



LiDAR Report:

LA_Catahoula_Concordia_2017_D17 D1

LiDAR Collection, Processing, and QA/QC

G17PD1255: LA_Catahoula_Concordia_2017_D17 D1

QL1 LiDAR

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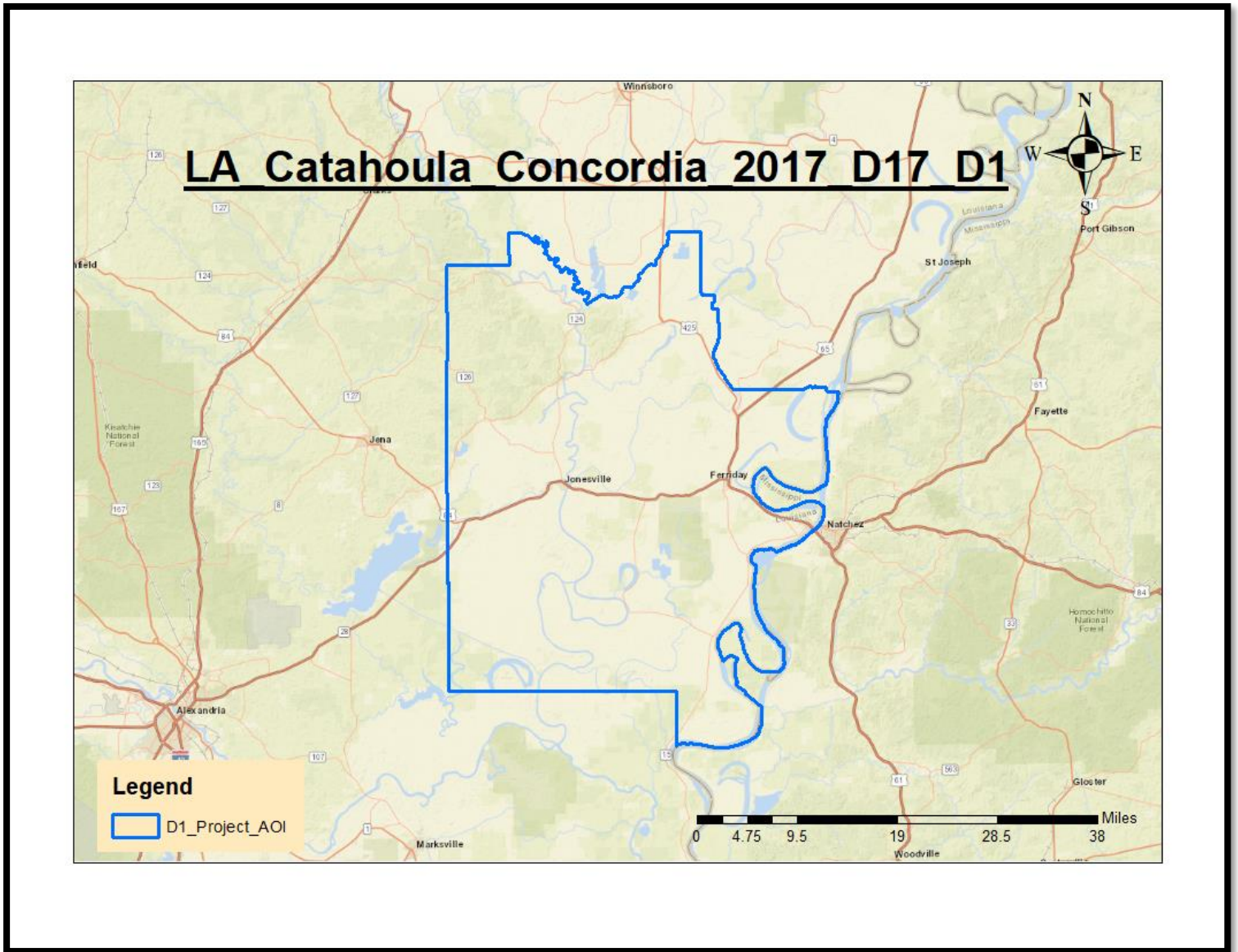


Image 1: LA_Catahoula_Concordia_2017_D17 D1 AOI

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1 Introduction and Specifications

Digital Aerial Solutions, LLC (Das) was tasked to collect and process a Light Detection and Ranging (LiDAR) derived elevated dataset for the **G17PD1255:LA_Catahoula_Concordia_2017_D17 D1**. The area encompasses approximately 1,261 square miles. Aerial LiDAR data was collected utilizing a Leica Terrain Mapper. The Terrain Mapper is a discrete return topographic LiDAR mapping system manufactured by Leica Geosystems. LiDAR data collected for **G17PD1255:LA_Catahoula_Concordia_2017_D17 D1** LiDAR survey has an Aggregated Nominal Pulse (ANPS) spacing of 0.35 meters (**QL1**) and includes up to 2 discrete return per pulse, along with intensity values of each return.

LIDAR datasets were post process to generate elevation point cloud swaths for each flight lines. Deliverables include tiled point cloud classified by land cover type, breaklines to support hydro-flattening of digital elevations models (DEM), intensity tiles, and bare-earth DEM titles. The point cloud deliverables are store in the LAS Version 1.4, point data record format 6. The tiling scheme for the tiled deliverables is a **1,000 x 1,000** meters grid. Tile naming convection is based on the Based on the U.S. National Grid and named according to the U.S. National Grid System based on the SW corner (**e.g. 12TVK0616**). All deliverables were generated in conformance with the U.S Geological Survey National Geospatial Program Guidelines and Base Specifications, Version 2.1.

2 Spatial Reference System

The spatial reference of the data is as follows:

Horizontal Spatial Reference

- Coordinates: Universal Transverse Mercator, UTM, Zone 15 North Meters (to 2 decimal places)
- Datum: North American Datum 1983 (2011), Meters (to 2 decimal places)

Vertical Spatial Reference

All datasets are available with orthometric elevation; point cloud datasets are also available with ellipsoid heights.

- Datum: North American Vertical Datum of 1988 (GEOID 12B)

3 LiDAR Acquisition

3.1 Survey Area

The **G17PD1255:LA_Catahoula_Concordia_2017_D17 D1** survey covers approximately 1,261 square miles located Catahoula and Concordia parishes in Louisiana. The project consisted of consisted of 95 flight lines totaling 3,206.94 nautical miles.

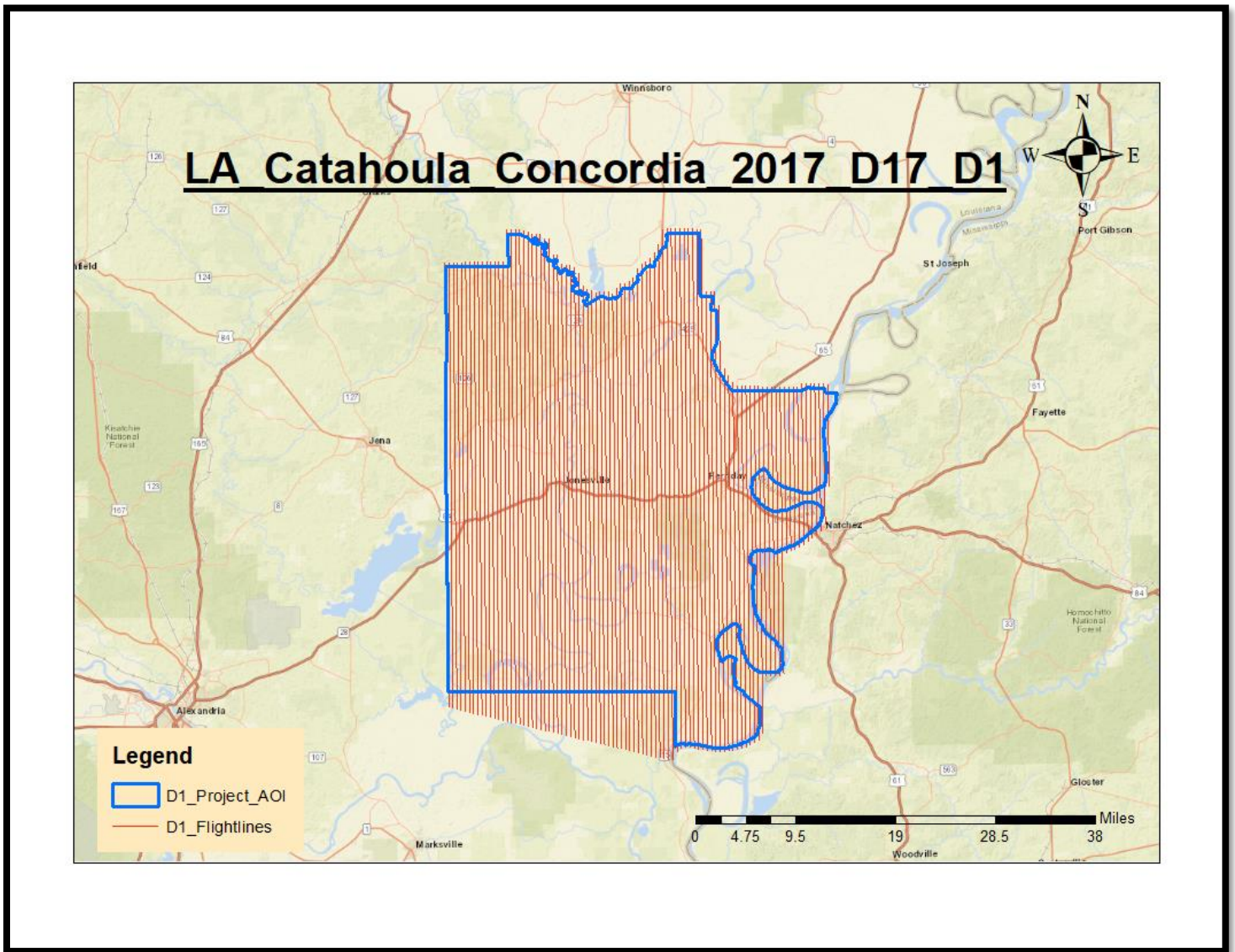


Image 2: LA_Cathoula_Concordia_2017_D17 D1 Flightlines

3.2 Acquisition Parameters

Acquisition parameters include the sensor configuration and the flight plan characteristics, and are selected based on a number of project specific criteria. Criteria reviewed include the required accuracies for the final dataset, the land cover types within the project survey area, and the required nominal pulse spacing. Aggregate Nominal Pulse Density (ANPD) for QL1 AOI is no less than 8ppm. The project parameters are summarized below.

Parameter (QL1)	Terrain Mapper
Flying Height Above Ground Level:	6,234 feet
Nominal Sidelap:	30-55%
Nominal Speed Over Ground:	170 Knots
Field of View:	40°
Laser Rate:	154.00 kHz
Scan Rate:	150.00 Hz
Maximum Across Track Spacing:	0.43meters
Maximum Along Track Spacing:	0.58 meters
Average point Spacing:	0.35 meters

Table 1: Flight Parameters

3.3 Acquisition Mission

The acquisition mission for **G179D1255: LA_Catahoula_Concordia_2017_D17 D1** QL1 LiDAR survey was coordinated for optimal collection conditions and was completed in 10 lifts from December 2nd 2019–December 14th, 2019. The GPS Session forms and NGS monument information can be found in **Appendix B**.

3.4 Airborne GPS/IMU

Airborne global positioning system (GPS) and inertial measurement unit (IMU) data was collected on the aircraft during the acquisition mission, providing sensor position and orientation information for geo-referencing the LiDAR data. Airborne GPS observations were collected at a frequency of 0.5Hz, and IMU observations are collected at a frequency of 200Hz.

Aircraft	Sensor	GPS Lever Arm (m)	IMU Lever Arm (m)
C441-N207SS	TM_9054	X: -0.054, Y: -0.199, Z: -1.131	X: -0.174, Y: -.0178, Z: 1.256

Table 2: Aircraft and Lever Arms

GPS data was collected with ground base stations during the acquisition missions, providing corrections to support differential post-processing of the airborne GPS. Base stations were setup at the following Airports St Hardy-Anders Field Natchez Adams County Airport (**KHEZ**). Ground GPS observations were collected at a frequency of 0.5Hz.

Name	Latitude	Longitude	Ellipsoid (m)
Hardy-Anders Field Natchez Adams County Airport (KHEZ)	31°36' 56.46414"	-91° 28' 38.66190"	55.417

Table 3: Base Stations Location

4 LiDAR Processing

4.1 Acquisition Post Processing

Inertial Explorer 8.90 software was used to compute inertial solution file (*.sol) for each mission using ground GPS base station (**KHEZ**) and Grafnet position coordinate in table above. The resulting solution was checked to ensure a minimum accuracy of +/- 0.10m, combined separation, for horizontal and vertical positions. Inertial Explorer methodology integrates Inertial Navigation Solution by processing the GPS data and Inertial Measurement Unit (IMU). The software applies the reference lever arms for the GPS and IMU during the process to determine the trajectory (position and orientation) of the LiDAR sensor during the acquisition mission. Inertial Explorer generated graphical results were reviewed to ensure that the IMU data was healthy.

Raw LiDAR sensor ranging data and the final solution sensor trajectory (*.sol), from Inertial Explorer, were processed in Leica's HxMap software to produce LiDAR point cloud swath for each flight line in LAS version 1.4 file format. Quality control of the swath point cloud was performed to validate proper functioning of the sensor system, full coverage of the project area and point density of the LiDAR data. Swath point clouds were assigned unique file source identification. The data was found to be complete and consistent with the sensor calibration parameters.

4.2 Geometric Calibration

LiDAR data calibration was done using Leica HxMap v2.6.0 software. HxMap is the common workflow platform for Leica airborne sensors. The processing workflow involves; Ingest, Block Creation, LiDAR Matching, Quality Assurance (QA) and Product Generation. LiDAR is processed in HxMap by generating point clouds from raw sensor data during the Ingest step. Noise filtering, sensor installation calibration and atmospheric condition parameters are also applied during the ingest process. Once all data is processed through ingest, they are assembled into a block for LiDAR Matching. The LiDAR Matching step resolves LiDAR registration errors which remain in the point clouds after sensor and installation calibration parameters are applied in the ingest step.

QA tool is run on the Block after LiDAR Matching to verify quality of results. QA results are reviewed to ensure that, 95% of patches < 5cm for Vertical Scan Direction and Vertical Line Separation. Ground control points are also included to assess absolute accuracy for the point cloud data. LiDAR products are finally generated in the Product Generation step as LAS swaths (LAS 1.4). Vertical (Z) shift (calculated from QA step) is also applied during the product generation. The exported LAS 1.4 swath data from HxMap is imported into GeoCue Group's product workflow management software, GeoCue v2017. The full point cloud is tiled into a manageable size for processing in TerraScan.

For **G17PD1255:LA_Catahoula_Concordia_2017_D17 D1** QL1 LiDAR project, the control lines listed below were used in data adjustment.

Point Id	Easting	Northing	Orth. Height
3_GS00002	636192.807	3499335.093	16.994
3_GS00007	602176.796	3474469.542	20.018
3_GS00001	616573.25	3517105.716	17.573
3_GS00003	621279.198	3497796.315	17.754
3_GS00004	599482.794	3509326.095	25.681
3_GS00005	607421.396	3483723.11	17.774
3_GS00006	608491.665	3470809.549	19.05

The final geometrically calibrated swath point clouds were compared to the bare-earth profile survey data. The data fit the profile surveys within the vertical accuracy tolerance specified for the project. Full documentation of the vertical accuracy checks maybe found in section 5.1.

4.3 Point Cloud Classification

Georeferenced information was applied to the swath point cloud LAS files. Geometrically calibrated swath point clouds were cut into USNG index, **1,000 meters x 1,000 meters** LAS 1.4 format tiles for point cloud classification and derived in LAS 1.4 format for product creation.

Tiled point cloud data was processed in Terrasolid’s TerraScan software to assign initial classification values. The TerraScan software provides a number of routines to algorithmically detect and assign points to their appropriate class. Points left unclassified by the algorithmic routine remain as Class 1– Processed, but unclassified. Automated classification routines assigned points to one of the following classes:

Class 1 – Processed, but unclassified

Class 2 – Bare-earth ground

Class 7 – Low Noise (low, manually identified, if necessary)

Class 9 — Water

Class 17 — Bridge Decks

Class 18 – High Noise (high, manually identified, if necessary)

Class 20 — Ignored Ground (Breakline Proximity)

Class 21- Snow (If present and identifiable)

Class 22- Temporal exclusion (typically non-favored data in intertidal zones)

Automated classification results were reviewed for each tiled point cloud, and manual edits made where necessary to correct for misclassified points. Points remaining in Class 1 after the automated classification routines were run were left in Class 1. Points falling outside of a 100-meter buffer of the project AOI polygon were excluded from the tiled point clouds.

4.4 Breakline Collection

Hydro break lines were compiled in ArcMap using the LiDAR intensity data and surface terrain model of the entire project area. After the collection of hydro lines all features were conflated and validated for monotonicity and vertical variance, to ensure that no points were floating above ground. The hydro break lines were then embedded into the LiDAR surface and used to create a hydro enforced DEM.

The data collected for the **G17PD1255:LA_Catahoula_Concordia_2017_D17 D1** survey maintained significant point density in the water, marsh, and swamp, limiting the usefulness of point density as guiding factor in breakline placement. Points classified as **Class 2 – Bare-earth ground**, falling within a tenth of a meter buffer of the collected breaklines, were reassigned to **Class 20 – Ignored Ground**. These points are excluded from the surface model during DEM generation to preserve the hydro-flattening characteristics of the breaklines.

4.5 DEM Generation

The final classified point clouds and collected breaklines were reviewed for conformance to the task order (scope of work). Within the LP360 software, points in Class 2 – Bare- earth ground and breaklines were combined to generate TIN elevation models for each tile, from which the bare-earth DEM tiles were interpolated and exported as GeoTIFF 32-bit floating point raster format “.tiff” format

5 Quality Control

5.1 Point Clouds

Accuracy and completeness of the LiDAR point clouds directly impacts the quality of all other derived LiDAR derived products. Ensuring a quality LiDAR dataset begins with proper mission planning and execution. Ground GPS base stations are located such that GPS baselines between the ground and airborne receivers do not exceed 30km. For the **G17PD1255:LA_Catahoula_Concordia_2017_D17 D1** project, two base stations were used to meet this requirement. Static alignment is performed both before take-off and after landing to allow for GPS integer ambiguity resolution. Sensor operators carefully monitor the LiDAR unit and its various subsystems during the acquisition mission to ensure proper function. Airborne GPS positional dilution of precision (PDOP) estimates are monitored to ensure they remain less than 3. The optical system is monitored to ensure there are no ranging errors encountered during the flight lines

During acquisition post-processing estimates of the trajectory data accuracy are reviewed to ensure they will support the required accuracies of the point cloud data. The trajectory accuracy is a function of the differentially corrected GPS data and the IMU data.

Geometric calibration quality control validates that the positional accuracy requirements of the project are met, and includes relative accuracy assessments for intra-swath (within) and inter-swath (between) accuracy, along with absolute accuracy assessments against project ground control.

Image 3 below, shows the swath to swath calibration assessment depicted by an intensity ortho created by using all returns, and colored by elevation difference between the swaths. The source deltas are an image type used for visualizing the elevation mismatch between overlapping swaths of LAS data. The granularity is controlled by the interval's selection. The interval size specifies the Z threshold at which the color bands apply. The interval used to create the difference elevation image is 0.040m. Colors shown as green indicates swath separation <0.040m, yellow indicates separation > 0.040m and <0.080m, red indicates separation >0.080m. All red areas depicted in the image have been reviewed and represent locations of high vegetation.



Image 3: Swath Separation Raster

This data set was produced to meet ASPRS “Positional Accuracy Standards for Digital Geospatial Data” (2014) for a 21.3(cm) RMSE_x / RMSE_y Horizontal Accuracy Class which equates to Positional Horizontal Accuracy = +/- 41.7cm at a 95%

Absolute vertical accuracy assessments for the point cloud data are made against ground check point data. For the **G17PD1255:LA_Catahoula_Concordia_2017_D17 D1** project, ground check point data consisted of the ground GPS base station and real-time kinematic (RTK) GPS techniques.

Check point locations were collected at .5 second intervals during the RTK survey. Points collected during the static pre-initialization and post-initialization was removed from the assessment so as not to bias the assessment.

Local TIN models of the elevation points are built around each ground check points. The tin model elevation is sampled at the horizontal position of the ground check point. The TIN model elevation and ground check point survey elevation values were used to calculate the Non-vegetated Vertical Accuracy (NVA) of the swath point clouds. Table 7 below shows the tested accuracy values for TIN and DEM data at 95% confidence level. The full calculations for all check points can be found in Appendix C.

Tested Accuracy	RMSE _z	NVA	VVA
Classified LiDAR	0.088	32	35
Digital Elevation Model	0.088	32	35

Table 7: Tested RMSE_z of NVA, NVA and VVA of LiDAR Point Cloud and Digital Elevation Model

Total #	# NVA	# VVA
67	32	35

Table 8: Number of Survey Points used to calculate accuracy of data.

The tiled point cloud products were reviewed for full coverage of the AOI and proper classification. As part of the QC process, TINs are built in the Terramodeler software for each tile using the ground class and the hydro-flattening breaklines. The TINs are reviewed for non-ground features, and edited where necessary to remove any remaining non-ground features. Points were also reviewed for absolute elevation, and points falling below the selected orthometric elevation for water were removed from the ground class.

5.2 Breaklines

The final breaklines in ESRI 3D shapefile format were reviewed for topological consistency and correct elevation. Breaklines features are continuous and do not have overlaps or dangles

5.3 Digital Elevation Models

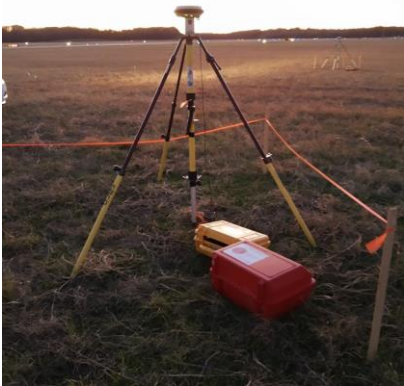
Digital elevation models (DEMs) were reviewed for conformance with the SOW and the Base Mapping Specification version 2.1 guidelines. DEM files were loaded in the Global Mapper software and inspected visually for edge matching between tiles, void areas within the project AOI, and proper coding of the NODATA values. DEM file naming was verified for consistency with the USNG index.

Appendix A. Flight Logs

Appendix B. Basestation GPS Session Forms

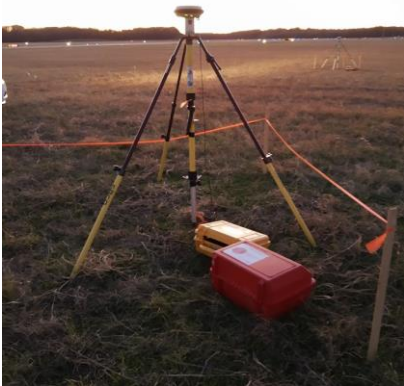
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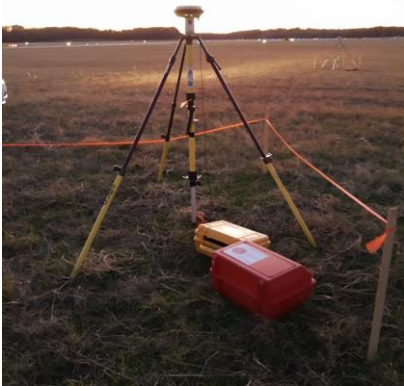
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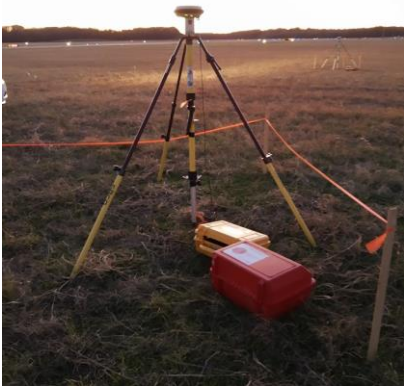
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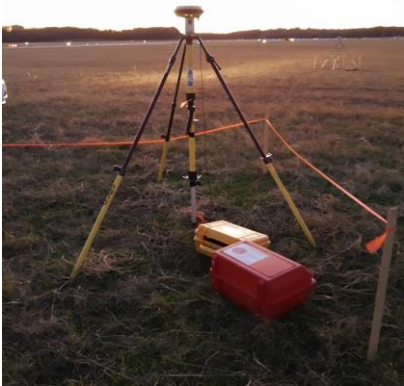
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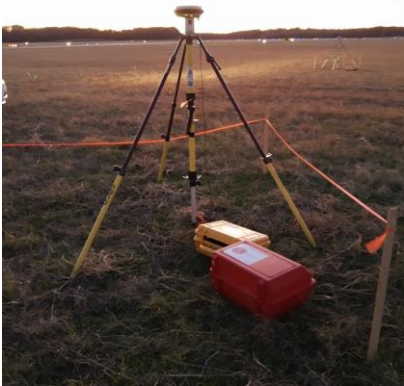
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Ending Antenna Height in Feet 1 2 3 AVG		Ending Antenna Height in Meters 1 2 3 AVG 1.5		Type of Measurement (circle one) TRUE VERTICAL <input checked="" type="radio"/> ARP
Antenna Reference Point (include and reference a dimensional diagram in Survey Report) (e.g., bottom edge of notch in ground plane, Page 5, Figure 2)				
Start Date (UTC) 12.04.2019		Start Time (UTC) 15:15		Approx. Lat. (if available) N 31 36 56.48549
End Date (UTC) 12.05.2019		End Time (UTC) 1:45		Approx. Long. (if available) W 91 17 39.44453
Describe any abnormalities and/or problems encountered during the session, include time of occurrence and duration.			Site Diagram/Setup-Photo 	

GPS SESSION FORM



Contract # / TO # G16PC00044		Client / Project Name U. S. GEOLOGICAL SURVEY Denver, Colorado LA_Catahoula_Concordia_2017_D17		Date 12.11.2019	
DAS Project No. 18003		Survey Firm DAS		Operator Name Cynthia Williams	
Monument Name/Designation KHEZ01			Exact Stamping <i>(include photo in survey report)</i> n/a		
Monument No./PID n/a		Collection Type <i>(circle one)</i> <input checked="" type="radio"/> ABGPS <input type="radio"/> STATIC <input type="radio"/> RTK		File Name <i>(receiver generated)</i> 6684_1211_151504.m00	
Receiver Manufacturer N/A		Receiver Model N/A		Receiver Serial No. N/A	
Data Collector Manufacturer Leica		Data Collector Model GS15		Data Collector Serial No. 1506684	
Antenna Part No. 4255298		Antenna Model N/A		Antenna Serial No. N/A	
Starting Antenna Height in Feet 1 2 3 AVG		Starting Antenna Height in Meters 1 2 3 AVG 1.5		Type of Measurement <i>(circle one)</i> TRUE VERTICAL <input checked="" type="radio"/> ARP	
Ending Antenna Height in Feet 1 2 3 AVG		Ending Antenna Height in Meters 1 2 3 AVG 1.5		Type of Measurement <i>(circle one)</i> TRUE VERTICAL <input checked="" type="radio"/> ARP	
Antenna Reference Point <i>(include and reference a dimensional diagram in Survey Report)</i> <i>(e.g., bottom edge of notch in ground plane, Page 5, Figure 2)</i>					
Start Date (UTC) 12.11.2019		Start Time (UTC) 22:14		Approx. Lat. <i>(if available)</i> N 31 36 56.50570	
End Date (UTC) 12.11.2019		End Time (UTC) 2:15		Approx. Long. <i>(if available)</i> W 91 17 38.72067	
Describe any abnormalities and/or problems encountered during the session, include time of occurrence and duration.			Site Diagram/Setup-Photo		

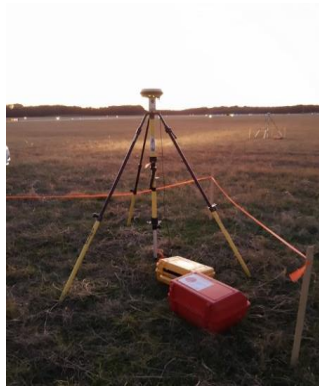
GPS SESSION FORM



Contract # / TO # G16PC00044		Client / Project Name U. S. GEOLOGICAL SURVEY Denver, Colorado LA_Catahoula_Concordia_2017_D17		Date 12.11.2019	
DAS Project No. 18003		Survey Firm DAS		Operator Name Cynthia Williams	
Monument Name/Designation KHEZ02			Exact Stamping <i>(include photo in survey report)</i> n/a		
Monument No./PID n/a		Collection Type <i>(circle one)</i> <input checked="" type="radio"/> ABGPS <input type="radio"/> STATIC <input type="radio"/> RTK		File Name <i>(receiver generated)</i> 1514_1211_182304.m00	
Receiver Manufacturer N/A		Receiver Model N/A		Receiver Serial No. N/A	
Data Collector Manufacturer Leica		Data Collector Model GS15		Data Collector Serial No. 1501514	
Antenna Part No. 3725413		Antenna Model N/A		Antenna Serial No. N/A	
Starting Antenna Height in Feet 1 2 3 AVG		Starting Antenna Height in Meters 1 2 3 AVG 1.5		Type of Measurement <i>(circle one)</i> TRUE VERTICAL <input checked="" type="radio"/> ARP	
Ending Antenna Height in Feet 1 2 3 AVG		Ending Antenna Height in Meters 1 2 3 AVG 1.5		Type of Measurement <i>(circle one)</i> TRUE VERTICAL <input checked="" type="radio"/> ARP	
Antenna Reference Point <i>(include and reference a dimensional diagram in Survey Report)</i> <i>(e.g., bottom edge of notch in ground plane, Page 5, Figure 2)</i>					
Start Date (UTC) 12.11.2019		Start Time (UTC) 22:25		Approx. Lat. <i>(if available)</i> N 31 36 56.52102	
End Date (UTC) 12.11.2019		End Time (UTC) 2:15		Approx. Long. <i>(if available)</i> W 91 17 39.45885	
Describe any abnormalities and/or problems encountered during the session, include time of occurrence and duration.			Site Diagram/Setup-Photo		

GPS SESSION FORM



Contract # / TO # G16PC00044		Client / Project Name U. S. GEOLOGICAL SURVEY Denver, Colorado LA_Catahoula_Concordia_2017_D17		Date 12.12.2019
DAS Project No. 18003		Survey Firm DAS		Operator Name Cynthia Williams
Monument Name/Designation KHEZ01			Exact Stamping (include photo in survey report) n/a	
Monument No./PID n/a		Collection Type (circle one) <input checked="" type="radio"/> ABGPS <input type="radio"/> STATIC <input type="radio"/> RTK		File Name (receiver generated) 6684_1211_151504.m00
Receiver Manufacturer N/A		Receiver Model N/A		Receiver Serial No. N/A
Data Collector Manufacturer Leica		Data Collector Model GS15		Data Collector Serial No. 1506684
Antenna Part No. 4255298		Antenna Model N/A		Antenna Serial No. N/A
Starting Antenna Height in Feet 1 2 3 AVG		Starting Antenna Height in Meters 1 2 3 AVG 1.5		Type of Measurement (circle one) TRUE VERTICAL <input checked="" type="radio"/> ARP
Ending Antenna Height in Feet 1 2 3 AVG		Ending Antenna Height in Meters 1 2 3 AVG 1.5		Type of Measurement (circle one) TRUE VERTICAL <input checked="" type="radio"/> ARP
Antenna Reference Point (include and reference a dimensional diagram in Survey Report) (e.g., bottom edge of notch in ground plane, Page 5, Figure 2)				
Start Date (UTC) 12.12.2019		Start Time (UTC) 13:45		Approx. Lat. (if available) N 31 36 56.50570
End Date (UTC) 12.12.2019		End Time (UTC) 20:04		Approx. Long. (if available) W 91 17 38.72067
Describe any abnormalities and/or problems encountered during the session, include time of occurrence and duration.			Site Diagram/Setup-Photo 	

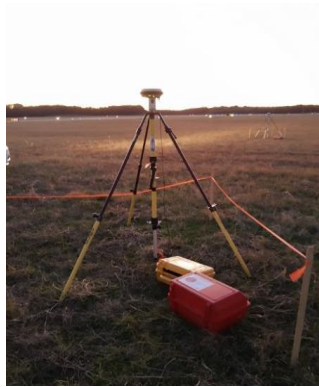
GPS SESSION FORM



Contract # / TO # G16PC00044		Client / Project Name U. S. GEOLOGICAL SURVEY Denver, Colorado LA_Catahoula_Concordia_2017_D17		Date 12.12.2019	
DAS Project No. 18003		Survey Firm DAS		Operator Name Cynthia Williams	
Monument Name/Designation KHEZ02			Exact Stamping <i>(include photo in survey report)</i> n/a		
Monument No./PID n/a		Collection Type <i>(circle one)</i> <input checked="" type="radio"/> ABGPS <input type="radio"/> STATIC <input type="radio"/> RTK		File Name <i>(receiver generated)</i> 1514_1211_182304.m00	
Receiver Manufacturer N/A		Receiver Model N/A		Receiver Serial No. N/A	
Data Collector Manufacturer Leica		Data Collector Model GS15		Data Collector Serial No. 1501514	
Antenna Part No. 3725413		Antenna Model N/A		Antenna Serial No. N/A	
Starting Antenna Height in Feet 1 2 3 AVG		Starting Antenna Height in Meters 1 2 3 AVG 1.5		Type of Measurement <i>(circle one)</i> TRUE VERTICAL <input checked="" type="radio"/> ARP	
Ending Antenna Height in Feet 1 2 3 AVG		Ending Antenna Height in Meters 1 2 3 AVG 1.5		Type of Measurement <i>(circle one)</i> TRUE VERTICAL <input checked="" type="radio"/> ARP	
Antenna Reference Point <i>(include and reference a dimensional diagram in Survey Report)</i> <i>(e.g., bottom edge of notch in ground plane, Page 5, Figure 2)</i>					
Start Date (UTC) 12.12.2019		Start Time (UTC) 13:40		Approx. Lat. <i>(if available)</i> N 31 36 56.52102	
End Date (UTC) 12.12.2019		End Time (UTC) 20:05		Approx. Long. <i>(if available)</i> W 91 17 39.45885	
Describe any abnormalities and/or problems encountered during the session, include time of occurrence and duration.			Site Diagram/Setup-Photo		

GPS SESSION FORM



Contract # / TO # G16PC00044		Client / Project Name U. S. GEOLOGICAL SURVEY Denver, Colorado LA_Catahoula_Concordia_2017_D17		Date 12.14.2019
DAS Project No. 18003		Survey Firm DAS		Operator Name Cynthia Williams
Monument Name/Designation KHEZ01			Exact Stamping (include photo in survey report) n/a	
Monument No./PID n/a		Collection Type (circle one) <input checked="" type="radio"/> ABGPS <input type="radio"/> STATIC <input type="radio"/> RTK		File Name (receiver generated) 6684_1211_151504.m00
Receiver Manufacturer N/A		Receiver Model N/A		Receiver Serial No. N/A
Data Collector Manufacturer Leica		Data Collector Model GS15		Data Collector Serial No. 1506684
Antenna Part No. 4255298		Antenna Model N/A		Antenna Serial No. N/A
Starting Antenna Height in Feet 1 2 3 AVG		Starting Antenna Height in Meters 1 2 3 AVG 1.5		Type of Measurement (circle one) TRUE VERTICAL <input checked="" type="radio"/> ARP
Ending Antenna Height in Feet 1 2 3 AVG		Ending Antenna Height in Meters 1 2 3 AVG 1.5		Type of Measurement (circle one) TRUE VERTICAL <input checked="" type="radio"/> ARP
Antenna Reference Point (include and reference a dimensional diagram in Survey Report) (e.g., bottom edge of notch in ground plane, Page 5, Figure 2)				
Start Date (UTC) 12.14.2019		Start Time (UTC) 19:32		Approx. Lat. (if available) N 31 36 56.50570
End Date (UTC) 12.14.2019		End Time (UTC) 3:34		Approx. Long. (if available) W 91 17 38.72067
Describe any abnormalities and/or problems encountered during the session, include time of occurrence and duration.			Site Diagram/Setup-Photo 	

GPS SESSION FORM



Contract # / TO # G16PC00044		Client / Project Name U. S. GEOLOGICAL SURVEY Denver, Colorado LA_Catahoula_Concordia_2017_D17		Date 12.14.2019	
DAS Project No. 18003		Survey Firm DAS		Operator Name Cynthia Williams	
Monument Name/Designation KHEZ02			Exact Stamping (include photo in survey report) n/a		
Monument No./PID n/a		Collection Type (circle one) <input checked="" type="radio"/> ABGPS <input type="radio"/> STATIC <input type="radio"/> RTK		File Name (receiver generated) 1514_1211_182304.m00	
Receiver Manufacturer N/A		Receiver Model N/A		Receiver Serial No. N/A	
Data Collector Manufacturer Leica		Data Collector Model GS15		Data Collector Serial No. 1501514	
Antenna Part No. 3725413		Antenna Model N/A		Antenna Serial No. N/A	
Starting Antenna Height in Feet 1 2 3 AVG		Starting Antenna Height in Meters 1 2 3 AVG 1.5		Type of Measurement (circle one) TRUE VERTICAL <input checked="" type="radio"/> ARP	
Ending Antenna Height in Feet 1 2 3 AVG		Ending Antenna Height in Meters 1 2 3 AVG 1.5		Type of Measurement (circle one) TRUE VERTICAL <input checked="" type="radio"/> ARP	
Antenna Reference Point (include and reference a dimensional diagram in Survey Report) (e.g., bottom edge of notch in ground plane, Page 5, Figure 2)					
Start Date (UTC) 12.14.2019		Start Time (UTC) 19:36		Approx. Lat. (if available) N 31 36 56.52102	
End Date (UTC) 12.14.2019		End Time (UTC) 3:38		Approx. Long. (if available) W 91 17 39.45885	
Describe any abnormalities and/or problems encountered during the session, include time of occurrence and duration.			Site Diagram/Setup-Photo		

Appendix C. Vertical Accuracy Calculations



Project Information

Prepared By: DAS
Project Name: G17PD1255: LA_Catahoula_Concordia_2017_D17
Sensor Info: TM90524
Required Nominal Pulse Spacing: 0.35
Vendor Name: Digital Aerial Solutions LLC
Units: Meters
Percent of Extent Tolerance: Extents Not Checked
Date of Aquisition: Start: 1/24/2018 Finish: 12/15/2019

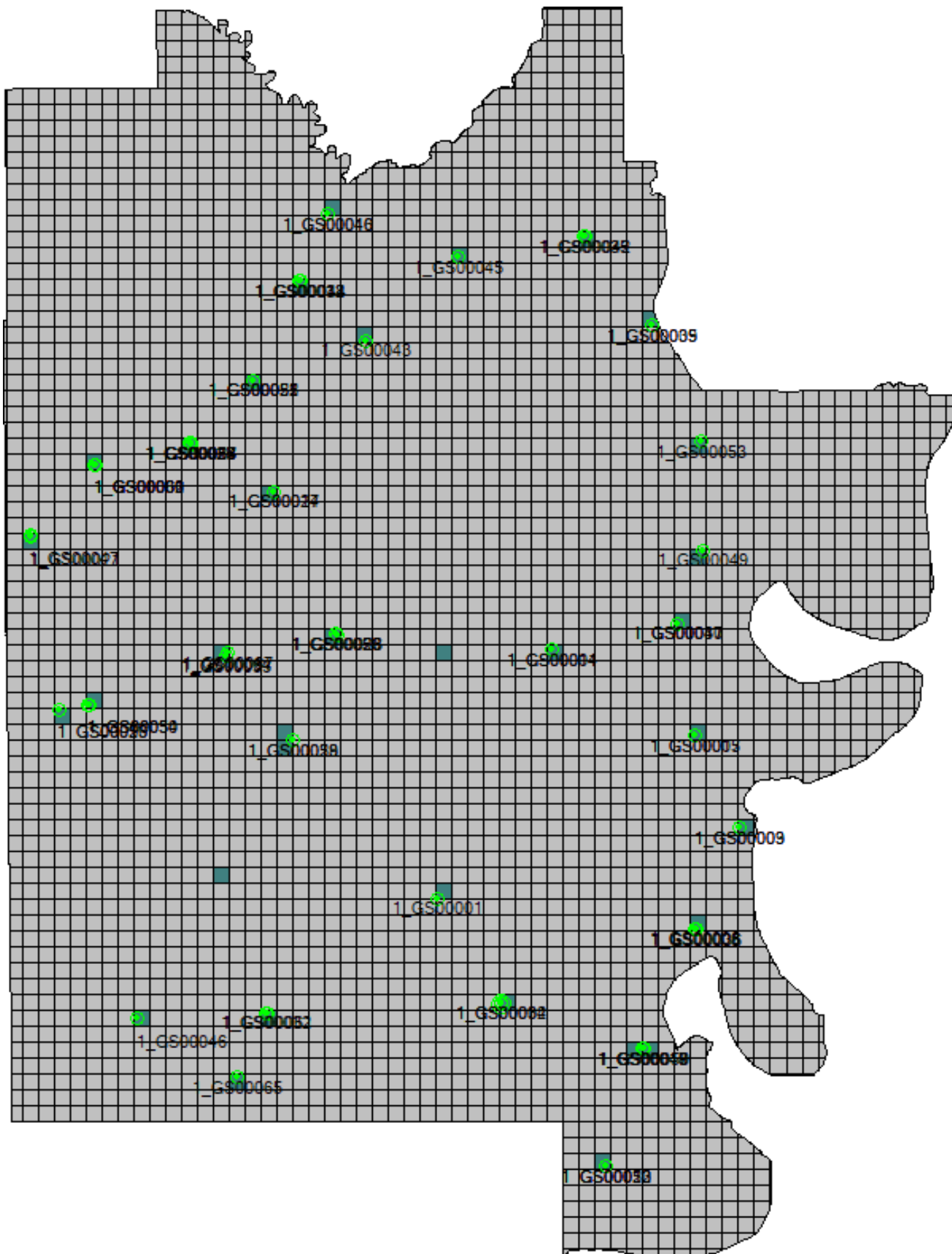
Metadata Information

Tile Index:
Filename: Tile_Index_DAS_Delivery1_Use.shp
Number of Polys: 0
Intensity:
Tile Index Attribute: Not Specified
Data Filename: Not Specified

DEM:
Tile Index Attribute: Name
Data Filename: TIFF

LAS:
Tile Index Attribute: Name
Data Filename: LAS

Tiled-Data Area



LiDAR Accuracy Assessment Summary

LC Type	# Points	NVA	VVA	RMSE Z
LAS		95% Confidence	95 Percentile	
Bare Earth	18	0.163		0.083
High Vegetation	6		0.163	0.087
Low Vegetation	24		0.163	0.093
Med Vegetation	5		0.127	0.100
Urban Terrian	14	0.158		0.081
NVA Total:	32	0.161		0.082
VVA Total:	35		0.163	0.093
Total:	67			0.088
DEM		95% Confidence	95 Percentile	
Bare Earth	18	0.168		0.085
High Vegetation	6		0.161	0.089
Low Vegetation	24		0.186	0.098
Med Vegetation	5		0.130	0.100
Urban Terrian	14	0.158		0.081
NVA Total:	32	0.163		0.083
VVA Total:	35		0.176	0.097
Total:	67			0.088
			Units:	Meters

Coordinates and Offsets of Analyzed Locations

	ID			Z1	Z DEM	Z LAS	
		Survey X	Survey Y				
				LC Type	ΔZ DEM	ΔZ LAS	
1)	<input checked="" type="checkbox"/>	1_GS00002					
		625085.067	3475452.375	14.182	14.316	14.314	
				Bare Earth	0.134	0.132	
2)	<input checked="" type="checkbox"/>	1_GS00003					
		640044.118	3486471.016	24.642	24.765	24.765	
				Bare Earth	0.123	0.123	
3)	<input checked="" type="checkbox"/>	1_GS00004					
		628279.633	3497672.884	16.624	16.738	16.738	
				Bare Earth	0.114	0.114	
4)	<input checked="" type="checkbox"/>	1_GS00007					
		637248.915	3492276.021	16.461	16.532	16.532	
				Bare Earth	0.071	0.071	
5)	<input checked="" type="checkbox"/>	1_GS00008					
		637294.59	3480113.842	24.97	25.048	25.038	
				Bare Earth	0.078	0.068	
6)	<input checked="" type="checkbox"/>	1_GS00009					
		640058.895	3486478.4	26.32	26.408	26.396	
				Bare Earth	0.088	0.076	
7)	<input checked="" type="checkbox"/>	1_GS00010					
		636204.663	3499312.685	16.899	16.974	16.972	
				Bare Earth	0.075	0.073	

Coordinates and Offsets of Analyzed Locations (Continued)

	ID			Z1	Z DEM	Z LAS	
		Survey X	Survey Y				
			LC Type				ΔZ DEM
8)	<input checked="" type="checkbox"/>	1_GS00013					
		631644.674	3465227.496	13.612	13.641	13.643	
				Bare Earth	0.029	0.031	
9)	<input checked="" type="checkbox"/>	1_GS00017					
		634003.396	3472614.767	15.221	15.22	15.223	
				Bare Earth	-0.001	0.002	
10)	<input checked="" type="checkbox"/>	1_GS00018					
		605560.123	3510671.327	21.367	21.357	21.358	
				Bare Earth	-0.01	-0.009	
11)	<input checked="" type="checkbox"/>	1_GS00020					
		631643.82	3465211.885	13.854	13.847	13.843	
				Bare Earth	-0.007	-0.011	
12)	<input checked="" type="checkbox"/>	1_GS00021					
		595515.297	3504770.325	17.657	17.638	17.634	
				Bare Earth	-0.019	-0.023	
13)	<input checked="" type="checkbox"/>	1_GS00022					
		609481.409	3514627.253	31.193	31.157	31.157	
				Bare Earth	-0.036	-0.036	
14)	<input checked="" type="checkbox"/>	1_GS00024					
		605549.053	3510662.067	21.622	21.562	21.565	
				Bare Earth	-0.06	-0.057	

Coordinates and Offsets of Analyzed Locations (Continued)

		ID				
		Survey X	Survey Y	Z1	Z DEM	Z LAS
				LC Type	ΔZ DEM	ΔZ LAS
15)	<input checked="" type="checkbox"/>	1_GS00026				
		614720.819	3498682.782	17.413	17.335	17.342
				Bare Earth	-0.078	-0.071
16)	<input checked="" type="checkbox"/>	1_GS00030				
		599165.202	3494219.386	17.128	17.025	17.025
				Bare Earth	-0.103	-0.103
17)	<input checked="" type="checkbox"/>	1_GS00031				
		599544.233	3509339.302	26.57	26.449	26.453
				Bare Earth	-0.121	-0.117
18)	<input checked="" type="checkbox"/>	1_GS00033				
		607809.779	3497279.117	17.238	17.085	17.089
				Bare Earth	-0.153	-0.149
19)	<input checked="" type="checkbox"/>	1_GS00001				
		621026.397	3482034.442	16.477	16.601	16.596
				Urban Terrian	0.124	0.119
20)	<input checked="" type="checkbox"/>	1_GS00005				
		634583.74	3518053.574	19.976	20.081	20.077
				Urban Terrian	0.105	0.101
21)	<input checked="" type="checkbox"/>	1_GS00006				
		637276.974	3480122.289	23.188	23.266	23.278
				Urban Terrian	0.078	0.09

Coordinates and Offsets of Analyzed Locations (Continued)

		ID				
		Survey X	Survey Y	Z1	Z DEM	Z LAS
				LC Type	ΔZ DEM	ΔZ LAS
22)	<input checked="" type="checkbox"/>	1_GS00011				
		628251.504	3497692.465	17.44	17.495	17.497
				Urban Terrian	0.055	0.057
23)	<input checked="" type="checkbox"/>	1_GS00012				
		612385.7	3520862.09	17.643	17.683	17.677
				Urban Terrian	0.04	0.034
24)	<input checked="" type="checkbox"/>	1_GS00015				
		637259.042	3492277.689	16.714	16.735	16.735
				Urban Terrian	0.021	0.021
25)	<input checked="" type="checkbox"/>	1_GS00016				
		614186.442	3525062.401	16.698	16.714	16.711
				Urban Terrian	0.016	0.013
26)	<input checked="" type="checkbox"/>	1_GS00019				
		633982.296	3472618.091	15.921	15.914	15.912
				Urban Terrian	-0.007	-0.009
27)	<input checked="" type="checkbox"/>	1_GS00023				
		597248.794	3493929.788	16.344	16.292	16.293
				Urban Terrian	-0.052	-0.051
28)	<input checked="" type="checkbox"/>	1_GS00025				
		605521.26	3510657.335	22.29	22.235	22.229
				Urban Terrian	-0.055	-0.061

Coordinates and Offsets of Analyzed Locations (Continued)

	ID			Z1	Z DEM	Z LAS	
		Survey X	Survey Y				
			LC Type				ΔZ DEM
29)	<input checked="" type="checkbox"/>	1_GS00027					
		610750.224	3507630.915	19.458	19.375	19.376	
				Urban Terrian	-0.083	-0.082	
30)	<input checked="" type="checkbox"/>	1_GS00028					
		614729.876	3498650.112	17.365	17.268	17.276	
				Urban Terrian	-0.097	-0.089	
31)	<input checked="" type="checkbox"/>	1_GS00029					
		611970.997	3492011.484	17.59	17.481	17.485	
				Urban Terrian	-0.109	-0.105	
32)	<input checked="" type="checkbox"/>	1_GS00032					
		610316.289	3474847.048	18.77	18.632	18.624	
				Urban Terrian	-0.138	-0.146	
33)	<input checked="" type="checkbox"/>	1_GS00034					
		625087.364	3475479.348	14.234	14.41	14.397	
				Low Vegetation	0.176	0.163	
34)	<input checked="" type="checkbox"/>	1_GS00035					
		630290.688	3523686.524	16.926	17.112	17.094	
				Low Vegetation	0.186	0.168	
35)	<input checked="" type="checkbox"/>	1_GS00036					
		637332.888	3480088.59	16.645	16.834	16.799	
				Low Vegetation	0.189	0.154	

Coordinates and Offsets of Analyzed Locations (Continued)

	ID			Z1	Z DEM	Z LAS	
		Survey X	Survey Y				
			LC Type				ΔZ DEM
36)	<input checked="" type="checkbox"/>	1_GS00038					
		612413.586	3520881.676	17.325	17.475	17.474	
				Low Vegetation	0.15	0.149	
37)	<input checked="" type="checkbox"/>	1_GS00039					
		634598.564	3518082.613	19.697	19.845	19.852	
				Low Vegetation	0.148	0.155	
38)	<input checked="" type="checkbox"/>	1_GS00041					
		636141.286	3499317.507	16.35	16.49	16.489	
				Low Vegetation	0.14	0.139	
39)	<input checked="" type="checkbox"/>	1_GS00042					
		630351.669	3523643.326	16.418	16.542	16.544	
				Low Vegetation	0.124	0.126	
40)	<input checked="" type="checkbox"/>	1_GS00046					
		602186.752	3474507.917	15.38	15.465	15.456	
				Low Vegetation	0.085	0.076	
41)	<input checked="" type="checkbox"/>	1_GS00047					
		595471.404	3504876.033	17.726	17.79	17.785	
				Low Vegetation	0.064	0.059	
42)	<input checked="" type="checkbox"/>	1_GS00048					
		633938.842	3472612.297	14.454	14.512	14.515	
				Low Vegetation	0.058	0.061	

Coordinates and Offsets of Analyzed Locations (Continued)

	ID			Z1	Z DEM	Z LAS	
		Survey X	Survey Y				
			LC Type				ΔZ DEM
43)	<input checked="" type="checkbox"/>	1_GS00049					
		637798.94	3503926.008	17.726	17.762	17.762	
				Low Vegetation	0.036	0.036	
44)	<input checked="" type="checkbox"/>	1_GS00050					
		634046.707	3472600.958	14.954	14.994	14.991	
				Low Vegetation	0.04	0.037	
45)	<input checked="" type="checkbox"/>	1_GS00051					
		609463.448	3514608.815	30.93	30.949	30.953	
				Low Vegetation	0.019	0.023	
46)	<input checked="" type="checkbox"/>	1_GS00052					
		631660.016	3465199.583	13.612	13.631	13.631	
				Low Vegetation	0.019	0.019	
47)	<input checked="" type="checkbox"/>	1_GS00053					
		637666.765	3510772.162	18.24	18.254	18.266	
				Low Vegetation	0.014	0.026	
48)	<input checked="" type="checkbox"/>	1_GS00054					
		599131.332	3494216.271	16.261	16.279	16.27	
				Low Vegetation	0.018	0.009	
49)	<input checked="" type="checkbox"/>	1_GS00055					
		609457.283	3514631.928	30.71	30.707	30.703	
				Low Vegetation	-0.003	-0.007	

Coordinates and Offsets of Analyzed Locations (Continued)

	ID			Z1	Z DEM	Z LAS	
		Survey X	Survey Y				
			LC Type				ΔZ DEM
50)	<input checked="" type="checkbox"/>	1_GS00056					
		597238.251	3493955.861	16.314	16.304	16.306	
				Low Vegetation	-0.01	-0.008	
51)	<input checked="" type="checkbox"/>	1_GS00057					
		605534.822	3510655.156	21.832	21.821	21.815	
				Low Vegetation	-0.011	-0.017	
52)	<input checked="" type="checkbox"/>	1_GS00059					
		614705.957	3498689.658	17.396	17.363	17.369	
				Low Vegetation	-0.033	-0.027	
53)	<input checked="" type="checkbox"/>	1_GS00060					
		599505.497	3509314.153	26.194	26.15	26.147	
				Low Vegetation	-0.044	-0.047	
54)	<input checked="" type="checkbox"/>	1_GS00061					
		610328.717	3474859.983	16.028	15.961	15.964	
				Low Vegetation	-0.067	-0.064	
55)	<input checked="" type="checkbox"/>	1_GS00062					
		599491.493	3509318.178	24.44	24.363	24.377	
				Low Vegetation	-0.077	-0.063	
56)	<input checked="" type="checkbox"/>	1_GS00067					
		607831.64	3497462.762	17.207	17.072	17.068	
				Low Vegetation	-0.135	-0.139	

Coordinates and Offsets of Analyzed Locations (Continued)

	ID			Z1	Z DEM	Z LAS	
		Survey X	Survey Y				
			LC Type				ΔZ DEM
57)	<input checked="" type="checkbox"/>	1_GS00040					
		614204.979	3525050.739	16.794	16.924	16.921	
				Med Vegetation	0.13	0.127	
58)	<input checked="" type="checkbox"/>	1_GS00043					
		616580.136	3517120.444	17.457	17.559	17.564	
				Med Vegetation	0.102	0.107	
59)	<input checked="" type="checkbox"/>	1_GS00044					
		612441.09	3520852.796	17.083	17.168	17.179	
				Med Vegetation	0.085	0.096	
60)	<input checked="" type="checkbox"/>	1_GS00045					
		622319.127	3522342.106	20.891	20.973	20.974	
				Med Vegetation	0.082	0.083	
61)	<input checked="" type="checkbox"/>	1_GS00066					
		599527.808	3509328.39	25.938	25.847	25.855	
				Med Vegetation	-0.091	-0.083	
62)	<input checked="" type="checkbox"/>	1_GS00014					
		610731.181	3507640.082	18.559	18.581	18.588	
				High Vegetation	0.022	0.029	
63)	<input checked="" type="checkbox"/>	1_GS00037					
		636119.478	3499320.122	16.251	16.412	16.414	
				High Vegetation	0.161	0.163	

Coordinates and Offsets of Analyzed Locations (Continued)

		ID				
		Survey X	Survey Y	Z1	Z DEM	Z LAS
				LC Type	ΔZ DEM	ΔZ LAS
64)	<input checked="" type="checkbox"/>	1_GS00058				
		611953.852	3491993.991	17.282	17.253	17.249
				High Vegetation	-0.029	-0.033
65)	<input checked="" type="checkbox"/>	1_GS00063				
		605537.709	3510638.599	21.644	21.581	21.593
				High Vegetation	-0.063	-0.051
66)	<input checked="" type="checkbox"/>	1_GS00064				
		607805.834	3497318.133	17.138	17.047	17.057
				High Vegetation	-0.091	-0.081
67)	<input checked="" type="checkbox"/>	1_GS00065				
		608489.192	3470783.796	18.285	18.192	18.196
				High Vegetation	-0.093	-0.089

LAS

Nonvegetated Vertical Accuracy

LandCover Type: Bare Earth, Urban Terrian

Minimum DZ: -0.149

Maximum DZ: 0.132

Mean DZ: 0

Mean Magnitude DZ: 0.265

Number Observations: 32

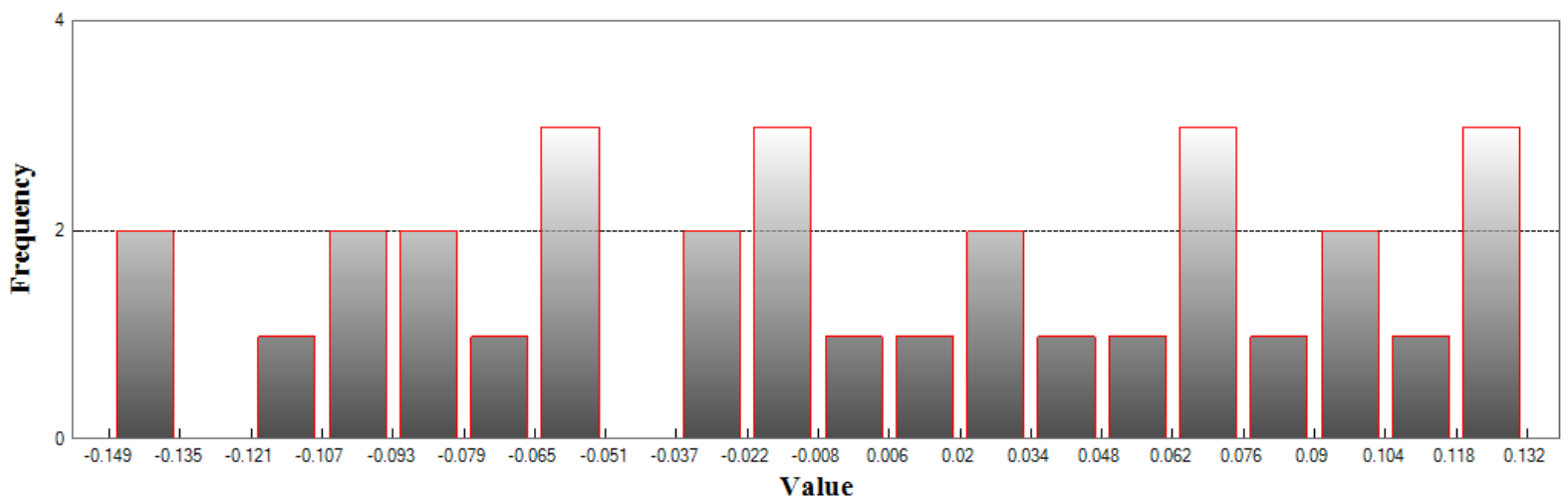
Standard Deviation DZ: 0.083

RMSE Z: 0.082

95% Confidence Level Z: 0.161

Units: Meters

Histogram



Min: -0.149
 Max: 0.132
 Number Of Bins: 20
 Bin Interval: 0.014

LAS (Continued)

Vegetated Vertical Accuracy

LandCover Type: High Vegetation

Minimum DZ: -0.089

Maximum DZ: 0.163

Mean DZ: -0.01

Mean Magnitude DZ: 0.272

Number Observations: 6

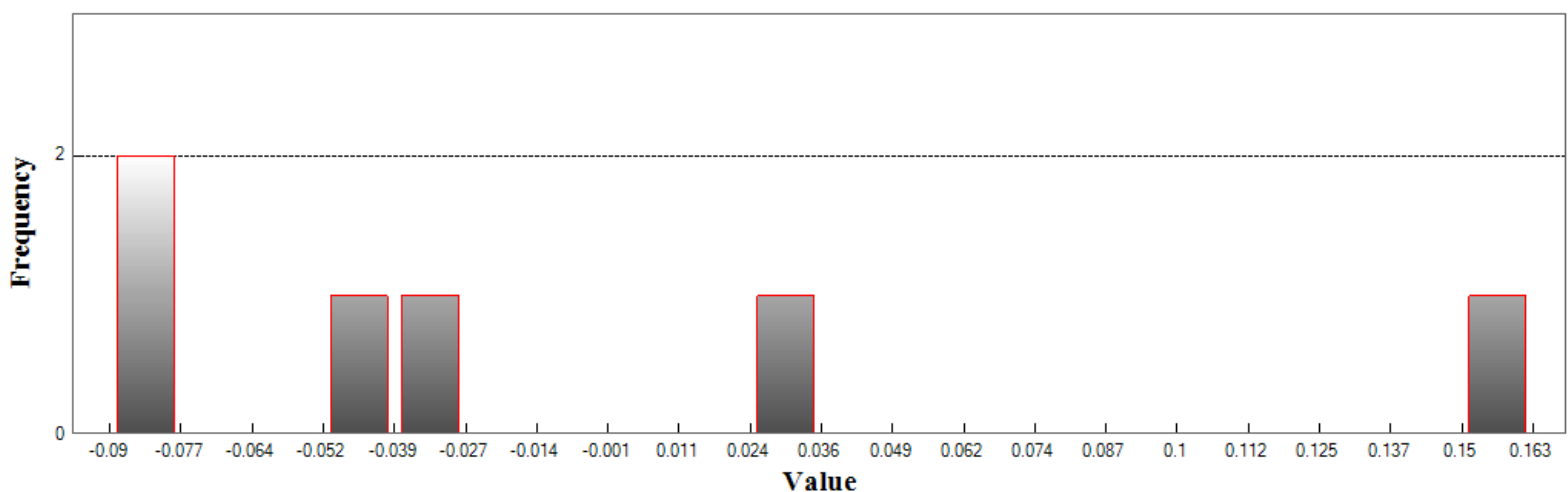
Standard Deviation DZ: 0.095

RMSE Z: 0.087

95th Percentile: 0.163

Units: Meters

Histogram



Min: -0.089

Max: 0.163

Number Of Bins: 20

Bin Interval: 0.013

LAS (Continued)

Vegetated Vertical Accuracy

LandCover Type: Low Vegetation

Minimum DZ: -0.139

Maximum DZ: 0.168

Mean DZ: 0.043

Mean Magnitude DZ: 0.272

Number Observations: 24

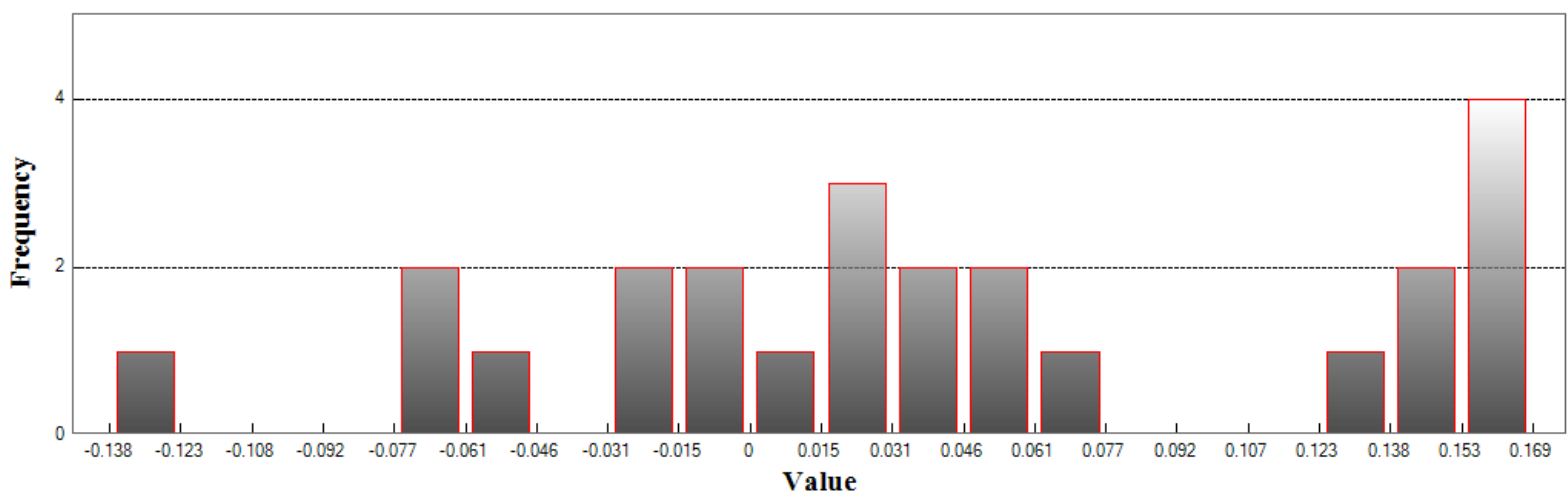
Standard Deviation DZ: 0.084

RMSE Z: 0.093

95th Percentile: 0.163

Units: Meters

Histogram



Min: -0.139

Max: 0.168

Number Of Bins: 20

Bin Interval: 0.015

LAS (Continued)

Vegetated Vertical Accuracy

LandCover Type: Med Vegetation

Minimum DZ: -0.083

Maximum DZ: 0.127

Mean DZ: 0.066

Mean Magnitude DZ: 0.315

Number Observations: 5

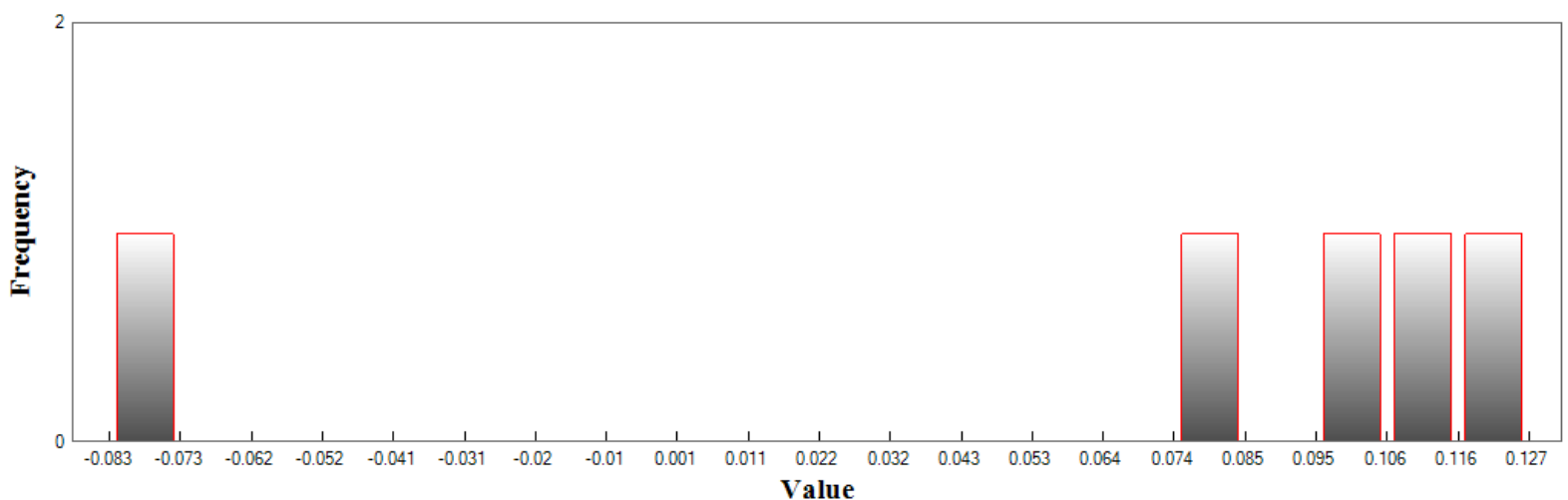
Standard Deviation DZ: 0.085

RMSE Z: 0.1

95th Percentile: 0.127

Units: Meters

Histogram



Min: -0.083

Max: 0.127

Number Of Bins: 20

Bin Interval: 0.01

DEM

Nonvegetated Vertical Accuracy

LandCover Type: Bare Earth, Urban Terrian

Minimum DZ: -0.153

Maximum DZ: 0.134

Mean DZ: 0.001

Mean Magnitude DZ: 0.267

Number Observations: 32

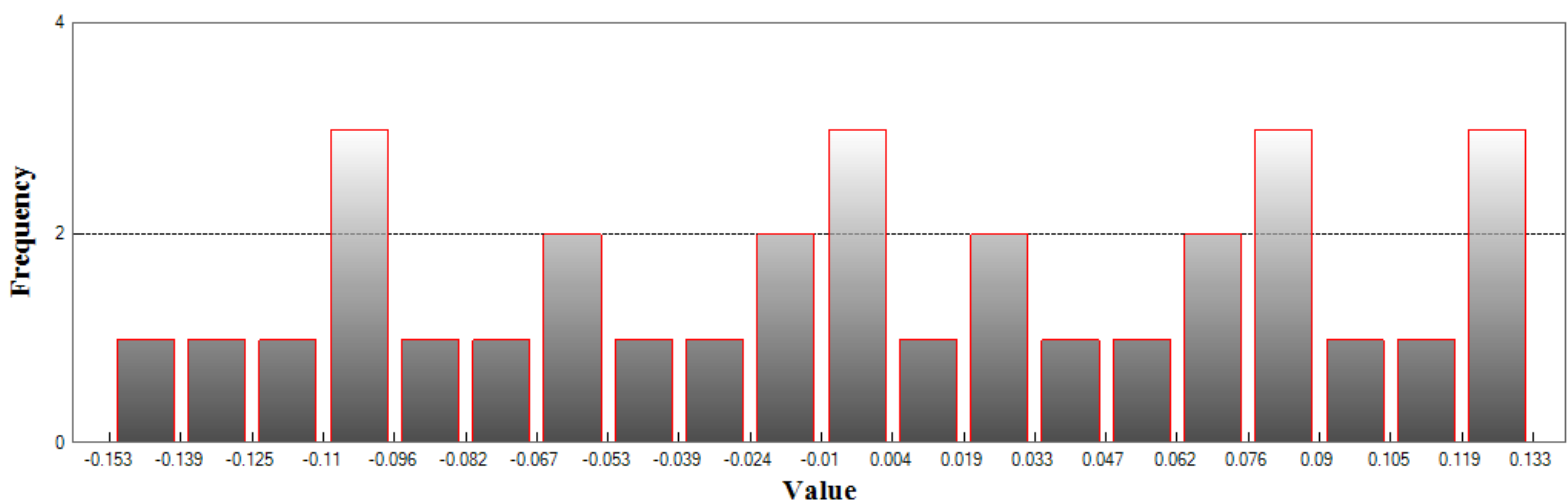
Standard Deviation DZ: 0.085

RMSE Z: 0.083

95% Confidence Level Z: 0.163

Units: Meters

Histogram



Min: -0.153

Max: 0.134

Number Of Bins: 20

Bin Interval: 0.014

DEM (Continued)

Vegetated Vertical Accuracy

LandCover Type: High Vegetation

Minimum DZ: -0.093

Maximum DZ: 0.161

Mean DZ: -0.015

Mean Magnitude DZ: 0.276

Number Observations: 6

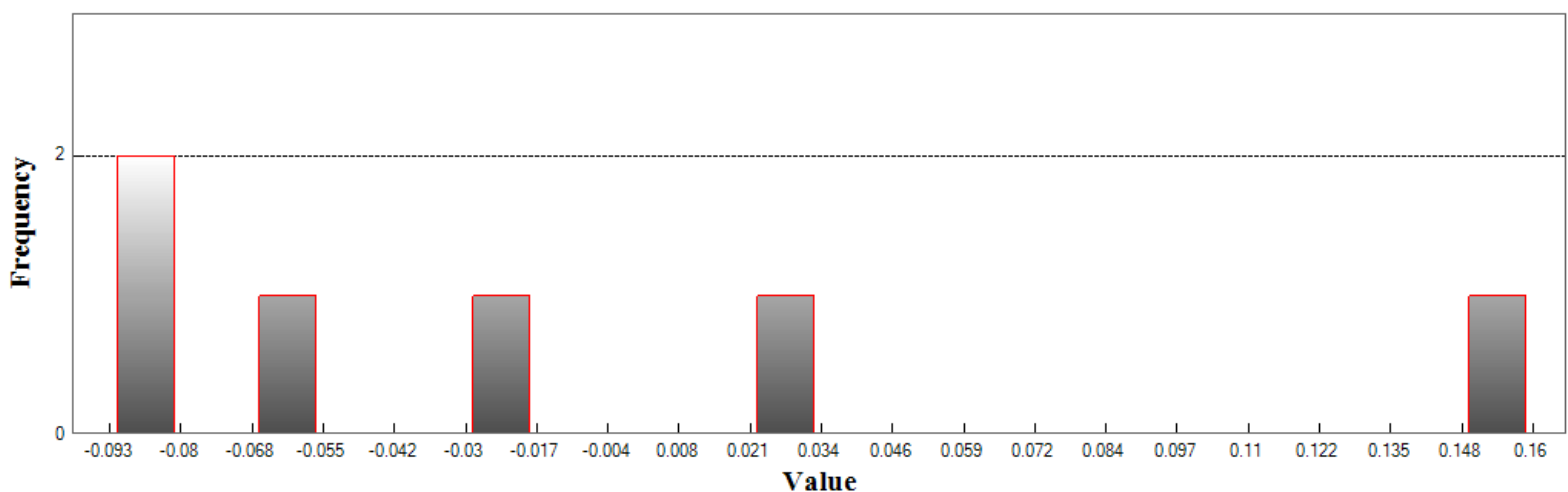
Standard Deviation DZ: 0.096

RMSE Z: 0.089

95th Percentile: 0.161

Units: Meters

Histogram



Min: -0.093

Max: 0.161

Number Of Bins: 20

Bin Interval: 0.013

DEM (Continued)

Vegetated Vertical Accuracy

LandCover Type: Low Vegetation

Minimum DZ: -0.135

Maximum DZ: 0.189

Mean DZ: 0.045

Mean Magnitude DZ: 0.277

Number Observations: 24

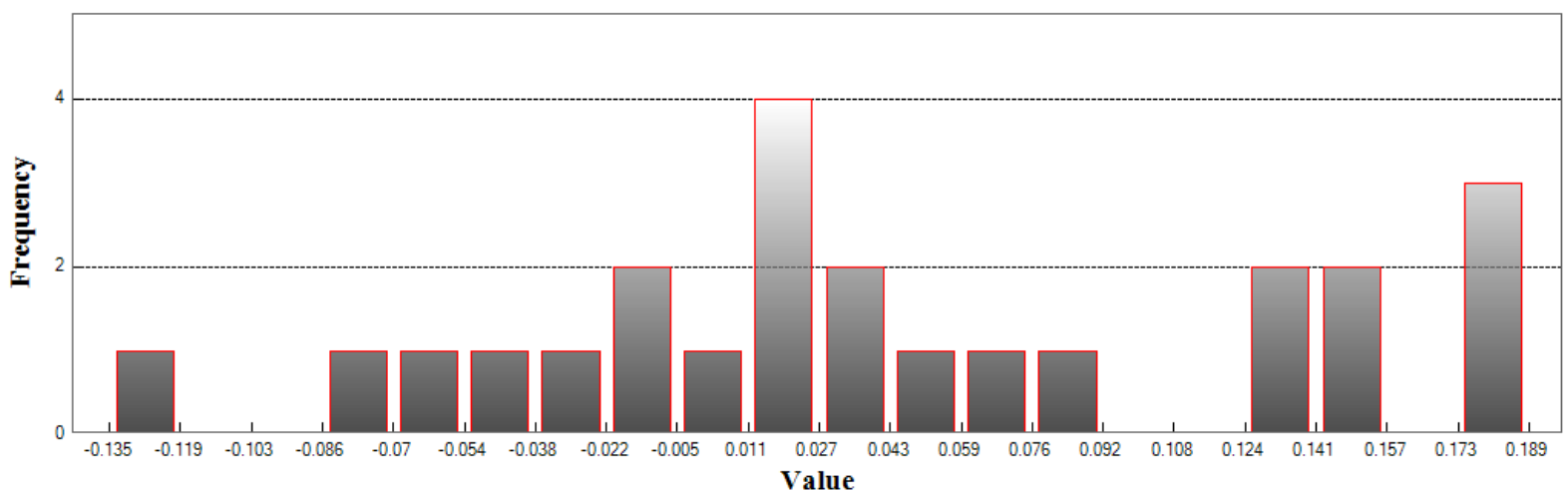
Standard Deviation DZ: 0.089

RMSE Z: 0.098

95th Percentile: 0.186

Units: Meters

Histogram



Min: -0.135

Max: 0.189

Number Of Bins: 20

Bin Interval: 0.016

DEM (Continued)

Vegetated Vertical Accuracy

LandCover Type: Med Vegetation

Minimum DZ: -0.091

Maximum DZ: 0.13

Mean DZ: 0.062

Mean Magnitude DZ: 0.313

Number Observations: 5

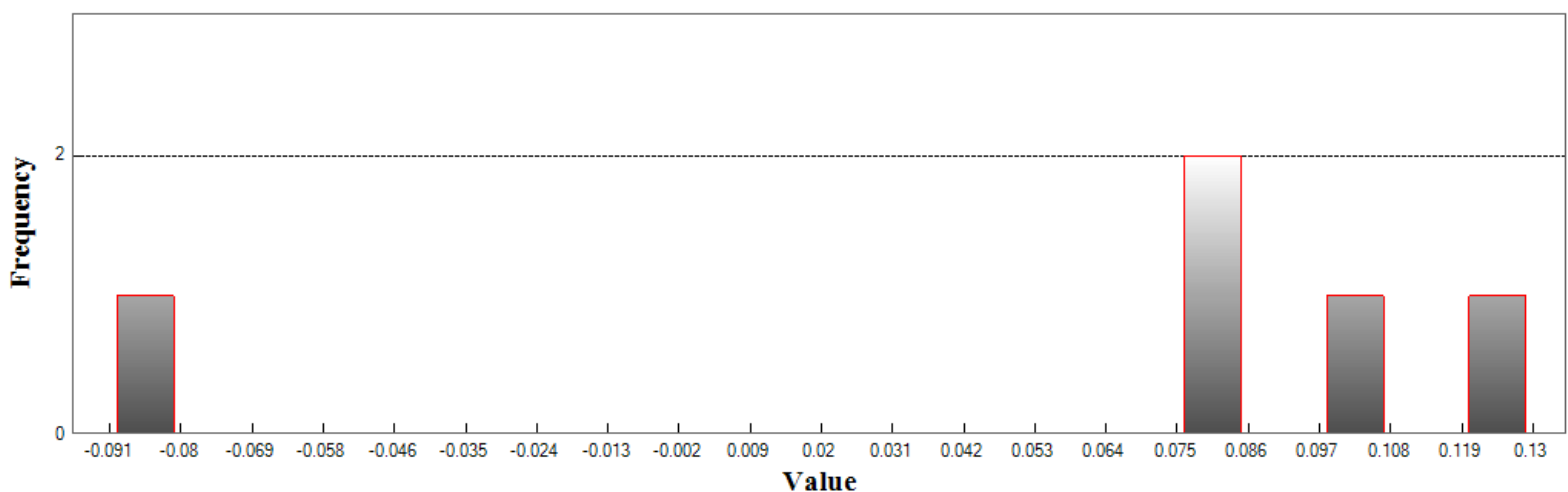
Standard Deviation DZ: 0.087

RMSE Z: 0.1

95th Percentile: 0.13

Units: Meters

Histogram



Min: -0.091

Max: 0.13

Number Of Bins: 20

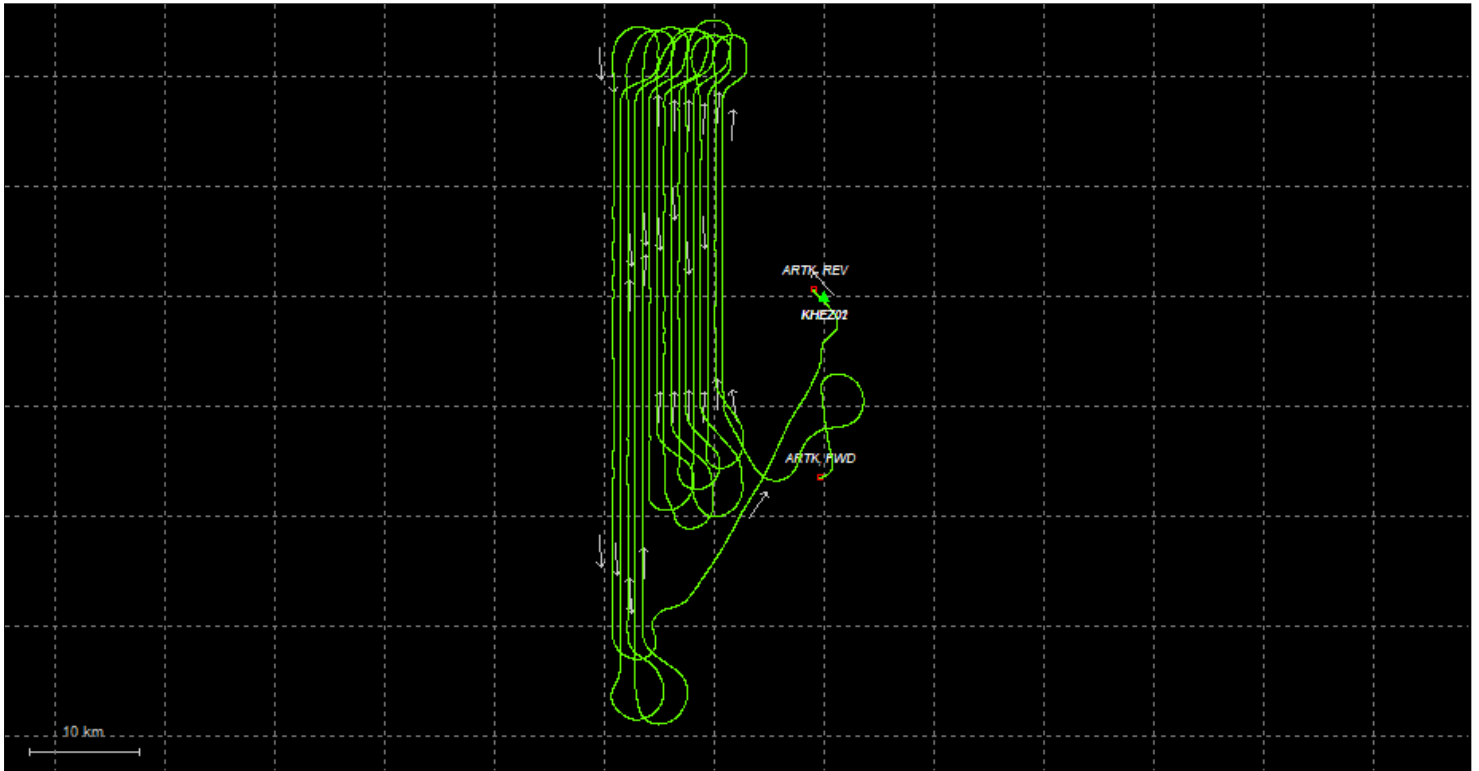
Bin Interval: 0.011

Appendix D. Inertial Explorer

Output Results for 20191202212125

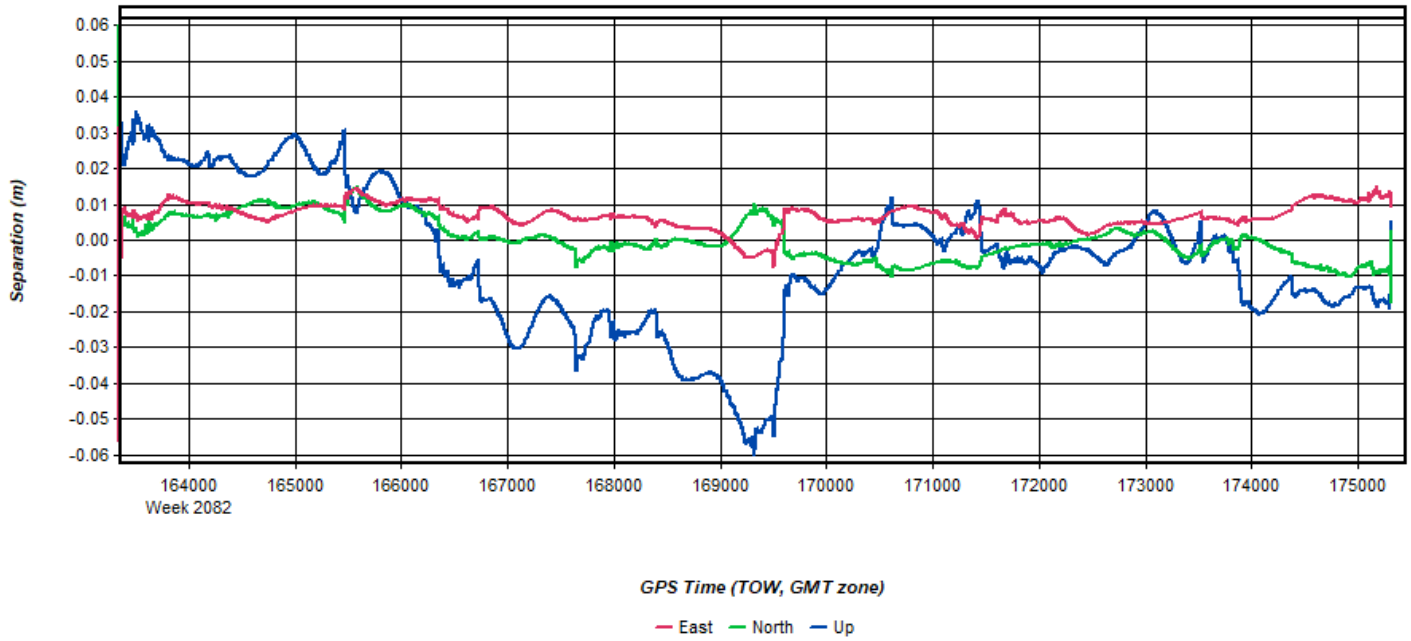
Inertial Explorer Version 8.80.2305
12/11/2019

Figure 1: Smoothed TC Combined - Map



Process	20191202212125	by Unknown	on 12/11/2019	at 16:35:26
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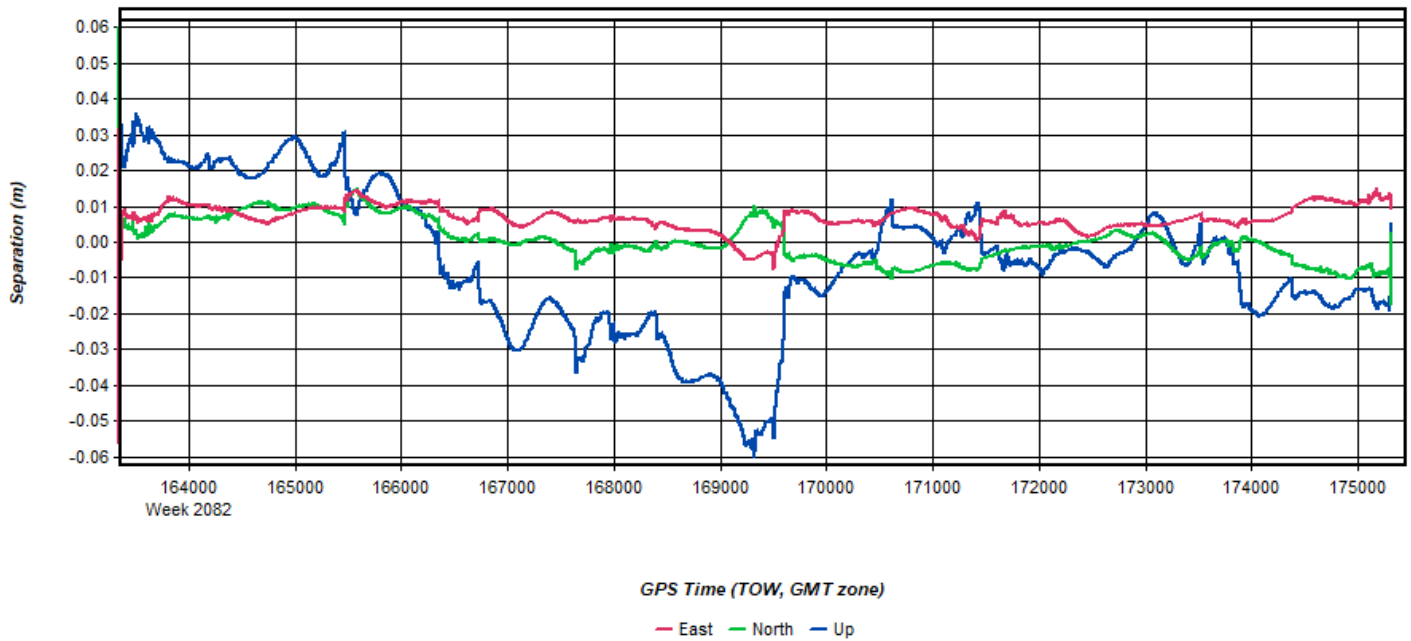
Figure 2: 20191202212125 [Smoothed TC Combined] - Forward/Reverse or Combined Separation Plot



Process	20191202212125	by Unknown	on 12/11/2019	at 16:35:26
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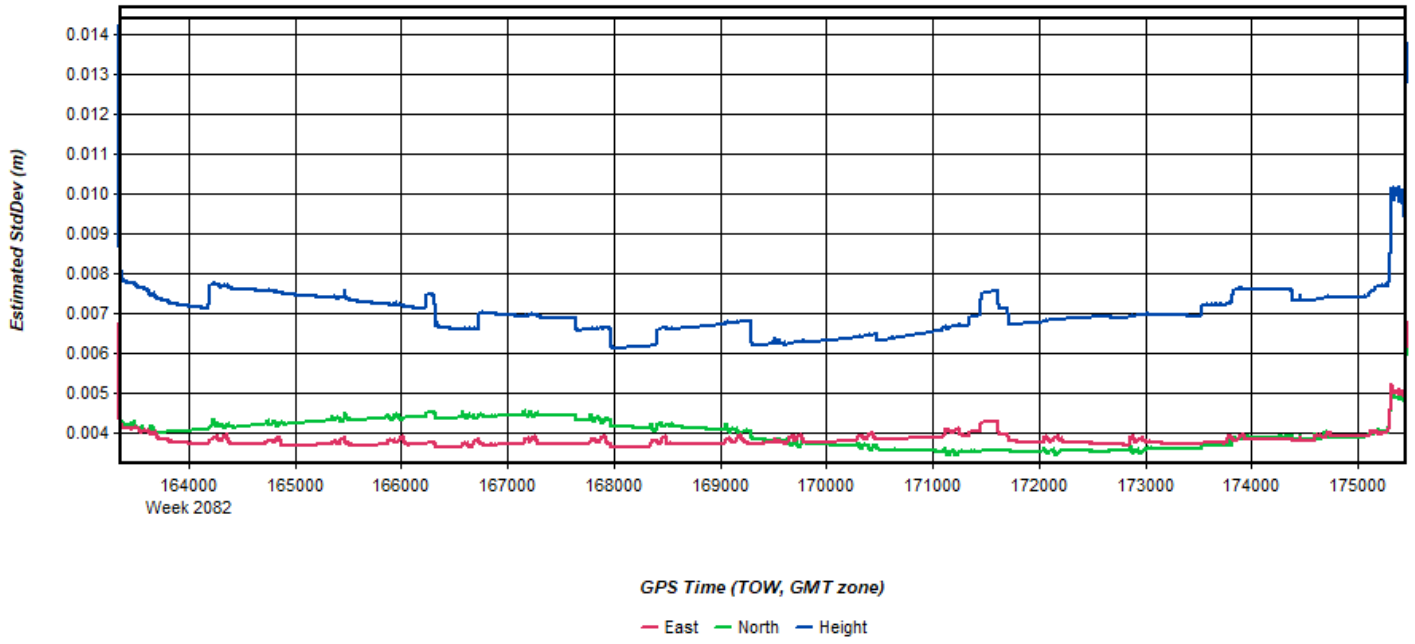
Object 20191202212125 [Smoothed TC Combined] - Float or Fixed Ambiguity failed--NULL bitmap handle

Figure 3: 20191202212125 [Smoothed TC Combined] - Forward/Reverse Separation Plot (Fixed)



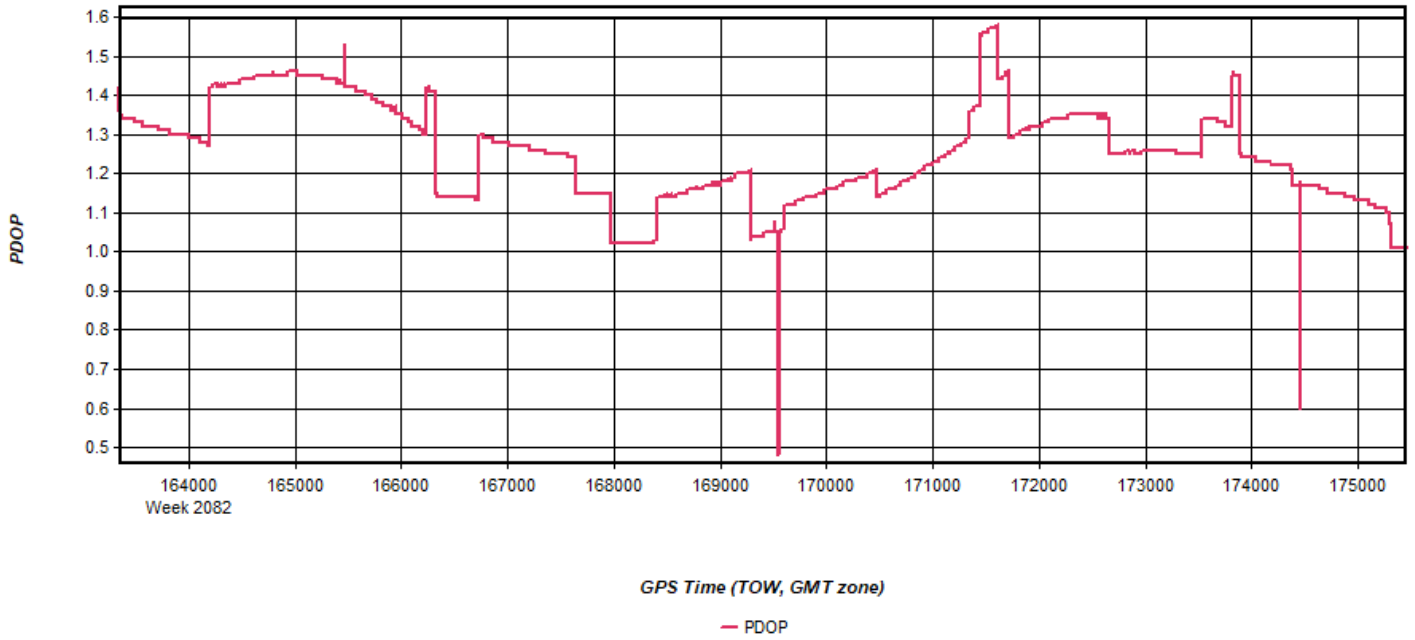
Process	20191202212125	by Unknown	on 12/11/2019	at 16:35:26
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Figure 4: 20191202212125 [Smoothed TC Combined] - Estimated Position Accuracy Plot



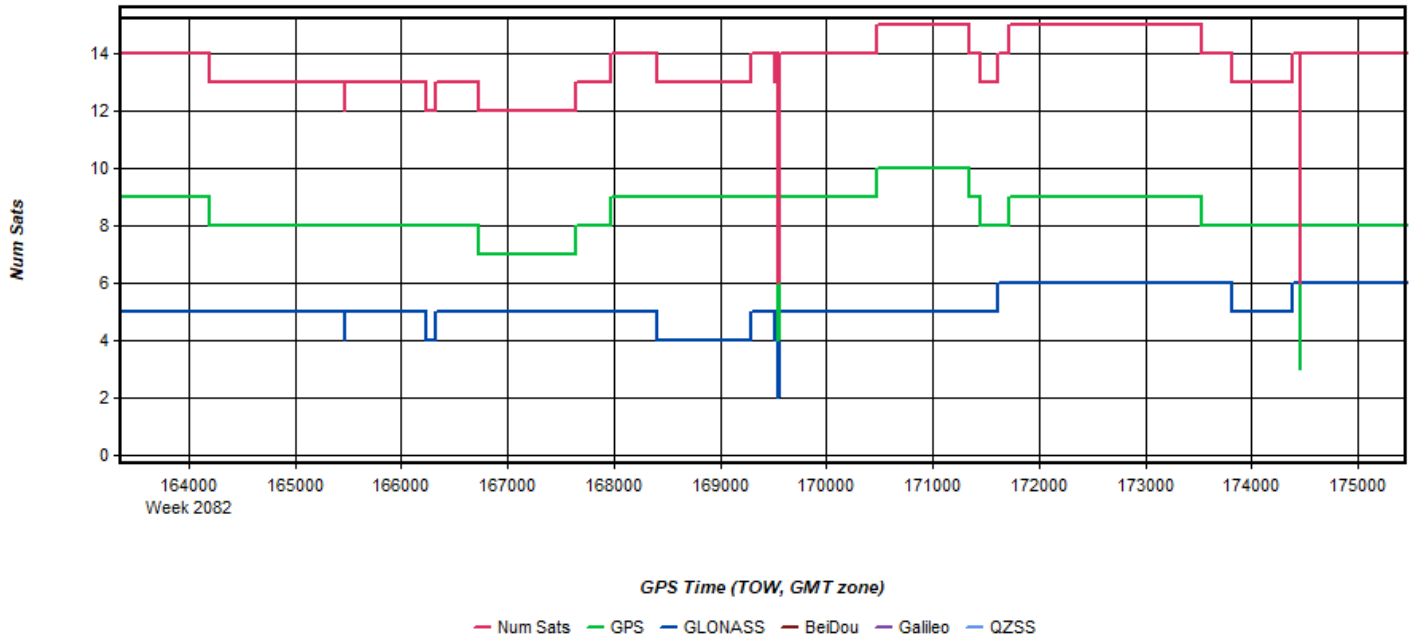
Process	20191202212125	by Unknown	on 12/11/2019	at 16:35:26
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Figure 5: 20191202212125 [Smoothed TC Combined] - PDOP Plot



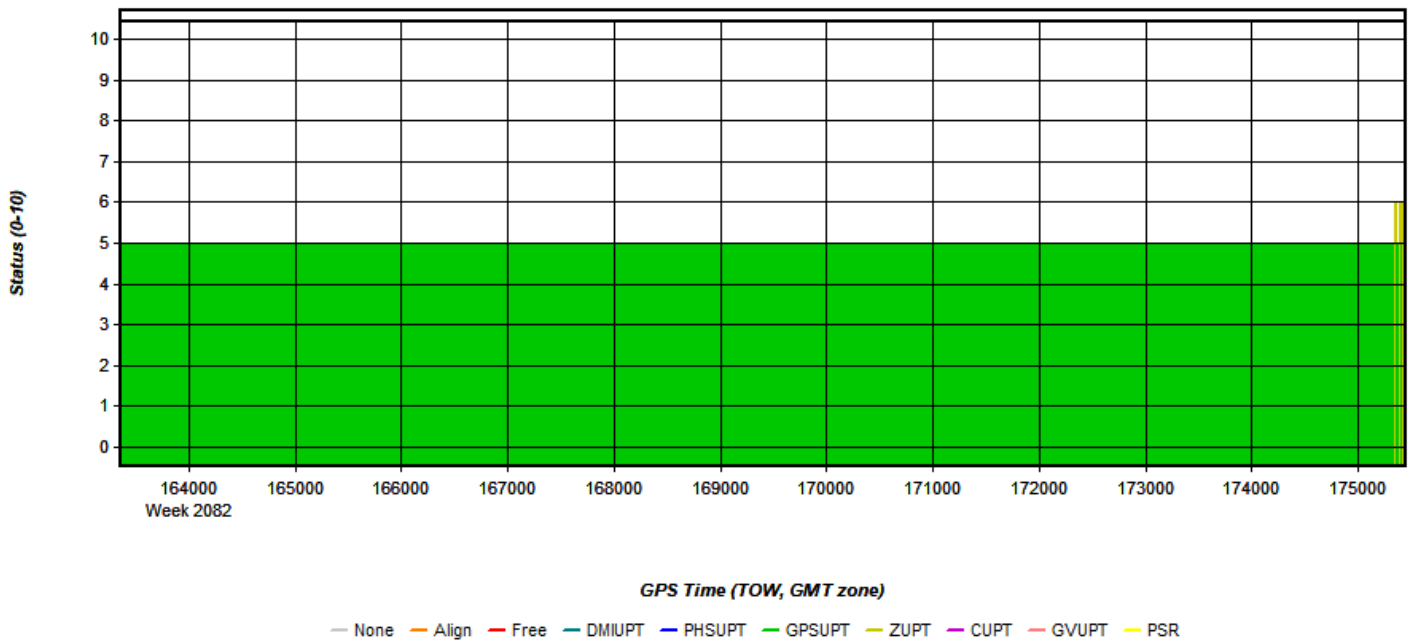
Process	20191202212125	by Unknown	on 12/11/2019	at 16:35:26
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Figure 6: 20191202212125 [Smoothed TC Combined] - Number of Satellites Line Plot



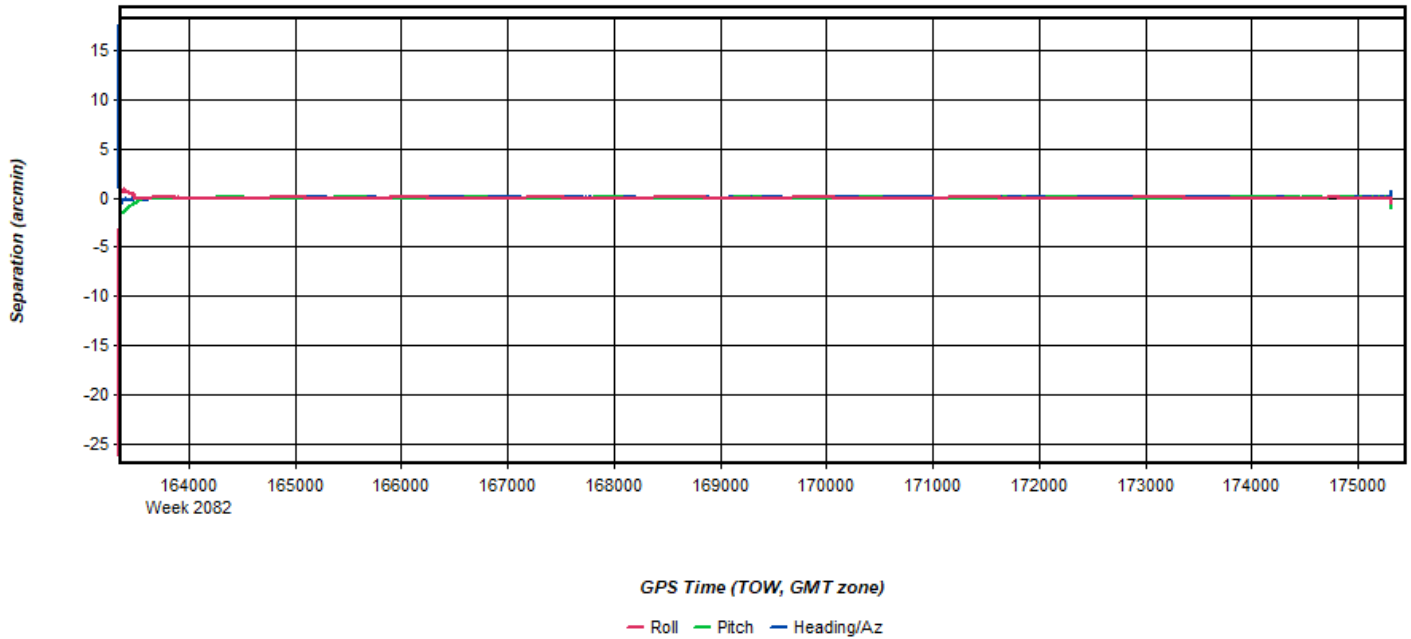
Process	20191202212125	by Unknown	on 12/11/2019	at 16:35:26
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Figure 7: 20191202212125 [Smoothed TC Combined] - Status flag for IMU processing



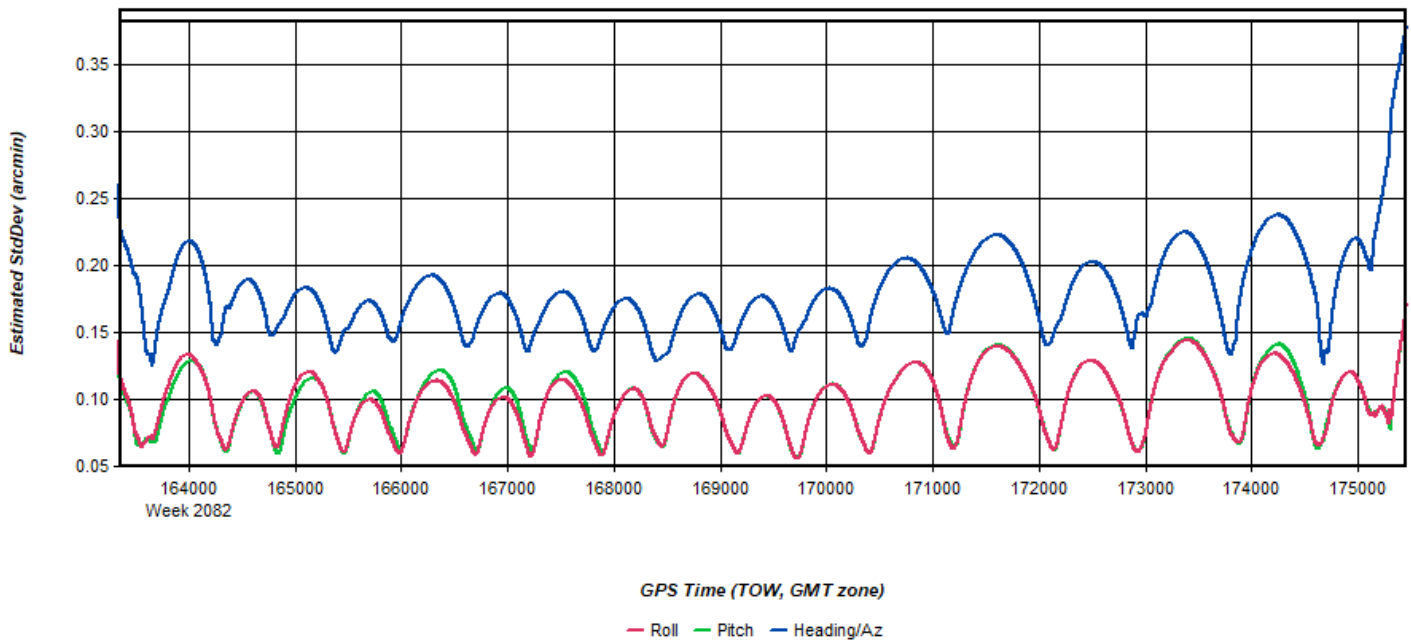
Process	20191202212125	by Unknown	on 12/11/2019	at 16:35:26
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Figure 8: 20191202212125 [Smoothed TC Combined] - Fwd/Rev Attitude Separation Plot



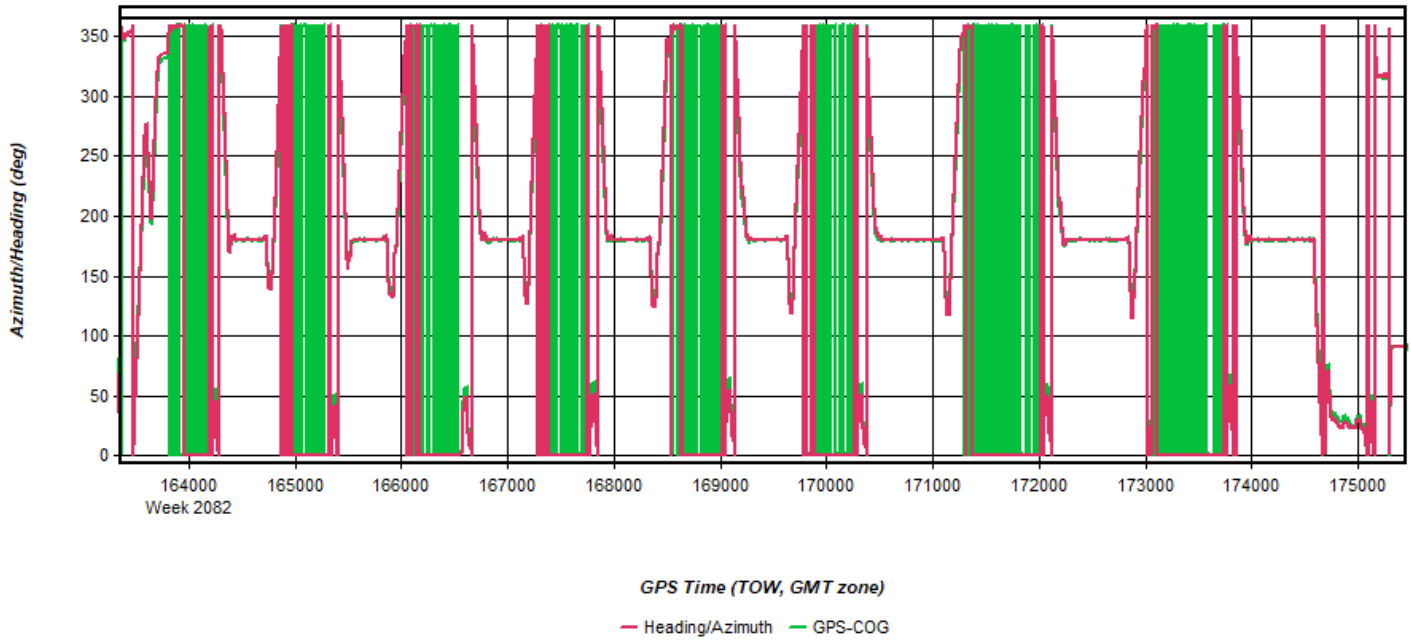
Process	20191202212125	by Unknown	on 12/11/2019	at 16:35:26
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Figure 9: 20191202212125 [Smoothed TC Combined] - Estimated Attitude Accuracy Plot



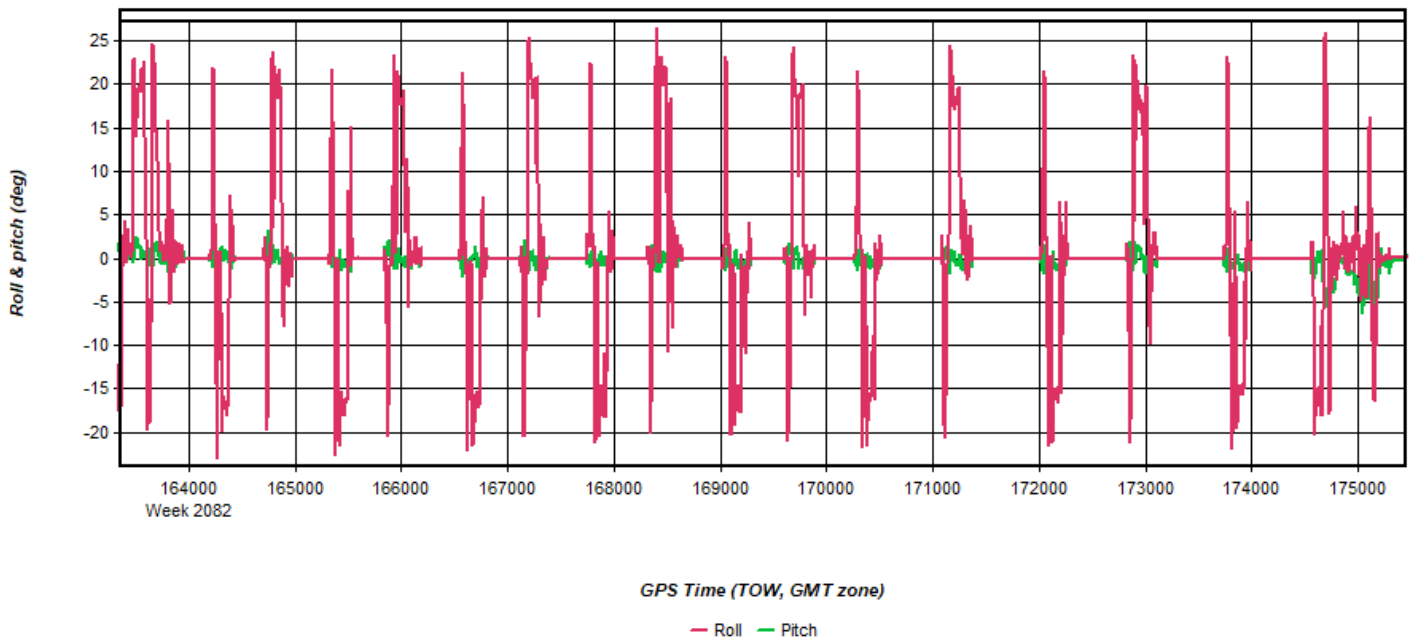
Process	20191202212125	by Unknown	on 12/11/2019	at 16:35:26
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Figure 10: 20191202212125 [Smoothed TC Combined] - Azimuth Plot



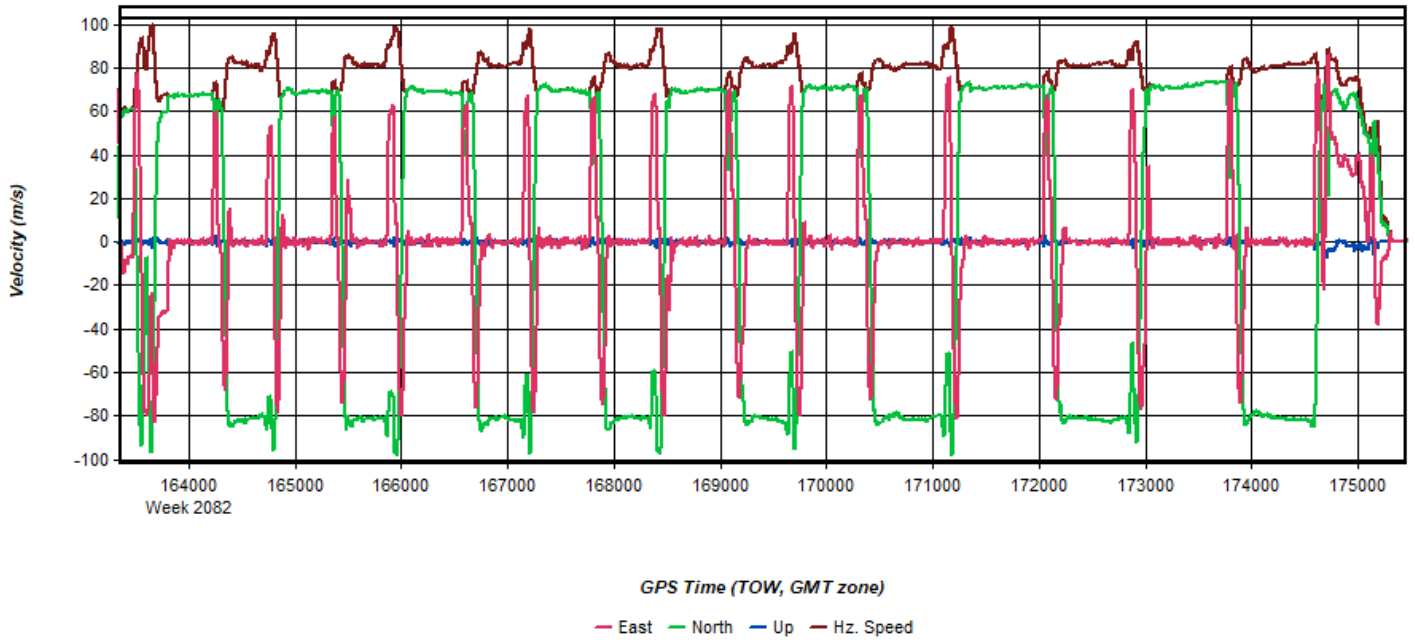
Process	20191202212125	by Unknown	on 12/11/2019	at 16:35:26
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Figure 11: 20191202212125 [Smoothed TC Combined] - Roll & Pitch Plot



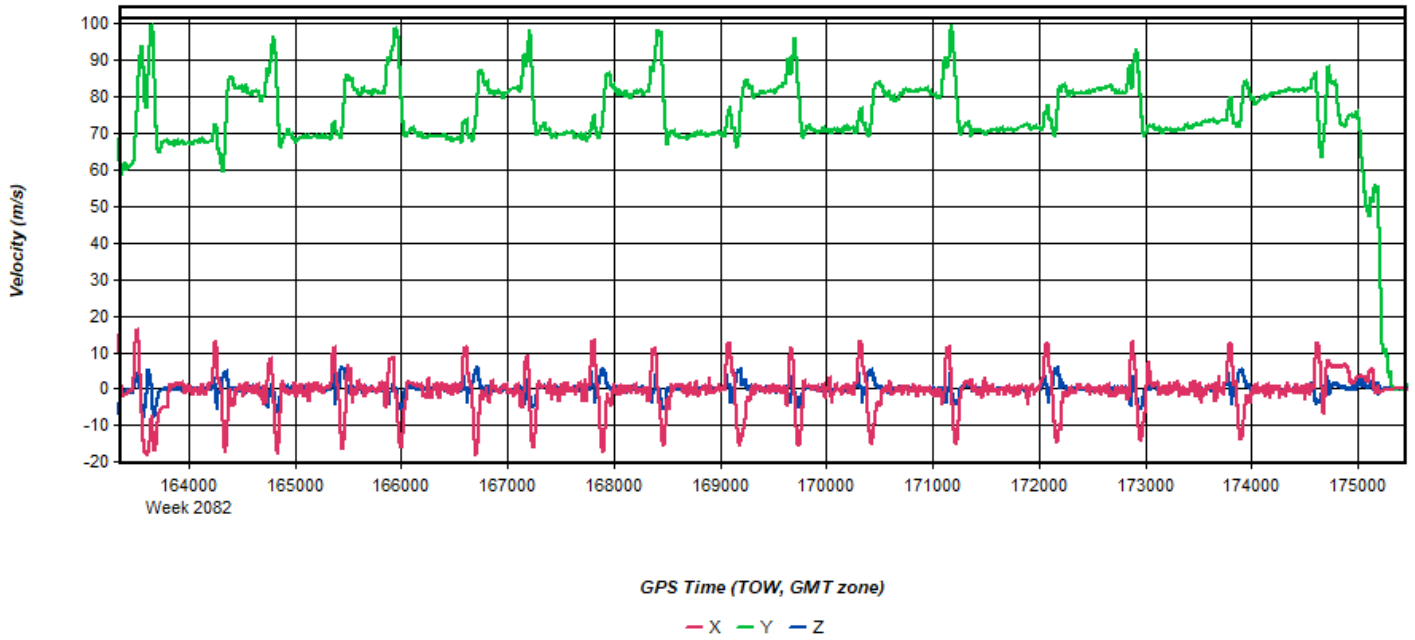
Process	20191202212125	by Unknown	on 12/11/2019	at 16:35:26
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Figure 12: 20191202212125 [Smoothed TC Combined] - Velocity Profile Plot



Process	20191202212125	by Unknown	on 12/11/2019	at 16:35:26
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Figure 13: 20191202212125 [Smoothed TC Combined] - Body Frame Velocity Plot



Process	20191202212125	by Unknown	on 12/11/2019	at 16:35:26
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Figure 14: 20191202212125 [Smoothed TC Combined] - Height Profile Plot

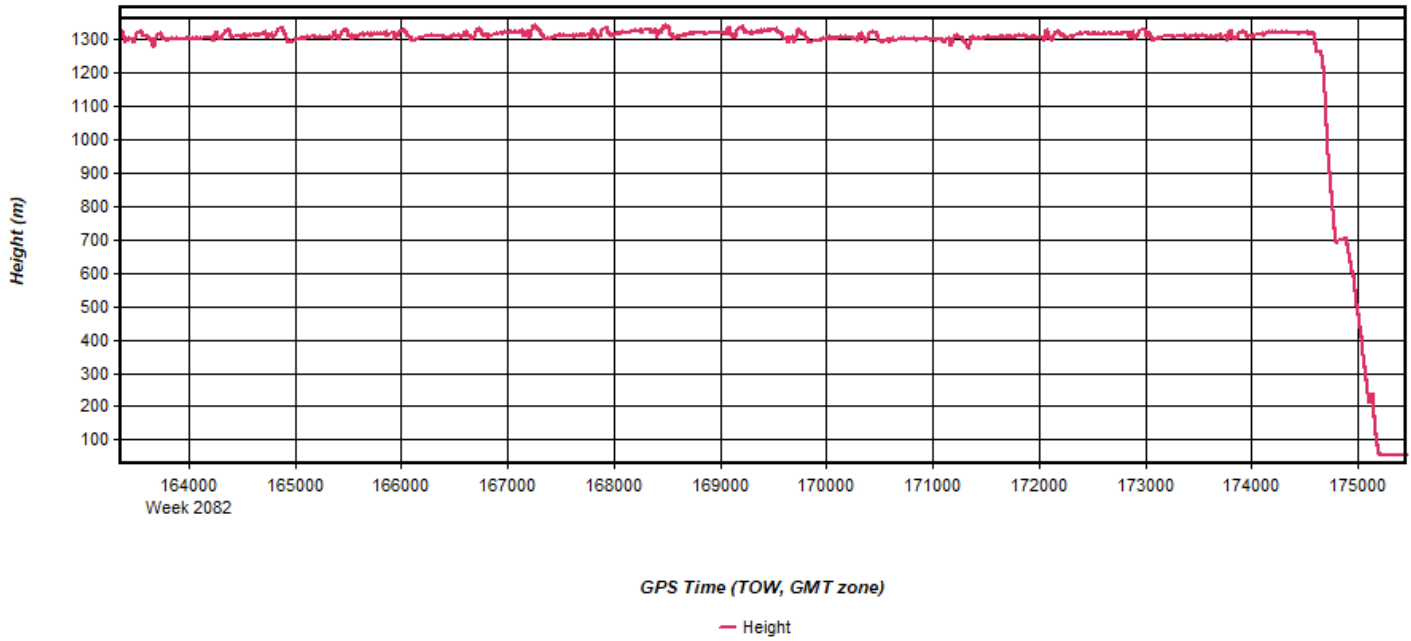


Figure 15: 20191202212125 [Smoothed TC Combined] - C/A Code Residual RMS Plot

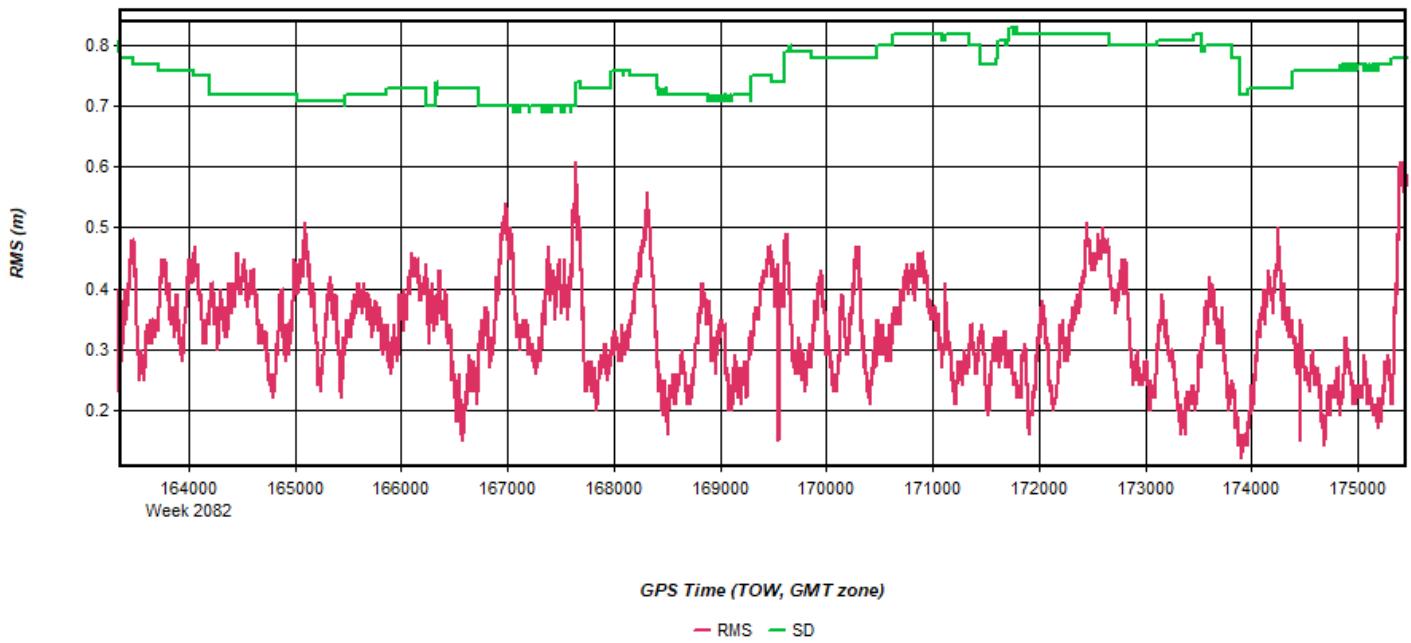


Figure 16: 20191202212125 [Smoothed TC Combined] - Carrier Residual RMS Plot

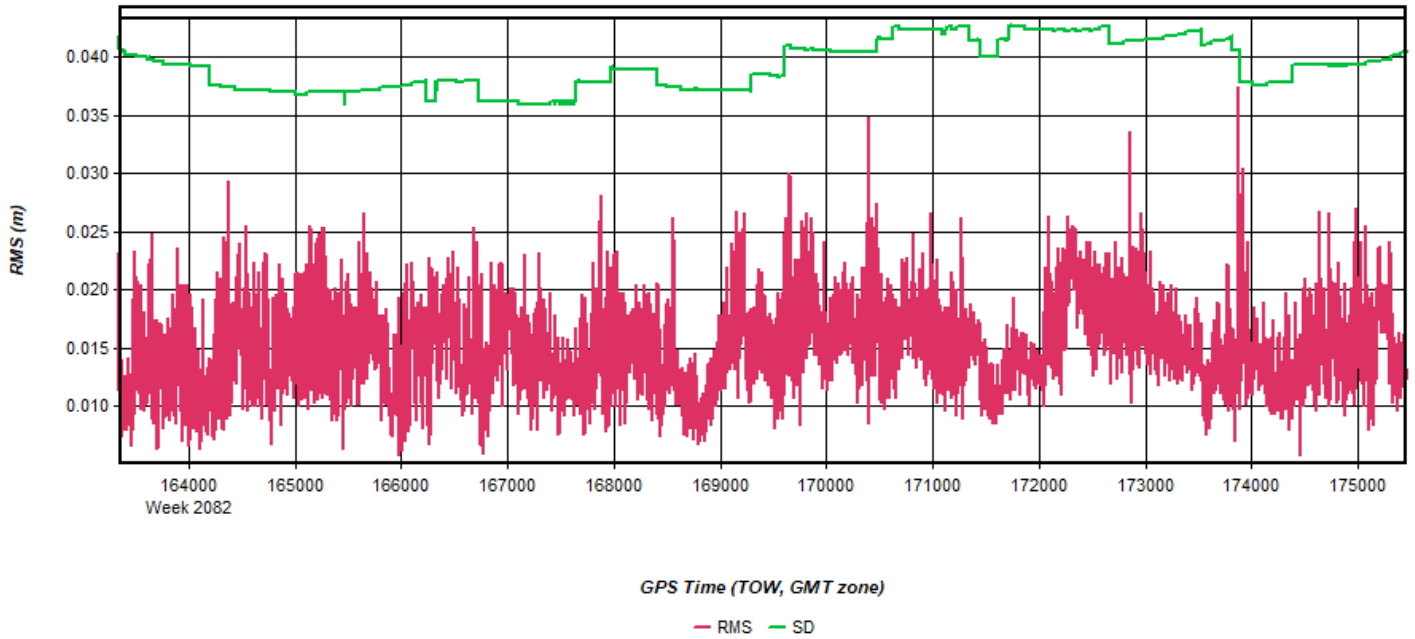


Figure 17: 20191202212125 [Smoothed TC Combined] - L1 Doppler Residual RMS Plot

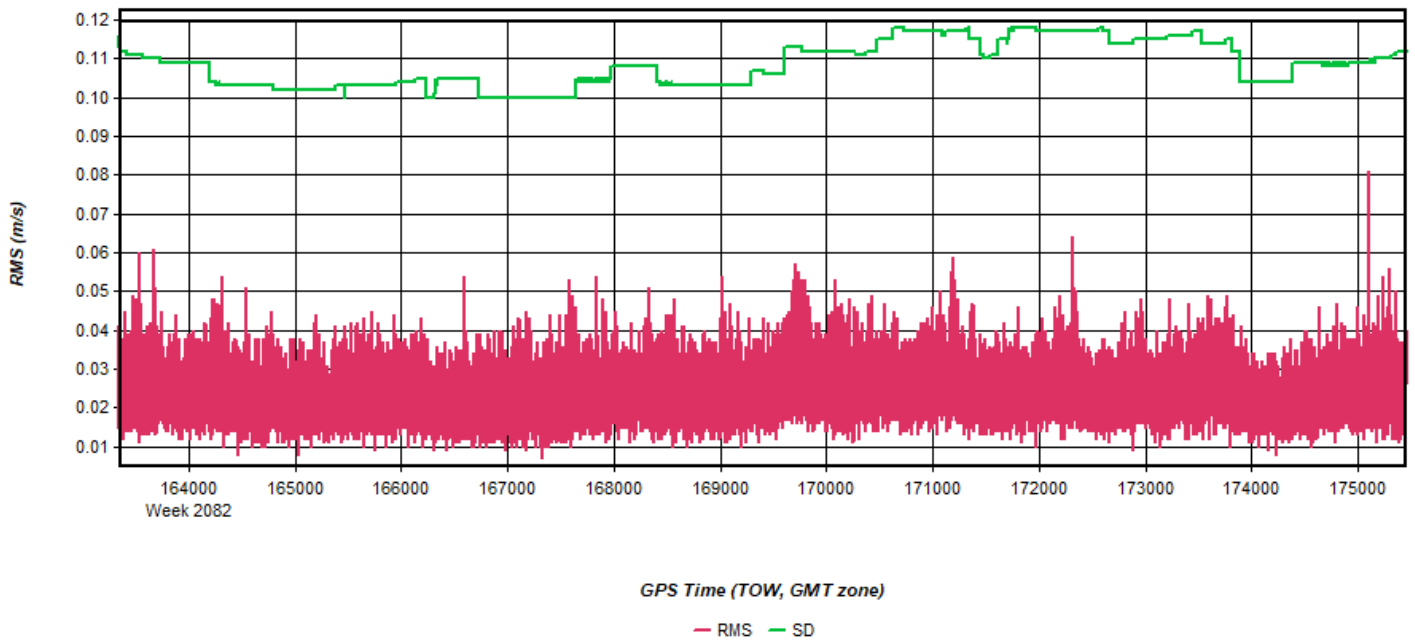
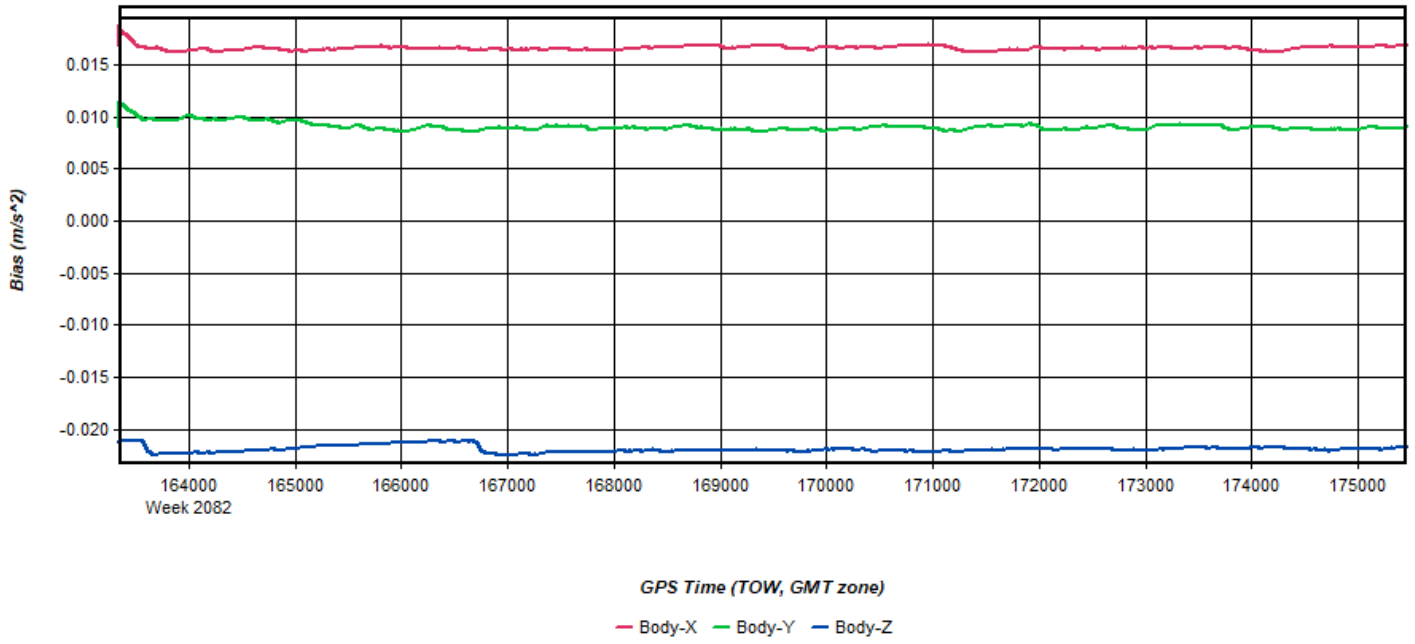
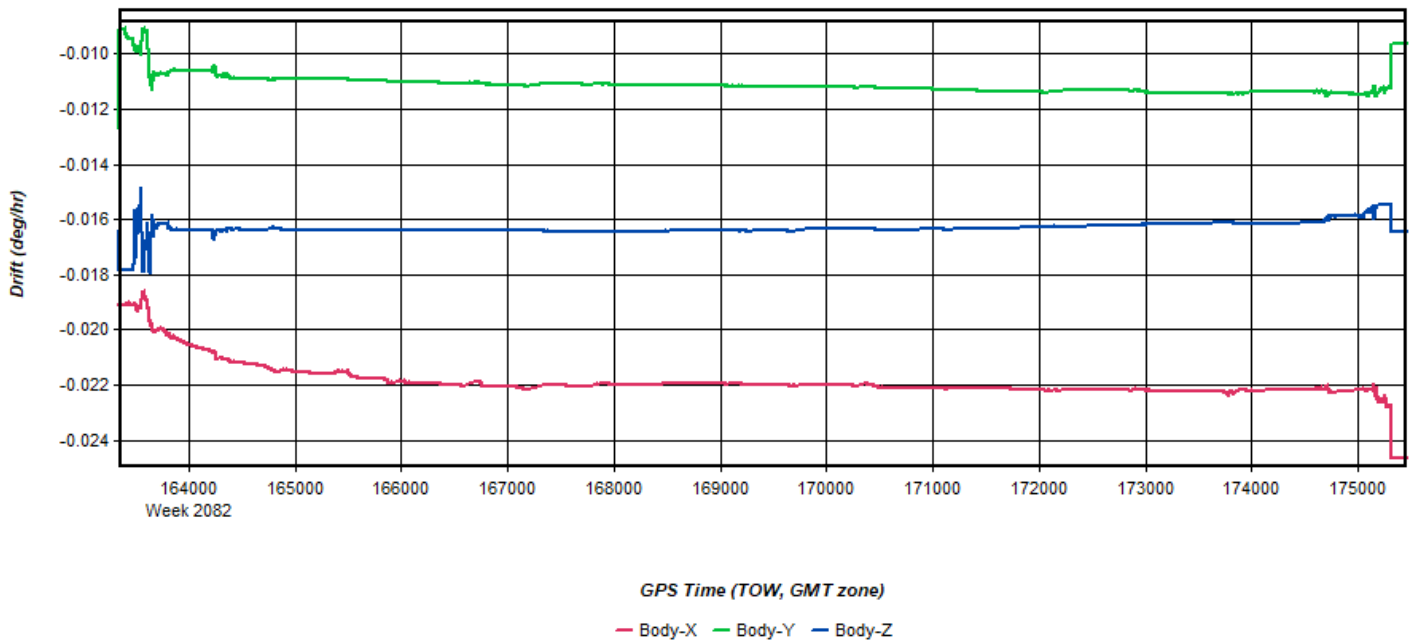


Figure 18: 20191202212125 [Smoothed TC Combined] - Accelerometer Bias Plot



Process	20191202212125	by Unknown	on 12/11/2019	at 16:35:26
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Figure 19: 20191202212125 [Smoothed TC Combined] - Gyro Drift Plot



Process	20191202212125	by Unknown	on 12/11/2019	at 16:35:26
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Output Results for 20191203151442

Inertial Explorer Version 8.80.2305
12/13/2019

Figure 1: Smoothed TC Combined - Map



Process	20191203151442	by Unknown	on 12/13/2019	at 15:20:58
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Figure 2: 20191203151442 [Smoothed TC Combined] - Forward/Reverse or Combined Separation Plot



Figure 3: 20191203151442 [Smoothed TC Combined] - Float or Fixed Ambiguity

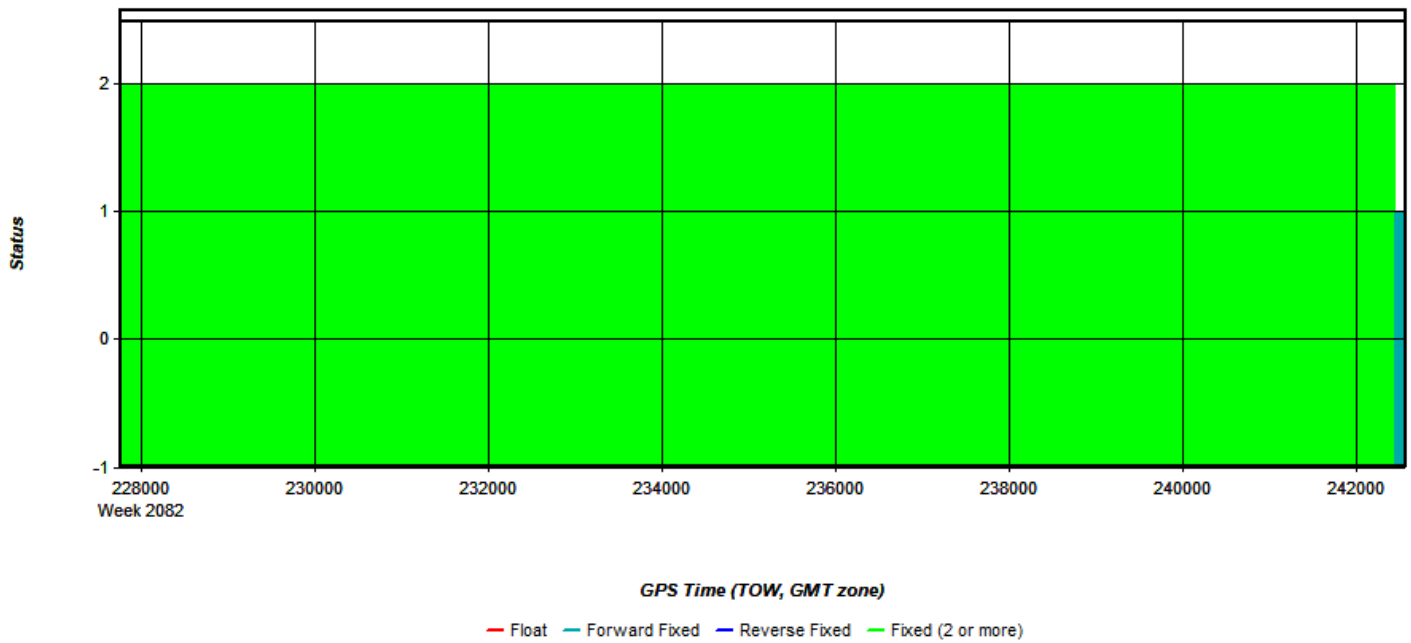


Figure 4: 20191203151442 [Smoothed TC Combined] - Forward/Reverse Separation Plot (Fixed)



Figure 5: 20191203151442 [Smoothed TC Combined] - Estimated Position Accuracy Plot

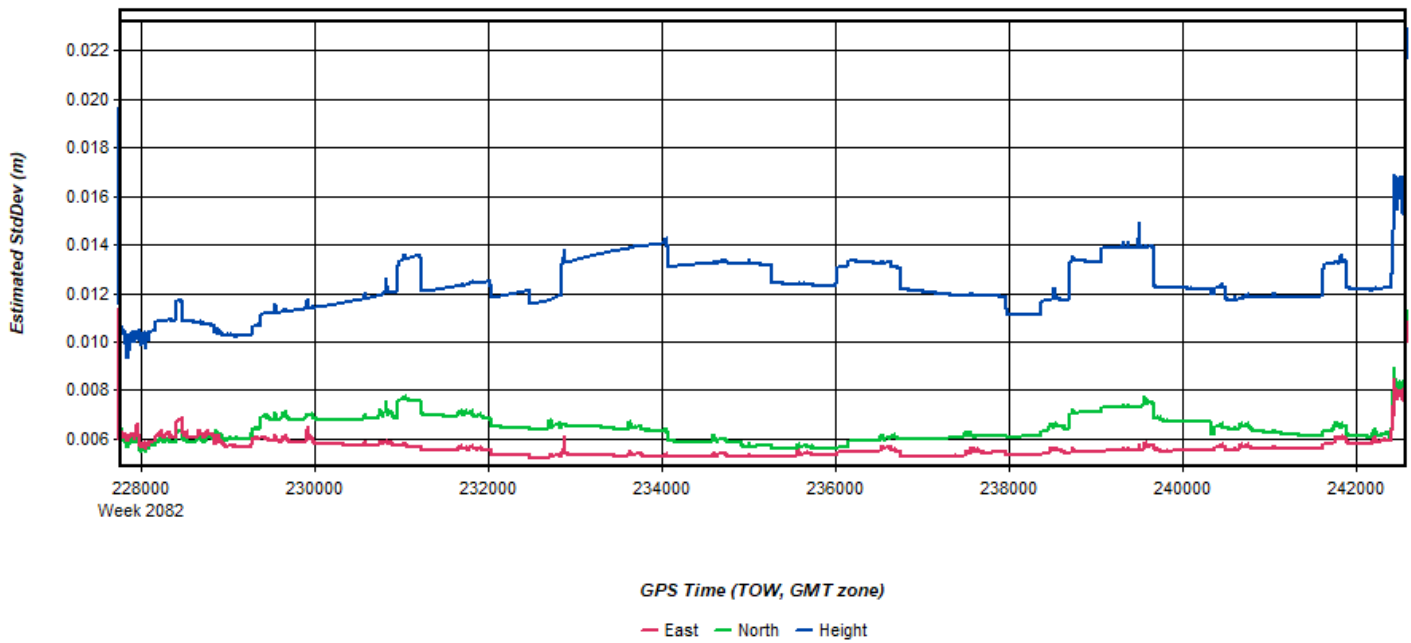


Figure 6: 20191203151442 [Smoothed TC Combined] - PDOP Plot

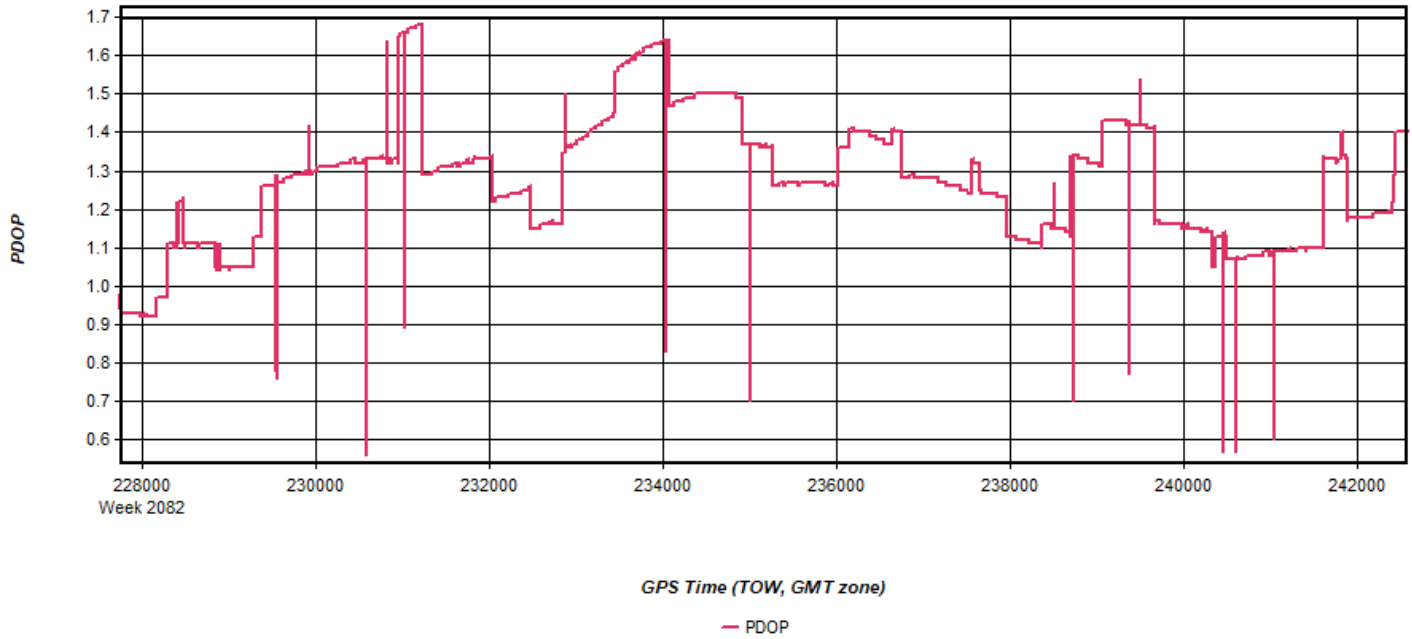


Figure 7: 20191203151442 [Smoothed TC Combined] - Number of Satellites Line Plot

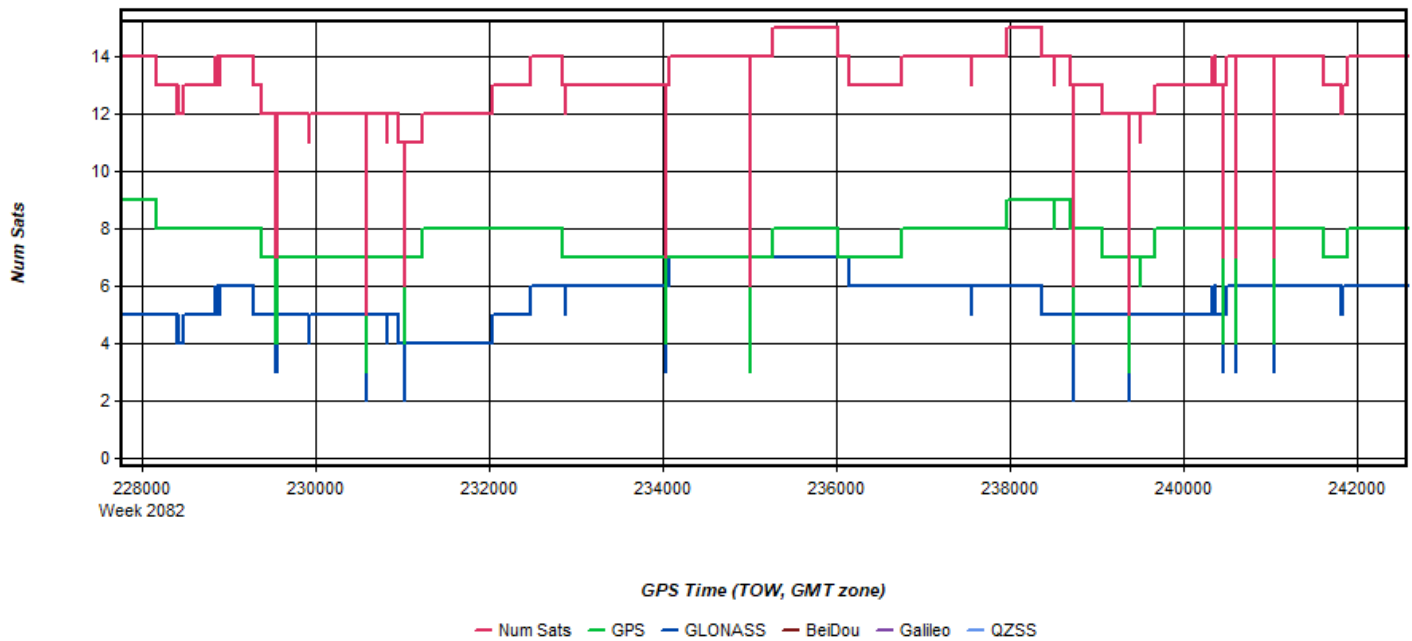


Figure 8: 20191203151442 [Smoothed TC Combined] - Status flag for IMU processing

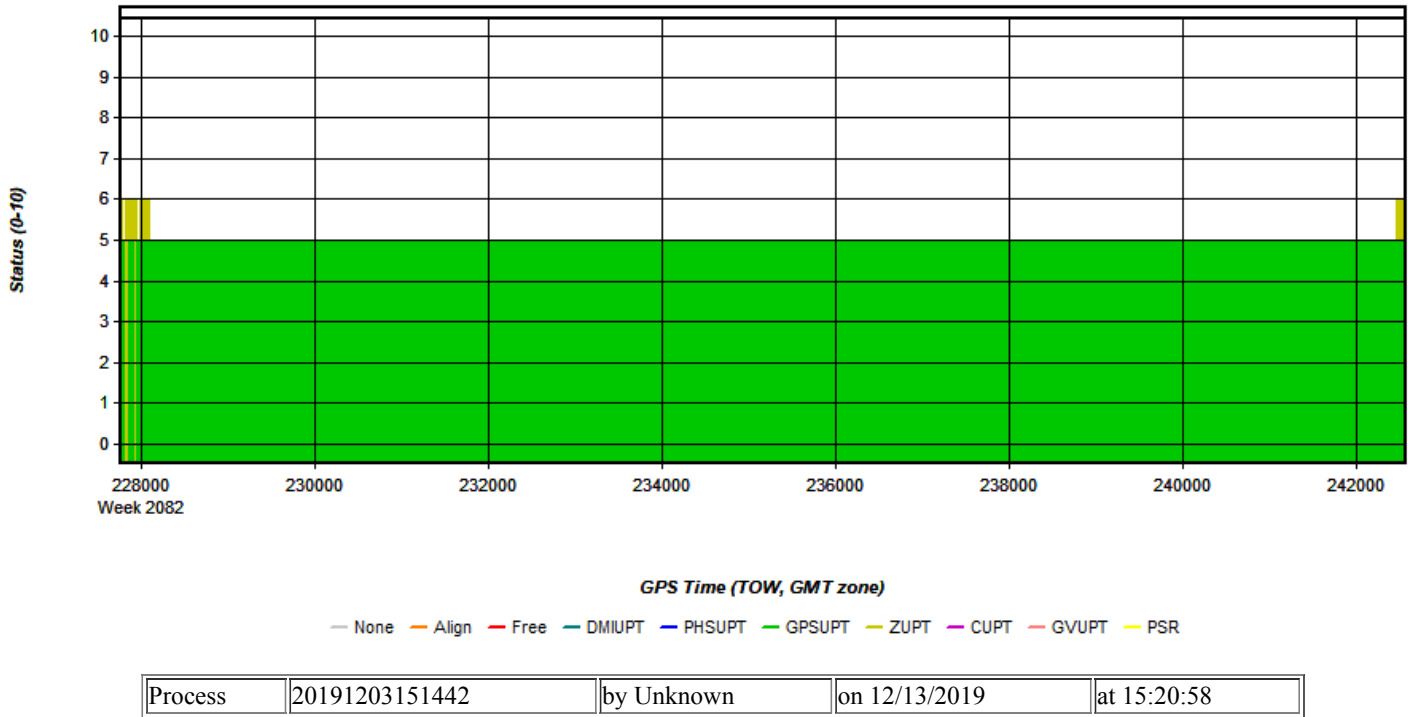


Figure 9: 20191203151442 [Smoothed TC Combined] - Fwd/Rev Attitude Separation Plot

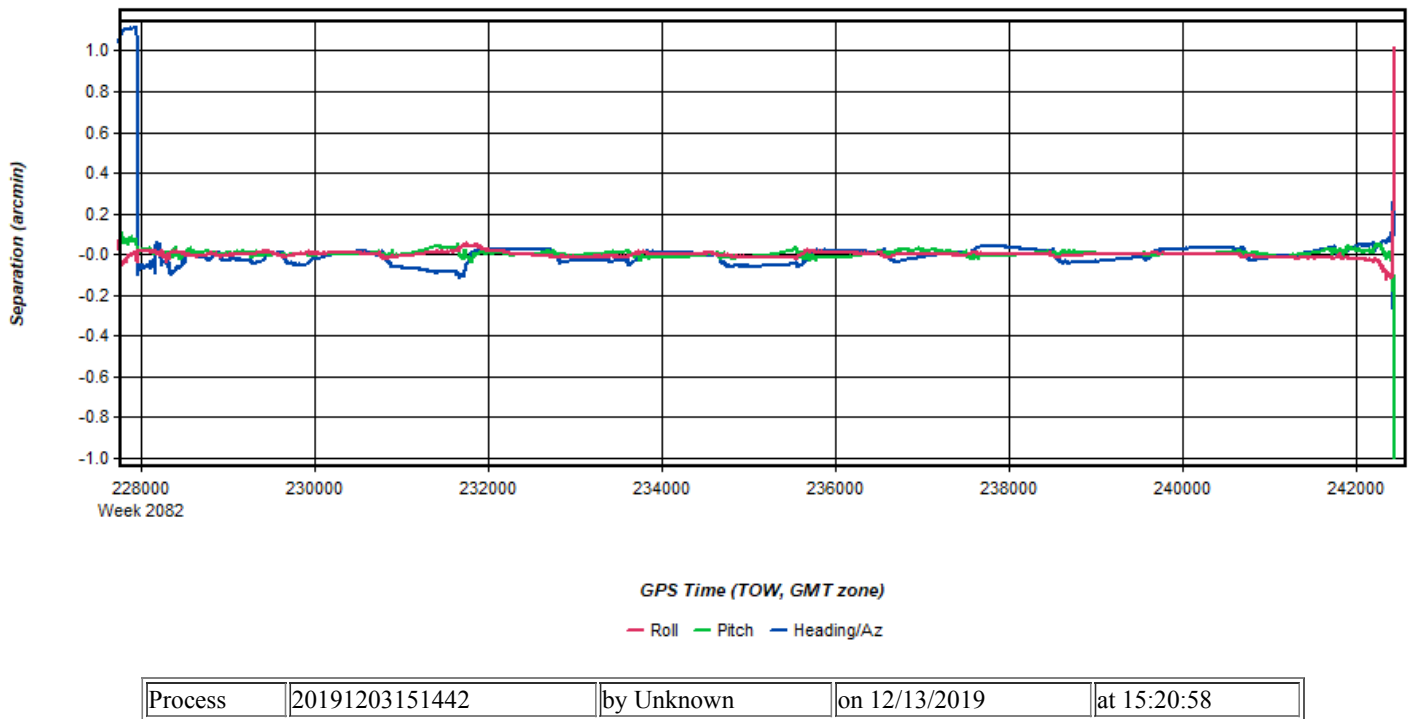
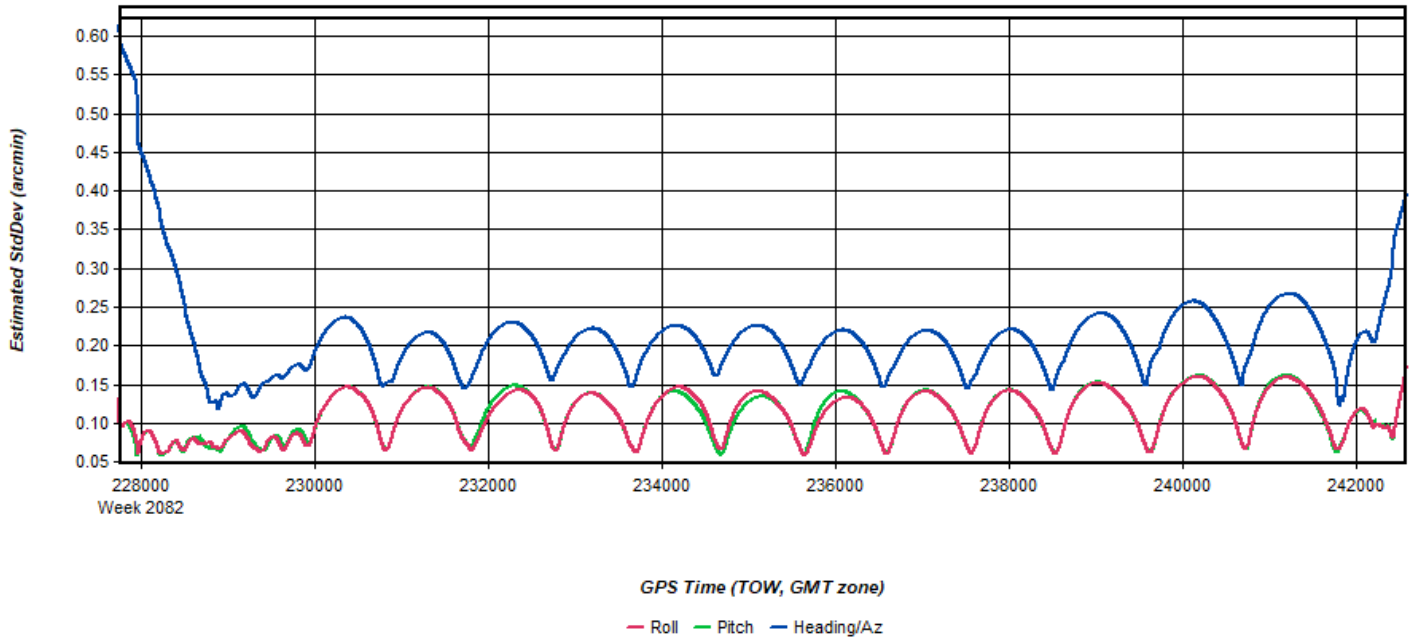
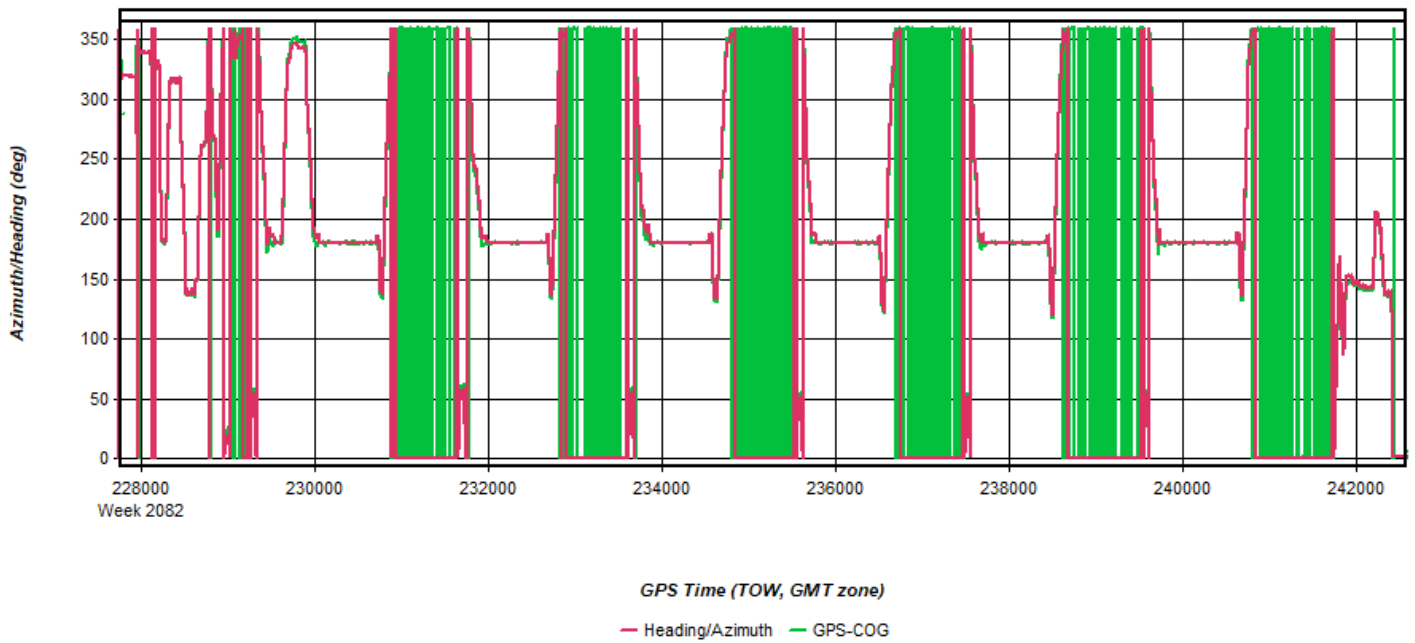


Figure 10: 20191203151442 [Smoothed TC Combined] - Estimated Attitude Accuracy Plot



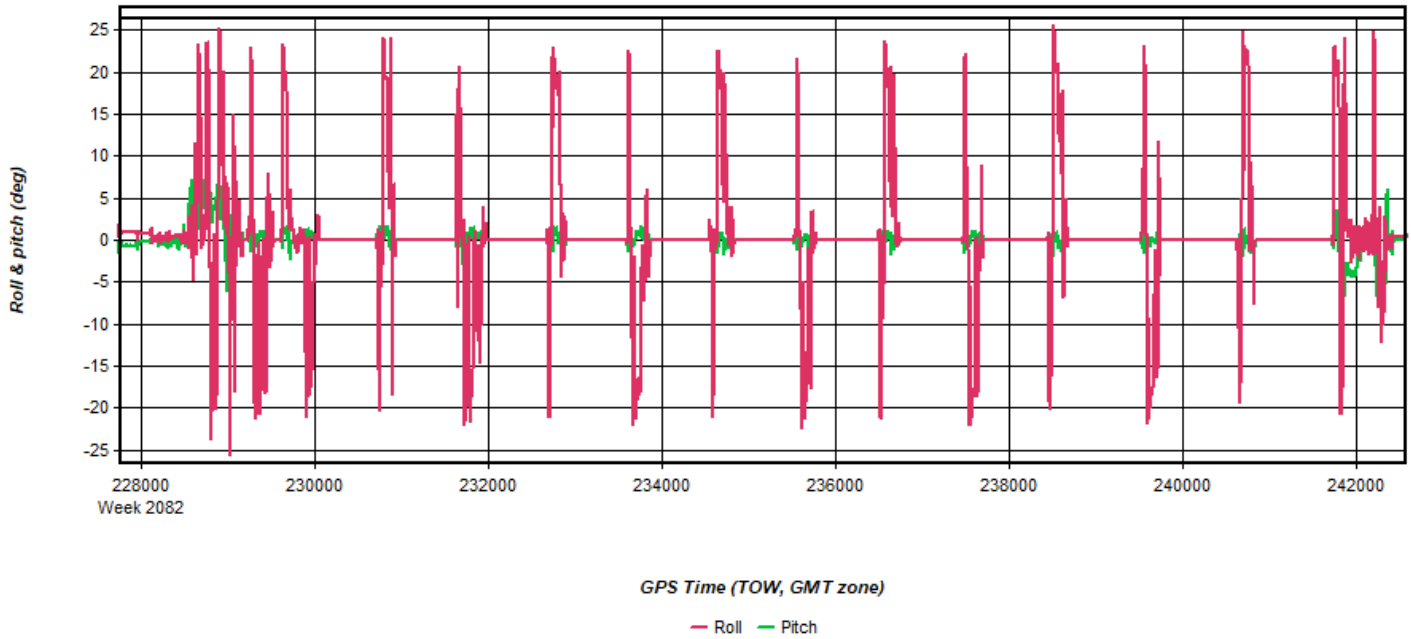
Process	20191203151442	by Unknown	on 12/13/2019	at 15:20:58
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Figure 11: 20191203151442 [Smoothed TC Combined] - Azimuth Plot



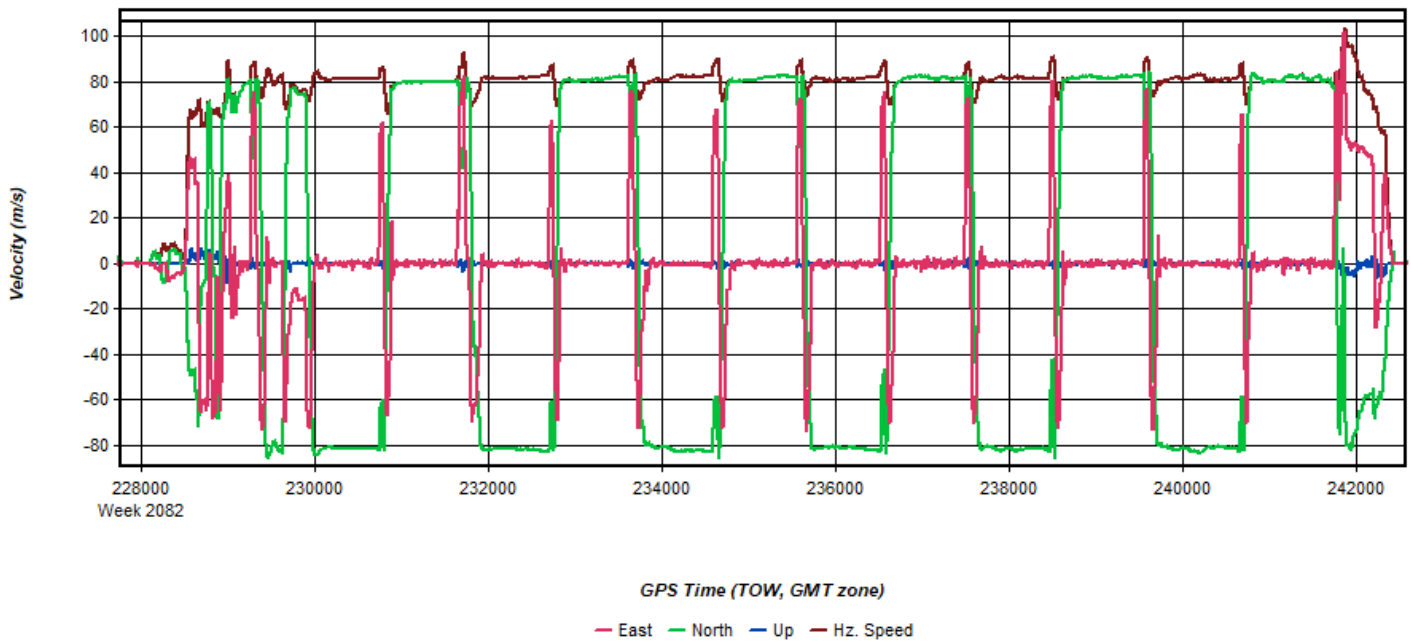
Process	20191203151442	by Unknown	on 12/13/2019	at 15:20:58
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Figure 12: 20191203151442 [Smoothed TC Combined] - Roll & Pitch Plot



Process	20191203151442	by Unknown	on 12/13/2019	at 15:20:58
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Figure 13: 20191203151442 [Smoothed TC Combined] - Velocity Profile Plot



Process	20191203151442	by Unknown	on 12/13/2019	at 15:20:58
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Figure 14: 20191203151442 [Smoothed TC Combined] - Body Frame Velocity Plot



Figure 15: 20191203151442 [Smoothed TC Combined] - Height Profile Plot

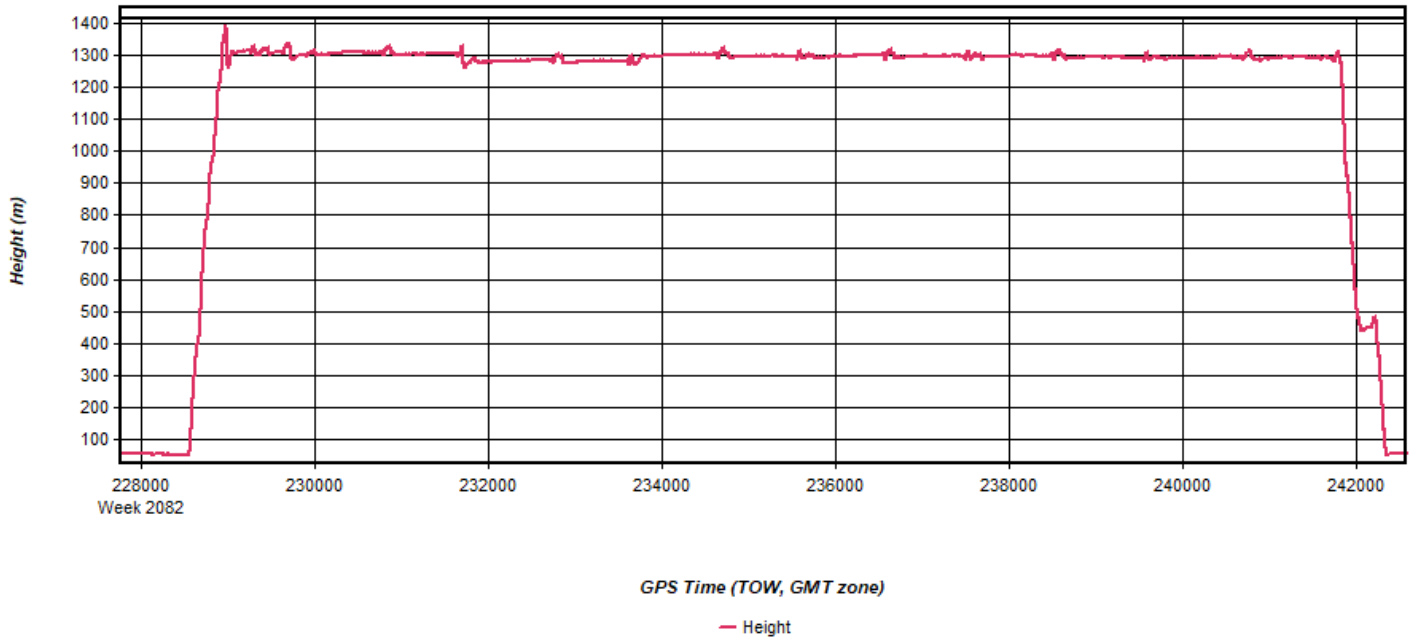
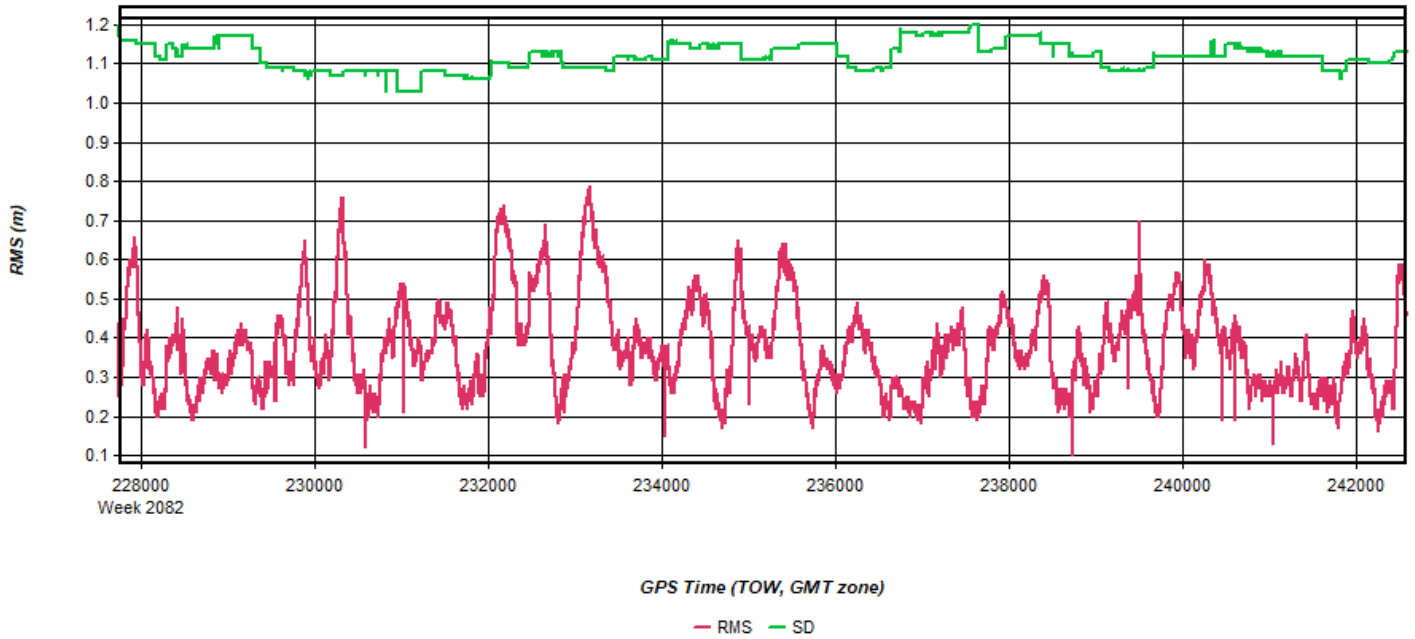
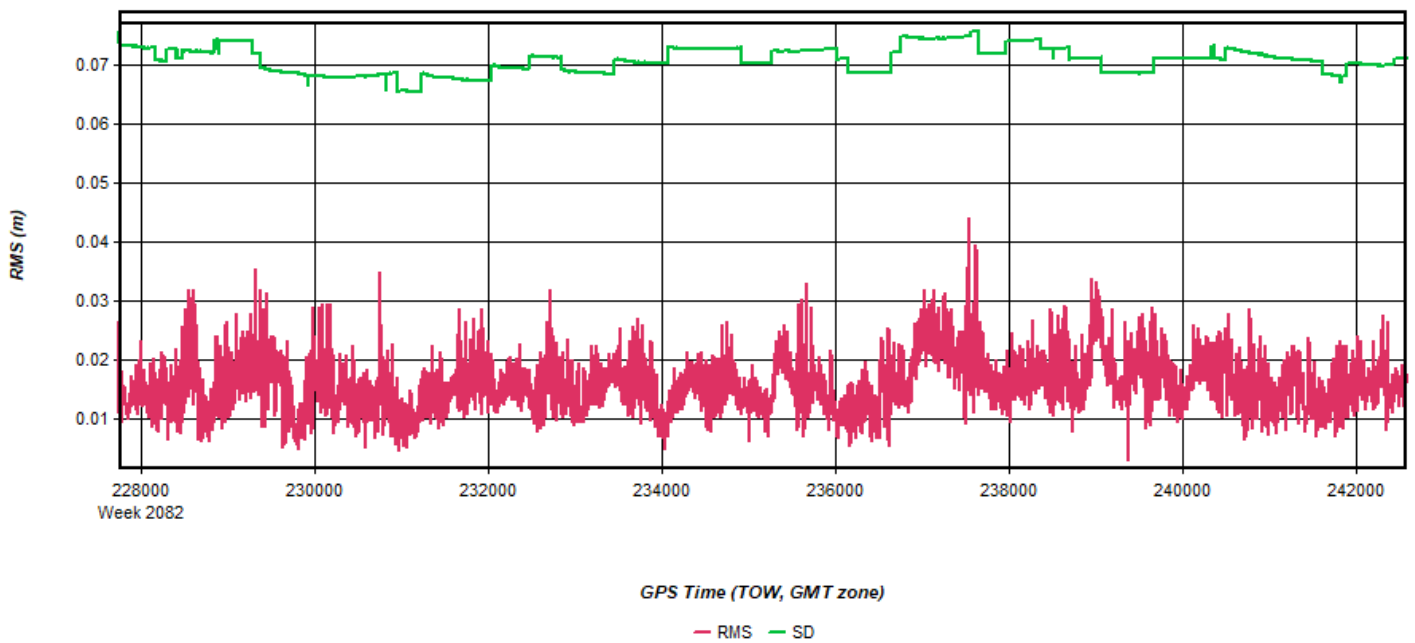


Figure 16: 20191203151442 [Smoothed TC Combined] - C/A Code Residual RMS Plot



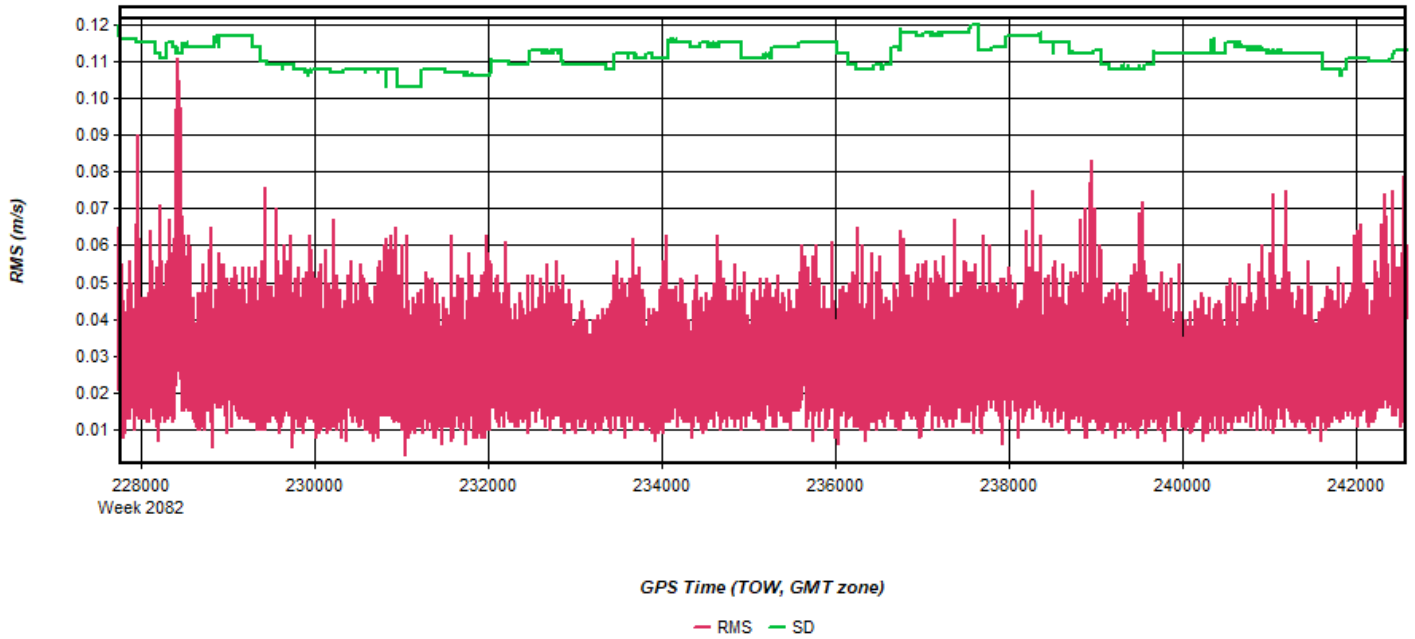
Process	20191203151442	by Unknown	on 12/13/2019	at 15:20:58
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Figure 17: 20191203151442 [Smoothed TC Combined] - Carrier Residual RMS Plot



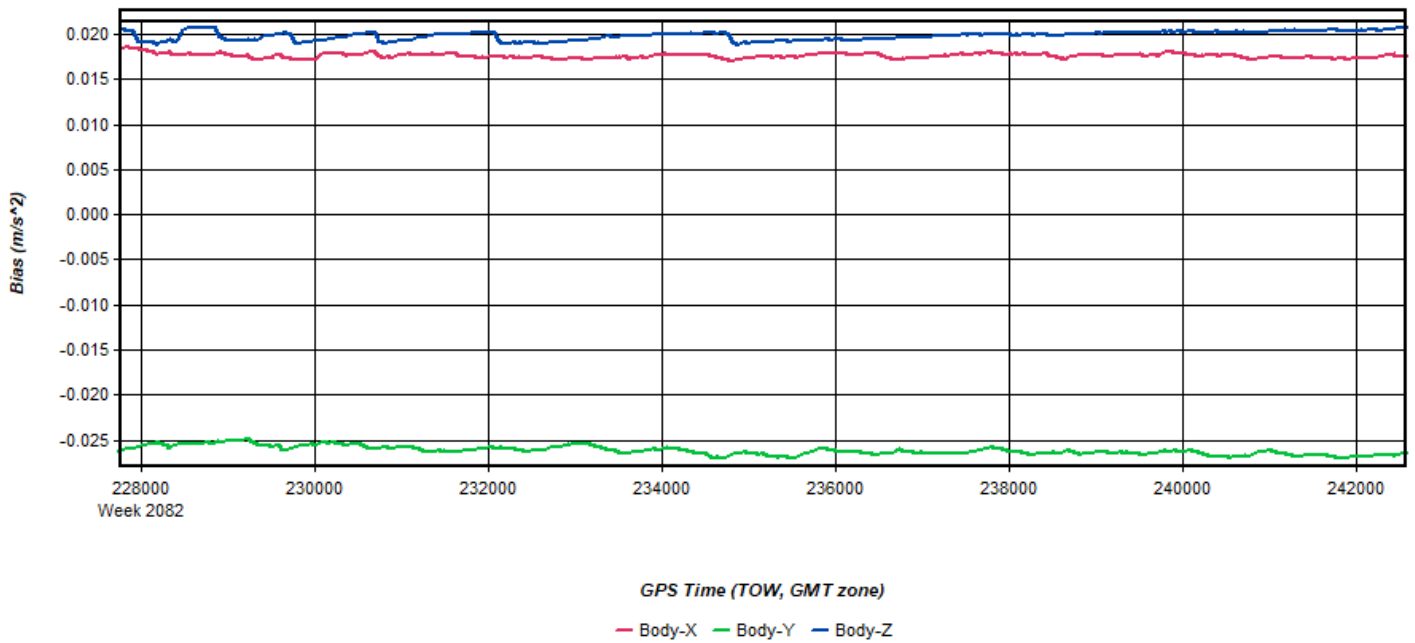
Process	20191203151442	by Unknown	on 12/13/2019	at 15:20:58
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Figure 18: 20191203151442 [Smoothed TC Combined] - L1 Doppler Residual RMS Plot



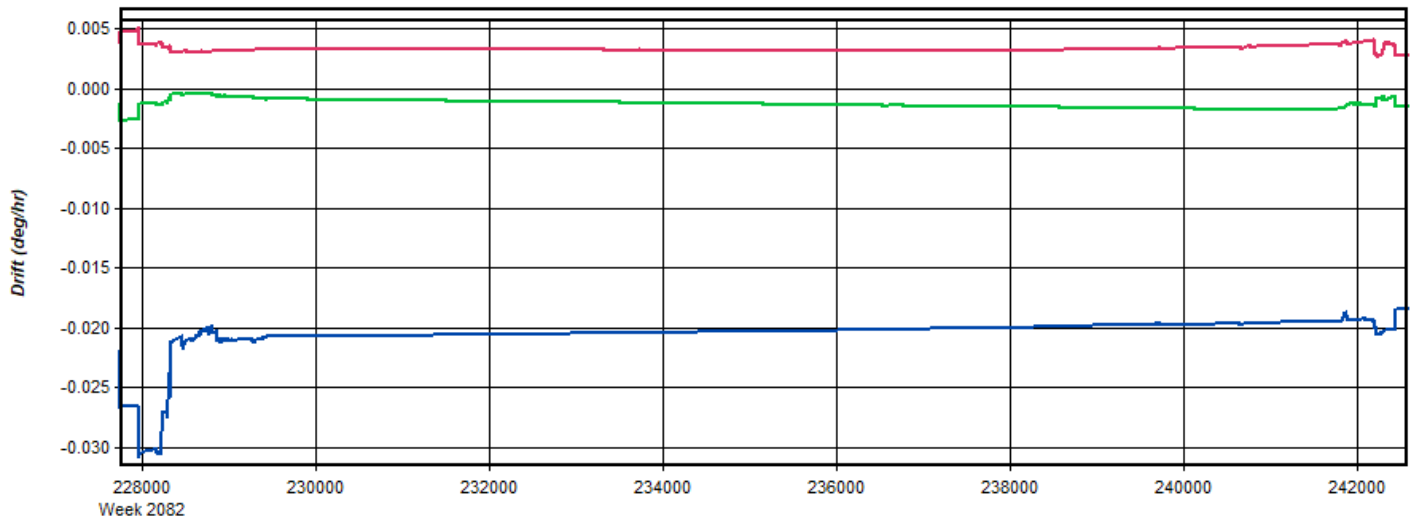
Process	20191203151442	by Unknown	on 12/13/2019	at 15:20:58
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Figure 19: 20191203151442 [Smoothed TC Combined] - Accelerometer Bias Plot



Process	20191203151442	by Unknown	on 12/13/2019	at 15:20:58
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Figure 20: 20191203151442 [Smoothed TC Combined] - Gyro Drift Plot



GPS Time (TOW, GMT zone)

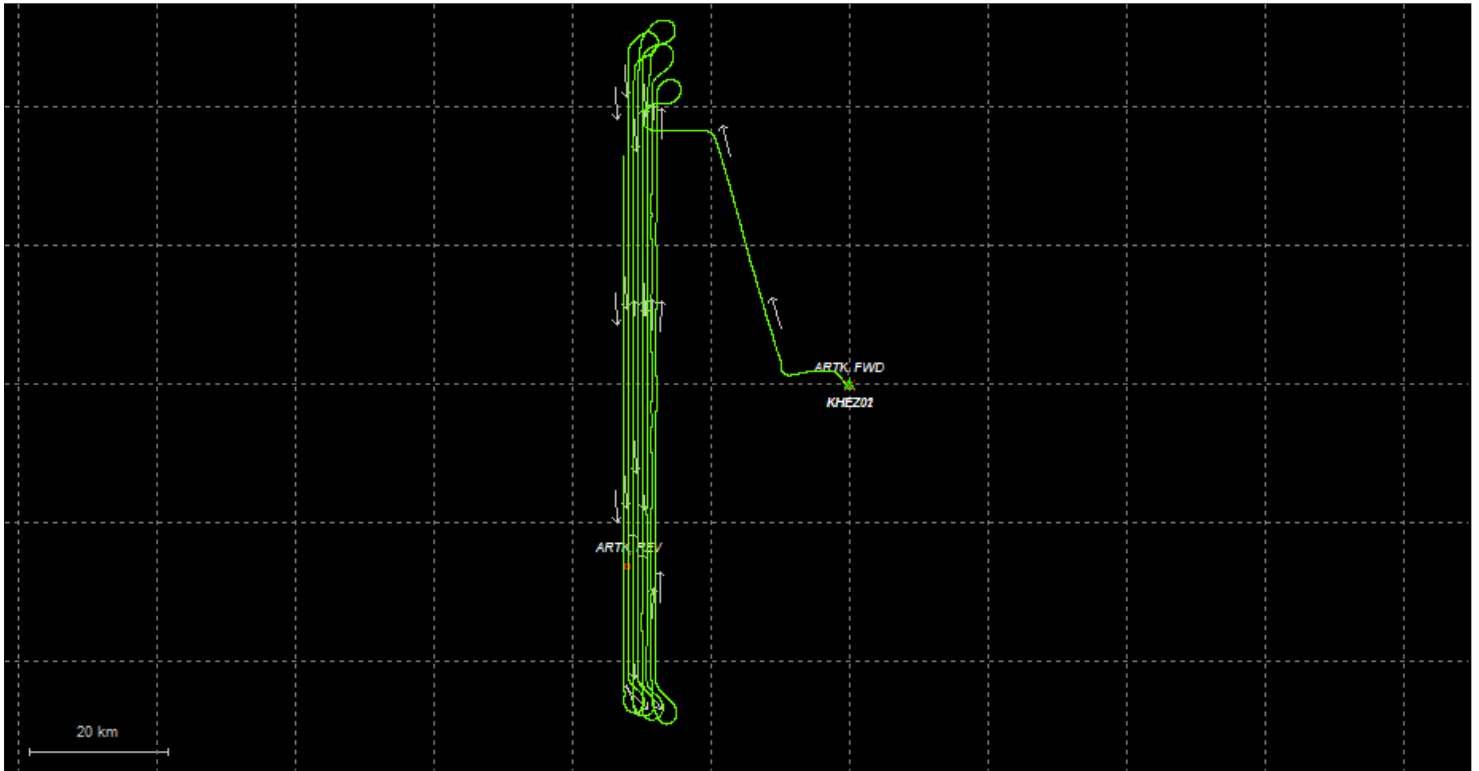
— Body-X — Body-Y — Body-Z

Process	20191203151442	by Unknown	on 12/13/2019	at 15:20:58
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Output Results for 20191203211932

Inertial Explorer Version 8.80.2305
12/13/2019

Figure 1: Smoothed TC Combined - Map



Process	20191203211932	by Unknown	on 12/13/2019	at 16:40:21
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Figure 2: 20191203211932 [Smoothed TC Combined] - Forward/Reverse or Combined Separation Plot

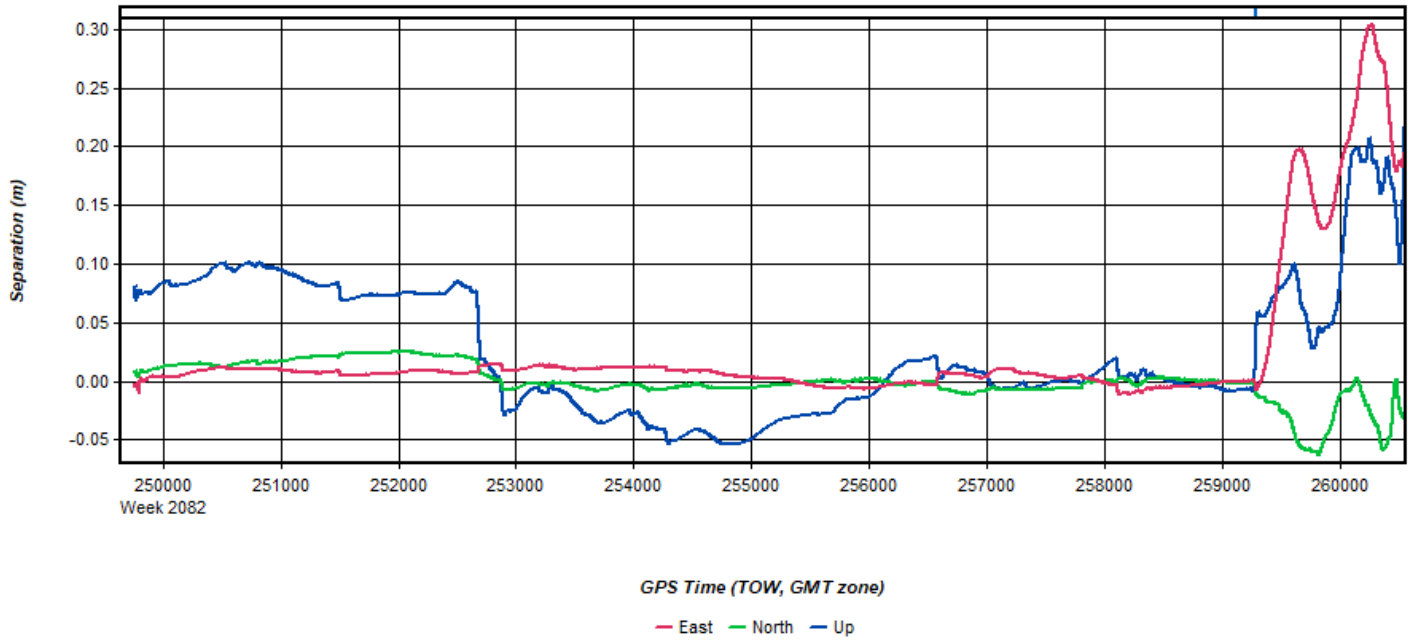


Figure 3: 20191203211932 [Smoothed TC Combined] - Float or Fixed Ambiguity

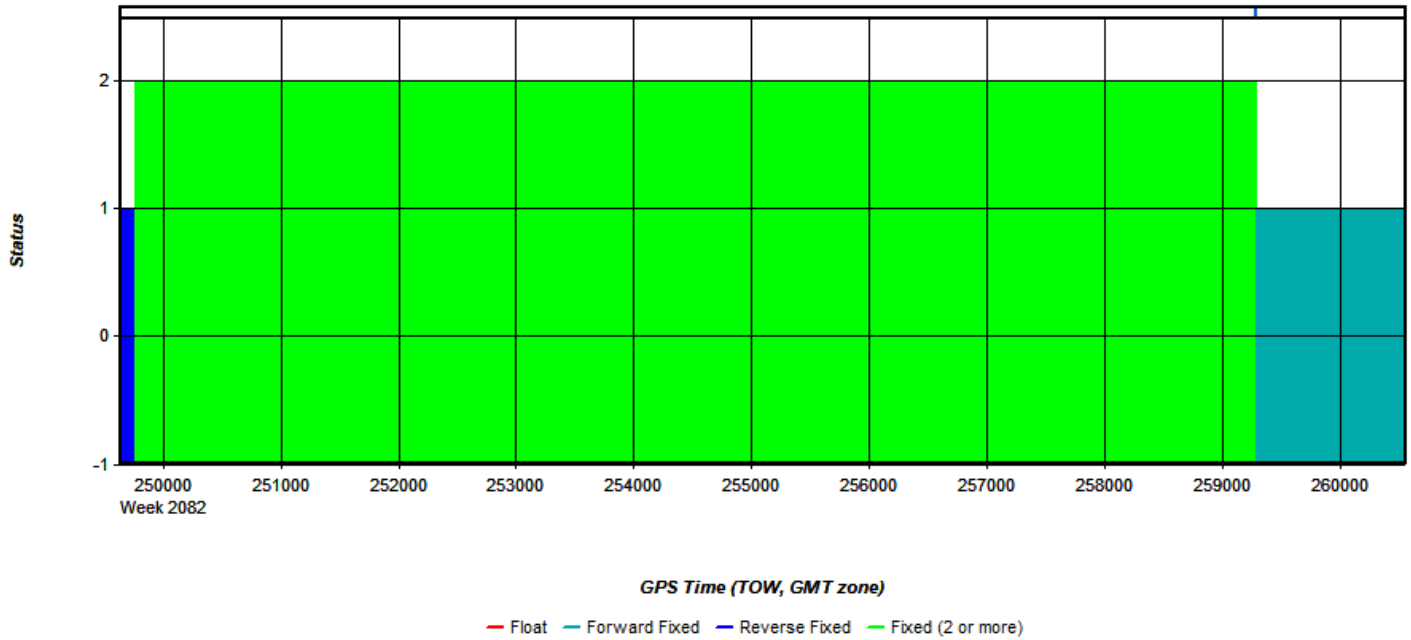


Figure 4: 20191203211932 [Smoothed TC Combined] - Forward/Reverse Separation Plot (Fixed)

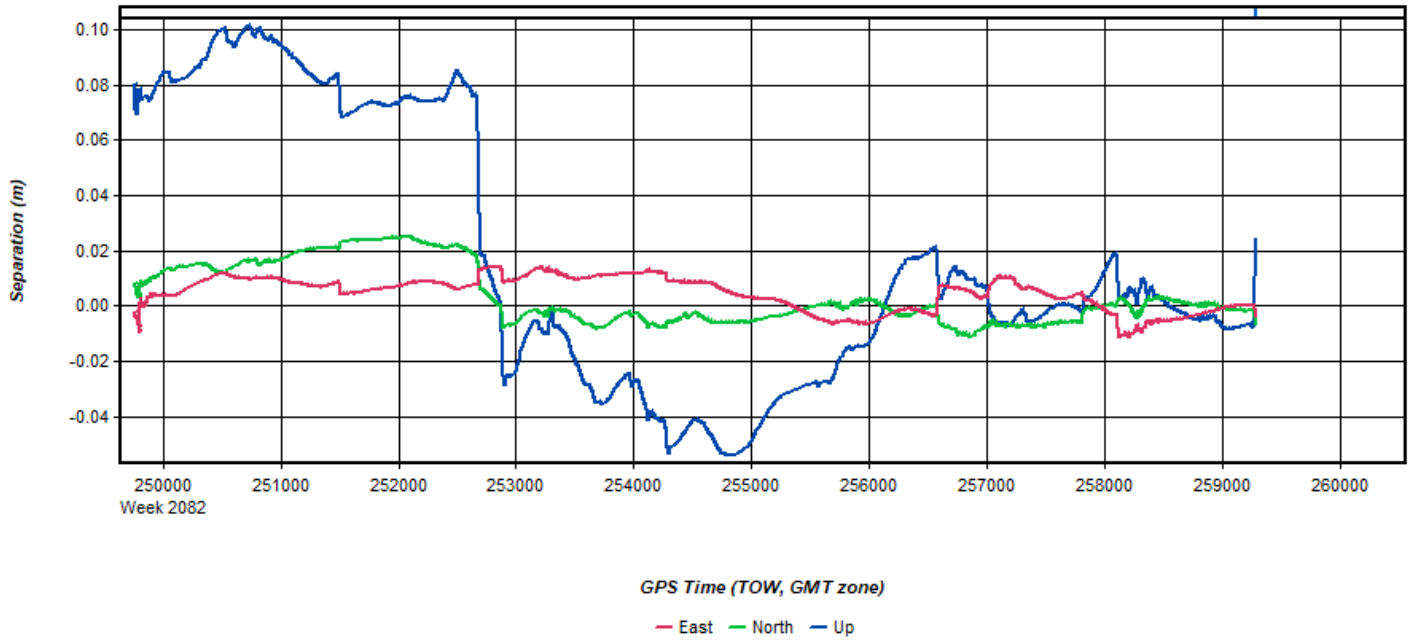


Figure 5: 20191203211932 [Smoothed TC Combined] - Estimated Position Accuracy Plot

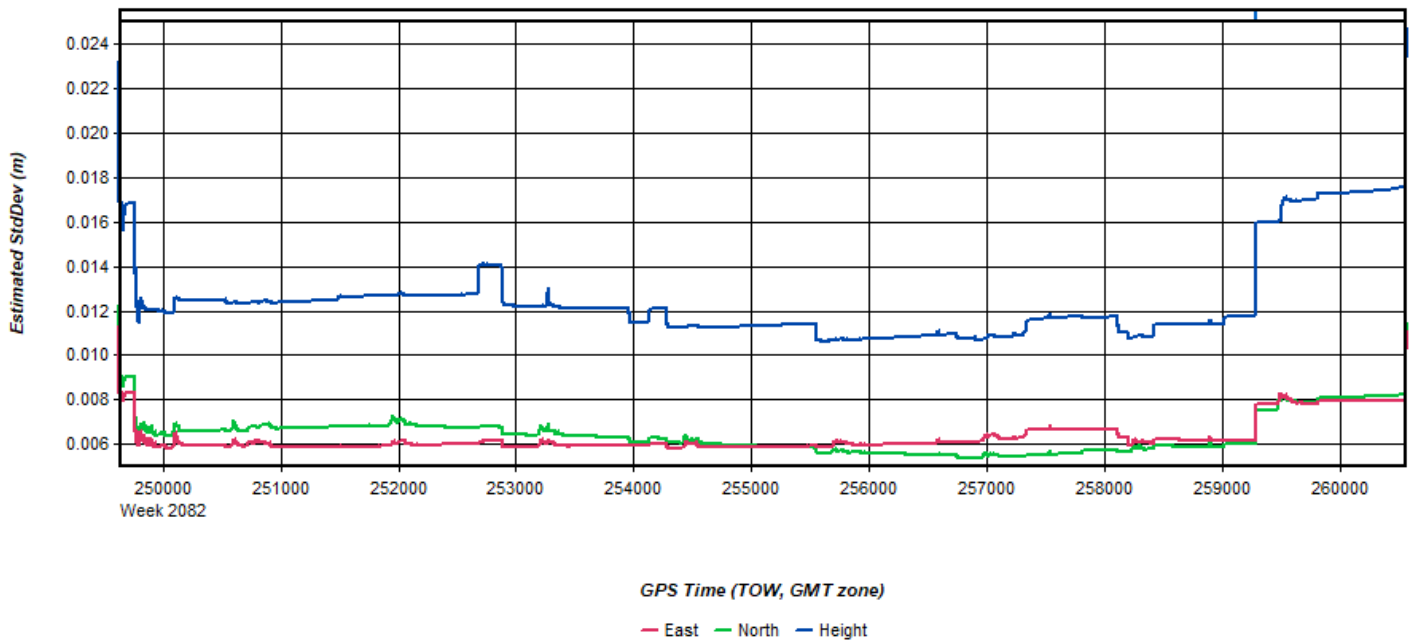
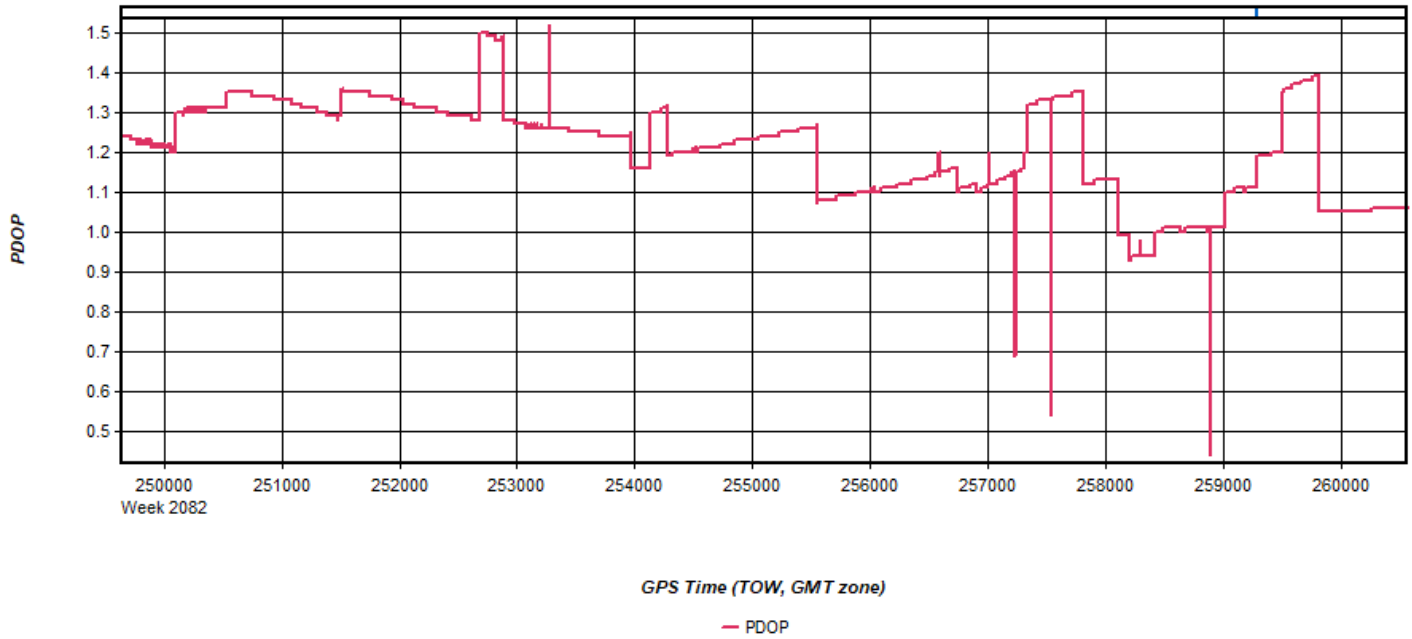
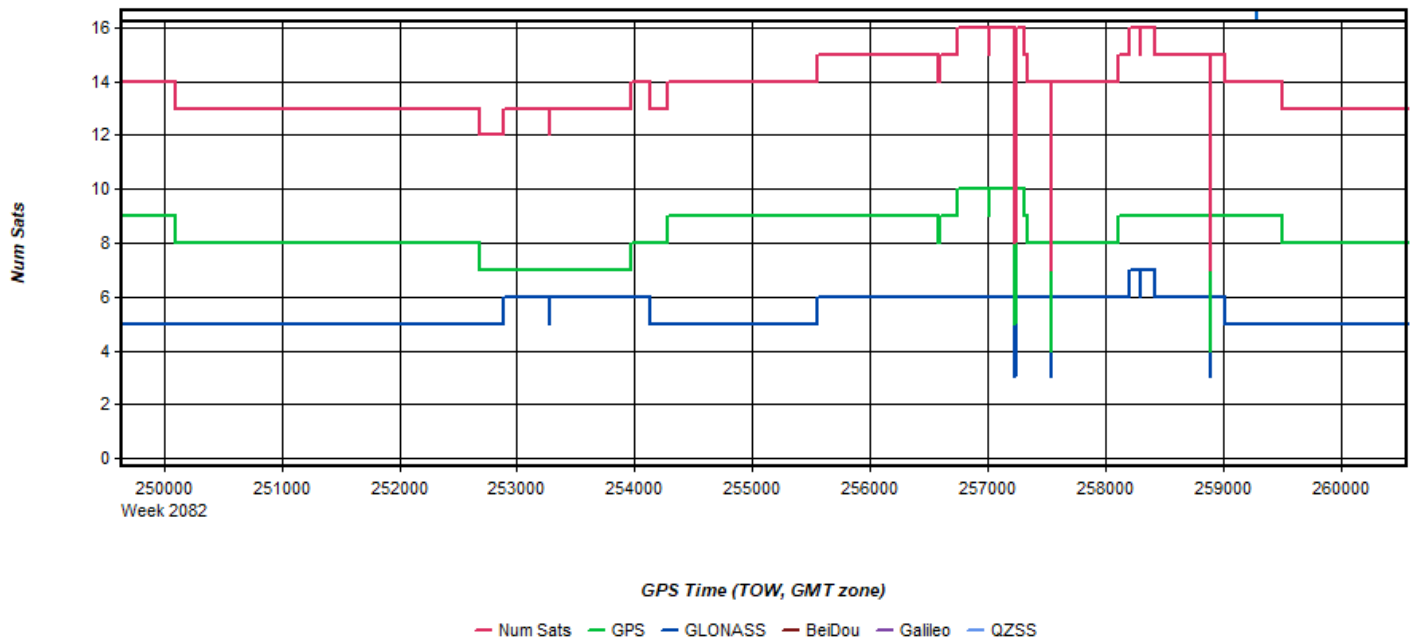


Figure 6: 20191203211932 [Smoothed TC Combined] - PDOP Plot



Process	20191203211932	by Unknown	on 12/13/2019	at 16:40:21
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Figure 7: 20191203211932 [Smoothed TC Combined] - Number of Satellites Line Plot



Process	20191203211932	by Unknown	on 12/13/2019	at 16:40:21
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Figure 8: 20191203211932 [Smoothed TC Combined] - Status flag for IMU processing

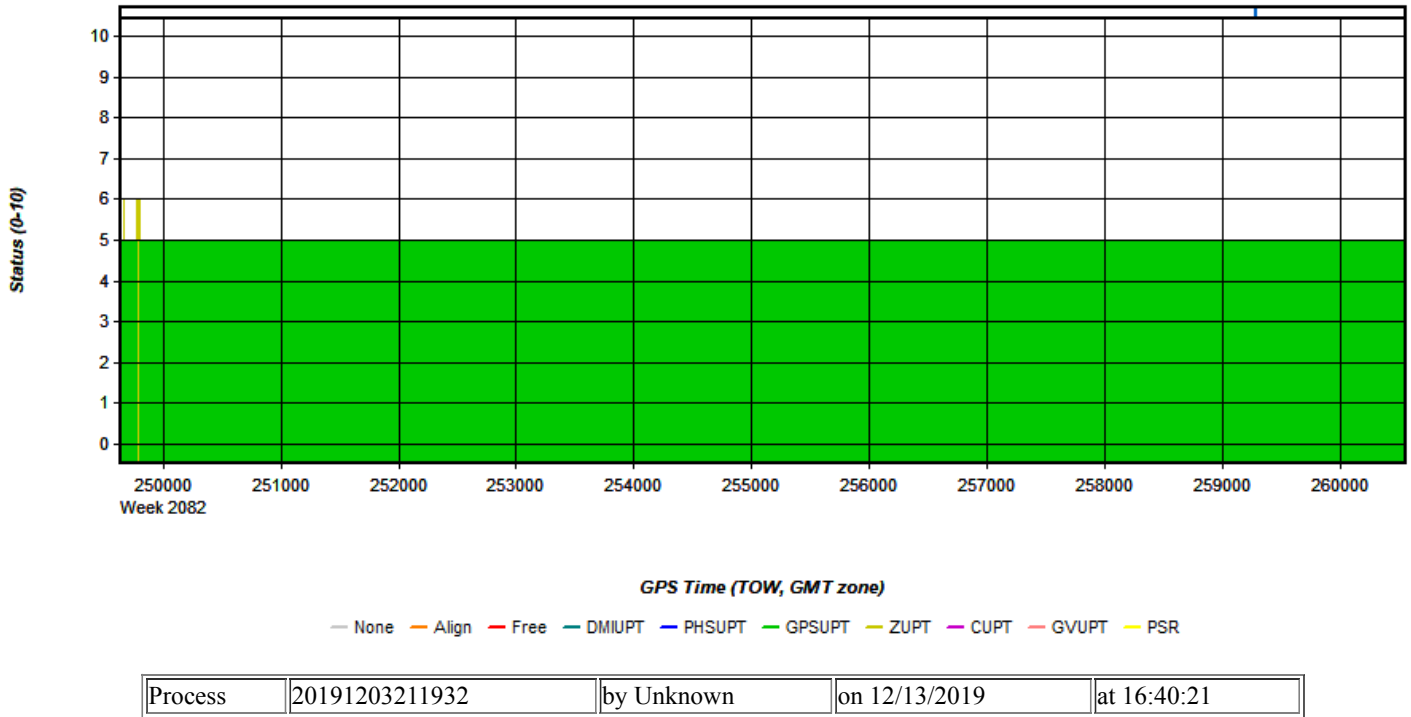


Figure 9: 20191203211932 [Smoothed TC Combined] - Fwd/Rev Attitude Separation Plot

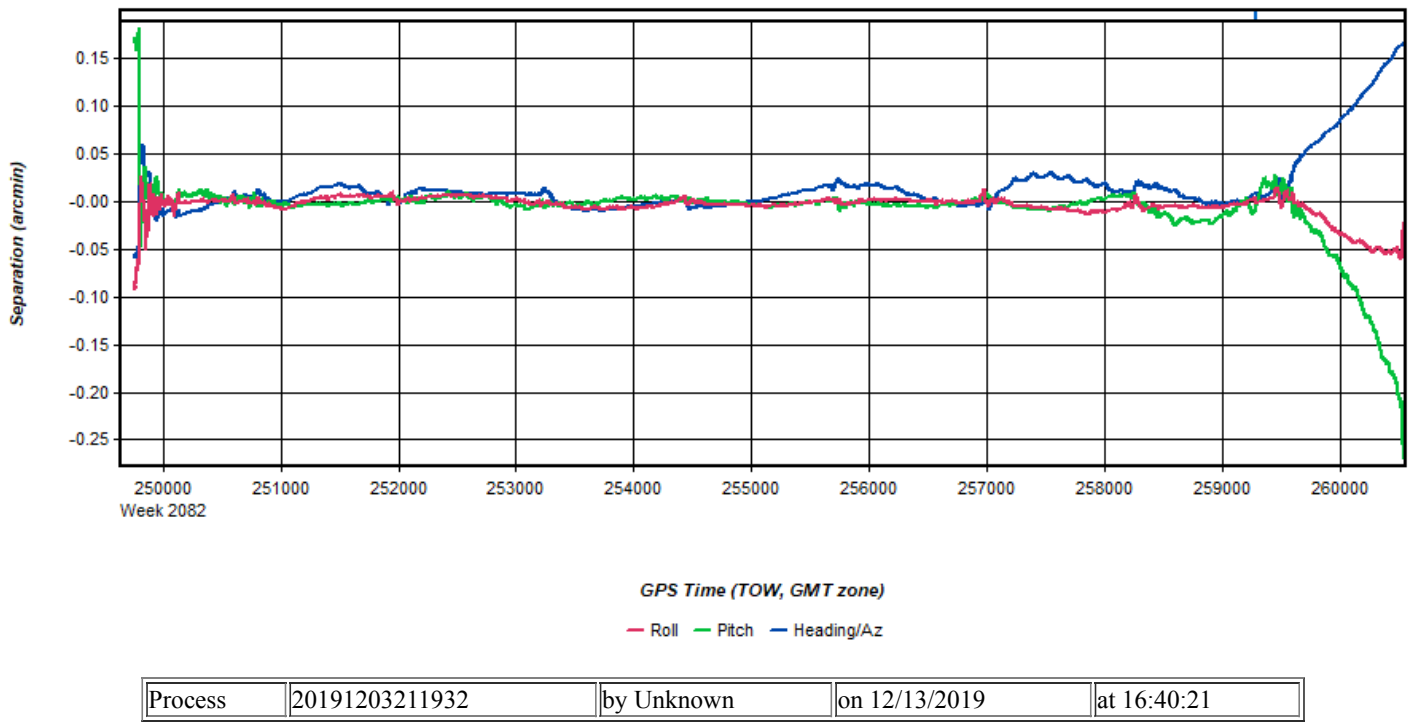
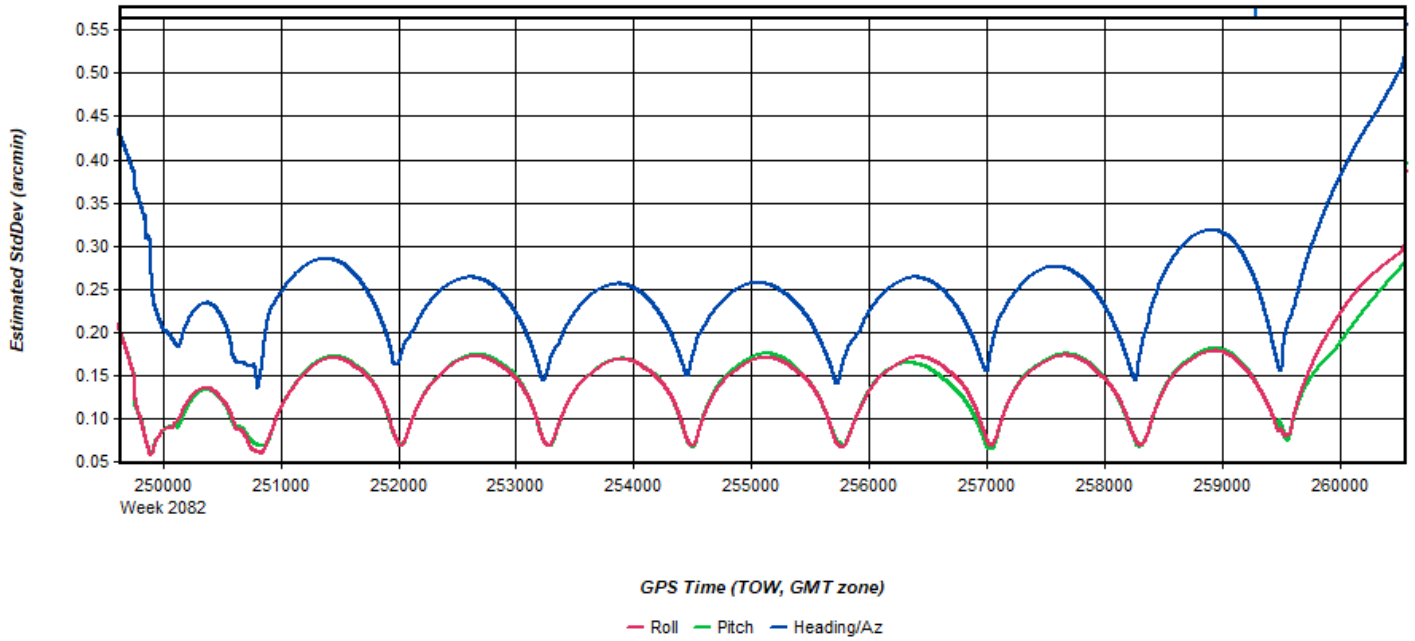
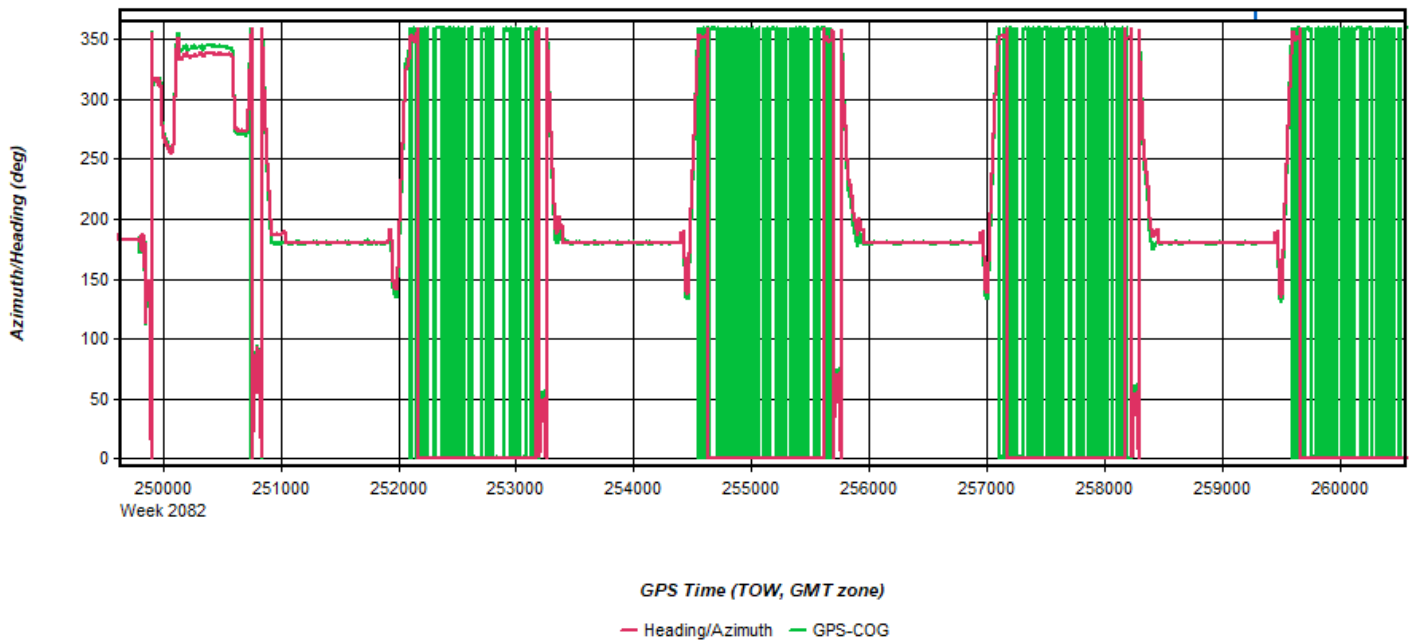


Figure 10: 20191203211932 [Smoothed TC Combined] - Estimated Attitude Accuracy Plot



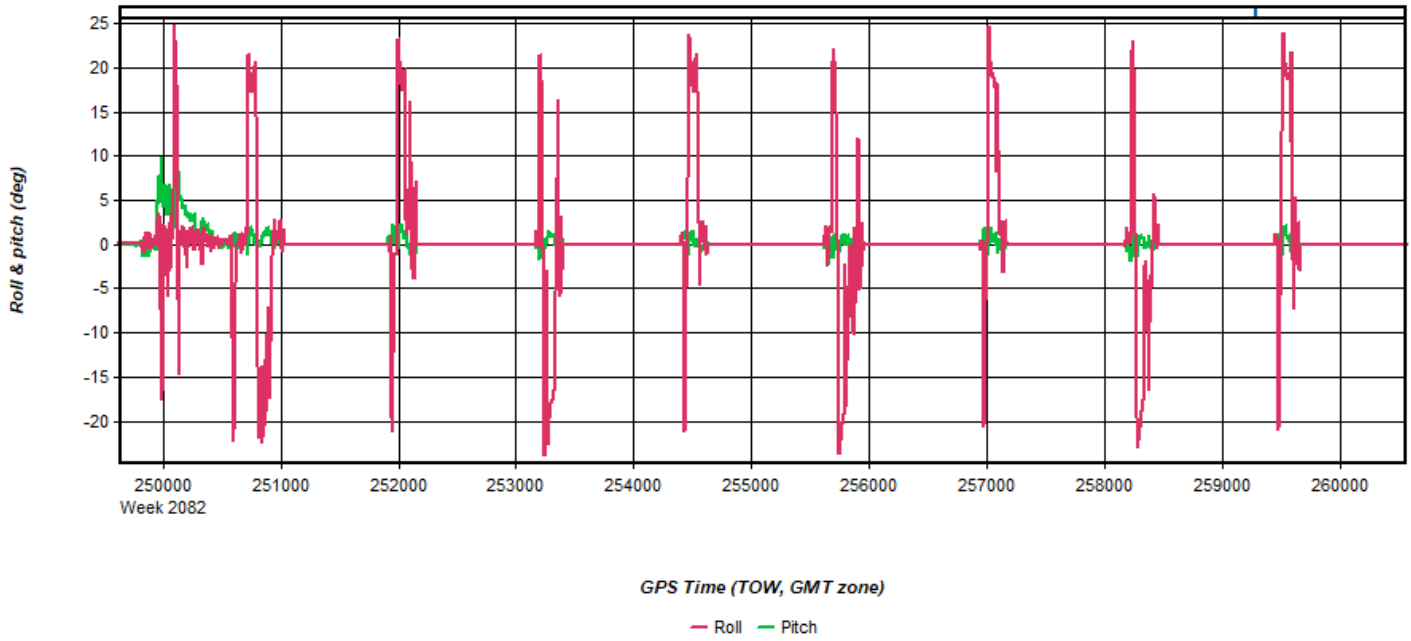
Process	20191203211932	by Unknown	on 12/13/2019	at 16:40:21
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Figure 11: 20191203211932 [Smoothed TC Combined] - Azimuth Plot



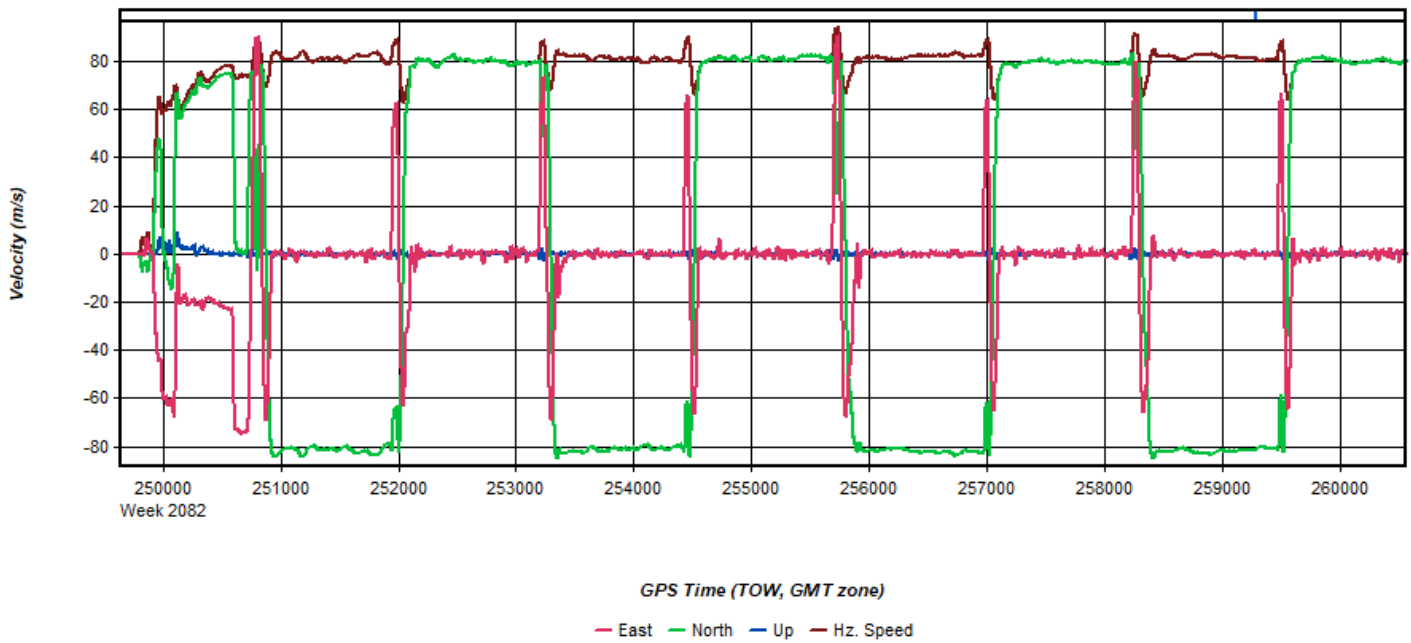
Process	20191203211932	by Unknown	on 12/13/2019	at 16:40:21
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Figure 12: 20191203211932 [Smoothed TC Combined] - Roll & Pitch Plot



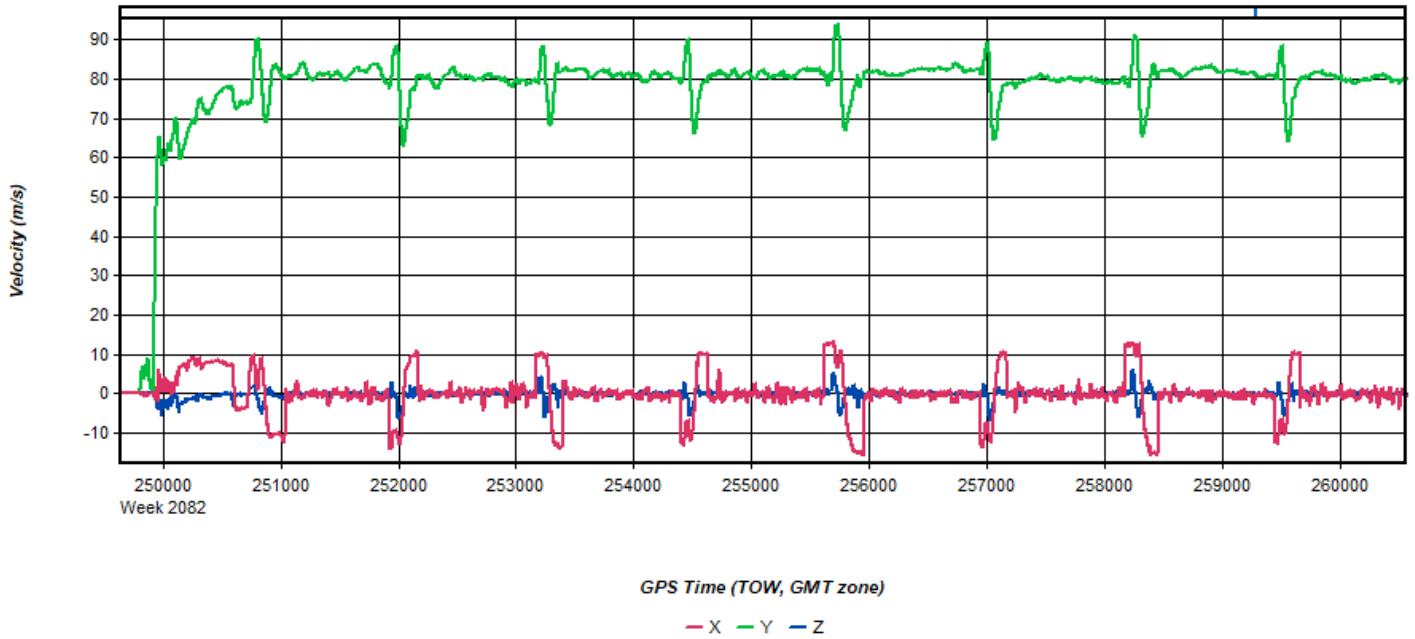
Process	20191203211932	by Unknown	on 12/13/2019	at 16:40:21
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Figure 13: 20191203211932 [Smoothed TC Combined] - Velocity Profile Plot



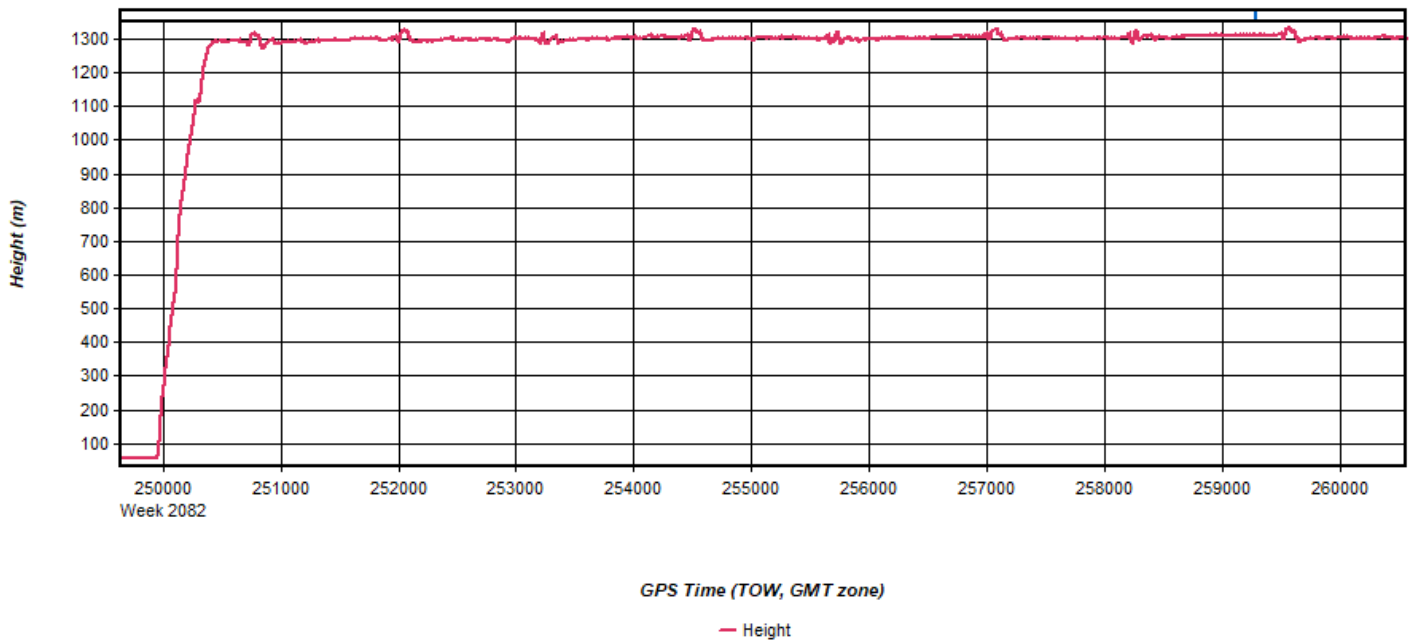
Process	20191203211932	by Unknown	on 12/13/2019	at 16:40:21
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Figure 14: 20191203211932 [Smoothed TC Combined] - Body Frame Velocity Plot



Process	20191203211932	by Unknown	on 12/13/2019	at 16:40:21
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Figure 15: 20191203211932 [Smoothed TC Combined] - Height Profile Plot



Process	20191203211932	by Unknown	on 12/13/2019	at 16:40:21
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Figure 16: 20191203211932 [Smoothed TC Combined] - C/A Code Residual RMS Plot

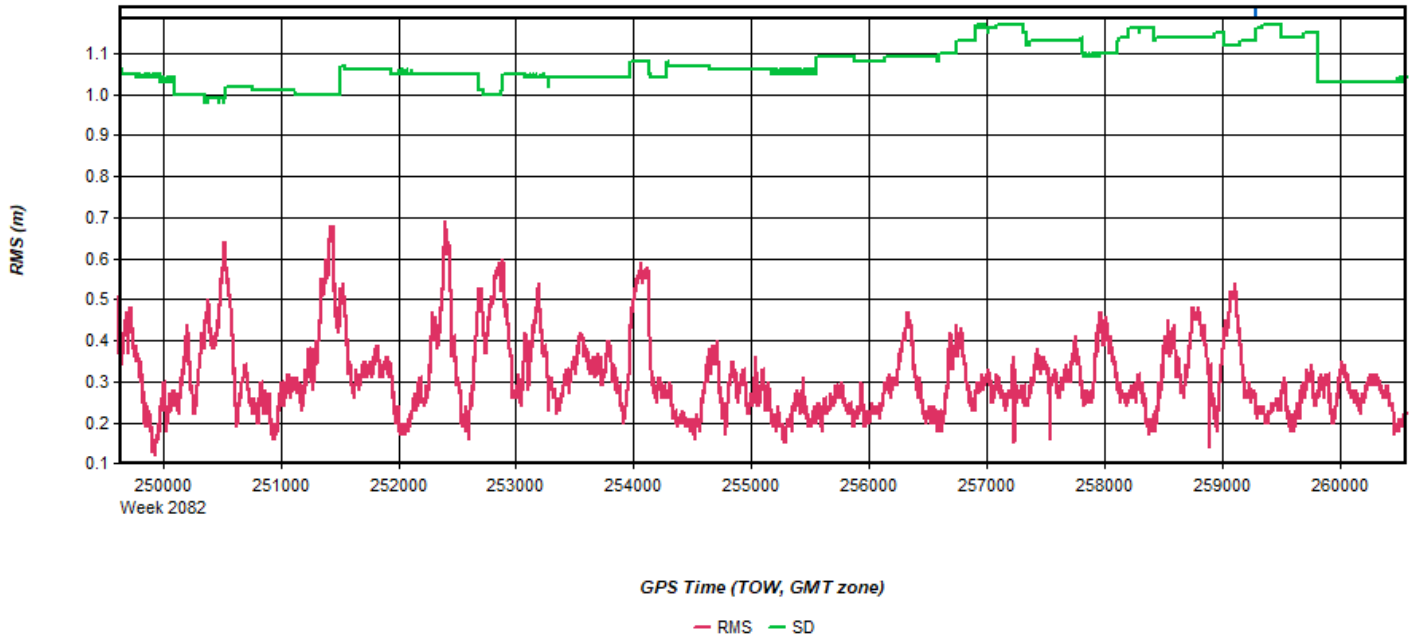


Figure 17: 20191203211932 [Smoothed TC Combined] - Carrier Residual RMS Plot

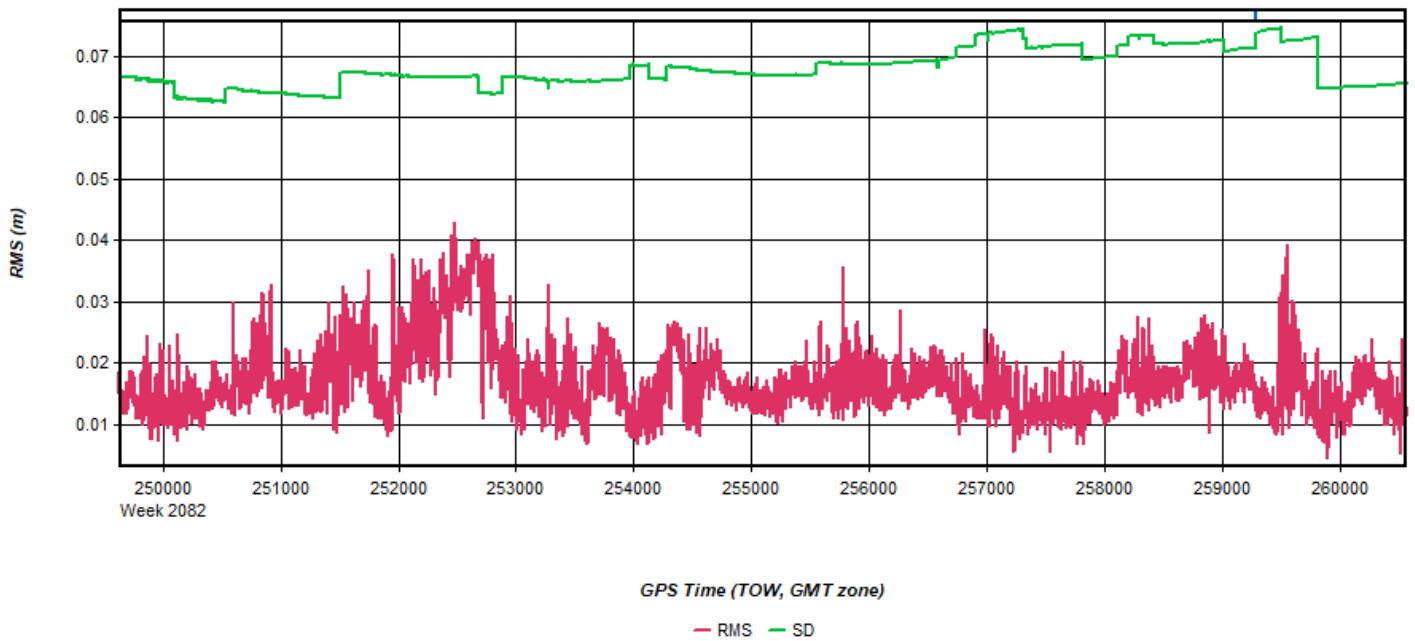
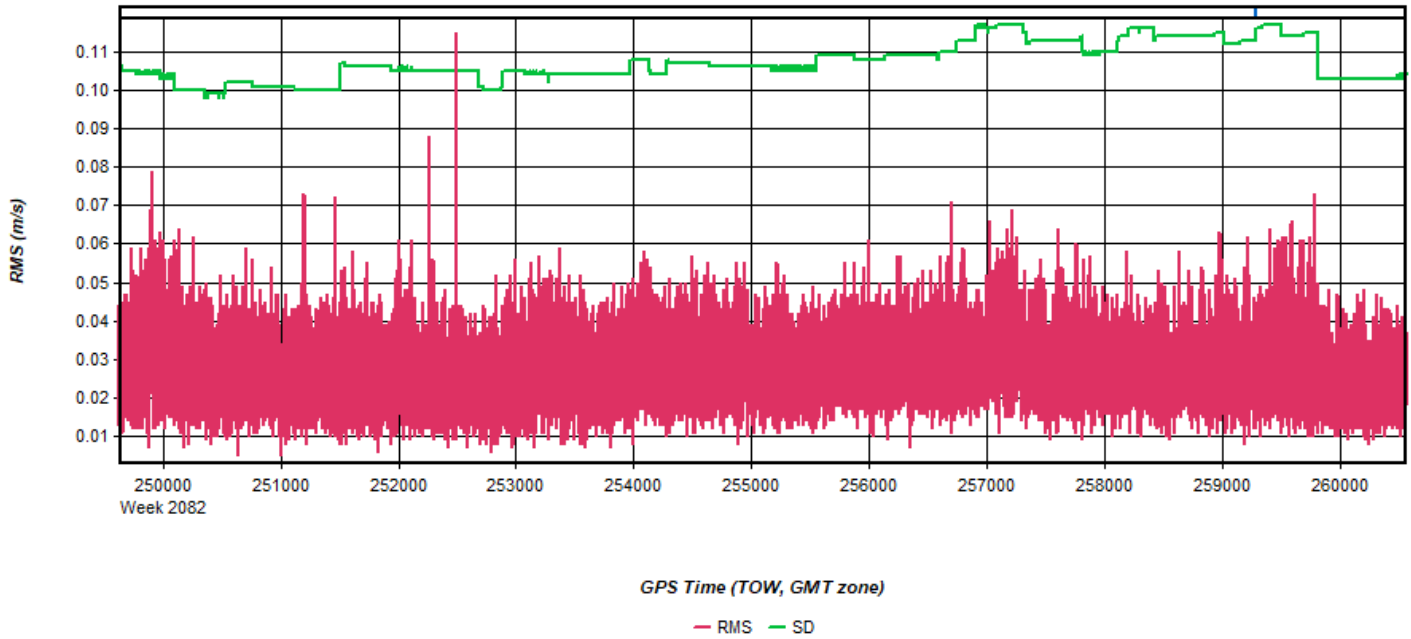
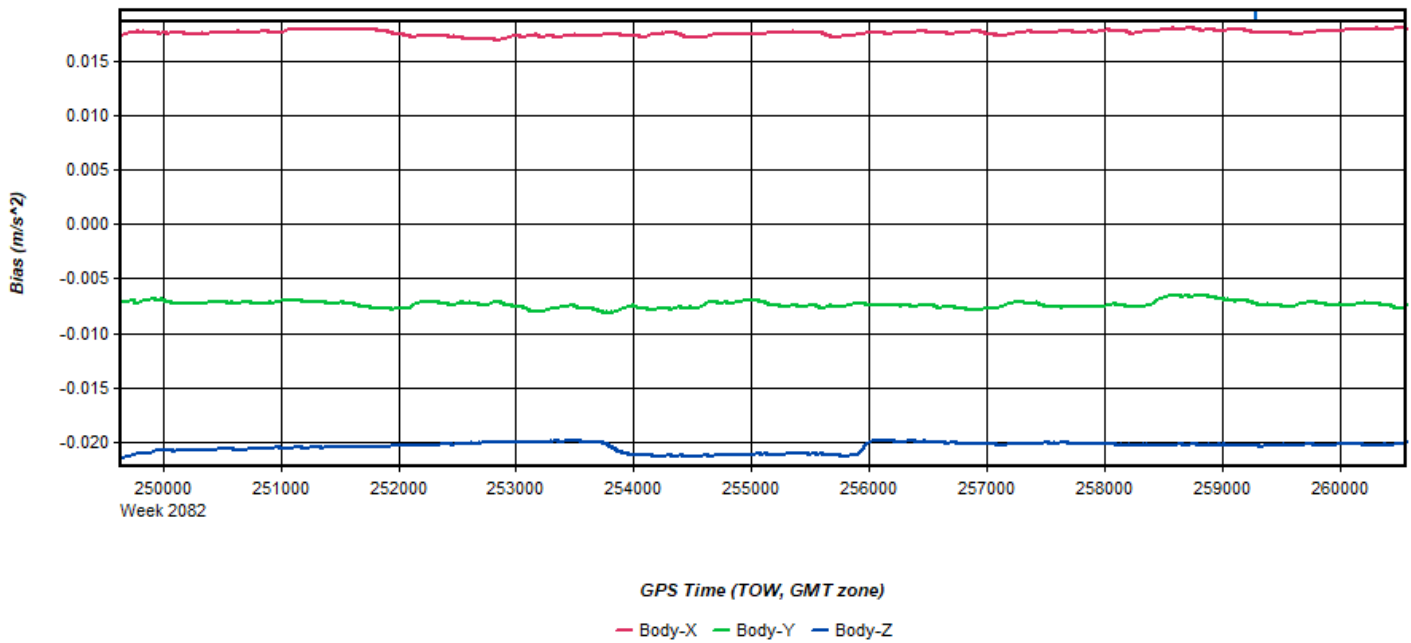


Figure 18: 20191203211932 [Smoothed TC Combined] - L1 Doppler Residual RMS Plot



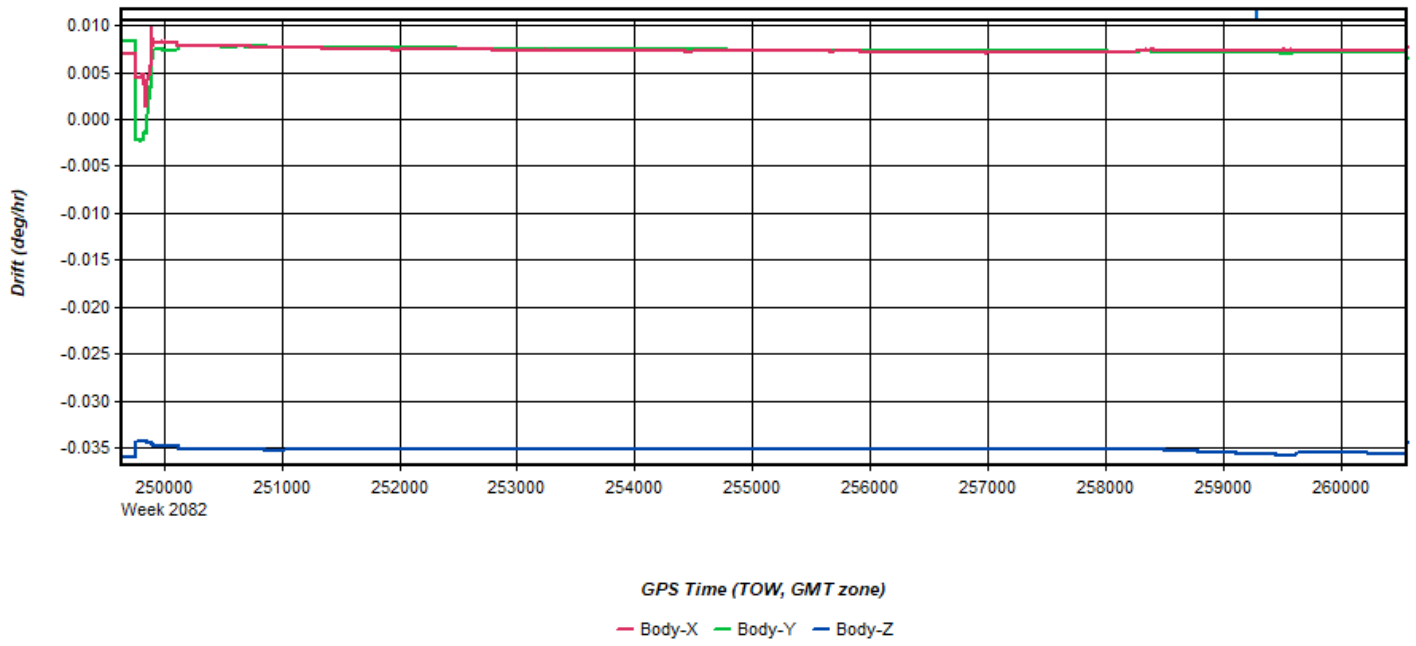
Process	20191203211932	by Unknown	on 12/13/2019	at 16:40:21
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Figure 19: 20191203211932 [Smoothed TC Combined] - Accelerometer Bias Plot



Process	20191203211932	by Unknown	on 12/13/2019	at 16:40:21
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Figure 20: 20191203211932 [Smoothed TC Combined] - Gyro Drift Plot

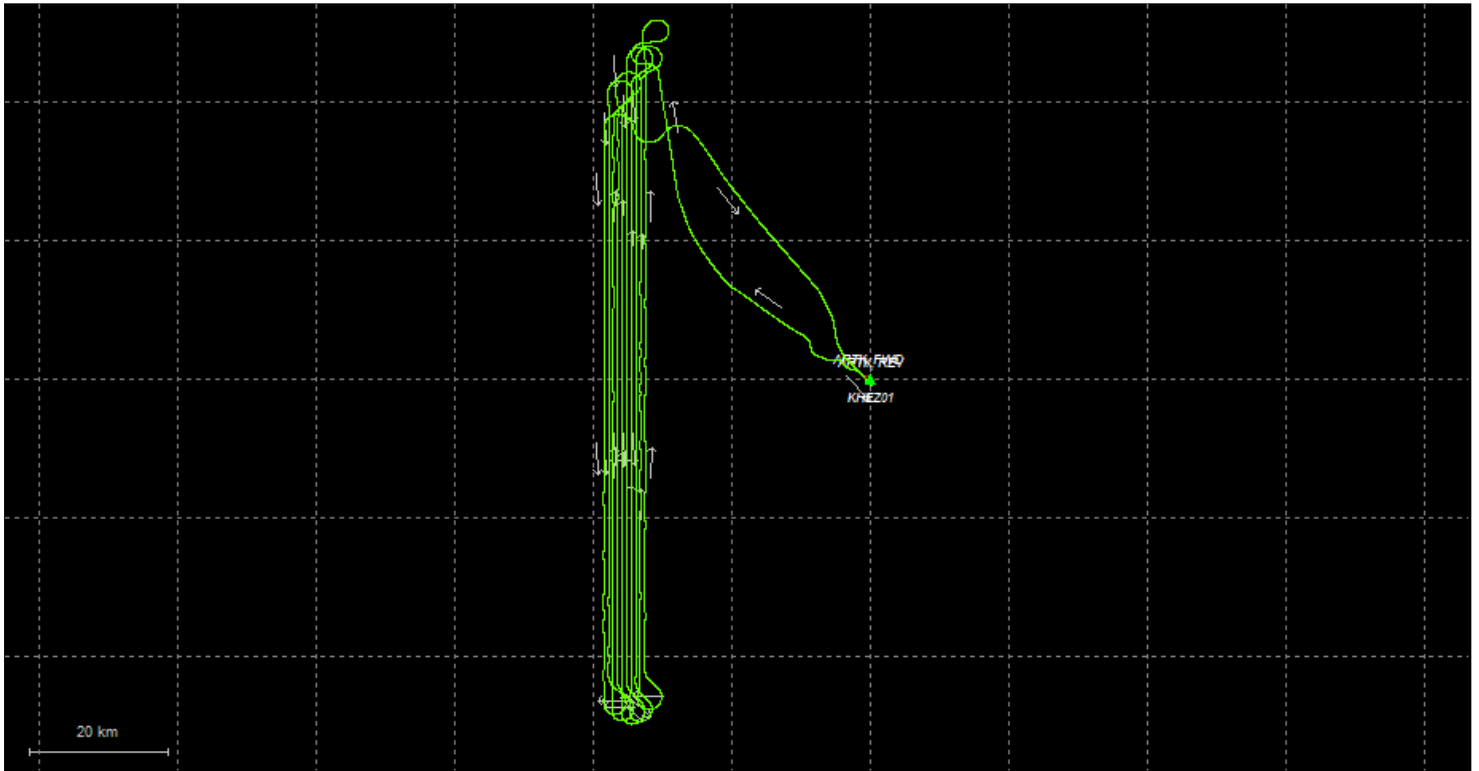


Process	20191203211932	by Unknown	on 12/13/2019	at 16:40:21
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Output Results for 20191204151927

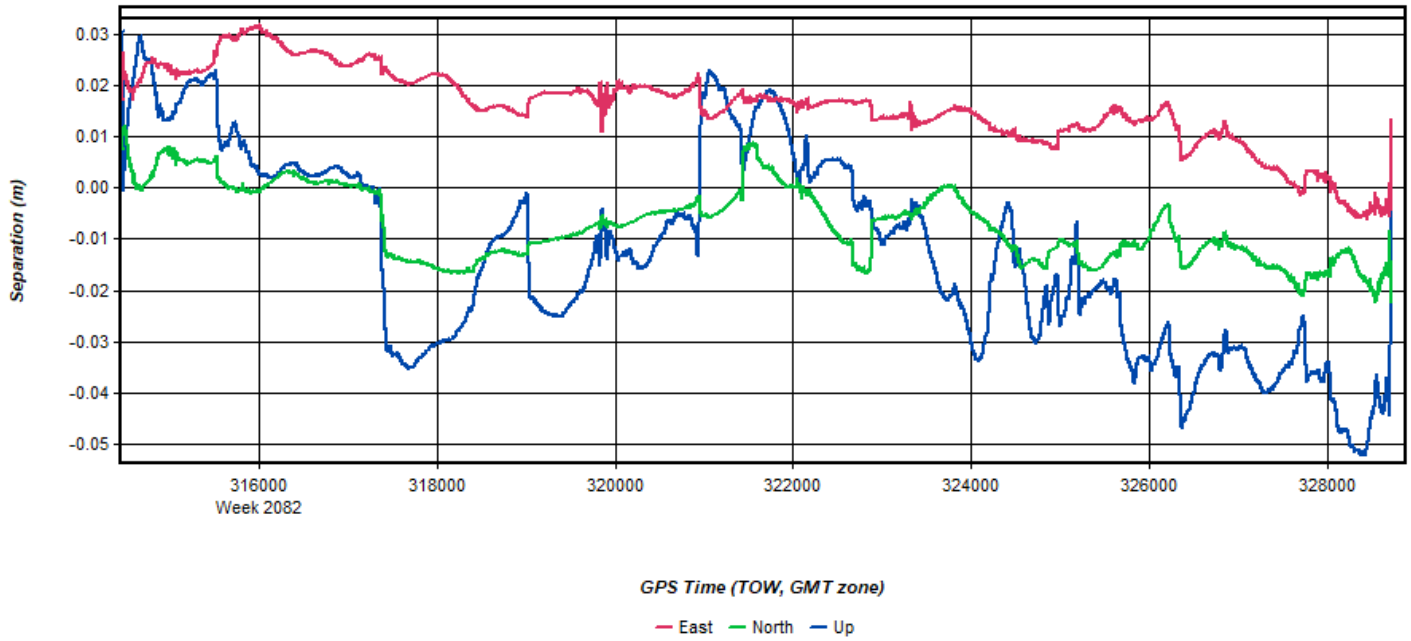
Inertial Explorer Version 8.80.2305
12/13/2019

Figure 1: Smoothed TC Combined - Map



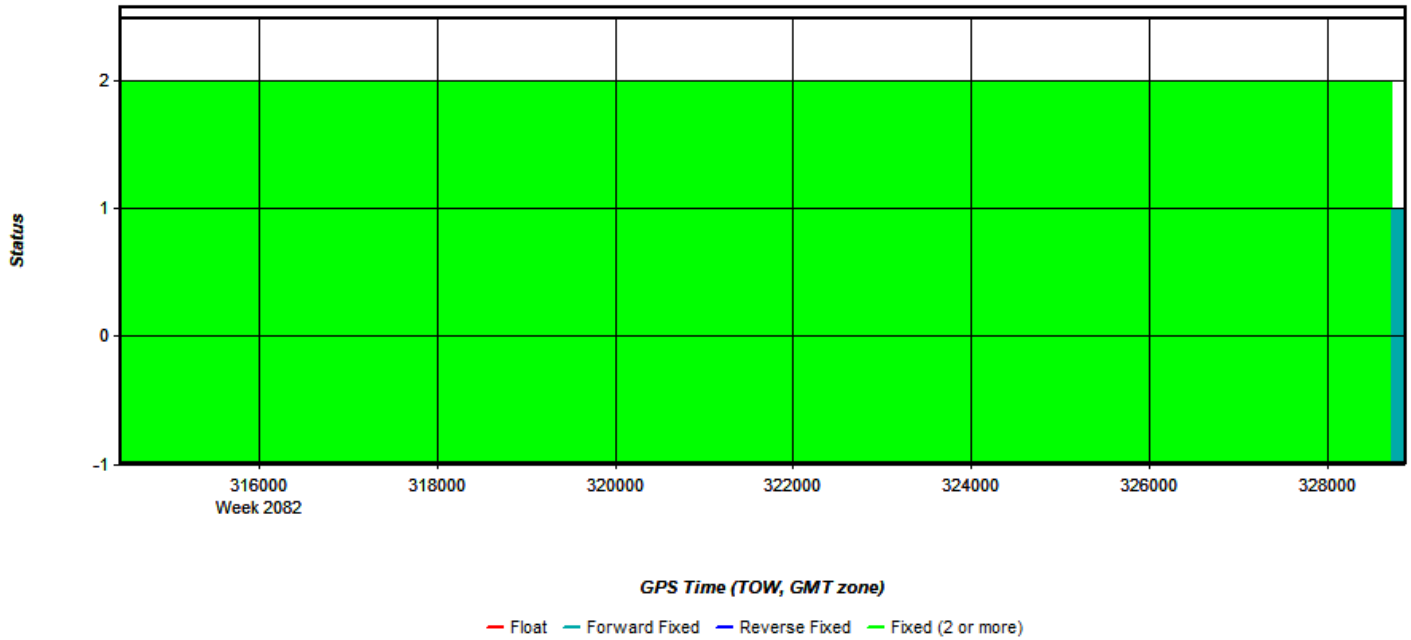
Process	20191204151927	by Unknown	on 12/13/2019	at 18:12:06
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Figure 2: 20191204151927 [Smoothed TC Combined] - Forward/Reverse or Combined Separation Plot



Process	20191204151927	by Unknown	on 12/13/2019	at 18:12:06
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Figure 3: 20191204151927 [Smoothed TC Combined] - Float or Fixed Ambiguity



Process	20191204151927	by Unknown	on 12/13/2019	at 18:12:06
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Figure 4: 20191204151927 [Smoothed TC Combined] - Forward/Reverse Separation Plot (Fixed)

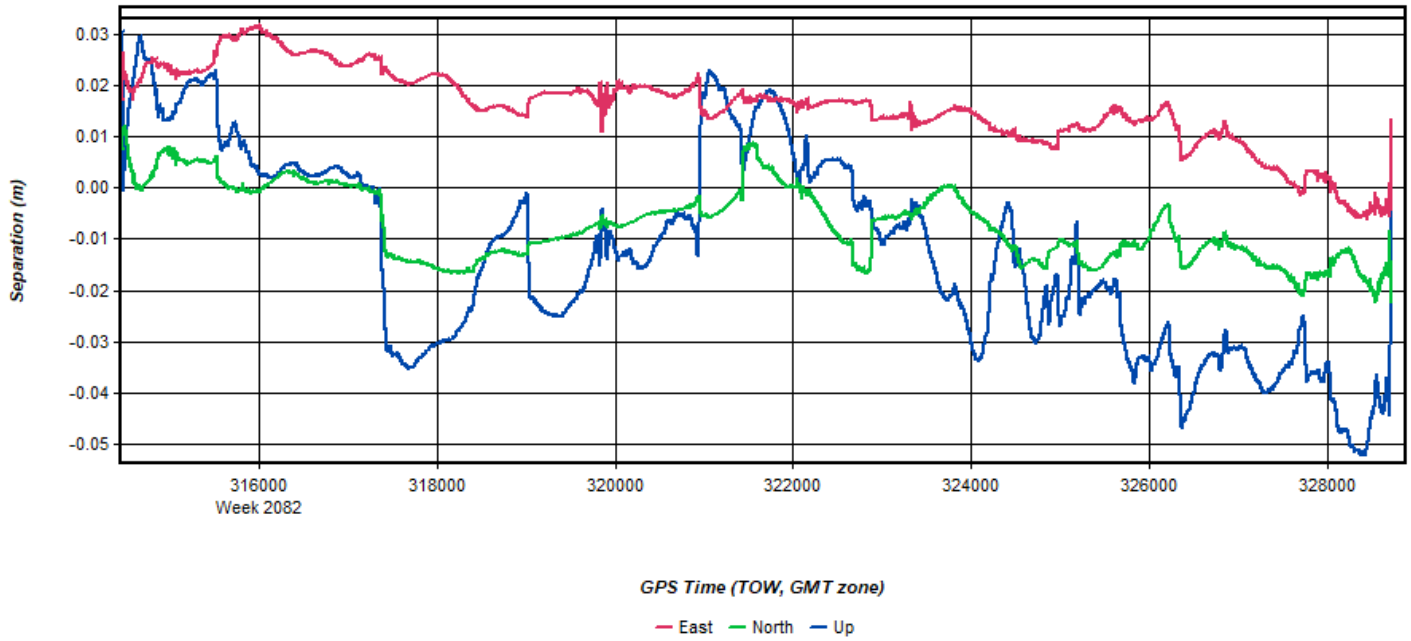


Figure 5: 20191204151927 [Smoothed TC Combined] - Estimated Position Accuracy Plot

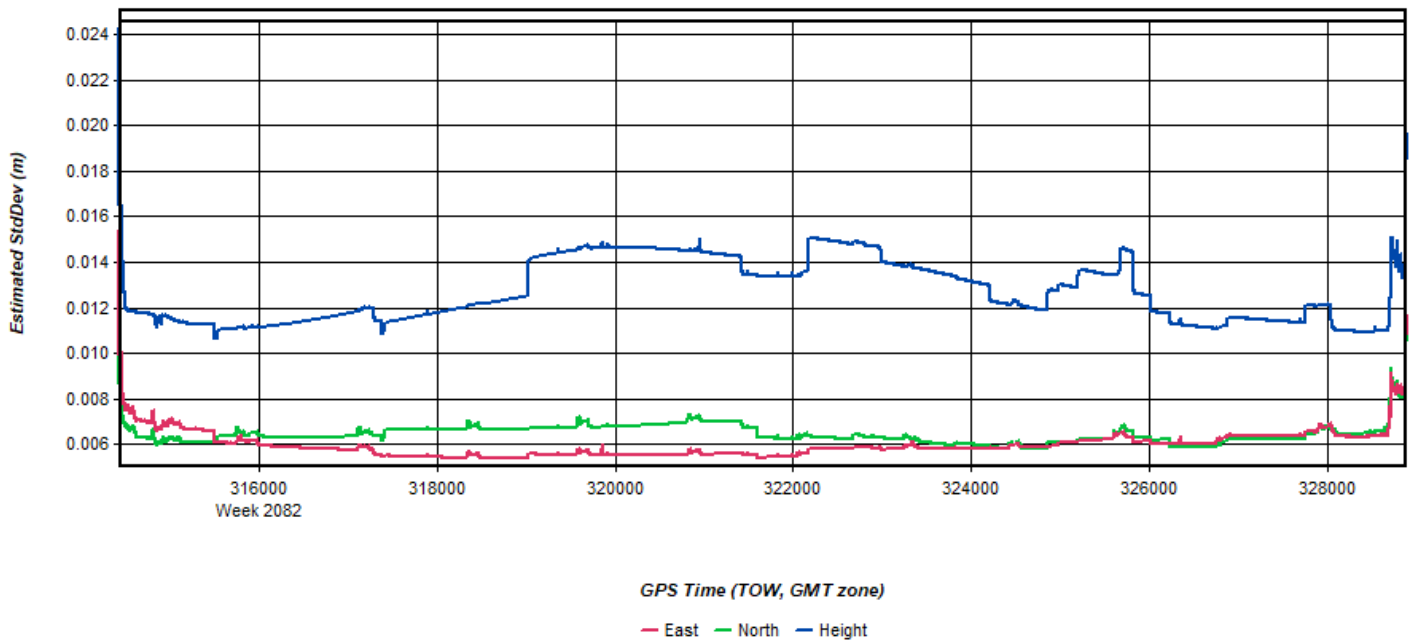
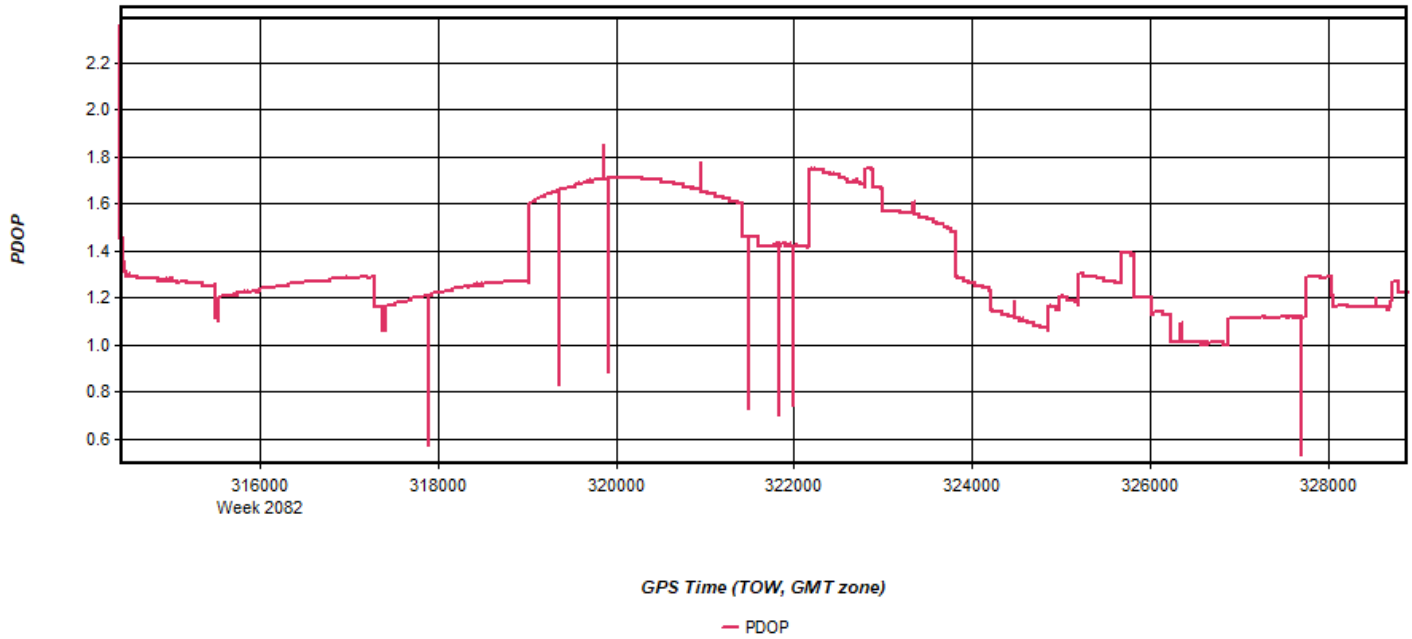
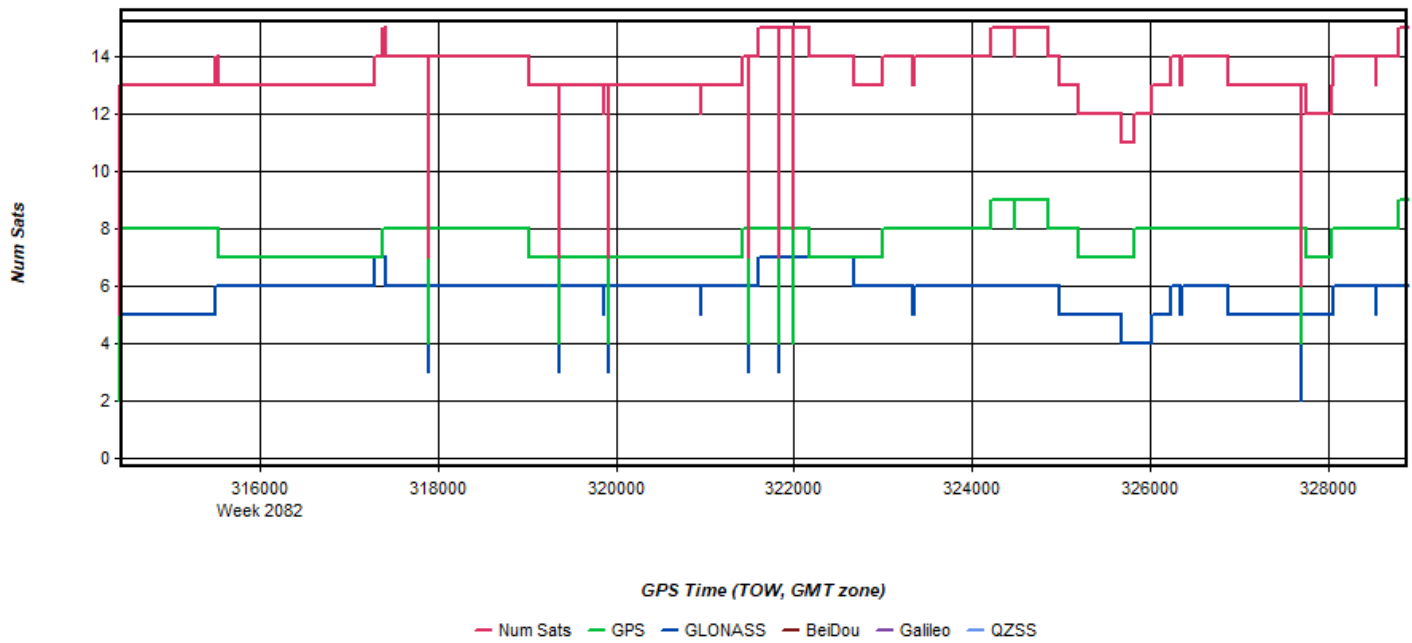


Figure 6: 20191204151927 [Smoothed TC Combined] - PDOP Plot



Process	20191204151927	by Unknown	on 12/13/2019	at 18:12:06
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Figure 7: 20191204151927 [Smoothed TC Combined] - Number of Satellites Line Plot



Process	20191204151927	by Unknown	on 12/13/2019	at 18:12:06
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Figure 8: 20191204151927 [Smoothed TC Combined] - Status flag for IMU processing

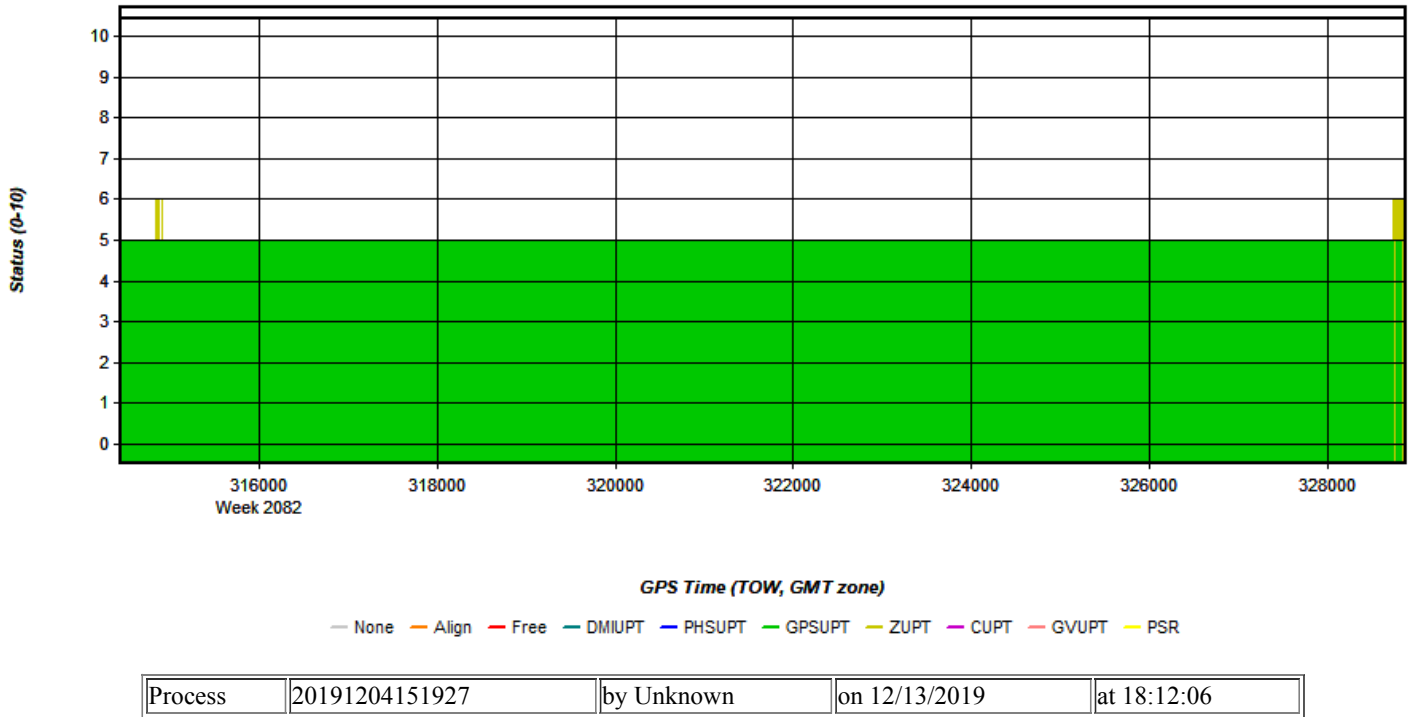


Figure 9: 20191204151927 [Smoothed TC Combined] - Fwd/Rev Attitude Separation Plot

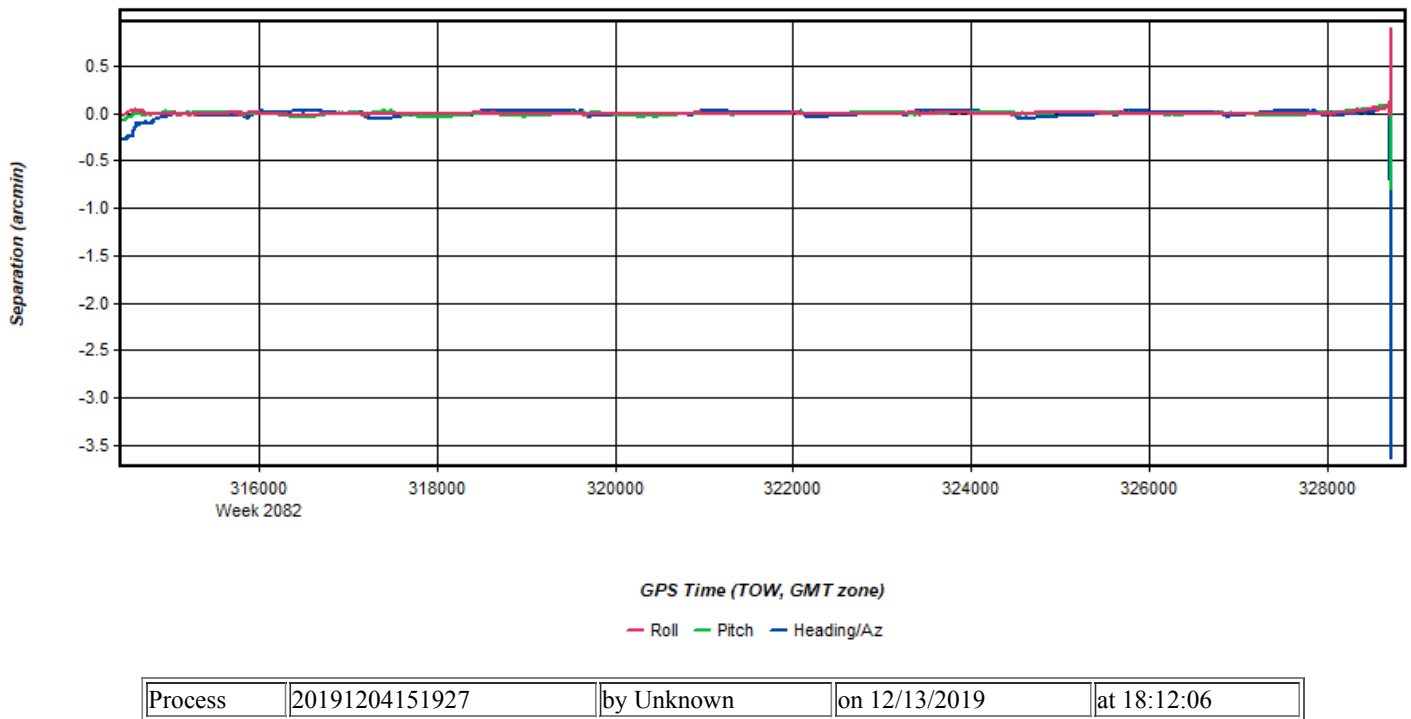
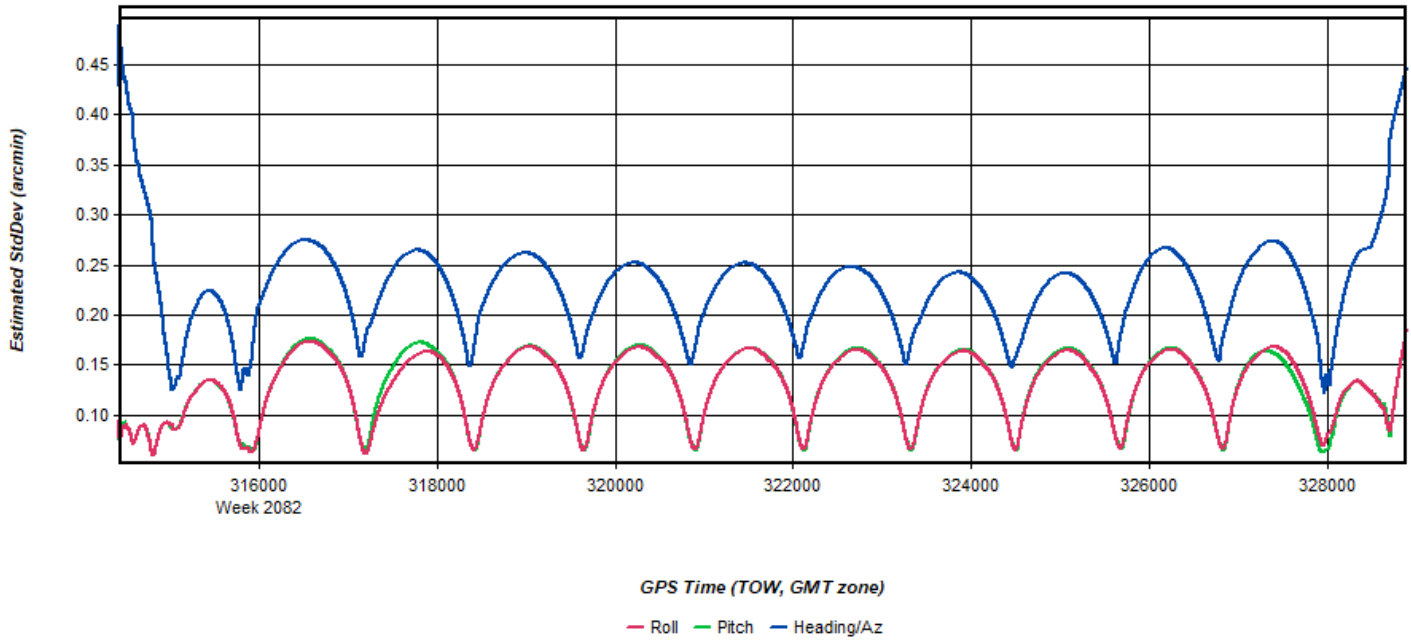
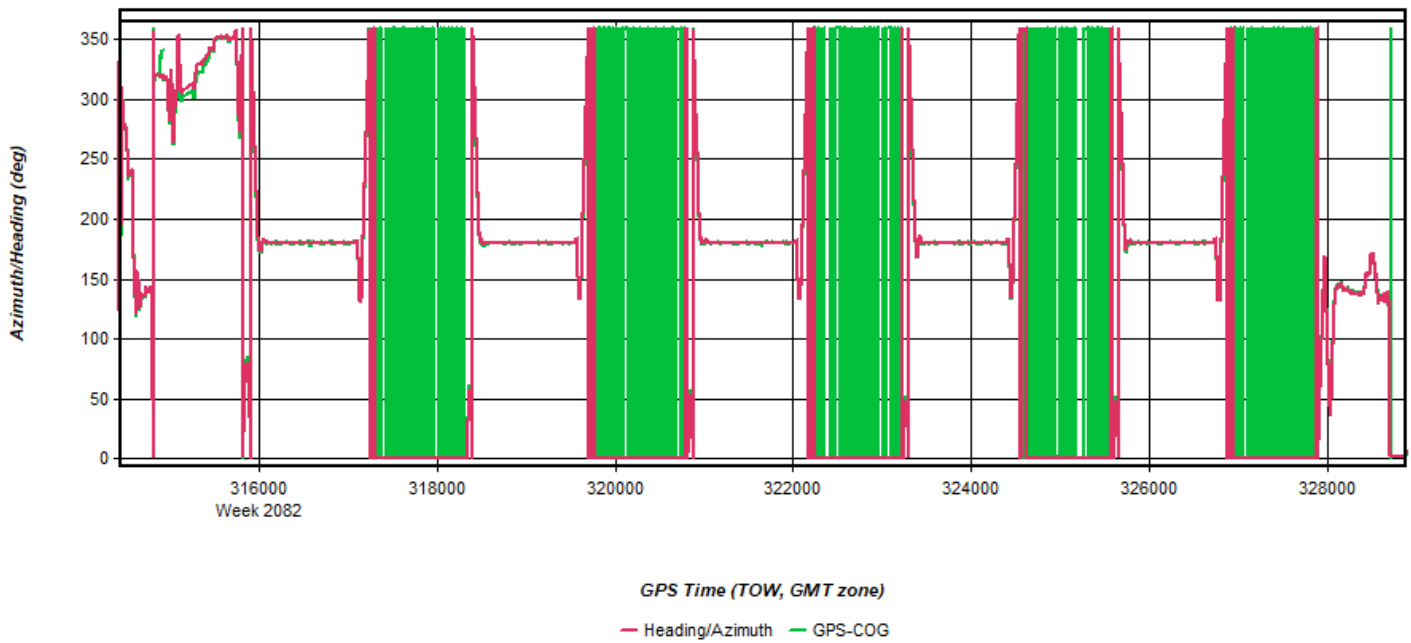


Figure 10: 20191204151927 [Smoothed TC Combined] - Estimated Attitude Accuracy Plot



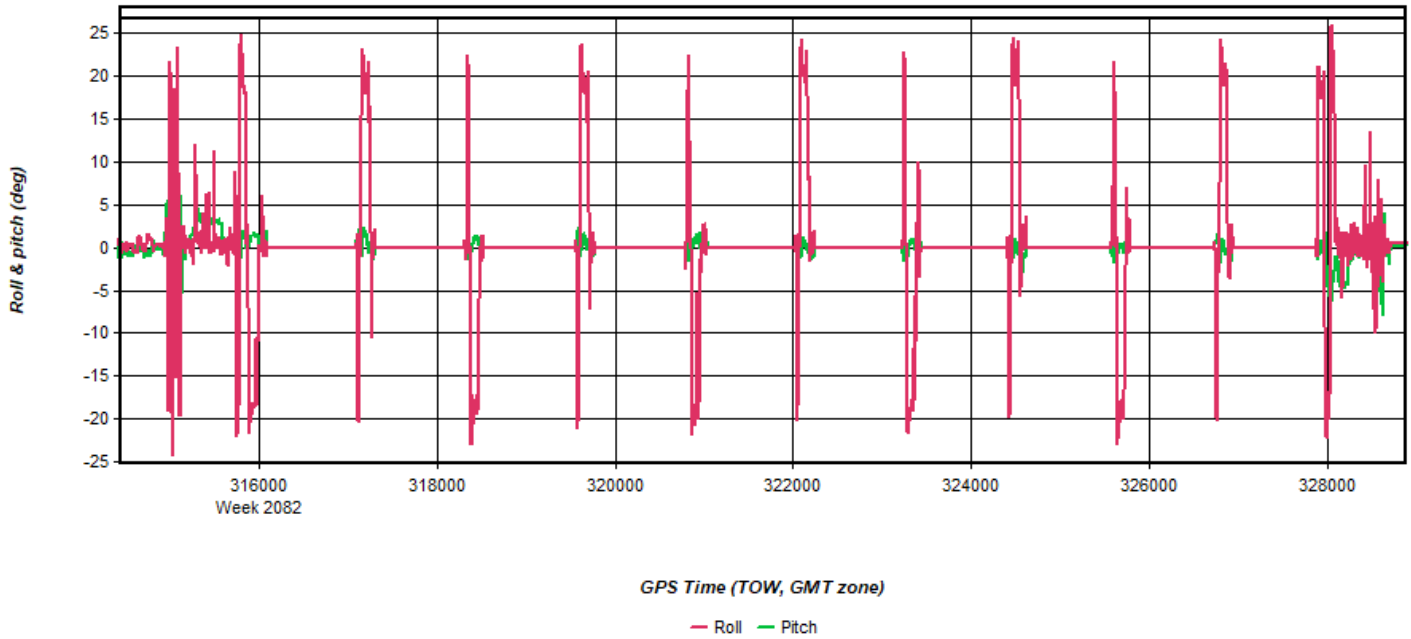
Process	20191204151927	by Unknown	on 12/13/2019	at 18:12:06
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Figure 11: 20191204151927 [Smoothed TC Combined] - Azimuth Plot



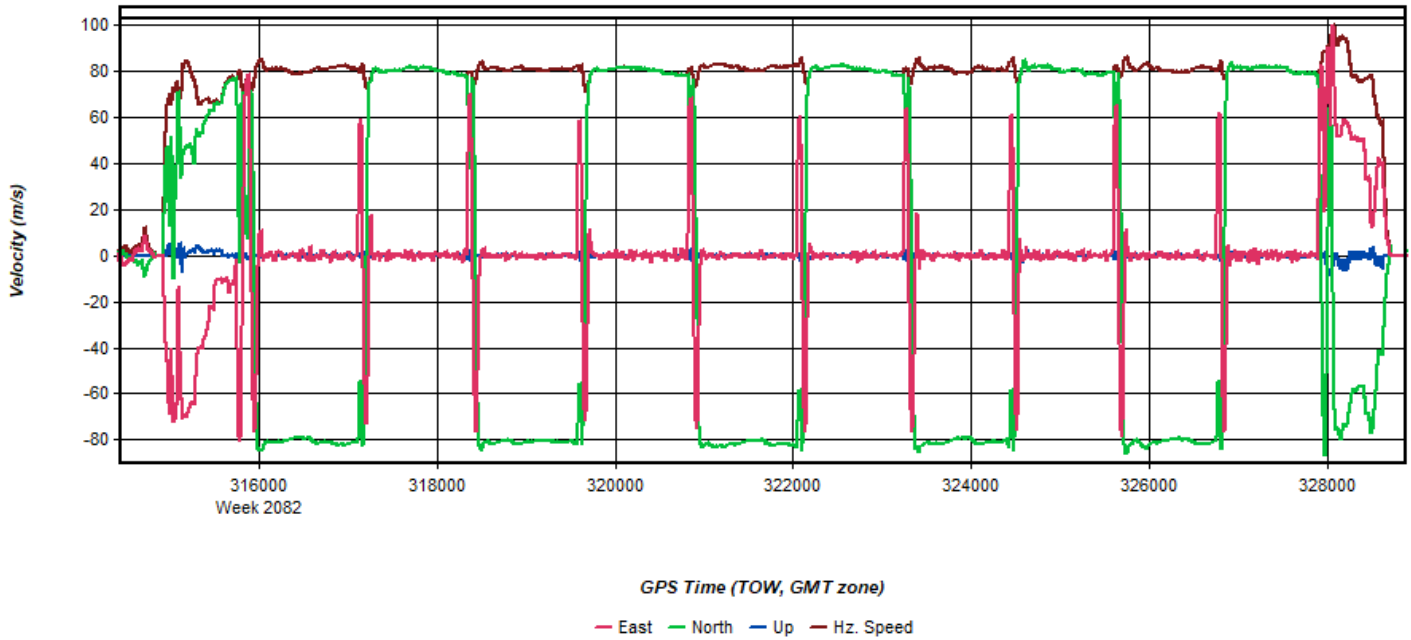
Process	20191204151927	by Unknown	on 12/13/2019	at 18:12:06
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Figure 12: 20191204151927 [Smoothed TC Combined] - Roll & Pitch Plot



Process	20191204151927	by Unknown	on 12/13/2019	at 18:12:06
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Figure 13: 20191204151927 [Smoothed TC Combined] - Velocity Profile Plot



Process	20191204151927	by Unknown	on 12/13/2019	at 18:12:06
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Figure 14: 20191204151927 [Smoothed TC Combined] - Body Frame Velocity Plot

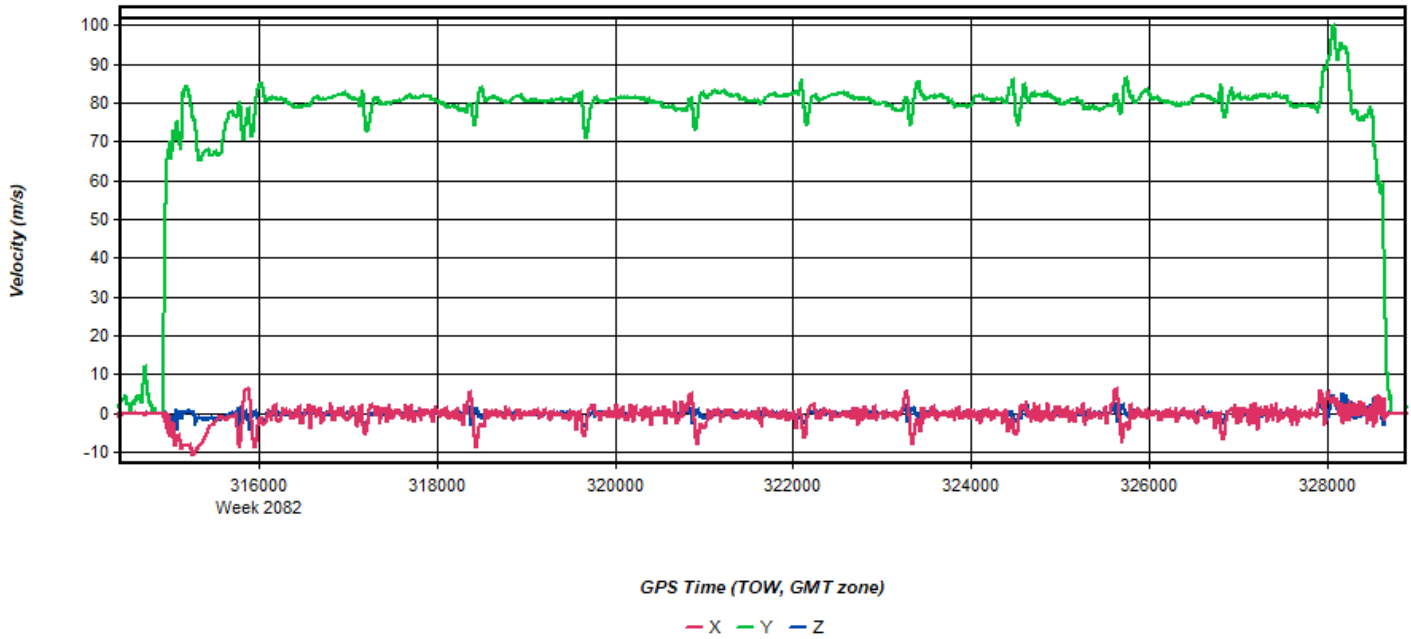


Figure 15: 20191204151927 [Smoothed TC Combined] - Height Profile Plot

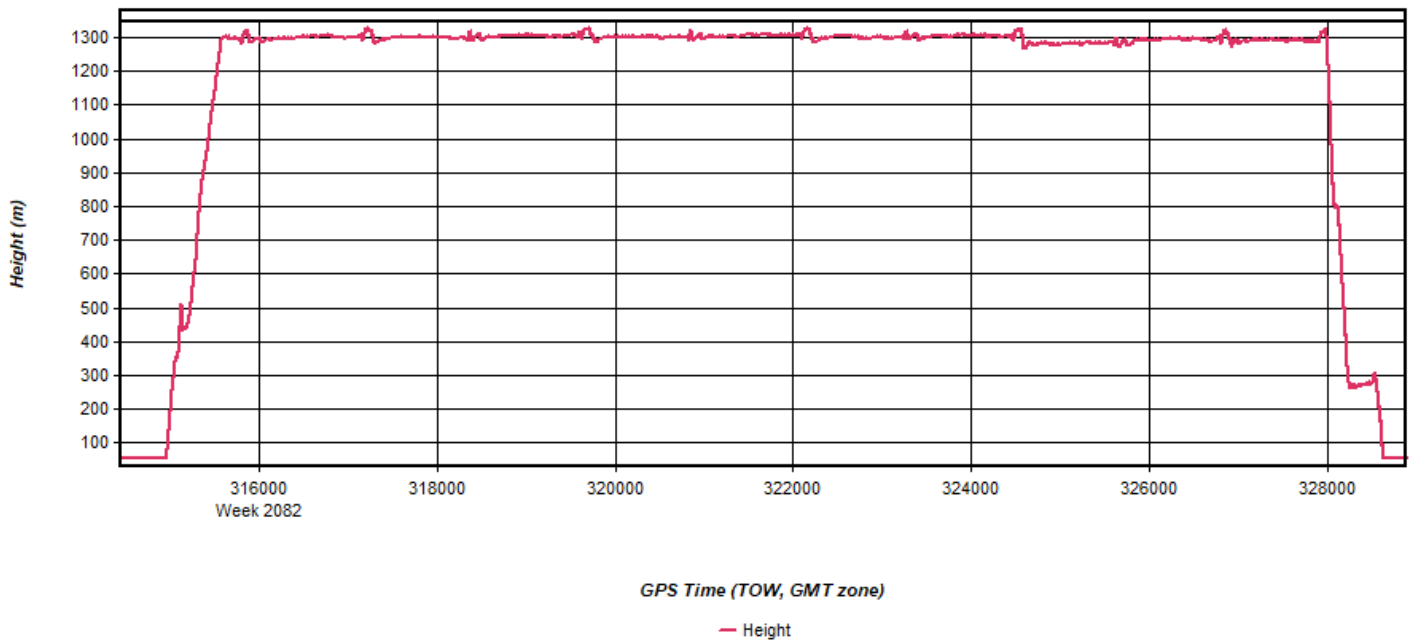
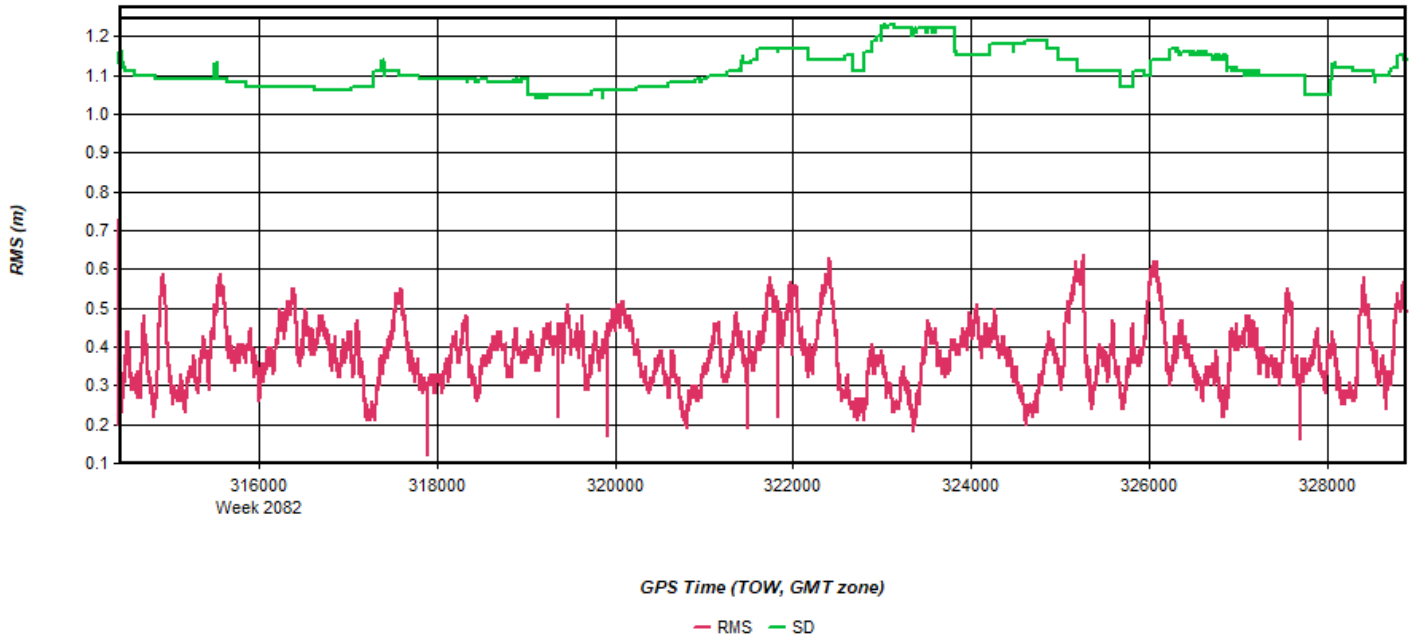
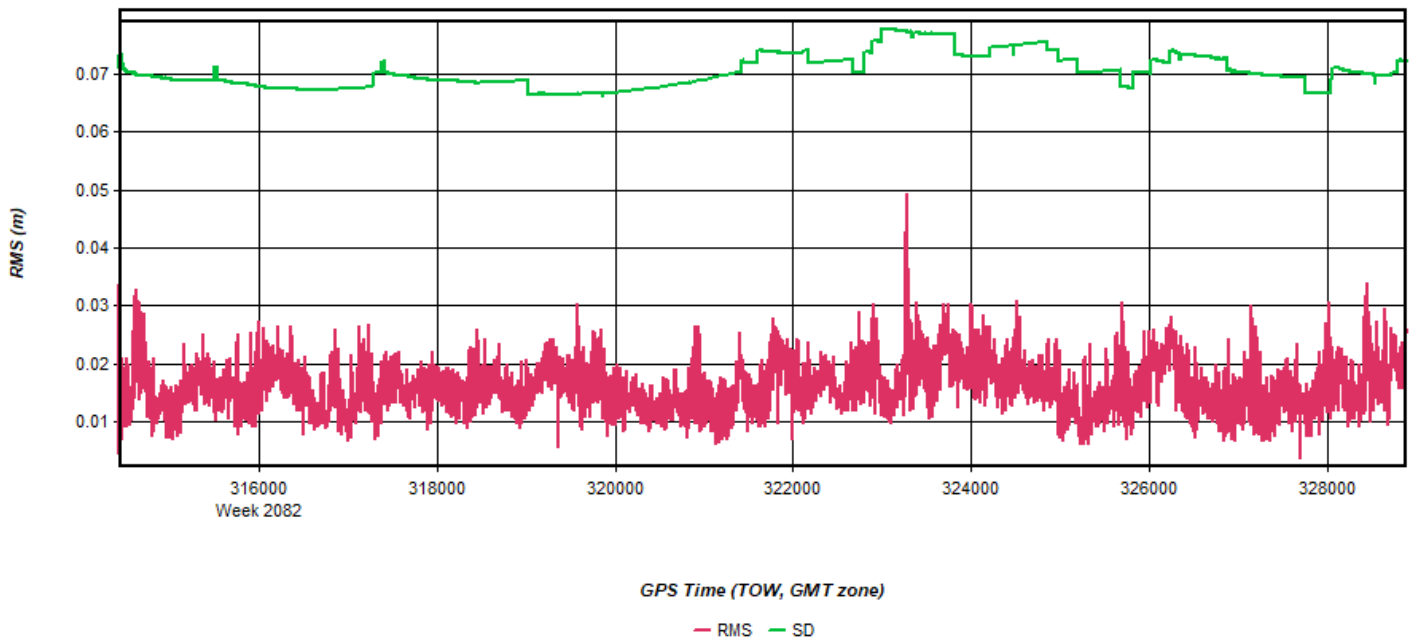


Figure 16: 20191204151927 [Smoothed TC Combined] - C/A Code Residual RMS Plot



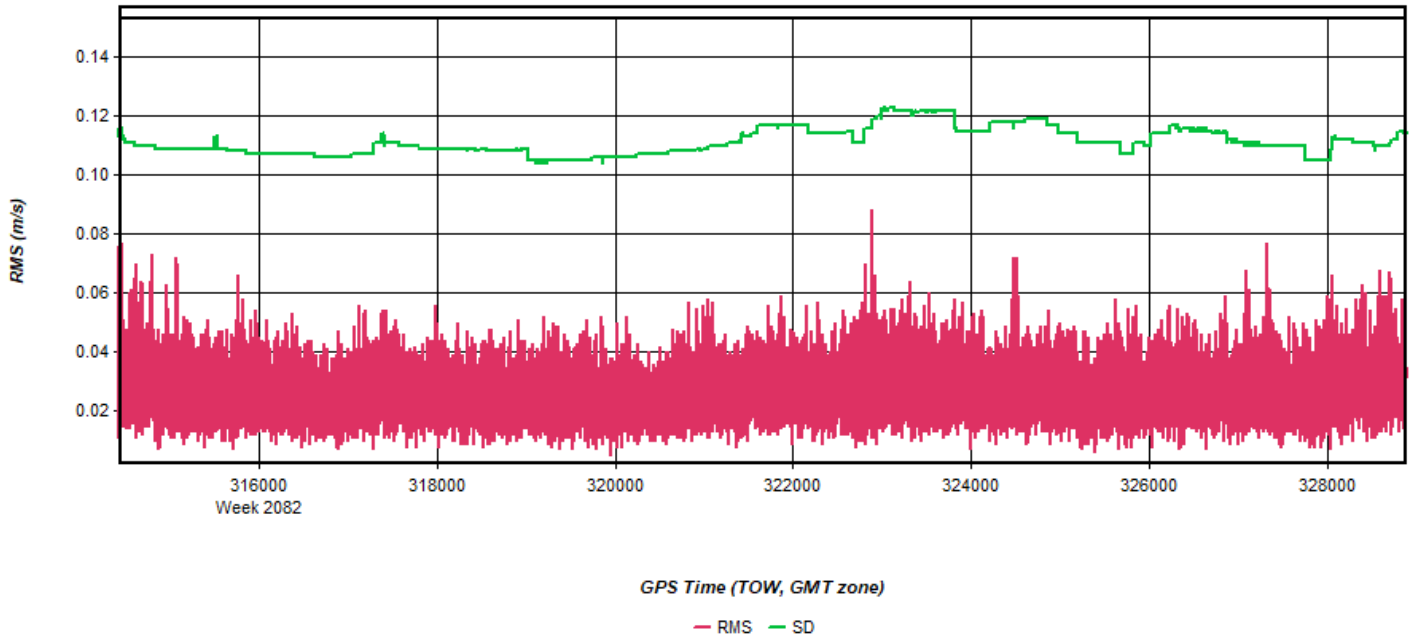
Process	20191204151927	by Unknown	on 12/13/2019	at 18:12:06
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Figure 17: 20191204151927 [Smoothed TC Combined] - Carrier Residual RMS Plot



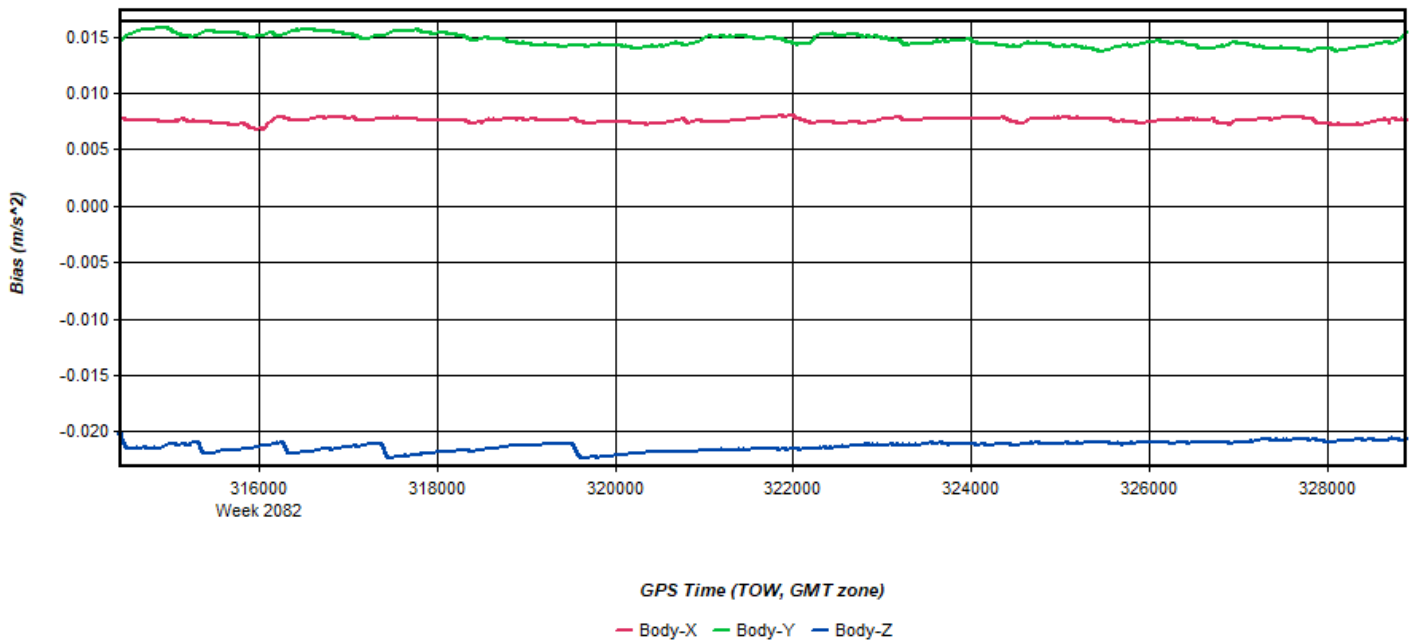
Process	20191204151927	by Unknown	on 12/13/2019	at 18:12:06
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Figure 18: 20191204151927 [Smoothed TC Combined] - L1 Doppler Residual RMS Plot



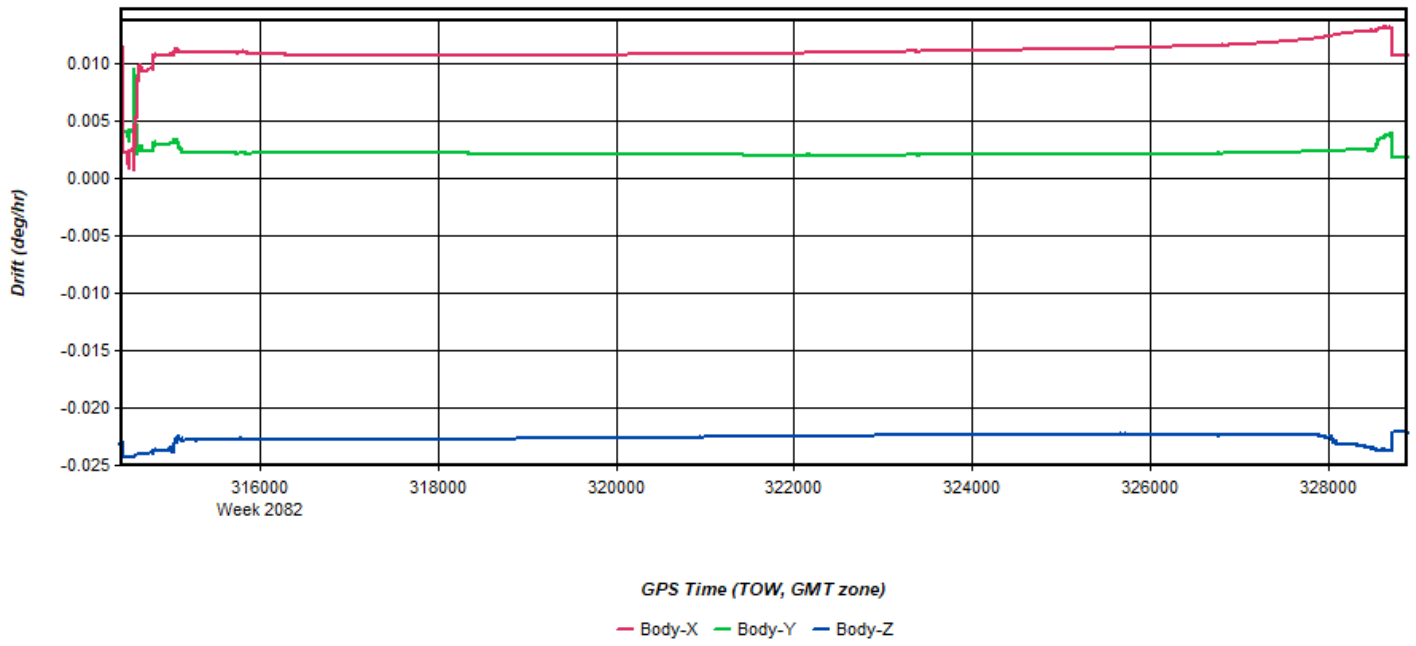
Process	20191204151927	by Unknown	on 12/13/2019	at 18:12:06
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Figure 19: 20191204151927 [Smoothed TC Combined] - Accelerometer Bias Plot



Process	20191204151927	by Unknown	on 12/13/2019	at 18:12:06
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Figure 20: 20191204151927 [Smoothed TC Combined] - Gyro Drift Plot

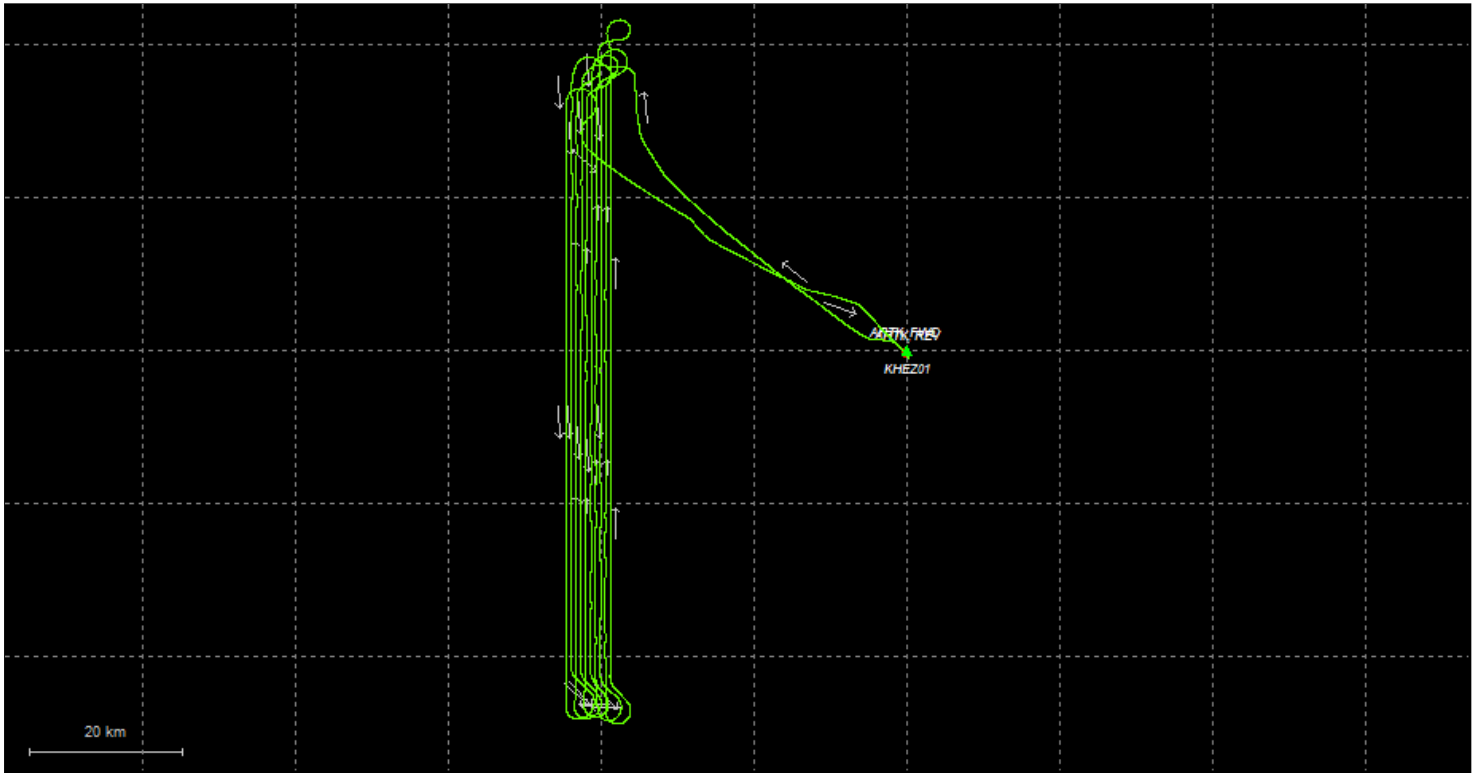


Process	20191204151927	by Unknown	on 12/13/2019	at 18:12:06
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Output Results for 20191204205851

Inertial Explorer Version 8.80.2305
12/14/2019

Figure 1: Smoothed TC Combined - Map



Process	20191204205851	by Unknown	on 12/13/2019	at 20:13:15
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Figure 2: 20191204205851 [Smoothed TC Combined] - Forward/Reverse or Combined Separation Plot

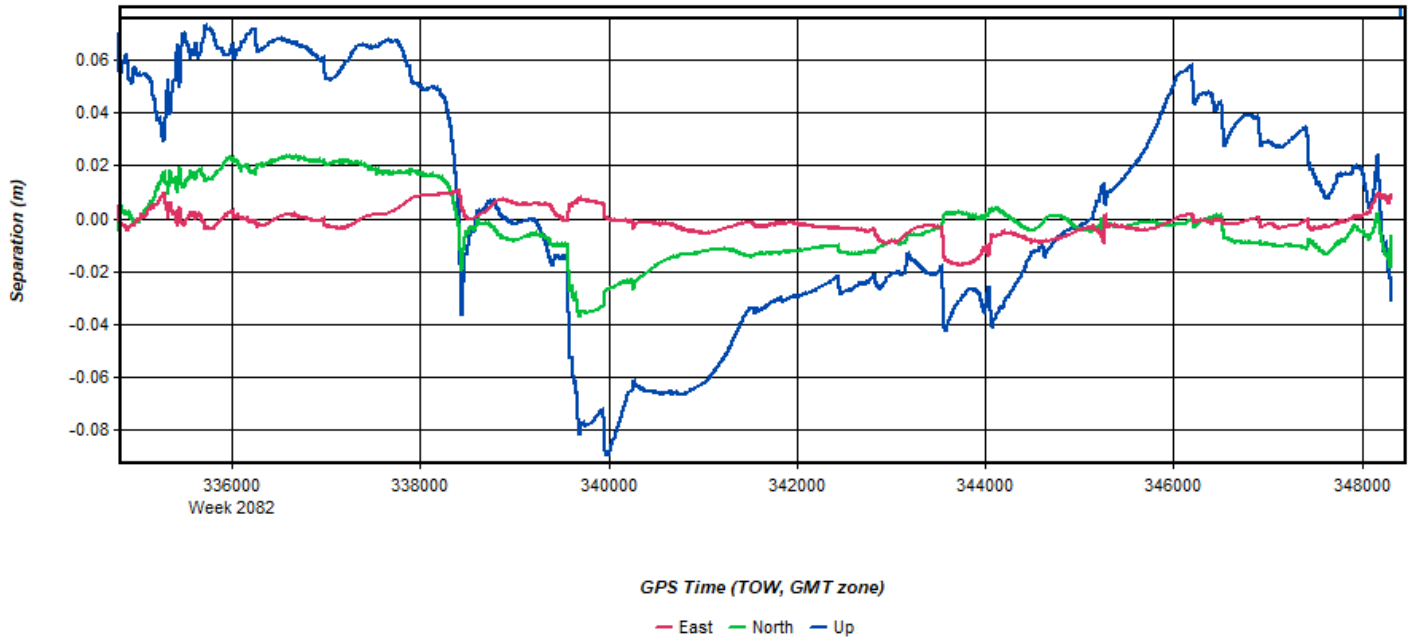


Figure 3: 20191204205851 [Smoothed TC Combined] - Float or Fixed Ambiguity

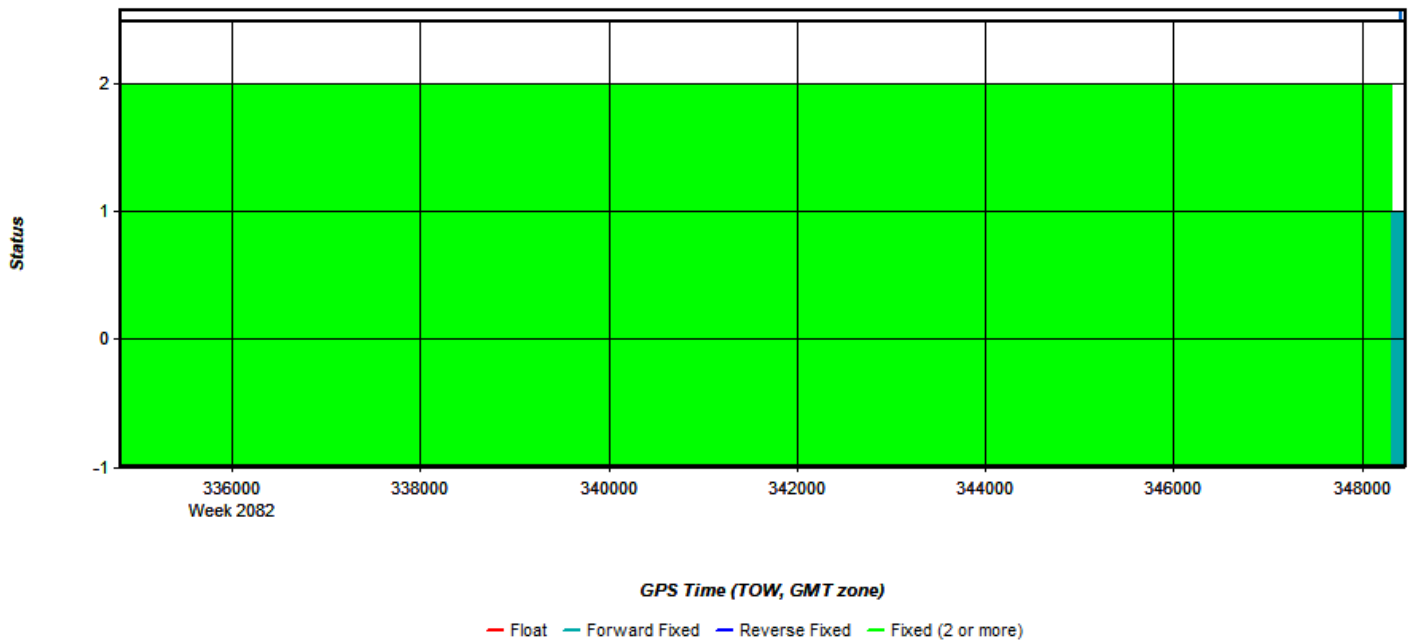


Figure 4: 20191204205851 [Smoothed TC Combined] - Forward/Reverse Separation Plot (Fixed)

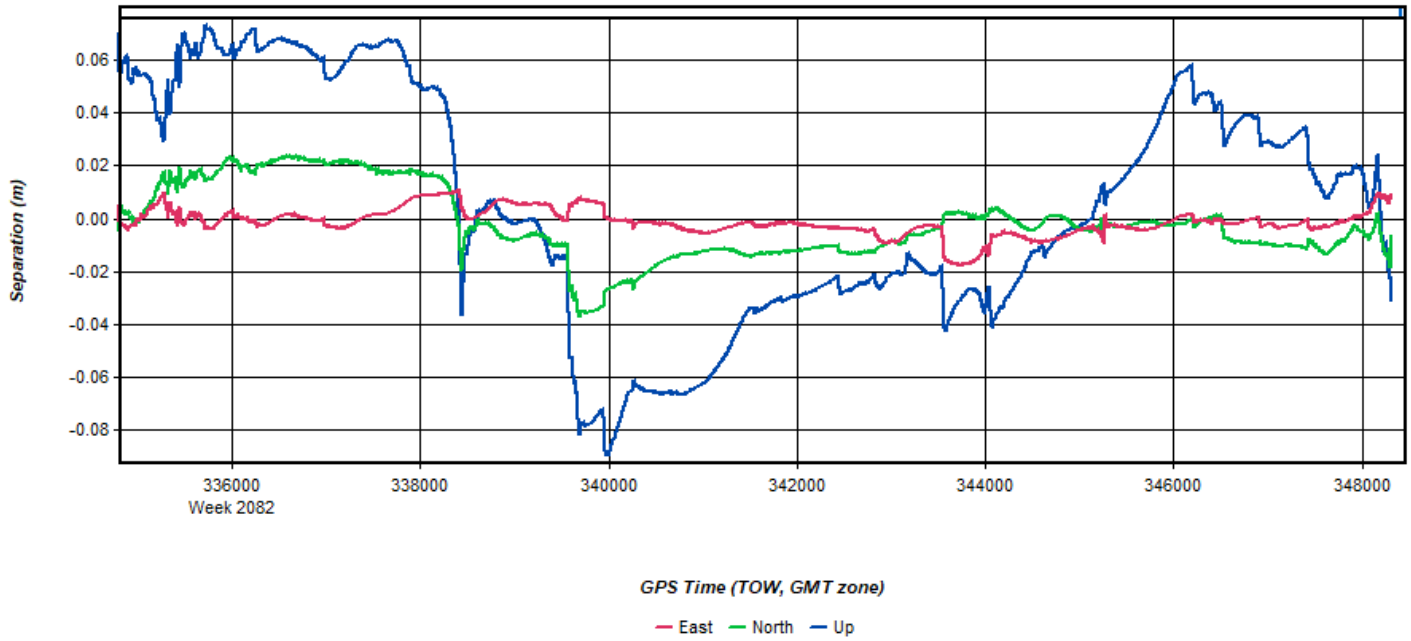


Figure 5: 20191204205851 [Smoothed TC Combined] - Estimated Position Accuracy Plot

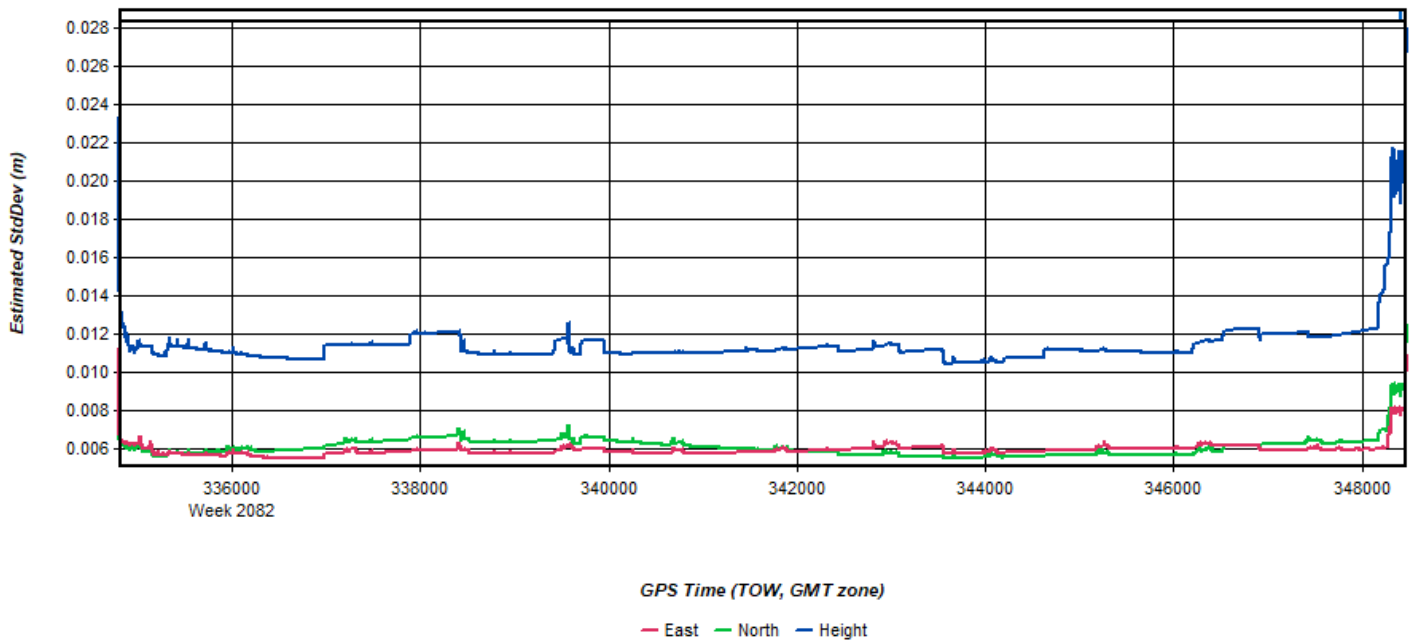
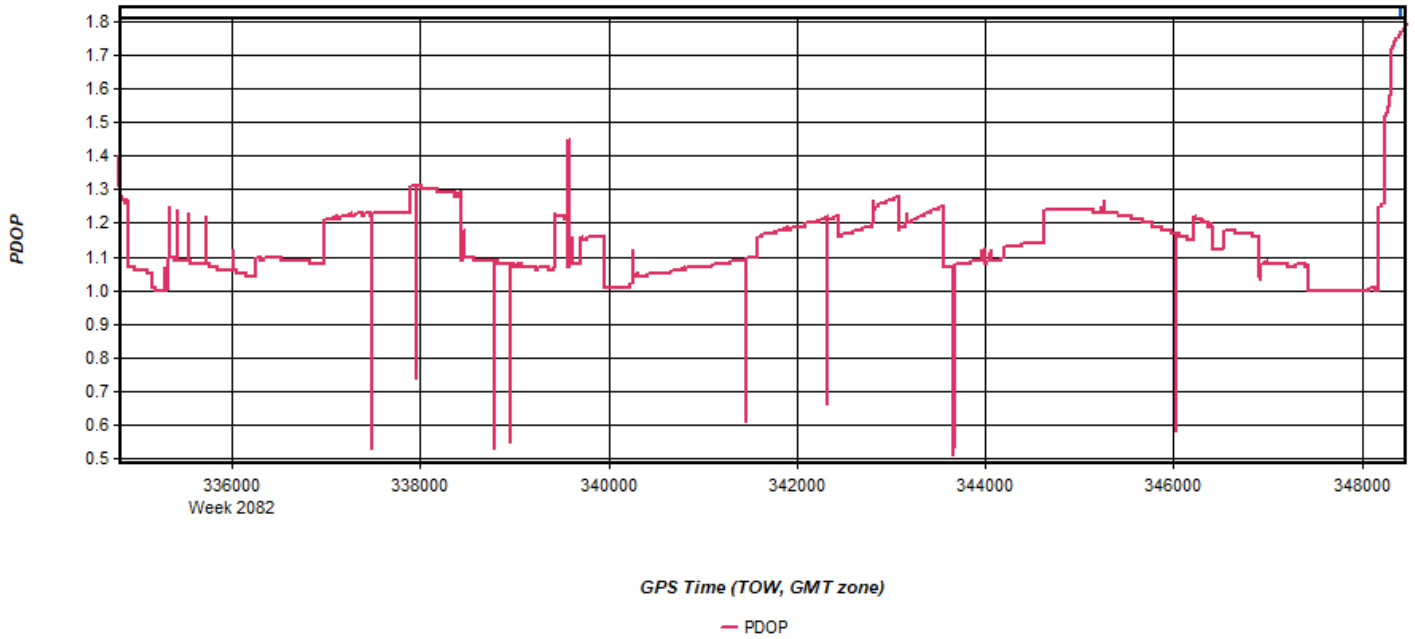
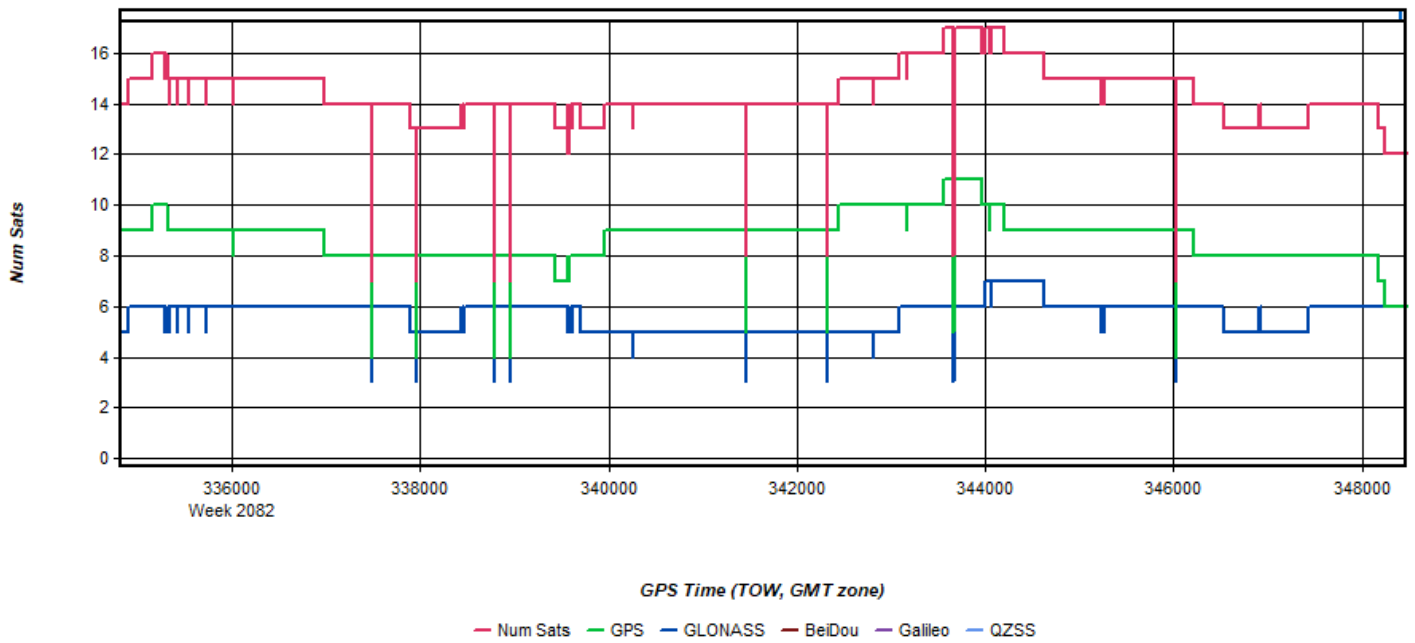


Figure 6: 20191204205851 [Smoothed TC Combined] - PDOP Plot



Process	20191204205851	by Unknown	on 12/13/2019	at 20:13:15
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Figure 7: 20191204205851 [Smoothed TC Combined] - Number of Satellites Line Plot



Process	20191204205851	by Unknown	on 12/13/2019	at 20:13:15
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Figure 8: 20191204205851 [Smoothed TC Combined] - Status flag for IMU processing

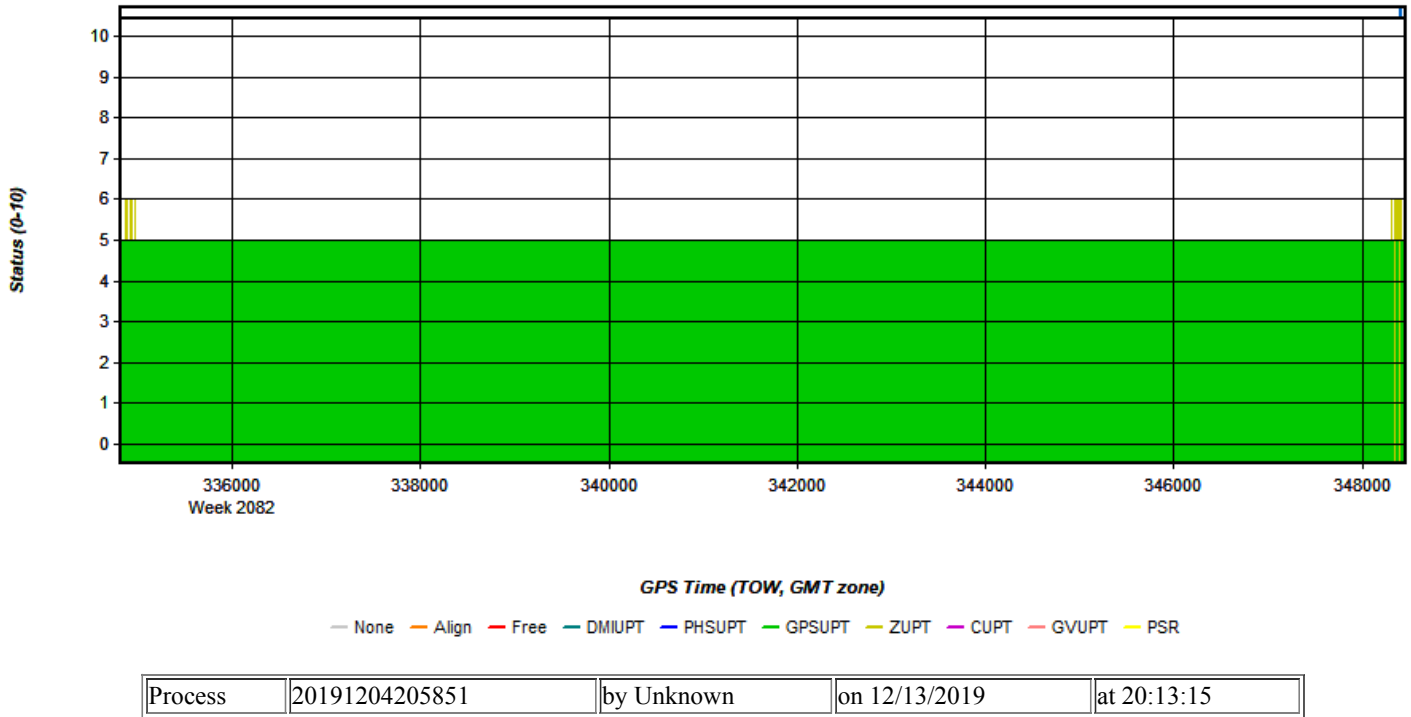


Figure 9: 20191204205851 [Smoothed TC Combined] - Fwd/Rev Attitude Separation Plot

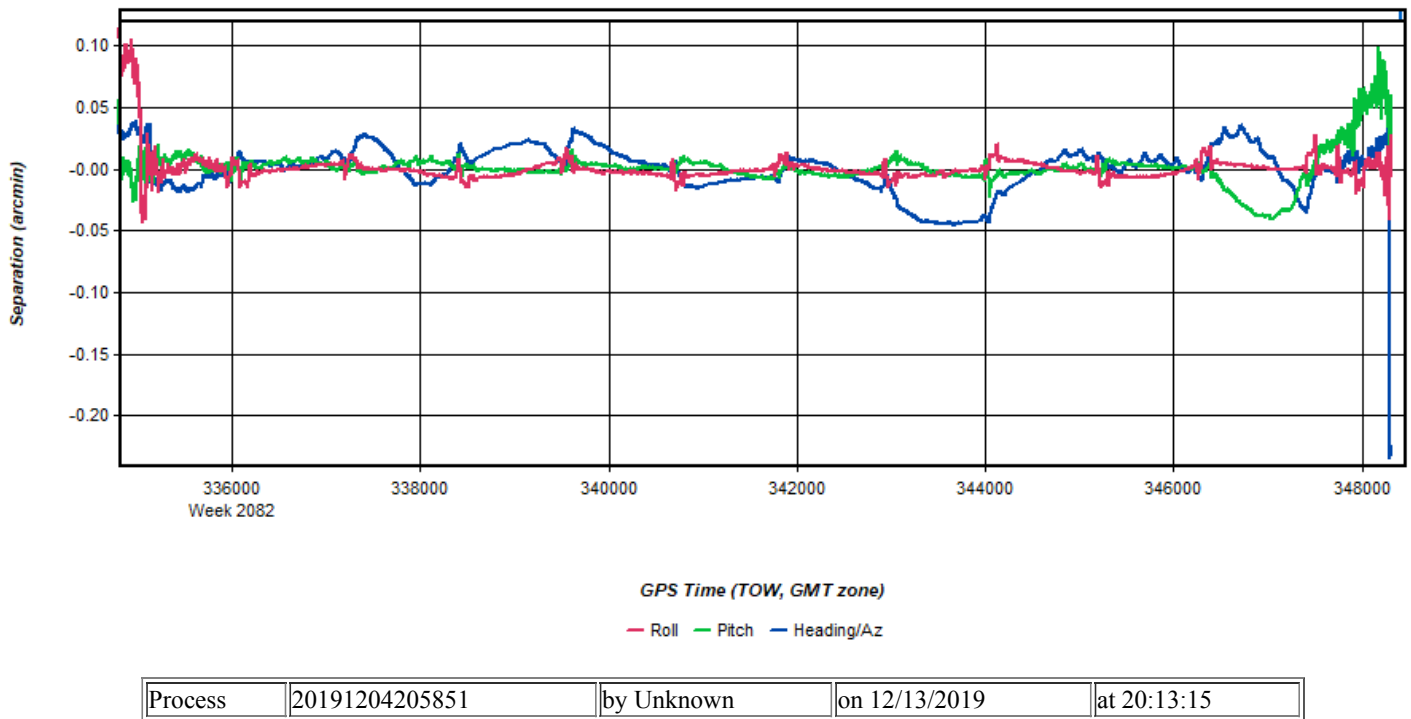
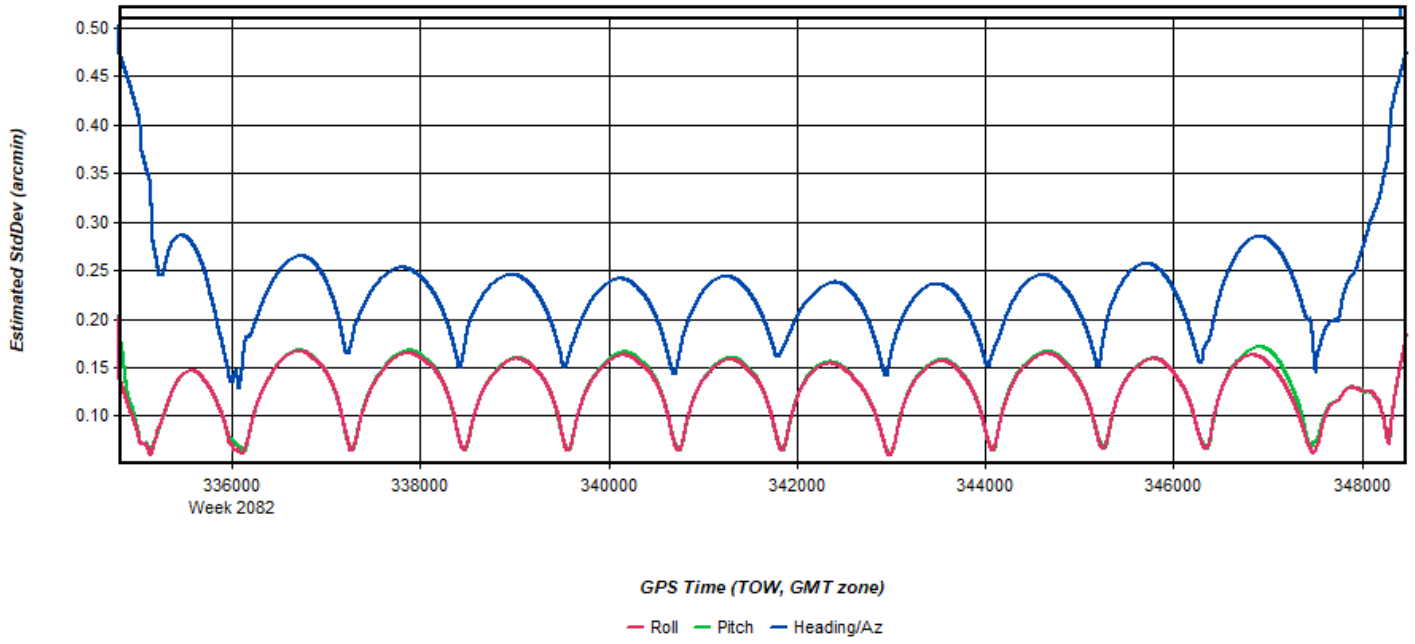
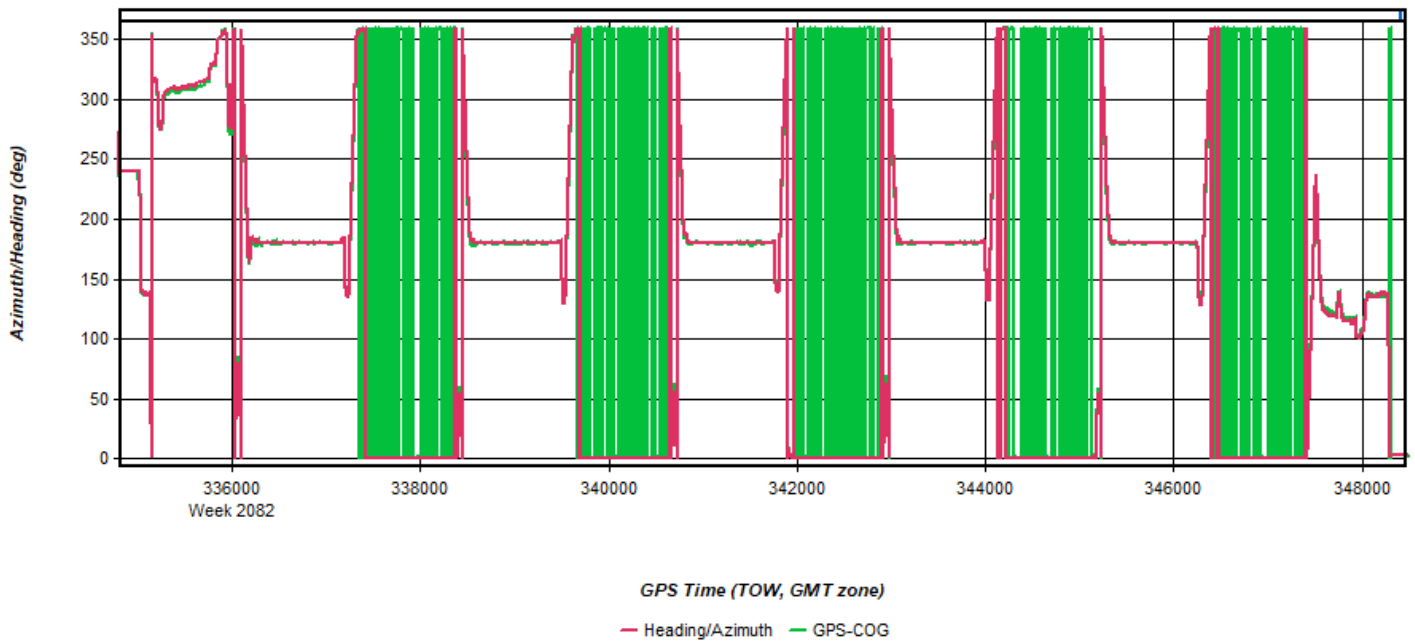


Figure 10: 20191204205851 [Smoothed TC Combined] - Estimated Attitude Accuracy Plot



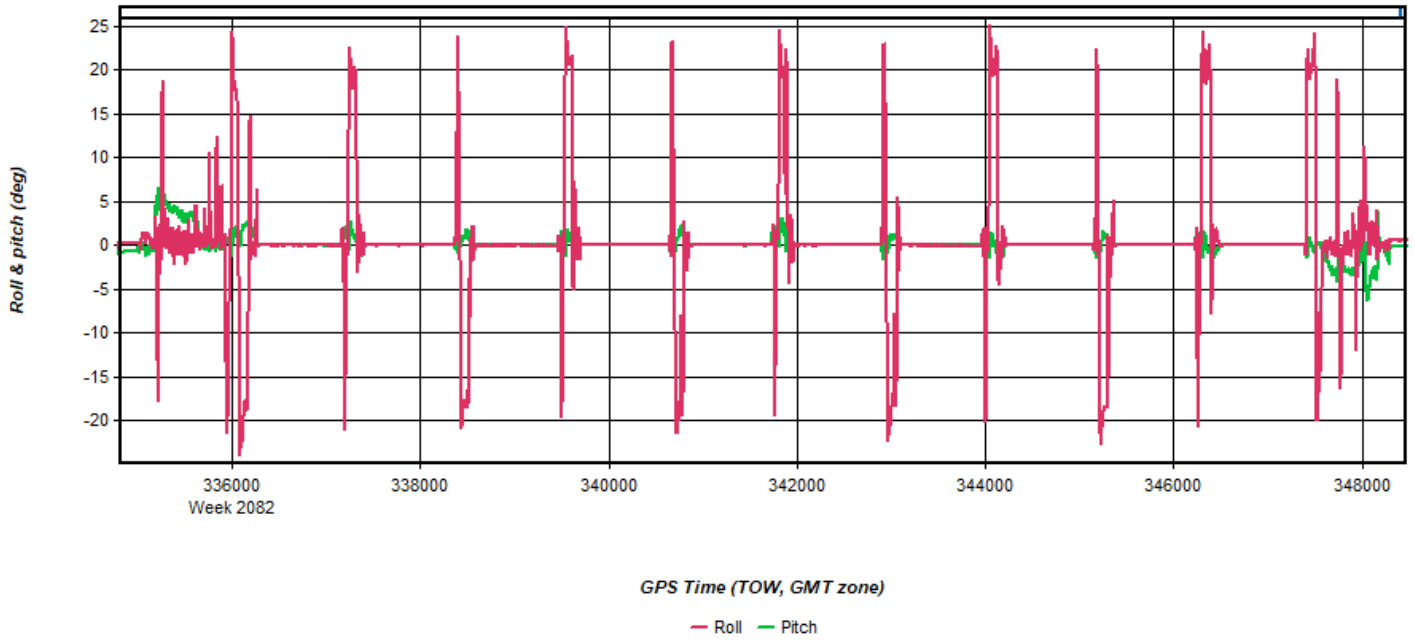
Process	20191204205851	by Unknown	on 12/13/2019	at 20:13:15
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Figure 11: 20191204205851 [Smoothed TC Combined] - Azimuth Plot



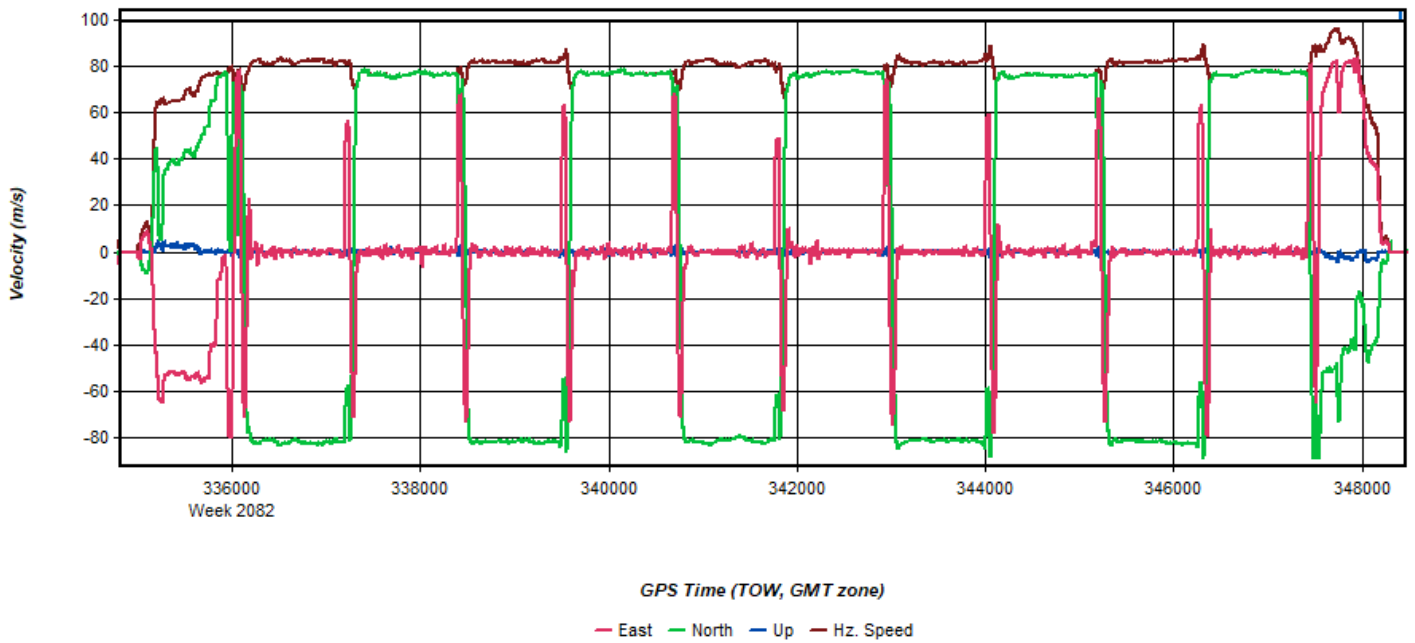
Process	20191204205851	by Unknown	on 12/13/2019	at 20:13:15
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Figure 12: 20191204205851 [Smoothed TC Combined] - Roll & Pitch Plot



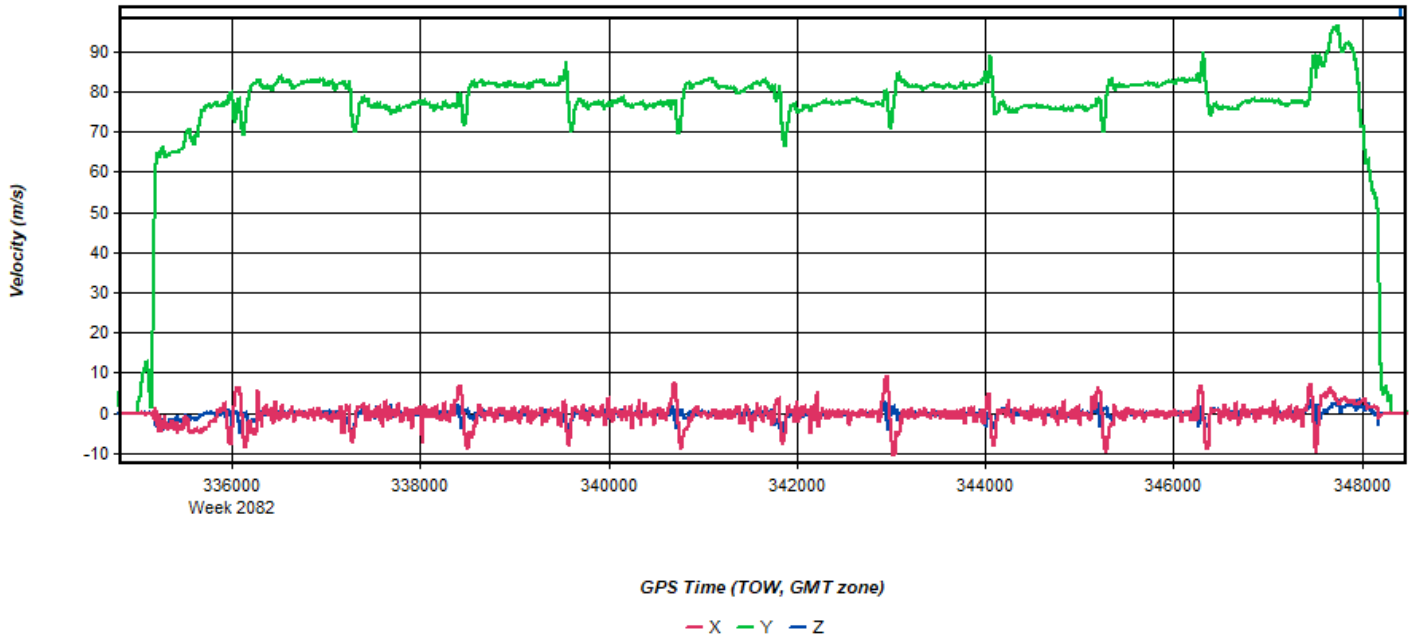
Process	20191204205851	by Unknown	on 12/13/2019	at 20:13:15
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Figure 13: 20191204205851 [Smoothed TC Combined] - Velocity Profile Plot



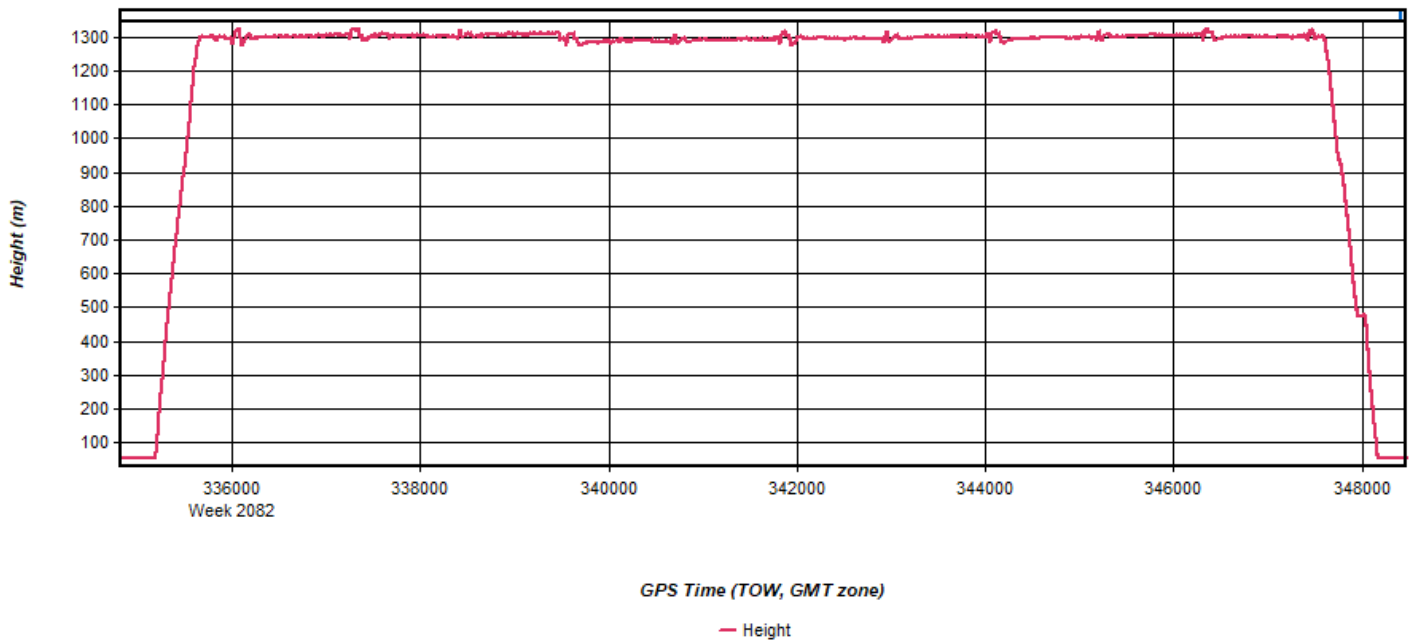
Process	20191204205851	by Unknown	on 12/13/2019	at 20:13:15
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Figure 14: 20191204205851 [Smoothed TC Combined] - Body Frame Velocity Plot



Process	20191204205851	by Unknown	on 12/13/2019	at 20:13:15
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Figure 15: 20191204205851 [Smoothed TC Combined] - Height Profile Plot



Process	20191204205851	by Unknown	on 12/13/2019	at 20:13:15
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Figure 16: 20191204205851 [Smoothed TC Combined] - C/A Code Residual RMS Plot

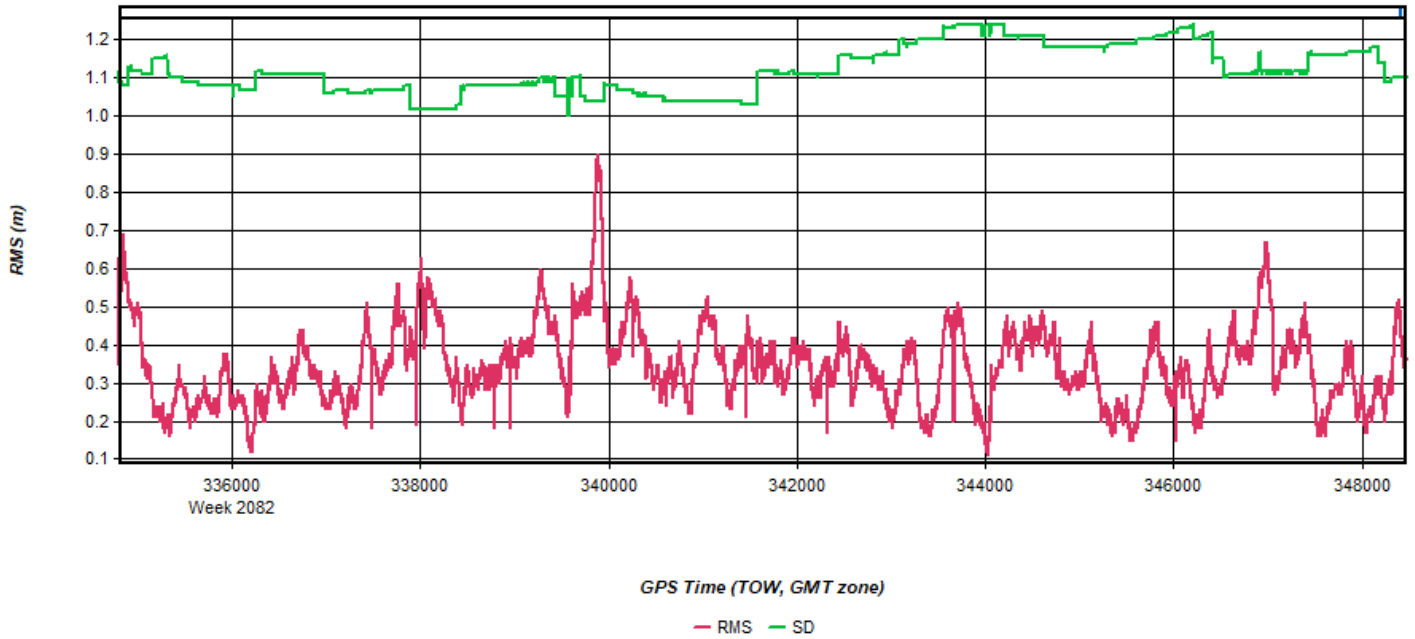


Figure 17: 20191204205851 [Smoothed TC Combined] - Carrier Residual RMS Plot

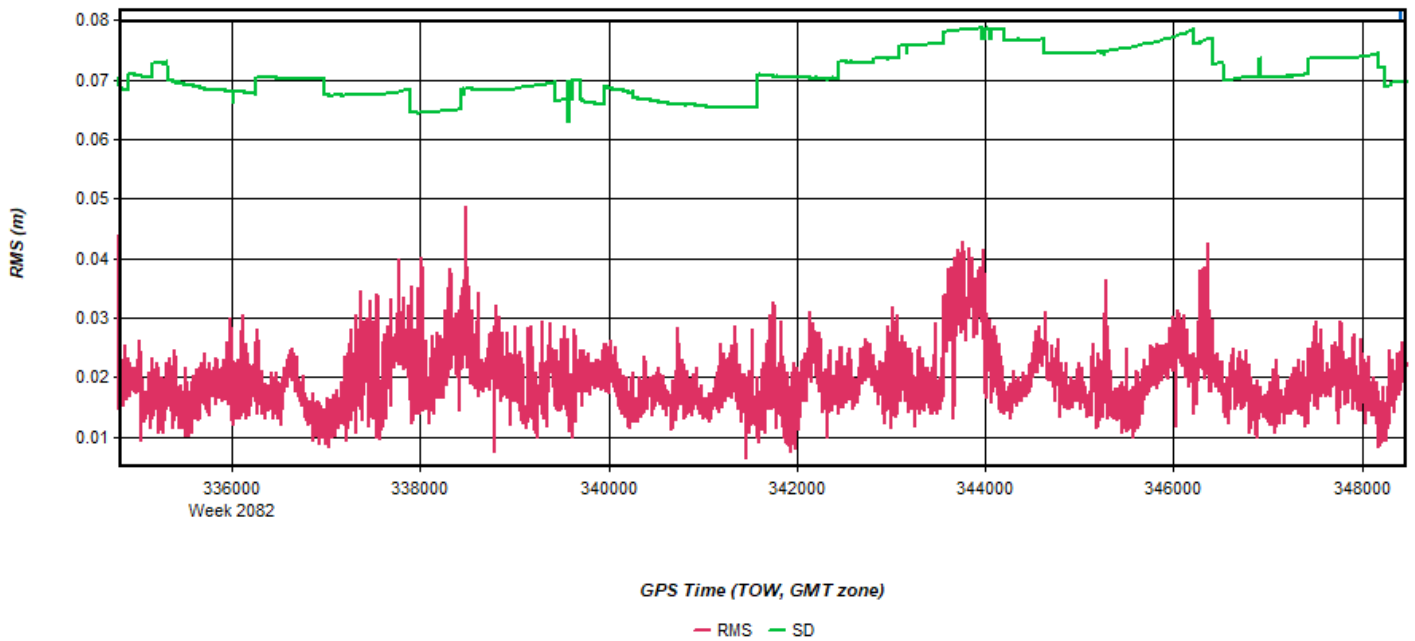
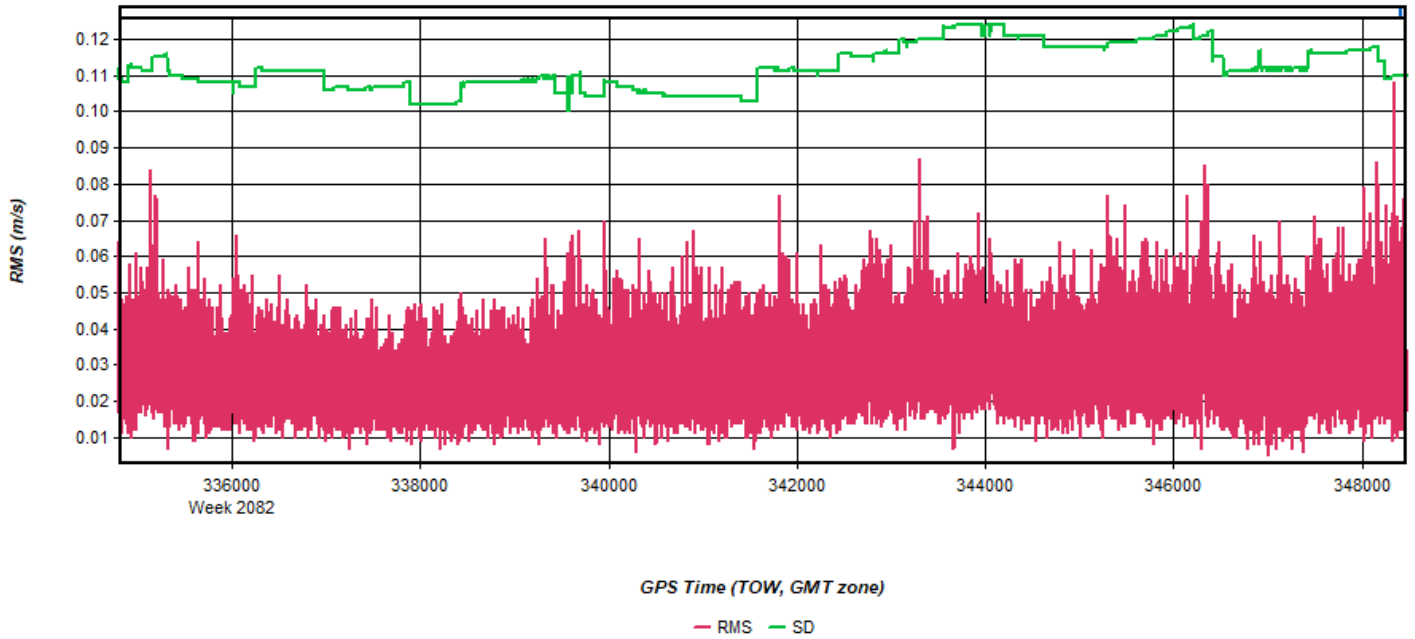
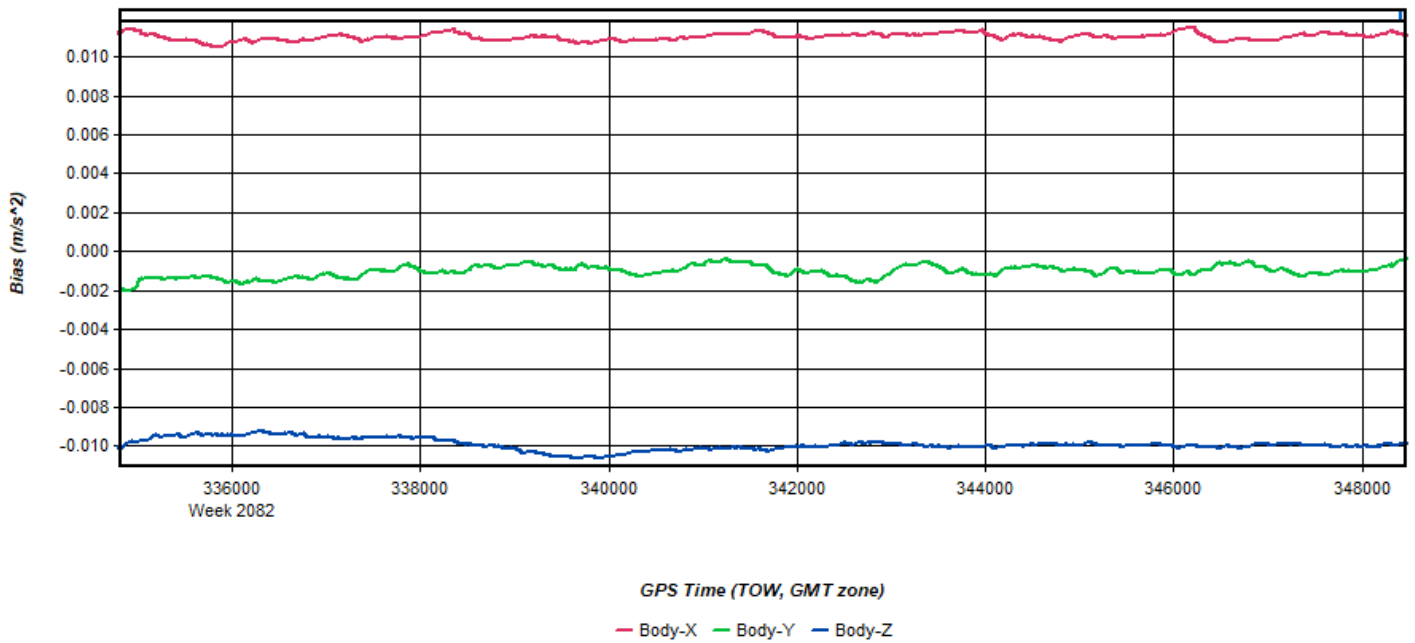


Figure 18: 20191204205851 [Smoothed TC Combined] - L1 Doppler Residual RMS Plot



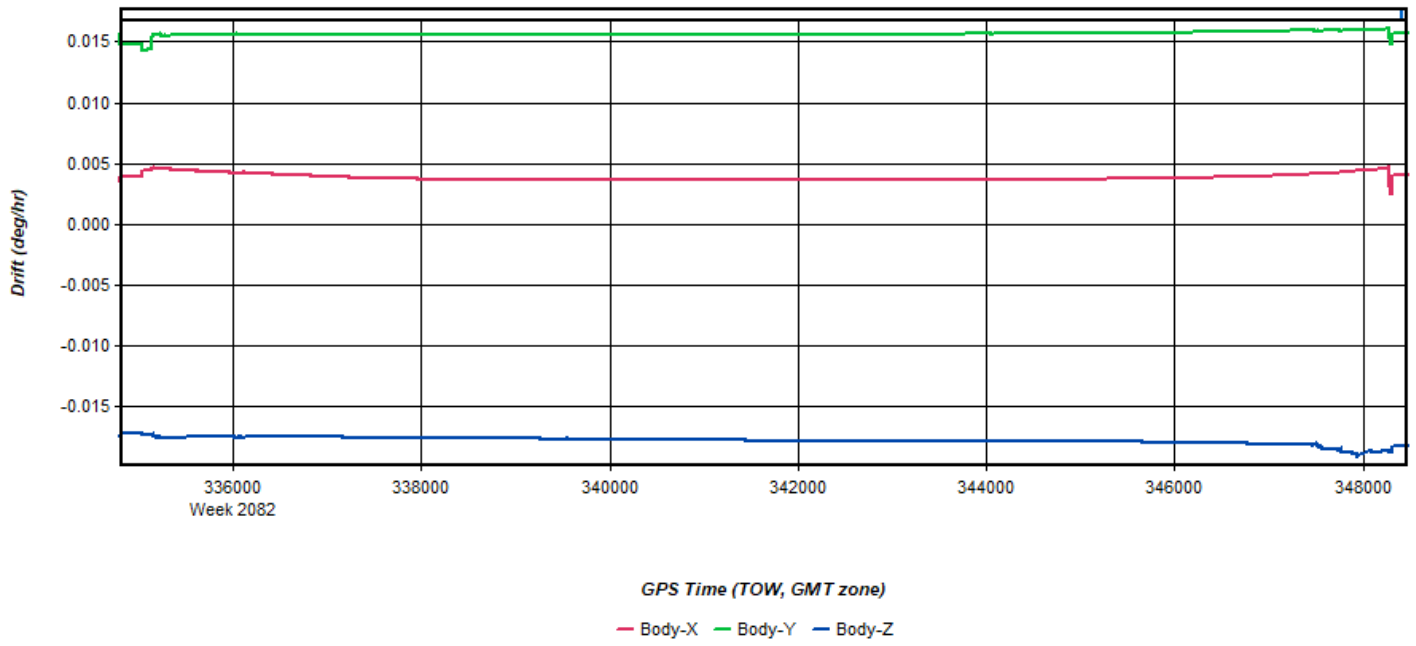
Process	20191204205851	by Unknown	on 12/13/2019	at 20:13:15
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Figure 19: 20191204205851 [Smoothed TC Combined] - Accelerometer Bias Plot



Process	20191204205851	by Unknown	on 12/13/2019	at 20:13:15
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Figure 20: 20191204205851 [Smoothed TC Combined] - Gyro Drift Plot

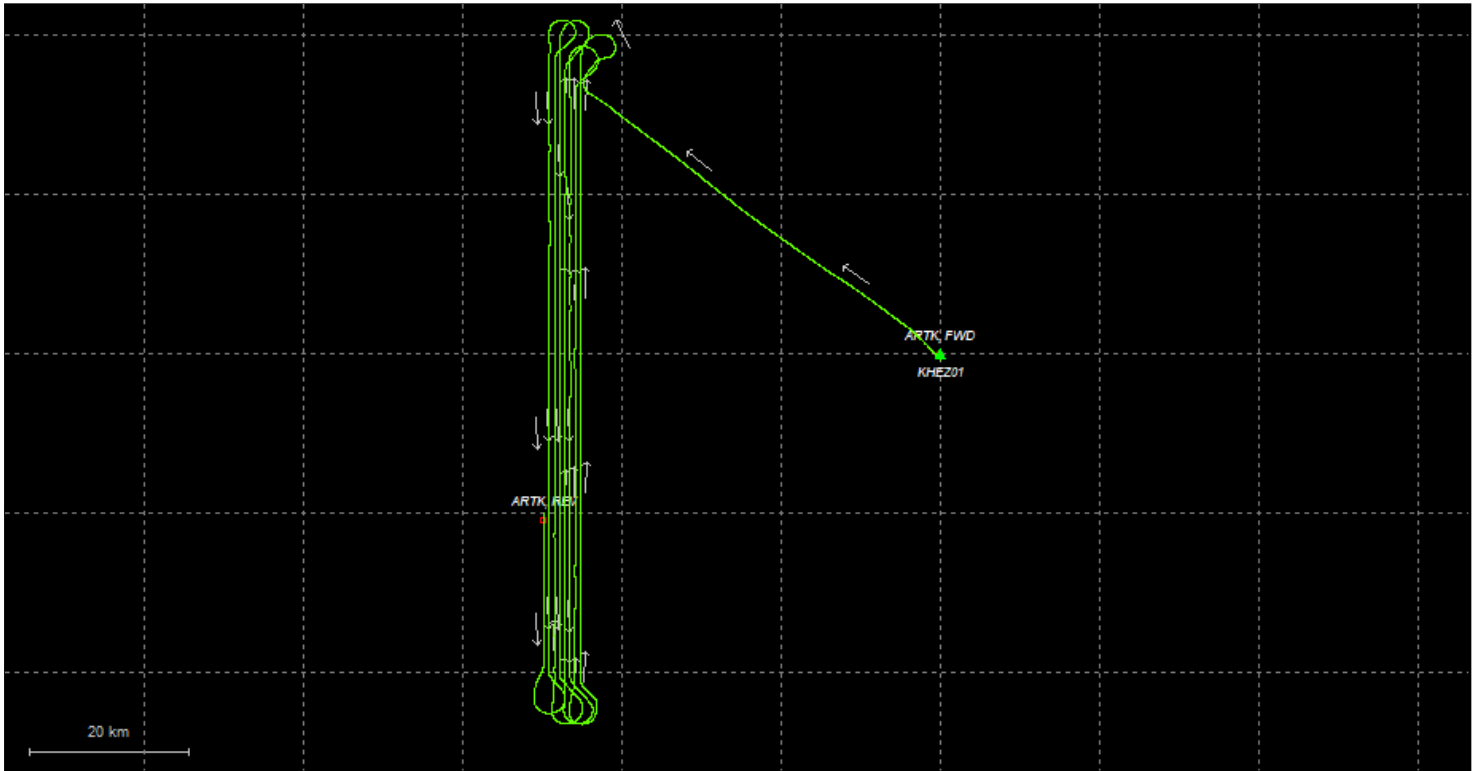


Process	20191204205851	by Unknown	on 12/13/2019	at 20:13:15
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Output Results for 20191211235253

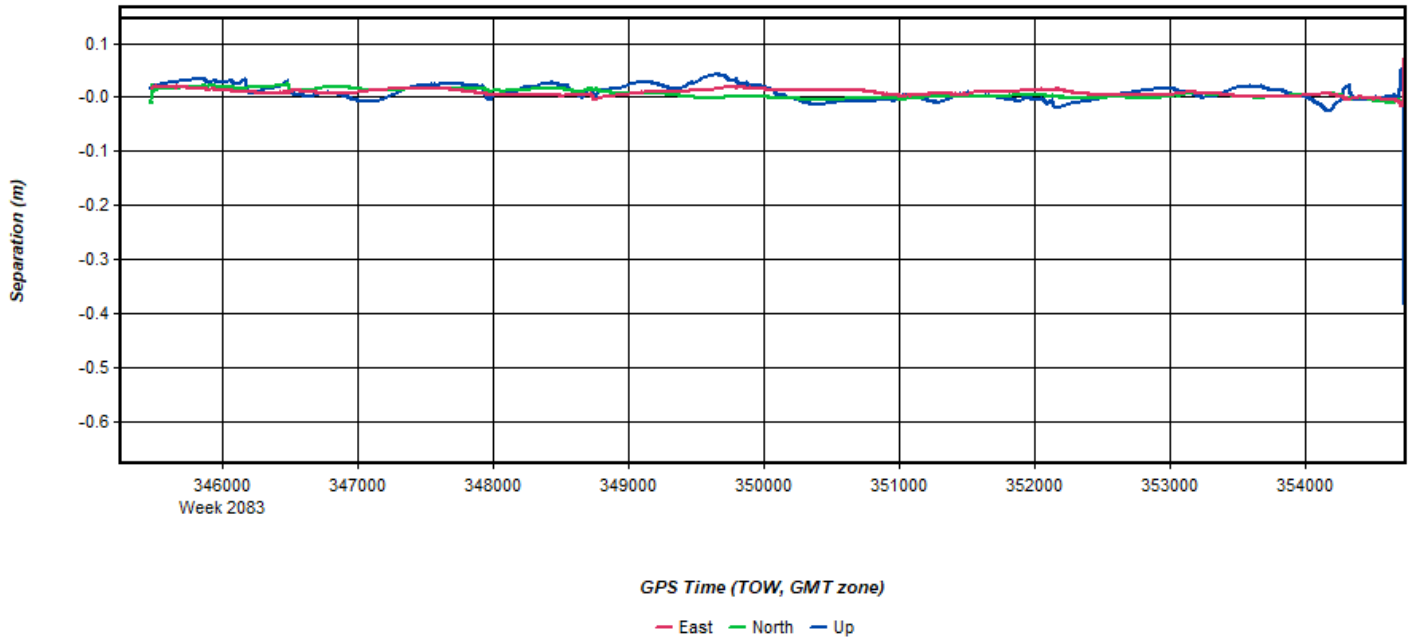
Inertial Explorer Version 8.80.2305
12/18/2019

Figure 1: Smoothed TC Combined - Map



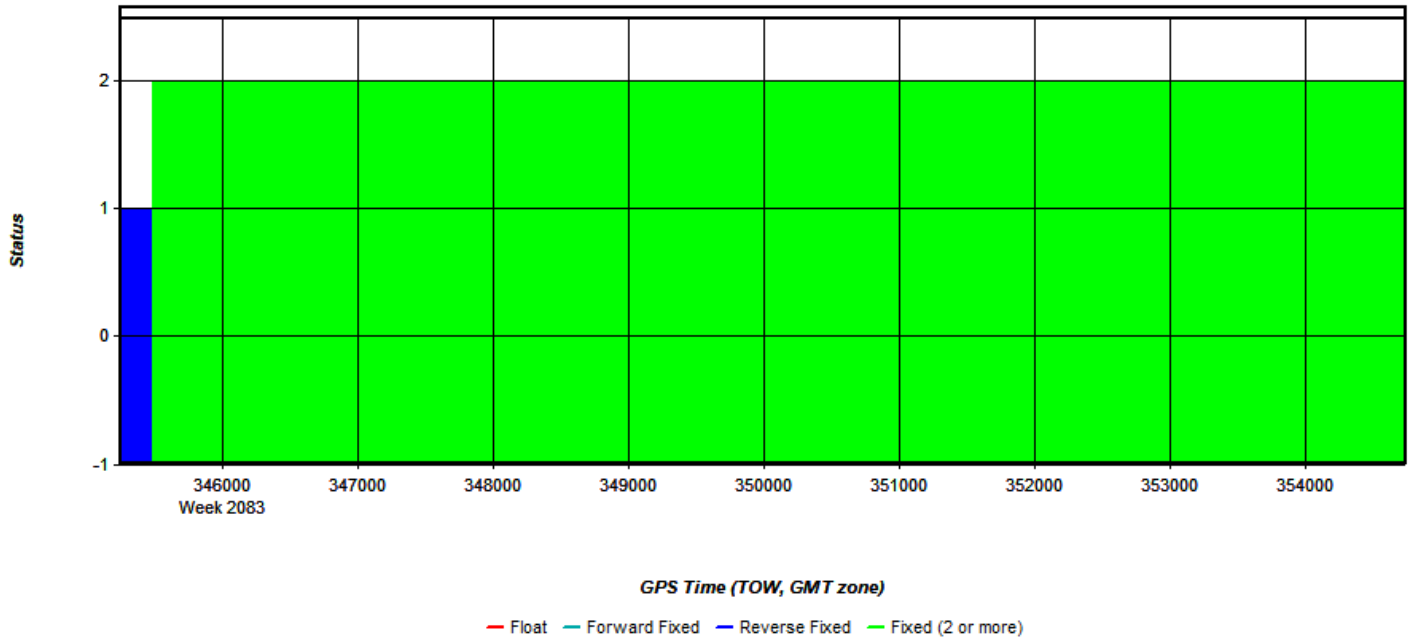
Process	20191211235253	by Unknown	on 12/18/2019	at 12:56:45
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Figure 2: 20191211235253 [Smoothed TC Combined] - Forward/Reverse or Combined Separation Plot



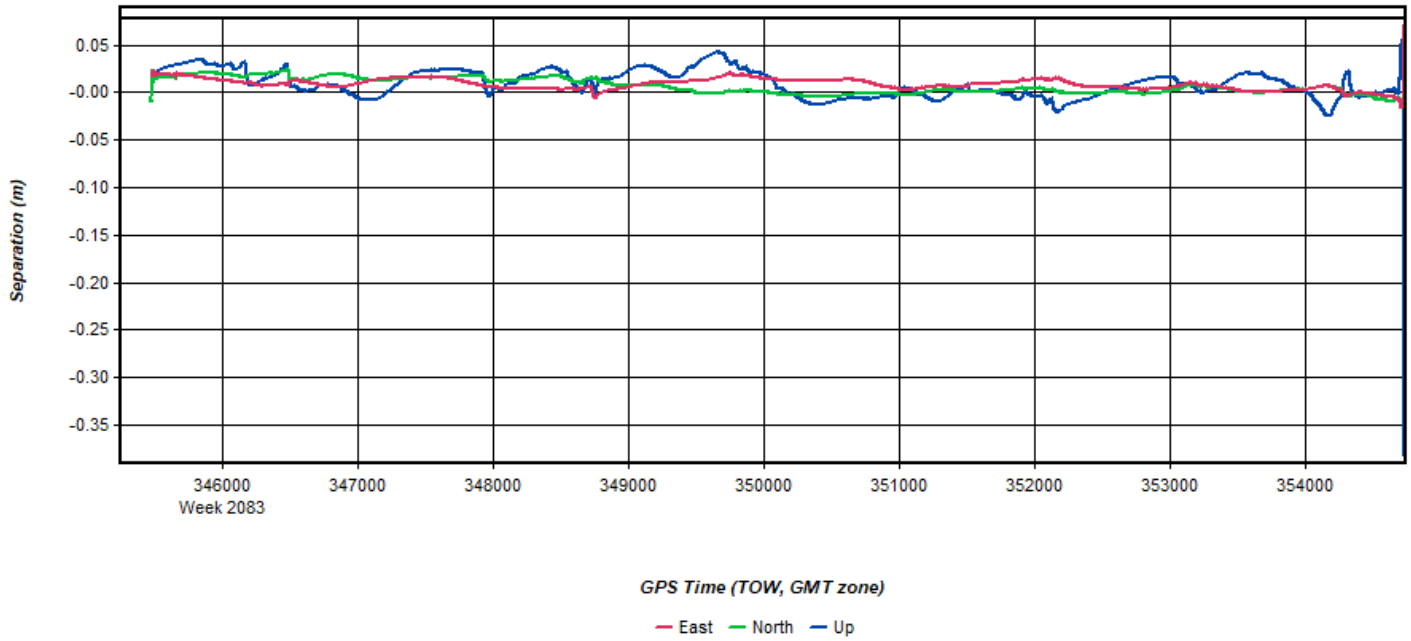
Process	20191211235253	by Unknown	on 12/18/2019	at 12:56:45
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Figure 3: 20191211235253 [Smoothed TC Combined] - Float or Fixed Ambiguity



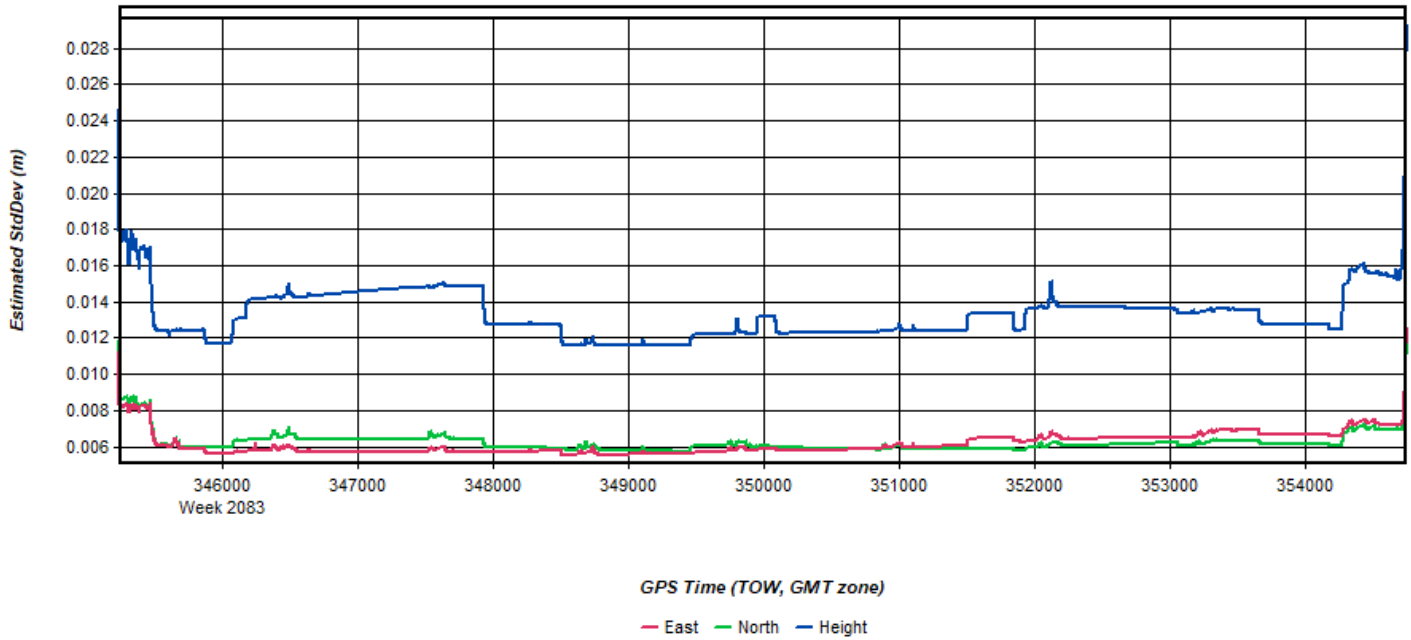
Process	20191211235253	by Unknown	on 12/18/2019	at 12:56:45
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Figure 4: 20191211235253 [Smoothed TC Combined] - Forward/Reverse Separation Plot (Fixed)



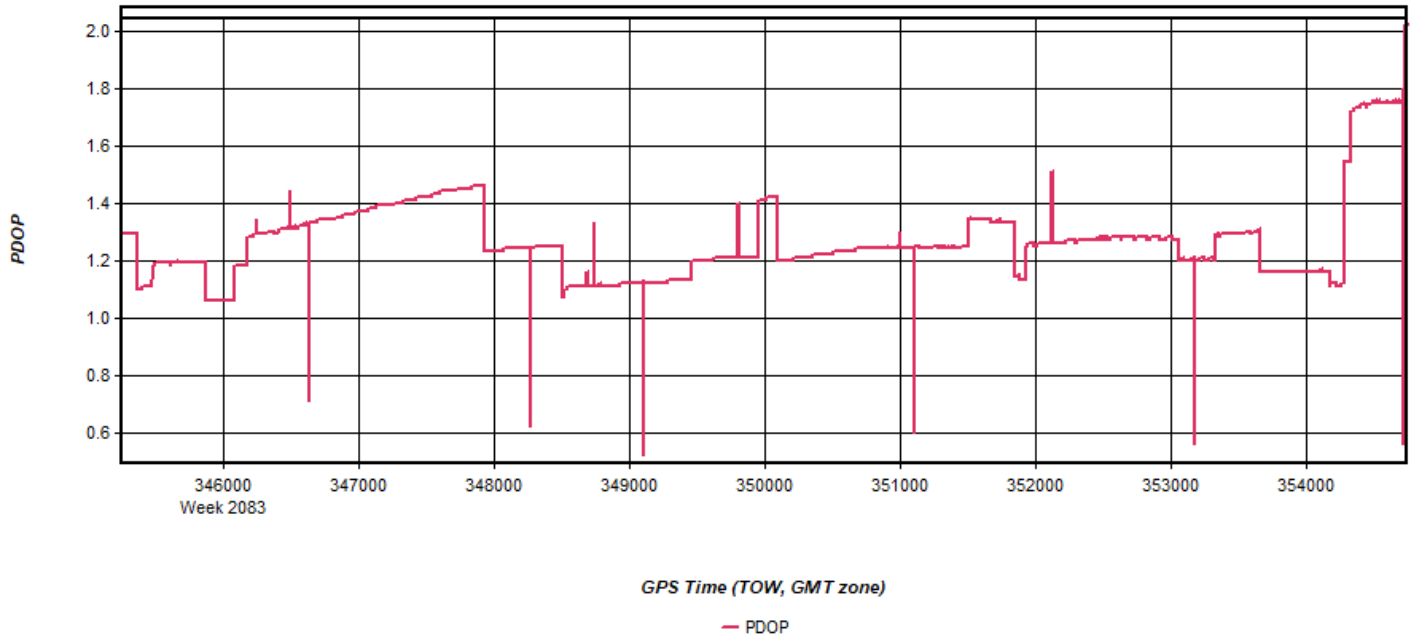
Process	20191211235253	by Unknown	on 12/18/2019	at 12:56:45
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Figure 5: 20191211235253 [Smoothed TC Combined] - Estimated Position Accuracy Plot



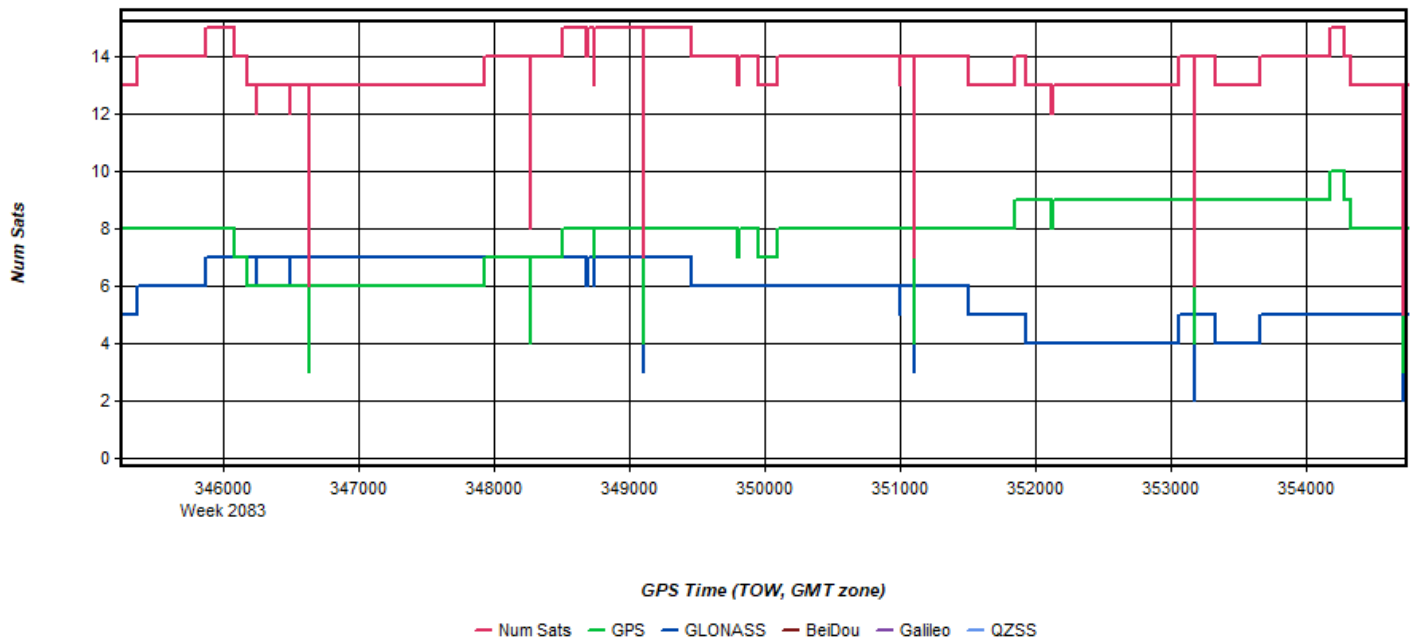
Process	20191211235253	by Unknown	on 12/18/2019	at 12:56:45
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Figure 6: 20191211235253 [Smoothed TC Combined] - PDOP Plot



Process	20191211235253	by Unknown	on 12/18/2019	at 12:56:45
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Figure 7: 20191211235253 [Smoothed TC Combined] - Number of Satellites Line Plot



Process	20191211235253	by Unknown	on 12/18/2019	at 12:56:45
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Figure 8: 20191211235253 [Smoothed TC Combined] - Status flag for IMU processing

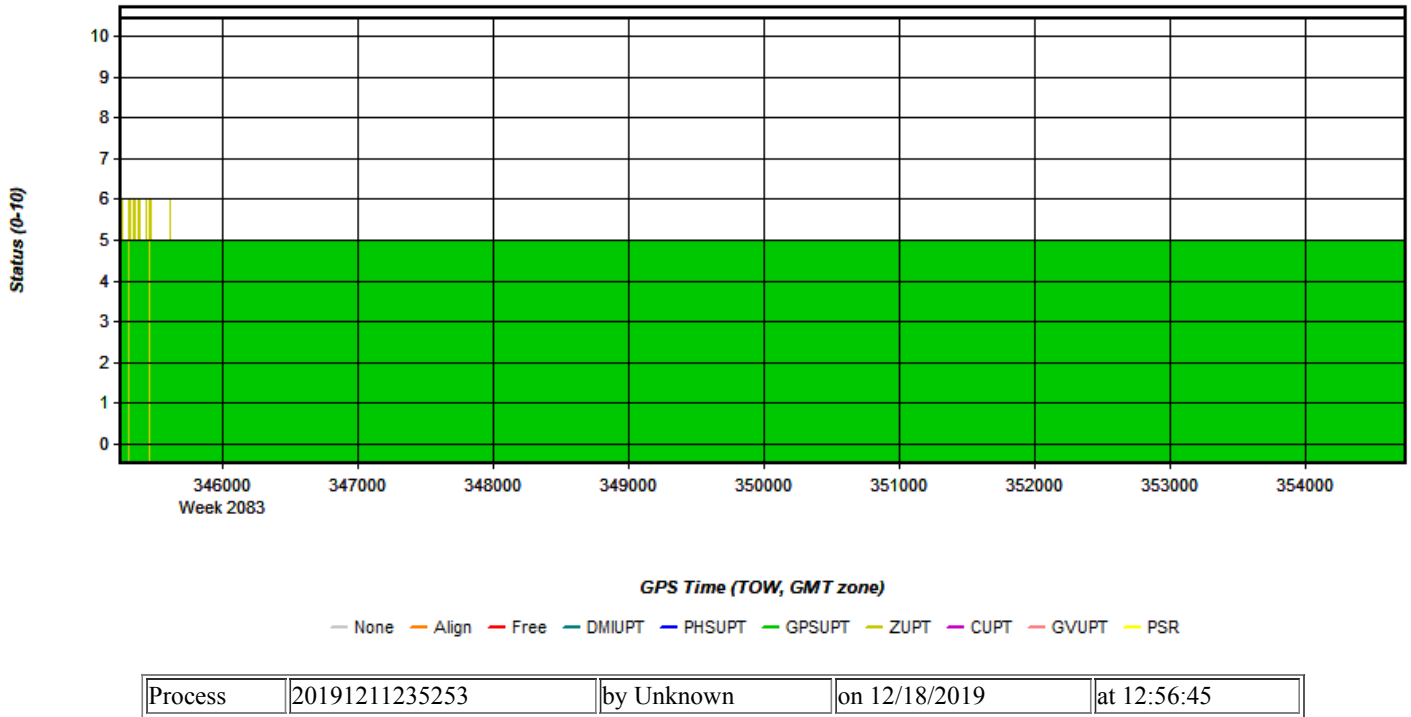


Figure 9: 20191211235253 [Smoothed TC Combined] - Fwd/Rev Attitude Separation Plot

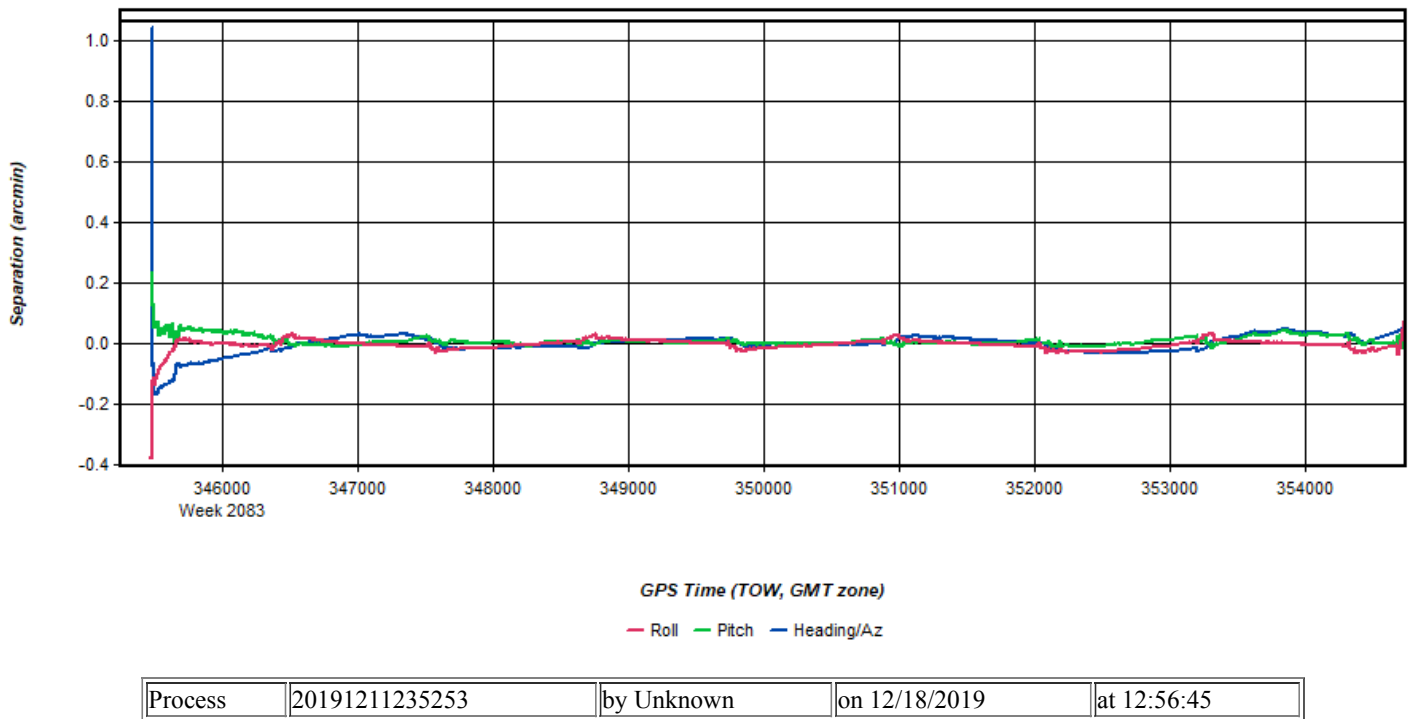


Figure 10: 20191211235253 [Smoothed TC Combined] - Estimated Attitude Accuracy Plot

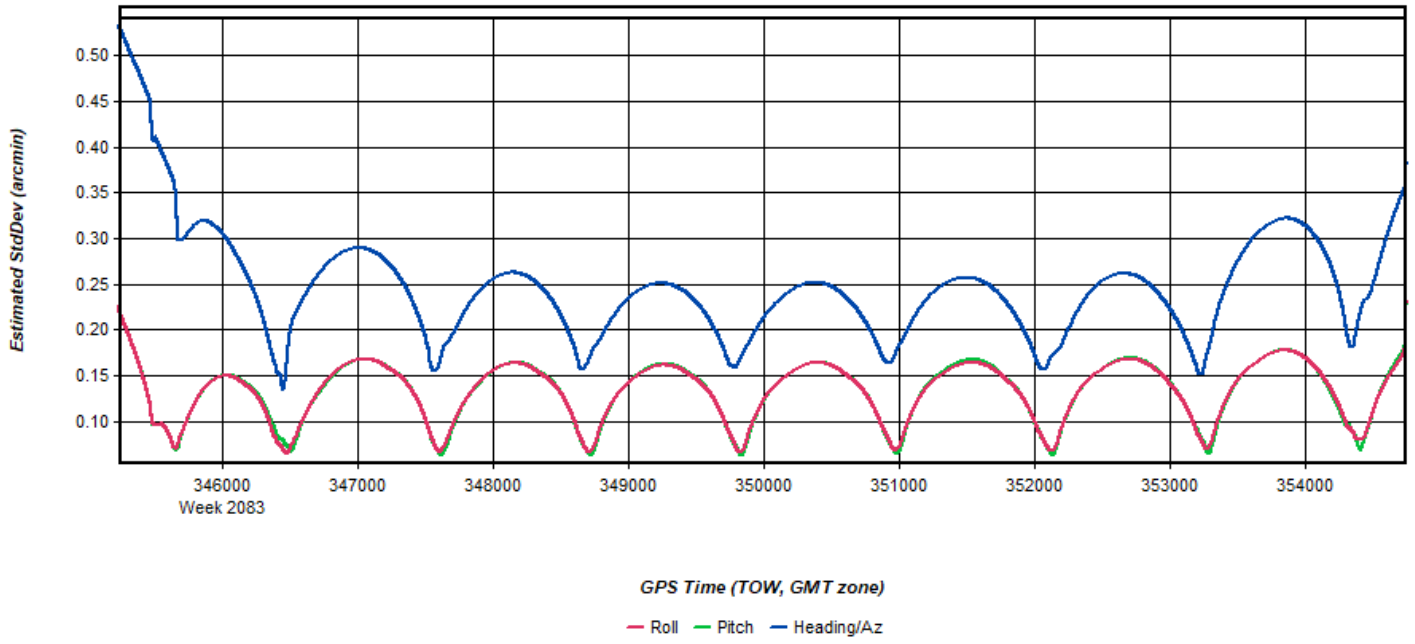


Figure 11: 20191211235253 [Smoothed TC Combined] - Azimuth Plot

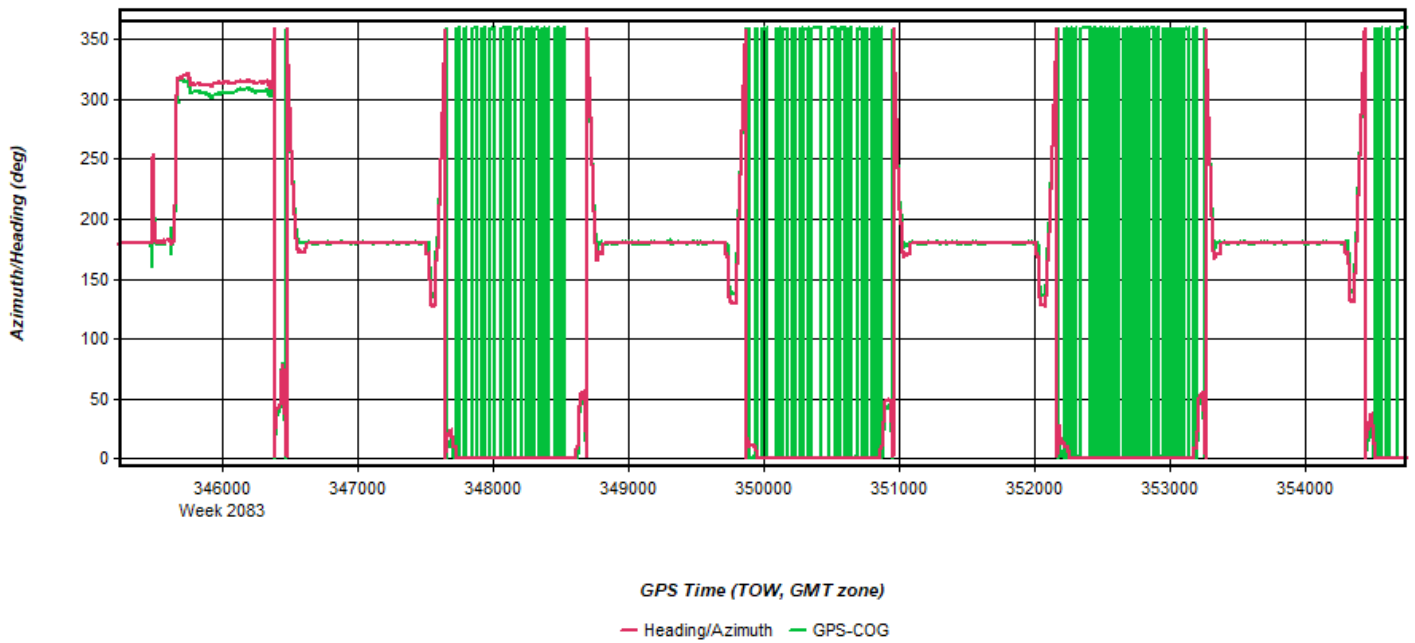
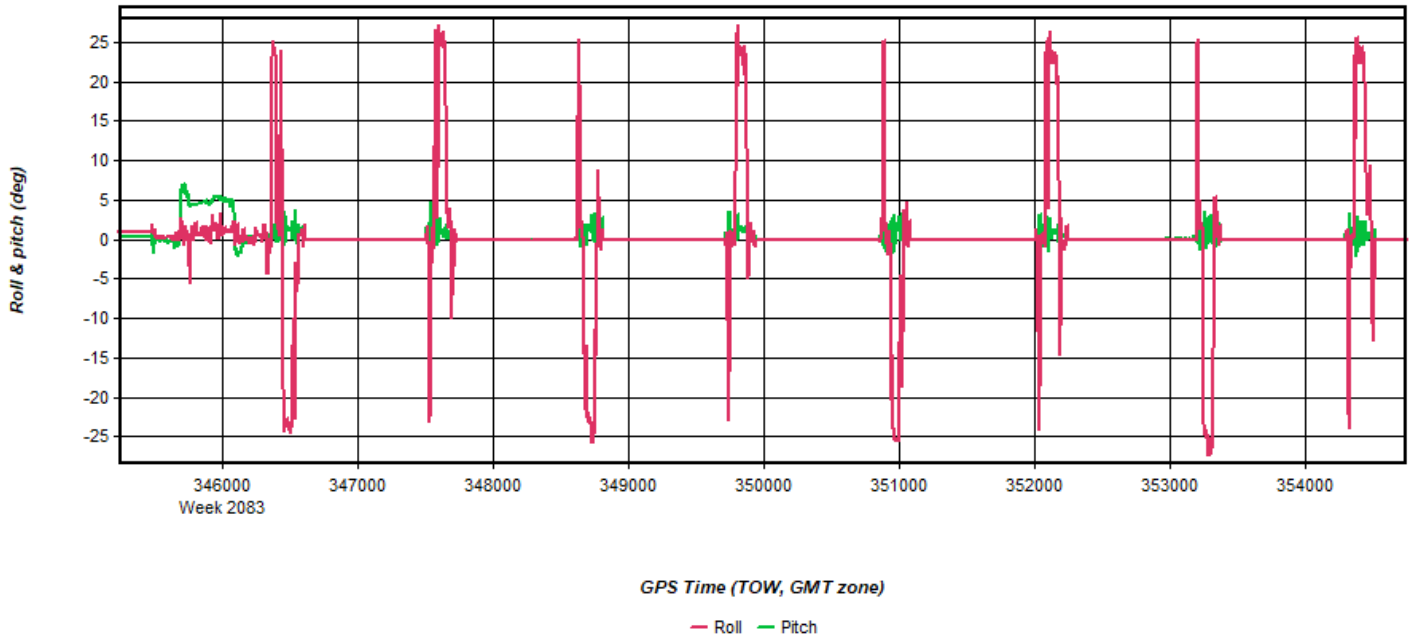
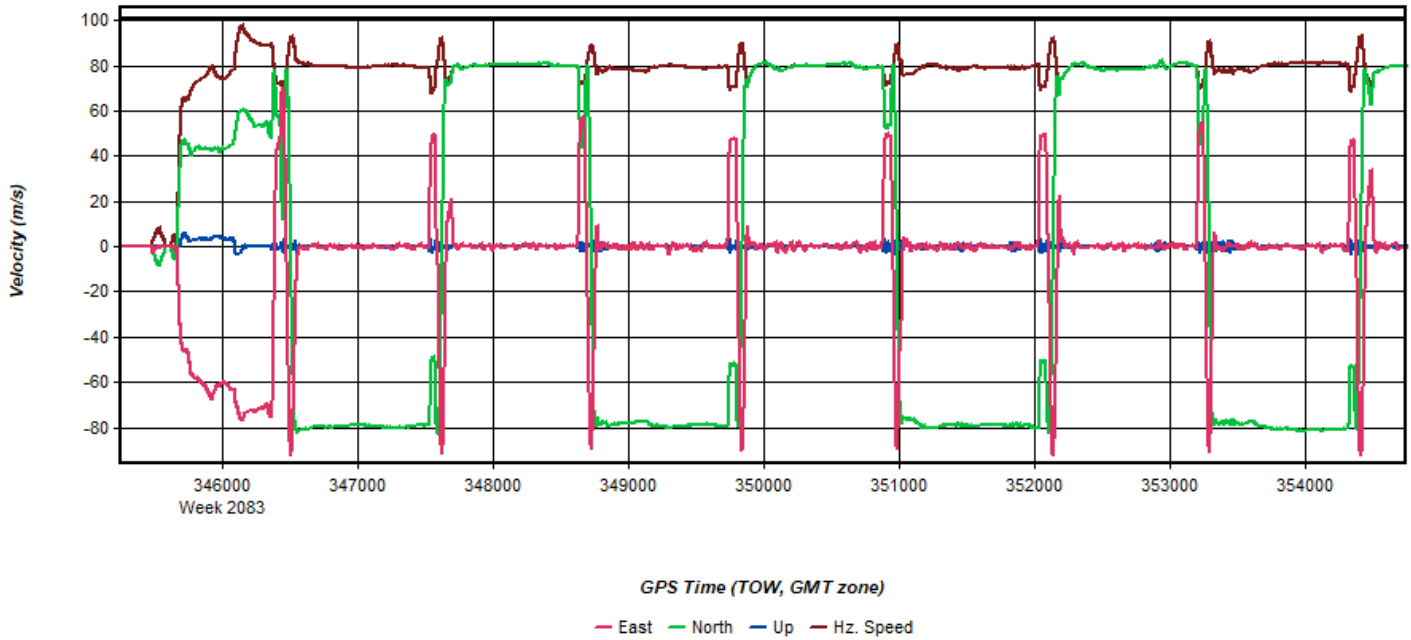


Figure 12: 20191211235253 [Smoothed TC Combined] - Roll & Pitch Plot



Process	20191211235253	by Unknown	on 12/18/2019	at 12:56:45
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Figure 13: 20191211235253 [Smoothed TC Combined] - Velocity Profile Plot



Process	20191211235253	by Unknown	on 12/18/2019	at 12:56:45
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Figure 14: 20191211235253 [Smoothed TC Combined] - Body Frame Velocity Plot

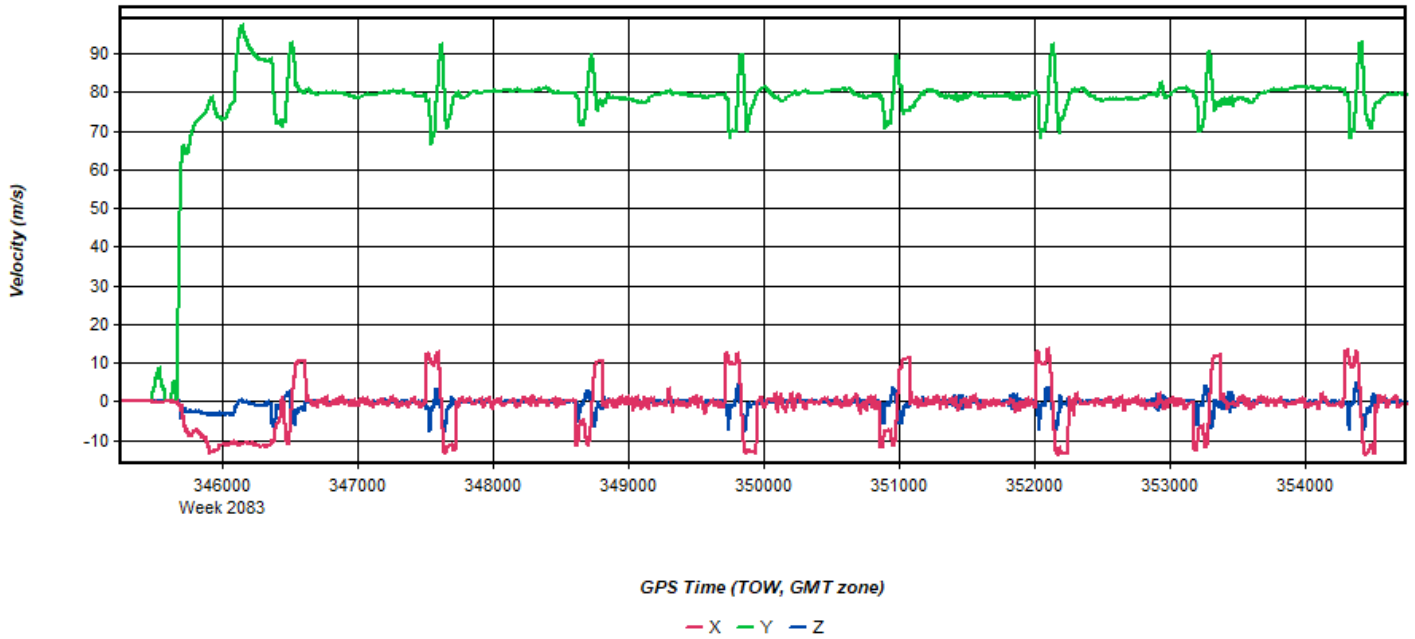


Figure 15: 20191211235253 [Smoothed TC Combined] - Height Profile Plot

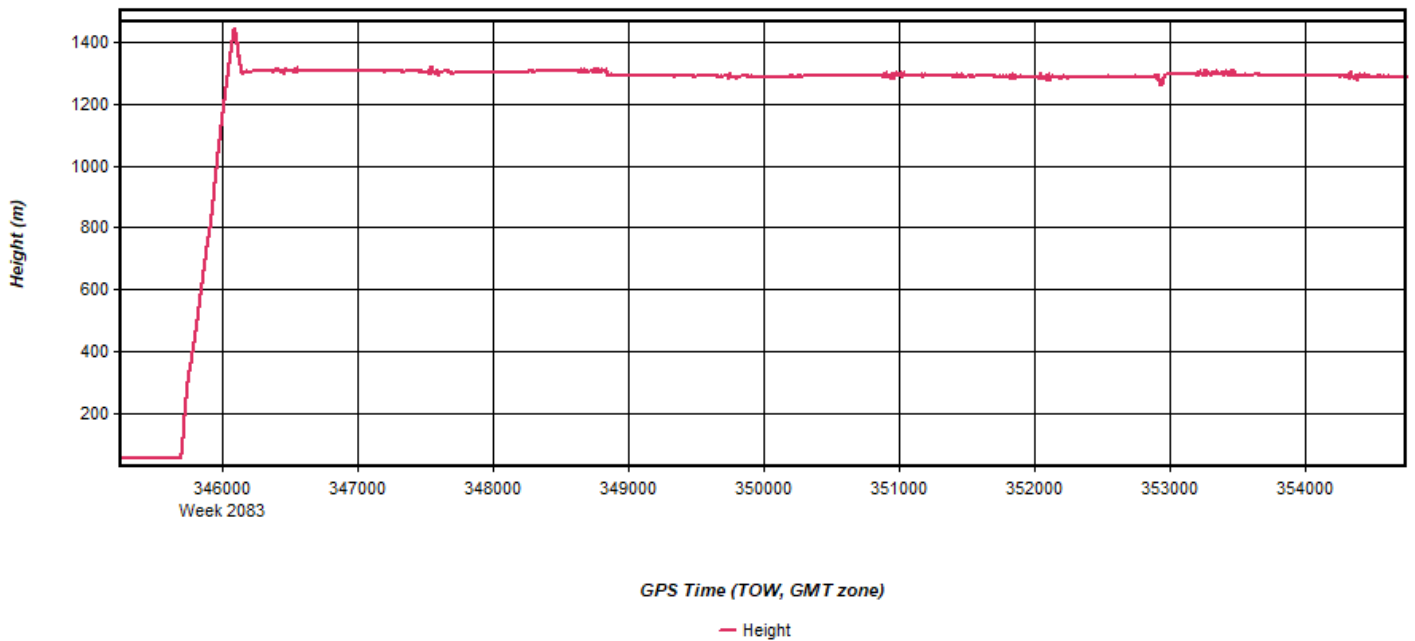
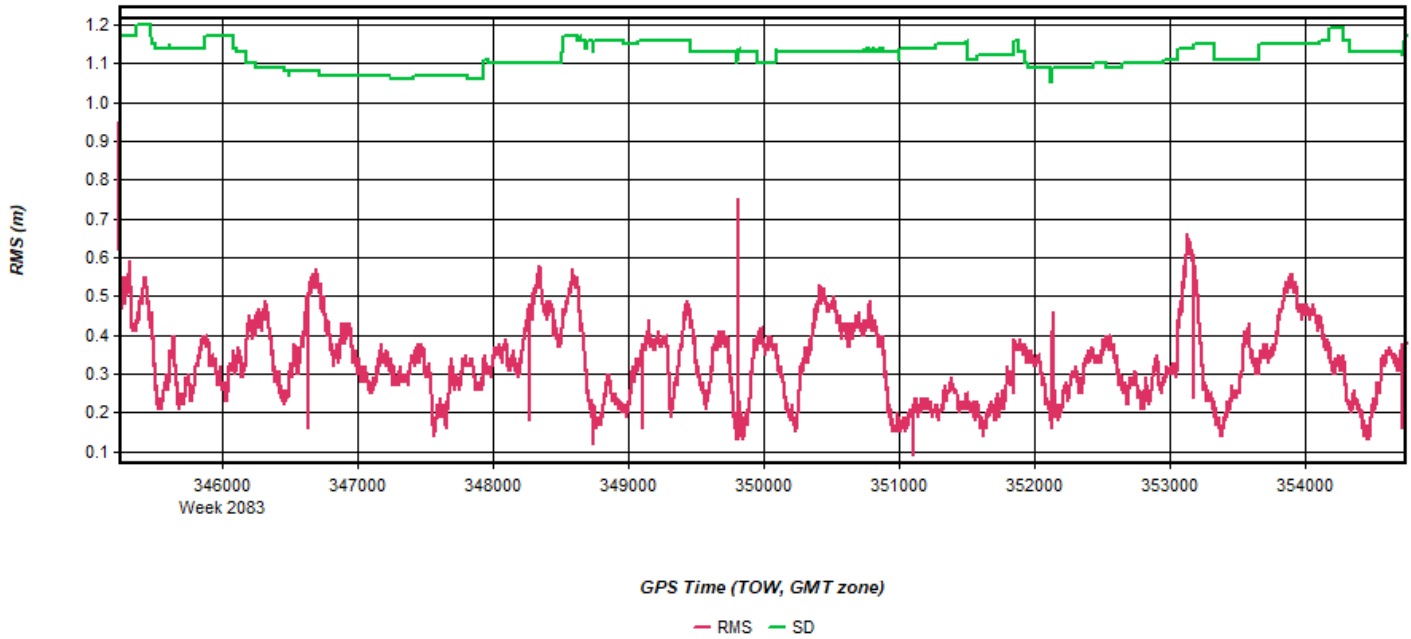
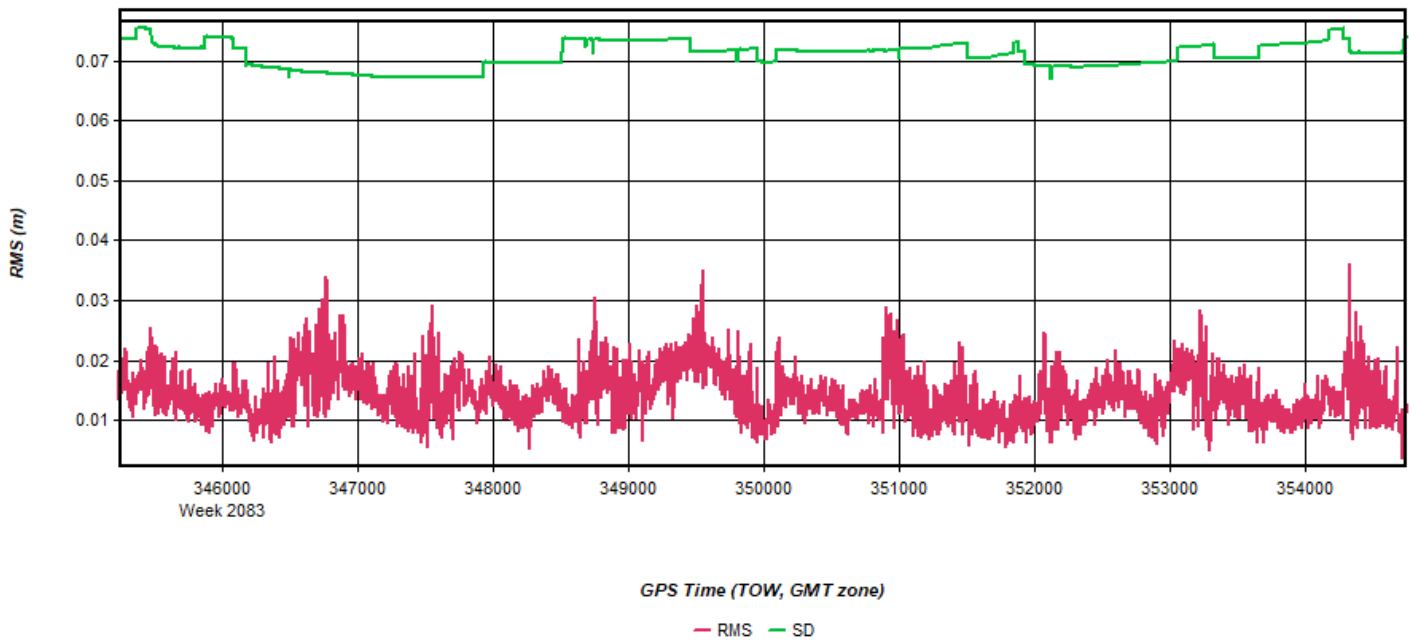


Figure 16: 20191211235253 [Smoothed TC Combined] - C/A Code Residual RMS Plot



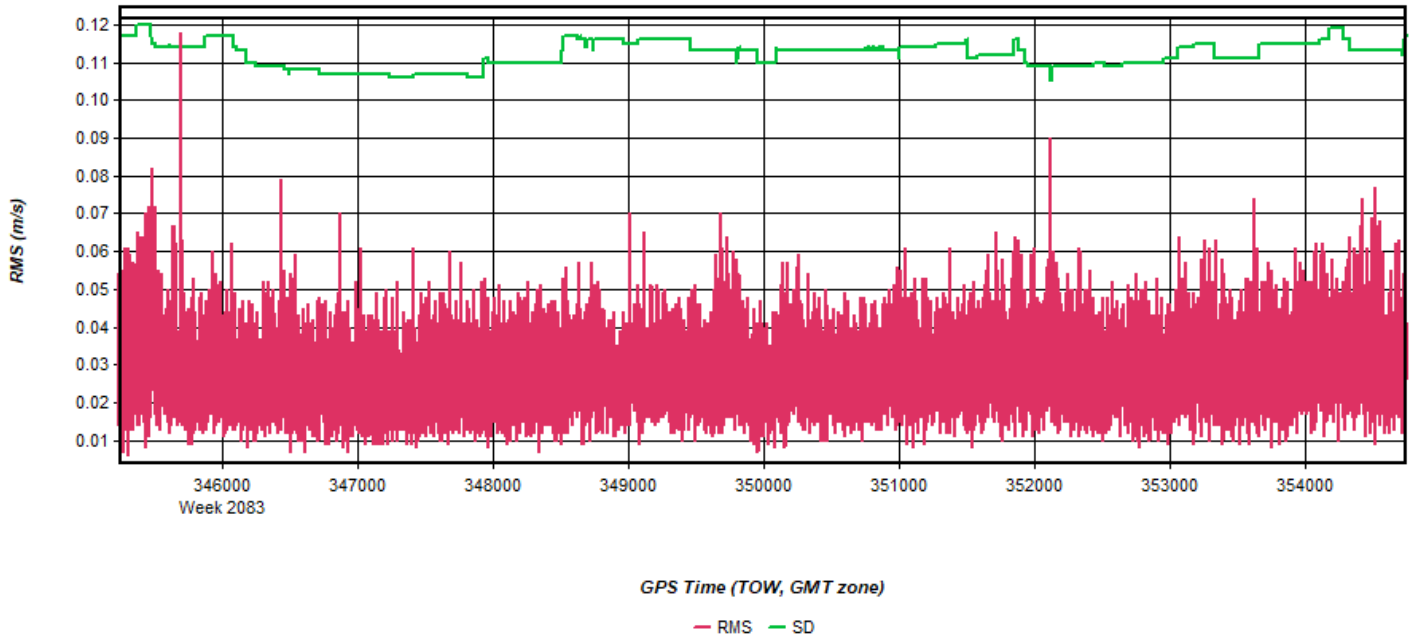
Process	20191211235253	by Unknown	on 12/18/2019	at 12:56:45
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Figure 17: 20191211235253 [Smoothed TC Combined] - Carrier Residual RMS Plot



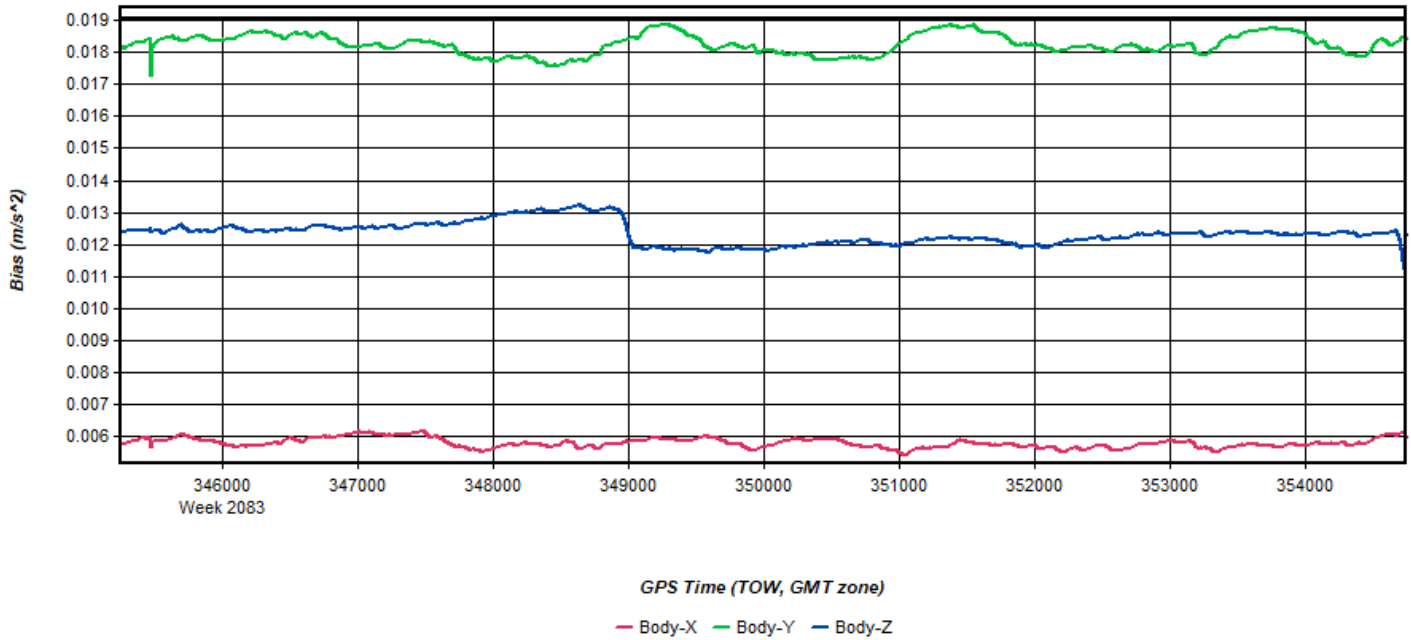
Process	20191211235253	by Unknown	on 12/18/2019	at 12:56:45
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Figure 18: 20191211235253 [Smoothed TC Combined] - L1 Doppler Residual RMS Plot



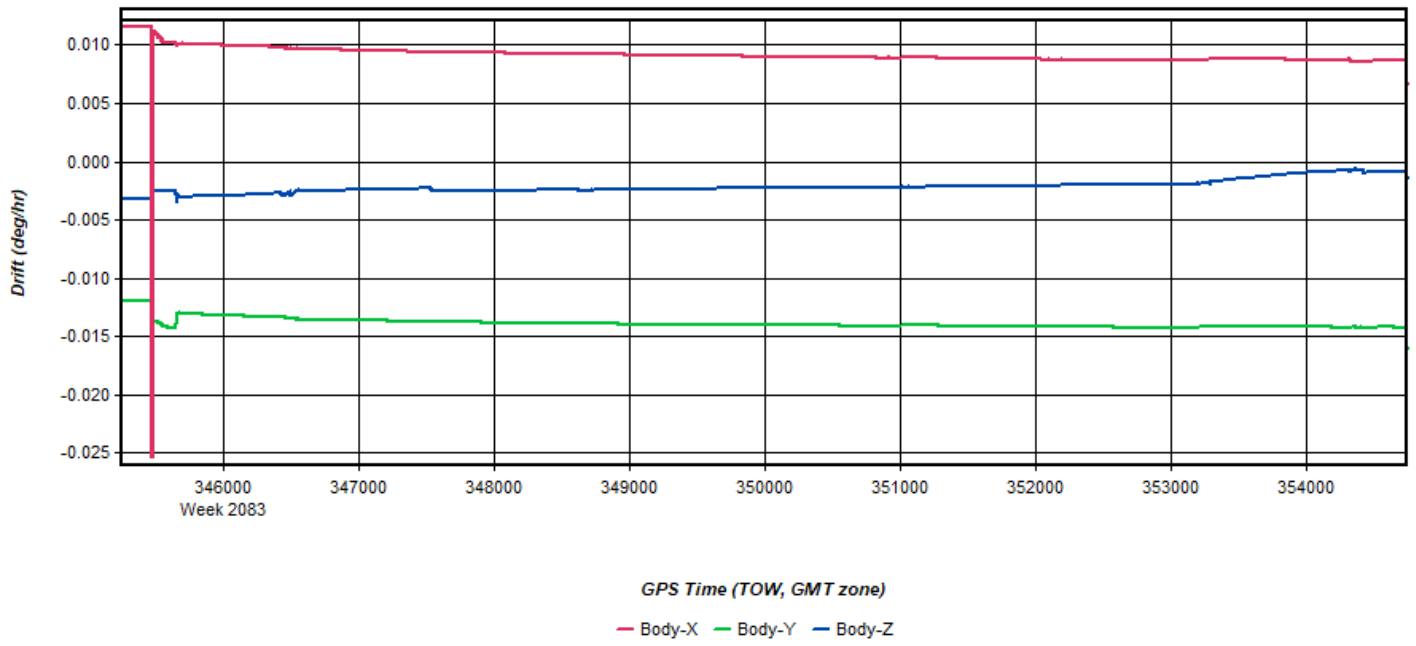
Process	20191211235253	by Unknown	on 12/18/2019	at 12:56:45
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Figure 19: 20191211235253 [Smoothed TC Combined] - Accelerometer Bias Plot



Process	20191211235253	by Unknown	on 12/18/2019	at 12:56:45
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Figure 20: 20191211235253 [Smoothed TC Combined] - Gyro Drift Plot



Process	20191211235253	by Unknown	on 12/18/2019	at 12:56:45
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Output Results for 20191212150331

Inertial Explorer Version 8.80.2305
12/24/2019

Figure 1: Smoothed TC Combined - Map



Process	20191212150331	by Unknown	on 12/24/2019	at 10:43:06
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Figure 2: 20191212150331 [Smoothed TC Combined] - Forward/Reverse or Combined Separation Plot

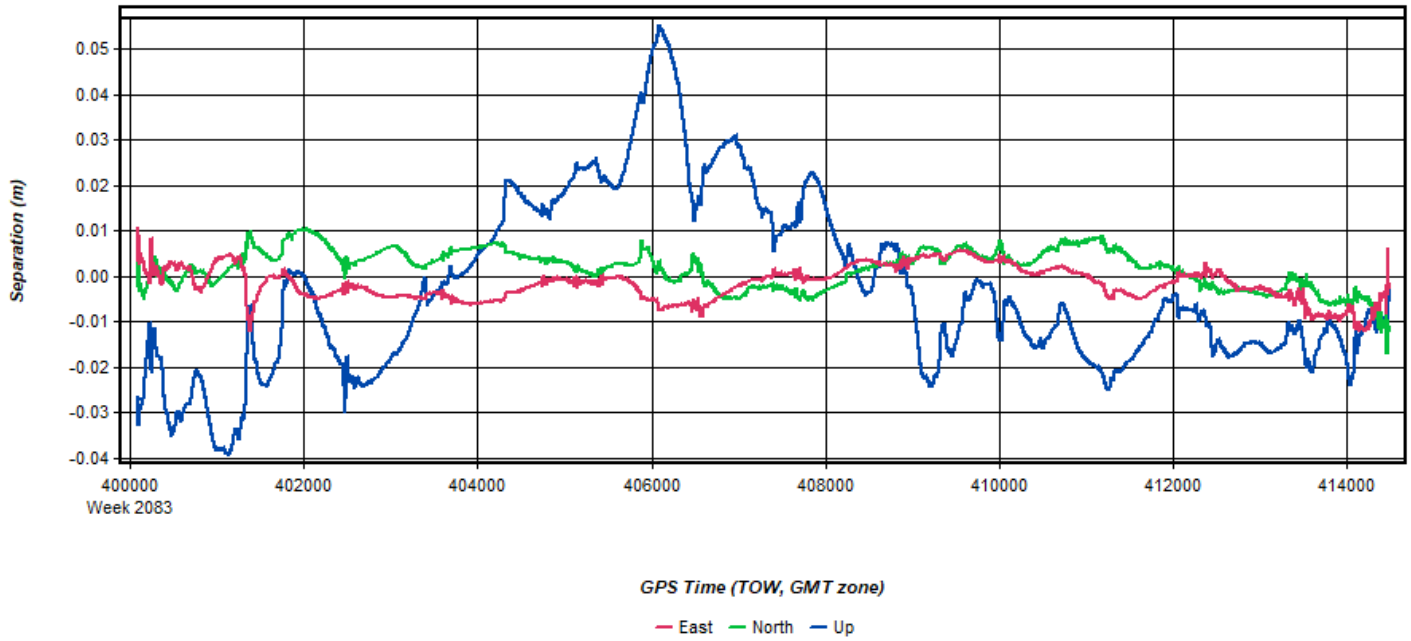


Figure 3: 20191212150331 [Smoothed TC Combined] - Float or Fixed Ambiguity

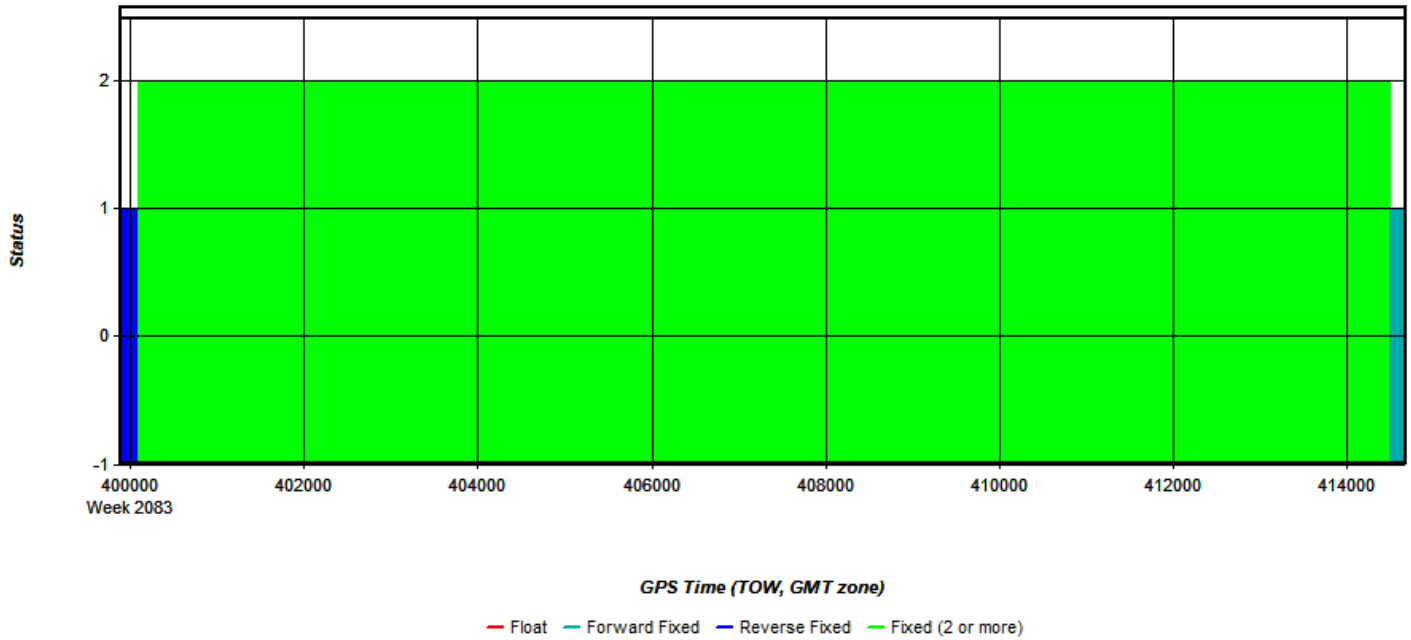


Figure 4: 20191212150331 [Smoothed TC Combined] - Forward/Reverse Separation Plot (Fixed)

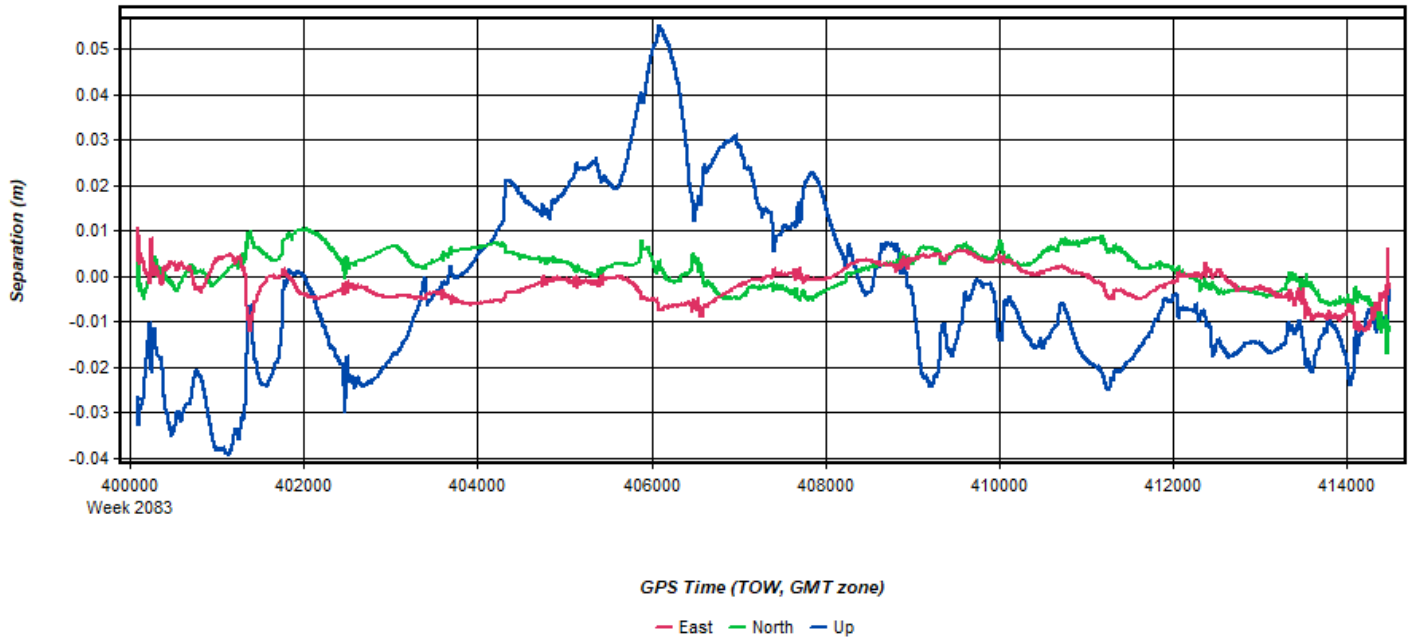


Figure 5: 20191212150331 [Smoothed TC Combined] - Estimated Position Accuracy Plot

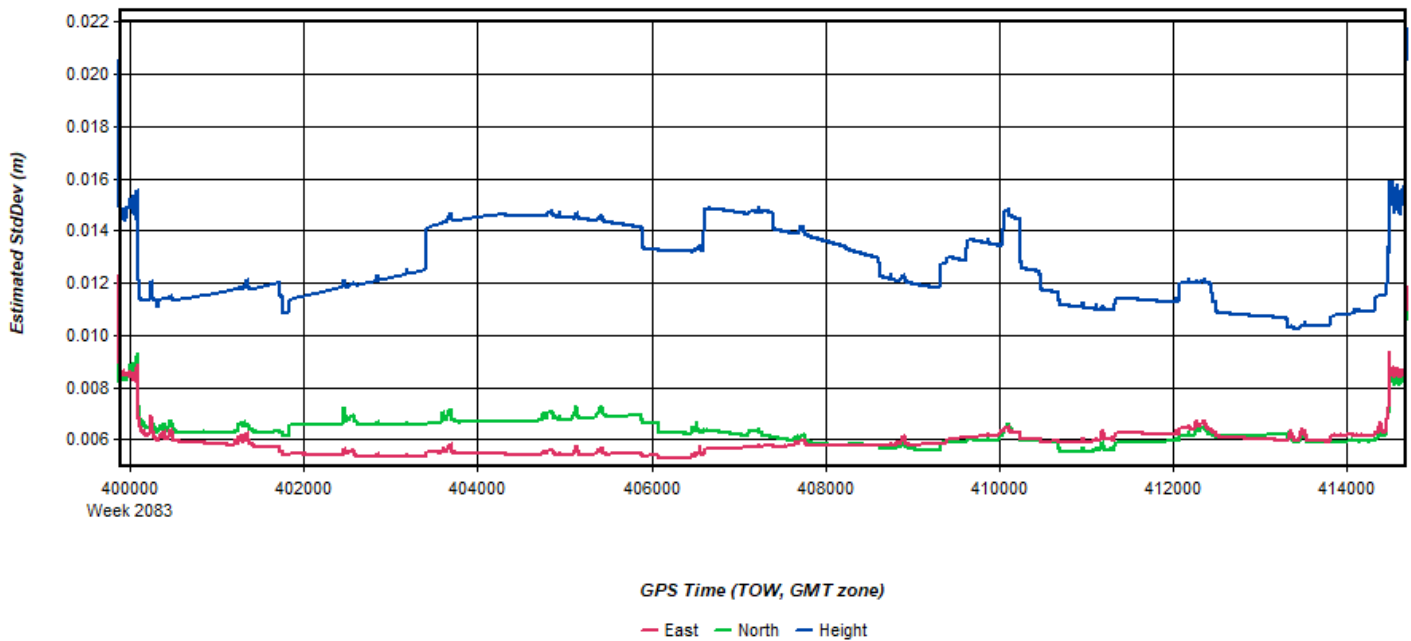
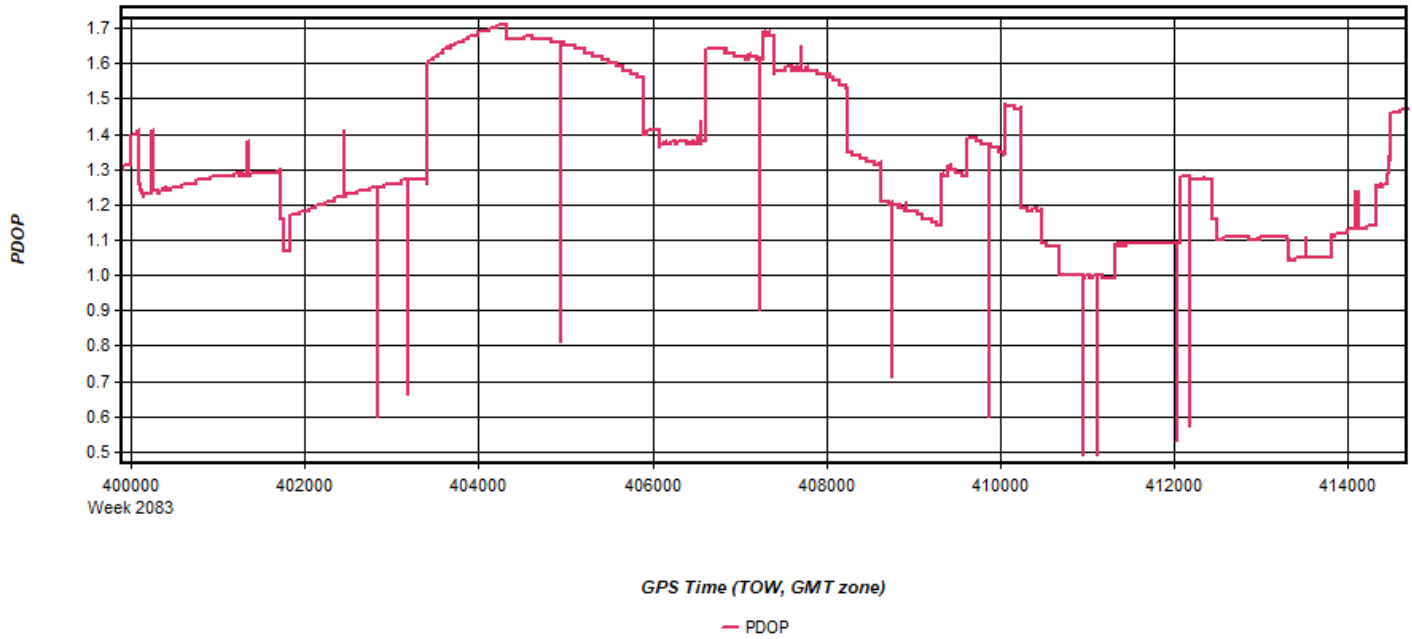
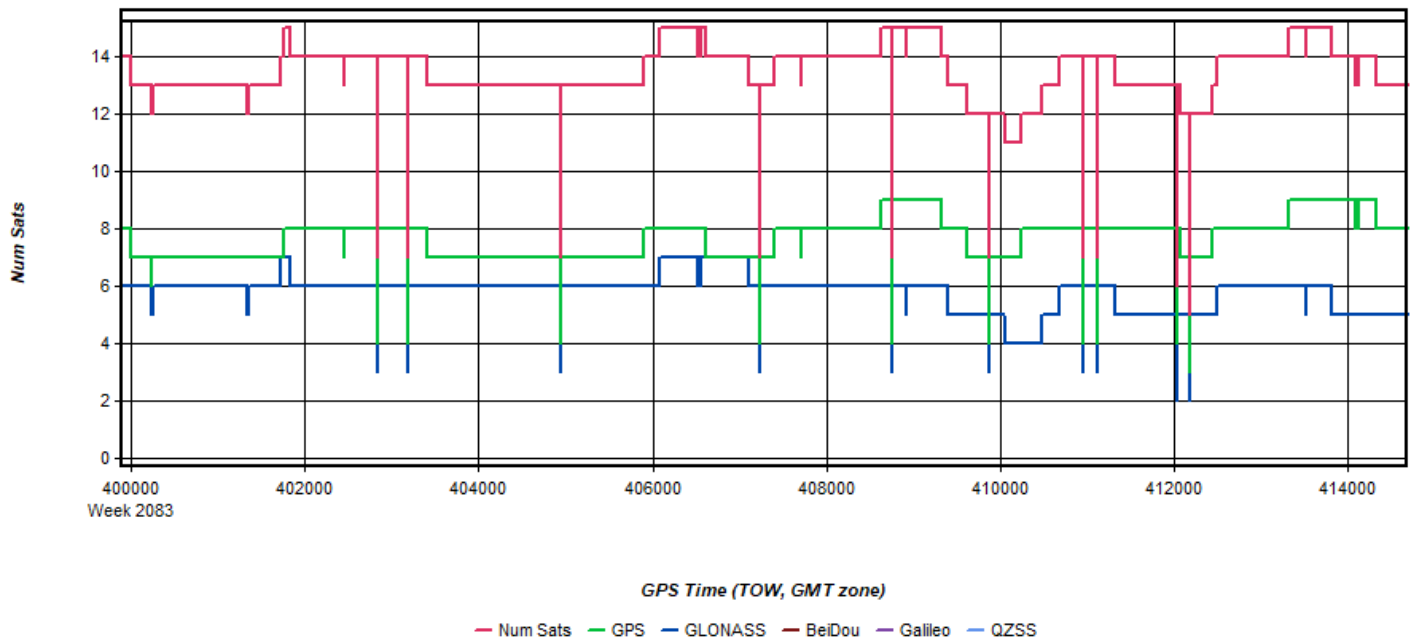


Figure 6: 20191212150331 [Smoothed TC Combined] - PDOP Plot



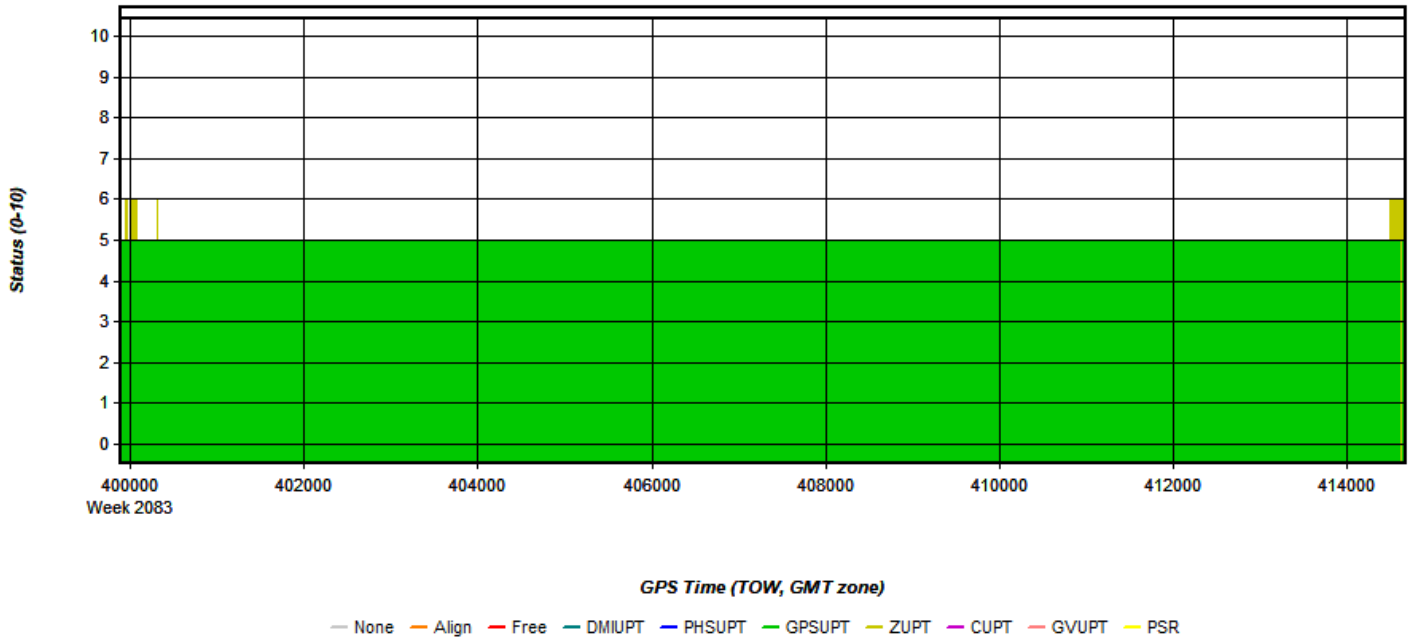
Process	20191212150331	by Unknown	on 12/24/2019	at 10:43:06
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Figure 7: 20191212150331 [Smoothed TC Combined] - Number of Satellites Line Plot



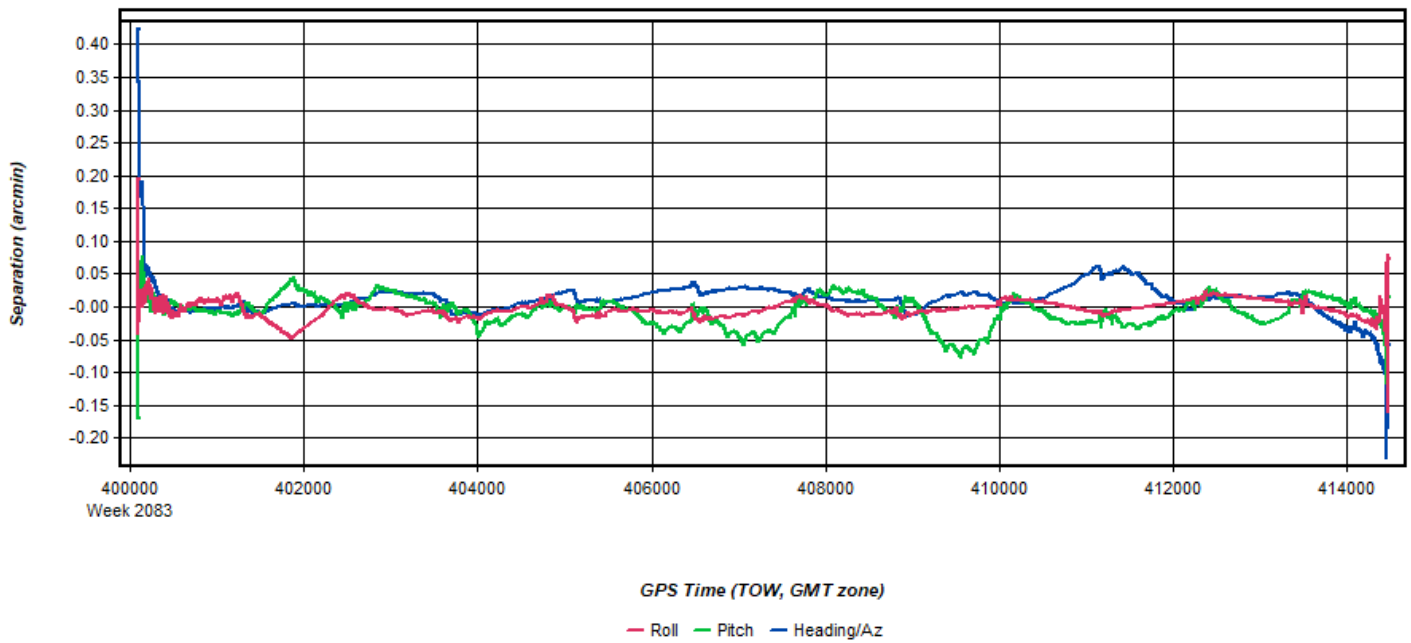
Process	20191212150331	by Unknown	on 12/24/2019	at 10:43:06
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Figure 8: 20191212150331 [Smoothed TC Combined] - Status flag for IMU processing



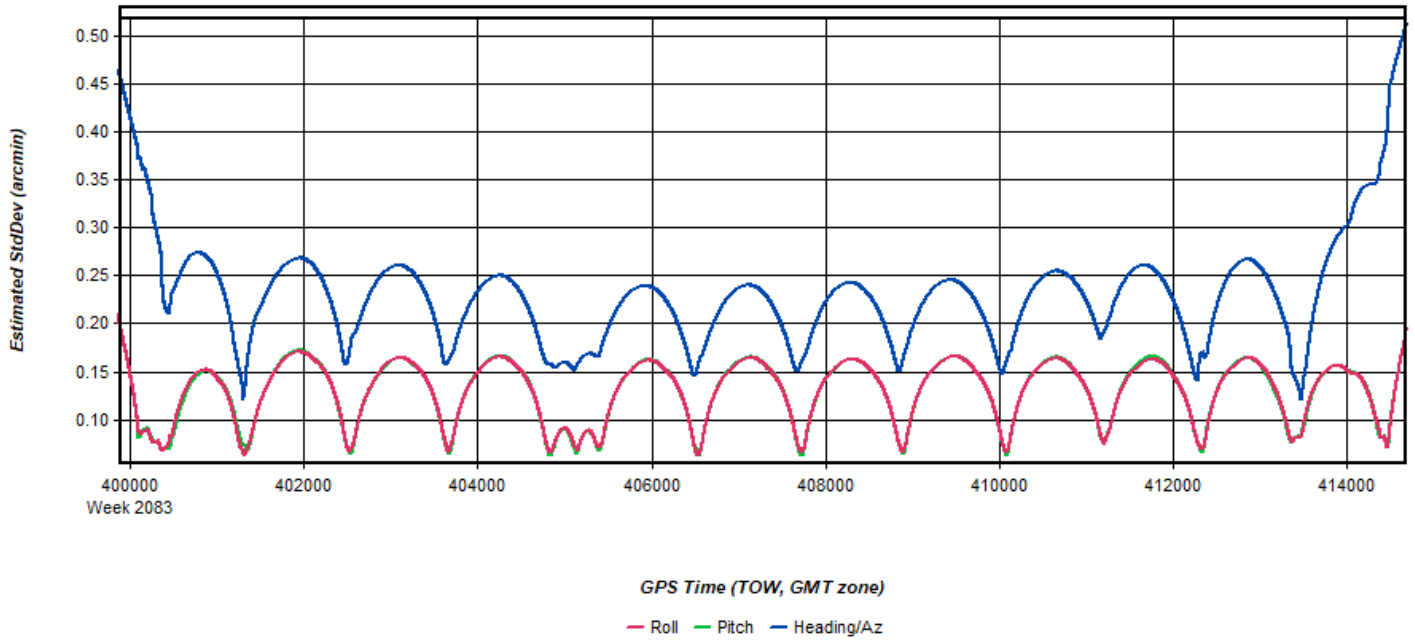
Process	20191212150331	by Unknown	on 12/24/2019	at 10:43:06
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Figure 9: 20191212150331 [Smoothed TC Combined] - Fwd/Rev Attitude Separation Plot



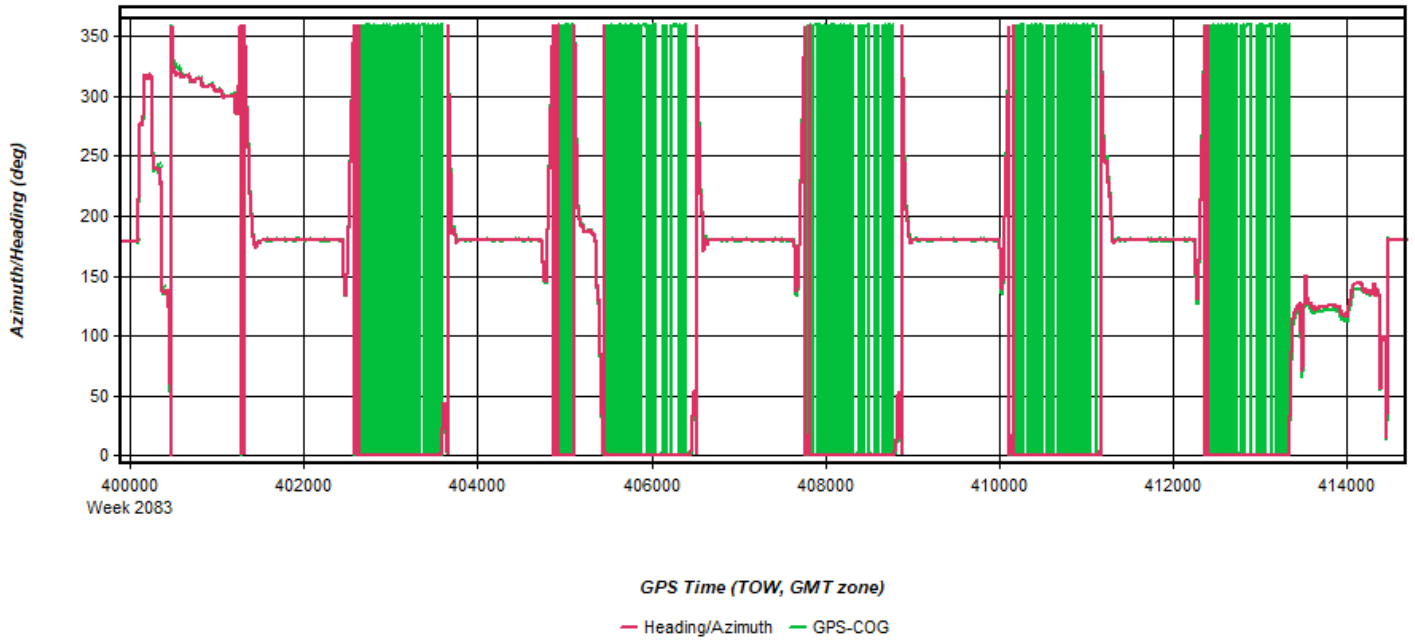
Process	20191212150331	by Unknown	on 12/24/2019	at 10:43:06
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Figure 10: 20191212150331 [Smoothed TC Combined] - Estimated Attitude Accuracy Plot



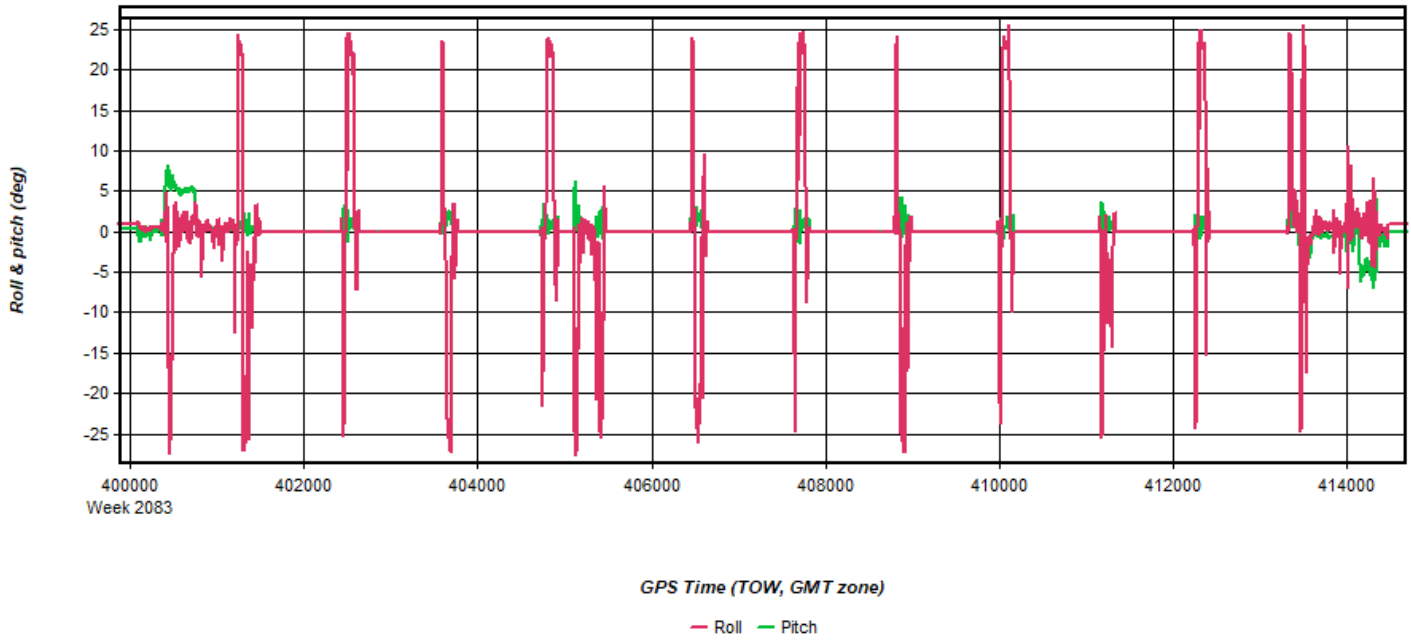
Process	20191212150331	by Unknown	on 12/24/2019	at 10:43:06
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Figure 11: 20191212150331 [Smoothed TC Combined] - Azimuth Plot



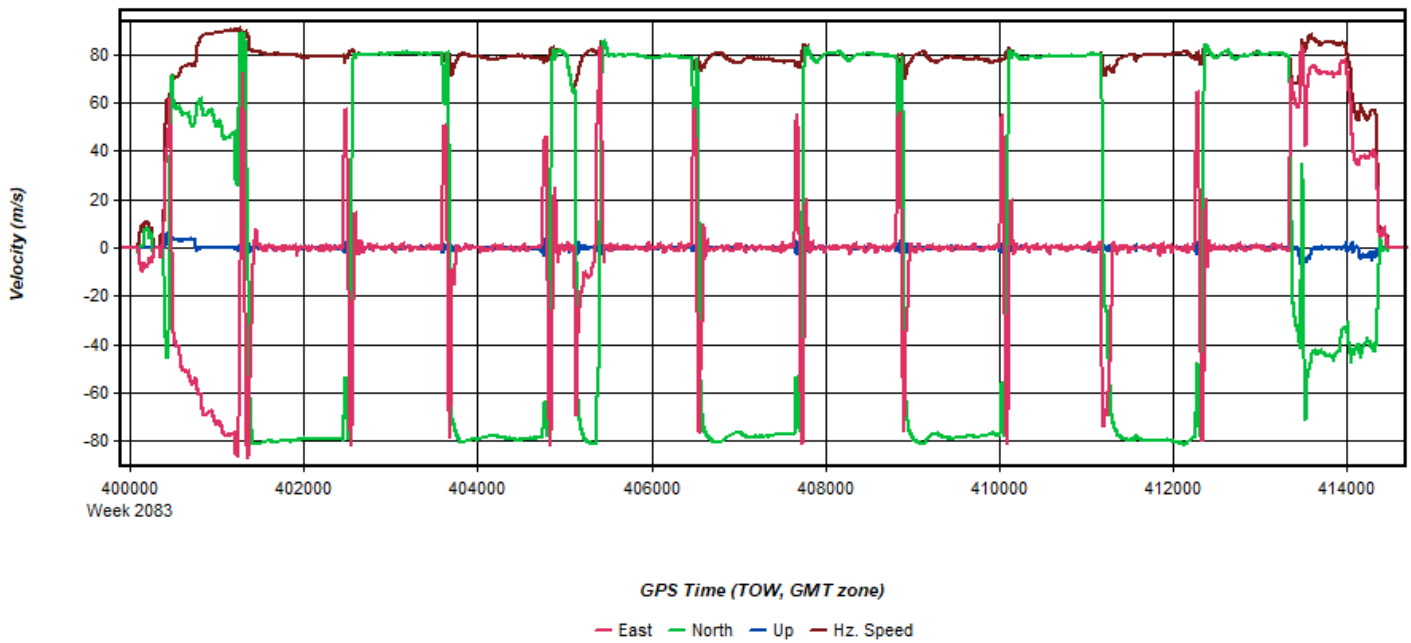
Process	20191212150331	by Unknown	on 12/24/2019	at 10:43:06
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Figure 12: 20191212150331 [Smoothed TC Combined] - Roll & Pitch Plot



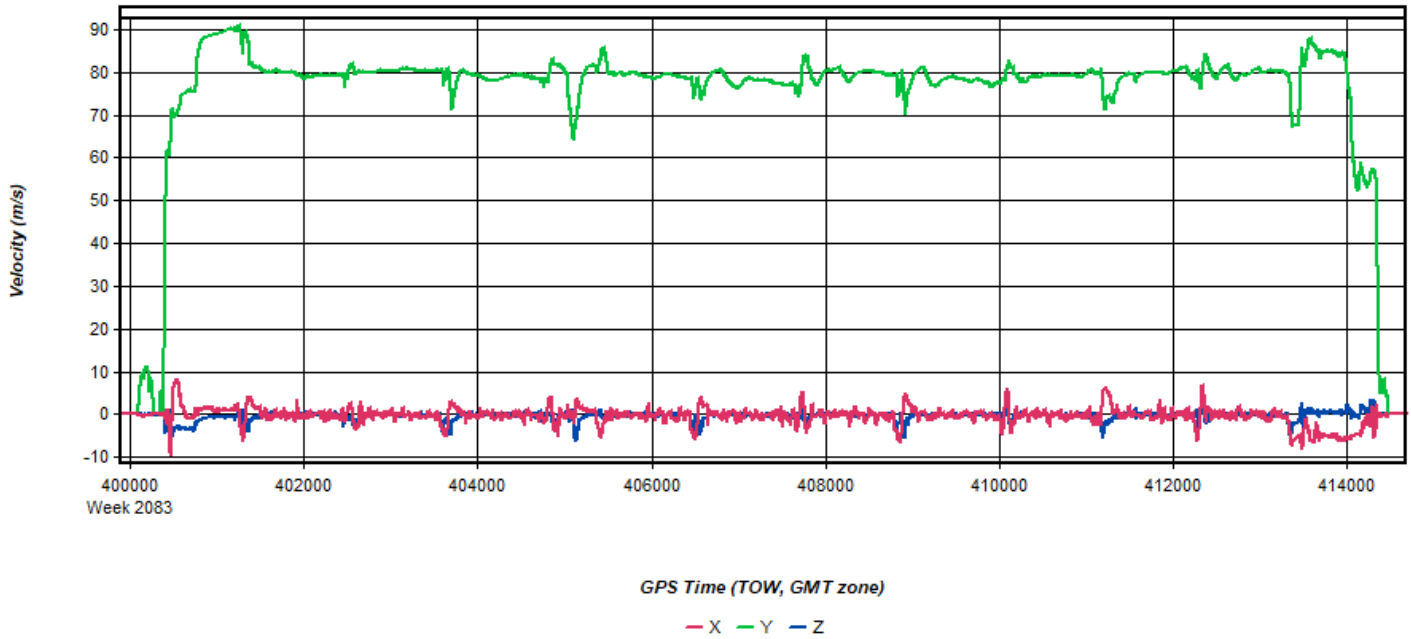
Process	20191212150331	by Unknown	on 12/24/2019	at 10:43:06
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Figure 13: 20191212150331 [Smoothed TC Combined] - Velocity Profile Plot



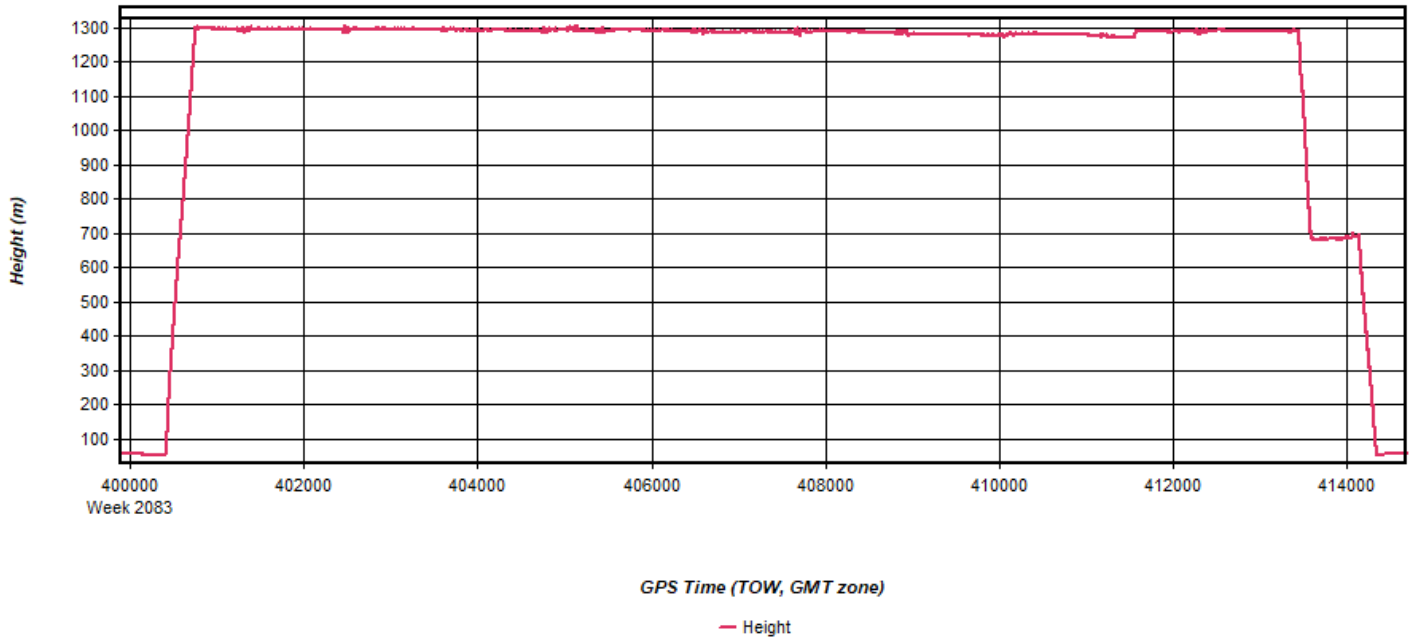
Process	20191212150331	by Unknown	on 12/24/2019	at 10:43:06
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Figure 14: 20191212150331 [Smoothed TC Combined] - Body Frame Velocity Plot



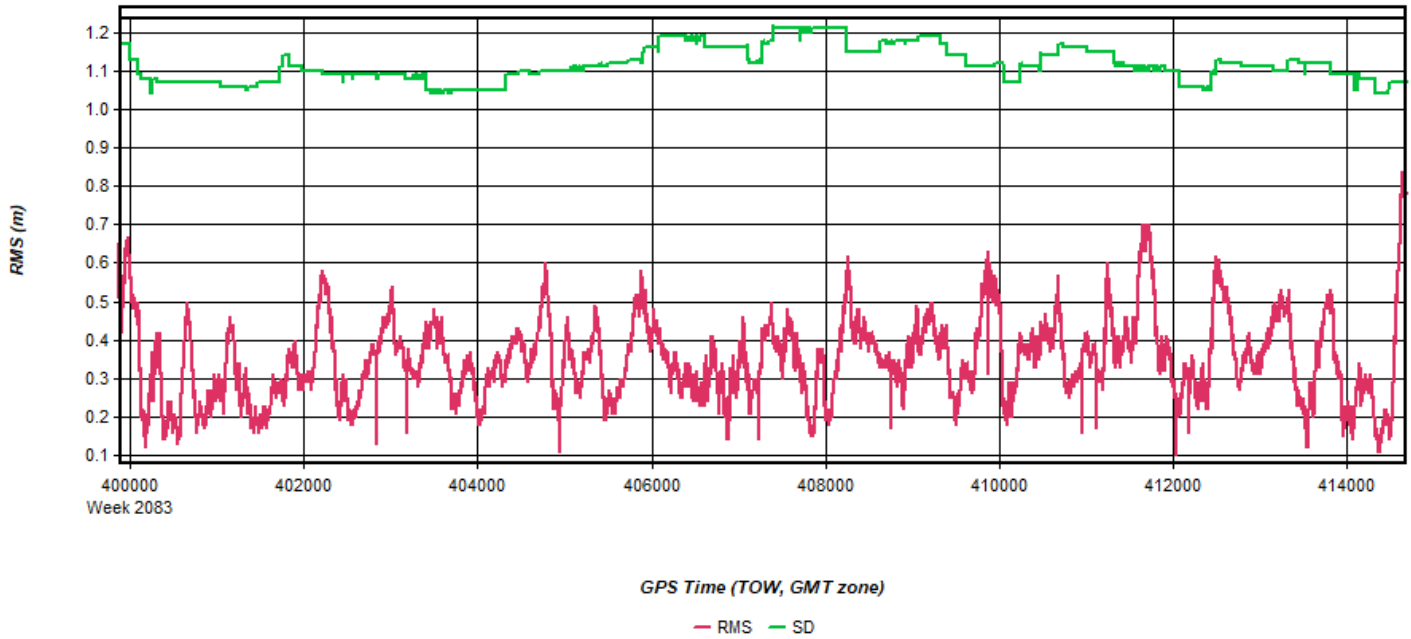
Process	20191212150331	by Unknown	on 12/24/2019	at 10:43:06
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Figure 15: 20191212150331 [Smoothed TC Combined] - Height Profile Plot



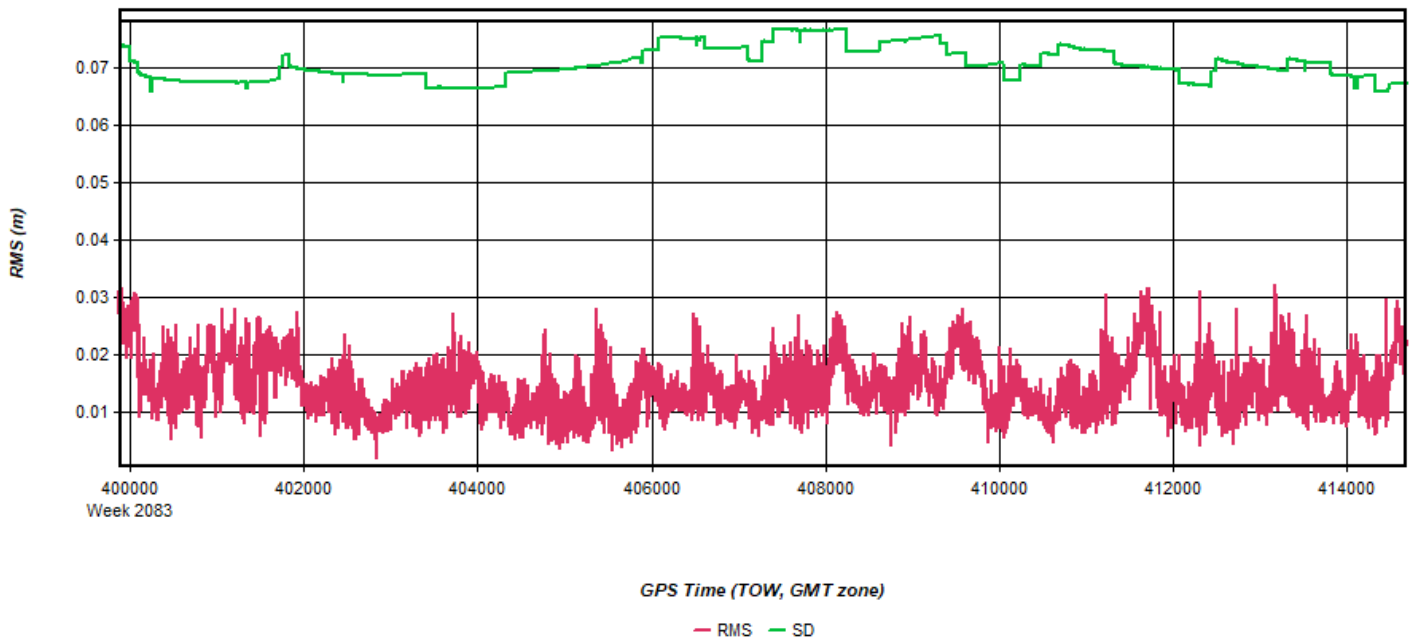
Process	20191212150331	by Unknown	on 12/24/2019	at 10:43:06
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Figure 16: 20191212150331 [Smoothed TC Combined] - C/A Code Residual RMS Plot



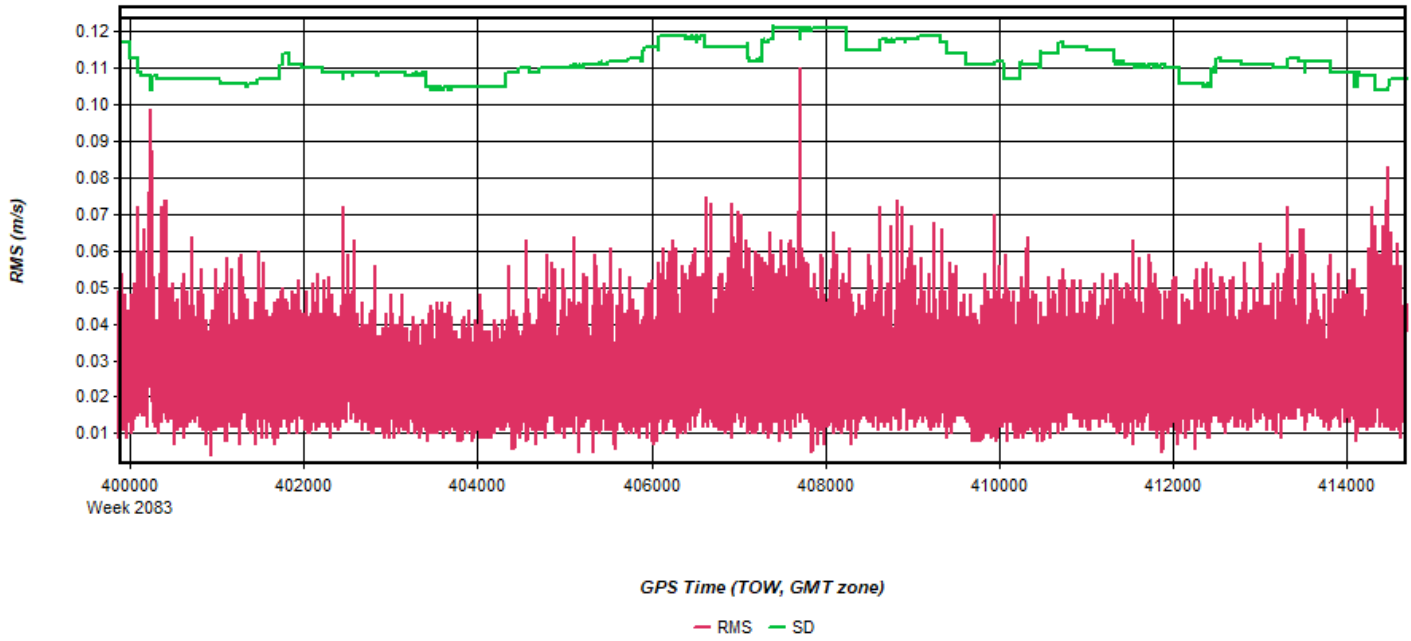
Process	20191212150331	by Unknown	on 12/24/2019	at 10:43:06
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Figure 17: 20191212150331 [Smoothed TC Combined] - Carrier Residual RMS Plot



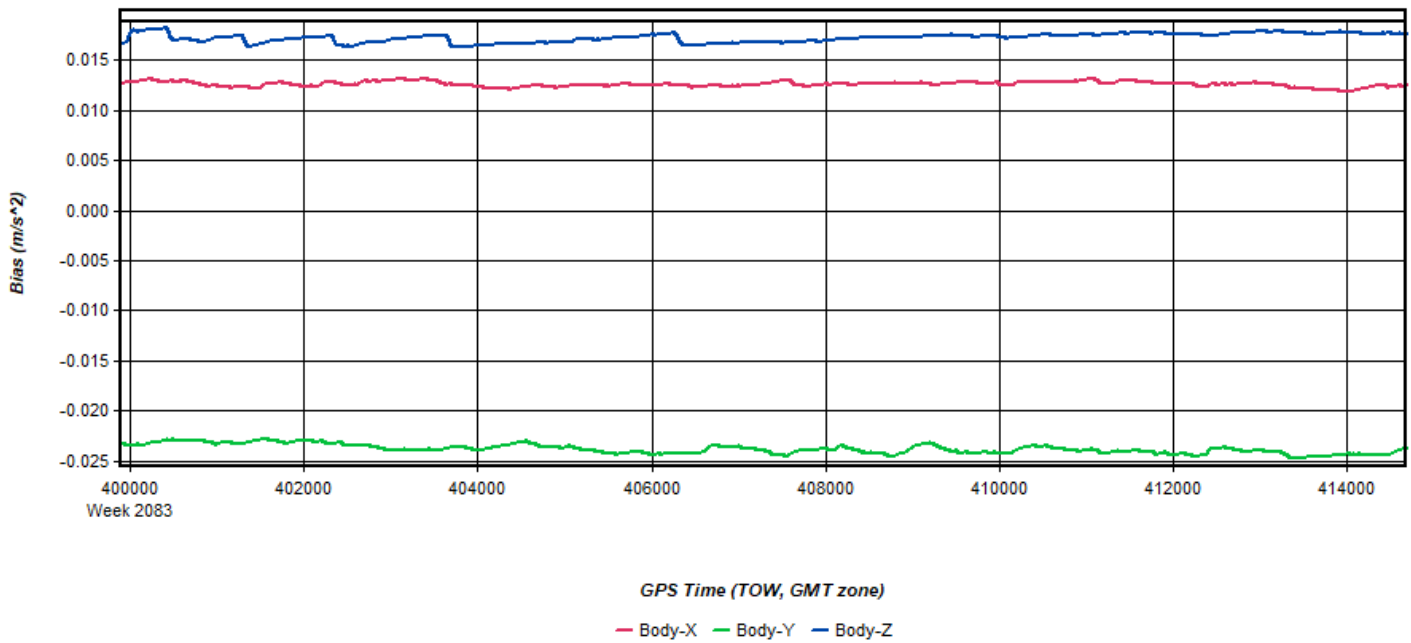
Process	20191212150331	by Unknown	on 12/24/2019	at 10:43:06
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Figure 18: 20191212150331 [Smoothed TC Combined] - L1 Doppler Residual RMS Plot



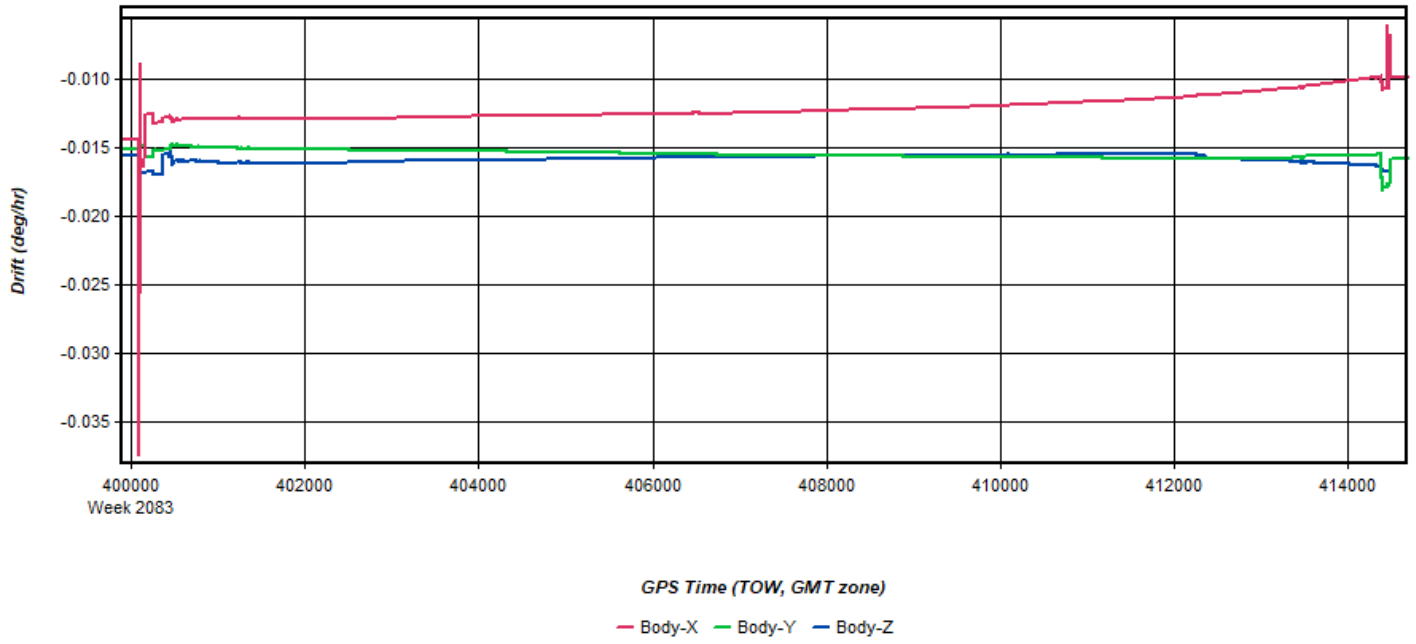
Process	20191212150331	by Unknown	on 12/24/2019	at 10:43:06
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Figure 19: 20191212150331 [Smoothed TC Combined] - Accelerometer Bias Plot



Process	20191212150331	by Unknown	on 12/24/2019	at 10:43:06
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Figure 20: 20191212150331 [Smoothed TC Combined] - Gyro Drift Plot

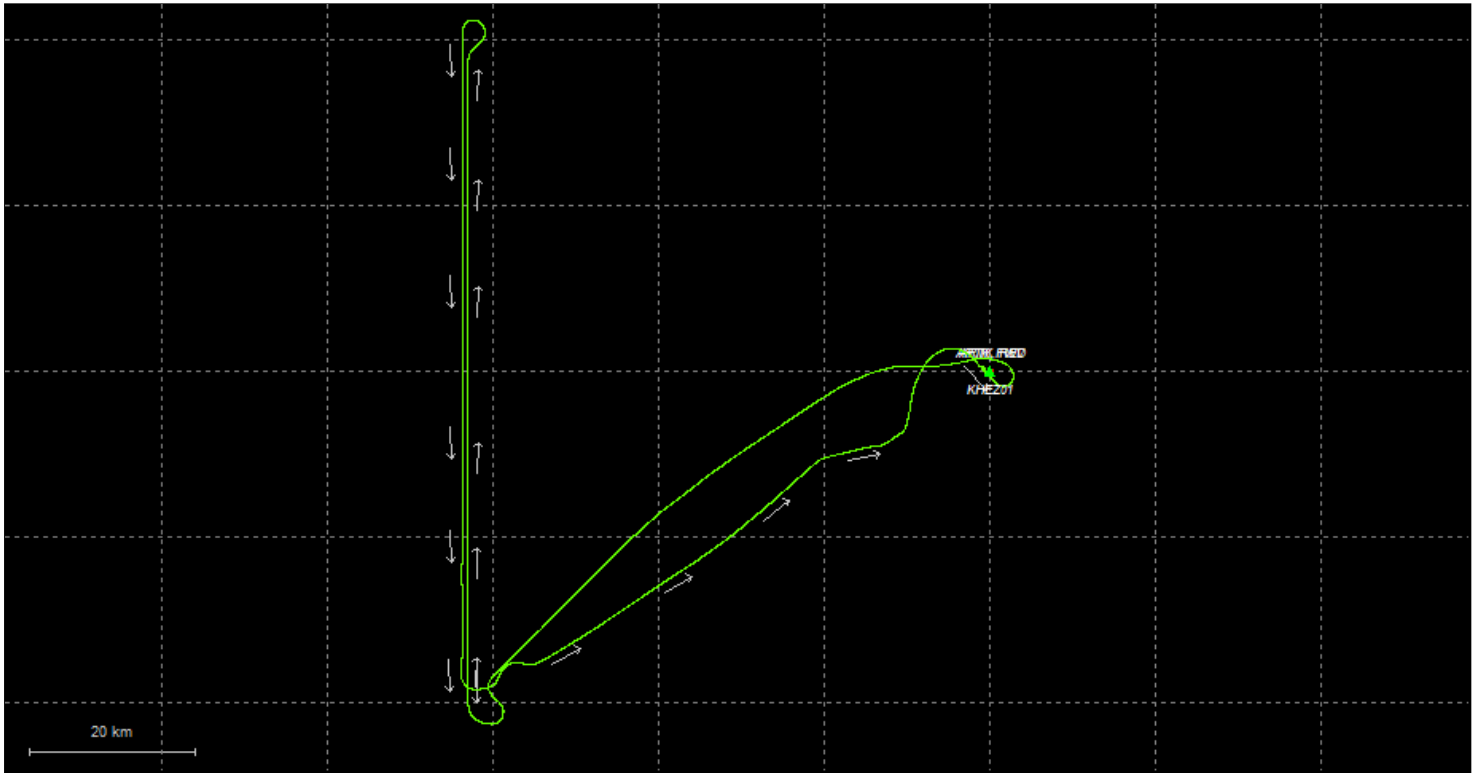


Process	20191212150331	by Unknown	on 12/24/2019	at 10:43:06
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Output Results for 20191212193215

Inertial Explorer Version 8.80.2305
12/24/2019

Figure 1: Smoothed TC Combined - Map



Process	20191212193215	by Unknown	on 12/24/2019	at 14:12:55
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Figure 2: 20191212193215 [Smoothed TC Combined] - Forward/Reverse or Combined Separation Plot

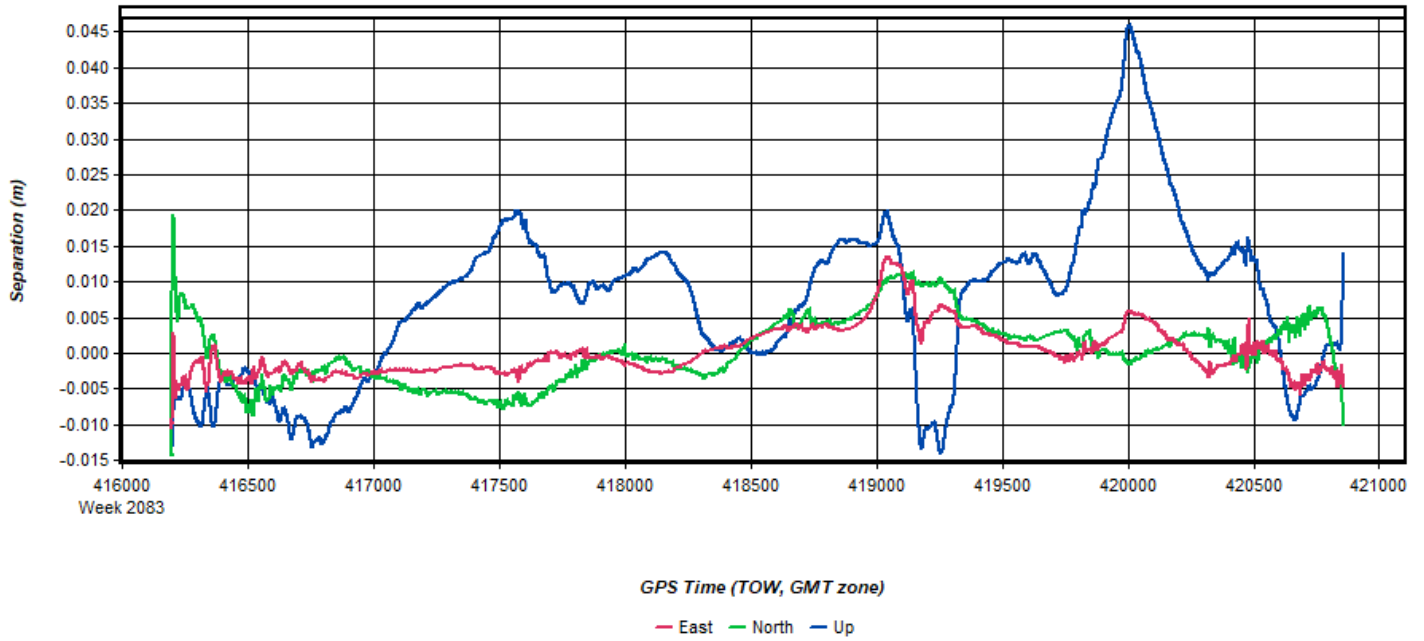


Figure 3: 20191212193215 [Smoothed TC Combined] - Float or Fixed Ambiguity

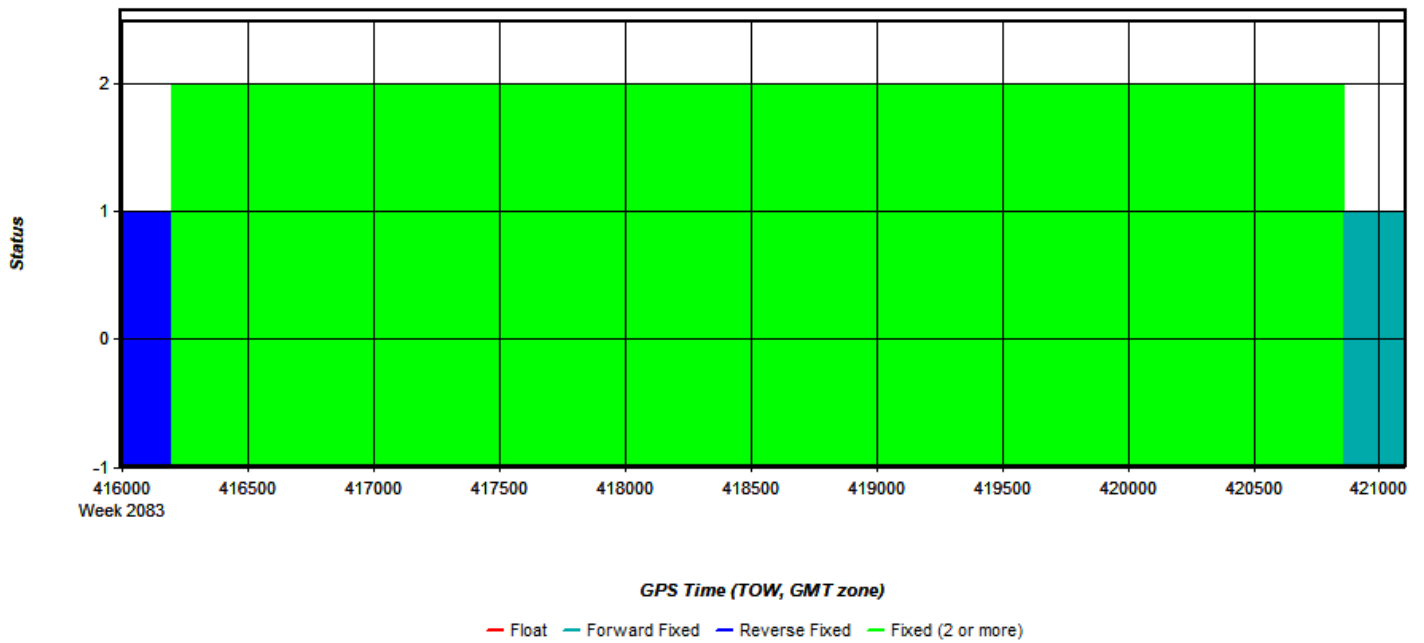


Figure 4: 20191212193215 [Smoothed TC Combined] - Forward/Reverse Separation Plot (Fixed)

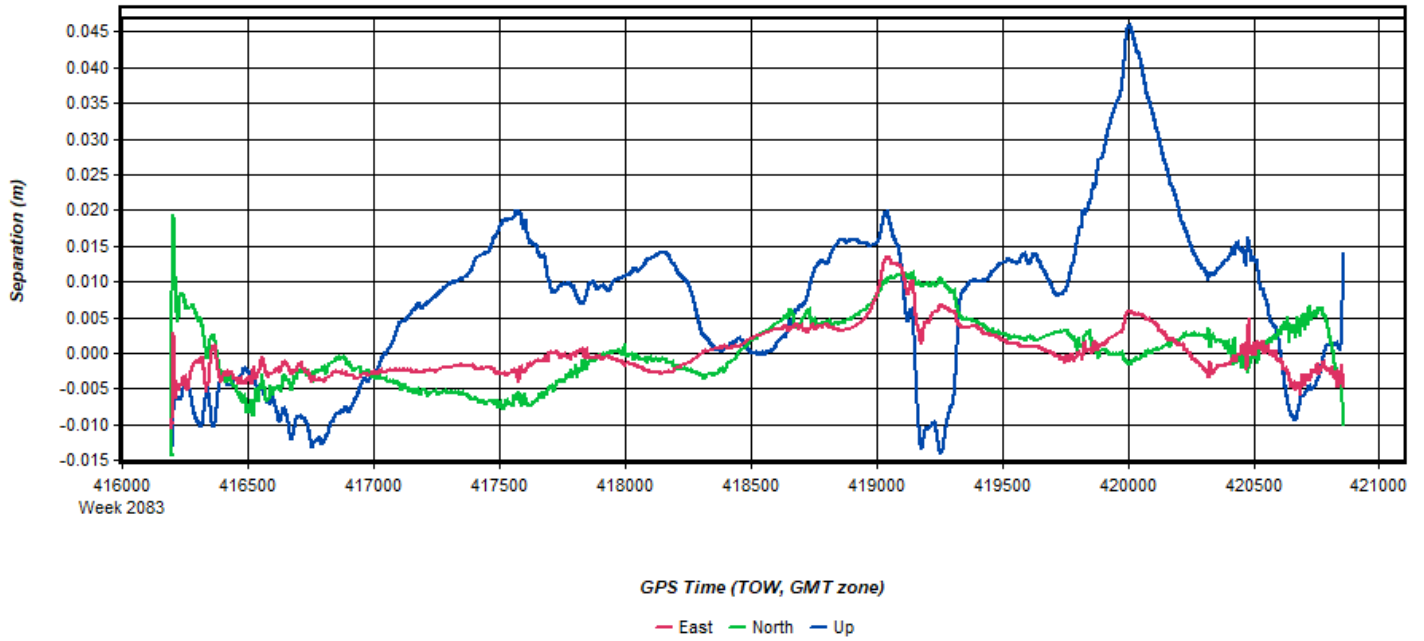


Figure 5: 20191212193215 [Smoothed TC Combined] - Estimated Position Accuracy Plot

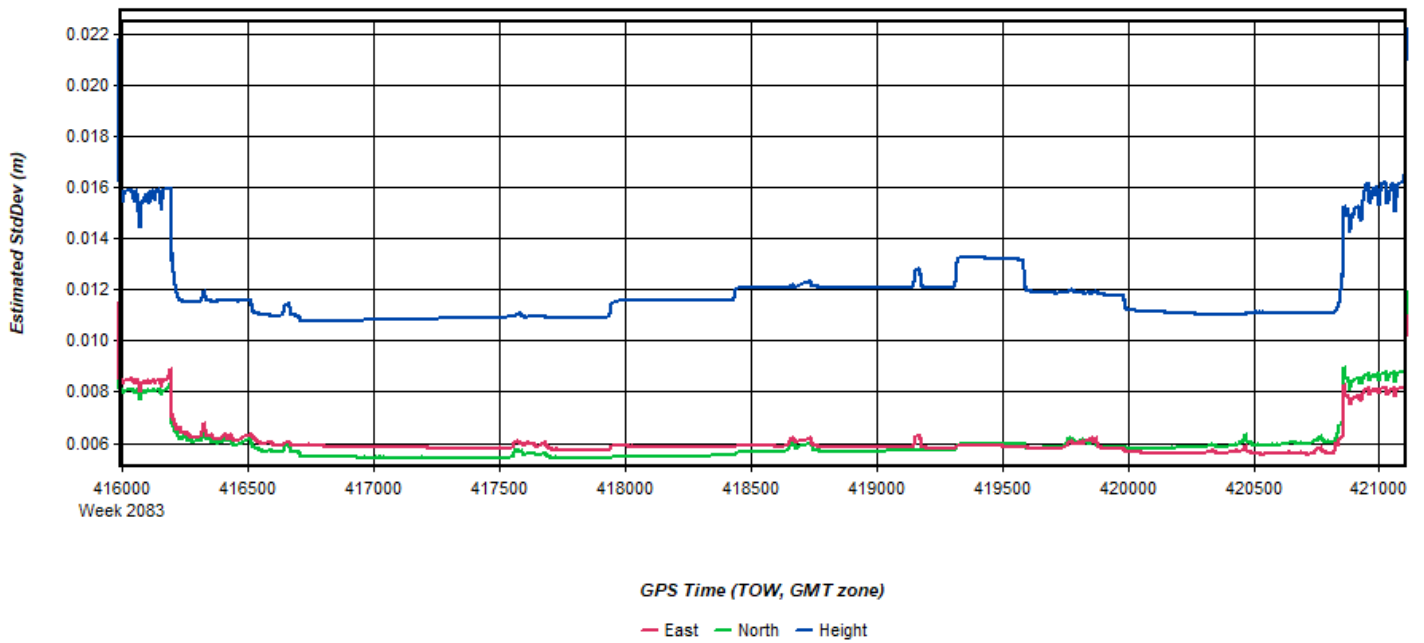


Figure 6: 20191212193215 [Smoothed TC Combined] - PDOP Plot

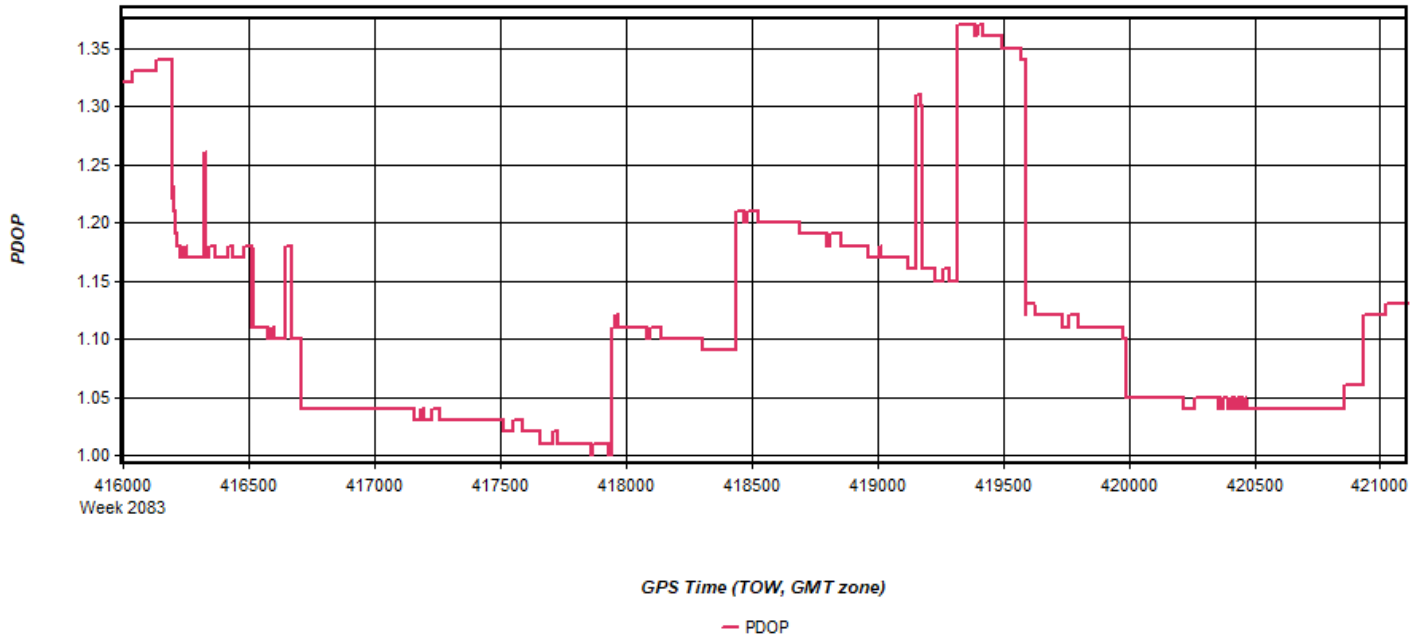


Figure 7: 20191212193215 [Smoothed TC Combined] - Number of Satellites Line Plot

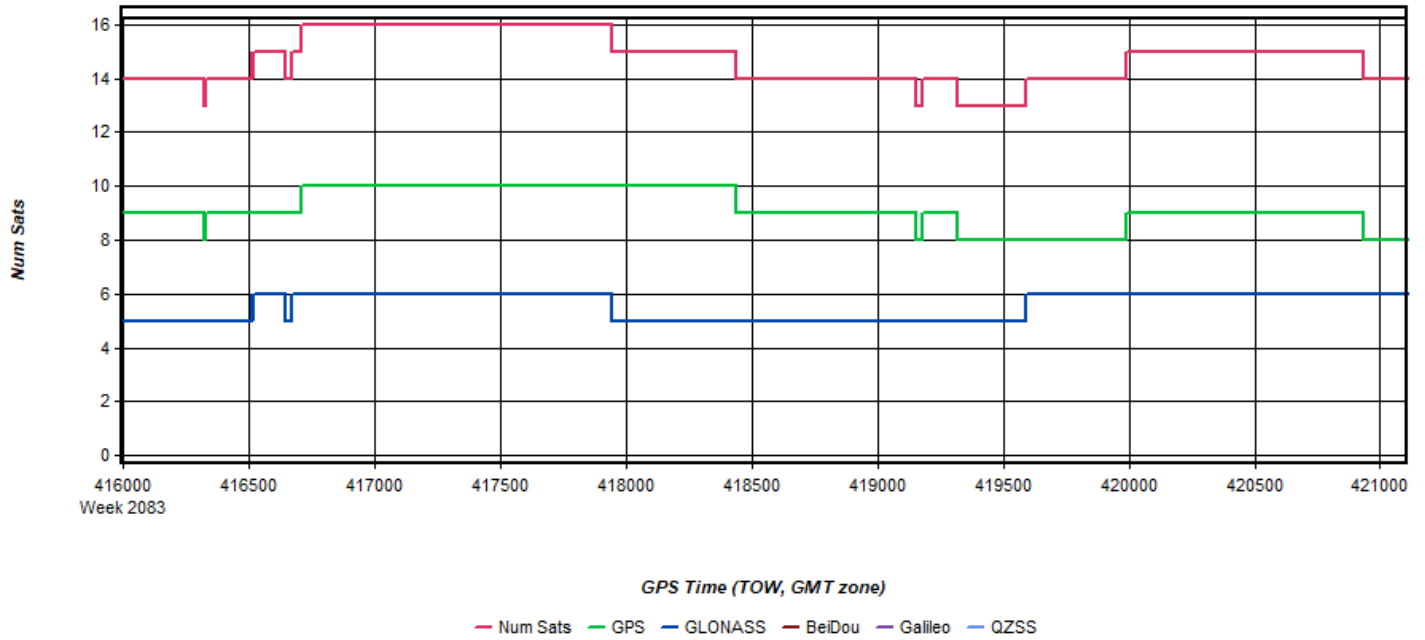


Figure 8: 20191212193215 [Smoothed TC Combined] - Status flag for IMU processing

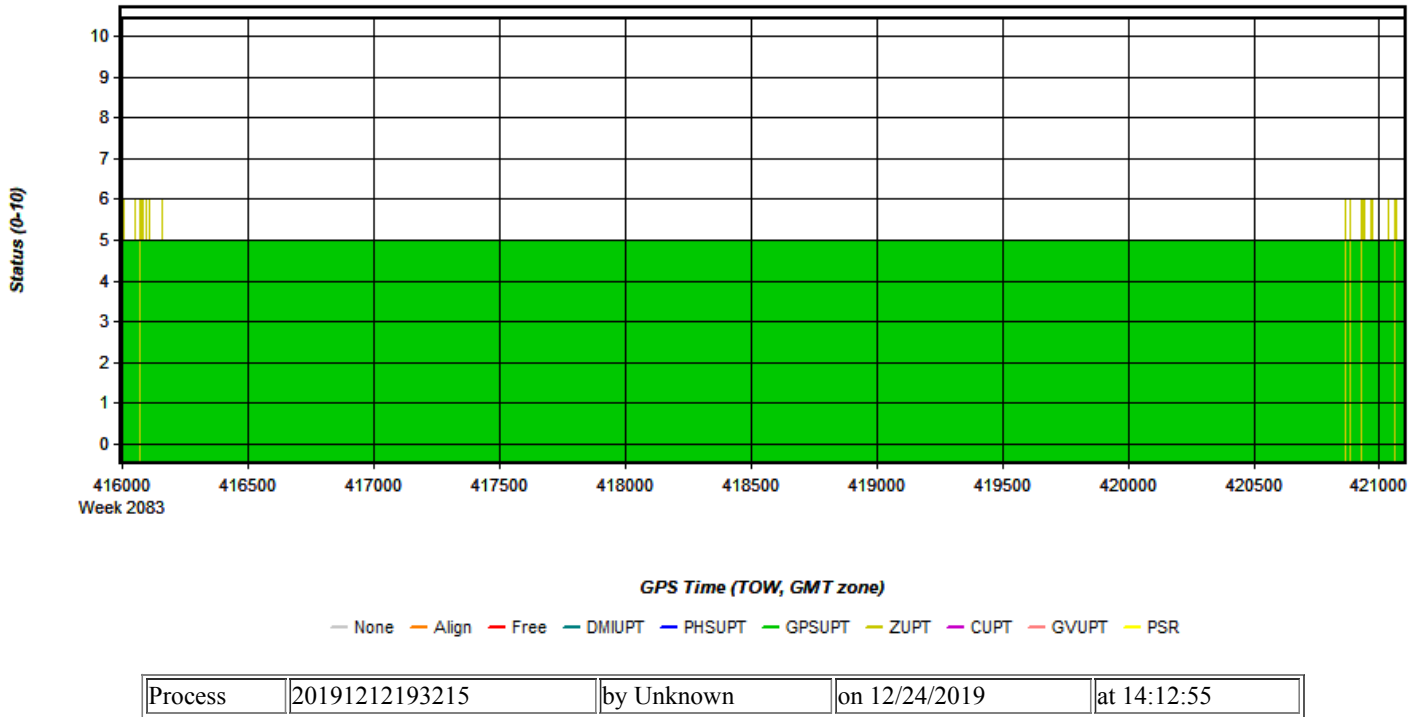


Figure 9: 20191212193215 [Smoothed TC Combined] - Fwd/Rev Attitude Separation Plot

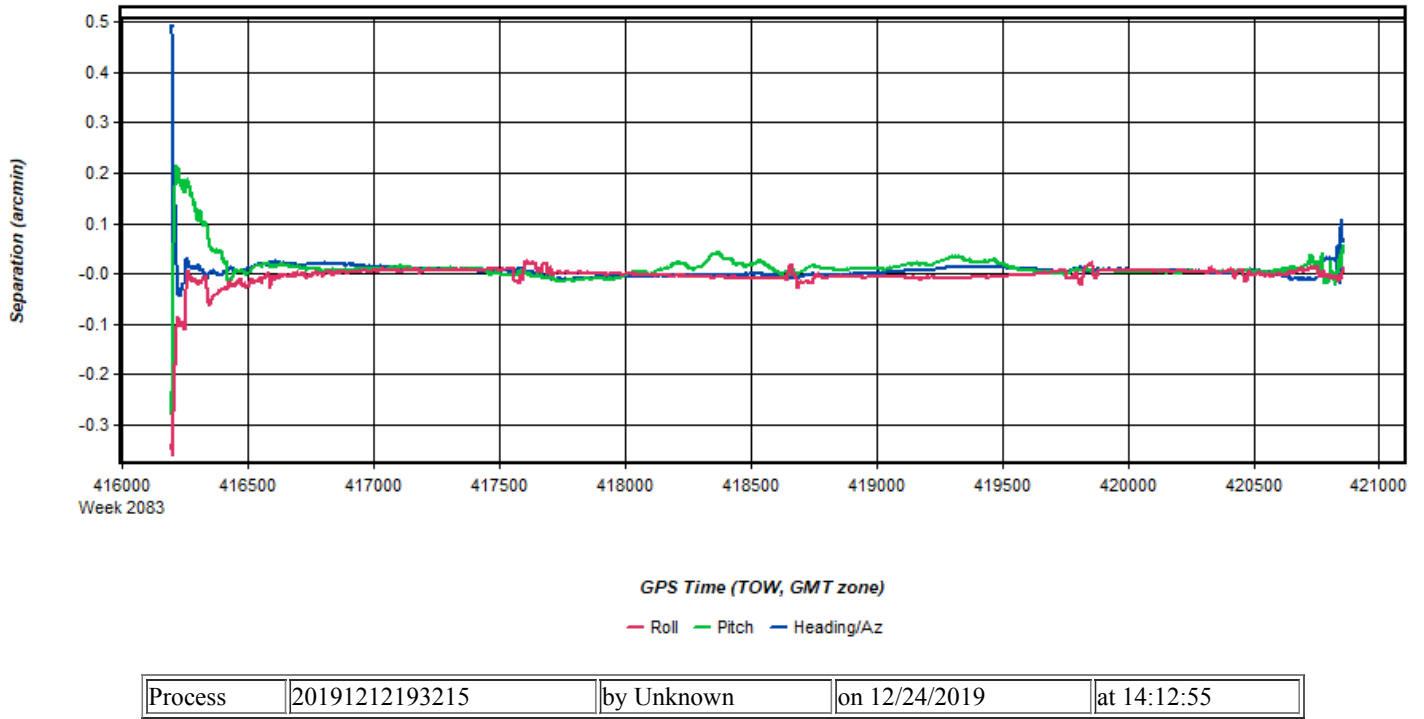
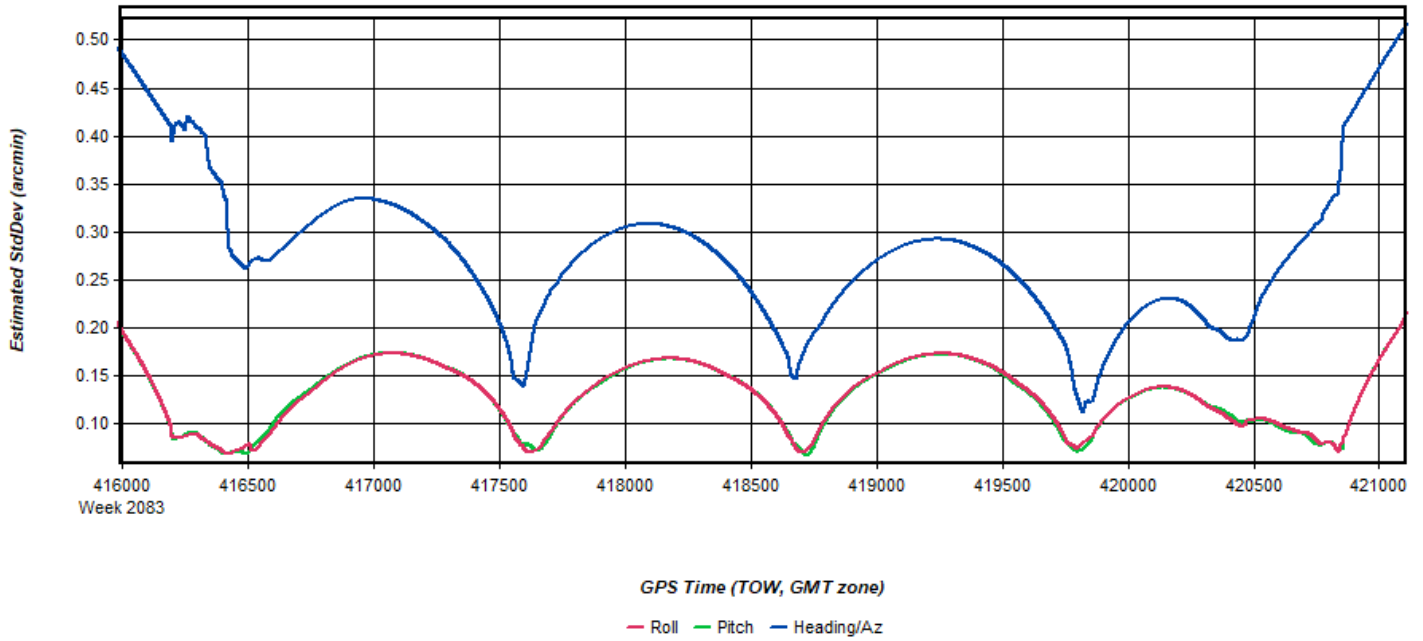
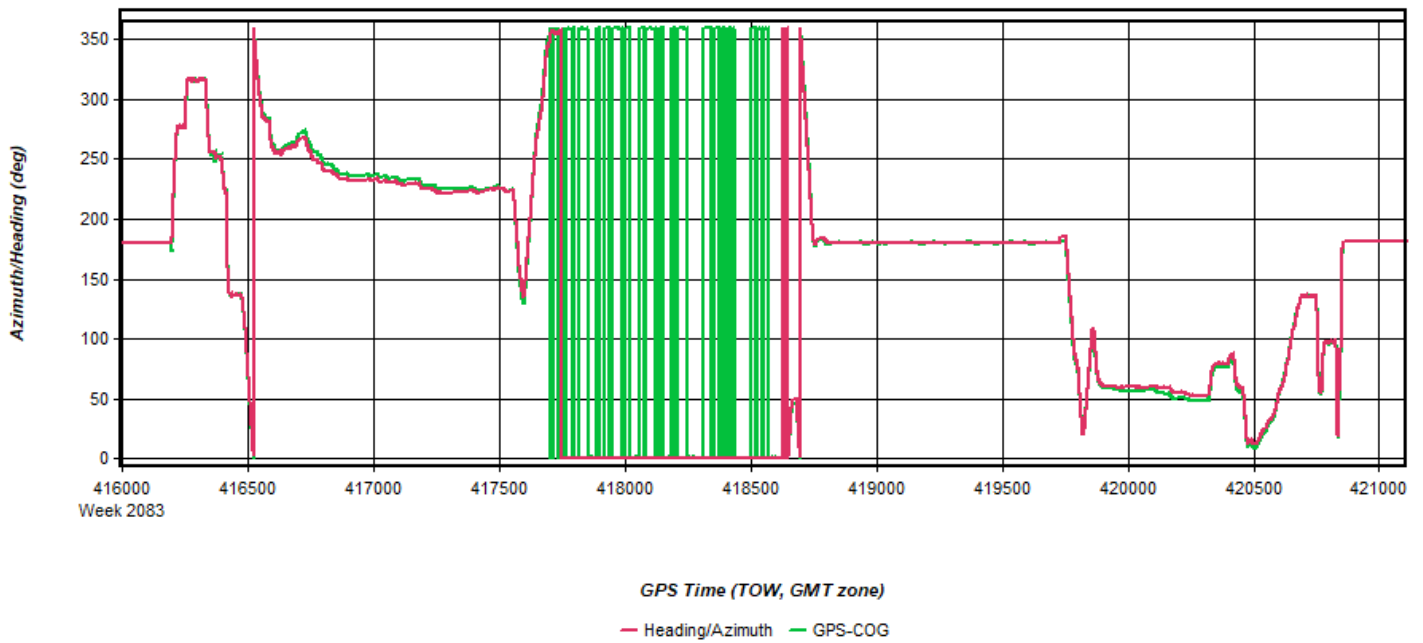


Figure 10: 20191212193215 [Smoothed TC Combined] - Estimated Attitude Accuracy Plot



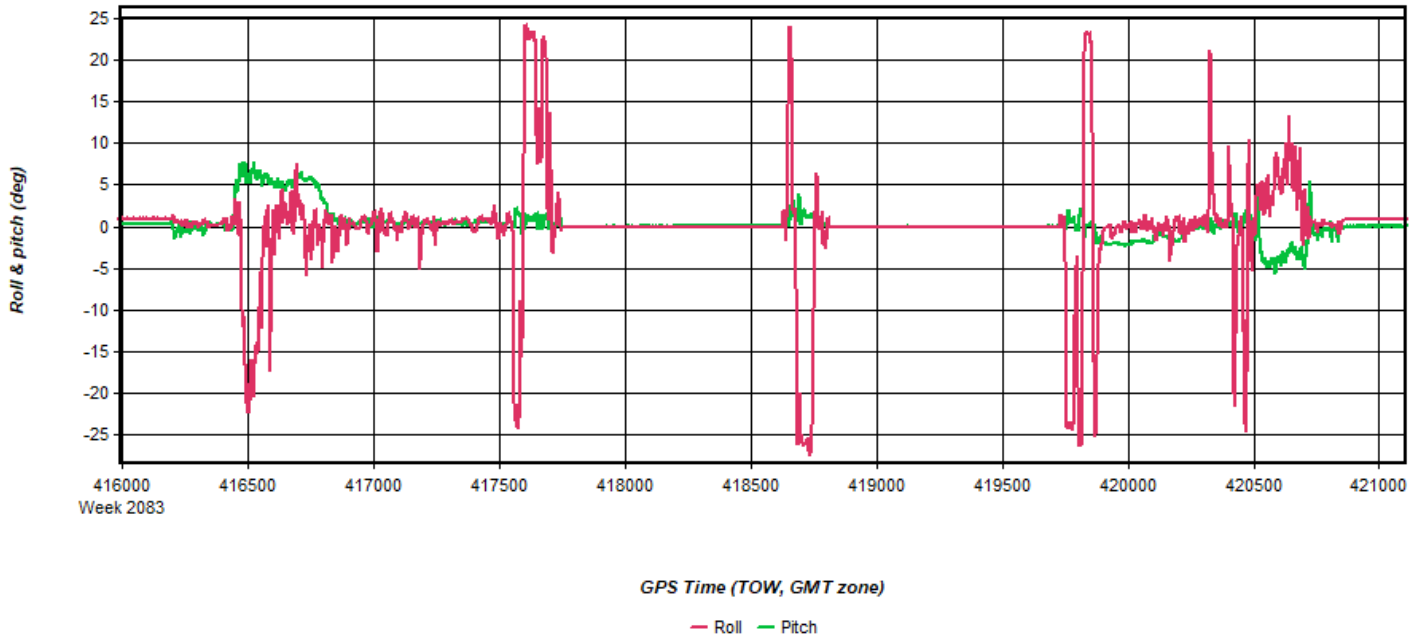
Process	20191212193215	by Unknown	on 12/24/2019	at 14:12:55
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Figure 11: 20191212193215 [Smoothed TC Combined] - Azimuth Plot



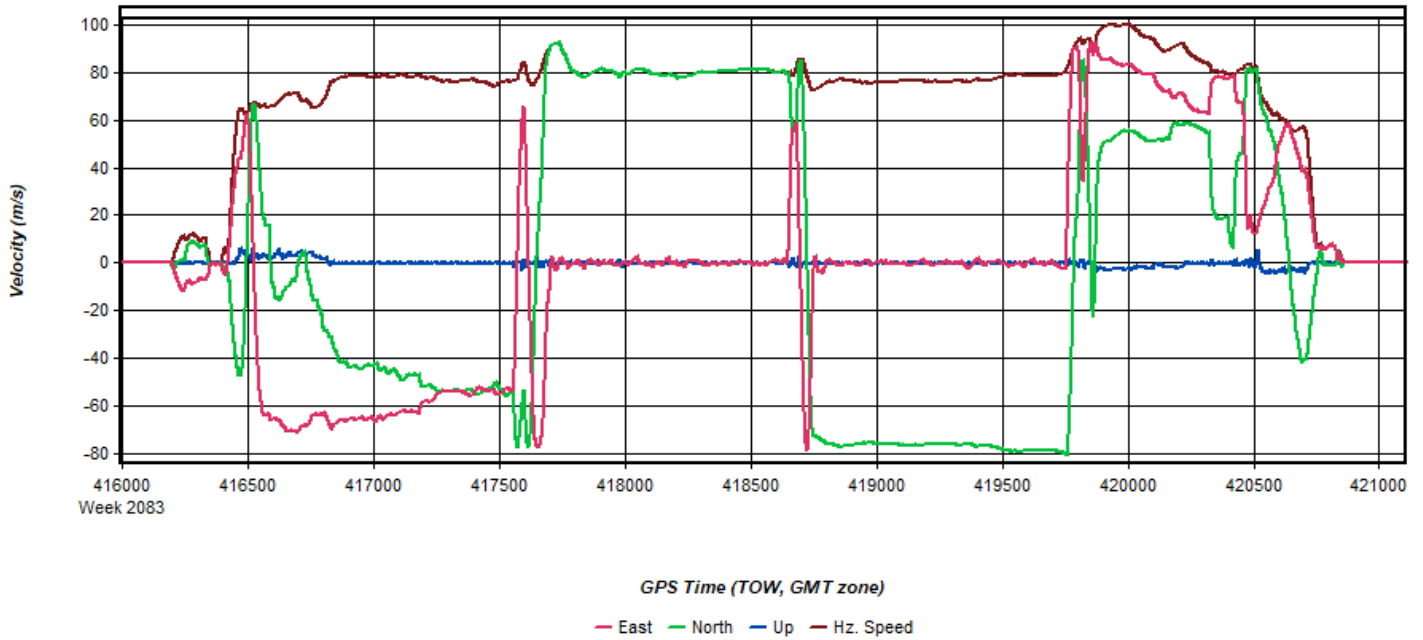
Process	20191212193215	by Unknown	on 12/24/2019	at 14:12:55
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Figure 12: 20191212193215 [Smoothed TC Combined] - Roll & Pitch Plot



Process	20191212193215	by Unknown	on 12/24/2019	at 14:12:55
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Figure 13: 20191212193215 [Smoothed TC Combined] - Velocity Profile Plot



Process	20191212193215	by Unknown	on 12/24/2019	at 14:12:55
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Figure 14: 20191212193215 [Smoothed TC Combined] - Body Frame Velocity Plot

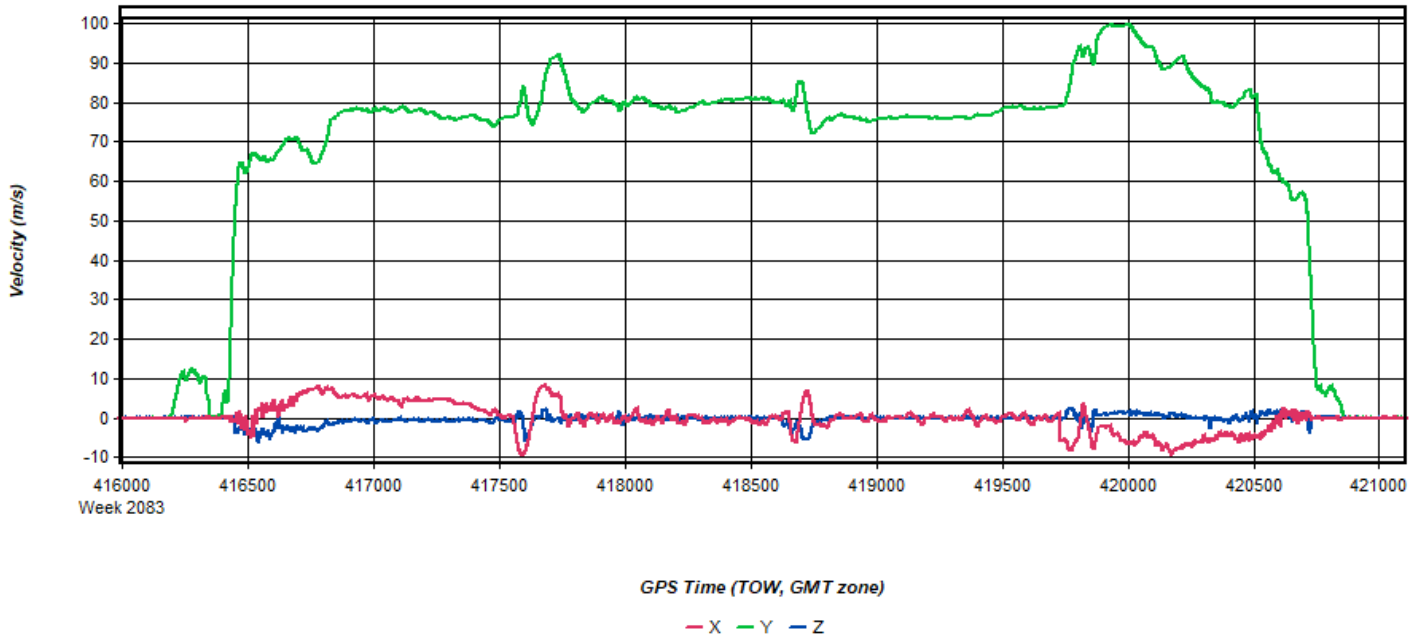


Figure 15: 20191212193215 [Smoothed TC Combined] - Height Profile Plot

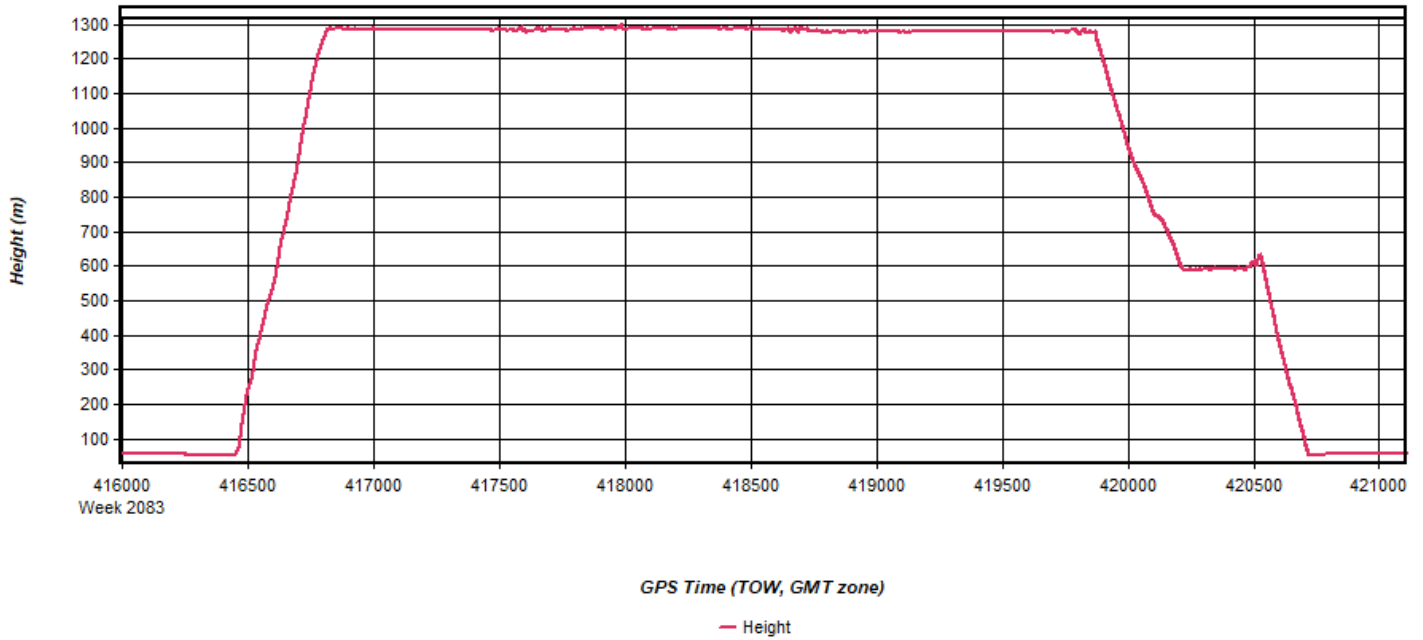


Figure 16: 20191212193215 [Smoothed TC Combined] - C/A Code Residual RMS Plot

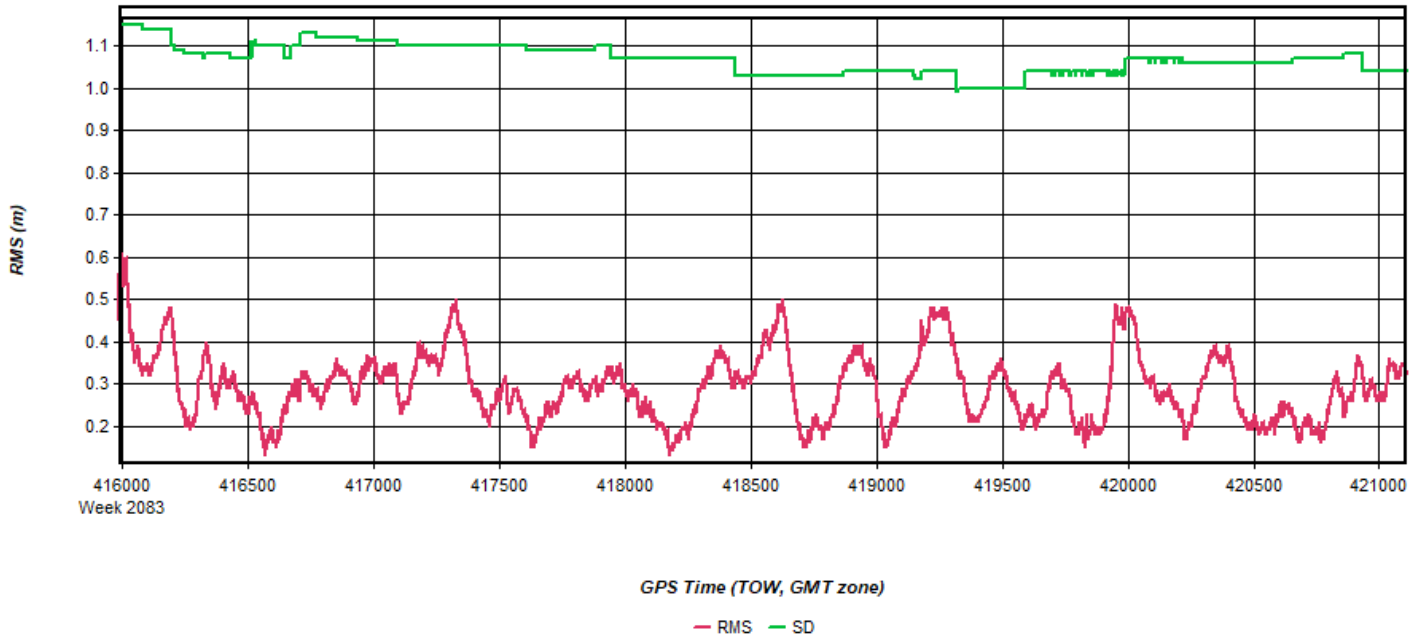


Figure 17: 20191212193215 [Smoothed TC Combined] - Carrier Residual RMS Plot

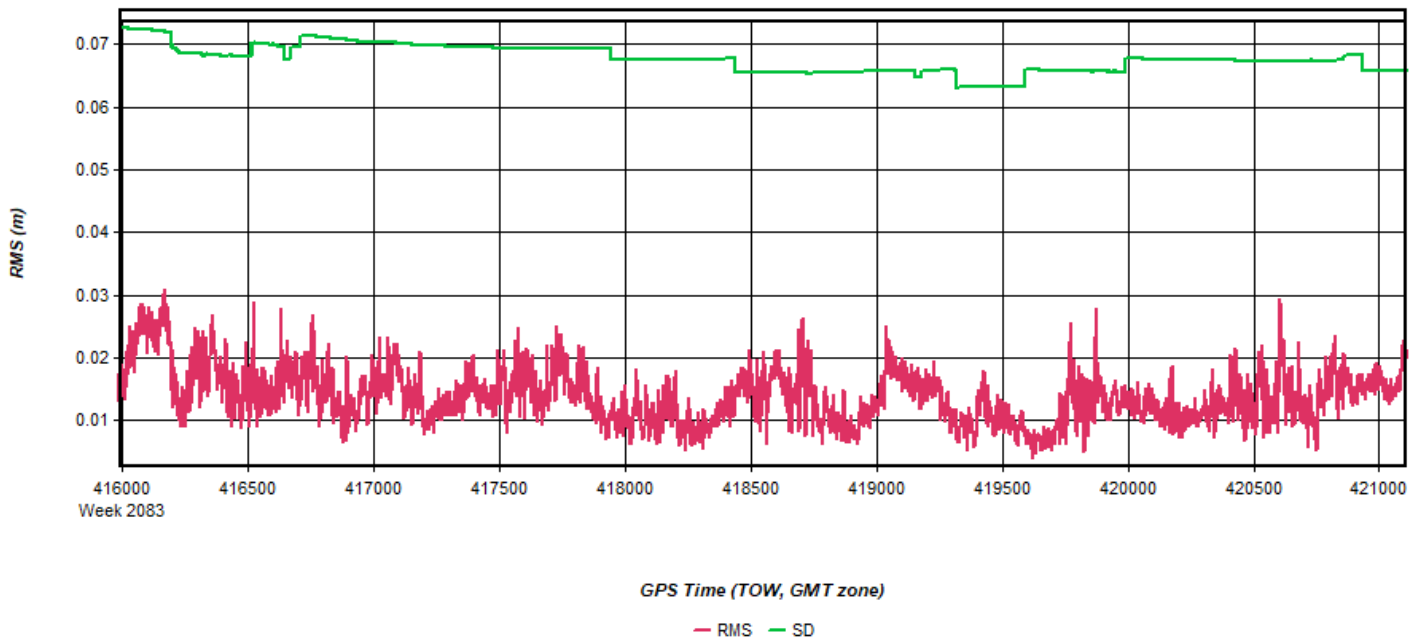
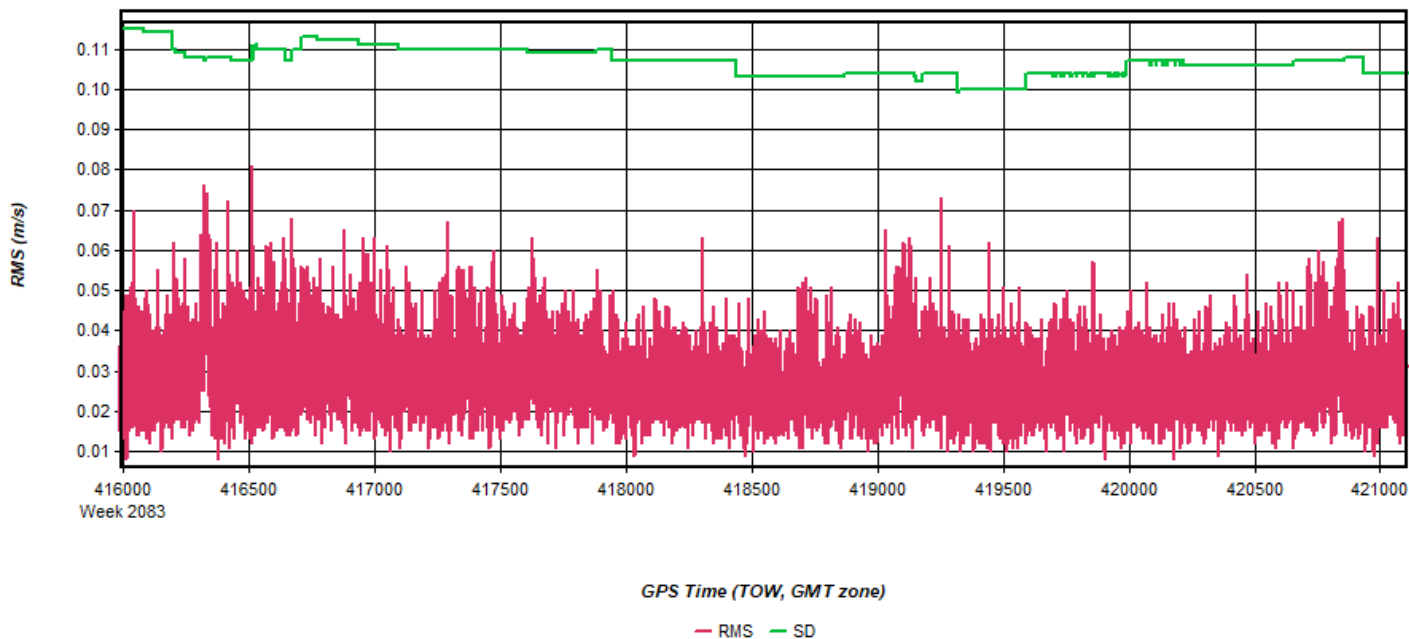
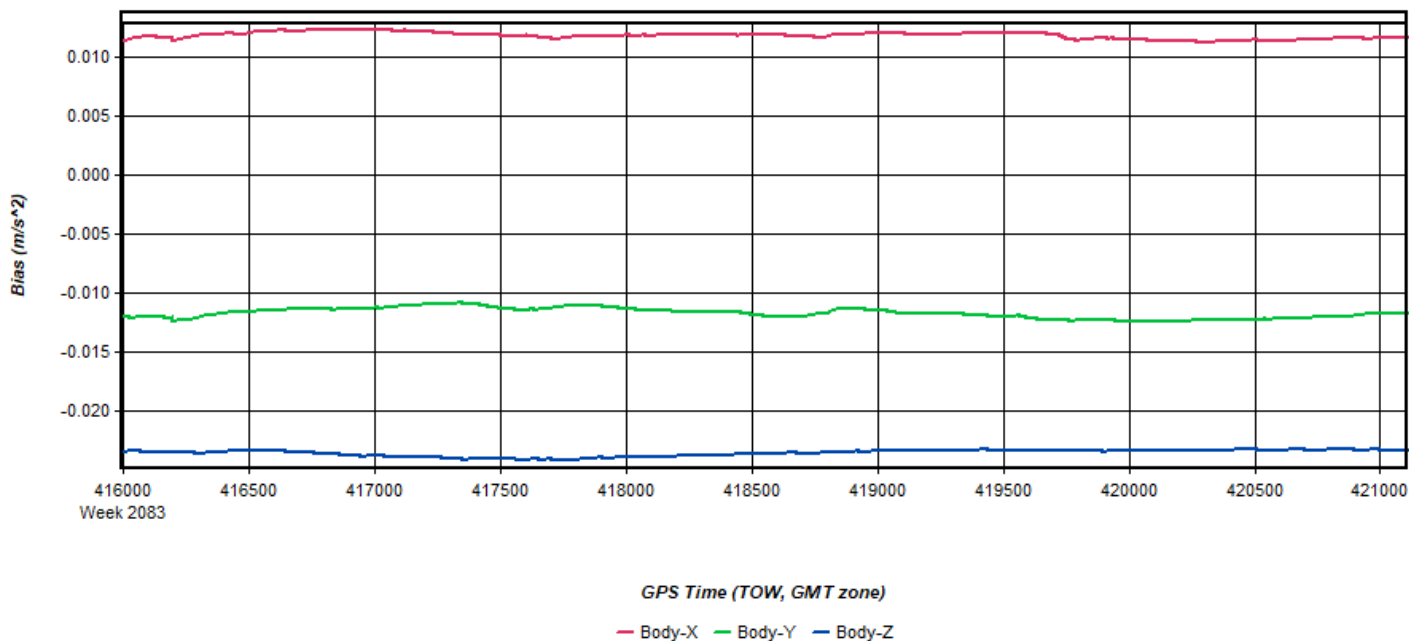


Figure 18: 20191212193215 [Smoothed TC Combined] - L1 Doppler Residual RMS Plot



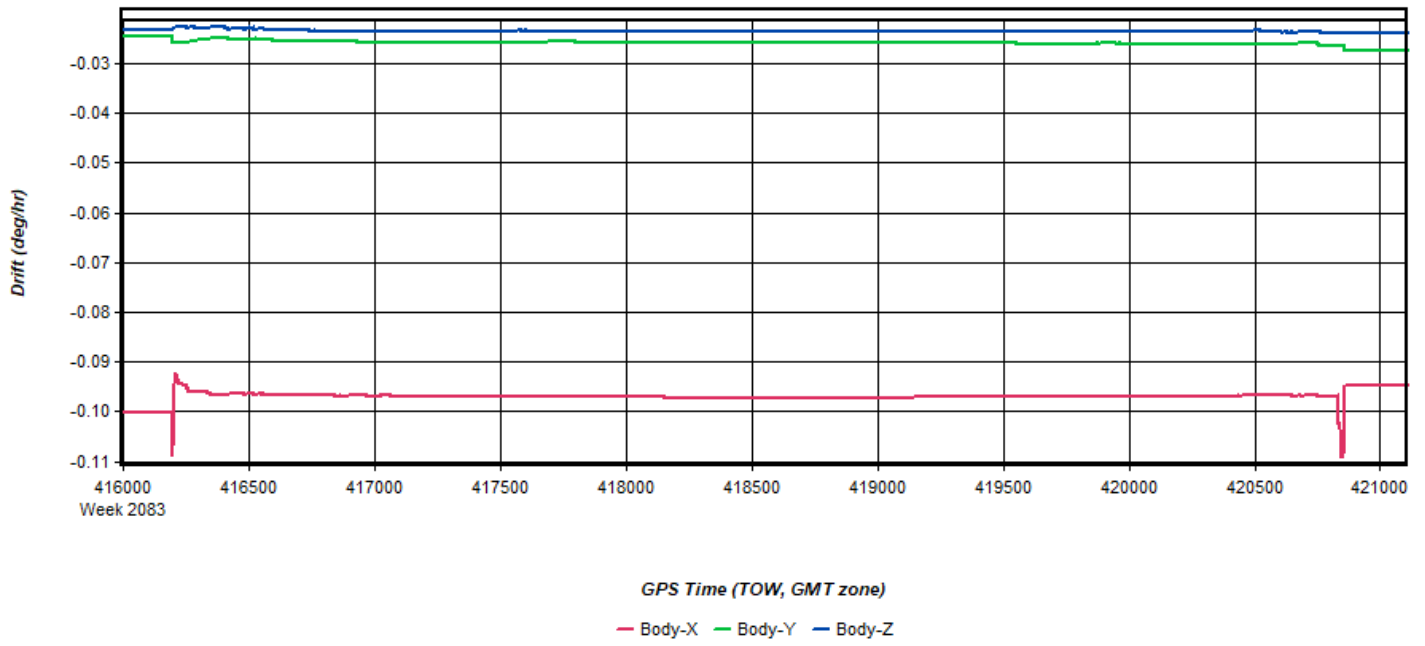
Process	20191212193215	by Unknown	on 12/24/2019	at 14:12:55
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Figure 19: 20191212193215 [Smoothed TC Combined] - Accelerometer Bias Plot



Process	20191212193215	by Unknown	on 12/24/2019	at 14:12:55
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Figure 20: 20191212193215 [Smoothed TC Combined] - Gyro Drift Plot

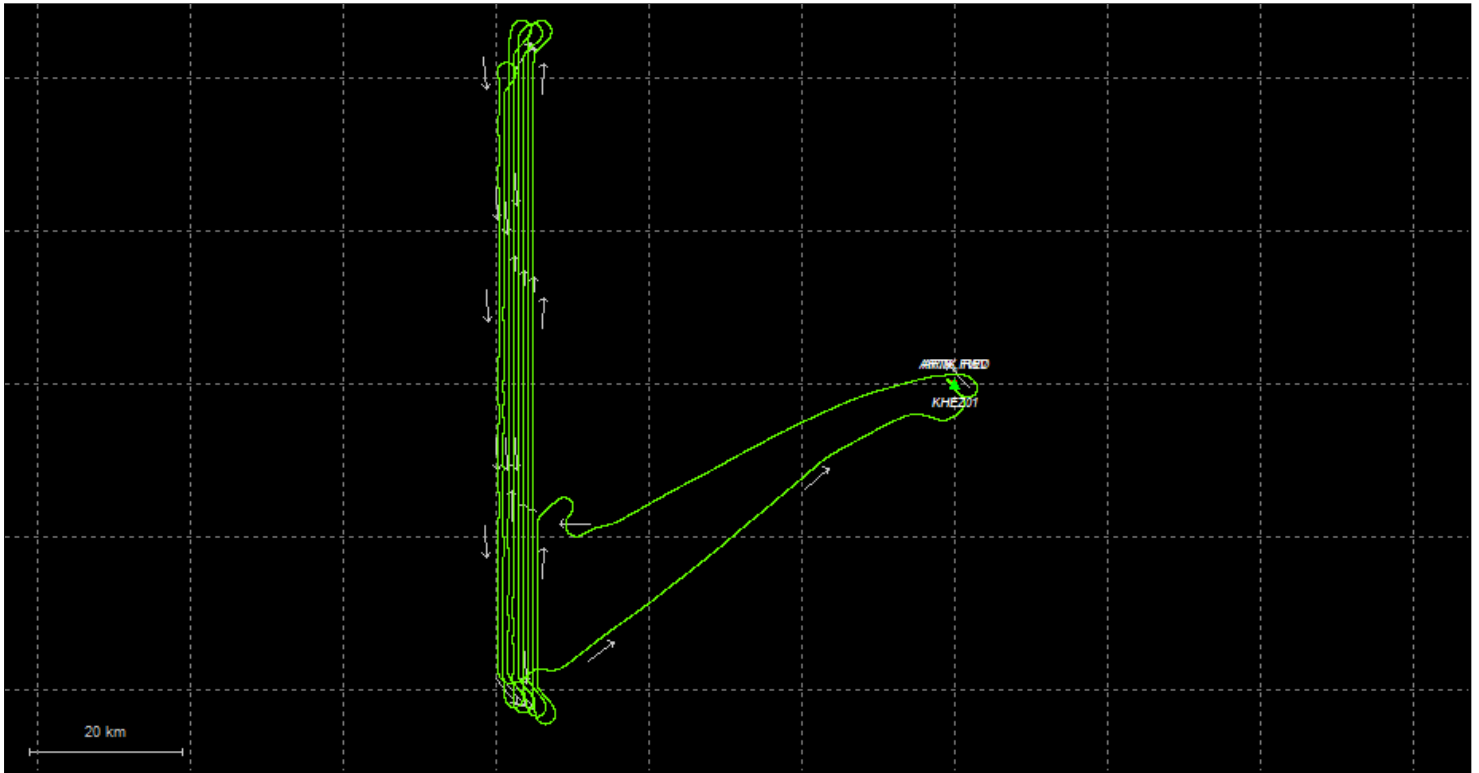


Process	20191212193215	by Unknown	on 12/24/2019	at 14:12:55
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Output Results for 20191214204650

Inertial Explorer Version 8.80.2305
12/24/2019

Figure 1: Smoothed TC Combined - Map



Process	20191214204650	by Unknown	on 12/24/2019	at 15:05:42
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Figure 2: 20191214204650 [Smoothed TC Combined] - Forward/Reverse or Combined Separation Plot

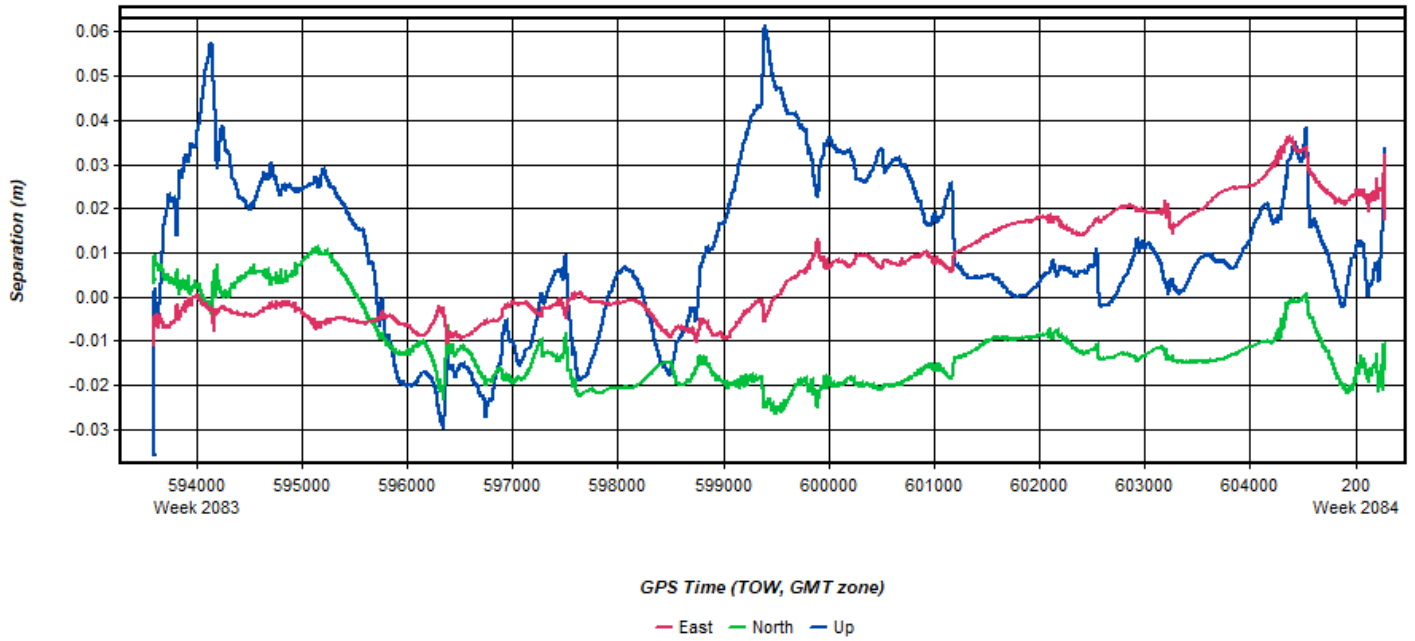


Figure 3: 20191214204650 [Smoothed TC Combined] - Float or Fixed Ambiguity

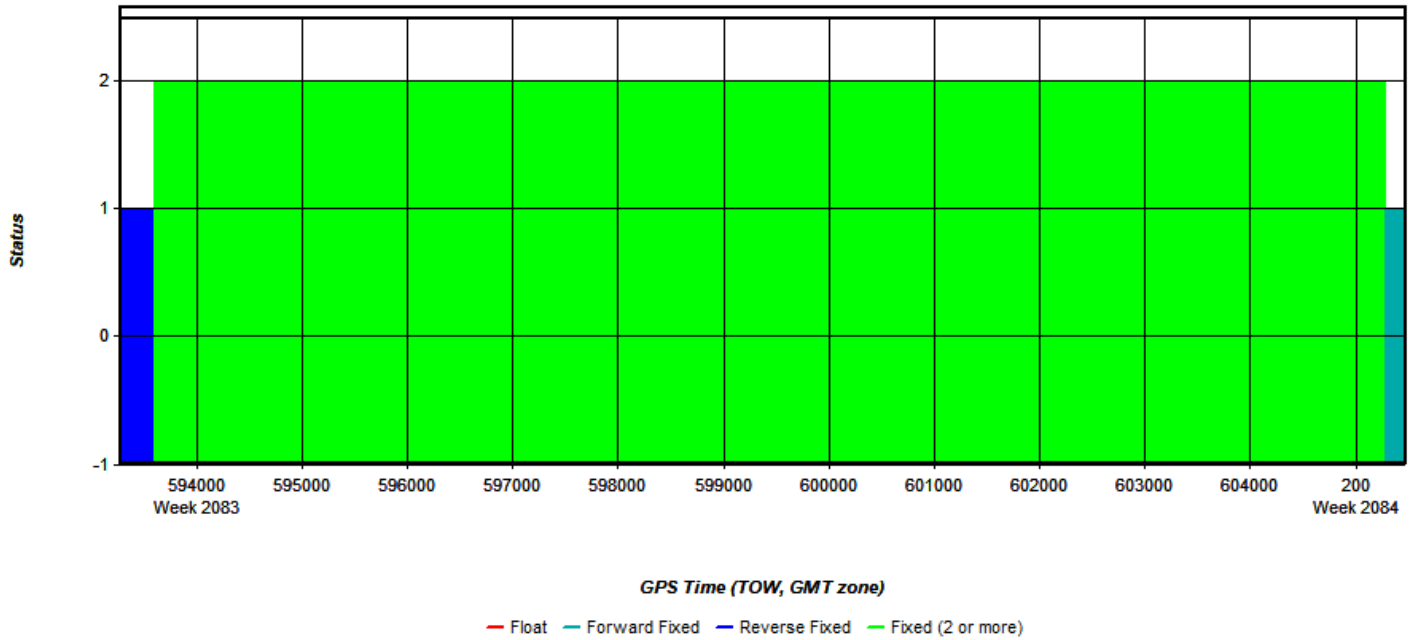


Figure 4: 20191214204650 [Smoothed TC Combined] - Forward/Reverse Separation Plot (Fixed)

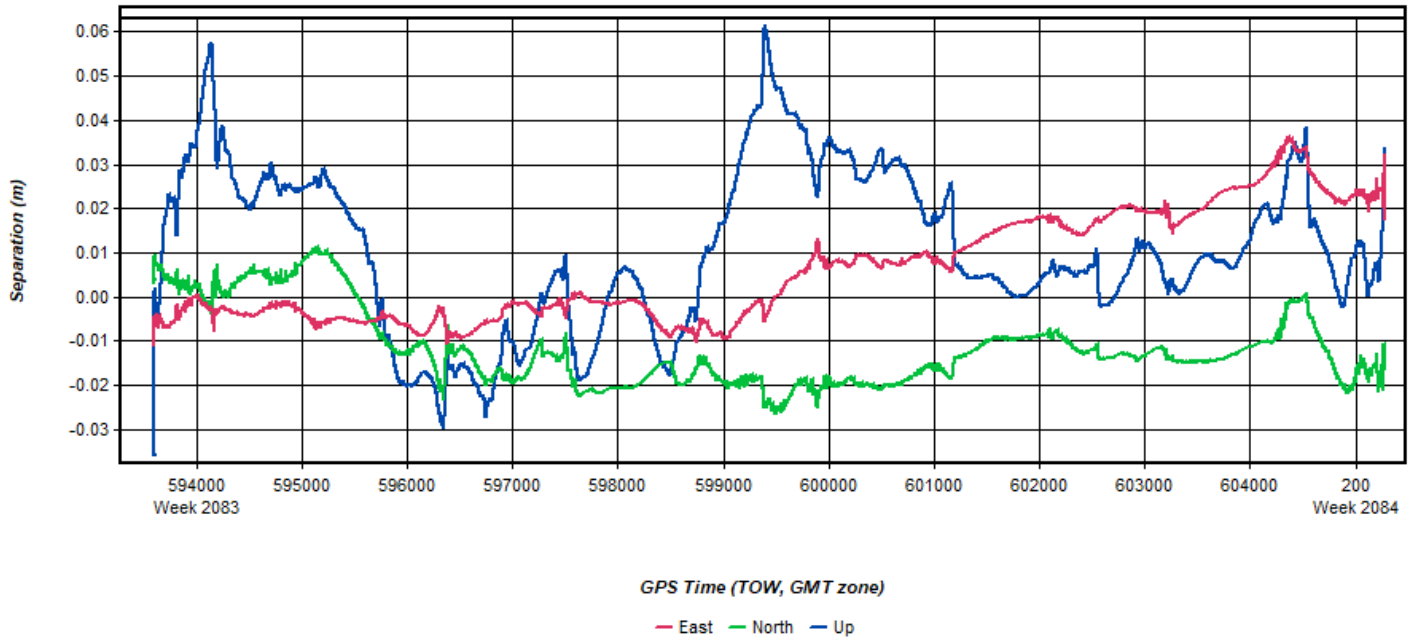


Figure 5: 20191214204650 [Smoothed TC Combined] - Estimated Position Accuracy Plot

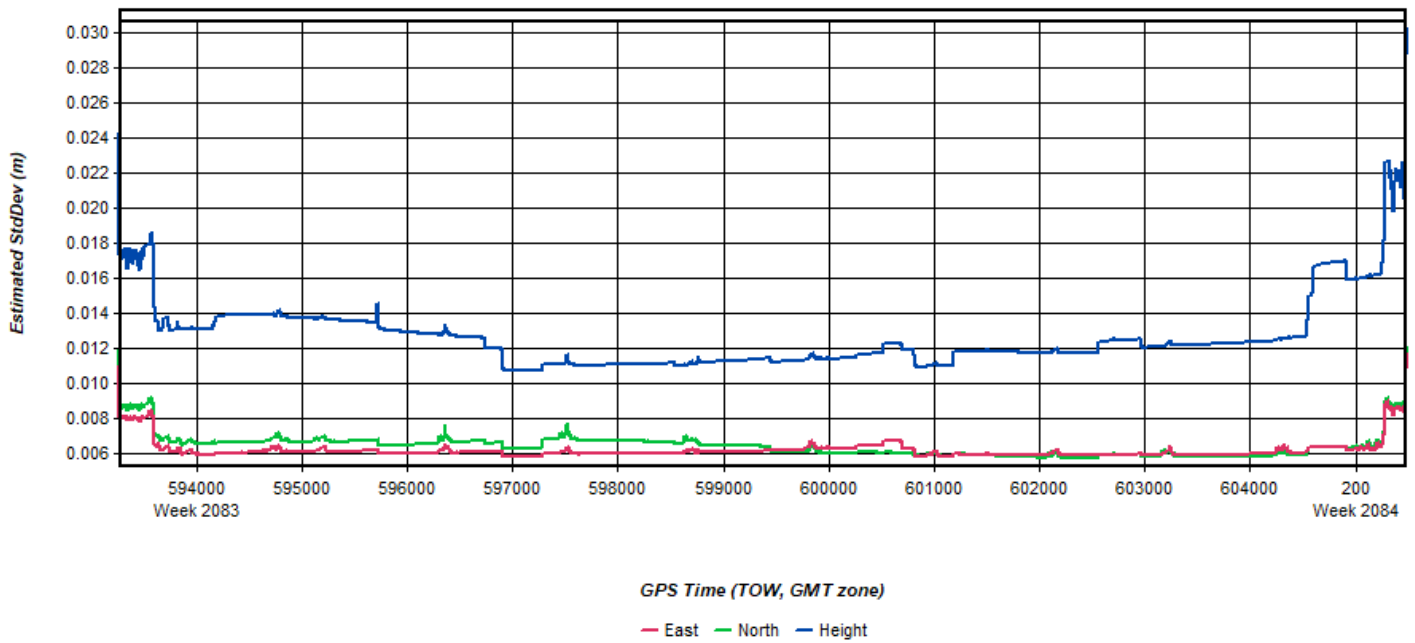
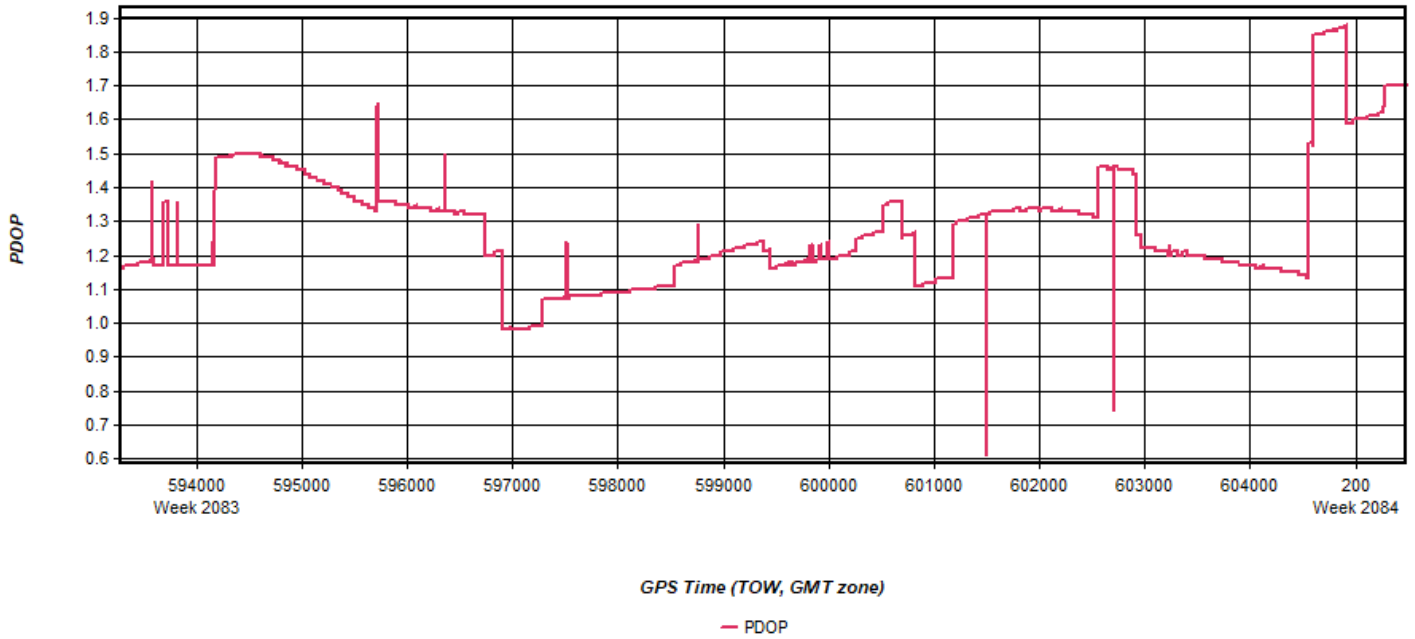
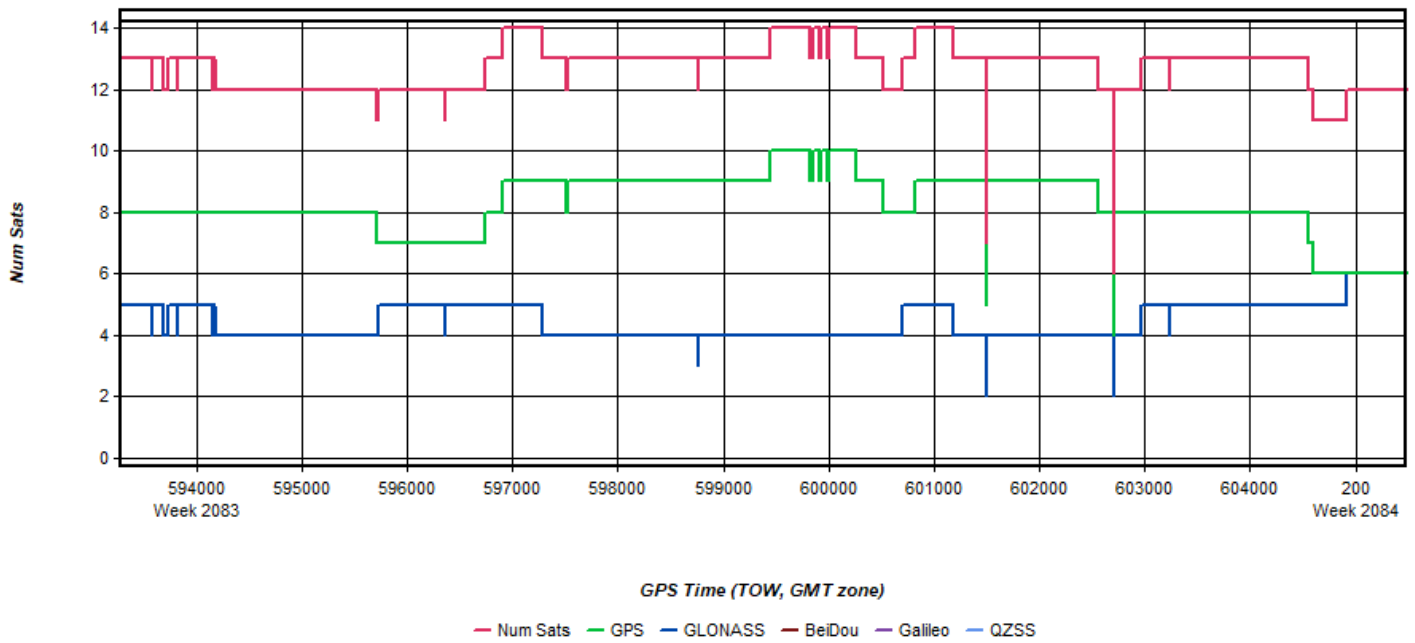


Figure 6: 20191214204650 [Smoothed TC Combined] - PDOP Plot



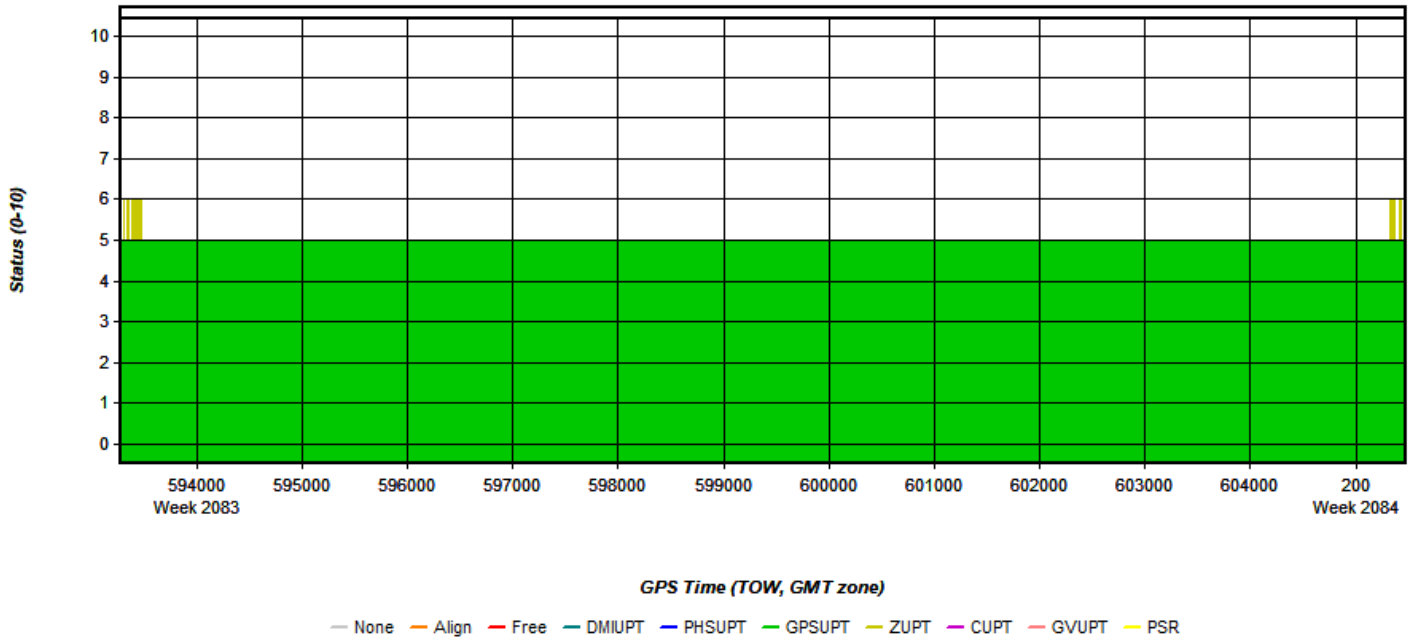
Process	20191214204650	by Unknown	on 12/24/2019	at 15:05:42
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Figure 7: 20191214204650 [Smoothed TC Combined] - Number of Satellites Line Plot



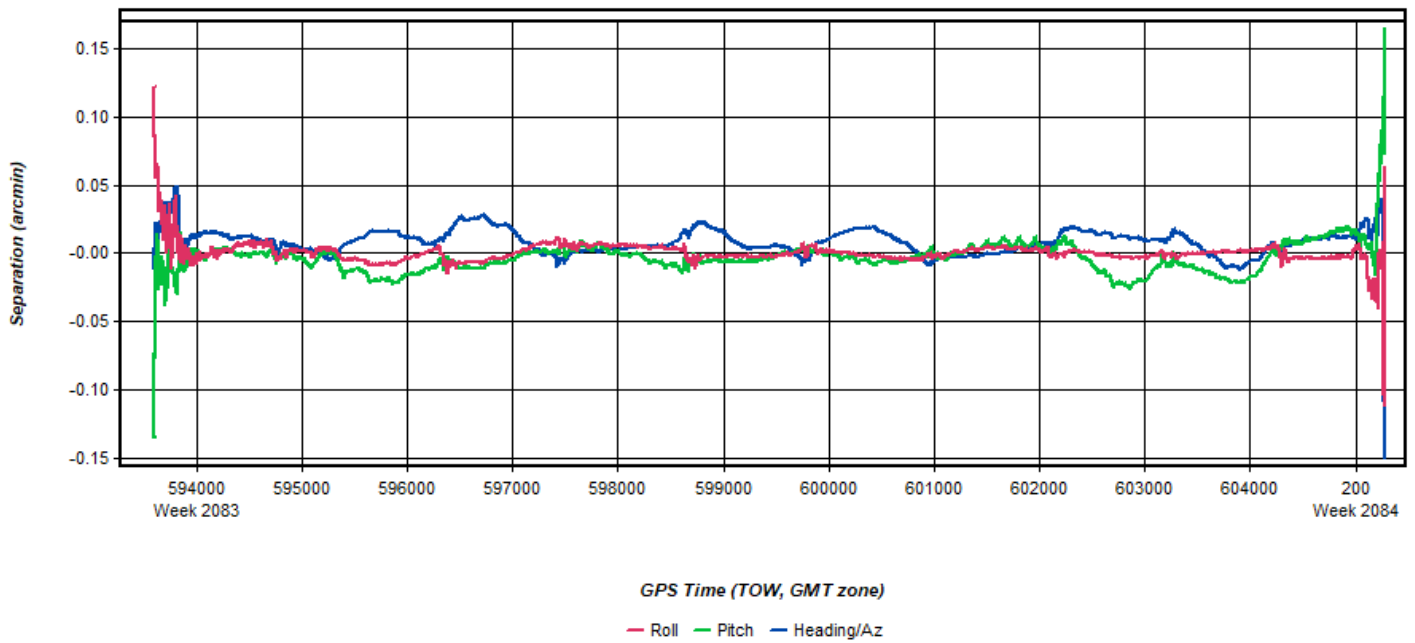
Process	20191214204650	by Unknown	on 12/24/2019	at 15:05:42
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Figure 8: 20191214204650 [Smoothed TC Combined] - Status flag for IMU processing



Process	20191214204650	by Unknown	on 12/24/2019	at 15:05:42
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Figure 9: 20191214204650 [Smoothed TC Combined] - Fwd/Rev Attitude Separation Plot



Process	20191214204650	by Unknown	on 12/24/2019	at 15:05:42
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Figure 10: 20191214204650 [Smoothed TC Combined] - Estimated Attitude Accuracy Plot

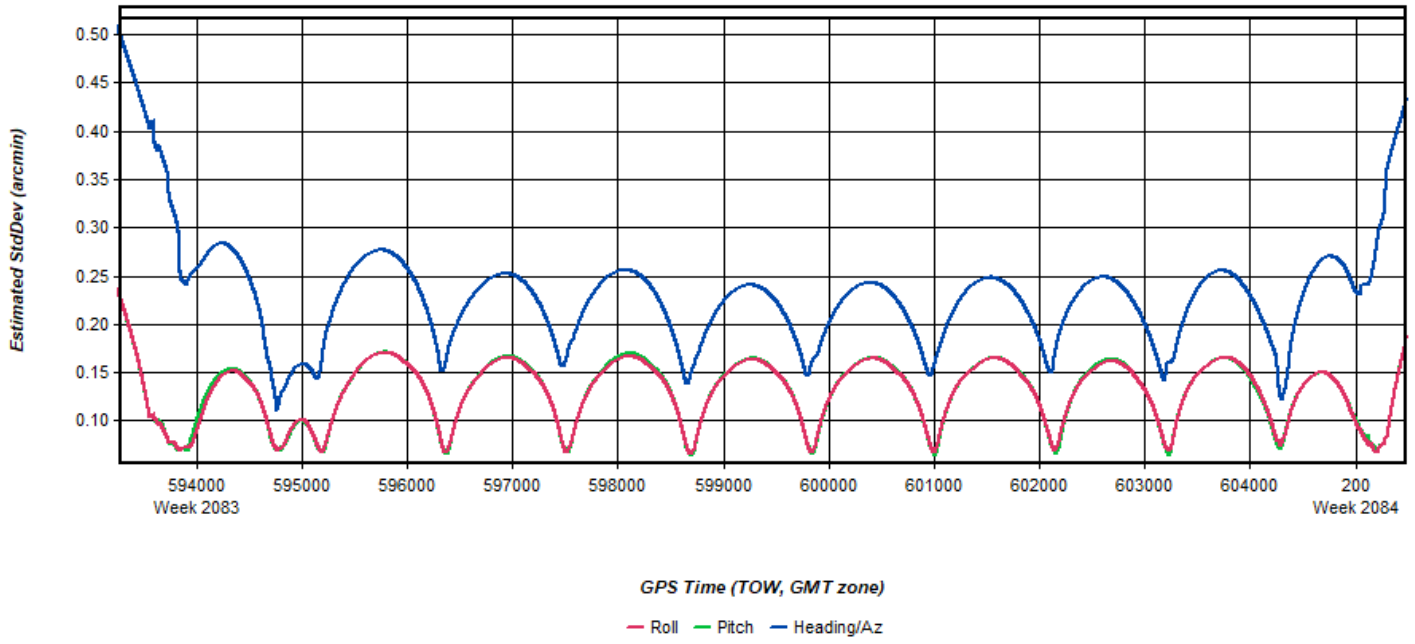


Figure 11: 20191214204650 [Smoothed TC Combined] - Azimuth Plot

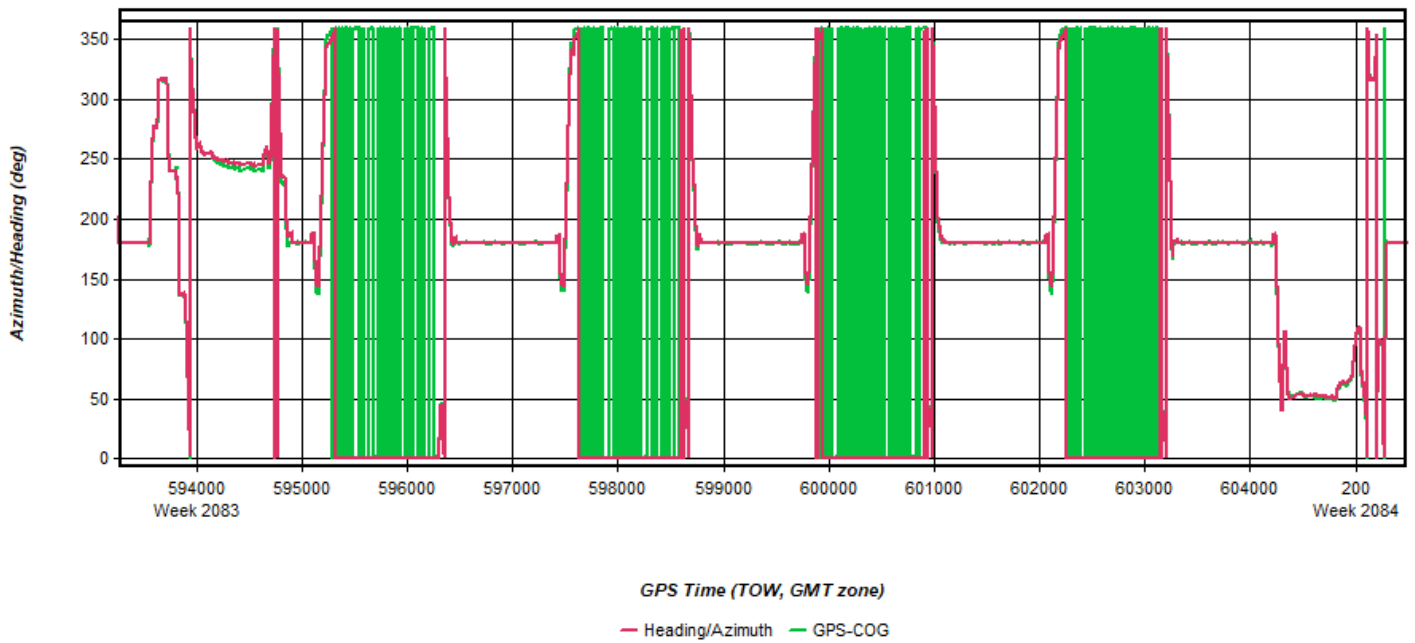
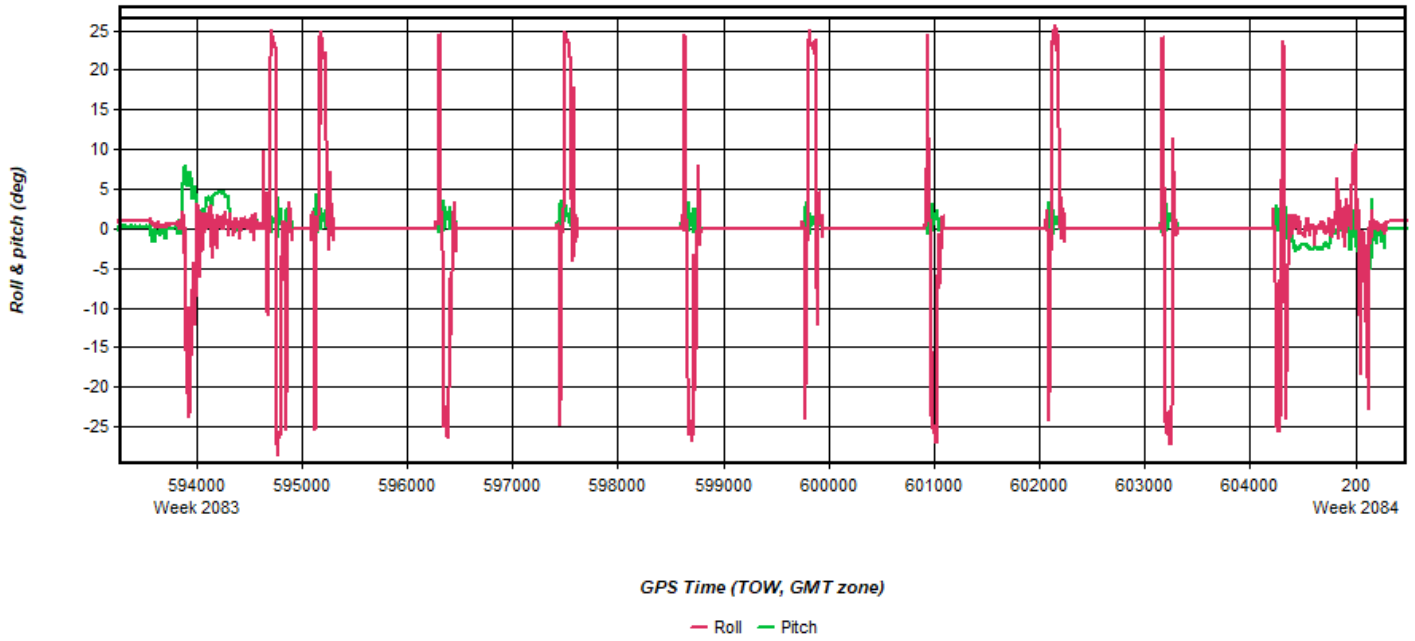
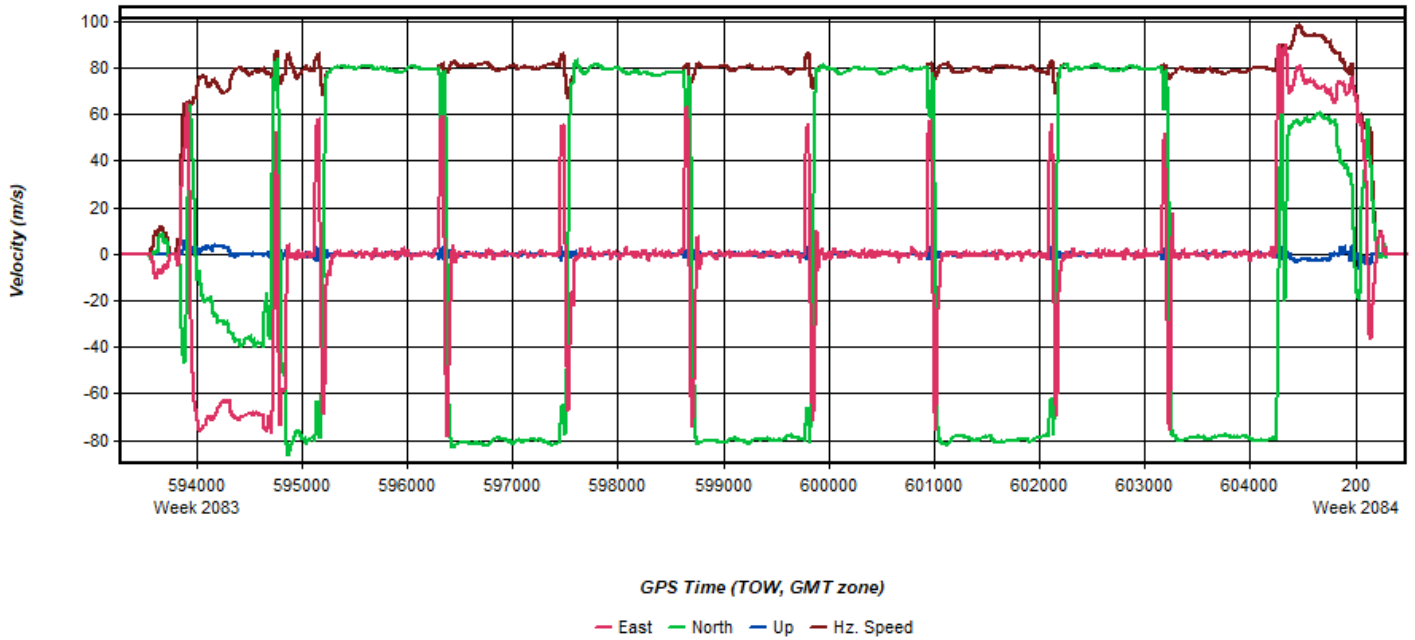


Figure 12: 20191214204650 [Smoothed TC Combined] - Roll & Pitch Plot



Process	20191214204650	by Unknown	on 12/24/2019	at 15:05:42
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Figure 13: 20191214204650 [Smoothed TC Combined] - Velocity Profile Plot



Process	20191214204650	by Unknown	on 12/24/2019	at 15:05:42
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Figure 14: 20191214204650 [Smoothed TC Combined] - Body Frame Velocity Plot

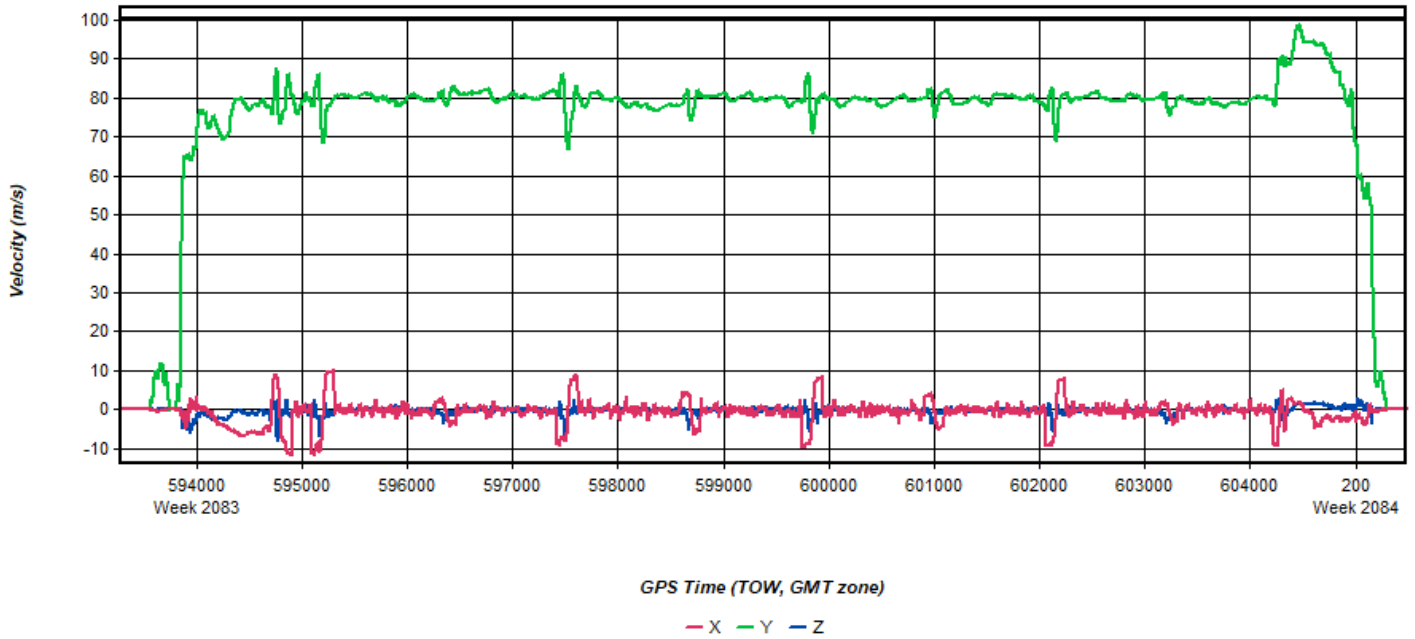


Figure 15: 20191214204650 [Smoothed TC Combined] - Height Profile Plot

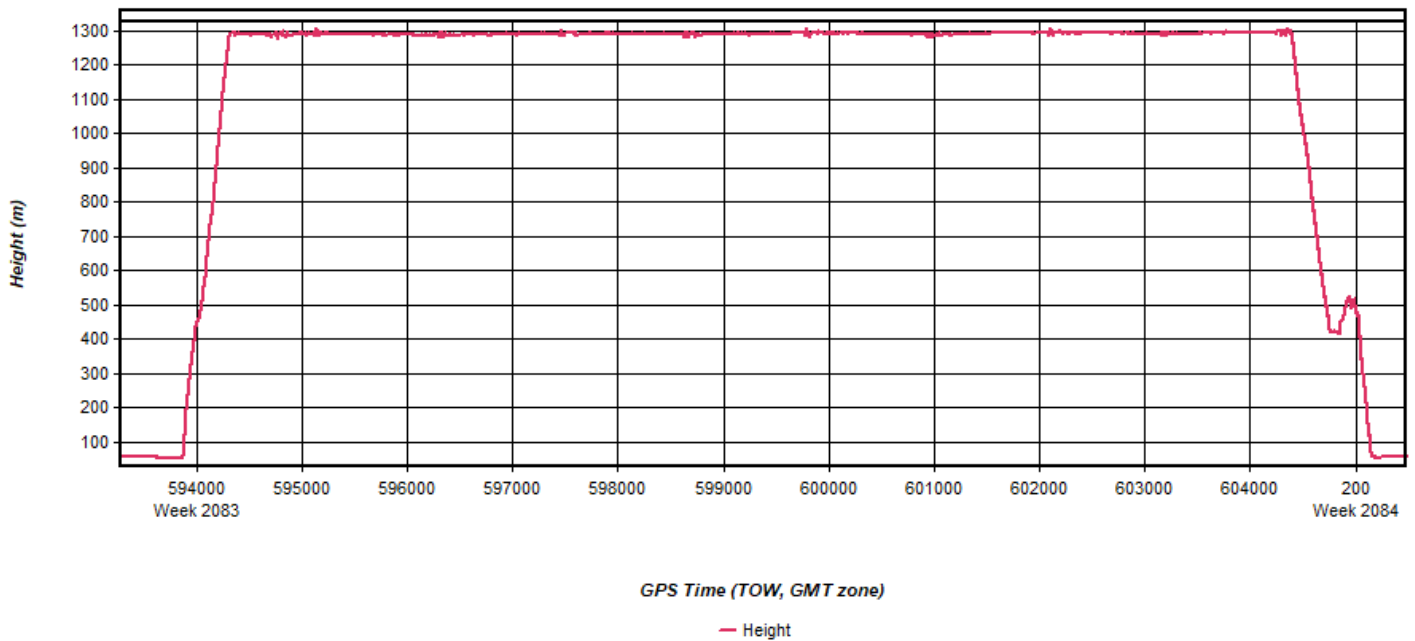


Figure 16: 20191214204650 [Smoothed TC Combined] - C/A Code Residual RMS Plot

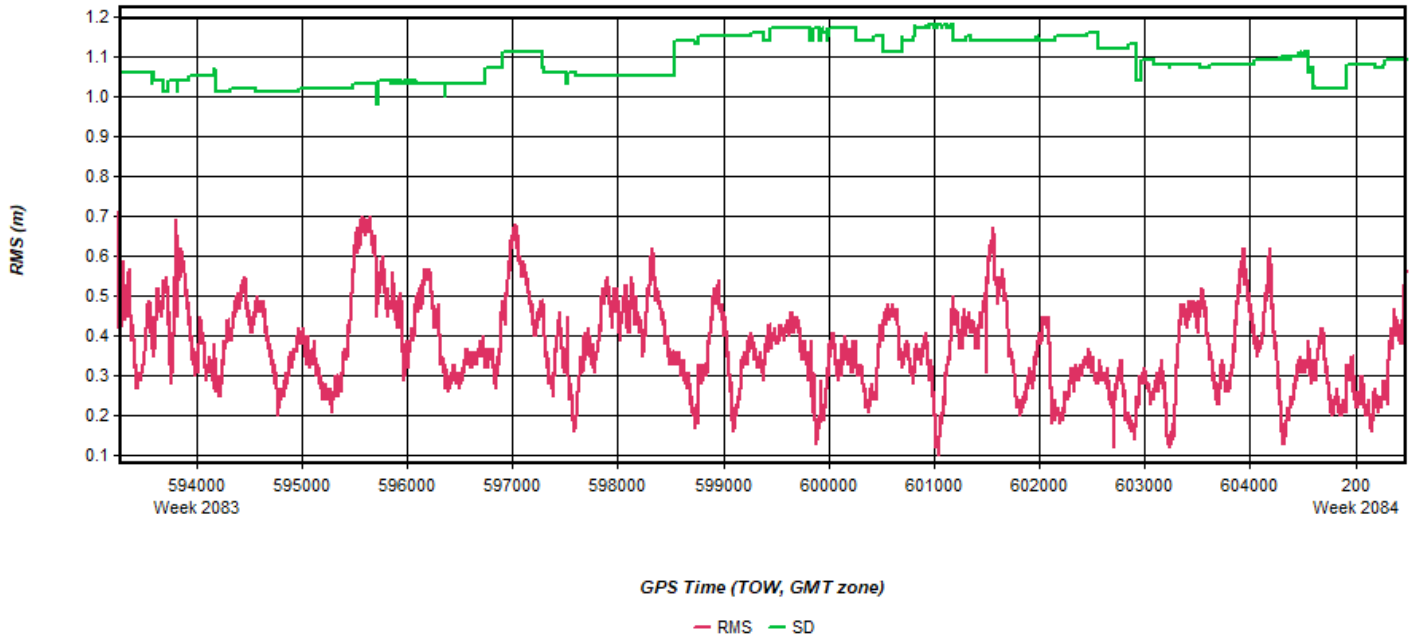


Figure 17: 20191214204650 [Smoothed TC Combined] - Carrier Residual RMS Plot

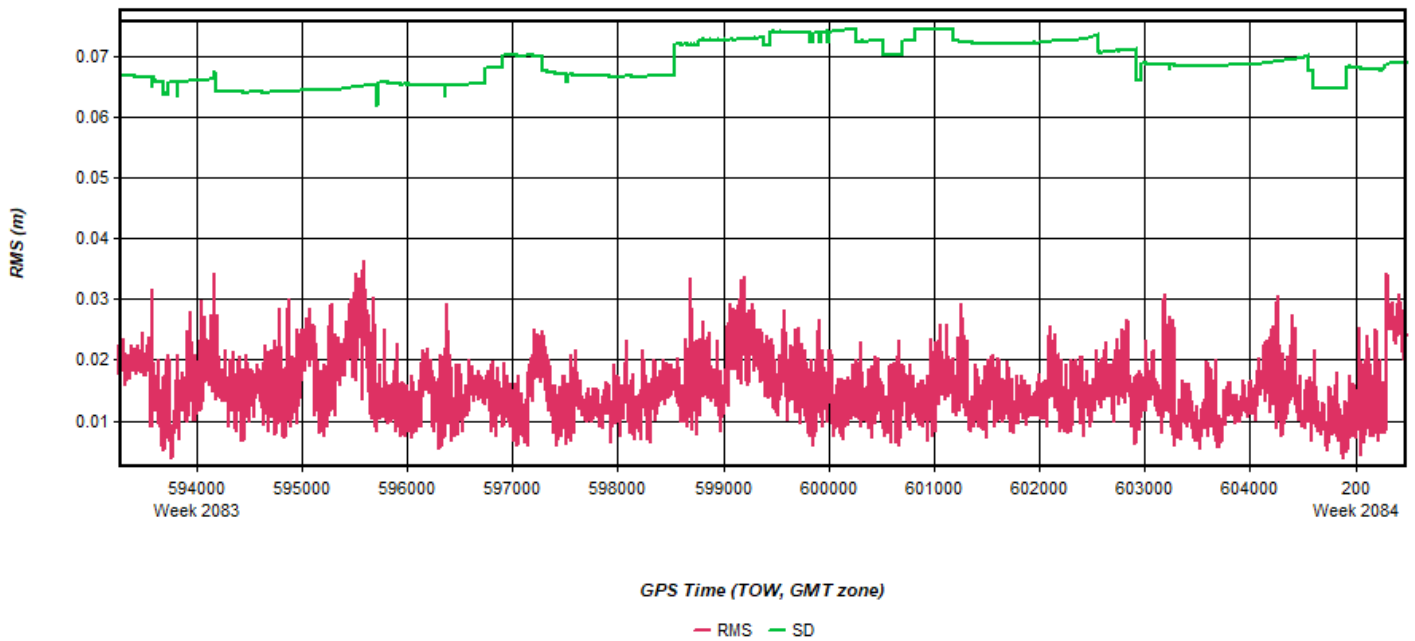


Figure 18: 20191214204650 [Smoothed TC Combined] - L1 Doppler Residual RMS Plot

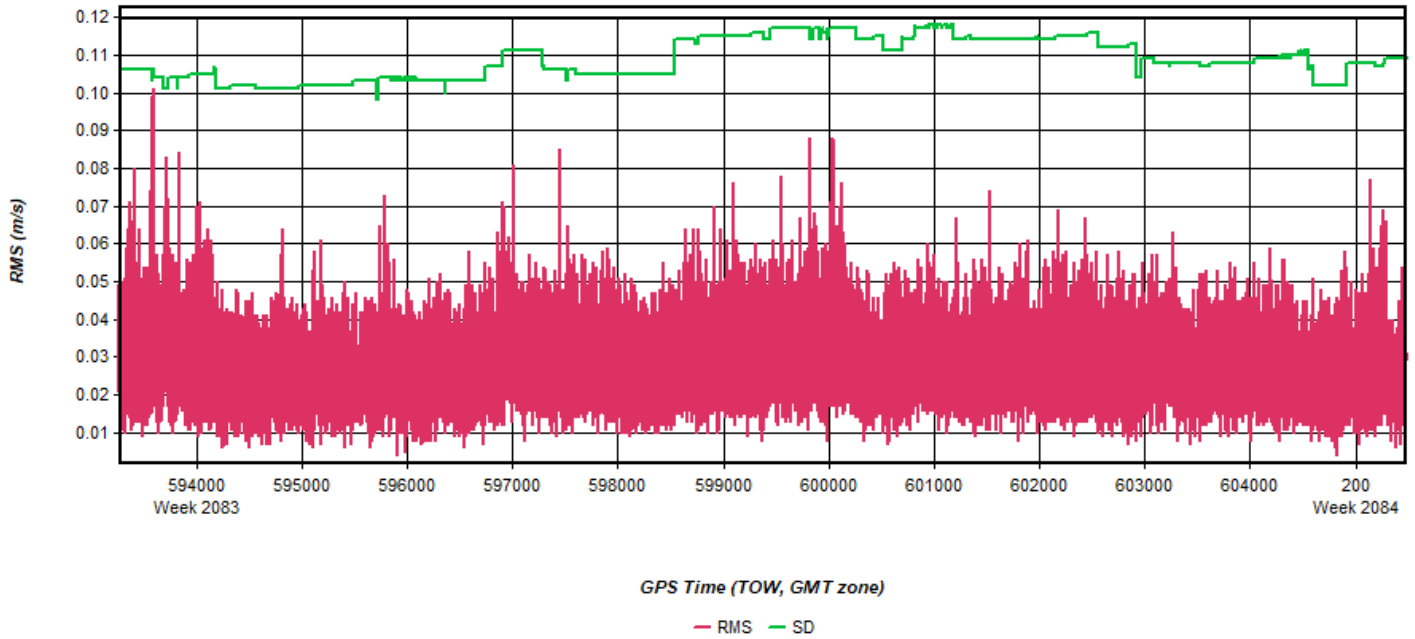


Figure 19: 20191214204650 [Smoothed TC Combined] - Accelerometer Bias Plot

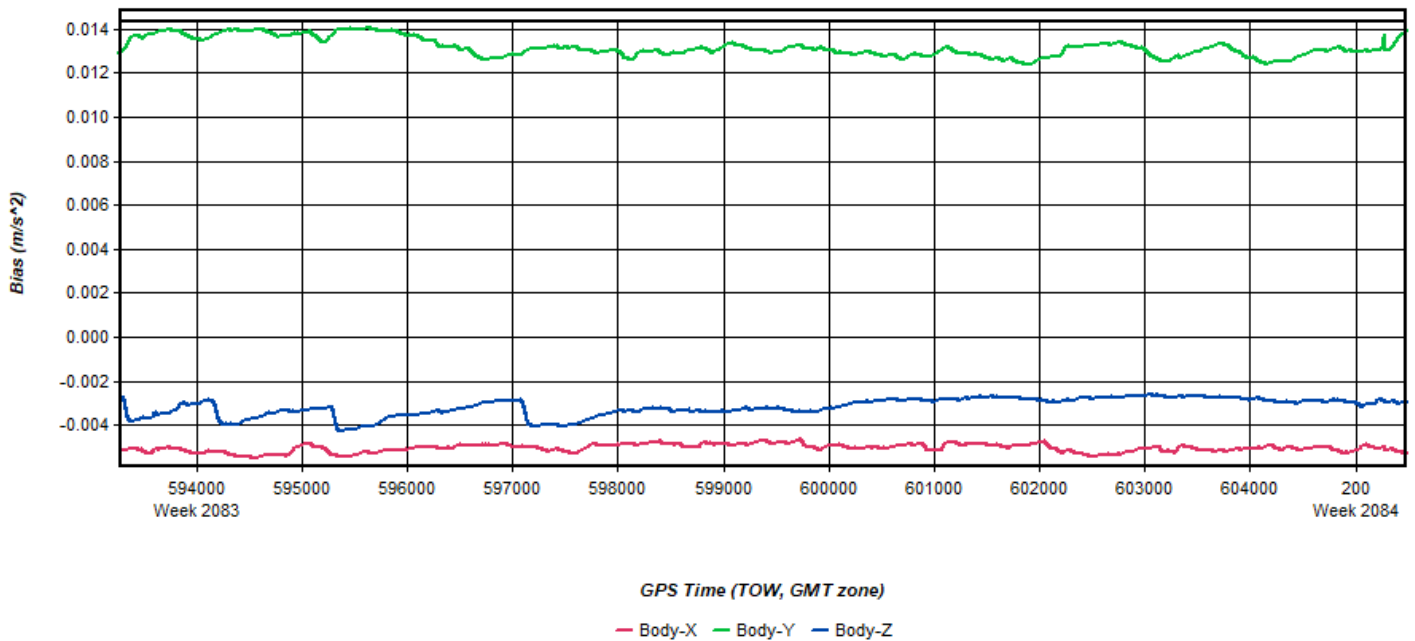
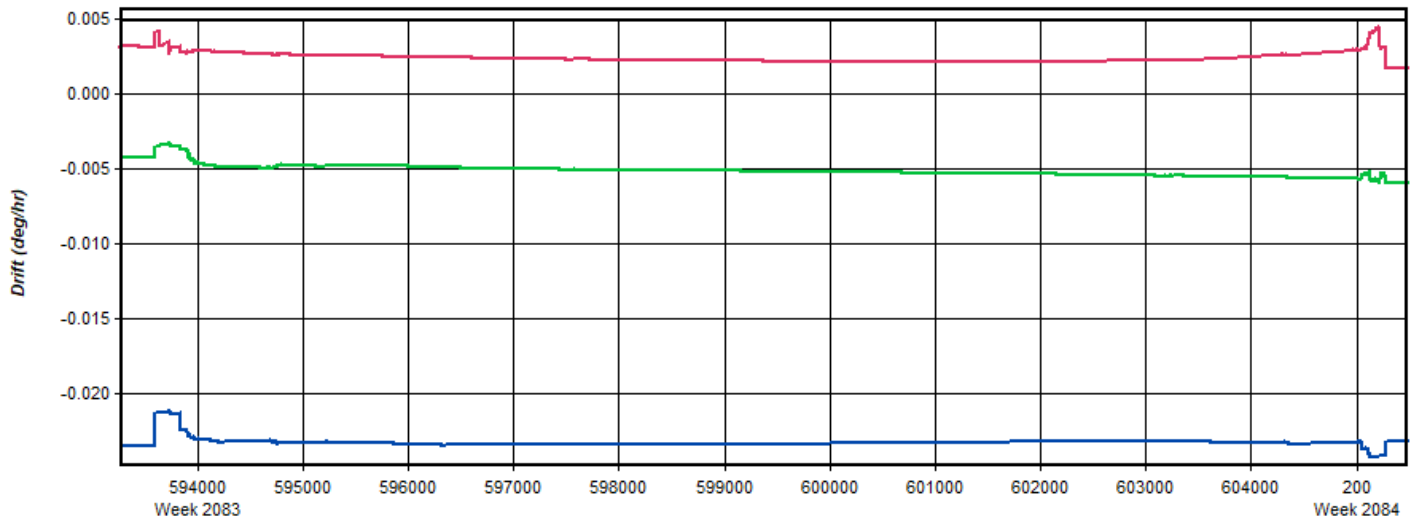


Figure 20: 20191214204650 [Smoothed TC Combined] - Gyro Drift Plot



GPS Time (TOW, GMT zone)

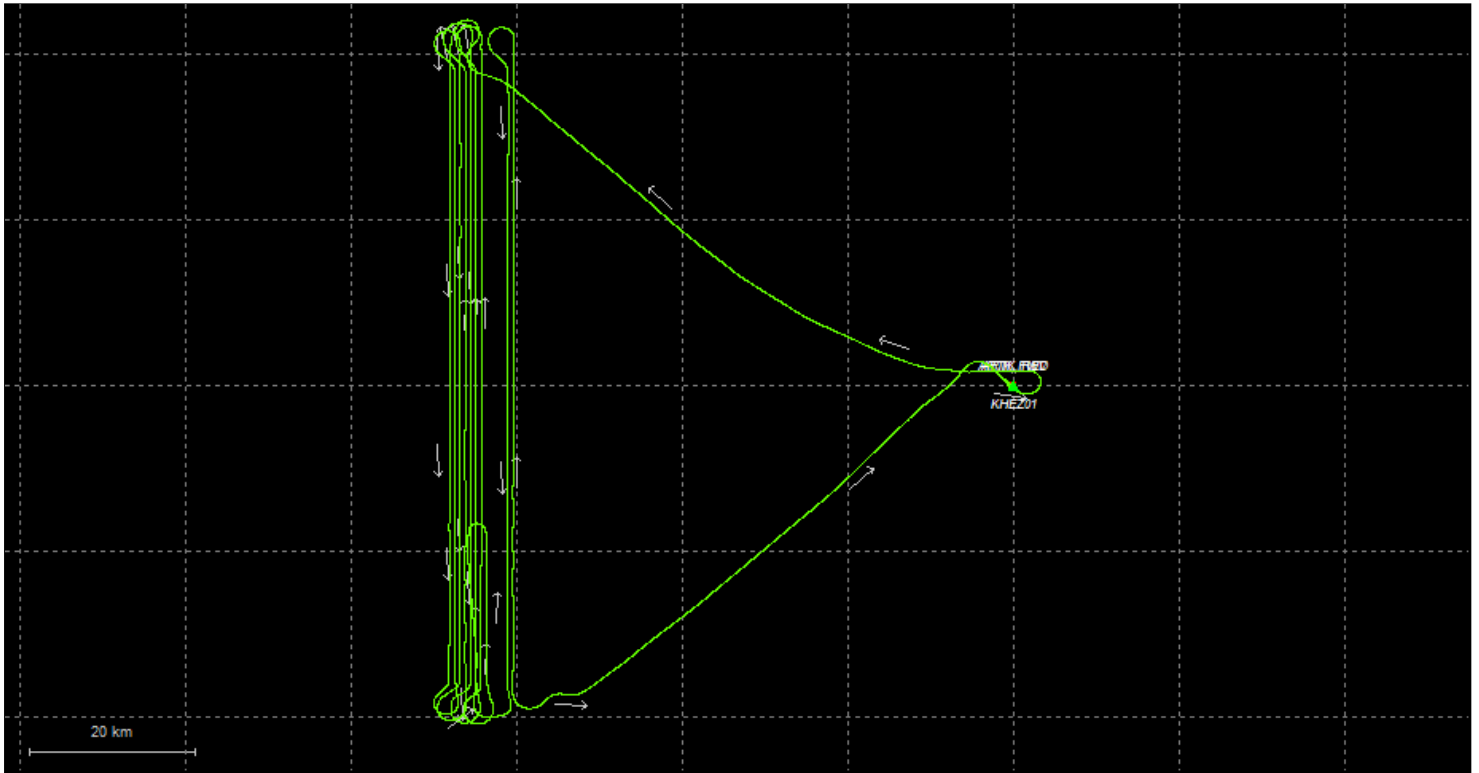
— Body-X — Body-Y — Body-Z

Process	20191214204650	by Unknown	on 12/24/2019	at 15:05:42
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Output Results for 20191215004501

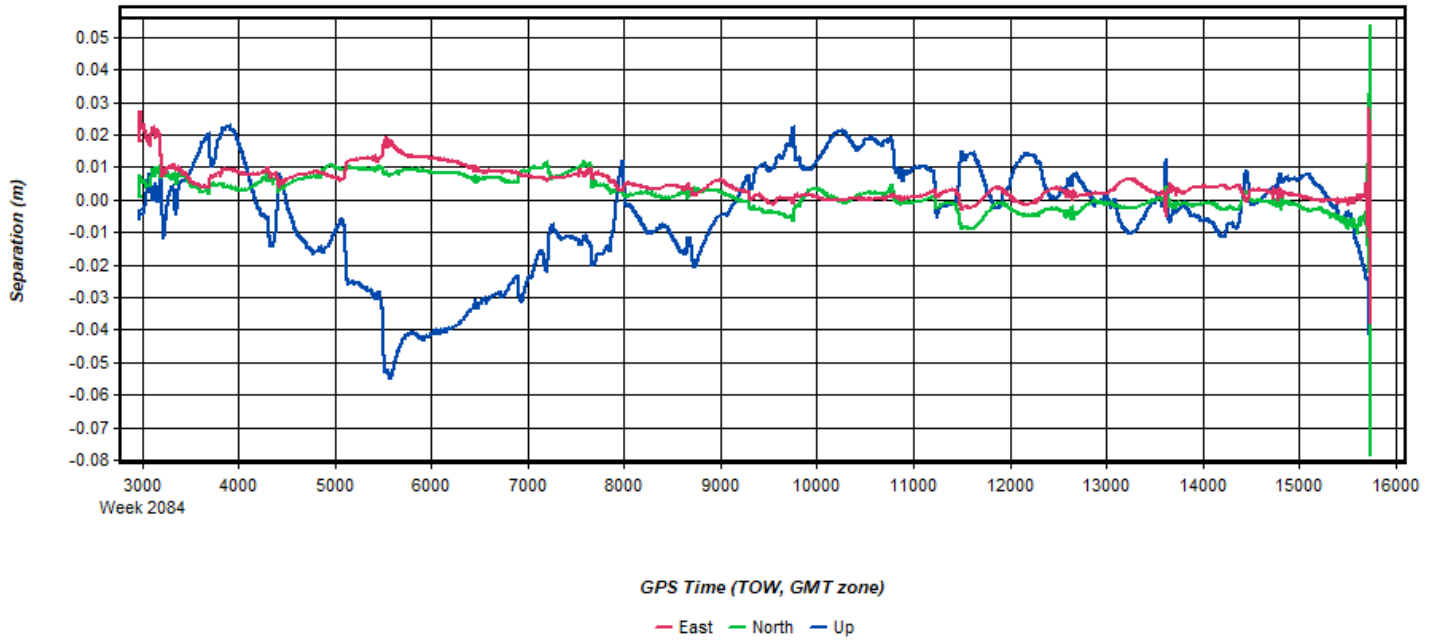
Inertial Explorer Version 8.80.2305
12/24/2019

Figure 1: Smoothed TC Combined - Map



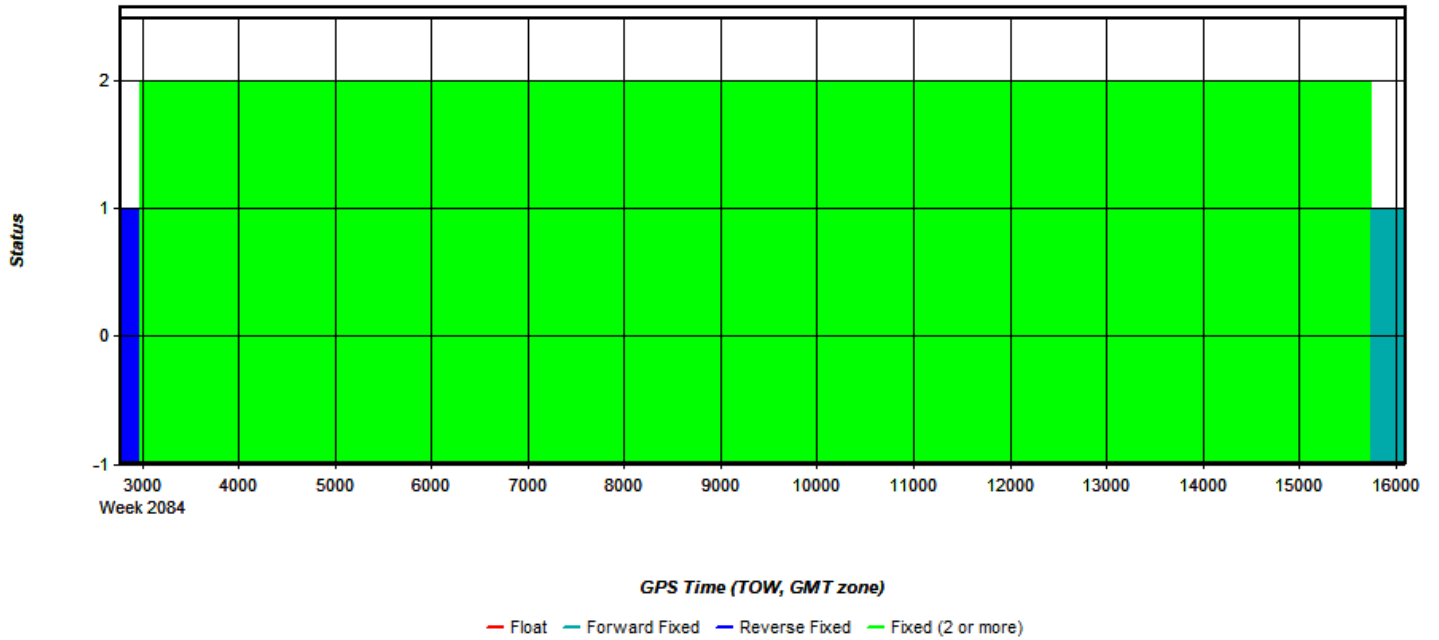
Process	20191215004501	by Unknown	on 12/24/2019	at 15:49:40
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Figure 2: 20191215004501 [Smoothed TC Combined] - Forward/Reverse or Combined Separation Plot



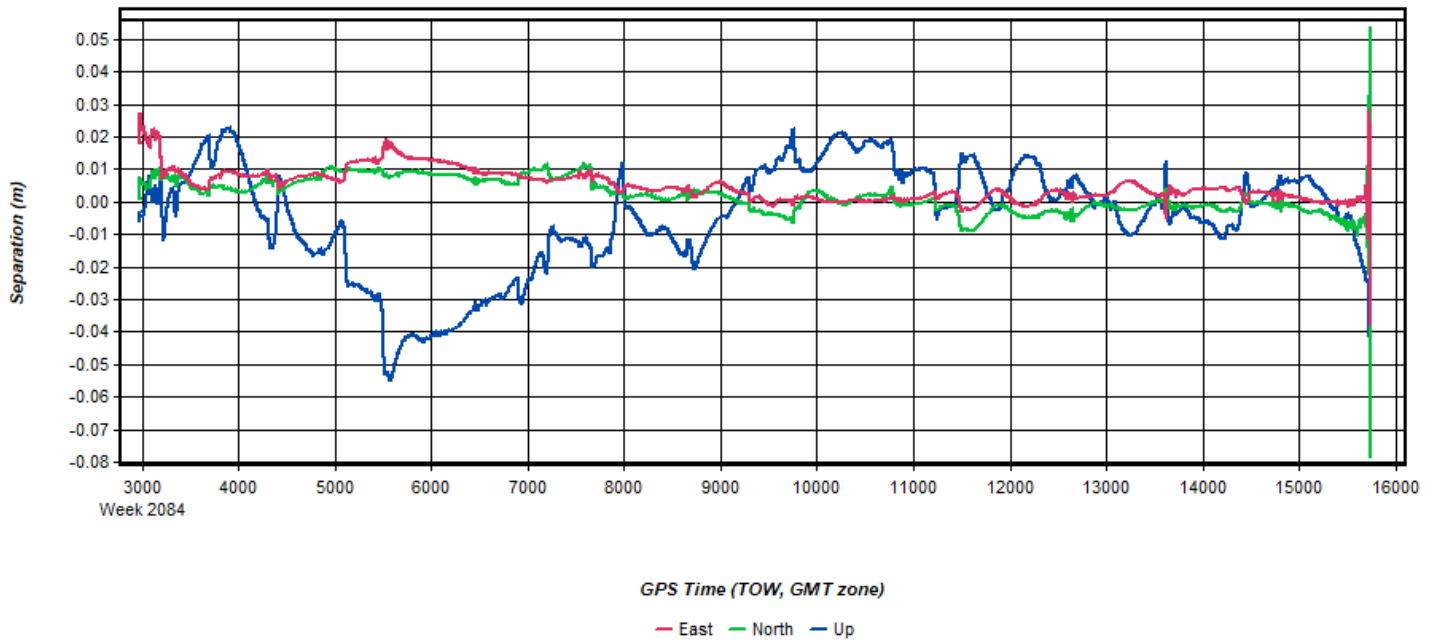
Process	20191215004501	by Unknown	on 12/24/2019	at 15:49:40
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Figure 3: 20191215004501 [Smoothed TC Combined] - Float or Fixed Ambiguity



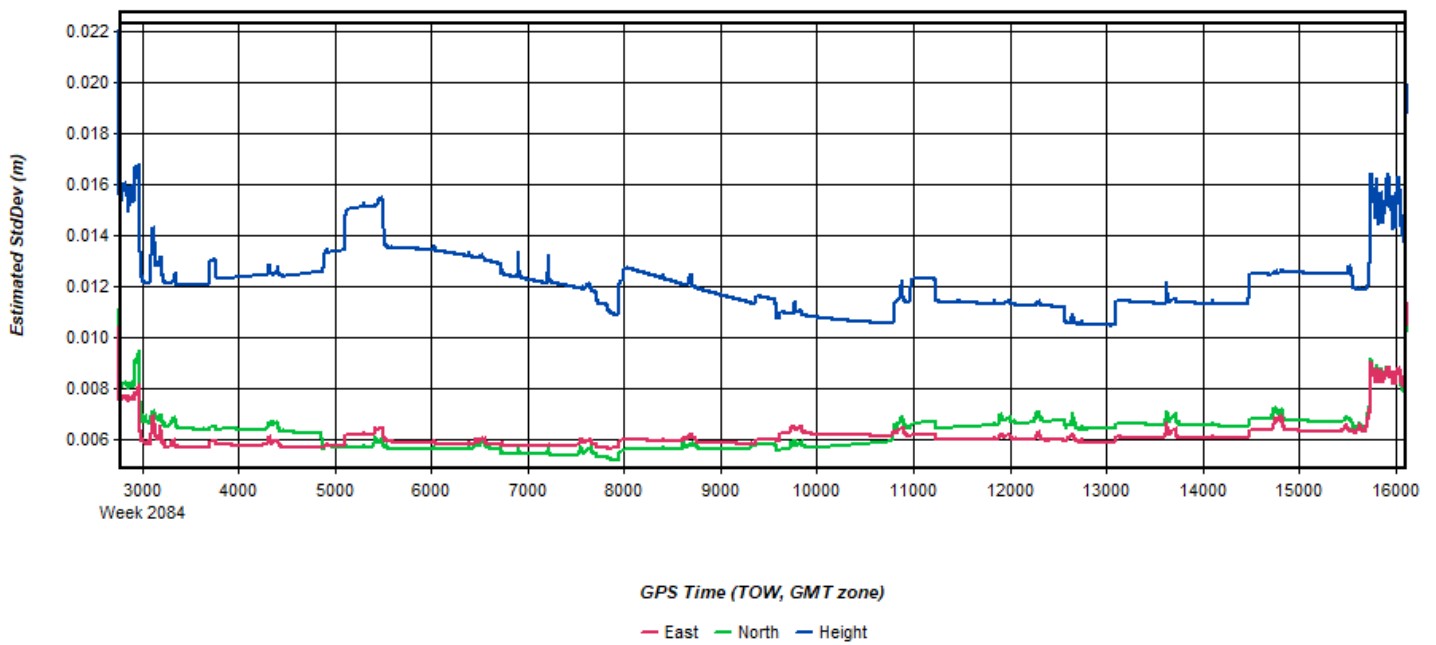
Process	20191215004501	by Unknown	on 12/24/2019	at 15:49:40
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Figure 4: 20191215004501 [Smoothed TC Combined] - Forward/Reverse Separation Plot (Fixed)



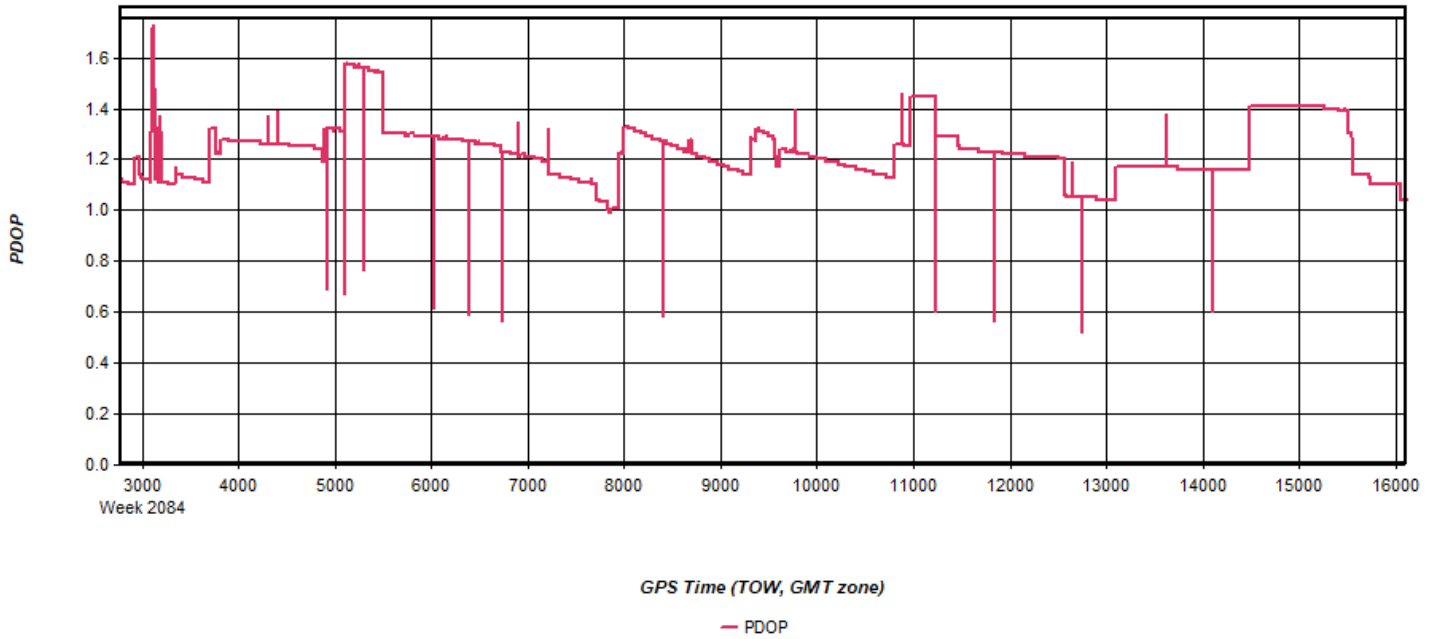
Process	20191215004501	by Unknown	on 12/24/2019	at 15:49:40
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Figure 5: 20191215004501 [Smoothed TC Combined] - Estimated Position Accuracy Plot



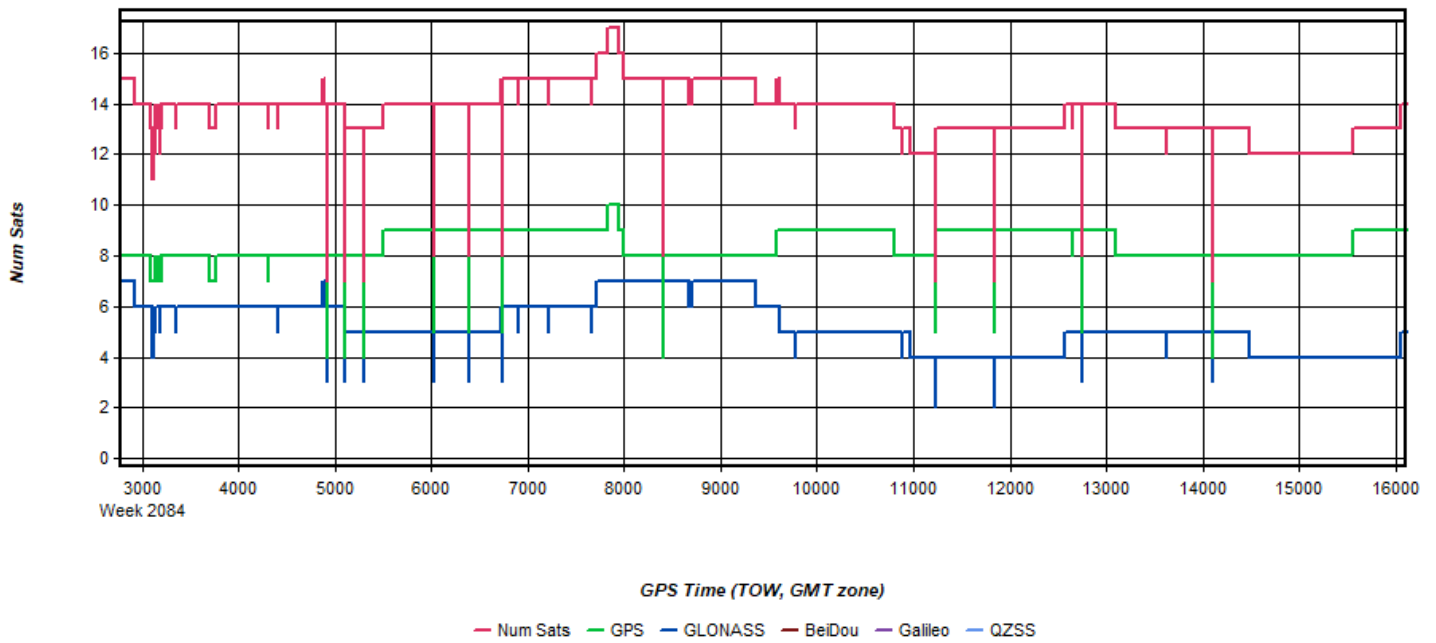
Process	20191215004501	by Unknown	on 12/24/2019	at 15:49:40
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Figure 6: 20191215004501 [Smoothed TC Combined] - PDOP Plot



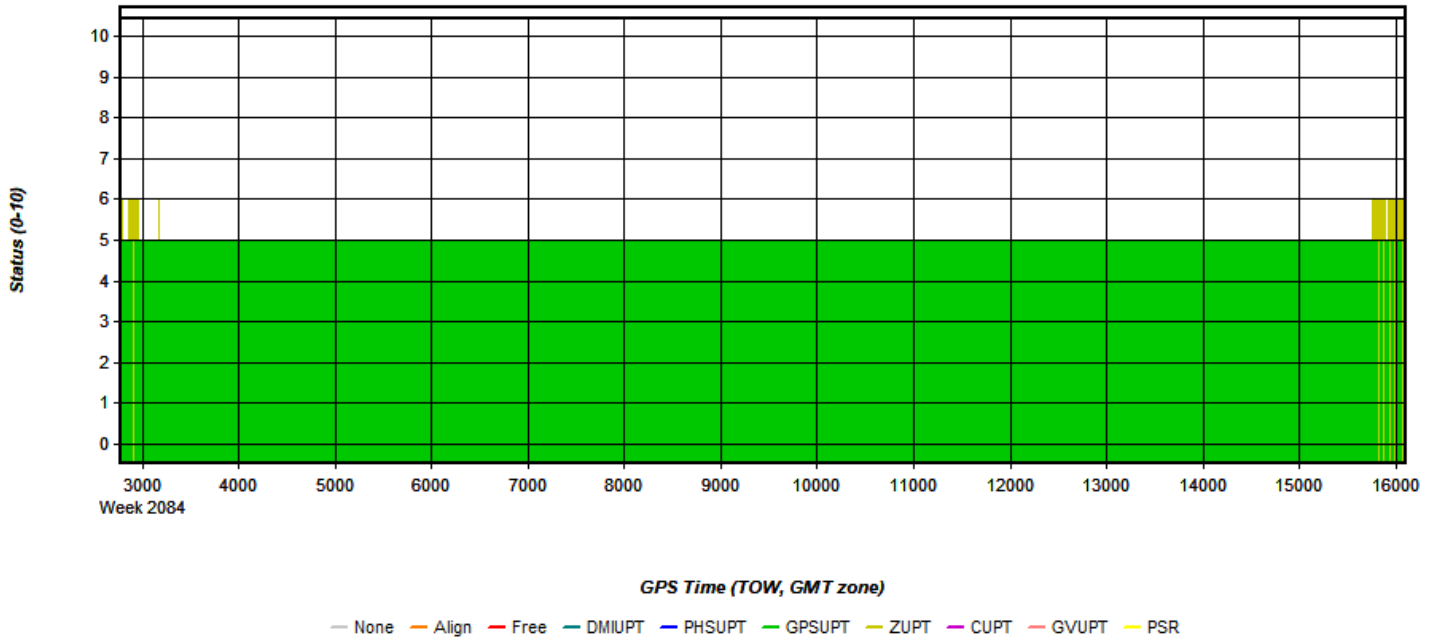
Process	20191215004501	by Unknown	on 12/24/2019	at 15:49:40
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Figure 7: 20191215004501 [Smoothed TC Combined] - Number of Satellites Line Plot



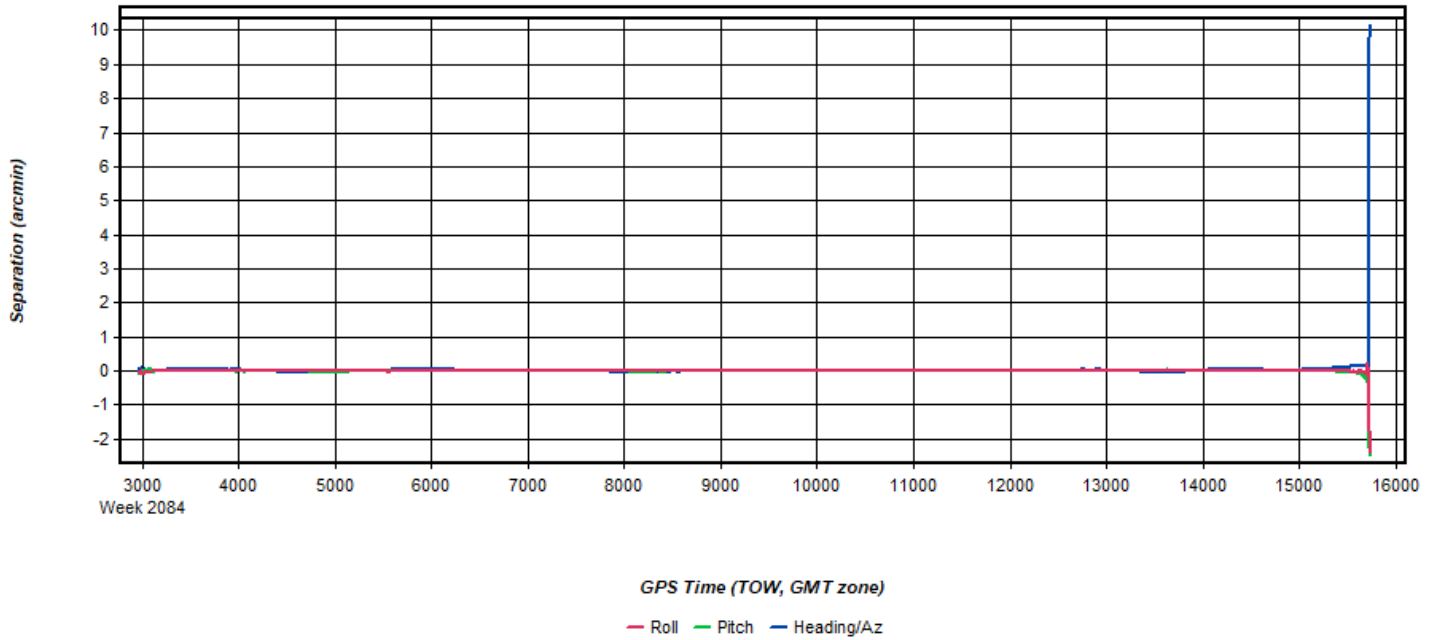
Process	20191215004501	by Unknown	on 12/24/2019	at 15:49:40
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Figure 8: 20191215004501 [Smoothed TC Combined] - Status flag for IMU processing



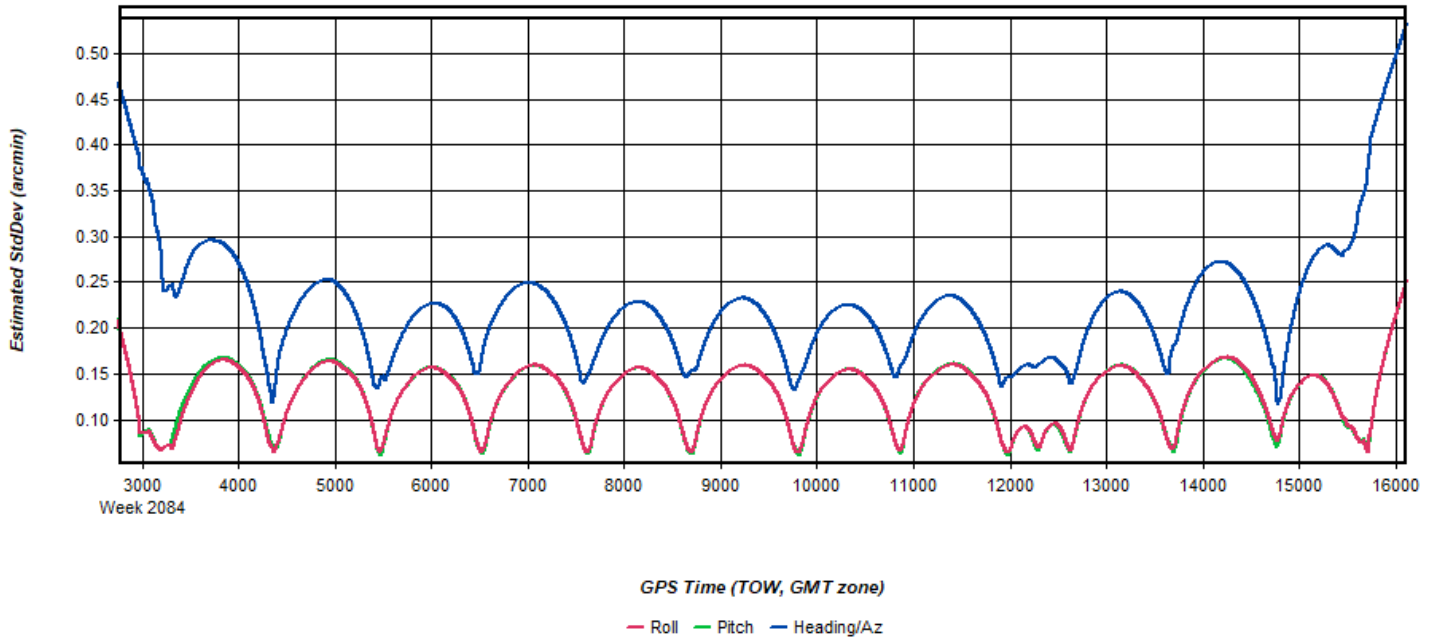
Process	20191215004501	by Unknown	on 12/24/2019	at 15:49:40
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Figure 9: 20191215004501 [Smoothed TC Combined] - Fwd/Rev Attitude Separation Plot



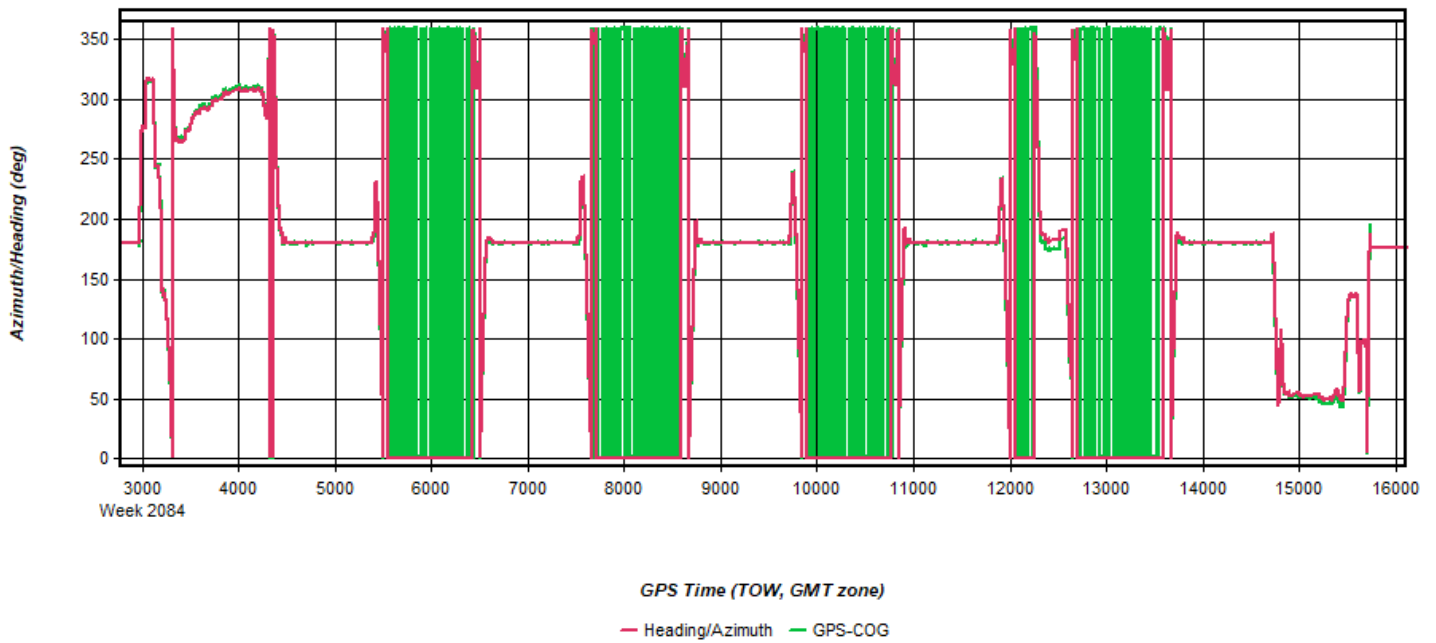
Process	20191215004501	by Unknown	on 12/24/2019	at 15:49:40
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Figure 10: 20191215004501 [Smoothed TC Combined] - Estimated Attitude Accuracy Plot



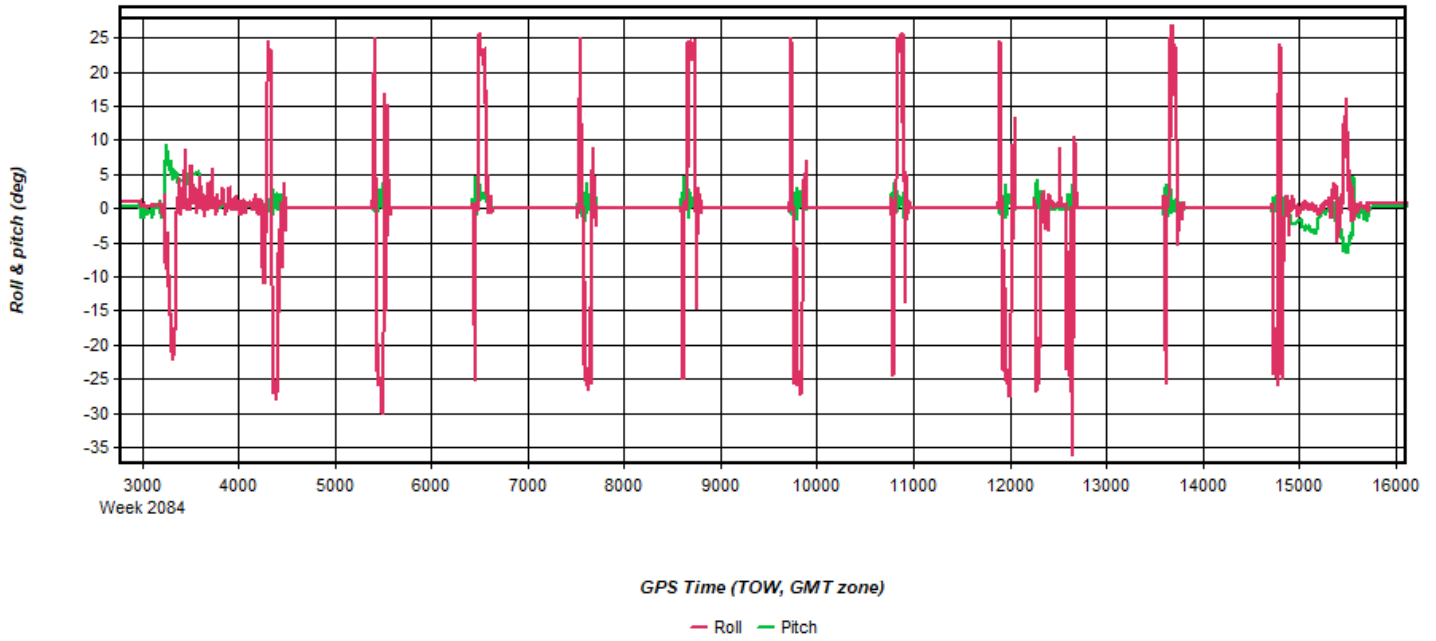
Process	20191215004501	by Unknown	on 12/24/2019	at 15:49:40
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Figure 11: 20191215004501 [Smoothed TC Combined] - Azimuth Plot



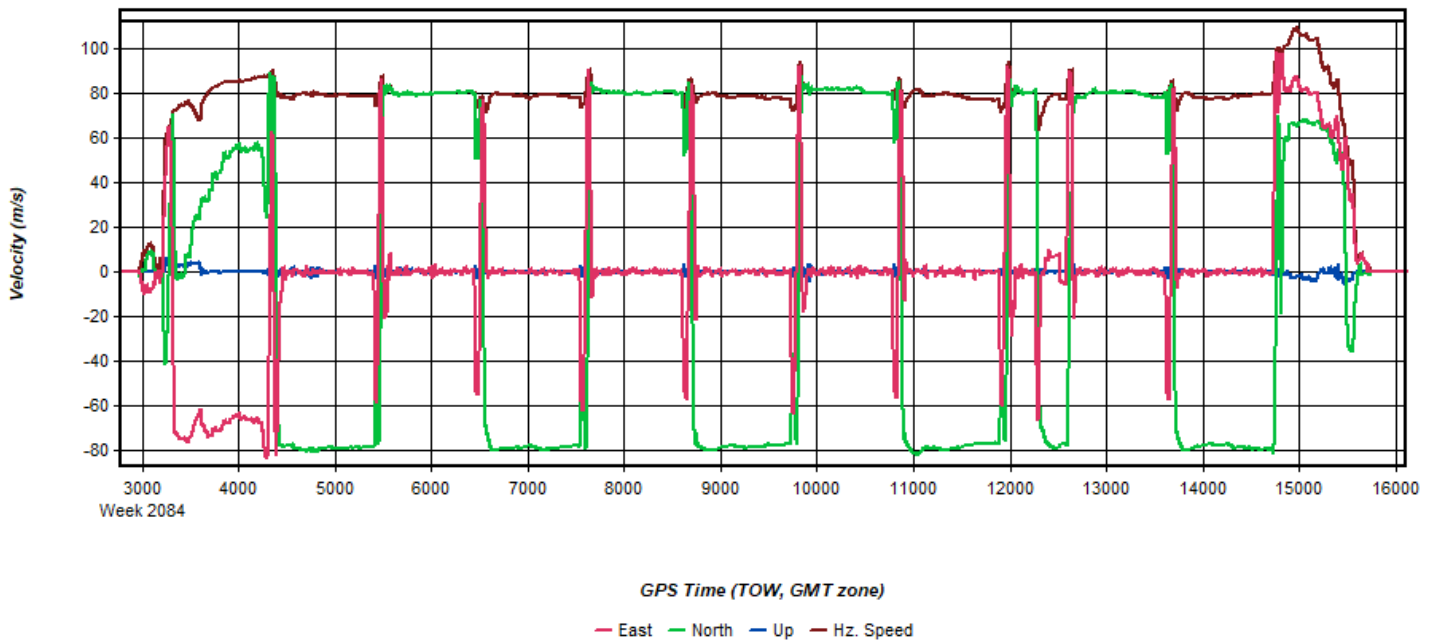
Process	20191215004501	by Unknown	on 12/24/2019	at 15:49:40
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Figure 12: 20191215004501 [Smoothed TC Combined] - Roll & Pitch Plot



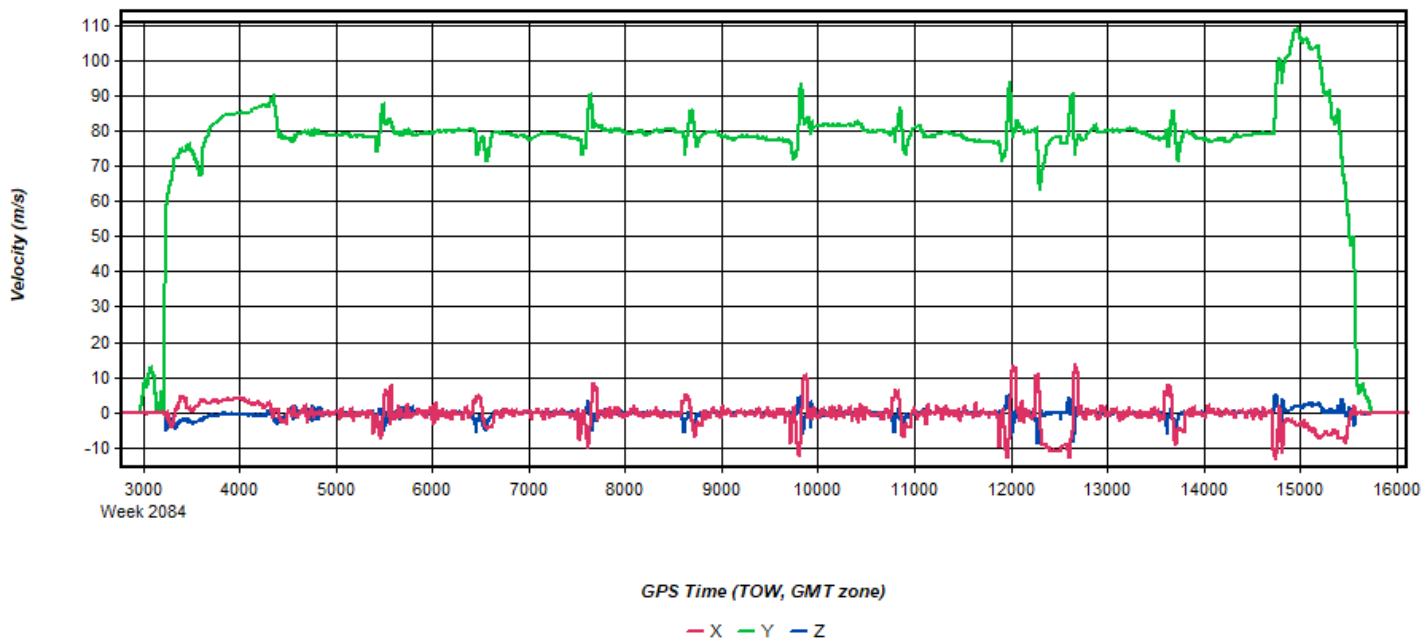
Process	20191215004501	by Unknown	on 12/24/2019	at 15:49:40
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Figure 13: 20191215004501 [Smoothed TC Combined] - Velocity Profile Plot



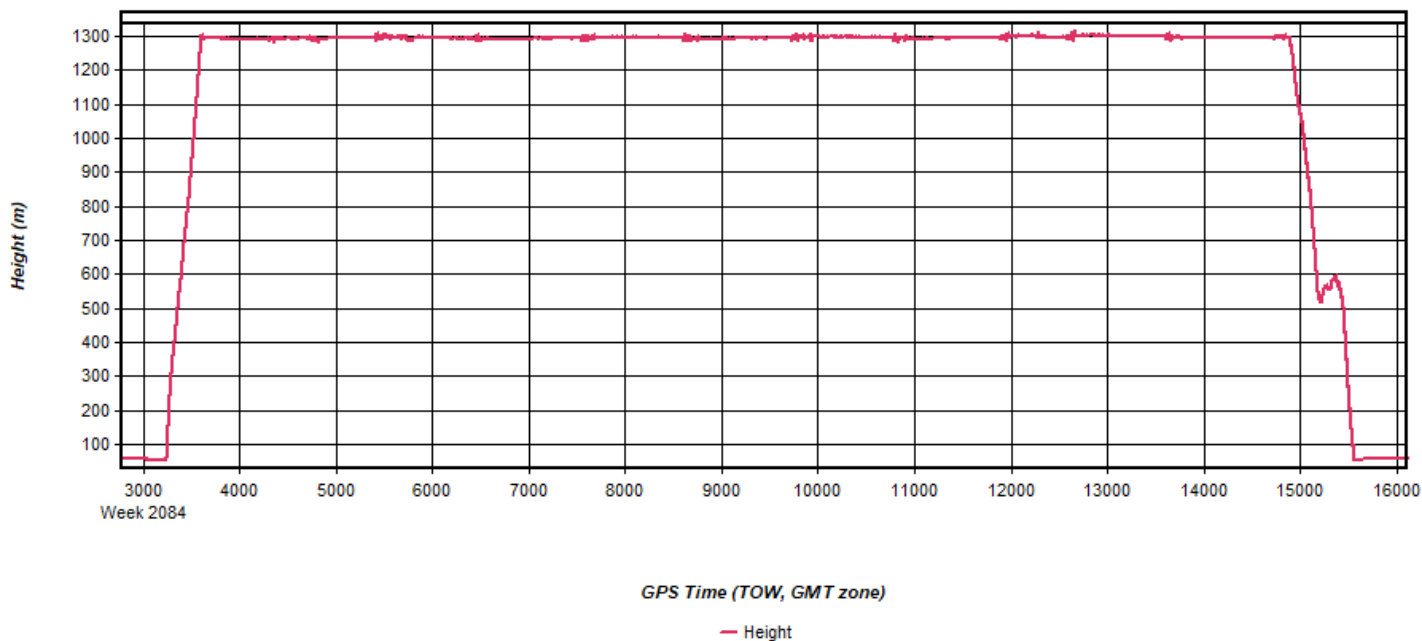
Process	20191215004501	by Unknown	on 12/24/2019	at 15:49:40
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Figure 14: 20191215004501 [Smoothed TC Combined] - Body Frame Velocity Plot



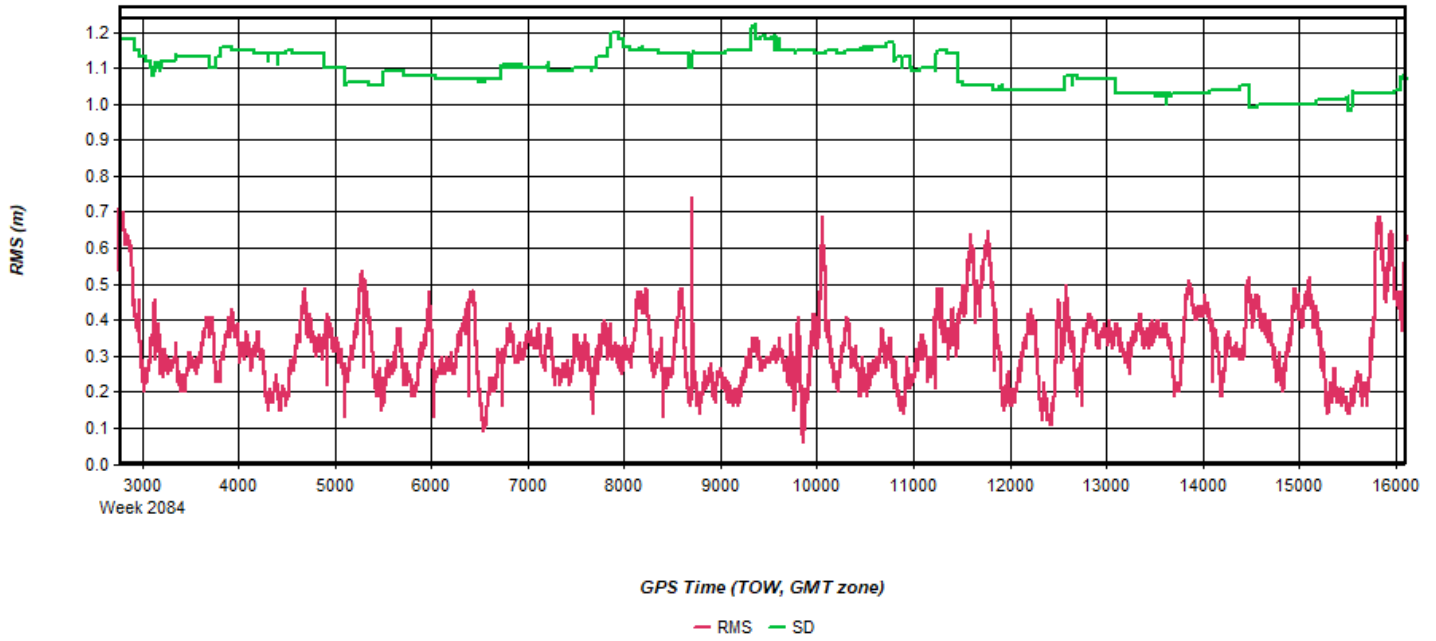
Process	20191215004501	by Unknown	on 12/24/2019	at 15:49:40
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Figure 15: 20191215004501 [Smoothed TC Combined] - Height Profile Plot



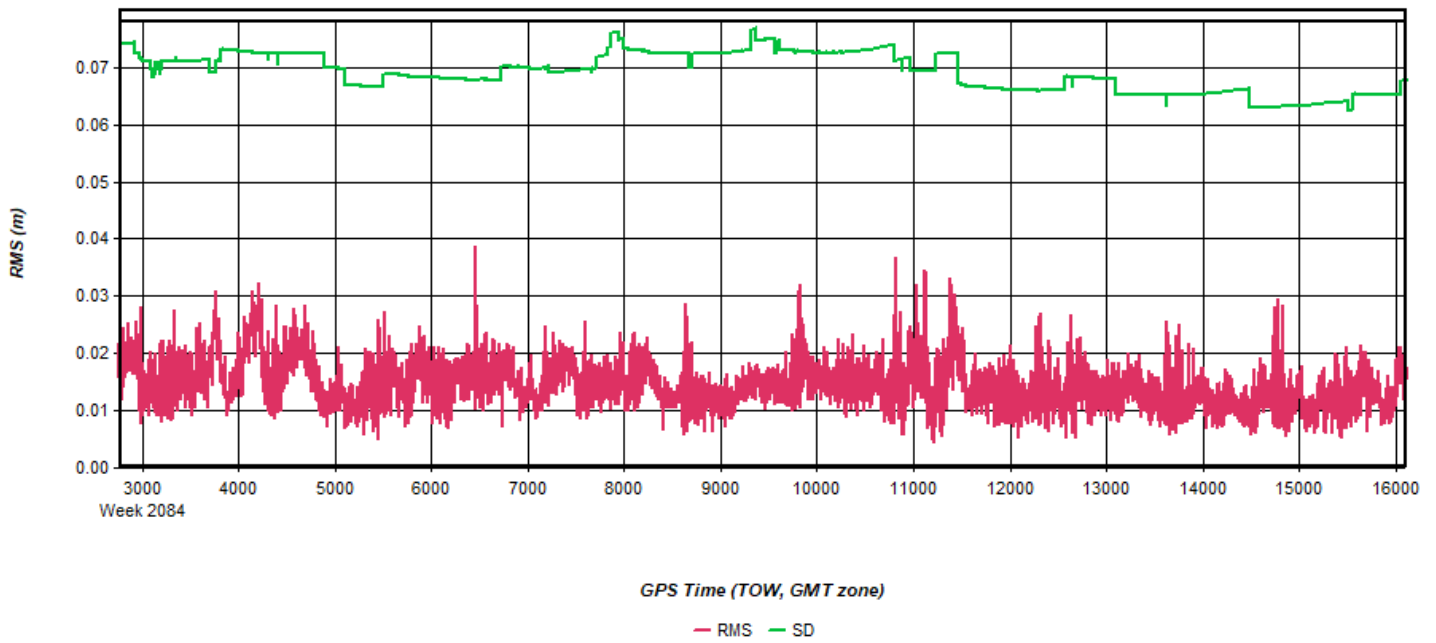
Process	20191215004501	by Unknown	on 12/24/2019	at 15:49:40
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Figure 16: 20191215004501 [Smoothed TC Combined] - C/A Code Residual RMS Plot



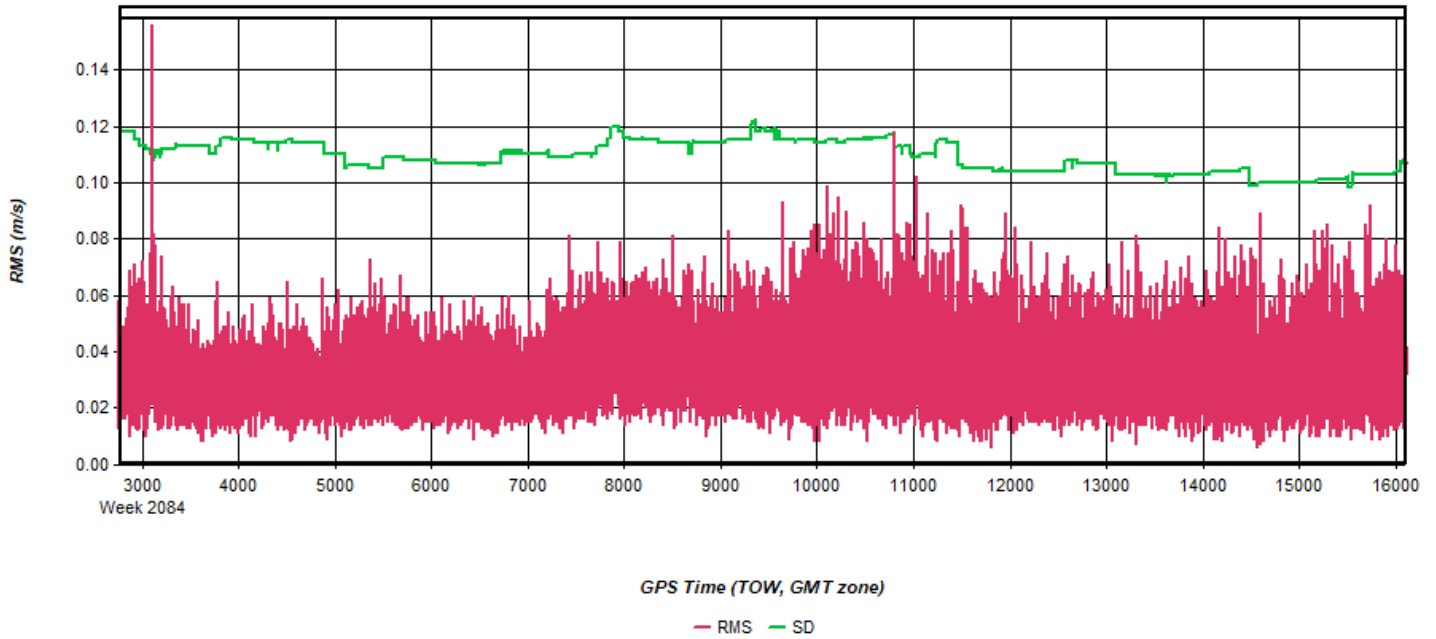
Process	20191215004501	by Unknown	on 12/24/2019	at 15:49:40
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Figure 17: 20191215004501 [Smoothed TC Combined] - Carrier Residual RMS Plot



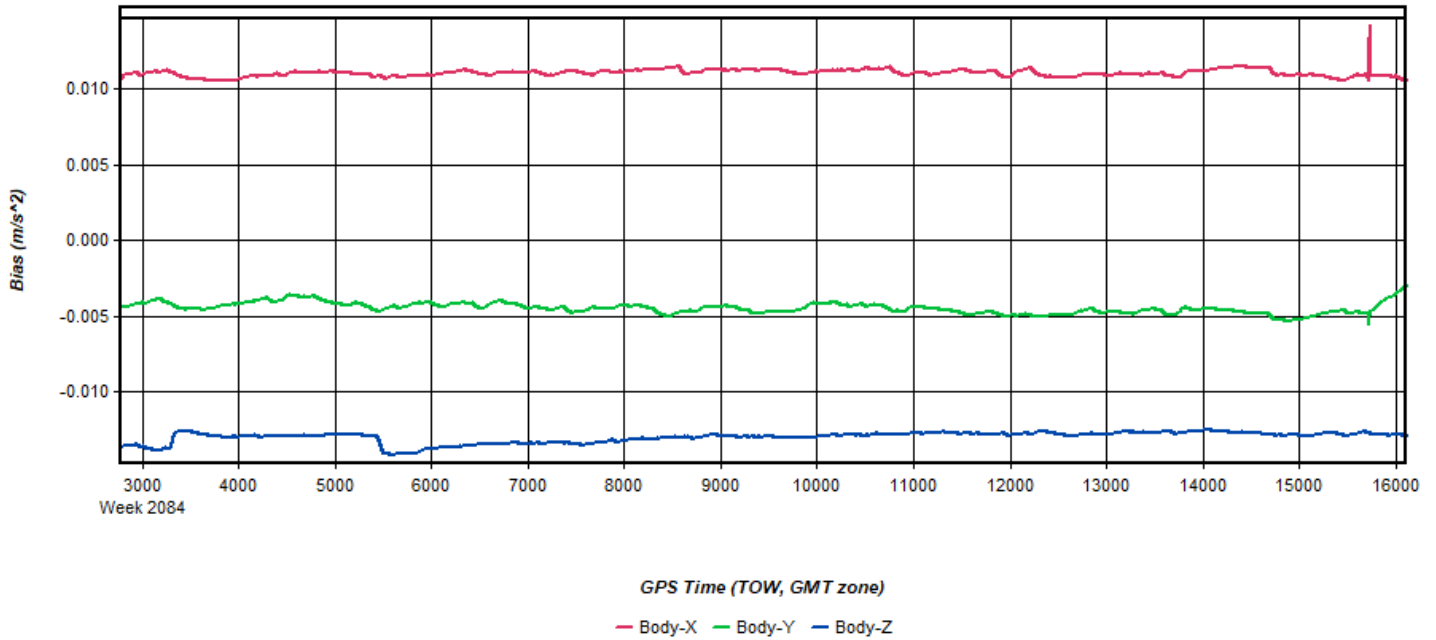
Process	20191215004501	by Unknown	on 12/24/2019	at 15:49:40
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Figure 18: 20191215004501 [Smoothed TC Combined] - L1 Doppler Residual RMS Plot



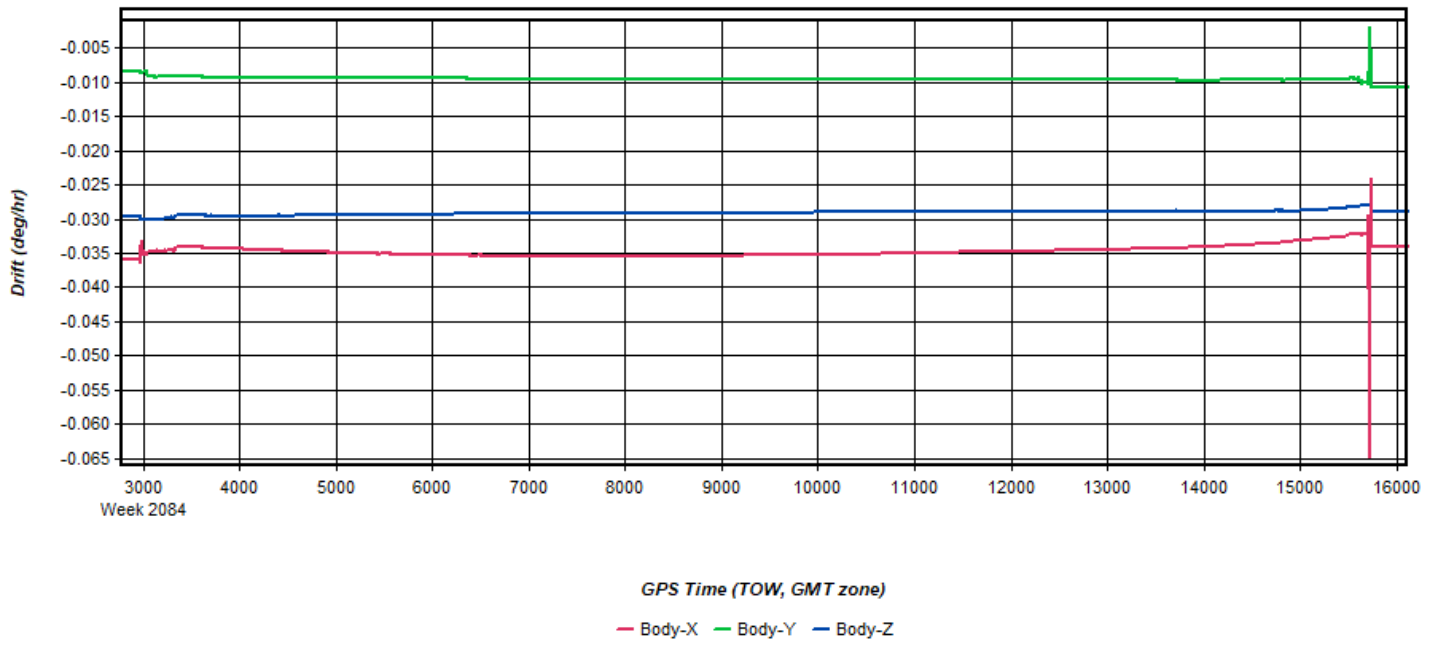
Process	20191215004501	by Unknown	on 12/24/2019	at 15:49:40
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Figure 19: 20191215004501 [Smoothed TC Combined] - Accelerometer Bias Plot



Process	20191215004501	by Unknown	on 12/24/2019	at 15:49:40
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Figure 20: 20191215004501 [Smoothed TC Combined] - Gyro Drift Plot



Process	20191215004501	by Unknown	on 12/24/2019	at 15:49:40
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