

General Information

Mission Information

Project name	220507_C_5060495_nad2011_FINAL
Processing date	2022-05-20 21:14:41
Mission date	2022-05-07 22:24:23
Mission duration	02:56:22.000
Processing mode	IN-Fusion PP-RTX

Rover Hardware Information

Product	POS AV 610 VER6 HW2.5-12
Serial number	S/N13003
IMU type	57
Receiver type	BD982
Antenna type	AV39

Project File List

Rover Data Files

File name	File type
survey3.pos	POS Data

Input Files

File Name	File Type
Ephm1270.22g	GLONASS Broadcast Ephemeris
Ephm1270.22n	GPS Broadcast Ephemeris
Ephm1280.22g	GLONASS Broadcast Ephemeris
Ephm1280.22n	GPS Broadcast Ephemeris
igs22085.sp3	GPS Precise Ephemeris
igs22086.sp3	GPS Precise Ephemeris

Output Files

Filename	File type
sbet_220507_C_5060495_nad2011_FINAL.out	SBET Trajectory File

Rover Data Summary

First raw data file	survey3.pos		
Last raw data file	survey3.pos		
Start GPS week	2208		
Start time	599062.100 (05/07/2022 22:24:22)		
End time	4845.086 (05/08/2022 01:20:45)		
Start of fine alignment	599649.083 (05/07/2022 22:34:09)		
Available subsystems	Primary GNSS, IMU		
POS Event Input	None		
Correction data	None		
IMU Installation Lever Arms & Mounting Angles			
Reference to IMU lever arm (m)	0.000	0.000	0.000
Reference to IMU mounting angles (deg)	0.000	0.000	180.000
Reference to Primary GNSS lever arm (m)	-0.399	-0.382	-1.125
Reference to Primary GNSS lever arm std dev (m)	-1.000		
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

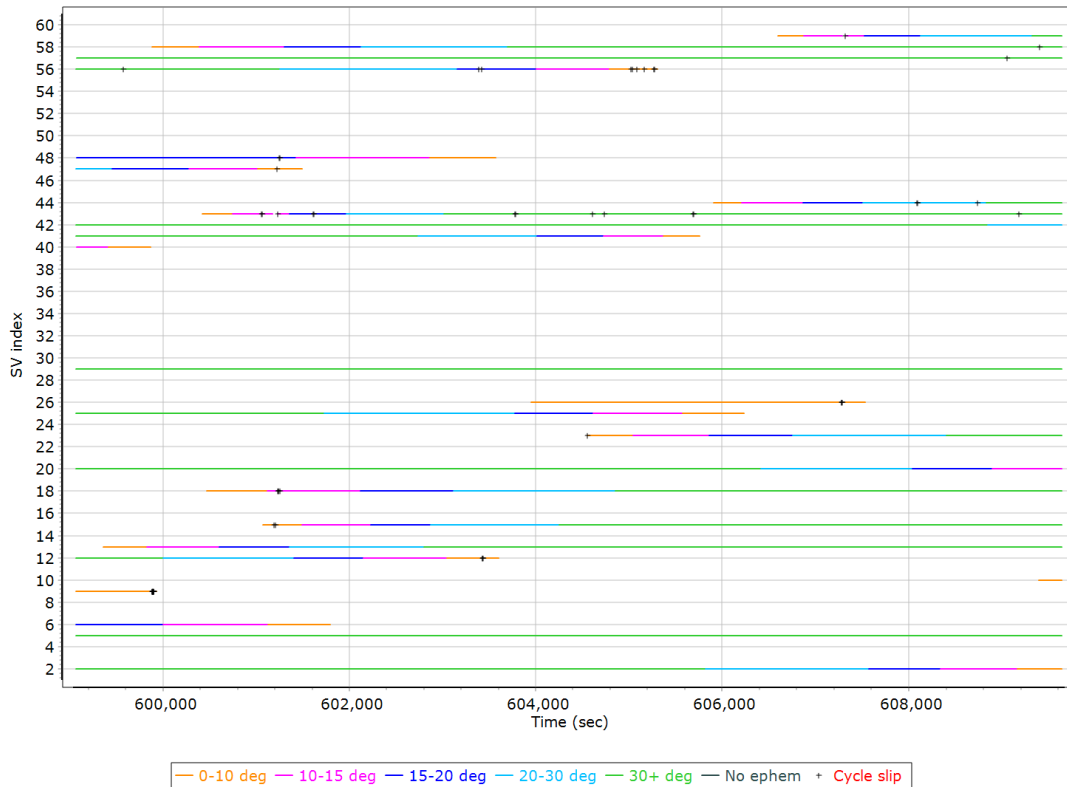
Rover Data QC

Raw IMU Import QC Summary

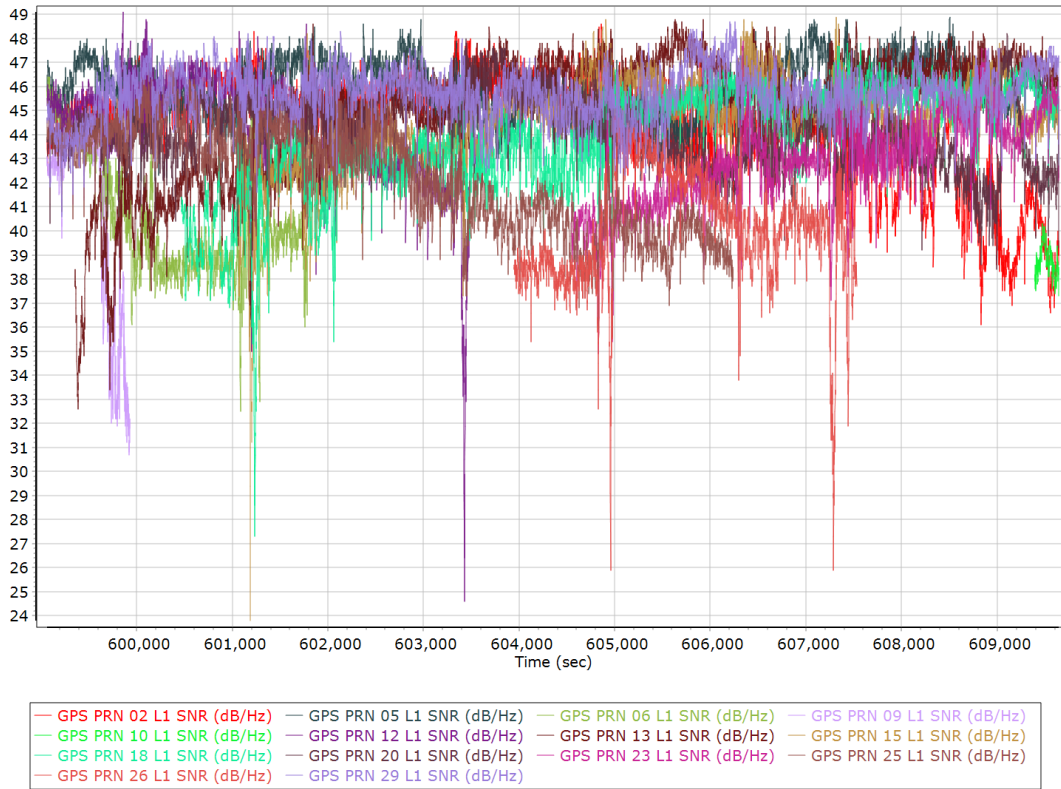
IMU data input file	imu_Mission 1.dat
IMU data check log file	imudt_220507_C_5060495_nad2011_FINAL.log
IMU Records Processed	2116351
Termination Status	Normal
IMU Anomalies	0

Primary Observables & Satellite Data

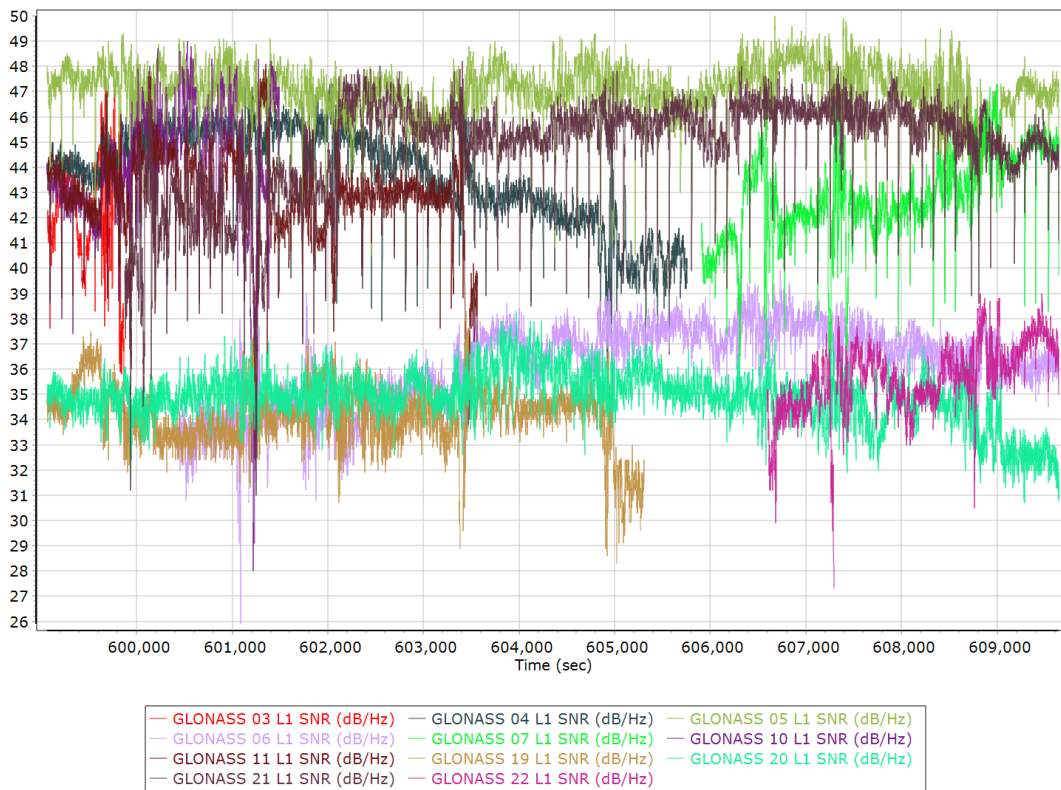
GPS/GLONASS L1 Satellite Lock/Elevation



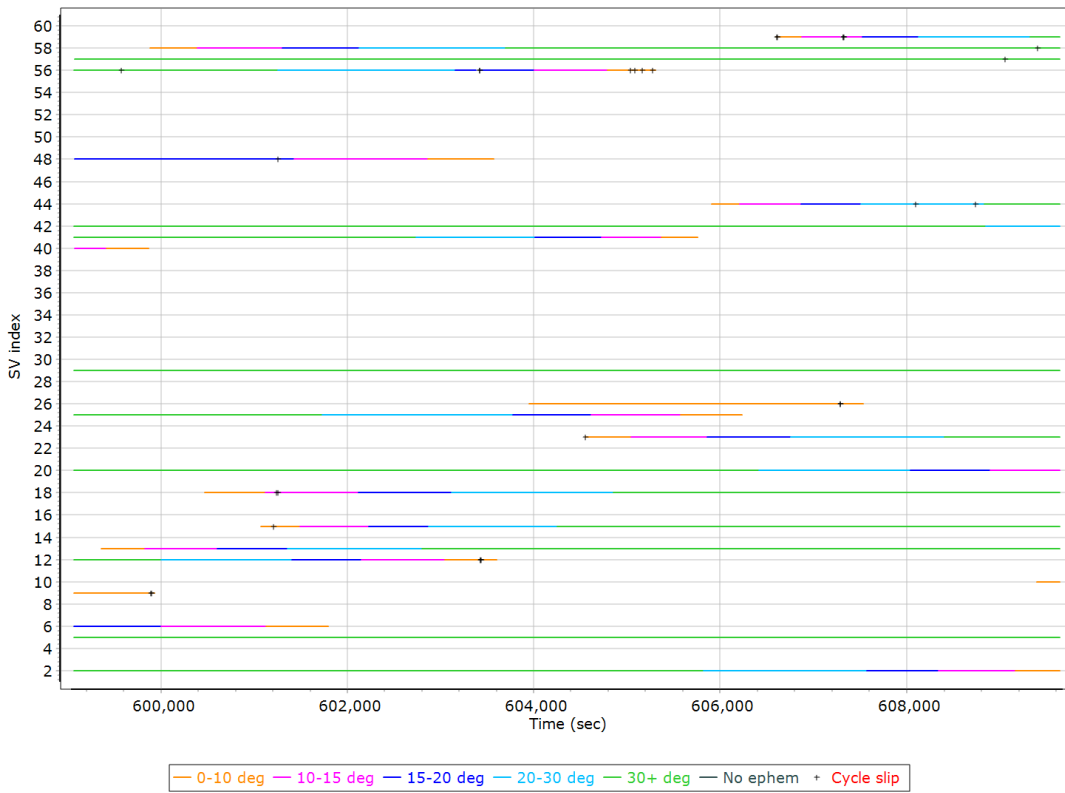
GPS L1 SNR



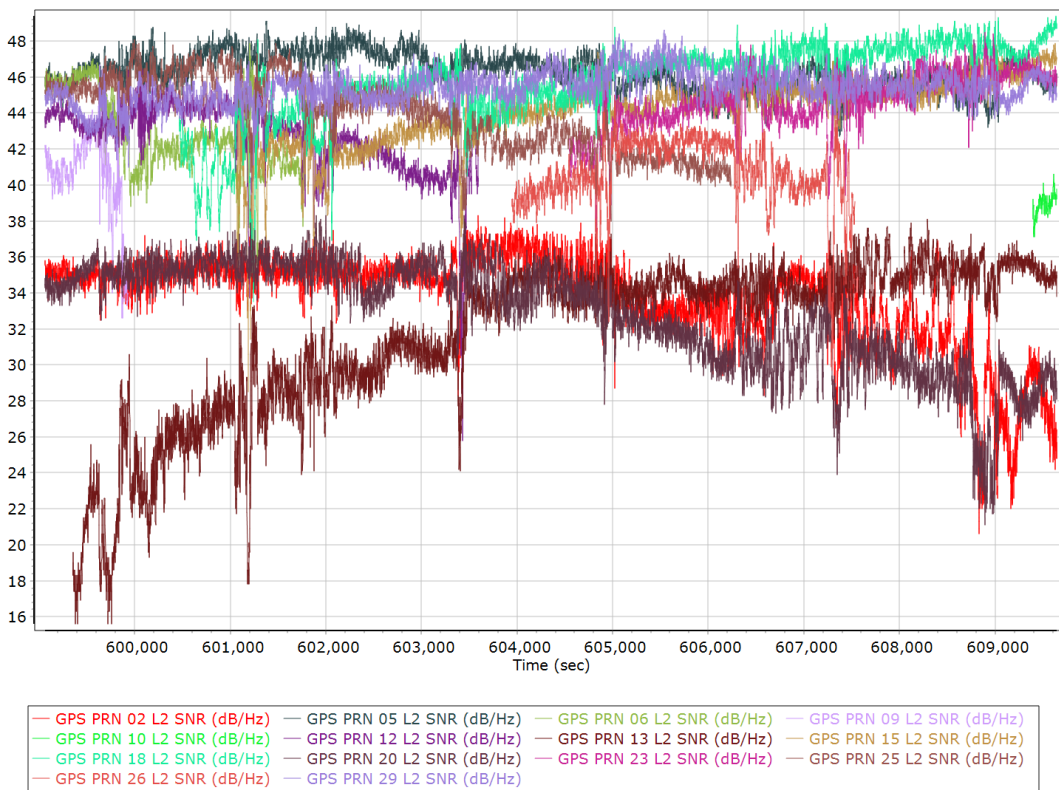
GLONASS L1 SNR



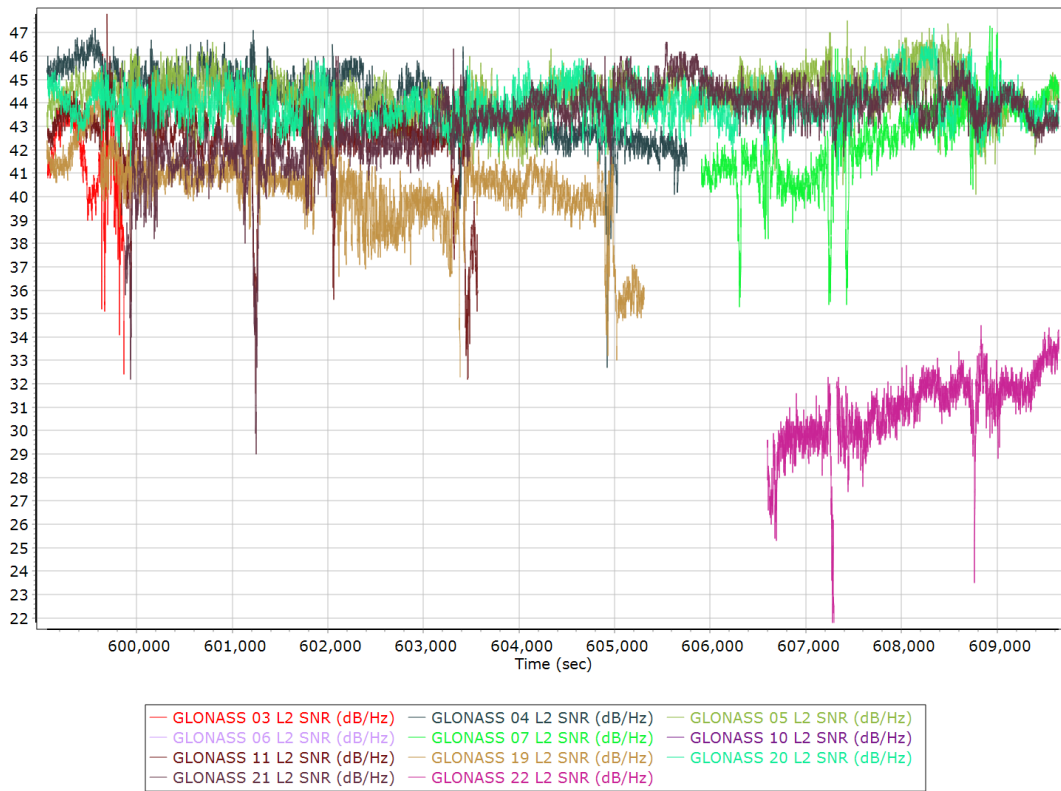
GPS/GLONASS L2 Satellite Lock/Elevation



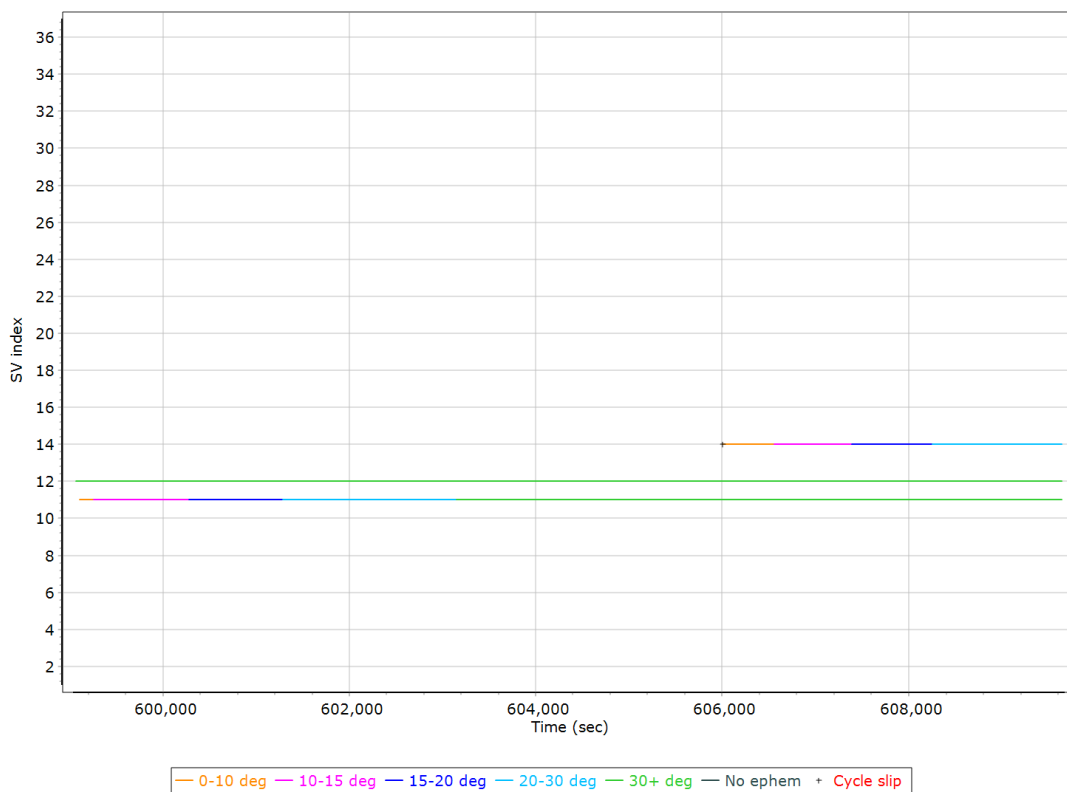
GPS L2 SNR



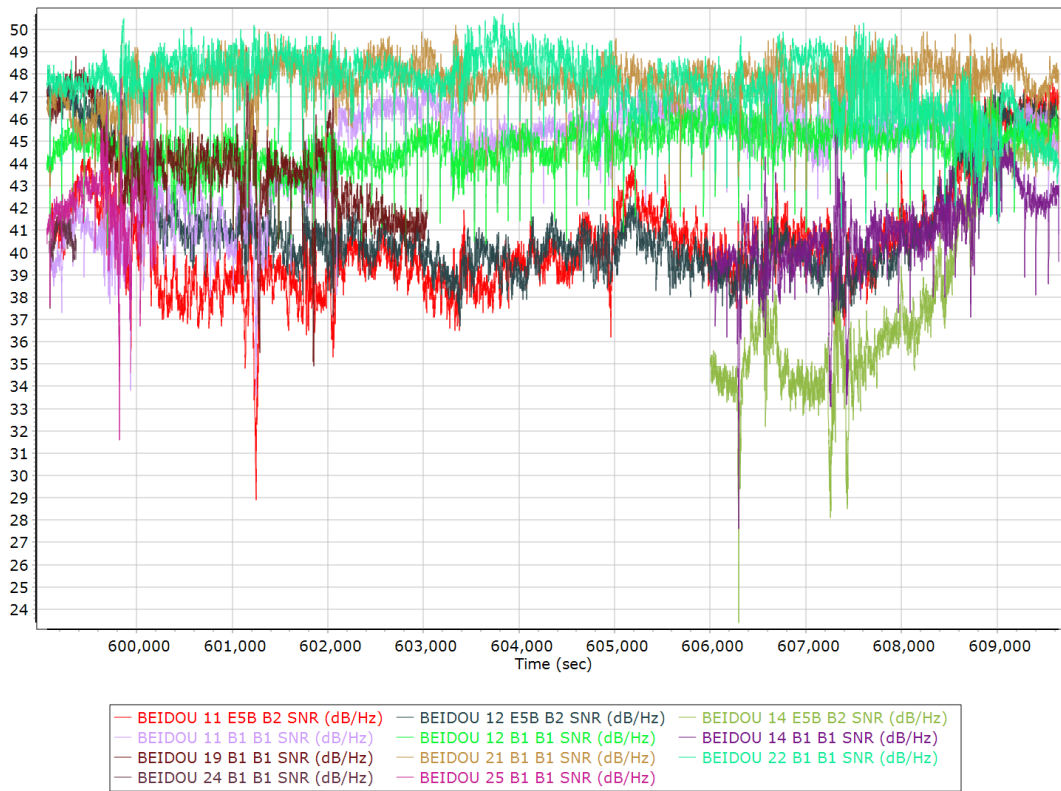
GLONASS L2 SNR



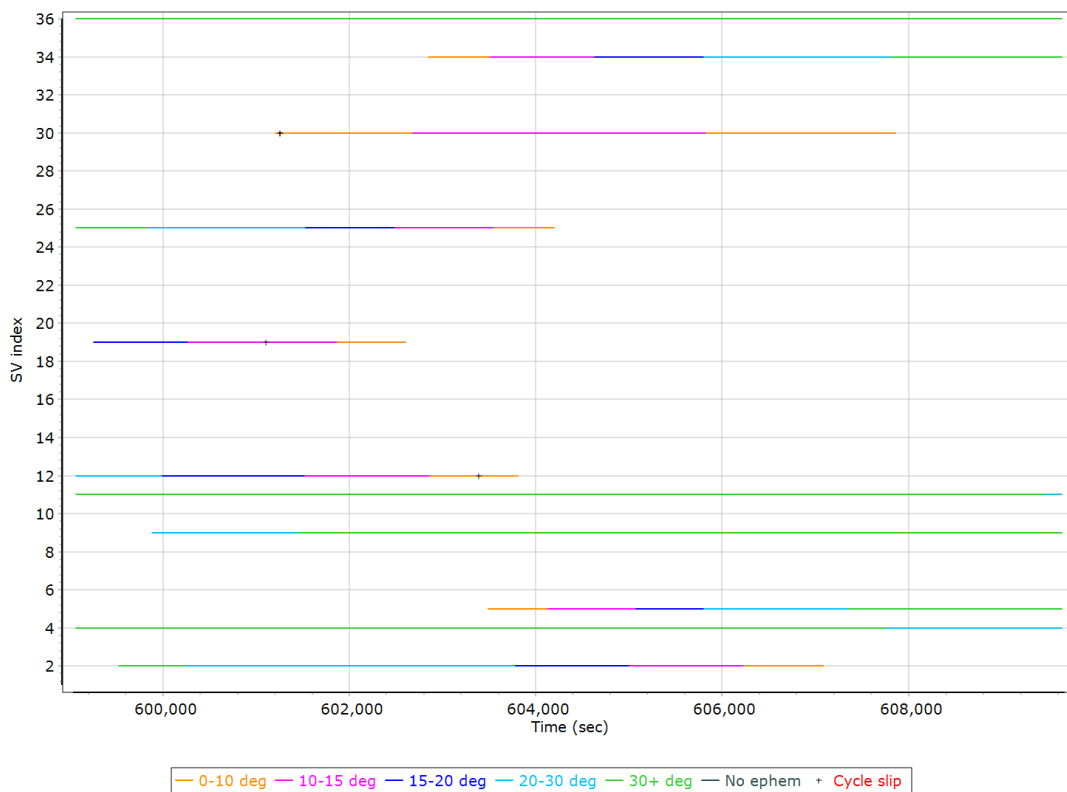
BEIDOU Satellite Lock/Elevation



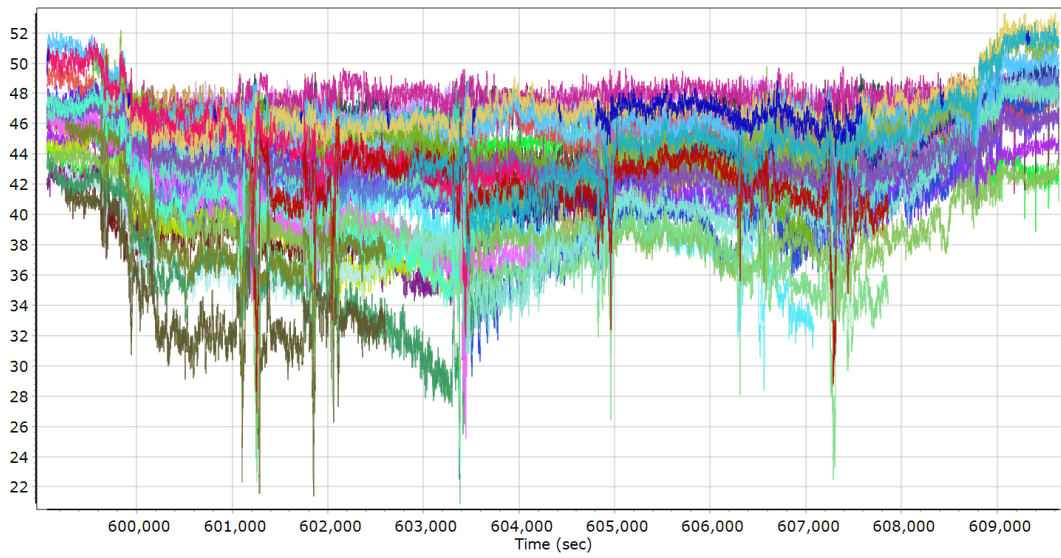
BEIDOU SNR



GALILEO Satellite Lock/Elevation



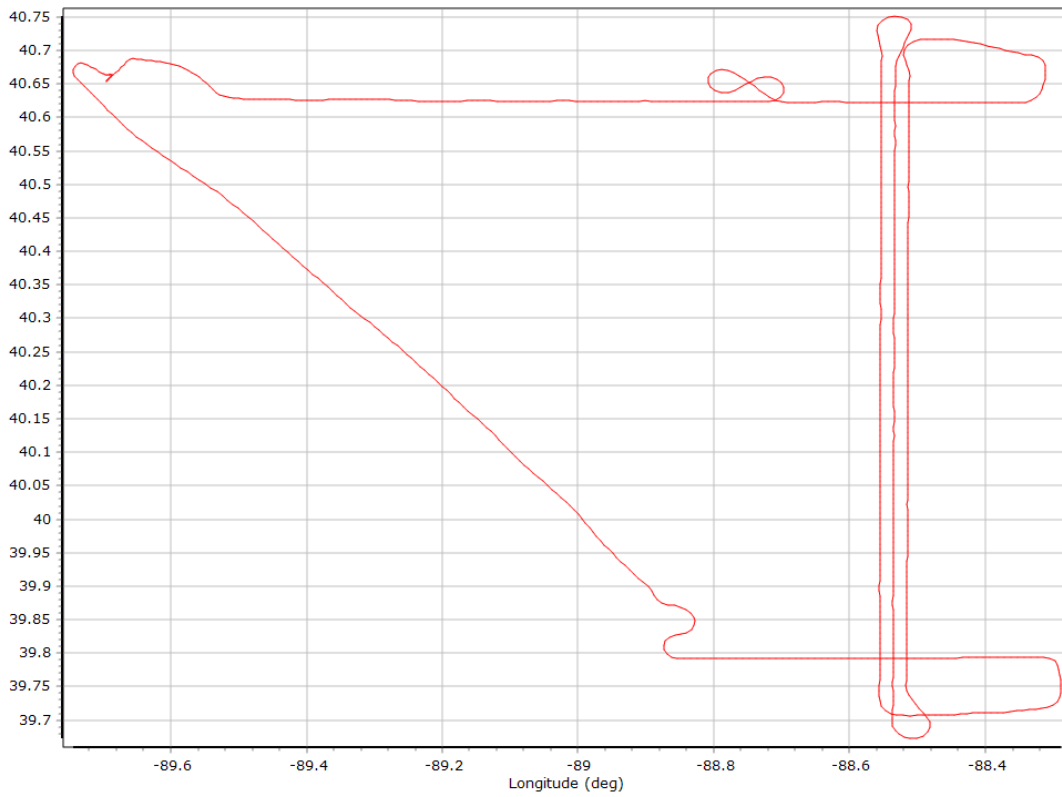
GALILEO SNR



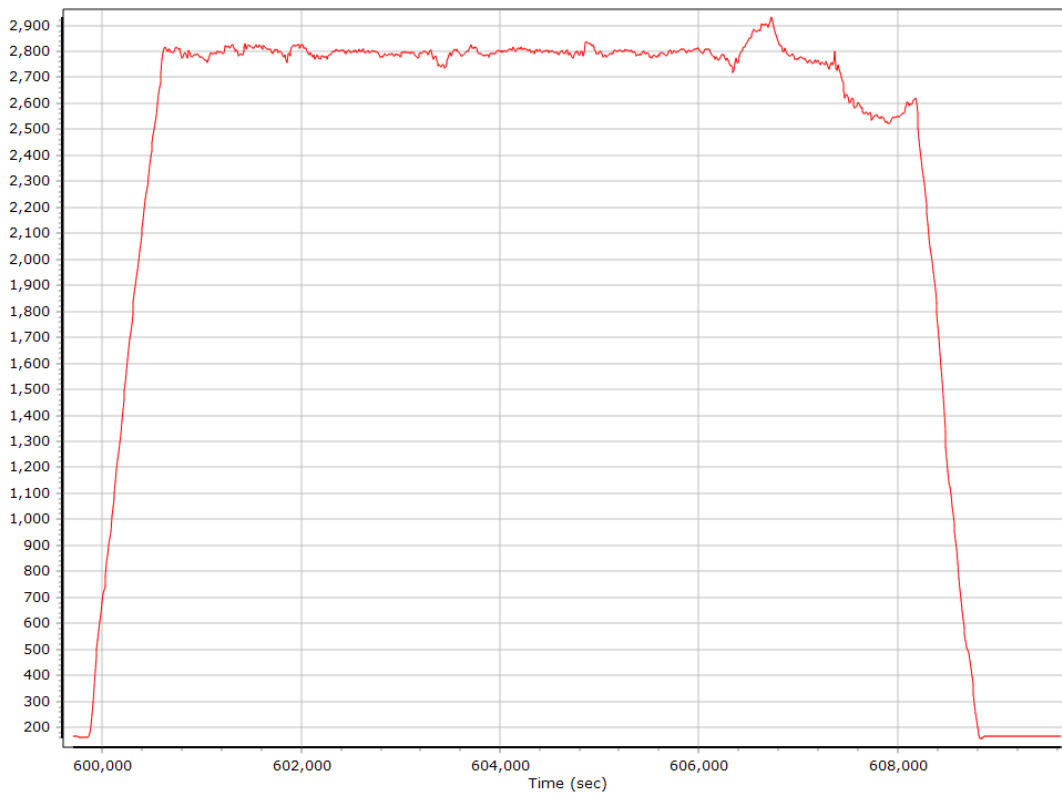
- | | |
|---|---|
| — GALILEO 02 L1 BOC_1_1_DP_MBOC SNR (dB/Hz) | — GALILEO 04 L1 BOC_1_1_DP_MBOC SNR (dB/Hz) |
| — GALILEO 05 L1 BOC_1_1_DP_MBOC SNR (dB/Hz) | — GALILEO 09 L1 BOC_1_1_DP_MBOC SNR (dB/Hz) |
| — GALILEO 11 L1 BOC_1_1_DP_MBOC SNR (dB/Hz) | — GALILEO 12 L1 BOC_1_1_DP_MBOC SNR (dB/Hz) |
| — GALILEO 19 L1 BOC_1_1_DP_MBOC SNR (dB/Hz) | — GALILEO 25 L1 BOC_1_1_DP_MBOC SNR (dB/Hz) |
| — GALILEO 30 L1 BOC_1_1_DP_MBOC SNR (dB/Hz) | — GALILEO 34 L1 BOC_1_1_DP_MBOC SNR (dB/Hz) |
| — GALILEO 36 L1 BOC_1_1_DP_MBOC SNR (dB/Hz) | — GALILEO 02 L5E5A BPSK10_PD SNR (dB/Hz) |
| — GALILEO 04 L5E5A BPSK10_PD SNR (dB/Hz) | — GALILEO 05 L5E5A BPSK10_PD SNR (dB/Hz) |
| — GALILEO 09 L5E5A BPSK10_PD SNR (dB/Hz) | — GALILEO 11 L5E5A BPSK10_PD SNR (dB/Hz) |
| — GALILEO 12 L5E5A BPSK10_PD SNR (dB/Hz) | — GALILEO 19 L5E5A BPSK10_PD SNR (dB/Hz) |
| — GALILEO 25 L5E5A BPSK10_PD SNR (dB/Hz) | — GALILEO 30 L5E5A BPSK10_PD SNR (dB/Hz) |

Smoothed Trajectory Information

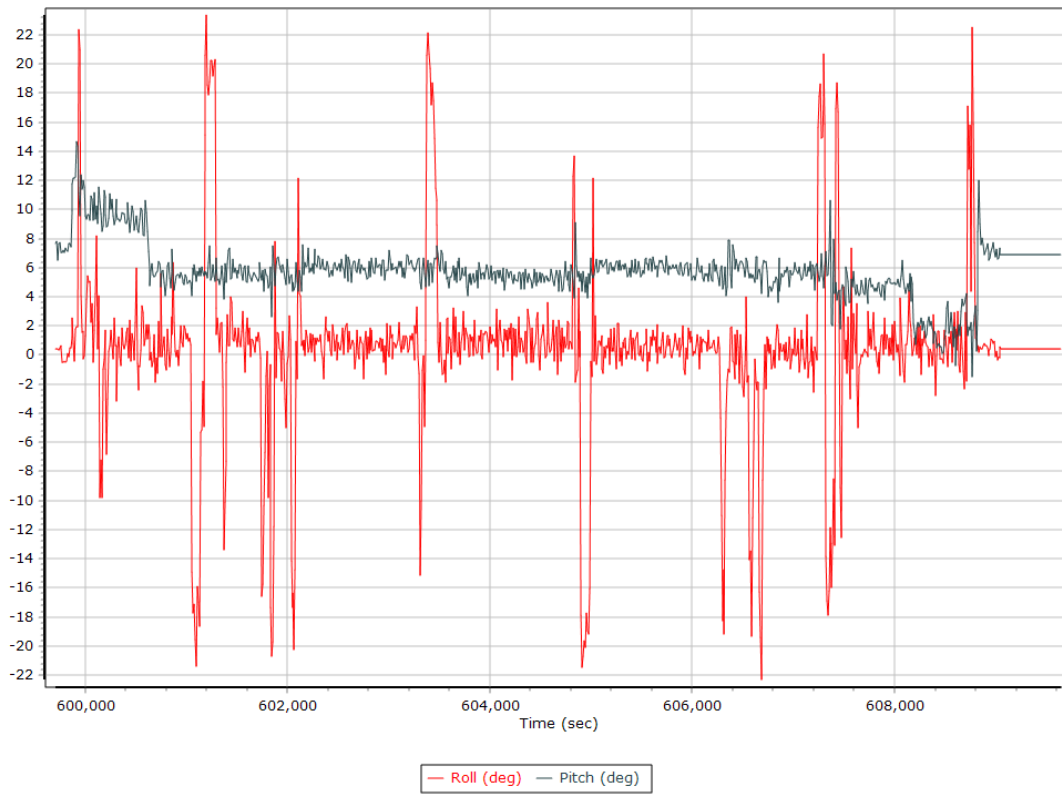
Top View



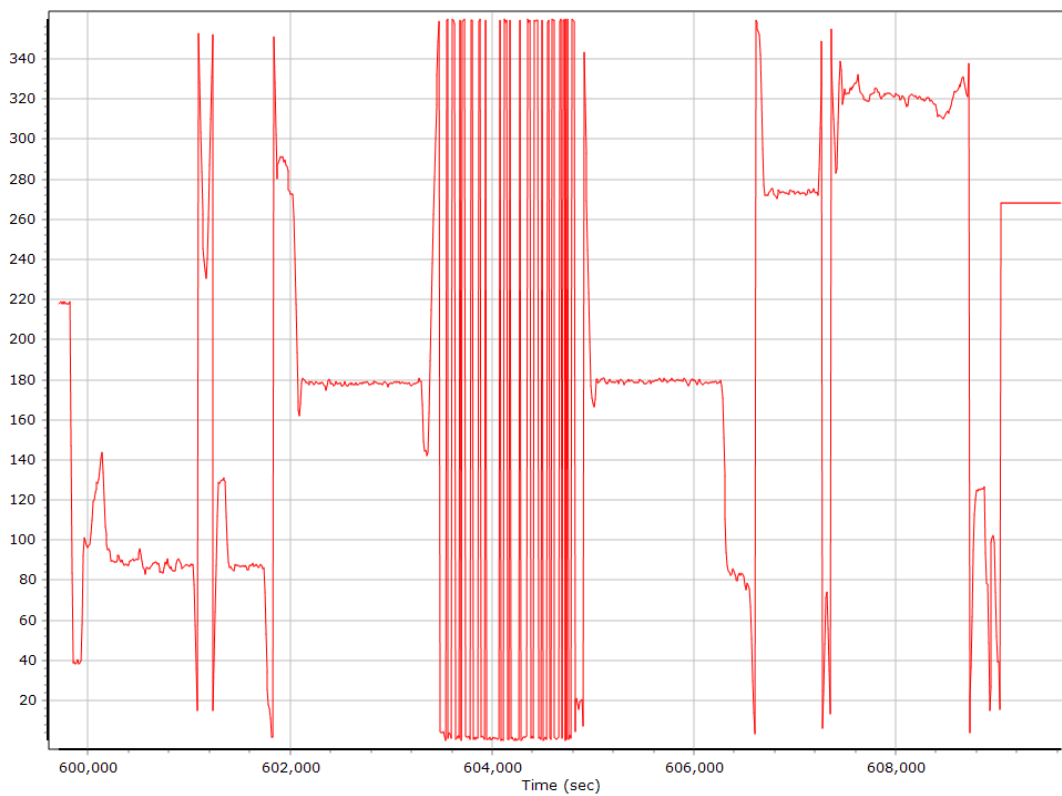
Altitude



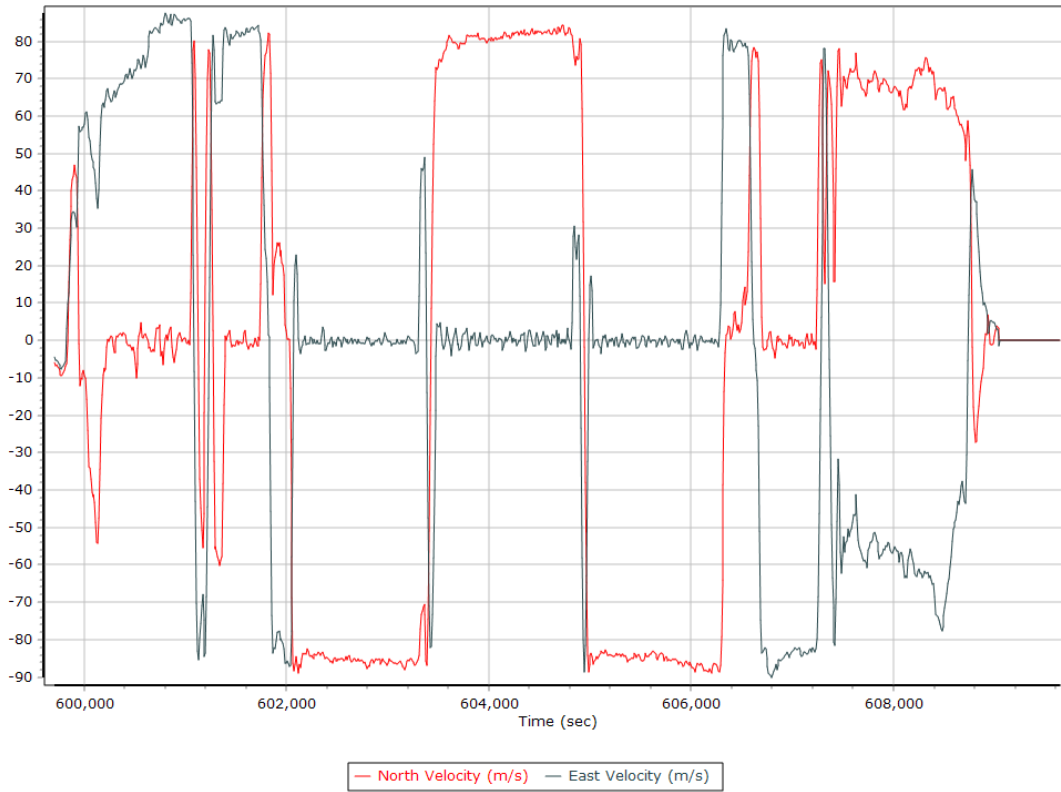
Roll/Pitch



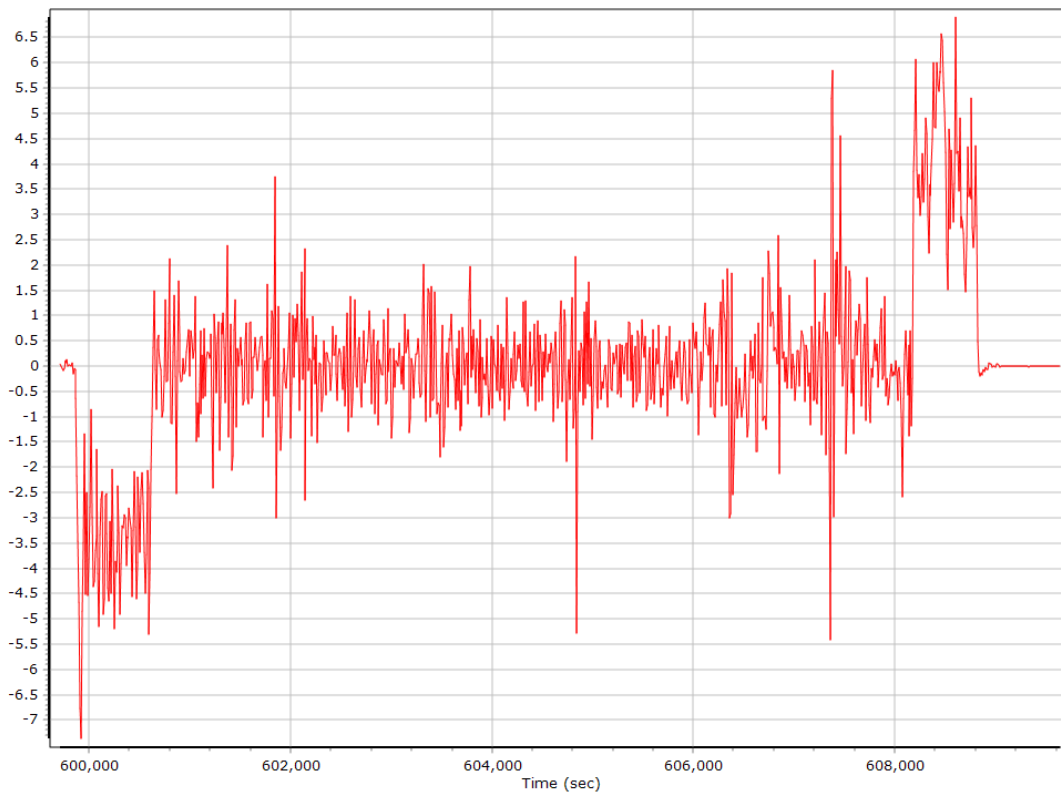
Heading



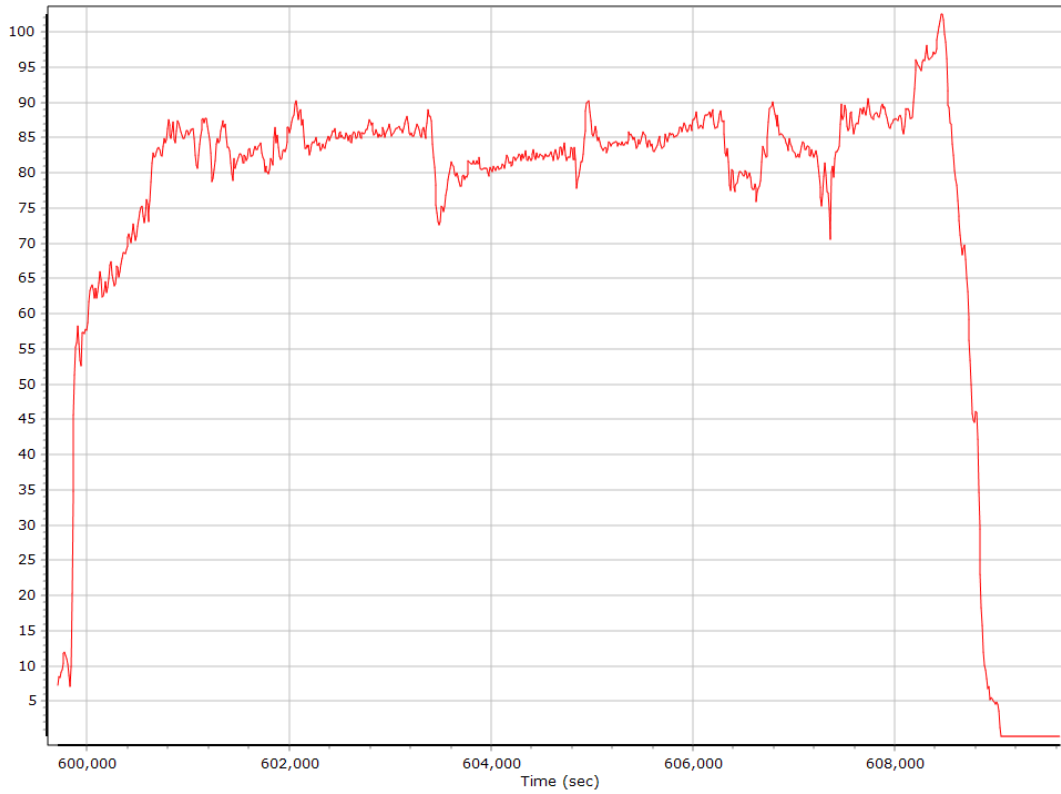
North/East Velocity



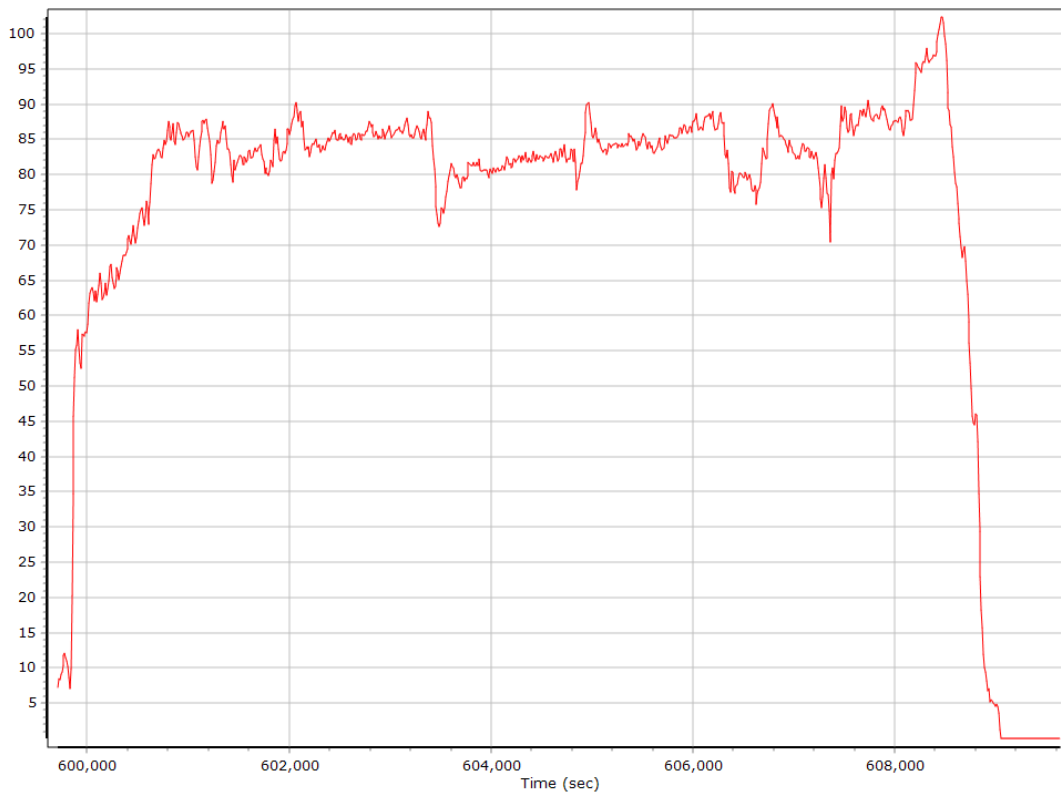
Down Velocity



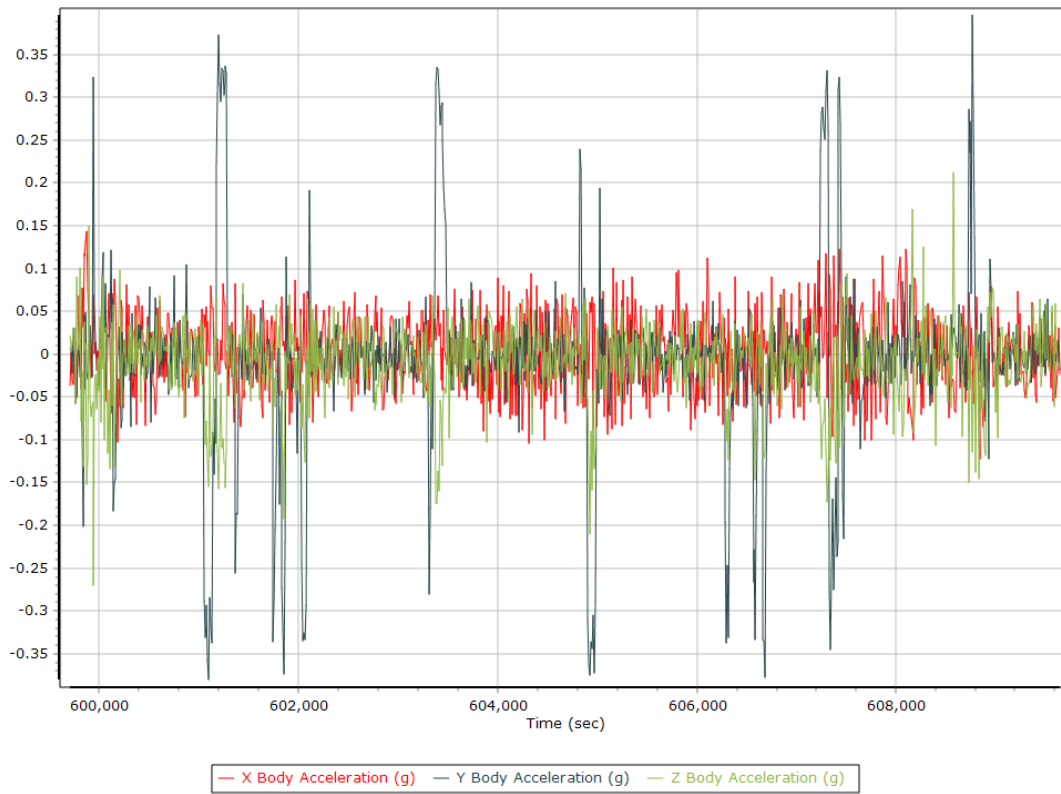
Total Speed



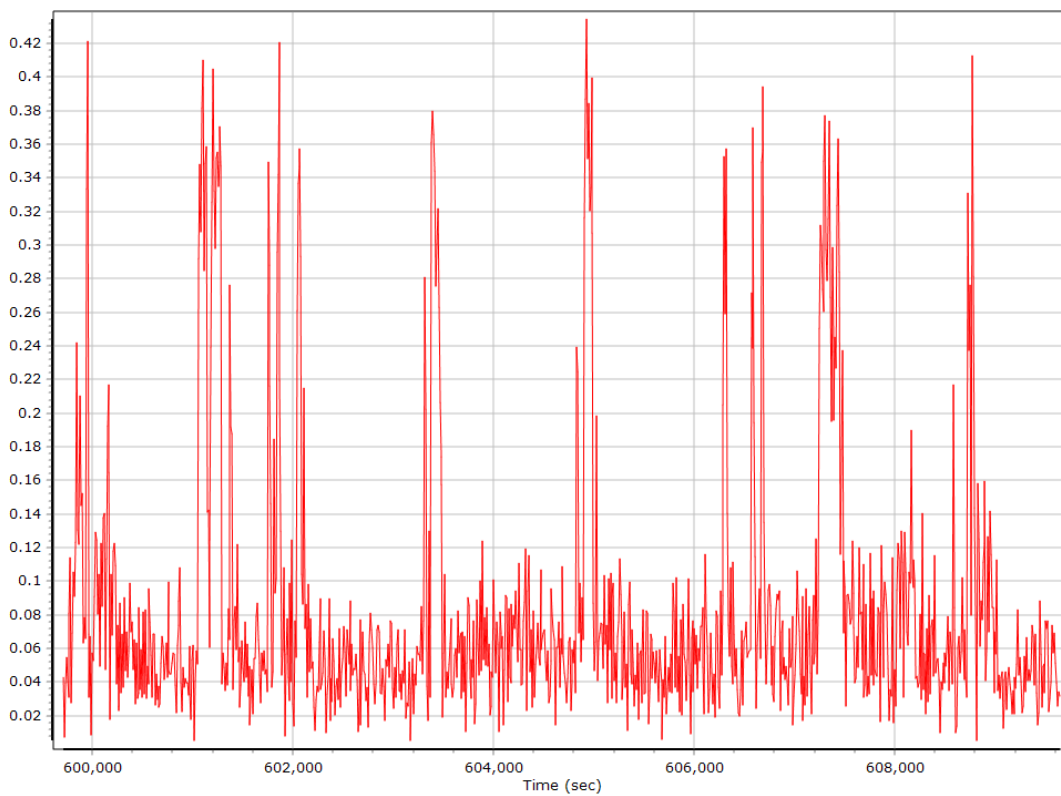
Ground Speed



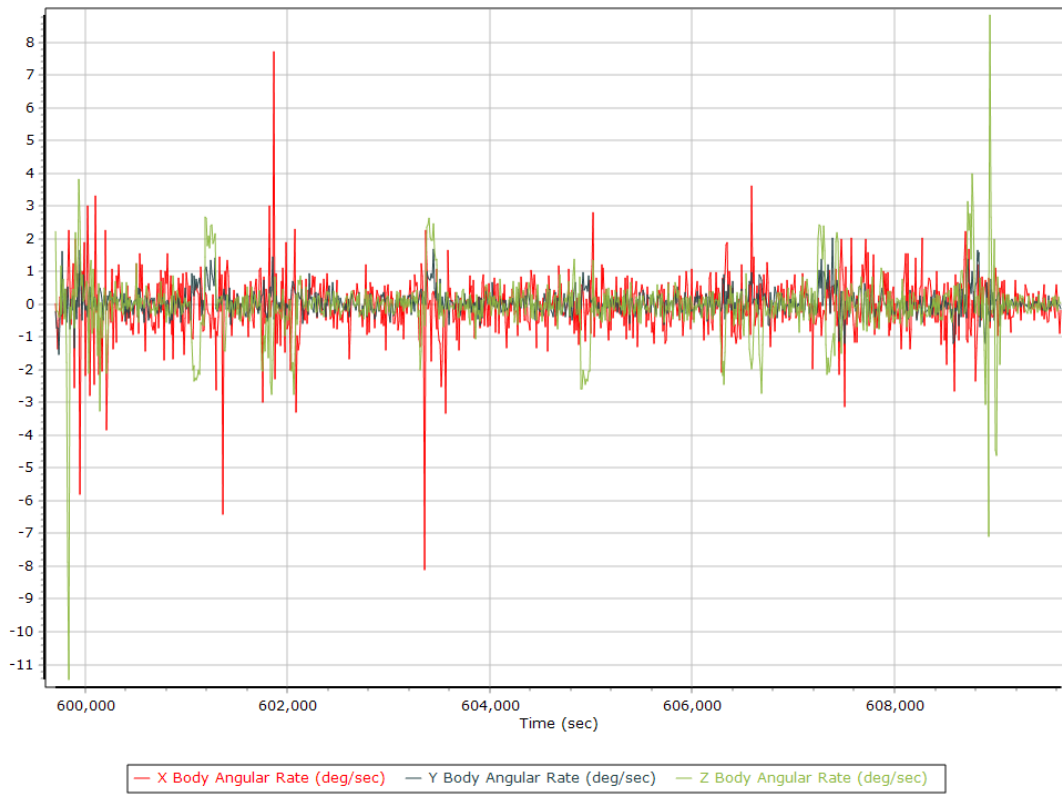
Body Acceleration



Total Body Acceleration

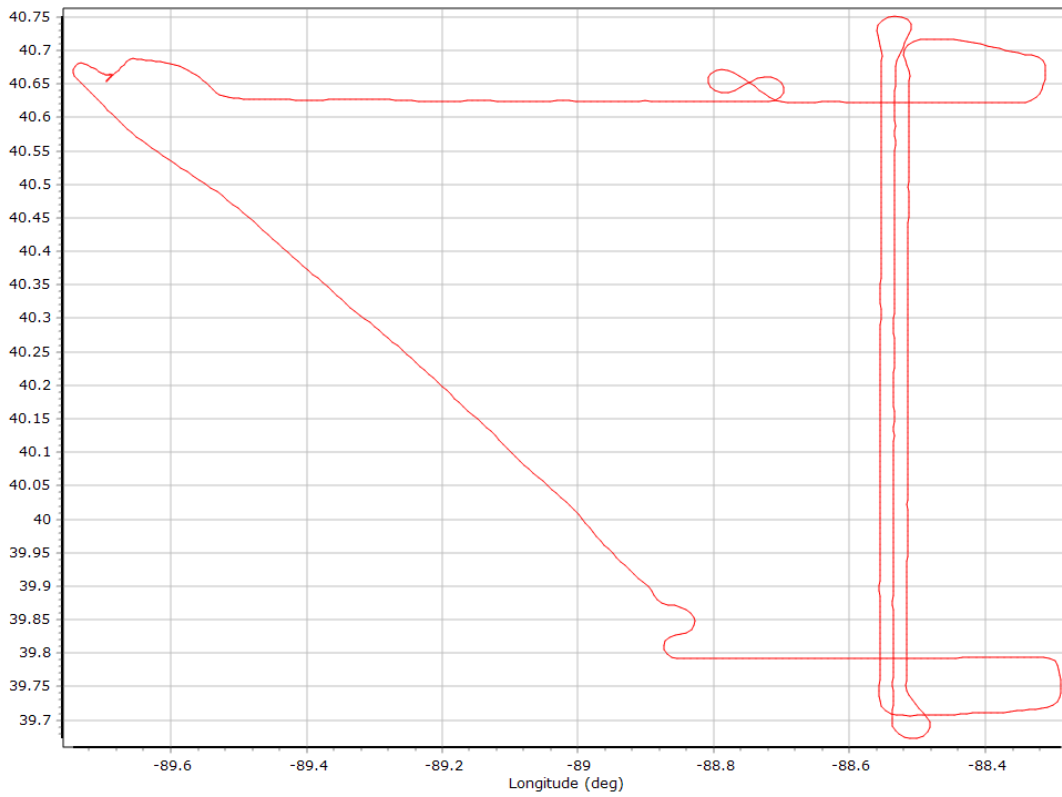


Body Angular Rate

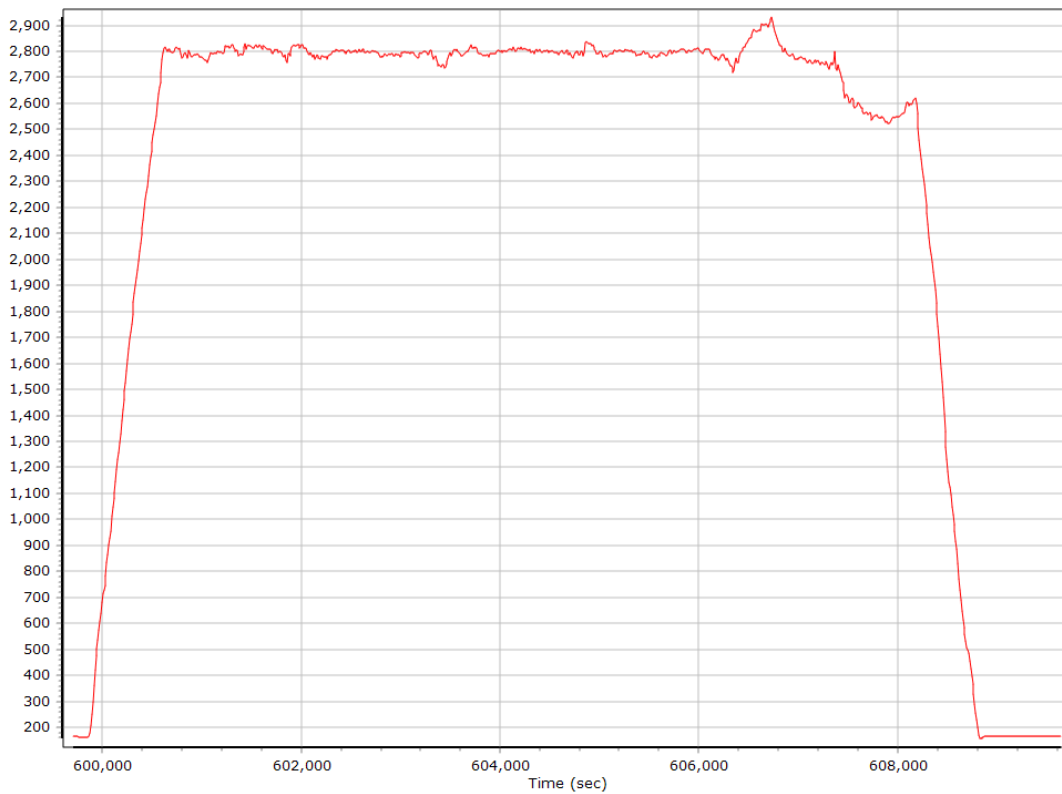


Forward Processed Trajectory Information

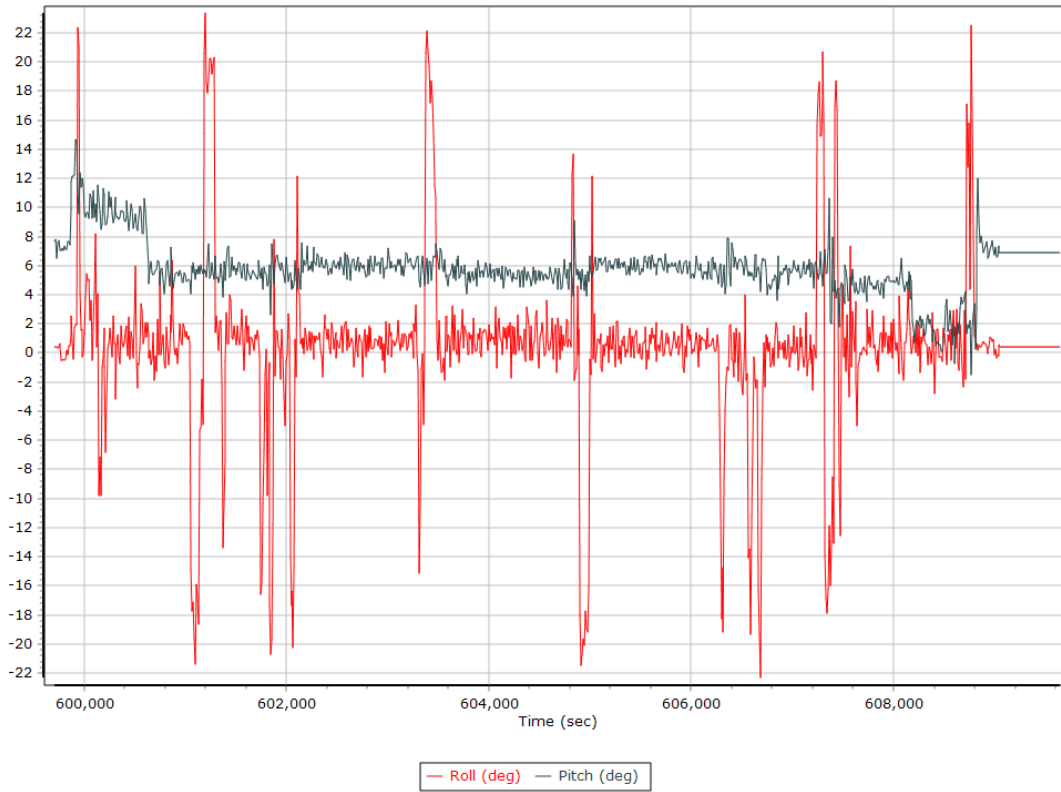
Top View



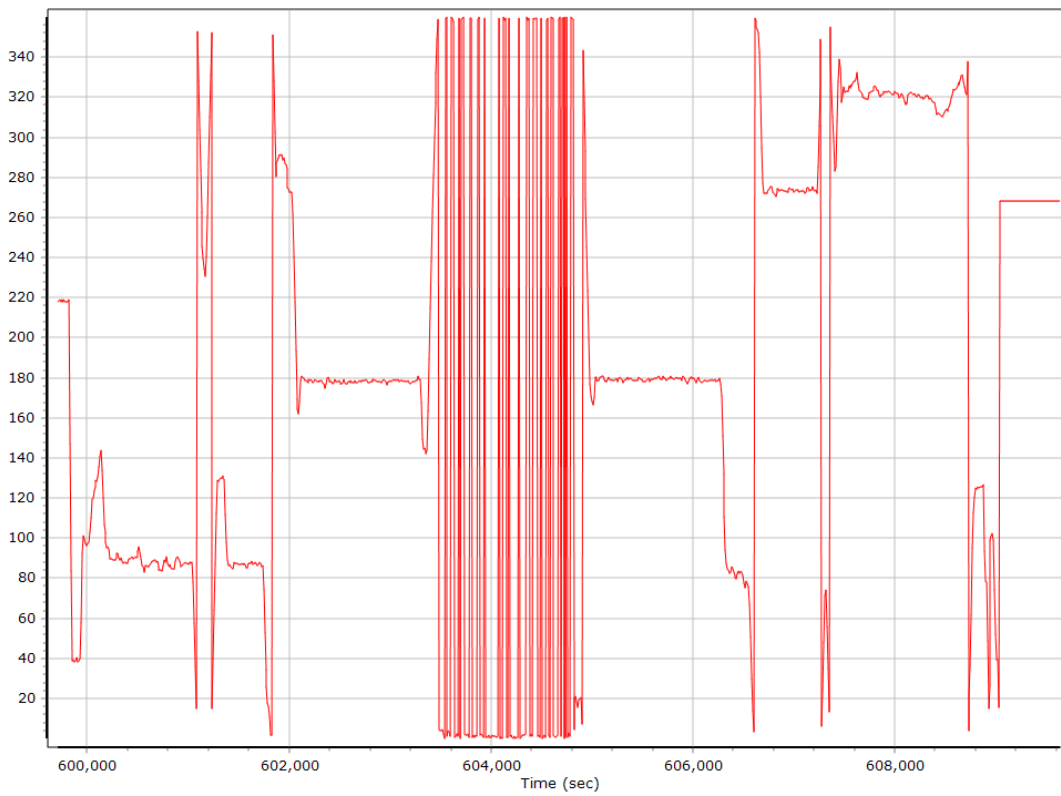
Altitude



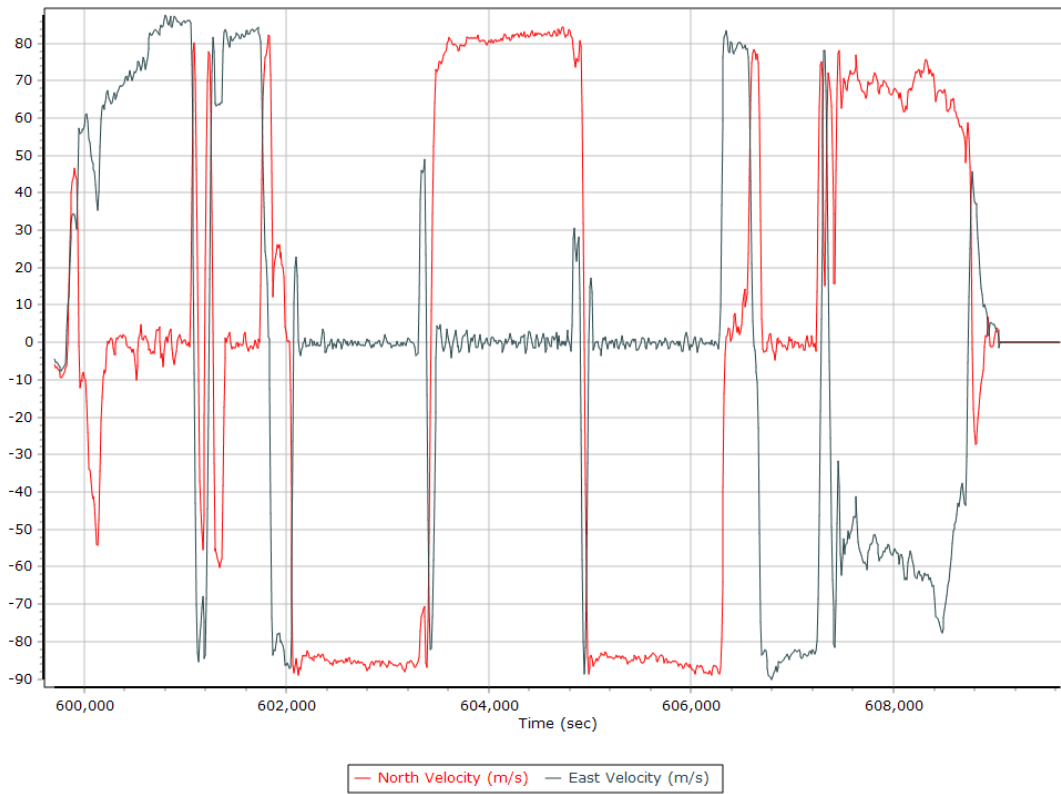
Roll/Pitch



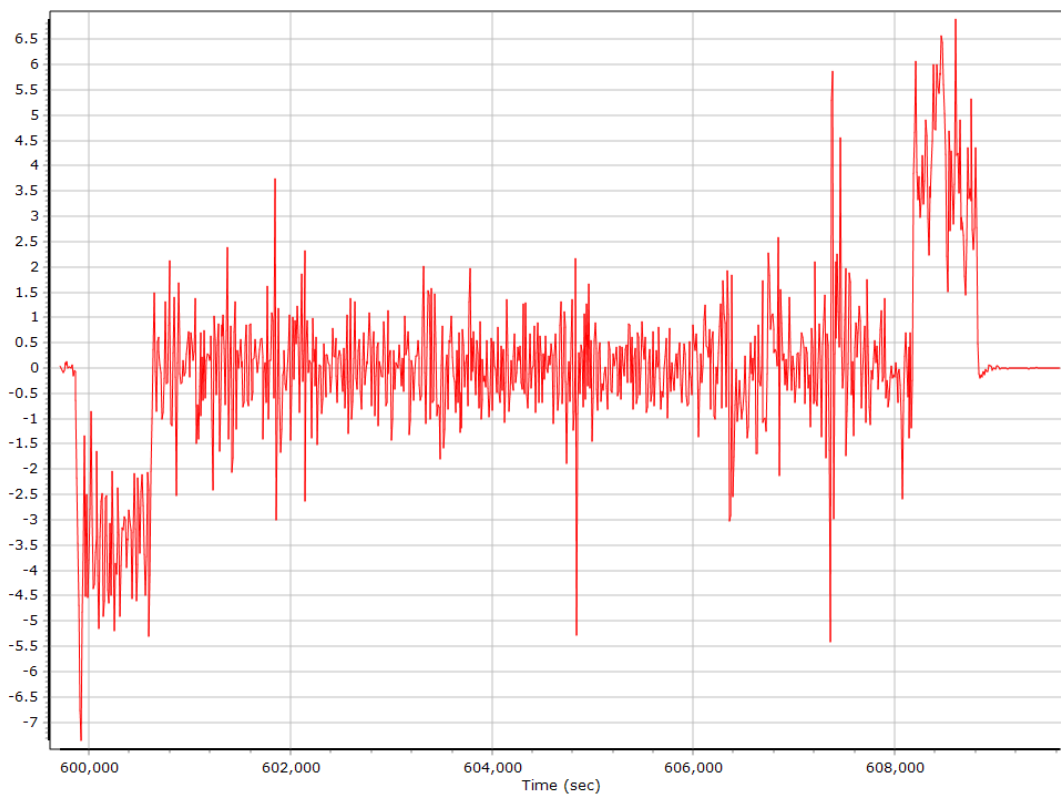
Heading



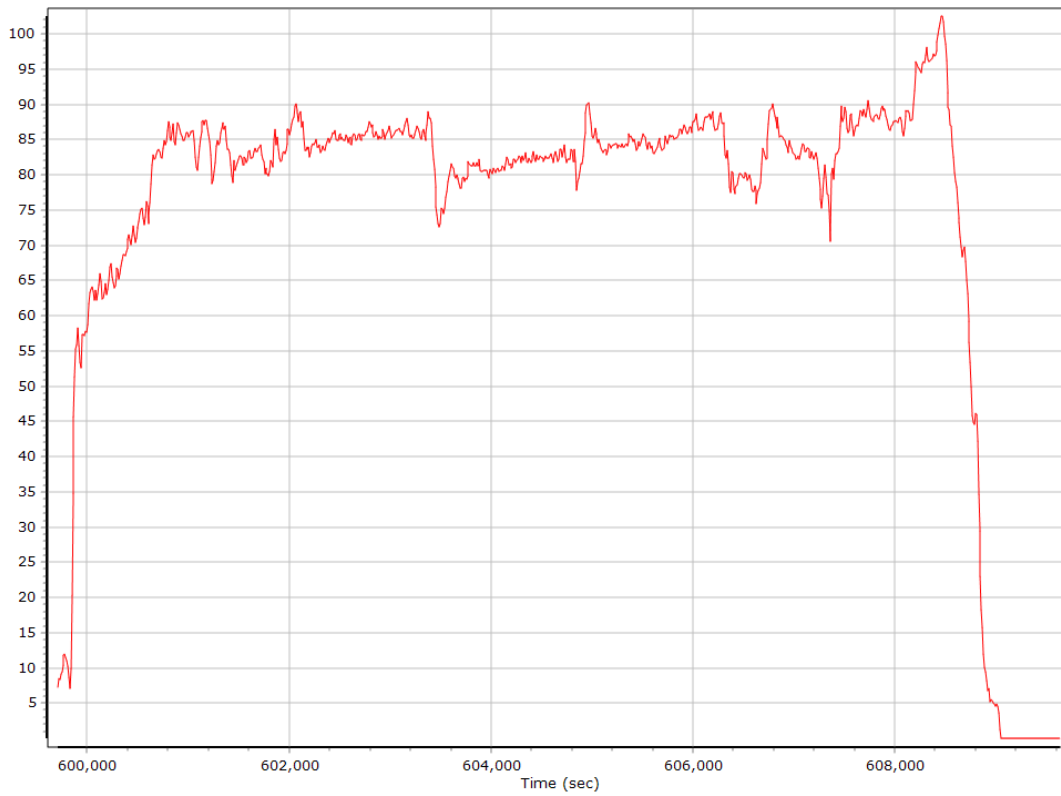
North/East Velocity



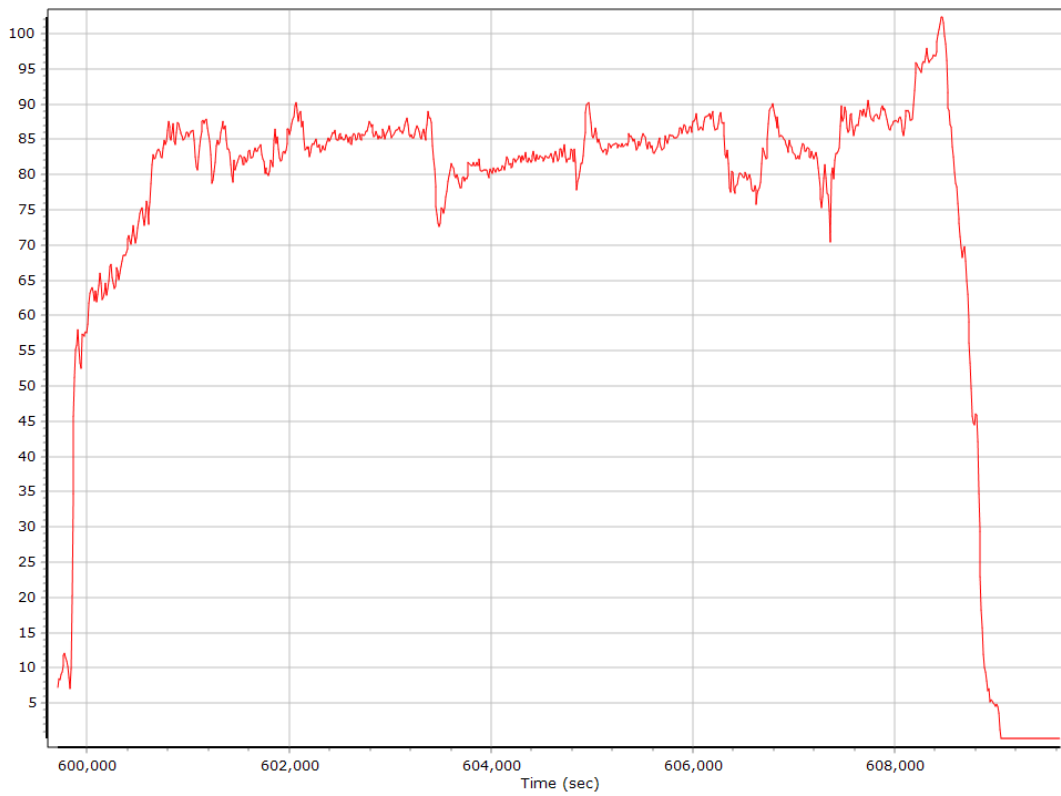
Down Velocity



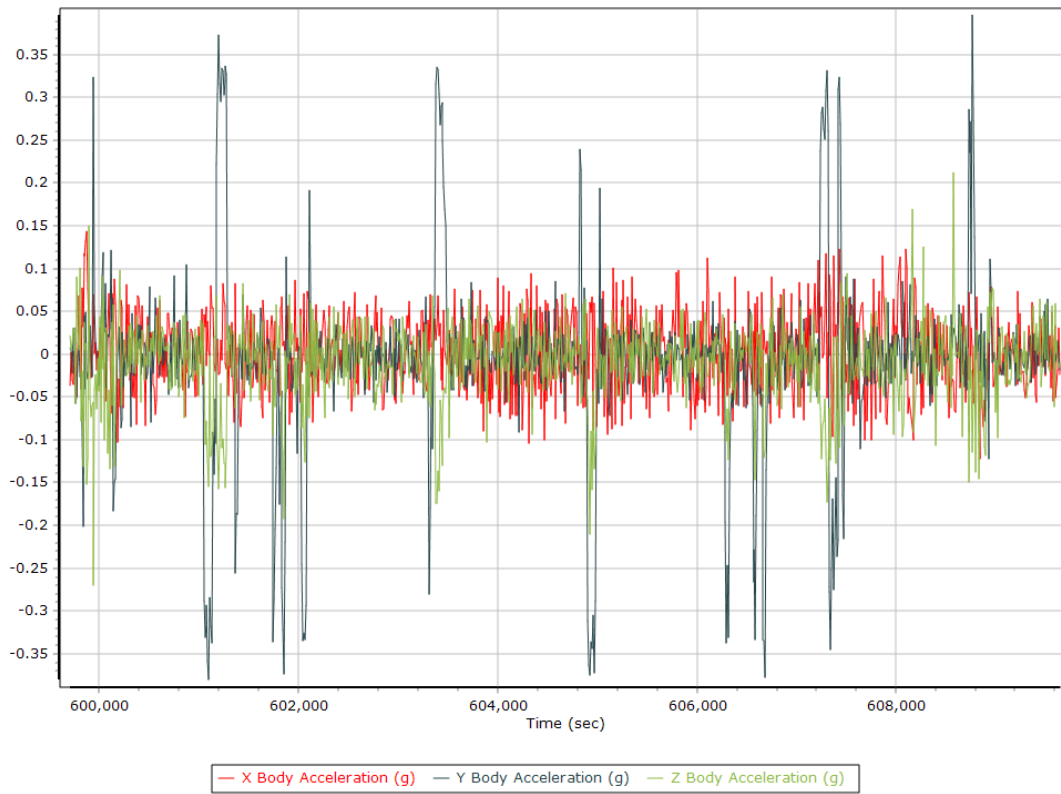
Total Speed



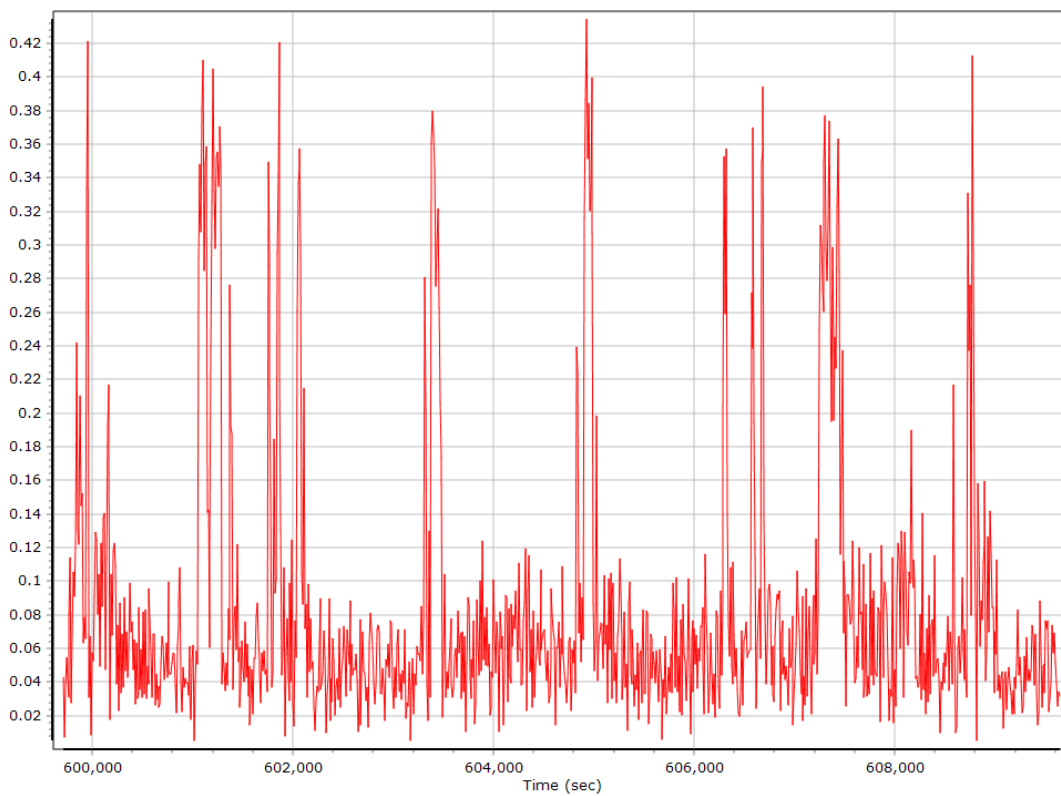
Ground Speed



Body Acceleration



Total Body Acceleration



Body Angular Rate

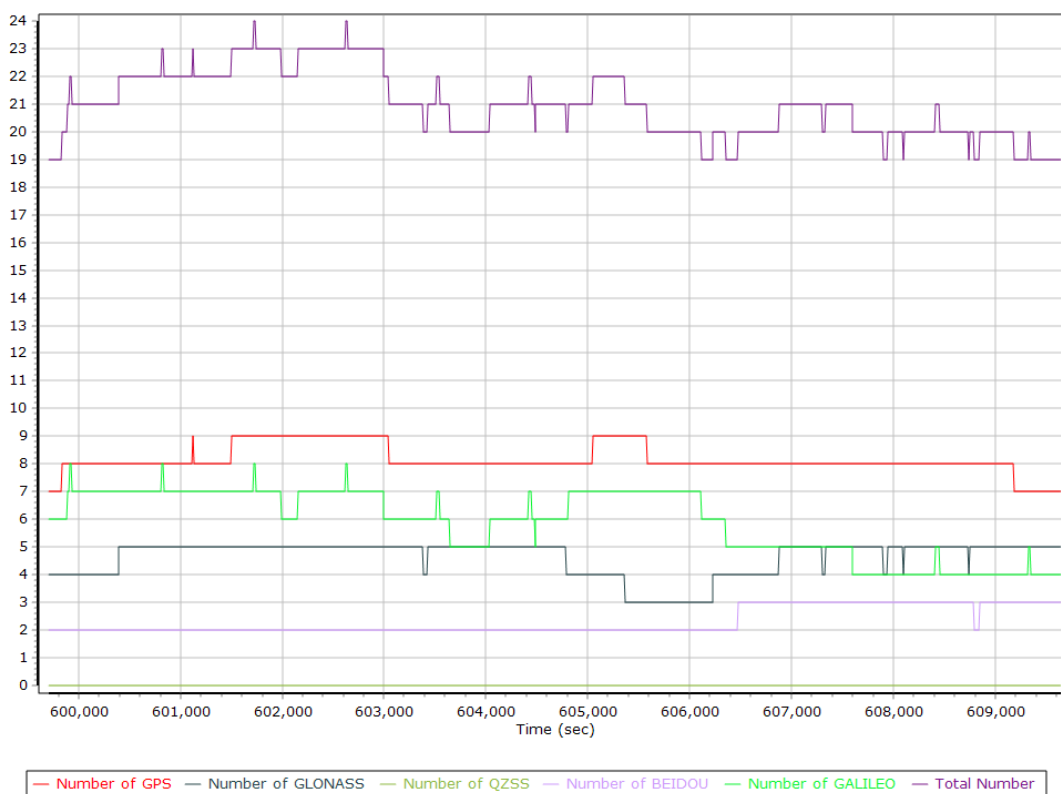


GNSS QC

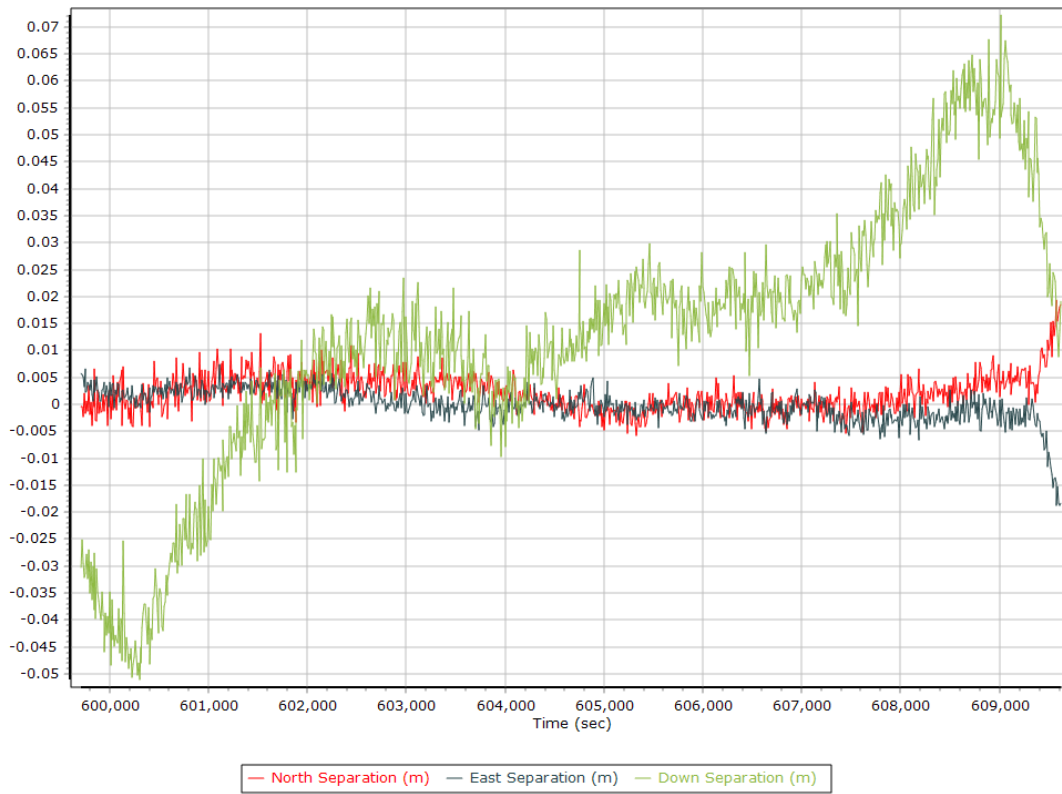
GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	7	9	8
Number of GLONASS SV	3	5	5
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	3	2
Number of GALILEO SV	4	8	6
Total number of SV	15	24	21
PDOP	1.00	1.69	1.22
QC Solution Gaps	0.00	0.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	10576.00	0.00	0.00
Percentage	100.00	0.00	0.00

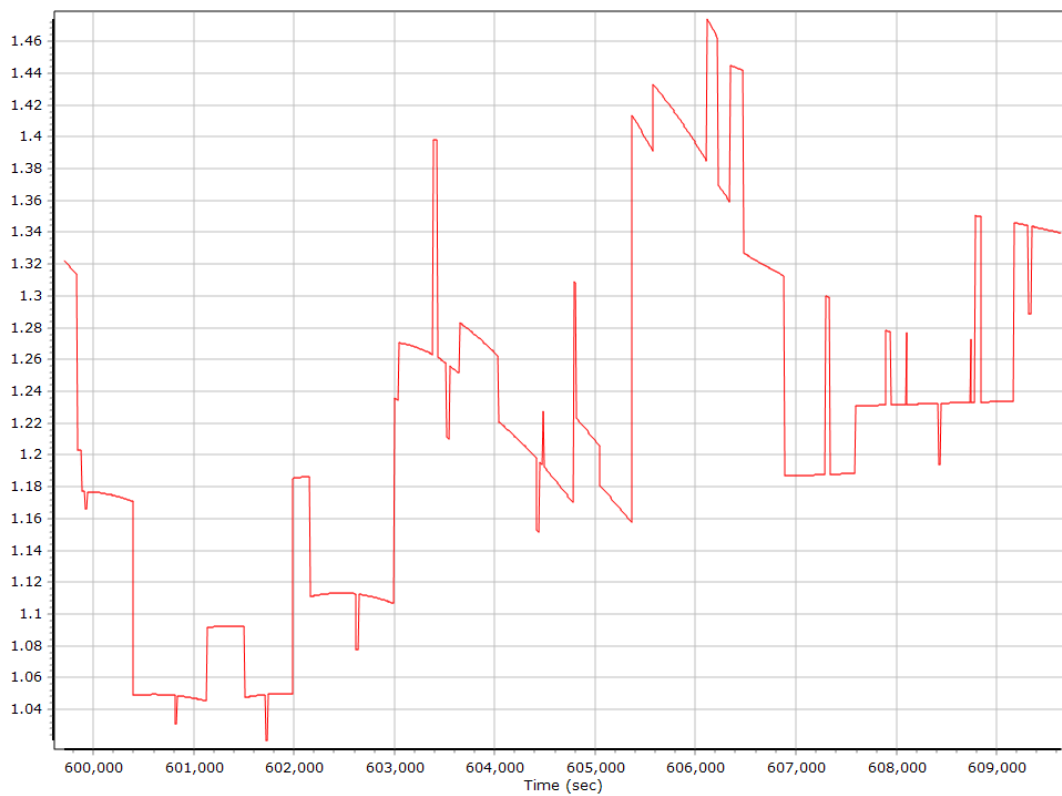
Num SVs in solution



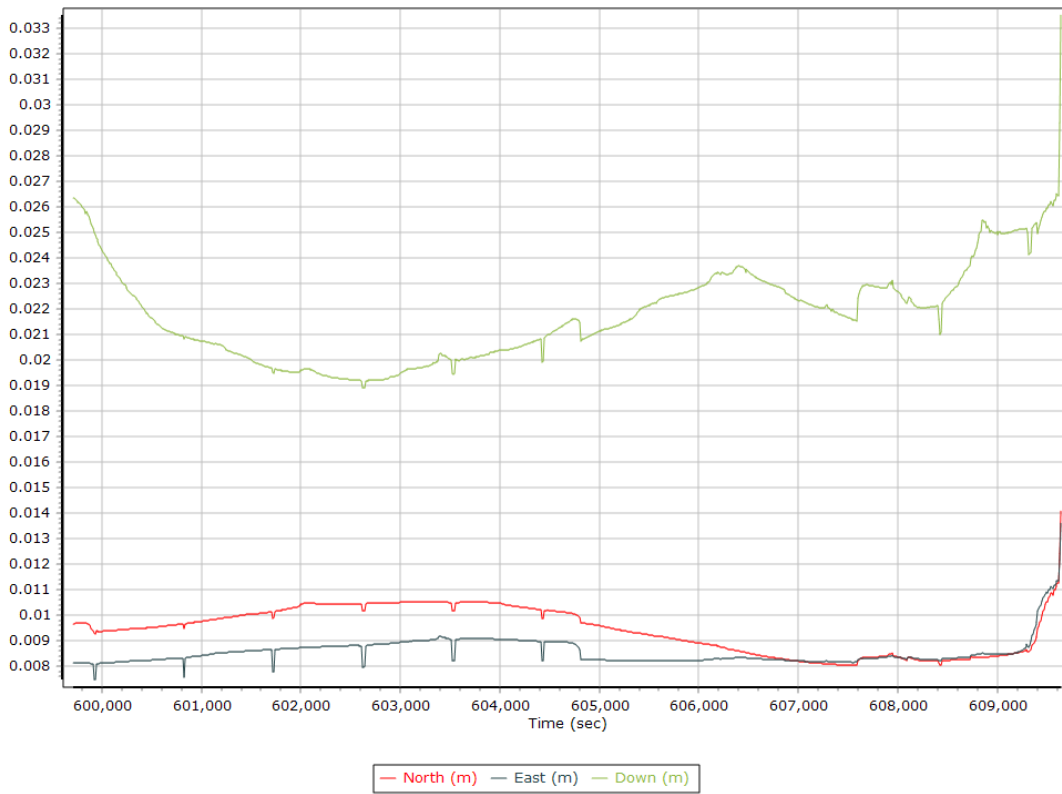
Forward/Reverse Separation



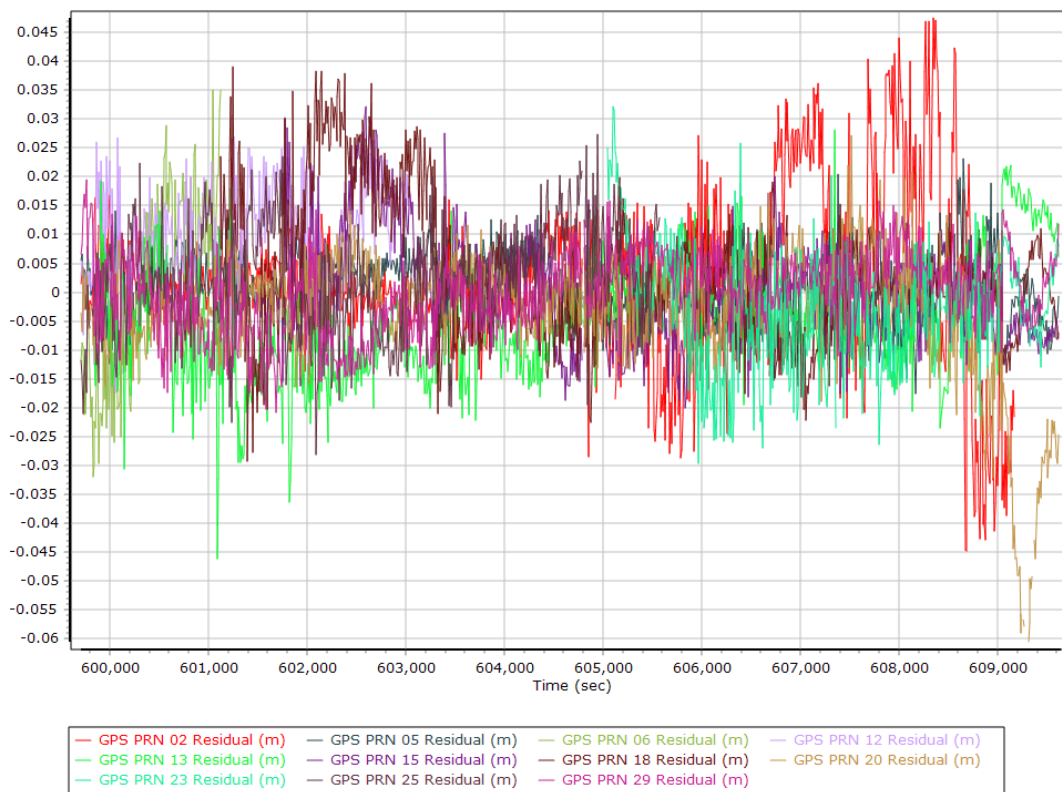
PDOP



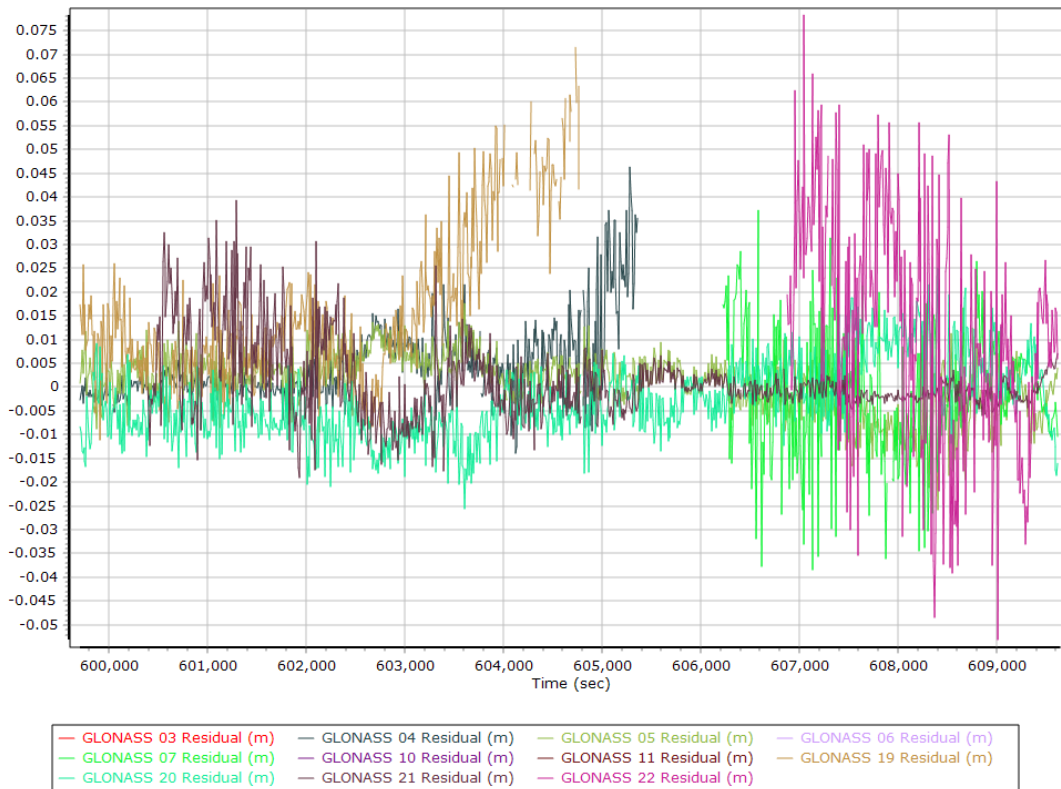
Estimated Position Accuracy



GPS Residuals



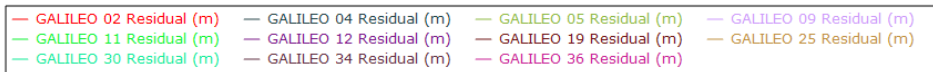
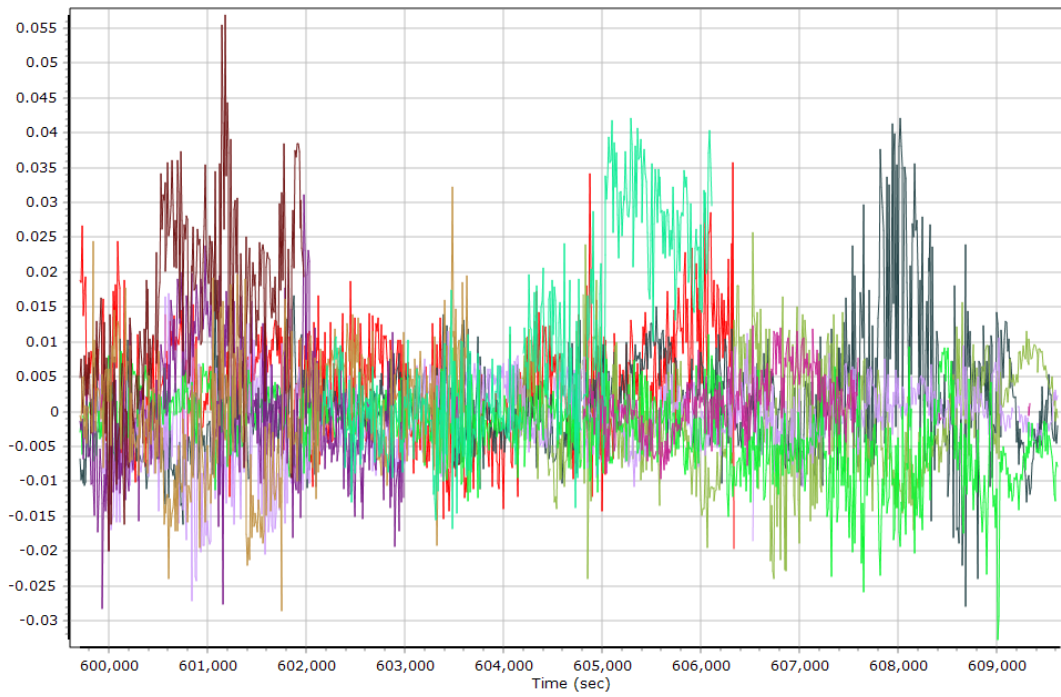
GLONASS Residuals



BEIDOU Residuals



GALILEO Residuals



GNSS-Inertial Processor Configuration

Processing mode	IN-Fusion PP-RTX		
Stabilized mount	False		
Processing start time	599063.000 (05/07/2022 22:24:23)		
Processing end time	4845.000 (05/08/2022 01:20:45)		
Initial attitude source	Real-Time VNAV/RNAV Attitude		
IMU Sensor Context	Processing with Onboard IMU		
Reference to IMU lever arm (m)	0.000	0.000	0.000
Reference to IMU mounting angles (deg)	0.000	0.000	180.000
Reference to Primary GNSS lever arm (m)	0.377	-0.072	-1.065
Reference to Primary GNSS lever arm std dev (m)	0.030	0.030	0.030
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

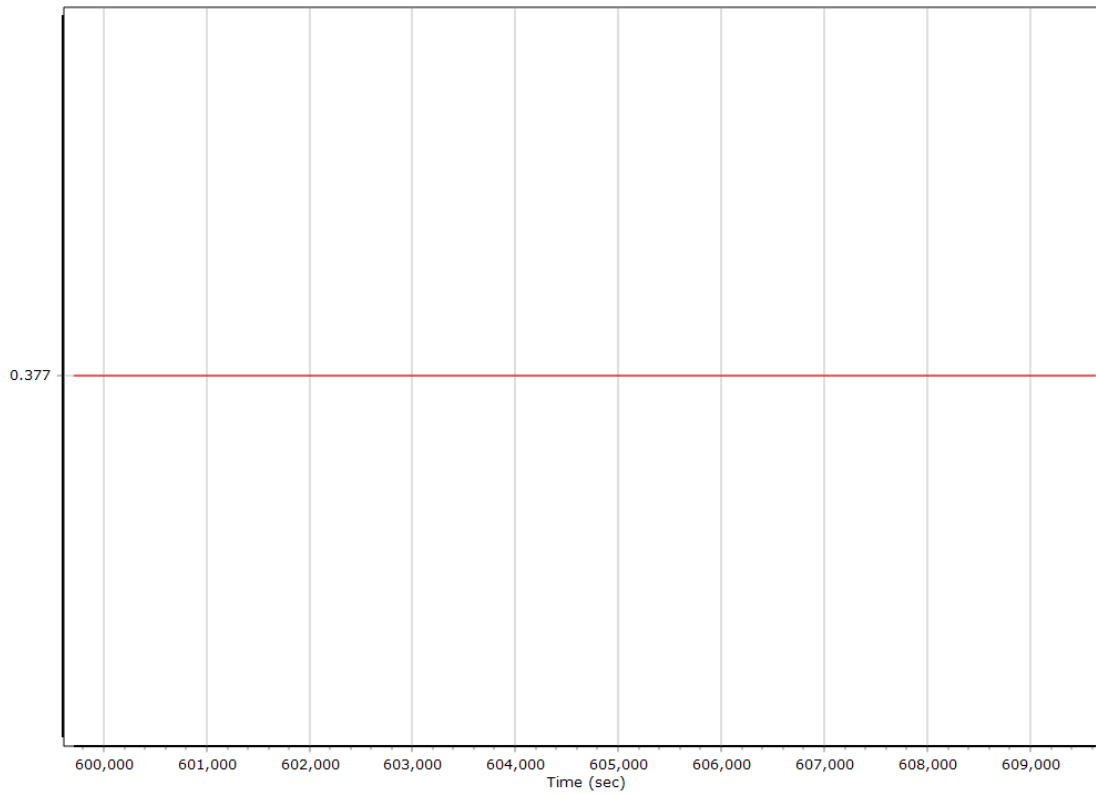
Calibrated Installation Parameters

Reference-Primary GNSS Lever Arm (m)

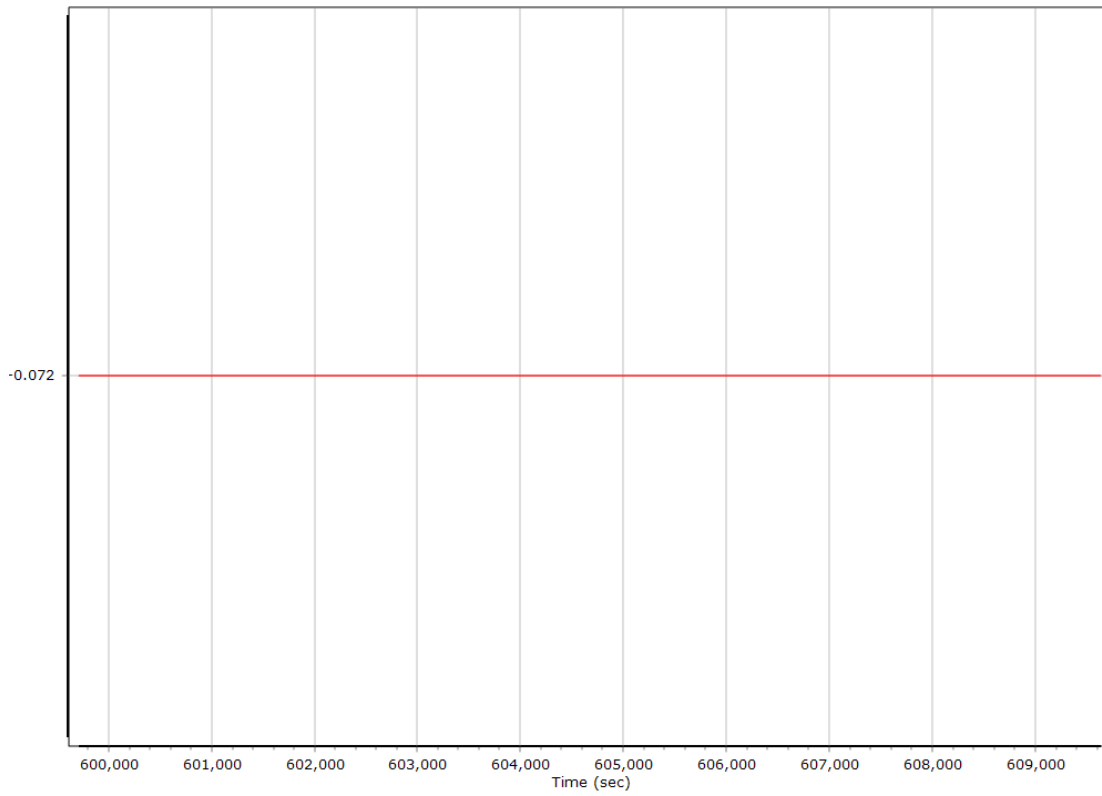
Reference-Primary GNSS Lever Arm Automatic Calibration Results

Original Reference to Primary GNSS lever arm (m)	-0.399	-0.382	-1.125
Iteration 1 Reference to Primary GNSS lever arm (m)	0.344	-0.091	-1.068
Iteration 2 Reference to Primary GNSS lever arm (m)	0.377	-0.072	-1.065
Primary GNSS Lever Arm In use	Iteration 2		

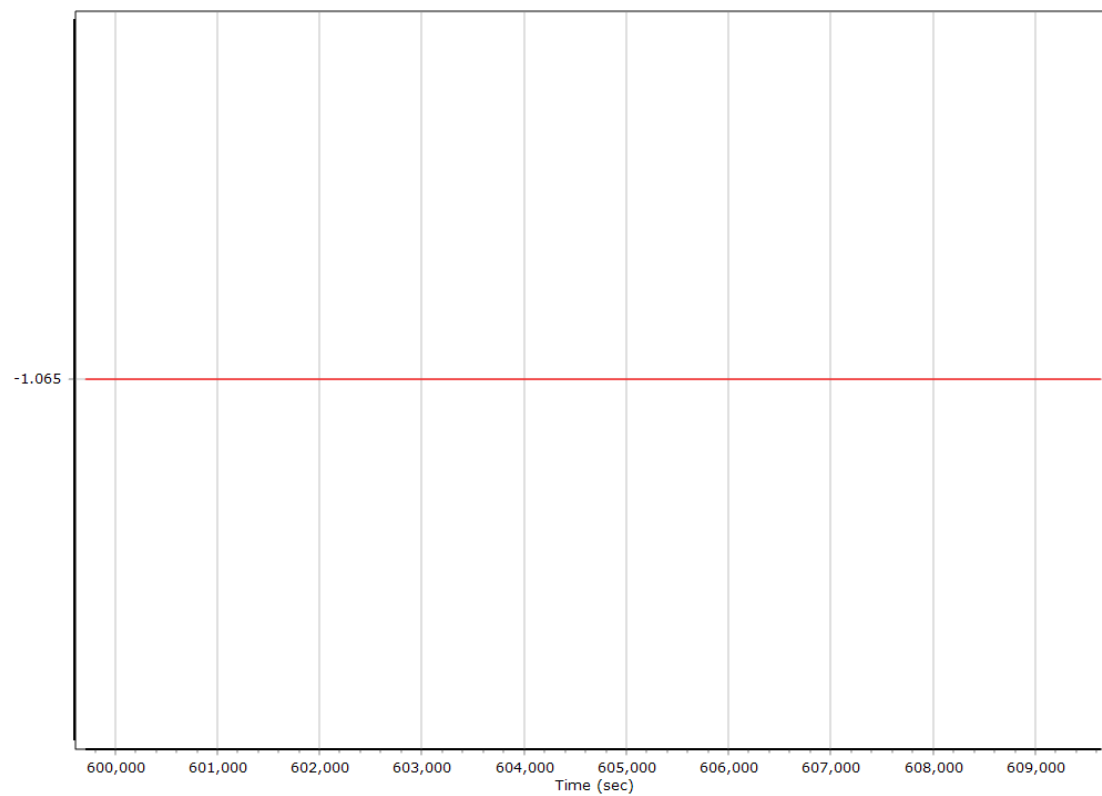
X Reference-Primary GNSS Lever Arm (m)



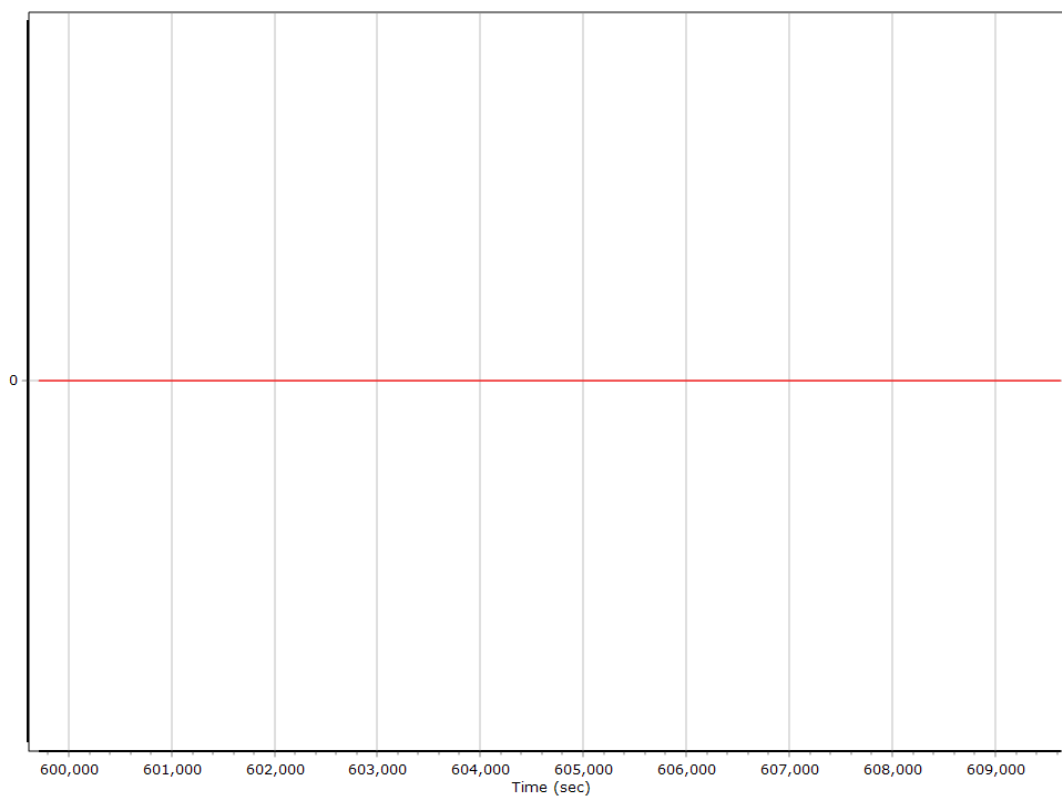
Y Reference-Primary GNSS Lever Arm (m)



Z Reference-Primary GNSS Lever Arm (m)



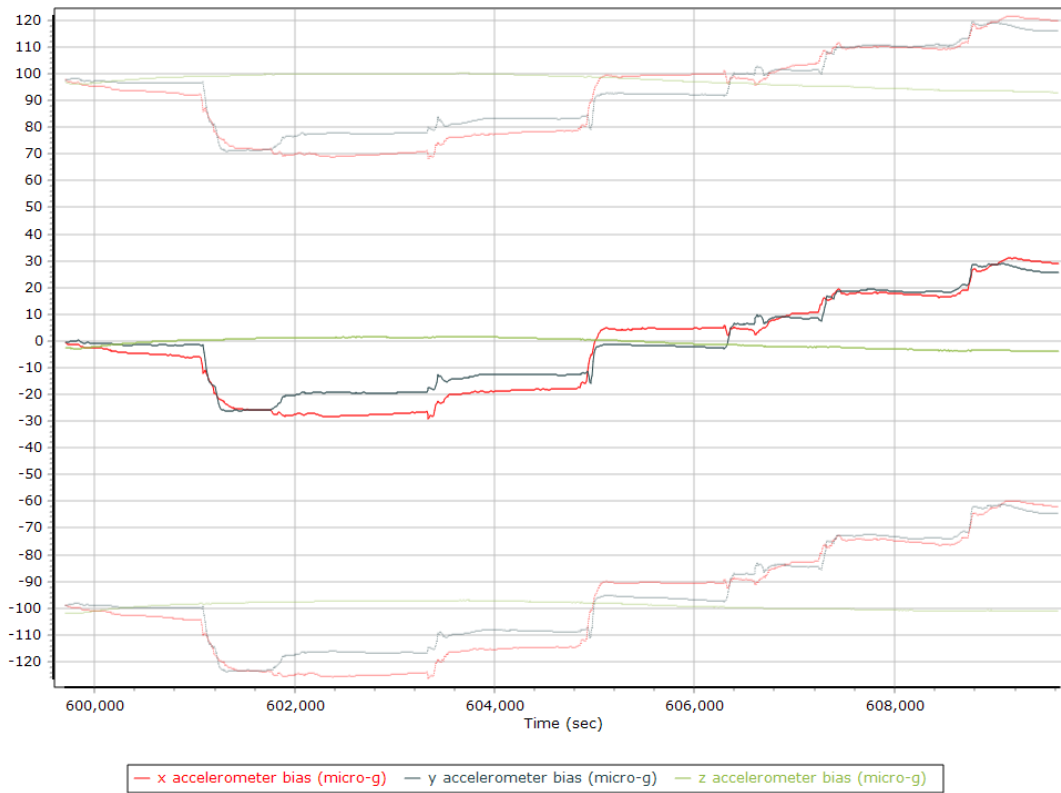
Reference-Primary GNSS Lever Arm Figure of Merit



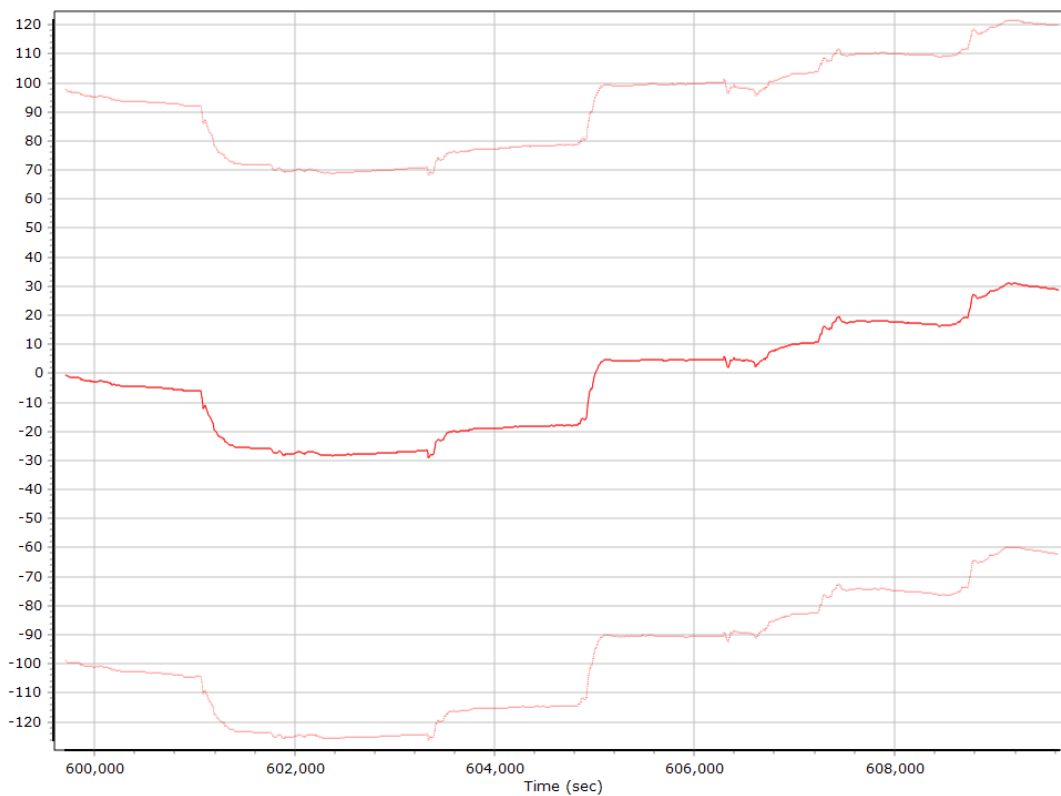
IN-Fusion QC

Forward Processed Estimated Errors, Reference Frame

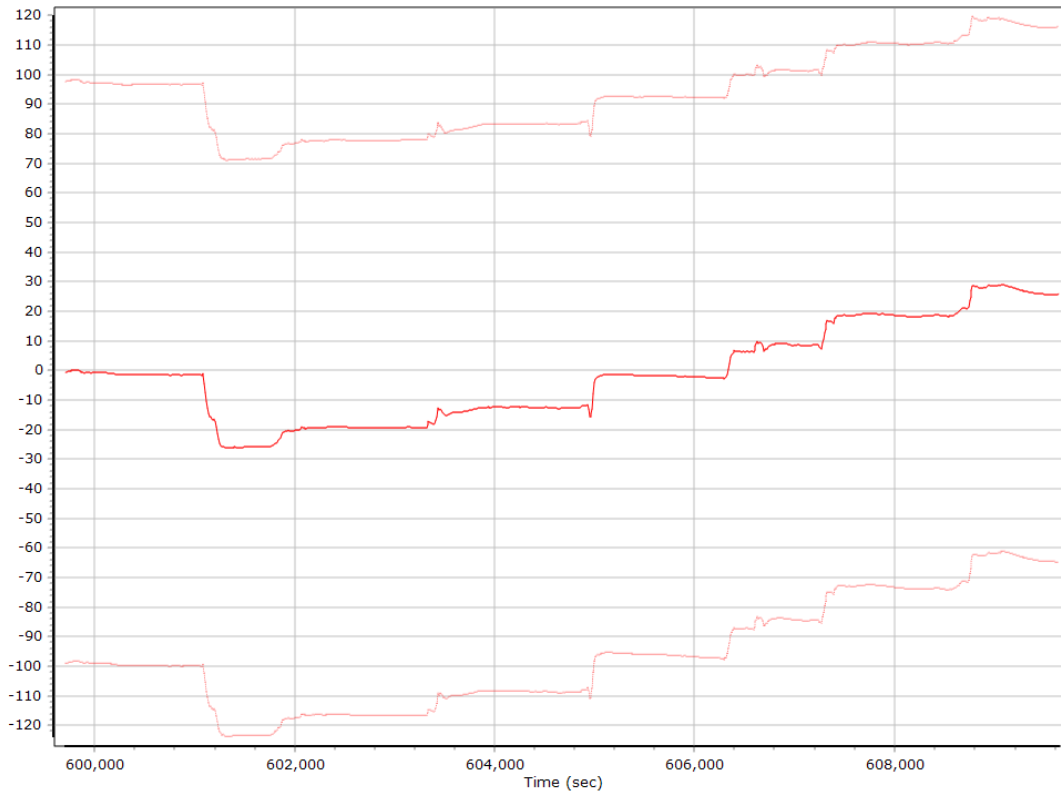
Accelerometer Bias (micro-g)



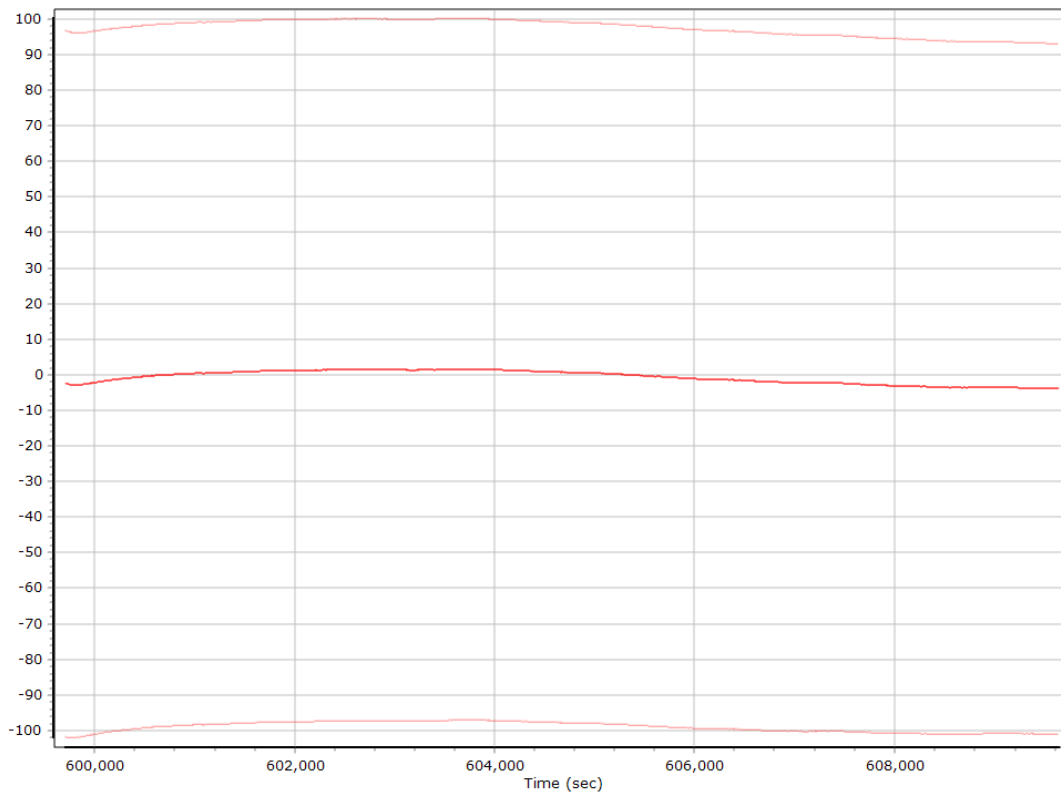
X Accelerometer Bias (micro-g)



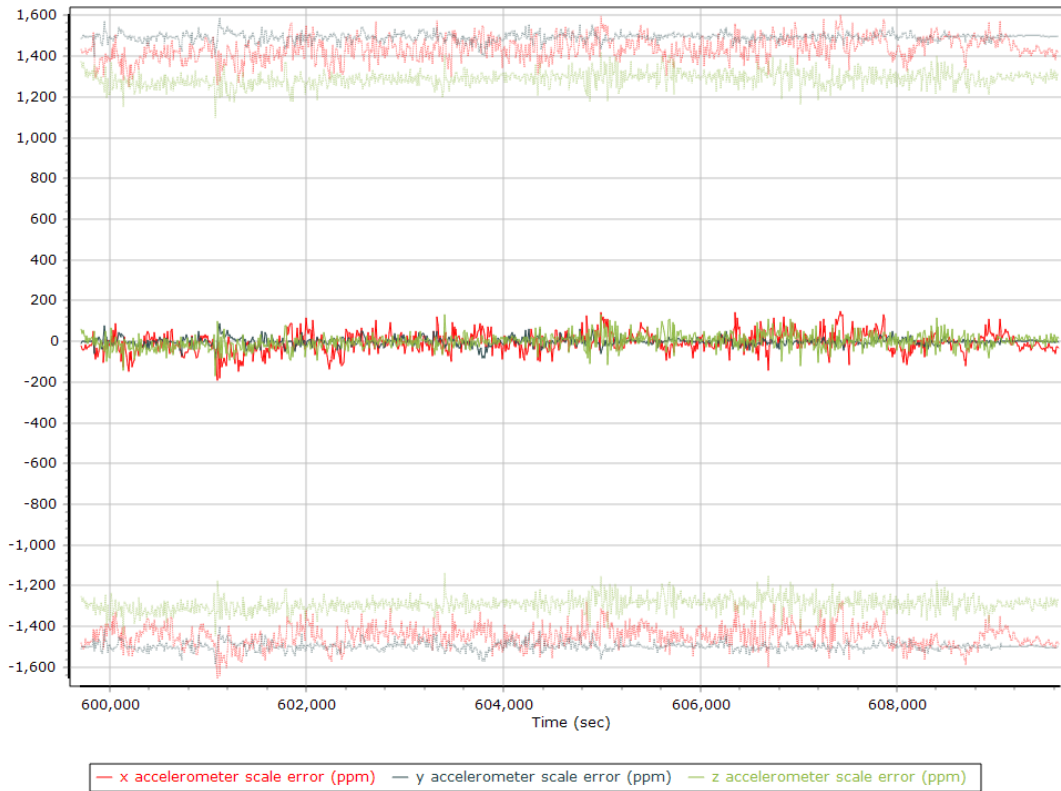
Y Accelerometer Bias (micro-g)



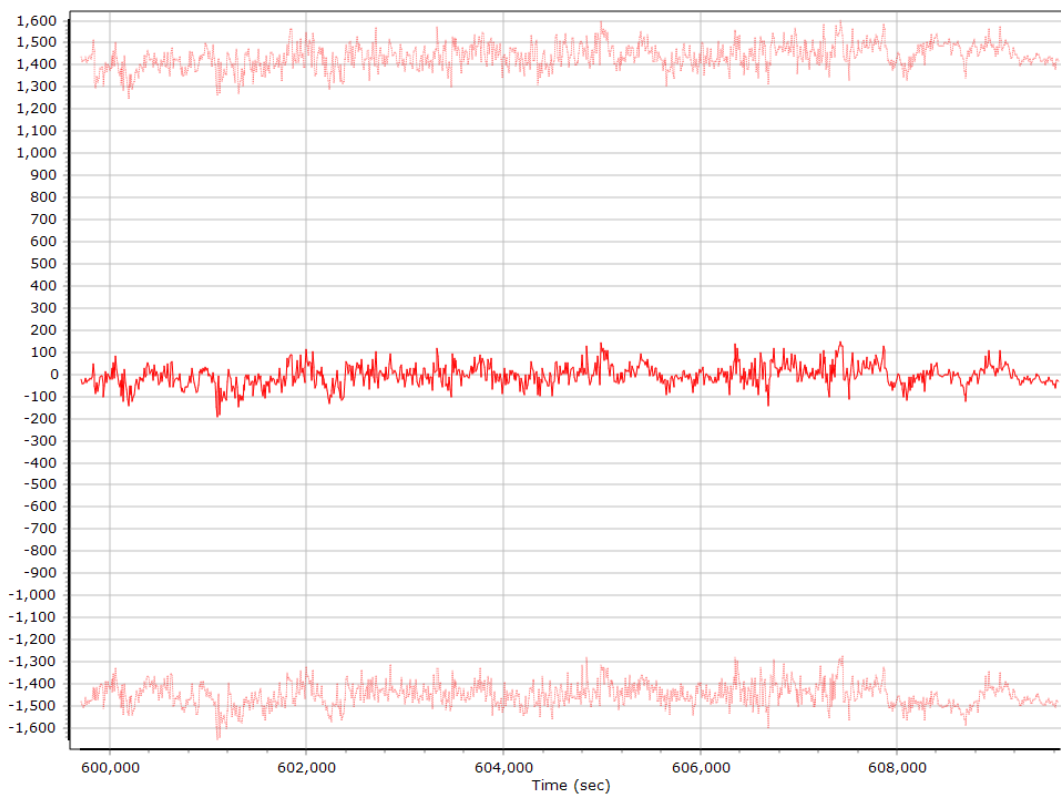
Z Accelerometer Bias (micro-g)



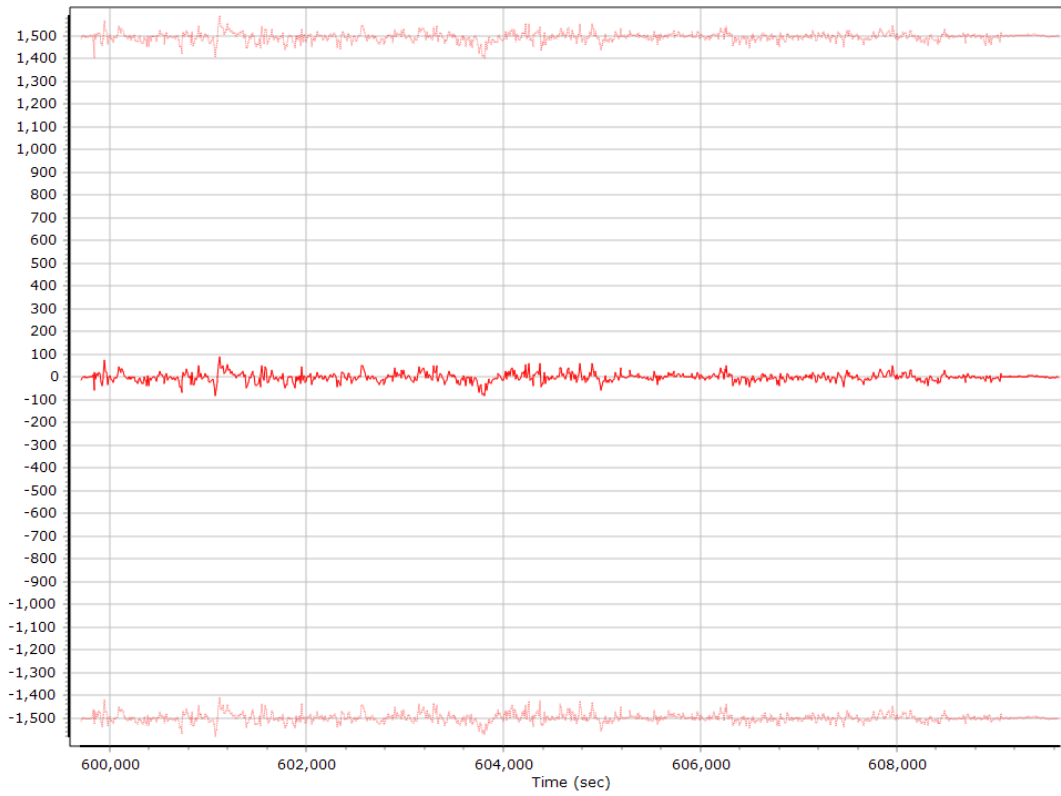
Accelerometer Scale Error (ppm)



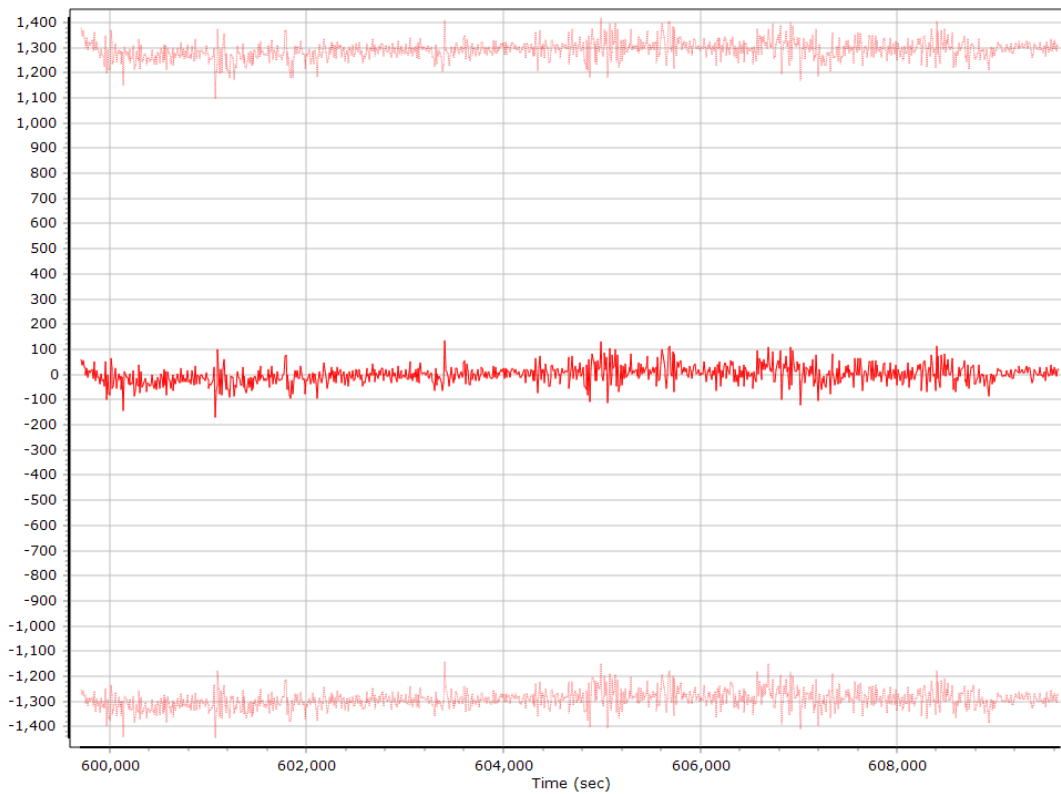
X Accelerometer Scale Error (ppm)



Y Accelerometer Scale Error (ppm)



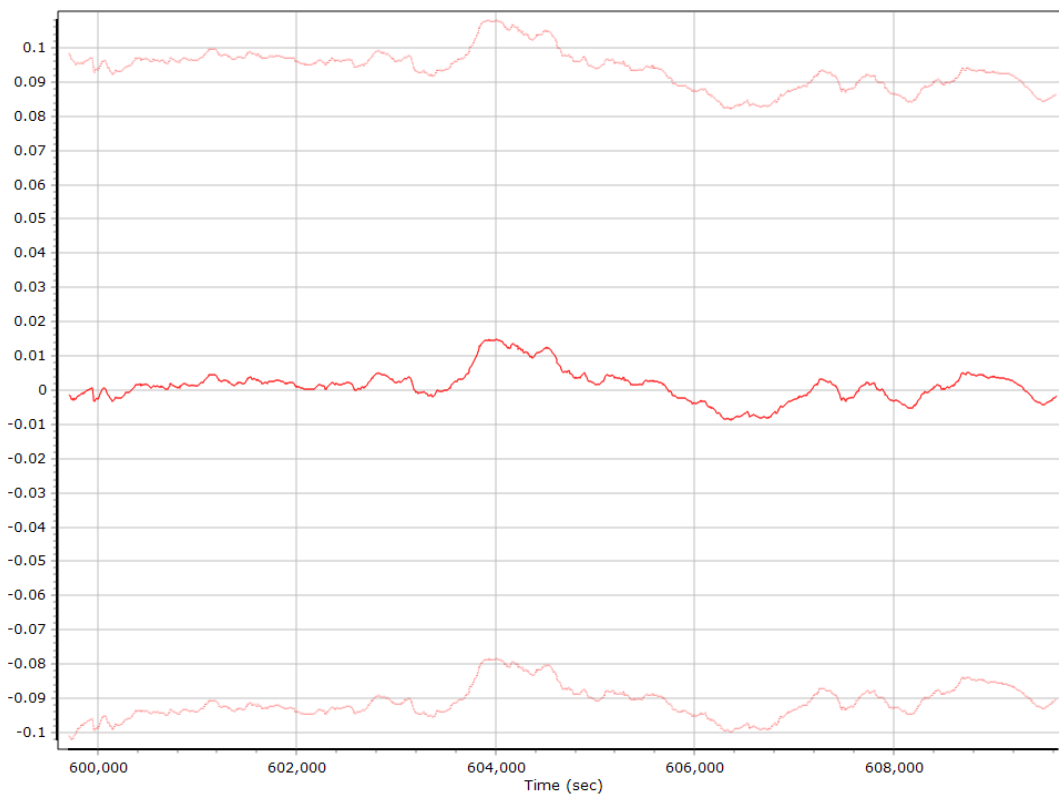
Z Accelerometer Scale Error (ppm)



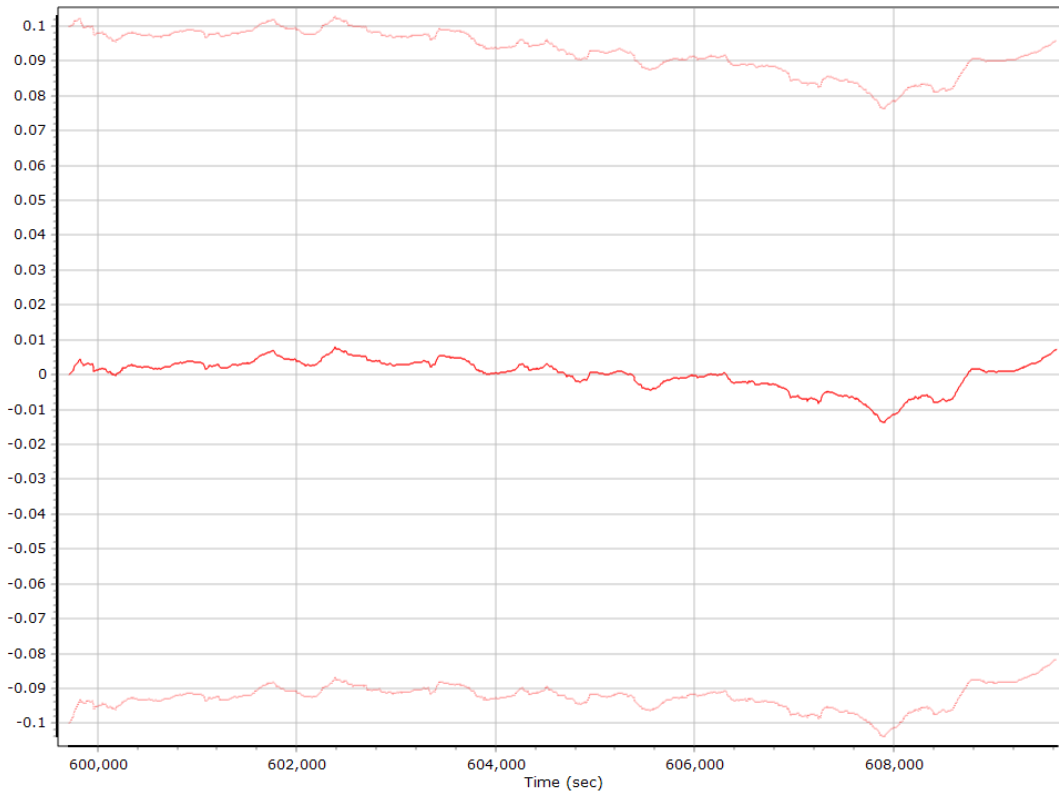
Gyro Bias (deg/h)



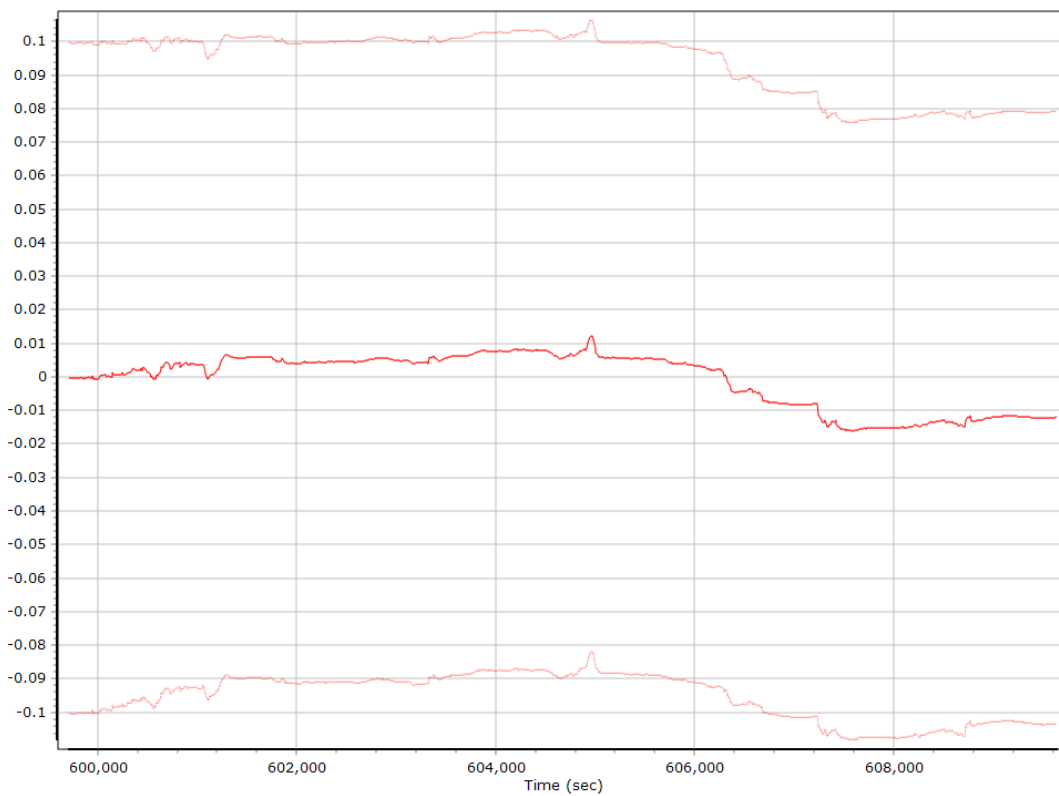
X Gyro Bias (deg/h)



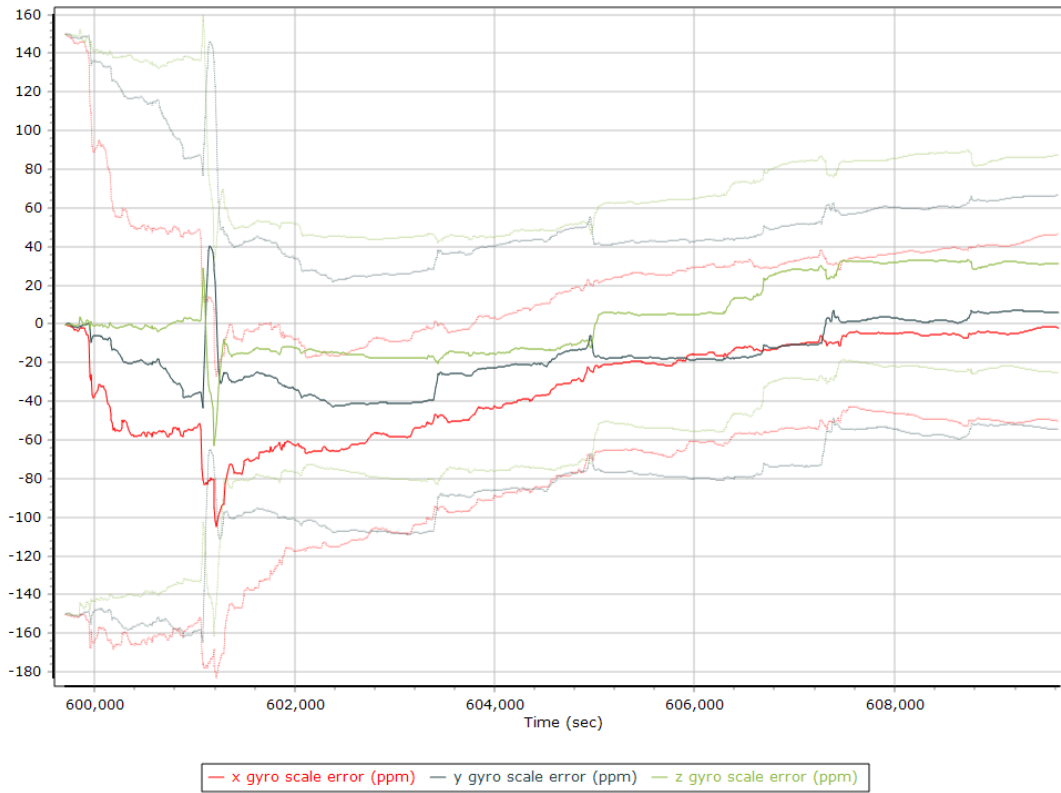
Y Gyro Bias (deg/h)



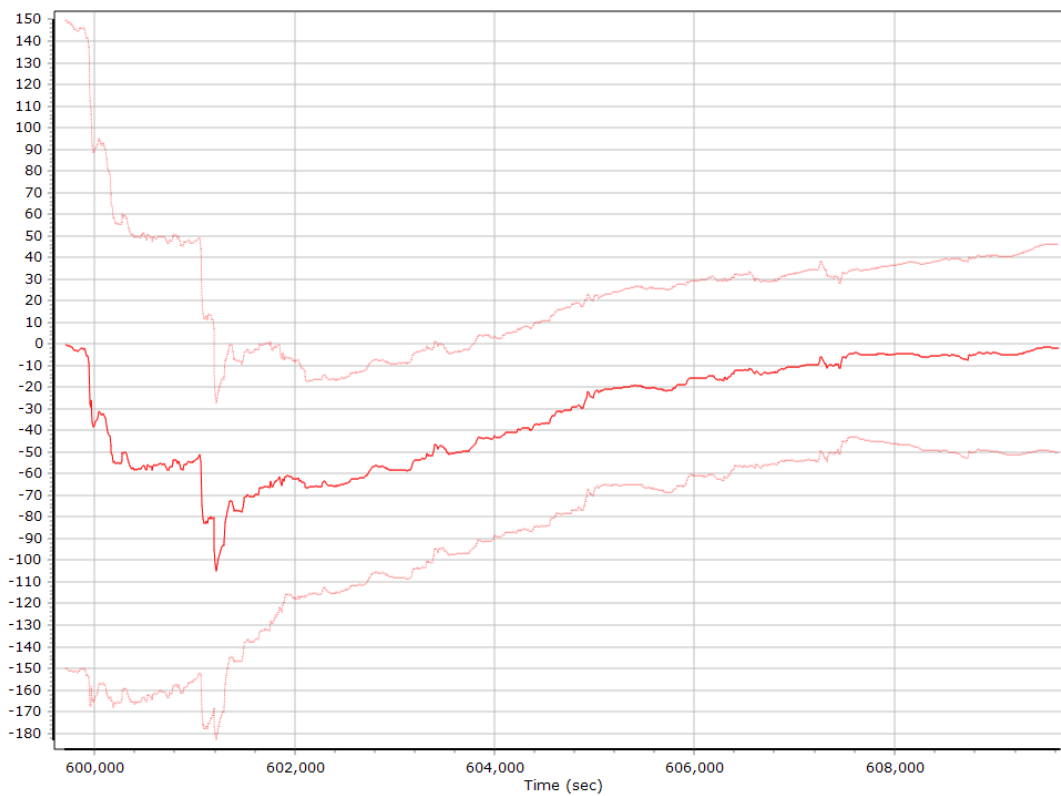
Z Gyro Bias (deg/h)



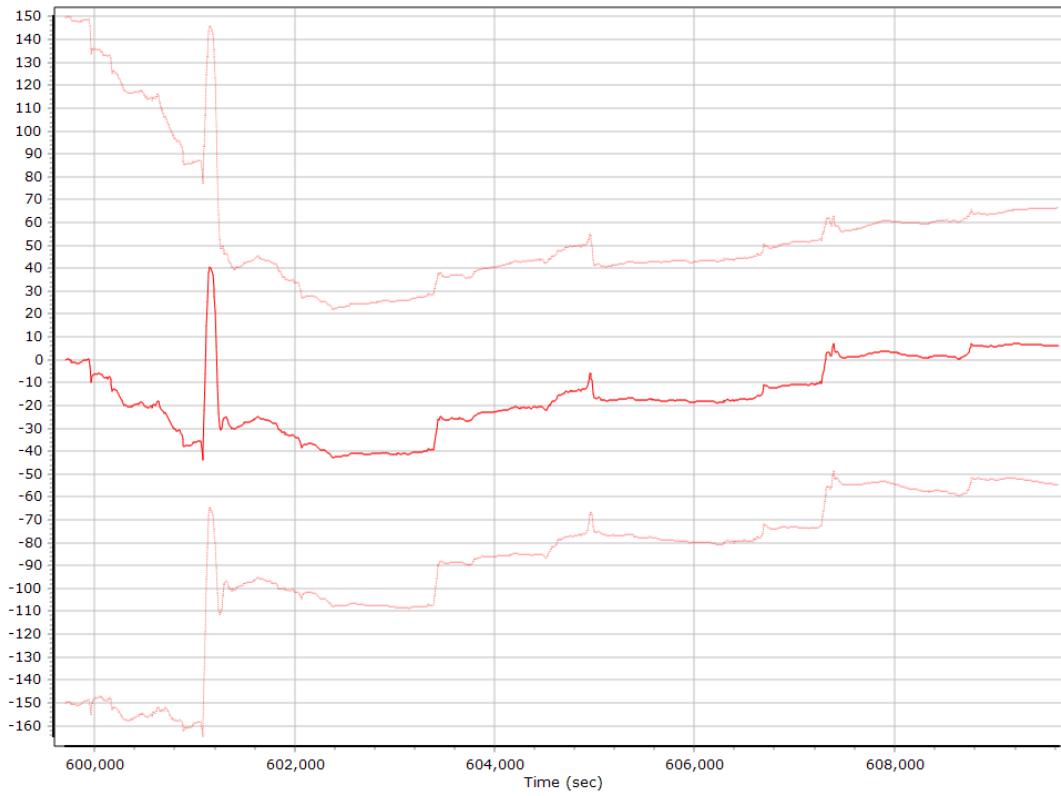
Gyro Scale Error (ppm)



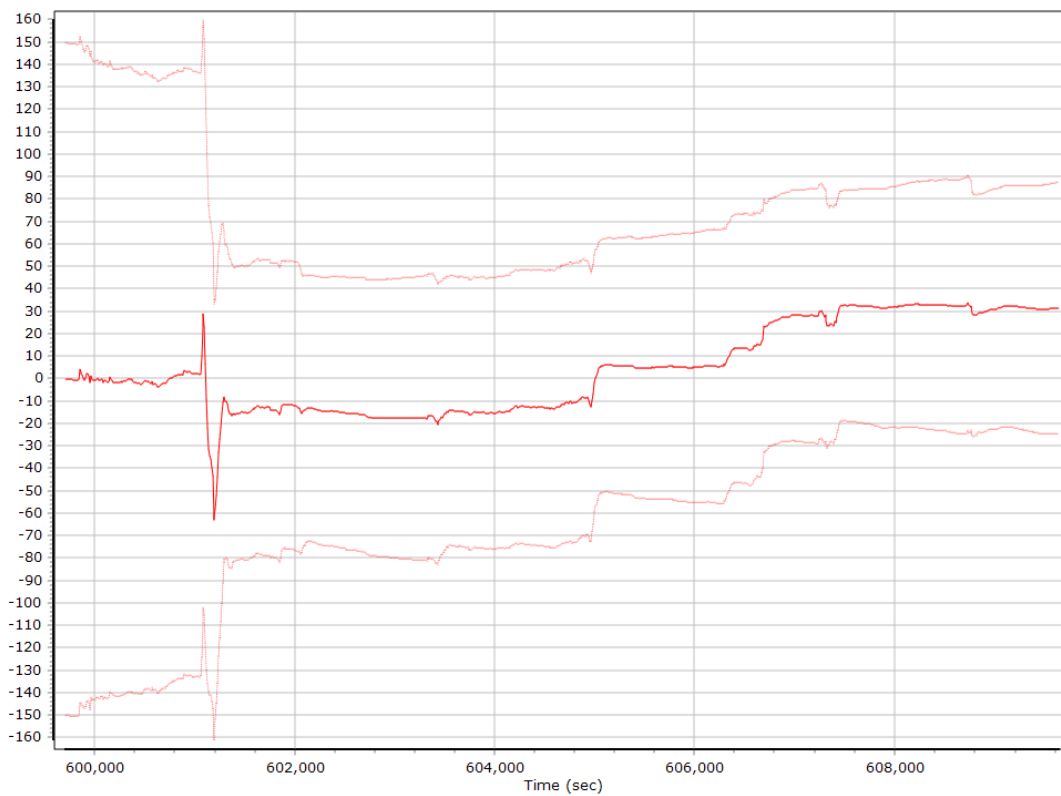
X Gyro Scale Error (ppm)



Y Gyro Scale Error (ppm)

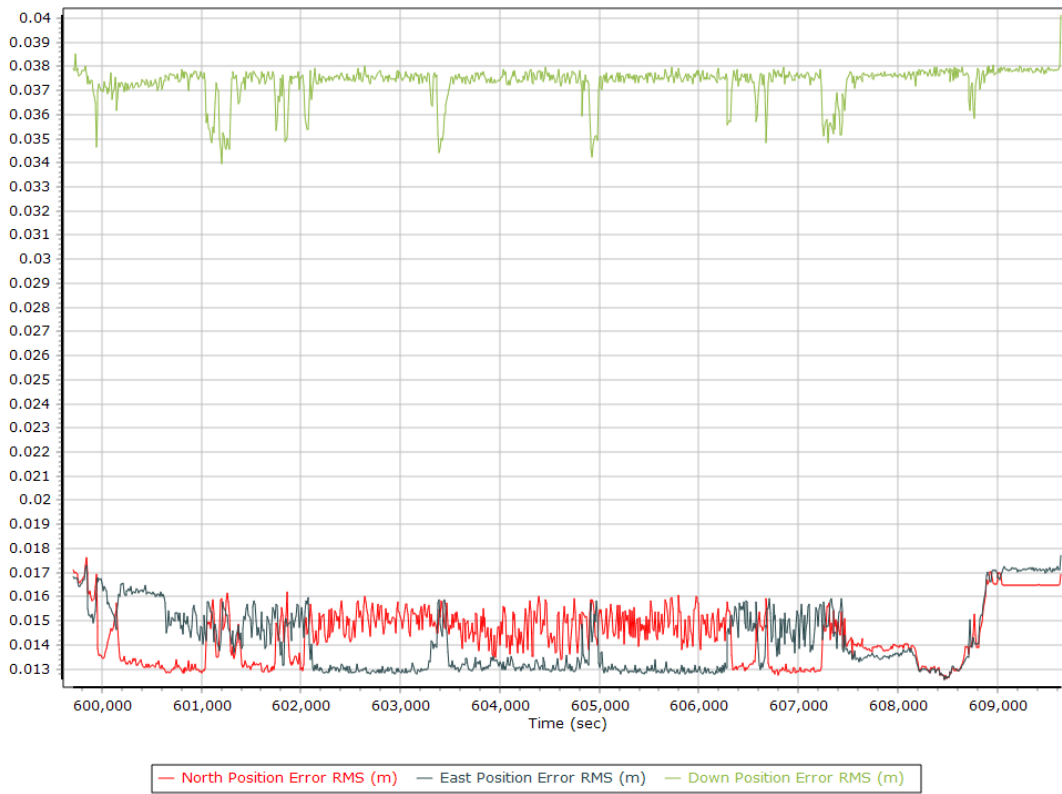


Z Gyro Scale Error (ppm)

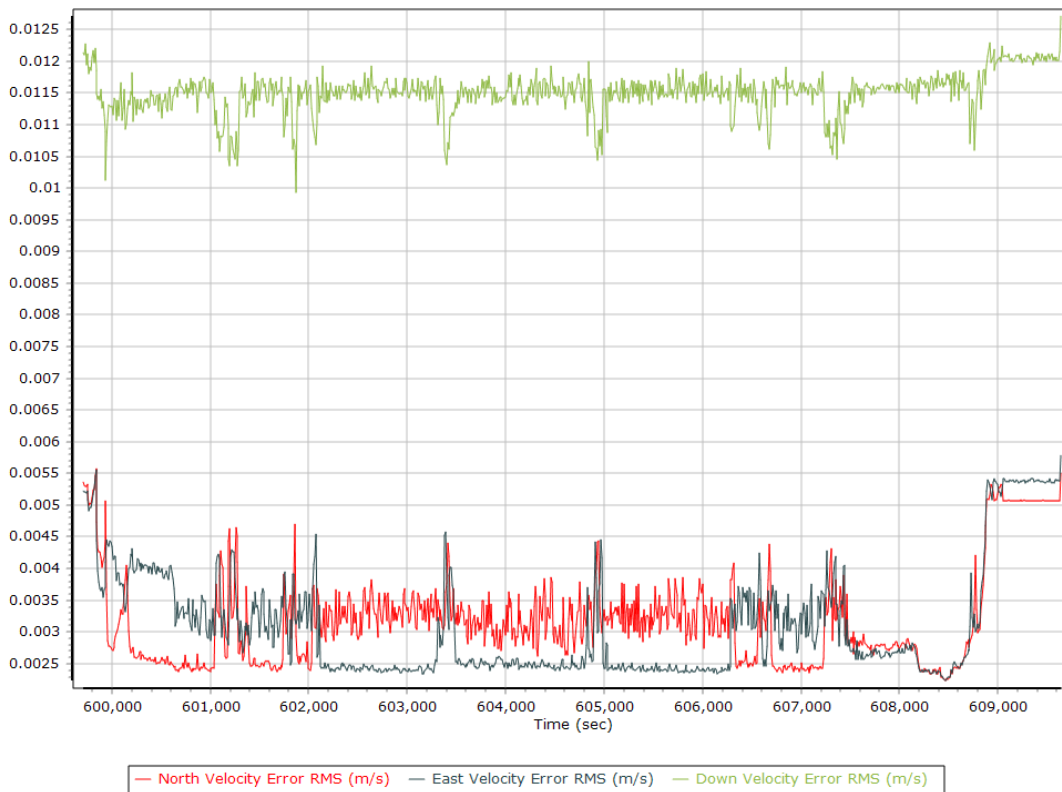


Smoothed Performance Metrics

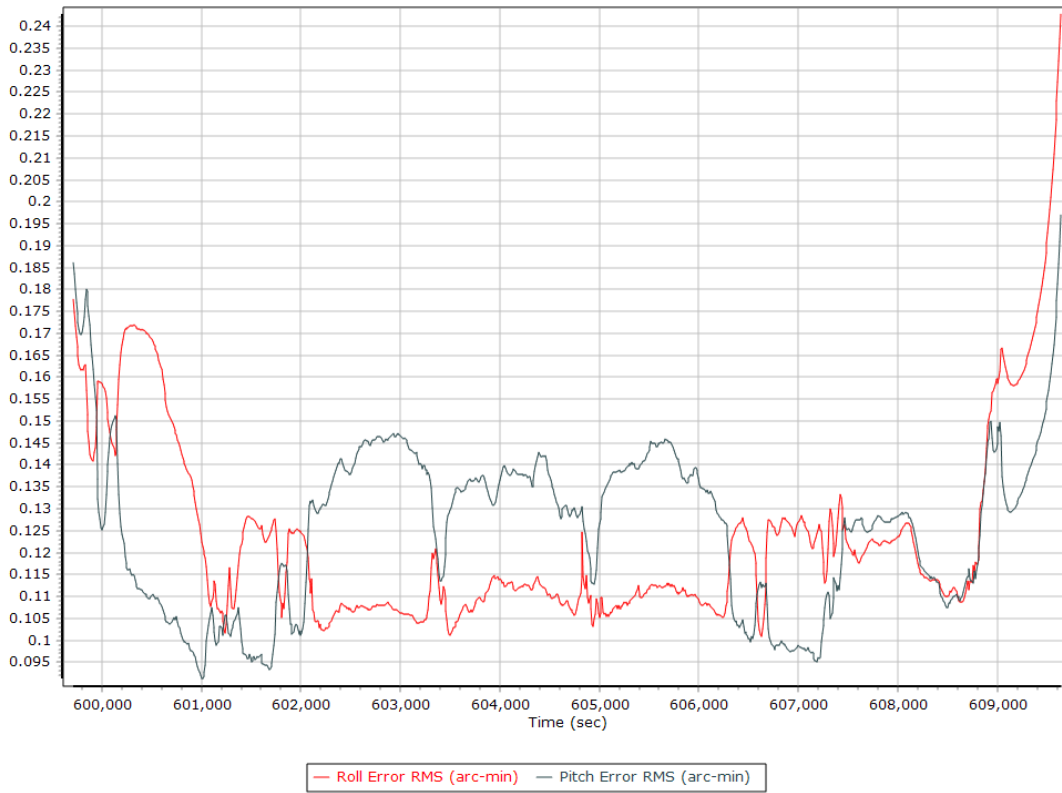
Position Error RMS (m)



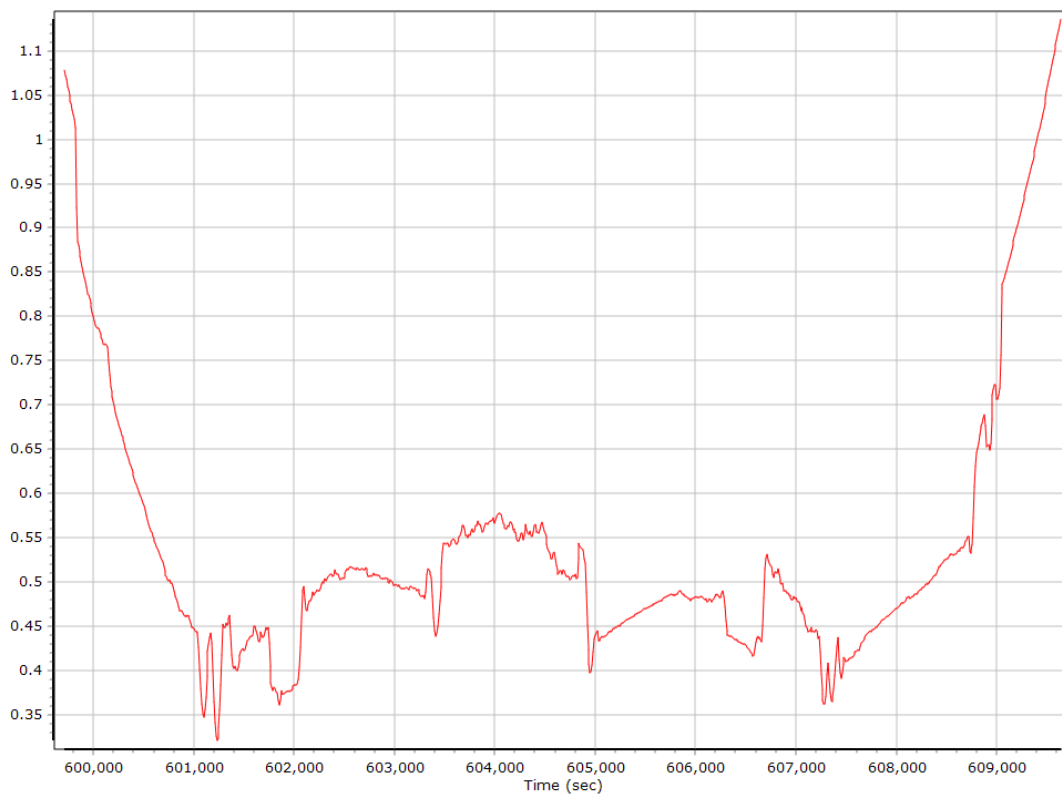
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

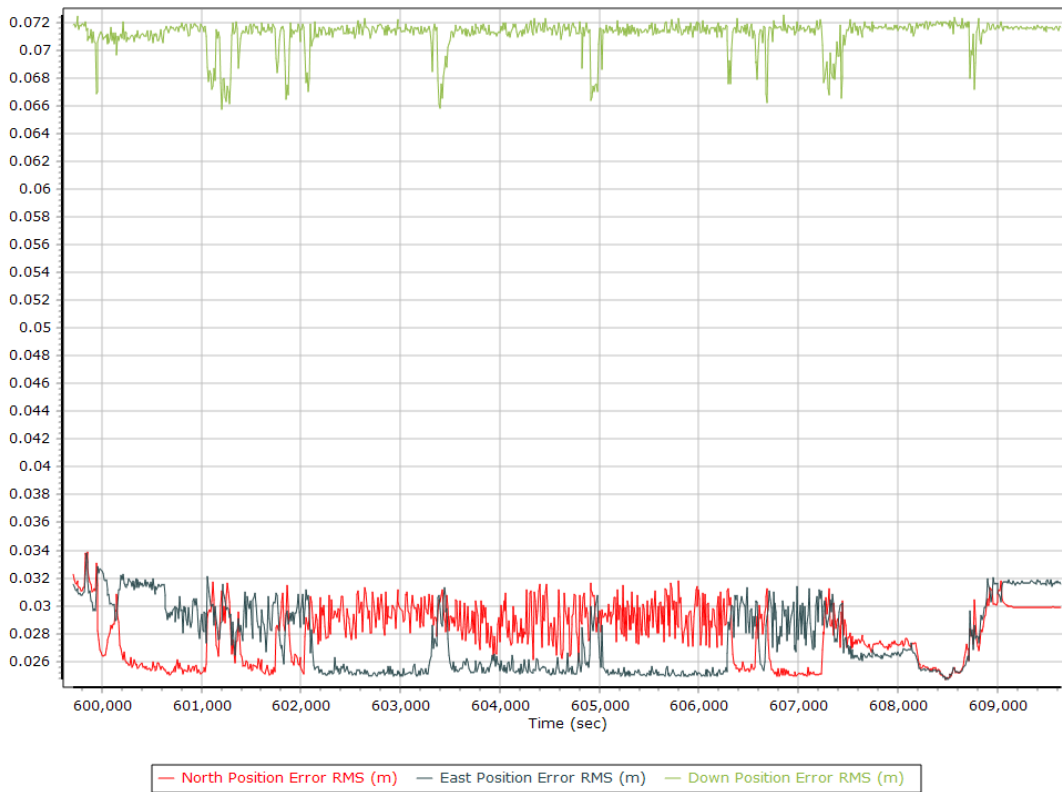


Heading Error RMS (arc-min)

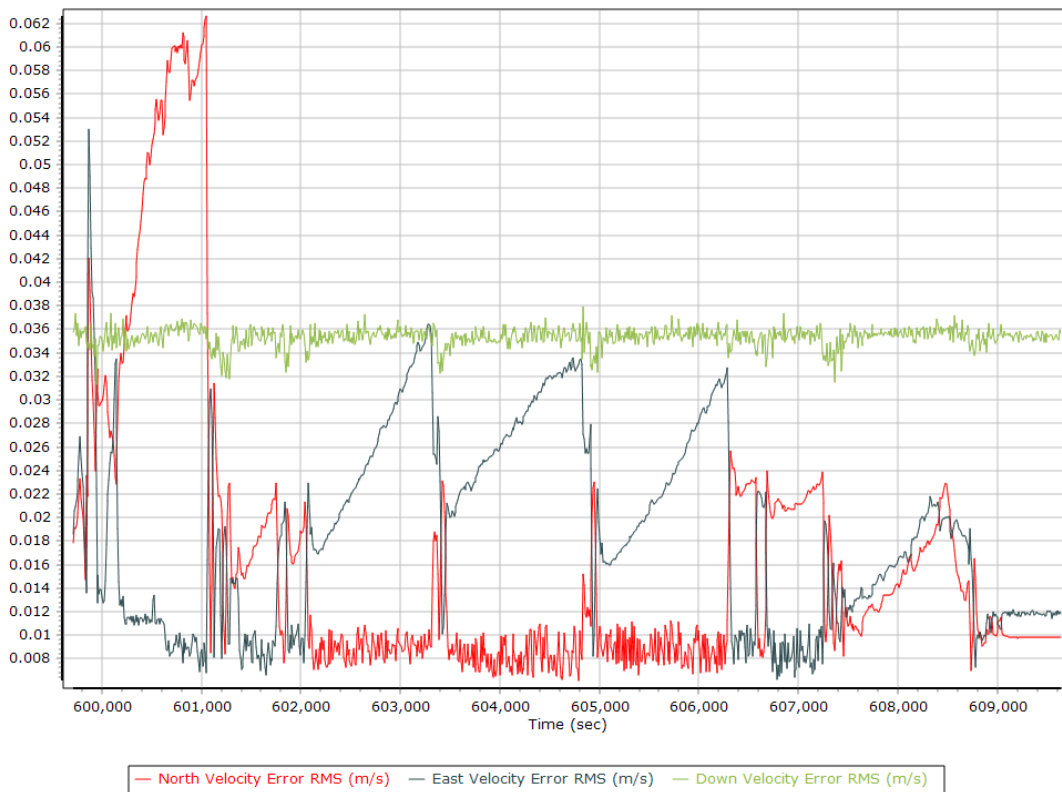


Forward Processed Performance Metrics

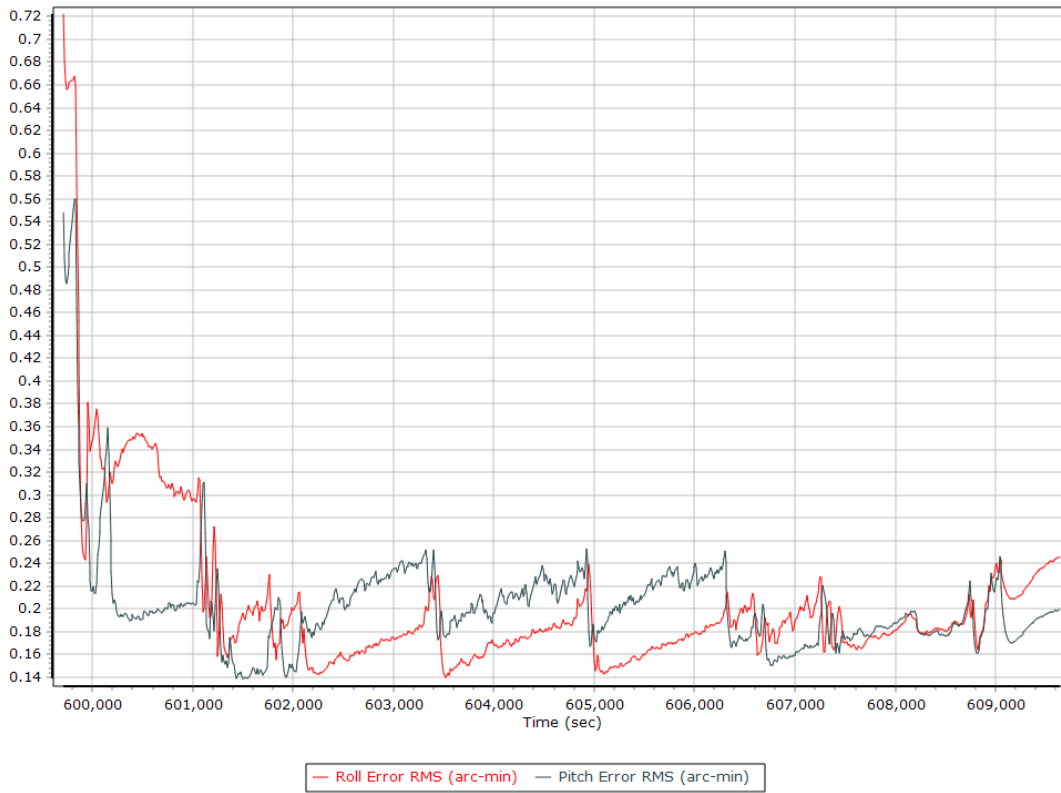
Position Error RMS (m)



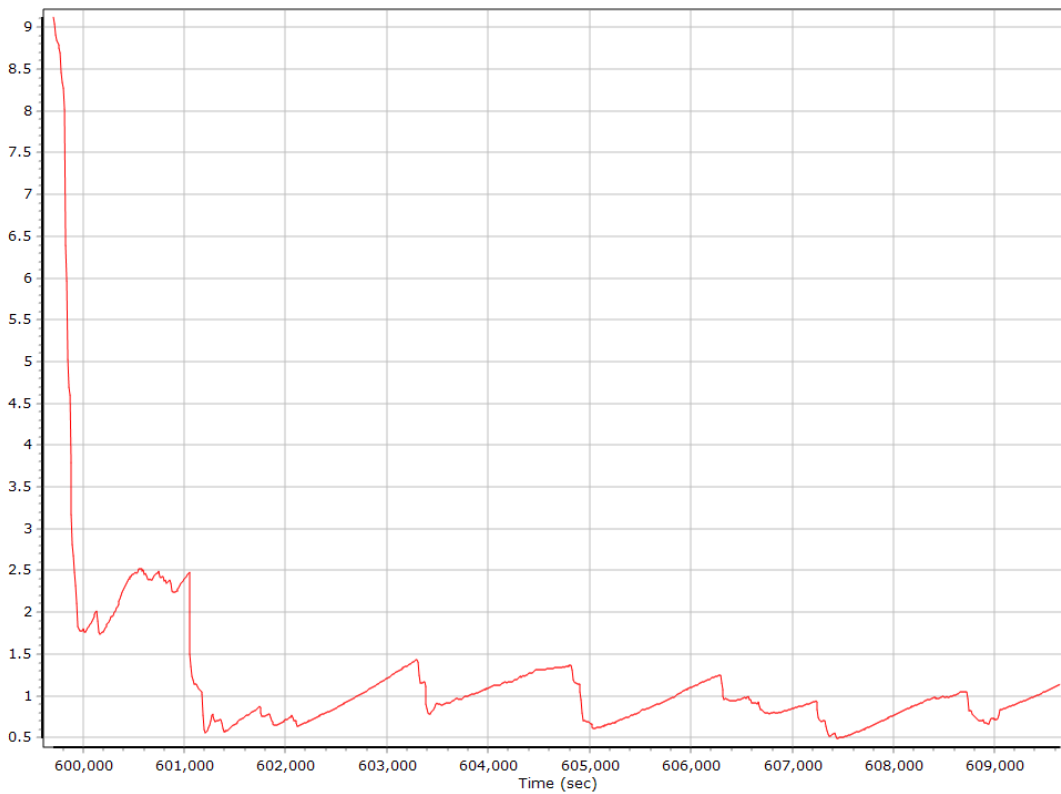
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

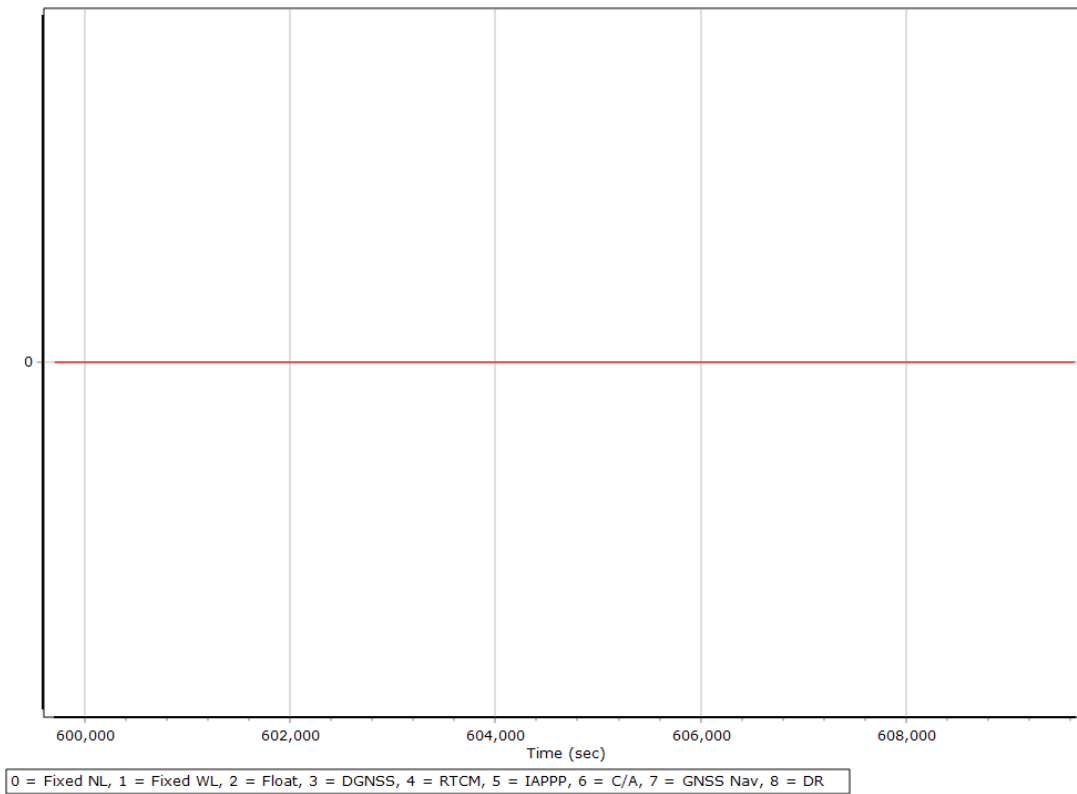


Heading Error RMS (arc-min)

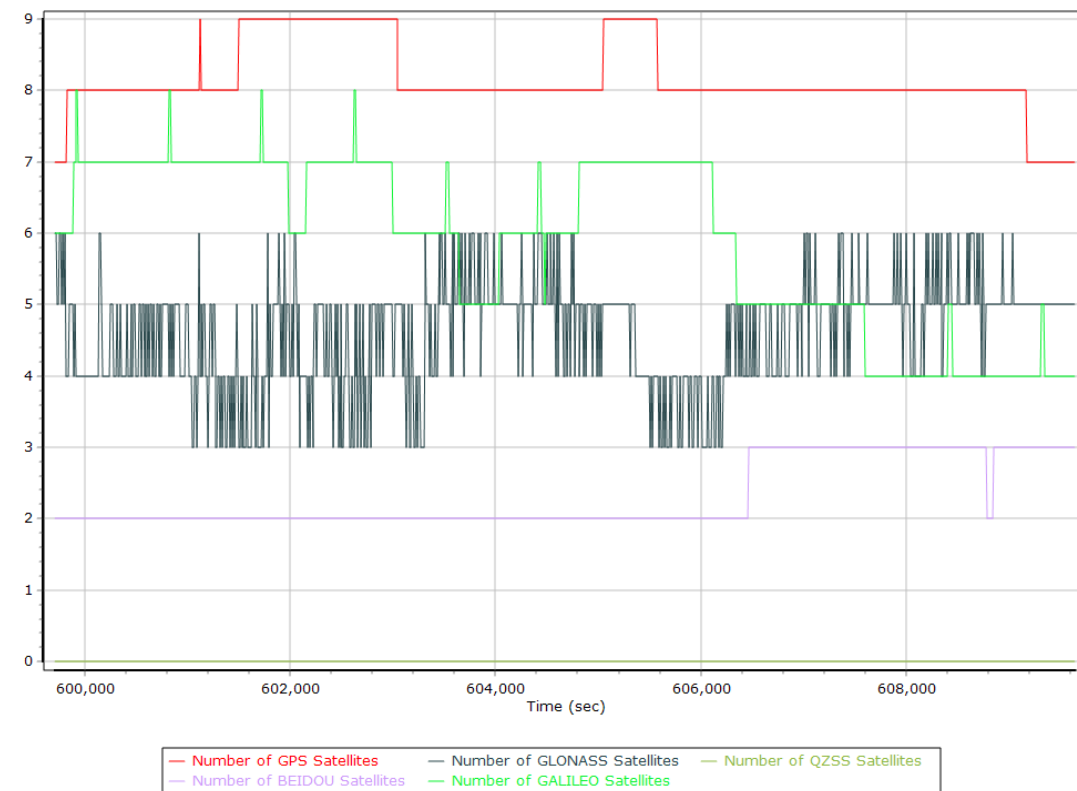


Forward Processed Solution Status

Processing Mode



Number of Satellites



Baseline Length

