

# Airborne Lidar Report



## Mississippi NRCS FY16 Lidar

Contract Number: G16PC0022

Task Number: G16PD00331

Contractor: Woolpert, Inc.  
Woolpert Project # 76268

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# Table of Contents

Section 1: Overview .....	1-1
Section 2: Acquisition.....	2-1
Section 3: Lidar Data Processing .....	3-1
Section 4: Hydrologic Flattening .....	4-1
Section 5: Accuracy Assessment .....	5-1
Section 6: Flight Logs.....	6-1
Section 7: Final Deliverables .....	7-1

## List of Figures

Figure 1.1: Mississippi NRCS FY16 Lidar Task Order AOI.....	1-2
Figure 2.1: Lidar Flight Layout, Mississippi NRCS FY16 Lidar.....	2-3
Figure 3.1: Trajectory, Day03616_PAR_A .....	3-3
Figure 3.2: Combined Separation, Day00817_SH8170 .....	3-4
Figure 3.3: Estimated Positional Accuracy, Day00817_SH8170.....	3-5
Figure 3.4: PDOP, Day00817_SH8170.....	3-6
Figure 4.1: Example Hydrologic Breaklines .....	4-1
Figure 4.2: DEM Generated from Lidar Bare Earth Point Data .....	4-2
Figure 4.3: DEM Generated from Lidar with Breaklines .....	4-2
Figure 5.1: Lidar Relative Accuracy Histogram.....	5-11

## List of Tables

Table 1.1: ALS80 Specifications – WOOLPERT and QSI .....	1-1
Table 1.2: ALS70 Specifications - QSI .....	1-1
Table 2.1: ALS80 HP Lidar System Specifications .....	2-1
Table 2.2: ALS70 Lidar System Specifications .....	2-2
Table 2.3: Airborne Lidar Acquisition Flight Summary.....	2-4
Table 3.1: GNSS Base Station .....	3-1
Table 5.1: Overall Vertical Accuracy Statistics .....	5-1
Table 5.2: RAW Swath Quality Check Point Analysis NVA.....	5-1
Table 5.3: NVA Check Point Analysis DEM .....	5-4
Table 5.4: VVA Quality Check Point Analysis DEM .....	5-7

# Section 1: Overview

TASK ORDER NAME: Mississippi NRCS FY16 Lidar

Project: # 76268

This report contains a comprehensive outline of the Mississippi NRCS FY16 Lidar. Processing task order for the United States Geological Survey (USGS). This task is issued under USGS Contract No. G16PC0022, Task Order No. G16PD00331. This task order requires lidar data to be acquired over 4,780 square miles of V.1.2 lidar, for the area of interest (AOI) collected at a nominal pulse spacing (NPS) of 0.7 meters. The NPS assessment is made against single swath, first return data located within the geometrically usable center portion (typically ~90%) of each swath.

The data was collected using:

- Two Leica ALS80 HP 1000 kHz Multiple Pulses in Air (MPiA) lidar systems on board WoolpertQSI aircraft. The ALS80 sensor collects up to four returns per pulse, as well as intensity data, for the first three returns. If a fourth return was captured, the system does not record an associated intensity value. The aerial lidar was collected at the following sensor specifications:

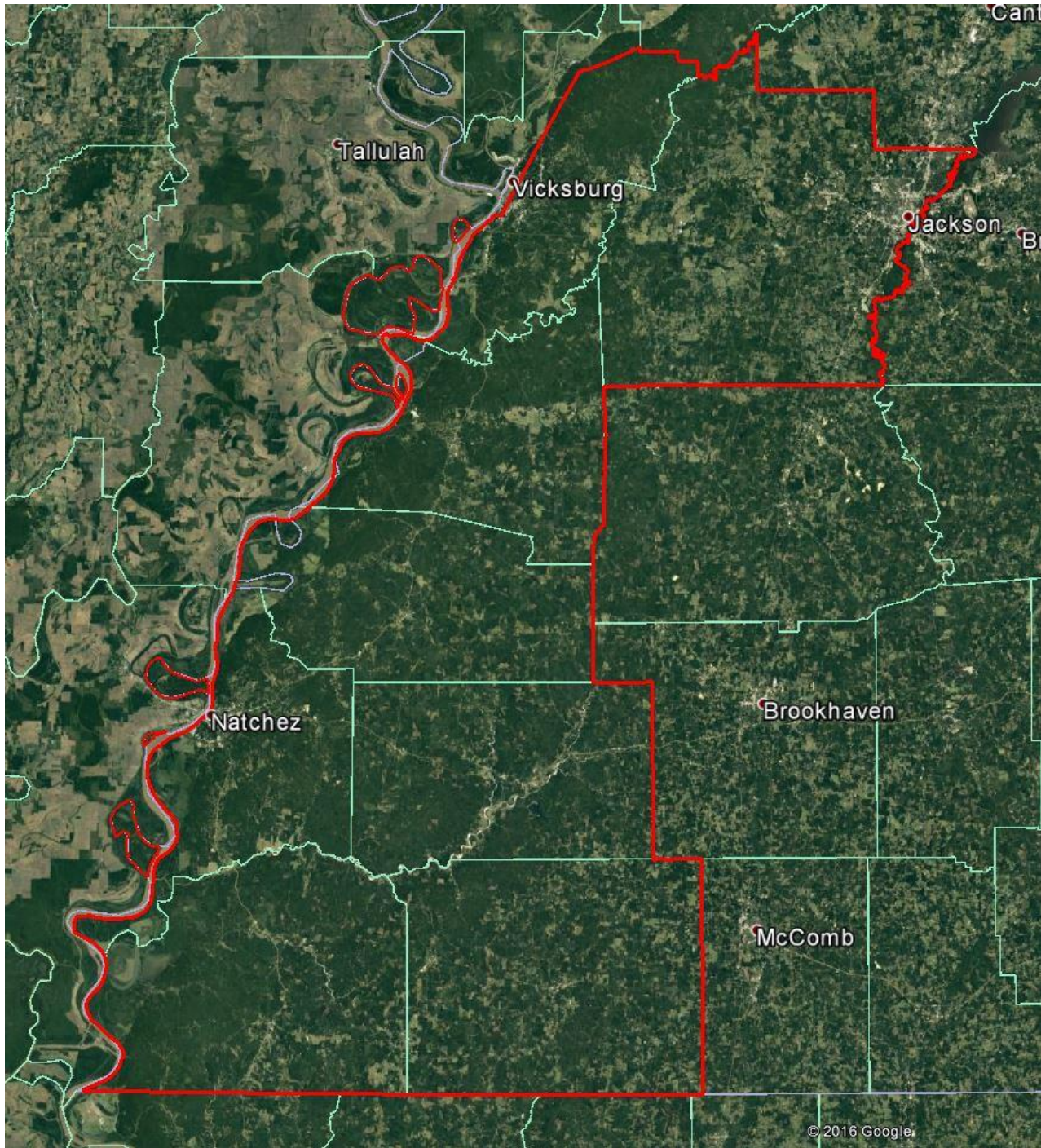
Post Spacing	0.70 m
AGL (Above Ground Level) average flying height	1,981 m
Average Ground Speed:	150 knots
Field of View (full)	40 degrees
Pulse Rate	272 kHz
Scan Rate	50 Hz
Side Lap	25%

- One Leica ALS70 500 kHz Multiple Pulses in Air (MPiA) lidar sensors owned and operated by Quantum Spatial. The sensor was mounted in Quantum Spatial aircraft. The aerial lidar was collected at the following sensor specifications:

Post Spacing	0.7 m
AGL (Above Ground Level) average flying height	1,900m
Average Ground Speed:	170 knots
Field of View (full)	40 degrees
Pulse Rate	273 kHz
Scan Rate	53 Hz
Side Lap	25%

The horizontal datum used for the task order was referenced to NAD83 (2011), Zone 15, Meters. The vertical datum used for the task order was referenced to NAVD 1988, Meters, GEOID12B.

Figure 1.1: Mississippi NRCS FY16 Lidar Task Order AOI



## Section 2: Acquisition

The lidar data was acquired with three Leica ALS80HP 1000 kHz Multiple Pulses in Air (MPiA) Lidar Sensor Systems. The ALS80 HP lidar system, developed by Leica Geosystems of Heerbrugg, Switzerland, includes the simultaneous first, intermediate and last pulse data capture module, the extended altitude range module, and the target signal intensity capture module.

The ALS80HP 1000 kHz Multiple Pulses in Air (MPiA) Lidar System has the following specifications:

<b>Table 2.1: ALS80 HP Lidar System Specifications</b>	
Operating Altitude	100 – 7,620 meters
Scan Angle	0 to 72° (variable)
Swath Width	0 to 1.5 X altitude (variable)
Scan Frequency	0 – 200 Hz (variable based on scan angle)
Maximum Pulse Rate	1000 kHz (Effective)
Range Resolution	Better than 1 cm
Elevation Accuracy	6 - 19 cm single shot (one standard deviation)
Horizontal Accuracy	5 – 43 cm (one standard deviation)
Number of Returns per Pulse	Unlimited
Number of Intensities	3 (first, second, third)
Intensity Digitization	8 bit intensity + 8 bit AGC (Automatic Gain Control) level
MPiA (Multiple Pulses in Air)	8 bits @ 1nsec interval @ 50kHz
Laser Beam Divergence	0.22 mrad @ 1/e <sup>2</sup> (~0.15 mrad @ 1/e)
Laser Classification	Class IV laser product (FDA CFR 21)
Eye Safe Range	400m single shot depending on laser repetition rate
Roll Stabilization	Automatic adaptive, range = 75 degrees minus current FOV
Power Requirements	28 VDC @ 25A
Operating Temperature	0-40°C
Humidity	0-95% non-condensing
Supported GNSS Receivers	Ashtech Z12, Trimble 7400, Novatel Millenium

The lidar data was acquired with a Leica ALS70 500 kHz Multiple Pulses in Air (MPiA) Lidar Sensor System. The ALS70 lidar system, developed by Leica Geosystems of Heerbrugg, Switzerland, includes the simultaneous first, intermediate and last pulse data capture module, the extended altitude range module, and the target signal intensity capture module.

The ALS70 500 kHz Multiple Pulses in Air (MPiA) Lidar System has the following specifications:

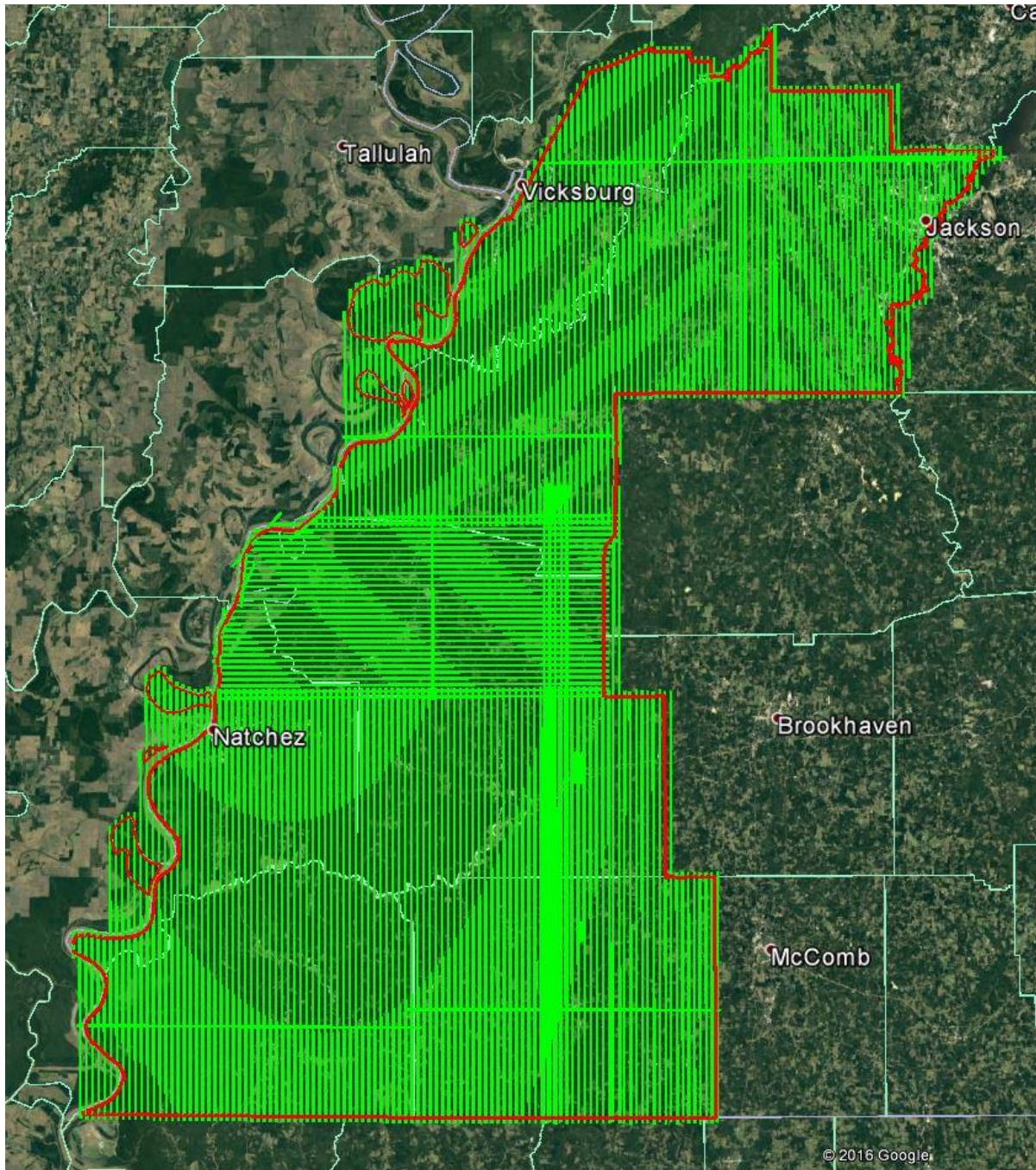
Operating Altitude	200 – 3,500 meters
Scan Angle	0 to 75° (variable)
Swath Width	0 to 1.5 X altitude (variable)
Scan Frequency	0 – 200 Hz (variable based on scan angle)
Maximum Pulse Rate	500 kHz (Effective)
Range Resolution	Better than 1 cm
Elevation Accuracy	7 - 16 cm single shot (one standard deviation)
Horizontal Accuracy	5 – 38 cm (one standard deviation)
Number of Returns per Pulse	7 (infinite)
Number of Intensities	3 (first, second, third)
Intensity Digitization	8 bit intensity + 8 bit AGC (Automatic Gain Control) level
MPiA (Multiple Pulses in Air)	8 bits @ 1nsec interval @ 50kHz
Laser Beam Divergence	0.22 mrad @ 1/e <sup>2</sup> (~0.15 mrad @ 1/e)
Laser Classification	Class IV laser product (FDA CFR 21)
Eye Safe Range	400m single shot depending on laser repetition rate
Roll Stabilization	Automatic adaptive, range = 75 degrees minus current FOV
Power Requirements	28 VDC @ 25A
Operating Temperature	0-40°C
Humidity	0-95% non-condensing
Supported GNSS Receivers	Ashtech Z12, Trimble 7400, Novatel Millenium

Prior to mobilizing to the project site, flight crews coordinated with the necessary Air Traffic Control personnel to ensure airspace access.

Crews were onsite, operating a Global Navigation Satellite System (GNSS) Base Station for the airborne GPS support.

The Lidar data was collected in Twenty-five (25) missions, flown as close together as the weather permitted, to ensure consistent ground conditions across the project area. An initial quality control process was performed immediately on the Lidar data to review the data coverage, airborne GPS data, and trajectory solution. Initial collection of lidar data took place January and February of 2016. During this time some significant precipitation events occurred in the region and led to significantly increased water levels in the Mississippi River and surrounding low-lying areas. Due to these high water levels it was determined that data acquisition be postponed until water levels lowered. Approximately 80% of the AOI had been acquired at this point. The remaining 20% was collected in January of 2017. Some water level differences will be observed in the point cloud and DEM data due to the differing collection dates, specifically in the low-lying areas near the Mississippi River. Woolpert has taken great care to limit the amount of temporal differences between the two collection dates.

Figure 2.1: Lidar Flight Layout, Mississippi NRCS FY16 Lidar



**Table 2.3: Airborne Lidar Acquisition Flight Summary**

Date of Mission	Lines Flown	Mission Time (UTC) Wheels Up/ Wheels Down
January 16, 2016_QSI7178_A	501-508	16:16 – 18:08
January 16, 2016_QSI7178_B	509-514, 599	19:59 – 21:41
January 17, 2016_QSI7178	518-539	20:17 – 20:36
January 18, 2016_QSI7178_A	944-954	16:00 – 18:34
January 18, 2016_QSI7178_B	936-943	20:24 – 23:02
January 19, 2016_QSI7178_A	515-517, 924-927	15:34 – 19:10
January 19, 2016_QSI7178_B	665-671	23:37 – 1:15
January 24, 2016_QSI7178	672-674	17:35 – 18:33
January 30, 2016_SH8170	192-196	14:30 – 17:01
February 3, 2016_SH8170	171-191	16:04 – 22:36
February 4, 2016_SH8170_A	167-170	15:31 – 16:45
February 4, 2016_SH8170_B	161-166	21:50 – 23:43
February 5, 2016_SH8170	139-160	15:57 – 22:46
February 6, 2016_SH8170	106, 107, 133-138, 197, 198	20:10 – 23:58
February 7, 2016_SH8170	82-105	15:47 – 23:06
February 8, 2016_SH8170	37, 38, 61-65, 76-81, 108	15:53 – 20:50
February 11, 2016_SH8170	39-60, 66	17:48 – 01:38
February 13, 2016_SH8170	37, 38, 61-64, 167, 176, 185, 192, 193	15:45 – 19:56
January 8, 2017_SH8170	109 - 127	17:11 – 22:38
January 9, 2017_SH8170	1-7, 9, 128	22:49 – 01:00
January 13, 2017_SH8170	8-25	21:19 – 2:23
January 14, 2017_SH8170_A	5, 6, 24-36	15:11 – 19:23
January 14, 2017_SH8170_B	1-4	20:42 – 22:03
January 15, 2017_SH8170	7, 8, 128-132	00:48 – 03:26
January 20, 2017_SH8170	8, 25	19:30 – 20:43



# Section 3: LiDAR Data Processing

## Applications and Work Flow Overview

1. Resolved kinematic corrections for three subsystems: inertial measurement unit (IMU), sensor orientation information and airborne GPS data. Developed a blending post-processed aircraft position with attitude data using Kalman filtering technology or the smoothed best estimate trajectory (SBET).

Software: POSPac Software v. 5.3, IPAS Pro v.1.35., Novatel Inertial Explorer v8.60.6129

2. Calculated laser point position by associating the SBET position to each laser point return time, scan angle, intensity, etc. Created raw laser point cloud data for the entire survey in LAS format. Automated line-to-line calibrations were then performed for system attitude parameters (pitch, roll, heading), mirror flex (scale) and GPS/IMU drift.

Software: ALS Post Processing Software v.2.75 build #25, Proprietary Software, TerraMatch v. 16.01., Add Leica Cloud Pro v1.2.3

3. Imported processed LAS point cloud data into the task order tiles. Resulting data were classified as ground and non-ground points with additional filters created to meet the task order classification specifications. Statistical absolute accuracy was assessed via direct comparisons of ground classified points to ground RTK survey data. Based on the statistical analysis, the lidar data was then adjusted to reduce the vertical bias when compared to the survey ground control.

Software: TerraScan v.16.01.

4. The LAS files were evaluated through a series of manual QA/QC steps to eliminate remaining artifacts from the ground class.

Software: TerraScan v.16.01.

## Global Navigation Satellite System (GNSS)–Inertial Measurement Unit (IMU) Trajectory Processing

### Equipment

The pilots are skilled at maintaining their planned trajectory, while holding the aircraft steady and level. If atmospheric conditions are such that the trajectory, ground speed, roll, pitch and/or heading cannot be properly maintained, the mission is aborted until suitable conditions occur.

Base stations were set by acquisition staff and were used to support the Lidar data acquisition. The GNSS base station operated during the Lidar acquisition missions is listed below:

Station (Name)	Latitude (DMS)	Longitude (DMS)	Ellipsoid Height (L1 Phase center) (Meters)
<b>MSJK CORS</b>	32°19'37.38128"	90°10'52.77645"	87.829
<b>MSBU CORS</b>	31°27'44.12478"	90°50'15.12326"	50.665
<b>TALL CORS</b>	32°24'01.19649"	91°10'58.81157"	7.477
<b>NGS PID CP0258</b>	32°19'44.13115"	90°12'57.82073"	70.11
<b>KHEZ Base</b>	31°36'51.75081"	91°17'39.33840"	55.736
<b>KHEZ Airport</b>	31°36'53.02032"	91°17'38.72688"	55.739
<b>SIHS CORS</b>	31°50'36.15839"	91°39'19.56089"	7.135

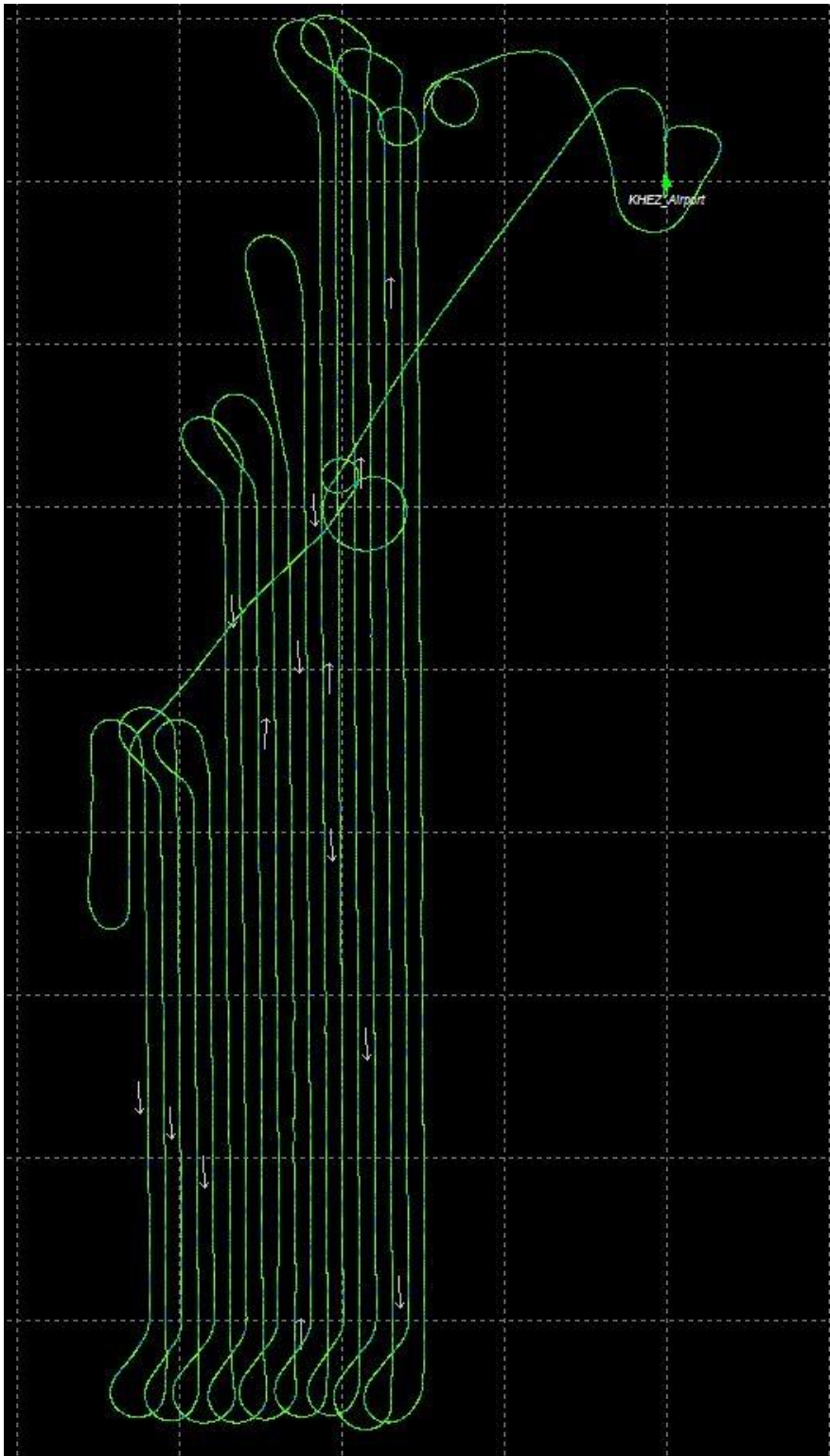
## Data Processing

All airborne GNSS and IMU data was post-processed and quality controlled using Applanix MMS software. GNSS data was processed at a 1 and 2 Hz data capture rate and the IMU data was processed at 200 Hz.

## Trajectory Quality

The GNSS Trajectory, along with high quality IMU data are key factors in determining the overall positional accuracy of the final sensor data. Within the trajectory processing, there are many factors that affect the overall quality, but the most indicative are the combined separation, the estimated positional accuracy, and the Positional Dilution of Precision (PDOP).

Figure 3.1: Trajectory, Day00817\_SH8170

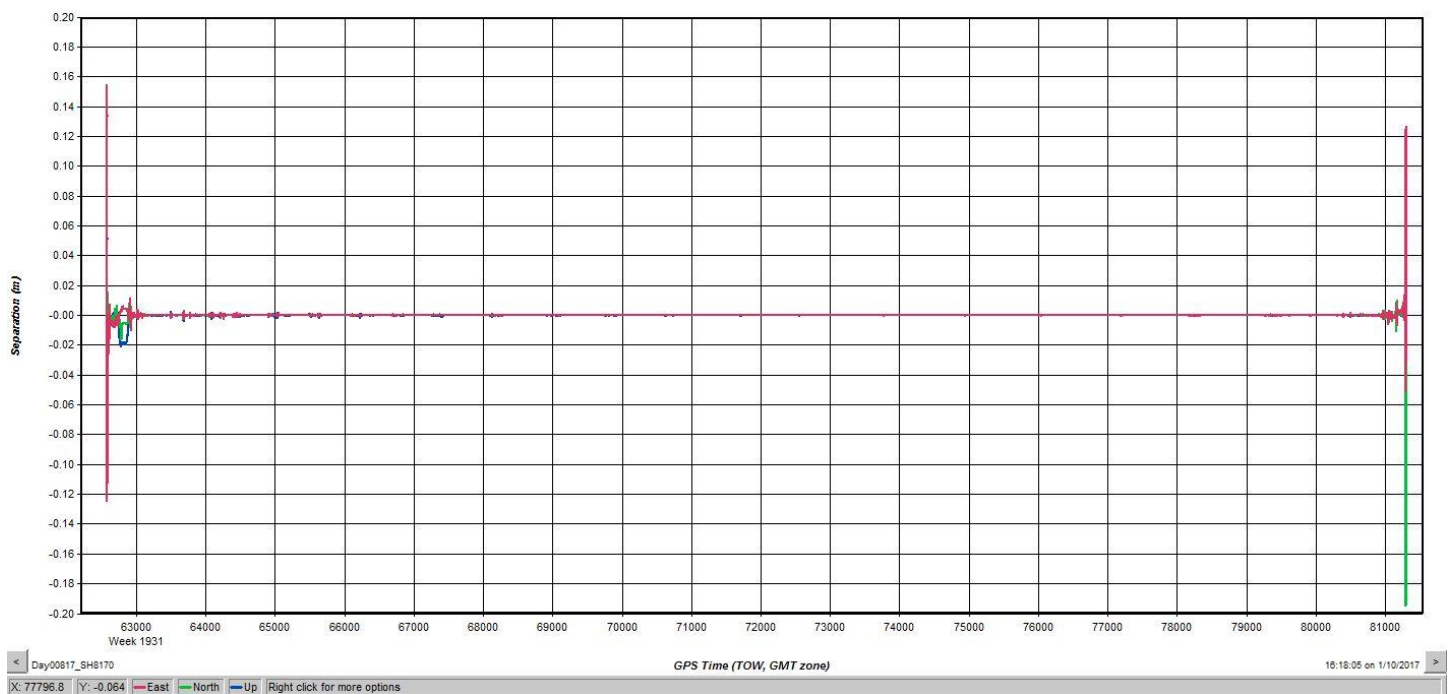


## Combination Separation

The Combined Separation is a measure of the difference between the forward run and the backward run solution of the trajectory. The Kalman filter is processed in both directions to remove the combined directional anomalies. In general, when these two solutions match closely, an optimally accurate reliable solution is achieved.

Woolpert's goal is to maintain a Combined Separation Difference of less than ten (10) centimeters. In most cases we achieve results below this threshold.

Figure 3.2: Combined Separation, Day00817\_SH8170

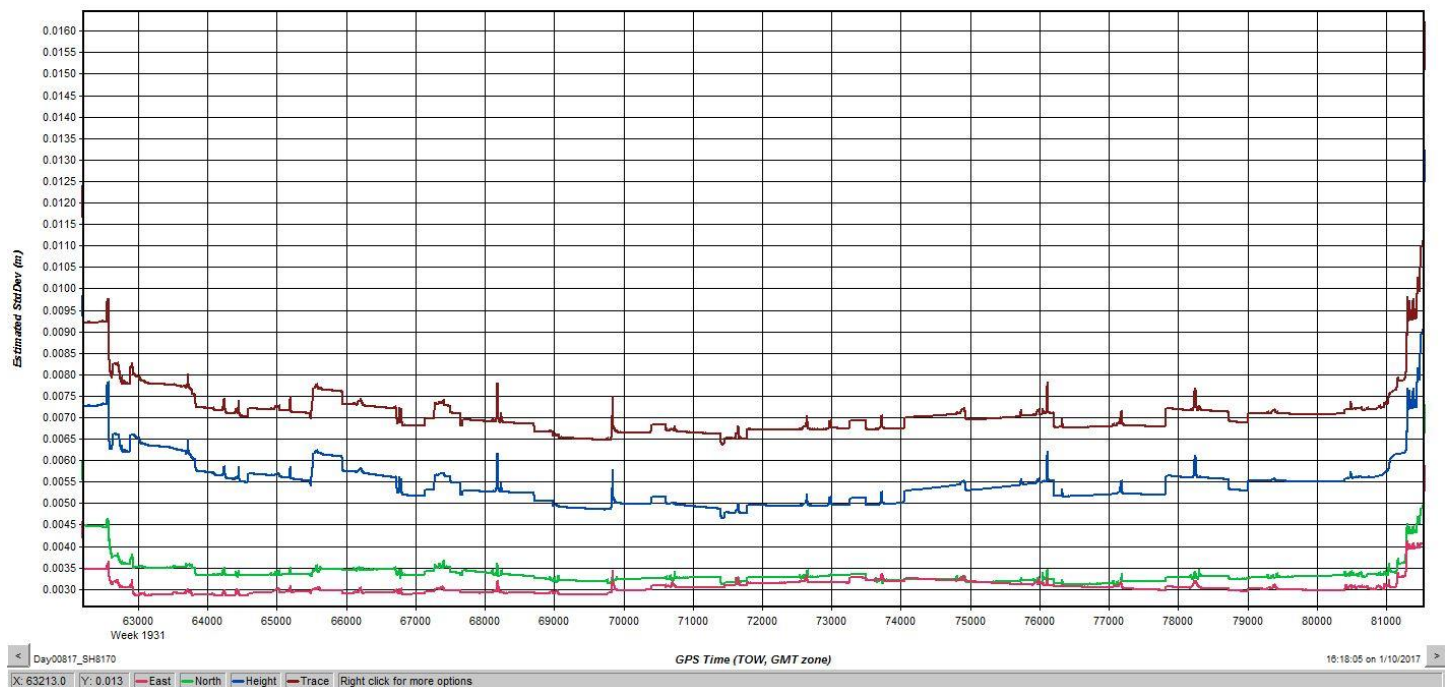


## Estimated Positional Accuracy

The Estimated Positional Accuracy plots the standard deviations of the east, north, and vertical directions along a time scale of the trajectory. It illustrates loss of satellite lock issues, as well as issues arising from long baselines, noise, and/or other atmospheric interference.

Woolpert's goal is to maintain an Estimated Positional Accuracy of less than ten (10) centimeters, often achieving results well below this threshold.

Figure 3.3: Estimated Positional Accuracy, Day00817\_SH8170

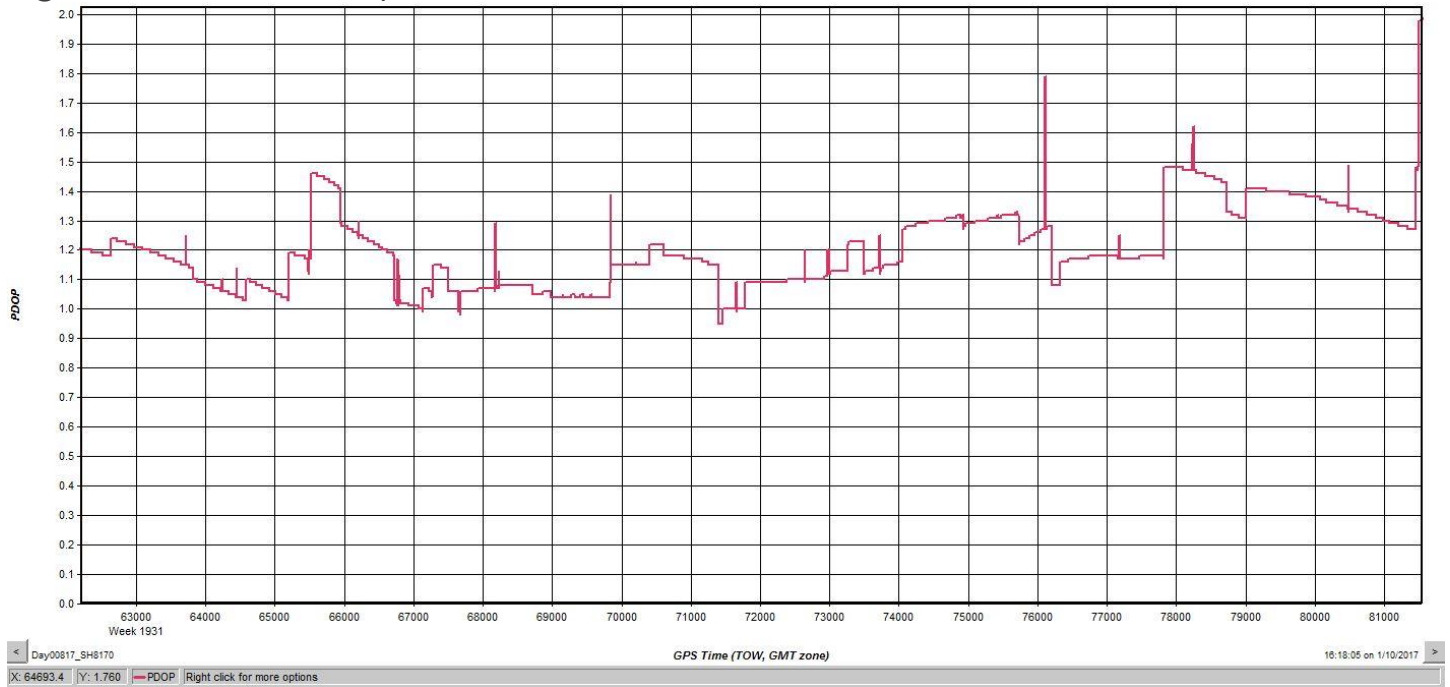


## PDOP

The PDOP measures the precision of the GPS solution in regards to the geometry of the satellites acquired and used for the solution.

Woolpert's goal is to maintain an average PDOP value below 3.0. Brief periods of PDOP over 3.0 are acceptable due to the calibration and control process if other metrics are within specification.

Figure 3.4: PDOP, Day00817\_SH8170



## LiDAR Data Processing

When the sensor calibration, data acquisition, and GPS processing phases were complete, the formal data reduction processes by Woolpert lidar specialists included:

- Processed individual flight lines to derive a raw “Point Cloud” LAS file. Matched overlapping flight lines, generated statistics for evaluation comparisons, and made the necessary adjustments to remove any residual systematic error.
- Calibrated LAS files were imported into the task order tiles and initially filtered to create a ground and non-ground class. Then additional classes were filtered as necessary to meet client specified classes.
- Once all project data was imported and classified, survey ground control data was imported and calculated for an accuracy assessment. As a QC measure, Woolpert has developed a routine to generate accuracy statistical reports by comparisons against the TIN and the DEM using surveyed ground control of higher accuracy. The lidar is adjusted accordingly to meet or exceed the vertical accuracy requirements.
- The lidar tiles were reviewed using a series of proprietary QA/QC procedures to ensure it fulfills the task order requirements. A portion of this requires a manual step to ensure anomalies have been removed from the ground class.
- The lidar LAS files are classified into the Default (Class 1), Ground (Class 2), Low Noise (Class 7), Water (Class 9), Ignored ground (Class10), Bridge Decks (Class 17), High Noise (Class 18) classifications.
- FGDC Compliant metadata was developed for the task order in .xml format per product.
- The horizontal datum used for the task order was referenced to NAD83 (2011), Zone 15, Meters. The vertical datum used for the task order was referenced to NAVD 1988, Meters, GEOID12B
- Please note that tiles 15RXQ330320 and 15RXQ405950 do not contain lidar points. The data boundary intersects these tiles and a hydro breakline was digitized based on this boundary. For this reason a hydro-flattened DEM IMG and Intensity Image was generated. There will be no LAS 1.4 for tiles 15RXQ330320 and 15RXQ405950. The DEM IMG/Intensity tiff file count is 5903. The LAS 1.4 count is 5901.

# Section 4: Hydrologic Flattening

## HYDROLOGIC FLATTENING OF LIDAR DEM DATA

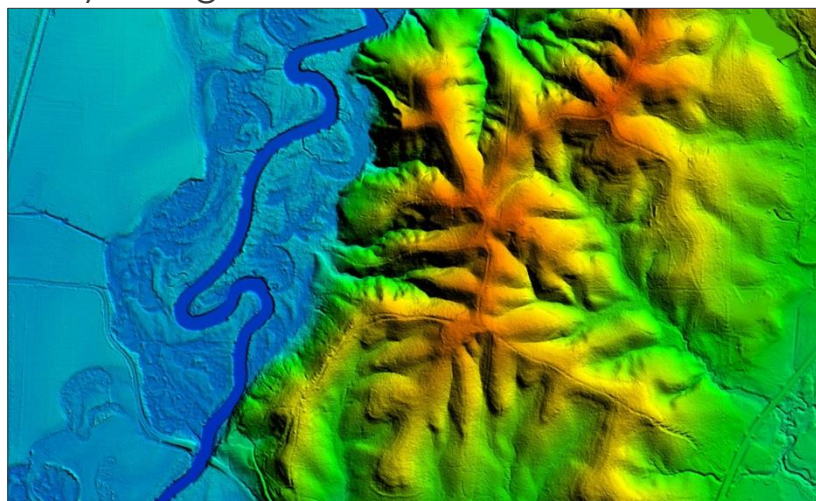
Mississippi NRCS FY16 Lidar processing task order required the compilation of breaklines defining water bodies and rivers. The breaklines were used to perform the hydrologic flattening of water bodies, and gradient hydrologic flattening of double line streams and rivers. Lakes, reservoirs and ponds, at a minimum size of 2-acre or greater, were compiled as closed polygons. The closed water bodies were collected at a constant elevation. Rivers and streams, at a nominal minimum width of 30 meters (100 feet), were compiled in the direction of flow with both sides of the stream maintaining an equal gradient elevation.

## LIDAR DATA REVIEW AND PROCESSING

Woolpert utilized the following steps to hydrologically flatten the water bodies and for gradient hydrologic flattening of the double line streams within the existing lidar data.

1. Woolpert used the newly acquired lidar data to manually draw the hydrologic features in a 2D environment using the lidar intensity and bare earth surface. Open Source imagery was used as reference when necessary.
2. Woolpert utilizes an integrated software approach to combine the lidar data and 2D breaklines. This process “drapes” the 2D breaklines onto the 3D lidar surface model to assign an elevation. A monotonic process is performed to ensure the streams are consistently flowing in a gradient manner. A secondary step within the program verifies an equally matching elevation of both stream edges. The breaklines that characterize the closed water bodies are draped onto the 3D lidar surface and assigned a constant elevation at or just below ground elevation.
3. The lakes, reservoirs and ponds, at a minimum size of 2-acre or greater and streams at a minimum size of 30 meters (100 feet) nominal width, were compiled to meet task order requirements. **Figure 4.1** illustrates an example of 30 meters (100 feet) nominal streams identified and defined with hydrologic breaklines. The breaklines defining rivers and streams, at a nominal minimum width of 30 meters (100 feet), were draped with both sides of the stream maintaining an equal gradient elevation.
4. All ground points were reclassified from inside the hydrologic feature polygons to water, class nine (9).
5. All ground points were reclassified from within a buffer along the hydrologic feature breaklines to buffered ground, class ten (10).
6. The lidar ground points and hydrologic feature breaklines were used to generate a new digital elevation model (DEM).

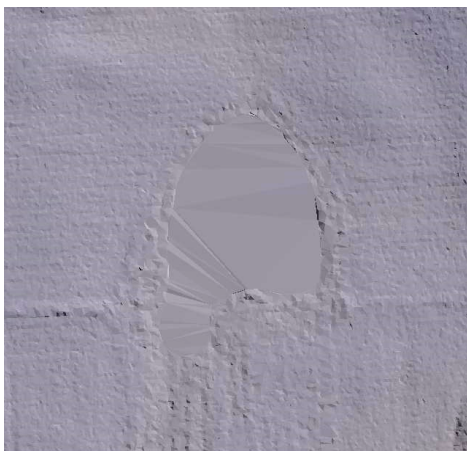
Figure 4.1: Example Hydrologic Breaklines





**Figure 4.2** reflects a DEM generated from original lidar bare earth point data prior to the hydrologic flattening process. Note the “tinning” across the lake surface.

**Figure 4.3** reflects a DEM generated from lidar with breaklines compiled to define the hydrologic features. This figure illustrates the results of adding the breaklines to hydrologically flatten the DEM data. Note the smooth appearance of the lake surface in the DEM.



**Figure 4.2**



**Figure 4.3**

Terrascan was used to add the hydrologic breakline vertices and export the lattice models. The hydrologically flattened DEM data was provided to USGS in ERDAS .IMG format.

The hydrologic breaklines compiled as part of the flattening process were provided to the USGS in ESRI shapefile format. The breaklines defining the water bodies greater than 2-acre and for the gradient flattening of all rivers and streams at a nominal minimum width of 30 meters (100 feet) were provided as a Polygon-Z and Polyline-Z shape file, respectively.

## DATA QA/QC

Initial QA/QC for this task order was performed in Global Mapper v17, by reviewing the grids and hydrologic breakline features. Additionally, ESRI software and proprietary methods were used to review the overall connectivity of the hydrologic breaklines.

Edits and corrections were addressed individually by tile. If a water body breakline needed to be adjusted to improve the flattening of the DEM data, the area was cross referenced by tile number, corrected accordingly, a new DEM file was regenerated and reviewed.

# Section 5: ACCURACY ASSESSMENT

## Accuracy Assessment

The vertical accuracy statistics were calculated by comparison of all lidar points to the ground surveyed QC points.

**Table 5.1: Overall Vertical Accuracy Statistics**

Average error	+0.009	Meter
Minimum error	-0.156	Meter
Maximum error	+0.231	Meter
Average magnitude	0.036	Meter
Root mean square	0.050	Meter
Standard deviation	0.050	Meter

**Table 5.2: RAW Swath Quality Check Point Analysis NVA**

Point ID	Easting (Meter)	Northing (Meter)	Elevation (Meter)	TIN Elevation (Meter)	Dz (Meter)
2001	642432.381	3438393.705	115.051	115.020	-0.031
2002	638385.709	3440023.583	17.356	17.410	0.054
2003	652290.806	3473582.584	50.296	50.200	-0.096
2004	646164.916	3447423.767	28.544	28.550	0.006
2005	647970.254	3489983.281	25.234	25.260	0.026
2006	664846.881	3498250.453	92.452	92.470	0.018
2007	658981.983	3480705.583	113.098	113.100	0.002
2008	658363.172	3459498.909	38.270	38.370	0.100
2009	667355.856	3440939.046	109.956	109.920	-0.036
2010	681333.281	3431790.400	104.406	104.370	-0.036
2011	676458.158	3459977.263	95.106	95.120	0.014
2012	680203.510	3480805.061	66.770	66.720	-0.050
2013	710868.729	3449771.485	124.206	124.260	0.054
2014	688156.591	3451963.539	116.909	117.000	0.091
2015	699907.069	3437597.322	103.726	103.740	0.014
2016	719017.750	3441559.752	99.971	99.980	0.009
2017	726652.143	3458232.013	136.849	136.830	-0.019
2018	707536.837	3466683.338	125.165	125.200	0.035
2019	706235.884	3484251.510	80.084	80.100	0.016
2020	691631.583	3495179.292	108.801	108.810	0.009
2021	721969.050	3489259.563	99.603	99.630	0.027
2022	711198.368	3508683.330	128.673	128.700	0.027
2023	678028.521	3504757.690	95.540	95.540	0.000

<b>2024</b>	704570.182	3499001.319	149.854	149.860	0.006
<b>2025</b>	686690.216	3511623.007	65.297	65.340	0.043
<b>2026</b>	699035.141	3507682.736	113.972	113.940	-0.032
<b>2027</b>	706448.237	3516278.277	87.175	87.190	0.015
<b>2028</b>	691487.689	3518924.516	81.940	81.970	0.030
<b>2029</b>	701752.231	3527896.000	69.904	69.900	-0.004
<b>2030</b>	677029.349	3528145.891	76.017	75.990	-0.027
<b>2031</b>	673047.760	3513900.262	45.674	45.690	0.016
<b>2032</b>	667140.188	3509606.984	69.205	69.120	-0.085
<b>2033</b>	656050.372	3500284.945	81.203	81.130	-0.073
<b>2034</b>	696478.166	3471309.988	82.318	82.360	0.042
<b>2035</b>	701589.063	3542389.874	38.147	38.070	-0.077
<b>2036</b>	690398.333	3536218.226	54.689	54.590	-0.099
<b>2037</b>	684695.223	3544043.766	53.448	53.510	0.062
<b>2038</b>	693899.416	3559571.981	39.460	39.570	0.110
<b>2039</b>	712774.707	3558409.109	76.408	76.410	0.002
<b>2040</b>	704399.634	3580300.097	77.127	77.180	0.053
<b>2041</b>	712619.193	3599279.386	89.478	89.470	-0.008
<b>2042</b>	719736.491	3583858.885	50.684	50.700	0.016
<b>2043</b>	712078.485	3569826.361	34.074	34.100	0.026
<b>2044</b>	733690.663	3568973.673	59.442	59.470	0.028
<b>2045</b>	724437.494	3574326.930	54.778	54.840	0.062
<b>2046</b>	715075.571	3594362.599	105.535	105.520	-0.015
<b>2047</b>	735698.082	3596830.814	85.019	85.010	-0.009
<b>2048</b>	738776.295	3559050.136	104.283	104.270	-0.013
<b>2049</b>	723610.421	3564541.570	105.669	105.700	0.031
<b>2050</b>	747605.469	3554580.224	131.984	131.960	-0.024
<b>2051</b>	742751.315	3552614.055	99.400	99.470	0.070
<b>2052</b>	757420.828	3550522.377	99.998	99.950	-0.048
<b>2053</b>	750131.878	3567394.817	132.916	132.760	-0.156
<b>2054</b>	735448.366	3590035.000	81.552	81.510	-0.042
<b>2055</b>	738209.191	3583323.610	63.274	63.330	0.056
<b>2056</b>	749961.528	3581870.454	93.456	93.410	-0.046
<b>2057</b>	746988.008	3593602.296	82.222	82.190	-0.032
<b>2058</b>	757424.391	3597269.585	83.538	83.470	-0.068
<b>2059</b>	760665.508	3586930.470	108.742	108.730	-0.012
<b>2060</b>	753352.254	3592483.833	71.626	71.610	-0.016
<b>2061</b>	743856.577	3588523.507	98.990	99.010	0.020
<b>2062</b>	767785.549	3581316.974	89.423	89.440	0.017
<b>2063</b>	759661.588	3579032.011	97.197	97.200	0.003
<b>2064</b>	762424.844	3571725.225	103.333	103.370	0.037

<b>2065</b>	759216.816	3563827.865	79.734	79.730	-0.004
<b>2066</b>	684291.381	3442663.140	116.149	116.170	0.021
<b>2067</b>	700139.647	3460689.259	130.001	130.030	0.029
<b>2068</b>	729531.075	3449393.654	127.632	127.620	-0.012
<b>2069</b>	716735.235	3464052.834	136.758	136.770	0.012
<b>2070</b>	663795.418	3475764.136	58.089	58.120	0.031
<b>2071</b>	679381.788	3473256.555	51.875	51.900	0.025
<b>2072</b>	677622.112	3491250.743	119.850	119.860	0.010
<b>2073</b>	692486.659	3504953.819	136.929	136.950	0.021
<b>2074</b>	694569.157	3512875.806	86.789	86.780	-0.009
<b>2075</b>	680416.395	3518476.329	45.956	45.930	-0.026
<b>2076</b>	670723.005	3526521.722	36.888	36.820	-0.068
<b>2077</b>	695960.870	3548932.977	51.864	51.940	0.076
<b>2078</b>	710148.274	3551577.402	99.139	99.370	0.231
<b>2079</b>	703194.722	3569748.354	79.370	79.360	-0.010
<b>2080</b>	706093.624	3563719.978	47.572	47.570	-0.002
<b>2081</b>	709129.205	3588411.333	84.541	84.530	-0.011
<b>2082</b>	717382.937	3587202.699	92.255	92.270	0.015
<b>2083</b>	723654.830	3592980.517	73.388	73.350	-0.038
<b>2084</b>	732550.301	3586847.238	95.669	95.680	0.011
<b>2085</b>	732746.183	3595089.841	53.813	53.790	-0.023
<b>2086</b>	726166.522	3555648.307	88.022	88.060	0.038
<b>2087</b>	747374.714	3562093.816	122.309	122.250	-0.059
<b>2088</b>	743872.844	3575718.365	82.441	82.540	0.099
<b>2089</b>	755555.013	3574118.344	142.427	142.460	0.033
<b>2090</b>	732459.546	3581088.495	77.088	77.270	0.182
<b>2091</b>	768269.491	3588327.542	95.811	95.820	0.009
<b>2092</b>	759190.693	3568711.641	102.674	102.640	-0.034
<b>2093</b>	754626.879	3559331.792	115.725	115.730	0.005
<b>2094</b>	734278.451	3550008.197	83.537	83.530	-0.007
<b>2095</b>	732104.215	3559277.980	70.111	70.140	0.029
<b>2096</b>	741154.602	3566420.797	73.785	73.840	0.055
<b>2097</b>	713325.181	3576589.542	51.634	51.610	-0.024
<b>2098</b>	720114.259	3573101.520	38.926	38.940	0.014
<b>2099</b>	717874.292	3567821.718	39.322	39.390	0.068
<b>2100</b>	724441.983	3569385.049	58.942	59.000	0.058
<b>2101</b>	726254.669	3580610.706	80.573	80.610	0.037
<b>2102</b>	726698.796	3588291.704	78.964	78.960	-0.004
<b>2103</b>	717268.868	3560553.155	81.282	81.270	-0.012
<b>2104</b>	717340.961	3554814.216	78.273	78.310	0.037
<b>2105</b>	714090.816	3542740.359	57.348	57.380	0.032

<b>2106</b>	704117.180	3537891.357	55.503	55.510	0.007
<b>2107</b>	708074.233	3524378.300	80.973	80.980	0.007
<b>2108</b>	721752.913	3497641.494	141.658	141.690	0.032
<b>2109</b>	717125.490	3479902.220	102.808	102.840	0.032
<b>2110</b>	711980.329	3458314.094	130.290	130.340	0.050
<b>2111</b>	711983.566	3432318.767	106.051	106.110	0.059
<b>2112</b>	733390.757	3439405.021	102.643	102.630	-0.013
<b>2113</b>	719031.796	3453028.141	99.695	99.710	0.015
<b>2114</b>	697601.328	3447107.902	114.948	114.930	-0.018
<b>2115</b>	687340.078	3462033.300	75.227	75.260	0.033
<b>2116</b>	688723.097	3486192.781	125.684	125.670	-0.014
<b>2117</b>	667815.002	3455553.676	40.787	40.800	0.013
<b>2118</b>	667947.153	3486013.422	116.500	116.520	0.020
<b>2119</b>	684895.357	3501439.328	141.568	141.570	0.002
<b>2120</b>	678364.897	3451911.845	113.413	113.350	-0.063

## VERTICAL ACCURACY CONCLUSIONS

Raw Swath Non-Vegetated Vertical Accuracy (NVA) Tested 0.098 Meters Non vegetated vertical accuracy at a 95 percent confidence level, derived according to NSSDA, in open terrain using (RMSEz) x 1.96000 as defined by the National Standards for Spatial Data Accuracy (NSSDA); assessed and reported against 120 NVA points using National Digital Elevation Program (NDEP)/ASPRS Guidelines and tested against the TIN using all points.

LAS Swath Non-Vegetated Vertical Accuracy (NVA) Tested 0.086 Meters Non vegetated vertical accuracy at a 95 percent confidence level, derived according to NSSDA, in open terrain using (RMSEz) x 1.96000 as defined by the National Standards for Spatial Data Accuracy (NSSDA); assessed and reported against 120 NVA points using National Digital Elevation Program (NDEP)/ASPRS Guidelines and tested against the TIN using ground points.

**Table 5.3: NVA Check Point Analysis DEM**

Point ID	Easting (Meter)	Northing (Meter)	Elevation (Meter)	DEM Elevation (Meter)	Dz (Meter)
<b>2001</b>	642432.381	3438393.705	115.051	115.010	0.041
<b>2002</b>	638385.709	3440023.583	17.356	17.410	-0.054
<b>2003</b>	652290.806	3473582.584	50.296	50.200	0.096
<b>2004</b>	646164.916	3447423.767	28.544	28.520	0.024
<b>2005</b>	647970.254	3489983.281	25.234	25.270	-0.036
<b>2006</b>	664846.881	3498250.453	92.452	92.480	-0.028
<b>2007</b>	658981.983	3480705.583	113.098	113.060	0.038
<b>2008</b>	658363.172	3459498.909	38.270	38.370	-0.100
<b>2009</b>	667355.856	3440939.046	109.956	109.960	-0.004
<b>2010</b>	681333.281	3431790.400	104.406	104.370	0.036
<b>2011</b>	676458.158	3459977.263	95.106	95.120	-0.014

<b>2012</b>	680203.510	3480805.061	66.770	66.680	0.090
<b>2013</b>	710868.729	3449771.485	124.206	124.250	-0.044
<b>2014</b>	688156.591	3451963.539	116.909	117.000	-0.091
<b>2015</b>	699907.069	3437597.322	103.726	103.750	-0.024
<b>2016</b>	719017.750	3441559.752	99.971	100.020	-0.049
<b>2017</b>	726652.143	3458232.013	136.849	136.840	0.009
<b>2018</b>	707536.837	3466683.338	125.165	125.210	-0.045
<b>2019</b>	706235.884	3484251.510	80.084	80.120	-0.036
<b>2020</b>	691631.583	3495179.292	108.801	108.800	0.001
<b>2021</b>	721969.050	3489259.563	99.603	99.630	-0.027
<b>2022</b>	711198.368	3508683.330	128.673	128.700	-0.027
<b>2023</b>	678028.521	3504757.690	95.540	95.530	0.010
<b>2024</b>	704570.182	3499001.319	149.854	149.840	0.014
<b>2025</b>	686690.216	3511623.007	65.297	65.350	-0.053
<b>2026</b>	699035.141	3507682.736	113.972	113.950	0.022
<b>2027</b>	706448.237	3516278.277	87.175	87.180	-0.005
<b>2028</b>	691487.689	3518924.516	81.940	81.970	-0.030
<b>2029</b>	701752.231	3527896.000	69.904	69.870	0.034
<b>2030</b>	677029.349	3528145.891	76.017	76.030	-0.013
<b>2031</b>	673047.760	3513900.262	45.674	45.650	0.024
<b>2032</b>	667140.188	3509606.984	69.205	69.130	0.075
<b>2033</b>	656050.372	3500284.945	81.203	81.130	0.073
<b>2034</b>	696478.166	3471309.988	82.318	82.380	-0.062
<b>2035</b>	701589.063	3542389.874	38.147	38.080	0.067
<b>2036</b>	690398.333	3536218.226	54.689	54.600	0.089
<b>2037</b>	684695.223	3544043.766	53.448	53.470	-0.022
<b>2038</b>	693899.416	3559571.981	39.460	39.610	-0.150
<b>2039</b>	712774.707	3558409.109	76.408	76.410	-0.002
<b>2040</b>	704399.634	3580300.097	77.127	77.150	-0.023
<b>2041</b>	712619.193	3599279.386	89.478	89.490	-0.012
<b>2042</b>	719736.491	3583858.885	50.684	50.710	-0.026
<b>2043</b>	712078.485	3569826.361	34.074	34.090	-0.016
<b>2044</b>	733690.663	3568973.673	59.442	59.470	-0.028
<b>2045</b>	724437.494	3574326.930	54.778	54.850	-0.072
<b>2046</b>	715075.571	3594362.599	105.535	105.520	0.015
<b>2047</b>	735698.082	3596830.814	85.019	85.010	0.009
<b>2048</b>	738776.295	3559050.136	104.283	104.290	-0.007
<b>2049</b>	723610.421	3564541.570	105.669	105.710	-0.041
<b>2050</b>	747605.469	3554580.224	131.984	131.970	0.014
<b>2051</b>	742751.315	3552614.055	99.400	99.440	-0.040
<b>2052</b>	757420.828	3550522.377	99.998	99.950	0.048

<b>2053</b>	750131.878	3567394.817	132.916	132.820	0.096
<b>2054</b>	735448.366	3590035.000	81.552	81.510	0.042
<b>2055</b>	738209.191	3583323.610	63.274	63.320	-0.046
<b>2056</b>	749961.528	3581870.454	93.456	93.410	0.046
<b>2057</b>	746988.008	3593602.296	82.222	82.190	0.032
<b>2058</b>	757424.391	3597269.585	83.538	83.470	0.068
<b>2059</b>	760665.508	3586930.470	108.742	108.730	0.012
<b>2060</b>	753352.254	3592483.833	71.626	71.600	0.026
<b>2061</b>	743856.577	3588523.507	98.990	99.010	-0.020
<b>2062</b>	767785.549	3581316.974	89.423	89.440	-0.017
<b>2063</b>	759661.588	3579032.011	97.197	97.200	-0.003
<b>2064</b>	762424.844	3571725.225	103.333	103.390	-0.057
<b>2065</b>	759216.816	3563827.865	79.734	79.710	0.024
<b>2066</b>	684291.381	3442663.140	116.149	116.180	-0.031
<b>2067</b>	700139.647	3460689.259	130.001	130.030	-0.029
<b>2068</b>	729531.075	3449393.654	127.632	127.620	0.012
<b>2069</b>	716735.235	3464052.834	136.758	136.780	-0.022
<b>2070</b>	663795.418	3475764.136	58.089	58.100	-0.011
<b>2071</b>	679381.788	3473256.555	51.875	51.900	-0.025
<b>2072</b>	677622.112	3491250.743	119.850	119.870	-0.020
<b>2073</b>	692486.659	3504953.819	136.929	136.940	-0.011
<b>2074</b>	694569.157	3512875.806	86.789	86.780	0.009
<b>2075</b>	680416.395	3518476.329	45.956	45.930	0.026
<b>2076</b>	670723.005	3526521.722	36.888	36.850	0.038
<b>2077</b>	695960.870	3548932.977	51.864	51.920	-0.056
<b>2078</b>	710148.274	3551577.402	99.139	99.360	-0.221
<b>2079</b>	703194.722	3569748.354	79.370	79.360	0.010
<b>2080</b>	706093.624	3563719.978	47.572	47.570	0.002
<b>2081</b>	709129.205	3588411.333	84.541	84.510	0.031
<b>2082</b>	717382.937	3587202.699	92.255	92.270	-0.015
<b>2083</b>	723654.830	3592980.517	73.388	73.350	0.038
<b>2084</b>	732550.301	3586847.238	95.669	95.700	-0.031
<b>2085</b>	732746.183	3595089.841	53.813	53.790	0.023
<b>2086</b>	726166.522	3555648.307	88.022	88.060	-0.038
<b>2087</b>	747374.714	3562093.816	122.309	122.310	-0.001
<b>2088</b>	743872.844	3575718.365	82.441	82.540	-0.099
<b>2089</b>	755555.013	3574118.344	142.427	142.460	-0.033
<b>2090</b>	732459.546	3581088.495	77.088	77.080	0.008
<b>2091</b>	768269.491	3588327.542	95.811	95.820	-0.009
<b>2092</b>	759190.693	3568711.641	102.674	102.630	0.044
<b>2093</b>	754626.879	3559331.792	115.725	115.740	-0.015

<b>2094</b>	734278.451	3550008.197	83.537	83.560	-0.023
<b>2095</b>	732104.215	3559277.980	70.111	70.150	-0.039
<b>2096</b>	741154.602	3566420.797	73.785	73.820	-0.035
<b>2097</b>	713325.181	3576589.542	51.634	51.600	0.034
<b>2098</b>	720114.259	3573101.520	38.926	38.930	-0.004
<b>2099</b>	717874.292	3567821.718	39.322	39.400	-0.078
<b>2100</b>	724441.983	3569385.049	58.942	59.010	-0.068
<b>2101</b>	726254.669	3580610.706	80.573	80.590	-0.017
<b>2102</b>	726698.796	3588291.704	78.964	78.970	-0.006
<b>2103</b>	717268.868	3560553.155	81.282	81.280	0.002
<b>2104</b>	717340.961	3554814.216	78.273	78.280	-0.007
<b>2105</b>	714090.816	3542740.359	57.348	57.370	-0.022
<b>2106</b>	704117.180	3537891.357	55.503	55.490	0.013
<b>2107</b>	708074.233	3524378.300	80.973	81.000	-0.027
<b>2108</b>	721752.913	3497641.494	141.658	141.700	-0.042
<b>2109</b>	717125.490	3479902.220	102.808	102.810	-0.002
<b>2110</b>	711980.329	3458314.094	130.290	130.340	-0.050
<b>2111</b>	711983.566	3432318.767	106.051	106.100	-0.049
<b>2112</b>	733390.757	3439405.021	102.643	102.650	-0.007
<b>2113</b>	719031.796	3453028.141	99.695	99.710	-0.015
<b>2114</b>	697601.328	3447107.902	114.948	114.930	0.018
<b>2115</b>	687340.078	3462033.300	75.227	75.240	-0.013
<b>2116</b>	688723.097	3486192.781	125.684	125.680	0.004
<b>2117</b>	667815.002	3455553.676	40.787	40.800	-0.013
<b>2118</b>	667947.153	3486013.422	116.500	116.520	-0.020
<b>2119</b>	684895.357	3501439.328	141.568	141.580	-0.012
<b>2120</b>	678364.897	3451911.845	113.413	113.350	0.063

## VERTICAL ACCURACY CONCLUSIONS

Bare-Earth DEM Non-Vegetated Vertical Accuracy (NVA) Tested 0.090 Meters Non-Vegetated vertical accuracy at a 95 percent confidence level, derived according to NSSDA, in open terrain using (RMSEz) x 1.96000 as defined by the National Standards for Spatial Data Accuracy (NSSDA); assessed and reported against 120 NVA points using National Digital Elevation Program (NDEP)/ASPRS Guidelines and tested against the DEM.

**Table 5.4: VVA Quality Check Point Analysis DEM**

<b>Point ID</b>	<b>Easting (Meter)</b>	<b>Northing (Meter)</b>	<b>Elevation (Meter)</b>	<b>DEM Elevation (Meter)</b>	<b>Dz (Meter)</b>
<b>3001</b>	642191.591	3438327.564	121.596	121.580	0.016
<b>3002</b>	638622.094	3440260.727	19.075	18.960	0.115
<b>3003</b>	652463.609	3472730.752	34.908	34.860	0.048



<b>3004</b>	647106.283	3447526.145	32.921	32.840	0.081
<b>3005</b>	648165.691	3489740.144	21.111	21.230	-0.119
<b>3006</b>	664951.646	3498651.432	91.793	91.910	-0.117
<b>3007</b>	659395.369	3481067.478	111.328	111.370	-0.042
<b>3008</b>	658812.466	3459888.404	48.381	48.440	-0.059
<b>3009</b>	667185.089	3440665.052	113.309	113.410	-0.101
<b>3010</b>	681417.958	3431348.956	91.036	91.080	-0.044
<b>3011</b>	675825.520	3459581.594	91.273	91.490	-0.217
<b>3012</b>	680340.929	3480308.561	62.251	62.240	0.011
<b>3013</b>	709066.888	3449257.946	107.782	107.850	-0.068
<b>3014</b>	688934.350	3453228.600	121.108	121.120	-0.012
<b>3015</b>	700384.312	3437629.715	88.664	88.730	-0.066
<b>3016</b>	719787.301	3441018.691	106.762	106.790	-0.028
<b>3017</b>	727097.676	3458525.288	136.965	137.030	-0.065
<b>3018</b>	706829.208	3466532.573	139.153	139.250	-0.097
<b>3019</b>	705231.814	3483782.870	89.936	89.990	-0.054
<b>3020</b>	692267.587	3495080.371	101.294	101.280	0.014
<b>3021</b>	722546.554	3489460.743	97.073	97.110	-0.037
<b>3022</b>	711576.214	3509134.542	119.076	119.120	-0.044
<b>3023</b>	678046.406	3505057.761	102.848	102.830	0.018
<b>3024</b>	704563.550	3499382.420	148.040	148.070	-0.030
<b>3025</b>	686797.299	3511311.755	68.590	68.650	-0.060
<b>3026</b>	699437.911	3507816.836	115.391	115.360	0.031
<b>3027</b>	706858.177	3516318.137	76.363	76.430	-0.067
<b>3028</b>	692071.686	3518443.429	89.396	89.420	-0.024
<b>3029</b>	702290.492	3527542.081	62.410	62.560	-0.150
<b>3030</b>	677242.155	3527405.096	72.035	72.010	0.025
<b>3031</b>	672795.469	3514105.945	32.133	32.150	-0.017
<b>3032</b>	666916.744	3510332.913	63.723	63.720	0.003
<b>3033</b>	656656.185	3500707.272	82.165	82.170	-0.005
<b>3034A</b>	696559.360	3470932.781	73.751	73.770	-0.019
<b>3035</b>	701703.913	3541477.207	49.958	50.030	-0.072
<b>3036</b>	690216.961	3536292.956	53.654	53.600	0.054
<b>3037</b>	684400.191	3544380.906	58.912	59.070	-0.158
<b>3038</b>	694111.292	3559179.754	69.453	69.500	-0.047
<b>3039</b>	712311.243	3558425.294	73.366	73.530	-0.164
<b>3040</b>	704548.192	3580680.973	68.840	68.950	-0.110
<b>3041</b>	712149.376	3600318.611	44.378	44.480	-0.102
<b>3042</b>	719521.794	3583856.173	51.120	51.200	-0.080
<b>3043</b>	711765.463	3570092.722	35.500	35.560	-0.060
<b>3044</b>	733067.281	3568882.454	58.574	58.700	-0.126

<b>3045</b>	723890.329	3573982.526	52.562	52.670	-0.108
<b>3046</b>	714932.765	3594141.883	106.579	106.620	-0.041
<b>3047</b>	736050.480	3596725.680	94.441	94.550	-0.109
<b>3048</b>	738347.751	3559310.954	92.251	92.310	-0.059
<b>3049</b>	724037.574	3564539.753	106.438	106.500	-0.062
<b>3050</b>	747866.782	3554473.460	121.626	121.610	0.016
<b>3051</b>	742820.318	3552934.695	102.773	102.770	0.003
<b>3052</b>	756650.231	3550591.996	94.123	94.140	-0.017
<b>3053</b>	750122.454	3567613.767	135.485	135.410	0.075
<b>3054</b>	735331.603	3589858.478	80.160	80.210	-0.050
<b>3055</b>	738632.212	3583497.315	63.890	63.950	-0.060
<b>3056</b>	749633.838	3581871.476	101.643	101.550	0.093
<b>3057</b>	746759.331	3593488.945	84.894	84.960	-0.066
<b>3058</b>	757408.441	3597001.177	75.206	75.280	-0.074
<b>3059</b>	760588.123	3586645.248	105.176	105.230	-0.054
<b>3060</b>	752973.037	3592262.292	70.679	70.700	-0.021
<b>3061</b>	744164.641	3588351.117	95.452	95.530	-0.078
<b>3062</b>	767952.046	3581221.124	88.282	88.310	-0.028
<b>3063</b>	759261.035	3579180.627	99.288	99.220	0.068
<b>3064</b>	762443.707	3571469.393	100.209	100.180	0.029
<b>3065</b>	759685.655	3563636.079	79.657	79.910	-0.253
<b>3066</b>	684311.460	3443001.365	115.665	115.780	-0.115
<b>3067</b>	700165.714	3460370.634	127.221	127.260	-0.039
<b>3068</b>	729591.503	3449707.600	130.804	130.880	-0.076
<b>3069</b>	716373.470	3464148.076	134.462	134.500	-0.038
<b>3070</b>	663603.927	3476075.430	59.687	59.830	-0.143
<b>3071A</b>	678947.011	3473384.100	42.707	42.720	-0.013
<b>3072</b>	677280.435	3491387.522	117.043	117.110	-0.067
<b>3073</b>	693024.198	3505017.644	145.363	145.400	-0.037
<b>3074</b>	694719.288	3512473.366	95.082	95.130	-0.048
<b>3075</b>	680696.829	3518567.464	48.307	48.330	-0.023
<b>3076</b>	670295.340	3526483.925	24.889	24.890	-0.001
<b>3077</b>	696013.838	3549277.376	39.171	39.130	0.041
<b>3078</b>	710493.234	3551227.209	102.631	102.640	-0.009
<b>3079</b>	702562.412	3569732.166	77.350	77.420	-0.070
<b>3080</b>	706023.602	3564096.586	48.972	48.990	-0.018
<b>3081</b>	708545.312	3588549.641	100.485	100.530	-0.045
<b>3082</b>	716803.448	3586933.044	88.848	89.030	-0.182
<b>3083</b>	723720.652	3592543.530	77.306	77.480	-0.174
<b>3084</b>	732222.380	3586731.462	87.868	87.950	-0.082
<b>3085</b>	732576.005	3594472.954	68.148	68.150	-0.002

<b>3086</b>	725862.813	3555438.977	93.971	94.020	-0.049
<b>3087</b>	747401.130	3561913.259	119.096	119.080	0.016
<b>3088</b>	744221.954	3575863.555	82.770	82.830	-0.060
<b>3089</b>	755745.938	3573935.386	135.127	135.150	-0.023
<b>3090</b>	731657.679	3580770.611	69.167	69.250	-0.083

## VERTICAL ACCURACY CONCLUSIONS

Vegetated Vertical Accuracy (VVA) Tested 0.168 Meters at the 95th percentile reported using National Digital Elevation Program (NDEP)/ASPRS Guidelines and tested against the DEM using 90 VVA points. VVA Errors larger than 95th percentile include:

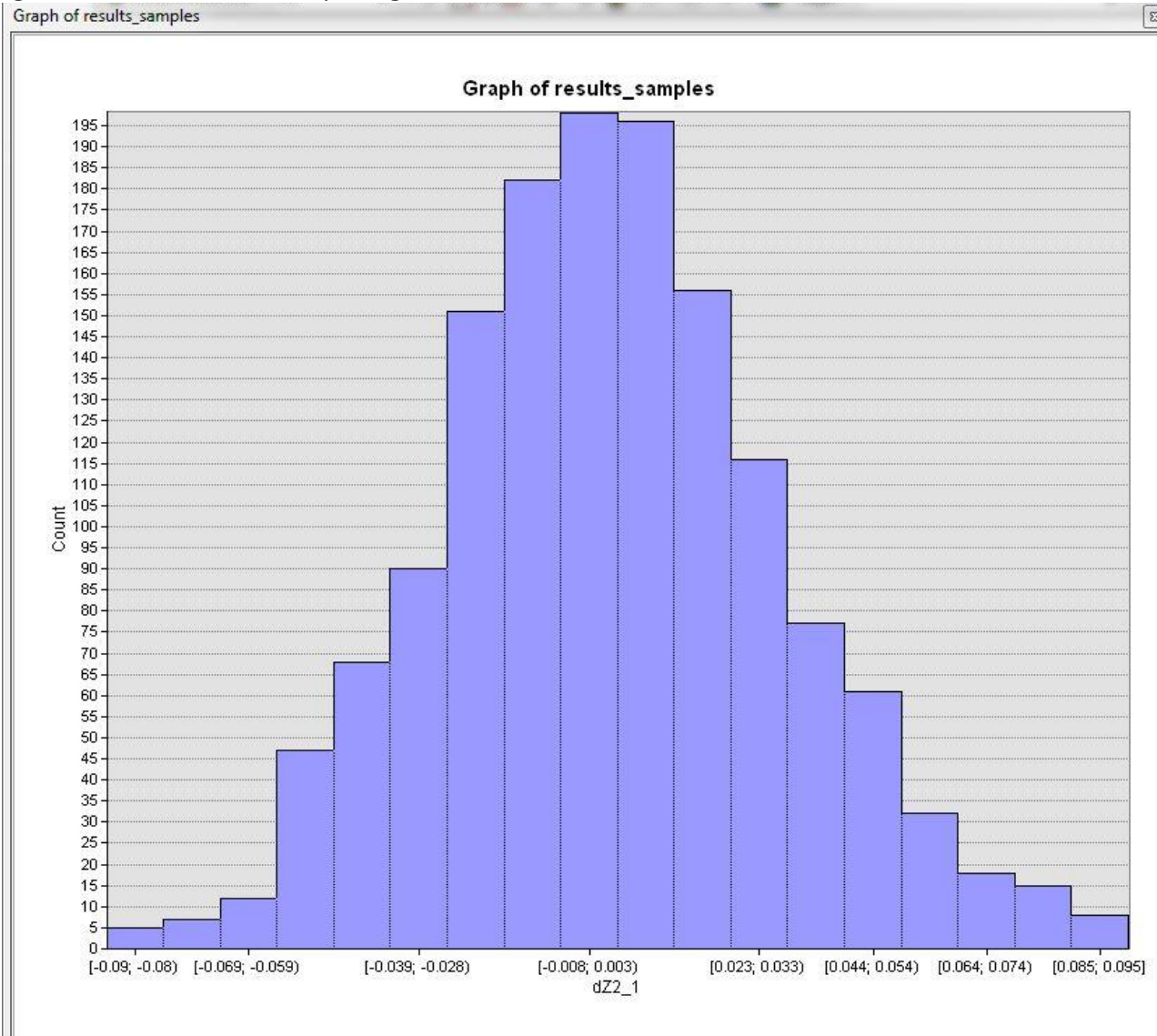
Point 3011, Easting 675825.520, Northing 3459581.594, Z-Error 0.217 Meters

Point 3065, Easting 759685.655, Northing 3563636.079, Z-Error 0.253 Meters

Point 3082, Easting 716803.448, Northing 3586933.044, Z-Error 0.182 Meters


Point 3083, Easting 723720.652, Northing 3592543.530, Z-Error 0.174 Meters

Figure 5.1: Lidar Relative Accuracy Histogram



RELATIVE ACCURACY ASSESSMENT AND CONCLUSION

Relative accuracy also known as "between swath" accuracy was tested through a series of well distributed flight line overlap locations. The relative accuracy for the Mississippi NRCS FY16 Lidar measured at 0.030 Meters RMSDz.

Approved by:	Name	Signature	Date
Associate Member, Lidar Specialist Certified Photogrammetrist #1381	Qian Xiao		March 2017

## Section 6: Flight Logs

Flight logs for the project are shown on the following pages:



**OPERATORS FLIGHT LOG**

MISSION: S 20160118 - 145231 DATE: 1/18/2016 LEICA ALS80 SN 8227

PILOT: Devin Moady OPERATOR: Gary Long AIRCRAFT: N208NR

PROJECT NUMBER	LINE NO. & Hdg	GND SPEED (KTS)	FREQ Hz	SCAN ANGLE	PRF kHz	FIXED GAIN	ALT (m)	TIME		REMARKS
								START	STOP	
28212 - USGS -MS								15:46	15:46	MSJ Keel MS VC clouded over
AOL MSBU CoRS							2000	15:45	15:47	5 turn before CoRS to wake up FMU
							1770	15:52	15:57	Flavour of MSBU CoRS Pre-line Figure 8
	954 180°	168	39	40	269		2000	16:00	16:08	
	953 0°	156					2000	16:09	16:18	
	952 180°	163					2000	16:19	16:27	
	951 0°	146					2000	16:28	16:37	
	950 180°	166					1950	16:38	16:46	
	949 0°	155					2015	16:47	16:56	
	948 180°	165					1965	16:57	17:06	
	947 0°	150					1990	17:07	17:16	
	946 180°	157					1940	17:23	17:37	
	945 0°	160					2000	17:38	17:53	
	944 180°	157					1960	17:54	18:08	
	XFE	146					2014	18:15	18:18	Using east end of 999 sq. X FIE
STATUS	TOTAL LINES	FLOWN	LEFT	SITE	AIRCRAFT	FERRY	STATIC	START	STOP	NOTES:
MSBU AOL	55	11	44	2.3		1.3	1755	18:56		3688.6 - 3692.2 15:10HP 18:47down
							WN	Clear in South		KHSK → KHEZ for refuel No Backup Base Available

AERO-METRIC, INC. N.6216 Resource Drive Sheboygan Falls, WI. 53085 PHONE: 920-467-2655 FAX: 888-253-6695 E-Mail: amphoto@aerometric.com























Woolpert											
Leica LIDAR		MM/DD/YYYY	Day of Year	Project #	Phase #	Project Name					
User/Alt		02/05/16	035	076268	02	SW Mississippi USGS					
Altitude		N 7079F		264.8		Local Start Time		ZULU Start Time		Date	
Pilot		Sensor Type		ICM355 FHD		Local End Time		Zulu End Time		Woolpert	
Wind Dir/Speed		Visibility		Ceiling		Cloud Cover %		Temp		Dew Point	
—		710						7		-4	
Scan Angle (FOV)		Scan Frequency (Hz)		Pulse Rate (kHz)		Laser Power %		Fixed Gain		Mode	
40		50		272		100				Single	
Air Speed		AGL		MSL		Waveform Used		Waveform Mode		Pre-Trigger Dist.	
150		Kts 6,500		Ft 6,500		Rt 3053		@		NS	
Line #		Dir.		Line Start Time		Line End Time		Time On Line		SVs	
Test		n/a						n/a		n/a	
↓ Times entered are Zulu / GMT ↓										GPS Began Logging At: 9:06am	
										Verify S-Turns Before Mission Yes <input checked="" type="checkbox"/> No <input type="checkbox"/>	
160	S	15:57	16:13	0:00:00	20	0.7	1.3				
159	N	16:16	16:32	0:00:00	21	0.6	1.1				
158	S	16:36	16:51	0:00:00	22	0.5	1.1				
157	N	16:55	17:10	0:00:00	21	0.6	1.1	Cloud			
156	S	17:14	17:29	0:00:00	22	0.5	1.0				
155	N	17:32	17:47	0:00:00	22	0.5	1.0				
154	S	17:51	18:07	0:00:00	19	0.6	1.1				
153	N	18:09	18:24	0:00:00	18	0.6	1.1				
152	S	18:28	18:43	0:00:00	17	0.7	1.2	Flood.ing?			
151	N	18:47	19:02	0:00:00	17	0.7	1.1	Low Return over Lake			
150	S	19:05	19:21	0:00:00	18	0.6	1.0	Low Return over Lake			
149	N	19:24	19:38	0:00:00	16	0.7	1.2				
148	S	19:42	19:57	0:00:00	16	0.7	1.2				
147	N	20:00	20:15	0:00:00	17	0.6	1.1				
146	S	20:19	20:34	0:00:00	15	0.7	1.3				
145	N	20:37	20:52	0:00:00	16	0.7	1.2				
144	S	20:55	21:11	0:00:00	15	0.7	1.2				
143	N	21:14	21:28	0:00:00	14	0.8	1.4				
142	S	21:32	21:47	0:00:00	15	0.7	1.1				
141	N	21:50	22:05	0:00:00	15	0.7	1.2				
140	S	22:08	22:23	0:00:00	15	0.7	1.1	Low Return over Lake			
139	N	22:31	22:46	0:00:00	16	0.7	1.2	Smoke			
				0:00:00							
				0:00:00							
				0:00:00							
				0:00:00							
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				0:00:00							
				0:00:00							
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				0:00:00							
↑ Times entered are Zulu / GMT ↑										Page 1	
Additional Comments:										Verify S-Turns After Mission Yes <input type="checkbox"/> No <input type="checkbox"/>	
										Drive #	

### Woolpert

Leica LIDAR		MM/DD/YYYY	Day of Year	Project #	Phase #	Project Name		
		02/06/16	036	076268	02	SW Mississippi USGS 2016		
Operator		Aircraft			HOURS START		ZULU START TIME	
Pilot		Sensor Type			HOURS END		ZULU END TIME	
		ALS 80 / 18170			275.7		5:58 20:10 23:58	
Wind Dir/Speed	Visibility	Ceiling	Cloud Cover %	Temp	Dew Point	Pressure	Haze/Fire/Cloud	Departing
360/10	10	1200	—	13	-5	3026		HEZ
Scan Angle (FOV)	Scan Frequency (Hz)	Pulse Rate (kHz)	Laser Power %	Fixed Gain	Mode		Threshold Values	
40	50	272	100		Gain - Course/Up	Single	A	
Air Speed	AGL	MSL	Waveform Used	Waveform Mode		Gain - Fine/Down	Multi	B
150	6,500	6,500	@				NS	R
Line #	Dir.	Line Start Time	Line End Time	Time On Line	SV's	HDOP	PDOP	Line Notes/Comments
Test	n/a			n/a	n/a	n/a	n/a	GPS Began Logging At: 11:11
* Times entered are Zulu / GMT *								
198	W	20:41	20:52	0:00:00	16	0.7	1.2	
197	W	20:56	21:08	0:00:00	14	0.8	1.21	
138	S	21:24	21:40	0:00:00	15	0.7	1.2	Low Return over R. ves
137	N	21:42	21:58	0:00:00	15	0.7	1.2	
136	S	22:00	22:15	0:00:00	16	0.7	1.1	
135	N	22:18	22:33	0:00:00	16	0.7	1.2	Water in fields
134	S	22:36	22:51	0:00:00	16	0.7	1.3	Water in fields
133	N	22:54	23:08	0:00:00	18	0.6	1.1	
107	E	23:12	23:26	0:00:00	18	0.6	1.1	
106	W	23:29	23:42	0:00:00	17	0.6	1.2	Low Return over water
				0:00:00				
				0:00:00				
				0:00:00				
				0:00:00				
				0:00:00				
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↑ Times entered are Zulu / GMT ↑		Page			1		Verify S-Turns After Mission Yes <input checked="" type="checkbox"/> No	
Additional Comments: Lots of flood still along the mississippi lines 132-109								Drive #

Woolpert																
Leica LIDAR		MM/DD/YYYY	Day of Year	Project #	Phase #	Project Name										
		02/07/16		076268	02	SW M:55:55:PP; USGS 2016										
Starbucks		N 7079 F		275.7		9:47		15:47	Woolpert							
Pilot		Sensor Type		282.8		5:06		23:06	Woolpert							
Wind Dir/Speed	Visibility	Ceiling	Cloud Cover %	Temp	Dew Point	Pressure		Haze/Fire/Cloud	Departing	ARRIVING						
350/4	+10	12,000		9	1	30.31				ARRIVING						
Scan Angle (FOV)	Scan Frequency (Hz)	Pulse Rate (kHz)	Laser Power %	Fixed Gain	Gain - Course/Up	Gain - Fine/Down	Mode	Threshold Values								
40	50	272	100				Single	A								
Air Speed	AGL	MSL	Waveform Used	Waveform Mode	Pre-Trigger Dist.											
150	Kts 6,500	Ft 6,500	YES NO	@	NS	Ft										
Line #	Dir.	Line Start Time	Line End Time	Time On Line	SV's	HDOP	PDOP	Line Notes/Comments								
Test	n/a			n/a	n/a	n/a	n/a	GPS Began Logging At: 9:15								
↓ Times entered are Zulu / GMT ↓												Verify S-Turns Before Mission	Yes	No		
105	E	16:07	16:21	0:00:00	20	0.6	1.1									
104	W	16:24	16:39	0:00:00	21	0.6	1.1									
103	E	16:42	16:56	0:00:00	23	0.6	1.0									
102	W	16:59	17:13	0:00:00	21	0.6	1.1									
101	E	16:56	17:31	0:00:00	21	0.6	1.0									
100	W	17:34	17:48	0:00:00	21	0.6	1.1									
99	E	17:52	18:05	0:00:00	21	0.6	1.1									
98	W	18:08	18:23	0:00:00	19	0.7	1.2									
97	E	18:26	18:40	0:00:00	19	0.7	1.2									
96	W	18:43	18:57	0:00:00	19	0.7	1.1									
95	E	19:00	19:14	0:00:00	20	0.6	1.0									
94	W	19:17	19:31	0:00:00	17	0.6	1.2	Flooded fields								
93	E	19:34	19:48	0:00:00	17	0.7	1.2									
92	W	19:51	20:04	0:00:00	18	0.6	1.1									
91	E	20:07	20:21	0:00:00	16	0.7	1.3									
90	W	20:24	20:37	0:00:00	16	0.7	1.2									
89	E	20:40	20:53	0:00:00	15	0.7	1.3									
88	W	20:57	21:10	0:00:00	15	0.7	1.2									
87	E	21:13	21:26	0:00:00	15	0.7	1.2									
86	W	21:30	21:42	0:00:00	14	0.7	1.3									
85	E	21:46	21:59	0:00:00	15	0.7	1.2									
84	W	22:02	22:16	0:00:00	16	0.7	1.1									
83	E	22:19	22:32	0:00:00	17	0.7	1.3									
82	W	22:35	22:49	0:00:00	17	0.7	1.3									
				0:00:00												
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↑ Times entered are Zulu / GMT ↑												Page	1	Verify S-Turns After Mission	Yes	No
Additional Comments:												Drive #				

### Woolpert

Leica LIDAR		MM/DD/YEAR	Day of Year	Project #	Phase #	Project Name		
		02/08/16	038	076268	02	SW M. 35.55, pp. USGS		
Operator	Altitude	HUBS Start		Local Start Time	ZULU Start Time		Uprst	
	N7079F	287.8		9:53	15:53		Woolpert	
Pilot	Sensor Type	HUBS END		Local End Time	ZULU End Time		PIV	
	ALS 80/8170	287.6		2:50	20:50		Woolpert	
Wind Dir/Speed	Visibility	Calling	Cloud Cover %	Temp	Dew Point	Pressure	Haze/Fire/Cloud	
290 / 14	10	12,000		11	-4	3013		
Scan Angle (FOV)	Scan Frequency (Hz)	Pulse Rate (kHz)	Laser Power %	Fixed Gain		Mode		
40	50	272	100	Gain - Course/Up	Gain - Fine/Down	Single	Multi	
Air Speed	AGL	MSL	Waveform Used	Waveform Mode	Pre-Trigger Dist.			
150	Kts 6,500	Ft 6,500	Q		NS Ft			
Line #	Dir.	Line Start Time	Line End Time	Time On Line	SV's	HDOP	PDOP	
Test	n/a			n/a	n/a	n/a	n/a	
↑ Times entered are Zulu / GMT ↓							GPS Began Logging At:	9:00
Verify S-Turns Before Mission							Yes	<input checked="" type="checkbox"/> No
108	N	16:09	16:17	0:00:00	19	0.6	1.1	
81	E	16:28	16:41	0:00:00	20	0.6	1.1	
80	W	16:45	16:58	0:00:00	20	0.6	1.0	
79	E	17:01	17:14	0:00:00	20	0.6	1.0	
78	W	17:17	17:29	0:00:00	22	0.6	1.0	
77	E	17:33	17:43	0:00:00	20	0.6	1.1	
76	E	17:57	18:13	0:00:00	19	0.6	1.1	
65	S	18:27	18:39	0:00:00	18	0.8	1.3	
64	N	18:42	18:55	0:00:00	18	0.7	1.1	
63	S	18:58	19:10	0:00:00	19	0.6	1.0	
62	N	19:14	19:26	0:00:00	17	0.7	1.2	
61	S	19:29	19:42	0:00:00	17	0.7	1.2	
37	N	19:51	20:04	0:00:00	17	0.7	1.2	
38	S	20:07	20:21	0:00:00	16	0.7	1.3	
				0:00:00				
				0:00:00				
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				0:00:00				
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↑ Times entered are Zulu / GMT ↑				Page	1	Verify S-Turns After Mission	Yes	<input checked="" type="checkbox"/> No
Additional Comments:							Drive #	

Woolpert																				
Leica LIDAR		MM/DD/YYYY	Day of Year	Project #	Phase #	Project Name														
		2/11/16	042	076268	02	SW Mississippi USGS														
Operator		Aircraft		HOBBS Start		Local Start Time		ZULU Start Time		Date										
		N7079P		288.2		11:48		17:48		Woolpert										
Pilot		Sensor Type		HOBBS END		Local End Time		ZULU End Time		PID										
		ALS80 / R170		295.8		1:38		1:38		Woolpert										
Wind Dir/Speed	Visibility	Ceiling	Cloud Cover %	Temp	Dew Point	Pressure		Haze/Fire/Cloud		Departing	HEZ									
230/16	+10	1200	C	21	-8	3016				Arriving	HEZ									
Scan Angle (FOV)	Scan Frequency (Hz)	Pulse Rate (kHz)		Laser Power %		Fixed Gain		Mode		Threshold Values										
40	50	272		100		Gain - Course/Up		Single		A										
						Gain - Fine/Down		Multi		B										
Air Speed	AGL	MSL		Waveform Used		Waveform Mode		Pre-Trigger Dist.												
150	Kts	6,500	Ft	6,500	Yes	No	@		NS											
Line #	Dir.	Line Start Time	Line End Time	Time On Line	SV's	HDOP	PDOP	Line Notes/Comments												
Test	n/a			n/a	n/a	n/a	n/a	GPS Began Logging At: 11:21												
↓ Times entered are Zulu / GMT ↓											Verify S-Turns Before Mission		Yes	<input checked="" type="checkbox"/>	No	<input type="checkbox"/>				
39	N	18:33	18:47	0:00:00	18	0.6	1.1													
40	S	18:51	19:04	0:00:00	18	0.6	1.0													
41	N	19:07	19:21	0:00:00	16	0.7	1.2													
42	S	19:25	19:40	0:00:00	17	0.6	1.1													
43	N	19:43	19:59	0:00:00	16	0.7	1.2	Smoke												
44	S	20:02	20:18	0:00:00	16	0.7	1.2	Smoke												
45	N	20:21	20:37	0:00:00	16	0.7	1.1													
46	S	20:40	20:56	0:00:00	15	0.7	1.2	Smoke												
47	N	20:59	21:16	0:00:00	15	0.7	1.2													
48	S	21:19	21:35	0:00:00	16	0.7	1.2													
49	N	21:38	21:54	0:00:00	16	0.7	1.2													
50	S	21:58	22:11	0:00:00	16	0.7	1.2													
51	N	22:15	22:27	0:00:00	16	0.7	1.3	Smoke												
52	S	22:30	22:42	0:00:00	17	0.6	1.2													
53	N	22:44	22:57	0:00:00	19	0.6	1.1													
54	S	22:59	23:11	0:00:00	20	0.6	1.1													
55	N	23:14	23:27	0:00:00	17	0.6	1.4													
56	S	23:30	23:42	0:00:00	17	0.6	1.4													
57	N	23:45	23:57	0:00:00	18	0.6	1.3													
58	S	00:00	00:12	0:00:00	17	0.6	1.2													
59	N	00:15	00:27	0:00:00	17	0.6	1.2													
60	S	00:30	00:42	0:00:00	17	0.6	1.3													
66	N	00:45	00:57	0:00:00	18	0.6	1.2													
				0:00:00																
				0:00:00																
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				0:00:00																
↑ Times entered are Zulu / GMT ↑											Page		1		Verify S-Turns After Mission		Yes	<input type="checkbox"/>	No	<input type="checkbox"/>
Additional Comments:											Drive #									
39-60, 66																				

## Woolpert

<b>Leica LIDAR</b>		MM/DD/YEAR	Day of Year	Project #	Phase #	Project Name		
		02/12/16	044	076288	02	SW Mississippi USGS		
Operator	Aircraft	Altitude	HOBS Start	Local Start Time	Zulu Start Time	Base		
	N7079F	2958	2958	10:45	15:45	Woolpert		
Pilot	Sensor Type	HOBS END	Local End Time	Zulu End Time	File #			
	ALS 80/8170	299.8	1:56	19:56	Woolpert			
Wind Dir/Speed	Visibility	Ceiling	Cloud Cover %	Temp	Dew Point	Pressure	Haze/Fire/Cloud	Departing
030/12	710	12,000		8	-3	3049		HEZ
								Arriving
								HEZ
Scan Angle (FOV)	Scan Frequency (Hz)	Pulse Rate (kHz)	Laser Power %	Fixed Gain	Mode	Threshold Values		
40	50	272	100		Single	A		
				Gain - Course/Up	Multi	B		
				Gain - Fine/Down				
Air Speed	AGL	MSL	Waveform Used		Waveform Mode	Pre-Trigger Dist.		
150	Kts	6,500	6,500	Yes	@	NS	Ft	
Line #	Dir.	Line Start Time	Line End Time	Time On Line	SVs	HDOP	PDOP	Line Notes/Comments
Test	n/a			n/a	n/a	n/a	n/a	
↓ Times entered are Zulu / GMT ↓								GPS Began Logging At: 9:30
161	S	16:05	16:20	0:00:00	21	0.5	1.0	
185	N	16:27	16:29	0:00:00	21	0.6	1.1	
176	N			0:00:00				Missed start
176	N	16:37	16:40	0:00:00	21	0.6	1.1	
192	S	16:48	16:51	0:00:00	20	0.6	1.1	
193	N	16:58	17:02	0:00:00	22	0.5	1.0	Lateral deviation out of limits
	Re Alus	193		0:00:00				Image Data stopped recording
193	S	17:11	17:15	0:00:00	22	0.5	1.0	
37	S	17:43	17:56	0:00:00	18	0.7	1.2	
38	N	17:59	18:12	0:00:00	18	0.7	1.2	
61	S	18:18	18:32	0:00:00	18	0.7	1.1	
62	N	18:35	18:47	0:00:00	17	0.6	1.0	
63	S	18:49	19:01	0:00:00	17	0.6	1.0	
64	N	19:05	19:17	0:00:00	15	0.7	1.3	
				0:00:00				
				0:00:00				
				0:00:00				
				0:00:00				
				0:00:00				
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				0:00:00				
↑ Times entered are Zulu / GMT ↑								Page 1
Additional Comments:								Verify S-Turns After Mission Yes No
Re flight 193 WP 1-12   185 WP 46-52   Full line 192 WP 1-15   176 WP 24-30   37 62 167 38 63 61 64								Drive #

<b>Woolpert</b>												
Leica LIDAR		MM/DD/YEAR	Day of Year	Project #	Phase #	Project Name						
		1/8/2017	8	77025	2	USGS MISSISSIPPI, Natchez						
Operator	Aircraft	ROBBS Start		Local Start Time (MM)		ZULU Start Time (MM)		Base				
Linville	N111SD	339.7		11:11:00		17:11:00		WOOLPERT PIN				
Pilot	Sensor Type	344.8		4:38:00		22:38:00		PID				
LaROCQUE		OTHER										
Wind Dir/Speed	Visibility	Ceiling	Cloud Cover %	Temp	Dew Point	Pressure		Haze/Fire/Cloud		Departing	KHEZ	
090@4	10	clr	0	1	-11	30.76				Arriving	KHEZ	
Scan Angle (FOV)	Scan Frequency (Hz)	Pulse Rate (kHz)		Laser Power %		Fixed Gain		X	Mode		Threshold Values	
40	50	272		100		Gain - Course/Up		Single		A	PreSet	
		Gain - Fine/Down				Multi				B	PreSet	
Air Speed	AGL		MSL	Waveform Used			Waveform Mode			Pre-Trigger Dist.		
150	6500		agl	6,500			@			NS		
Line #	Dir.	Line Start Time	Line End Time	Time On Line	SV's	HDOP	PDOP	Line Notes/Comments				
Test	n/a			n/a	n/a	n/a	n/a	Base GPS Began Logging At:		11:00:00		
									Figure 8-Turns Before Mission			Yes X No
109	179.5	17:48:39	17:49:36		23	0.6	1.1					
110	179.3	17:54:48	18:01:24		21	0.6	1.1					
111	359.3	18:04:44	18:11:16		22	0.6	1.1					
112	179.4	18:14:32	18:21:17		25	0.6	1.1					
113	359.4	18:24:39	18:31:08		23	0.6	1					
114	179.4	18:34:10	18:40:48		22	0.6	1.1					
115	359.4	18:44:21	18:54:27		22	0.6	1.1					
116	179.4	18:57:50	19:08:24		22	0.6	1.1					
117	359.4	19:11:54	19:22:14		19	0.7	1.3					
118	179.5	19:25:35	19:36:23		20	0.7	1.3					
119	359.4	19:39:43	19:50:10		21	0.6	1.1					
120	179.5	19:55:19	20:08:28		20	0.6	1.1					
121	359.5	20:11:43	20:26:46		21	0.6	1.1					
122	179.5	20:30:12	20:46:19		20	0.7	1.3					
123	359.5	20:49:32	21:04:41		19	0.7	1.3					
124	179.6	21:08:04	21:23:54		19	0.7	1.3					
125	359.5	21:27:26	21:42:30		19	0.7	1.3					
126	179.6	21:45:02	22:00:57		19	0.7	1.2					
127	359.5	22:04:26	22:19:16		17	0.8	1.4					

Woolpert													
Leica LIDAR		MM/DD/YEAR	Day of Year	Project #	Phase #	Project Name							
		1/9/2017	9	77025	2	USGS MISSISSIPPI, Natchez							
Operator		Aircraft		HOBS Start		Local Start Time IMU		ZULU Start Time IMU		BASE			
Linville		N1115D		344.8		4:49:00		22:49:00		WOOLPERT PIN			
Pilot		Sensor Type								PID			
LaROCQUE		OTHER		346.8		7:00:00		1:00:00					
Wind Dir/Speed	Visibility	Ceiling	Cloud Cover %	Temp	Dew Point	Pressure		Haze/Fire/Cloud		Departing	KHEZ		
160@11g20	10	clr	0	14	6	30.37				Arriving	KHEZ		
Scan Angle (FOV)	Scan Frequency (Hz)		Pulse Rate (kHz)		Laser Power %		Fixed Gain		X	Mode	Threshold Values		
40	50		272		100		Gain - Course/Up			Single	A		PreSet
						Gain - Fine/Down				Multi	B		PreSet
Air Speed	AGL		MSL		Waveform Used		Waveform Mode		Pre-Trigger Dist.				
150	6500		agl 6,500		Ft Yes No X		@ NS		Ft				
Line #	Dir.	Line Start Time	Line End Time	Time On Line	SV's	HDOP	PDOP	Line Notes/Comments					
Test	n/a			n/a	n/a	n/a	n/a	Base GPS Began Logging At:		4:40:00			
										Figure 8-Turns Before Mission <input checked="" type="checkbox"/> Yes <input type="checkbox"/> No			
128	179.6	23:09:31	23:24:28		18	0.7	1.2	could not capture ladt 5 miles of line 128 due to clouds					
1	358.9	23:42:20	23:43:00		23	0.6	1.1	all flights are right at base of clouds					
2	179.0	23:46:54	23:47:53		23	0.6	1.1						
3	359.0	23:51:26	23:52:31		24	0.5	1.1						
4	179.0	23:57:30	23:59:53		24	0.5	1.1						
5	359.0	0:03:22	0:05:49		24	0.5	1.1						
6	359.0	0:13:56	0:21:10		21	0.6	1.2						
7	179.1	0:24:55	0:33:58		20	0.6	1.2						
9	230.4	0:39:47	0:41:39		19	0.6	1.3	Line 9 is an F flight					





Woolpert													
Leica LIDAR		MM/DD/YYYY	Day of Year	Project #	Phase #	Project Name							
		1/14/2017	14	76268	0.02	USGS Natchez, Mississippi							
Operator		Aircraft		HOBBSS Start		Local Start Time		ZULU Start Time		Case			
Justin Linville		N625SQ		351.6		9:11:00		15:11:00		woolpert pin			
Pilot		Sensor Type		HOBBSS END		Local End Time		Zulu End Time		PIB			
Ray Larocque		Leica 8170		355.5		1:23:00		19:23					
Wind Dir/Speed	Visibility	Ceiling	Cloud Cover %	Temp	Dew Point	Pressure		Haze/Fire/Cloud		Departing	KHEZ		
150@6kts	10sm		clear	17	15	30.45				Arriving	KHEZ		
Scan Angle (FOV)	Scan Frequency (Hz)		Pulse Rate (kHz)		Laser Power %		Fixed Gain	X	Mode	Threshold Values			
40	50		272		100%		Gain - Course/Up		Single	A			
							Gain - Fine/Down		Multi	B			
Air Speed	AGL		MSL		Waveform Used		Waveform Mode		Pre-Trigger Dist.				
150 kts	Kts	6500	Ft	6500	Ft	Yes	No	x	@	NS	Ft		
Line #	Dir.	Line Start Time	Line End Time	Time On Line	SV's	HDOP	PDOP	Line Notes/Comments					
Test	n/a			n/a	n/a	n/a	n/a	GPS Began Logging At:	8:47:00				
↓ Times entered are Zulu / GMT ↓										Verify S-Turns Before Mission		Yes	No
26	359.1	15:46:31	15:57:10		19	0.6	1.1						
27	179.3	16:00:26	16:10:57		20	0.6	1.1						
28	359.3	16:14:02	16:24:31		18	0.6	1.3						
29	179.3	16:27:34	16:37:33		18	0.7	1.3						
30	359.3	16:41:07	16:51:42		19	0.6	1.2						
31	179.4	16:54:57	17:05:17		20	0.6	1.1						
32	359.3	17:08:46	17:19:35		21	0.5	1.1						
33	179.4	17:22:54	17:33:26		22	0.6	1.1						
34	359.4	17:36:48	17:48:20		21	0.6	1.1						
35	179.4	17:51:47	18:03:11		23	0.6	1.1						
36	359.4	18:06:34	18:18:52		22	0.6	1.1						
8	179.3	18:29:22	18:30:32		24	0.6	1	Patch for clouds					
24	359.2	18:35:53	18:37:55		23	0.6	1	Patch for clouds					
25	179.3	18:40:27	18:41:24		21	0.7	1.2	Patch for clouds					
F	Flights												
6	181.0	18:56:01	18:57:11		22	0.7	1.2						
5	001.0	18:59:57	19:01:10		22	0.7	1.1						
↑ Times entered are Zulu / GMT ↑				Page		1		Verify S-Turns After Mission		Yes	No		
Additional Comments:										Drive #			
Notes: Patch flights 8, 24, and 25 for clouds. Two missions were flown this day. This is the first mission, labelled as Day014A													



Woolpert																	
Leica LIDAR		MM/DD/YEAR	Day of Year	Project #	Phase #	Project Name											
		1/15/2017	15	76268	0.02	USGS Natchez, Mississippi											
Operator		Aircraft		HOBBBS Start		Local Start Time		ZULU Start Time		Base							
Justin Linville		N6255Q		357.3		6:43:00		0:48:00		woolpert pin							
Pilot		Sensor Type		HOBBBS END		Local End Time		Zulu End Time		PID							
Ray Larocque		Leica 8170		359.7		9:33		03:26:00									
Wind Dir/Speed	Visibility	Ceiling	Cloud Cover %	Temp	Dew Point	Pressure		Haze/Fire/Cloud		Departing	KHEZ						
100@4kts	10sm		clear	18	14	30.13				Arriving	KHEZ						
Scan Angle (FOV)	Scan Frequency (Hz)	Pulse Rate (kHz)		Laser Power %		Fixed Gain		Mode		Threshold Values							
40	50	272		100%		Gain - Course/Up		Single		A							
						Gain - Fine/Down		Multi		B							
Air Speed	AGL	MSL		Waveform Used		Waveform Mode		Pre-Trigger Dist.									
150	Kts	6500	Ft	6500	Ft	Yes	No	X	@	NS	Ft						
Line #	Dir.	Line Start Time	Line End Time	Time On Line	SV's	HDOP	PDOP	Line Notes/Comments									
Test	n/a			n/a	n/a	n/a	n/a	GPS Began Logging At:		6:43 - 9:33							
↓ Times entered are Zulu / GMT ↓											Verify S-Turns Before Mission		Yes	No			
129	359.6	01:23:14	01:37:58		19	0.6	1.2										
130	179.6	01:41:16	01:56:53		19	0.6	1.3										
131	359.6	02:00:07	02:14:53		23	0.6	1										
132	179.6	02:18:12	02:33:31		22	0.6	1.1										
128	359.5	02:36:58	02:39:57		20	0.6	1.3										
7	001.5	02:55:29	02:56:11		21	0.6	1.1										
8	180.3	02:59:27	03:00:31		21	0.6	1.1										
↑ Times entered are Zulu / GMT ↑											Page		1	Verify S-Turns After Mission		Yes	No
Additional Comments:											Drive #						

## Section 7: Final Deliverables

The final lidar deliverables are listed below.

- LAS v1.4 classified point cloud
- LAS v1.4 raw unclassified point cloud flight line strips.
- Hydro Breaklines as ESRI shapefile
- Bridge Breaklines as ESRI shapefile
- Digital Elevation Model in ERDAS .IMG format
- 8-bit gray scale intensity images in .TIF format
- 0.3 meters contours
- Tile layout provided as ESRI shapefile
- Control Points provided as ESRI shapefile
- FGDC compliant metadata per product in XML format
- Lidar processing report in pdf format
- Survey report in pdf format