General Information

Mission Information

Project name	19118_DewberryID_P1_1005
Processing date	2020-10-22 22:56:48
Mission date	2019-10-05 14:19:37
Mission duration	04:05:04.000
Processing mode	IN-Fusion PP-RTX

Rover Hardware Information

Product	POS AV 610 VER6 HW2.5-12
Serial number	S/N9273
IMU type	57
Receiver type	BD982
Antenna type	AV39

Project File List

Rover Data Files

File name	File type
20191005.724	POS Data
20191005.725	POS Data
20191005.726	POS Data
20191005.727	POS Data
20191005.728	POS Data
20191005.729	POS Data
20191005.730	POS Data
20191005.731	POS Data
20191005.732	POS Data
20191005.733	POS Data
20191005.734	POS Data
20191005.735	POS Data
20191005.736	POS Data
20191005.737	POS Data
20191005.738	POS Data
20191005.739	POS Data
20191005.740	POS Data
20191005.741	POS Data
20191005.742	POS Data
20191005.743	POS Data
20191005.744	POS Data
20191005.745	POS Data
20191005.746	POS Data
20191005.747	POS Data
20191005.748	POS Data

Input Files

File Name	File Type
Ephm2780.19g	GLONASS Broadcast Ephemeris
Ephm2780.19n	GPS Broadcast Ephemeris

Output Files

Filename	File type
sbet_Mission 1.out	SBET Trajectory File

Rover Data Summary

First raw data file	20191005.724		
Last raw data file	20191005.748		
Start GPS week	2073		
Start time	569977.056 (10/5/2019 2:19:37 PM)		
End time	584681.263 (10/5/2019 6:24:41 PM)		
Start of fine alignment	570102.803 (10/5/2019 2:21:42 PM)		
Available subsystems	Primary GNSS, IMU		
POS Event Input	None		
Correction data	None		
IMU Installation Lever Arms & Mounting Angles			
Reference to IMU lever arm (m)	0.000	0.000	0.000
Reference to IMU mounting angles (deg)	0.000	0.000	180.000
Reference to Primary GNSS lever arm (m)	-0.010	-0.315	-0.926
Reference to Primary GNSS lever arm std dev (m)	-1.000		
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

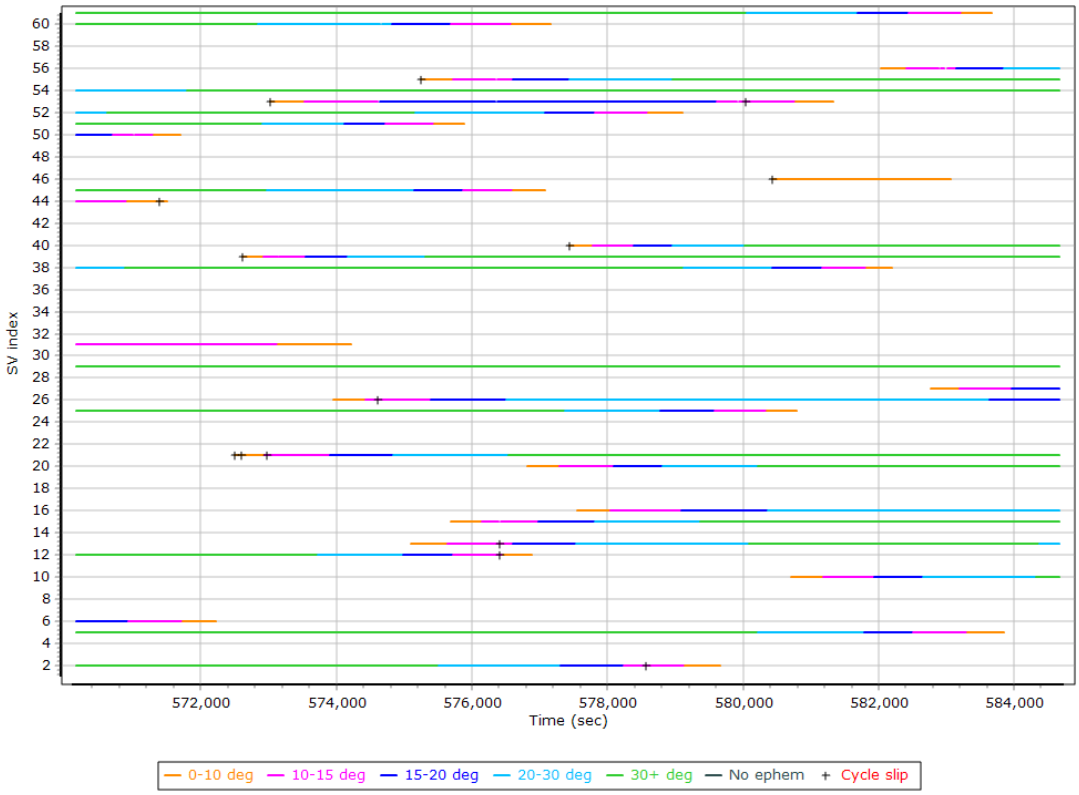
Rover Data QC

Raw IMU Import QC Summary

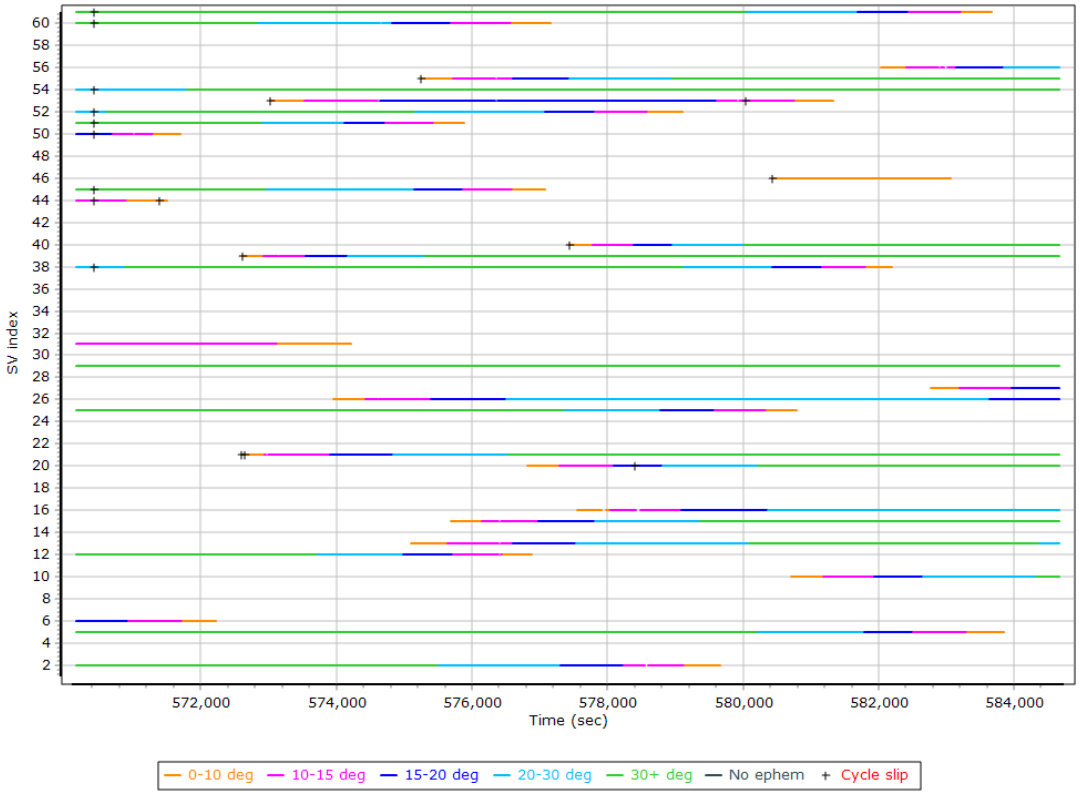
IMU data input file	imu_Mission 1.dat
IMU data check log file	imudt_Mission 1.log
IMU Records Processed	2940405
Termination Status	Normal
IMU Anomalies	0

Primary Observables & Satellite Data

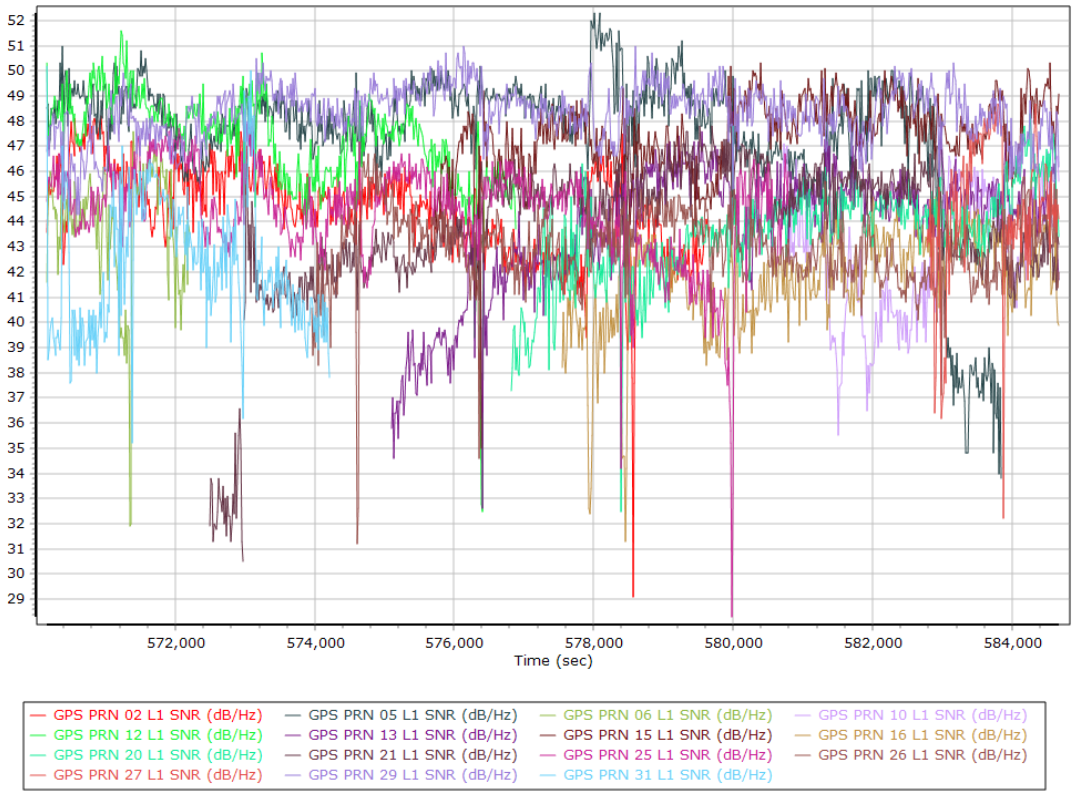
L1 Satellite Lock/Elevation



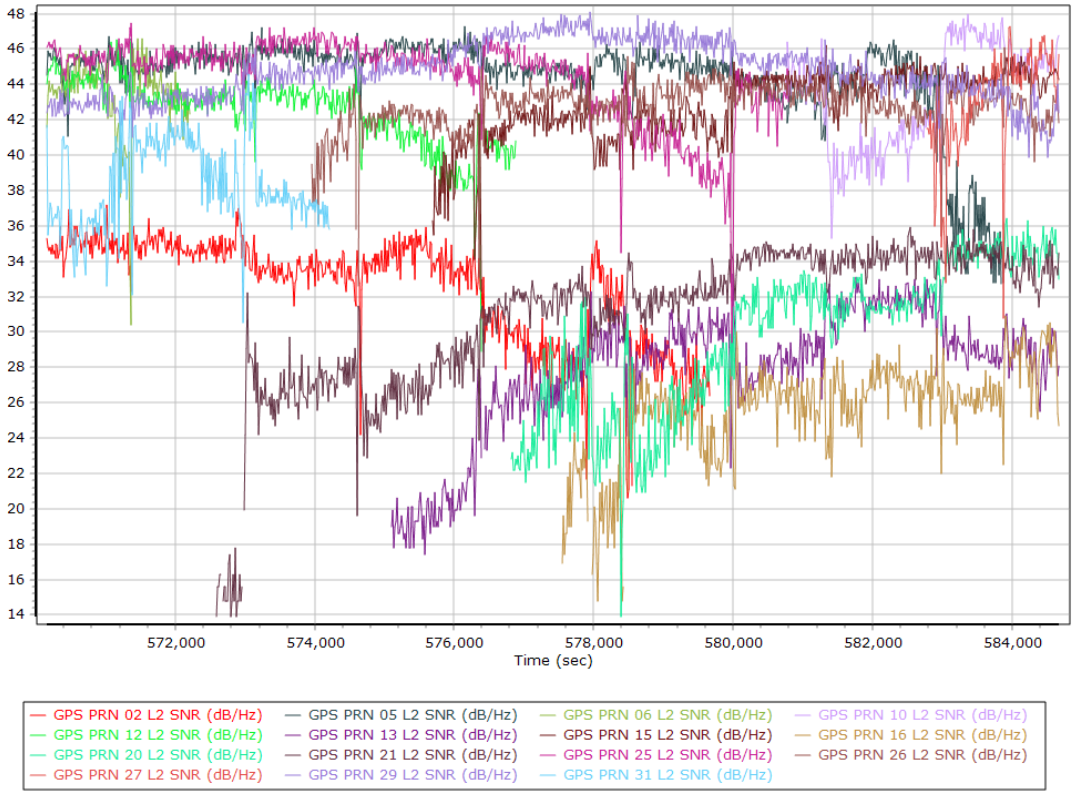
L2 Satellite Lock/Elevation



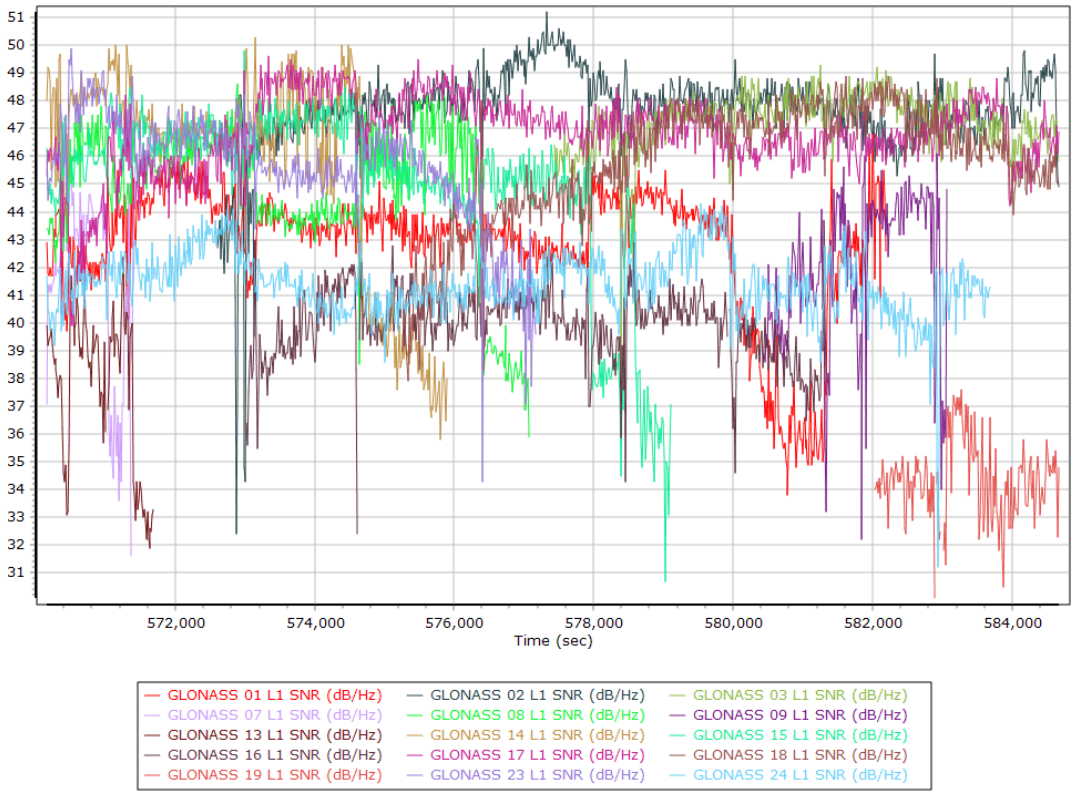
GPS L1 SNR



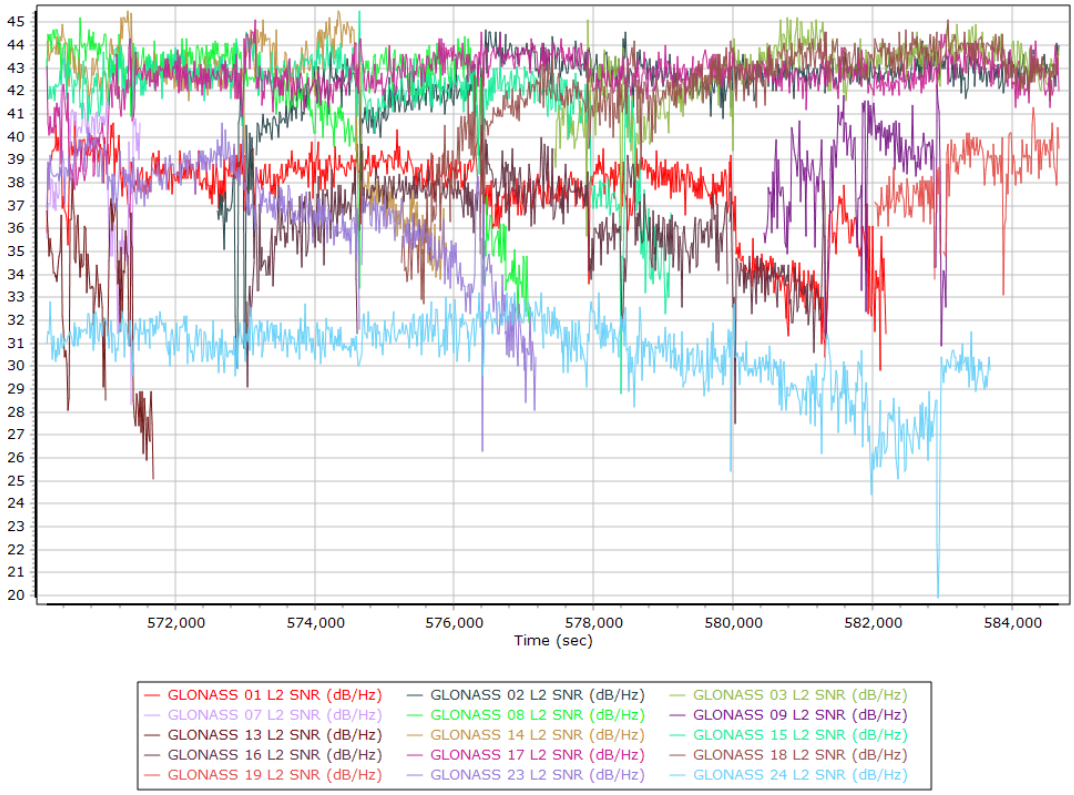
GPS L2 SNR



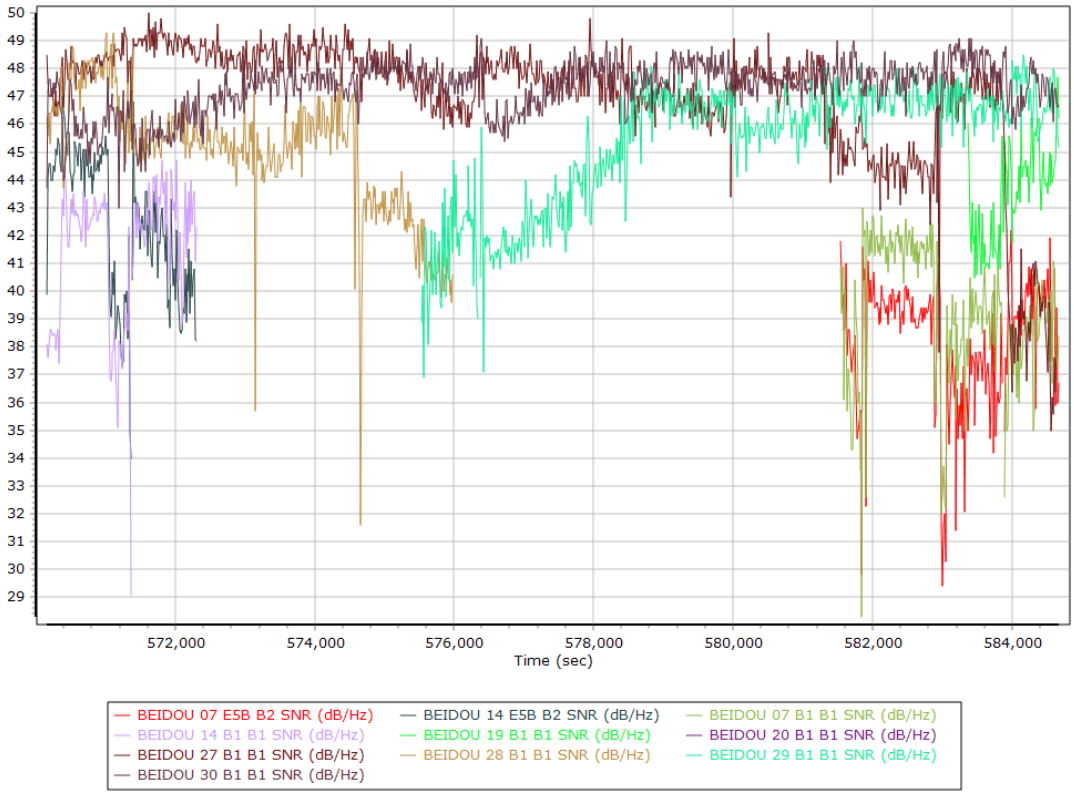
GLONASS L1 SNR



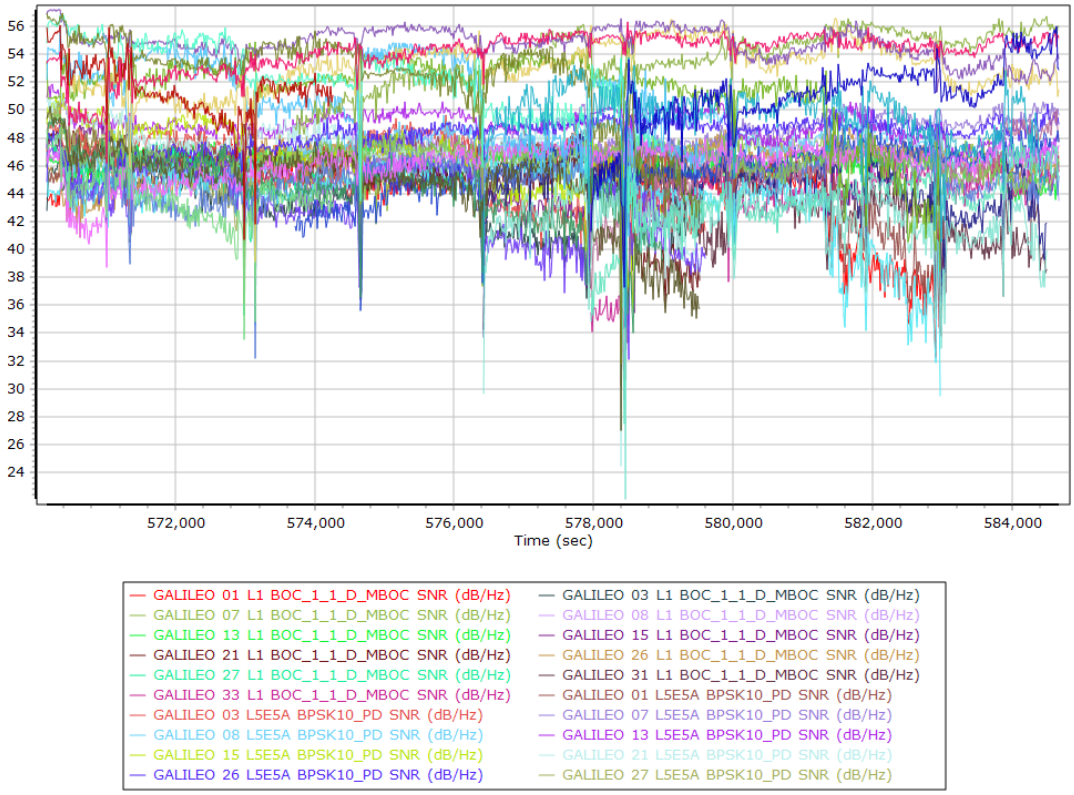
GLONASS L2 SNR



BEIDOU SNR



GALILEO SNR


56
54
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38
36
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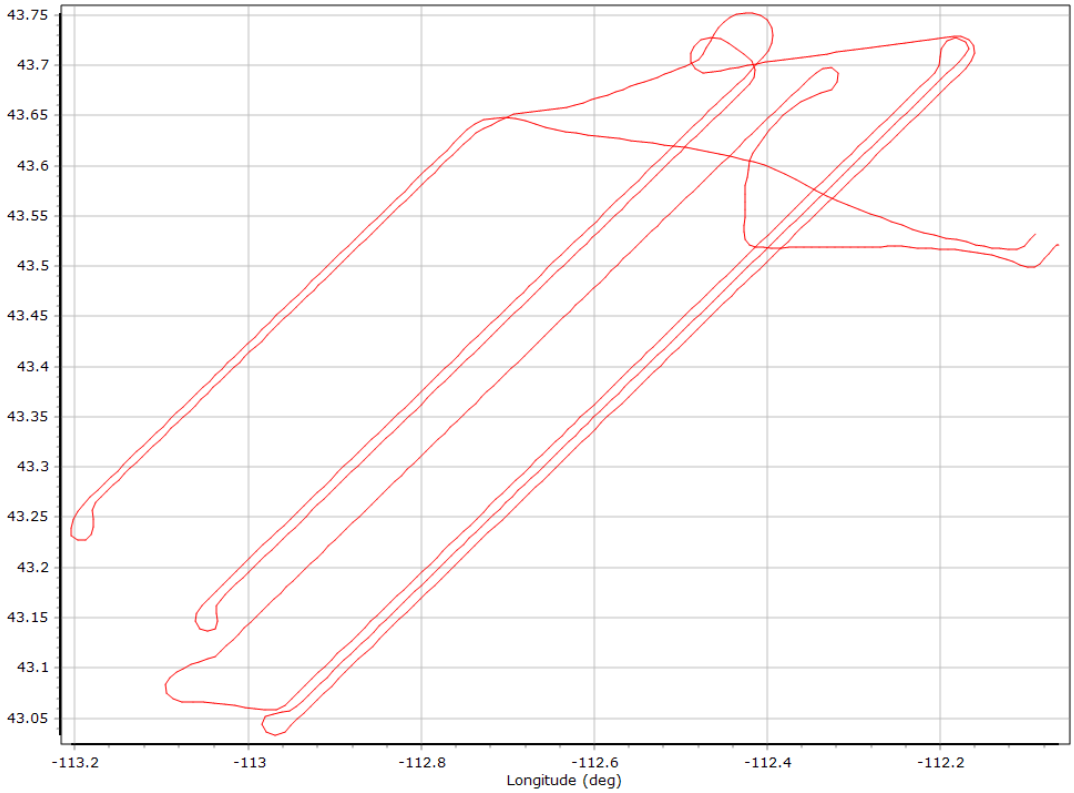
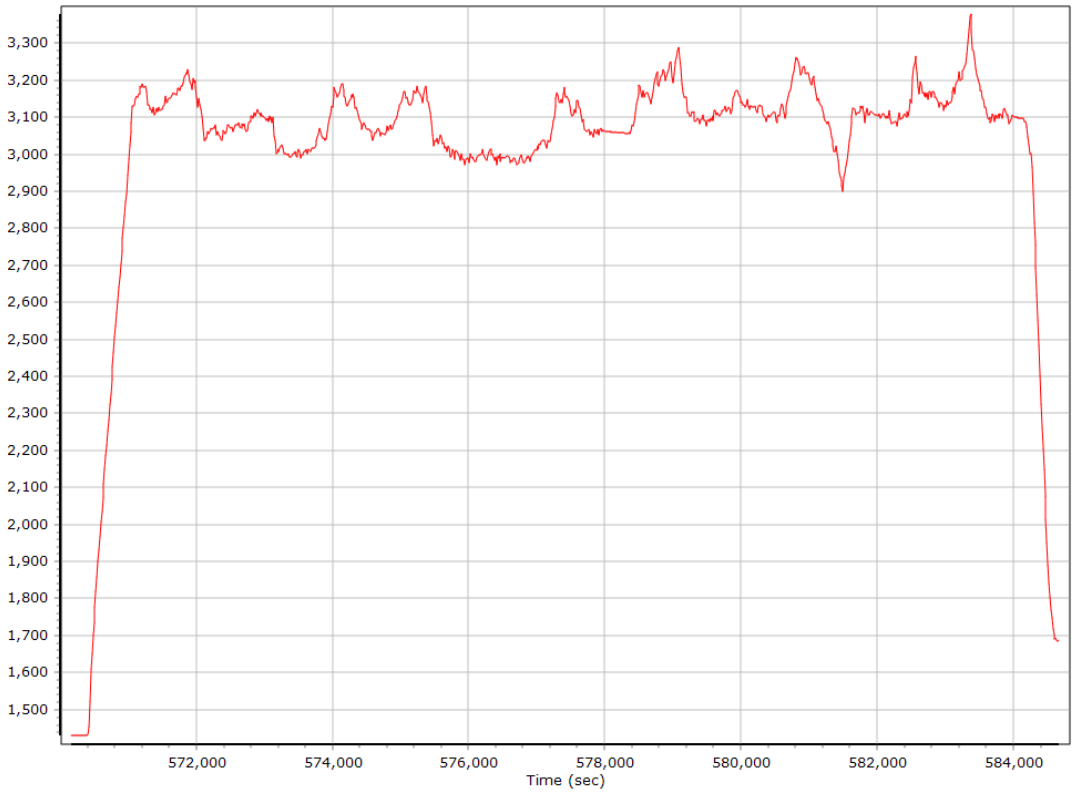
32
30
28
26
24
572,000
574,000
576,000
578,000
580,000
582,000
584,000
Time (sec)
GALILEO 01 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 03 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 07 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 08 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 13 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 15 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 21 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 26 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 27 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 31 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 33 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 01 L5E5A BPSK10_PD SNR (dB/Hz)
GALILEO 03 L5E5A BPSK10_PD SNR (dB/Hz)
GALILEO 07 L5E5A BPSK10_PD SNR (dB/Hz)
GALILEO 08 L5E5A BPSK10_PD SNR (dB/Hz)
GALILEO 13 L5E5A BPSK10_PD SNR (dB/Hz)
GALILEO 15 L5E5A BPSK10_PD SNR (dB/Hz)
GALILEO 21 L5E5A BPSK10_PD SNR (dB/Hz)
GALILEO 26 L5E5A BPSK10_PD SNR (dB/Hz)
GALILEO 27 L5E5A BPSK10_PD SNR (dB/Hz)

Smoothed Trajectory Information

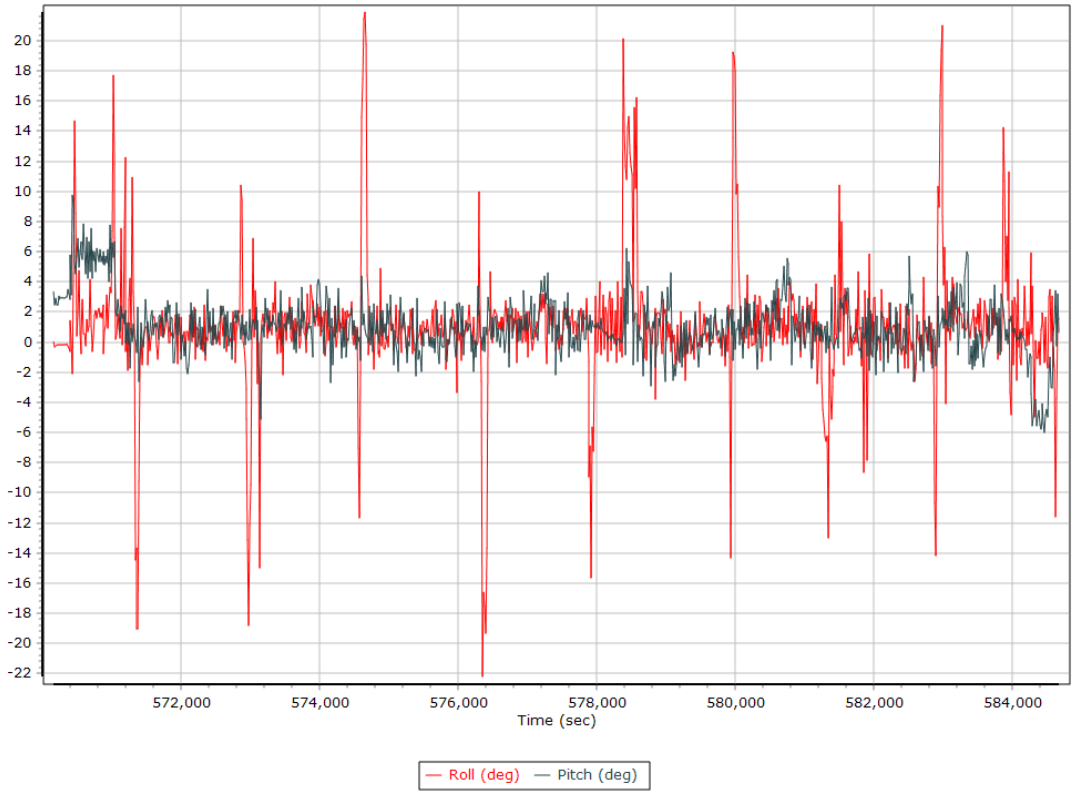
Top View



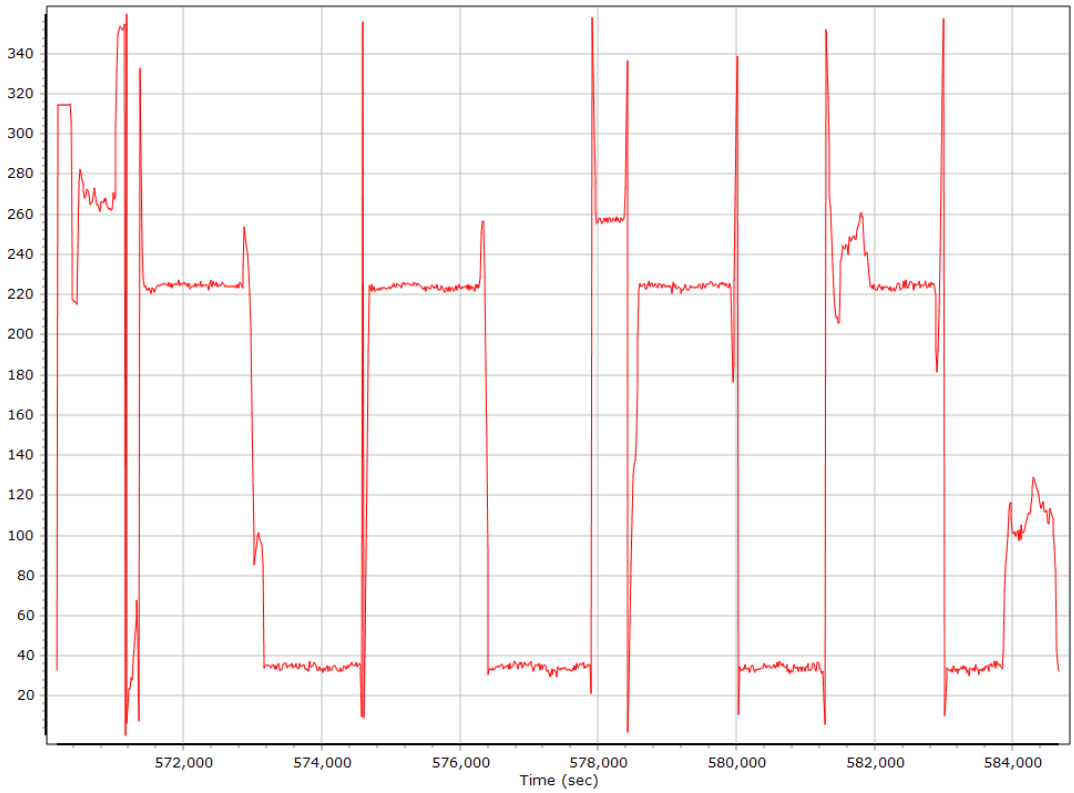
Altitude



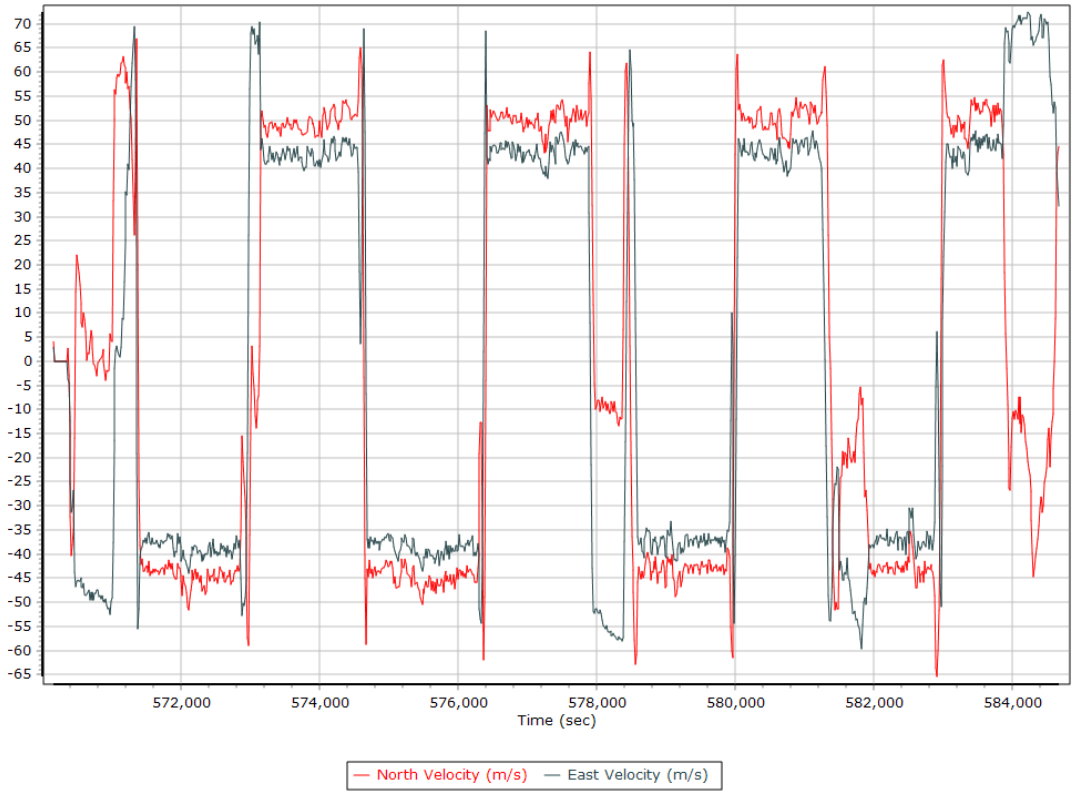
Roll/Pitch



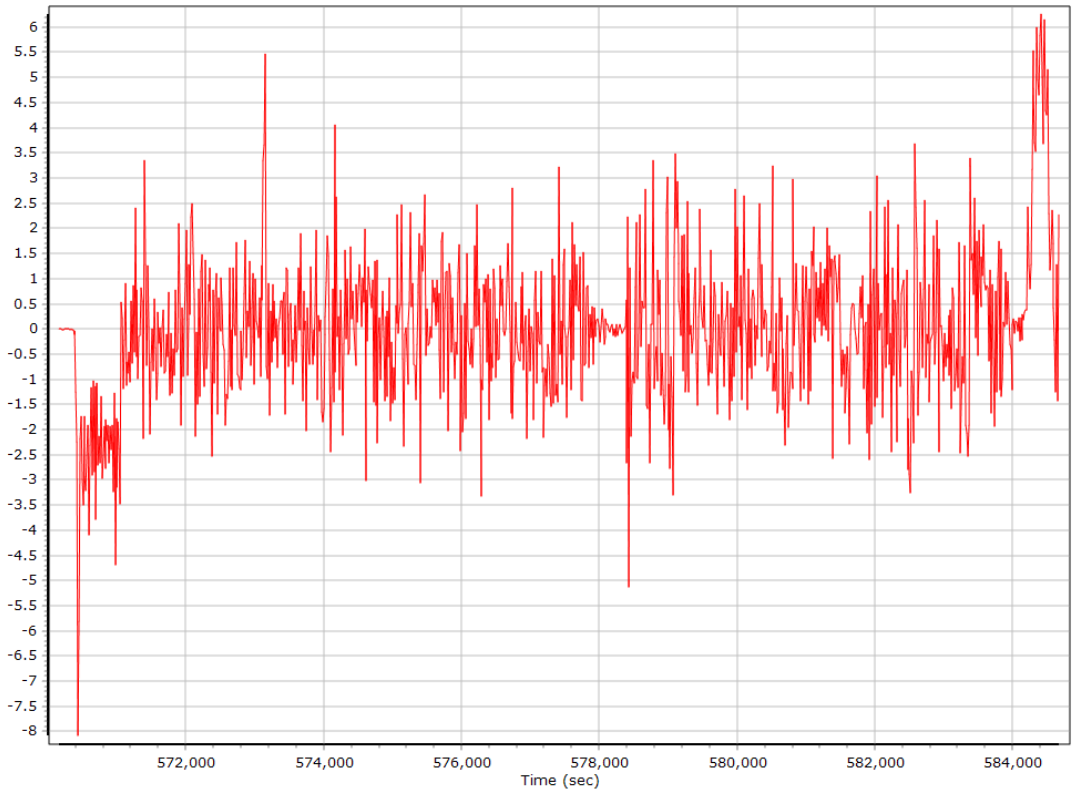
Heading



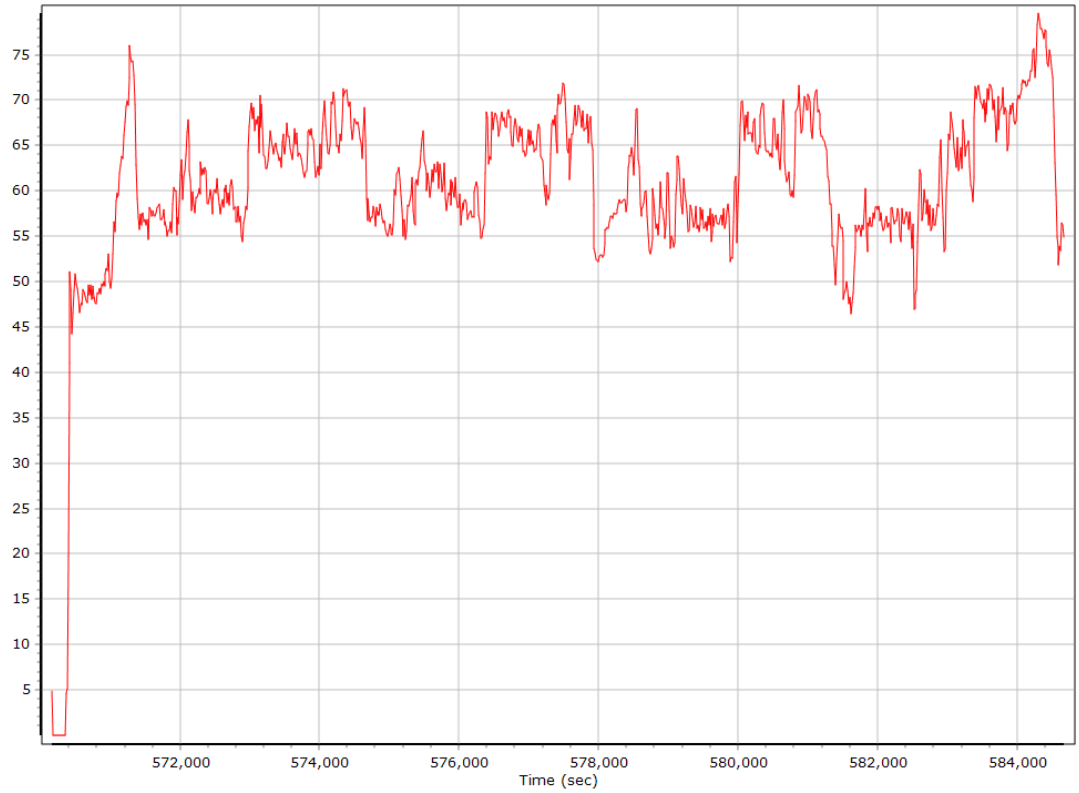
North/East Velocity



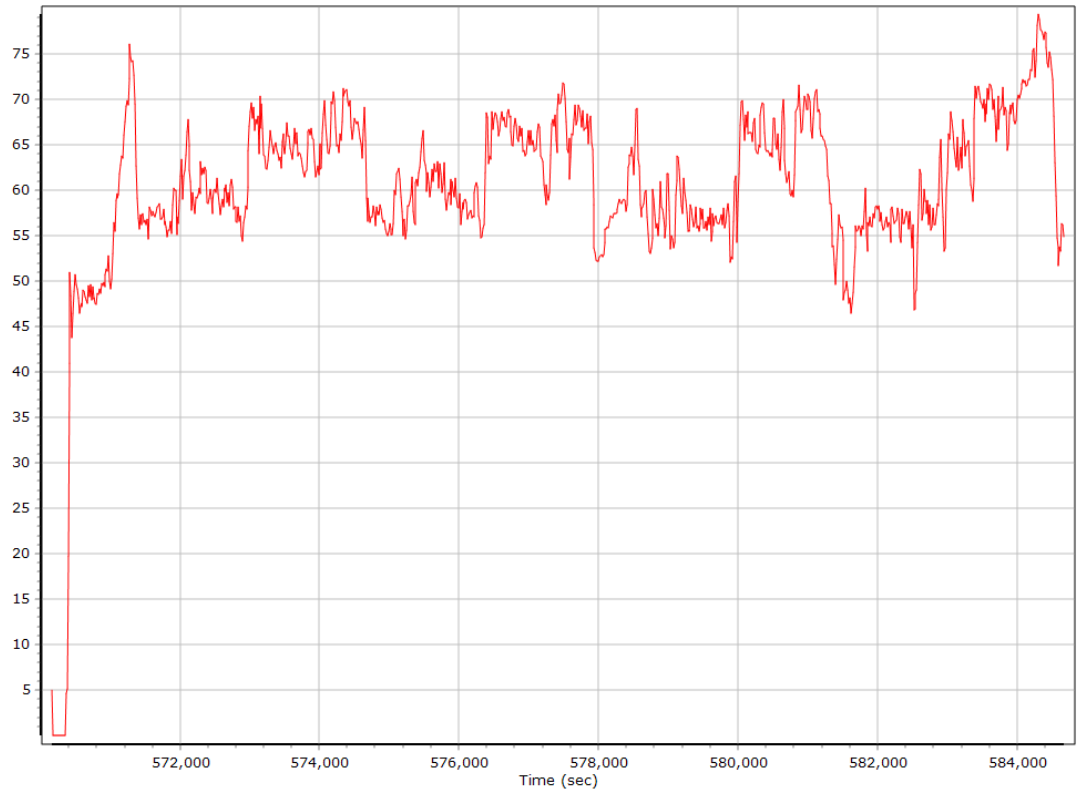
Down Velocity



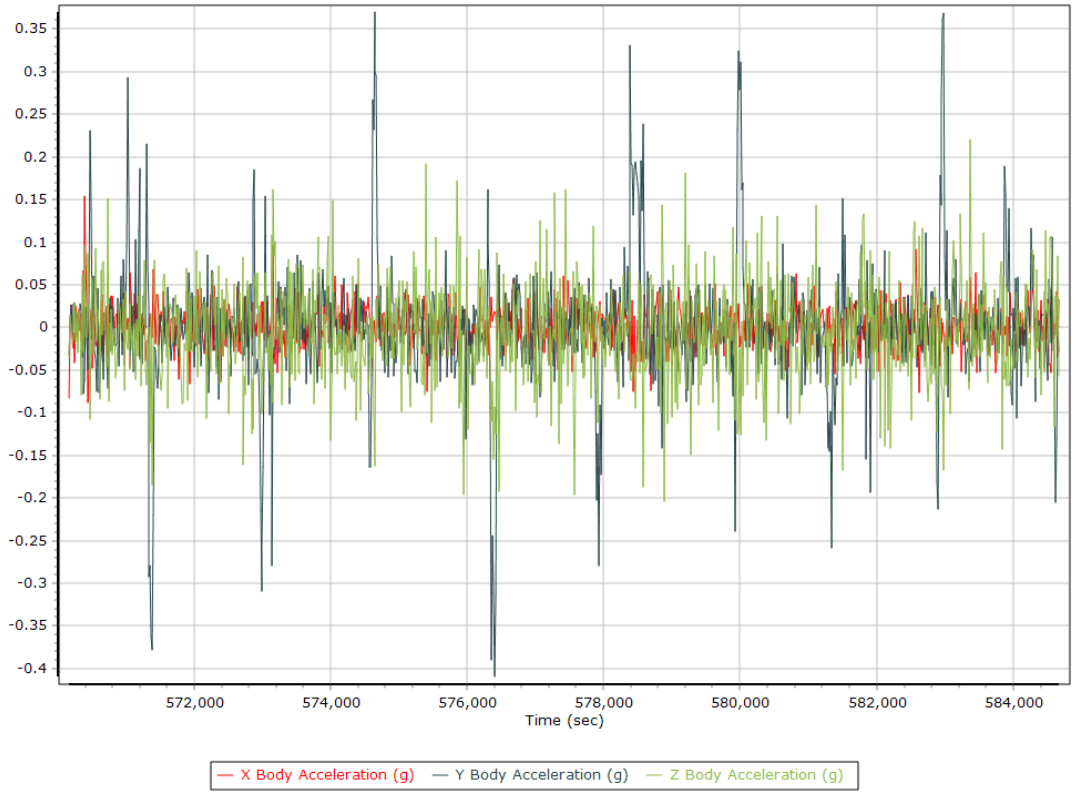
Total Speed



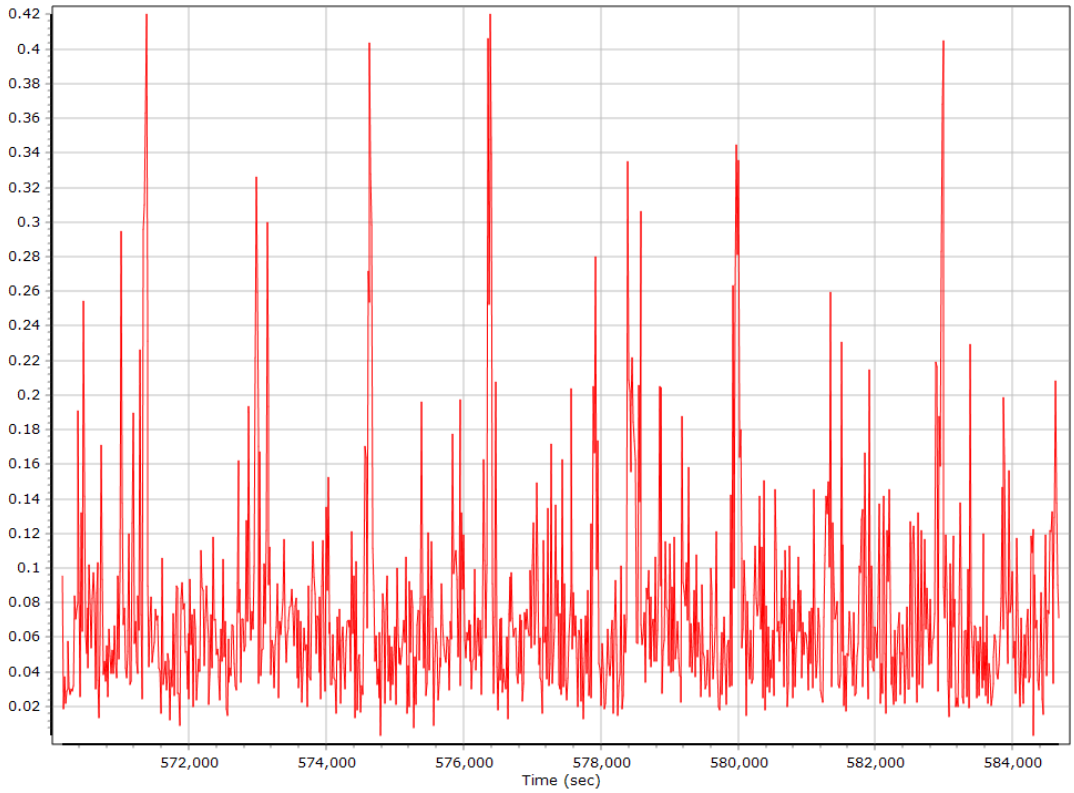
Ground Speed



Body Acceleration



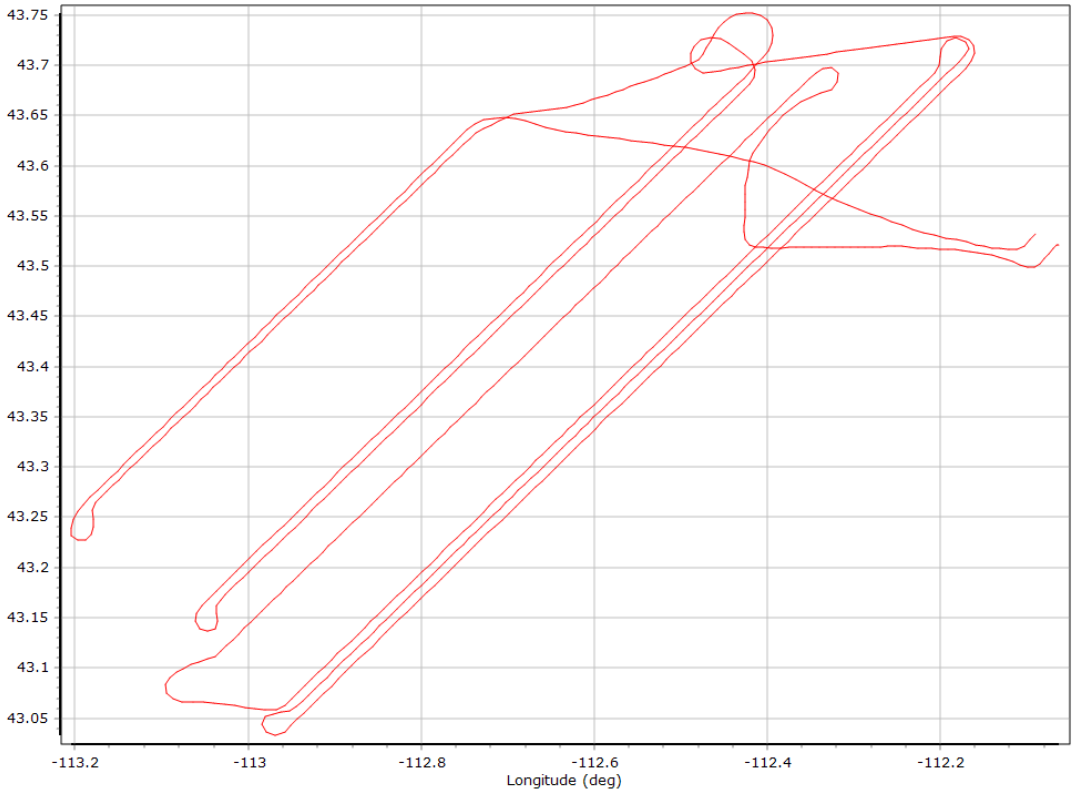
Total Body Acceleration



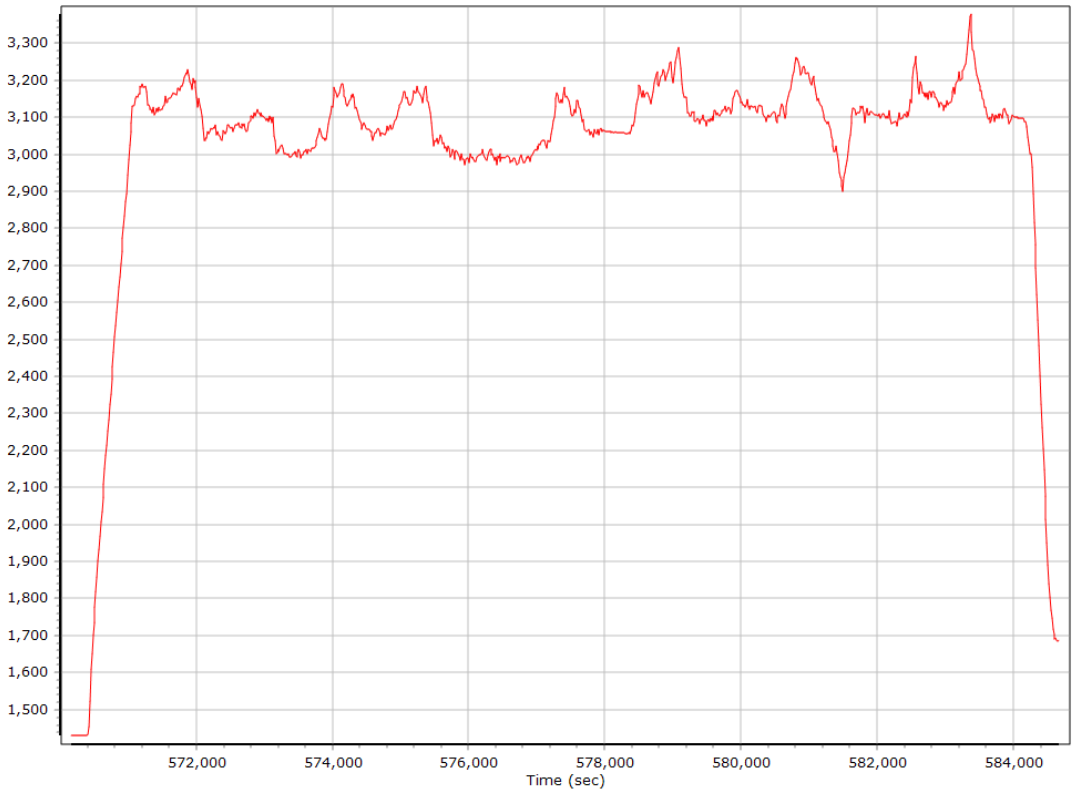
Body Angular Rate

Forward Processed Trajectory Information

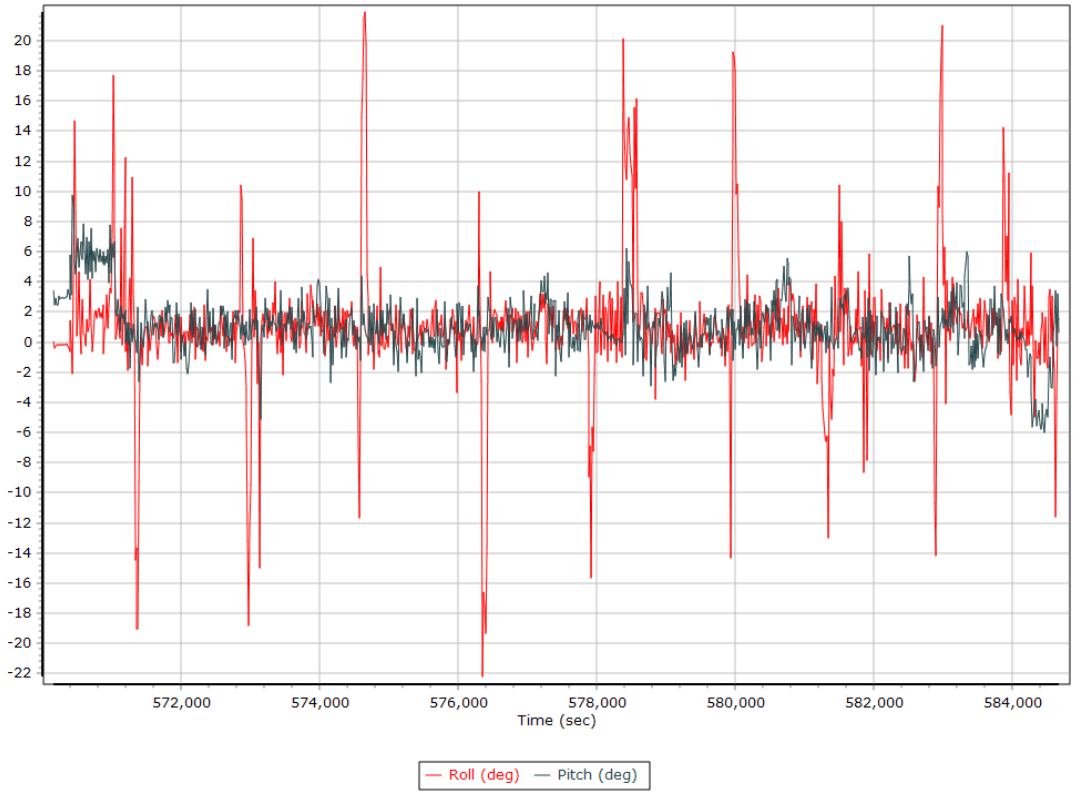
Top View



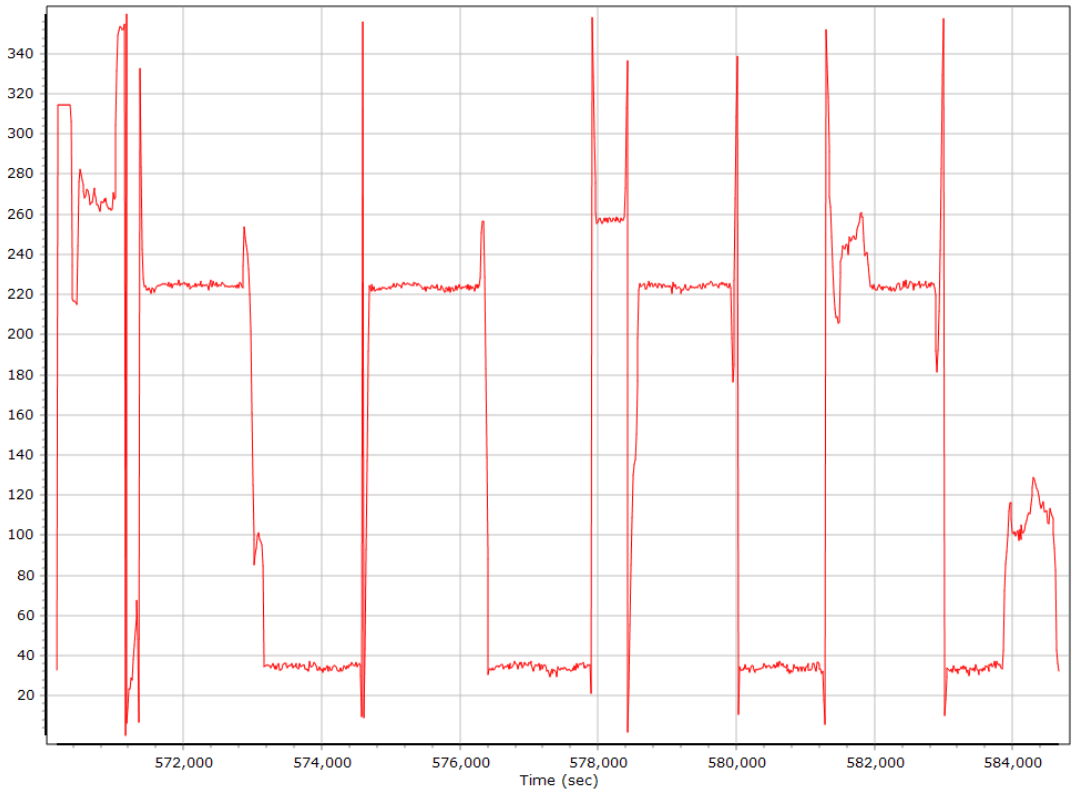
Altitude



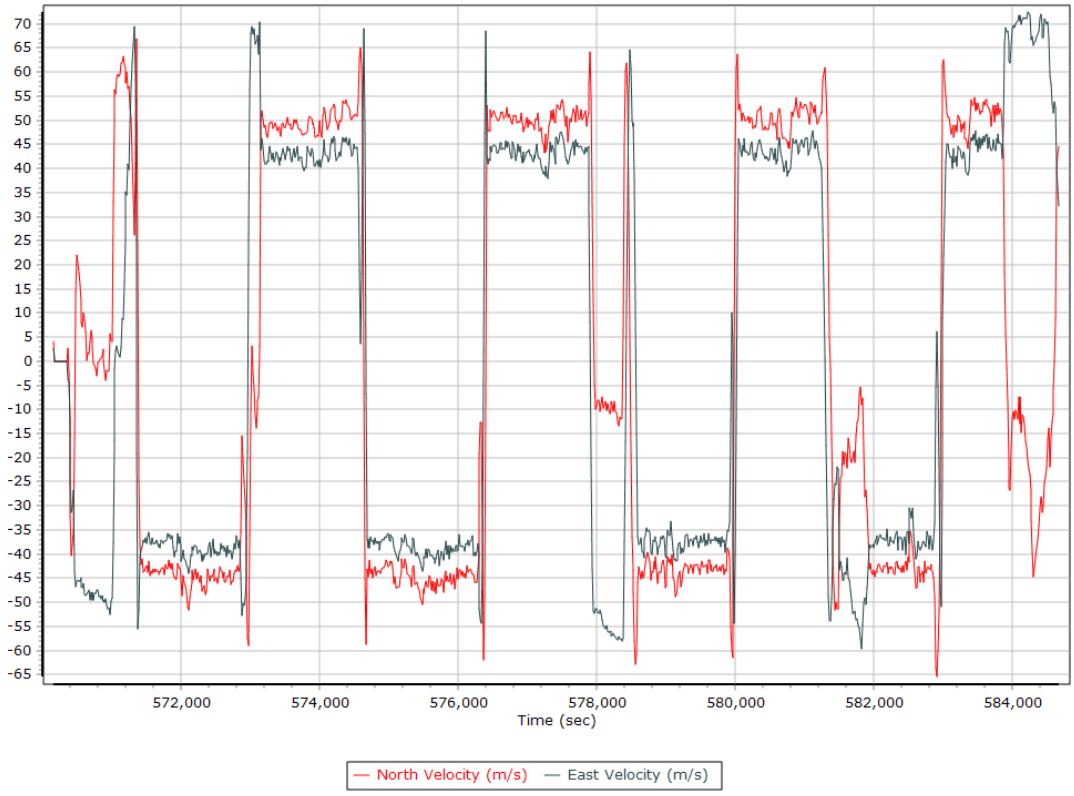
Roll/Pitch



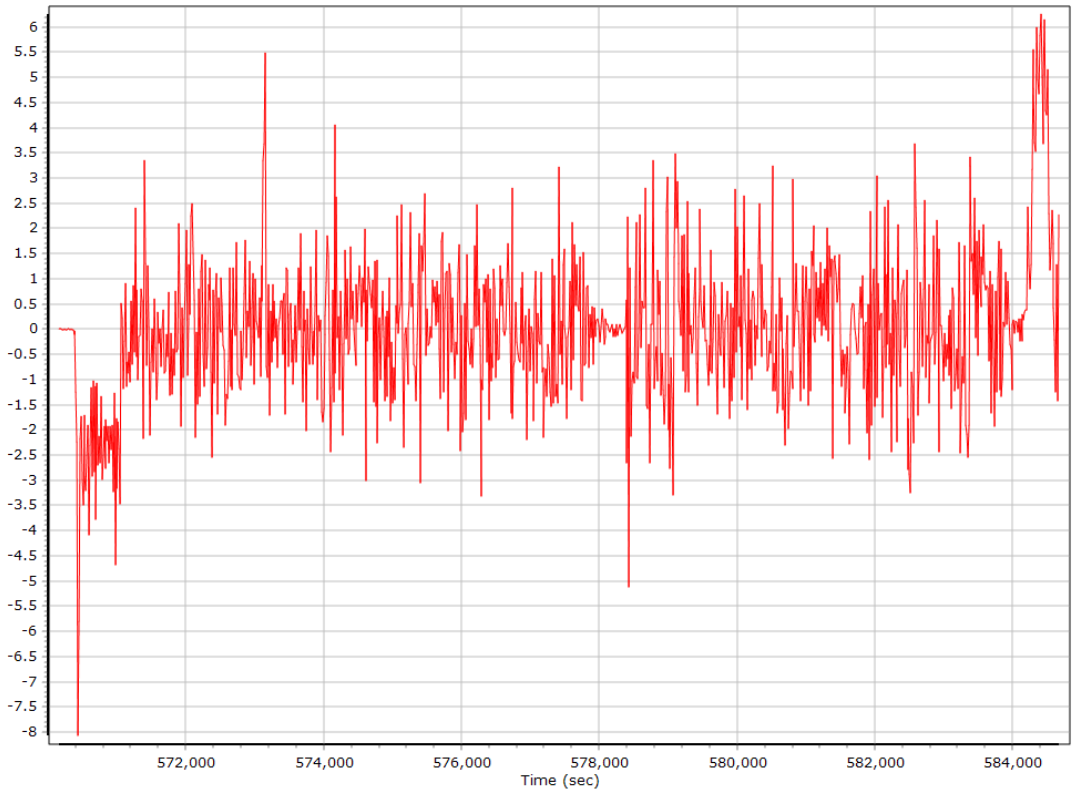
Heading



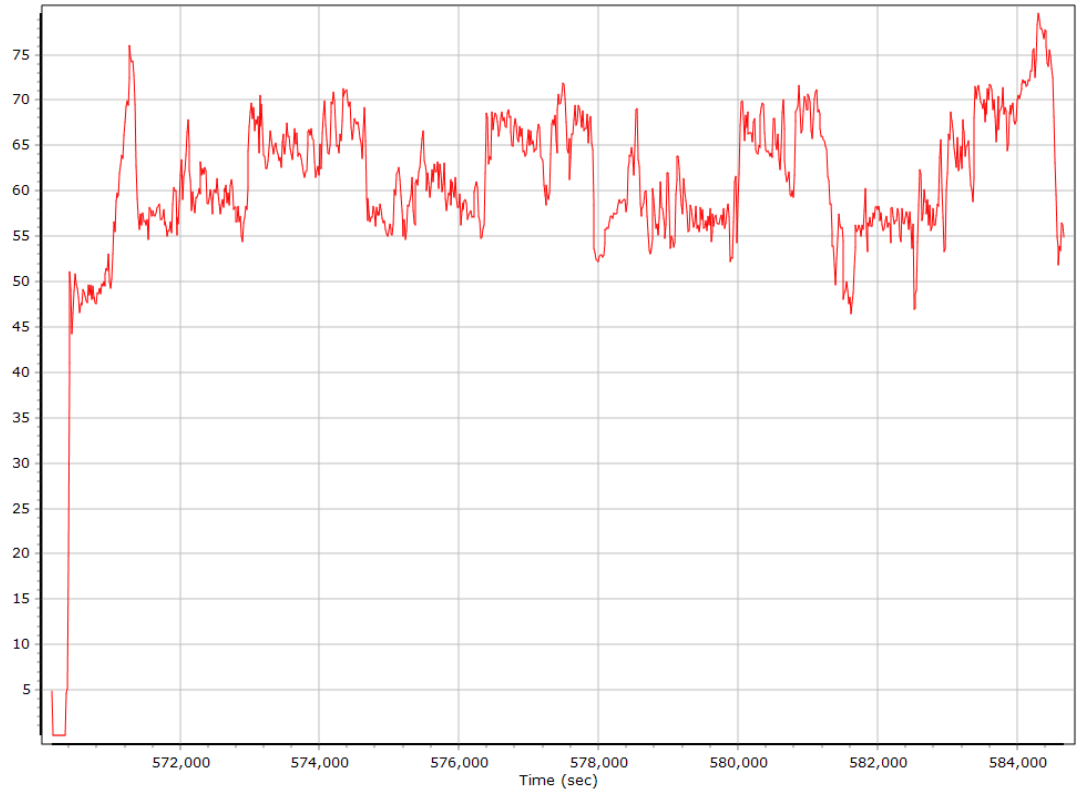
North/East Velocity



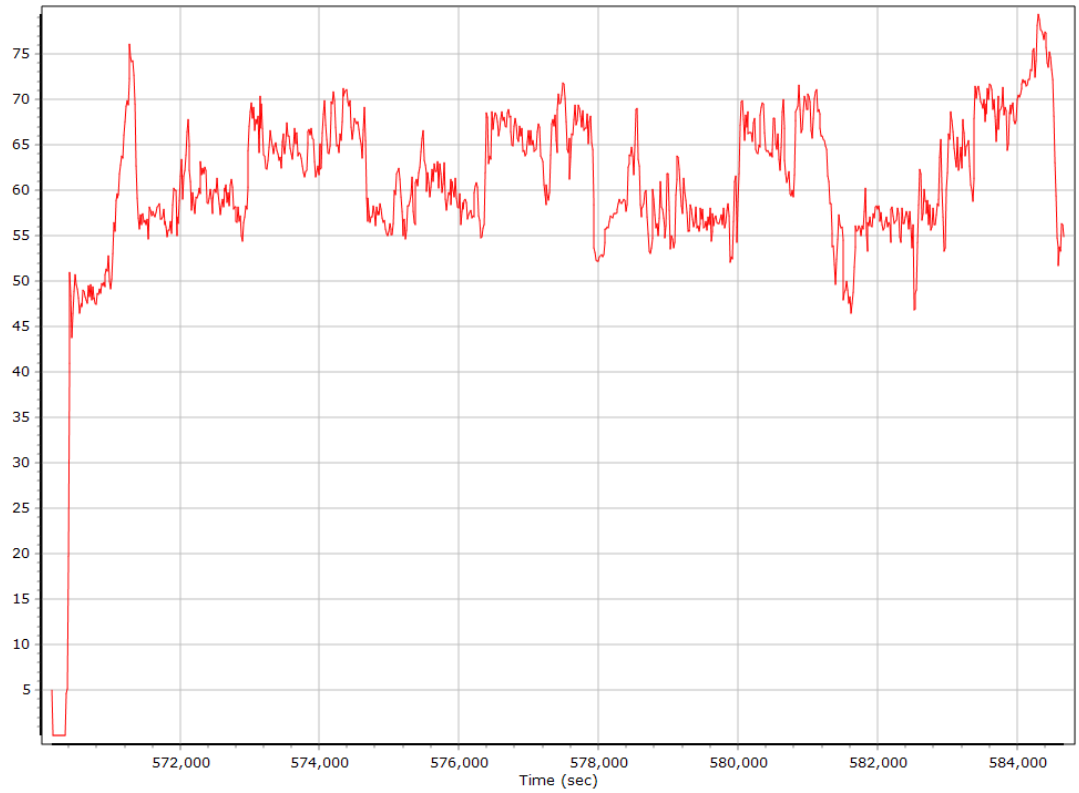
Down Velocity



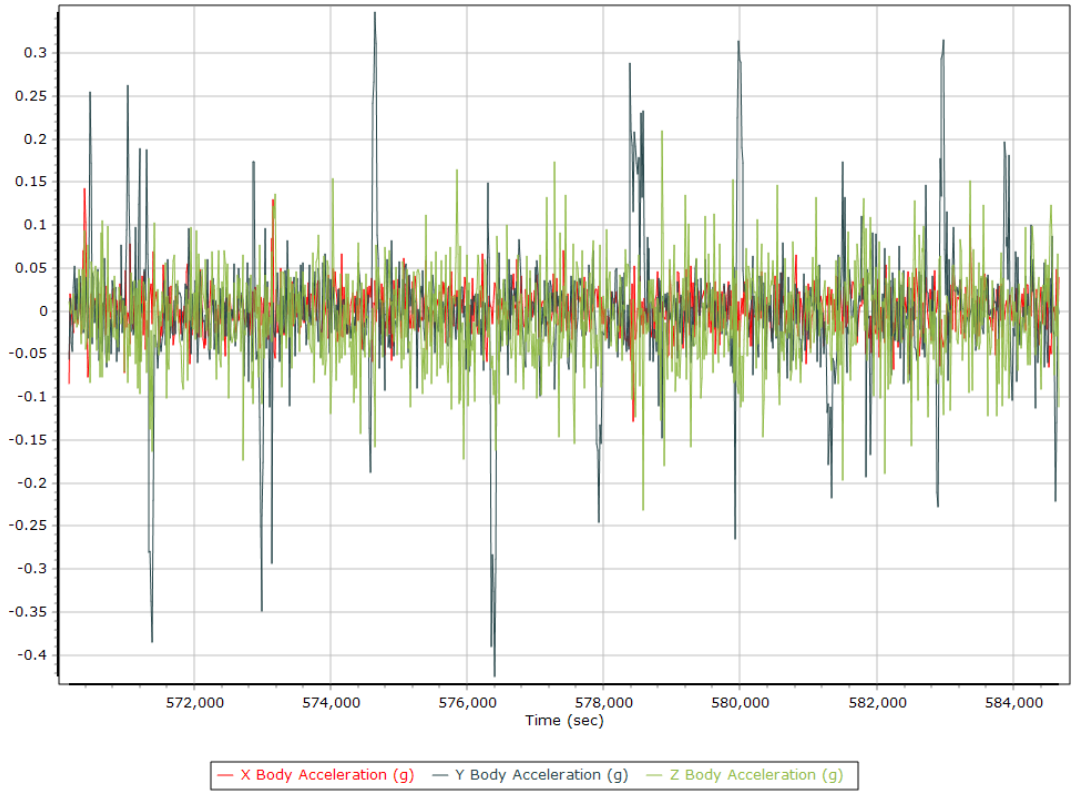
Total Speed



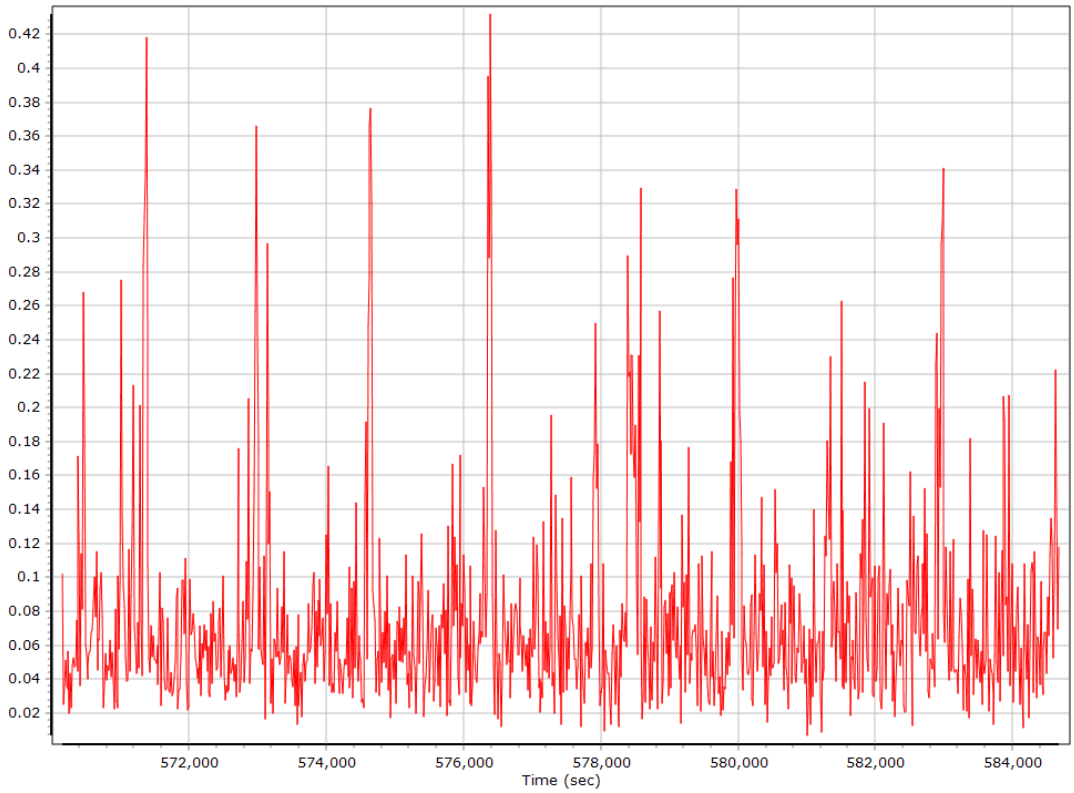
Ground Speed



Body Acceleration



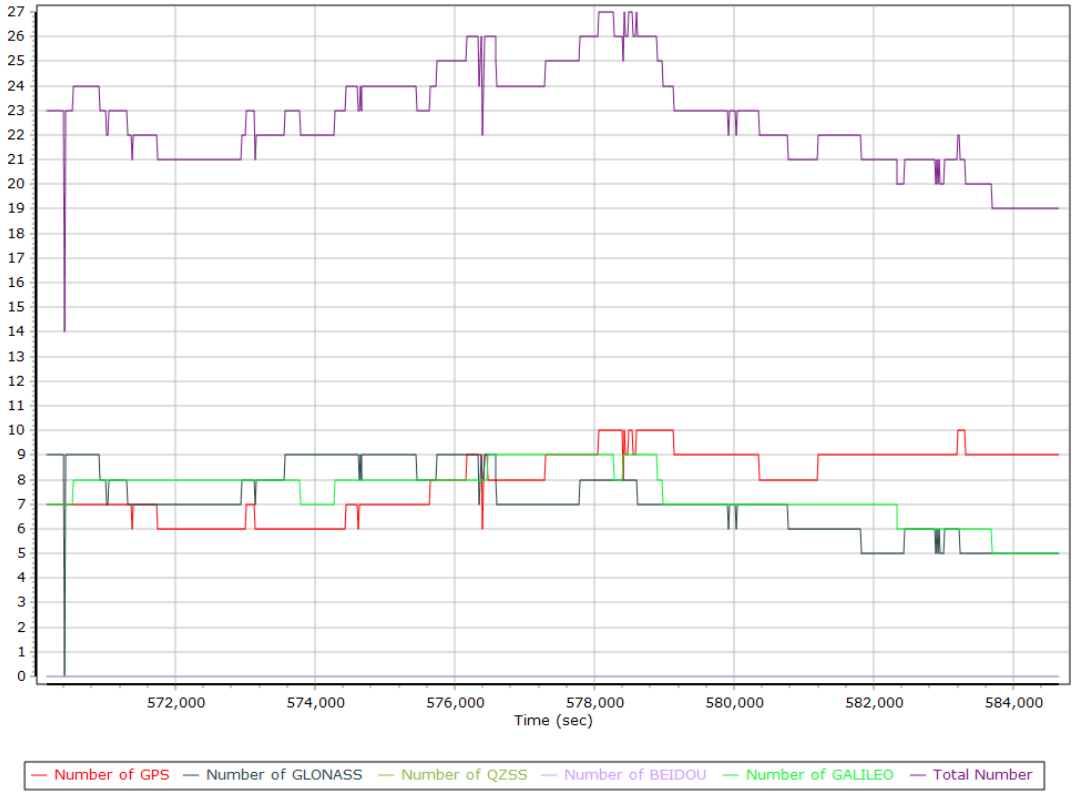
Total Body Acceleration



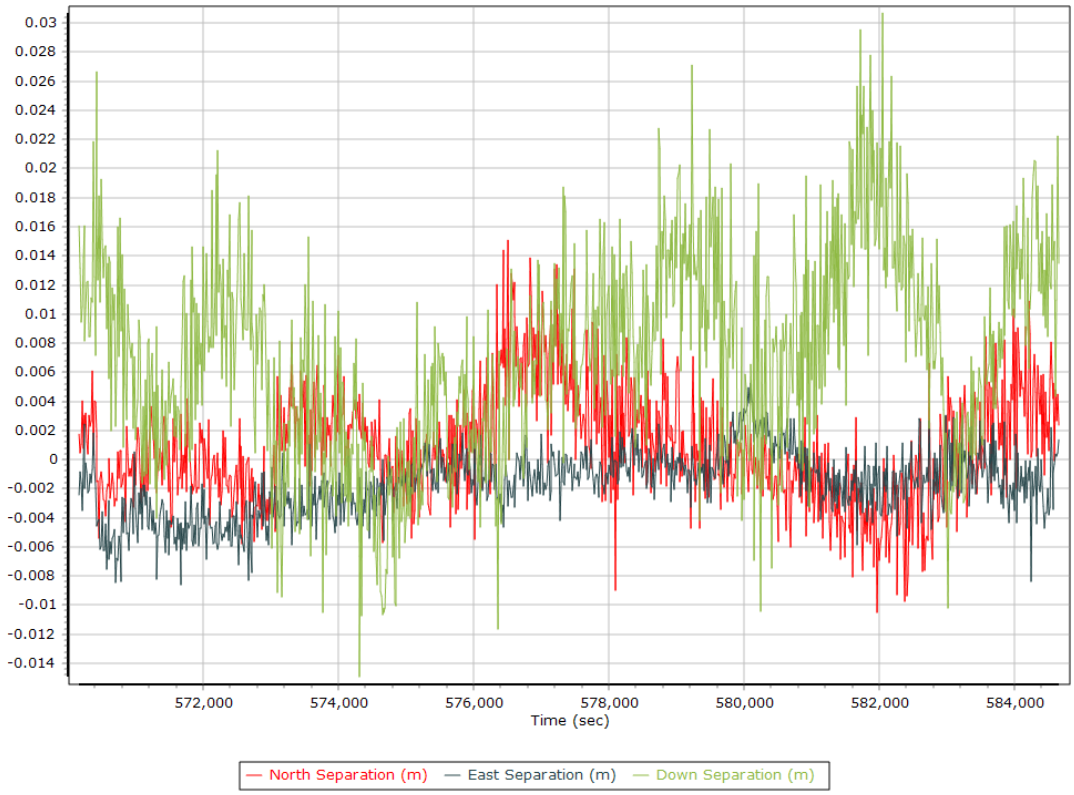
Body Angular Rate

GNSS QC

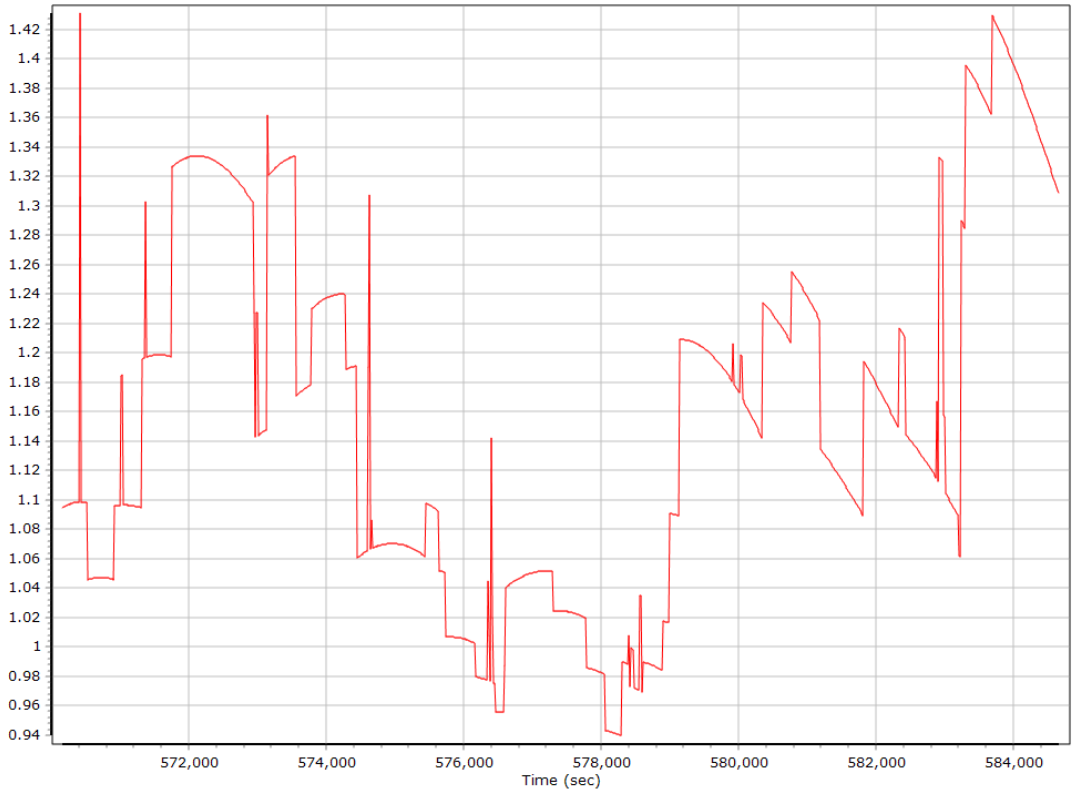
Num SVs in solution



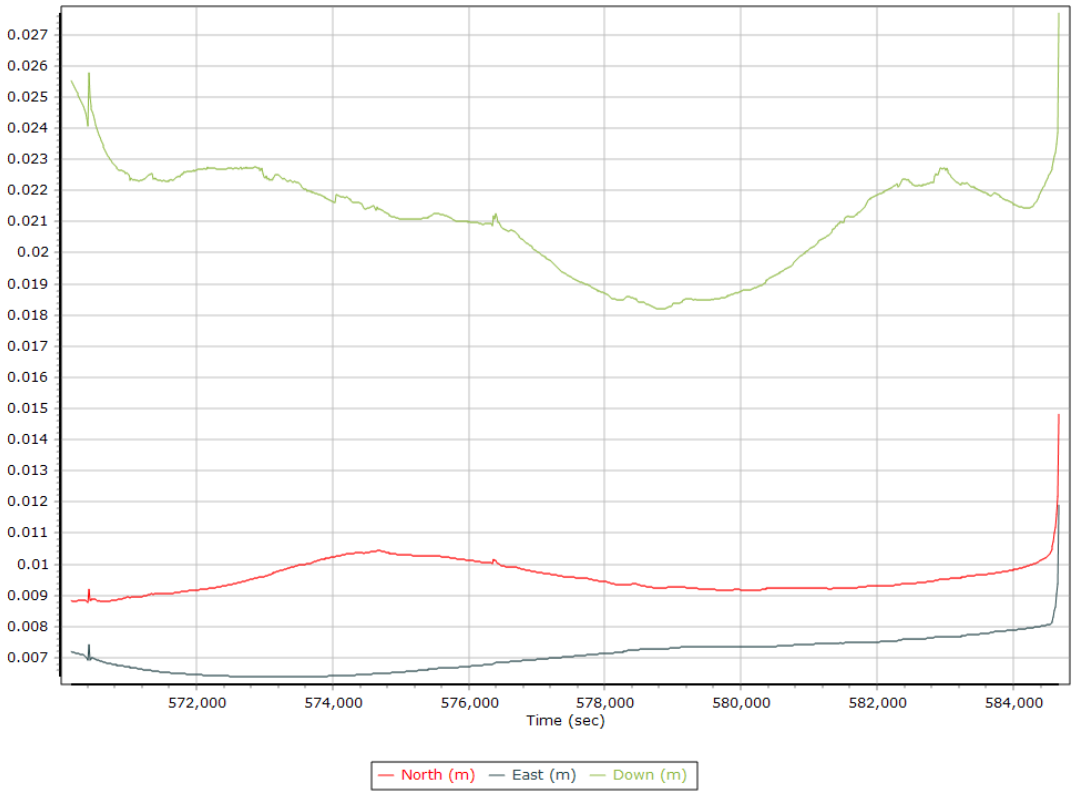
Forward/Reverse Separation



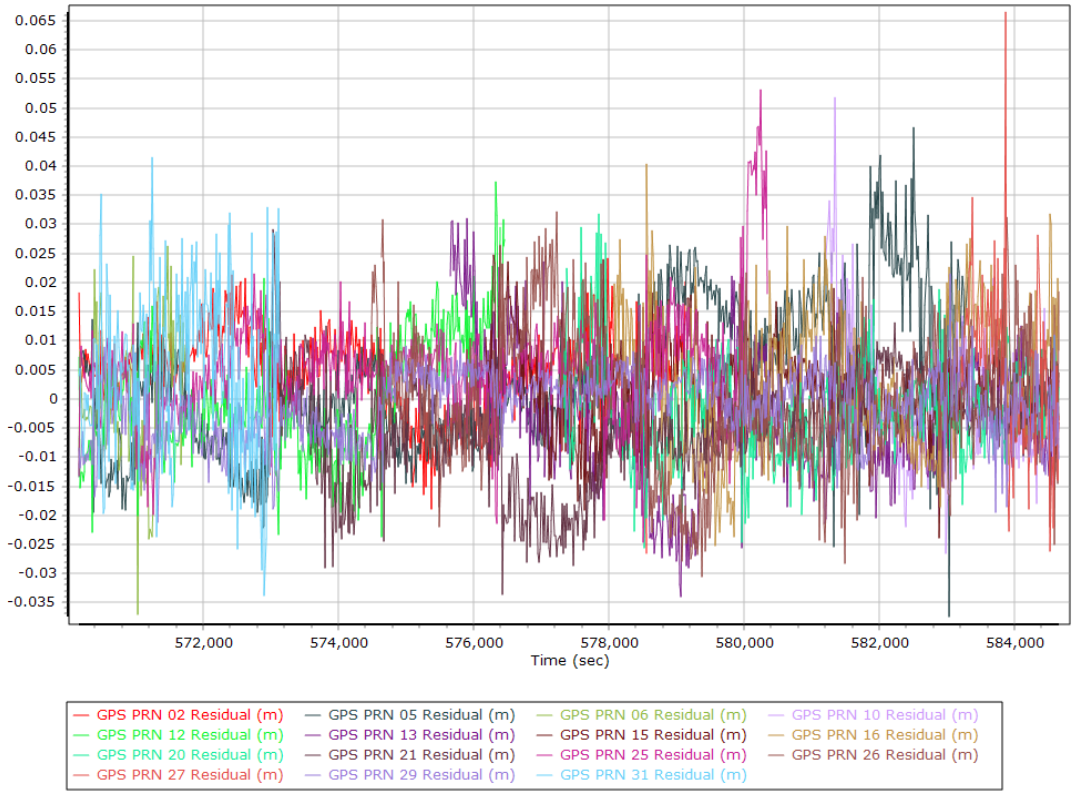
PDOP



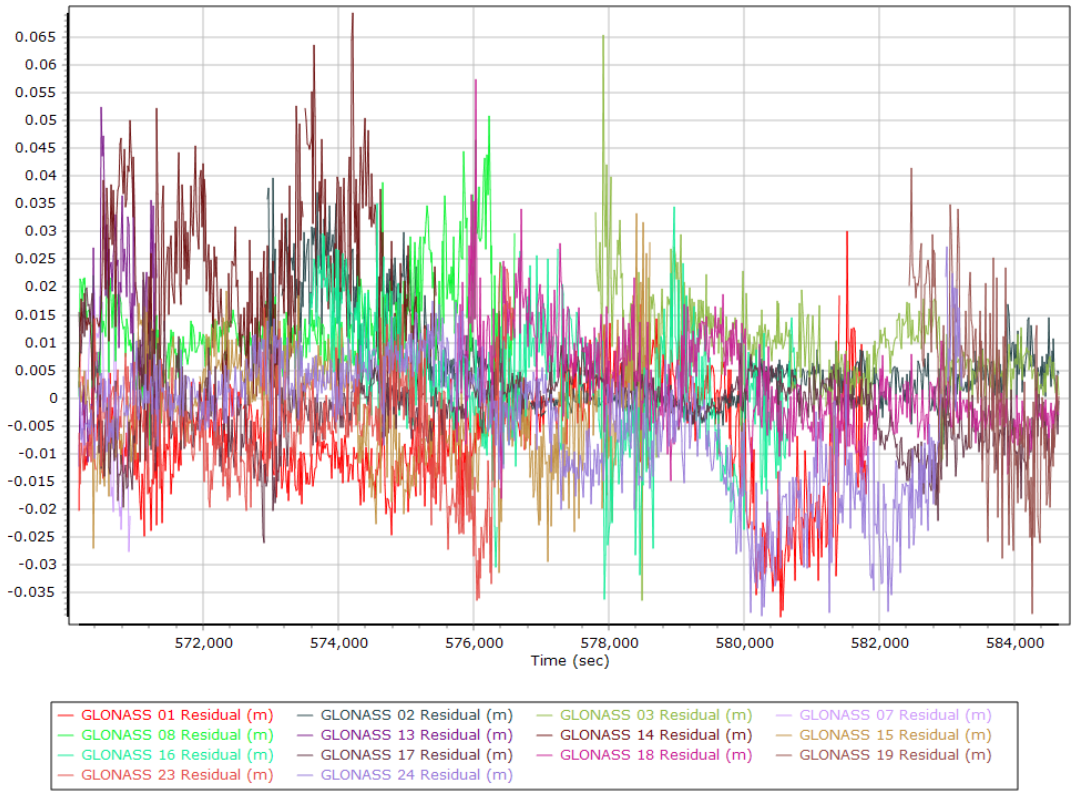
Estimated Position Accuracy



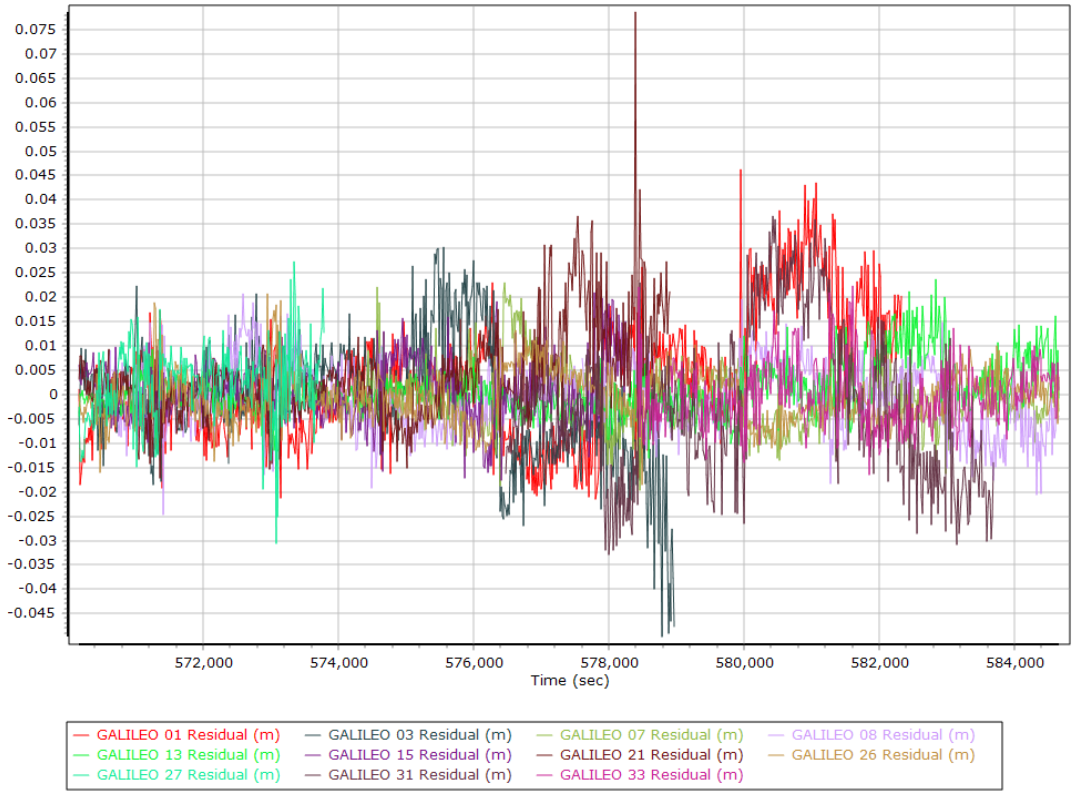
GPS Residuals



GLONASS Residuals



GALILEO Residuals



GNSS-Inertial Processor Configuration

Processing mode	IN-Fusion PP-RTX		
Stabilized mount	False		
Processing start time	569977.000 (10/5/2019 2:19:37 PM)		
Processing end time	584681.000 (10/5/2019 6:24:41 PM)		
Initial attitude source	Real-Time VNAV/RNAV Attitude		
IMU Sensor Context	Processing with Onboard IMU		
Reference to IMU lever arm (m)	0.000	0.000	0.000
Reference to IMU mounting angles (deg)	0.000	0.000	180.000
Reference to Primary GNSS lever arm (m)	0.000	-0.315	-0.926
Reference to Primary GNSS lever arm std dev (m)	0.030	0.030	0.030
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

Calibrated Installation Parameters

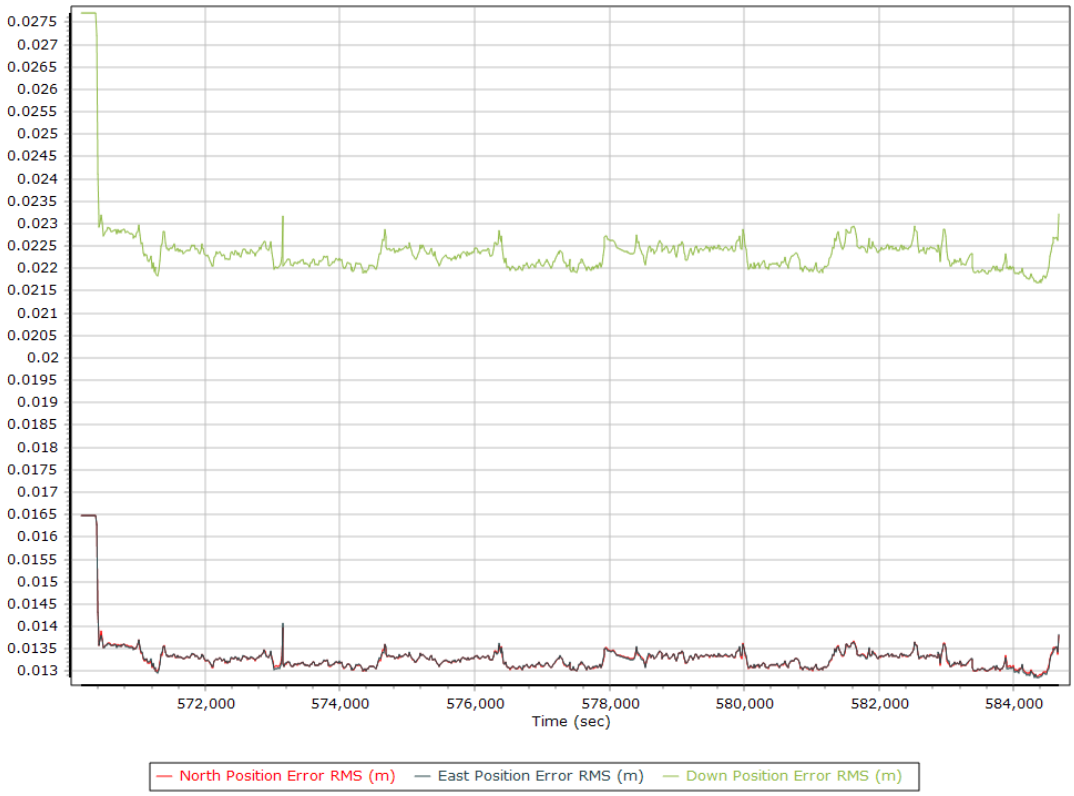
Reference-Primary GNSS Lever Arm (m)

IN-Fusion QC

Forward Processed Estimated Errors, Reference Frame

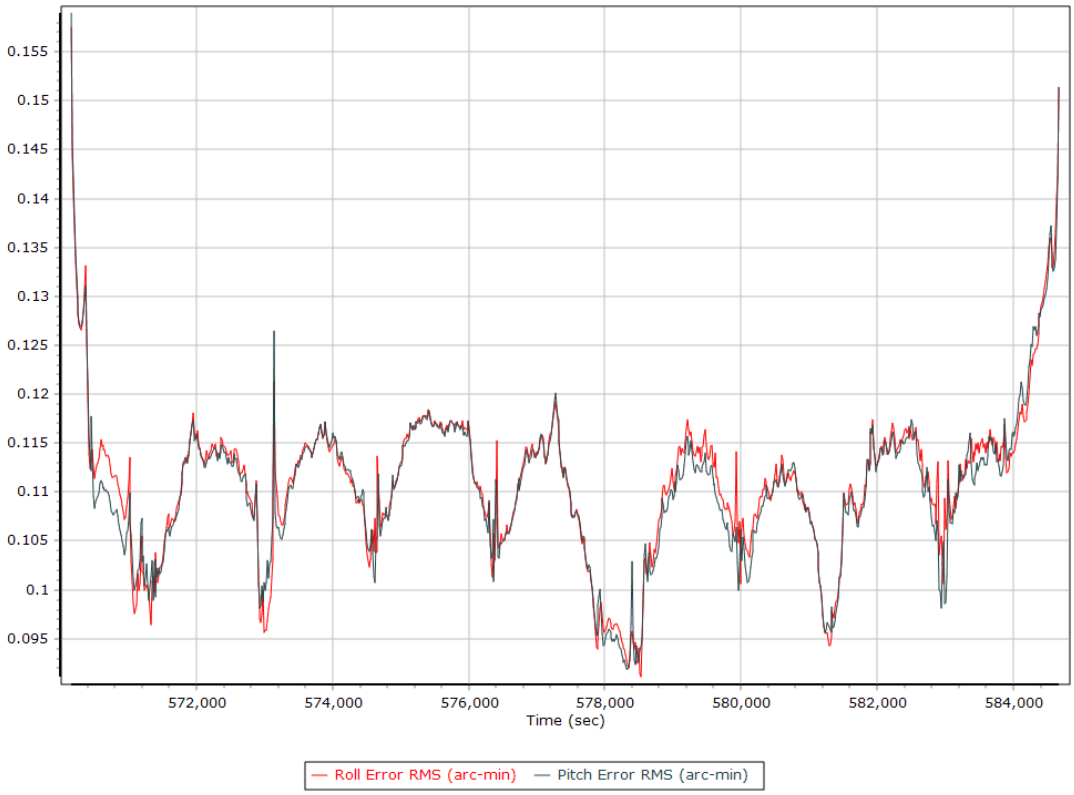
Smoothed Performance Metrics

Position Error RMS (m)

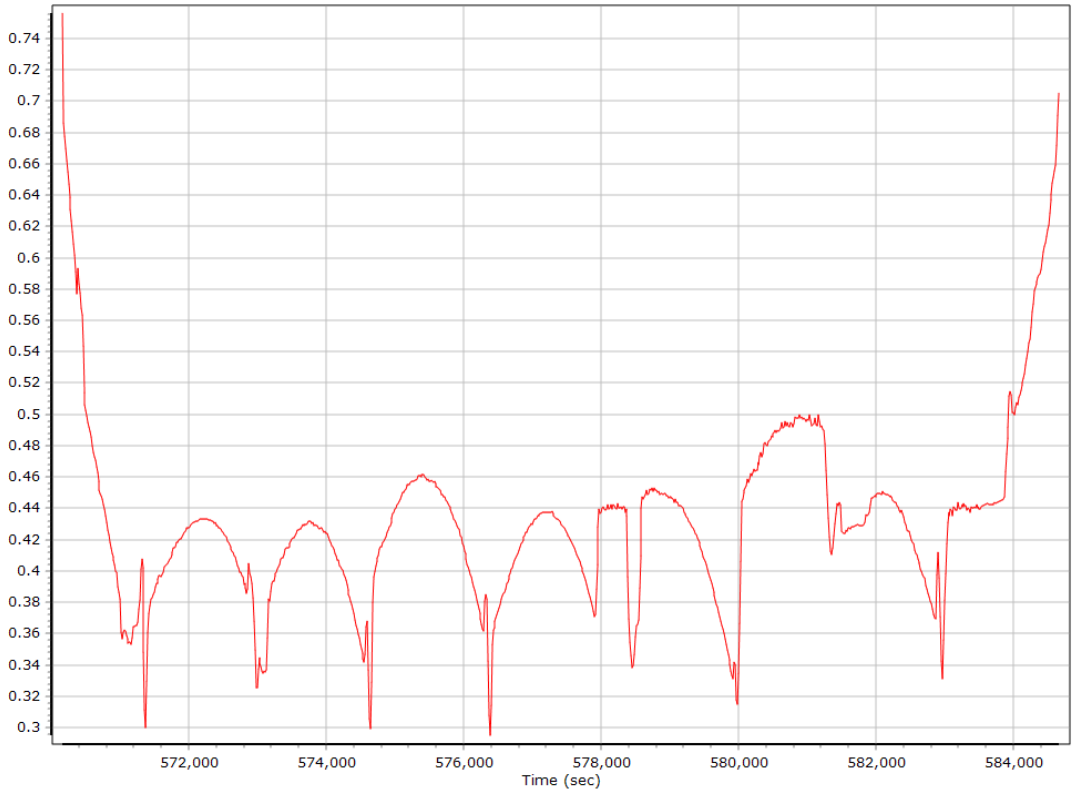


Velocity Error RMS (m/s)

Roll/Pitch Error RMS (arc-min)

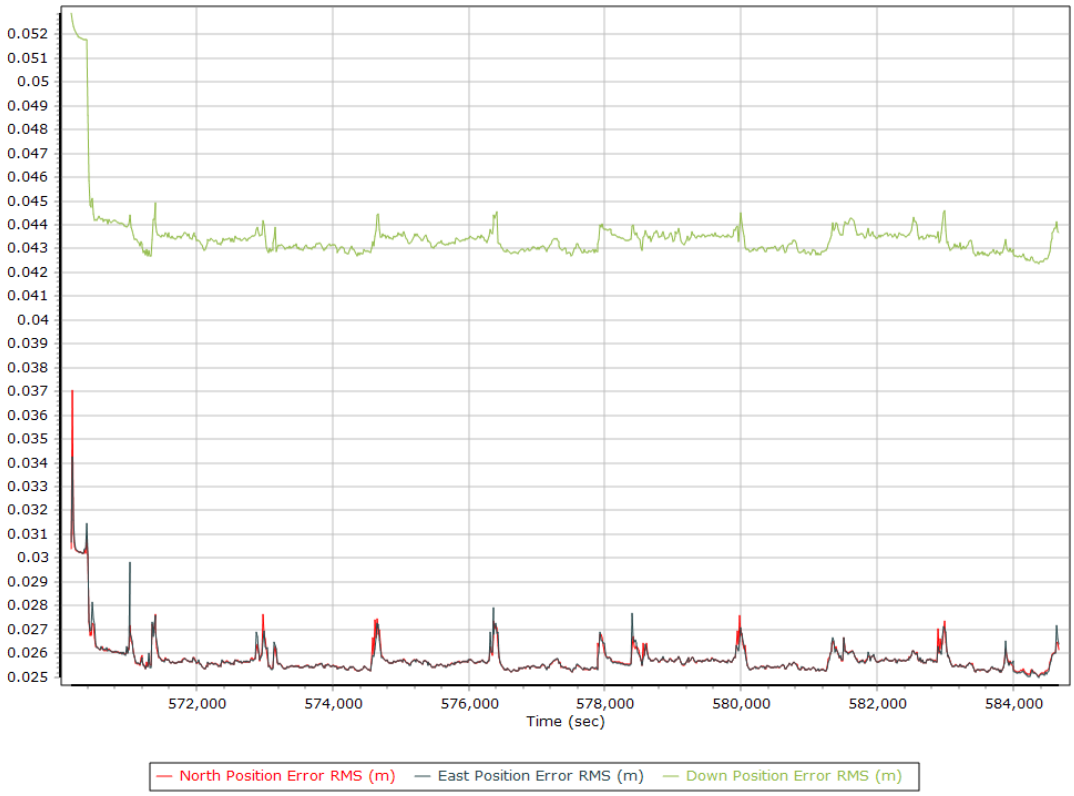


Heading Error RMS (arc-min)

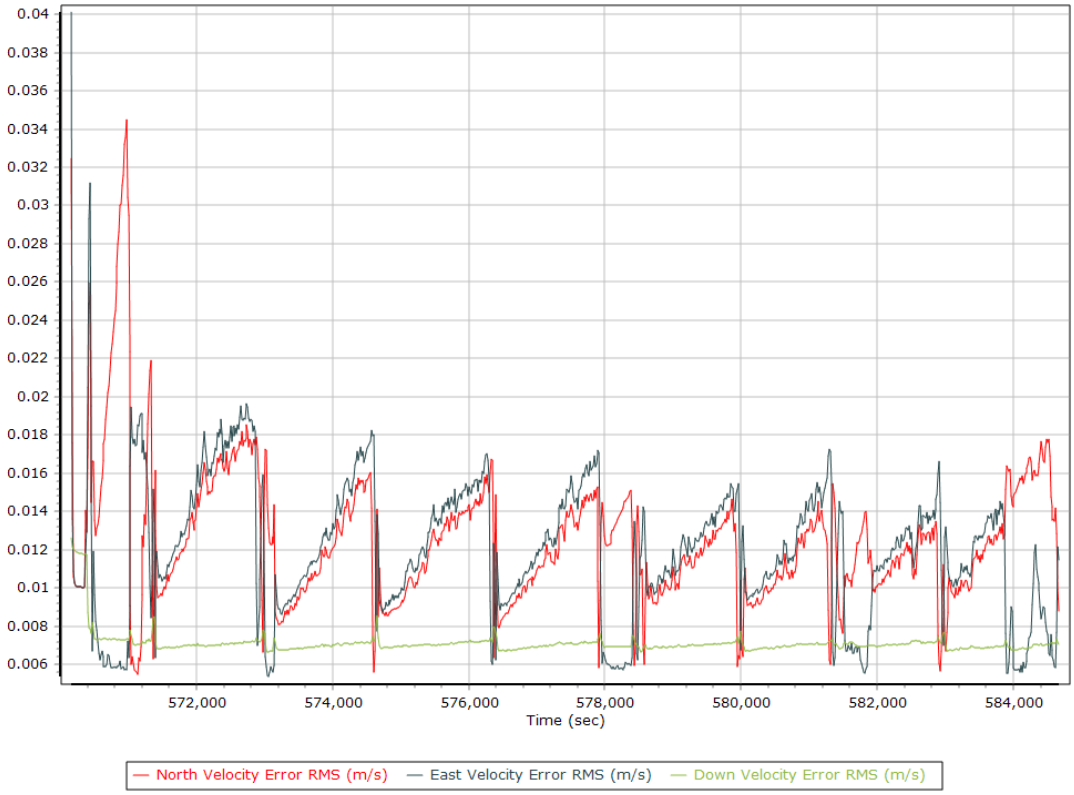


Forward Processed Performance Metrics

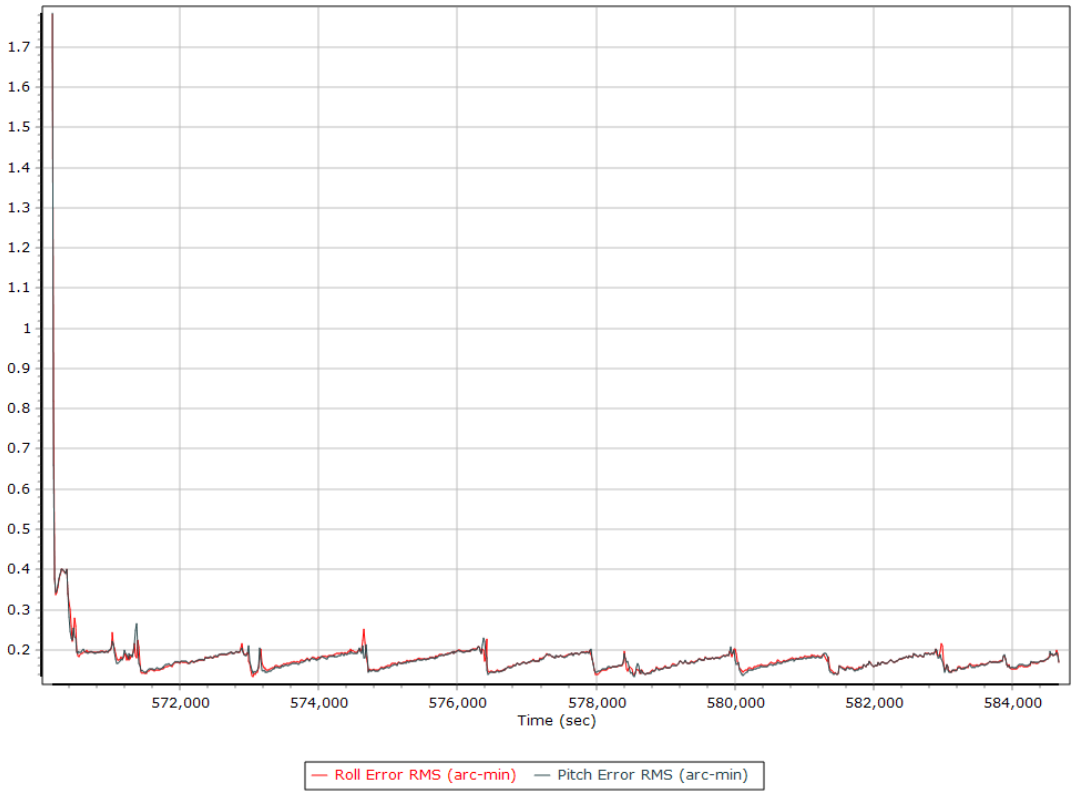
Position Error RMS (m)



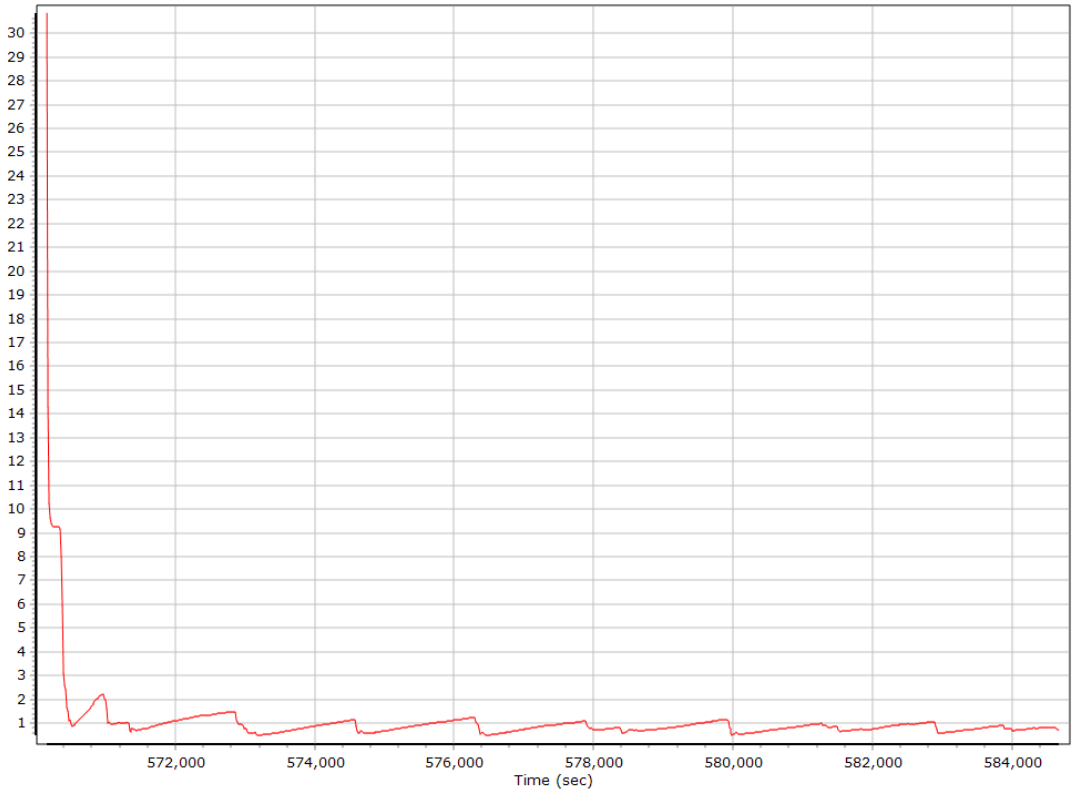
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

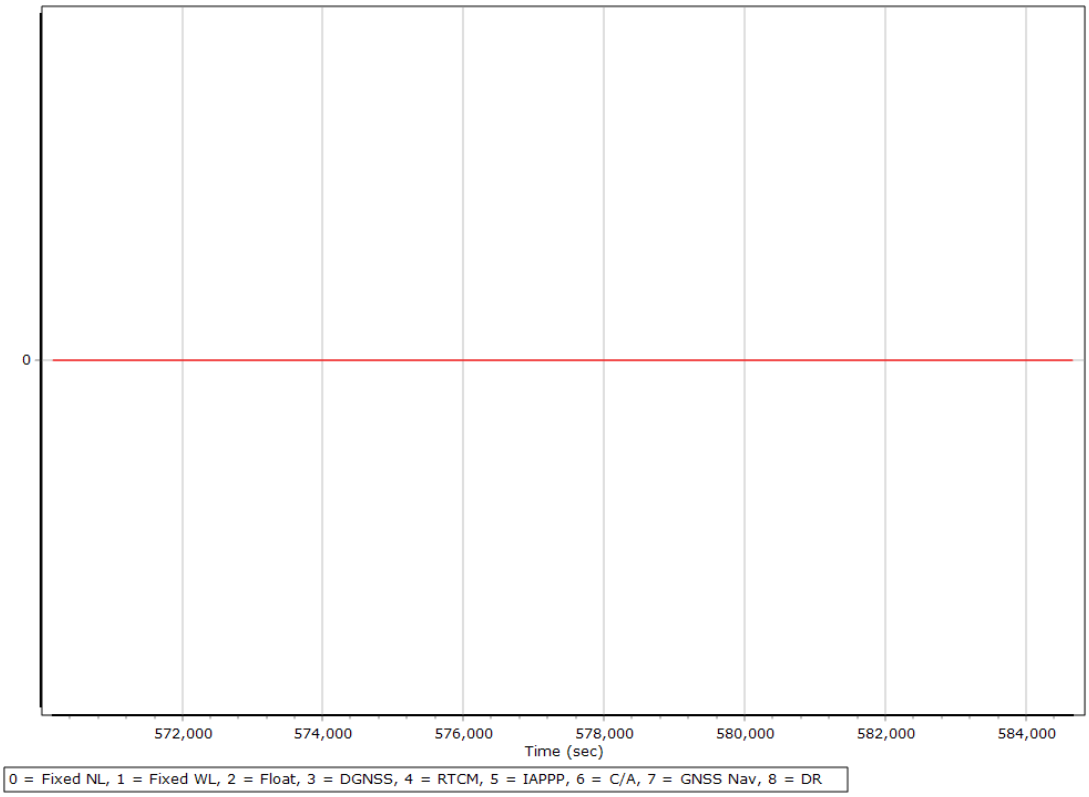


Heading Error RMS (arc-min)

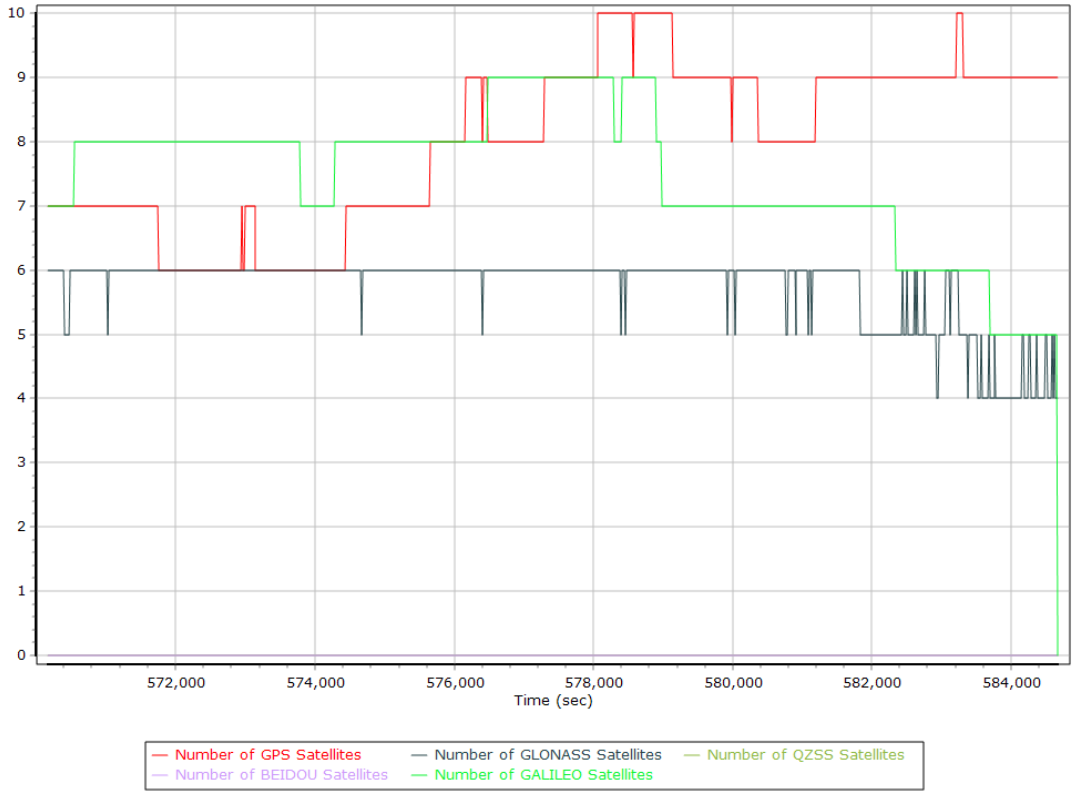
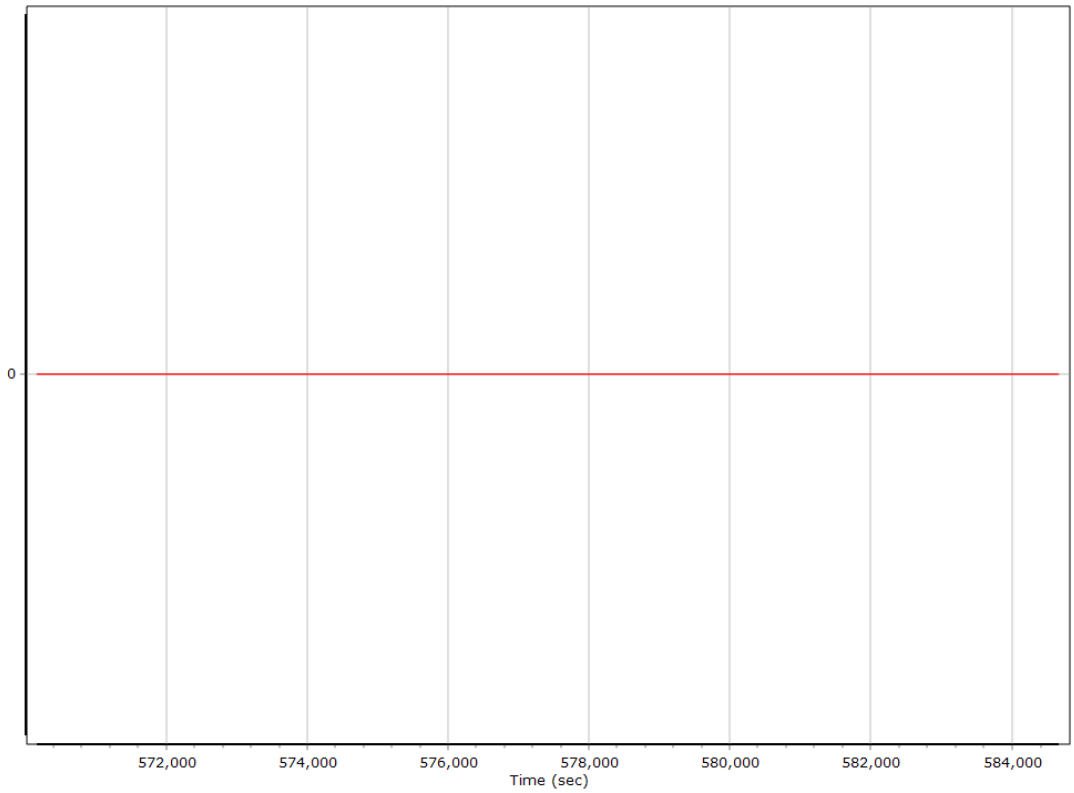


Forward Processed Solution Status

Processing Mode



Number of Satellites



Baseline Length