Dewberry Ground control point documentation report

Date: <u>01/02/19</u>	Time: 02:17	a.m. ⊠ p.m. Employee Name: <u>Alberto Martinez</u>	
Job Name: <u>Florid</u>	a Peninsular LiDAR	Point ID: <u>15016 (GCP AXIS 33E)</u>	
State: <u>FL</u>	Latitude: 28°52'27.60915" N	⊠ + □ – Longitude: <u>81°46′50.50486″ W</u> +	+ 🛛 –

Address and/or Intersection: 10650 CR 44, Leesburg, FL 34788

OBSERVATION METHOD

⊠	VRS GPS	RMS:	_H: <u>0.009 V:0.015</u>	Duration: <u>90 seconds</u>			
	STATIC GPS	Start Time:	t Time:□ a.m. □ p.m. End Time:			p.m. 🗆	
	Conventional	Point Number:	RMS:	H:	V: <u>Dura</u>	ation:	
	Pairs VRS	Point Number:	RMS:	H:	V:Dura	ation:	
☐ Conventional Pairs STATIC	Conventional	Point Number:	Start Time:	□ a.m. □	□ a.m. □ p.m.		
	Pairs	Point Number:	Start Time: a.m.		p.m.End Time:	□ a.m □ p.m.	
	Occupied Point	Pt. #/HT:	_/ 🗆 BS	Pt. #/HT/	D FS	Pt. #/HT/	
	Back Site Point	Distance:	Vertical Angle:		□ Angle	□ Angle00°00′00″	
	FS Point	Angle:	Vertical Angle:	Slope Distance:	Нс	rizontal Distance:	

TYPE OF SURFACE

- ☑ PAVEMENT
- □ MOWED GRASS
- □ BARE SOIL
- □ NGS Control

PICTURES

Picture(s) of Area & Setup

POINT RE-CHECK

Date:<u>01/14/19 Time:10:48 ⊠</u> a.m. □ p.m.

Re-Check Point ID: 15051

Description of Point:

SET MND " TRAV PT LB 8011"

Sketch or Image of Area





