Dewberry Ground control point documentation report

Date: 01/15/19	Time: <u>11:25</u>	a.m. 🛛 p.m. Employee Name: <u>Andrew Strickland</u>	
Job Name: <u>Florida P</u> e	eninsular LiDAR	Point ID: <u>(GCP QSI 12) 60105</u>	
State: FL	Latitude: 30°41'41.16532"N	⊠ + □ – Longitude: <u>81°27'29.30464"</u> W	□ + ⊠ –

Address and/or Intersection: Pogy Place / Parking Lot

OBSERVATION METHOD

	VRS GPS	RMS:	H: <u>0.005</u> V: <u>0.008</u>	Duration: <u>180 seconds</u>		
	STATIC GPS	Start Time: a.m. □ p.m. End Time:			a.m. 🗆 p.m. 🗆	1
□ Conventional Pairs VRS	Point Number:	RMS:	H:V:	Duration:		
	Point Number:	RMS:	H:V:	Duration:		
☐ Conventional Pairs STATIC	Point Number:	Start Time:	a.m. 🛛 p.m.End Time:		□ a.m. □ p.m.	
	Point Number:	Start Time:	a.m. 🗆 p.m.End Time:		□ a.m □ p.m.	
	Occupied Point	Pt. #/HT:	/ 🗆 BS	Pt. #/HT/	_ 🗆 FS Pt. #/H	łT/
	Back Site Point	Distance:	nce: Vertical Angle:		□ Angle00°00′00″	
	FS Point	Angle:	Vertical Angle:	Slope Distance:	Horizontal I	Distance:

TYPE OF SURFACE

- ☑ PAVEMENT
- □ MOWED GRASS
- □ BARE SOIL
- □ NGS Control

PICTURES

Picture(s) of Area & Setup

POINT RE-CHECK

Date:<u>01/16/19</u> Time:<u>02:44</u> □ a.m. ⊠ p.m.

Re-Check Point ID: 60113

Description of Point: _____

SET MND Stamped "TRAV PT LB 8011"

Sketch or Image of Area



