

Date: 01/30/19 Time: 12:26 a.m. p.m. Employee Name: ALBERTO MARTINEZ

Job Name: Florida Peninsular LiDAR Point ID: NVA 370 BE (15078)

State: FL Latitude: 28 10 04.57213 + - Longitude: 81 40 54.78401 + -

Address and/or Intersection: KUDER RANCH RD

OBSERVATION METHOD

| | | | | | |
|--|--|-----------------------------|--|-----------------------------|------------------------|
| <input checked="" type="checkbox"/> VRS GPS | RMS: _____ H: <u>0.012</u> V: <u>0.019</u> Duration: <u>90 SECONDS</u> | | | | |
| <input type="checkbox"/> STATIC GPS | Start Time: _____ <input type="checkbox"/> a.m. <input type="checkbox"/> p.m. End Time: _____ <input type="checkbox"/> a.m. <input type="checkbox"/> p.m. | | | | |
| <input type="checkbox"/> Conventional Pairs VRS | Point Number: _____ RMS: _____ H: _____ V: _____ Duration: _____ Point Number: _____ RMS: _____ H: _____ V: _____ Duration: _____ | | | | |
| <input type="checkbox"/> Conventional Pairs STATIC | Point Number: _____ Start Time: _____ <input type="checkbox"/> a.m. <input type="checkbox"/> p.m. End Time: _____ <input type="checkbox"/> a.m. <input type="checkbox"/> p.m. Point Number: _____ Start Time: _____ <input type="checkbox"/> a.m. <input type="checkbox"/> p.m. End Time: _____ <input type="checkbox"/> a.m. <input type="checkbox"/> p.m. | | | | |
| <input type="checkbox"/> Occupied Point | Pt. #/HT: _____ / _____ | <input type="checkbox"/> BS | Pt. #/HT _____ / _____ | <input type="checkbox"/> FS | Pt. #/HT _____ / _____ |
| <input type="checkbox"/> Back Site Point | Distance: _____ Vertical Angle: _____ | | Angle: <u>00°00'00"</u> | | |
| <input type="checkbox"/> Fore Site Point | Angle: _____ Vertical Angle: _____ | | Slope Distance: _____ Horizontal Distance: _____ | | |

TYPE OF LAND COVER

- NVA: OPEN Terrain
- VVA: GWC Terrain
- VVA: BLT Terrain
- VVA: Forested
- NVA: Urban Areas
- NGS Control

PICTURES

- Picture(s) of Area & Setup

POINT RE-CHECK

Date: 05/30/19 Time: 01:00 a.m. p.m.

Re-Check Point ID: 15420

Description of Point:
IRC LB8011



