

Dewberry Ground control point documentation report

Date: 0/10/19											
Conventional Pairs VRS Point Number: Start Time: a.m. p.m.End Time: a.m. p.m.	Date: _	01/10/19	Time: <u>11:</u>	20	⊠ a.m. □	p.m. Employe	e Name: <u>Andrev</u>	w Strickland			
OBSERVATION METHOD	Job Na	ame: <u>Florida Pen</u>	insular LiDAR			Pc	oint ID: <u>(GCP QS</u>	SI 92) 60081			
OBSERVATION METHOD Ø VRS GPS RMS:											
OBSERVATION METHOD Ø VRS GPS RMS. H.0.005 V.0.008 Duration: 180 seconds □ STATIC GPS Start Time: □ a.m. □ p.m. End Time: _a.m. □ p.m. □ □ Conventional Pairs VRS Point Number: RMS: H: _V:											
VRS GPS	Addres	ss and/or Interse	ction: County R	oad 316 / A	<u>ddress 22850 (</u>	County Road 31	6				
STATIC GPS Start Time:	OBS	ERVATION	N METHOD								
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Conventional Pairs Start Time:											
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Point Distance: Vertical Angle: Angle		•	Pt. #/HT:		□BS	Pt. #/HT		□ FS	Pt. #/HT		
Angle: Vertical Angle: Slope Distance: Horizontal Distance: Sketch or Image of Area TYPE OF SURFACE PAVEMENT MOWED GRASS BARE SOIL NGS Control PICTURES Picture(s) of Area & Setup POINT RE-CHECK Date:			Distance:		Vertical Angle	:		☐ Angle	□ Angle00°00′00″		
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