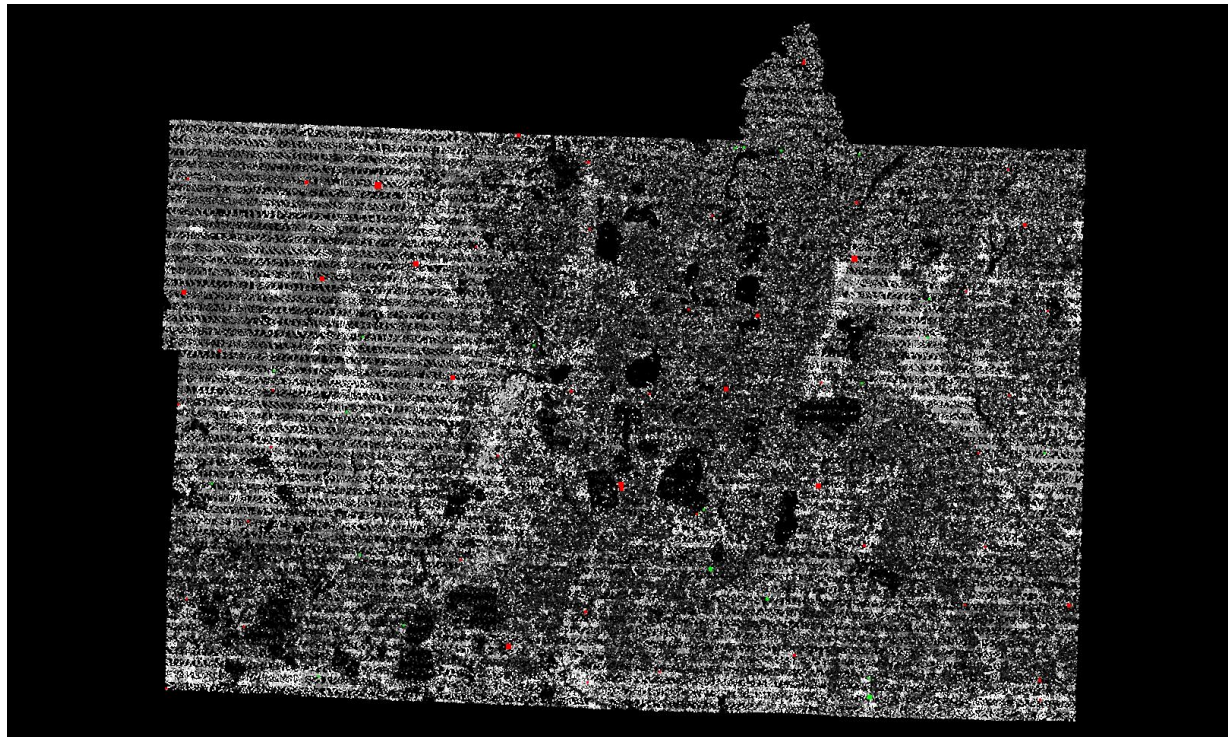


## *DPH-11 Report on Absolute Vertical Accuracy - continued*

The purpose of this section is to show a graphic of lidar data points colored by intensity with NVA check points rendered "thematically" showing the green and red squares sized by Z error.

[Data Source - Y:\Mapping\Projects\65221102\\_MN\\_BeckerCounty\Production\Final\\_Client\\_Deliverables\223407\223404\\_MN\\_BeckerCo\\_1\\_2021\point\\_cloud\tilecls](Y:\Mapping\Projects\65221102_MN_BeckerCounty\Production\Final_Client_Deliverables\223407\223404_MN_BeckerCo_1_2021\point_cloud\tilecls)

[Result Path - Y:\Mapping\Projects\65221102\\_MN\\_BeckerCounty\Admin\QA\\_OC\MN\\_Becker\\_County\\_OC\\_USGS\DPH\\_11\ColorBy\\_Intensity\\_CheckPoints\\_NVA.jpg](Y:\Mapping\Projects\65221102_MN_BeckerCounty\Admin\QA_OC\MN_Becker_County_OC_USGS\DPH_11\ColorBy_Intensity_CheckPoints_NVA.jpg)



■ Green represents where the lidar surface is above the check point (positive elevation error).

■ Red represents where the lidar surface is below the check point (negative elevation error).

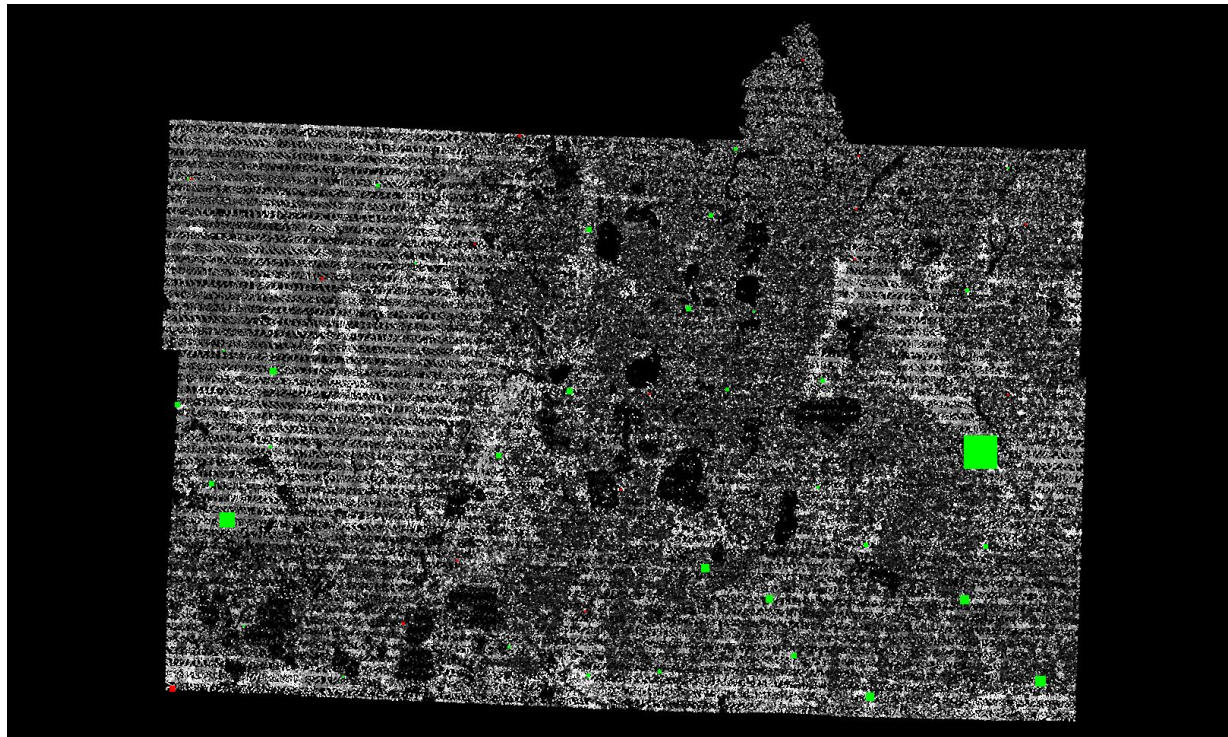
The size of the square symbol represents the absolute value magnitude of error.

## *DPH-11 Report on Absolute Vertical Accuracy - continued*

The purpose of this section is to show a graphic of lidar data points colored by intensity with VVA check points rendered "thematically" showing the green and red squares sized by Z error.

[Data Source - Y:\Mapping\Projects\65221102\\_MN\\_BeckerCounty\Production\Final\\_Client\\_Deliverables\223407\223404\\_MN\\_BeckerCo\\_1\\_2021\point\\_cloud\tilecls](Y:\Mapping\Projects\65221102_MN_BeckerCounty\Production\Final_Client_Deliverables\223407\223404_MN_BeckerCo_1_2021\point_cloud\tilecls)

[Result Path - Y:\Mapping\Projects\65221102\\_MN\\_BeckerCounty\Admin\QA\\_OC\MN\\_Becker\\_County\\_OC\\_USGS\DPH\\_11\ColorBy\\_Intensity\\_CheckPoints\\_VVA.jpg](Y:\Mapping\Projects\65221102_MN_BeckerCounty\Admin\QA_OC\MN_Becker_County_OC_USGS\DPH_11\ColorBy_Intensity_CheckPoints_VVA.jpg)



■ Green represents where a DEM of the lidar surface is above the check point (positive elevation error).

■ Red represents where a DEM of the lidar surface is below the check point (negative elevation error).

The size of the square symbol represents the absolute value magnitude of error.