

Figure 1. 211003_Potomac_F1 Number_GPS_Satellites

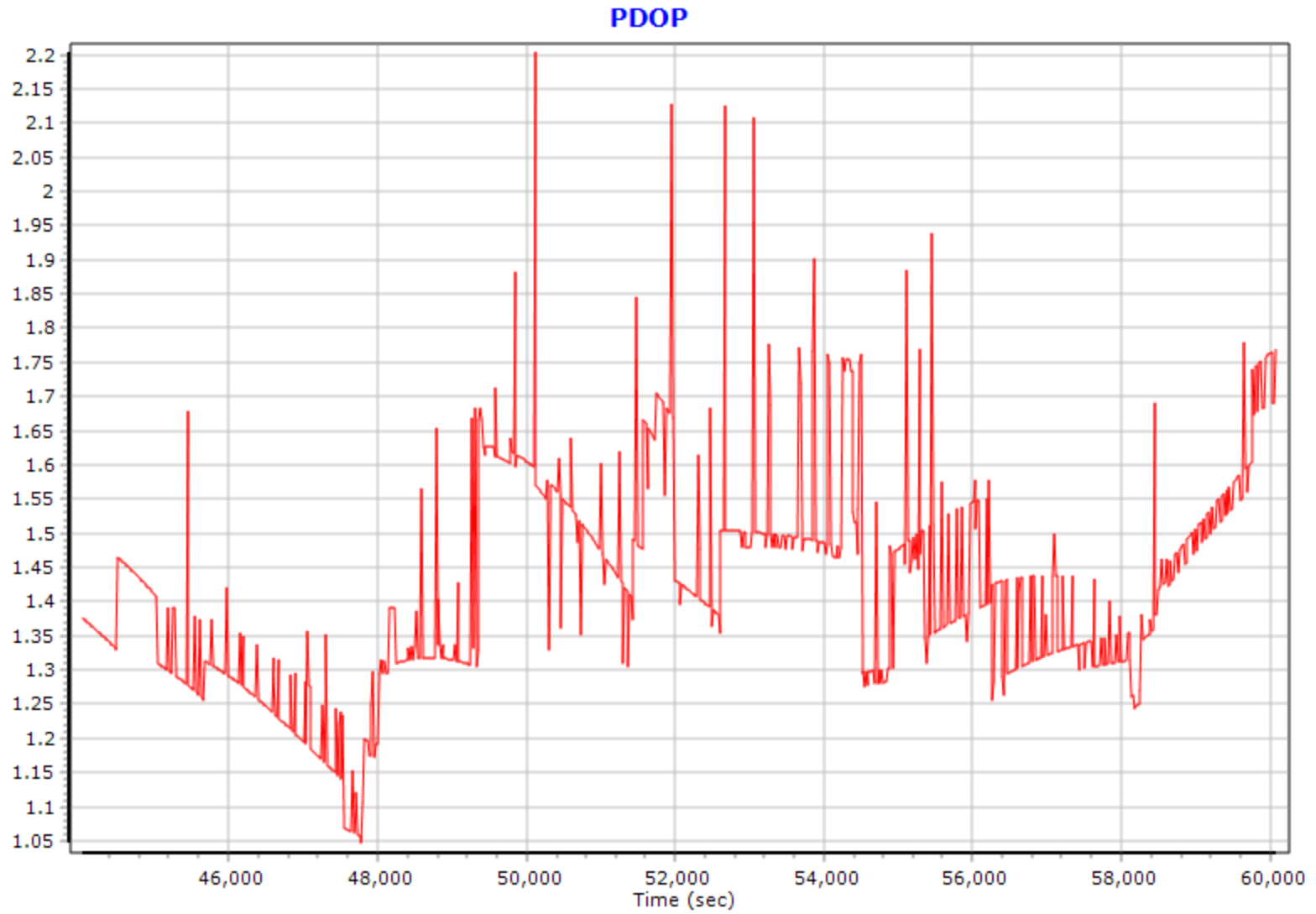


Figure 2. 211003_Potomac_F1 PDOP

Processing Mode

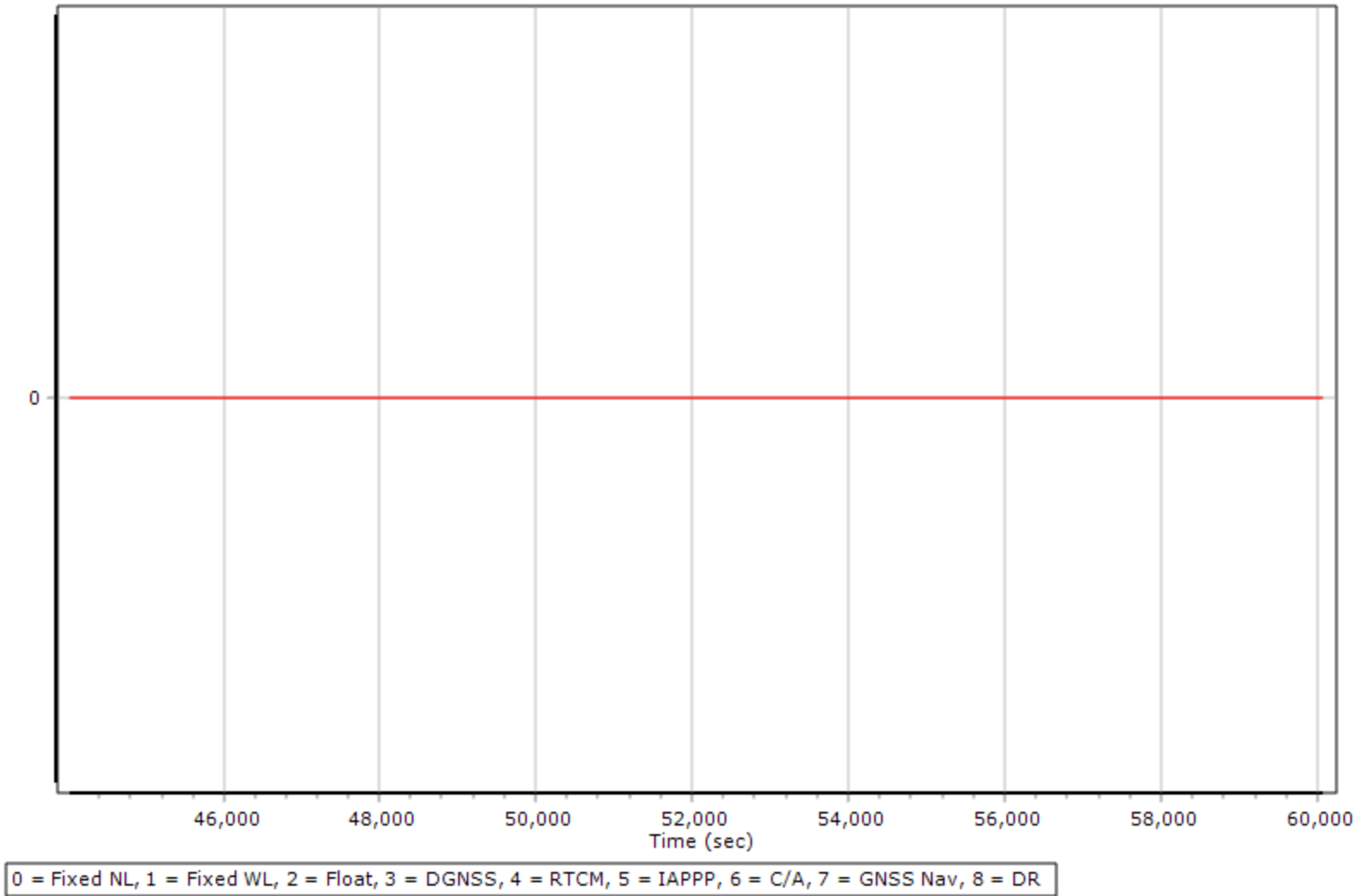


Figure 3. 211003_Potomac_F1 Processing Mode

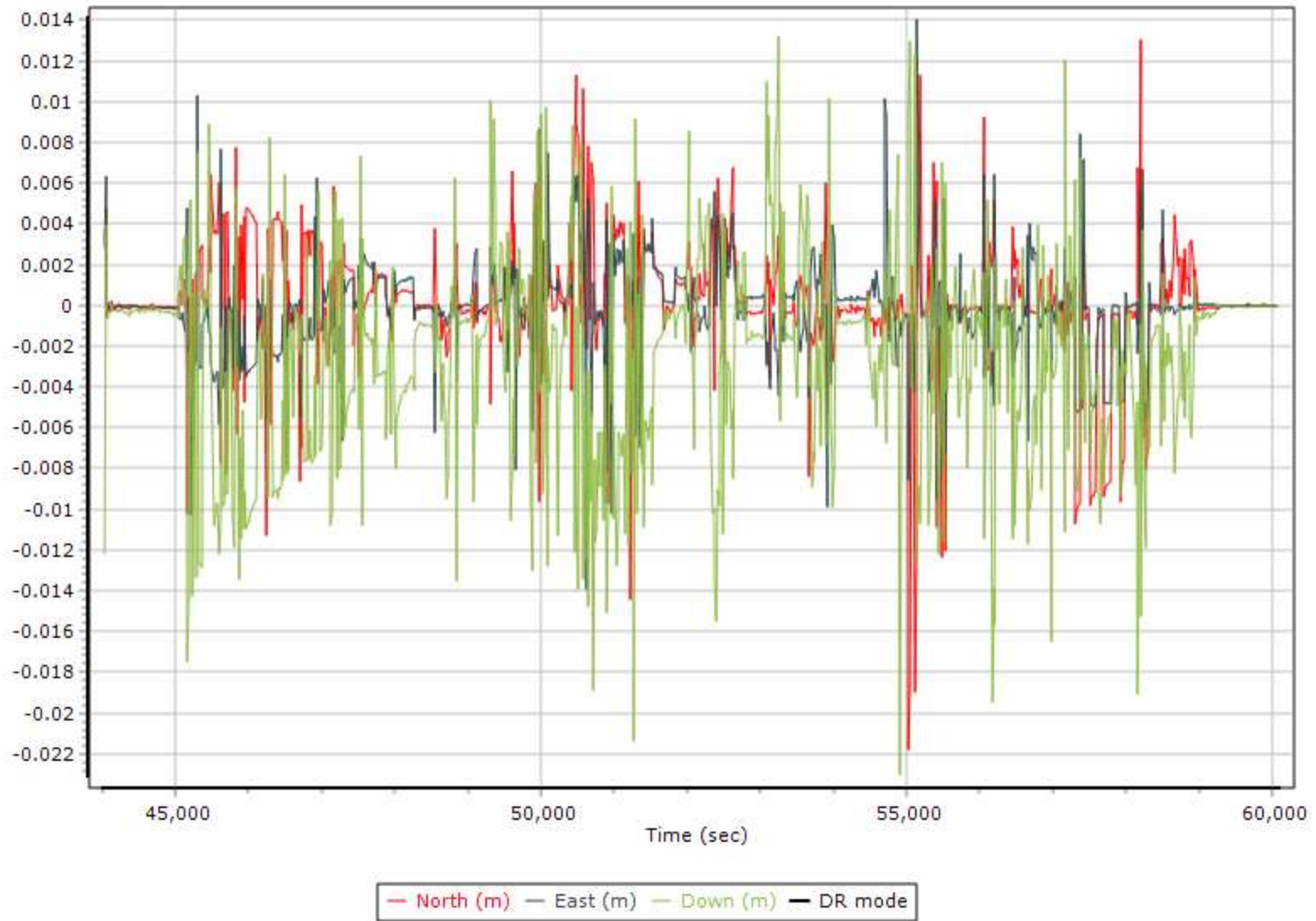


Figure 4. 211003_Potomac_F1 SBET IAKAR Separation

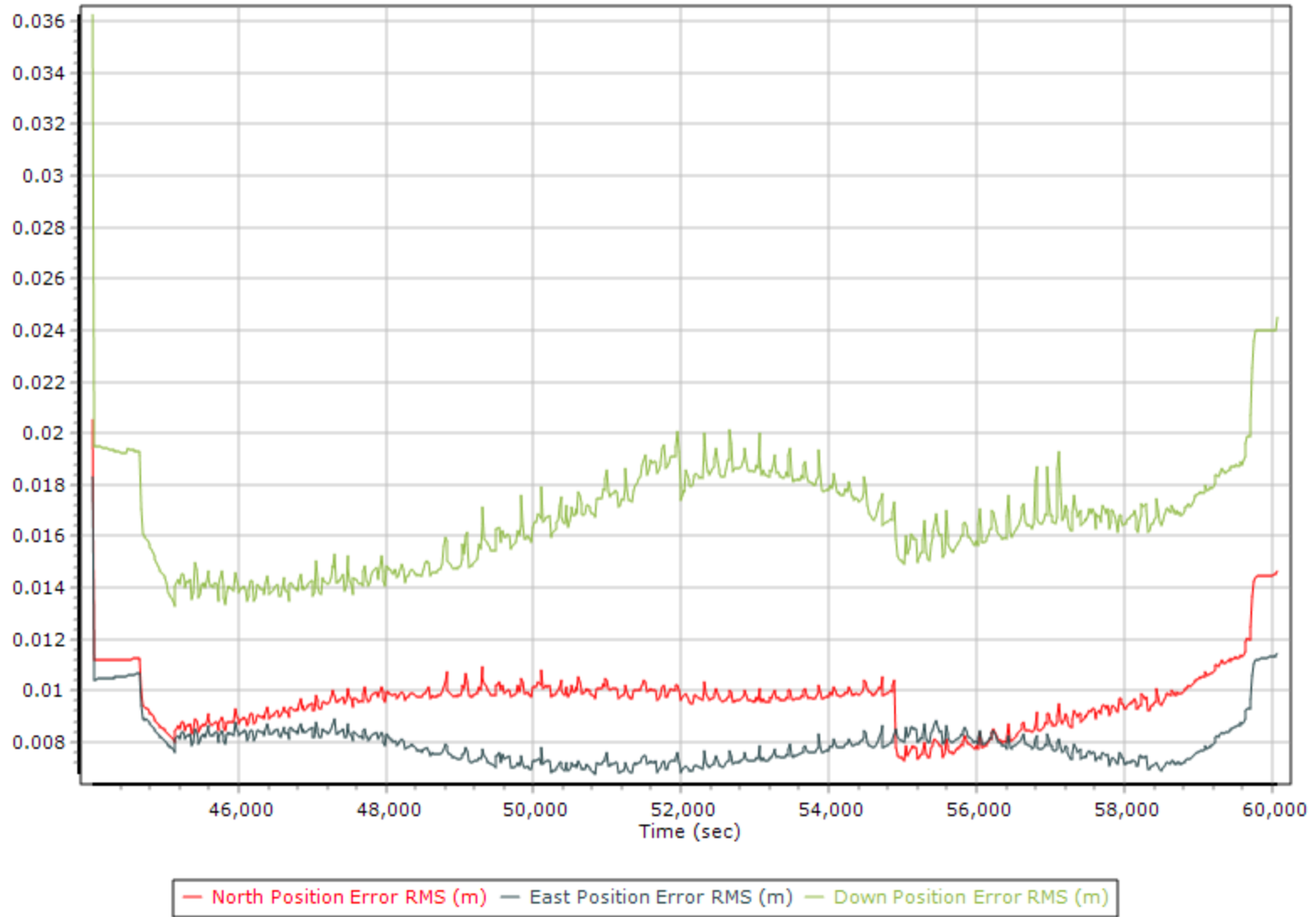


Figure 5. 211003_Potomac_F1 Smoothed Performance Metrics Reference Frame

X Reference-Primary GNSS Lever Arm (m)

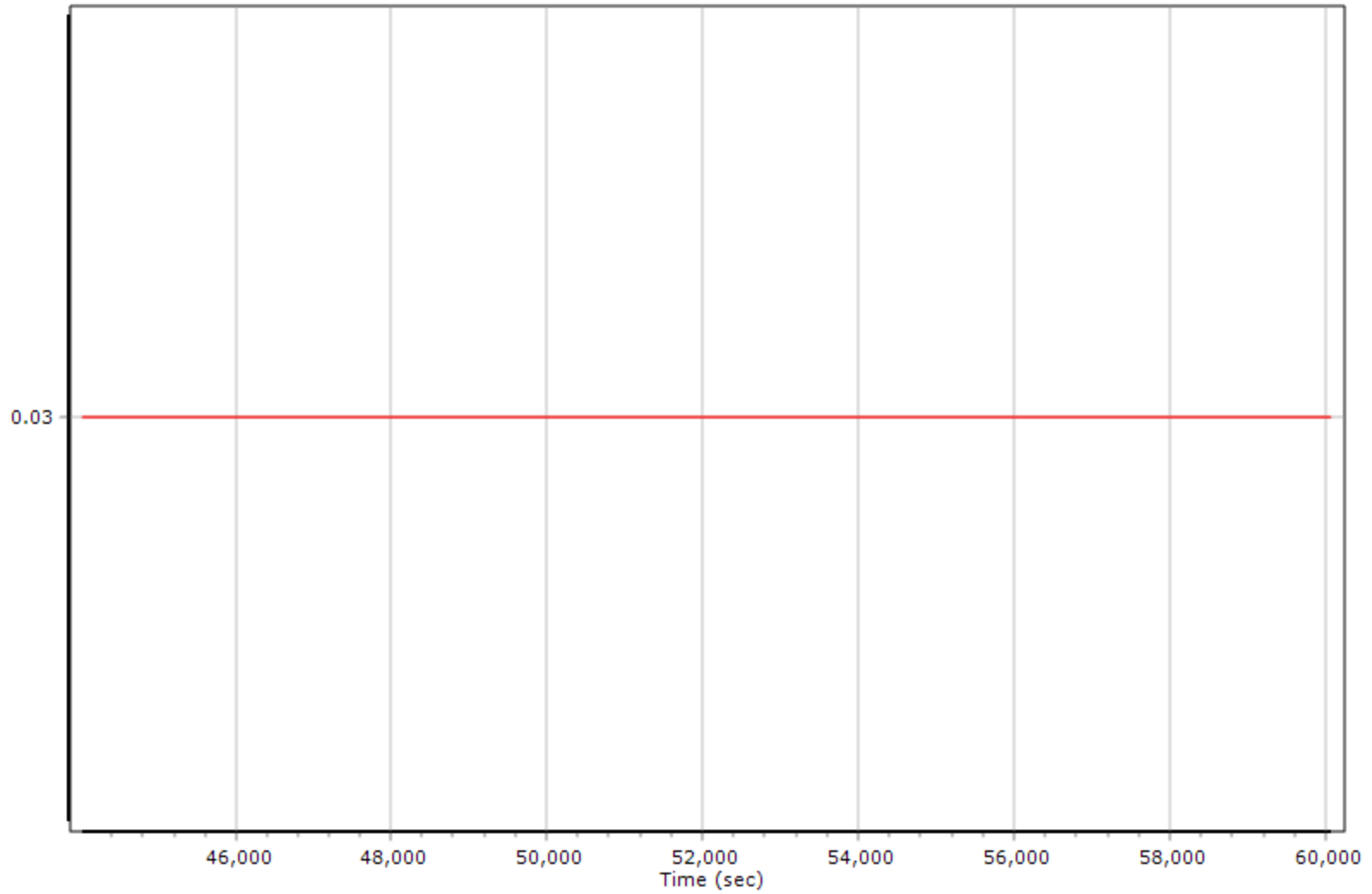


Figure 6. 211003_Potomac_F1 X Reference Primary Lever Arm

Y Reference-Primary GNSS Lever Arm (m)

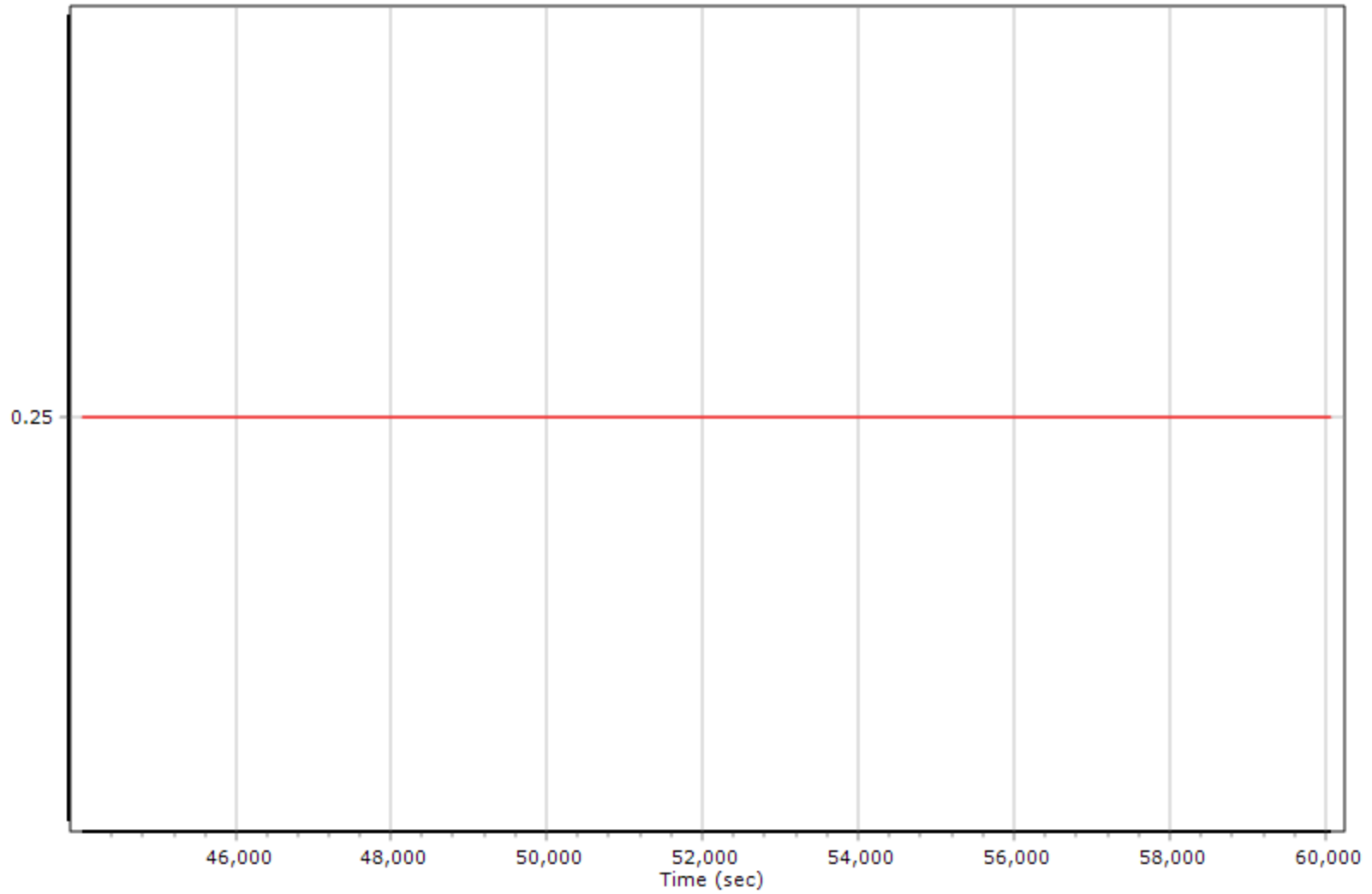


Figure 7. 211003_Potomac_F1 Y Reference Primary Lever Arm

Z Reference-Primary GNSS Lever Arm (m)

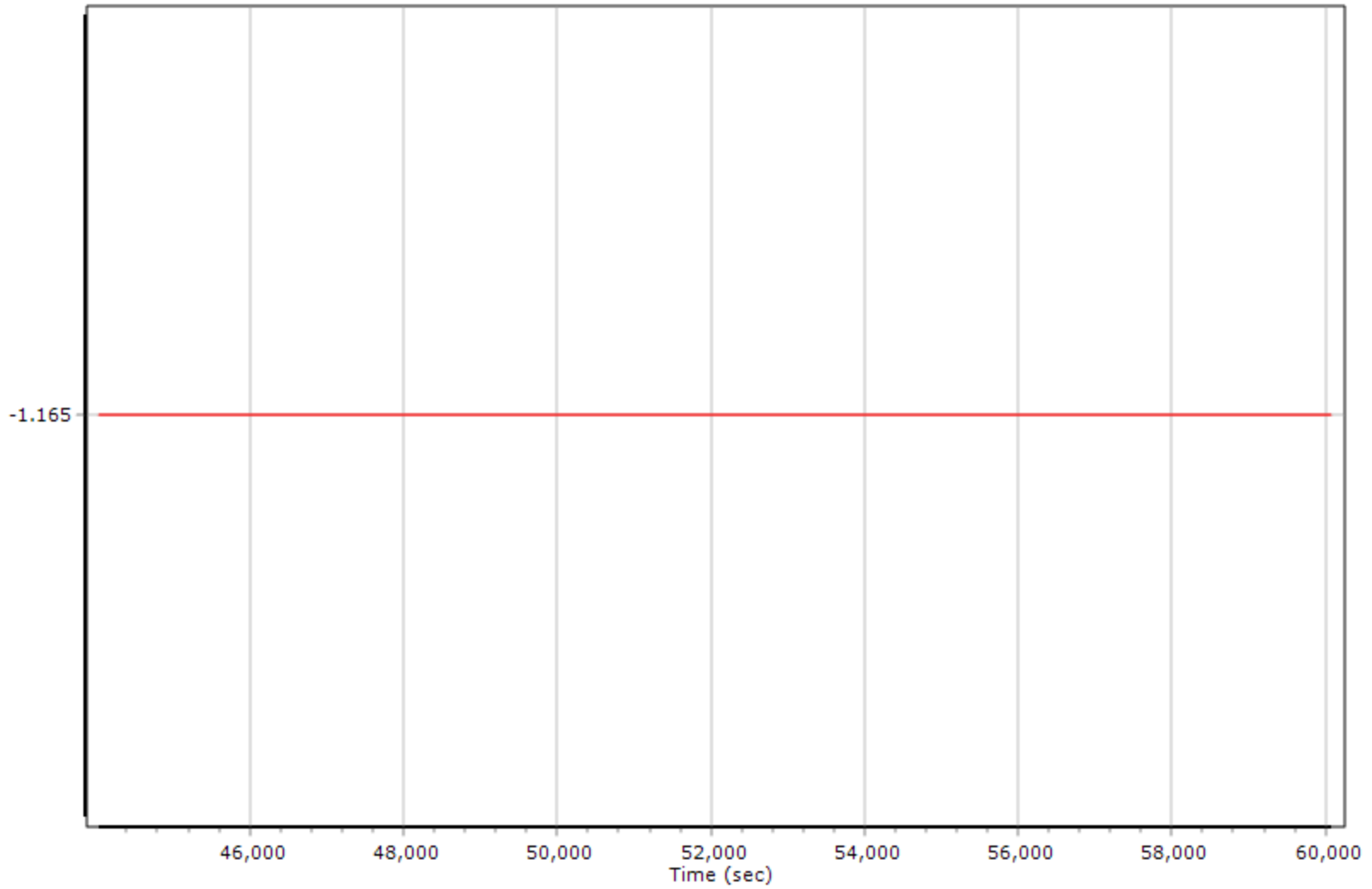


Figure 8. 211003_Potomac_F1 Z Reference Primary Lever Arm

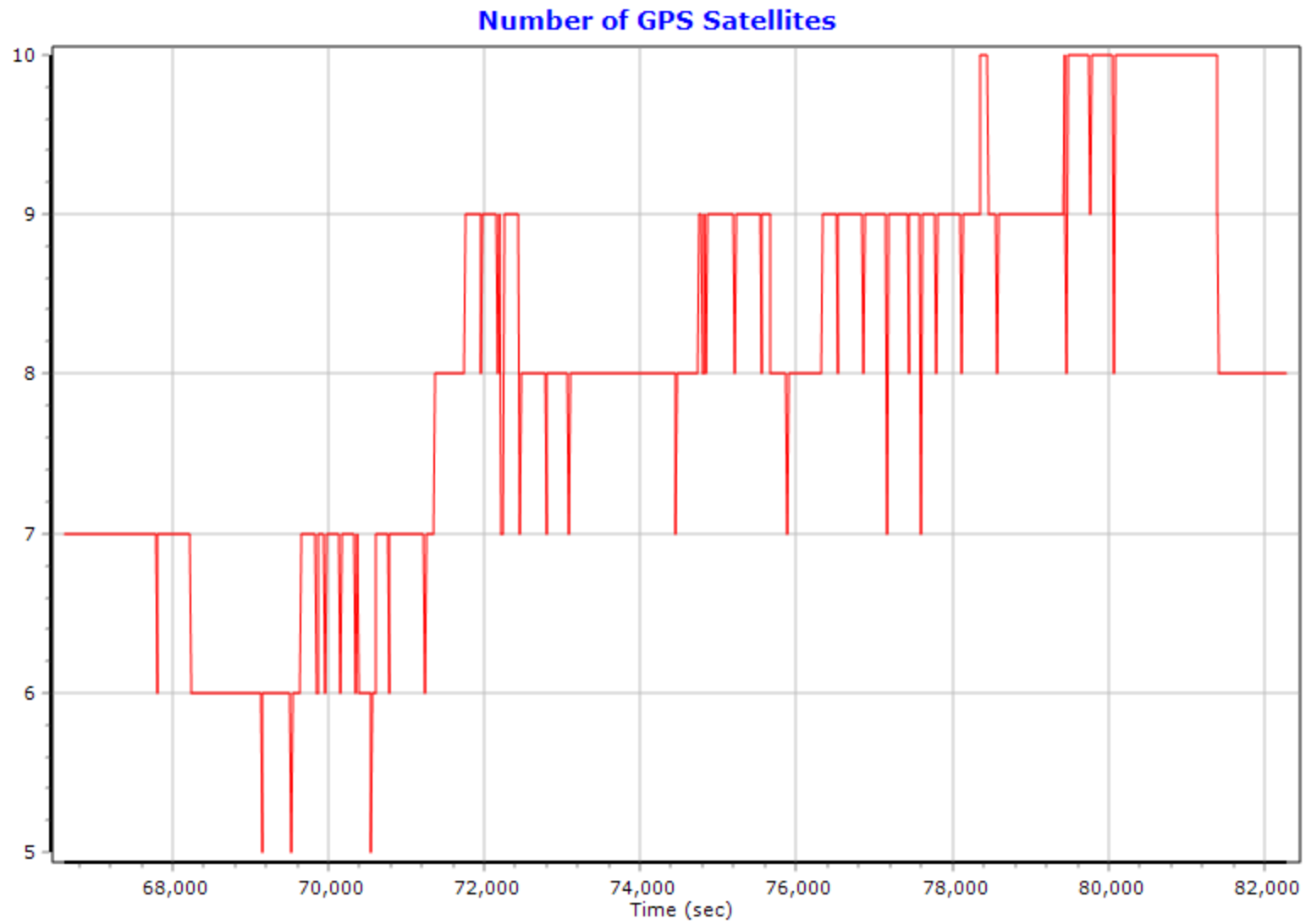


Figure 9. 211003_Potomac_F2 Number_GPS_Satellites

PDOP

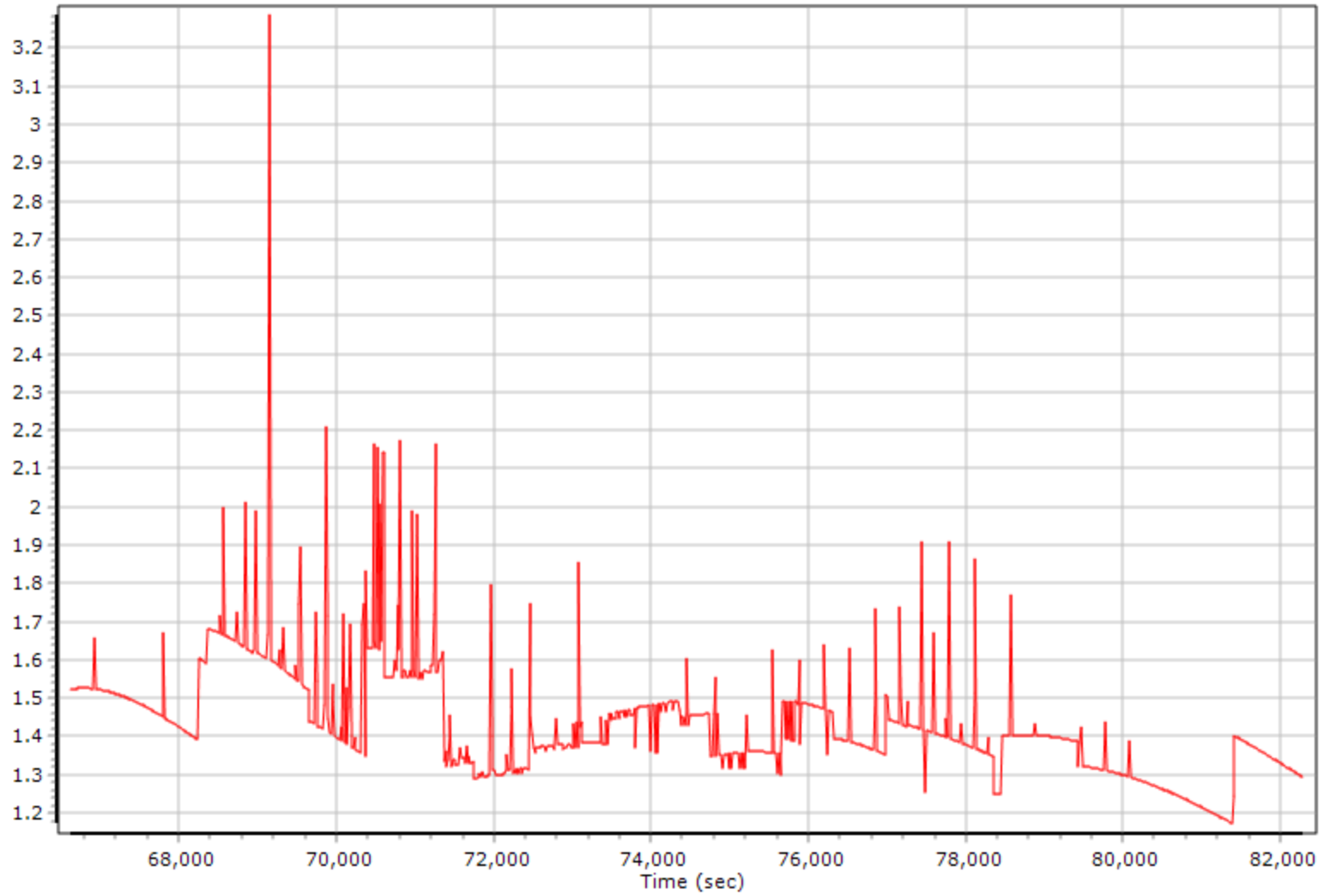
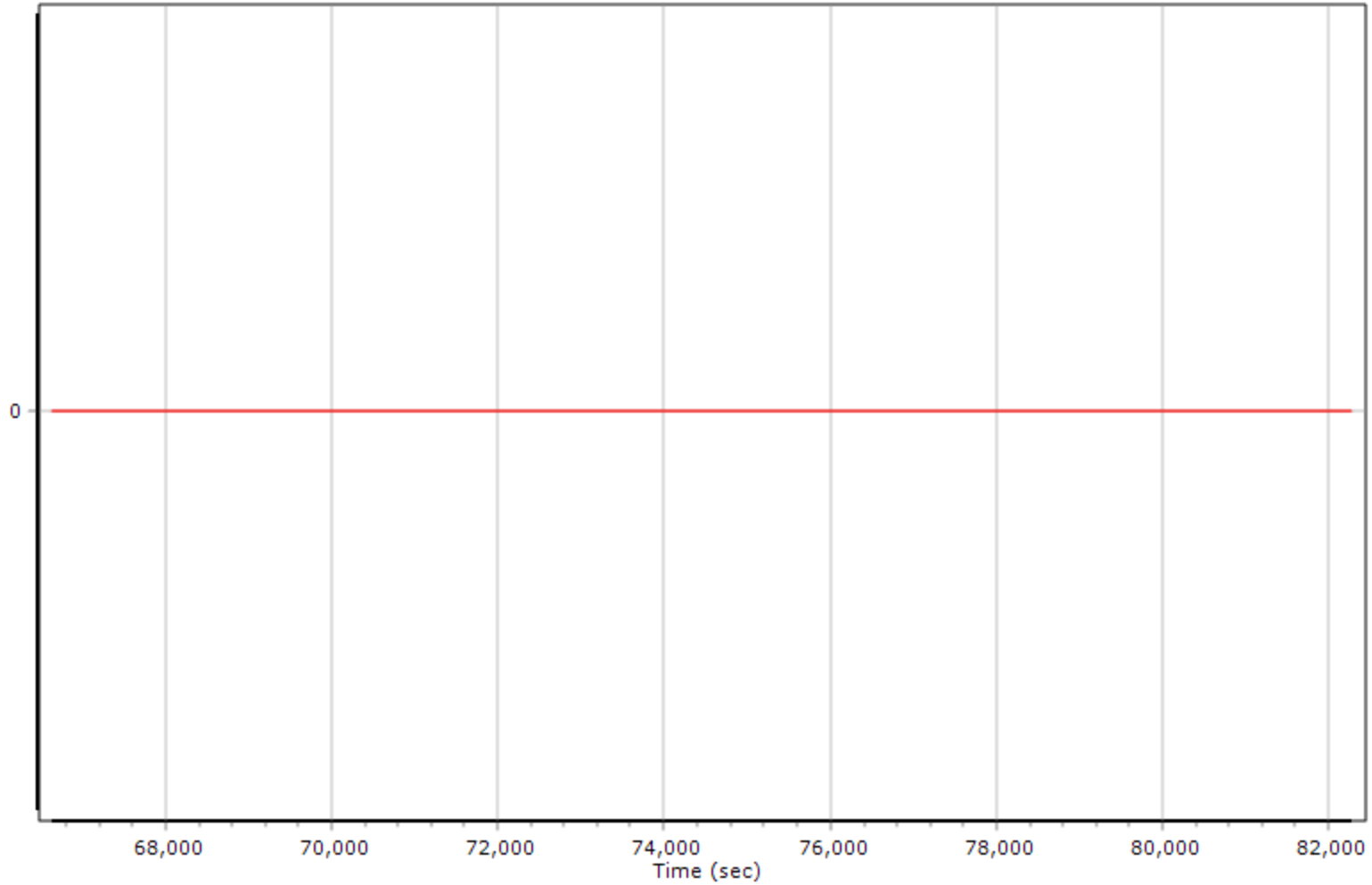


Figure 10. 211003_Potomac_F2 PDOP

Processing Mode



0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = C/A, 7 = GNSS Nav, 8 = DR

Figure 11. 211003_Potomac_F2 Processing Mode

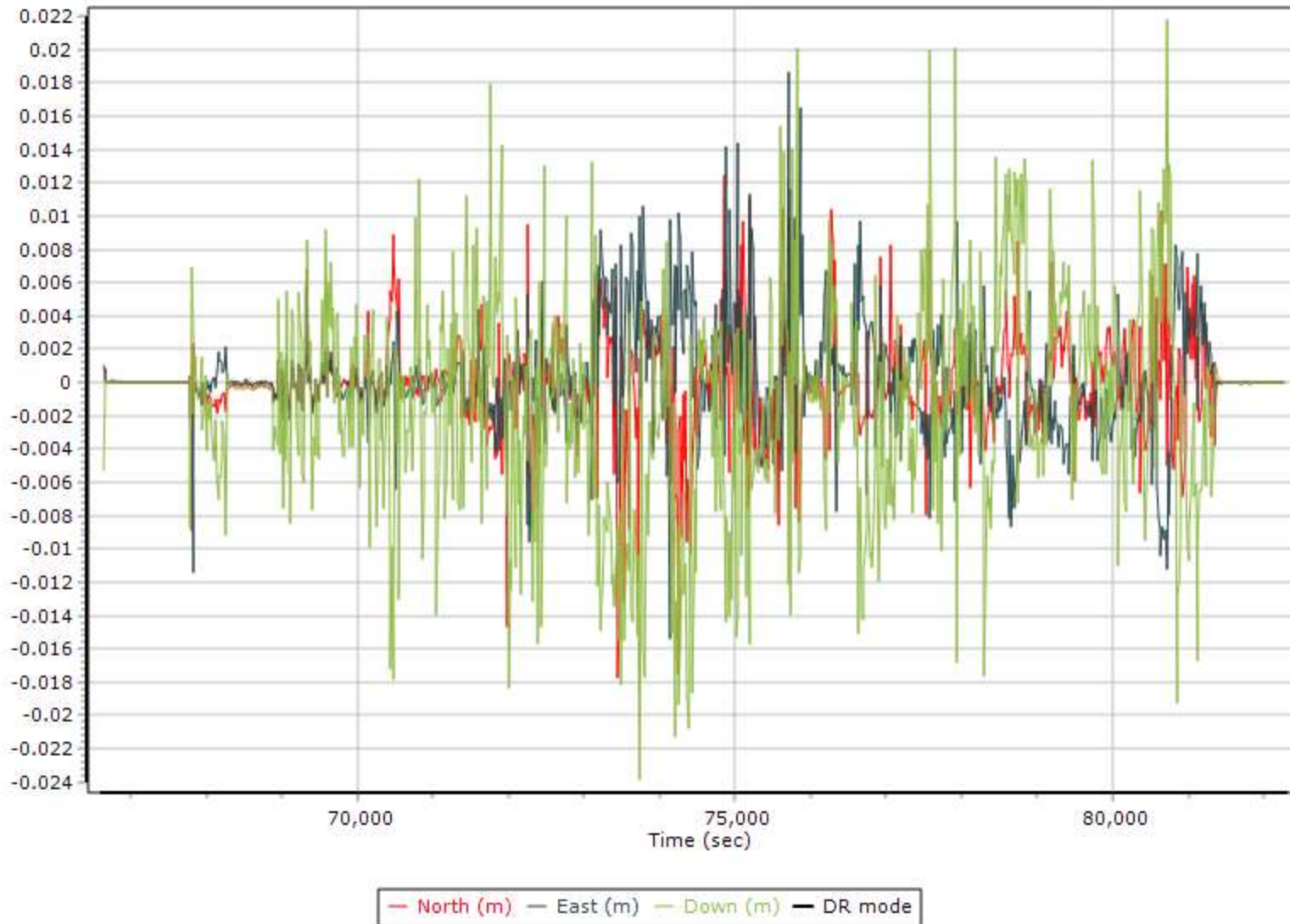


Figure 12. 211003_Potomac_F2 SBET IAKAR Separation

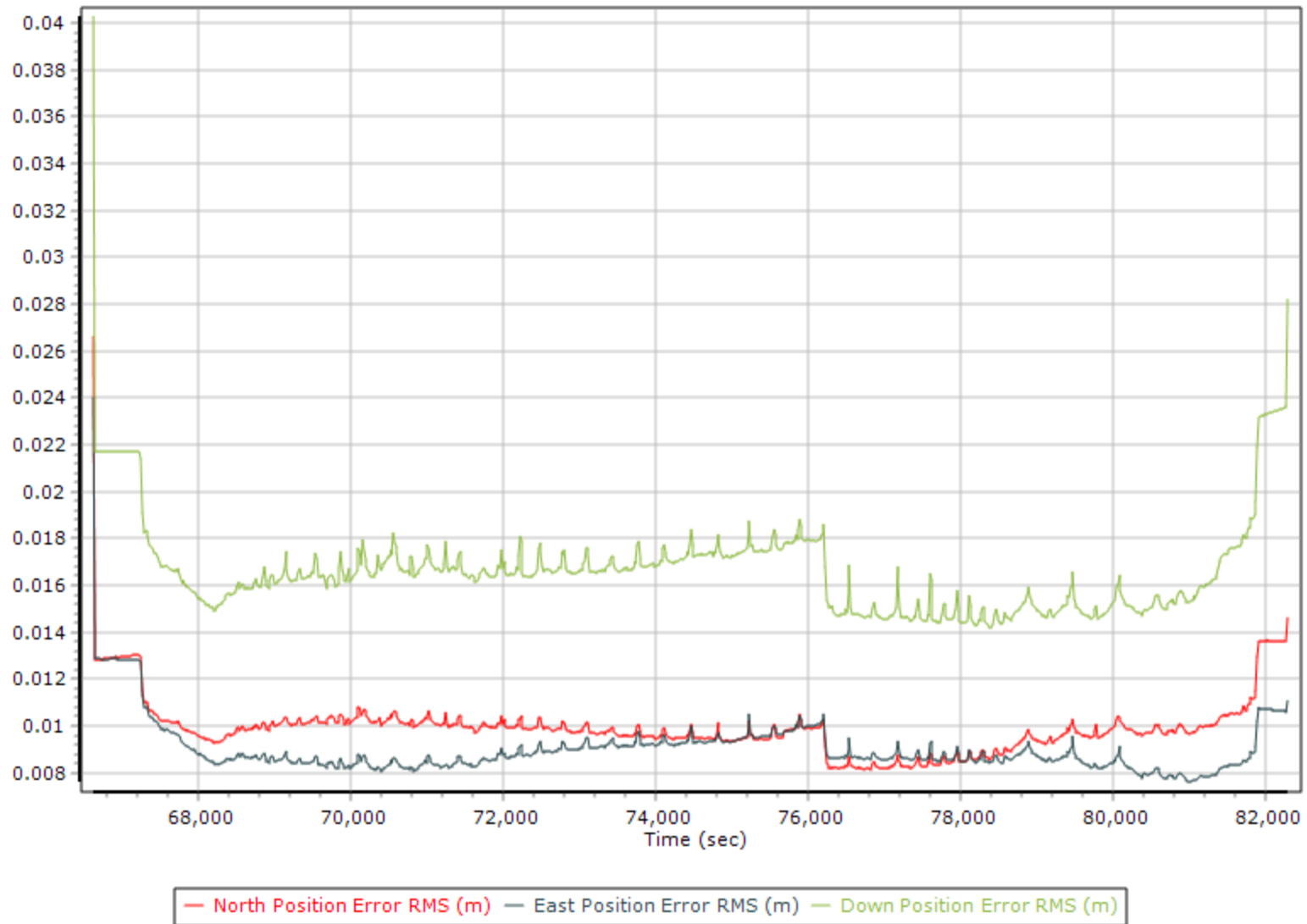


Figure 13. 211003_Potomac_F2 Smoothed Performance Metrics Reference Frame

X Reference-Primary GNSS Lever Arm (m)

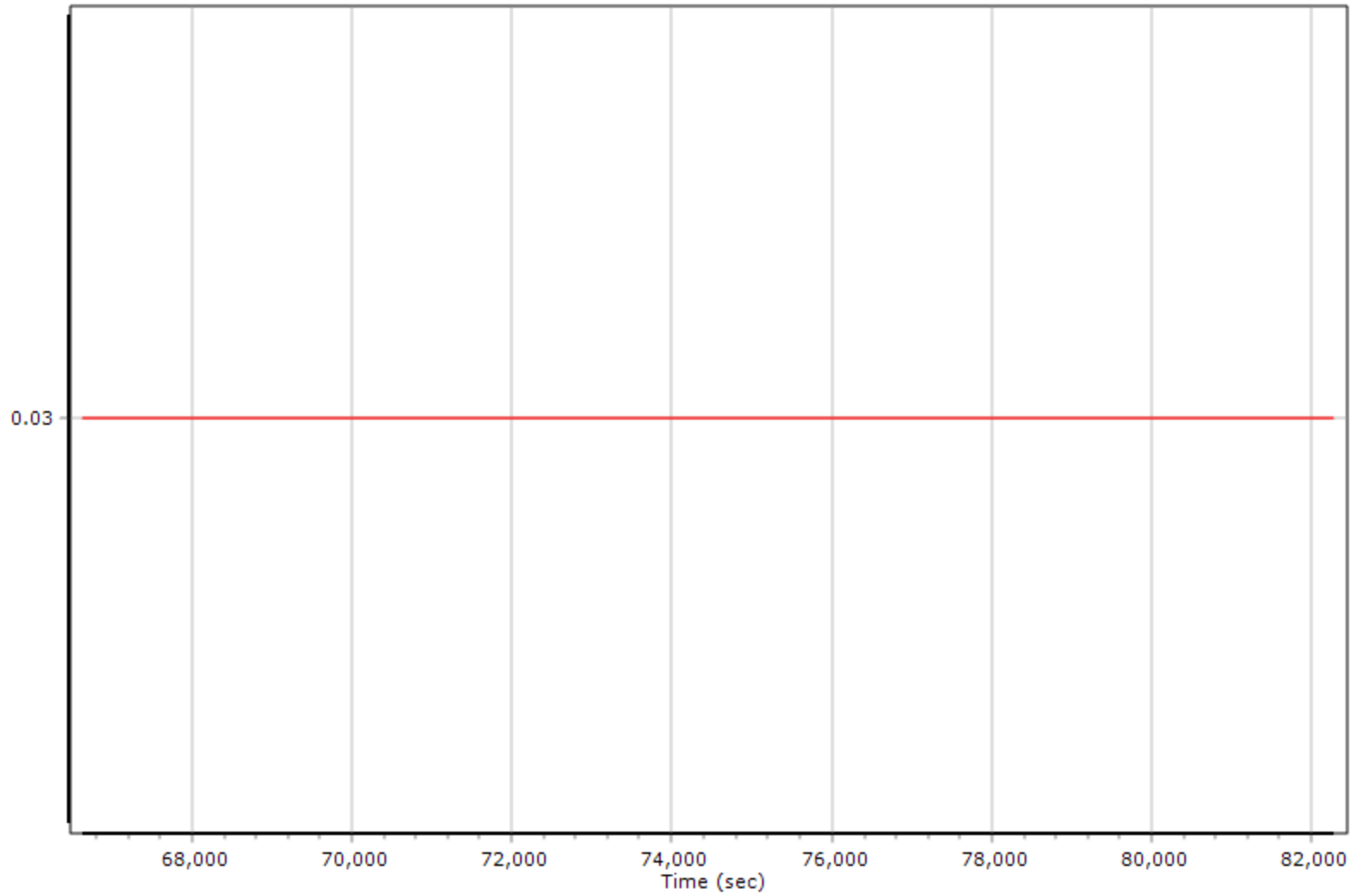


Figure 14. 211003_Potomac_F2 X Reference Primary Lever Arm

Y Reference-Primary GNSS Lever Arm (m)

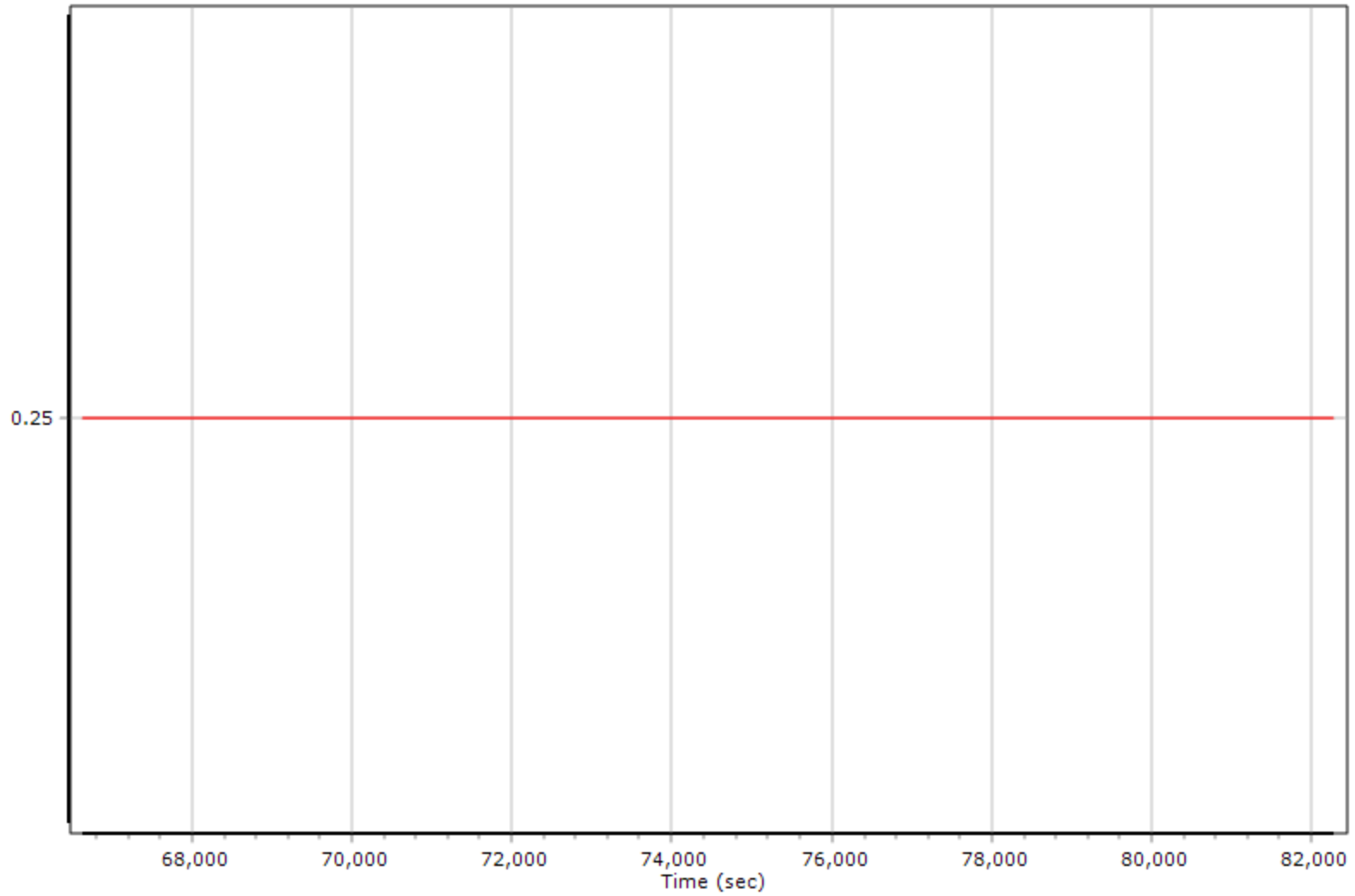


Figure 15. 211003_Potomac_F2 Y Reference Primary Lever Arm

Z Reference-Primary GNSS Lever Arm (m)

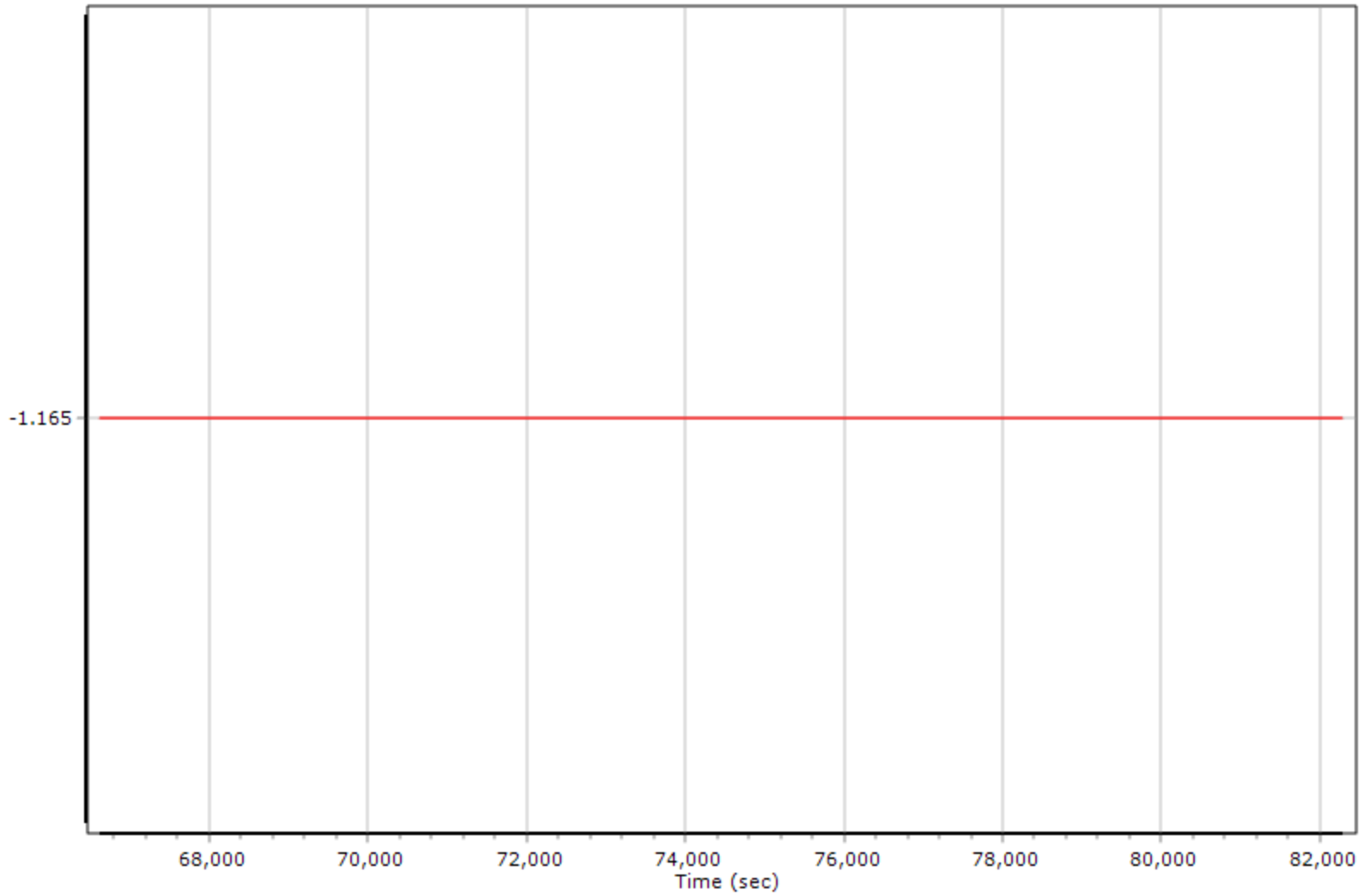


Figure 16. 211003_Potomac_F2 Z Reference Primary Lever Arm

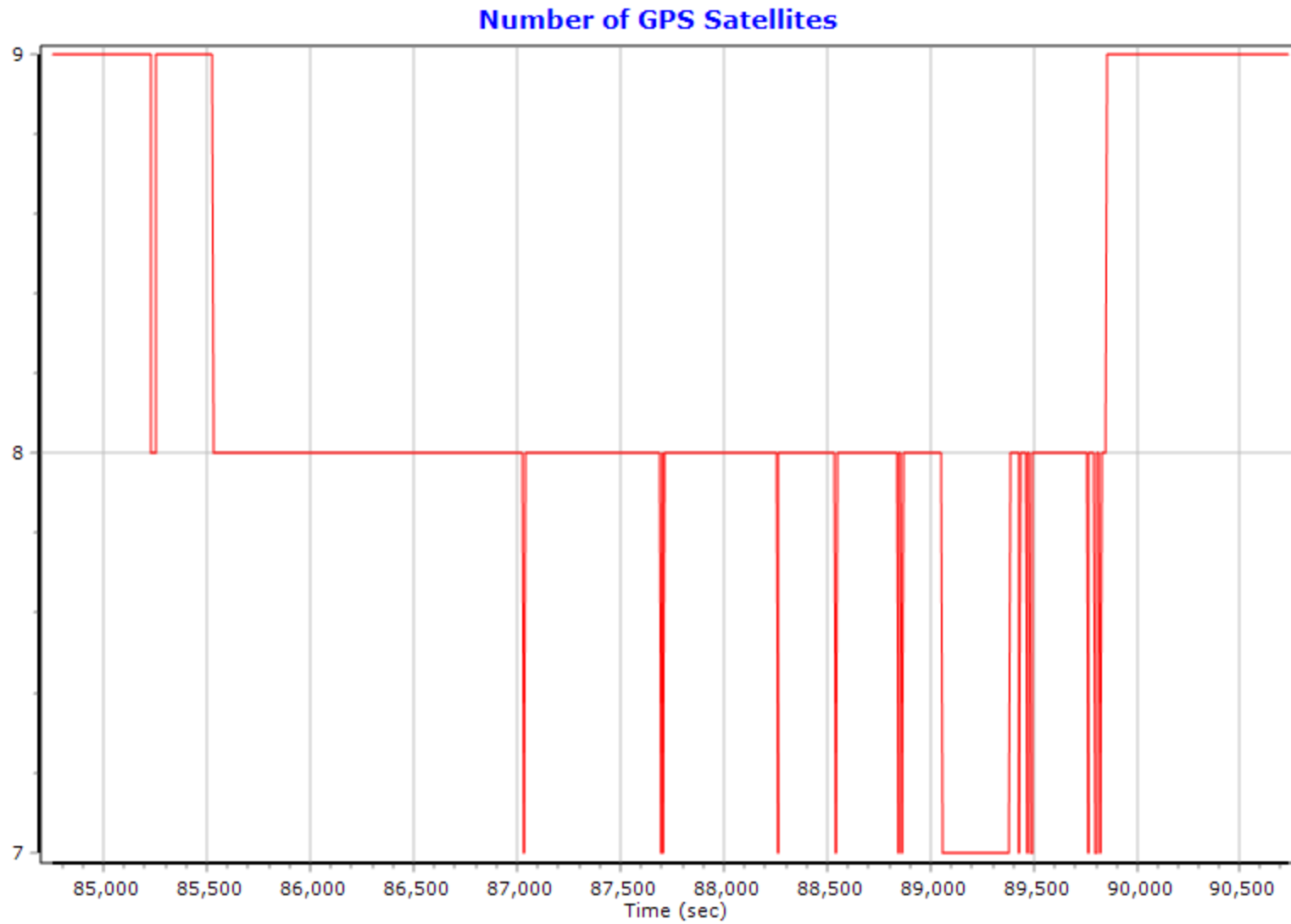


Figure 17. 211003_Potomac_F3 Number GPS Satellites

PDOP

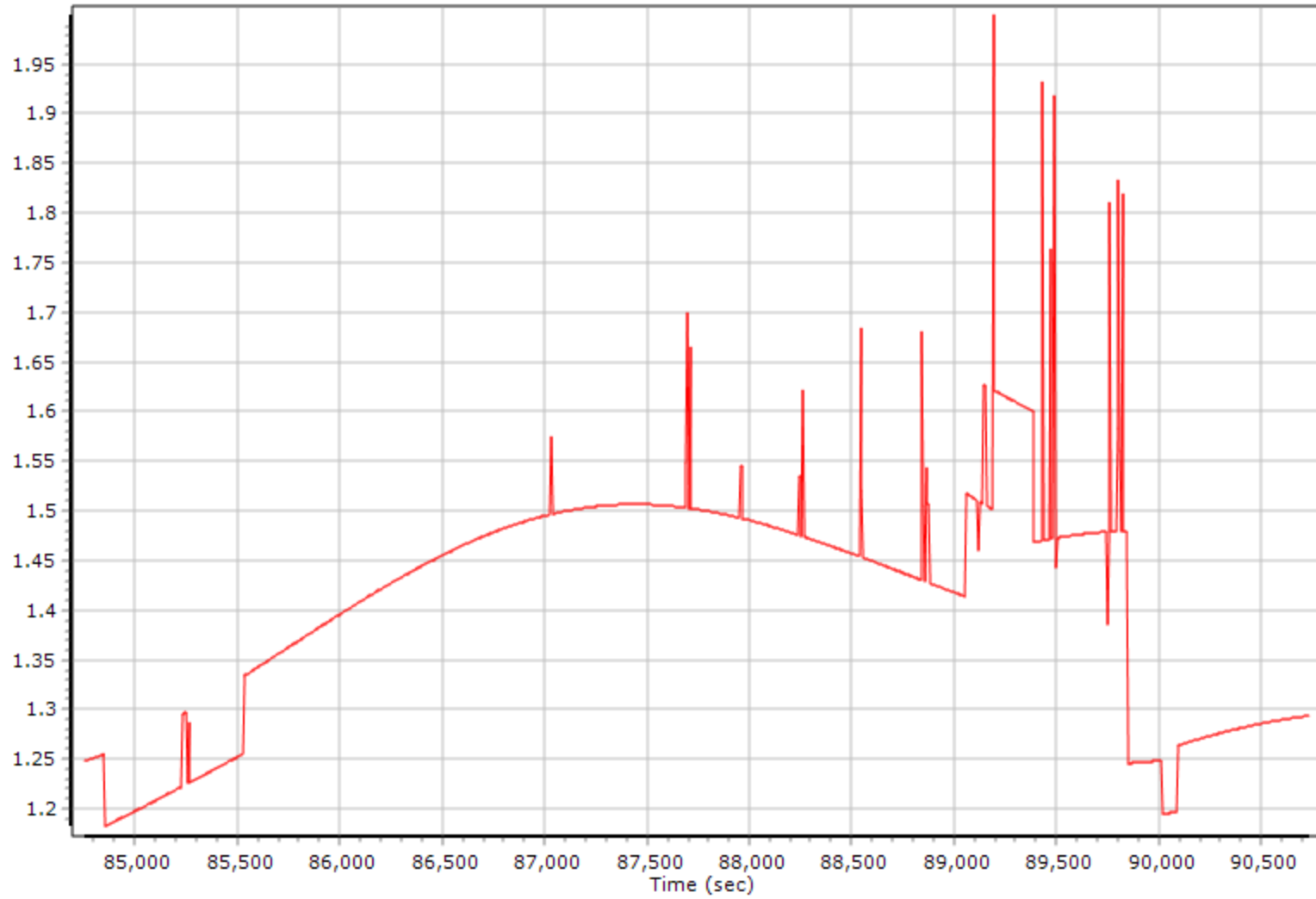
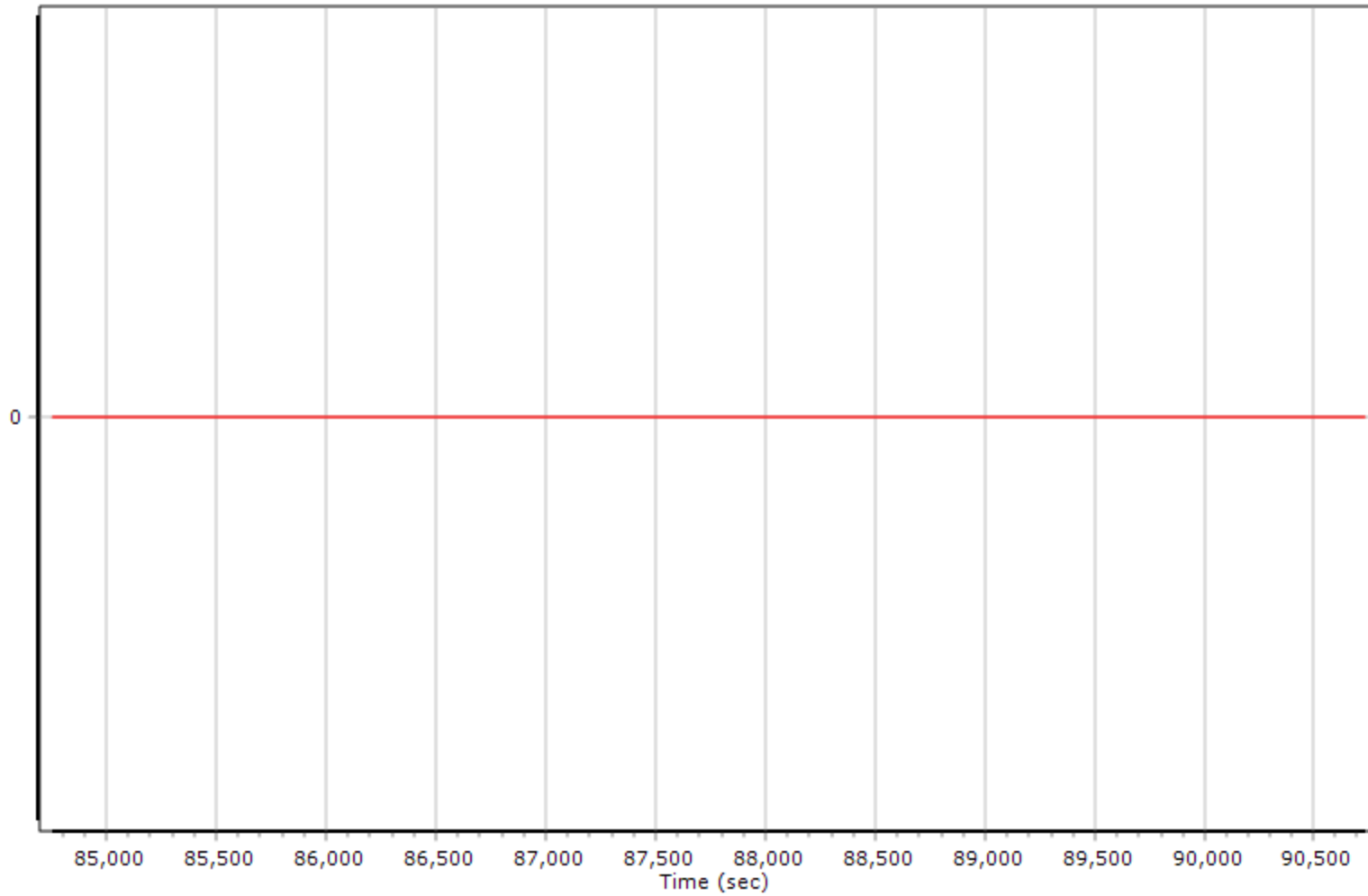


Figure 18. 211003_Potomac_F3 PDOP

Processing Mode



0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = C/A, 7 = GNSS Nav, 8 = DR

Figure 19. 211003_Potomac_F3 Processing Mode

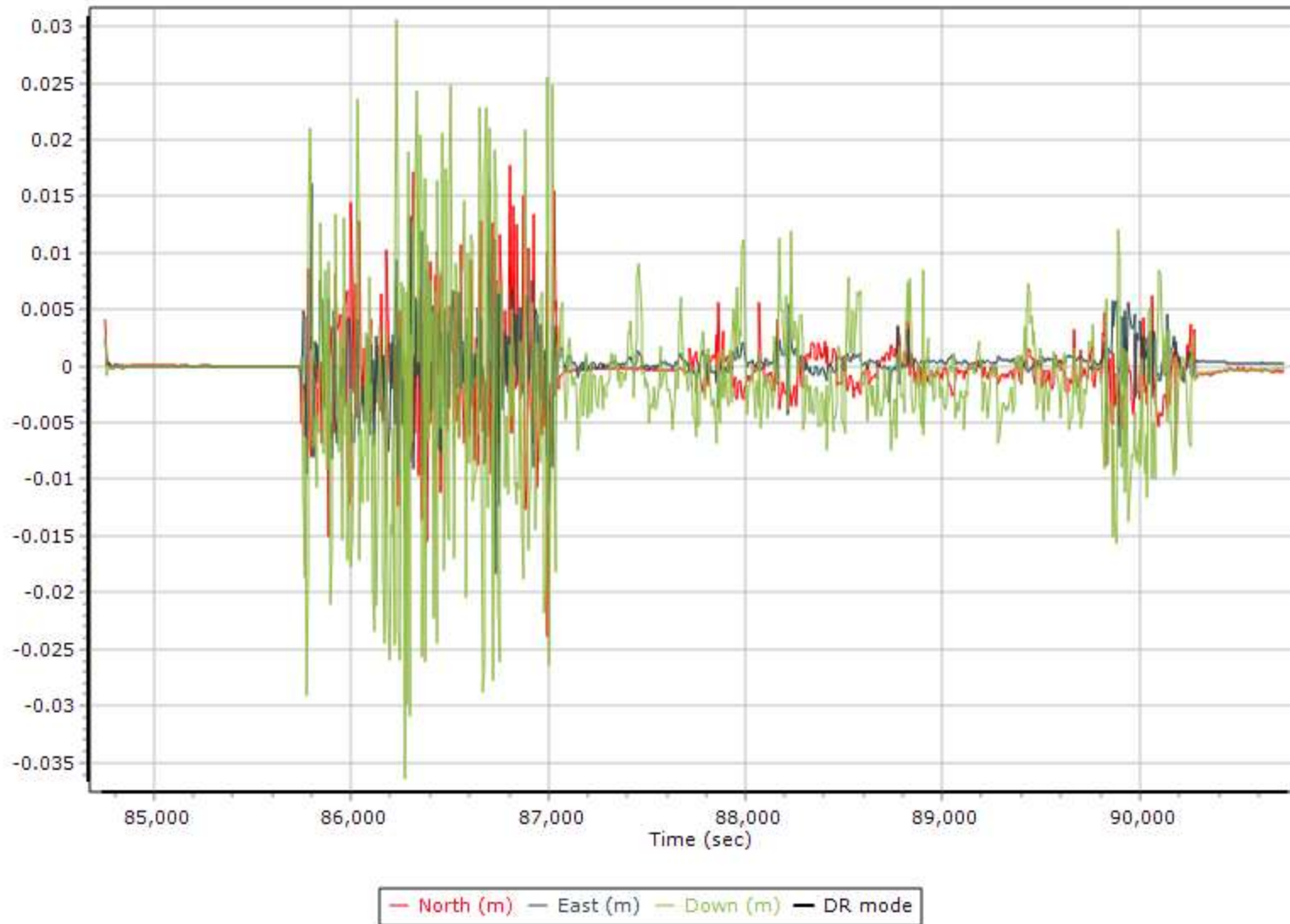


Figure 20. 211003_Potomac_F3 SBET IAKAR Separation

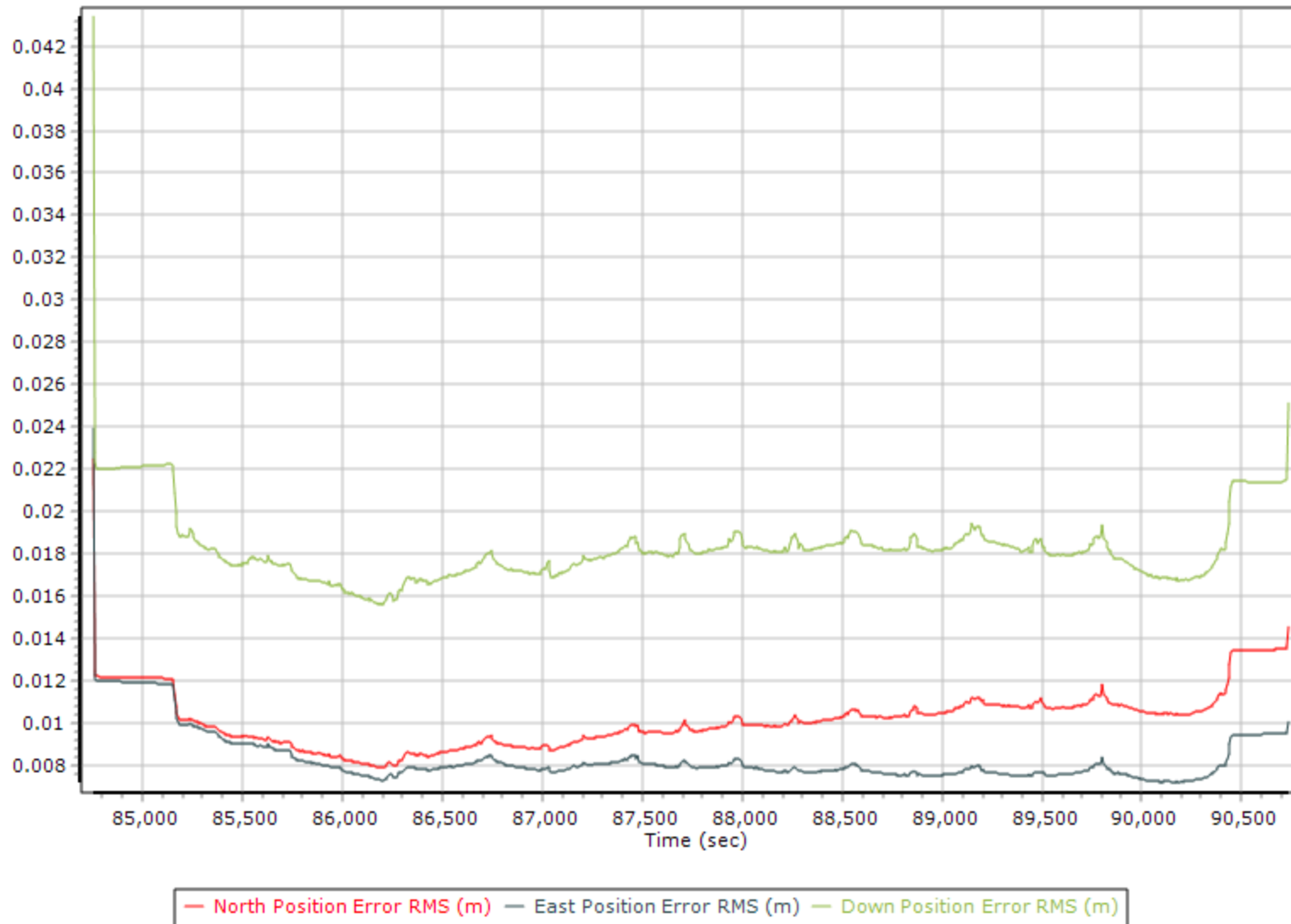


Figure 21. 211003_Potomac_F3 Smoothed Performance Metrics Reference Frame

X Reference-Primary GNSS Lever Arm (m)

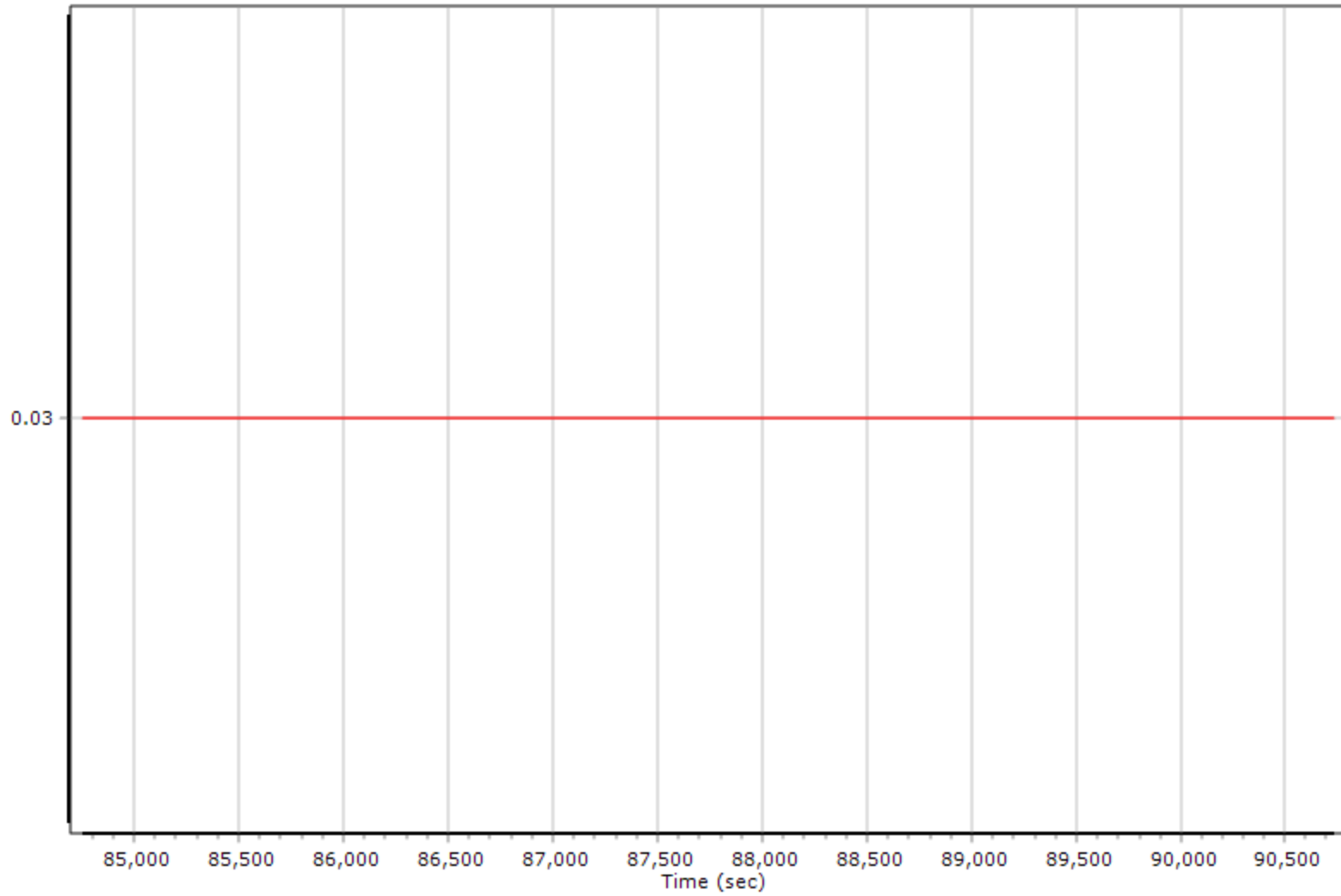


Figure 22. 211003_Potomac_F3 X Reference Primary Lever Arm

Y Reference-Primary GNSS Lever Arm (m)

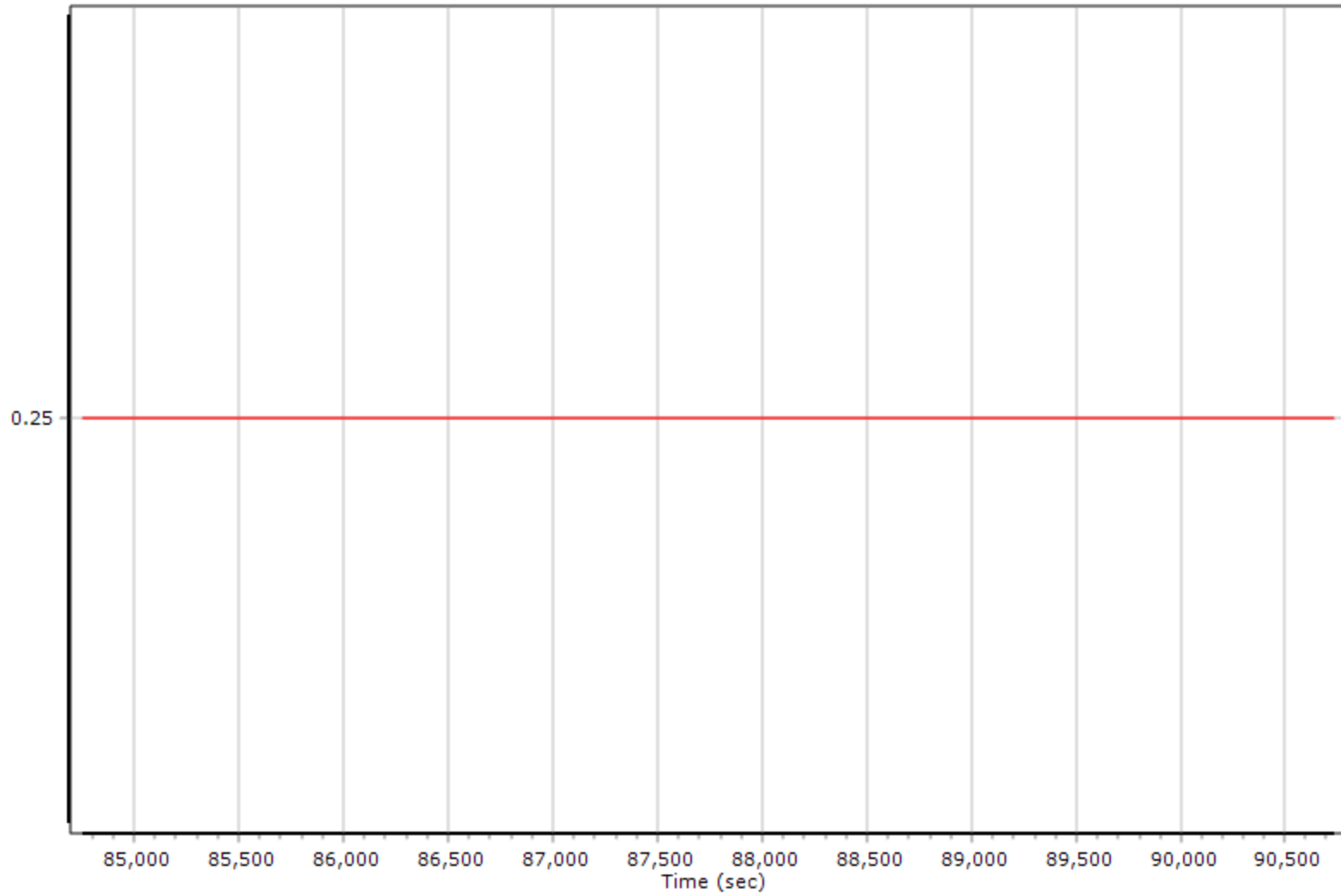


Figure 23. 211003_Potomac_F3 Y Reference Primary Lever Arm

Z Reference-Primary GNSS Lever Arm (m)

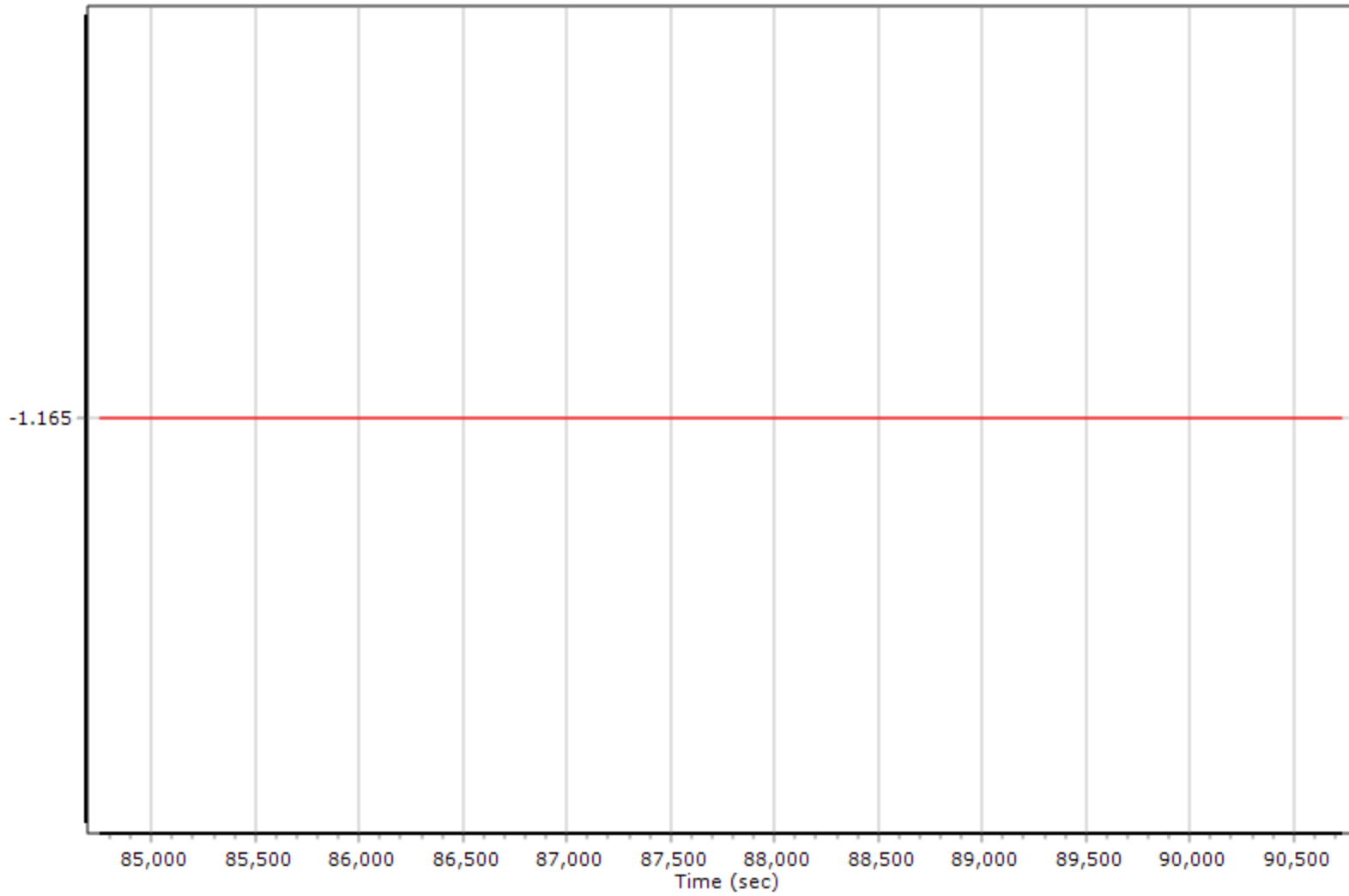


Figure 24. 211003_Potomac_F3 Z Reference Primary Lever Arm

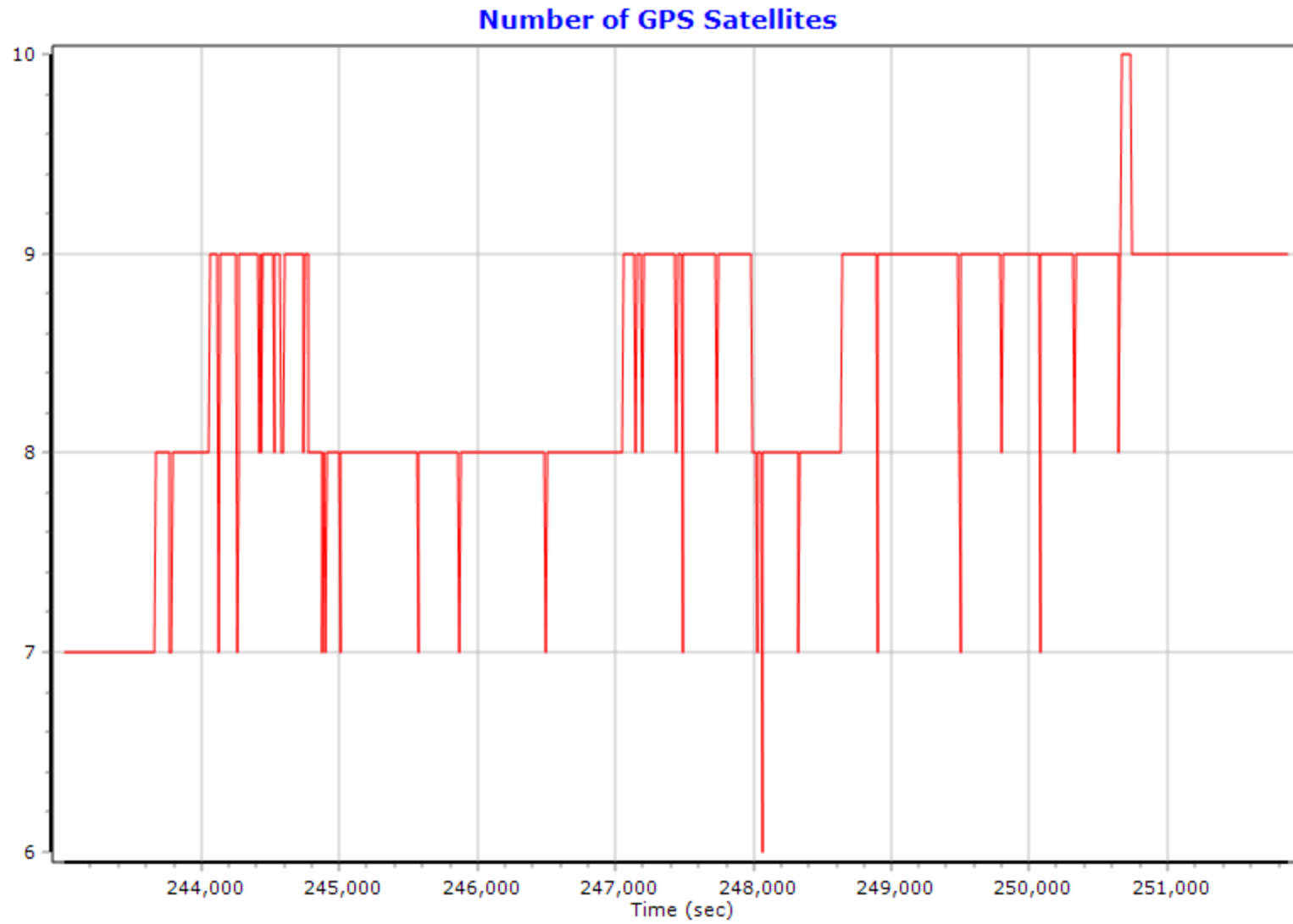


Figure 25. 211005_Potomac_F1 Number GPS Satellites

PDOP

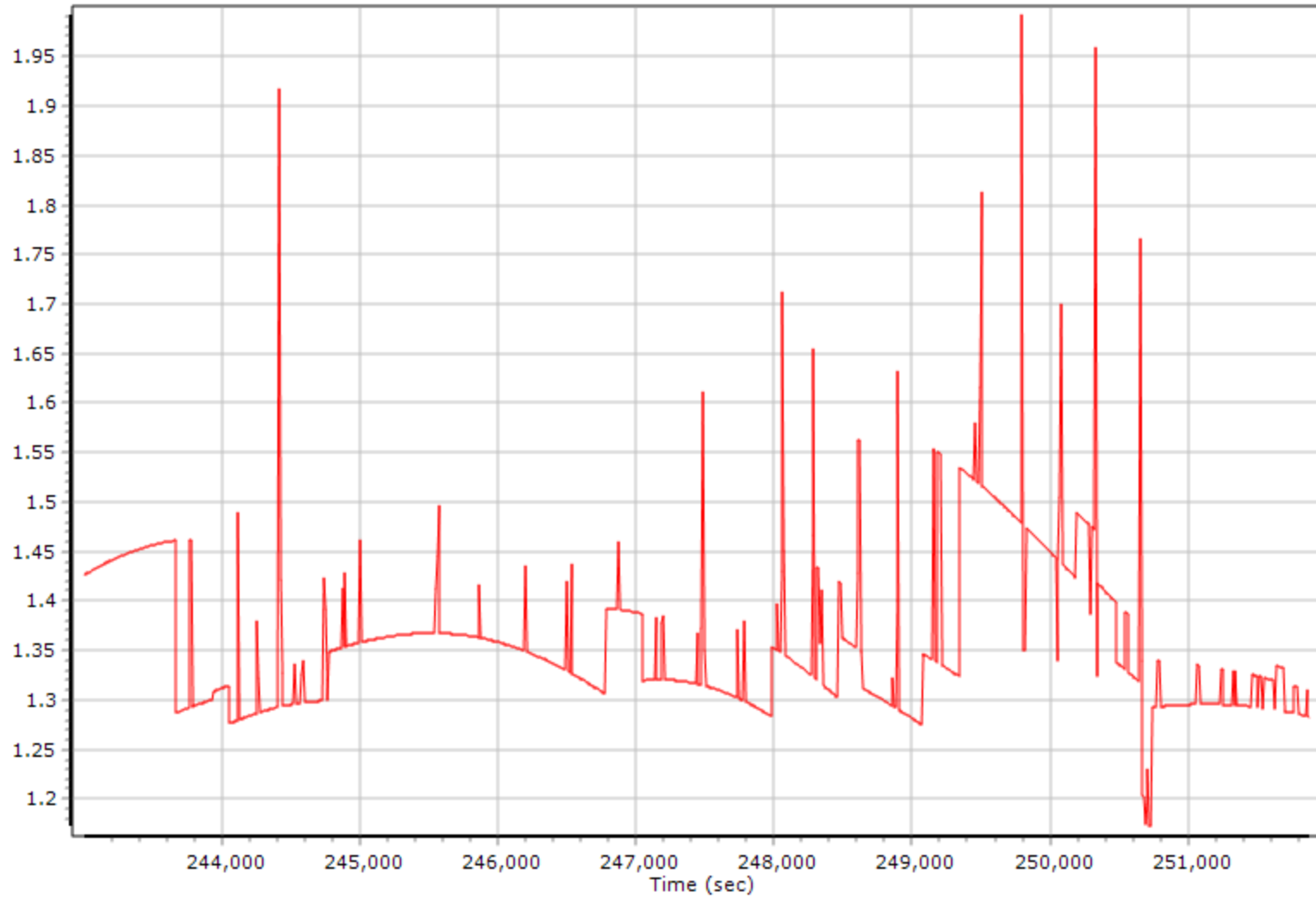
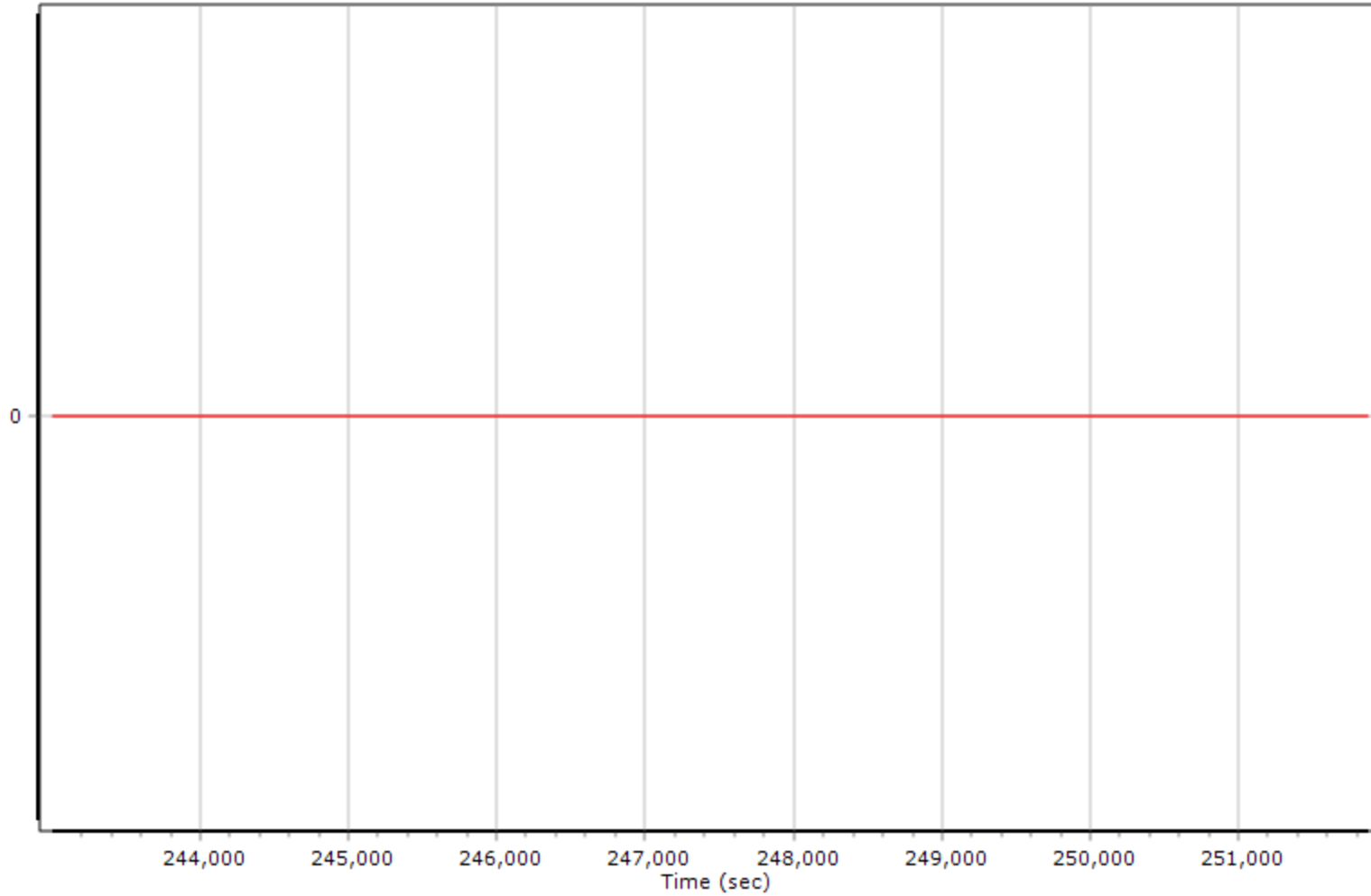


Figure 26. 211005_Potomac_F1 PDOP

Processing Mode



0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = C/A, 7 = GNSS Nav, 8 = DR

Figure 27. 211005_Potomac_F1 Processing Mode



Figure 28. 211005_Potomac_F1 SBET IAKAR Separation

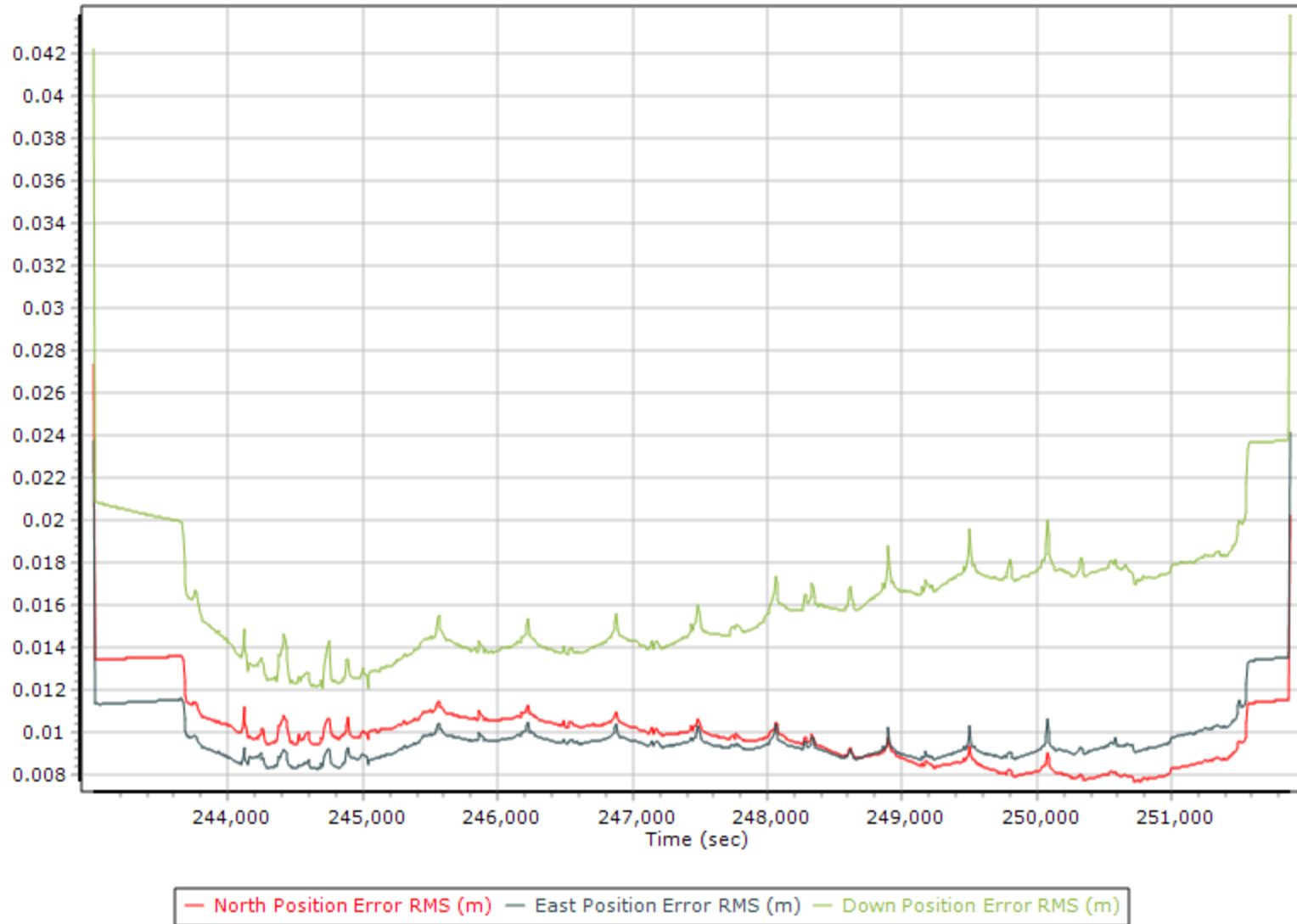


Figure 29. 211005_Potomac_F1 Smoothed Performance Metrics Reference Frame

X Reference-Primary GNSS Lever Arm (m)

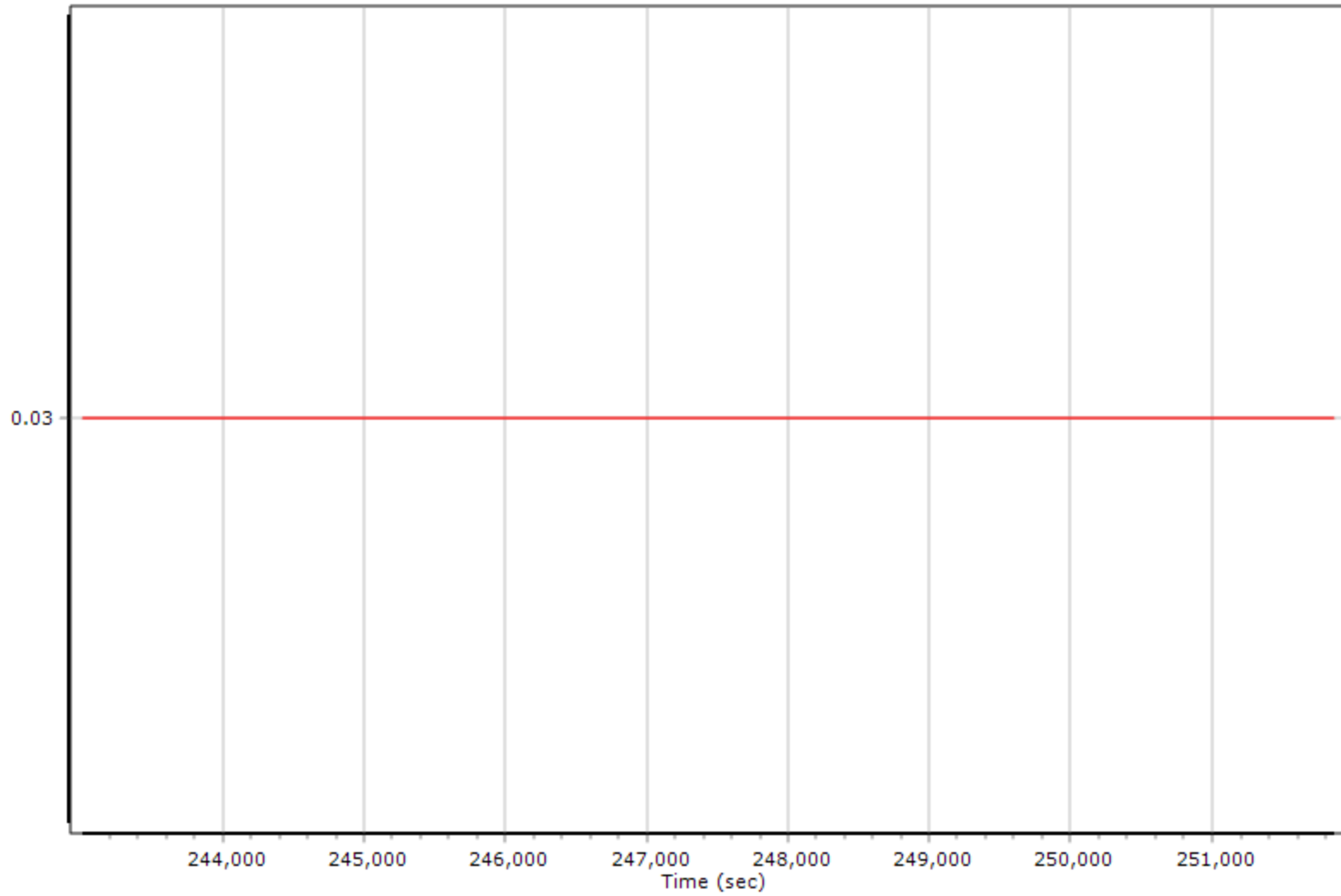


Figure 30. 211005_Potomac_F1 X Reference Primary Lever Arm

Y Reference-Primary GNSS Lever Arm (m)

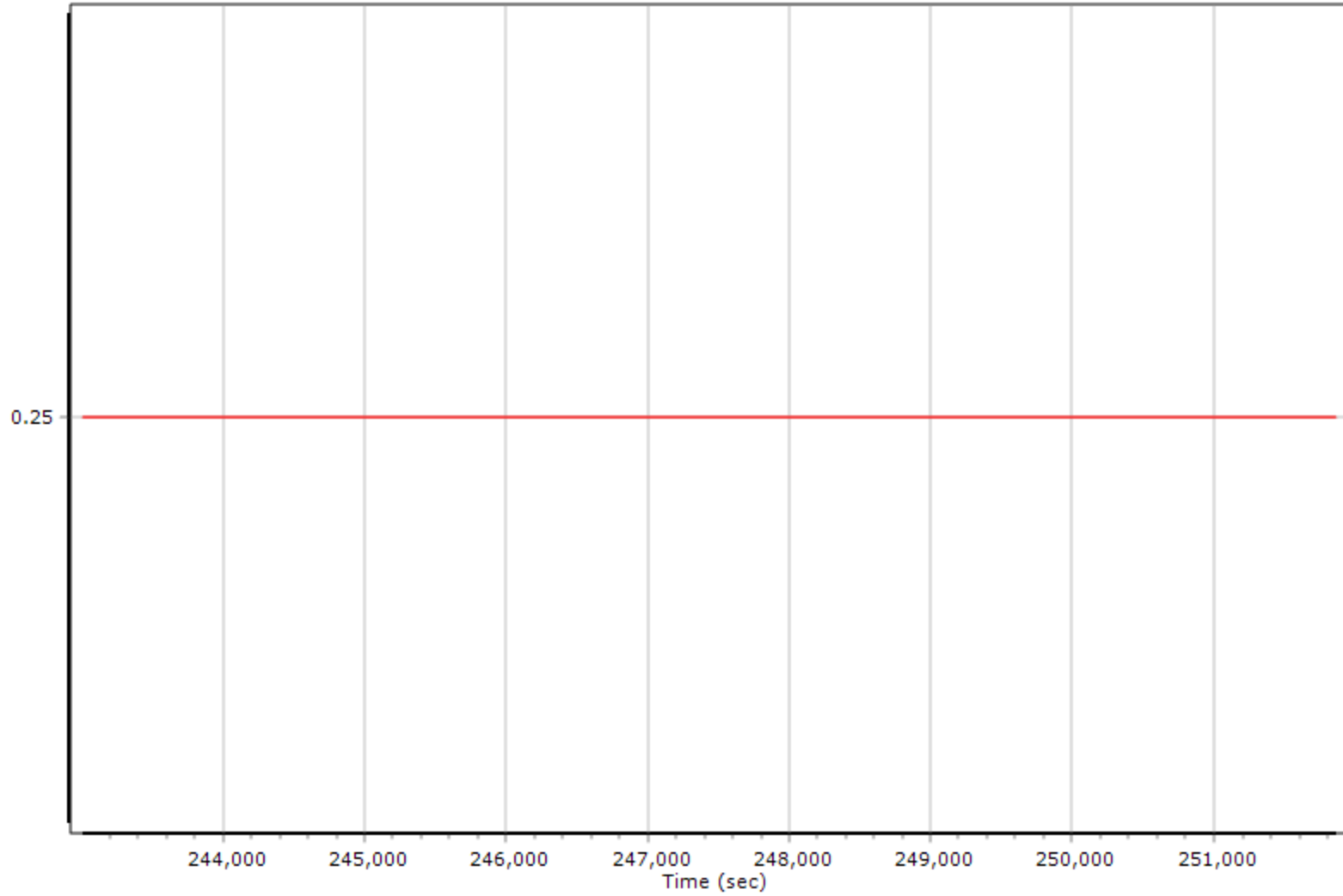


Figure 31. 211005_Potomac_F1 Y Reference Primary Lever Arm

Z Reference-Primary GNSS Lever Arm (m)

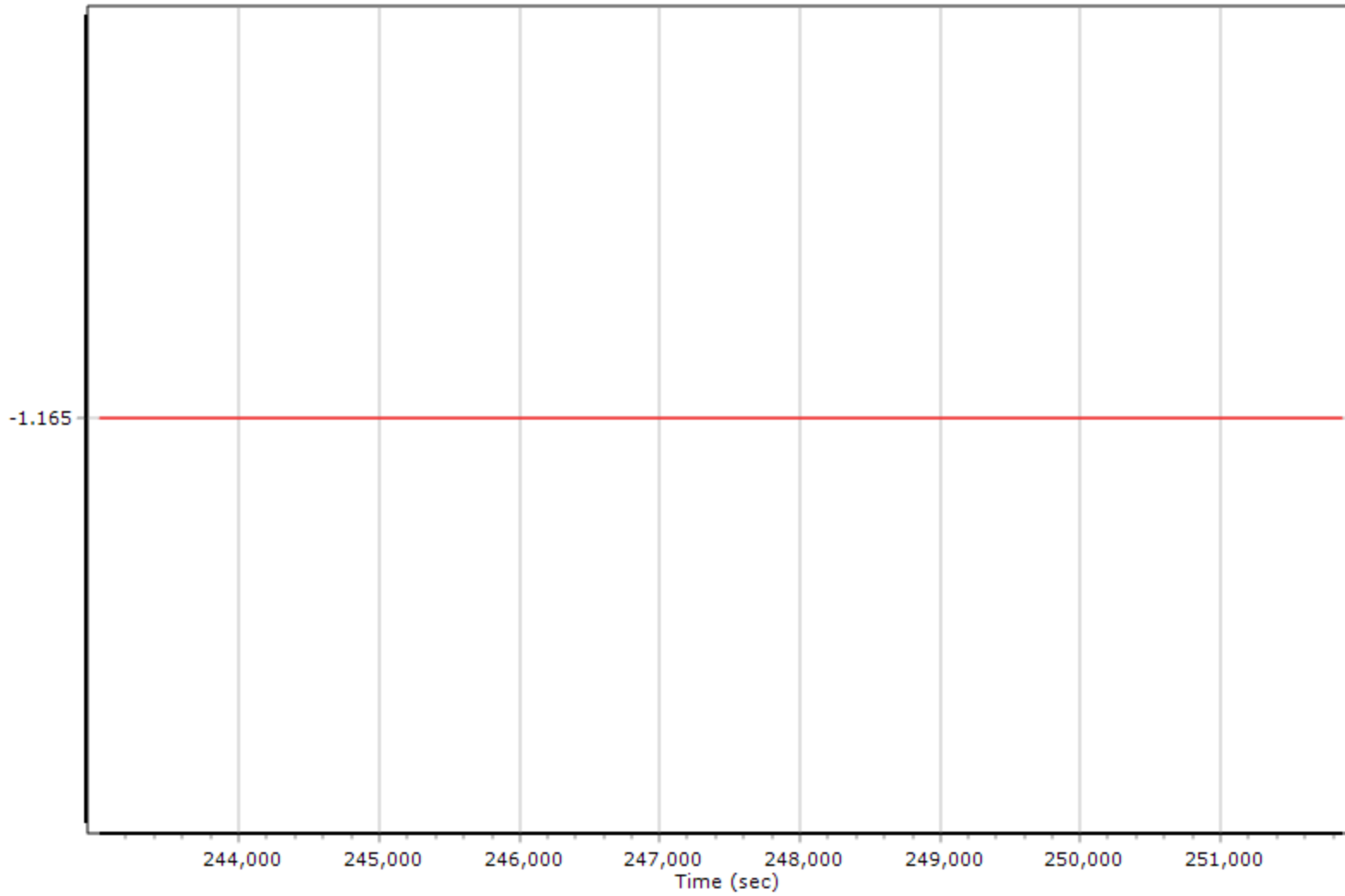


Figure 32. 211005_Potomac_F1 Z Reference Primary Lever Arm