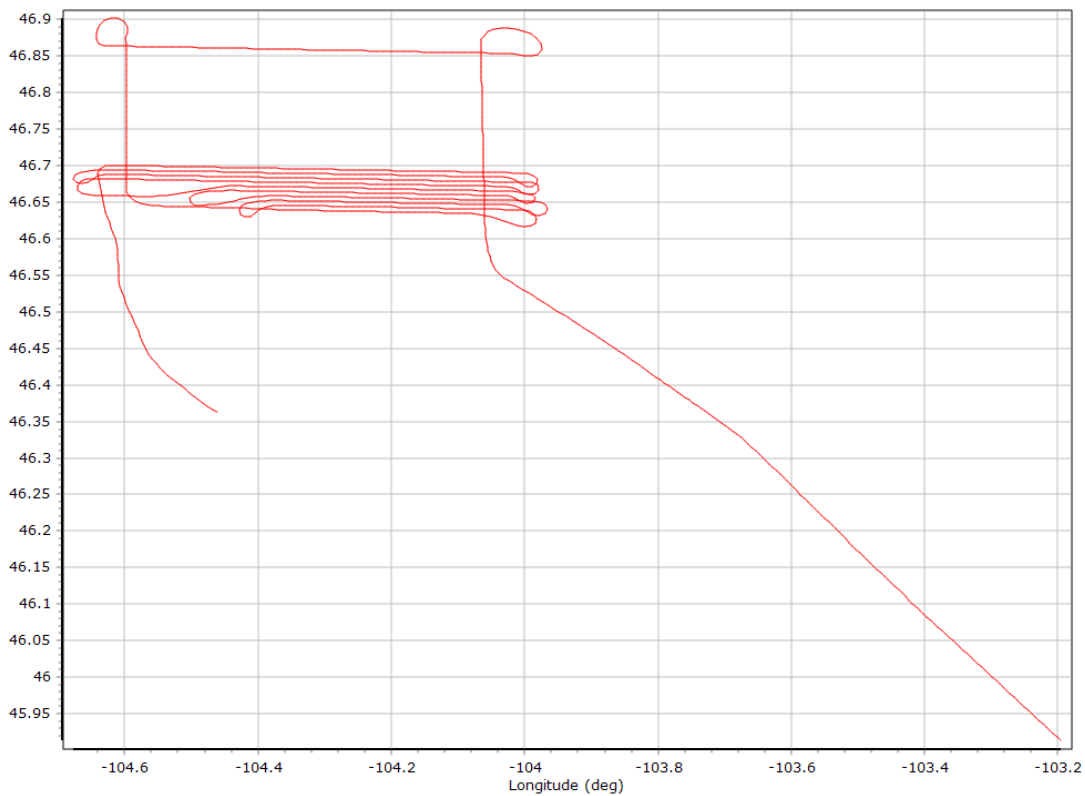
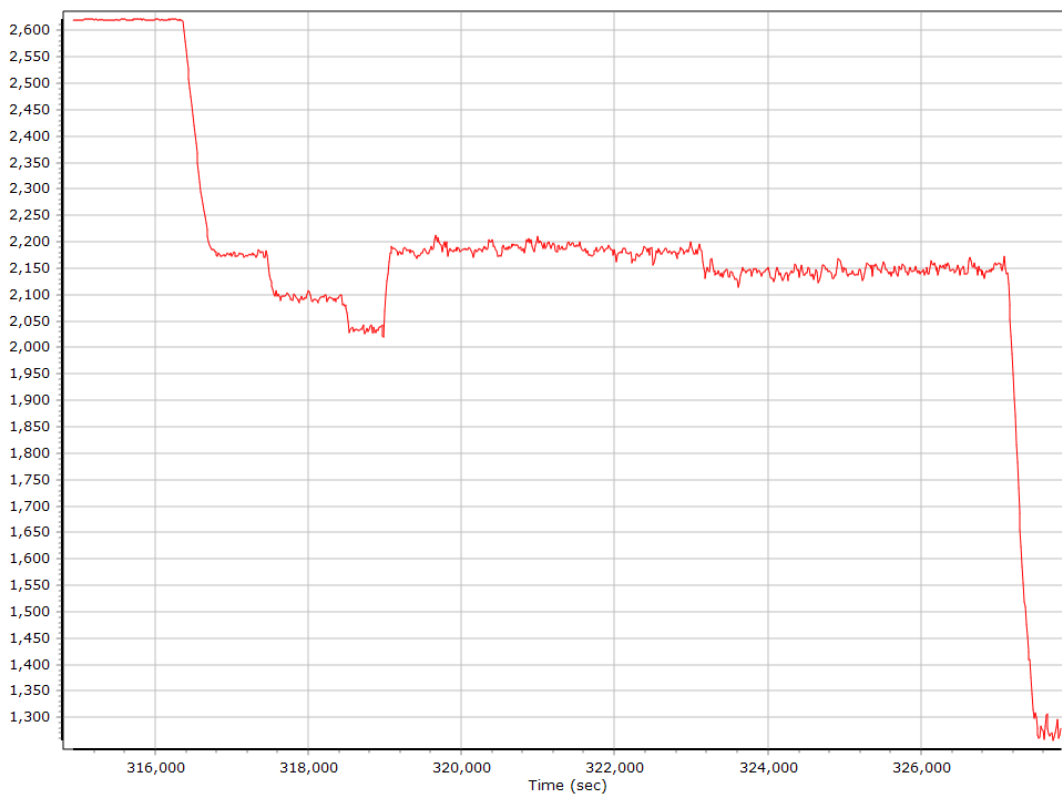


## Smoothed Trajectory Information

### Top View



### Altitude

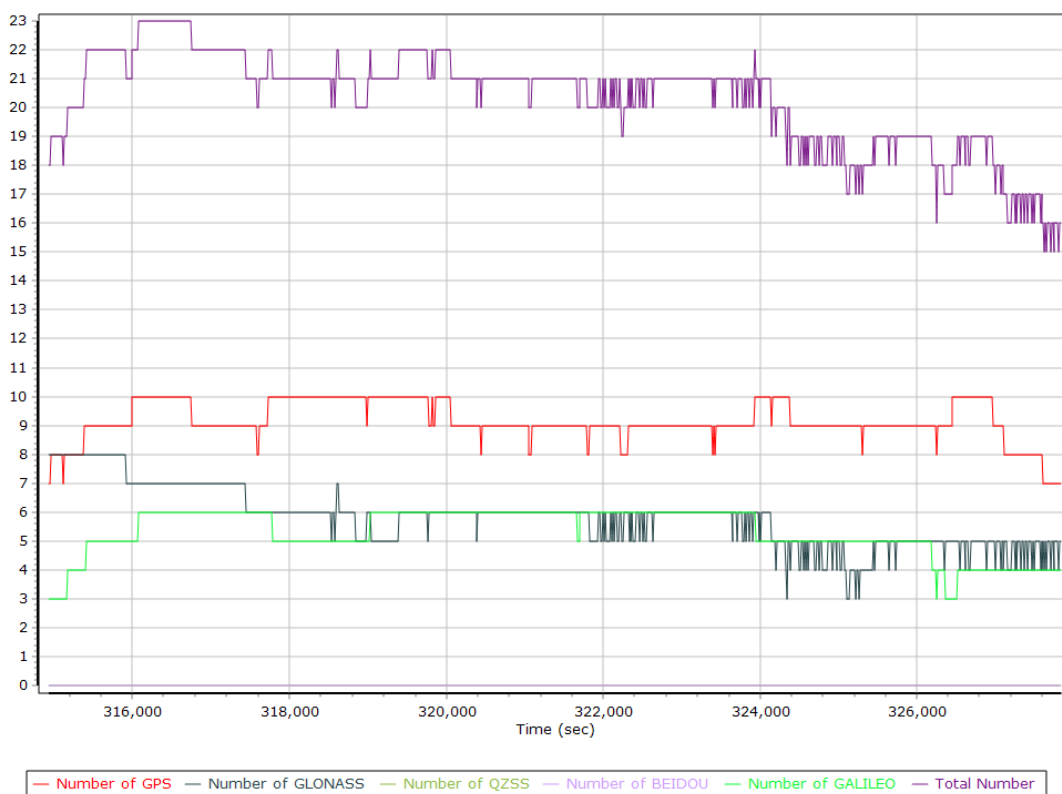


## GNSS QC

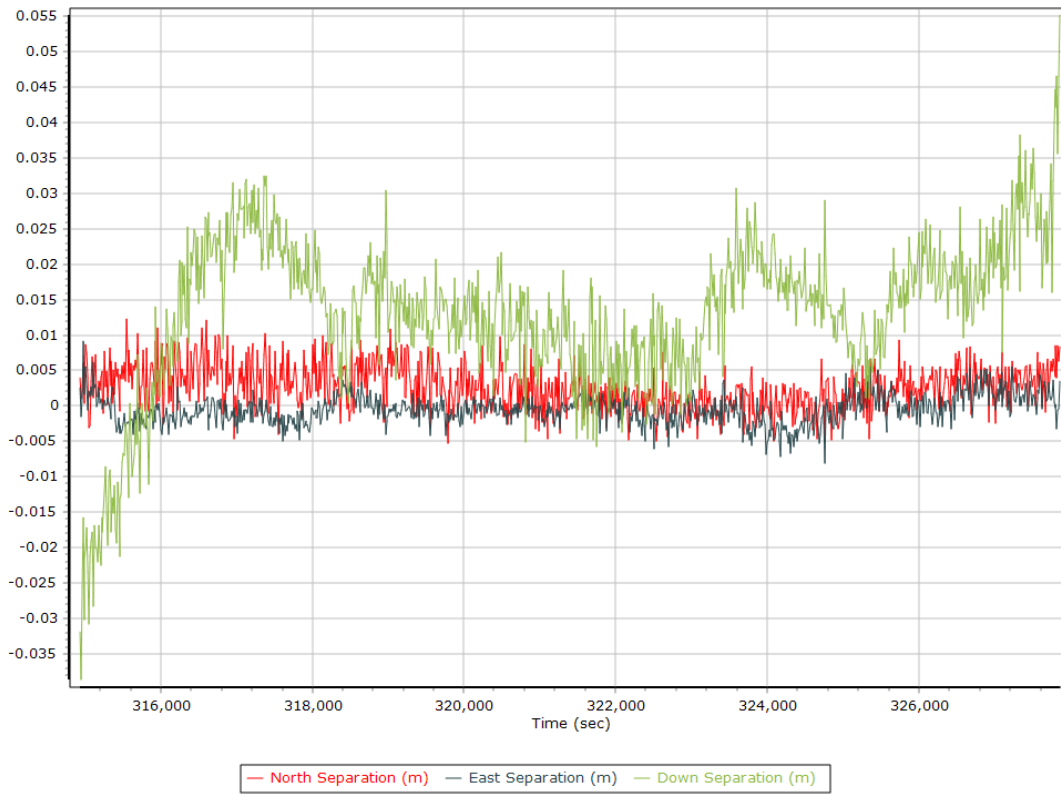
### GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	7	10	9
Number of GLONASS SV	3	8	6
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	0	0
Number of GALILEO SV	3	6	5
Total number of SV	15	23	20
PDOP	1.00	1.40	1.14
QC Solution Gaps	1.00	1.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	12965.00	0.00	3.00
Percentage	99.98	0.00	0.02

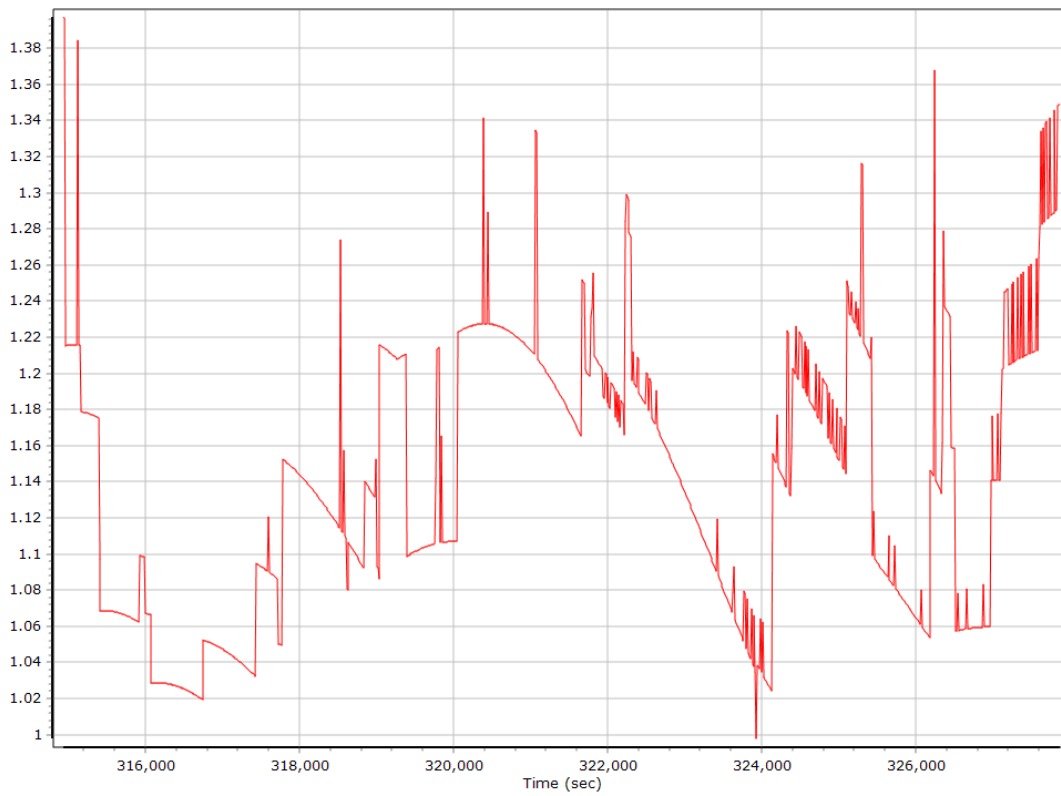
### Num SVs in solution



## Forward/Reverse Separation



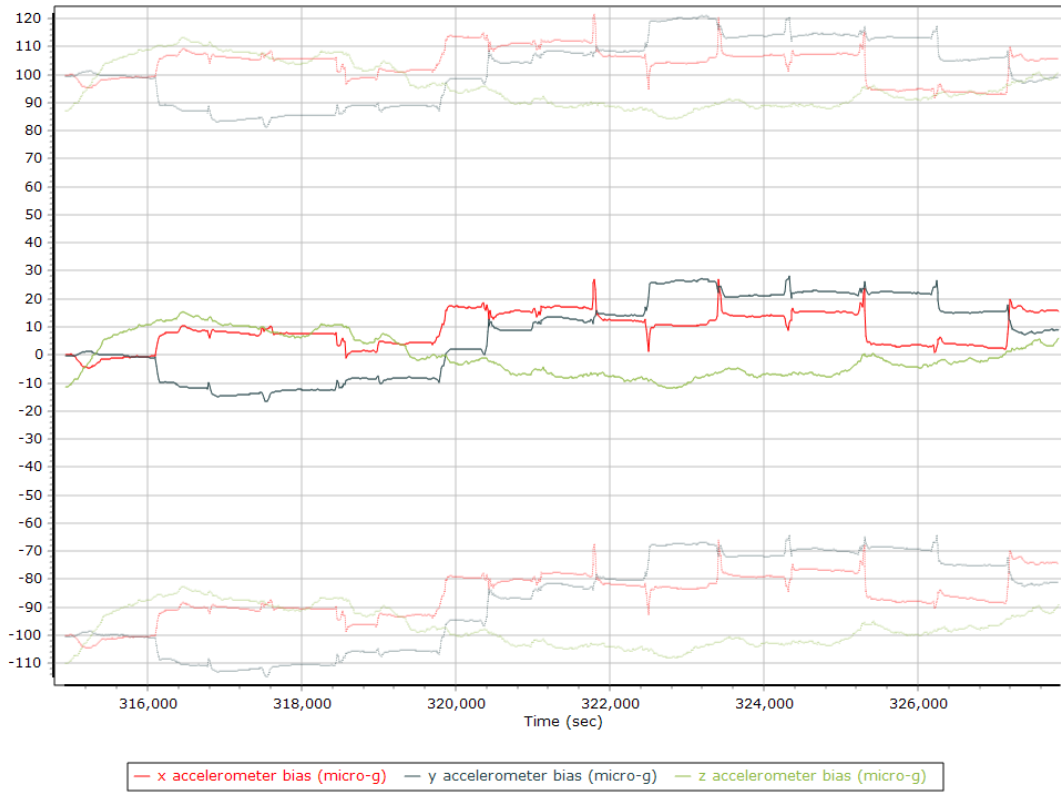
## PDOP



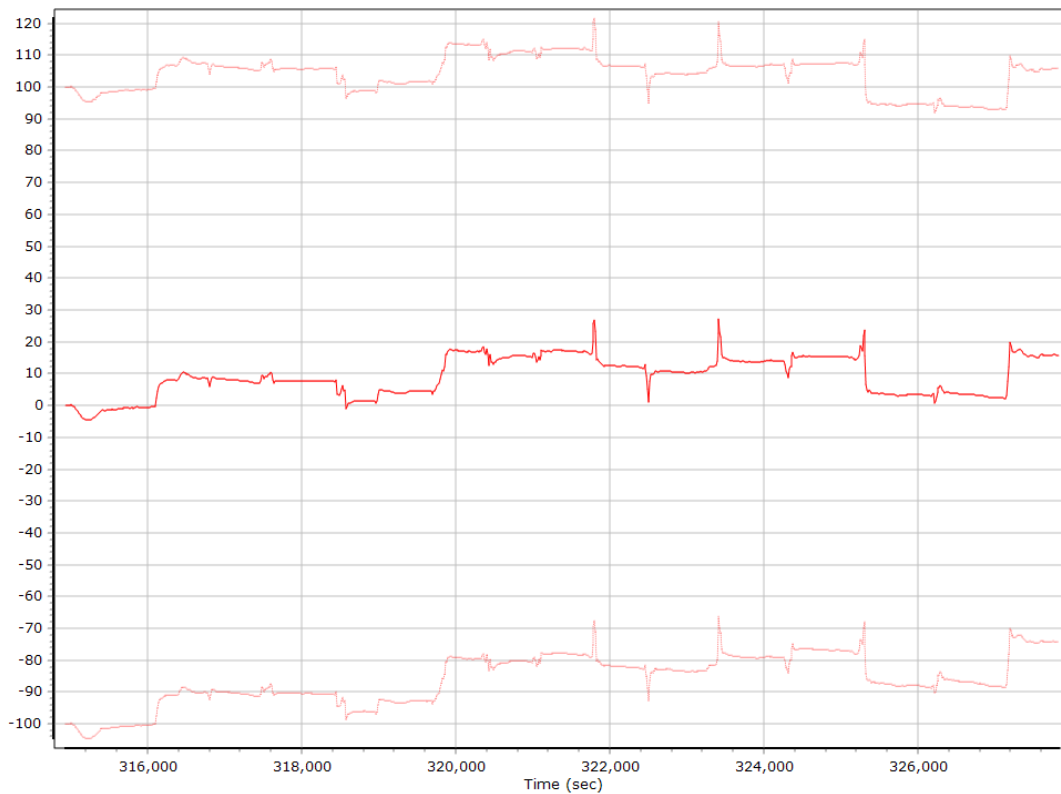
## IN-Fusion QC

### Forward Processed Estimated Errors, Reference Frame

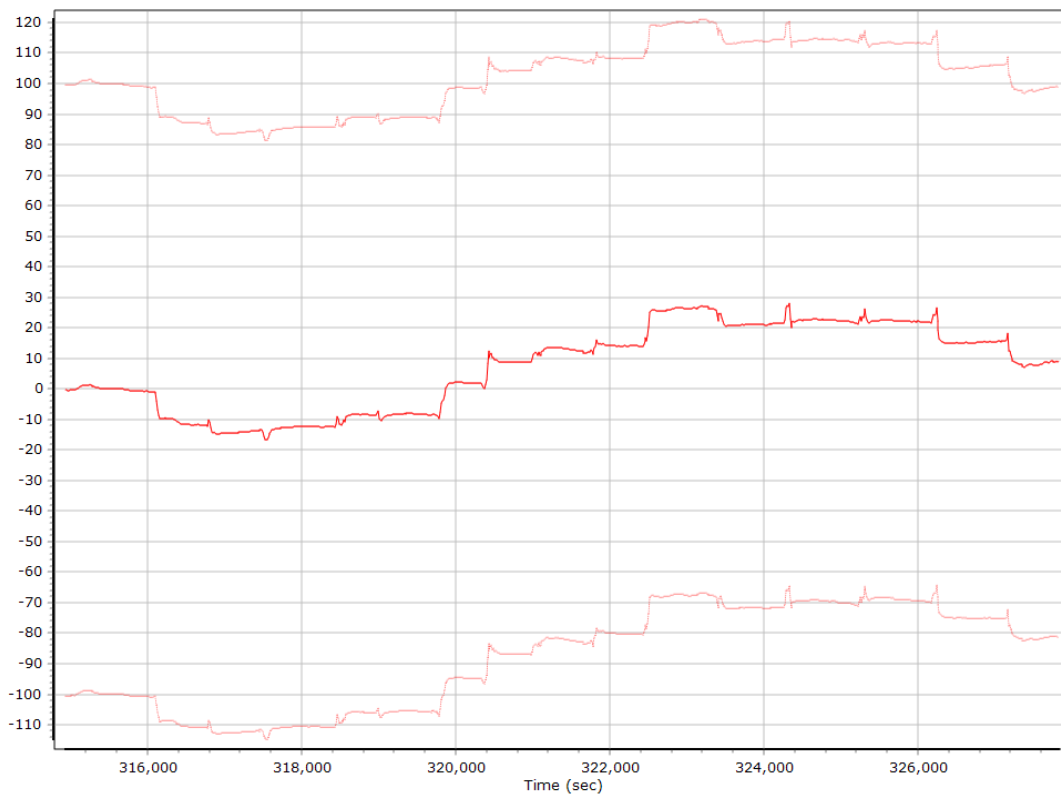
#### Accelerometer Bias (micro-g)



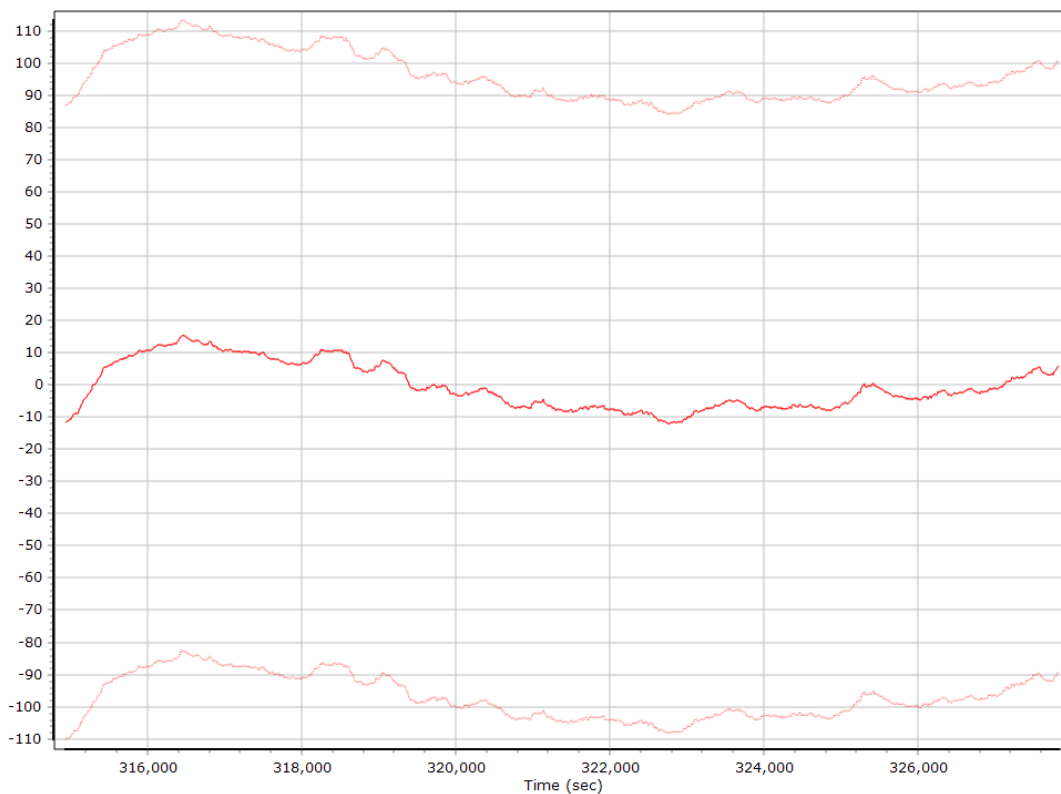
#### X Accelerometer Bias (micro-g)



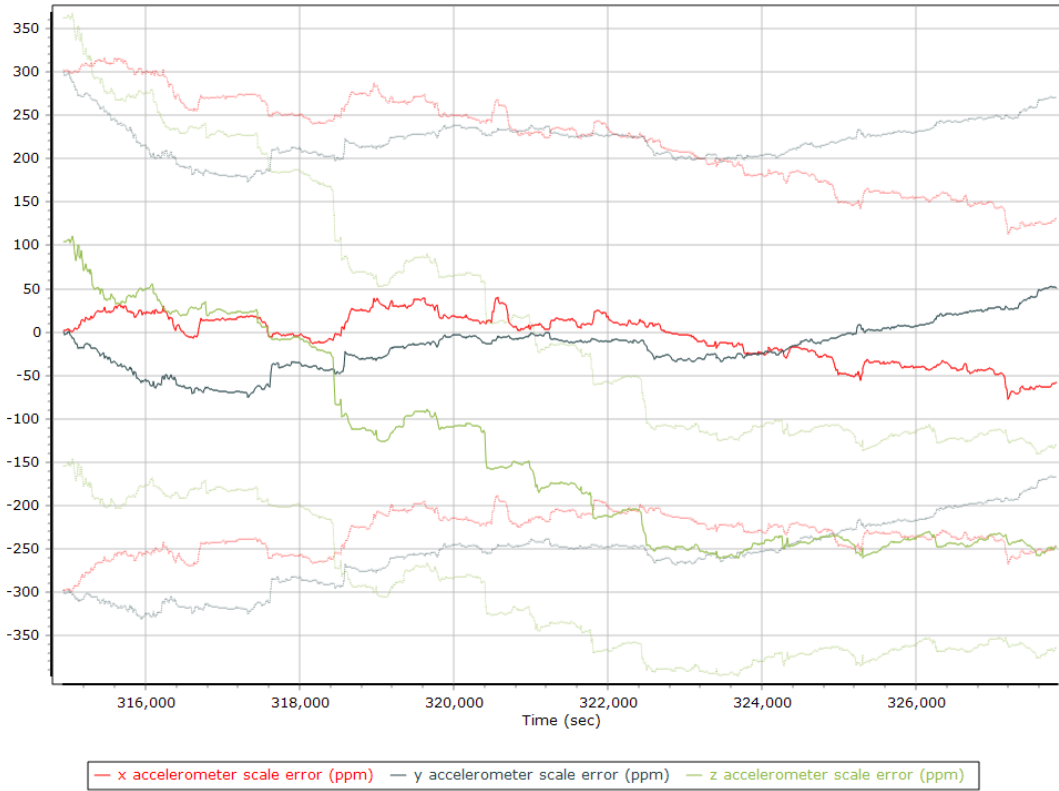
### Y Accelerometer Bias (micro-g)



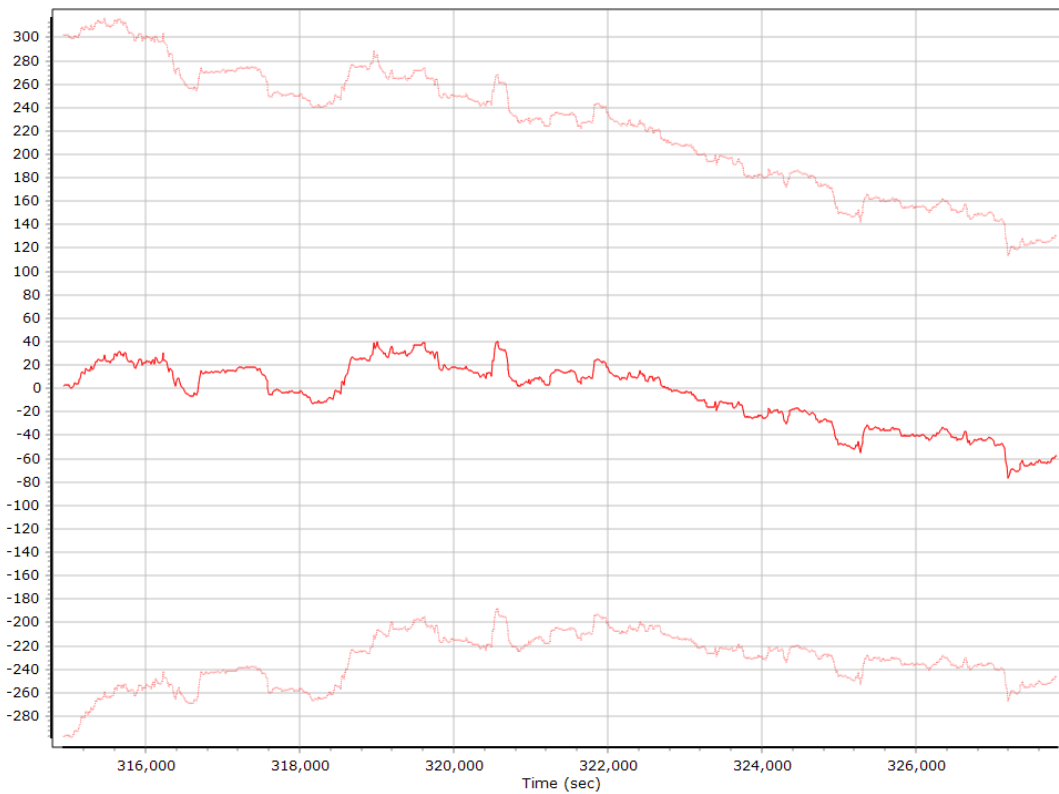
### Z Accelerometer Bias (micro-g)



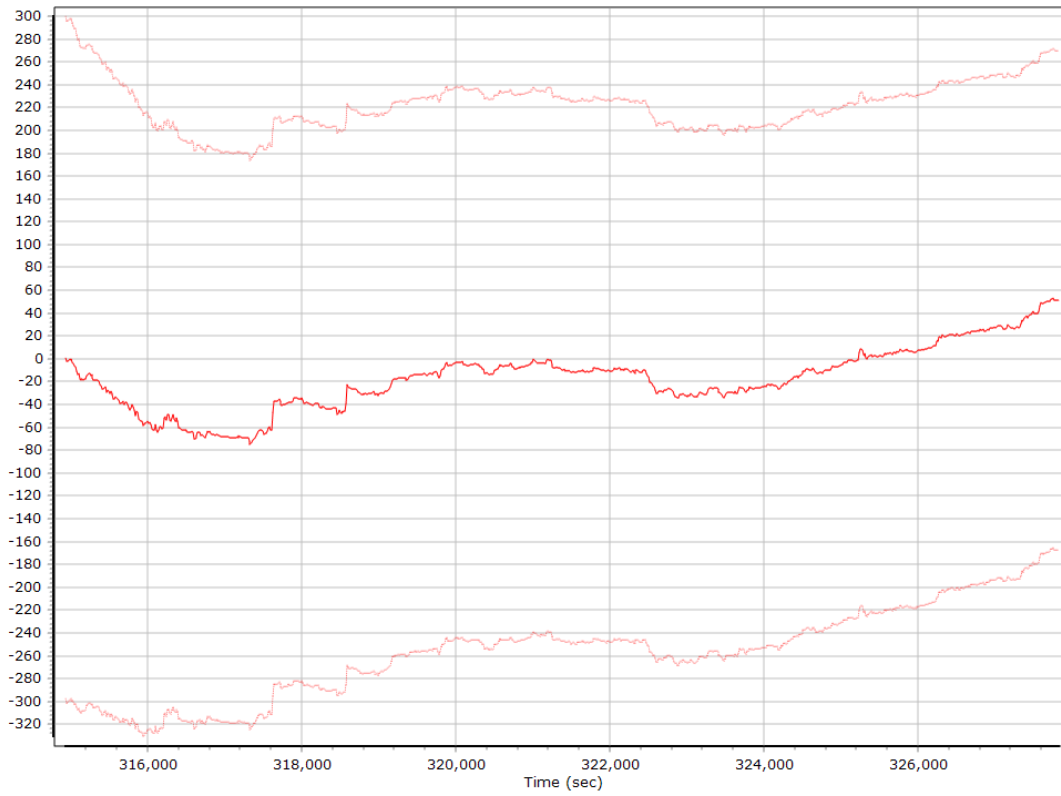
### Accelerometer Scale Error (ppm)



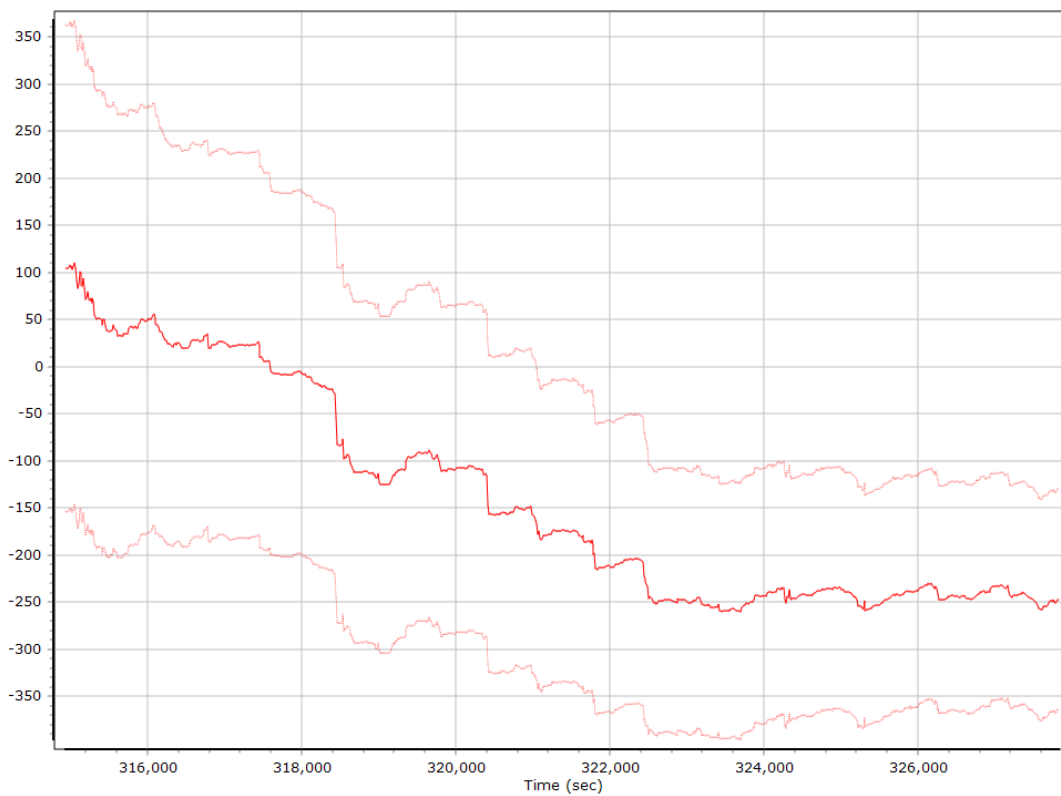
### X Accelerometer Scale Error (ppm)



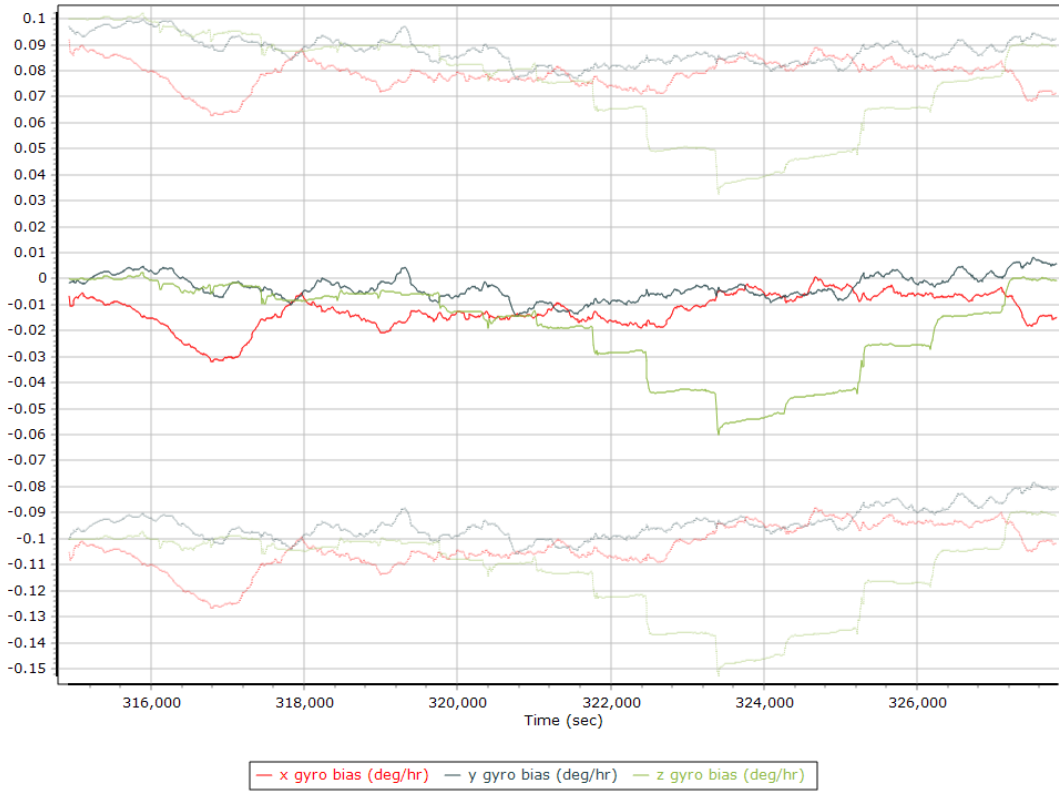
### Y Accelerometer Scale Error (ppm)



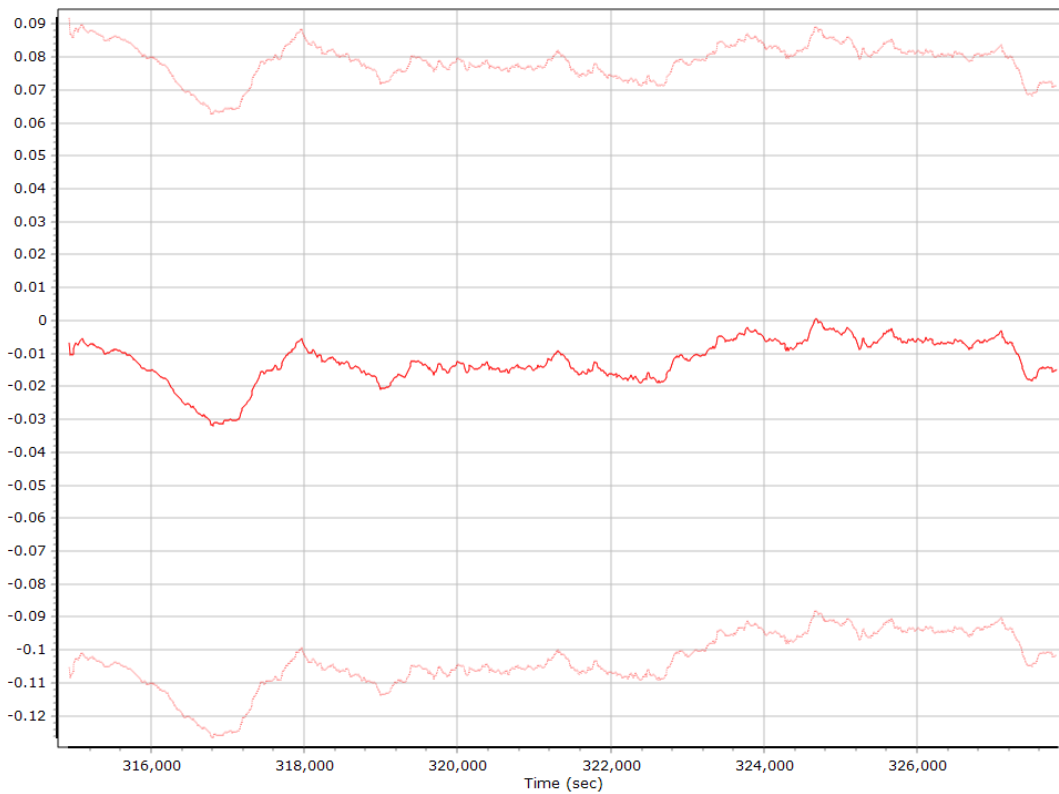
### Z Accelerometer Scale Error (ppm)



### Gyro Bias (deg/h)

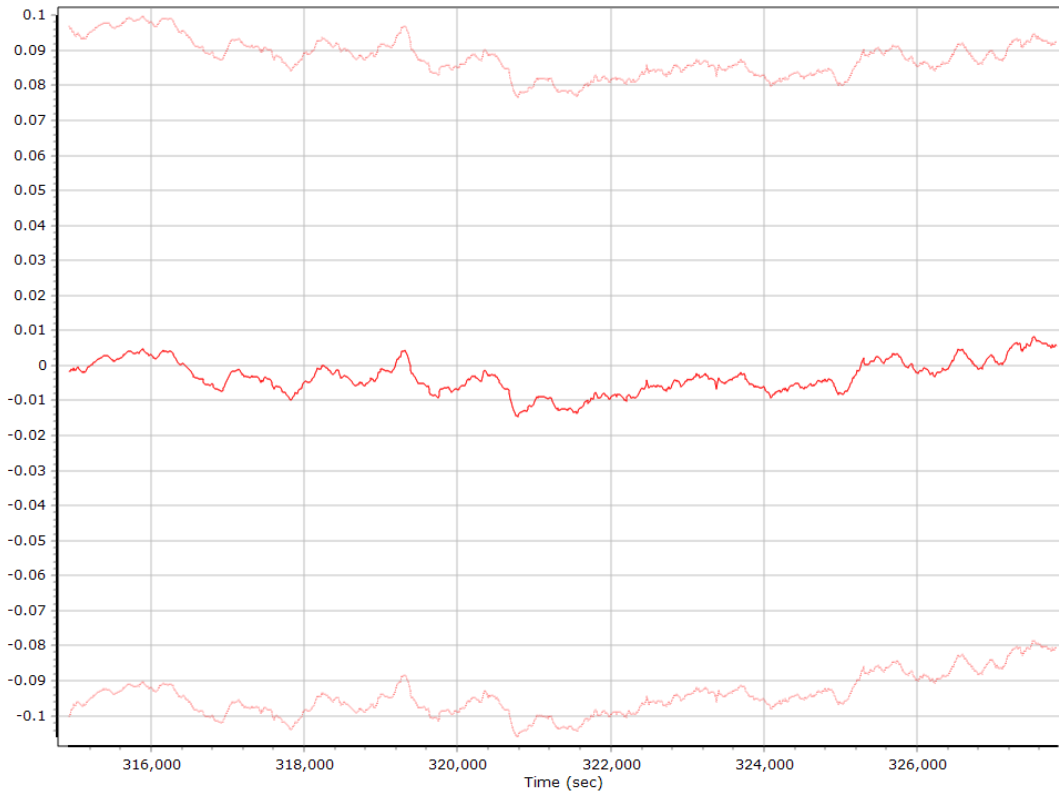


### X Gyro Bias (deg/h)

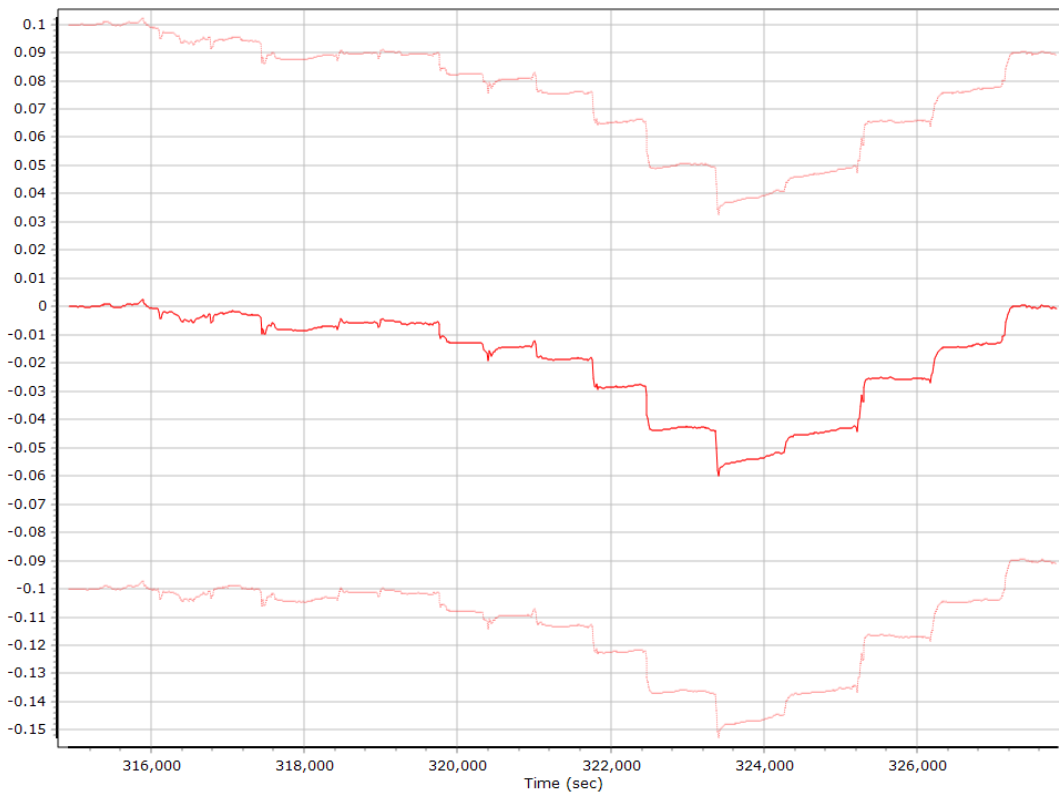




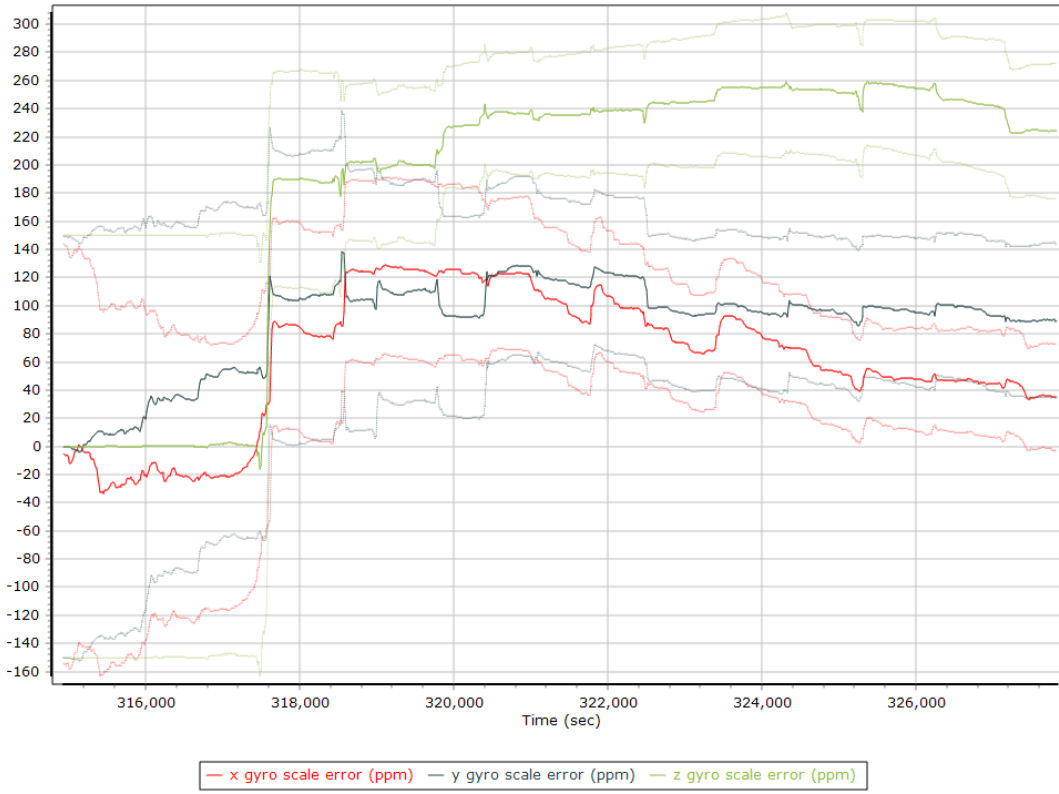
### Y Gyro Bias (deg/h)



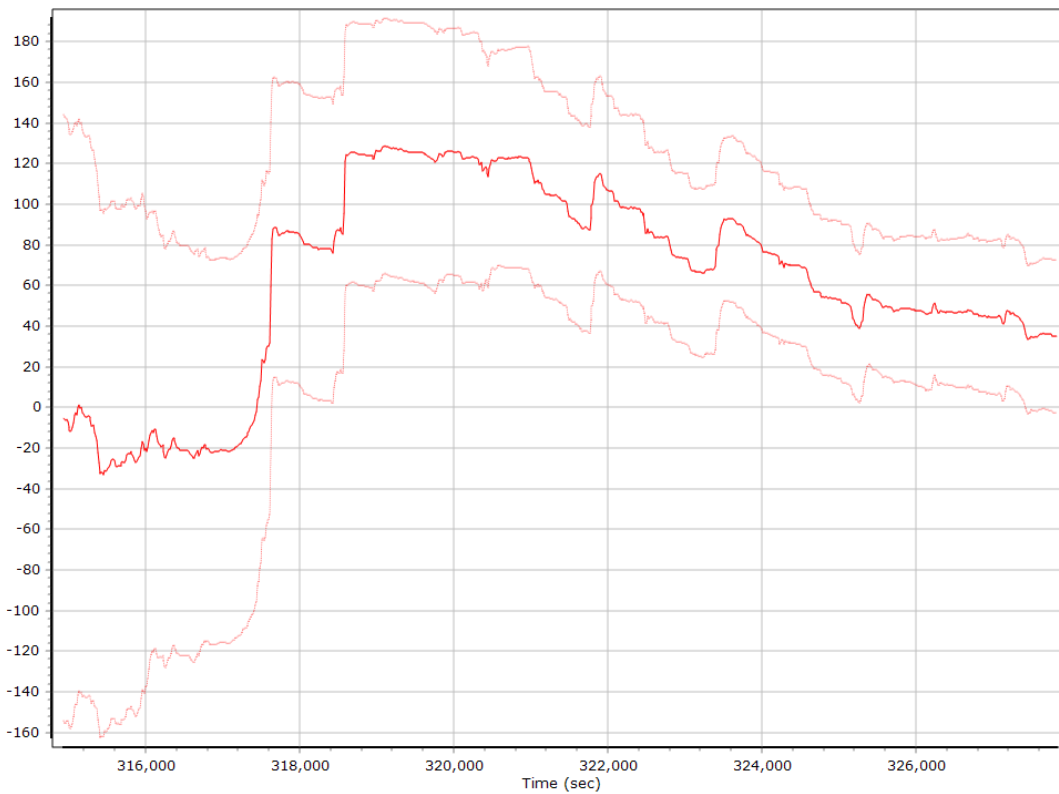
### Z Gyro Bias (deg/h)



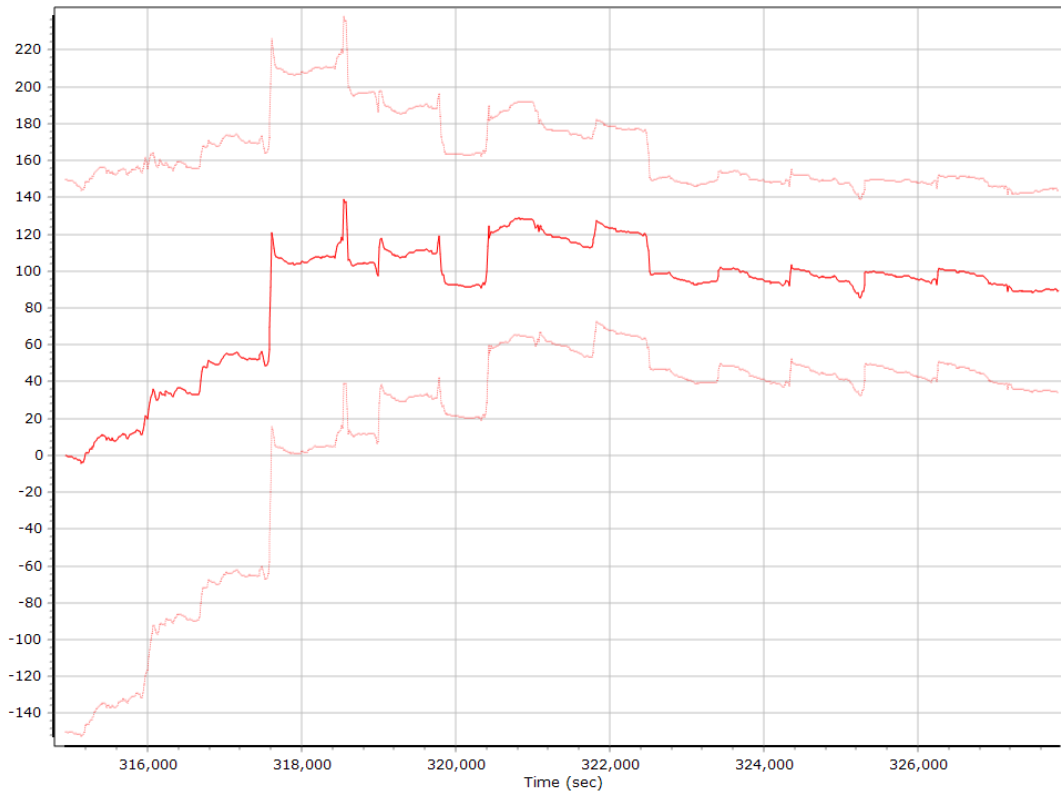
### Gyro Scale Error (ppm)



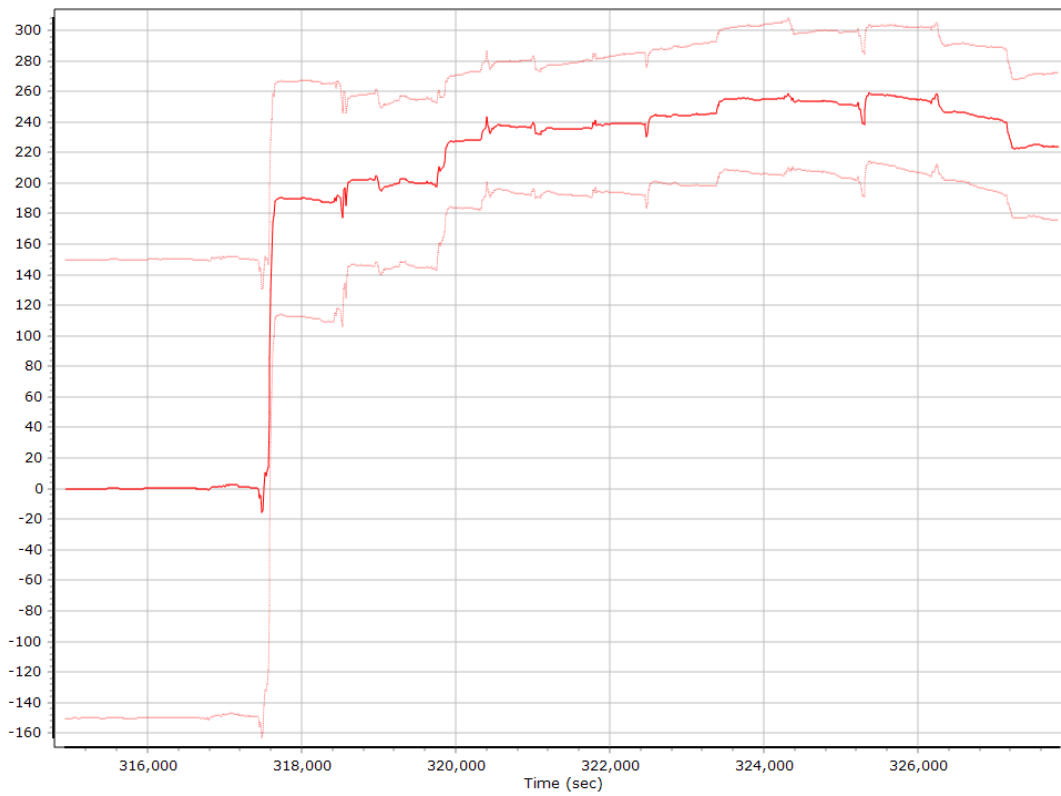
### X Gyro Scale Error (ppm)



### Y Gyro Scale Error (ppm)

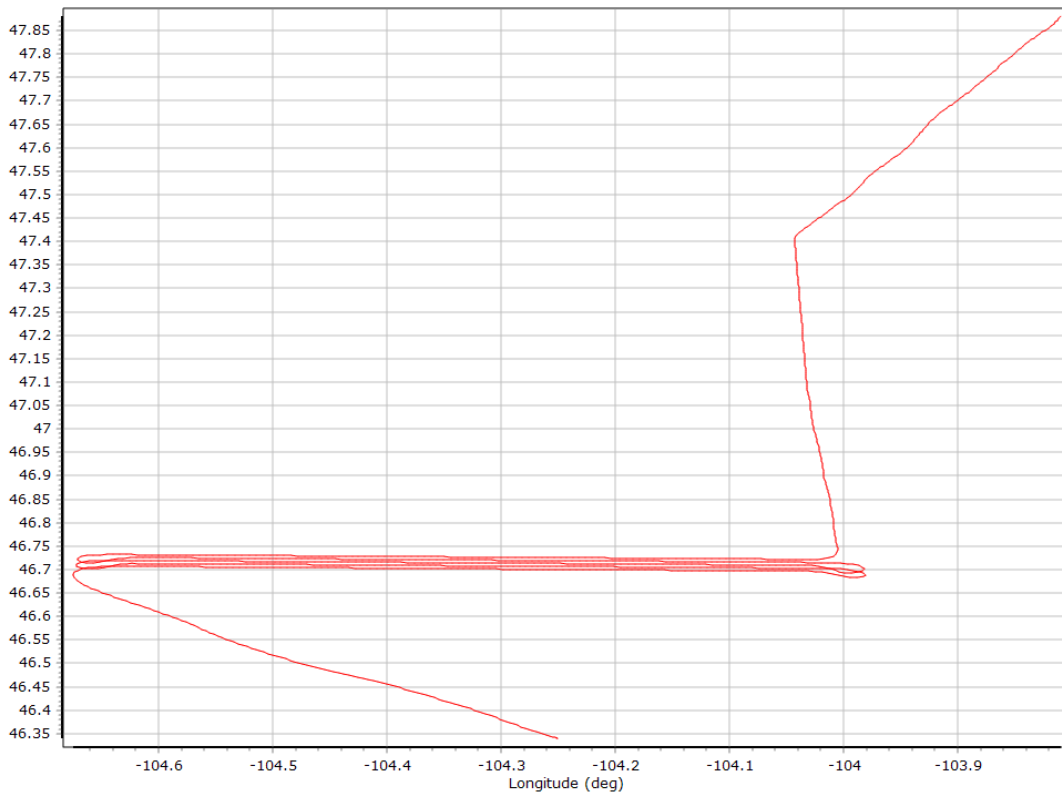


### Z Gyro Scale Error (ppm)

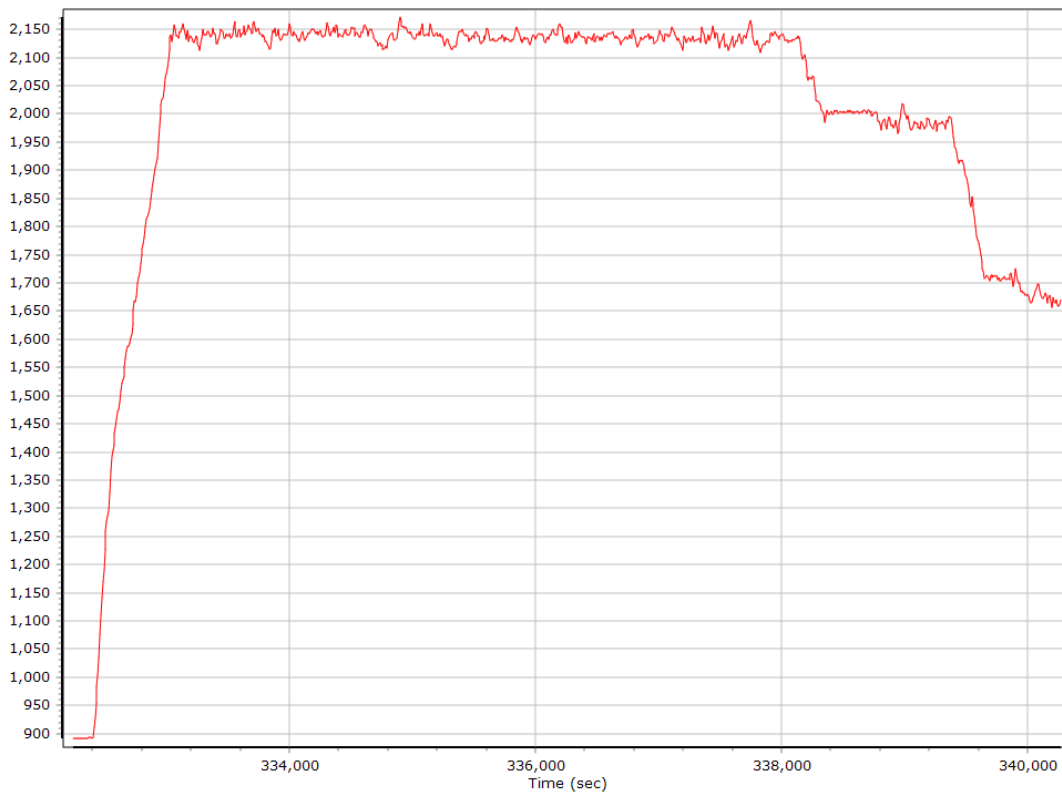


## Smoothed Trajectory Information

### Top View



### Altitude

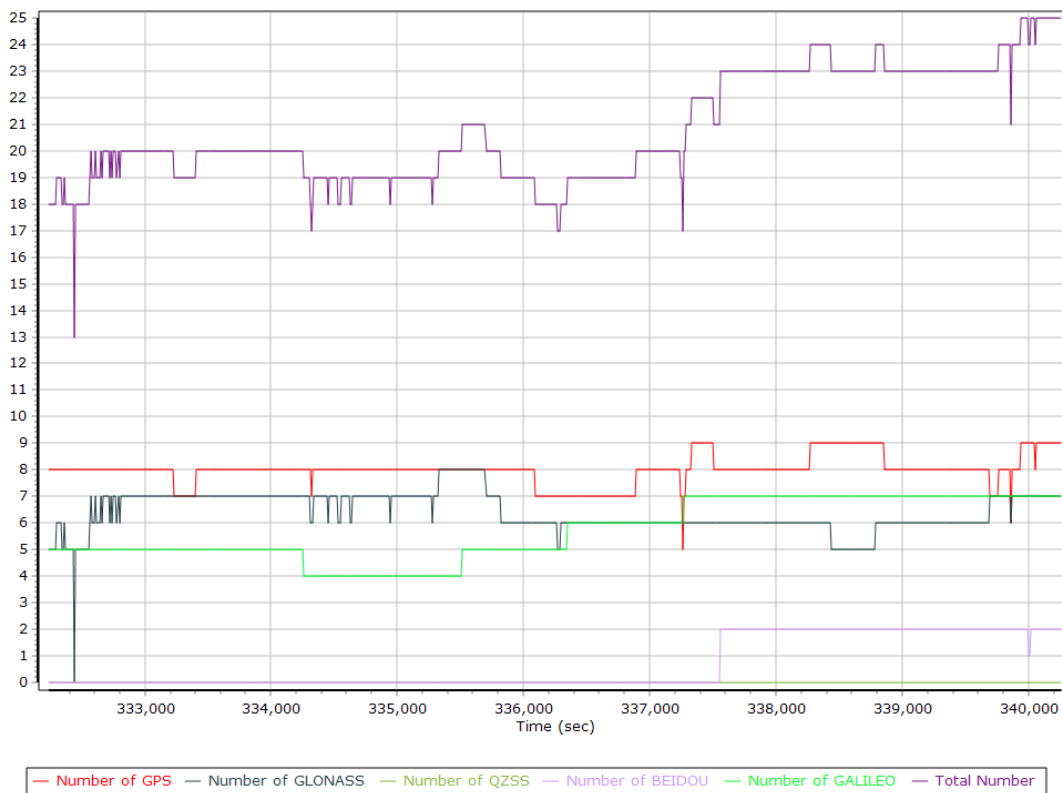


## GNSS QC

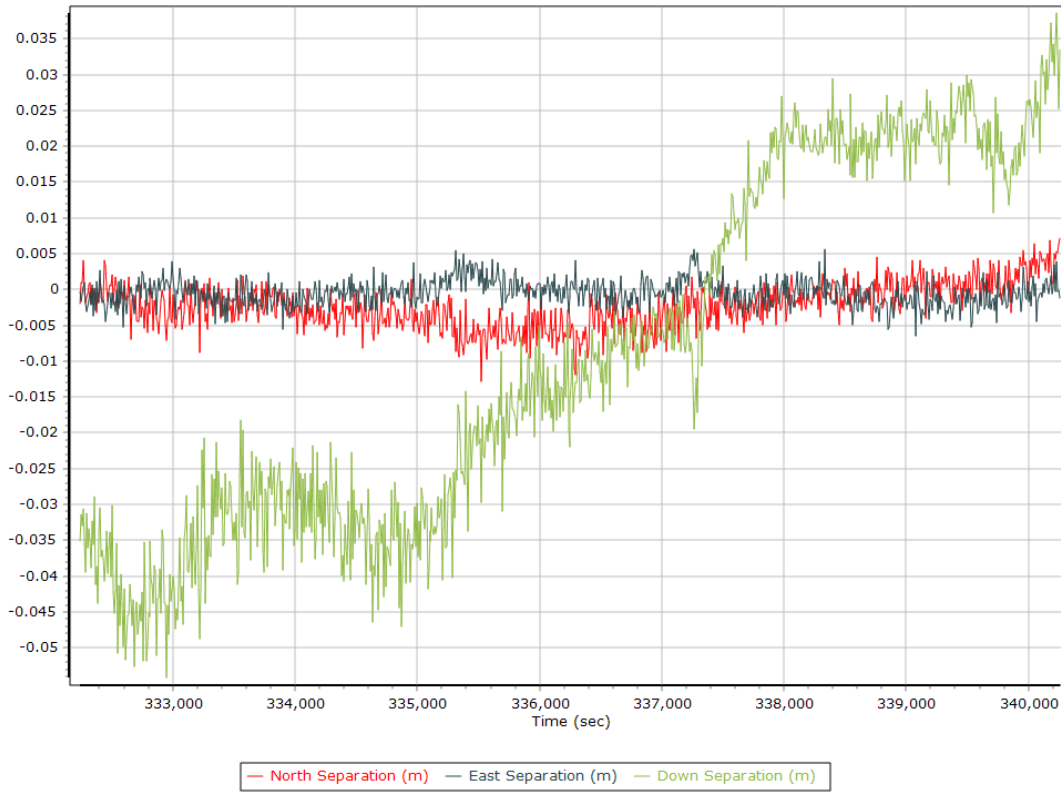
### GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	5	9	8
Number of GLONASS SV	0	8	6
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	2	1
Number of GALILEO SV	4	7	6
Total number of SV	13	25	21
PDOP	1.03	1.62	1.18
QC Solution Gaps	0.00	0.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	8414.00	0.00	0.00
Percentage	100.00	0.00	0.00

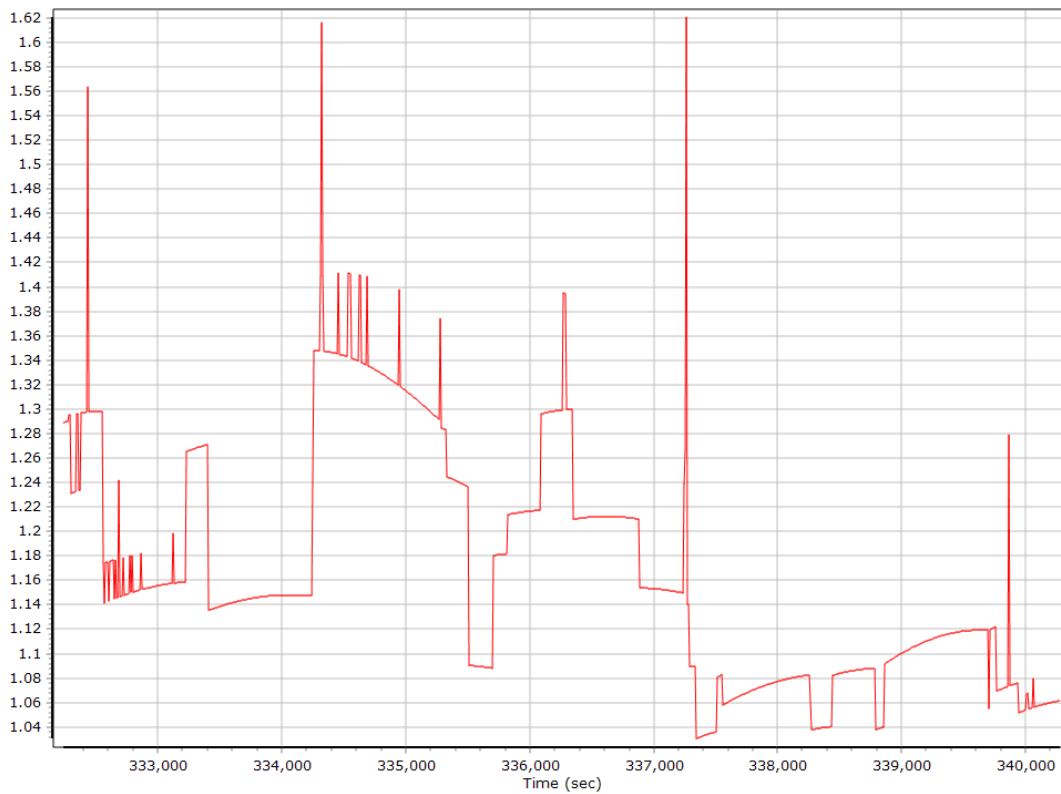
### Num SVs in solution



## Forward/Reverse Separation



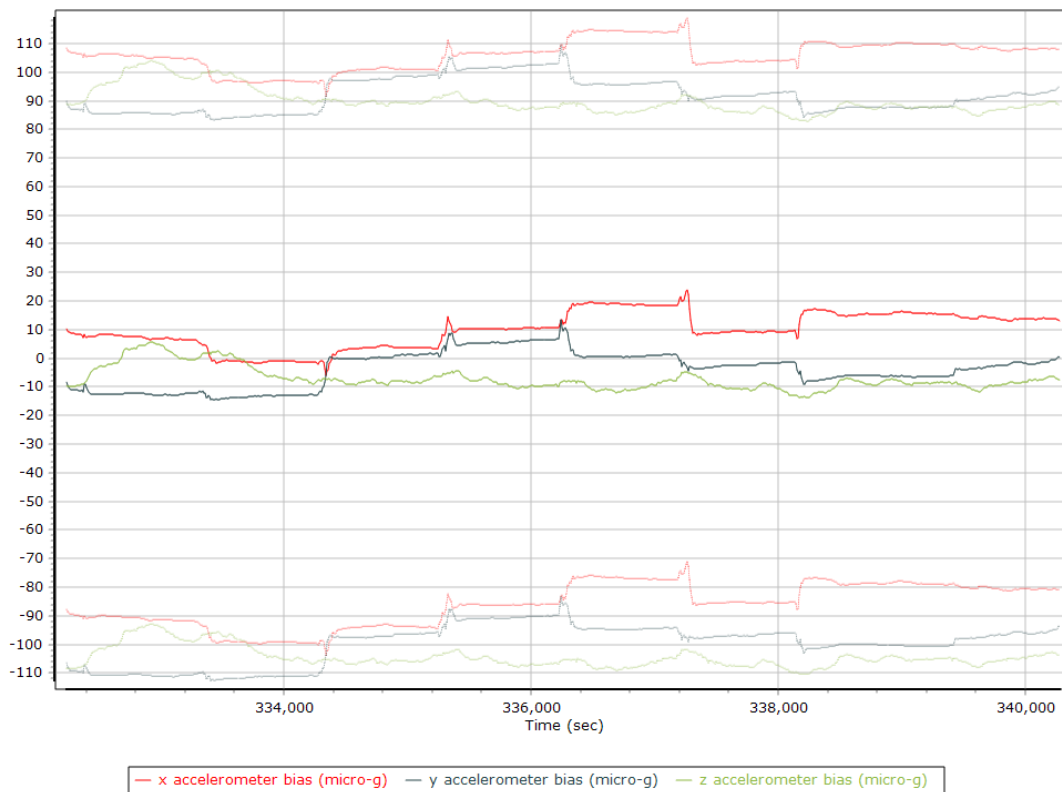
## PDOP



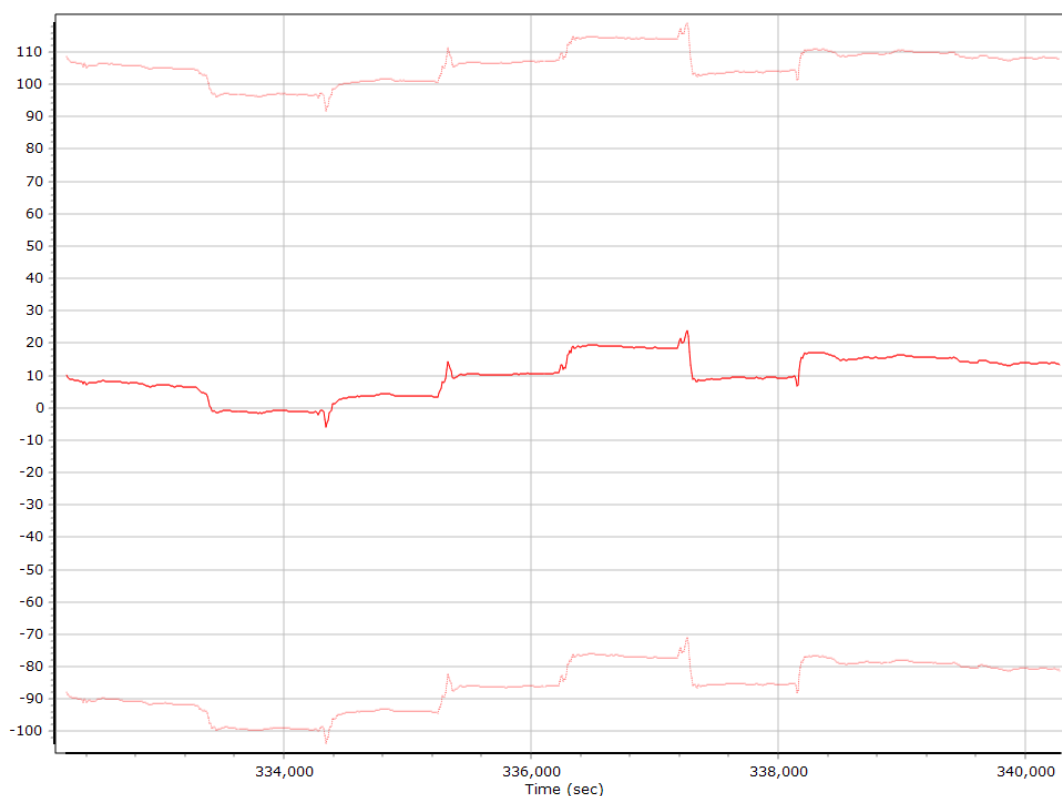
## IN-Fusion QC

### Forward Processed Estimated Errors, Reference Frame

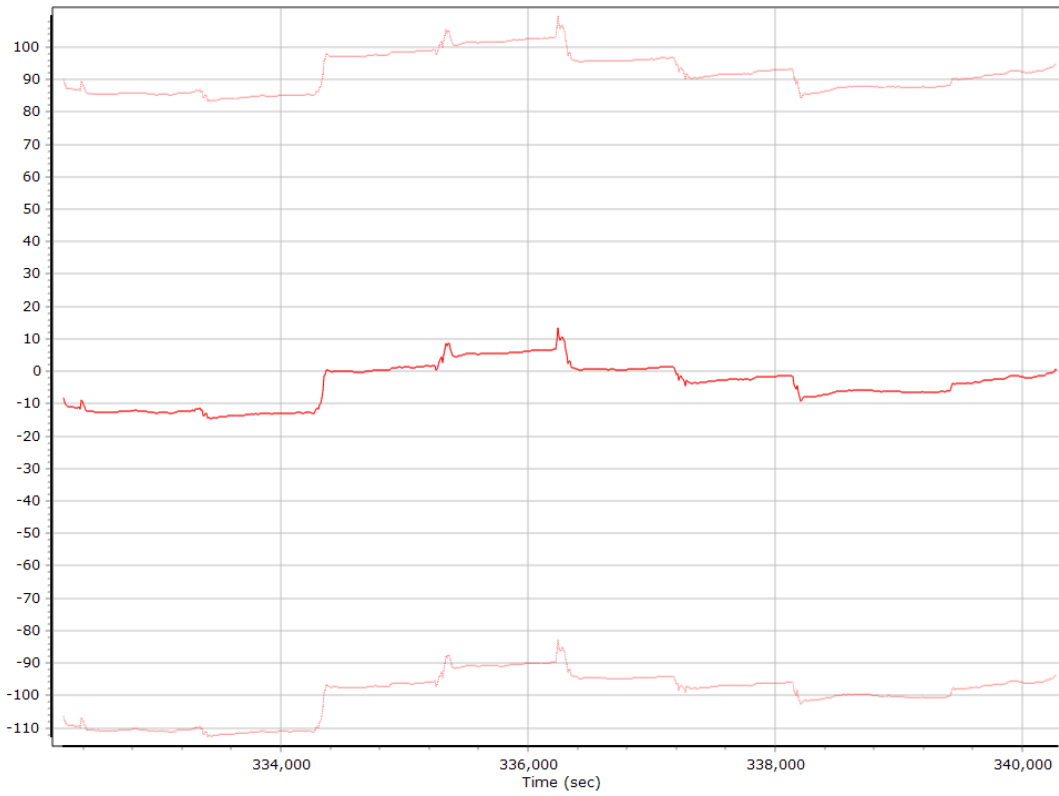
#### Accelerometer Bias (micro-g)



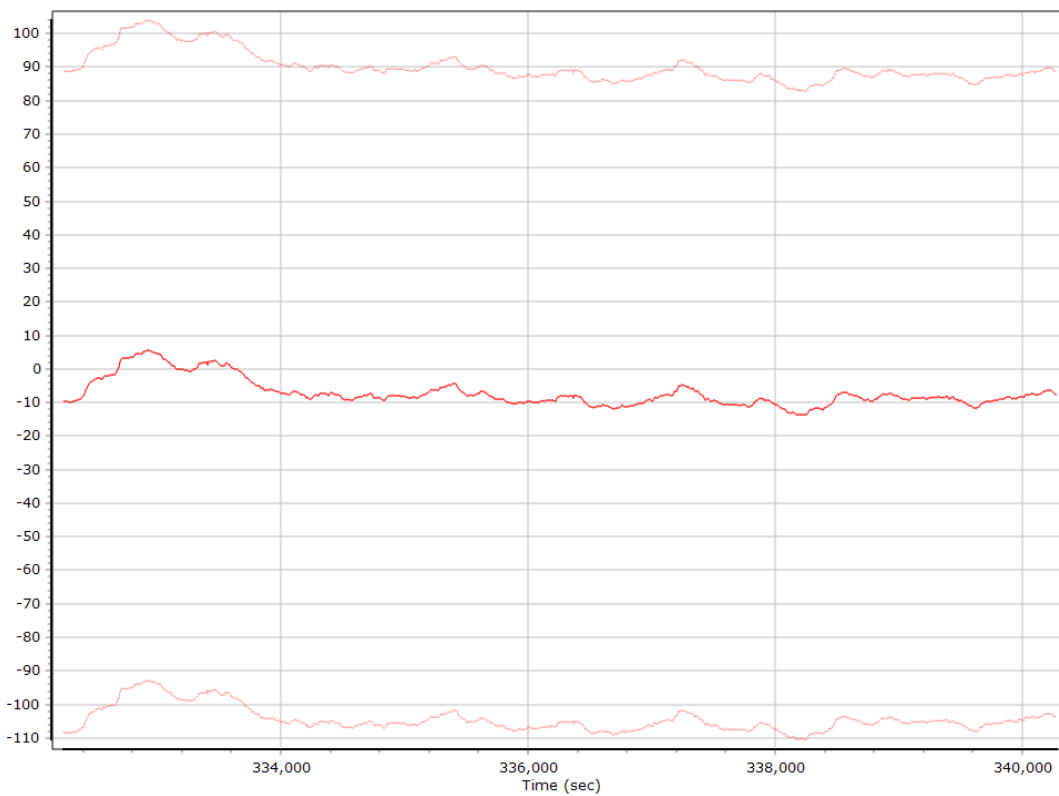
#### X Accelerometer Bias (micro-g)



### Y Accelerometer Bias (micro-g)

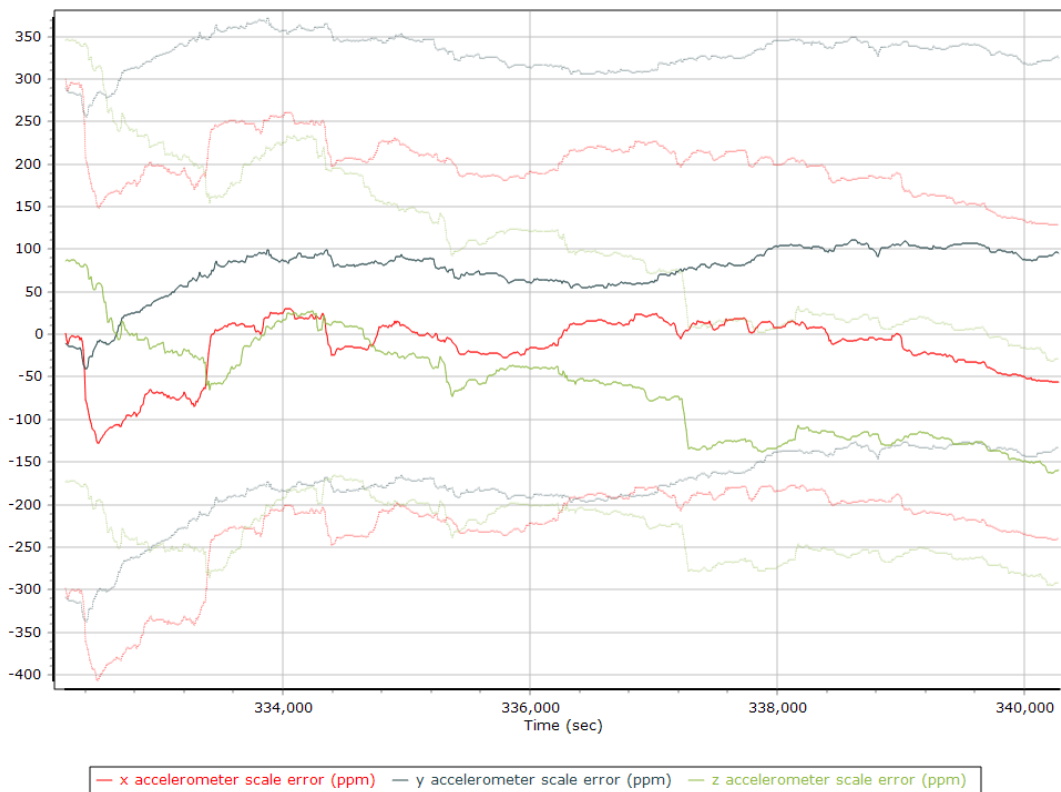


### Z Accelerometer Bias (micro-g)

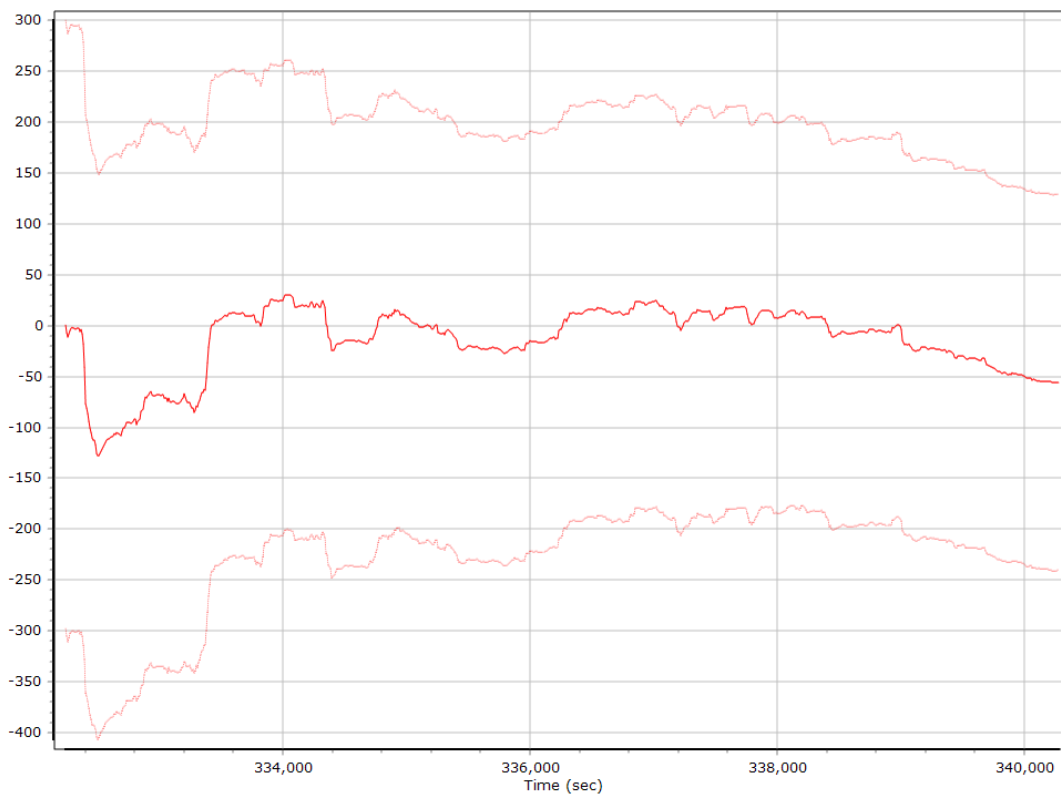




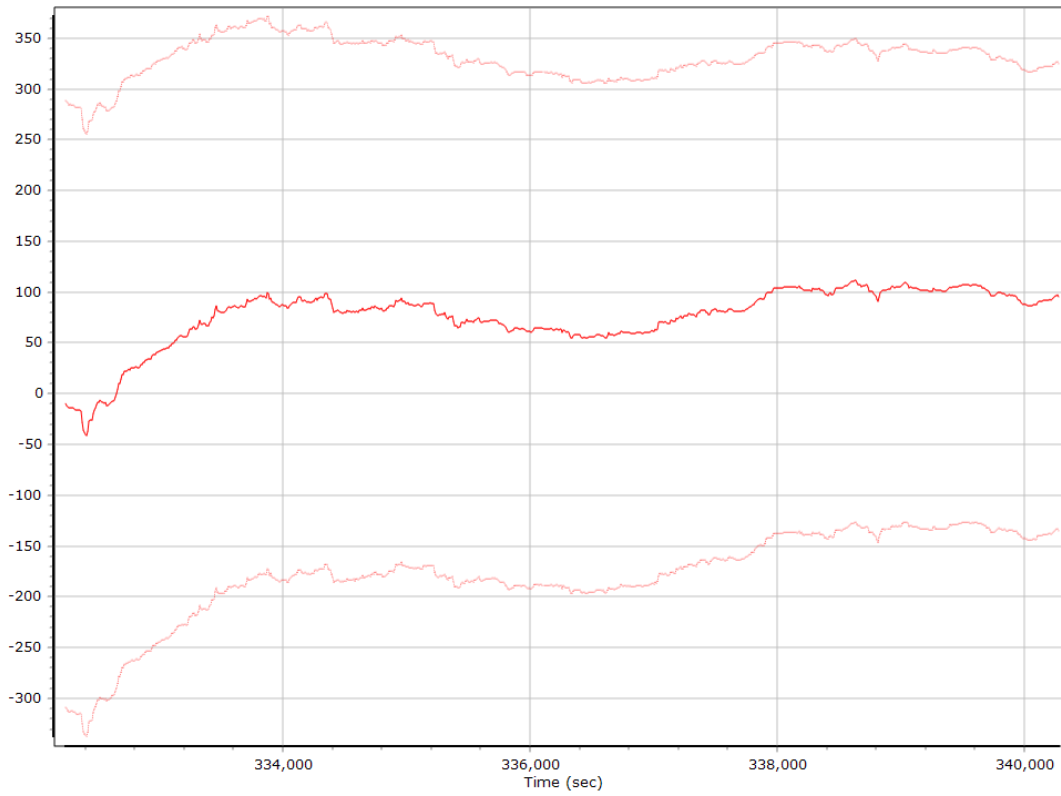
### Accelerometer Scale Error (ppm)



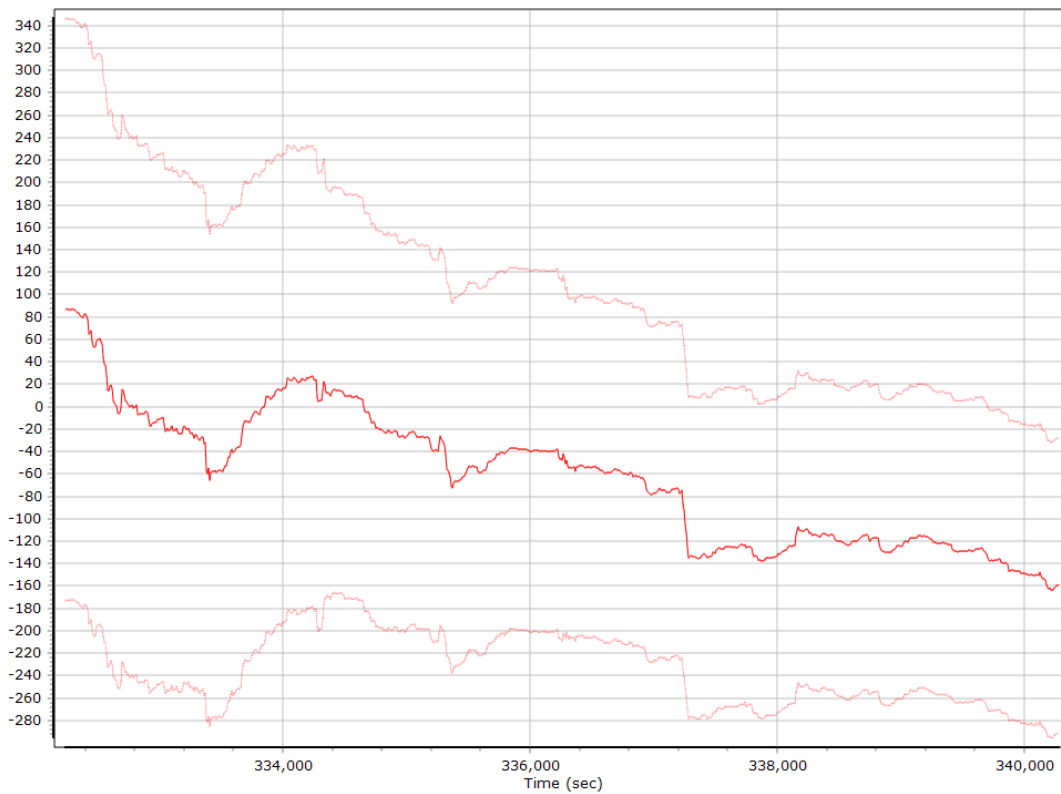
### X Accelerometer Scale Error (ppm)



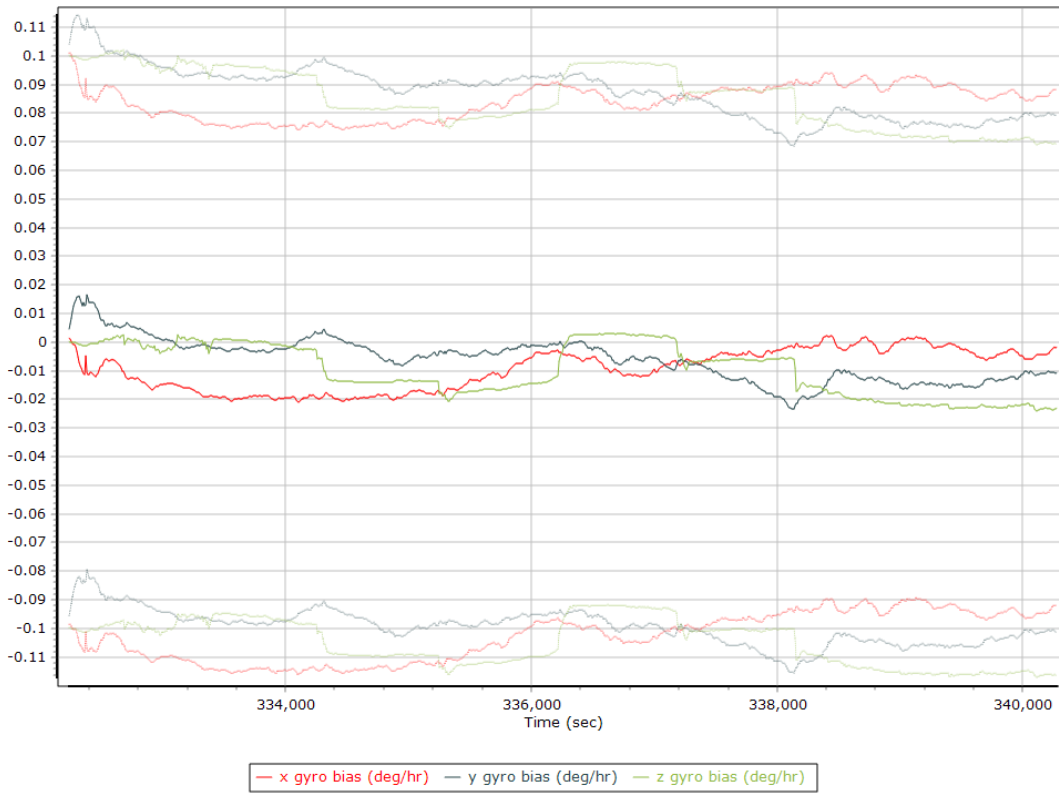
### Y Accelerometer Scale Error (ppm)



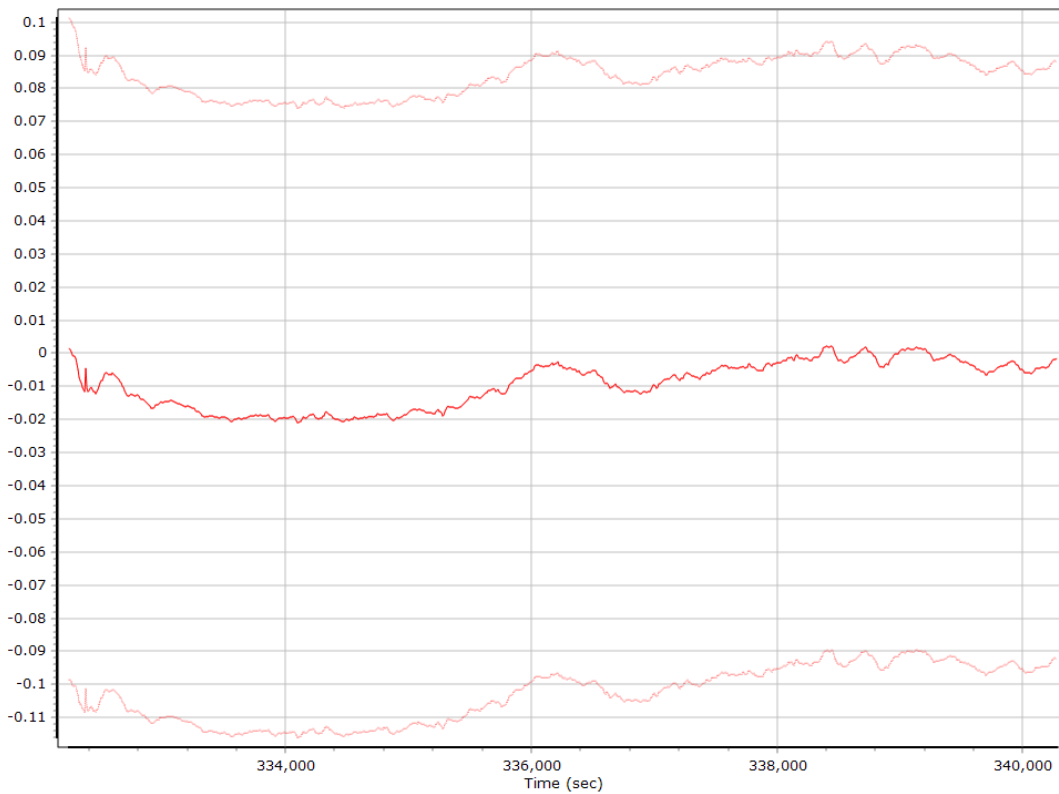
### Z Accelerometer Scale Error (ppm)



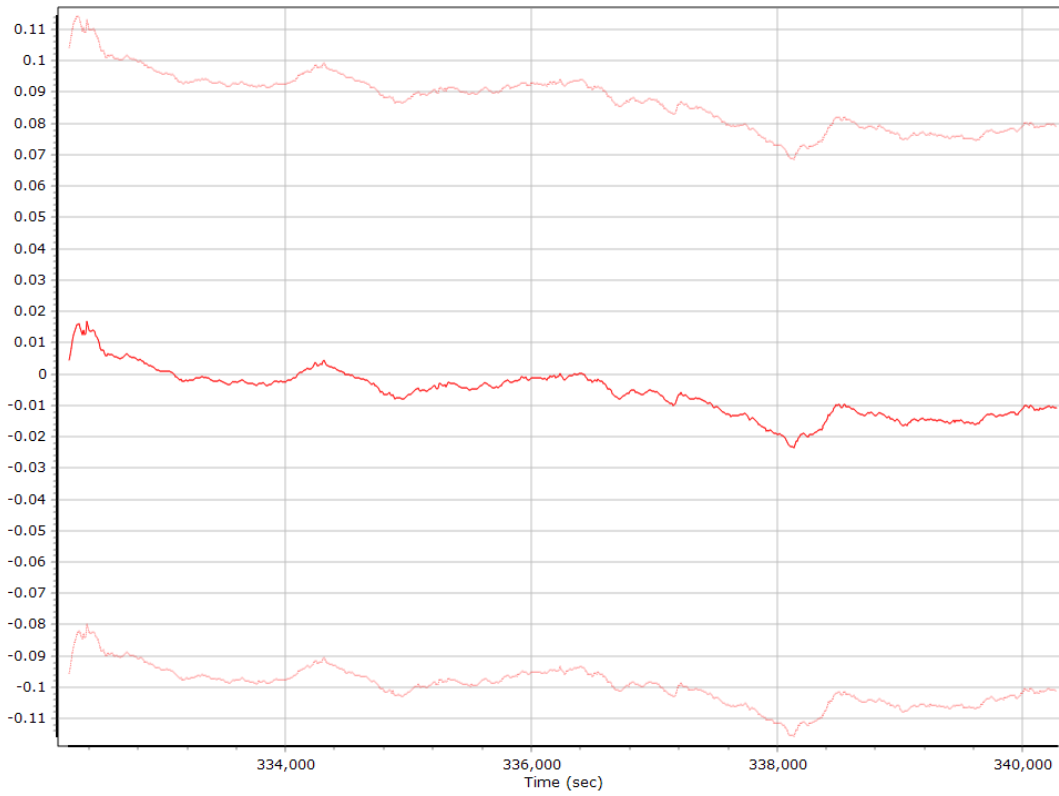
### Gyro Bias (deg/h)



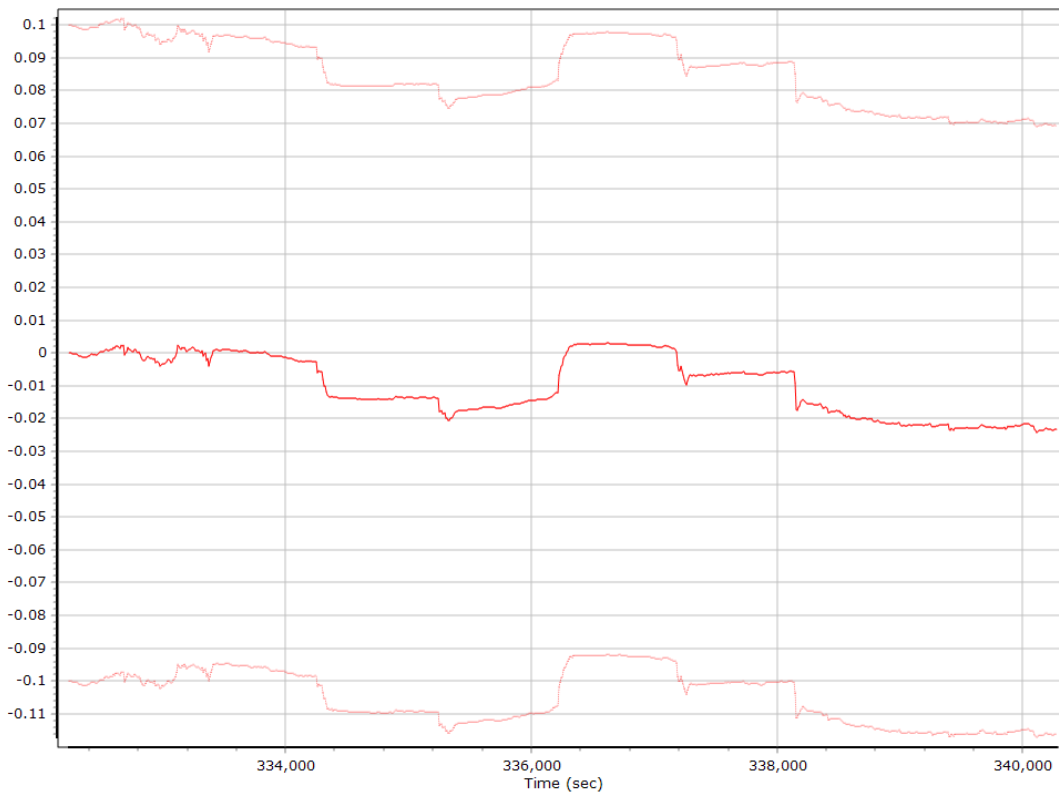
### X Gyro Bias (deg/h)



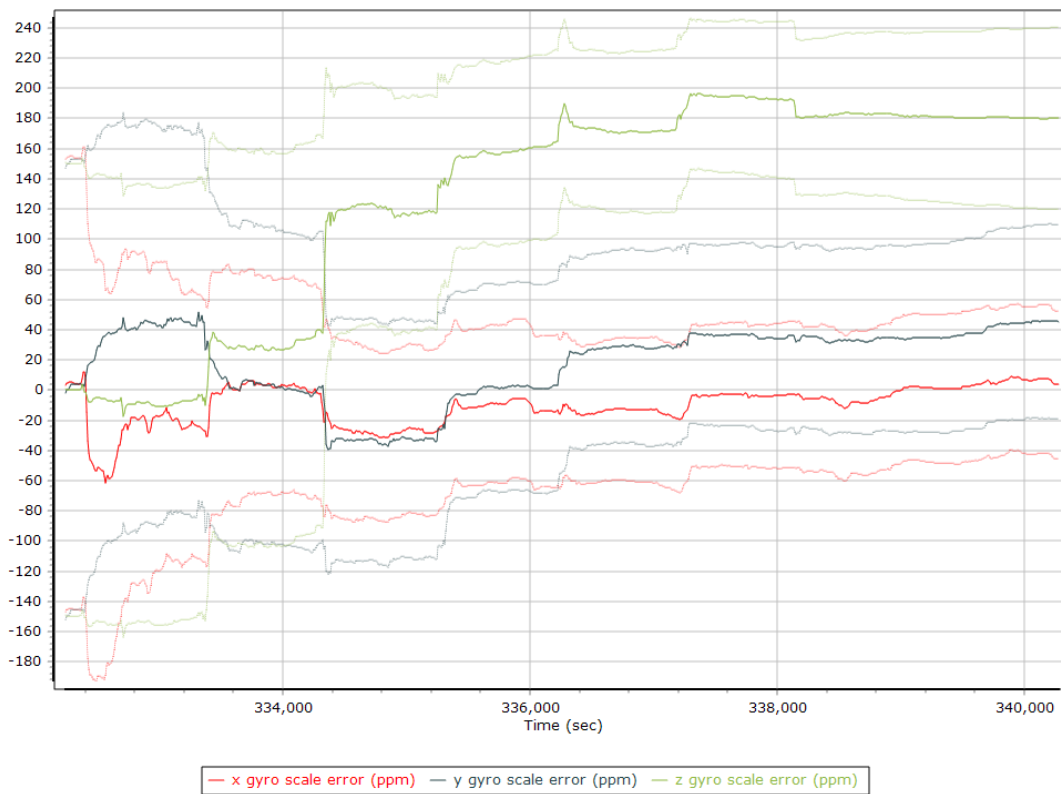
### Y Gyro Bias (deg/h)



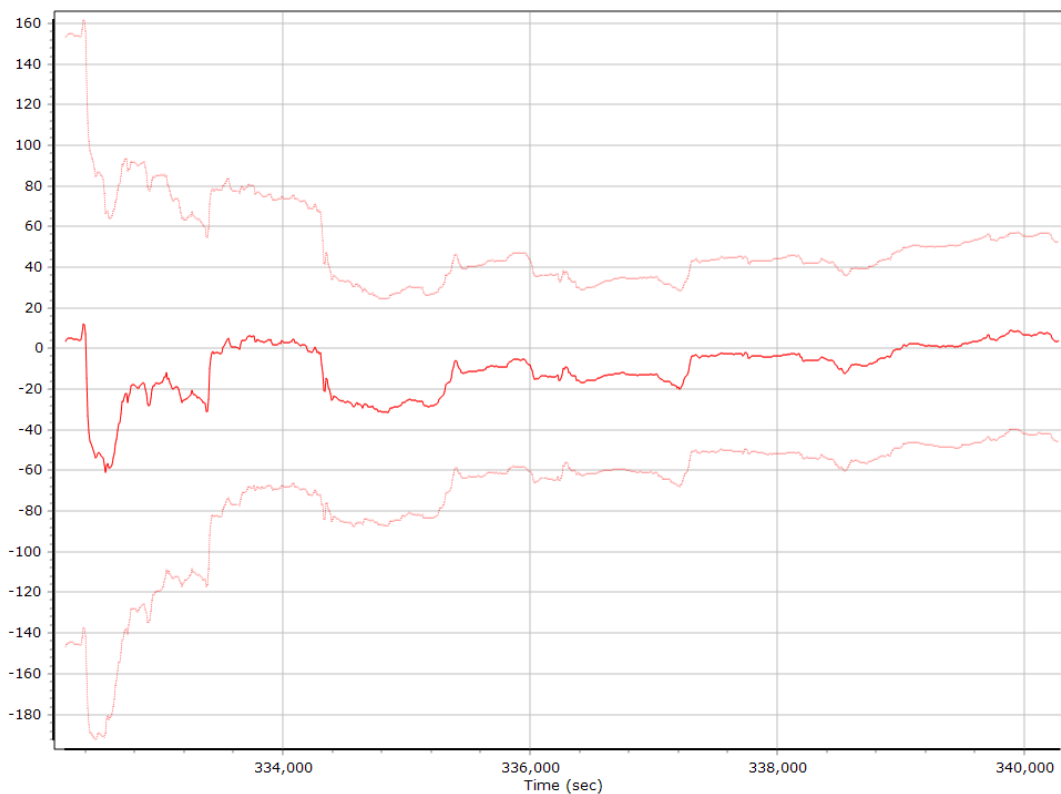
### Z Gyro Bias (deg/h)



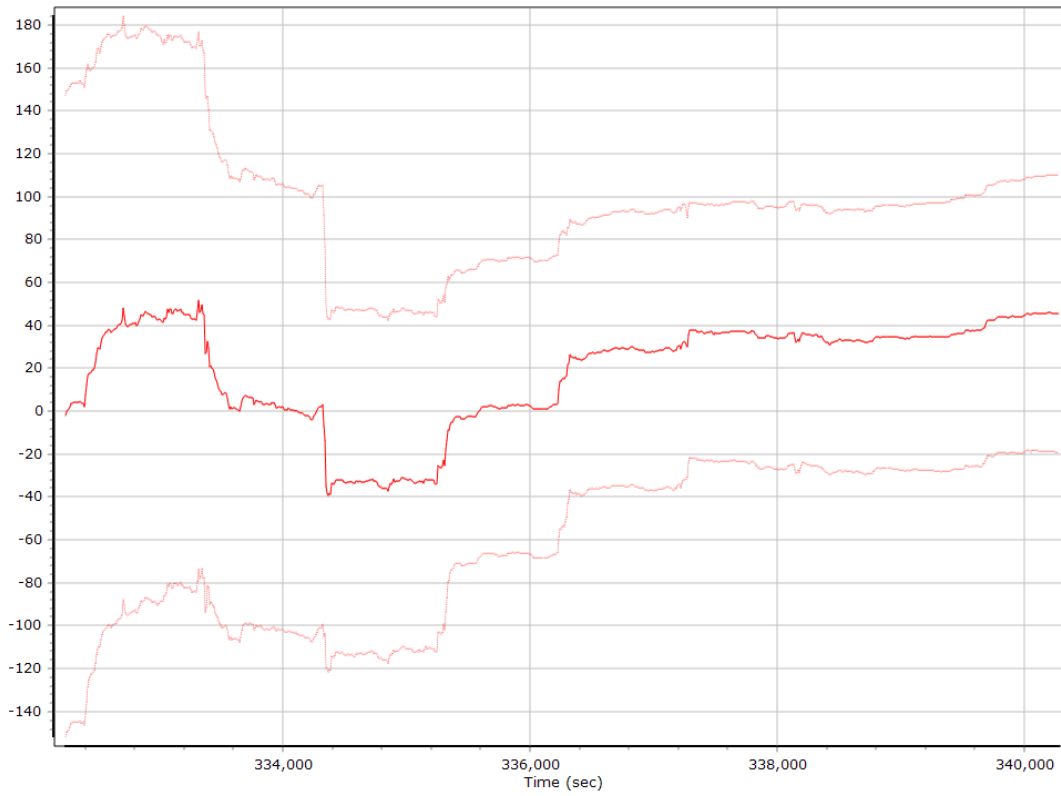
### Gyro Scale Error (ppm)



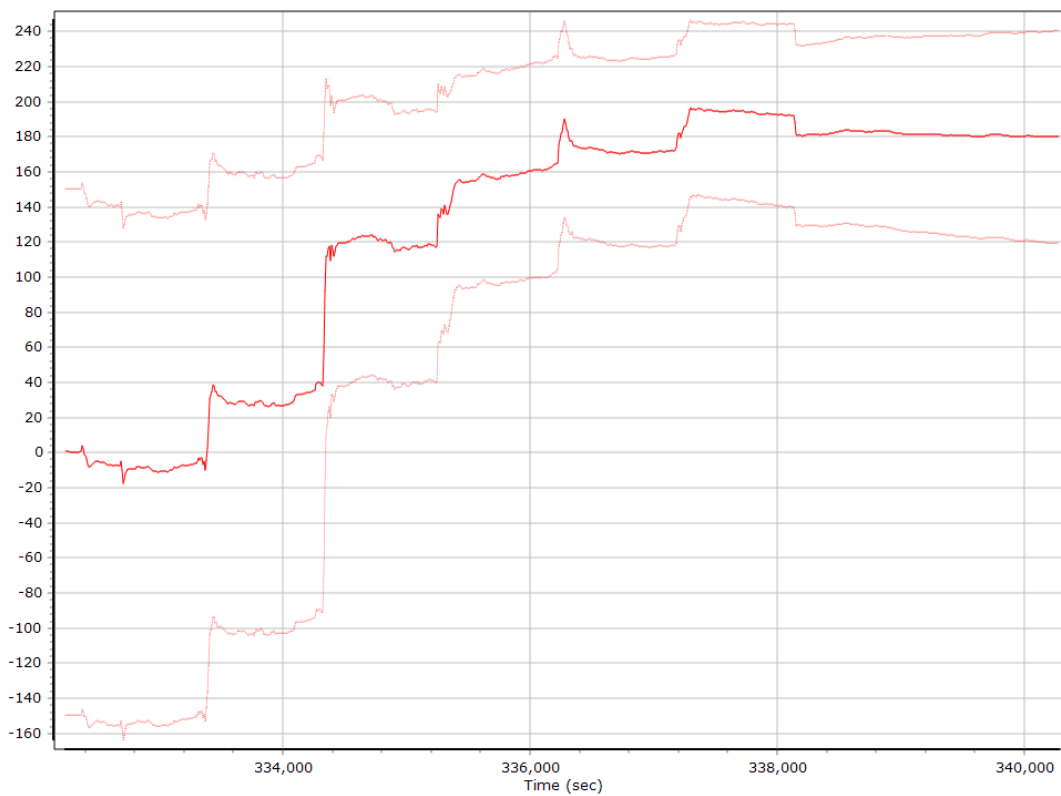
### X Gyro Scale Error (ppm)



### Y Gyro Scale Error (ppm)

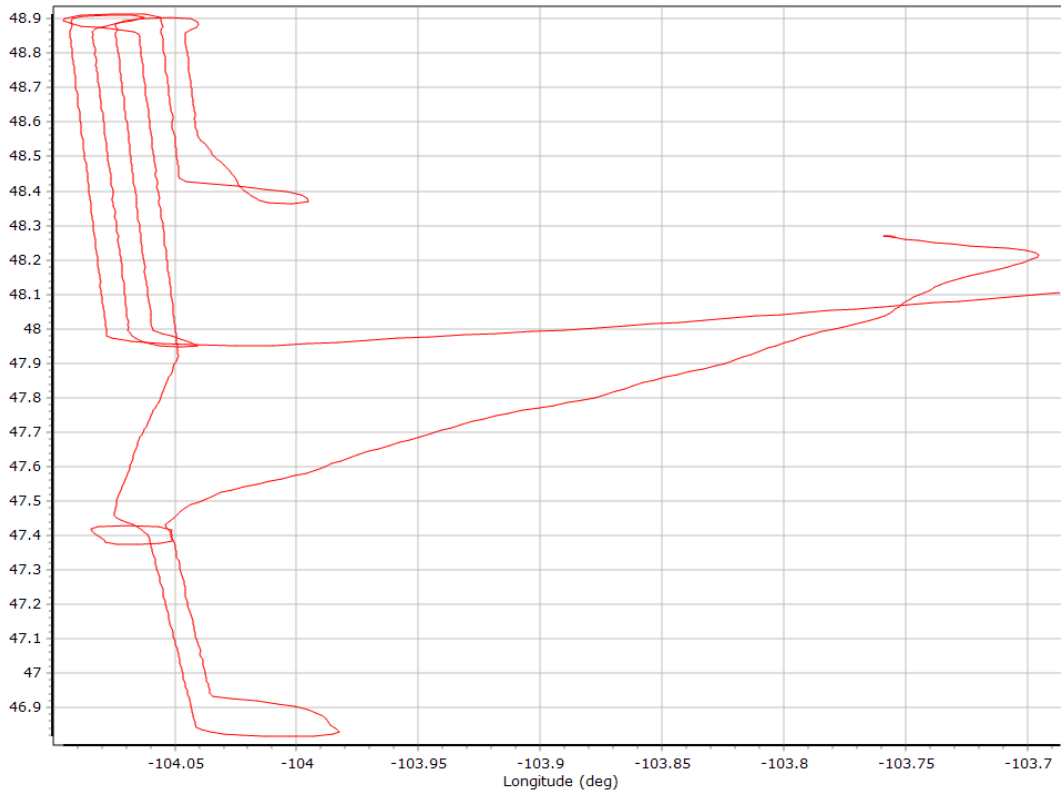


### Z Gyro Scale Error (ppm)

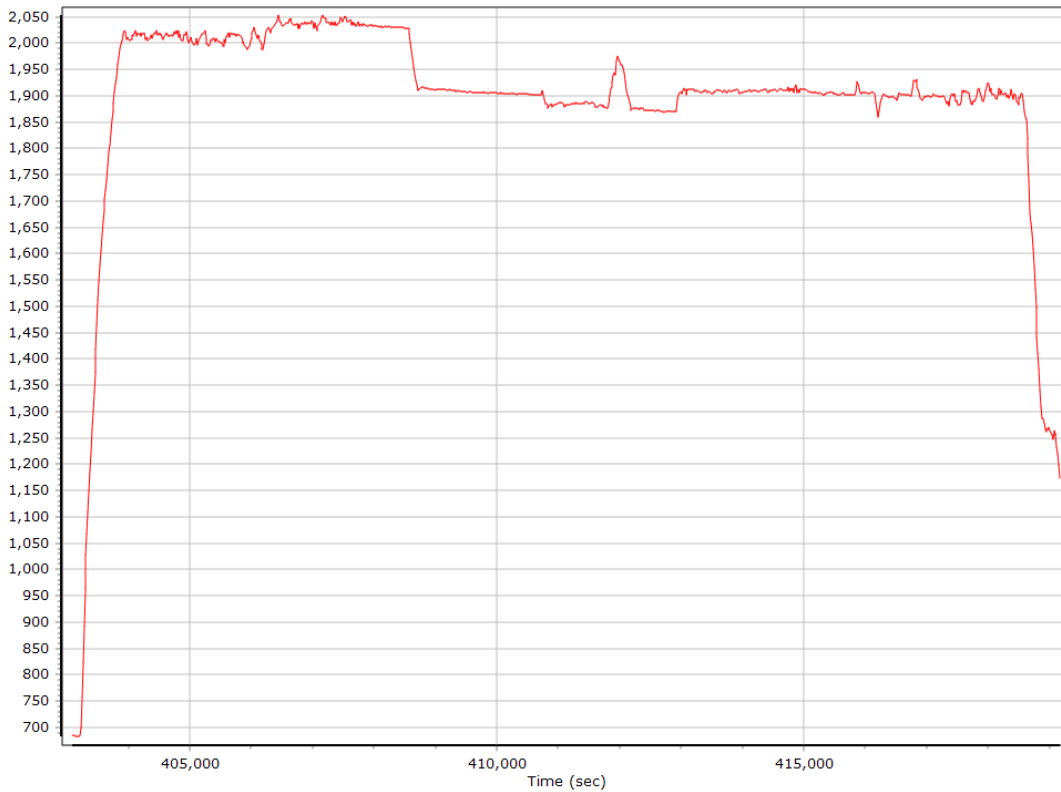


## Smoothed Trajectory Information

### Top View



### Altitude

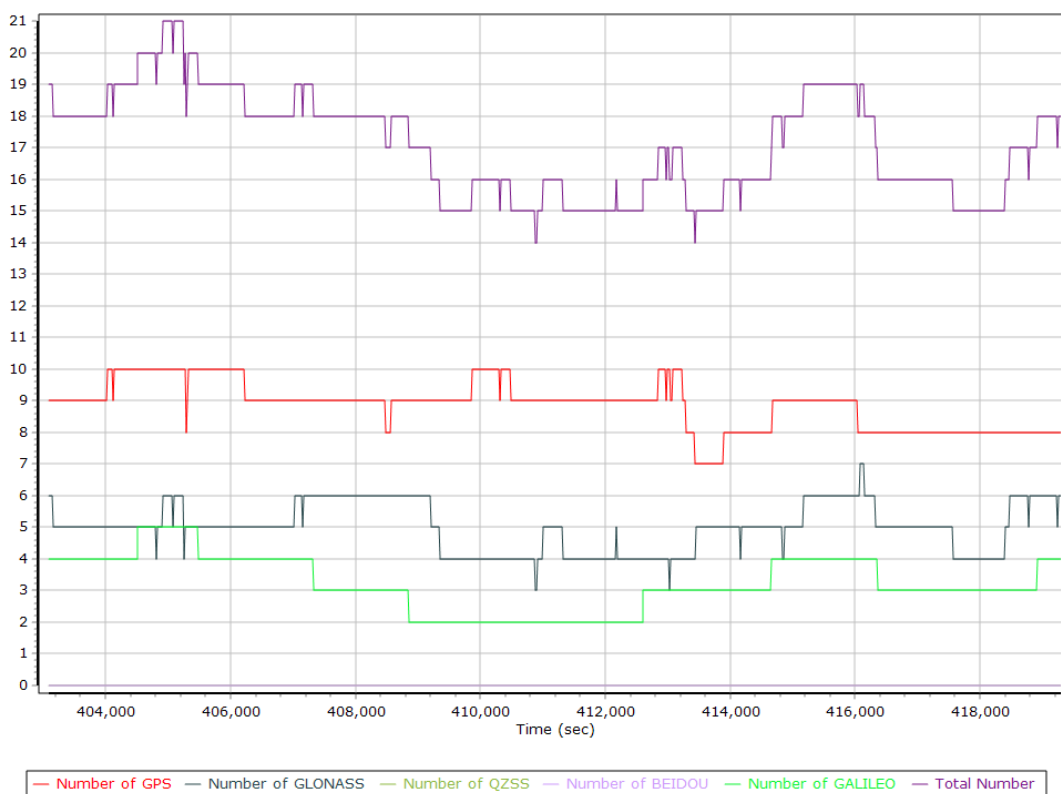


## GNSS QC

### GNSS QC Statistics

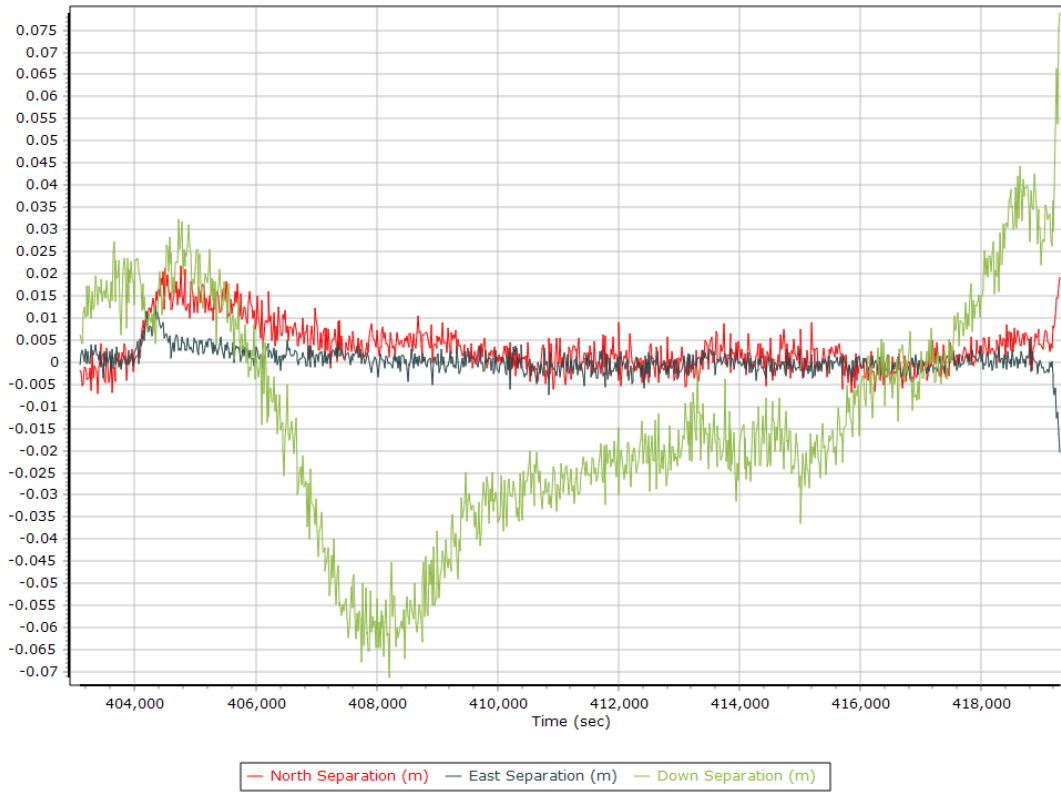
Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	7	10	9
Number of GLONASS SV	0	7	5
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	0	0
Number of GALILEO SV	0	5	3
Total number of SV	13	21	17
PDOP	1.07	1.69	1.34
QC Solution Gaps	0.00	0.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	16606.00	0.00	0.00
Percentage	100.00	0.00	0.00

### Num SVs in solution

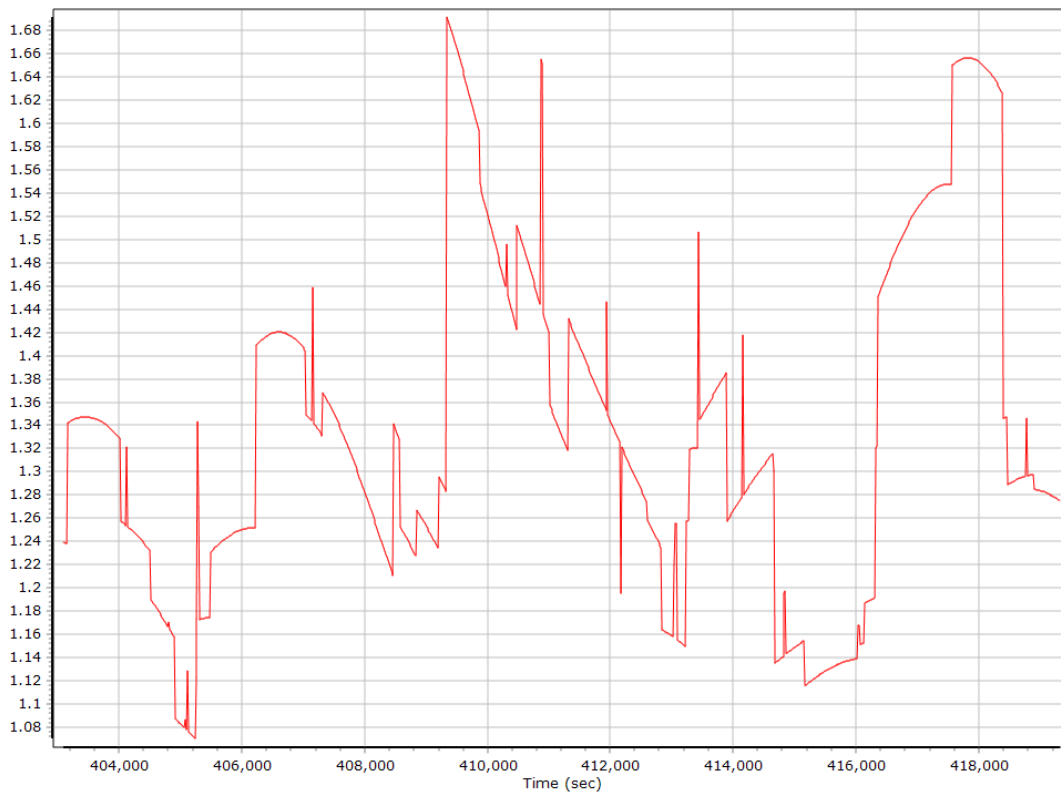




## Forward/Reverse Separation



## PDOP



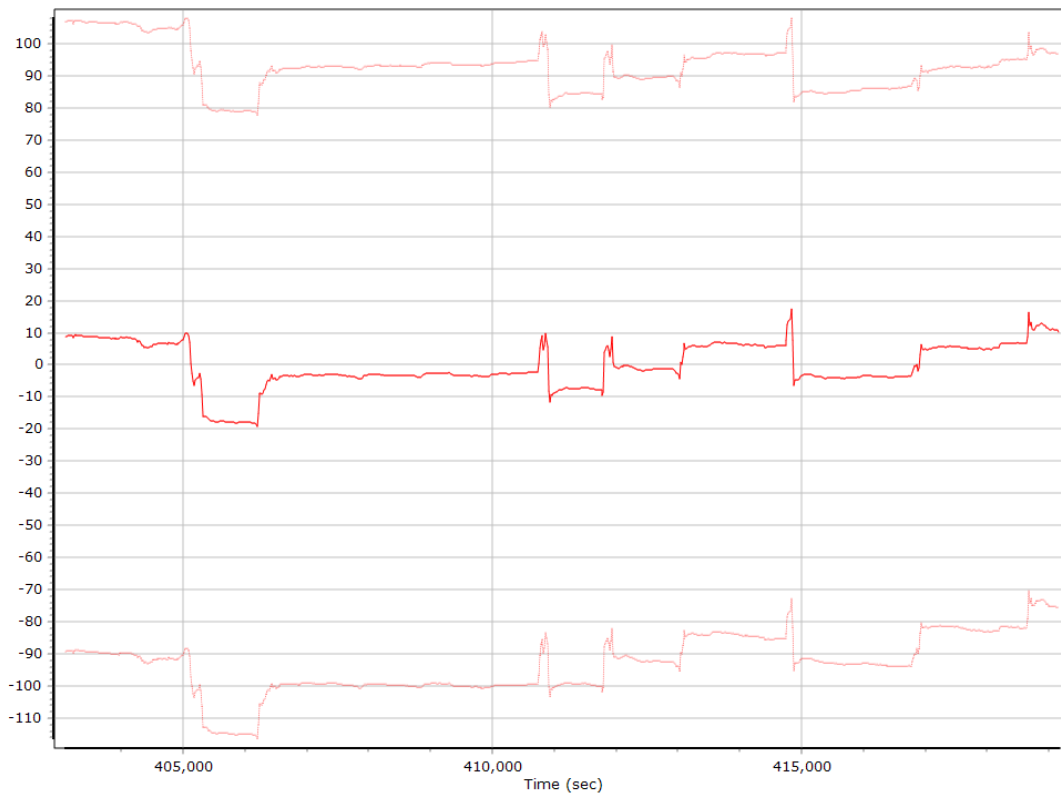
## IN-Fusion QC

### Forward Processed Estimated Errors, Reference Frame

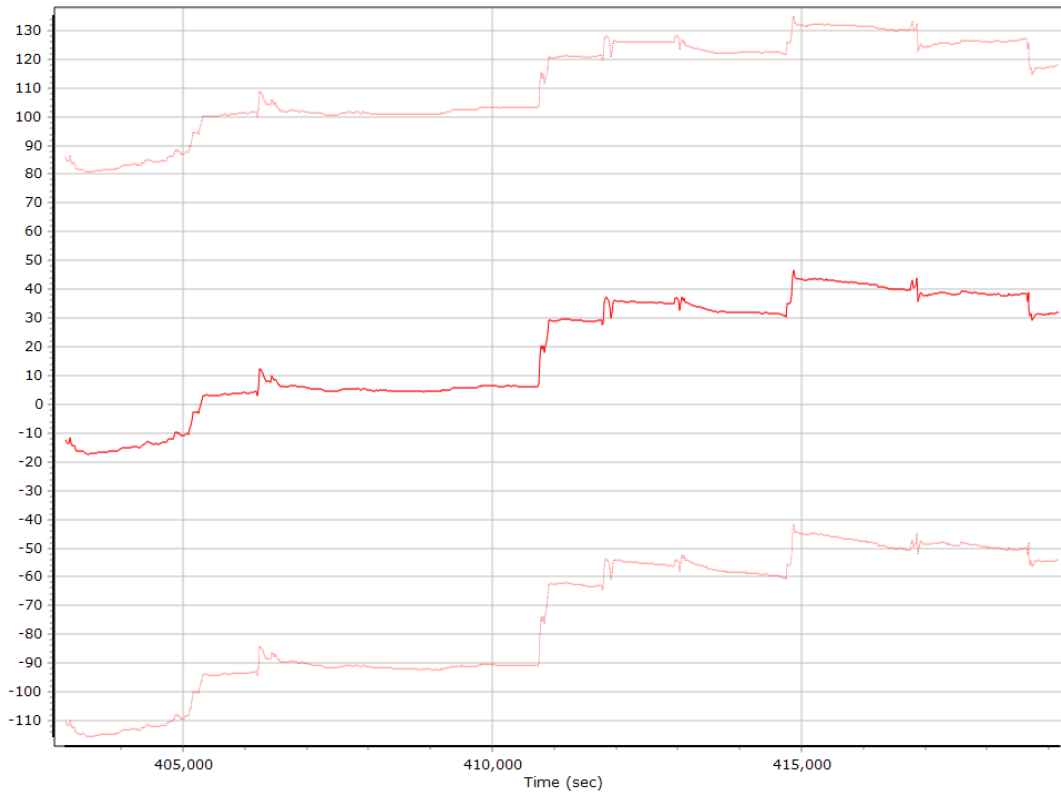
#### Accelerometer Bias (micro-g)



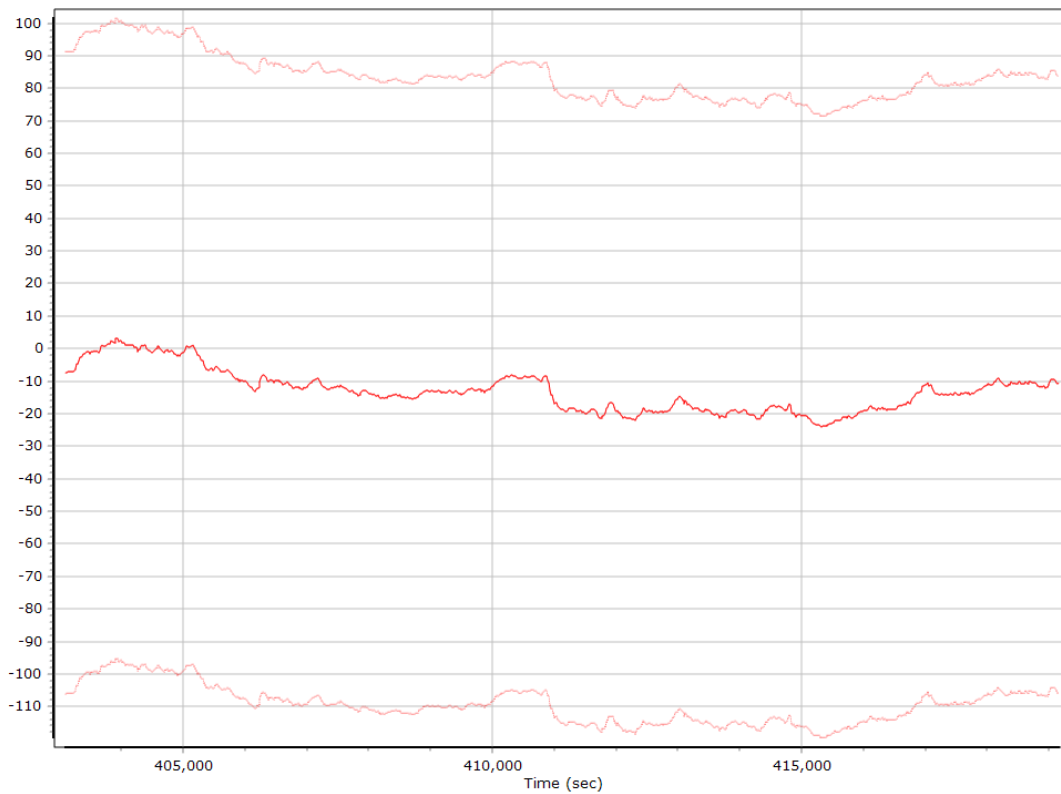
#### X Accelerometer Bias (micro-g)



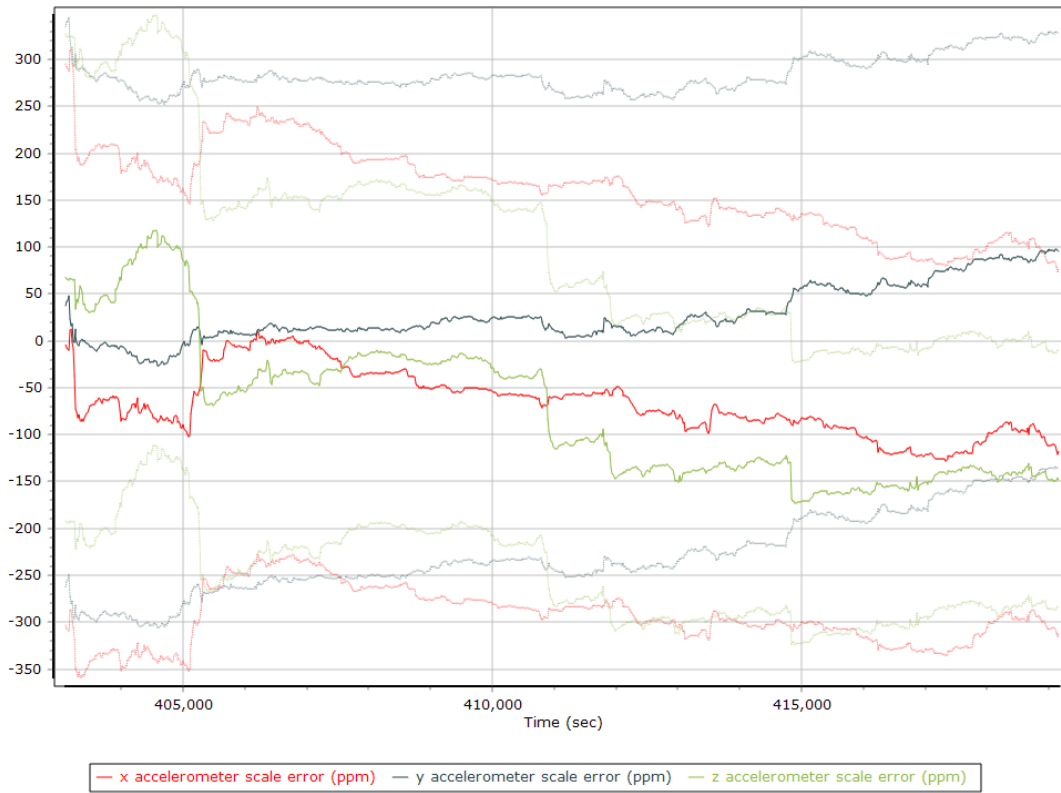
### Y Accelerometer Bias (micro-g)



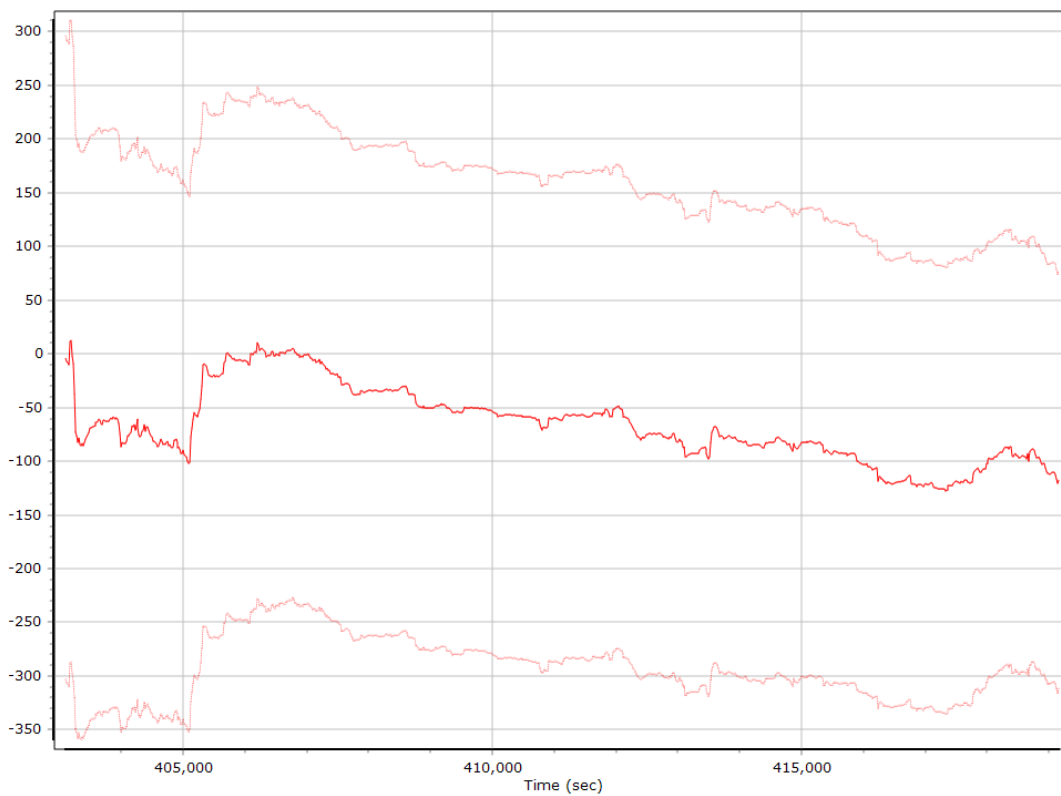
### Z Accelerometer Bias (micro-g)



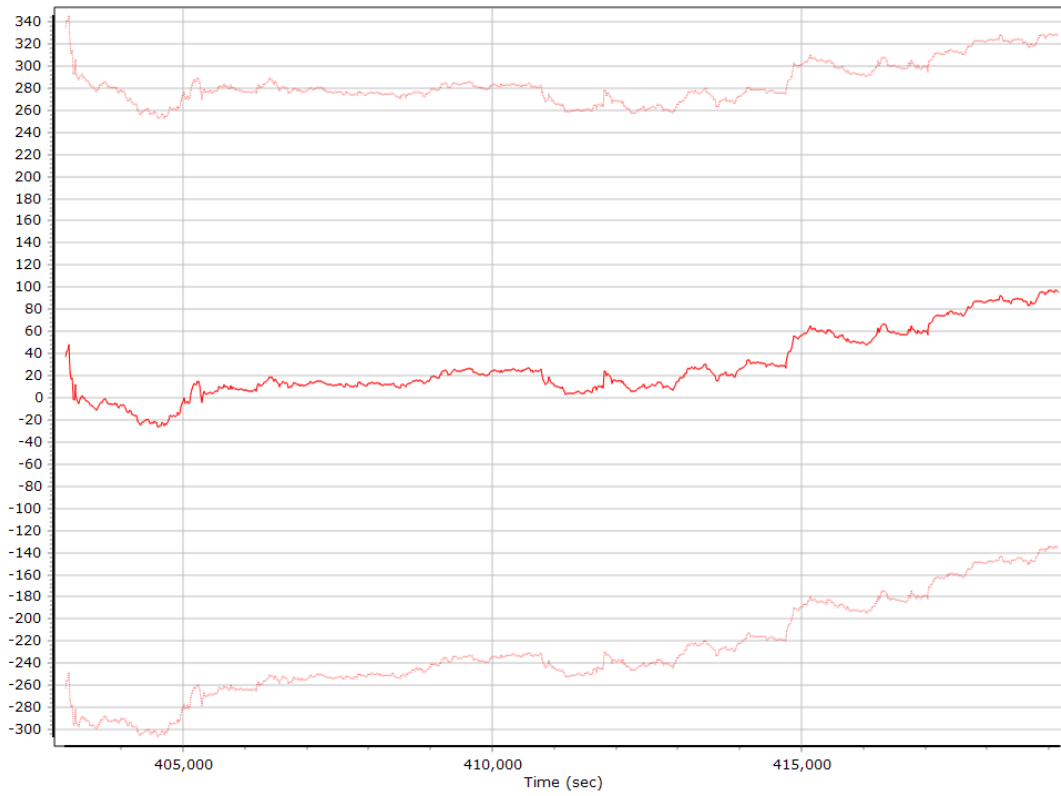
### Accelerometer Scale Error (ppm)



### X Accelerometer Scale Error (ppm)



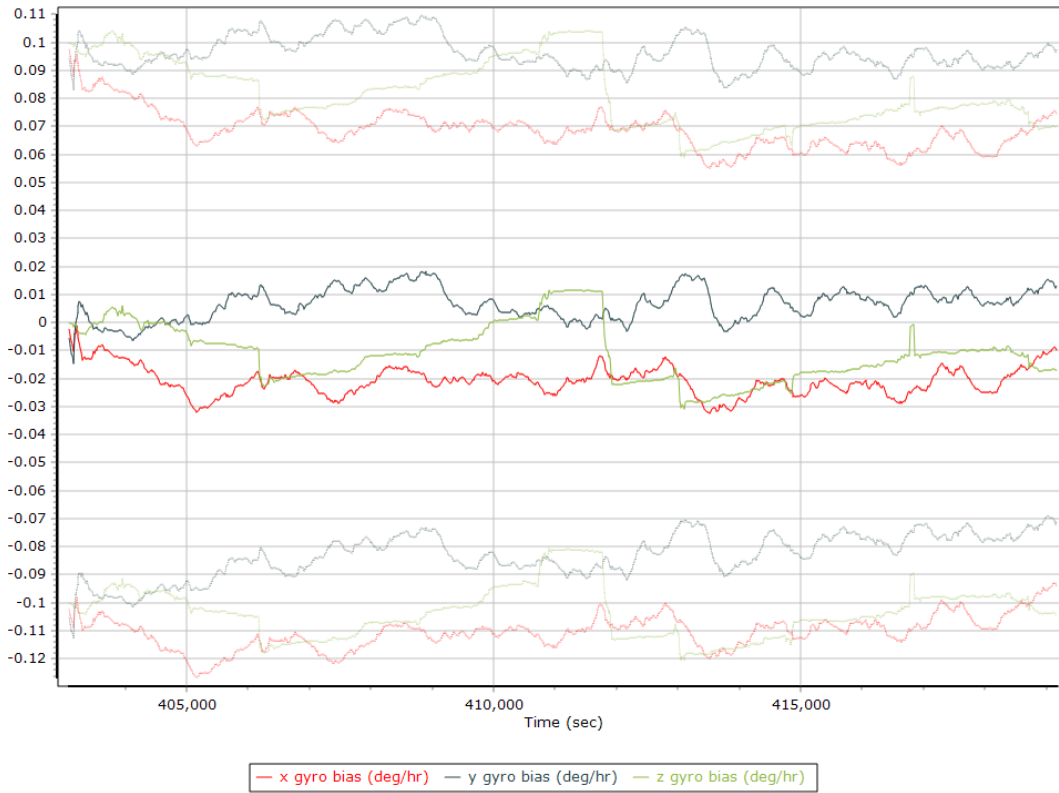
### Y Accelerometer Scale Error (ppm)



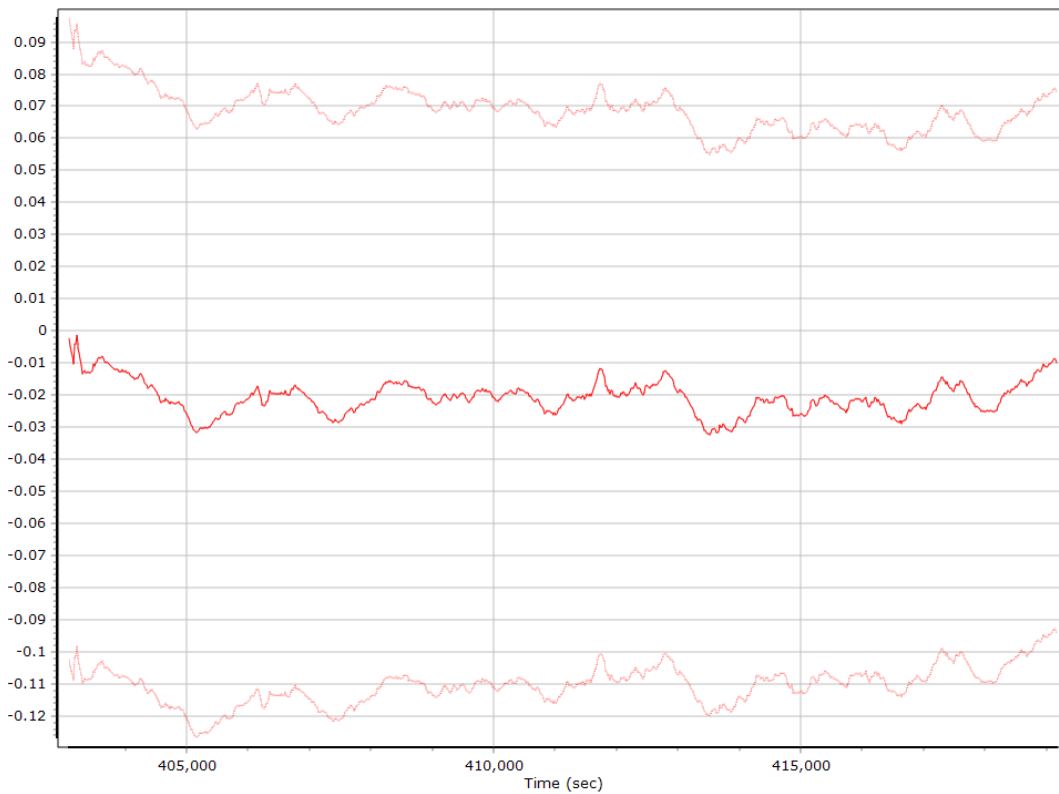
### Z Accelerometer Scale Error (ppm)



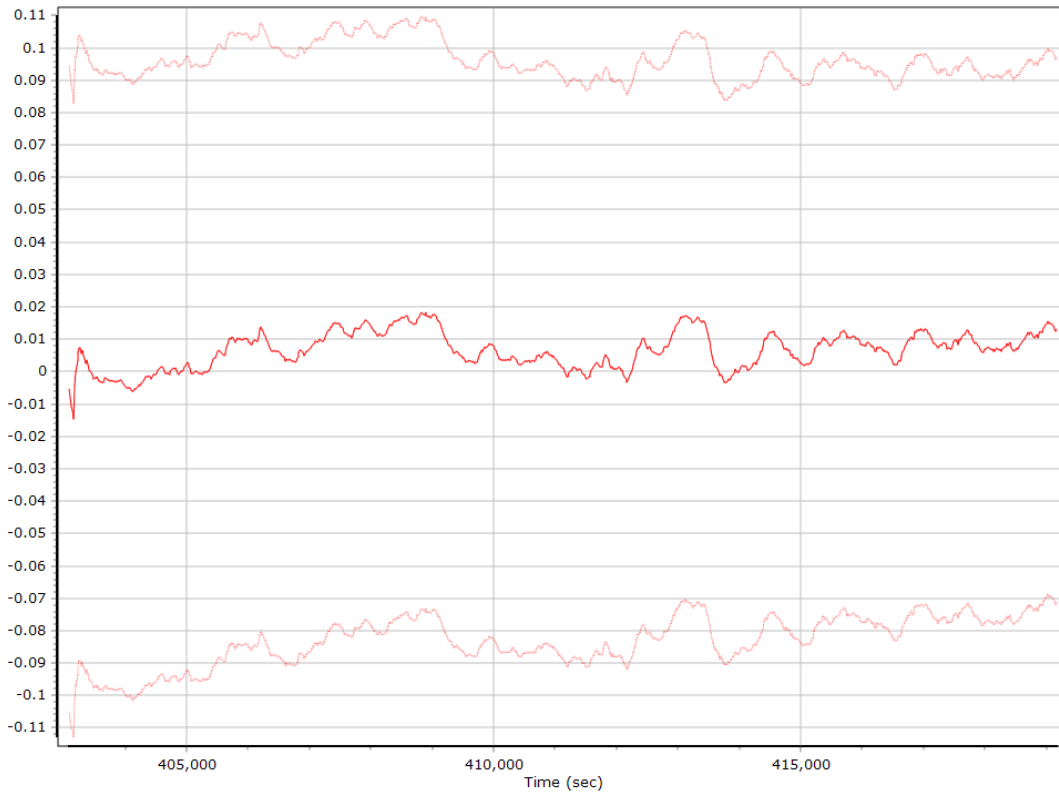
### Gyro Bias (deg/h)



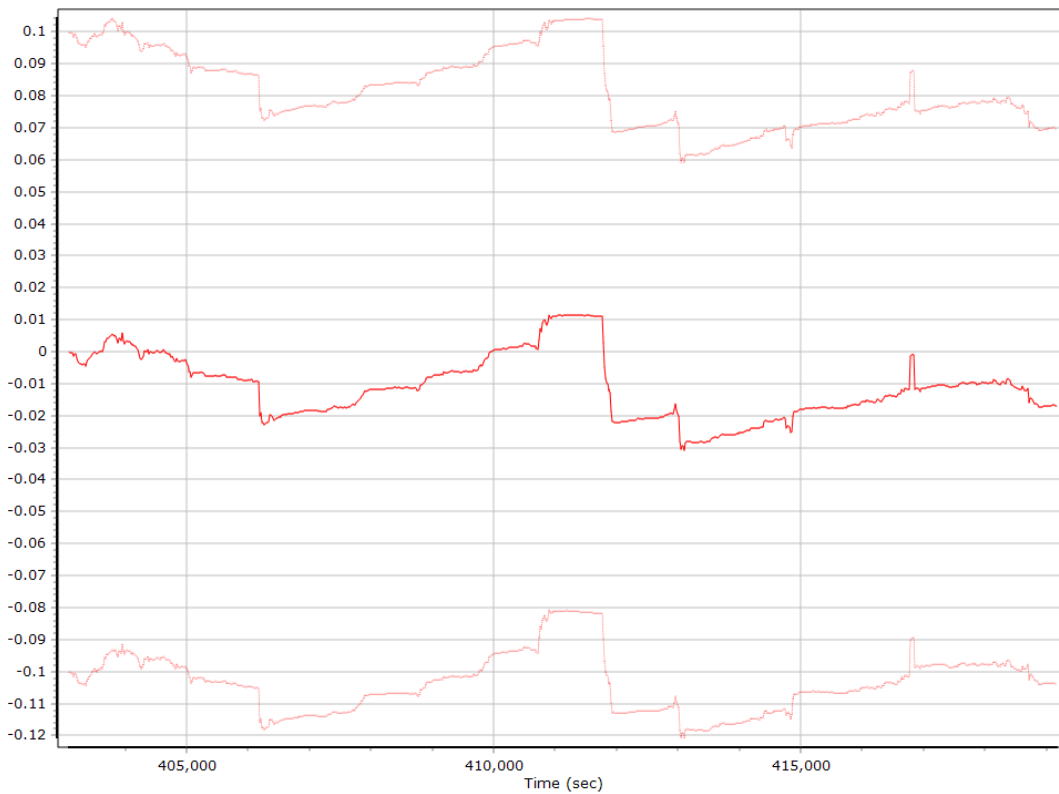
### X Gyro Bias (deg/h)



### Y Gyro Bias (deg/h)



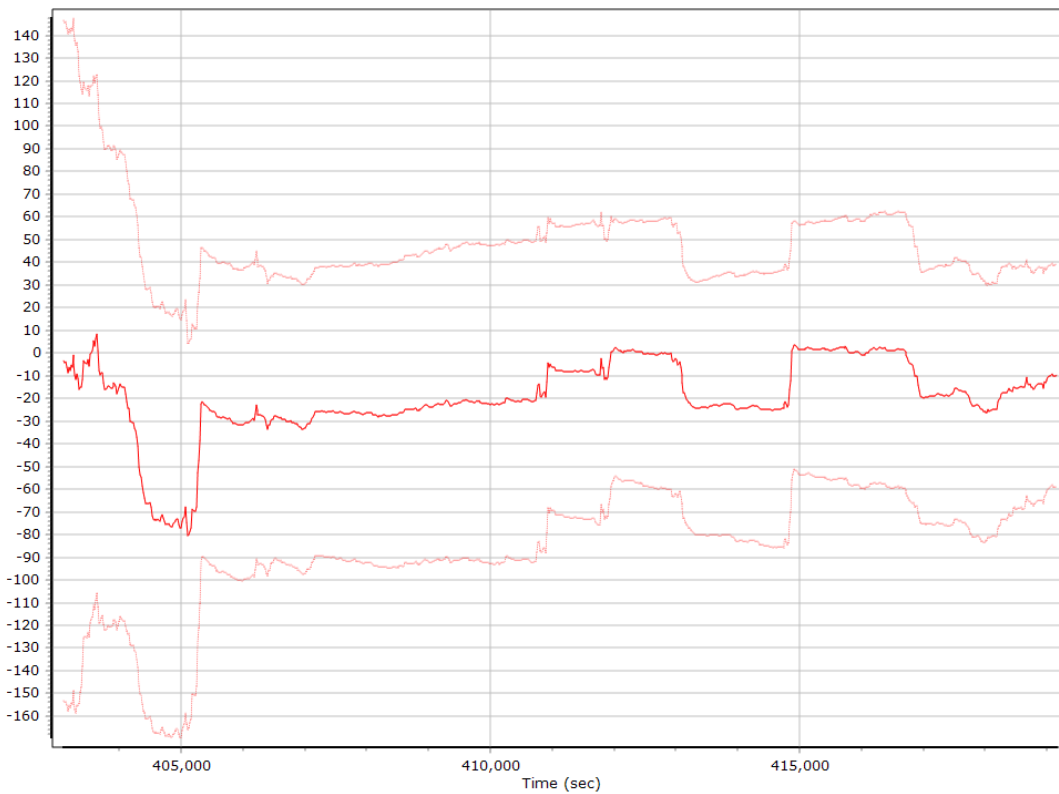
### Z Gyro Bias (deg/h)



### Gyro Scale Error (ppm)

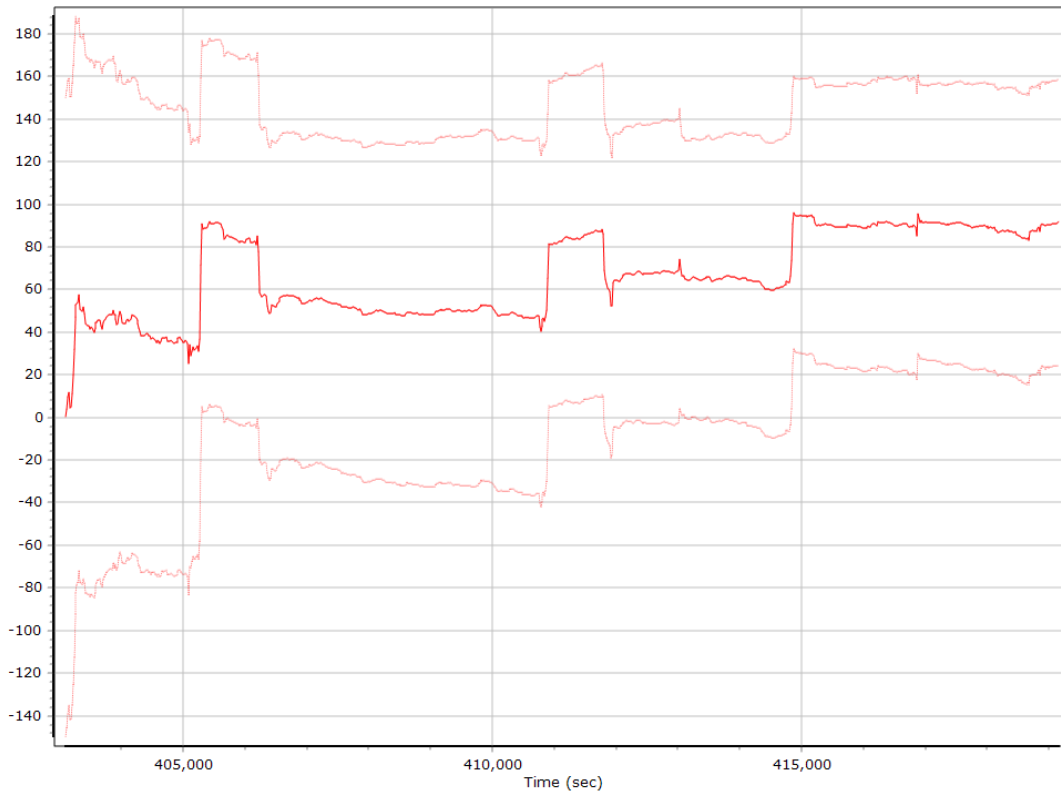


### X Gyro Scale Error (ppm)

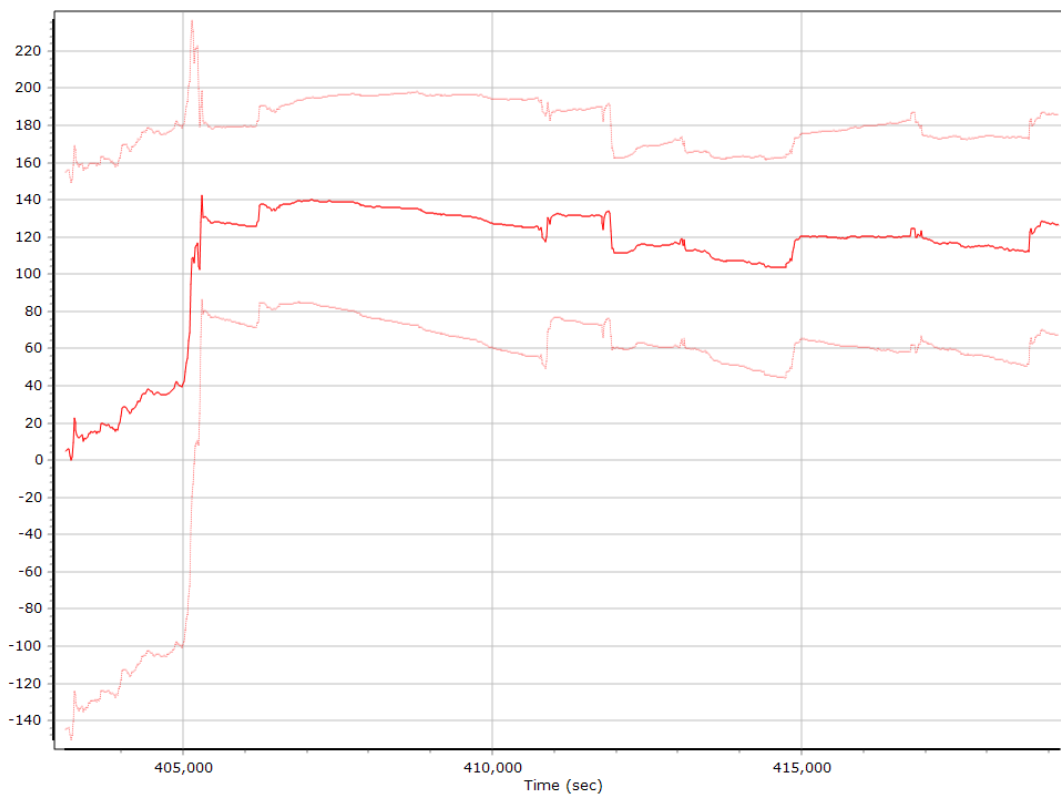




### Y Gyro Scale Error (ppm)

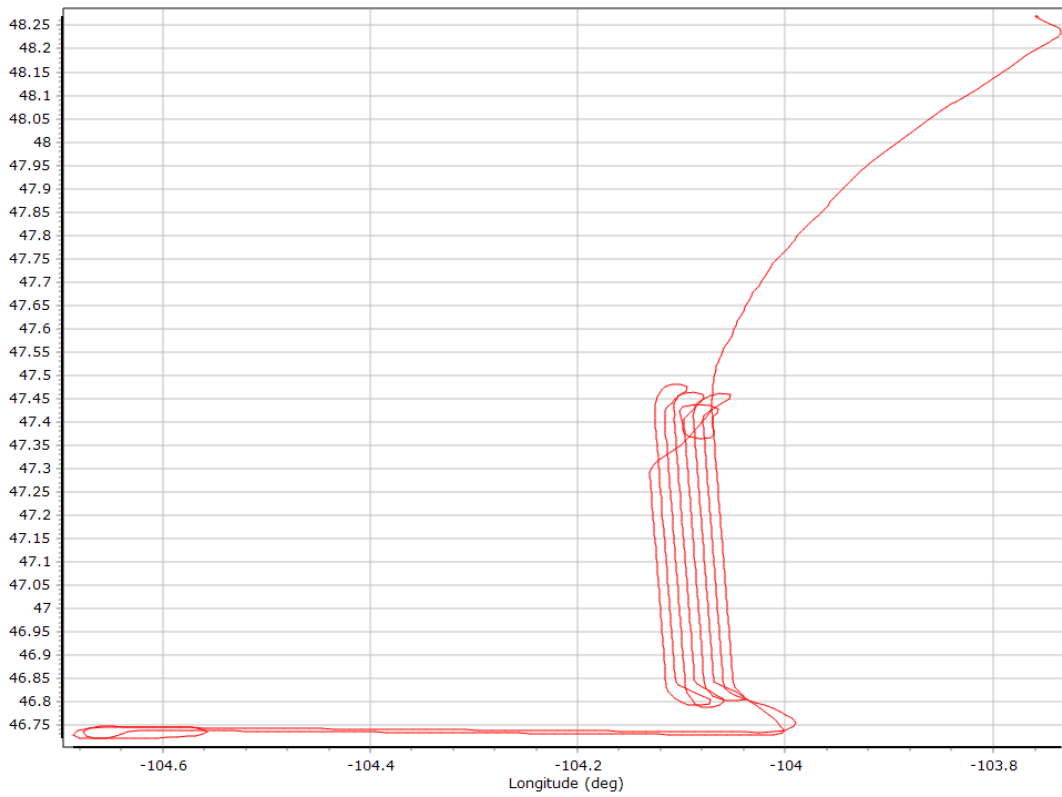


### Z Gyro Scale Error (ppm)



## Smoothed Trajectory Information

### Top View



### Altitude

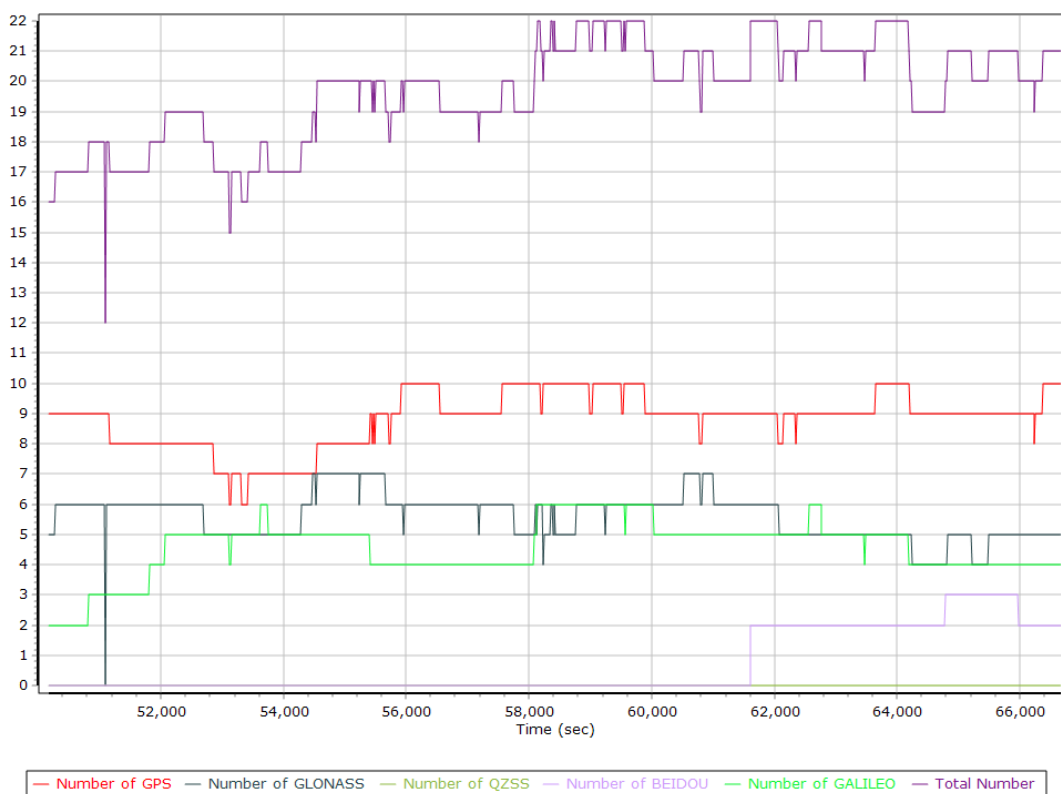


## GNSS QC

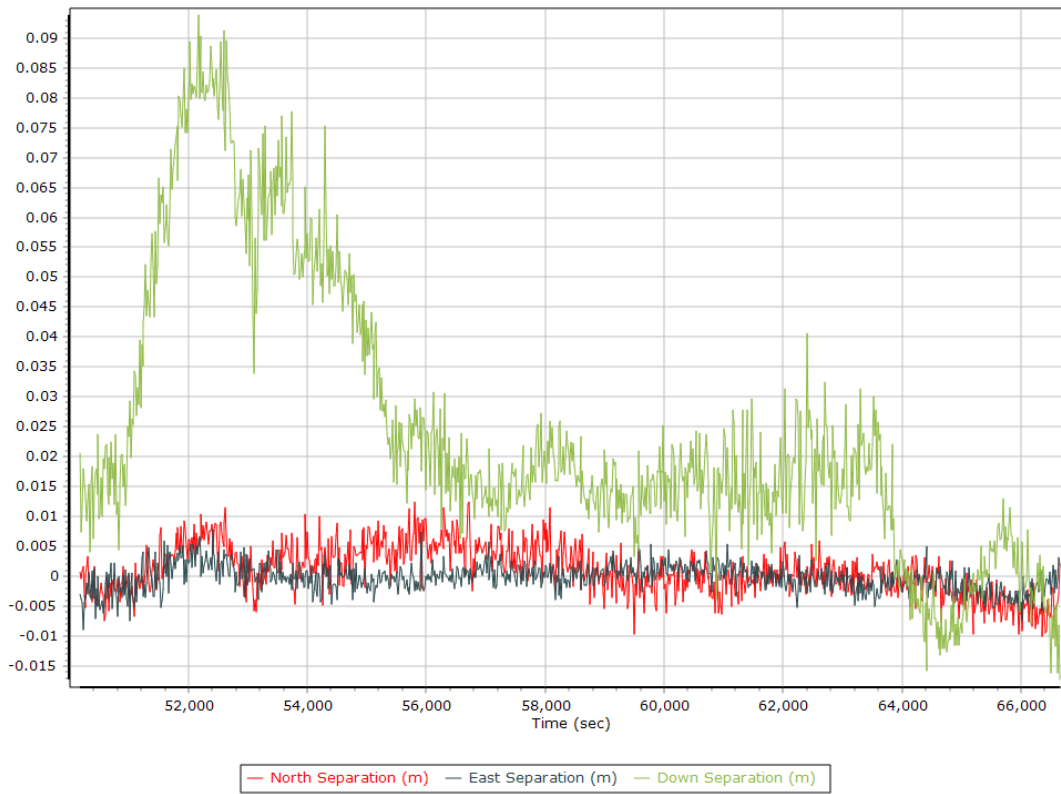
### GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	6	10	9
Number of GLONASS SV	0	7	6
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	3	1
Number of GALILEO SV	0	6	5
Total number of SV	12	22	20
PDOP	1.00	2.16	1.24
QC Solution Gaps	0.00	0.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	16663.00	0.00	0.00
Percentage	100.00	0.00	0.00

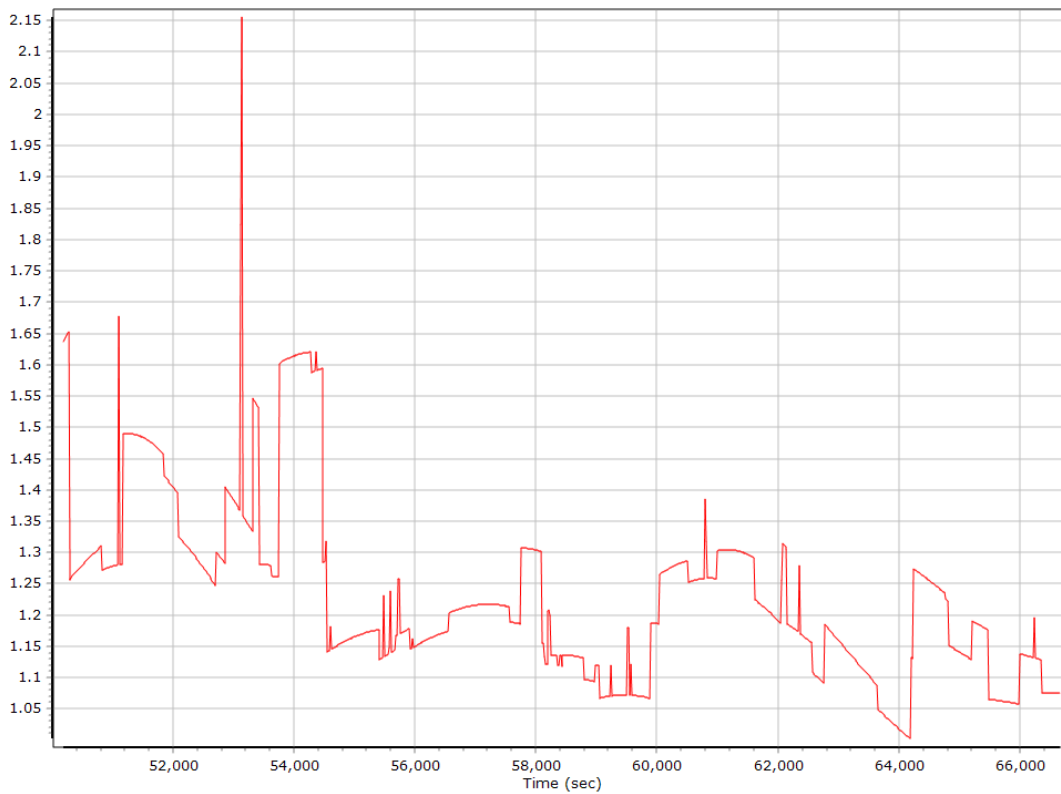
### Num SVs in solution



## Forward/Reverse Separation



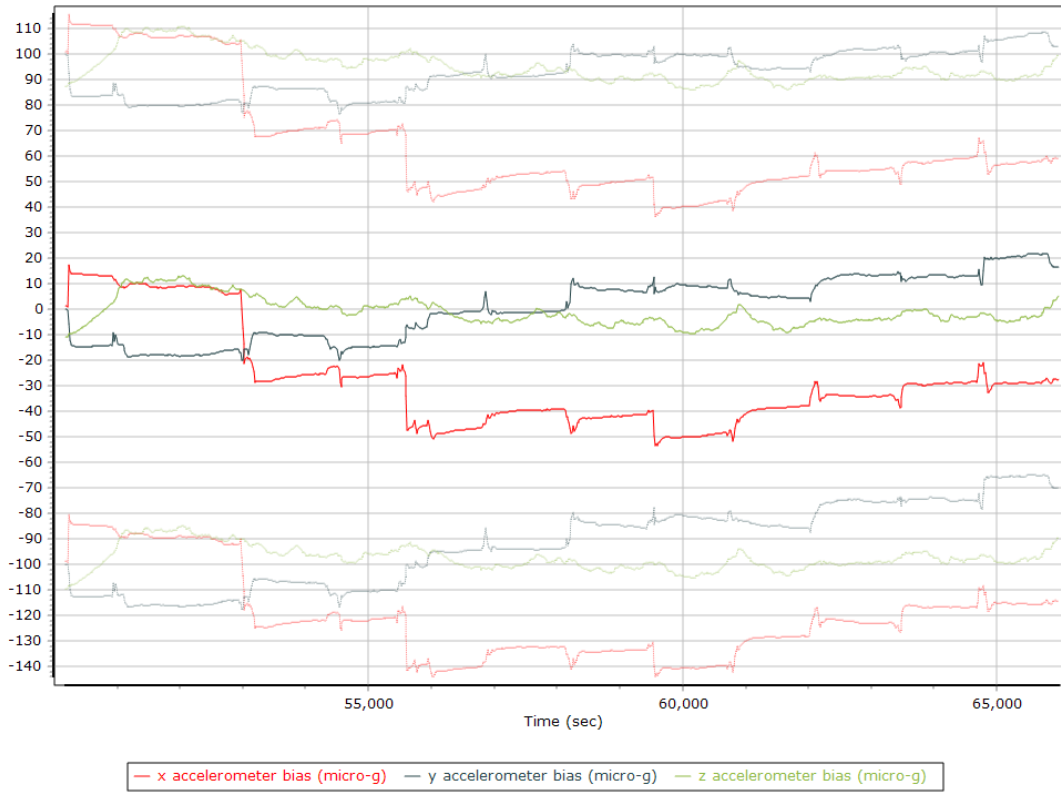
## PDOP



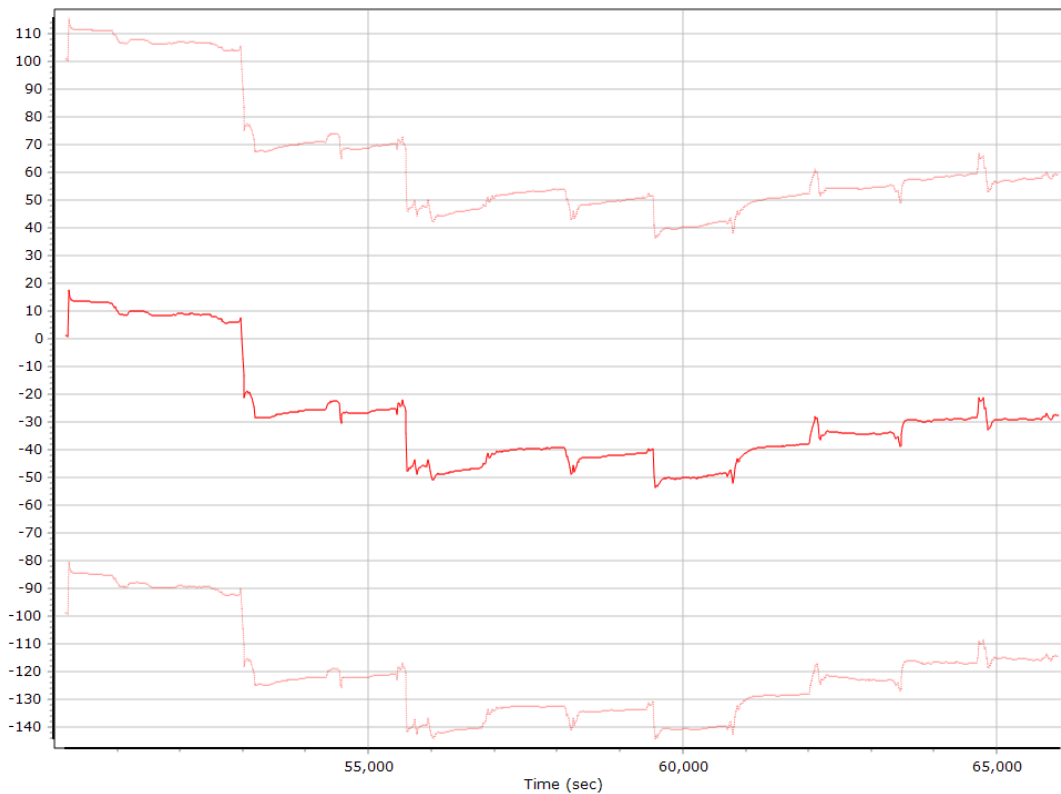
## IN-Fusion QC

### Forward Processed Estimated Errors, Reference Frame

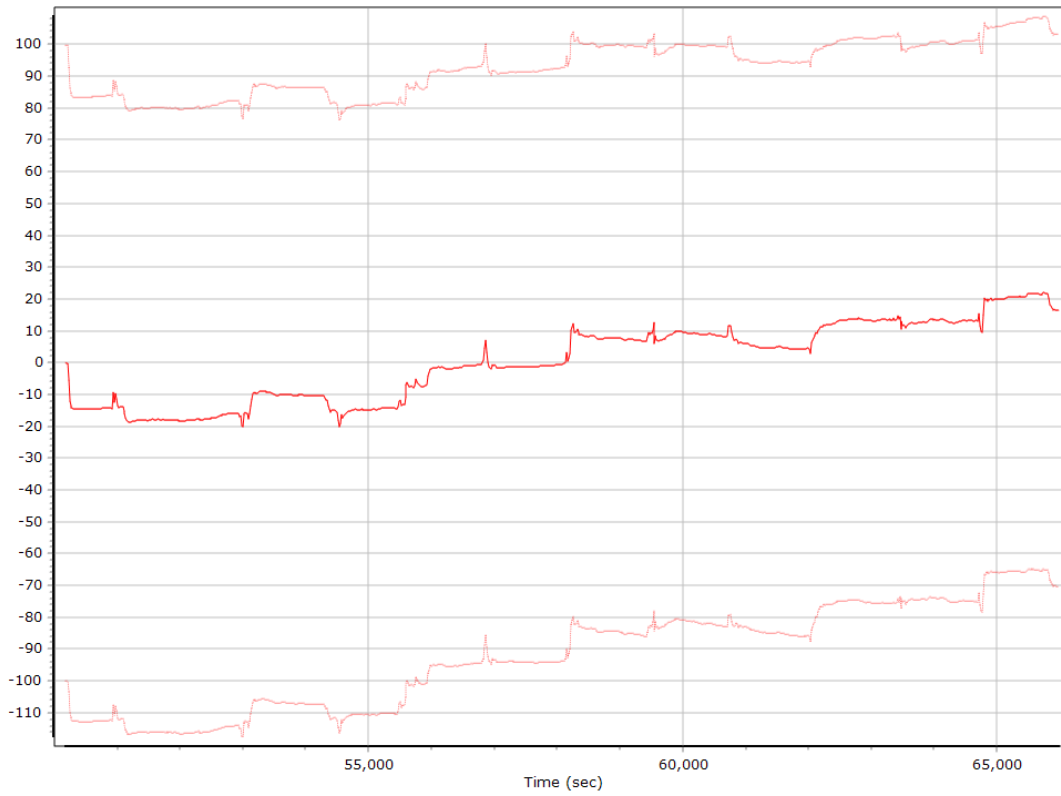
#### Accelerometer Bias (micro-g)



#### X Accelerometer Bias (micro-g)



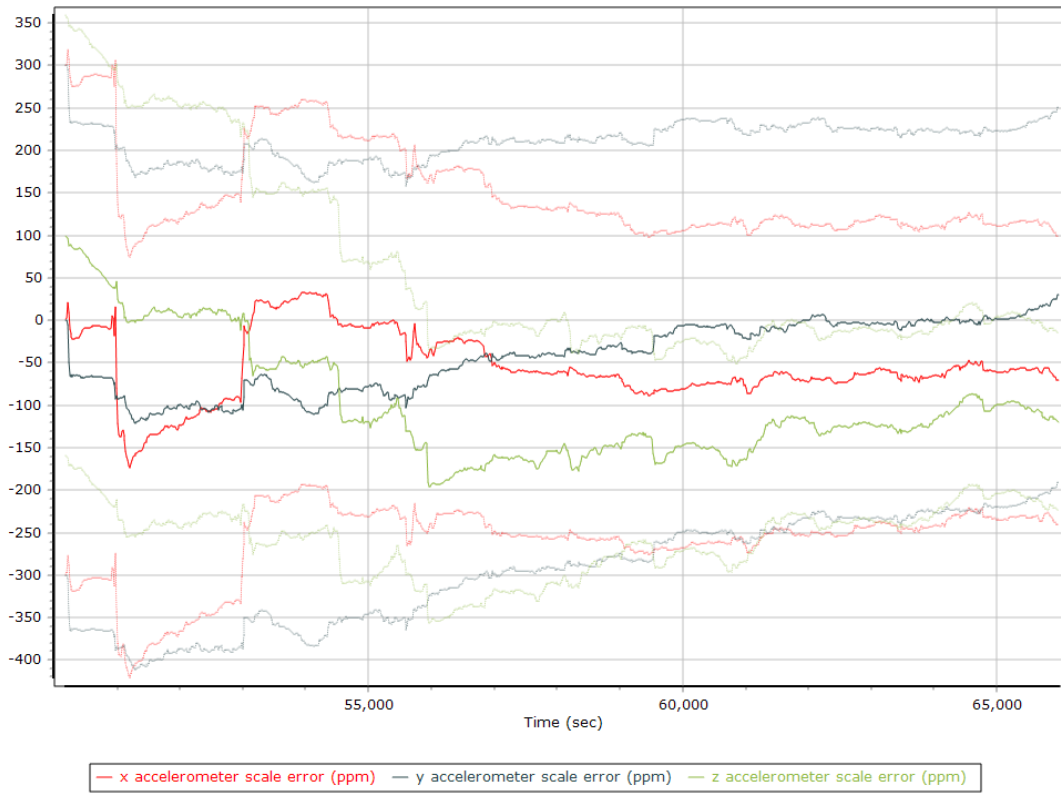
### Y Accelerometer Bias (micro-g)



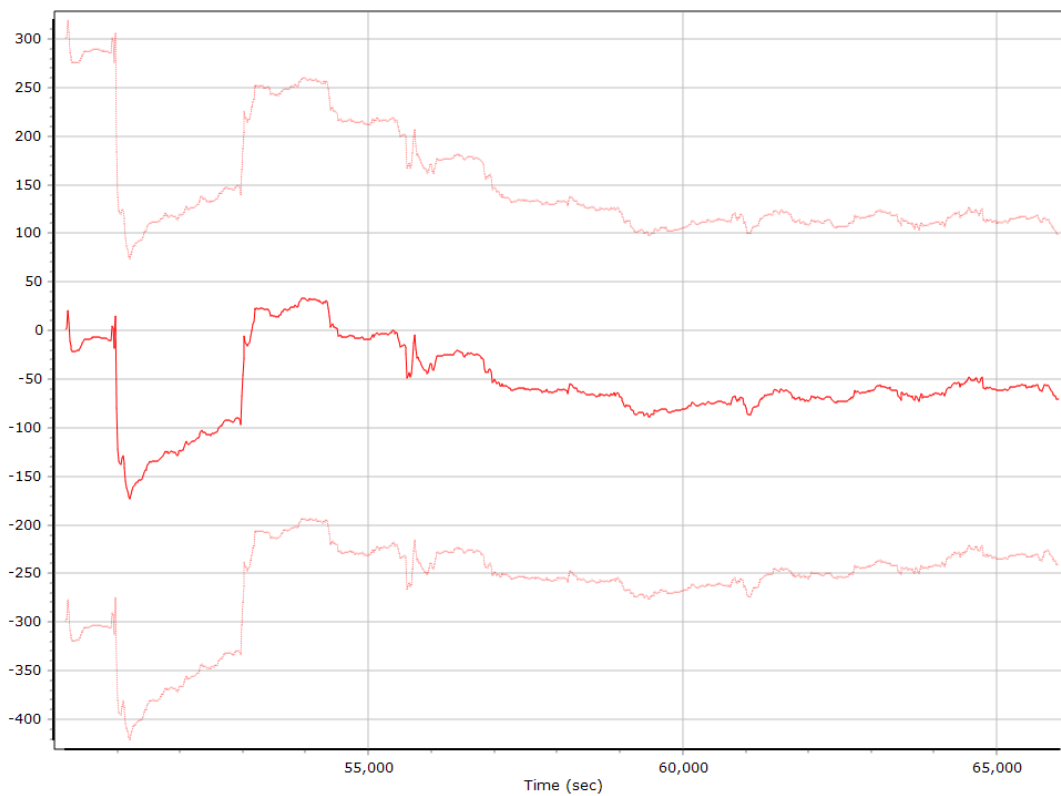
### Z Accelerometer Bias (micro-g)



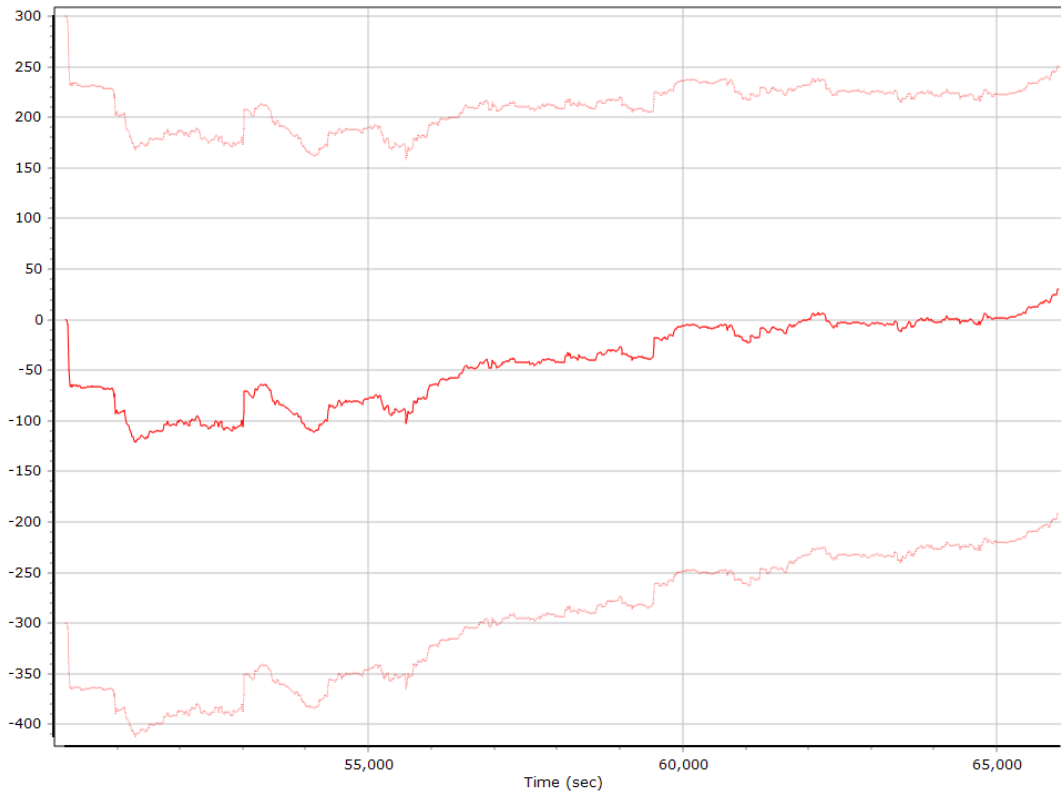
### Accelerometer Scale Error (ppm)



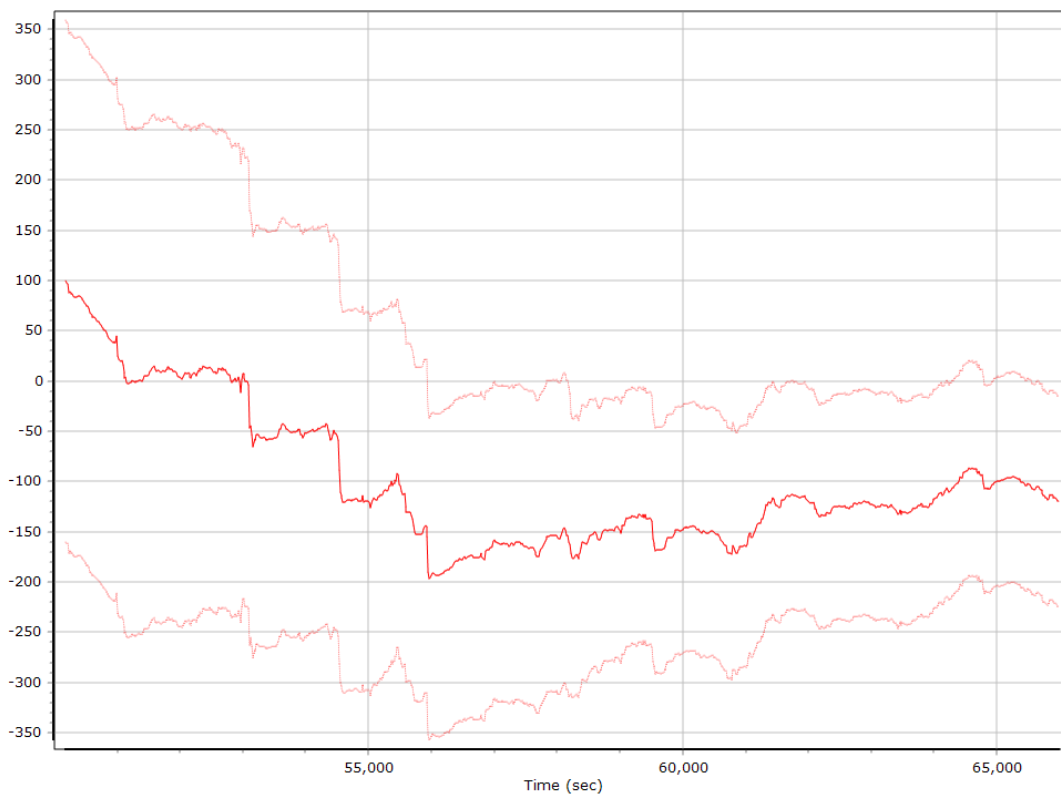
### X Accelerometer Scale Error (ppm)



### Y Accelerometer Scale Error (ppm)

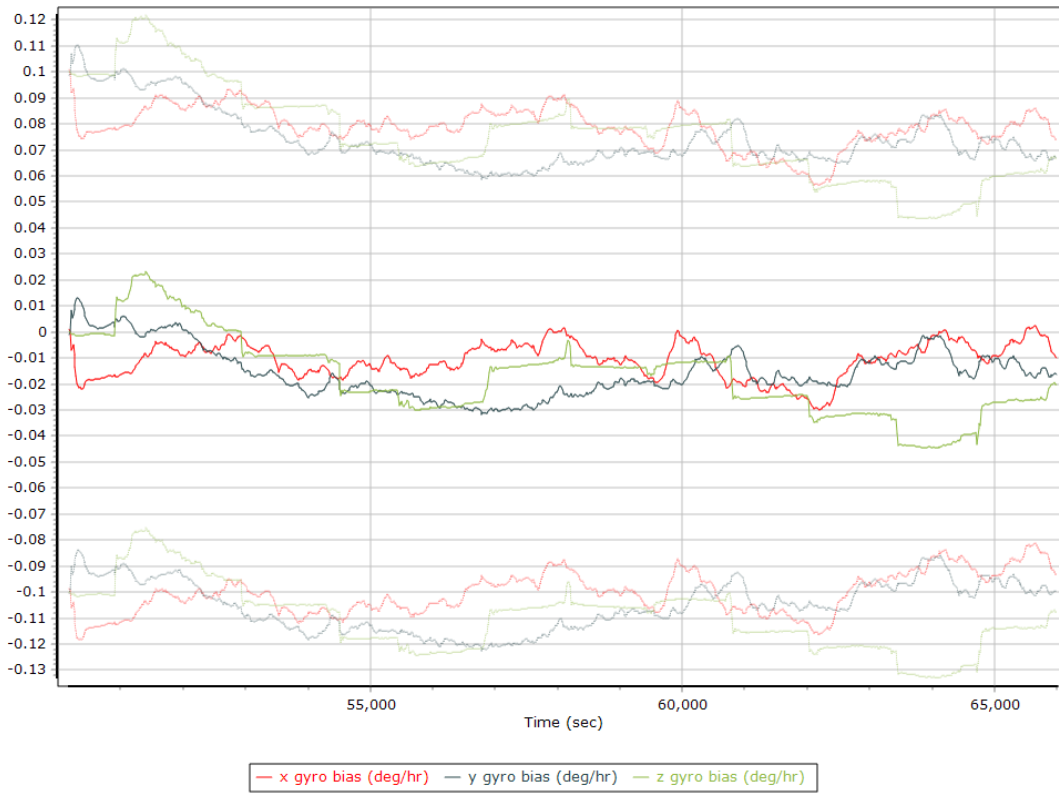


### Z Accelerometer Scale Error (ppm)

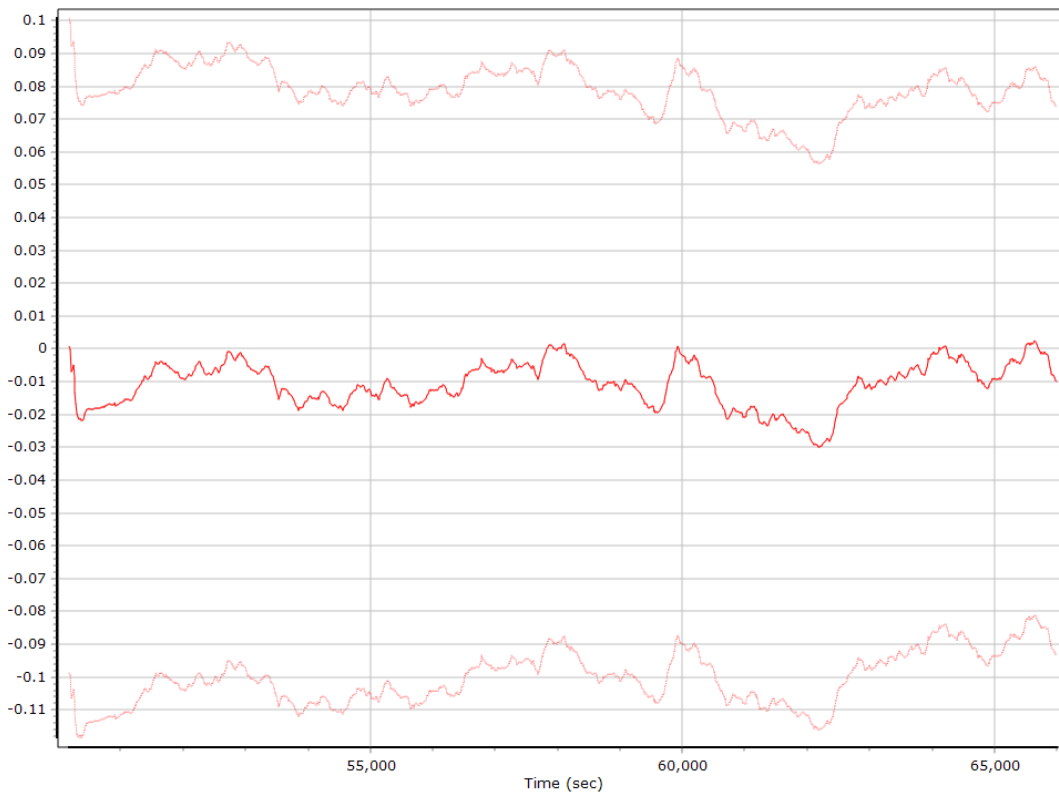




### Gyro Bias (deg/h)



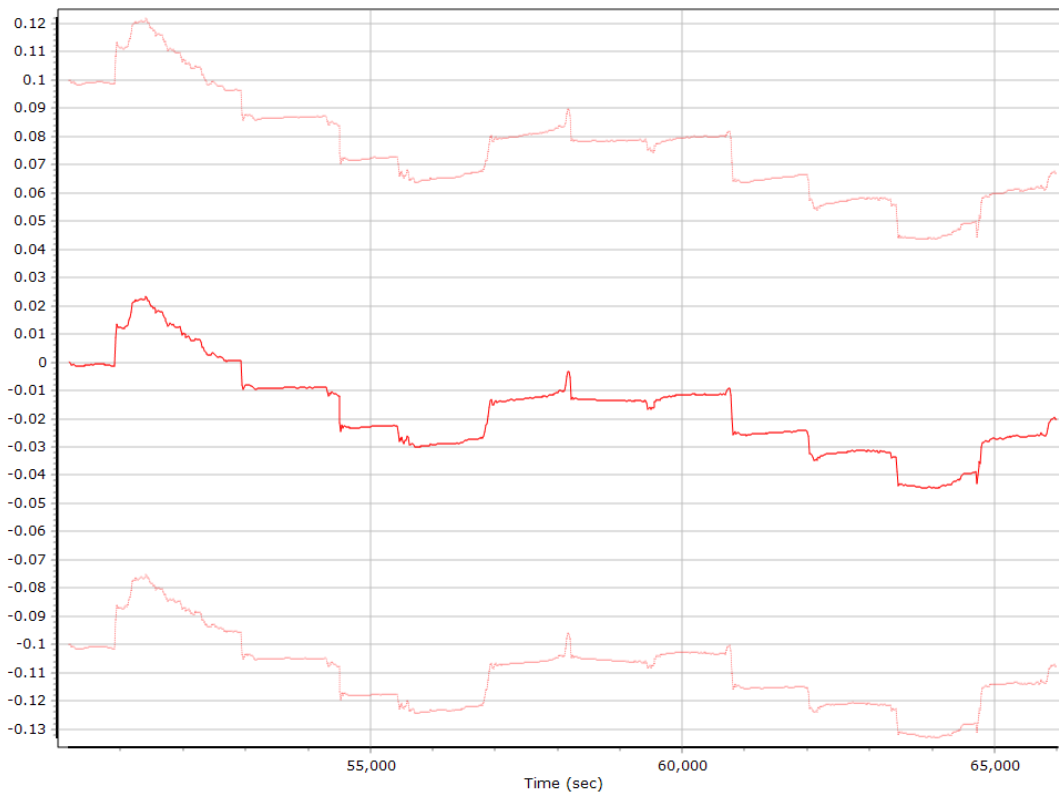
### X Gyro Bias (deg/h)



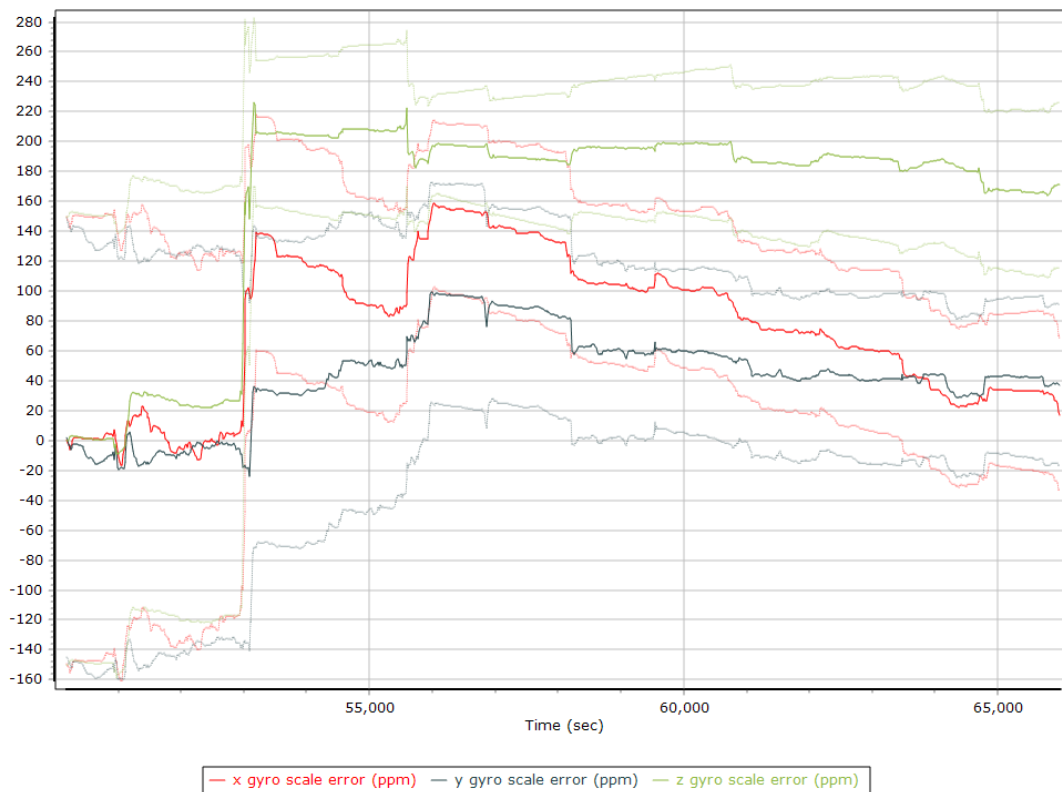
### Y Gyro Bias (deg/h)



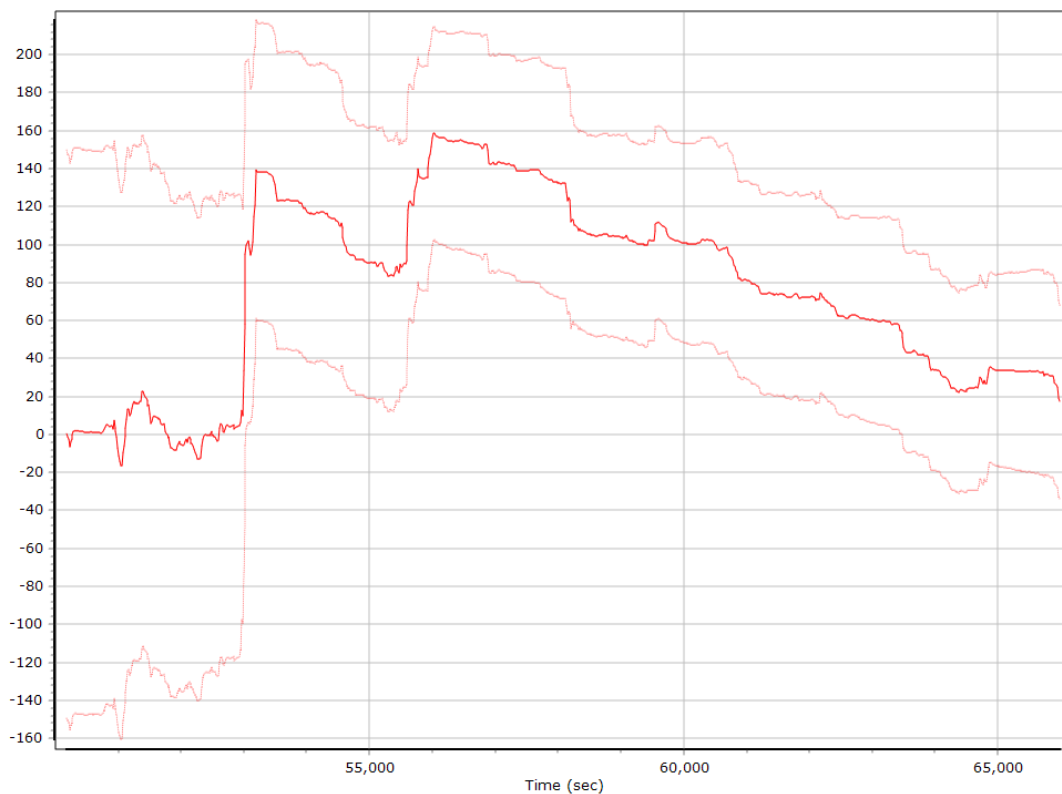
### Z Gyro Bias (deg/h)



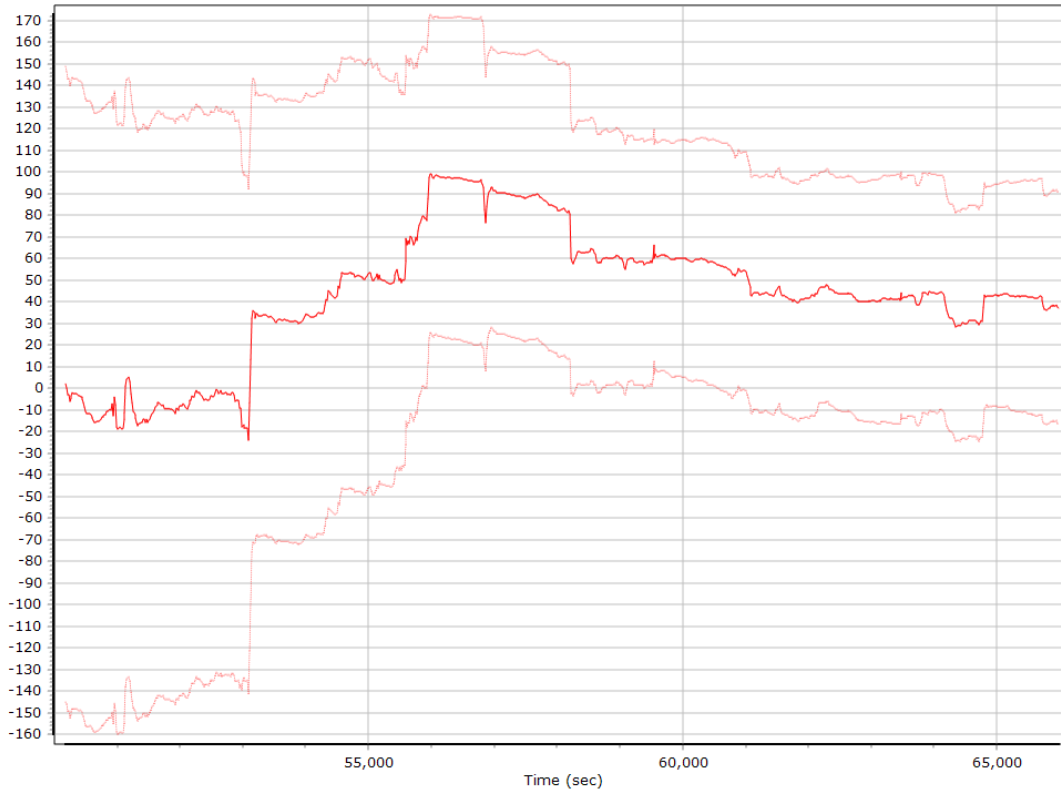
### Gyro Scale Error (ppm)



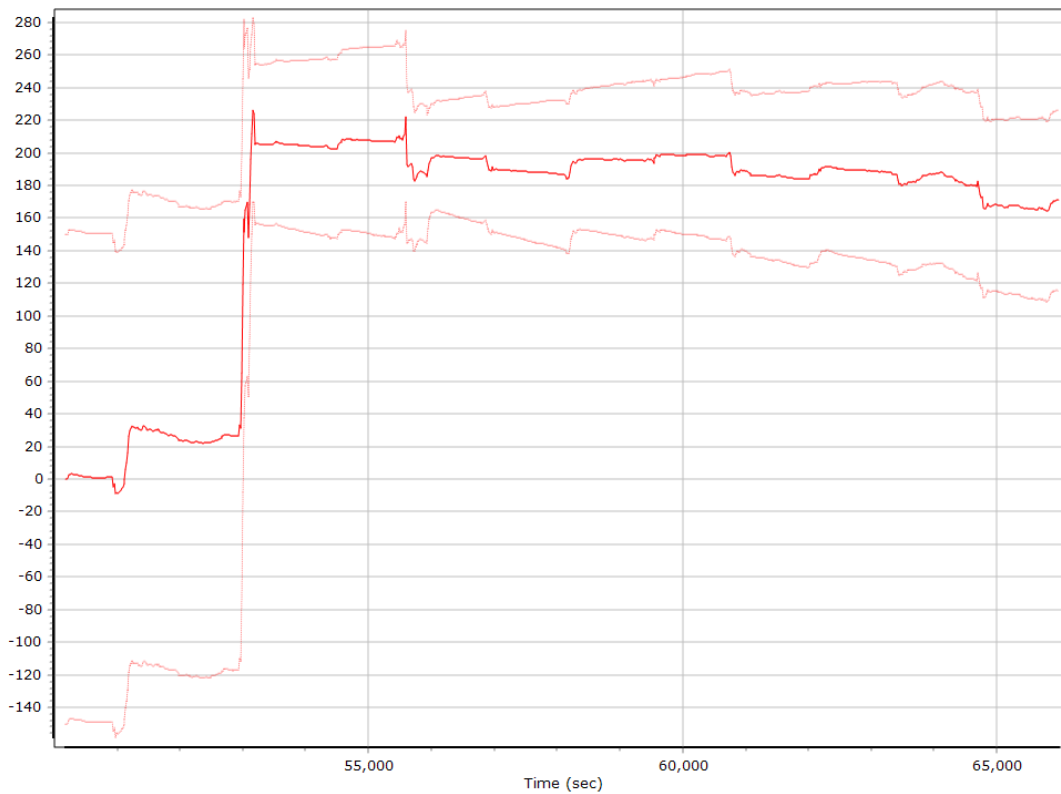
### X Gyro Scale Error (ppm)



### Y Gyro Scale Error (ppm)

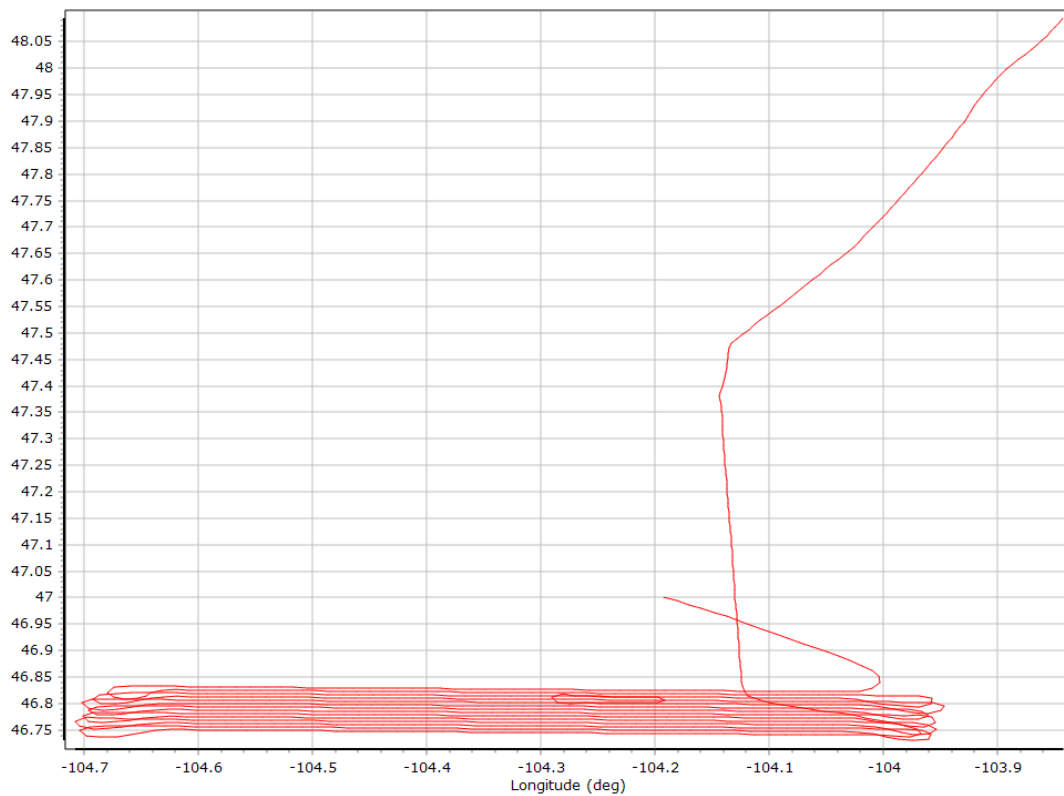


### Z Gyro Scale Error (ppm)

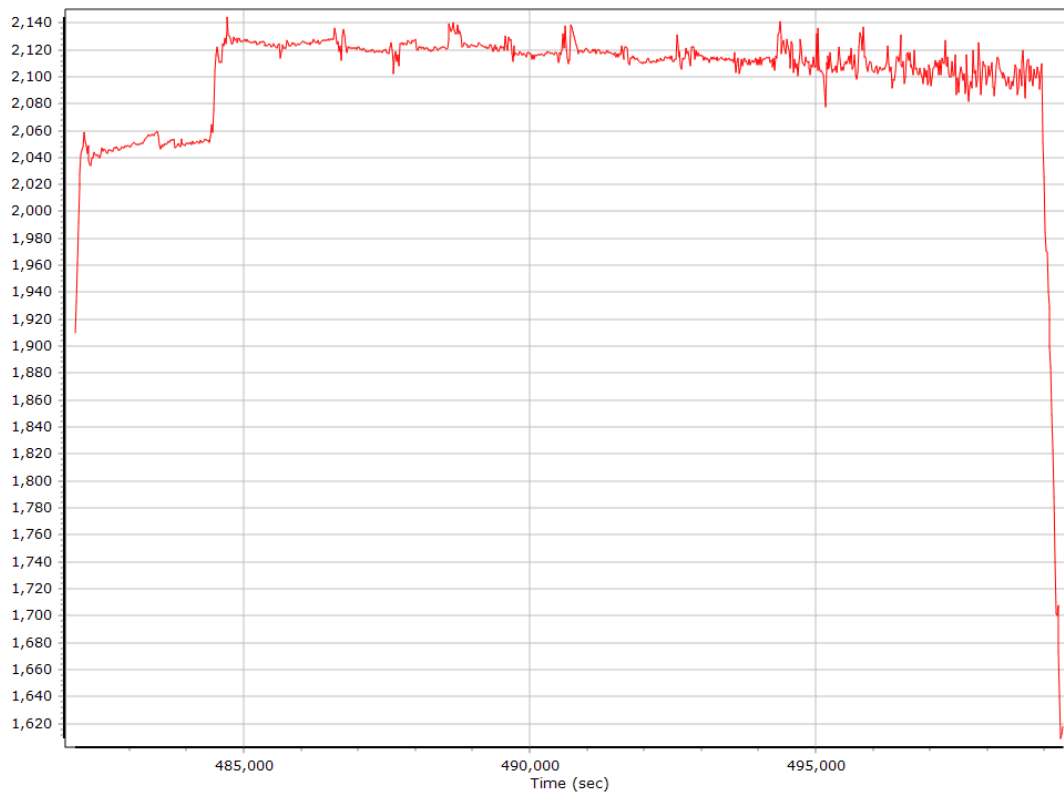


## Smoothed Trajectory Information

### Top View



### Altitude

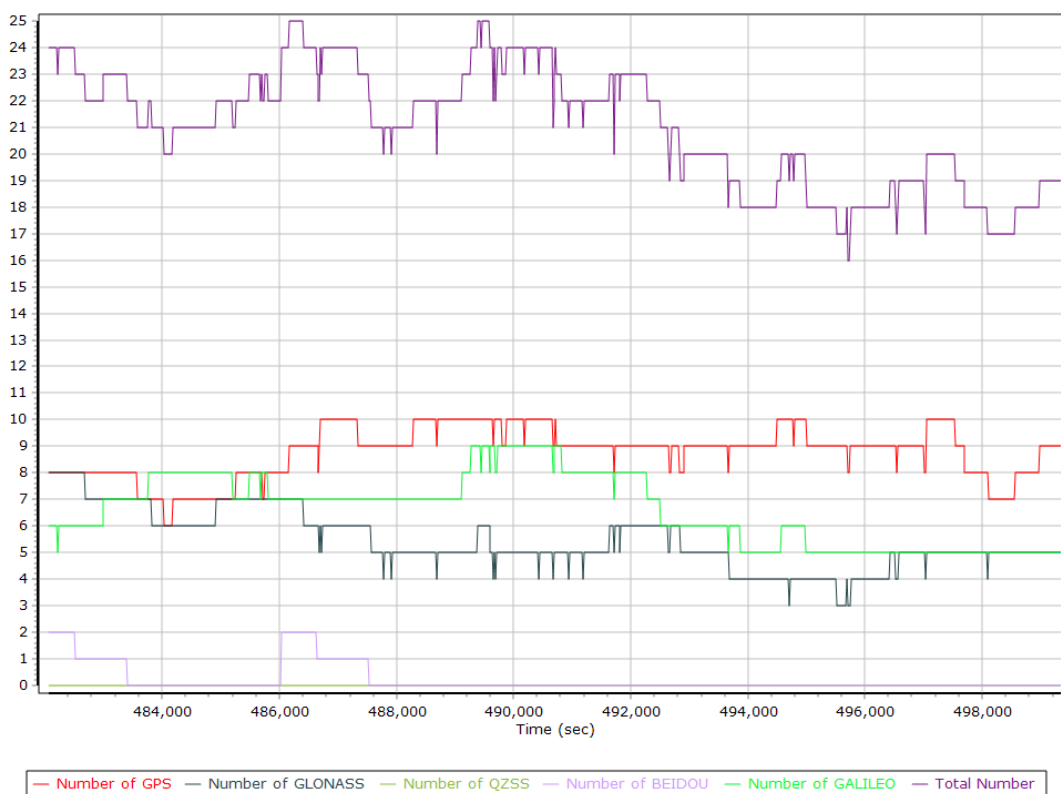


## GNSS QC

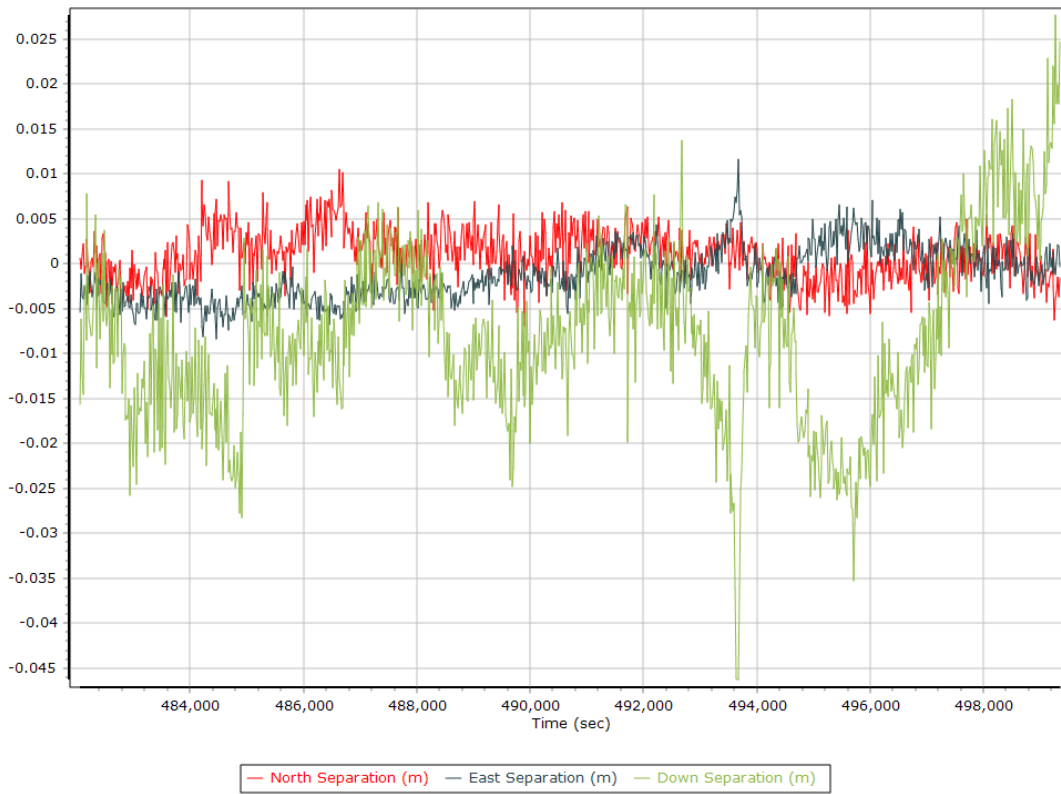
### GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	6	10	9
Number of GLONASS SV	0	8	6
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	2	0
Number of GALILEO SV	4	9	7
Total number of SV	14	25	21
PDOP	0.95	1.60	1.17
QC Solution Gaps	0.00	0.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	18142.00	0.00	0.00
Percentage	100.00	0.00	0.00

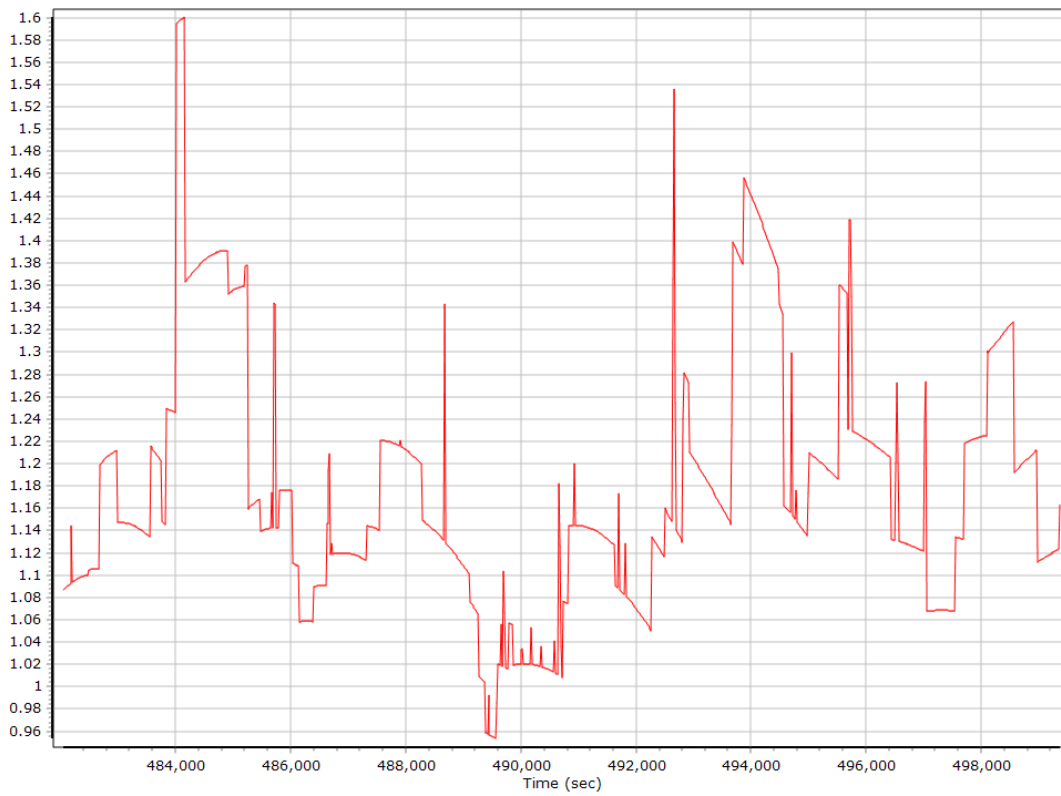
### Num SVs in solution



## Forward/Reverse Separation



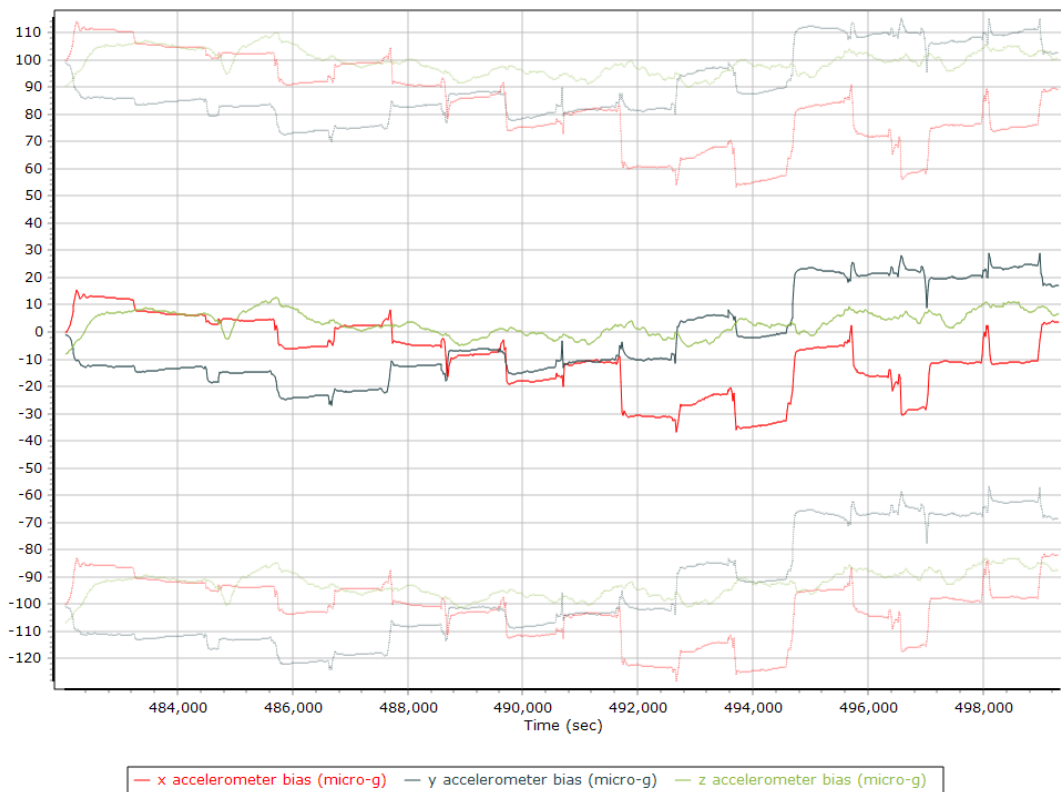
## PDOP



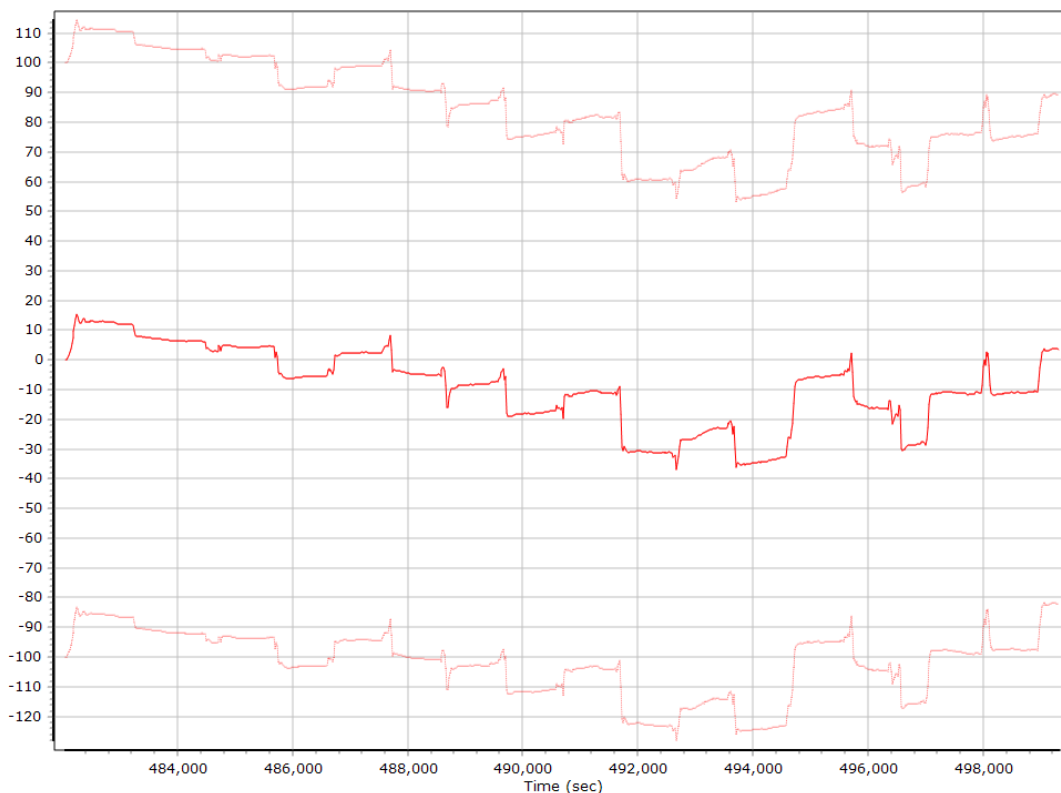
## IN-Fusion QC

### Forward Processed Estimated Errors, Reference Frame

#### Accelerometer Bias (micro-g)

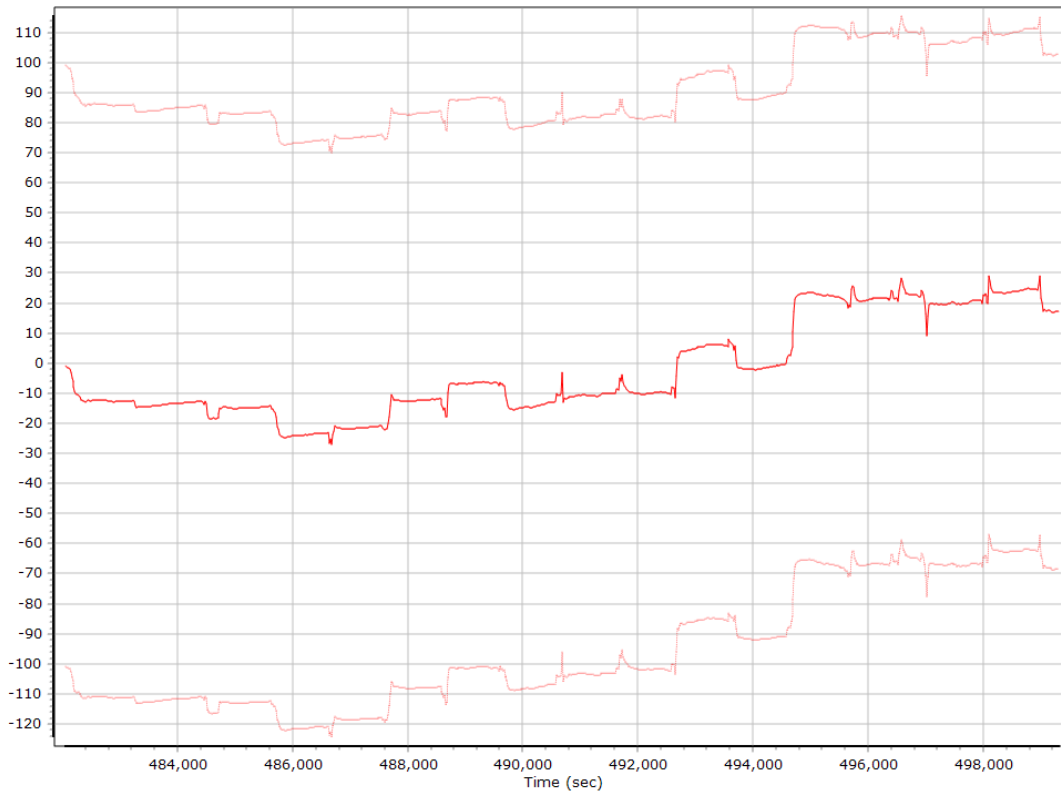


#### X Accelerometer Bias (micro-g)

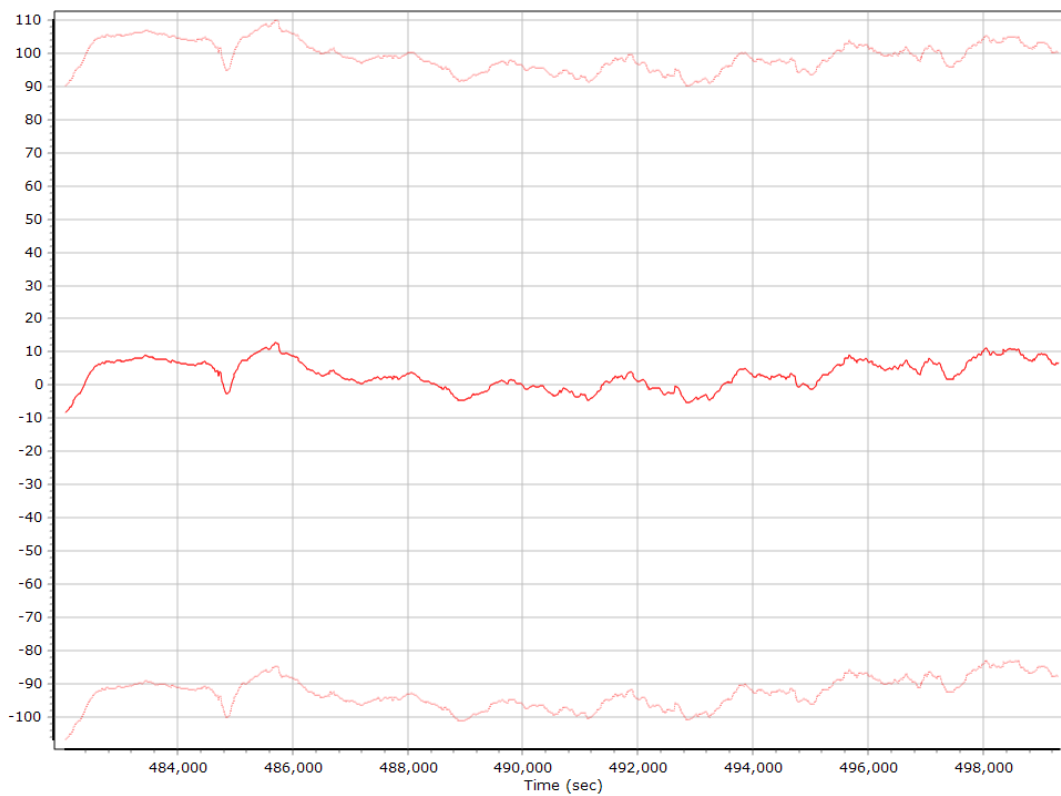




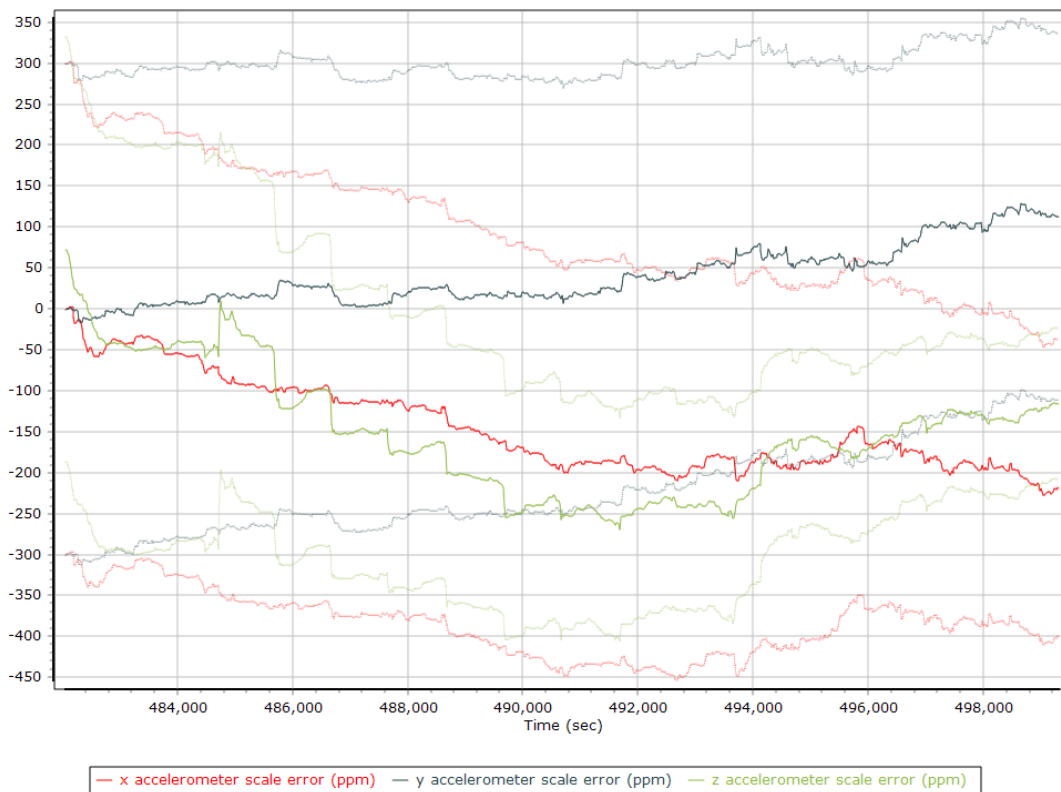
### Y Accelerometer Bias (micro-g)



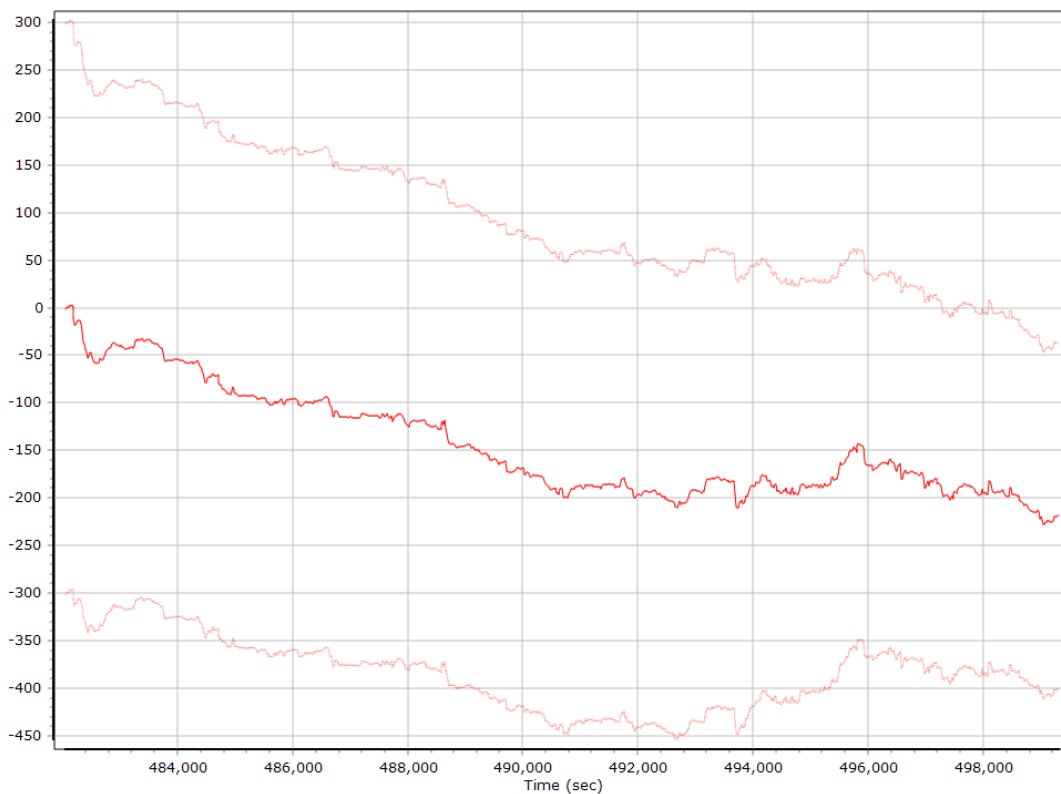
### Z Accelerometer Bias (micro-g)



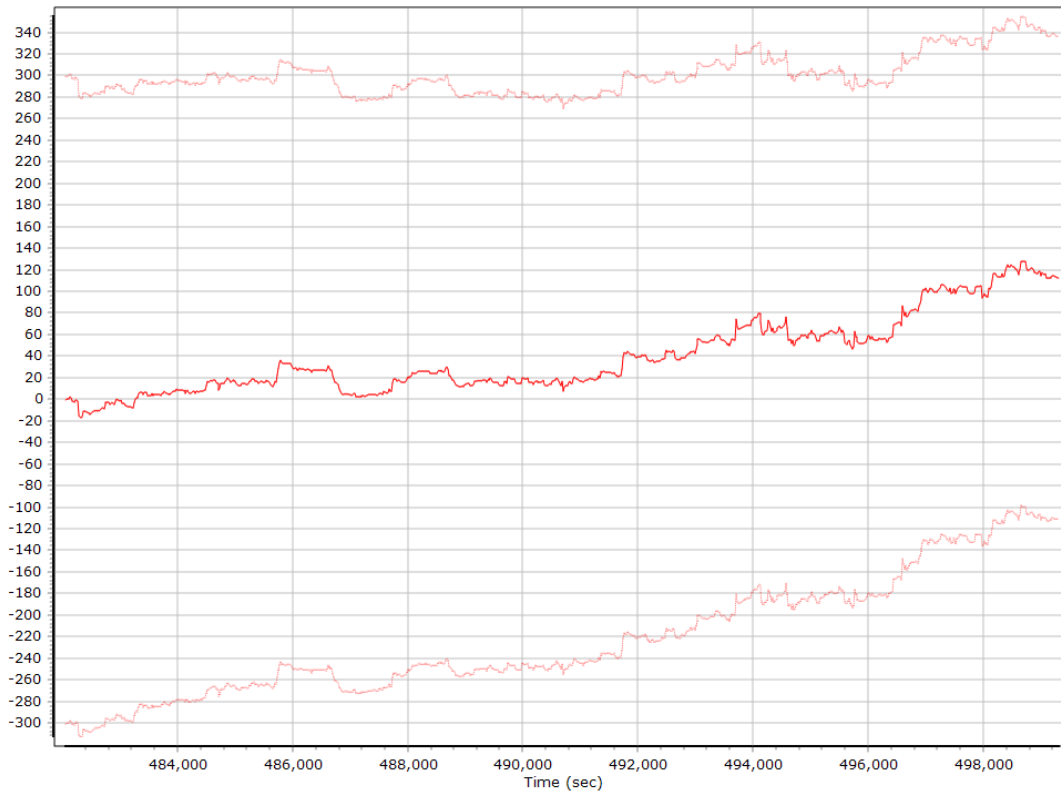
### Accelerometer Scale Error (ppm)



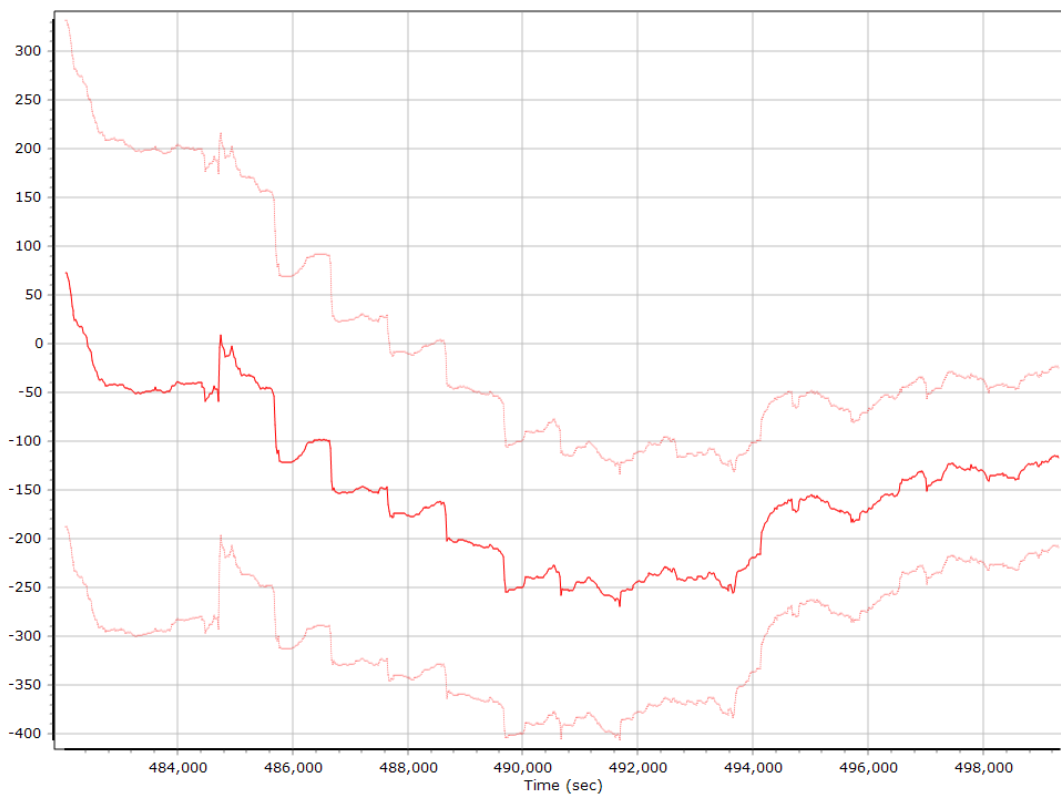
### X Accelerometer Scale Error (ppm)



### Y Accelerometer Scale Error (ppm)



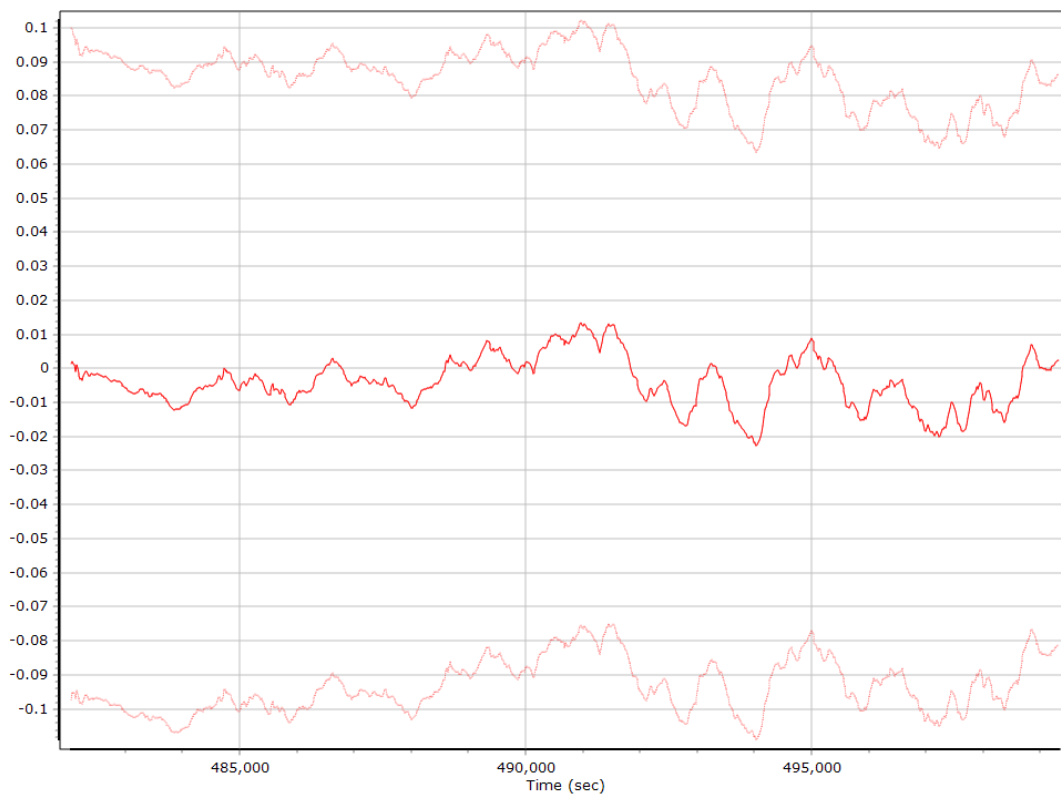
### Z Accelerometer Scale Error (ppm)



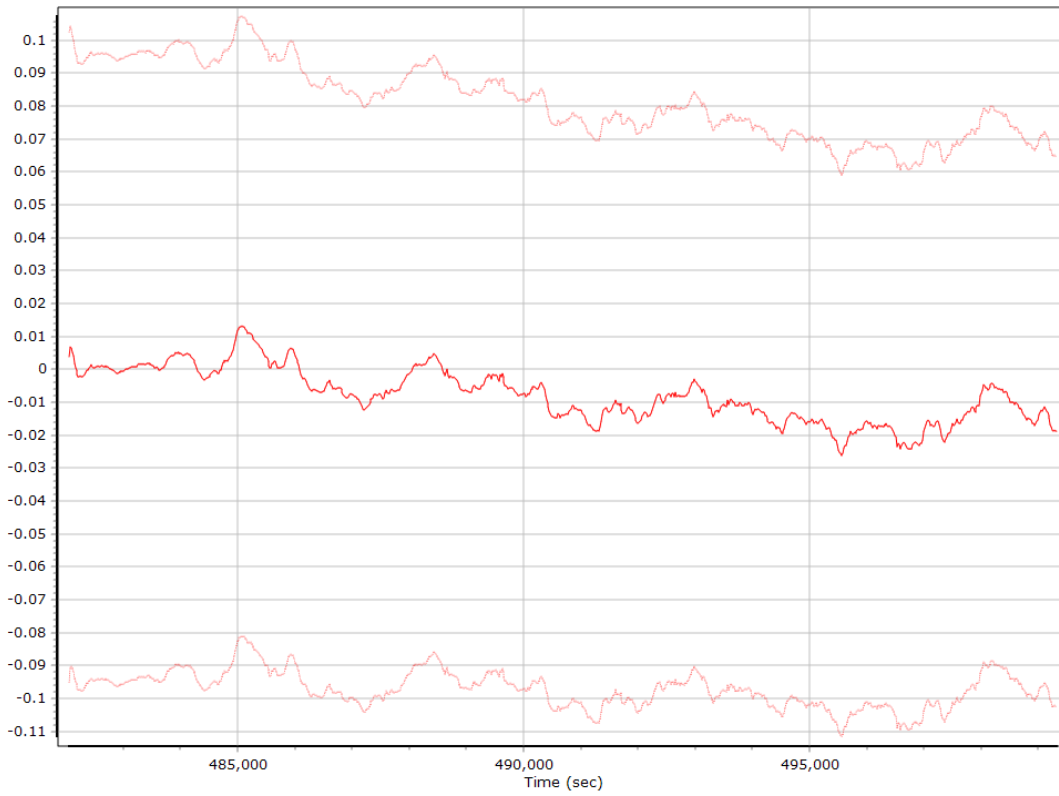
### Gyro Bias (deg/h)



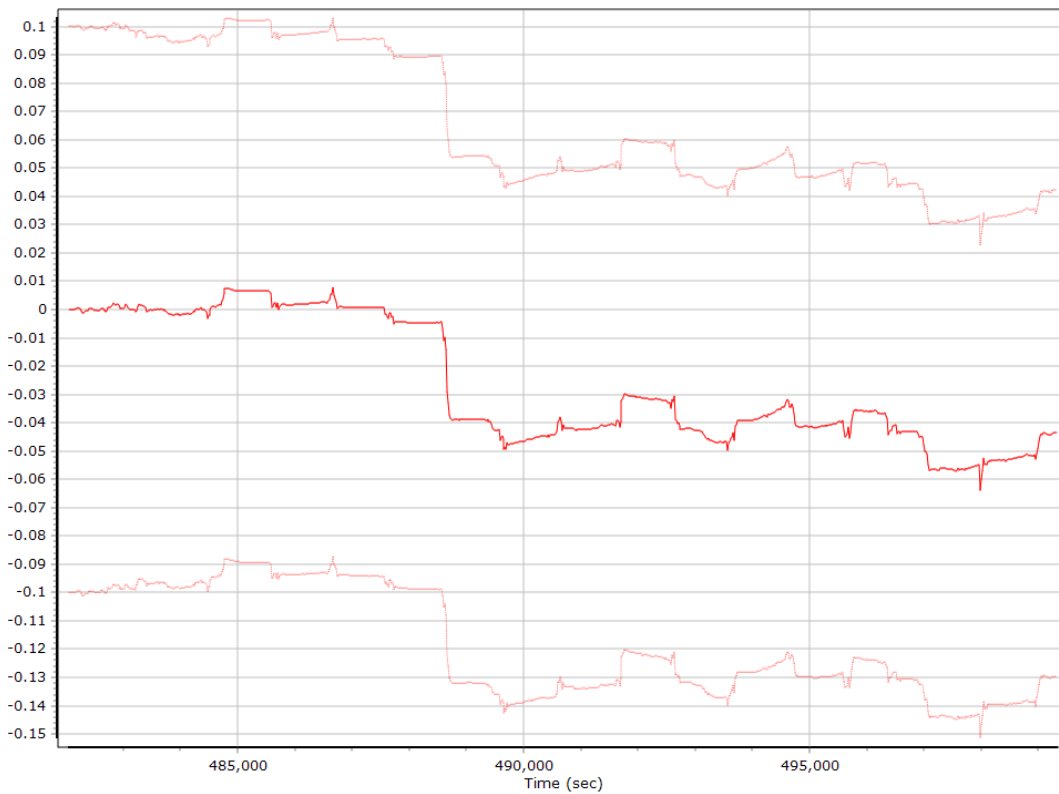
### X Gyro Bias (deg/h)



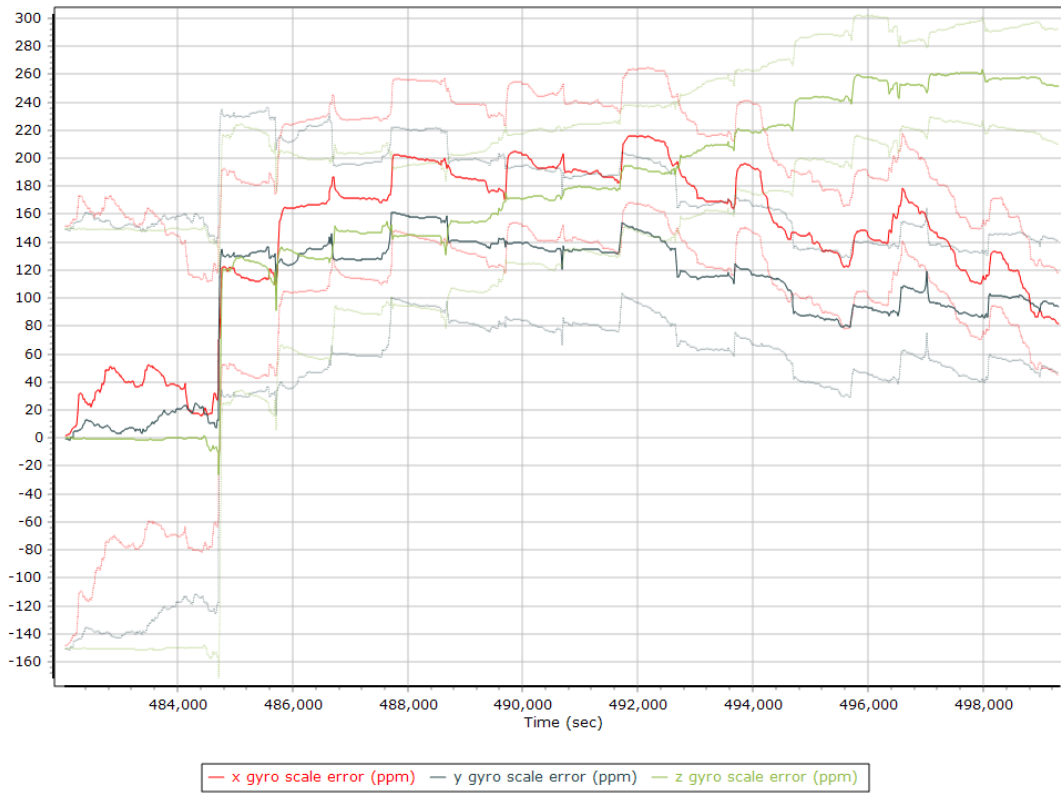
### Y Gyro Bias (deg/h)



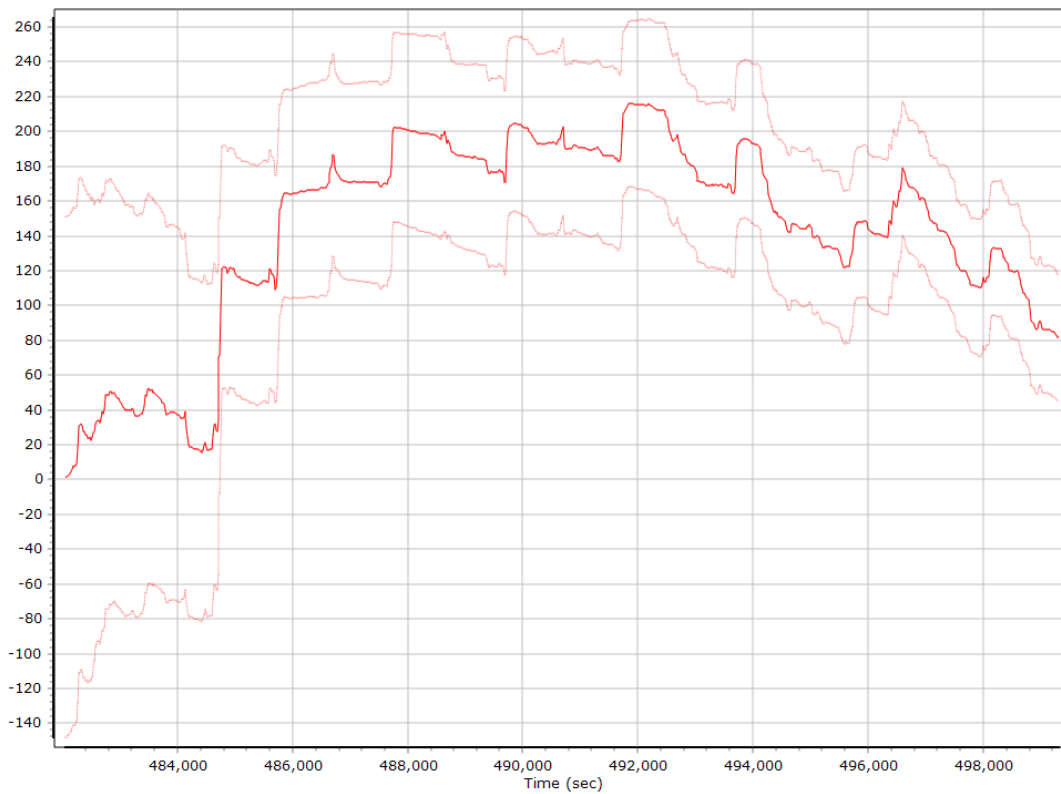
### Z Gyro Bias (deg/h)



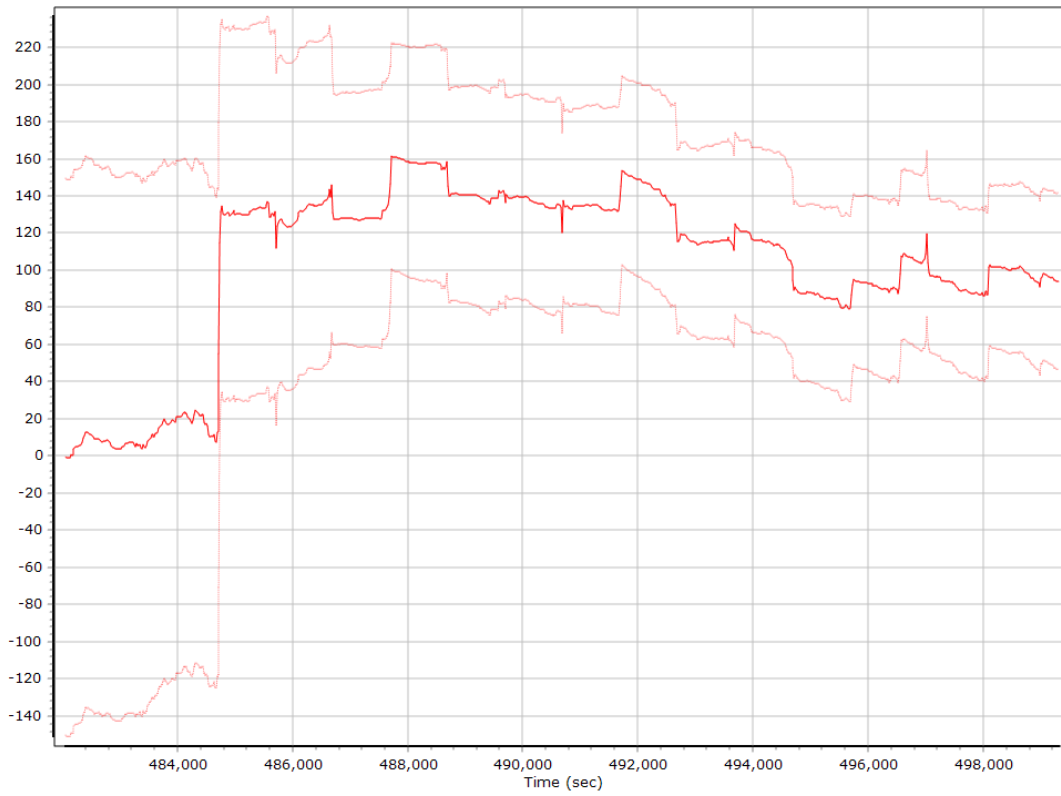
### Gyro Scale Error (ppm)



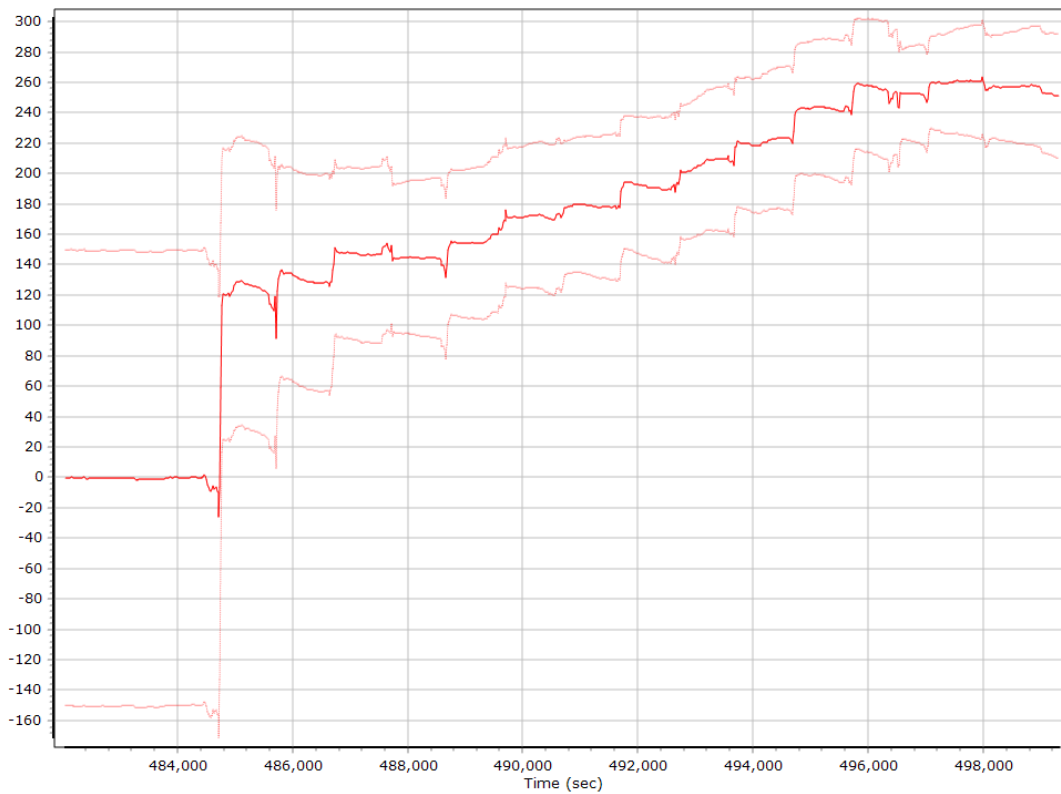
### X Gyro Scale Error (ppm)



### Y Gyro Scale Error (ppm)

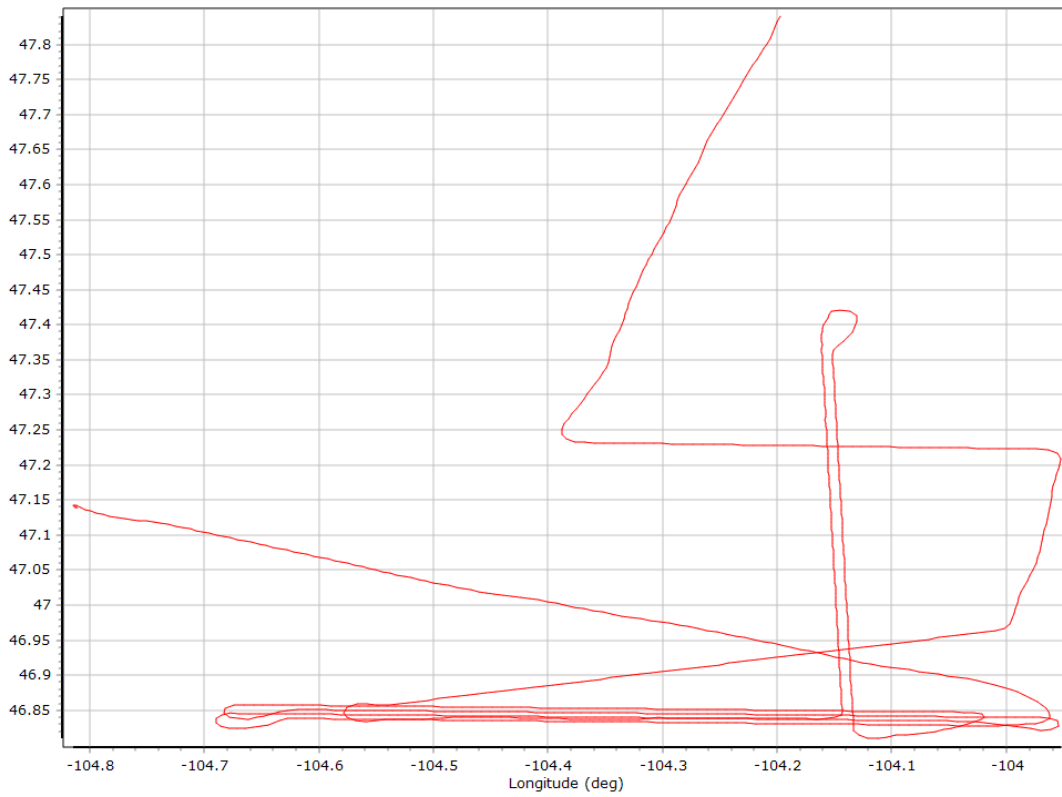


### Z Gyro Scale Error (ppm)

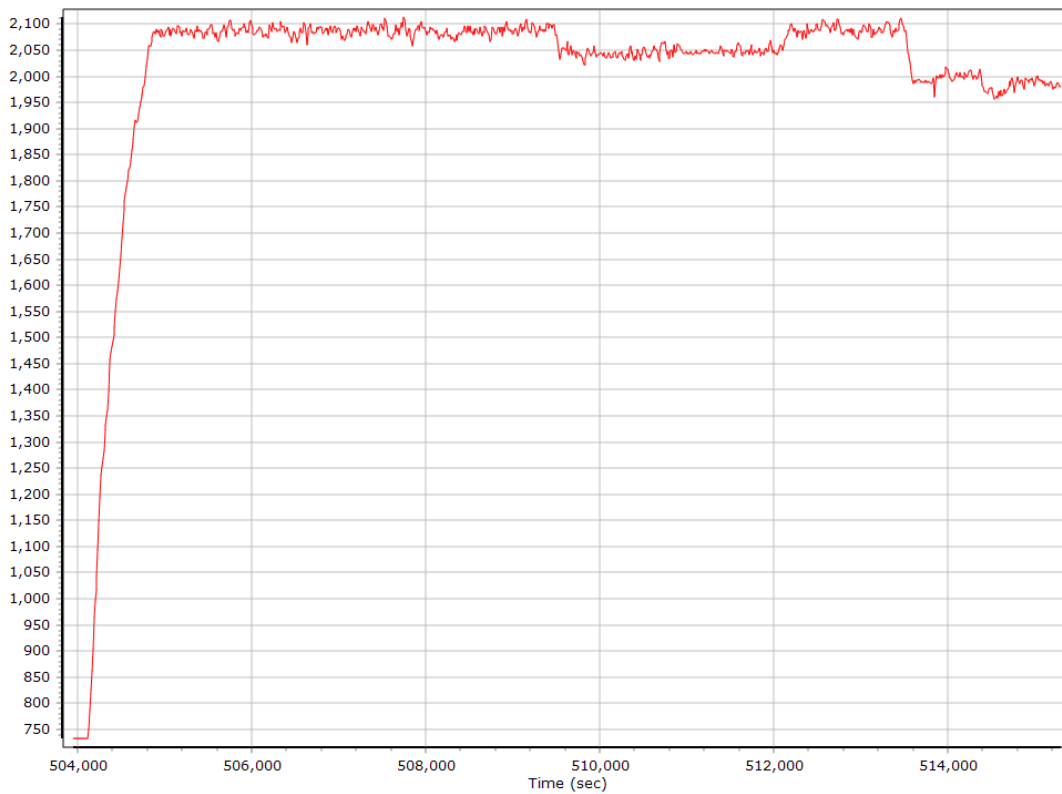


## Smoothed Trajectory Information

### Top View



### Altitude



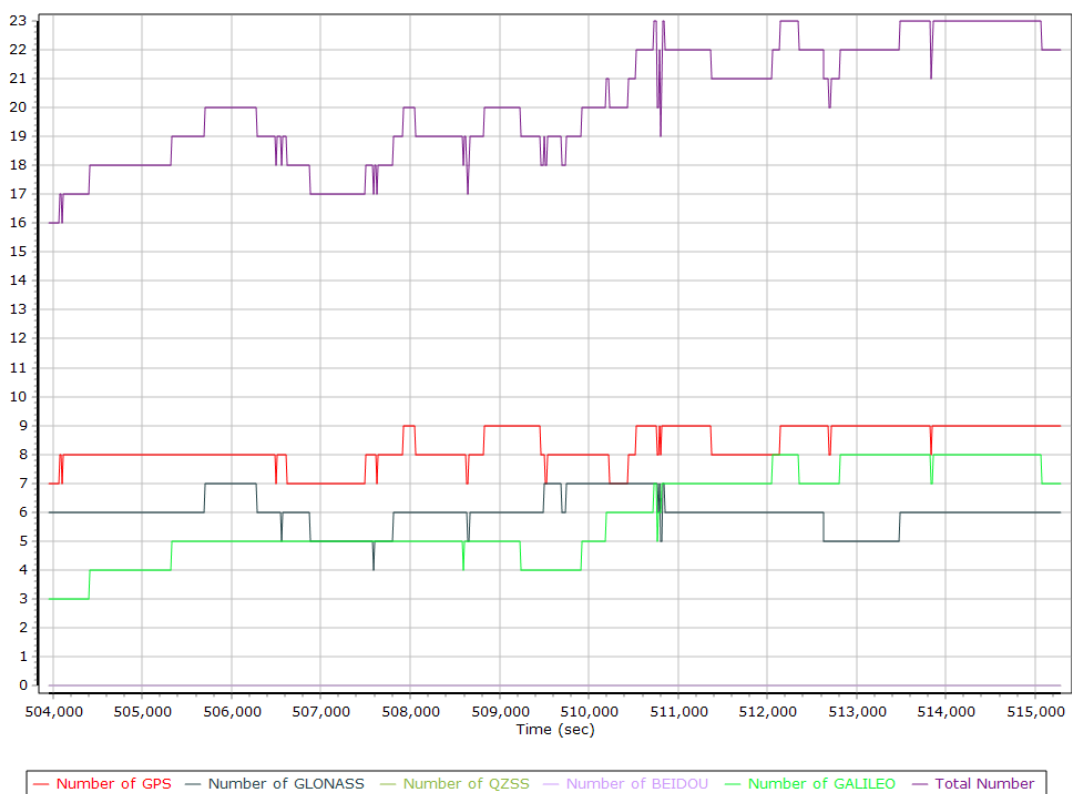


## GNSS QC

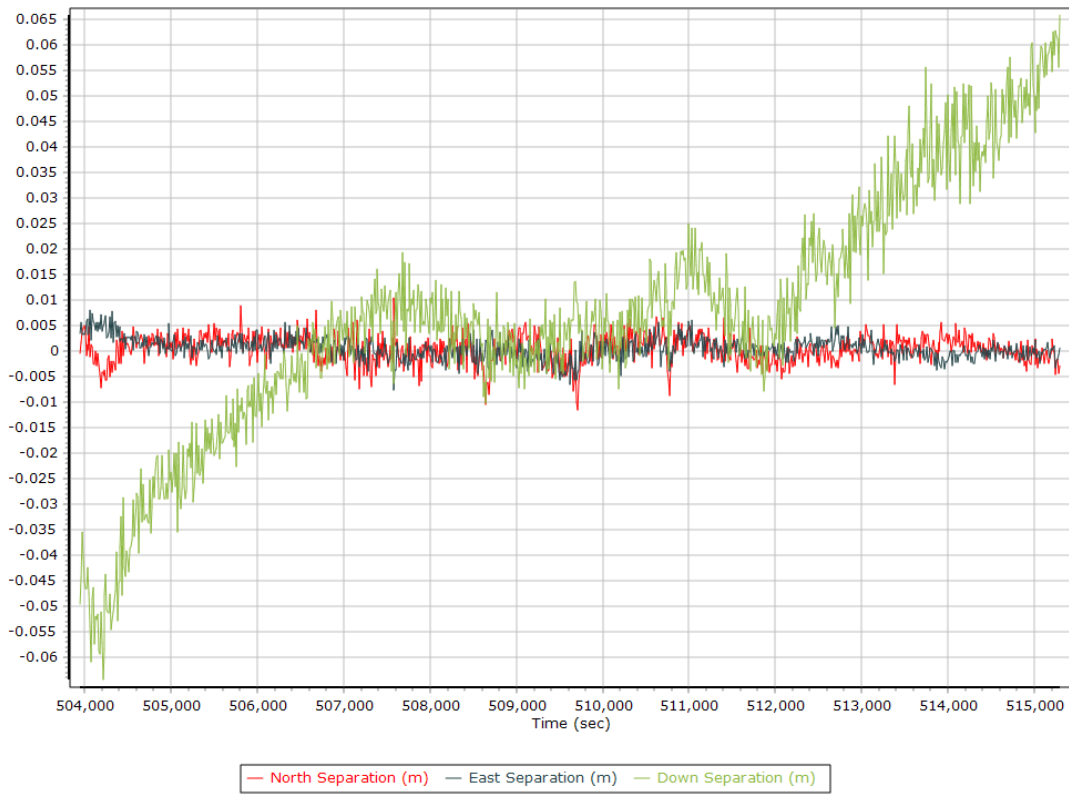
### GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	6	9	8
Number of GLONASS SV	0	7	6
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	0	0
Number of GALILEO SV	3	8	6
Total number of SV	11	23	20
PDOP	1.03	1.78	1.20
QC Solution Gaps	0.00	0.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	11771.00	0.00	0.00
Percentage	100.00	0.00	0.00

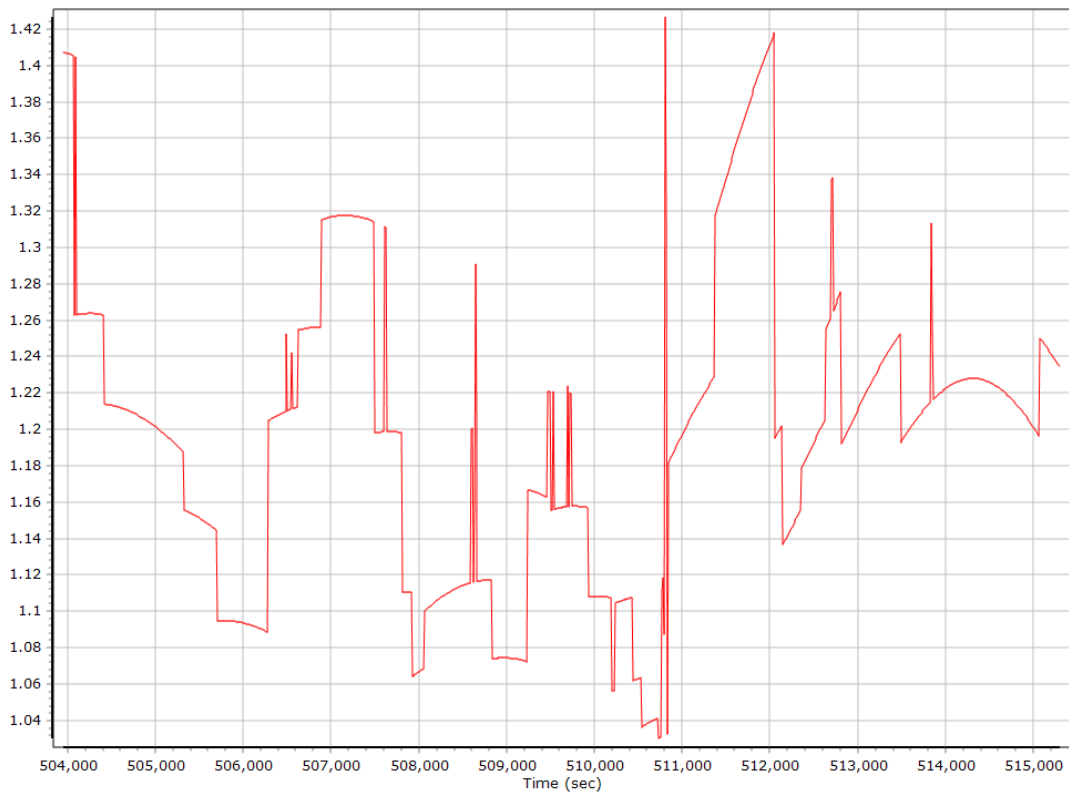
### Num SVs in solution



## Forward/Reverse Separation



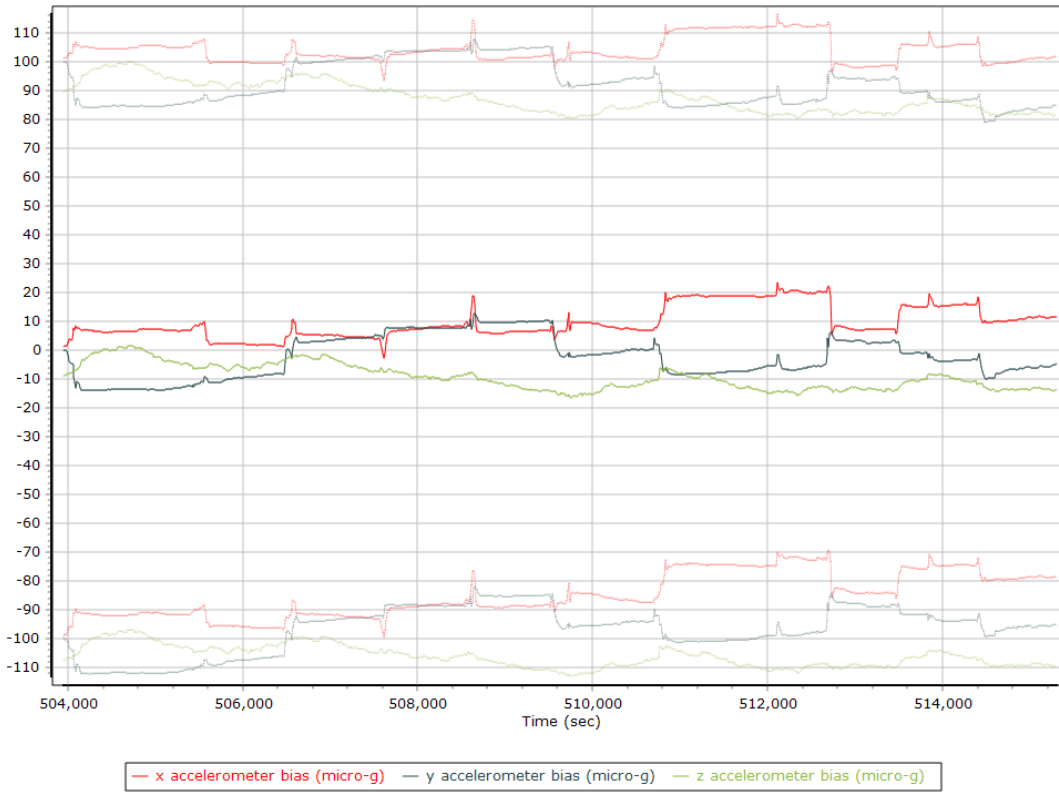
## PDOP



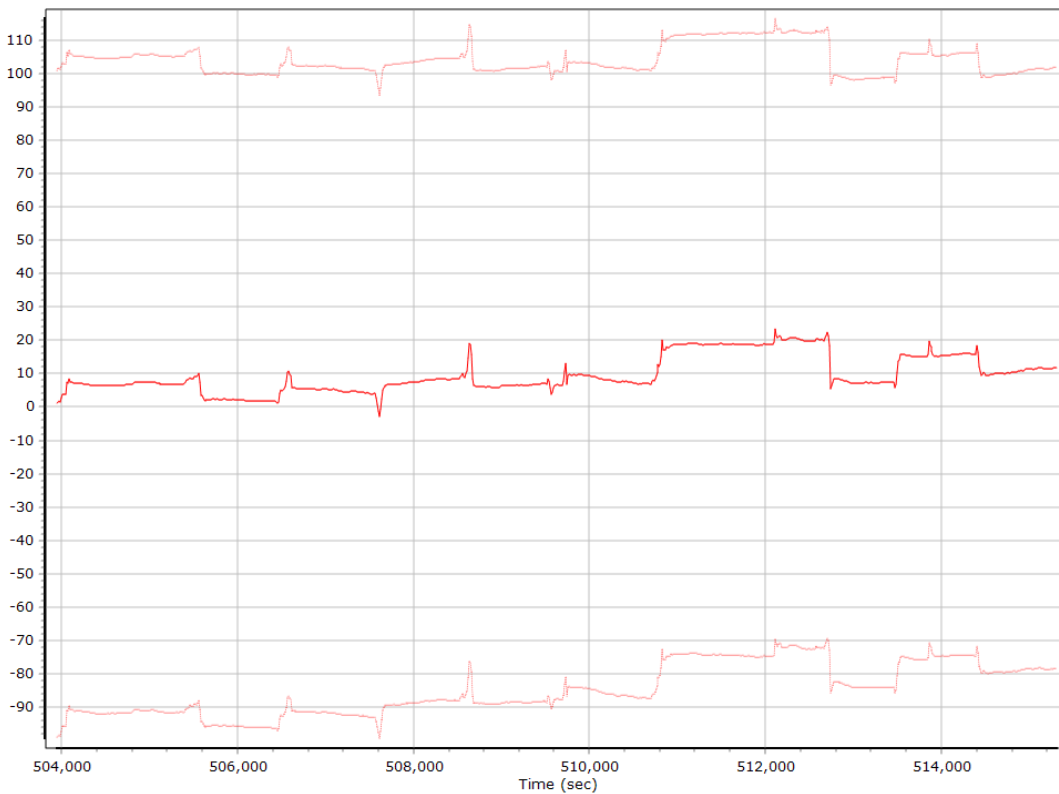
## IN-Fusion QC

### Forward Processed Estimated Errors, Reference Frame

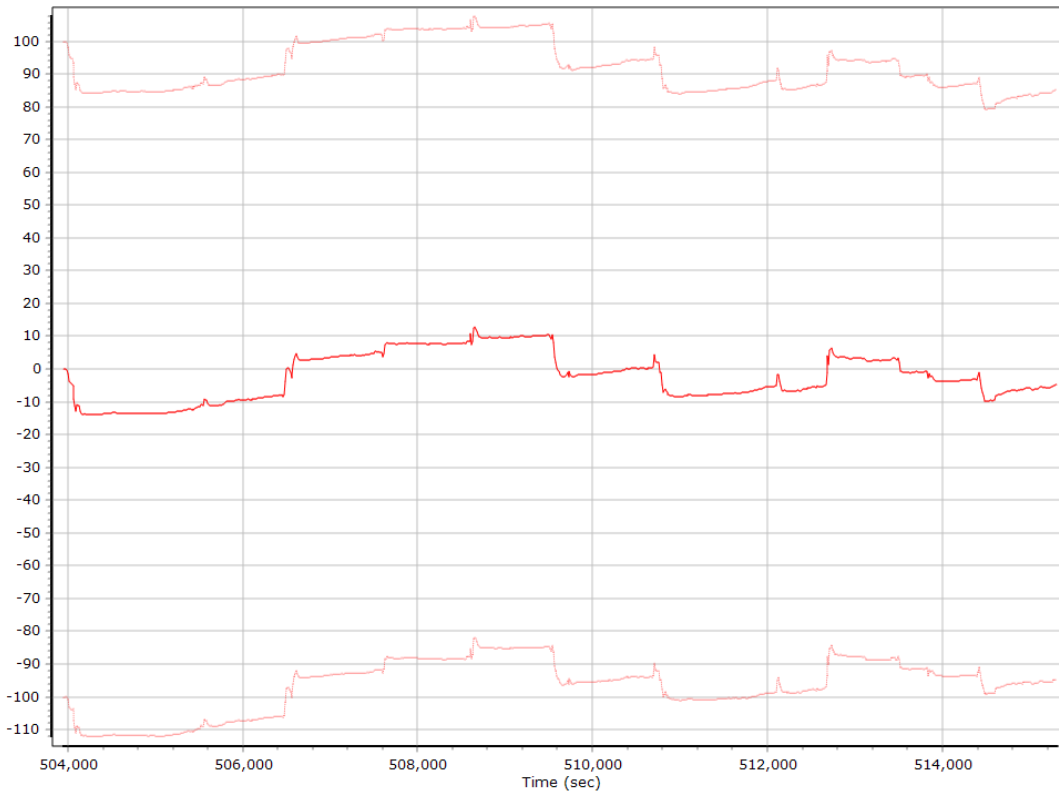
#### Accelerometer Bias (micro-g)



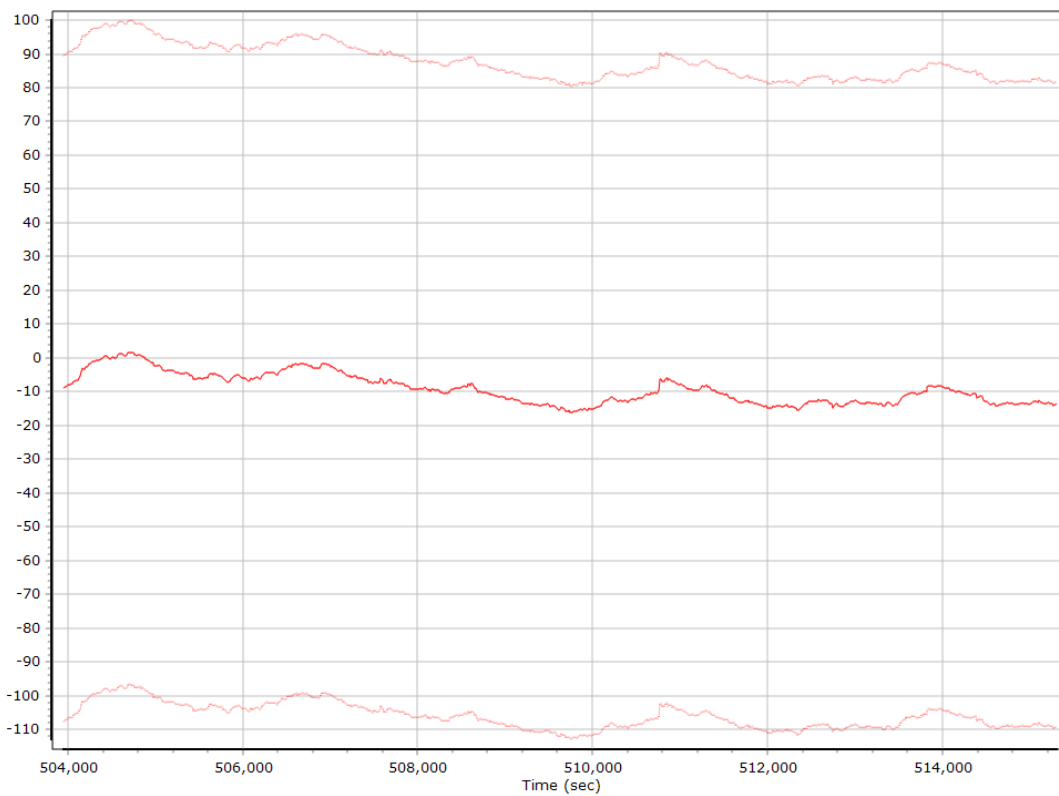
#### X Accelerometer Bias (micro-g)



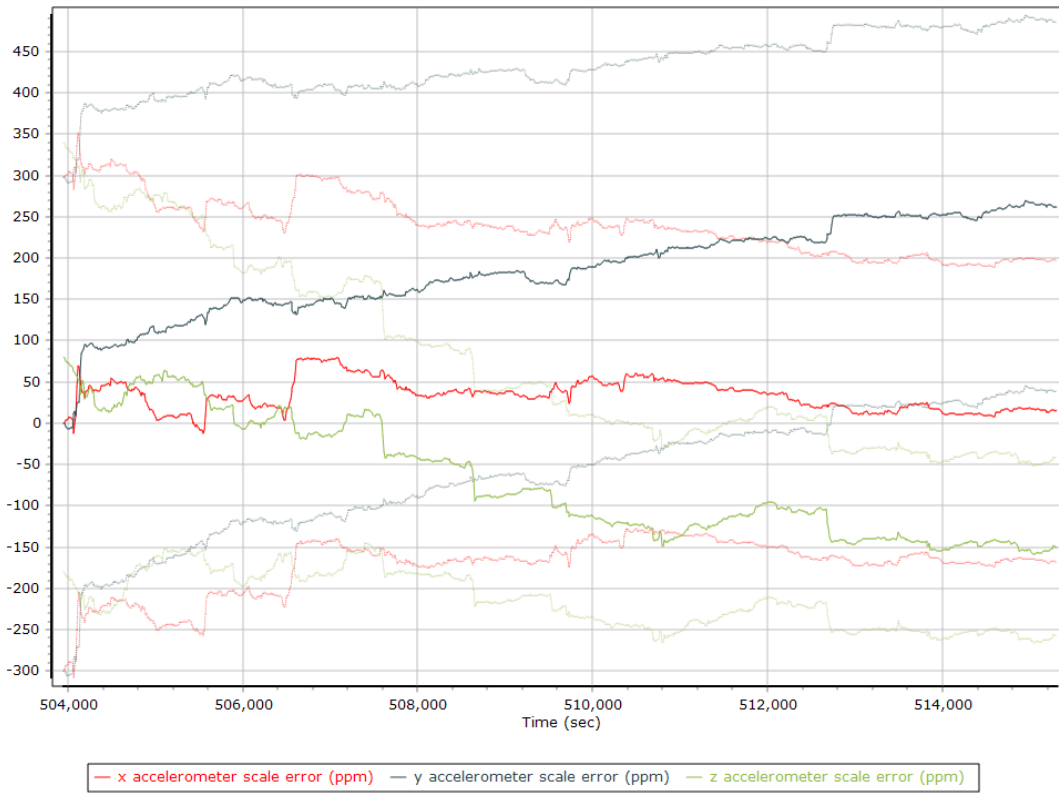
### Y Accelerometer Bias (micro-g)



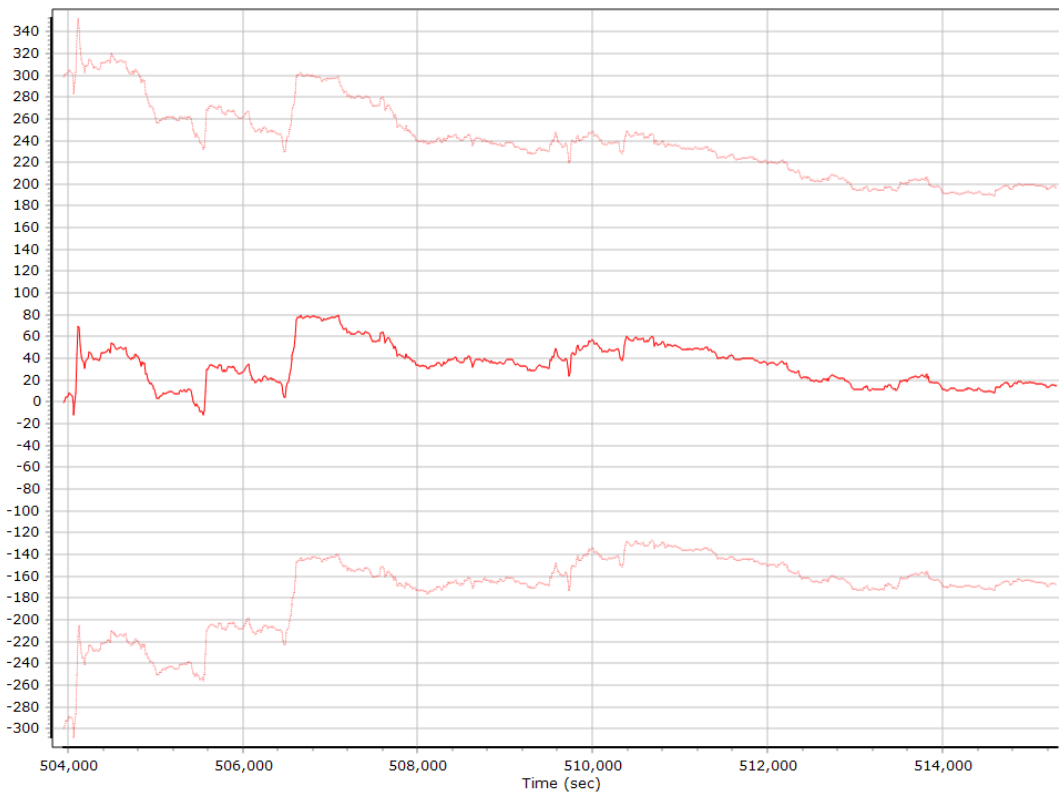
### Z Accelerometer Bias (micro-g)



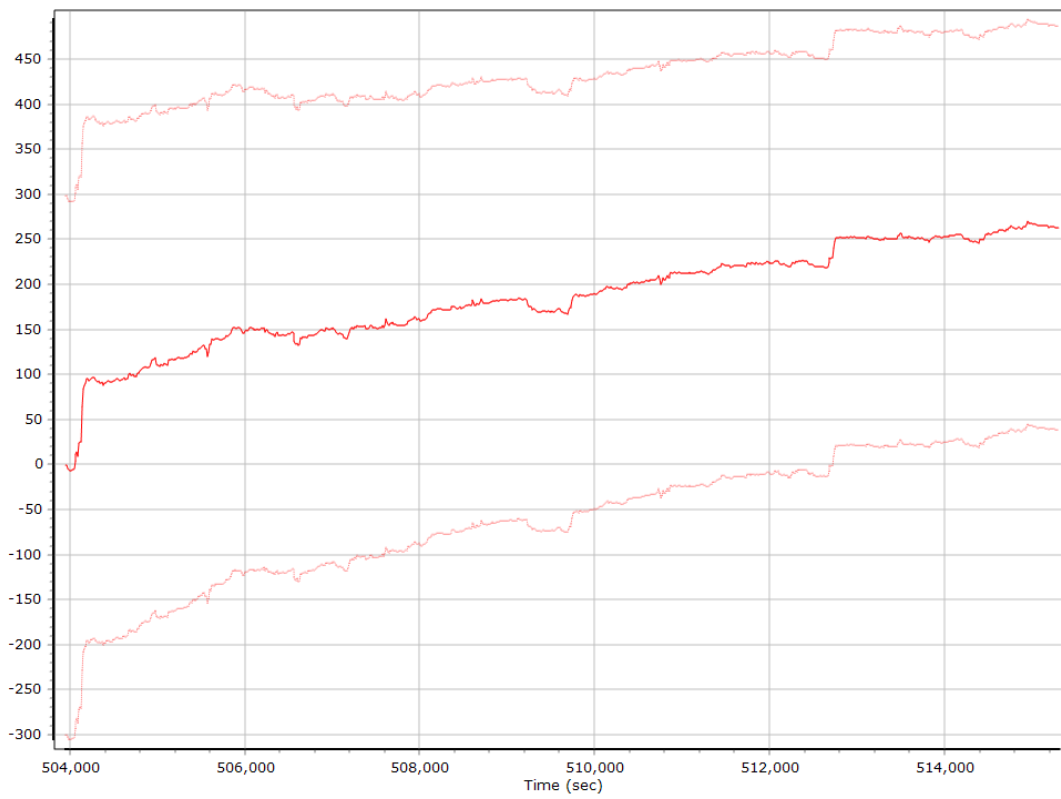
### Accelerometer Scale Error (ppm)



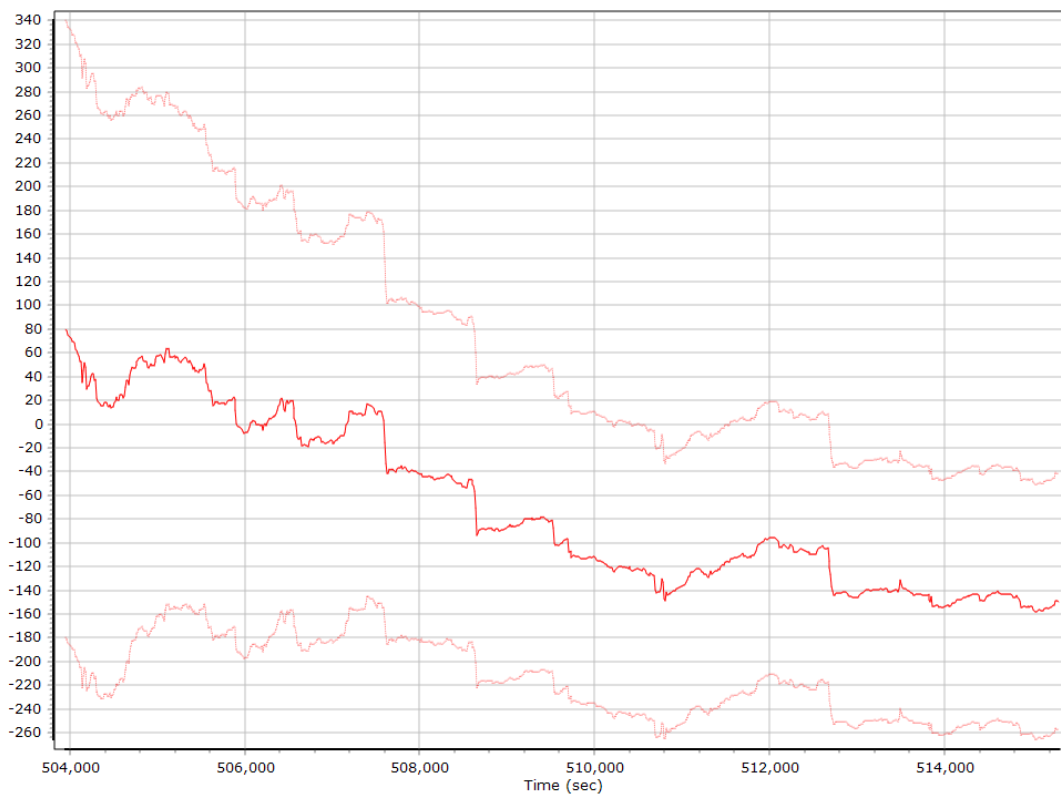
### X Accelerometer Scale Error (ppm)



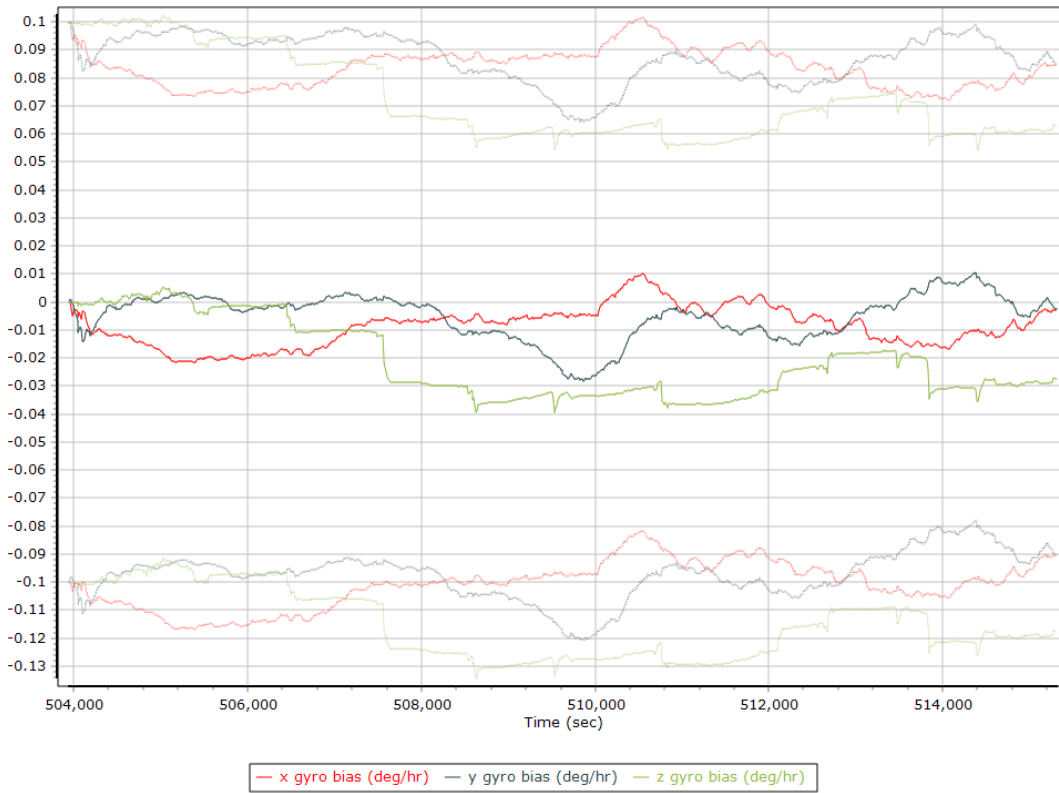
### Y Accelerometer Scale Error (ppm)



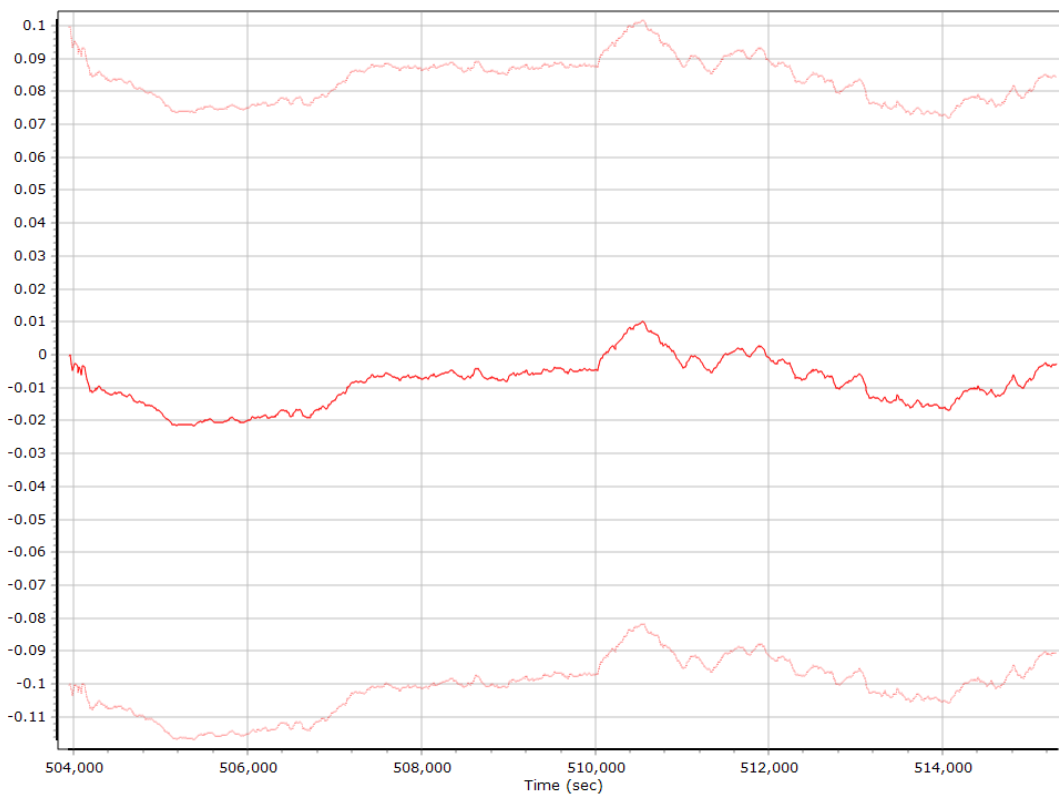
### Z Accelerometer Scale Error (ppm)



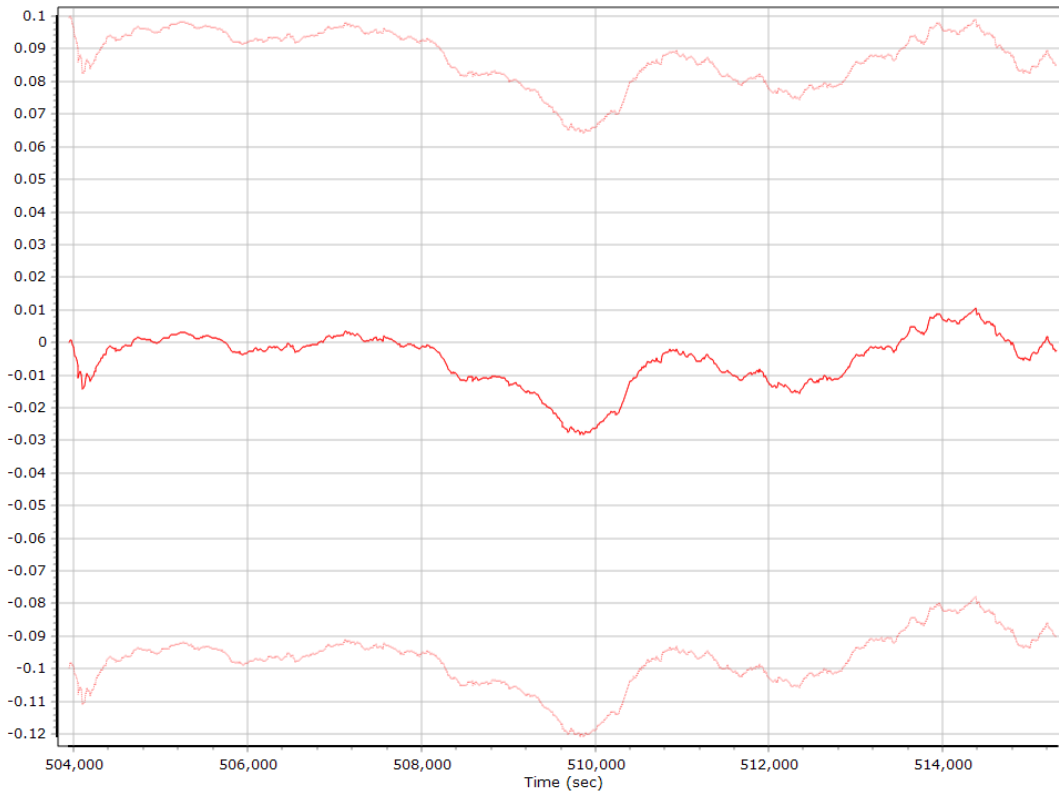
### Gyro Bias (deg/h)



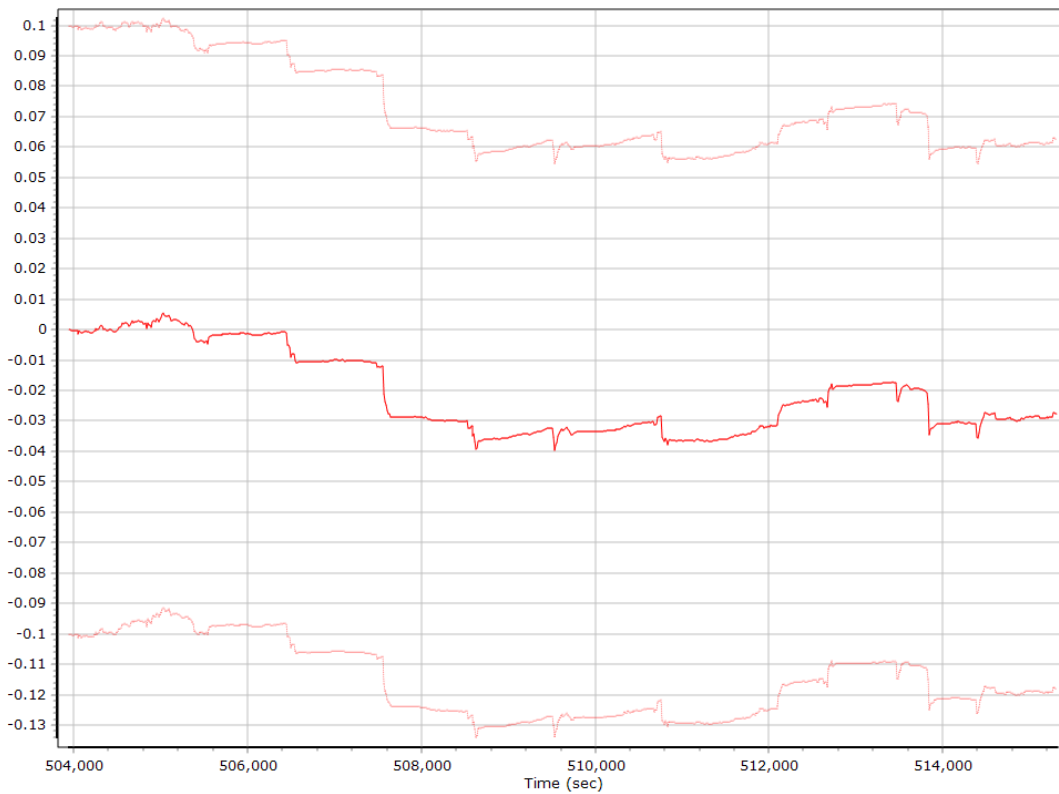
### X Gyro Bias (deg/h)



### Y Gyro Bias (deg/h)

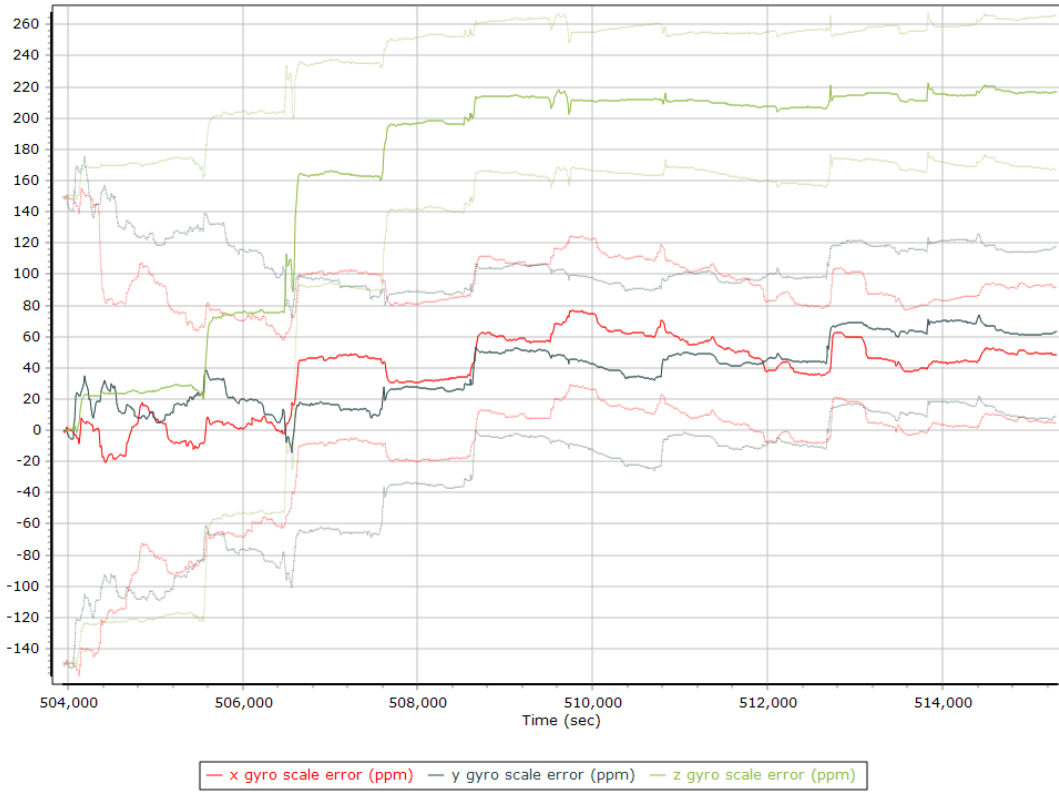


### Z Gyro Bias (deg/h)

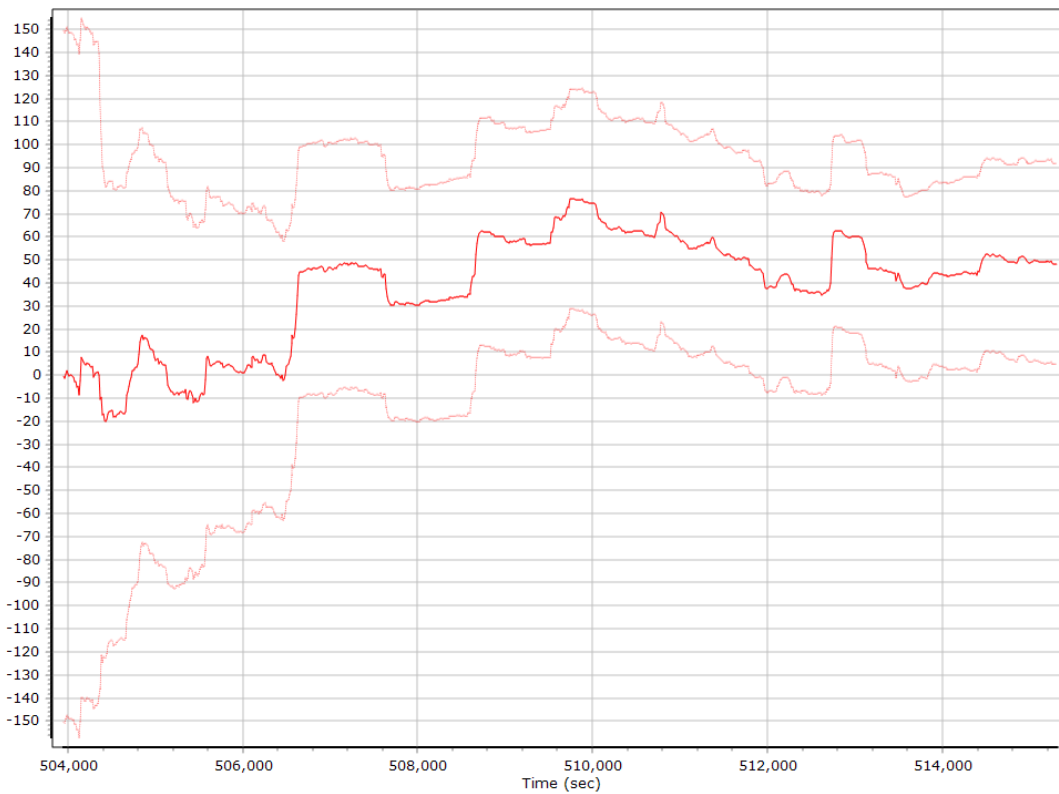




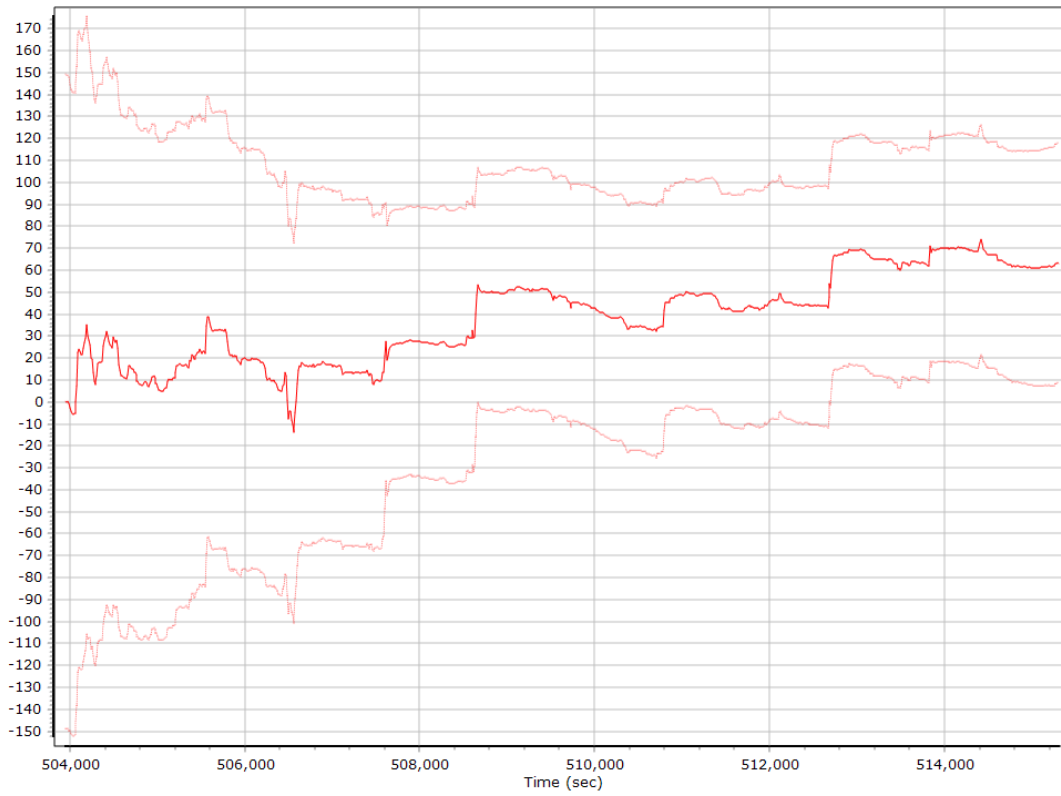
### Gyro Scale Error (ppm)



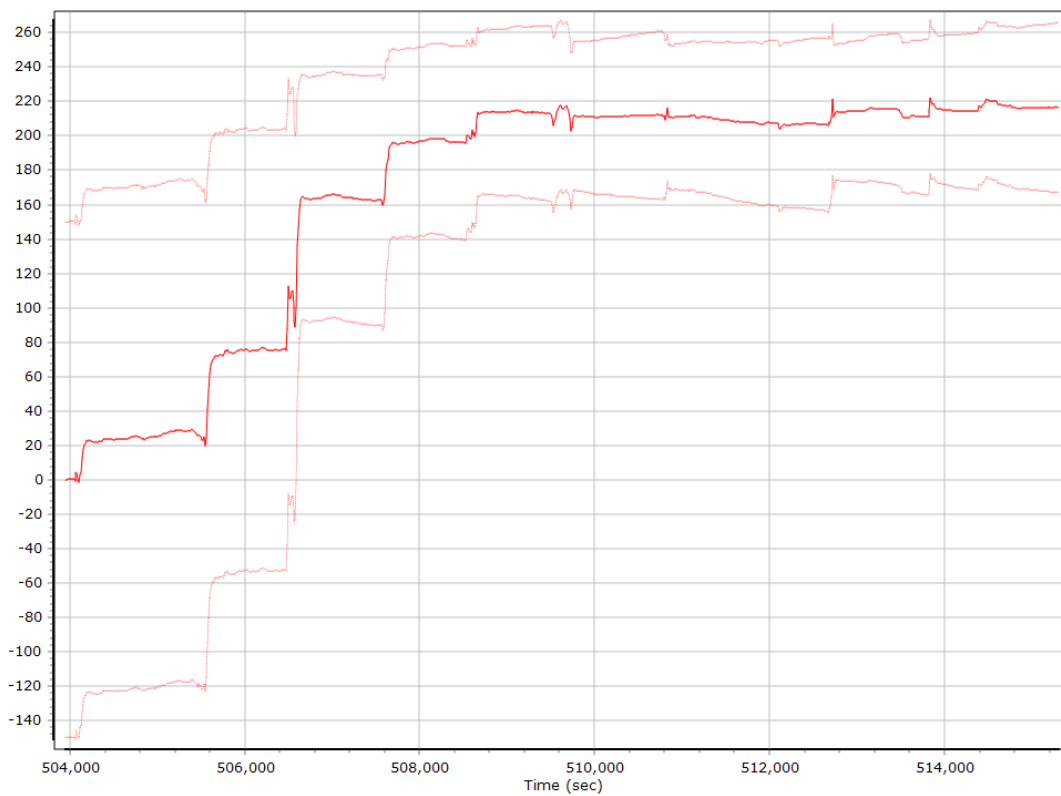
### X Gyro Scale Error (ppm)



### Y Gyro Scale Error (ppm)

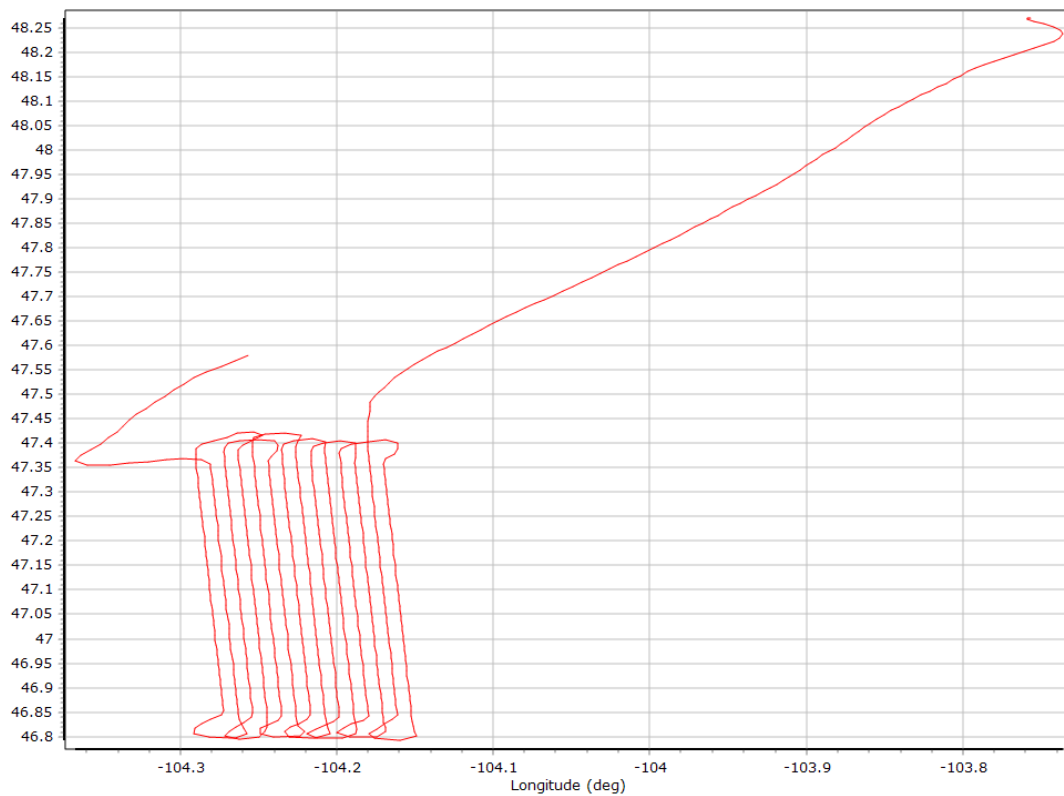


### Z Gyro Scale Error (ppm)

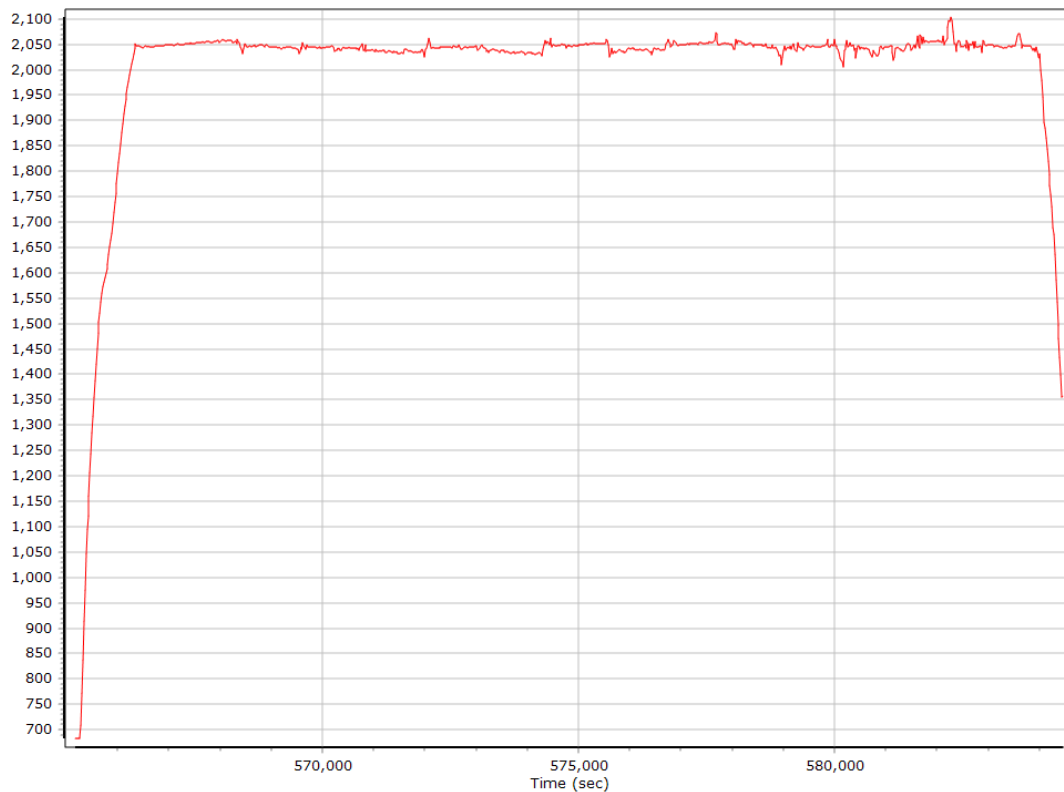


## Smoothed Trajectory Information

### Top View



### Altitude

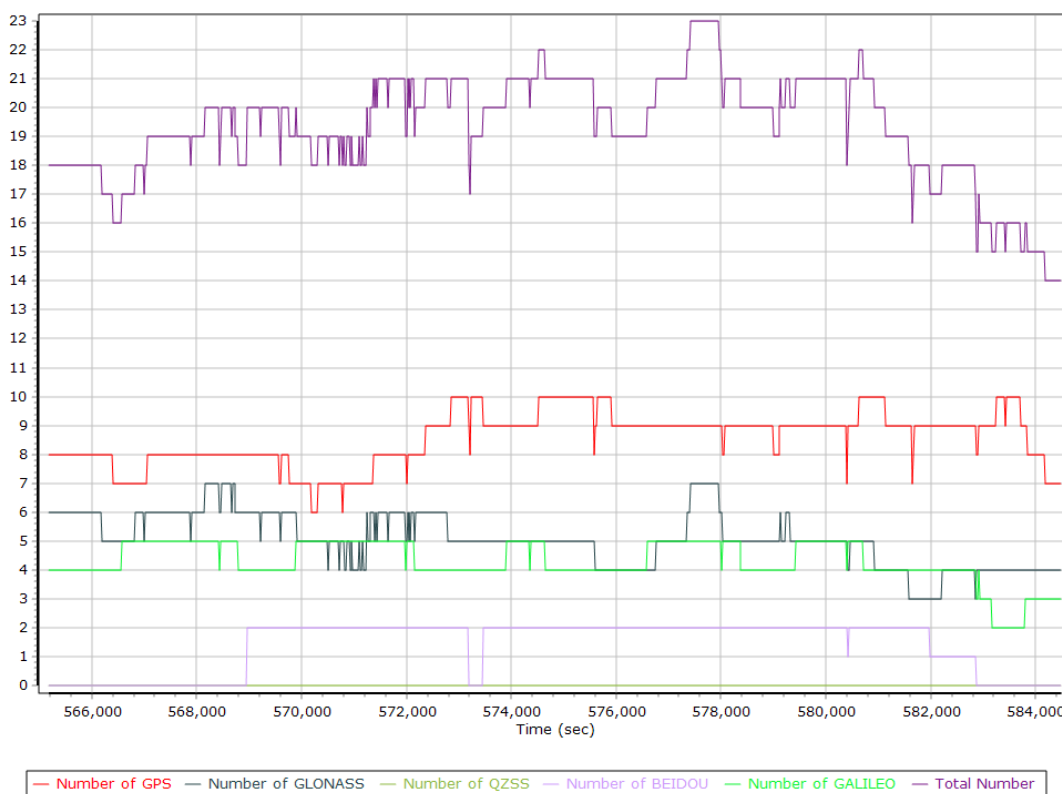


## GNSS QC

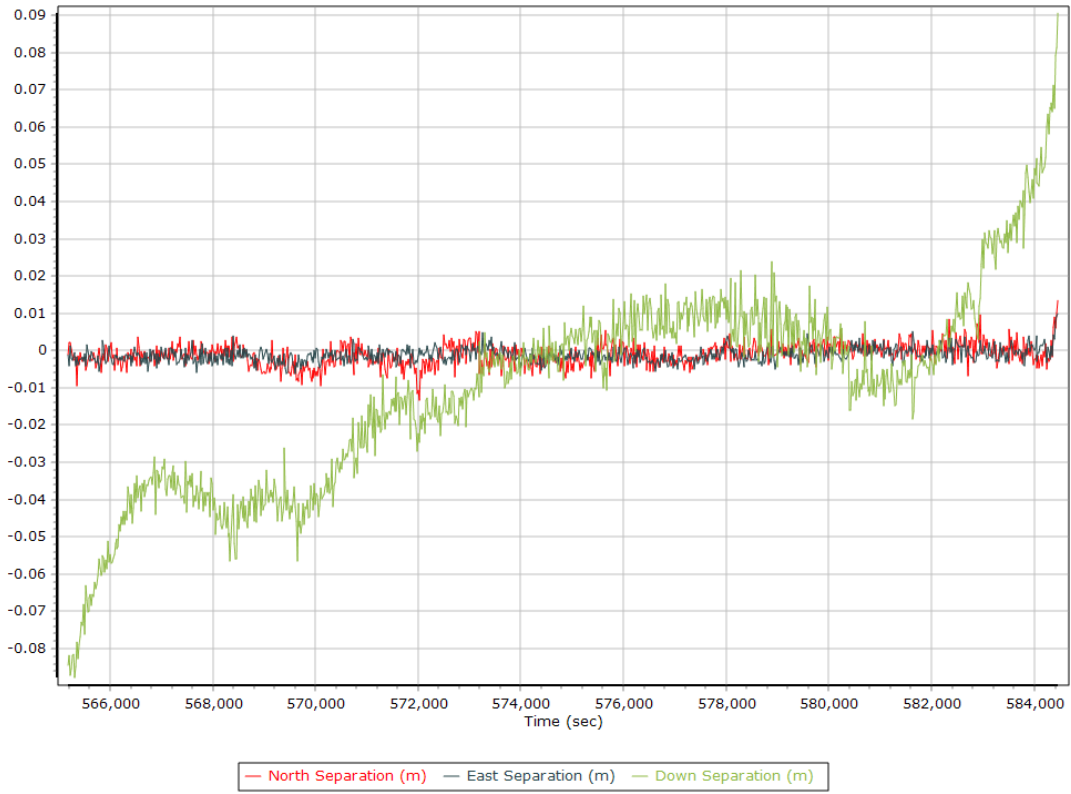
### GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	6	10	9
Number of GLONASS SV	0	7	5
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	2	1
Number of GALILEO SV	2	5	4
Total number of SV	12	23	19
PDOP	0.98	1.63	1.23
QC Solution Gaps	1.00	1.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	19564.00	0.00	1.00
Percentage	99.99	0.00	0.01

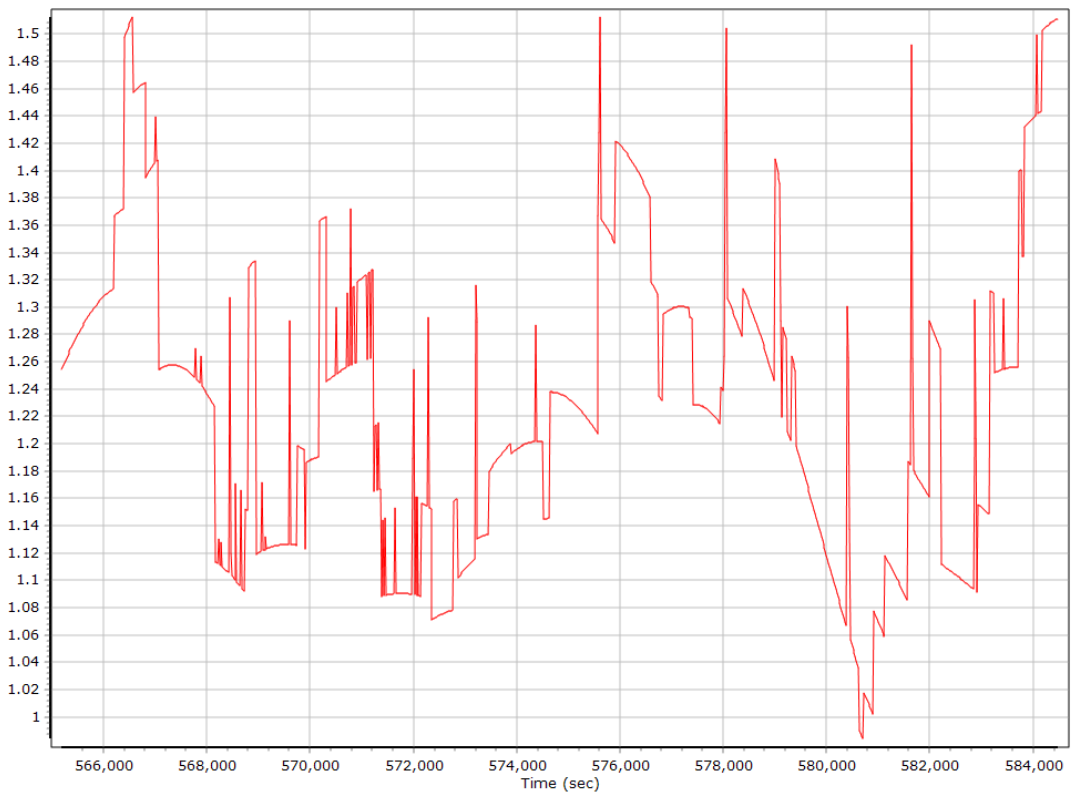
### Num SVs in solution



## Forward/Reverse Separation



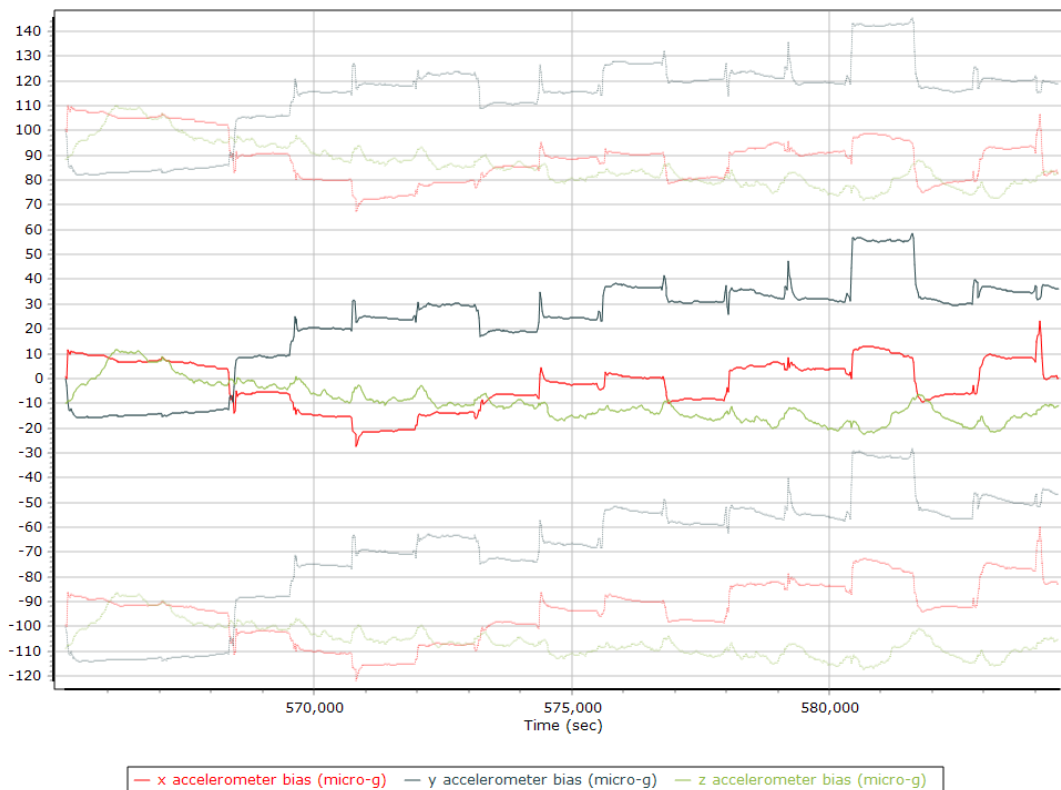
## PDOP



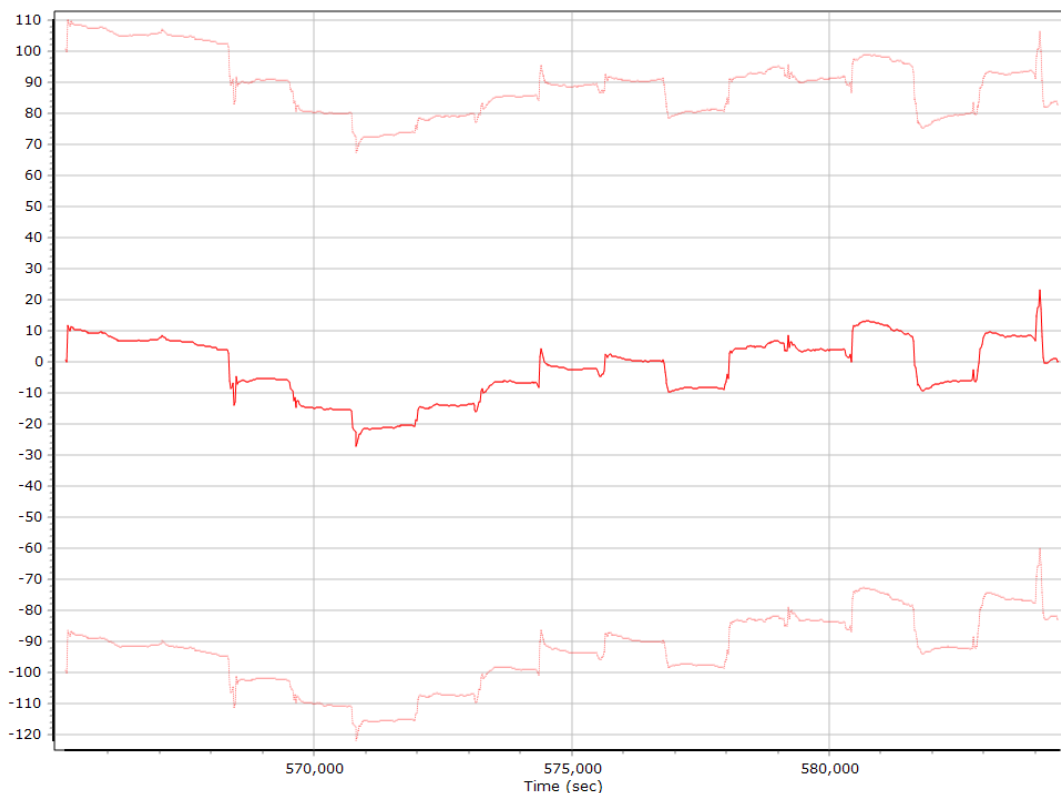
## IN-Fusion QC

### Forward Processed Estimated Errors, Reference Frame

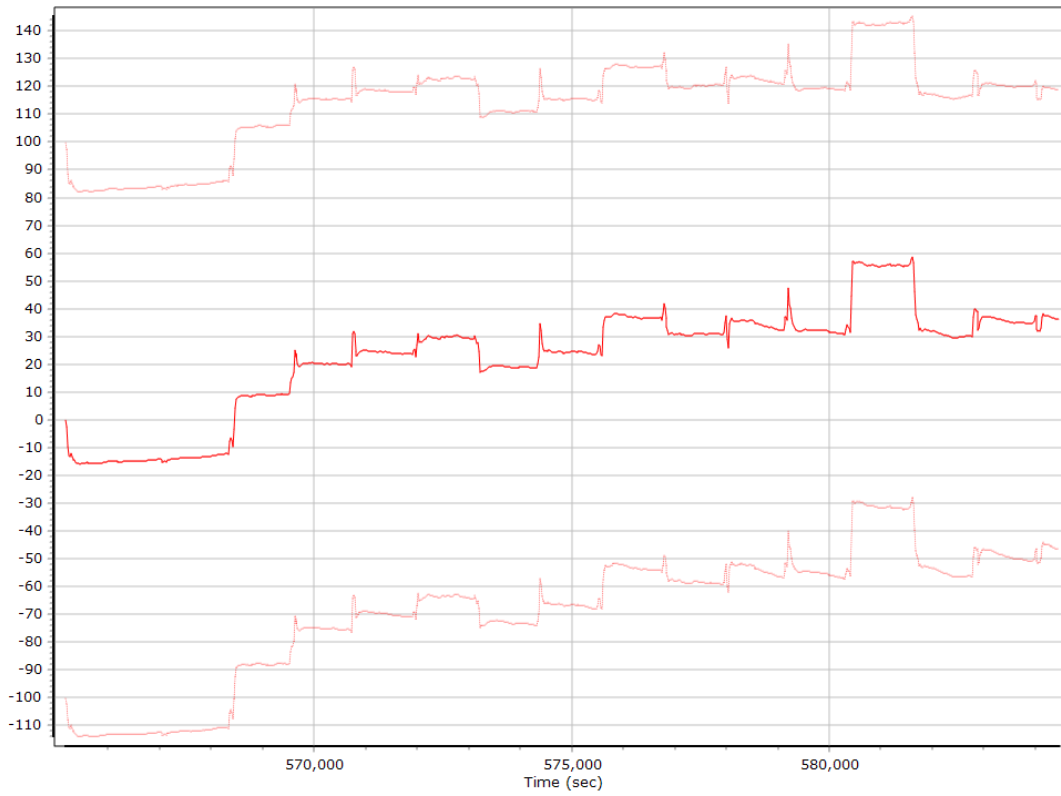
#### Accelerometer Bias (micro-g)



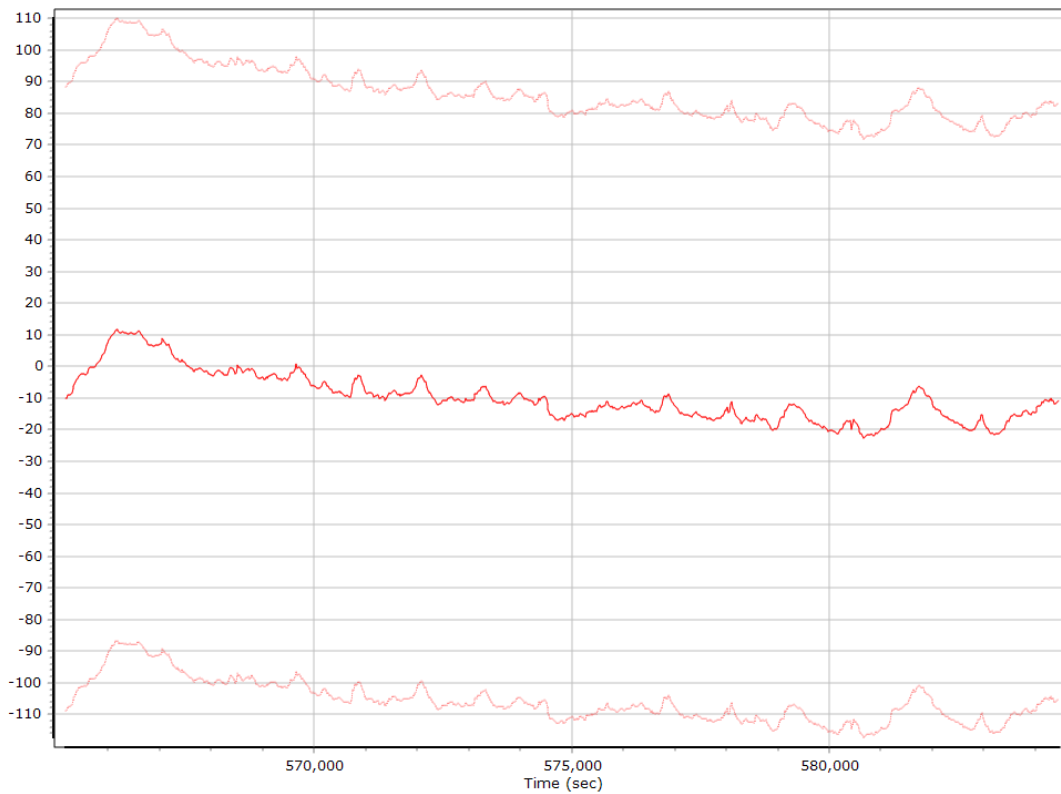
#### X Accelerometer Bias (micro-g)



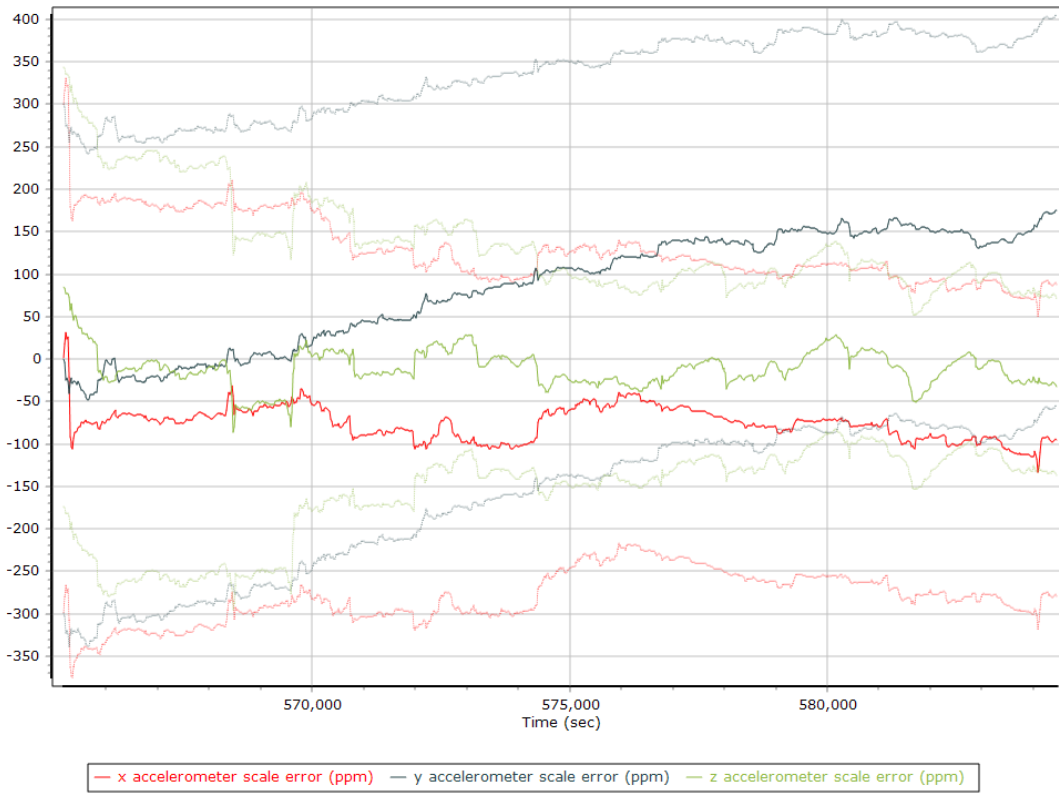
### Y Accelerometer Bias (micro-g)



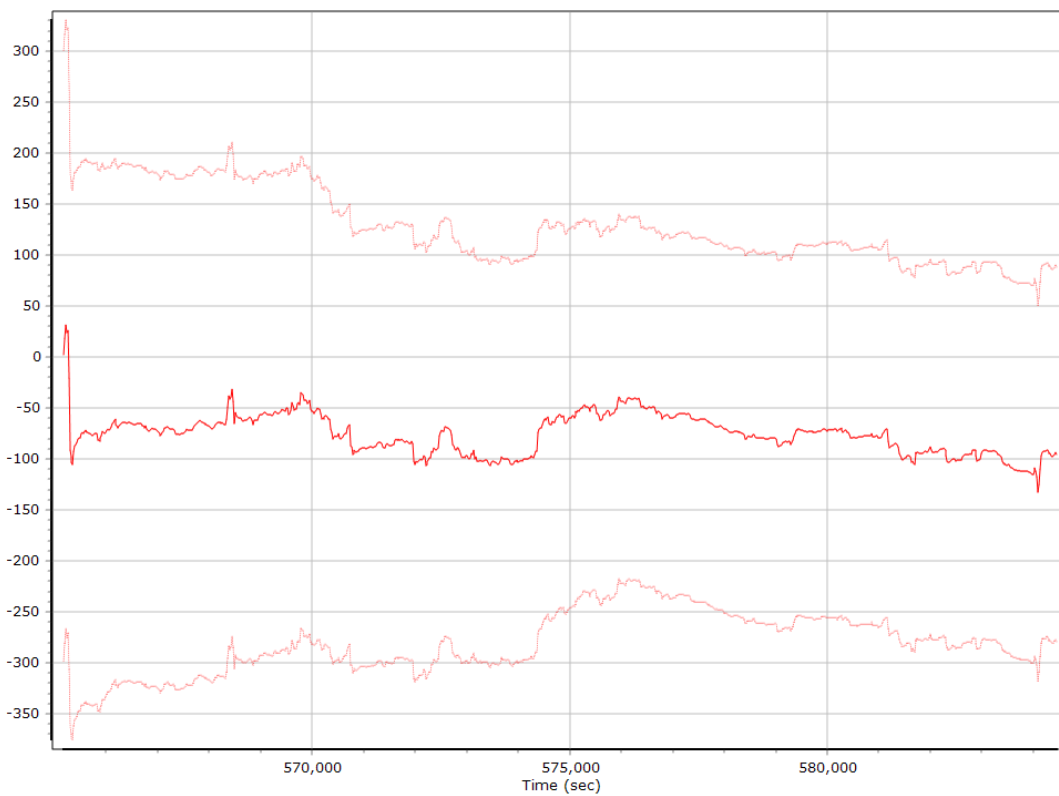
### Z Accelerometer Bias (micro-g)



### Accelerometer Scale Error (ppm)

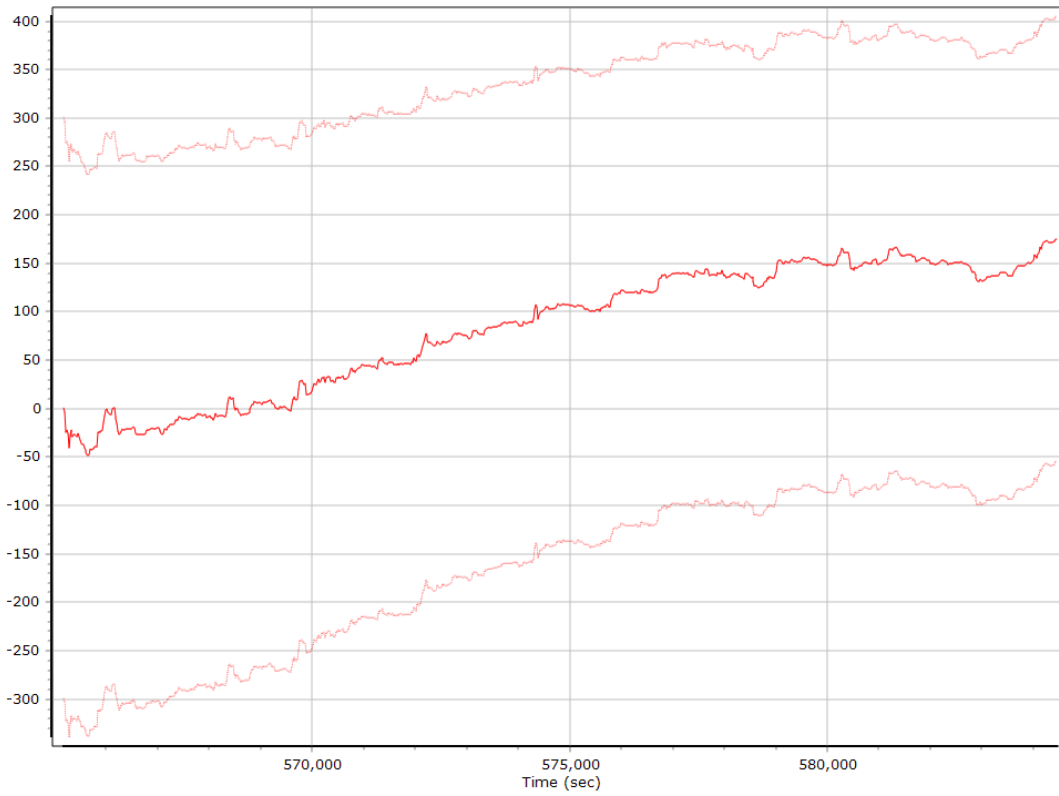


### X Accelerometer Scale Error (ppm)

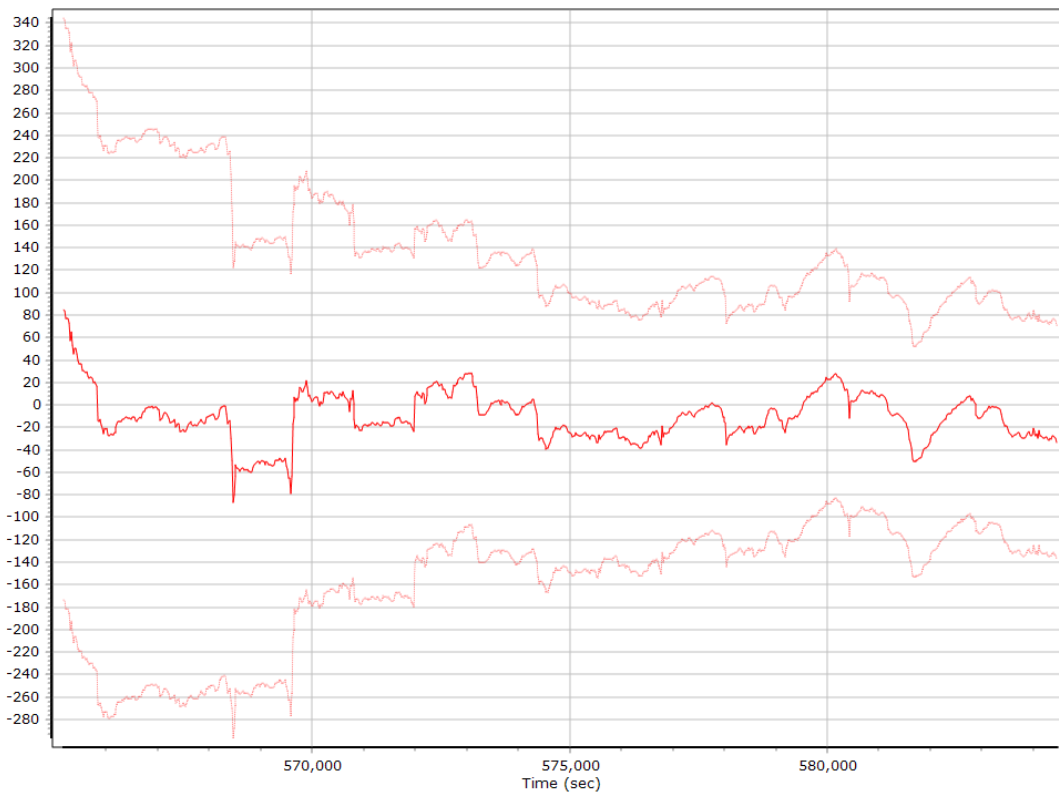




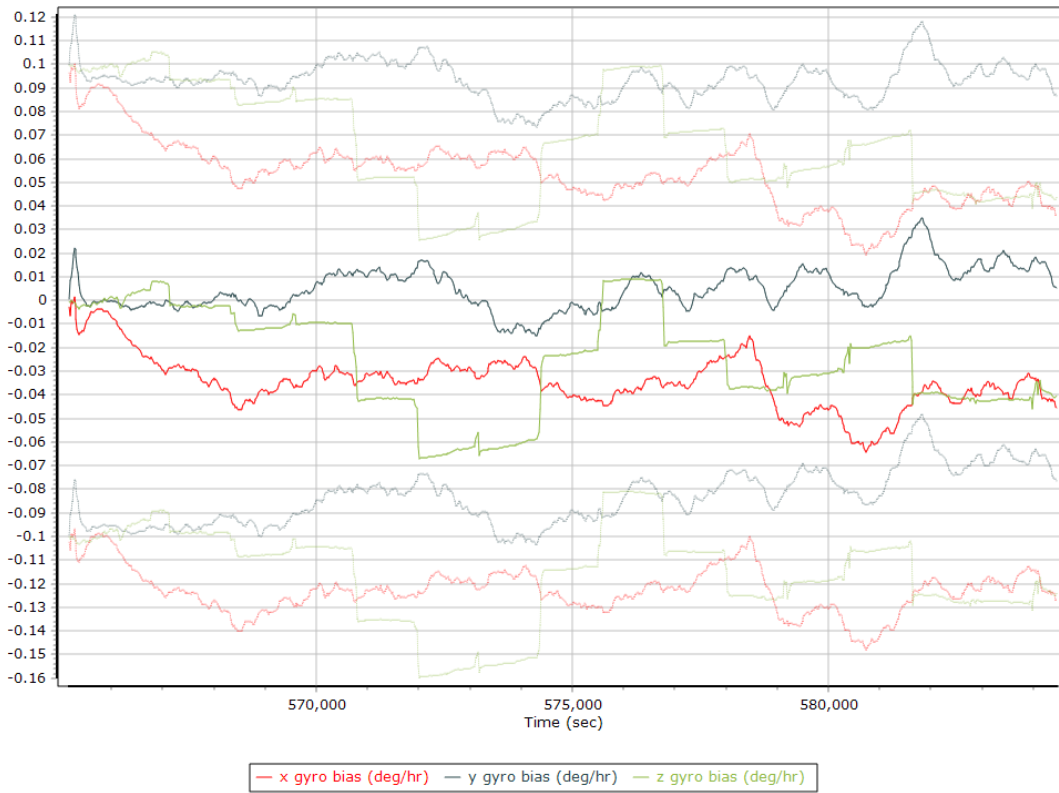
### Y Accelerometer Scale Error (ppm)



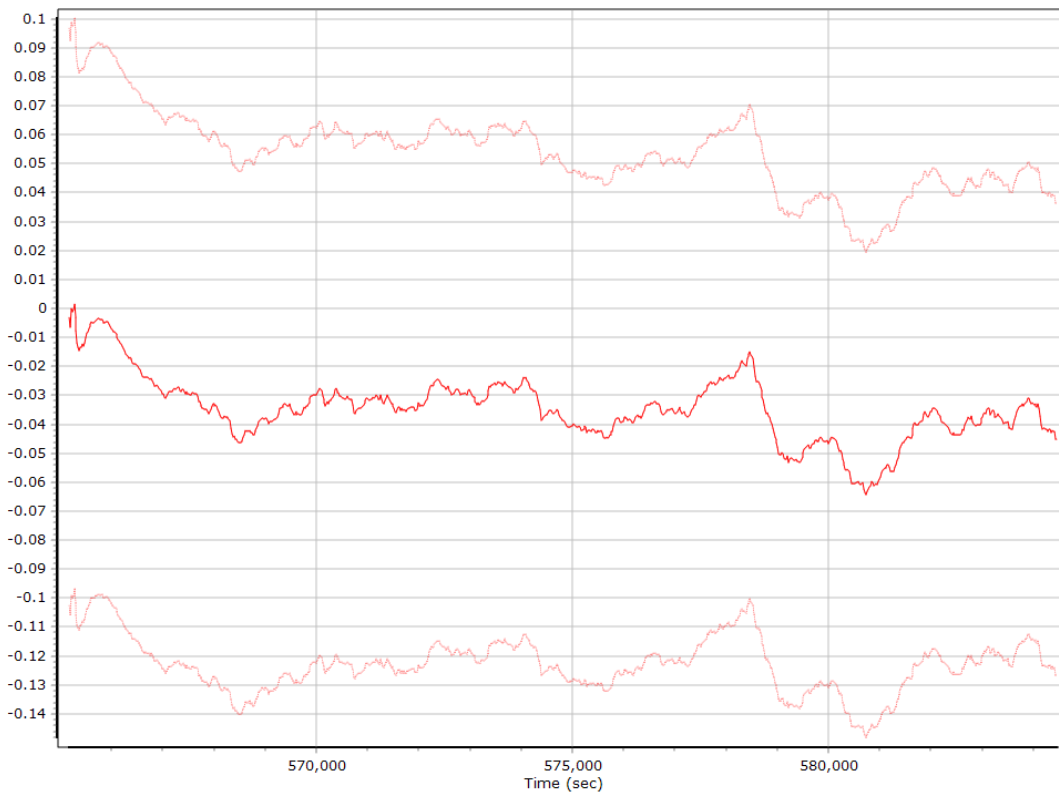
### Z Accelerometer Scale Error (ppm)



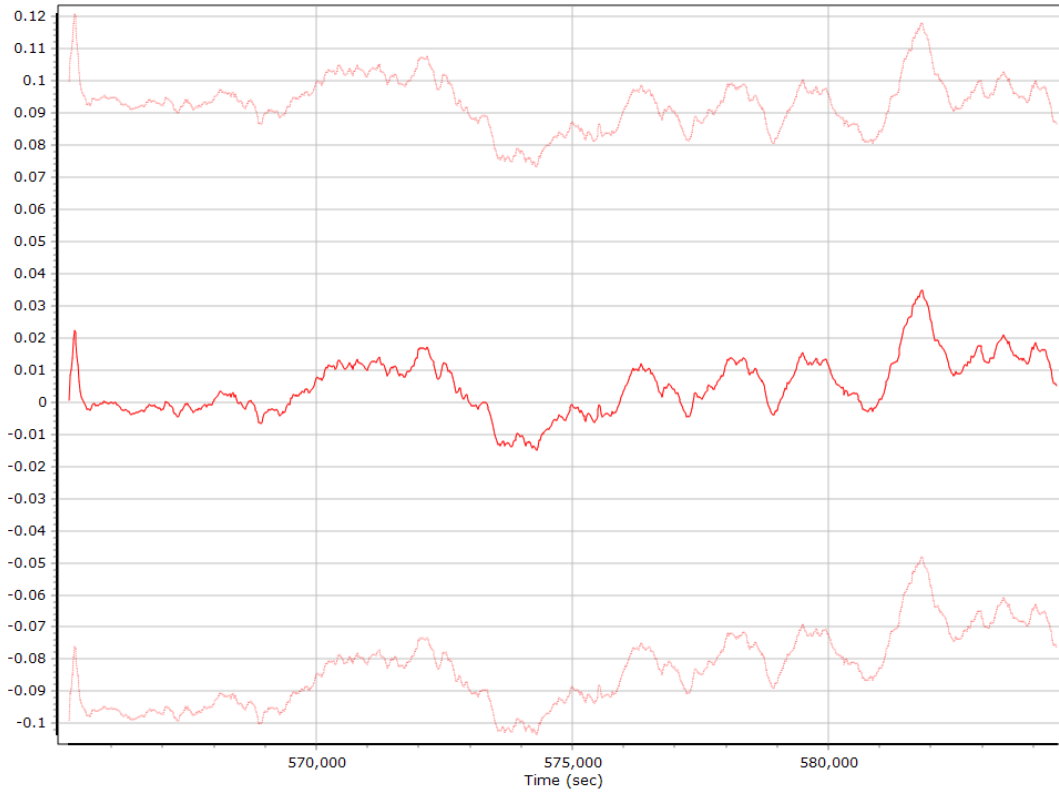
### Gyro Bias (deg/h)



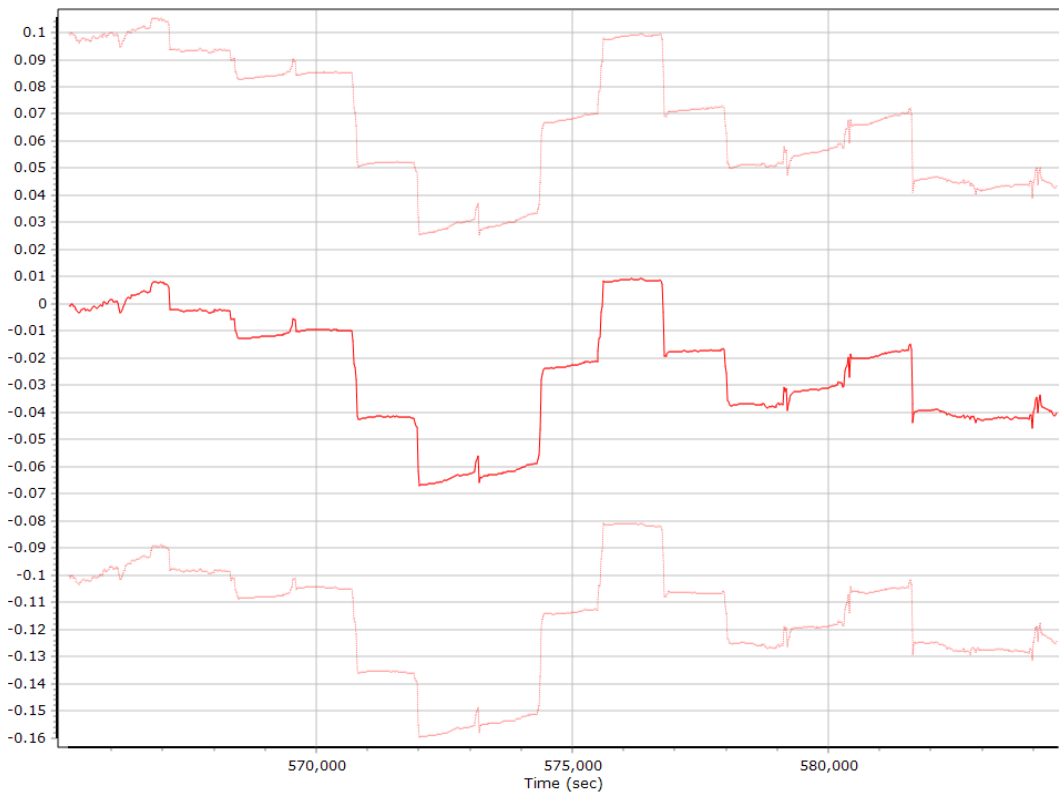
### X Gyro Bias (deg/h)



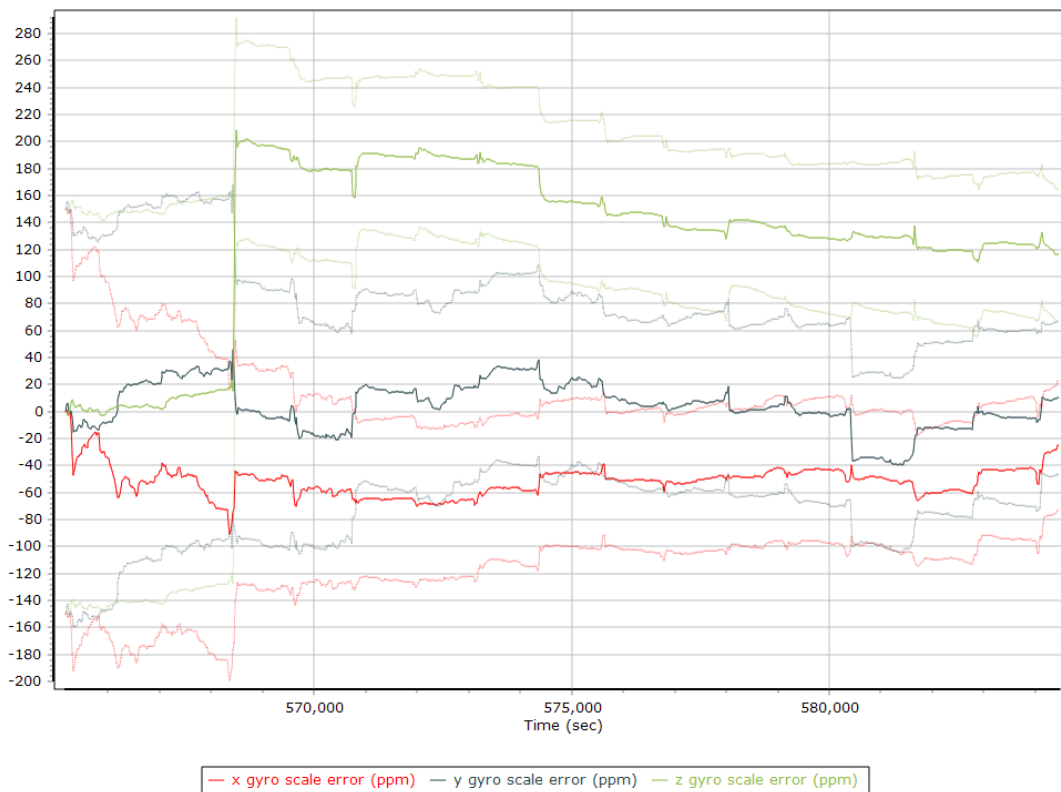
### Y Gyro Bias (deg/h)



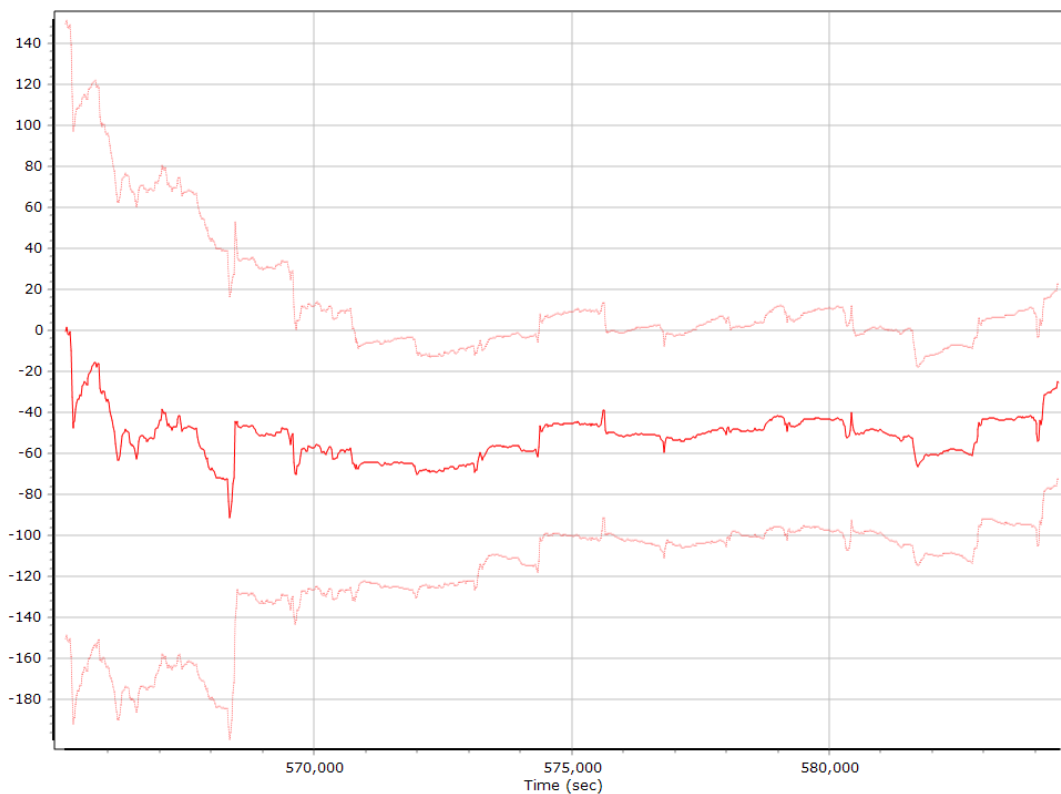
### Z Gyro Bias (deg/h)



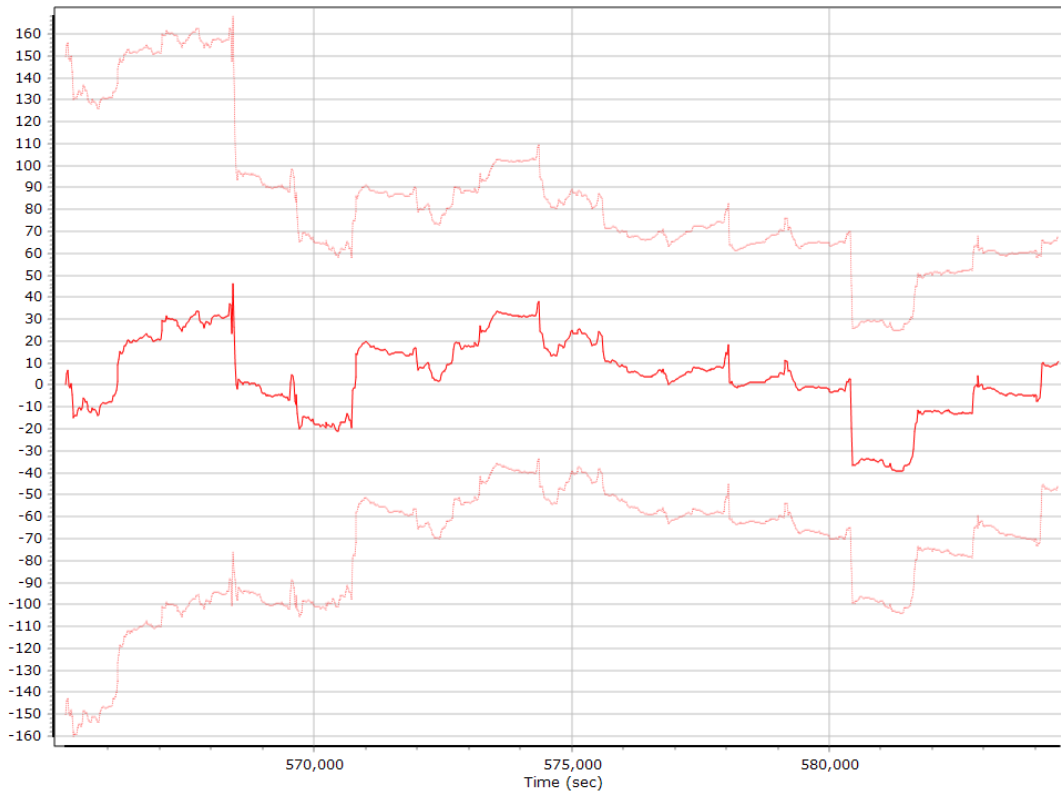
### Gyro Scale Error (ppm)



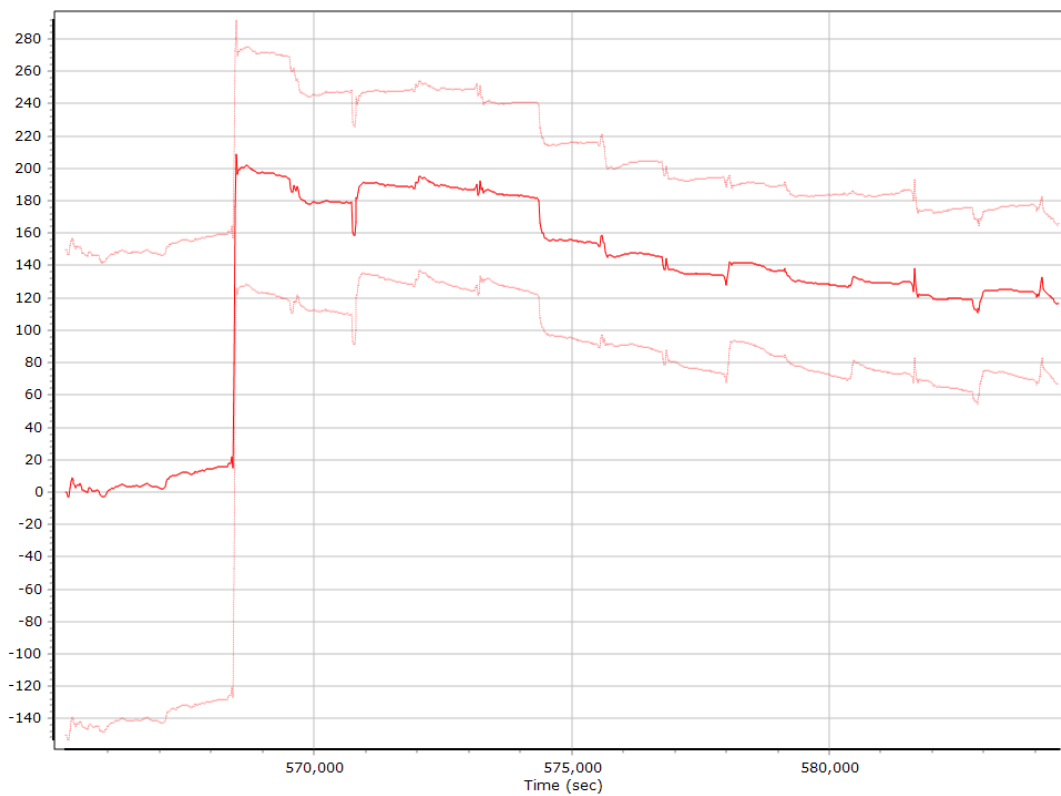
### X Gyro Scale Error (ppm)



### Y Gyro Scale Error (ppm)

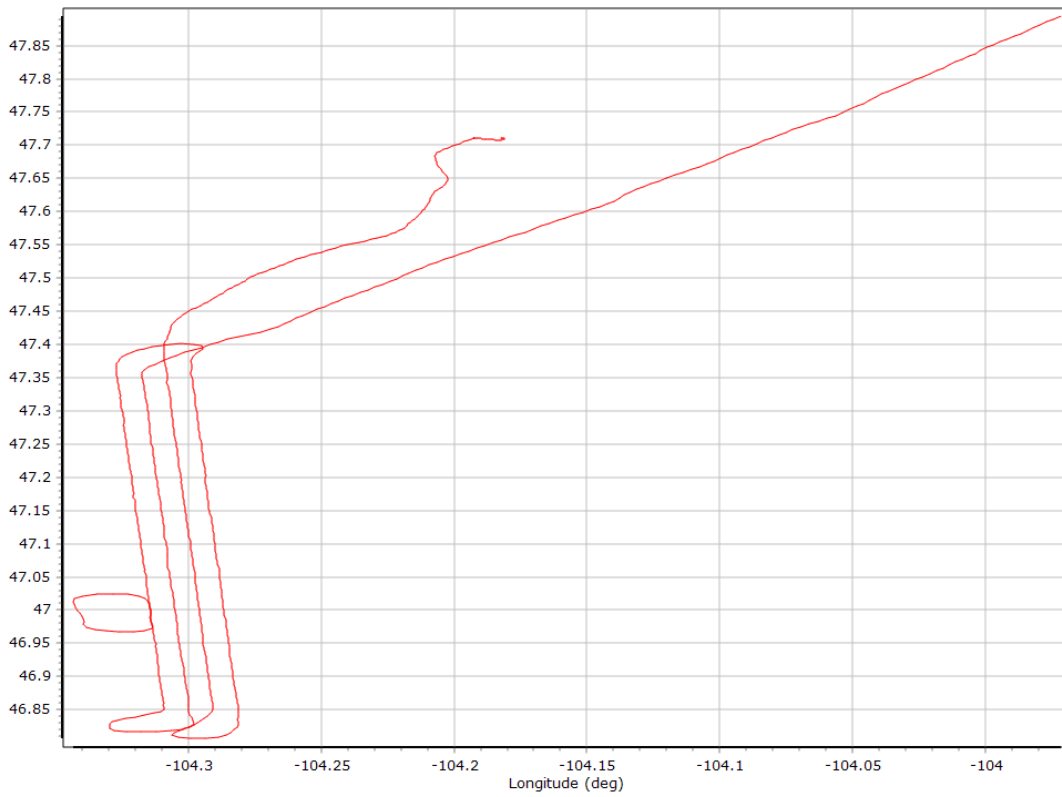


### Z Gyro Scale Error (ppm)

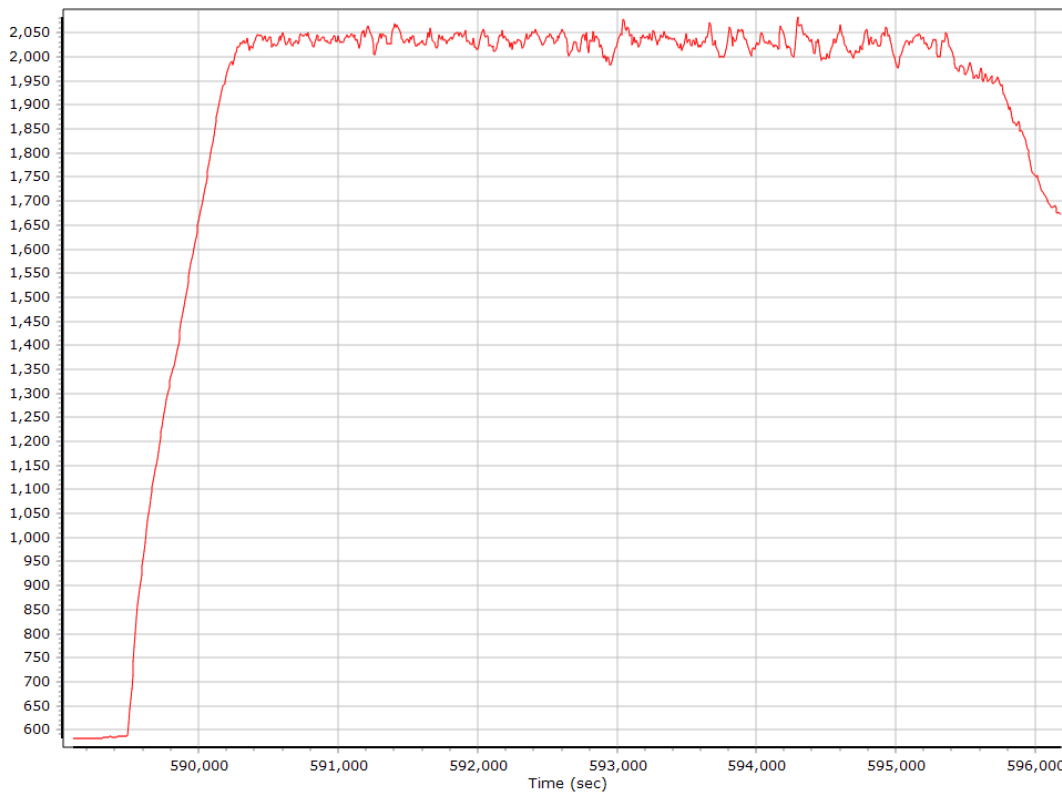


## Smoothed Trajectory Information

### Top View



### Altitude

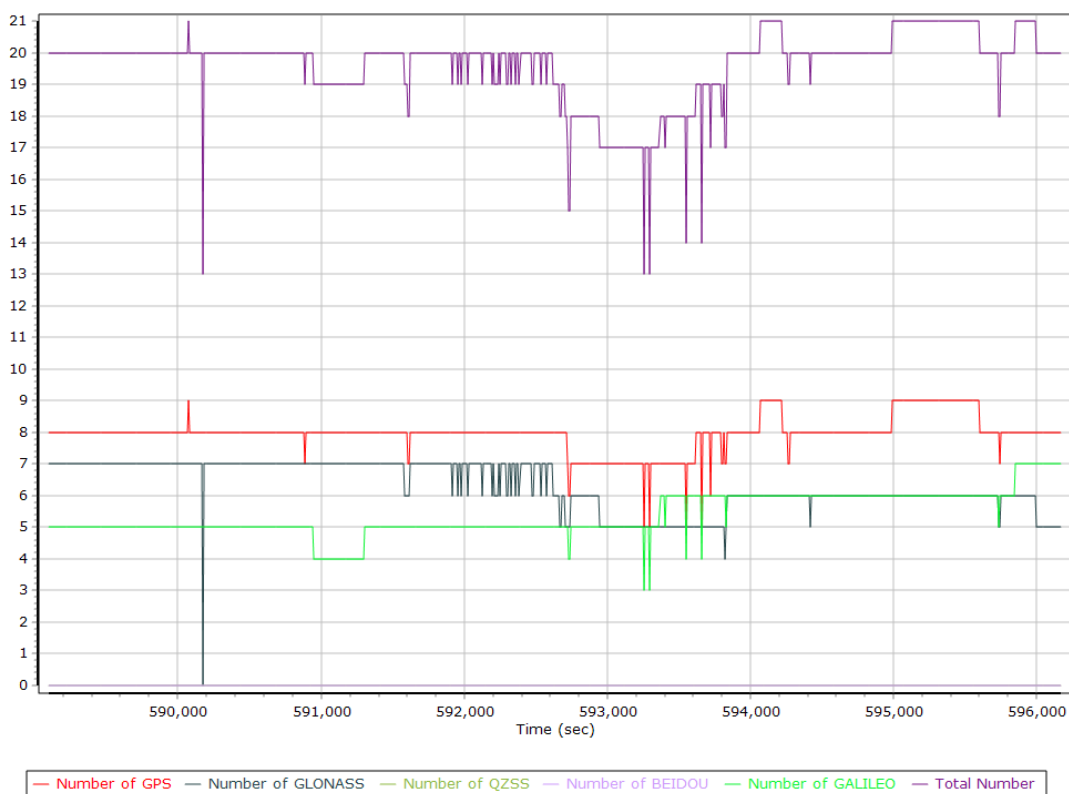


## GNSS QC

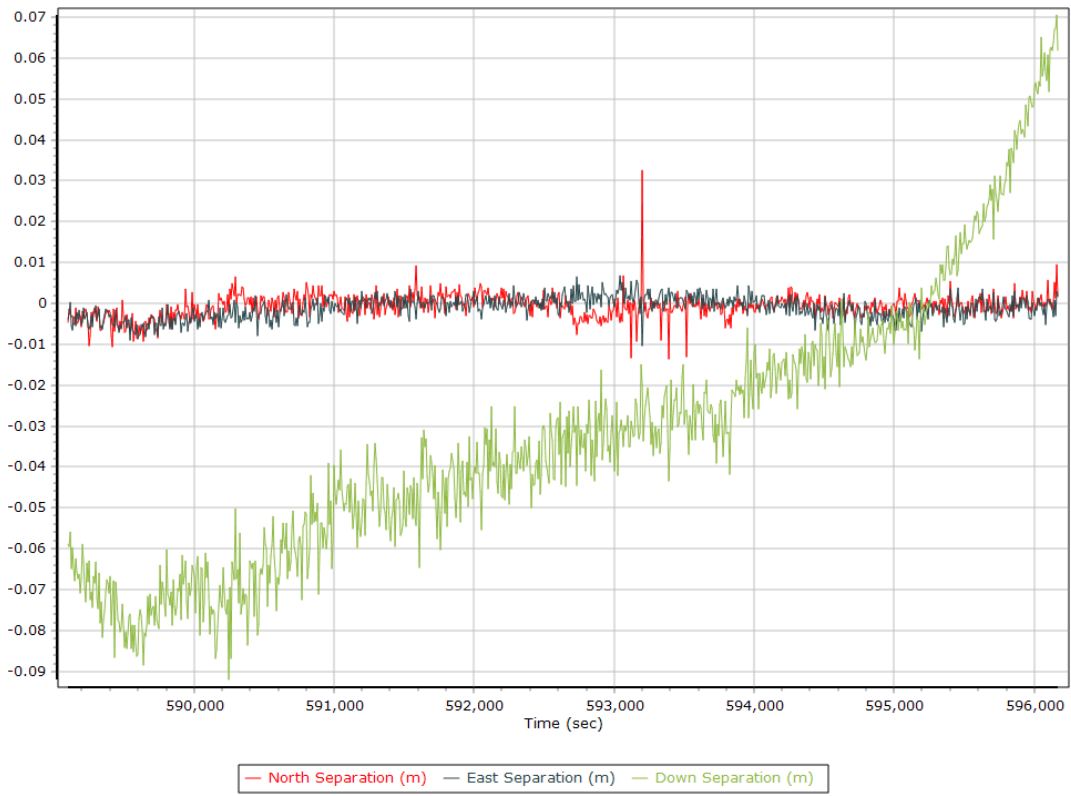
### GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	5	9	8
Number of GLONASS SV	0	7	6
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	0	0
Number of GALILEO SV	3	7	5
Total number of SV	13	21	20
PDOP	1.03	2.51	1.18
QC Solution Gaps	0.00	0.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	7504.00	0.00	0.00
Percentage	100.00	0.00	0.00

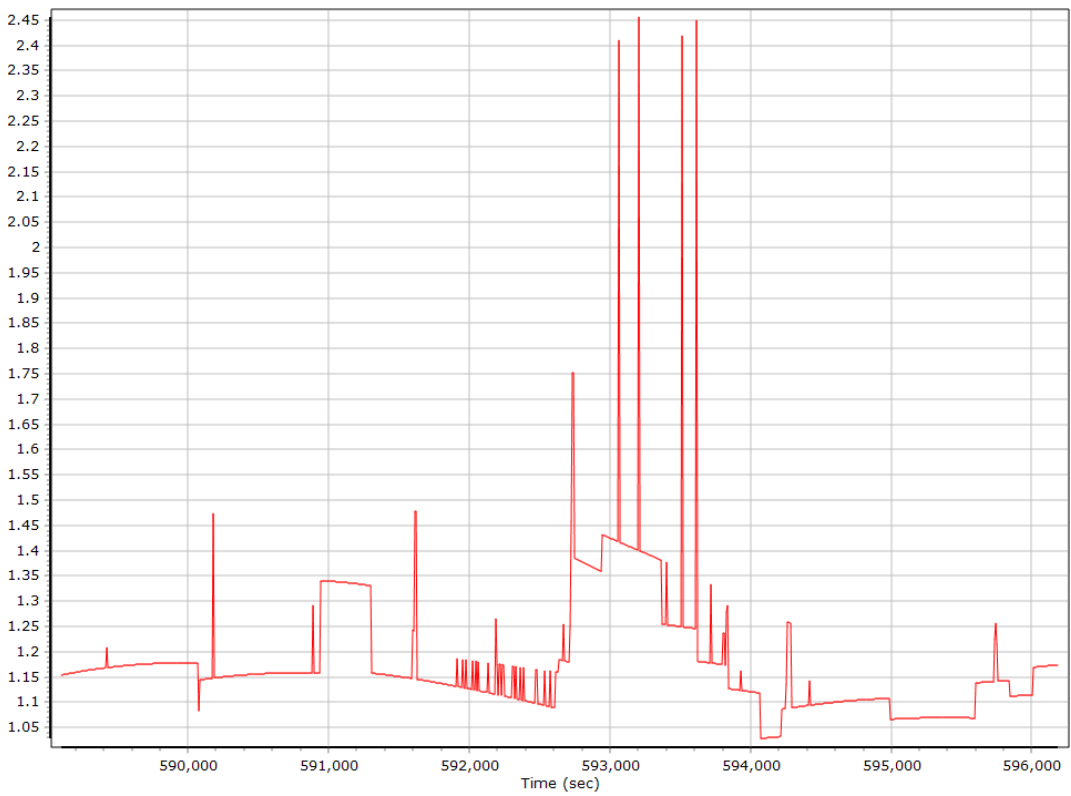
### Num SVs in solution



## Forward/Reverse Separation



## PDOP

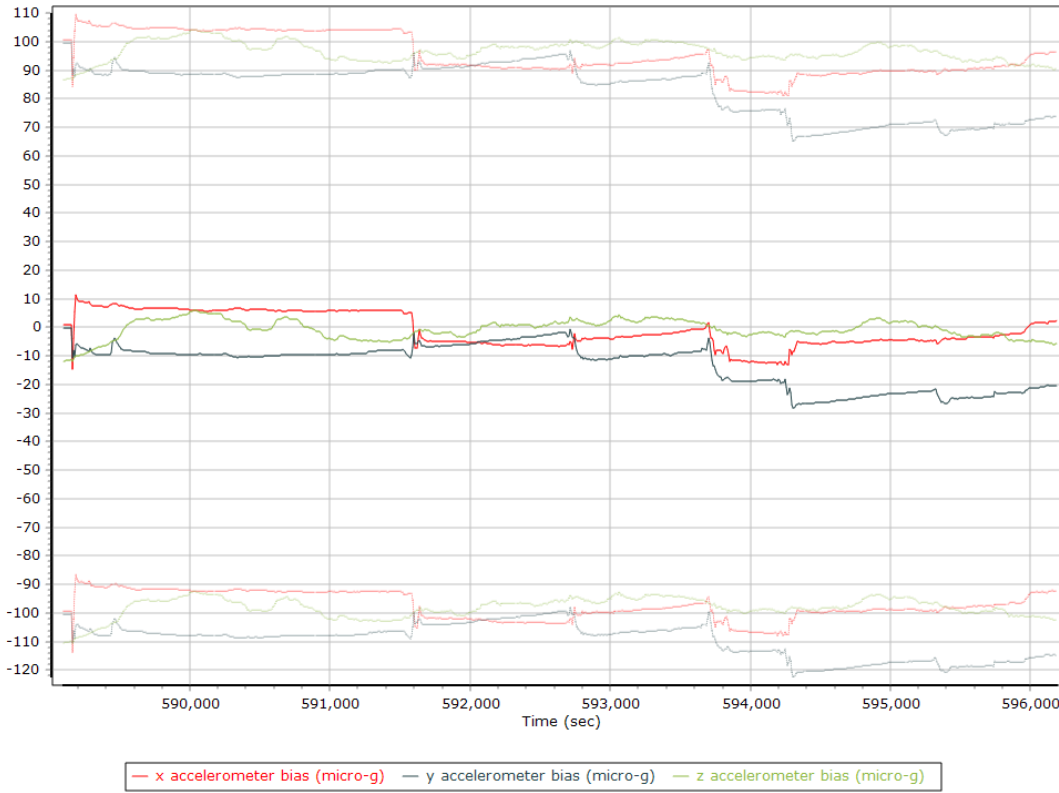




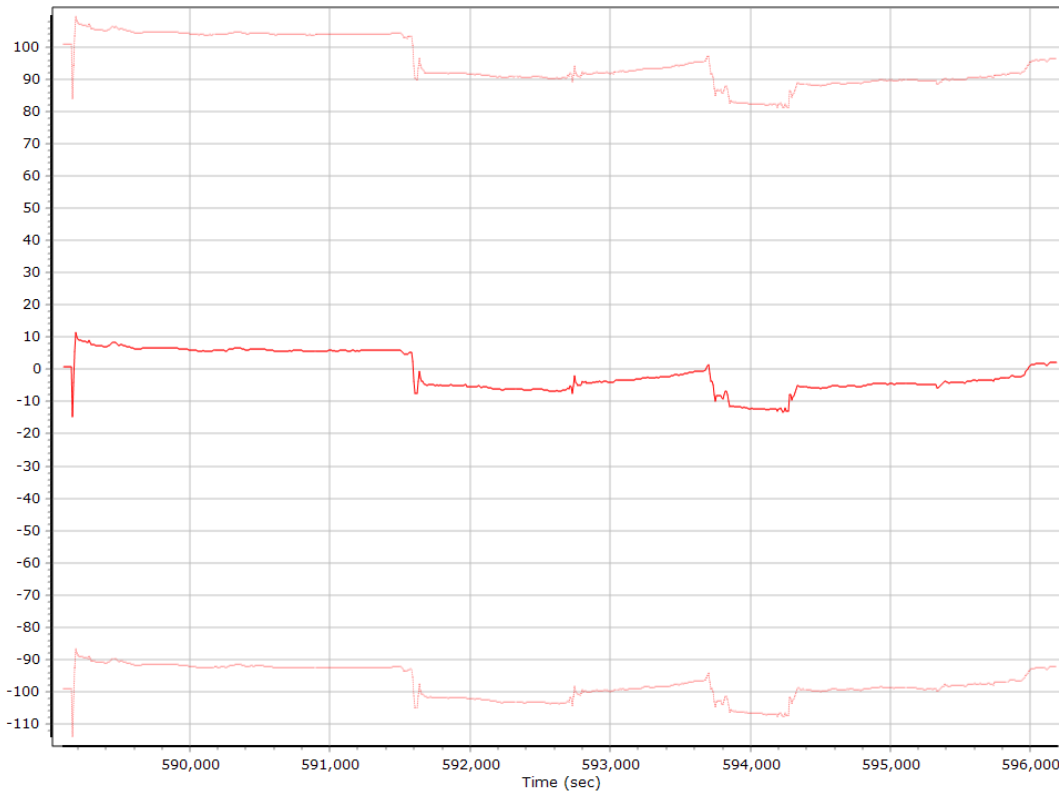
## IN-Fusion QC

### Forward Processed Estimated Errors, Reference Frame

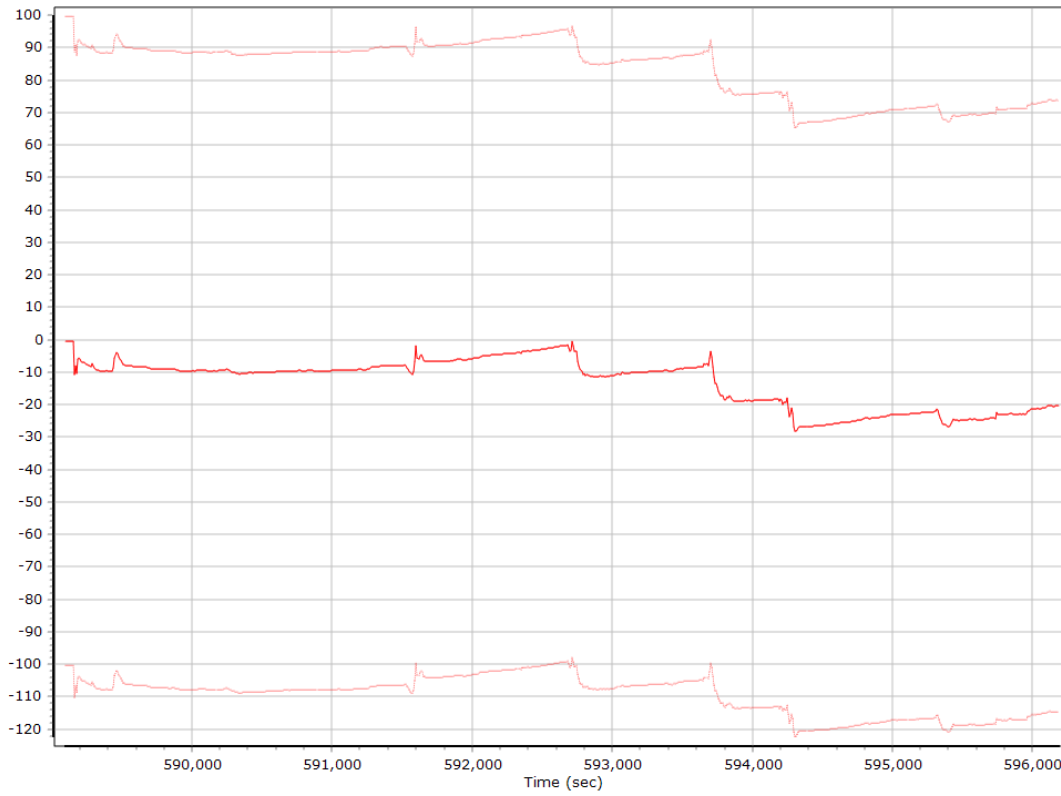
#### Accelerometer Bias (micro-g)



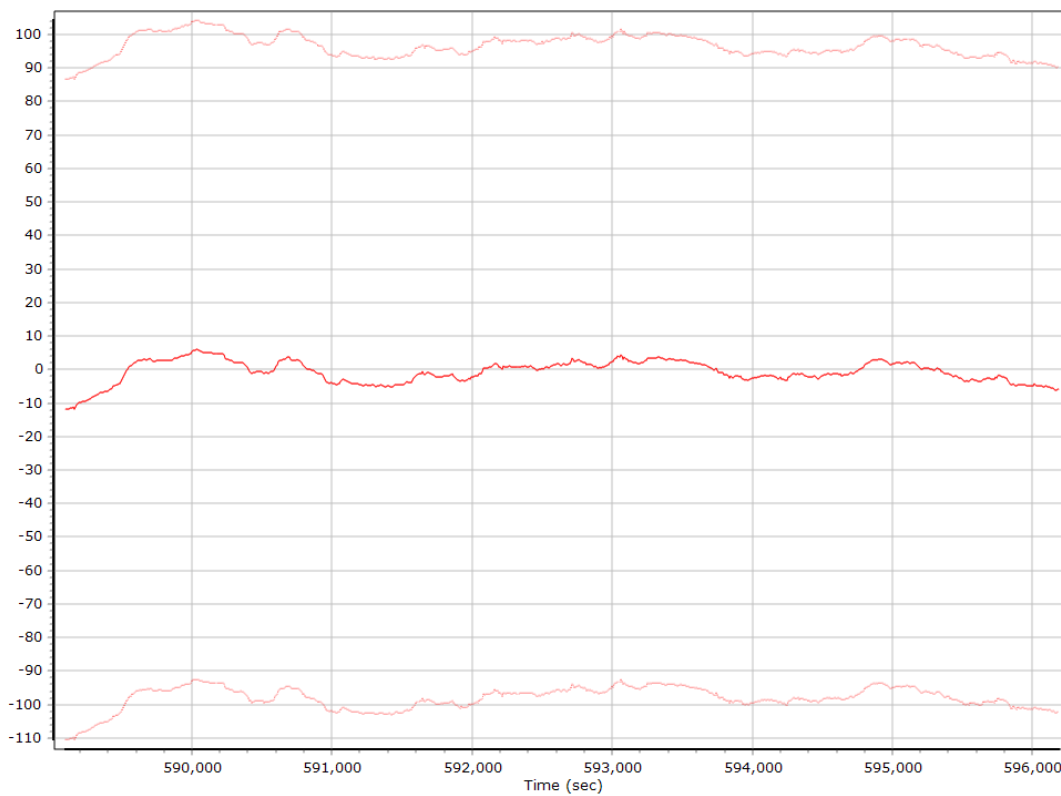
#### X Accelerometer Bias (micro-g)



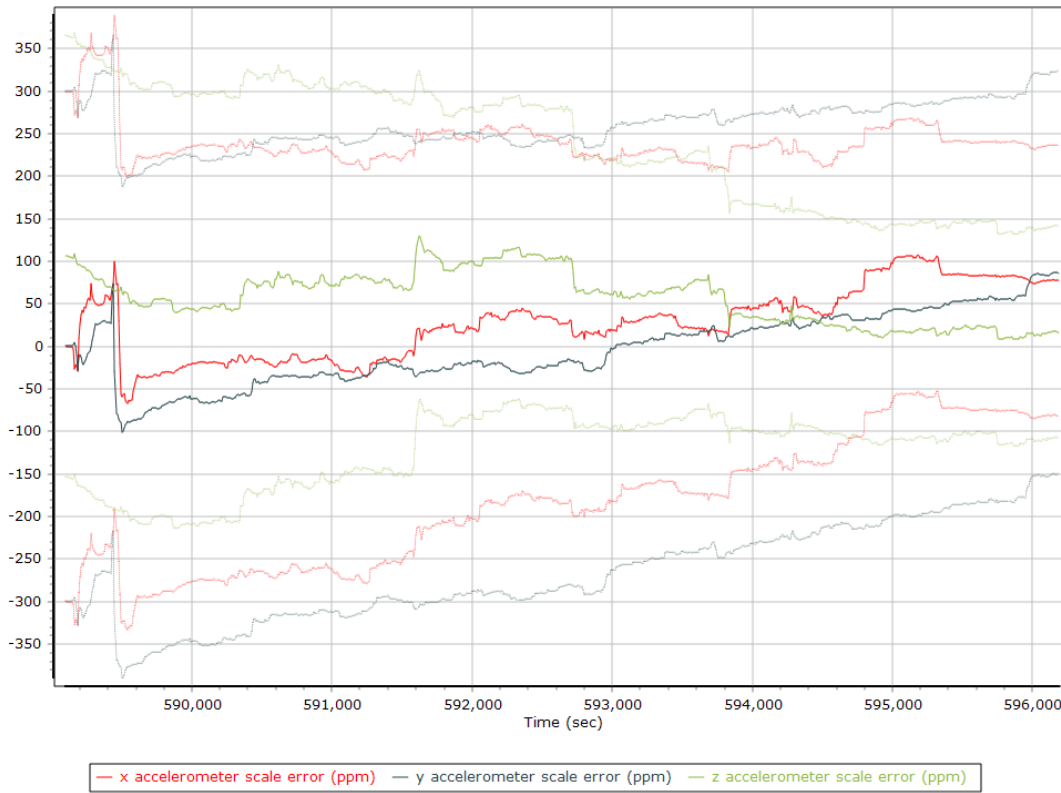
### Y Accelerometer Bias (micro-g)



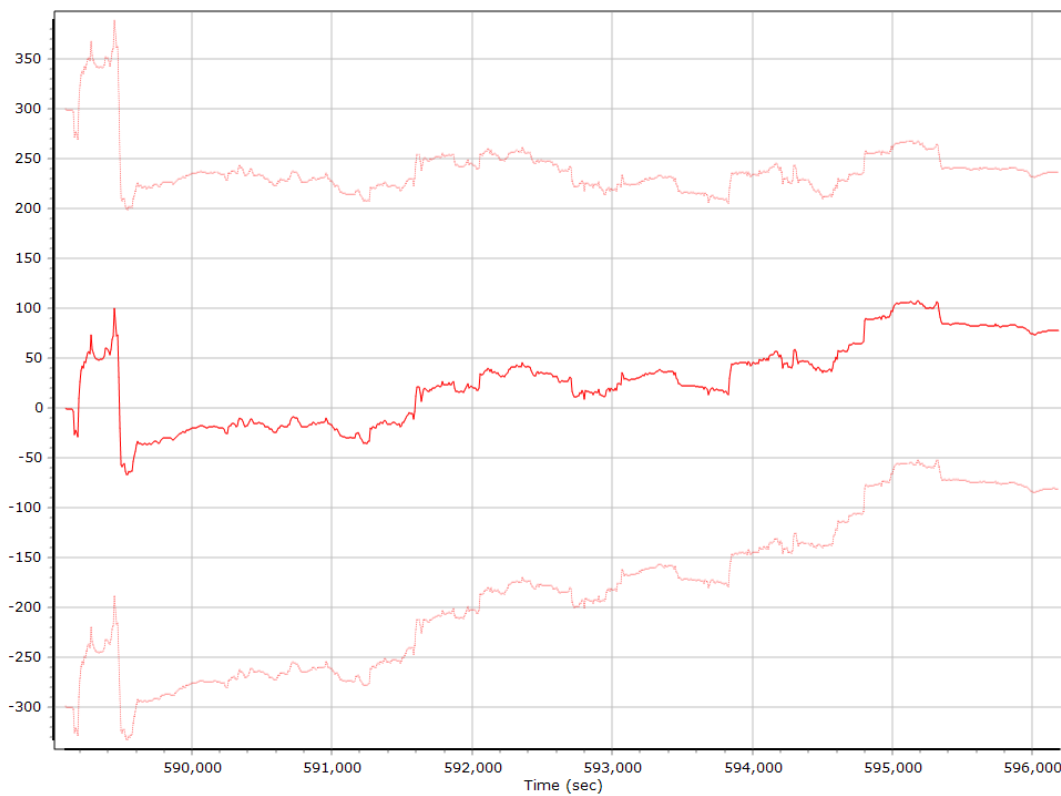
### Z Accelerometer Bias (micro-g)



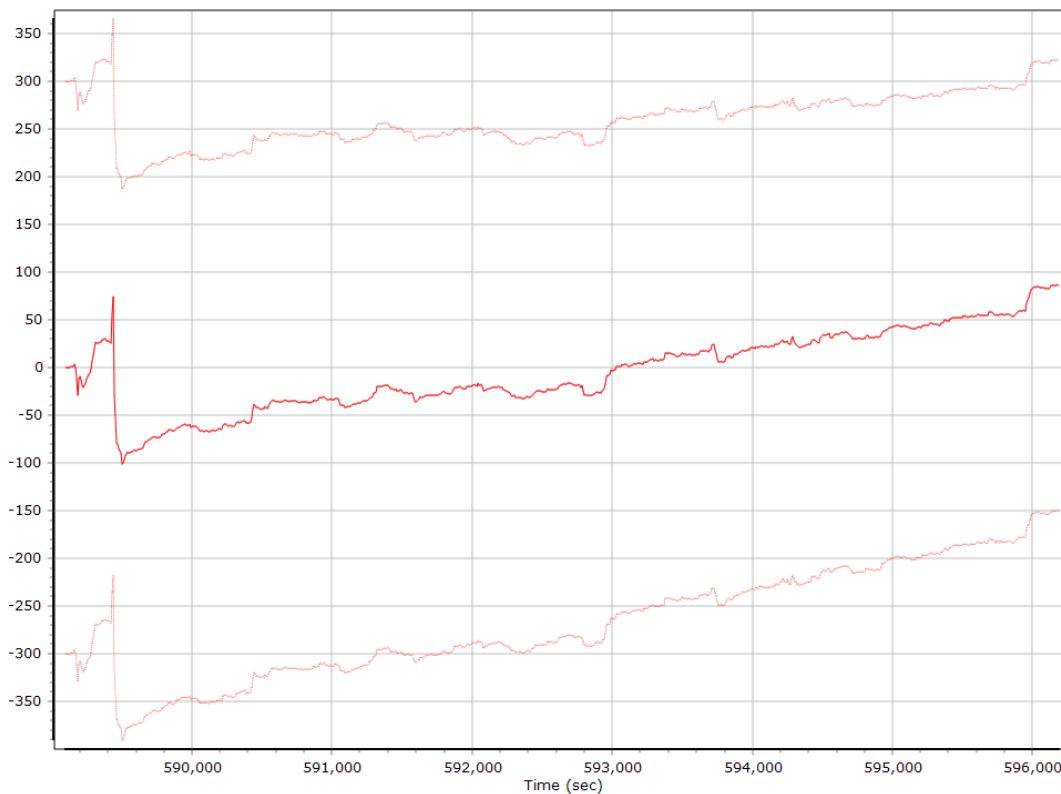
### Accelerometer Scale Error (ppm)



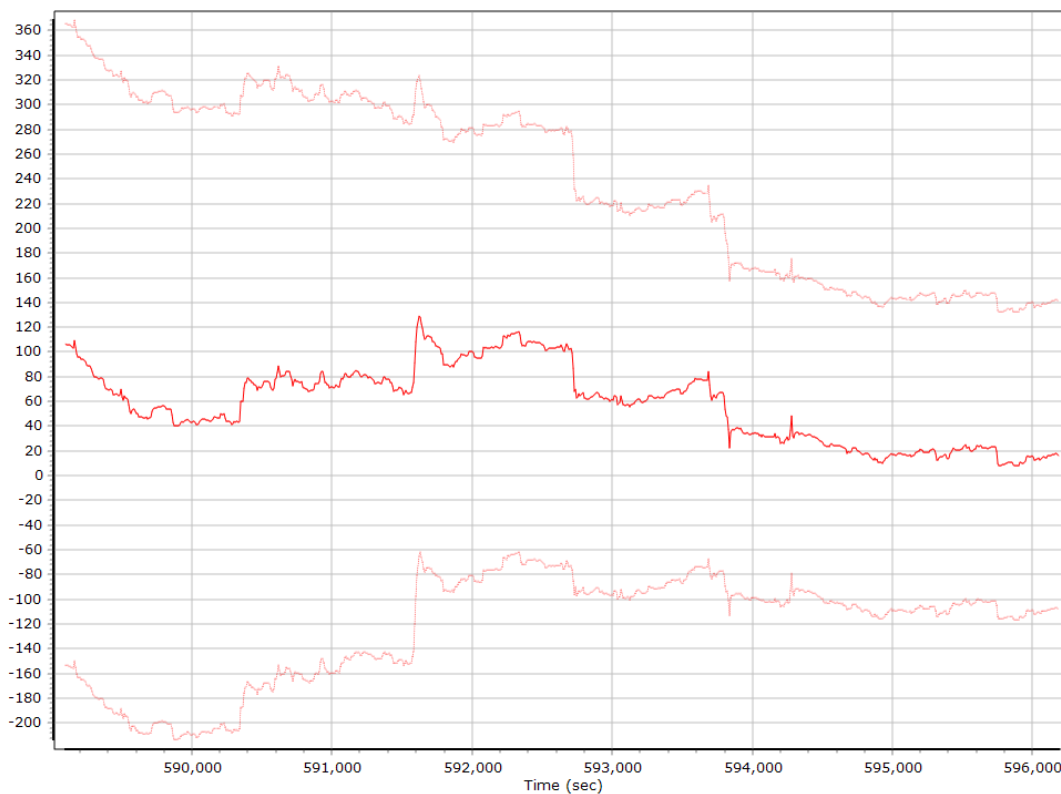
### X Accelerometer Scale Error (ppm)



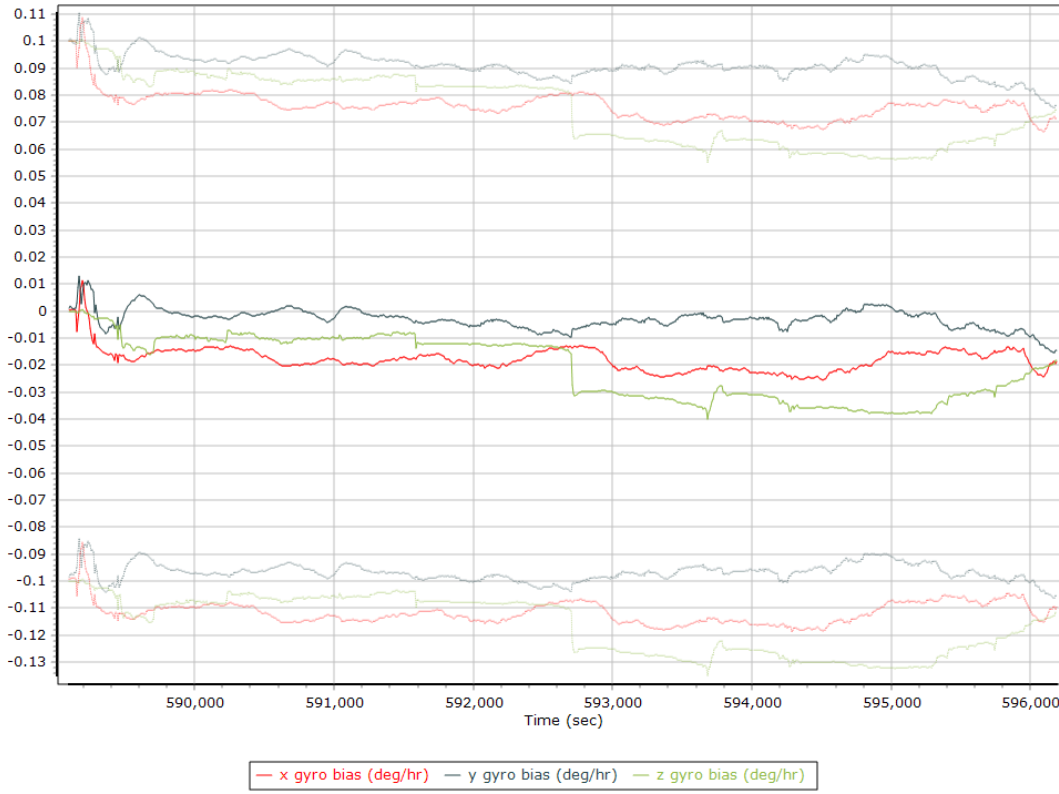
### Y Accelerometer Scale Error (ppm)



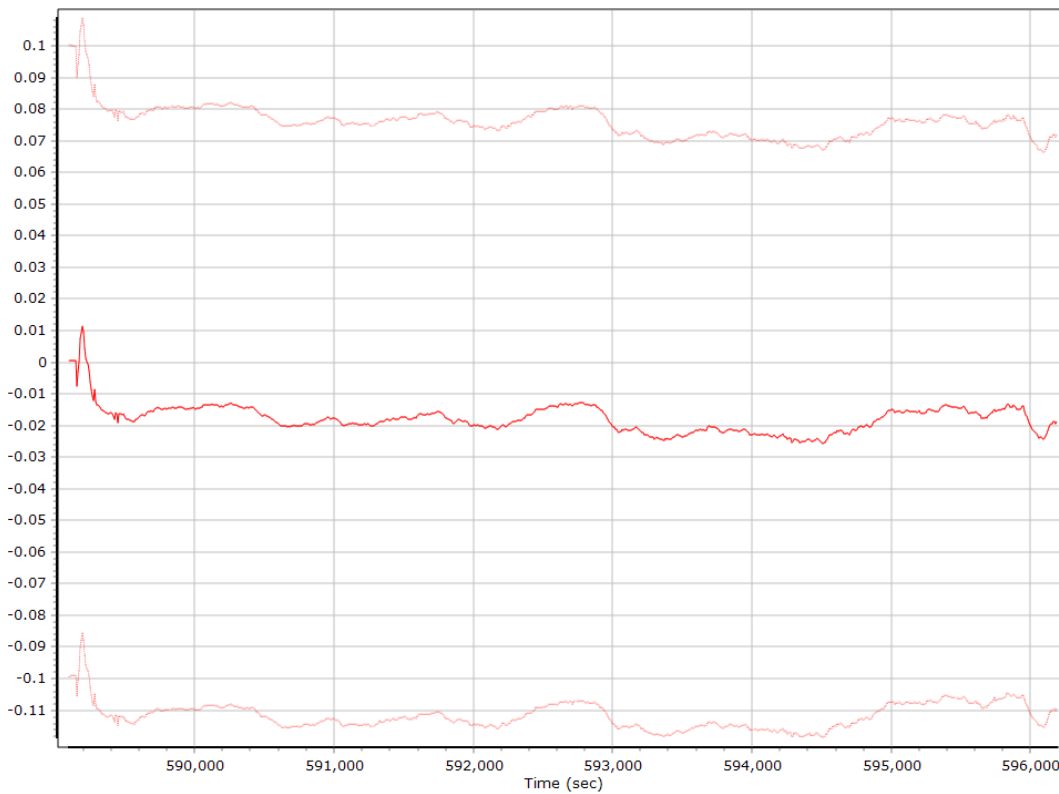
### Z Accelerometer Scale Error (ppm)



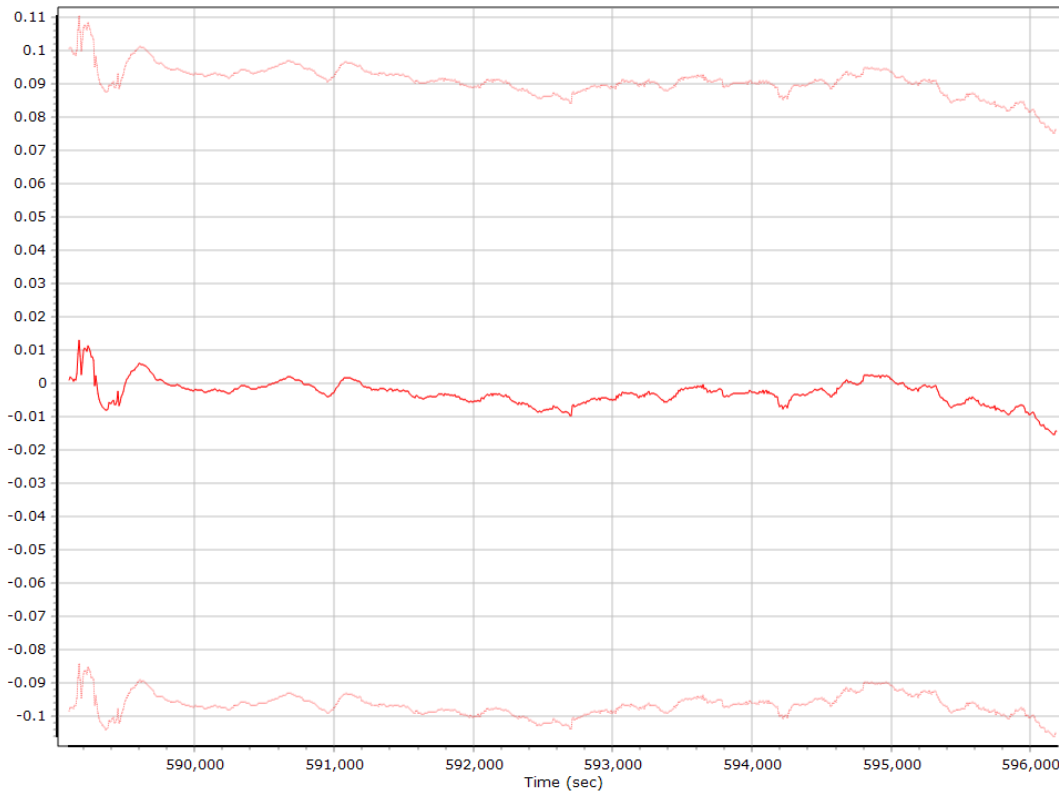
### Gyro Bias (deg/h)



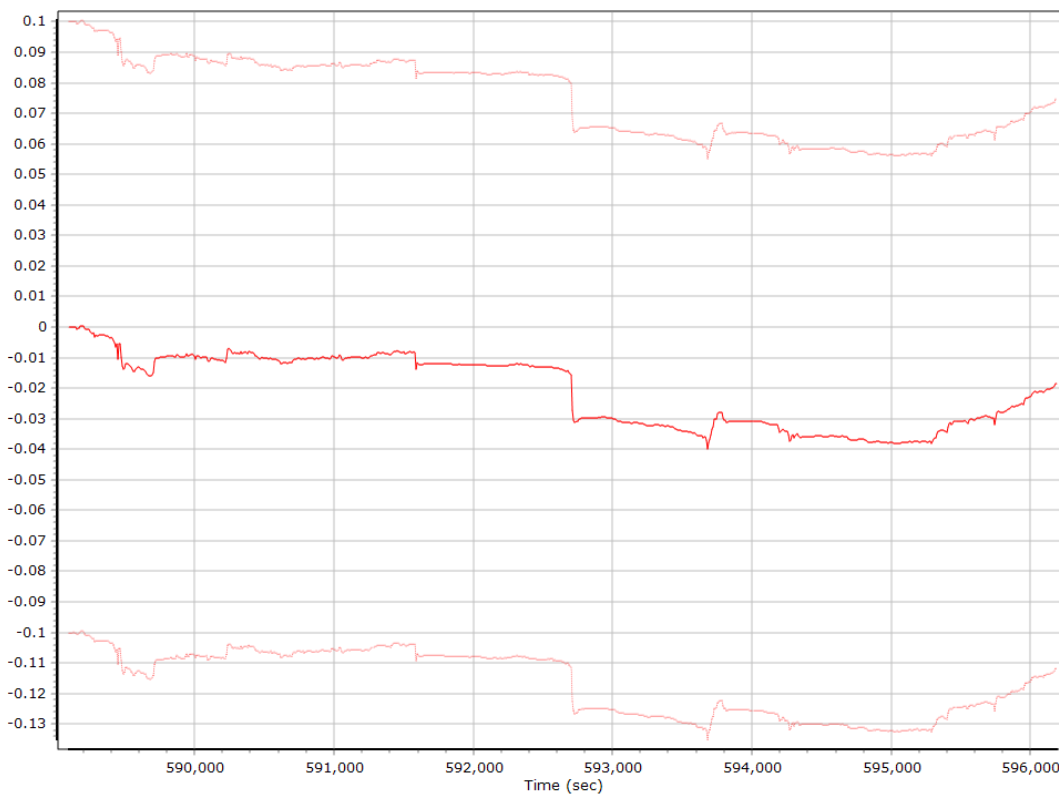
### X Gyro Bias (deg/h)



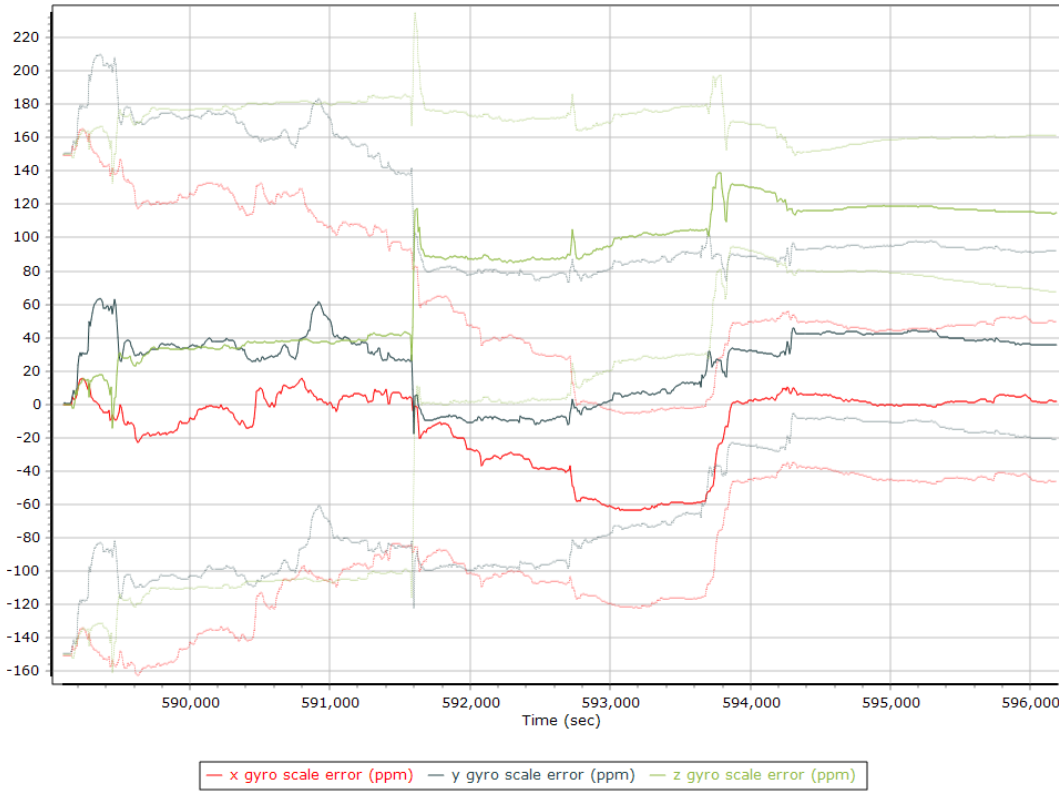
### Y Gyro Bias (deg/h)



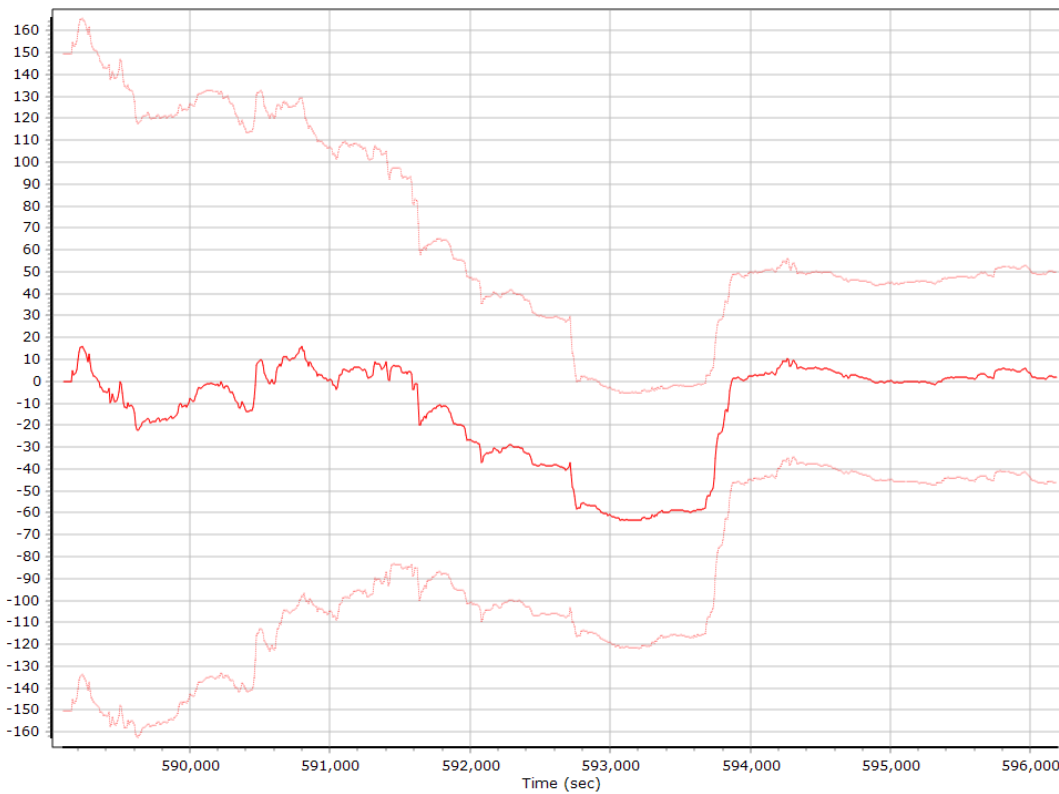
### Z Gyro Bias (deg/h)



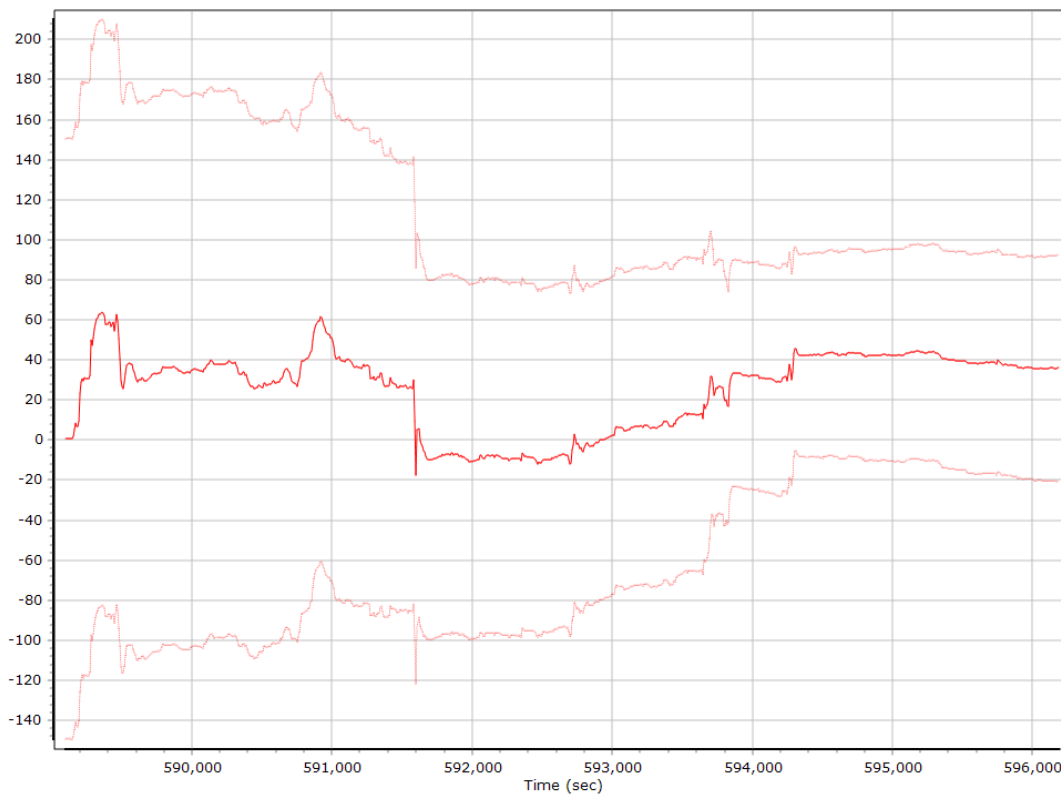
### Gyro Scale Error (ppm)



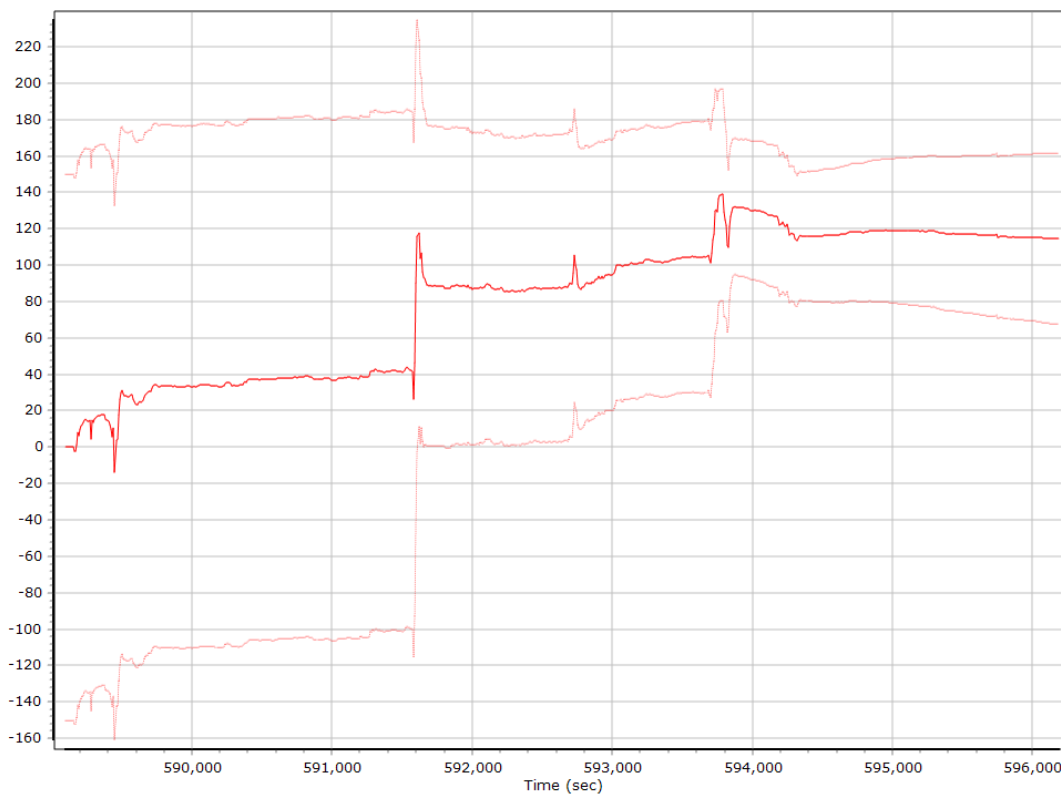
### X Gyro Scale Error (ppm)



### Y Gyro Scale Error (ppm)



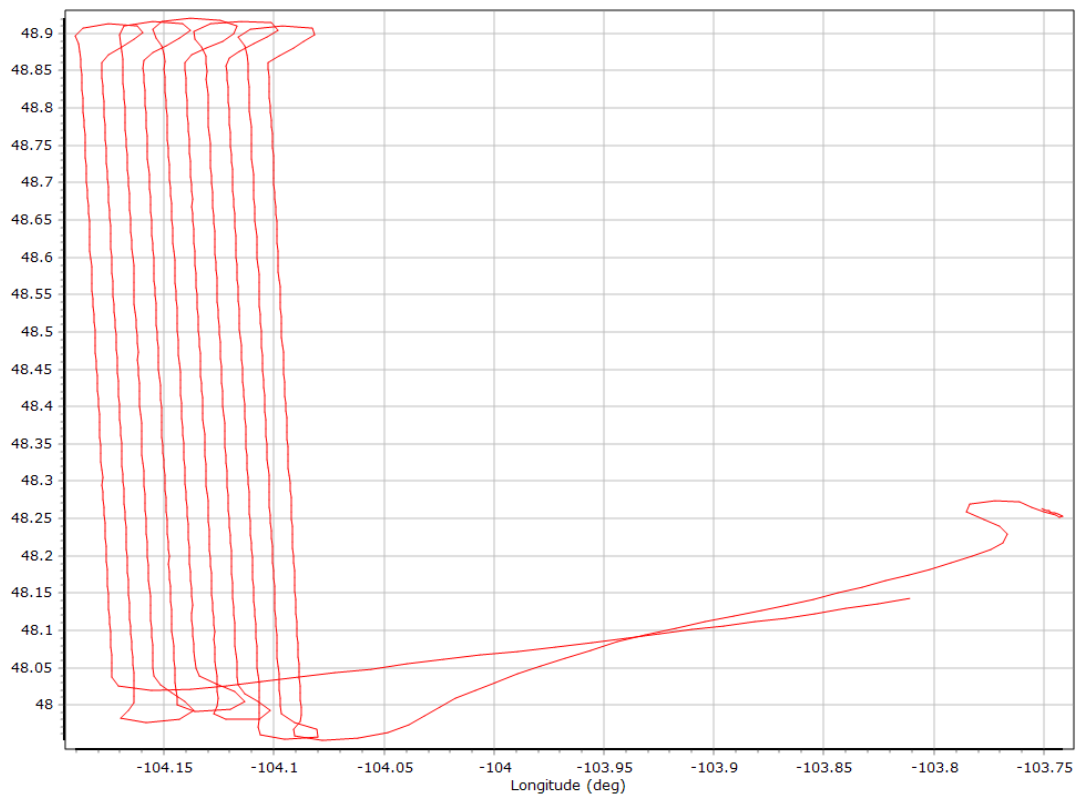
### Z Gyro Scale Error (ppm)



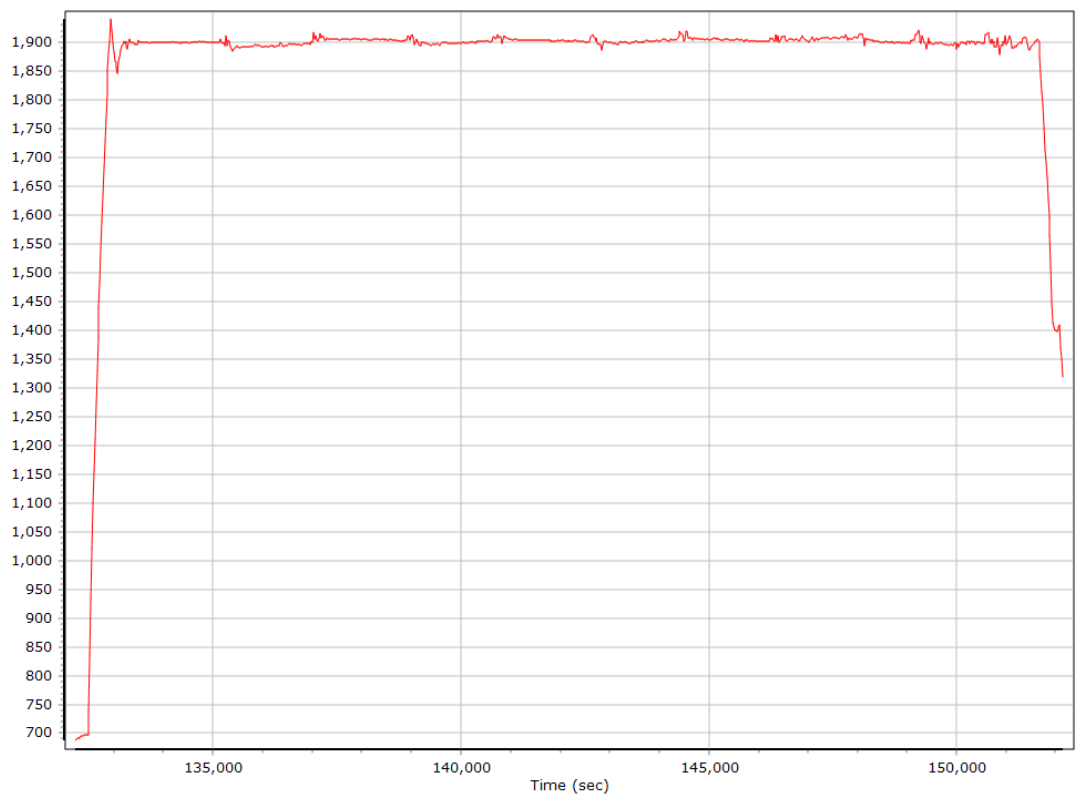


## Smoothed Trajectory Information

### Top View



### Altitude

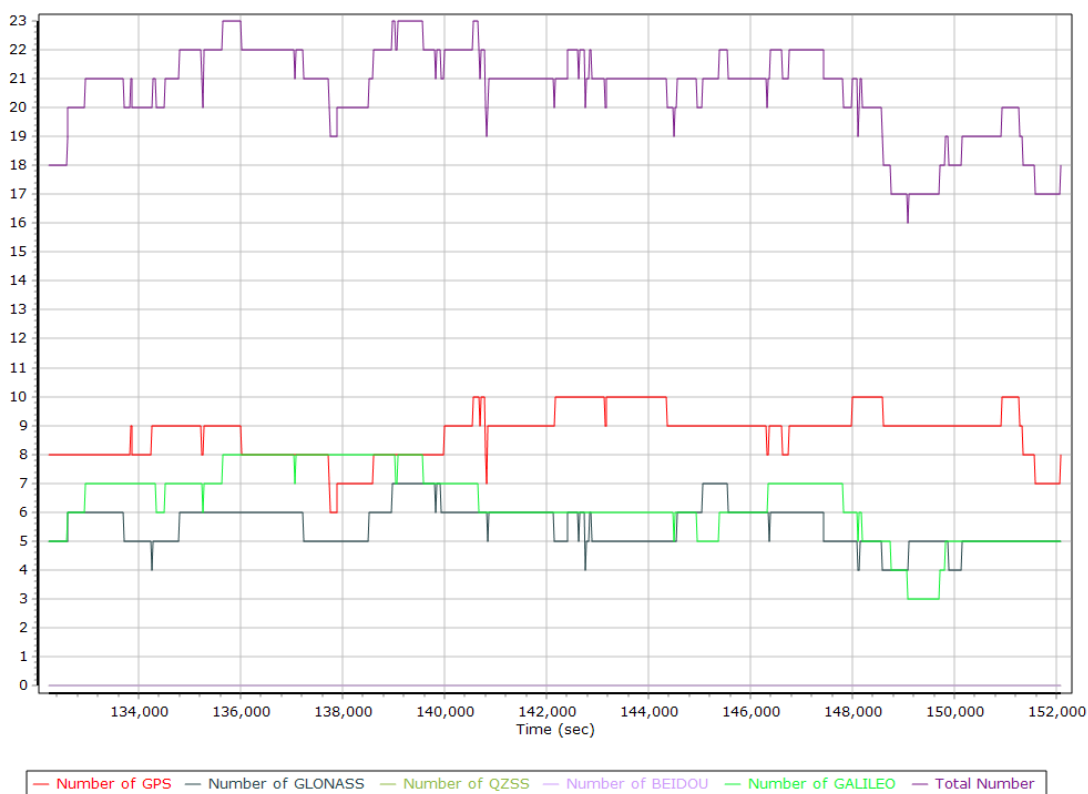


## GNSS QC

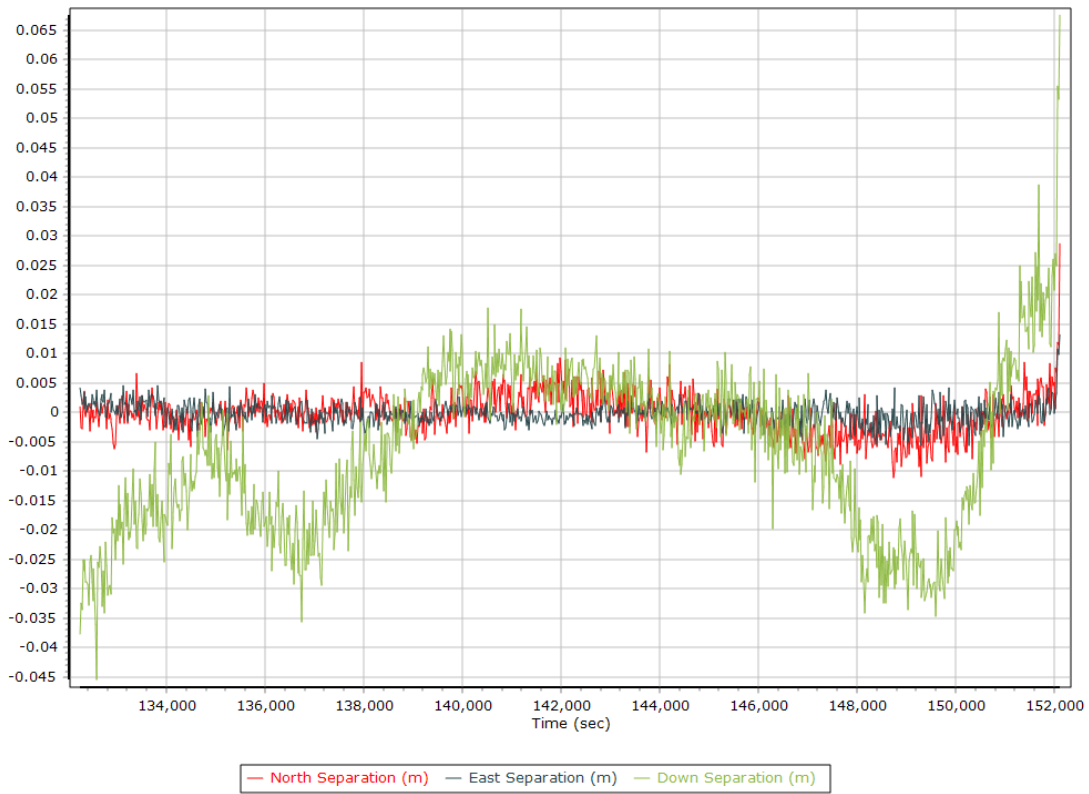
### GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	6	10	9
Number of GLONASS SV	0	7	6
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	0	0
Number of GALILEO SV	0	8	6
Total number of SV	12	23	21
PDOP	1.01	1.49	1.17
QC Solution Gaps	0.00	0.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	20304.00	0.00	0.00
Percentage	100.00	0.00	0.00

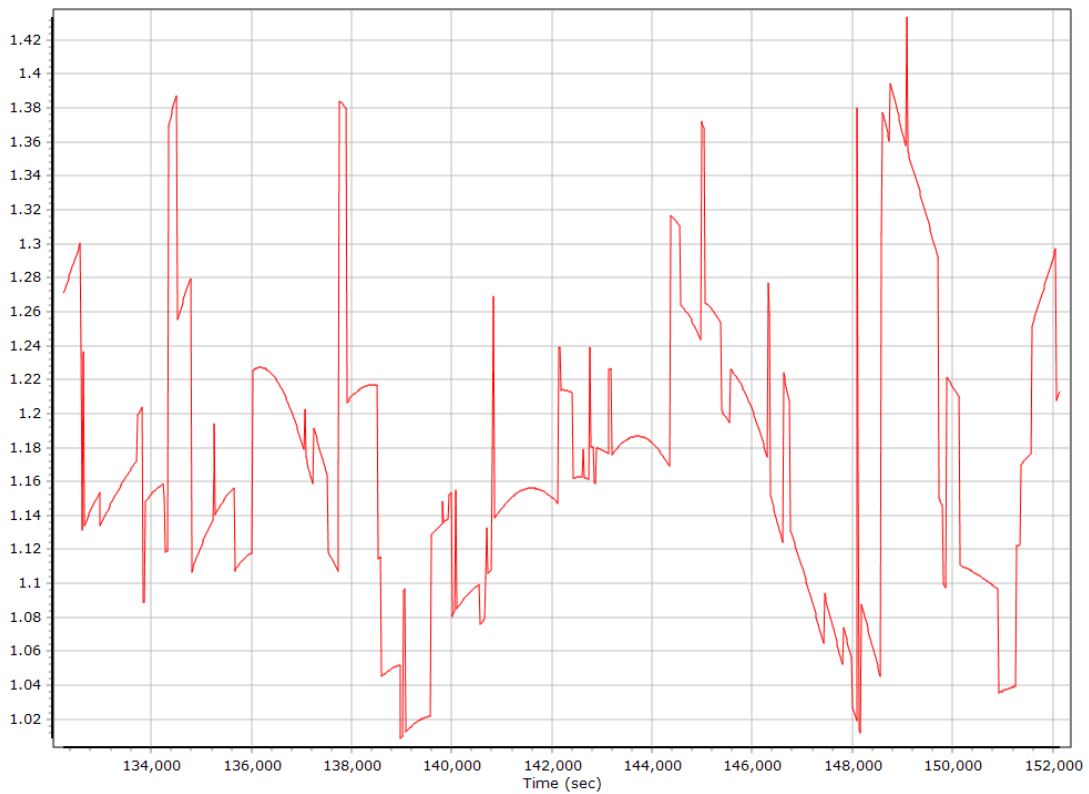
### Num SVs in solution



## Forward/Reverse Separation



## PDOP



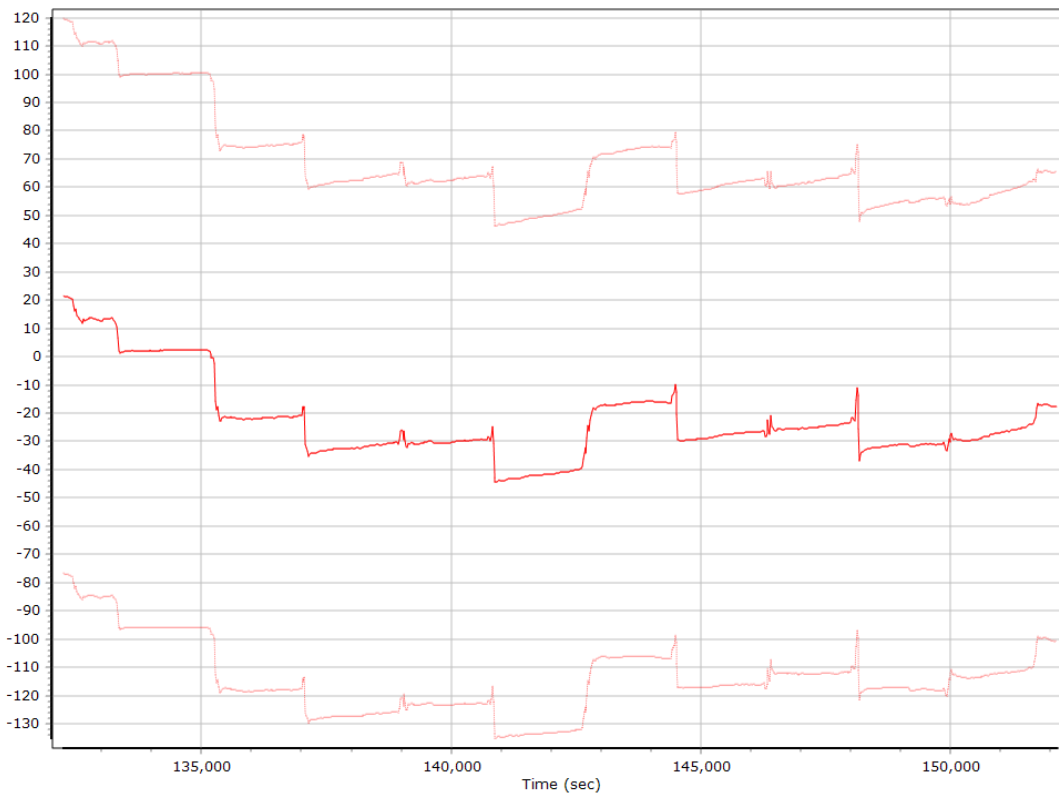
## IN-Fusion QC

### Forward Processed Estimated Errors, Reference Frame

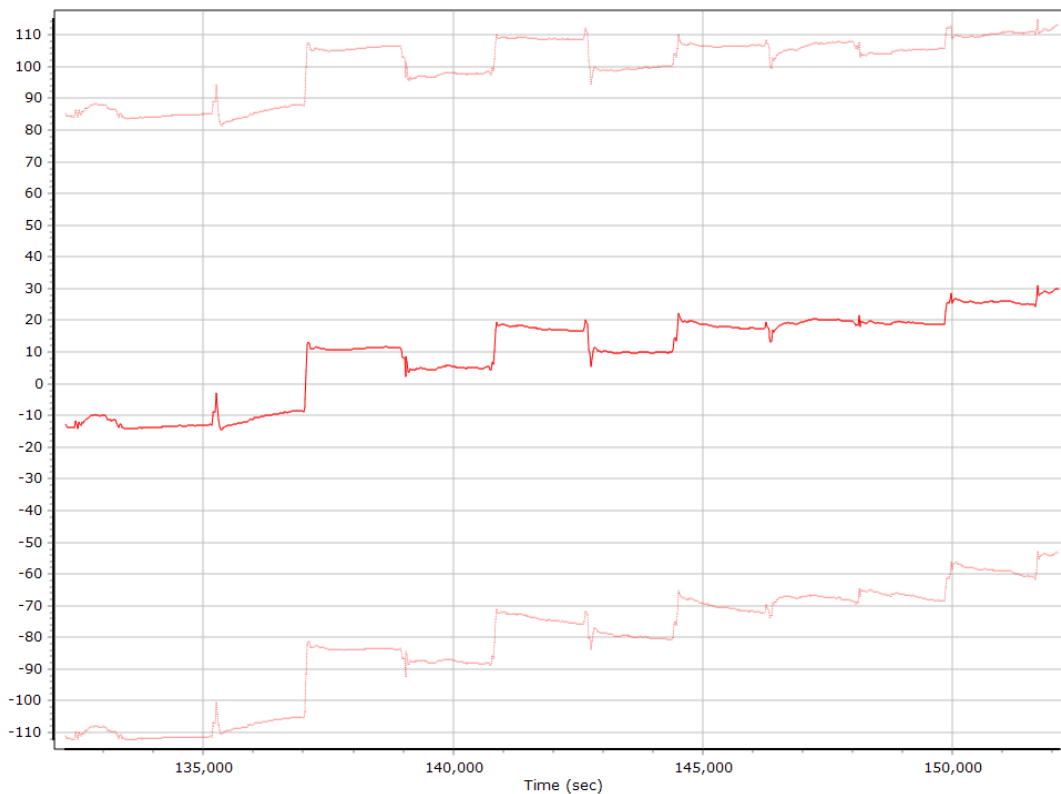
#### Accelerometer Bias (micro-g)



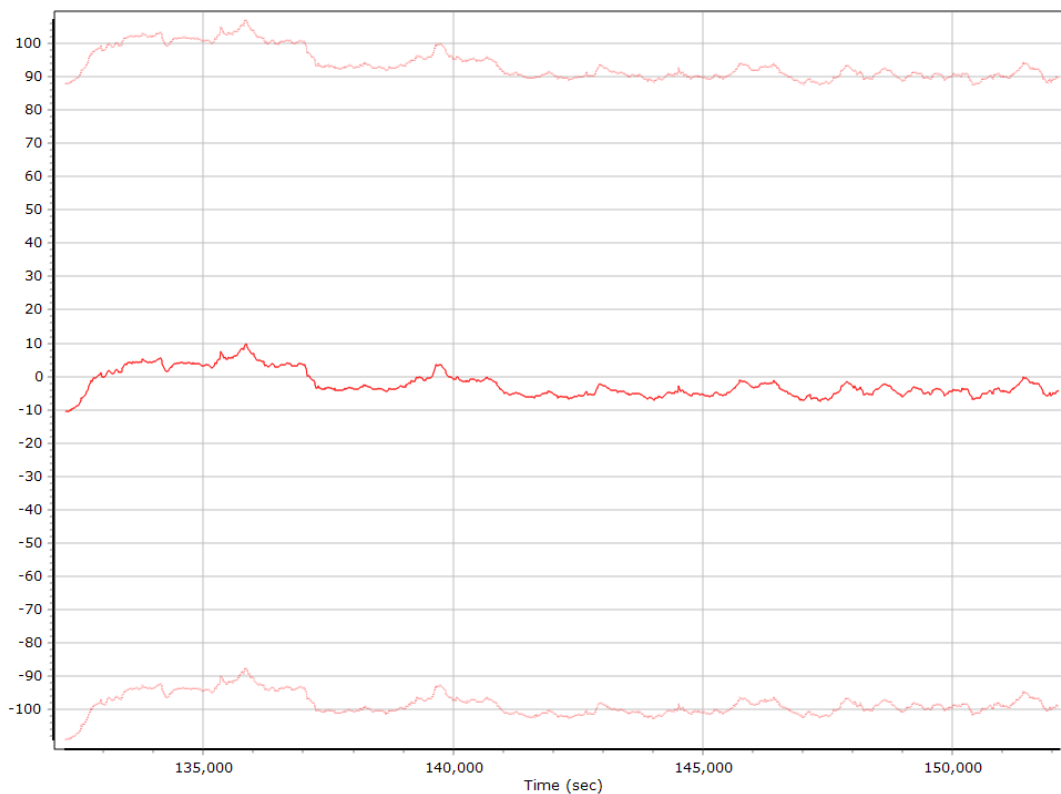
#### X Accelerometer Bias (micro-g)



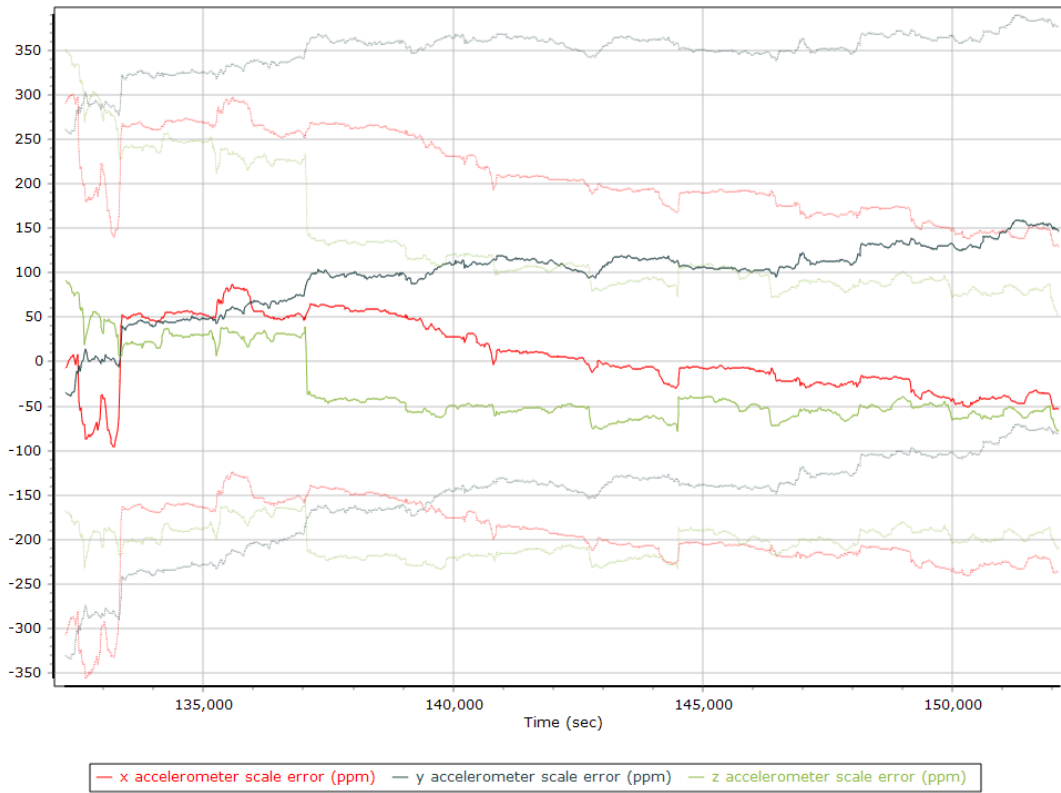
### Y Accelerometer Bias (micro-g)



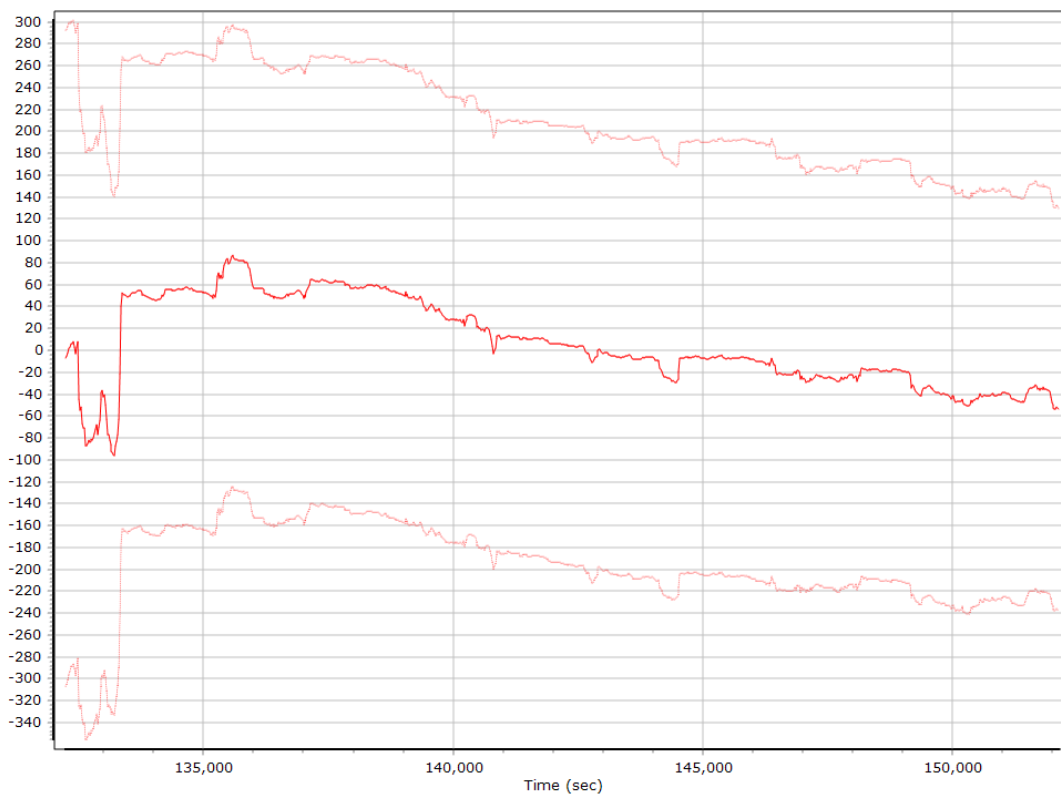
### Z Accelerometer Bias (micro-g)



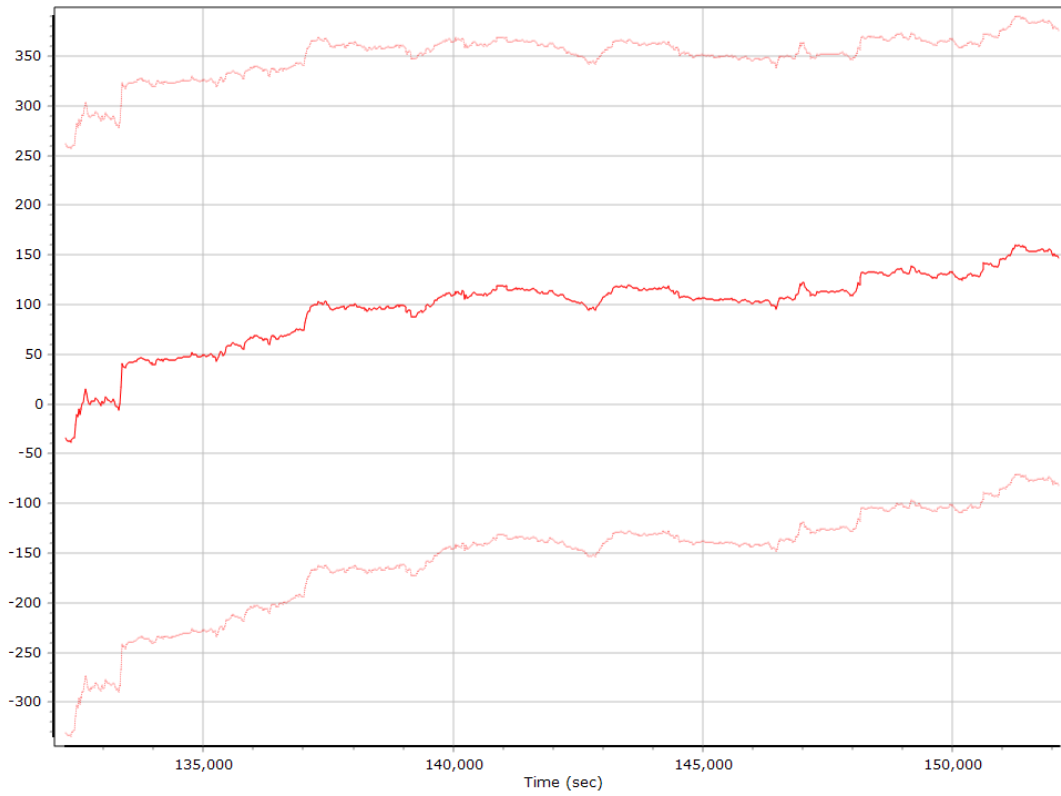
### Accelerometer Scale Error (ppm)



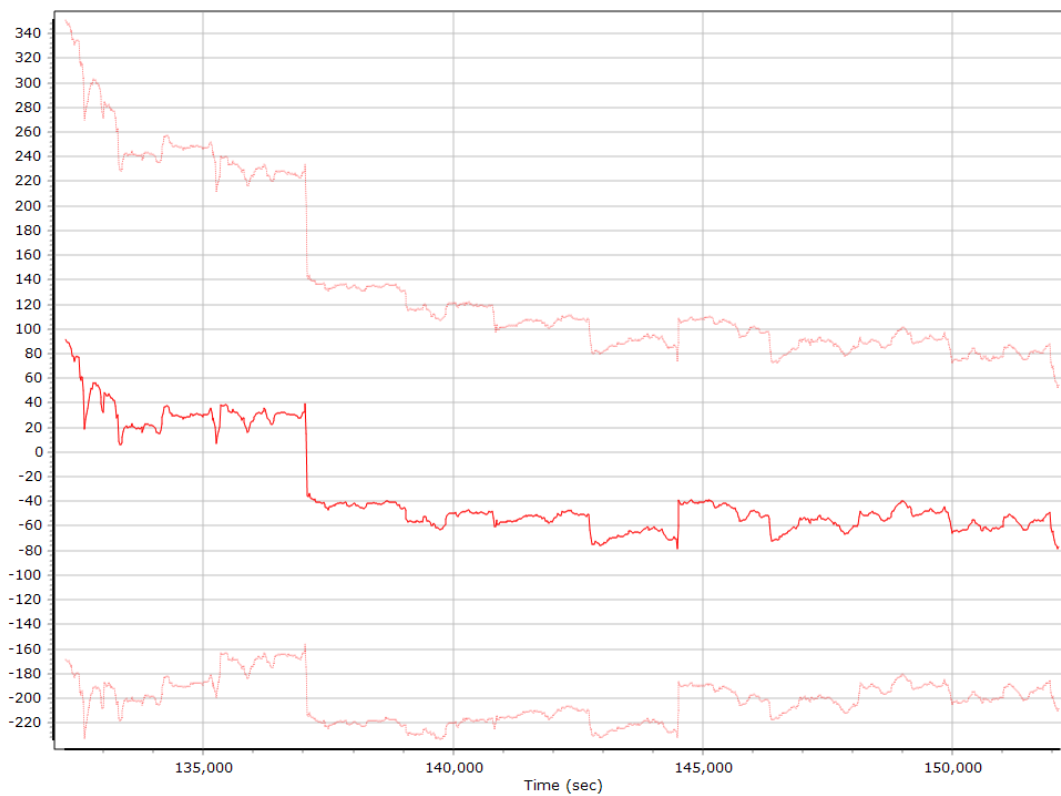
### X Accelerometer Scale Error (ppm)



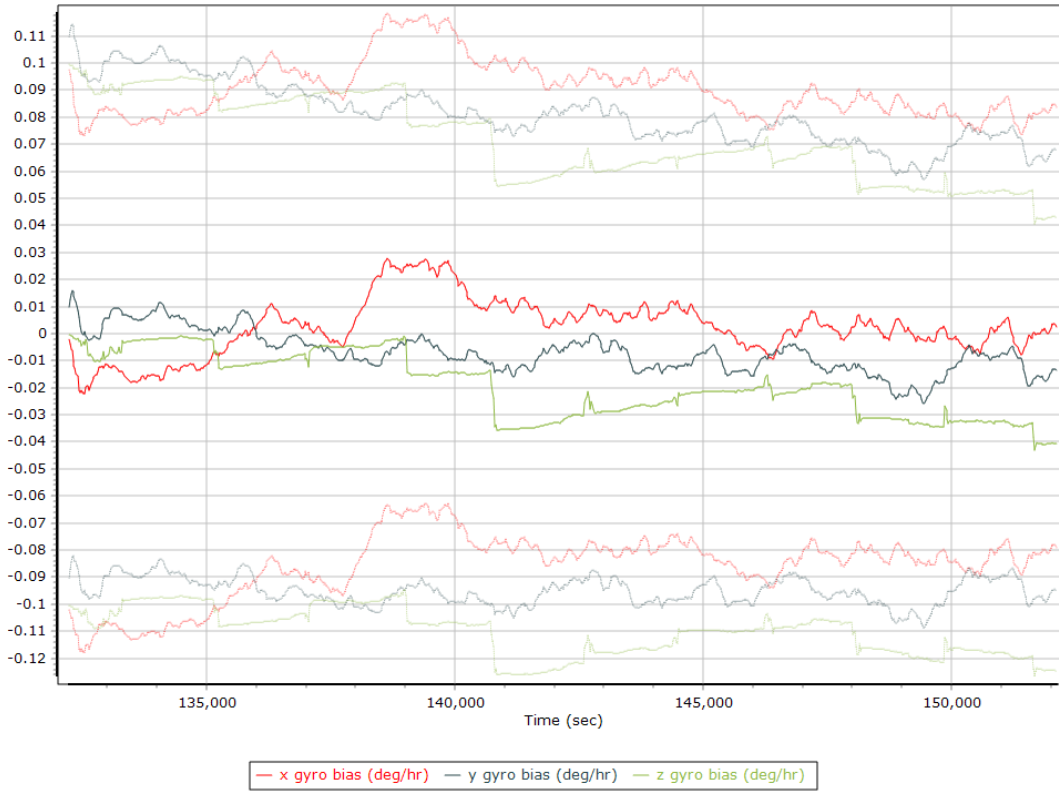
### Y Accelerometer Scale Error (ppm)



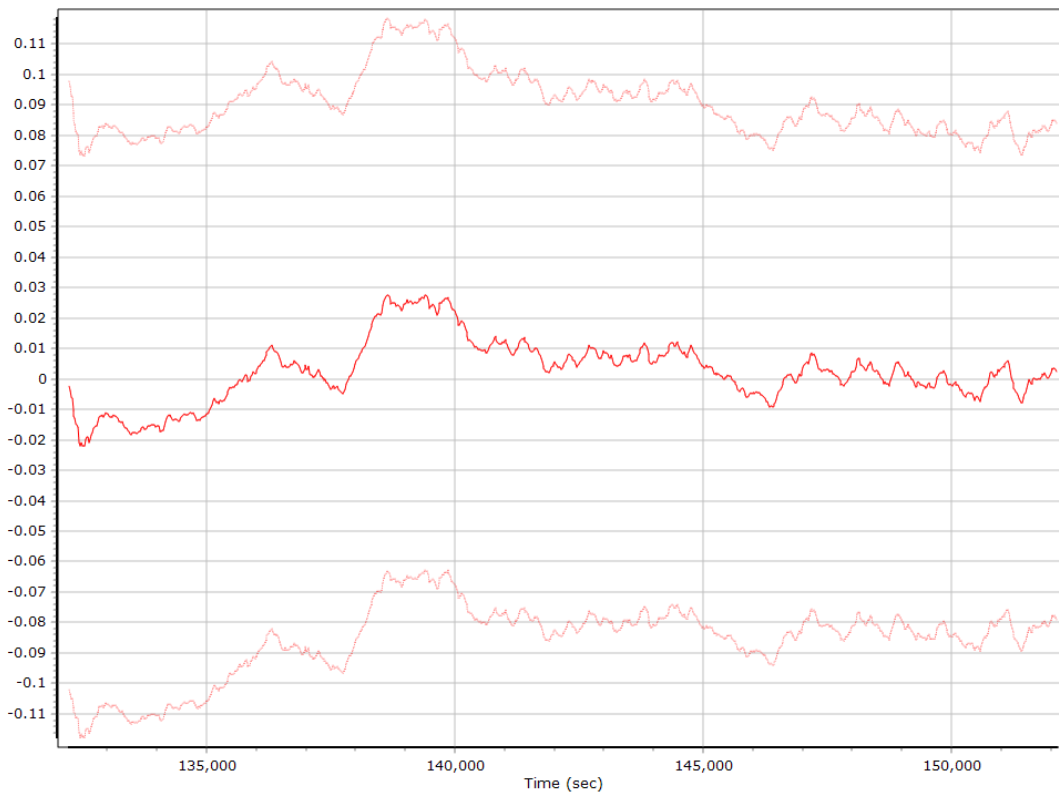
### Z Accelerometer Scale Error (ppm)



### Gyro Bias (deg/h)

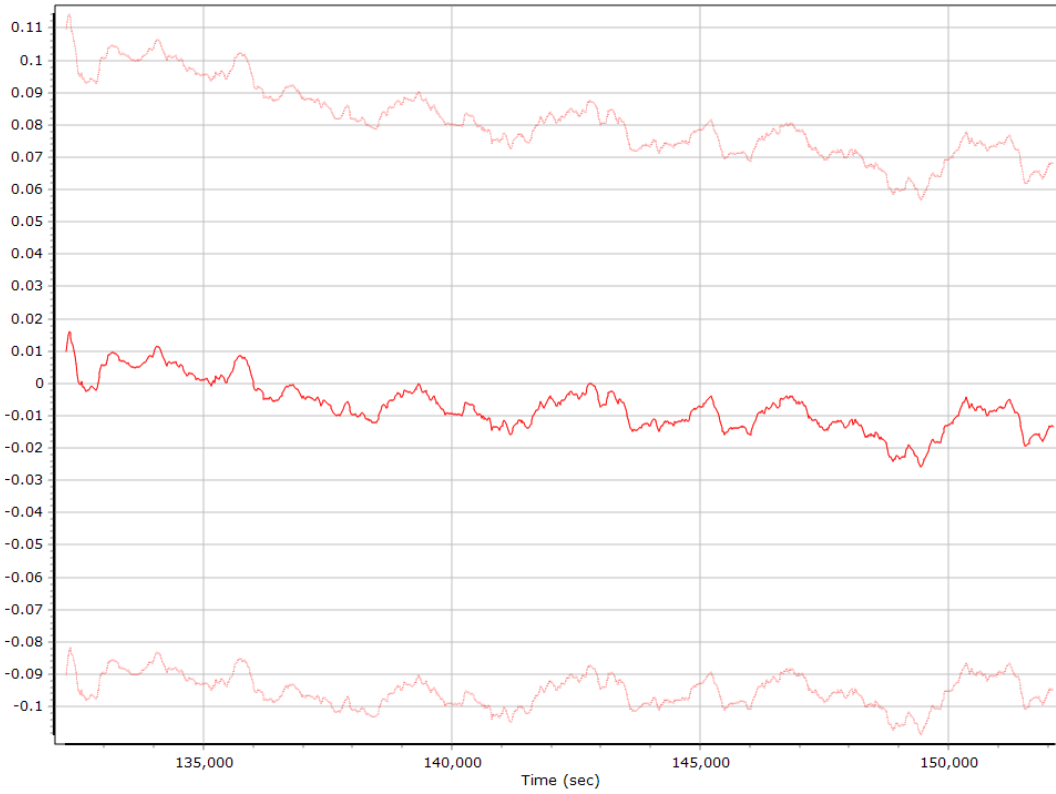


### X Gyro Bias (deg/h)

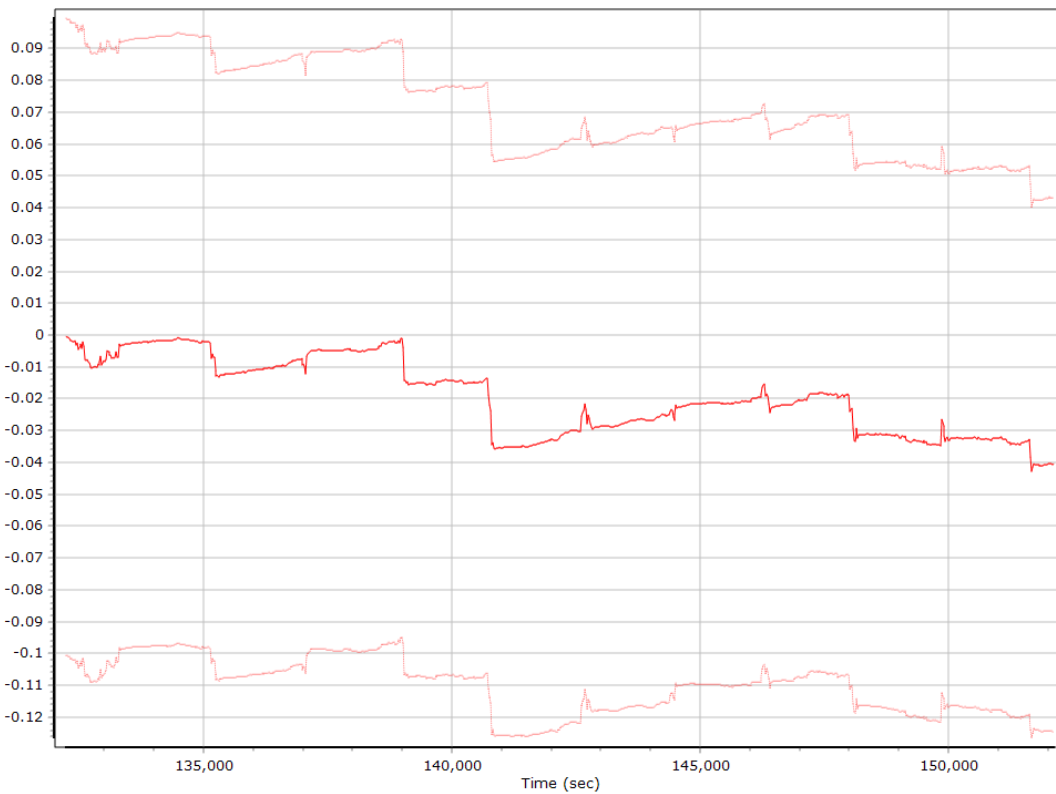




### Y Gyro Bias (deg/h)



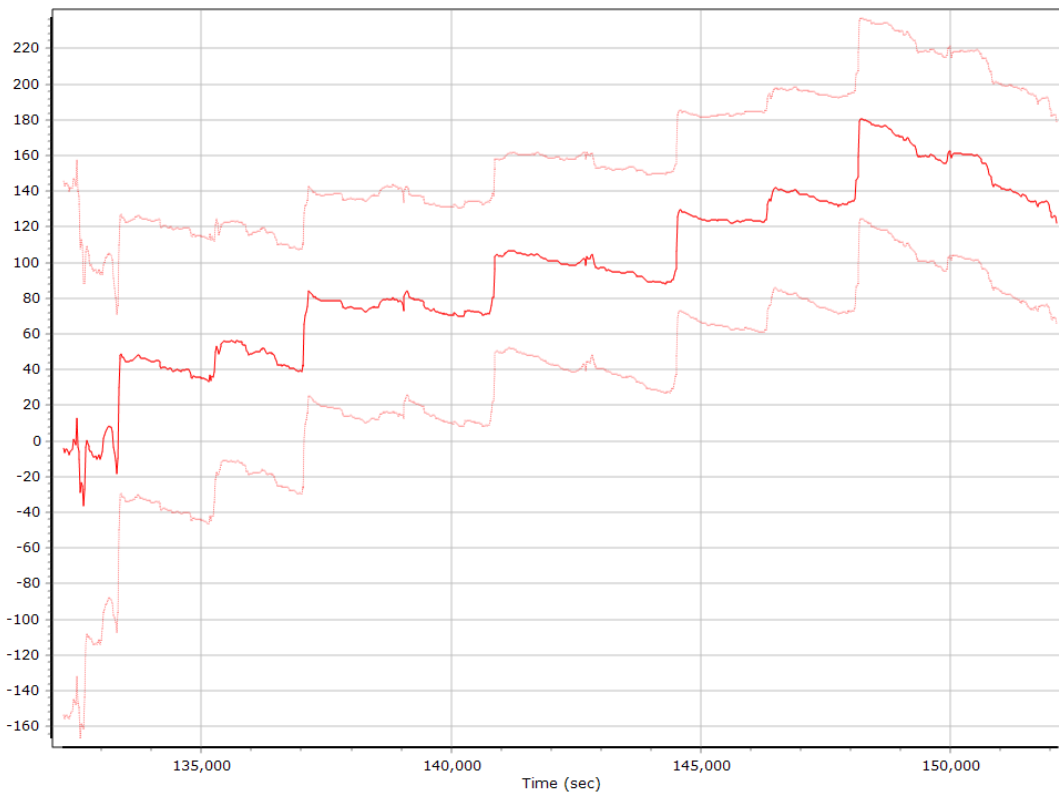
### Z Gyro Bias (deg/h)



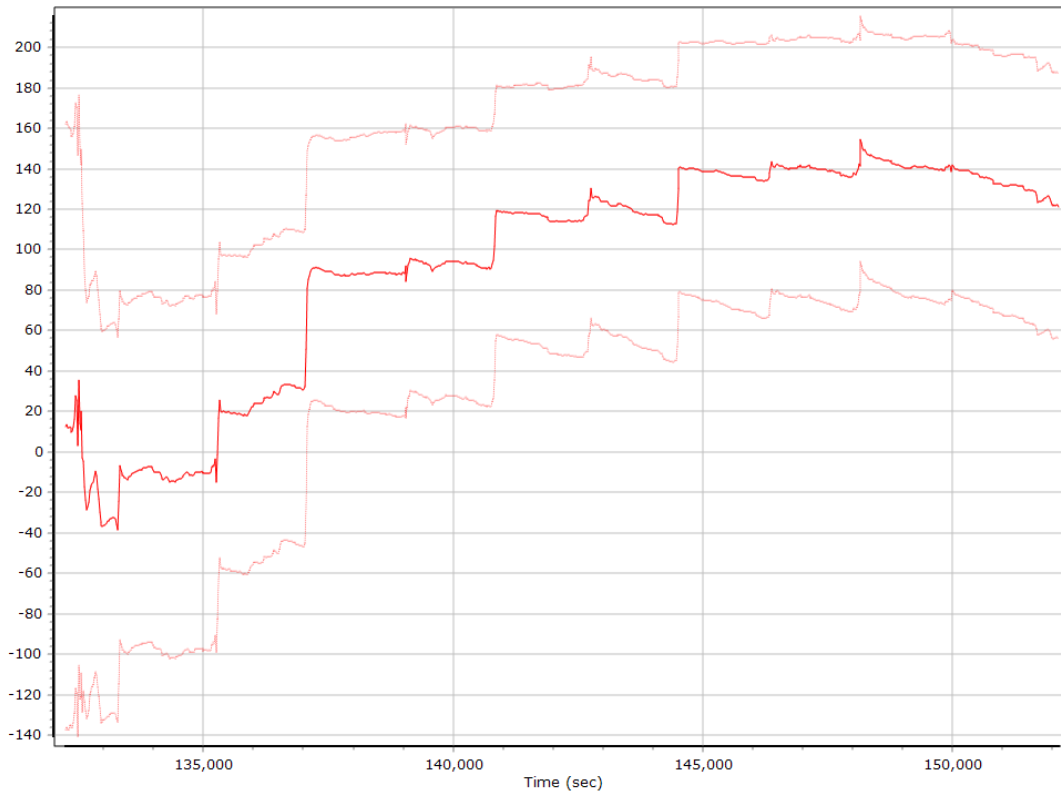
### Gyro Scale Error (ppm)



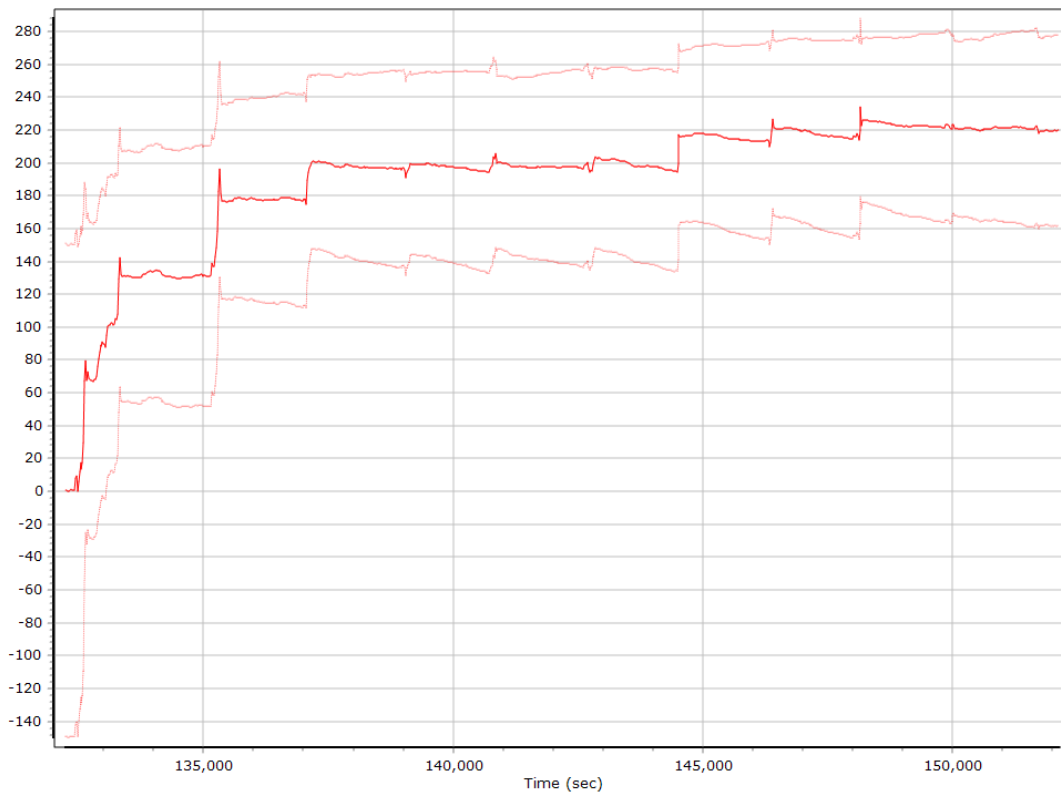
### X Gyro Scale Error (ppm)



### Y Gyro Scale Error (ppm)

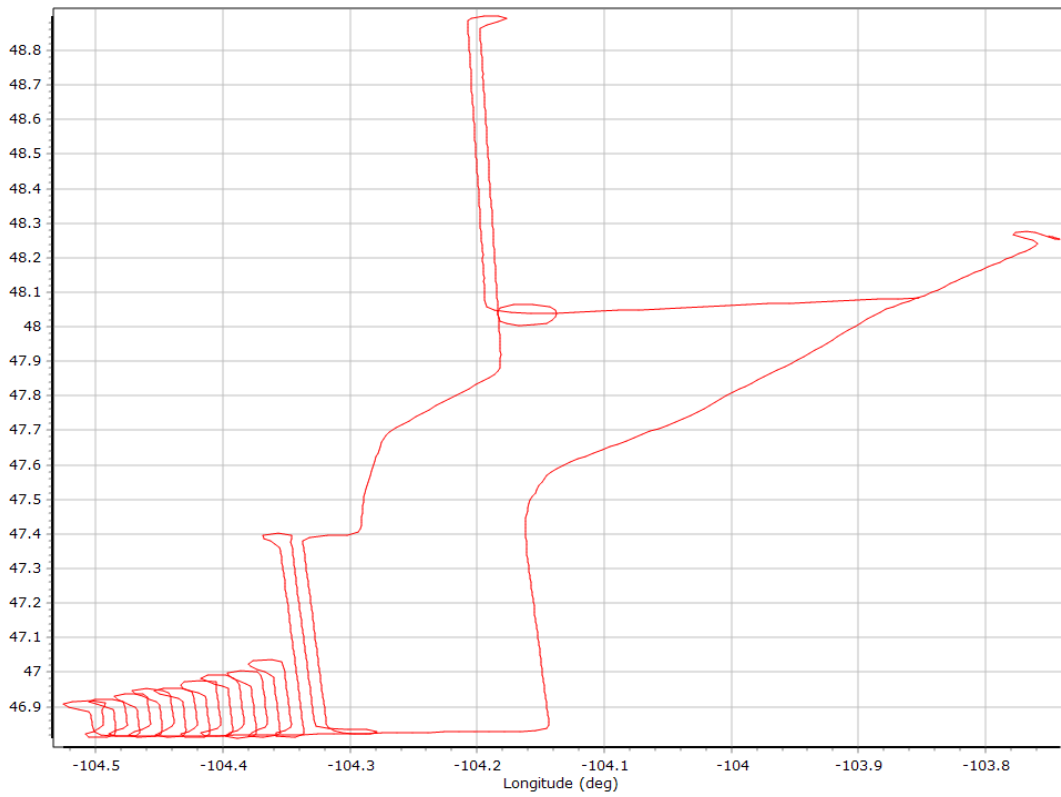


### Z Gyro Scale Error (ppm)

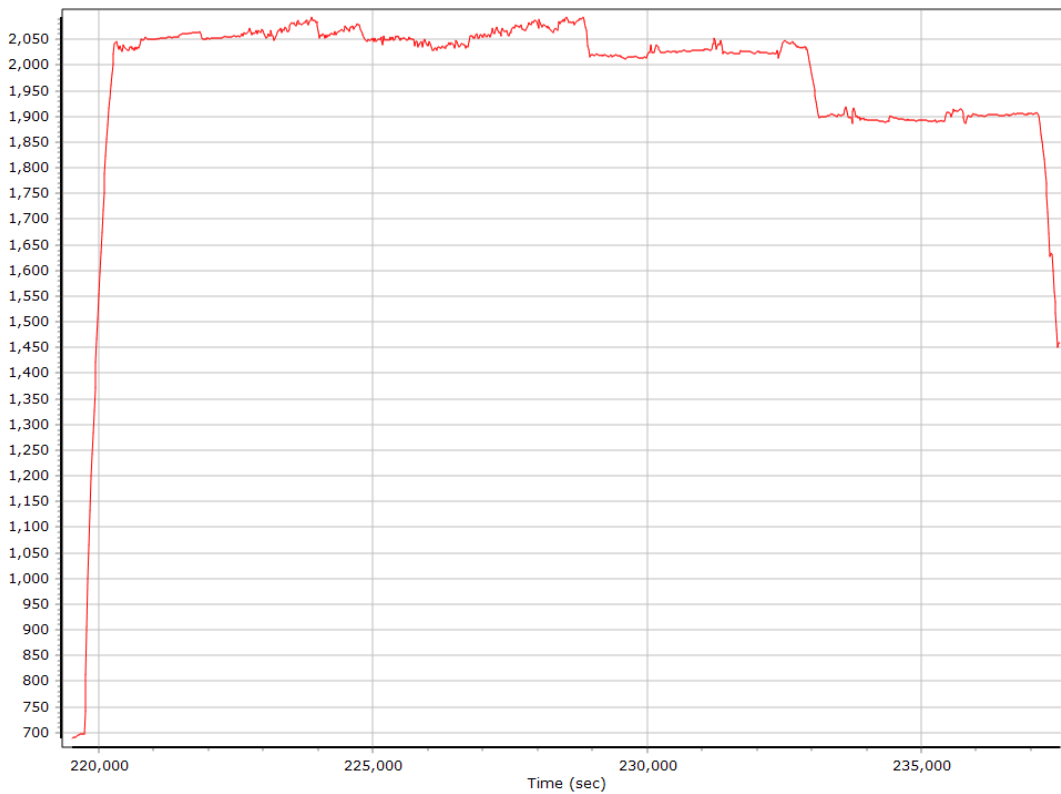


## Smoothed Trajectory Information

### Top View



### Altitude

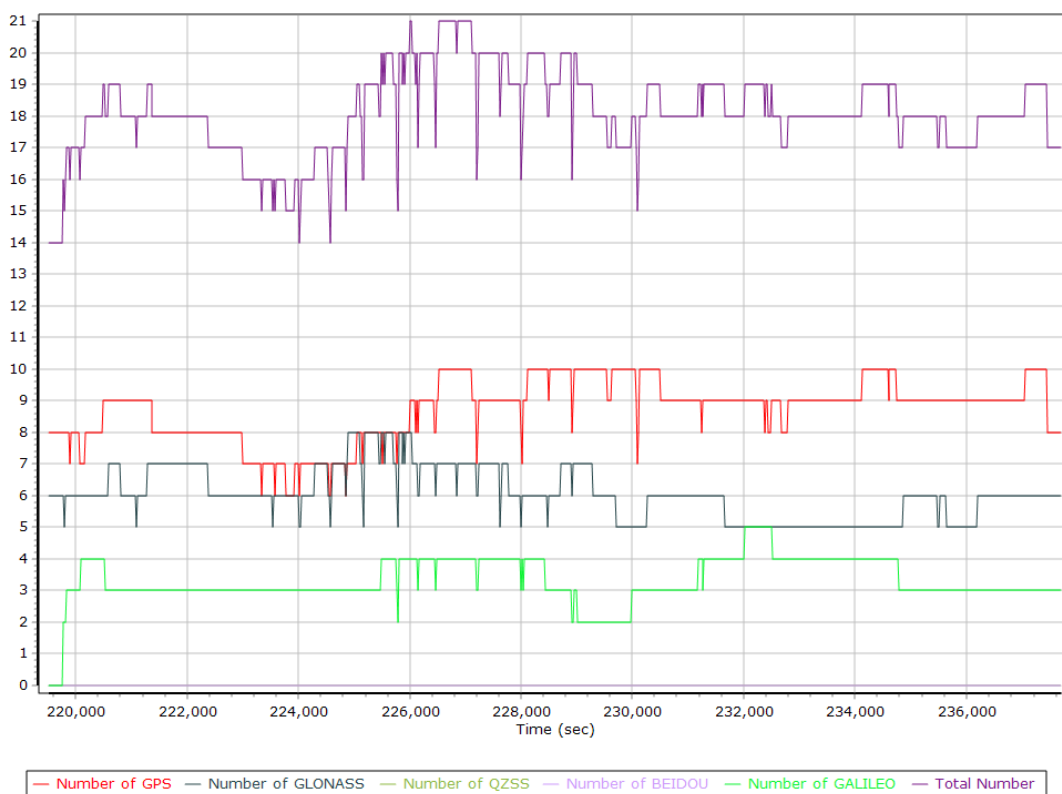


## GNSS QC

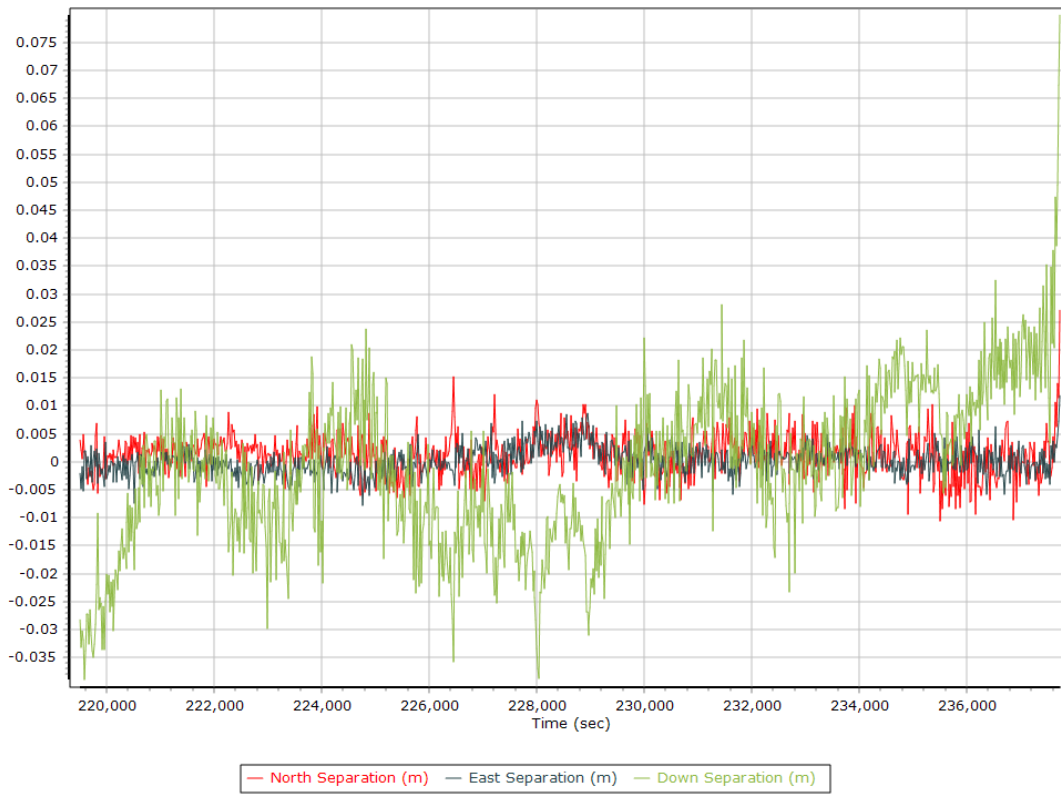
### GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	6	10	9
Number of GLONASS SV	0	8	6
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	0	0
Number of GALILEO SV	0	5	3
Total number of SV	8	21	18
PDOP	1.11	3.55	1.36
QC Solution Gaps	1.00	1.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	18483.00	0.00	6.00
Percentage	99.97	0.00	0.03

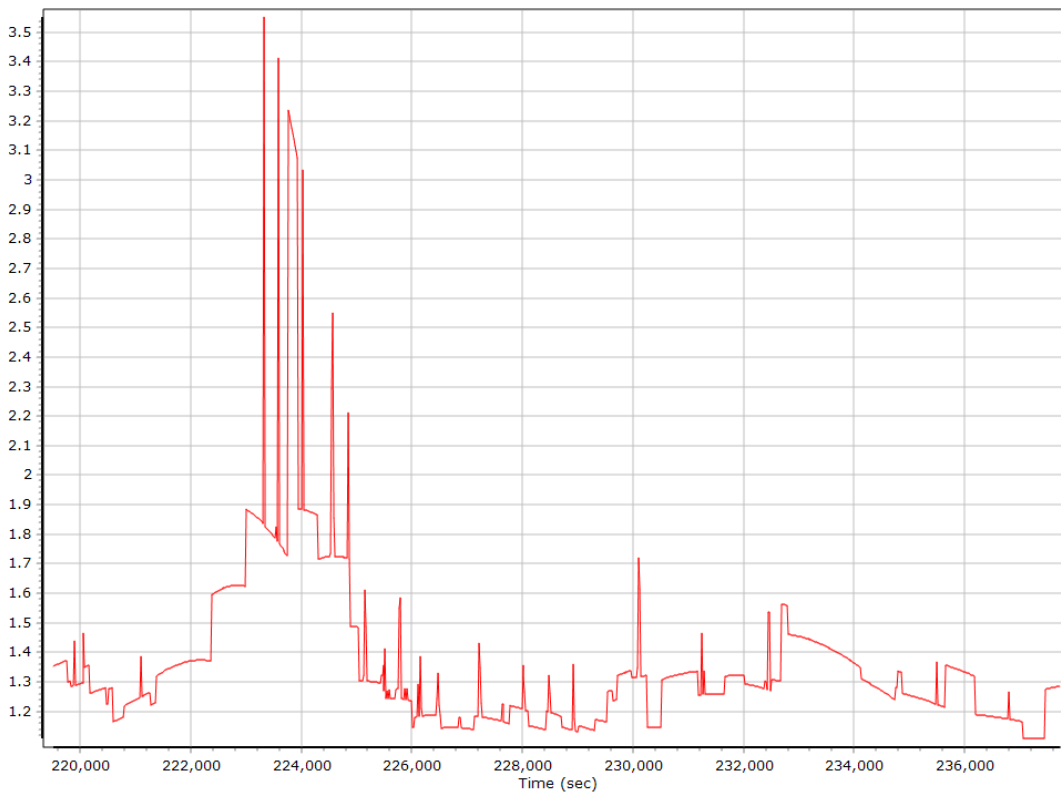
### Num SVs in solution



## Forward/Reverse Separation



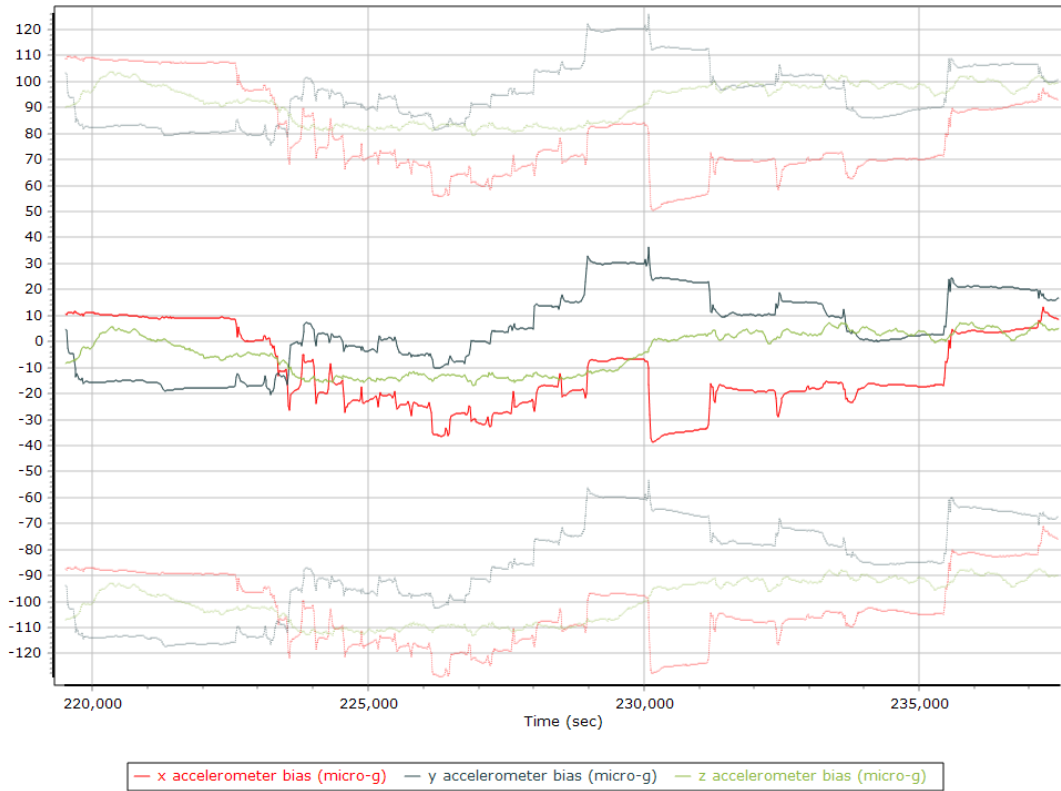
## PDOP



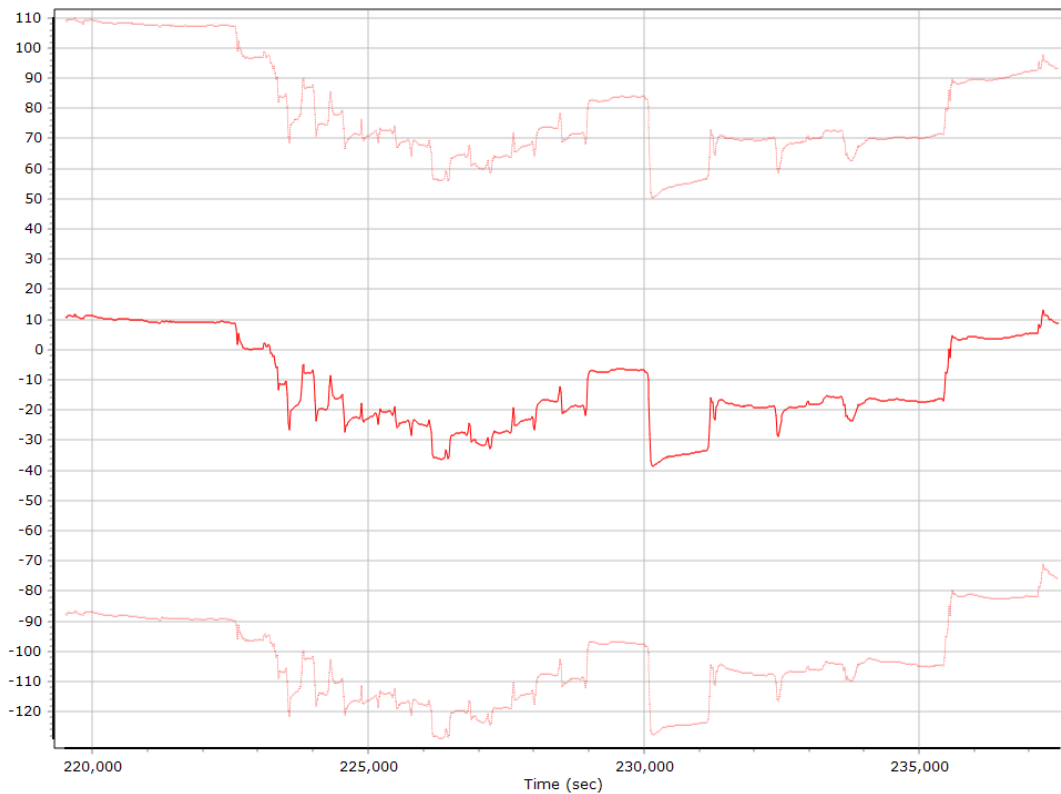
## IN-Fusion QC

### Forward Processed Estimated Errors, Reference Frame

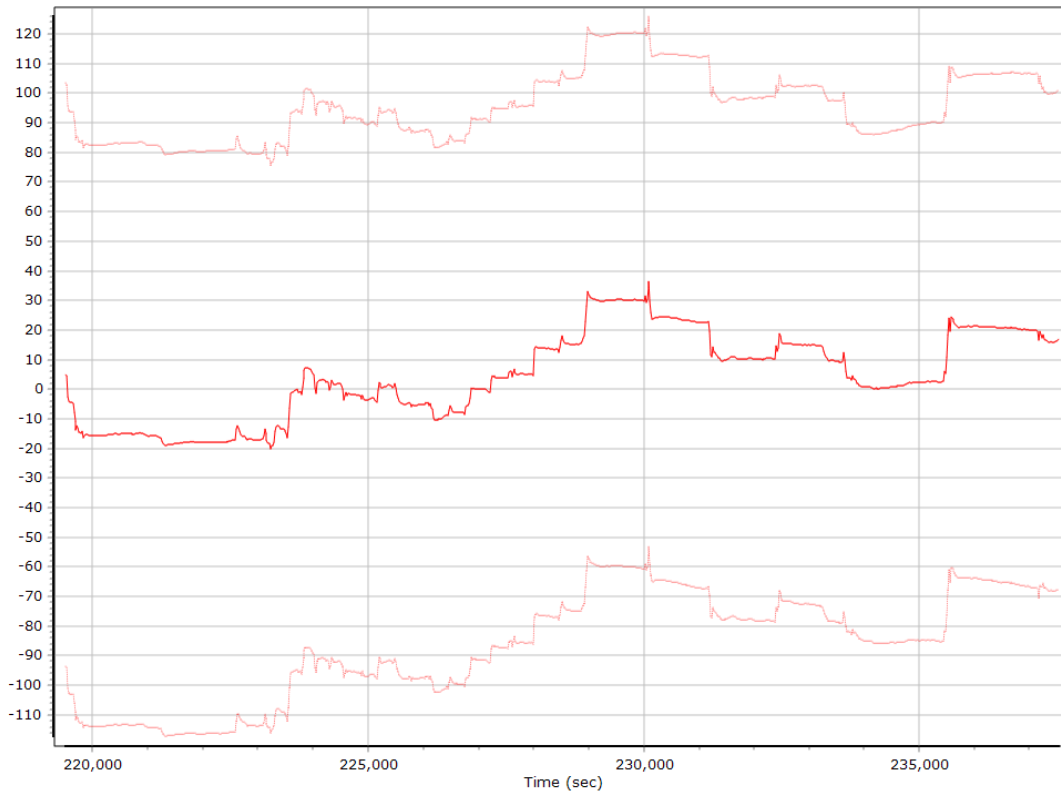
#### Accelerometer Bias (micro-g)



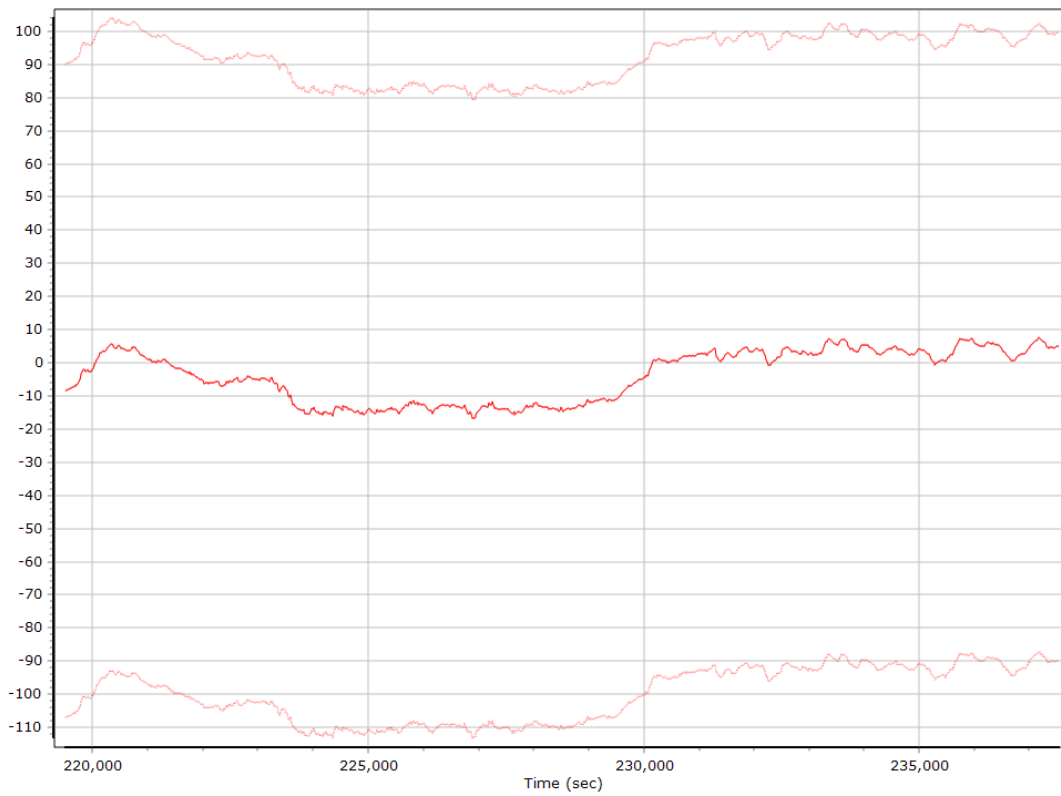
#### X Accelerometer Bias (micro-g)



### Y Accelerometer Bias (micro-g)

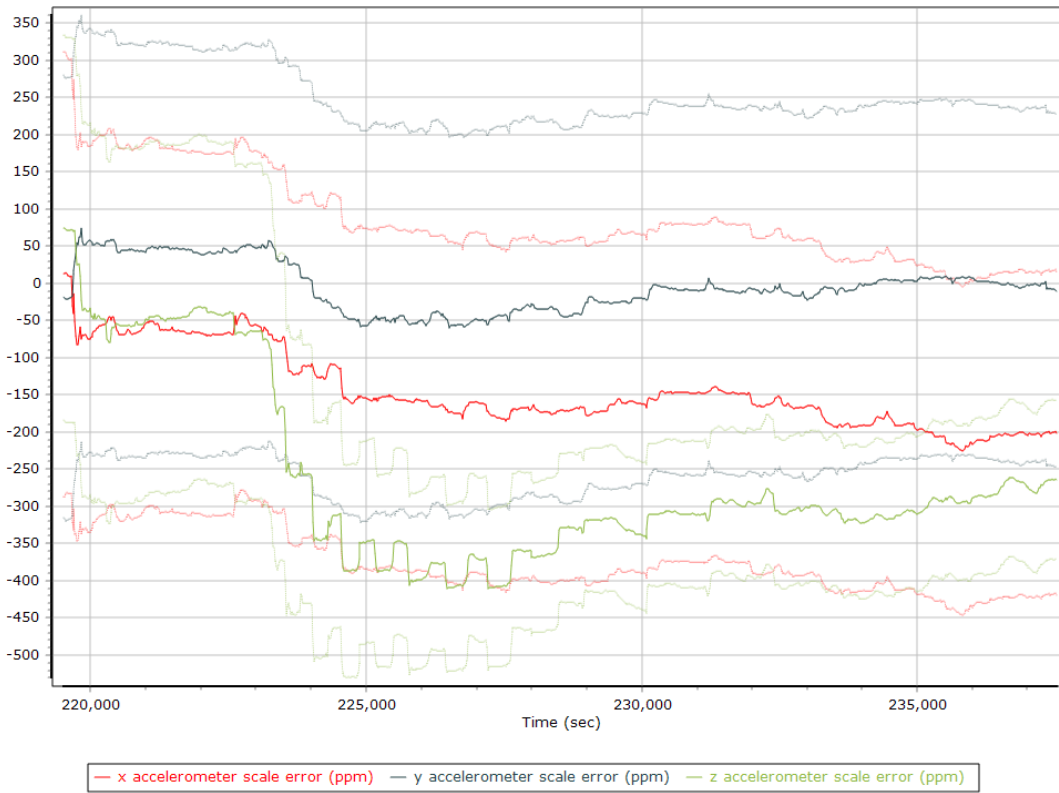


### Z Accelerometer Bias (micro-g)

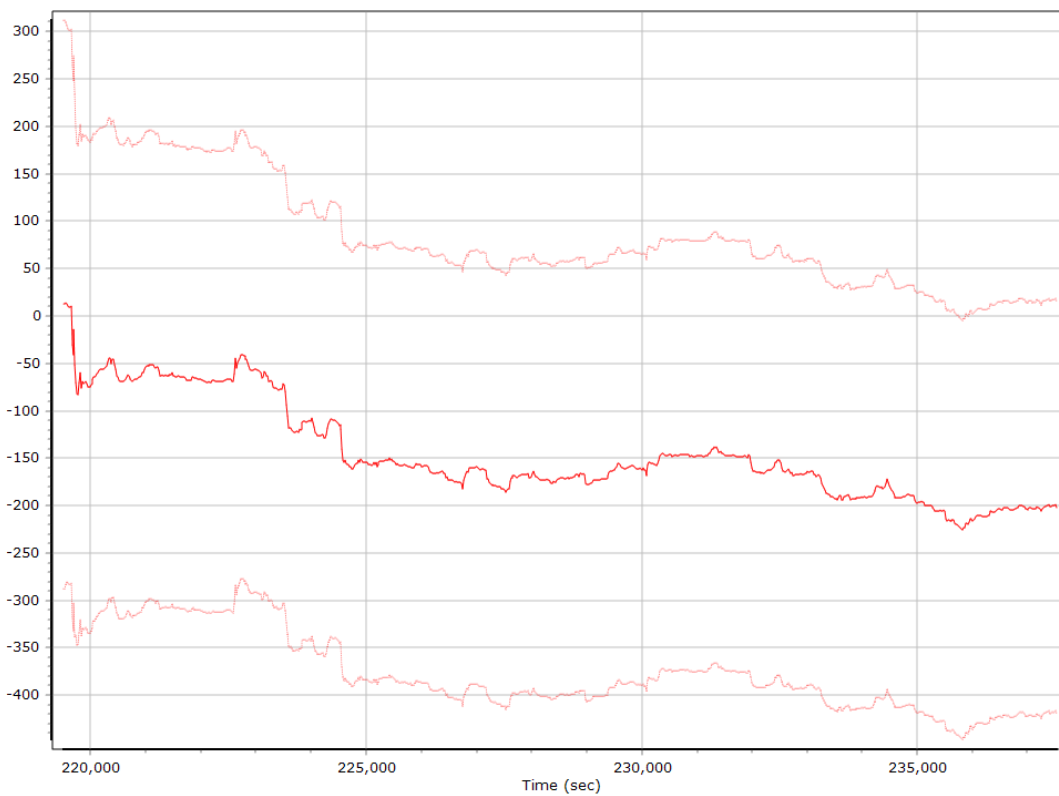




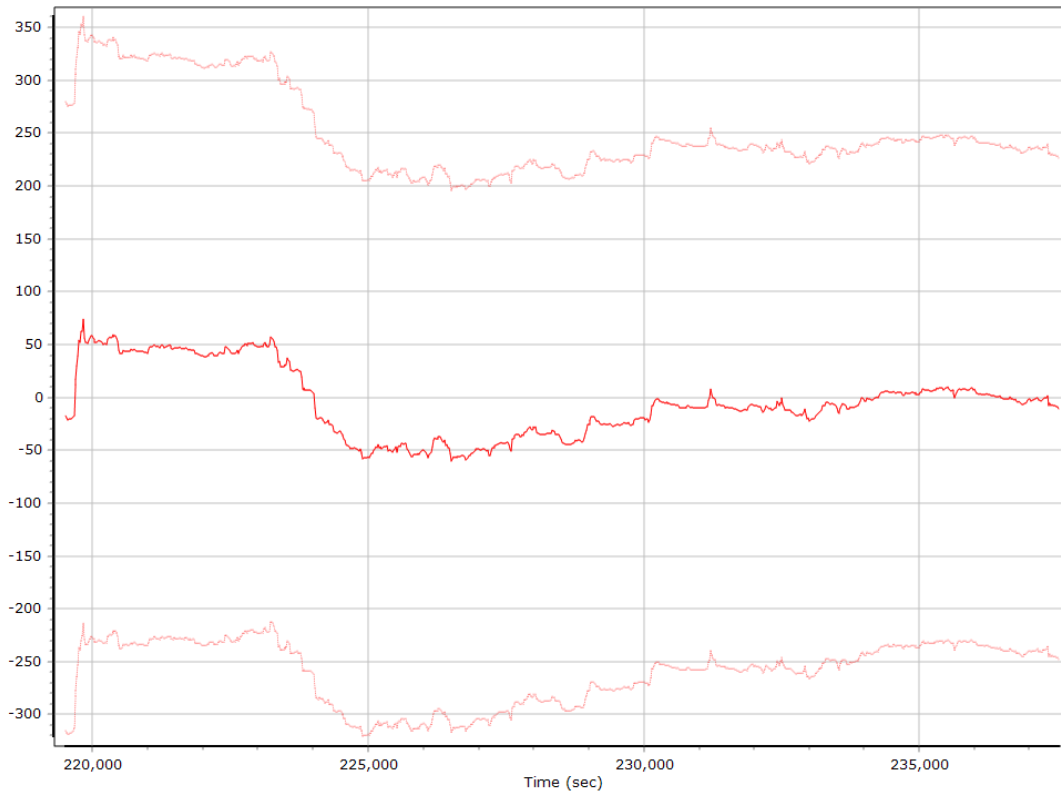
### Accelerometer Scale Error (ppm)



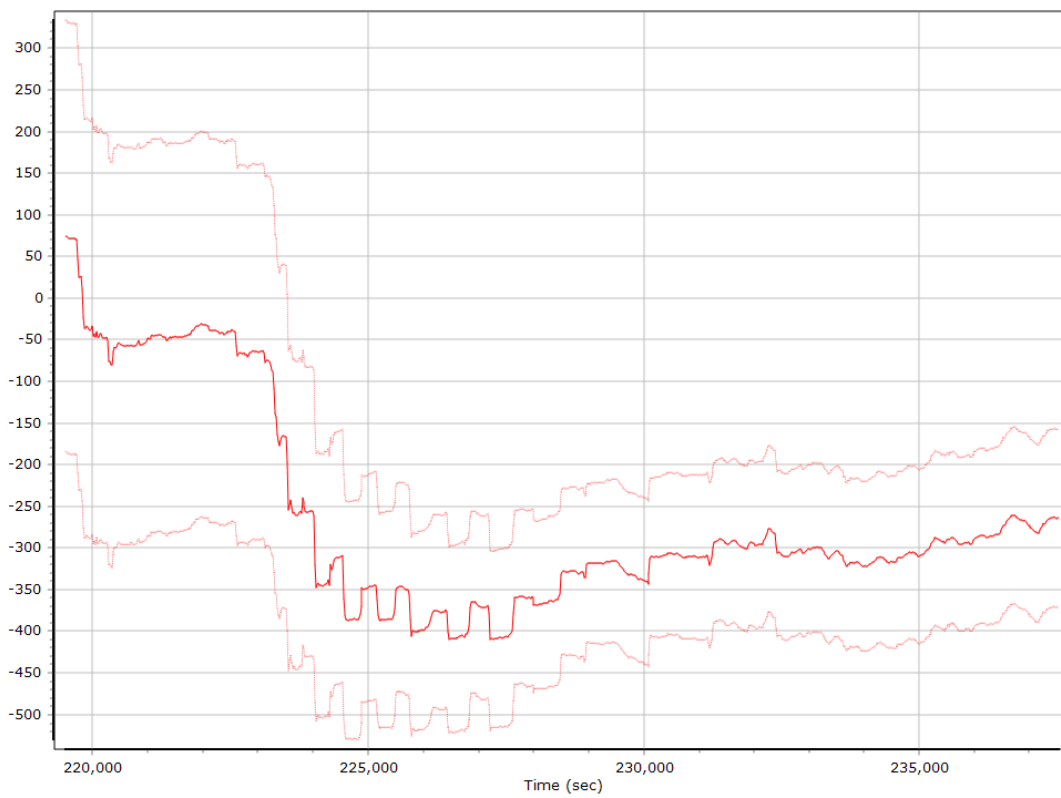
### X Accelerometer Scale Error (ppm)



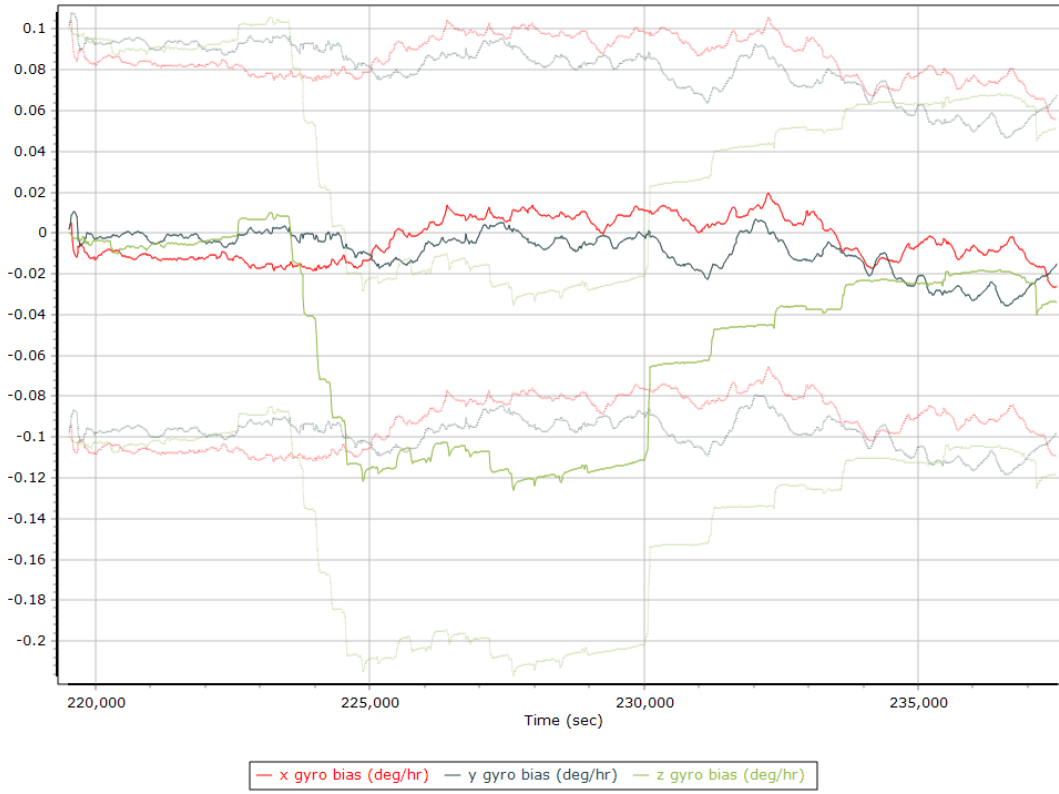
### Y Accelerometer Scale Error (ppm)



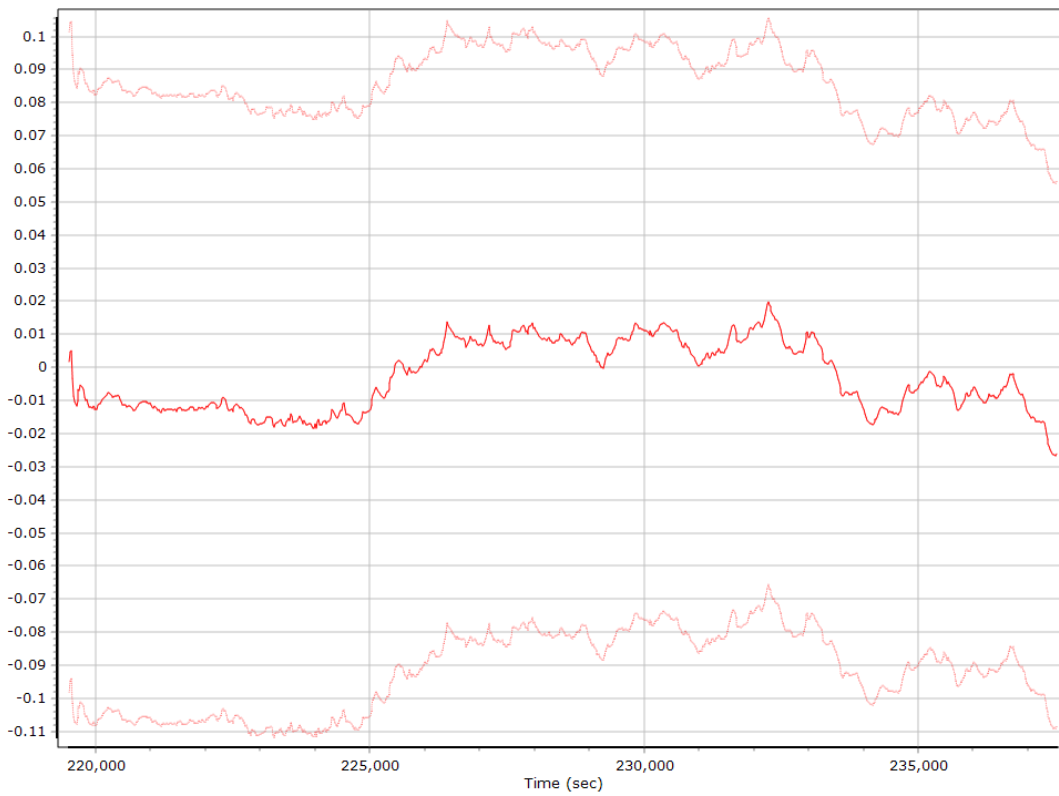
### Z Accelerometer Scale Error (ppm)



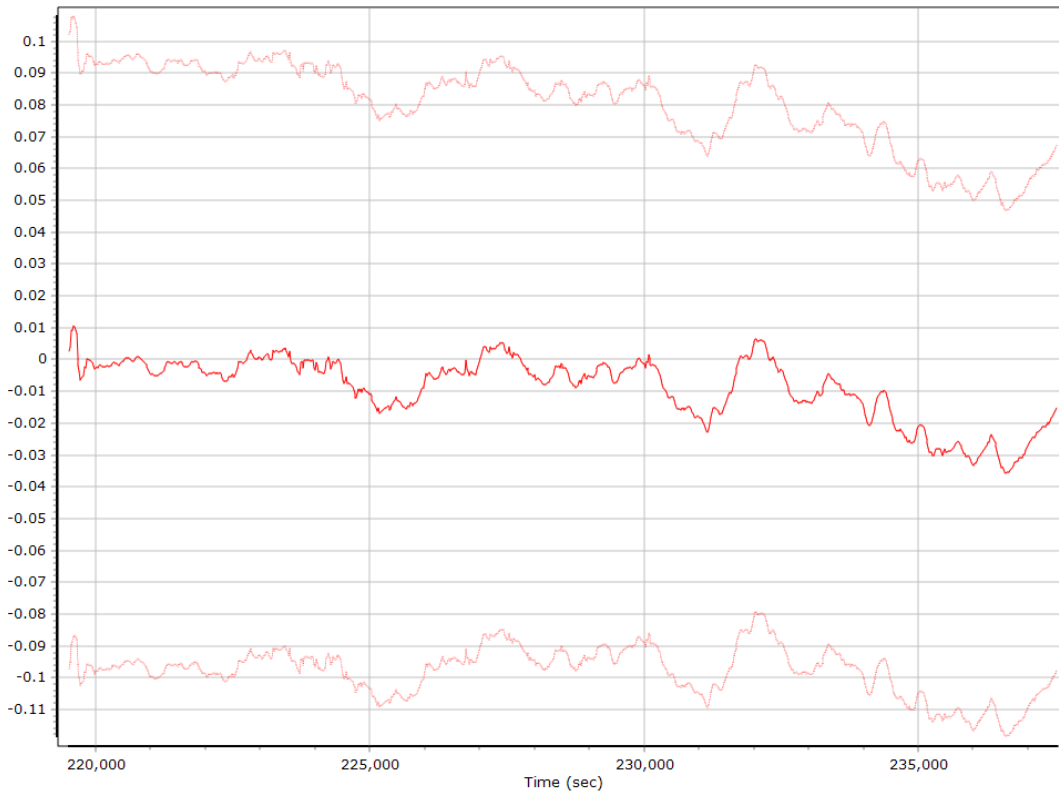
### Gyro Bias (deg/h)



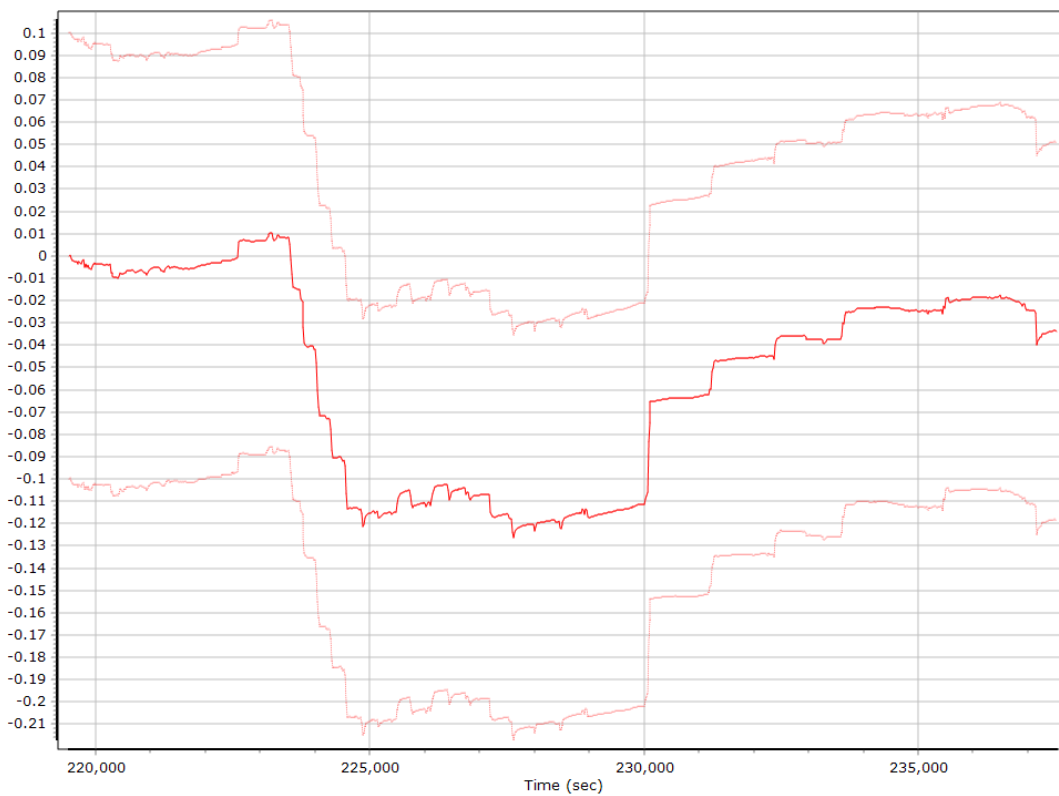
### X Gyro Bias (deg/h)



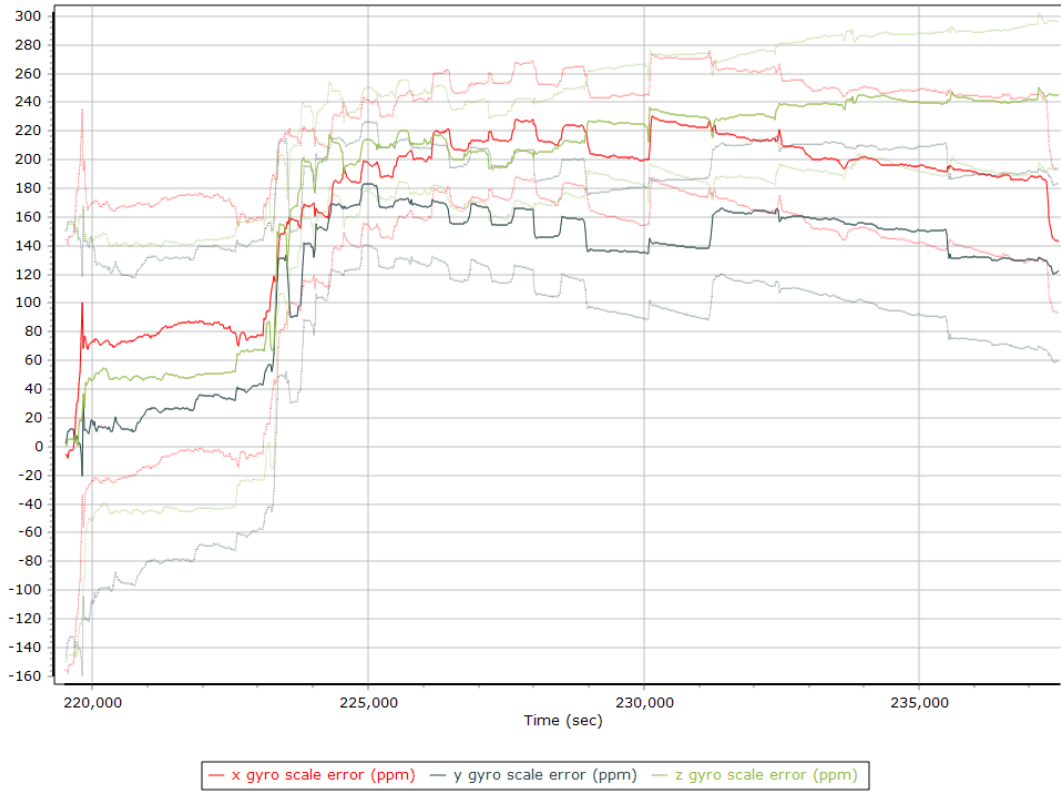
### Y Gyro Bias (deg/h)



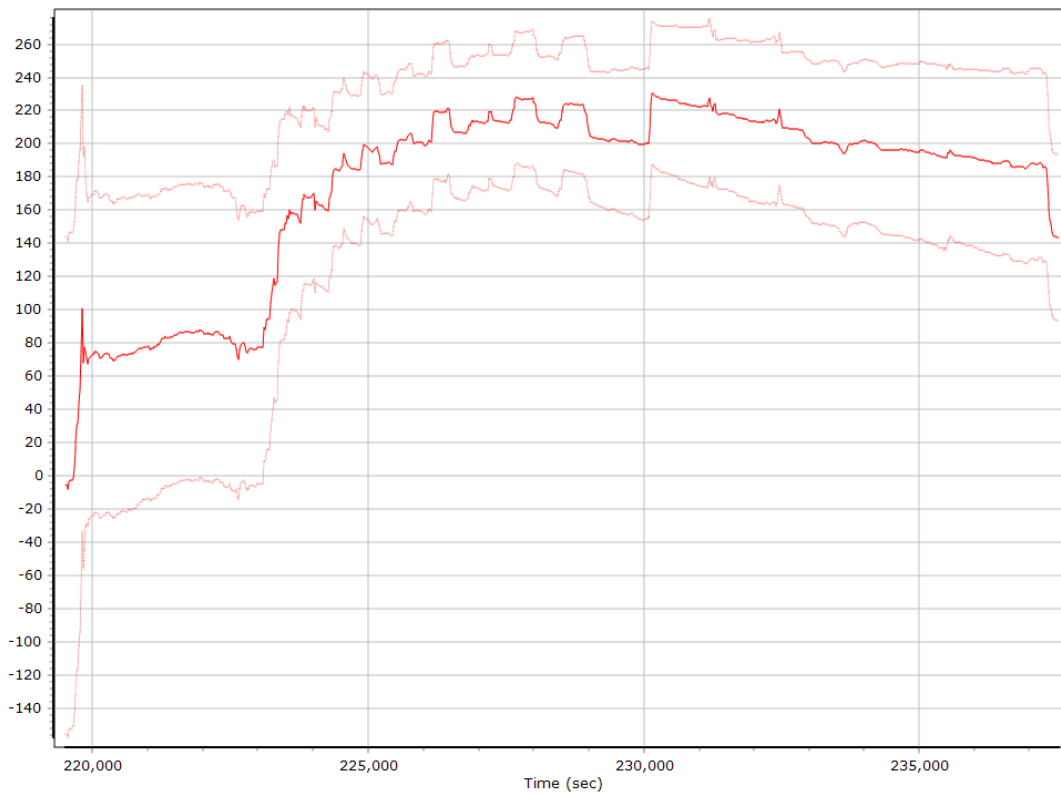
### Z Gyro Bias (deg/h)



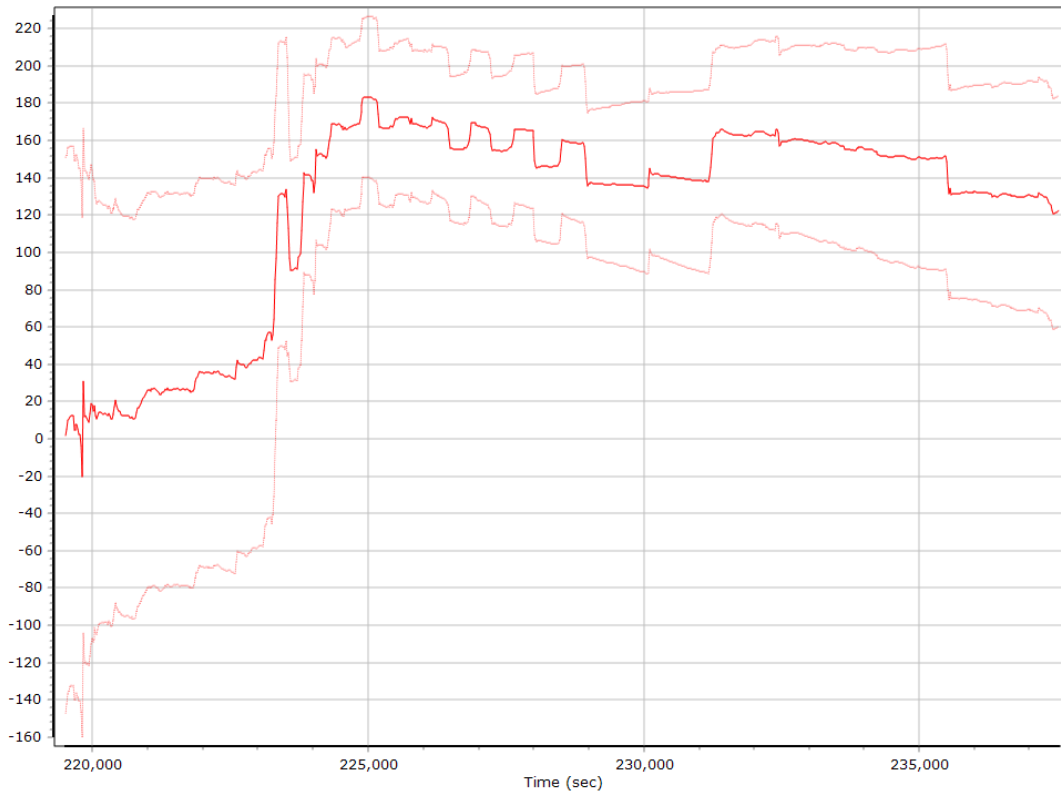
### Gyro Scale Error (ppm)



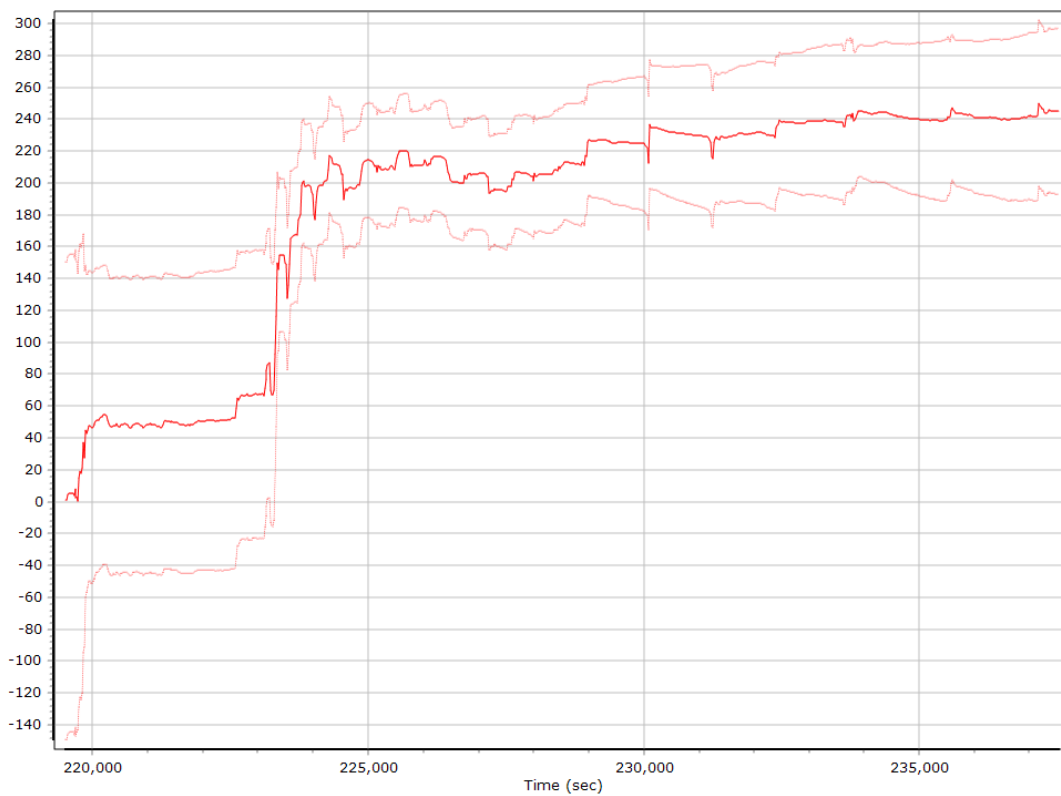
### X Gyro Scale Error (ppm)



### Y Gyro Scale Error (ppm)

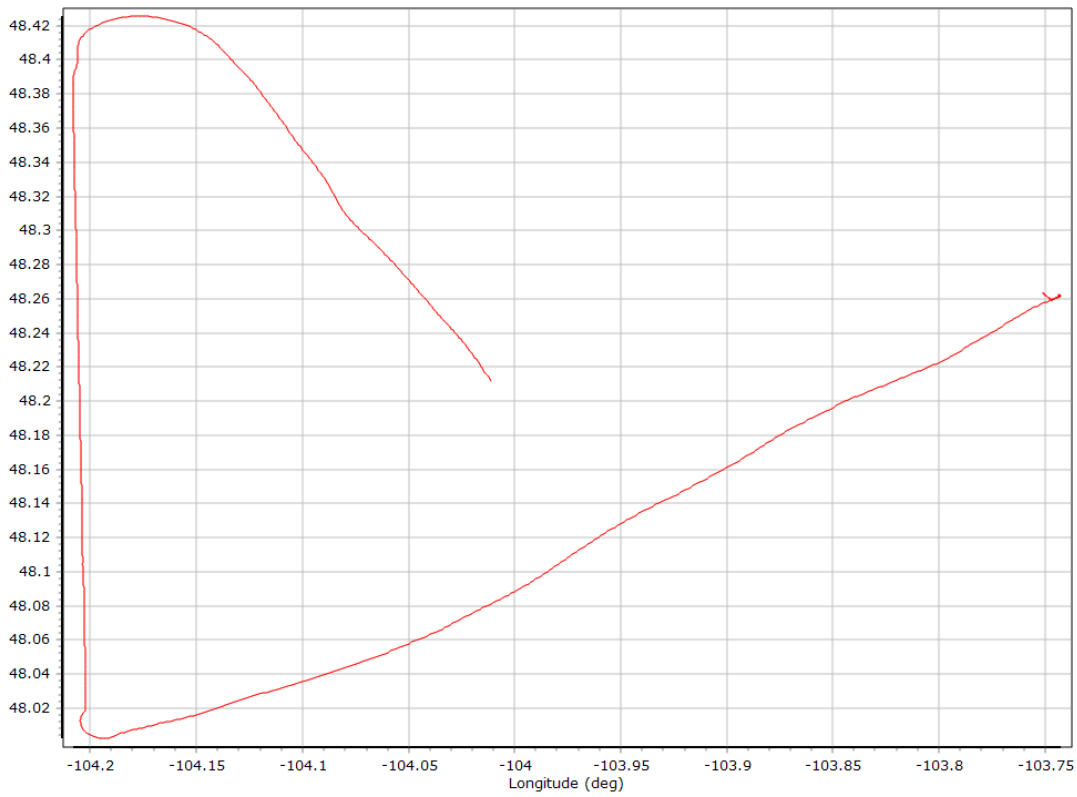


### Z Gyro Scale Error (ppm)

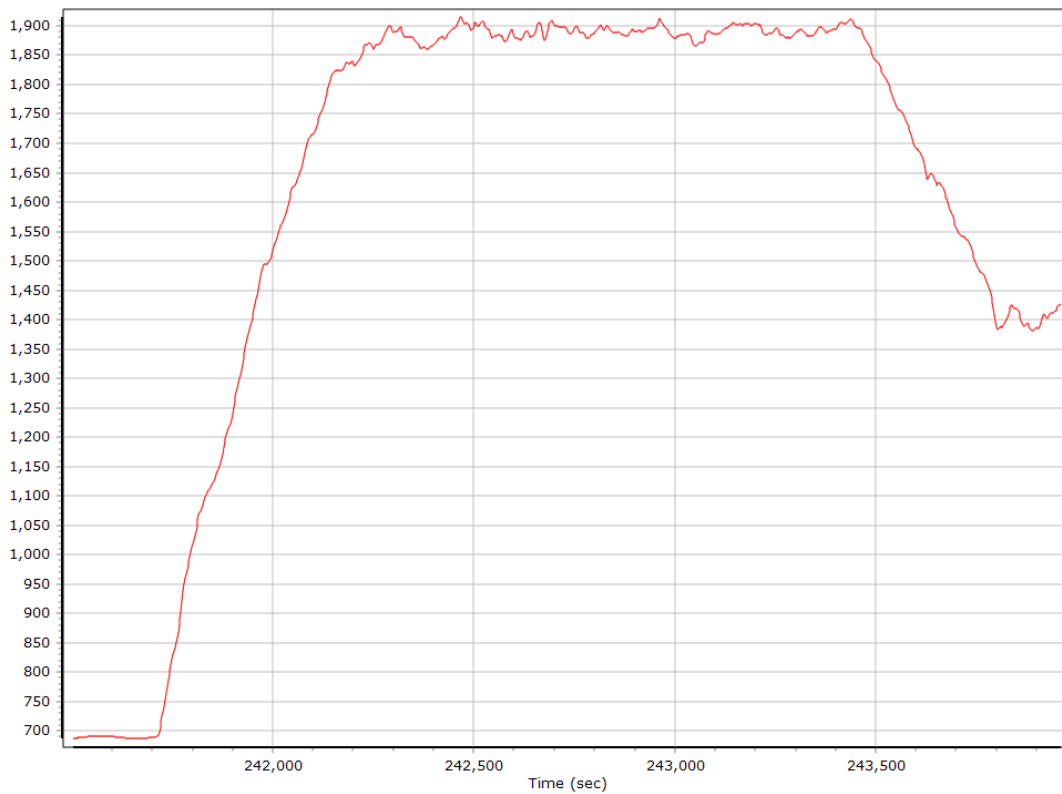


## Smoothed Trajectory Information

### Top View



### Altitude

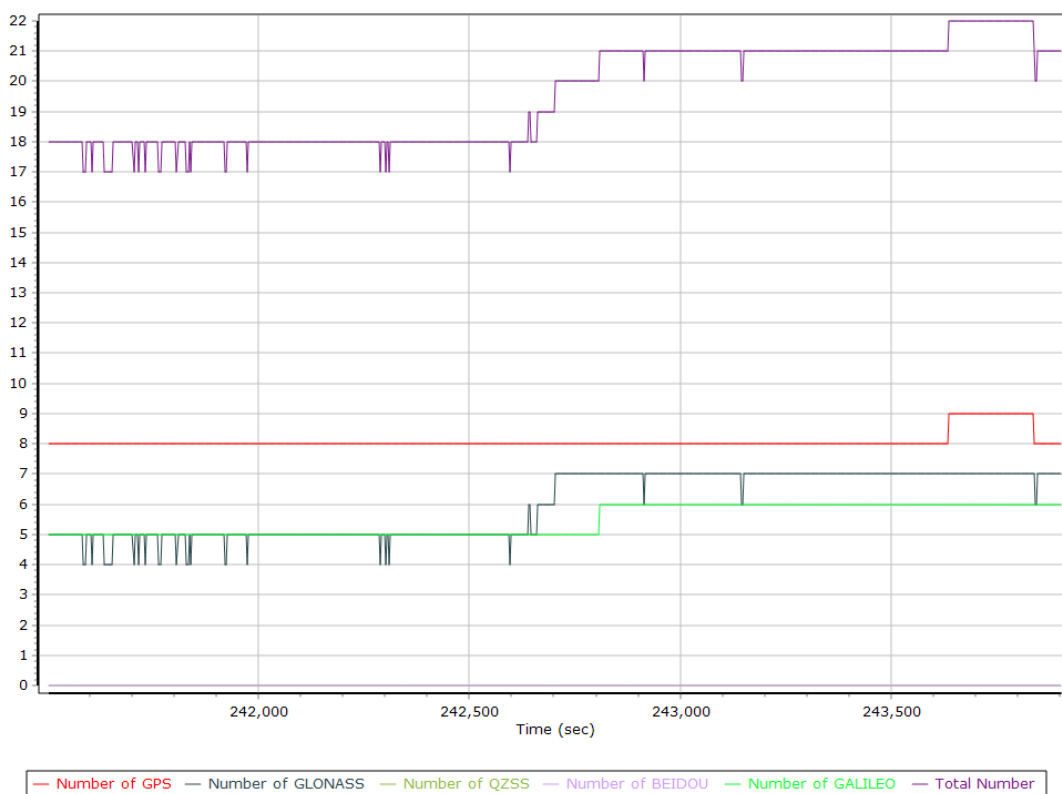


## GNSS QC

### GNSS QC Statistics

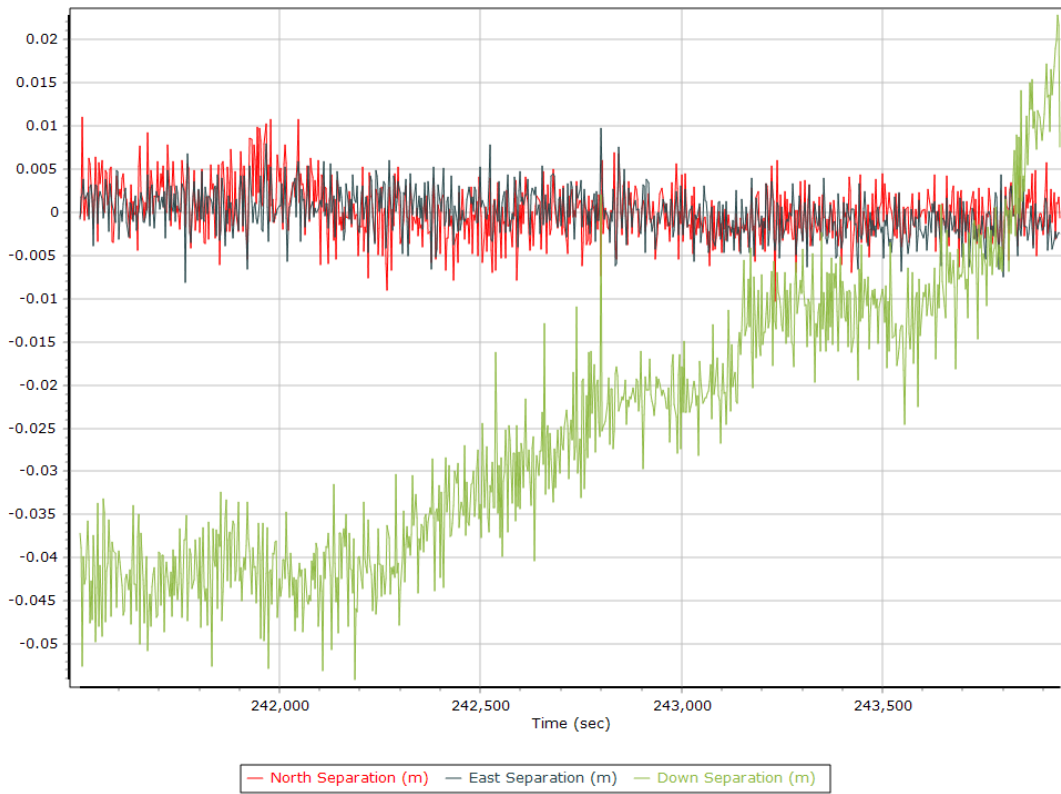
Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	8	9	8
Number of GLONASS SV	0	7	6
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	0	0
Number of GALILEO SV	5	6	5
Total number of SV	13	22	19
PDOP	1.06	1.58	1.26
QC Solution Gaps	1.00	1.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	2896.00	0.00	2.00
Percentage	99.93	0.00	0.07

### Num SVs in solution

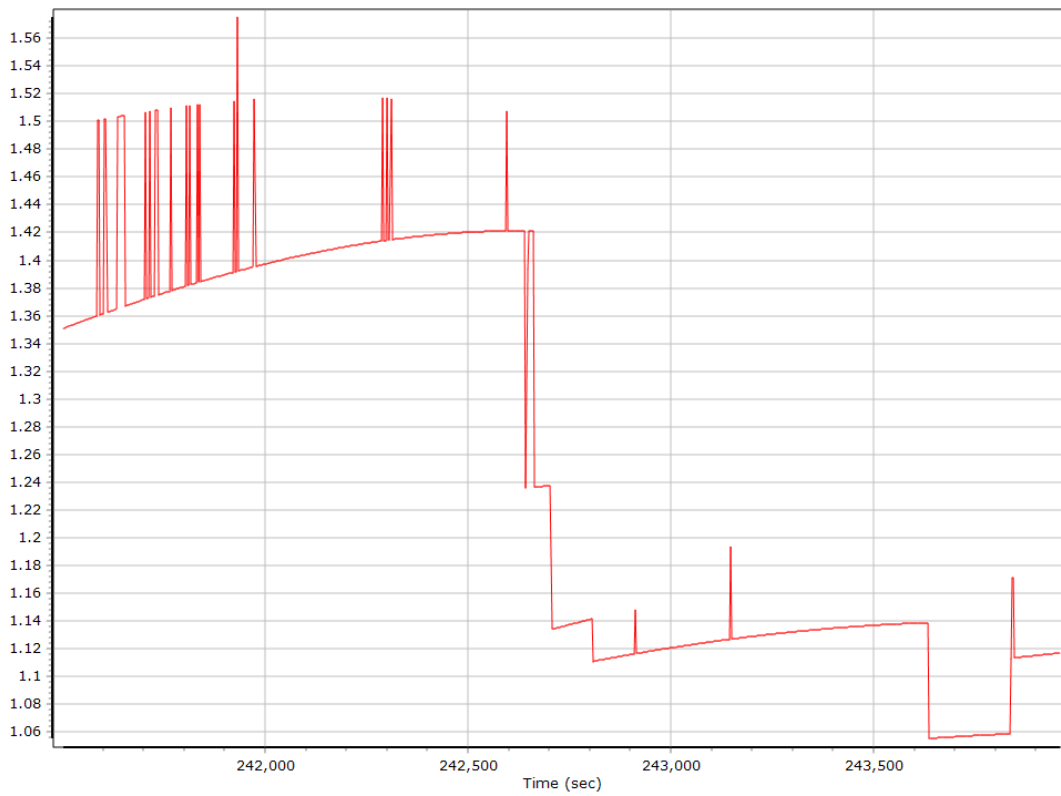




## Forward/Reverse Separation



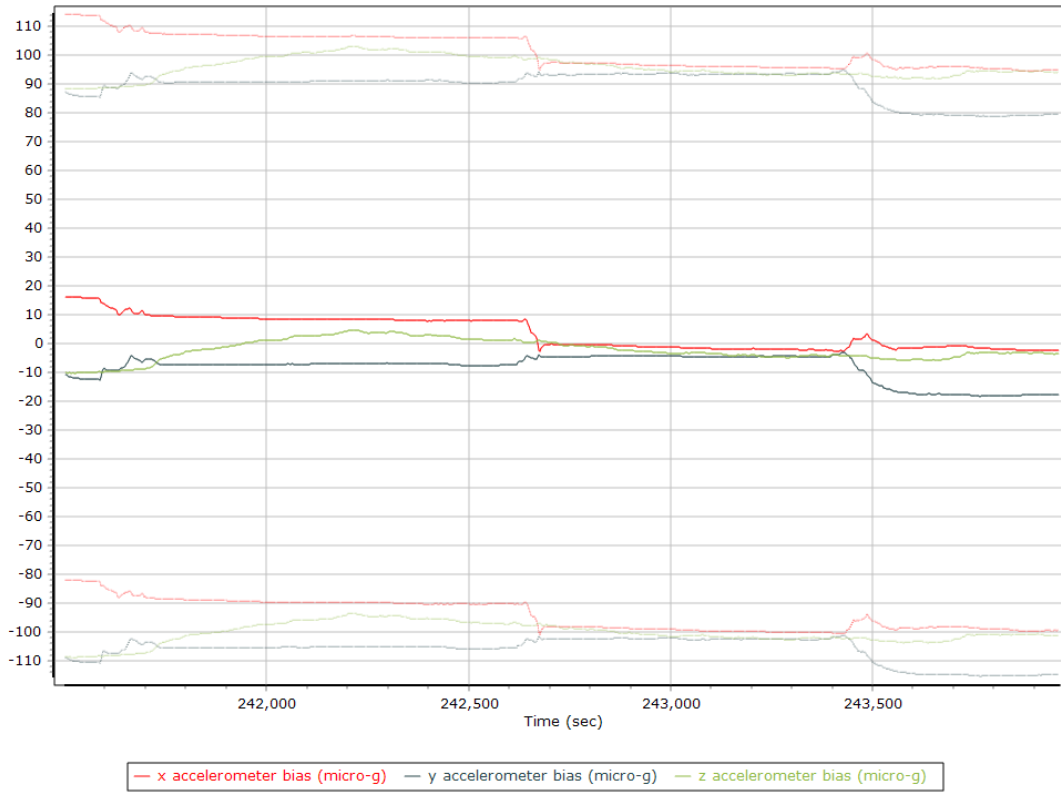
## PDOP



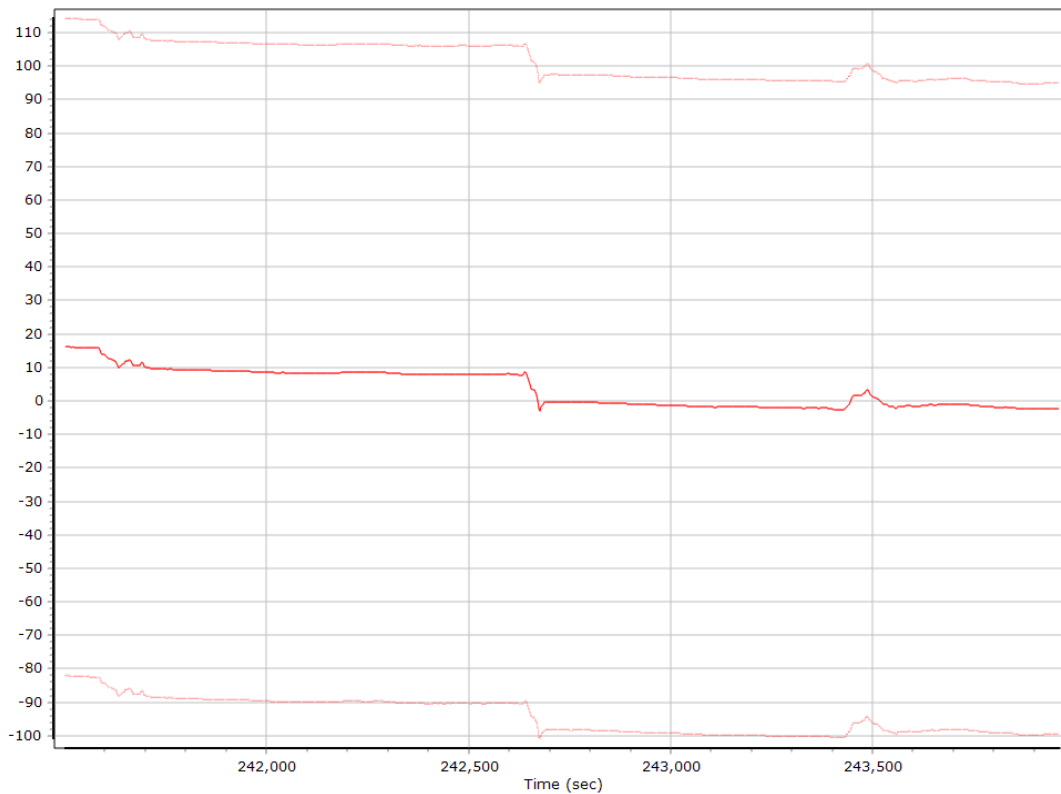
## IN-Fusion QC

### Forward Processed Estimated Errors, Reference Frame

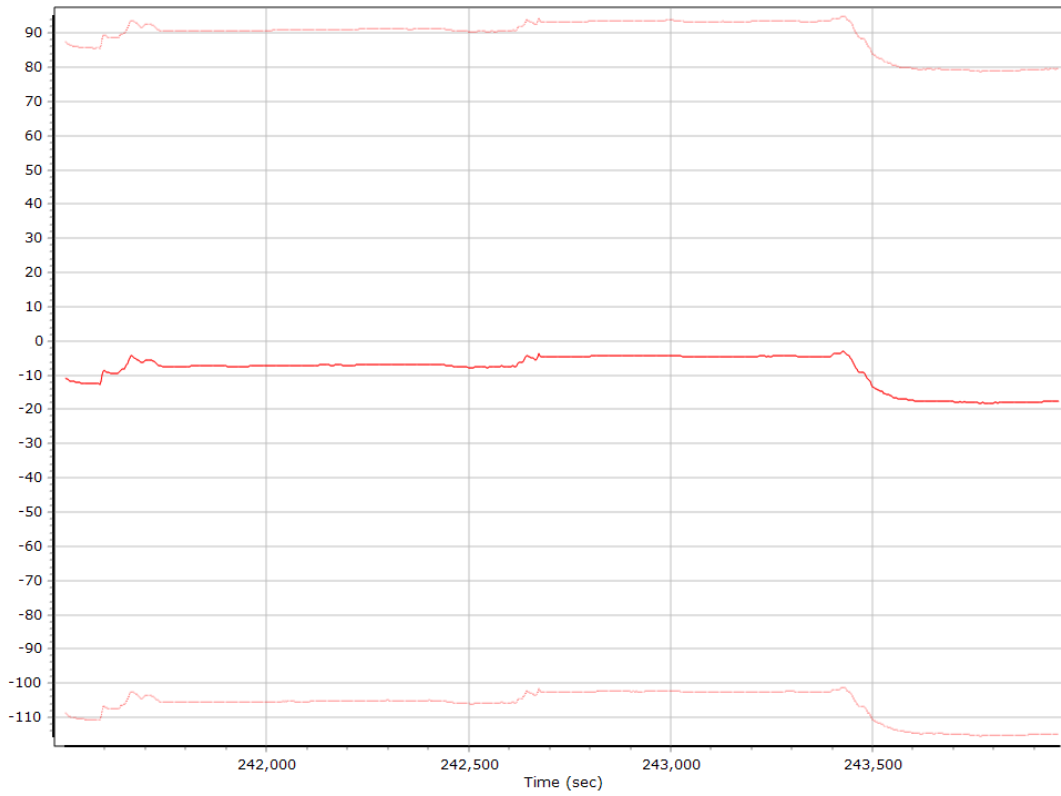
#### Accelerometer Bias (micro-g)



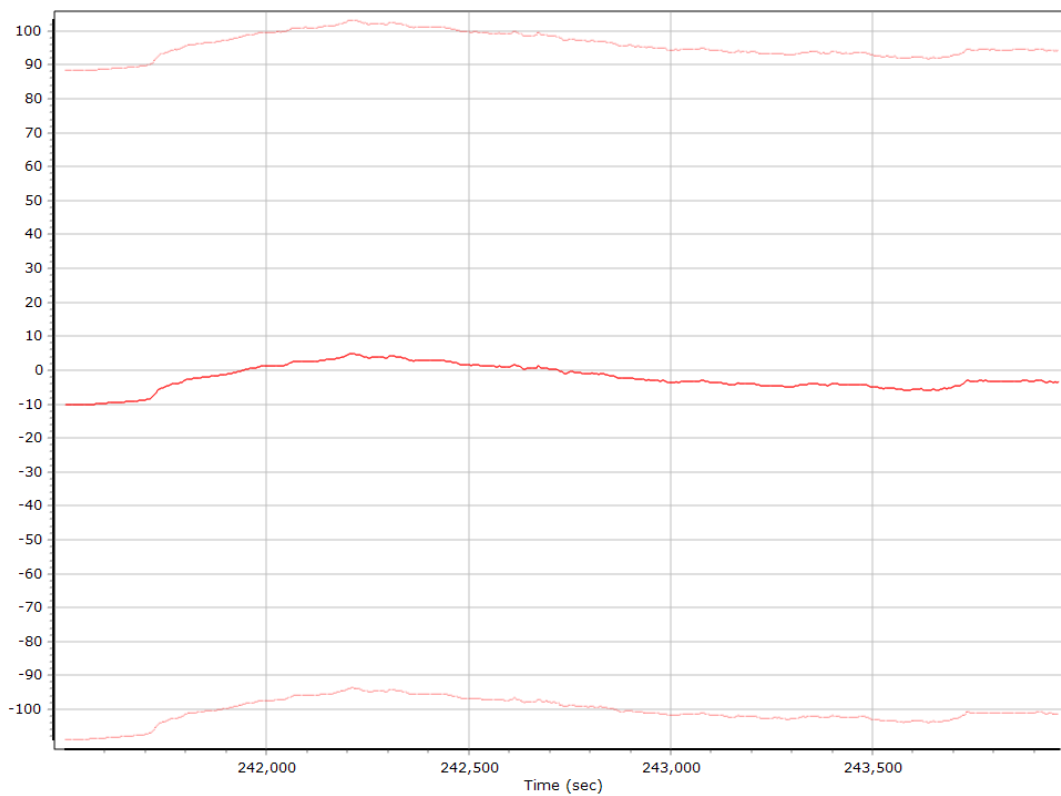
#### X Accelerometer Bias (micro-g)



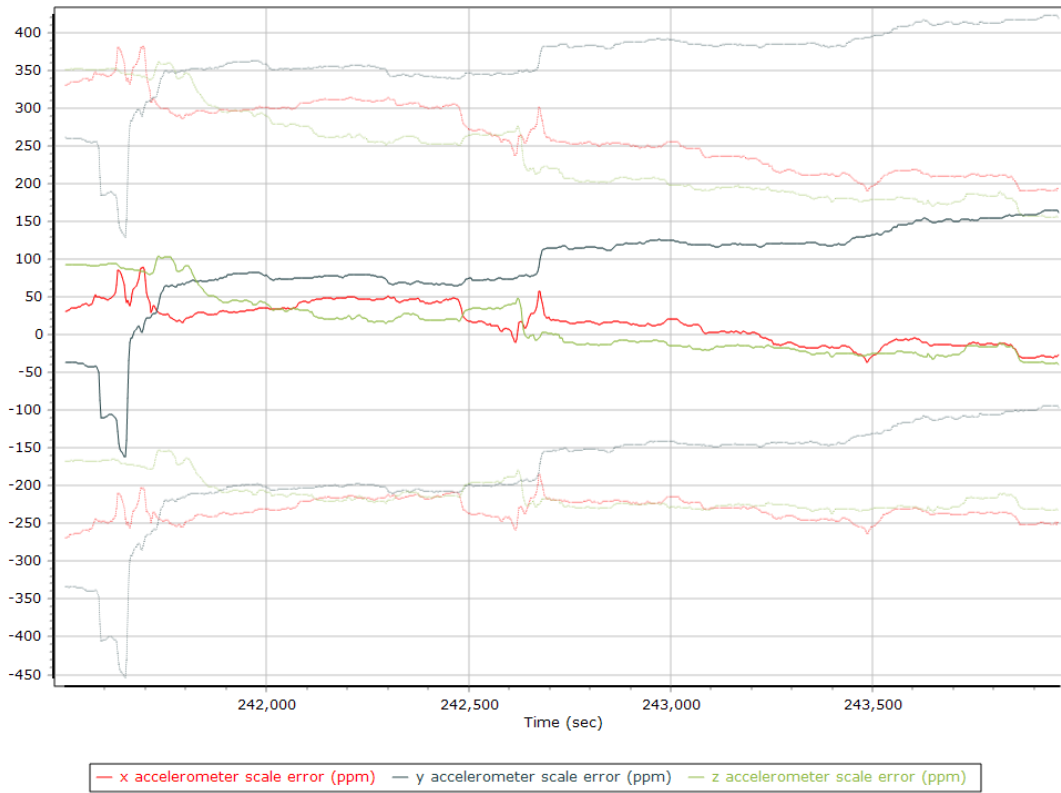
### Y Accelerometer Bias (micro-g)



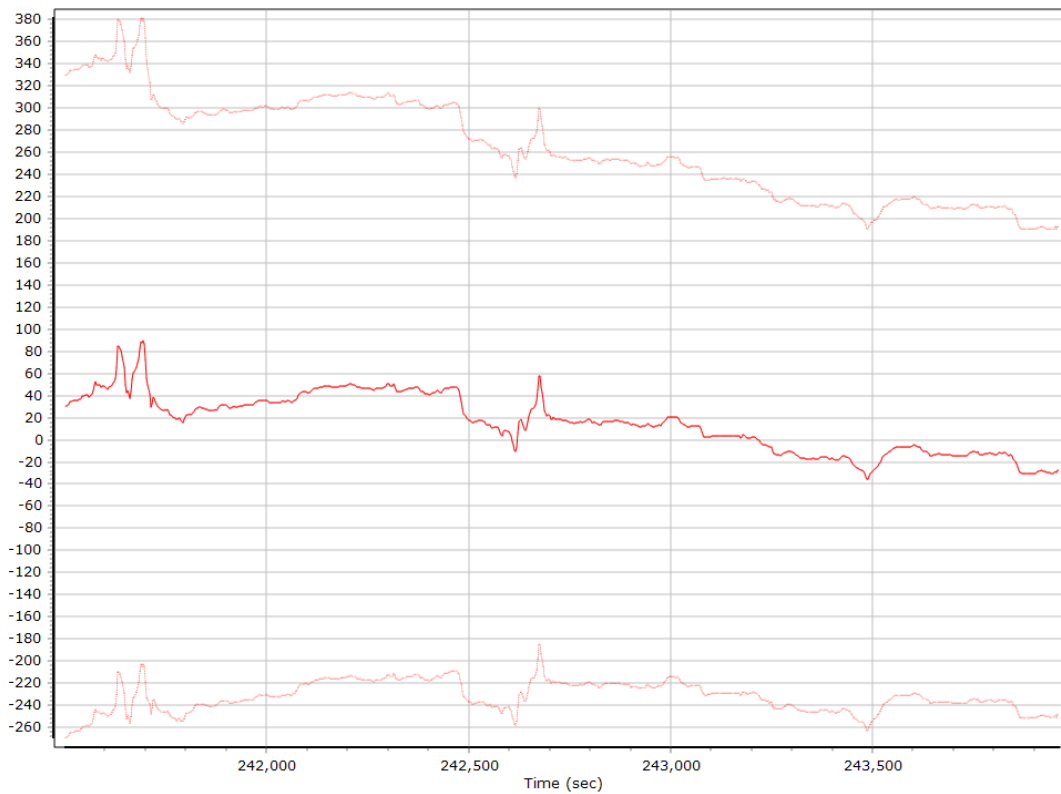
### Z Accelerometer Bias (micro-g)



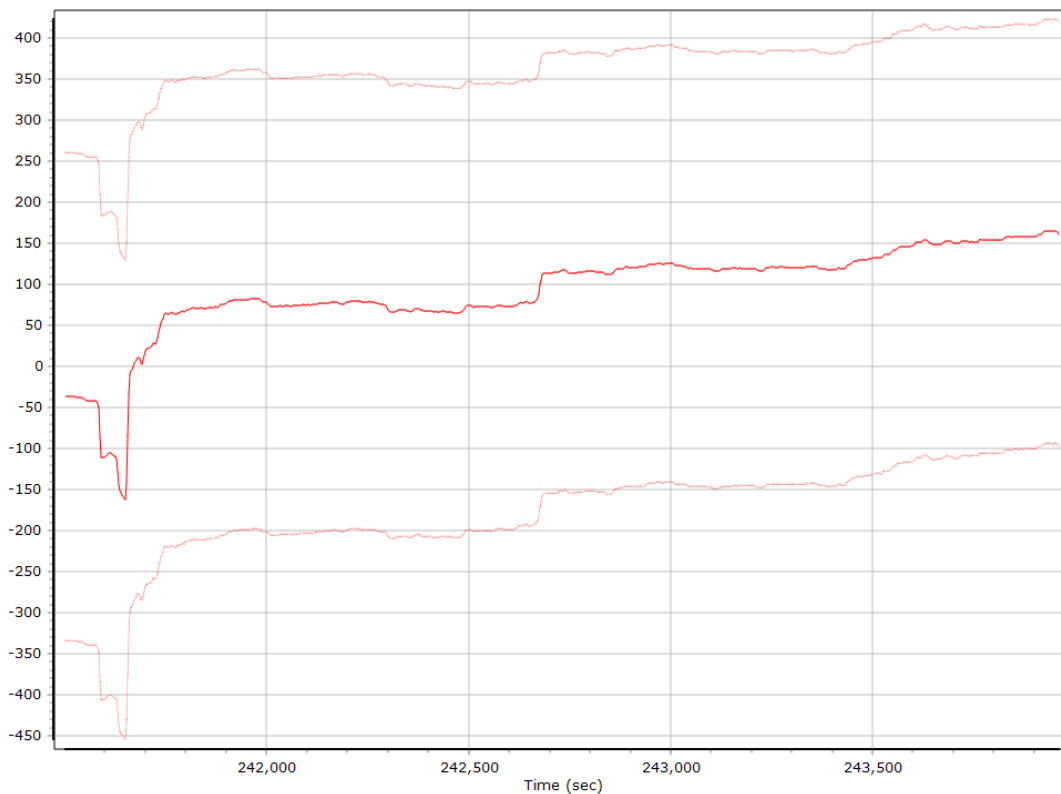
### Accelerometer Scale Error (ppm)



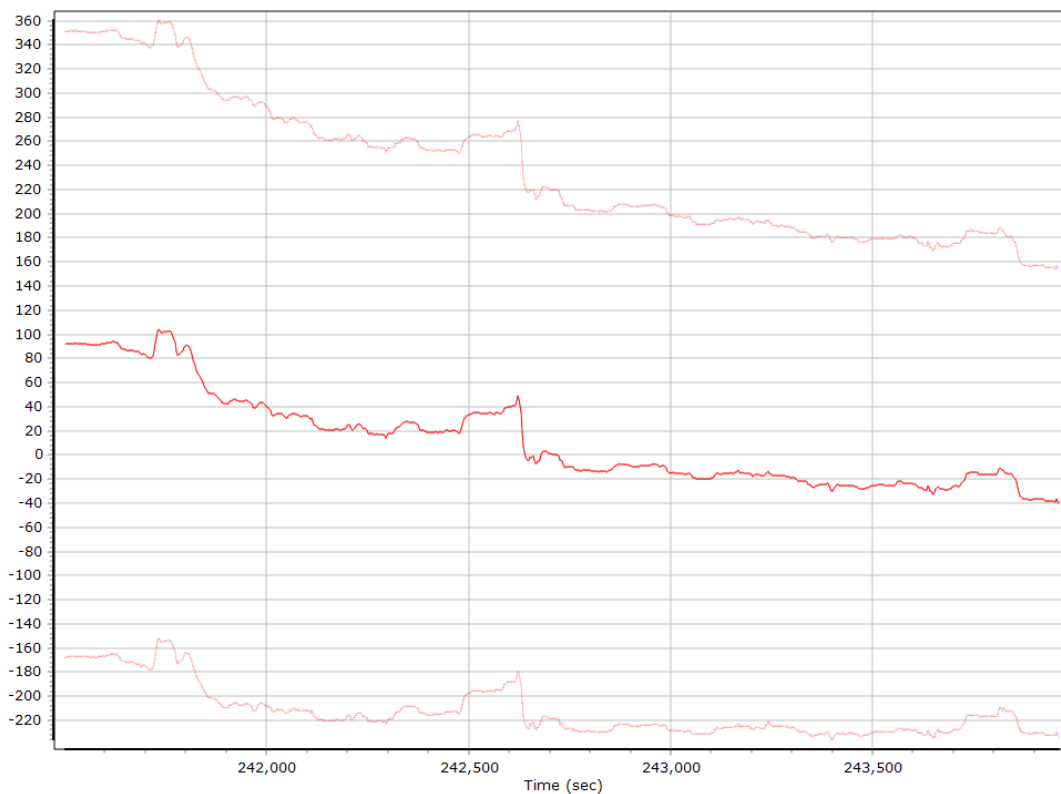
### X Accelerometer Scale Error (ppm)



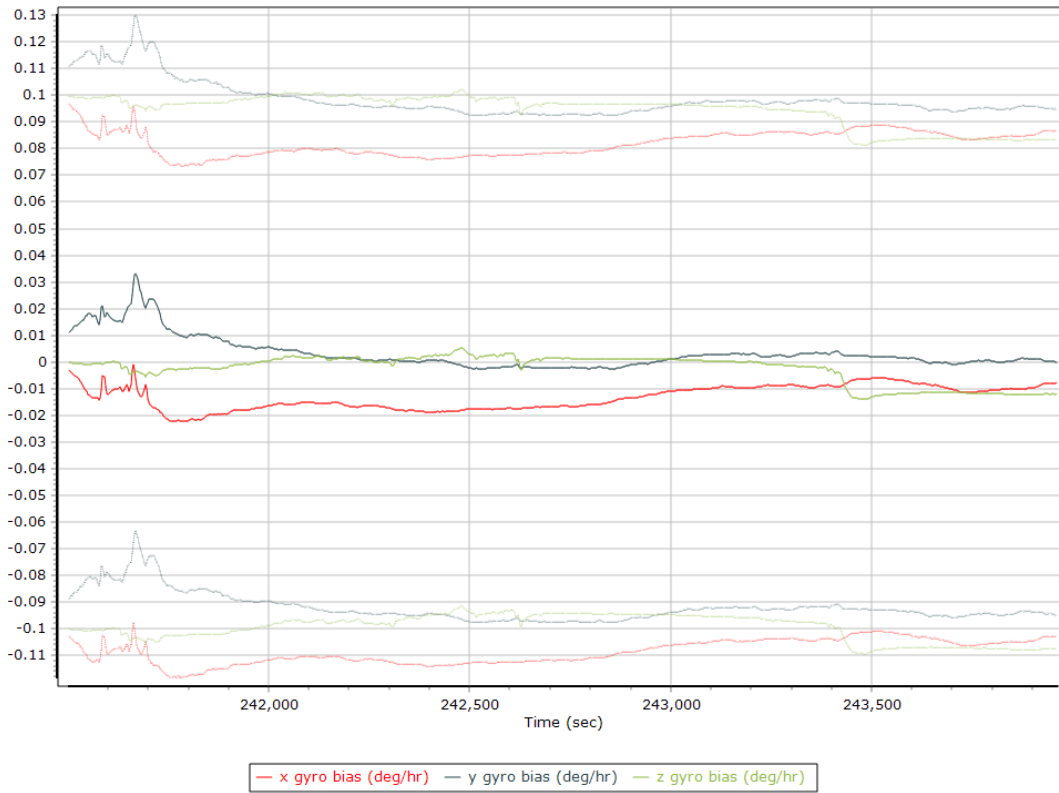
### Y Accelerometer Scale Error (ppm)



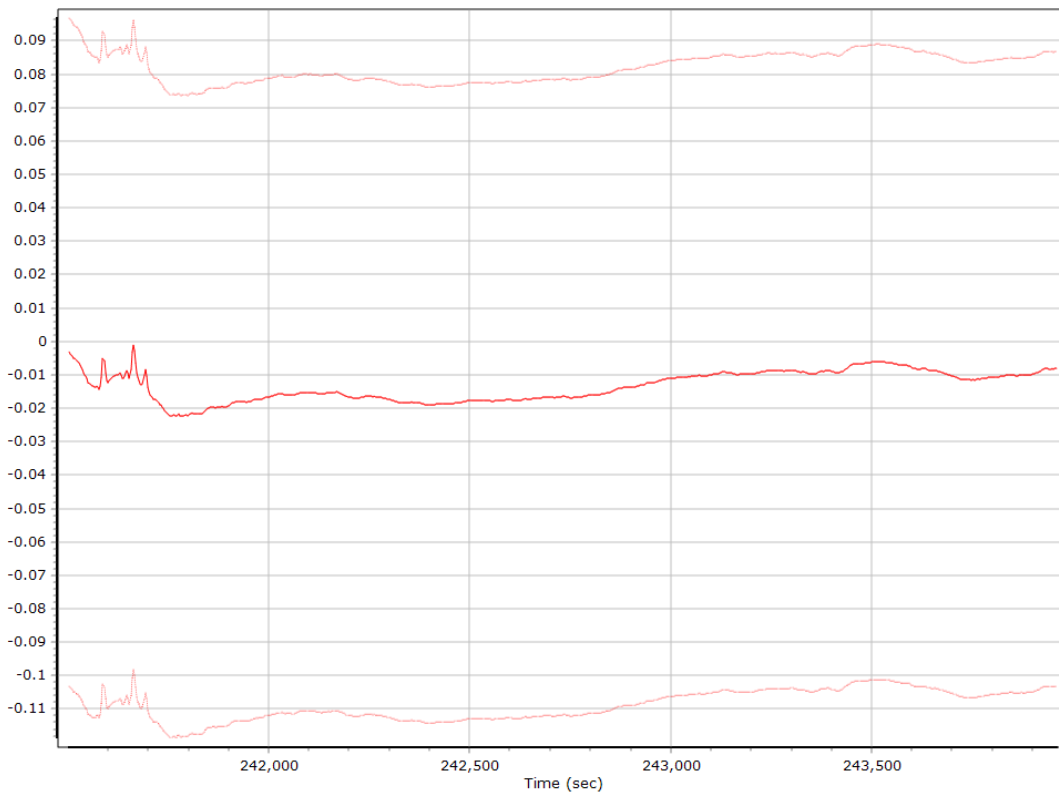
### Z Accelerometer Scale Error (ppm)



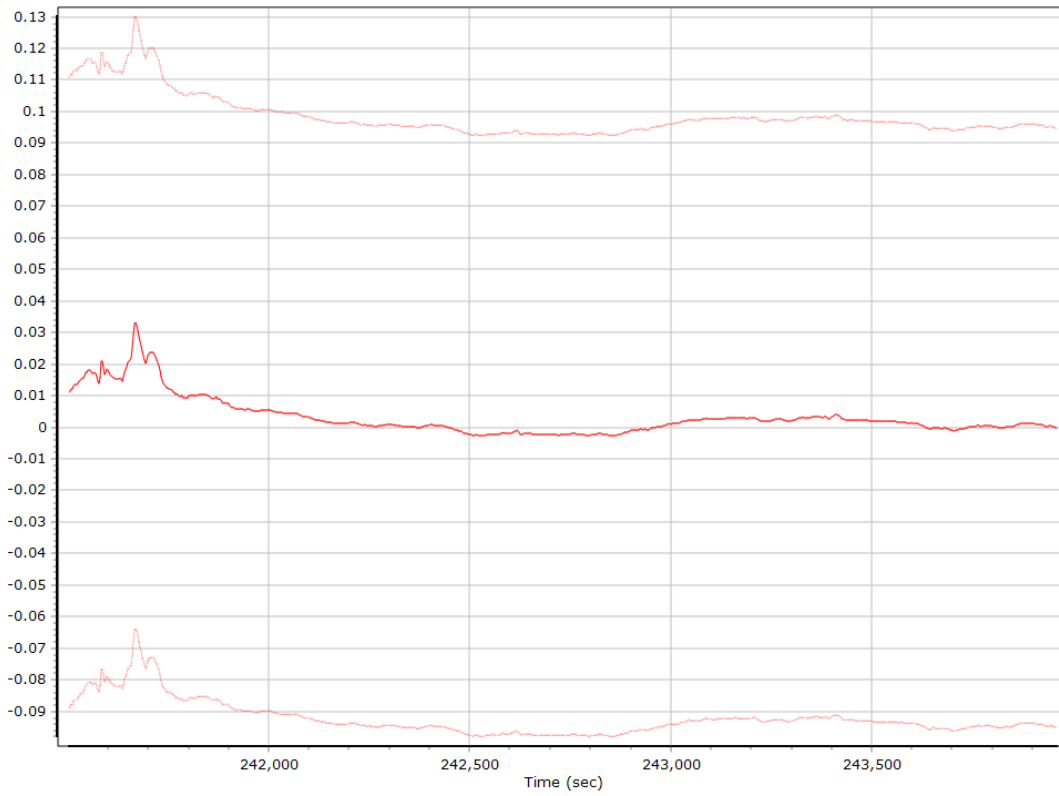
### Gyro Bias (deg/h)



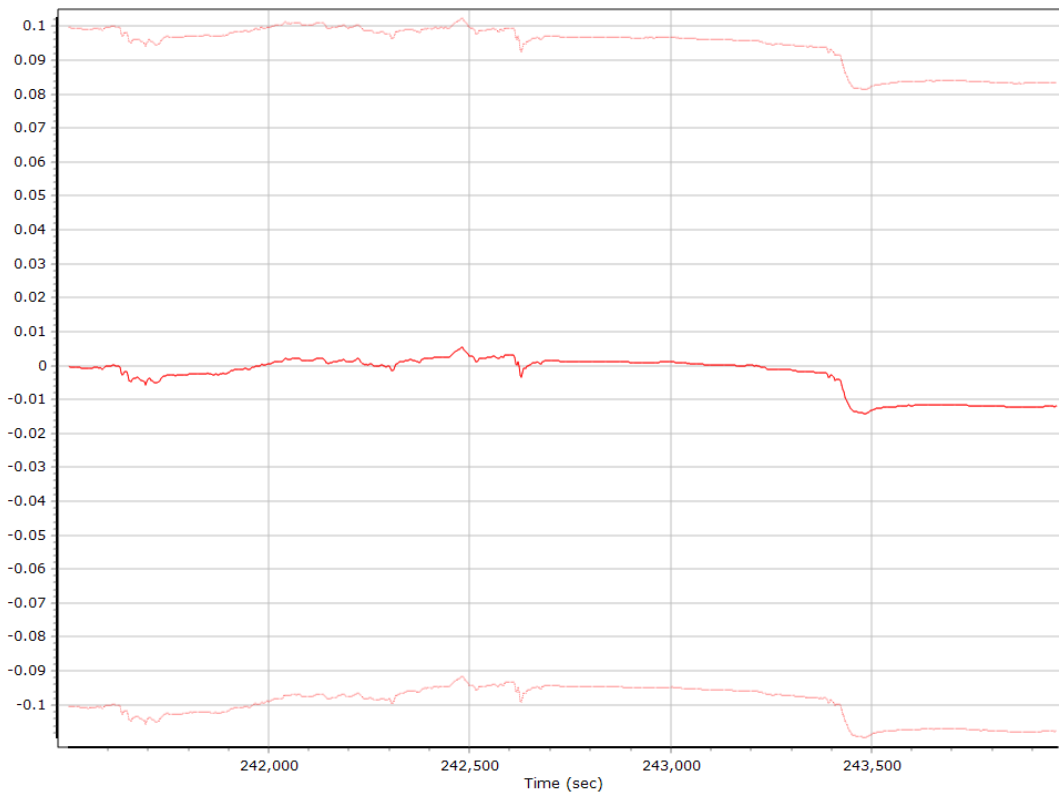
### X Gyro Bias (deg/h)



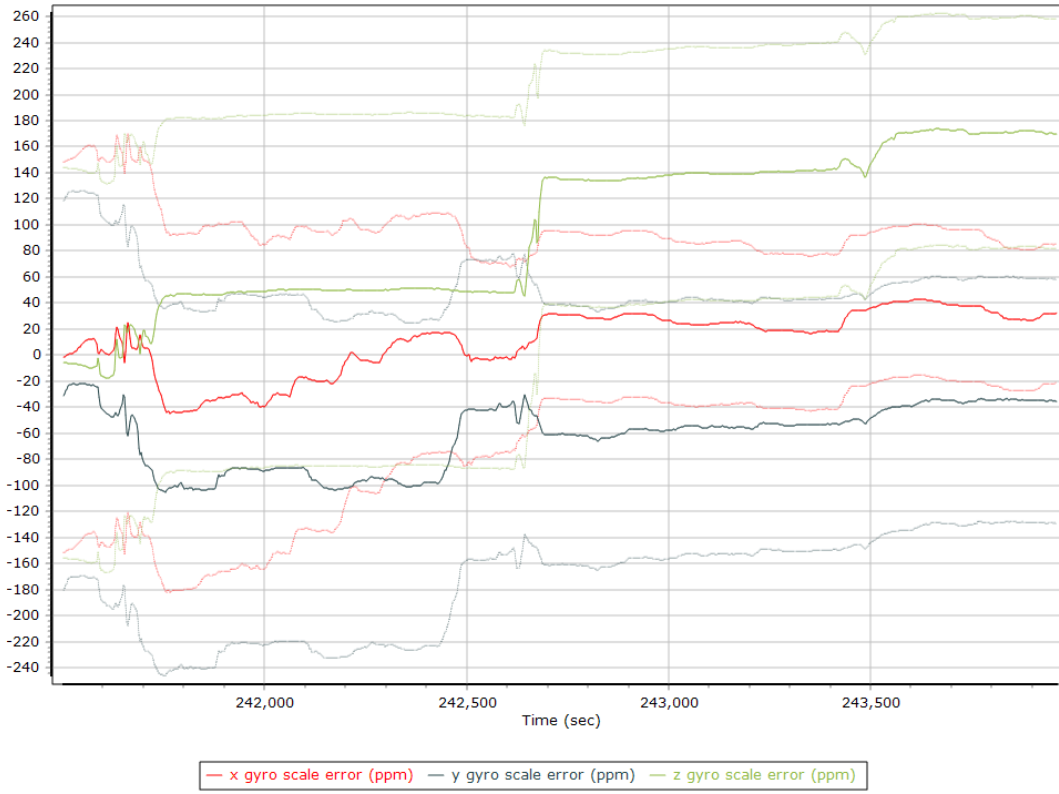
### Y Gyro Bias (deg/h)



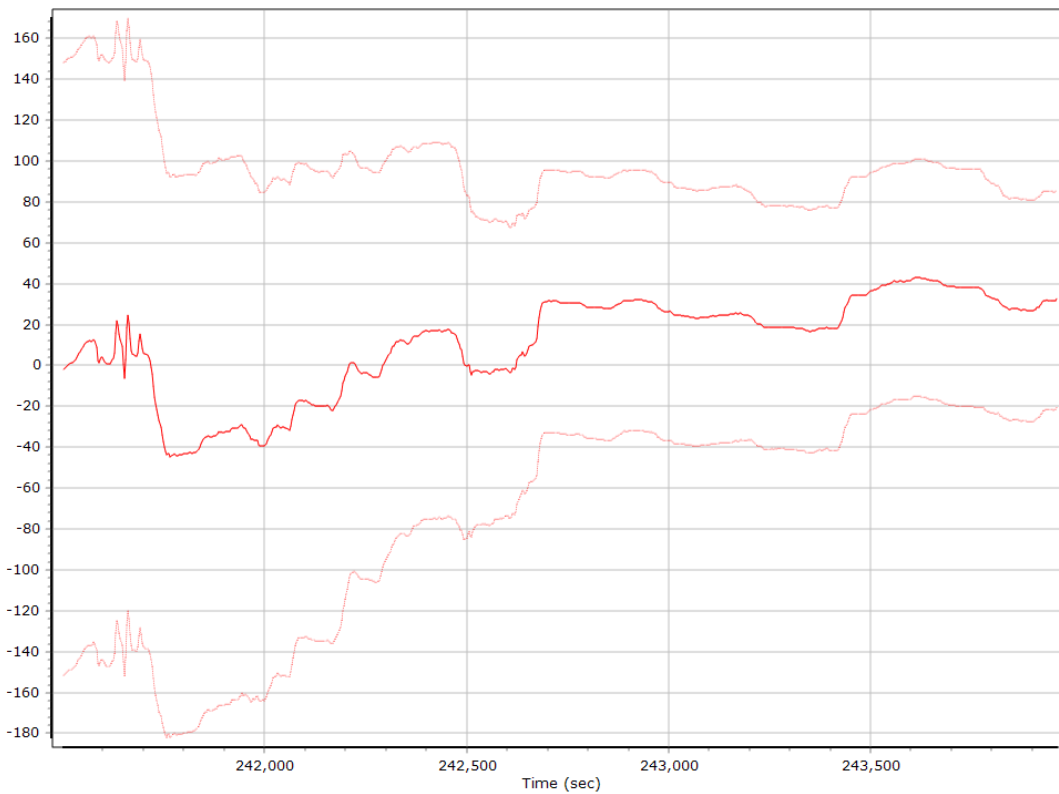
### Z Gyro Bias (deg/h)



### Gyro Scale Error (ppm)

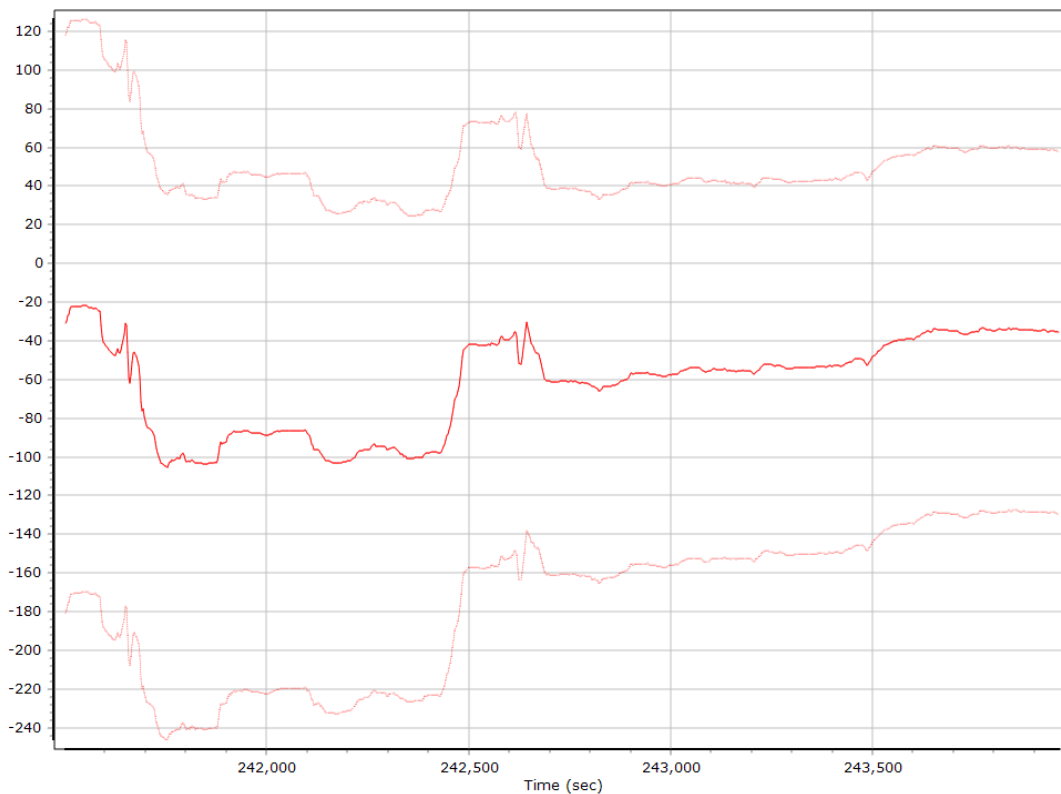


### X Gyro Scale Error (ppm)

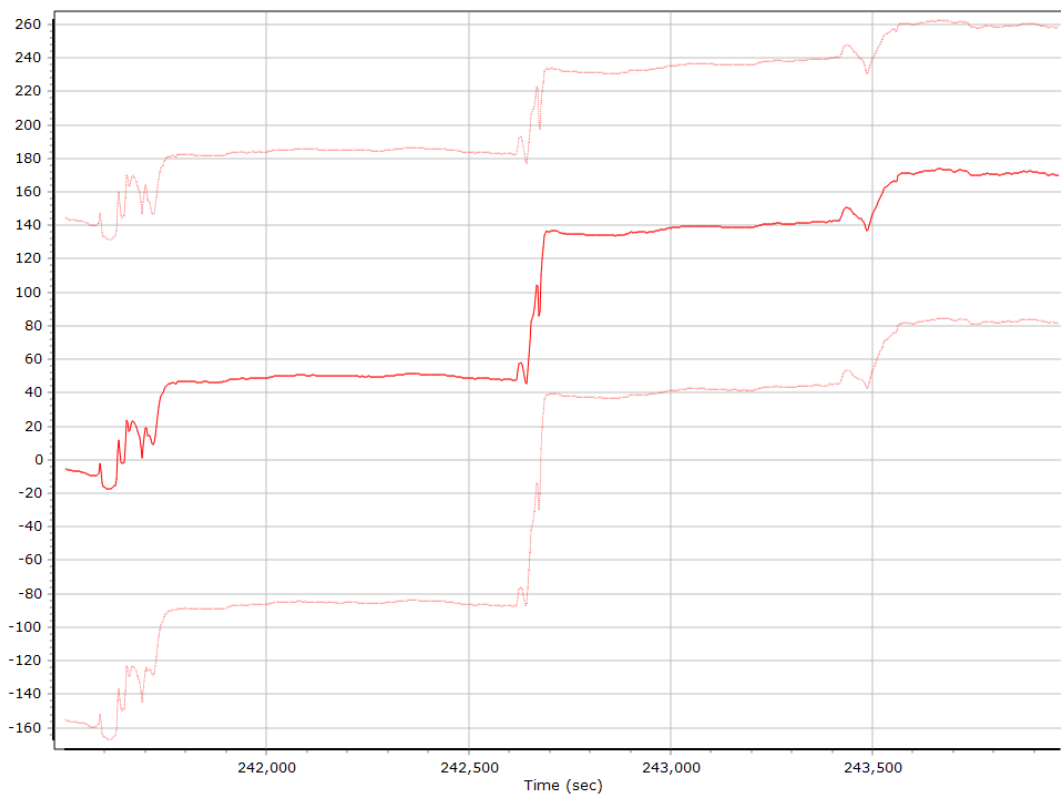




### Y Gyro Scale Error (ppm)

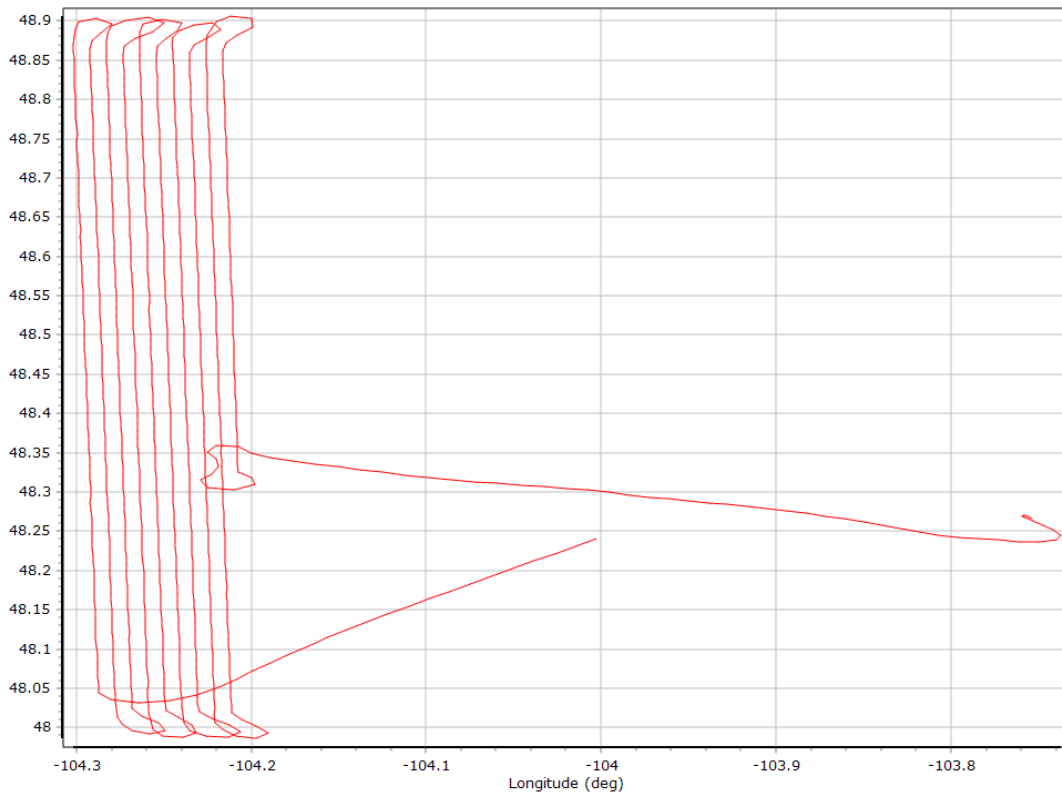


### Z Gyro Scale Error (ppm)

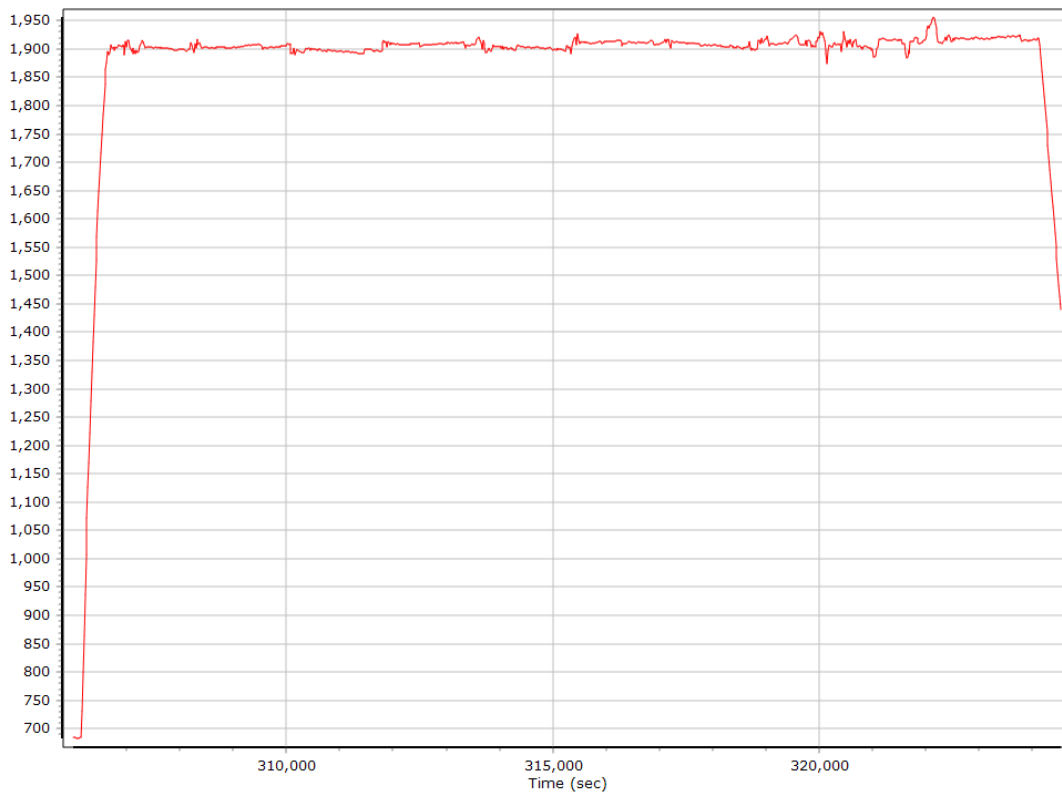


## Smoothed Trajectory Information

### Top View



### Altitude

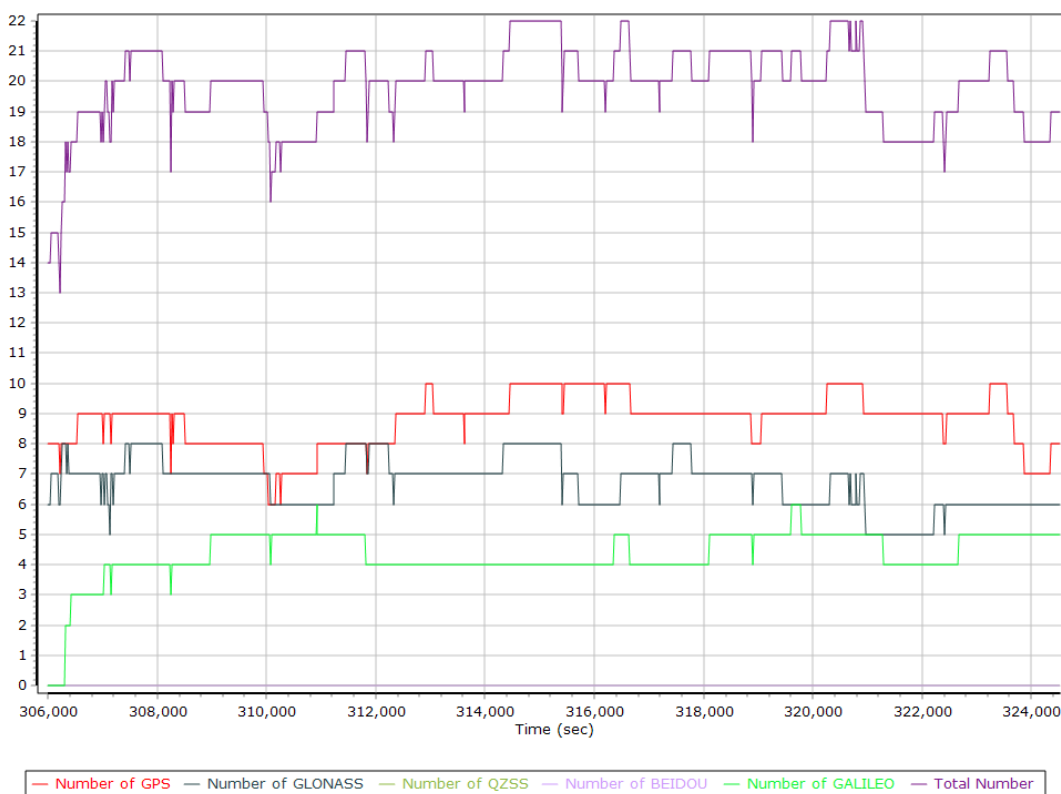


## GNSS QC

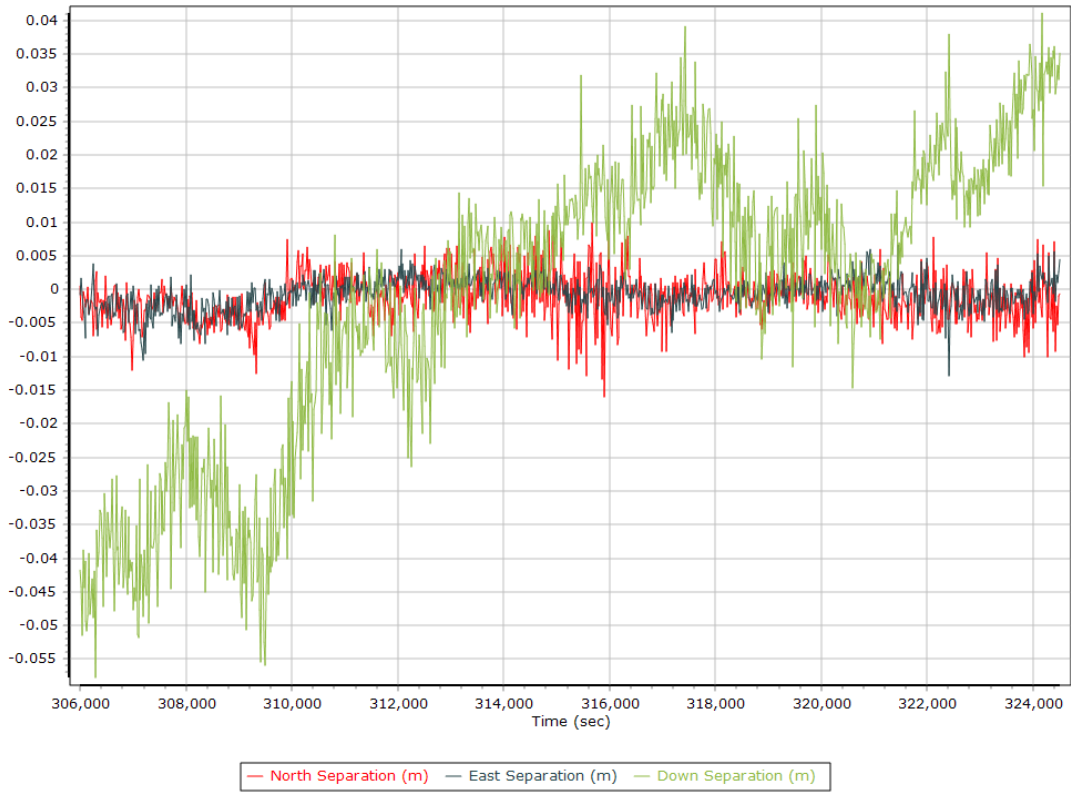
### GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	6	10	9
Number of GLONASS SV	0	8	7
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	0	0
Number of GALILEO SV	0	6	4
Total number of SV	8	22	20
PDOP	1.00	1.89	1.23
QC Solution Gaps	0.00	0.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	18995.00	0.00	0.00
Percentage	100.00	0.00	0.00

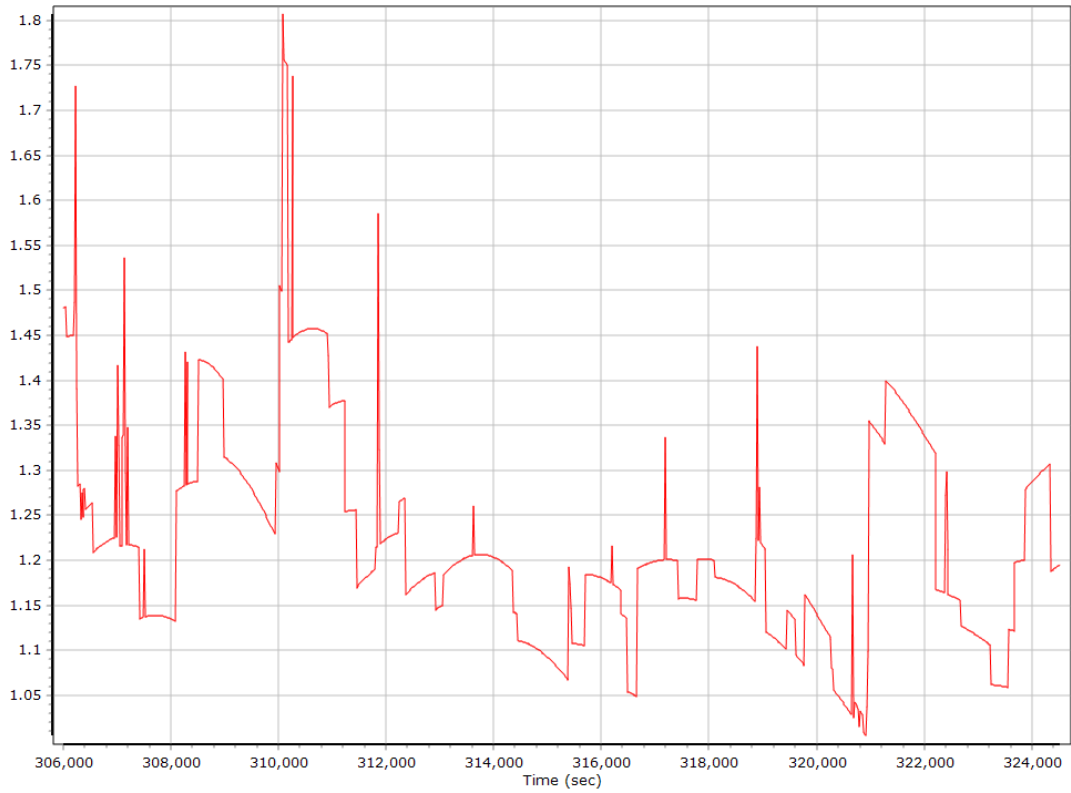
### Num SVs in solution



## Forward/Reverse Separation



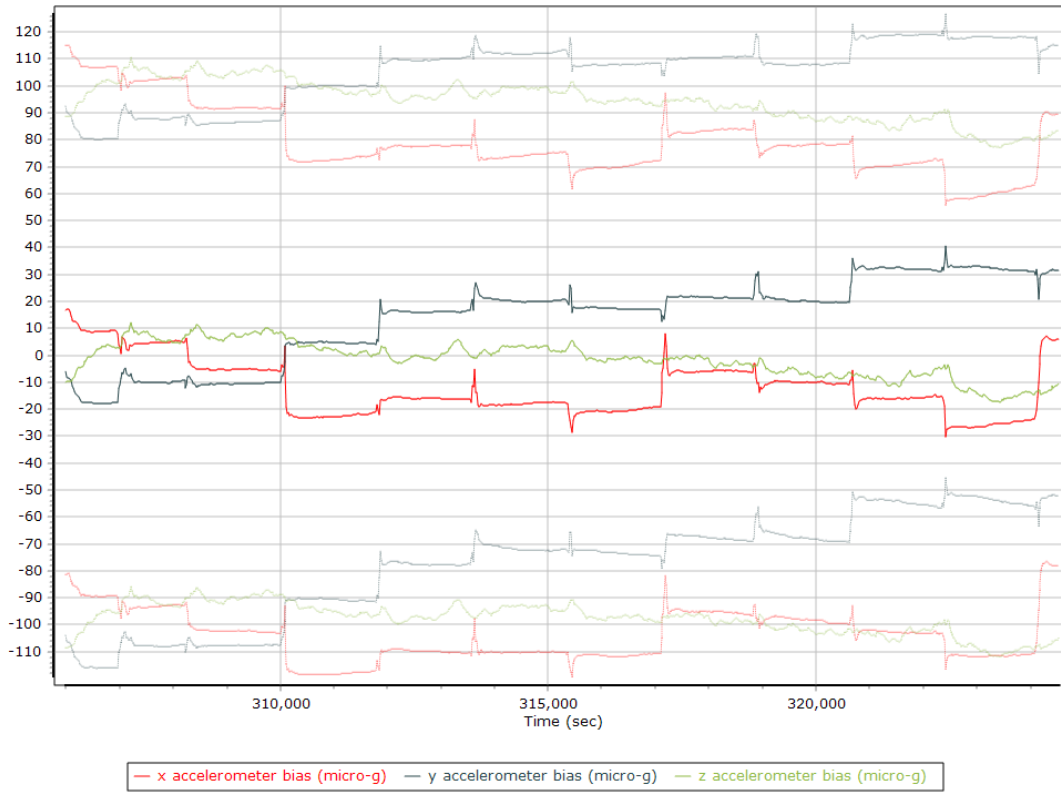
## PDOP



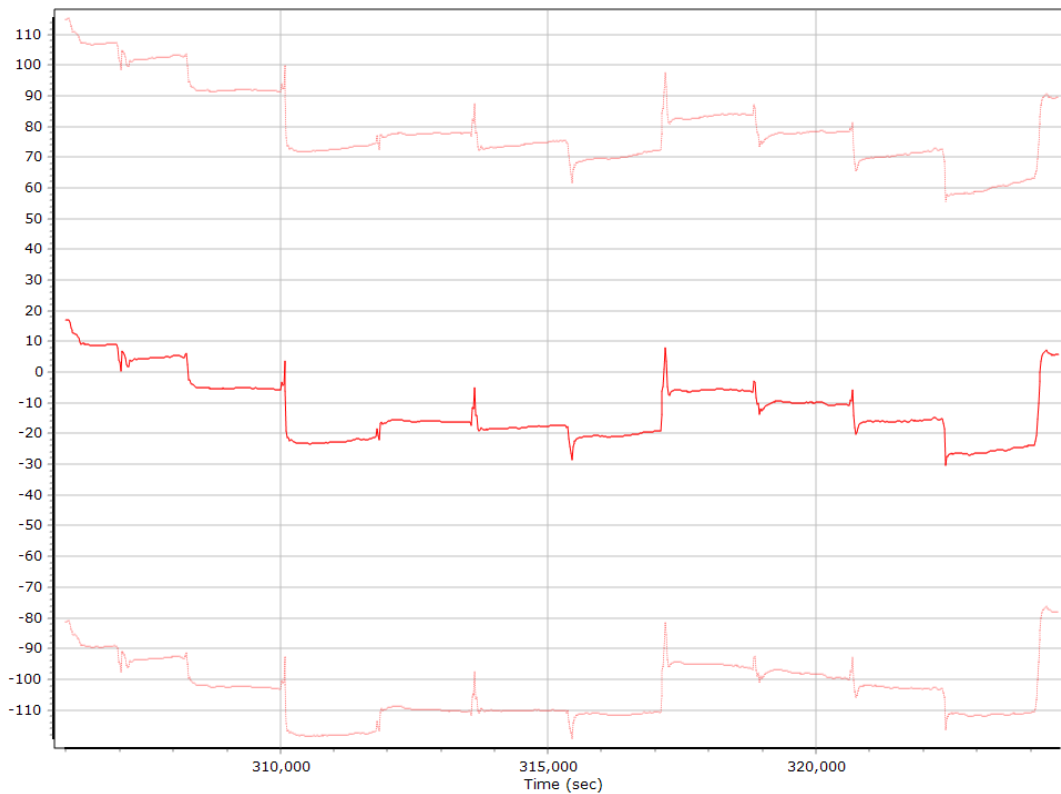
## IN-Fusion QC

### Forward Processed Estimated Errors, Reference Frame

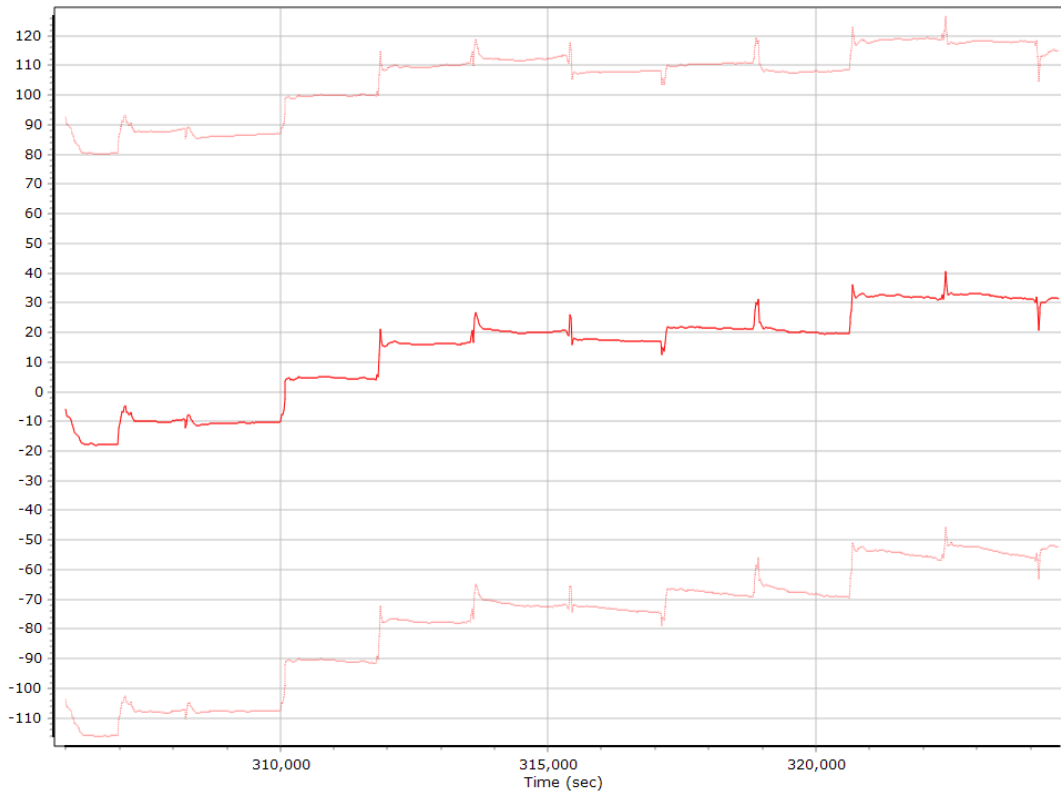
#### Accelerometer Bias (micro-g)



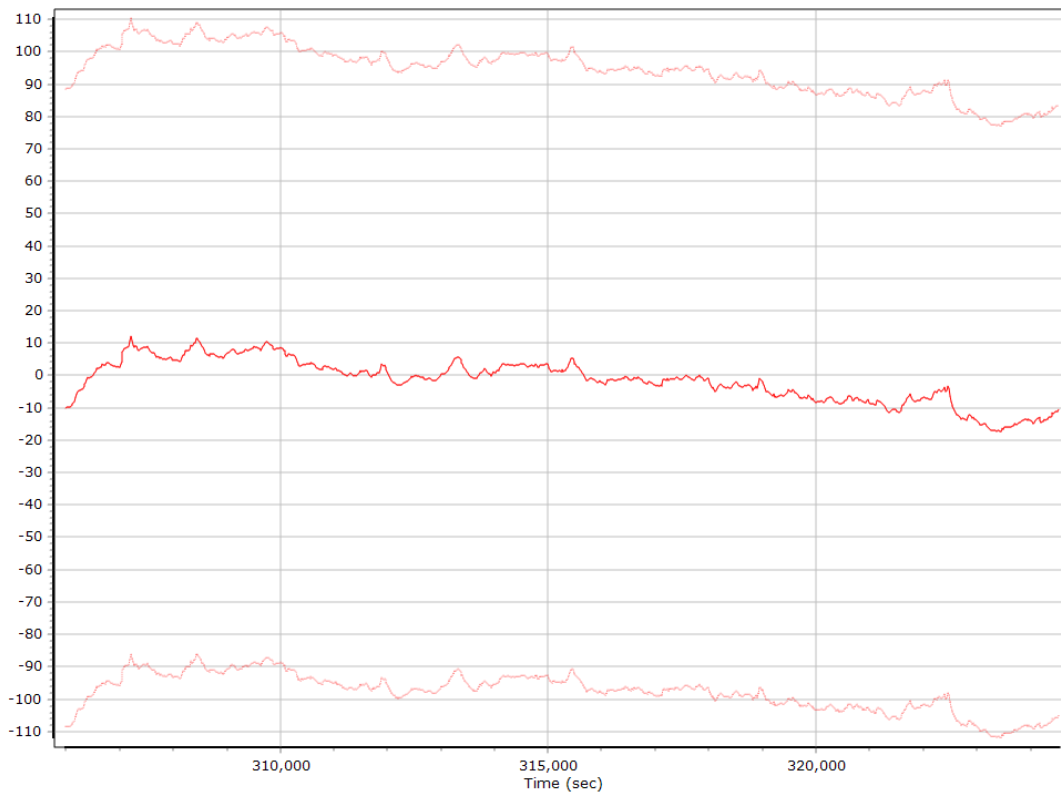
#### X Accelerometer Bias (micro-g)



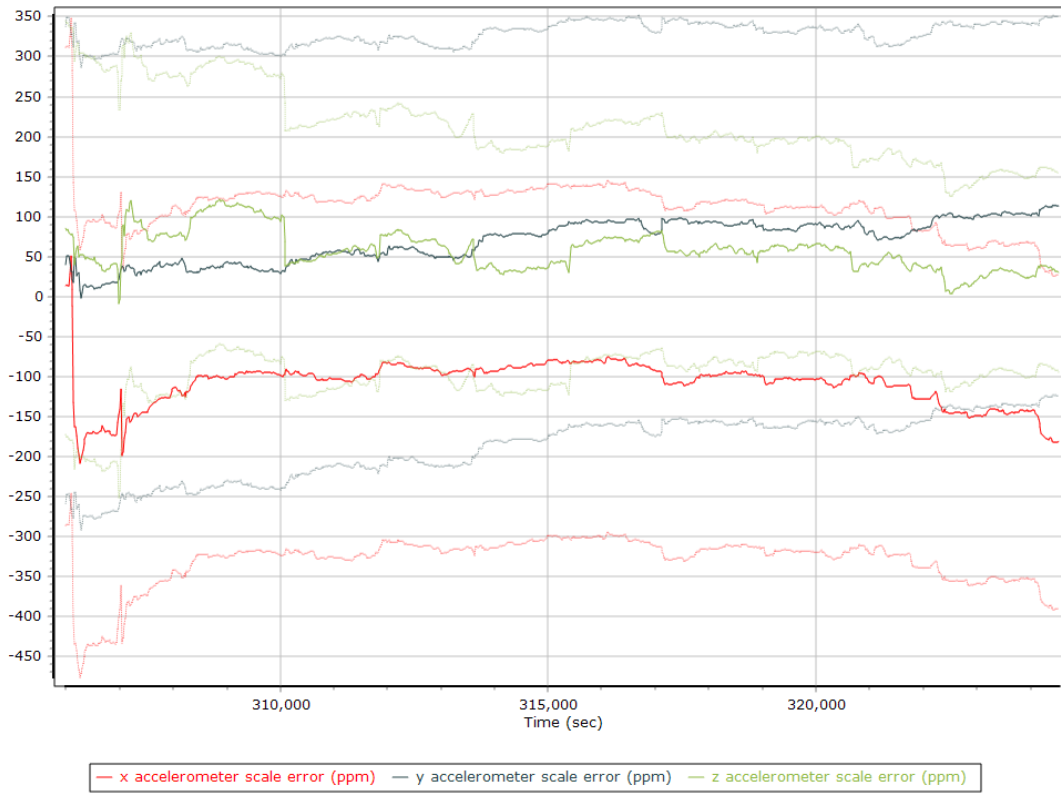
### Y Accelerometer Bias (micro-g)



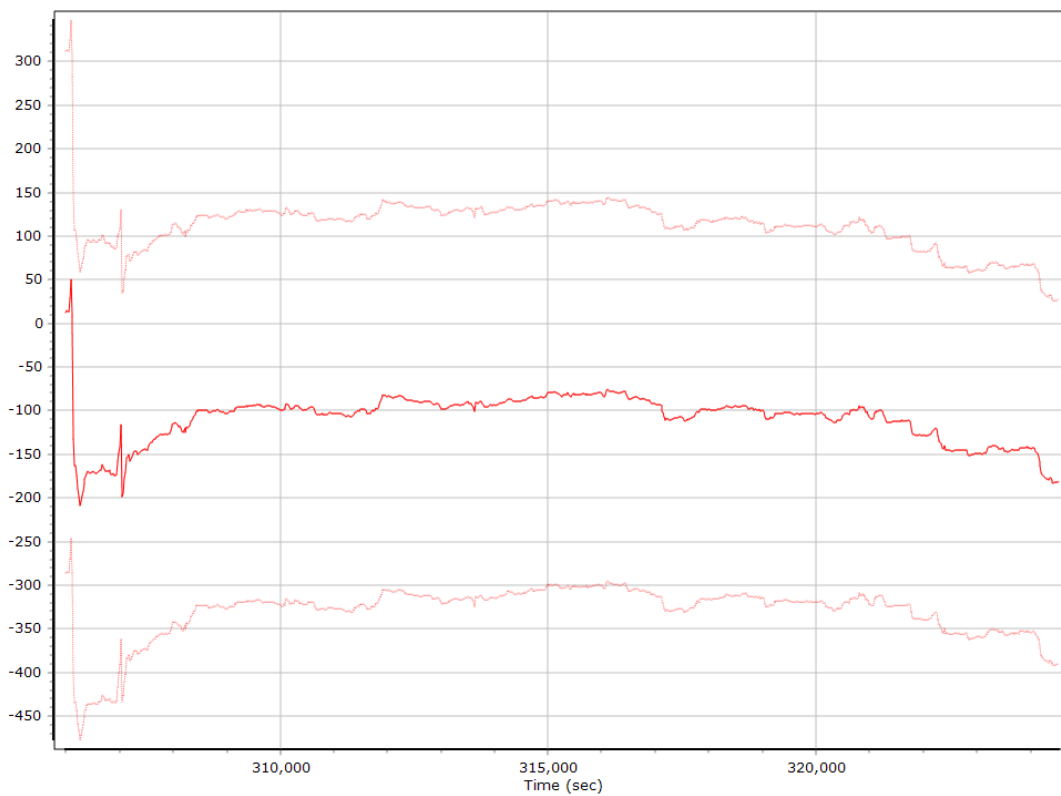
### Z Accelerometer Bias (micro-g)



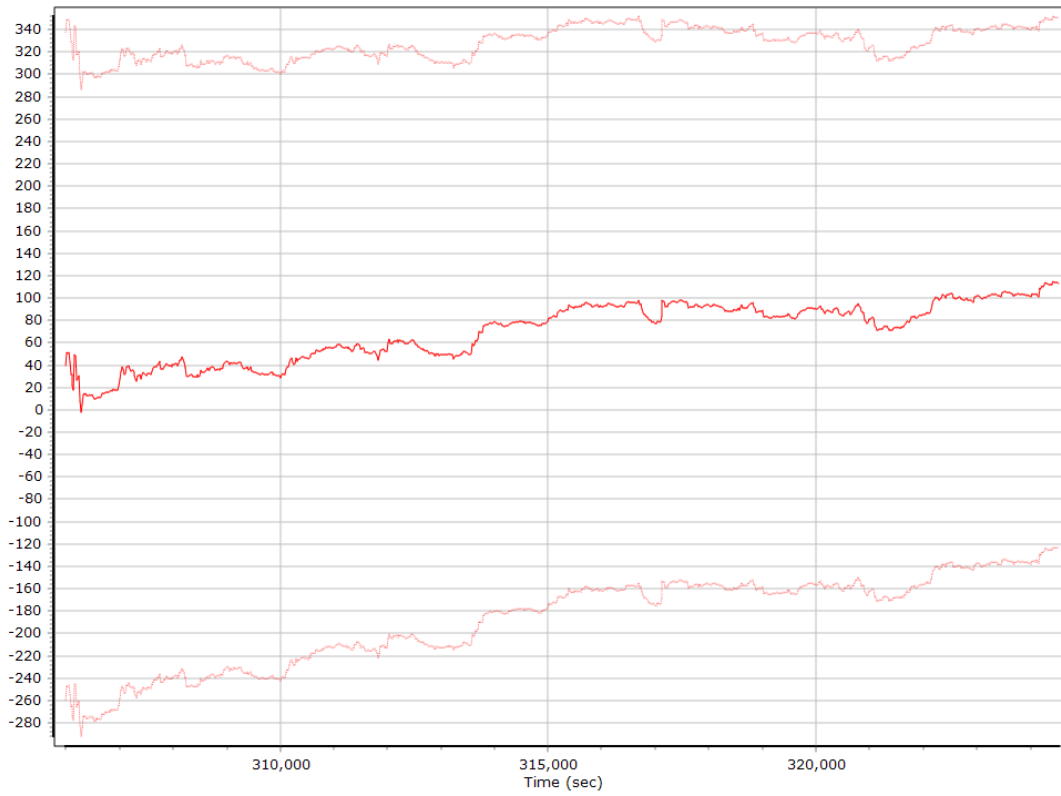
### Accelerometer Scale Error (ppm)



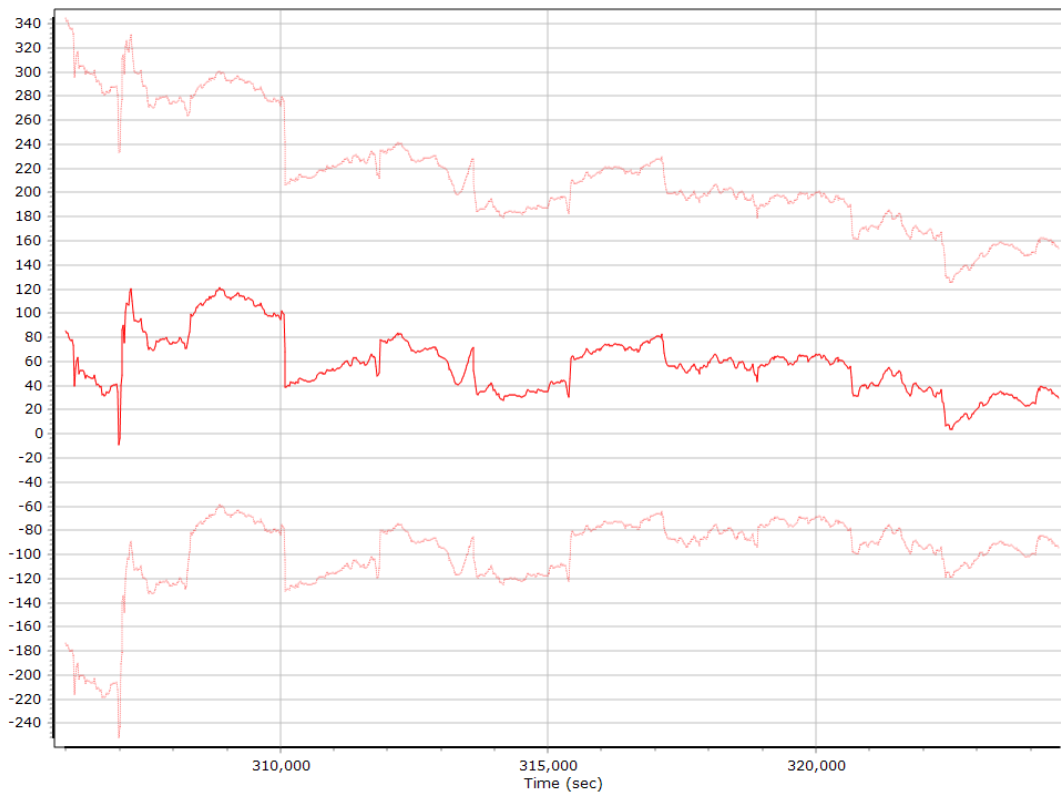
### X Accelerometer Scale Error (ppm)



### Y Accelerometer Scale Error (ppm)

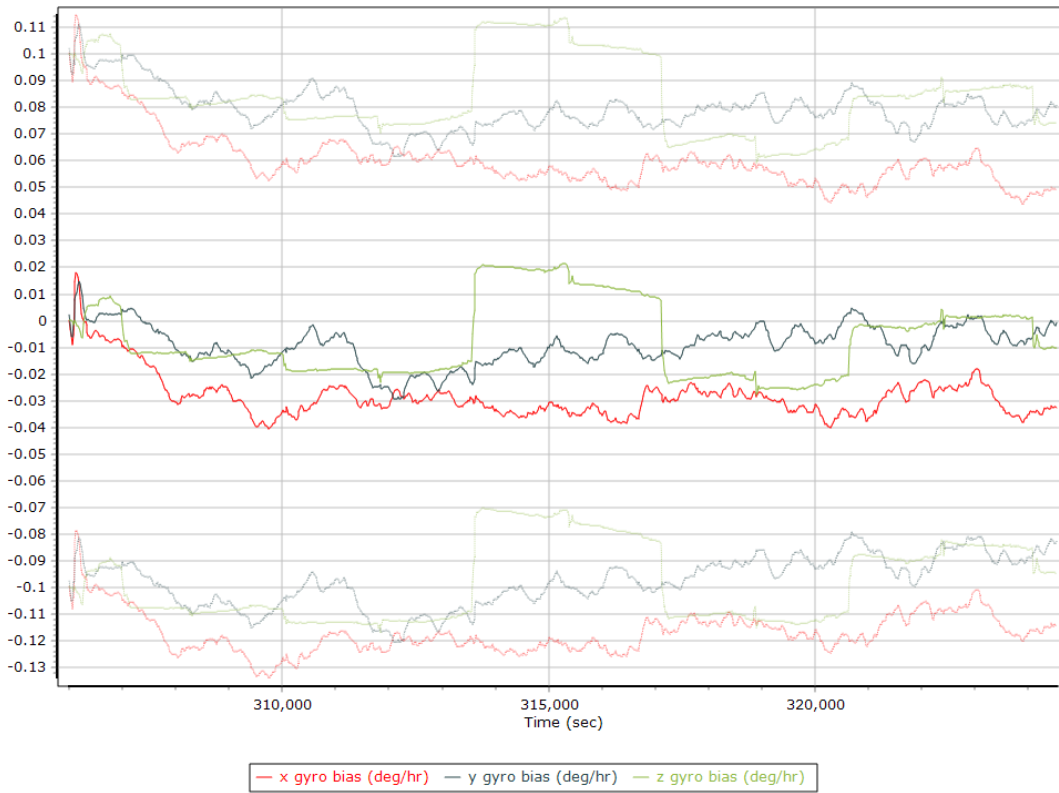


### Z Accelerometer Scale Error (ppm)

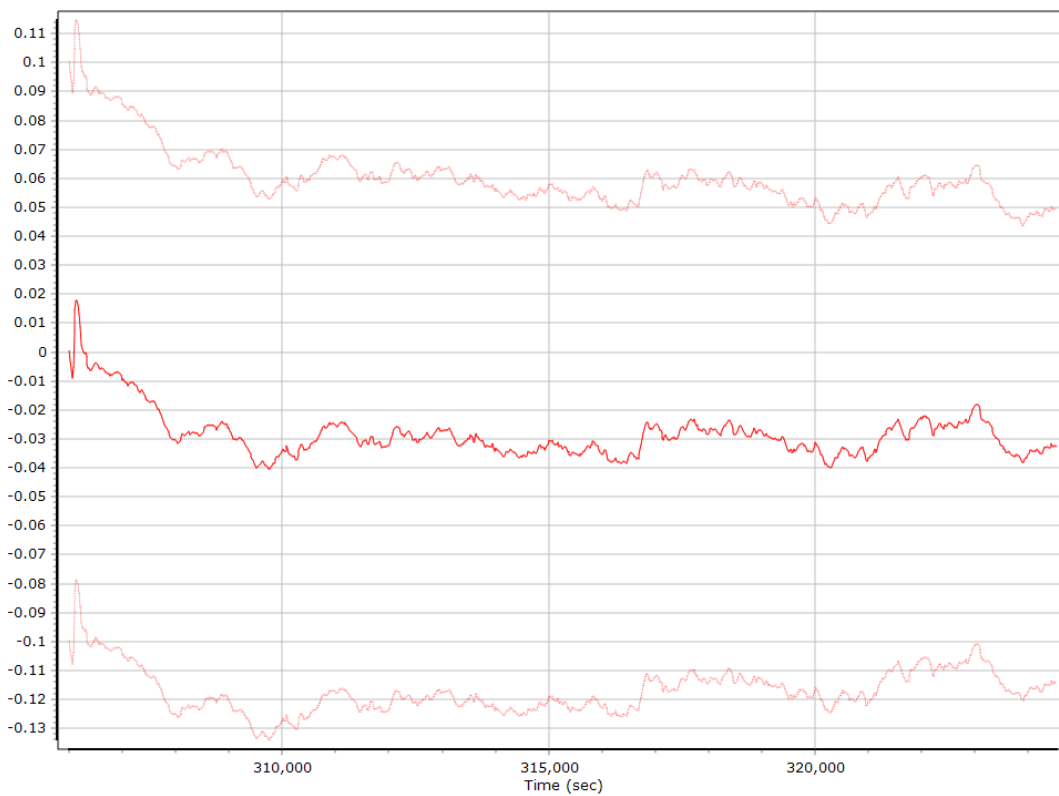




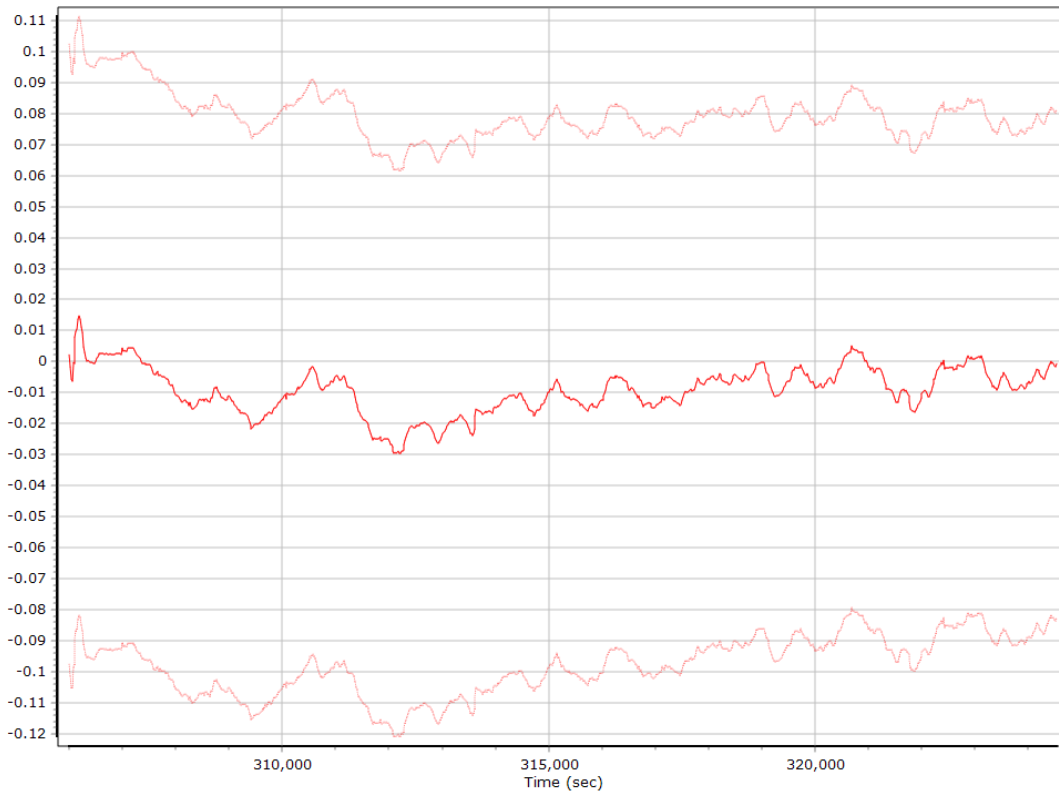
### Gyro Bias (deg/h)



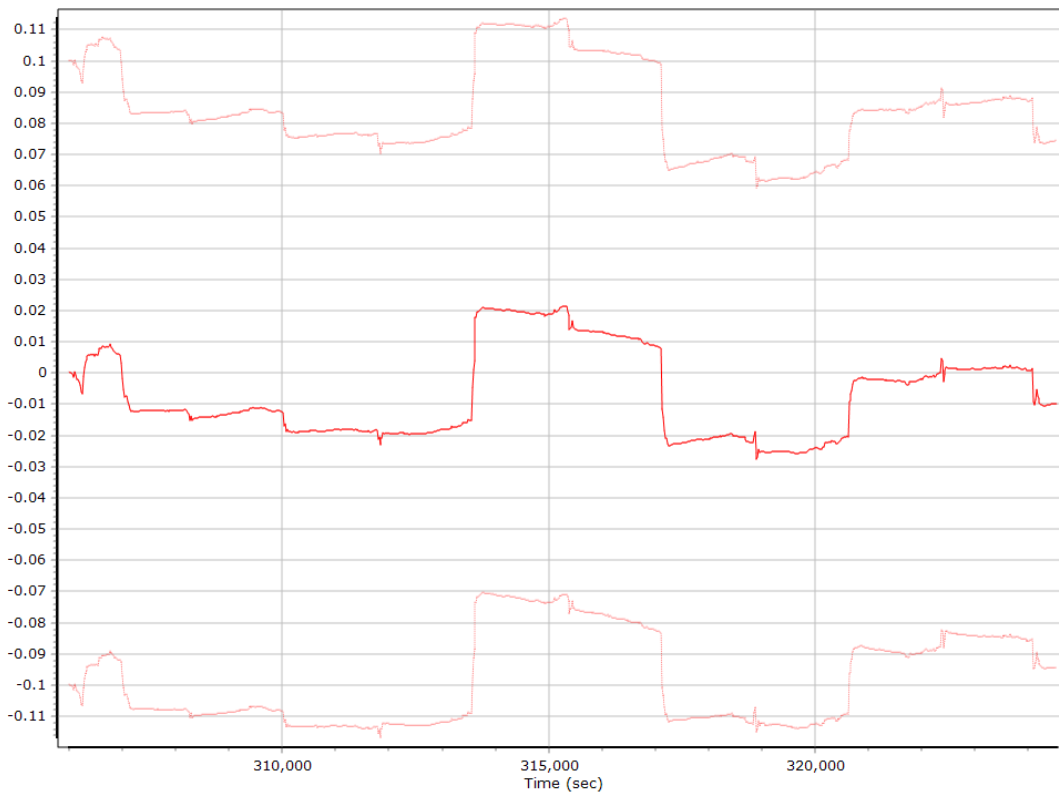
### X Gyro Bias (deg/h)



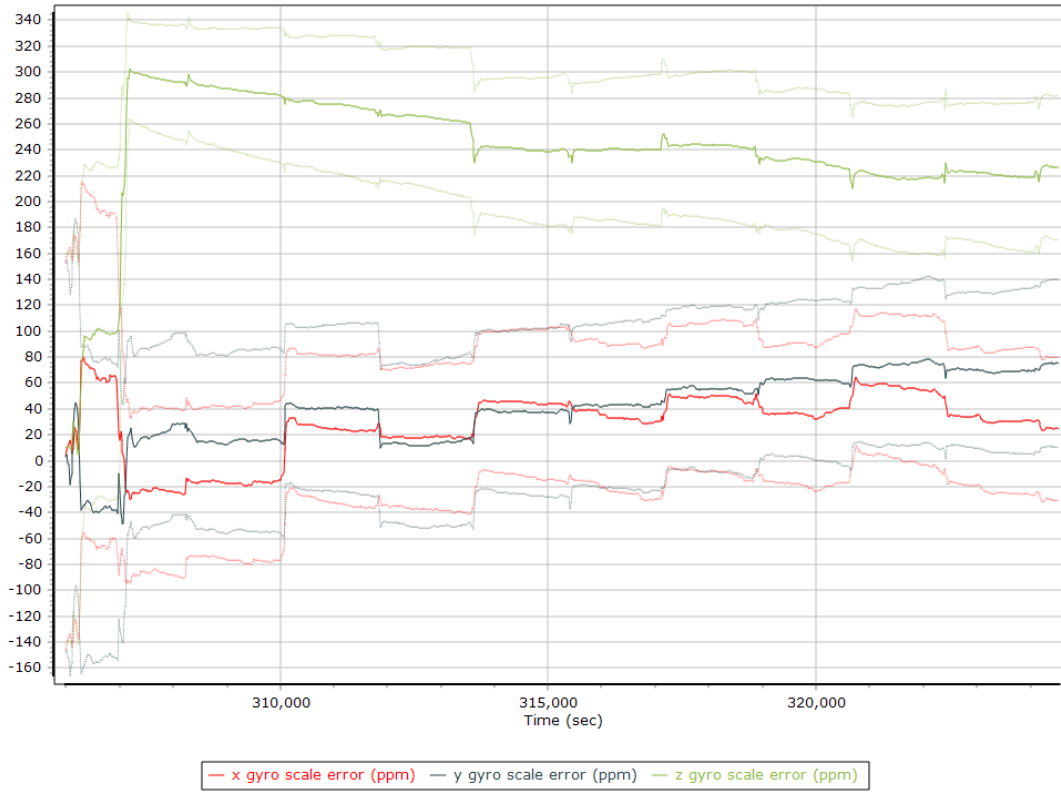
### Y Gyro Bias (deg/h)



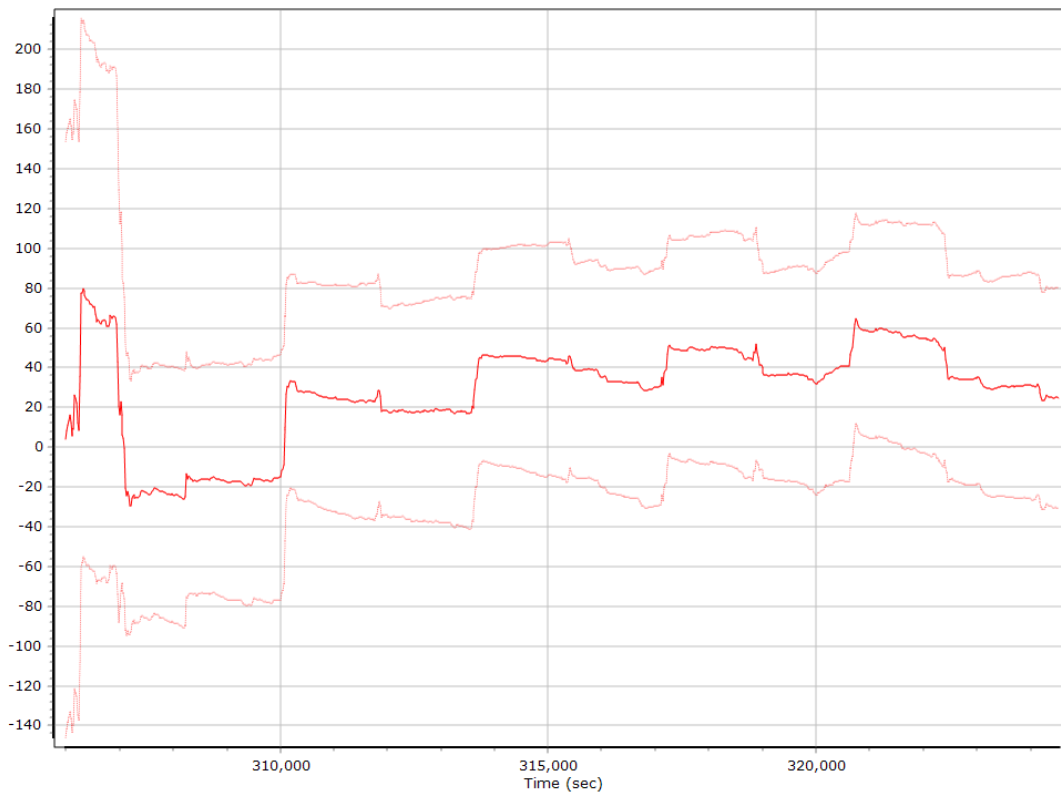
### Z Gyro Bias (deg/h)



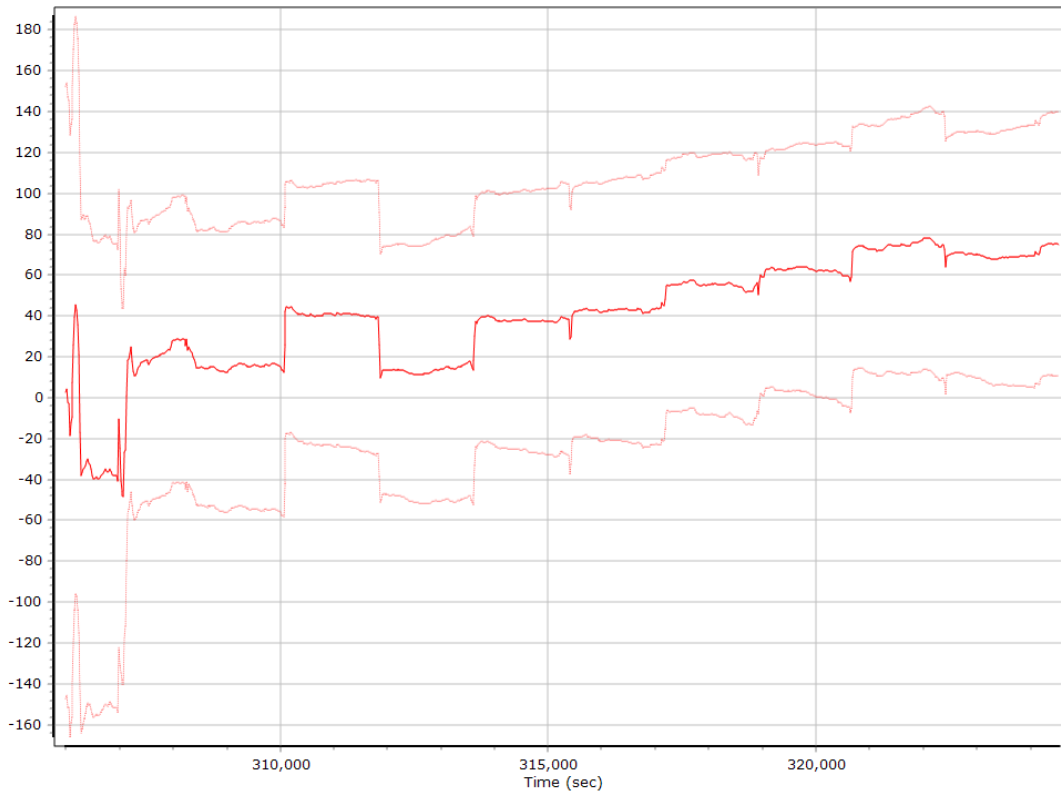
### Gyro Scale Error (ppm)



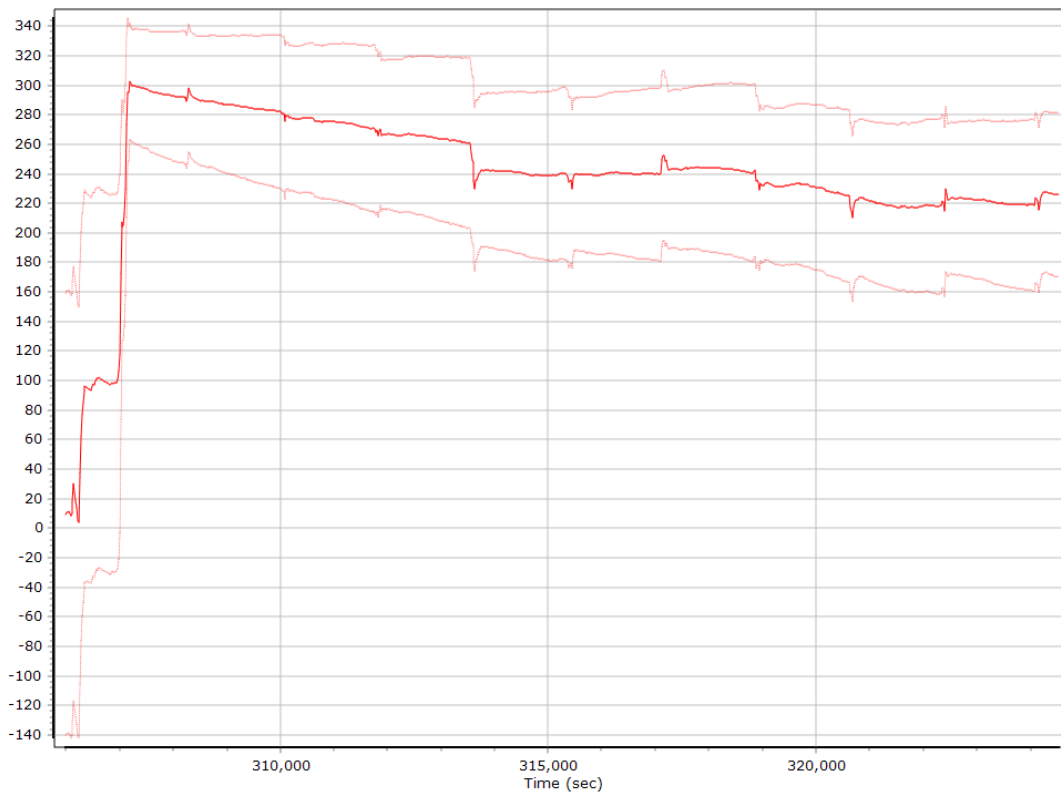
### X Gyro Scale Error (ppm)



### Y Gyro Scale Error (ppm)

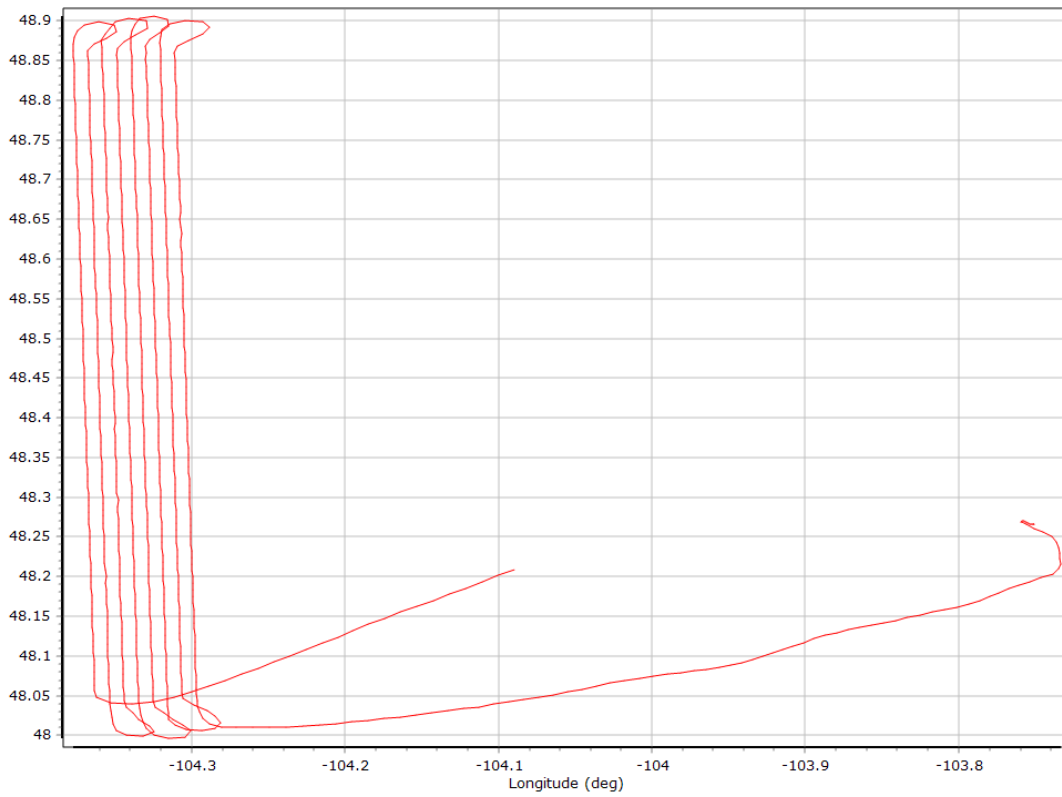


### Z Gyro Scale Error (ppm)



## Smoothed Trajectory Information

### Top View



### Altitude

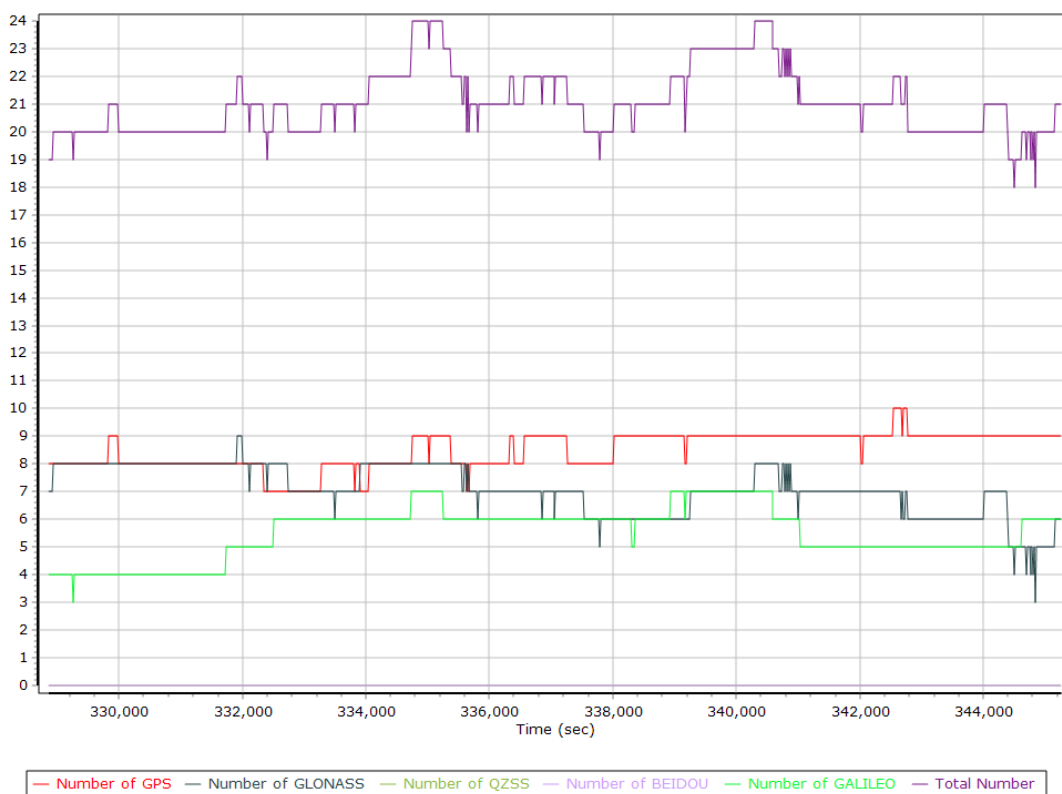


## GNSS QC

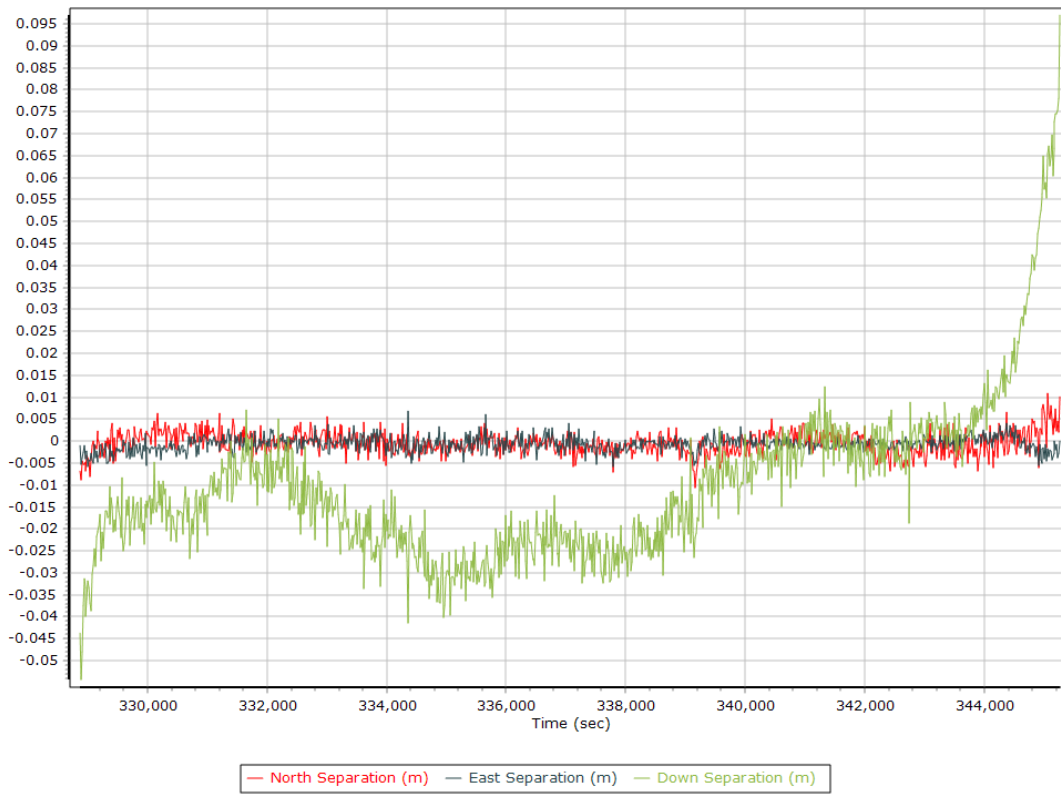
### GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	7	10	8
Number of GLONASS SV	0	9	7
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	0	0
Number of GALILEO SV	3	7	5
Total number of SV	12	24	21
PDOP	0.99	1.61	1.17
QC Solution Gaps	0.00	0.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	16834.00	0.00	0.00
Percentage	100.00	0.00	0.00

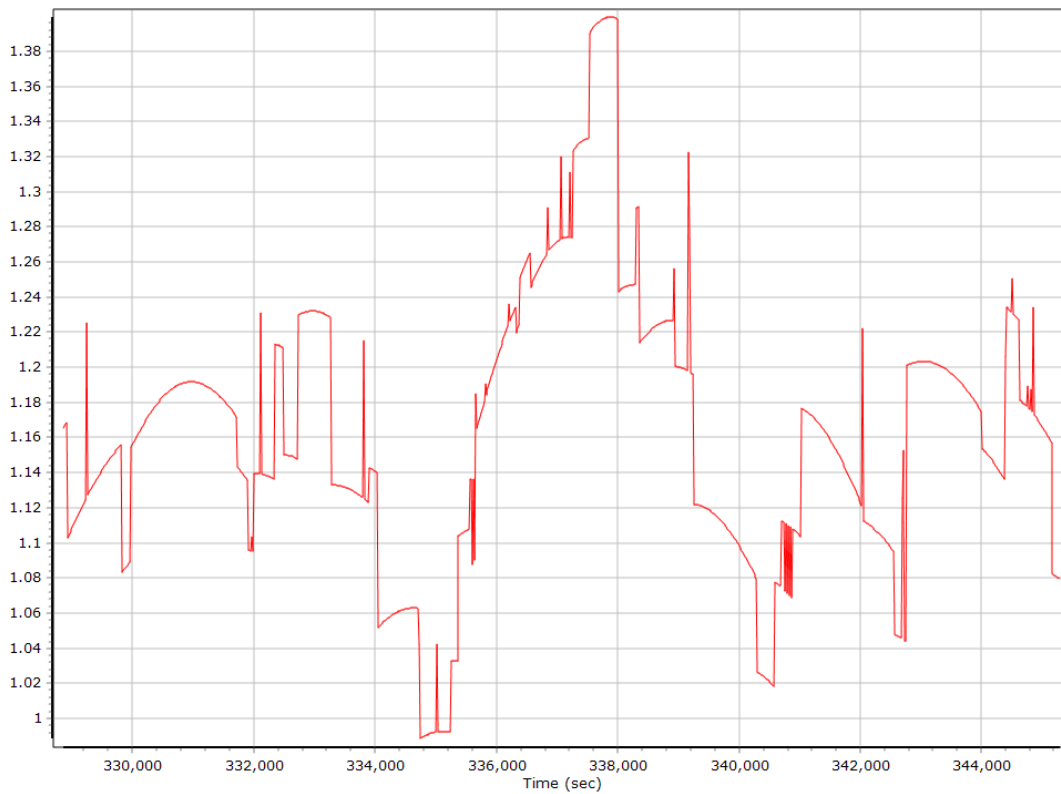
### Num SVs in solution



## Forward/Reverse Separation



## PDOP



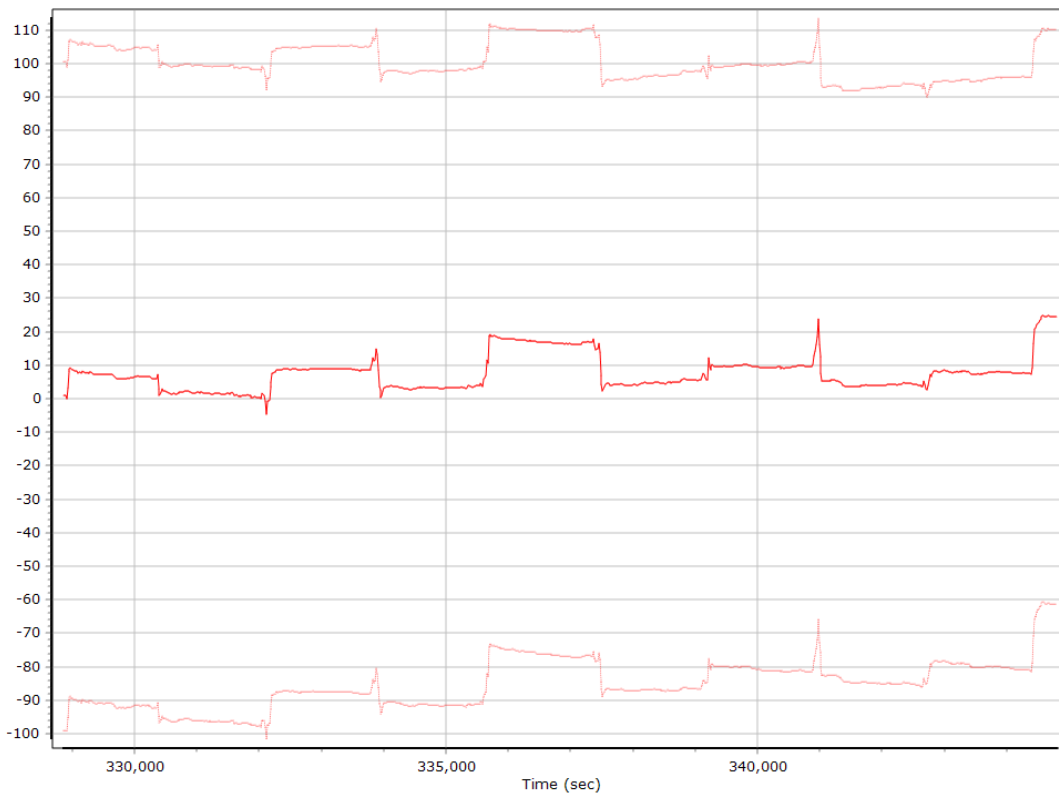
## IN-Fusion QC

### Forward Processed Estimated Errors, Reference Frame

#### Accelerometer Bias (micro-g)

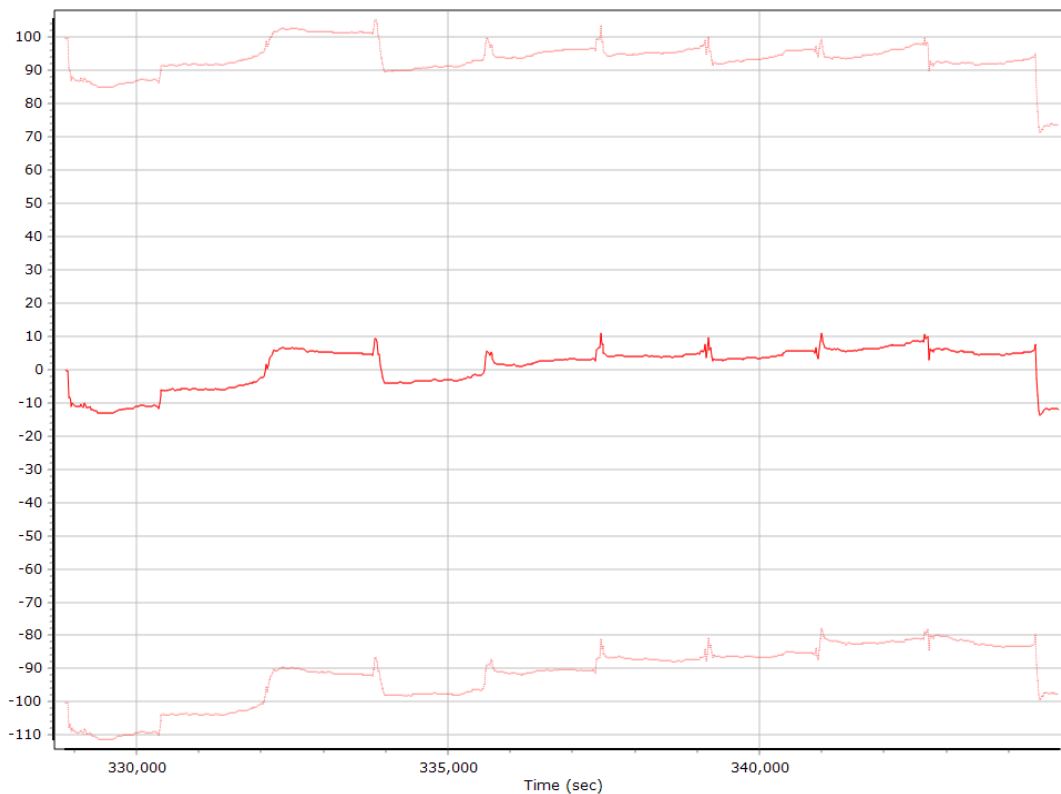


#### X Accelerometer Bias (micro-g)





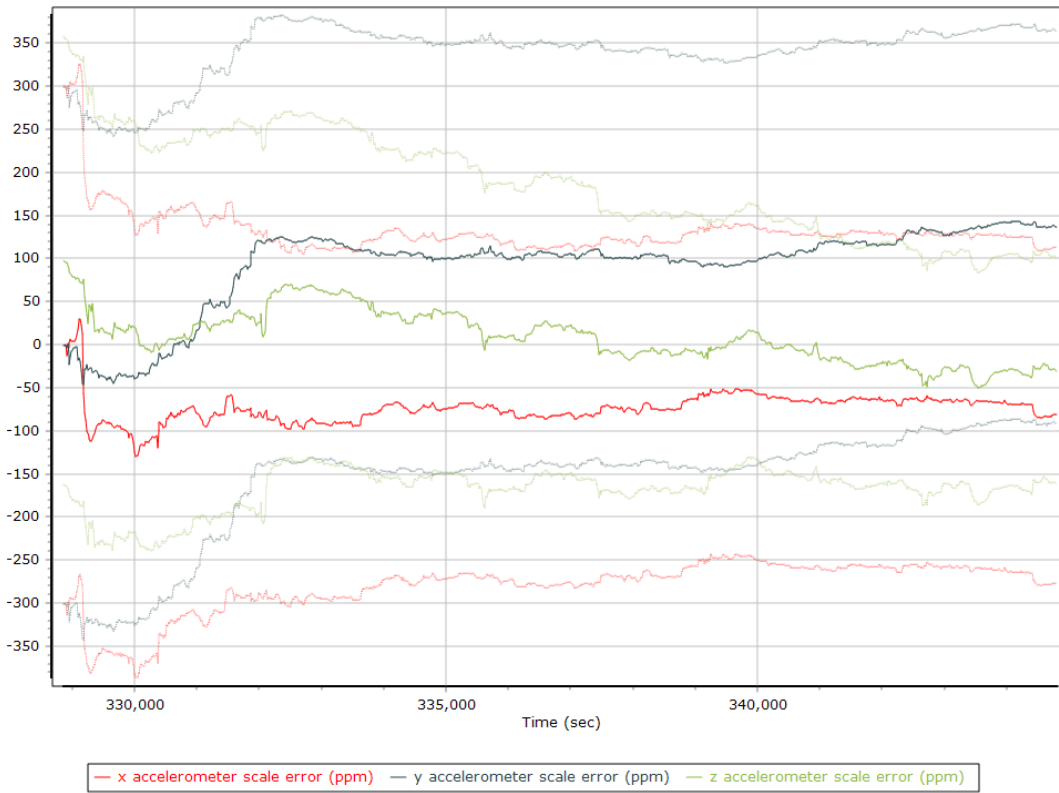
### Y Accelerometer Bias (micro-g)



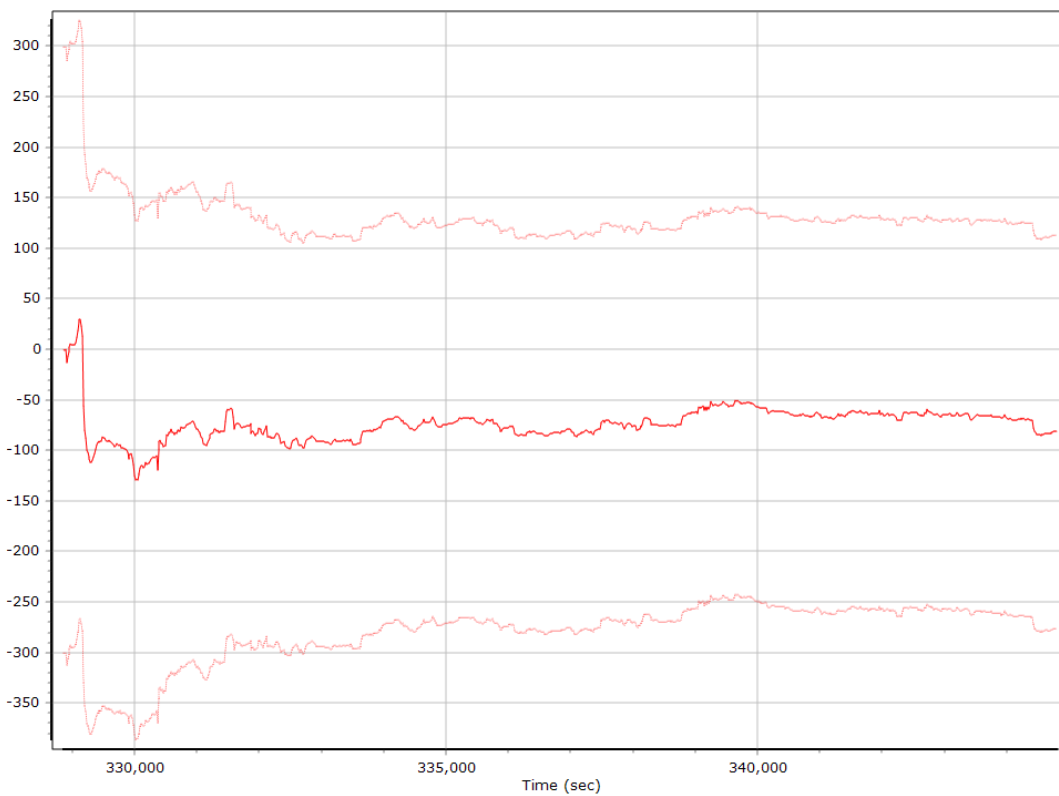
### Z Accelerometer Bias (micro-g)



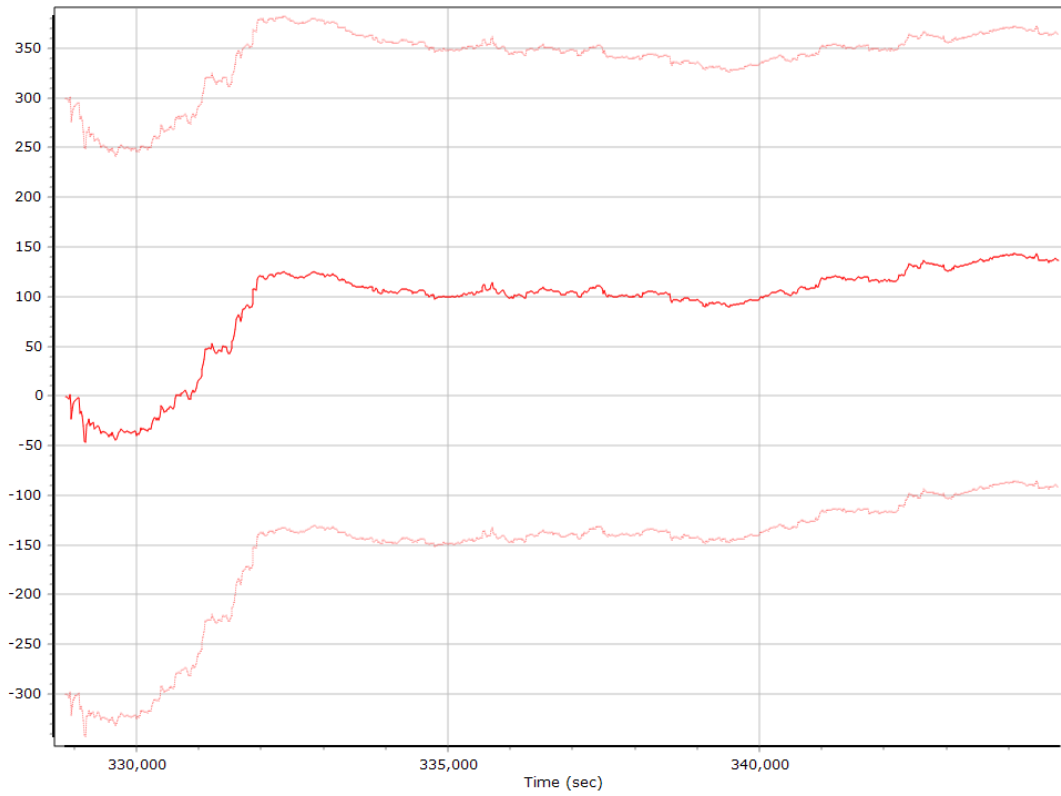
### Accelerometer Scale Error (ppm)



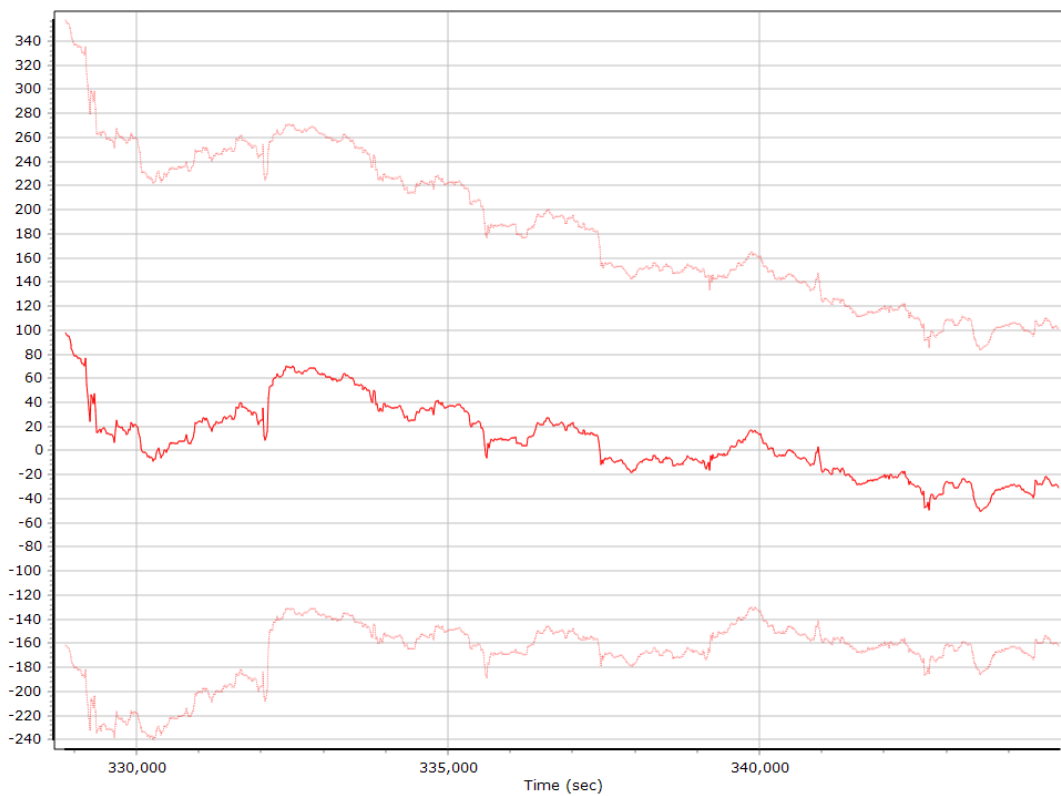
### X Accelerometer Scale Error (ppm)



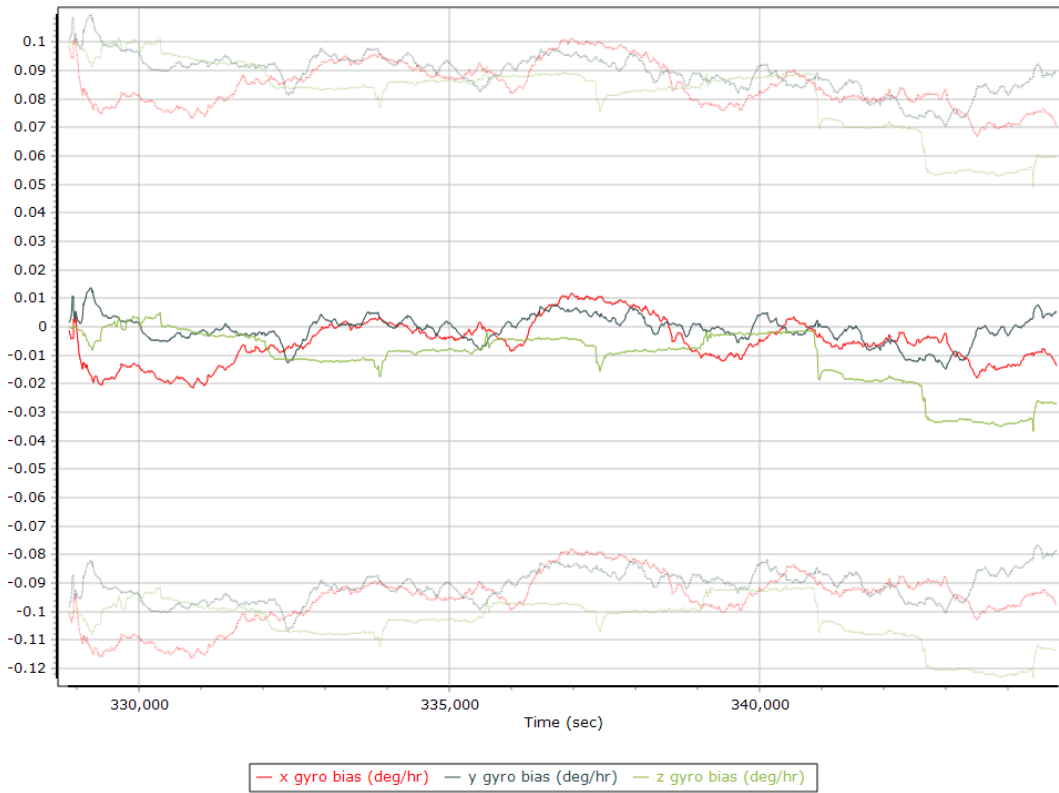
### Y Accelerometer Scale Error (ppm)



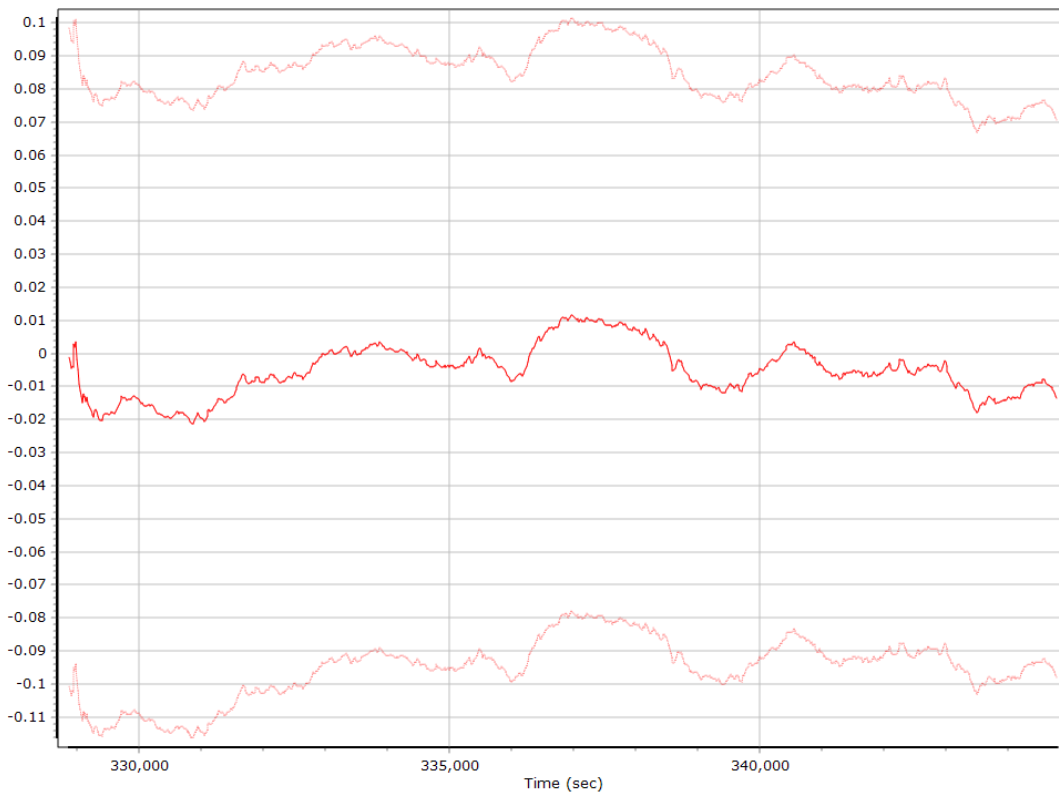
### Z Accelerometer Scale Error (ppm)



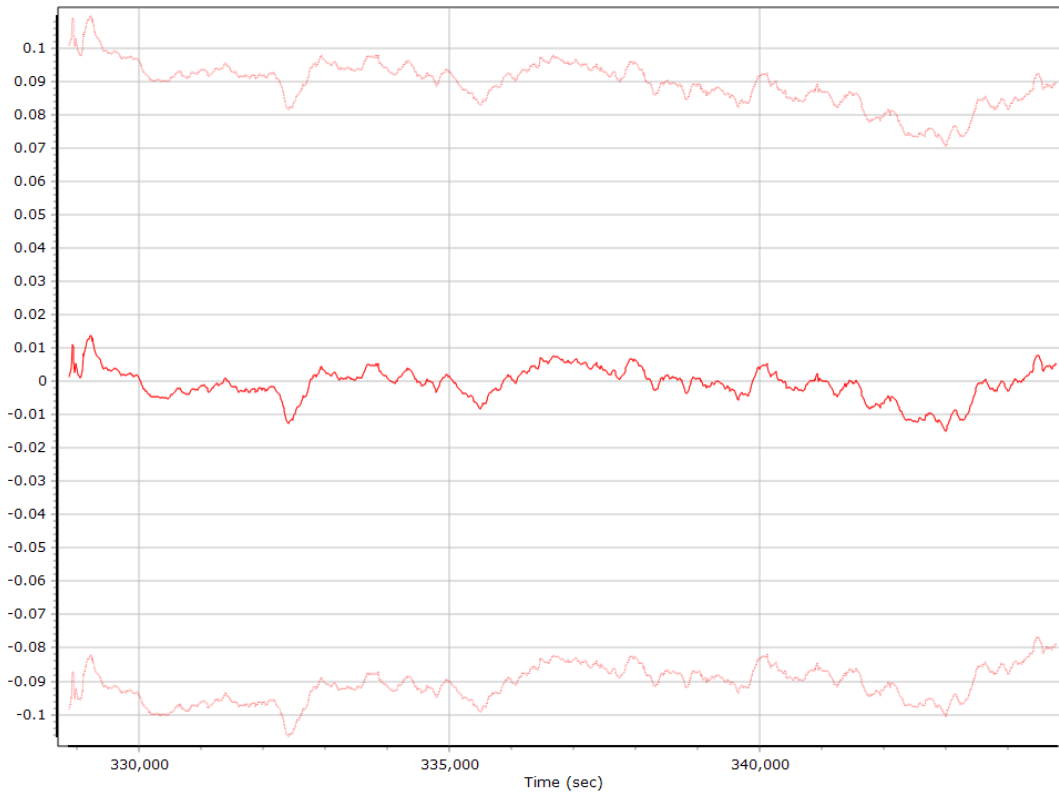
### Gyro Bias (deg/h)



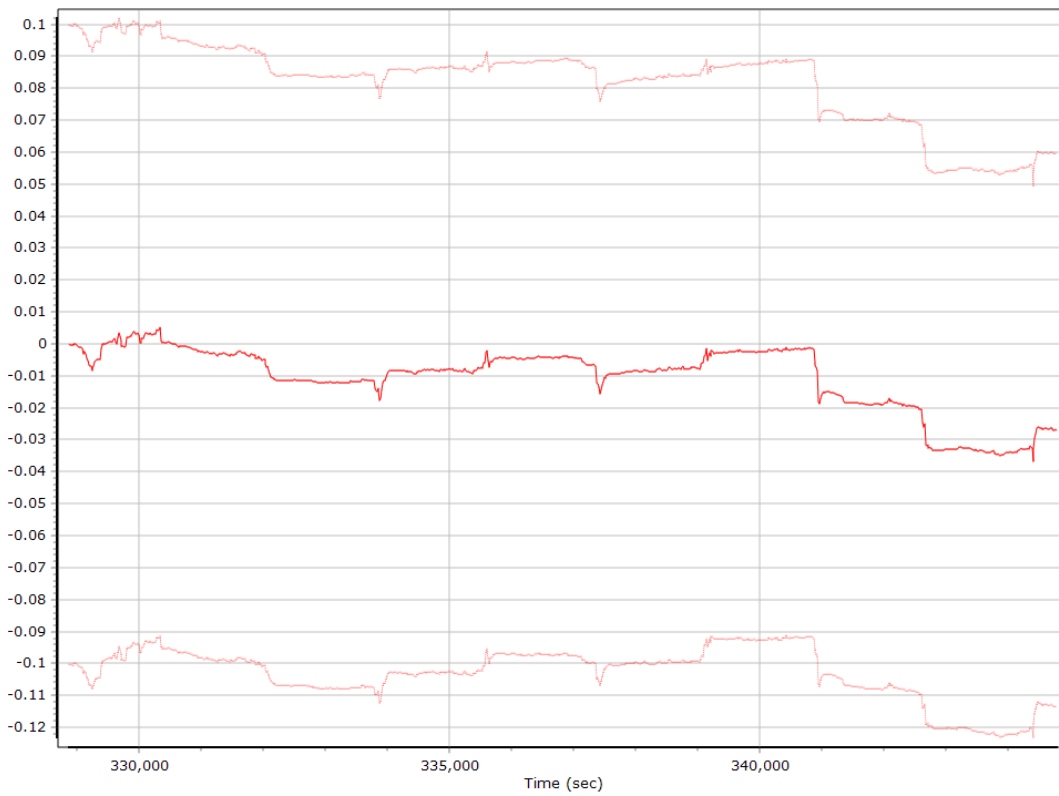
### X Gyro Bias (deg/h)



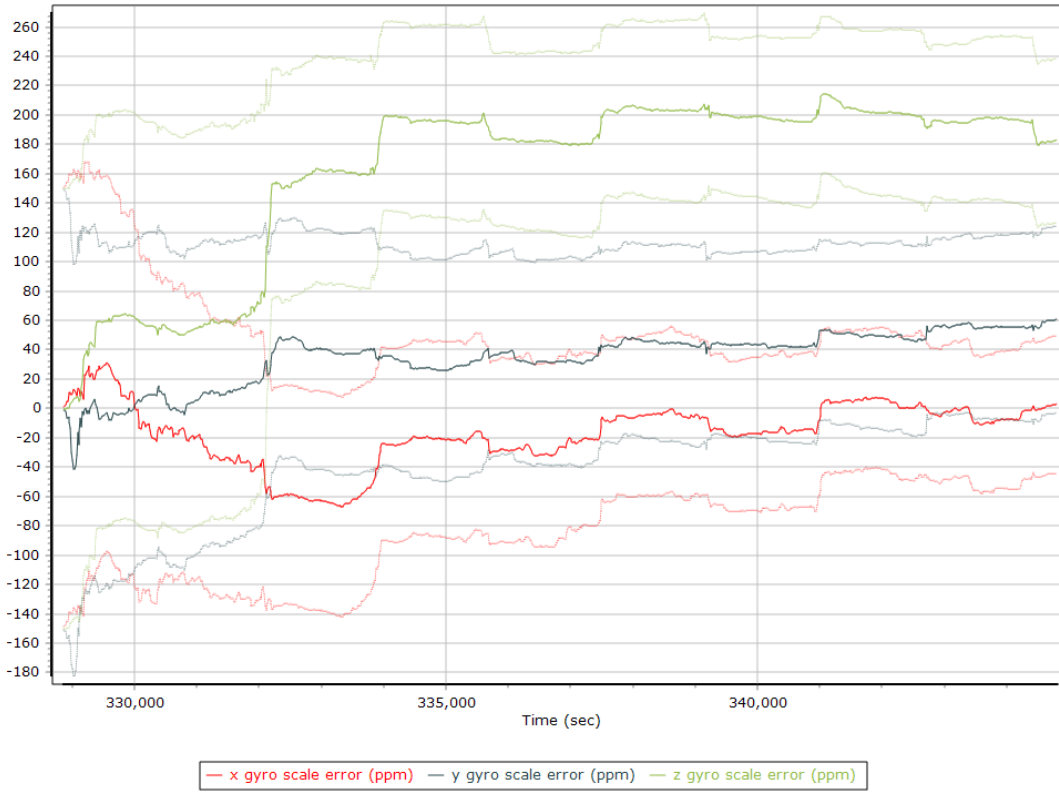
### Y Gyro Bias (deg/h)



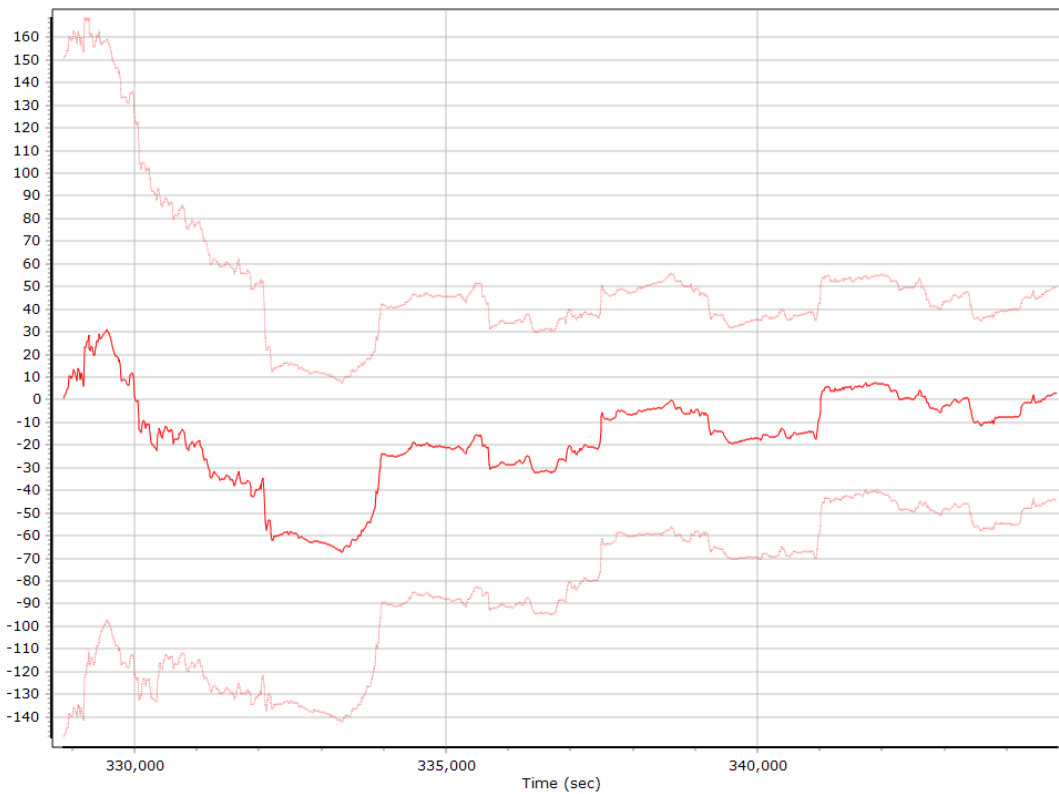
### Z Gyro Bias (deg/h)



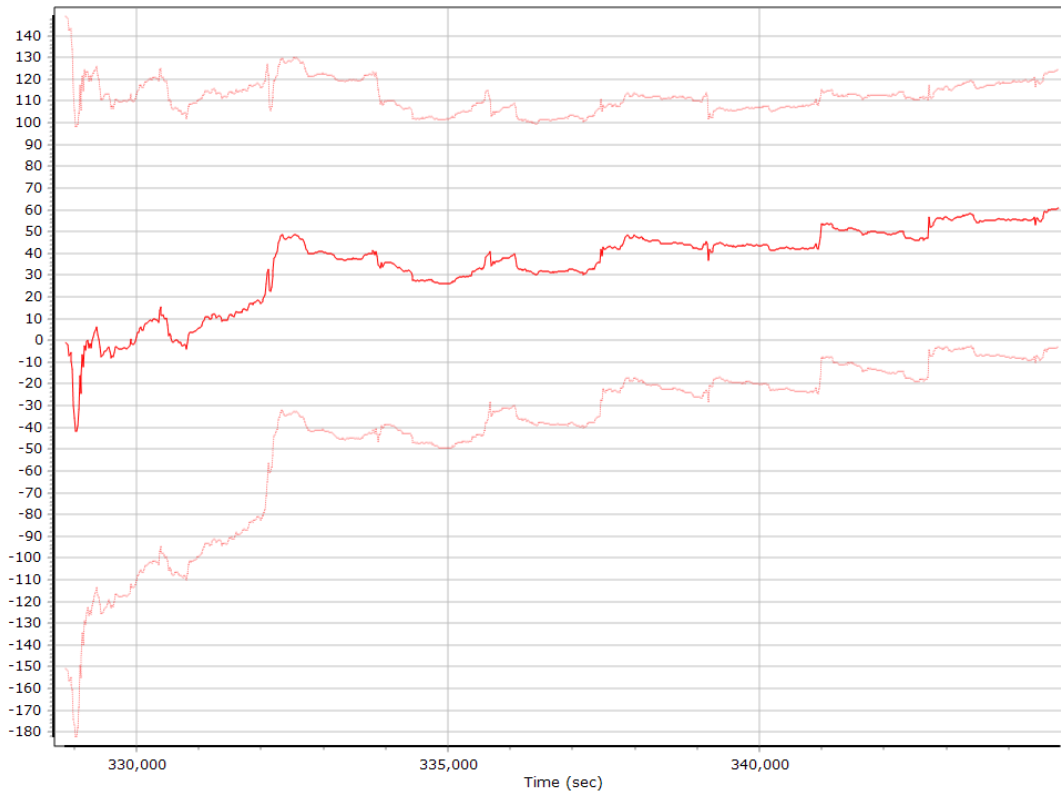
### Gyro Scale Error (ppm)



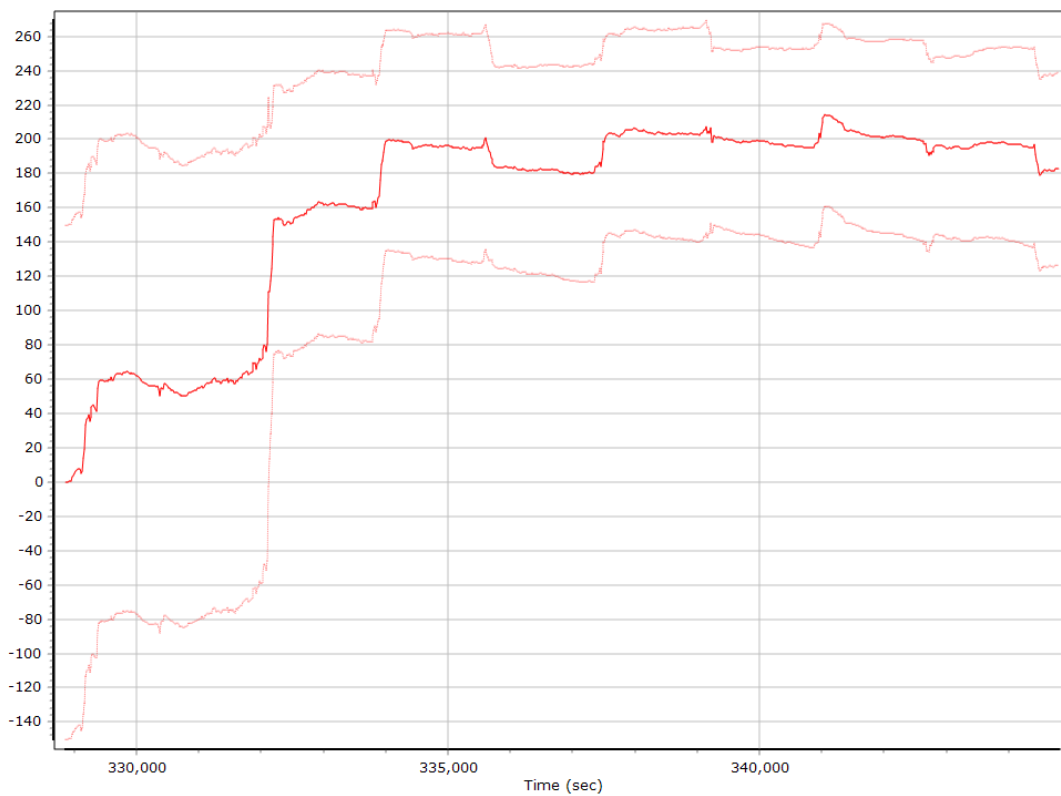
### X Gyro Scale Error (ppm)



### Y Gyro Scale Error (ppm)

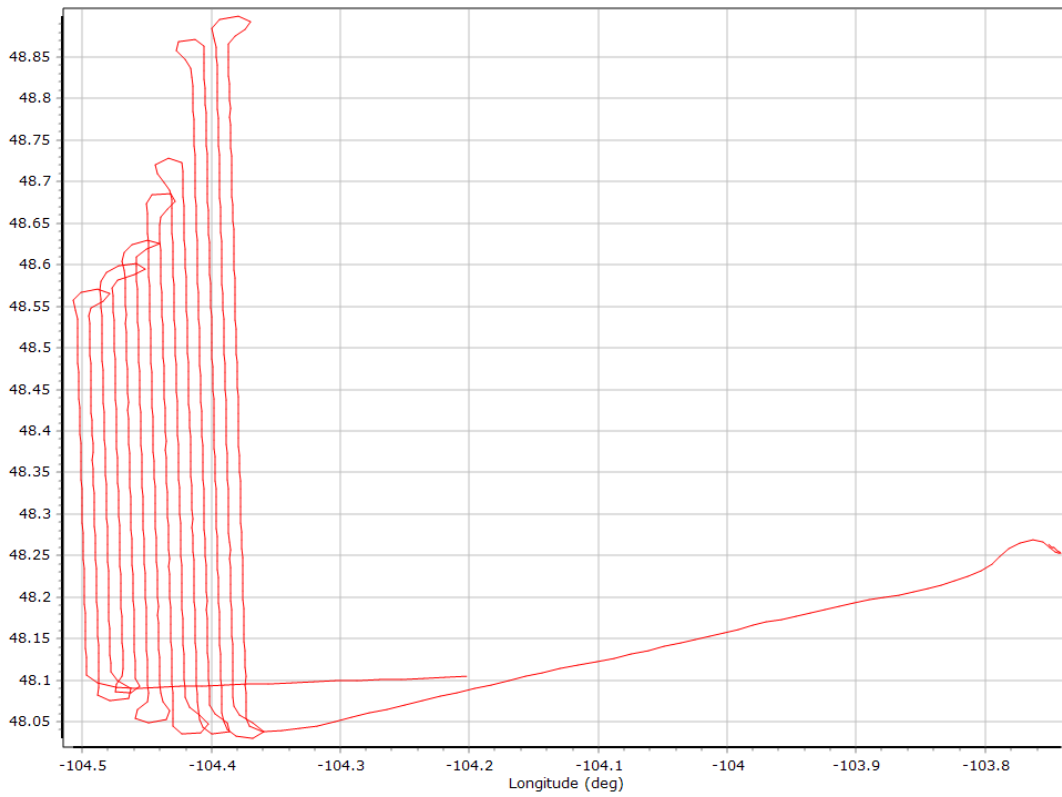


### Z Gyro Scale Error (ppm)

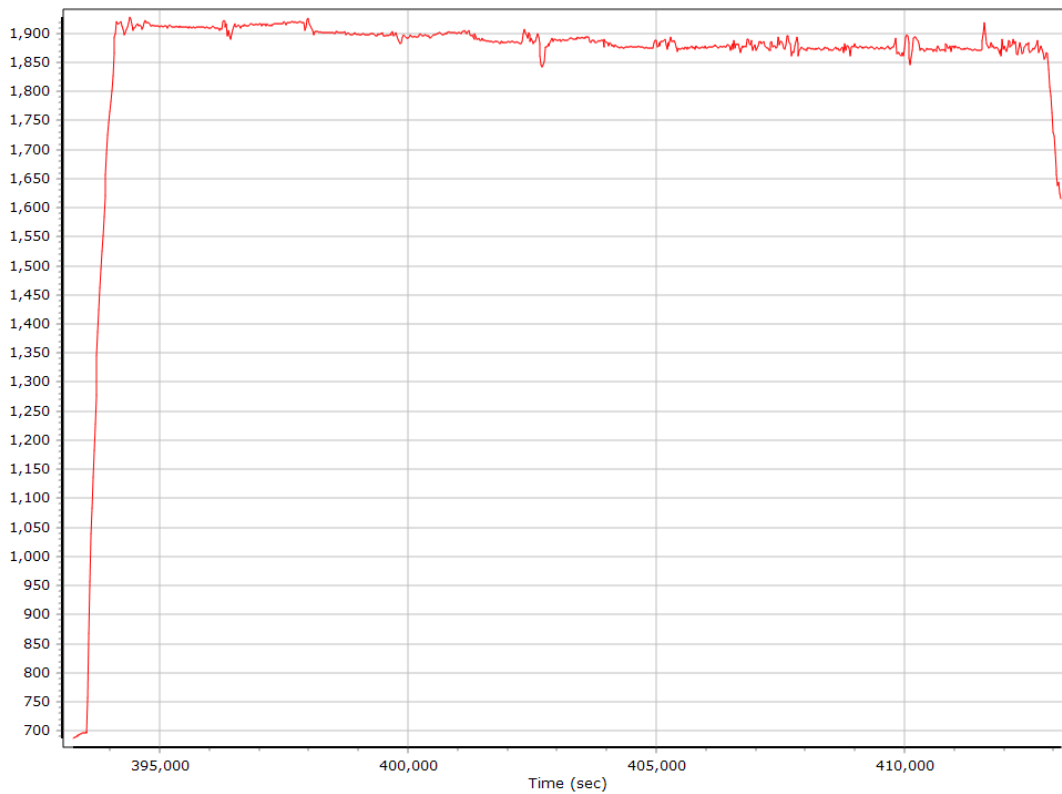


## Smoothed Trajectory Information

### Top View



### Altitude



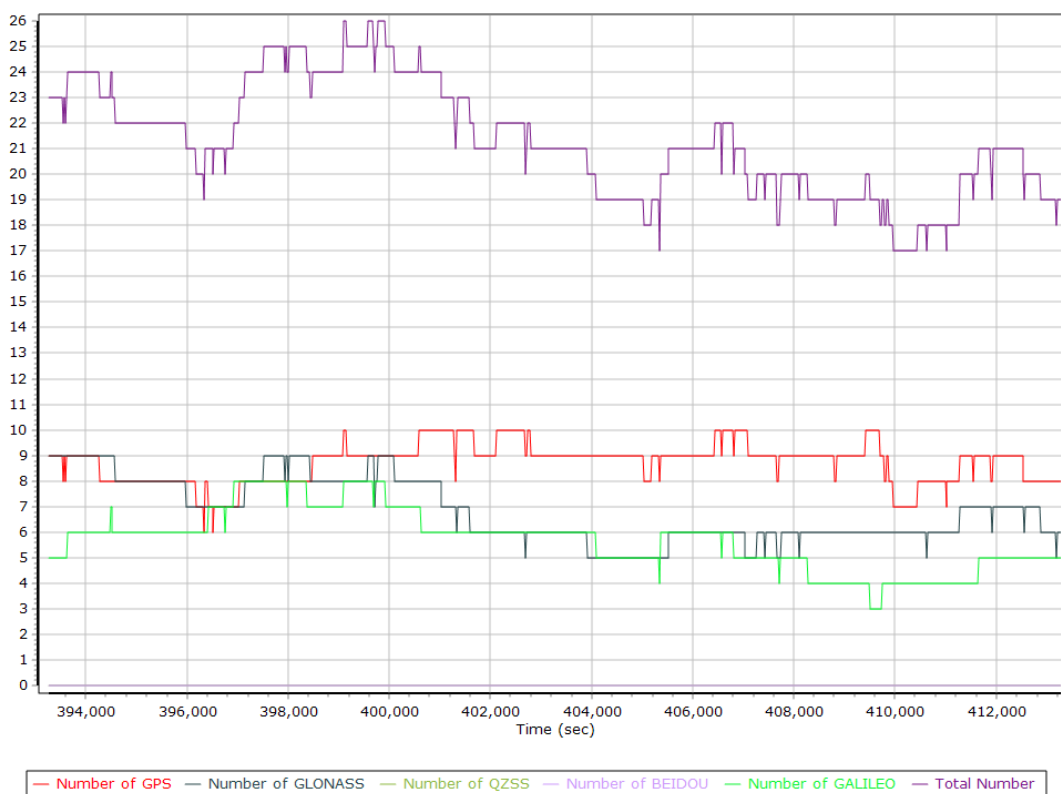


## GNSS QC

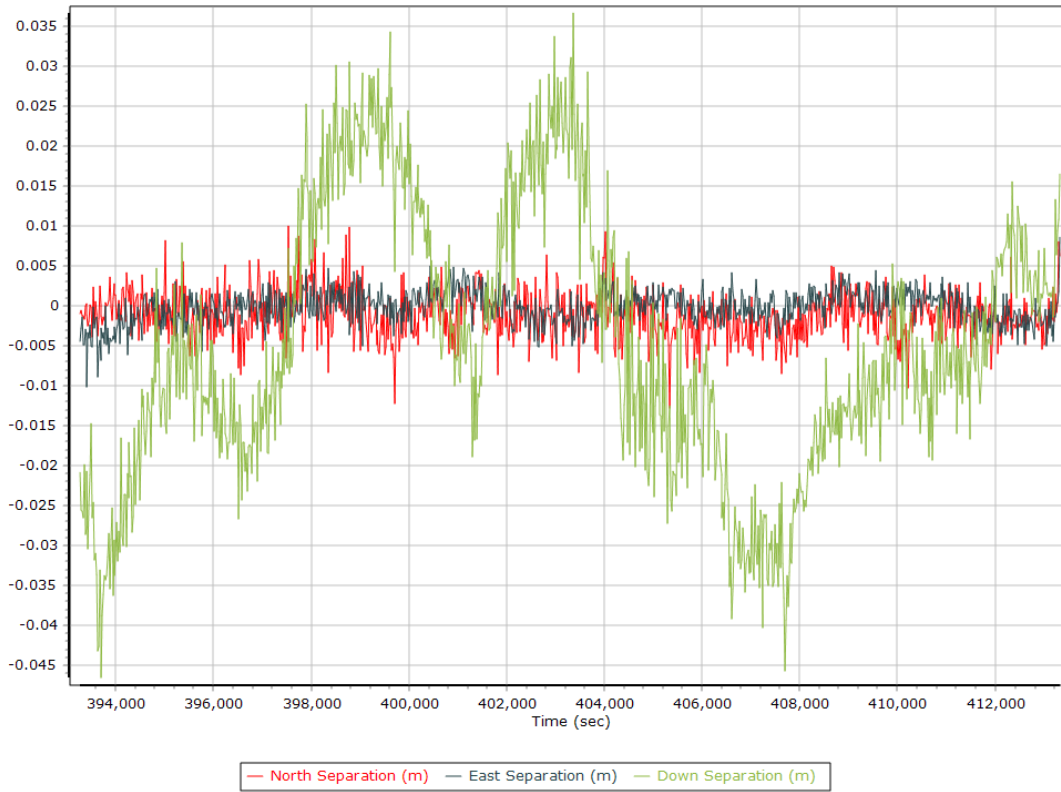
### GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	6	10	9
Number of GLONASS SV	0	9	7
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	0	0
Number of GALILEO SV	3	8	6
Total number of SV	14	26	21
PDOP	0.97	1.61	1.15
QC Solution Gaps	0.00	0.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	20531.00	0.00	0.00
Percentage	100.00	0.00	0.00

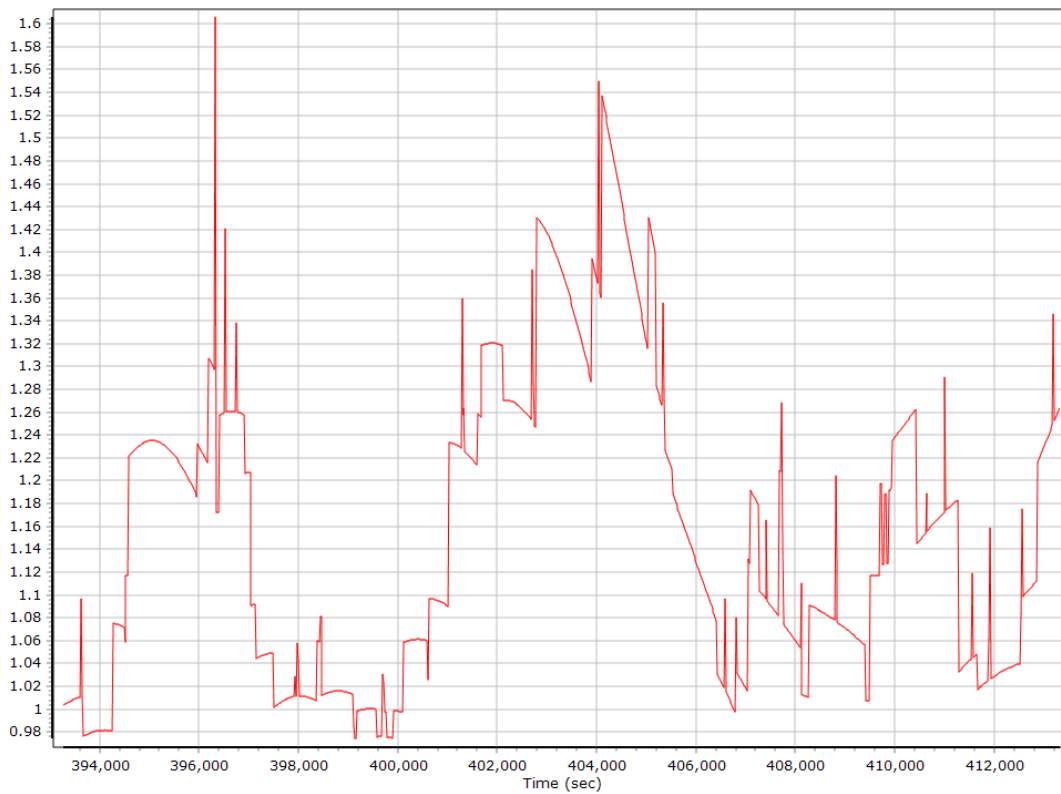
### Num SVs in solution



## Forward/Reverse Separation



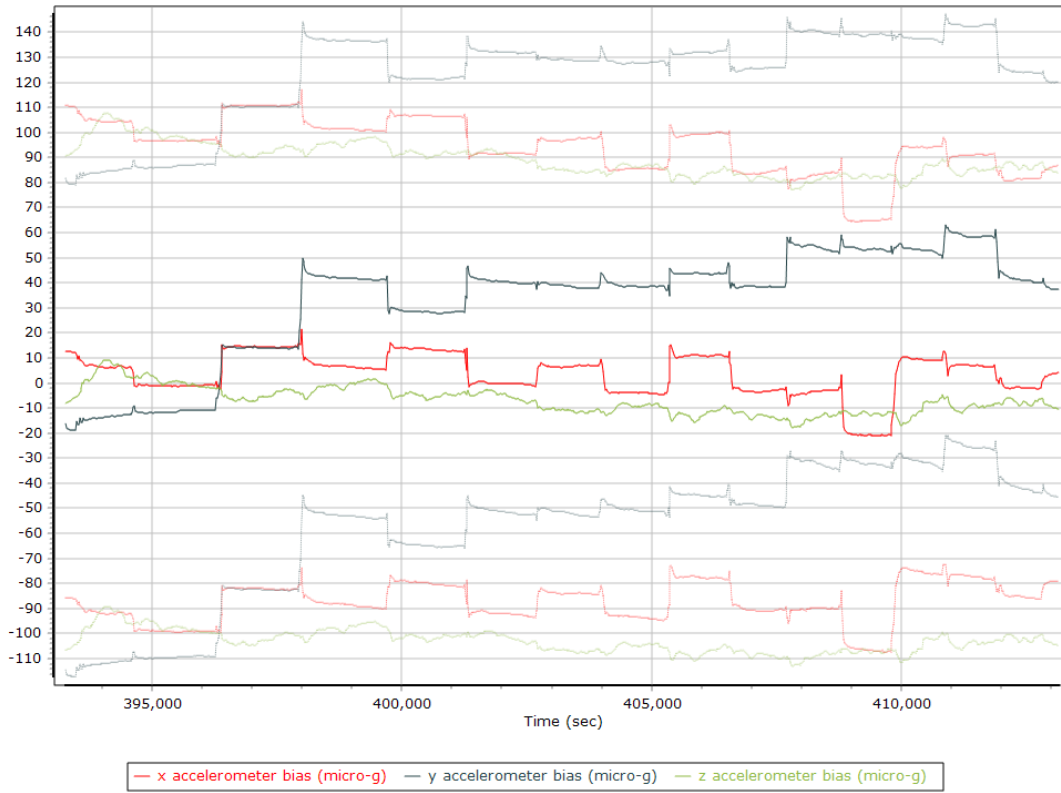
## PDOP



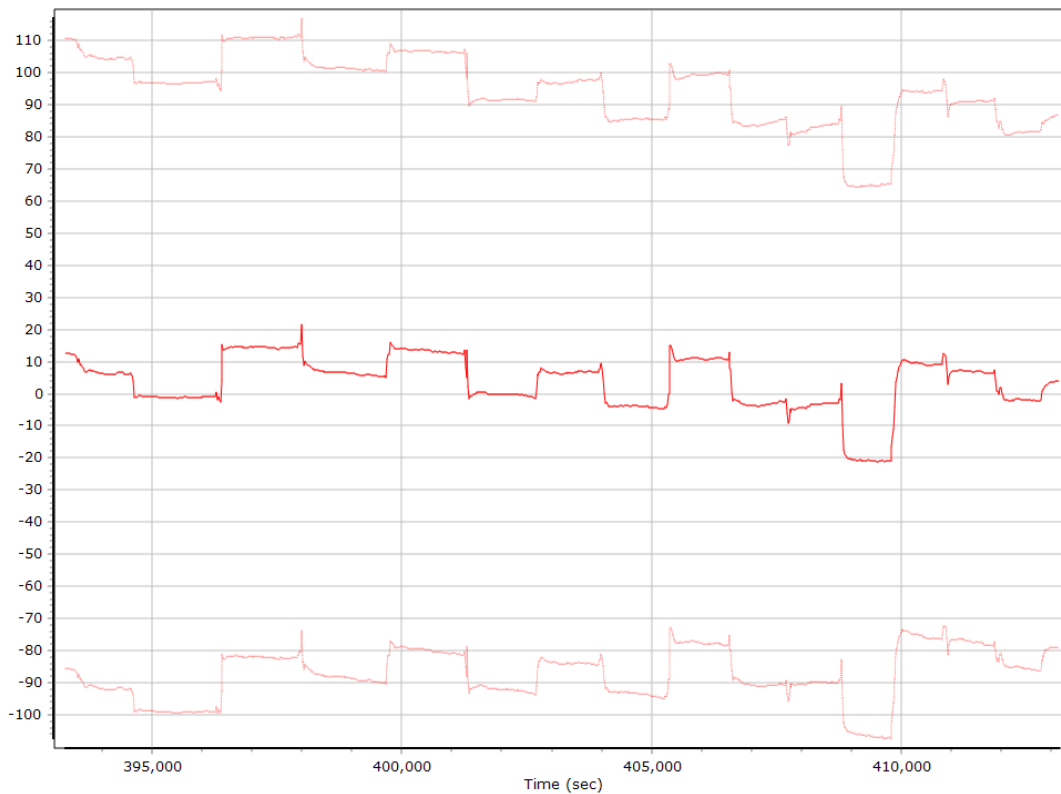
## IN-Fusion QC

### Forward Processed Estimated Errors, Reference Frame

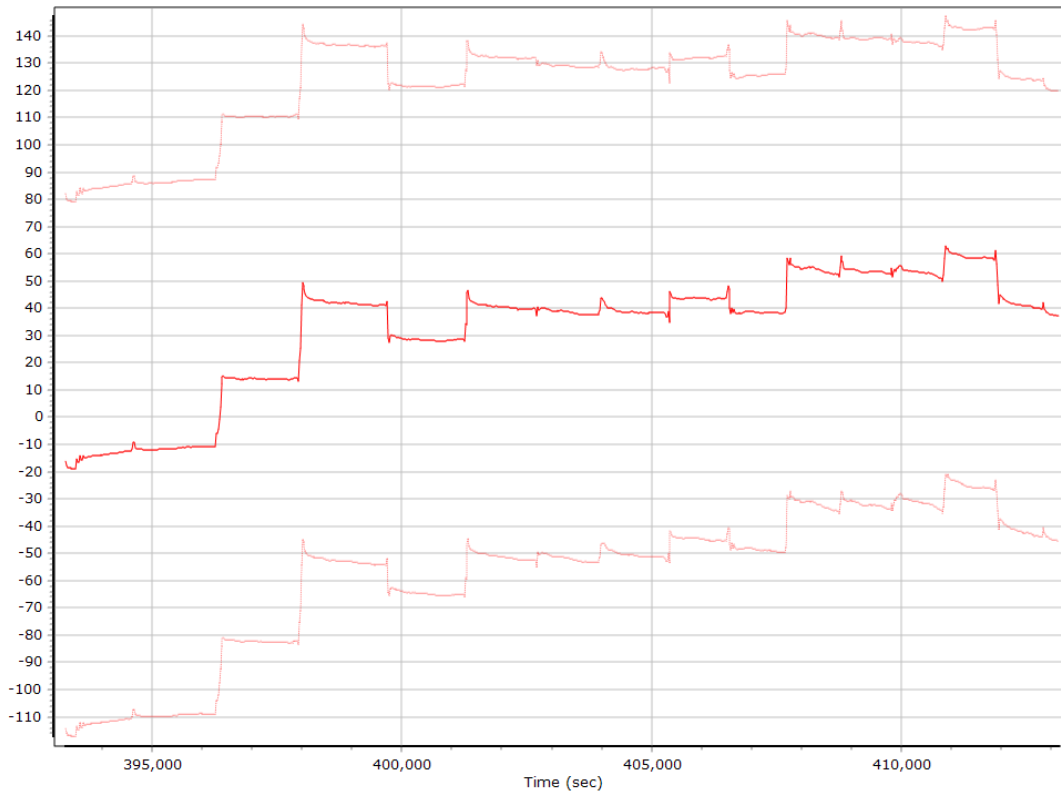
#### Accelerometer Bias (micro-g)



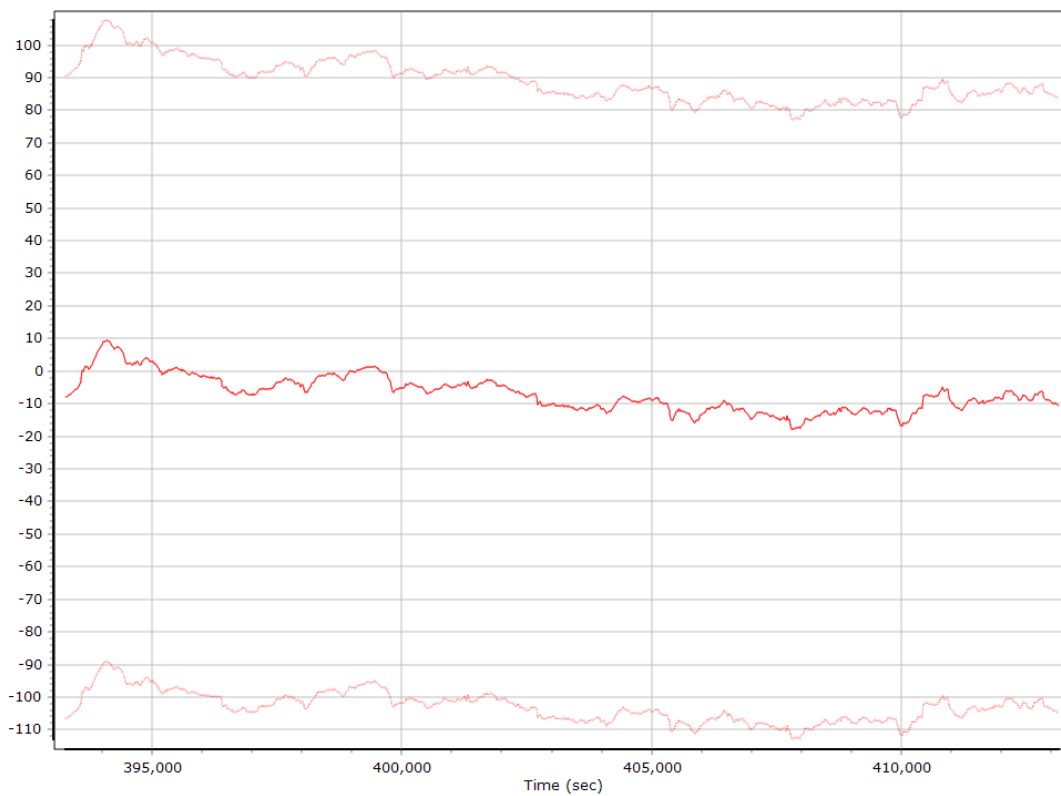
#### X Accelerometer Bias (micro-g)



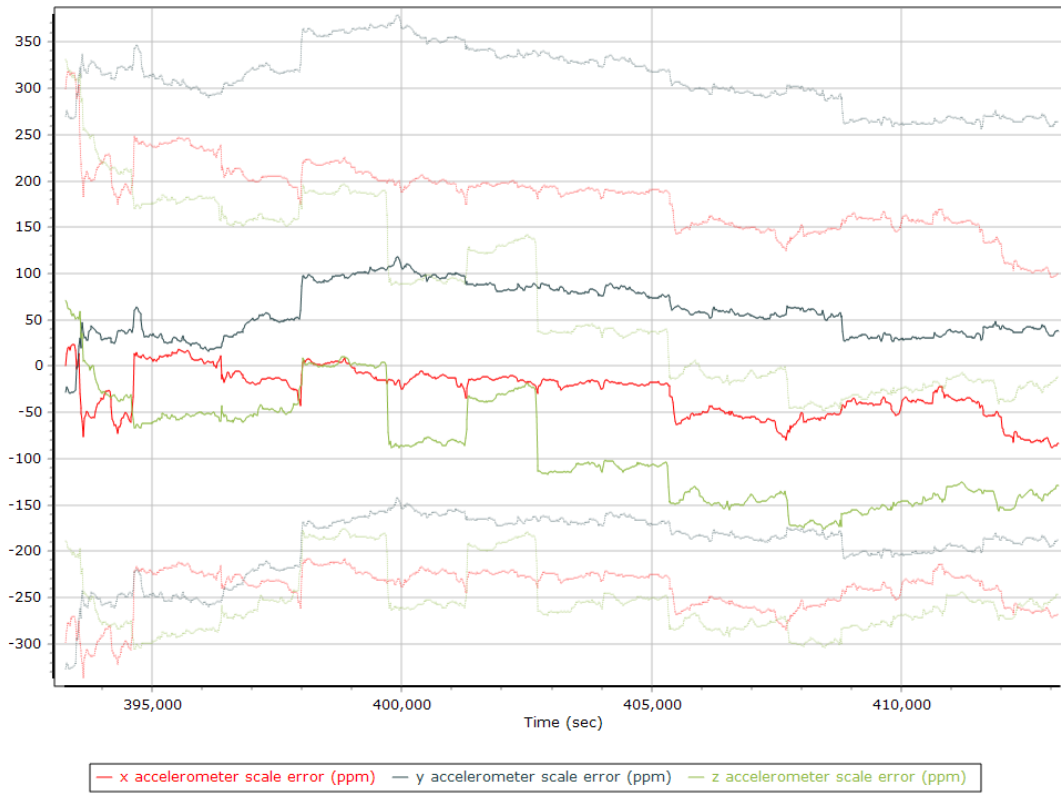
### Y Accelerometer Bias (micro-g)



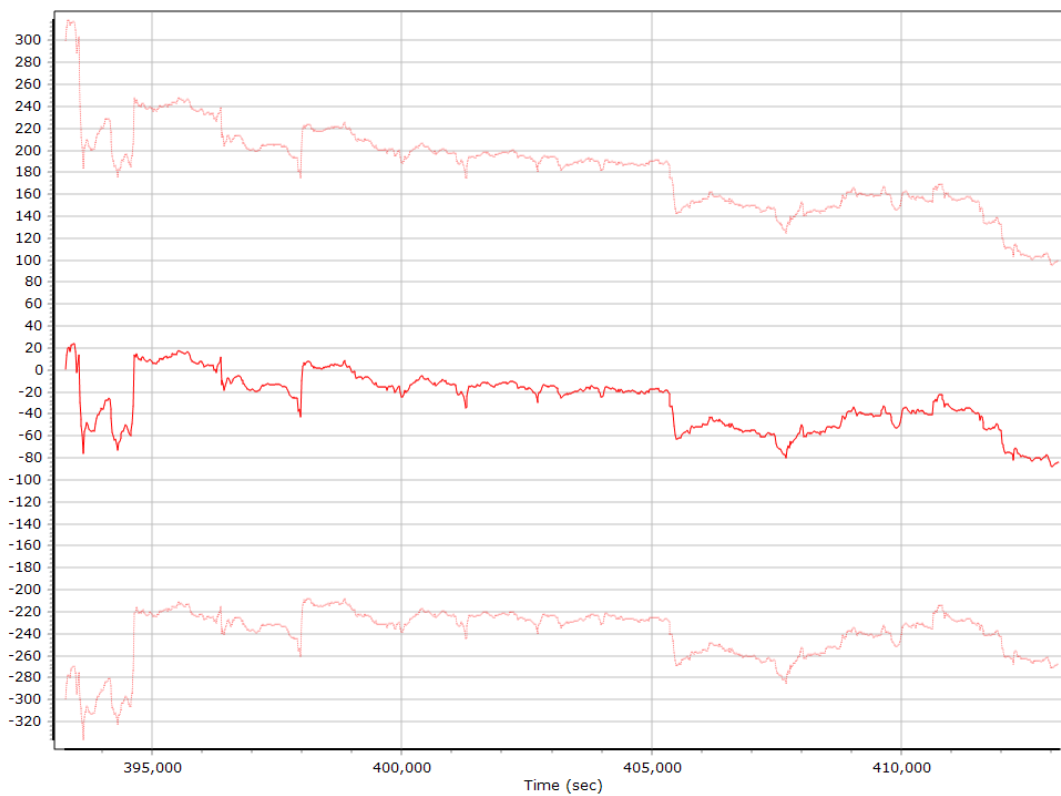
### Z Accelerometer Bias (micro-g)



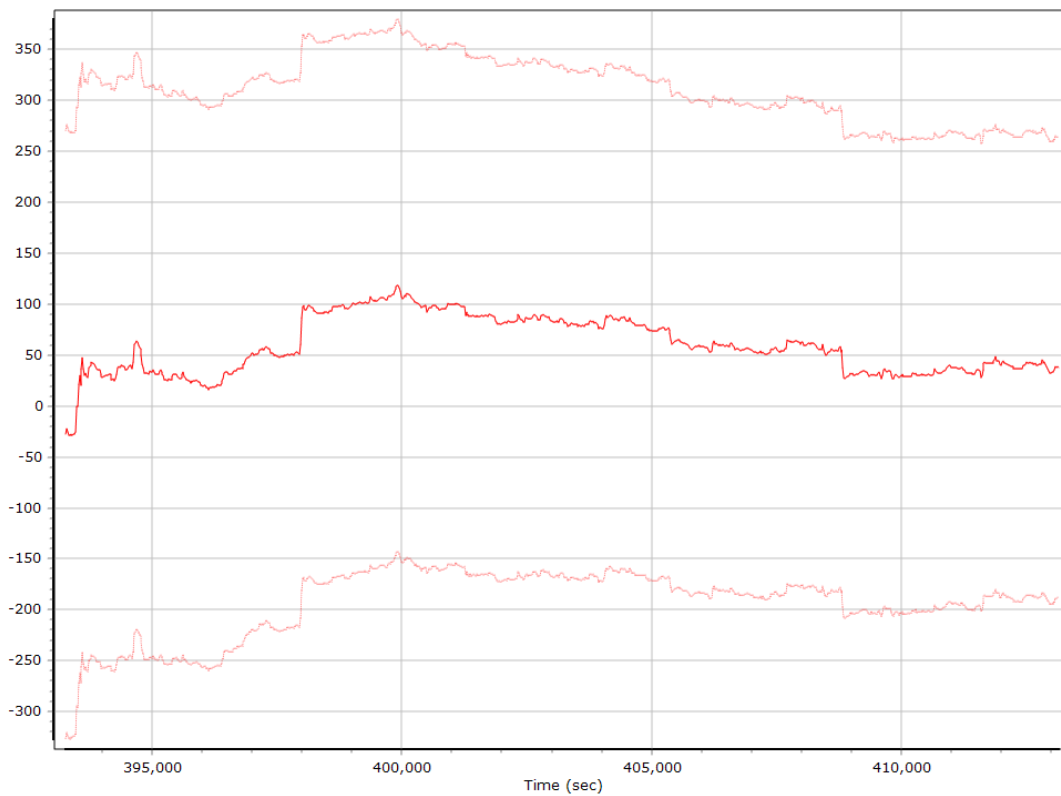
### Accelerometer Scale Error (ppm)



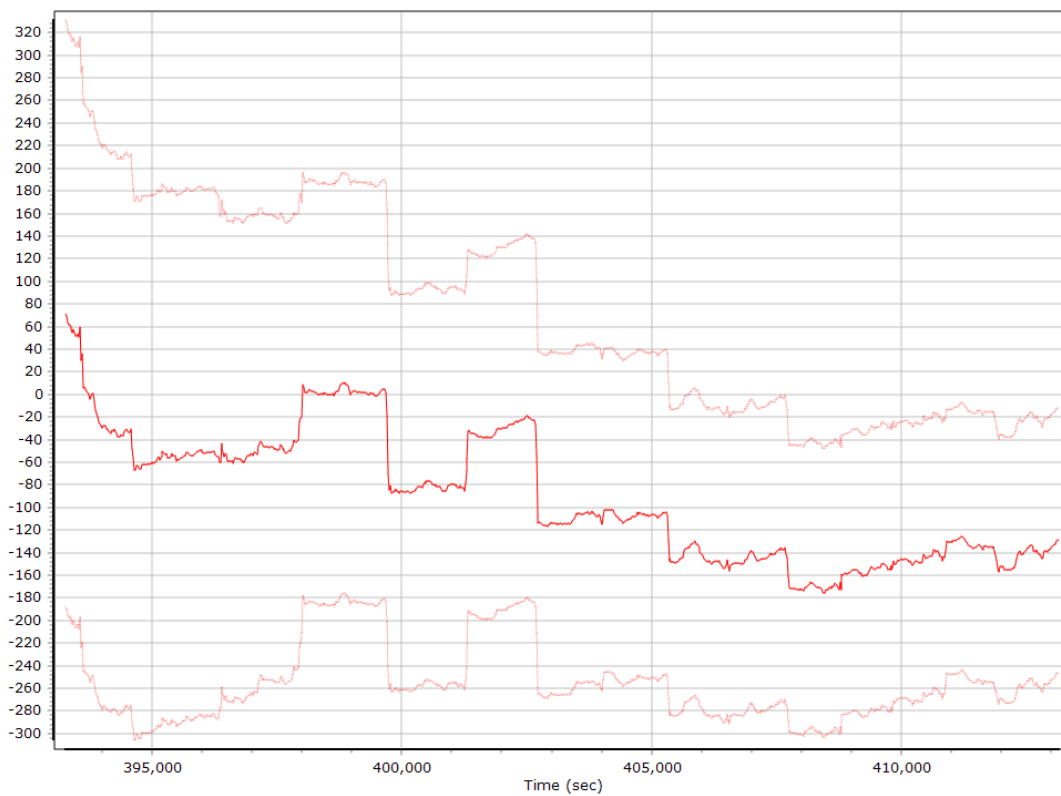
### X Accelerometer Scale Error (ppm)



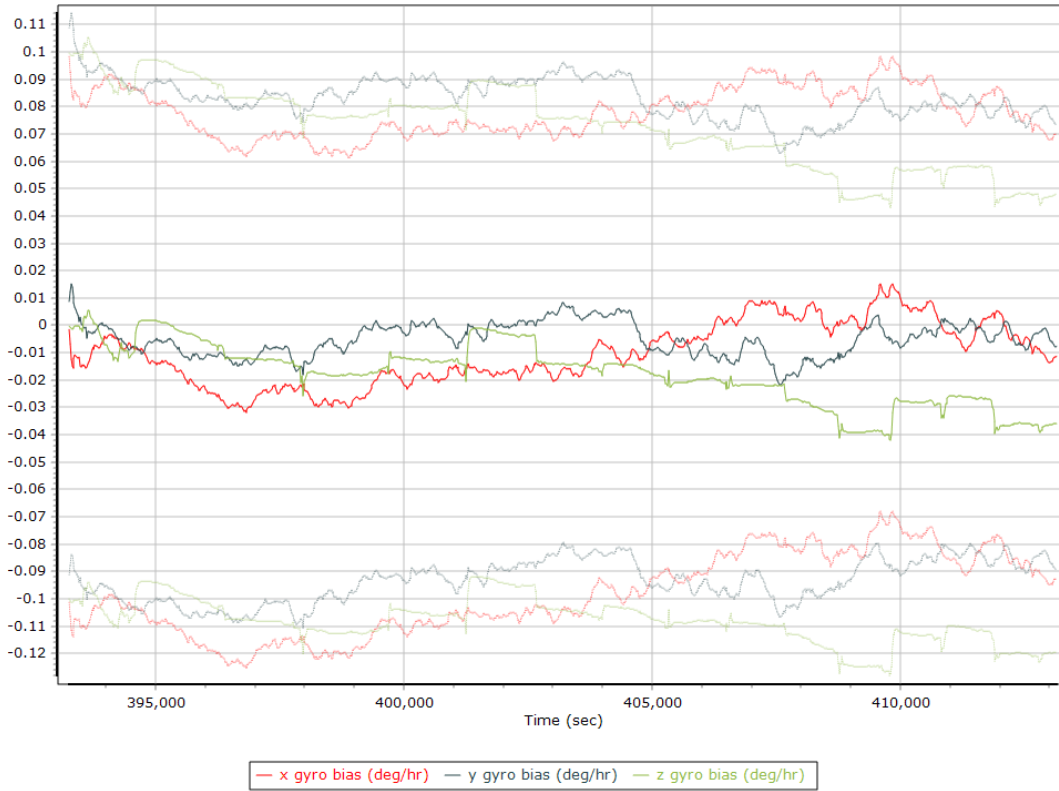
### Y Accelerometer Scale Error (ppm)



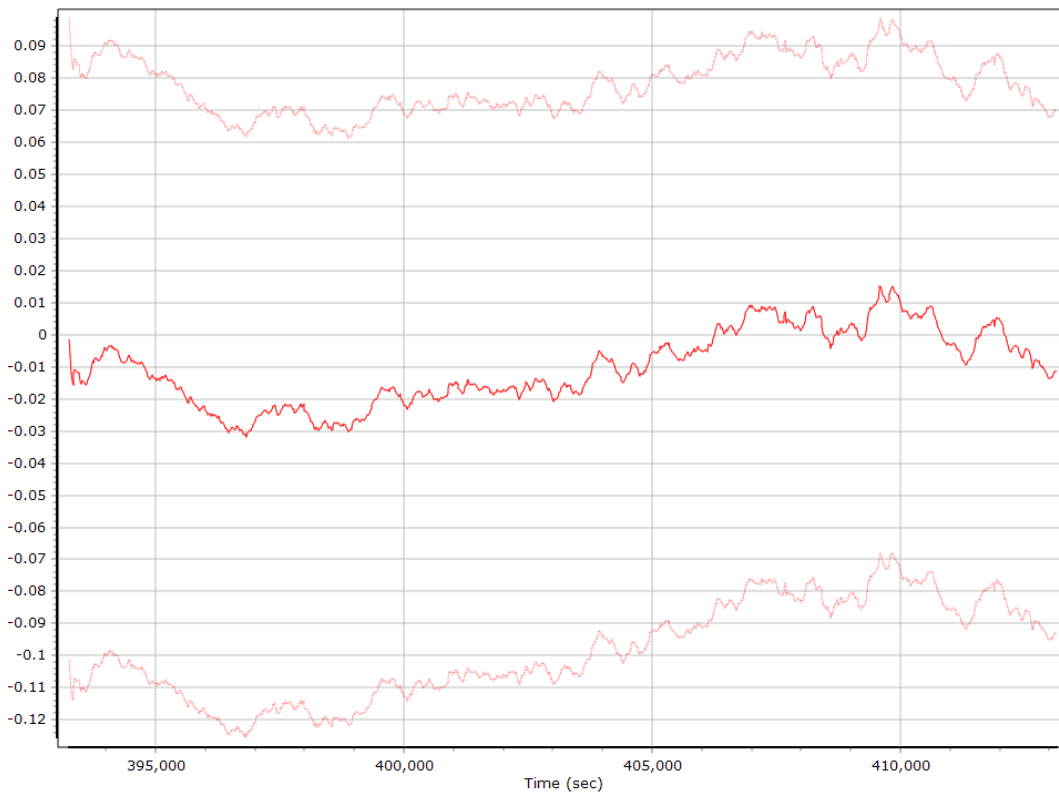
### Z Accelerometer Scale Error (ppm)



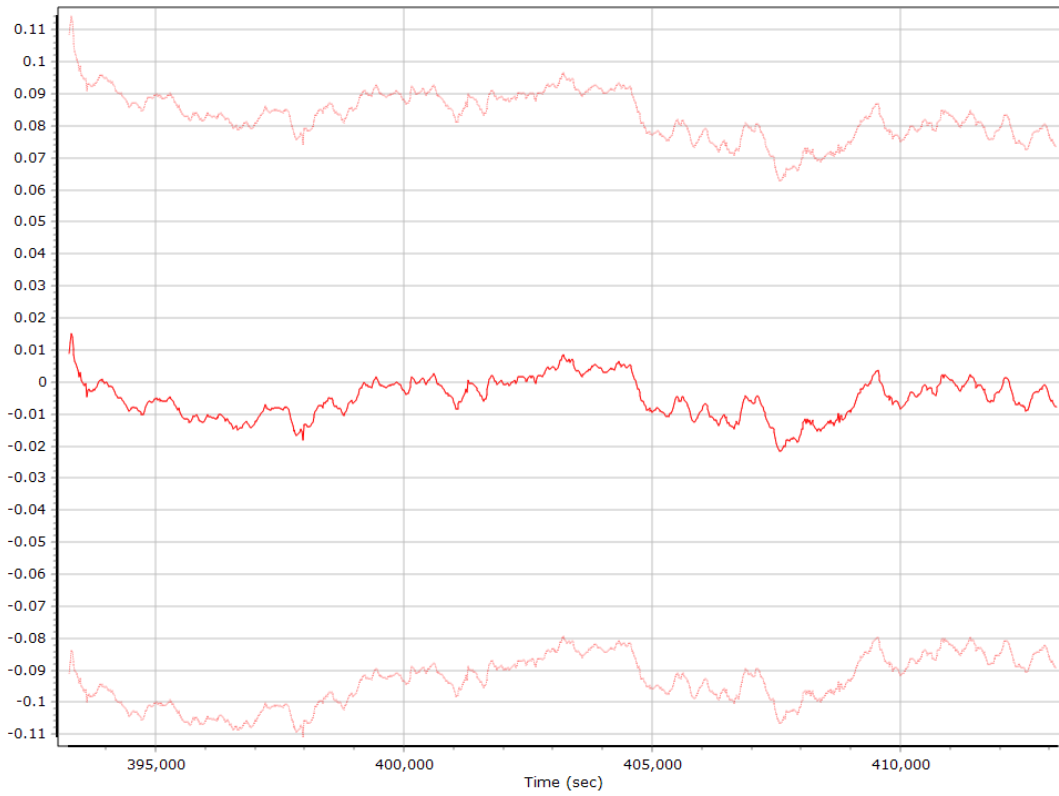
### Gyro Bias (deg/h)



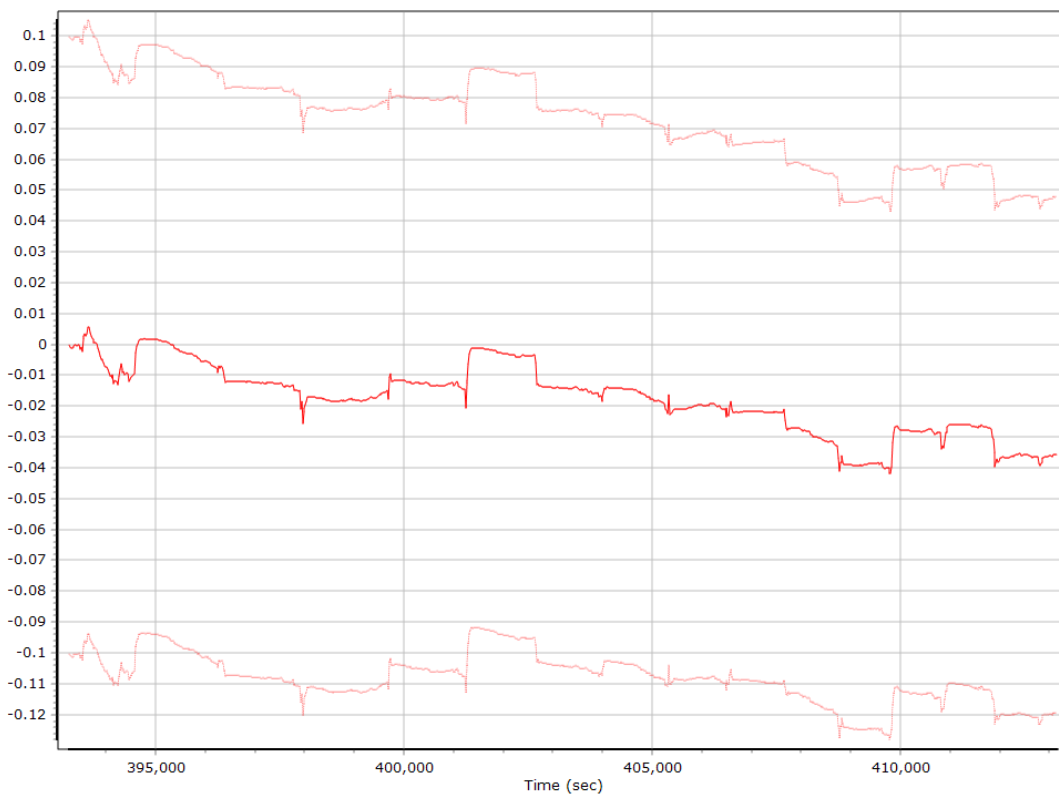
### X Gyro Bias (deg/h)



### Y Gyro Bias (deg/h)



### Z Gyro Bias (deg/h)

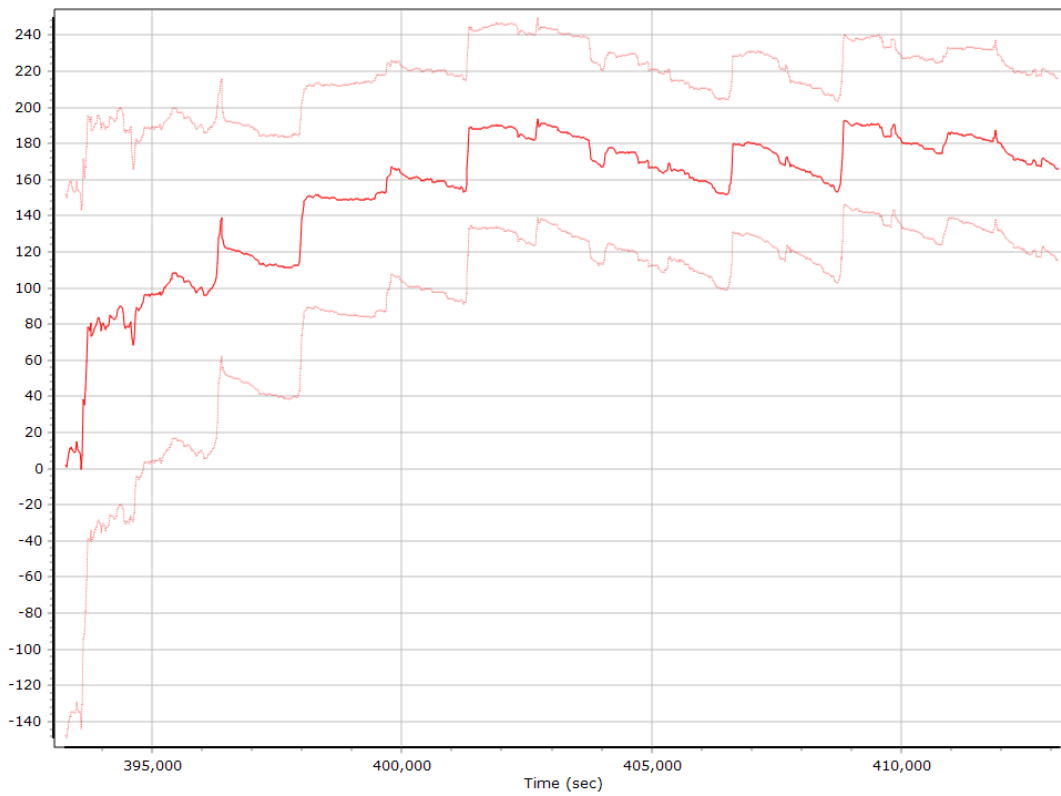




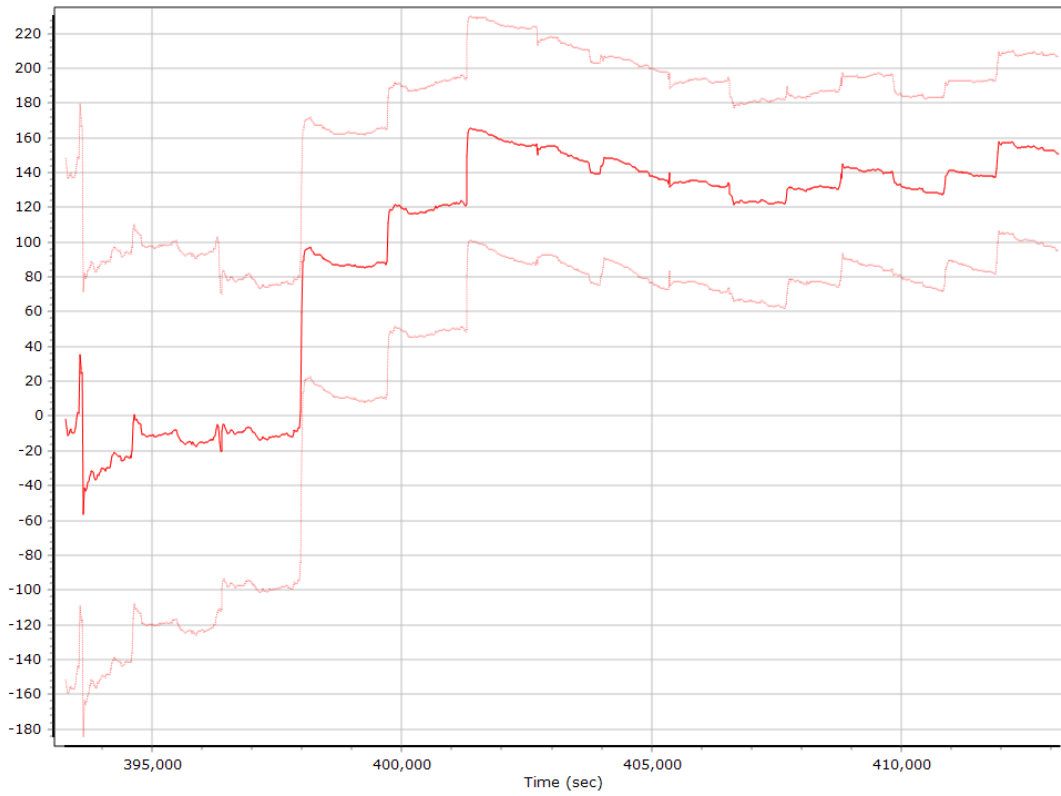
### Gyro Scale Error (ppm)



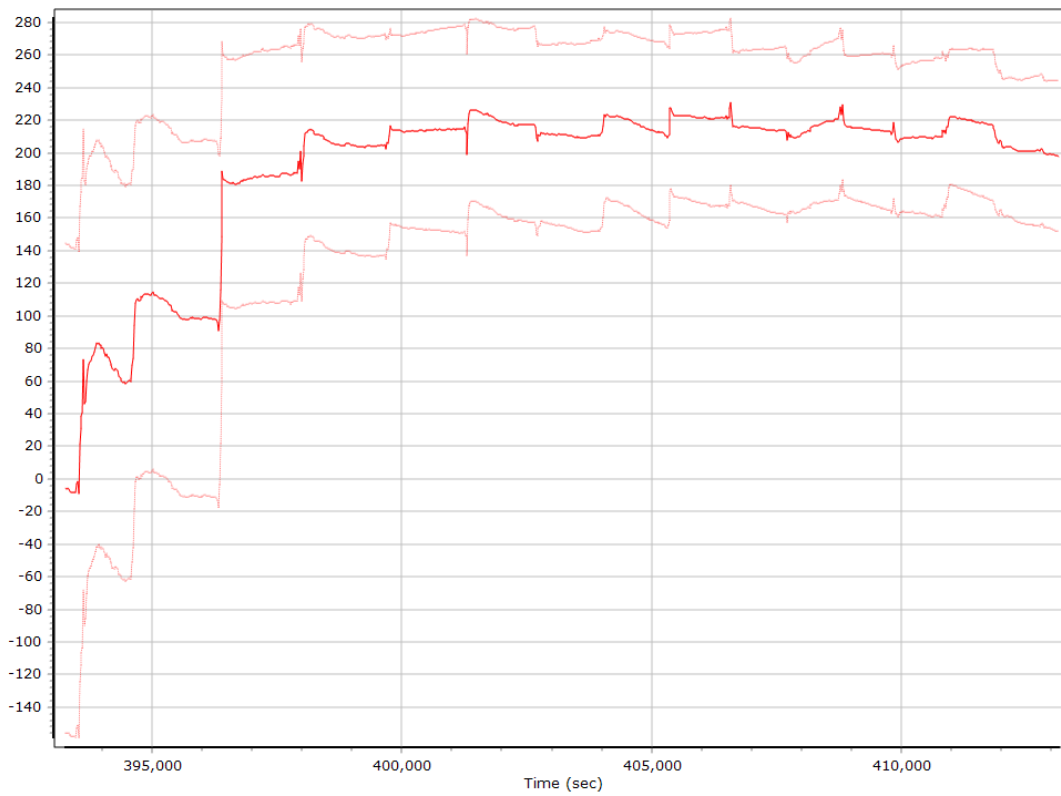
### X Gyro Scale Error (ppm)



### Y Gyro Scale Error (ppm)

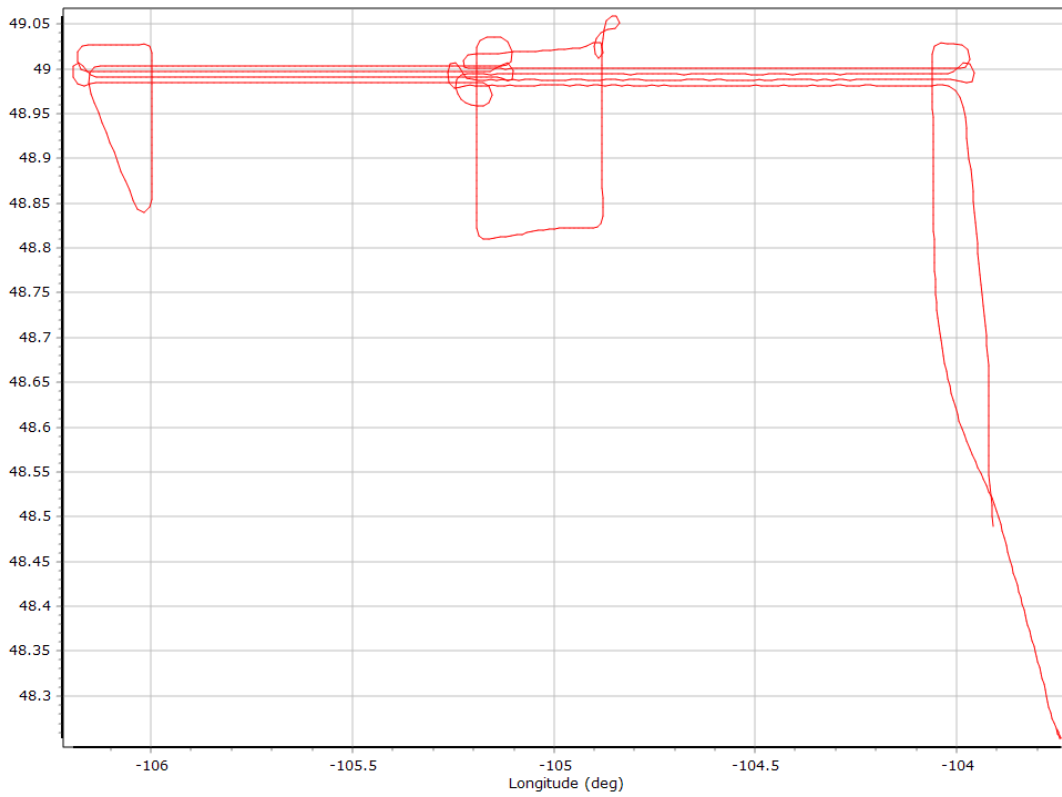


### Z Gyro Scale Error (ppm)

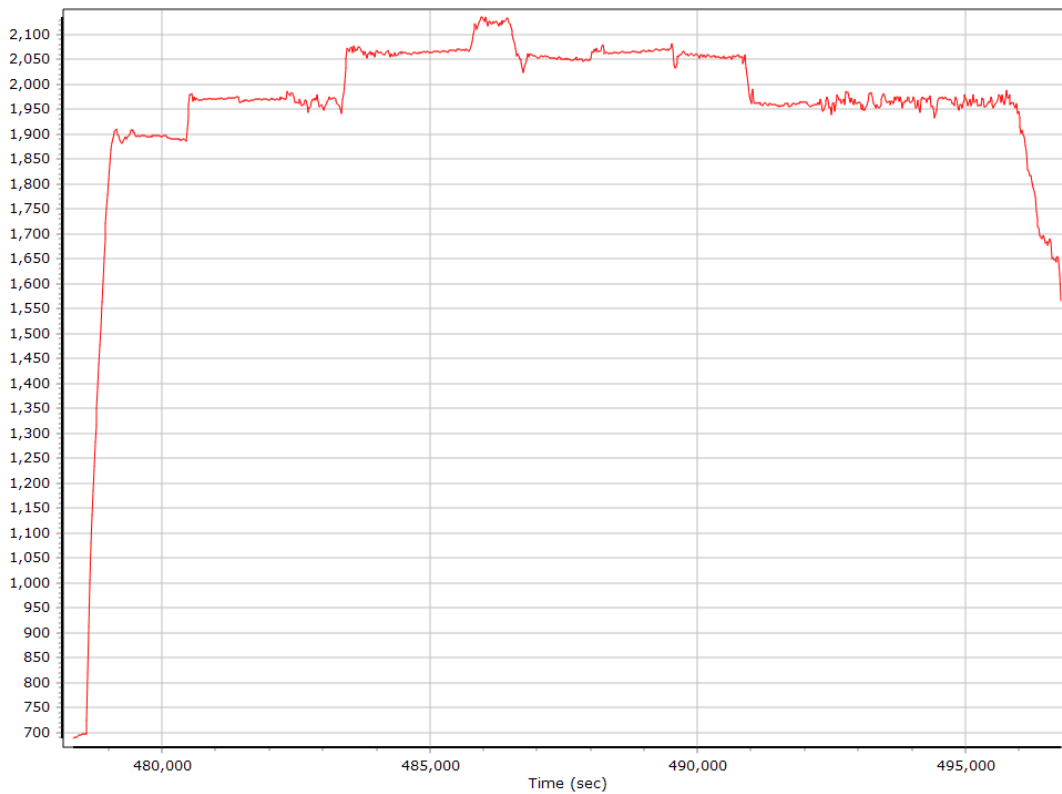


## Smoothed Trajectory Information

### Top View



### Altitude

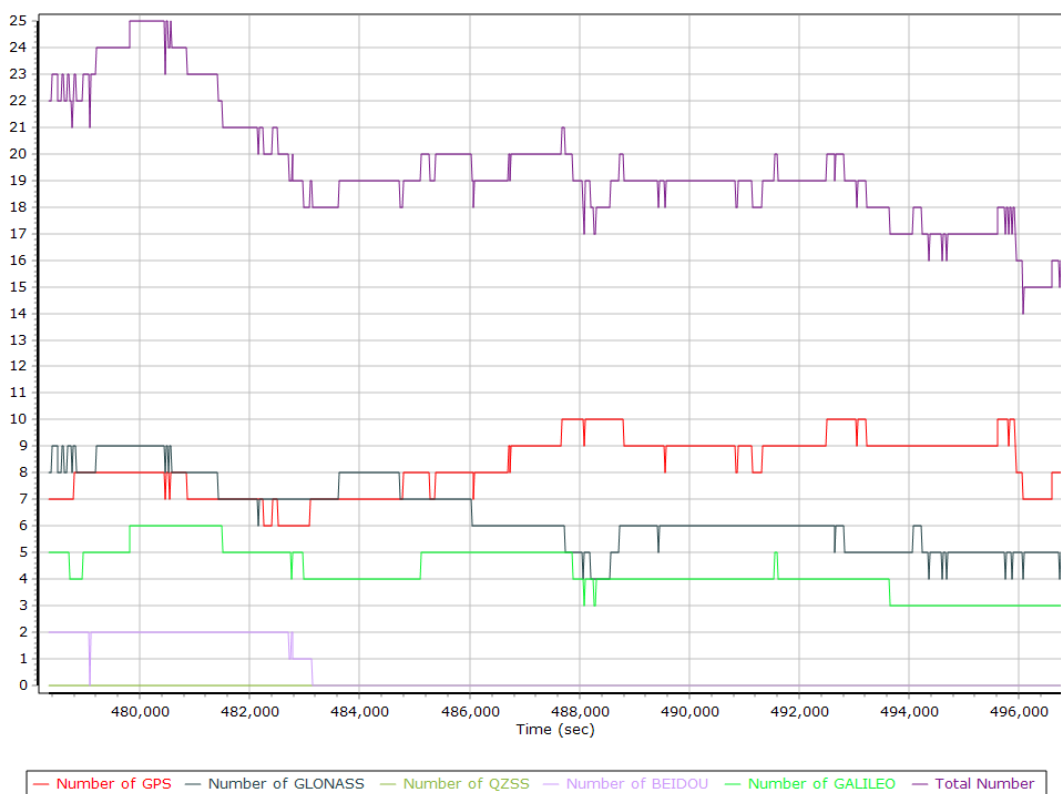


## GNSS QC

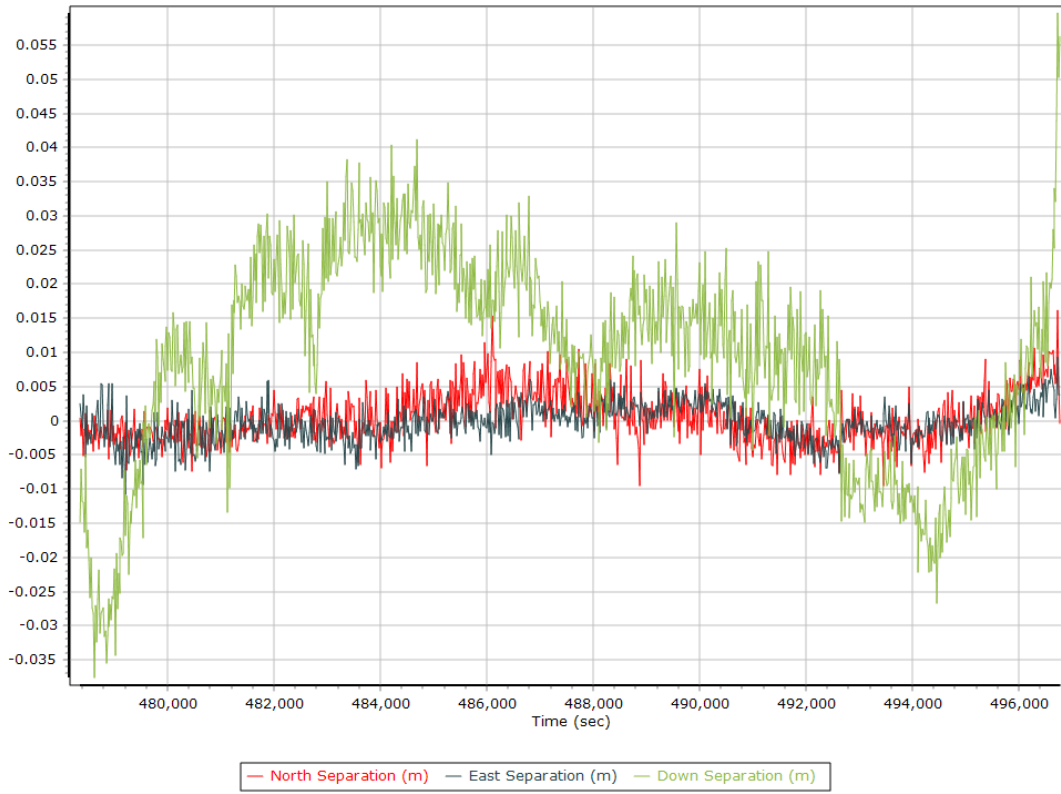
### GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	5	10	8
Number of GLONASS SV	0	9	6
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	2	1
Number of GALILEO SV	3	6	4
Total number of SV	13	25	20
PDOP	1.02	1.73	1.22
QC Solution Gaps	0.00	0.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	18540.00	0.00	0.00
Percentage	100.00	0.00	0.00

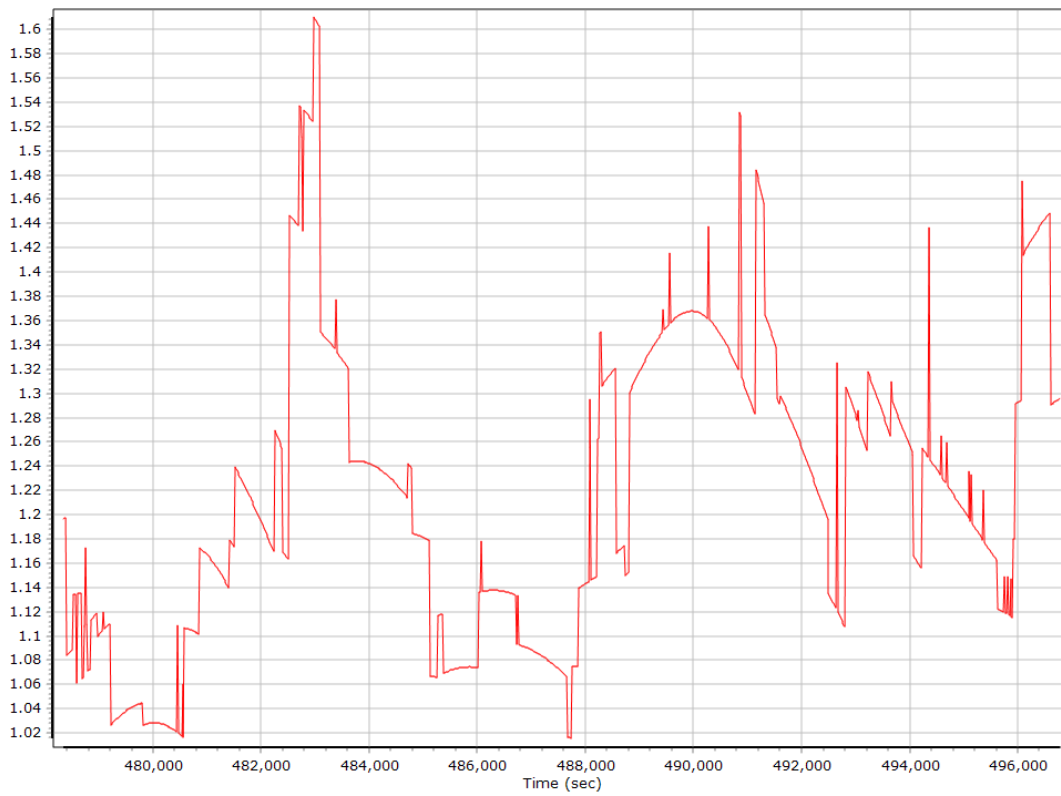
### Num SVs in solution



## Forward/Reverse Separation



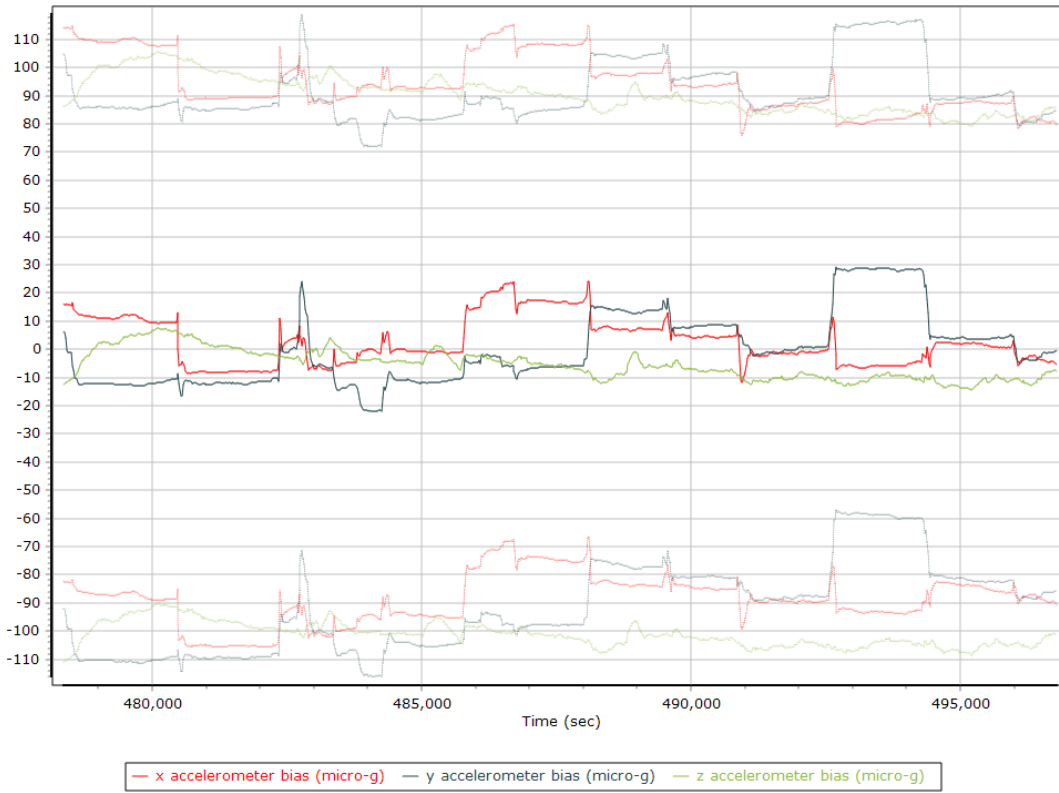
## PDOP



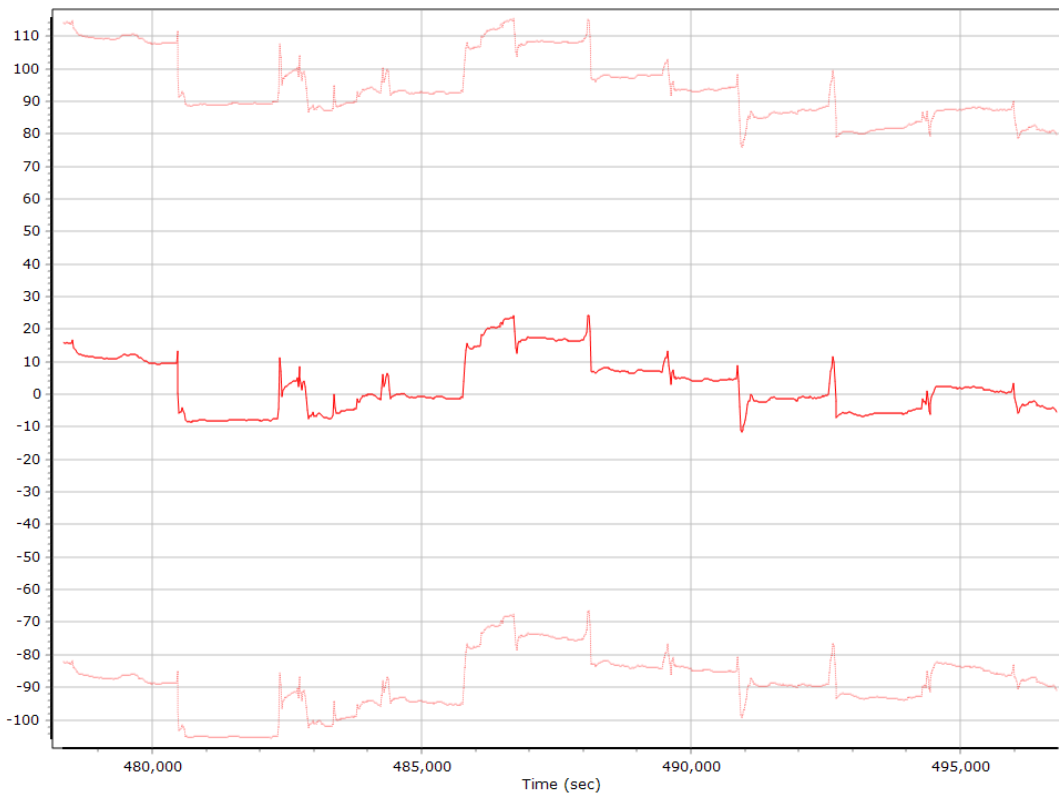
## IN-Fusion QC

### Forward Processed Estimated Errors, Reference Frame

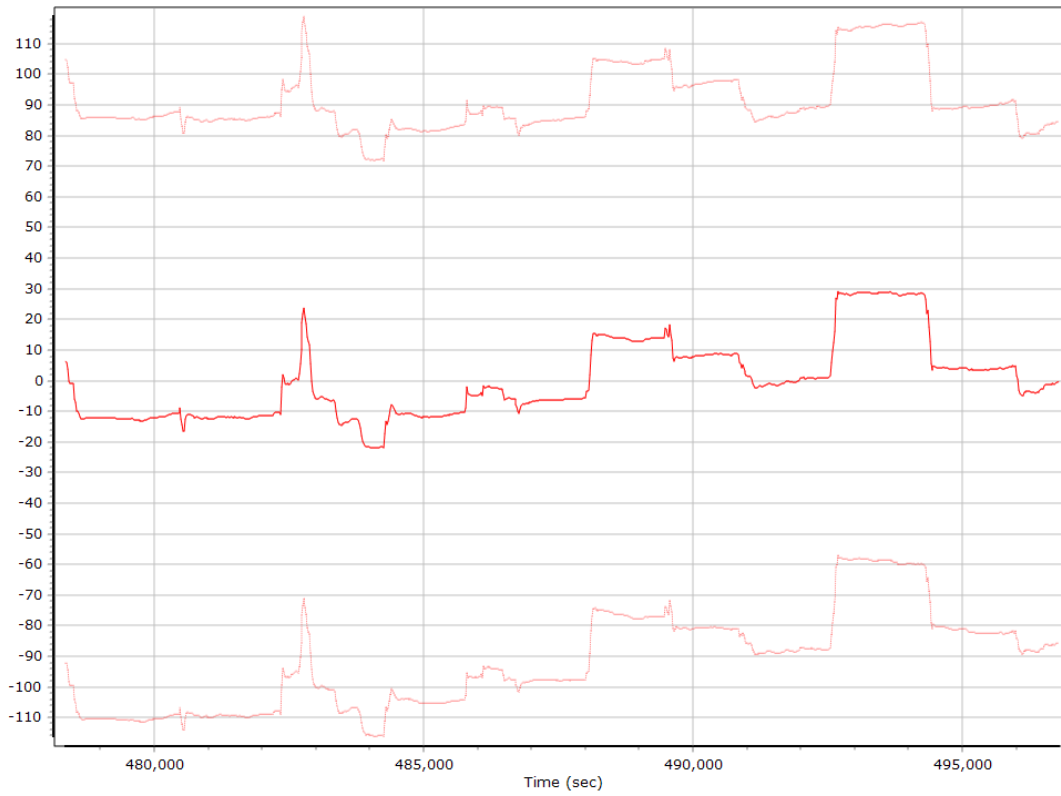
#### Accelerometer Bias (micro-g)



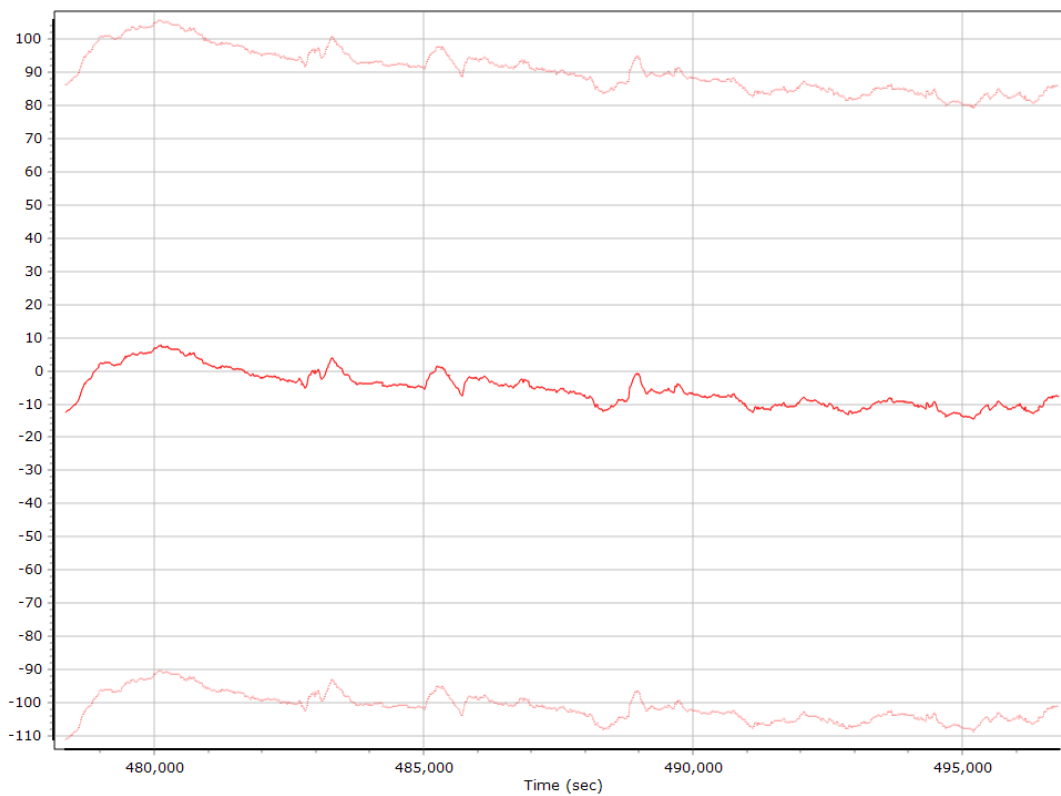
#### X Accelerometer Bias (micro-g)



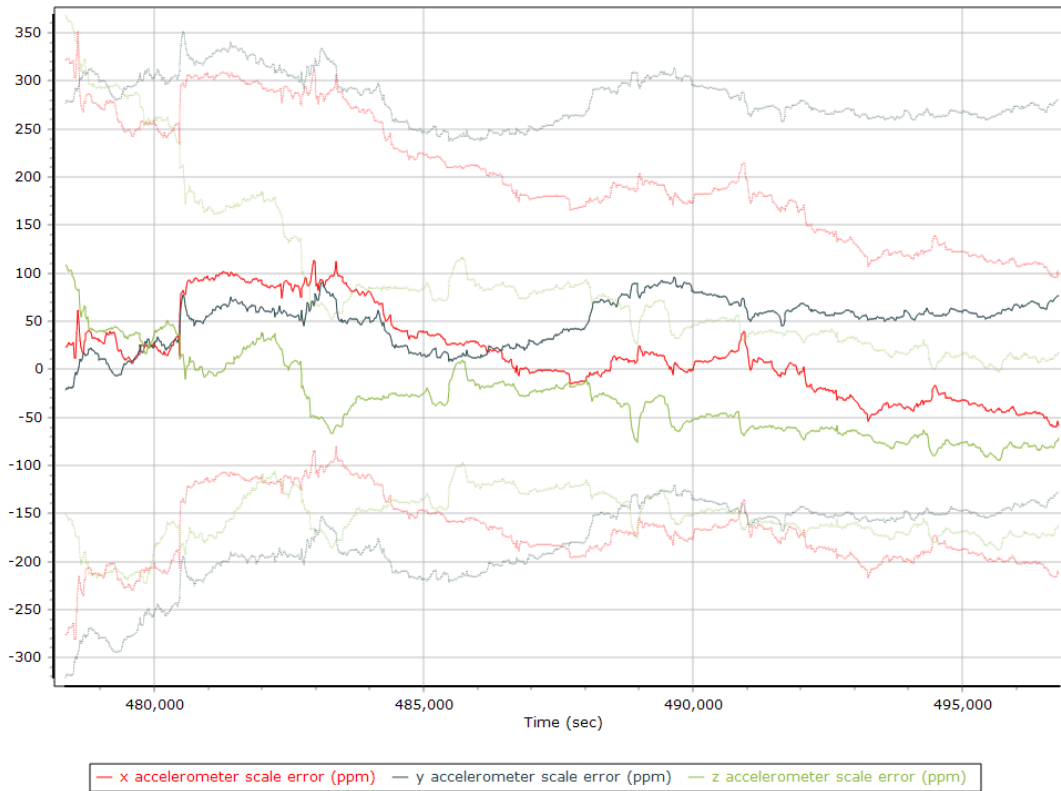
### Y Accelerometer Bias (micro-g)



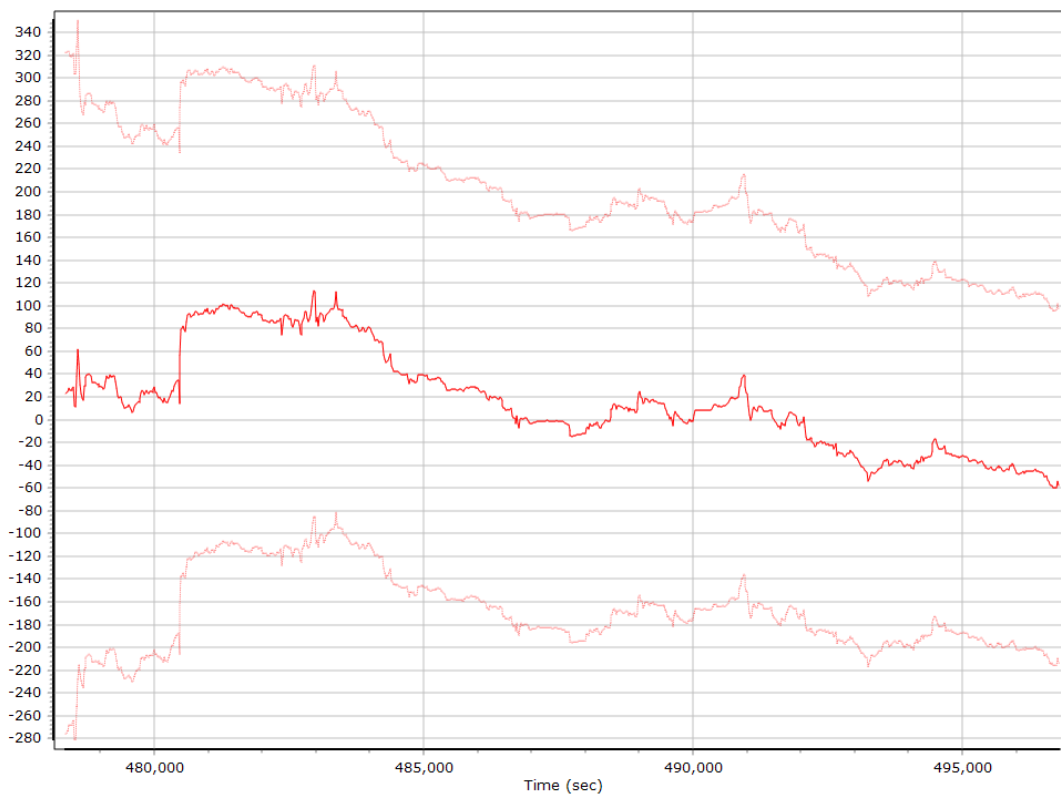
### Z Accelerometer Bias (micro-g)



### Accelerometer Scale Error (ppm)

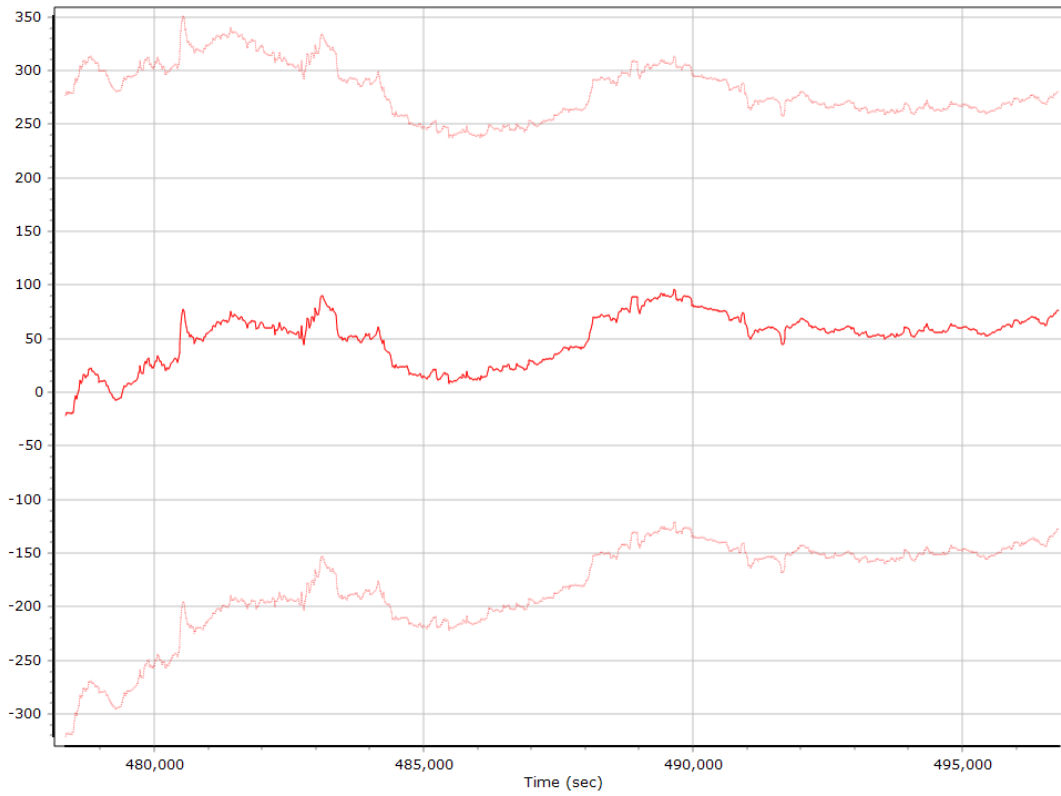


### X Accelerometer Scale Error (ppm)

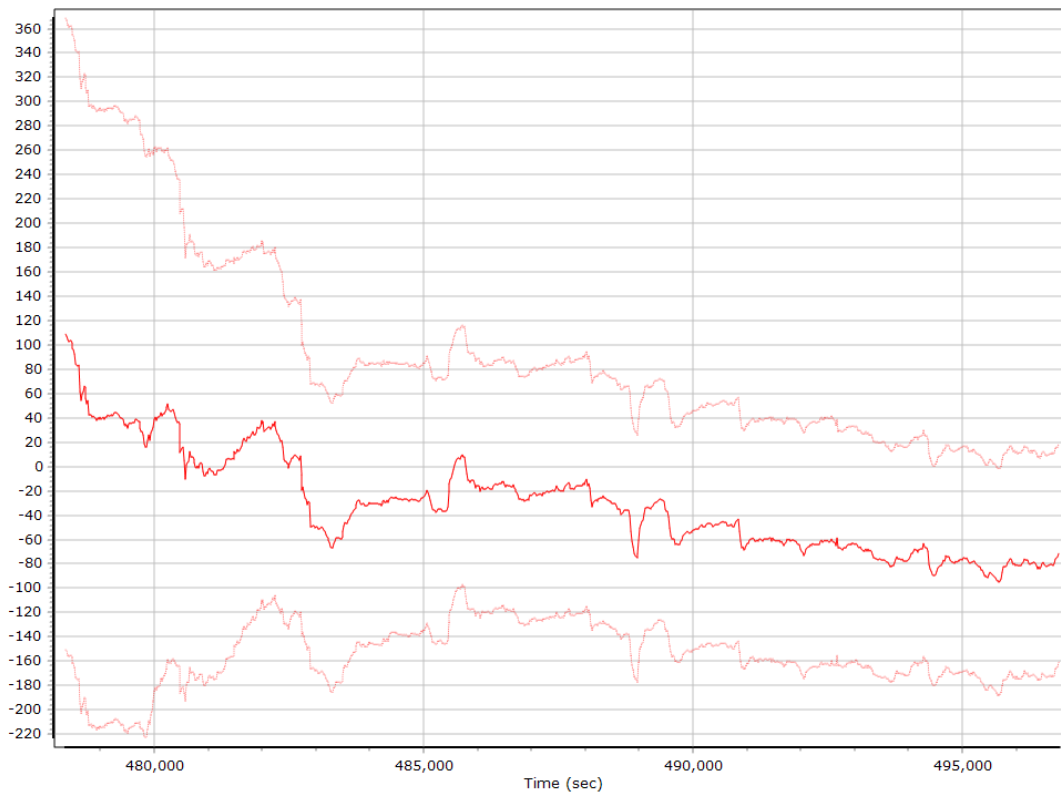




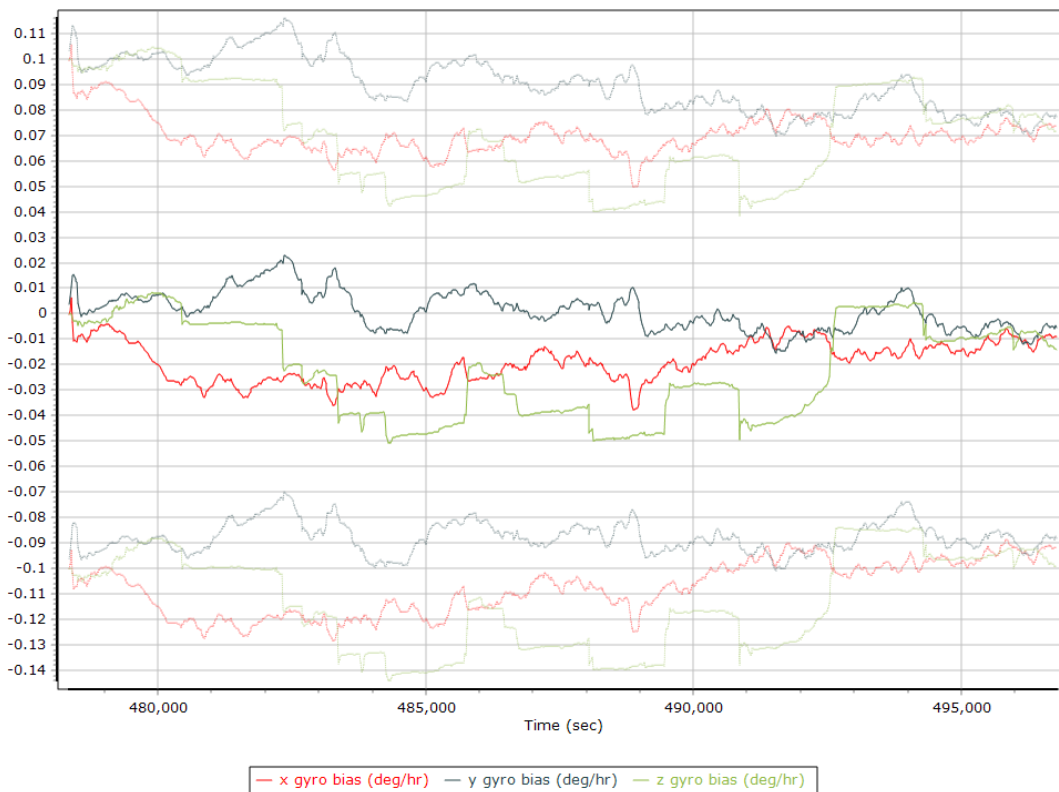
### Y Accelerometer Scale Error (ppm)



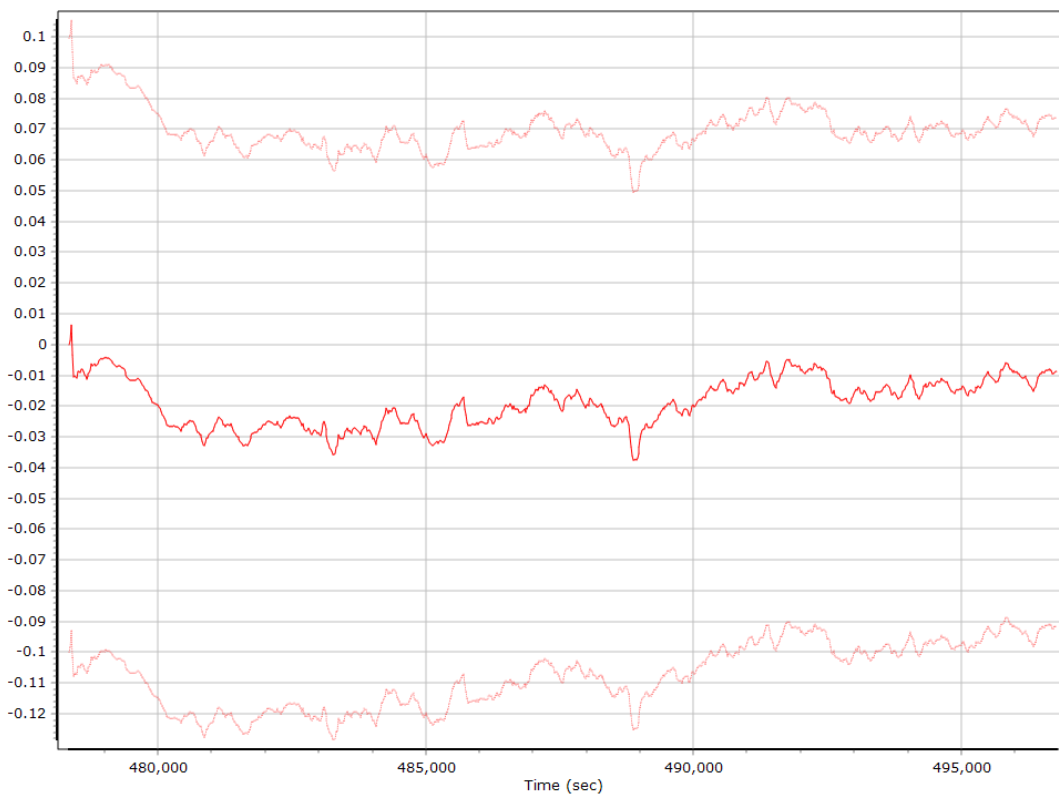
### Z Accelerometer Scale Error (ppm)



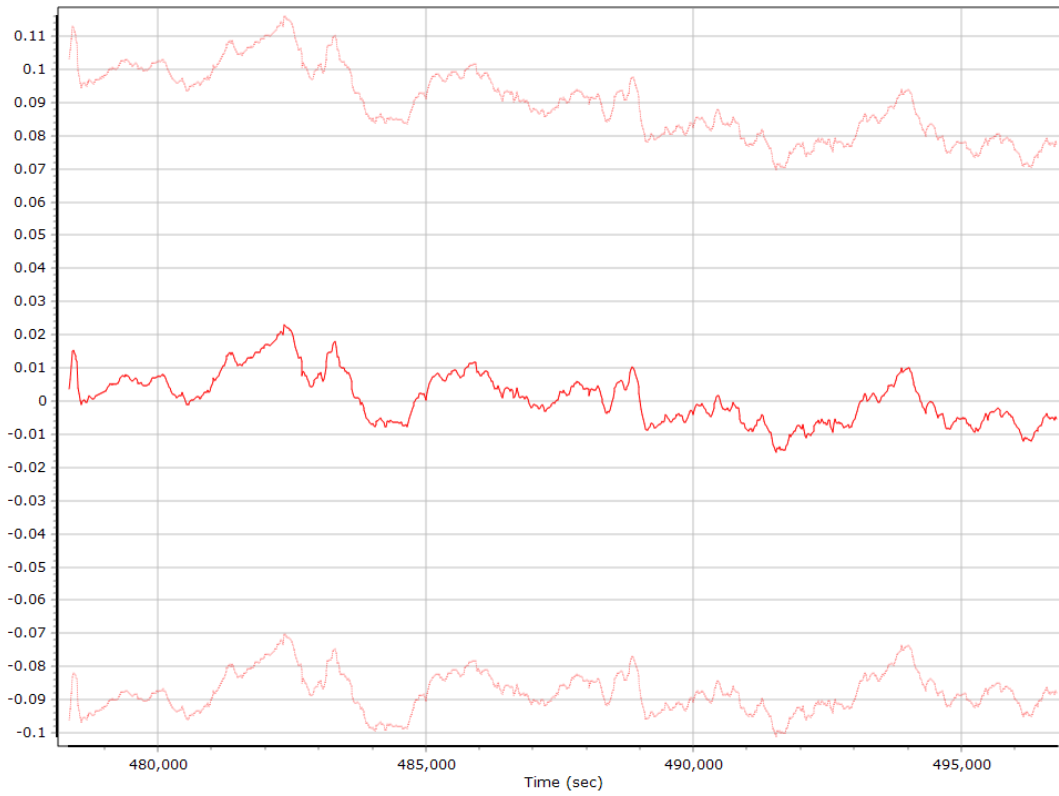
### Gyro Bias (deg/h)



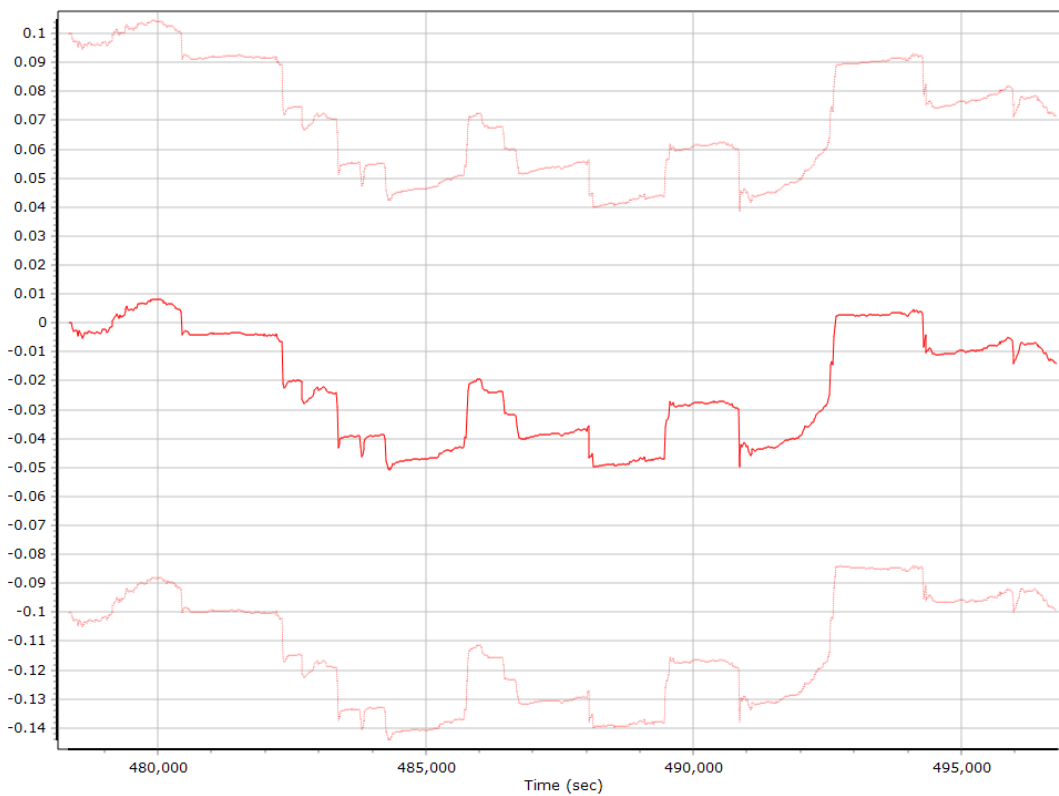
### X Gyro Bias (deg/h)



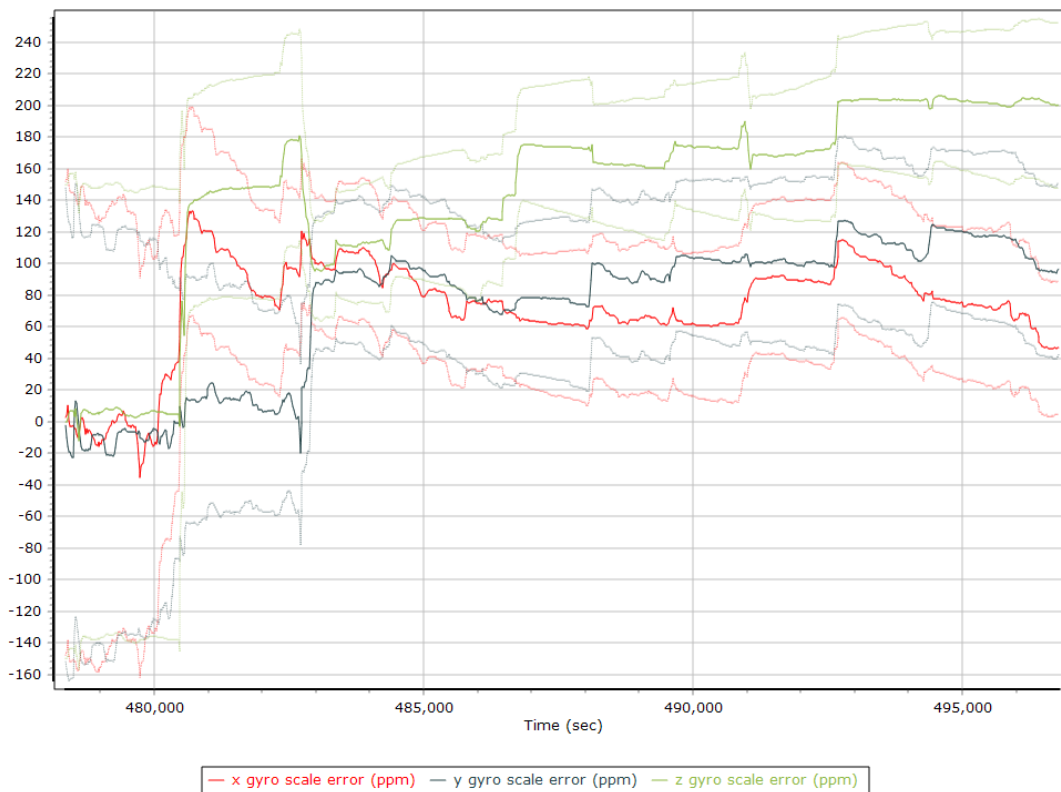
### Y Gyro Bias (deg/h)



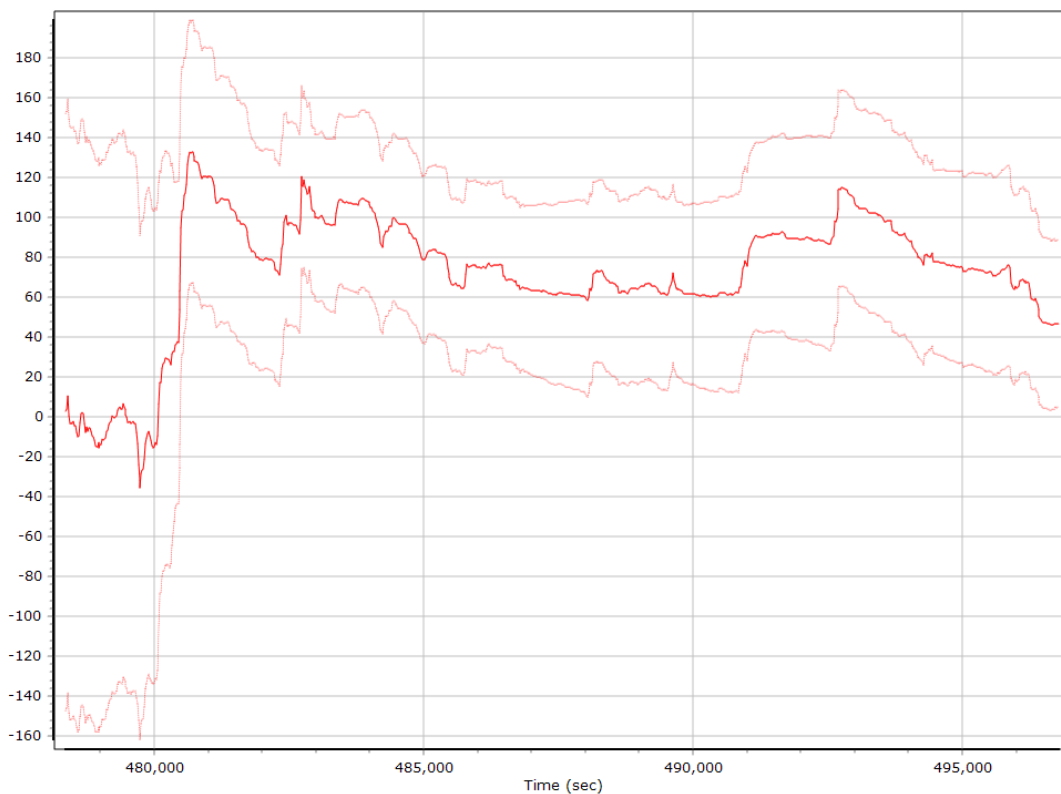
### Z Gyro Bias (deg/h)



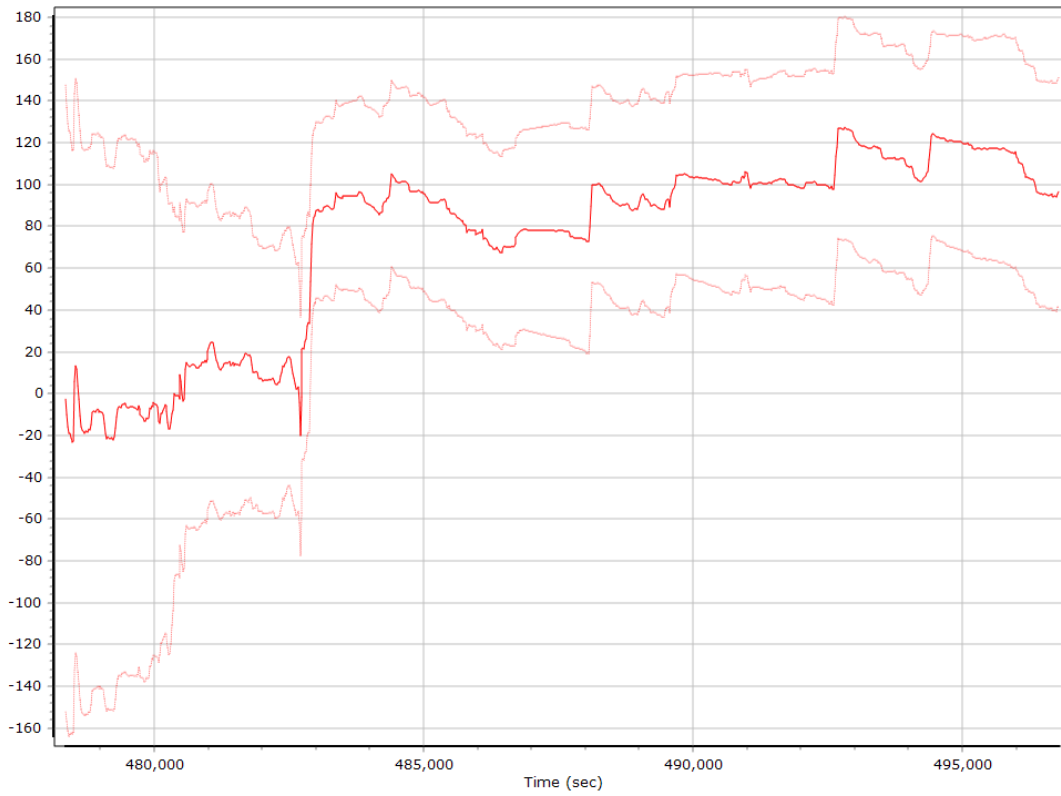
### Gyro Scale Error (ppm)



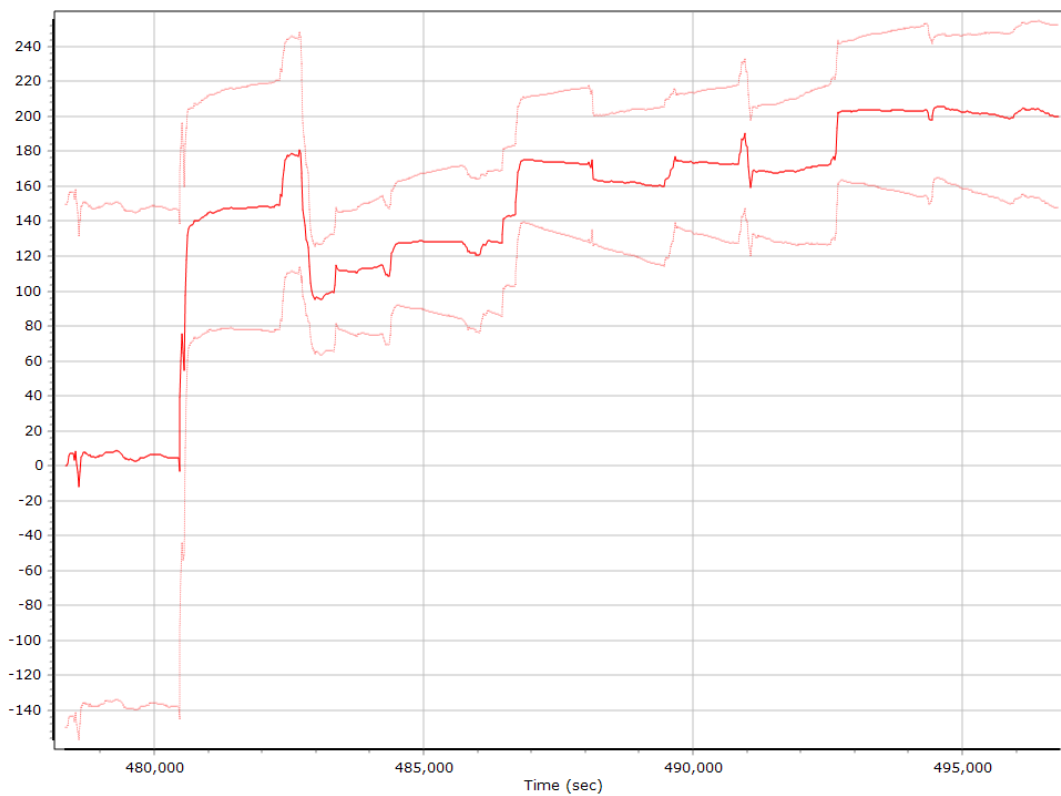
### X Gyro Scale Error (ppm)



### Y Gyro Scale Error (ppm)

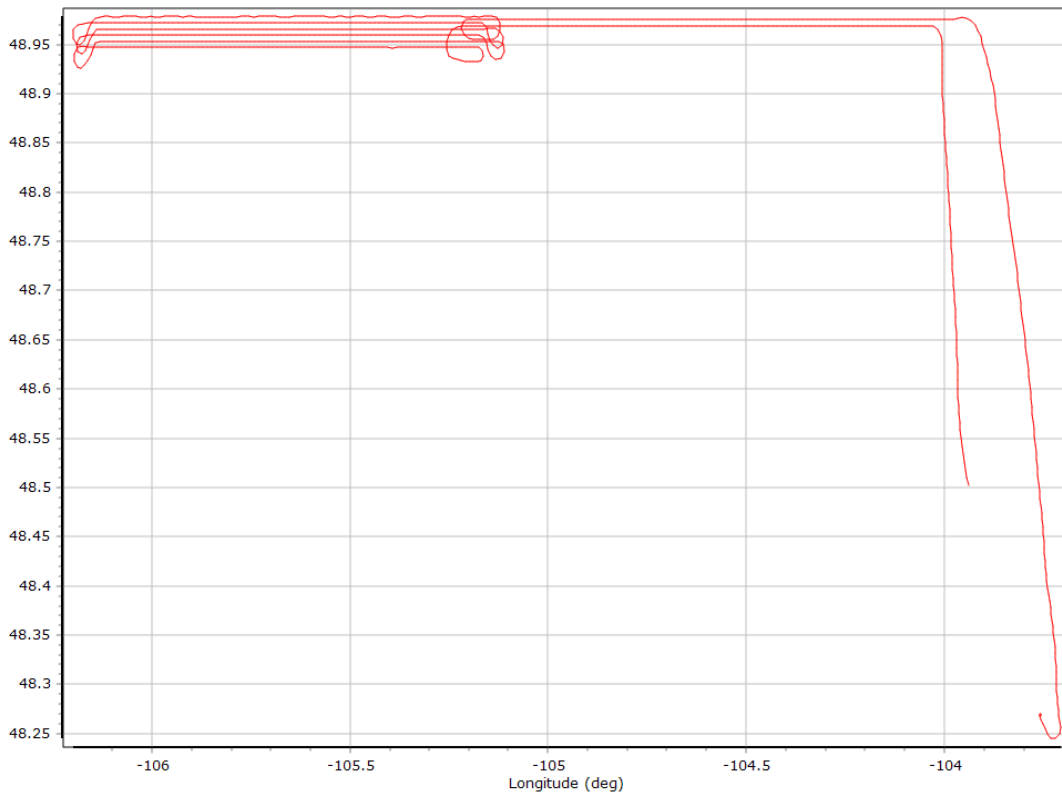


### Z Gyro Scale Error (ppm)

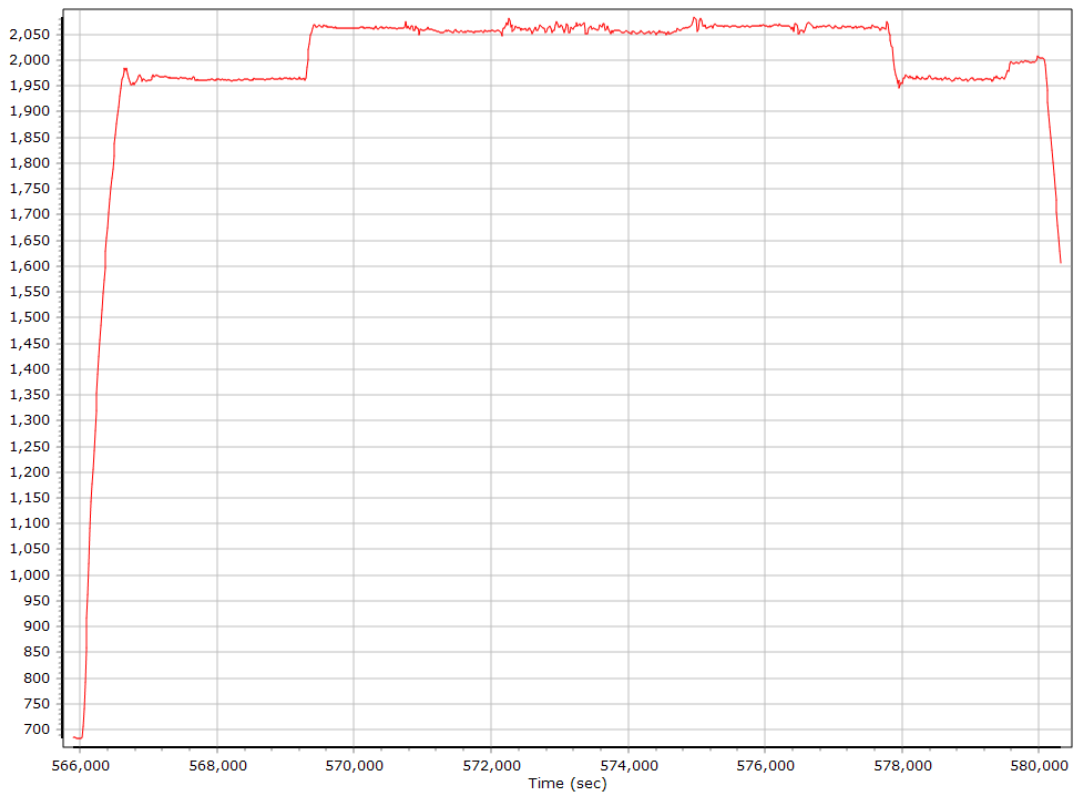


## Smoothed Trajectory Information

### Top View



### Altitude

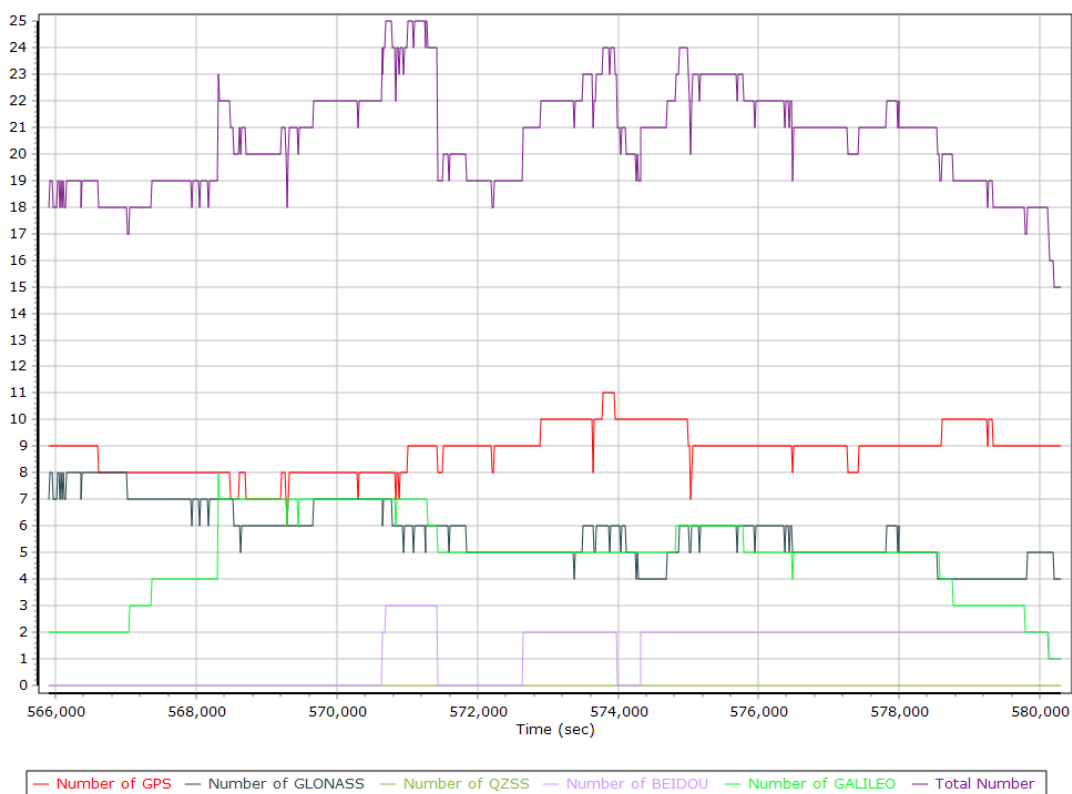


## GNSS QC

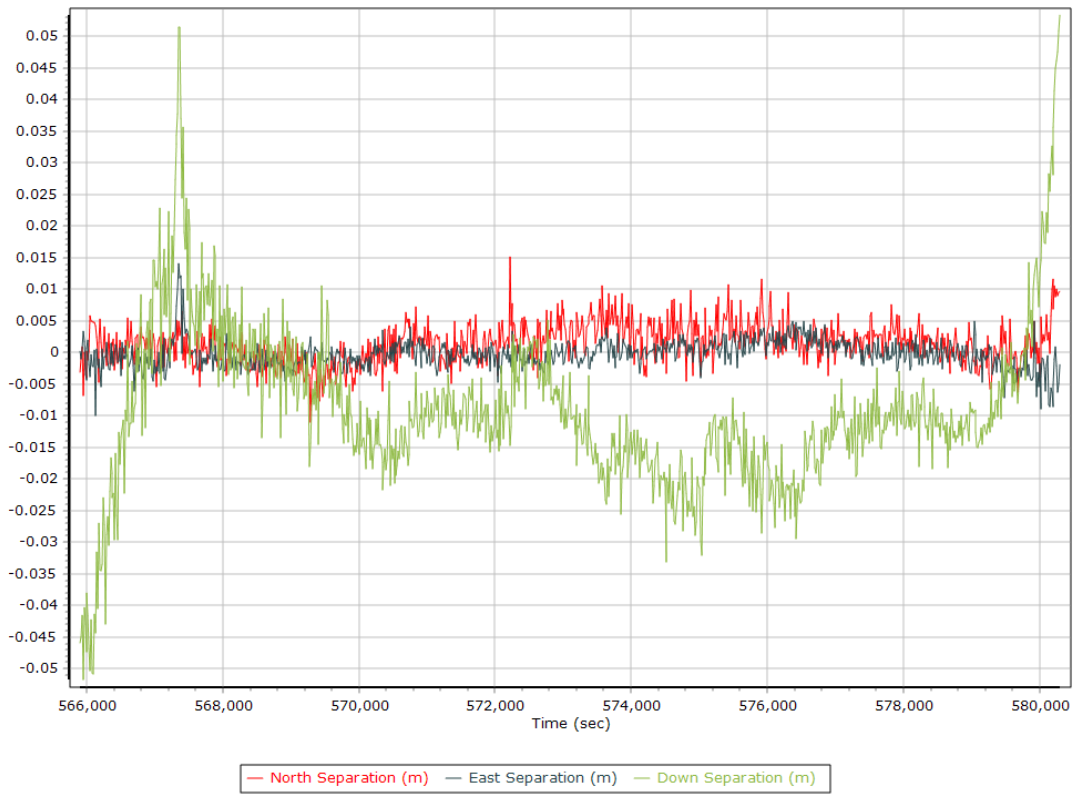
### GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	6	11	9
Number of GLONASS SV	0	8	6
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	3	1
Number of GALILEO SV	0	8	5
Total number of SV	11	25	21
PDOP	0.98	1.89	1.19
QC Solution Gaps	0.00	0.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	14729.00	0.00	0.00
Percentage	100.00	0.00	0.00

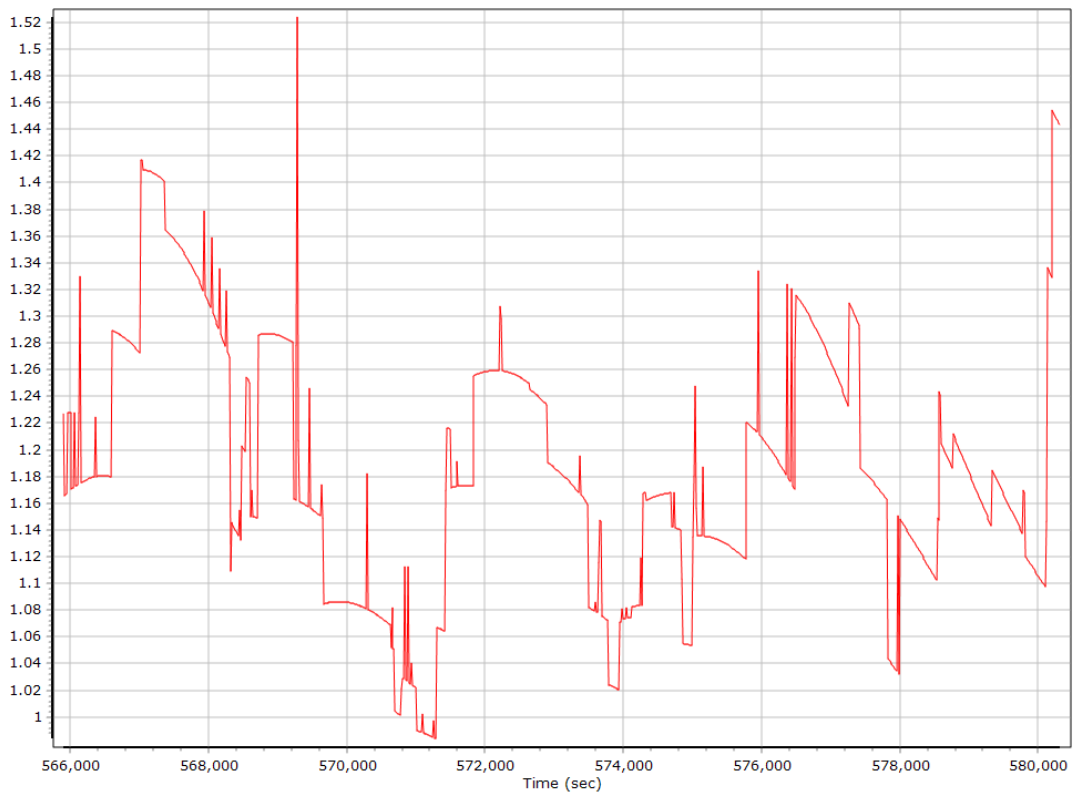
### Num SVs in solution



## Forward/Reverse Separation



## PDOP

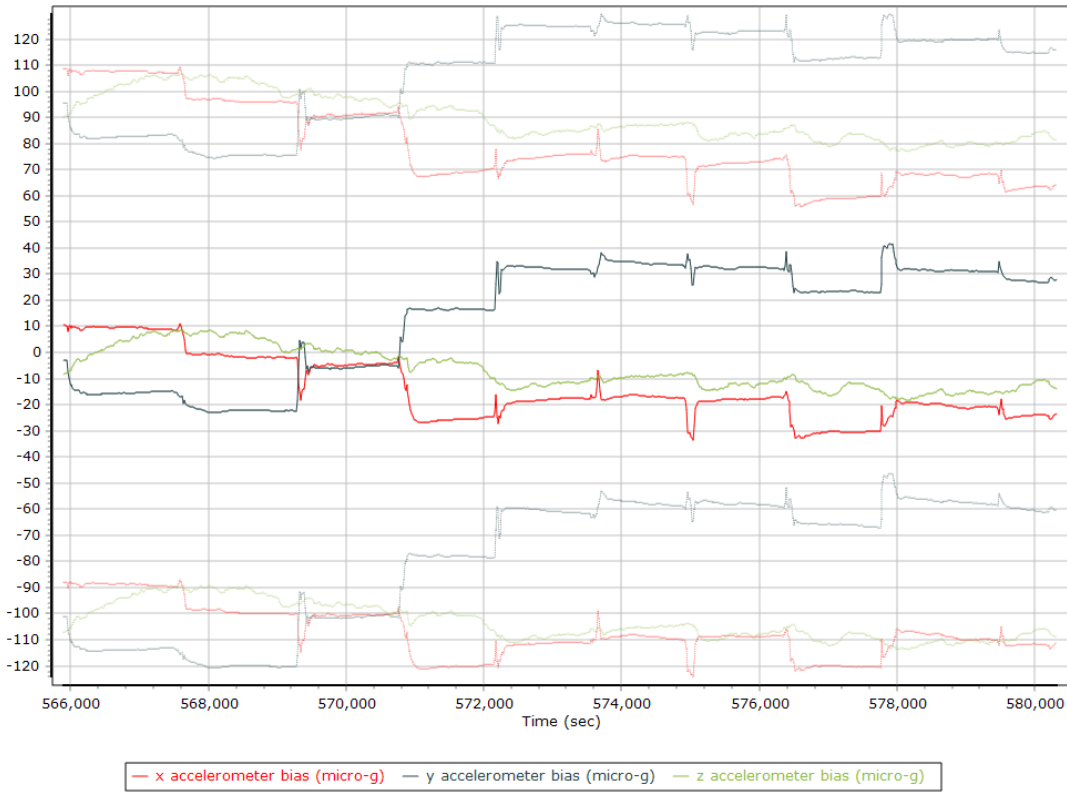




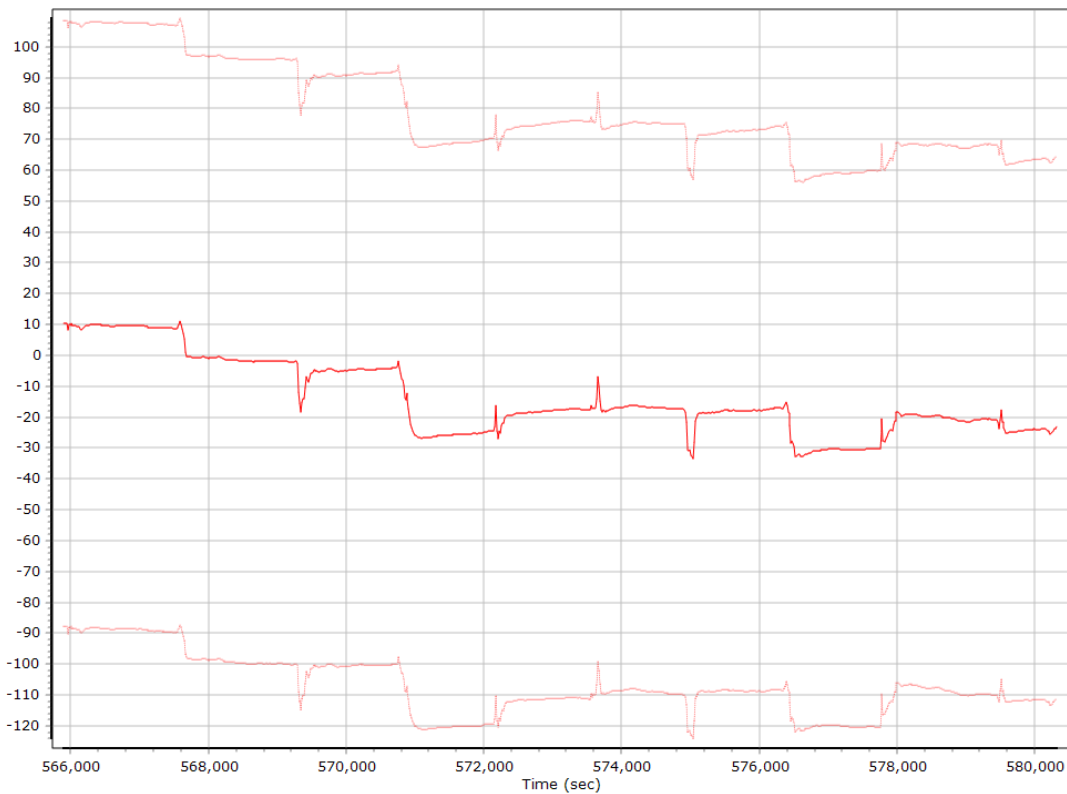
## IN-Fusion QC

### Forward Processed Estimated Errors, Reference Frame

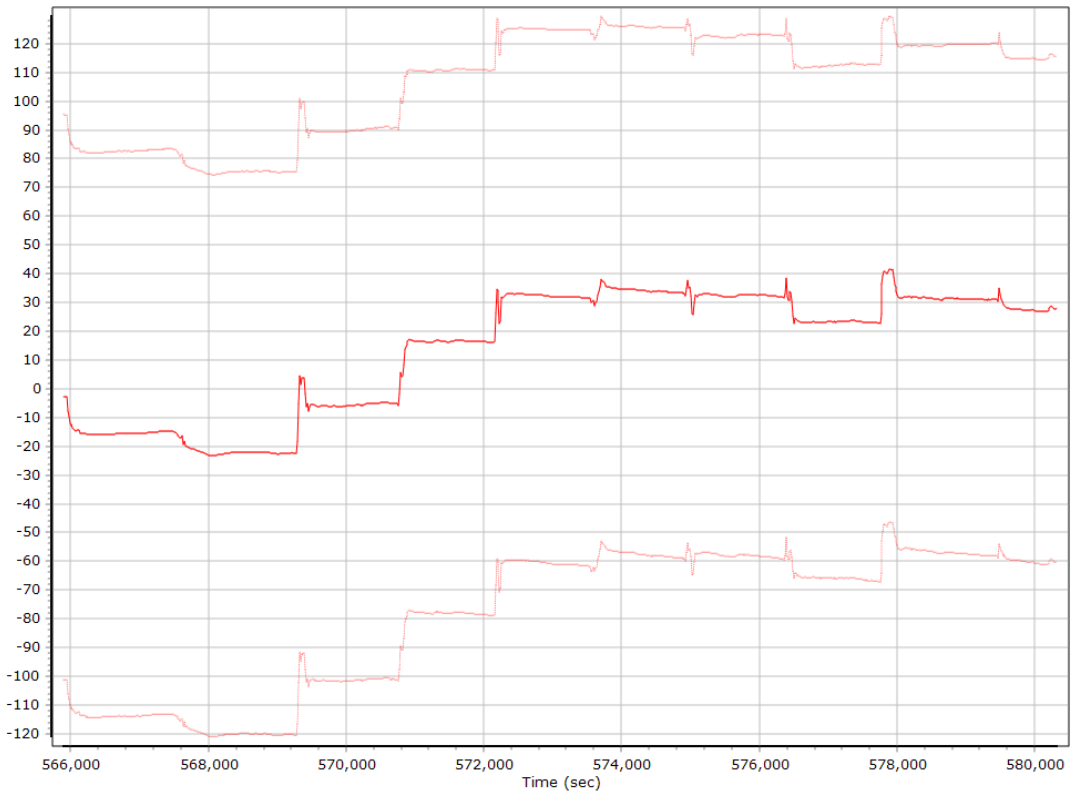
#### Accelerometer Bias (micro-g)



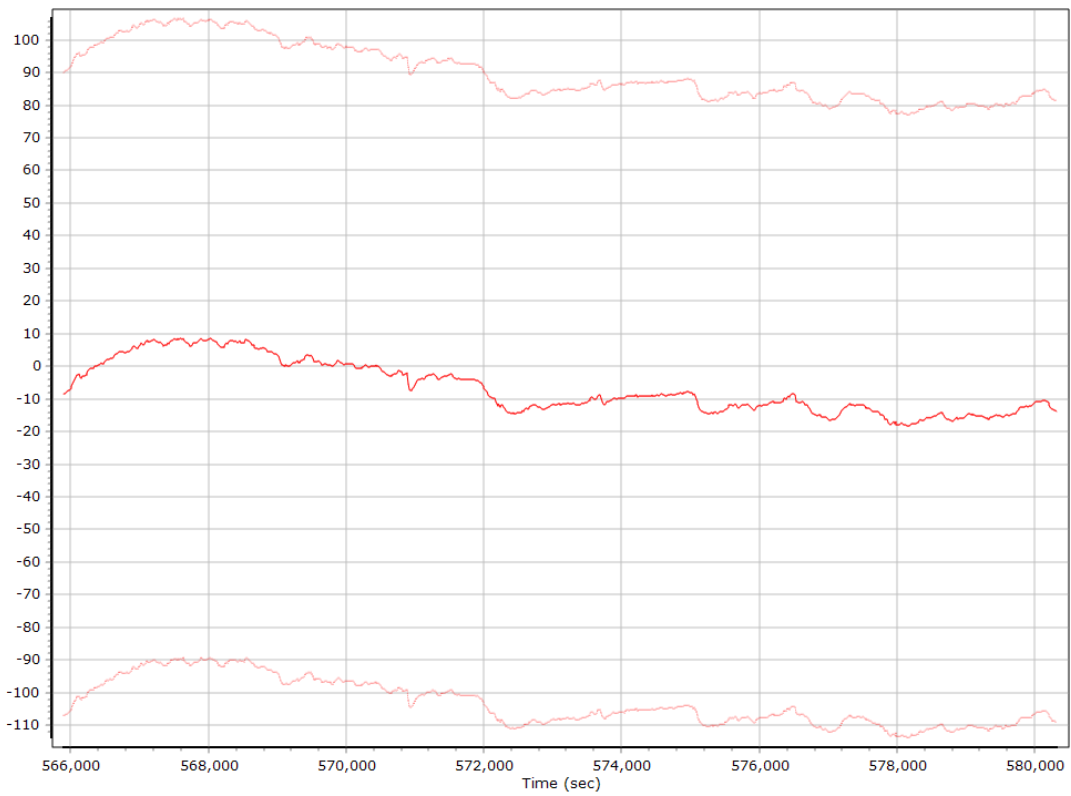
#### X Accelerometer Bias (micro-g)



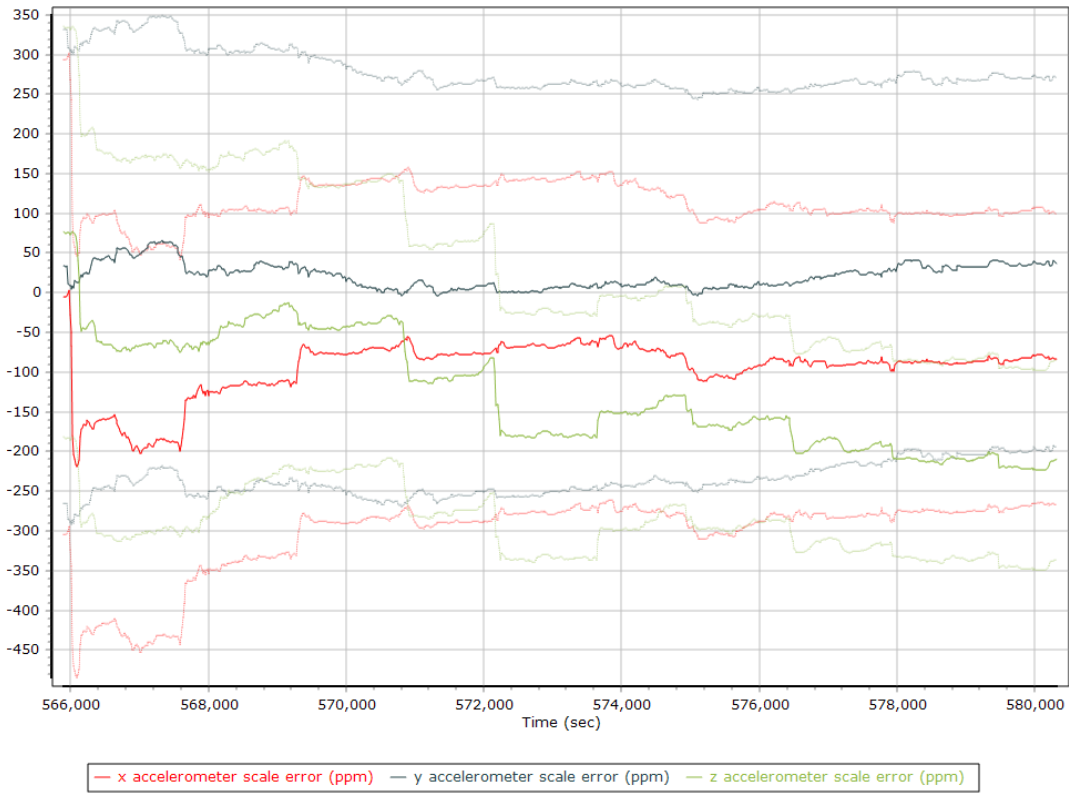
### Y Accelerometer Bias (micro-g)



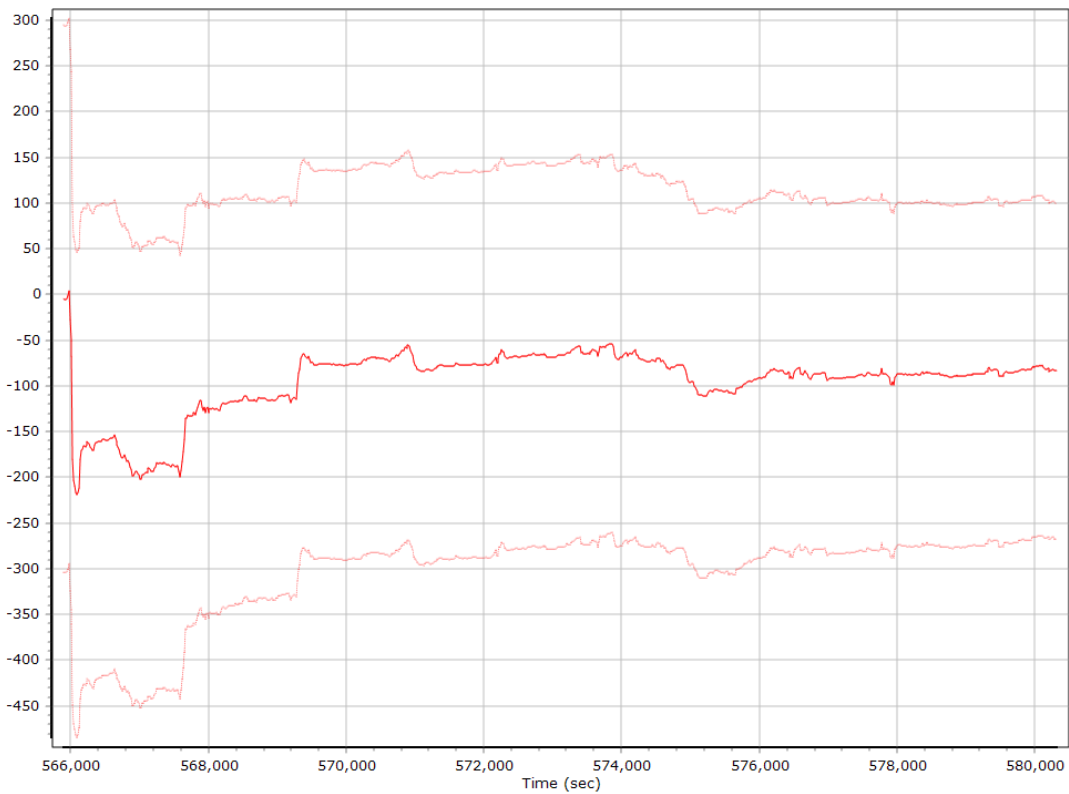
### Z Accelerometer Bias (micro-g)



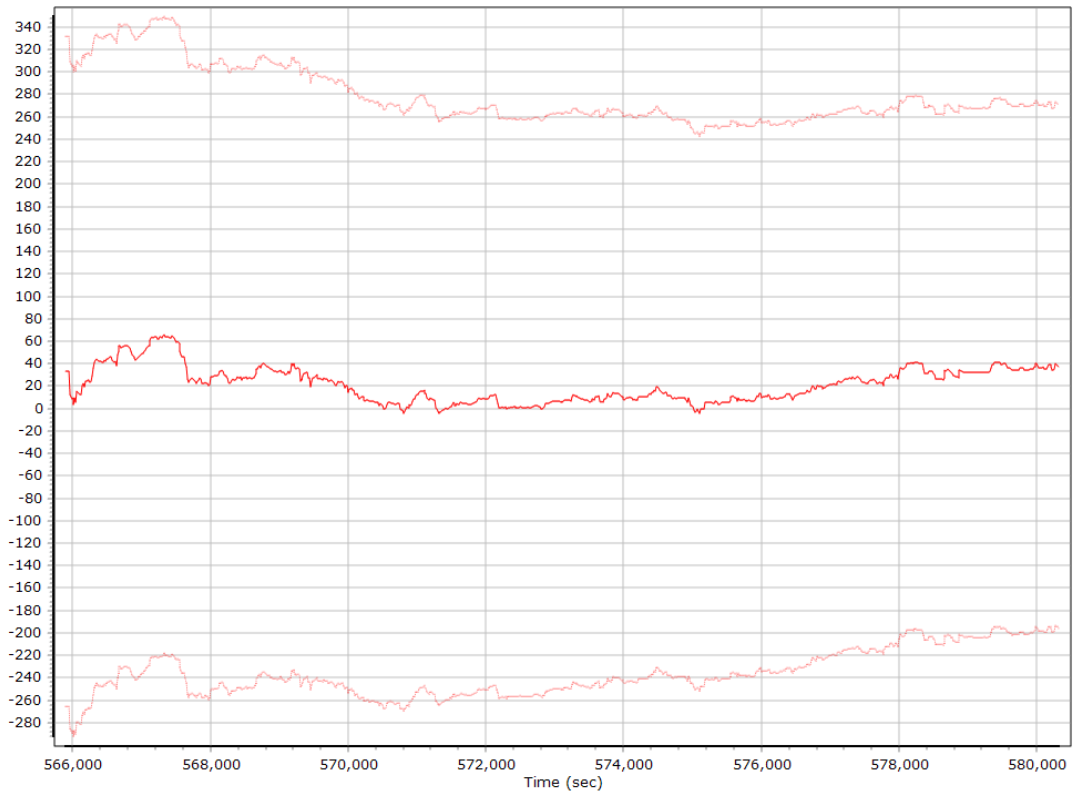
### Accelerometer Scale Error (ppm)



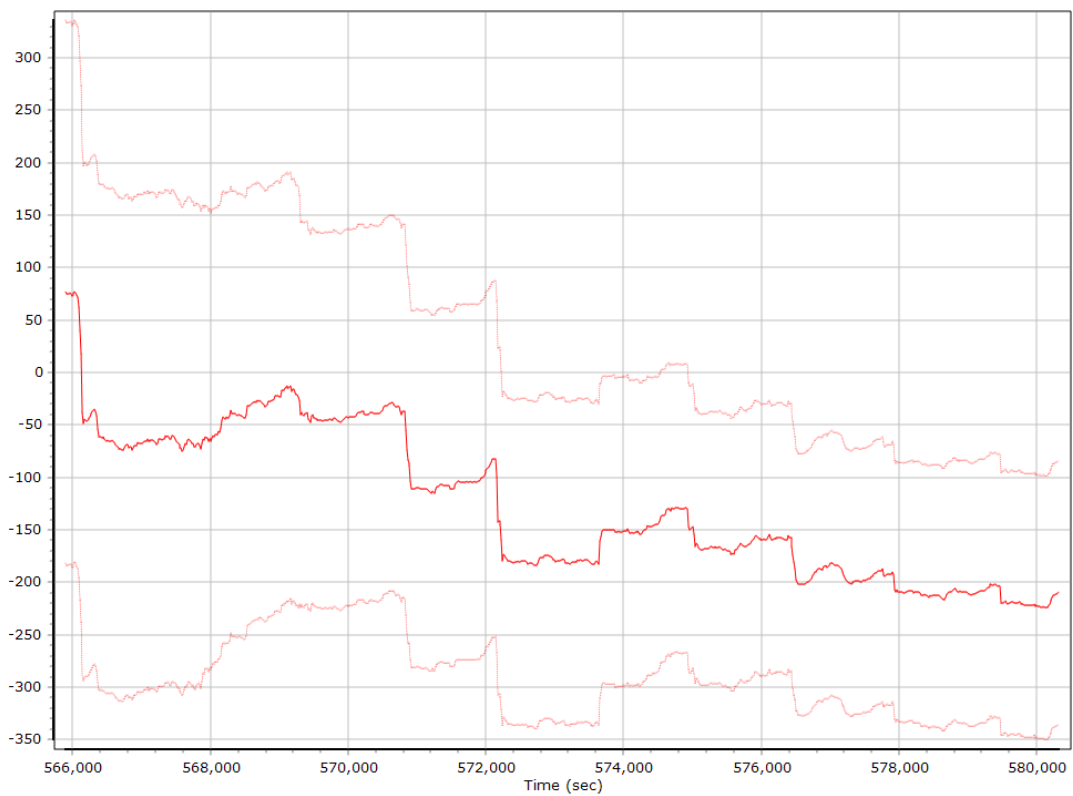
### X Accelerometer Scale Error (ppm)



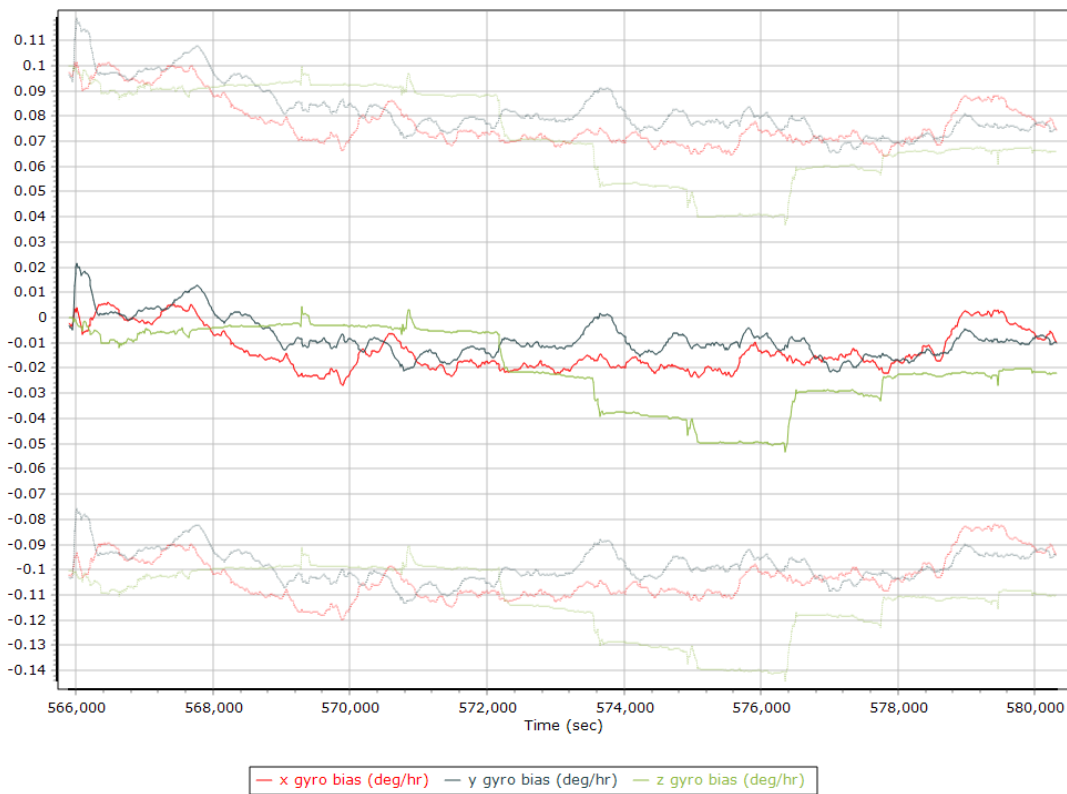
### Y Accelerometer Scale Error (ppm)



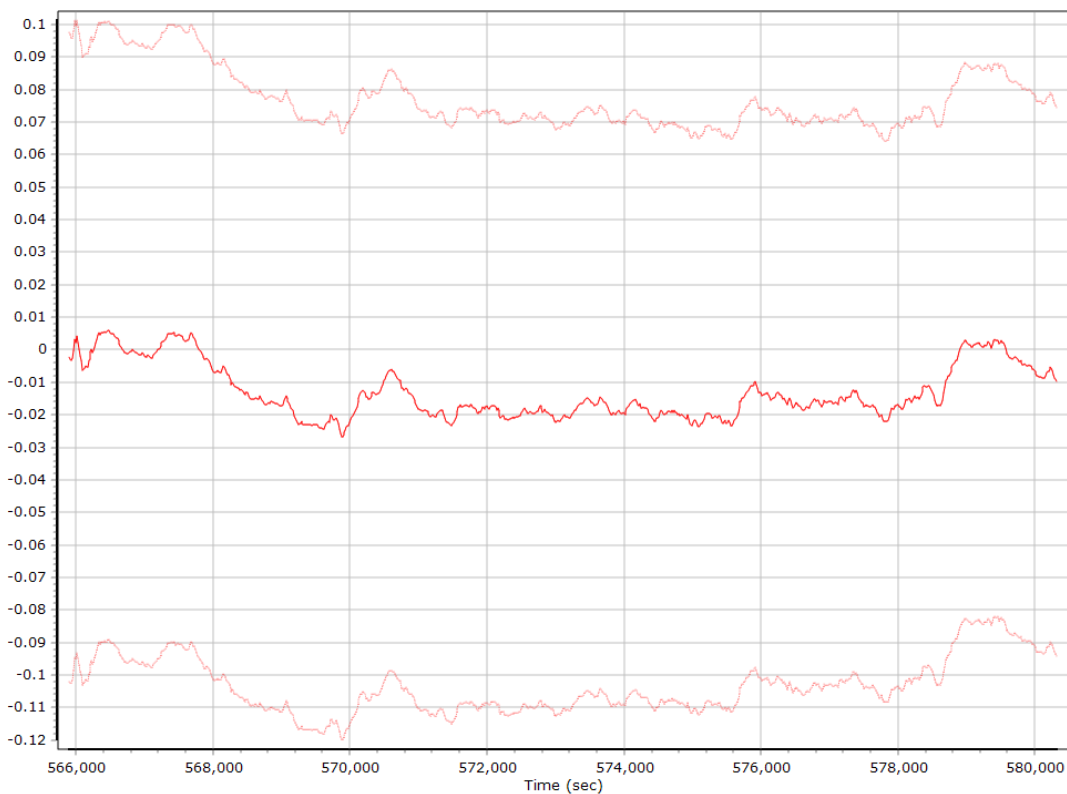
### Z Accelerometer Scale Error (ppm)



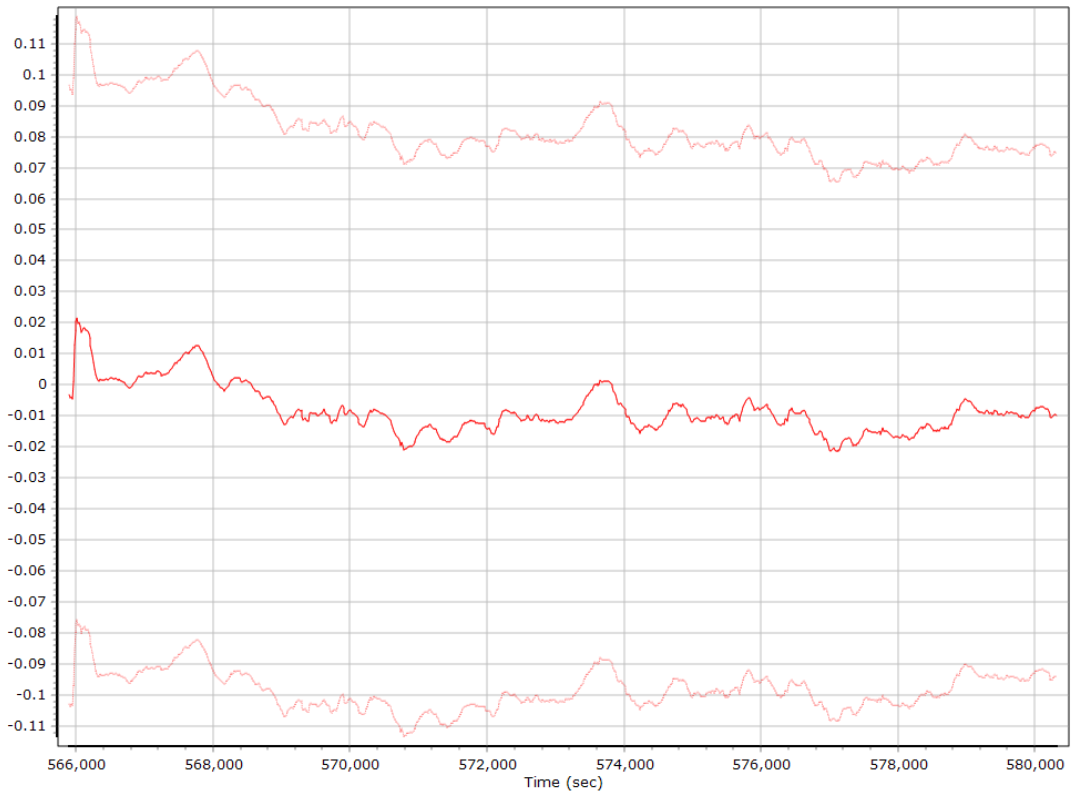
### Gyro Bias (deg/h)



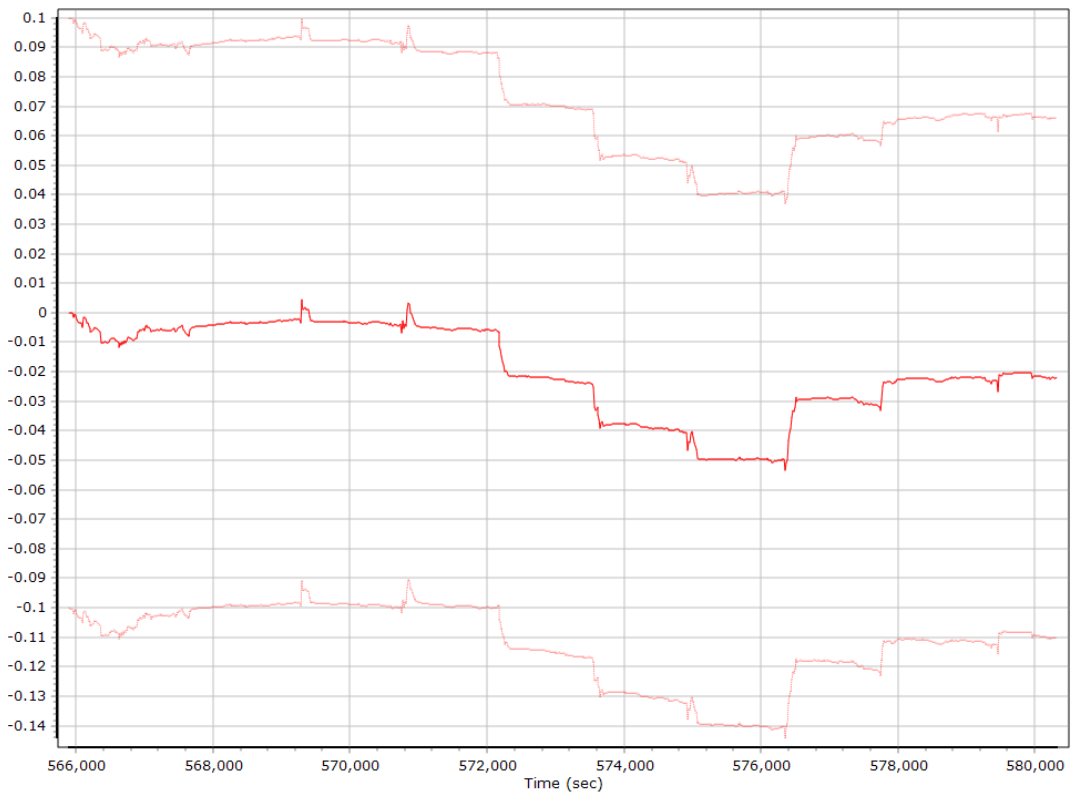
### X Gyro Bias (deg/h)



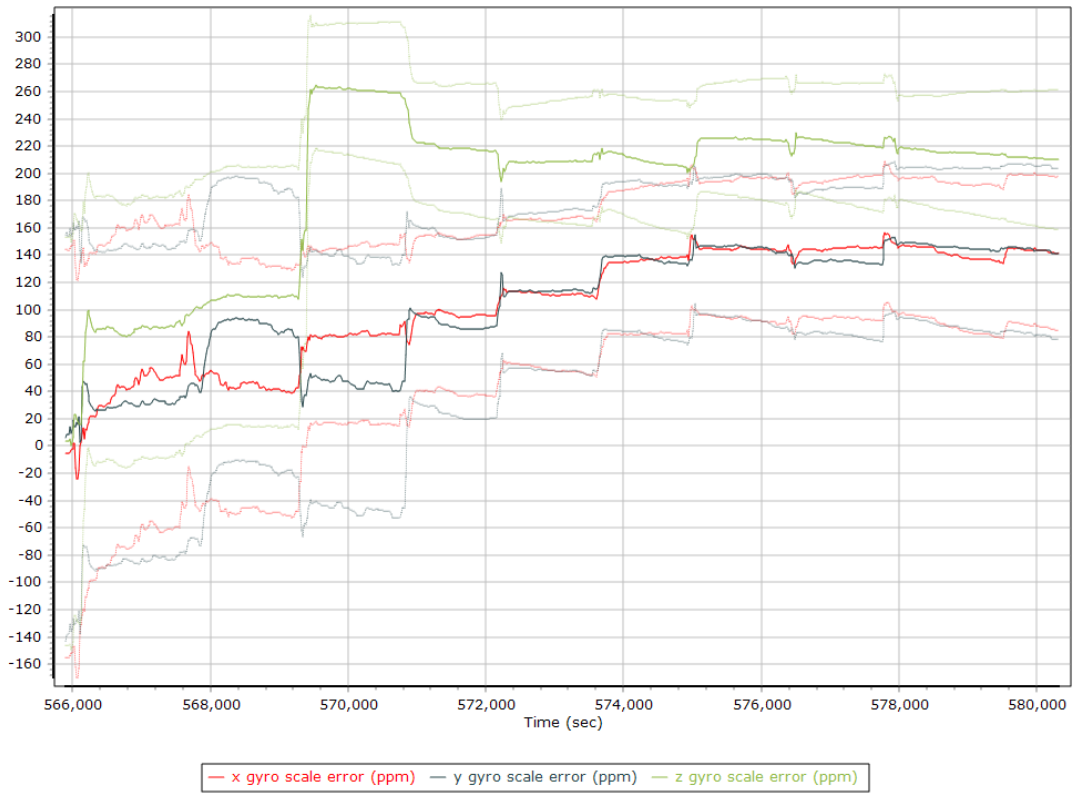
### Y Gyro Bias (deg/h)



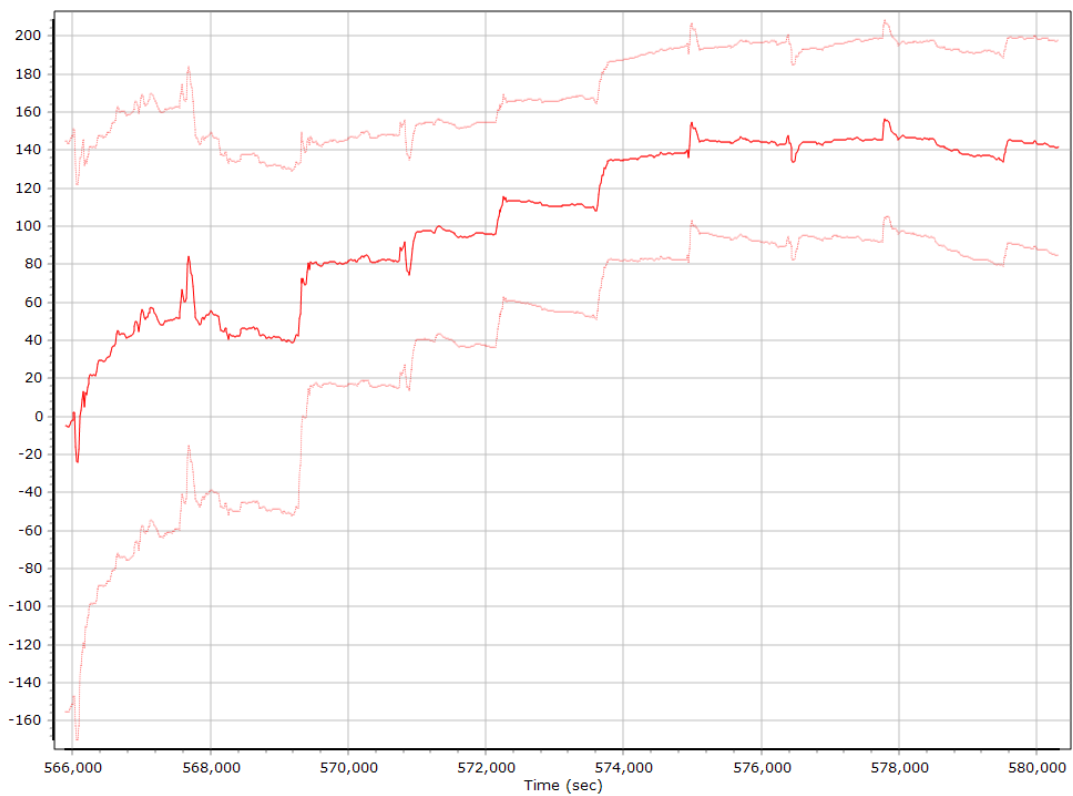
### Z Gyro Bias (deg/h)



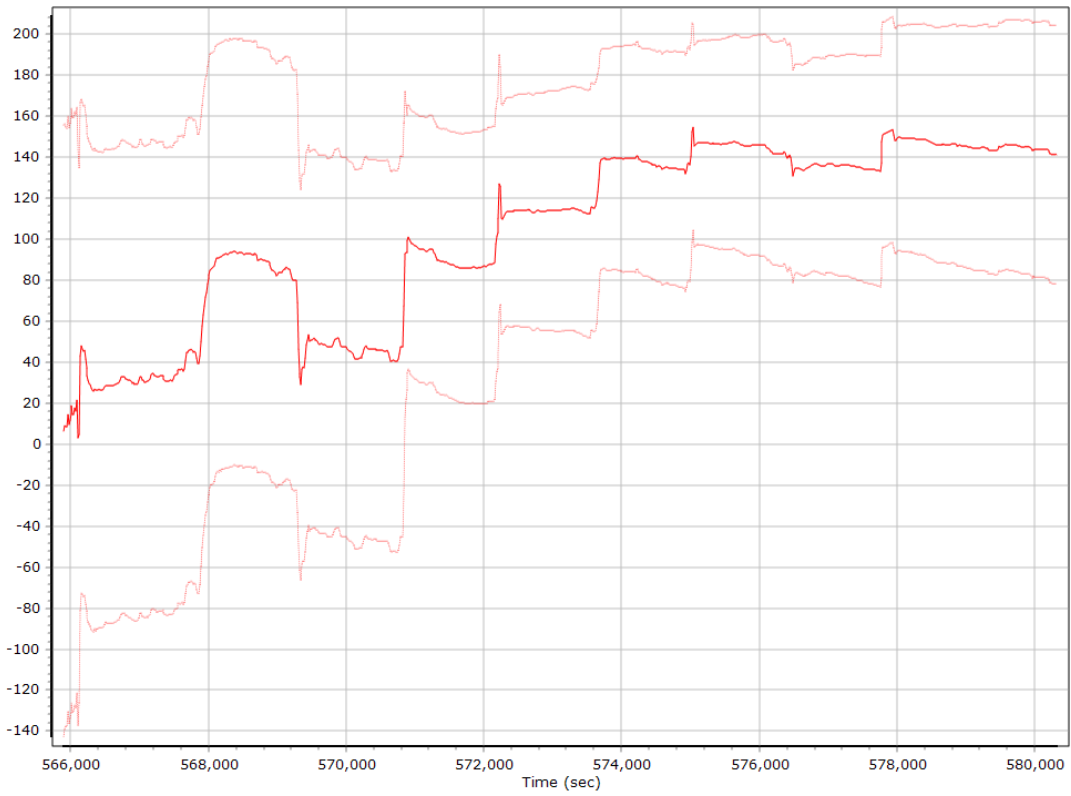
### Gyro Scale Error (ppm)



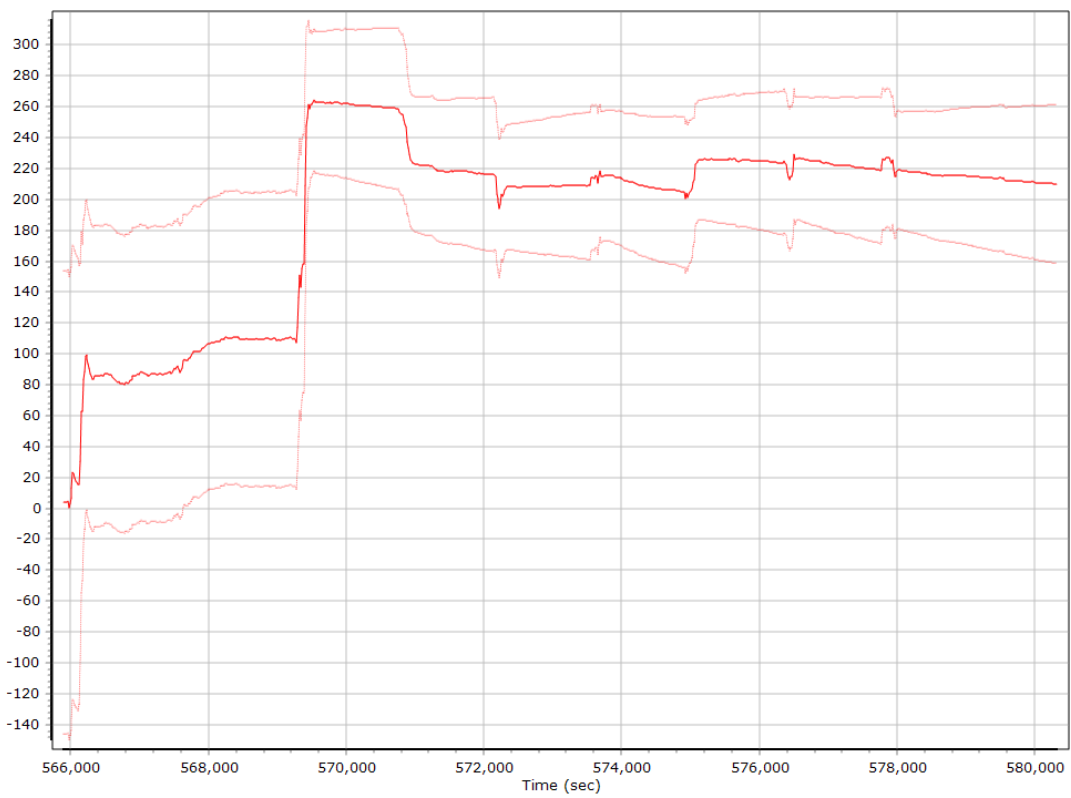
### X Gyro Scale Error (ppm)



### Y Gyro Scale Error (ppm)



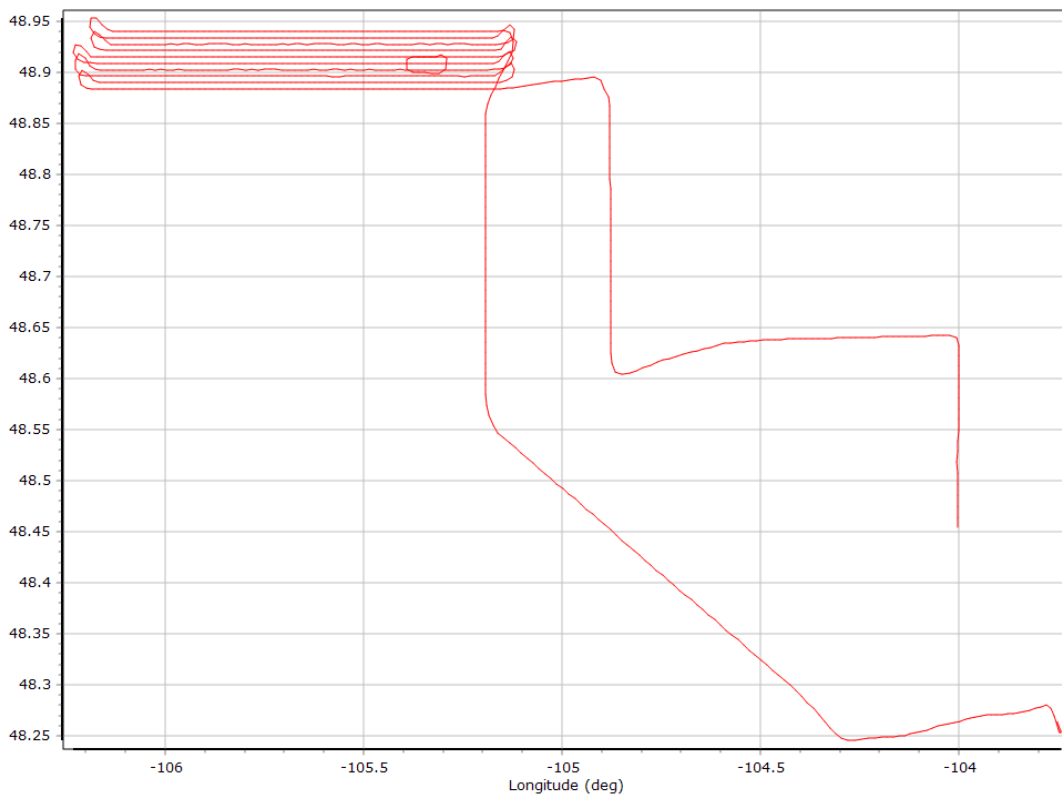
### Z Gyro Scale Error (ppm)



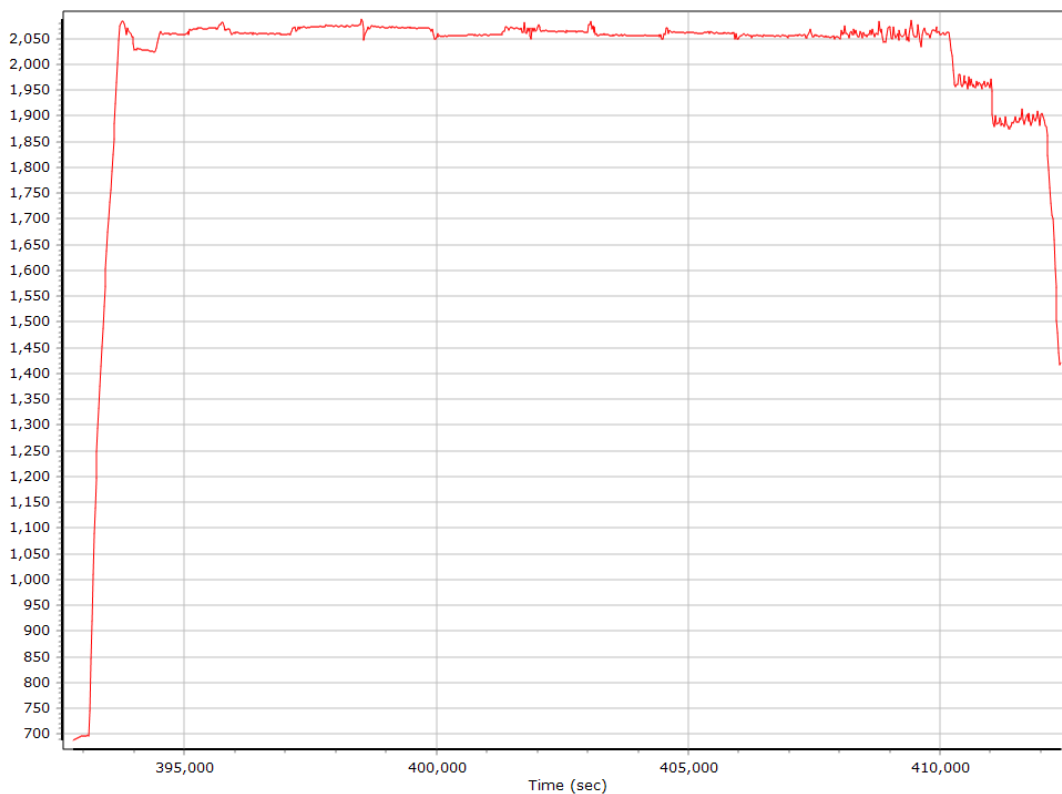


## Smoothed Trajectory Information

### Top View



### Altitude

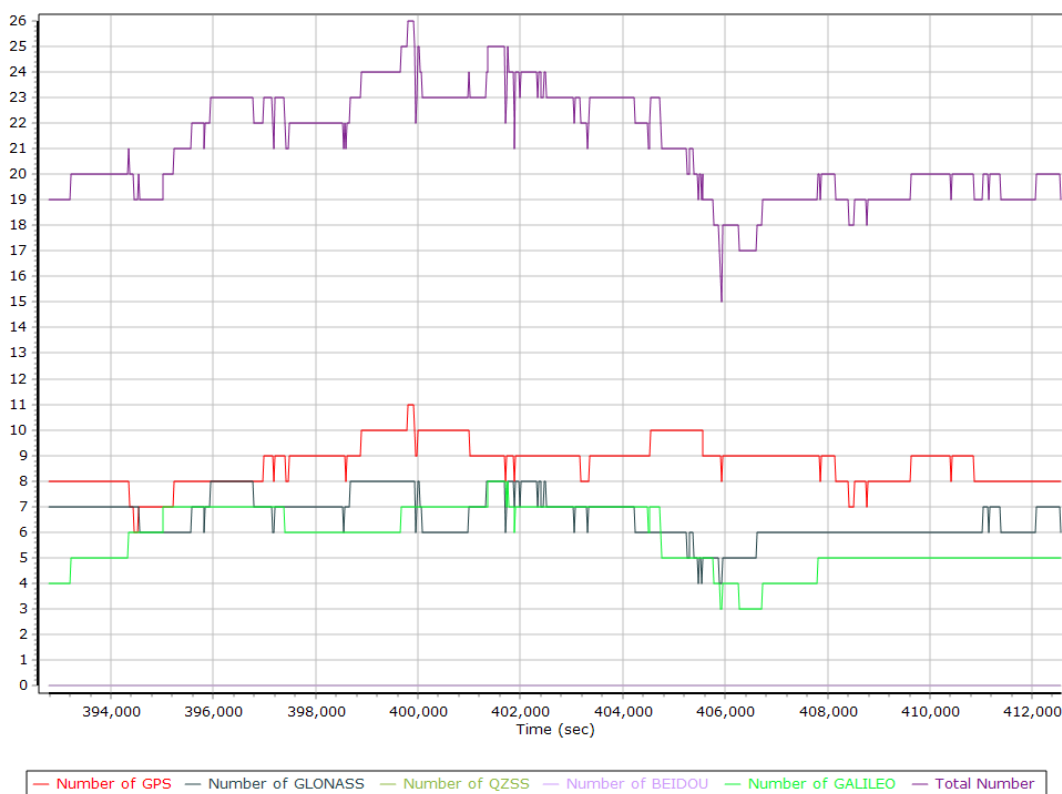


## GNSS QC

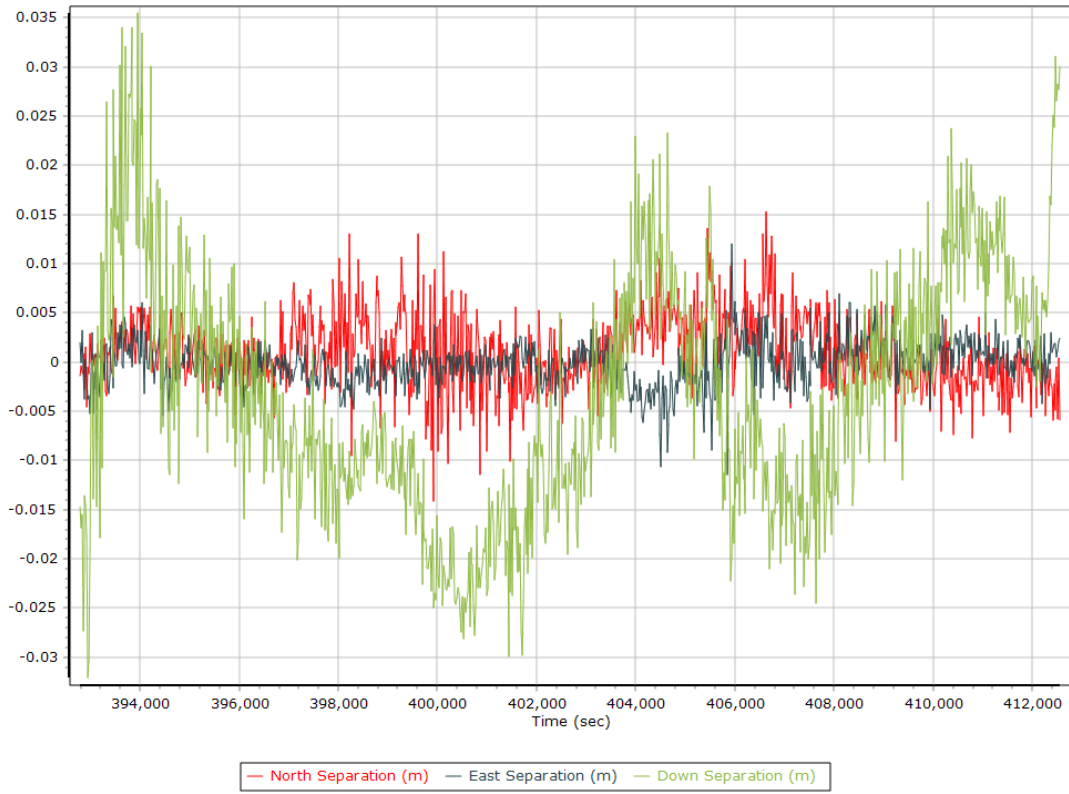
### GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	6	11	9
Number of GLONASS SV	0	8	7
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	0	0
Number of GALILEO SV	3	8	6
Total number of SV	12	26	21
PDOP	0.96	1.69	1.16
QC Solution Gaps	0.00	0.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	19906.00	0.00	0.00
Percentage	100.00	0.00	0.00

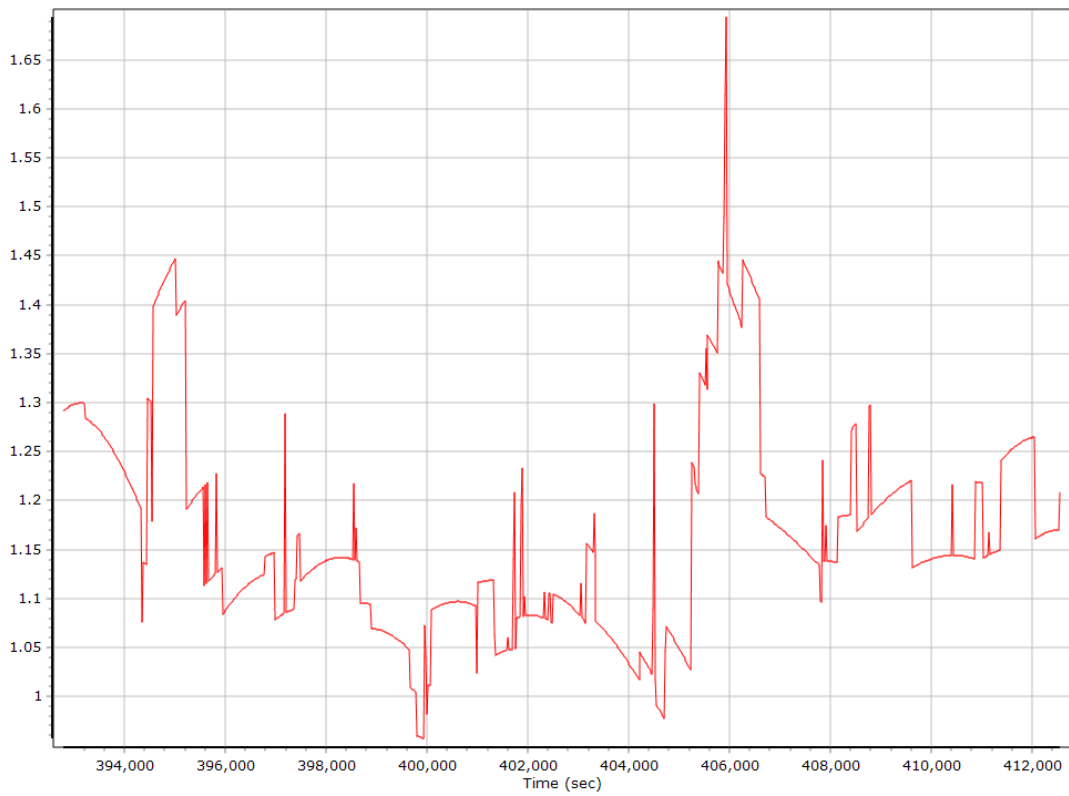
### Num SVs in solution



## Forward/Reverse Separation



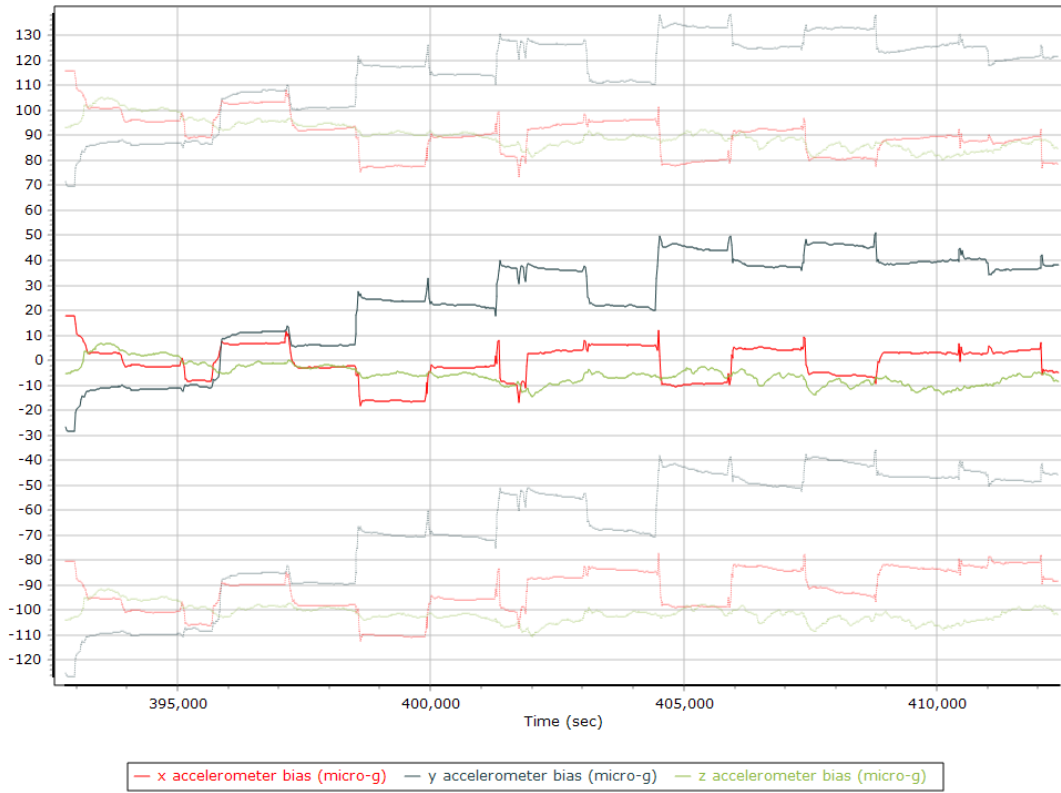
## PDOP



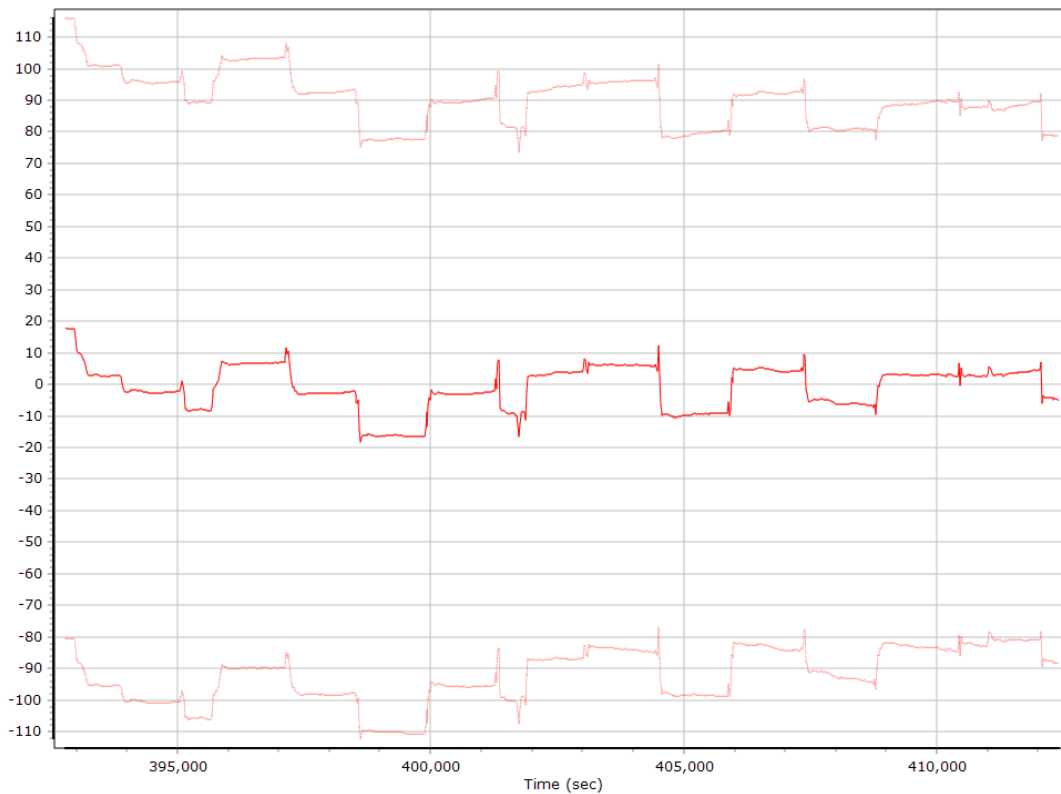
## IN-Fusion QC

### Forward Processed Estimated Errors, Reference Frame

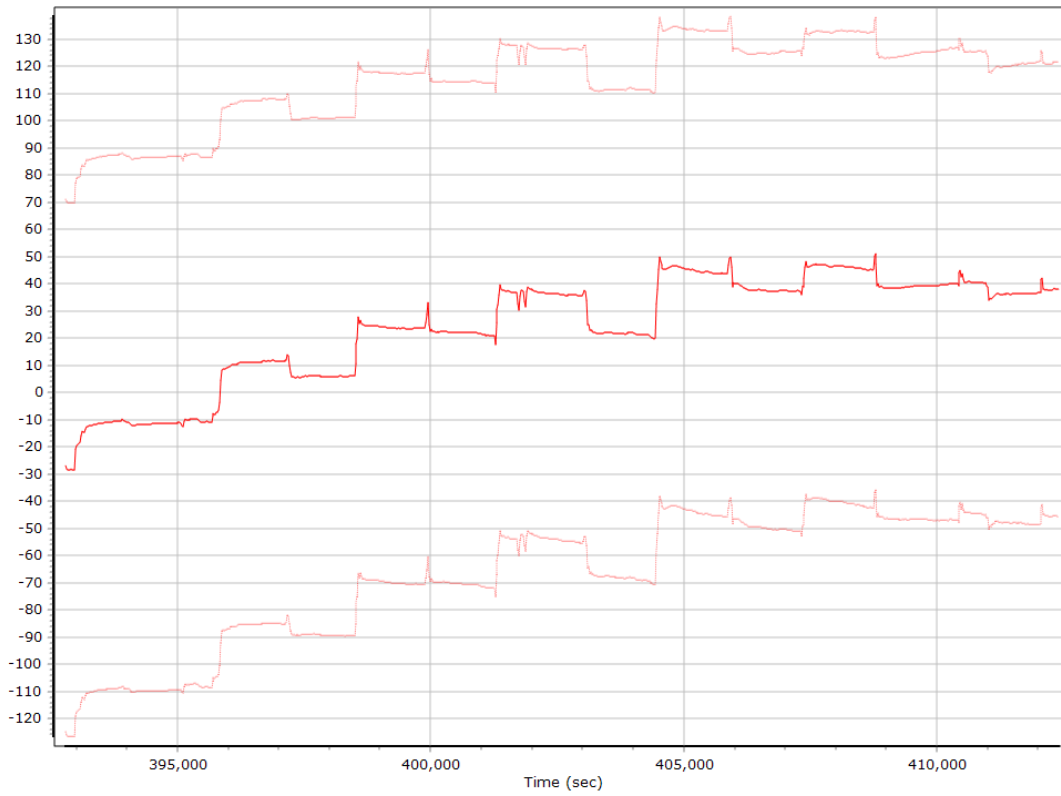
#### Accelerometer Bias (micro-g)



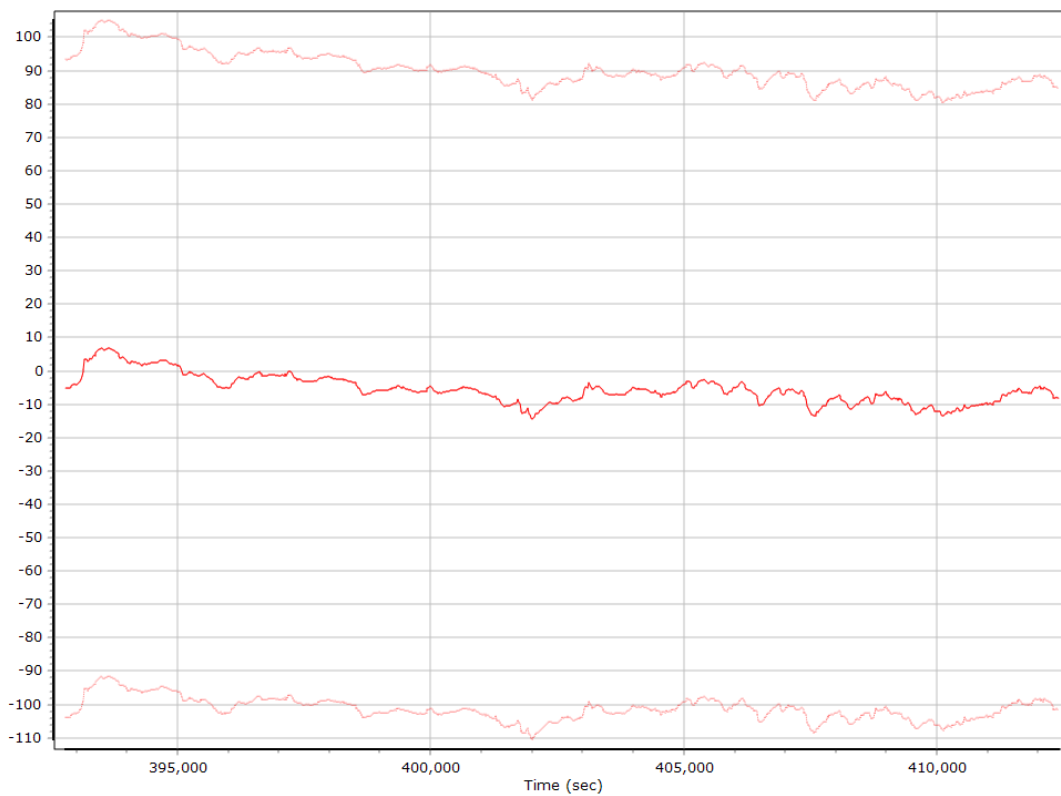
#### X Accelerometer Bias (micro-g)



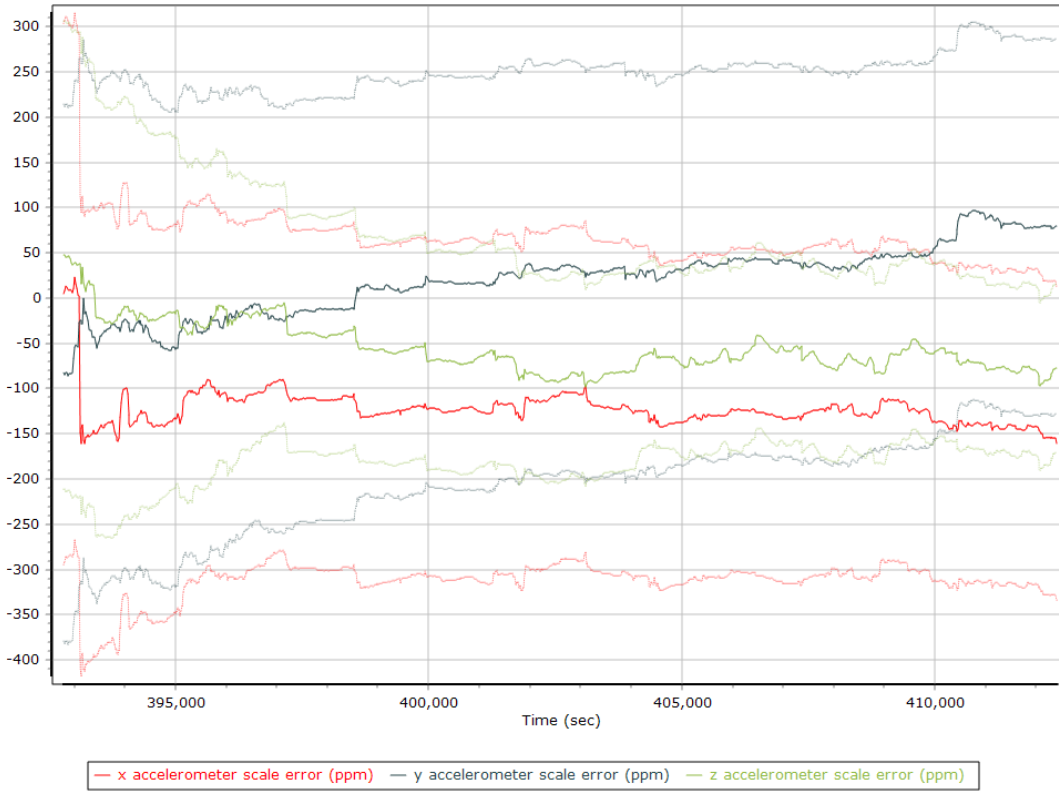
### Y Accelerometer Bias (micro-g)



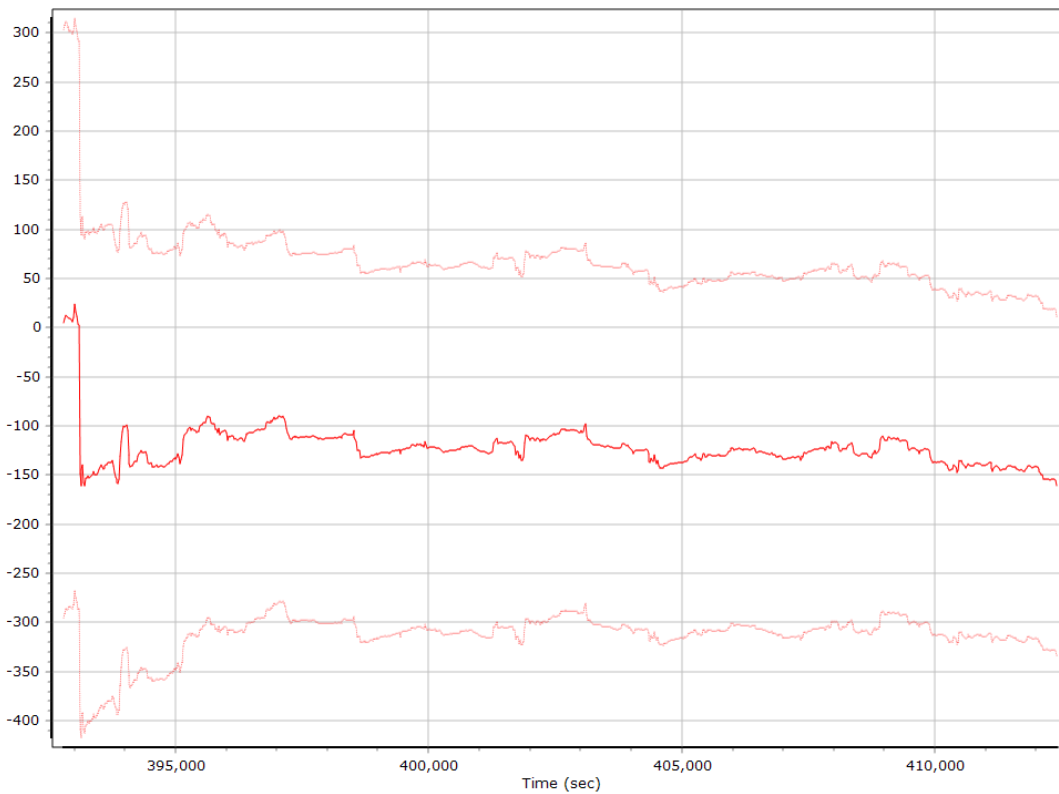
### Z Accelerometer Bias (micro-g)



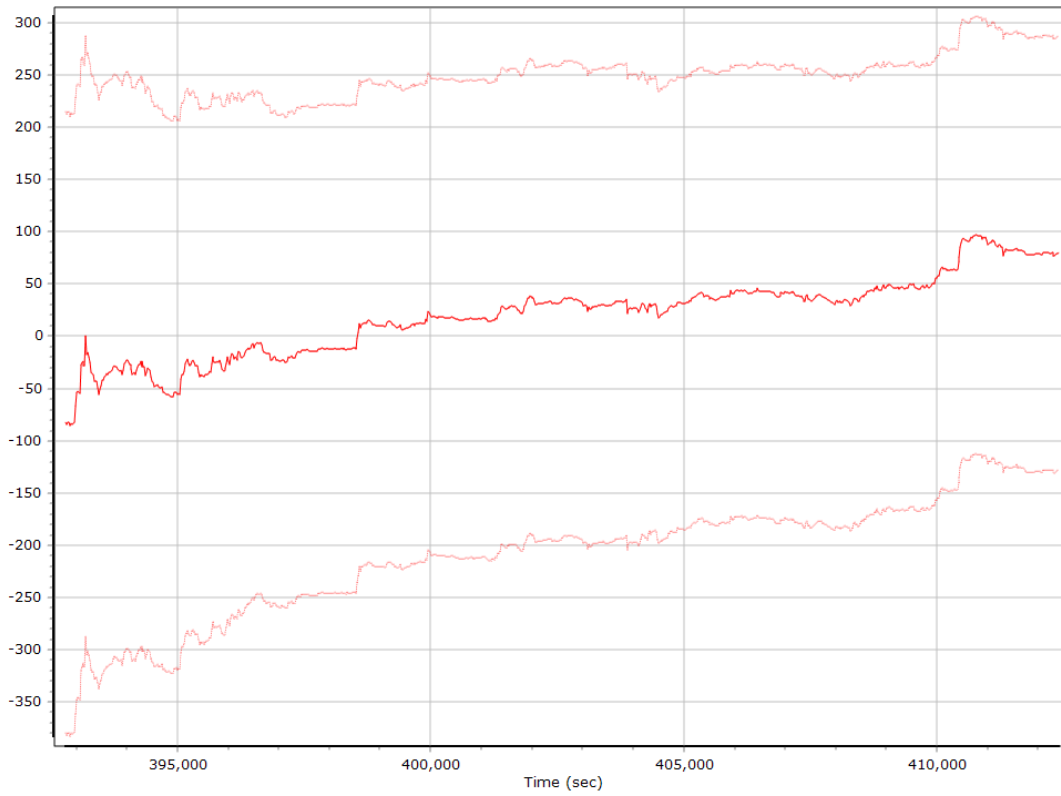
### Accelerometer Scale Error (ppm)



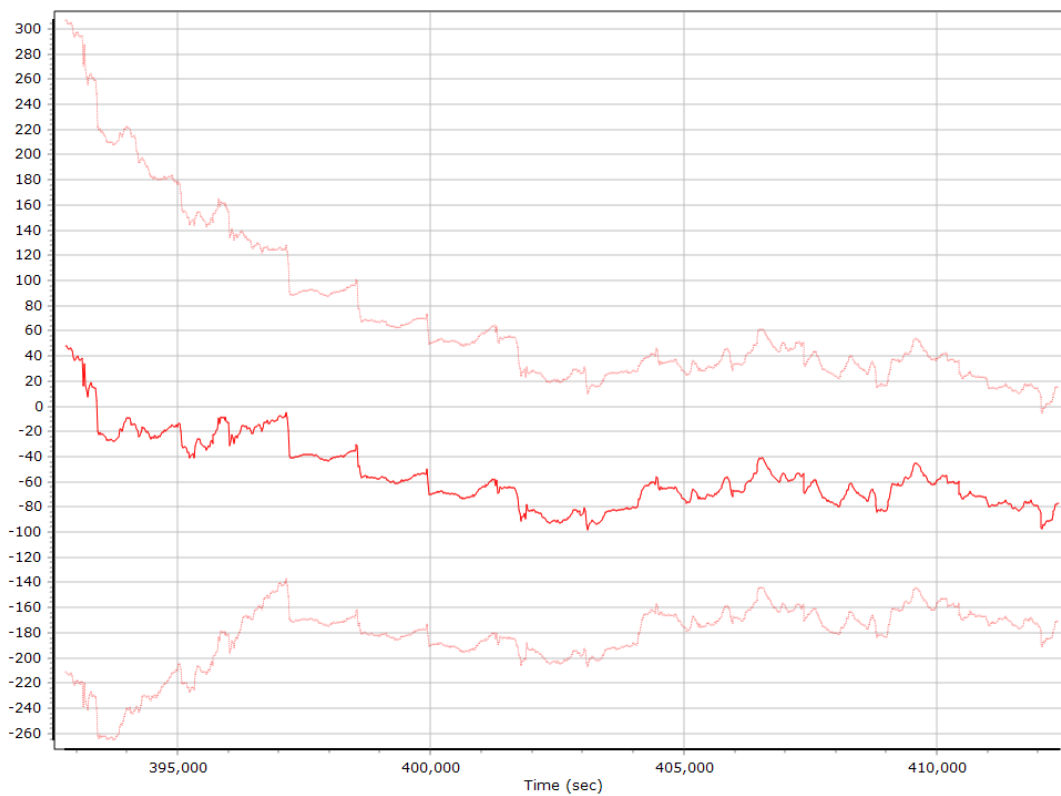
### X Accelerometer Scale Error (ppm)



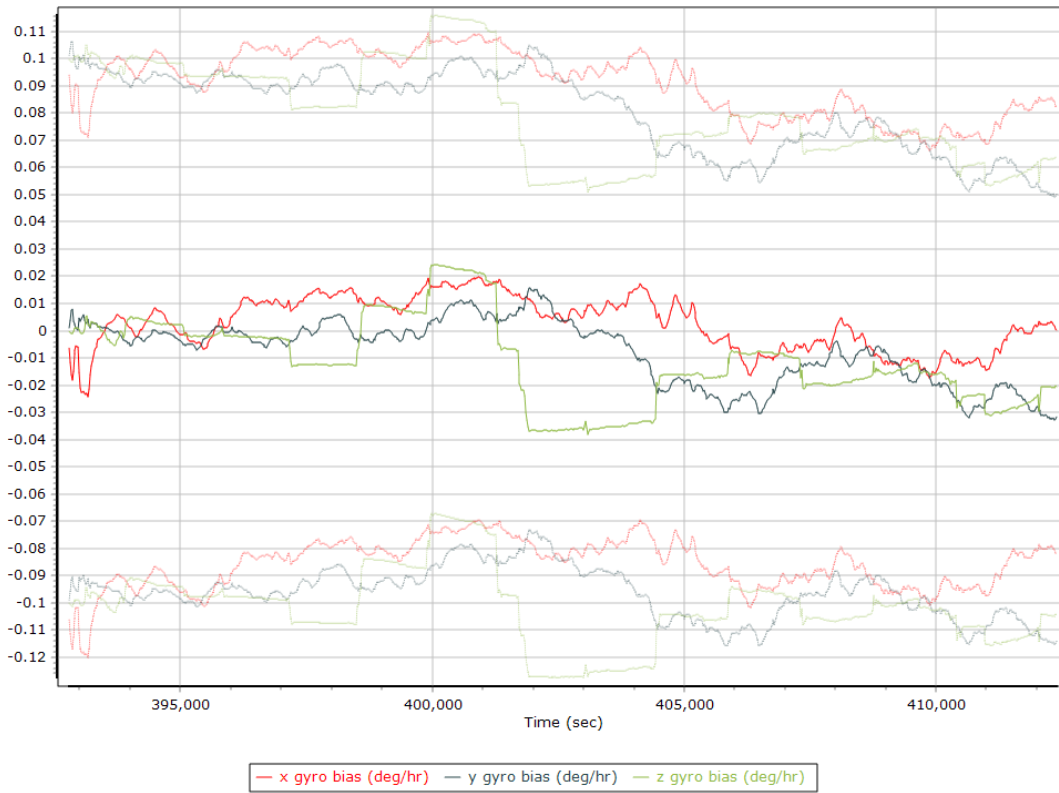
### Y Accelerometer Scale Error (ppm)



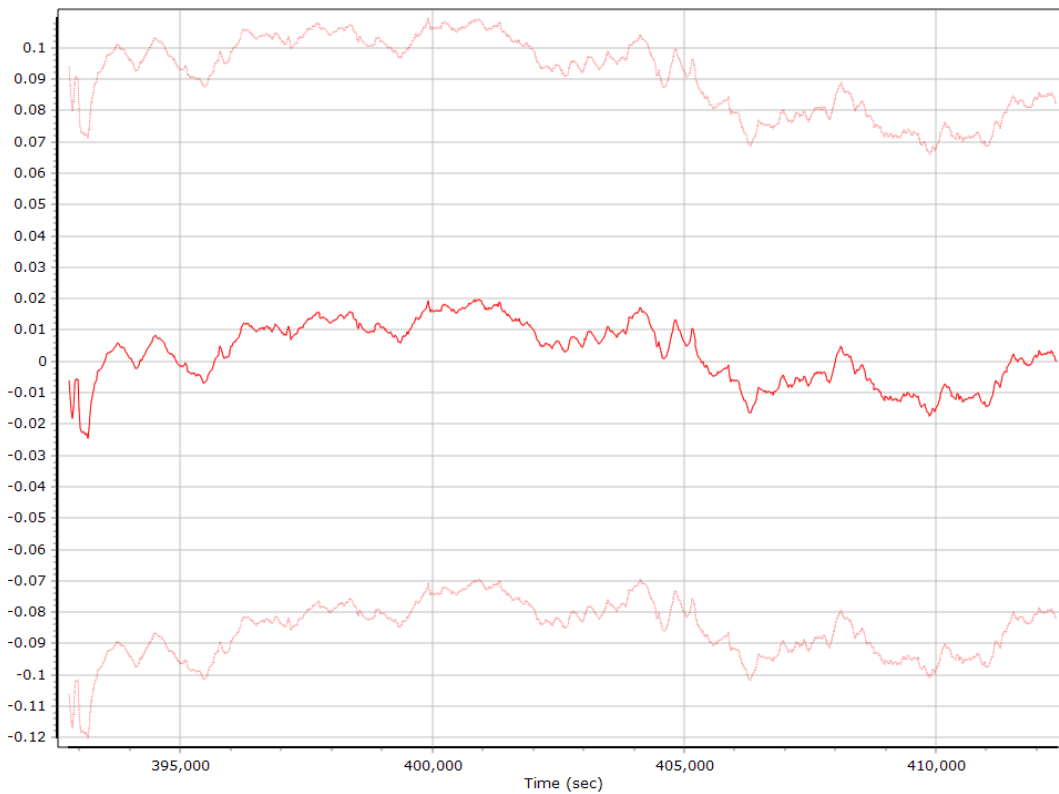
### Z Accelerometer Scale Error (ppm)



### Gyro Bias (deg/h)

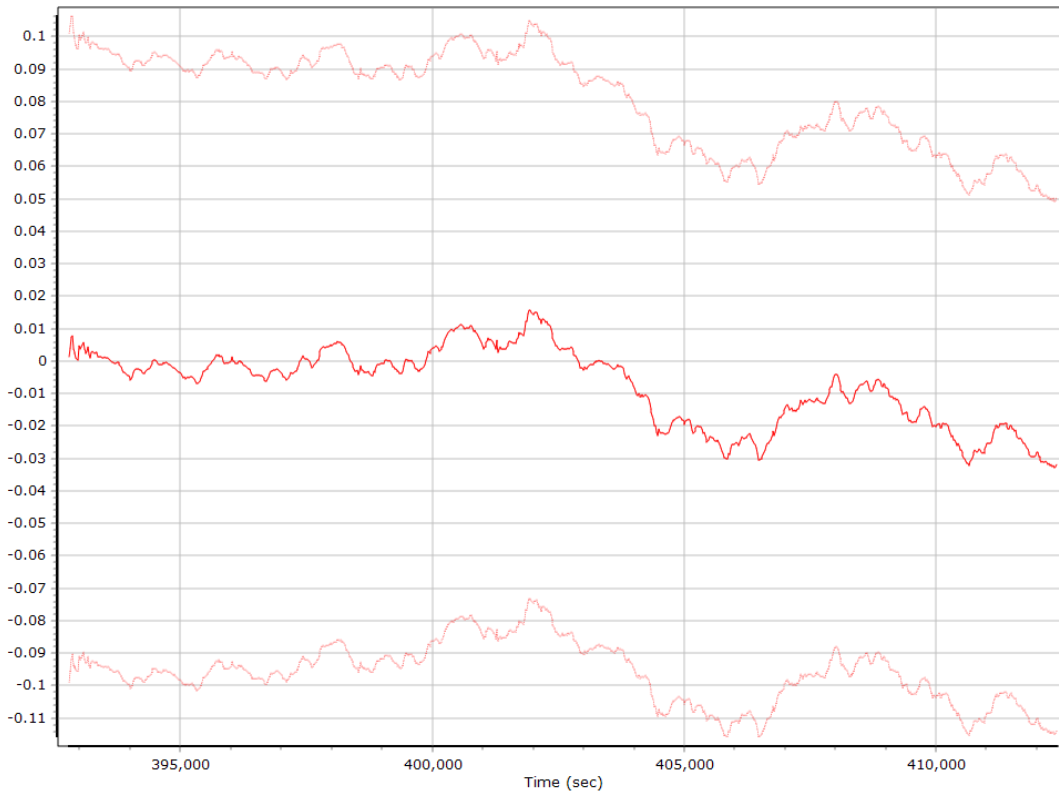


### X Gyro Bias (deg/h)

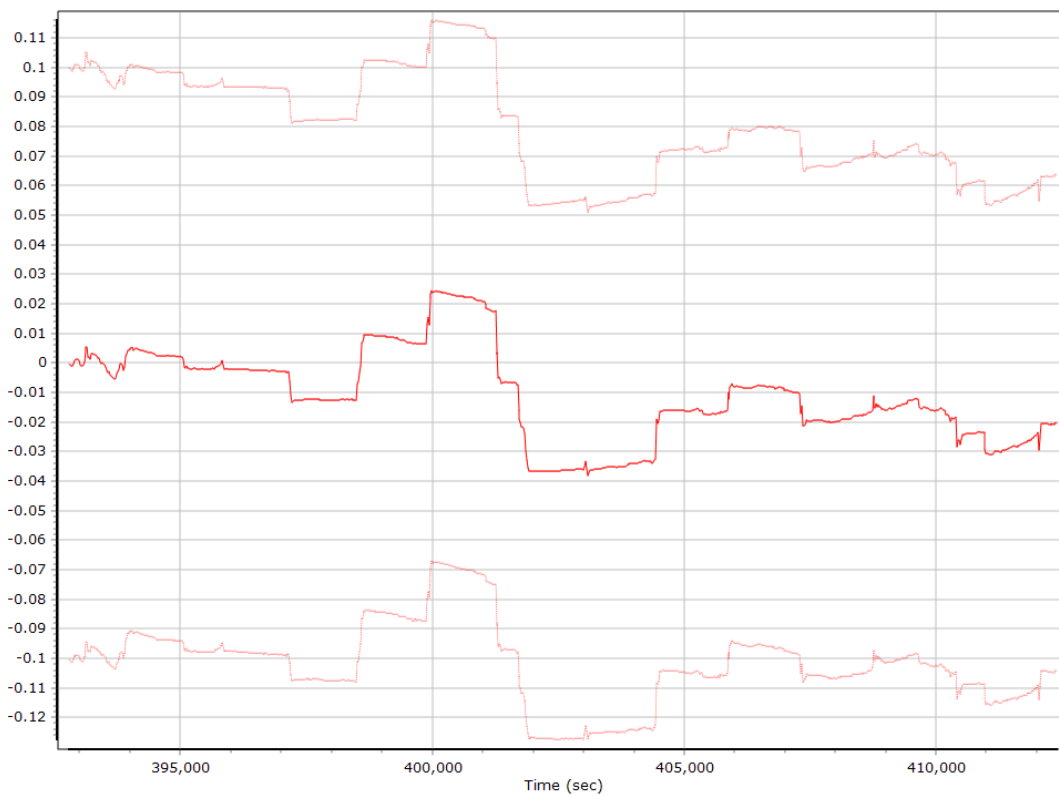




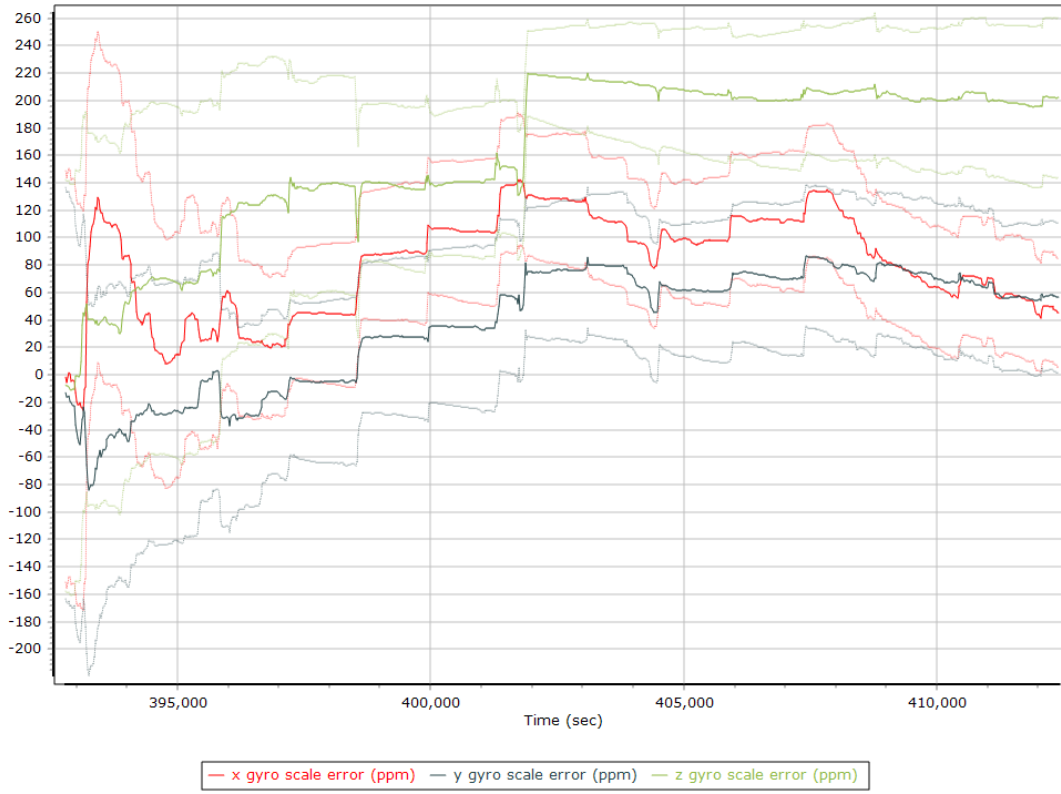
### Y Gyro Bias (deg/h)



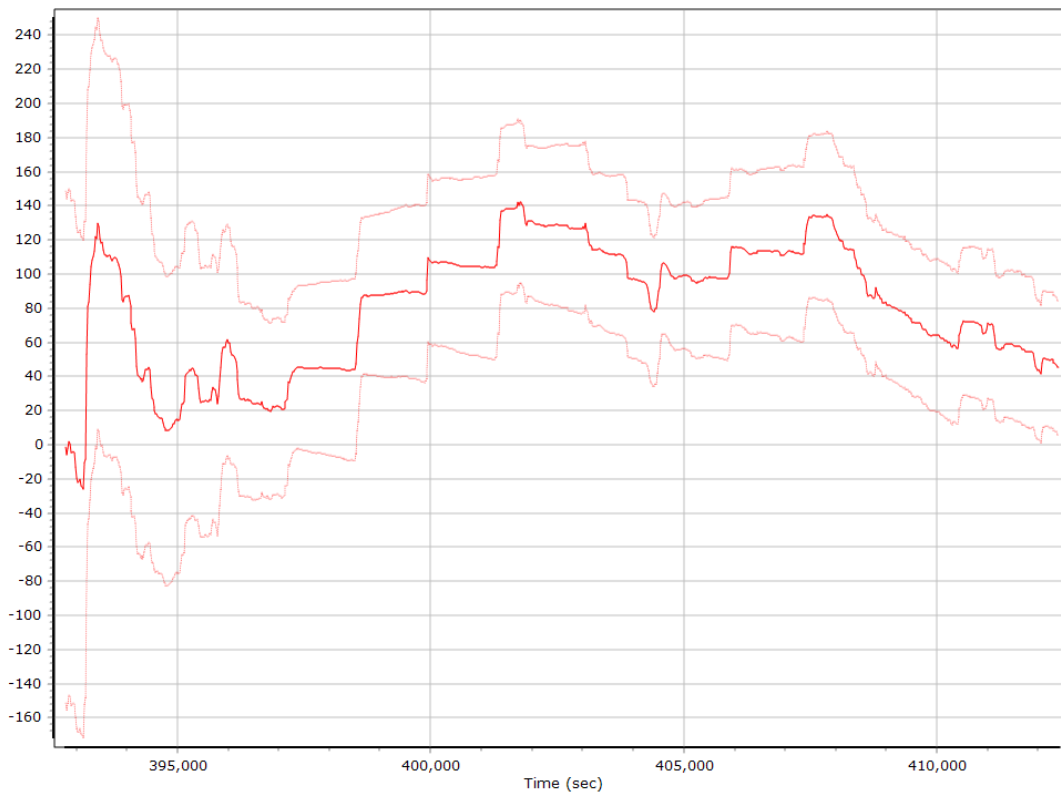
### Z Gyro Bias (deg/h)



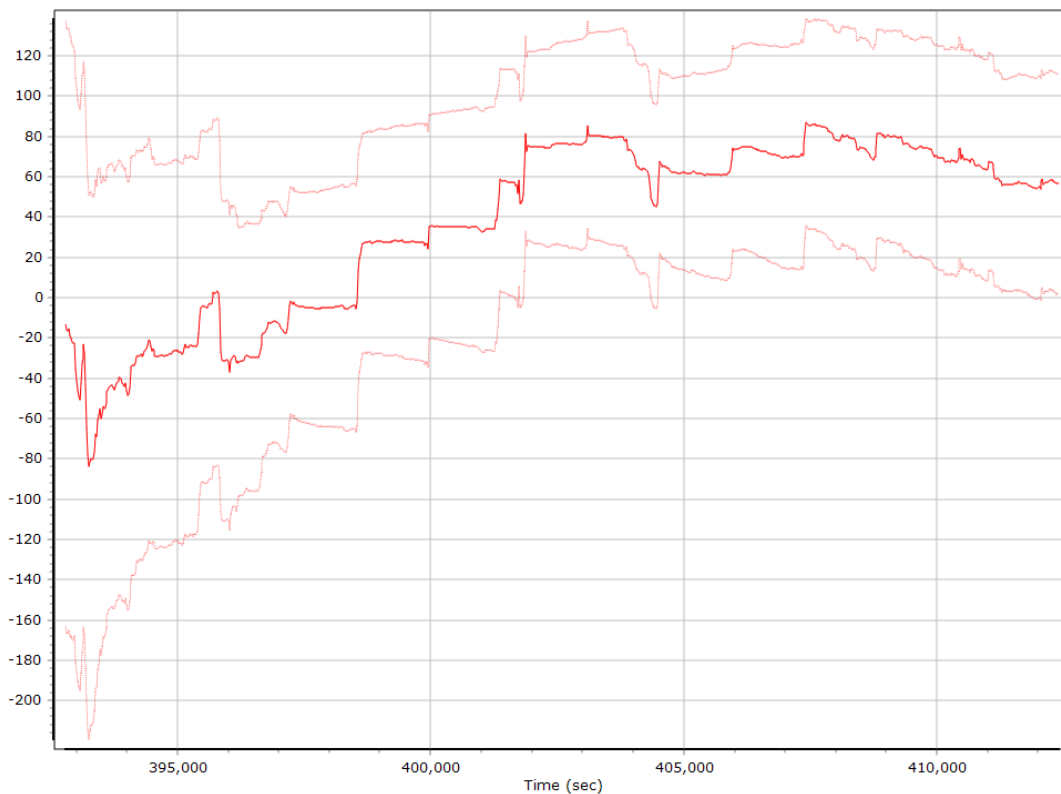
### Gyro Scale Error (ppm)



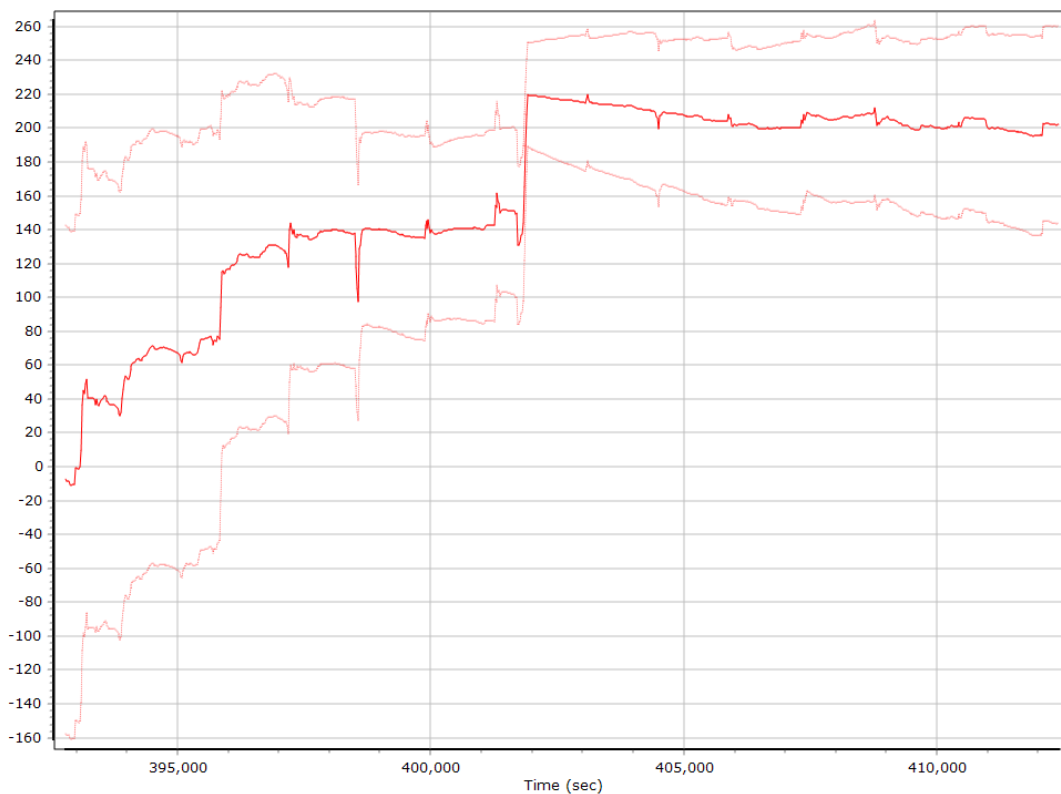
### X Gyro Scale Error (ppm)



### Y Gyro Scale Error (ppm)

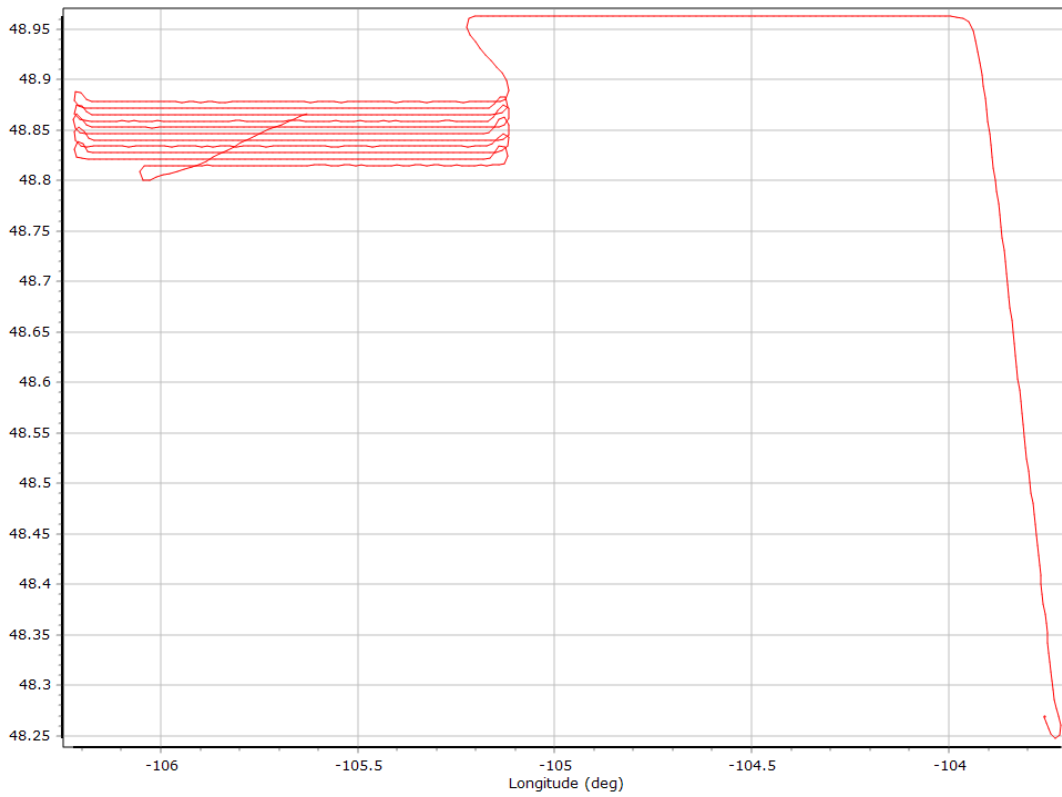


### Z Gyro Scale Error (ppm)

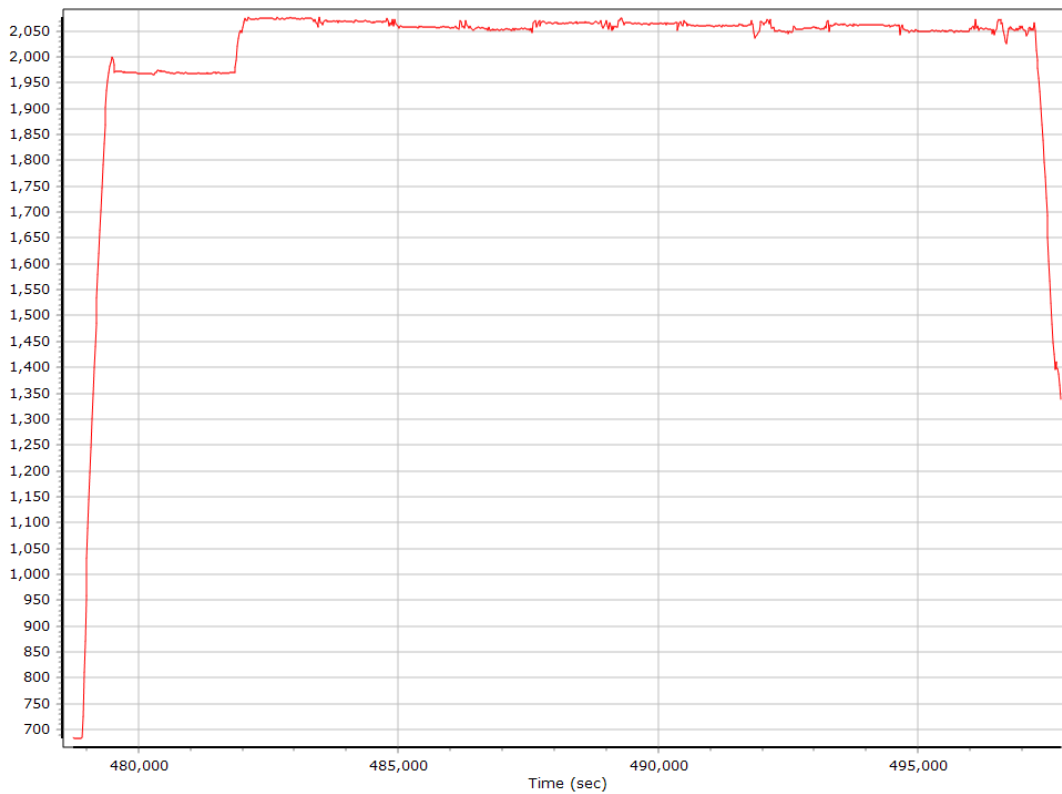


## Smoothed Trajectory Information

### Top View



### Altitude

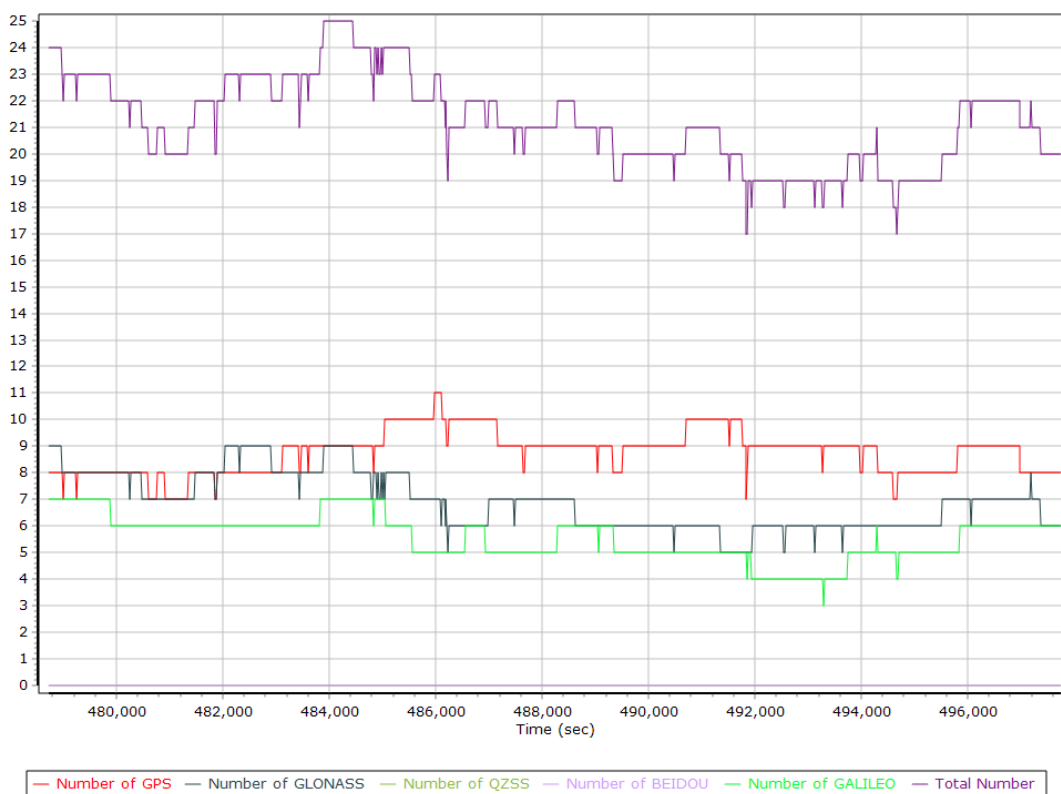


## GNSS QC

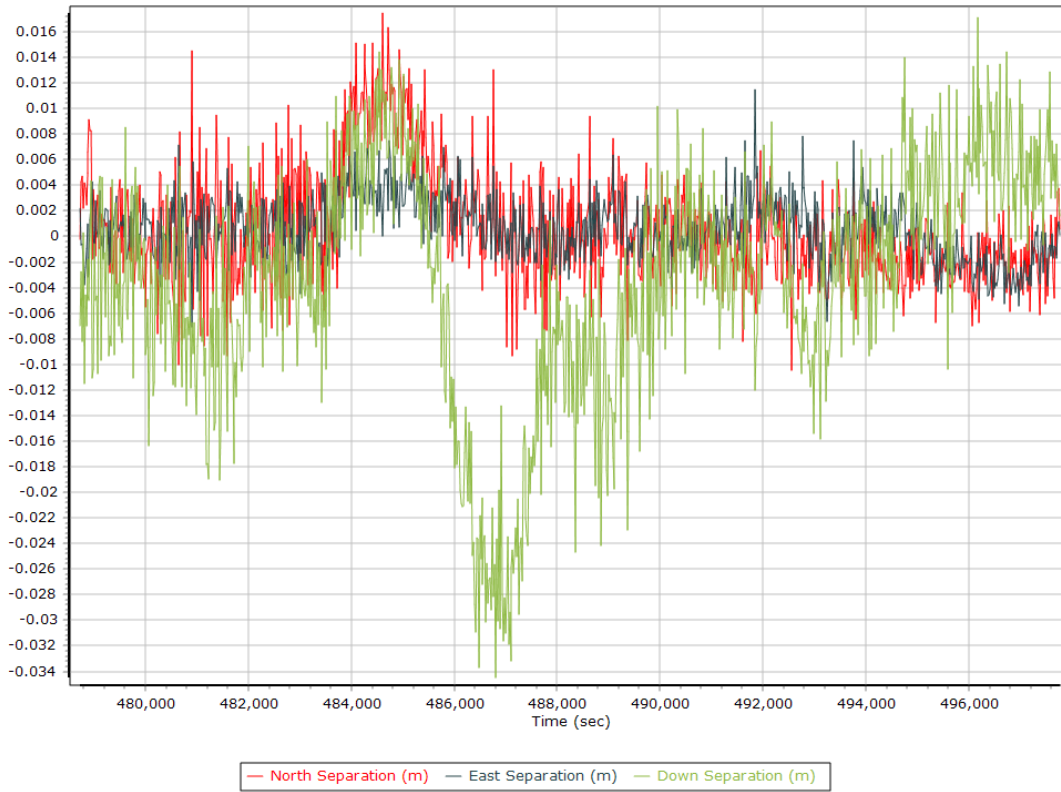
### GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	7	11	9
Number of GLONASS SV	0	9	7
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	0	0
Number of GALILEO SV	3	7	6
Total number of SV	15	25	21
PDOP	0.93	1.44	1.12
QC Solution Gaps	0.00	0.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	19166.00	0.00	0.00
Percentage	100.00	0.00	0.00

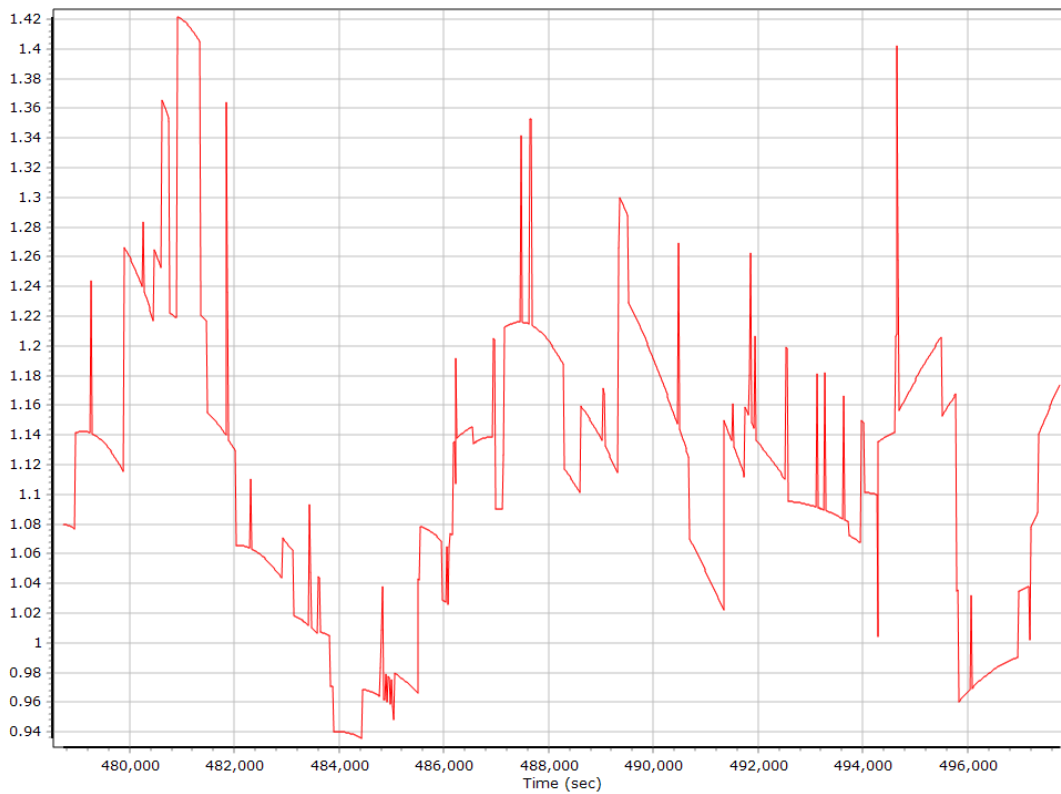
### Num SVs in solution



## Forward/Reverse Separation



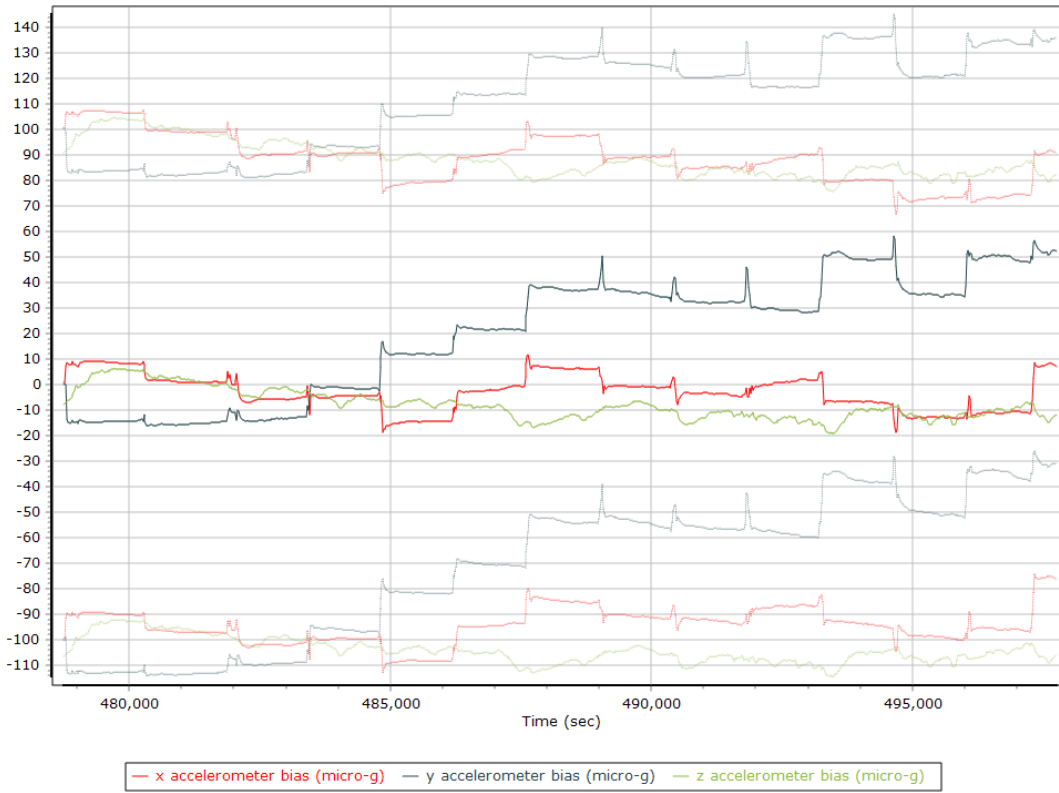
## PDOP



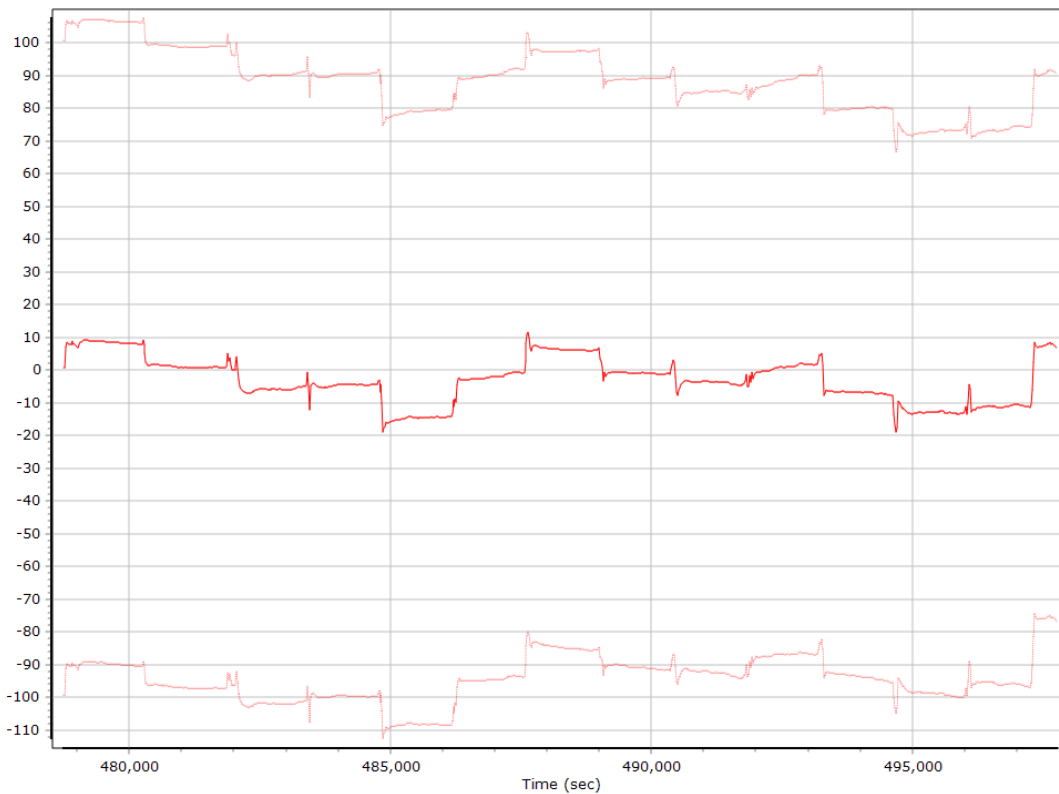
## IN-Fusion QC

### Forward Processed Estimated Errors, Reference Frame

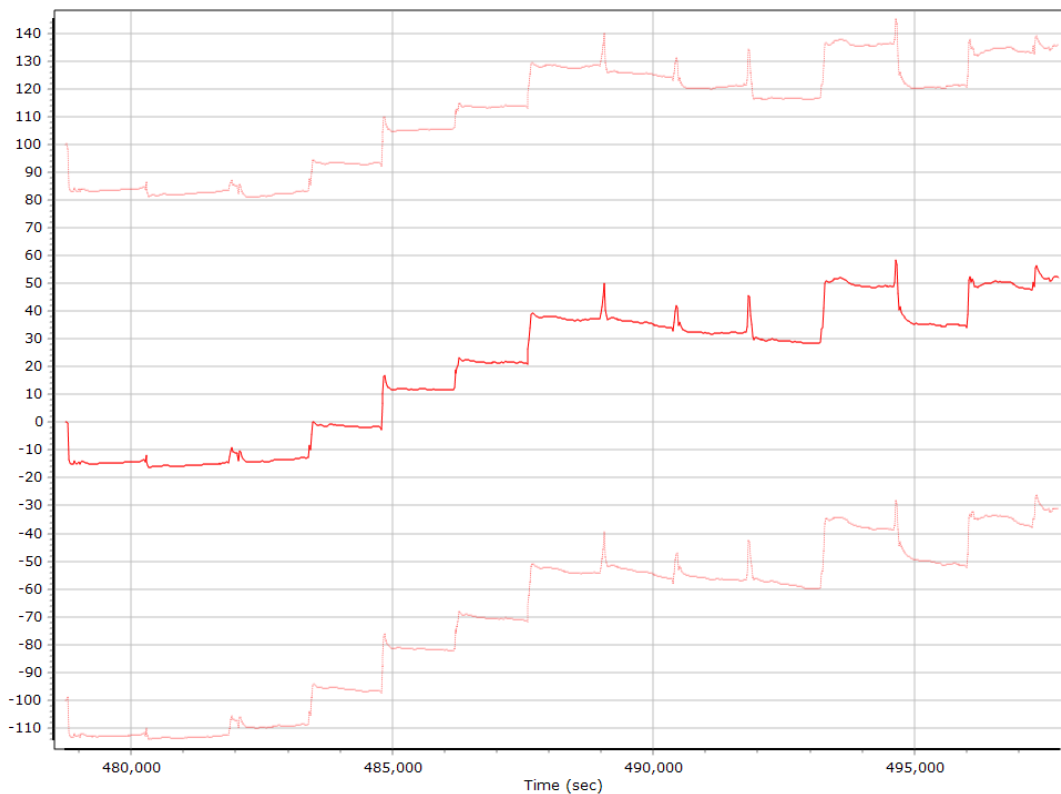
#### Accelerometer Bias (micro-g)



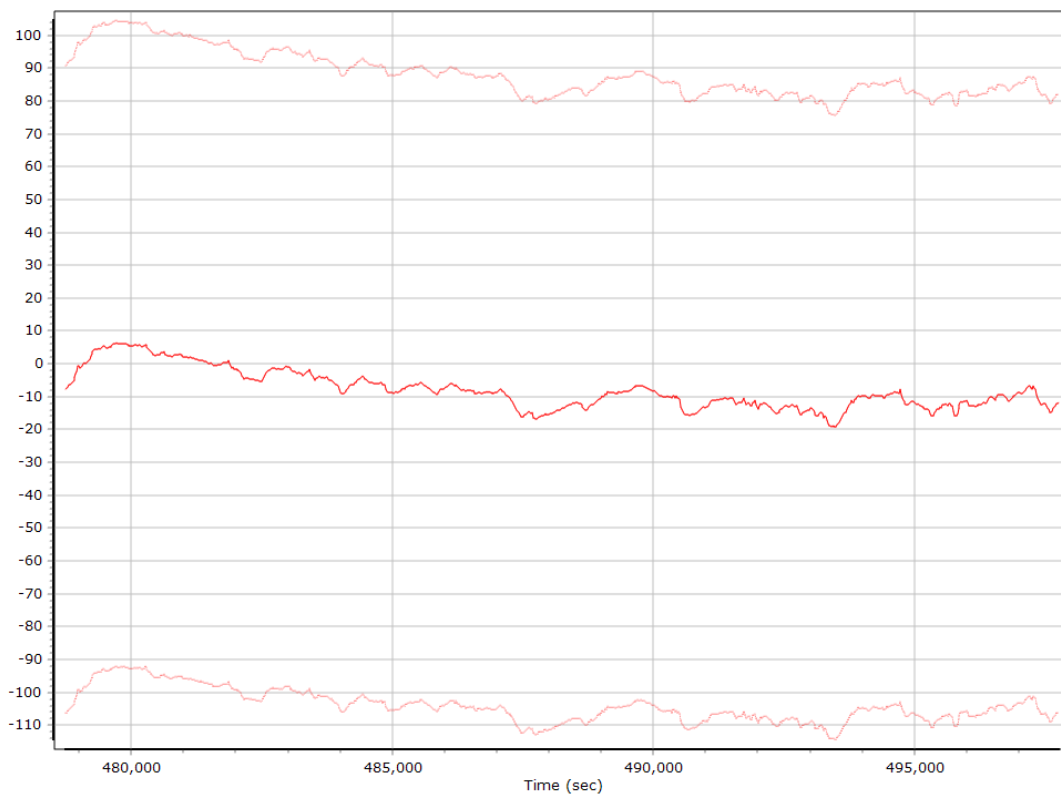
#### X Accelerometer Bias (micro-g)



### Y Accelerometer Bias (micro-g)

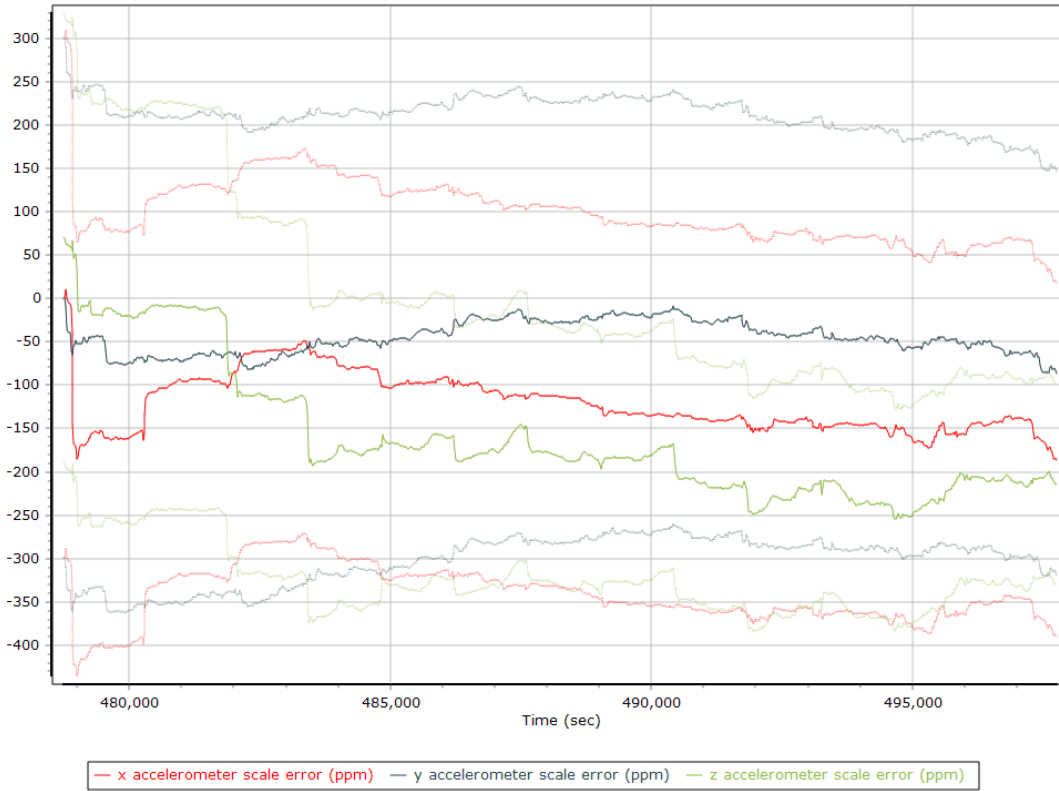


### Z Accelerometer Bias (micro-g)

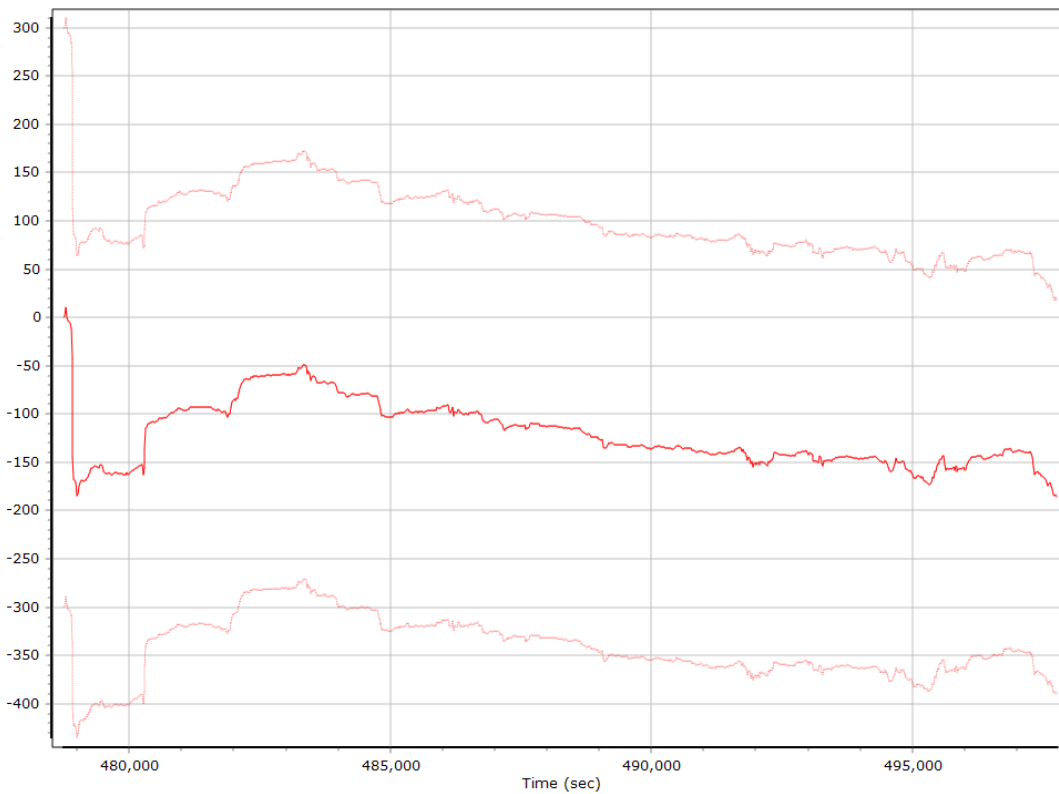




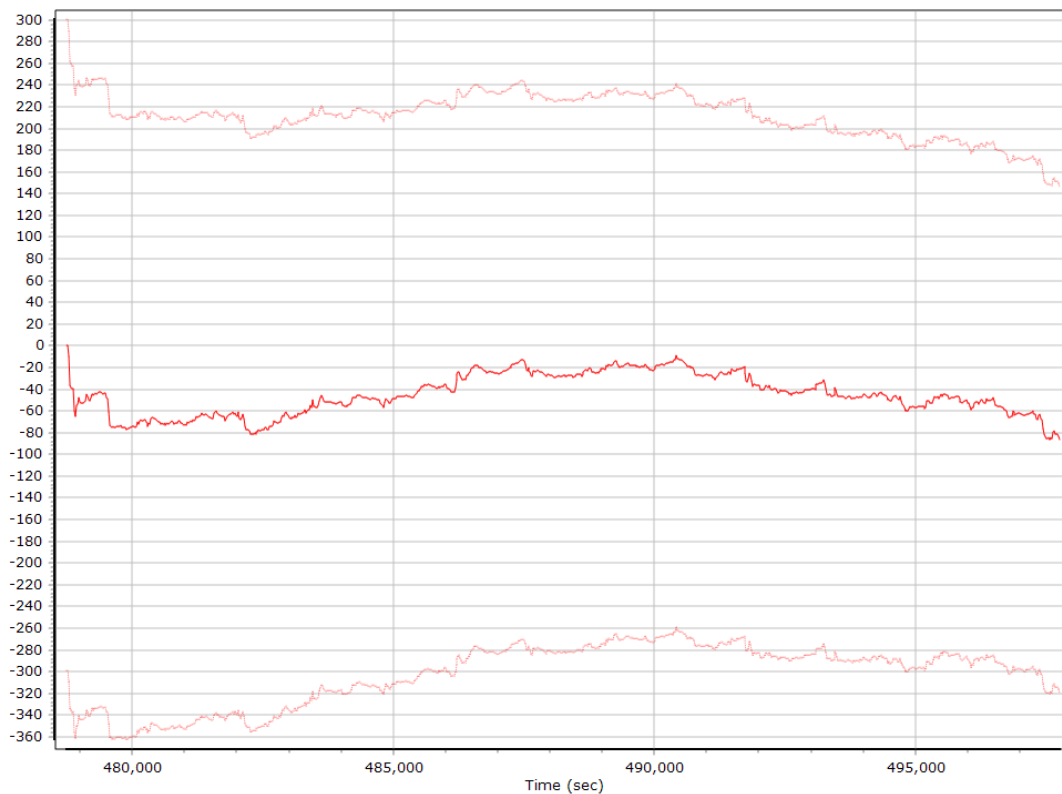
### Accelerometer Scale Error (ppm)



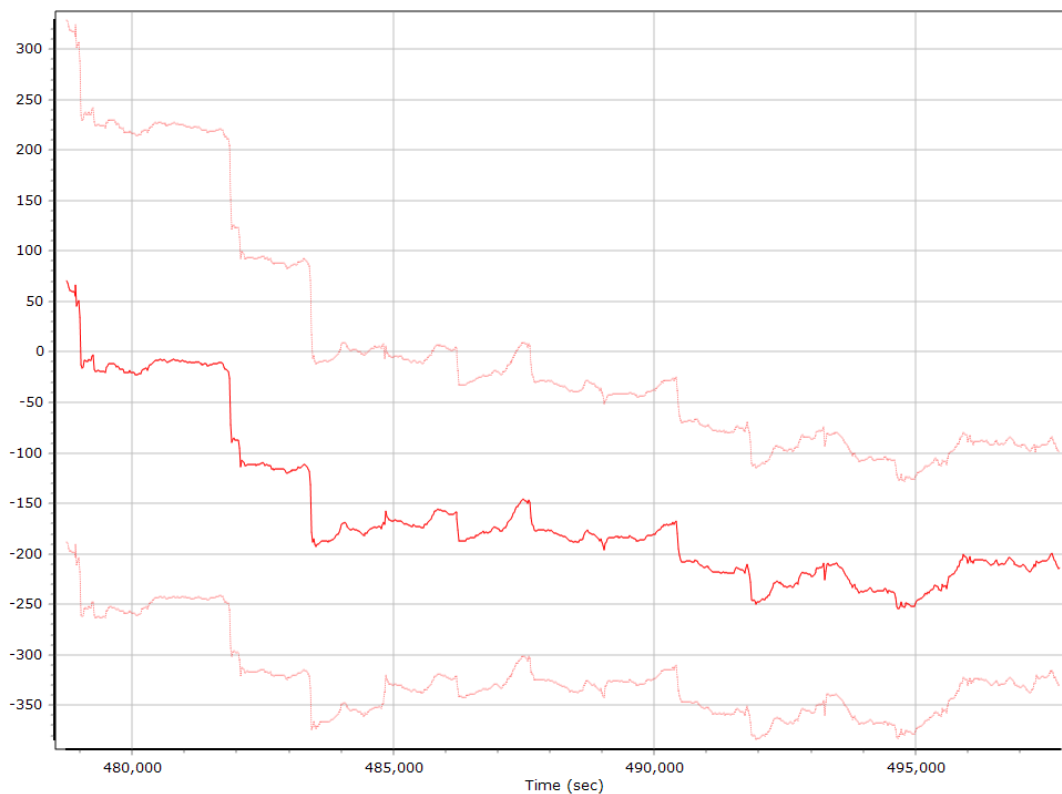
### X Accelerometer Scale Error (ppm)



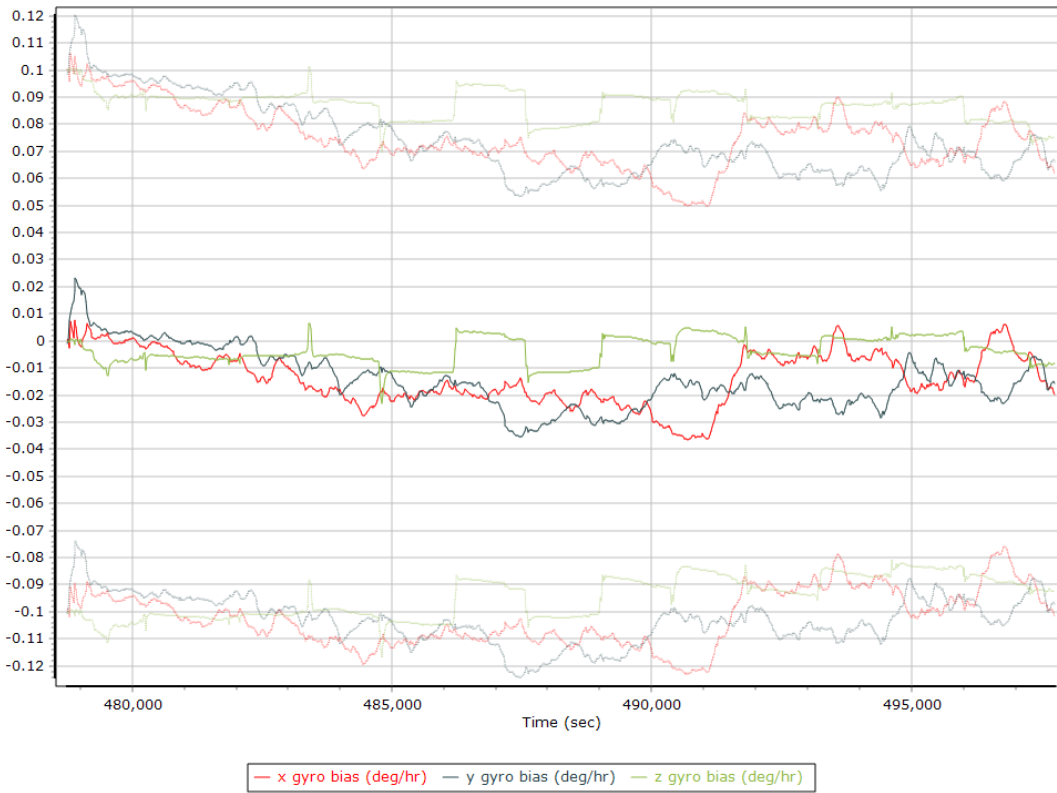
### Y Accelerometer Scale Error (ppm)



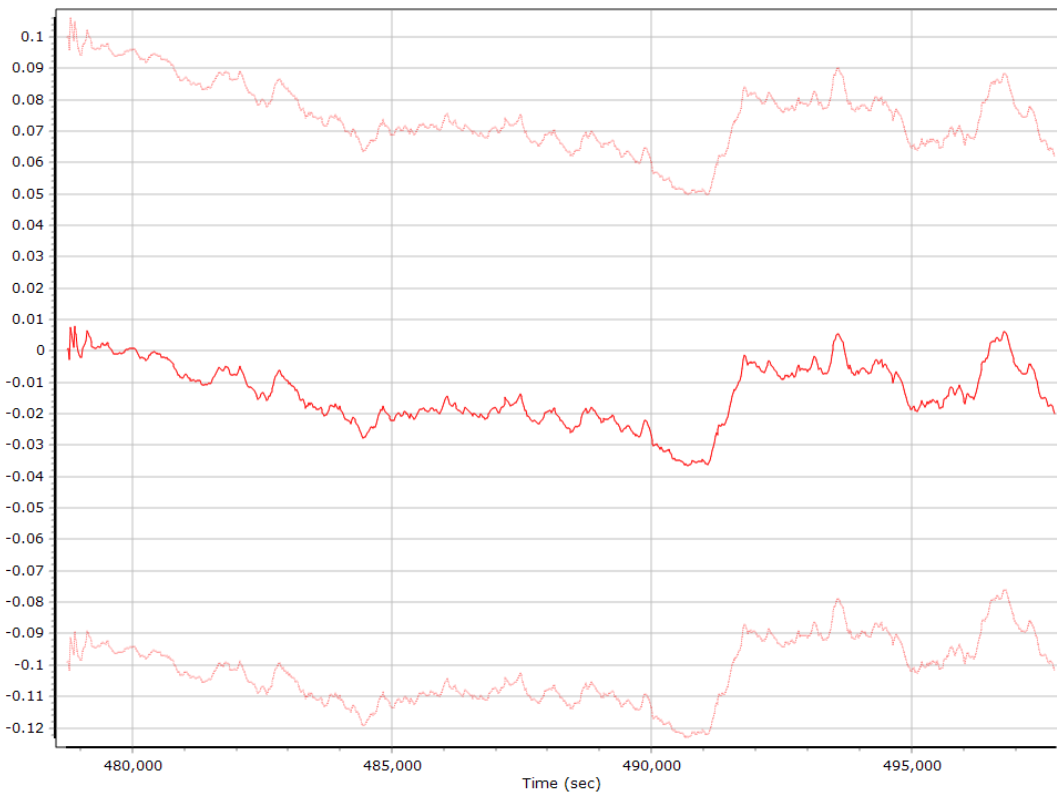
### Z Accelerometer Scale Error (ppm)



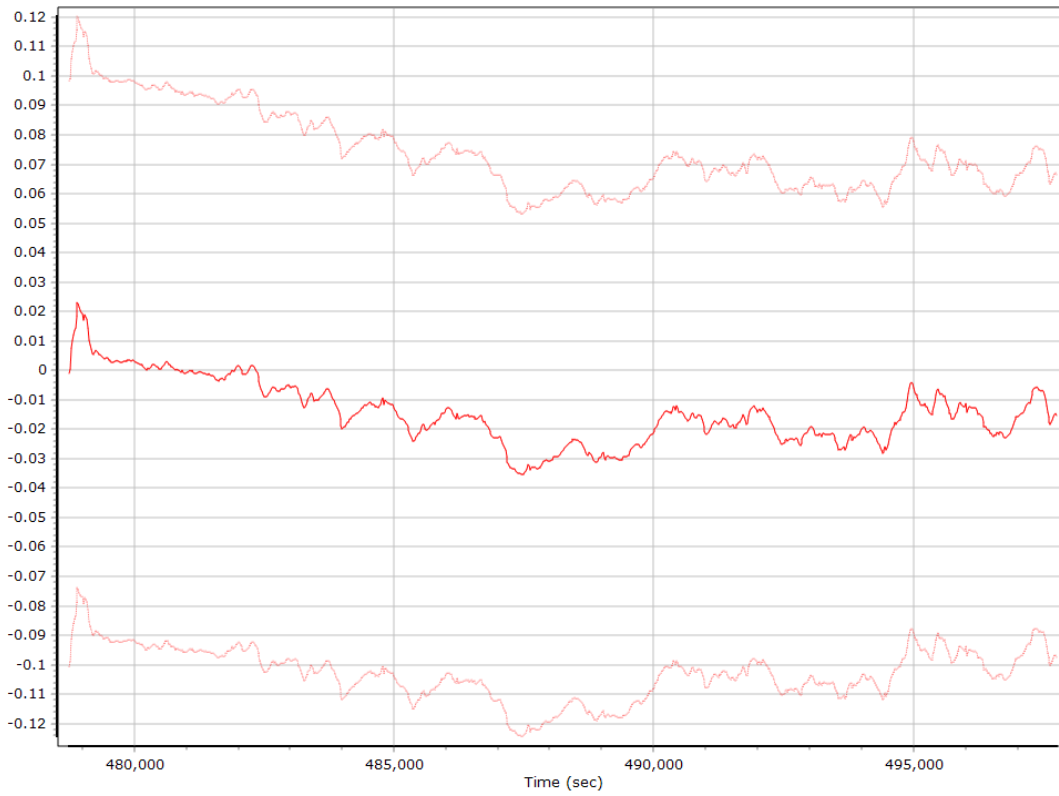
### Gyro Bias (deg/h)



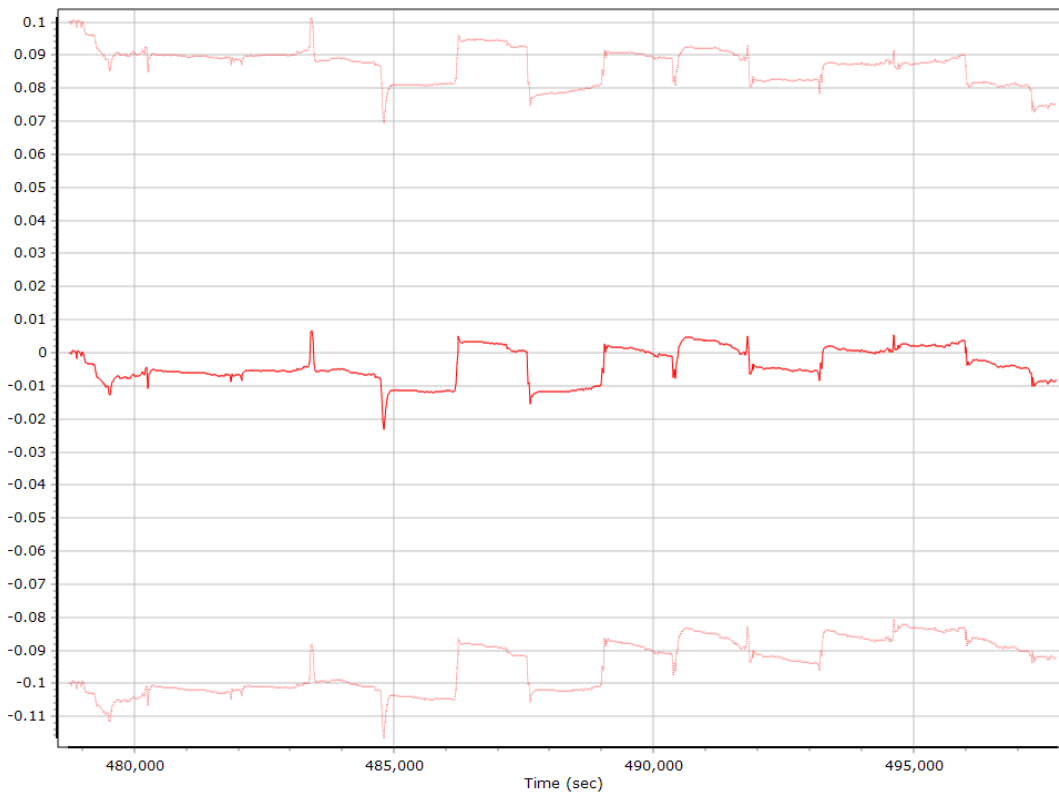
### X Gyro Bias (deg/h)



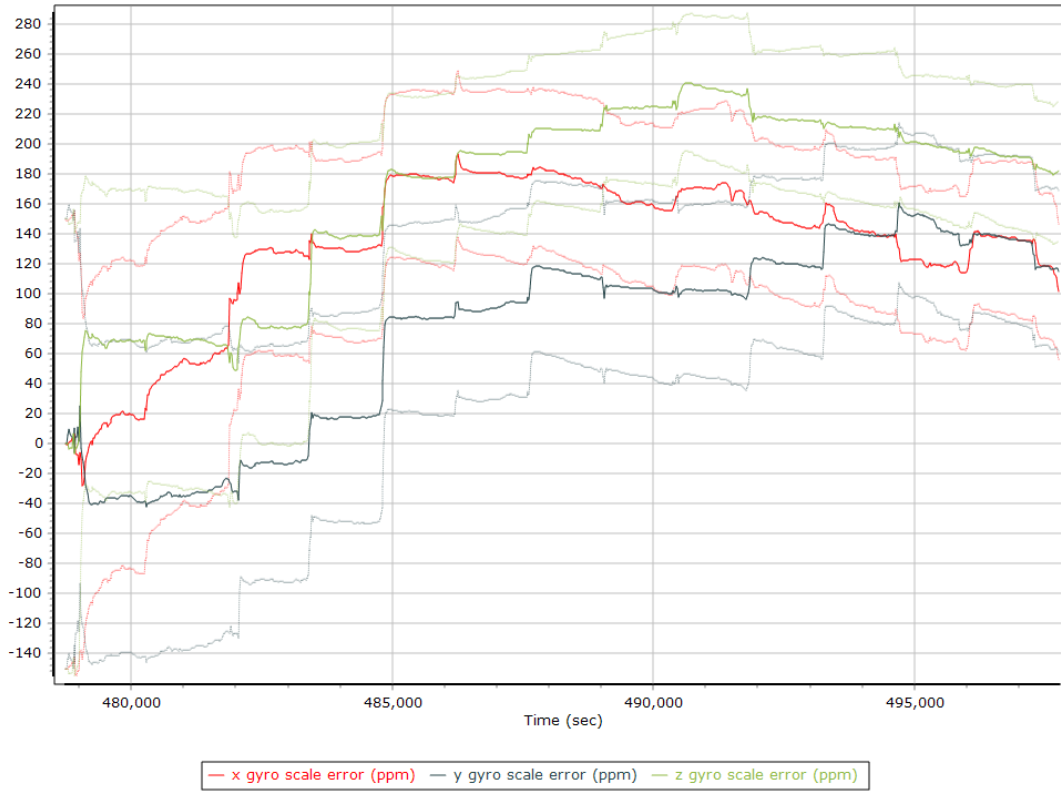
### Y Gyro Bias (deg/h)



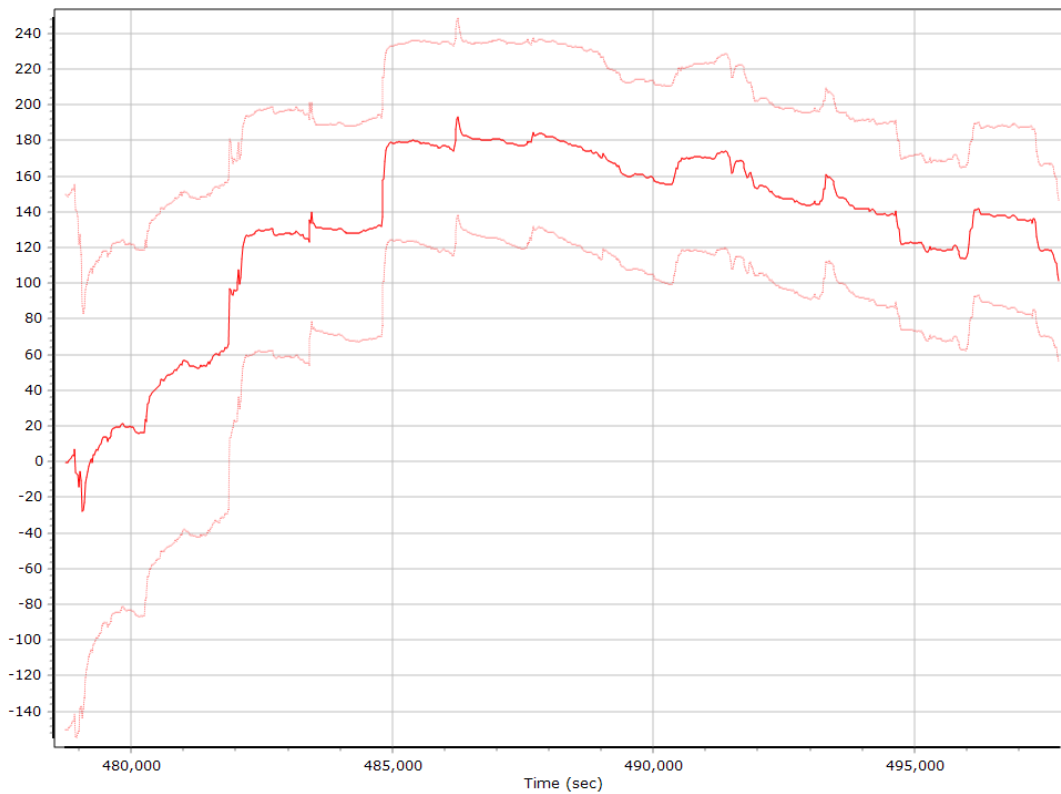
### Z Gyro Bias (deg/h)



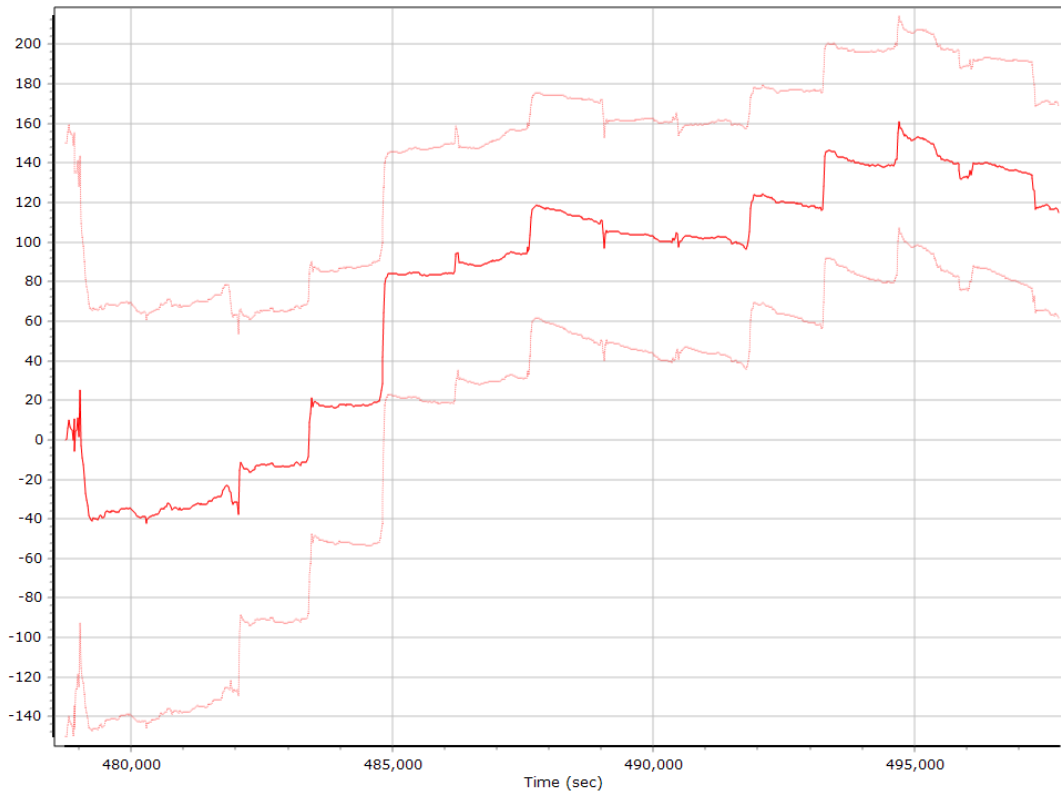
### Gyro Scale Error (ppm)



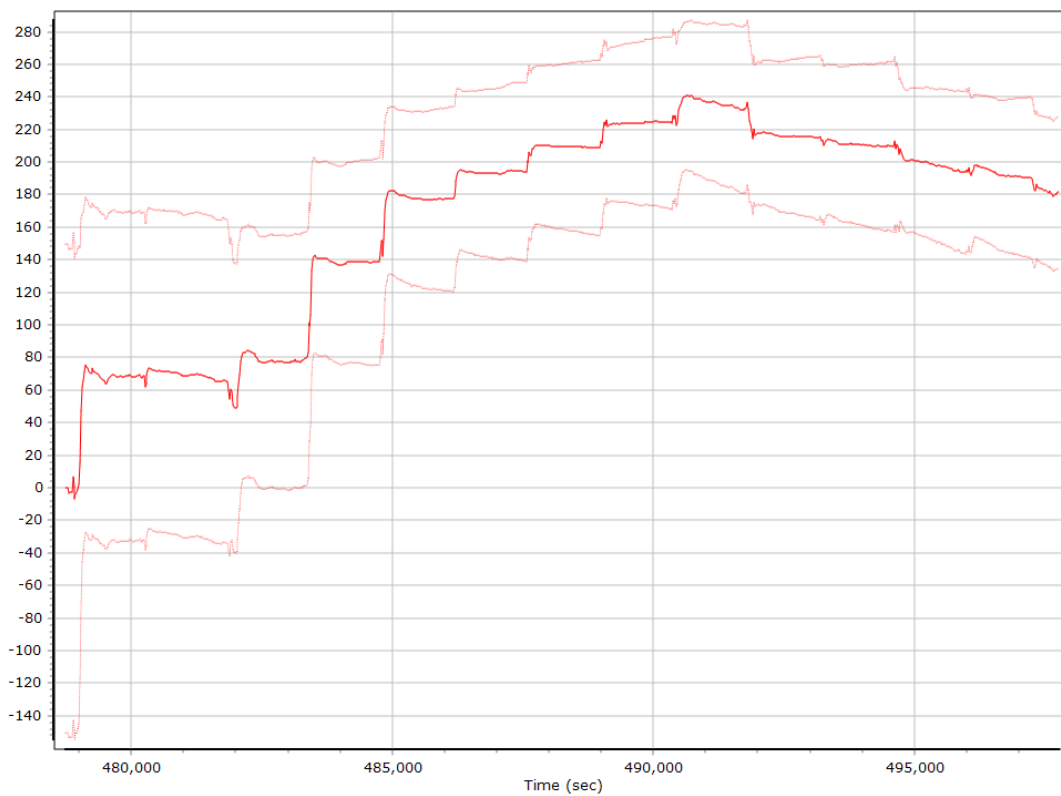
### X Gyro Scale Error (ppm)



### Y Gyro Scale Error (ppm)

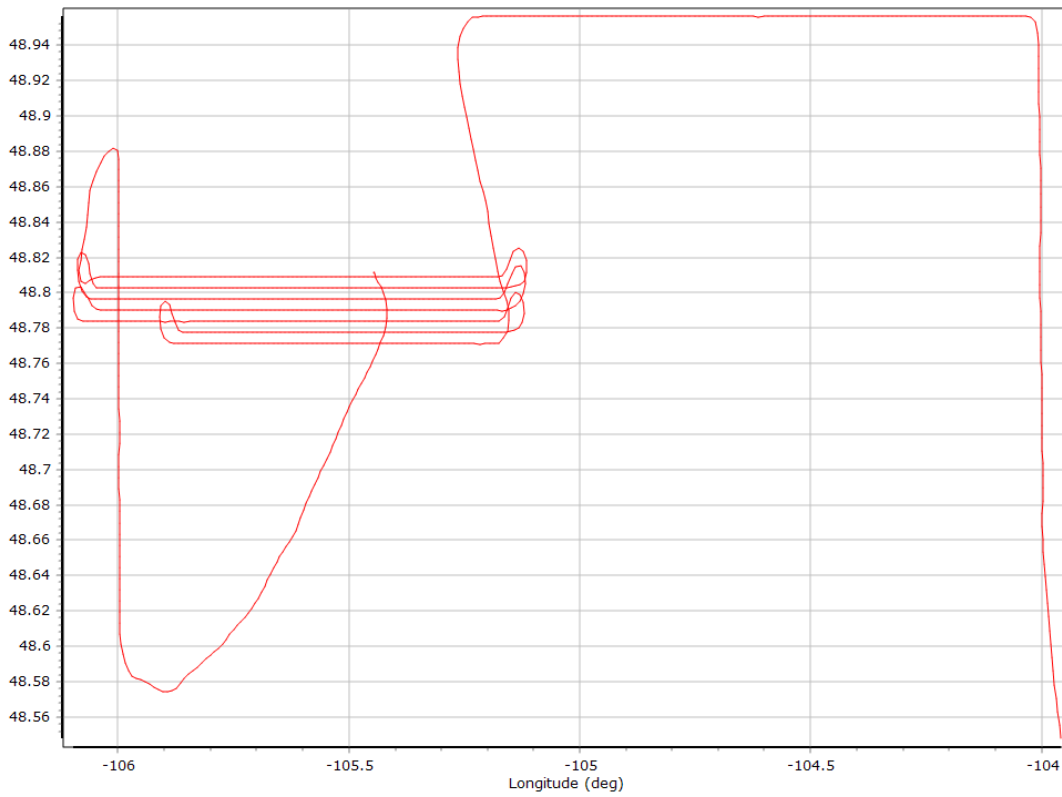


### Z Gyro Scale Error (ppm)

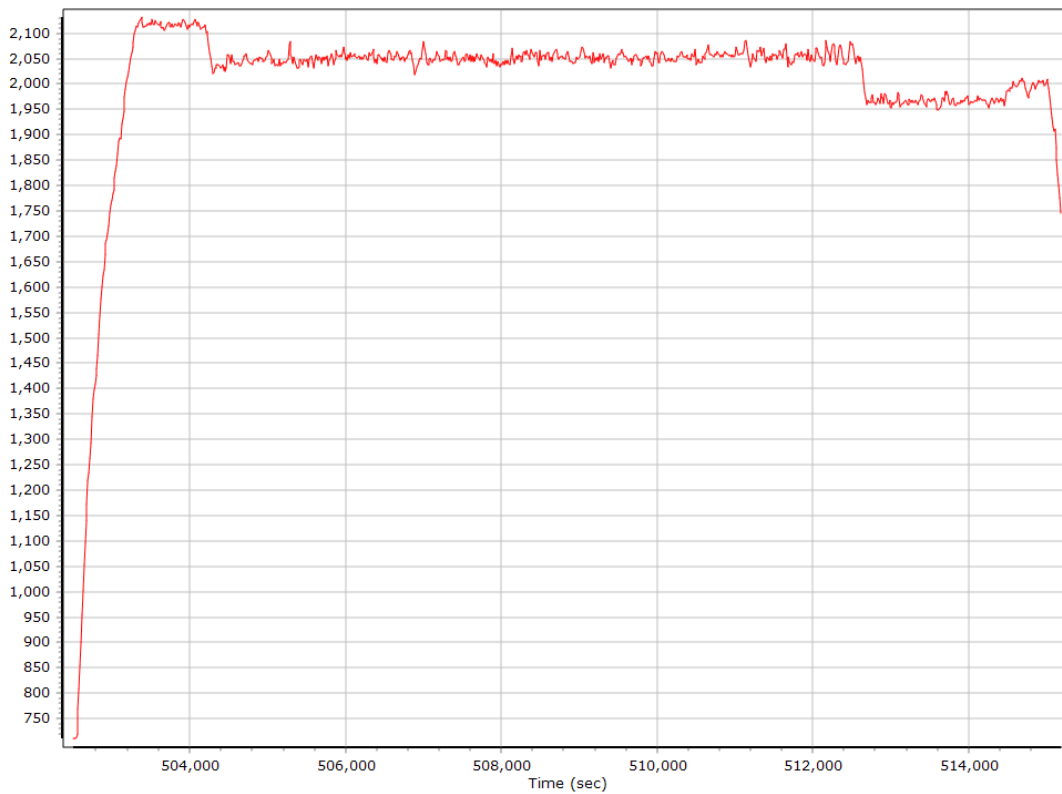


## Smoothed Trajectory Information

### Top View



### Altitude

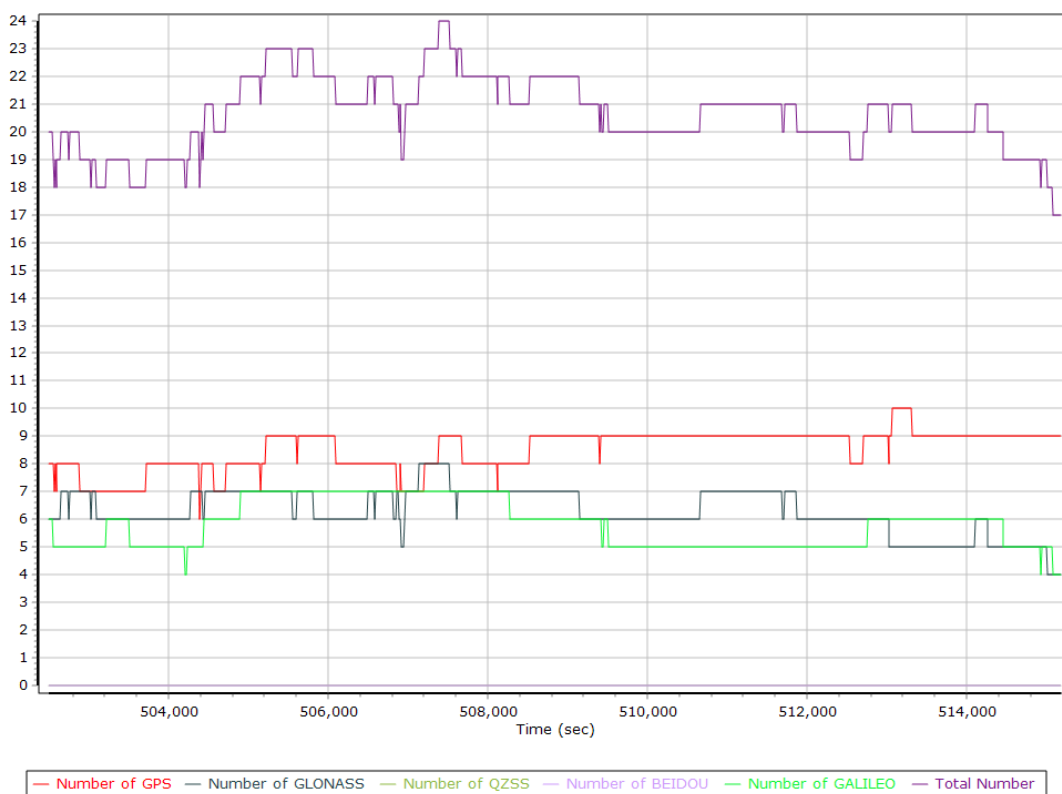


## GNSS QC

### GNSS QC Statistics

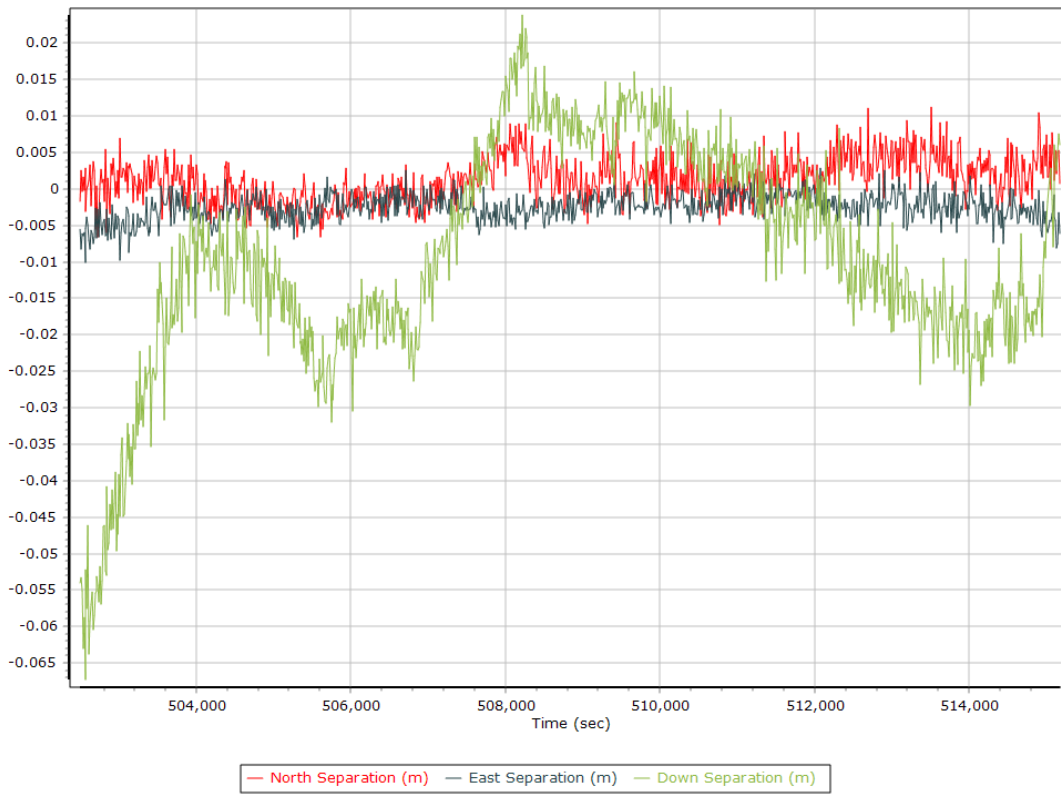
Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	6	10	9
Number of GLONASS SV	0	8	6
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	0	0
Number of GALILEO SV	4	7	6
Total number of SV	13	24	21
PDOP	0.97	1.50	1.17
QC Solution Gaps	0.00	0.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	12965.00	0.00	0.00
Percentage	100.00	0.00	0.00

### Num SVs in solution

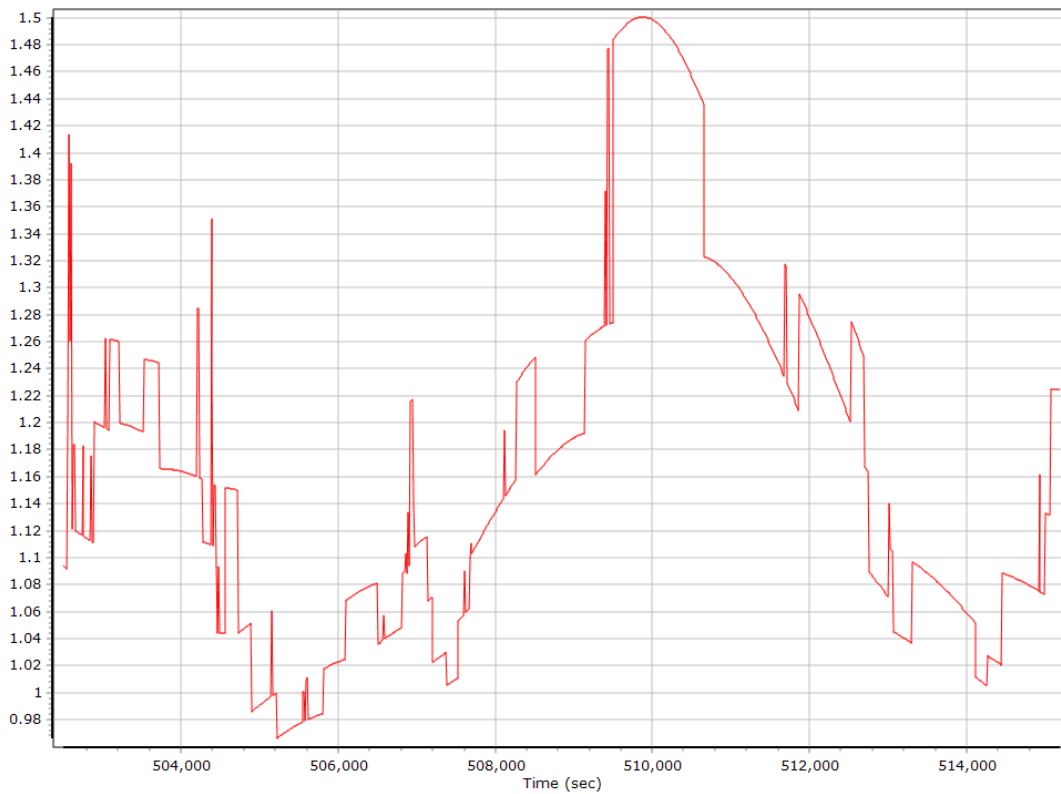




## Forward/Reverse Separation



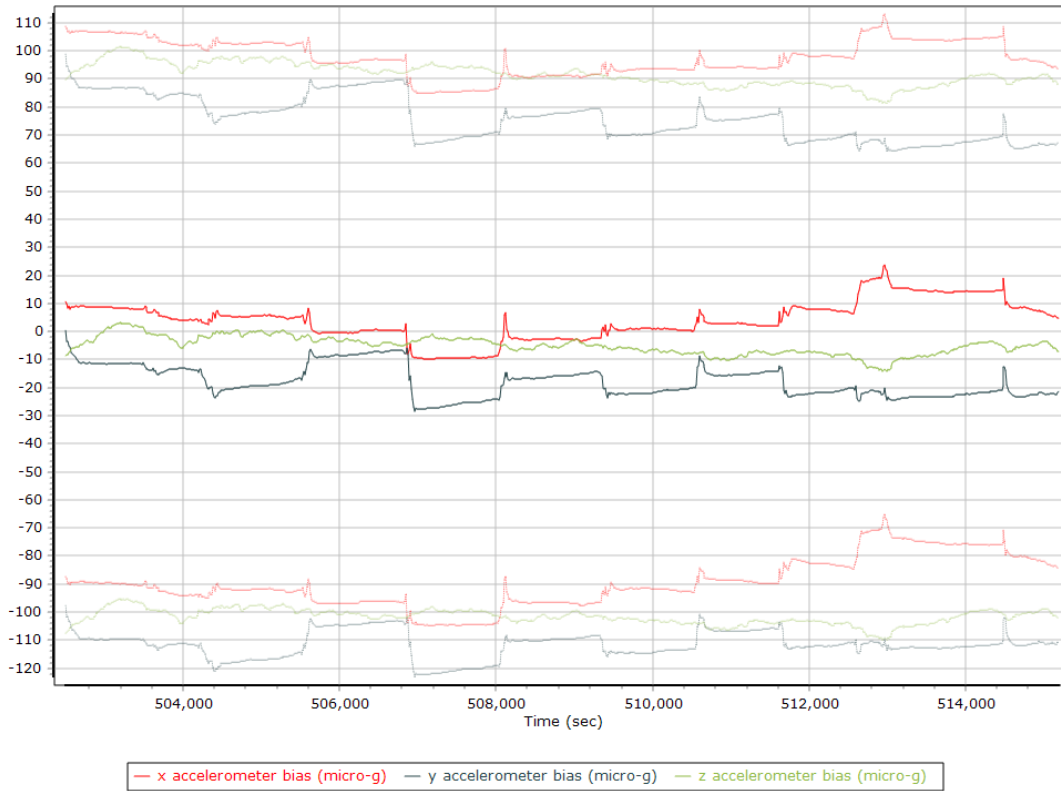
## PDOP



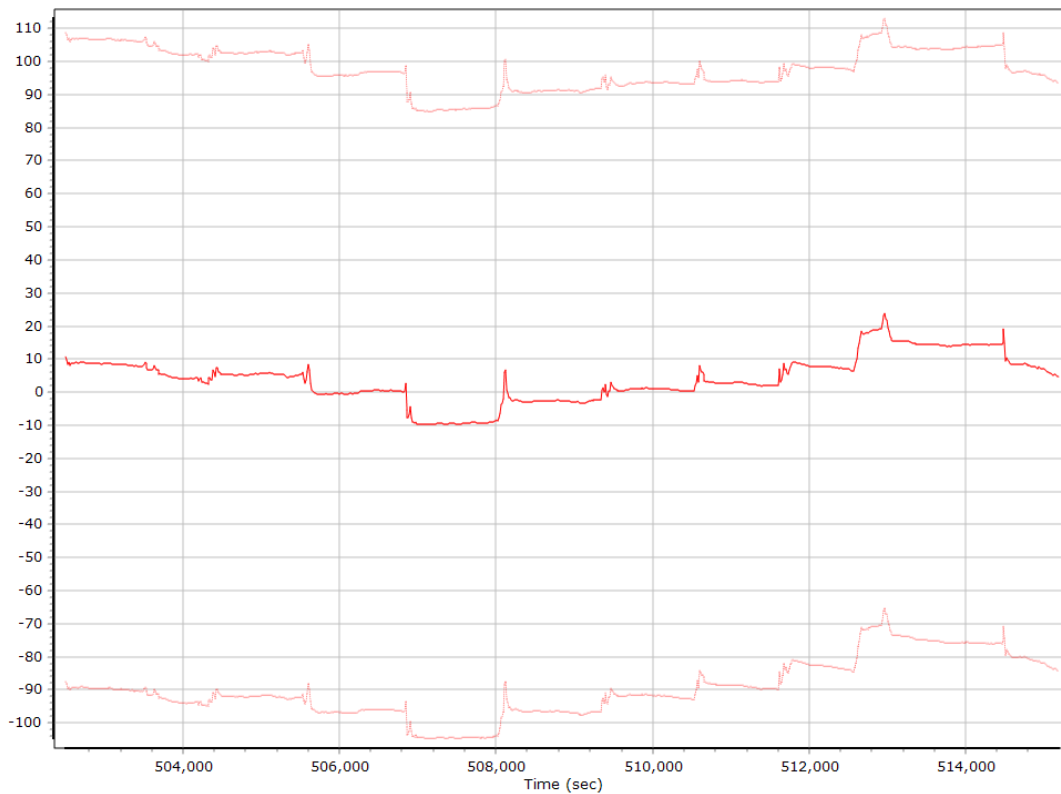
## IN-Fusion QC

### Forward Processed Estimated Errors, Reference Frame

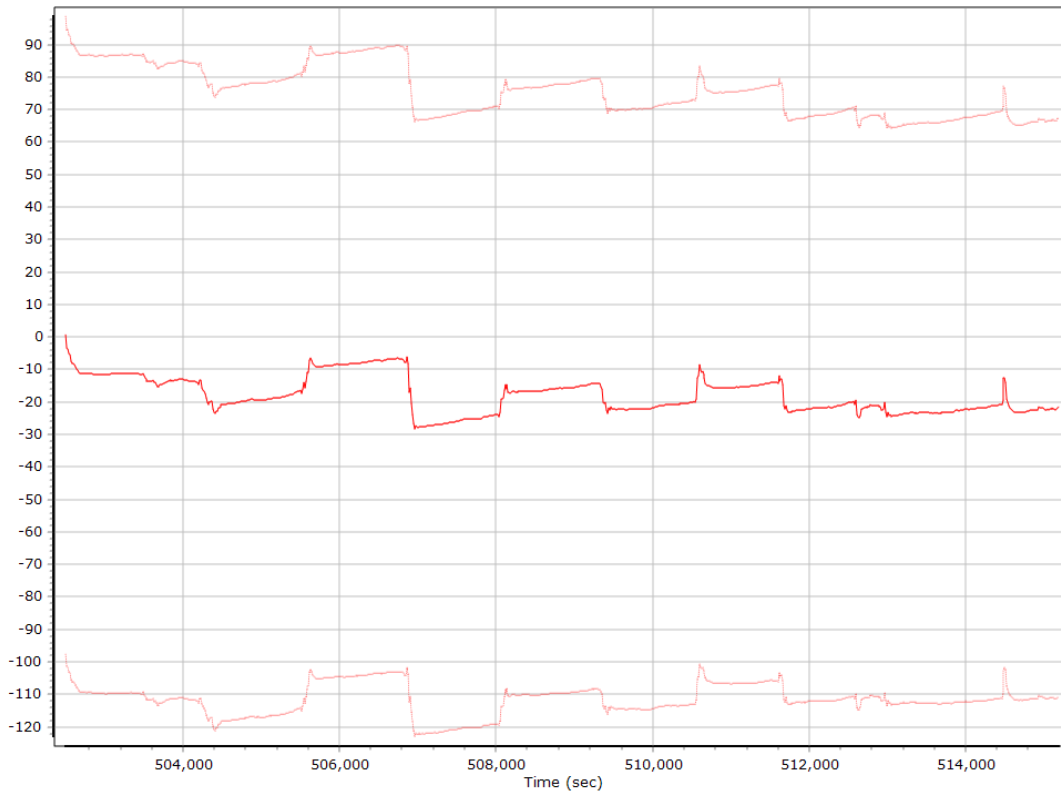
#### Accelerometer Bias (micro-g)



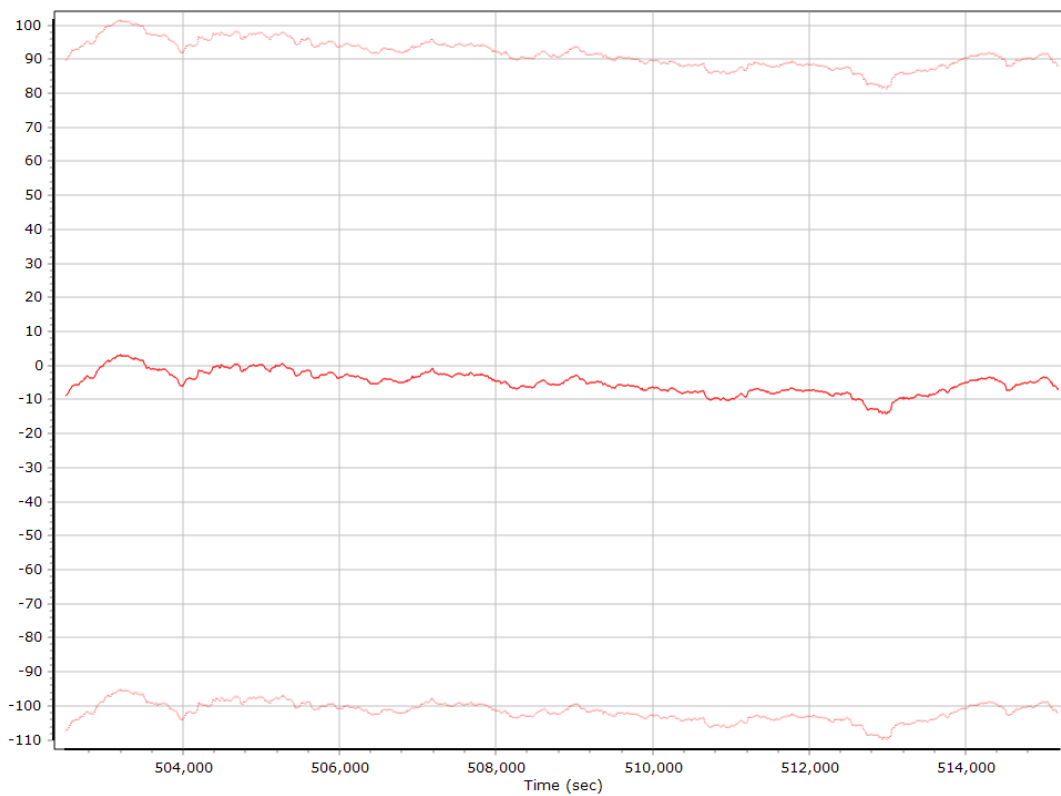
#### X Accelerometer Bias (micro-g)



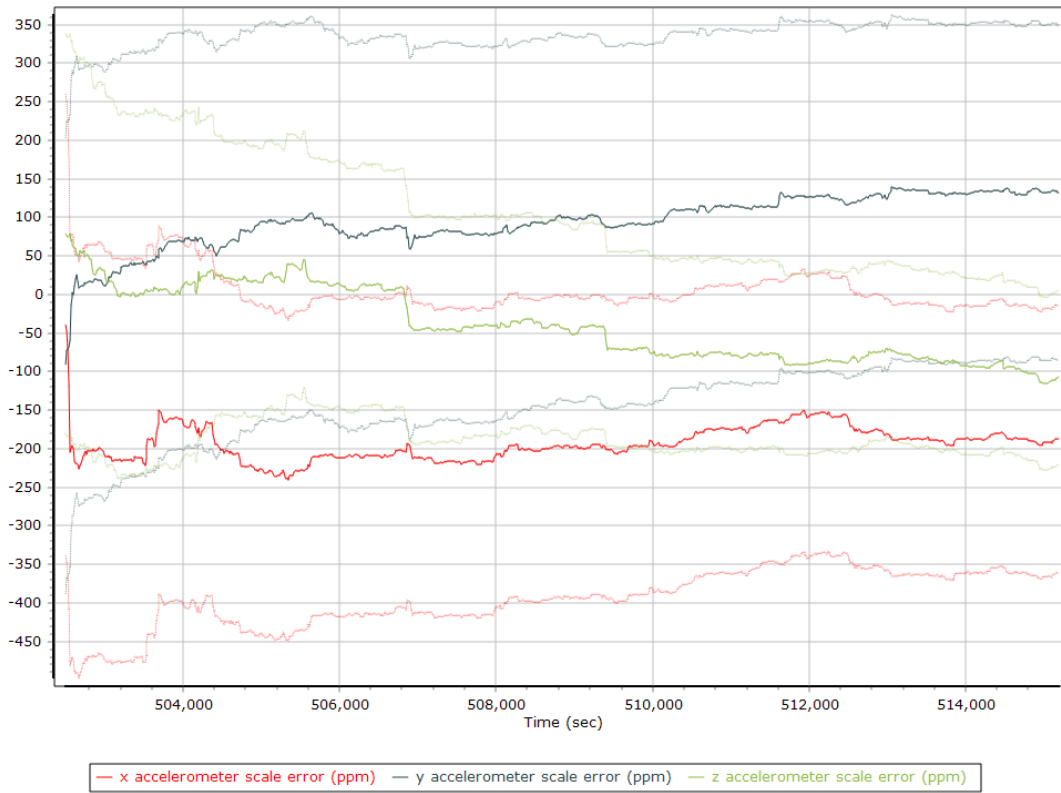
### Y Accelerometer Bias (micro-g)



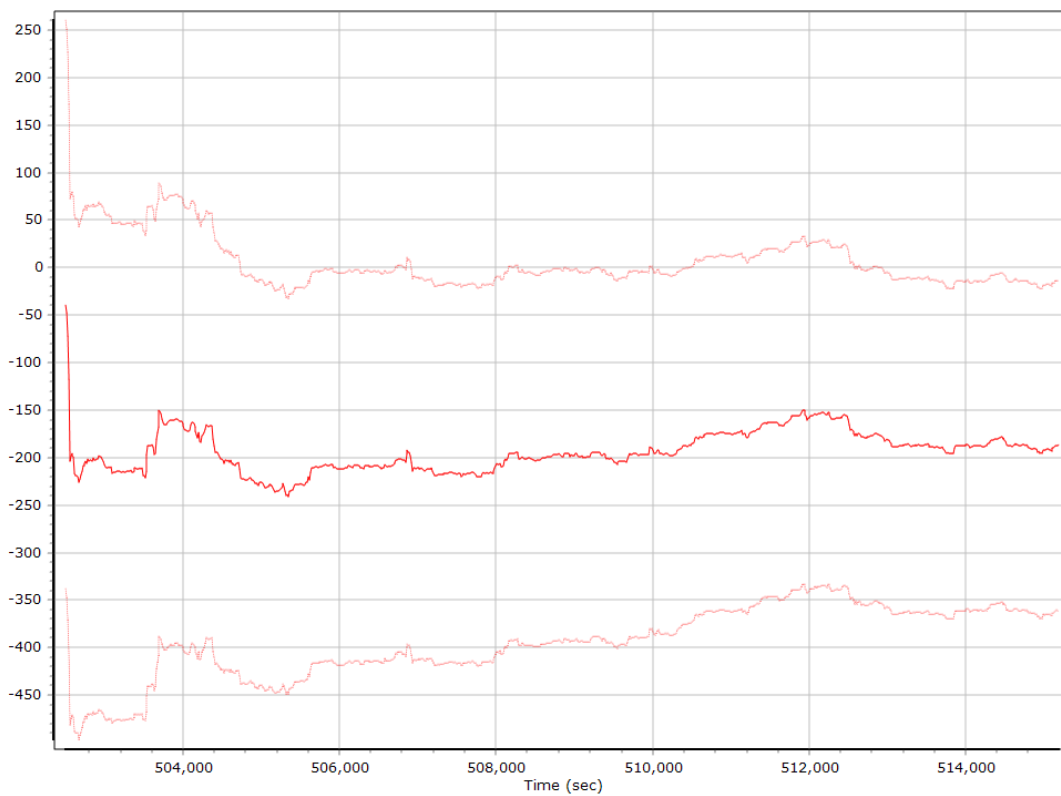
### Z Accelerometer Bias (micro-g)



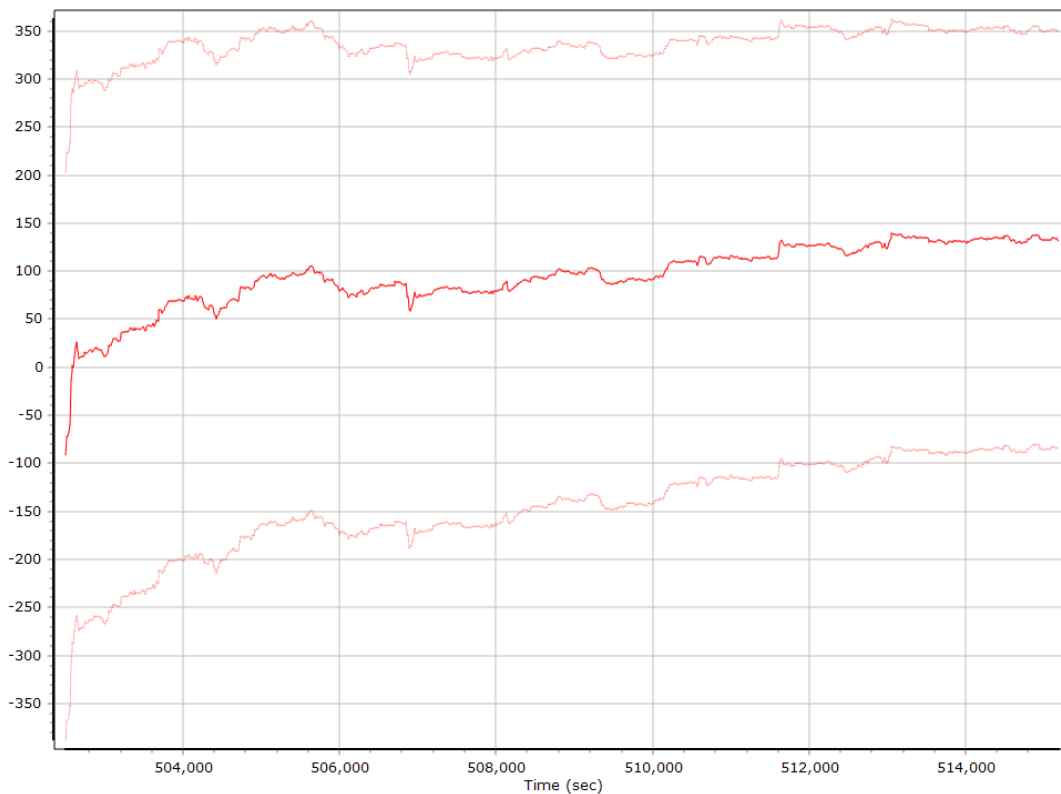
### Accelerometer Scale Error (ppm)



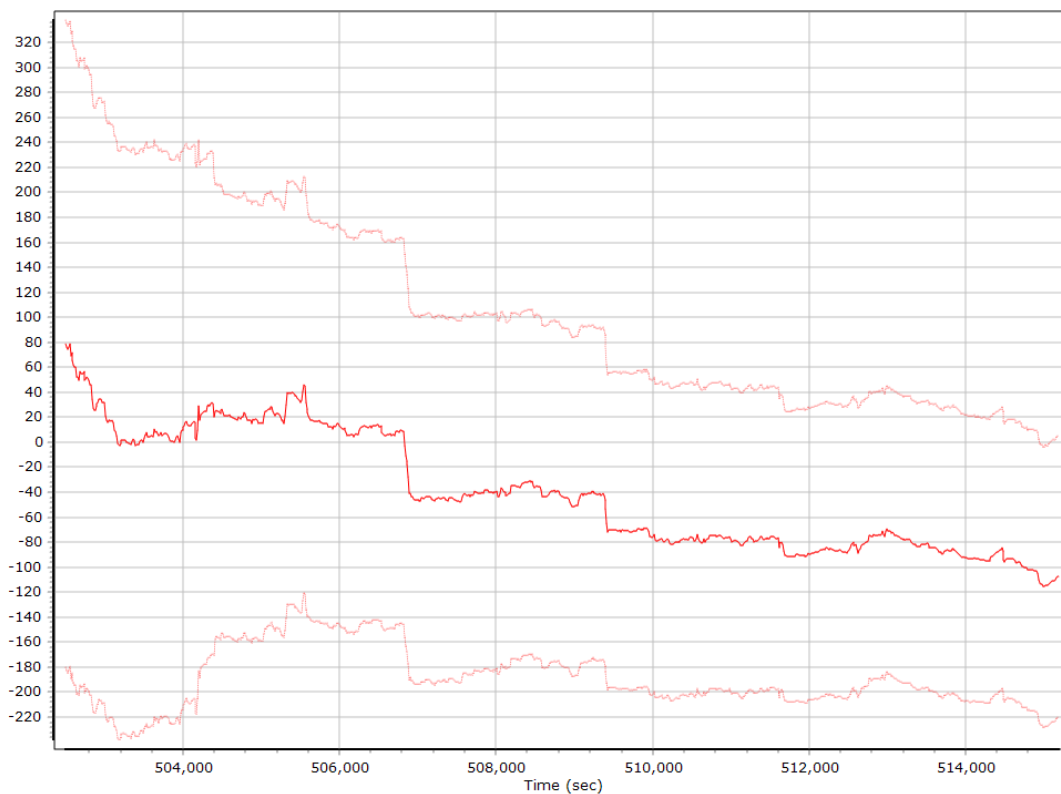
### X Accelerometer Scale Error (ppm)



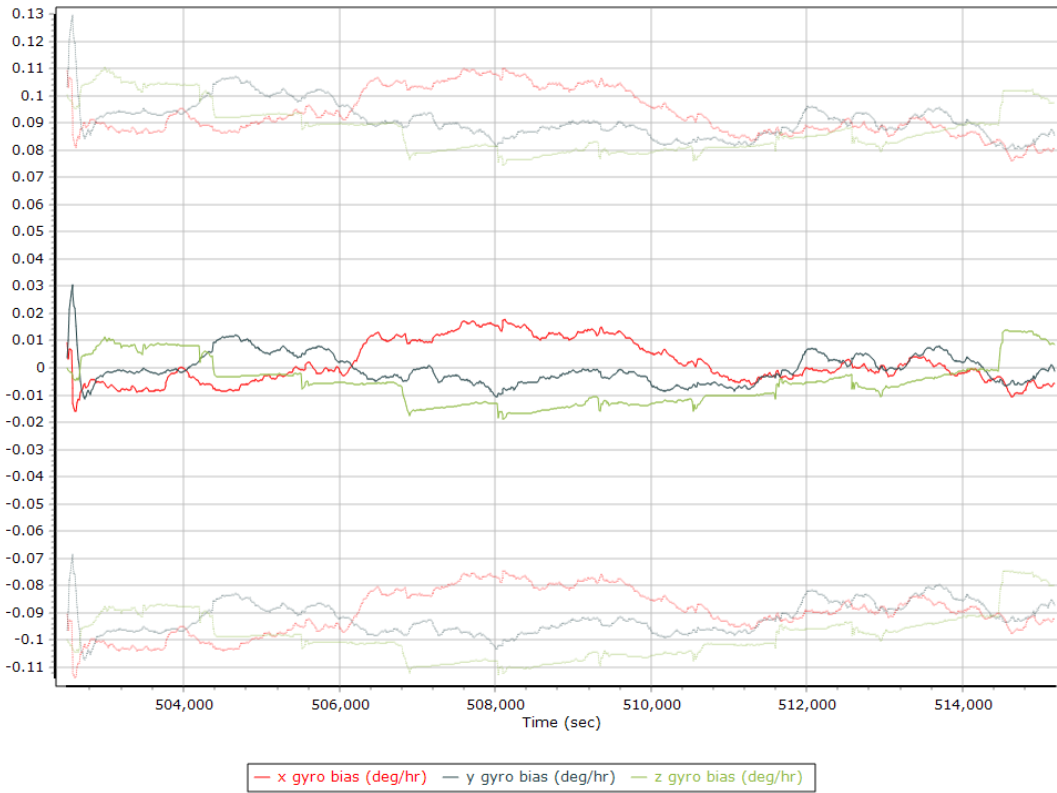
### Y Accelerometer Scale Error (ppm)



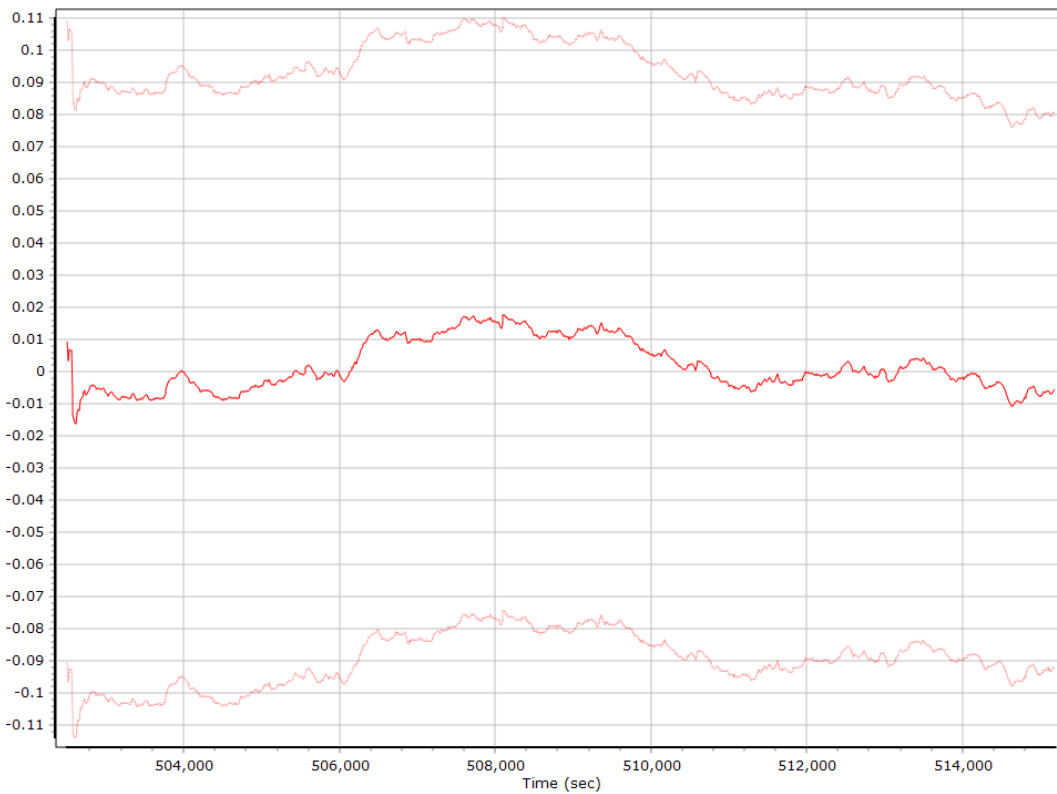
### Z Accelerometer Scale Error (ppm)



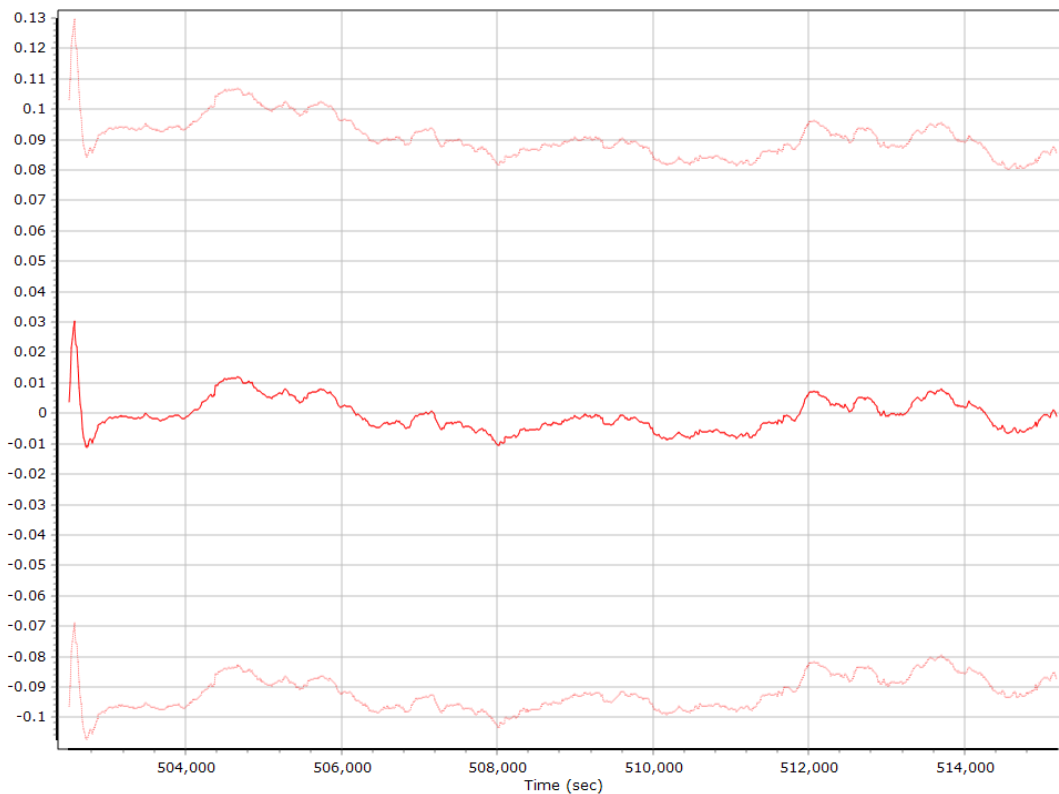
### Gyro Bias (deg/h)



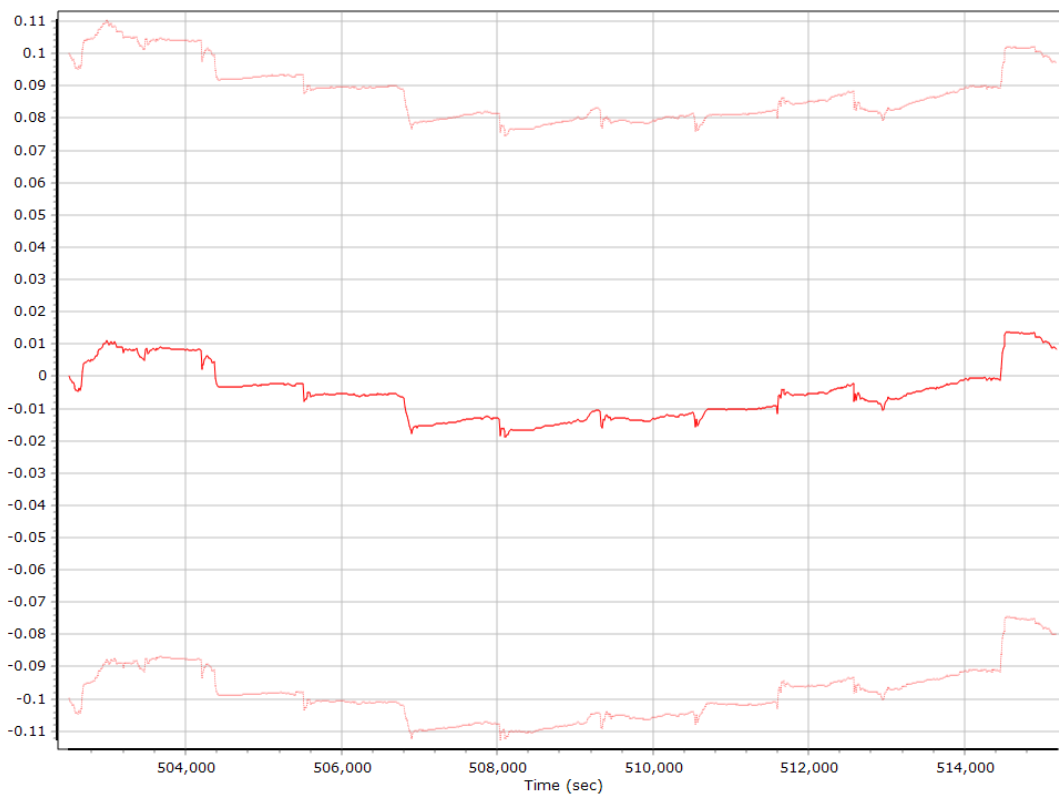
### X Gyro Bias (deg/h)



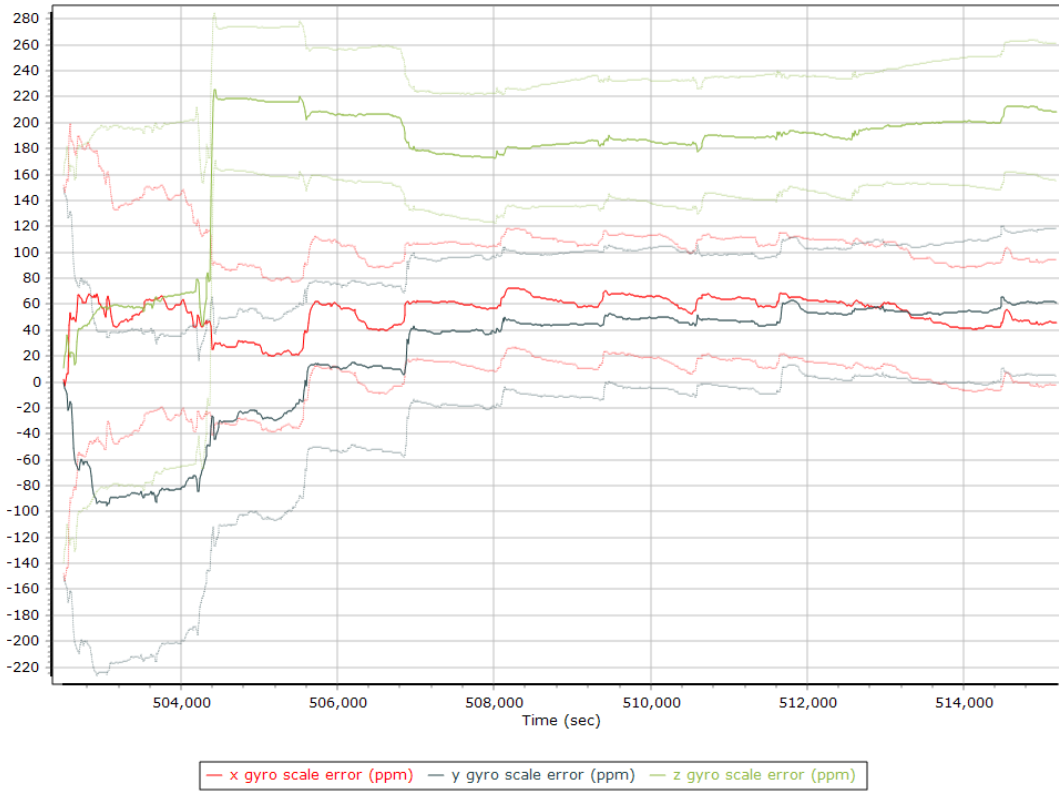
### Y Gyro Bias (deg/h)



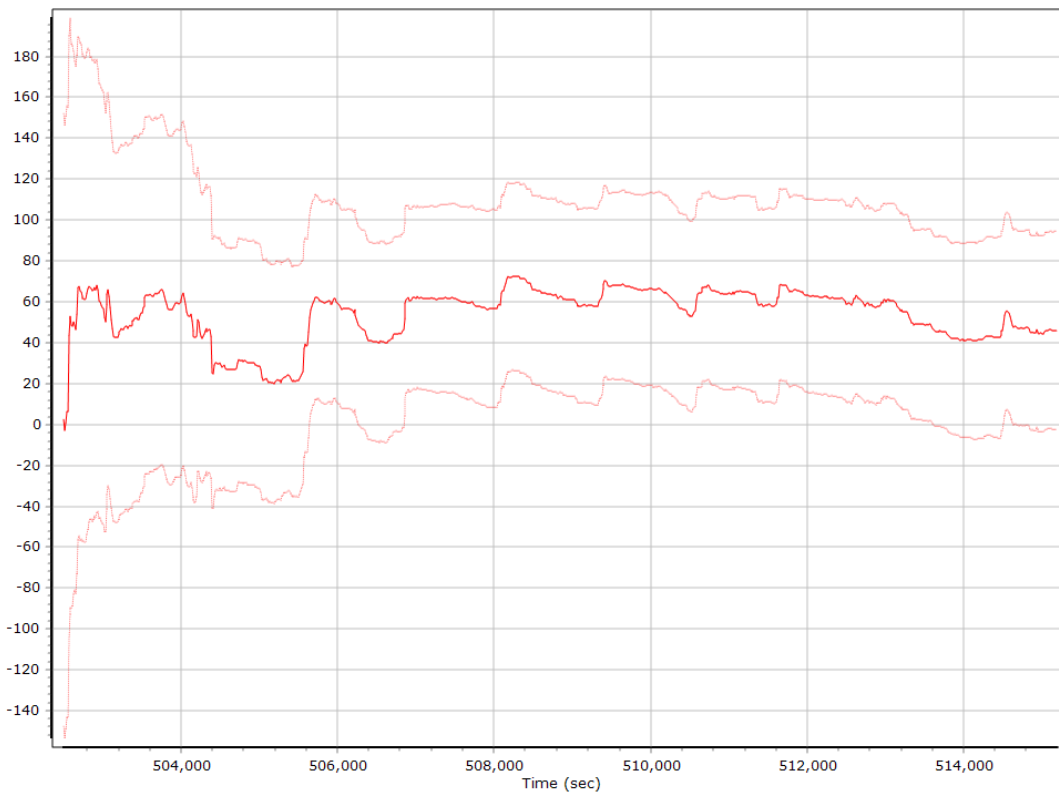
### Z Gyro Bias (deg/h)



### Gyro Scale Error (ppm)

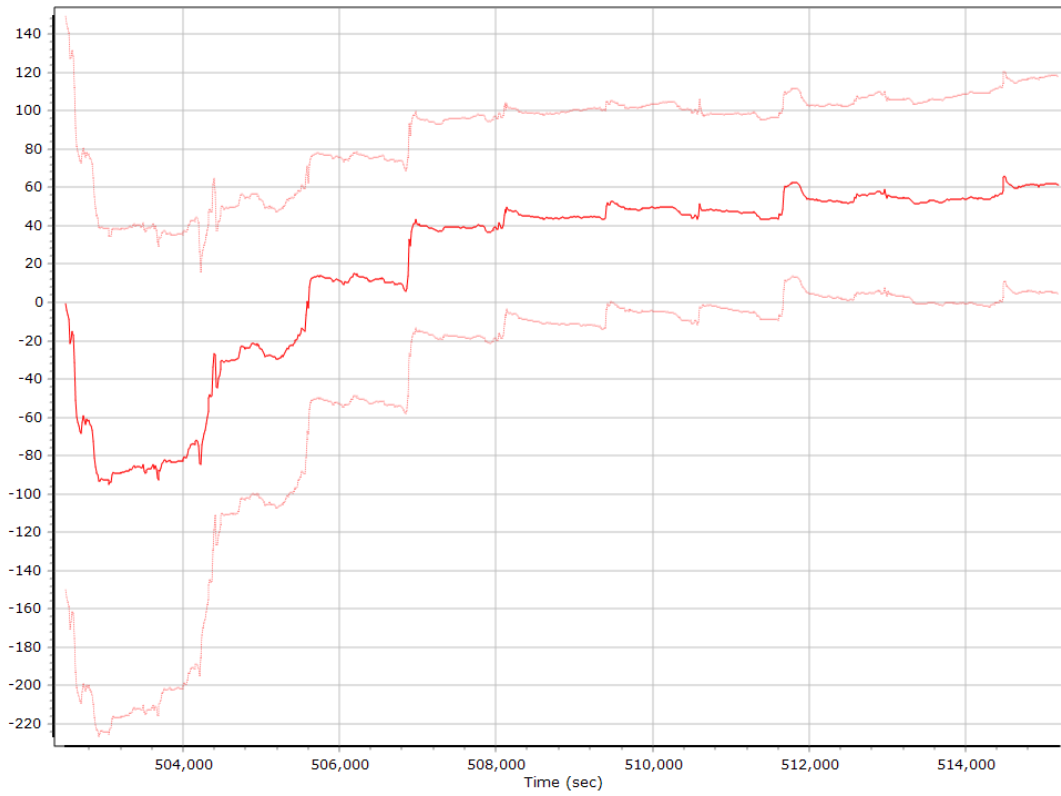


### X Gyro Scale Error (ppm)

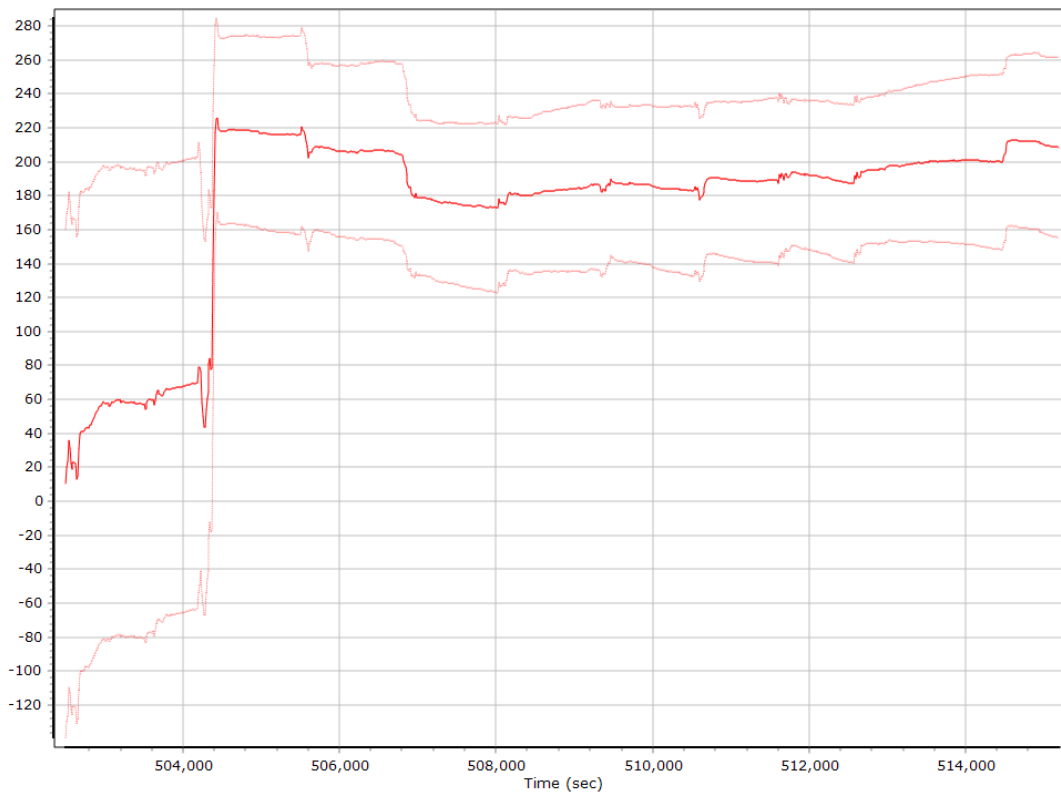




### Y Gyro Scale Error (ppm)

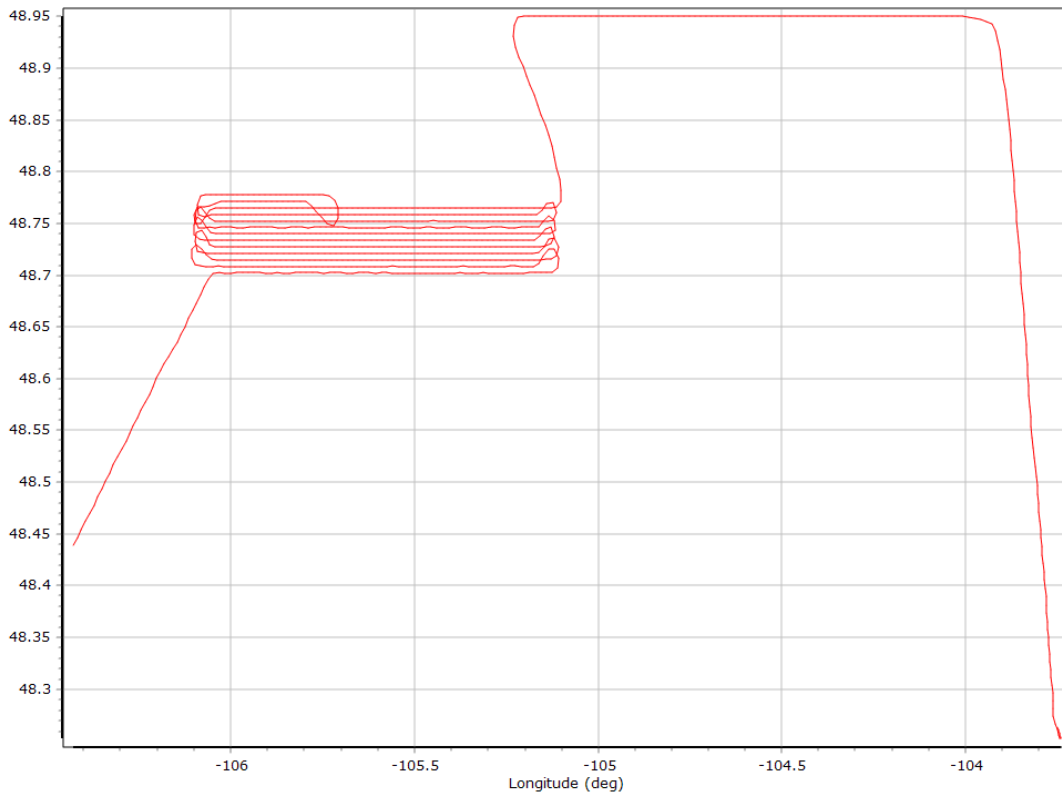


### Z Gyro Scale Error (ppm)

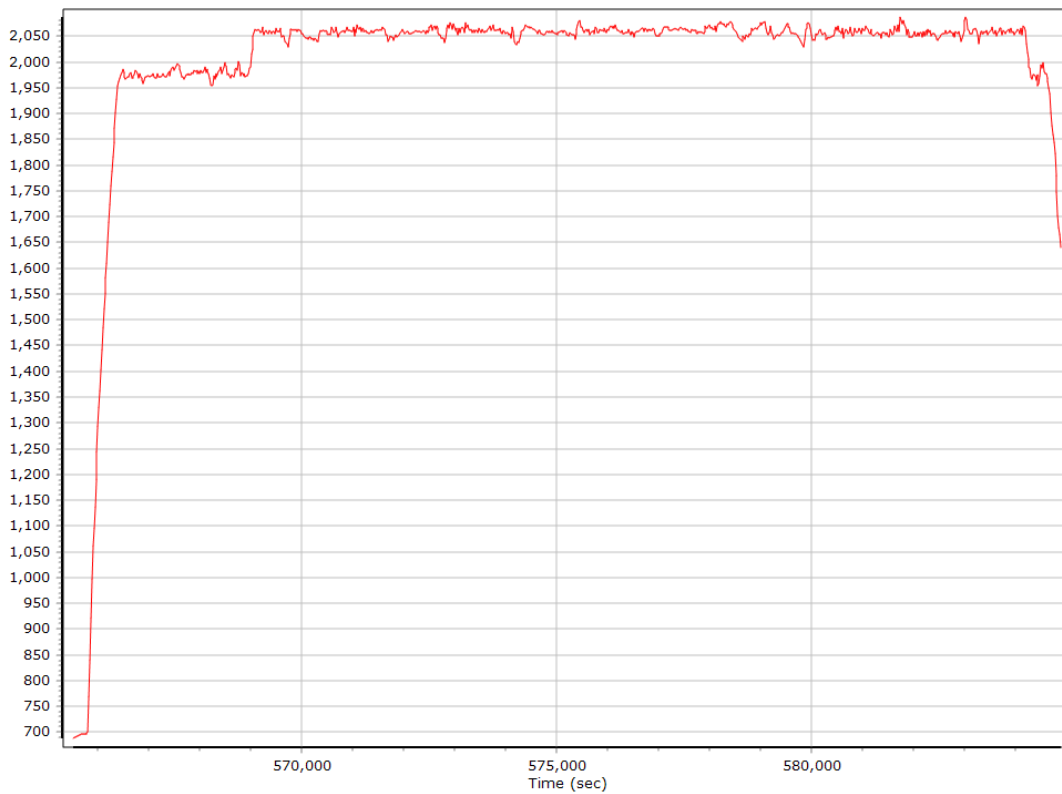


## Smoothed Trajectory Information

### Top View



### Altitude

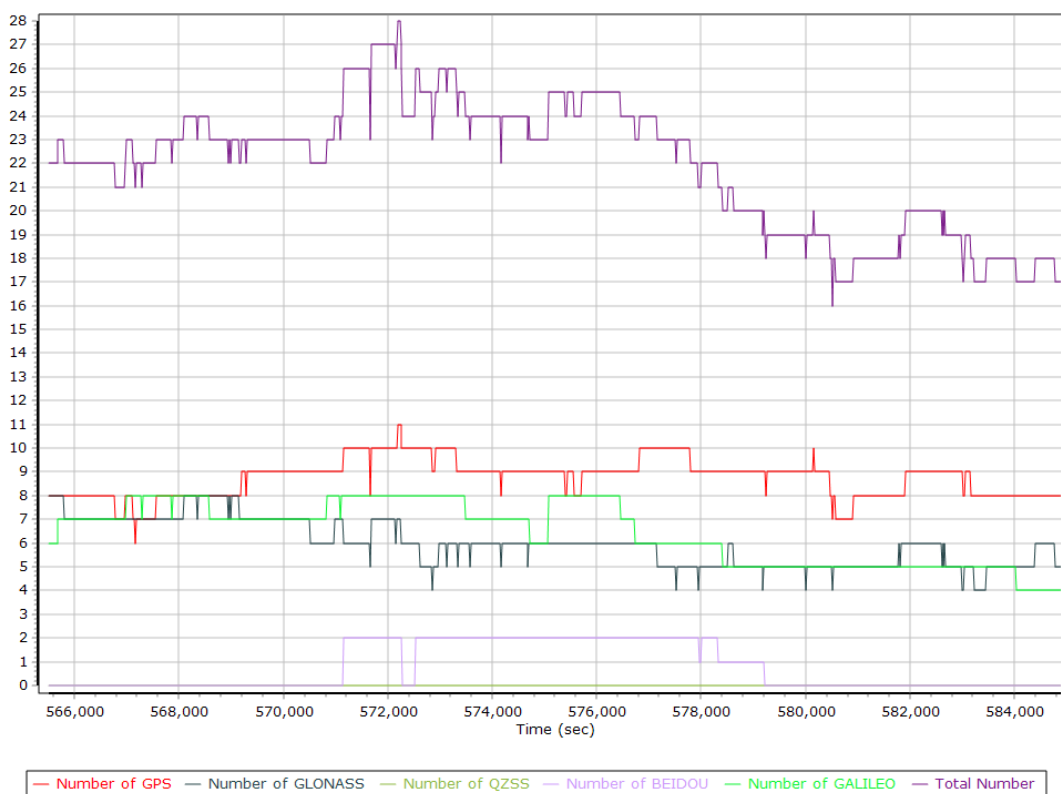


## GNSS QC

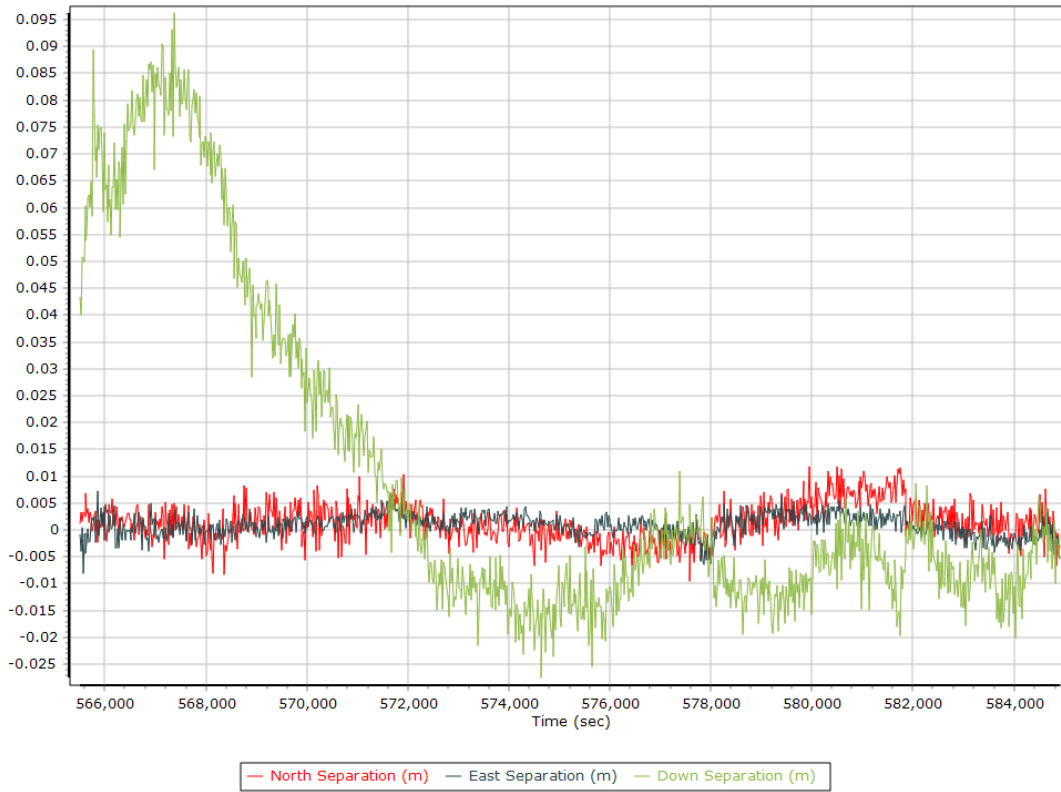
### GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	6	11	9
Number of GLONASS SV	0	8	6
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	2	1
Number of GALILEO SV	0	8	6
Total number of SV	15	28	22
PDOP	0.94	1.55	1.13
QC Solution Gaps	0.00	0.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	19735.00	0.00	0.00
Percentage	100.00	0.00	0.00

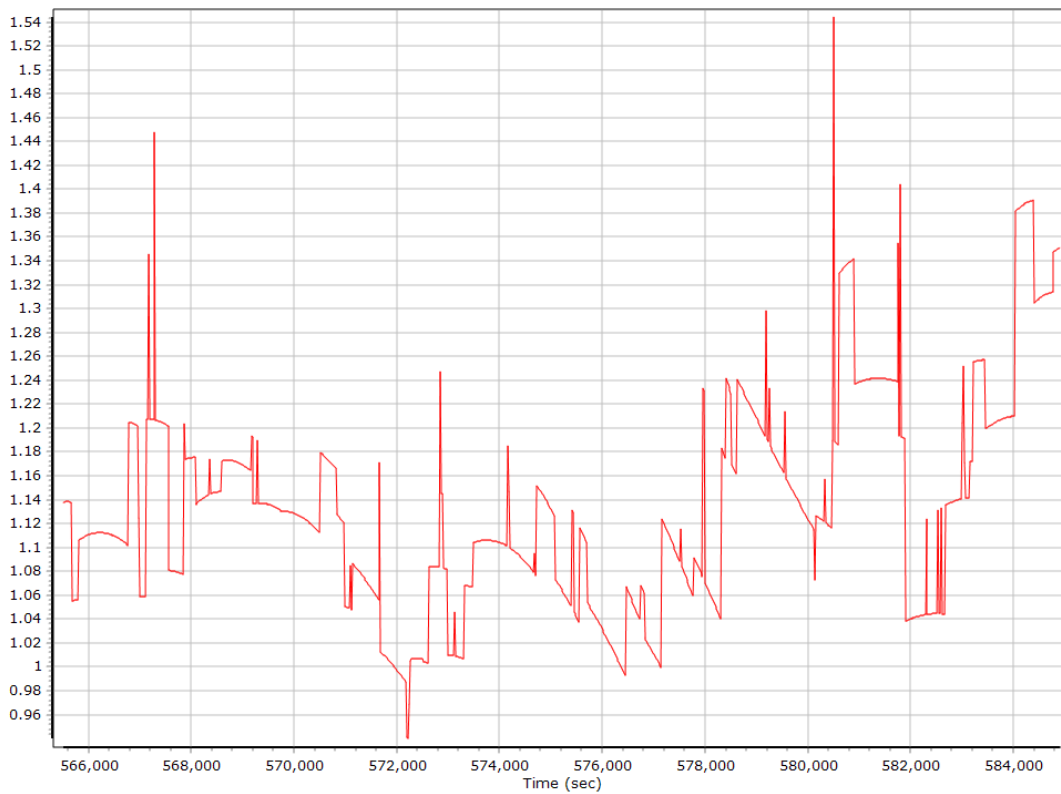
### Num SVs in solution



## Forward/Reverse Separation



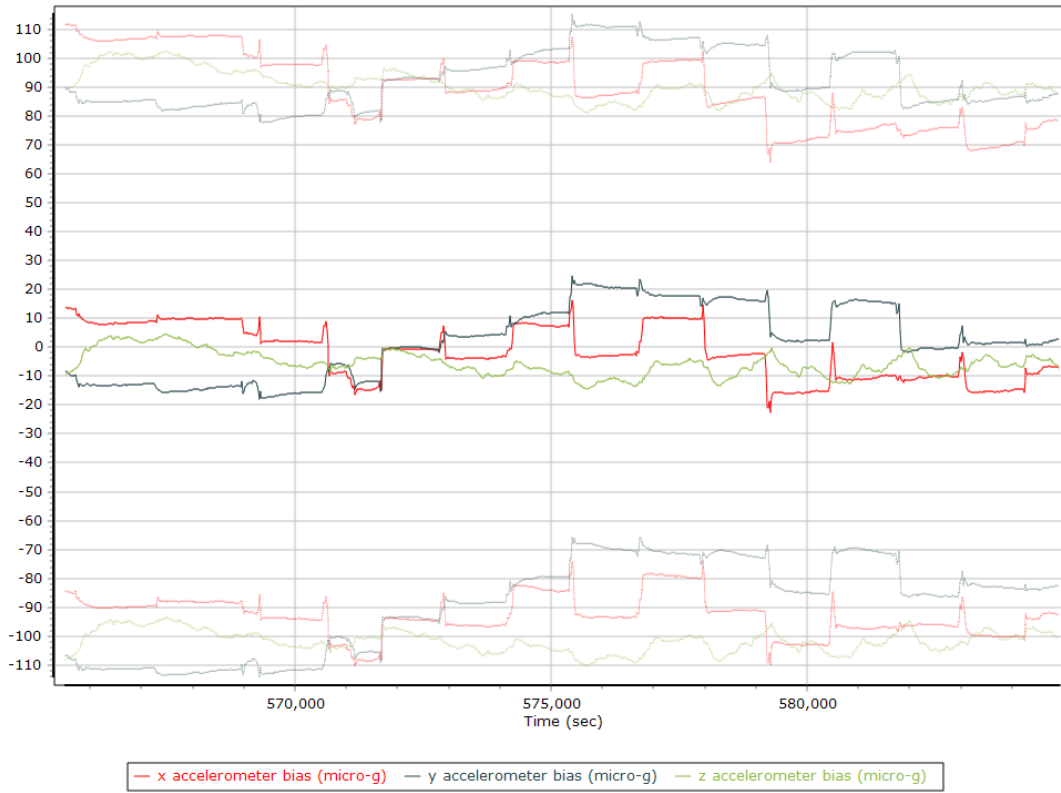
## PDOP



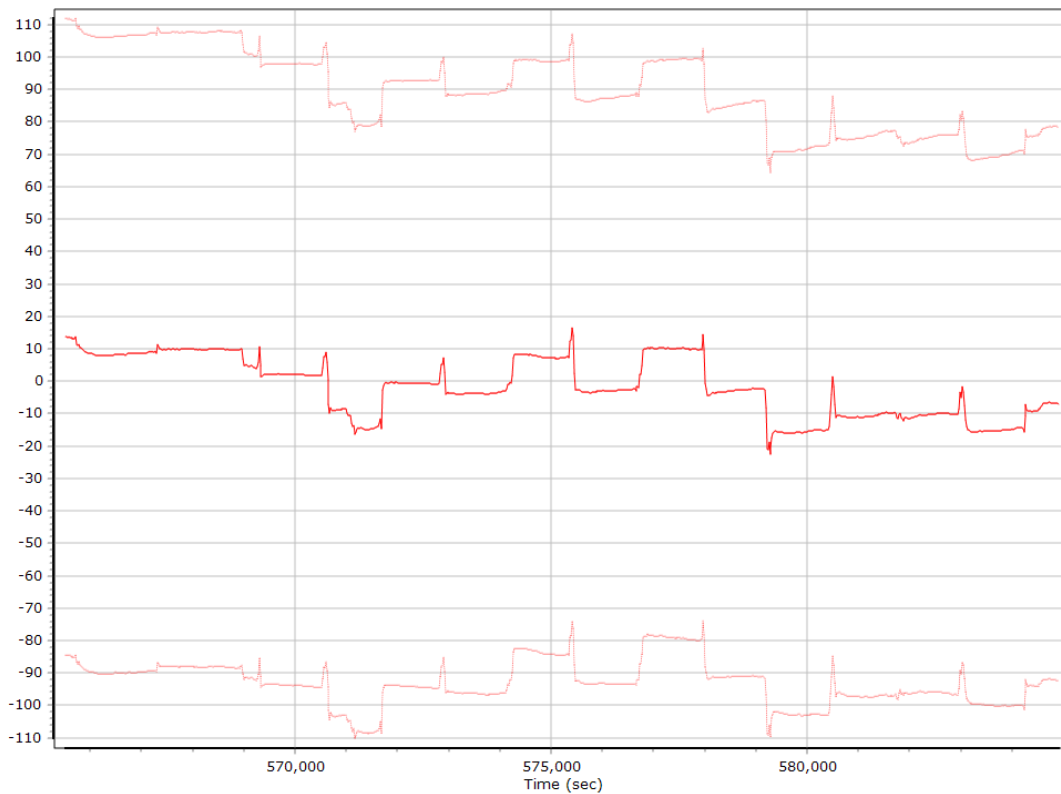
## IN-Fusion QC

### Forward Processed Estimated Errors, Reference Frame

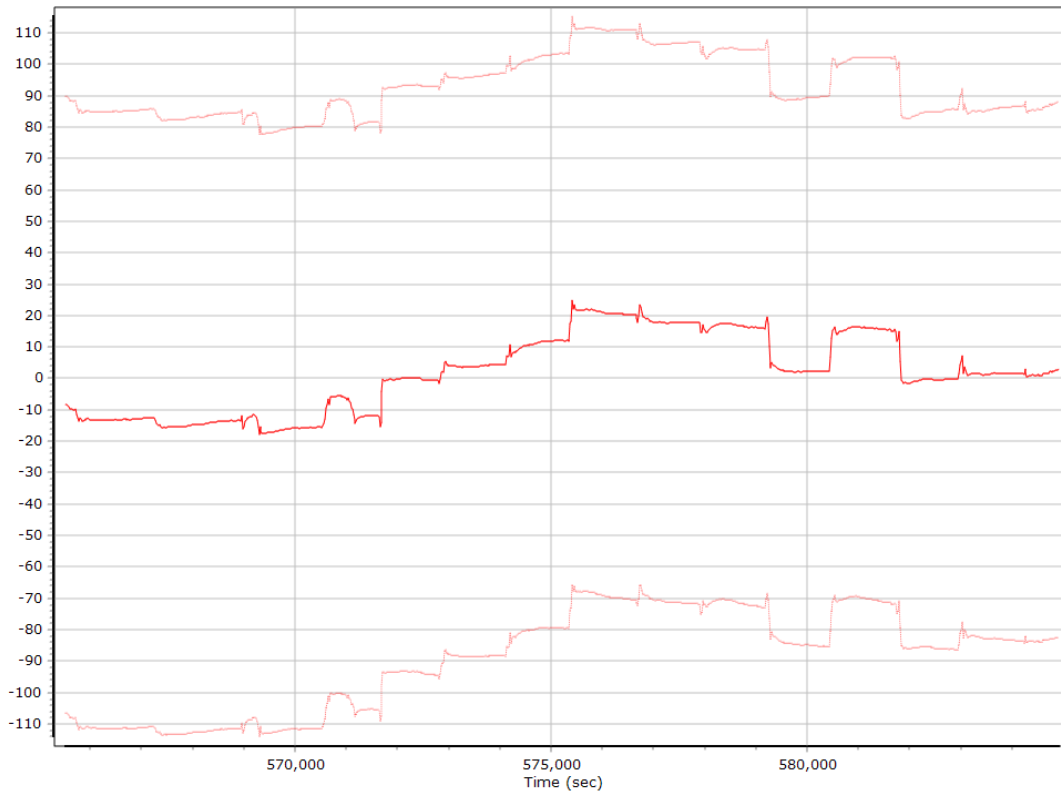
#### Accelerometer Bias (micro-g)



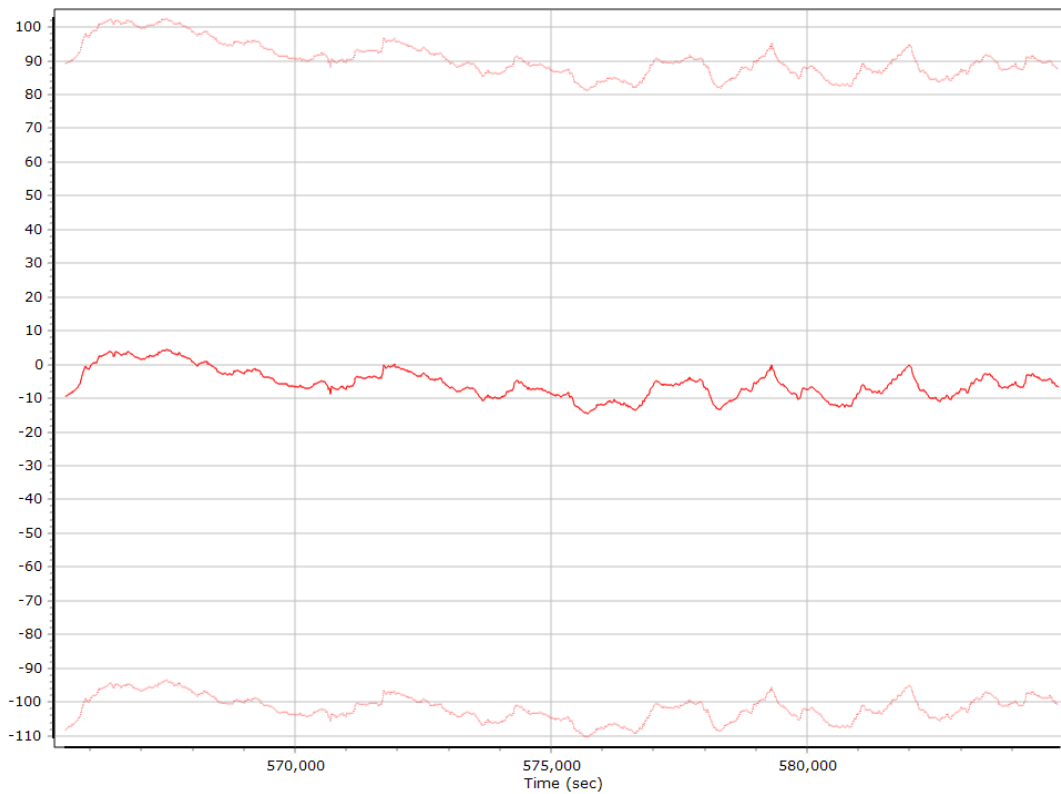
#### X Accelerometer Bias (micro-g)



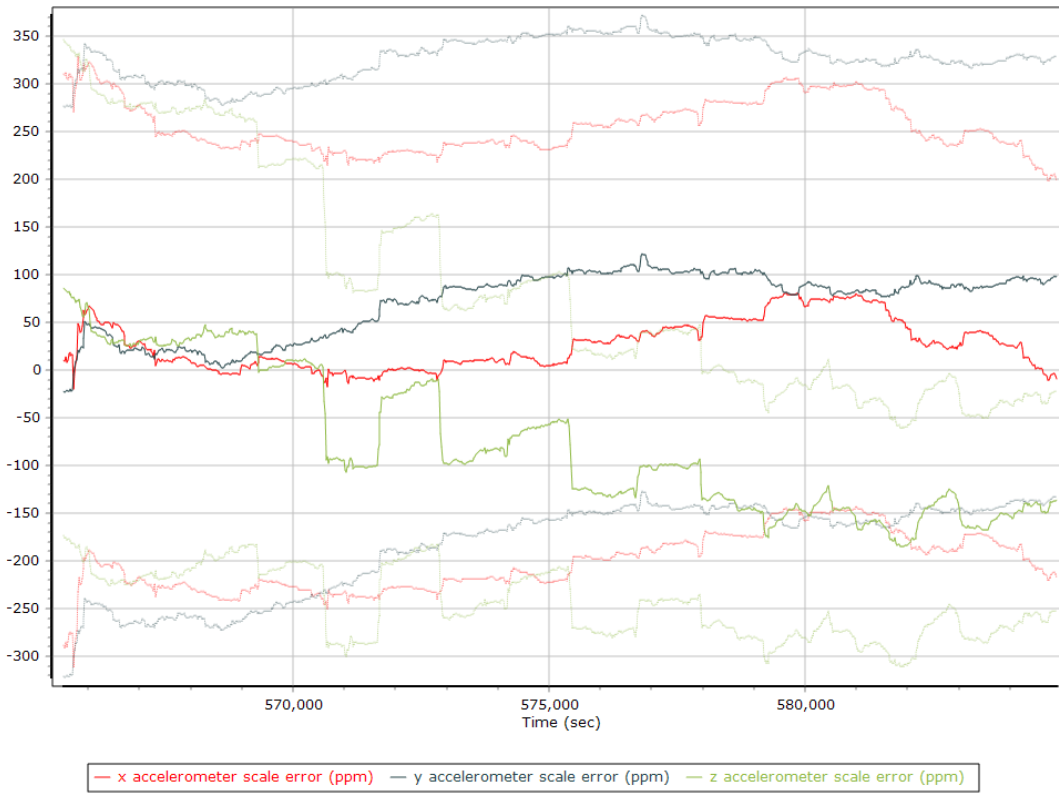
### Y Accelerometer Bias (micro-g)



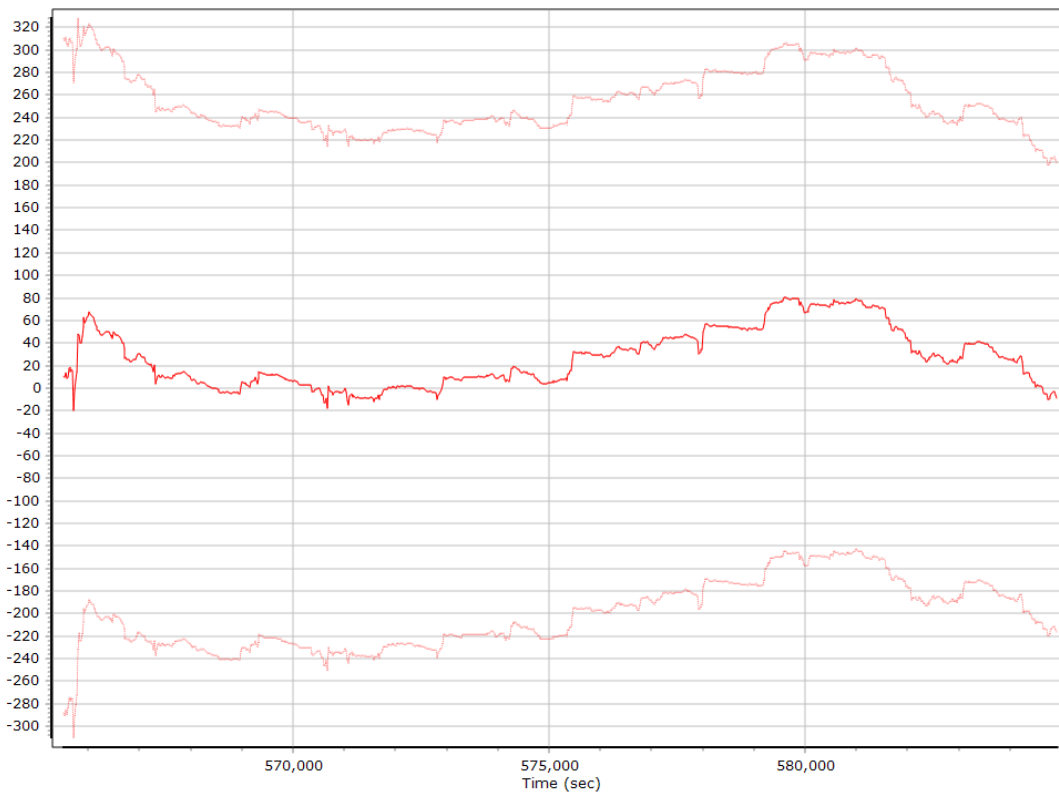
### Z Accelerometer Bias (micro-g)



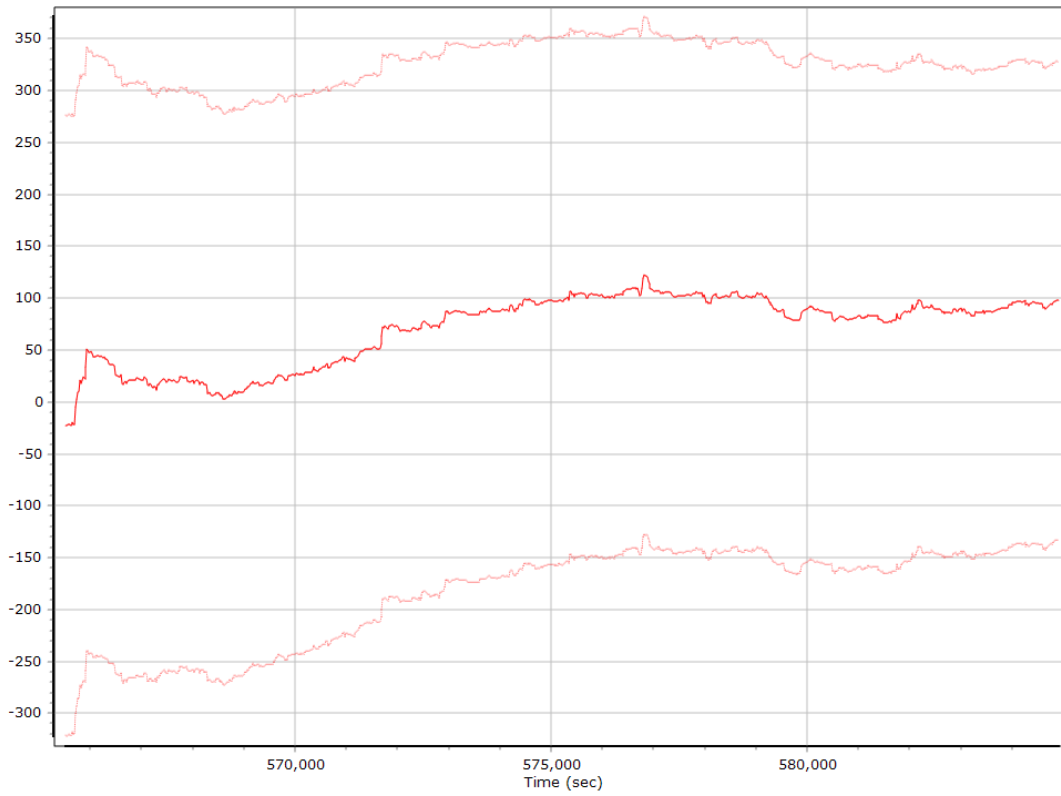
### Accelerometer Scale Error (ppm)



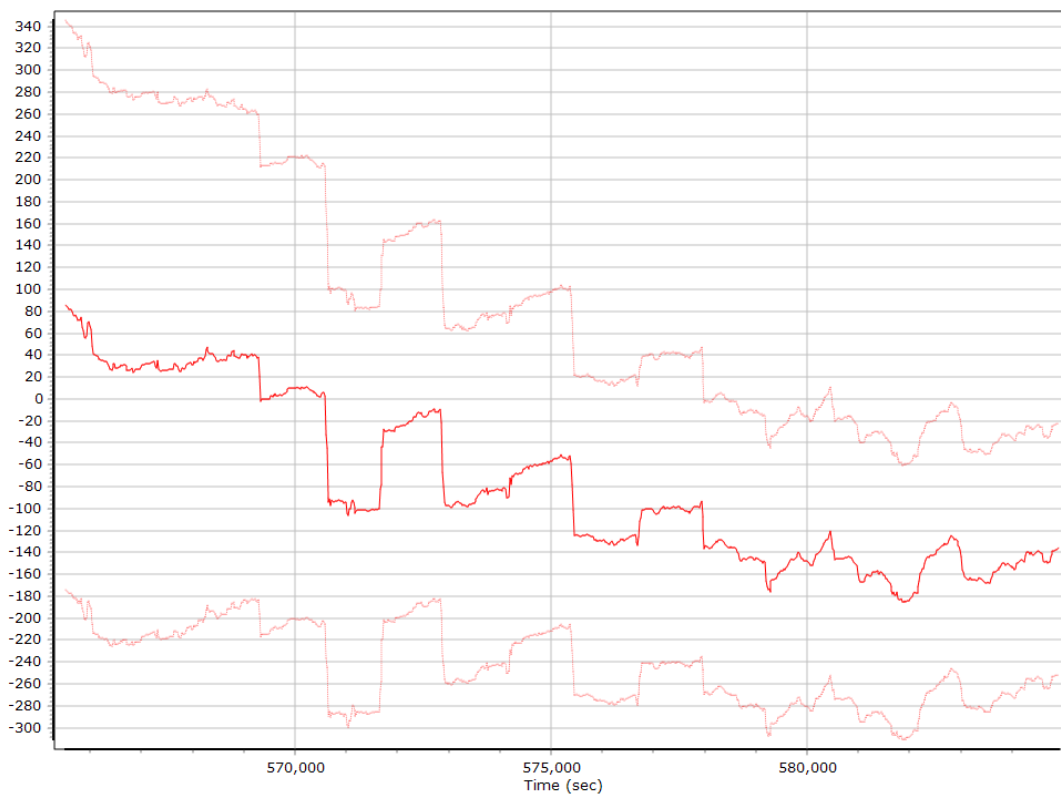
### X Accelerometer Scale Error (ppm)



### Y Accelerometer Scale Error (ppm)

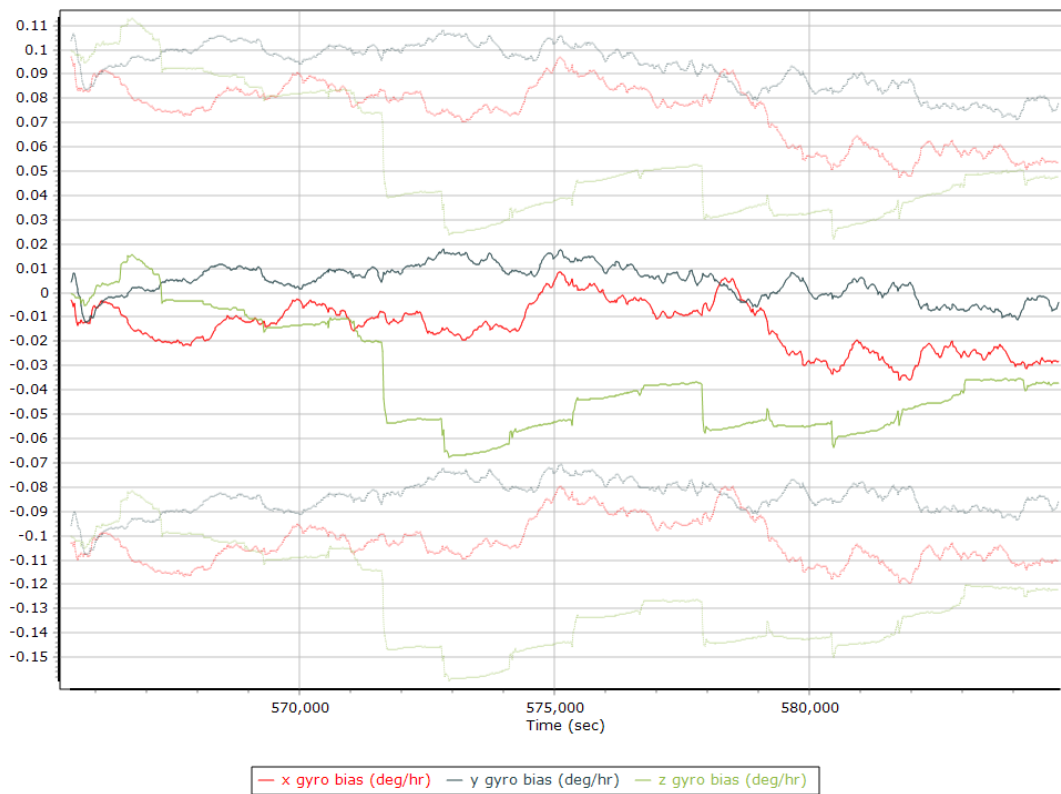


### Z Accelerometer Scale Error (ppm)

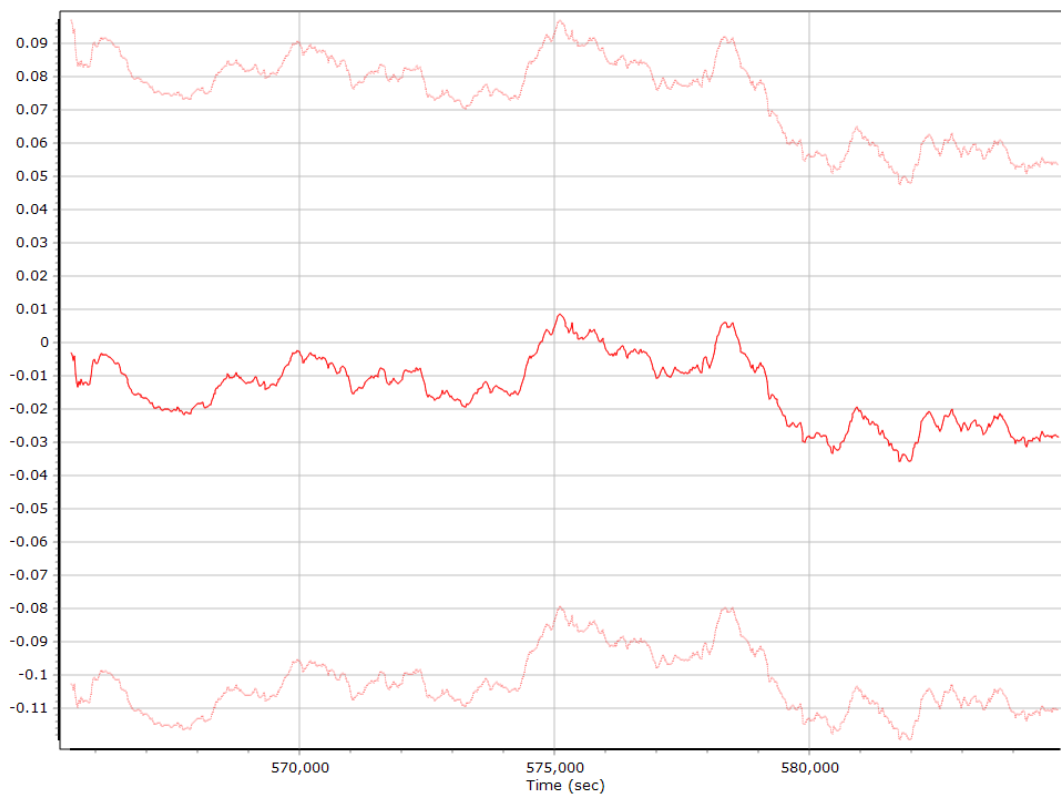




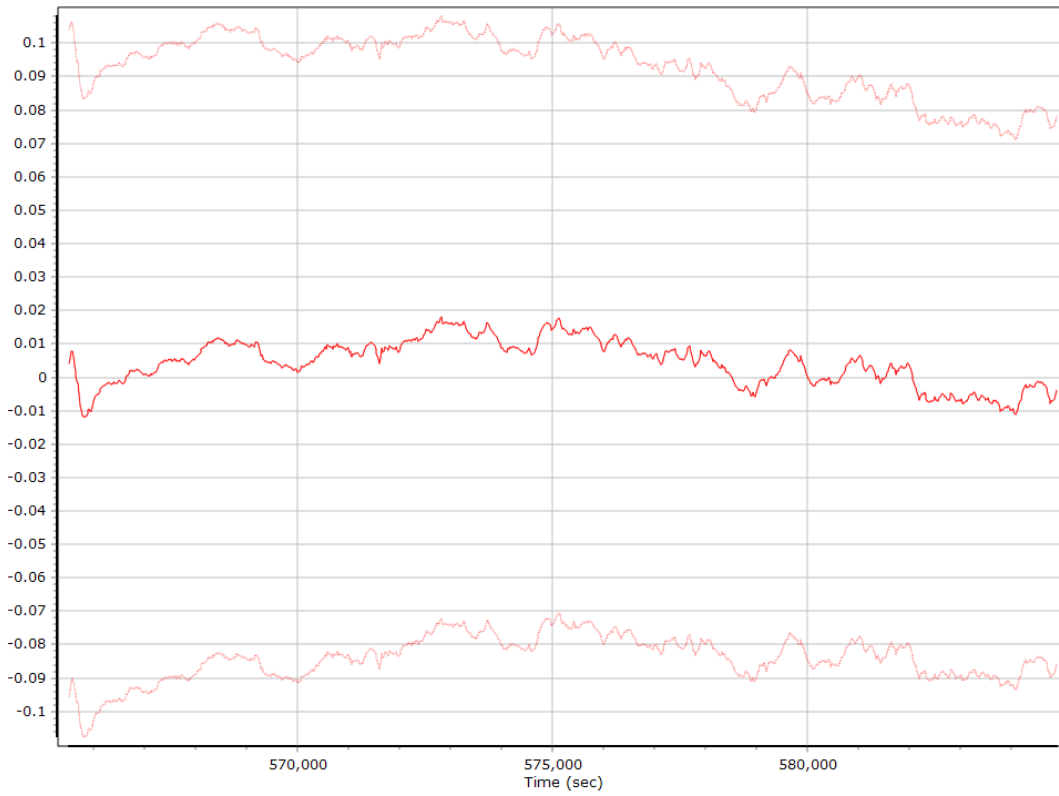
### Gyro Bias (deg/h)



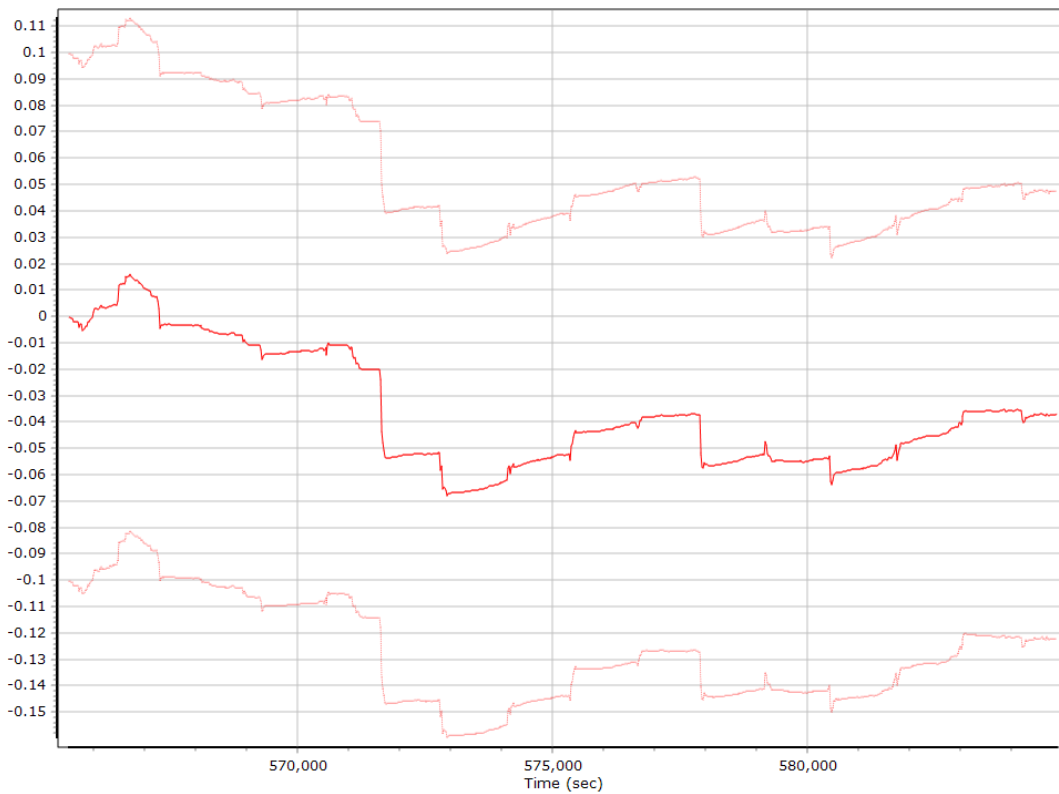
### X Gyro Bias (deg/h)



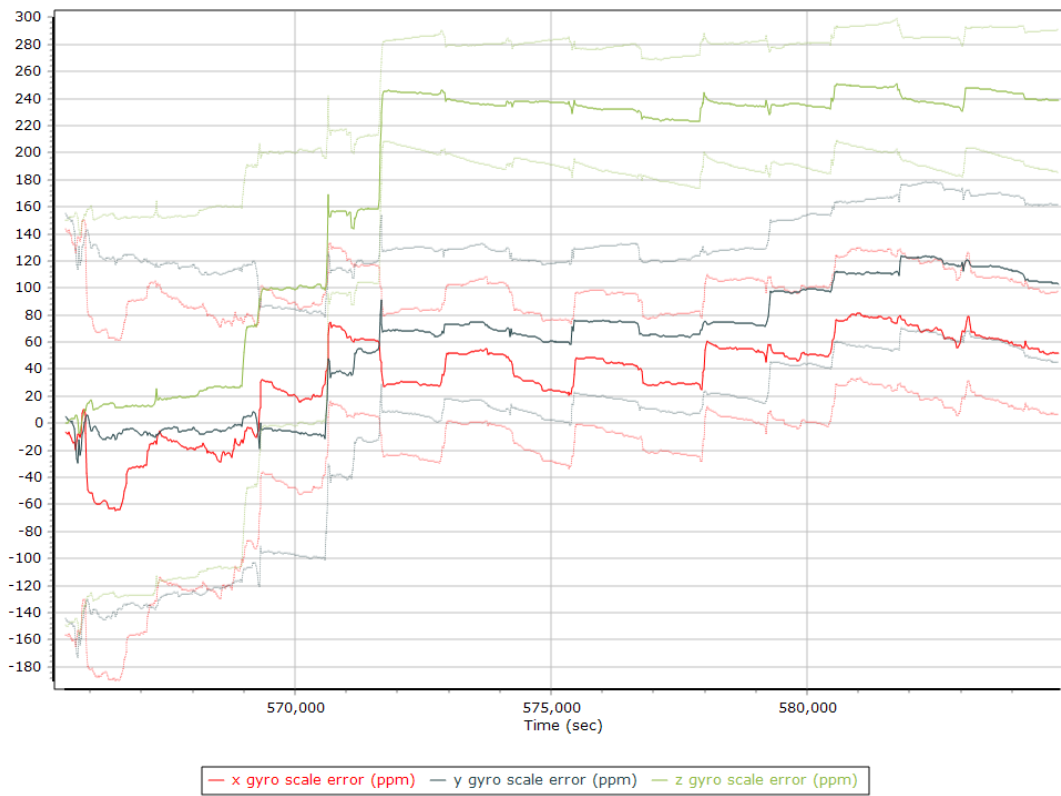
### Y Gyro Bias (deg/h)



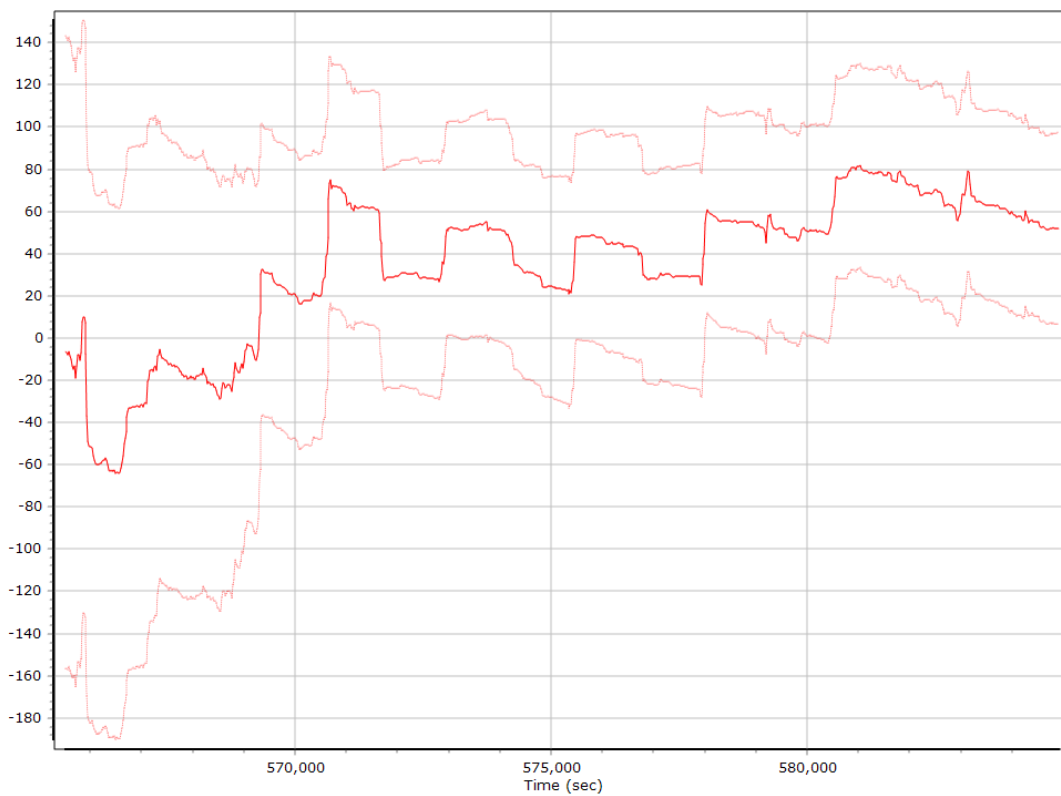
### Z Gyro Bias (deg/h)



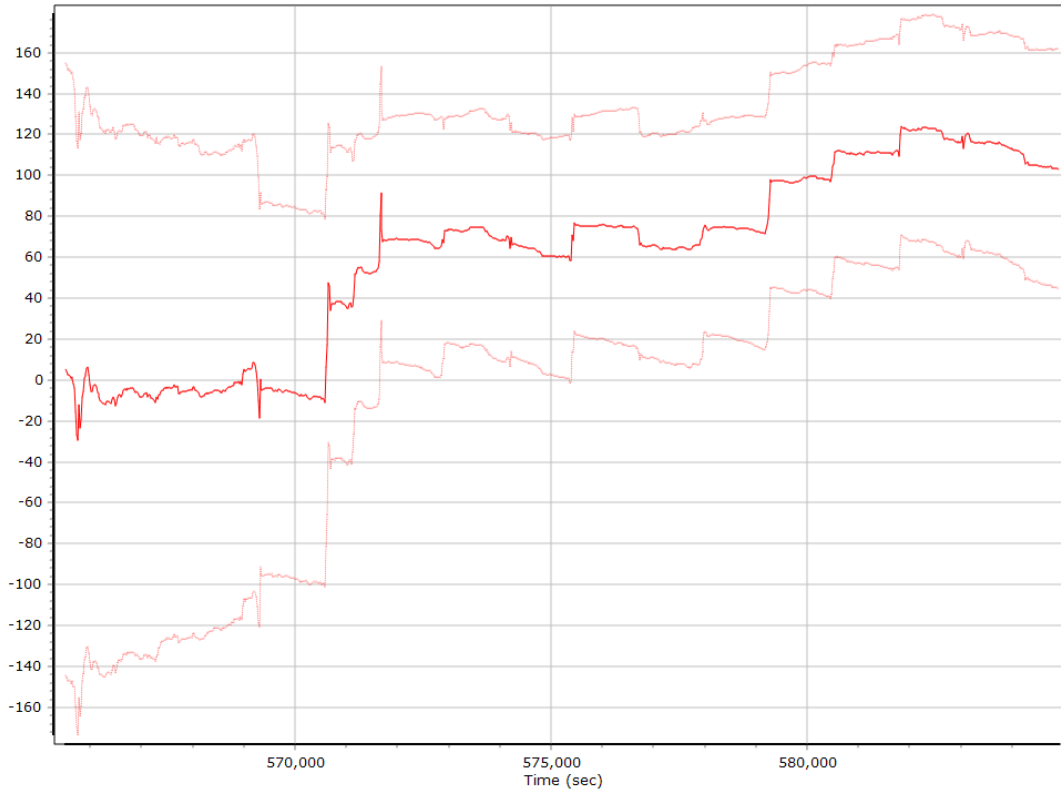
### Gyro Scale Error (ppm)



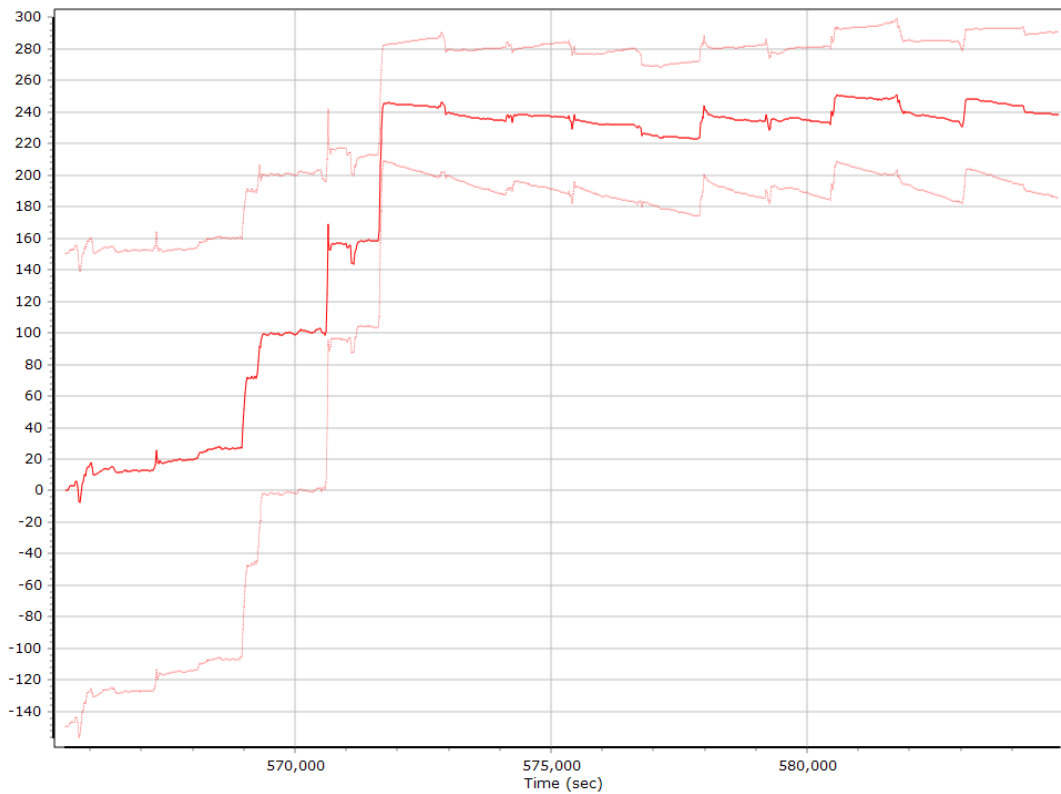
### X Gyro Scale Error (ppm)



### Y Gyro Scale Error (ppm)

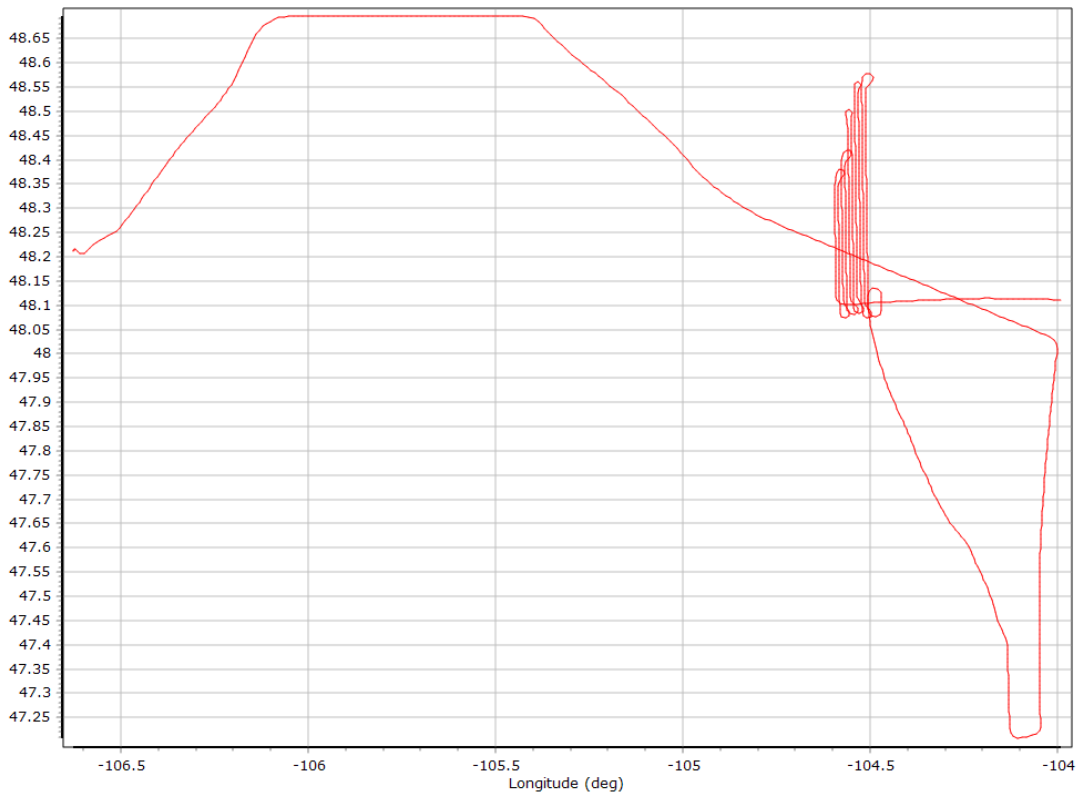


### Z Gyro Scale Error (ppm)

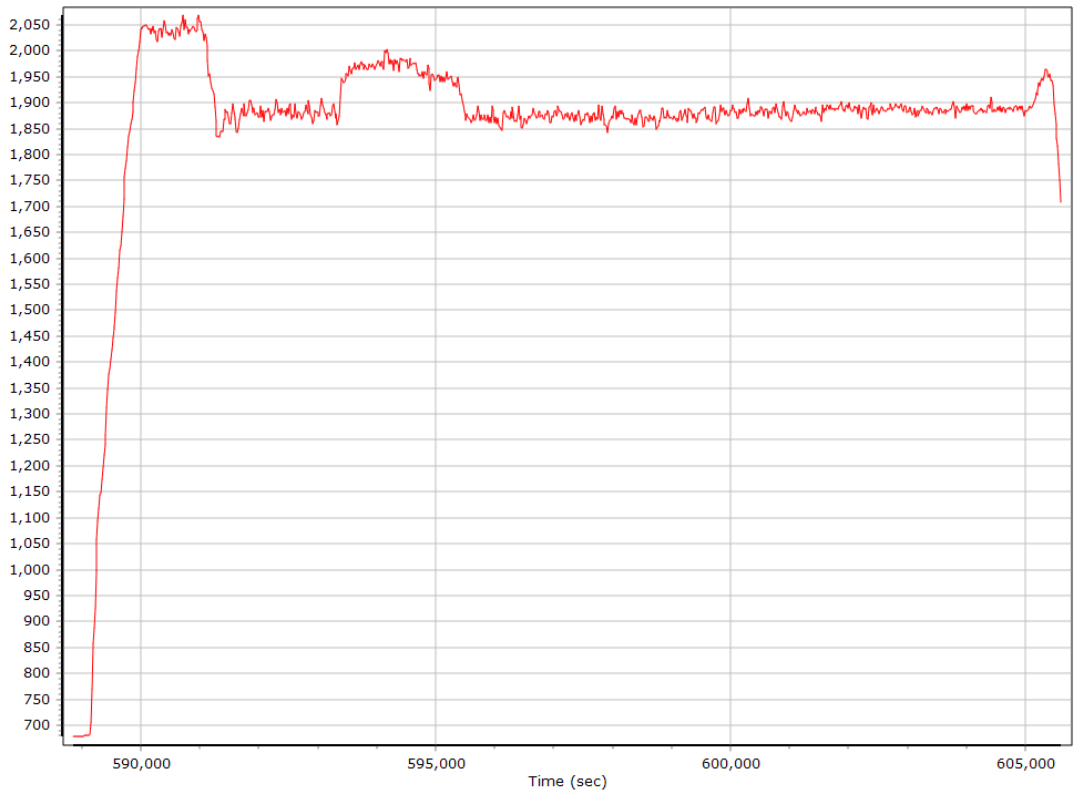


## Smoothed Trajectory Information

### Top View



### Altitude

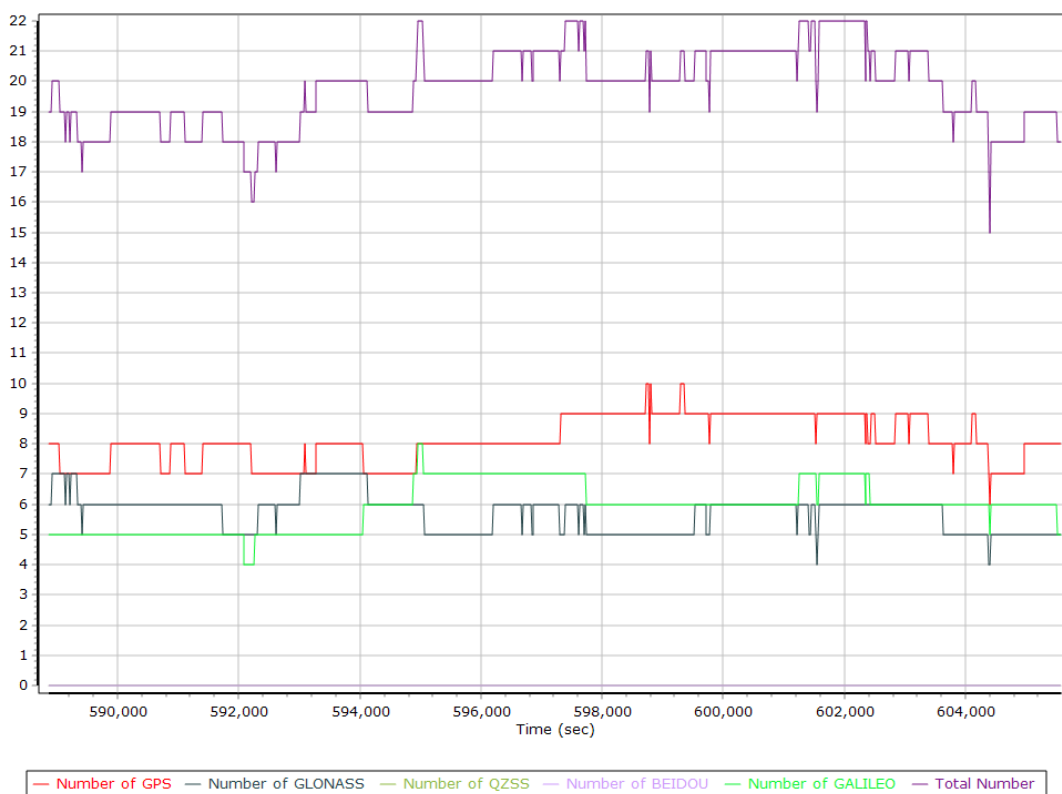


## GNSS QC

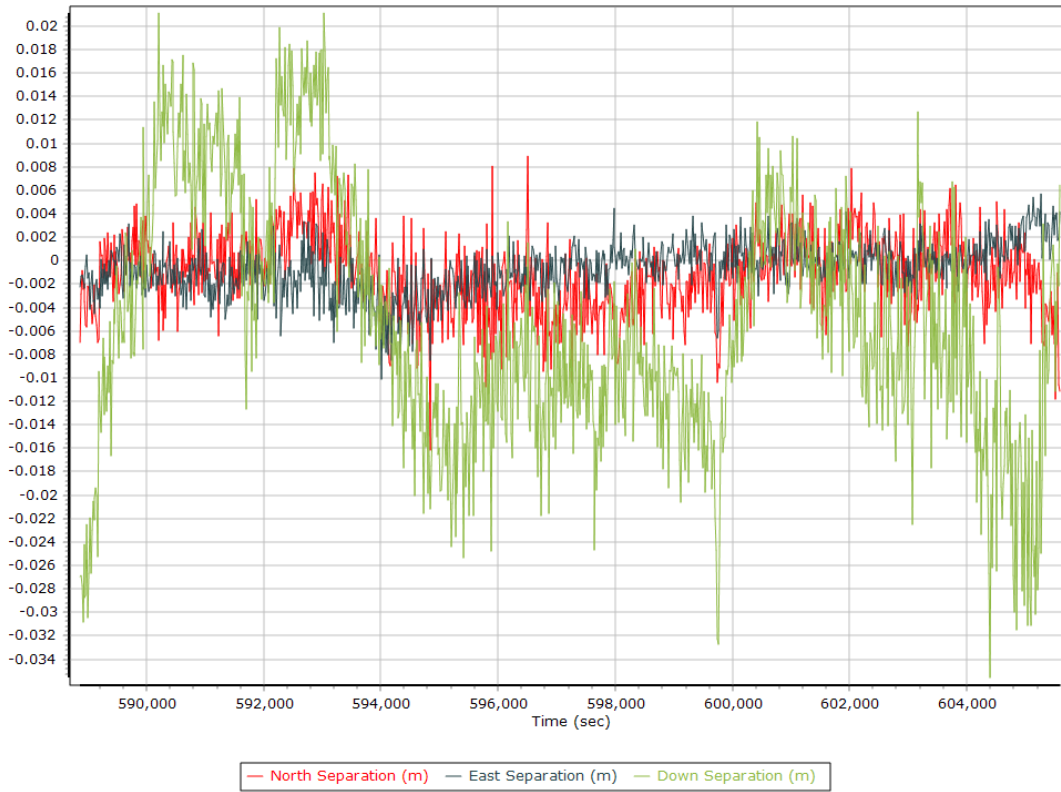
### GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	6	10	8
Number of GLONASS SV	0	7	6
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	0	0
Number of GALILEO SV	4	8	6
Total number of SV	12	22	20
PDOP	1.04	1.72	1.21
QC Solution Gaps	0.00	0.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	16947.00	0.00	0.00
Percentage	100.00	0.00	0.00

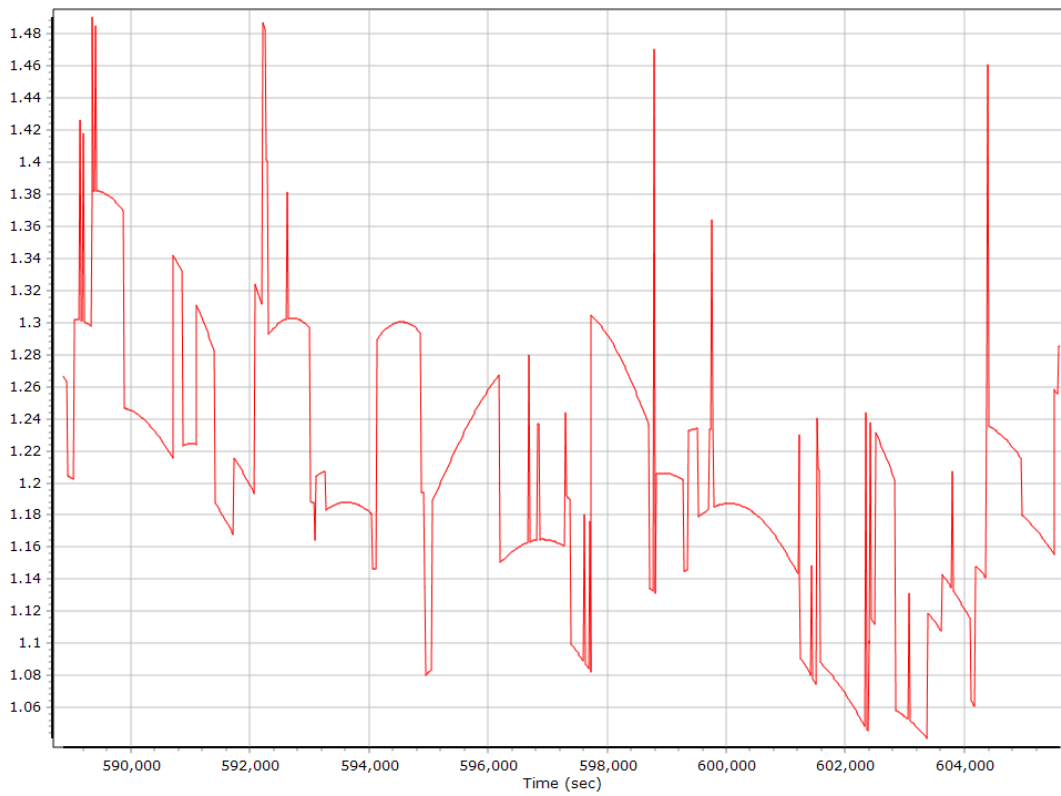
### Num SVs in solution



## Forward/Reverse Separation



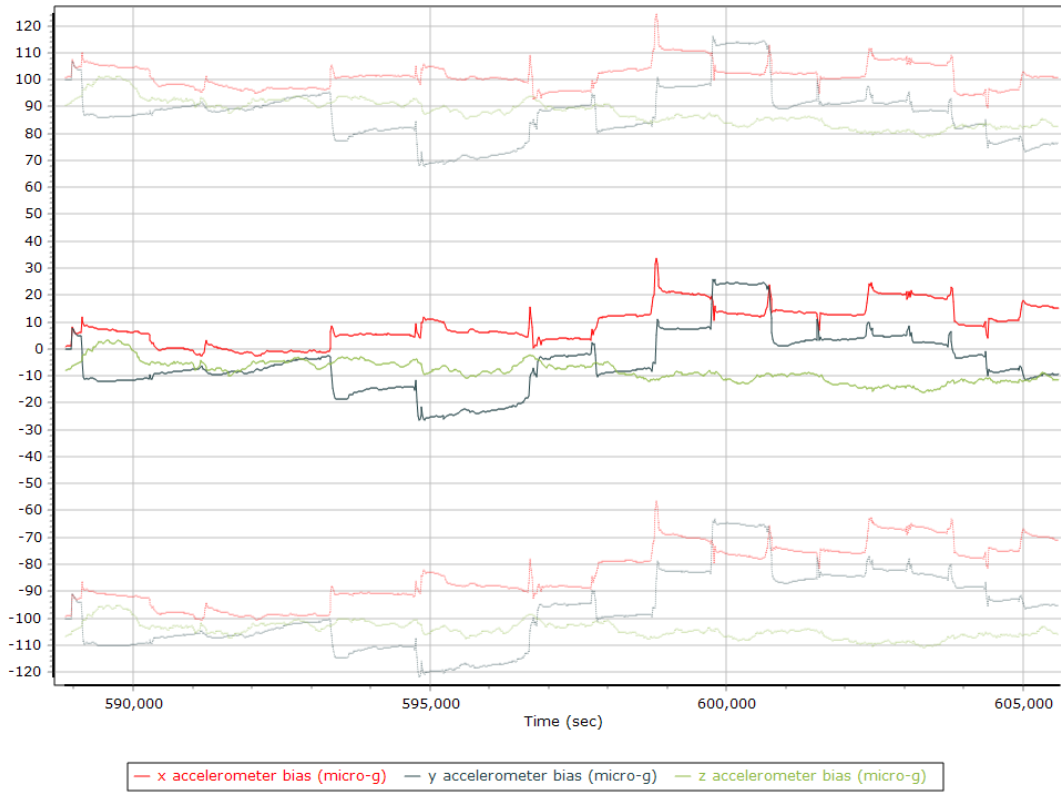
## PDOP



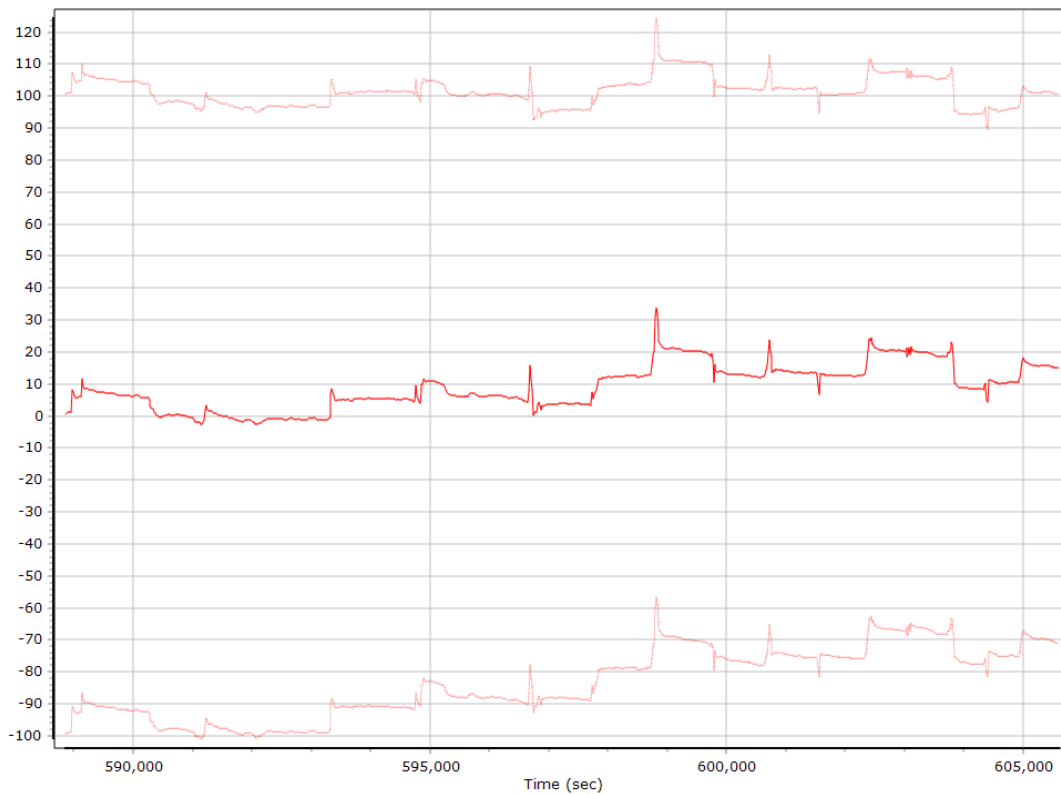
## IN-Fusion QC

### Forward Processed Estimated Errors, Reference Frame

#### Accelerometer Bias (micro-g)

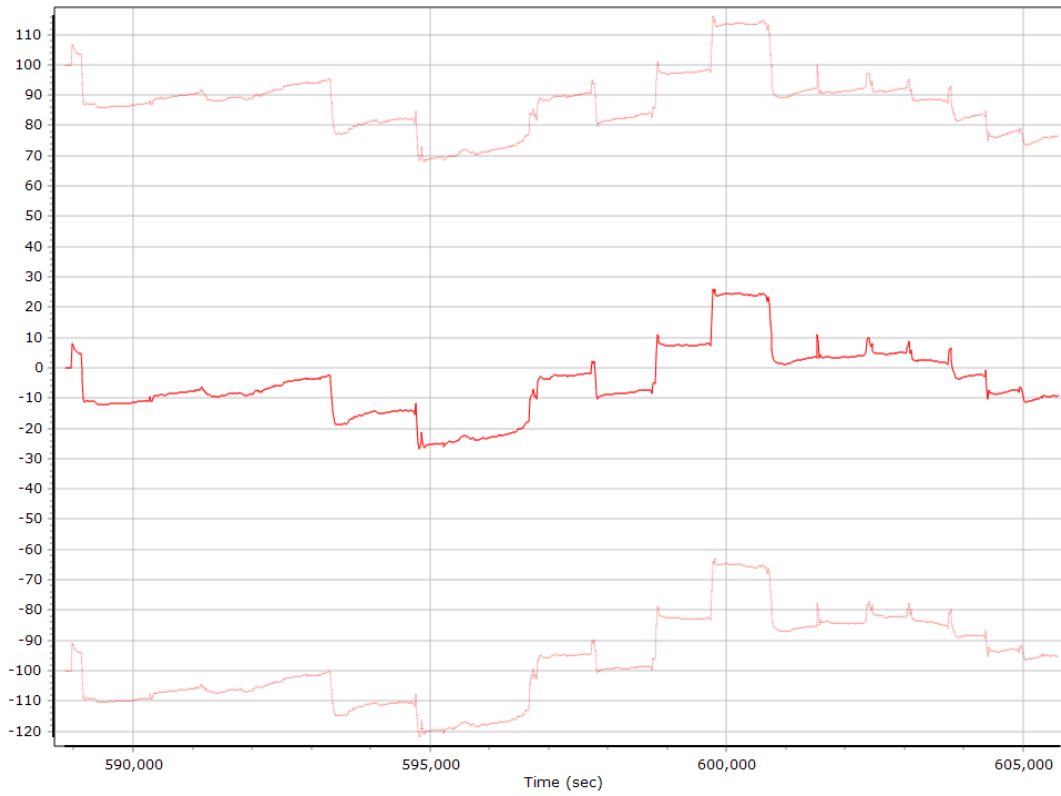


#### X Accelerometer Bias (micro-g)

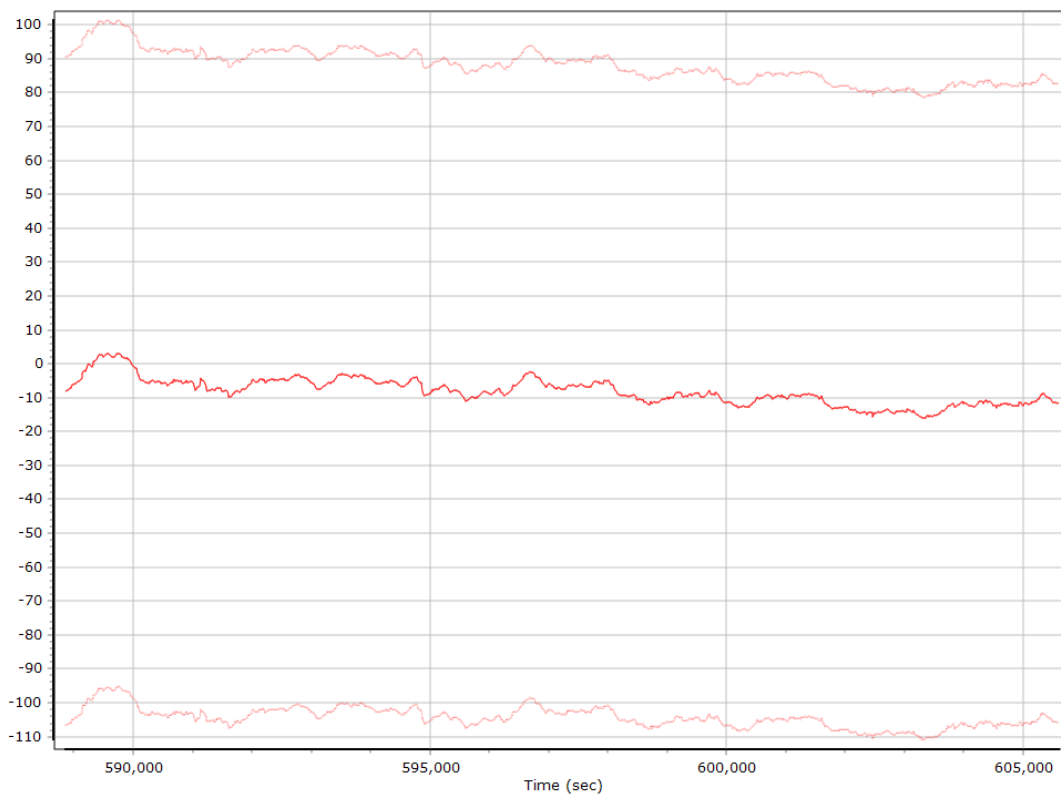




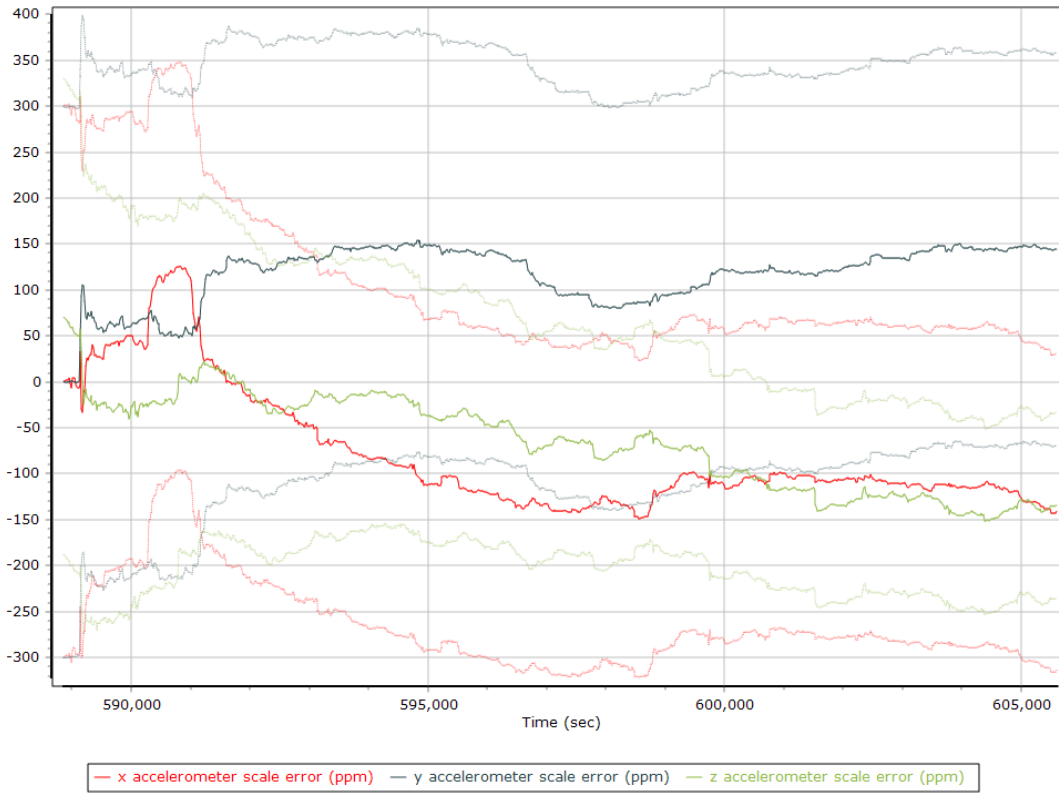
### Y Accelerometer Bias (micro-g)



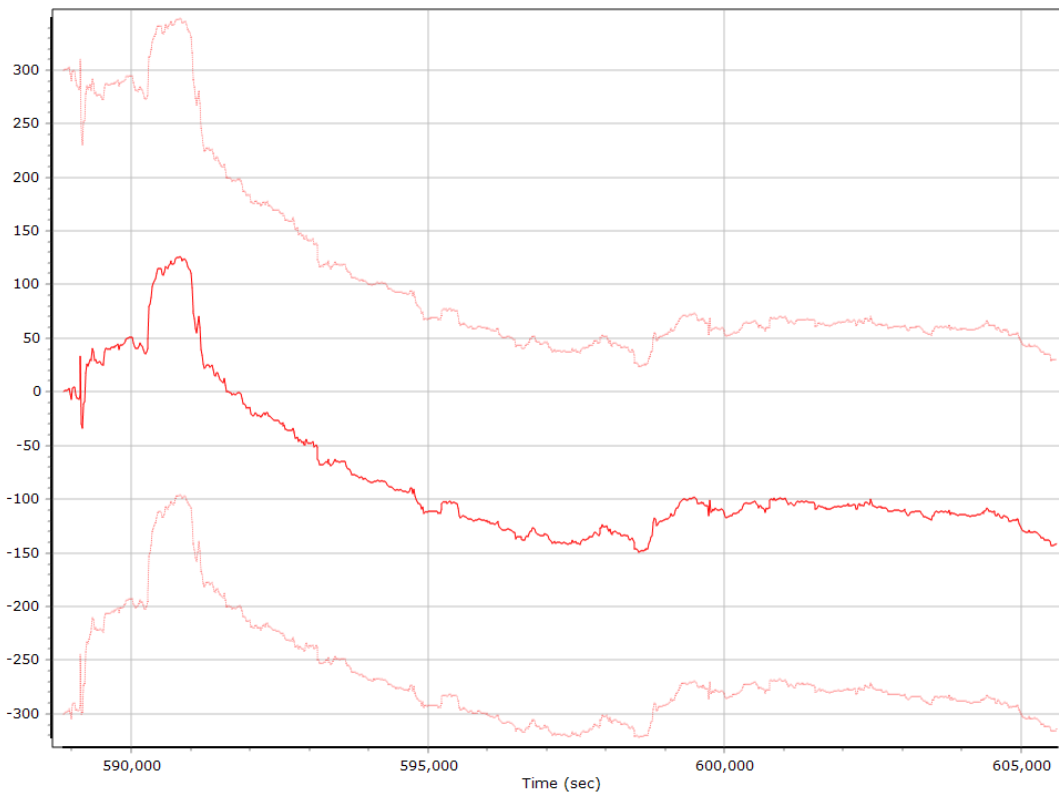
### Z Accelerometer Bias (micro-g)



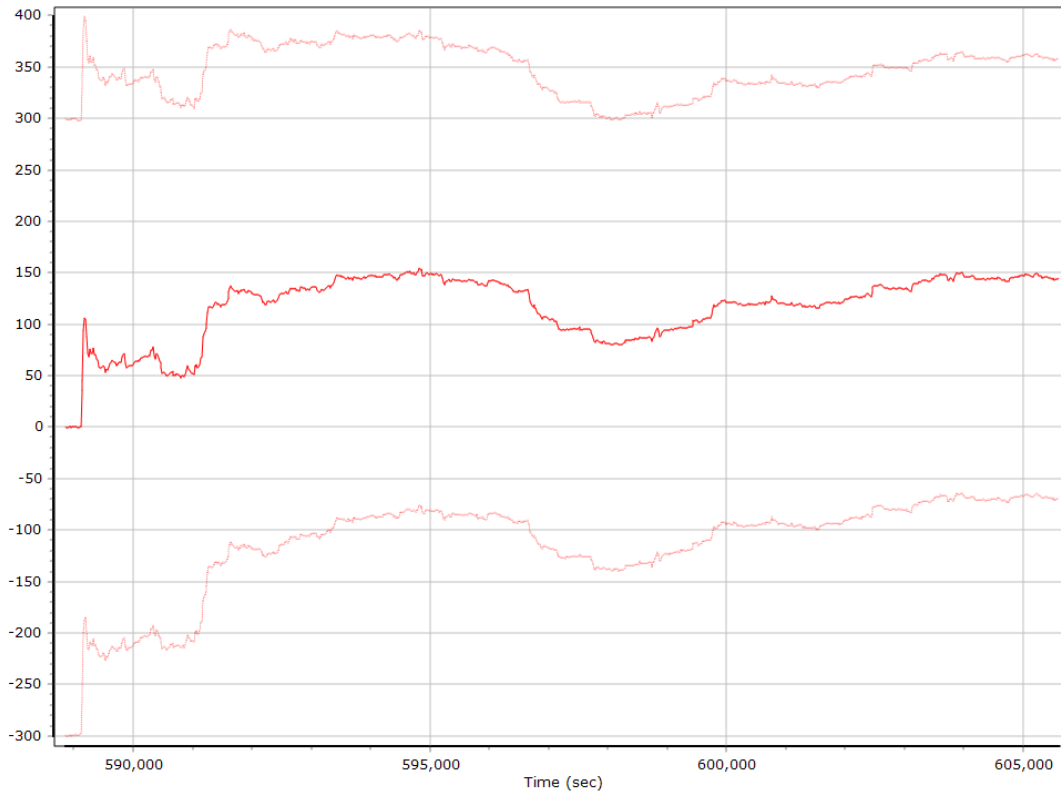
### Accelerometer Scale Error (ppm)



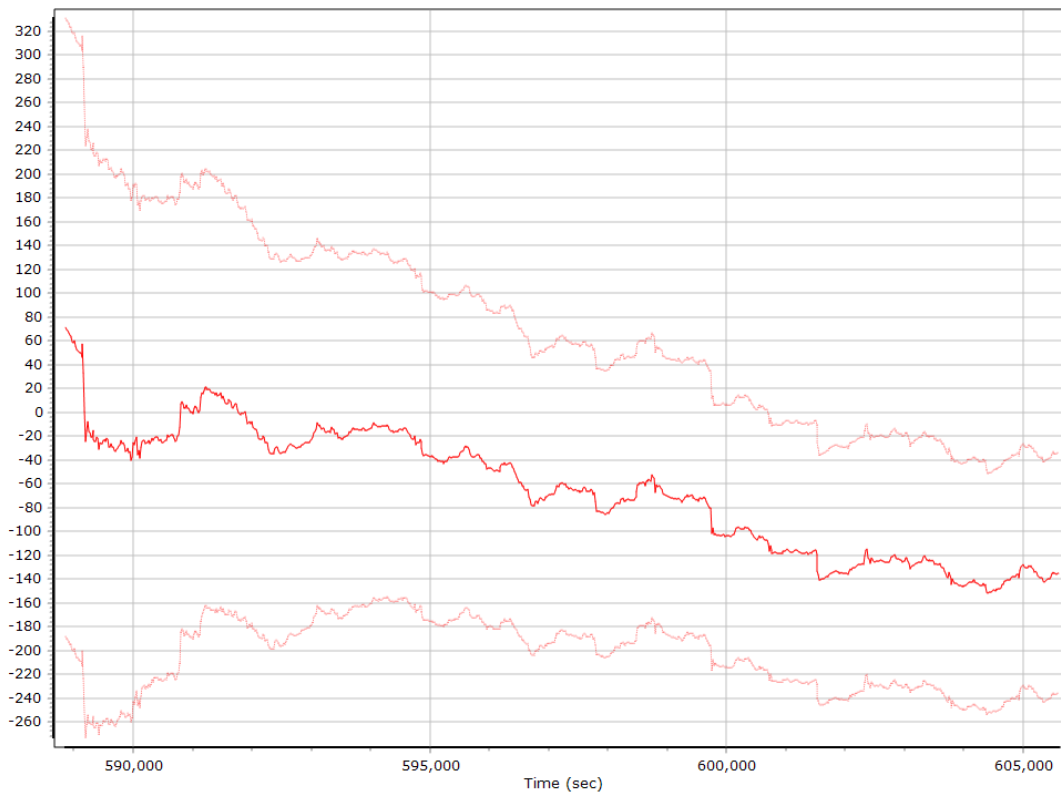
### X Accelerometer Scale Error (ppm)



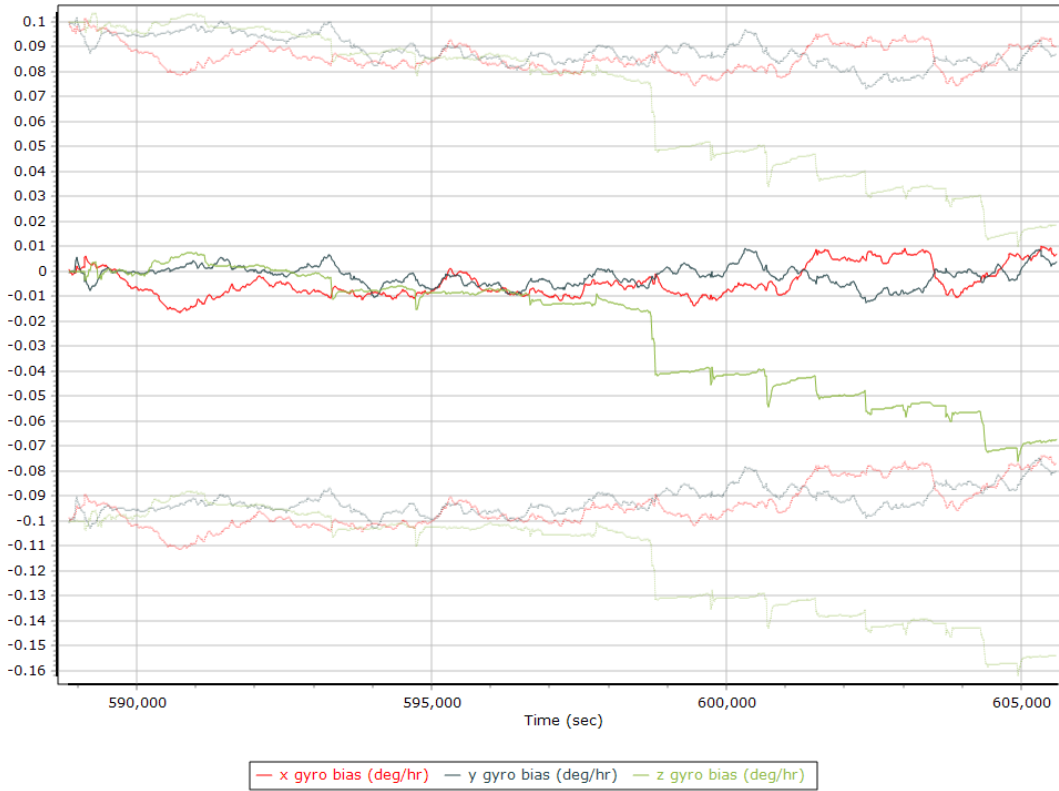
### Y Accelerometer Scale Error (ppm)



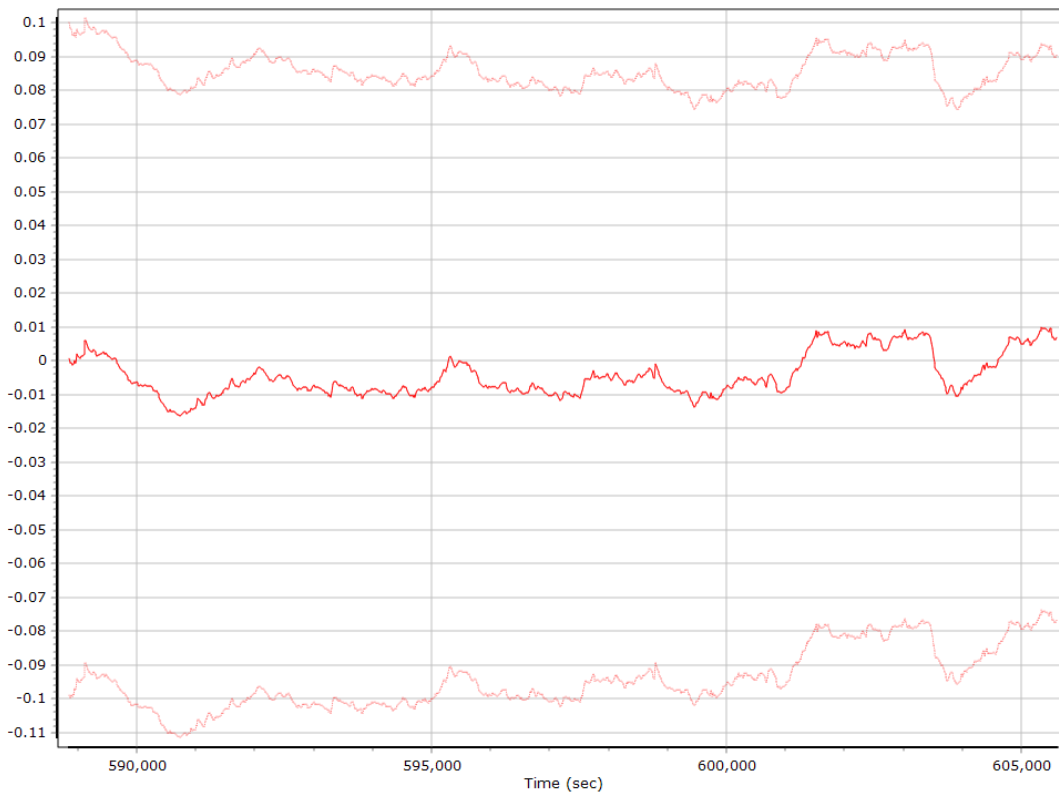
### Z Accelerometer Scale Error (ppm)



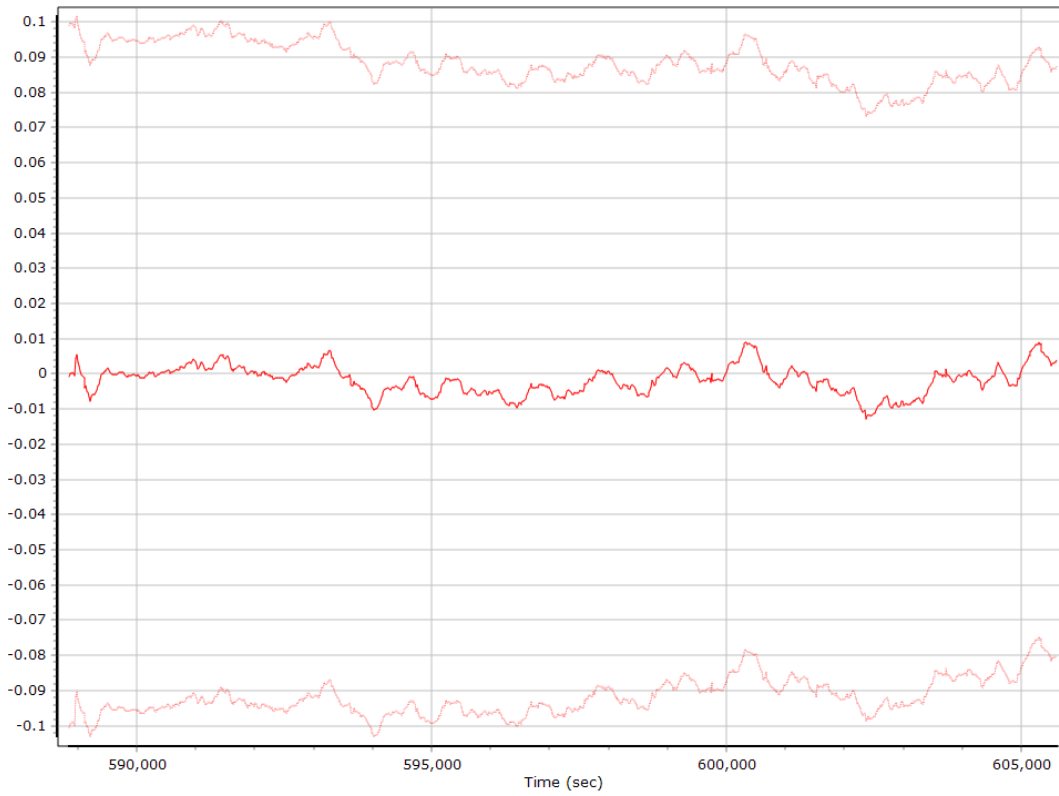
### Gyro Bias (deg/h)



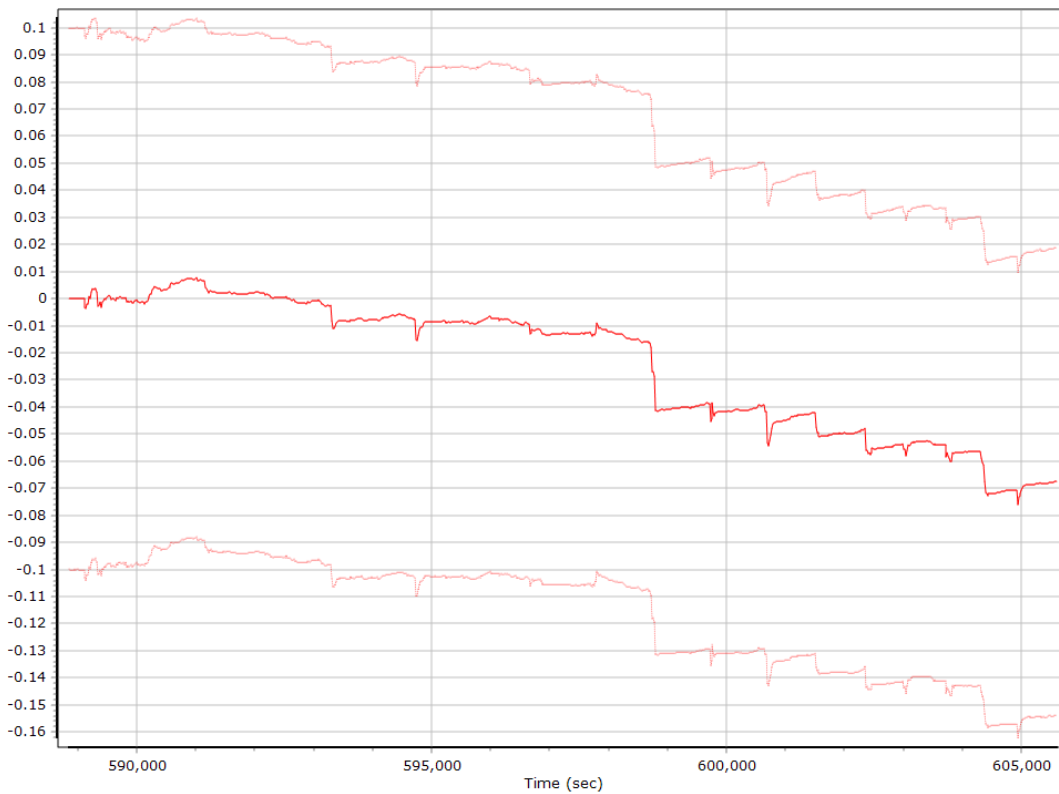
### X Gyro Bias (deg/h)



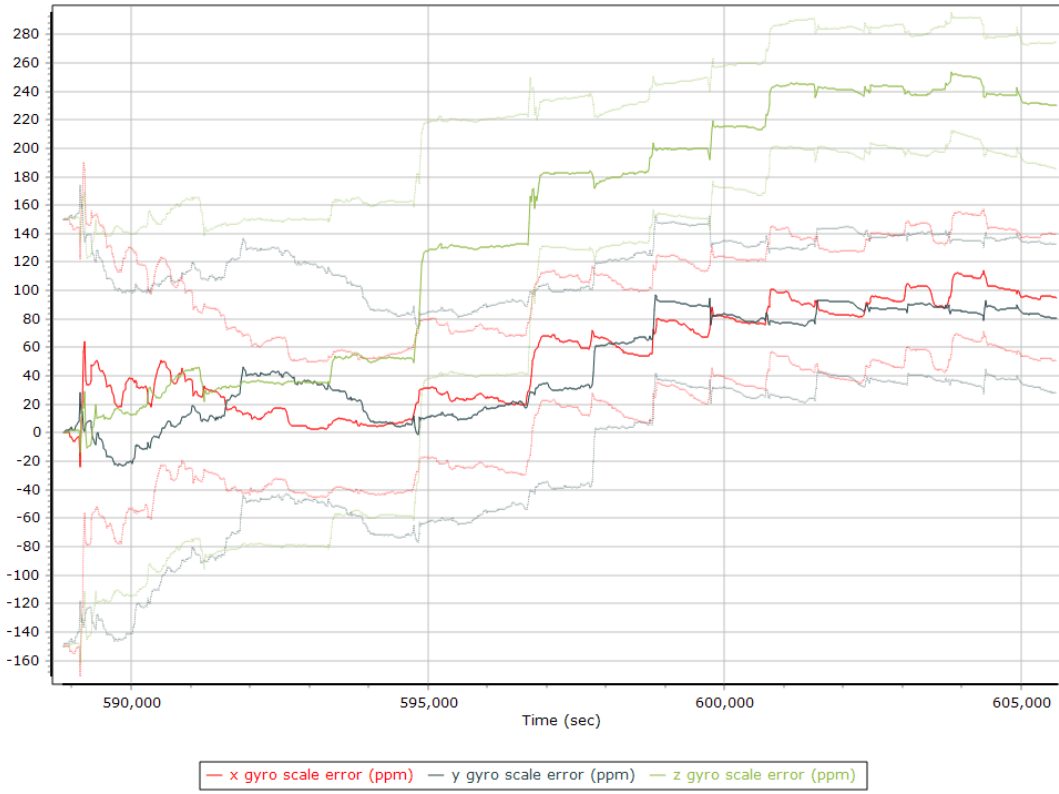
### Y Gyro Bias (deg/h)



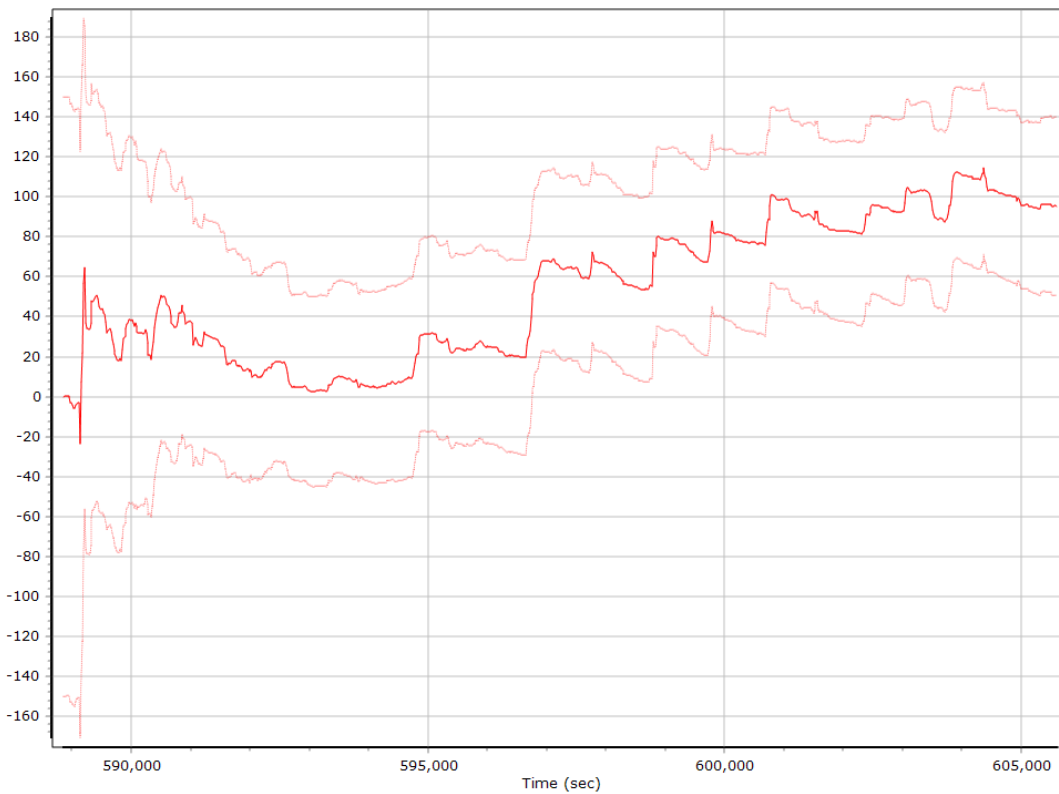
### Z Gyro Bias (deg/h)



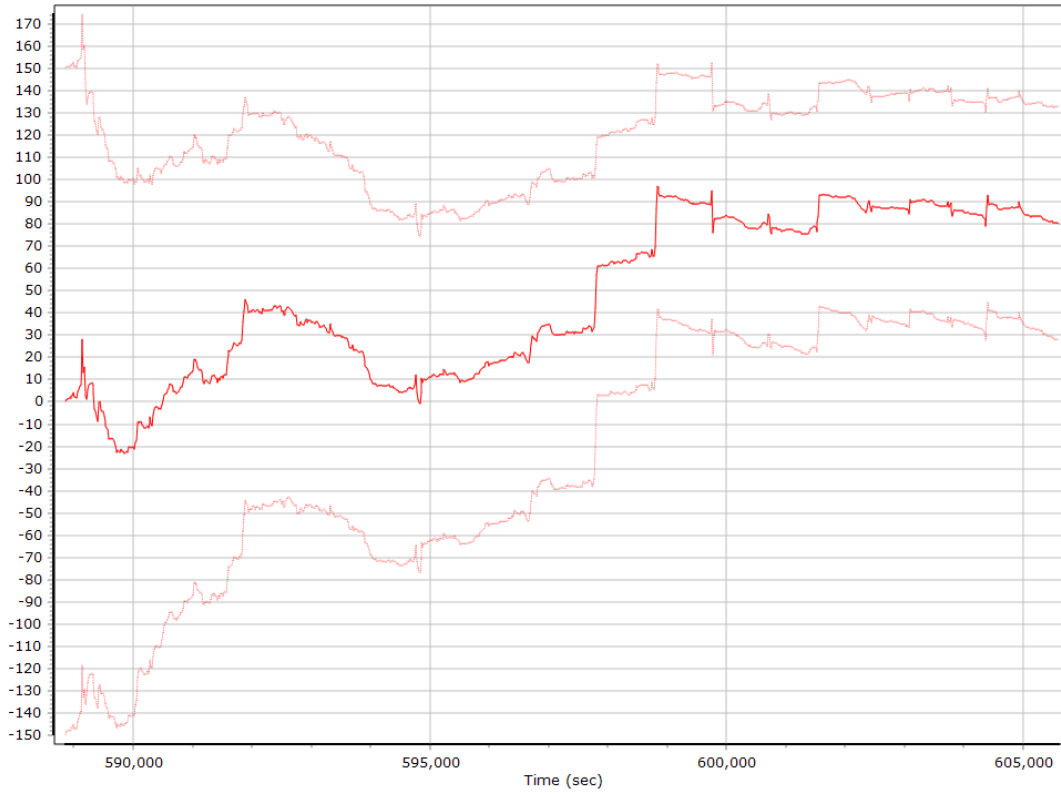
### Gyro Scale Error (ppm)



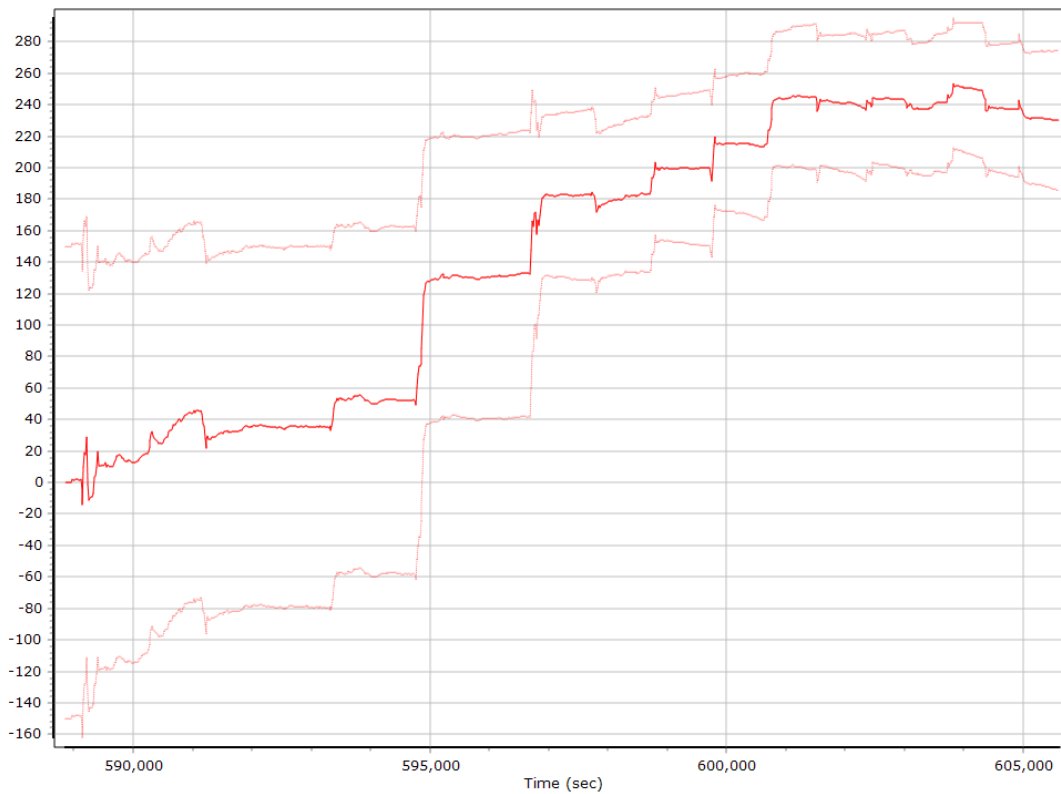
### X Gyro Scale Error (ppm)



### Y Gyro Scale Error (ppm)

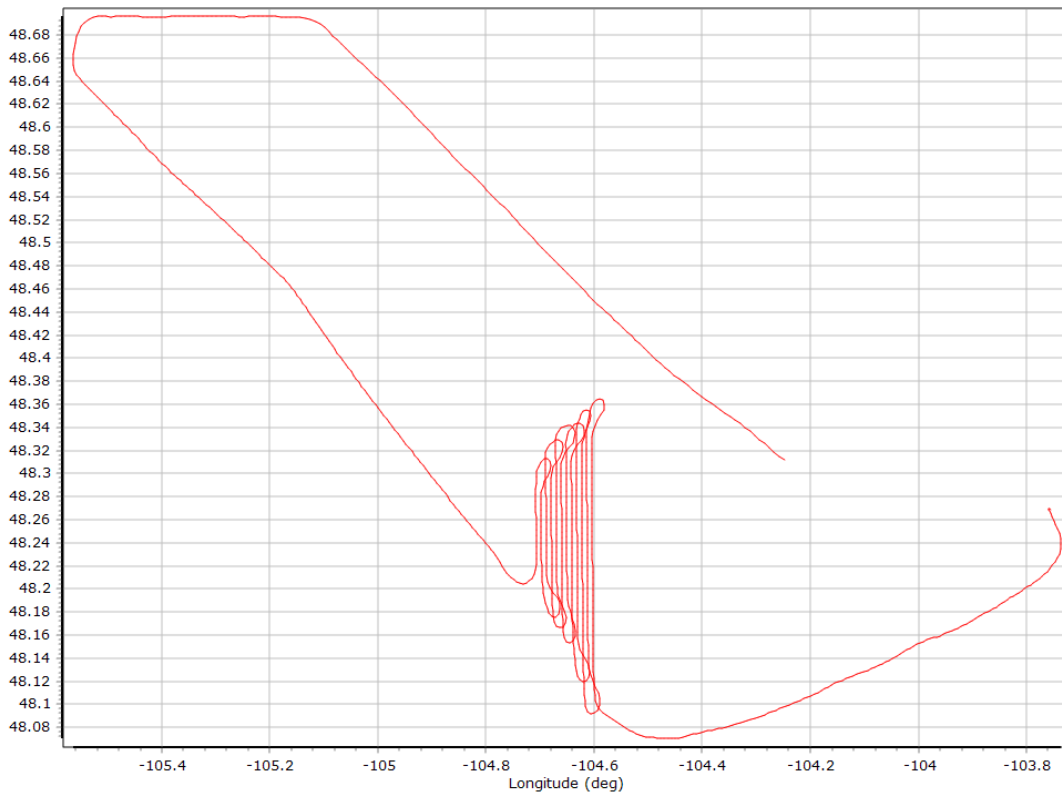


### Z Gyro Scale Error (ppm)

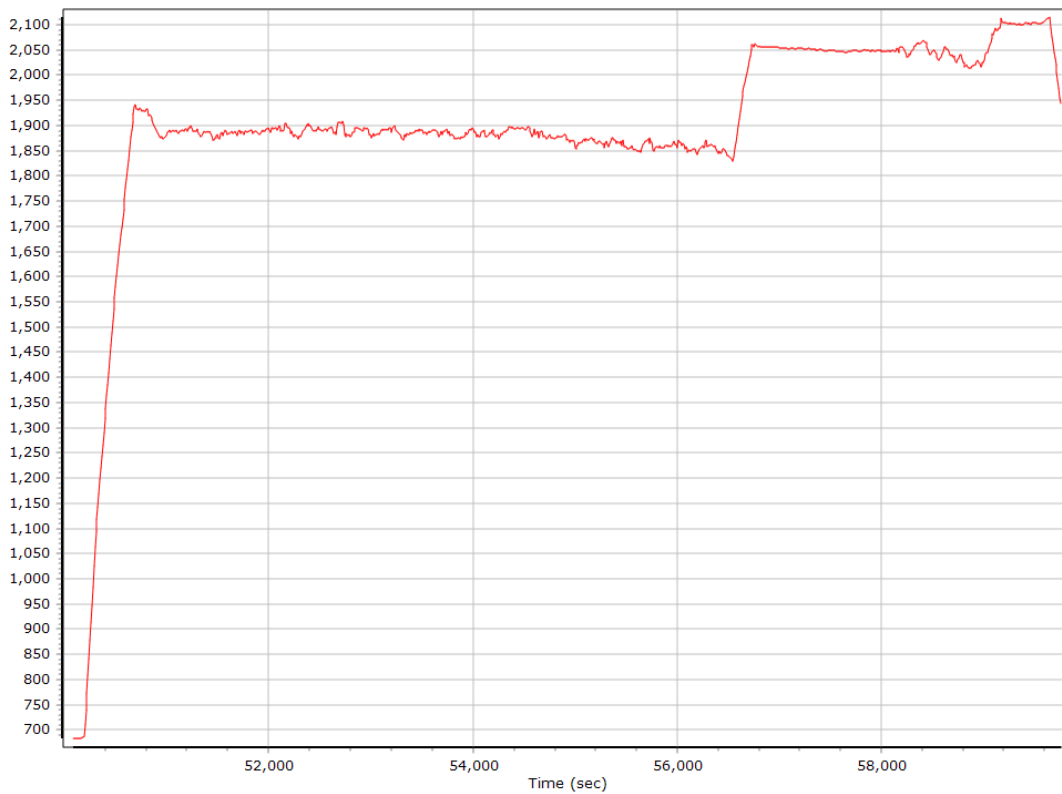


## Smoothed Trajectory Information

### Top View



### Altitude



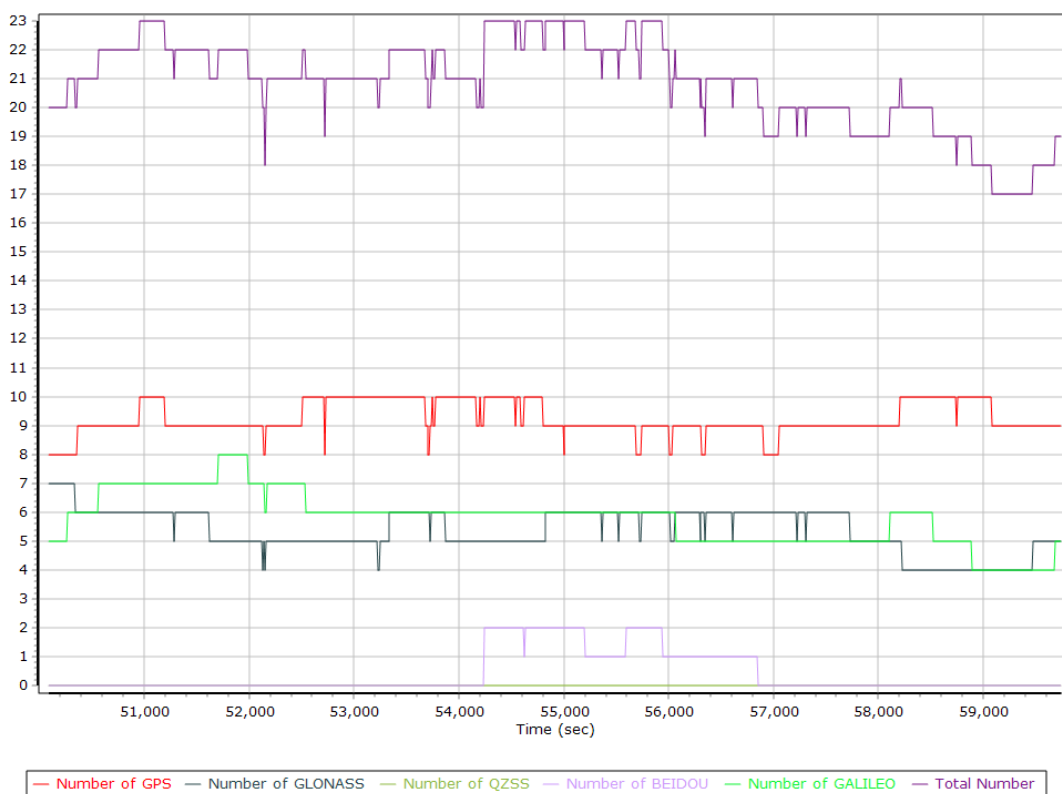


## GNSS QC

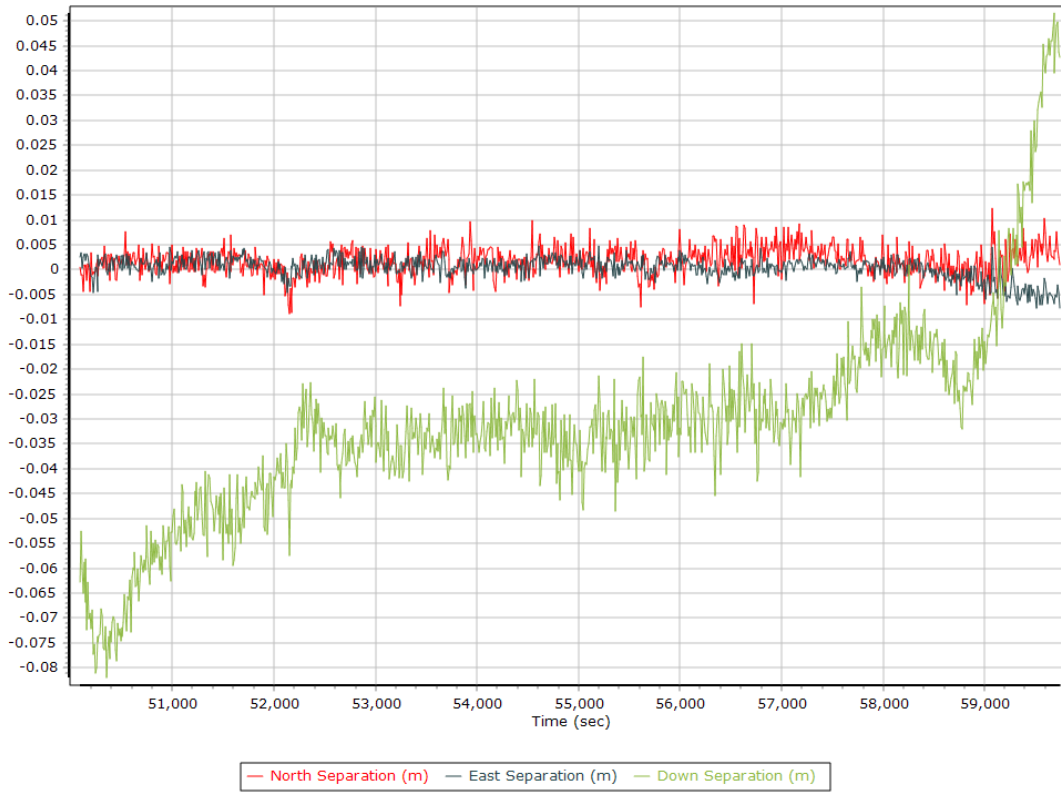
### GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	8	10	9
Number of GLONASS SV	0	7	5
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	2	0
Number of GALILEO SV	4	8	6
Total number of SV	13	23	21
PDOP	1.06	1.62	1.19
QC Solution Gaps	0.00	0.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	9893.00	0.00	0.00
Percentage	100.00	0.00	0.00

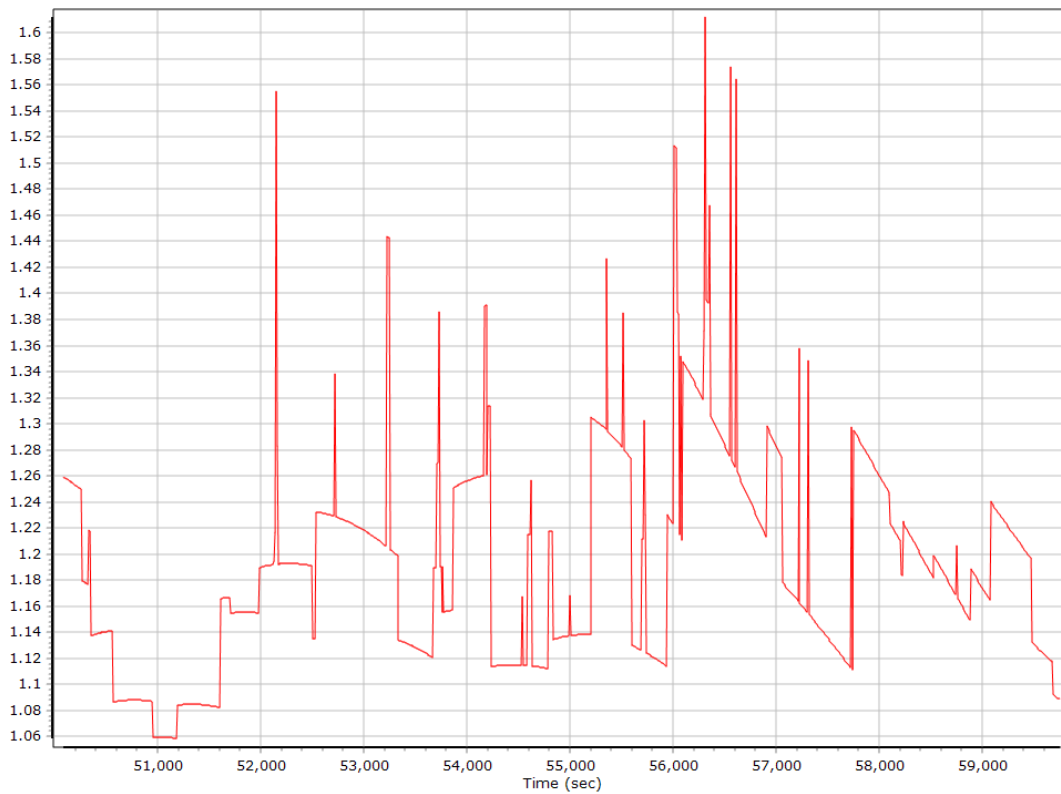
### Num SVs in solution



## Forward/Reverse Separation



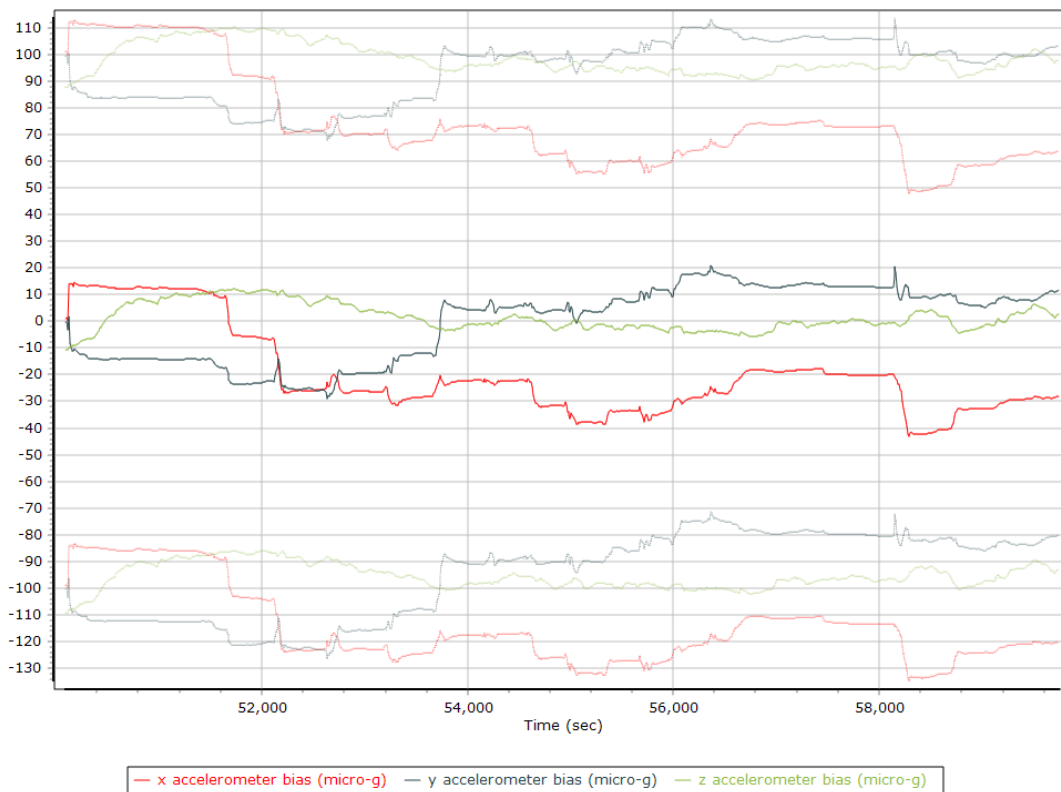
## PDOP



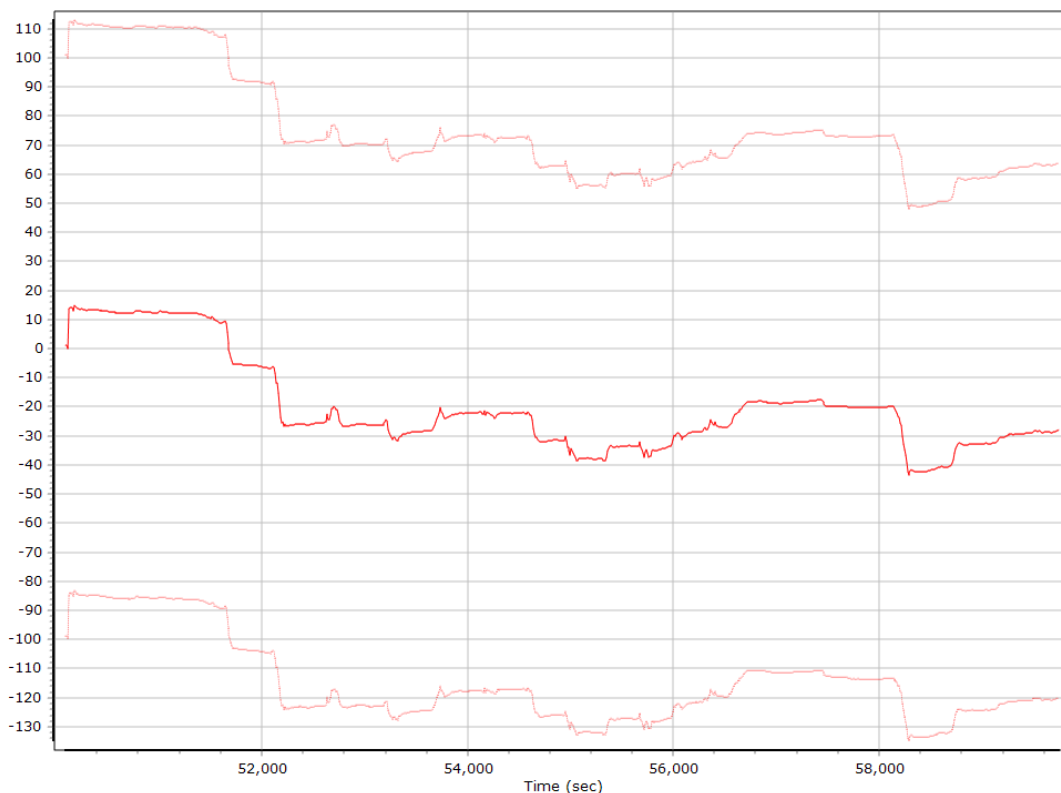
## IN-Fusion QC

### Forward Processed Estimated Errors, Reference Frame

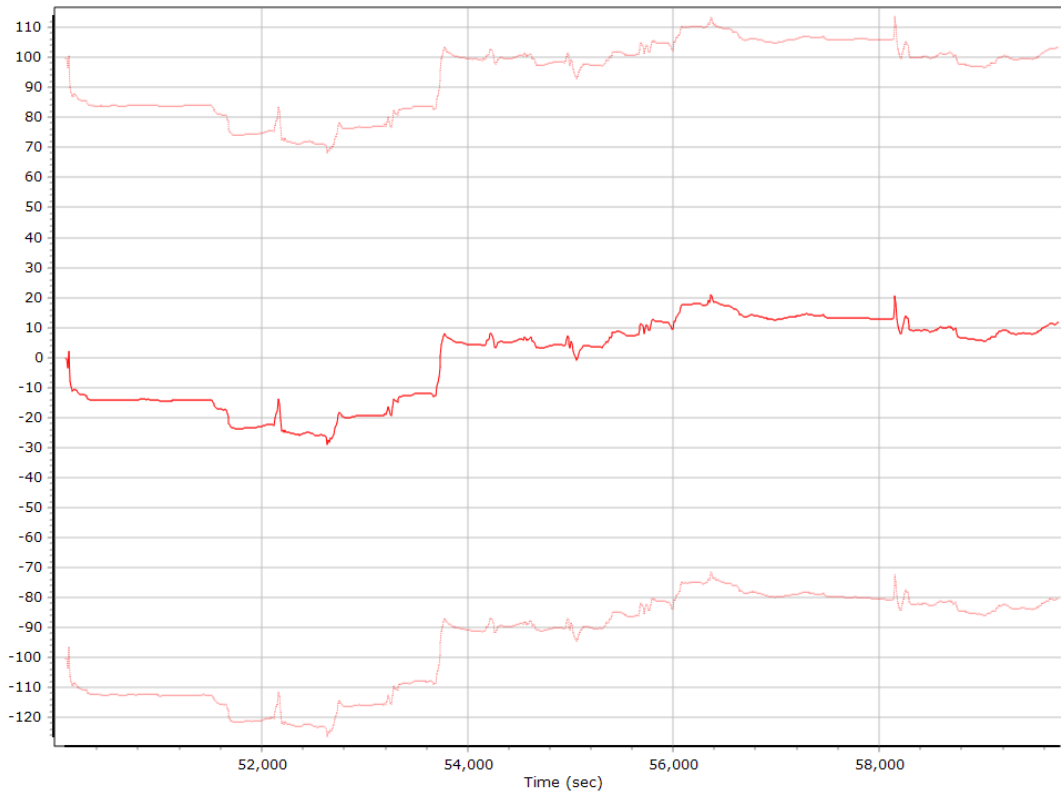
#### Accelerometer Bias (micro-g)



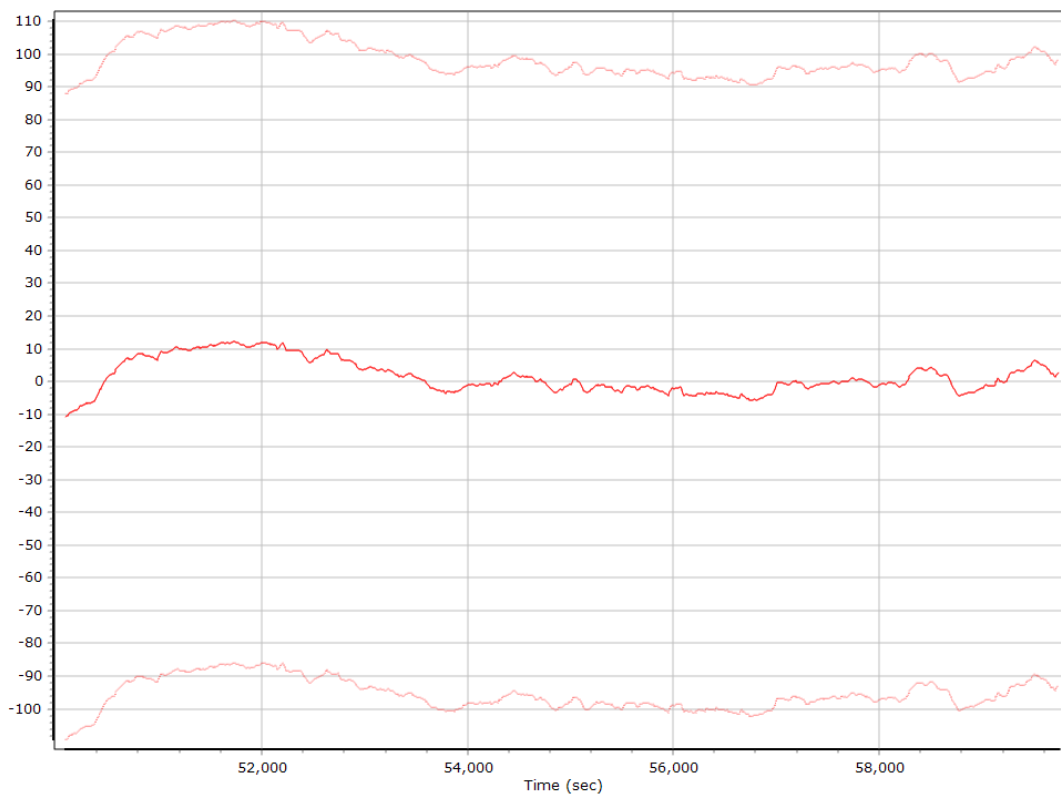
#### X Accelerometer Bias (micro-g)



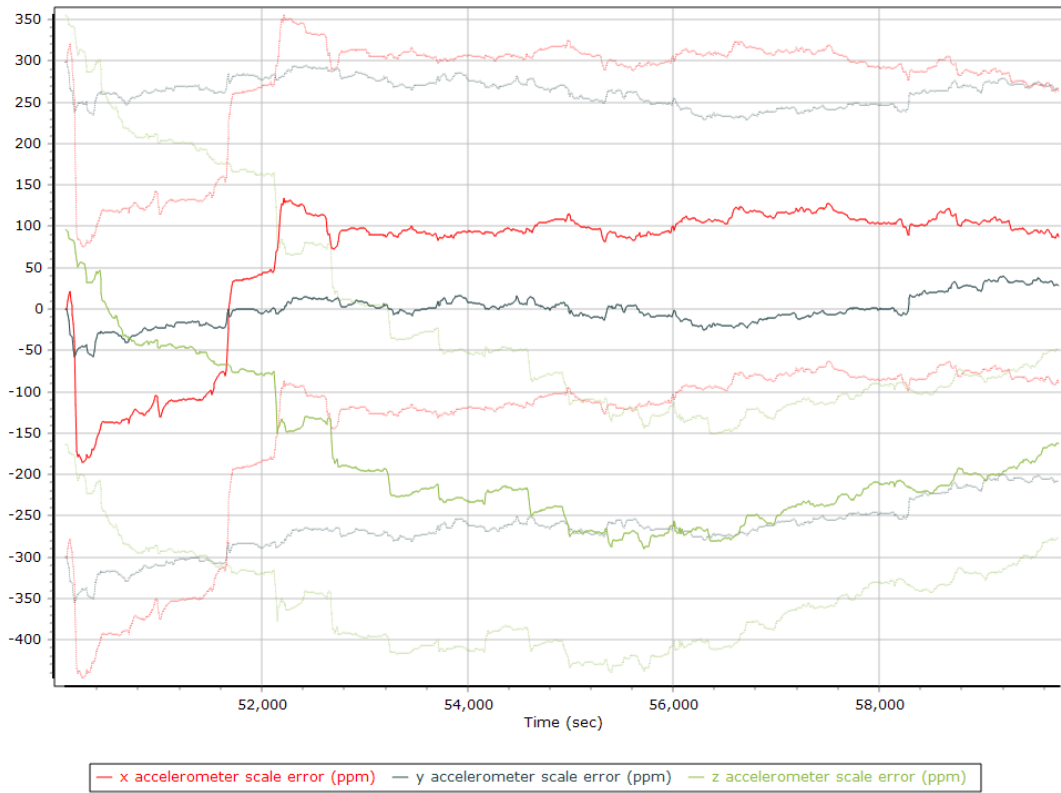
### Y Accelerometer Bias (micro-g)



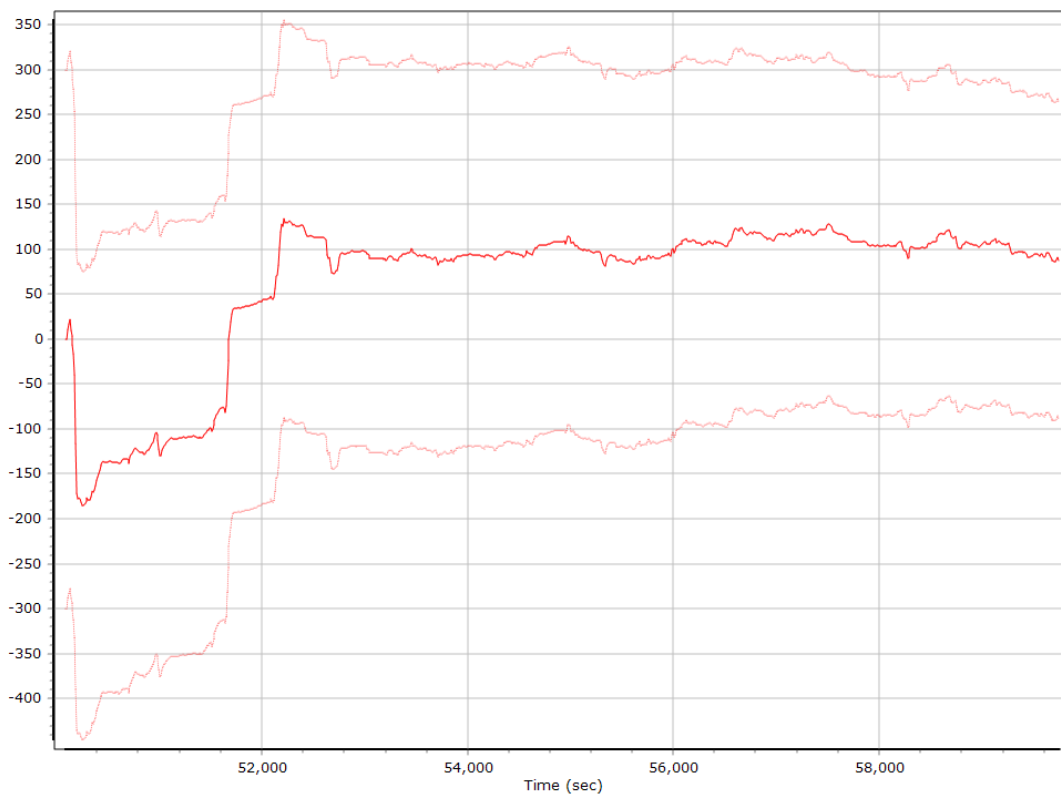
### Z Accelerometer Bias (micro-g)



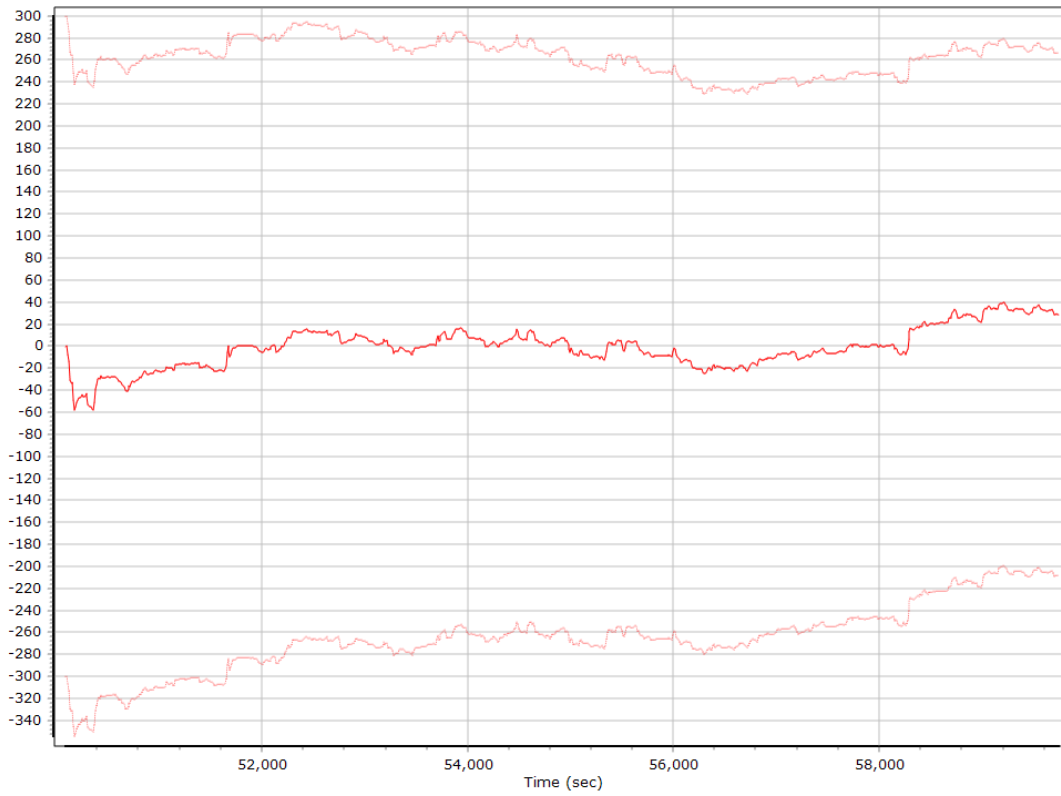
### Accelerometer Scale Error (ppm)



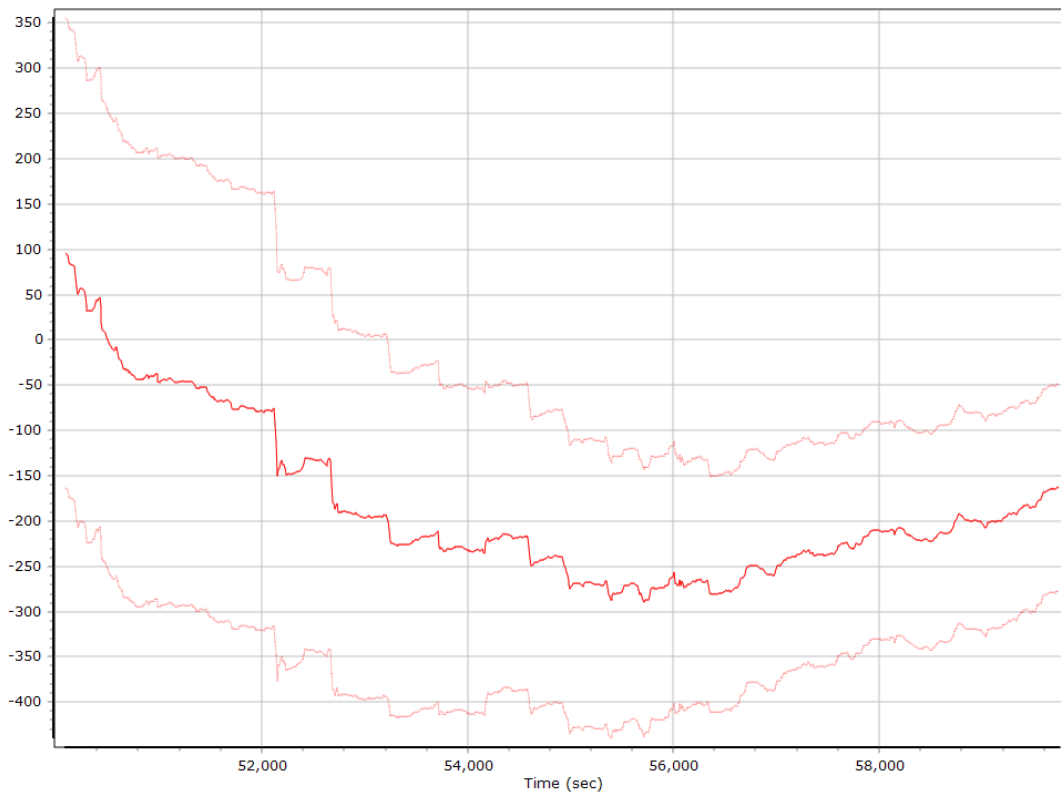
### X Accelerometer Scale Error (ppm)



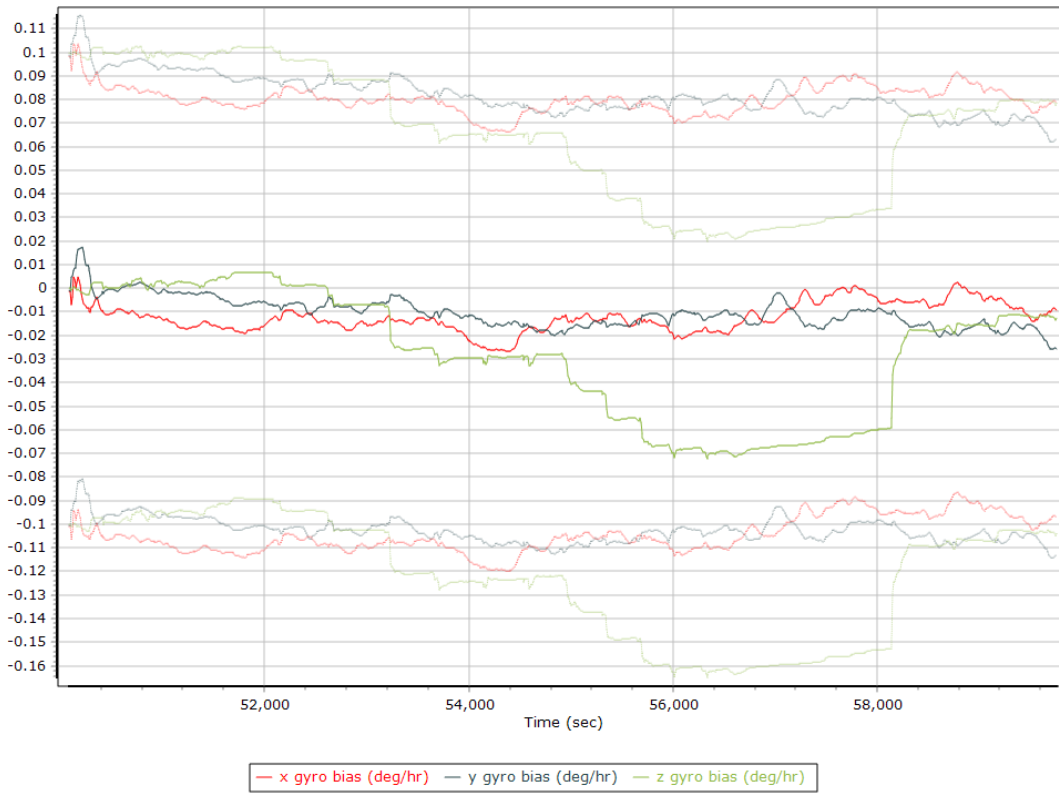
### Y Accelerometer Scale Error (ppm)



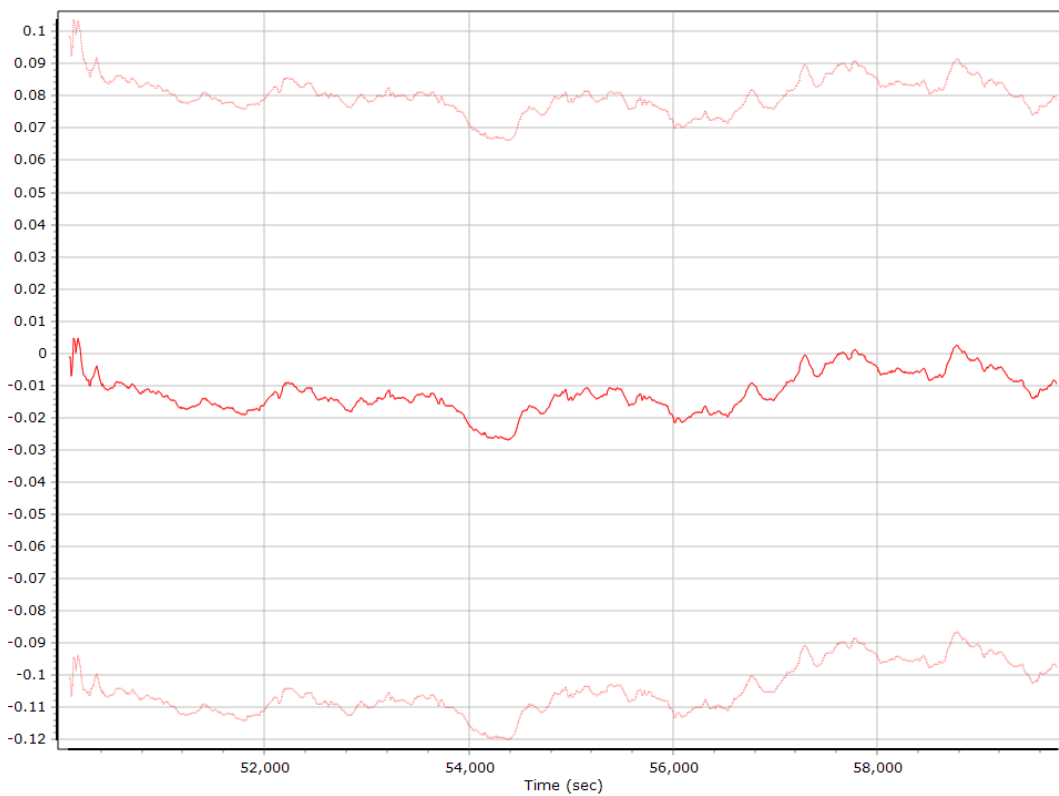
### Z Accelerometer Scale Error (ppm)



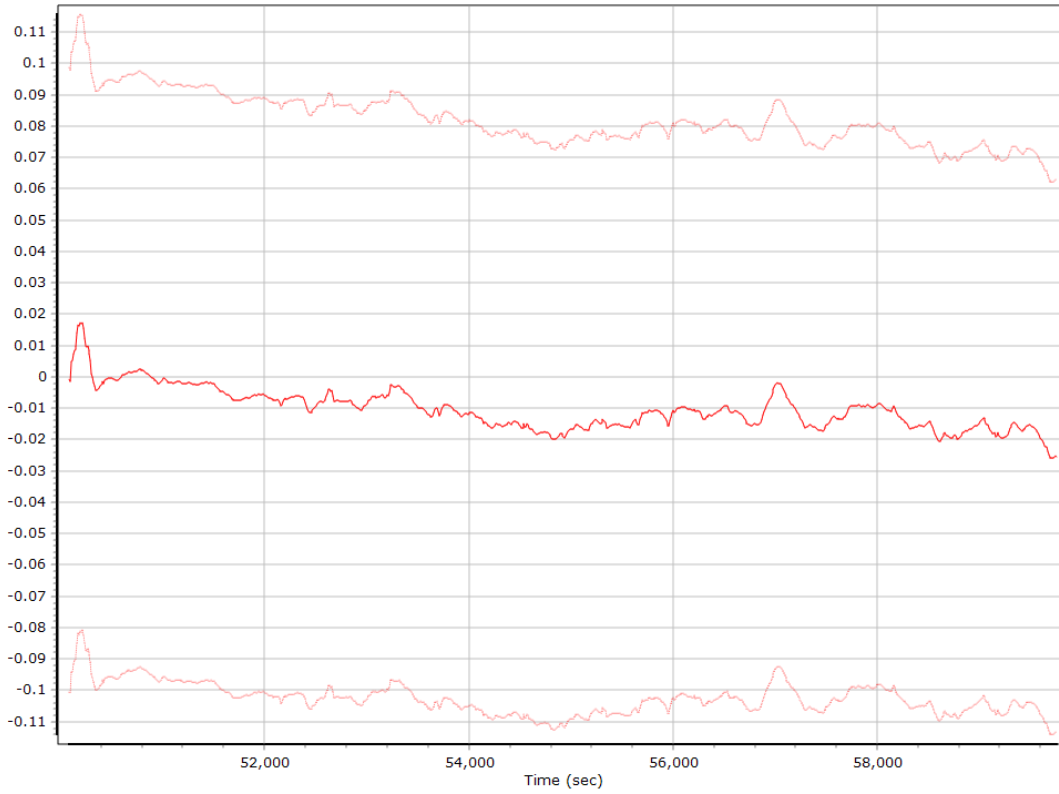
### Gyro Bias (deg/h)



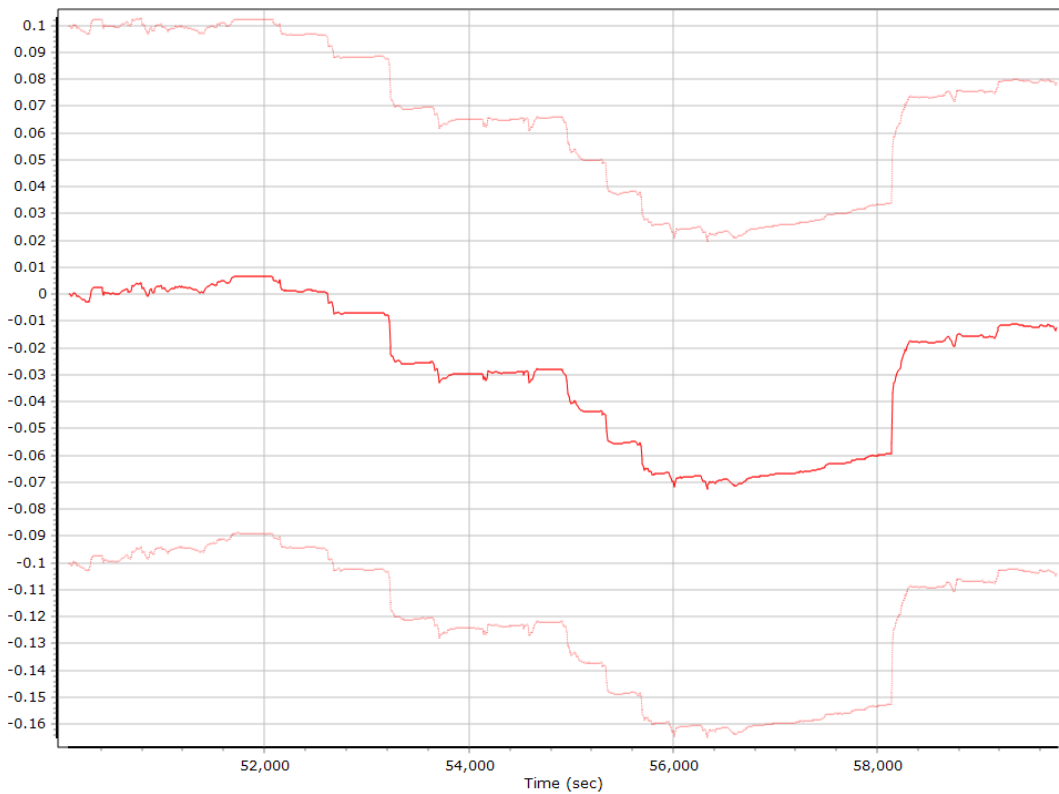
### X Gyro Bias (deg/h)



### Y Gyro Bias (deg/h)

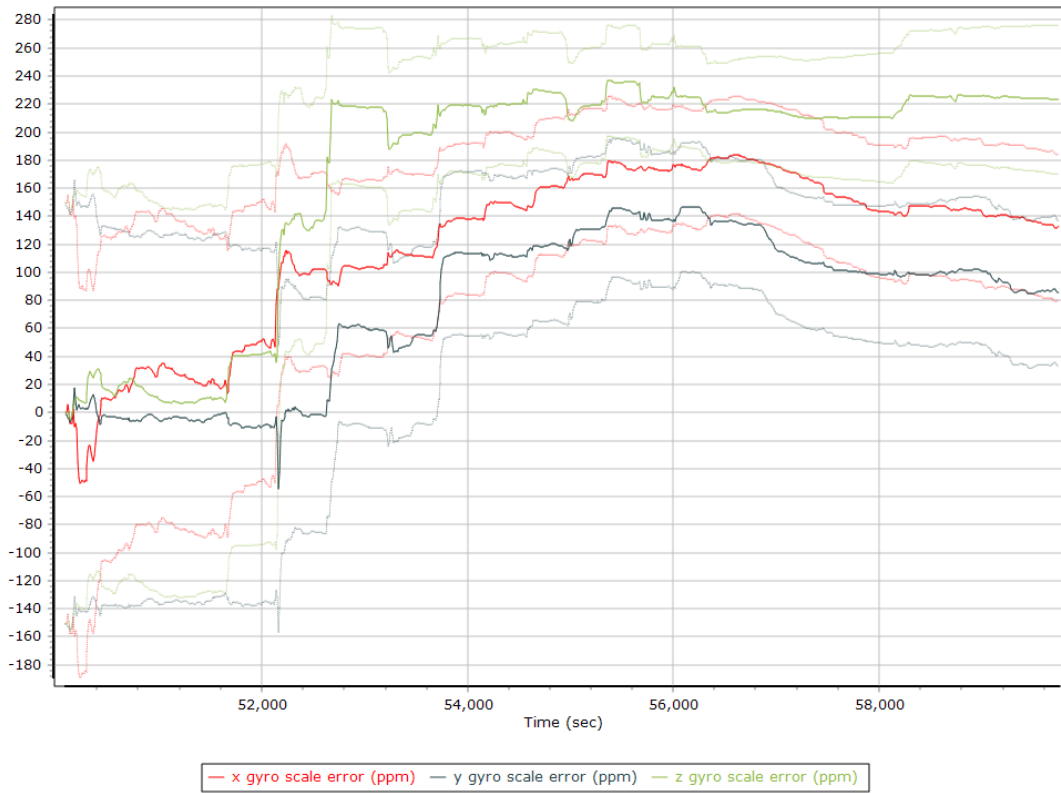


### Z Gyro Bias (deg/h)

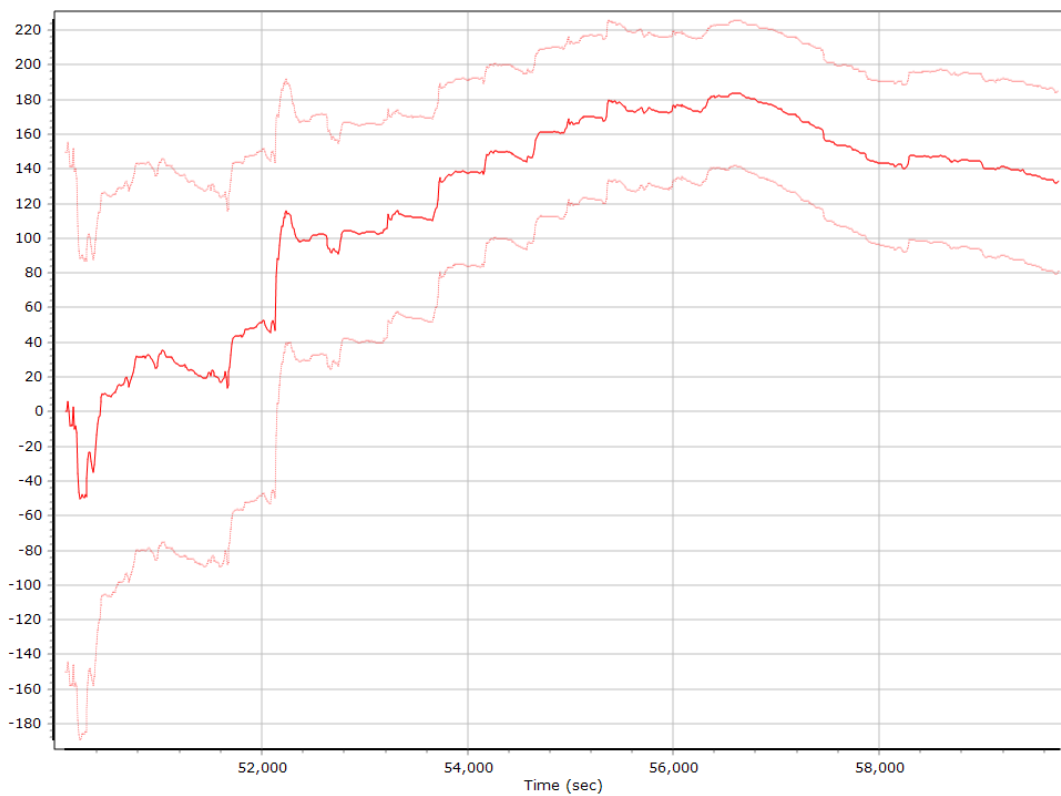




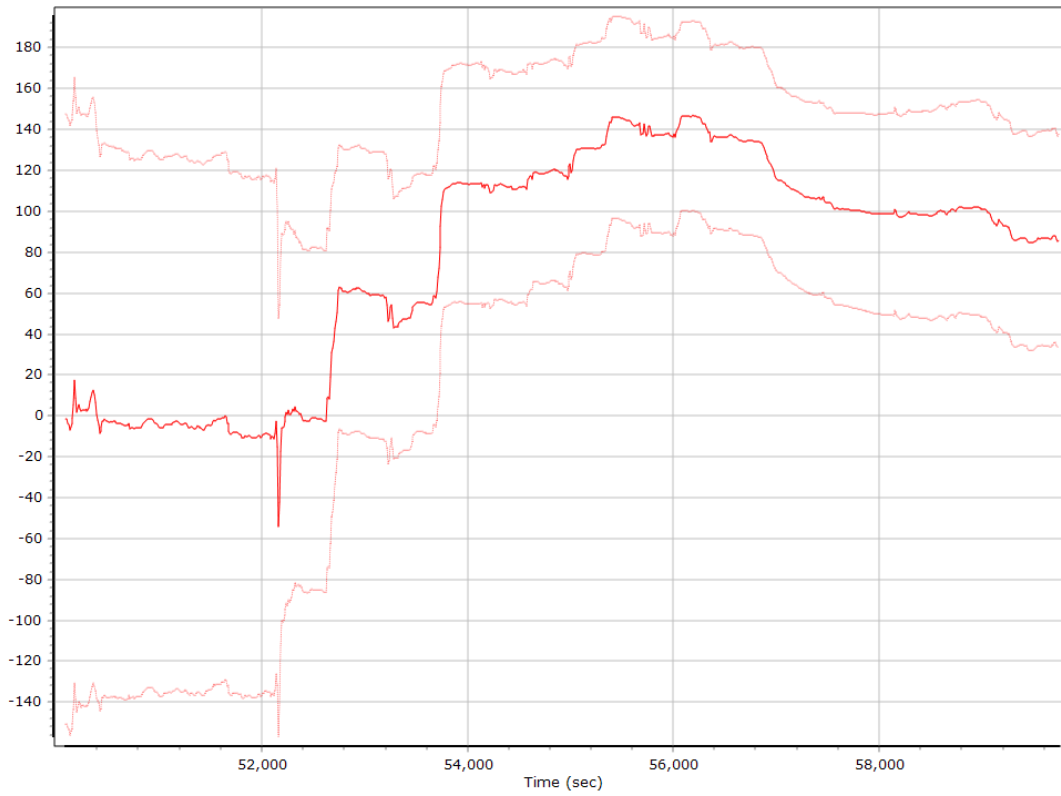
### Gyro Scale Error (ppm)



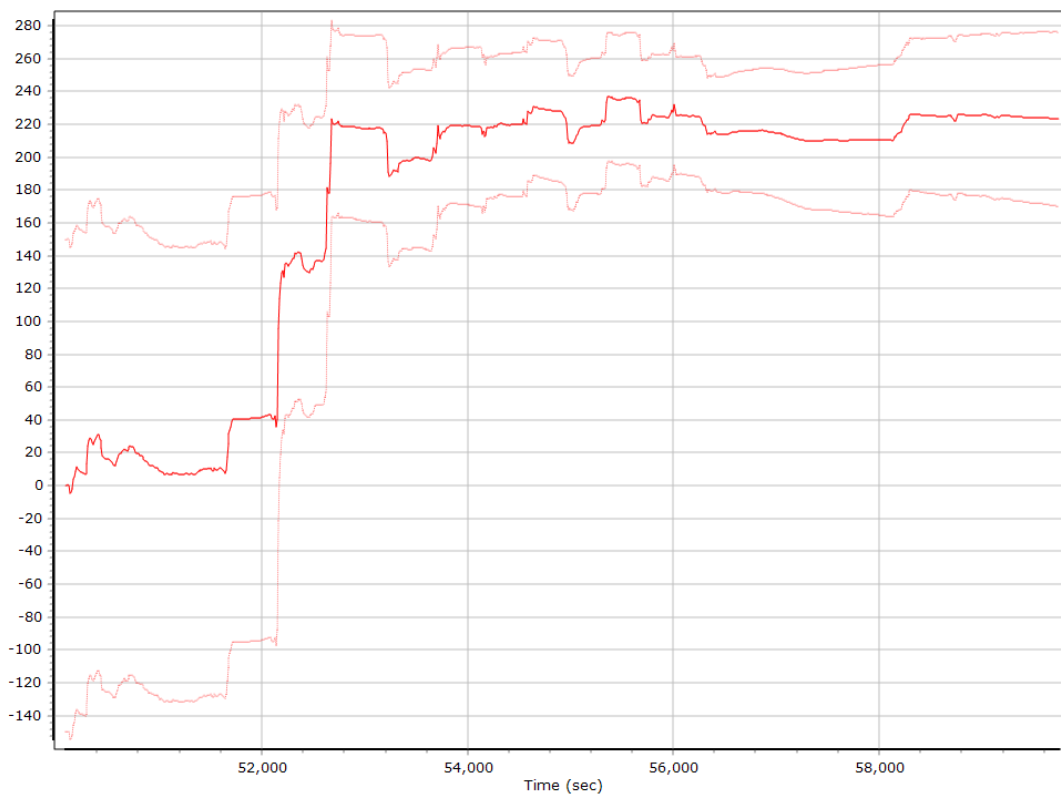
### X Gyro Scale Error (ppm)



### Y Gyro Scale Error (ppm)

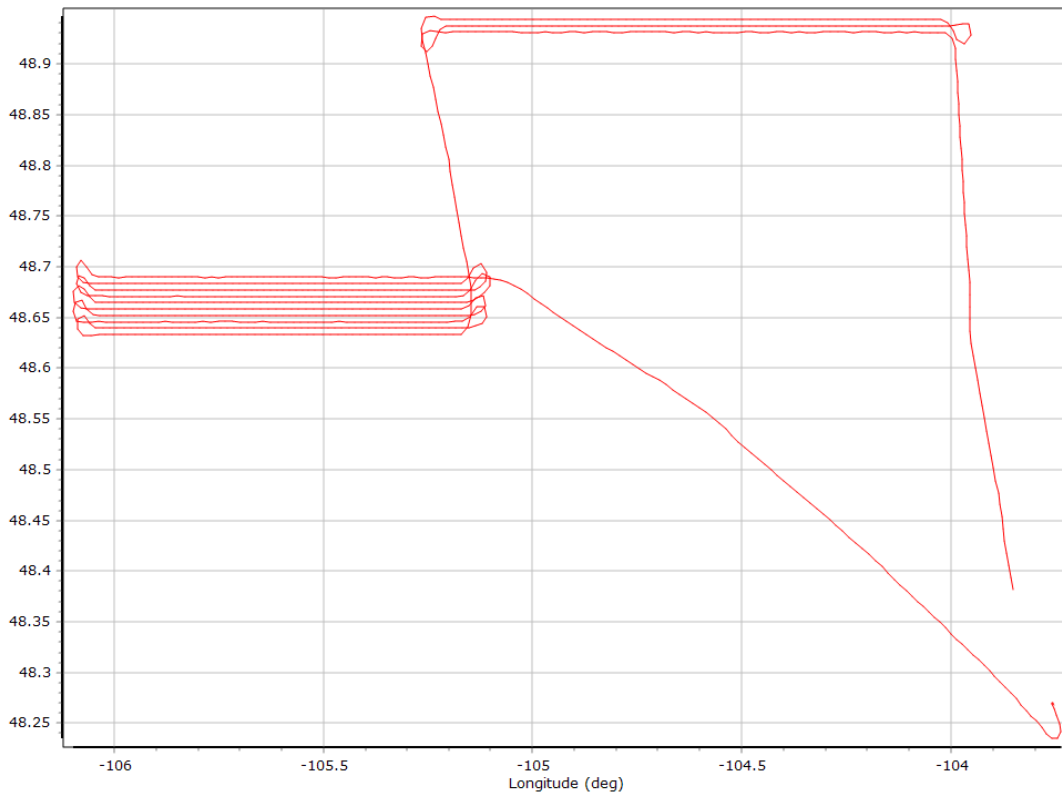


### Z Gyro Scale Error (ppm)

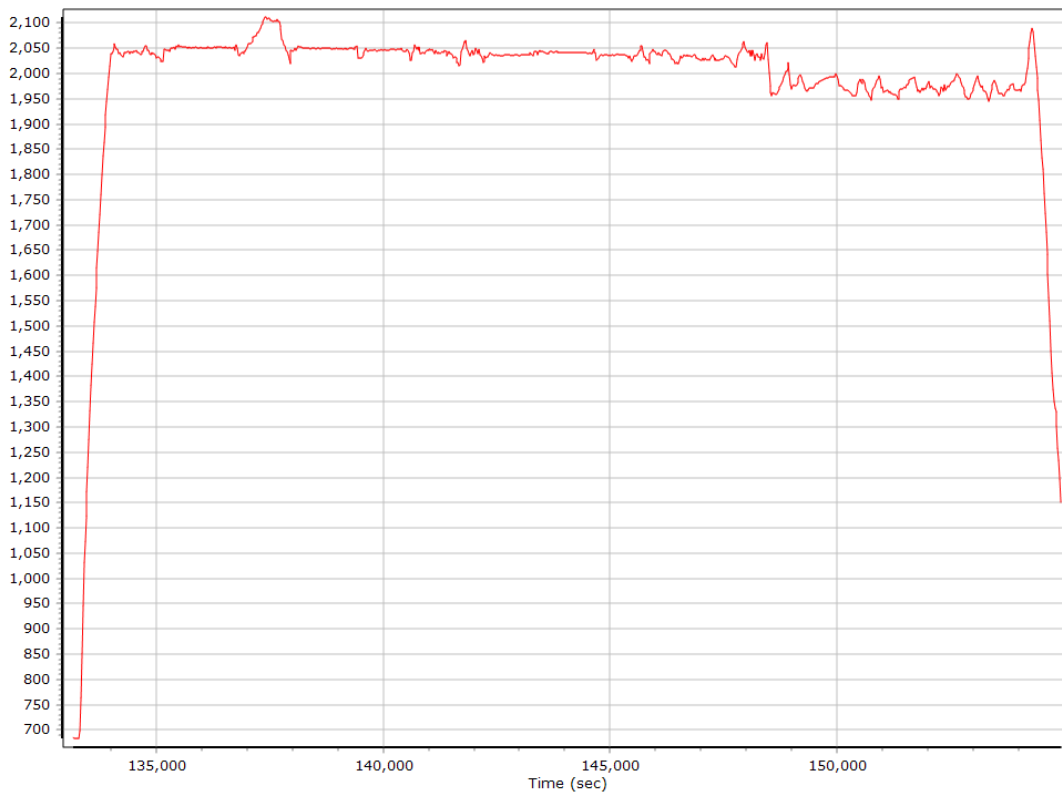


## Smoothed Trajectory Information

### Top View



### Altitude

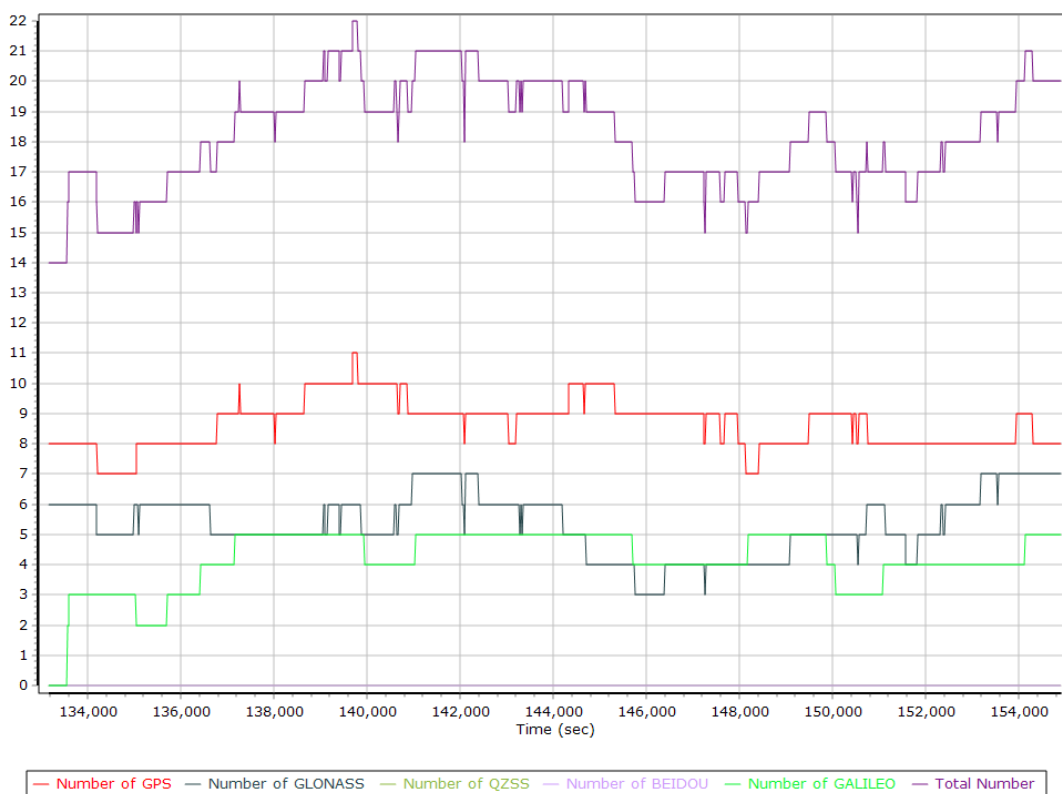


## GNSS QC

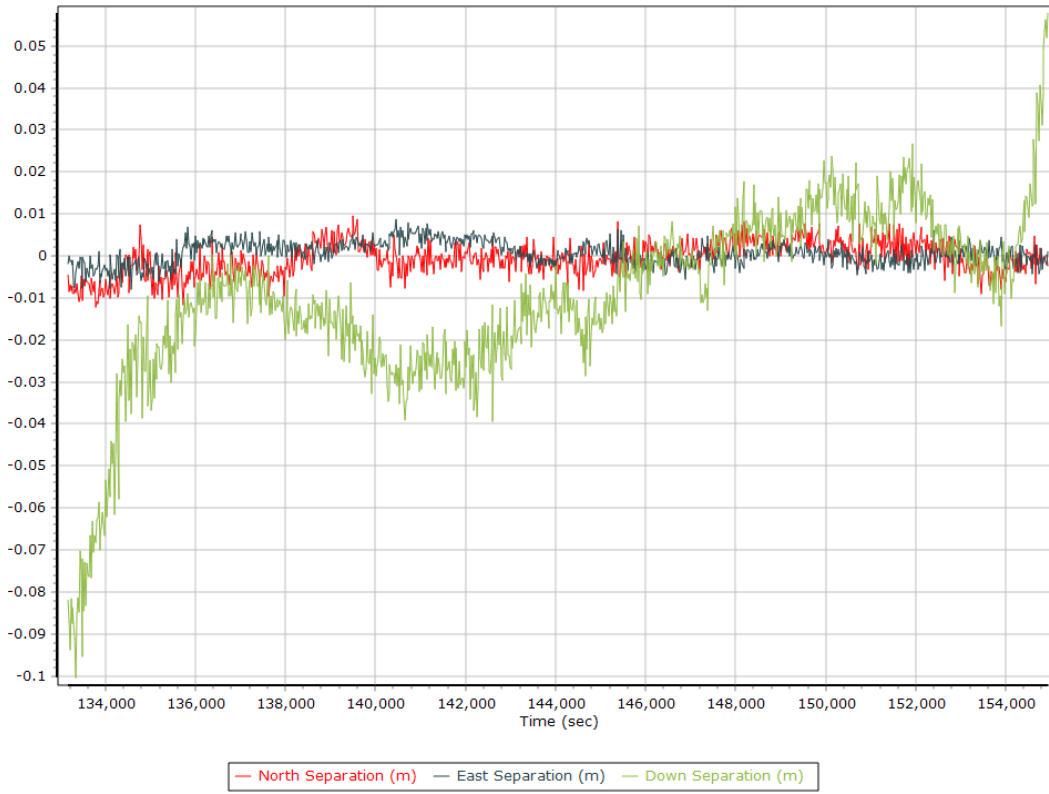
### GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	6	11	9
Number of GLONASS SV	0	7	5
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	0	0
Number of GALILEO SV	0	5	4
Total number of SV	8	22	18
PDOP	1.03	2.20	1.25
QC Solution Gaps	1.00	1.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	22067.00	0.00	1.00
Percentage	100.00	0.00	0.00

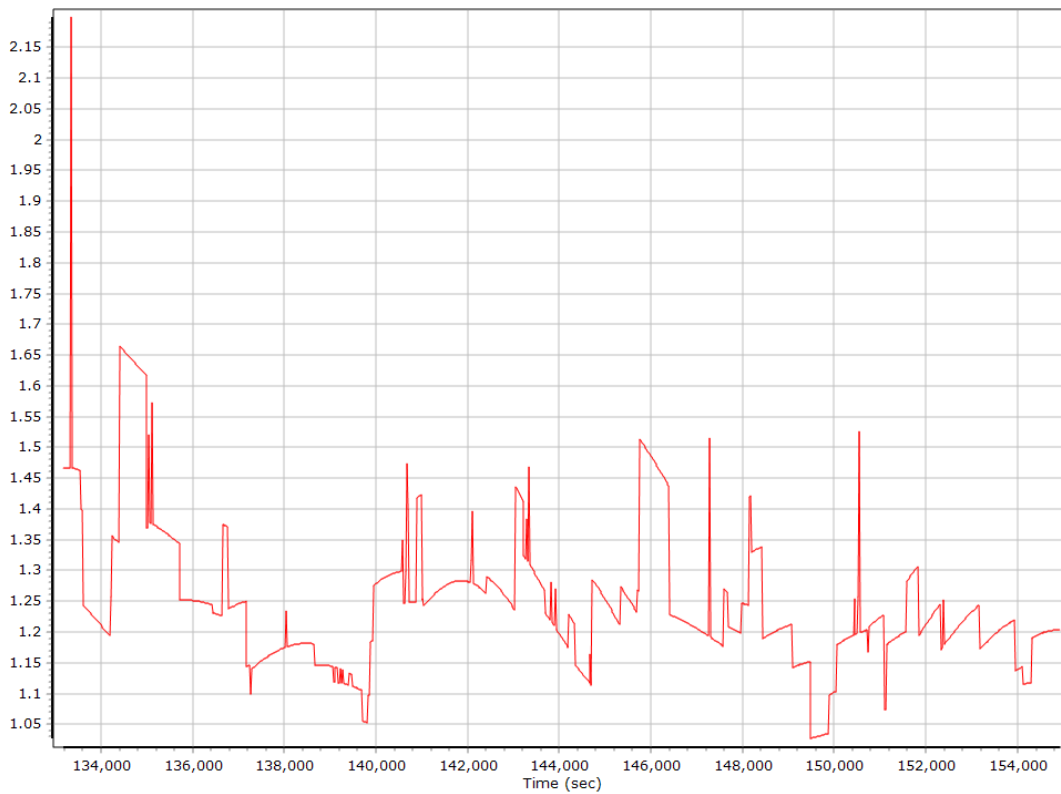
### Num SVs in solution



## Forward/Reverse Separation



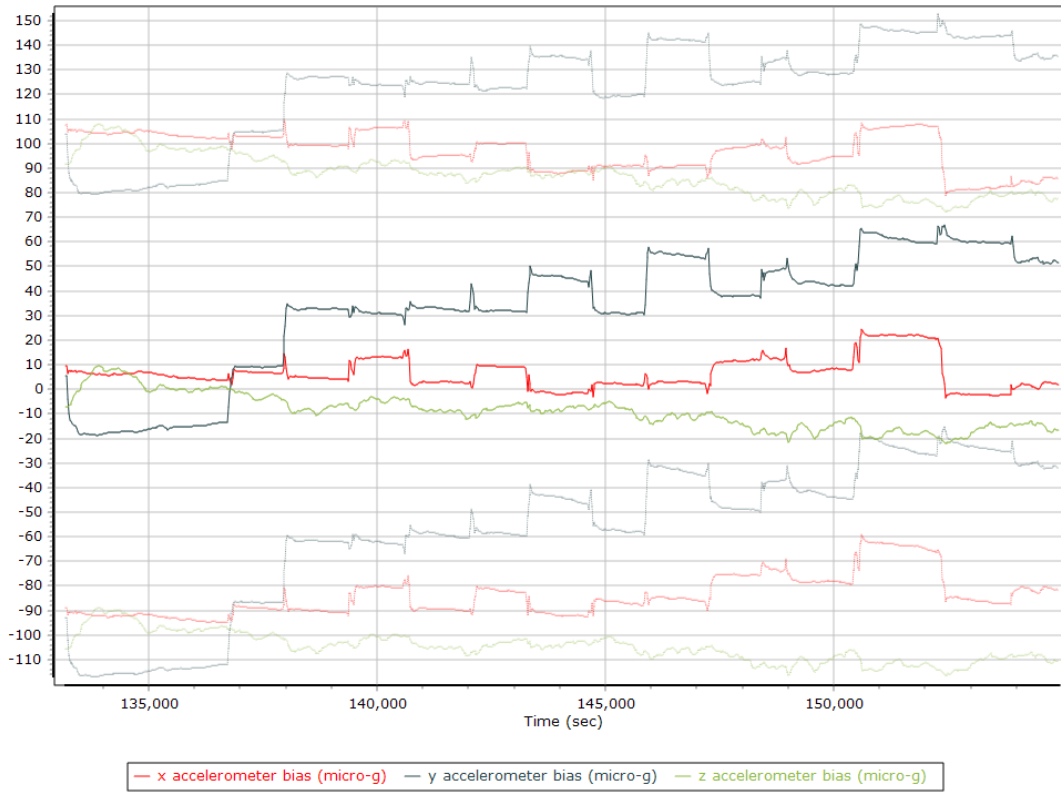
## PDOP



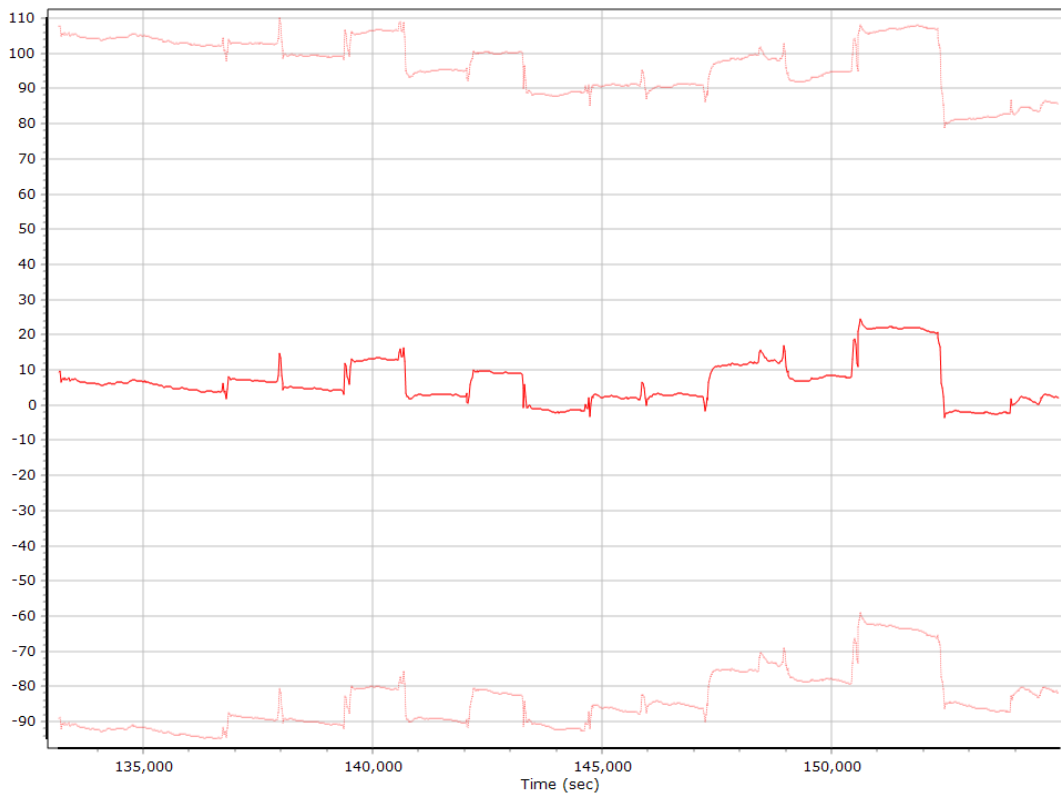
## IN-Fusion QC

### Forward Processed Estimated Errors, Reference Frame

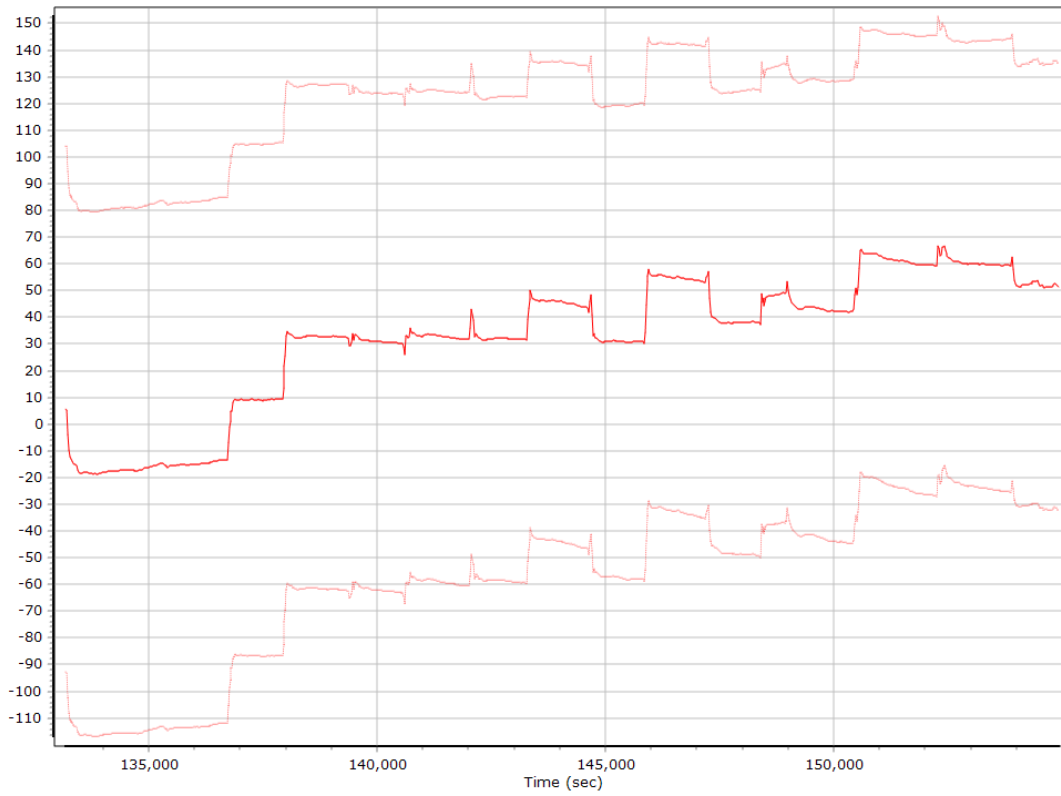
#### Accelerometer Bias (micro-g)



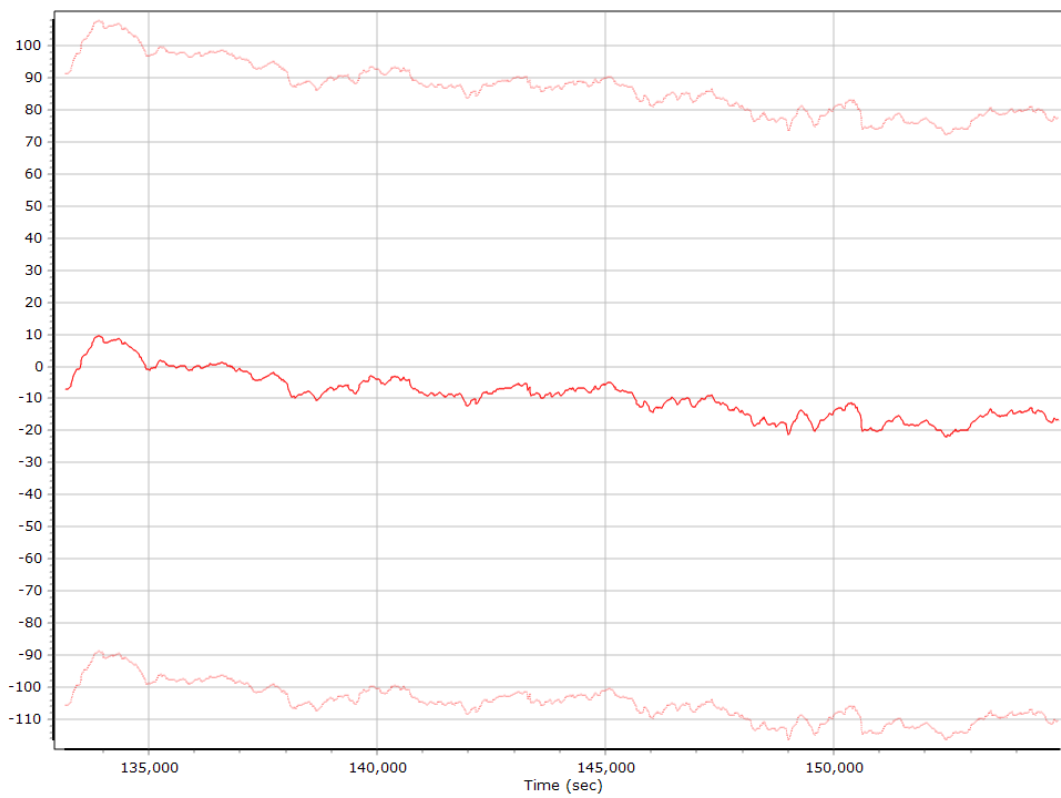
#### X Accelerometer Bias (micro-g)



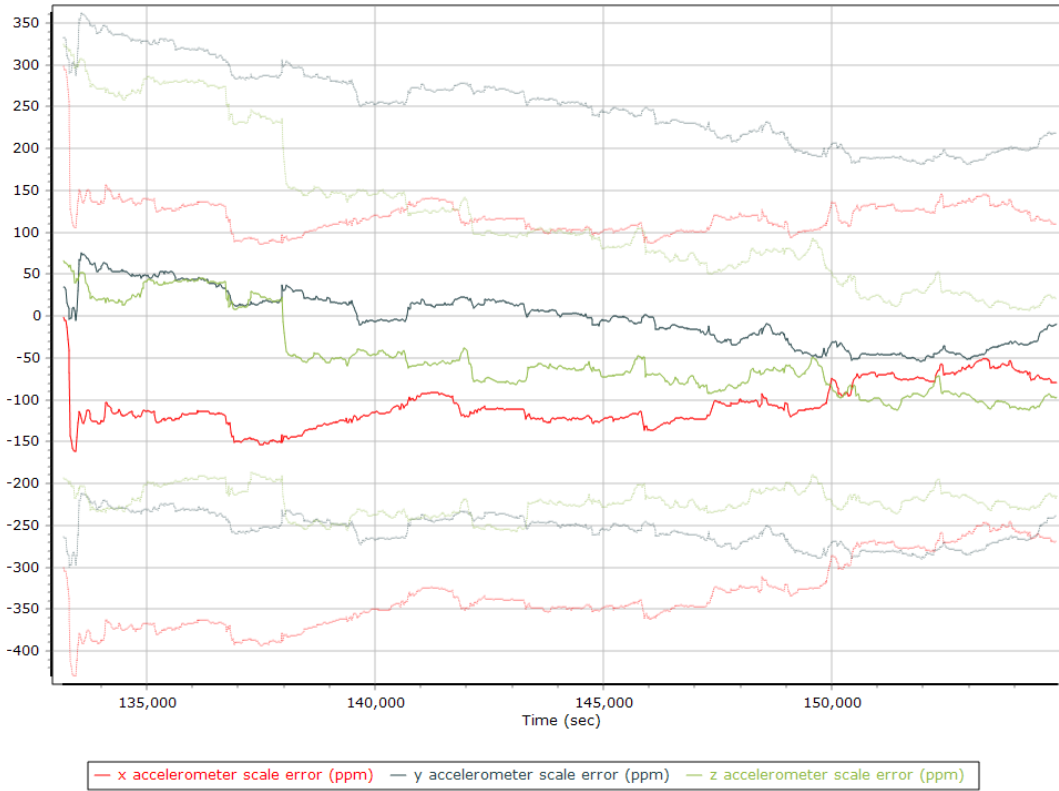
### Y Accelerometer Bias (micro-g)



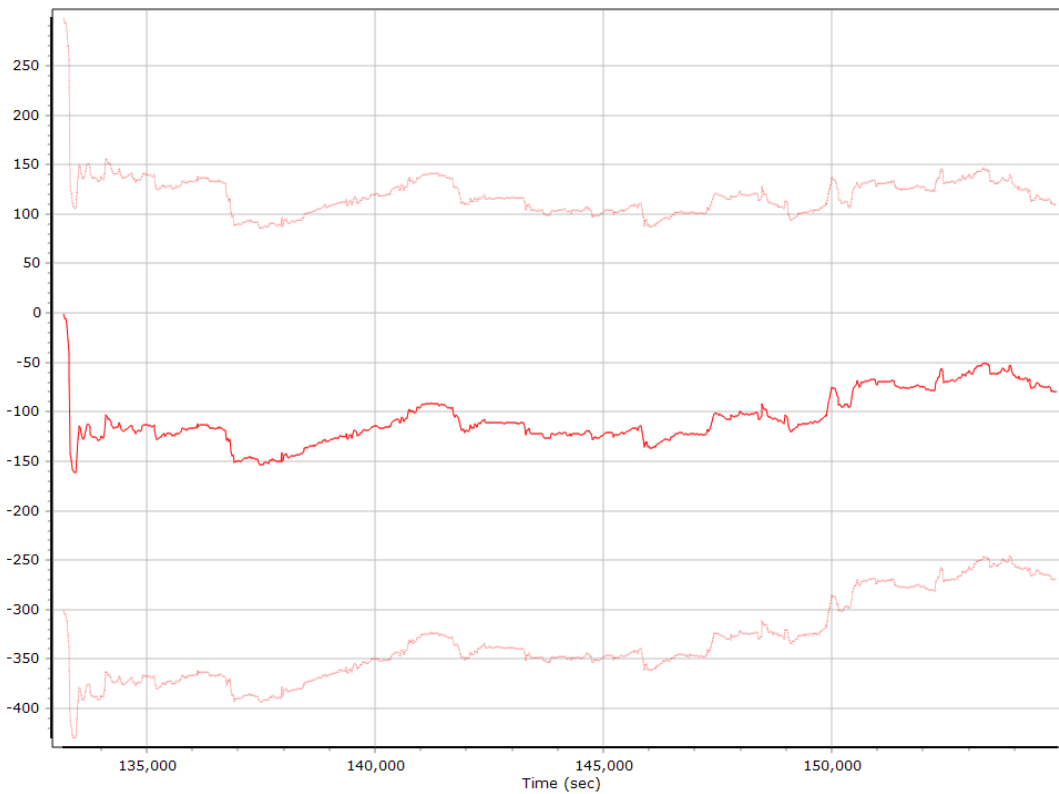
### Z Accelerometer Bias (micro-g)



### Accelerometer Scale Error (ppm)

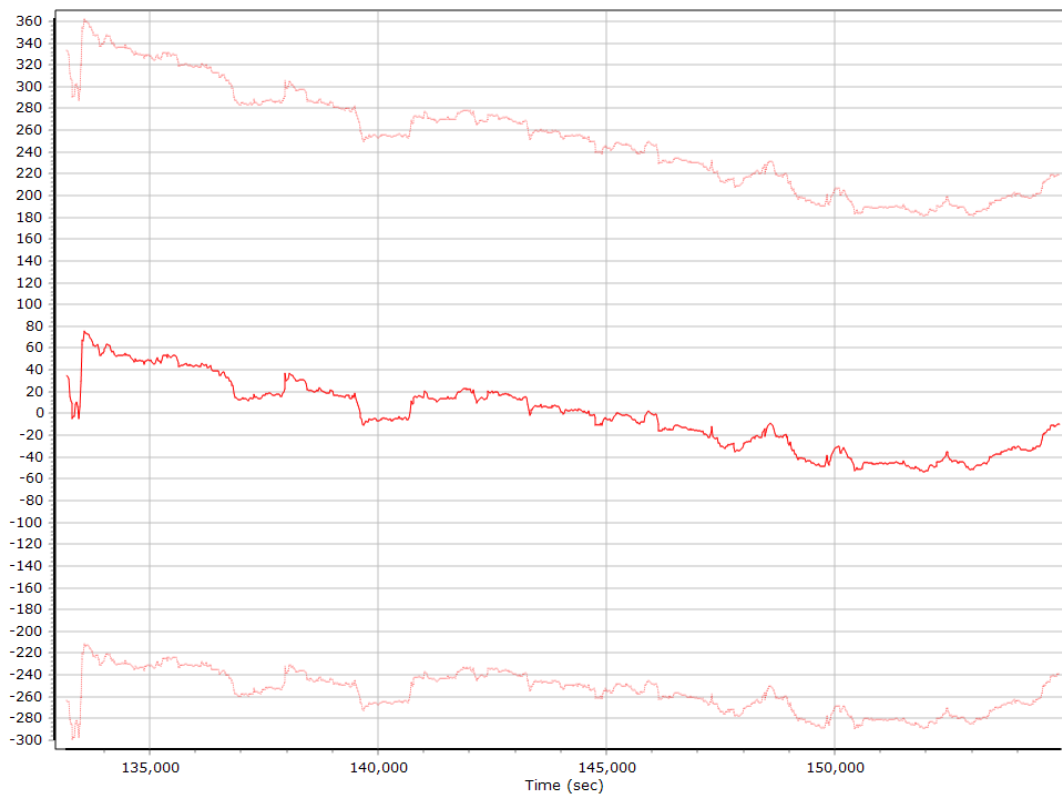


### X Accelerometer Scale Error (ppm)

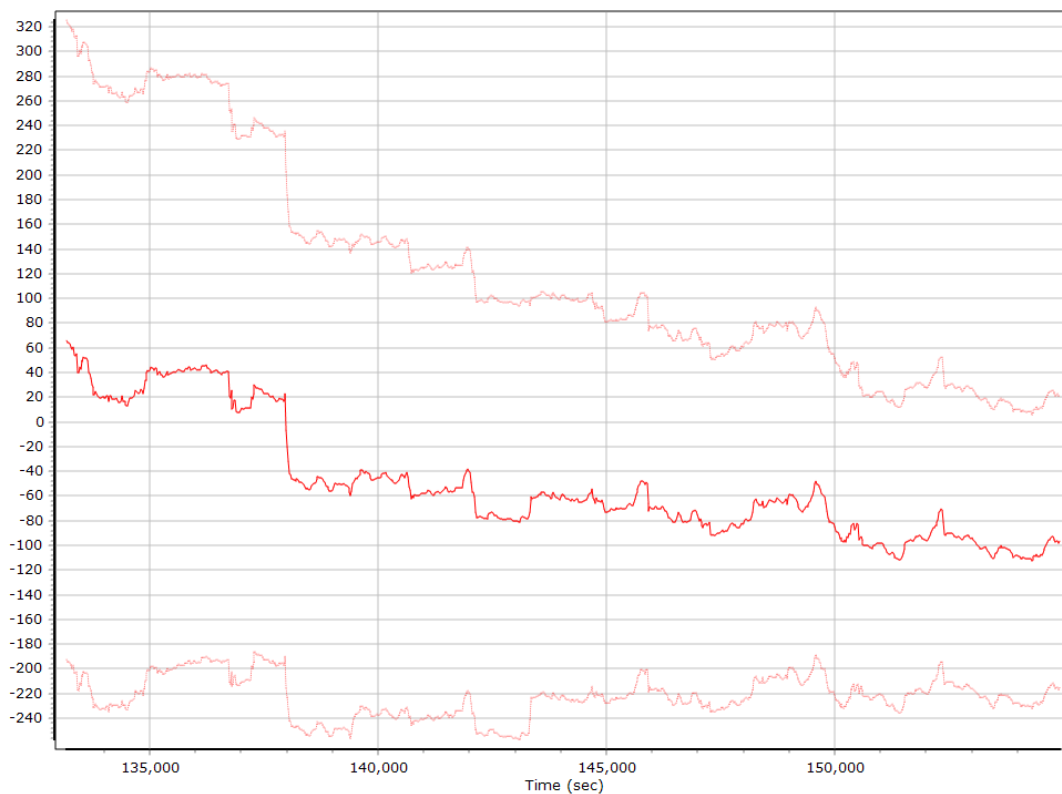




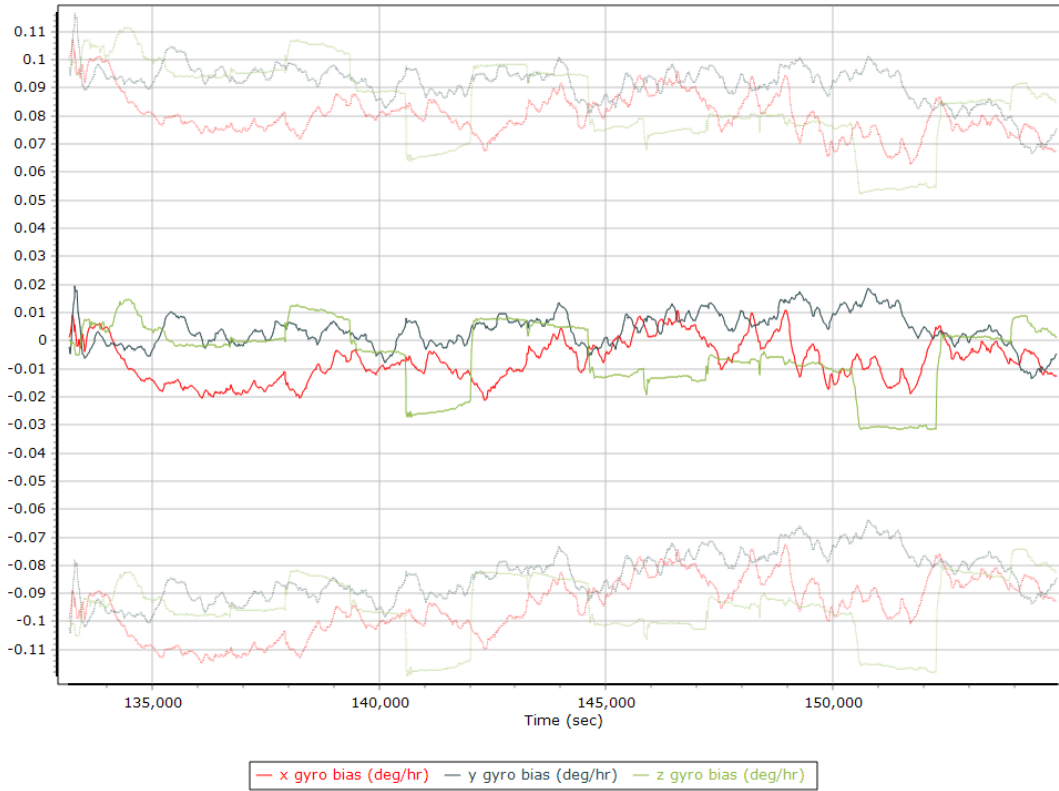
### Y Accelerometer Scale Error (ppm)



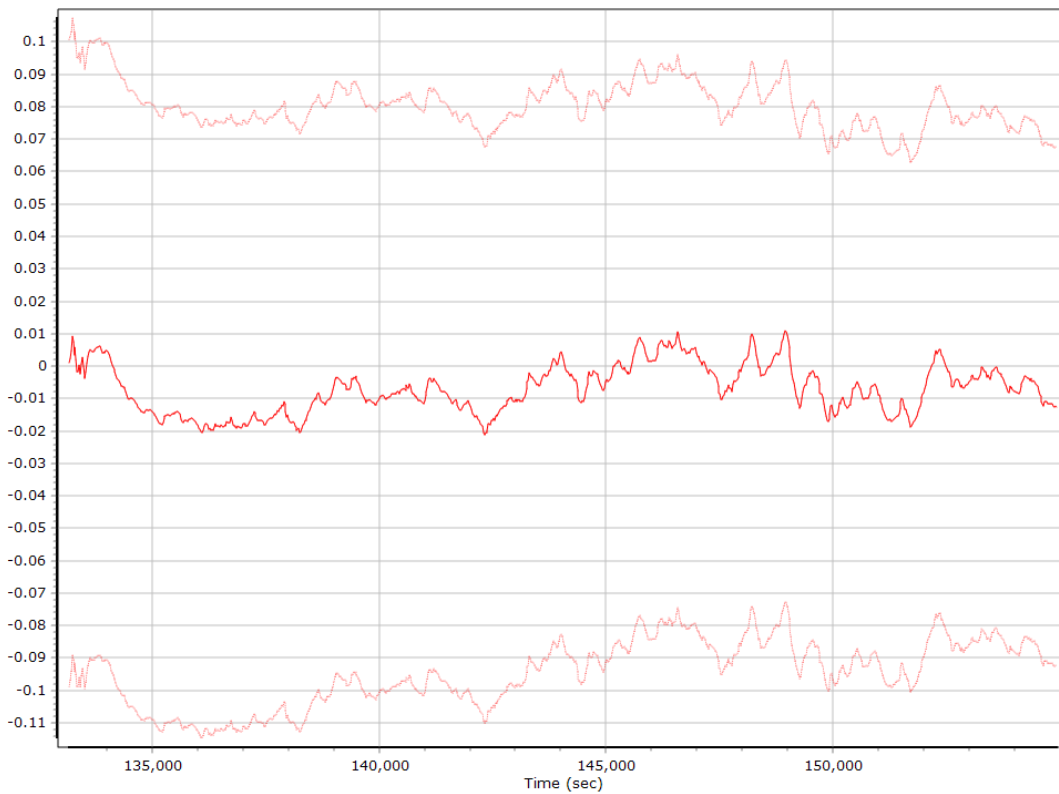
### Z Accelerometer Scale Error (ppm)



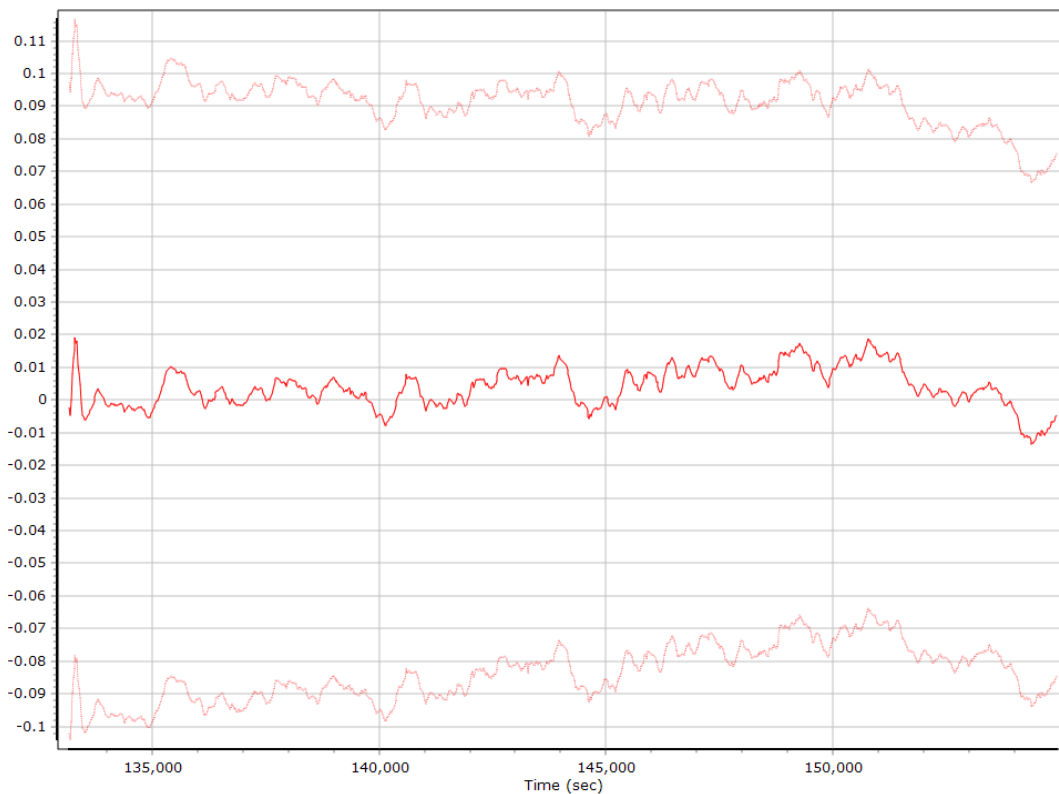
### Gyro Bias (deg/h)



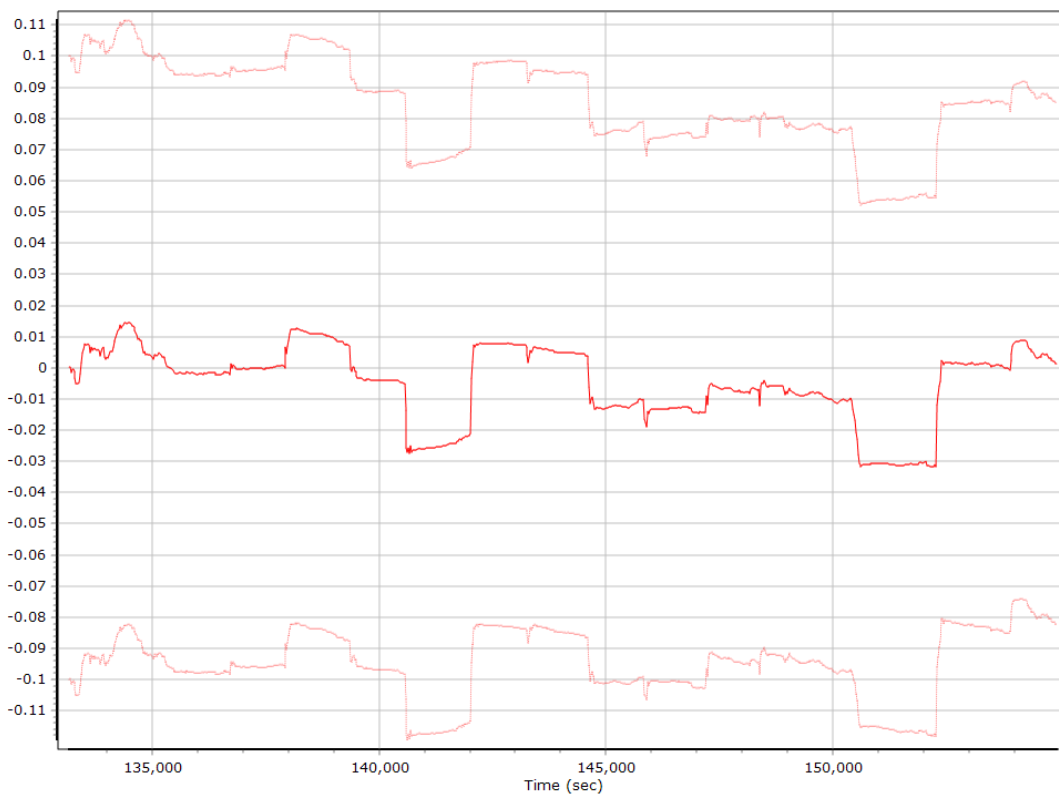
### X Gyro Bias (deg/h)



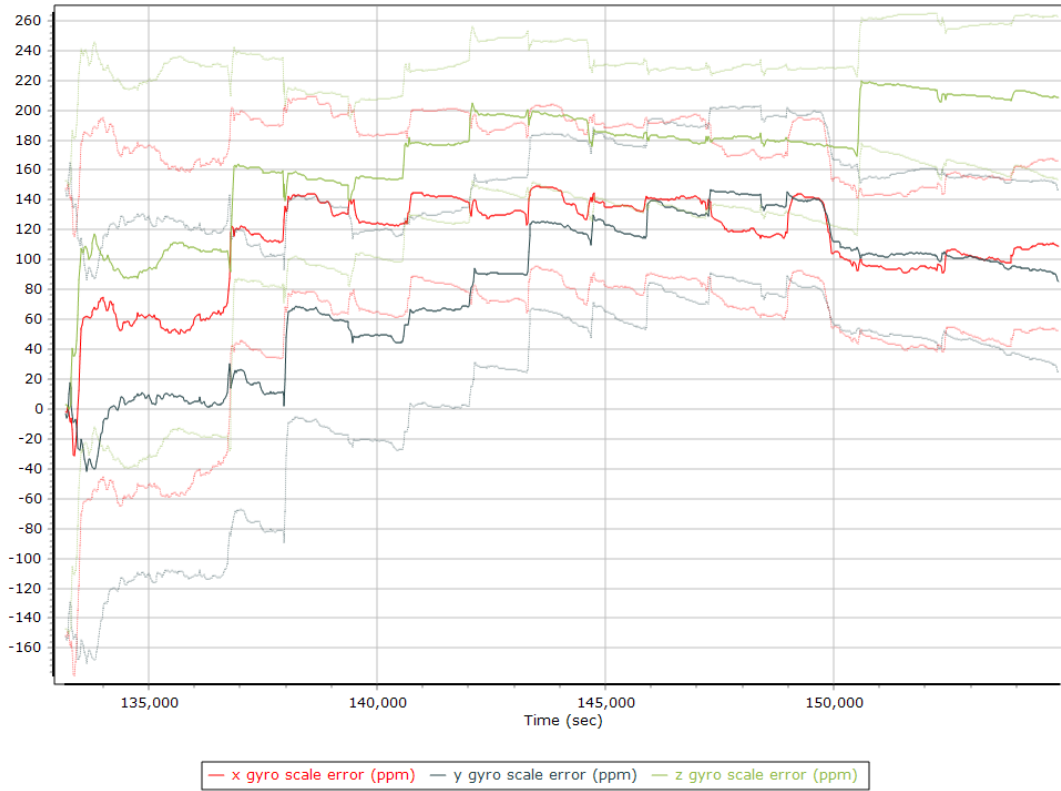
### Y Gyro Bias (deg/h)



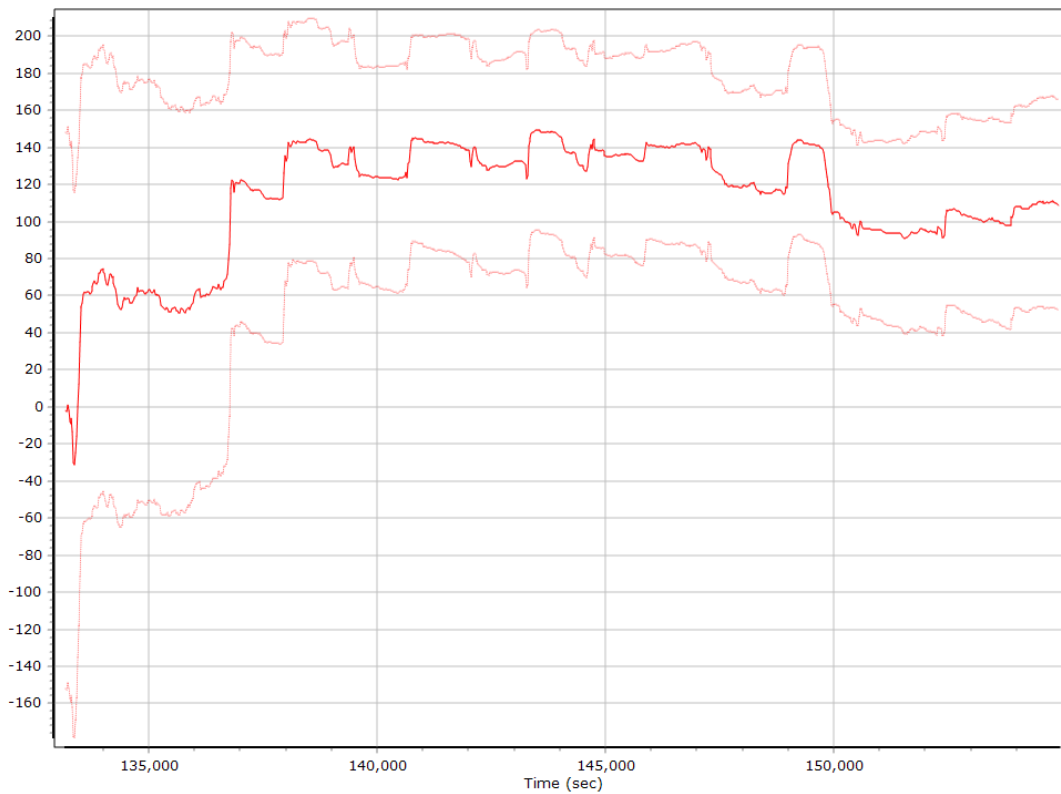
### Z Gyro Bias (deg/h)



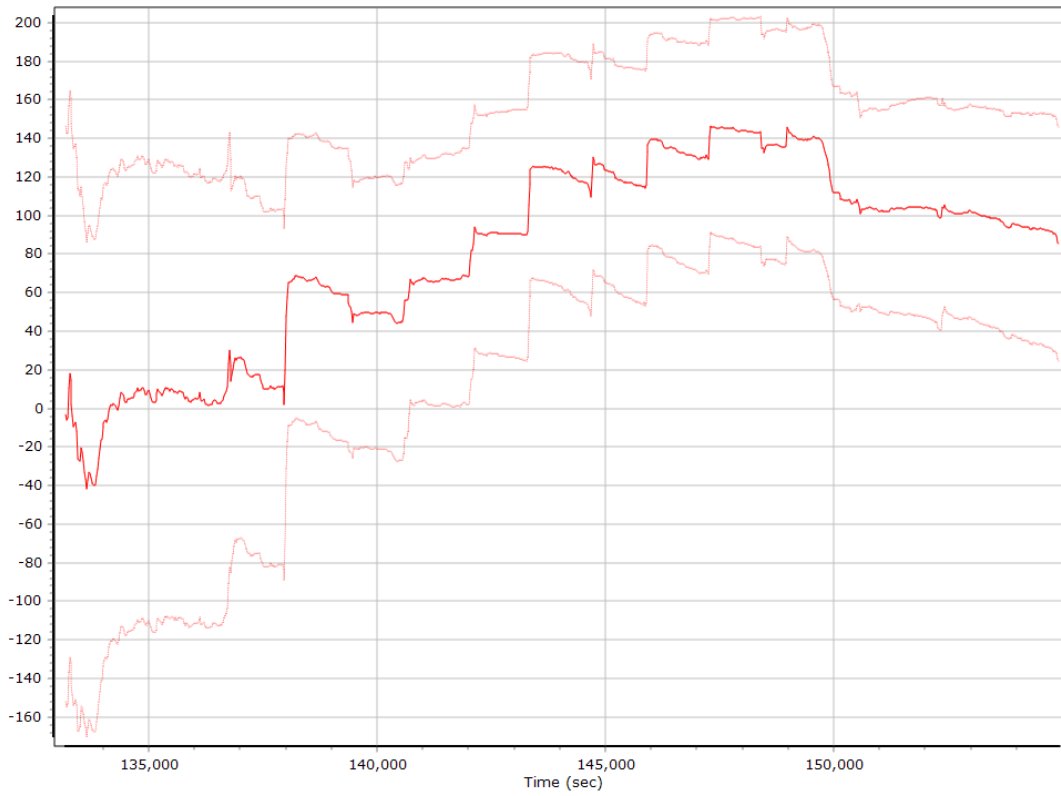
### Gyro Scale Error (ppm)



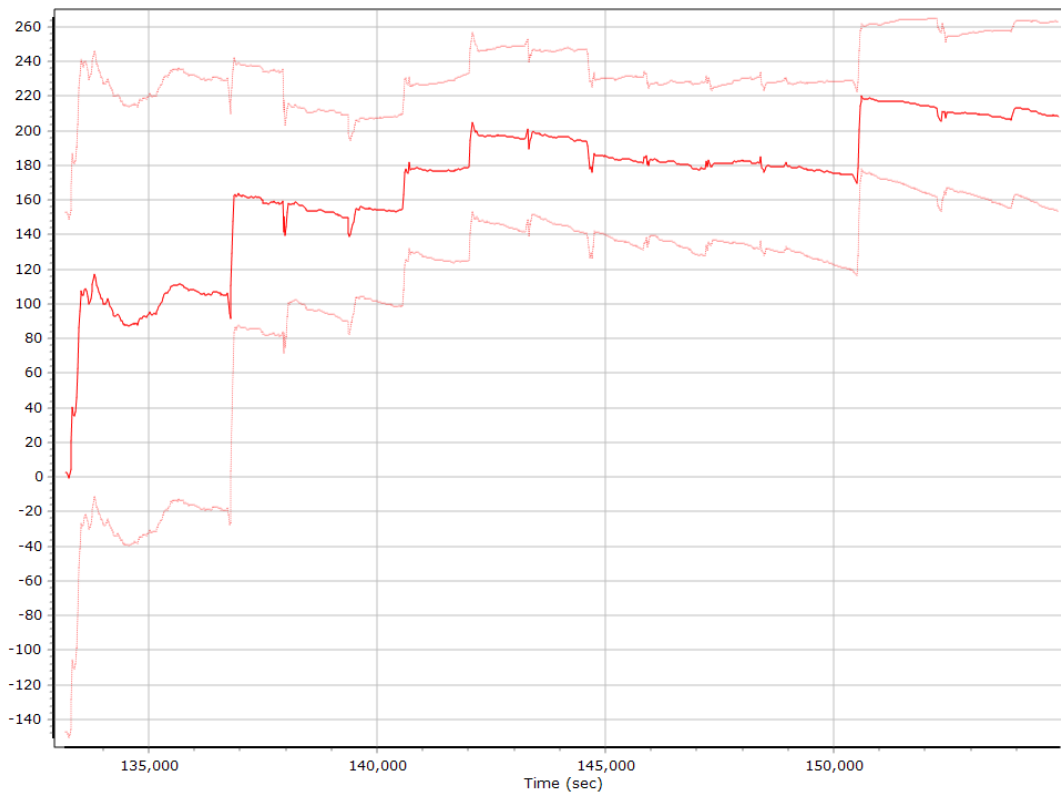
### X Gyro Scale Error (ppm)



### Y Gyro Scale Error (ppm)

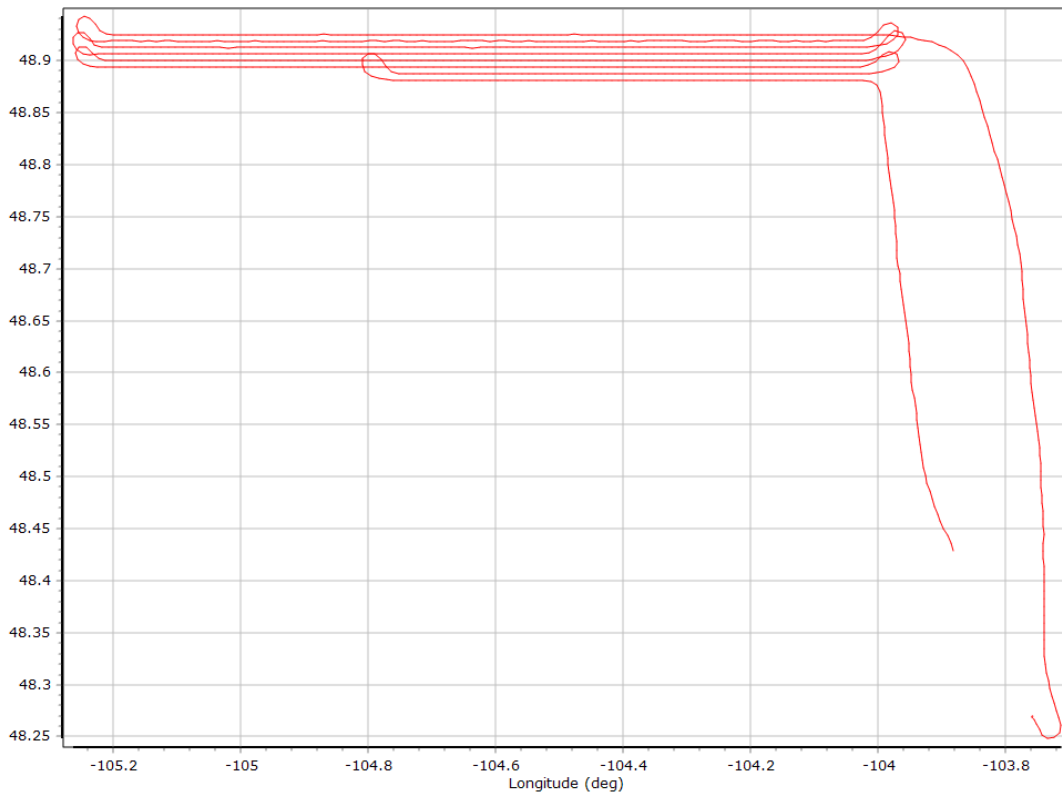


### Z Gyro Scale Error (ppm)

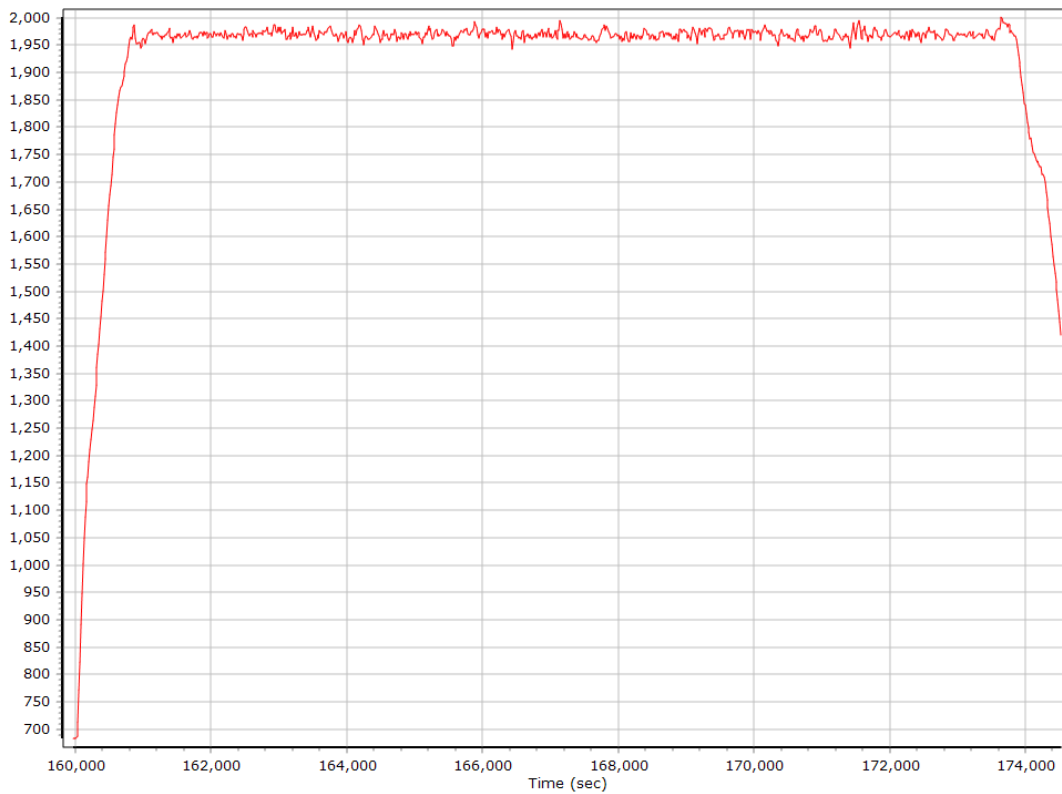


## Smoothed Trajectory Information

### Top View



### Altitude

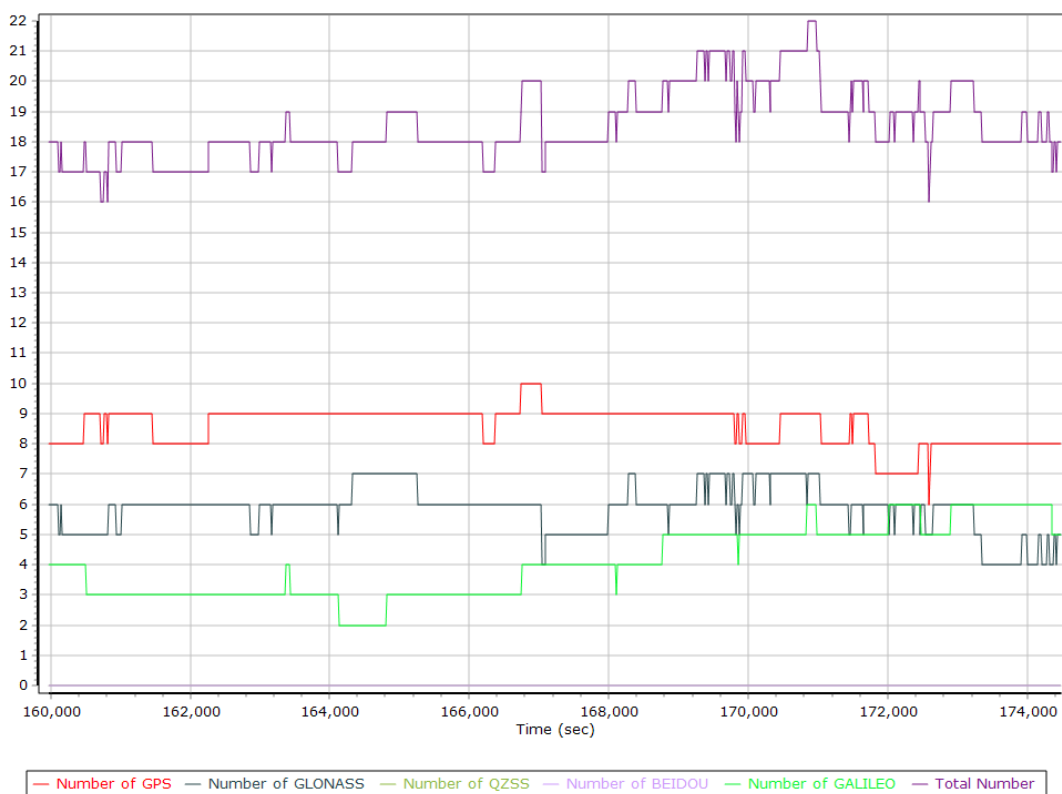


## GNSS QC

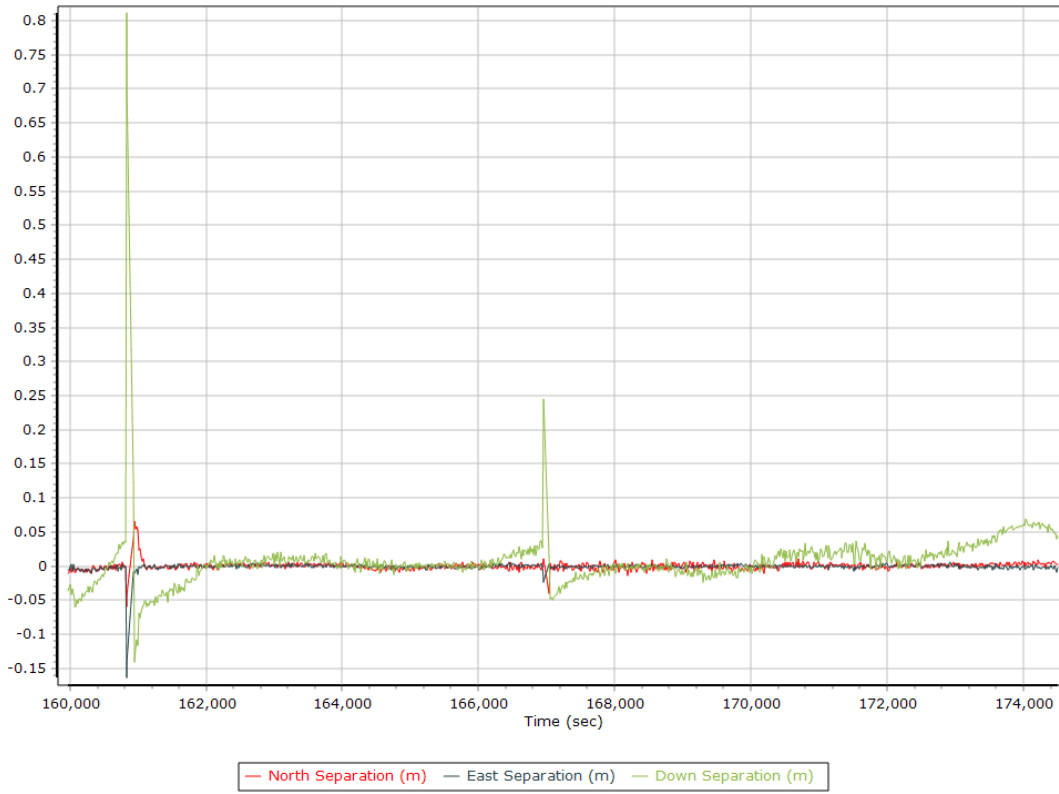
### GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	6	10	9
Number of GLONASS SV	0	7	6
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	0	0
Number of GALILEO SV	2	6	4
Total number of SV	12	22	19
PDOP	0.96	1.56	1.22
QC Solution Gaps	5.00	5.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	14719.00	0.00	10.00
Percentage	99.93	0.00	0.07

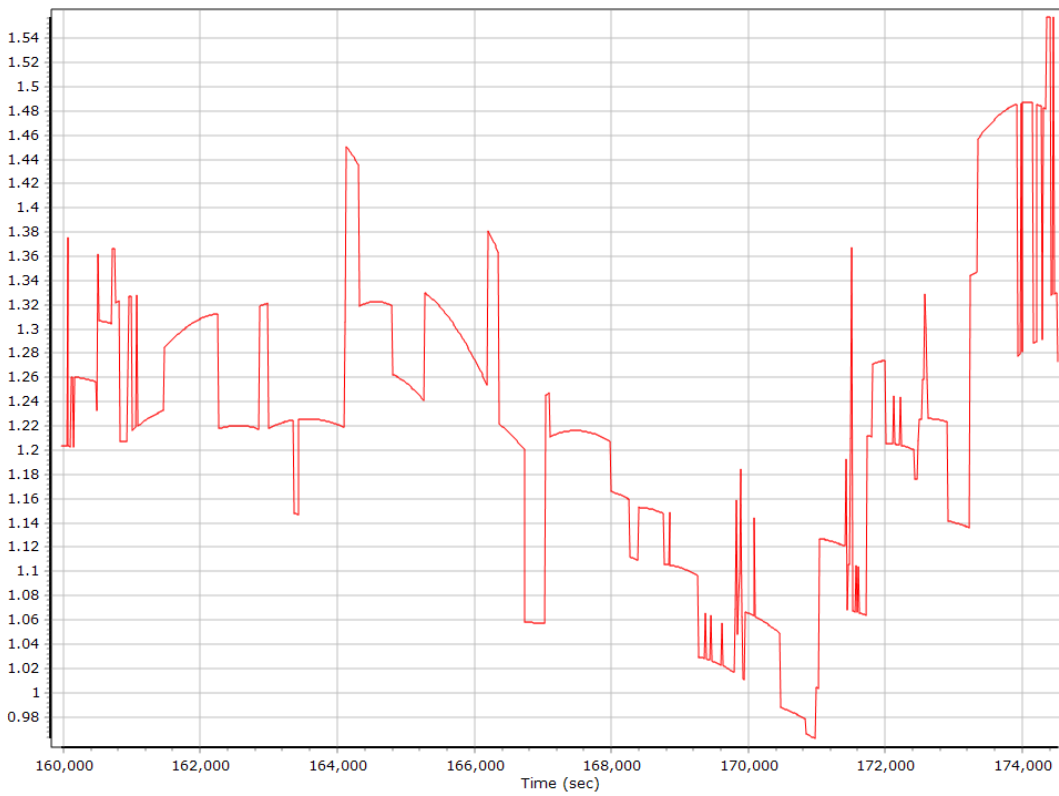
### Num SVs in solution



## Forward/Reverse Separation



## PDOP

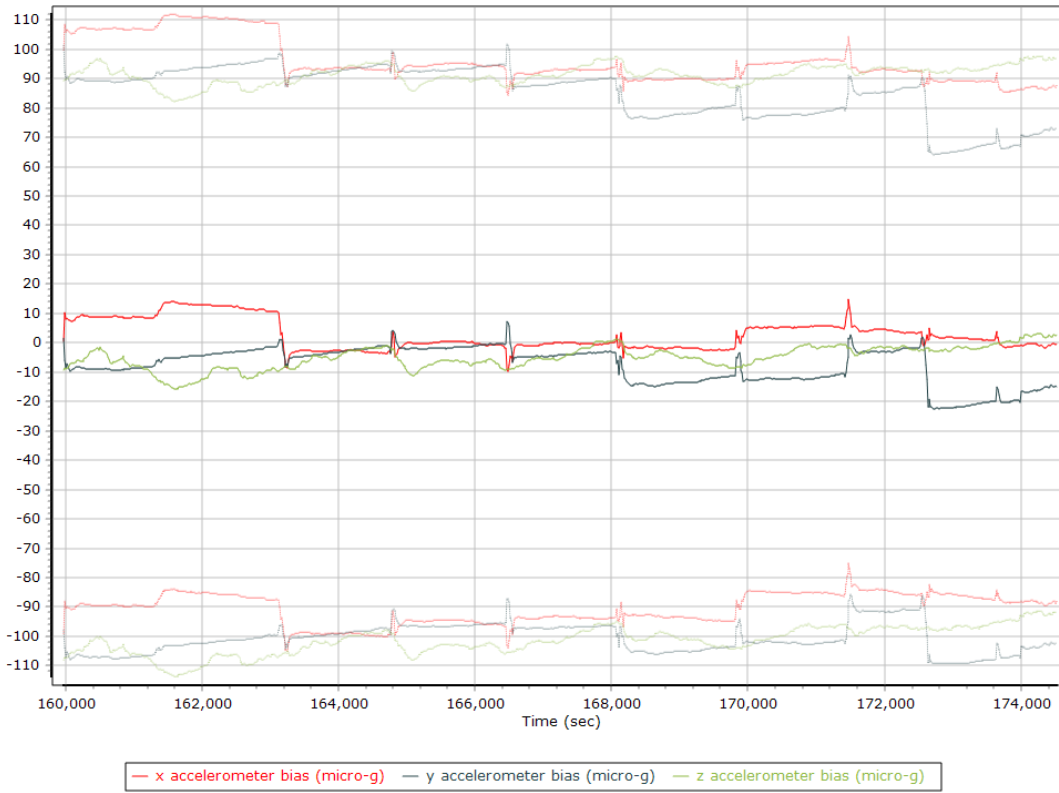




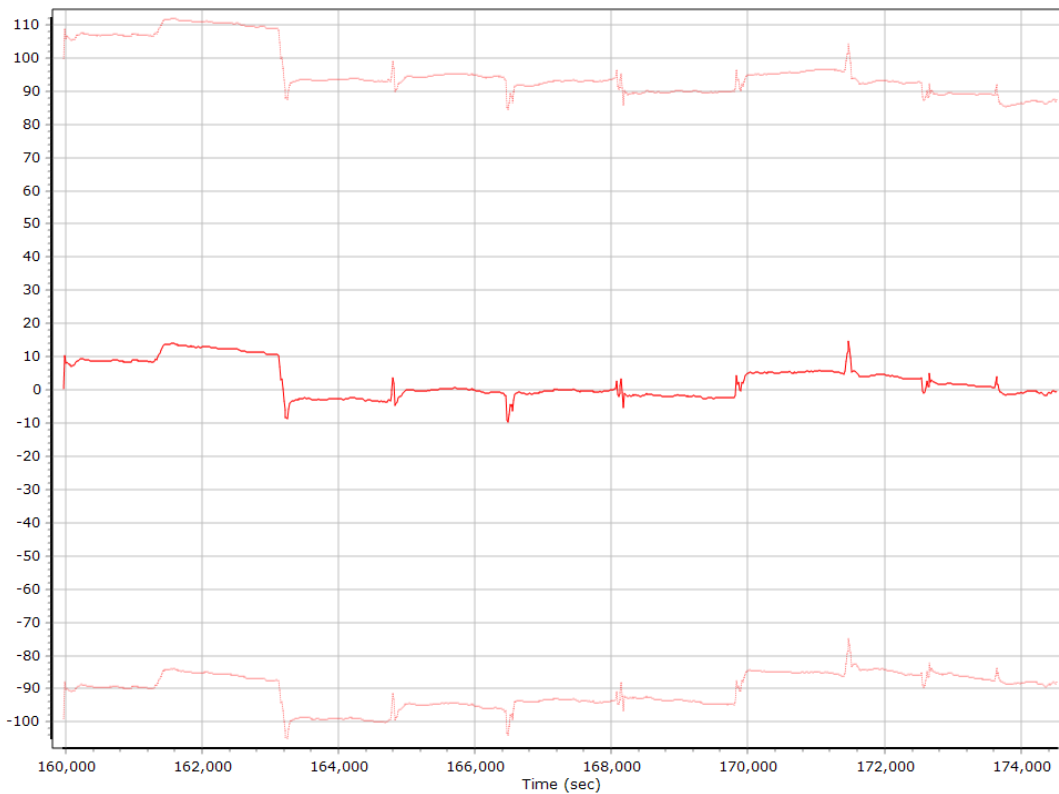
## IN-Fusion QC

### Forward Processed Estimated Errors, Reference Frame

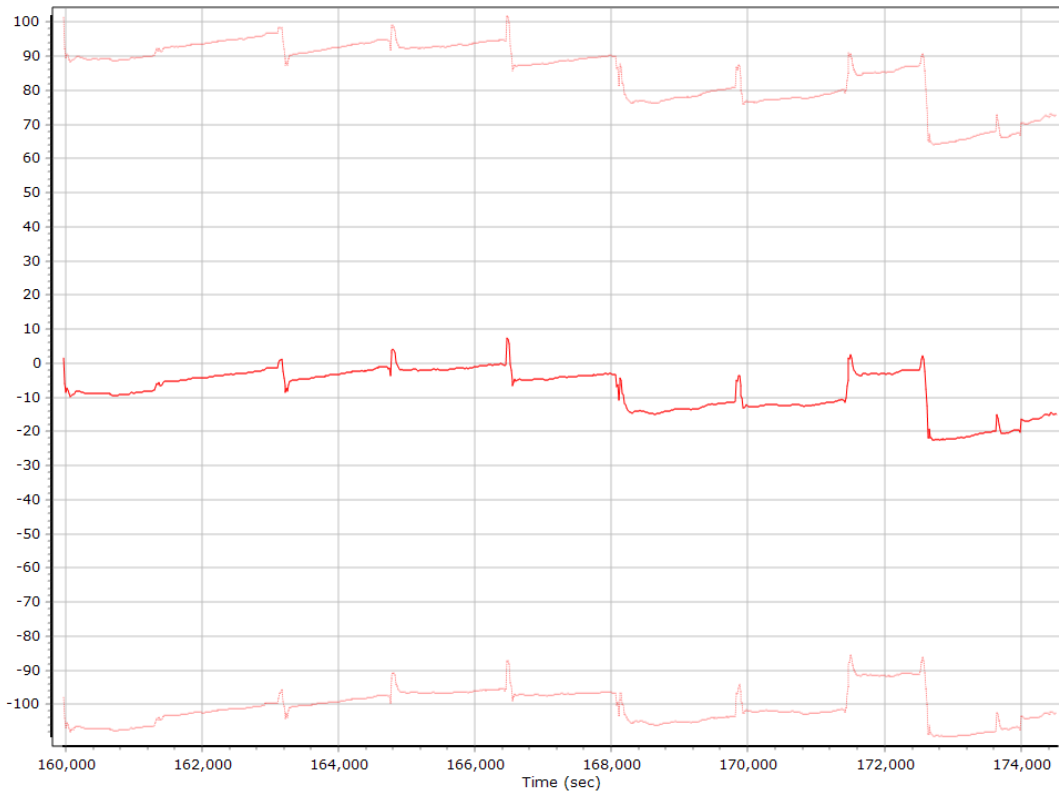
#### Accelerometer Bias (micro-g)



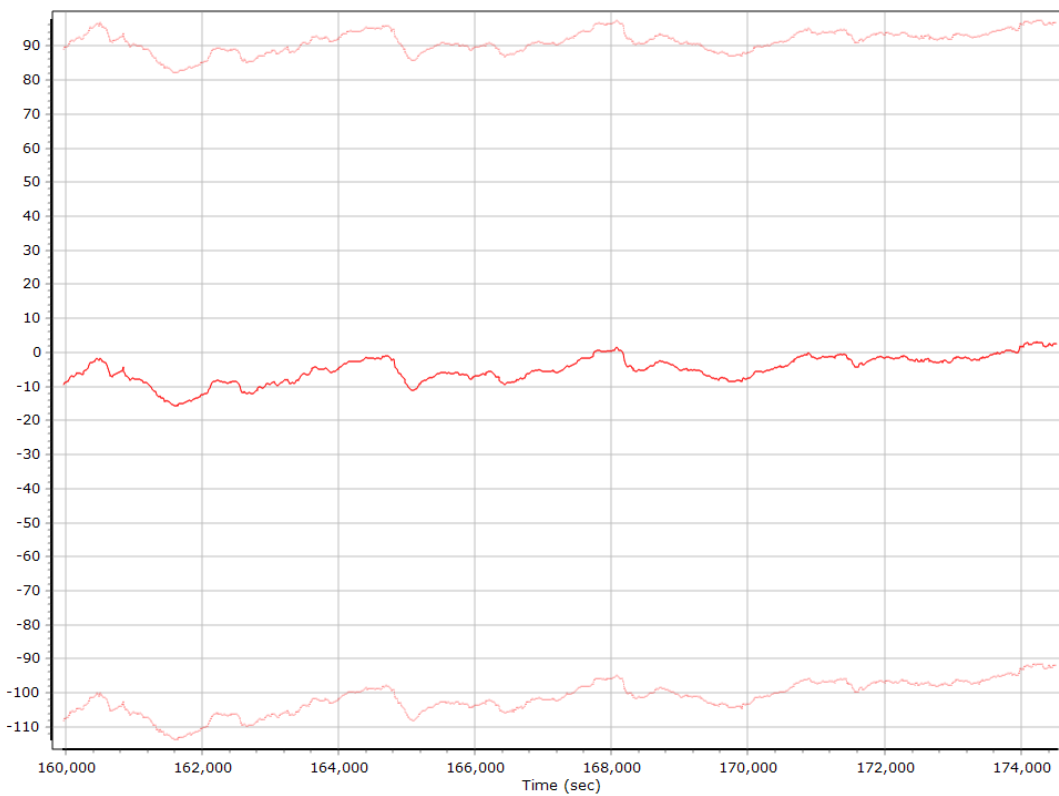
#### X Accelerometer Bias (micro-g)



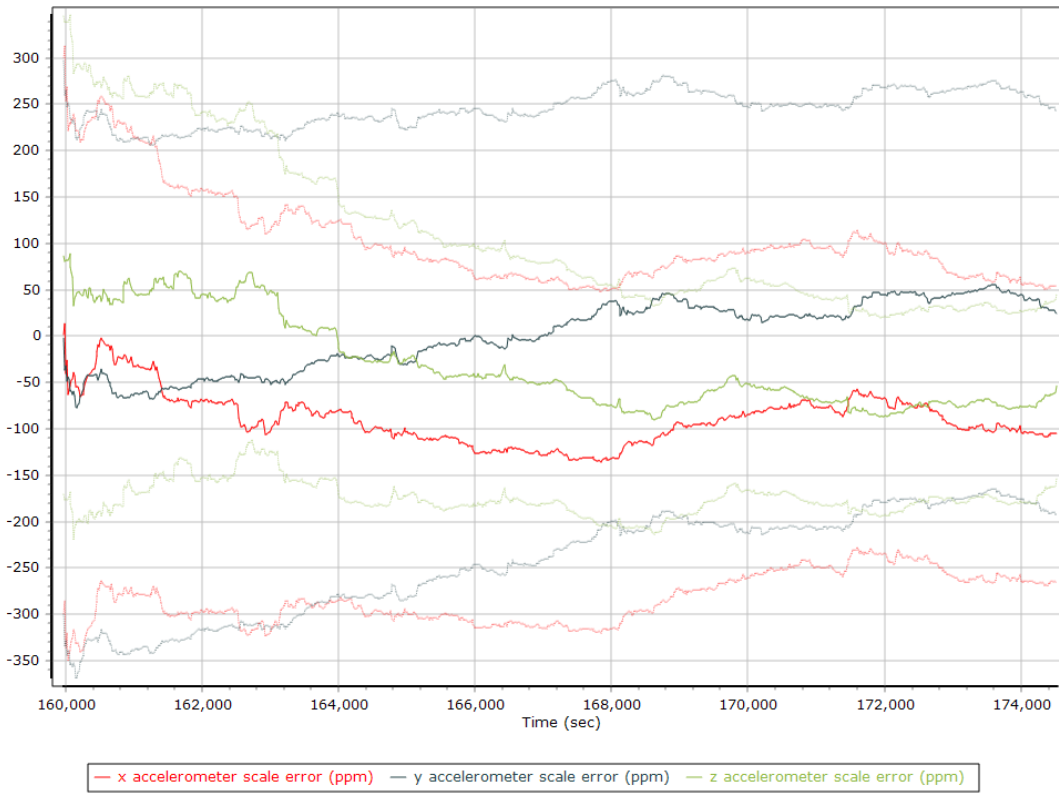
### Y Accelerometer Bias (micro-g)



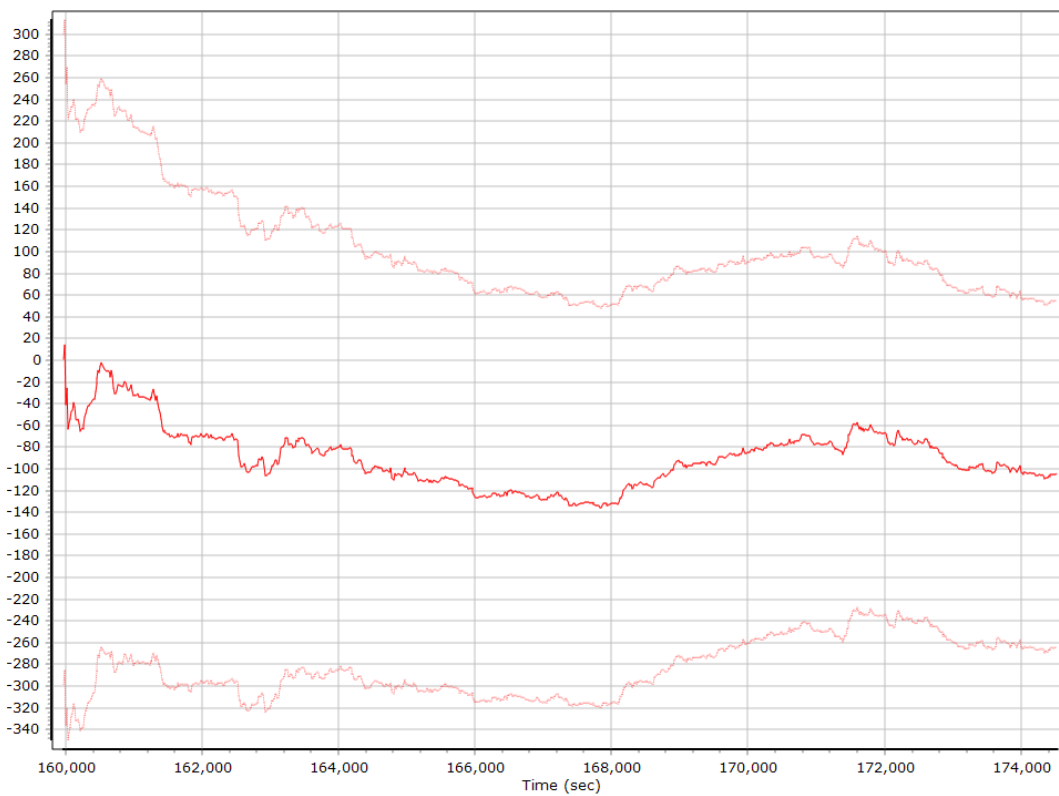
### Z Accelerometer Bias (micro-g)



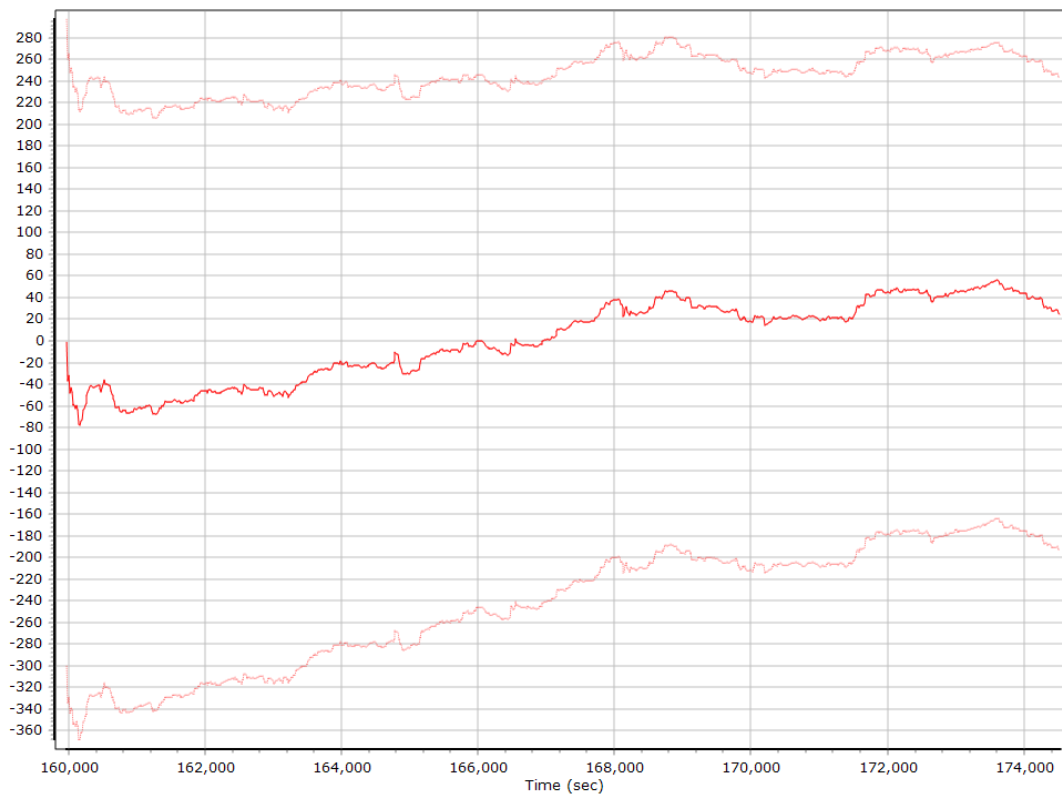
### Accelerometer Scale Error (ppm)



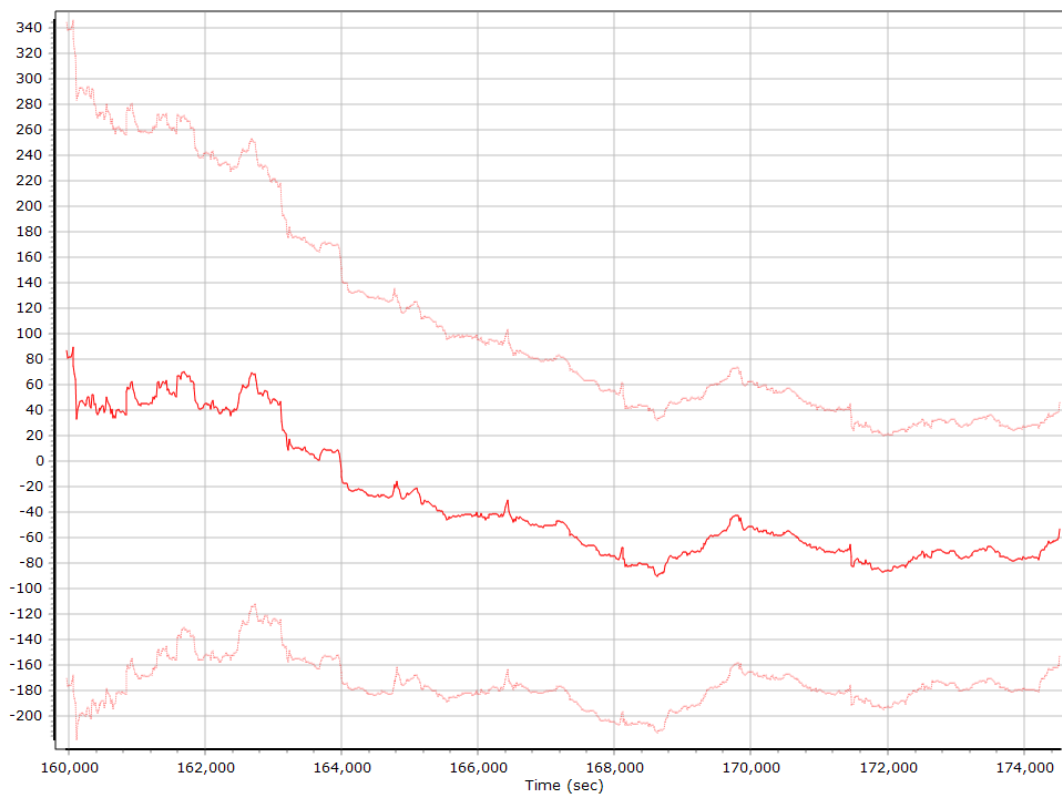
### X Accelerometer Scale Error (ppm)



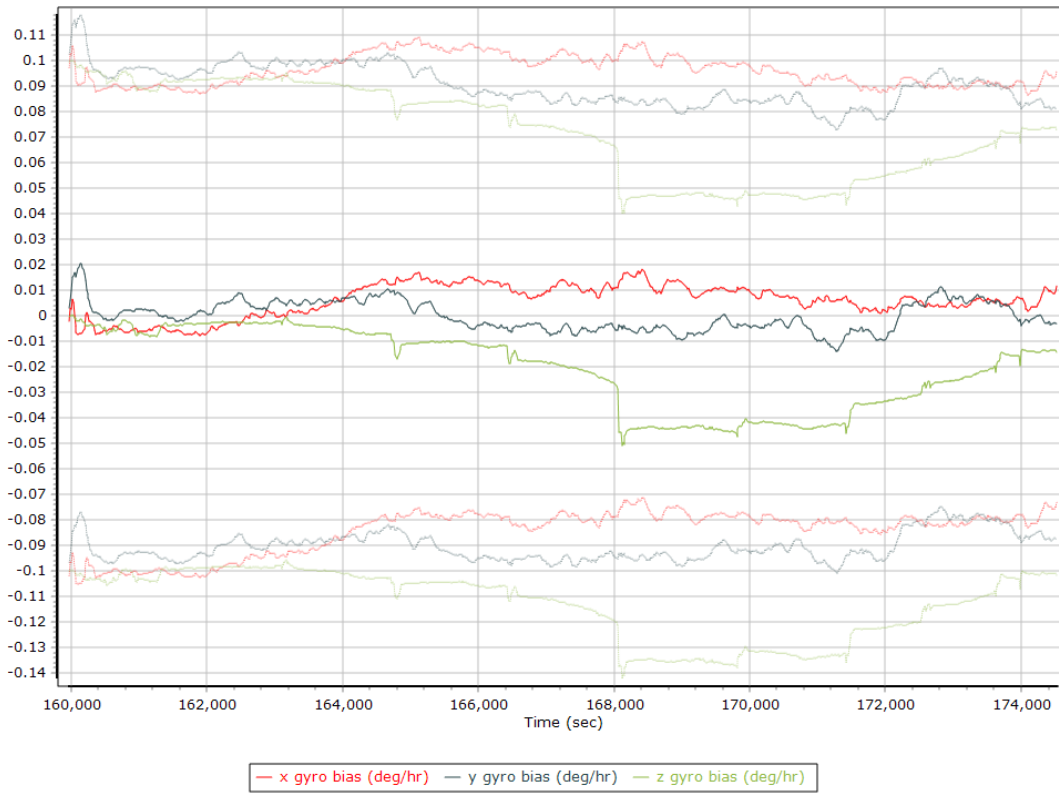
### Y Accelerometer Scale Error (ppm)



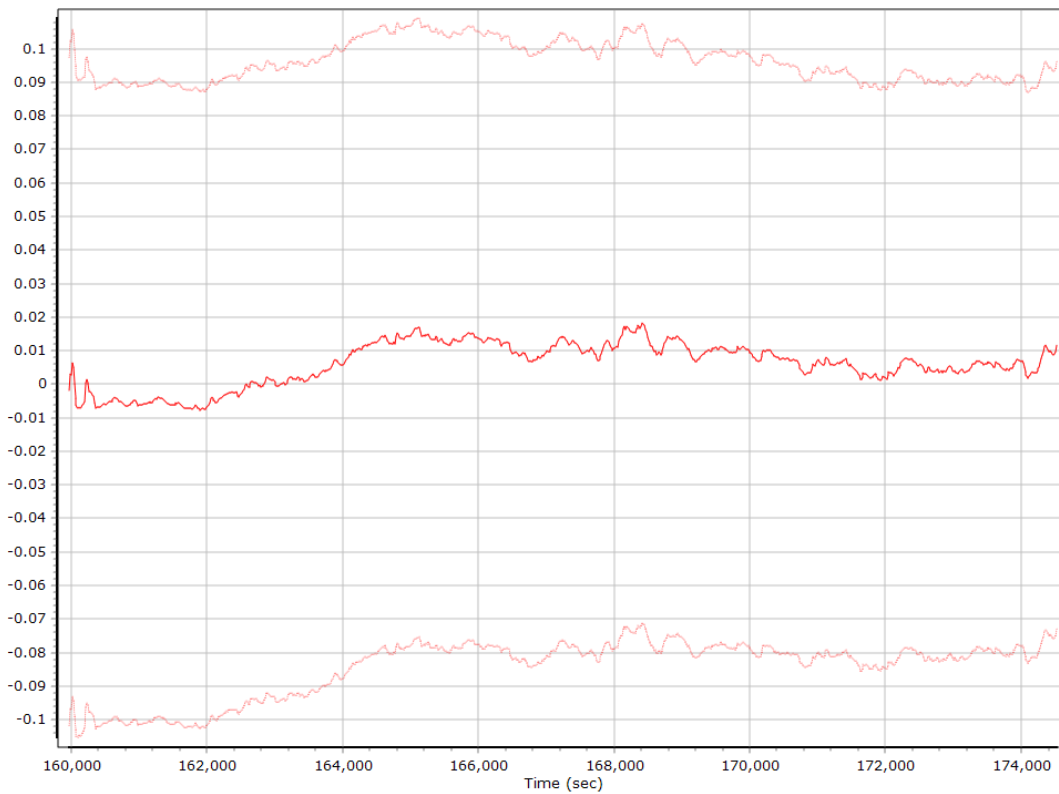
### Z Accelerometer Scale Error (ppm)



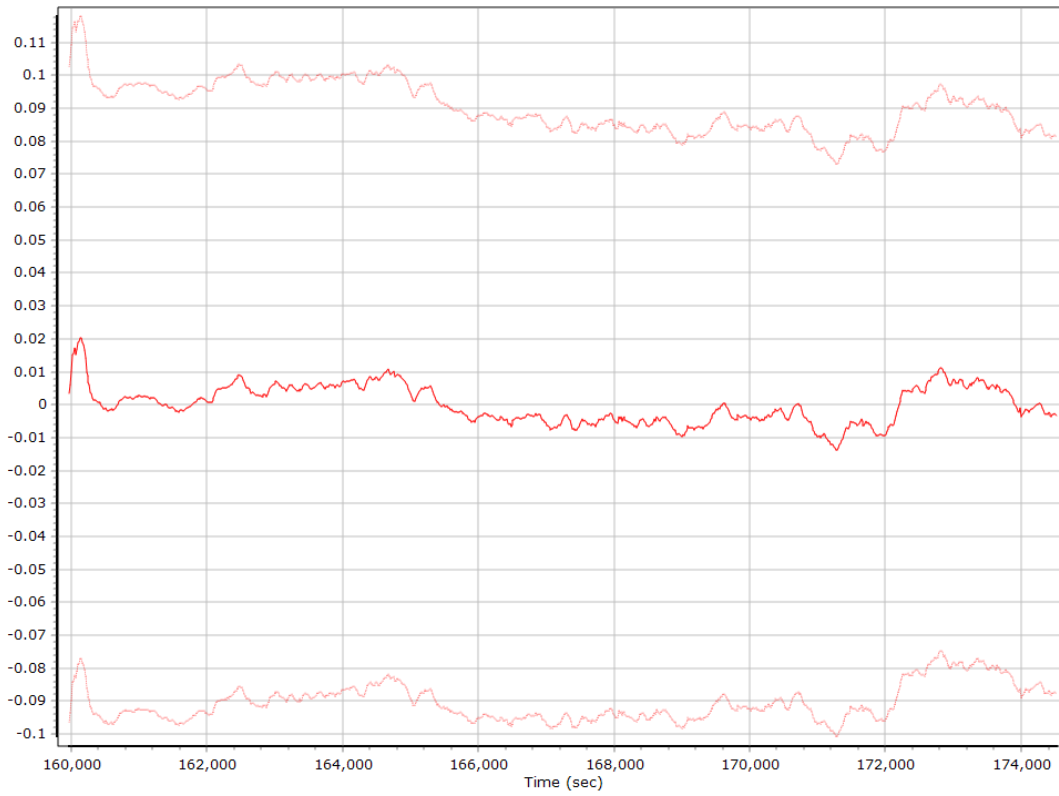
### Gyro Bias (deg/h)



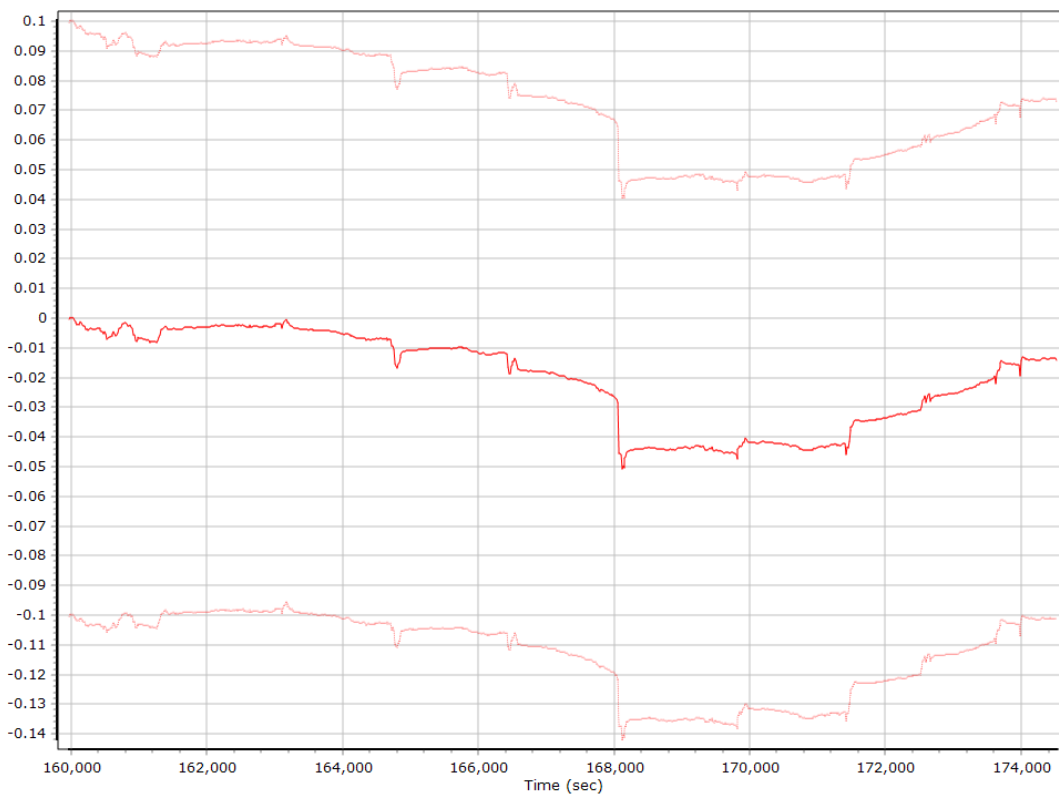
### X Gyro Bias (deg/h)



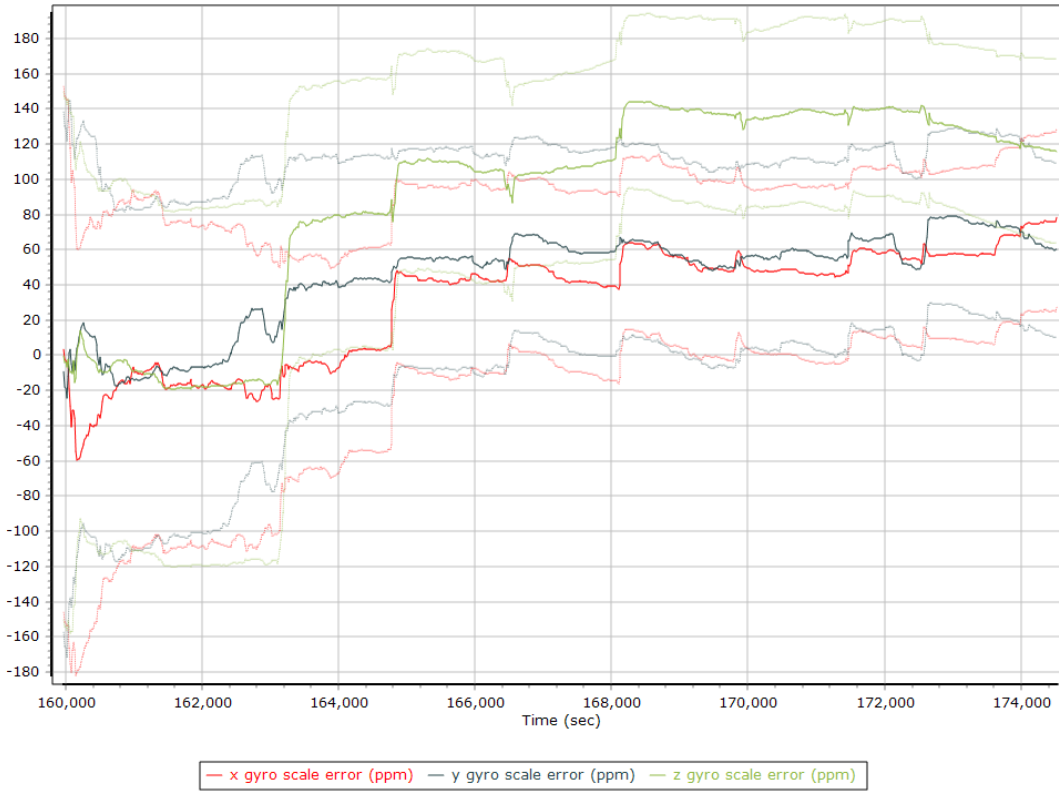
### Y Gyro Bias (deg/h)



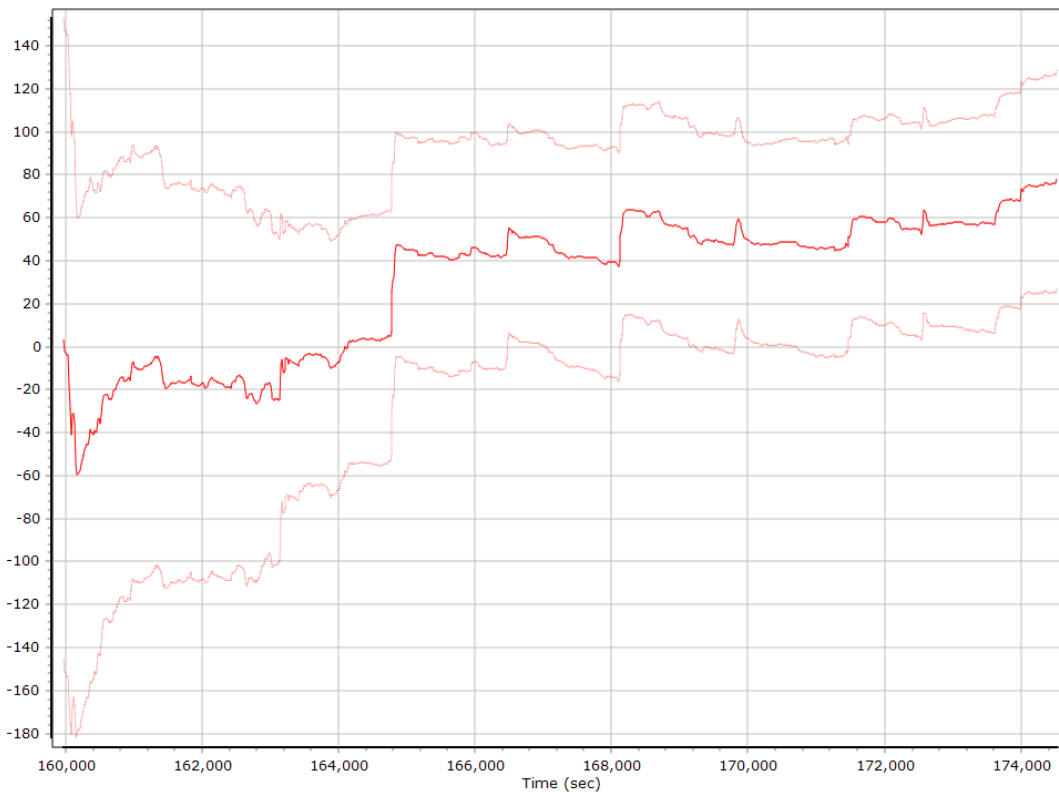
### Z Gyro Bias (deg/h)



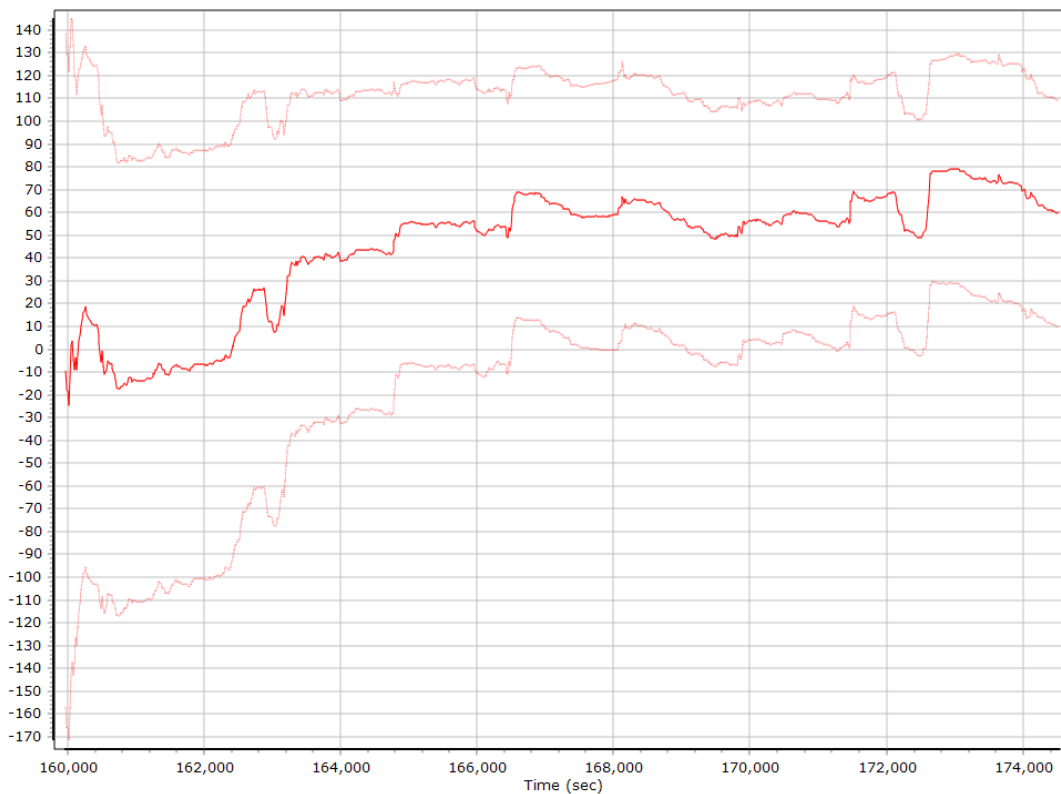
### Gyro Scale Error (ppm)



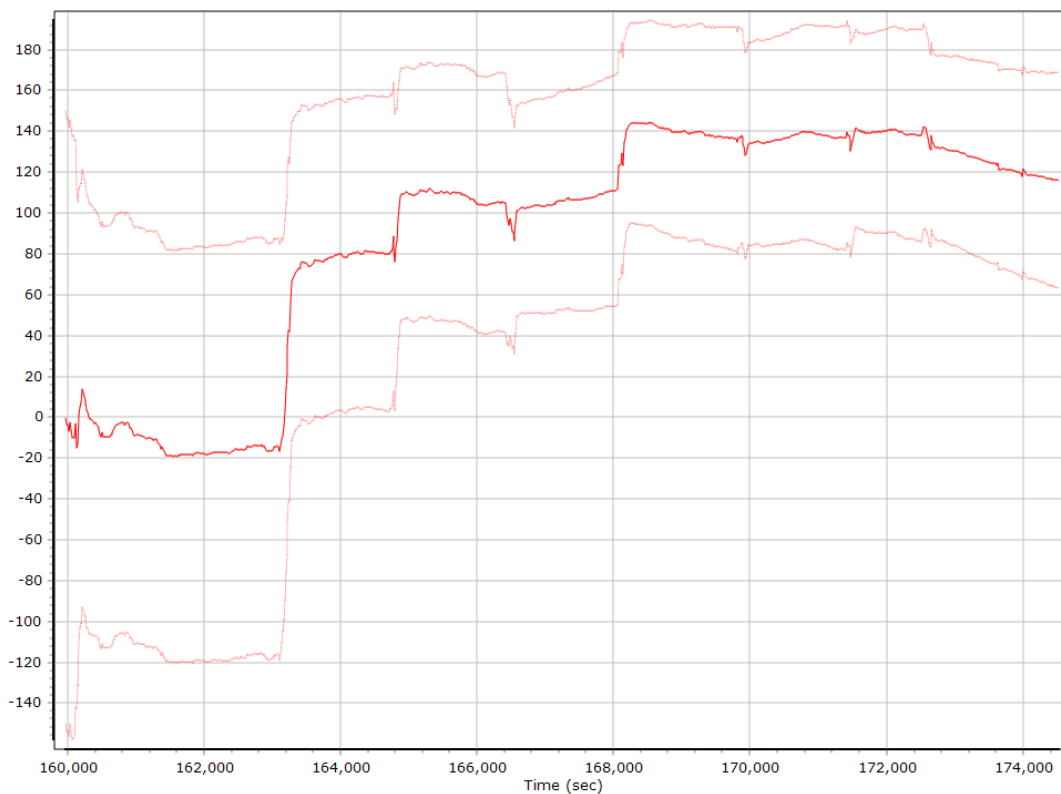
### X Gyro Scale Error (ppm)



### Y Gyro Scale Error (ppm)



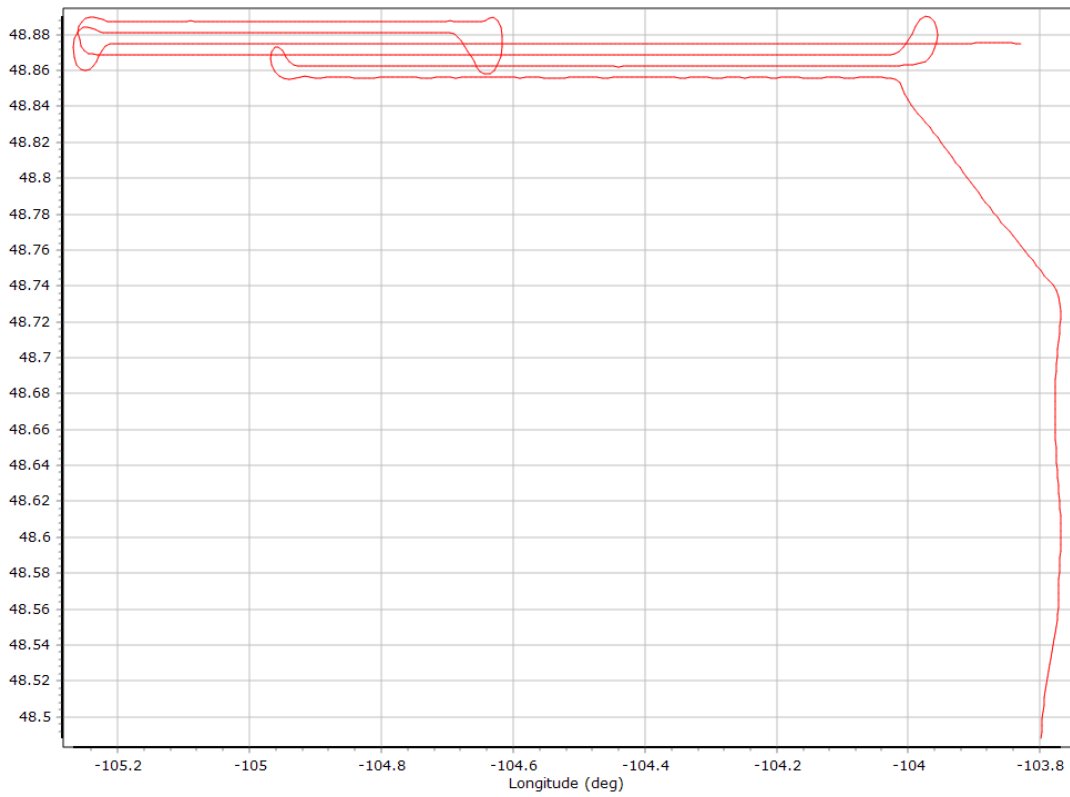
### Z Gyro Scale Error (ppm)



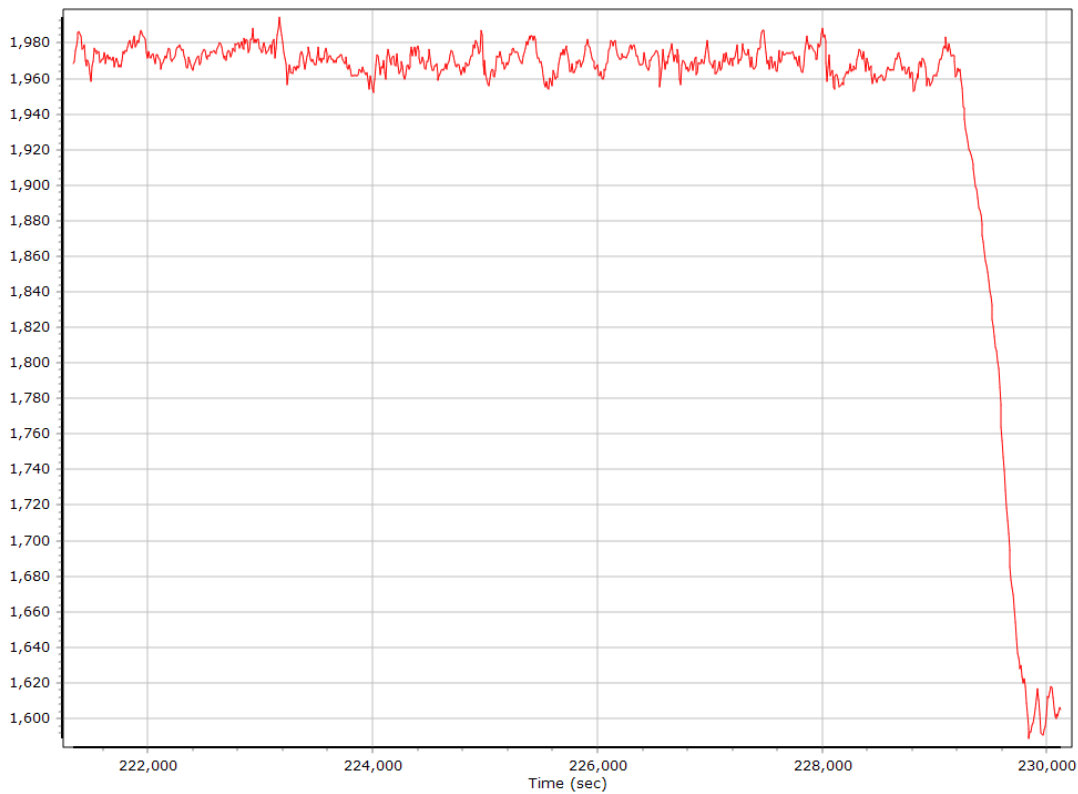


## Smoothed Trajectory Information

### Top View



### Altitude

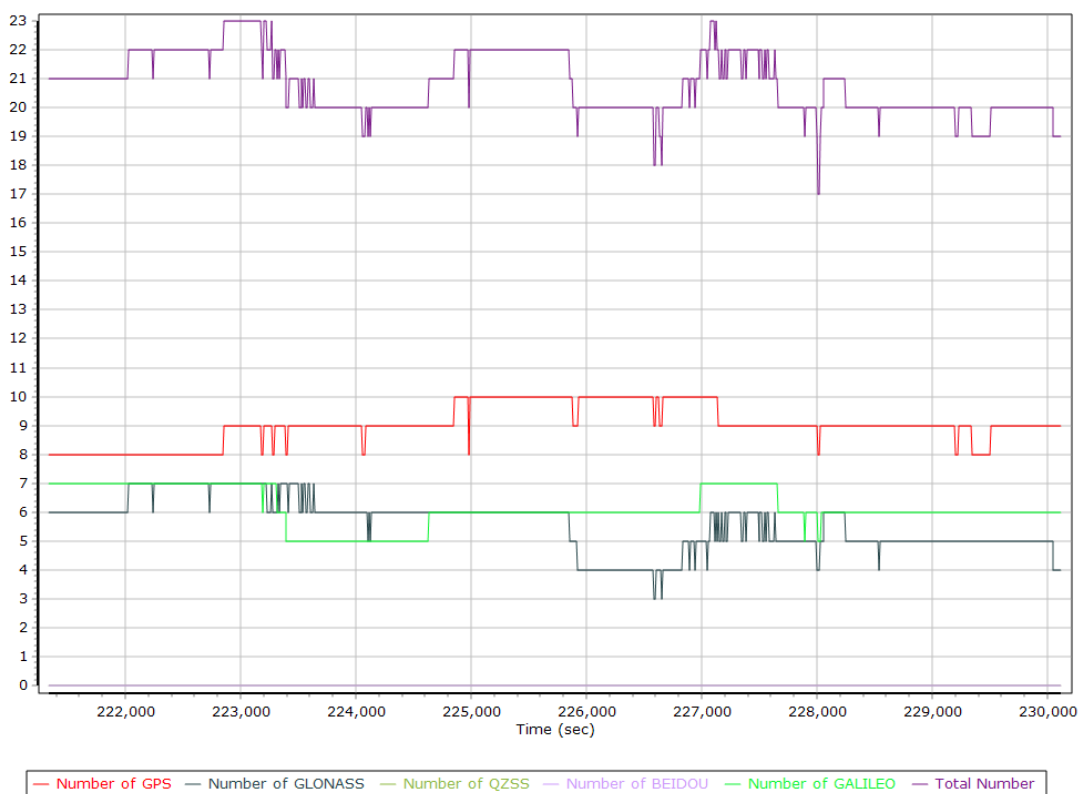


## GNSS QC

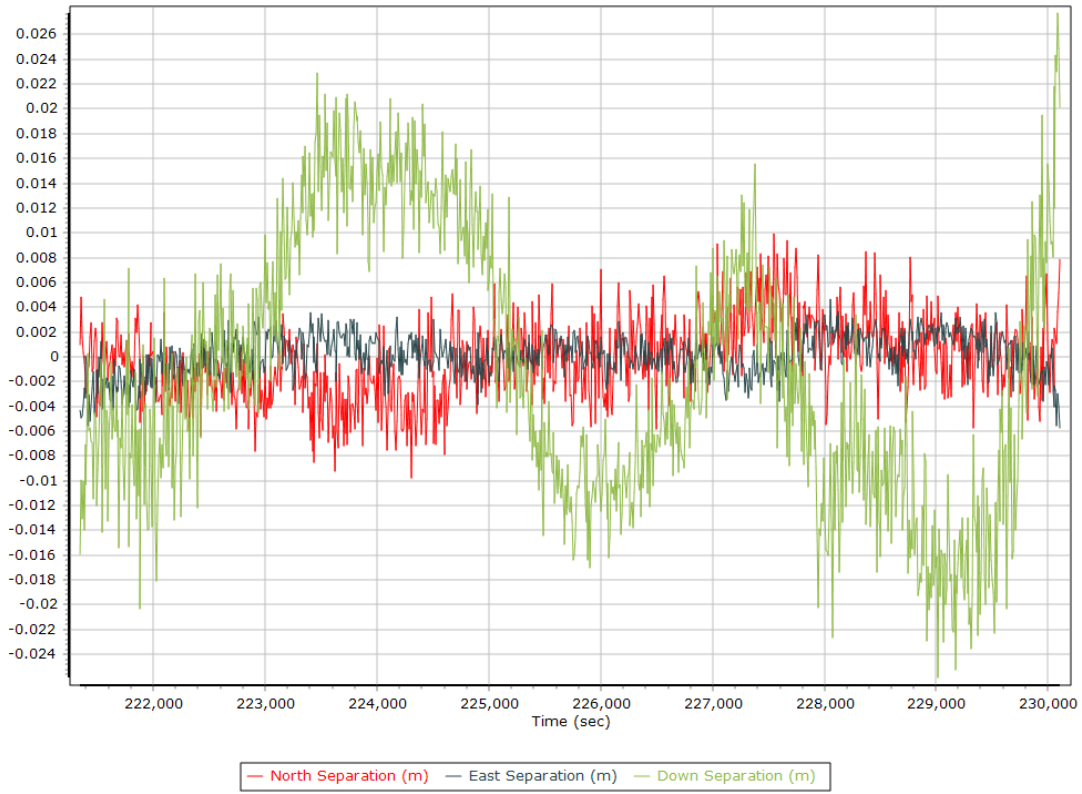
### GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	7	10	9
Number of GLONASS SV	3	7	6
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	0	0
Number of GALILEO SV	5	7	6
Total number of SV	17	23	21
PDOP	0.99	1.35	1.14
QC Solution Gaps	0.00	0.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	9154.00	0.00	0.00
Percentage	100.00	0.00	0.00

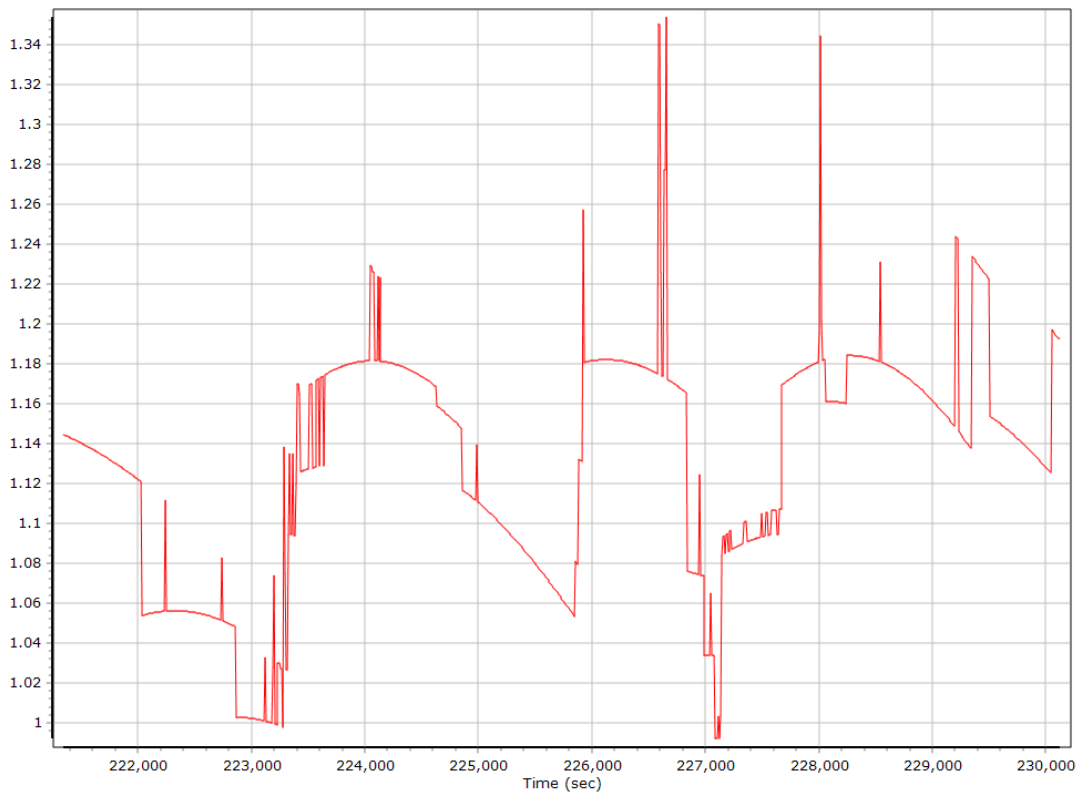
### Num SVs in solution



## Forward/Reverse Separation



## PDOP



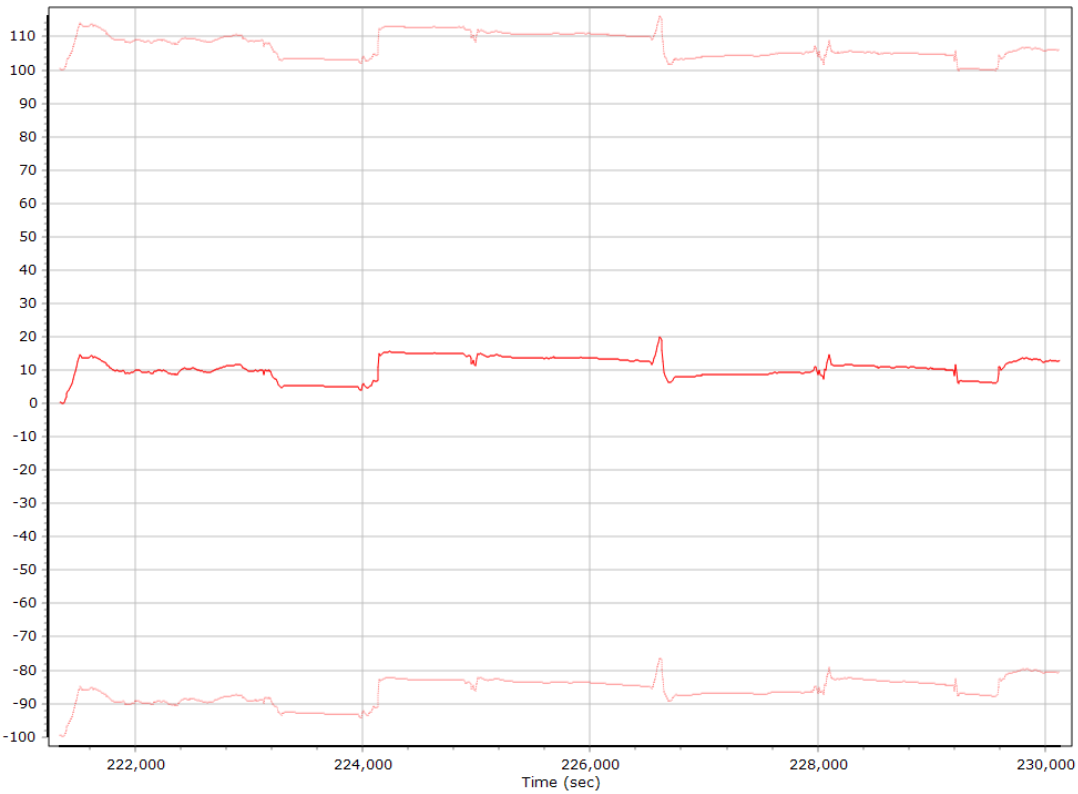
## IN-Fusion QC

### Forward Processed Estimated Errors, Reference Frame

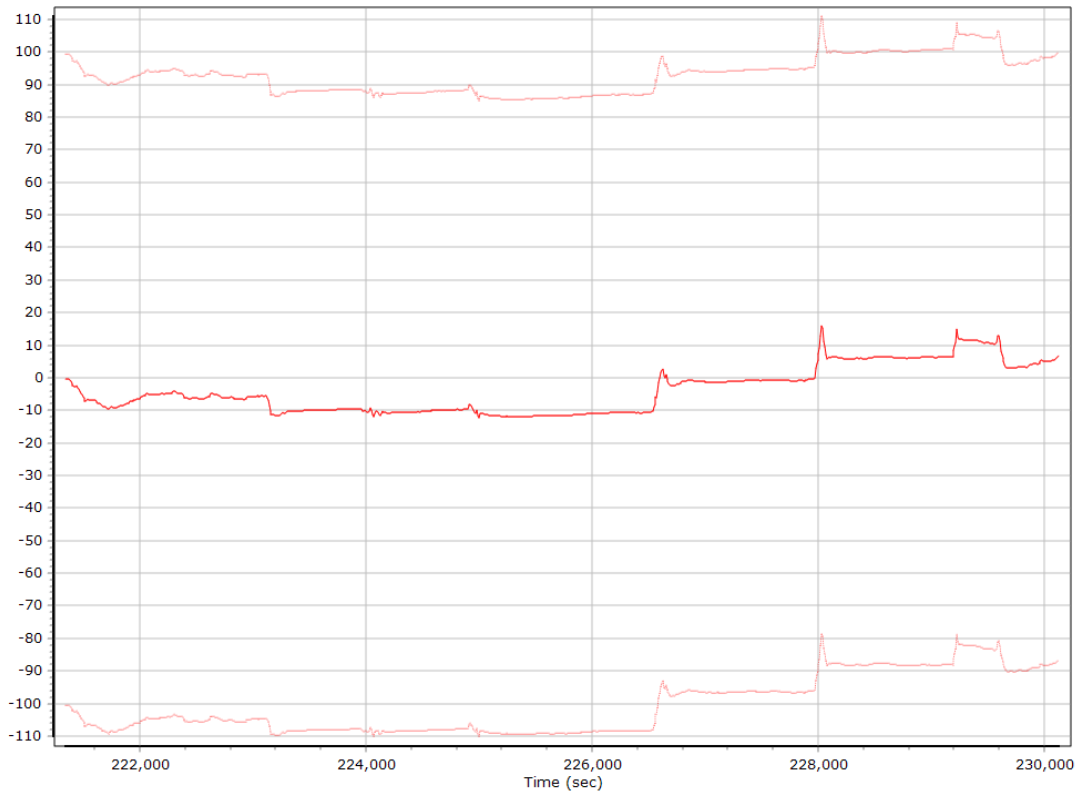
#### Accelerometer Bias (micro-g)



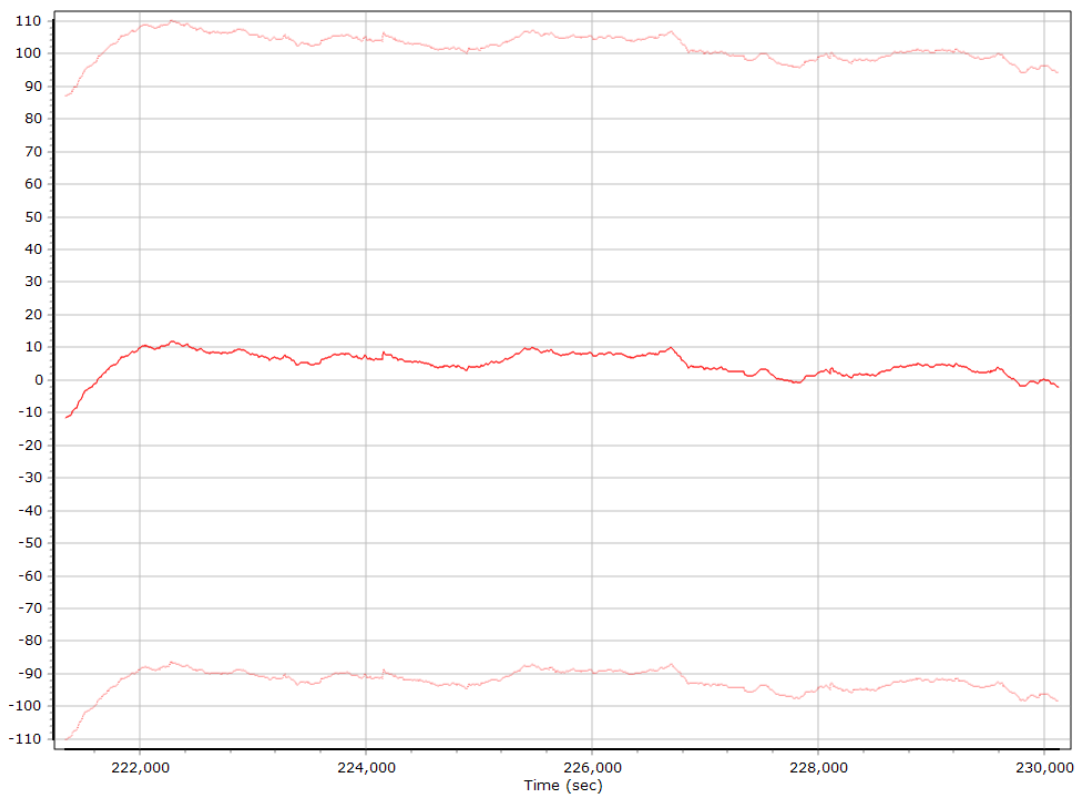
#### X Accelerometer Bias (micro-g)



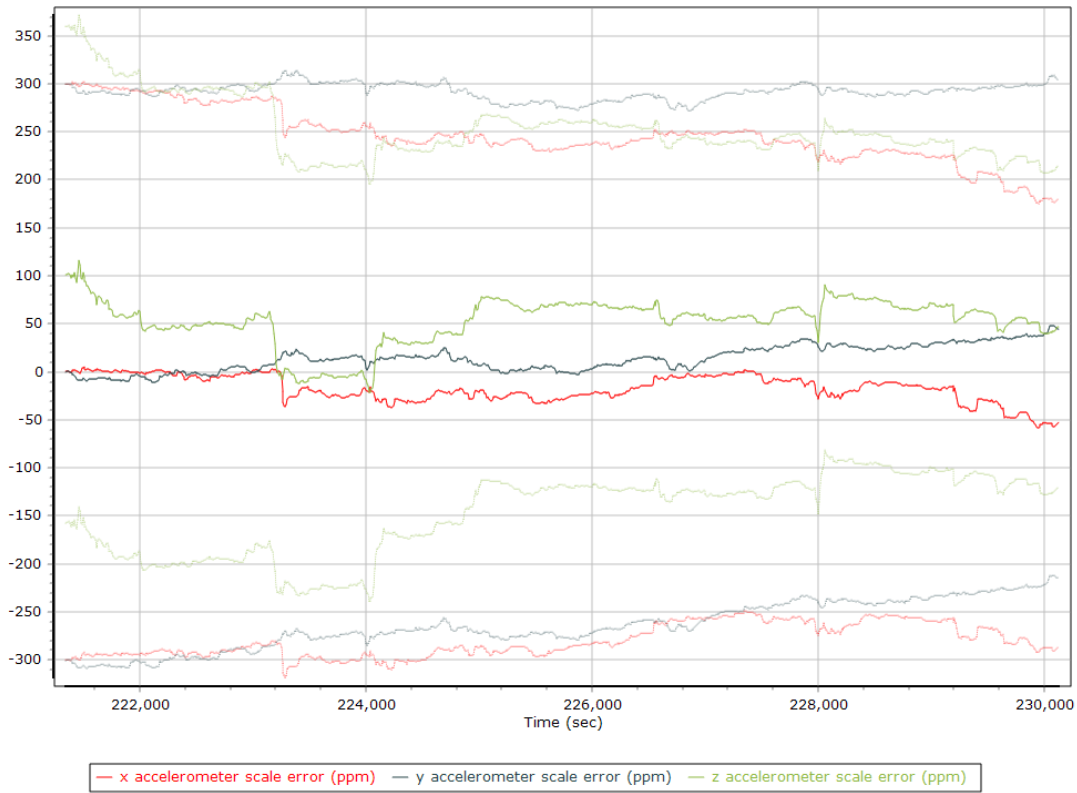
### Y Accelerometer Bias (micro-g)



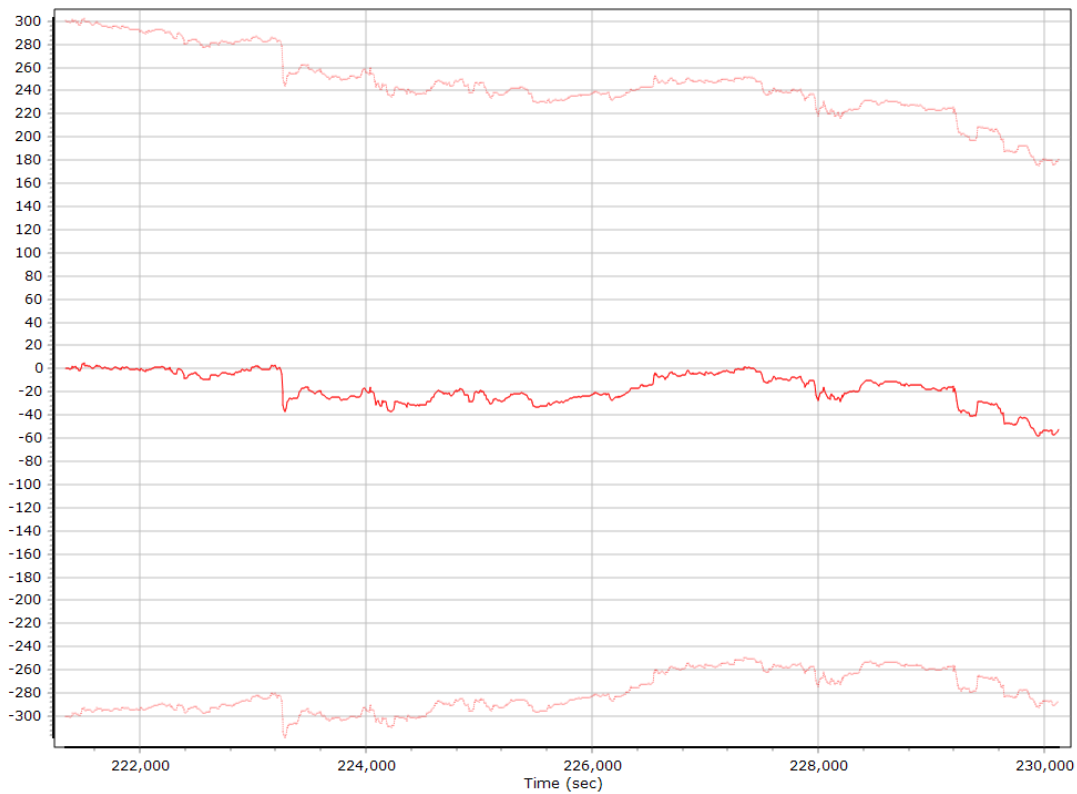
### Z Accelerometer Bias (micro-g)



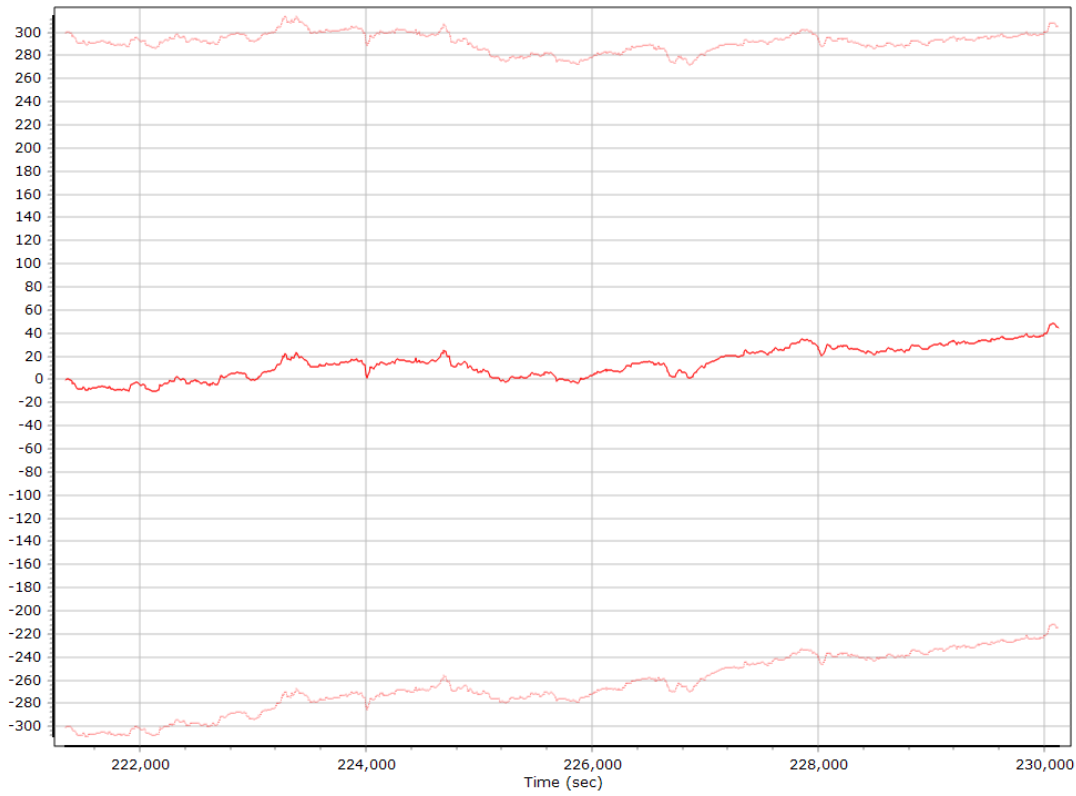
### Accelerometer Scale Error (ppm)



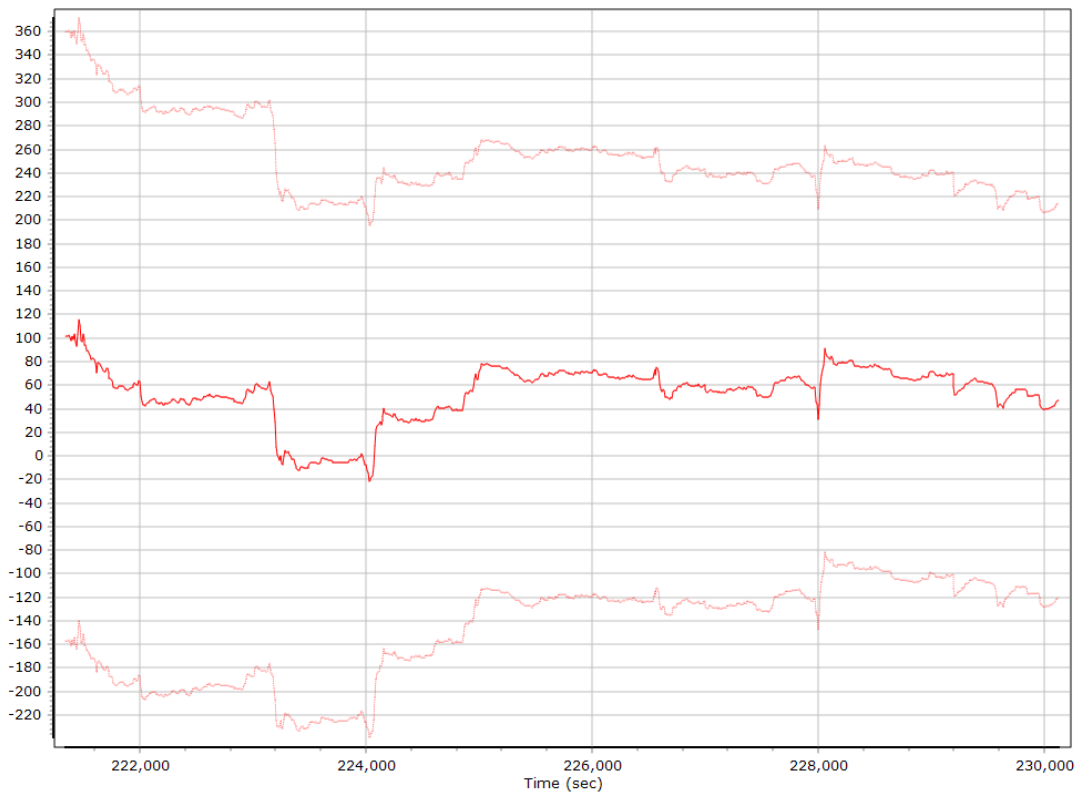
### X Accelerometer Scale Error (ppm)



### Y Accelerometer Scale Error (ppm)



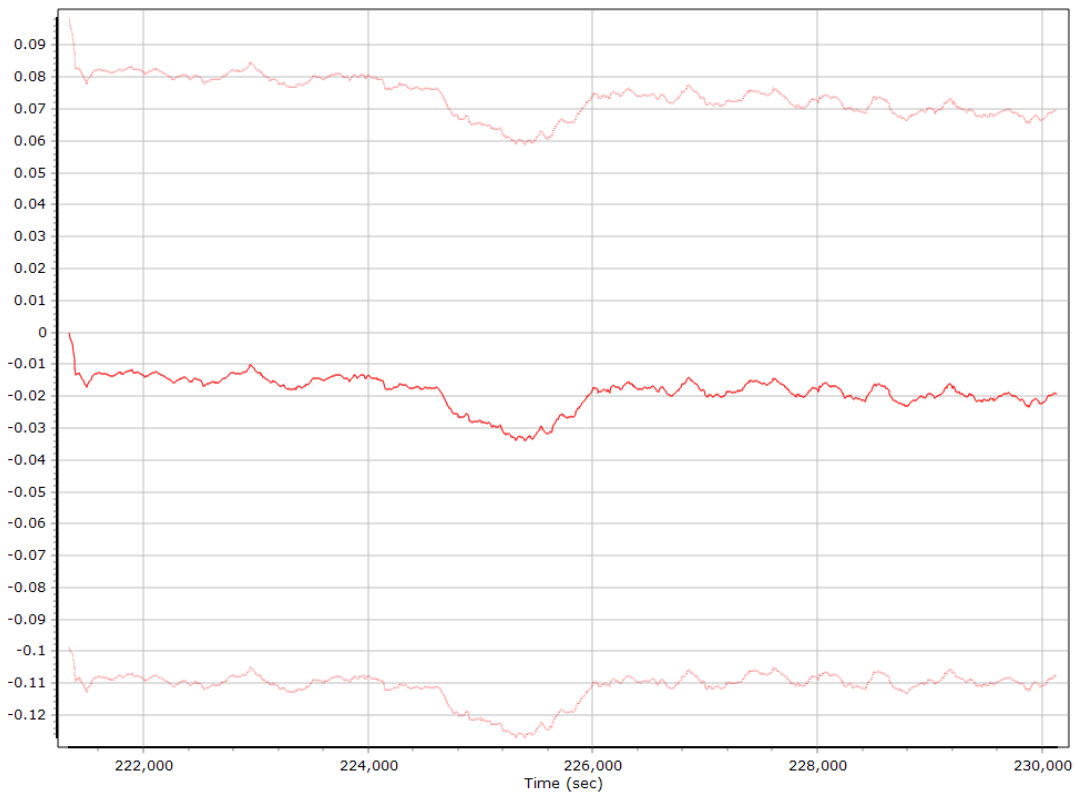
### Z Accelerometer Scale Error (ppm)



### Gyro Bias (deg/h)

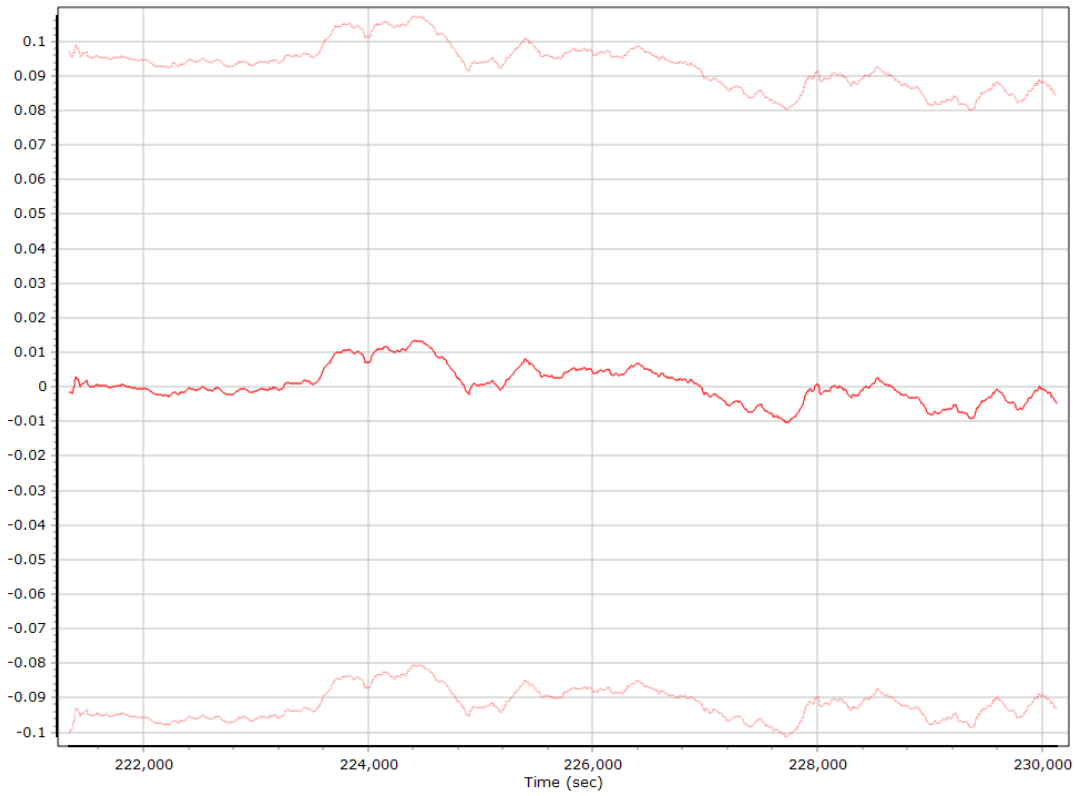


### X Gyro Bias (deg/h)

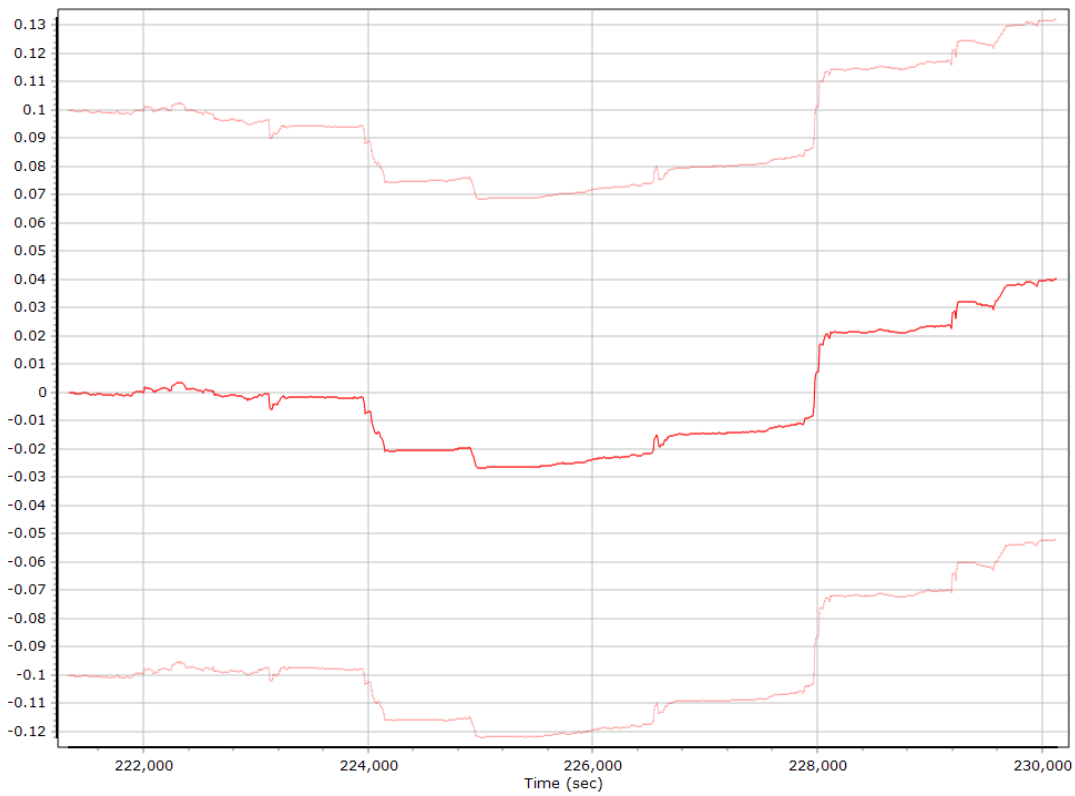




### Y Gyro Bias (deg/h)

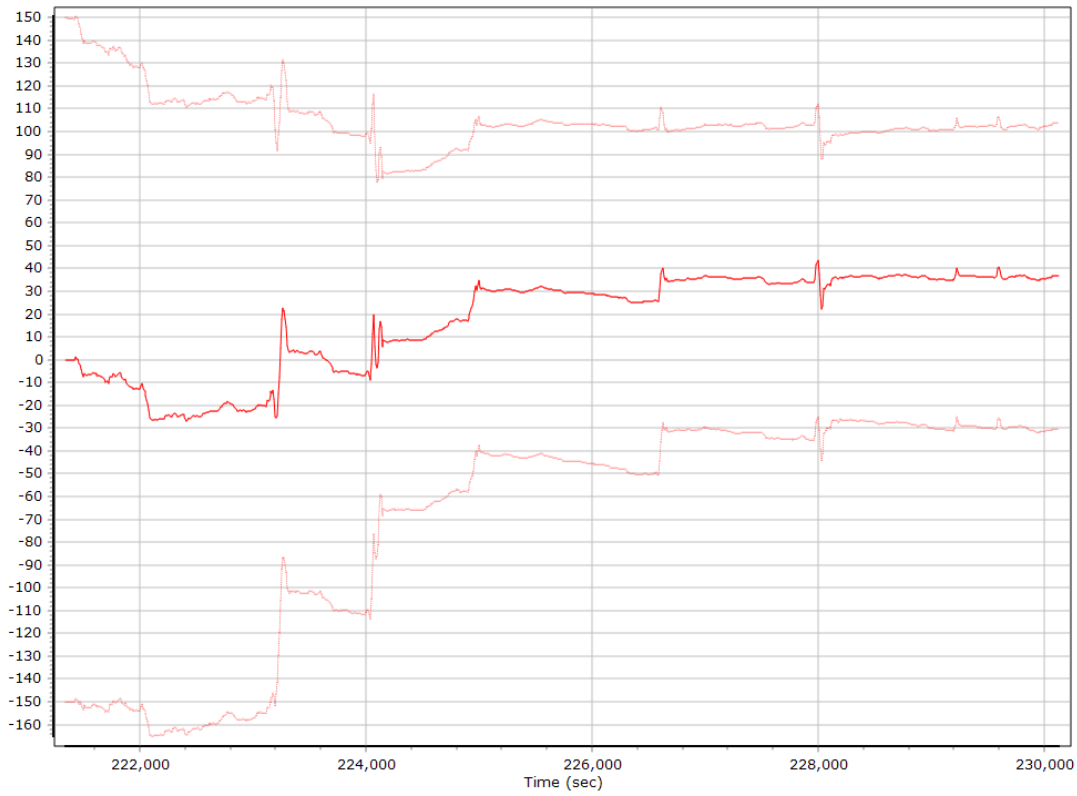


### Z Gyro Bias (deg/h)

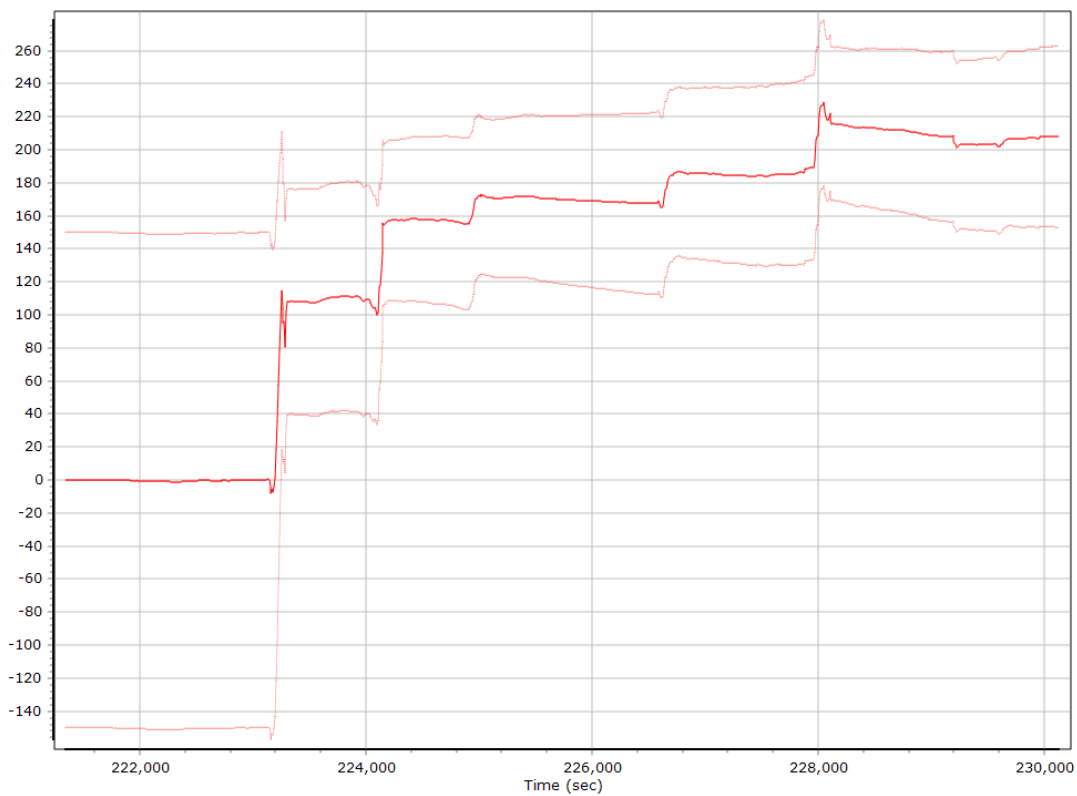




### Y Gyro Scale Error (ppm)

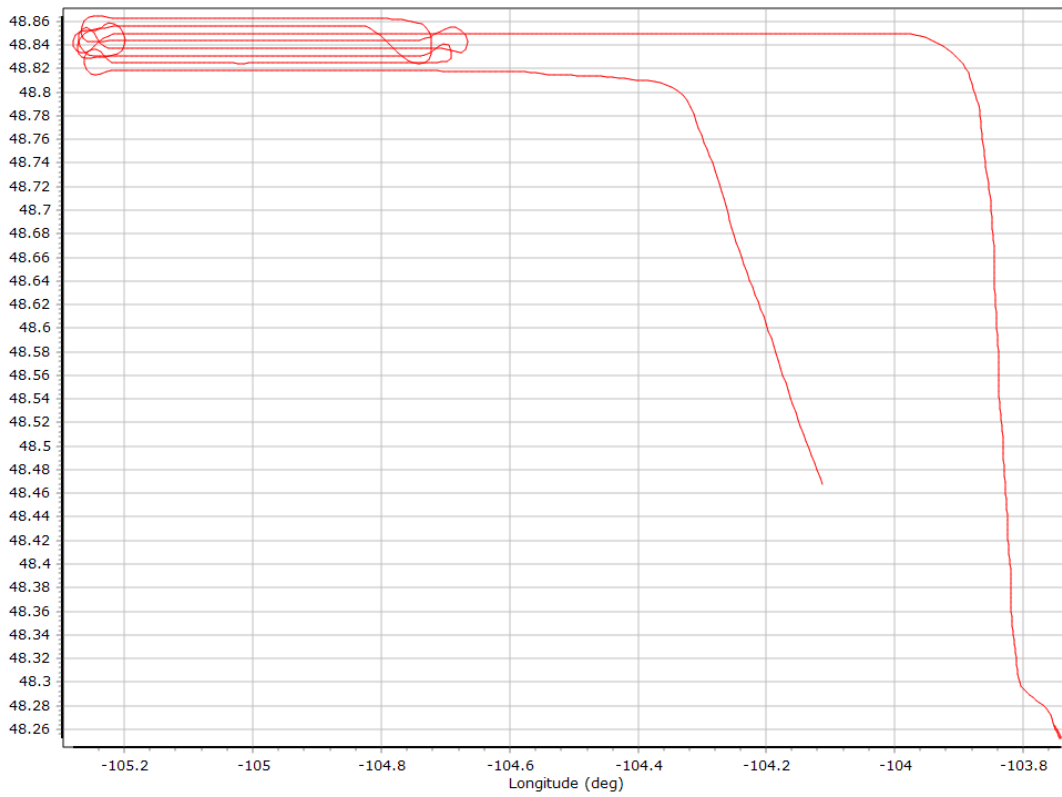


### Z Gyro Scale Error (ppm)

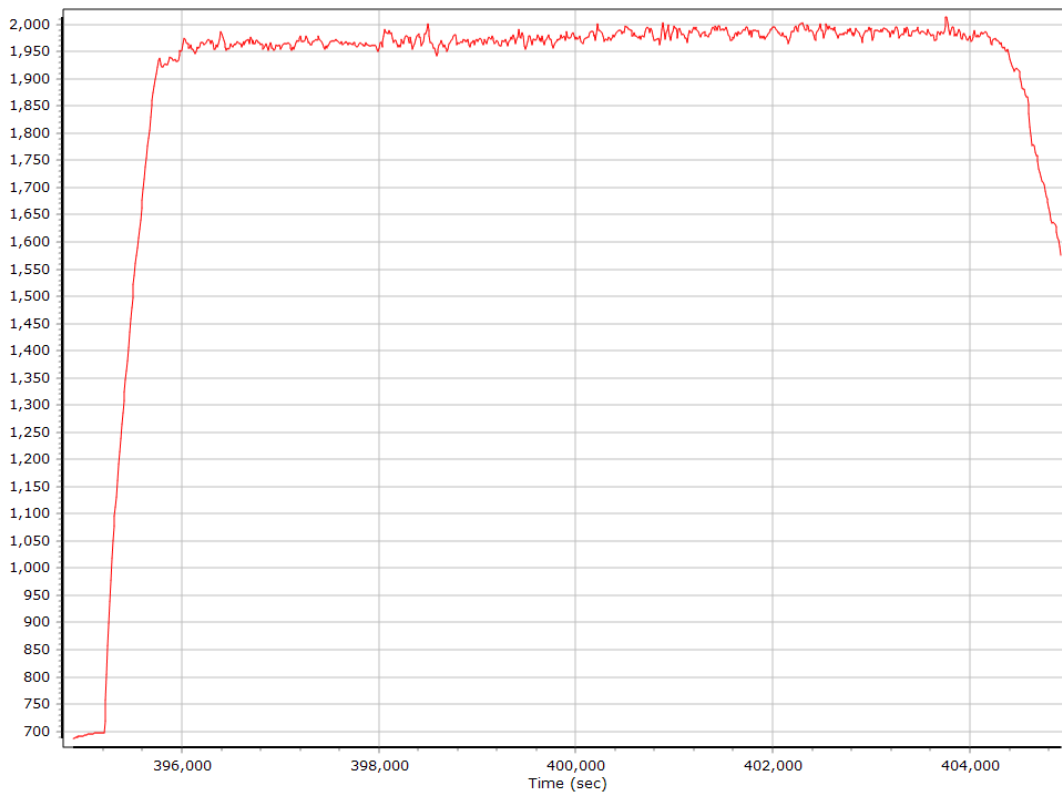


## Smoothed Trajectory Information

### Top View



### Altitude

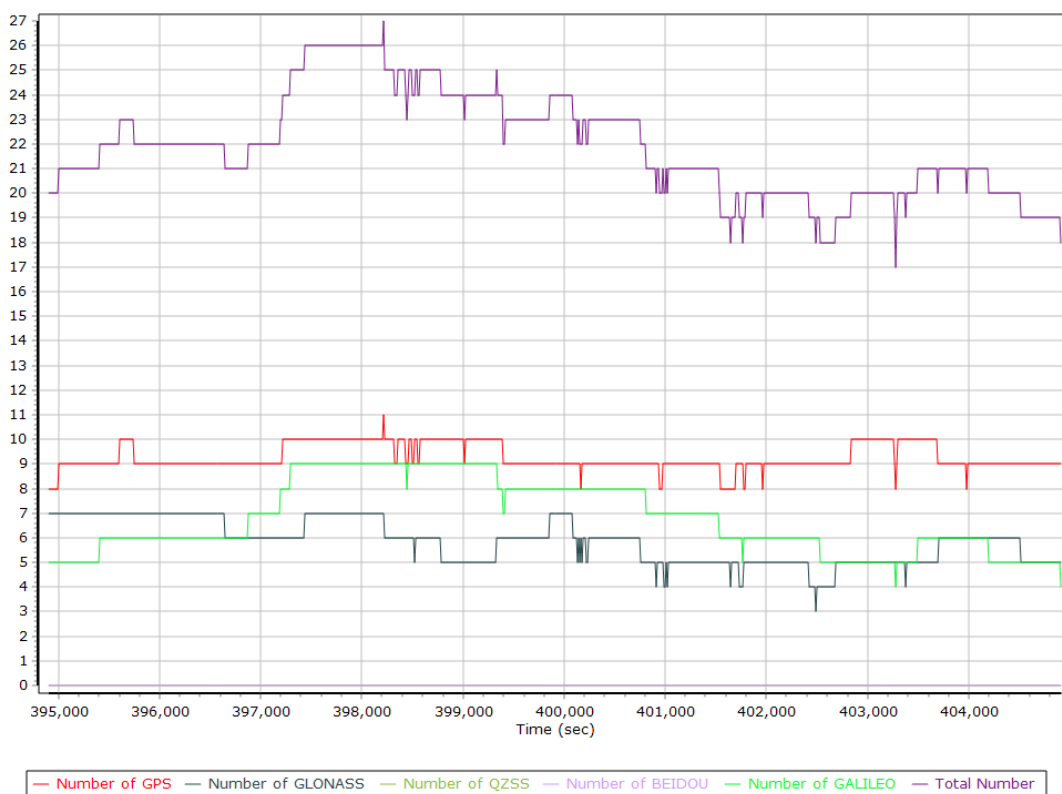


## GNSS QC

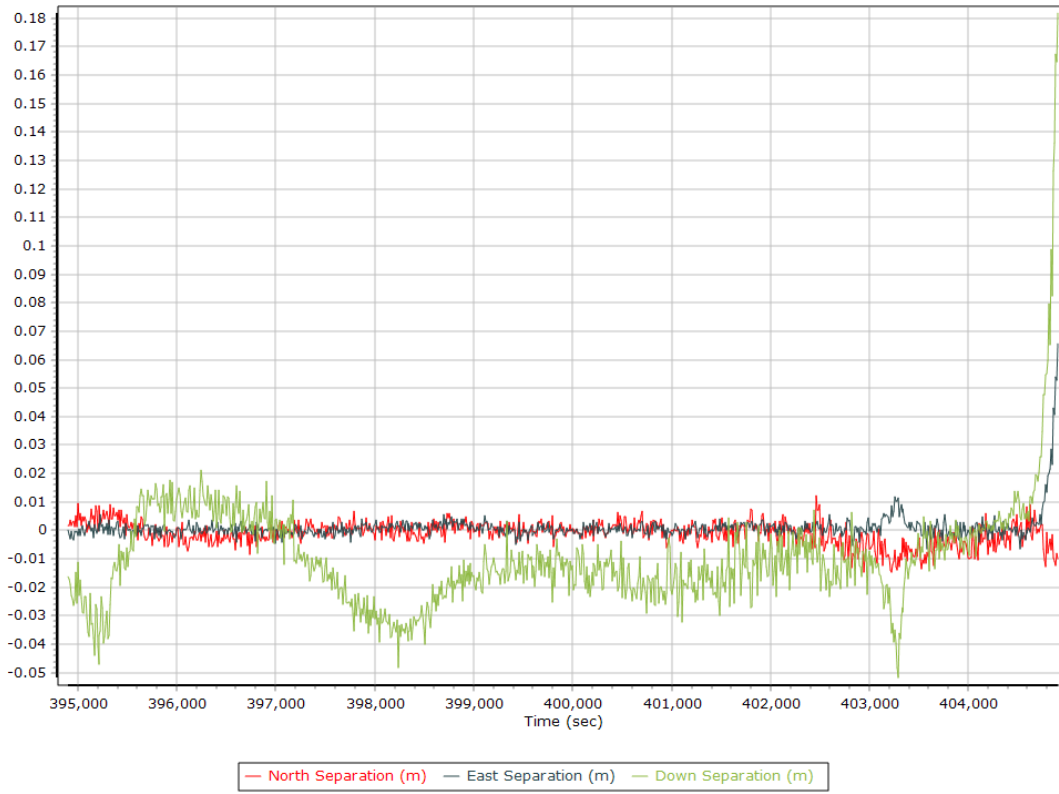
### GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	7	11	9
Number of GLONASS SV	0	8	6
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	0	0
Number of GALILEO SV	4	9	7
Total number of SV	14	27	22
PDOP	0.91	1.60	1.16
QC Solution Gaps	0.00	0.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	10291.00	0.00	0.00
Percentage	100.00	0.00	0.00

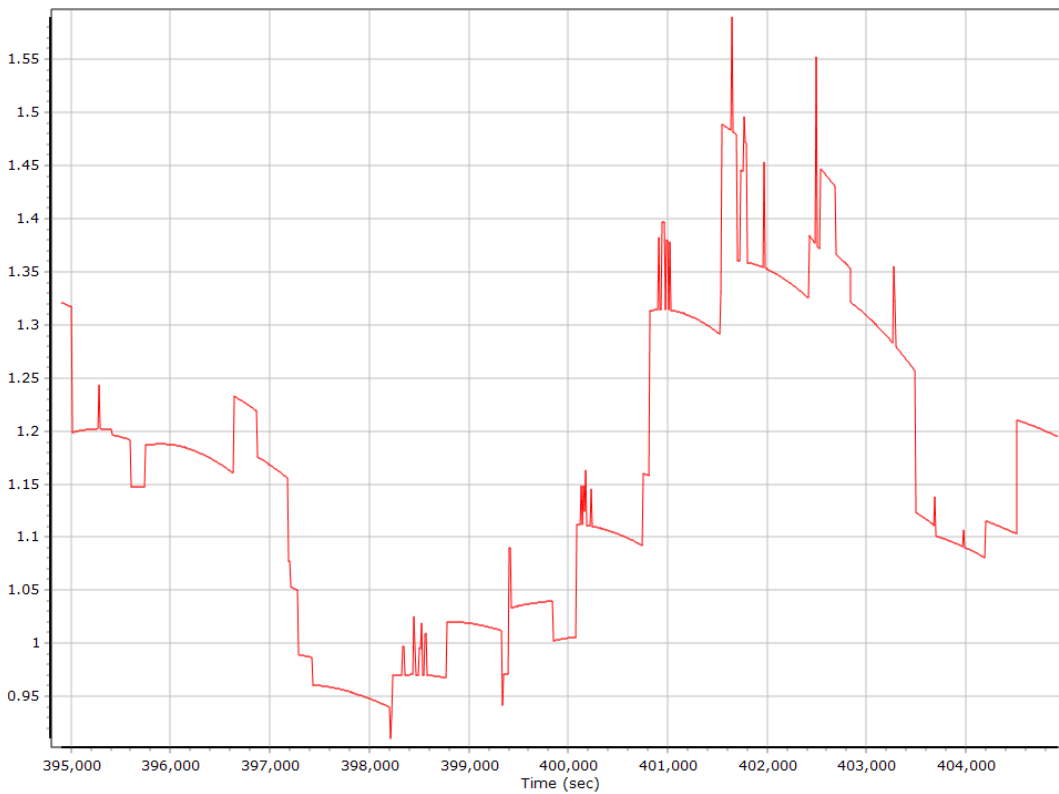
### Num SVs in solution



## Forward/Reverse Separation



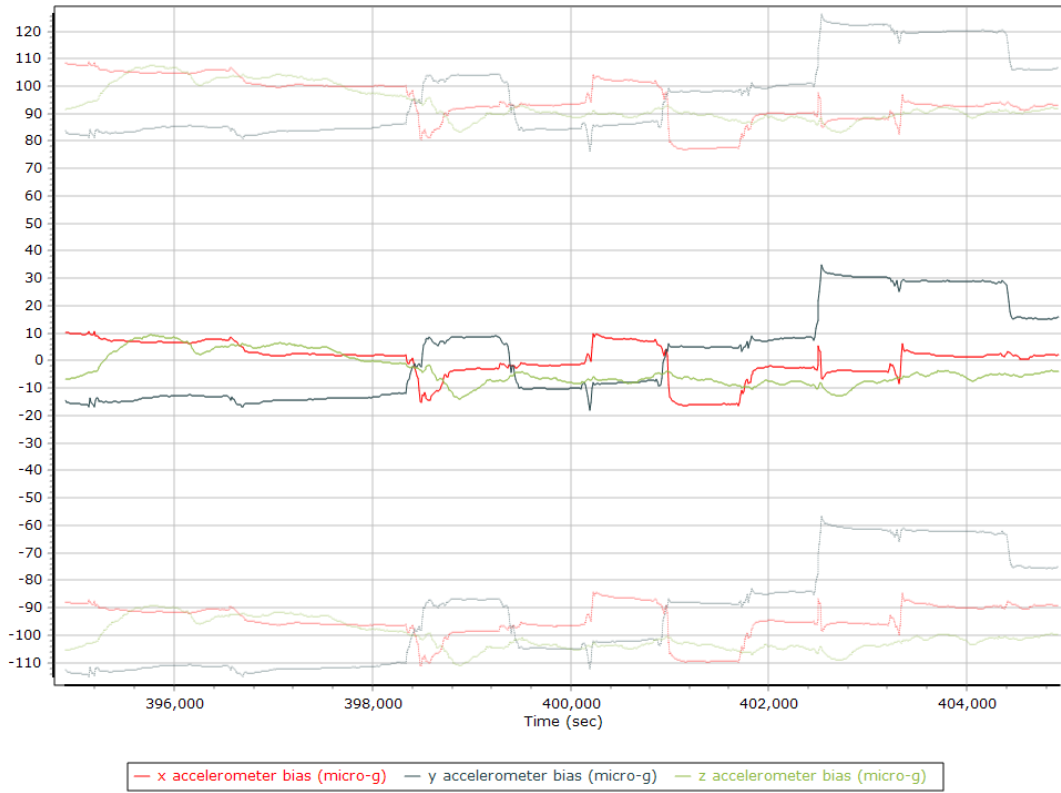
## PDOP



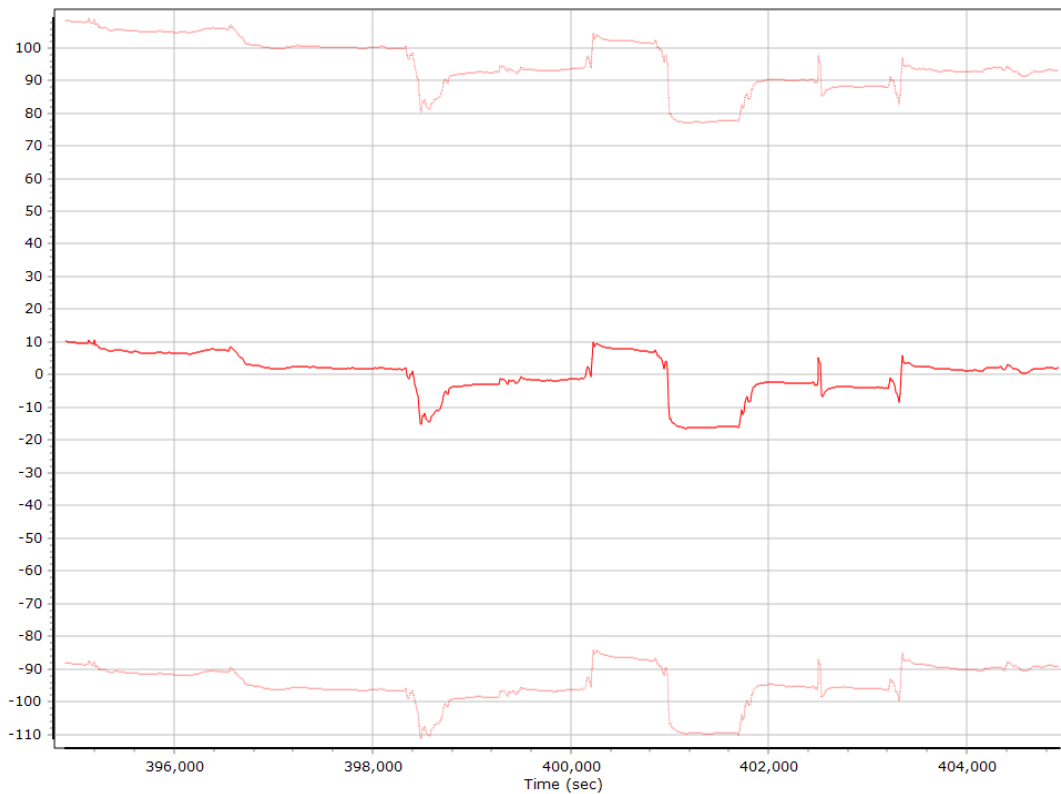
## IN-Fusion QC

### Forward Processed Estimated Errors, Reference Frame

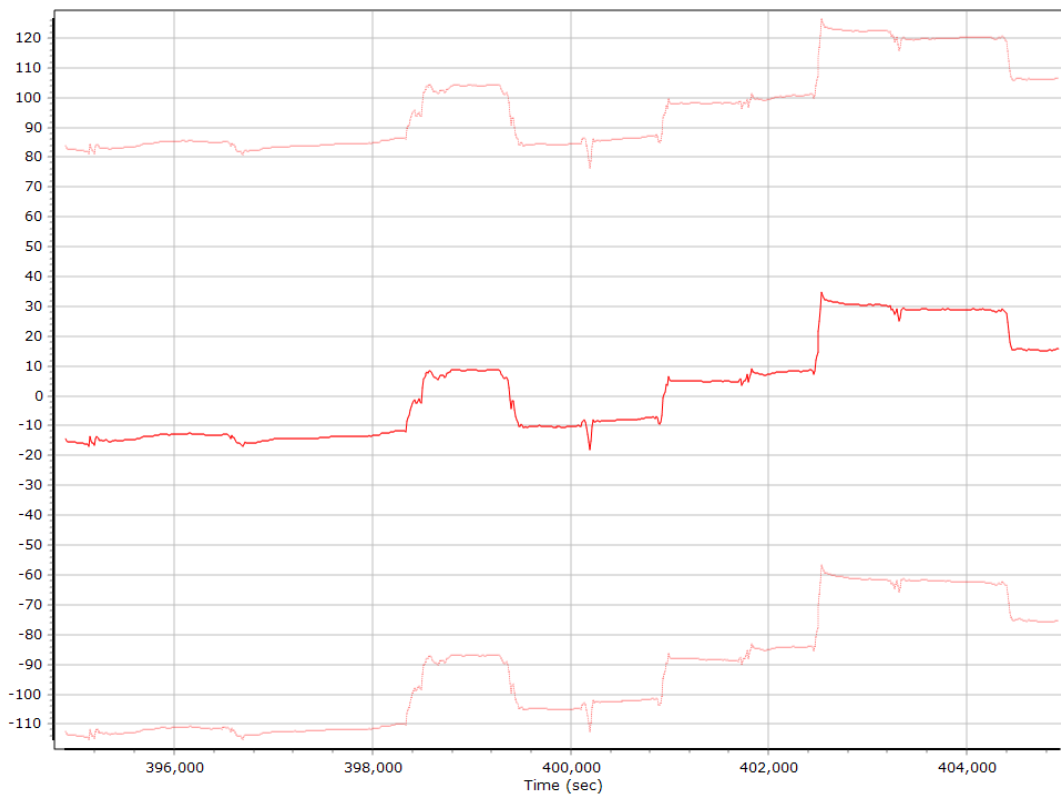
#### Accelerometer Bias (micro-g)



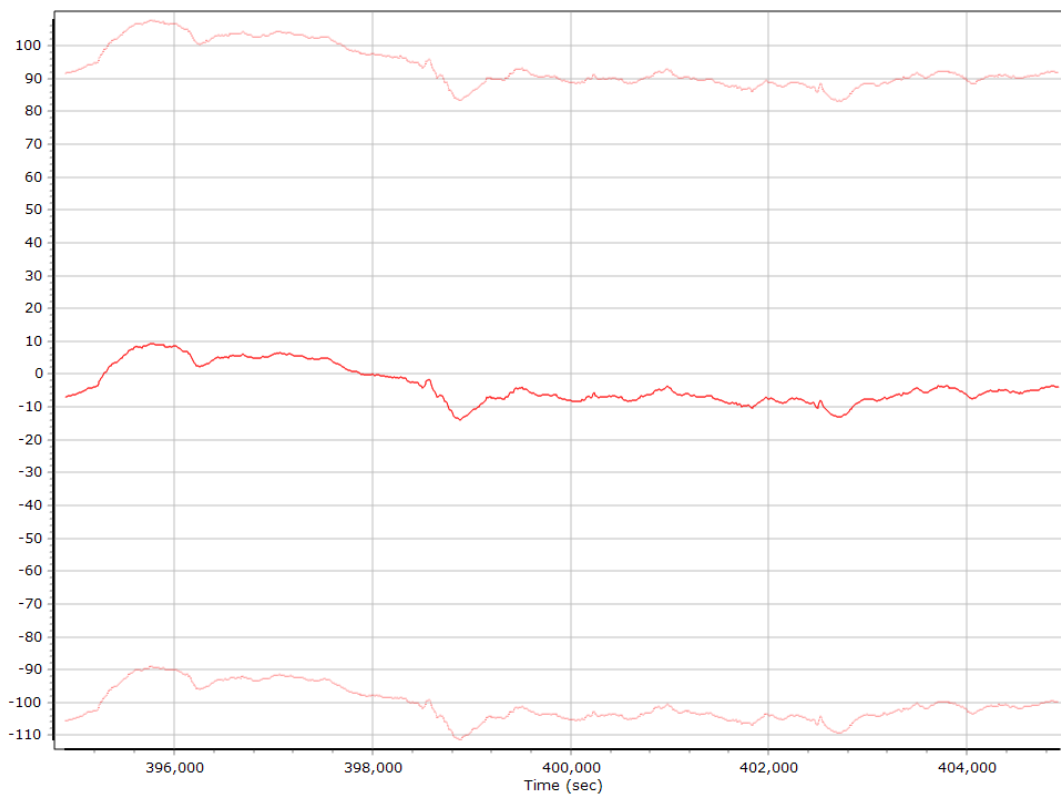
#### X Accelerometer Bias (micro-g)



### Y Accelerometer Bias (micro-g)

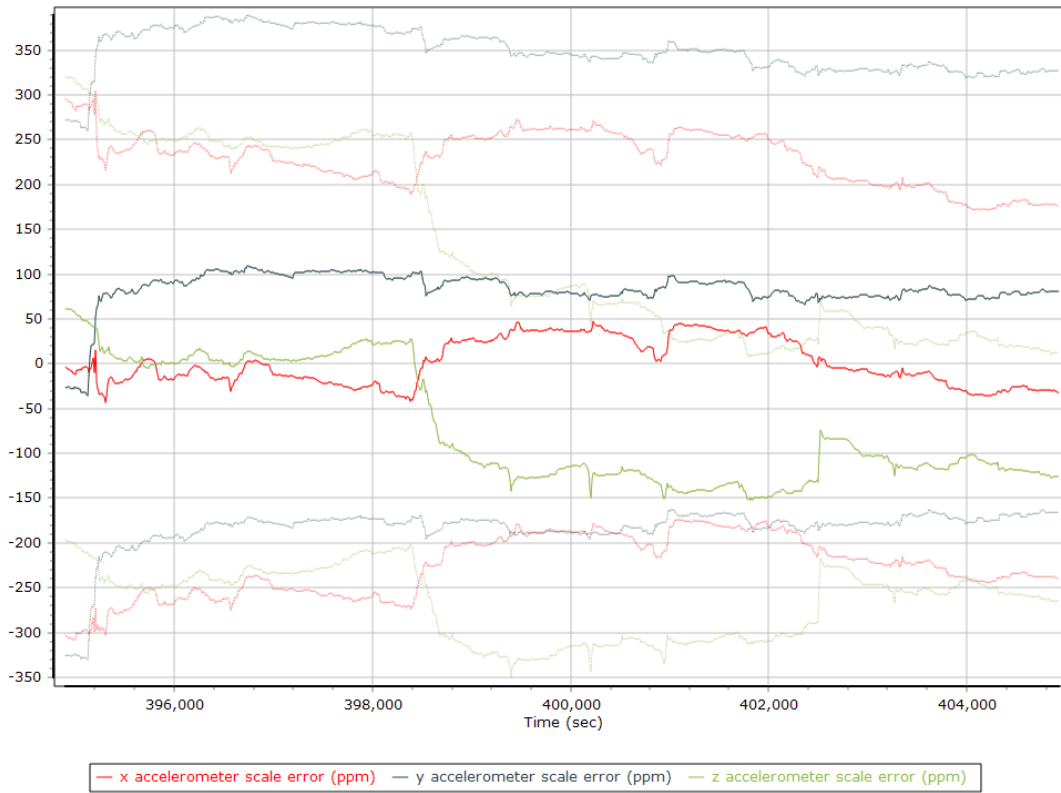


### Z Accelerometer Bias (micro-g)

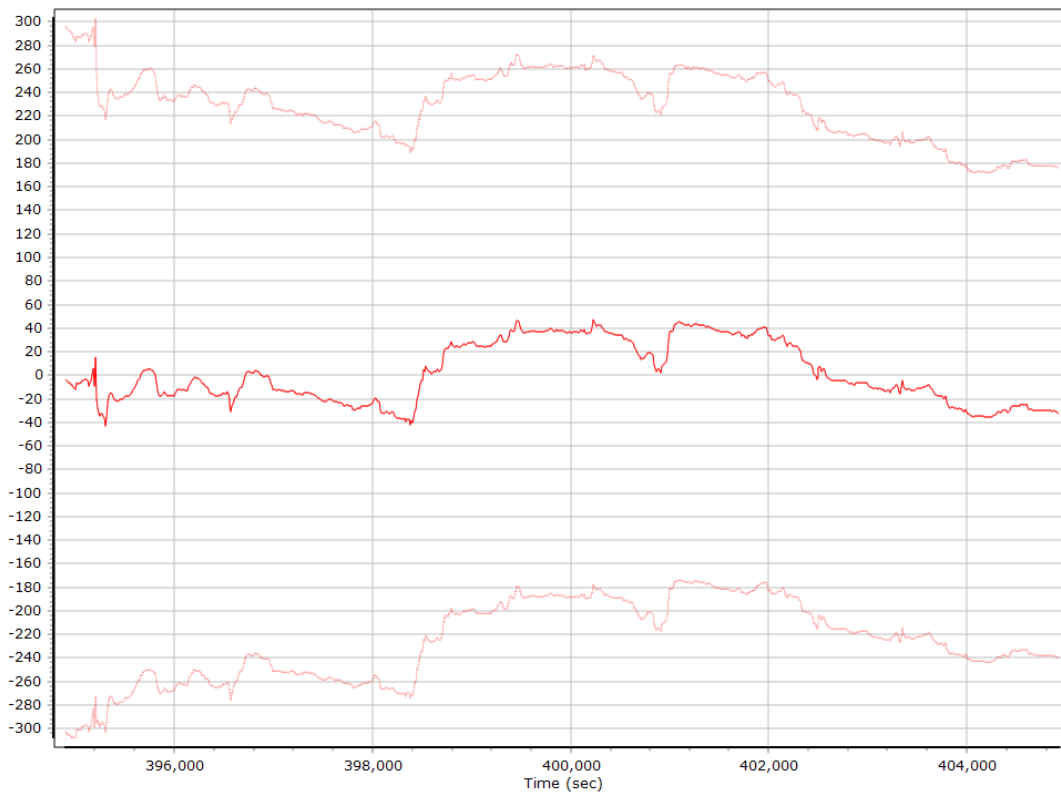




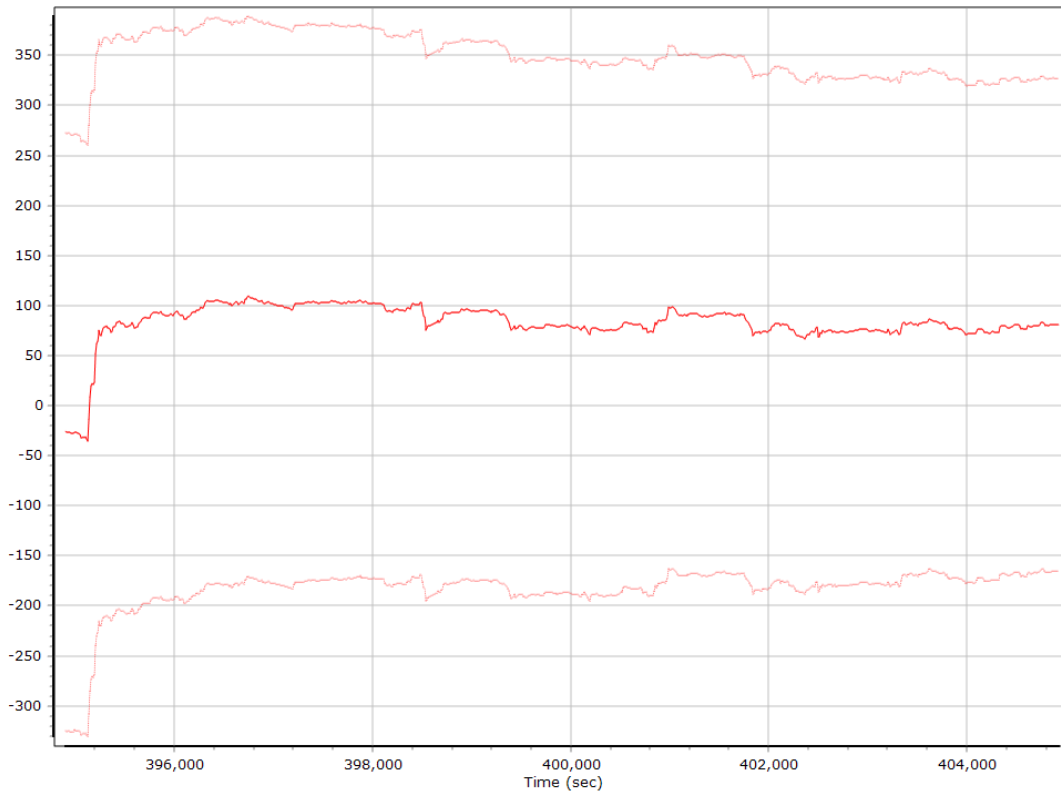
### Accelerometer Scale Error (ppm)



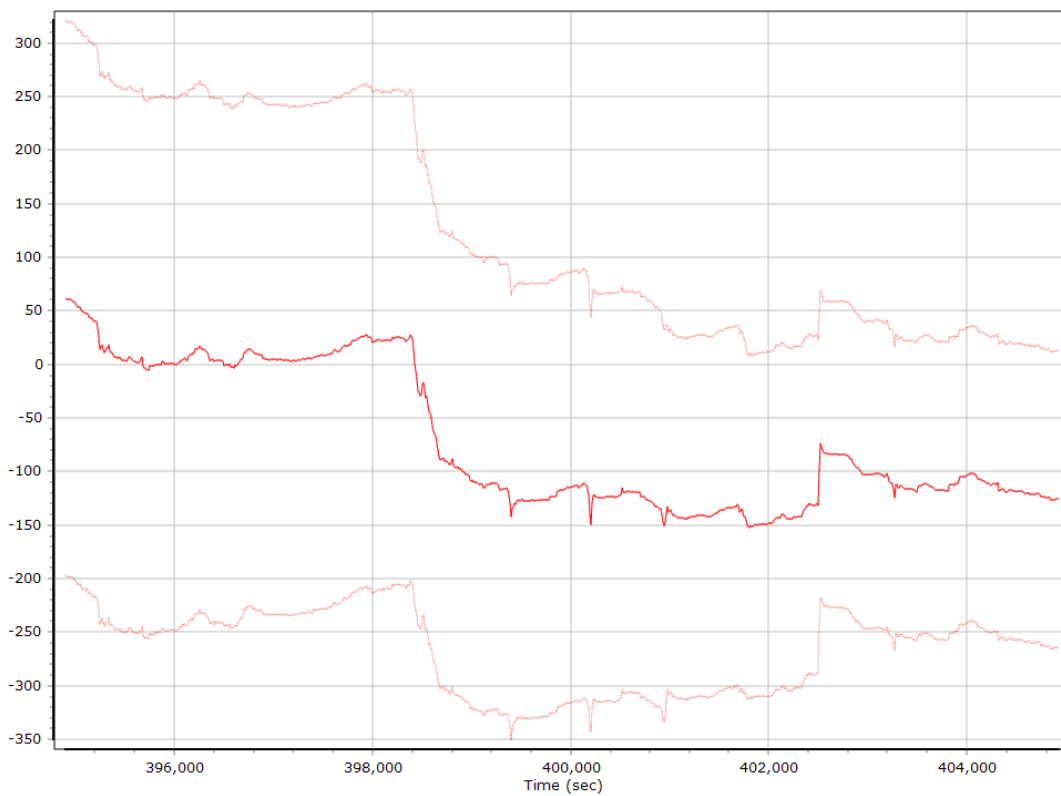
### X Accelerometer Scale Error (ppm)



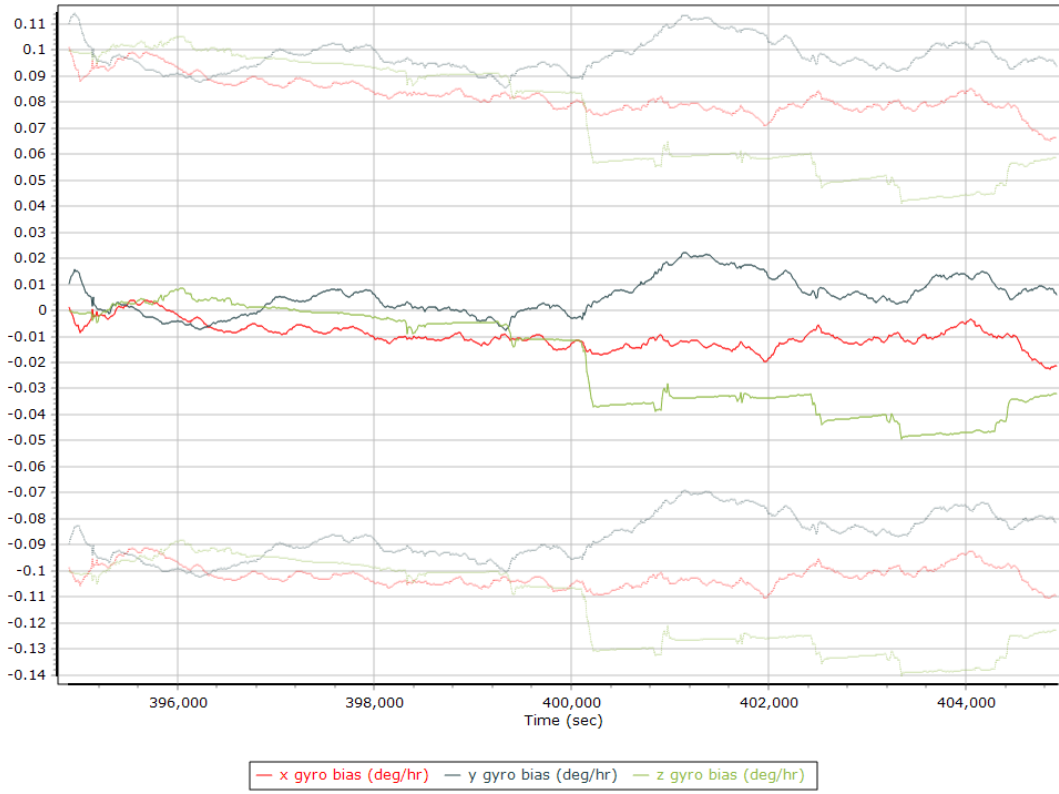
### Y Accelerometer Scale Error (ppm)



### Z Accelerometer Scale Error (ppm)



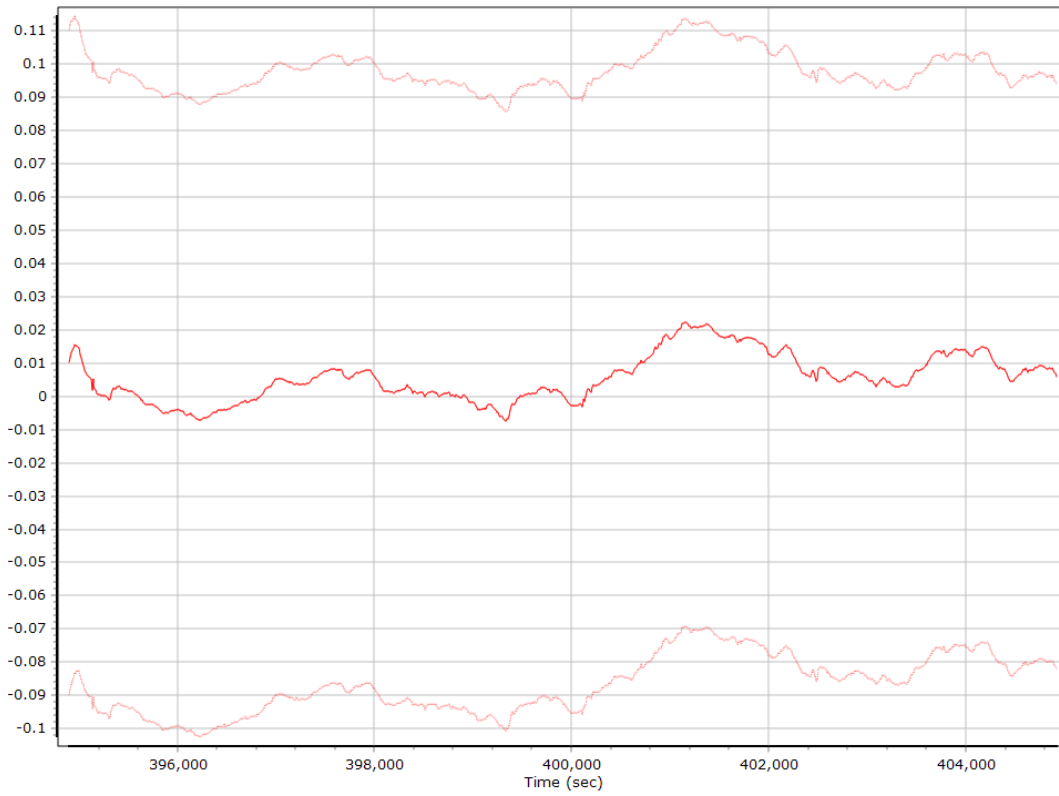
### Gyro Bias (deg/h)



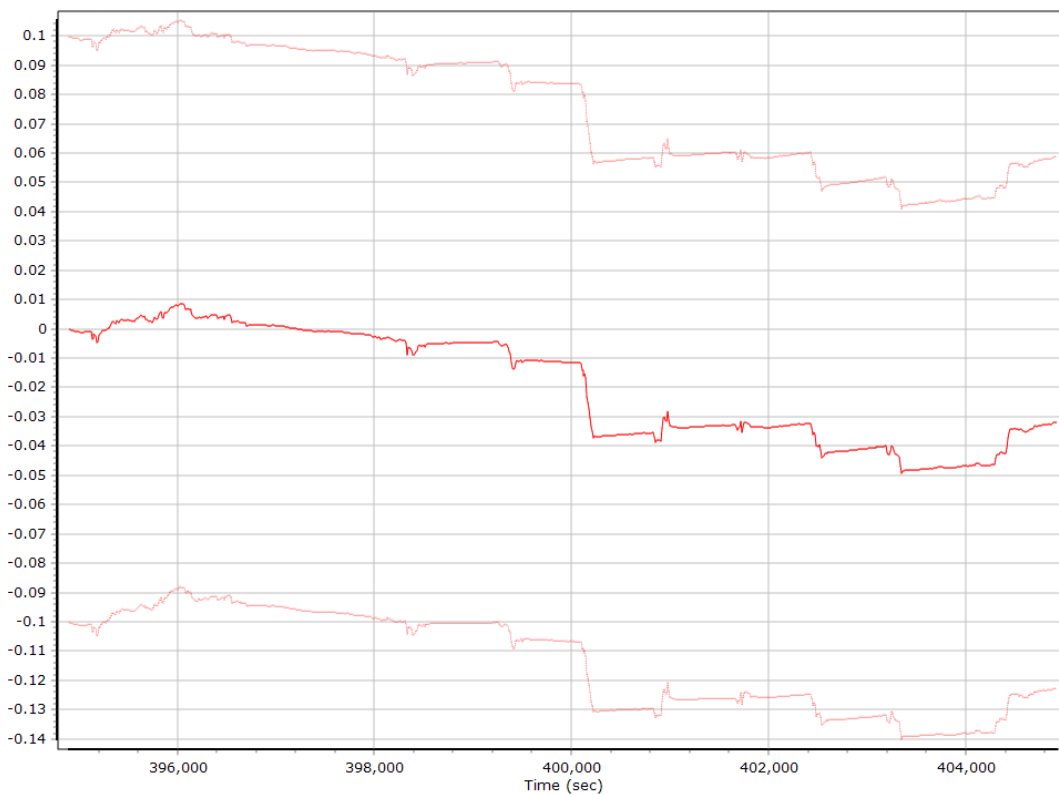
### X Gyro Bias (deg/h)



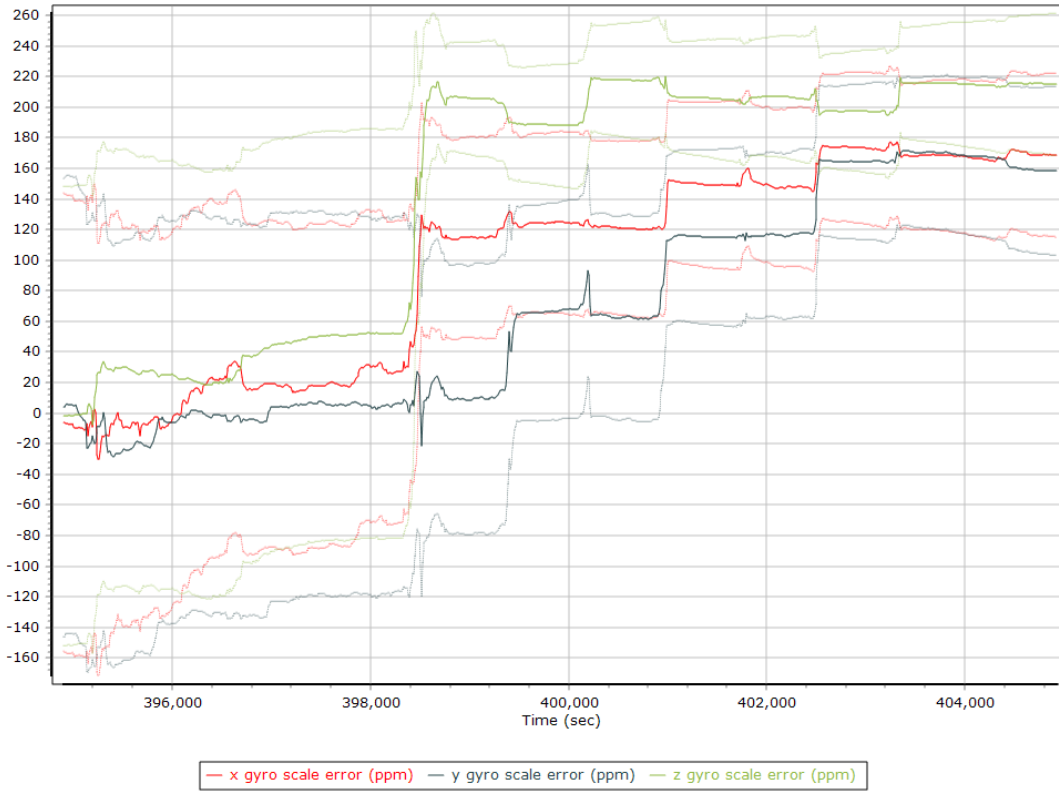
### Y Gyro Bias (deg/h)



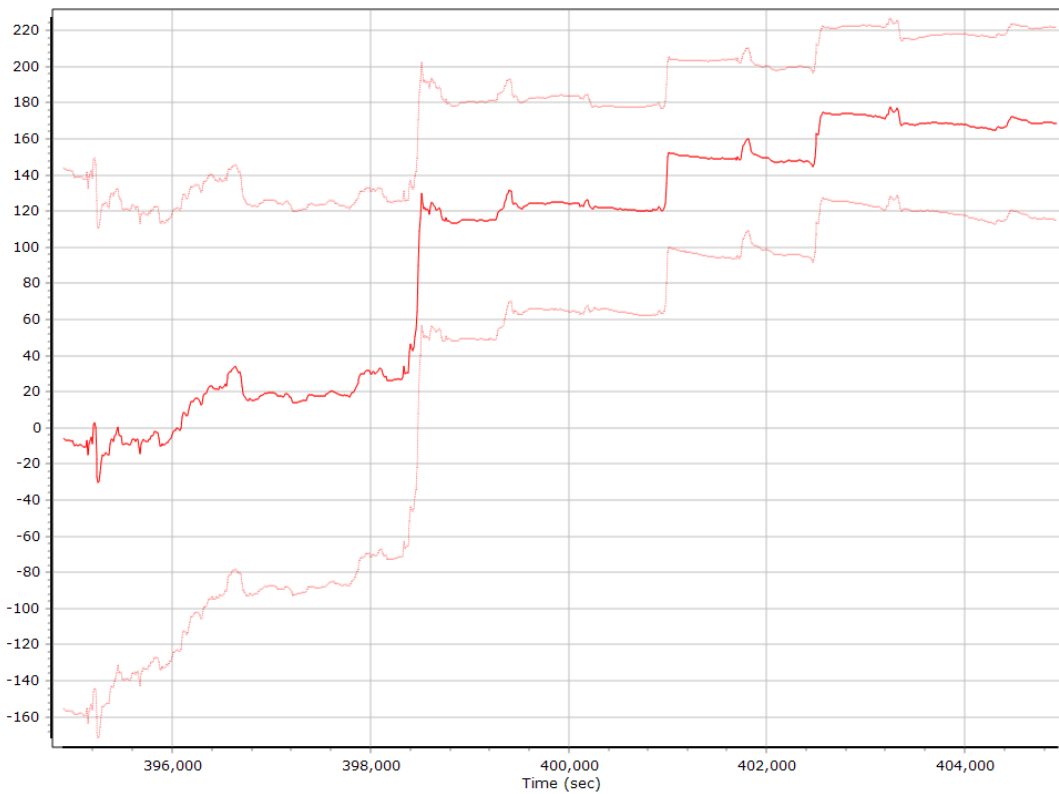
### Z Gyro Bias (deg/h)



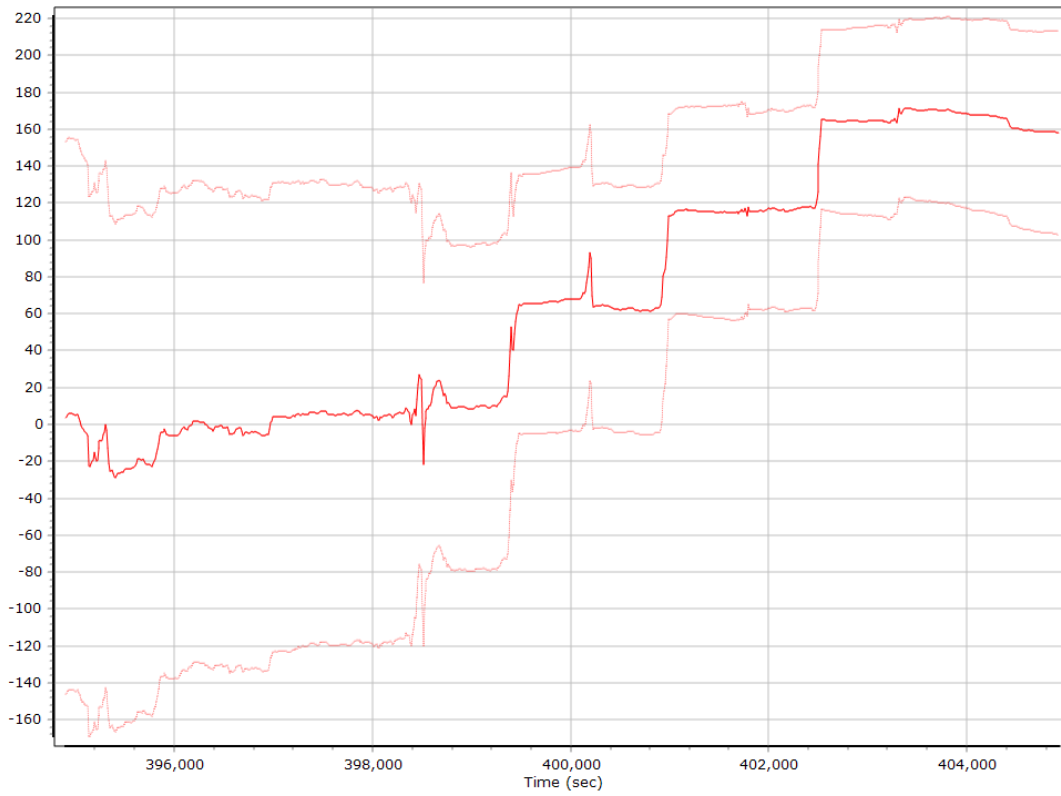
### Gyro Scale Error (ppm)



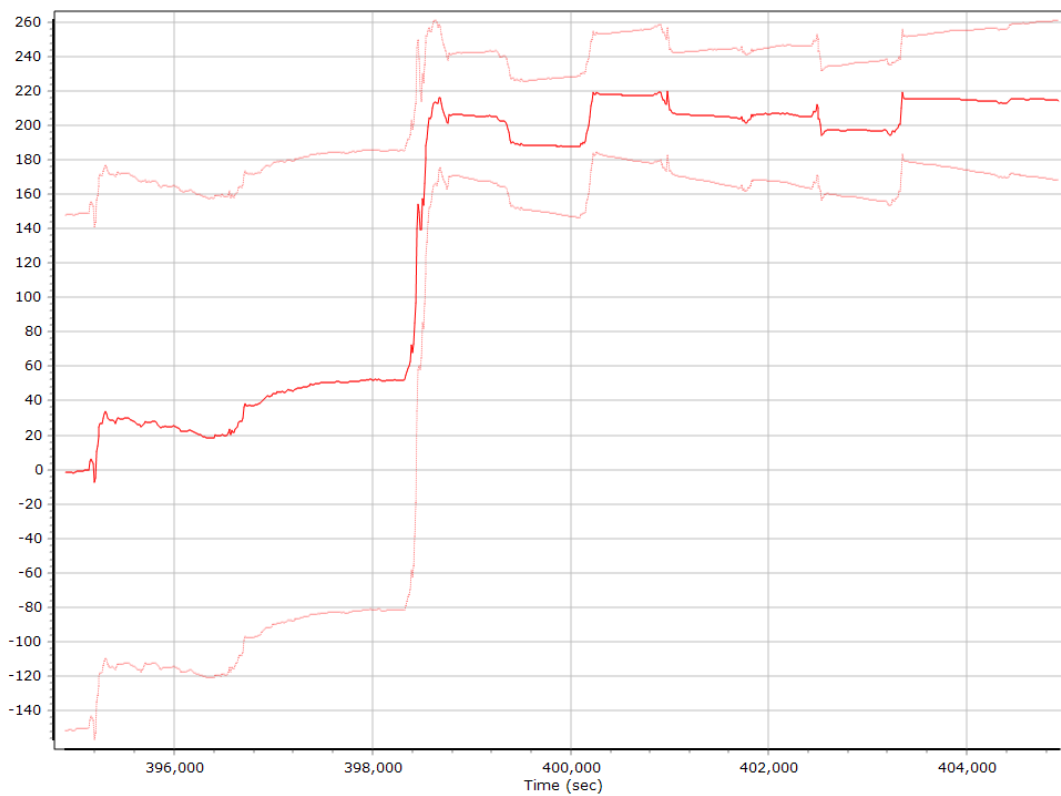
### X Gyro Scale Error (ppm)



### Y Gyro Scale Error (ppm)

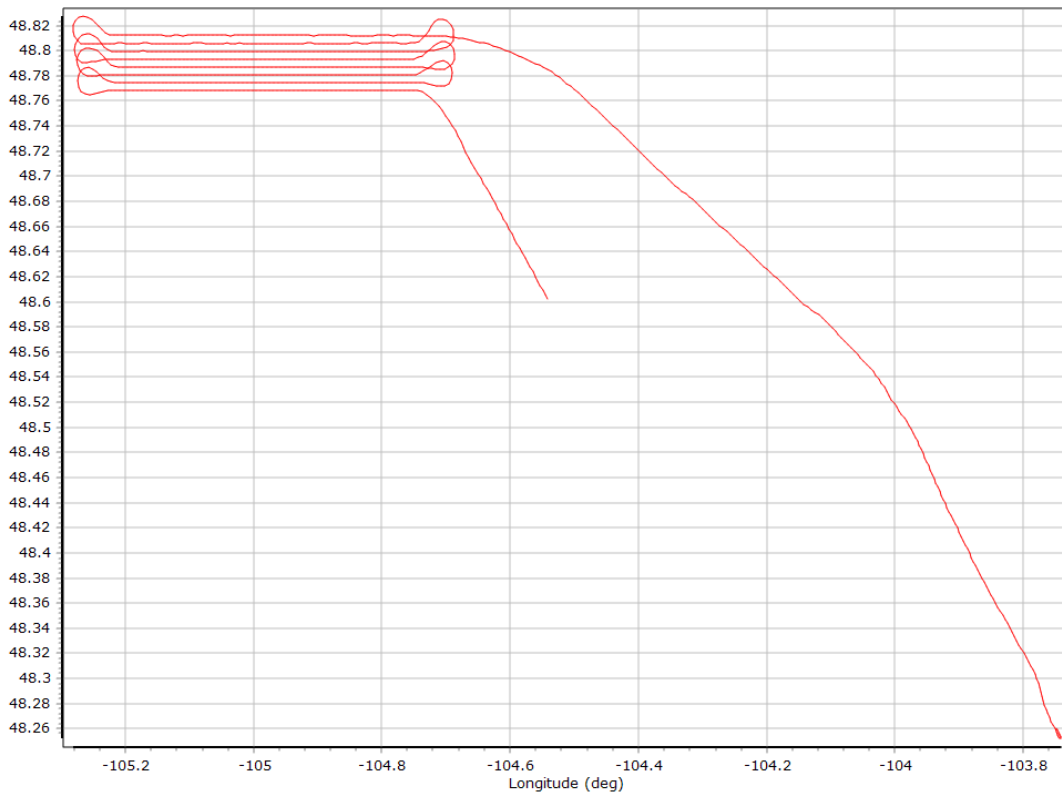


### Z Gyro Scale Error (ppm)

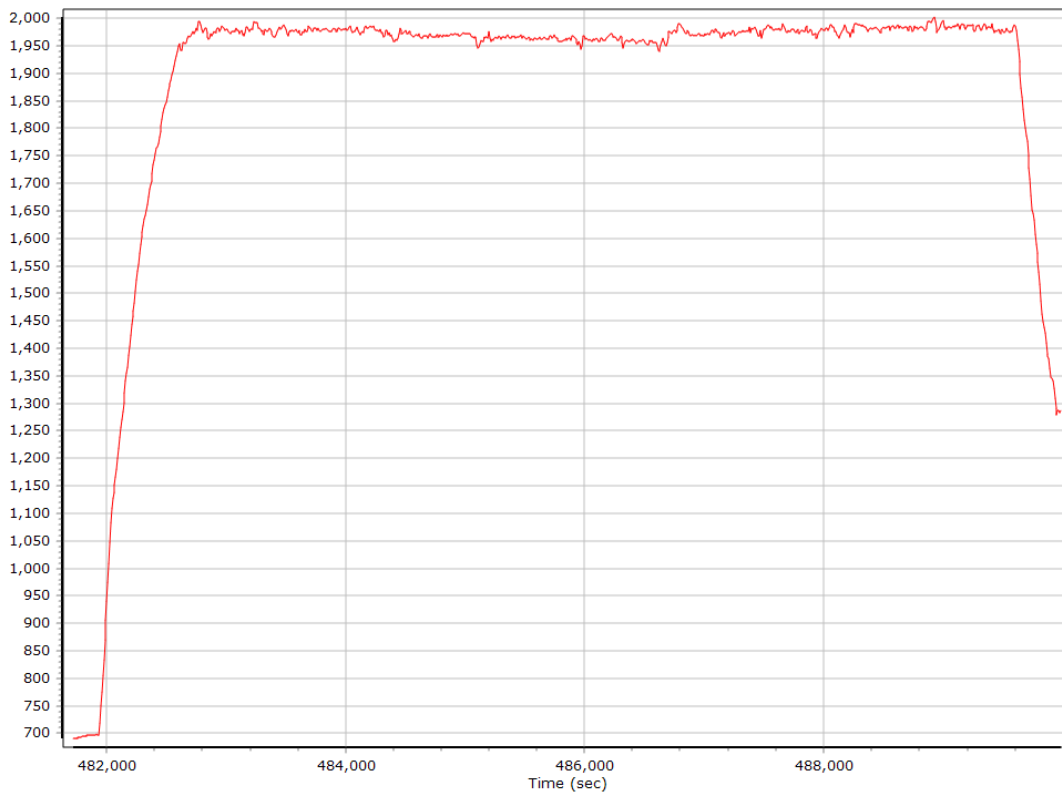


## Smoothed Trajectory Information

### Top View



### Altitude

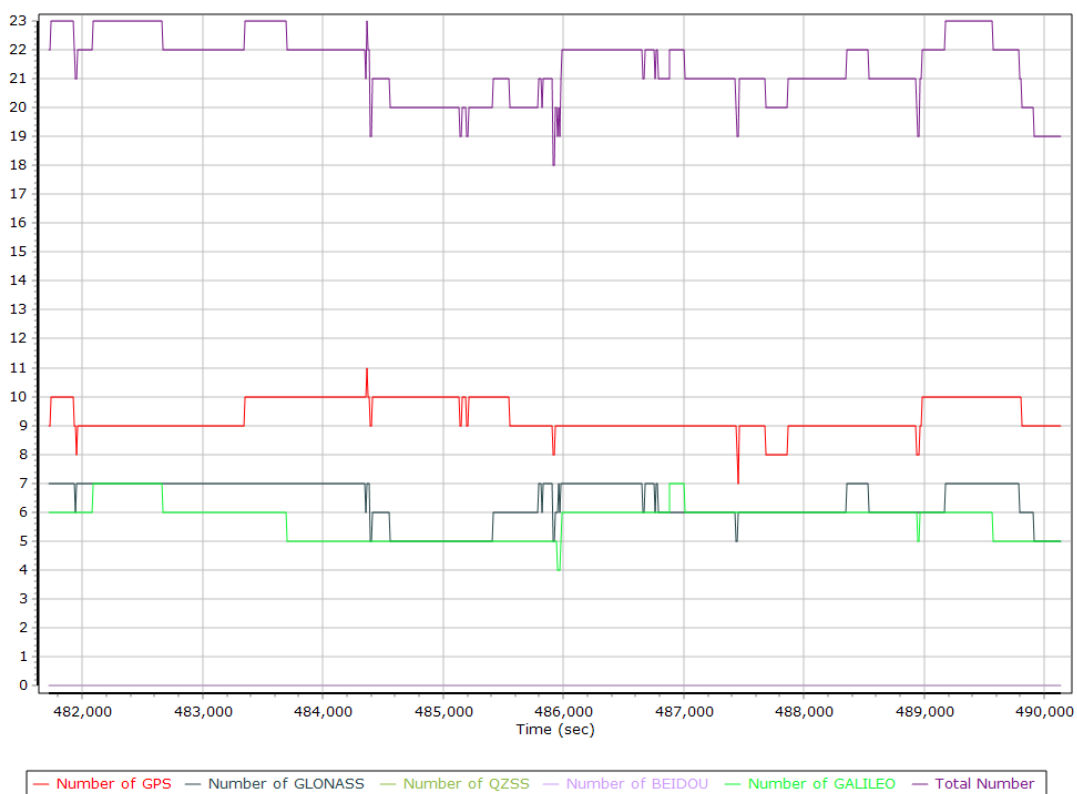


## GNSS QC

### GNSS QC Statistics

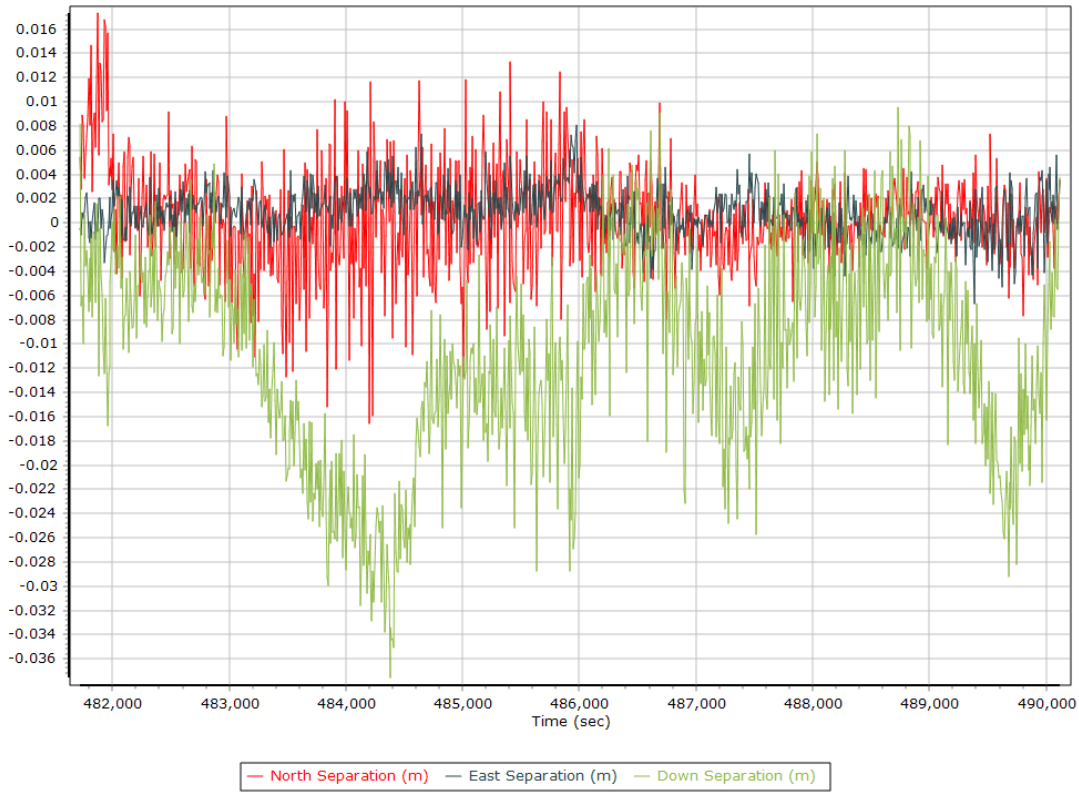
Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	7	11	9
Number of GLONASS SV	0	7	6
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	0	0
Number of GALILEO SV	4	7	6
Total number of SV	15	23	21
PDOP	0.95	1.38	1.10
QC Solution Gaps	0.00	0.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	8585.00	0.00	0.00
Percentage	100.00	0.00	0.00

### Num SVs in solution

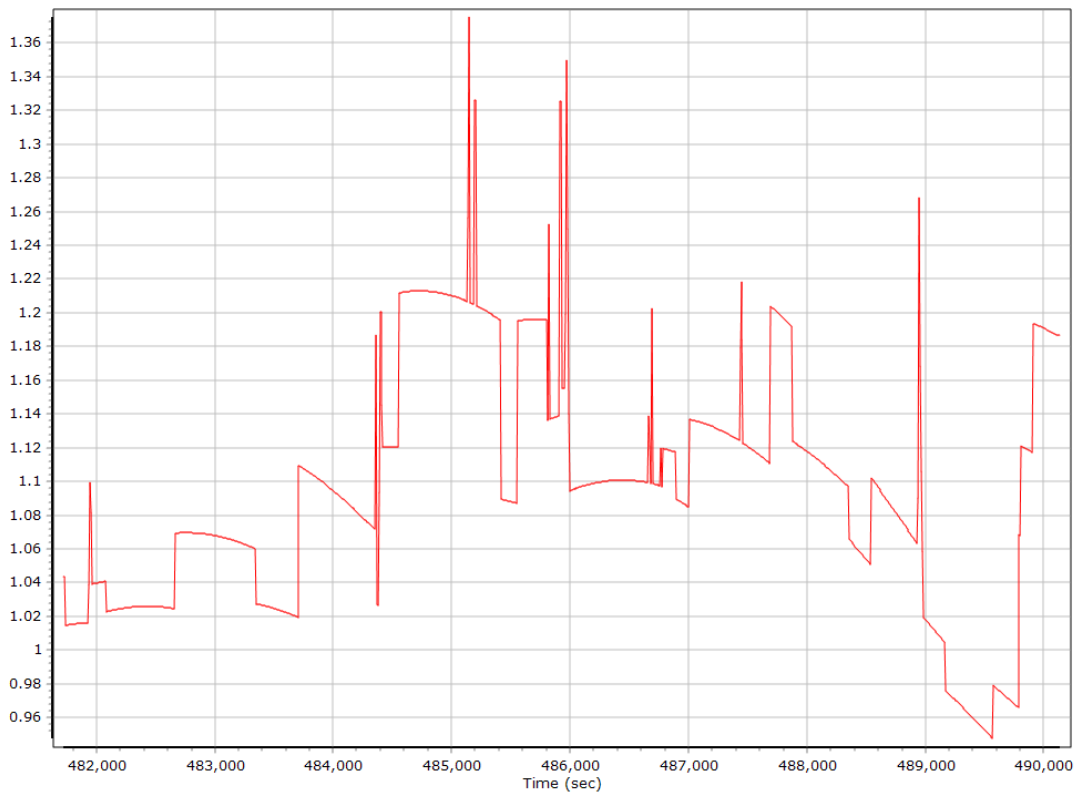




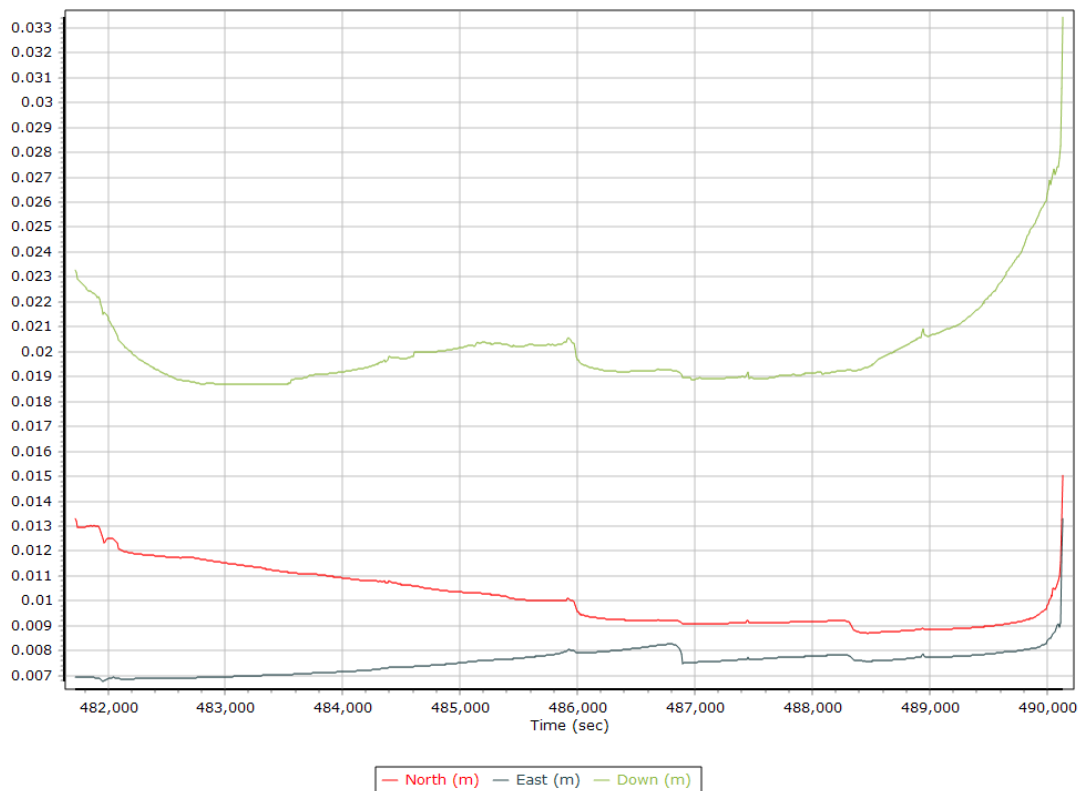
## Forward/Reverse Separation



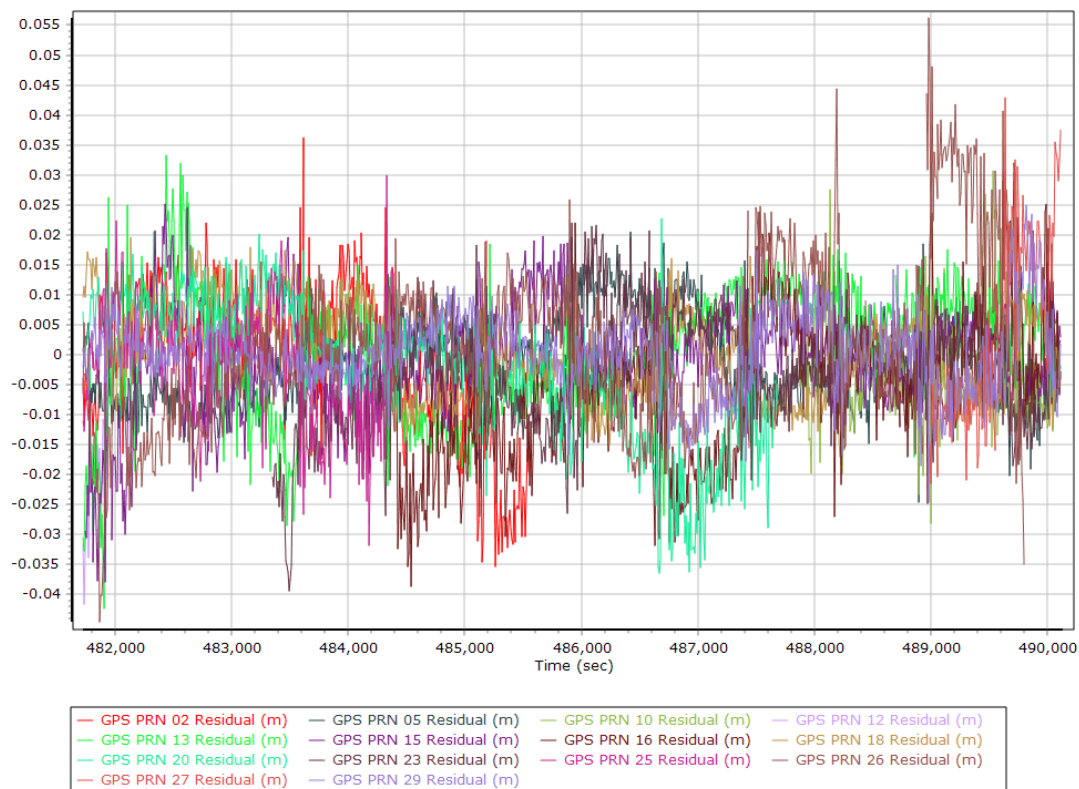
## PDOP



## Estimated Position Accuracy

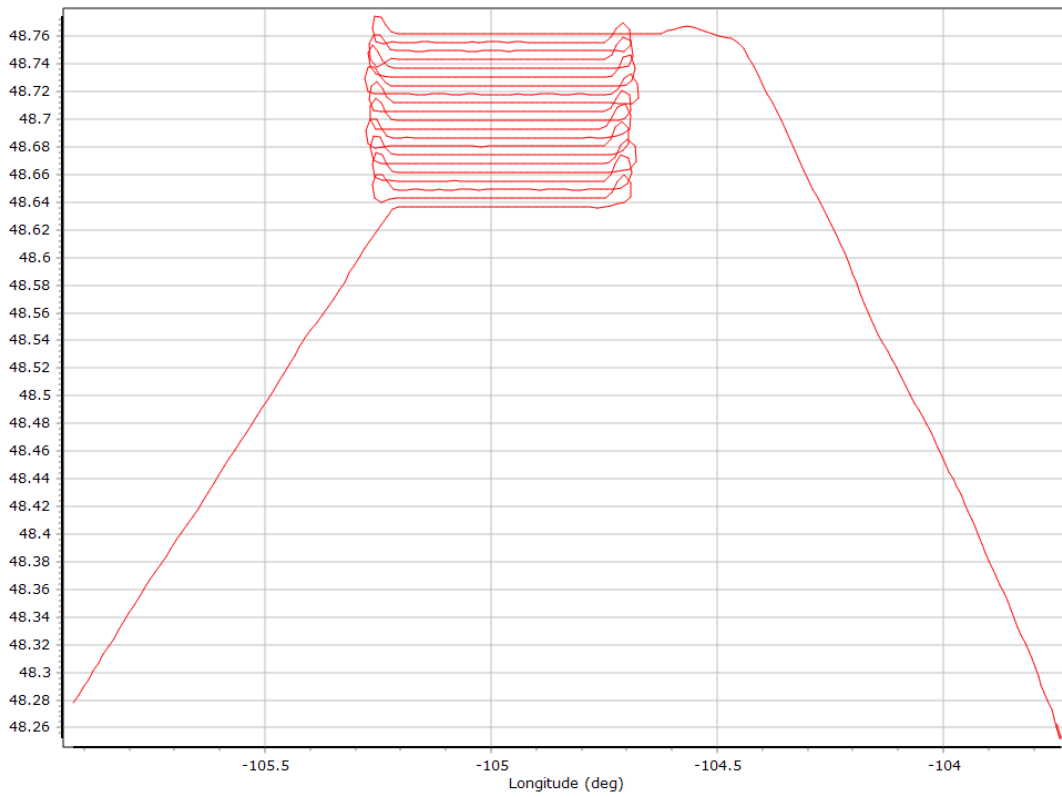


## GPS Residuals

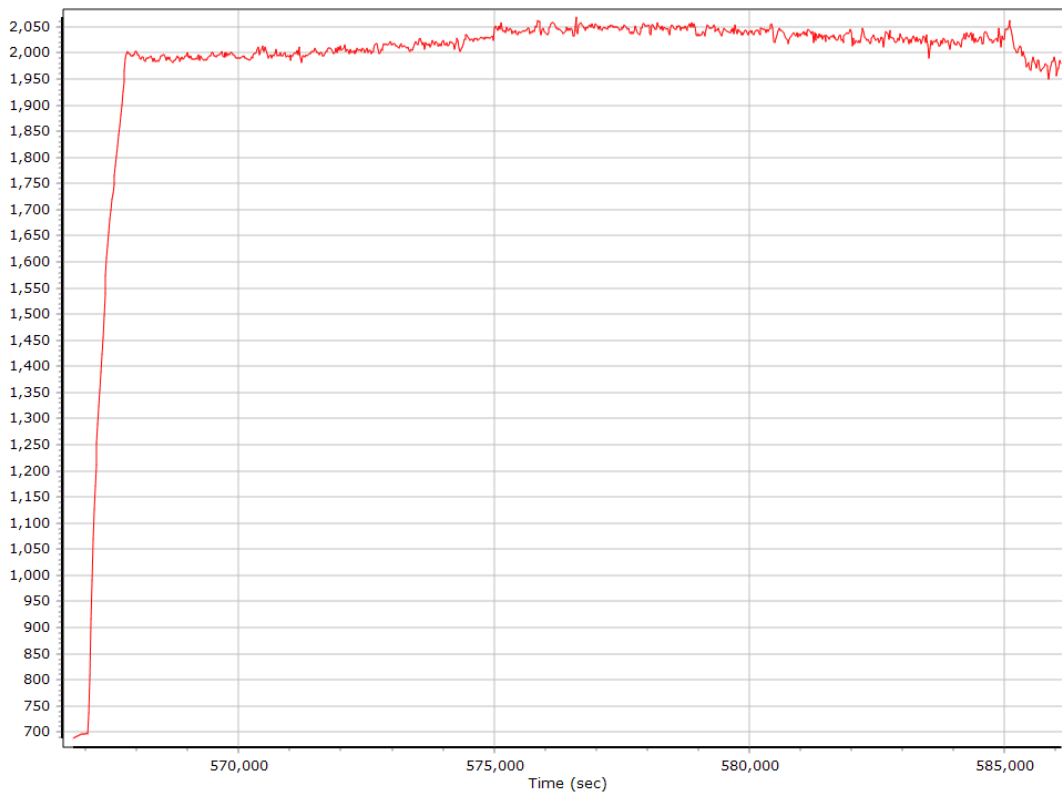


## Smoothed Trajectory Information

### Top View



### Altitude

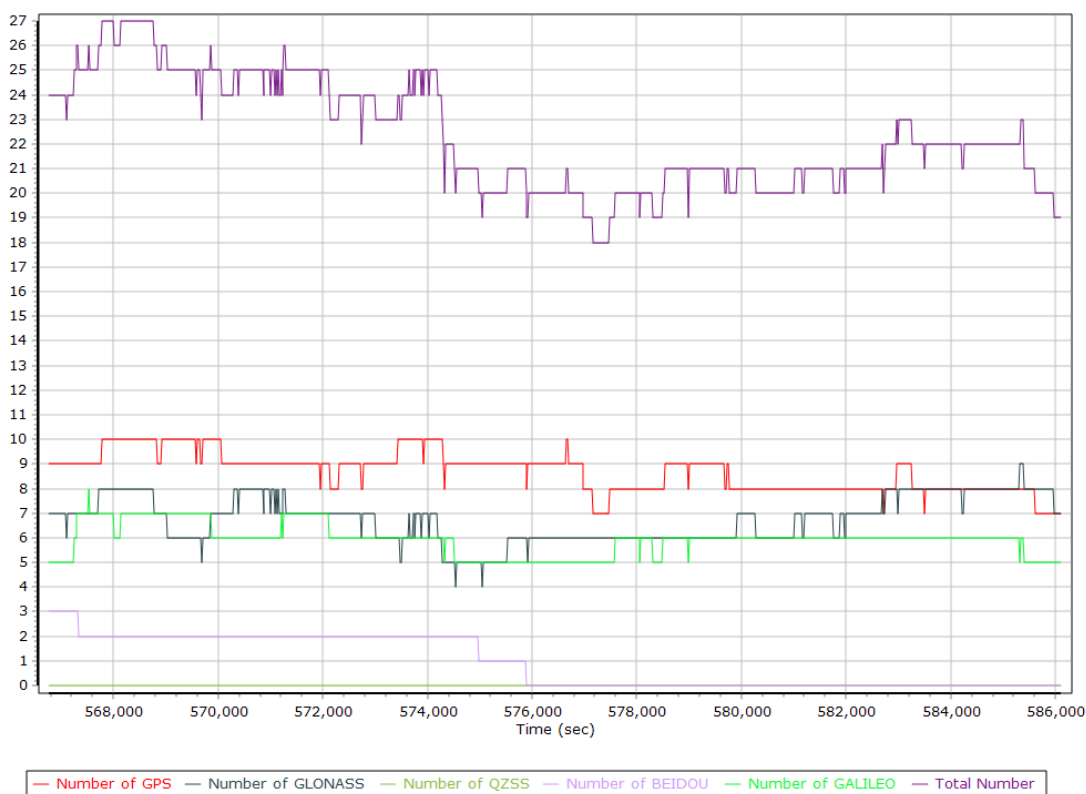


## GNSS QC

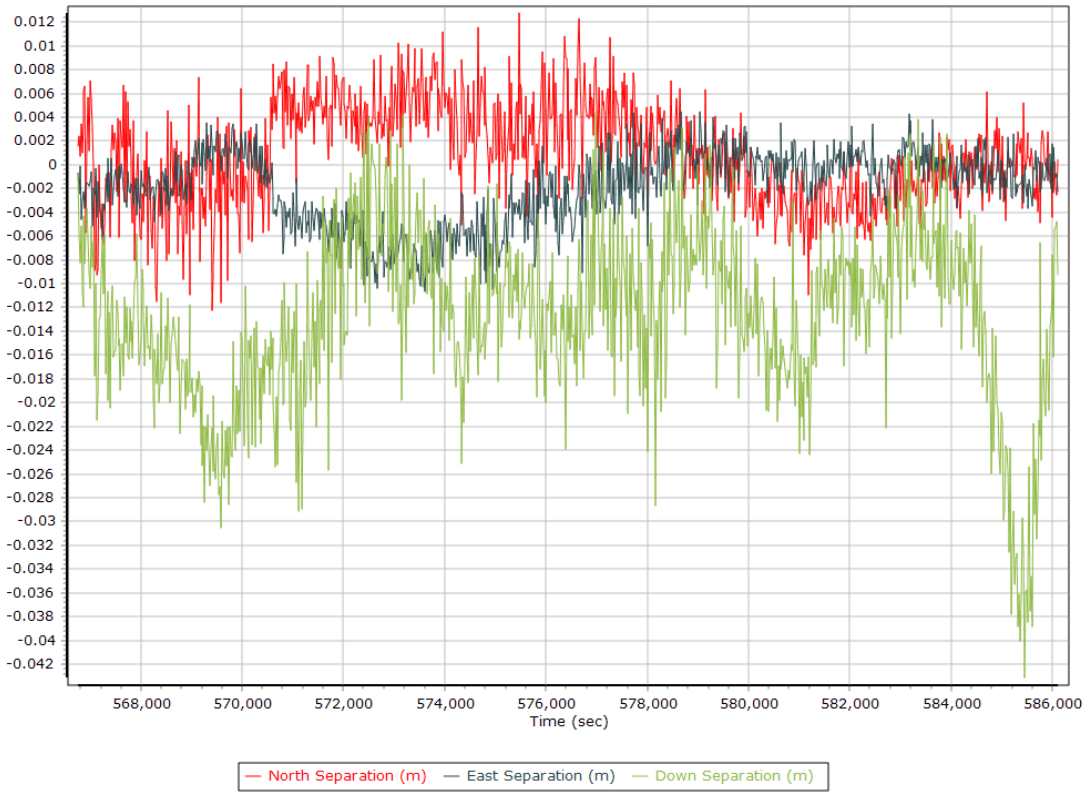
### GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	7	10	9
Number of GLONASS SV	0	9	7
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	3	1
Number of GALILEO SV	5	8	6
Total number of SV	14	27	22
PDOP	0.91	1.59	1.09
QC Solution Gaps	0.00	0.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	19621.00	0.00	0.00
Percentage	100.00	0.00	0.00

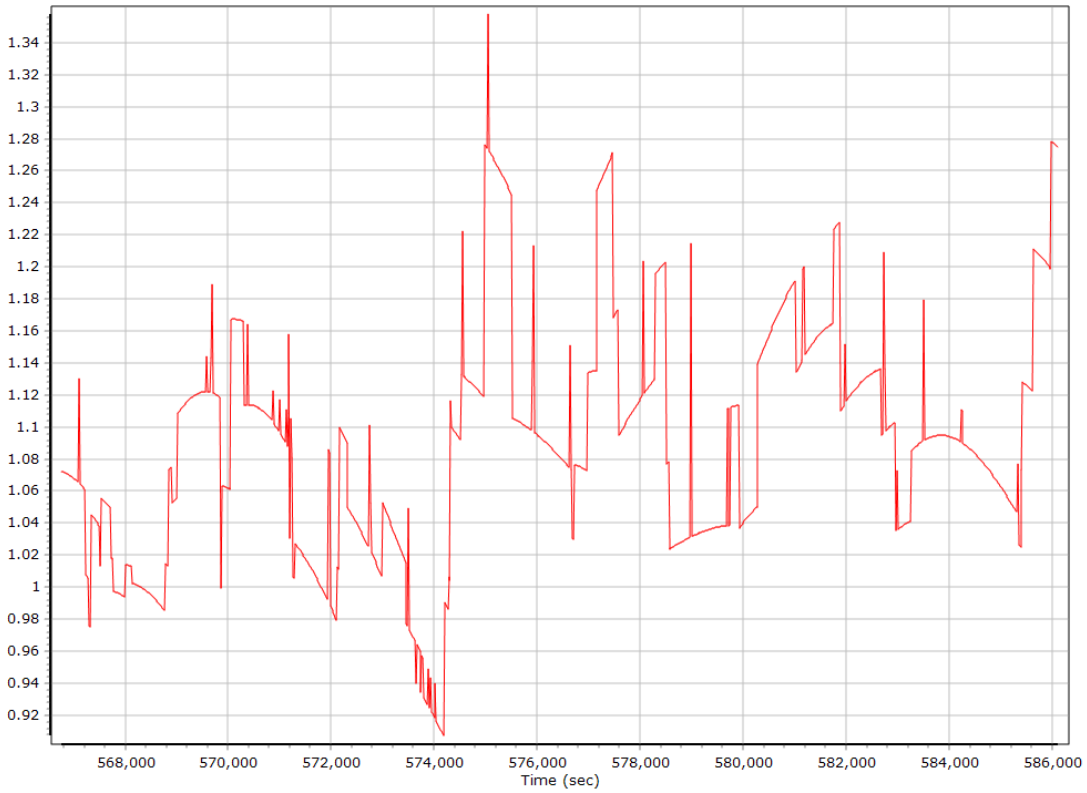
### Num SVs in solution



### Forward/Reverse Separation

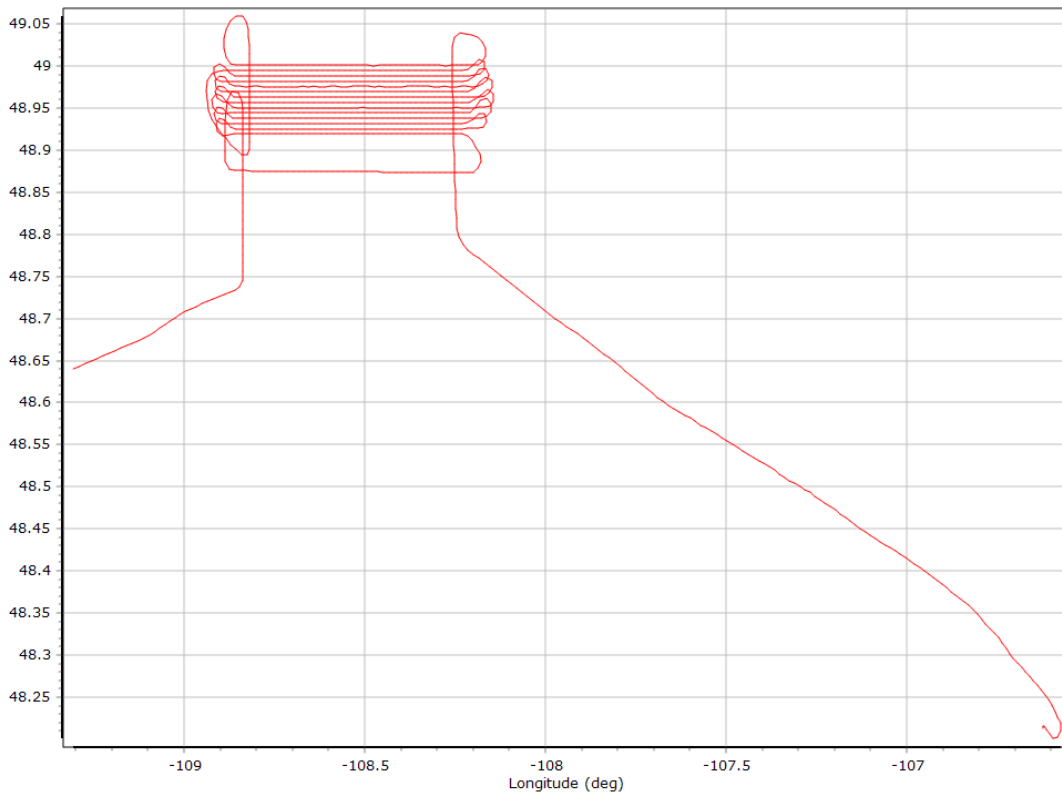


### PDOP

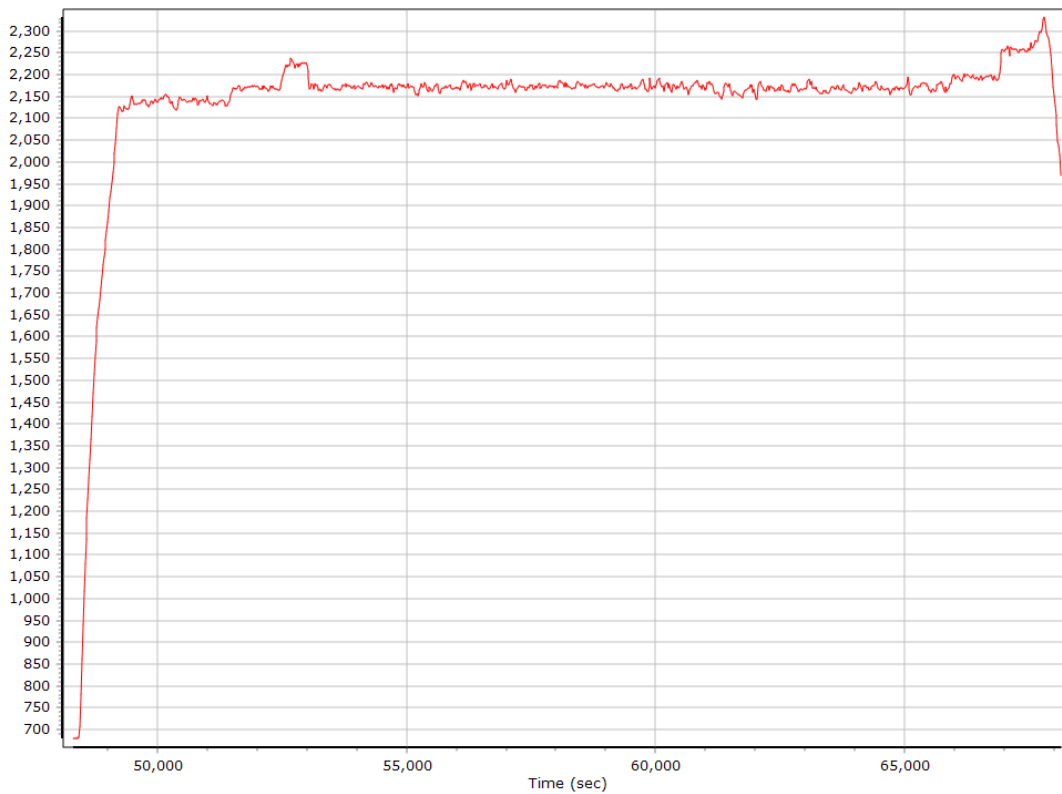


## Smoothed Trajectory Information

### Top View



### Altitude

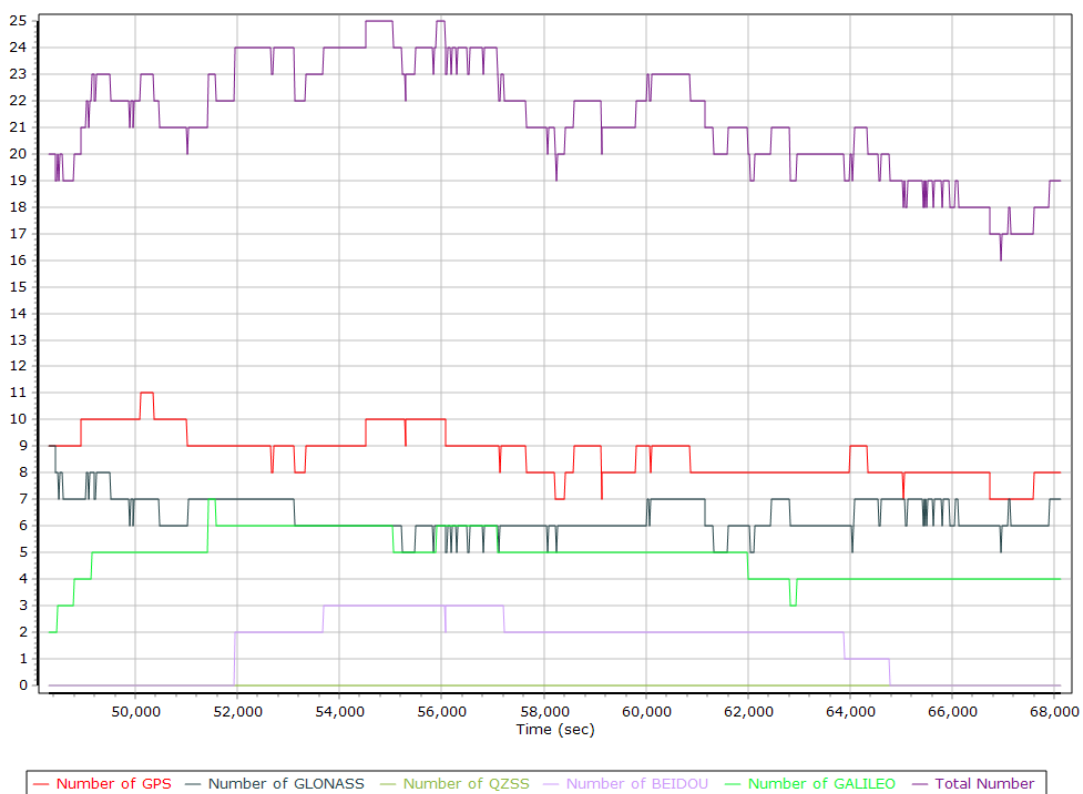


## GNSS QC

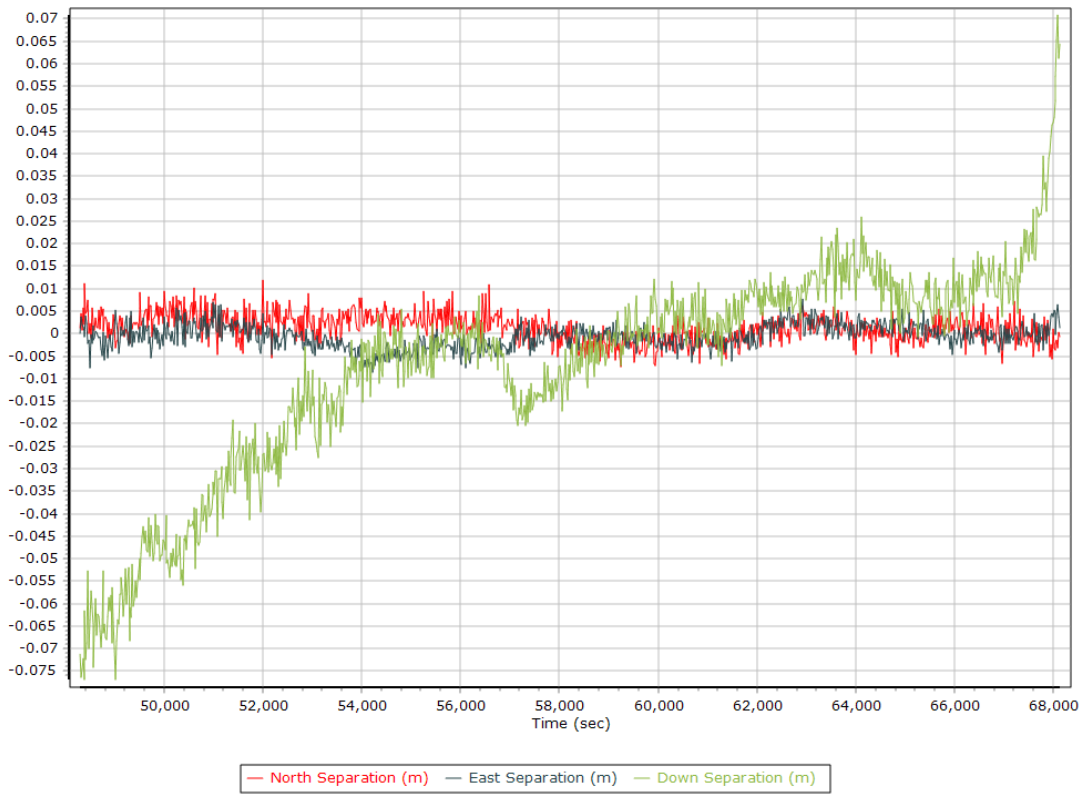
### GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	7	11	9
Number of GLONASS SV	0	9	6
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	3	1
Number of GALILEO SV	0	7	5
Total number of SV	12	25	21
PDOP	0.96	1.70	1.13
QC Solution Gaps	1.00	1.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	20304.00	0.00	4.00
Percentage	99.98	0.00	0.02

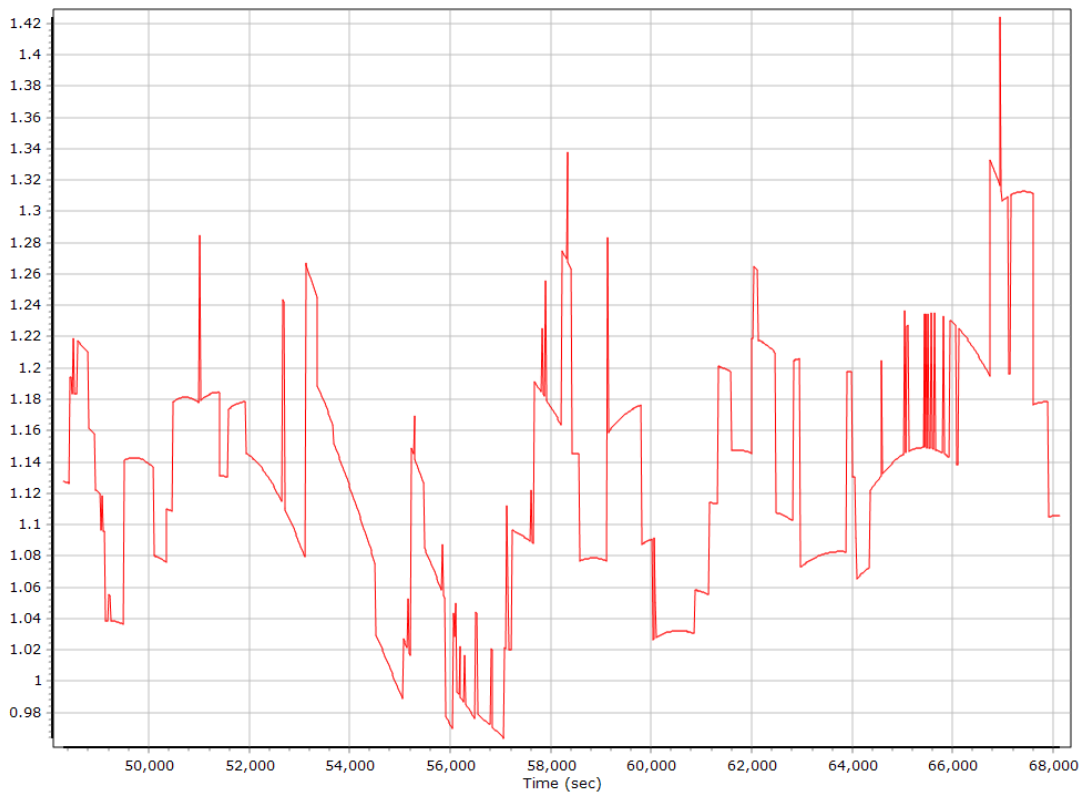
### Num SVs in solution



## Forward/Reverse Separation



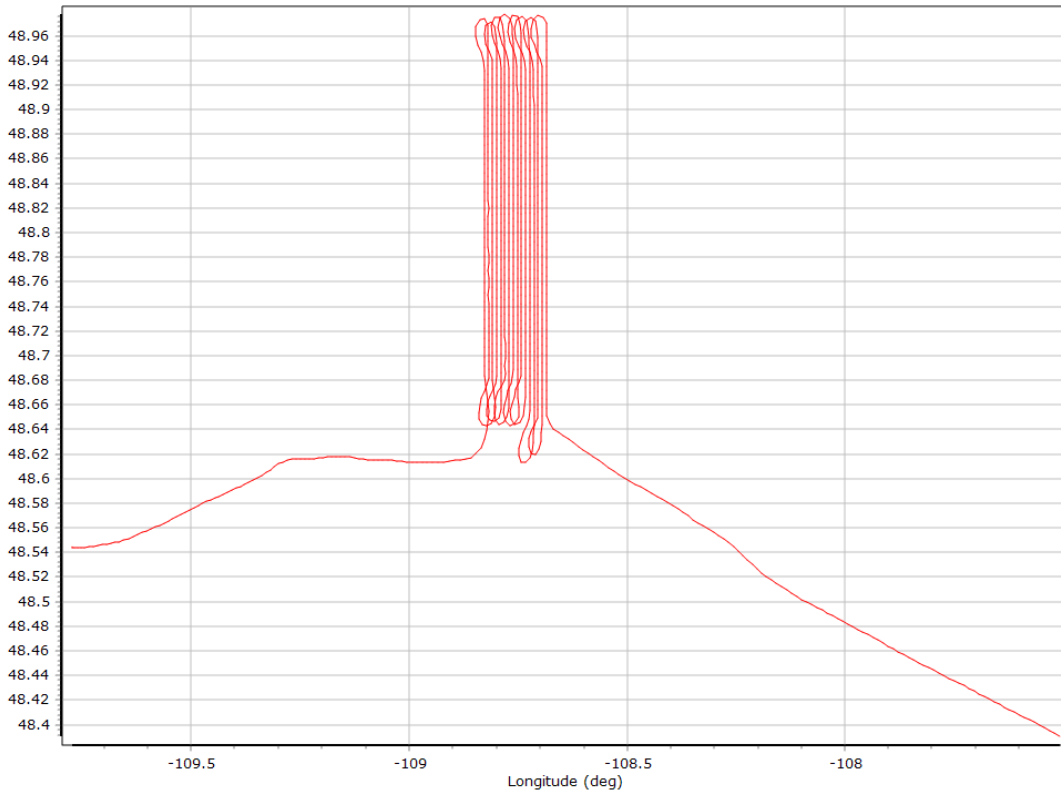
## PDOP



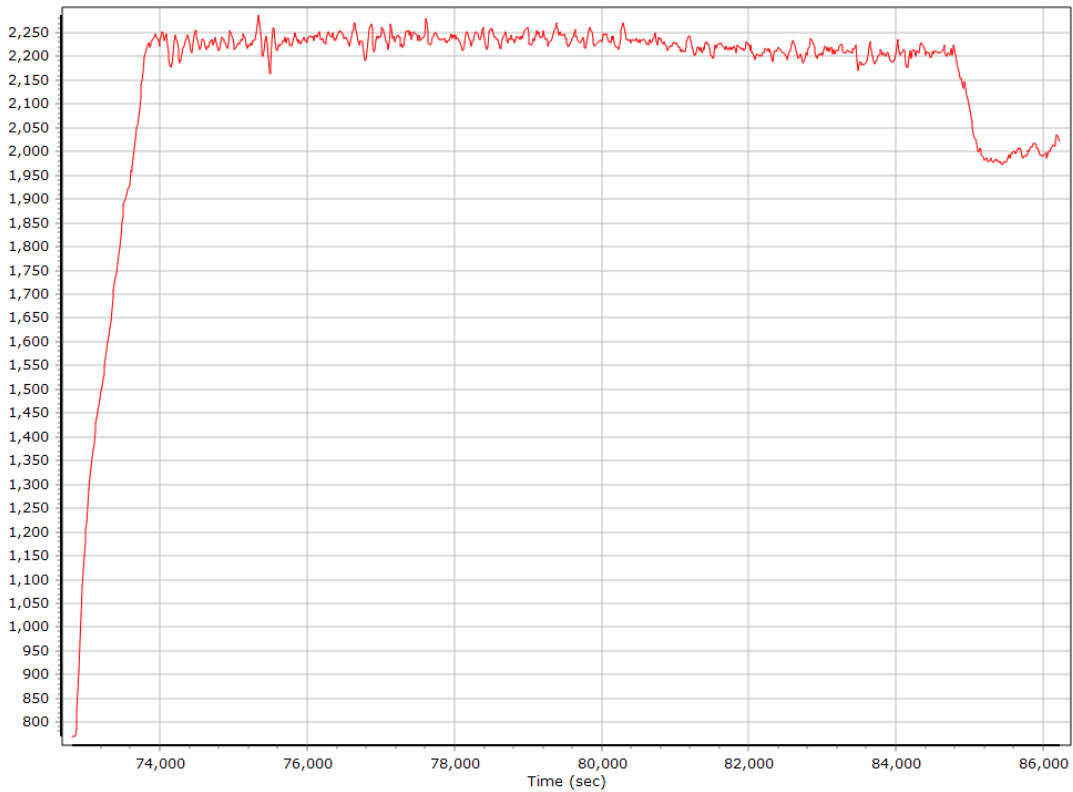


## Smoothed Trajectory Information

### Top View



### Altitude

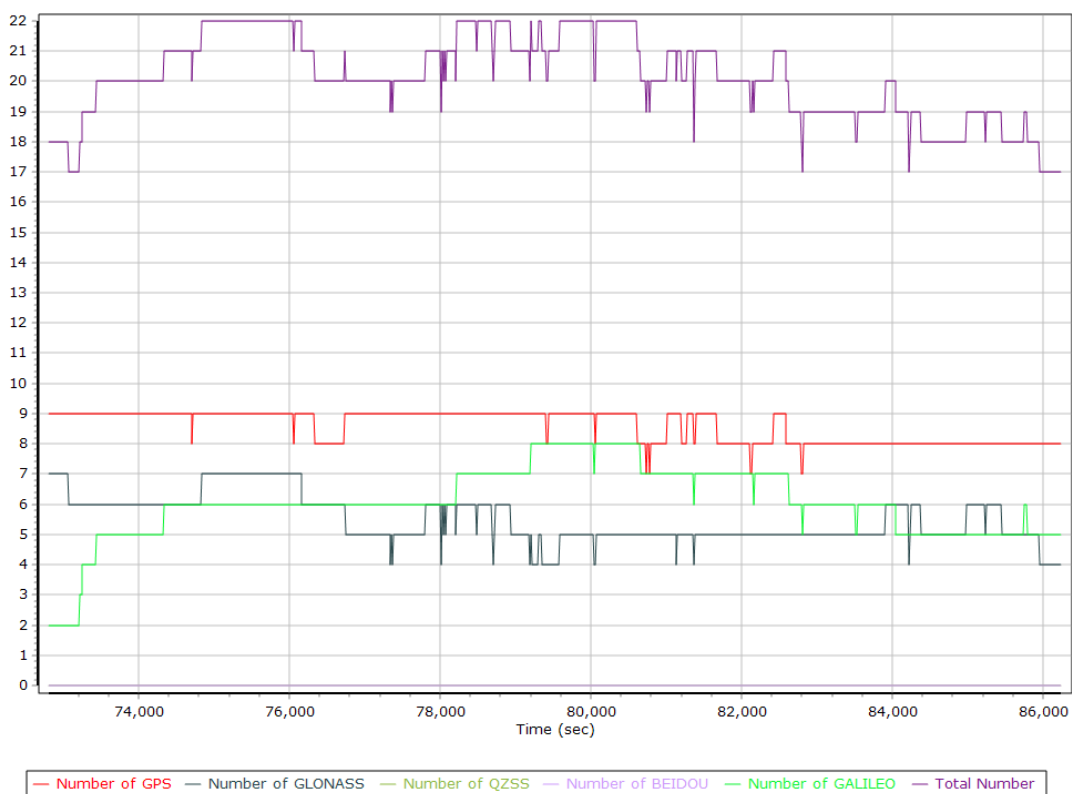


## GNSS QC

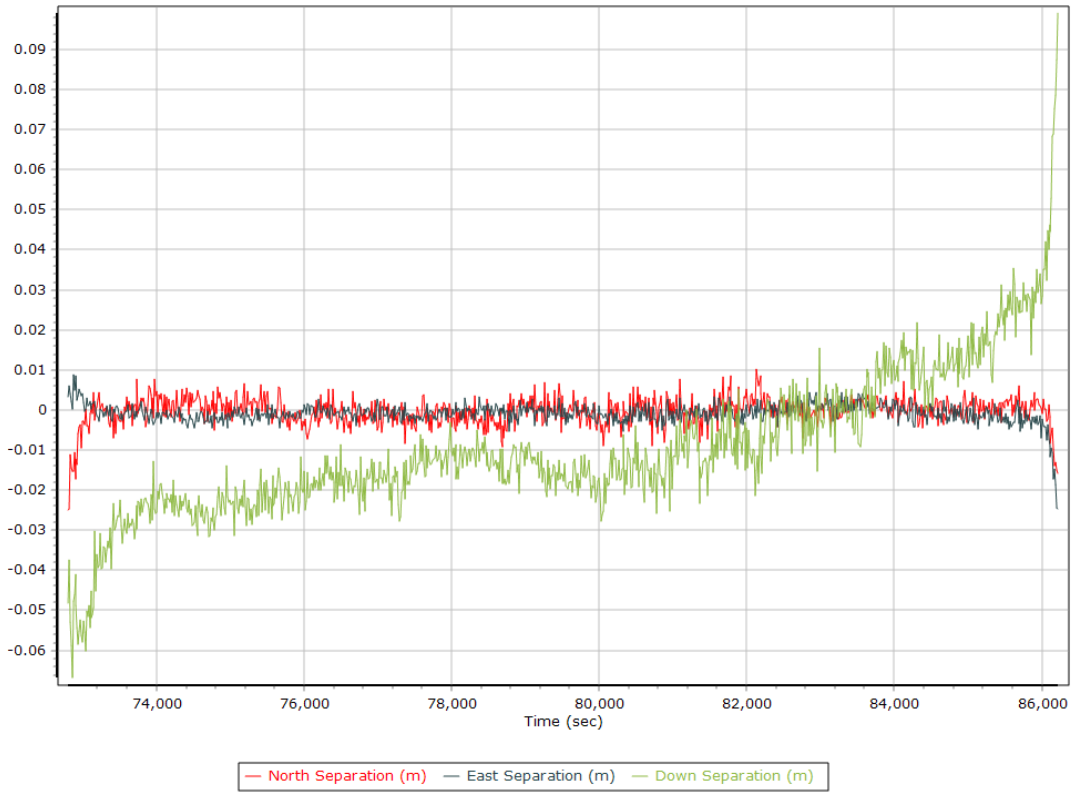
### GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	6	9	9
Number of GLONASS SV	0	7	6
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	0	0
Number of GALILEO SV	2	8	6
Total number of SV	11	22	20
PDOP	0.98	1.92	1.25
QC Solution Gaps	0.00	0.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	13705.00	0.00	0.00
Percentage	100.00	0.00	0.00

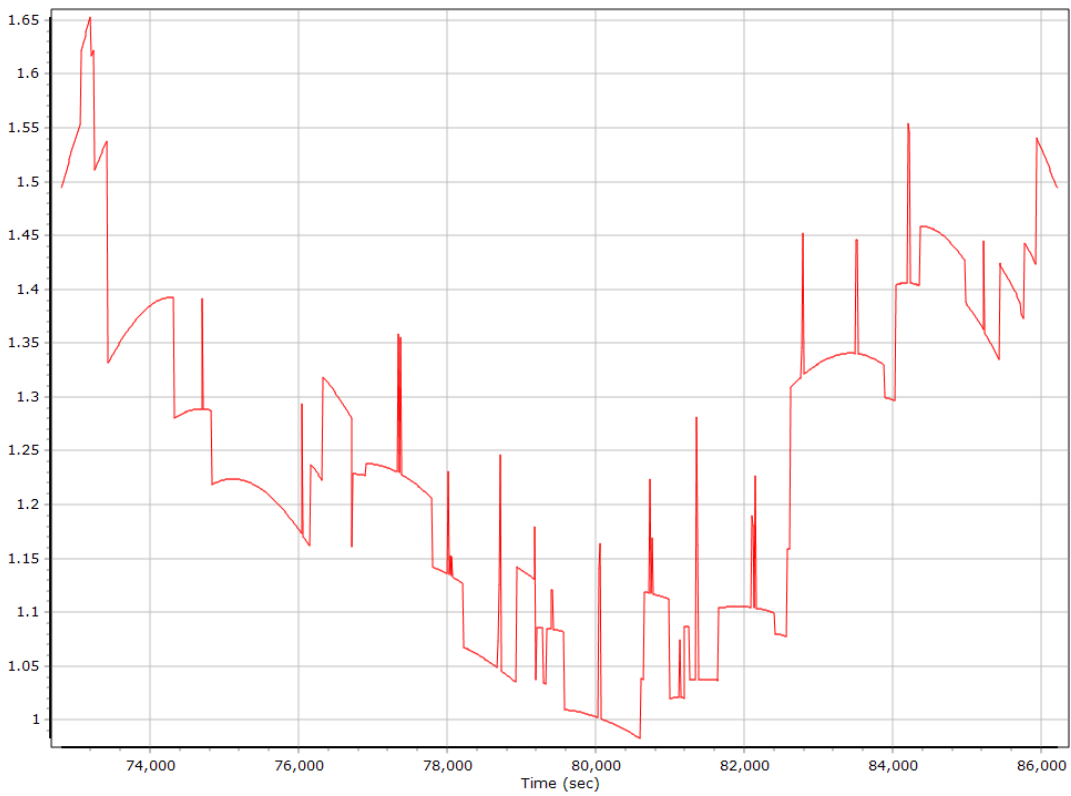
### Num SVs in solution



## Forward/Reverse Separation

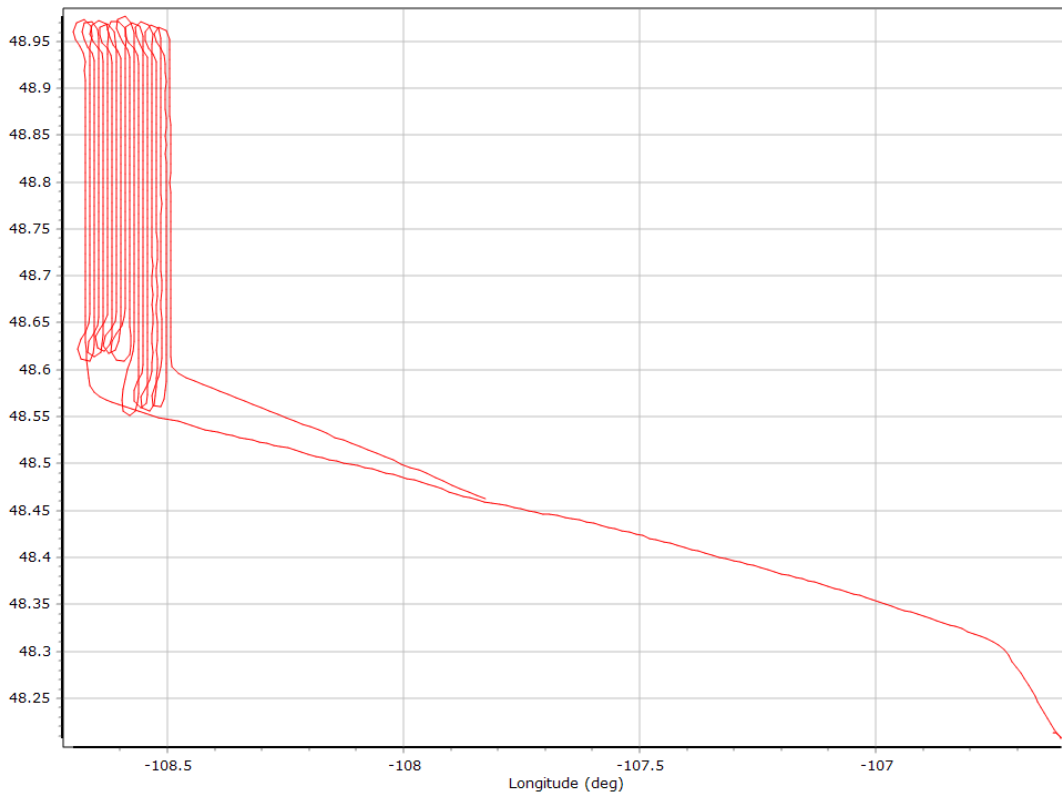


## PDOP

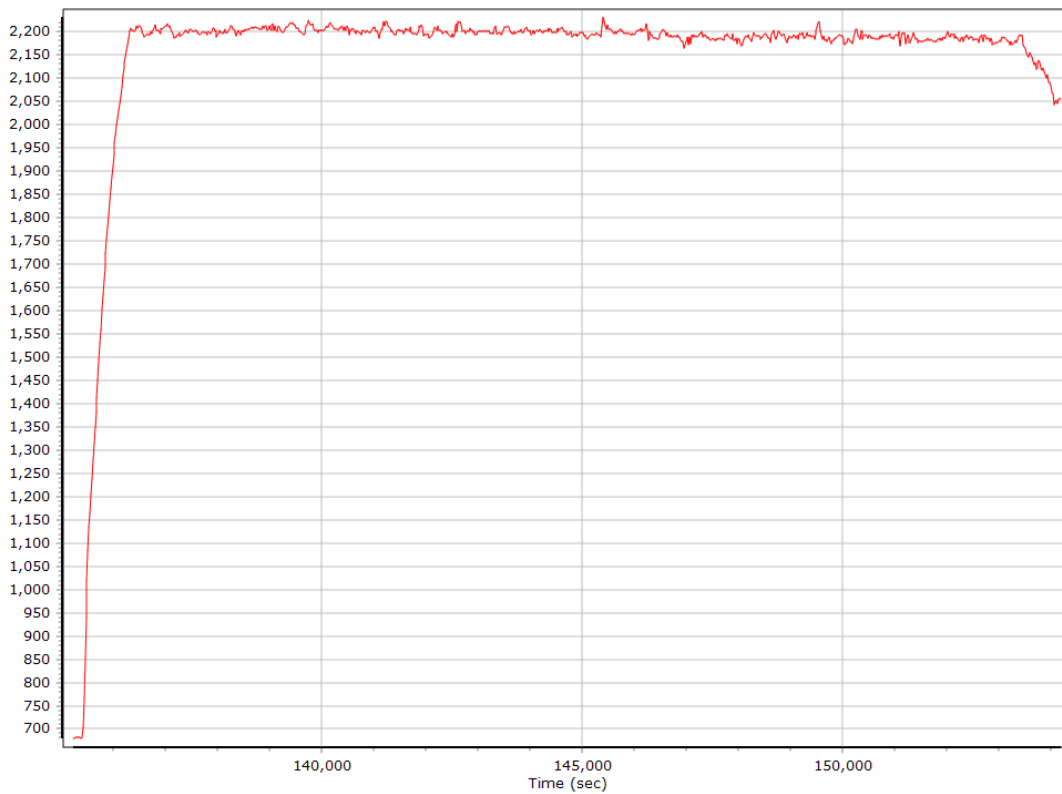


## Smoothed Trajectory Information

### Top View



### Altitude

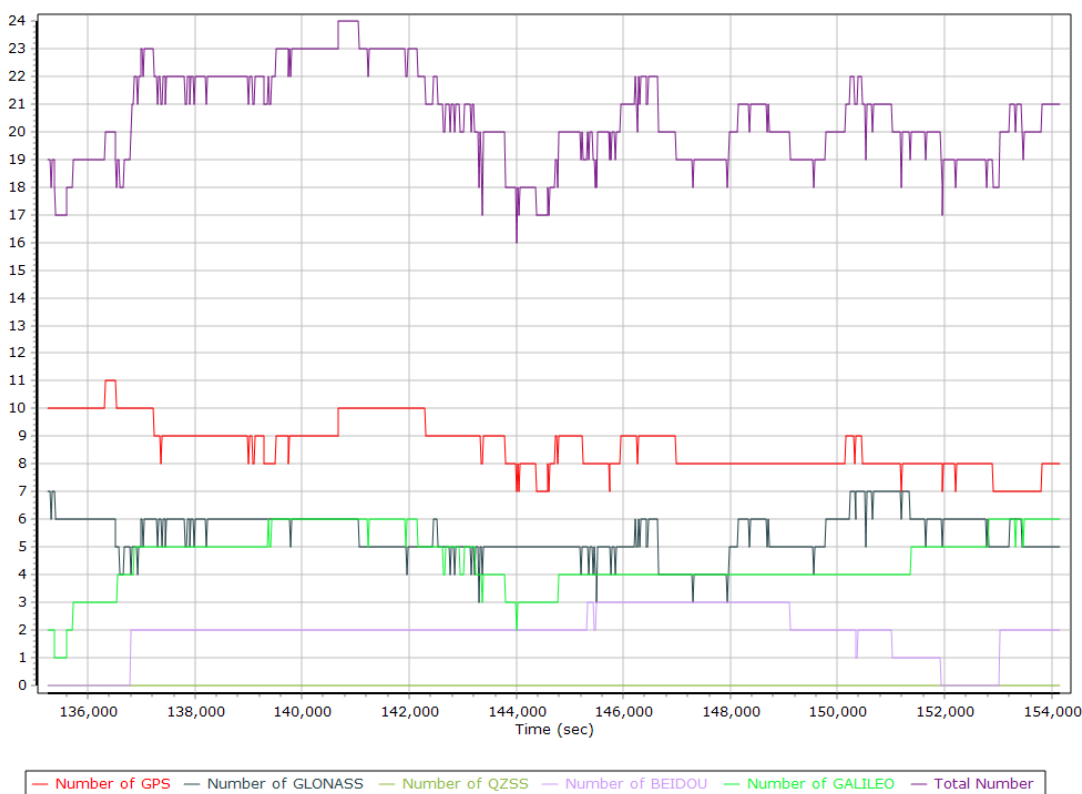


## GNSS QC

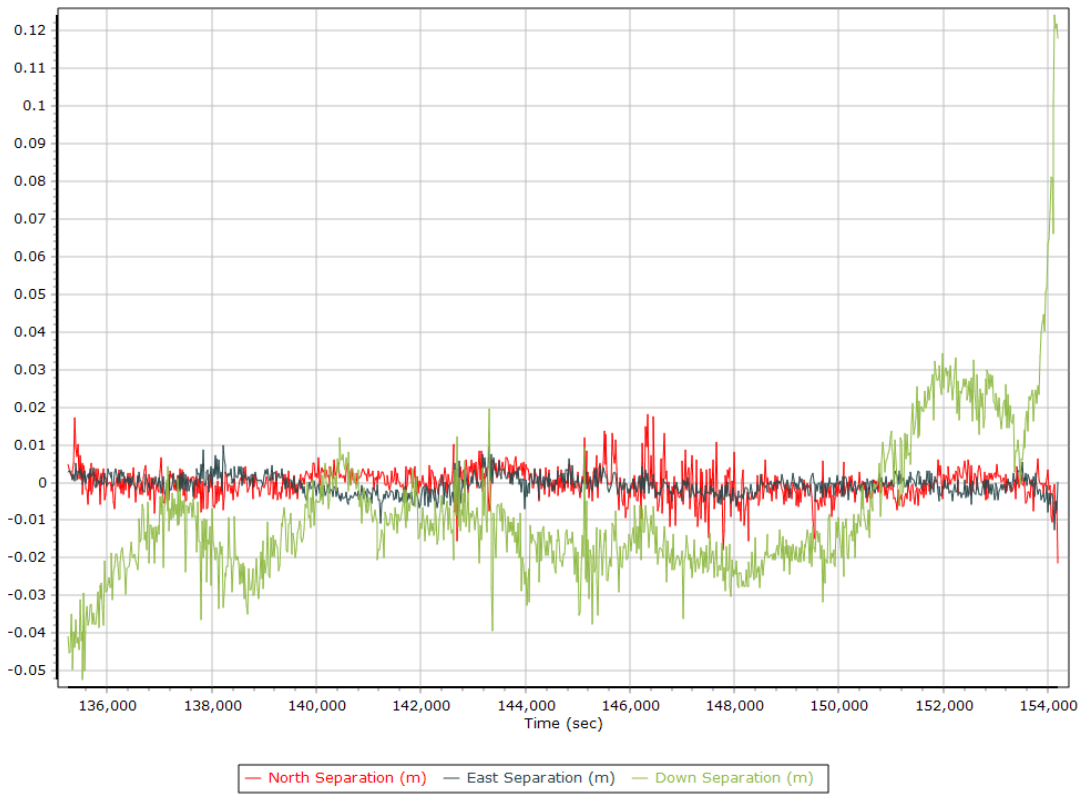
### GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	4	11	9
Number of GLONASS SV	0	7	5
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	3	2
Number of GALILEO SV	0	6	4
Total number of SV	11	24	20
PDOP	0.97	2.66	1.18
QC Solution Gaps	0.00	0.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	19280.00	0.00	0.00
Percentage	100.00	0.00	0.00

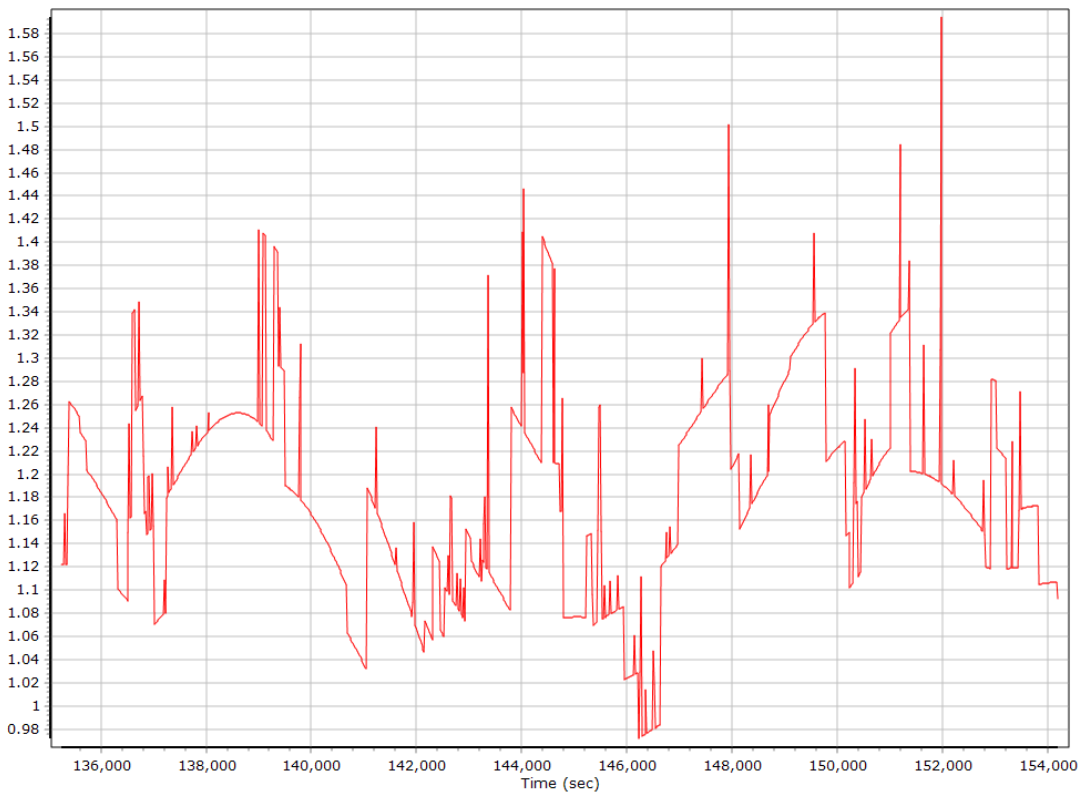
### Num SVs in solution



## Forward/Reverse Separation

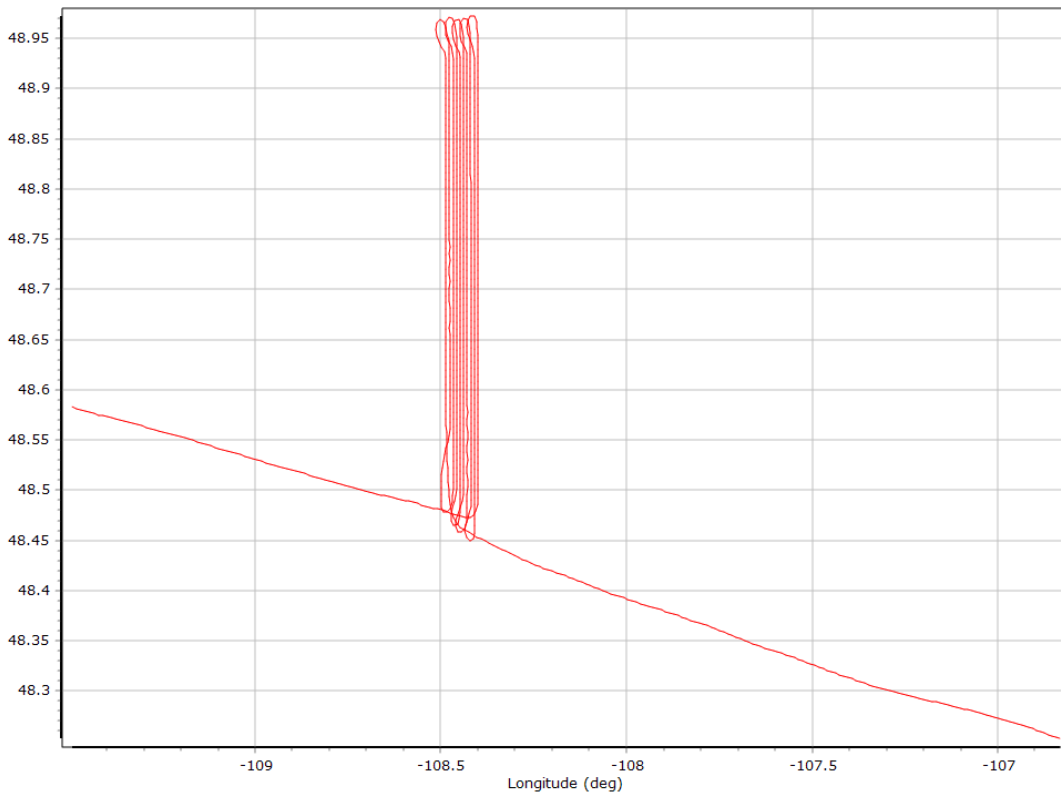


## PDOP

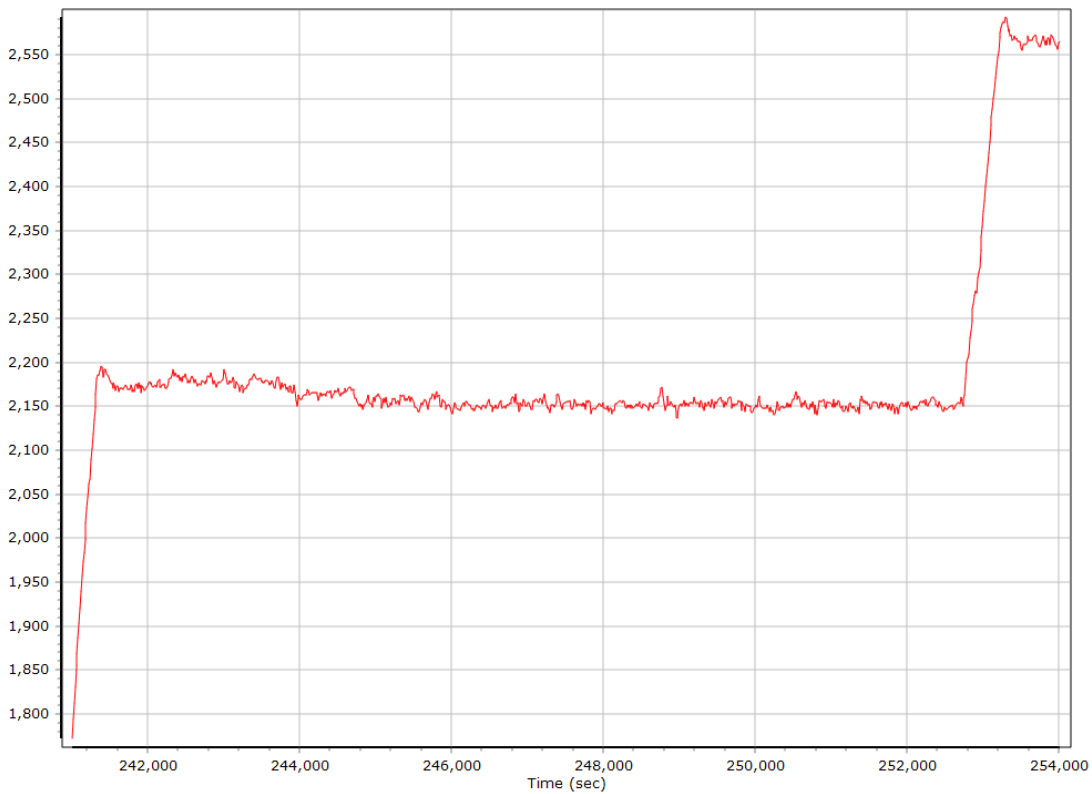


## Smoothed Trajectory Information

### Top View



### Altitude

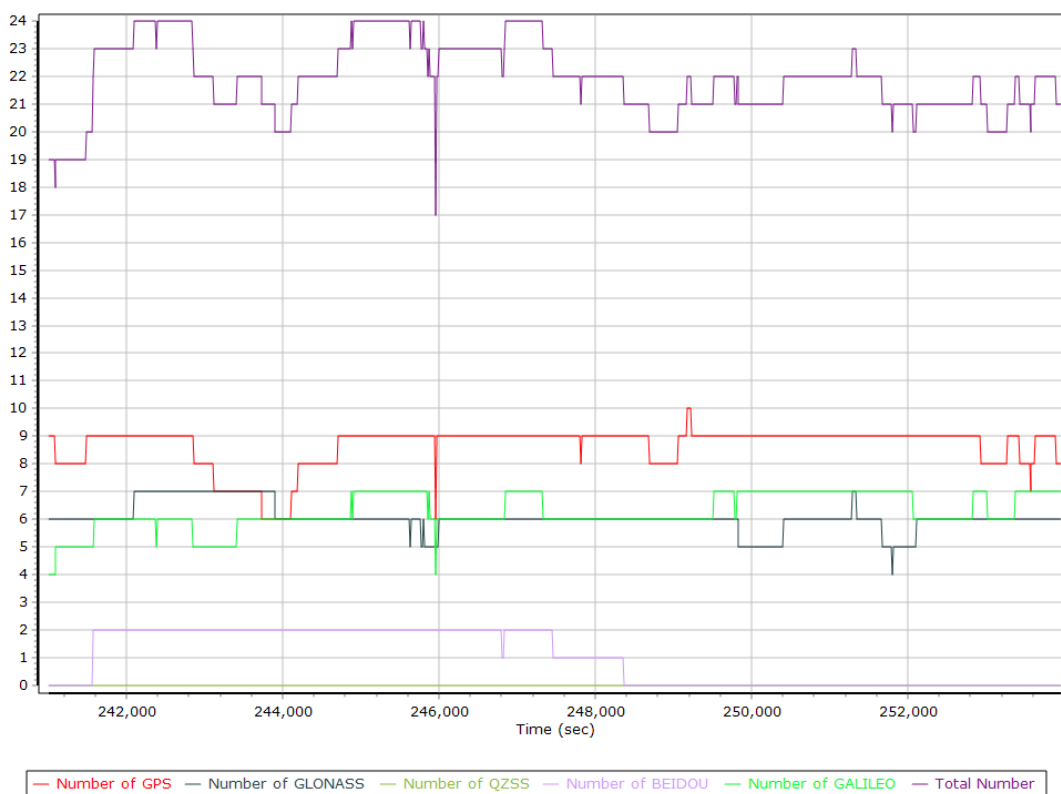


## GNSS QC

### GNSS QC Statistics

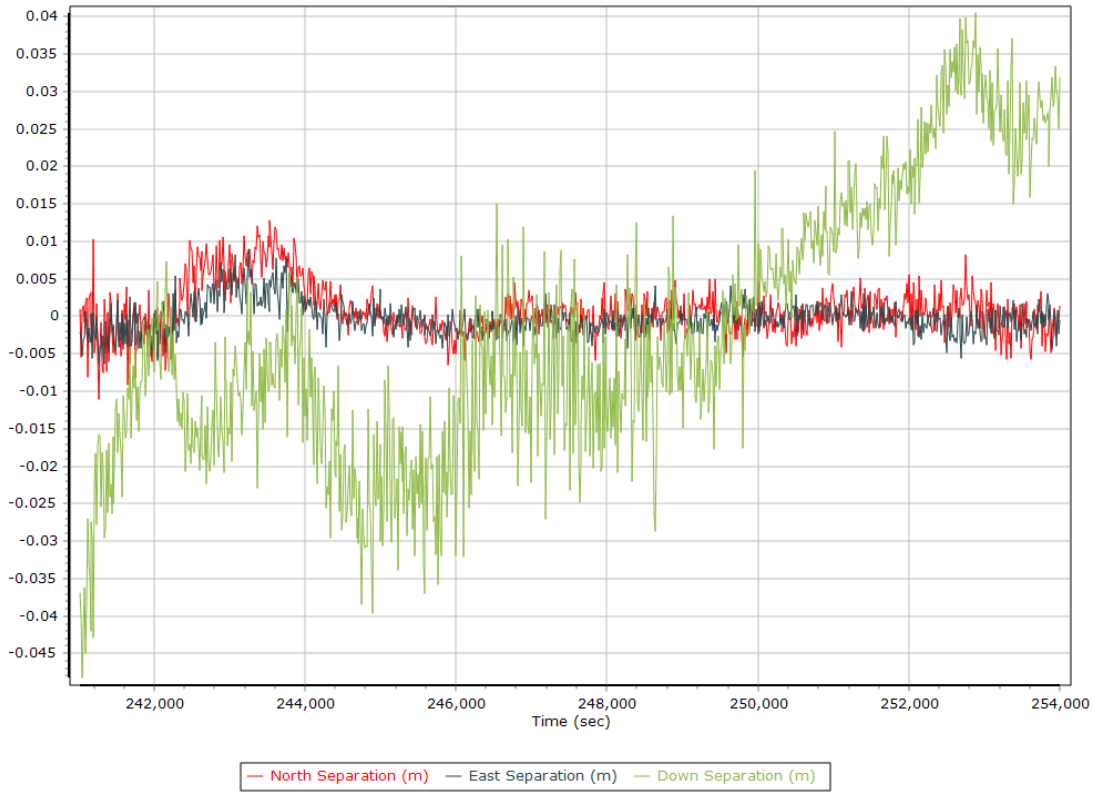
Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	6	10	9
Number of GLONASS SV	4	7	6
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	2	1
Number of GALILEO SV	4	7	6
Total number of SV	17	24	22
PDOP	0.97	2.04	1.18
QC Solution Gaps	0.00	0.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	13136.00	0.00	0.00
Percentage	100.00	0.00	0.00

### Num SVs in solution

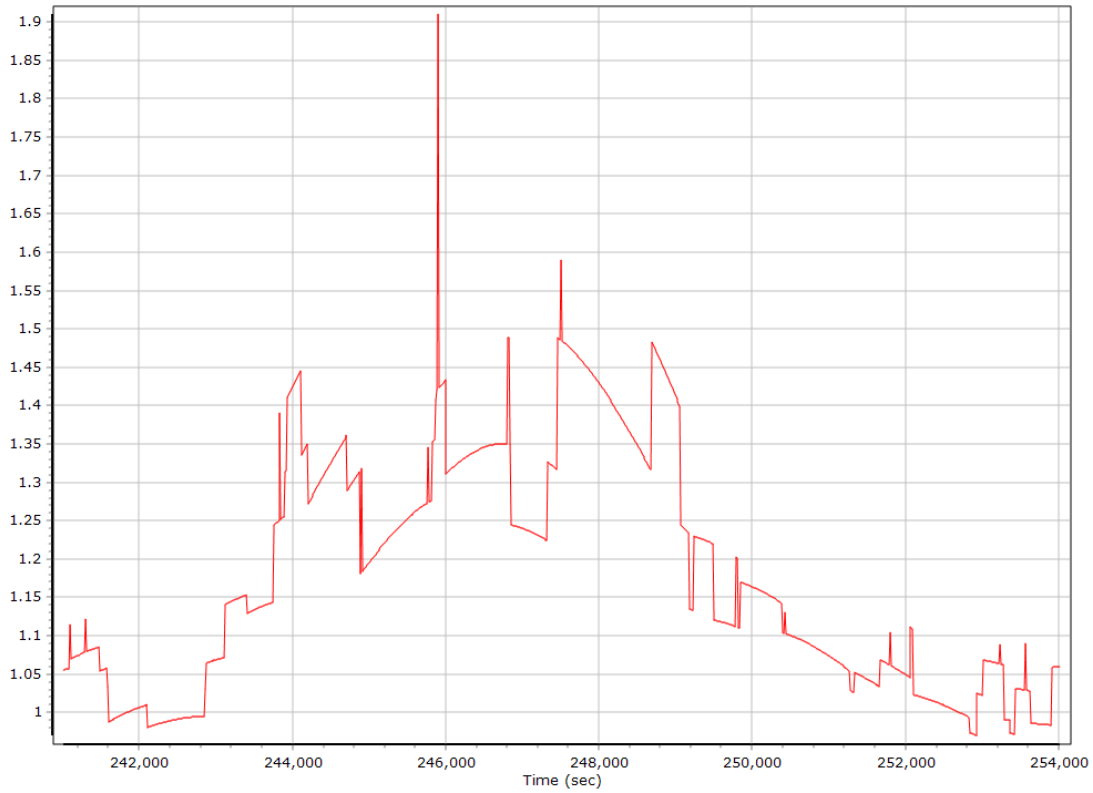




## Forward/Reverse Separation

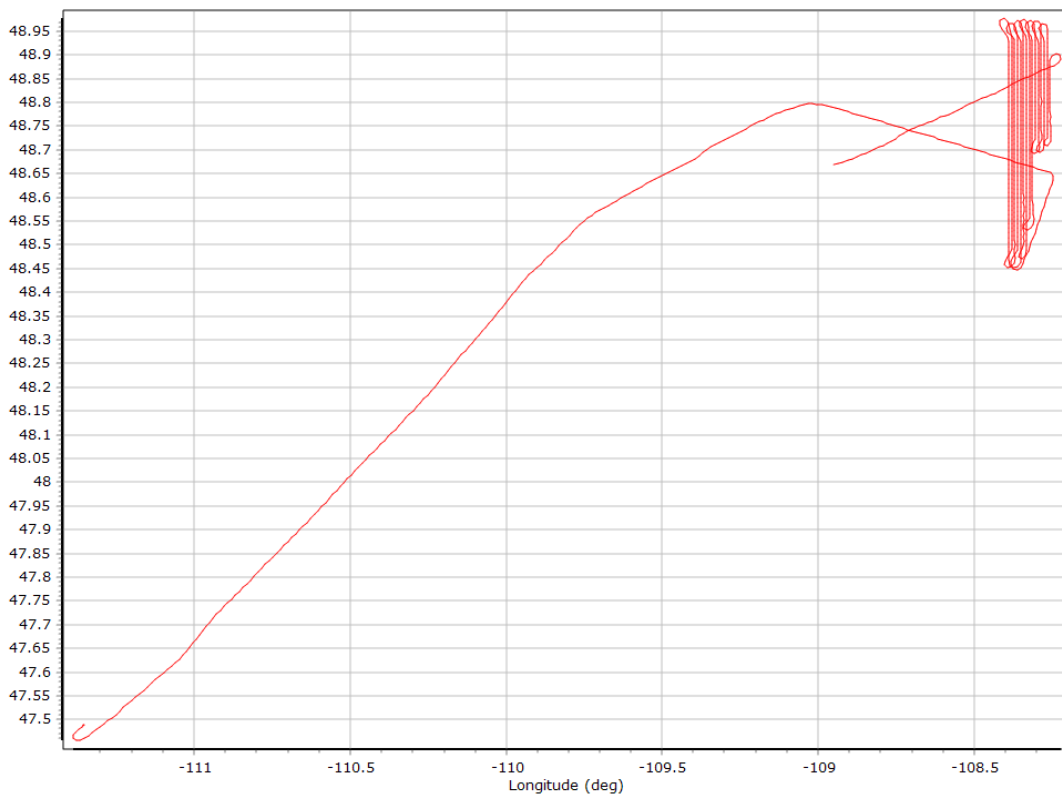


## PDOP

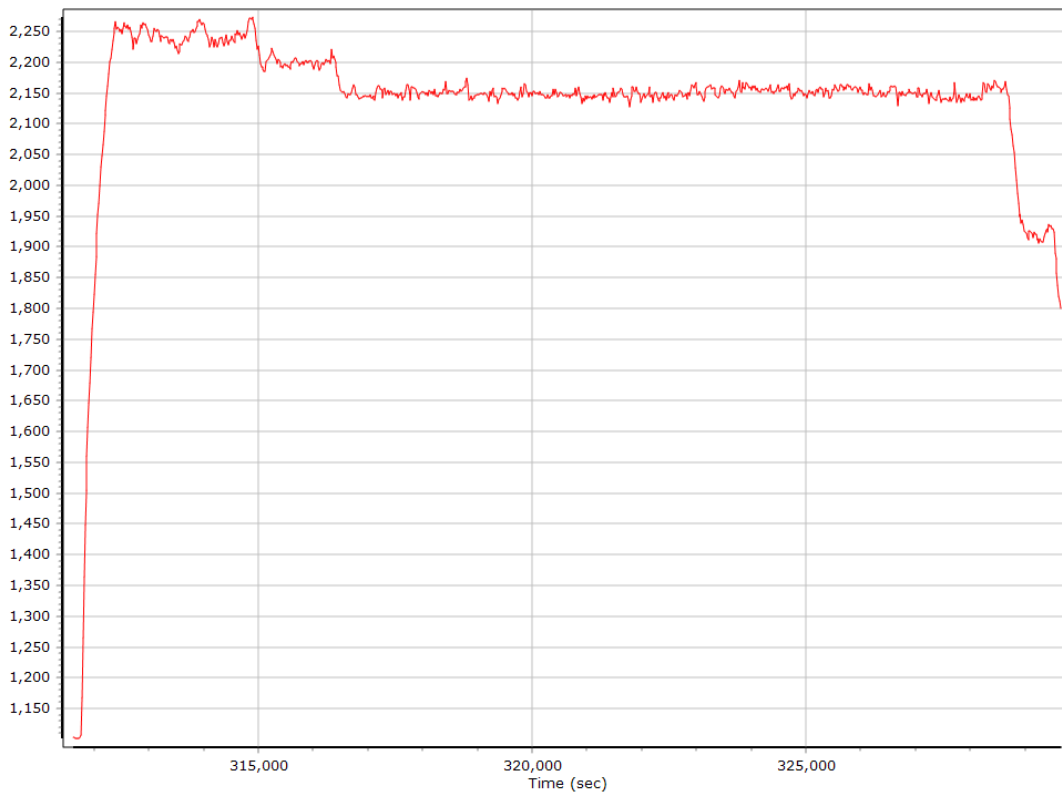


## Smoothed Trajectory Information

### Top View



### Altitude

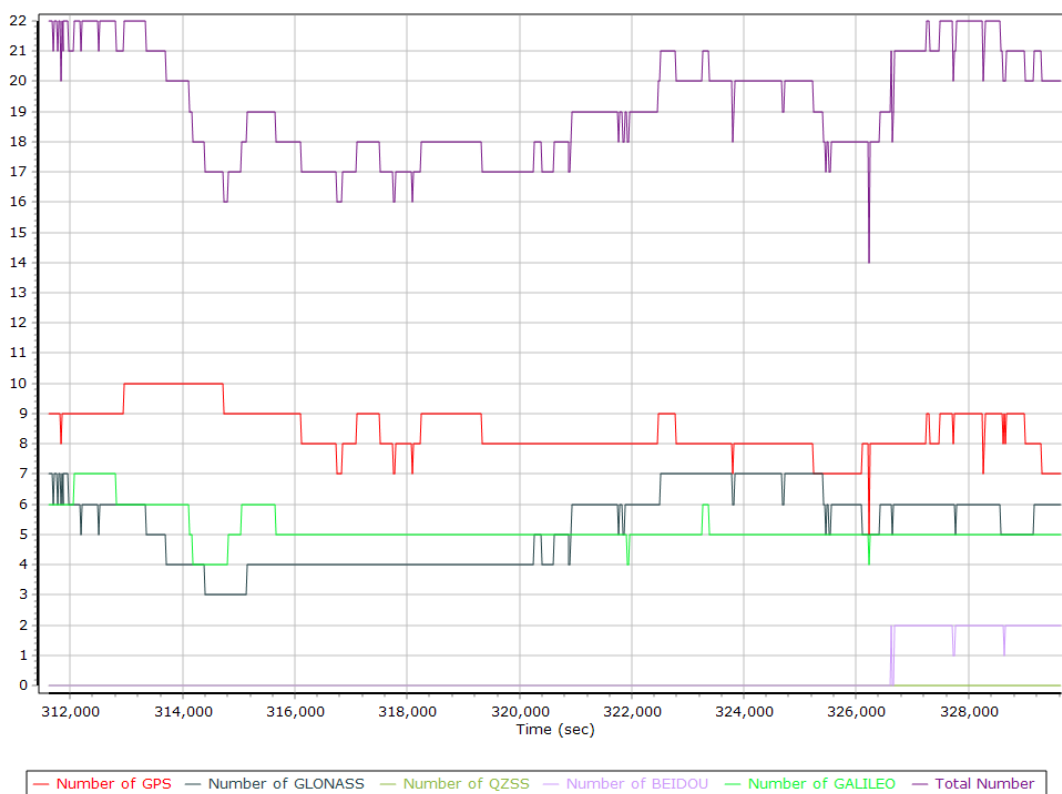


## GNSS QC

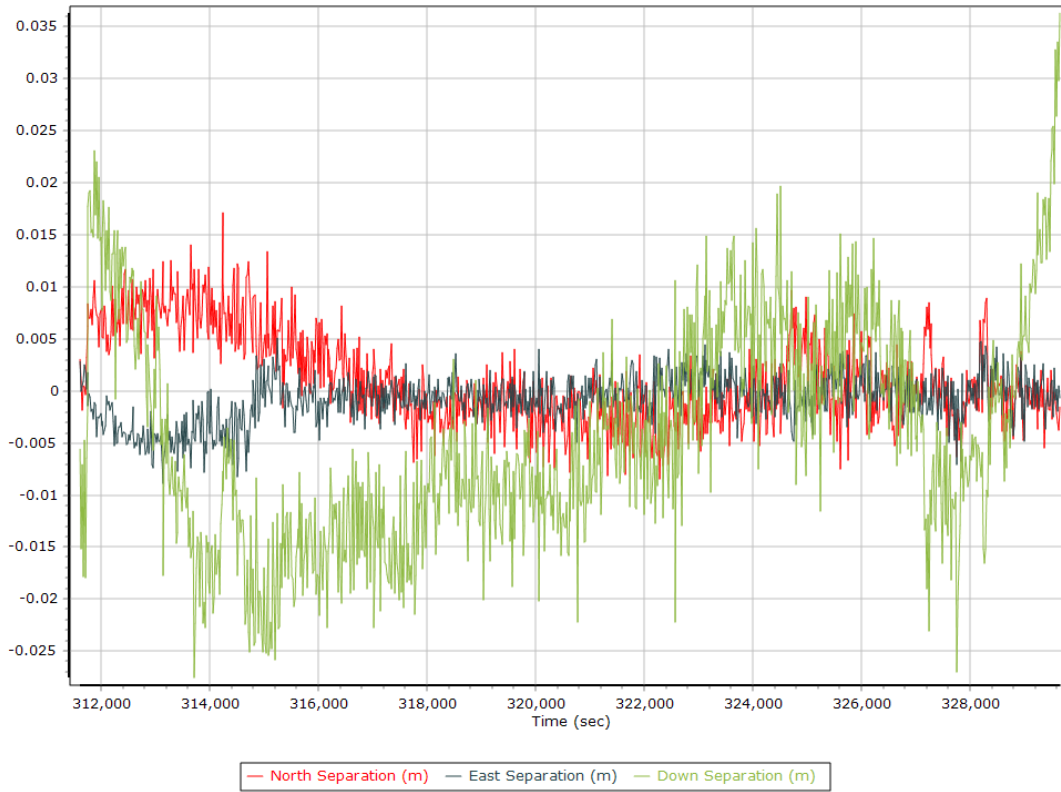
### GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	5	10	8
Number of GLONASS SV	0	7	5
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	2	0
Number of GALILEO SV	3	7	5
Total number of SV	14	22	19
PDOP	1.03	2.05	1.21
QC Solution Gaps	0.00	0.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	18540.00	0.00	0.00
Percentage	100.00	0.00	0.00

### Num SVs in solution



## Forward/Reverse Separation



## PDOP

