOT 7 | <input type="checkbox"/> SLOT 16 | |
| <input type="checkbox"/> SLOT 8 | <input type="checkbox"/> SLOT 17 | |
| <input type="checkbox"/> SLOT 9 | <input type="checkbox"/> SLOT 18 | |

Elevation Mask Angle

Force GPS Only

Disable Satellites

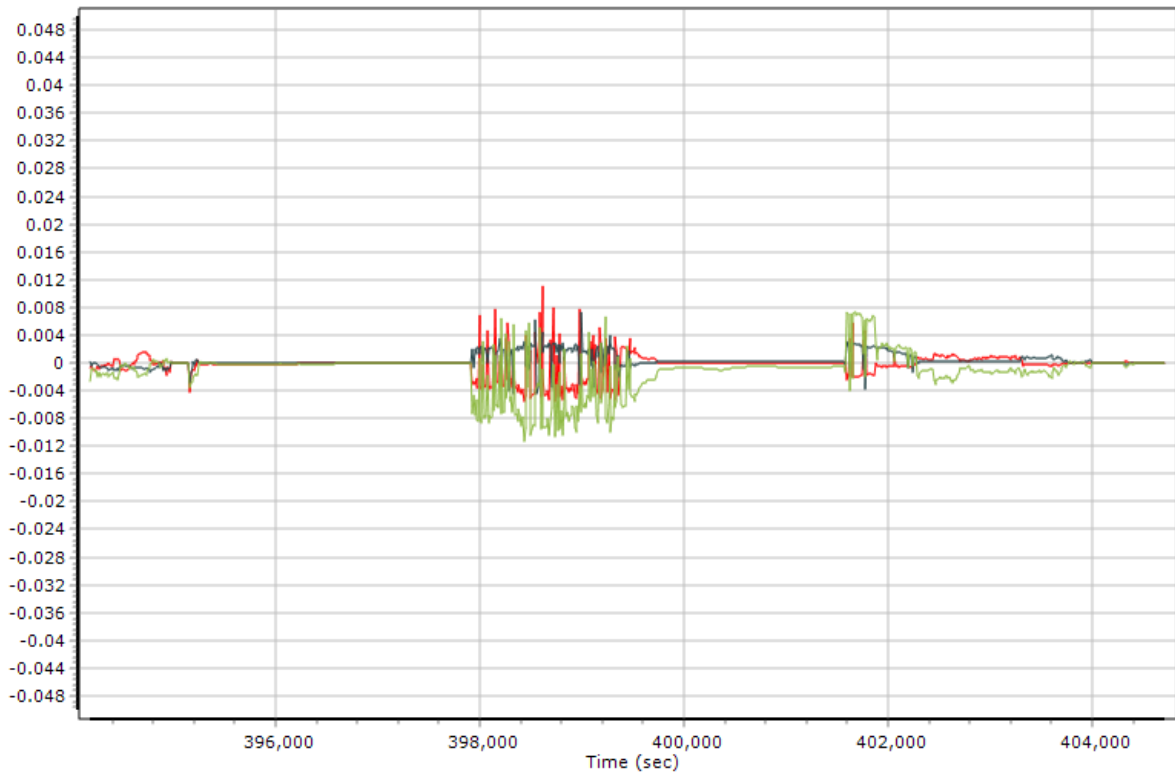
GPS GLONASS BEIDOU QZSS

- | | | | |
|--------------------------------|---------------------------------|---------------------------------|---------------------------------|
| <input type="checkbox"/> PRN 1 | <input type="checkbox"/> PRN 10 | <input type="checkbox"/> PRN 19 | <input type="checkbox"/> PRN 28 |
| <input type="checkbox"/> PRN 2 | <input type="checkbox"/> PRN 11 | <input type="checkbox"/> PRN 20 | <input type="checkbox"/> PRN 29 |
| <input type="checkbox"/> PRN 3 | <input type="checkbox"/> PRN 12 | <input type="checkbox"/> PRN 21 | <input type="checkbox"/> PRN 30 |
| <input type="checkbox"/> PRN 4 | <input type="checkbox"/> PRN 13 | <input type="checkbox"/> PRN 22 | <input type="checkbox"/> PRN 31 |
| <input type="checkbox"/> PRN 5 | <input type="checkbox"/> PRN 14 | <input type="checkbox"/> PRN 23 | <input type="checkbox"/> PRN 32 |
| <input type="checkbox"/> PRN 6 | <input type="checkbox"/> PRN 15 | <input type="checkbox"/> PRN 24 | |
| <input type="checkbox"/> PRN 7 | <input type="checkbox"/> PRN 16 | <input type="checkbox"/> PRN 25 | |
| <input type="checkbox"/> PRN 8 | <input type="checkbox"/> PRN 17 | <input type="checkbox"/> PRN 26 | |
| <input type="checkbox"/> PRN 9 | <input type="checkbox"/> PRN 18 | <input type="checkbox"/> PRN 27 | |



Elevation Mask Angle

Force GPS Only



— North (m) — East (m) — Down (m) — DR mode

Timing

Start

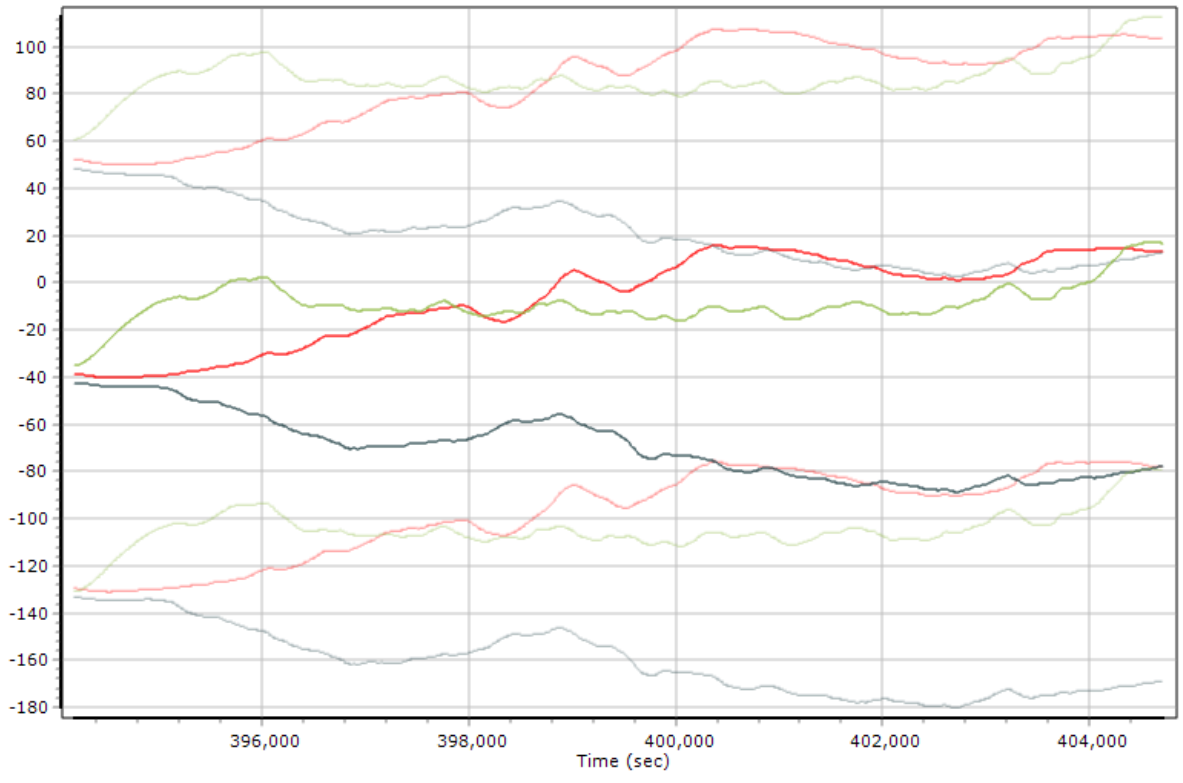
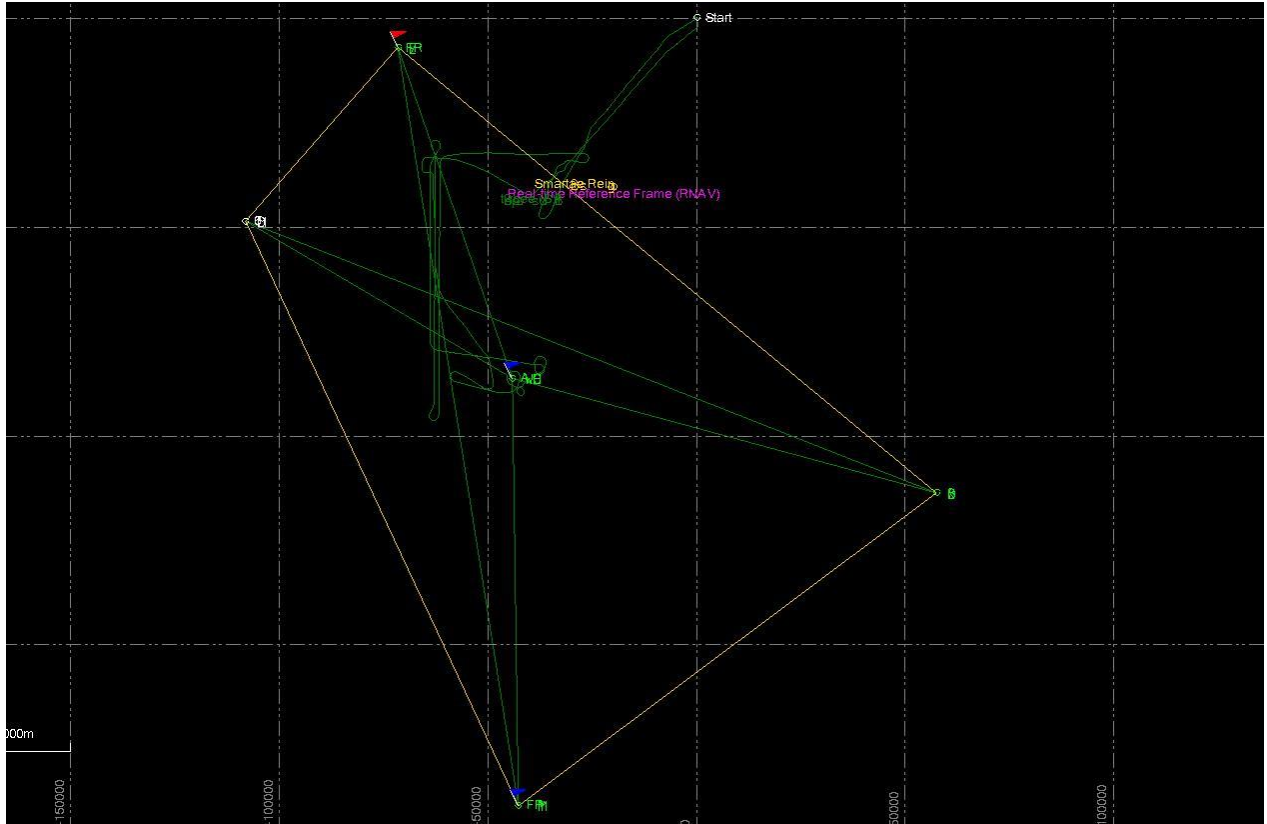
End

Entire time interval

Seconds of start week

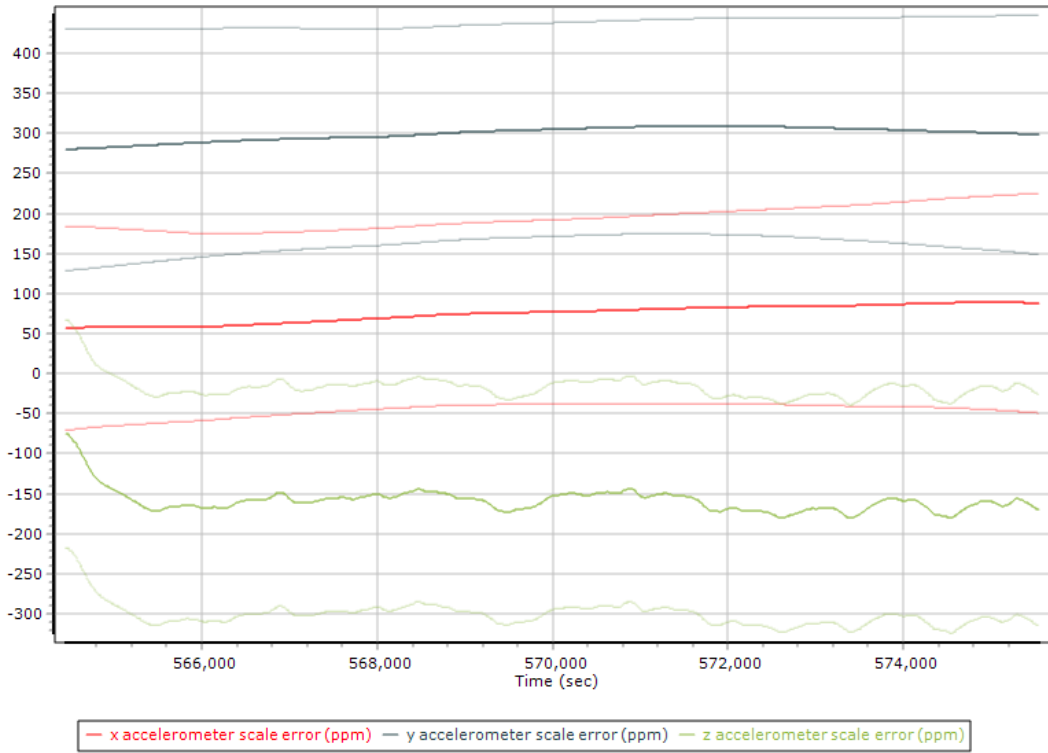
UTC Offset

Data	Incr. (sec)
Output Record	0.005000
IMU	0.005000
Primary GNSS	1.000000

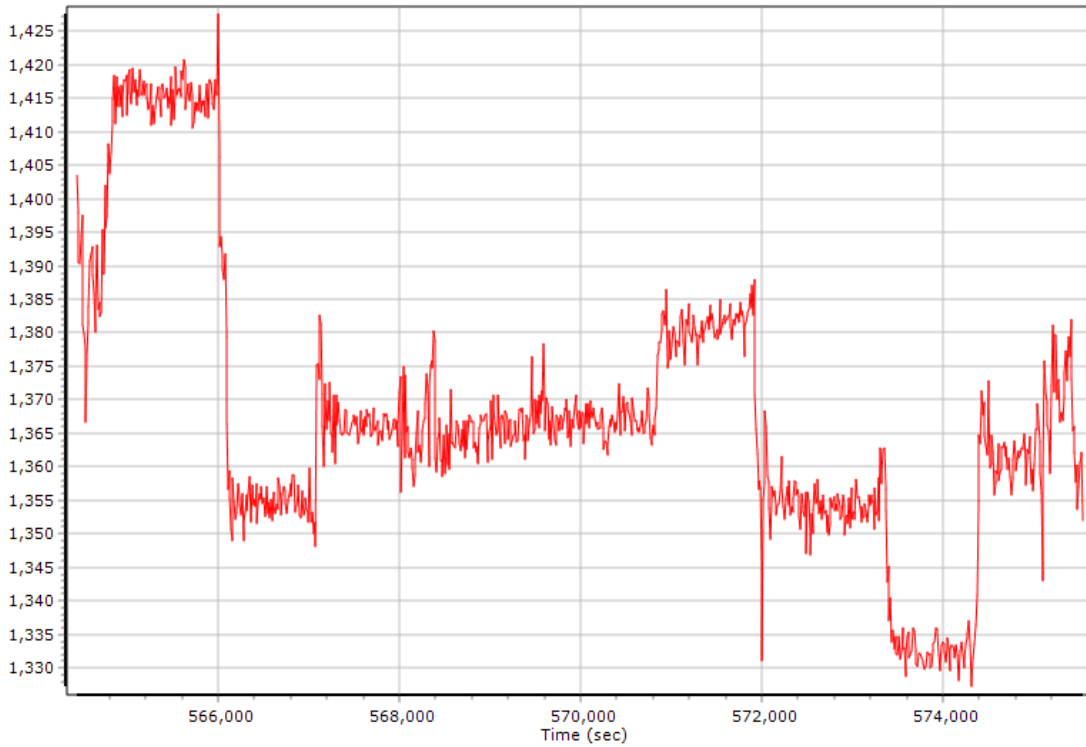


— x accelerometer bias (micro-g) — y accelerometer bias (micro-g) — z accelerometer bias (micro-g)

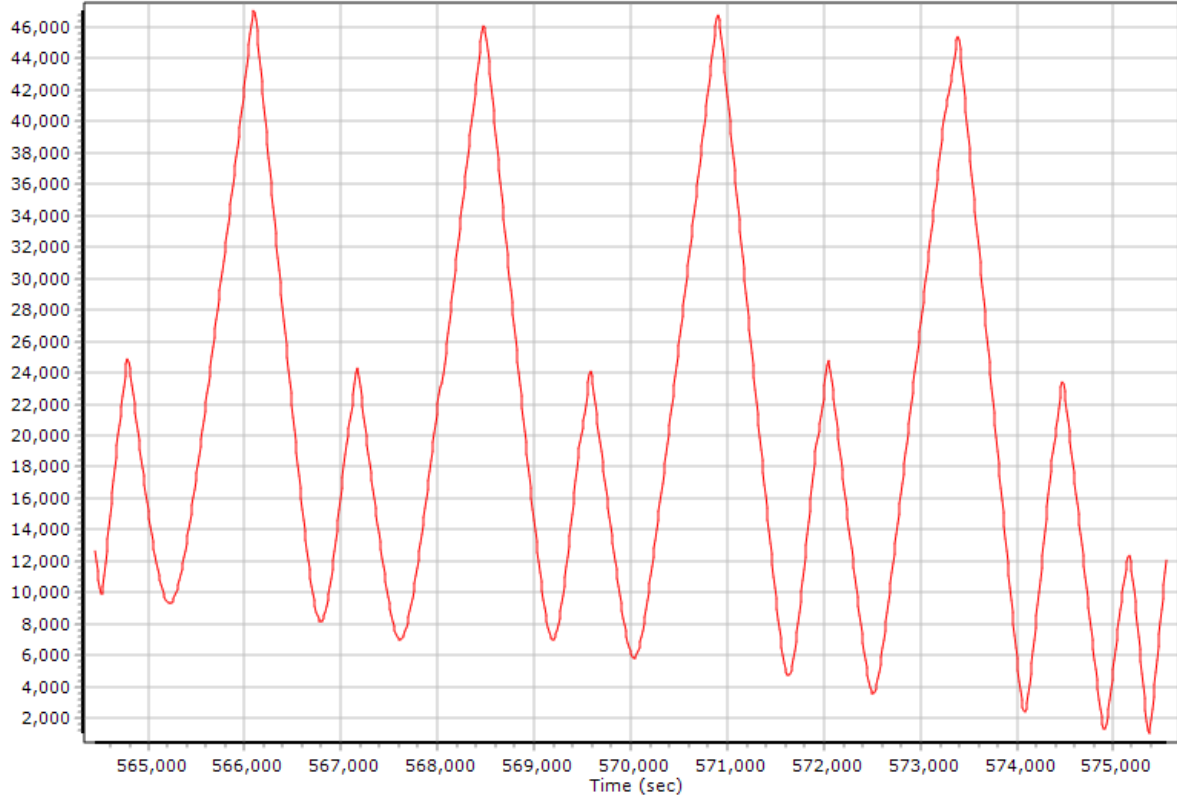
MISSION: PTG19096A

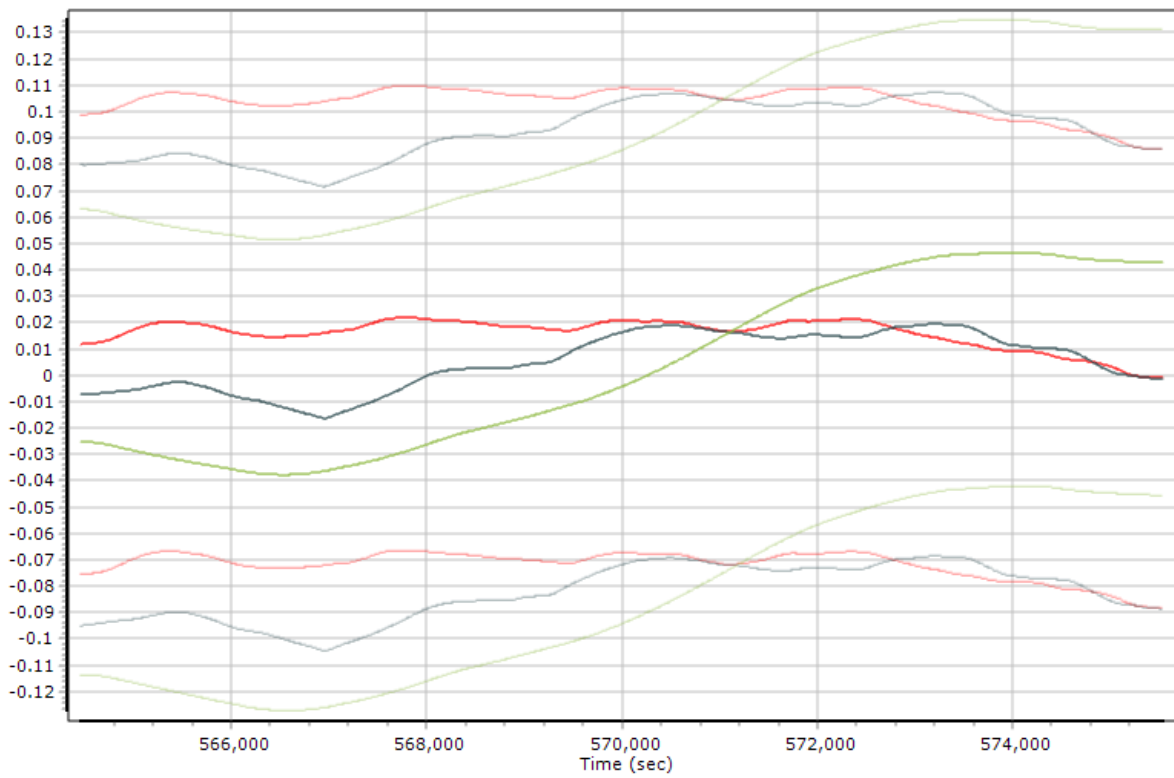


Altitude (m)

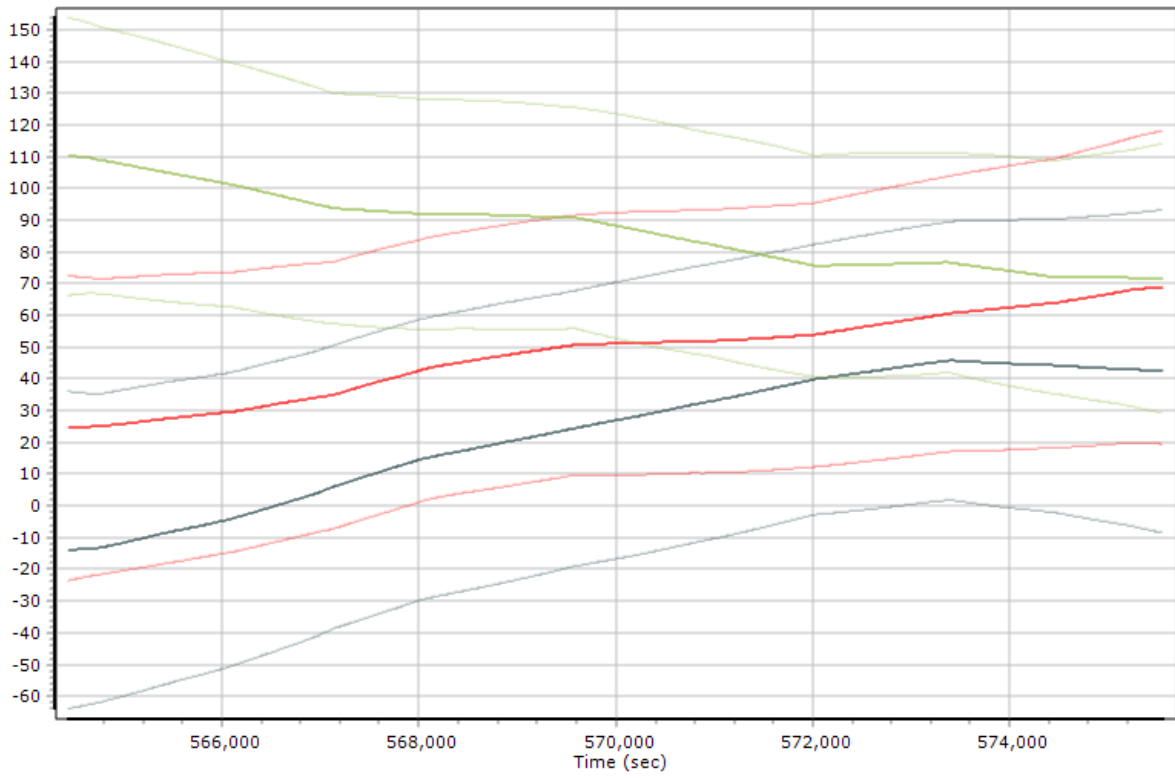


Baseline Length(m)





— x gyro bias (deg/hr) — y gyro bias (deg/hr) — z gyro bias (deg/hr)



— x gyro scale error (ppm) — y gyro scale error (ppm) — z gyro scale error (ppm)

Stabilized Mount to IMU Lever Arm

X
Y
Z

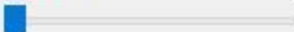
Stabilized Mount to IMU Mounting Angles

X
Y
Z

Stabilized Mount to Primary GNSS Lever Arm

X
Y
Z

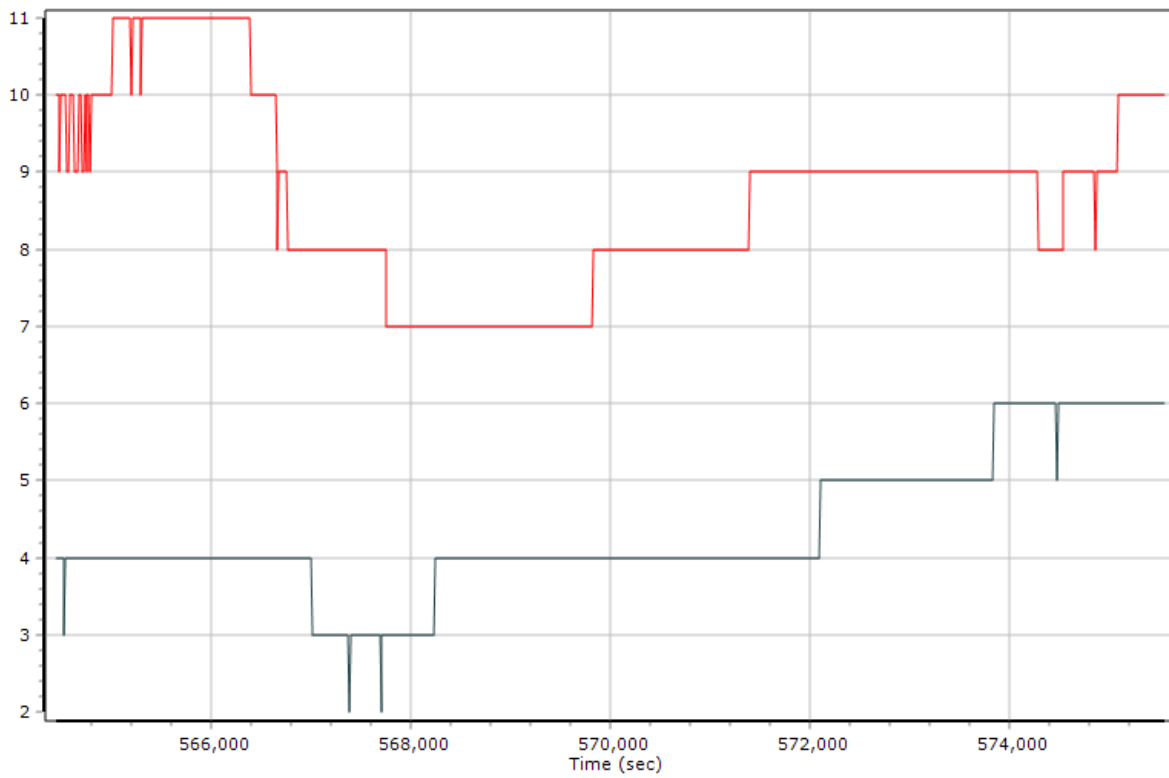
Standard Deviation


<3cm 10cm 50cm 1m 10m

Aircraft to Stabilized Mount Mounting Angles

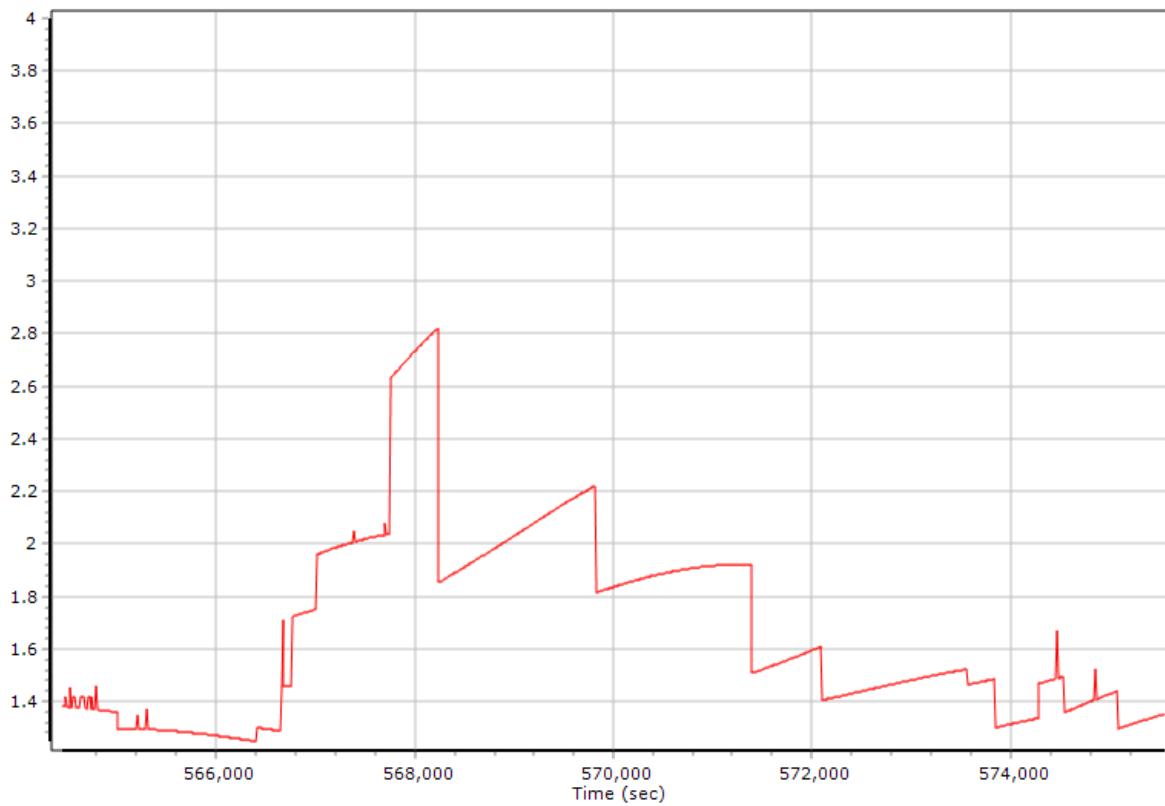
X
Y
Z

Measurements are to the stabilized platform's center of rotation with the Gimbal in the rest position.

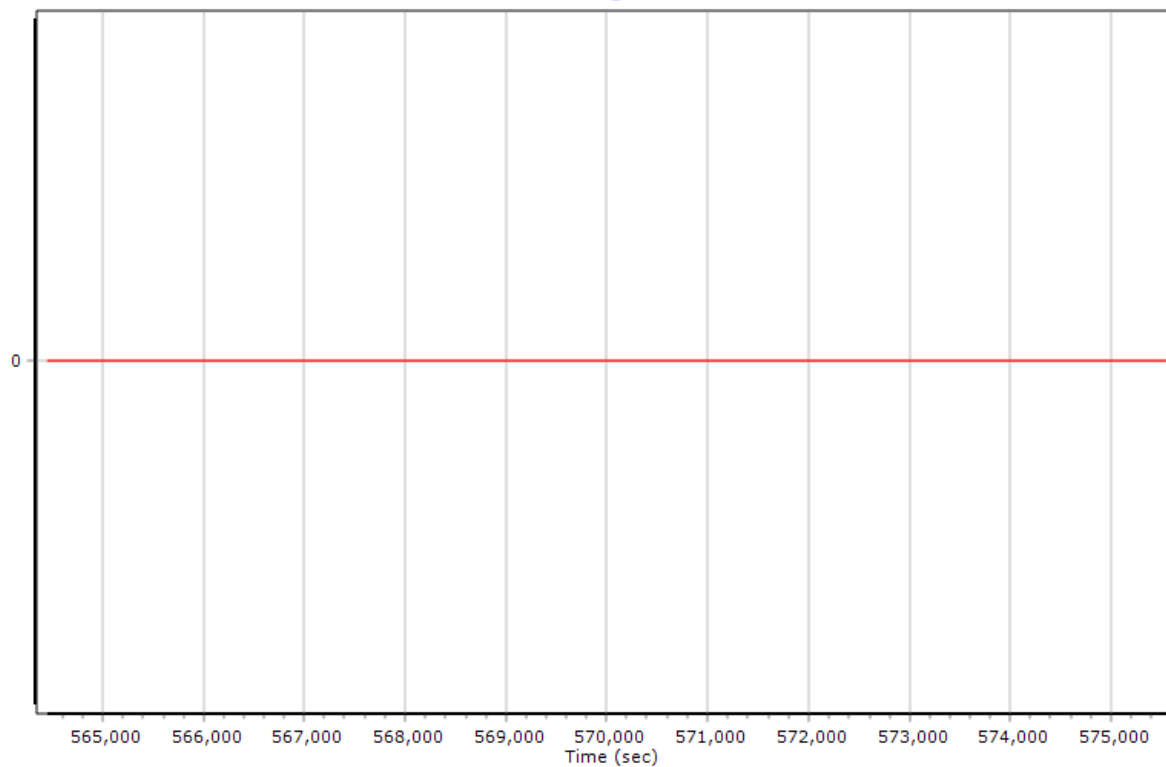


— Number of GPS Satellites — Number of GLONASS Satellites

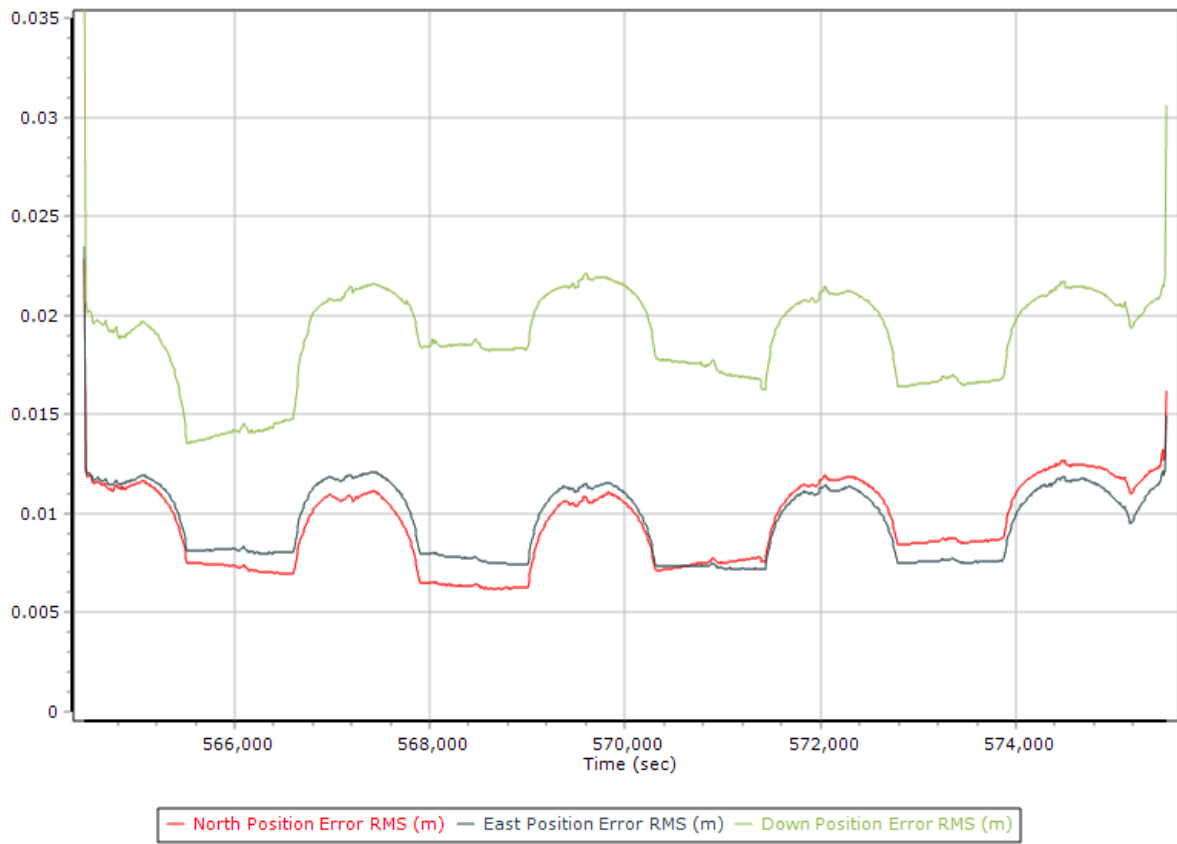
PDOP

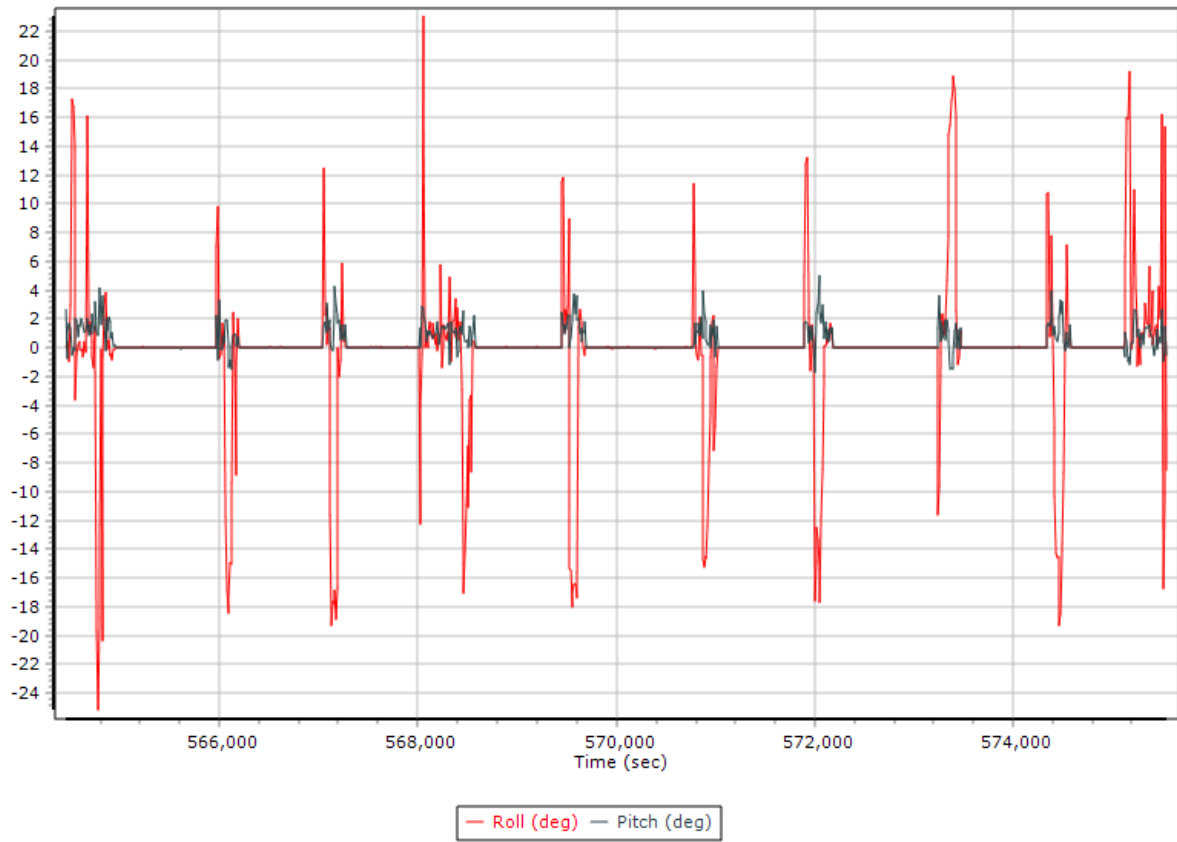


Processing Mode



0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = C/A, 7 = GNSS Nav, 8 = DR





Disable Satellites

GPS GLONASS BEIDOU QZSS

- | | | |
|---------------------------------|----------------------------------|----------------------------------|
| <input type="checkbox"/> SLOT 1 | <input type="checkbox"/> SLOT 10 | <input type="checkbox"/> SLOT 19 |
| <input type="checkbox"/> SLOT 2 | <input type="checkbox"/> SLOT 11 | <input type="checkbox"/> SLOT 20 |
| <input type="checkbox"/> SLOT 3 | <input type="checkbox"/> SLOT 12 | <input type="checkbox"/> SLOT 21 |
| <input type="checkbox"/> SLOT 4 | <input type="checkbox"/> SLOT 13 | <input type="checkbox"/> SLOT 22 |
| <input type="checkbox"/> SLOT 5 | <input type="checkbox"/> SLOT 14 | <input type="checkbox"/> SLOT 23 |
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| <input type="checkbox"/> SLOT 7 | <input type="checkbox"/> SLOT 16 | |
| <input type="checkbox"/> SLOT 8 | <input type="checkbox"/> SLOT 17 | |
| <input type="checkbox"/> SLOT 9 | <input type="checkbox"/> SLOT 18 | |

Elevation Mask Angle

Force GPS Only

Disable Satellites

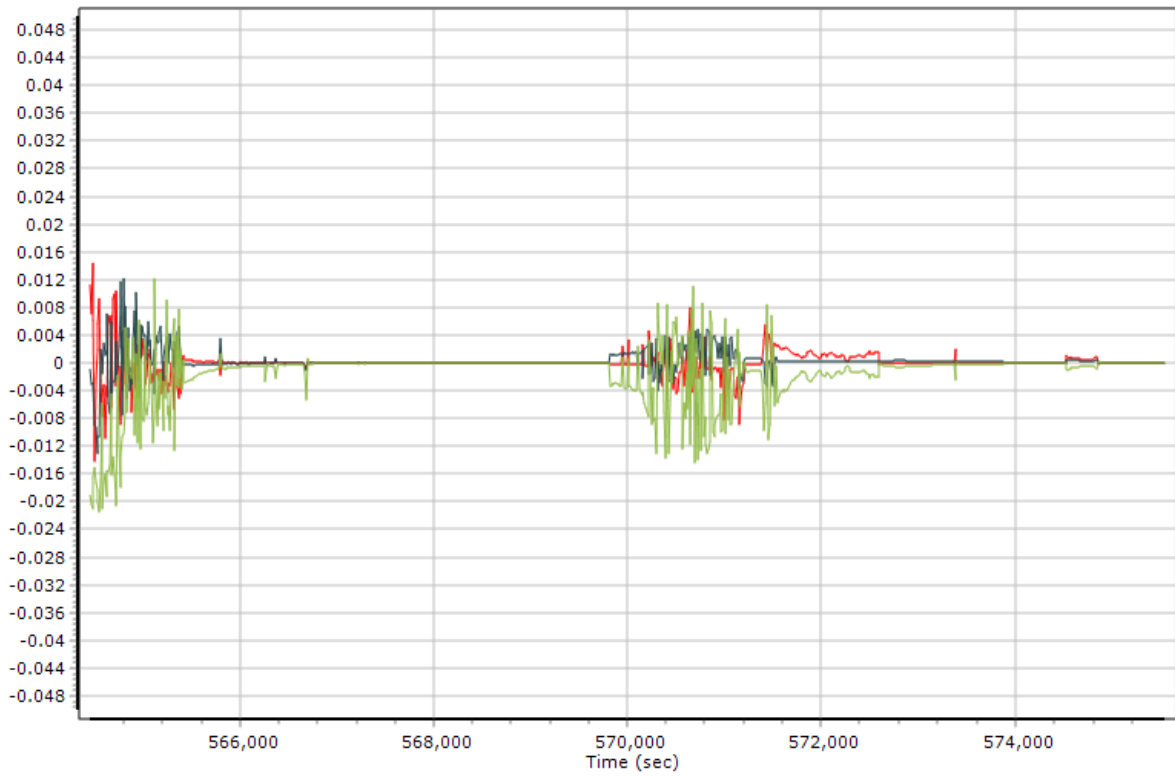
GPS GLONASS BEIDOU QZSS

- | | | | |
|--------------------------------|---------------------------------|---------------------------------|---------------------------------|
| <input type="checkbox"/> PRN 1 | <input type="checkbox"/> PRN 10 | <input type="checkbox"/> PRN 19 | <input type="checkbox"/> PRN 28 |
| <input type="checkbox"/> PRN 2 | <input type="checkbox"/> PRN 11 | <input type="checkbox"/> PRN 20 | <input type="checkbox"/> PRN 29 |
| <input type="checkbox"/> PRN 3 | <input type="checkbox"/> PRN 12 | <input type="checkbox"/> PRN 21 | <input type="checkbox"/> PRN 30 |
| <input type="checkbox"/> PRN 4 | <input type="checkbox"/> PRN 13 | <input type="checkbox"/> PRN 22 | <input type="checkbox"/> PRN 31 |
| <input type="checkbox"/> PRN 5 | <input type="checkbox"/> PRN 14 | <input type="checkbox"/> PRN 23 | <input type="checkbox"/> PRN 32 |
| <input type="checkbox"/> PRN 6 | <input type="checkbox"/> PRN 15 | <input type="checkbox"/> PRN 24 | |
| <input type="checkbox"/> PRN 7 | <input type="checkbox"/> PRN 16 | <input type="checkbox"/> PRN 25 | |
| <input type="checkbox"/> PRN 8 | <input type="checkbox"/> PRN 17 | <input type="checkbox"/> PRN 26 | |
| <input type="checkbox"/> PRN 9 | <input type="checkbox"/> PRN 18 | <input type="checkbox"/> PRN 27 | |



Elevation Mask Angle

Force GPS Only



— North (m) — East (m) — Down (m) — DR mode

Timing

Start

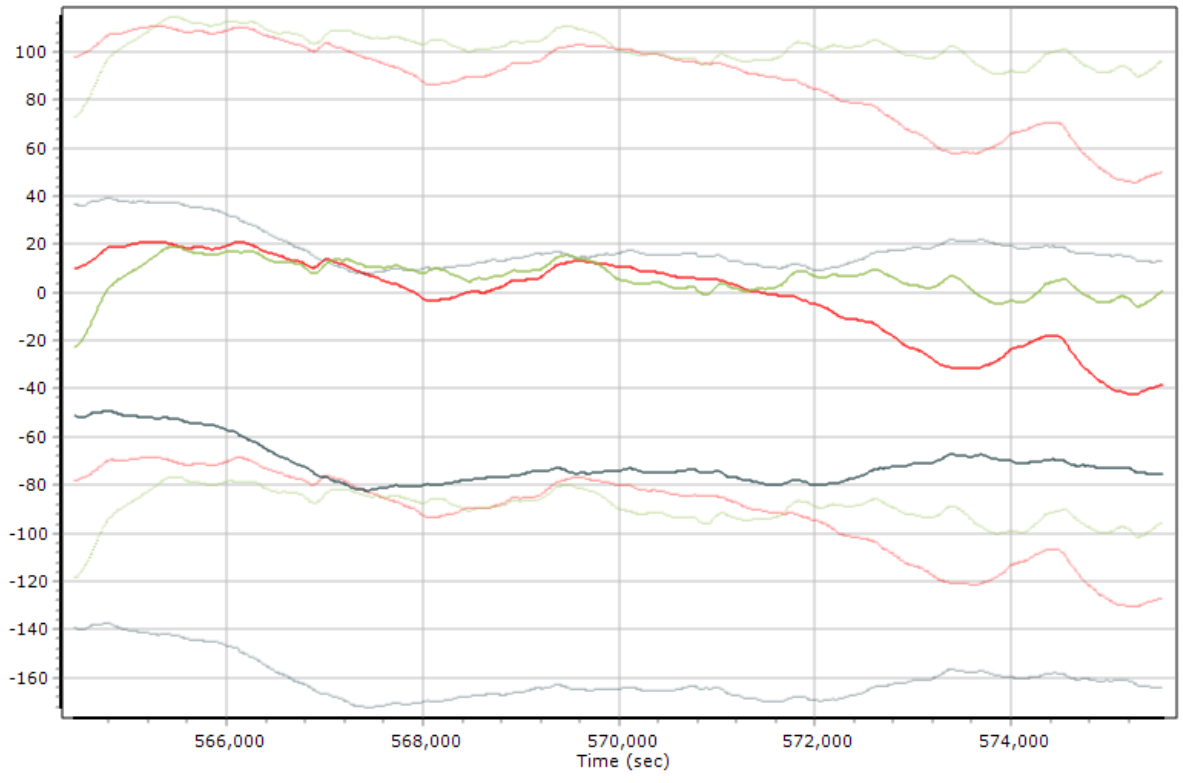
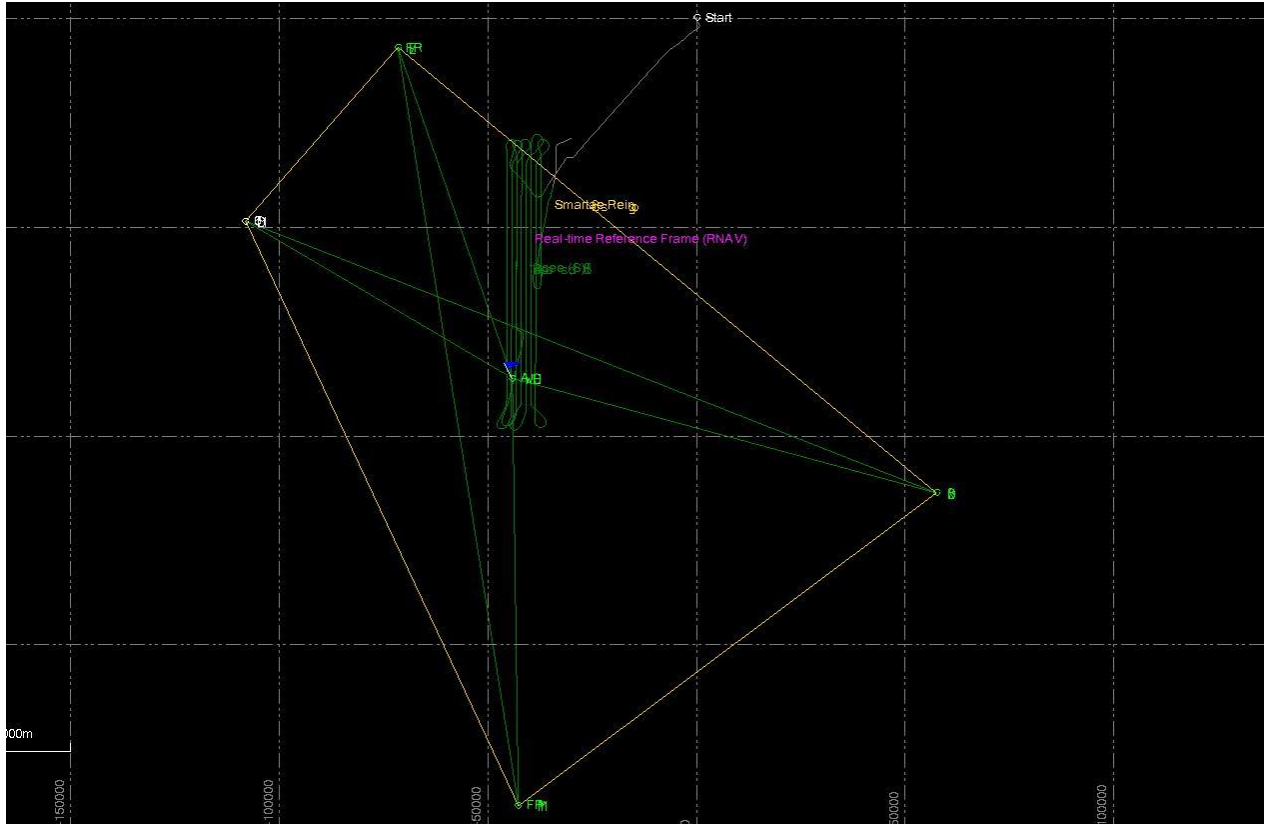
End

Entire time interval

Seconds of start week

UTC Offset

Data	Incr. (sec)
Output Record	0.005000
IMU	0.005000
Primary GNSS	1.000000



— x accelerometer bias (micro-g) — y accelerometer bias (micro-g) — z accelerometer bias (micro-g)

