Dewberry Ground control point documentation report

Date: <u>01/14/19</u>	Time: 08:50	⊠ a.m. □ p.m. Employee Name: <u>Andrew Strickland</u>	
Job Name: Florid	a Peninsular LiDAR	Point ID: (GCP QSI 44) 60092	
State: FL	Latitude: <u>30°12'27.70757"N</u>	⊠ + □ – Longitude: <u>81°51'33.96870</u> "W	+ 🛛 –

Address and/or Intersection: 11485 Paceys Pond Circle

OBSERVATION METHOD

	VRS GPS	RMS:	H: <u>0.005</u> V: <u>0.008</u>	Duration: <u>180 seco</u>	nds	
	STATIC GPS	Start Time:	Start Time:□ a.m. □ p.m. End Time:			⊐ p.m. □
☐ Conventional Pairs VRS	Conventional	Point Number:	RMS:	H:	V:Du	iration:
	Pairs VRS	Point Number:	RMS:	H:	V:Du	iration:
☐ Conventional Pairs STATIC	Point Number:	Start Time: a.m. 🛛		p.m.End Time:	□ a.m. □ p.m.	
	Point Number:	Start Time: a.m. 🗆 p.m		p.m.End Time:	□ a.m □ p.m.	
	Occupied Point	Pt. #/HT:	/ □ BS	Pt. #/HT/	D FS	Pt. #/HT/
	Back Site Point	Distance:	Vertical Angle:		🗆 Angle	<u> </u>
	FS Point	Angle:	Vertical Angle:	Slope Distanc	:e:H	lorizontal Distance:

TYPE OF SURFACE

- ☑ PAVEMENT
- □ MOWED GRASS
- □ BARE SOIL
- □ NGS Control

PICTURES

Picture(s) of Area & Setup

POINT RE-CHECK

Date:_____Time:____⊠ a.m. □ p.m.

Re-Check Point ID:

Description of Point: _____

SET MND Stamped "TRAV PT LB 8011"

Sketch or Image of Area





