

LiDAR Report: LA_Catahoula_Concordia_2017_D17 D1

LiDAR Collection, Processing, and QA/QC

G17PD1255: LA_Catahoula_Concordia_2017_D17 D1

QL1 LIDAR

Prepared For:

US Geological Survey

1400 Independence Road

Rolla, MO 65401

Phone: (573) 308-3759

Prepared By:

Digital Aerial Solutions, LLC

4027 Crescent Park Drive

Riverview, FL

33578

Phone: (813) 628-0788

Contract: G16P00044 Contractor: Digital Aerial Solutions Task Order: G17PD1255: LA_Catahoula_Concordia_2017_D17



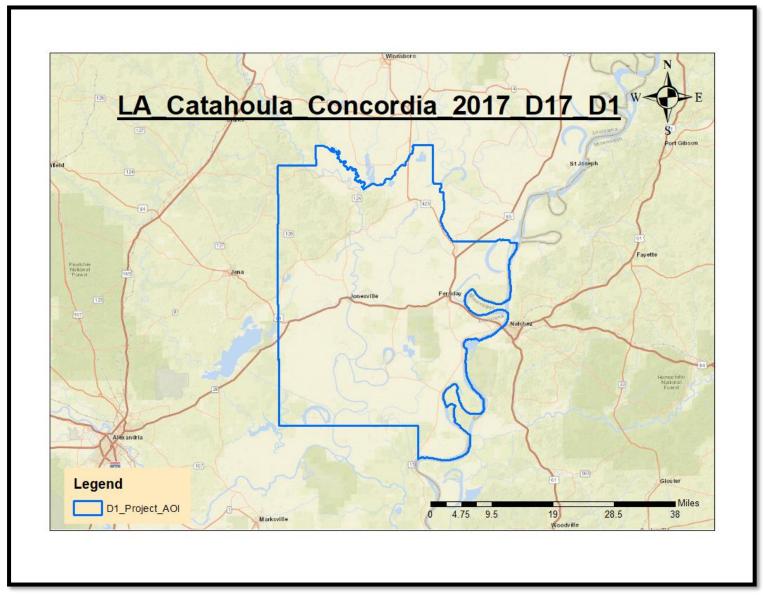


Image 1: LA_Catahoula_Concordia_2017_D17 D1 AOI



Table of Contents

1 INTRODUCTION AND SPECIFICATIONS	4
2 SPATIAL REFERENCE SYSTEM	4
3 LIDAR ACQUISITION	5
3.1 SURVEY AREA	5
3.2 Acquisition Parameters	6
3.3 Acquisition Mission	6
3.4 AIRBORNE GPS/IMU	7
4 LIDAR PROCESSING	8
4.1 ACQUISITION POST PROCESSING	8
4.2 GEOMETRIC CALIBRATION	8
4.3 POINT CLOUD CLASSIFICATION.	9
4.4 Breakline Collection	0
4.5 DEM GENERATION	1
5 QUALITY CONTROL	1
5.1 POINT CLOUDS	1
5.2 Breaklines	4
5.3 DIGITAL ELEVATION MODELS	
APPENDIX A. FLIGHT LOGS	5
APPENDIX B. BASESTATION GPS SESSION FORMS	6
APPENDIX C. VERTICAL ACCURACY CALCULATIONS	Э
APPENDIX D. INERTIAL EXPLORER	1



1 Introduction and Specifications

Digital Aerial Solutions, LLC (Das) was tasked to collect and process a Light Detection and Ranging (LiDAR) derived elevated dataset for the **G17PD1255:LA_Catahoula_Concordia_2017_D17 D1**. The area encompasses approximately 1,261 square miles. Aerial LiDAR data was collected utilizing a Lecia Terrain Mapper. The Terrain Mapper is a discrete return topographic LiDAR mapping system manufactured by Leica Geosystems. LiDAR data collected for **G17PD1255:LA_Catahoula_Concordia_2017_D17 D1** LiDAR survey has an Aggregated Nominal Pulse (ANPS) spacing of 0.35 meters (**QL1**) and includes up to 2 discrete return per pulse, along with intensity values of each return.

LIDAR datasets were post process to generate elevation point cloud swaths for each flight lines. Deliverables include tiled point cloud classified by land cover type, breaklines to support hydro-flattening of digital elevations models (DEM), intensity tiles, and bare-earth DEM titles. The point cloud deliverables are store in the LAS Version 1.4, point data record format 6. The tiling scheme for the tiled deliverables is a **1,000 x 1,000** meters grid. Tile naming convection is based on the Based on the U.S. National Grid and named according to the U.S. National Grid System based on the SW corner (**e.g. 12TVK0616**). All deliverables were generated in conformance with the U.S Geological Survey National Geospatial Program Guidelines and Base Specifications, Version 2.1.

2 Spatial Reference System

The spatial reference of the data is as follows:

Horizontal Spatial Reference

- Coordinates: Universal Transverse Mercator, UTM, Zone 15 North Meters (to 2 decimal places)
- Datum: North American Datum 1983 (2011), Meters (to 2 decimal places)

Vertical Spatial Reference

All datasets are available with orthometric elevation; point cloud datasets are also available with ellipsoid heights.

- Datum: North American Vertical Datum of 1988 (GEOID 12B)



3 LiDAR Acquisition 3.1 Survey Area

The **G17PD1255:LA_Catahoula_Concordia_2017_D17 D1** survey covers approximately 1,261 square miles located Catahoula and Concordia parishes in Louisiana. The project consisted of consisted of 95 flight lines totaling 3,206.94 nautical miles.

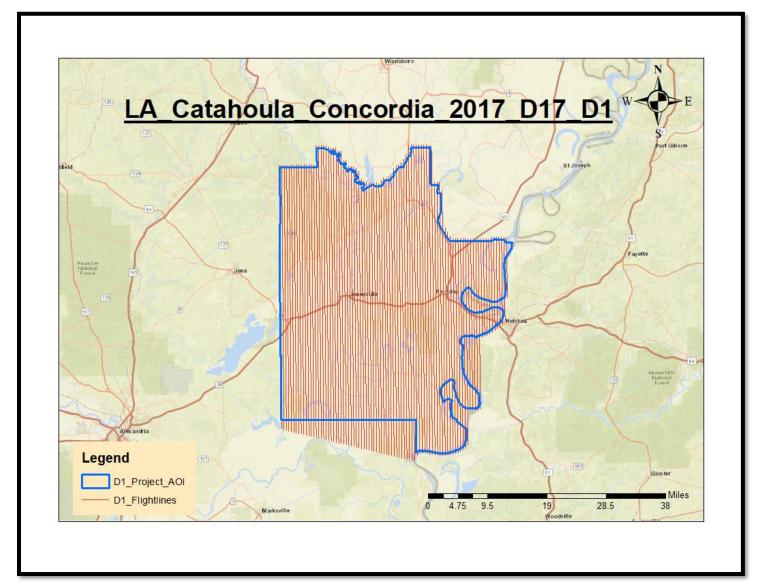


Image 2: LA_Cathoula_Concordia_2017_D17 D1 Flightlines



3.2 Acquisition Parameters

Acquisition parameters include the sensor configuration and the flight plan characteristics, and are selected based on a number of project specific criteria. Criteria reviewed include the required accuracies for the final dataset, the land cover types within the project survey area, and the required nominal pulse spacing. Aggregate Nominal Pulse Density (ANPD) for QL1 AOI is no less than 8ppm. The project parameters are summarized below.

Parameter (QL1)	Terrain Mapper
Flying Height Above Ground Level:	6,234 feet
Nominal Sidelap:	30-55%
Nominal Speed Over Ground:	170 Knots
Field of View:	40°
Laser Rate:	154.00 kHz
Scan Rate:	150.00 Hz
Maximum Across Track Spacing:	0.43meters
Maximum Along Track Spacing:	0.58 meters
Average point Spacing:	0.35 meters

Table 1: Flight Parameters

3.3 Acquisition Mission

The acquisition mission for **G179D1255: LA_Catahoula_Concordia_2017_D17 D1** QL1 LiDAR survey was coordinated for optimal collection conditions and was completed in 10 lifts from December 2nd 2019–December 14th, 2019. The GPS Session forms and NGS monument information can be found in **Appendix B**.



3.4 Airborne GPS/IMU

Airborne global positioning system (GPS) and inertial measurement unit (IMU) data was collected on the aircraft during the acquisition mission, providing sensor position and orientation information for georeferencing the LiDAR data. Airborne GPS observations were collected at a frequency of 0.5Hz, and IMU observations are collected at a frequency of 200Hz.

Aircraft	Sensor	GPS Lever Arm (m)	IMU Lever Arm (m)			
C441-N207SS	TM_9054	X: -0.054, Y: -0.199, Z: -1.131	X: -0.174, Y:0178, Z: 1.256			

Table 2: Aircraft and Lever Arms

GPS data was collected with ground base stations during the acquisition missions, providing corrections to support differential post-processing of the airborne GPS. Base stations were setup at the following Airports St Hardy-Anders Field Natchez Adams County Airport (**KHEZ**). Ground GPS observations were collected at a frequency of 0.5Hz.

Name	Latitude	Longitude	Ellipsoid (m)
Hardy-Anders Field Natchez Adams County Airport (KHEZ)	31°36' 56.46414"	-91° 28' 38.66190"	55.417

Table 3: Base Stations Location



4 LiDAR Processing 4.1 Acquisition Post Processing

Inertial Explorer 8.90 software was used to compute inertial solution file (*.sol) for each mission using ground GPS base station (**KHEZ**) and Grafnet position coordinate in table above. The resulting solution was checked to ensure a minimum accuracy of +/- 0.10m, combined separation, for horizontal and vertical positions. Inertial Explorer methodology integrates Inertial Navigation Solution by processing the GPS data and Inertial Measurement Unit (IMU). The software applies the reference lever arms for the GPS and IMU during the process to determine the trajectory (position and orientation) of the LiDAR sensor during the acquisition mission. Inertial Explorer generated graphical results were reviewed to ensure that the IMU data was healthy.

Raw LiDAR sensor ranging data and the final solution sensor trajectory (*.sol), from Inertial Explorer, were processed in Leica's HxMap software to produce LiDAR point cloud swath for each flight line in LAS version 1.4 file format. Quality control of the swath point cloud was performed to validate proper functioning of the sensor system, full coverage of the project area and point density of the LiDAR data. Swath point clouds were assigned unique file source identification. The data was found to be complete and consistent with the sensor calibration parameters.

4.2 Geometric Calibration

LiDAR data calibration was done using Leica HxMap v2.6.0 software. HxMap is the common workflow platform for Leica airborne sensors. The processing workflow involves; Ingest, Block Creation, LiDAR Matching, Quality Assurance (QA) and Product Generation. LiDAR is processed in HxMap by generating point clouds from raw sensor data during the Ingest step. Noise filtering, sensor installation calibration and atmospheric condition parameters are also applied during the ingest process. Once all data is processed through ingest, they are assembled into a block for LiDAR Matching. The LiDAR Matching step resolves LiDAR registration errors which remain in the point clouds after sensor and installation calibration parameters are applied in the ingest step.

QA tool is run on the Block after LiDAR Matching to verify quality of results. QA results are reviewed to ensure that, 95% of patches<5cm for Vertical Scan Direction and Vertical Line Separation. Ground control points are also included to assess absolute accuracy for the point cloud data. LiDAR products are finally generated in the Product Generation step as LAS swaths (LAS 1.4). Vertical (Z) shift (calculated from QA step) is also applied during the product generation. The exported LAS 1.4 swath data from HxMap is imported into GeoCue Group's product workflow management software, GeoCue v2017. The full point cloud is tiled into a manageable size for processing in TerraScan.



For G17PD1255:LA_Catahoula_Concordia_2017_D17 D1 QL1 LiDAR project, the control lines listed below were used in data adjustment.

Point Id	Easting	Northing	Orth. Height
3_GS00002	636192.807	3499335.093	16.994
3_GS00007	602176.796	3474469.542	20.018
3_GS00001	616573.25	3517105.716	17.573
3_GS00003	621279.198	3497796.315	17.754
3_GS00004	599482.794	3509326.095	25.681
3_GS00005	607421.396	3483723.11	17.774
3_GS00006	608491.665	3470809.549	19.05

The final geometrically calibrated swath point clouds were compared to the bare-earth profile survey data. The data fit the profile surveys within the vertical accuracy tolerance specified for the project. Full documentation of the vertical accuracy checks maybe found in section 5.1.

4.3 Point Cloud Classification

Georeferenced information was applied to the swath point cloud LAS files. Geometrically calibrated swath point clouds were cut into USNG index, **1,000 meters x 1,000 meters** LAS 1.4 format tiles for point cloud classification and derived in LAS 1.4 format for product creation.

Tiled point cloud data was processed in Terrasolid's TerraScan software to assign initial classification values. The TerraScan software provides a number of routines to algorithmically detect and assign points to their appropriate class. Points left unclassified by the algorithmic routine remain as Class 1– Processed, but unclassified. Automated classification routines assigned points to one of the following classes:



Class 1 – Processed, but unclassified Class 2 – Bare-earth ground Class 7 – Low Noise (low, manually identified, if necessary) Class 9 — Water Class 17 — Bridge Decks Class 18 – High Noise (high, manually identified, if necessary) Class 20 — Ignored Ground (Breakline Proximity) Class 21- Snow (If present and identifiable) Class 22- Temporal exclusion (typically non-favored data in intertidal zones)

Automated classification results were reviewed for each tiled point cloud, and manual edits made where necessary to correct for misclassified points. Points remaining in Class 1 after the automated classification routines were run were left in Class 1. Points falling outside of a 100-meter buffer of the project AOI polygon were excluded from the tiled point clouds.

4.4 Breakline Collection

Hydro break lines were compiled in ArcMap using the LiDAR intensity data and surface terrain model of the entire project area. After the collection of hydro lines all features were conflated and validated for monotonicity and vertical variance, to ensure that no points were floating above ground. The hydro break lines were then embedded into the LiDAR surface and used to create a hydro enforced DEM.

The data collected for the **G17PD1255:LA_Catahoula_Concordia_2017_D17 D1** survey maintained significant point density in the water, marsh, and swamp, limiting the usefulness of point density as guiding factor in breakline placement. Points classified as **Class 2 – Bare-earth ground**, falling within a tenth of a meter buffer of the collected breaklines, were reassigned to **Class 20 – Ignored Ground**. These points are excluded from the surface model during DEM generation to preserve the hydro-flattening characteristics of the breaklines.



4.5 DEM Generation

The final classified point clouds and collected breaklines were reviewed for conformance to the task order (scope of work). Within the LP360 software, points in Class 2 – Bare- earth ground and breaklines were combined to generate TIN elevation models for each tile, from which the bare-earth DEM tiles were interpolated and exported as GeoTIFF 32-bit floating point raster format ".tiff" format

5 Quality Control 5.1 Point Clouds

Accuracy and completeness of the LiDAR point clouds directly impacts the quality of all other derived LiDAR derived products. Ensuring a quality LiDAR dataset begins with proper mission planning and execution. Ground GPS base stations are located such that GPS baselines between the ground and airborne receivers do not exceed 30km.For the G17PD1255:LA_Catahoula_Concordia_2017_D17 D1 project, two base stations were used to meet this requirement. Static alignment is performed both before take-off and after landing to allow for GPS integer ambiguity resolution. Sensor operators carefully monitor the LiDAR unit and its various subsystems during the acquisition mission to ensure proper function. Airborne GPS positional dilution of precision (PDOP) estimates are monitored to ensure they remain less than 3. The optical system is monitored to ensure there are no ranging errors encountered during the flight lines

During acquisition post-processing estimates of the trajectory data accuracy are reviewed to ensure they will support the required accuracies of the point cloud data. The trajectory accuracy is a function of the differentially corrected GPS data and the IMU data.

Geometric calibration quality control validates that the positional accuracy requirements of the project are met, and includes relative accuracy assessments for intra-swath (within) and inter-swath (between) accuracy, along with absolute accuracy assessments against project ground control.

Image 3 below, shows the swath to swath calibration assessment depicted by an intensity ortho created by using all returns, and colored by elevation difference between the swaths. The source deltas are an image type used for visualizing the elevation mismatch between overlapping swaths of LAS data. The granularity is controlled by the interval's selection. The interval size specifies the Z threshold at which the color bands apply. The interval used to create the difference elevation image is 0.040m. Colors shown as green indicates swath separation <0.040m, yellow indicates separation > 0.040m and <0.080m, red indicates separation >0.080m. All red areas depicted in the image have been reviewed and represent locations of high vegetation.



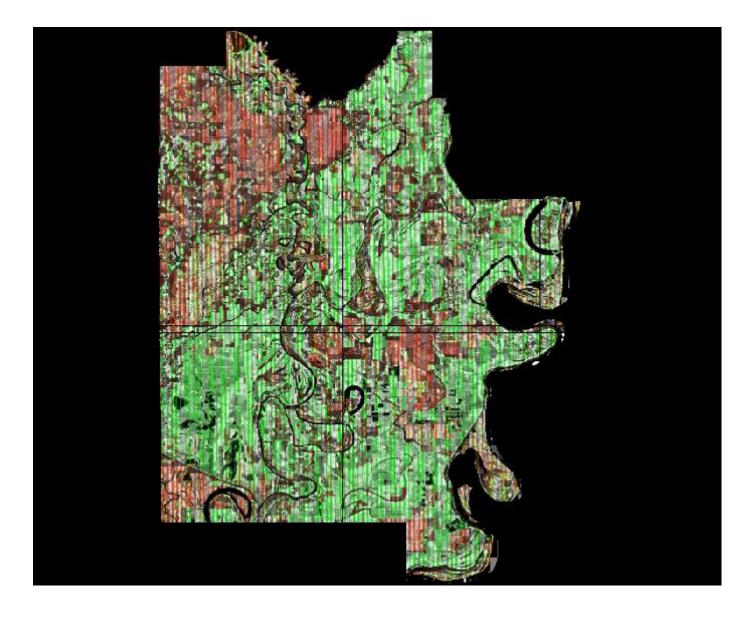


Image 3: Swath Separation Raster



This data set was produced to meet ASPRS "Positional Accuracy Standards for Digital Geospatial Data" (2014) for a 21.3(cm) RMSEx / RMSEy Horizontal Accuracy Class which equates to Positional Horizontal Accuracy =+/-41.7cm at a 95%

Absolute vertical accuracy assessments for the point cloud data are made against ground check point data. For the **G17PD1255:LA_Catahoula_Concordia_2017_D17 D1** project, ground check point data consisted of the ground GPS base station and real-time kinematic (RTK) GPS techniques.

Check point locations were collected at .5 second intervals during the RTK survey. Points collected during the static pre-initialization and post-initialization was removed from the assessment so as not to bias the assessment.

Local TIN models of the elevation points are built around each ground check points. The tin model elevation is sampled at the horizontal position of the ground check point. The TIN model elevation and ground check point survey elevation values were used to calculate the Non-vegetated Vertical Accuracy (NVA) of the swath point clouds. Table 7 below shows the tested accuracy values for TIN and DEM data at 95% confidence level. The full calculations for all check points can be found in Appendix C.

Tested Accuracy	RMSE _Z	NVA	VVA
Classified LiDAR	0.088	32	35
Digital Elevation Model	0.088	32	35

Table 7: Tested RMSE_z of NVA, NVA and VVA of LiDAR Point Cloud and Digital Elevation Model

Total #	# NVA	# VVA
67	32	35

 Table 8: Number of Survey Points used to calculate accuracy of data.



The tiled point cloud products were reviewed for full coverage of the AOI and proper classification. As part of the QC process, TINs are built in the Terramodeler software for each tile using the ground class and the hydroflattening breaklines. The TINs are reviewed for non-ground features, and edited where necessary to remove any remaining non-ground features. Points were also reviewed for absolute elevation, and points falling below the selected orthometric elevation for water were removed from the ground class.

5.2 Breaklines

The final breaklines in ESRI 3D shapefile format were reviewed for topological consistency and correct elevation. Breaklines features are continuous and do not have overlaps or dangles

5.3 Digital Elevation Models

Digital elevation models (DEMs) were reviewed for conformance with the SOW and the Base Mapping Specification version 2.1 guidelines. DEM files were loaded in the Global Mapper software and inspected visually for edge matching between tiles, void areas within the project AOI, and proper coding of the NODATA values. DEM file naming was verified for consistency with the USNG index.



Appendix A. Flight Logs



Project/Fl	ight Diane	La Cat	_Con_TM		Lift	Temp °C	Before	Temp	°C After	Press	ure (kPa)		Sensor Operator
FIOJECI/FI	igin Pian.				1	10			6	3	0.19		Geoffrey McCall
Date/J	ulian:	12/2/2019			Disk Driv	e			Sensor				Pilot
Hobb	s End	2110		TM	MM30 (10	3, 104)			TM_90524			1	Mike Wasielewski
Hobb	os ST	2107.4		TARGET	MSL	Target AIRSPD	Base Name	PID	Base Name	PID	Base Height	Aircraft	Airport Identifcation:
Flight	Time	2.6		4,31	L4	160	KHEZ01		KHEZ02		1.500	C421-N112MJ KHEZ (Natchez, MS)	
			UTC	time:	0		Carried	Available	c.hu	Position Acc.		Comments and Conditions:	
	Flight Line	Mission Line	Begin:	End:	Direction	GPS Altitude	Speed	MM Space	S/Vs	AVG PDOP	AVG HDOP	Comr	nents and Conditions:
	234	234 N	21:15		2°	4278	130	7153	21	1.2	0.7	failed	to change state of lidar
	234	234 N	21:32	21:36	1°	4271	131	7152	19	1.3	0.7		
	233	233 S	21:40	21:44	181°	4288	166	7132	17	1.5	0.8		
	232	232 N	21:49	21:54	359°	4245	137	7113	17	1.4	0.8		
	231	231 S	21:59	22:03	180°	4303	160	7087	19	1.1	0.7		
	230	230 N	22:09	22:15	0°	4275	136	7064	19	1.1	0.7		
	229	229 S	22:19	22:25	182°	4325	162	7033	20	1.1	0.7		
	228	228 N	22:29	22:35	0°	4278	141	7008	19	1.2	0.8		
	227	227 S	22:39	22:44	180°	4315	165	6980	19	1.2	0.8		
	226	226 N	22:50	22:56	0°	4297	135	6953	19	1.2	0.7		
	225	225 S	23:01	23:06	180°	4325	164	6924	19	1.2	0.7		
	224	224 N	23:11	23:17	358°	4250	137	6900	21	1.2	0.7		
	223	223 S	23:21	23:30	181°	4257	163	6870	24	1.1	0.6		
	222	222 N	23:36	23:46	358°	4240	142	6825	24	1.2	0.6		
	221	221 S	23:50	24:00	178°	4282	162	6772	24	1.2	0.6		
	220	220 N	24:05	24:15	0°	4282	140	6727	23	1.2	0.6		
	219	219 S	24:19	24:29	180°	4300	161	6677	24	1.1	0.6		



Droject/E	light Plan:	La Cat	Con_TM		Lift	Temp °C	Before	Temp	°C After	Press	ure (kPa)		Sensor Operator	
Project/F	light Plan.	La_Cat_			2	7		13 30.01			0.01	Geoffrey McCall		
Date/J	Julian:	12/3/2019			Disk Driv	e			Sensor				Pilot	
Hobb	os End	2114.9		TM	MM30 (10	3, 104)			TM_90524			1	Mike Wasielewski	
Hobl	bs ST	2111		TARGET	MSL	Target AIRSPD	Base Name	PID	Base Name	PID	Base Height	Aircraft	Airport Identifcation:	
Flight	Time	3.9		4,31	.4	160	KHEZ01		KHEZ02		1.500	C421-N112MJ	KHEZ (Natchez, MS)	
	ellaha dia a		UTC	time:	D ¹		Grand	Available	c.hu	Position Acc.				
Ζ	Flight Line	Mission Line	Begin:	End:	Direction	GPS Altitude	Speed	MM Space	S/Vs	AVG PDOP	AVG HDOP	Comn	nents and Conditions:	
	236	236 N	15:39	15:40	1°	4304	148	6632	19	1.2	0.6			
	235	235 S	15:45	15:46	179°	4290	155	6627	18	1.3	0.7			
	218	218 S	15:54	16:04	181°	4262	161	6623	18	1.3	0.7			
	217	217 N	16:08	16:20	0°	4260	152	6570	20	1.2	0.7			
	216	216 S	16:26	16:37	179°	4186	159	6515	21	1.1	0.7			
	215	215 N	16:41	16:52	1°	4180	157	6461	20	1.3	0.7			
	214	214 S	16:57	17:08	185°	4250	154	6404	21	1.2	0.7			
	213	213 N	17:13	17:25	359°	4240	158	6347	22	1.3	0.7			
	212	212 S	17:29	17:41	180°	4236	159	6291	26	1.1	0.6			
	211	211 N	17:45	17:57	0°	4236	157	6232	25	1.1	0.6			
	210	210 S	18:01	18:13	180°	4229	159	6172	22	1.2	0.7			
	209	209 N	18:17	18:31	0°	4226	158	6110	26	1.2	0.6			
	208	208 S	18:35	18:50	180°	4227	156	6040	27	1.0	0.6			
	207	207 N	18:53	19:08	2°	4232	163	5966	24	1.2	0.7			



Drainat/F	icht Dien.	1	Co., TM		Lift	Temp °C	Before	Temp	°C After	Press	ure (kPa)		Sensor Operator				
Project/F	light Plan:	La_Cat_	Con_TM		3	15			7	2	9.69		Geoffrey McCall				
Date/J	Iulian:	12/3/2019			Disk Driv	e			Sensor				Pilot				
Hobb	s End	2118.1		TM	I MM30 (10	3, 104)	TM_90524					n	Mike Wasielewski				
Hobl	bs ST	2114.9		TARGET	MSL	Target AIRSPD	Base Name	PID	Base Name	PID	Base Height	Aircraft	Airport Identifcation:				
Flight	Time	3.2		4,31	14	160	KHEZ01		KHEZ02		1.500	C421-N112MJ	KHEZ (Natchez, MS)				
	Flight Line	Missian Line	UTC	time:	Discotion	GPS Altitude	Ground	Available	Available	Available	Available	Available	c hu	Position Acc.		6	
Ζ	Flight Line	Mission Line	Begin:	End:	Direction	GPS Altitude	Speed	MM Space	S/Vs	AVG PDOP	AVG HDOP	Comn	nents and Conditions:				
	206	206 S	21:43	21:58	180°	4214	160	5892	18	1.4	0.8						
	205	205 N	22:02	22:19	2°	4235	157	5817	19	1.3	0.8						
	204	204 S	22:23	22:40	182°	4249	159	5731	21	1.2	0.7						
	203	203 N	22:43	22:59	0°	4250	155	5645	21	1.3	0.7						
	202	203 S	23:05	23:22	184°	4258	155	5558	22	1.2	0.6						
	201	201 N	23:26	23:42	358°	4256	153	5474	23	1.1	0.6						
	200	200 S	23:47	24:03	180°	4267	162	5387	24	1.2	0.6						
	199	199 N	24:07		358°	4242	153	5300	22	1.2	0.6	*0022 Screen	frozen config error on sensor				
					ļ												
					ļ												
					ļ												
					ļ												
					ļ		ļ										
					ļ												



		Th4 CA			Lift	Temp °C	Before	Temp '	°C After	Press	ure (kPa)	:	Sensor Operator
Project/F	light Plan:	IWI_CA	T_CORD		4	11		1	.8	10)1.69		Geoffrey McCall
Date/J	Iulian:	12.4.19		Disk Drive					Sensor				Pilot
Hobb	s End	2121.9		TM	I MM30 (10	7, 108)			TM_90524				Wes Ashmore
Hobl	bs ST	2118.1		TARGET	MSL	Target AIRSPD	Base Name	PID	Base Name	PID	Base Height	Aircraft	Airport Identifcation:
Flight	Time	3.8		4,20	00	160	KHEZ01		KHEZ02		1.500	C421_N811A KHEZ (Natchez, MS)	
,	Flight Line	Mission Line	UTC	time:	Direction	GPS Altitude	Groud	Available	Position Acc.		Comments and Conditions:		
Ζ	Fight Line	WISSION LINE	Begin:	End:	Direction	GPS Altitude	Speed	MM Space	S/Vs	AVG PDOP	AVG HDOP	Comm	nents and conditions.
	199	199	15:48	16:04	180°	4233	159	7153	18	1.2	0.6		
	198	198	16:08	16:24	359°	4214	158	7065	20	1.2	0.7		
	197	197	16:28	169:45	178°	4235	163	6979	20	1.3	0.8		
	196	196	16:49	17:06	1°	4242	156	68891	19	1.4	0.8		
	195	195	17:10	17:26	180°	4260	159	6805	22	1.3	0.7		
	194	194	17:30	17:46	359°	4236	159	6720	25	1.2	0.6		
	193	193	17:50	18:06	179°	4257	160	6639	25	1.1	0.6		
	192	192	18:10	18:25	359°	4144	162	6558	22	1.3	0.7		
	191	191	18:29	18:45	179°	4189°	166	6476	27	1.0	0.6		
	190	190	18:48	19:04	0°	4177°	163	6395	22	1.2	0.7		



	light Plan:	The Co	T_CORD		Lift	Temp °C	Before	Temp	°C After	Press	ure (kPa)		Sensor Operator	
	light Plan:	TWI_CA			5	19		1	11	10)1.79		Geoffrey McCall	
Date/J	Julian:	12.4.19			Disk Driv	e			Sensor				Pilot	
Hobb	os End	2125.5		TN	I MM30 (10	7, 108)		TM_90524				١	Aike Wasielewski	
Hobl	bs ST	2121.9		TARGET	r MSL	Target AIRSPD	Base Name	PID	Base Name	PID	Base Height	Aircraft	Airport Identifcation:	
Flight	t Time	3.6		4,20	00	160	KHEZ01		KHEZ02		1.500	C421_N811A	KHEZ (Natchez, MS)	
,	Flight Line	Mission Line	UTC	time:	Discotion	CDC Altitude	Grand	Available	Available	S/Vs	Position Acc.		6	nents and Conditions:
Ζ	Flight Line	Wission Line	Begin:	End:	Direction	GPS Altitude	Speed	MM Space	5/ VS	AVG PDOP	AVG HDOP	Comin	nents and conditions:	
	189	189	21:24	21:39	178°	4266	160	6311	20	1.4	0.7			
	188	188	21:43	21:59	359°	4228	153	6231	20	1.3	0.7			
	187	187	22:02	22:17	179°	4276	159	6148	19	1.1	0.7			
	186	186	22:21	22:37	0°	4180	152	6073	20	1.1	0.7			
	185	185	22:40	22:55	182°	4213	159	5995	18	1.4	0.8			
	184	184	22:59	23:14	1°	4208	149	5921	18	1.4	0.7			
	183	183	23:18	23:32	181°	4246	165	5841	20	1.2	0.6			
	182	182	23:36	23:52	359°	4220	150	5764	21	1.2	0.6			
	181	181	23:56	:10	179°	4255	159	5682	21	1.2	0.6			
	180	180	:14	:29	0°	4250	149	5609	19	1.2	0.6			



Project/F	light Dlan:	TM CA	T_CORD		Lift	Temp °C	Before	Temp '	°C After	Press	ure (kPa)		Sensor Operator
Project/F	iigiit Fiaii.	IW_CA			1	8			2	10)3.15		Cynthia Williams
Date/.	Julian:	12.11.19			Disk Driv	e			Sensor				Pilot
Hobb	os End	4860.3		TM	MM30 (10	5, 106)			TM_90524				Wes Ashmore
Hob	bs ST	4856.4		TARGET	MSL	Target AIRSPD	Base Name	PID	Base Name	PID	Base Height	Aircraft	Airport Identifcation:
Flight	: Time	3.9		4,20	00	160	KHEZ01		KHEZ02		1.500	C421_N811A	KHEZ (Natchez, MS)
			UTC	time:				Available	<i></i>	Posit	ion Acc.		
Ζ	Flight Line	Mission Line	Begin:	End:	Direction	GPS Altitude	Speed	MM Space	S/Vs	AVG PDOP	AVG HDOP	Comr	nents and Conditions:
	179	179	:16	:31	181°	4280	157	5220	20	1.3	0.7	g	imbal pav missing
	178	178	:34	:49	1°	4264	156	5142	18	1.3	0.7		
	177	177	:52	1:06	179°	4286	131	5068	20	1.2	0.6		
	176	176	11:11	1:27	0°	4216	154	4988	21	1.2	0.6		
	175	175	1:30	1:46	180°	4235	148	4910	22	1.2	0.6		
	174	174	1:49	2:06	361°	4217	143	4819	23	1.2	0.6		
	173	173	2:09	2:24	180°	4273	141	4654	23	1.3	0.7		
	172	172	2:29		359°	4228	155	4670	23	1.3	0.7	hea	rt beat error airstart
ļ													
ļ													
ļ													



Droject/El	light Plan:	TM CA	T_CORD		Lift	Temp °C	Before	Temp '	°C After	Press	ure (kPa)		Sensor Operator
Project/Fi	ligitt Fiall.	IW_CA			2	16			8	10)2.30		Cynthia Williams
Date/J	Julian:	12.12.19			Disk Driv	e			Sensor				Pilot
Hobb	os End	4860.3		TM	I MM30 (10	5, 106)			TM_90524				Wes Ashmore
Hobl	bs ST	4856.4		TARGET	MSL	Target AIRSPD	Base Name	PID	Base Name	PID	Base Height	Aircraft	Airport Identifcation:
Flight	: Time	3.9		4,20	00	160	KHEZ01		KHEZ02		1.500	C421_N811A	KHEZ (Natchez, MS)
	Flight Line		UTC	time:	Discotion	CDC Altitude	Creard	Available	c hu	Posit	ion Acc.	6	
Ζ	Flight Line	Mission Line	Begin:	End:	Direction	GPS Altitude	Speed	MM Space	S/Vs	AVG PDOP	AVG HDOP	Comin	nents and Conditions:
	172	172	15:31	151:47	180°	4249°	157	4659	20	12	0.7		
	171	171	15:50	16:06	359°	4245°	156	4579	21	1.1	0.6		
	170	170	16:09	16:25	180°	4244°	154	4411	19	1.4	0.7		
	169	169	16:37	16:53	356°	4232°	162	4395	20	1.3	0.7		
	168	168	16:56	17:13	8°	4229°	151	4307	24	1.2	0.6		
	167	167	17:16	17:33	178°	4227°	157	4220	24	1.1	0.6		
	166	166	17:36	17:52	359°	4210°	157	4132	25	1.1	0.6		
	165	165	17:55	18:12	151°	4212°	155	4208	26	1.0	0.6	clo	uds at end 35 miles
	154	154	18:15	18:31	359°	4186°	147	4180	22	1.2	0.7		
	153	153	18:32	18:48	179°	4238°	159	4238	24	1.1	0.6		
					ļ								
ļ													
ļ													



Droject/E	light Plan:	TM CA	T_CORD		Lift	Temp °C	Before	Temp '	°C After	Press	ure (kPa)		Sensor Operator
FIOJECI/F	ligiti Fiali.	TW_CA			3	16			8	10)2.30		Cynthia Williams
Date/	Julian:	12.12.19			Disk Driv	e			Sensor				Pilot
Hobb	os End	4861.5		TM	MM30 (10	7, 108)			TM_90524				Wes Ashmore
Hob	bs ST	4860.3		TARGET	MSL	Target AIRSPD	Base Name	PID	Base Name	PID	Base Height	Aircraft	Airport Identifcation:
Flight	t Time	1.2		4,20	00	160	KHEZ01		KHEZ02		1.500	C421_N811A	KHEZ (Natchez, MS)
,	Flight Line	Mission Line	UTC	time:	Direction	GPS Altitude	Speed	Available	S/Vs	Posit	ion Acc.	Comr	nents and Conditions:
Ζ	right Line		Begin:	End:	Direction	GF5 Altitude	Speed	MM Space	3/ 13	AVG PDOP	AVG HDOP	Conn	nents and conditions.
	152	152	20:07	20:16	6°	4210°	169	5527	21	1.4	0.7		pav
	151	151	20:19	20:34	179°	4186°	148	5445	24	1.1	0.6	c	louds at 6.85 end



Droject/E	light Plan:	TM CA	T_CORD		Lift	Temp °C	Before	Temp '	°C After	Press	ure (kPa)		Sensor Operator
FIOJECI	ligiti Fiall.	IW_CA			4	17		1	.3	10)1.19		Cynthia Williams
Date/J	Julian:	12.14.19			Disk Driv	e			Sensor				Pilot
Hobb	os End	4864.6		TM	MM30 (10	3, 104)			TM_90524				Wes Ashmore
Hobl	bs ST	4861.5		TARGET	MSL	Target AIRSPD	Base Name	PID	Base Name	PID	Base Height	Aircraft	Airport Identifcation:
Flight	t Time	3.1		4,20	00	160	KHEZ01		KHEZ02		1.500	C421_N811A	KHEZ (Natchez, MS)
	ella ha d'an		UTC	time:	D ¹		Caraad	Available	chu	Posit	ion Acc.		
Ζ	Flight Line	Mission Line	Begin:	End:	Direction	GPS Altitude	Speed	MM Space	S/Vs	AVG PDOP	AVG HDOP	Comin	nents and Conditions:
	165	165	21:14	21:18	181°	4218°	158	5728	19	1.2	0.7		refly gimbal pav
	164	164	21:21	21:23	355°	4225°	156	5712	17	1.5	0.8		
	163	163	21:40	21:56	182°	4216°	159	5626	19	1.2	0.7		
	162	162	22:00	22:16	360°	4232°	156	5540	18	1.4	0.7		
	161	161	22:19	22:35	184°	4214°	157	5451	19	1.5	0.8		
	160	160	23:38	22:54	359°	4234°	156	5363	21	1.2	0.7		
	159	159	22:57	23:14	180°	4221°	159	5276	22	1.3	0.7		
	158	158	23:17	23:32	1°	4242°	158	5189	20	1.3	0.7		
	157	157	23:34	23:50	181°	4244°	154	5107	19	1.4	0.7		



Project/Fl	ight Dian.	TNA CA	T_CORD		Lift	Temp °C	Before	Temp '	°C After	Press	ure (kPa)		Sensor Operator
FIOJECU	igiit Fiaii.	IW_CA			5	10			7	10)1.46		Cynthia Williams
Date/J	ulian:	12.14.19			Disk Driv	e			Sensor				Pilot
Hobb	s End	4868.1		TM	I MM30 (10	3, 104)			TM_90524				Wes Ashmore
Hobb	os ST	4864.6		TARGET	MSL	Target AIRSPD	Base Name	PID	Base Name	PID	Base Height	Aircraft	Airport Identifcation:
Flight	Time	3.5		4,20	00	160	KHEZ01		KHEZ02		1.500	C421_N811A	KHEZ (Natchez, MS)
	Flight Line	Mission Line	UTC	time:	Direction	GPS Altitude	Speed	Available	S/Vs	Posit	ion Acc.	Comm	nents and Conditions:
	Fight Line	WISSION LINE	Begin:	End:	Direction	GPS Altitude	Speed	MM Space	3/ VS	AVG PDOP	AVG HDOP	Com	ients and conditions.
	144	144	1:14	1:29	182°	4247°	151	5025	1.2	0.6			
	145	145	1:32	1:46	359°	4261°	156	4932	1.2	0.6			roll mount
	146	146	1:49	2:05	180°	4240°	154	4851	1.3	0.6			
	147	147	2:08	2:22	390°	4252°	158	4760	1.3	0.6			
	148	148	2:26	2:41	180°	4241°	154	4673	1.1	0.6			
	149	149	2:44	2:59	360°	4248°	163	4581	1.3	0.7			
	150	150	3:02	3:19	180°	4247°	155	4494	1.1	0.7			
	151	151	3:20	3:23	360°	4269°	160	4406	1.2	0.7			
	155	155	3:31	3:46	353°	4272°	152	4392	1.3	0.8			
	156	156	3:49	4:05	180°	4246°	155	4308	1.3	0.8			
					<u> </u>								
					<u> </u>								



Appendix B. Basestation GPS Session Forms



Contract	t # / TO #		Client /	Project Nar	ne				Date
				-		Denver, C	olorado		
G16PC0	0044				ncordia_20				12.02.2019
DAS Pro	ject No.		Survey I					Operato	or Name
18003			DAS					Geoffre	y McCall
Monume	ent Name/D	esiginatio	n			Exact S	tamping (in	clude photo	o in survey report)
KHEZ01						n/a			
Monume	ent No./PID		Collectio	on Type (ci	rcle one)	File Na	me (receiver	generated)
n/a			ABGPS	STATIC	RTK	6684_1	202_114221.	.m 00	
Receiver	r Manufact	urer		Receive	r Model			Receive	r Serial No.
N/A				N/A				N/A	
Data Col	llector Man	ufacturer		Data Co	llector Mod	lel		Data Co	llector Serial No.
Leica				GS15				1506684	L .
Antenna	Part No.			Antenna	Model			Antenna	a Serial No.
4255298				N/A				N/A	
Starting	Antenna H	leight in Fe	et	Starting	Antenna H	eight in M	eters	Type of	Measurement (circle one)
1	2	3	AVG	1	2	3	AVG 1.5	TRUE V	ERTICAL ARP
Ending A	Antenna He	eight in Fee	et	Ending	Antenna He	eight in Me		Type of	Measurement (circle one)
1	2	3	AVG	1	2	3	AVG 1.5	TRUE V	ERTICAL ARP
Antenna	Reference	Point (inc	lude and ref	ference a di	mensional c	liagram in	Survey Repo	ort)	
(e.g., bot	ttom edge o	of notch in g	round plane	, Page 5, F	igure 2)				
Start Dat	te (UTC)			Start Tir	ne (UTC)			Approx	Lat. (if available)
12.02.20 ⁻	-			20:40					56.47358
End Date	e (UTC)			End Tim	e (UTC)			Approx.	Long. (if available)
12.03.20	19			1:55				W 911	7 38.70616
			nd/or proble		Site Diag	gram/Setu	p-Photo		
	ce and during		on, include	e ame of					
									T
								C. Sarahar	11-1
								a former	
								Jac	
								A dec	



Contrac	t # / TO #		Client /	Project Nar	ne				Date
				-	SURVEY	Denver, Co	olorado		
G16PC0					ncordia_20 ⁻	17_D17			12.03.2019
DAS Pro	oject No.		Survey I	Firm				Operato	or Name
18003			DAS						y McCall
Monume	ent Name/D	Desiginatio	n			Exact S	tamping (in	clude photo	o in survey report)
KHEZ01						n/a			
Monume	ent No./PID		Collectio	on Type (ci	rcle one)	File Nar	ne (receiver	generated)
n/a			ABGPS	STATIC	RTK	6684_12	203_065206	.m00	
Receive	r Manufact	urer		Receive	r Model			Receive	er Serial No.
N/A				N/A				N/A	
Data Co	llector Mar	nufacturer		Data Co	llector Mod	lel		Data Co	llector Serial No.
Leica				GS15				1506684	L Contraction of the second
Antenna	a Part No.			Antenna	Model			Antenna	a Serial No.
4255298	8			N/A				N/A	
Starting	Antenna H	leight in Fe	et	Starting	Antenna H	eight in M	eters	Type of	Measurement (circle one)
1	2	3	AVG	1	2	3	AVG 1.5	TRUE V	ERTICAL ARP
Ending	Antenna H	eight in Fee	et	Ending	Antenna He	eight in Me	eters	Type of	Measurement (circle one)
1	2	3	AVG	1	2	3	AVG 1.5	TRUE V	ERTICAL ARP
		•				liagram in S	Survey Repo	ort)	
(e.g., bo	ttom edge c	of notch in g	round plane	, Page 5, F	igure 2)				
Start Da	te (UTC)			Start Tir	ne (UTC)			Approx	. Lat. (if available)
12.03.20				15:15					56.47358
End Dat	e (UTC)			End Tim	e (UTC)			Approx	. Long. (if available)
12.04.20				1:55				W 911	7 38.70616
	-	rmalites ar	•		Site Diag	gram/Setu	p-Photo		
	tered durin	g the sessi ration.	on, include	ame of					
									T
								C. Samer	11-1
								1	
							5.4	- Leon	
								A	
									CALL X AND
							14		ANT AND AND A REASON OF A STATE



Contrac	t # / TO #		Client /	Project Nar	ne				Date
				•	SURVEY	Denver, C	olorado		
G16PC0	0044				ncordia_20 ⁻	17_D17			12.04.2019
DAS Pro	oject No.		Survey I	Firm				Operato	or Name
18003			DAS					Geoffre	y McCall
Monume	ent Name/E	Desiginatio	n			Exact S	tamping (in	clude photo	o in survey report)
KHEZ01						n/a			
Monume	ent No./PID)	Collectio	on Type (ci	rcle one)	File Na	ne (receiver	generated)
n/a			ABGPS	STATIC	RTK	6684_12	204_065220	.m00	
Receive	r Manufact	urer		Receive	r Model			Receive	er Serial No.
N/A				N/A				N/A	
Data Co	llector Mar	nufacturer		Data Co	llector Mod	lel		Data Co	ollector Serial No.
Leica				GS15				1506684	4
Antenna	a Part No.			Antenna	Model			Antenna	a Serial No.
4255298	3			N/A				N/A	
Starting	Antenna H	leight in Fe	et	Starting	Antenna H	eight in M	eters	Type of	Measurement (circle one)
1	2	3	AVG	1	2	3	AVG 1.5	TRUE V	ERTICAL ARP
Ending	Antenna H	eight in Fee	et	Ending	Antenna He	eight in Me	eters	Type of	Measurement (circle one)
1	2	3	AVG	1	2	3	AVG 1.5	TRUE V	ERTICAL ARP
						liagram in	Survey Repo	ort)	
(e.g., bo	ttom edge o	of notch in g	round plane	, Page 5, F	igure 2)				
Start Da	te (UTC)			Start Tir	ne (UTC)			Approx	. Lat. (if available)
12.04.20)19			15:10				N 31 36	56.47358
End Dat	te (UTC)			End Tim	e (UTC)			Approx	. Long. (if available)
12.05.20)19			1:40				W 911	7 38.70616
	-		nd/or proble		Site Diag	gram/Setu	p-Photo		
		-	on, include	e time of					
occuran	ice and dui	auon.							
									-
								The season	/17
								and f	
								- Ade	
								C. D. Ki	



Contrac	t # / TO #		Client /	Project Nar	ne				Date
				•	SURVEY	Denver, Co	olorado		
G16PC0					ncordia_20 ⁻	17_D17			12.02.2019
DAS Pro	oject No.		Survey I	Firm				Operato	or Name
18003			DAS						y McCall
Monume	ent Name/D	Desiginatio	n			Exact S	tamping (in	clude photo	o in survey report)
KHEZ02						n/a			
Monume	ent No./PID		Collectio	on Type (ci	rcle one)	File Nar	ne (receiver	generated)
n/a			ABGPS	STATIC	RTK	1514_12	202_144732	.m00	
Receive	r Manufact	urer		Receive	r Model			Receive	er Serial No.
N/A				N/A				N/A	
Data Co	llector Mar	nufacturer		Data Co	llector Mod	lel		Data Co	llector Serial No.
Leica				GS15				1501514	L Contraction of the second
Antenna	a Part No.			Antenna	Model			Antenna	a Serial No.
3725413	8			N/A				N/A	
Starting	Antenna H	leight in Fe	et	Starting	Antenna H	eight in M	eters	Type of	Measurement (circle one)
1	2	3	AVG	1	2	3	AVG 1.5	TRUE V	ERTICAL ARP
Ending	Antenna H	eight in Fee	et	Ending	Antenna He	eight in Me	eters	Type of	Measurement (circle one)
1	2	3	AVG	1	2	3	AVG 1.5	TRUE V	ERTICAL ARP
						liagram in S	Survey Repo	ort)	
(e.g., bo	ttom edge c	of notch in g	round plane	, Page 5, F	igure 2)				
Start Da	te (UTC)			Start Tir	ne (UTC)			Approx	. Lat. (if available)
12.02.20	019			20:45					56.48549
End Dat	e (UTC)			End Tim	e (UTC)			Approx	. Long. (if available)
12.03.20)19			2:00				W 911	7 39.44453
	-	rmalites ar	-		Site Diag	gram/Setu	p-Photo		
	tered durin	g the sessi ration.	on, include	etime of					
eesaran									
									T
								C. Larrison	11-1
								- A	
								1	
							S	1	
								A.	
							14	The second	AND A REAL PARTY AND A REAL



Contract # / TO #		Client / I	Project Nar	ne				Date
G16PC00044			-	L SURVEY	Denver, C	olorado		12.03.2019
G10FC00044				ncordia_20 ⁻	17_D17			12.03.2019
DAS Project No.		Survey I	Firm				Operato	or Name
18003		DAS					Geoffre	y McCall
Monument Name/D	Desiginatio	n			Exact S	Stamping (in	clude photo	o in survey report)
KHEZ02					n/a			
Monument No./PID)	Collectio	on Type (ci	ircle one)	File Na	me (receiver	generated)
n/a		ABGPS	STATIC	RTK	1514_1	203_095647.	.m00	
Receiver Manufact	urer		Receive	r Model			Receive	er Serial No.
N/A			N/A				N/A	
Data Collector Mar	nufacturer		Data Co	llector Mod	lel		Data Co	ollector Serial No.
Leica			GS15				1501514	4
Antenna Part No.			Antenna	a Model			Antenna	a Serial No.
3725413			N/A				N/A	
Starting Antenna H	leight in Fe	et	Starting	Antenna H	eight in M	leters	Type of	Measurement (circle one)
1 2	3	AVG	1	2	3	AVG 1.5	TRUE V	ERTICAL ARP
Ending Antenna H	eight in Fee	et	Ending	Antenna He	eight in Me	eters	Type of	Measurement (circle one)
1 2	3	AVG	1	2	3	AVG 1.5	TRUE V	ERTICAL ARP
Antenna Reference	e Point (inc	lude and ref	erence a di	mensional c	liagram in	Survey Repo	ort)	
(e.g., bottom edge o	of notch in g	round plane	, Page 5, F	igure 2)				
Start Date (UTC)			Stort Tir	ne (UTC)			A 19 19 19 19 19	. Lat. (if available)
Start Date (UTC)			Start III	ne (01C)				
12.03.2019			15:20					56.48549
End Date (UTC)			End Tim	ne (UTC)			Approx	. Long. (if available)
12.04.2019			2:00				W 911	7 39.44453
Describe any abno				Site Diag	gram/Setu	p-Photo		
encountered durin		on, include	e time of					
occurance and dur	allon.							
								-
						-		
						1	A STATE OF	//1
							1	
						1	- Atte	
								States of the France of the Fr
							- Det	



Contract # / TO #	Client /	Project Nar	ne				Date
		•		Denver. Co	olorado		
G16PC00044			ncordia_20 ⁷				12.04.2019
DAS Project No.	Survey I					Operato	or Name
18003	DAS					Geoffre	y McCall
Monument Name/Desiginatio	n			Exact S	tamping (in	clude photo	o in survey report)
KHEZ02				n/a			
Monument No./PID	Collectio	on Type (ci	rcle one)	File Nar	ne (receiver	generated)
n/a	ABGPS	STATIC	RTK	1514_12	204_095714.	.m00	
Receiver Manufacturer		Receive	r Model			Receive	er Serial No.
N/A		N/A				N/A	
Data Collector Manufacturer		Data Co	llector Mod	el		Data Co	llector Serial No.
Leica		GS15				1501514	l .
Antenna Part No.		Antenna	a Model			Antenna	a Serial No.
3725413		N/A				N/A	
Starting Antenna Height in Fe		Starting	Antenna H	eight in M	eters	Type of	Measurement (circle one)
1 2 3	AVG	1	2	3	AVG 1.5	TRUE V	ERTICAL ARP
Ending Antenna Height in Fe	et	Ending	Antenna He	eight in Me	ters	Type of	Measurement (circle one)
1 2 3	AVG	1	2	3	AVG 1.5	TRUE V	ERTICAL ARP
Antenna Reference Point (inc (e.g., bottom edge of notch in g				liagram in S	Survey Repo	ort)	
Start Date (UTC)		Start Tir	ne (UTC)			Approx	. Lat. (if available)
12.04.2019		15:15				N 31 36	56.48549
End Date (UTC)		End Tim	e (UTC)			Approx	. Long. (if available)
12.05.2019		1:45				W 911	7 39.44453
Describe any abnormalites an encountered during the sessi occurance and duration.			Site Diag	gram/Setu	p-Photo		



Contract # / TO #	Client /	Project Nar	me			Date
		EOLOGICAL		Denver, Co	lorado	
G16PC00044	LA_Cata	ahoula_Cor	ncordia_20	17_D17		12.11.2019
DAS Project No.	Survey I	Firm				Operator Name
18003	DAS					Cynthia Williams
Monument Name/Desigination	n			Exact St	amping (in	nclude photo in survey report)
KHEZ01				n/a		
Monument No./PID	Collection	on Type (ci	rcle one)	File Nan	ne (receiver	r generated)
n/a	ABGPS	STATIC	RTK	6684_12	11_151504	l.m00
Receiver Manufacturer		Receive	r Model			Receiver Serial No.
N/A		N/A				N/A
Data Collector Manufacturer		Data Co	llector Mod	lel		Data Collector Serial No.
Leica		GS15				1506684
Antenna Part No.		Antenna	Model			Antenna Serial No.
4255298		N/A				N/A
Starting Antenna Height in Fe			Antenna H	leight in Me		Type of Measurement (circle one)
1 2 3	AVG	1	2	3	AVG 1.5	TRUE VERTICAL ARP
Ending Antenna Height in Fee	et	Ending	Antenna He	eight in Me		Type of Measurement (circle one)
1 2 3	AVG	1	2	3	AVG 1.5	TRUE VERTICAL ARP
Antenna Reference Point (inc (e.g., bottom edge of notch in g				diagram in S		
(e.g., bollon eage of noton in g	llound plane	, гау с э, т	igure zj			
Start Date (UTC)		Start Tir	me (UTC)			Approx. Lat. (if available)
12.11.2019		22:14				N 31 36 56.50570
End Date (UTC)		End Tim	ne (UTC)			Approx. Long. (if available)
12.11.2019		2:15				W 91 17 38.72067
Describe any abnormalites ar	ad/or proble		Site Dia	gram/Setup	Photo	
encountered during the sessi			Sile Dia	grain/Setup)-F11010	
occurance and duration.						
						-
					-	
						11-1
					in 1	
					s	
					a file	
						and the second
					A State	



Contract # / TO #	Client / Project Name Date								
	EOLOGICAI		Denver, Co	olorado					
G16PC00044		ahoula_Cor			12.11.2019				
DAS Project No.	Survey	Firm				Operator Name			
18003	DAS					Cynthia Williams			
Monument Name/Desigination	n			Exact S	tamping (in	clude photo in survey report)			
KHEZ02		n/a							
-	0.0.0	T ()				eceiver generated)			
Monument No./PID	Collecti	on Type (ci	rcle one)	File Nan	ne (receiver	generated)			
n/a	ABGPS	GPS STATIC RTK 1514_1211_182304.m00							
Receiver Manufacturer		Receive	r Model			Receiver Serial No.			
N/A		N/A				N/A			
Data Collector Manufacturer		Data Collector Model				Data Collector Serial No.			
Leica		GS15				1501514			
Antenna Part No.		Antenna	Model			Antenna Serial No.			
3725413		N/A				N/A			
Starting Antenna Height in Fe	et	Starting	Antenna H	leight in Me	eters	Type of Measurement (circle one)			
1 2 3	AVG	1	2	3	AVG 1.5	TRUE VERTICAL ARP	>		
Ending Antenna Height in Fee	Ending Antenna Height in Feet Ending Antenr					Type of Measurement (circle one)			
1 2 3	AVG	1	2	3	AVG 1.5	TRUE VERTICAL ARP			
Antenna Reference Point (incl	lude and re	ference a di	mensional o	diagram in S		ort)			
(e.g., bottom edge of notch in g	pround plane	ə, Page 5, F	-igure 2)						
		•							
Start Date (UTC)	Start Time (UTC)				Approx. Lat. (if available)				
12.11.2019	22:25				N 31 36 56.52102				
End Date (UTC)		End Time (UTC)				Approx. Long. (if available)			
12.11.2019	2:15				W 91 17 39.45885				
Describe any abnormalites and/or problems Site Diagram/Setup-Photo									
encountered during the sessi occurance and duration.									
occurance and duration.									
						The second se			
					1				



Contract # / TO #	Client / Project Name Date							
	U. S. GEOLOGICAL SURVEY Denver, Colorado							
G16PC00044	LA_Catahoula_Concordia_2017_D17					12.12.2019		
DAS Project No.	Survey	Firm				Operator Name		
18003	DAS					Cynthia Williams		
Monument Name/Desigination	n			Exact Stamping (include photo in survey report)				
KHEZ01				n/a				
Monument No./PID	Collecti	on Type (ci	ircle one)	File Name (receiver generated)				
			,		•	°		
n/a	ABGPS STATIC RTK 6684_1211_151504.m00							
Receiver Manufacturer		Receiver Model				Receiver Serial No.		
N/A		N/A				N/A		
Data Collector Manufacturer		Data Collector Model				Data Collector Serial No.		
Leica		GS15				1506684		
Antenna Part No.		Antenna	Model			Antenna Serial No.		
4255298		N/A				N/A		
Starting Antenna Height in Fe	et	Starting	Antenna H	leight in Me	eters	Type of Measurement (circle one)		
1 2 3	AVG	1	2	3	AVG 1.5	TRUE VERTICAL ARP		
Ending Antenna Height in Fee	ət	Ending	Antenna He	eight in Me		Type of Measurement (circle one)		
1 2 3	AVG	1	2	3	AVG 1.5	TRUE VERTICAL		
Antenna Reference Point (include and reference a dimensional diagram in Survey Report)								
(e.g., bottom edge of notch in g	round plane	e, Page 5, F	igure 2)					
	Ctort Tir							
Start Date (UTC)		Start Time (UTC)				Approx. Lat. (if available)		
12.12.2019	13:45				N 31 36 56.50570			
End Date (UTC)		End Time (UTC)				Approx. Long. (if available)		
12.12.2019 20:04						W 91 17 38.72067		
Describe any abnormalites ar	nd/or proble	ems	Site Dia	gram/Setup	o-Photo			
encountered during the session, include tin								
occurance and duration.								
T								
						11 miles		
			and the second					
			and the second sec					



Contract # / TO #		Client / Project Name Date								
G16PC00044		•	L SURVEY							
	LA_Catahoula_Concordia_2017_D17					12.12.2019				
DAS Project No.	_	Survey I	Firm	_	_	_	Operator Name			
18003		DAS					Cynthia Williams			
Monument Name/Desig	ginatior	1		Exact Stamping (in				nclude photo in survey report)		
KHEZ02					n/a					
Monument No./PID		Collection	on Type (ci	ircle one)	File Nan	ne (receiver	r generated)			
n/a		ABGPS) STATIC	RTK	1514_12	211_182304	.m00			
Receiver Manufacturer	r		Receiver Model				Receiver	Serial No.		
N/A			N/A				N/A			
Data Collector Manufa	cturer		Data Collector Model				Data Collector Serial No.			
Leica			GS15	GS15				1501514		
Antenna Part No.			Antenna	a Model			Antenna Serial No.			
3725413			N/A				N/A			
Starting Antenna Heigl	ht in Fe	et	Starting	g Antenna H	leight in Me	eters	Type of Measurement (circle one)			
1 2	3	AVG	AVG 1 2 3 AVG					RTICAL ARP		
Ending Antenna Heigh	Ending Antenna Height in Feet Ending An				eight in Me	-	Type of N	Measurement (circle one)		
1 2	3	AVG	1	2	3	AVG 1.5	TRUE VE	RTICAL ARP		
Antenna Reference Point (include and reference a dimensional diagram in Survey Report)										
(e.g., bottom edge of no	otch in g	round plane	e, Page 5, F	-īgure 2)						
Start Date (UTC)	Start Time (UTC)				Approx. I	Lat. (if available)				
							N 31 36 56.52102			
12.12.2019			13:40							
End Date (UTC)		İ	End Time (UTC)				Approx. Long. (if available)			
12.12.2019	12.12.2019 20						W 91 17 39.45885			
Describe any abnorma				Site Dia	gram/Setu	p-Photo				
encountered during the session, include time of occurance and duration.										
	<i>"</i> .									

GPS SESSION FORM



Contract # / TO #	Client /	Project Nar	me			Date	
		•		Denver, Co	lorado		
G16PC00044		ahoula_Cor				12.14.2019	
DAS Project No.	Survey	Firm				Operator Name	
18003	DAS					Cynthia Williams	
Monument Name/Desigination	n			Exact St	tamping (in	clude photo in survey report)	
KHEZ01				n/a			
-	0.11.0.01	(-)			(<	
Monument No./PID	Collection	on Type (ci	rcle one)	File Nan	ne (receiver	r generated)	
n/a	ABGPS) STATIC	RTK	6684_12	11_151504		
Receiver Manufacturer		Receive	r Model			Receiver Serial No.	
N/A		N/A				N/A	
Data Collector Manufacturer		Data Co	llector Mod	lel		Data Collector Serial No.	
Leica		GS15			_	1506684	
Antenna Part No.		Antenna	Model			Antenna Serial No.	
4255298		N/A				N/A	
Starting Antenna Height in Fe	Starting	Antenna H	leight in Me	eters	Type of Measurement (circle one)		
1 2 3	AVG	1	2	3	AVG 1.5	TRUE VERTICAL ARP	
Ending Antenna Height in Fee	Ending	Antenna He	eight in Me		Type of Measurement (circle one)		
1 2 3	AVG	1	2	3	AVG 1.5	TRUE VERTICAL ARP	
Antenna Reference Point (inc.	lude and rea	ference a di	mensional (diagram in S			
(e.g., bottom edge of notch in g				-			
Start Date (UTC)		Start Tir	ne (UTC)			Approx. Lat. (if available)	
12.14.2019		19:32			_	N 31 36 56.50570	
End Date (UTC)		End Tim	End Time (UTC)			Approx. Long. (if available)	
12.14.2019		3:34				W 91 17 38.72067	
Describe any abnormalites ar	d/or proble	ome	Site Dia	gram/Setup	Photo		
encountered during the sessi			Olle Dia	yranii/oera _b	FILLO		
occurance and duration.	-						
					and the second		
					Contraction of the local diversion of the loc	//1	
					-		
					1		
					- he		
					- Art -		

GPS SESSION FORM



Contract # / TO #	Client /	Project Nar	me			Date	
		•		Denver, Co	olorado		
G16PC00044		ahoula_Cor				12.14.2019	
DAS Project No.	Survey	Firm				Operator Name	
18003	DAS					Cynthia Williams	
Monument Name/Desigination	n	Exact Stamping (inc				clude photo in survey report)	
KHEZ02		n/a					
Monument No./PID	Collecti	on Type (ci	ircle one)		ne (receiver	generated)	
			,			. ,	
n/a	ABGPS) STATIC	RTK	1514_12	211_182304	.m00	
Receiver Manufacturer		Receive	r Model			Receiver Serial No.	
N/A		N/A				N/A	
Data Collector Manufacturer		Data Co	llector Mod	lel		Data Collector Serial No.	
Leica		GS15				1501514	
Antenna Part No.		Antenna	Model			Antenna Serial No.	
3725413		N/A				N/A	
Starting Antenna Height in Fe	et	Starting Antenna Height in Meters				Type of Measurement (circle one)	
1 2 3	AVG	1	2	3	AVG 1.5	TRUE VERTICAL ARP	>
Ending Antenna Height in Fee	et	Ending	Antenna He	eight in Me		Type of Measurement (circle one)	
1 2 3	AVG	1	2	3	AVG 1.5	TRUE VERTICAL	
Antenna Reference Point (inc.	lude and rei	ference a di	imensional o	diagram in S		ort)	
(e.g., bottom edge of notch in g	round plane	ə, Page 5, F	-igure 2)				
		Oterst Tip	- (1170)				1
Start Date (UTC)			me (UTC)			Approx. Lat. (if available)	
12.14.2019		19:36				N 31 36 56.52102	
End Date (UTC)		End Tim	ne (UTC)			Approx. Long. (if available)	
12.14.2019		3:38				W 91 17 39.45885	
Describe any abnormalites ar			Site Dia	gram/Setup	p-Photo		
encountered during the sessi occurance and duration.	on, include	time of					
occurance and duration.							
						T	
					THE REAL PROPERTY OF		
					and the		
					a starter		
					1	201	
					A State		
					S. S. Same		



Appendix C. Vertical Accuracy Calculations





Project Information

Prepared By: DAS Project Name: G17PD1255: LA_Catahoula_Concordia_2017_D17 Sensor Info: TM90524 Required Nominal Pulse Spacing: 0.35 Vendor Name: Digital Aerial Solutions LLC Units: Meters Percent of Extent Tolerance: Extents Not Checked Date of Aquisition: Start: 1/24/2018 Finish: 12/15/2019

Metadata Information

Tile Index: Filename: Tile_Index_DAS_Delivery1_Use.shp Number of Polys: 0 Intensity: Tile Index Attribute: Not Specified Data Filename: Not Specified

DEM:

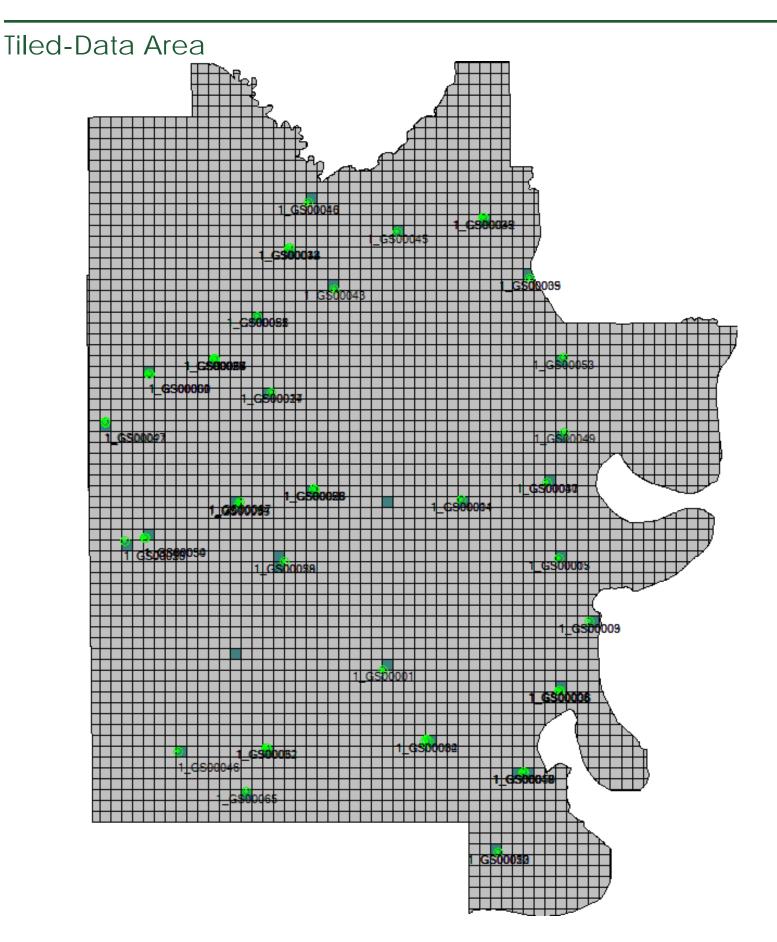
Tile Index Attribute: Name Data Filename: TIFF

LAS:

Tile Index Attribute: Name Data Filename: LAS











LiDAR Accuracy Assessment Summary

LC Туре	# Points	NVA	VVA	RMSE Z
LAS		95% Confidence	95 Percentile	
Bare Earth	18	0.163		0.083
High Vegetation	6		0.163	0.087
Low Vegetation	24		0.163	0.093
Med Vegetation	5		0.127	0.100
Urban Terrian	14	0.158		0.081
NVA Total:	32	0.161		0.082
VVA Total:	35		0.163	0.093
Total:	67			0.088
DEM		95% Confidence	95 Percentile	
Bare Earth	18	0.168		0.085
High Vegetation	6		0.161	0.089
Low Vegetation	24		0.186	0.098
Med Vegetation	5		0.130	0.100
Urban Terrian	14	0.158		0.081
NVA Total:	32	0.163		0.083
VVA Total:	35		0.176	0.097
Total:	67			0.088
			Units:	Meters





Coordinates and Offsets of Analyzed Locations

	ID		1		I	г
		Survey X	Survey Y	Z1	Z DEM	Z LAS
				LC Туре	ΔΖ ΔΕΜ	ΔZ LAS
✓	1_GS00002					
		625085.067	3475452.375	14.182	14.316	14.314
				Bare Earth	0.134	0.132
✓	1_GS00003					
		640044.118	3486471.016	24.642	24.765	24.765
				Bare Earth	0.123	0.123
>	1_GS00004					
		628279.633	3497672.884	16.624	16.738	16.738
				Bare Earth	0.114	0.114
>	1_GS00007					
		637248.915	3492276.021	16.461	16.532	16.532
				Bare Earth	0.071	0.071
>	1_GS00008					
		637294.59	3480113.842	24.97	25.048	25.038
				Bare Earth	0.078	0.068
>	1_GS00009					
		640058.895	3486478.4	26.32	26.408	26.396
				Bare Earth	0.088	0.076
✓	1_GS00010		_			_
		636204.663	3499312.685	16.899	16.974	16.972
				Bare Earth	0.075	0.073





	ID					T
		Survey X	Survey Y	Z1	Z DEM	Z LAS
				LC Type	ΔΖ ΔΕΜ	ΔZ LAS
~	1_GS00013					
		631644.674	3465227.496	13.612	13.641	13.643
				Bare Earth	0.029	0.031
~	1_GS00017					
		634003.396	3472614.767	15.221	15.22	15.223
				Bare Earth	-0.001	0.002
~	1_GS00018				1	
		605560.123	3510671.327	21.367	21.357	21.358
				Bare Earth	-0.01	-0.009
~	1_GS00020					
		631643.82	3465211.885	13.854	13.847	13.843
				Bare Earth	-0.007	-0.011
~	1_GS00021				1	
		595515.297	3504770.325	17.657	17.638	17.634
				Bare Earth	-0.019	-0.023
>	1_GS00022				· · · · · · · · · · · · · · · · · · ·	
		609481.409	3514627.253	31.193	31.157	31.157
				Bare Earth	-0.036	-0.036
~	1_GS00024	-				
		605549.053	3510662.067	21.622	21.562	21.565
				Bare Earth	-0.06	-0.057





	ID					
		Survey X	Survey Y	Z 1	Z DEM	Z LAS
				LC Type	ΔΖ ΔΕΜ	ΔZ LAS
~	1_GS00026					
		614720.819	3498682.782	17.413	17.335	17.342
				Bare Earth	-0.078	-0.071
~	1_GS00030					•
		599165.202	3494219.386	17.128	17.025	17.025
				Bare Earth	-0.103	-0.103
~	1_GS00031					
		599544.233	3509339.302	26.57	26.449	26.453
				Bare Earth	-0.121	-0.117
~	1_GS00033					•
		607809.779	3497279.117	17.238	17.085	17.089
				Bare Earth	-0.153	-0.149
~	1_GS00001					
		621026.397	3482034.442	16.477	16.601	16.596
				Urban Terrian	0.124	0.119
~	1_GS00005					-
		634583.74	3518053.574	19.976	20.081	20.077
				Urban Terrian	0.105	0.101
~	1_GS00006					
		637276.974	3480122.289	23.188	23.266	23.278
				Urban Terrian	0.078	0.09





	ID					_
		Survey X	Survey Y	Z1	Z DEM	Z LAS
		•		LC Type	ΔΖ ΔΕΜ	ΔZ LAS
>] 1_GS00011					
		628251.504	3497692.465	17.44	17.495	17.497
				Urban Terrian	0.055	0.057
>] 1_GS00012					
		612385.7	3520862.09	17.643	17.683	17.677
				Urban Terrian	0.04	0.034
>] 1_GS00015					
		637259.042	3492277.689	16.714	16.735	16.735
				Urban Terrian	0.021	0.021
>] 1_GS00016					
		614186.442	3525062.401	16.698	16.714	16.711
				Urban Terrian	0.016	0.013
>] 1_GS00019					
		633982.296	3472618.091	15.921	15.914	15.912
				Urban Terrian	-0.007	-0.009
>] 1_GS00023					-
		597248.794	3493929.788	16.344	16.292	16.293
				Urban Terrian	-0.052	-0.051
>] 1_GS00025					
		605521.26	3510657.335	22.29	22.235	22.229
				Urban Terrian	-0.055	-0.061





	ID					
		Survey X	Survey Y	Z1	Z DEM	Z LAS
				LC Туре	AZ DEM	ΔZ LAS
>	1_GS00027					
		610750.224	3507630.915	19.458	19.375	19.376
				Urban Terrian	-0.083	-0.082
>	1_GS00028					
		614729.876	3498650.112	17.365	17.268	17.276
				Urban Terrian	-0.097	-0.089
>	1_GS00029					•
		611970.997	3492011.484	17.59	17.481	17.485
				Urban Terrian	-0.109	-0.105
>	1_GS00032					
		610316.289	3474847.048	18.77	18.632	18.624
				Urban Terrian	-0.138	-0.146
>	1_GS00034					•
		625087.364	3475479.348	14.234	14.41	14.397
				Low Vegetation	0.176	0.163
>	1_GS00035					• •
		630290.688	3523686.524	16.926	17.112	17.094
				Low Vegetation	0.186	0.168
>	1_GS00036					
		637332.888	3480088.59	16.645	16.834	16.799
				Low Vegetation	0.189	0.154





	ID					
		Survey X	Survey Y	Z1	Z DEM	Z LAS
				LC Туре	AZ DEM	ΔZ LAS
>	1_GS00038					
		612413.586	3520881.676	17.325	17.475	17.474
				Low Vegetation	0.15	0.149
>	1_GS00039					
		634598.564	3518082.613	19.697	19.845	19.852
				Low Vegetation	0.148	0.155
>	1_GS00041					-
		636141.286	3499317.507	16.35	16.49	16.489
				Low Vegetation	0.14	0.139
>	1_GS00042					•
		630351.669	3523643.326	16.418	16.542	16.544
				Low Vegetation	0.124	0.126
>	1_GS00046					
		602186.752	3474507.917	15.38	15.465	15.456
				Low Vegetation	0.085	0.076
>	1_GS00047					
		595471.404	3504876.033	17.726	17.79	17.785
				Low Vegetation	0.064	0.059
>	1_GS00048					
		633938.842	3472612.297	14.454	14.512	14.515
				Low Vegetation	0.058	0.061





	ID					
		Survey X	Survey Y	Z1	Z DEM	Z LAS
				LC Type	AZ DEM	ΔZ LAS
>	1_GS00049					
		637798.94	3503926.008	17.726	17.762	17.762
				Low Vegetation	0.036	0.036
<	1_GS00050					
		634046.707	3472600.958	14.954	14.994	14.991
				Low Vegetation	0.04	0.037
K	1_GS00051					
		609463.448	3514608.815	30.93	30.949	30.953
				Low Vegetation	0.019	0.023
K	1_GS00052					
		631660.016	3465199.583	13.612	13.631	13.631
				Low Vegetation	0.019	0.019
K	1_GS00053					
		637666.765	3510772.162	18.24	18.254	18.266
				Low Vegetation	0.014	0.026
K	1_GS00054					
		599131.332	3494216.271	16.261	16.279	16.27
				Low Vegetation	0.018	0.009
<	1_GS00055					1
		609457.283	3514631.928	30.71	30.707	30.703
				Low Vegetation	-0.003	-0.007
		I I <t< td=""><td>Survey X□Survey X□1_GS00049□637798.94□637798.94□1_GS00050□634046.707□634046.707□1_GS00051□609463.448□609463.448□1_GS00052□631660.016□631660.016□637666.765□1_GS00054□599131.332□1_GS00055□1_GS00055</td><td>Survey XSurvey YI_GS00049I_GS00049G37798.94J_GS00050I_GS00050I_GS00051I_GS00051I_GS00052I_GS00052I_GS00053I_GS00053I_GS00053I_GS00054I_GS00054I_GS00053I_GS00055I_GS0055<</td><td>Image: Marking Survey X Survey Y Z1 Image: Marking Survey Y LC Type Image: Marking Survey A 3503926.008 17.726 Image: Marking Survey A 534046.707 3472600.958 14.954 Image: Marking Survey A 630465.707 3472600.958 14.954 Image: Marking Survey A 609463.448 3514608.815 30.93 Image: Marking Survey A 631660.016 3465199.583 13.612 Image: Marking Survey A 637666.765 3510772.162 18.24 Image: Marking Survey A 599131.332 3494216.271 16.</td><td>Image: Normal Survey X Survey Y Z1 Z DEM Image: Survey X Survey Y LC Type AZ DEM Image: Survey X Survey X LC Type AZ DEM Image: Survey X Survey X LC Type AZ DEM Image: Survey X Survey X Survey X LC Type AZ DEM Image: Survey X Survey X Survey X LC Type AZ DEM Image: Survey X Survey X Survey X LC Type AZ DEM Image: Survey X Survey X Survey X LC Type AZ DEM Image: Survey X Survey X Survey X Survey X Survey X Survey X Image: Survey X Survey X</td></t<>	Survey X□Survey X□1_GS00049□637798.94□637798.94□1_GS00050□634046.707□634046.707□1_GS00051□609463.448□609463.448□1_GS00052□631660.016□631660.016□637666.765□1_GS00054□599131.332□1_GS00055□1_GS00055	Survey XSurvey YI_GS00049I_GS00049G37798.94J_GS00050I_GS00050I_GS00051I_GS00051I_GS00052I_GS00052I_GS00053I_GS00053I_GS00053I_GS00054I_GS00054I_GS00053I_GS00055I_GS0055<	Image: Marking Survey X Survey Y Z1 Image: Marking Survey Y LC Type Image: Marking Survey A 3503926.008 17.726 Image: Marking Survey A 534046.707 3472600.958 14.954 Image: Marking Survey A 630465.707 3472600.958 14.954 Image: Marking Survey A 609463.448 3514608.815 30.93 Image: Marking Survey A 631660.016 3465199.583 13.612 Image: Marking Survey A 637666.765 3510772.162 18.24 Image: Marking Survey A 599131.332 3494216.271 16.	Image: Normal Survey X Survey Y Z1 Z DEM Image: Survey X Survey Y LC Type AZ DEM Image: Survey X Survey X LC Type AZ DEM Image: Survey X Survey X LC Type AZ DEM Image: Survey X Survey X Survey X LC Type AZ DEM Image: Survey X Survey X Survey X LC Type AZ DEM Image: Survey X Survey X Survey X LC Type AZ DEM Image: Survey X Survey X Survey X LC Type AZ DEM Image: Survey X Survey X Survey X Survey X Survey X Survey X Image: Survey X Survey X





	ID					
		Survey X	Survey Y	Z1	Z DEM	Z LAS
				LC Type	ΔΖ ΔΕΜ	ΔZ LAS
>	1_GS00056					
		597238.251	3493955.861	16.314	16.304	16.306
				Low Vegetation	-0.01	-0.008
>	1_GS00057					
		605534.822	3510655.156	21.832	21.821	21.815
				Low Vegetation	-0.011	-0.017
>	1_GS00059					
		614705.957	3498689.658	17.396	17.363	17.369
				Low Vegetation	-0.033	-0.027
>	1_GS00060					
		599505.497	3509314.153	26.194	26.15	26.147
				Low Vegetation	-0.044	-0.047
>	1_GS00061					
		610328.717	3474859.983	16.028	15.961	15.964
				Low Vegetation	-0.067	-0.064
>	1_GS00062				•	
		599491.493	3509318.178	24.44	24.363	24.377
				Low Vegetation	-0.077	-0.063
>	1_GS00067	-			-	
		607831.64	3497462.762	17.207	17.072	17.068
				Low Vegetation	-0.135	-0.139





	ID					
		Survey X	Survey Y	Z1	Z DEM	Z LAS
				LC Туре	AZ DEM	ΔZ LAS
>] 1_GS00040					
		614204.979	3525050.739	16.794	16.924	16.921
				Med Vegetation	0.13	0.127
>] 1_GS00043					
		616580.136	3517120.444	17.457	17.559	17.564
				Med Vegetation	0.102	0.107
>] 1_GS00044					-
		612441.09	3520852.796	17.083	17.168	17.179
				Med Vegetation	0.085	0.096
>] 1_GS00045					•
		622319.127	3522342.106	20.891	20.973	20.974
				Med Vegetation	0.082	0.083
>] 1_GS00066					
		599527.808	3509328.39	25.938	25.847	25.855
				Med Vegetation	-0.091	-0.083
>] 1_GS00014		-			
		610731.181	3507640.082	18.559	18.581	18.588
				High Vegetation	0.022	0.029
>] 1_GS00037				1	
		636119.478	3499320.122	16.251	16.412	16.414
				High Vegetation	0.161	0.163





		ID					
			Survey X	Survey Y	Z1	Z DEM	Z LAS
					LC Туре	AZ DEM	ΔZ LAS
4)	<	1_GS00058					
			611953.852	3491993.991	17.282	17.253	17.249
					High Vegetation	-0.029	-0.033
5)	>	1_GS00063					
			605537.709	3510638.599	21.644	21.581	21.593
					High Vegetation	-0.063	-0.051
)	K	1_GS00064					
			607805.834	3497318.133	17.138	17.047	17.057
					High Vegetation	-0.091	-0.081
')	<	1_GS00065	1				ı
			608489.192	3470783.796	18.285	18.192	18.196
					High Vegetation	-0.093	-0.089

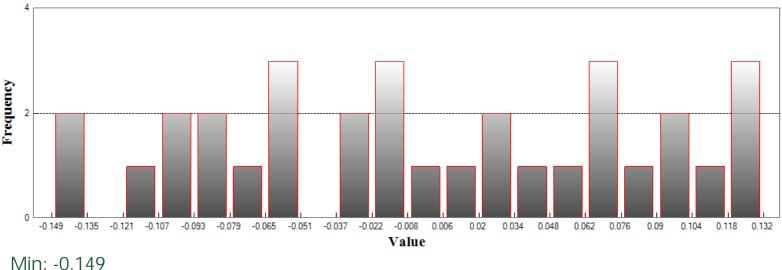




LAS

Nonvegetated Vertical Accuracy LandCover Type: Bare Earth, Urban Terrian Minimum DZ: -0.149 Maximum DZ: 0.132 Mean DZ: 0 Mean Magnitude DZ: 0.265 Number Observations: 32 Standard Deviation DZ: 0.083 RMSE Z: 0.082 95% Confidence Level Z: 0.161 Units: Meters

Histogram



Max: 0.132 Number Of Bins: 20 Bin Interval: 0.014

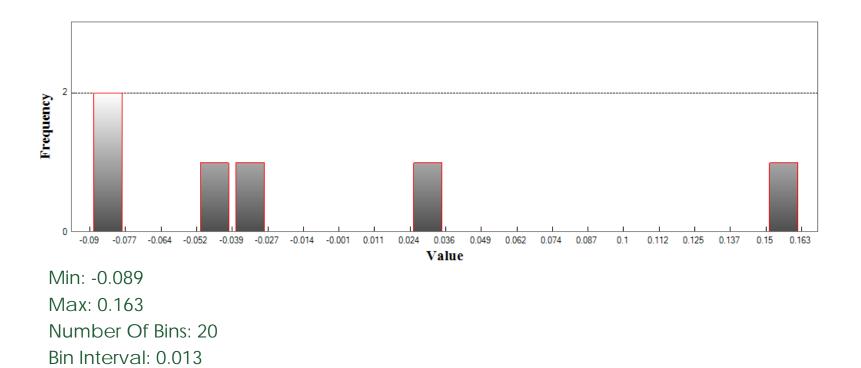




LAS (Continued)

Vegetated Vertical Accuracy LandCover Type: High Vegetation Minimum DZ: -0.089 Maximum DZ: 0.163 Mean DZ: -0.01 Mean Magnitude DZ: 0.272 Number Observations: 6 Standard Deviation DZ: 0.095 RMSE Z: 0.087 95th Percentile: 0.163 Units: Meters

Histogram



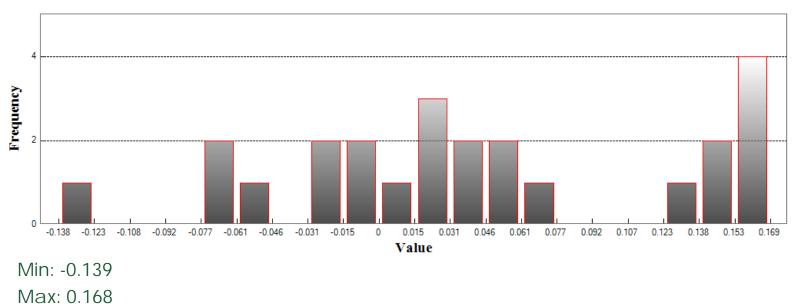




LAS (Continued)

Vegetated Vertical Accuracy LandCover Type: Low Vegetation Minimum DZ: -0.139 Maximum DZ: 0.168 Mean DZ: 0.043 Mean Magnitude DZ: 0.272 Number Observations: 24 Standard Deviation DZ: 0.084 RMSE Z: 0.093 95th Percentile: 0.163 Units: Meters

Histogram



Number Of Bins: 20 Bin Interval: 0.015

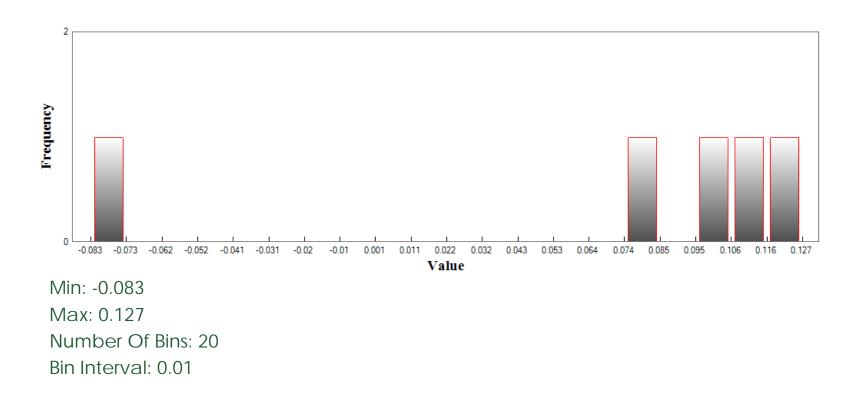




LAS (Continued)

Vegetated Vertical Accuracy LandCover Type: Med Vegetation Minimum DZ: -0.083 Maximum DZ: 0.127 Mean DZ: 0.066 Mean Magnitude DZ: 0.315 Number Observations: 5 Standard Deviation DZ: 0.085 RMSE Z: 0.1 95th Percentile: 0.127 Units: Meters

Histogram



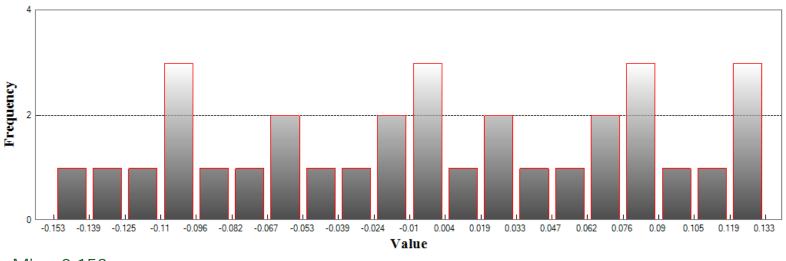




DEM

Nonvegetated Vertical Accuracy LandCover Type: Bare Earth, Urban Terrian Minimum DZ: -0.153 Maximum DZ: 0.134 Mean DZ: 0.001 Mean Magnitude DZ: 0.267 Number Observations: 32 Standard Deviation DZ: 0.085 RMSE Z: 0.083 95% Confidence Level Z: 0.163 Units: Meters

Histogram



Min: -0.153 Max: 0.134 Number Of Bins: 20 Bin Interval: 0.014

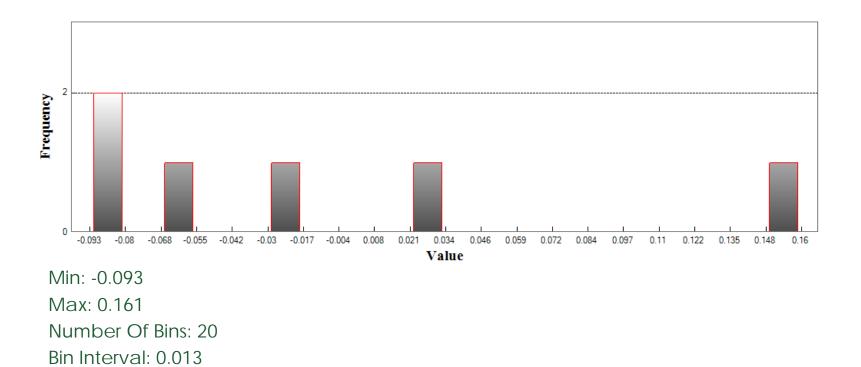




DEM (Continued)

Vegetated Vertical Accuracy LandCover Type: High Vegetation Minimum DZ: -0.093 Maximum DZ: 0.161 Mean DZ: -0.015 Mean Magnitude DZ: 0.276 Number Observations: 6 Standard Deviation DZ: 0.096 RMSE Z: 0.089 95th Percentile: 0.161 Units: Meters

Histogram



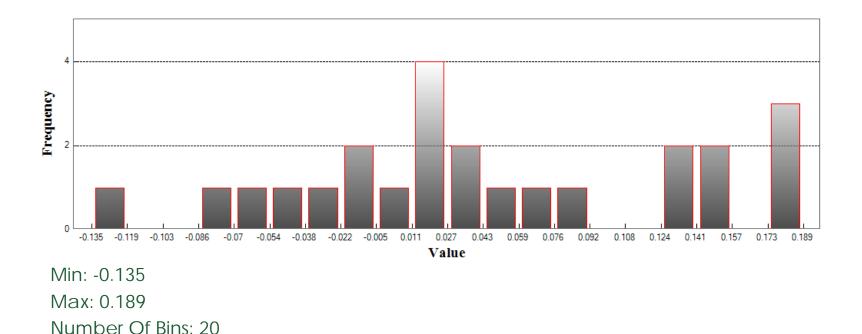




DEM (Continued)

Vegetated Vertical Accuracy LandCover Type: Low Vegetation Minimum DZ: -0.135 Maximum DZ: 0.189 Mean DZ: 0.045 Mean Magnitude DZ: 0.277 Number Observations: 24 Standard Deviation DZ: 0.089 RMSE Z: 0.098 95th Percentile: 0.186 Units: Meters

Histogram



Report for G17PD1255: LA_Catahoula_Concordia_2017_D17 CompassTA 2.5.0.0 - 9/16/2020 2:32:17 PM

Bin Interval: 0.016

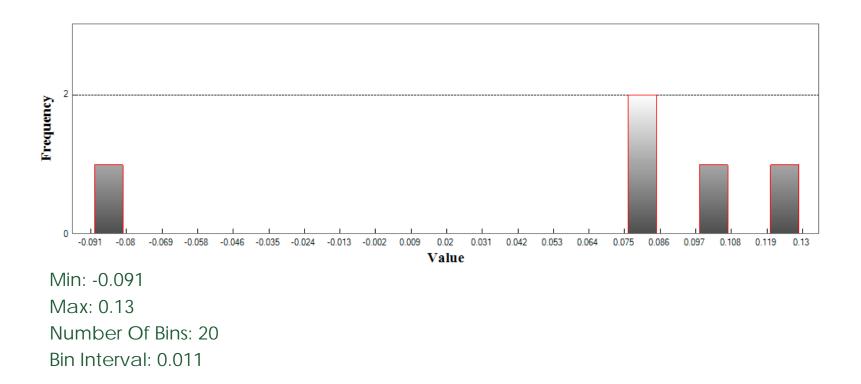




DEM (Continued)

Vegetated Vertical Accuracy LandCover Type: Med Vegetation Minimum DZ: -0.091 Maximum DZ: 0.13 Mean DZ: 0.062 Mean Magnitude DZ: 0.313 Number Observations: 5 Standard Deviation DZ: 0.087 RMSE Z: 0.1 95th Percentile: 0.13 Units: Meters

Histogram





Appendix D. Inertial Explorer

Output Results for 20191202212125

Inertial Explorer Version 8.80.2305 12/11/2019



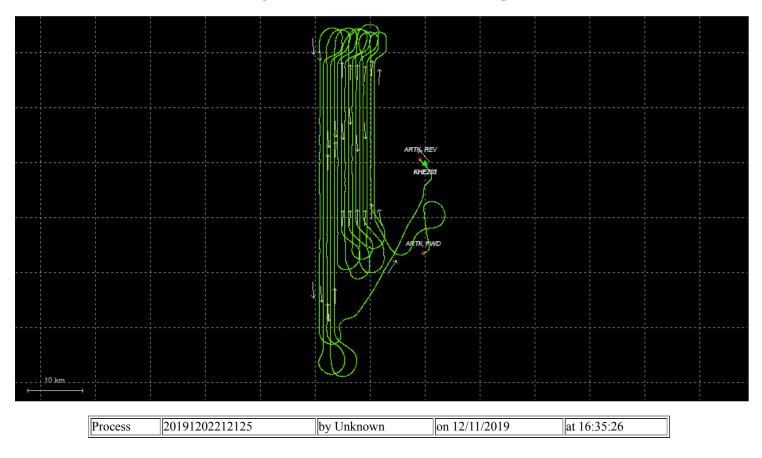
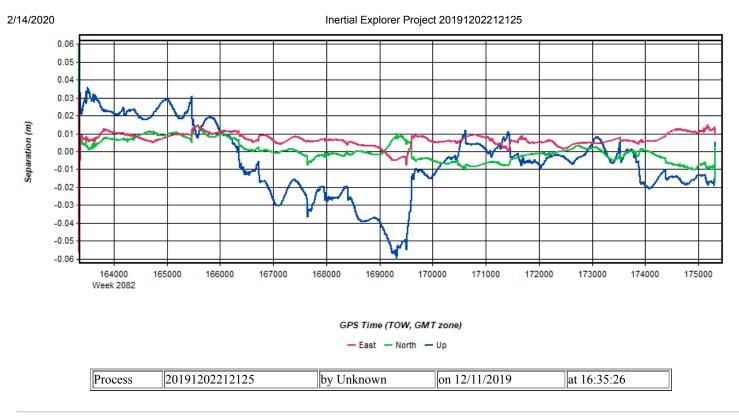


Figure 2: 20191202212125 [Smoothed TC Combined] - Forward/Reverse or Combined Separation Plot



Object 20191202212125 [Smoothed TC Combined] - Float or Fixed Ambiguity failed--NULL bitmap handle

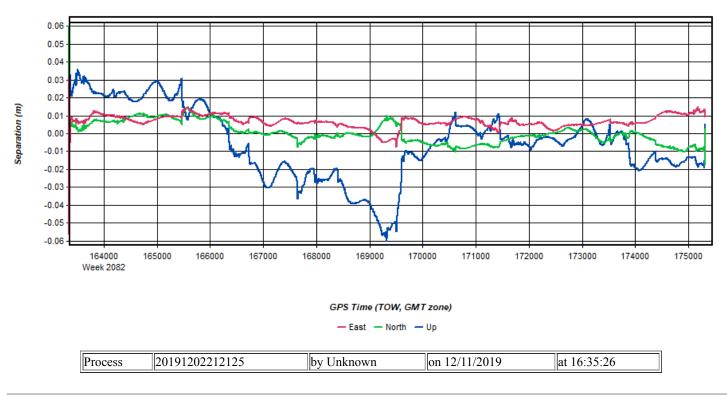


Figure 3: 20191202212125 [Smoothed TC Combined] - Forward/Reverse Separation Plot (Fixed)

Figure 4: 20191202212125 [Smoothed TC Combined] - Estimated Position Accuracy Plot

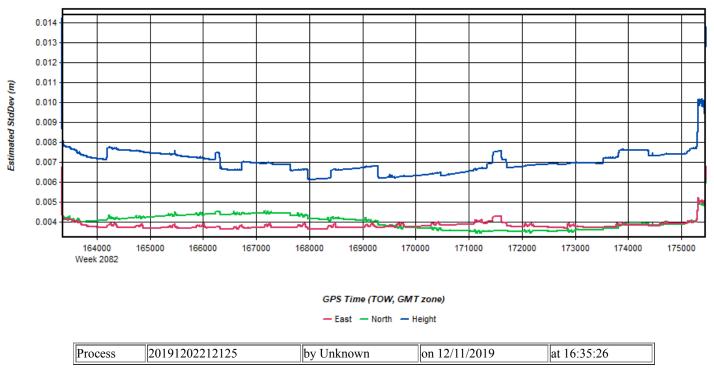


Figure 5: 20191202212125 [Smoothed TC Combined] - PDOP Plot

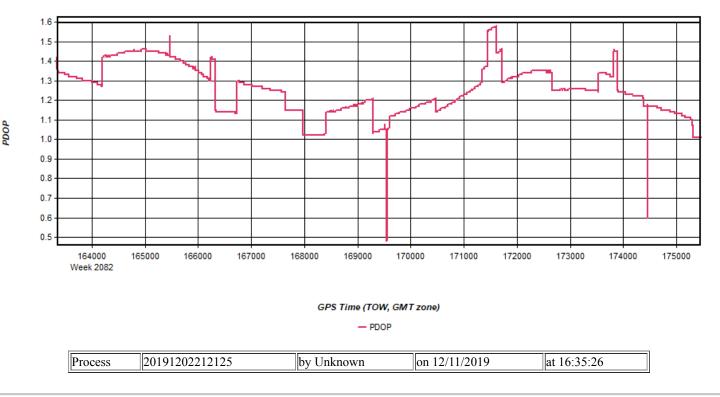


Figure 6: 20191202212125 [Smoothed TC Combined] - Number of Satellites Line Plot



Figure 7: 20191202212125 [Smoothed TC Combined] - Status flag for IMU processing

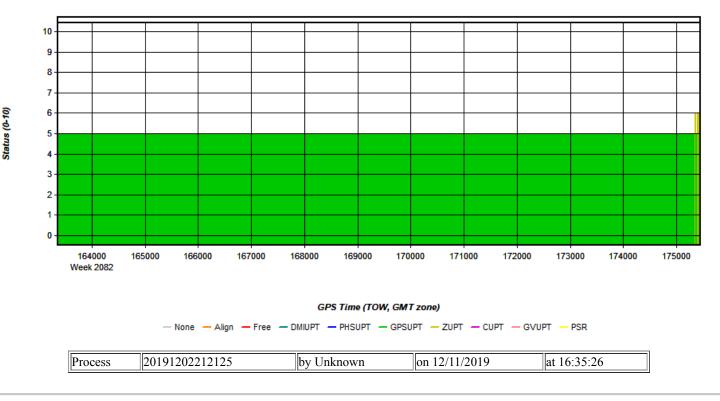


Figure 8: 20191202212125 [Smoothed TC Combined] - Fwd/Rev Attitude Separation Plot

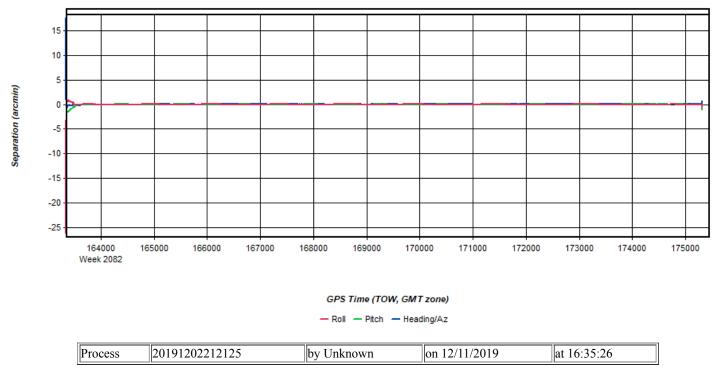


Figure 9: 20191202212125 [Smoothed TC Combined] - Estimated Attitude Accuracy Plot

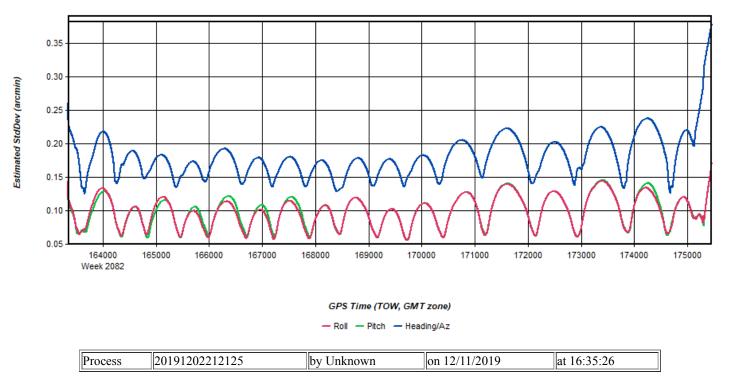


Figure 10: 20191202212125 [Smoothed TC Combined] - Azimuth Plot

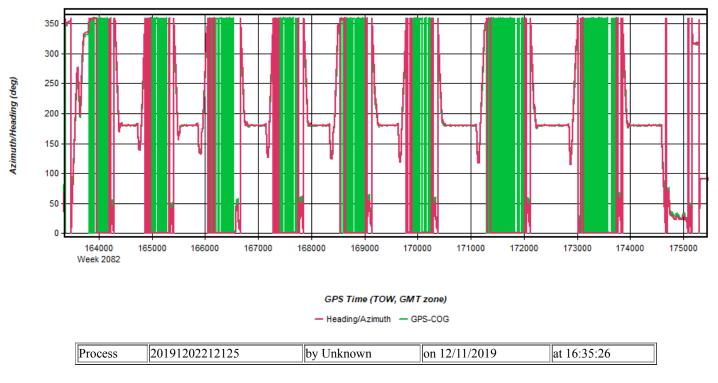


Figure 11: 20191202212125 [Smoothed TC Combined] - Roll & Pitch Plot

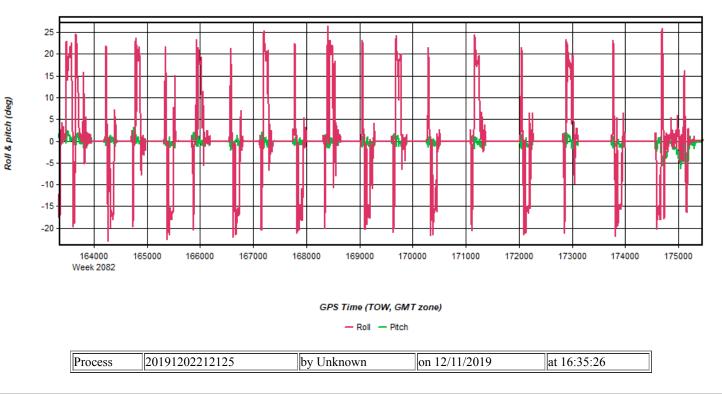


Figure 12: 20191202212125 [Smoothed TC Combined] - Velocity Profile Plot

Inertial Explorer Project 20191202212125



Figure 13: 20191202212125 [Smoothed TC Combined] - Body Frame Velocity Plot

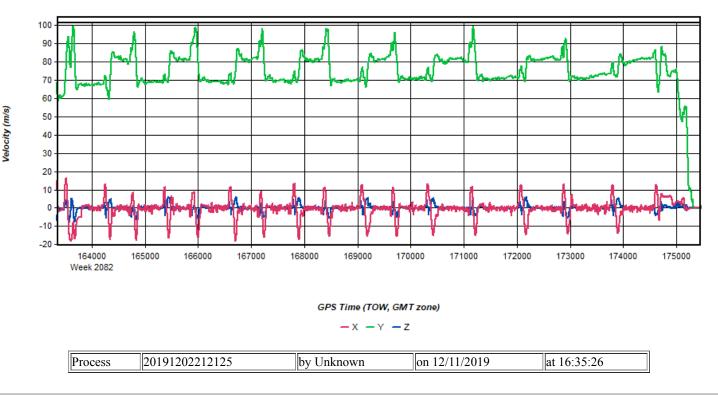


Figure 14: 20191202212125 [Smoothed TC Combined] - Height Profile Plot

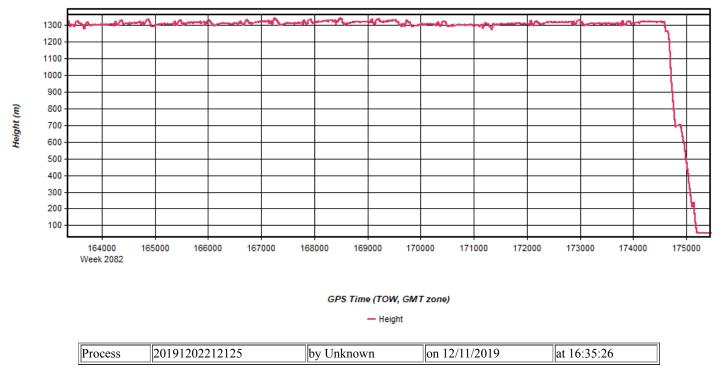


Figure 15: 20191202212125 [Smoothed TC Combined] - C/A Code Residual RMS Plot

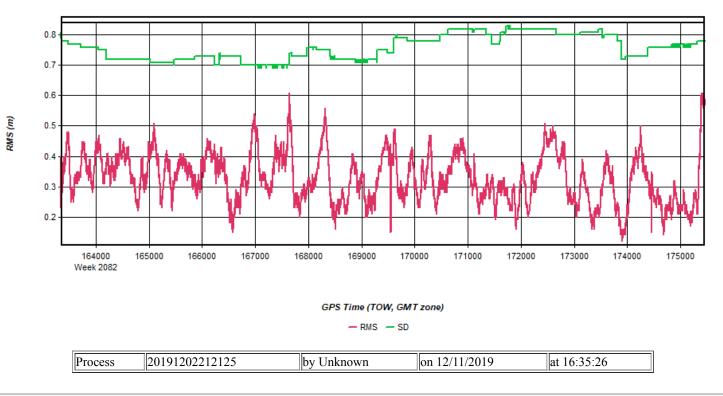


Figure 16: 20191202212125 [Smoothed TC Combined] - Carrier Residual RMS Plot

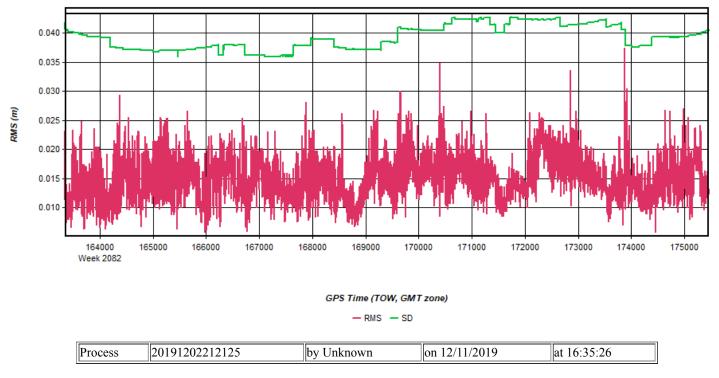


Figure 17: 20191202212125 [Smoothed TC Combined] - L1 Doppler Residual RMS Plot

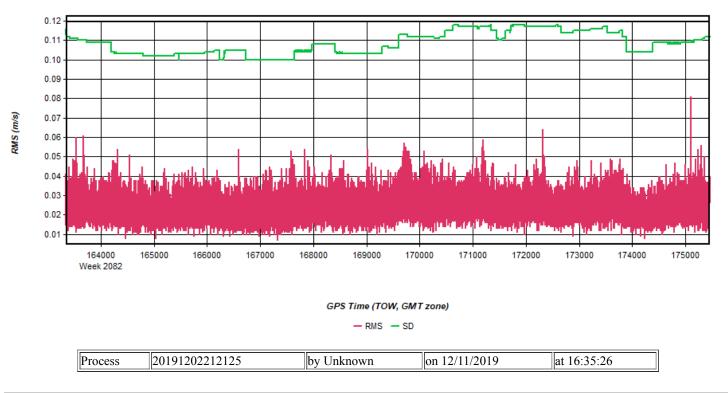


Figure 18: 20191202212125 [Smoothed TC Combined] - Accelerometer Bias Plot

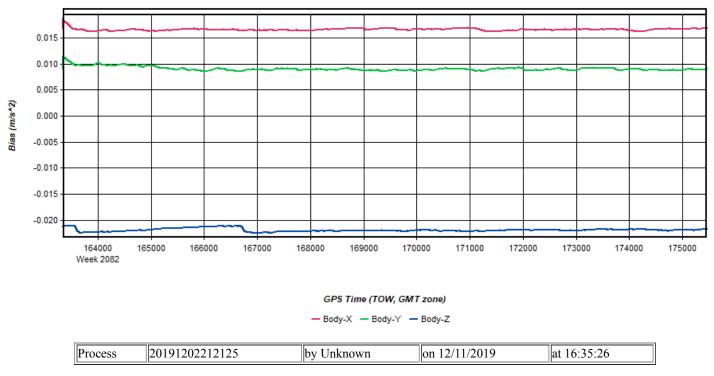
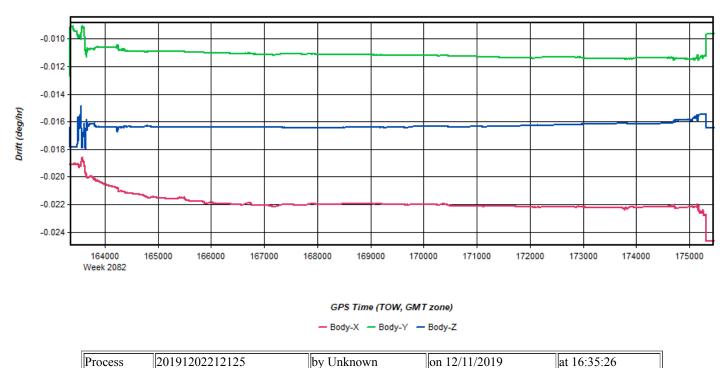


Figure 19: 20191202212125 [Smoothed TC Combined] - Gyro Drift Plot



Output Results for 20191203151442

Inertial Explorer Version 8.80.2305 12/13/2019





Figure 2: 20191203151442 [Smoothed TC Combined] - Forward/Reverse or Combined Separation Plot





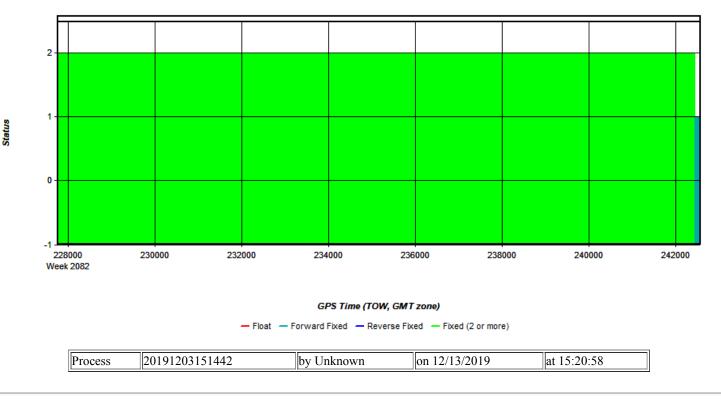
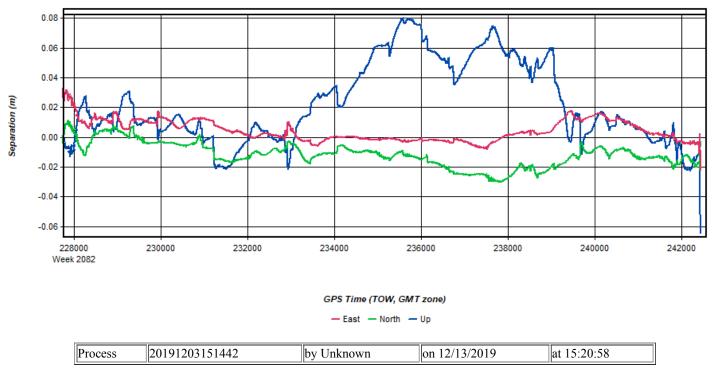


Figure 4: 20191203151442 [Smoothed TC Combined] - Forward/Reverse Separation Plot (Fixed)





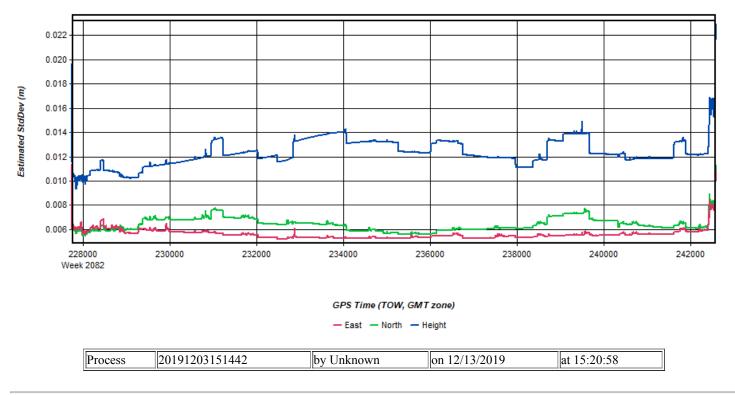


Figure 6: 20191203151442 [Smoothed TC Combined] - PDOP Plot

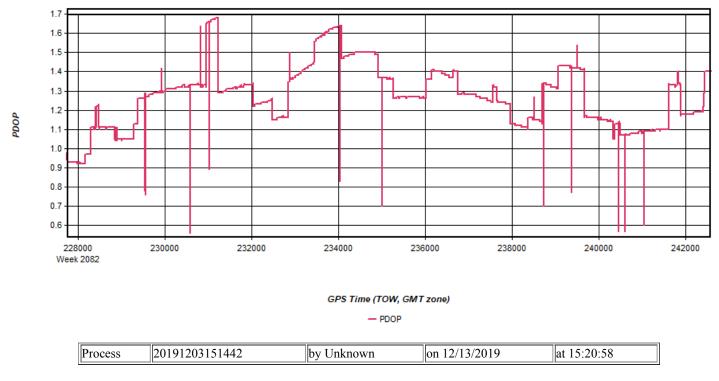


Figure 7: 20191203151442 [Smoothed TC Combined] - Number of Satellites Line Plot

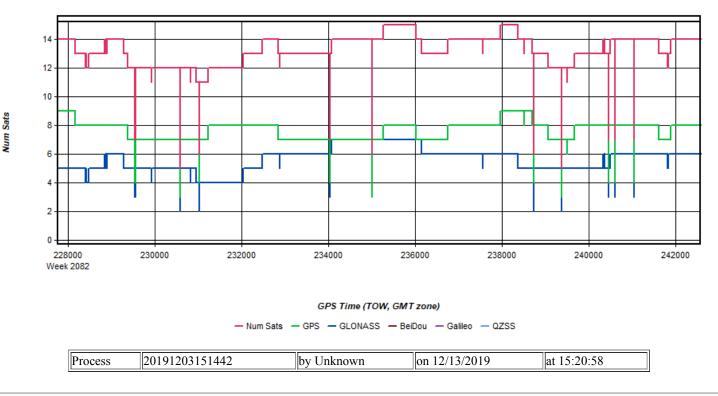


Figure 8: 20191203151442 [Smoothed TC Combined] - Status flag for IMU processing

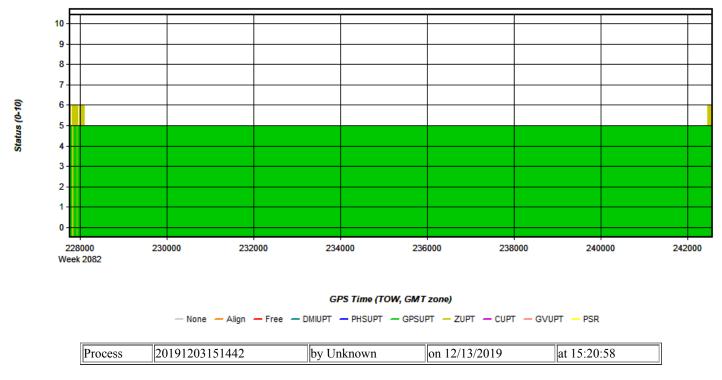


Figure 9: 20191203151442 [Smoothed TC Combined] - Fwd/Rev Attitude Separation Plot

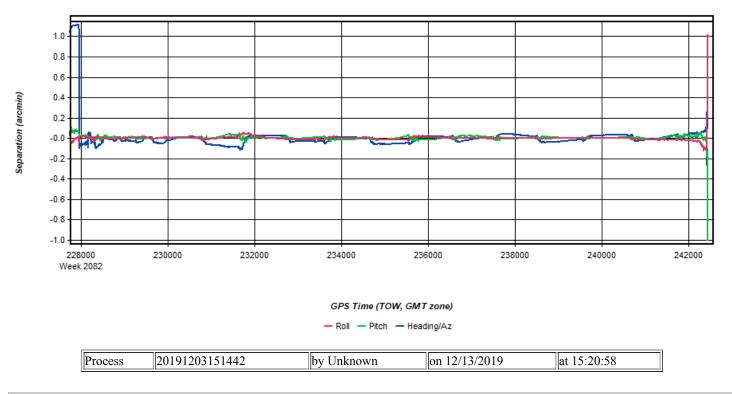


Figure 10: 20191203151442 [Smoothed TC Combined] - Estimated Attitude Accuracy Plot

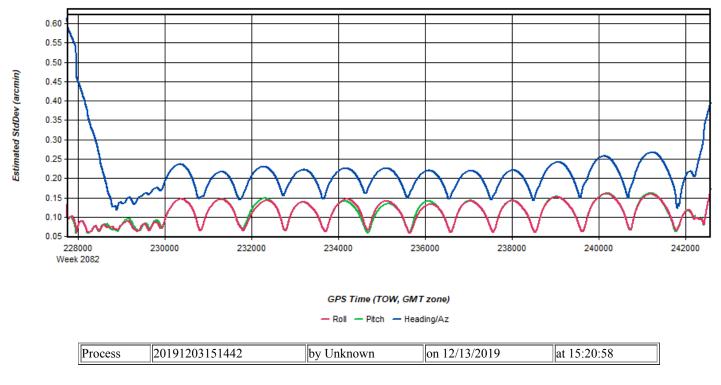


Figure 11: 20191203151442 [Smoothed TC Combined] - Azimuth Plot

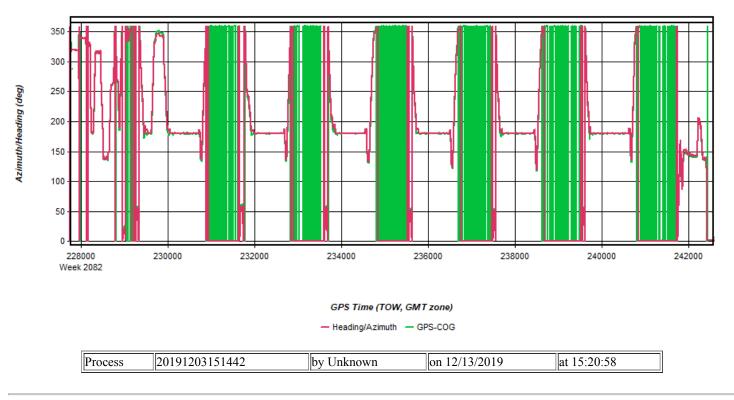


Figure 12: 20191203151442 [Smoothed TC Combined] - Roll & Pitch Plot



Figure 13: 20191203151442 [Smoothed TC Combined] - Velocity Profile Plot



Figure 14: 20191203151442 [Smoothed TC Combined] - Body Frame Velocity Plot



Figure 15: 20191203151442 [Smoothed TC Combined] - Height Profile Plot

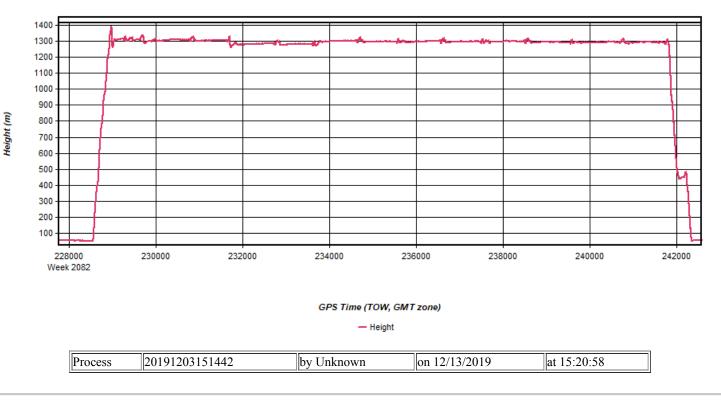


Figure 16: 20191203151442 [Smoothed TC Combined] - C/A Code Residual RMS Plot

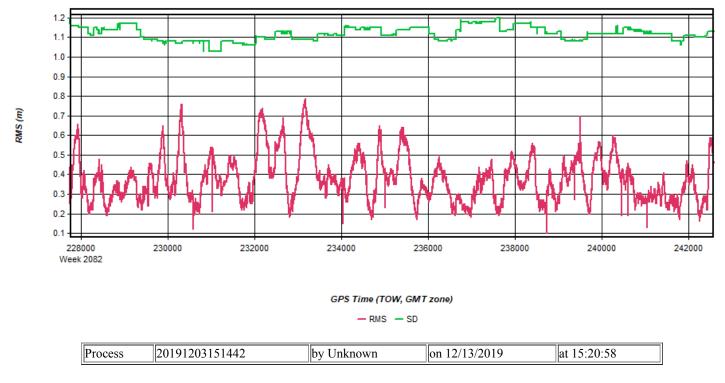


Figure 17: 20191203151442 [Smoothed TC Combined] - Carrier Residual RMS Plot

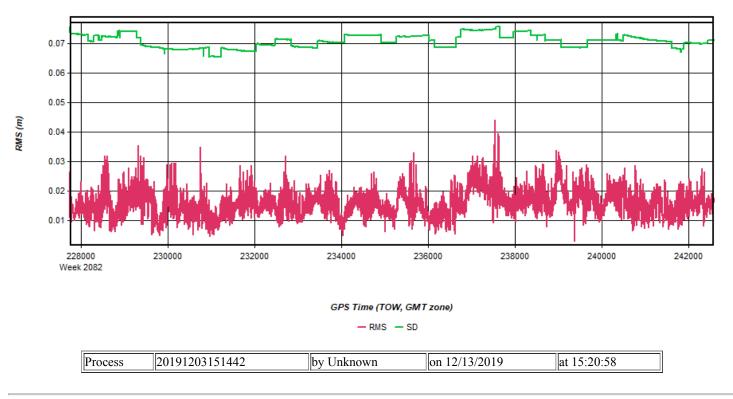
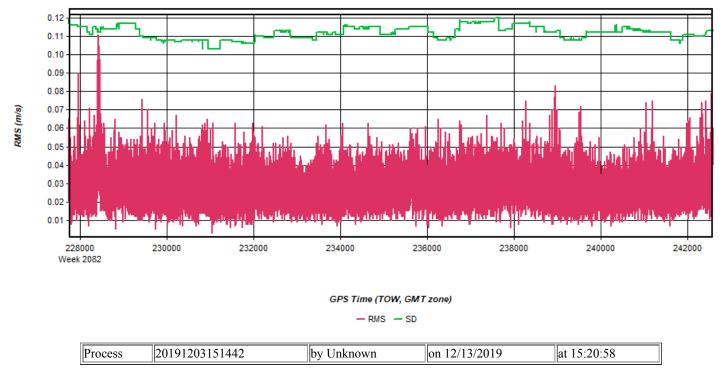


Figure 18: 20191203151442 [Smoothed TC Combined] - L1 Doppler Residual RMS Plot





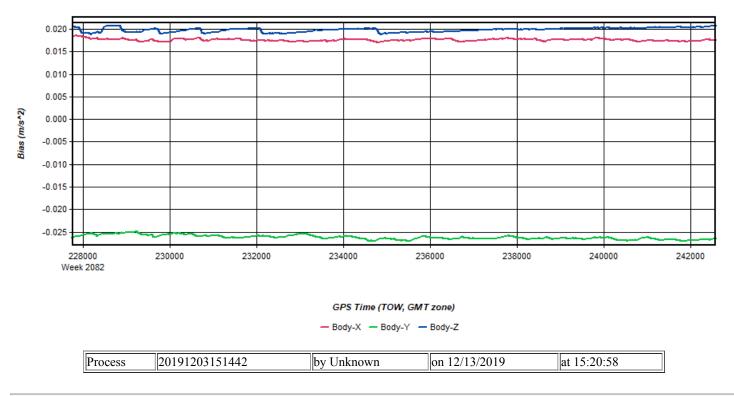


Figure 20: 20191203151442 [Smoothed TC Combined] - Gyro Drift Plot



Output Results for 20191203211932

Inertial Explorer Version 8.80.2305 12/13/2019

Figure 1: Smoothed TC Combined - Map

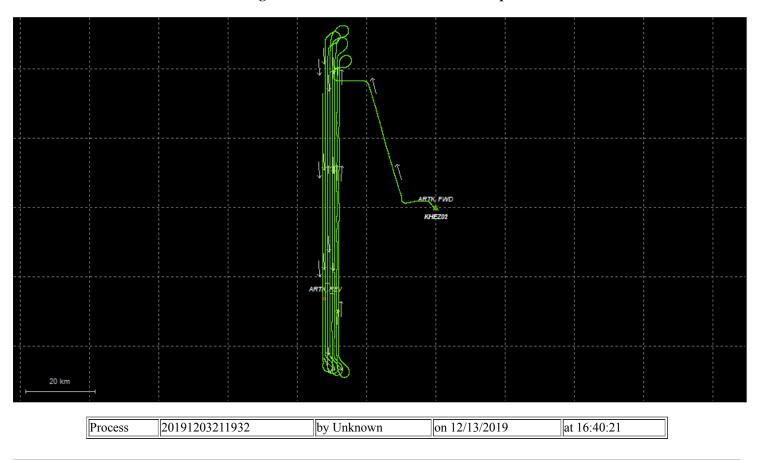
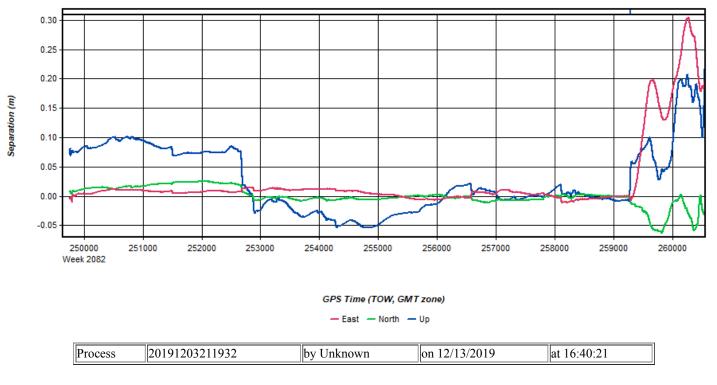


Figure 2: 20191203211932 [Smoothed TC Combined] - Forward/Reverse or Combined Separation Plot





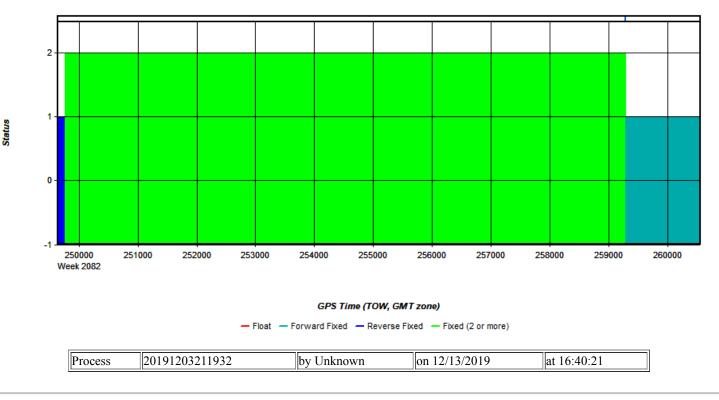
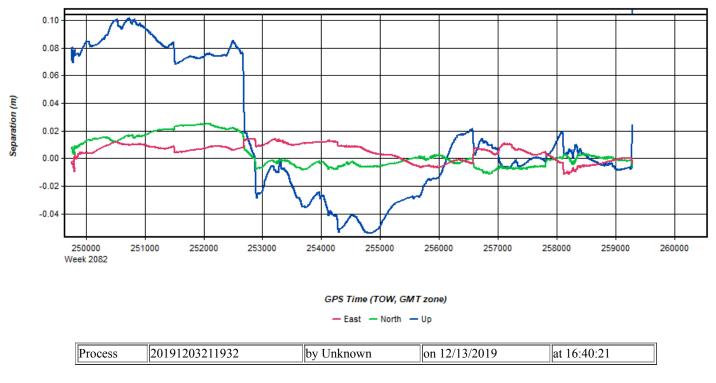
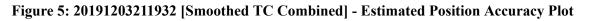


Figure 4: 20191203211932 [Smoothed TC Combined] - Forward/Reverse Separation Plot (Fixed)





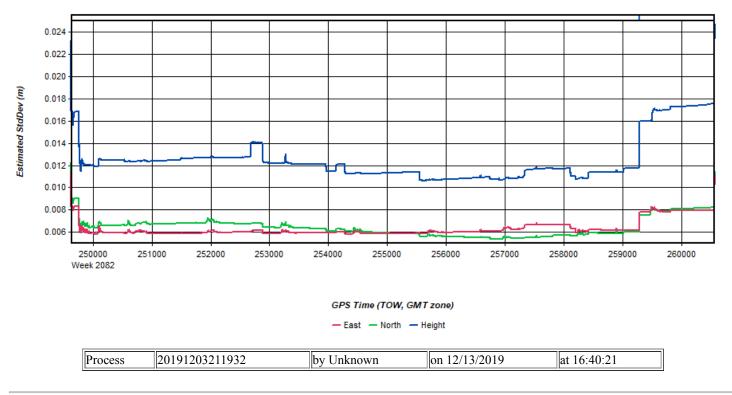


Figure 6: 20191203211932 [Smoothed TC Combined] - PDOP Plot

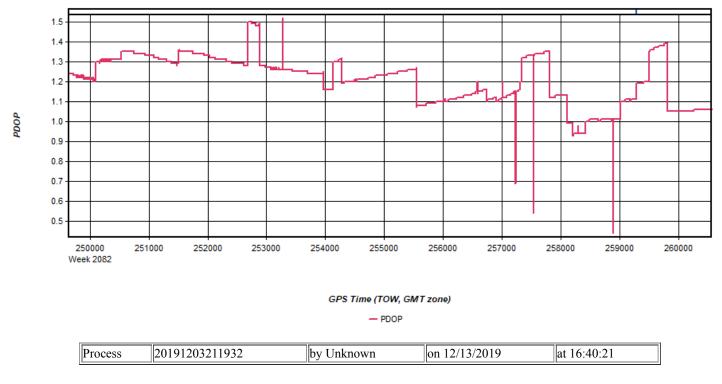


Figure 7: 20191203211932 [Smoothed TC Combined] - Number of Satellites Line Plot

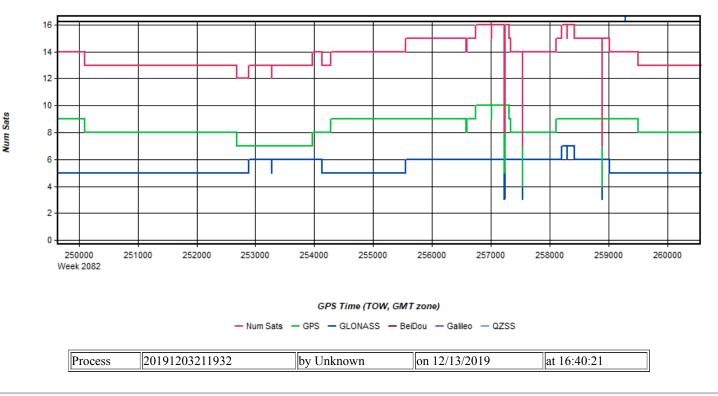


Figure 8: 20191203211932 [Smoothed TC Combined] - Status flag for IMU processing

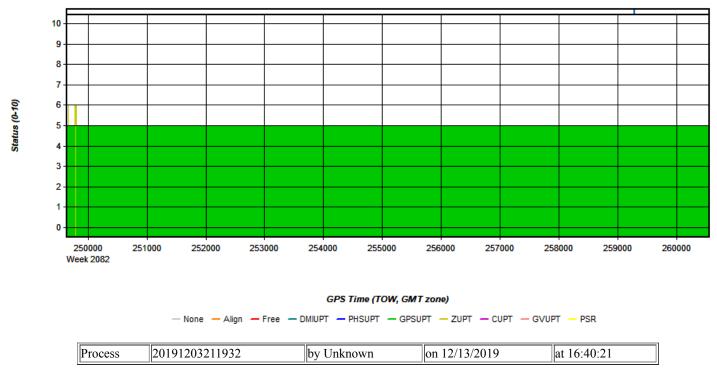


Figure 9: 20191203211932 [Smoothed TC Combined] - Fwd/Rev Attitude Separation Plot

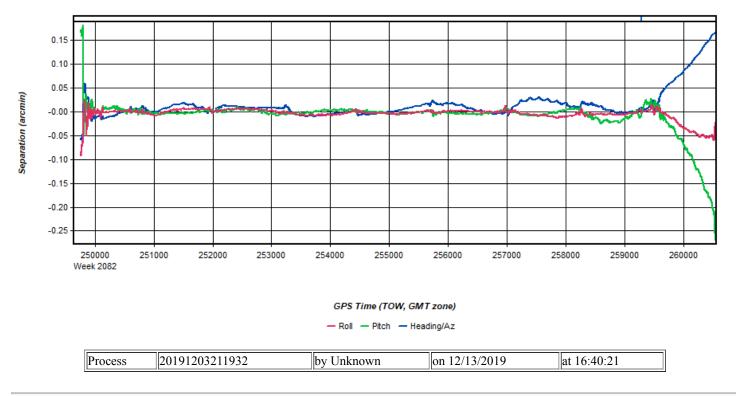


Figure 10: 20191203211932 [Smoothed TC Combined] - Estimated Attitude Accuracy Plot

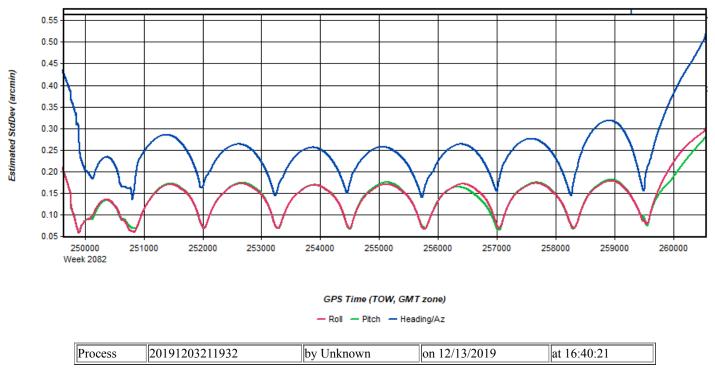






Figure 12: 20191203211932 [Smoothed TC Combined] - Roll & Pitch Plot



Figure 13: 20191203211932 [Smoothed TC Combined] - Velocity Profile Plot

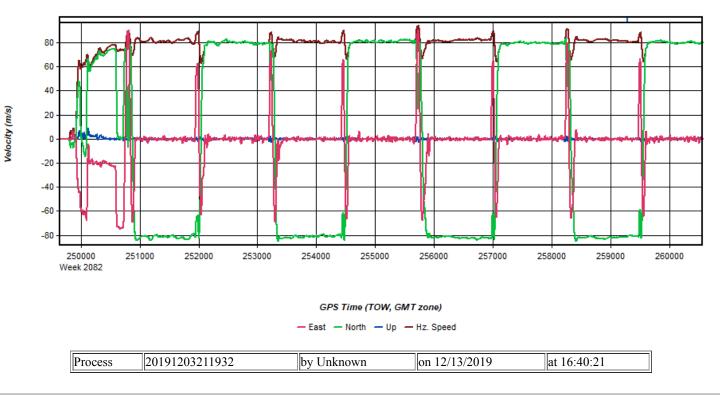


Figure 14: 20191203211932 [Smoothed TC Combined] - Body Frame Velocity Plot



Figure 15: 20191203211932 [Smoothed TC Combined] - Height Profile Plot

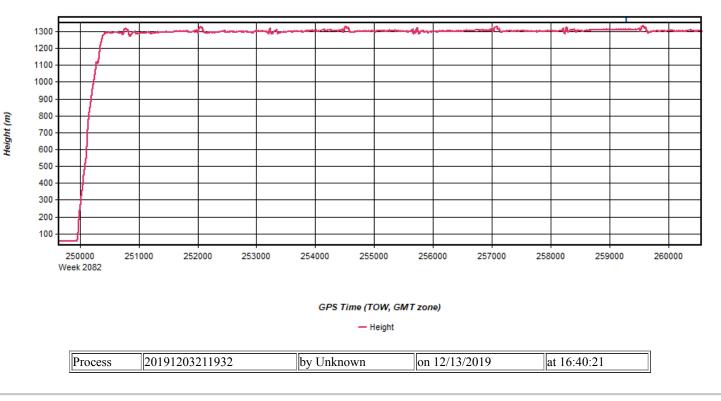


Figure 16: 20191203211932 [Smoothed TC Combined] - C/A Code Residual RMS Plot

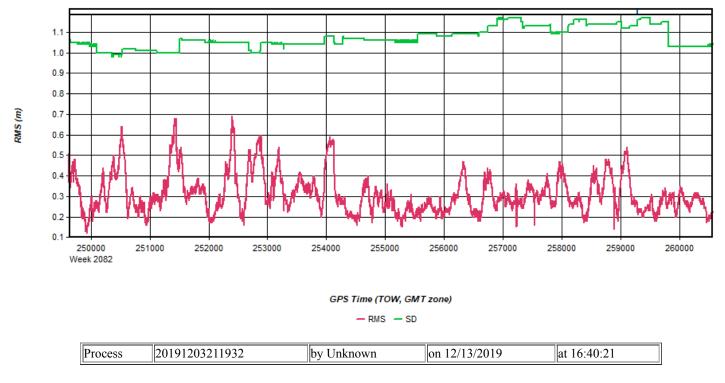


Figure 17: 20191203211932 [Smoothed TC Combined] - Carrier Residual RMS Plot

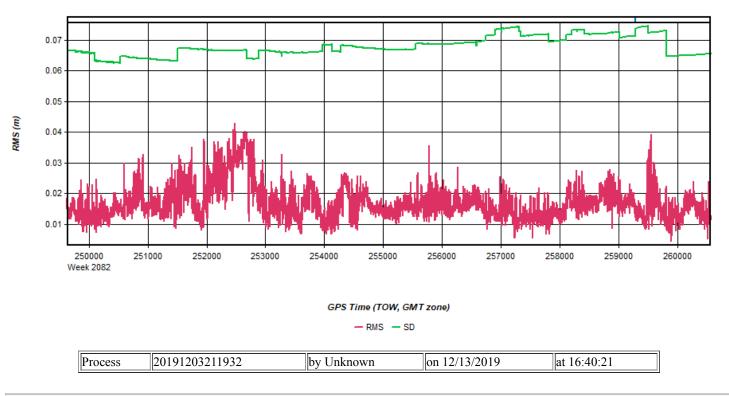


Figure 18: 20191203211932 [Smoothed TC Combined] - L1 Doppler Residual RMS Plot

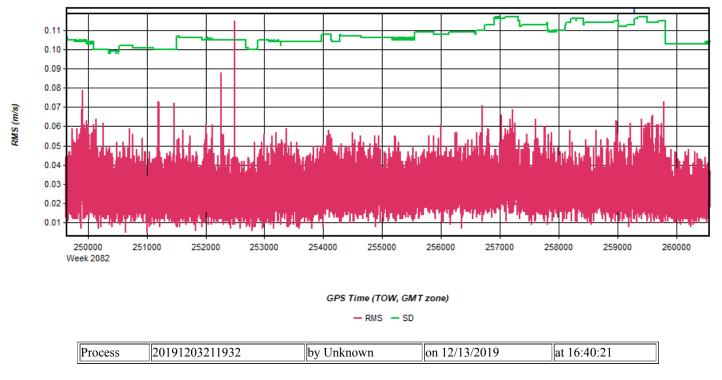


Figure 19: 20191203211932 [Smoothed TC Combined] - Accelerometer Bias Plot

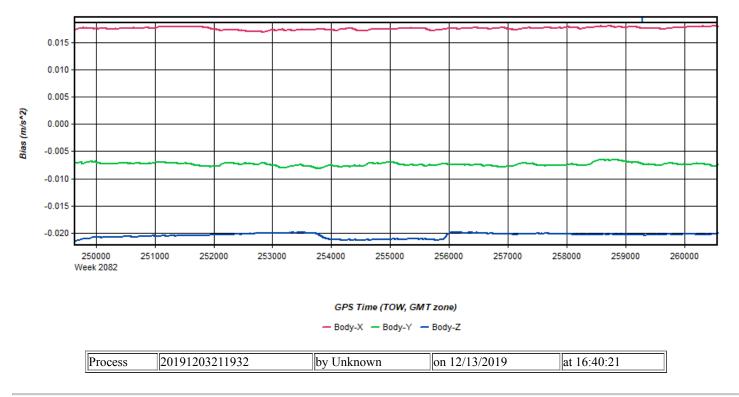
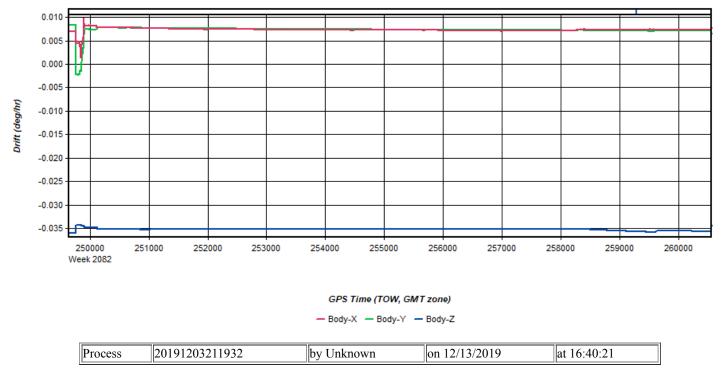


Figure 20: 20191203211932 [Smoothed TC Combined] - Gyro Drift Plot



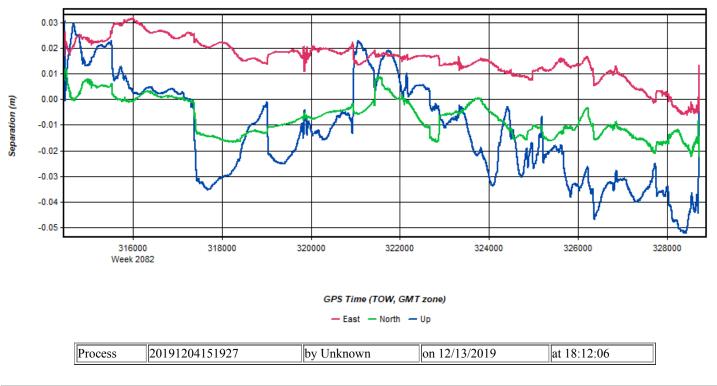
Output Results for 20191204151927

Inertial Explorer Version 8.80.2305 12/13/2019





Figure 2: 20191204151927 [Smoothed TC Combined] - Forward/Reverse or Combined Separation Plot





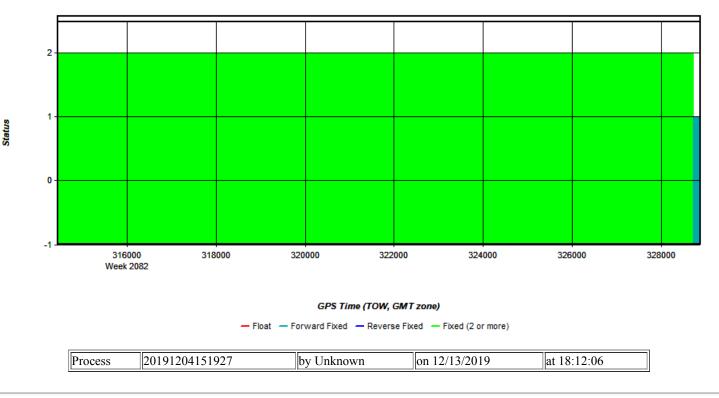


Figure 4: 20191204151927 [Smoothed TC Combined] - Forward/Reverse Separation Plot (Fixed)

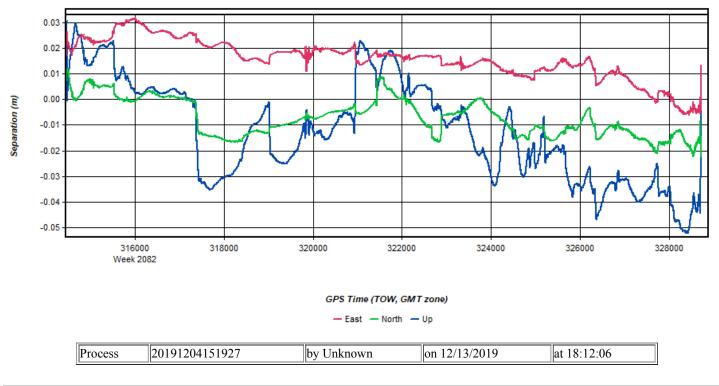


Figure 5: 20191204151927 [Smoothed TC Combined] - Estimated Position Accuracy Plot

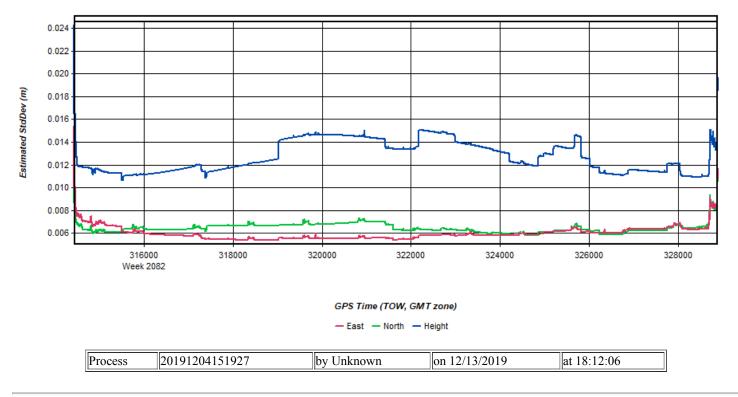


Figure 6: 20191204151927 [Smoothed TC Combined] - PDOP Plot

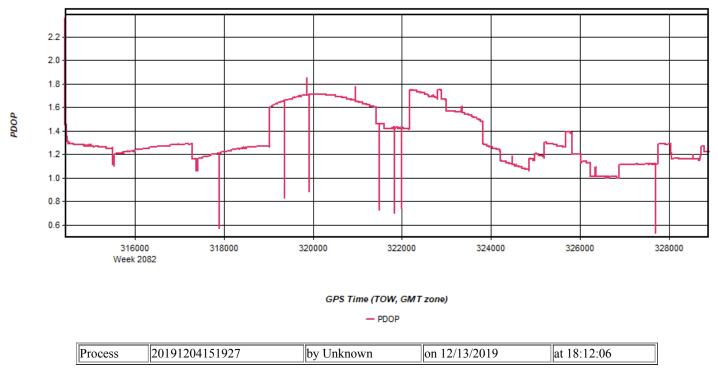


Figure 7: 20191204151927 [Smoothed TC Combined] - Number of Satellites Line Plot

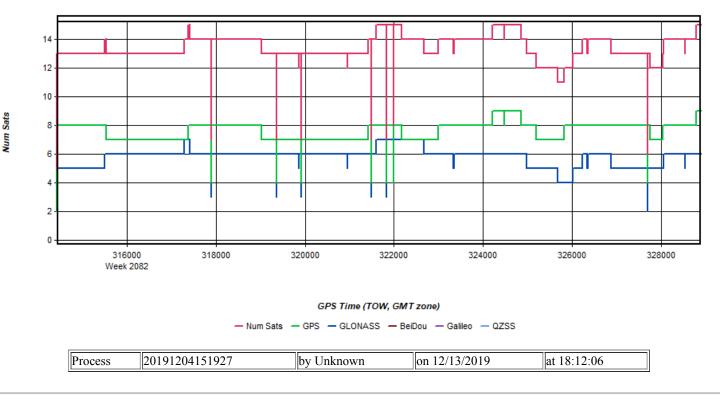


Figure 8: 20191204151927 [Smoothed TC Combined] - Status flag for IMU processing

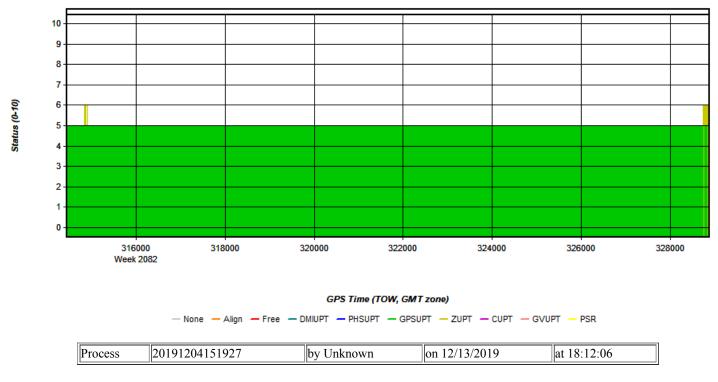


Figure 9: 20191204151927 [Smoothed TC Combined] - Fwd/Rev Attitude Separation Plot

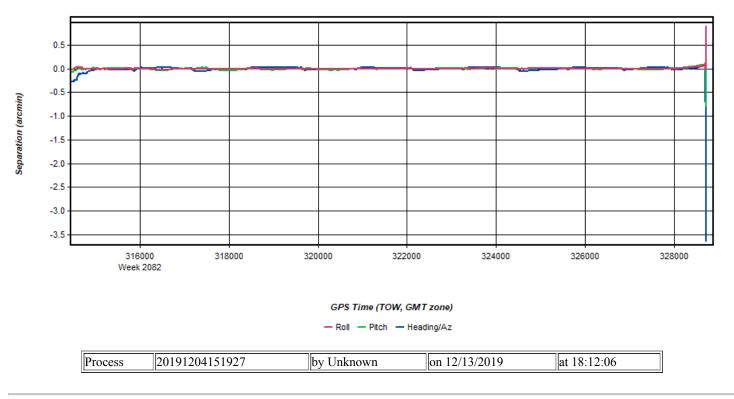


Figure 10: 20191204151927 [Smoothed TC Combined] - Estimated Attitude Accuracy Plot

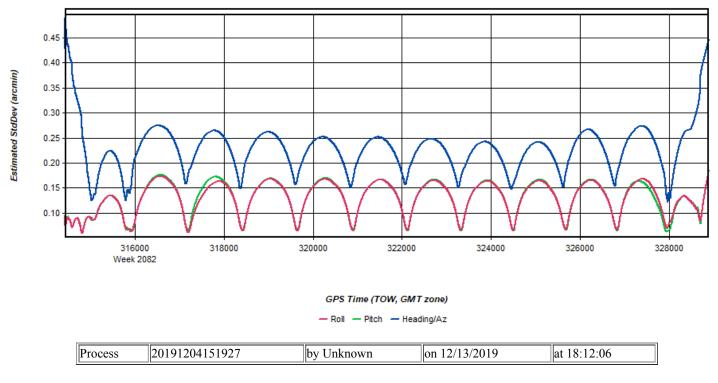


Figure 11: 20191204151927 [Smoothed TC Combined] - Azimuth Plot

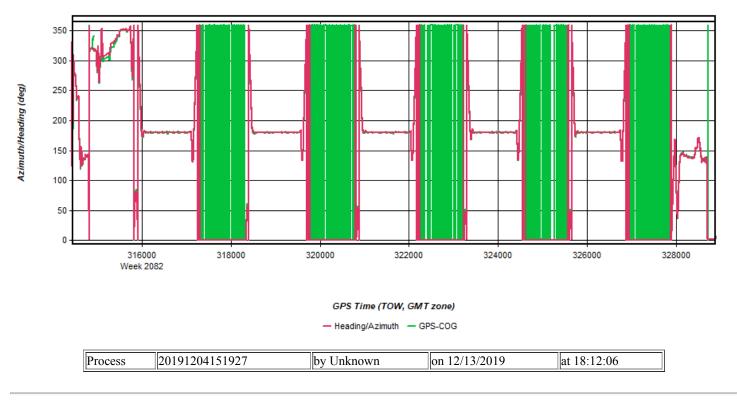


Figure 12: 20191204151927 [Smoothed TC Combined] - Roll & Pitch Plot

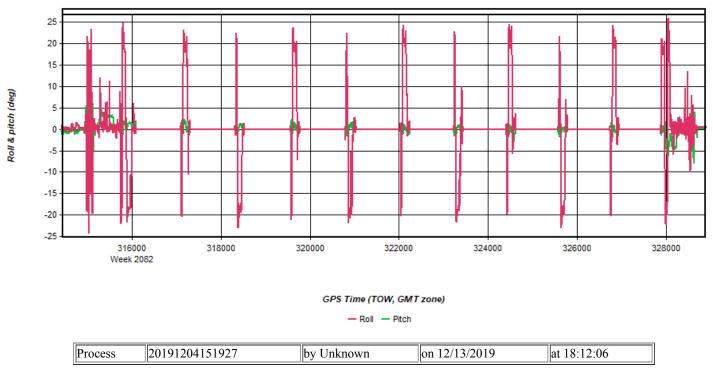


Figure 13: 20191204151927 [Smoothed TC Combined] - Velocity Profile Plot



Figure 14: 20191204151927 [Smoothed TC Combined] - Body Frame Velocity Plot



Figure 15: 20191204151927 [Smoothed TC Combined] - Height Profile Plot

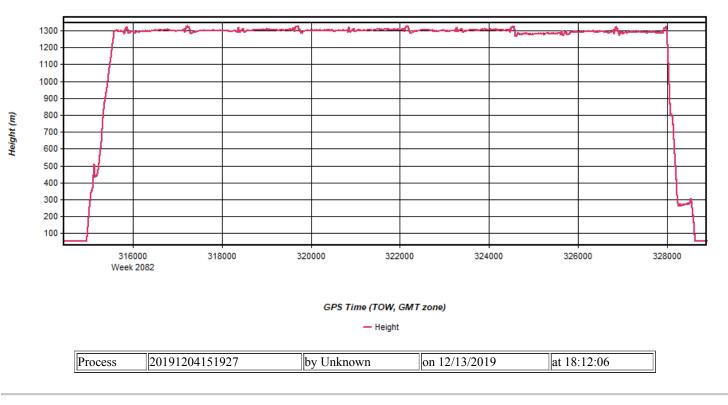


Figure 16: 20191204151927 [Smoothed TC Combined] - C/A Code Residual RMS Plot

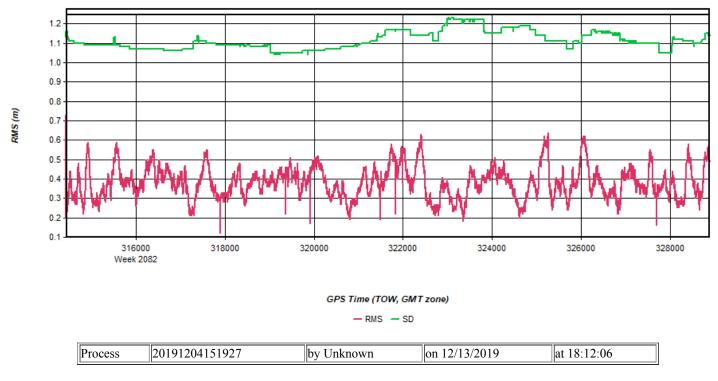


Figure 17: 20191204151927 [Smoothed TC Combined] - Carrier Residual RMS Plot

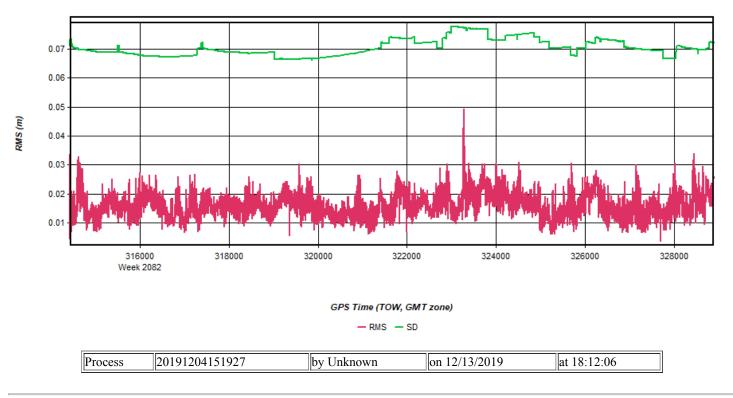
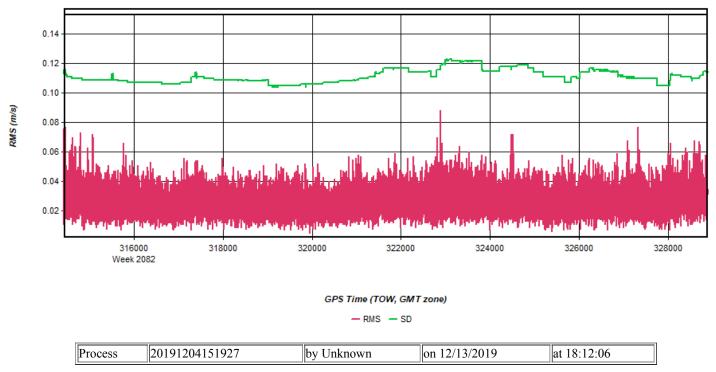


Figure 18: 20191204151927 [Smoothed TC Combined] - L1 Doppler Residual RMS Plot





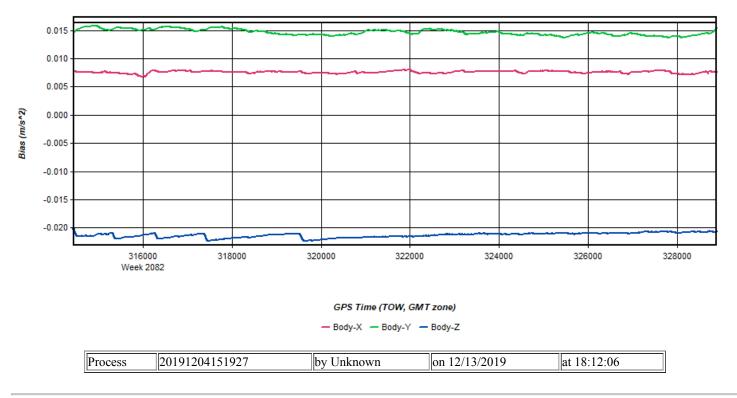
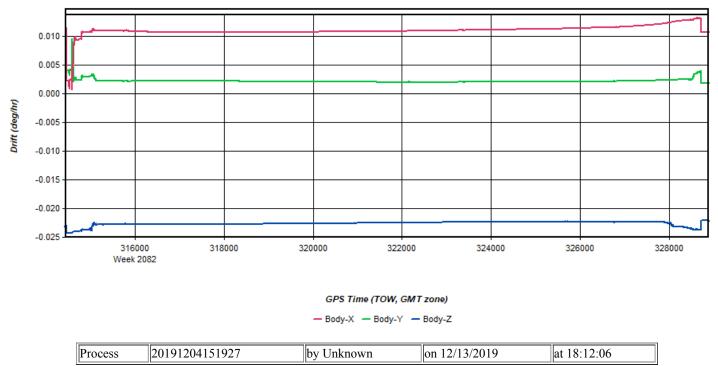


Figure 20: 20191204151927 [Smoothed TC Combined] - Gyro Drift Plot



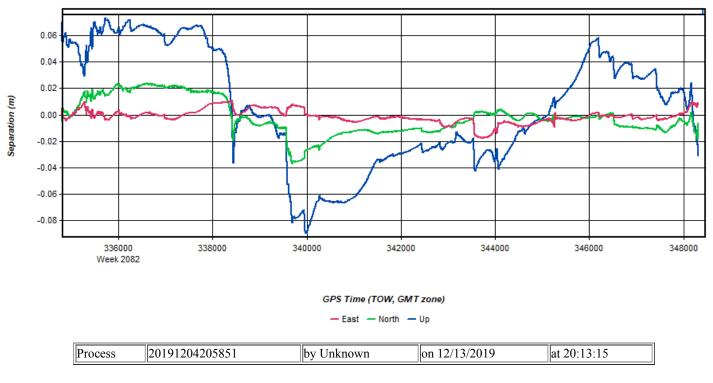
Output Results for 20191204205851

Inertial Explorer Version 8.80.2305 12/14/2019





Figure 2: 20191204205851 [Smoothed TC Combined] - Forward/Reverse or Combined Separation Plot





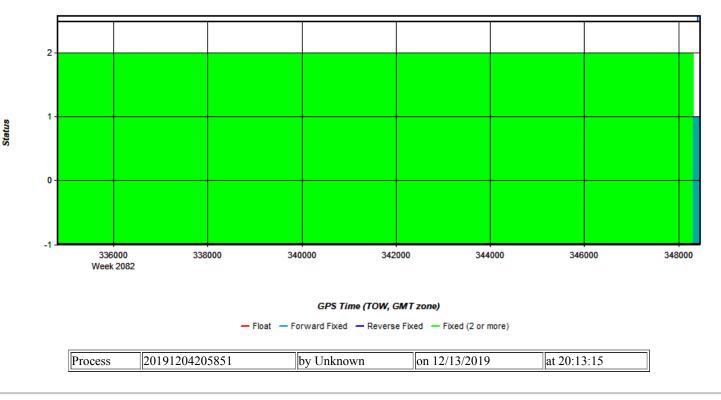


Figure 4: 20191204205851 [Smoothed TC Combined] - Forward/Reverse Separation Plot (Fixed)

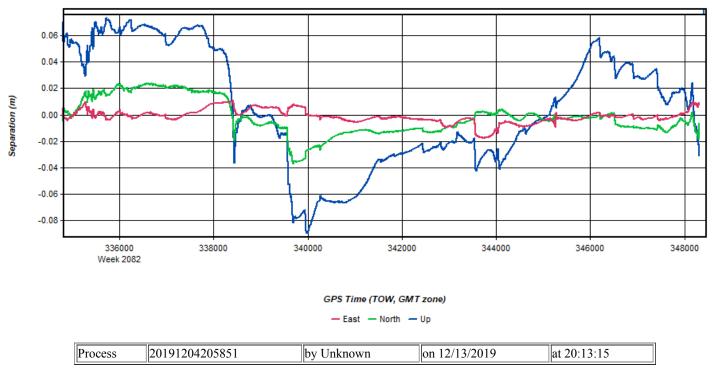


Figure 5: 20191204205851 [Smoothed TC Combined] - Estimated Position Accuracy Plot

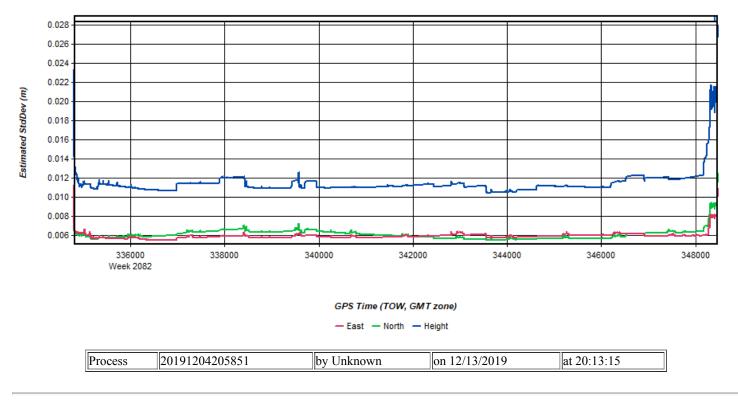


Figure 6: 20191204205851 [Smoothed TC Combined] - PDOP Plot



Figure 7: 20191204205851 [Smoothed TC Combined] - Number of Satellites Line Plot

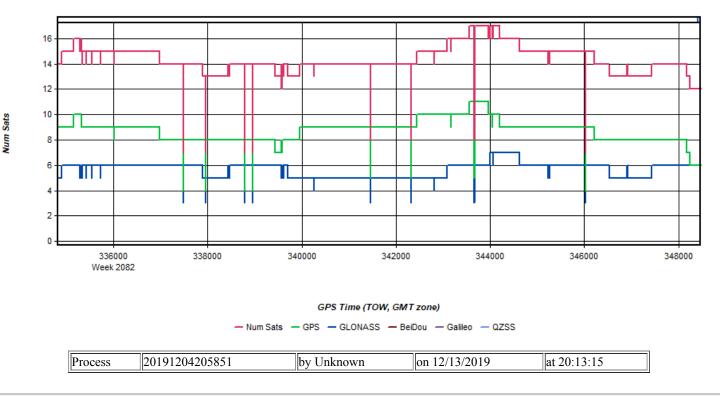


Figure 8: 20191204205851 [Smoothed TC Combined] - Status flag for IMU processing

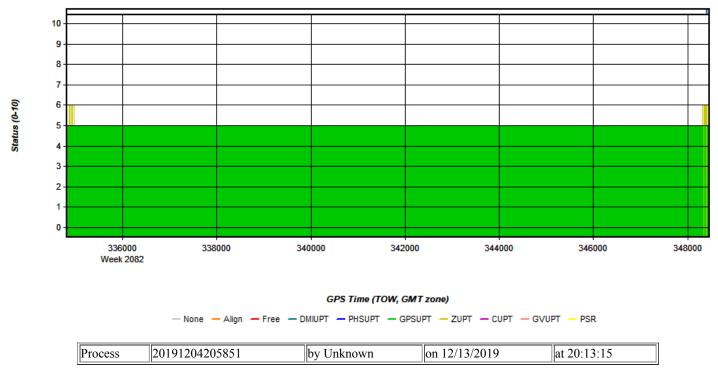


Figure 9: 20191204205851 [Smoothed TC Combined] - Fwd/Rev Attitude Separation Plot

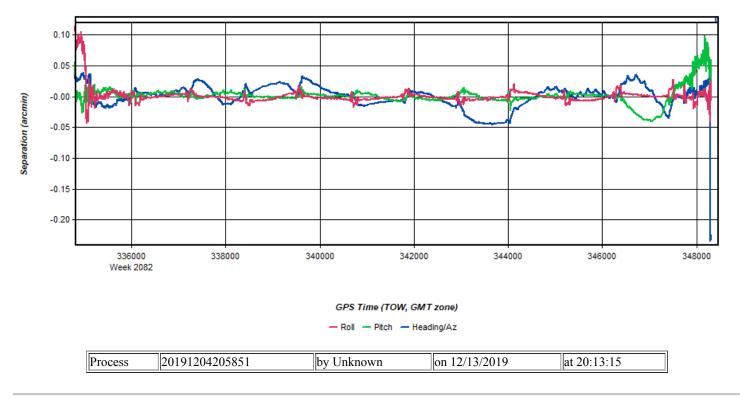


Figure 10: 20191204205851 [Smoothed TC Combined] - Estimated Attitude Accuracy Plot

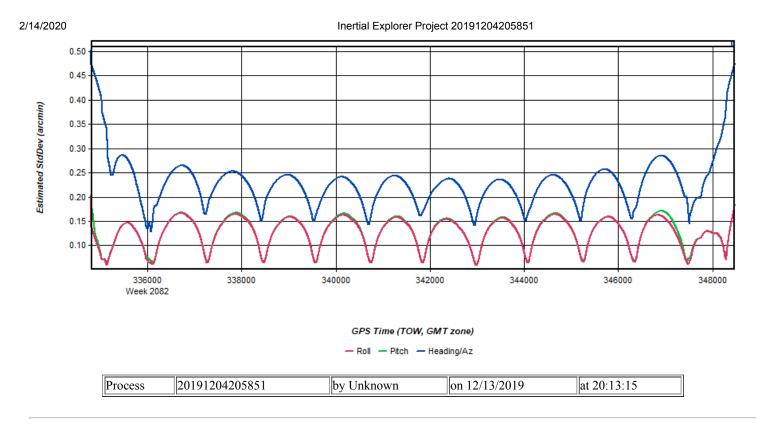






Figure 12: 20191204205851 [Smoothed TC Combined] - Roll & Pitch Plot

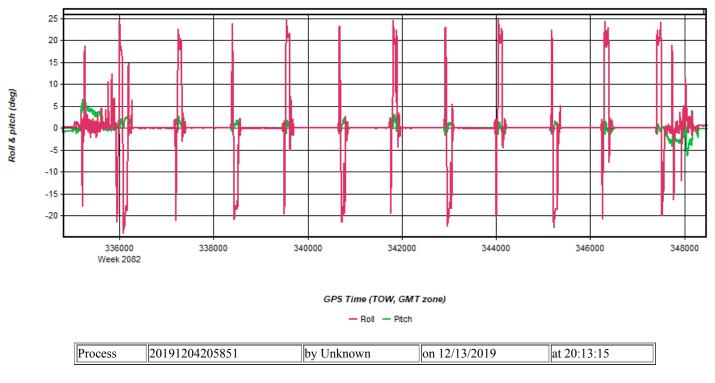


Figure 13: 20191204205851 [Smoothed TC Combined] - Velocity Profile Plot



Figure 14: 20191204205851 [Smoothed TC Combined] - Body Frame Velocity Plot

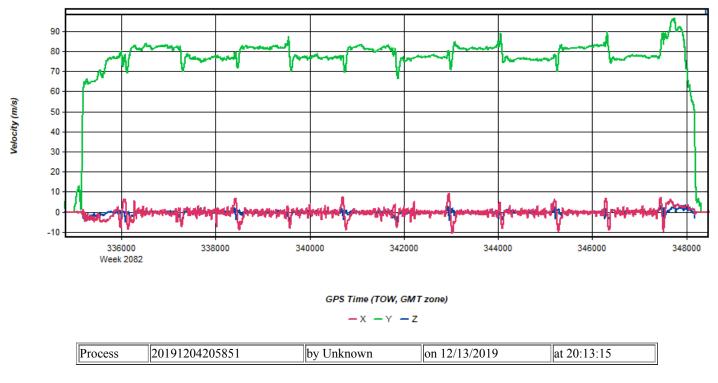


Figure 15: 20191204205851 [Smoothed TC Combined] - Height Profile Plot

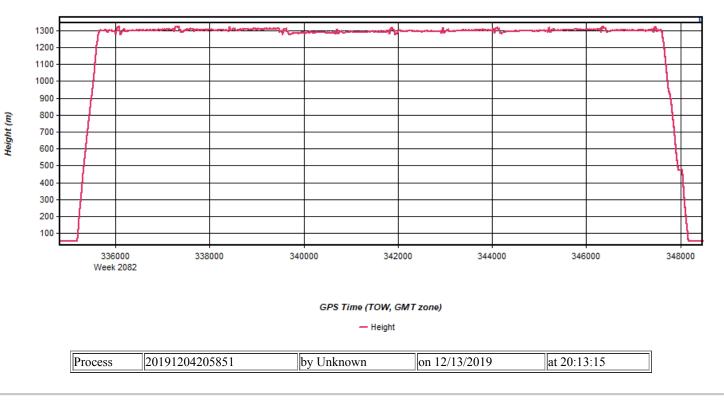


Figure 16: 20191204205851 [Smoothed TC Combined] - C/A Code Residual RMS Plot

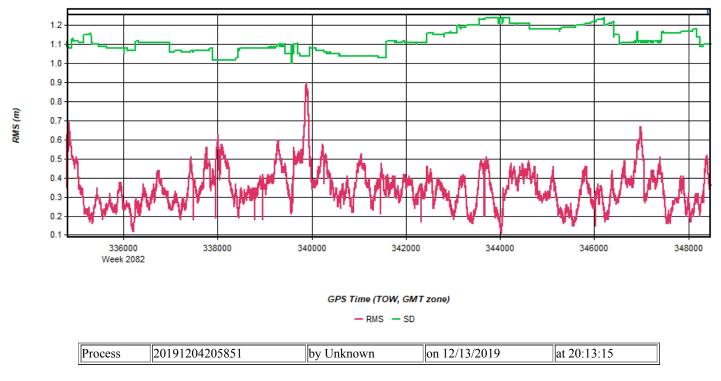


Figure 17: 20191204205851 [Smoothed TC Combined] - Carrier Residual RMS Plot

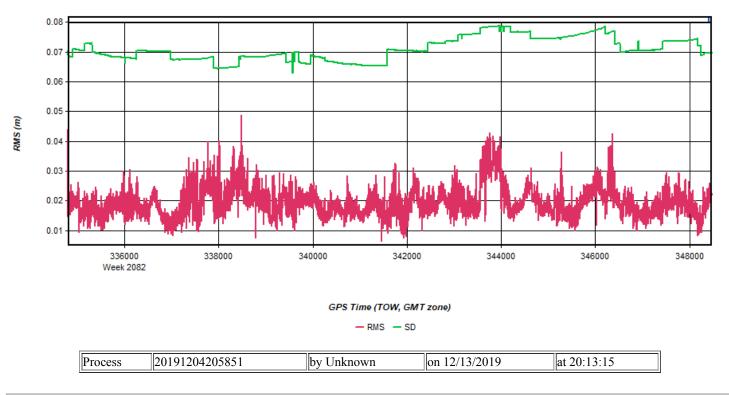
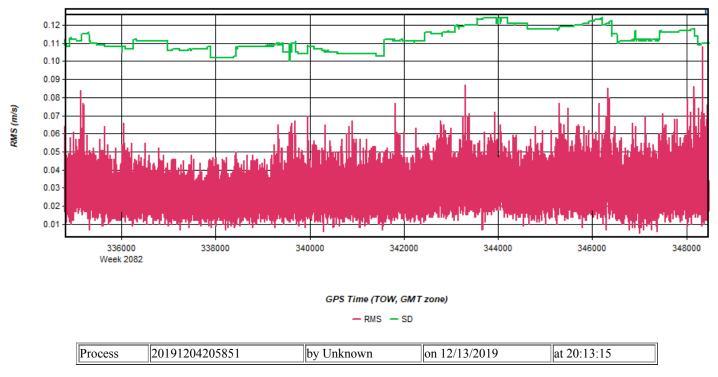


Figure 18: 20191204205851 [Smoothed TC Combined] - L1 Doppler Residual RMS Plot





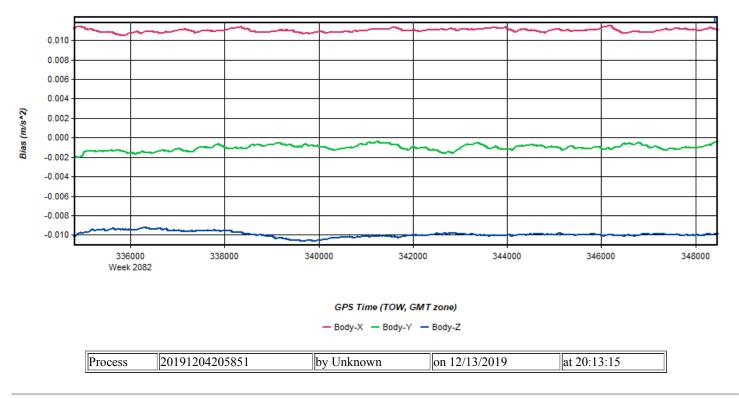
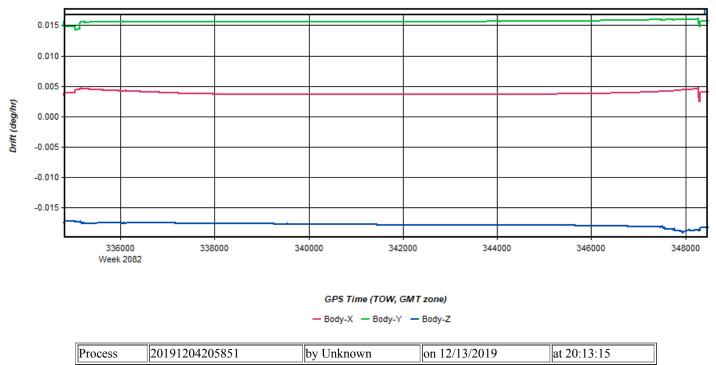


Figure 20: 20191204205851 [Smoothed TC Combined] - Gyro Drift Plot



Output Results for 20191211235253

Inertial Explorer Version 8.80.2305 12/18/2019

Figure 1: Smoothed TC Combined - Map



Figure 2: 20191211235253 [Smoothed TC Combined] - Forward/Reverse or Combined Separation Plot





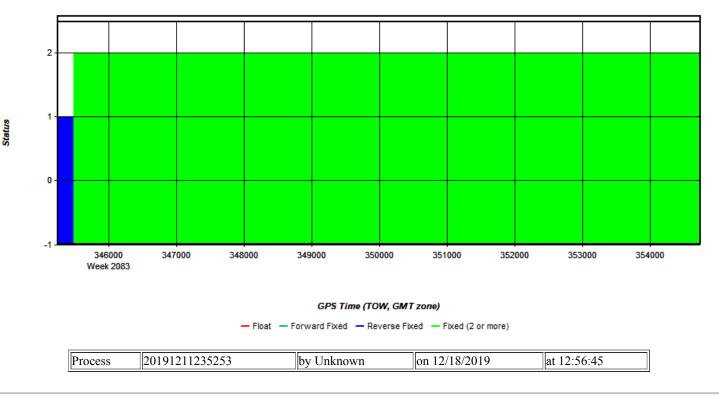


Figure 4: 20191211235253 [Smoothed TC Combined] - Forward/Reverse Separation Plot (Fixed)

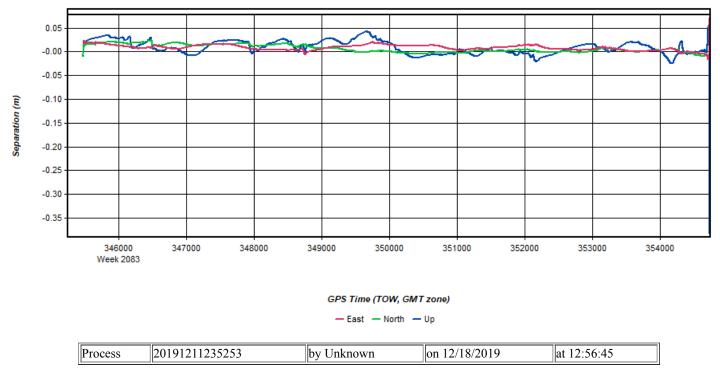


Figure 5: 20191211235253 [Smoothed TC Combined] - Estimated Position Accuracy Plot

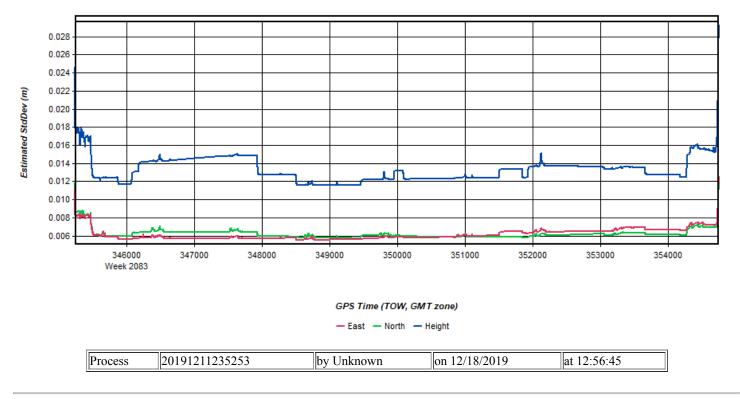


Figure 6: 20191211235253 [Smoothed TC Combined] - PDOP Plot

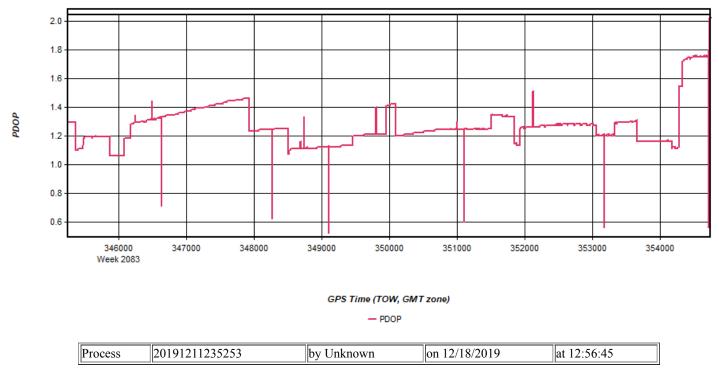


Figure 7: 20191211235253 [Smoothed TC Combined] - Number of Satellites Line Plot

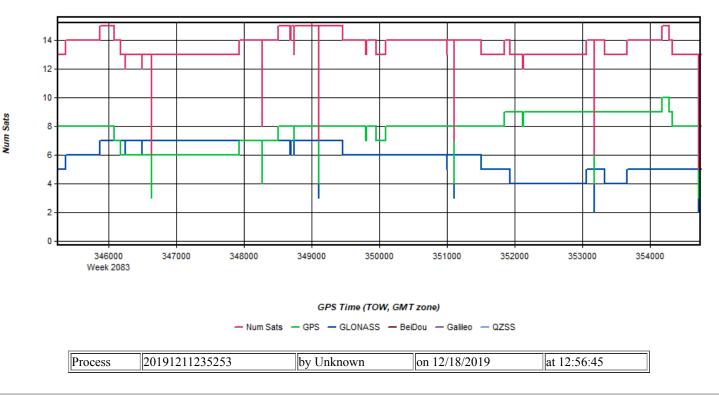


Figure 8: 20191211235253 [Smoothed TC Combined] - Status flag for IMU processing

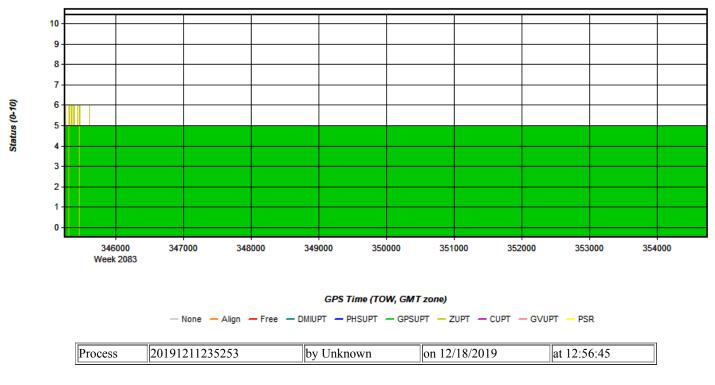


Figure 9: 20191211235253 [Smoothed TC Combined] - Fwd/Rev Attitude Separation Plot

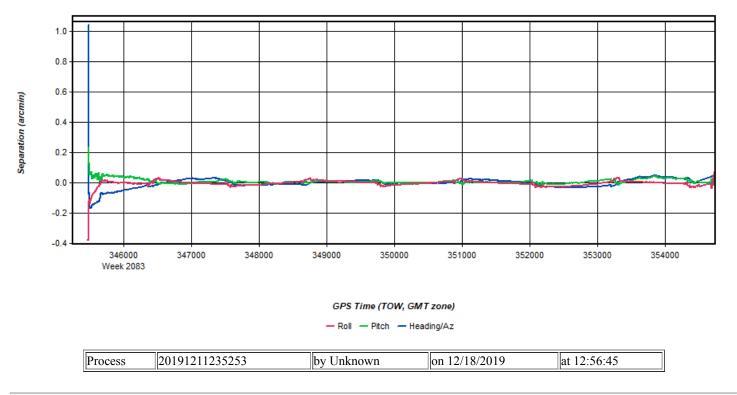


Figure 10: 20191211235253 [Smoothed TC Combined] - Estimated Attitude Accuracy Plot

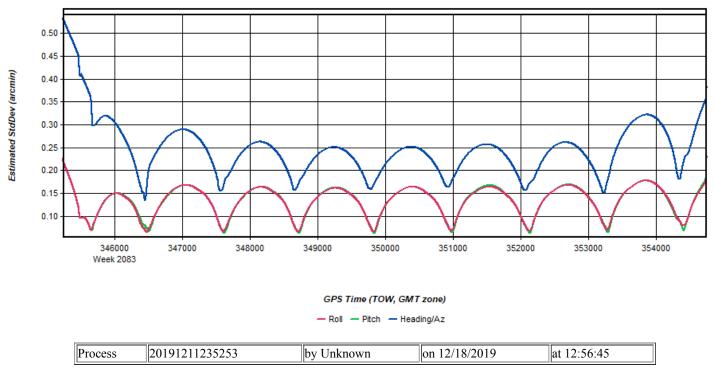






Figure 12: 20191211235253 [Smoothed TC Combined] - Roll & Pitch Plot



Figure 13: 20191211235253 [Smoothed TC Combined] - Velocity Profile Plot

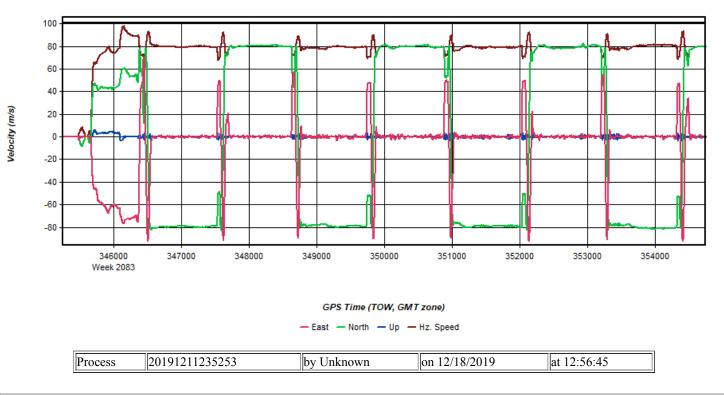


Figure 14: 20191211235253 [Smoothed TC Combined] - Body Frame Velocity Plot



Figure 15: 20191211235253 [Smoothed TC Combined] - Height Profile Plot

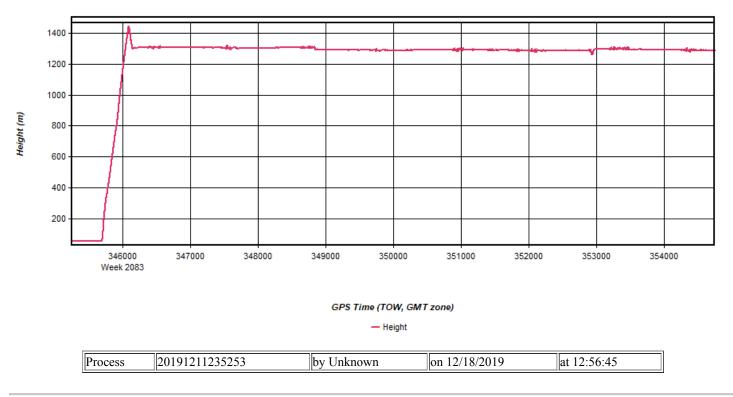


Figure 16: 20191211235253 [Smoothed TC Combined] - C/A Code Residual RMS Plot

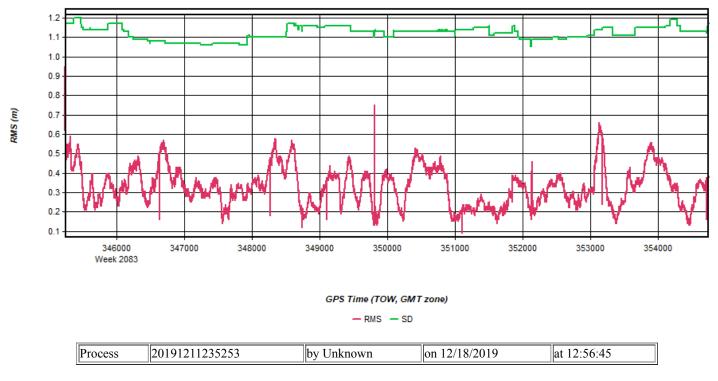


Figure 17: 20191211235253 [Smoothed TC Combined] - Carrier Residual RMS Plot

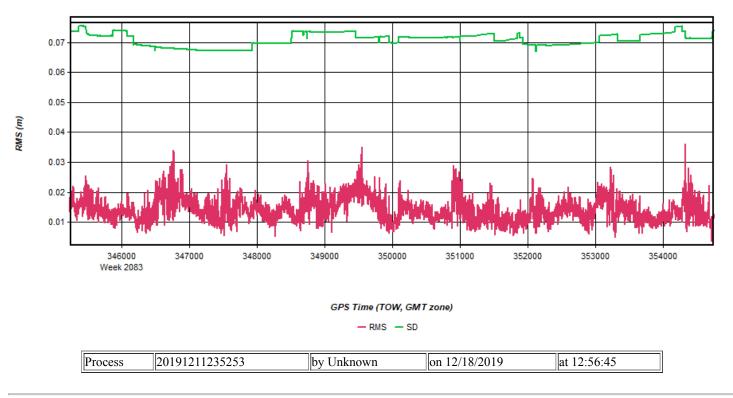
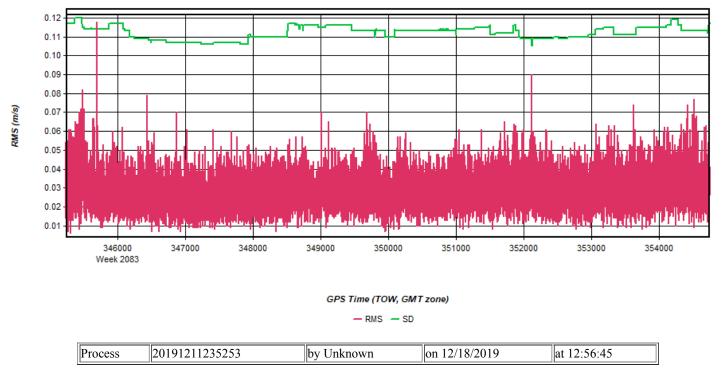


Figure 18: 20191211235253 [Smoothed TC Combined] - L1 Doppler Residual RMS Plot





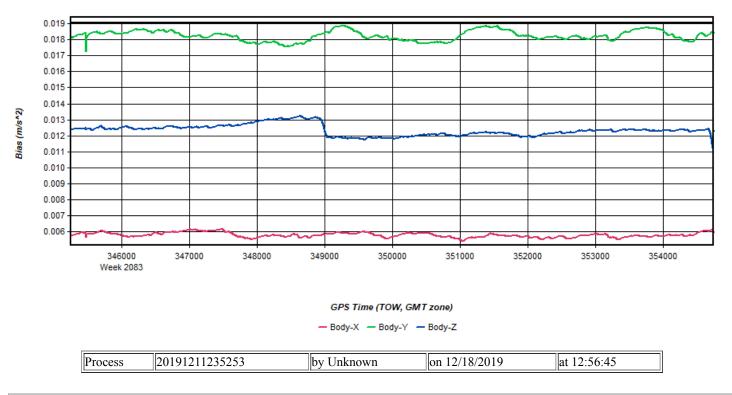
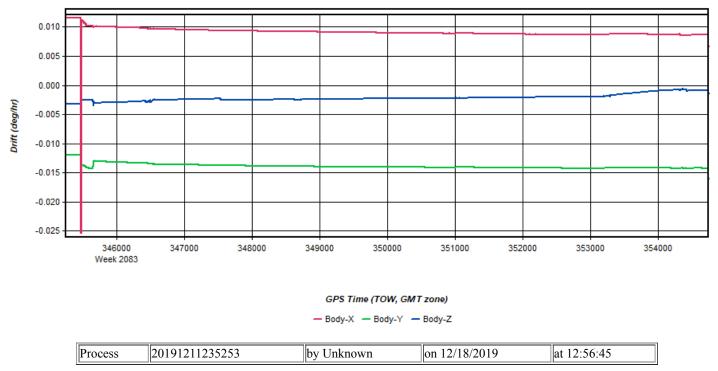


Figure 20: 20191211235253 [Smoothed TC Combined] - Gyro Drift Plot



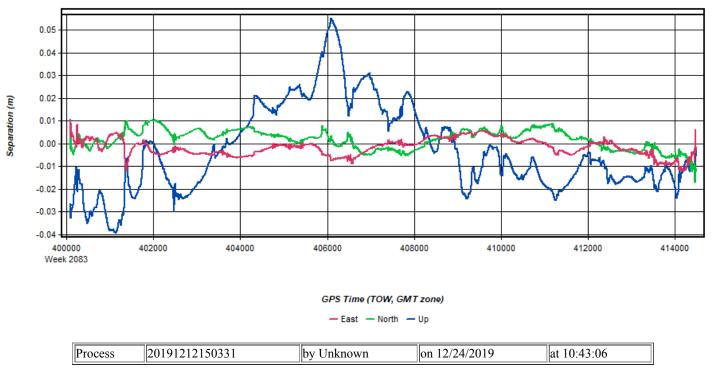
Output Results for 20191212150331

Inertial Explorer Version 8.80.2305 12/24/2019





Figure 2: 20191212150331 [Smoothed TC Combined] - Forward/Reverse or Combined Separation Plot





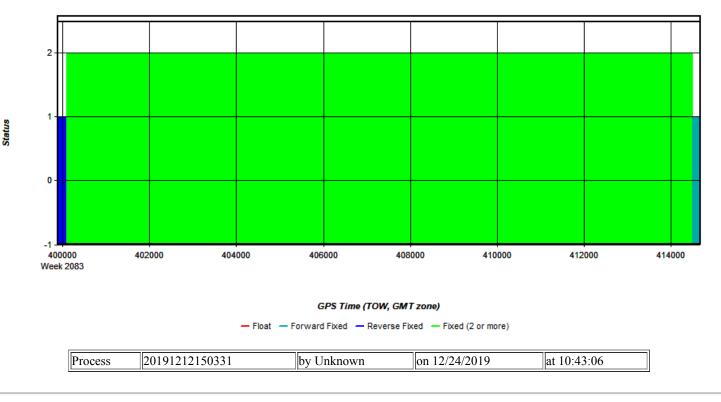


Figure 4: 20191212150331 [Smoothed TC Combined] - Forward/Reverse Separation Plot (Fixed)

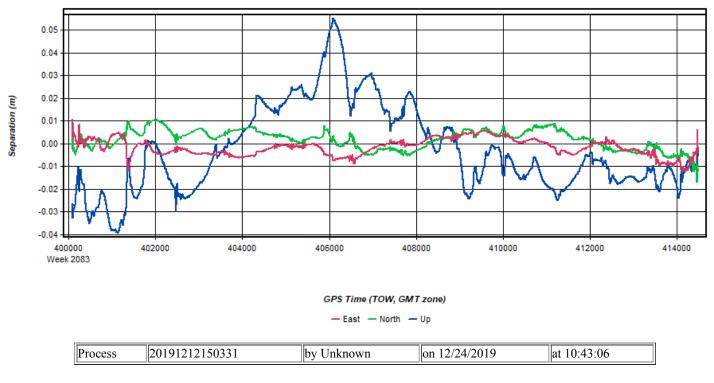


Figure 5: 20191212150331 [Smoothed TC Combined] - Estimated Position Accuracy Plot

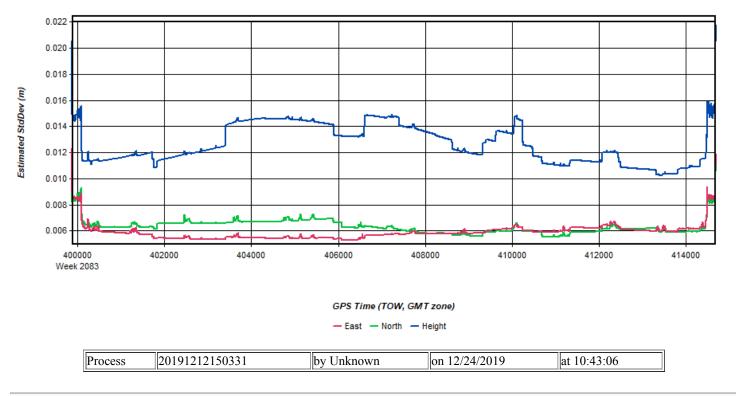


Figure 6: 20191212150331 [Smoothed TC Combined] - PDOP Plot

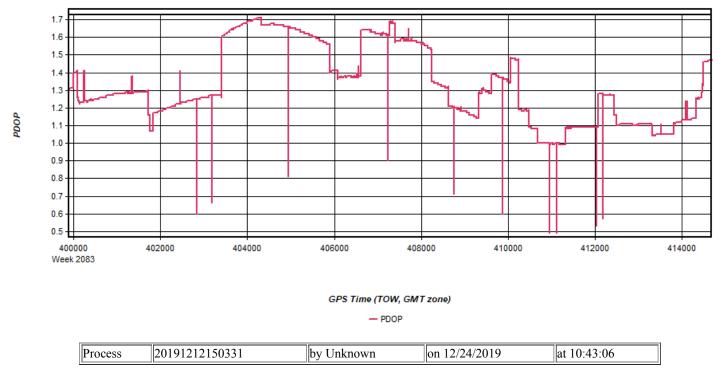


Figure 7: 20191212150331 [Smoothed TC Combined] - Number of Satellites Line Plot

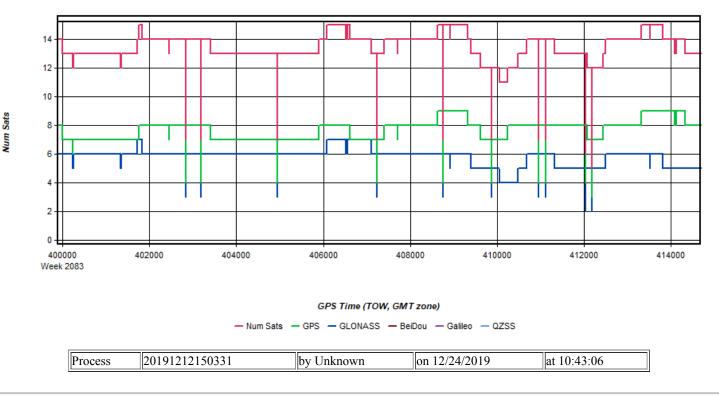


Figure 8: 20191212150331 [Smoothed TC Combined] - Status flag for IMU processing

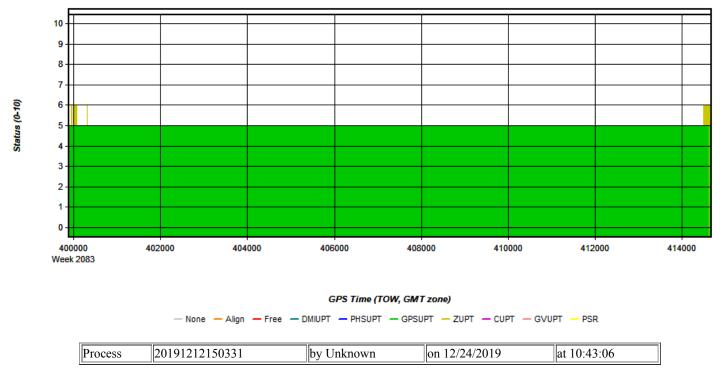


Figure 9: 20191212150331 [Smoothed TC Combined] - Fwd/Rev Attitude Separation Plot

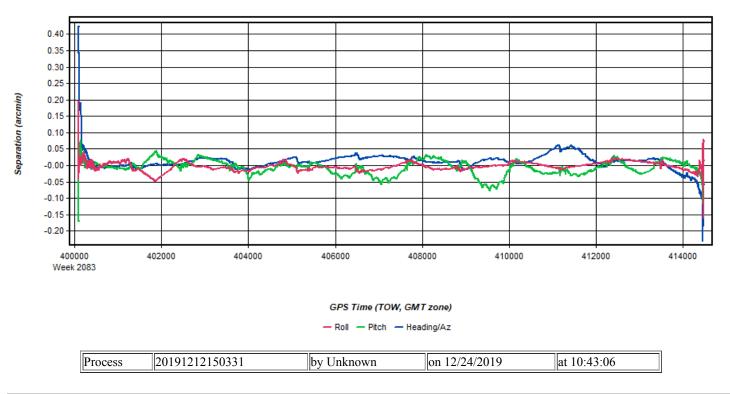
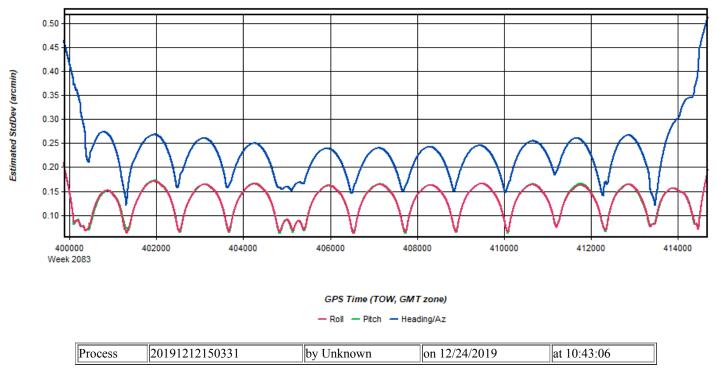


Figure 10: 20191212150331 [Smoothed TC Combined] - Estimated Attitude Accuracy Plot



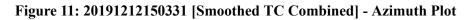




Figure 12: 20191212150331 [Smoothed TC Combined] - Roll & Pitch Plot



Figure 13: 20191212150331 [Smoothed TC Combined] - Velocity Profile Plot



Figure 14: 20191212150331 [Smoothed TC Combined] - Body Frame Velocity Plot

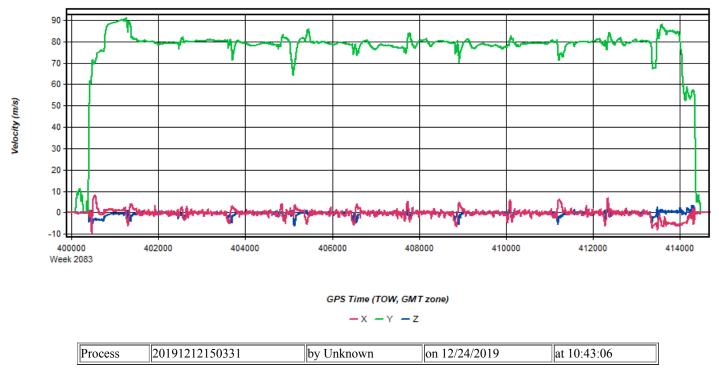


Figure 15: 20191212150331 [Smoothed TC Combined] - Height Profile Plot

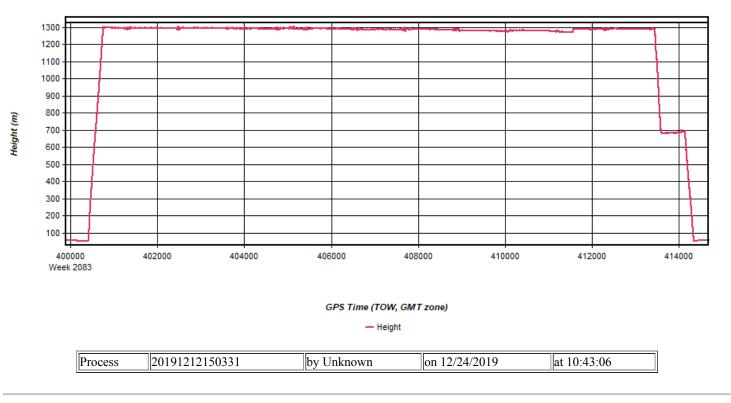


Figure 16: 20191212150331 [Smoothed TC Combined] - C/A Code Residual RMS Plot

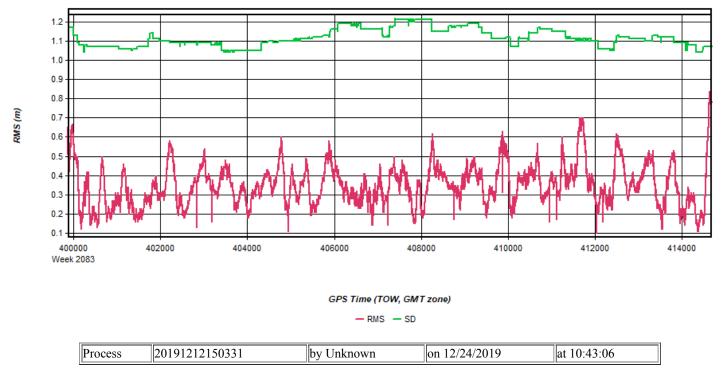


Figure 17: 20191212150331 [Smoothed TC Combined] - Carrier Residual RMS Plot

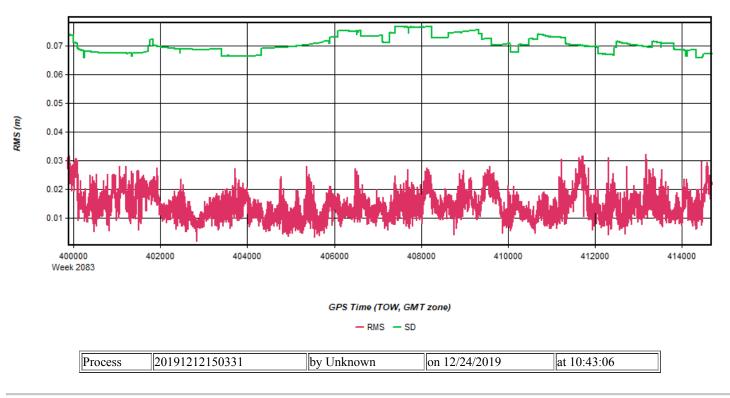
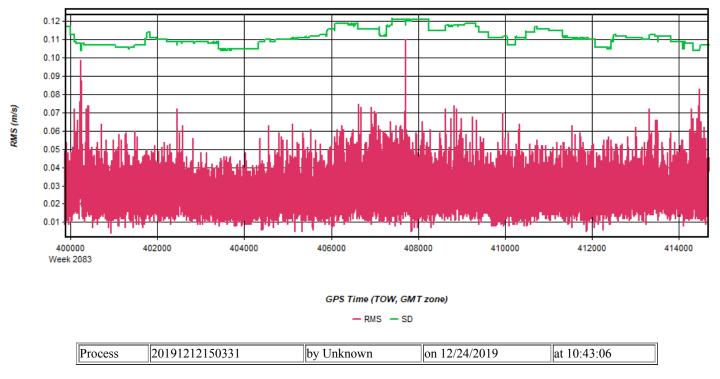


Figure 18: 20191212150331 [Smoothed TC Combined] - L1 Doppler Residual RMS Plot

Inertial Explorer Project 20191212150331





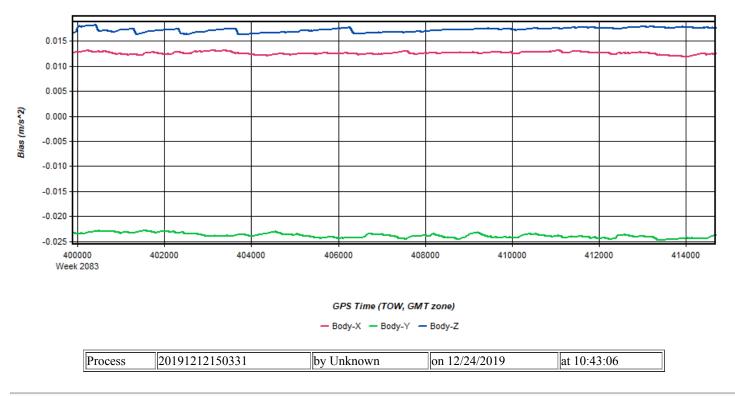
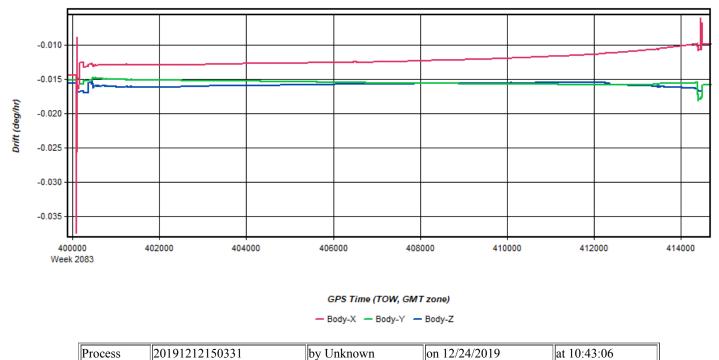


Figure 20: 20191212150331 [Smoothed TC Combined] - Gyro Drift Plot



Output Results for 20191212193215

Inertial Explorer Version 8.80.2305 12/24/2019

Figure 1: Smoothed TC Combined - Map

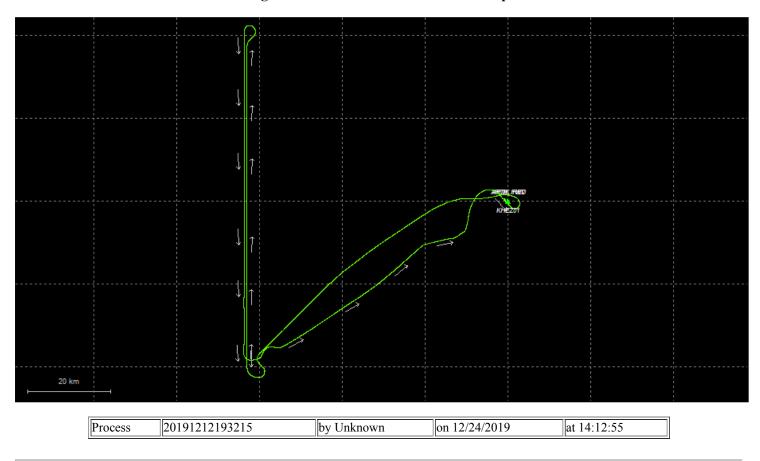
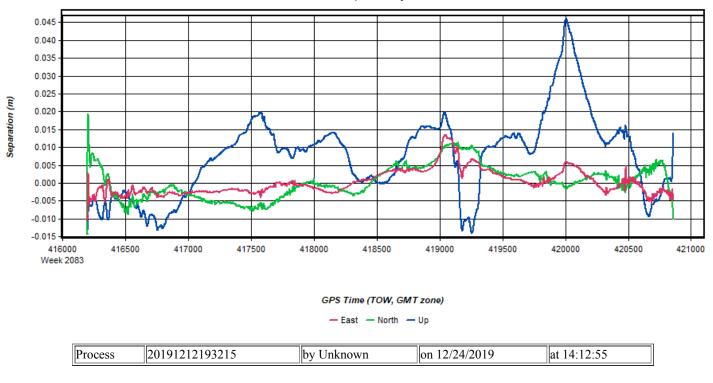


Figure 2: 20191212193215 [Smoothed TC Combined] - Forward/Reverse or Combined Separation Plot





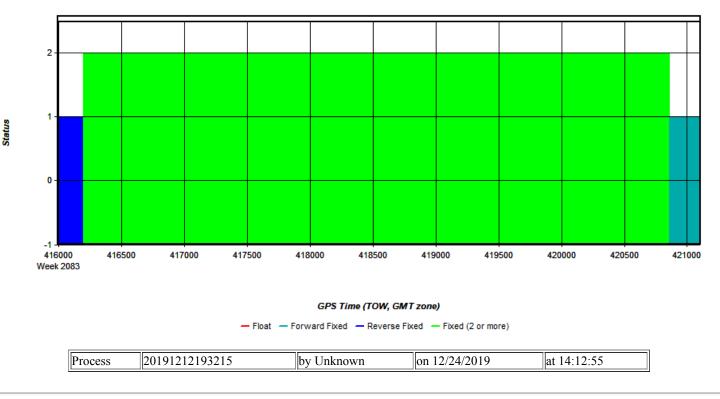
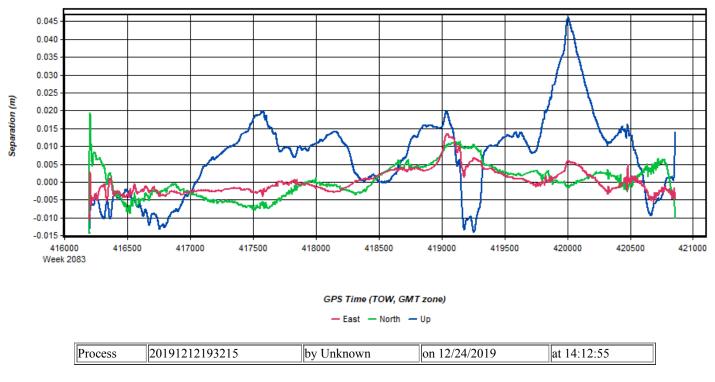


Figure 4: 20191212193215 [Smoothed TC Combined] - Forward/Reverse Separation Plot (Fixed)





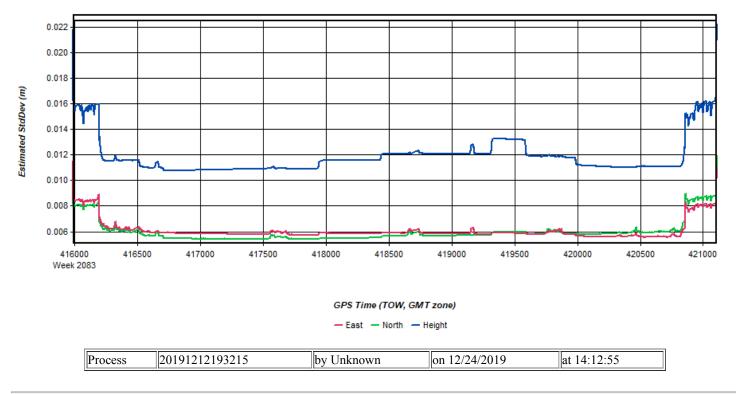


Figure 6: 20191212193215 [Smoothed TC Combined] - PDOP Plot

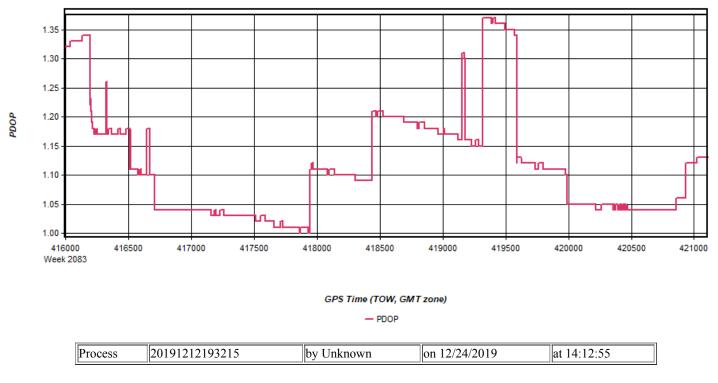


Figure 7: 20191212193215 [Smoothed TC Combined] - Number of Satellites Line Plot

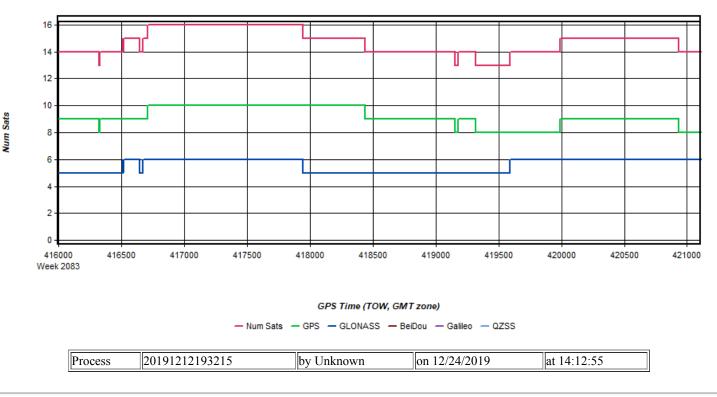


Figure 8: 20191212193215 [Smoothed TC Combined] - Status flag for IMU processing

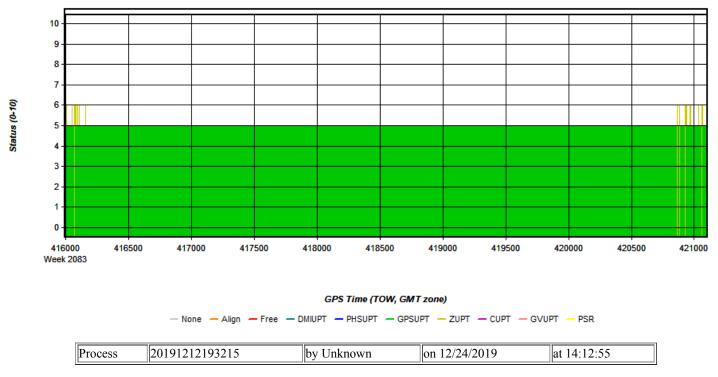


Figure 9: 20191212193215 [Smoothed TC Combined] - Fwd/Rev Attitude Separation Plot

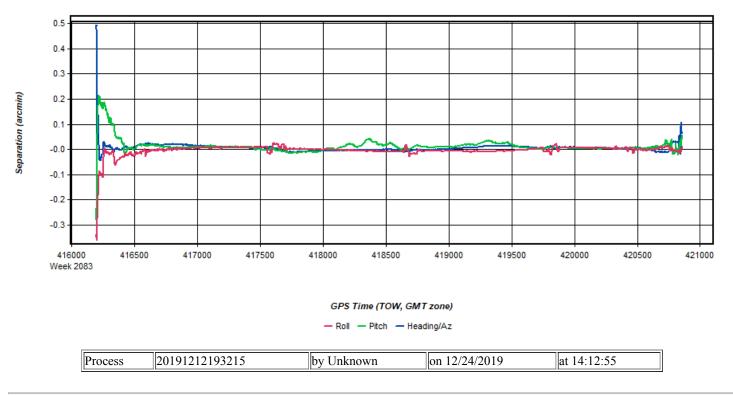


Figure 10: 20191212193215 [Smoothed TC Combined] - Estimated Attitude Accuracy Plot

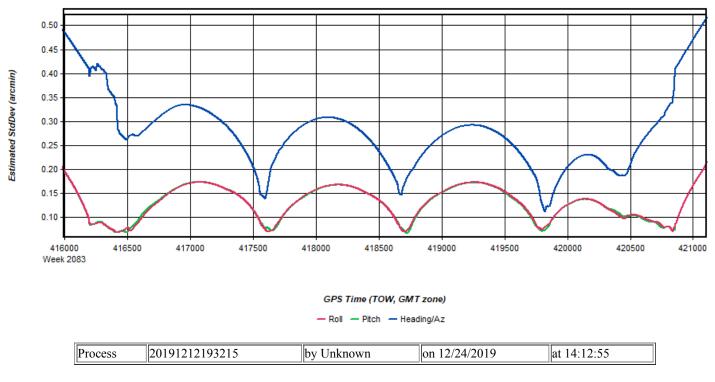


Figure 11: 20191212193215 [Smoothed TC Combined] - Azimuth Plot

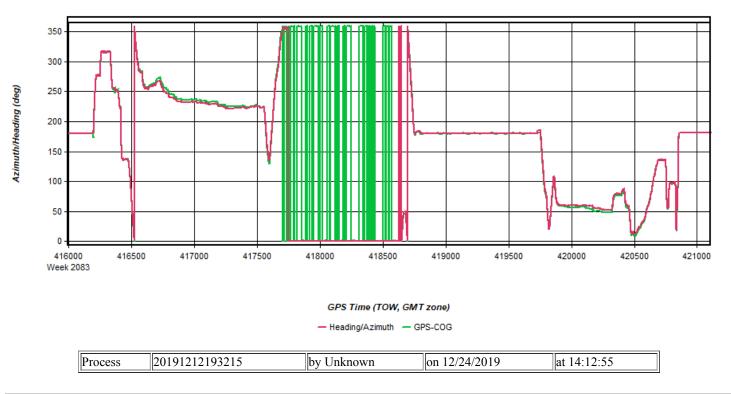


Figure 12: 20191212193215 [Smoothed TC Combined] - Roll & Pitch Plot



Figure 13: 20191212193215 [Smoothed TC Combined] - Velocity Profile Plot

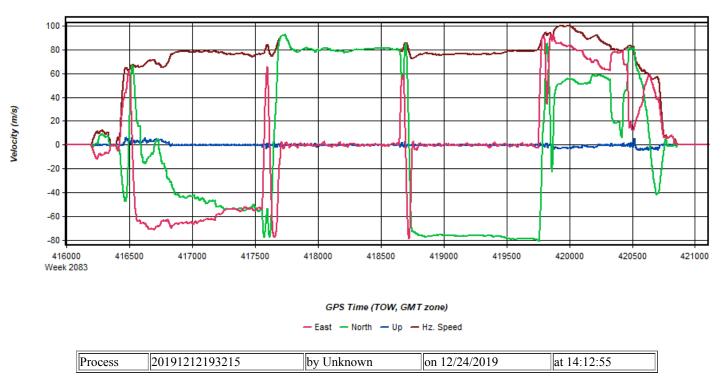
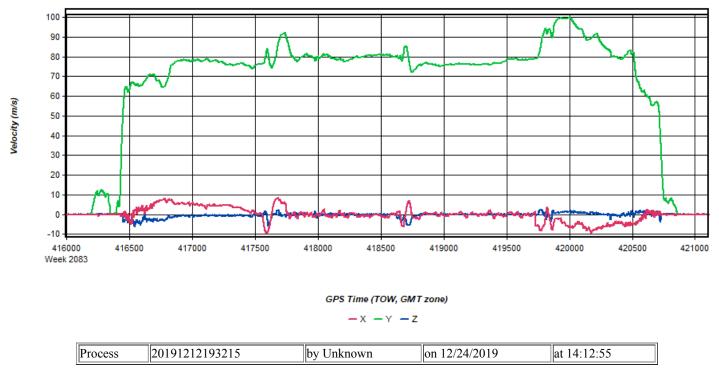
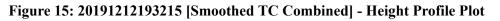


Figure 14: 20191212193215 [Smoothed TC Combined] - Body Frame Velocity Plot





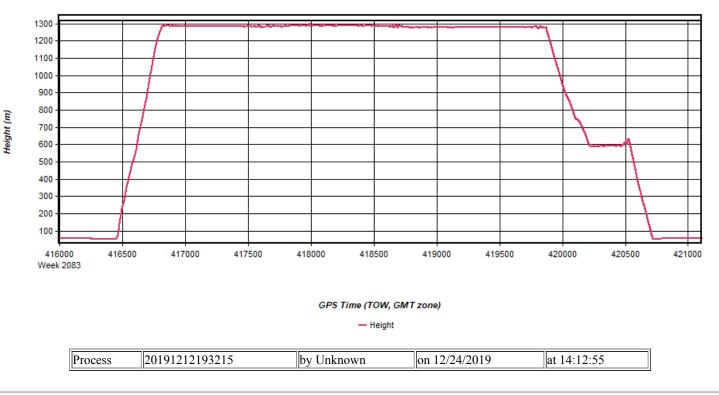


Figure 16: 20191212193215 [Smoothed TC Combined] - C/A Code Residual RMS Plot

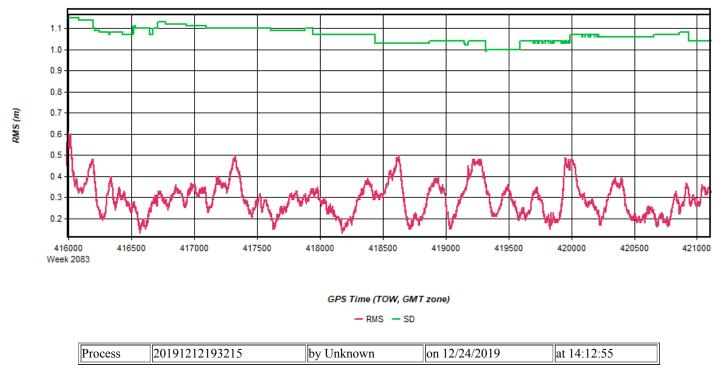


Figure 17: 20191212193215 [Smoothed TC Combined] - Carrier Residual RMS Plot

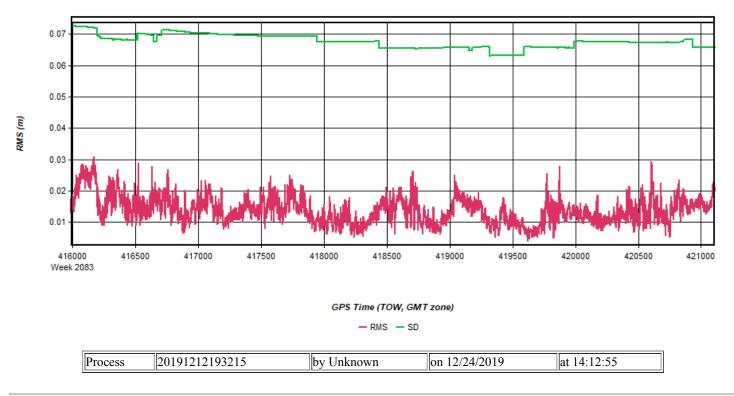
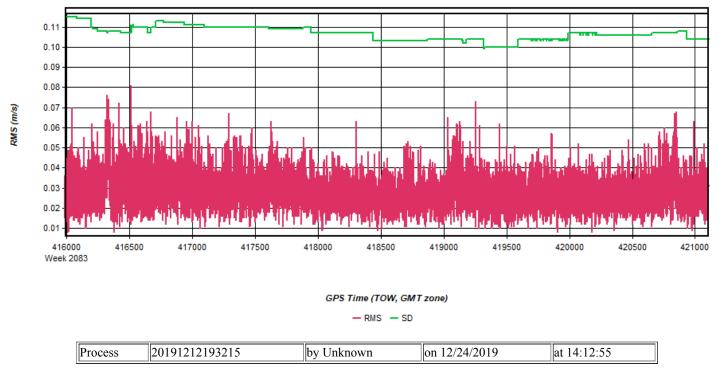


Figure 18: 20191212193215 [Smoothed TC Combined] - L1 Doppler Residual RMS Plot





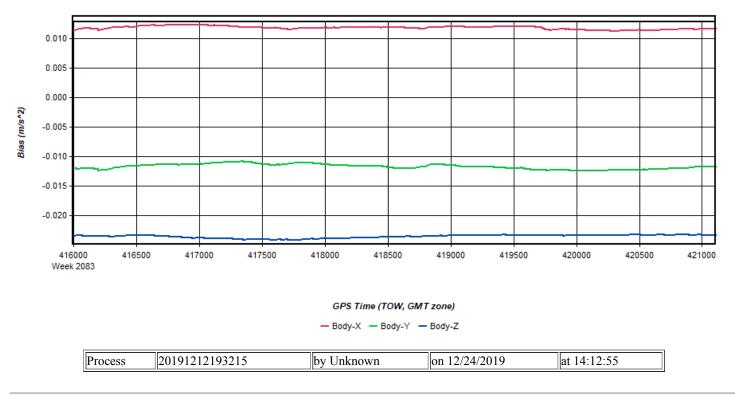
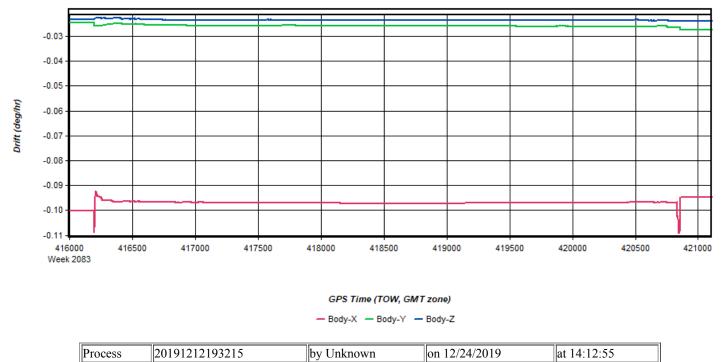


Figure 20: 20191212193215 [Smoothed TC Combined] - Gyro Drift Plot



Output Results for 20191214204650

Inertial Explorer Version 8.80.2305 12/24/2019

Figure 1: Smoothed TC Combined - Map



Figure 2: 20191214204650 [Smoothed TC Combined] - Forward/Reverse or Combined Separation Plot





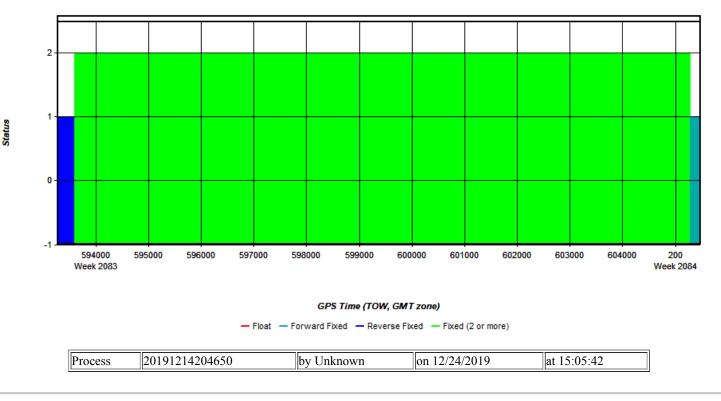


Figure 4: 20191214204650 [Smoothed TC Combined] - Forward/Reverse Separation Plot (Fixed)



Figure 5: 20191214204650 [Smoothed TC Combined] - Estimated Position Accuracy Plot

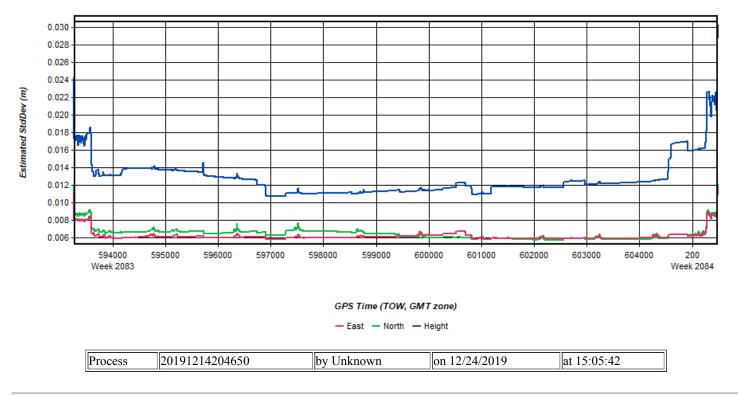


Figure 6: 20191214204650 [Smoothed TC Combined] - PDOP Plot

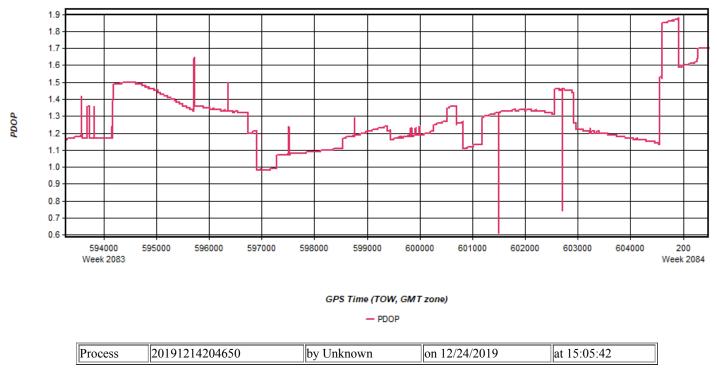


Figure 7: 20191214204650 [Smoothed TC Combined] - Number of Satellites Line Plot

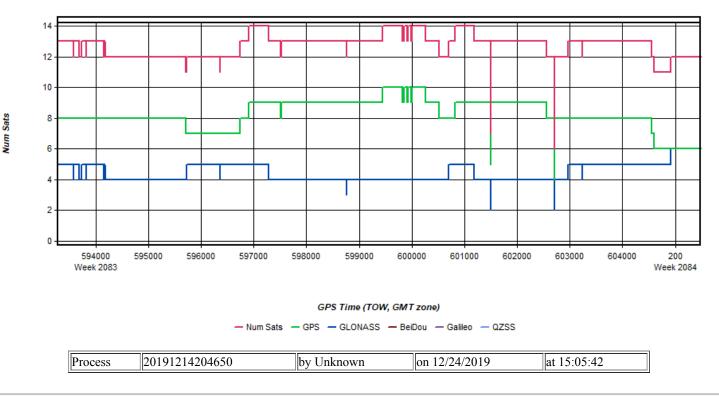


Figure 8: 20191214204650 [Smoothed TC Combined] - Status flag for IMU processing

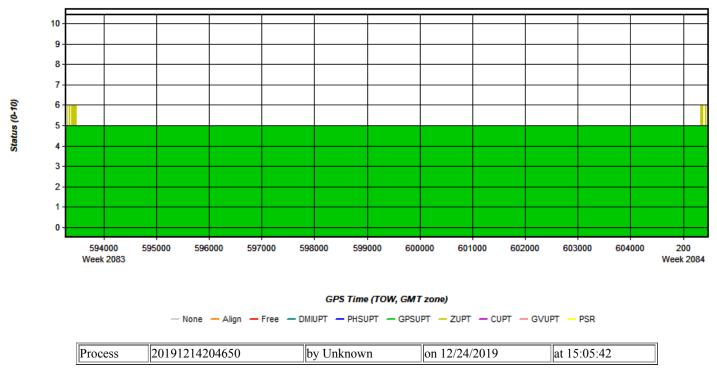


Figure 9: 20191214204650 [Smoothed TC Combined] - Fwd/Rev Attitude Separation Plot

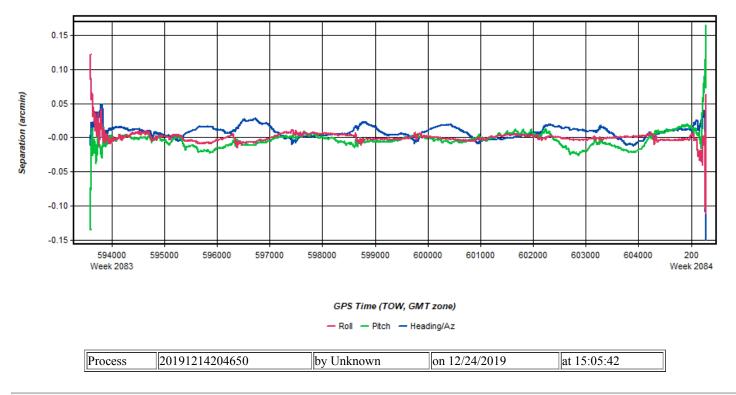


Figure 10: 20191214204650 [Smoothed TC Combined] - Estimated Attitude Accuracy Plot

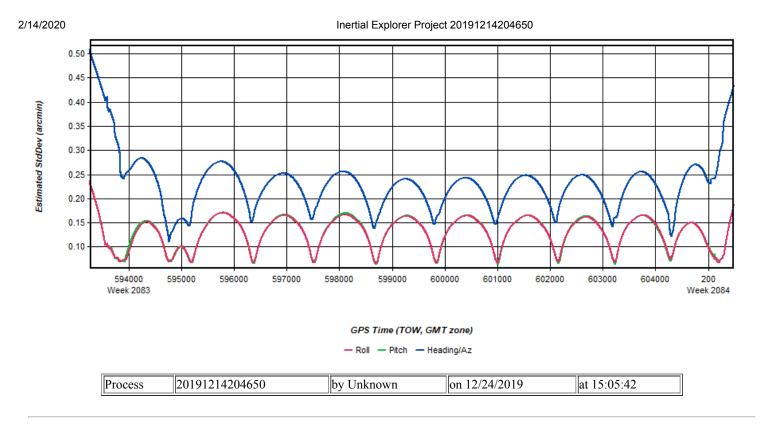


Figure 11: 20191214204650 [Smoothed TC Combined] - Azimuth Plot



Figure 12: 20191214204650 [Smoothed TC Combined] - Roll & Pitch Plot



Figure 13: 20191214204650 [Smoothed TC Combined] - Velocity Profile Plot

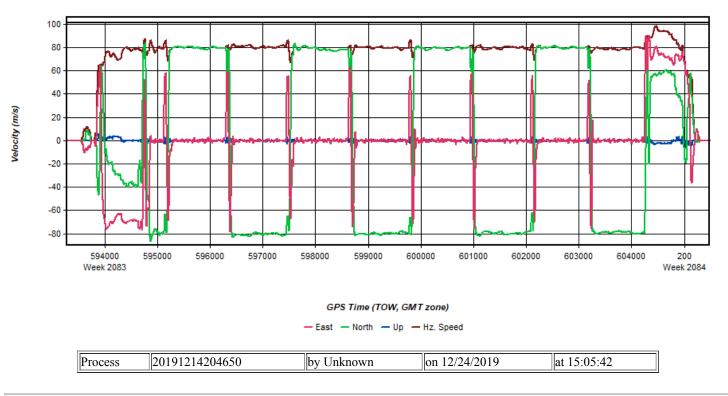


Figure 14: 20191214204650 [Smoothed TC Combined] - Body Frame Velocity Plot

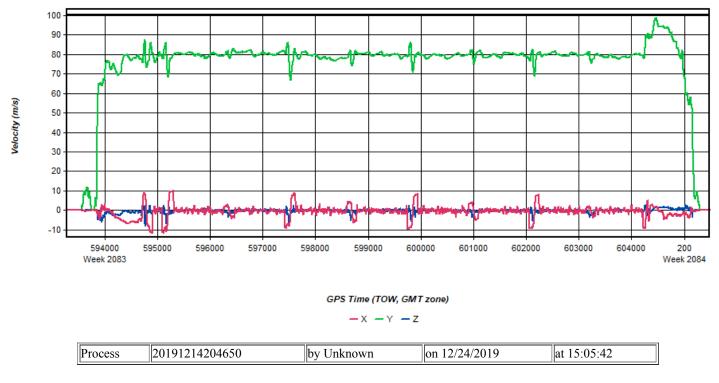


Figure 15: 20191214204650 [Smoothed TC Combined] - Height Profile Plot

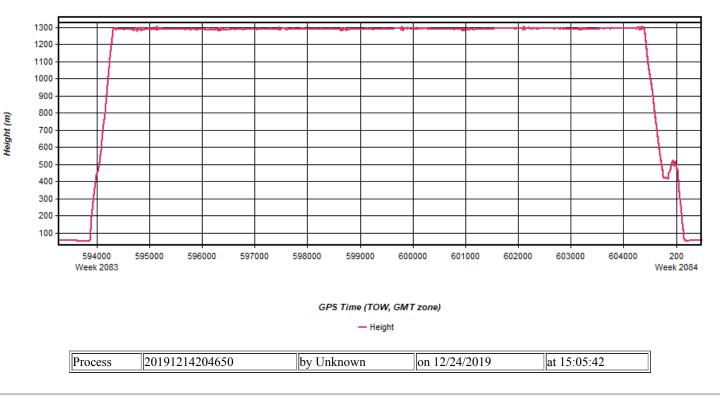


Figure 16: 20191214204650 [Smoothed TC Combined] - C/A Code Residual RMS Plot

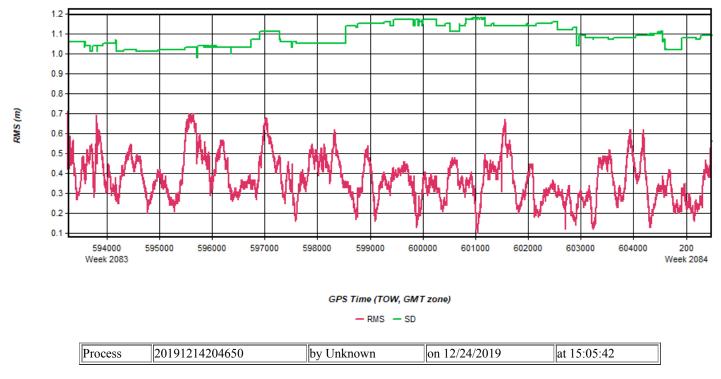


Figure 17: 20191214204650 [Smoothed TC Combined] - Carrier Residual RMS Plot

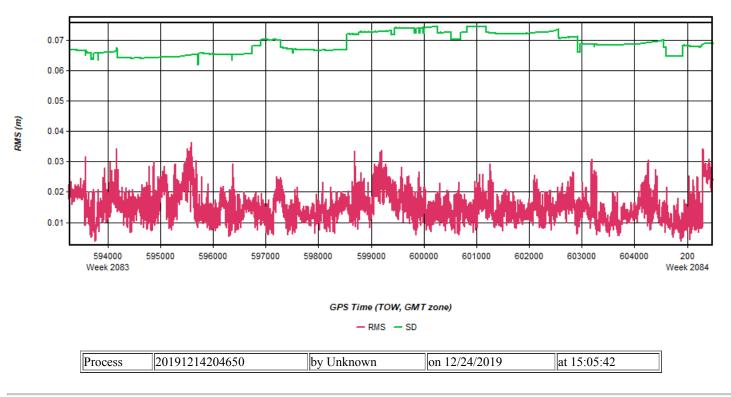
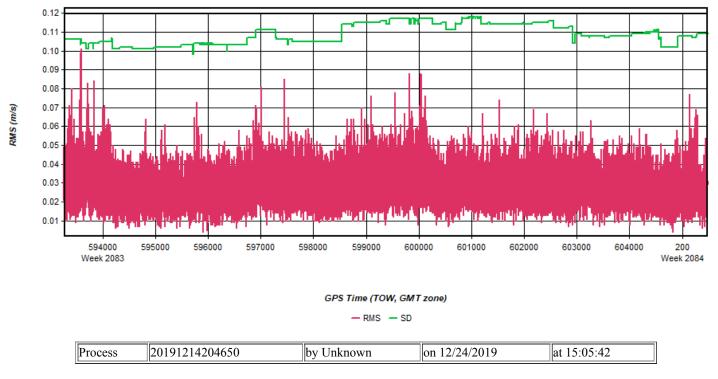


Figure 18: 20191214204650 [Smoothed TC Combined] - L1 Doppler Residual RMS Plot





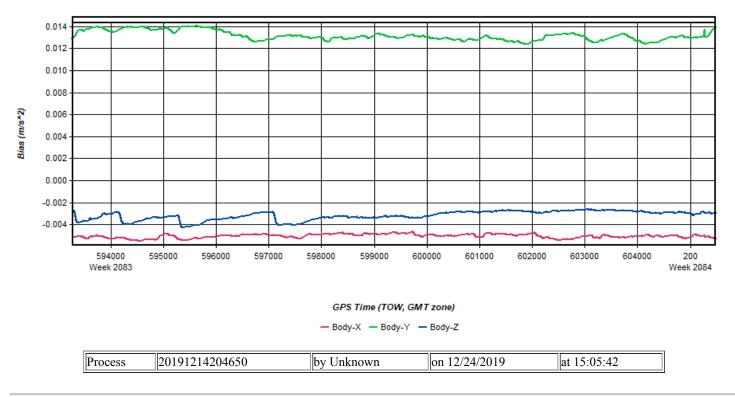


Figure 20: 20191214204650 [Smoothed TC Combined] - Gyro Drift Plot



Output Results for 20191215004501

Inertial Explorer Version 8.80.2305 12/24/2019

Figure 1: Smoothed TC Combined - Map

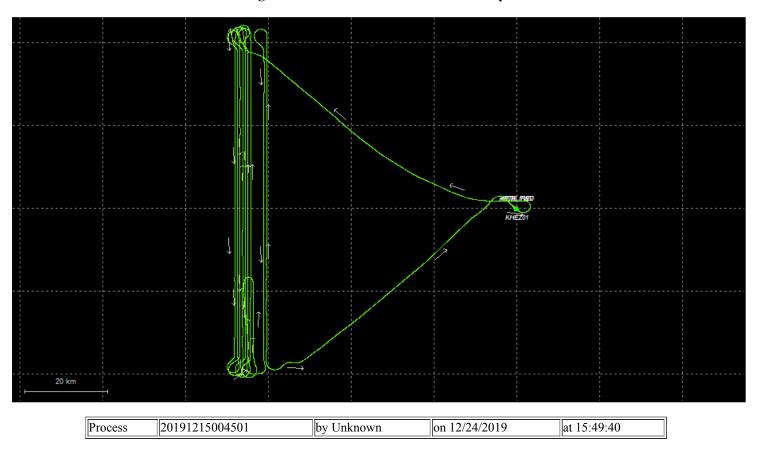
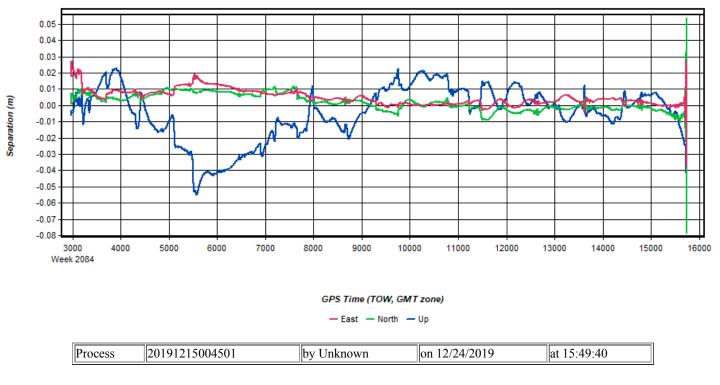


Figure 2: 20191215004501 [Smoothed TC Combined] - Forward/Reverse or Combined Separation Plot





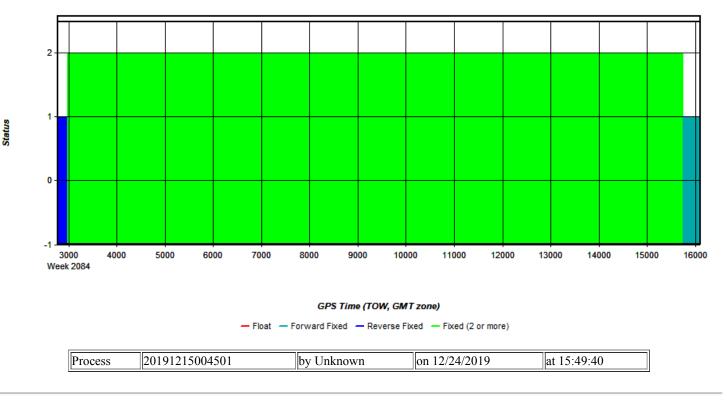


Figure 4: 20191215004501 [Smoothed TC Combined] - Forward/Reverse Separation Plot (Fixed)

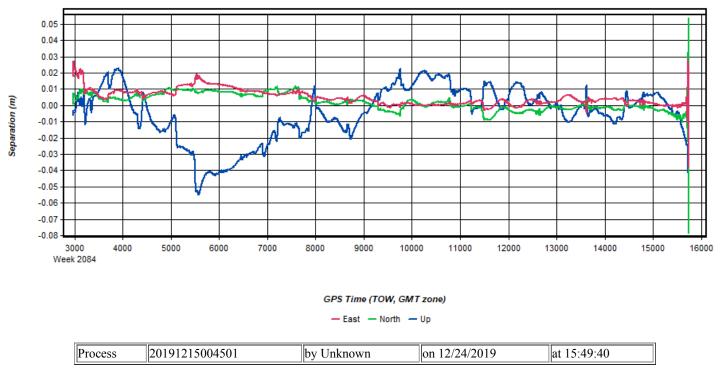


Figure 5: 20191215004501 [Smoothed TC Combined] - Estimated Position Accuracy Plot

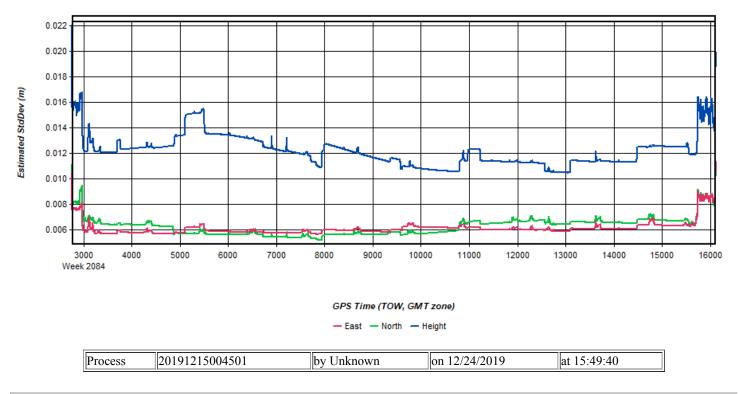


Figure 6: 20191215004501 [Smoothed TC Combined] - PDOP Plot

Num Sats

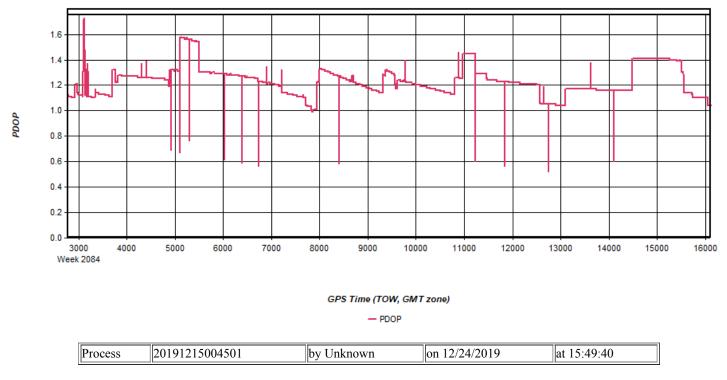


Figure 7: 20191215004501 [Smoothed TC Combined] - Number of Satellites Line Plot

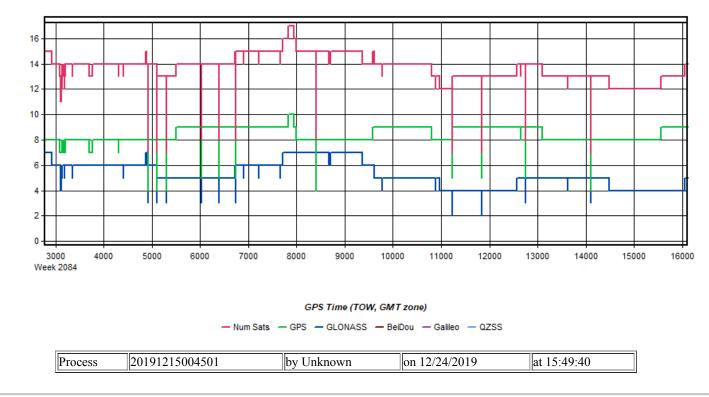


Figure 8: 20191215004501 [Smoothed TC Combined] - Status flag for IMU processing

Separation (arcmin)

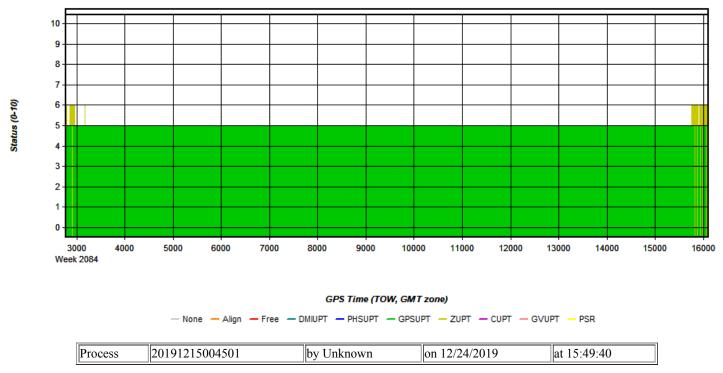


Figure 9: 20191215004501 [Smoothed TC Combined] - Fwd/Rev Attitude Separation Plot

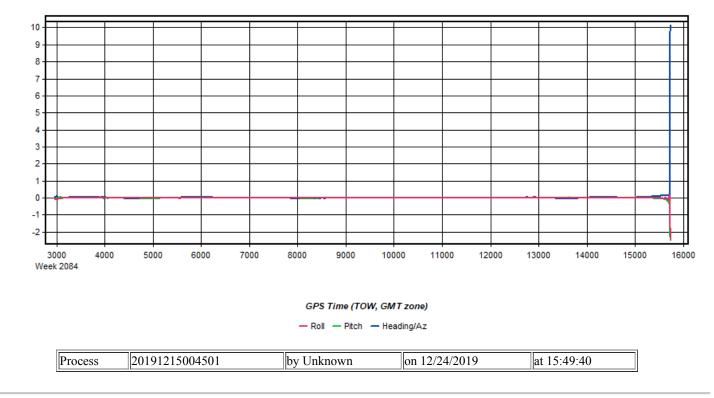


Figure 10: 20191215004501 [Smoothed TC Combined] - Estimated Attitude Accuracy Plot

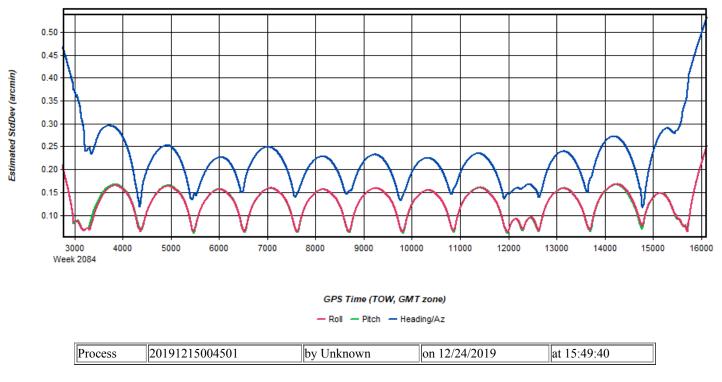


Figure 11: 20191215004501 [Smoothed TC Combined] - Azimuth Plot



Figure 12: 20191215004501 [Smoothed TC Combined] - Roll & Pitch Plot

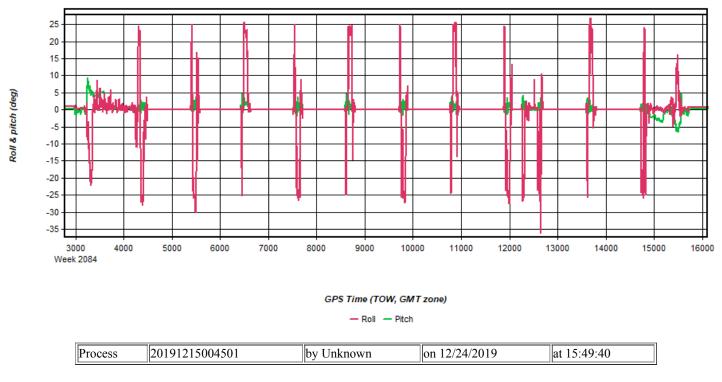


Figure 13: 20191215004501 [Smoothed TC Combined] - Velocity Profile Plot

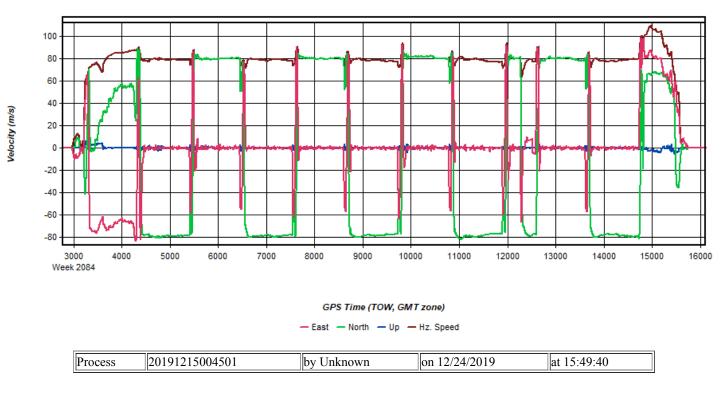
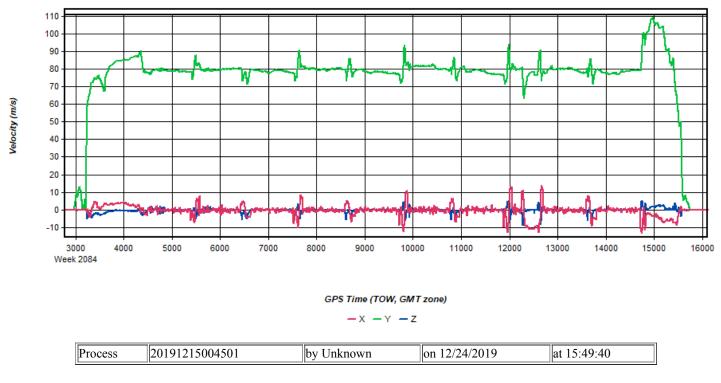


Figure 14: 20191215004501 [Smoothed TC Combined] - Body Frame Velocity Plot





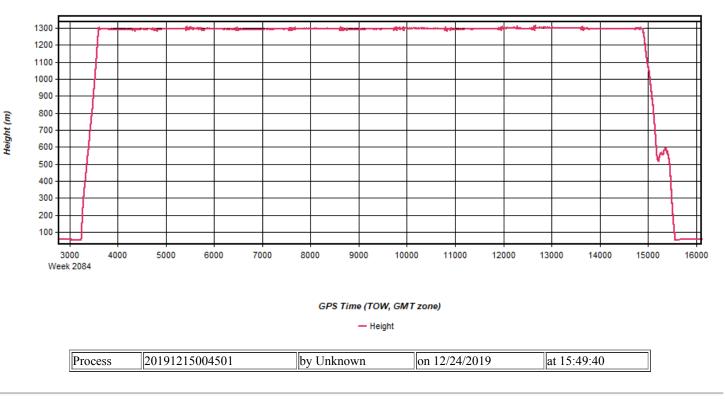


Figure 16: 20191215004501 [Smoothed TC Combined] - C/A Code Residual RMS Plot

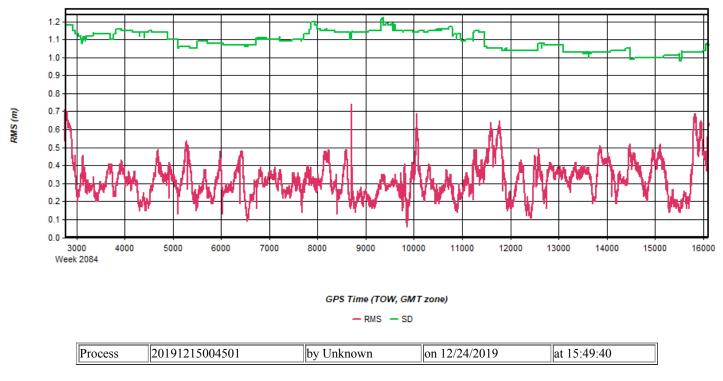


Figure 17: 20191215004501 [Smoothed TC Combined] - Carrier Residual RMS Plot

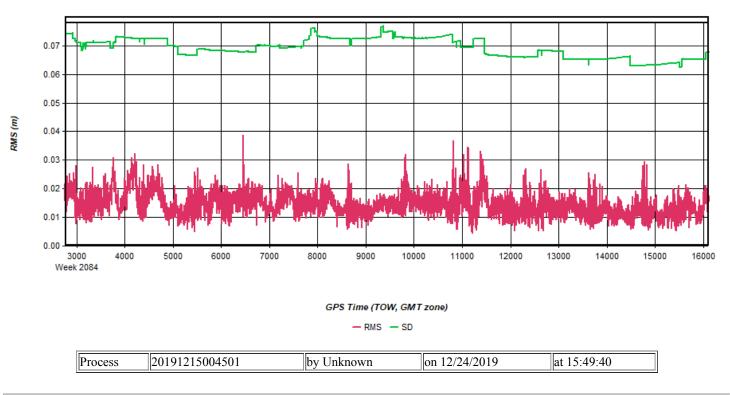
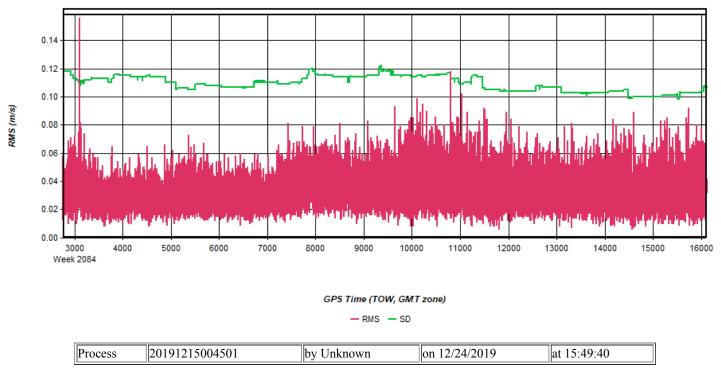


Figure 18: 20191215004501 [Smoothed TC Combined] - L1 Doppler Residual RMS Plot





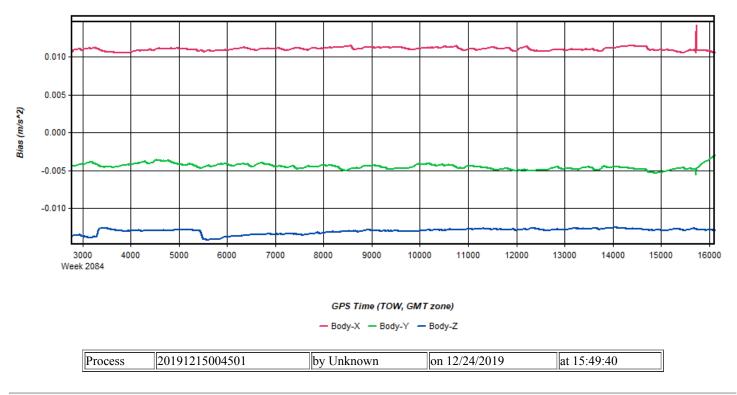


Figure 20: 20191215004501 [Smoothed TC Combined] - Gyro Drift Plot

