Block B Champaign County_QL2+ Lidar 2019 Final Report

Report Produced for U.S. Geological Survey TASK ORDER: G17PC00007 REPORT DATE: 07/01/2020

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Overview

The original purpose of this project was to develop a consistent and accurate surface elevation dataset derived from high-accuracy Light Detection and Ranging (LiDAR) technology for the USGS IL_8County_PlusChampaign_2019_B19 project Area. The AOI covered approximately 6,337 square miles in total and include the counties of Champaign, Jo Daviess, Stephenson, Carroll, Ogle, Whiteside, Lee, Rock Island, and Henry. Block B allows for an increase in the quality level of the areas over Champaign County (~1049 sq. mi.) of QL2+ (ANPS \leq 0.5m). Adverse ground conditions during the fall 2019 flight season limited Lidar acquisition to a small portion of the entire project area. Approximately 1049 square miles of Block B referred to as Block B Champaign County_QL2+ Lidar 2019 was acquired in the fall of 2019 and spring of 2020.

The LiDAR data for Block B Champaign County, Illinois was processed and classified according to project specifications. Detailed breaklines, bare earth Digital Elevation Models (DEMs), and Intensity Images were produced for the Block B project area. Data was formatted into tiles with each tile covering an area of 1000 meters by 1000 meters. A total of 2717 LAS files, 2717 DEMs, and 2717 Intensity Images were produced for the project, encompassing the Block B AOI of approximately 1049 square miles and formatted into 2717 total tiles.

PROJECT TEAM

Aerial Services, Inc. (ASI) served as the prime contractor for the project. In addition to project management ASI was responsible for LiDAR acquisition and calibration, LAS classification, LiDAR products, Digital Elevation Model (DEM) production, Intensity Image production, and quality assurance. All follow-on processing was completed by the prime contractor.

Surveying and Mapping, LLC (SAM) completed ground surveying for the project and delivered surveyed checkpoints. SAM was to acquire surveyed checkpoints for the project to use in independent testing of the vertical accuracy of the LiDAR-derived surface model. Please see SURVEY REPORT to view the separate Survey Report that was created for this portion of the project.

SURVEY AREA

The project area addressed by this report falls within the Block B Champaign County, covering Champaign County, Illinois.

DATE OF SURVEY

LiDAR acquisition for Block B Champaign County was conducted between the dates of November 23, to December 7, 2019, with one mission flown March 8, 2020 to fill in a data void.

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COORDINATE REFERENCE SYSTEM

Data produced for the project was delivered in the following reference system.
Horizontal Datum: The horizontal datum for the project is North American Datum of 1983 with the 2011 Adjustment (NAD 83 (2011)).
Vertical Datum: The Vertical datum for the project is North American Vertical Datum of 1988 (NAVD88).
Coordinate System: Albers Equal Area.
Units: Horizontal units are in meters, Vertical units are in meters.
Geoid Model: Geoid12B

LIDAR VERTICAL ACCURACY

For the Block B Champaign County QL2+ project, the tested RMSEz of the classified LiDAR data for checkpoints in non-vegetated terrain equaled 0.050 meters compared with the 10 cm specification: The 95% confidence value of NVA of the classified LiDAR data computed using RMSEz x 1.96 and was found to equal 0.098 meters compared with the 0.196 meter specification.

For the Block B Champaign County QL2+ project, the tested VVA of the classified LiDAR data computed using the 95th percentile was equal to 0.106 meters, compared with the 0.294 meter (0.96 ft) specification.

Additional accuracy information and statistics for the classified LiDAR data, raw swath data, and bare earth DEM data can be found in following sections of this report.

PROJECT DELIVERABLES

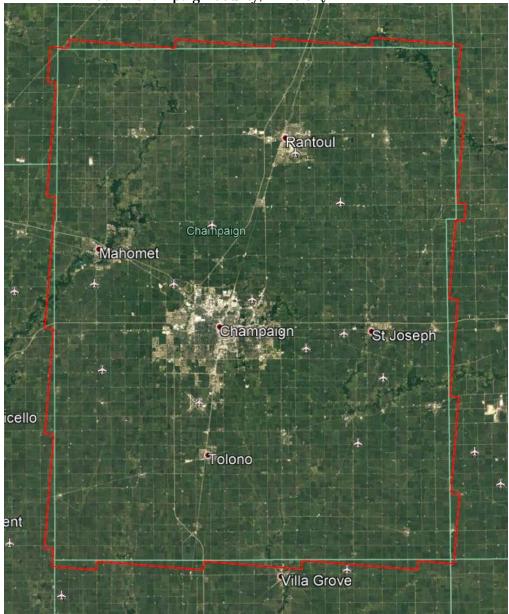
The deliverables for the project are listed below.

- 1. Classified Point Cloud Data (Tiled)
- 2. Bare Earth Surface (Raster DEM IMG format)
- 3. Intensity Images (8-bit gray scale, tiled, GeoTIFF format)
- 4. Breakline Data (File GDB)
- 5. Independent Survey Checkpoint Data (File GDB)
- 6. Calibration Points (File GDB)
- 7. Metadata
- 8. Project Report (Acquisition, Processing, QC)
- 9. Project Extent (File GDB)
- 10. Tile Index (File GDB)
- 11. Swath Footprint (File GDB)

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PROJECT TILING FOOTPRINT

2717 tiles, 2717 LAS files, 2717 DEM tiles, and 2717 Intensity Image tiles were delivered for the project. Each tile's extent is 1000 meter by 1000 meter. (See Appendix A for a complete listing of delivered tiles.)



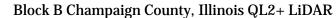


Figure 1 – Block B Champaign County Area of Interest

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Lidar Acquisition Details

Aerial Services, Inc. served as prime contractor for the Block B Champaign County QL2+ project and preformed the LiDAR Acquisition and Calibration.

Aerial Services, Inc. planned 60 passes for the project area as well as two additional cross flightlines for the purposes of quality control in our own processing which are not included in delivery. The flight plan included zigzag flight line collection as a result of the inherent IMU drift associated with all IMU systems. In order to reduce any margin for error in the flight plan, Aerial Services, Inc. followed FEMA's Appendix A "guidelines" for flight planning and, at a minimum, includes the following criteria:

• A digital flight line layout using LEICA MISSION PRO flight design software for direct integration into the aircraft flight navigation system.

- Planned flight lines; flight line numbers; and coverage area.
- Lidar coverage extended by a predetermined margin beyond all project borders to ensure necessary over-edge coverage appropriate for specific task order deliverables.

• Local restrictions related to air space and any controlled areas have been investigated so that required permissions can be obtained in a timely manner with respect to schedule. Additionally, Aerial Services, Inc. will file our flight plans as required by local Air Traffic Control (ATC) prior to each mission.

Aerial Services, Inc. monitored weather and atmospheric conditions and conducted lidar missions only when no conditions exist below the sensor that will affect the collection of data. These conditions include leaf-off for hardwoods, no snow, rain, fog, smoke, mist and low clouds. Lidar systems are active sensors, not requiring light, thus missions may be conducted during night hours when weather restrictions do not prevent collection. Aerial Services, Inc. accesses reliable weather sites and indicators (webcams) to establish the highest probability for successful collection in order to position our sensor to maximize successful data acquisition.

Within 72-hours prior to the planned day(s) of acquisition, Aerial Services, Inc. closely monitored the weather, checking all sources for forecasts at least twice daily. As soon as weather conditions were conducive to acquisition, our aircraft mobilized to the project site to begin data collection. Once on site, the acquisition team took responsibility for weather analysis.

Aerial Services, Inc. lidar sensors are calibrated at a designated site located at the Waverly Municipal Airport in Waverly, Iowa and are periodically checked and adjusted to minimize corrections at project sites.

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LIDAR SYSTEM PARAMETERS

Aerial Services, Inc. operated a Cessna (Tail # N5531A) outfitted with a LEICA ALS70-HP lidar system during the collection of the study area. Table 1 illustrates Aerial Services, Inc. system parameters for lidar acquisition on this project.

Item	Parameter
System	Leica ALS-70 HP
Maximum Number of Returns per Pulse	4
Nominal Pulse Spacing (single swath), (m)	0.5
Nominal Pulse Density (single swath) (ppsm), (m)	4
Aggregate NPS (m) (if ANPS was designed to be met through single coverage, ANPS and NPS will be equal)	0.5
Aggregate NPD (m) (if ANPD was designed to be met through single coverage, ANPD and NPD will be equal)	4
Altitude (AGL meters)	1300
Approx. Flight Speed (knots)	125
Total Sensor Scan Angle (degree)	50
Scan Frequency (hz)	47
Scanner Pulse Rate (kHz)	394
Did the Sensor Operate with Multiple Pulses in The Air? (yes/no)	Yes
Nominal Swath Width on the Ground (m)	1212
Swath Overlap (%)	30
Max. Point Spacing Along Track (m)	1.37
Max. Point Spacing Across Track (m)	0.84

Table 1: Aerial Services, Inc. Lidar System Parameters

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ACQUISITION STATUS REPORT AND FLIGHTLINES

Upon notification to proceed, the flight crew loaded the flight plans and validated the flight parameters. The Acquisition Manager contacted air traffic control and coordinated flight pattern requirements. Lidar acquisition began immediately upon notification that control base stations were in place. During flight operations, the flight crew monitored weather and atmospheric conditions. Lidar missions were flown only when no condition existed below the sensor that would affect the collection of data. The pilot constantly monitored the aircraft course, position, pitch, roll, and yaw of the aircraft. The sensor operator monitored the sensor, the status of PDOPs, and performed the first Q/C review during acquisition. The flight crew constantly reviewed weather and cloud locations. Any flight lines impacted by unfavorable conditions were marked as invalid and re-flown immediately or at an optimal time.

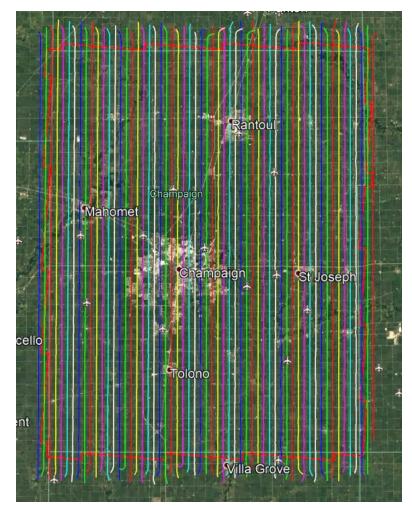


Figure 2 shows the combined trajectory of the flightlines.

Figure 2: G17PC00007_Block B Champaign County_2019_B19 trajectories as flown by Aerial Services, Inc.

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ACQUISITION CONTROL

Aerial Services, Inc. conducted the survey which provided the established base stations used to control the lidar acquisition for the Block B Champaign County project area. The coordinates of the base stations are provided in the table below.

	NAD83(20	011) Albers	
Name	Easting X (m)	Northing Y (m) Ellipsoid Ht (WGS84, m)	
ILUC	656696.577	1924964.492	232.663

Table 2 – Base station used to control lidar acquisition for the Project.

AIRBORNE GPS KINEMATIC

Airborne GPS data was processed using Waypoint's Inertial Explorer version 8.60 software suite. All flights were flown with PDOP less than or equal to 3.0 and with at least 6 satellites in common view of both a stationary reference receiver and the airborne GPS. Distances from base station to aircraft were kept to a maximum of 50 km.

For all flights, the GPS data can be classified as excellent, with GPS residuals no larger than 10 cm being recorded.

GPS processing reports for each mission are included in Appendix B.



figure 3 – G17PC00007_Block B Champaign County_2019_B19 Base station location

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GENERATION AND CALIBRATION OF LASER POINTS (RAW DATA)

After processing the GNSS/GPS and IMU data in Inertial Explorer, the data is then exported to raw LAS files using Leica's CloudPro software. CloudPro combines the raw data collected with the ALS 70 HP sensor, combines it with the airborne trajectory data, applies the sensor's calculated boresight correction angles, and then outputs the point cloud to the specified coordinate reference system and file format.

The initial step of calibration is to verify the complete coverage of the AOI with no internal voids present, as well as ensuring that minimum point density of 4.0 ppsm has been achieved.

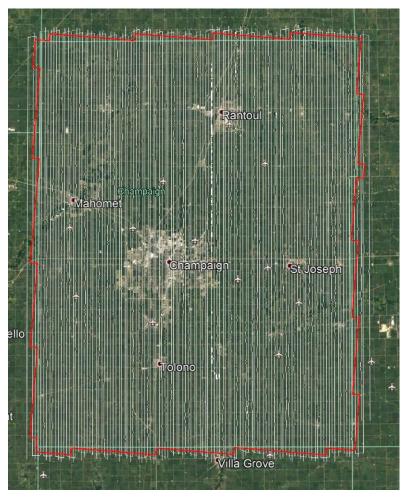


Figure 4 – Lidar swath coverage over AOI.

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Boresight and Relative Accuracy

Subsequently, the project's data is then loaded into Microstation/TerraScan for viewing and postprocessing of calibration errors. Roll, pitch, and heading corrections are calculated to produce the best relative accuracy that can be achieved, and at minimum 8 cm RMSDz with a 16 cm maximum difference. Tested interswath RMSDz was 0.013 meters.

The relative accuracy of every swath is checked and QC'd at 3 different points along its length. Cross sections are visually inspected across each block to validate point to point, flight line to flight line and mission to mission agreement to verify that the project meet the specifications.

For this project the specifications used are as follow

Relative accuracy <= 6 cm maximum differences within individual swaths and <=8 cm RMSDz between adjacent and overlapping swaths.

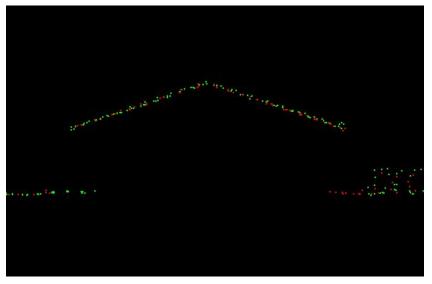


Figure 5 – Profile view showing proper interswath calibration.

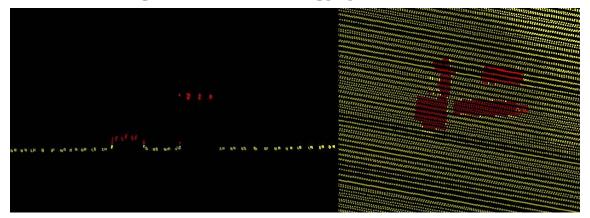


Figure 6 – Top view showing a parking lot with a car and raised feature on a single swath demonstrating intraswath accuracy. Yellow color is scaled to a range of 6 cm in elevation. Points are within 6 cm of variation until the raised curb and car. Also shown is a profile view showing low variability of ranges within the swath.

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DELTA-Z ACCURACY ASSESSMENT

Swath-to-swath relative accuracy is assessed by comparing the elevations of overlapping swaths. Delta-z is a raster file representing the differences in elevation of overlapping swaths and is generated from the subtraction of the two raster files created from each swath over the entire area of interest. It is then used to calculate the RMSDz, which in turn is displayed as a visual representation of error distribution.

The image below is a LIDAR "ortho" image created from the laser return intensity, Z (elevation) and swath number. The image is rendered as grayscale where there is no overlap between data from different flight lines (swath). Where two (or more) flight lines overlap, a color rendering is constructed base on the average maximum elevation difference between points in the overlapping swath. The distance (dZ) is indexed into a user-defined color. In the image below, four-color bands were separated into 8 cm increments. Thus green represents dZs from 0 to 8 cm, yellow from 8 cm to 16 cm, orange from 16 cm to 24 cm and red for dZ greater than 24 cm. The dZ image provides a quick method of quickly assessing the relative vertical accuracy of a LiDAR project.

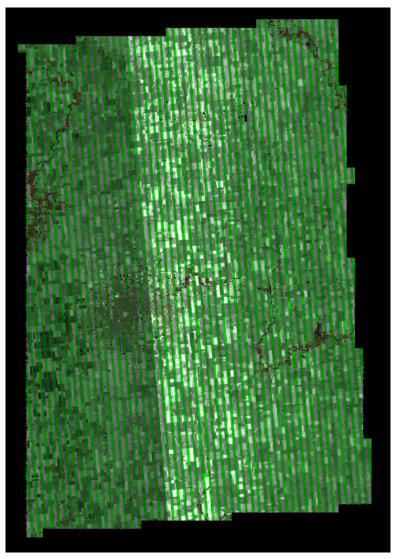


Figure 7: Block B Champaign County, Illinois Project Delta-z raster image.

Final Calibration Verification

Surveying and Mapping, LLC (SAM) conducted the survey for 34 ground control points (GCPs) which were used to test the accuracy of the calibrated swath data. These 34 GCPs were available to use as control in case the swath data exhibited any biases which would need to be adjusted or removed. The coordinates of all GCPs are provided in table 3 and the accuracy results from testing the calibrated swath data against the GCPs is provided in table 4; no further adjustments to the swath data were required based on the accuracy results of the GCPs. Accuracy of the raw point cloud against GCP: 0.04 meters (0.134 ft.) with a 95% confidence value of 0.078 meters (0.255 ft.).

	NAD83 (2011 adj) IL_East		NAVD88 (Geoid 12B)	
Point ID	Easting X	Northing Y	Z-Survey	Z-LiDAR	Dz
	(USft)	(USft)	(USft)	(USft)	(USft)
GCP43	948968.95	1357947.546	745.449	745.55	0.101
GCP44	1090796.096	1353412.891	721.656	721.76	0.104
GCP45	1034310.121	1325739.357	742.015	741.79	-0.225
GCP46	978660.997	1326857.997	718.698	718.81	0.112
GCP47	962170.781	1287285.742	776.76	776.77	0.01
GCP48	1010357.738	1265131.508	747.422	747.48	0.058
GCP49	1082710.407	1284249.283	681.251	681.31	0.059
GCP50	1008307.158	1233709.014	725.356	725.45	0.094
GCP51	1065651.404	1255316.175	671.096	671	-0.096
GCP52	990063.988	1255221.406	743.837	743.62	-0.217
GCP53	1031180.229	1256526.084	716.202	716.35	0.148
GCP54	1059265.211	1223143.572	673.35	673.43	0.08
GCP55	1095551.842	1181798.995	702.101	702.1	-0.001
GCP56	1005080.85	1208920.208	732.815	732.81	-0.005
GCP57	950014.508	1193196.364	683.242	683.09	-0.152
GCP92	1001502.308	1348654.231	720.117	720.13	0.013
GCP93	1060493.29	1343828.917	775.5	775.7	0.2
GCP94	996552.615	1305978.552	747.99	748	0.01
GCP95	1071400.244	1312096.162	712.786	712.74	-0.046
GCP96	1048337.073	1295831.148	698.173	698.22	0.047
GCP97	1026772.094	1282907.786	730.862	731.19	0.328
GCP98	1011093.982	1256125.515	728.263	728.24	-0.023
GCP99	989709.03	1272434.513	781.665	781.7	0.035
GCP100	1021678.738	1244550.299	735.532	735.7	0.168
GCP101	986738.375	1235029.791	700.212	700.07	-0.142
GCP102	958162.92	1252179.04	705.882	705.83	-0.052
GCP103	969057.741	1217976.28	687.593	687.24	-0.353
GCP104	1036258.972	1213003.028	720.8	720.72	-0.08
GCP105	1079124.6	1207289.037	689.53	689.51	-0.02
GCP106	975788.327	1178091.942	681.231	681	-0.231
GCP107	1027198.712	1196730.034	676.055	675.97	-0.085
GCP108	1060543.304	1172730.65	681.101	681.12	0.019
GCP109	1016694.862	1185890.001	670.267	670.27	0.003
GCP110	1041736.159	1354928.868	772.976	773.03	0.054

 Table 3 – Block B Champaign County, Illinois Project surveyed ground control points (GCPs).

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This project must meet Non-vegetated Vertical Accuracy (NVA) \leq 0.64 ft (19.6 cm) at the 95% confidence level based on RMSE_z \leq 0.33 ft (10 cm) x 1.9600.

100 % of Totals	# of Points	RMSEz NVA (m)	NVA- Non- vegetated Vertical Accuracy ((RMSEz x 1.9600) m	Mean (m)	Median (m)	Skew	Std Dev (m)	Min (m)	Max (m)	Kurtosis
NVA	64	0.050	0.098	-0.022	-0.024	0.167	0.044	-0.134	0.130	2.163

Table 4 – Non-vegetated Vertica Accuracy (NVA) results.

DATA CLASSIFICATION AND EDITING

Once the calibration, absolute swath vertical accuracy, and relative accuracy of the data were confirmed, ASI utilized TerraScan software for data processing. The acquired 3D laser point clouds, in LAS binary format, were imported into the project and tiled according to the project tile grid. Once tiled, the laser points were classified using a proprietary routine in TerraScan. This routine classifies any obvious low outliers in the dataset to class 7 and high outliers in the dataset to class 18. After points that could negatively affect the ground are removed from class 1, the ground layer is extracted from this remaining point cloud. The ground extraction process encompassed in this routine takes place by building an iterative surface model. This surface model is generated using three main parameters: building size, iteration angle and iteration distance. The initial model is based on low points being selected by a "roaming window" with the assumption that these are the ground points. The size of this roaming window is determined by the building size parameter. The low points are triangulated and the remaining points are evaluated and subsequently added to the model if they meet the iteration angle and distance constraints. This process is repeated until no additional points are added within iterations. A second critical parameter is the maximum terrain angle constraint, which determines the maximum terrain angle allowed within the classification model.

Once the ground surface had been deduced through the filtering process a vegetation class was then extracted by distance from ground from remaining class 1. With Building size parameters set, extraction of buildings from the vegetation class occurs. Once building had been deduced the remaining vegetation points were re-filtered by distance into Low Vegetation is 0.5-5 feet, Medium Vegetation is 5-20 feet, High Vegetation is >20 feet.

In TerraScan surface models for each tile was created to examine the ground classification. ASI analysts visually reviewed the ground surface model for artifacts left in the ground classification. Theses artifacts consist of vegetation, buildings, and bridges that were still present in the ground after initial processing. ASI analysts employ 3D visualization techniques to view the point cloud at multiple angles and in profile to ensure that errant points are removed from the ground classification. Bridge decks are manually classified to class 17. Building rooftops were manually reviewed to ensure that proper classification had occurred. Due to moist ground conditions of the 2019 flight season, the ground surface had a rougher appearance. A fence macro was utilized to reduce and mitigate the roughness of the ground surface. Another fence macro was used to smooth the ground surface by removing man-made structures and vegetation. ASI fence macros classified man-made structures to class code 1 (default) and rough below ground surface points to class code 7

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(low noise). After the ground classification and building corrections completed, the dataset was processed through a water classification routine that utilizes breaklines compiled by the prime ASI to automatically classify hydro features. The water classification routine selects ground points within the breakline polygons and automatically classifies them as class 9, water. During this water classification routine, ground points that are within 2x NPS or less of the hydrographic features are moved to class 20 ignored ground, due to breakline proximity. Overage points are then identified in TerraScan and used to set the overlap bit for those points. The withheld points identified during the classification routine are used to set the withheld bit. The LiDAR tiles were classified to the following classification schema:

- o Class 1 Default, Processed, but unclassified
- o Class 2 Ground, Bare-earth
- o Class 3 Low Vegetation is 0.5-5 feet
- o Class 4 Medium Vegetation is 5-20 feet
- o Class 5 High Vegetation is >20 feet
- o Class 6 Buildings (Champaign County only)
- o Class 7 Low Noise (low and manually identified)
- o Class 9 Water
- o Class 17 Bridge Decks
- o Class 18 High Noise (high, manually identified)
- o Class 20 Ignored Ground (Breakline Proximity)
- o Class 21- Snow (if present and identifiable)
- o Class 22- Temporal Exclusion (typically non-favored data in intertidal zones, as necessary)

After manual classification, the LAS tiles were peer reviewed and then underwent a final QA/QC. After the final QA/QC and corrections, the LAS files were then converted from LAS v1.2 to LAS v1.4 using TerraScan software to flag the overlap bit and withheld bit. LP360 64bit was used to deduce the Well Known Text (WKT) and an ASI proprietary software was used to format the LAS to the final LAS v1.4 Format 6 version. LAStools by rapidlasso GmbH, open source, lasvalidate (open source LGPL) and ASI proprietary software was used to perform final analysis to checks on LAS header information, LAS point classes, and LAS timestamps.

LIDAR QUALITATIVE ASSESSMENT

ASI's qualitative assessment utilizes a combination of statistical analysis and interpretative methodology or visualization to assess the quality of the data for a bare-earth digital terrain model (DTM). This includes creating pseudo image products such as LiDAR orthos produced from the intensity returns, Triangular Irregular Network (TIN)'s, Digital Elevation Models (DEM) and 3-

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dimensional models as well as reviewing the actual point cloud data. This process looks for anomalies in the data, areas where man-made structures or vegetation points may not have been classified properly to produce a bare-earth model, and other classification errors. This report will present representative examples where the LiDAR and post processing had issues as well as examples of where the LiDAR performed well.

VISUAL REVIEW

The following sections describe common types of issues identified in LiDAR data and the results of the visual review for Block B Champaign County project.

Data Voids

Acceptable voids (areas with no LiDAR returns in the LAS files) that are present in the majority of LiDAR projects include voids caused by bodies of water. No unacceptable voids are present in the Block B Champaign County project.

Bridge Removal Artifacts

The DEM surface models are created from TINs or Terrains. TIN and Terrain models create continuous surfaces from the inputs. Because a continuous surface is being created, the TIN or Terrain will use interpolation to continue the surface beneath the bridge where no LiDAR data was acquired. Locations where bridges were removed will generally contain less detail in the bare-earth surface because these areas are interpolated. The DEM in the bottom view shows an area where a bridge has been removed from ground. The surface model must make a continuous model and in order to do so, points are connected through interpolation. This results in less detail where the surface must be interpolated. The profile in the top view shows the LiDAR points of this particular feature colored by class. All bridge points have been removed from ground (orange) and are bridge deck (blue).

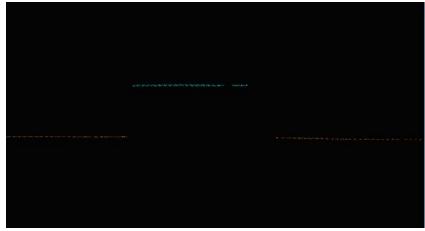


Figure 8: Profile view of a classified bridge deck (blue) and ground (orange).

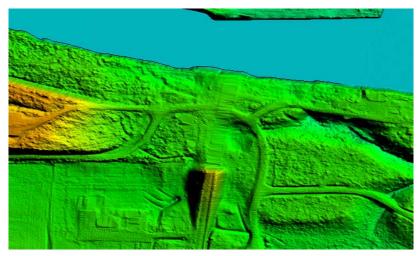


Figure 9: DEM with bridge removed from surface model.

Culverts

Bridges have been removed from the bare earth surface while culverts remain in the bare earth surface. In instances where it is difficult to determine if the feature is a culvert or bridge, such as with some small bridges, ASI erred on assuming they would be culverts especially if they are on secondary or tertiary roads. Below is an example of a culvert that has been left in the ground surface.

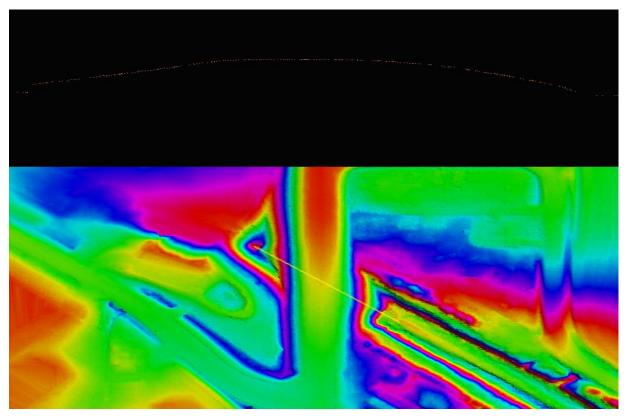


Figure 10: Profile with points colored by class (class 1=white, class 2=orange) is shown in the top view and the DEM is shown in the bottom view. This culvert remains in the bare earth surface. Bridges have been removed from the bare earth surface and classified to class 17.

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Dirt Mounds

Irregularities in the natural ground exist and may be misinterpreted as artifacts that should be removed. Hills and dirt mounds are present throughout the project area. These features are correctly included in the ground.

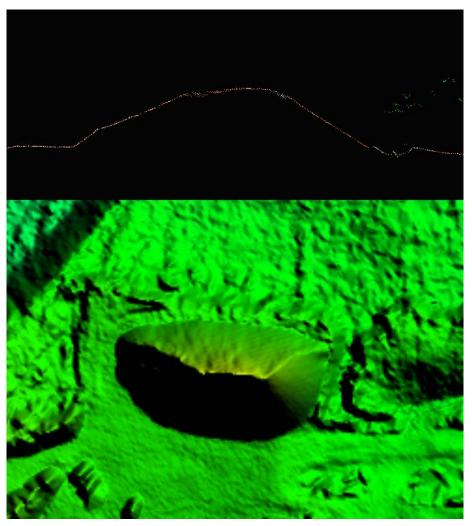


Figure 11 - Profile with the points colored by class (unclassified points are white, ground points are orange) is shown on the right and a DEM of the surface is shown to the left. These features are correctly included in the ground classification.

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Flightline Ridges

Ridges occur when there is a difference between the elevations of adjoining flight lines or swaths. Some flightline ridges are visible in the final DEMs but they do not exceed the project specifications and the overall relative accuracy requirements for the project area have been met. An example of a visible flightline ridge that is within tolerance is shown below.

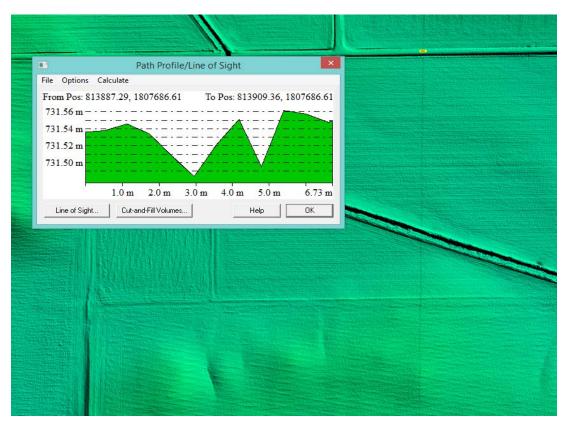


Figure 12 – The flight line ridge is less than 8 cm. Overall, the Block B Champaign County project data meets the project specifications for 8 cm RMSDz relative accuracy requirement.

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Dam and Lock system

Irregularities in the natural water flow exist in sections of river affected by Lock and Dam systems. Series of locks enable vessels to "step" up or down a river or canal from one water level to another. There are no Lock systems in the Block B Champaign County Lidar project area.

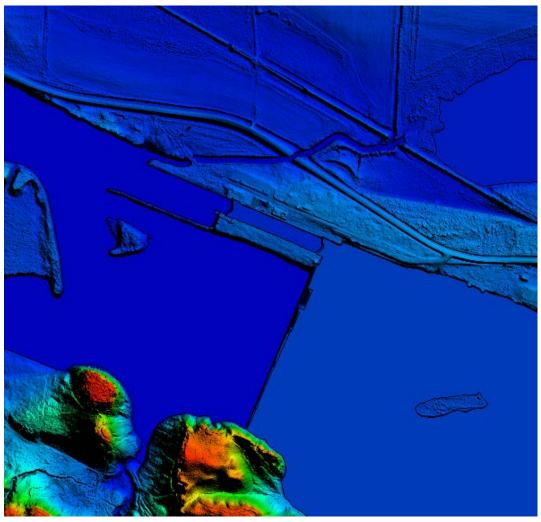


Figure 13 – DEM shows Large Dam structure that disrupts natural monotonic river flow, coupled with a lock system.

FORMATTING

After the final QA/QC is performed and all corrections have been applied to the dataset, all LiDAR files are updated to the final format requirements and the final formatting, header information, point data records, and variable length records are verified using ASI proprietary tools. ASI routinely reviews for: proper LAS versions, Coordinate Reference System, Global Encoder Bit, Time Stamp, System ID, Multiple Returns, Intensity, Classification, Overlap and Withheld Points, Scan angle, XYZ Coordinates.

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LiDAR Positional Accuracy

BACKGROUND

ASI quantitatively tested the dataset by testing the vertical accuracy of the LiDAR. The vertical accuracy is tested by comparing the discreet measurement of the survey checkpoints to that of the interpolated value within the three closest LiDAR points that constitute the vertices of a three-dimensional triangular face of the TIN. Therefore, the end result is that only a small sample of the LiDAR data is actually tested. However there is an increased level of confidence with LiDAR data due to the relative accuracy. This relative accuracy in turn is based on how well one LiDAR point "fits" in comparison to the next contiguous LiDAR measurement, and is verified as part of the initial processing. If the relative accuracy of a dataset is within specifications and the dataset passes vertical accuracy requirements at the location of survey checkpoints, the vertical accuracy results can be applied to the whole dataset with high confidence due to the passing relative accuracy. The nature of lidar data makes it difficult to assess absolute horizontal accuracy as one would with imagery or compiled planimetric data. Guidance on how absolute horizontal accuracy can be estimated and reported based on the error budget of the instrumentation and operational parameters can be found in ASPRS (2014). The horizontal accuracy of each lidar project shall be reported using the form specified by the ASPRS (2014).

SURVEY VERTICAL ACCURACY CHECKPOINTS

For the vertical accuracy assessment of Block B Champaign County project, sixty four check points were surveyed. All of those check points are located within bare earth/open terrain (64 NVA points). Please see provided survey report which details and validates how the survey was completed for this project. Checkpoints were evenly distributed throughout the project area so as to cover as many flight lines as possible using the "dispersed method" of placement. All checkpoints surveyed for vertical accuracy testing purposes are listed in the following table.

Point ID	NAD83 (2011) Albers Equal Area	NAD83 (2011) Albers Equal Area	NAVD88 (Geoid12B)
	Easting (M)	Northing (M)	Elevation (M)
NVA042	641114.007	1955283.019	220.491
NVA043	661757.869	1949739.54	224.357
NVA044	667548.253	1958075.164	229.178
NVA045	639982.725	1933822.037	215.753
NVA046	673733.595	1928352.831	209.238
NVA047	650909.866	1928393.034	233.38
NVA048	655106.949	1924700.919	224.304
NVA049	657866.726	1926939.638	214.841
NVA050	646875.635	1909372.805	208.084
NVA051	663507.225	1903726.764	199.613

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NVA052	679402.599	1919532.316	204.664
NVA032 NVA140	635039.843	1913532.510	227.336
NVA141	649407.221	1949119.713	222.319
NVA142	649785.99	1956493.343	219.394
NVA143	671077.199	1950543.4	240.285
NVA144	661325.999	1954814.276	236.85
NVA145	678316.726	1942220.183	228.275
NVA146	658135.513	1941571.878	223.062
NVA147	644110.441	1947184.223	217.067
NVA148	644021.973	1937128.511	219.407
NVA149	653512.253	1930692.204	227.677
NVA150	648439.747	1923050.665	217.352
NVA151	651062.915	1924668.668	220.314
NVA152	655144.476	1927482.6	223.86
NVA153	655221.329	1919407.989	218.872
NVA154	661626.112	1923926.129	212.215
NVA155	639257.009	1924474.162	213.315
NVA156	665609.479	1935476.194	212.232
NVA157	675945.487	1937208.937	206.915
NVA158	638212.208	1906072.123	208.355
NVA159	654791.987	1912936.511	225.132
NVA160	648096.526	1919656.033	211.972
NVA161	677648.744	1905164.935	207.907
NVA162	669648.759	1916933.604	202.535
NVA163	669291.197	1911170.088	216.369
NVA164	653679.688	1903982.443	217.509
NVA165	646226.512	1901945.024	208.693
NVA166	640036.689	1915351.824	210.899
NVA167	668930.406	1941705.657	208.843
NVA168	649332.791	1943299.71	222.965
NVA169	659362.198	1929565.858	217.87
NVA170	658198.411	1935041.67	220.671
NVA171	658992.937	1949467.758	224.886
NVA172	660911.368	1910668.082	208.5
NVA173	663729.416	1914385.023	219.719
NVA174	679935.454	1913682.922	206.961
NVA175	651285.525	1934550.734	234.233
NVA176	640464.228	1941810.92	222.047
NVA177	661810.248	1926670.814	214.346
NVA178	671768.821	1927101.566	203.285
NVA179	676374.015	1924272.252	201.265

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NVA180	678345.892	1928919.581	203.707
NVA181	671919.508	1902158.385	205.928
NVA182	662750.668	1948182.817	221.846
NVA183	644078.011	1933948.424	233.6
NVA184	636637.291	1952867.217	223.347
NVA185	634018.983	1956605.67	227.263
NVA186	661929.299	1957728.371	235.26
NVA187	676149.404	1957993.39	218.554
NVA188	647517.031	1908914.372	210.531
NVA189	677953.576	1950006.726	216.871
NVA190	644143.981	1925020.781	217.12
NVA191	675971.697	1908276.911	209.479
NVA192	658346.094	1940216.373	222.146
VVA93	637009.794	1952866.348	222.832
VVA94	643763.161	1947976.317	221.141
VVA95	660099.170	1946368.031	223.303
VVA96	661698.993	1950511.488	226.773
VVA97	661971.381	1956883.909	233.387
VVA98	675346.966	1958701.663	216.760
VVA99	677638.405	1949501.400	216.285
VVA100	643312.859	1937141.176	216.180
VVA101	637327.879	1933374.493	216.377
VVA102	658475.854	1941141.564	222.634
VVA103	676626.626	1937028.754	207.062
VVA104	668984.945	1941594.356	208.657
VVA105	658985.924	1931640.266	222.866
VVA106	653761.138	1925741.699	233.311
VVA107	657761.795	1925679.091	221.487
VVA108	661362.812	1923647.559	212.445
VVA109	648949.267	1922584.355	219.363
VVA110	672337.650	1927186.817	207.141
VVA111	644032.638	1925013.092	217.332
VVA112	647913.553	1951758.779	218.573
VVA113	639242.588	1924299.653	215.290
VVA114	642100.038	1915532.961	211.445
VVA115	654084.892	1919802.719	226.757
VVA116	662829.448	1915469.939	223.393
VVA117	670459.243	1917874.485	206.298
VVA118	678662.939	1919773.753	204.034
VVA119	677569.501	1904832.300	210.284
VVA120	654396.715	1903867.031	215.326

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638277.484	1905964.574	208.195
653751.508	1912210.180	223.231
669259.069	1911385.290	218.952
663513.032	1904162.039	199.579
646983.591	1909302.230	209.152
646178.282	1899752.610	206.267
641328.824	1941776.358	213.779
655252.523	1948705.628	220.816
649834.756	1955748.767	218.926
671588.533	1948700.627	237.786
670156.366	1955049.228	229.658
641163.305	1954804.860	217.182
634859.595	1947893.071	226.260
646515.634	1931867.668	226.640
665632.555	1935482.958	211.936
651051.004	1934265.903	234.738
661257.576	1910527.410	208.090
654697.227	1929823.996	228.121
648938.781	1944889.910	219.451
674333.648	1908597.686	212.411
	653751.508 669259.069 663513.032 646983.591 646983.591 646178.282 641328.824 655252.523 649834.756 671588.533 670156.366 641163.305 634859.595 646515.634 665632.555 651051.004 661257.576 654697.227 648938.781	653751.5081912210.1806635751.5081912210.180669259.0691911385.290663513.0321904162.039646983.5911909302.230646178.2821899752.610641328.8241941776.358655252.5231948705.628649834.7561955748.767671588.5331948700.627670156.3661955049.228641163.3051954804.860634859.5951947893.071646515.6341931867.668665632.5551935482.958651051.0041934265.903661257.5761910527.410654697.2271929823.996648938.7811944889.910

Table 5 – Block B (Champaign	County project	LiDAR	Checkpoints.
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Figure 14 – Location of Block B Champaign County LiDAR NVA Checkpoints



Figure 15- No VVA Checkpoints were located in Block B Champaign County

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VERTICAL ACCURACY TEST PROCEDURES

NVA (Non-vegetated Vertical Accuracy) is determined with check points located only in nonvegetated terrain, including open terrain (grass, dirt, sand, and/or rocks) and urban areas, where there is a very high probability that the LiDAR sensor will have detected the bare-earth ground surface and where random errors are expected to follow a normal error distribution. The NVA determines how well the calibrated LiDAR sensor performed. With a normal error distribution, the vertical accuracy at the 95% confidence level is computed as the vertical root mean square error (RMSEz) of the checkpoints x 1.9600. For the Block B Champaign County project, vertical accuracy must be 19.6 cm (0.64 ft) or less based on an RMSEz of 10 cm (0.33 ft) x 1.9600. VVA (Vegetated Vertical Accuracy) is determined with all checkpoints in vegetated land cover categories, including tall grass, weeds, crops, brush and low trees, and fully forested areas, where there is a possibility that the LiDAR sensor and post-processing may yield elevation errors that do not follow a normal error distribution. VVA at the 95% confidence level equals the 95th percentile error for all checkpoints in all vegetated land cover categories combined. The Block B Champaign County Lidar project VVA standard is 29.4 cm (0.96 ft) based on the 95th percentile.

Quantitative Criteria	Measure of Acceptability
Non-Vegetated Vertical Accuracy (NVA) in open terrain and urban land cover categories using RMSEz *1.96	19.6 cm (based on RMSEz (10 cm)*1.96)
Vegetated Vertical Accuracy (VVA) in all vegetated land cover categories combined and at the 95 th Percentile error	29.4 cm (based on combined 95th percentile)

Table 6 – Acceptance Criteria.

The primary QA/QC vertical accuracy testing steps used by ASI are summarized as follows:

1. SAM surveyed QA/QC vertical checkpoints in accordance with the project's specifications.

2. Next, ASI interpolated the bare-earth LiDAR DTM to provide the z-value for every checkpoint.

3. ASI then computed the associated z-value differences between the interpolated z-value from the LiDAR data and the ground truth survey checkpoints and computed NVA, VVA, and other statistics.

4. The data were analyzed by ASI to assess the accuracy of the data. The review process examined the various accuracy parameters as defined by the scope of work. The overall descriptive statistics of each dataset were computed to assess any trends or anomalies. This report provides tables, graphs and figures to summarize and illustrate data quality.

VERTICAL ACCURACY RESULTS

The table below summarizes the tested vertical accuracy resulting from a comparison of the surveyed checkpoints to the elevation values present within the fully classified LiDAR LAS files.

Land Cover Category	# of Points	NVA – Non-vegetated Vertical Accuracy (95% confidence)Spec = 0.196 m	VVA – Vegetated Vertical Accuracy (95 th Percentile) spec = 0.294 m
NVA	64	0.098	
VVA	48		0.106

Table 7 – Tested NVA and VVA.

HORIZONTAL ACCURACY TEST PROCEDURES

This data set was produced to meet ASPRS "Positional Accuracy Standards for Digital Geospatial Data" (2014) for a 20.8 (cm) RMSEx / RMSEy Horizontal Accuracy Class which equates to Positional Horizontal Accuracy = +/- 40.768 cm at a 95% confidence level."

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Breakline Production Methodology

MicroStation, in conjunction with TerraSolid's TerraScan and TerraModeler was utilized for the collection of hydrologic breaklines, which occurred independently of manual edit. Collection was done using 2D information in the LAS format, intensity format, and ground surface. Breaklines are developed to the limit of the project boundary. Breaklines are in the same coordinate reference system and unit of measure as the LiDAR point delivery. Hydrologic water-surface edges are set at or just below the immediately surrounding terrain. Breaklines are developed to the limit of the project boundary.

BREAKLINE QUALITATIVE ASSESSMENT

Completeness and horizontal placement is verified through visual review against LiDAR intensity imagery, and bare earth surface. Breakline features are check for connectivity of features, enforced monotonicity on linear hydrographic breaklines, and flatness on water bodies.

After all corrections and edits to the breakline features, the breaklines are imported into the final GDB and verified for correct formatting.

FEATURE DEFINITION

Inland Streams and Rivers

Streams and Rivers with a nominal width of 30 meters (100 feet), were collected to best fit the shoreline by using information in the LAS format; intensity format, ground surface TIN, and sometimes "quick guide" contours. Streams and rivers do not break at bridges, but they are closed ended breaks at culvert locations. Steams and Rivers breaklines have been delivered in PolylineZ format in the final GDB.

Inland Ponds and Lakes

Inland ponds and lakes of 2 acres (86,111 square feet/~350'/~106 meter diameter for a round pond) or greater were collected. Inland pond and Lakes were collected to best fit the shoreline by using information in the LAS format; intensity format, ground surface TIN, and sometimes "quick guide" contours. Inland pond and Lakes Breaklines have been delivered in PolygonZ format in the final GDB.

Islands

Permanent island 4046m² (1 acre) or larger were delineated within all water bodies. Breaklines have been delivered in PolygonZ format in the final GDB

Bridge Breaklines

Breaklines were placed across the bottom of the bridge embankment when triangulation occurred due to bridge deck classification. Breaklines have been delivered in PolylineZ format in the final GDB.

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Intensity Imagery Production & Qualitative Assessment

INTENSITY PRODUCTION METHODOLOGY

ASI utilized MicroStation in conjunction with TerraSolid's TerraScan for Intensity production. Global Mapper was used to QC the products. ArcGIS was used finalize the Intensity's projection.

Intensity Images are created for each tile in the tiling schema. The Intensities are reviewed for any issues requiring corrections. Tiles are verified for final formatting and loaded into Global Mapper to ensure there are no missing, or corrupt tiles, and to check for seamlessness across tile boundaries.

INTENSITY QUALITATIVE ASSESSMENT

ASI performed a qualitative assessment of the Intensity deliverables to ensure that all tiled Intensity products were delivered with the proper extents, and contained proper referencing information. This lidar survey was conducted over a span of time consisting of both day and nighttime missions. In this data set Lidar collected during daytime hours tends to have intensity returns of lighter higher range values as opposed to dark lower range value intensity returns of missions flown at night. Lighter daytime and darker nighttime intensity values are evident in the intensities of this dataset. Figure 16, is an example of an Intensity Image that contains both daytime and nighttime collections of lidar data. The left side of the image contains higher intensity values consistent with a daytime collection, while the darker right side exhibits lower intensity values consistent with a night time collection.



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Figure 16 – Intensity Image example.

DEM Production & Qualitative Assessment

DEM PRODUCTION METHODOLOGY

ASI utilized MicroStation Connect in conjunction with TerraSolid's TerraScan and TerraModeler for DEM production. Global Mapper version 21.0 was used to format and QC the products. GDAL version 2.4.0 was used finalize the DEMs projection.

The final bare earth LiDAR points are used to create a terrain. The final 3D breaklines collected for the project are enforced in the terrain. The terrain is then converted to raster format using linear interpolation. DEMs are created for each tile in the tiling schema. The DEMs are reviewed for any issues requiring corrections, including remaining LiDAR ground misclassification, erroneous breakline elevations, poor hydro flattening, and processing artifacts. Tiles are verified for final formatting and loaded into Global Mapper to ensure there are no missing, or corrupt tiles, and to check for seamlessness across tile boundaries.

DEM QUALITATIVE ASSESSMENT

ASI performed a qualitative assessment of the bare earth DEM deliverables to ensure that all tiled DEM products were delivered with the proper extents, were free of processing artifacts, and contained proper referencing information.

The image below shows an example of a bare earth DEM.

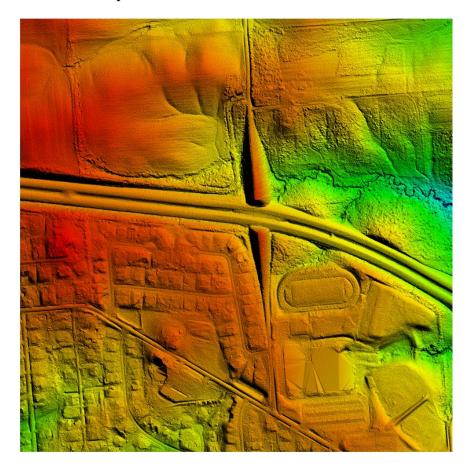


Figure 17 – Block B Champaign County project bare earth DEM

DEM VERTICAL ACCURACY RESULTS

The same 64 checkpoints that were used to test the vertical accuracy of the LIDAR were used to validate the vertical accuracy of the final DEM products as well. Accuracy results may vary between the source LiDAR and final DEM deliverable. DEMs are created by averaging several LiDAR points within each pixel which may result in slightly different elevation values at each survey checkpoint when compared to the source LAS. The DEM pixel does not average several LiDAR point's together, it interpolates (linearly) between two or three points to derive an elevation value. The vertical accuracy of the DEM is tested by extracting the elevation of the pixel that contains the x/y coordinates of the checkpoint and comparing these DEM elevations to the survey elevations.

Table 9; summarizes the tested vertical accuracy result from a comparison of surveyed checkpoint to the elevation values present within the final DEM dataset.

Land Cover Category	# of Points	NVA – Non-vegetated Vertical Accuracy (RMSEz x 1.960)	VVA – Vegetated Vertical Accuracy (95 th percentile)
NVA	64	0.092	
VVA	48		0.114

 Table 9– DEM vertical accuracy summary

DEM datasets were tested to meet ASPRS Positional Accuracy Standards for Digital Geospatial Data (2014) for a 10 cm RMSEz Vertical Accuracy Class. Actual NVA accuracy was found to be RMSEz = 0.047 meters with a 0.092 meters accuracy at 95 % confidence level. Actual VVA accuracy tested 0.114 meters using checkpoints located in forested land cover categories at the 95th percentile, derived according to ASPRS guidelines, tested against the DEM. Based on the vertical accuracy testing conducted by ASI, the DEM dataset for the Block B Champaign County project satisfies the project's pre-defined vertical accuracy criteria.

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Appendix A: List of Delivered LAS File

w6330n1953.las w6330n1954.las w6330n1955.las w6330n1956.las w6340n1940.las w6340n1941.las w6340n1942.las w6340n1943.las w6340n1944.las w6340n1945.las w6340n1946.las w6340n1947.las w6340n1948.las w6340n1949.las w6340n1950.las w6340n1951.las w6340n1952.las w6340n1953.las w6340n1954.las w6340n1955.las w6340n1956.las w6350n1925.las w6350n1926.las w6350n1927.las w6350n1928.las w6350n1929.las w6350n1930.las w6350n1931.las w6350n1932.las w6350n1933.las w6350n1934.las w6350n1935.las w6350n1936.las w6350n1937.las w6350n1938.las w6350n1939.las w6350n1940.las w6350n1941.las w6350n1942.las w6350n1943.las w6350n1944.las w6350n1945.las w6350n1946.las w6350n1947.las w6350n1948.las w6350n1949.las w6350n1950.las w6350n1951.las

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w6350n1952.las w6350n1953.las w6350n1954.las w6350n1955.las w6350n1956.las w6350n1957.las w6360n1913.las w6360n1914.las w6360n1915.las w6360n1916.las w6360n1917.las w6360n1918.las w6360n1919.las w6360n1920.las w6360n1921.las w6360n1922.las w6360n1923.las w6360n1924.las w6360n1925.las w6360n1926.las w6360n1927.las w6360n1928.las w6360n1929.las w6360n1930.las w6360n1931.las w6360n1932.las w6360n1933.las w6360n1934.las w6360n1935.las w6360n1936.las w6360n1937.las w6360n1938.las w6360n1939.las w6360n1940.las w6360n1941.las w6360n1942.las w6360n1943.las w6360n1944.las w6360n1945.las w6360n1946.las w6360n1947.las w6360n1948.las w6360n1949.las w6360n1950.las w6360n1951.las w6360n1952.las w6360n1953.las w6360n1954.las w6360n1955.las w6360n1956.las w6360n1957.las

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w6370n1900.las w6370n1901.las w6370n1902.las w6370n1903.las w6370n1904.las w6370n1905.las w6370n1906.las w6370n1907.las w6370n1908.las w6370n1909.las w6370n1910.las w6370n1911.las w6370n1912.las w6370n1913.las w6370n1914.las w6370n1915.las w6370n1916.las w6370n1917.las w6370n1918.las w6370n1919.las w6370n1920.las w6370n1921.las w6370n1922.las w6370n1923.las w6370n1924.las w6370n1925.las w6370n1926.las w6370n1927.las w6370n1928.las w6370n1929.las w6370n1930.las w6370n1931.las w6370n1932.las w6370n1933.las w6370n1934.las w6370n1935.las w6370n1936.las w6370n1937.las w6370n1938.las w6370n1939.las w6370n1940.las w6370n1941.las w6370n1942.las w6370n1943.las w6370n1944.las w6370n1945.las w6370n1946.las w6370n1947.las w6370n1948.las w6370n1949.las w6370n1950.las Block 2 Champaign County, Illinois 07/01/2020 Page 36 of 111

w6370n1951.las w6370n1952.las w6370n1953.las w6370n1954.las w6370n1955.las w6370n1956.las w6370n1957.las w6380n1898.las w6380n1899.las w6380n1900.las w6380n1901.las w6380n1902.las w6380n1903.las w6380n1904.las w6380n1905.las w6380n1906.las w6380n1907.las w6380n1908.las w6380n1909.las w6380n1910.las w6380n1911.las w6380n1912.las w6380n1913.las w6380n1914.las w6380n1915.las w6380n1916.las w6380n1917.las w6380n1918.las w6380n1919.las w6380n1920.las w6380n1921.las w6380n1922.las w6380n1923.las w6380n1924.las w6380n1925.las w6380n1926.las w6380n1927.las w6380n1928.las w6380n1929.las w6380n1930.las w6380n1931.las w6380n1932.las w6380n1933.las w6380n1934.las w6380n1935.las w6380n1936.las w6380n1937.las w6380n1938.las w6380n1939.las w6380n1940.las w6380n1941.las

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w6380n1942.las w6380n1943.las w6380n1944.las w6380n1945.las w6380n1946.las w6380n1947.las w6380n1948.las w6380n1949.las w6380n1950.las w6380n1951.las w6380n1952.las w6380n1953.las w6380n1954.las w6380n1955.las w6380n1956.las w6380n1957.las w6390n1898.las w6390n1899.las w6390n1900.las w6390n1901.las w6390n1902.las w6390n1903.las w6390n1904.las w6390n1905.las w6390n1906.las w6390n1907.las w6390n1908.las w6390n1909.las w6390n1910.las w6390n1911.las w6390n1912.las w6390n1913.las w6390n1914.las w6390n1915.las w6390n1916.las w6390n1917.las w6390n1918.las w6390n1919.las w6390n1920.las w6390n1921.las w6390n1922.las w6390n1923.las w6390n1924.las w6390n1925.las w6390n1926.las w6390n1927.las w6390n1928.las w6390n1929.las w6390n1930.las w6390n1931.las w6390n1932.las Block 2 Champaign County, Illinois 07/01/2020 Page 38 of 111

w6390n1933.las w6390n1934.las w6390n1935.las w6390n1936.las w6390n1937.las w6390n1938.las w6390n1939.las w6390n1940.las w6390n1941.las w6390n1942.las w6390n1943.las w6390n1944.las w6390n1945.las w6390n1946.las w6390n1947.las w6390n1948.las w6390n1949.las w6390n1950.las w6390n1951.las w6390n1952.las w6390n1953.las w6390n1954.las w6390n1955.las w6390n1956.las w6390n1957.las w6400n1898.las w6400n1899.las w6400n1900.las w6400n1901.las w6400n1902.las w6400n1903.las w6400n1904.las w6400n1905.las w6400n1906.las w6400n1907.las w6400n1908.las w6400n1909.las w6400n1910.las w6400n1911.las w6400n1912.las w6400n1913.las w6400n1914.las w6400n1915.las w6400n1916.las w6400n1917.las w6400n1918.las w6400n1919.las w6400n1920.las w6400n1921.las w6400n1922.las w6400n1923.las

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w6500n1941.las w6500n1942.las w6500n1943.las w6500n1944.las w6500n1945.las w6500n1946.las w6500n1947.las w6500n1948.las w6500n1949.las w6500n1950.las w6500n1951.las w6500n1952.las w6500n1953.las w6500n1954.las w6500n1955.las w6500n1956.las w6500n1957.las w6500n1958.las w6510n1899.las w6510n1900.las w6510n1901.las w6510n1902.las w6510n1903.las w6510n1904.las w6510n1905.las w6510n1906.las w6510n1907.las w6510n1908.las w6510n1909.las w6510n1910.las w6510n1911.las w6510n1912.las w6510n1913.las w6510n1914.las w6510n1915.las w6510n1916.las w6510n1917.las w6510n1918.las w6510n1919.las w6510n1920.las w6510n1921.las w6510n1922.las w6510n1923.las w6510n1924.las w6510n1925.las w6510n1926.las w6510n1927.las w6510n1928.las w6510n1929.las w6510n1930.las w6510n1931.las

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w6520n1923.las w6520n1924.las w6520n1925.las w6520n1926.las w6520n1927.las w6520n1928.las w6520n1929.las w6520n1930.las w6520n1931.las w6520n1932.las w6520n1933.las w6520n1934.las w6520n1935.las w6520n1936.las w6520n1937.las w6520n1938.las w6520n1939.las w6520n1940.las w6520n1941.las w6520n1942.las w6520n1943.las w6520n1944.las w6520n1945.las w6520n1946.las w6520n1947.las w6520n1948.las w6520n1949.las w6520n1950.las w6520n1951.las w6520n1952.las w6520n1953.las w6520n1954.las w6520n1955.las w6520n1956.las w6520n1957.las w6520n1958.las w6530n1899.las w6530n1900.las w6530n1901.las w6530n1902.las w6530n1903.las w6530n1904.las w6530n1905.las w6530n1906.las w6530n1907.las w6530n1908.las w6530n1909.las w6530n1910.las w6530n1911.las w6530n1912.las w6530n1913.las

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w6540n1905.las w6540n1906.las w6540n1907.las w6540n1908.las w6540n1909.las w6540n1910.las w6540n1911.las w6540n1912.las w6540n1913.las w6540n1914.las w6540n1915.las w6540n1916.las w6540n1917.las w6540n1918.las w6540n1919.las w6540n1920.las w6540n1921.las w6540n1922.las w6540n1923.las w6540n1924.las w6540n1925.las w6540n1926.las w6540n1927.las w6540n1928.las w6540n1929.las w6540n1930.las w6540n1931.las w6540n1932.las w6540n1933.las w6540n1934.las w6540n1935.las w6540n1936.las w6540n1937.las w6540n1938.las w6540n1939.las w6540n1940.las w6540n1941.las w6540n1942.las w6540n1943.las w6540n1944.las w6540n1945.las w6540n1946.las w6540n1947.las w6540n1948.las w6540n1949.las w6540n1950.las w6540n1951.las w6540n1952.las w6540n1953.las w6540n1954.las w6540n1955.las

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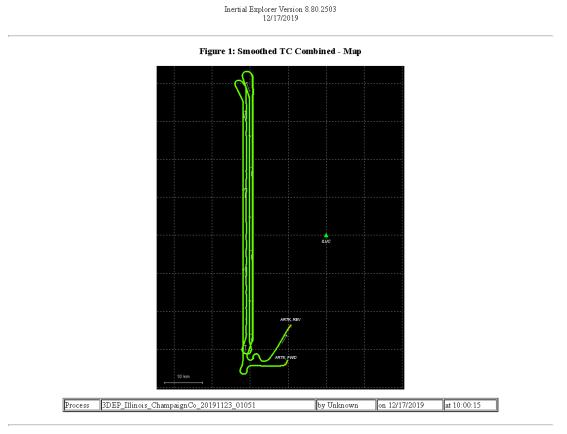
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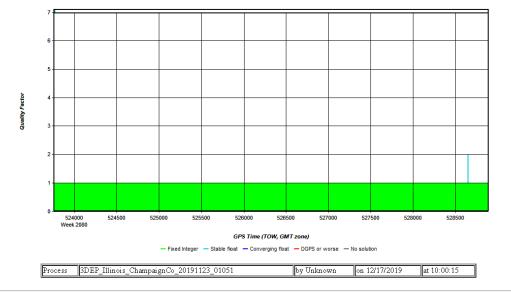
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Appendix B: Mission GPS and IMU Processing Report



Output Results for 3DEP_Illinois_ChampaignCo_20191123_010512

Figure 2: 3DEP_Illinois_ChampaignCo_20191123_010512 [Smoothed TC Combined] - Quality Factor Plot



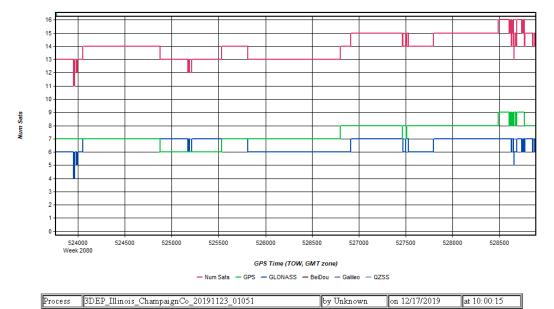


Figure 3: 3DEP_Illinois_ChampaignCo_20191123_010512 [Smoothed TC Combined] - Number of Satellites Line Plot



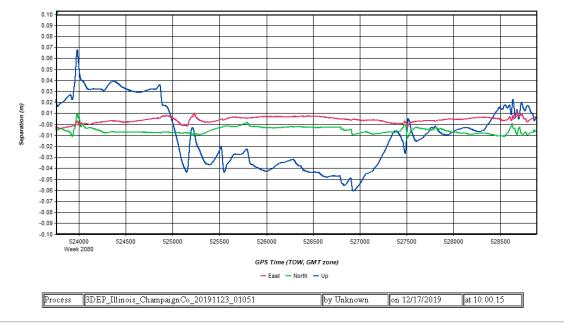
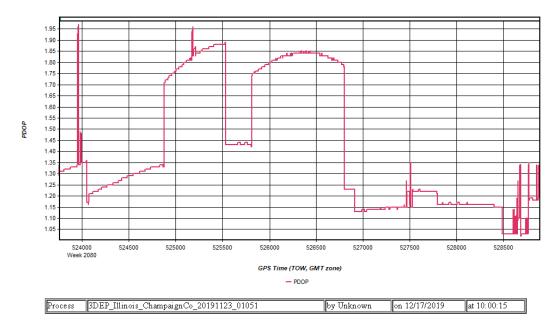


Figure 5: 3DEP_Illinois_ChampaignCo_20191123_010512 [Smoothed TC Combined] - PDOP Plot



Output Results for 3DEP_Illinois_ChampaignCo_20191124_225026

Inertial Explorer Version 8.80.2503 12/17/2019

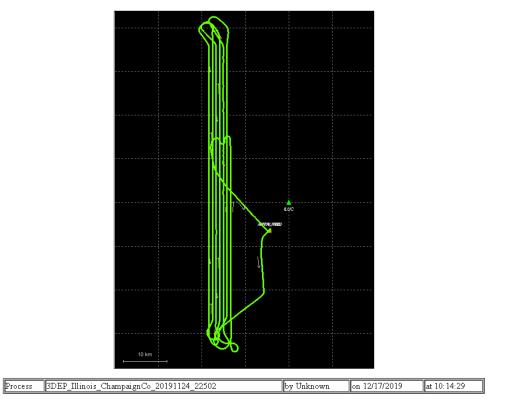


Figure 1: Smoothed TC Combined - Map

Object 3DEP_Illinois_ChampaignCo_20191124_225026 [Smoothed TC Combined] - Quality Factor Plot failed--NULL bitmap handle

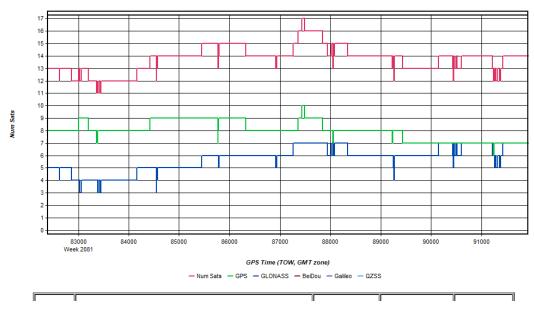
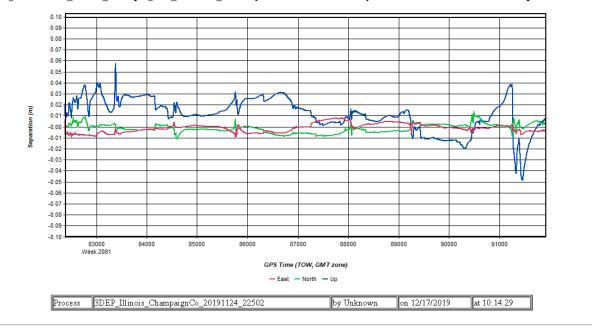


Figure 2: 3DEP_Illinois_ChampaignCo_20191124_225026 [Smoothed TC Combined] - Number of Satellites Line Plot

Process 3DEP_Illinois_ChampaignCo_20191124_22502

by Unknown on 12/17/2019 at 10:14:29





2.0 1.9 1.8 1.7 1.6 PDOP 1.5 1.4 1.3 1.2 1.1 1.0 0.9 83000 Week 2081 85000 90000 84000 86000 87000 88000 89000 91000 GPS Time (TOW, GMT zone) - PDOP Process 3DEP_Illinois_ChampaignCo_20191124_22502 by Unknown on 12/17/2019 at 10:14:29

Figure 4: 3DEP_Illinois_ChampaignCo_20191124_225026 [Smoothed TC Combined] - PDOP Plot

Output Results for 3DEP_Illinois_ChampaignCo_20191125_150902

Inertial Explorer Version 8.80.2503 12/17/2019



Figure 1: Smoothed TC Combined - Map

Object 3DEP_Illinois_ChampaignCo_20191125_150902 [Smoothed TC Combined] - Quality Factor Plot failed--NULL bitmap handle

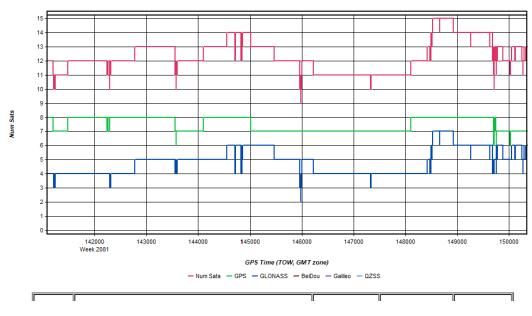


Figure 2: 3DEP_Illinois_ChampaignCo_20191125_150902 [Smoothed TC Combined] - Number of Satellites Line Plot

Process 3DEP_Illinois_ChampaignCo_20191125_15090

by Unknown on 12/17/2019 at 11:37:46

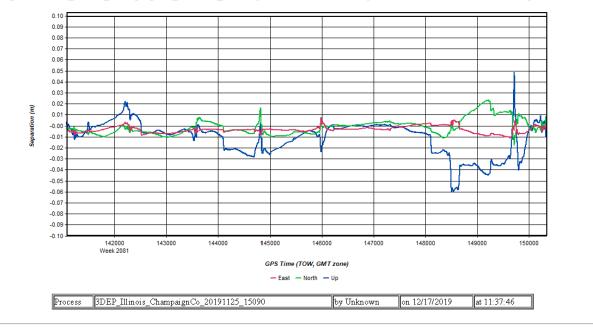


Figure 3: 3DEP_Illinois_ChampaignCo_20191125_150902 [Smoothed TC Combined] - Forward/Reverse or Combined Separation Plot



Figure 4: 3DEP_Illinois_ChampaignCo_20191125_150902 [Smoothed TC Combined] - PDOP Plot

Output Results for 3DEP_Illinois_ChampaignCo_20191125_184223

Inertial Explorer Version 8.80.2503 12/17/2019

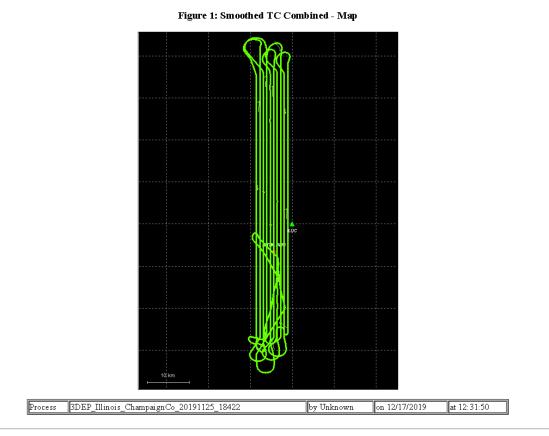
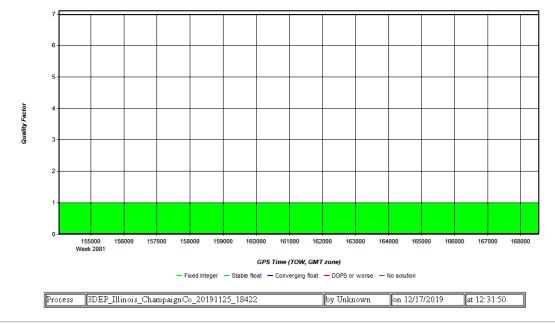


Figure 2: 3DEP_Illinois_ChampaignCo_20191125_184223 [Smoothed TC Combined] - Quality Factor Plot



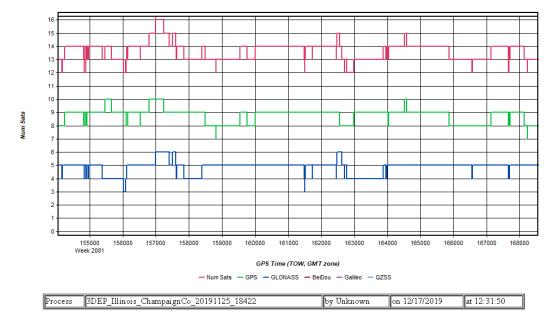


Figure 3: 3DEP_Illinois_ChampaignCo_20191125_184223 [Smoothed TC Combined] - Number of Satellites Line Plot



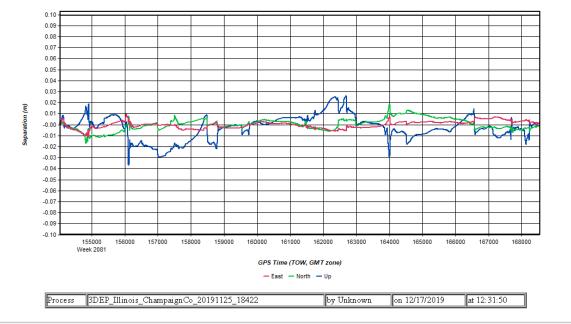
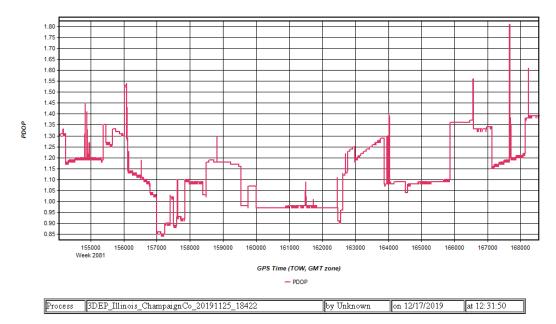


Figure 5: 3DEP_Illinois_ChampaignCo_20191125_184223 [Smoothed TC Combined] - PDOP Plot



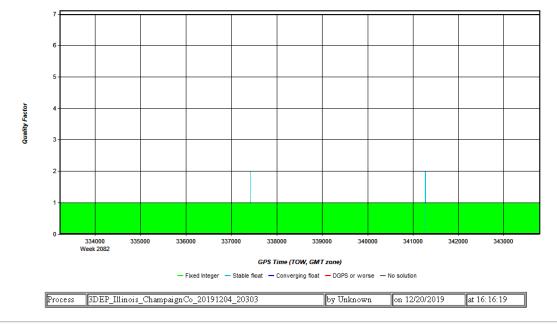
Output Results for 3DEP_Illinois_ChampaignCo_20191204_203038

Inertial Explorer Version 8.80.2503 12/20/2019



Figure 1: Smoothed TC Combined - Map

Figure 2: 3DEP_Illinois_ChampaignCo_20191204_203038 [Smoothed TC Combined] - Quality Factor Plot



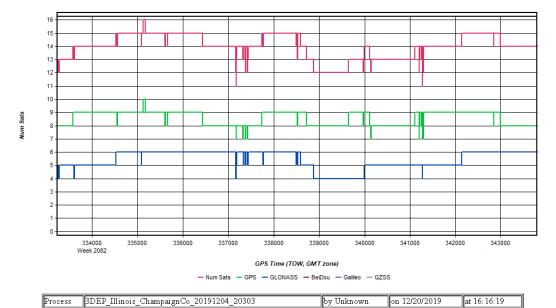


Figure 3: 3DEP_Illinois_ChampaignCo_20191204_203038 [Smoothed TC Combined] - Number of Satellites Line Plot



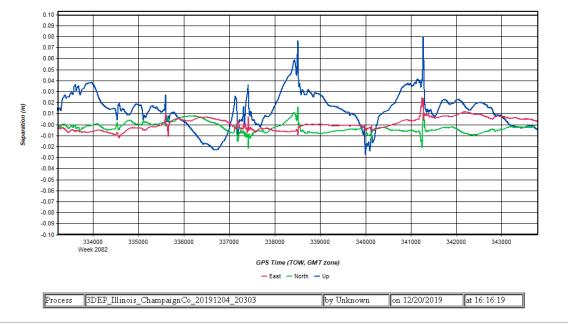
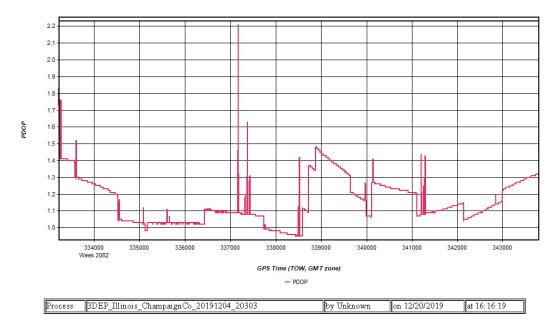


Figure 5: 3DEP_Illinois_ChampaignCo_20191204_203038 [Smoothed TC Combined] - PDOP Plot



Output Results for 3DEP_Illinois_ChampaignCo_20191205_001845

Inertial Explorer Version 8.80.2503 12/20/2019

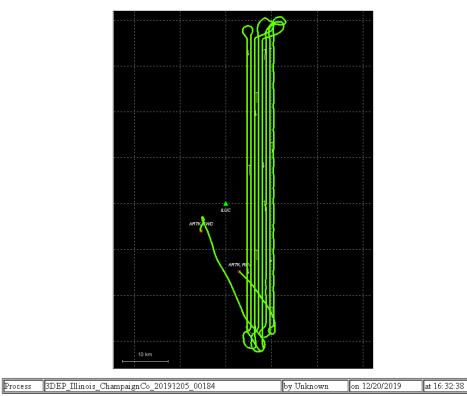
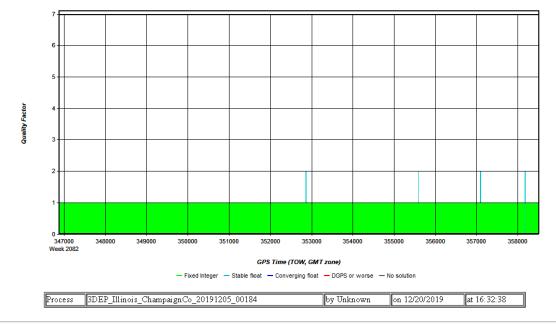


Figure 1: Smoothed TC Combined - Map

Figure 2: 3DEP_Illinois_ChampaignCo_20191205_001845 [Smoothed TC Combined] - Quality Factor Plot



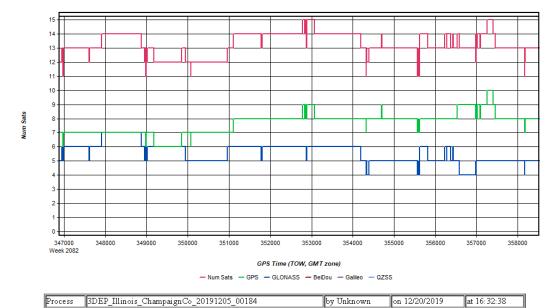


Figure 3: 3DEP_Illinois_ChampaignCo_20191205_001845 [Smoothed TC Combined] - Number of Satellites Line Plot



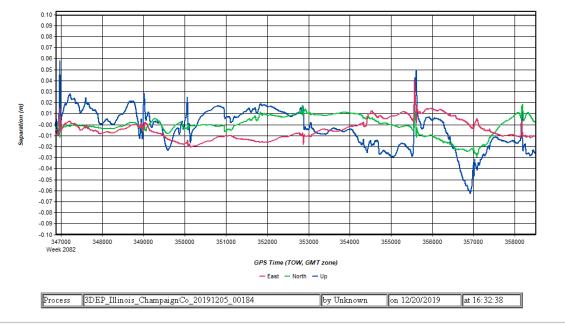
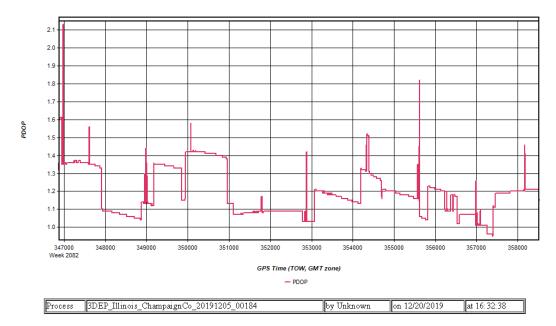


Figure 5: 3DEP_Illinois_ChampaignCo_20191205_001845 [Smoothed TC Combined] - PDOP Plot



Process

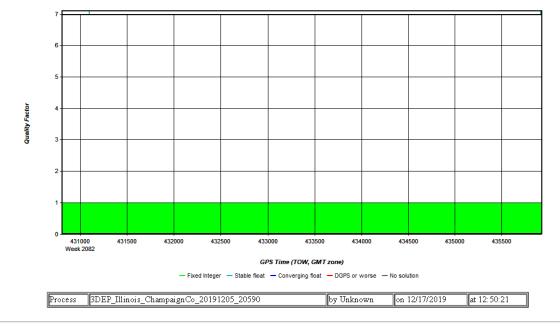
Output Results for 3DEP_Illinois_ChampaignCo_20191205_205908

Inertial Explorer Version 8.80.2503 12/17/2019

 BDEP_Illinois_ChampagnCo_20191205_20590
 by Unknown
 on 12/17/2019

Figure 2: 3DEP_Illinois_ChampaignCo_20191205_205908 [Smoothed TC Combined] - Quality Factor Plot

at 12:50:21



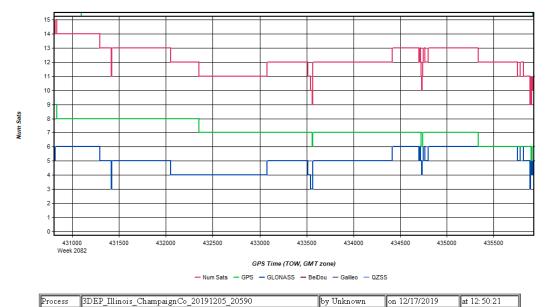


Figure 3: 3DEP_Illinois_ChampaignCo_20191205_205908 [Smoothed TC Combined] - Number of Satellites Line Plot



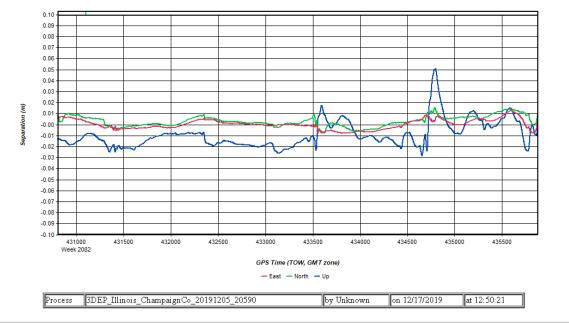
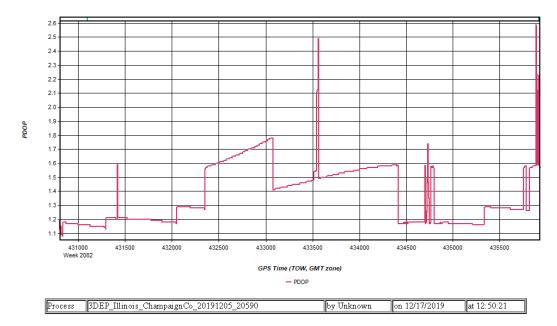


Figure 5: 3DEP_Illinois_ChampaignCo_20191205_205908 [Smoothed TC Combined] - PDOP Plot



Output Results for 3DEP_Illinois_ChampaignCo_20191206_024156

Inertial Explorer Version 8.80.2503 12/17/2019

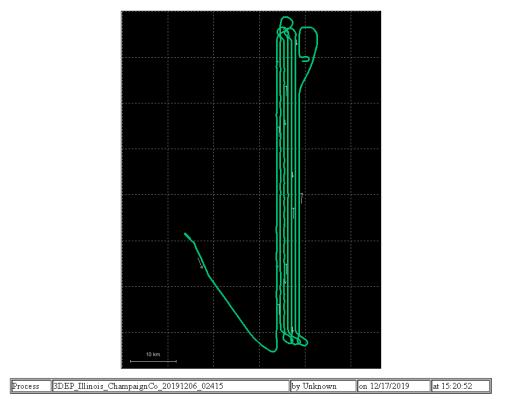
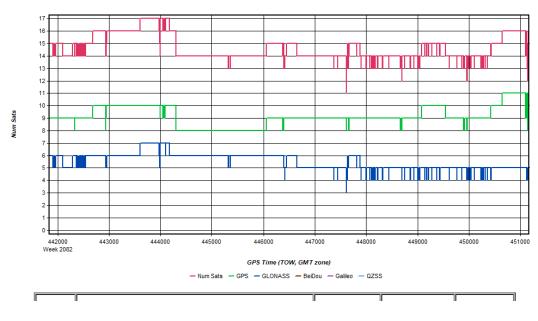
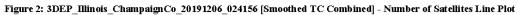


Figure 1: Smoothed TC Combined - Map

Object 3DEP_Illinois_ChampaignCo_20191206_024156 [Smoothed TC Combined] - Quality Factor Plot failed--NULL bitmap handle





Process 3DEP_Illinois_ChampaignCo_20191206_02415

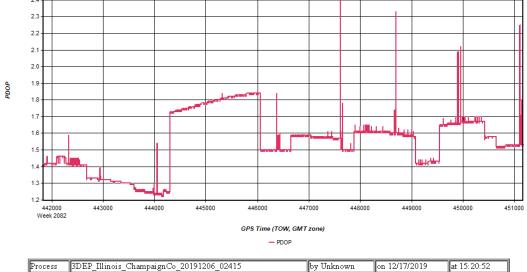
by Unknown on 12/17/2019 at 15:20:52





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Figure 4: 3DEP_Illinois_ChampaignCo_20191206_024156 [Smoothed TC Combined] - PDOP Plot



Output Results for 3DEP_Illinois_ChampaignCo_20191206_221016

Inertial Explorer Version 8.80.2503 12/17/2019

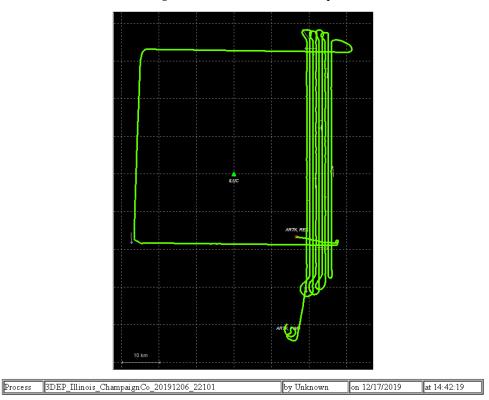
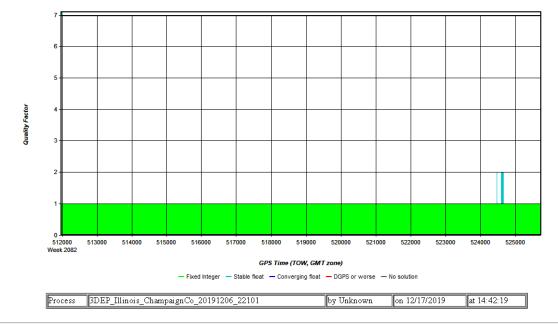


Figure 1: Smoothed TC Combined - Map

Figure 2: 3DEP_Illinois_ChampaignCo_20191206_221016 [Smoothed TC Combined] - Quality Factor Plot



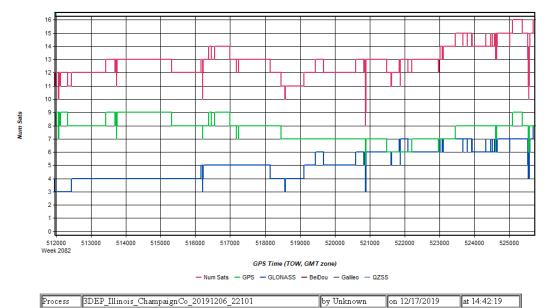


Figure 3: 3DEP_Illinois_ChampaignCo_20191206_221016 [Smoothed TC Combined] - Number of Satellites Line Plot





Figure 5: 3DEP_Illinois_ChampaignCo_20191206_221016 [Smoothed TC Combined] - PDOP Plot

