General Information

Mission Information

Project name	19118_DewberryID_P1_1003_L2
Processing date	2020-10-22 22:56:37
Mission date	2019-10-03 19:58:55
Mission duration	02:32:46.000
Processing mode	IN-Fusion PP-RTX

Rover Hardware Information

Product	POS AV 610 VER6 HW2.5-12
Serial number	S/N9273
IMU type	57
Receiver type	BD982
Antenna type	AV39

Project File List

Rover Data Files

File name	File type
20191003_1.708	POS Data
20191003_1.709	POS Data
20191003_1.710	POS Data
20191003_1.711	POS Data
20191003_1.712	POS Data
20191003_1.713	POS Data
20191003_1.714	POS Data
20191003_1.715	POS Data
20191003_1.716	POS Data
20191003_1.717	POS Data
20191003_1.718	POS Data
20191003_1.719	POS Data
20191003_1.720	POS Data
20191003_1.721	POS Data
20191003_1.722	POS Data
20191003_1.723	POS Data

Input Files

File Name	File Type
Ephm2760.19g	GLONASS Broadcast Ephemeris
Ephm2760.19n	GPS Broadcast Ephemeris

Output Files

Filename	File type
sbet_Mission 1.out	SBET Trajectory File

Rover Data Summary

First raw data file	20191003_1.708		
Last raw data file	20191003_1.723		
Start GPS week	2073		
Start time	417534.601 (10/3/2019 7:58:54 PM)		
End time	426701.701 (10/3/2019 10:31:41 PM)		
Start of fine alignment	417634.938 (10/3/2019 8:00:34 PM)		
Available subsystems	Primary GNSS, IMU		
POS Event Input	None		
Correction data	None		
IMU Installation Lever Arms & Mounting Angles			
Reference to IMU lever arm (m)	0.000	0.000	0.000
Reference to IMU mounting angles (deg)	0.000	0.000	180.000
Reference to Primary GNSS lever arm (m)	-0.010	-0.315	-0.926
Reference to Primary GNSS lever arm std dev (m)	-1.000		
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

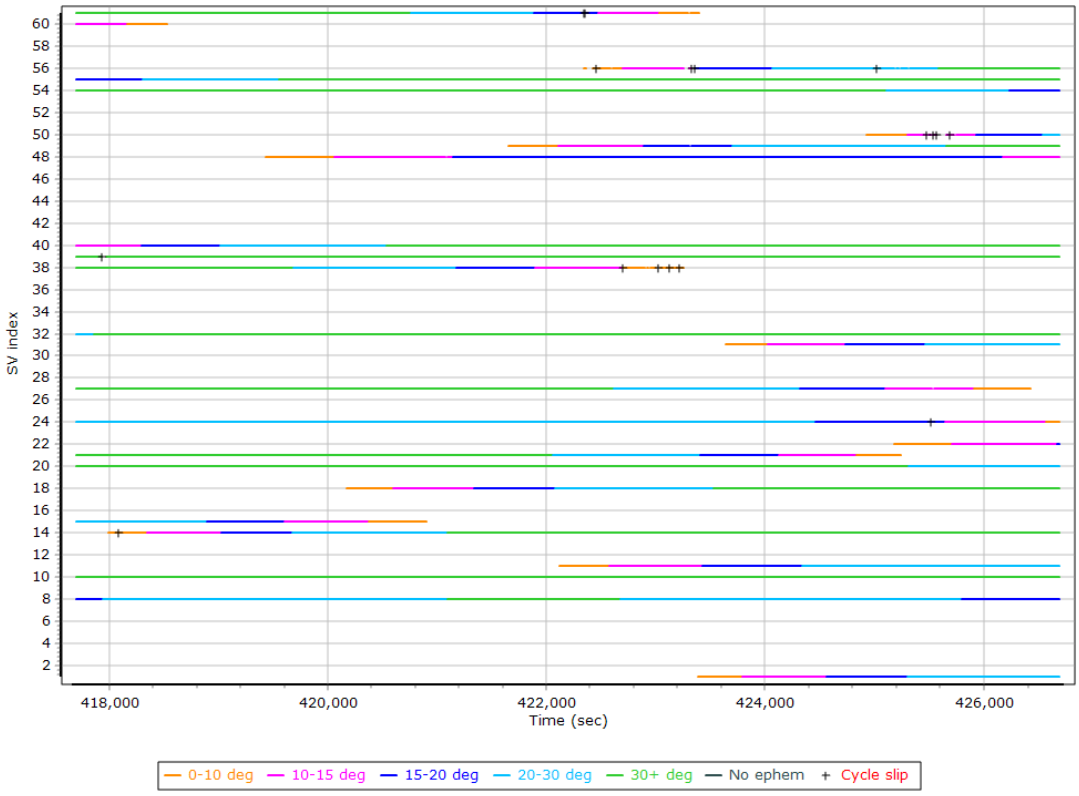
Rover Data QC

Raw IMU Import QC Summary

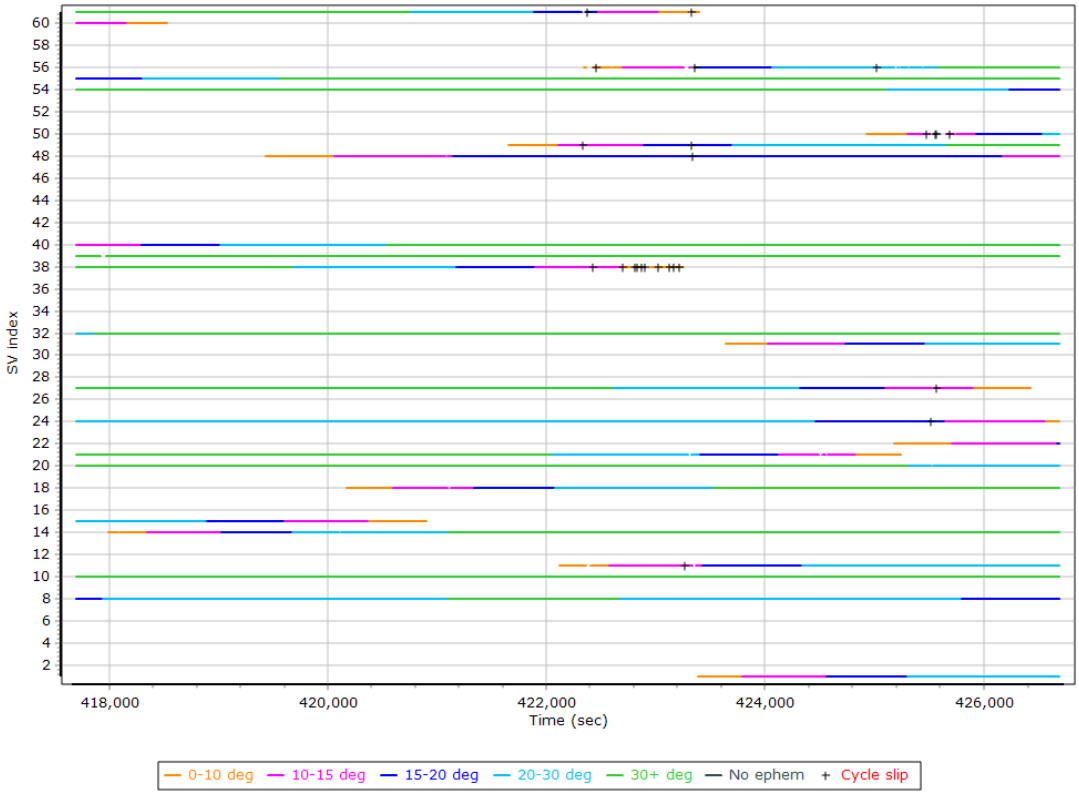
IMU data input file	imu_Mission 1.dat
IMU data check log file	imudt_Mission 1.log
IMU Records Processed	1833122
Termination Status	Normal
IMU Anomalies	0

Primary Observables & Satellite Data

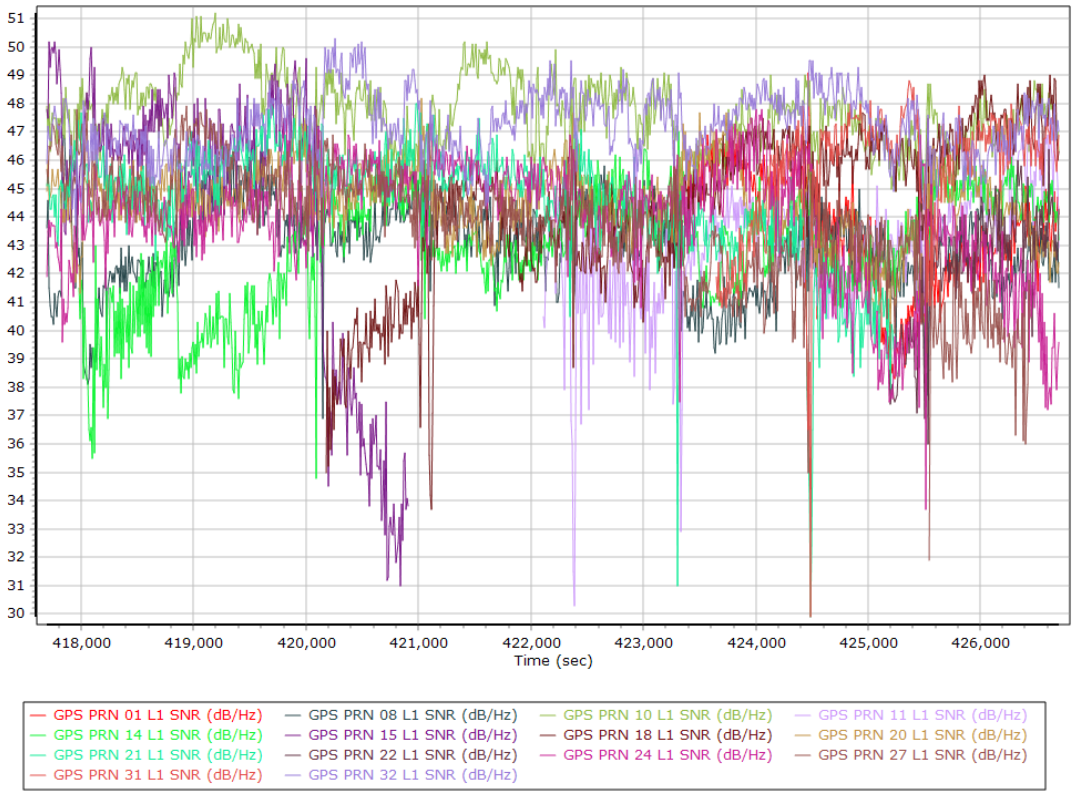
L1 Satellite Lock/Elevation



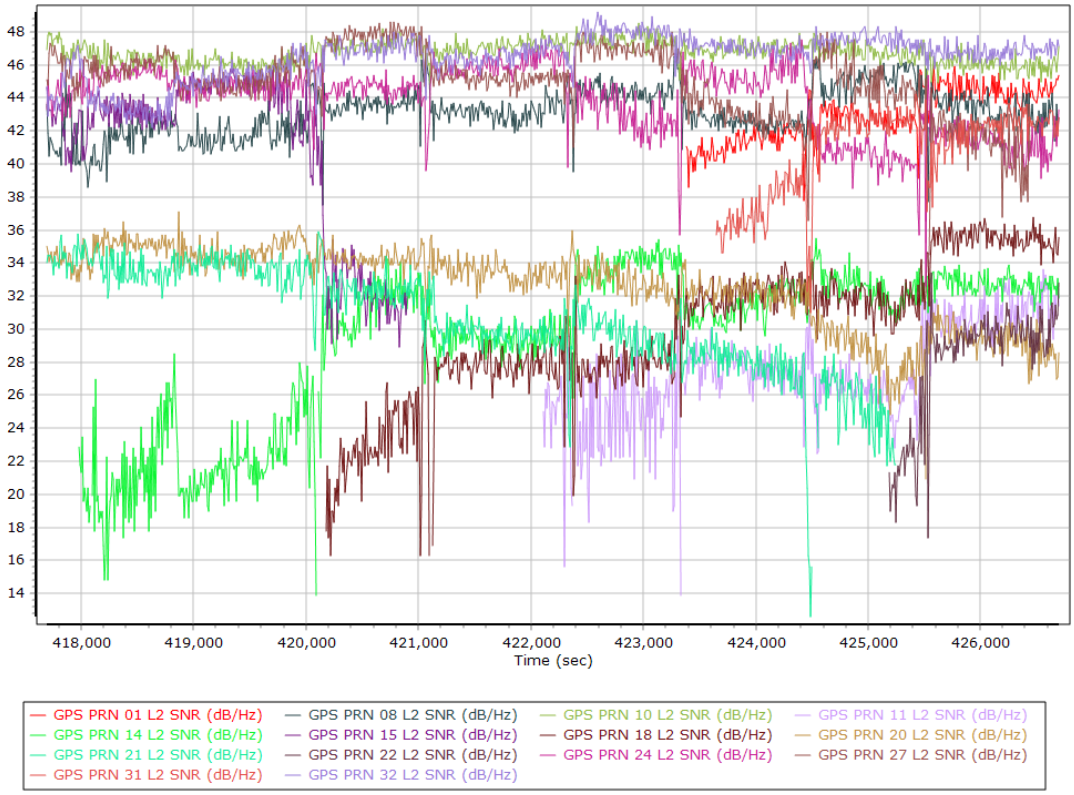
L2 Satellite Lock/Elevation



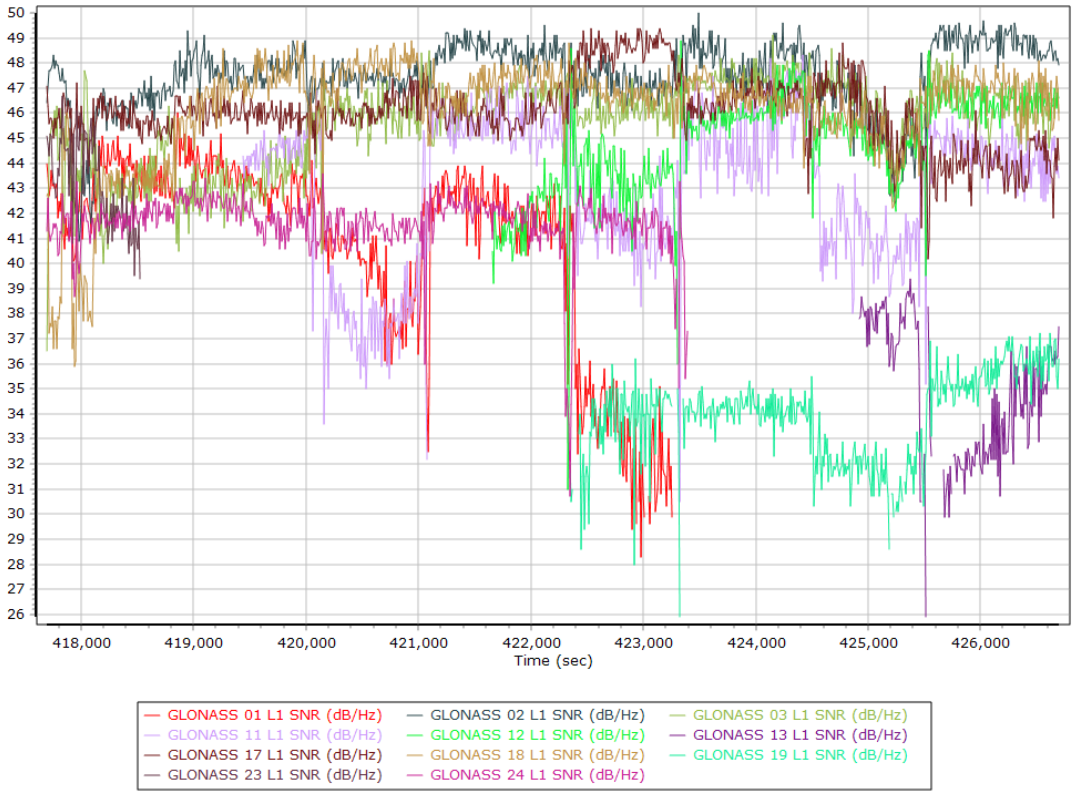
GPS L1 SNR



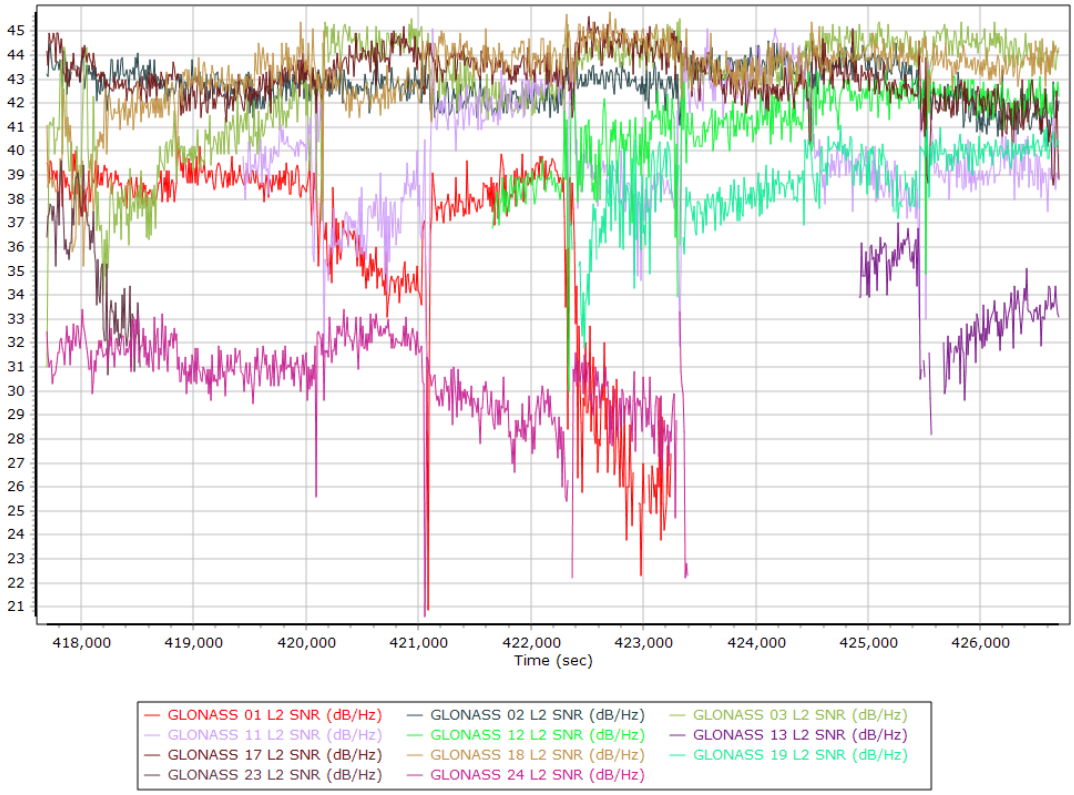
GPS L2 SNR



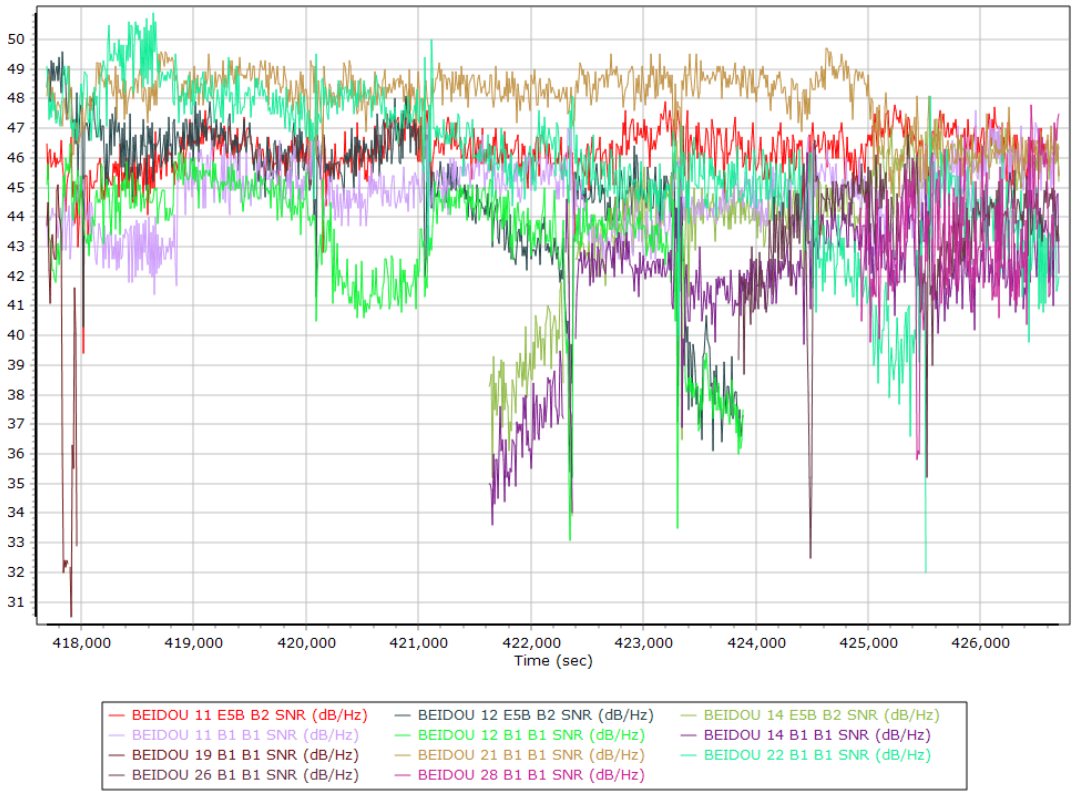
GLONASS L1 SNR



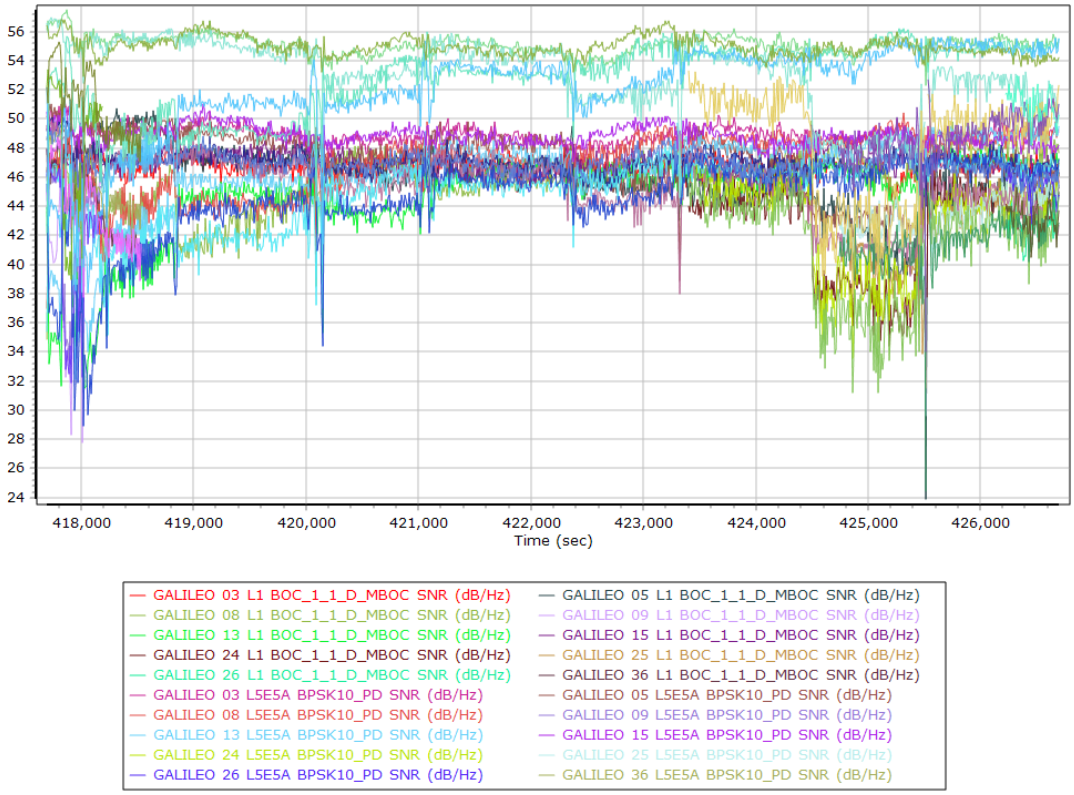
GLONASS L2 SNR



BEIDOU SNR



GALILEO SNR


56
54
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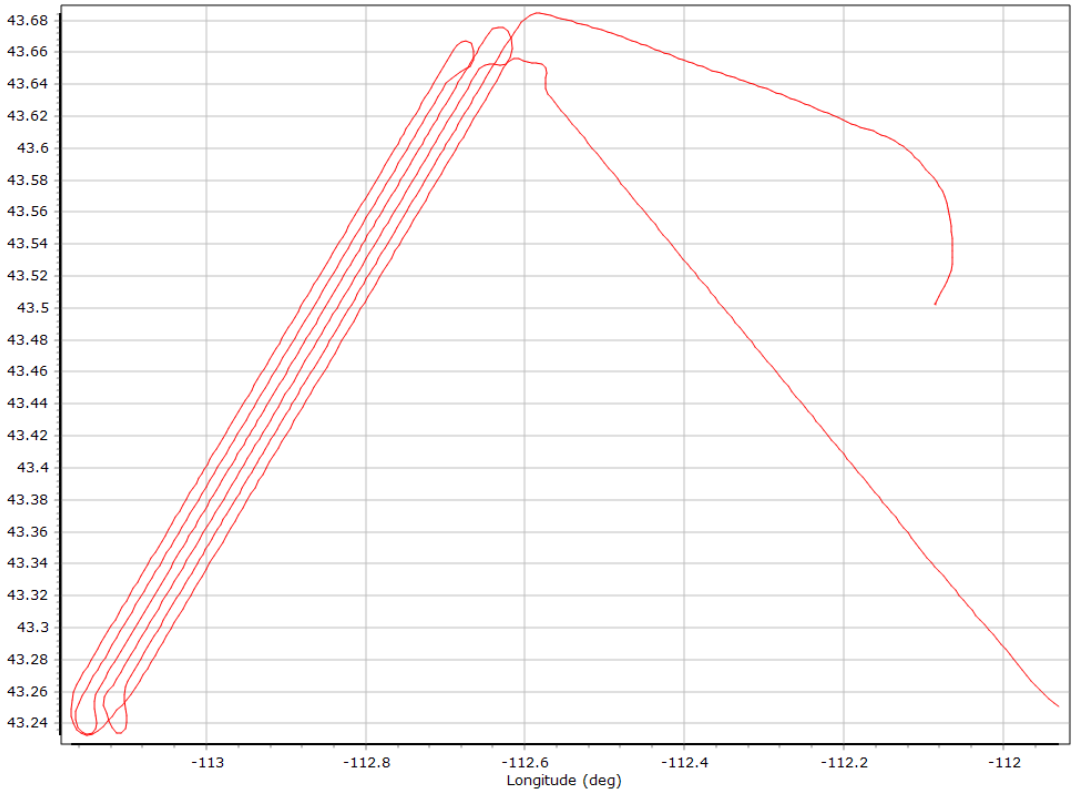
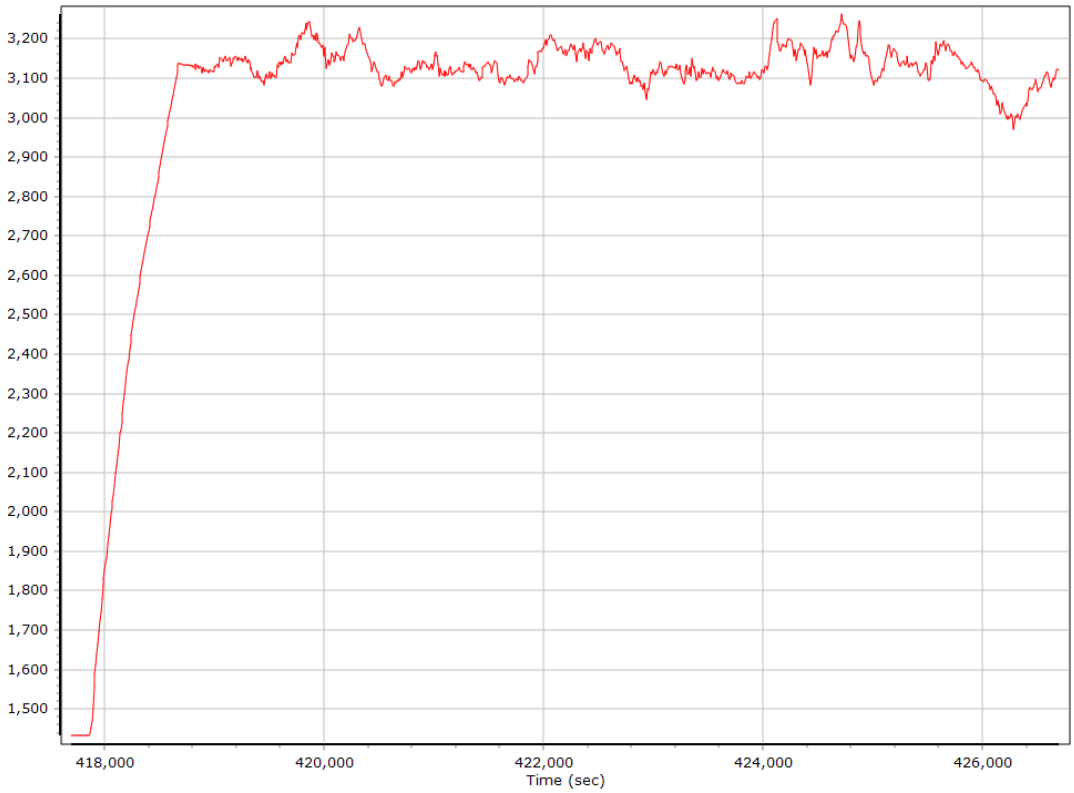
32
30
28
26
24
418,000
419,000
420,000
421,000
422,000
423,000
424,000
425,000
426,000
Time (sec)
GALILEO 03 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 05 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 08 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 09 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 13 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 15 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 24 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 25 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 26 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 36 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 03 L5E5A BPSK10_PD SNR (dB/Hz)
GALILEO 05 L5E5A BPSK10_PD SNR (dB/Hz)
GALILEO 08 L5E5A BPSK10_PD SNR (dB/Hz)
GALILEO 09 L5E5A BPSK10_PD SNR (dB/Hz)
GALILEO 13 L5E5A BPSK10_PD SNR (dB/Hz)
GALILEO 15 L5E5A BPSK10_PD SNR (dB/Hz)
GALILEO 24 L5E5A BPSK10_PD SNR (dB/Hz)
GALILEO 25 L5E5A BPSK10_PD SNR (dB/Hz)
GALILEO 26 L5E5A BPSK10_PD SNR (dB/Hz)
GALILEO 36 L5E5A BPSK10_PD SNR (dB/Hz)

Smoothed Trajectory Information

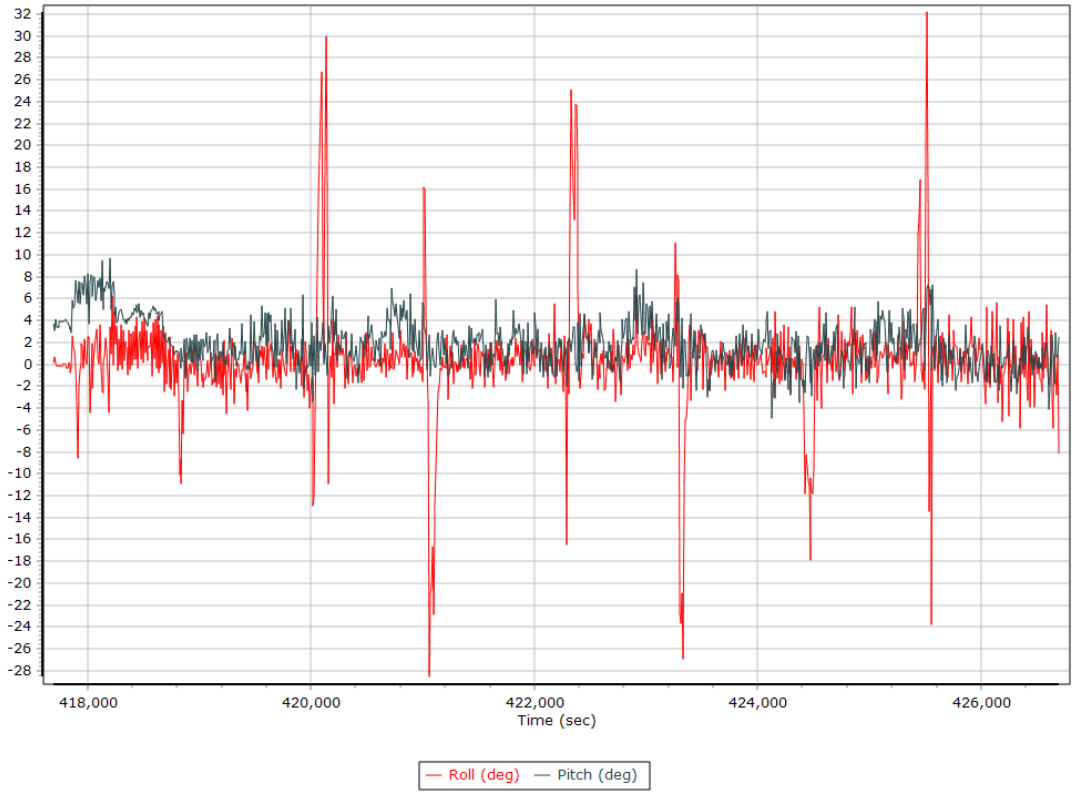
Top View



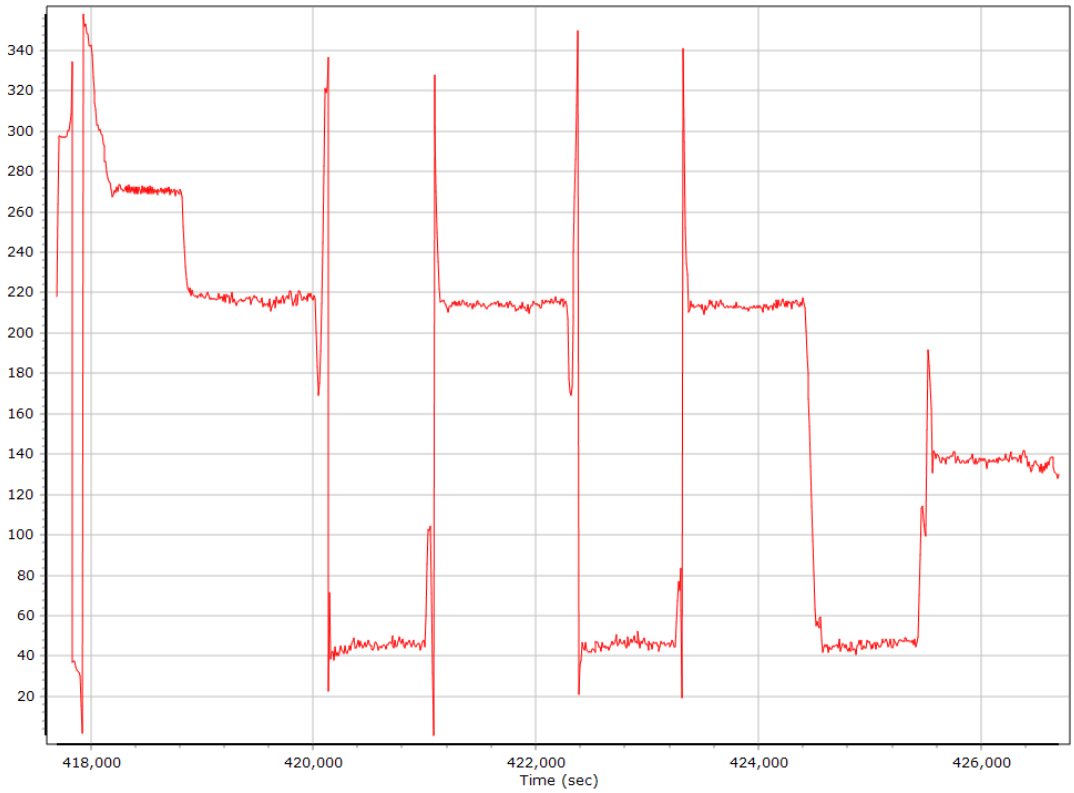
Altitude



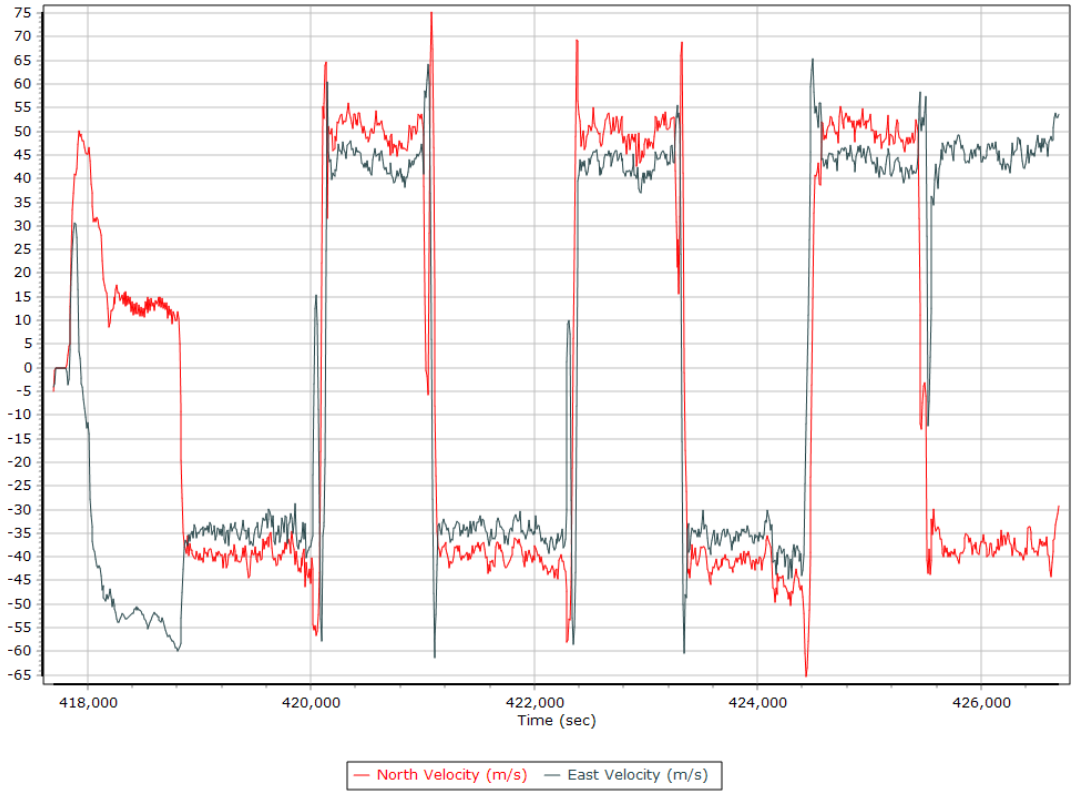
Roll/Pitch



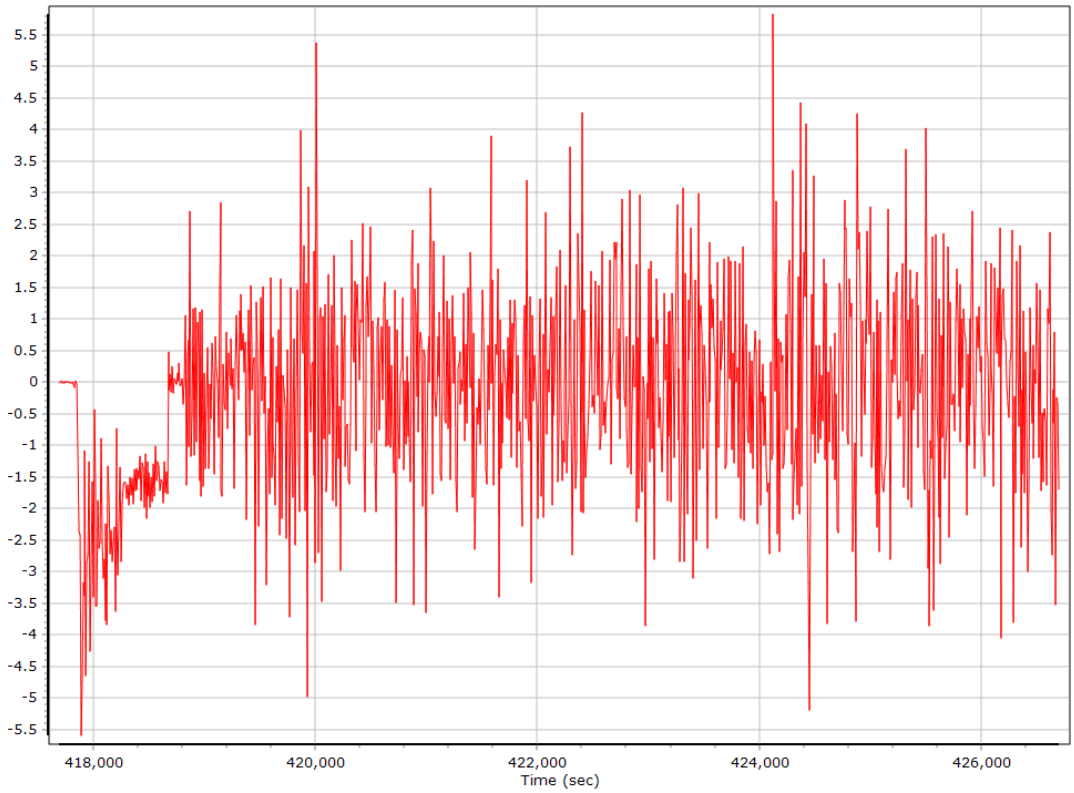
Heading



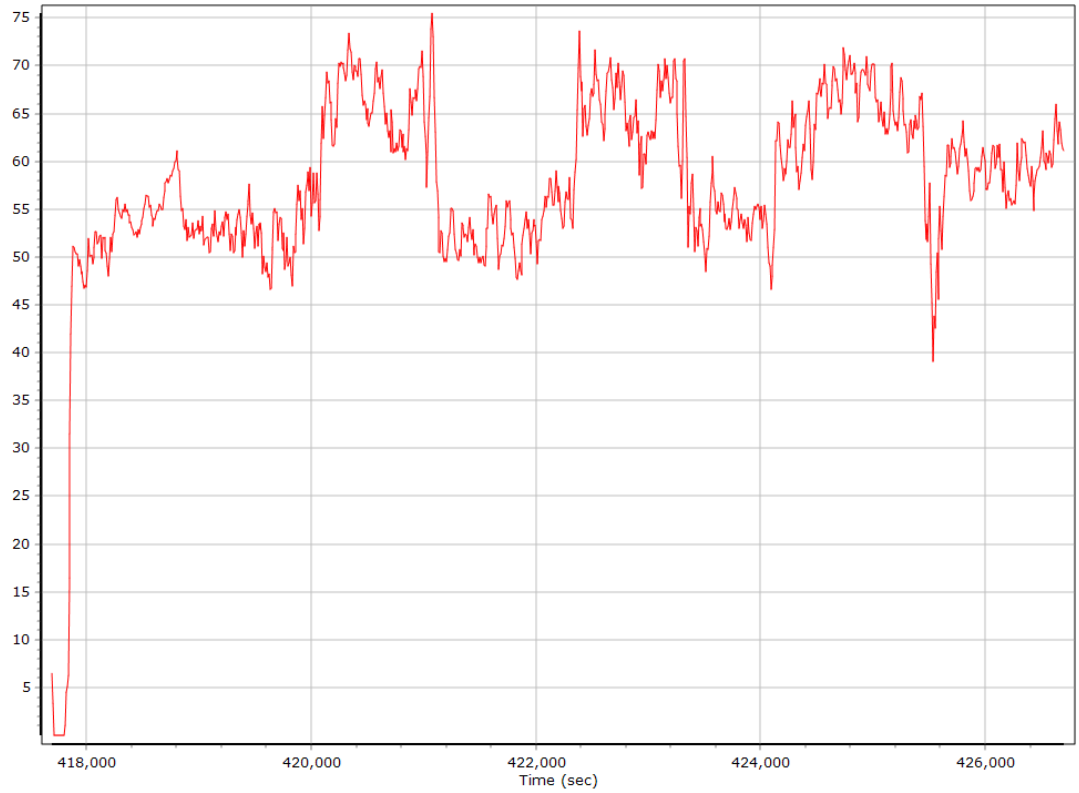
North/East Velocity



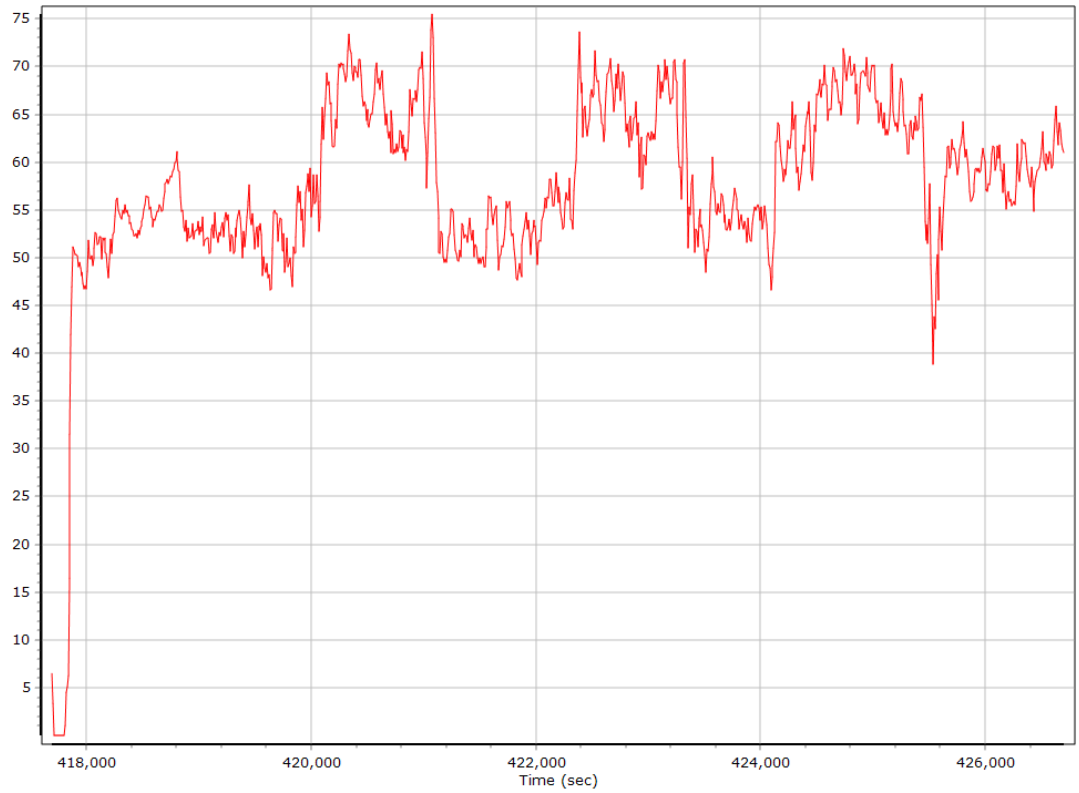
Down Velocity



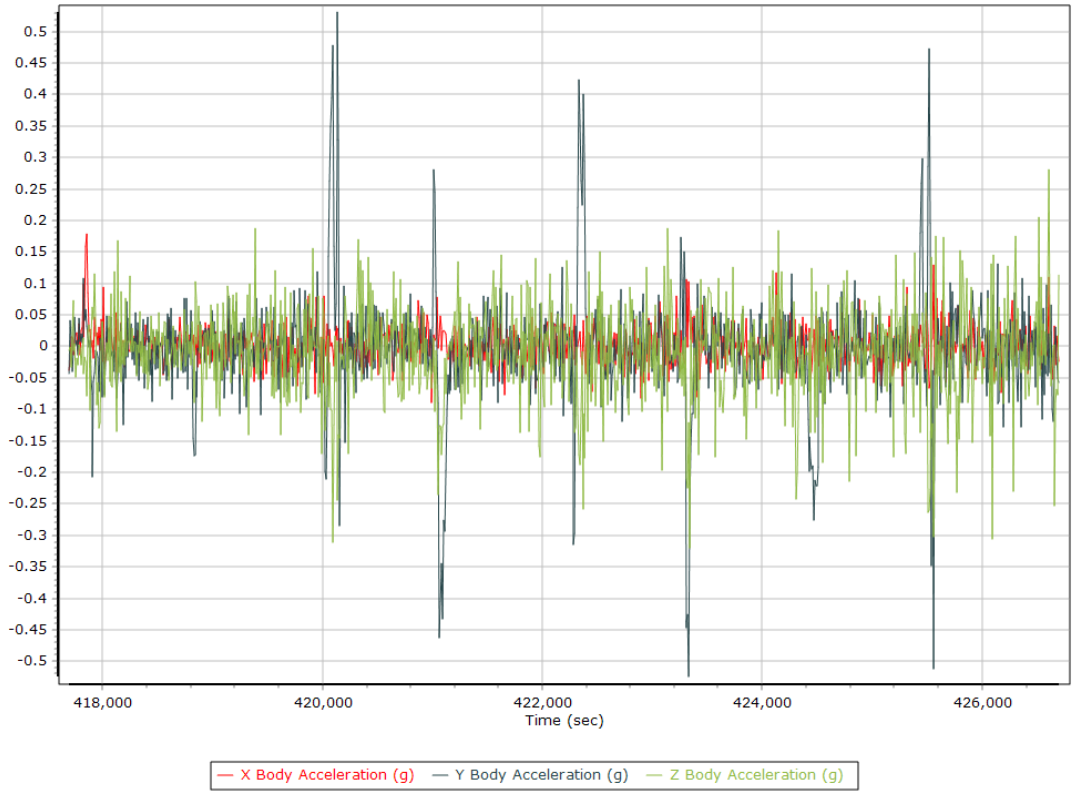
Total Speed



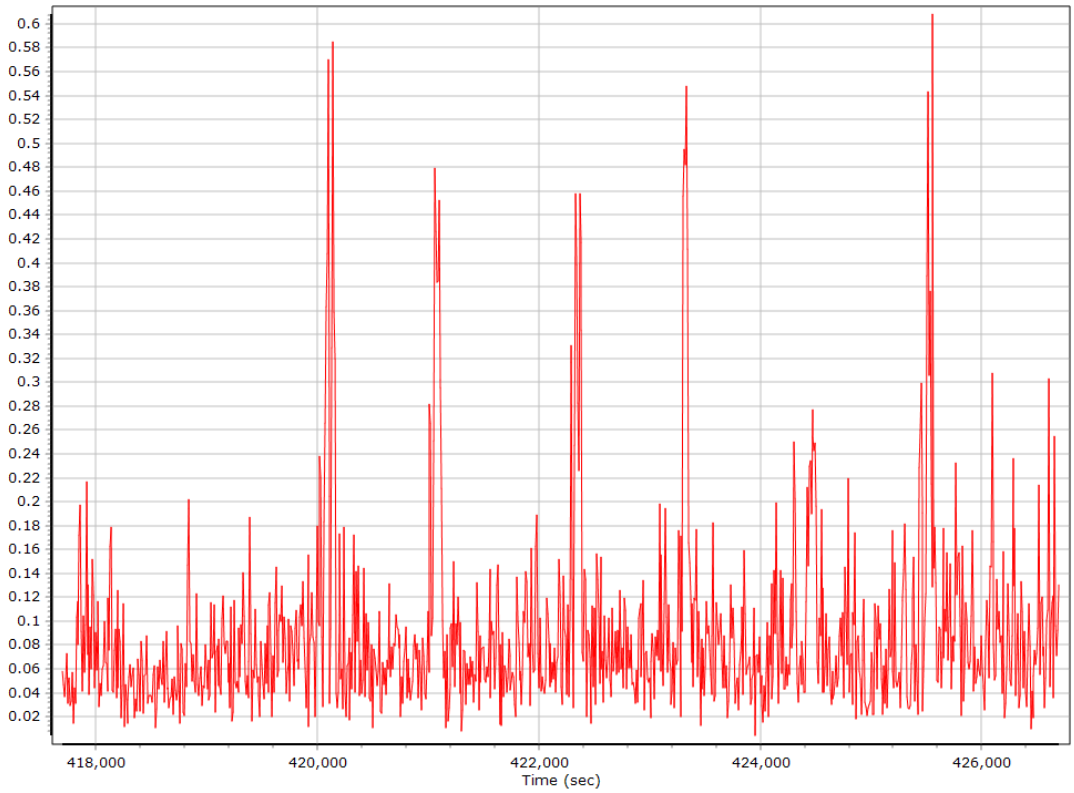
Ground Speed



Body Acceleration



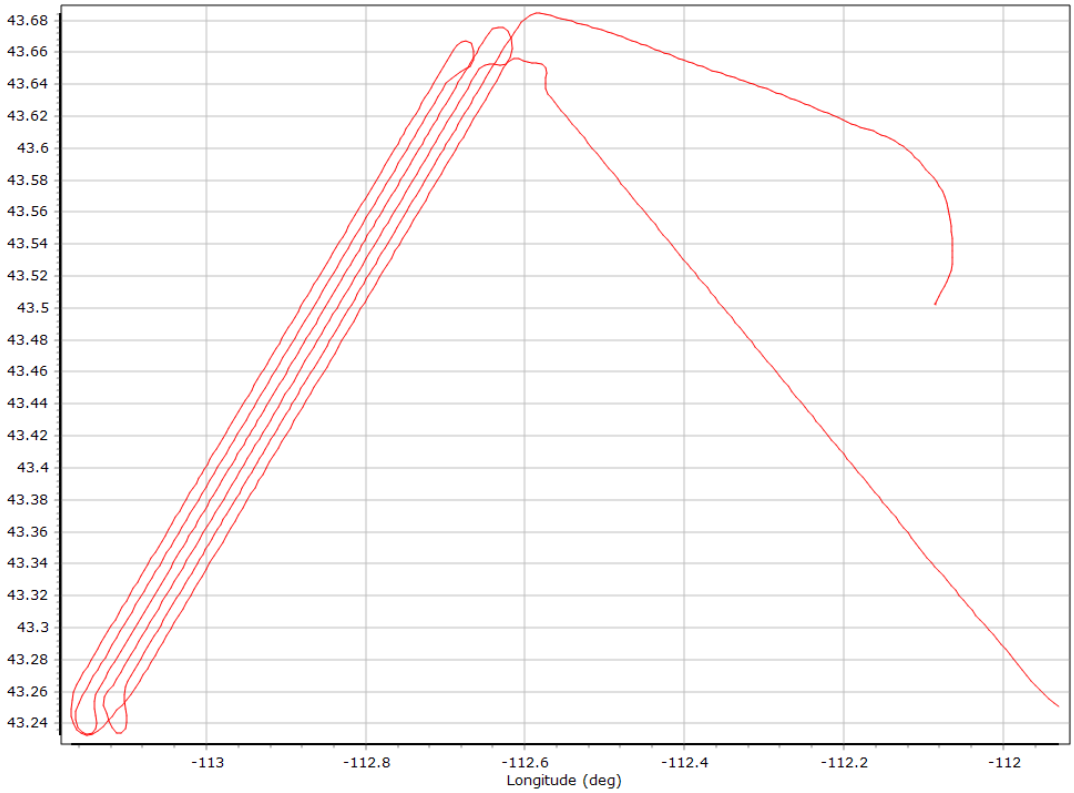
Total Body Acceleration



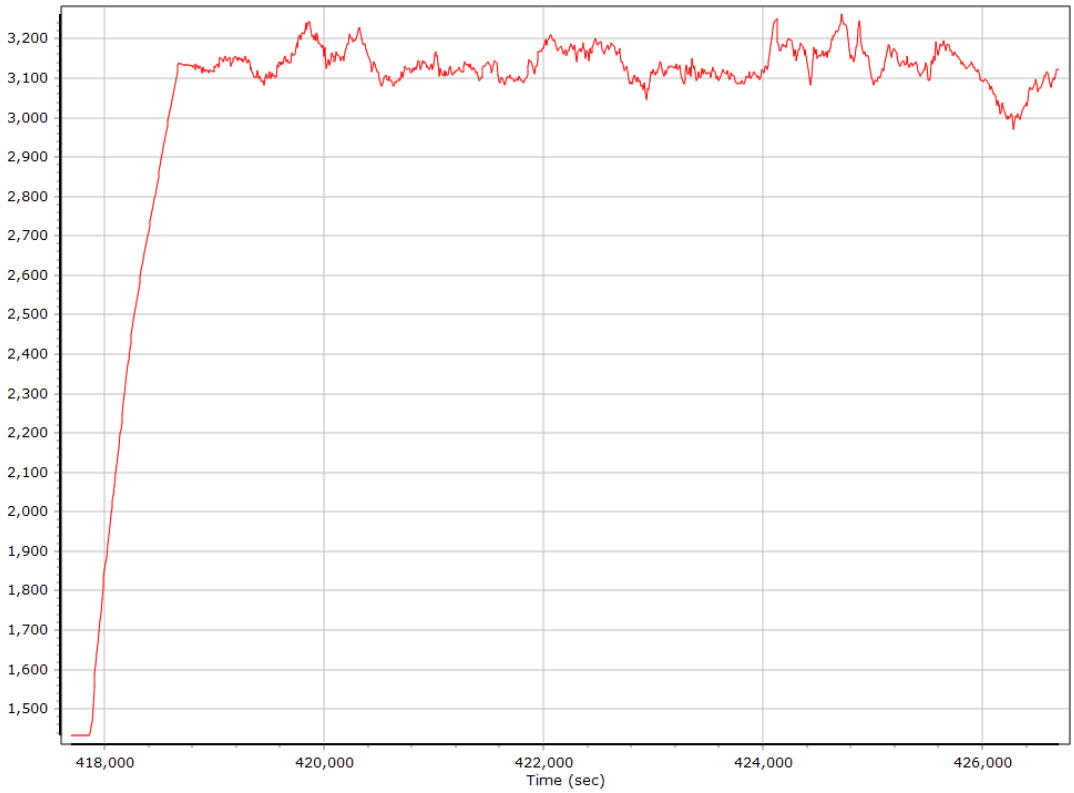
Body Angular Rate

Forward Processed Trajectory Information

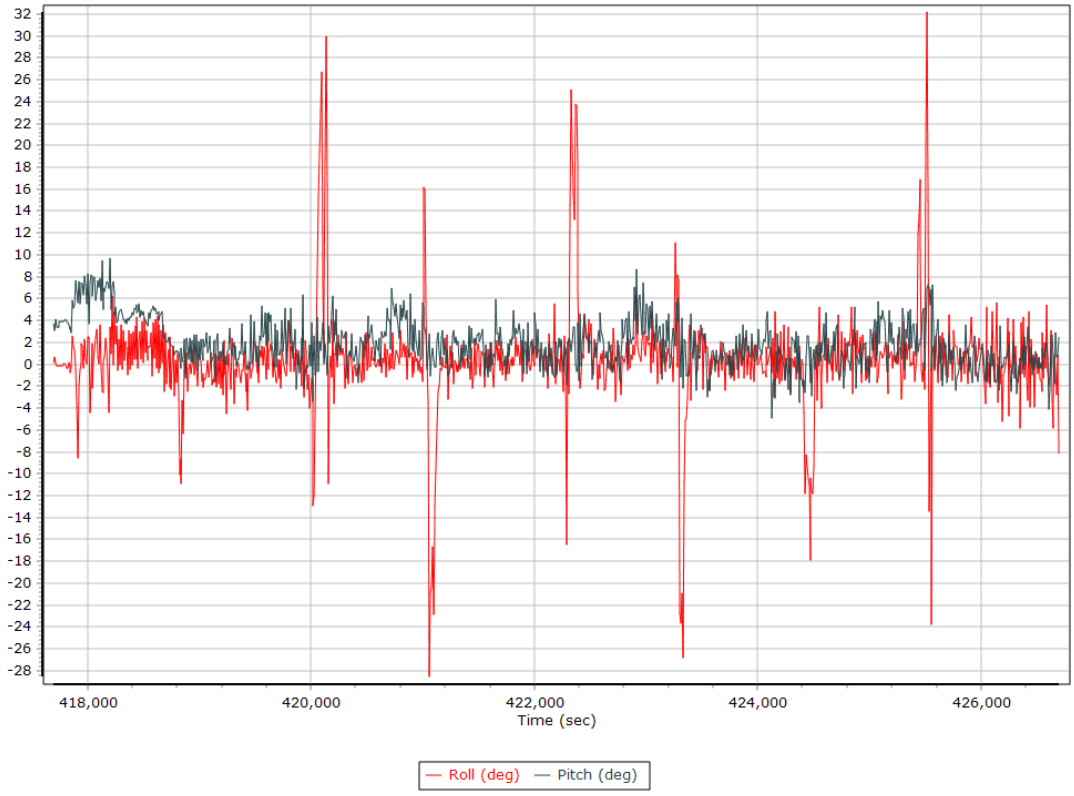
Top View



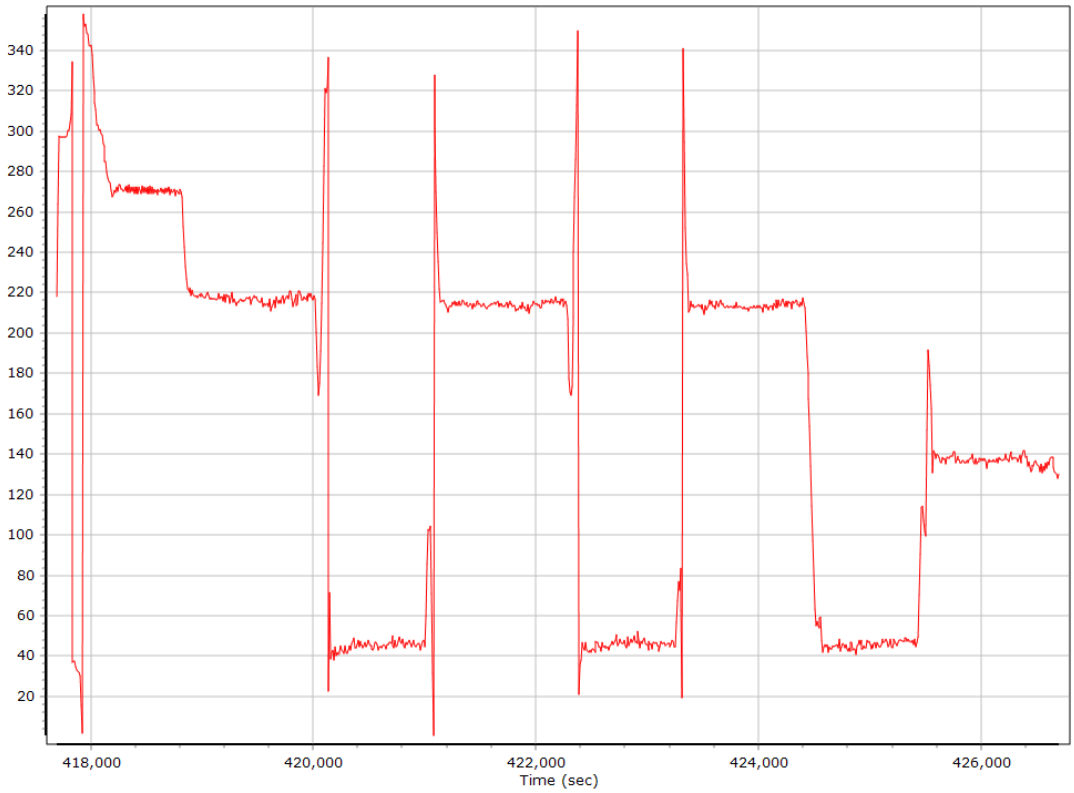
Altitude



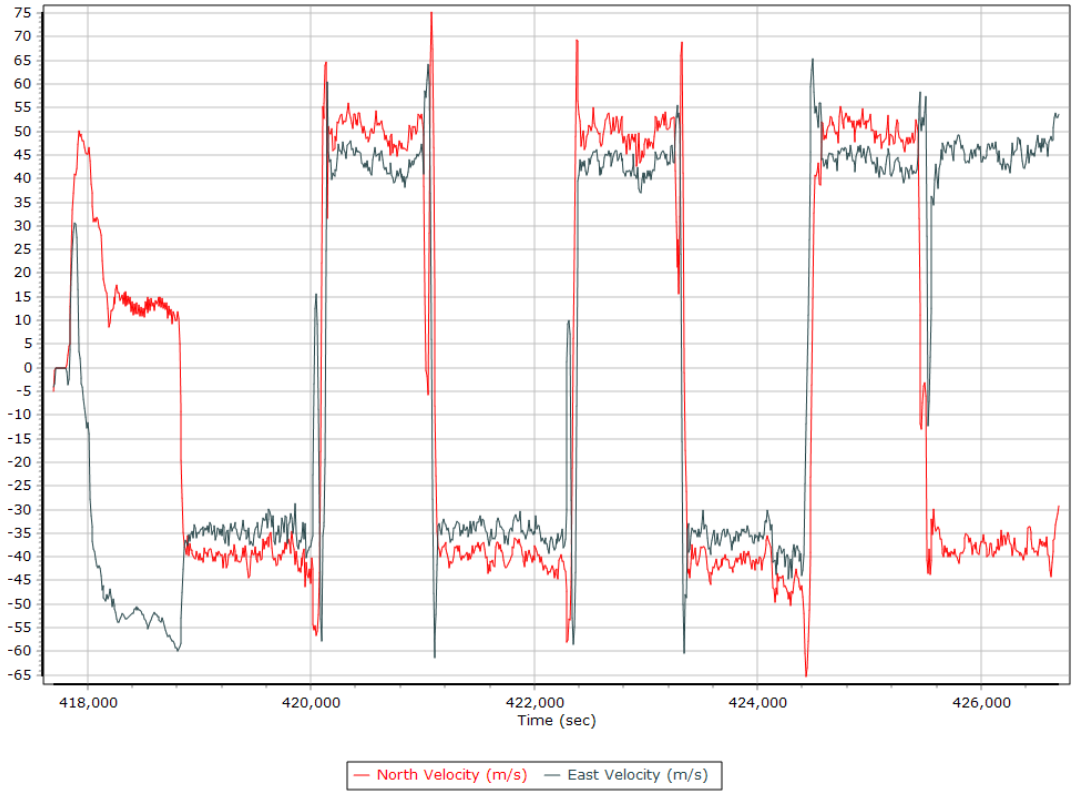
Roll/Pitch



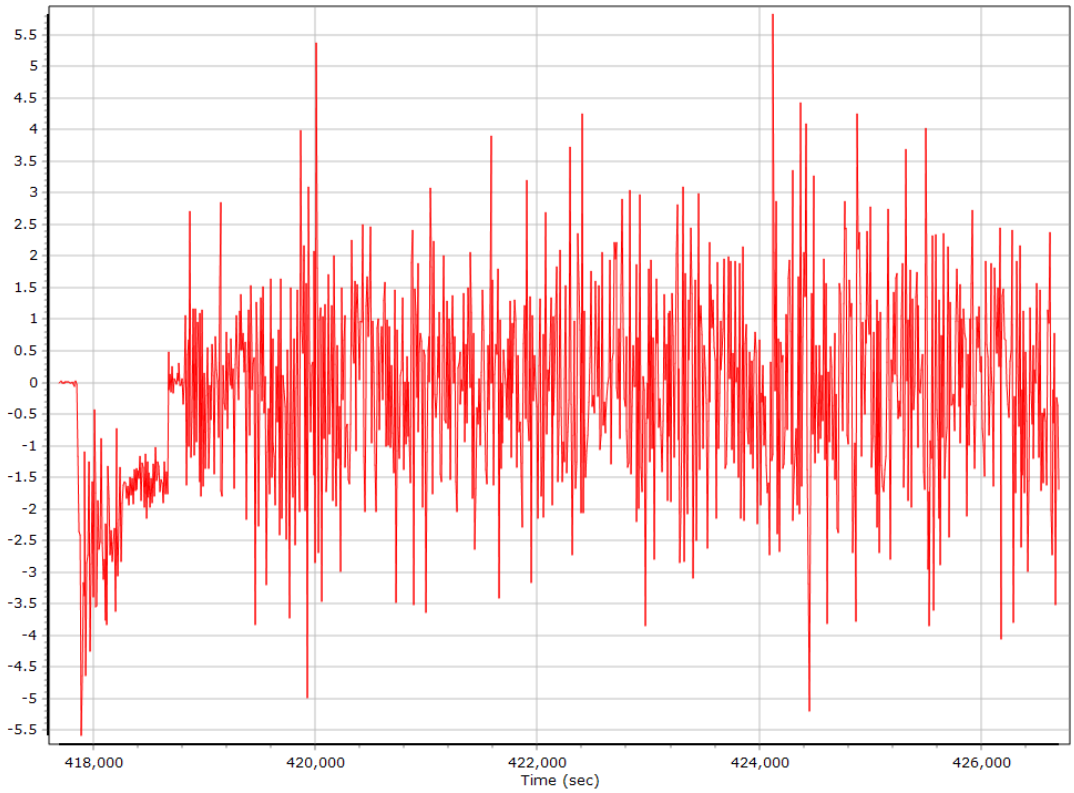
Heading



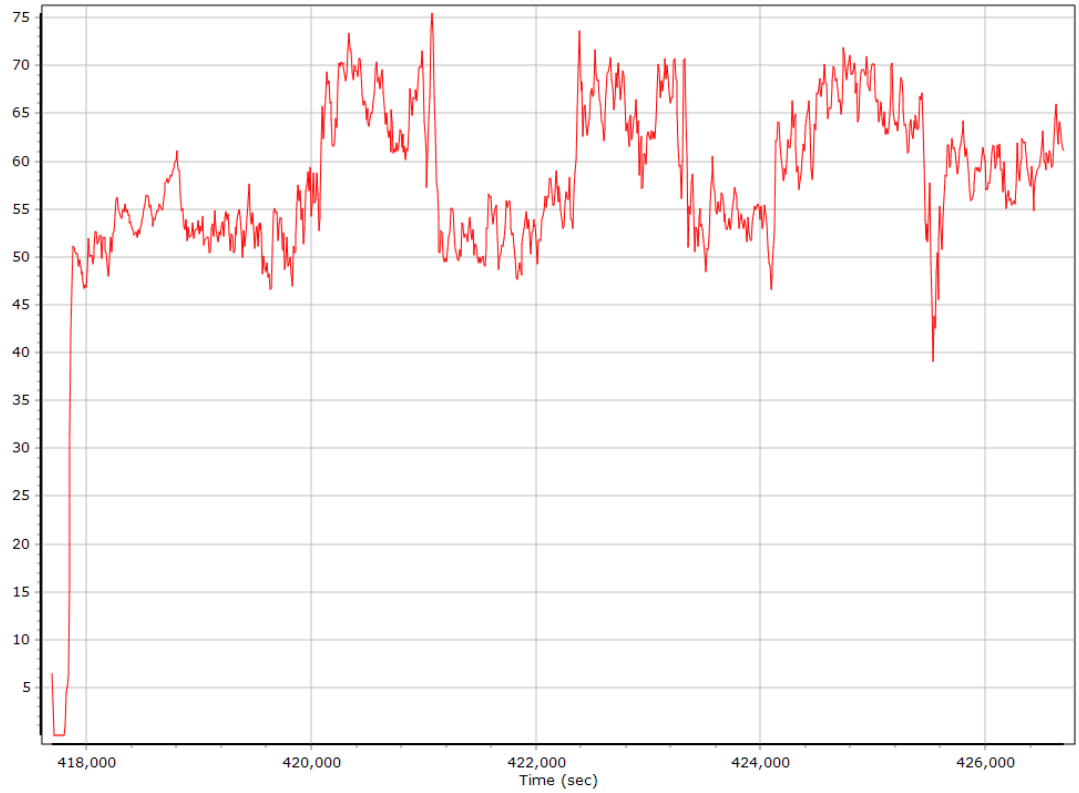
North/East Velocity



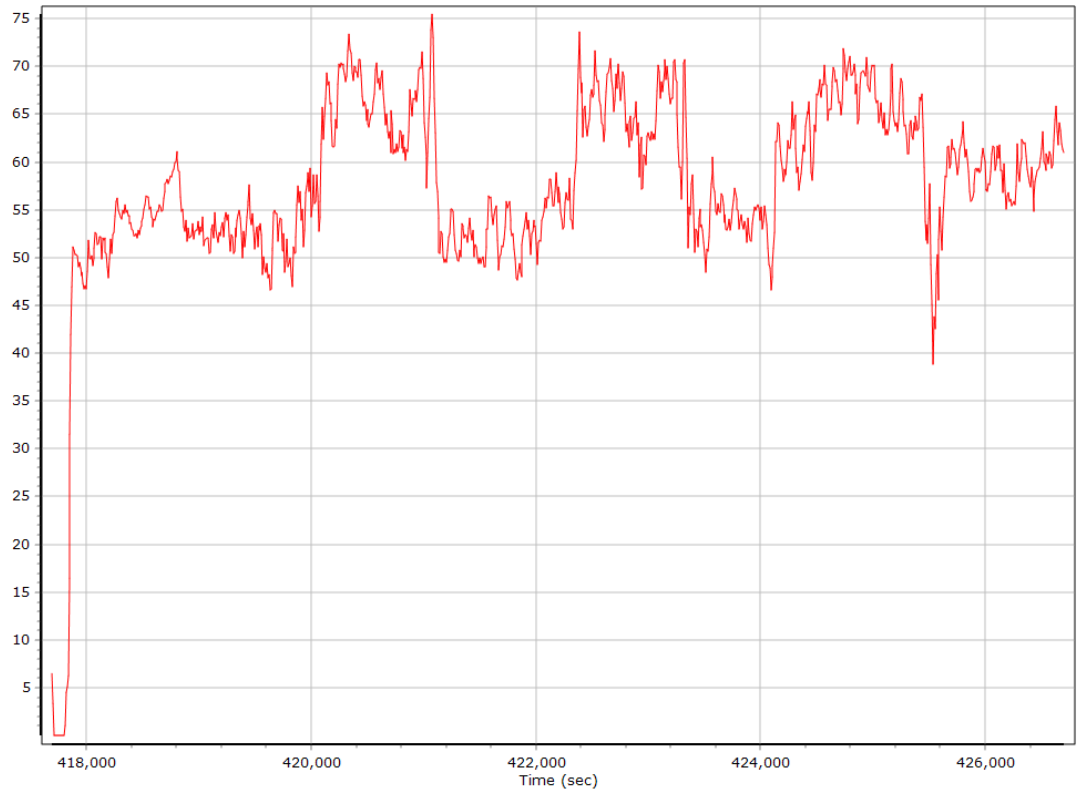
Down Velocity



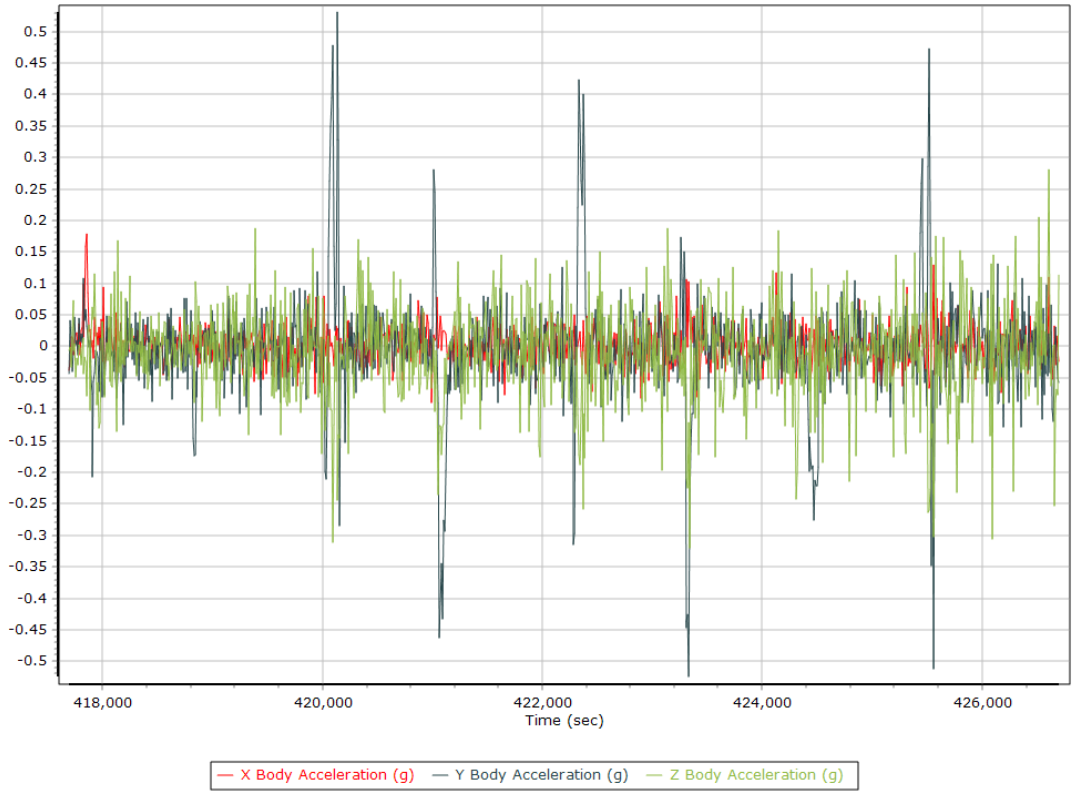
Total Speed



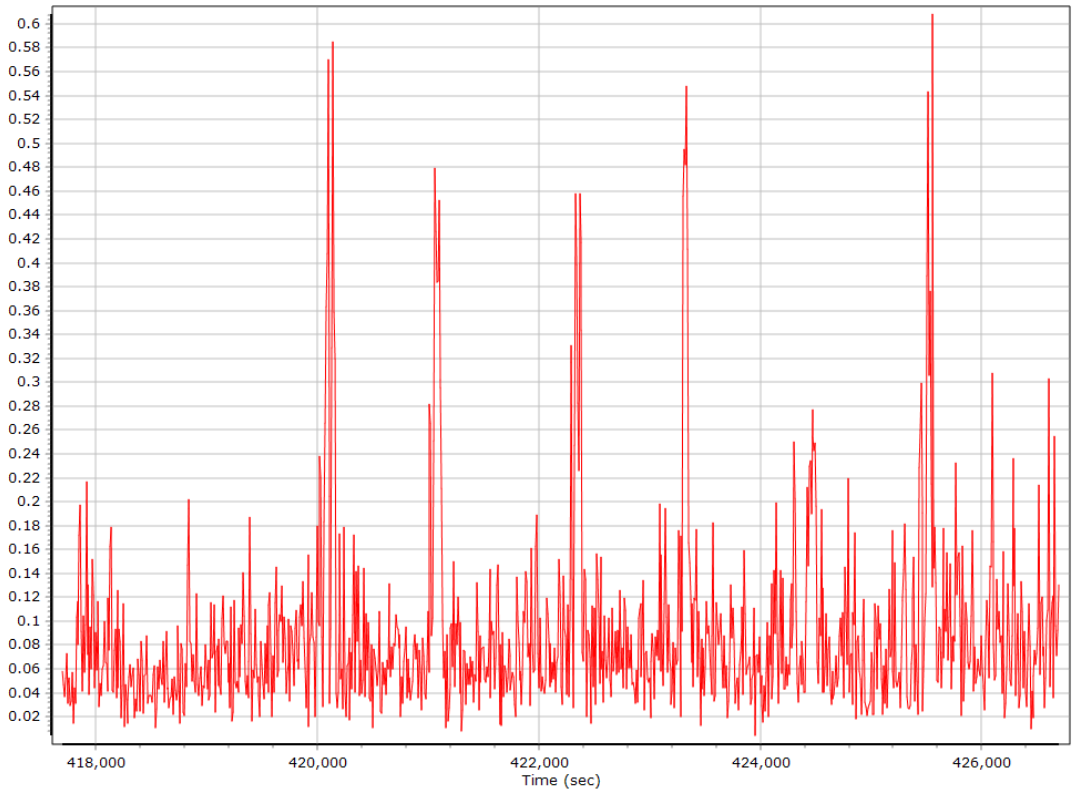
Ground Speed



Body Acceleration



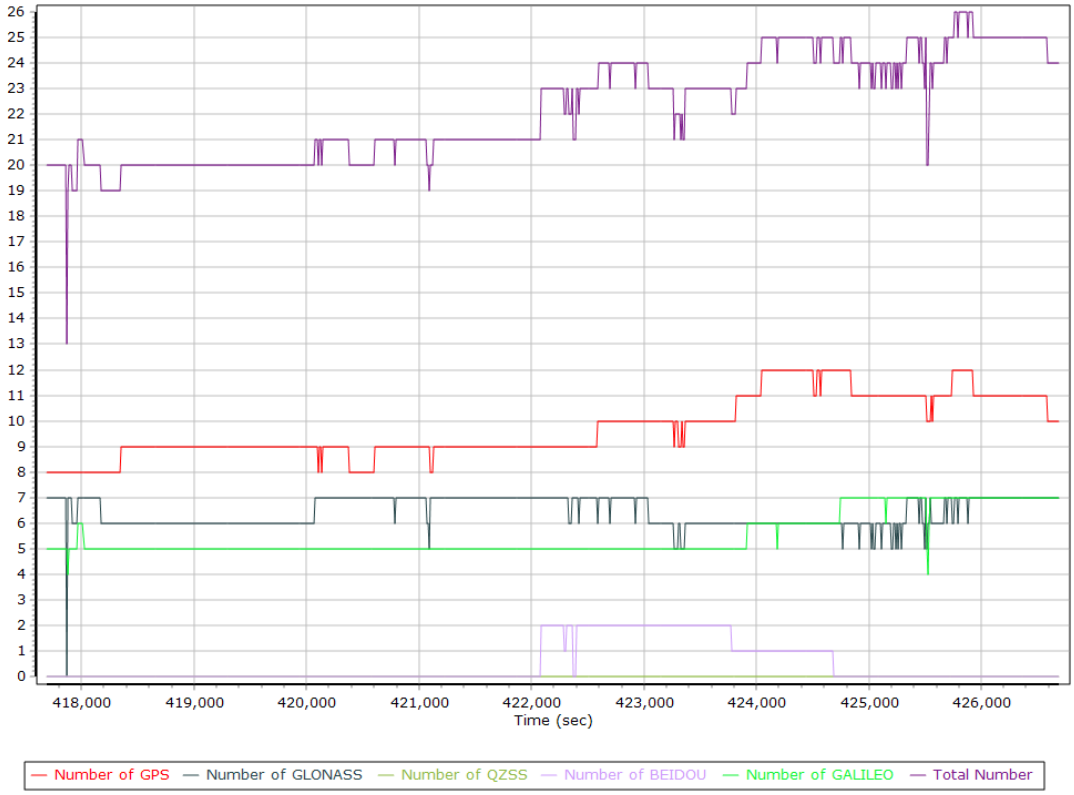
Total Body Acceleration



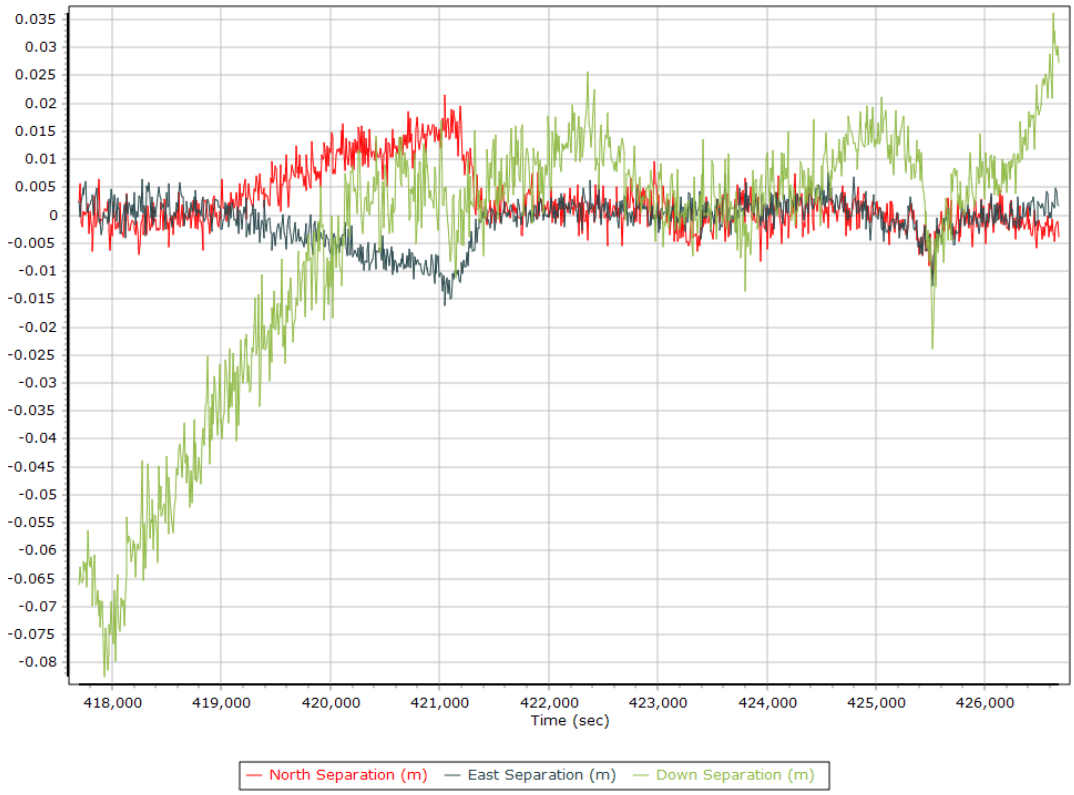
Body Angular Rate

GNSS QC

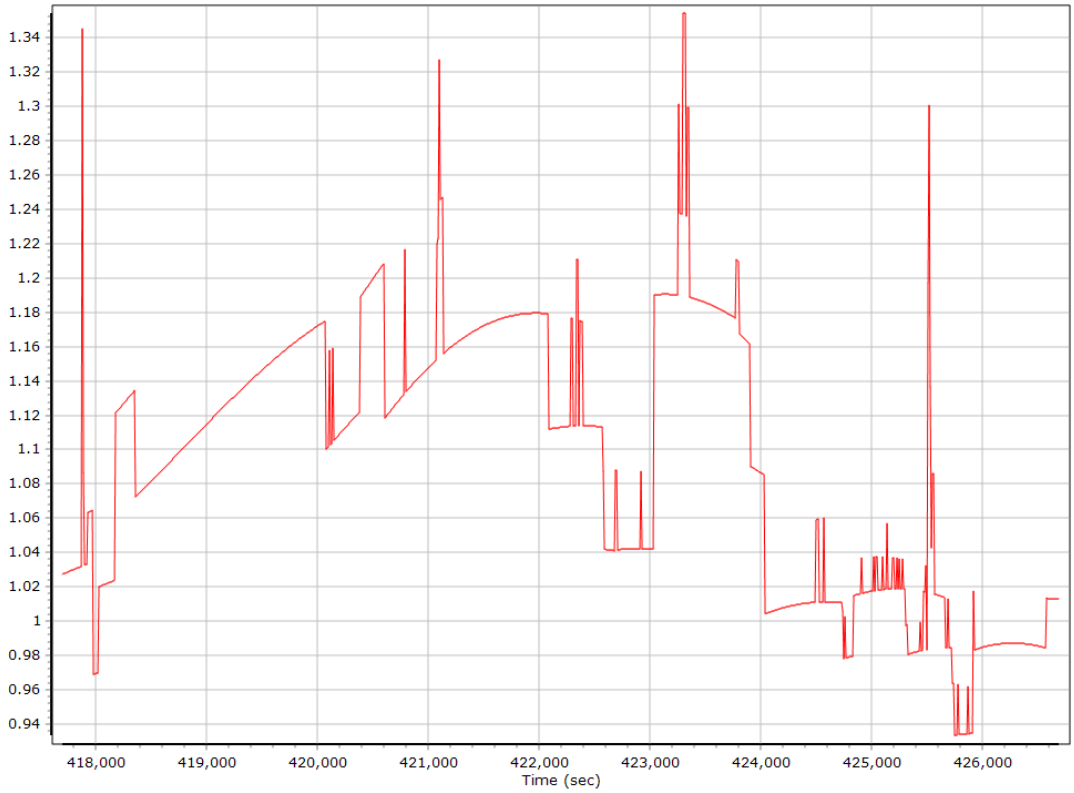
Num SVs in solution



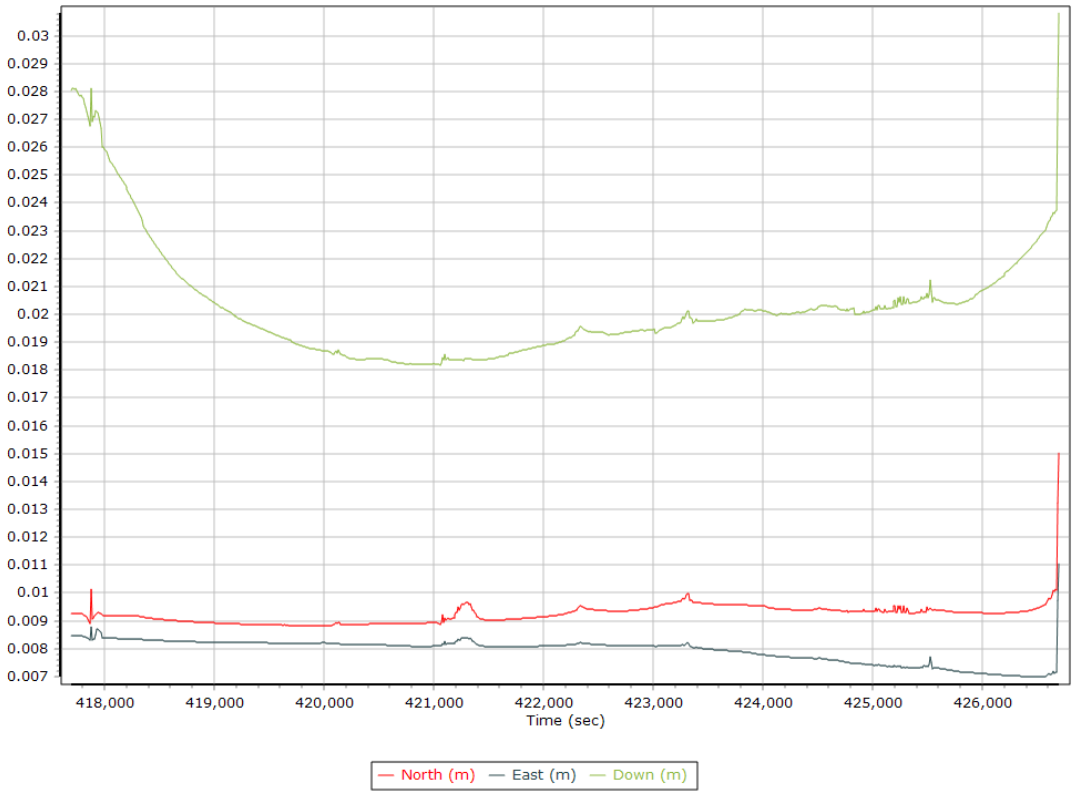
Forward/Reverse Separation



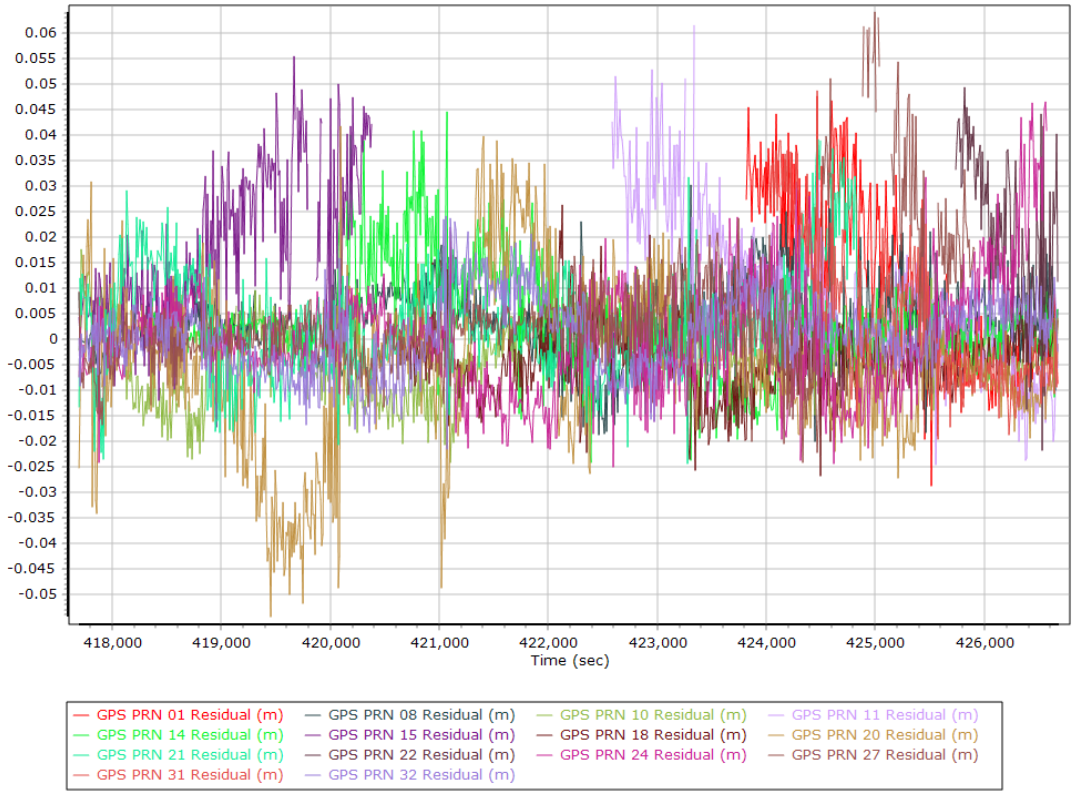
PDOP



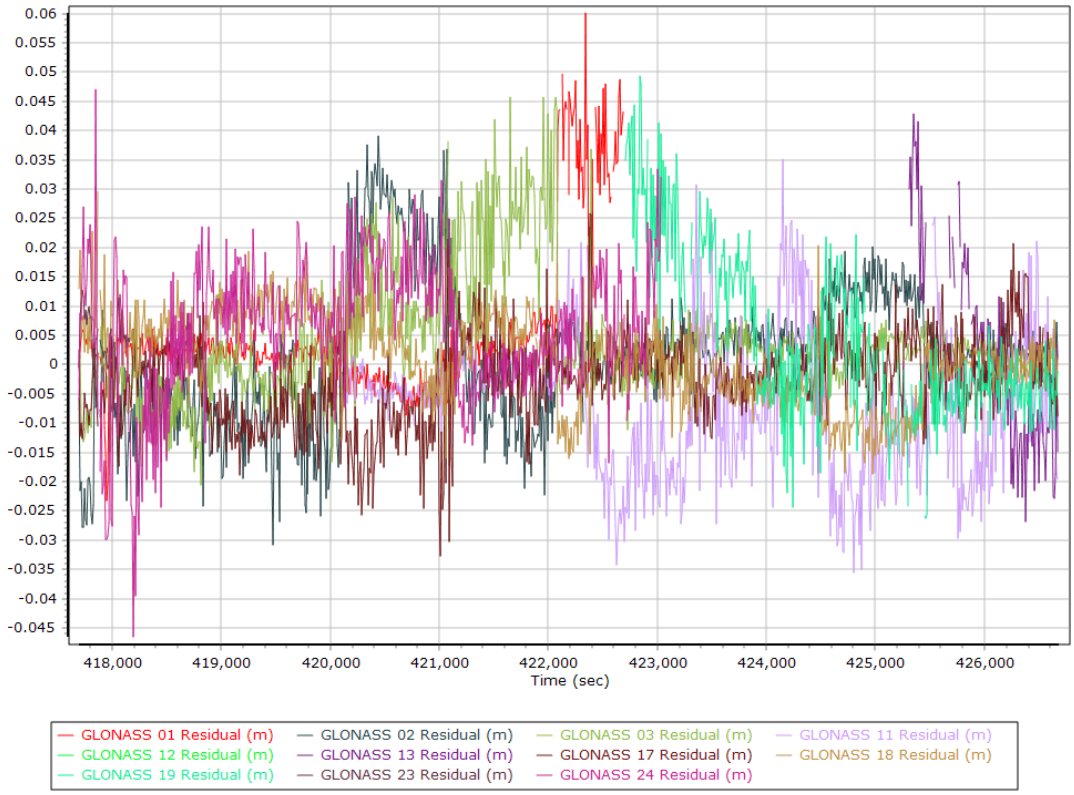
Estimated Position Accuracy



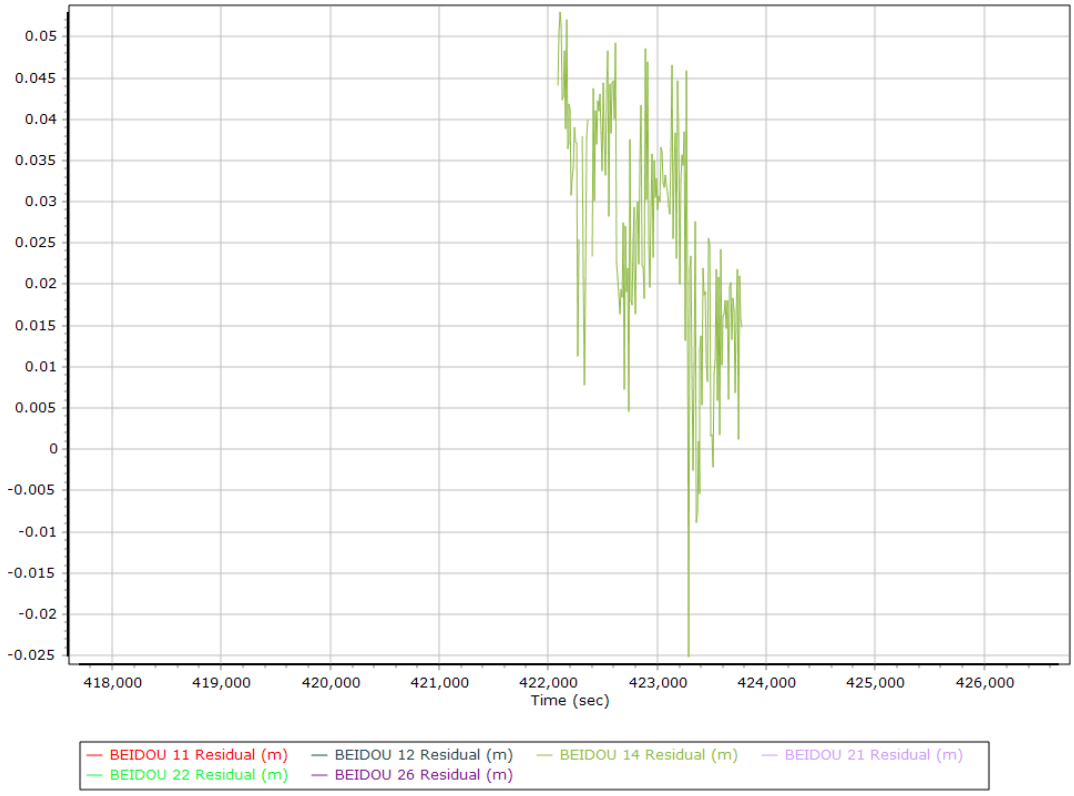
GPS Residuals



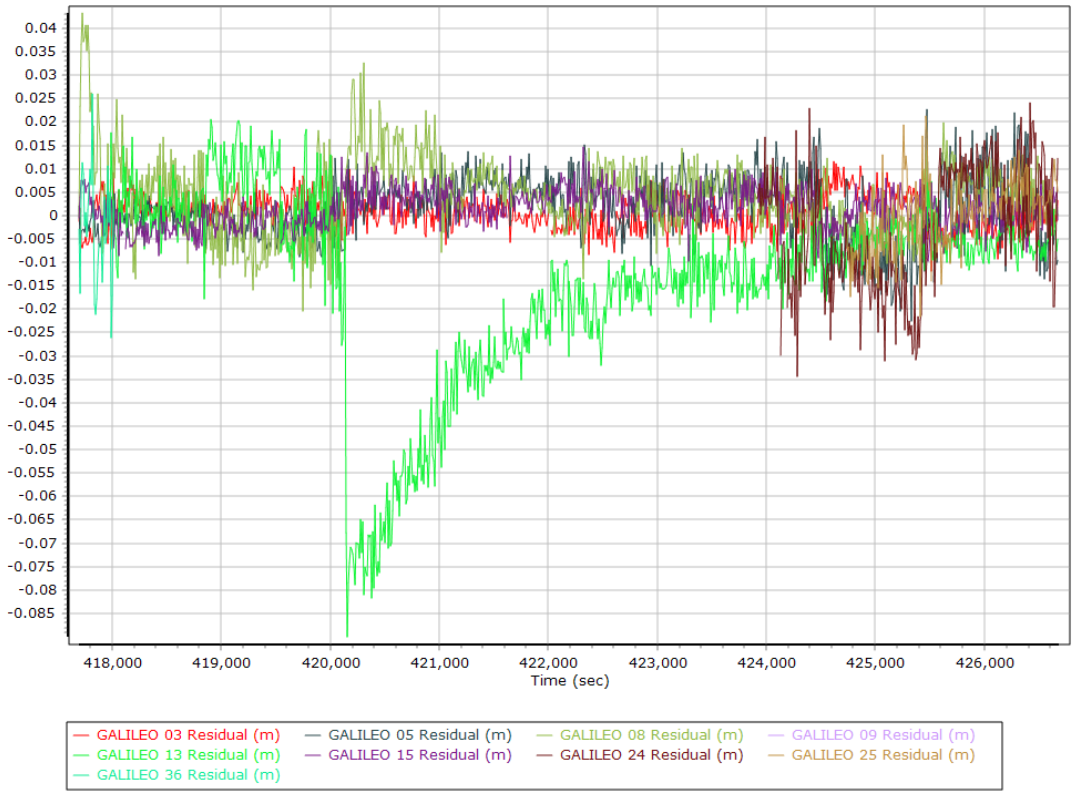
GLONASS Residuals



BEIDOU Residuals



GALILEO Residuals



GNSS-Inertial Processor Configuration

Processing mode	IN-Fusion PP-RTX		
Stabilized mount	False		
Processing start time	417535.000 (10/3/2019 7:58:55 PM)		
Processing end time	426701.000 (10/3/2019 10:31:41 PM)		
Initial attitude source	Real-Time VNAV/RNAV Attitude		
IMU Sensor Context	Processing with Onboard IMU		
Reference to IMU lever arm (m)	0.000	0.000	0.000
Reference to IMU mounting angles (deg)	0.000	0.000	180.000
Reference to Primary GNSS lever arm (m)	0.000	-0.315	-0.926
Reference to Primary GNSS lever arm std dev (m)	0.030	0.030	0.030
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

Calibrated Installation Parameters

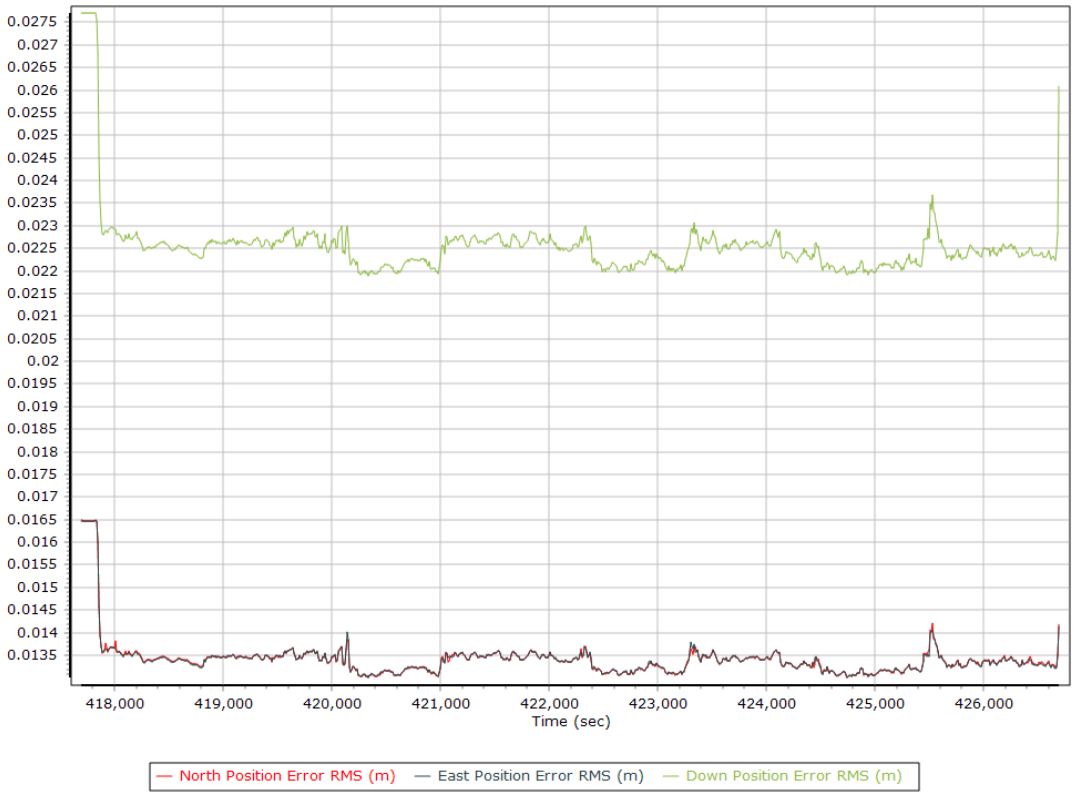
Reference-Primary GNSS Lever Arm (m)

IN-Fusion QC

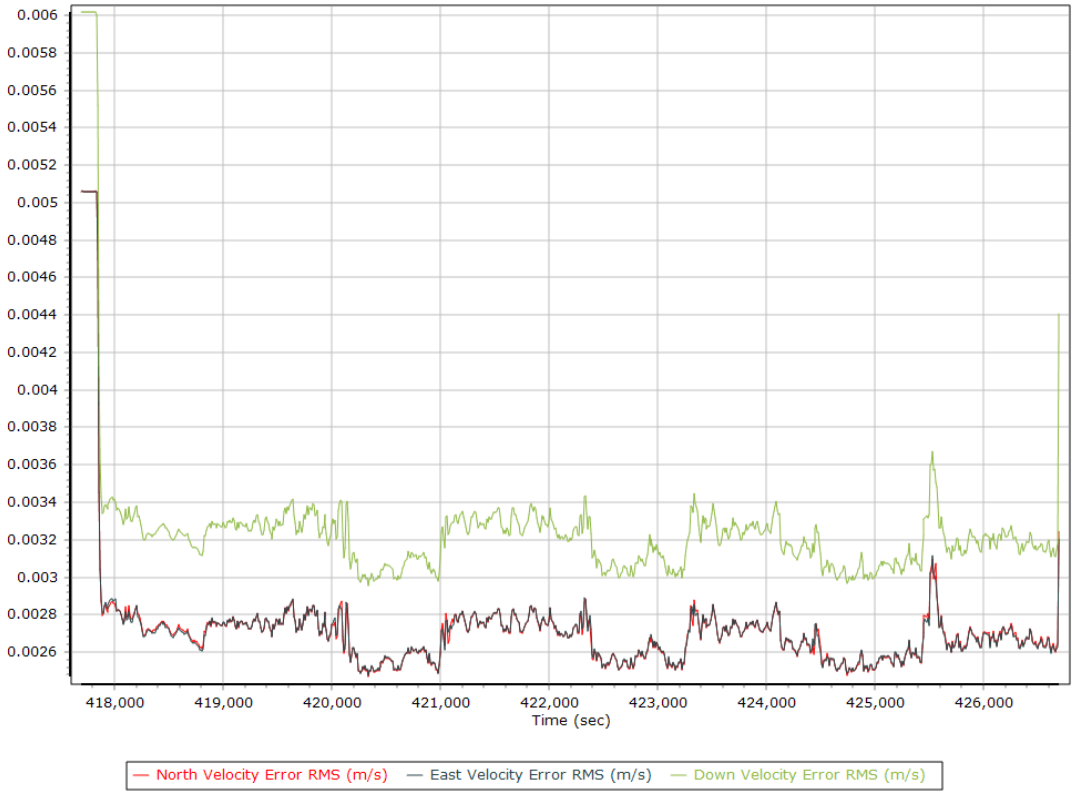
Forward Processed Estimated Errors, Reference Frame

Smoothed Performance Metrics

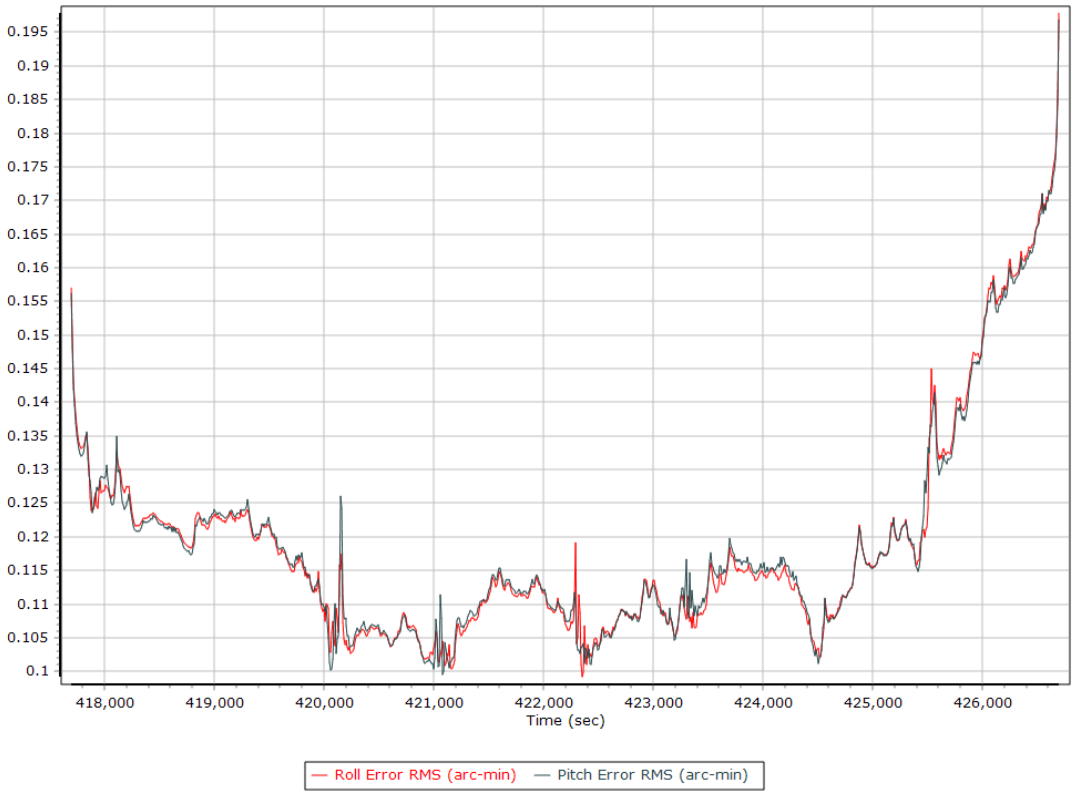
Position Error RMS (m)



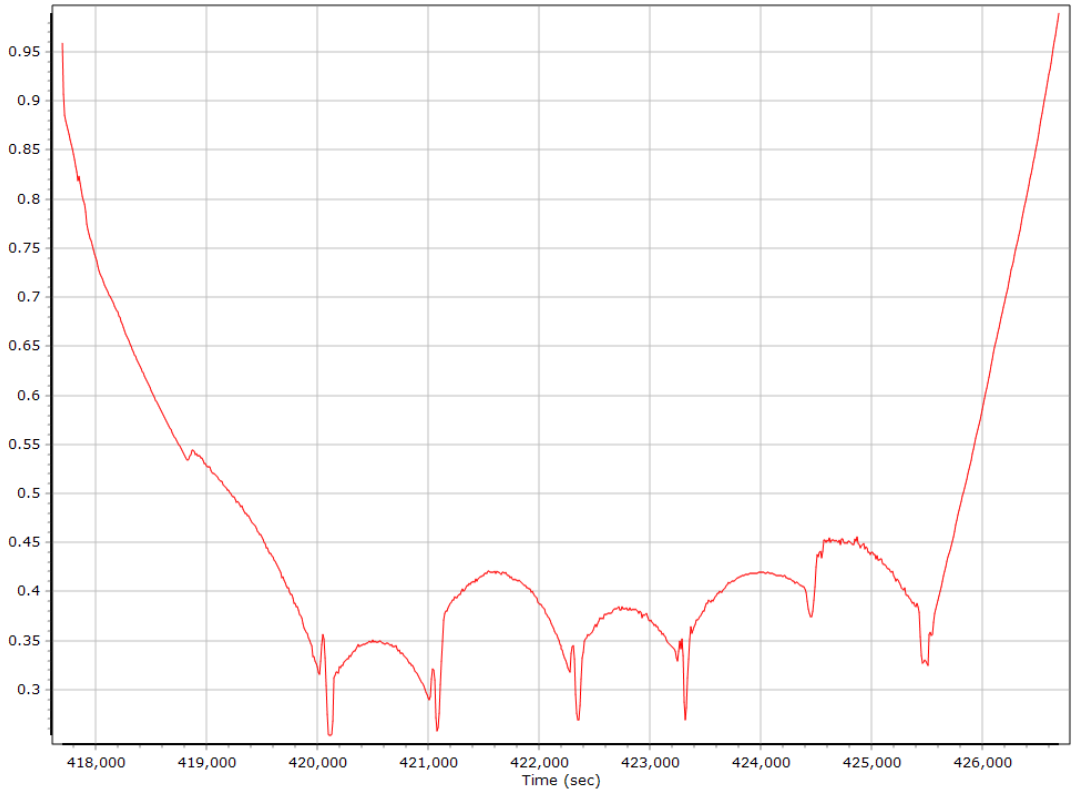
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

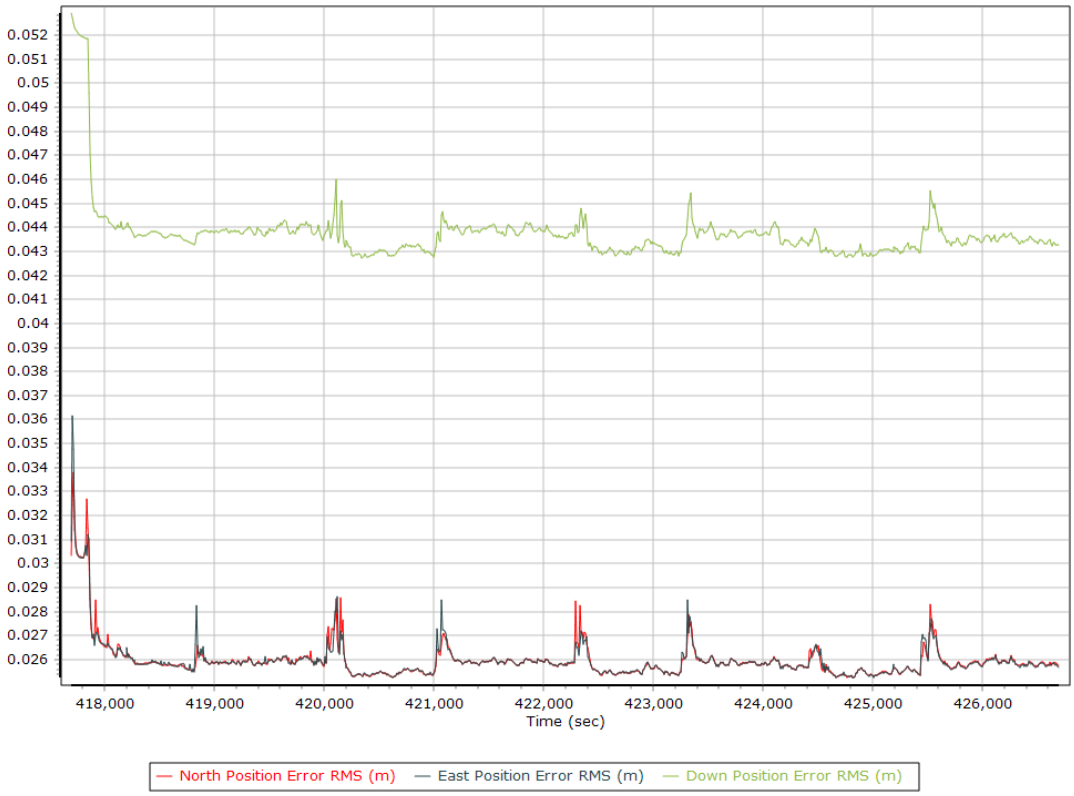


Heading Error RMS (arc-min)

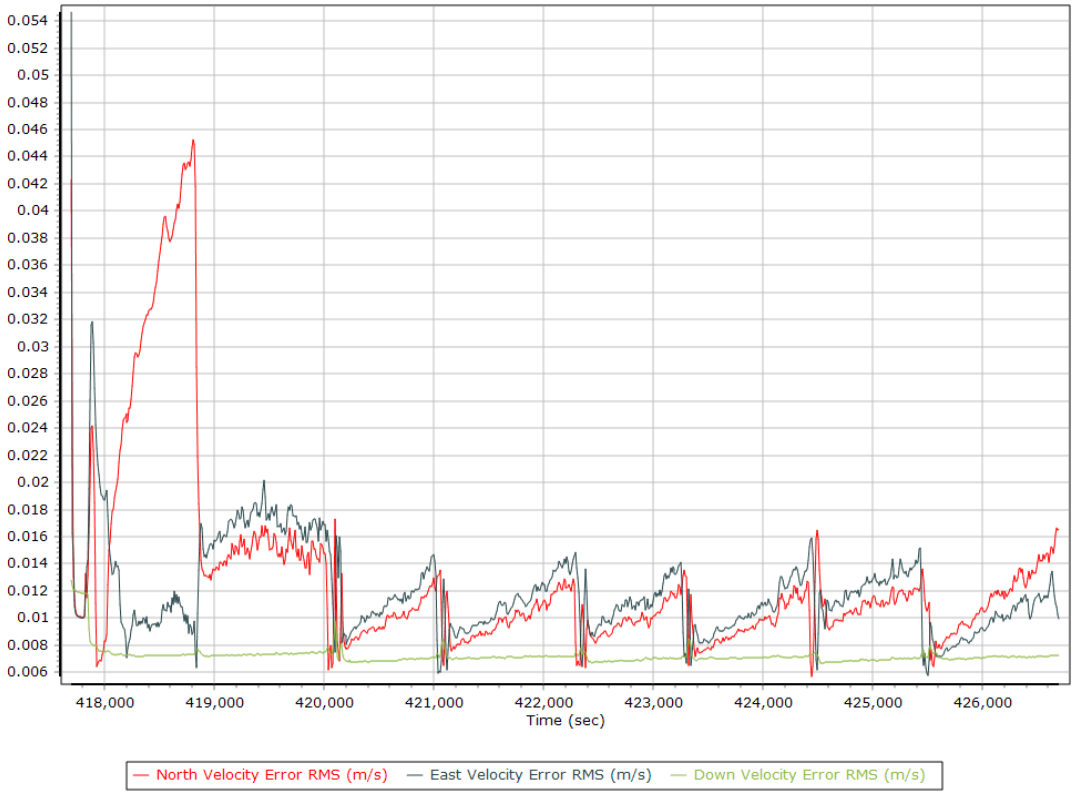


Forward Processed Performance Metrics

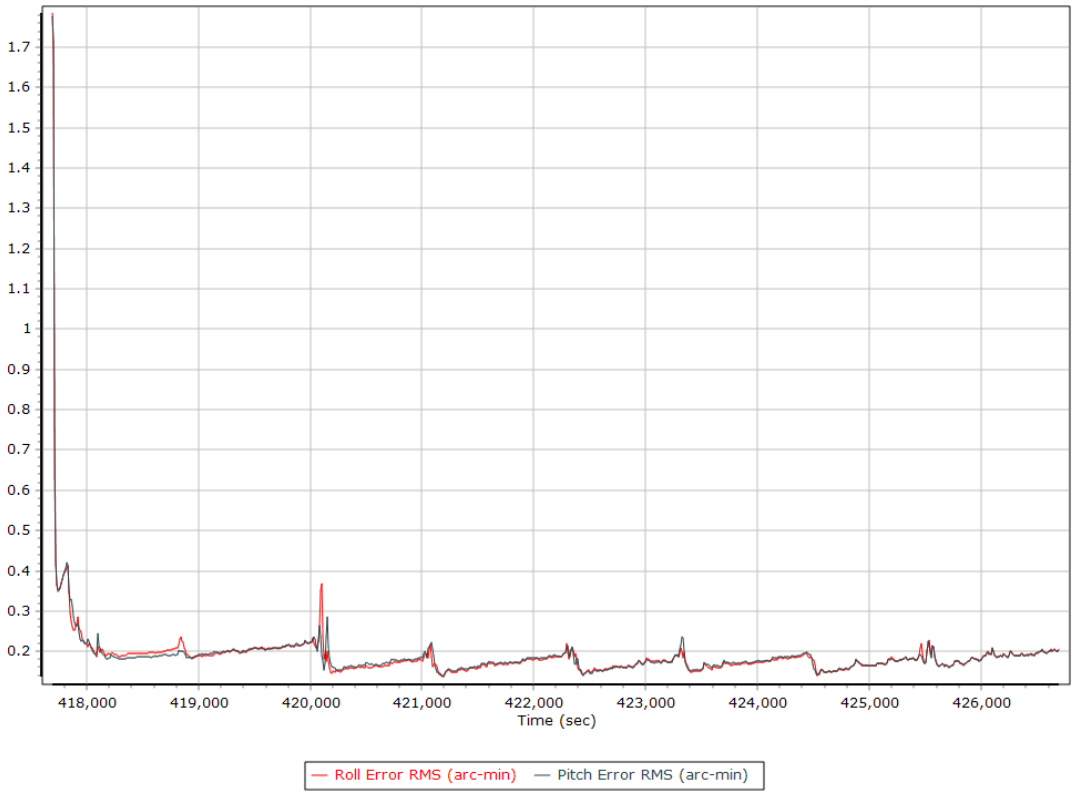
Position Error RMS (m)



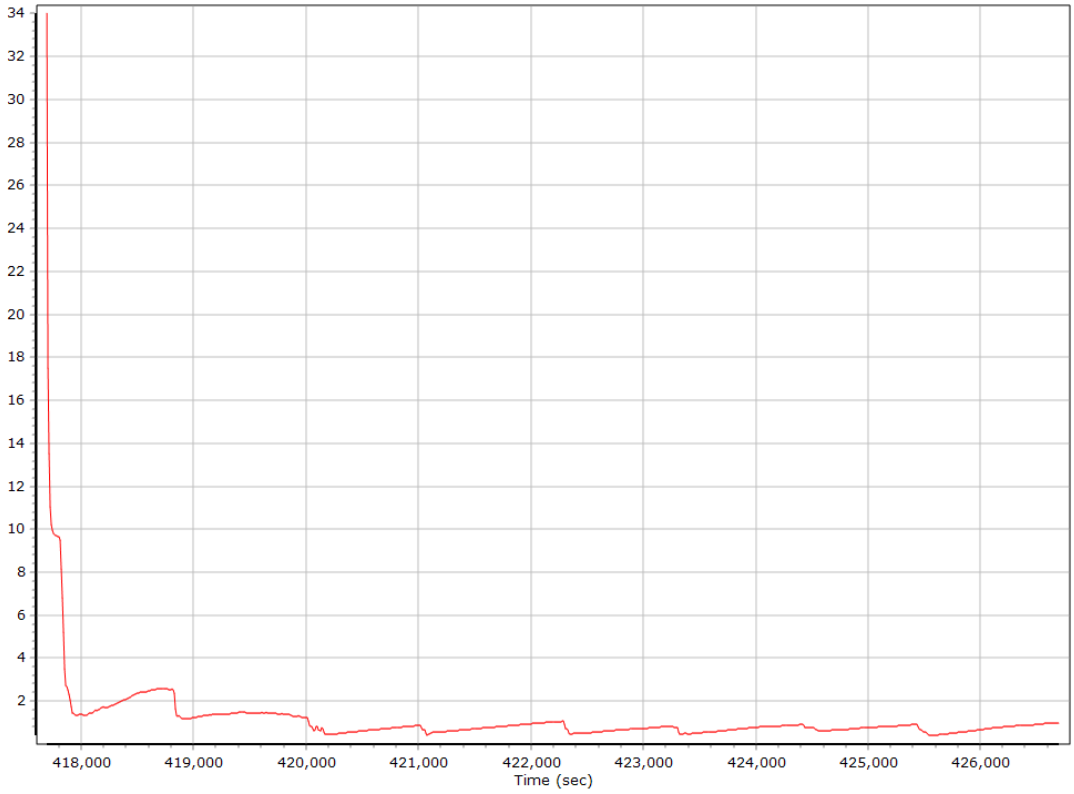
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

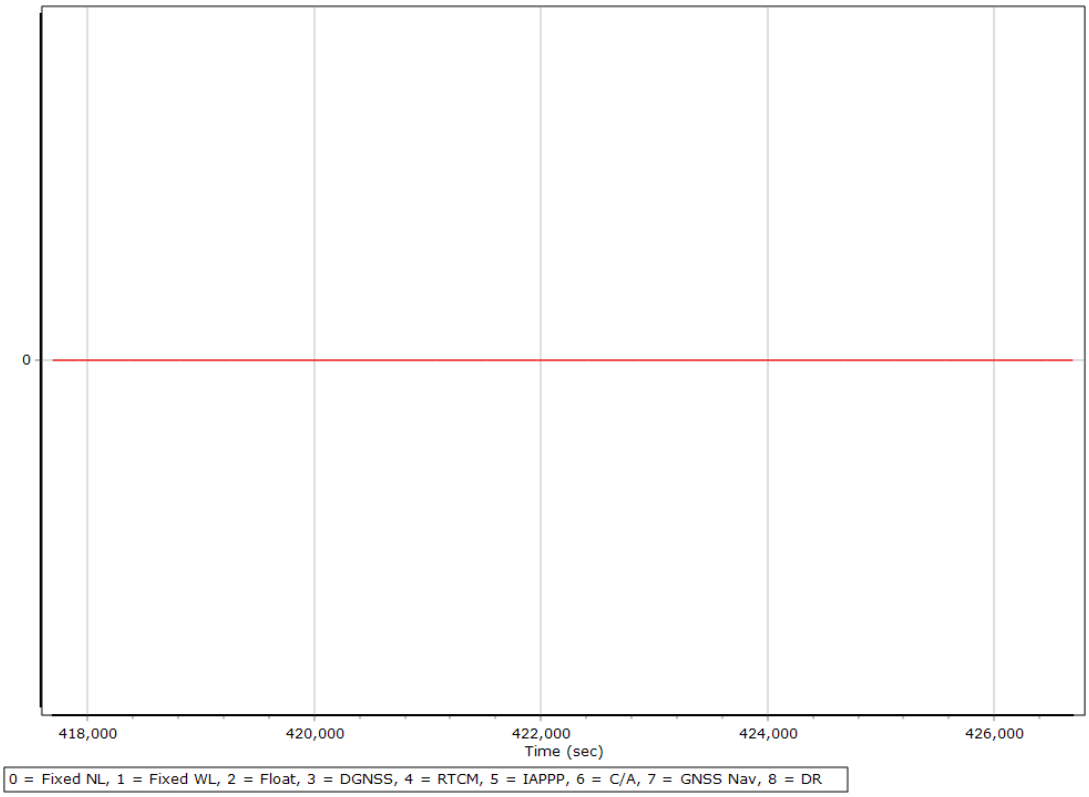


Heading Error RMS (arc-min)

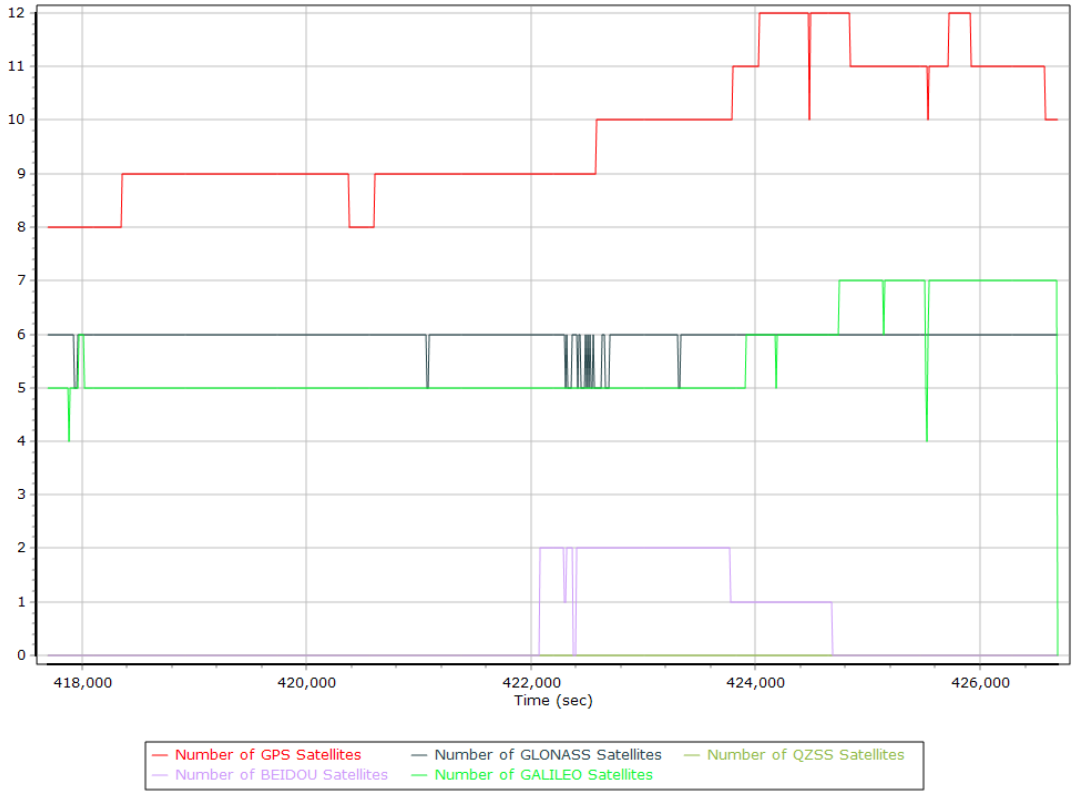
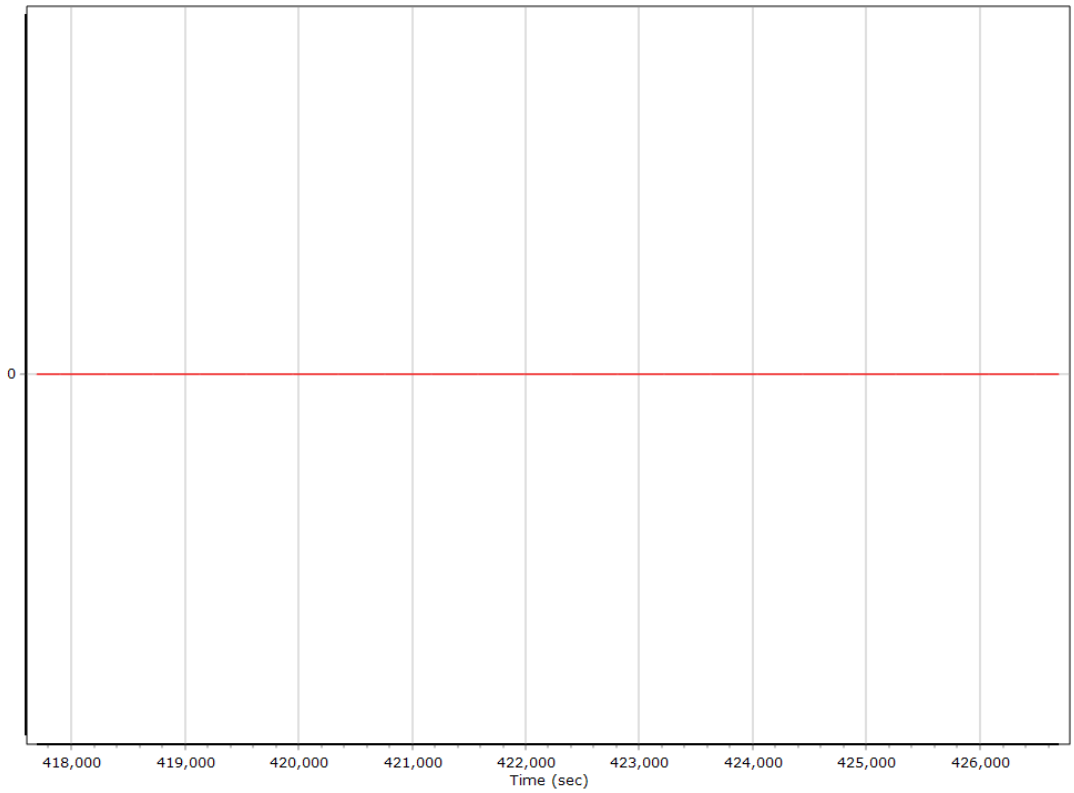


Forward Processed Solution Status

Processing Mode



Number of Satellites



Baseline Length