

General Information

Mission Information

Project name	220524_A_5060386_nad2011_FINAL
Processing date	2022-06-01 19:05:30
Mission date	2022-05-24 12:19:34
Mission duration	04:24:23.000
Processing mode	IN-Fusion PP-RTX

Rover Hardware Information

Product	POS AV 610 VER6 HW2.5-12
Serial number	S/N8083
IMU type	57
Receiver type	BD982
Antenna type	AV39

Project File List

Rover Data Files

File name	File type
survey23.pos	POS Data

Input Files

File Name	File Type
Ephm1440.22g	GLONASS Broadcast Ephemeris
Ephm1440.22n	GPS Broadcast Ephemeris

Output Files

Filename	File type
sbet_220524_A_5060386_nad2011_FINAL.out	SBET Trajectory File

Rover Data Summary

First raw data file	survey23.pos		
Last raw data file	survey23.pos		
Start GPS week	2211		
Start time	217173.170 (05/24/2022 12:19:33)		
End time	233038.816 (05/24/2022 16:43:58)		
Start of fine alignment	217629.147 (05/24/2022 12:27:09)		
Available subsystems	Primary GNSS, IMU		
POS Event Input	None		
Correction data	None		
IMU Installation Lever Arms & Mounting Angles			
Reference to IMU lever arm (m)	0.000	0.000	0.000
Reference to IMU mounting angles (deg)	0.000	0.000	180.000
Reference to Primary GNSS lever arm (m)	0.140	-0.150	-1.115
Reference to Primary GNSS lever arm std dev (m)	-1.000		
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

Rover Data QC

Raw IMU Import QC Summary

IMU data input file	imu_Mission 1.dat
IMU data check log file	imudt_220524_A_5060386_nad2011_FINAL.log
IMU Records Processed	3172410
Termination Status	Normal
IMU Anomalies	0

GNSS QC

GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	6	10	9
Number of GLONASS SV	0	7	5
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	2	1
Number of GALILEO SV	0	7	5
Total number of SV	12	24	20
PDOP	1.04	1.71	1.20
QC Solution Gaps	1.00	1.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	15810.00	0.00	1.00
Percentage	99.99	0.00	0.01

GNSS-Inertial Processor Configuration

Processing mode	IN-Fusion PP-RTX		
Stabilized mount	False		
Processing start time	217174.000 (05/24/2022 12:19:34)		
Processing end time	233037.000 (05/24/2022 16:43:57)		
Initial attitude source	Real-Time VNAV/RNAV Attitude		
IMU Sensor Context	Processing with Onboard IMU		
Reference to IMU lever arm (m)	0.000	0.000	0.000
Reference to IMU mounting angles (deg)	0.000	0.000	180.000
Reference to Primary GNSS lever arm (m)	0.084	-0.189	-0.941
Reference to Primary GNSS lever arm std dev (m)	0.030	0.030	0.030
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000