

Date: 02/21/19 Time: 01:14  a.m.  p.m. Employee Name: Micheal Tadros

Job Name: Florida Peninsular LiDAR Point ID: (GCP\_QSI 68) 15258

State: FL Latitude: 29°49'05.96662" N  +  - Longitude: 81°57'20.84677" W  +  -

Address and/or Intersection: Intersection of County Road 352 and Christian Camp Road

**OBSERVATION METHOD**

<input checked="" type="checkbox"/> <b>VRS GPS</b>	RMS: _____ H: <u>0.011</u> V: <u>0.017</u> Duration: <u>90 seconds</u>				
<input type="checkbox"/> <b>STATIC GPS</b>	Start Time: _____ <input type="checkbox"/> a.m. <input type="checkbox"/> p.m. End Time: _____ a.m. <input type="checkbox"/> p.m. <input type="checkbox"/>				
<input type="checkbox"/> <b>Conventional Pairs VRS</b>	Point Number: _____ RMS: _____ H: _____ V: _____ Duration: _____ Point Number: _____ RMS: _____ H: _____ V: _____ Duration: _____				
<input type="checkbox"/> <b>Conventional Pairs STATIC</b>	Point Number: _____ Start Time: _____ <input type="checkbox"/> a.m. <input type="checkbox"/> p.m. End Time: _____ <input type="checkbox"/> a.m. <input type="checkbox"/> p.m. Point Number: _____ Start Time: _____ <input type="checkbox"/> a.m. <input type="checkbox"/> p.m. End Time: _____ <input type="checkbox"/> a.m. <input type="checkbox"/> p.m.				
<input type="checkbox"/> <b>Occupied Point</b>	Pt. #/HT: _____ / _____	<input type="checkbox"/> <b>BS</b>	Pt. #/HT: _____ / _____	<input type="checkbox"/> <b>FS</b>	Pt. #/HT: _____ / _____
<input type="checkbox"/> <b>Back Site Point</b>	Distance: _____		Vertical Angle: _____	<input type="checkbox"/> <b>Angle</b>	<u>00°00'00"</u>
<input type="checkbox"/> <b>FS Point</b>	Angle: _____ Vertical Angle: _____ Slope Distance: _____ Horizontal Distance: _____				

**Sketch or Image of Area**

**TYPE OF SURFACE**

- PAVEMENT
- MOWED GRASS
- BARE SOIL
- NGS Control

**PICTURES**

- Picture(s) of Area & Setup

**POINT RE-CHECK**

Date: \_\_\_\_\_ Time: \_\_\_\_\_  a.m.  p.m.

Re-Check Point ID: \_\_\_\_\_

Description of Point: \_\_\_\_\_

**SET MAG N&D Stamped "TRAV PT LB 8011"**





