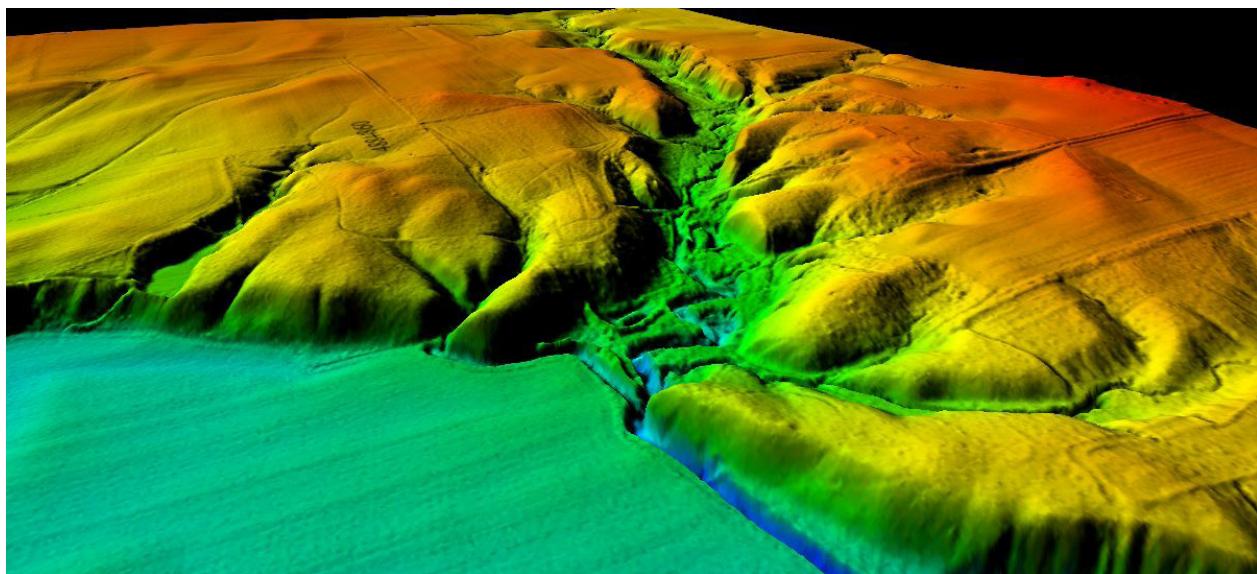


2014 Will County, Illinois 1 PPSM LiDAR Report



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1 PPSM LiDAR Survey

Will County, Illinois

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1. Introduction

This report contains a summary of the Light Detection and Ranging (LiDAR) data acquisition and processing for the project area to include Will County, Illinois.



1.1 Contact Info

Questions regarding the technical aspects of this report should be addressed to:

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1.2 Purpose

Quantum Spatial acquired high accuracy LiDAR data of Will County, Illinois in accordance with needs outlined by the Facilities and Services, Planning Division of the University of Illinois at Urbana-Champaign. Data provided to Facilities and Services will aid in analysis, planning and management of Will County.

1.3 Project Locations

This project consists of Will County, Illinois. The area of acquisition is approximately 922 square miles, located in northeastern Illinois. Image 1.3 on the following page shows the relative location of this area.

1.4 Time Period

LiDAR data acquisition for complete coverage of the project occurred between April 5th and April 19th, 2014. Data collection was completed in eleven (11) flight missions totaling one hundred forty-nine (149) flight lines, including cross flights.

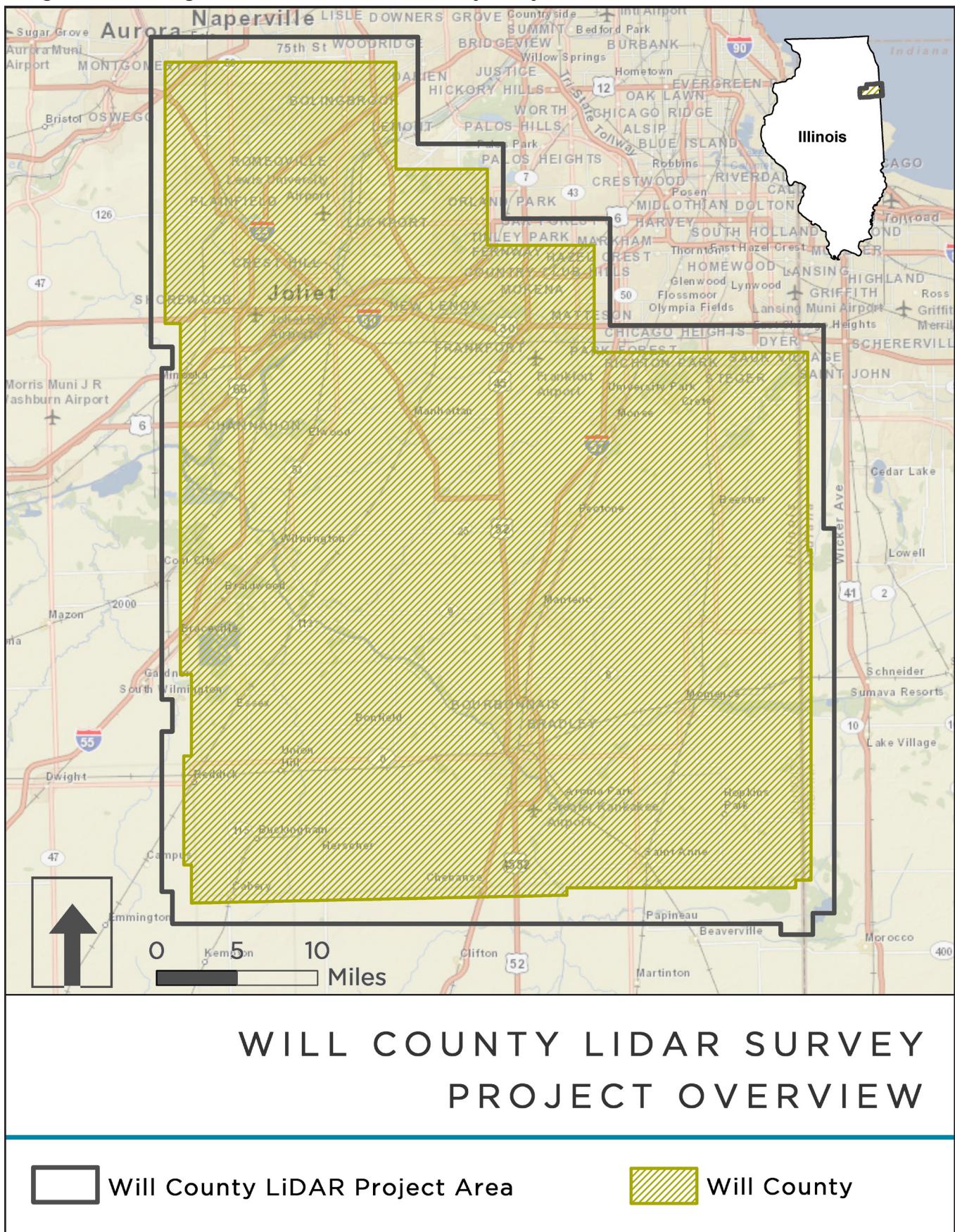
1.5 Project Scope

Data acquired with aircraft and LiDAR sensor operated by Quantum Spatial, Inc. is high accuracy LiDAR topographic data and is complete for the surface of Will County. The project area is approximately 922 square miles.

As documented in the Task Order, collected data was to achieve a Fundamental Vertical Accuracy (FVA) of 18.13cm (0.59 ft) at a 95% confidence level, and have an RSME of 9.25cm (0.30 ft) in the open terrain land cover category based on a Triangulated Integrated Network (TIN) of the LiDAR points and from values of the Digital Elevation Models (DEM) derived from LiDAR data.



Image 1.3: The image below shows the Will County study area.





2. Geodetic Control

Ground surveys were conducted to provide control points for LiDAR dataset indexing. Additional ground control points were collected in represented ground cover categories to provide for vertical accuracy assessment of the dataset pursuant to Federal Emergency Management Agency (FEMA) guidelines.

3. LiDAR Acquisition and Procedures

Image 3.1: Underbelly of QSI aircraft



3.1 Acquisition Time Period

LiDAR data acquisition and Airborne GPS control were completed between April 5th and April 19th, 2014. Data from the eleven (11) flight missions are included in the project.

3.2 LiDAR Planning

The LiDAR data for this project was collected with an aircraft operated by Quantum Spatial. The aircraft was equipped with LiDAR sensor systems as well as systems to collect GPS and IMU positioning data during flight. All flight planning was completed using Leica MissionPro software and data collection was completed using a Leica ALS70 sensor.



3.3 LiDAR Acquisition

Data acquired from eleven (11) flight missions were utilized to provide project area coverage. Refer to Table 3.0 for acquisition parameters. Acquired swaths can be seen in Image 3.0 on the following page. Section 7 contains the flight logs.

A Leica ALS70 sensor was used on board a fixed-wing aircraft. Airborne GPS and IMU position and trajectory data of the LiDAR sensor were also acquired during the time of flight.

Before take-off, the LiDAR system and the Airborne GPS and IMU system were initialized for a period of five minutes and continued in operation after landing for another five minutes. The missions acquired data according to the planned flight lines and included a minimum of one (usually two) cross flights. The cross flights were flown perpendicular to the planned flight lines and their was data used in the in-situ calibration of the sensor.

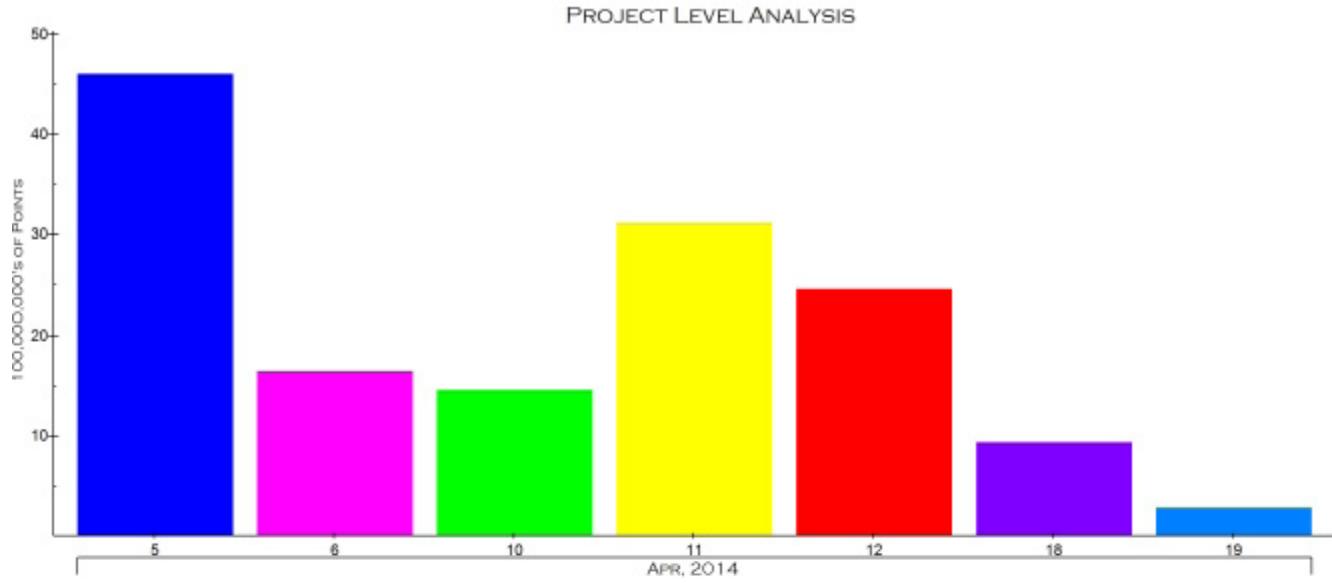
Table 3.0: Acquisition Parameters

1 point per square meter (ppsm)

Sensor Type	Leica ALS - 70
Sensor ID	SN7161
Field of View	+/- 20 degrees
Flying Height (Above Ground Level)	1,900 meters
Pulse Rate Frequency	273 kHz
Scan Angle (degrees)	40 degrees
Ground Speed	150 kts
Targeted Pulse Density	1.0 ppsm
Minimum Overlap	55%

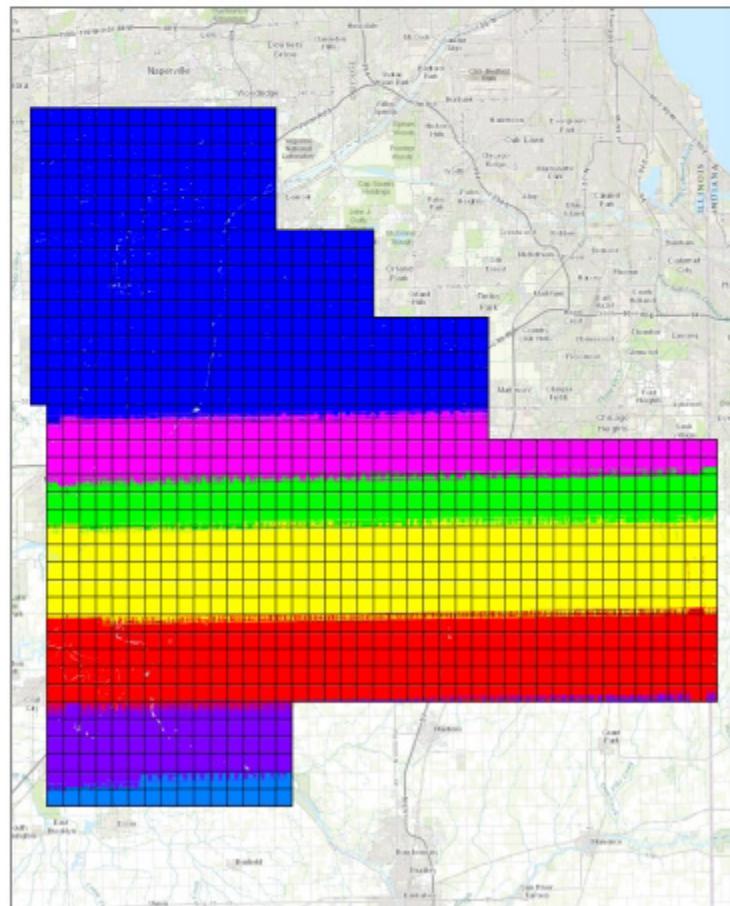


Image 3.3a: Swaths for 1 point per square meter (ppsm) data, colored by mission date.



APRIL, 2014

Day	Key	# of Points	% of Overall
5	Blue	4,588,103,230	31.9%
6	Magenta	1,631,847,113	11.4%
10	Green	1,447,011,675	10.1%
11	Yellow	3,077,665,857	21.4%
12	Red	2,442,648,291	17.0%
18	Purple	915,959,751	6.4%
19	Blue	270,531,069	1.9%





4. Quality Control Surveys

Ground survey points were collected by Quantum Spatial, Inc. The point measurements were used in calibration and evaluation of LiDAR data position.

See Section 9 for further details of the ground survey control data.

5. LiDAR Calibration and Processing

5.1 LiDAR Calibration

Table 5.1 LiDAR Calibration Steps	Software Used
Resolve GPS kinematic corrections for aircraft position and aligns all source data by time and filters. Smoothes the data, and provides a trajectory file indicating the latitude, longitude, ellipsoidal height, roll, pitch and heading of the scanner at intervals of 1/200 second in .sol format.	Leica IPAS TC v. 3.2
Calculate laser point position by associating .sol file information to each laser point return time, with offsets relative to scan angle, intensity, etc. included. As part of this process, correction for atmospheric refraction (bending) of the light path and correction for variations in the speed of light over the path are made. The post processor also provides inputs for various alignment coefficients (e.g., roll, pitch, heading, range offsets, etc.). This process creates the raw laser point cloud data for the entire survey in *.las (ASPRS v1.2) format, in which each point maintains the corresponding scan angle, return number (echo), intensity, and x, y, z information.	Leica ALS Post Processor v. 2.75 Build #25
Import .las strips from ALS Post Processor into GeoCue for calibration. Populate relative bin layout of mission extent. Filter bins for noise and run ground by flight line macro for calibration.	GeoCue v. 2013.1.45.1
Test relative accuracy using ground classified points per each flight line. Perform automated line-to-line calibrations for system attitude parameters (pitch, roll, heading), mirror flex (scale). Calibrations are performed on ground-classified points from paired flight lines. Every flight line is used for relative accuracy calibration.	TerraMatch v. 14, TerraScan v.14, GeoCue v. 2013.1.45.1
QC each mission line-to-line calibration by running DZ-orthos for each mission and after each mission is merged together for final project coverage	GeoCue v. 2013.1.45.1
Assess Fundamental vertical accuracy via direct comparisons of LiDAR data points to ground survey data.	TerraScan v.13
Assess vertical accuracy via direct comparisons of Digital Elevation Models to ground survey data.	TopoAnalyst

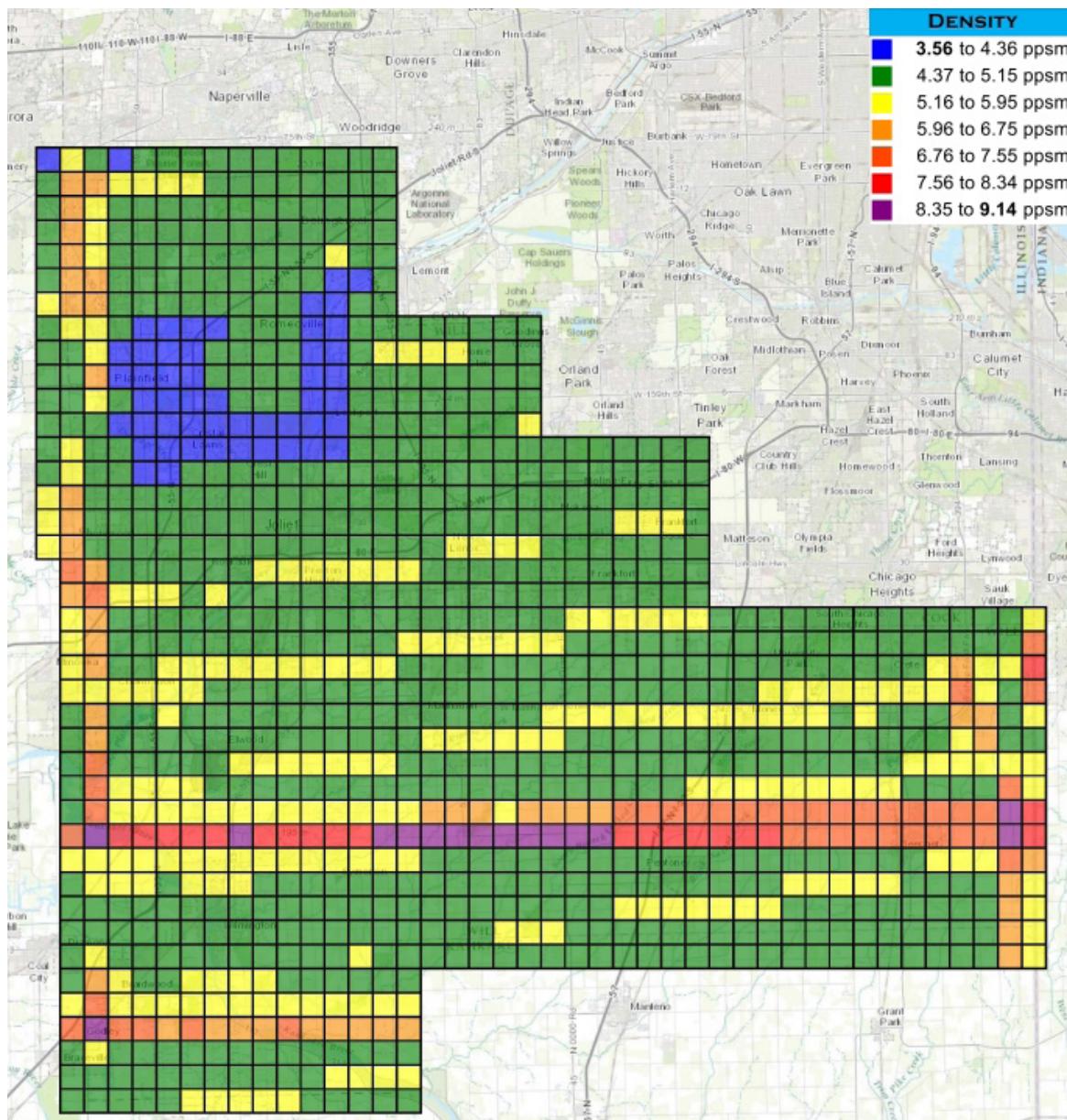


5.2 LiDAR Processing

The LAS files are imported, verified, and parsed into manageable, tiled grids using GeoCue version 2012.1.27.7. GeoCue allows for ease of data management and process tracking. Relative accuracy of flightline to flightline alignment is assessed. Areas containing dense vegetation coverage or inundation from water will show a greater elevation offset than is actually present in the ground data. This is due to these regions having a high number of returns from vegetation or non-ground objects and few returns from the ground causing the elevation offset to be exaggerated.

Each tile within the study area is evaluated to ensure that the desired point density has been met. Image 5.2b illustrates the results of the point density analysis. Quantum Spatial utilizes proprietary software to complete this task. A grid, sized according to the USGS version 13 specifications, based on the nominal post spacing, is used for point analysis. The USGS version 13 specification allows that a grid size up to 2 times the nominal post spacing be used. Point density is analyzed on the basis of this grid space size or cell and the result indicates the point density of the sampled tiles.

Image 5.2b: Point density analysis

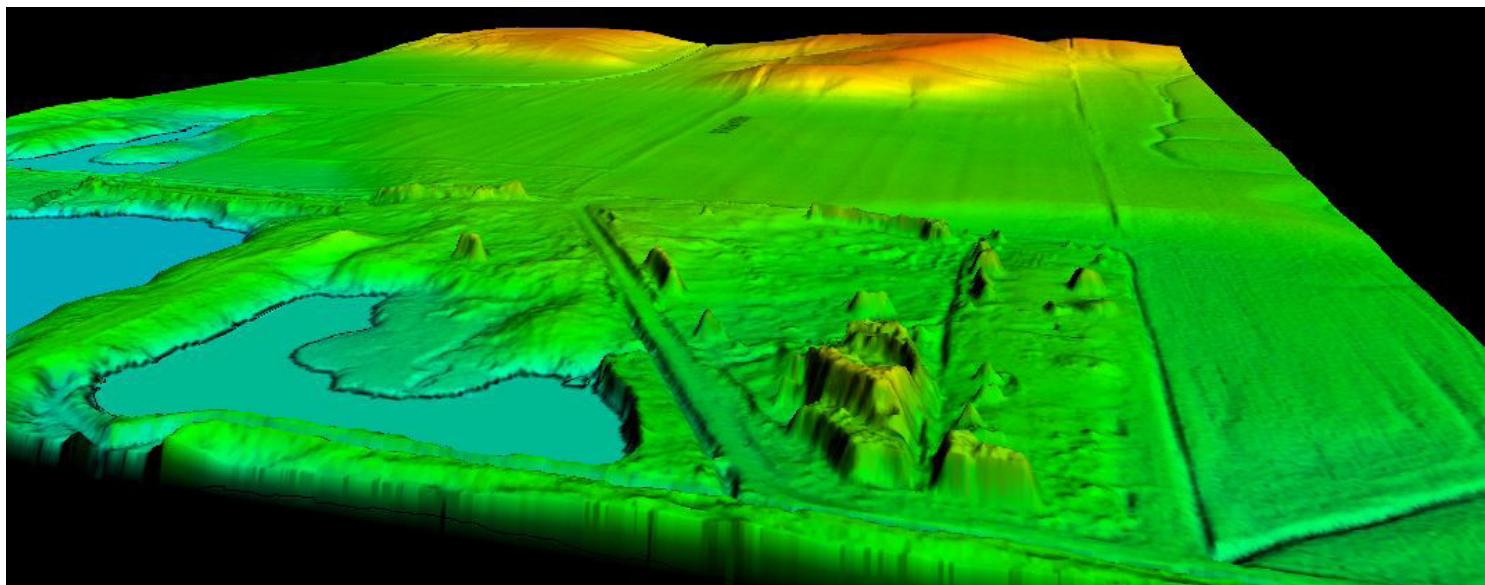




Once both the accuracy between swaths and data density is accepted an automated classification algorithm is performed using TerraSolid's TerraScan, version 013.011. This produces the majority of the bare-earth datasets. Further, the data is processed to classify specific vegetation classes and man-made structures.

The remainder of the data is classified using manual classification techniques. The majority of the manual editing involves changing points initially classified as ground (class 2), to unclassified or non-ground (class 1). Erroneous low points and high points, including clouds, are classified to Noise (class 7).

Image 5.2c: Bare earth ground model representation of LiDAR points.



5.3 Check Point Validation

To ensure position of the assembled data it is verified against surveyed ground control data. TerraScan computes the vertical differences between surveyed ground control points and LiDAR collected points.

Check points are surveyed within the project area to provide calibration checks of the LiDAR point cloud. A report indicating comparative positional statistics is produced when LiDAR has been adjusted to control and can be found in Section 9 of this report.

Twenty (20) ground check points were made across the project area to be used in adjusting the data to position. These twenty points were collected by Quantum Spatial, as part of the ninety seven (97) control points collected for the project as described in Section 4, acquired from May 13th to May 15th, 2014.



5.4 Vertical Accuracy Assessment

Vertical accuracy assessment is conducted by comparing ground survey check point z values to processed LiDAR data z values by horizontal proximity. Differences in z values are calculated to express an RMSEz value.

The Fundamental Vertical Accuracy (FVA) of the LAS data achieved 12.25 cm at a 95% confidence level with an RMSE of 6.25 cm utilizing twenty (20) Open Terrain ground survey check points compared to a Triangulated Integrated Network (TIN) of the LiDAR points.

See attached “Final_Delivery_Report” and Section 10-Accuracy Assessment for details of the ground survey control data.

Table 5.1: FVA Data Compared to TIN

	Ground Cover Category	Number of Checkpoints	Result cm (ft.)
FVA	Open Terrain	20	12.25 cm (0.40 ft.)
RMSEz	Open Terrain	20	6.25 cm (0.21 ft.)

The Supplemental Vertical Accuracy (SVA) and Consolidated Vertical Accuracy (CVA) results are in the following table. Ground survey check points made in various ground cover categories are compared to Digital Elevation Models (DEM) derived from the LiDAR data.

Table 5.2: Accuracy Results

	Ground Cover Category	Number of Checkpoints	Result cm (ft.)
FVA	Open Terrain	20	12.25 cm (0.40 ft.)
CVA	All Categories	97	17.55 cm (0.53 ft.)
SVA	Urban	18	14.29 cm (0.47 ft.)
SVA	Tall Grass	20	15.76 cm (0.52 ft.)
SVA	Brush	20	19.10 cm (0.63 ft.)
SVA	Forest	19	14.29 cm (0.47 ft.)



5.5 LiDAR Data Delivery

Point cloud data supplied is in the following format:

- LAS, version 1.2
- GPS times adjusted to Adjusted Standard GPS time

Classified point cloud data is also being supplied using the following criteria.

- LAS, version 1.2 in 5,000 foot grid
- Classification scheme:

1 - Unclassified
2 - Ground
3 - Low Vegetation
4 - Medium Vegetation
5 - High Vegetation
6 - Building
7 - Low Point (noise)
8 - Model Key-point
9 - Water
10 - Ignored Ground

LiDAR-derived products:

- 2.5 ft resolution hydro-flattened DEM in *.img format
- TIN surface provided in *.TIN format, by tile
- DAT, output with TIN from Geopack, in *.dat format

Shapefiles:

- Hydro breaklines (Microstation *.dgn and ESRI geodatabase format)
- *Las delivery tile index (Microstation *.dgn and ESRI geodatabase format)

USGS-compliant metadata for delivered products



6. Conclusion

Sound procedures and use of new technologies ensure this project data and derivative products will serve as reliable information and models for the University of Illinois Urbana - Champaign. The models produced are accurate and representative of surface conditions at the time of data acquisition.



7. Flight Logs

Image 7.1 a: Mission Ferry

OPERATORS FLIGHT LOG									
MISSION	YYMMDD	TIME(GPS)	DATE:	N.	BEGD	END	LEICA AL5-70	AIRCRAFT: N812TB	SENSOR: 1/b1
PILOT-TESTE	S.		OPERATOR:						
PROJECT NUMBER	LINE	GND SPEED	FREQ	SCAN ANGLE	PRF	FIXED GAIN	Flying HT.(m)	TIME	MW70 DRIVE
AND NAME	No	Lbs	Hz	kHz				START STOP	
1140310									
KANKAKEE									
IL									
STATUS	TOTAL LINES	FLOWN	LEFT	SITE	AIRCRAFT FERRY	STATIC	START STOP	NOTES:	
○	○	○	○	○	WW				
○	○	○	○	○					
○	○	○	○	○					

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Image 7.1b: Mission 20140405_145031 (continued)

OPERATORS FLIGHT LOG									
MISSION: 20140405_145031		DATE: 4/5/14		AIRCRAFT: N737W		LEICA ALS-70			
PILOT: DESSIE J.		OPERATOR: BRAD N.							
PROJECT NUMBER AND NAME	LINE NO.	GND SPEED KTS	FREQ Hz	SCAN ANGLE	PRF kHz	FIXED GAIN	Flying HT (m)	TIME START	MM/DD STOP DRIVE
140310 WELL COUNTY FL	150	41	40	274				046	-CONTINUE -
140405_172756	477.07	270	153				7180	17:18	17:35
140405_173810	478.018	90	150				7200	17:38	17:45
140405_174759	479.019	270	157				7200	17:49	17:55
140405_175818	480.020	90	153				7190	17:58	18:05
140405_180832	481.021	270	155				7200	18:08	18:15
140405_181829	482.022	90	156				7190	18:18	18:25
140405_182847	483.023	270	155				7200	18:29	18:35
140405_183906	484.024	90	152				7200	18:39	18:46
140405_184916	485.025	270	155				7215	18:49	18:56
140405_185929	486.026	90	157				7200	18:59	19:06
140405_191139	487.027	270	150				7220	19:11	19:21
140405_192407	488.028	90	155				7215	19:24	19:33
140405_193622	489.029	270	155				7225	19:36	19:45
140405_194818	X~FLT O	155					7250	19:48	19:53
								20:10	SITE → C56
									HOBBS 51928
AIRCRAFT FERRY STATIC START STOP NOTES:									
STATUS	TOTAL LINES	FLOWN LEFT	SITE	FERRY	STATIC	START	STOP		
O		29	4.7	1.4					
O									
O									

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Image 7.1c: Mission 20140405_210931

OPERATORS FLIGHT LOG									
MISSION:	DATE: 4/5/14			AIRCRAFT: N737M			LEICA ALS-70		
PILOT:	S	OPERATOR:	B RAD N	GND SPEED	FREQ	PRF	Flying	TIME	MOT70
PROJECT NUMBER AND NAME	LINE No.	Lbl	Hdg	kts	Hz	ANGLE	HL (m)	START	STOP
140310									036
Initial Constant				150	41	40	274	6:18:2	C56 → SITE
140405_213015	490	036	270	156				7:26:0	4:39
140405_214137	491	031	90	154				7:25:0	21:51
140405_215155	492	032	270	145				7:07:0	21:55
140405_226732	493	033	90	157				7:06:0	22:07
140405_227940	494	034	270	150				7:08:0	22:19
140405_228209	495	035	90	153				7:08:0	22:32
140405_224119	496	036	270	154				7:08:5	22:44
140405_225151	497	037	90	155				7:08:0	22:57
140405_230858	498	038	270	154				7:08:5	23:09
140405_232123	499	039	90	160				7:07:0	23:21
140405_233321	500	040	270	154				7:08:0	23:33
140405_234449	X	FLT O		158				7:09:0	23:45
									24:05
									SITE → C56
									HOBS 57955
STATUS	TOTAL LINES	FLOWN	LEFT	AIRCRAFT	SITE	FERRY	STATIC	START	STOP
○	11		2.3	0.4					W.W.
○									
○									

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Image 7.1d: Mission 20140406_123119

OPERATORS FLIGHT LOG							
MISSION: 20140406 - 123119	DATE: 4/6/14			LEICA ALS: 70			
PILOT: JESSE J	OPERATOR: DAD N		AIRCRAFT: N73TM				
PROJECT NUMBER AND NAME 140310 WILL COOK II	LINE	GRD SPEED (KTS)	FREQ Hz	SCAN ANGLE	PRF kHz	FIXED GAIN	TIME MM/DD START STOP
	No.	Lbl	Hdg				03 03 12:40
	150	41	40	274			C56 → SITE
140406-125559	501	041	270	150		6860	12:56 13:05
140406-130756	502	042	90	156		6850	13:08 13:17
140406-131402	503	043	270	155		6860	13:24 13:37
140406-134041	504	044	90	156		6870	13:40 13:54
140406-135704	505	045	270	150		6880	13:57 14:10
140406-141332	506	046	90	153		6860	14:13 14:27
140406-143008	507	047	270	150		6880	14:30 14:43
140406-144624	X-	FLT	180	165		6860	14:46 14:48
140406-145125	508	048	90	155		6860	14:51 15:05
							CROSS FLIGHT
							SITE → C56 Hoss 5198.0
							15:30 16:25 C56 → SBM Hoss 5198.9
STATUS	TOTAL LINES	FLOWN	LEFT	AIRCRAFT SITE	FERRY	STATIC START	STOP NOTES:
○	8		2.2	1.2			WKA
○							
○							



Q

Image 7.1e: Mission 20140410_004557

OPERATORS FLIGHT LOG

YYYYMMDD_ID - 004557			DATE: 04/10/14			LEICA ALS-70			7		
CALLSIGN: Reed / Tessett			OPERATOR: Jonathan Swan / Brad Nelson			AIRCRAFT: A/G12TB			SENSOR: 7161		
PROJECT NUMBER	LINE	GND SPEED	FREQ	SCAN	PRF	FIXED	Flying	TIME	MM70	STOP	REMARKS
AND NAME	No.	Lbl	Hdg	Hz	ANGLE	KHz	Ht. (m)	START	STOP	DIS	C56 → Site
140310											Hills 2579.9
Link Will IL											
Left Lines		150	41	40	274		6952	0057			
		509	049	270	150		6940	0119	0133		
		510	050	090	145		6910	0136	0150		
		511	051	070	148		6968	0154	0208		
		512	052	090	159		6932	0211	0224		
		X	0	139			6981	0228	0229		X Flight
							0242				Site → C56
Hills 2581.4											
APR. 10.	2014	11	9:50PM								
STATUS	TOTAL LINES	FLOWN	LEFT	AIRCRAFT	FERRY	STATIC	START	STOP		NOTES:	
							0057			flwP 256 @ 2 ns / 20 kHz max	



Image 7.1g: Mission 20140411_173945

OPERATORS FLIGHT LOG									
MISSION: 20140411 - 173945		DATE: 4/11/14		AIRCRAFT: N812T3		LEICA ALS-70			
PILOT: REED		OPERATOR: BRAID		PRF GAIN		TIME		REMARKS	
PROJECT NUMBER AND NAME		LINE	GND SPEED (KTS)	FREQ Hz	SCAN ANGLE	FLYING HT (m)	START STOP	MATO DRIVE	SENSOR: 7161
No.	Lbl	Hdg							
1140310	KAN WILL Co.	055	150	40	274	6952	17:50	015	HOBs 2590.5
IL	515	055 270	160			6925	17:59		
	516	056 90	157			6925	18:16	02:29	
	517	057 270	156			6950	18:33	08:46	
	518	058 90	150			6950	18:50	19:03	
	519	059 270	157			6975	19:07	19:20	
	520	060 90	155			6950	19:24	19:37	
	521	061 270	145			6950	19:41	19:54	
	522	062 90	150			6950	19:58	20:11	
	523	063 270	153			6950	20:15	20:29	
	X - PLT	180	165			6930	20:32	20:34	CROSSFLIGHT
							20:50		SITE → C56
									HOBs 2593.4
STATUS	TOTAL LINES	FLOWN	LEFT	AIRCRAFT SITE	FERRY	STATIC	START	STOP	NOTES:
<input checked="" type="checkbox"/>	1140310	9		26	0.3		17:45	20:50	
<input type="radio"/>									
<input type="radio"/>									

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Image 7.1i: Mission 20140411_225147

OPERATORS FLIGHT LOG													
YYYYMMDD_TIME(GPS)		DATE: 2014-04-11 13		LEICA ALS-70		AIRCRAFT: N812TB			TIME				
PROJECT NUMBER AND NAME		LINE No.		GND SPEED (KTS)	FREQ Hz	SCAN ANGLE	PRF kHz	FIXED GAIN	Flying Ht. (m)	START	STOP	MM70 DRIVE	
PILOT: Jesse J		OPERATOR: Jonathan S										REMARKS	
1146310	K96 Willco II	524	64	270	148	150	41	40	274	12:3	6932	2306	016 C56 → Site Hobbs 25943
		525	65	90	155					6926	2313	2327	Reflight
		526	66	270	144					6930	2330	2344	Reflight
		527	67	90	153					6962	2347	0001	
		528	68	270	154					6860	0003	0017	
		529	69	90	153					6902	0020	0024	
		530	70	270	148					6944	0037	0051	
		531	71	90	157					6899	0053	0107	
		532	72	270	149					6986	0111	0124	
		533	73	90	152					6923	0127	0141	
		534	74	270	148					6917	0144	0158	
		535	75	90	157					6914	0200	0214	
		536	76	270	158					6903	0218	0231	
		537	77	90	155					6931	0235	0248	
	X Flight				144					6912	0251	0305	
										6937	0308	0311	UL 001
										0322			Site → CS6 Hobbs 2598.5
STATUS	TOTAL LINES	FLOWN	LEFT	SITE	AIRCRAFT FERRY	STATIC	START	STOP					NOTES: PWF = 256 @ 2ns / 10Hz
○		14	4/0	0/2			2259	2304					
○							0323	0328					
○													

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Image 7.1j: Mission 20140418_220824

OPERATORS FLIGHT LOG									
MISSION: 20140418- 220824				DATE: 4/18/14				LEICA ALS-70	
PILOT: JESSE J.		OPERATOR: READ N.				AIRCRAFT: 4212TB	SENSOR: 761/		
PROJECT NUMBER AND NAME	No.	LINE	GRD SPEED KTS	FREQ Hz	SCAN ANGLE	PRF kHz	FIXED GAIN	Flying Ht (m)	TIME
MM TO DRIVE REMARKS	START	STOP	STOP	REMARKS	REMARKS	REMARKS	REMARKS	REMARKS	REMARKS
1140310 KANKAKEE QY JL.	542	082	270	152	41	40	274	6991	20:00 21:10
	543	083	90	150				7000	22:50 23:04
	544	084	270	153				7000	23:07 23:20
	545	085	90	150				6980	23:24 23:37
	546	086	270	154				6985	23:41 23:54
	547	087	90	152				7000	23:58 00:11
	548	088	270	152				7000	00:15 00:28
	549	089	90	155				7000	00:31 00:44
	550	090	270	154				6990	00:48 01:02
	551	091	90	150				6960	01:04 01:17
	552	092	270	153				7000	01:21 01:34
	553	093	90	154				7000	01:37 01:50
	554	094	270	155				7000	01:53 02:07
	555	095	90	153				7000	02:10 02:23
	X	PT	O	154				7000	02:26 02:29
									CROSSFLIGHT
									SITE → IKK
STATUS	TOTAL LINES	FLOWN	LEFT	AIRCRAFT SITE	FERRY	STATIC	START	STOP	NOTES:
○	○	14	4,0	1,3			22:12	24:13	HOBBS 2624.0
○	○								W LIGHT HAZE
○	○								W WINDS 15 knots
									FlwF 256 @ 2 knot,



Image 7.1k: Mission 20140419_132934

OPERATORS FLIGHT LOG

MISSION:	20140419-132934	DATE:	4/19/14	LEICA ALS-TB						
PILOT: JESSE J.	OPERATOR: RROAD	N.		AIRCRAFT: N812TB	SENSOR: 7161					
PROJECT NUMBER AND NAME	LINE No.	GRD SPEED (KTS)	FREQ Hz	SCAN ANGLE	PRF kHz	FIXED GAIN	Flying Ht (m)	TIME	MM/DD	REMARKS
1140310	KANKAKEE CITY	150	40	274				024 13:40	018	TICK → SITE
IL	556 96 270	153						0950	13-56	HOBBS 2626.3
	557 97 90	154						0950	14-12	
	558 98 270	150						0950	14-29	14:42
	559 99 90	155						0950	14-45	14:58
	560 100 270	150						0950	15-01	15:14
	561 101 90	154						0940	15-17	15:30
	562 102 270	150						0950	15-34	15:47
	563 103 90	156						0950	15-50	16:03
	564 104 270	150						0950	16-07	16:20
	565 105 90	155						0950	16-23	16:36
	566 106 270	150						0950	16-39	16:52
	567 107 90	153						0950	16-56	17:09
	568 108 270	157						0950	17-12	17:26
	569 109 90	157						1000	17-29	17:42
	570 110 270	153						1000	17-45	17:58
	571 111 90	155						1000	18-01	18:15
	X FLT 0	157						1000	18-17	CROSSFLIGHT
	STATUS TOTAL LINES	16	FLOWN LEFT	SITE FERRY	STATIC	AIRCRAFT	START STOP	18-30	SITE → IRK	NOTES:
Q	1146310							13-33	18-34	HOBBS 2631.1
O										FlwF 25f @ 2 Navo
O										

Quantum Spatial N 6216 Resource Drive Sheboygan Falls, WI 53085 PHONE: 920-467-2655 FAX: 888-253-6695 E-Mail: amphoto@quantumspatial.co





8 LiDAR GPS Processing Plots

Image 8.0a: PDOP Plot for mission 20140405_145031

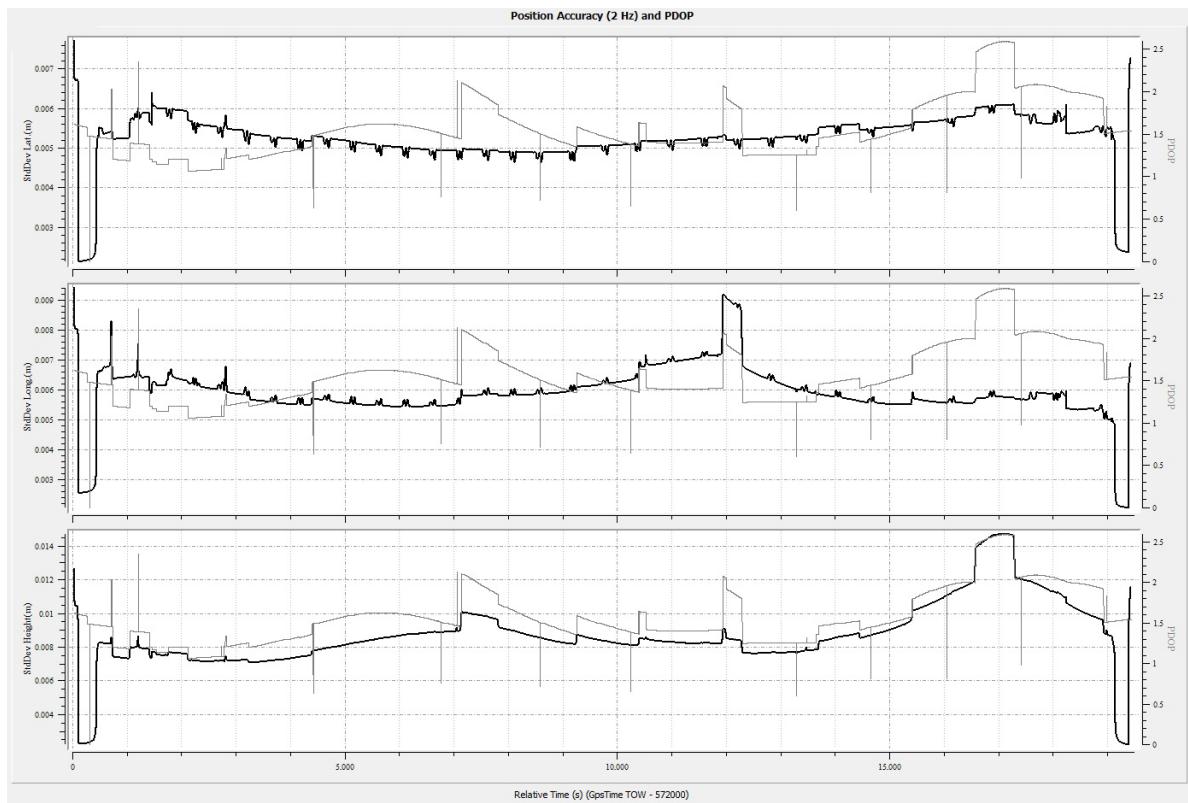


Image 8.0b: Separation Plot for mission 20140405_145031

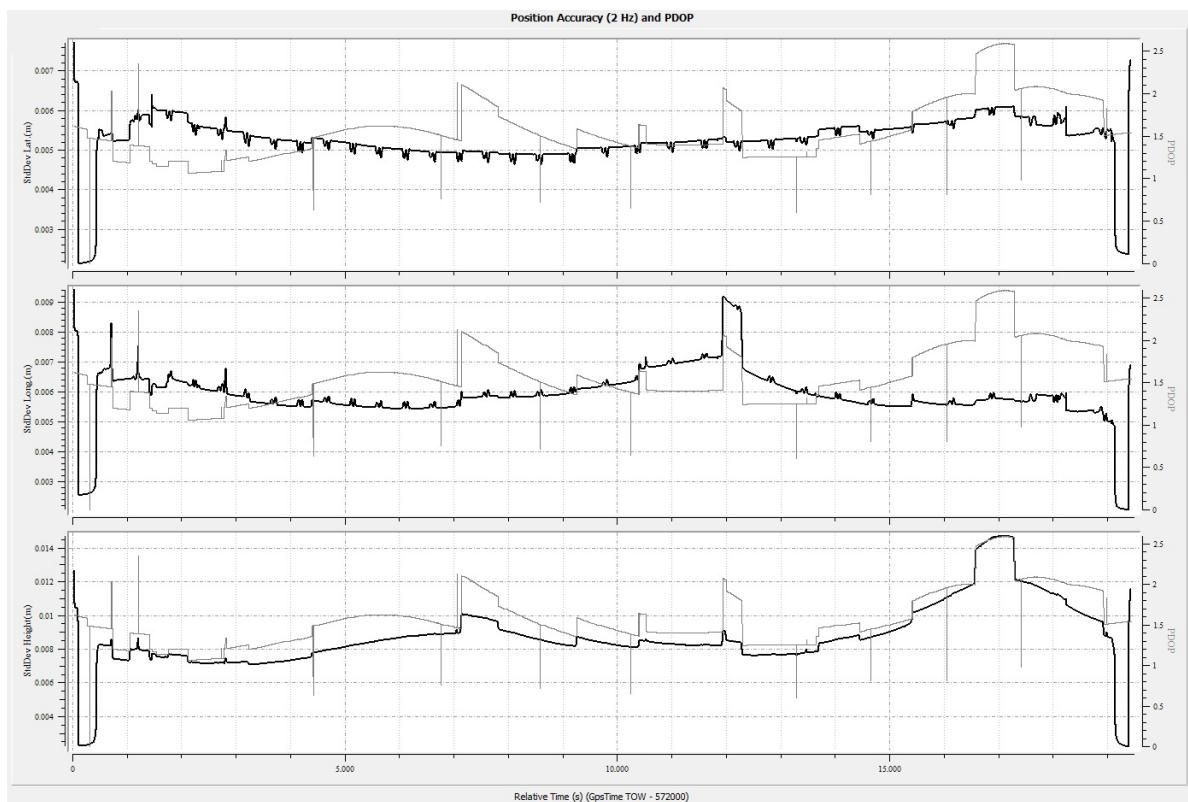




Image 8.0c: PDOP Plot for mission 20140405_210931

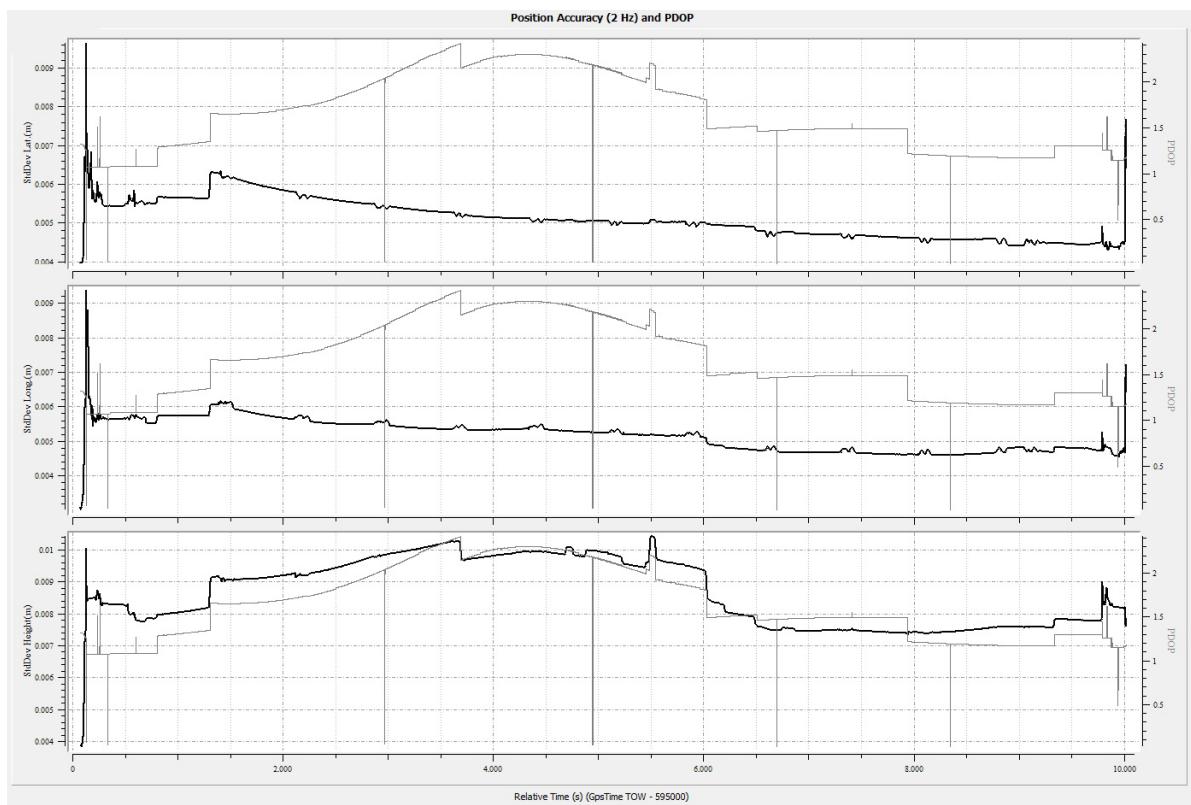
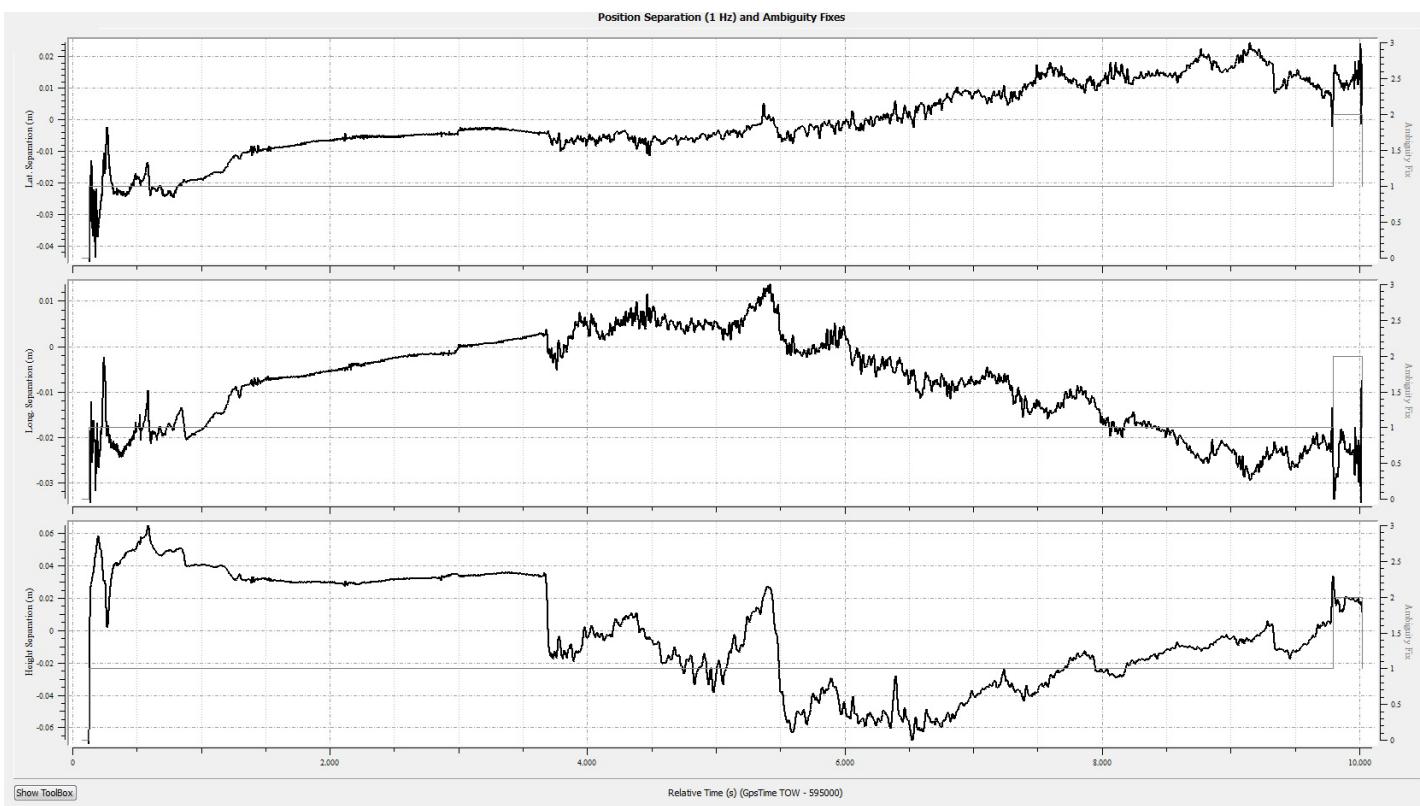


Image 8.0d: Separation Plot for mission 20140405_210931



Show ToolBox

Relative Time (s)



Image 8.0e: PDOP Plot for mission 20140406_123119

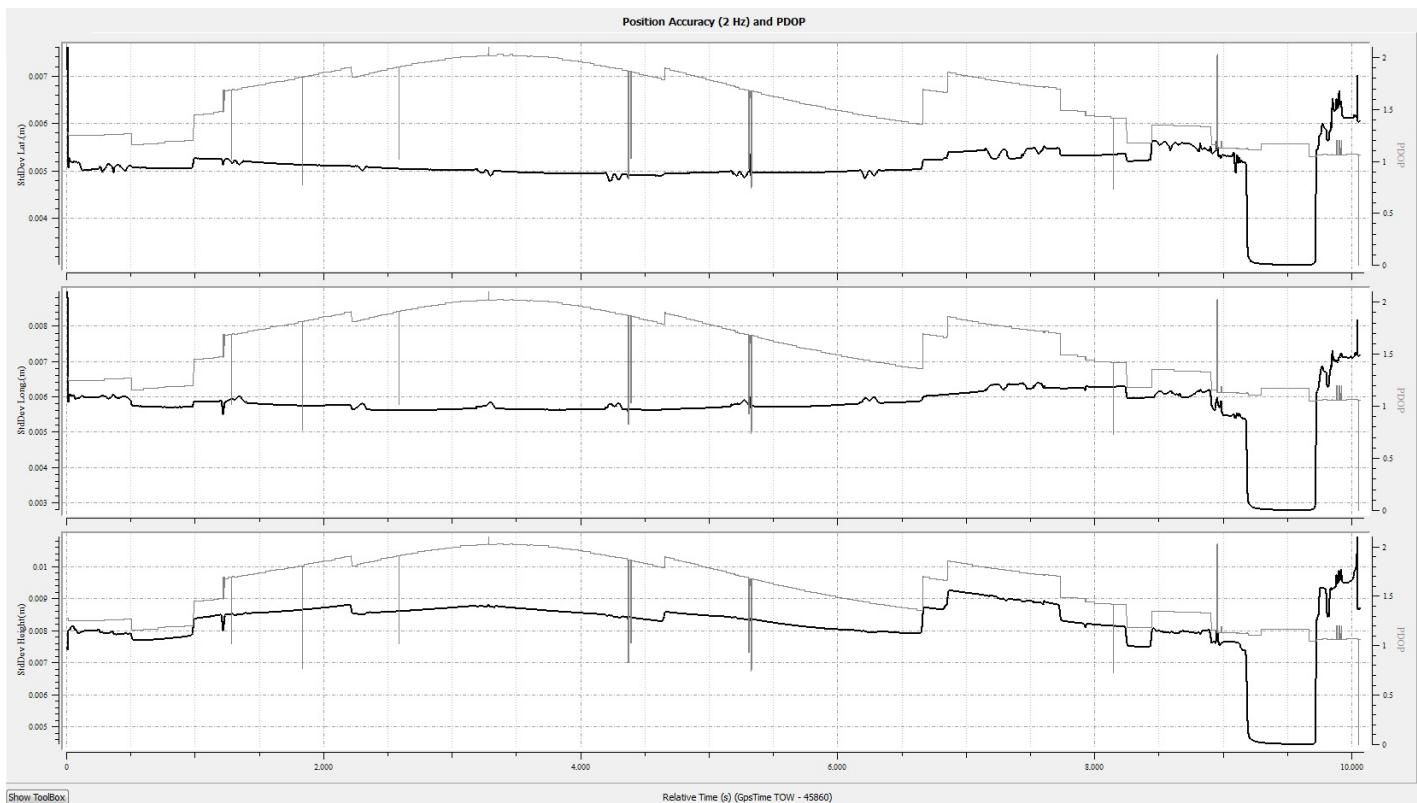


Image 8.0f: Separation Plot for mission 20140406_123119

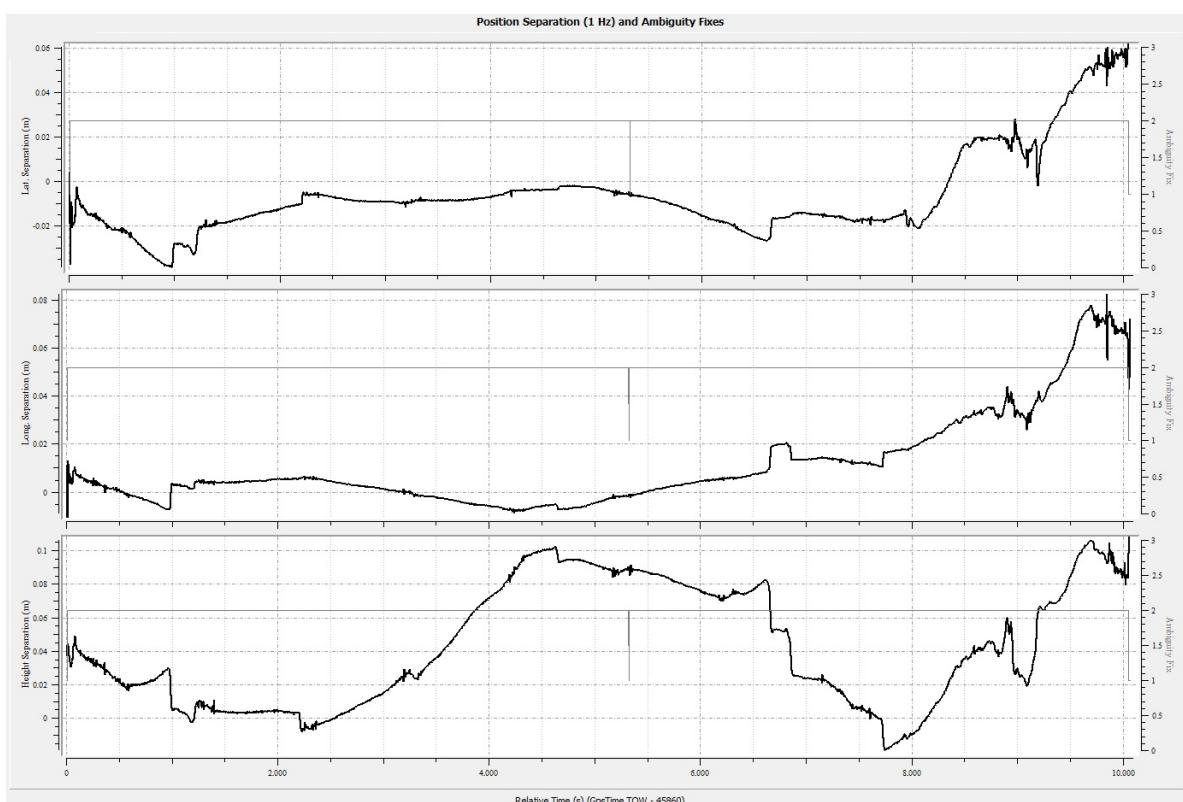




Image 8.0g: PDOP Plot for mission 20140410_004557

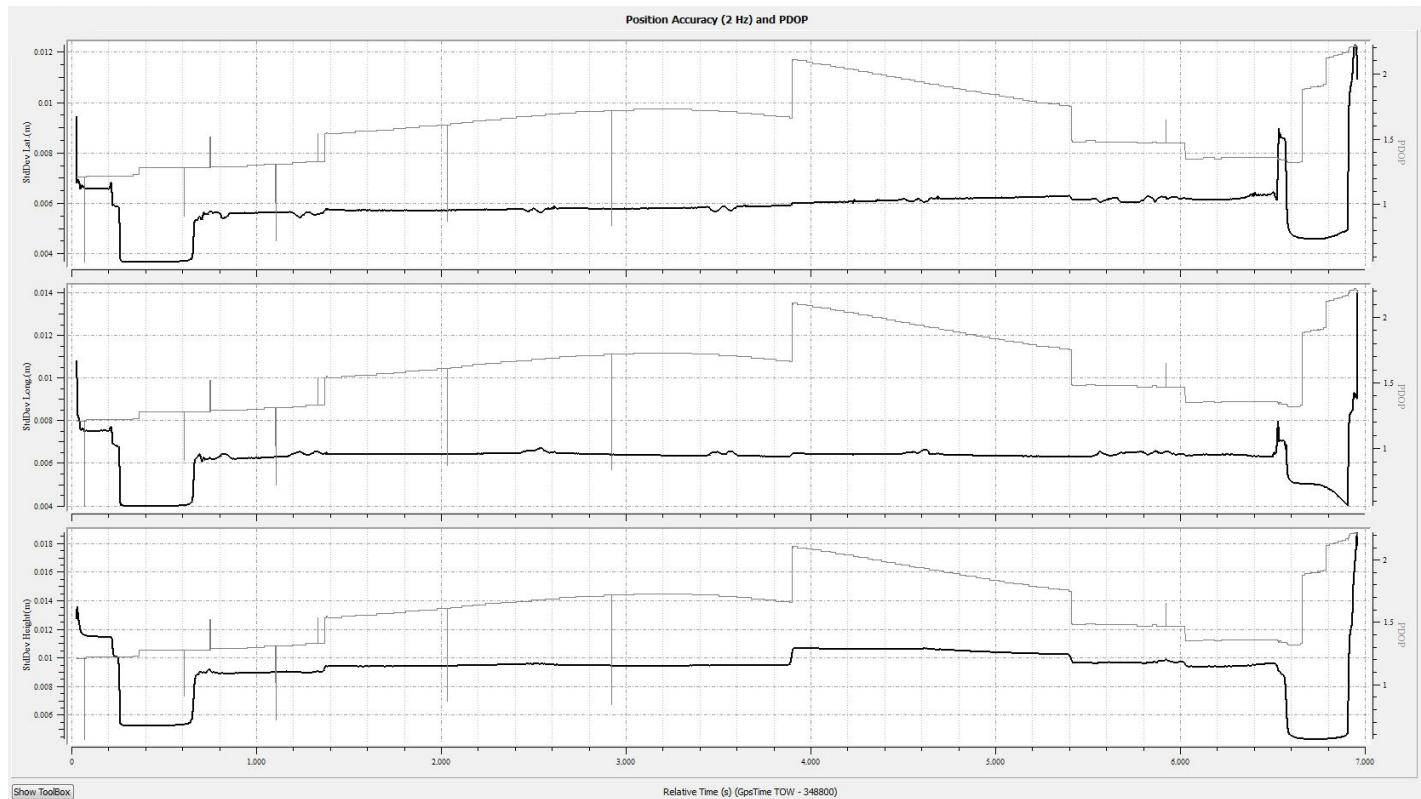


Image 8.0h: Separation Plot for mission 20140410_004557

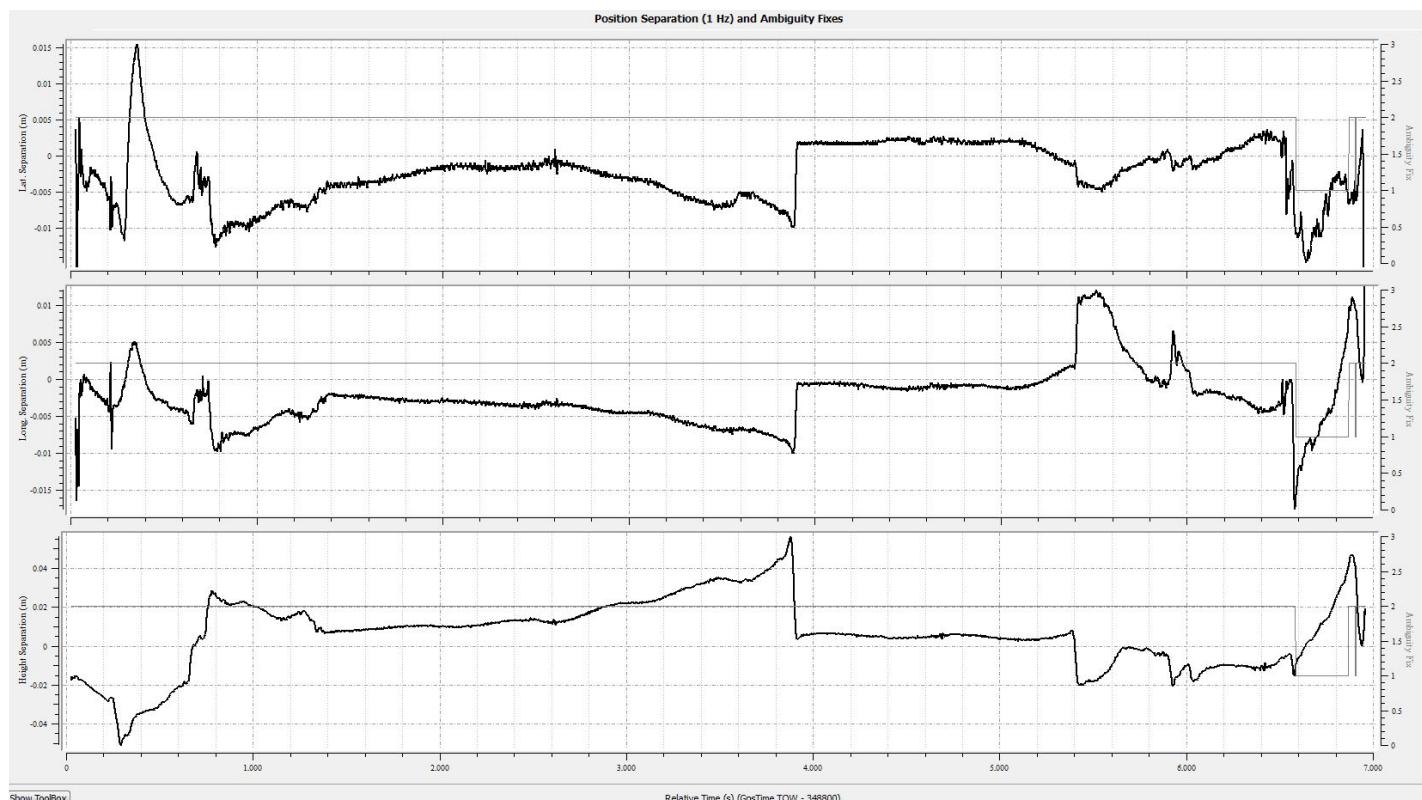




Image 8.0i: PDOP Plot for mission 20140410_140935

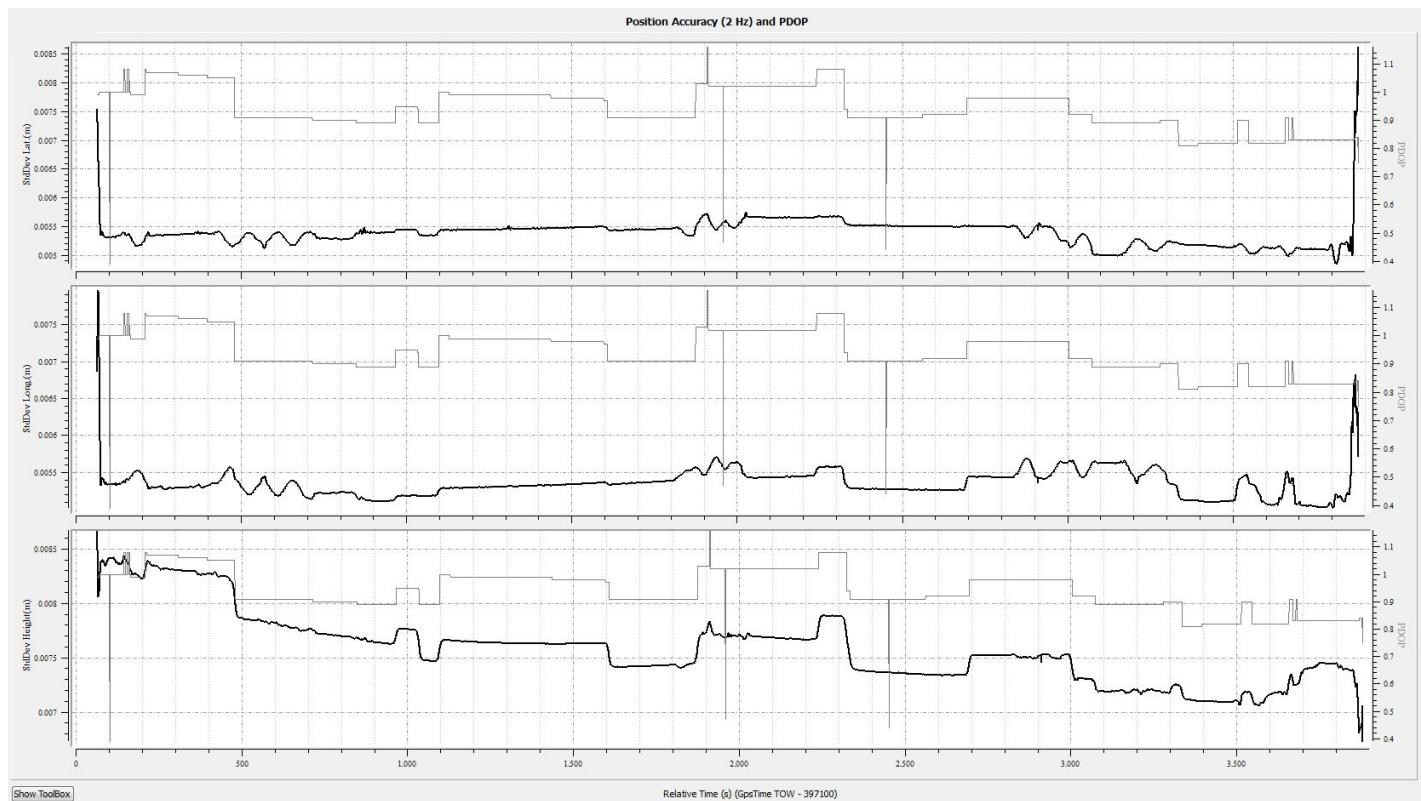


Image 8.0j: Separation Plot for mission 20140410_140935

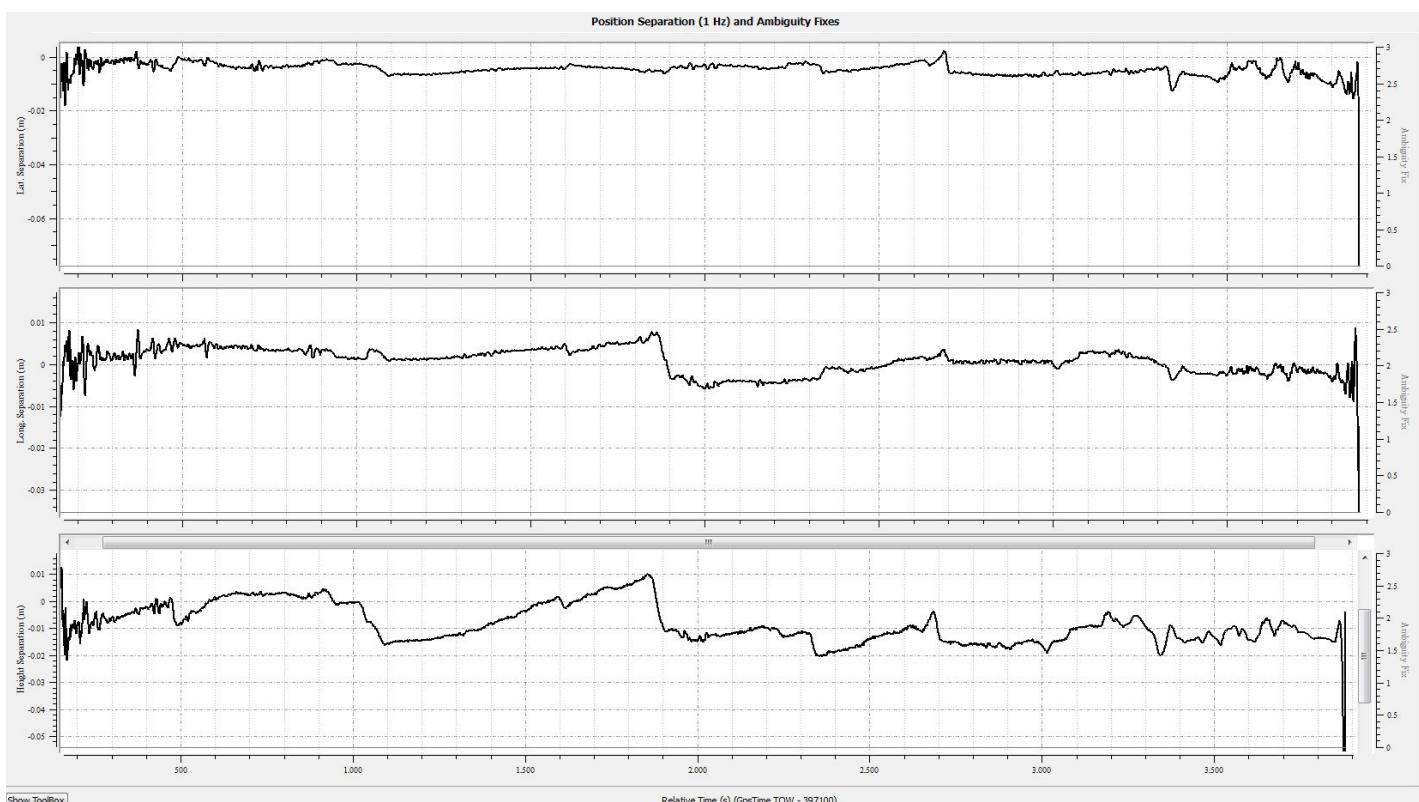




Image 8.0k: PDOP Plot for mission 20140411_173945

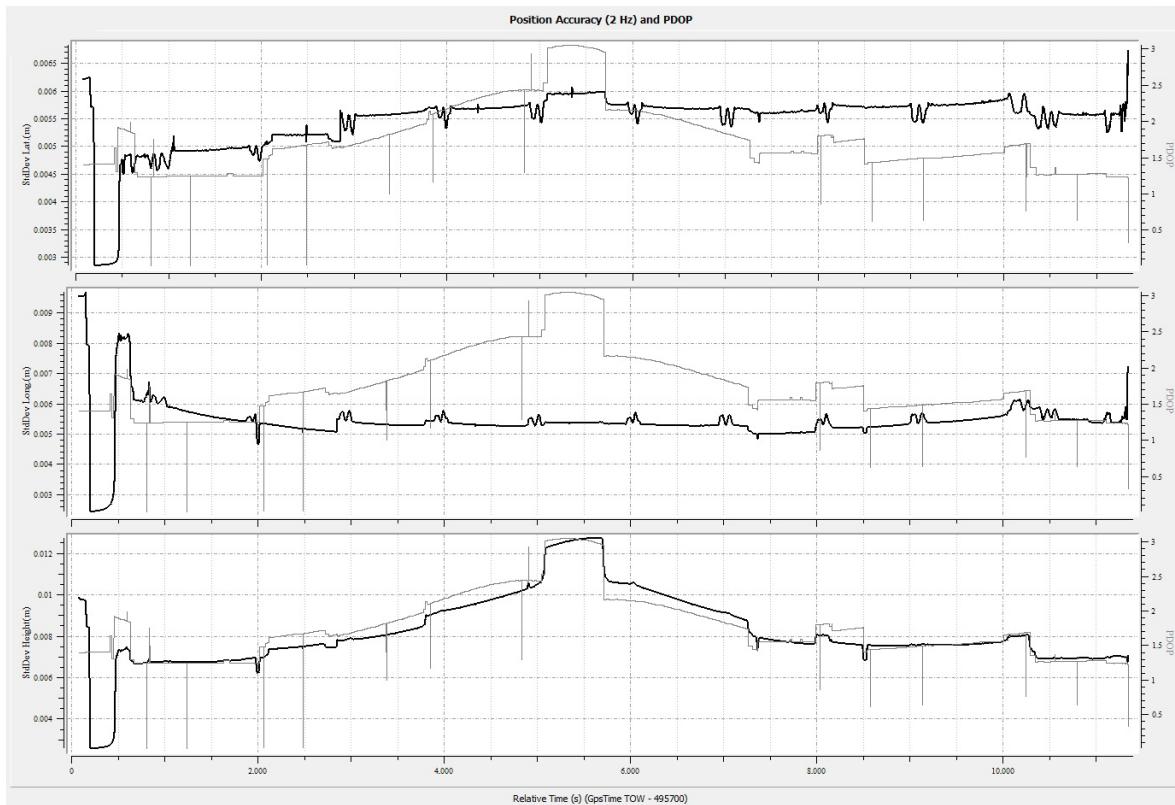


Image 8.0l: Separation Plot for mission 20140411_173945

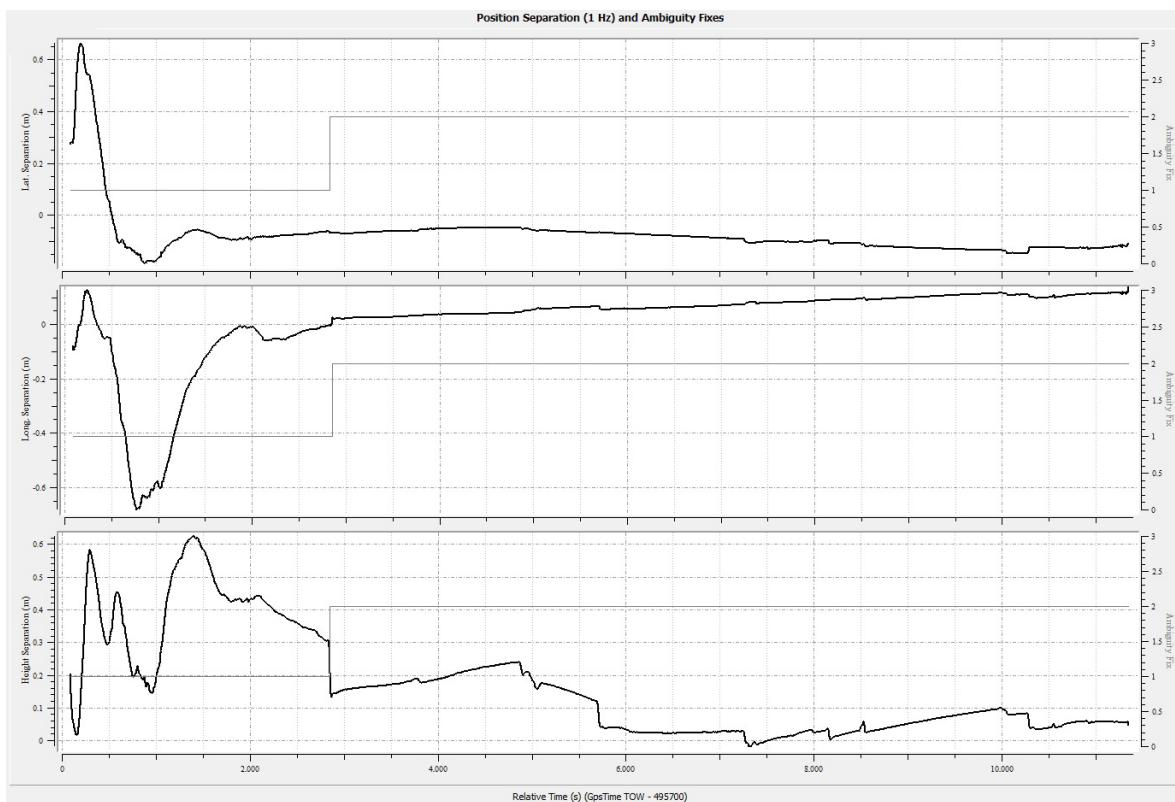




Image 8.0m: PDOP Plot for mission 20140411_213448

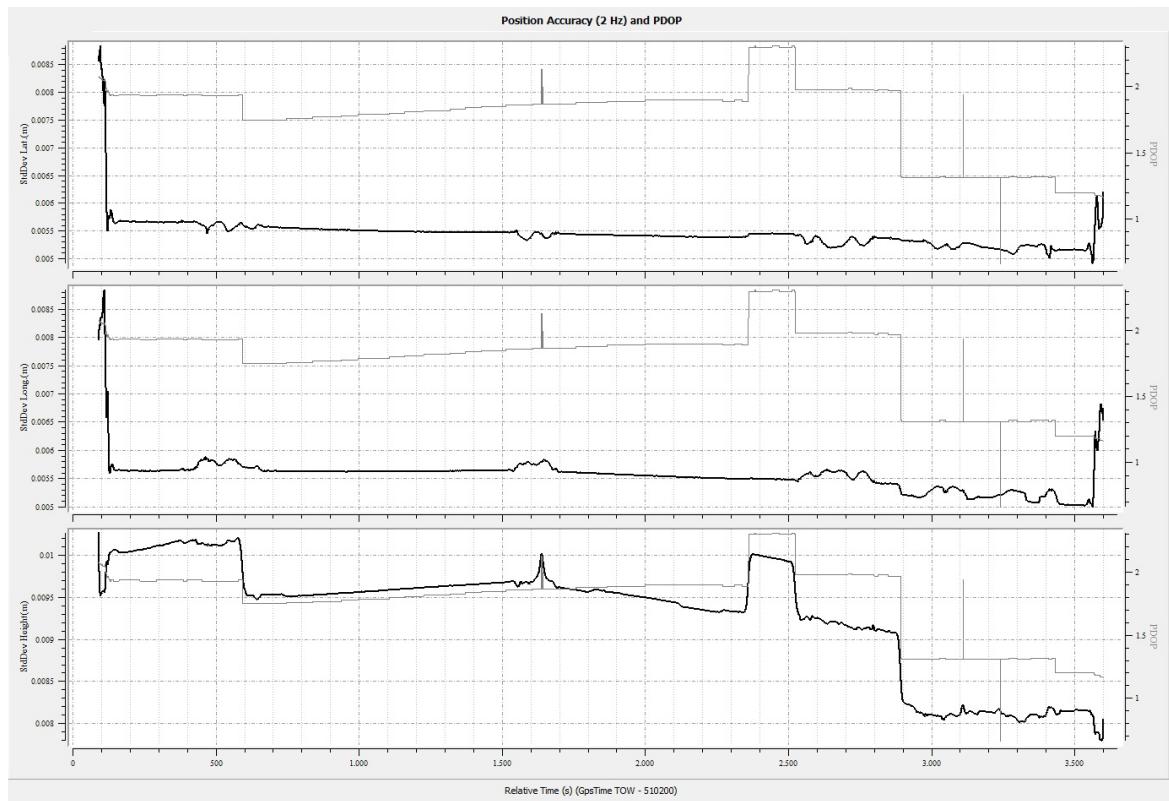


Image 8.0n: Separation Plot for mission 20140411_213448

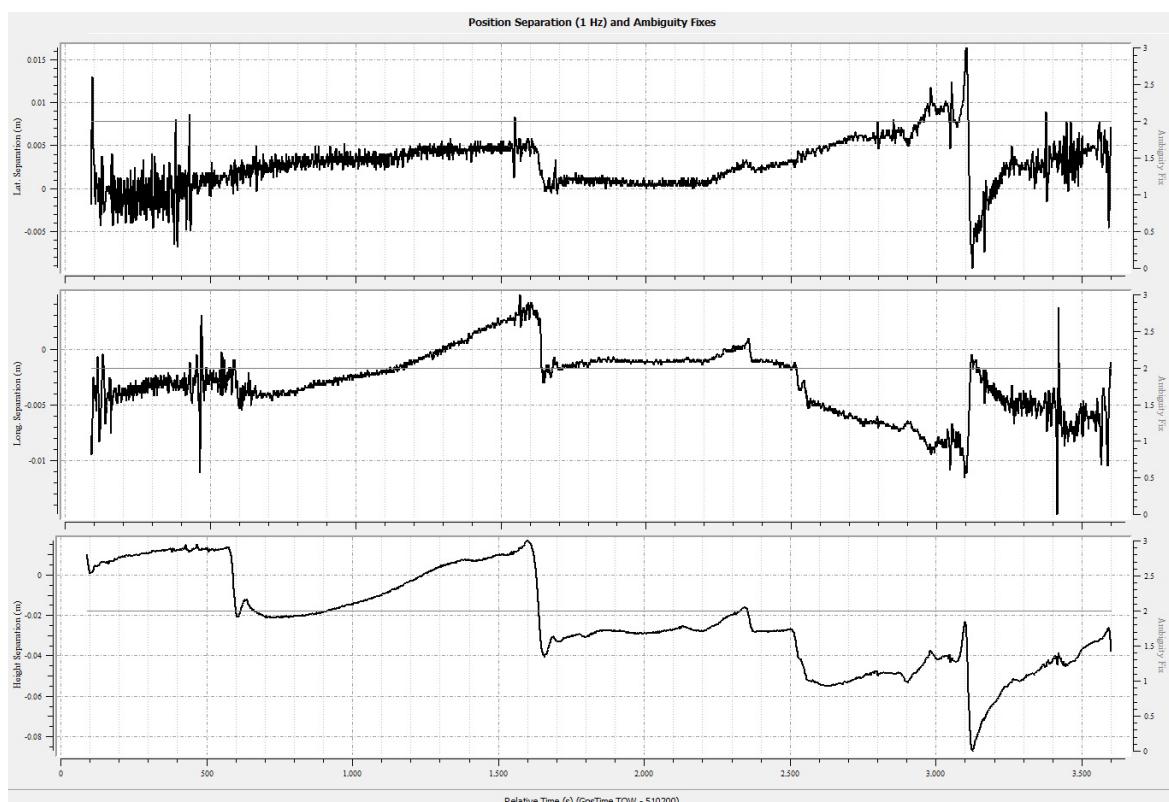




Image 8.0o: PDOP Plot for mission 20140418_220824

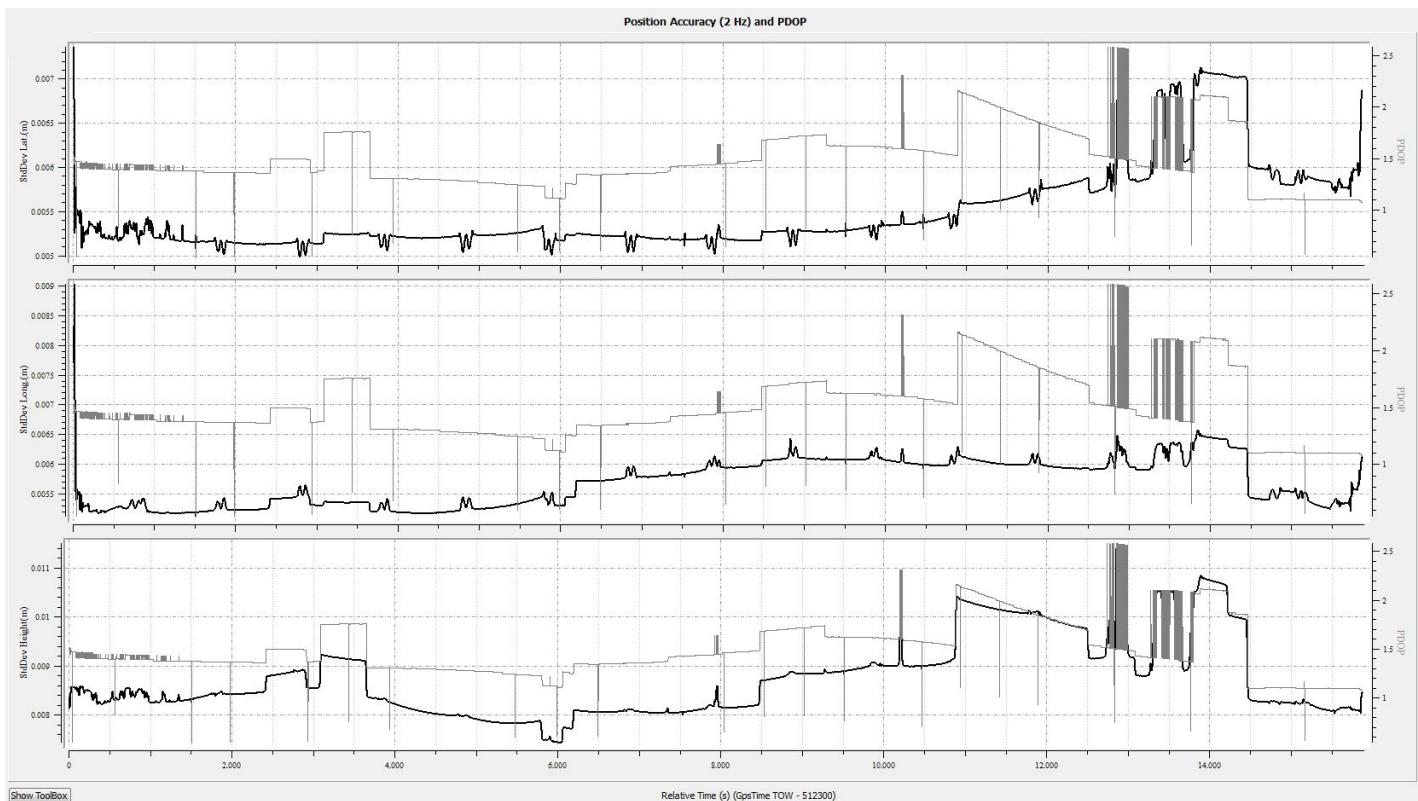


Image 8.0p: Separation Plot for mission 20140418_220824

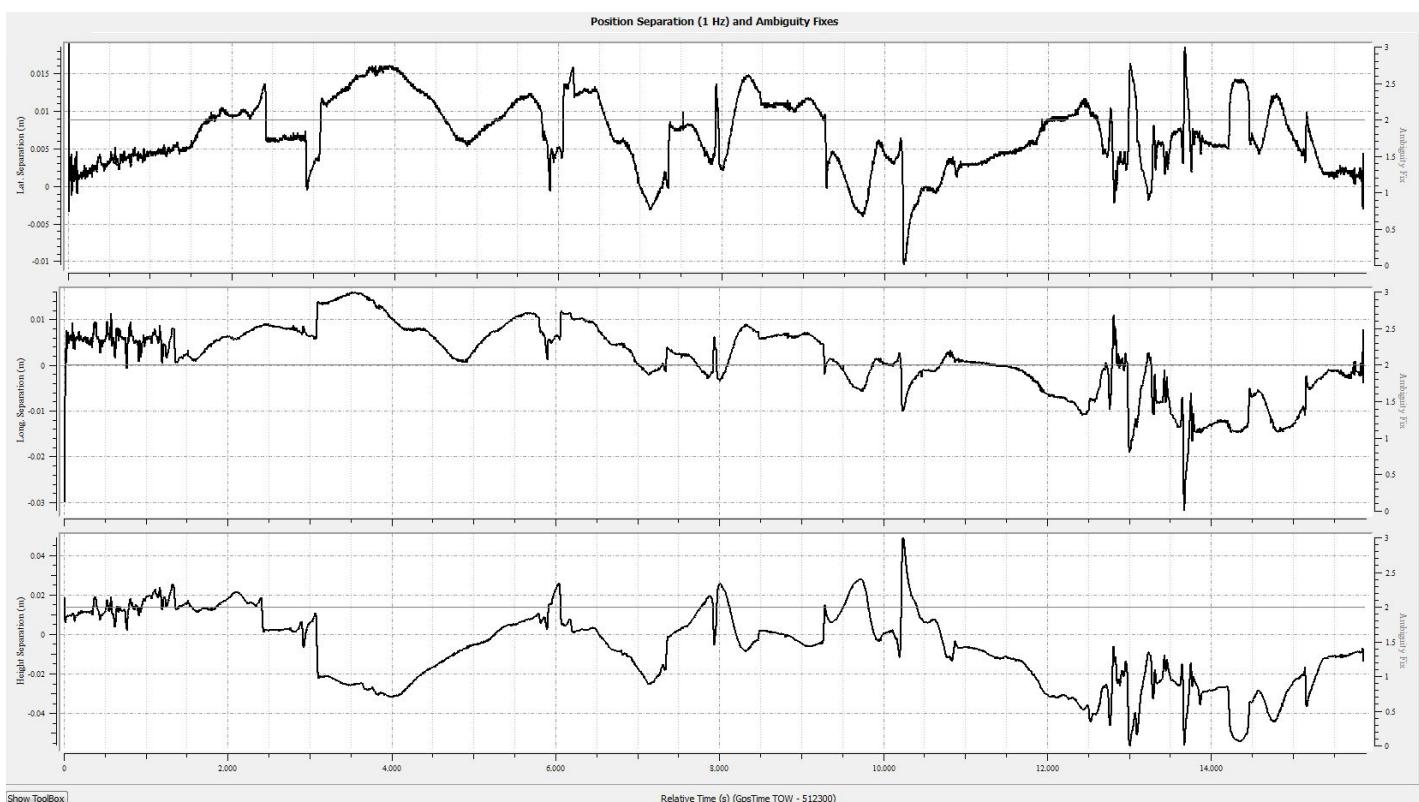




Image 8.0q: PDOP Plot for mission 20140419_132934

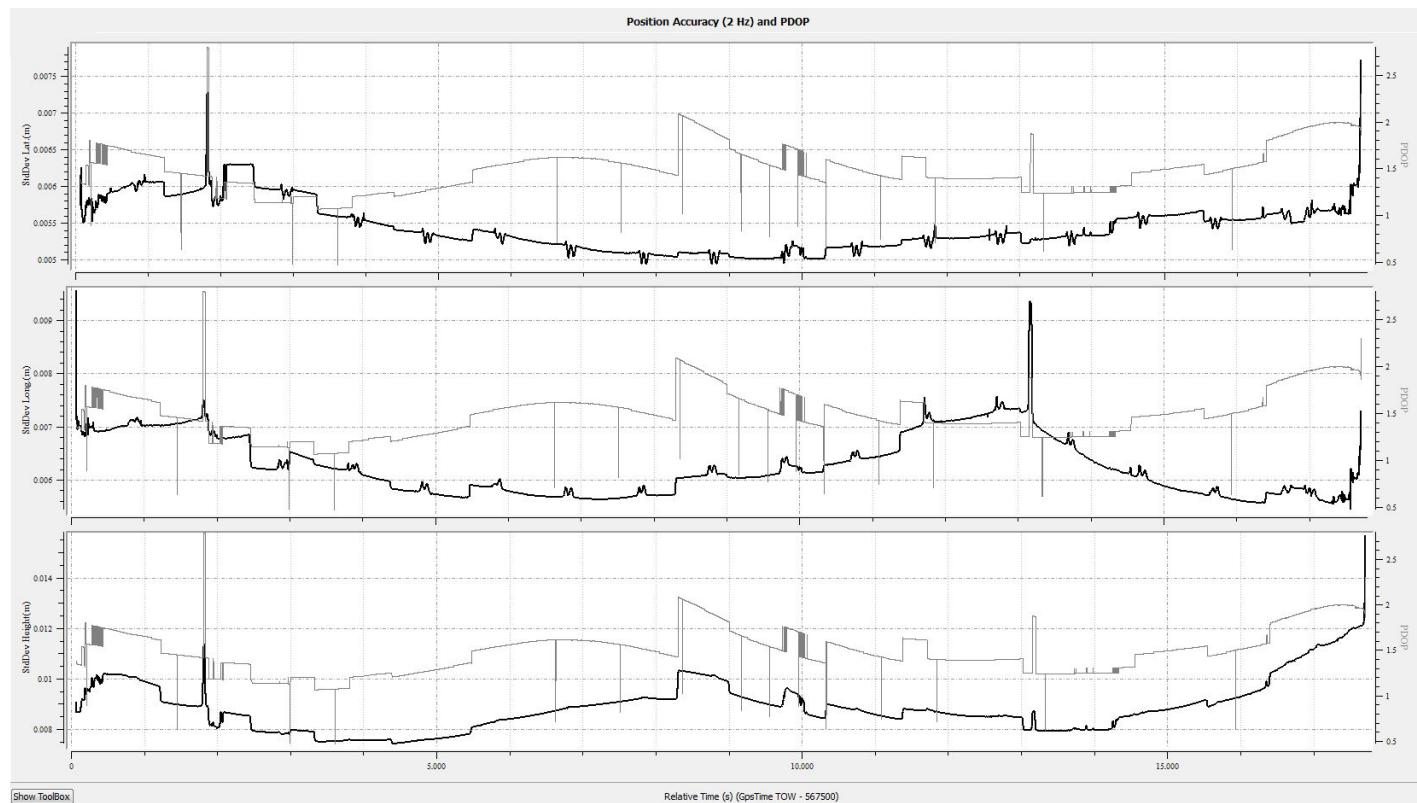
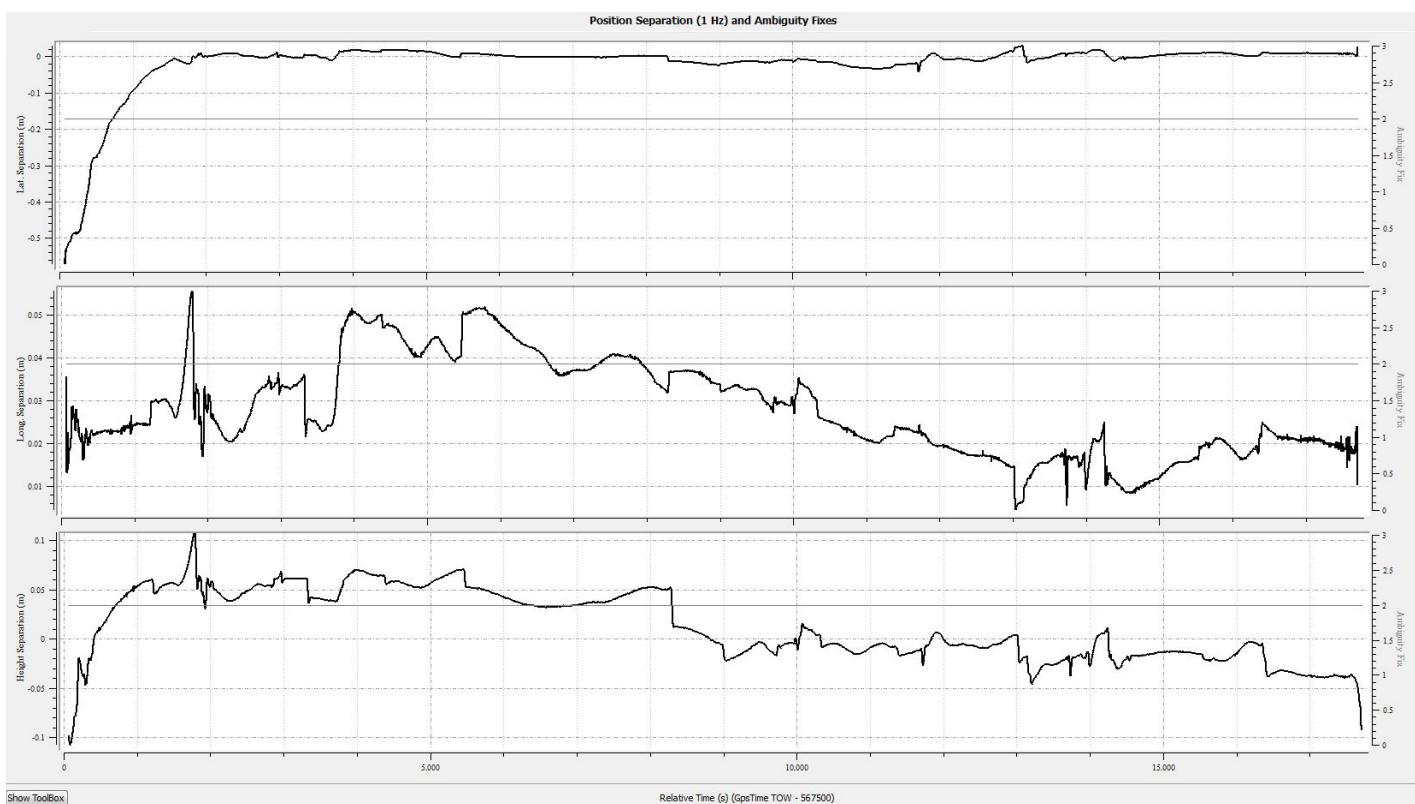


Image 8.0r: Separation Plot for mission 20140419_132934





9 QA/QC Output Control Report

Output Control Report on check points collected across the Will County project area and used to calibrate LiDAR data position.

Image 9.1: Will County Control Report

Will County Control Report					
Number	Easting	Northing	Known Z	Laser Z	Dz
1	1018836.862	1831633.703	667.970	667.490	-0.480
2	1036396.056	1731782.360	600.683	600.290	-0.393
3	1084867.774	1738572.801	702.995	702.810	-0.185
4	1118109.175	1742297.748	776.729	776.390	-0.339
5	1160632.651	1742172.905	772.295	772.010	-0.285
6	1191498.483	1737869.309	697.374	697.110	-0.264
7	1039502.725	1703032.198	562.393	562.660	0.267
8	1089047.569	1706170.493	691.301	690.940	-0.361
9	1150598.947	1702659.486	724.235	724.400	0.165
10	1198238.945	1703546.319	733.701	733.930	0.229
11	1029424.082	1668096.188	590.347	590.210	-0.137
12	1052019.609	1835970.320	723.148	722.660	-0.488
13	1056400.982	1668864.026	597.780	597.880	0.100
14	1020649.830	1794380.920	604.219	603.960	-0.259
15	1060140.484	1796049.901	584.702	584.730	0.028
16	1092137.162	1796349.749	748.228	748.110	-0.118
17	1021213.736	1768210.955	579.906	579.630	-0.276
18	1048507.226	1769286.099	647.264	646.880	-0.384
19	1085826.677	1765053.740	646.145	646.180	0.035
20	1117578.784	1763054.991	720.252	720.090	-0.162

Average dz	-0.17 ft
Minimum dz	-0.49 ft
Maximum dz	0.27 ft
Average magnitude	0.25 ft
Root mean square	0.23 ft
Std deviation	0.28 ft



10 Imagery of Control Locations

Image 10.0a: Control Location 1



Image 10.0b: Control Location 2



Image 10.0c: Control Location 3



Image 10.0d: Control Location 4



Image 10.0e: Control Location 5



Image 10.0f: Control Location 6





Image 10.0g: Control Location 7



Image 10.0h: Control Location 8



Image 10.0i: Control Location 9



Image 10.0j: Control Location 10



Image 10.0k: Control Location 11



Image 10.0l: Control Location 12





Image 10.0m: Control Location 13



Image 10.0n: Control Location 14



Image 10.0o: Control Location 15



Image 10.0p: Control Location 16



Image 10.0q: Control Location 17



Image 10.0r: Control Location 18





Image 10.0s: Control Location 19



Image 10.0t: Control Location 20





11 Accuracy Assessment

Image 11.0a: Vertical Accuracy Assessment

	LC Class	Count	Minimum	Maximum	St. Dev.	RMSE	95%	95th	Mean	Median	Skew
SVA	-	77	-0.64	0.77	0.27	0.30	-	0.58	0.13	0.12	0.03
CVA	-	97	-0.64	0.77	0.26	0.28	-	0.53	0.12	0.11	0.10
Bare Earth (FVA)	1	20	-0.30	0.52	0.20	0.21	0.40	-	0.08	0.10	0.18
Tall Weeds	2	20	-0.12	0.67	0.22	0.30	-	0.52	0.20	0.18	0.46
Brush Lands	3	20	-0.14	0.77	0.25	0.32	-	0.63	0.20	0.14	0.78
Forested	4	19	-0.24	0.71	0.25	0.26	-	0.50	0.07	0.08	0.81
Urban Areas	5	18	-0.64	0.48	0.33	0.32	-	0.47	0.02	0.03	-0.26

Image 11.0b: Ground check points used for accuracy assessment

Point #	Easting	Northing	Known Z	LIDAR Z	DZ	LC Class
1	1018690	1831661	666.265	666.15	-0.115	1
2	1051319	1836646	726.793	726.94	0.147	1
3	1021005	1794342	604.127	604.25	0.123	1
4	1059044	1794873	567.989	568.1	0.111	1
5	1092737	1794541	718.372	718.89	0.518	1
6	1020090	1768377	601.569	601.74	0.171	1
7	1048673	1769075	642.515	642.76	0.245	1
8	1085875	1765000	647.356	647.58	0.224	1
9	1117183	1762763	727.888	727.98	0.092	1
10	1045551	1735064	632.747	632.56	-0.187	1
11	1081484	1738747	688.56	688.55	-0.01	1
12	1114864	1744410	778.273	777.97	-0.303	1
13	1160395	1742263	767.043	767.06	0.018	1
14	1189746	1737690	707.346	707.34	-0.005	1
15	1039321	1703346	561.414	561.44	0.027	1
16	1089050	1706101	691.572	691.47	-0.102	1
17	1150494	1703323	727.972	727.81	-0.162	1
18	1198205	1701737	747.205	747.57	0.365	1
19	1031489	1668246	592.42	592.57	0.15	1
20	1057337	1669187	604.173	604.38	0.207	1
21	1020077	1830956	669.768	669.89	0.122	2
22	1050027	1836125	734.534	734.55	0.016	2
23	1020694	1794333	603.658	603.81	0.152	2
24	1060077	1795334	579.949	579.88	-0.069	2
25	1092989	1794484	711.023	711.69	0.667	2
26	1020822	1768635	606.266	606.15	-0.116	2
27	1051035	1767838	549.471	549.8	0.329	2
28	1087139	1762572	706.327	706.81	0.484	2
29	1118593	1763012	717.912	718.41	0.498	2
30	1044154	1734454	636.28	636.19	-0.09	2
31	1082680	1738047	700.333	700.37	0.037	2
32	1115891	1742896	761.731	762.24	0.509	2
33	1160393	1742620	762.855	763.07	0.216	2



Point #	Easting	Northing	Known Z	LIDAR Z	DZ	LC Class
34	1192079	1736559	689.063	689.08	0.018	2
35	1039080	1703224	561.3	561.59	0.29	2
36	1089404	1706105	696.514	696.54	0.026	2
37	1150531	1703444	727.653	727.95	0.297	2
38	1197961	1701980	738.491	738.82	0.33	2
39	1024811	1669681	588.966	588.98	0.014	2
40	1056320	1668727	601.281	601.51	0.229	2
41	1020002	1831265	667.467	667.5	0.033	3
42	1052200	1835658	723.183	723.3	0.117	3
43	1021287	1794307	605.293	605.2	-0.093	3
44	1060287	1795704	581.71	581.99	0.28	3
45	1092847	1794355	711.381	712	0.619	3
46	1020011	1768811	600.235	600.1	-0.135	3
47	1051324	1768905	543.017	543.33	0.313	3
48	1088262	1764890	686.705	686.79	0.085	3
49	1118075	1763381	716	716.77	0.769	3
50	1036990	1732003	611.318	611.32	0.002	3
51	1082962	1737895	692.223	692.35	0.127	3
52	1116154	1742626	776.41	776.66	0.25	3
53	1160339	1742161	765.965	766.53	0.565	3
54	1191827	1736610	693.038	692.95	-0.087	3
55	1039349	1700827	559.819	559.99	0.171	3
56	1089395	1705974	696.295	696.29	-0.005	3
57	1150423	1703433	725.933	726.09	0.157	3
58	1198038	1701954	742.365	742.82	0.455	3
59	1024675	1669445	587.192	587.28	0.088	3
60	1054928	1668941	592.308	592.67	0.361	3
61	1018902	1830882	666.096	666.22	0.124	4
62	1051363	1835478	725.173	725.25	0.077	4
63	1021271	1794533	604.976	605.08	0.104	4
64	1059028	1795011	567.58	567.73	0.15	4
65	1090591	1797305	750.955	751.2	0.245	4
66	1020488	1769257	600.01	599.77	-0.24	4
67	1051093	1767895	549.443	549.24	-0.203	4
68	1086656	1762462	701.971	702.1	0.13	4
69	1117206	1762868	721.436	721.23	-0.206	4
70	1036348	1731863	599.933	599.69	-0.243	4
71	1082704	1738100	701.192	701.19	-0.002	4
72	1116033	1741798	751.232	751.31	0.078	4
73	1160548	1742629	763.765	763.93	0.166	4
74	1191632	1735743	684.227	684.16	-0.067	4
75	1039406	1700814	559.158	559.64	0.482	4
76	1091362	1708240	698.928	698.72	-0.207	4



Point #	Easting	Northing	Known Z	LIDAR Z	DZ	LC Class
77	1150279	1702583	718.479	718.81	0.332	4
78	1198367	1699810	743.394	744.1	0.706	4
79	1031901	1668239	593.672	593.66	-0.012	4
80	1055019	1668960	593.42	593.62	0.2	5
82	1051895	1835693	724.683	724.42	-0.263	5
83	1021062	1793953	604.113	604.44	0.327	5
85	1090457	1797101	750.684	751.15	0.466	5
86	1020355	1768431	595.236	595.72	0.484	5
87	1048603	1769421	648.427	648.19	-0.237	5
89	1116500	1760403	755.702	755.29	-0.412	5
90	1036836	1732091	608.064	608.13	0.066	5
91	1081488	1738592	690.691	690.8	0.109	5
92	1115040	1744504	776.735	776.1	-0.635	5
93	1160548	1742533	773.127	772.99	-0.137	5
94	1189851	1737617	708.537	708.42	-0.117	5
95	1040015	1703312	565.26	564.88	-0.38	5
96	1088936	1706129	691.202	691.13	-0.072	5
97	1150710	1702367	729.506	729.5	-0.006	5
98	1198343	1702002	743.356	743.81	0.455	5
99	1031589	1668221	592.863	593.11	0.247	5
100	1054045	1667857	604.2	604.52	0.32	5



Thank You

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