

General Information

Mission Information

Project name	11888
Processing date	2020-12-08 09:38:47
Mission date	2020-12-06 05:11:57
Mission duration	01:41:48.489
Processing mode	IN-Fusion PP-RTX

Rover Hardware Information

Product	POS AV 610 VER6 HW2.5-12
Serial number	S/N10633
IMU type	57
Receiver type	BD982
Antenna type	AV39

Project File List

Rover Data Files

File name	File type
12052020F2Nights.395	POS Data
12052020F2Nights.396	POS Data
12052020F2Nights.397	POS Data
12052020F2Nights.398	POS Data
12052020F2Nights.399	POS Data
12052020F2Nights.400	POS Data
12052020F2Nights.401	POS Data
12052020F2Nights.402	POS Data
12052020F2Nights.403	POS Data
12052020F2Nights.404	POS Data
12052020F2Nights.405	POS Data
12052020F2Nights.406	POS Data
12052020F2Nights.407	POS Data

Input Files

File Name	File Type
Ephm3410.20g	GLONASS Broadcast Ephemeris
Ephm3410.20n	GPS Broadcast Ephemeris

Output Files

Filename	File type
sbet_11888.out	SBET Trajectory File
eo_11888.txt	ZI Imaging POSEO Output
sbet_11888_NAD83(2011).out	Custom Smoothed BET Export Output
lever_arm_values.txt	ReferenceToPrimaryLeverArms Export Output

Rover Data Summary

First raw data file	12052020F2Nights.395		
Last raw data file	12052020F2Nights.407		
Start GPS week	2135		
Start time	18716.501 (12/06/2020 05:11:56)		
End time	24824.990 (12/06/2020 06:53:44)		
Start of fine alignment	19024.663 (12/06/2020 05:17:04)		
Available subsystems	Primary GNSS, IMU		
POS Event Input	None		
Correction data	None		
IMU Installation Lever Arms & Mounting Angles			
Reference to IMU lever arm (m)	0.000	0.000	0.000
Reference to IMU mounting angles (deg)	0.000	0.000	180.000
Reference to Primary GNSS lever arm (m)	-0.485	-0.379	-1.087
Reference to Primary GNSS lever arm std dev (m)	-1.000		
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

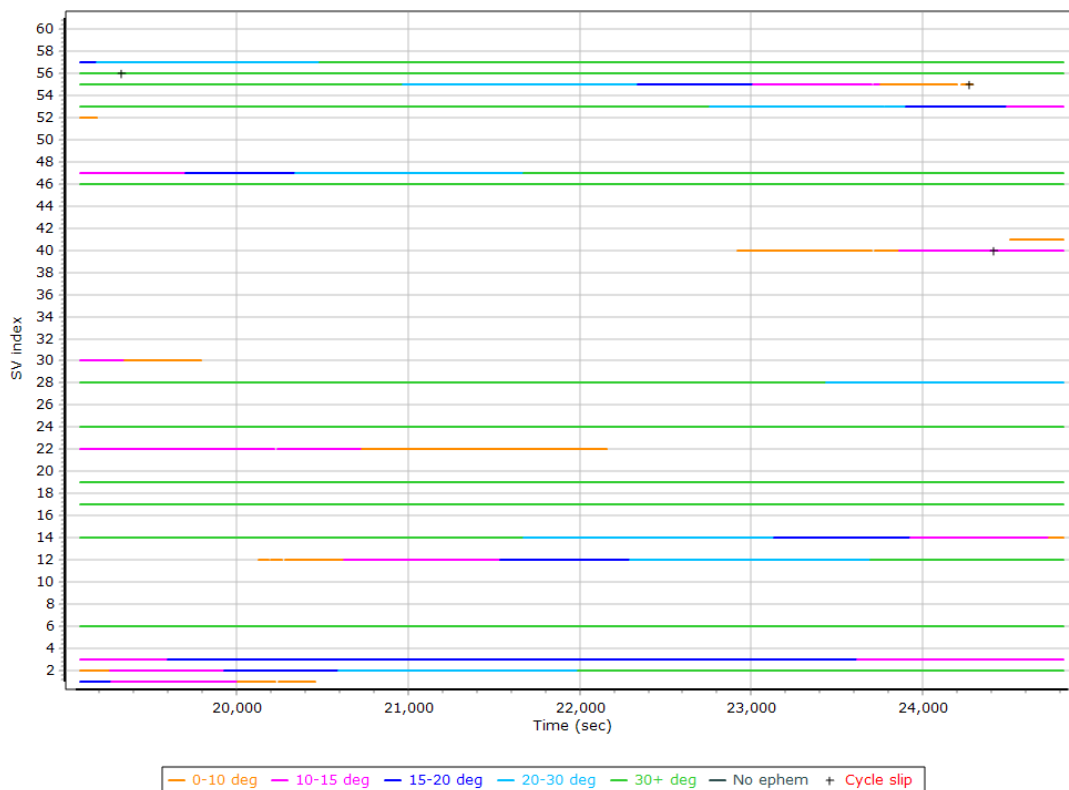
Rover Data QC

Raw IMU Import QC Summary

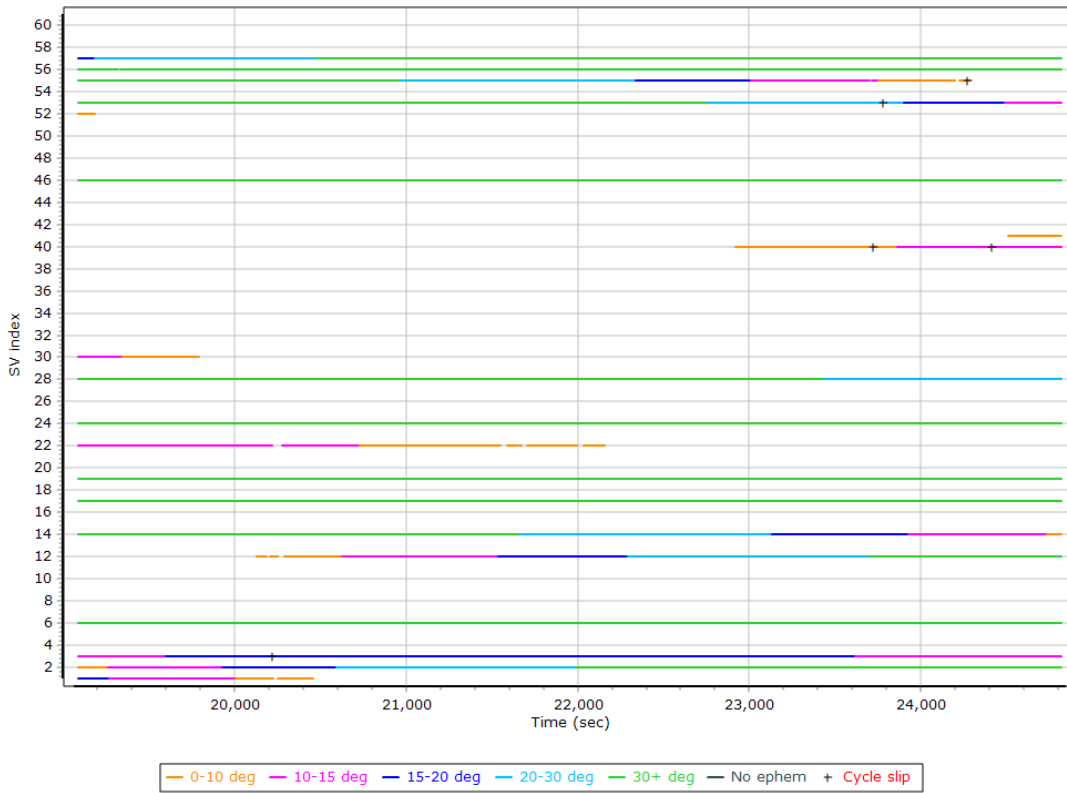
IMU data input file	imu_11888.dat
IMU data check log file	imudt_11888.log
IMU Records Processed	1221594
Termination Status	Normal
IMU Anomalies	0

Primary Observables & Satellite Data

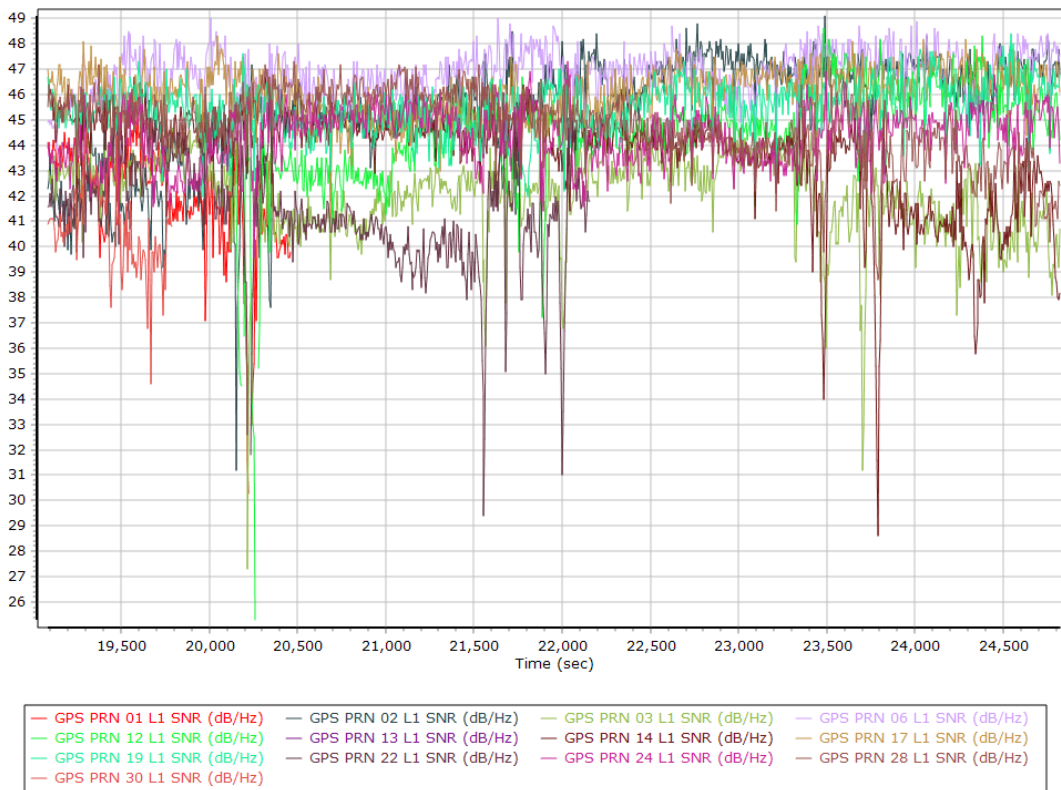
L1 Satellite Lock/Elevation



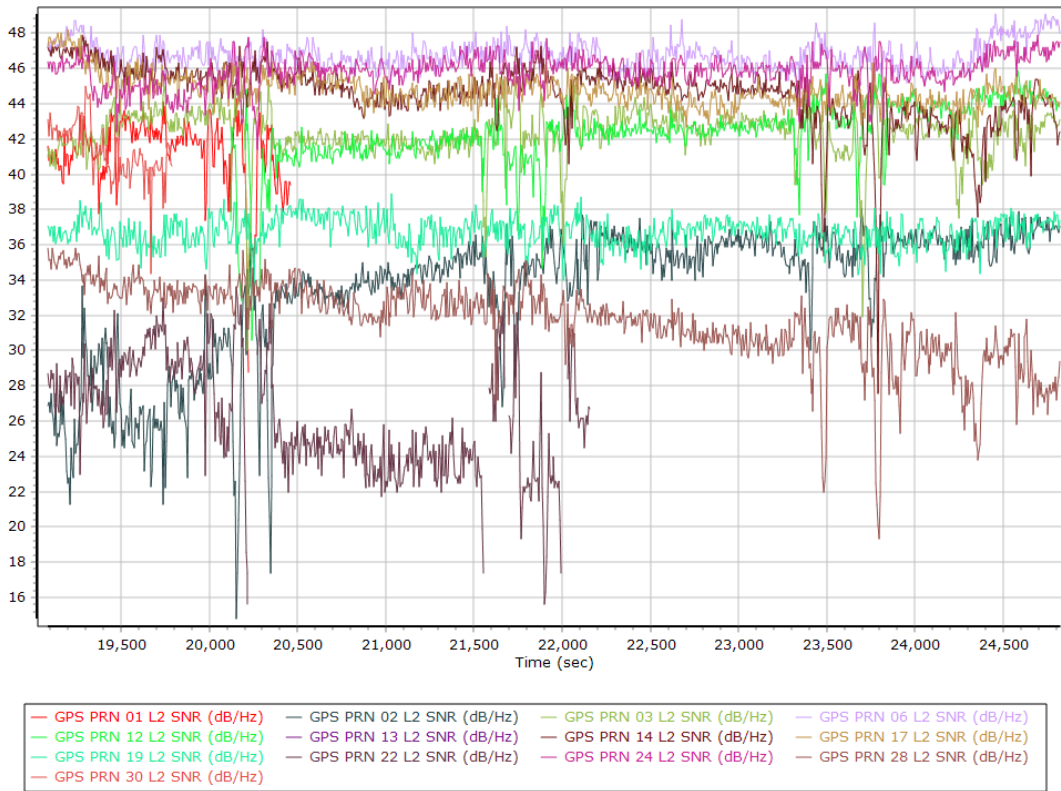
L2 Satellite Lock/Elevation



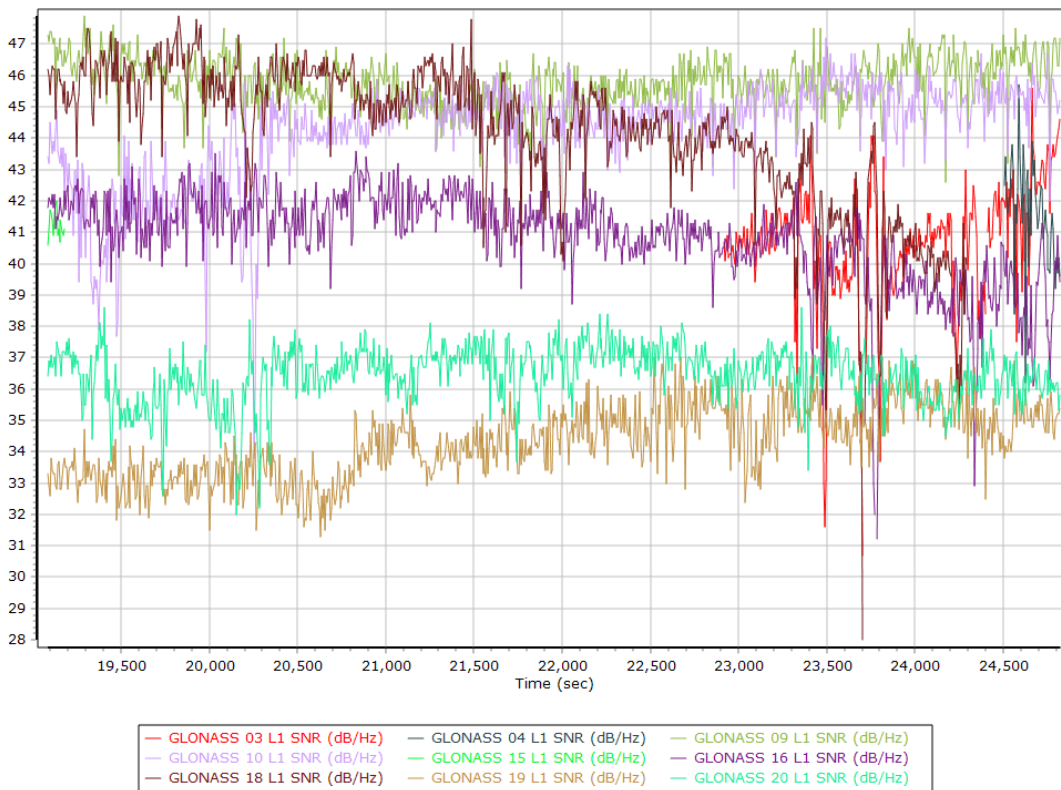
GPS L1 SNR



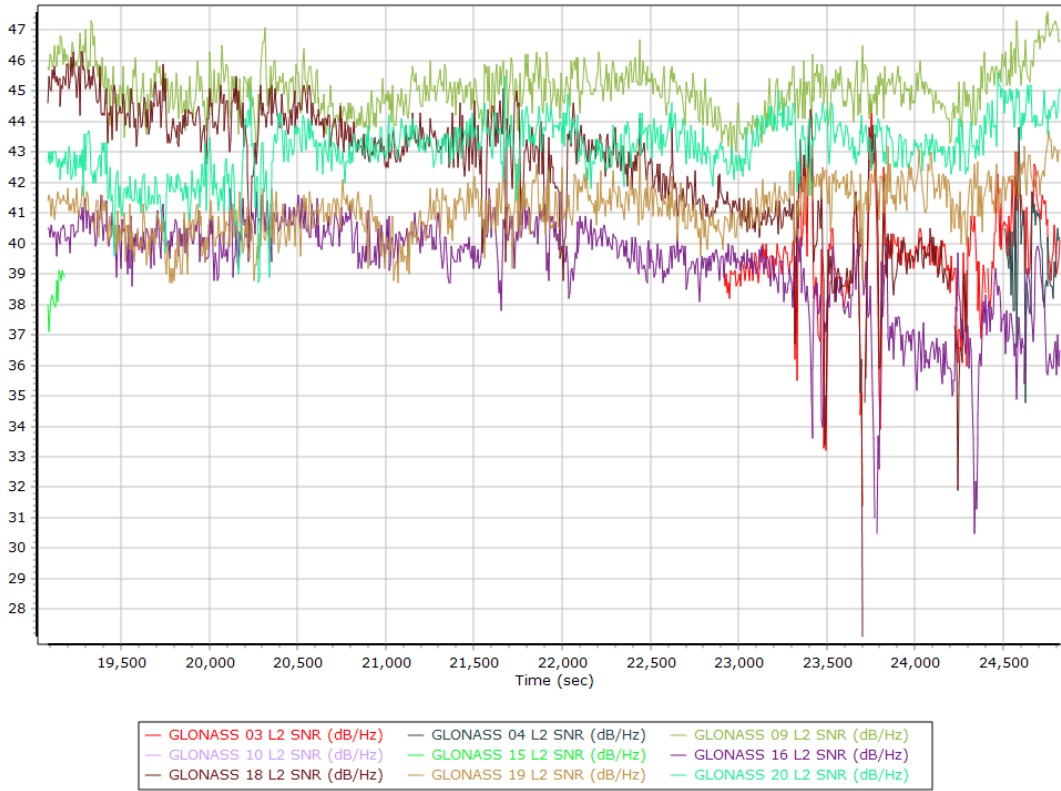
GPS L2 SNR



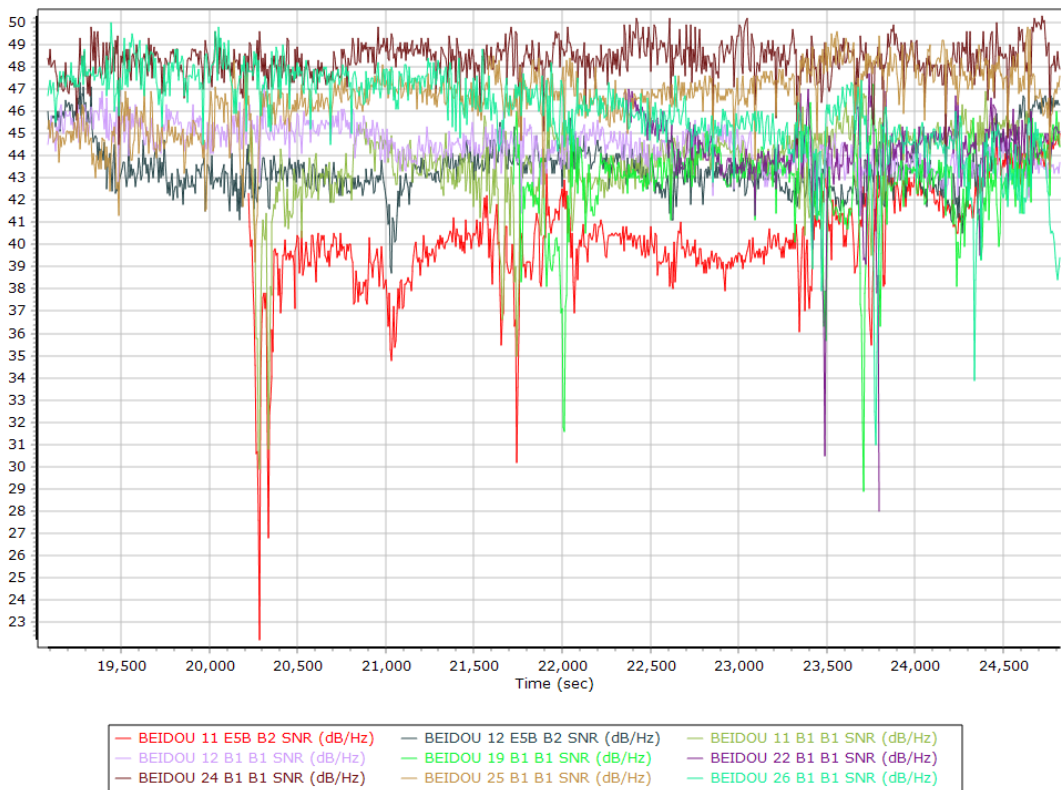
GLONASS L1 SNR



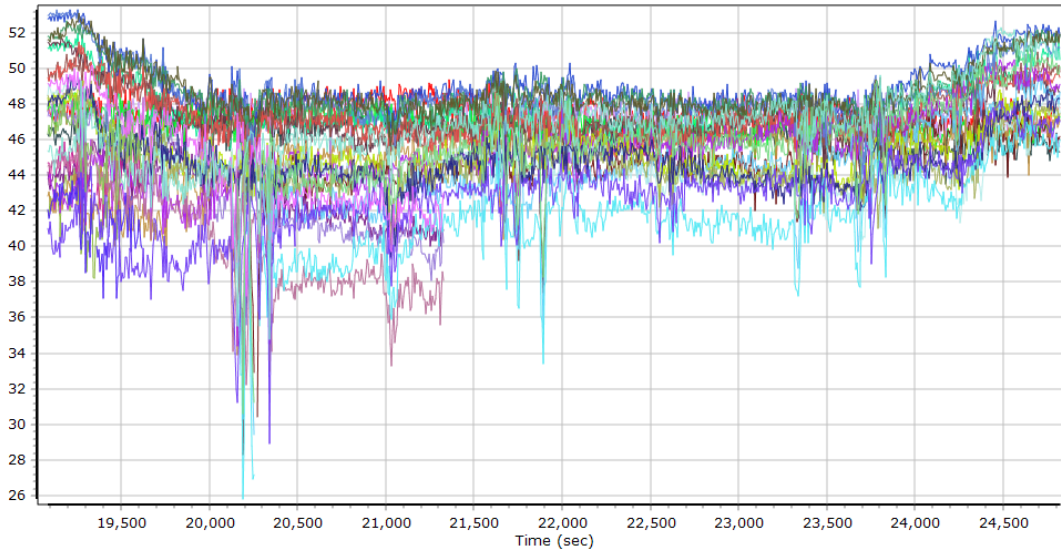
GLONASS L2 SNR



BEIDOU SNR



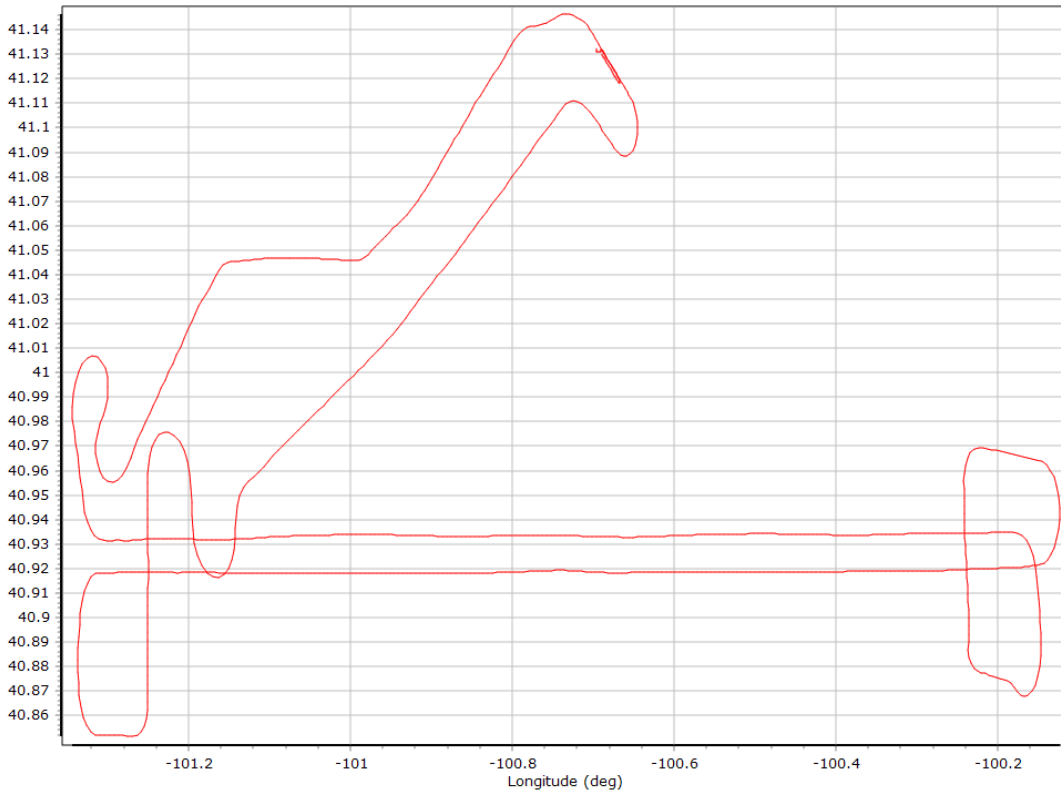
GALILEO SNR



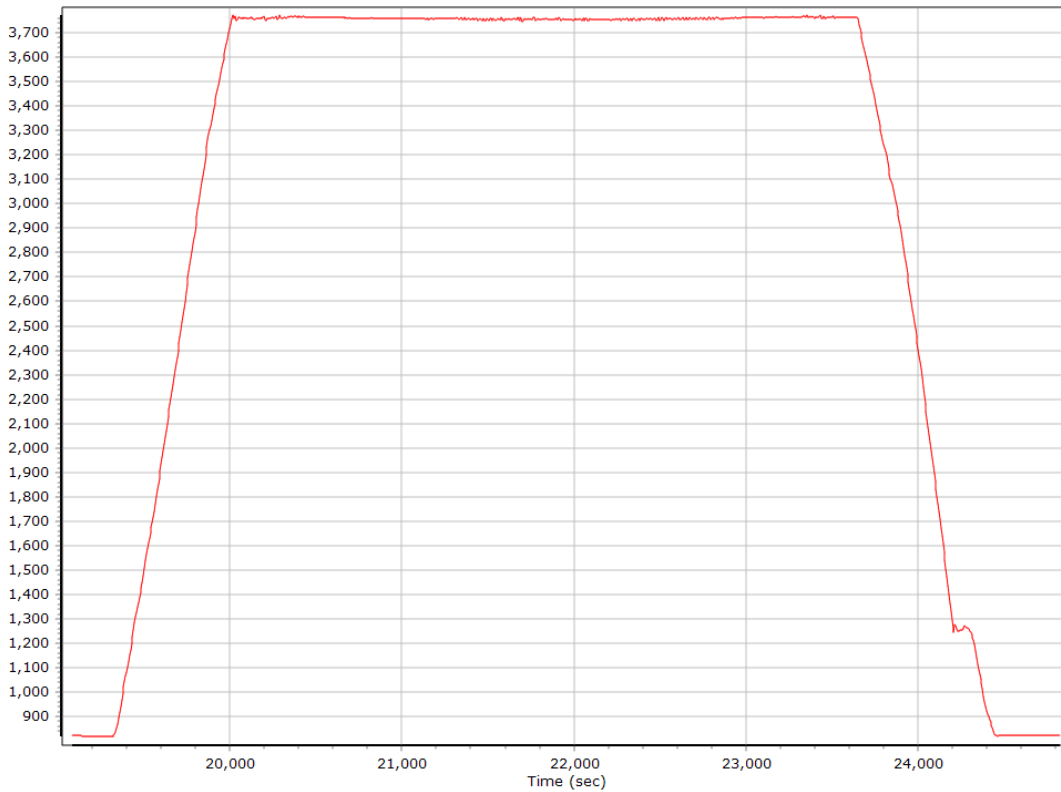
— GALILEO 01 L1 BOC_1_1_D_MBOC SNR (dB/Hz)	— GALILEO 13 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
— GALILEO 15 L1 BOC_1_1_D_MBOC SNR (dB/Hz)	— GALILEO 21 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
— GALILEO 26 L1 BOC_1_1_D_MBOC SNR (dB/Hz)	— GALILEO 27 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
— GALILEO 31 L1 BOC_1_1_D_MBOC SNR (dB/Hz)	— GALILEO 33 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
— GALILEO 01 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 13 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 15 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 21 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 26 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 27 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 31 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 33 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 01 E5B BPSK10_PD SNR (dB/Hz)	— GALILEO 13 E5B BPSK10_PD SNR (dB/Hz)
— GALILEO 15 E5B BPSK10_PD SNR (dB/Hz)	— GALILEO 21 E5B BPSK10_PD SNR (dB/Hz)

Smoothed Trajectory Information

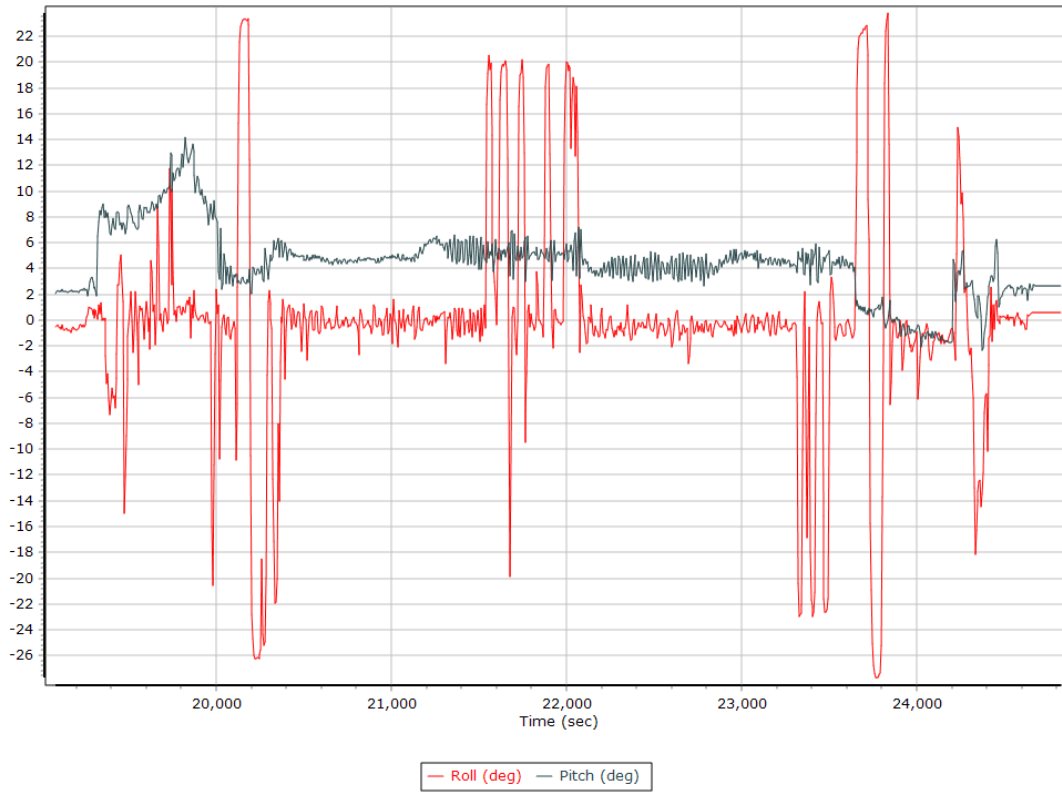
Top View



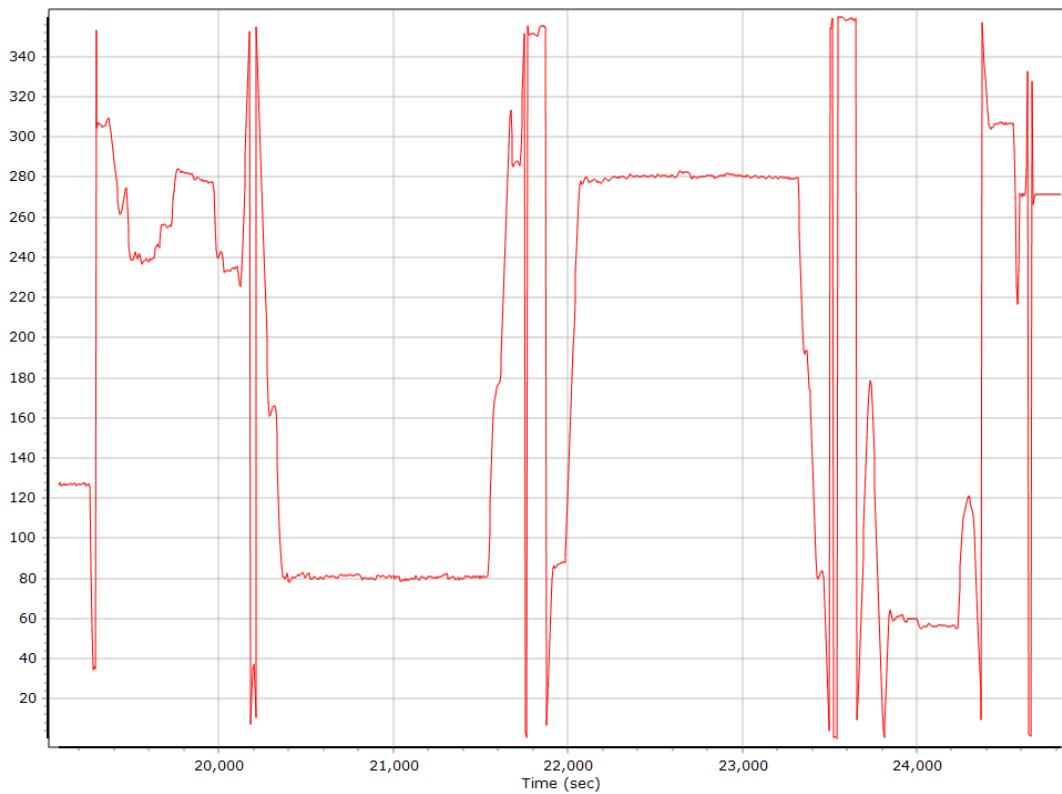
Altitude



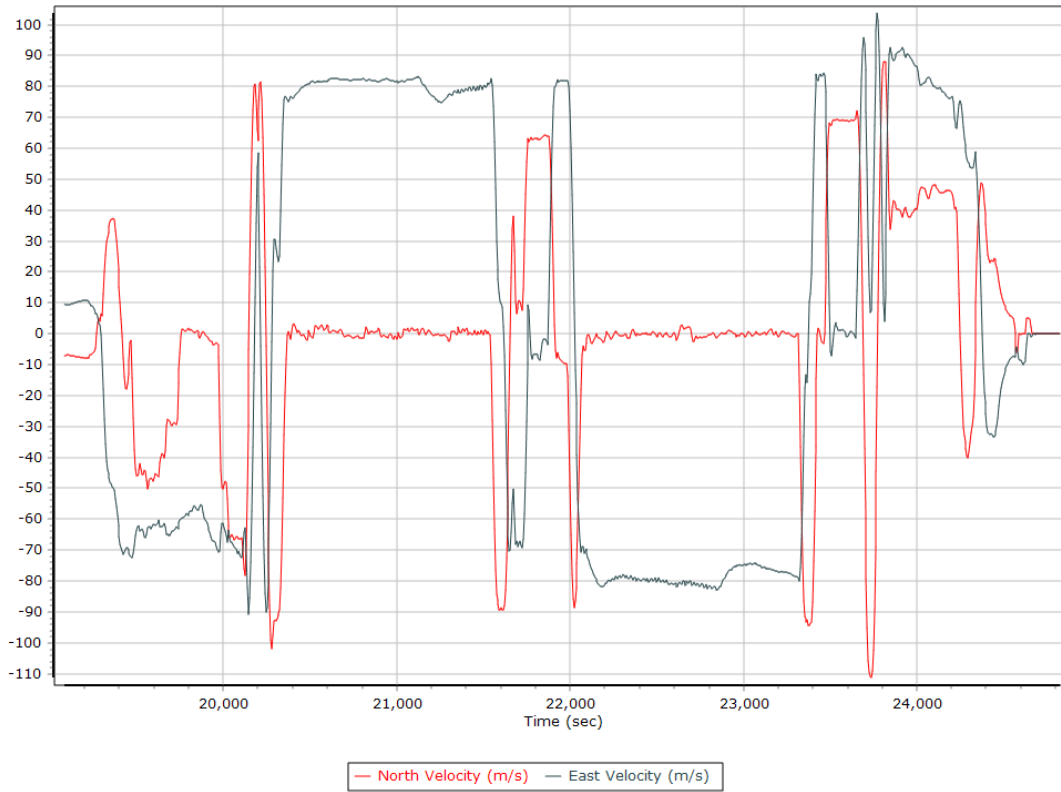
Roll/Pitch



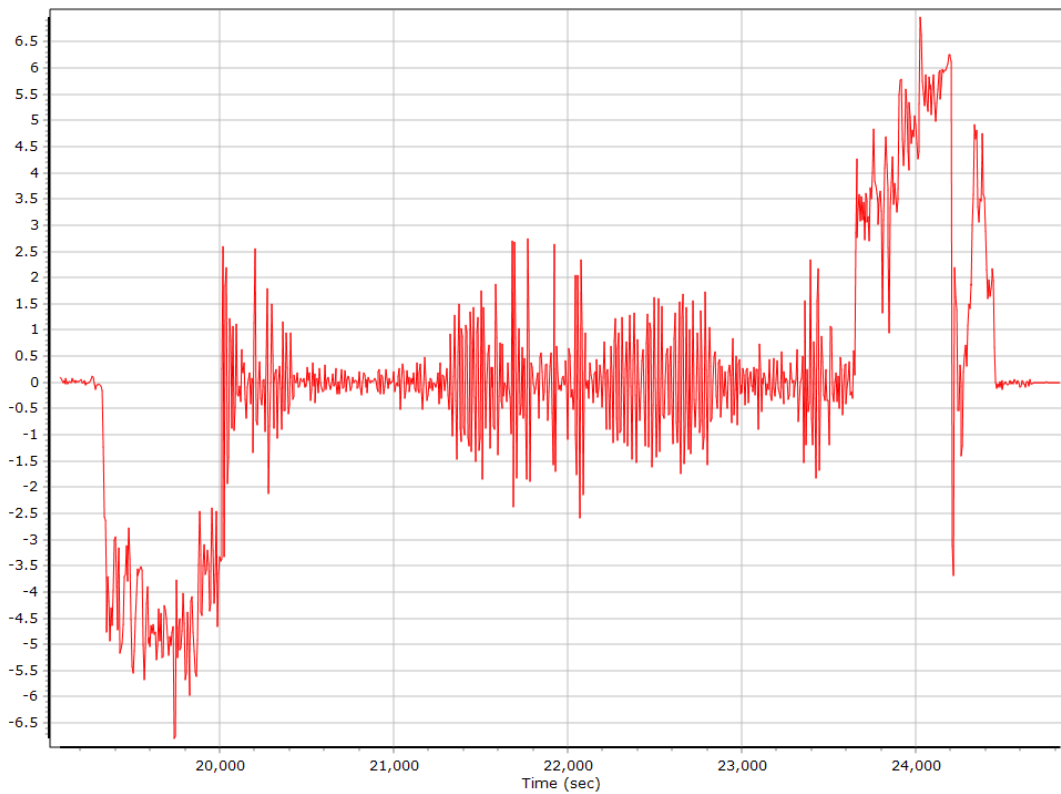
Heading



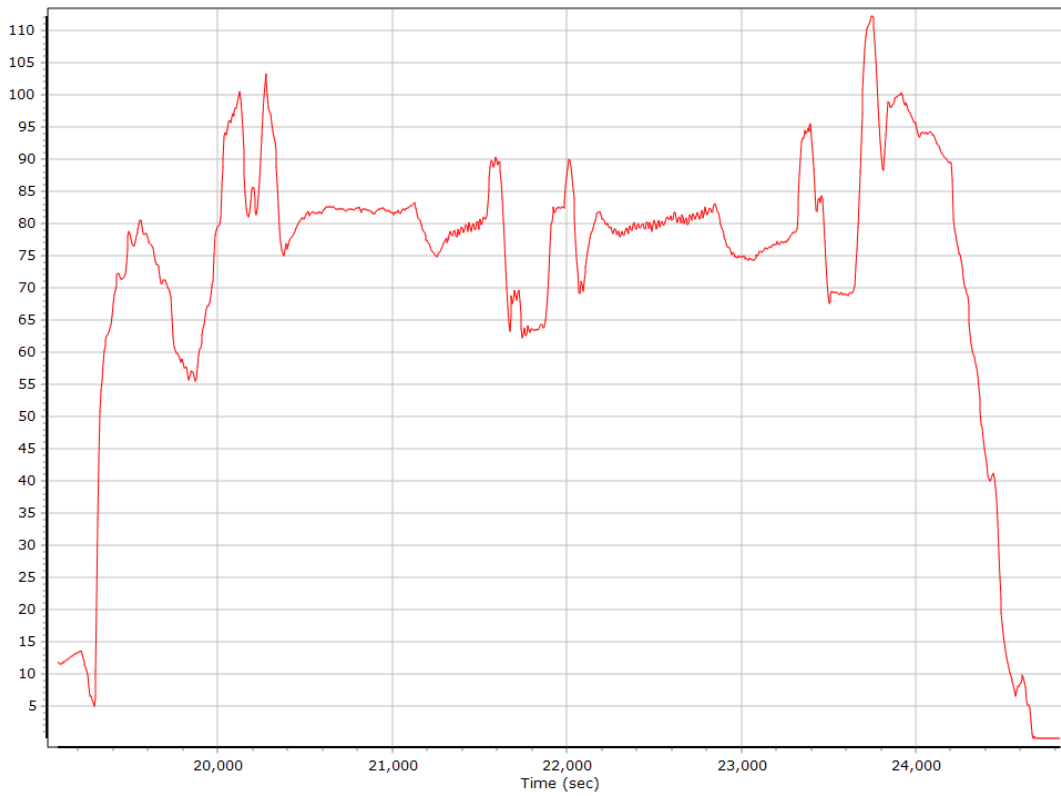
North/East Velocity



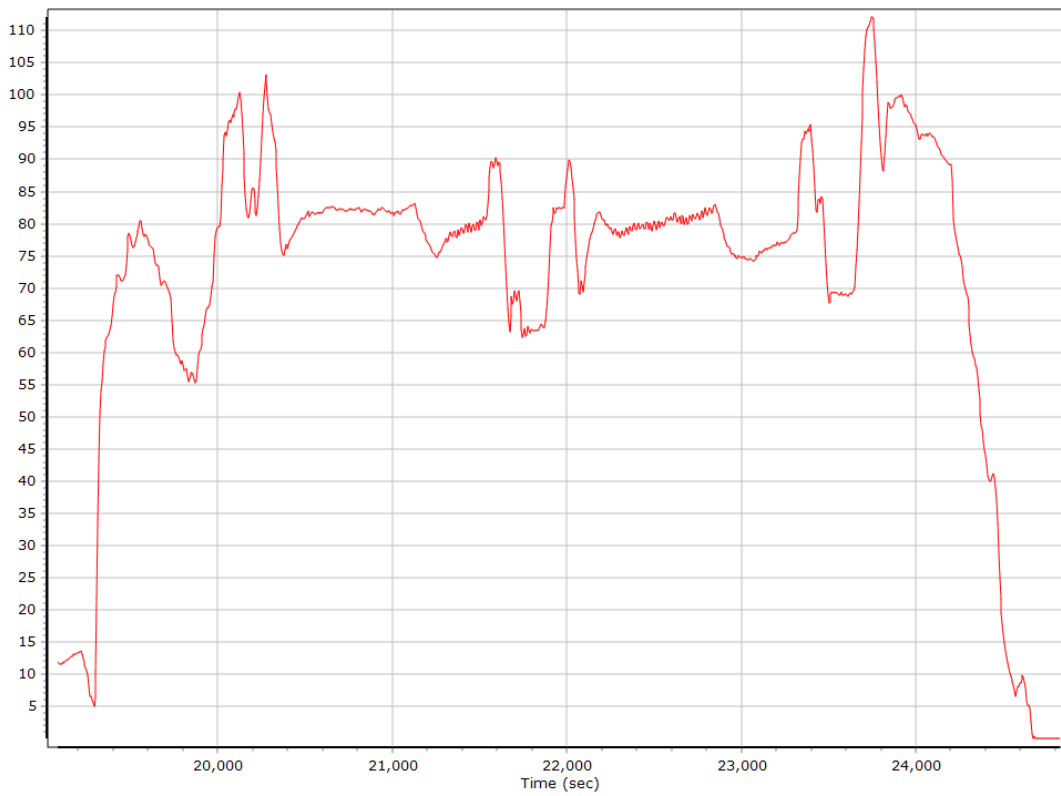
Down Velocity



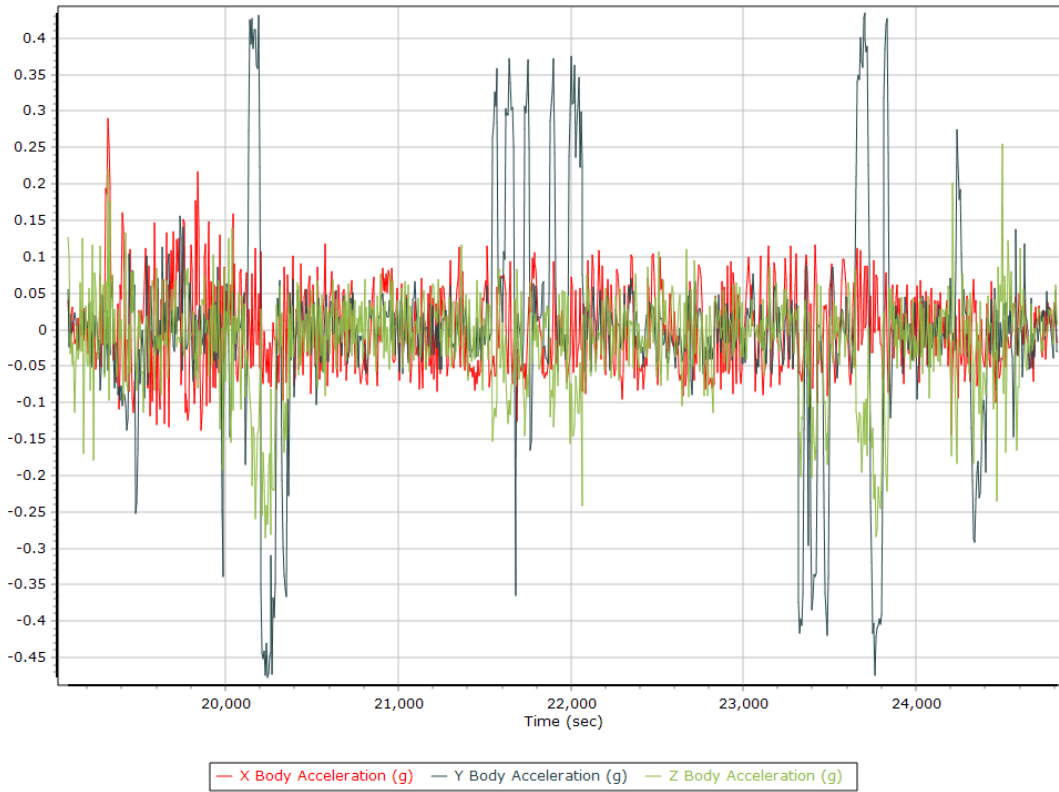
Total Speed



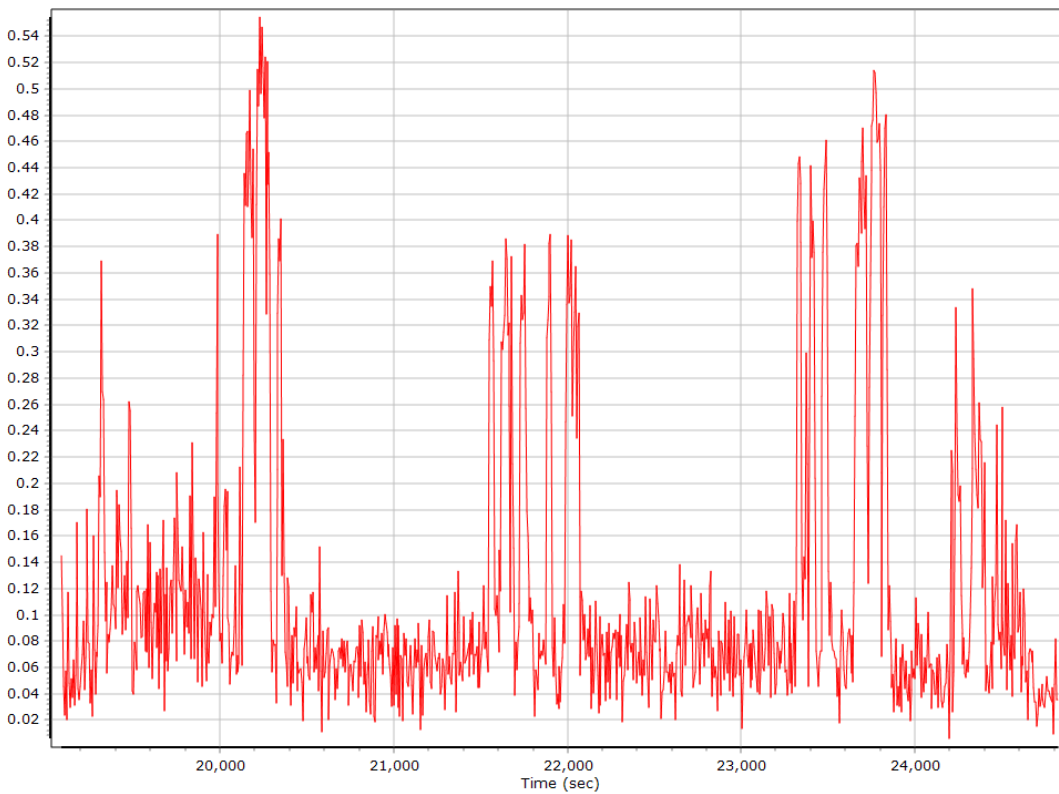
Ground Speed



Body Acceleration



Total Body Acceleration

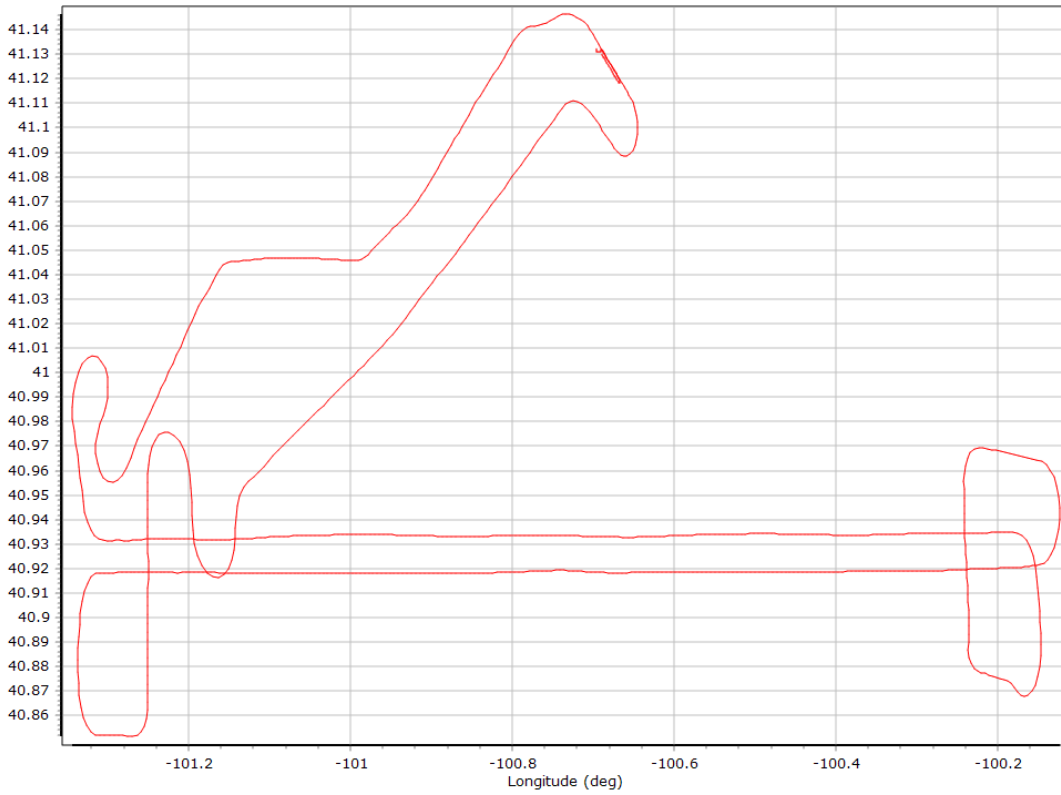


Body Angular Rate

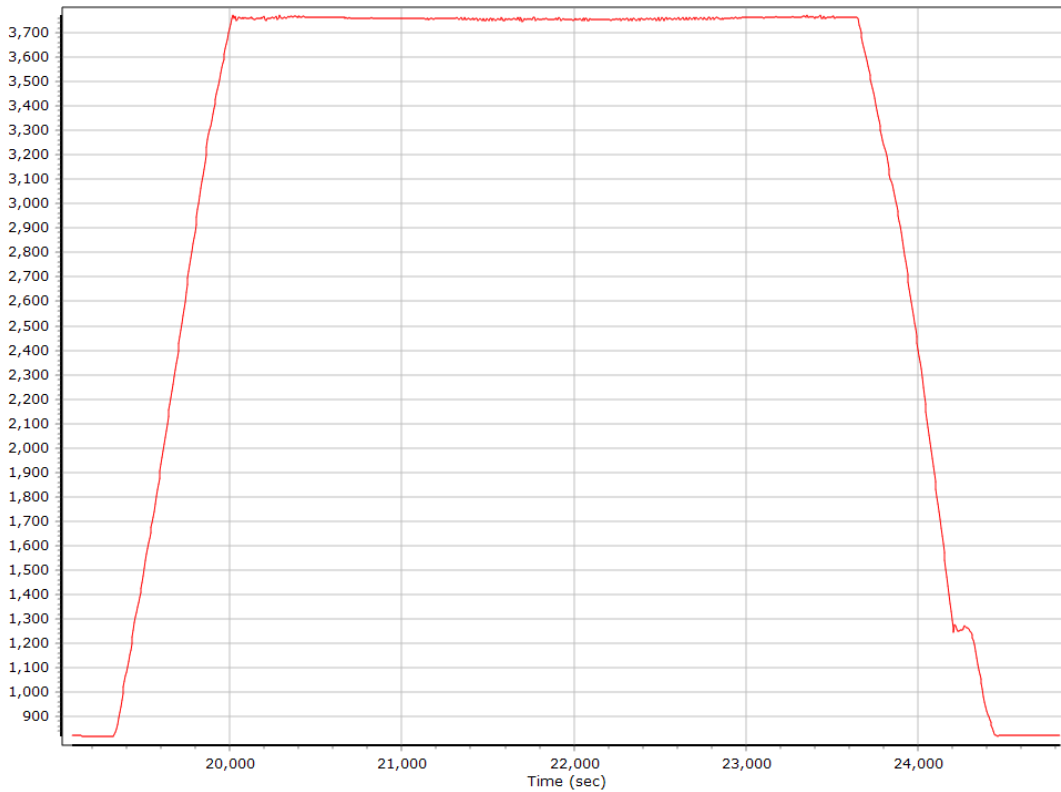


Forward Processed Trajectory Information

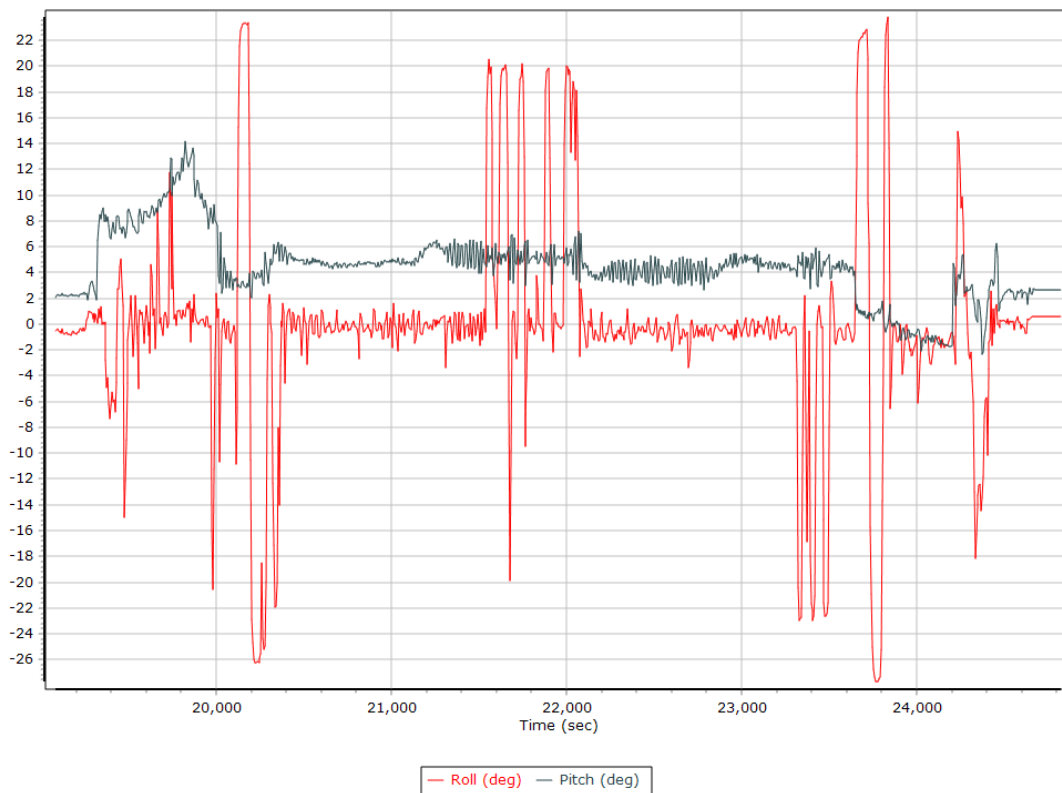
Top View



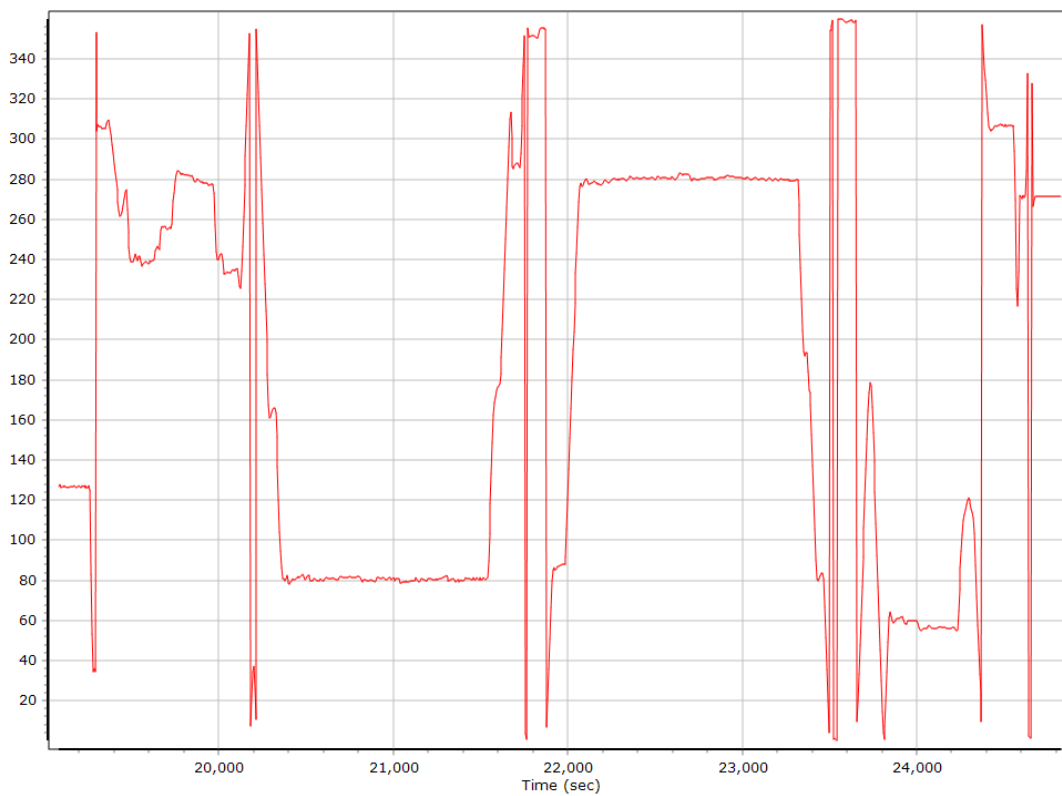
Altitude



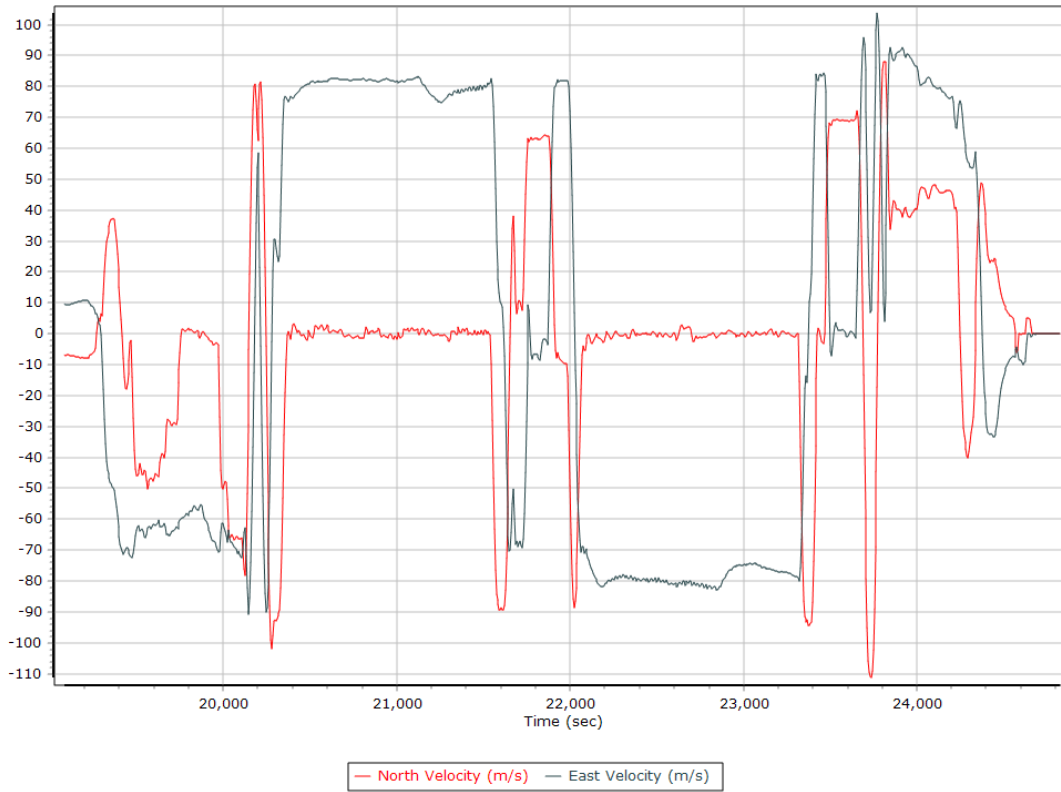
Roll/Pitch



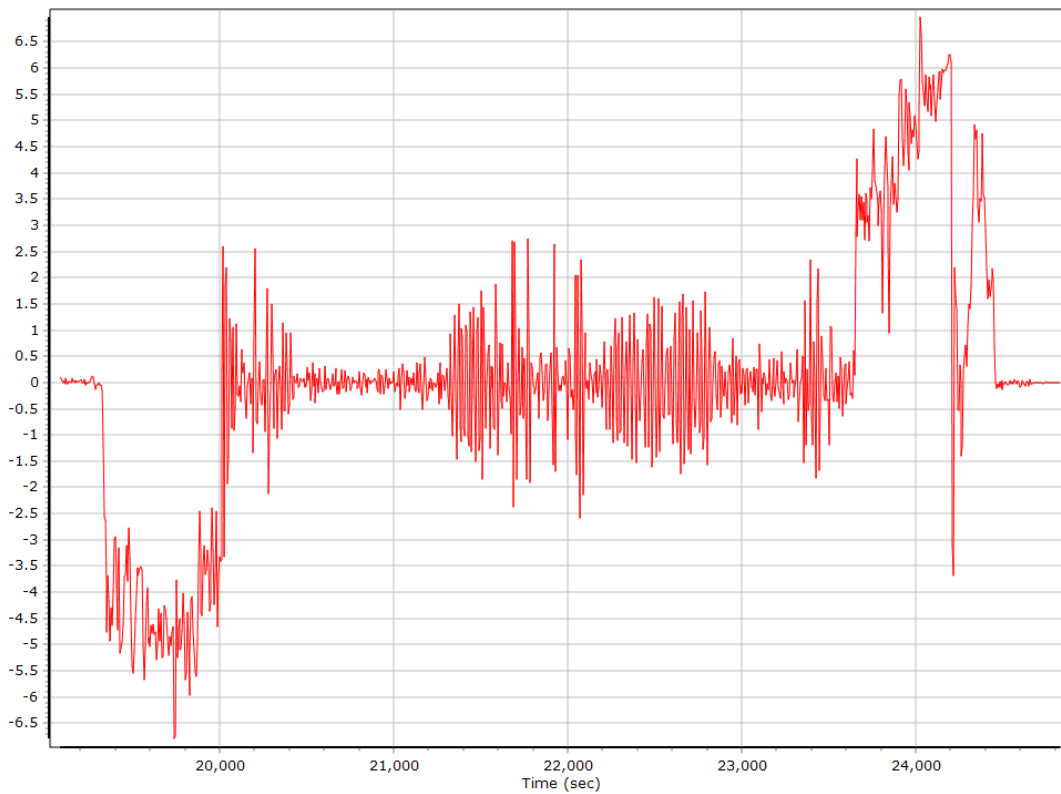
Heading



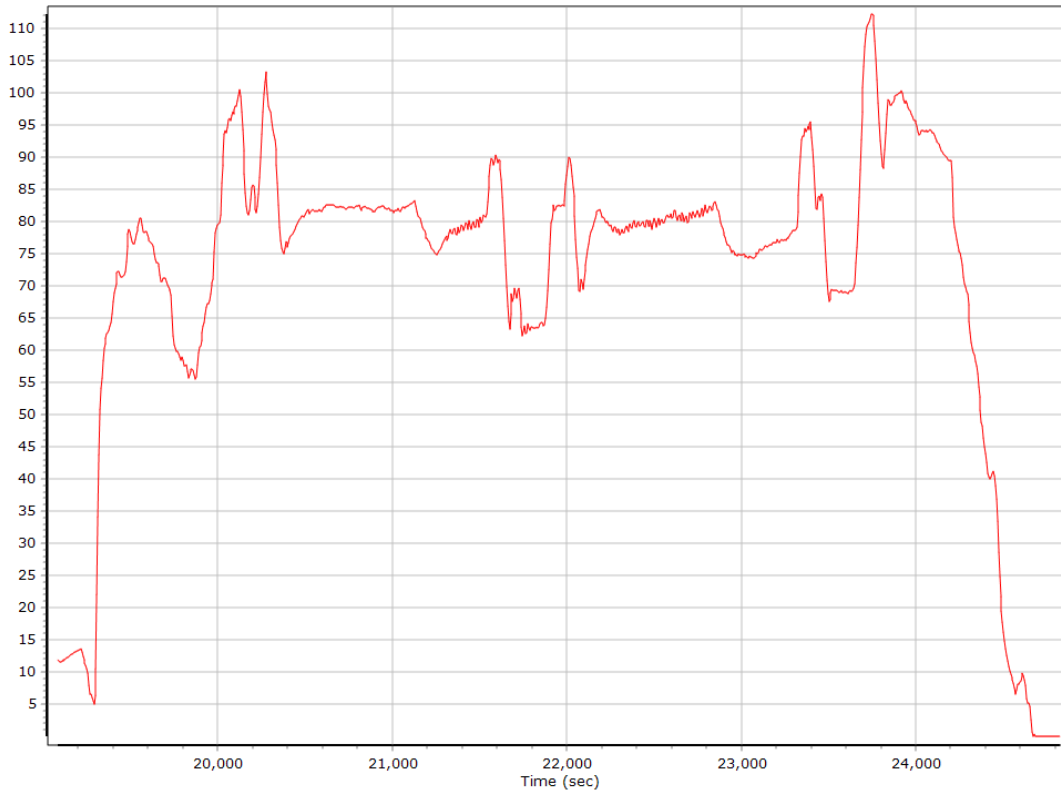
North/East Velocity



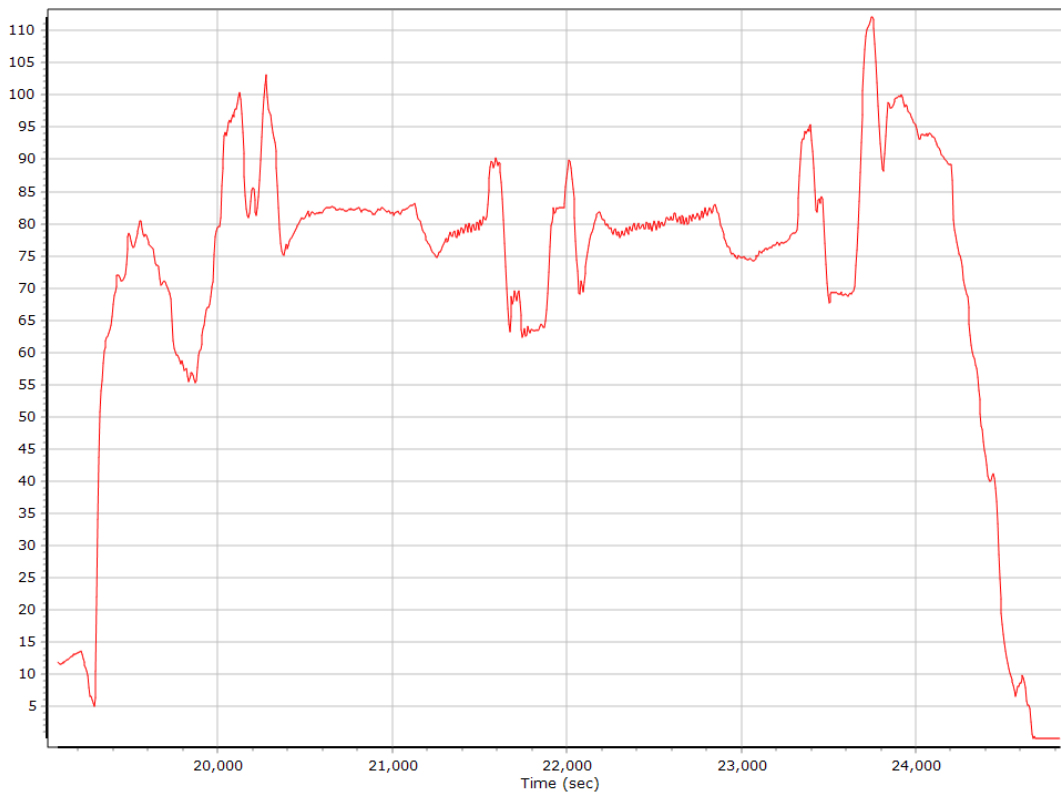
Down Velocity



Total Speed



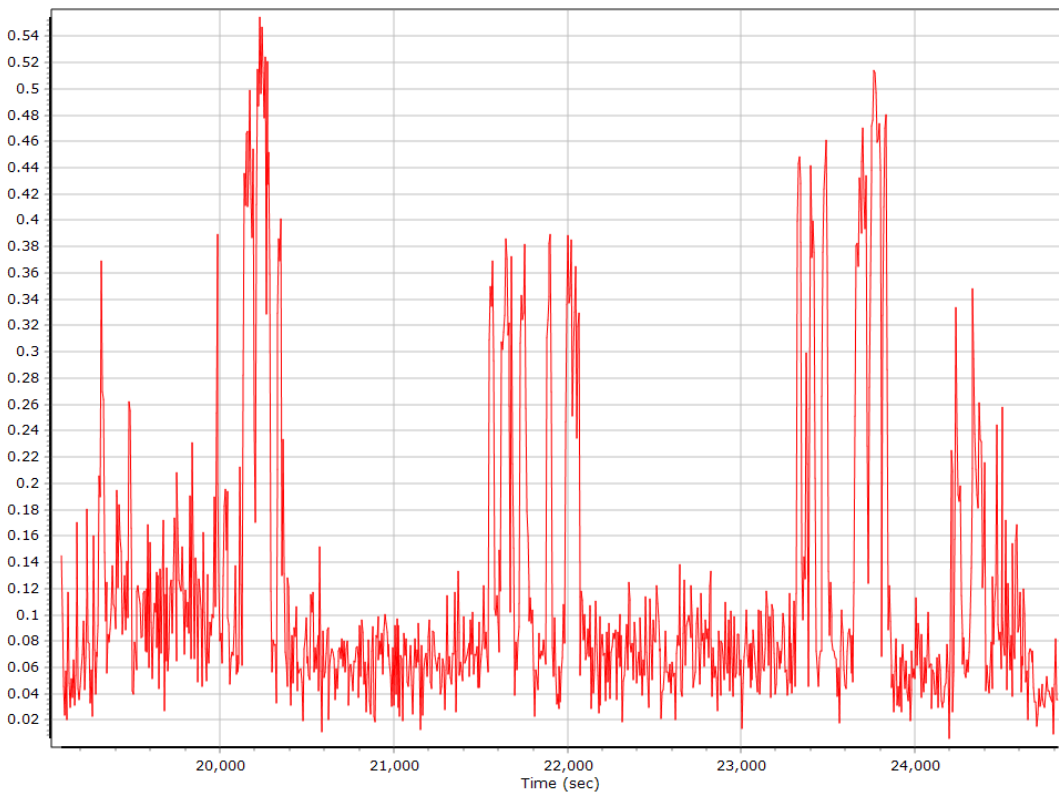
Ground Speed



Body Acceleration



Total Body Acceleration



Body Angular Rate

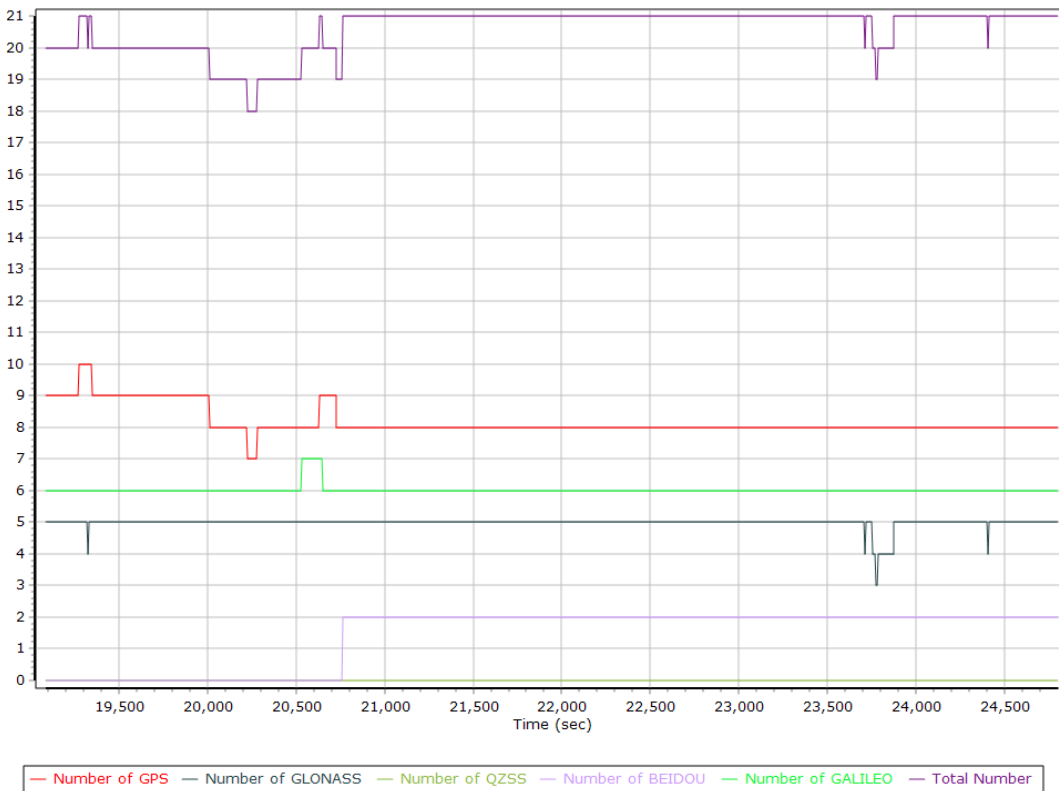


GNSS QC

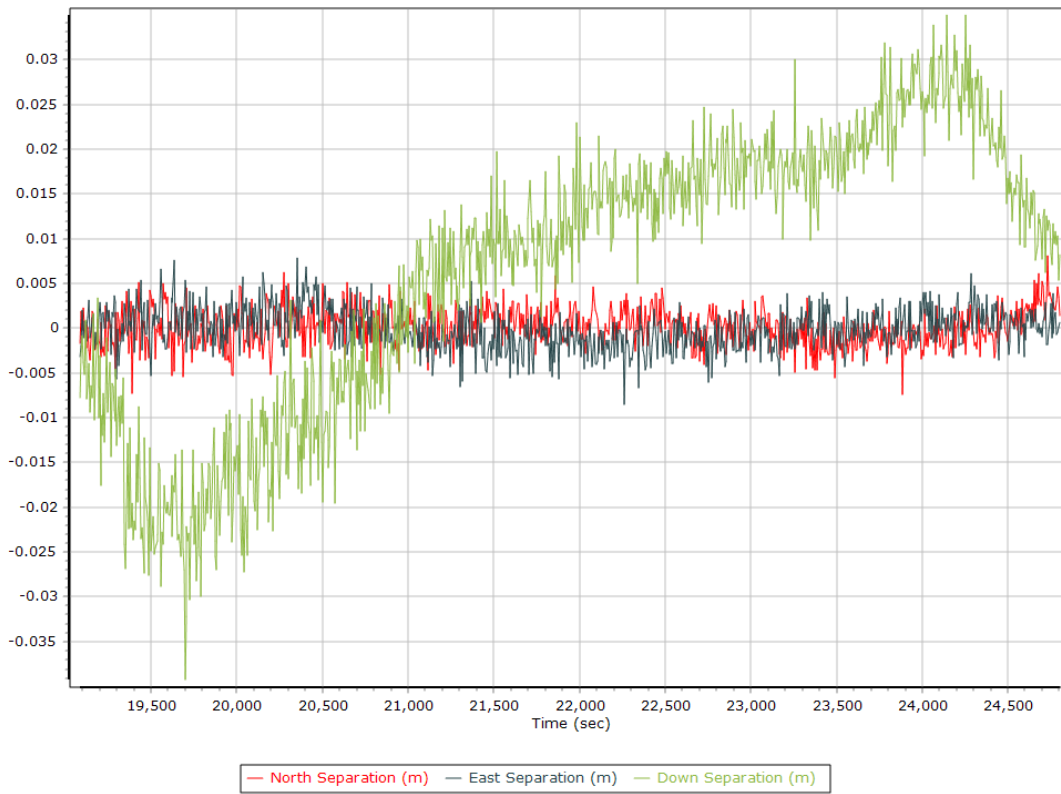
GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	7	10	8
Number of GLONASS SV	3	6	5
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	2	1
Number of GALILEO SV	5	7	6
Total number of SV	18	21	21
PDOP	0.97	1.35	1.12
QC Solution Gaps	0.00	0.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	6082.00	0.00	0.00
Percentage	100.00	0.00	0.00

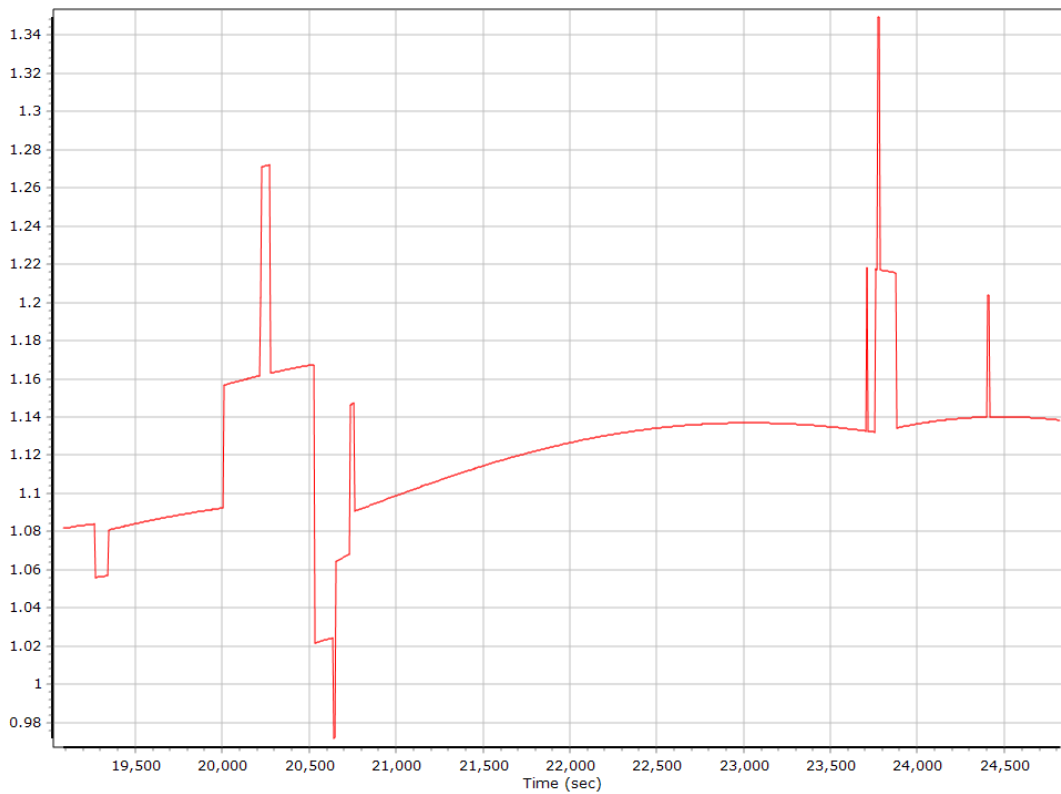
Num SVs in solution



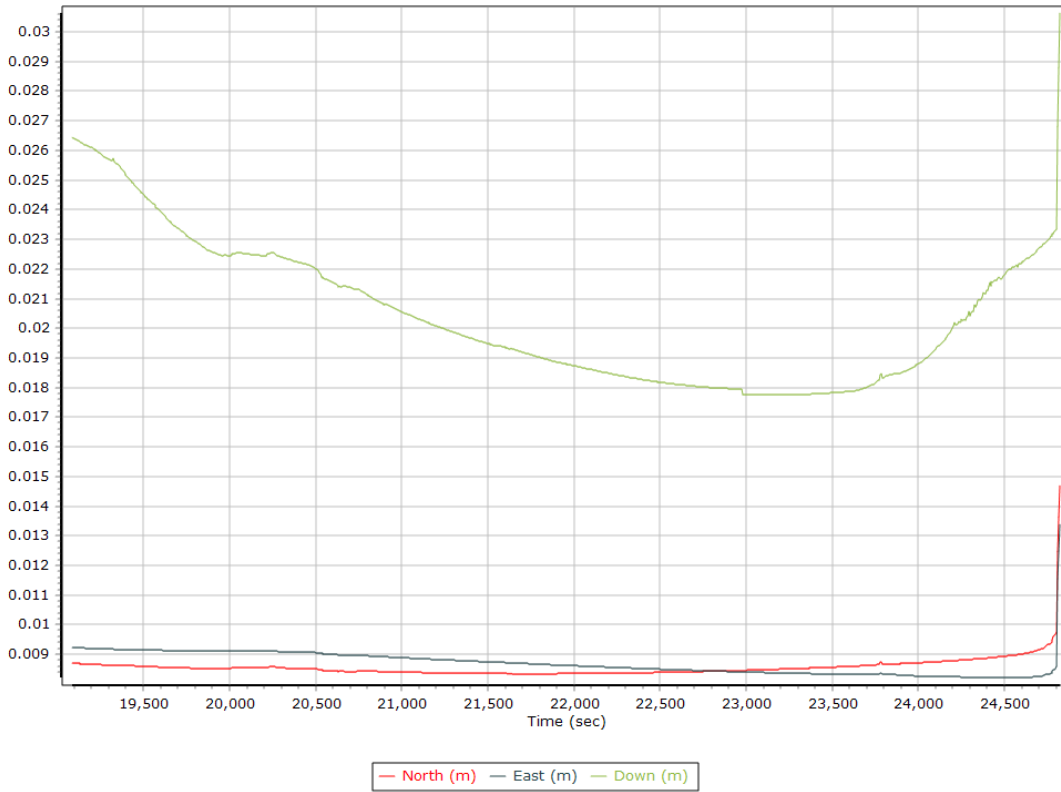
Forward/Reverse Separation



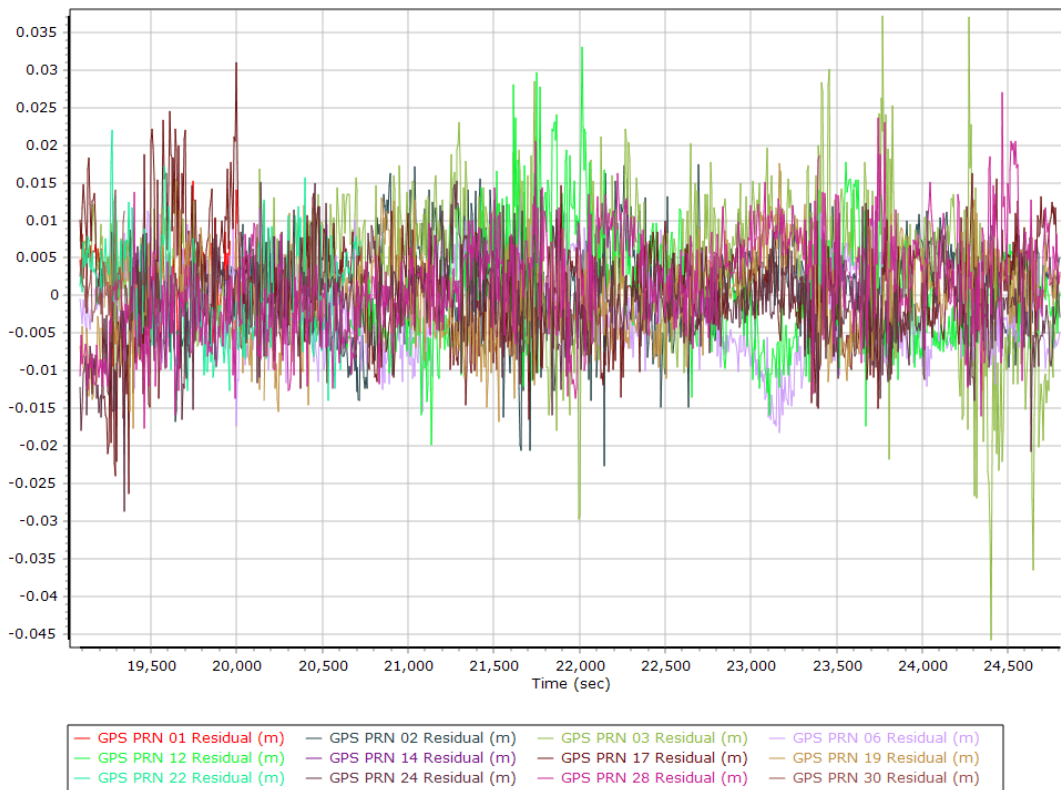
PDOP



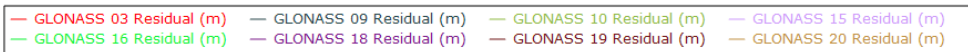
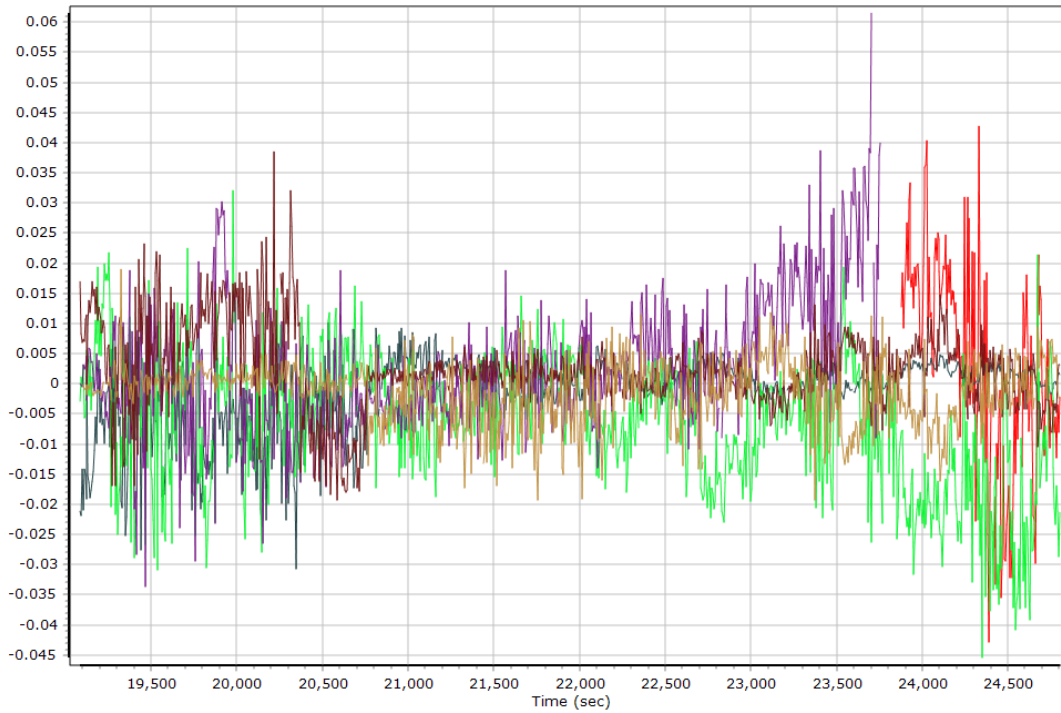
Estimated Position Accuracy



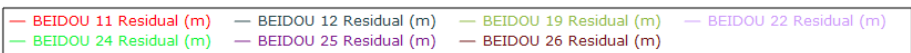
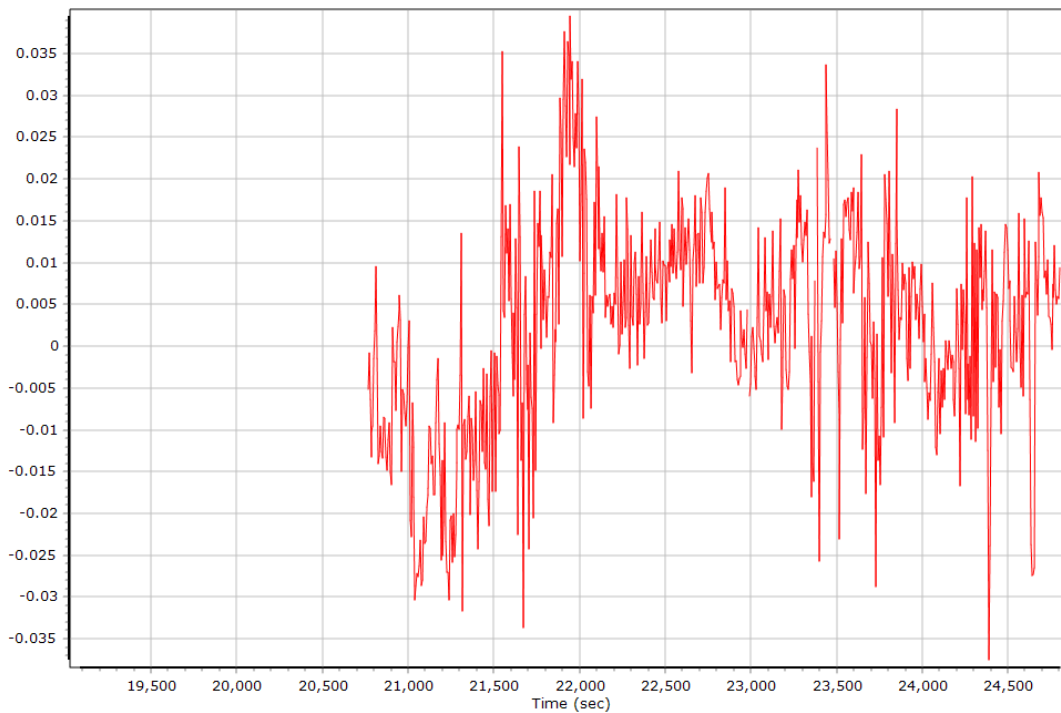
GPS Residuals



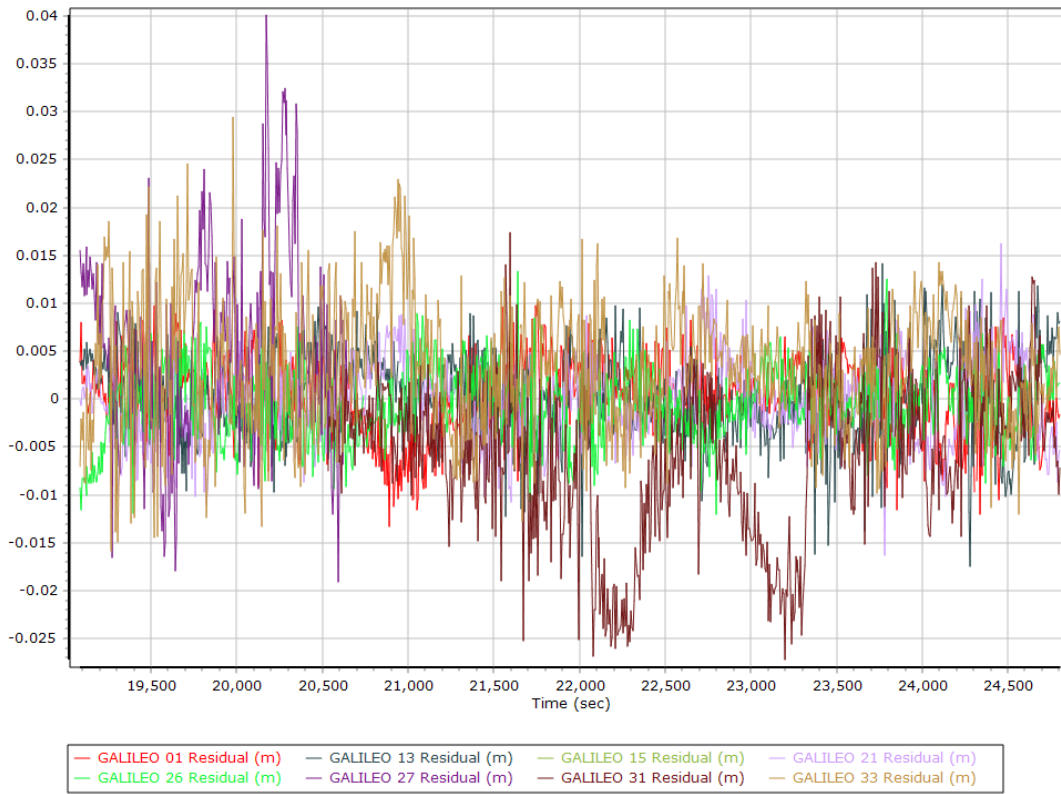
GLONASS Residuals



BEIDOU Residuals



GALILEO Residuals



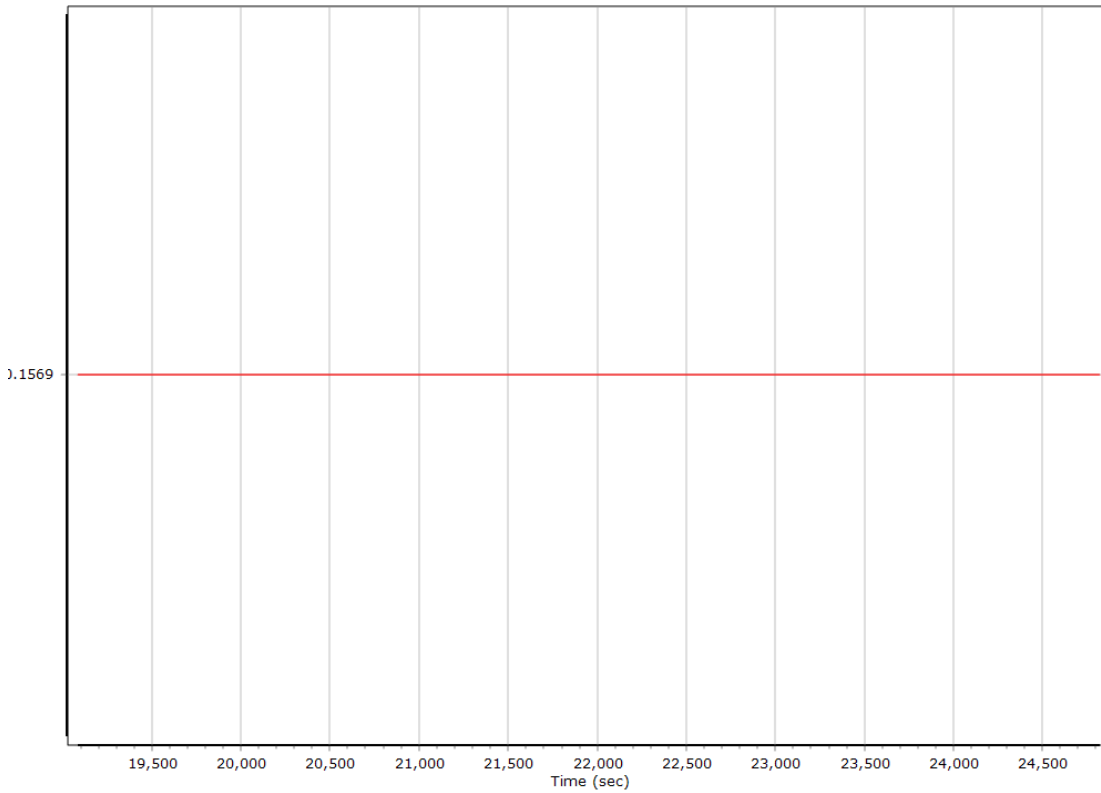
GNSS-Inertial Processor Configuration

Processing mode	IN-Fusion PP-RTX		
Stabilized mount	False		
Processing start time	18717.000 (12/06/2020 05:11:57)		
Processing end time	24825.000 (12/06/2020 06:53:45)		
Initial attitude source	Real-Time VNAV/RNAV Attitude		
IMU Sensor Context	Processing with Onboard IMU		
Reference to IMU lever arm (m)	0.000	0.000	0.000
Reference to IMU mounting angles (deg)	0.000	0.000	180.000
Reference to Primary GNSS lever arm (m)	0.157	-0.150	-1.090
Reference to Primary GNSS lever arm std dev (m)	0.030	0.030	0.030
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

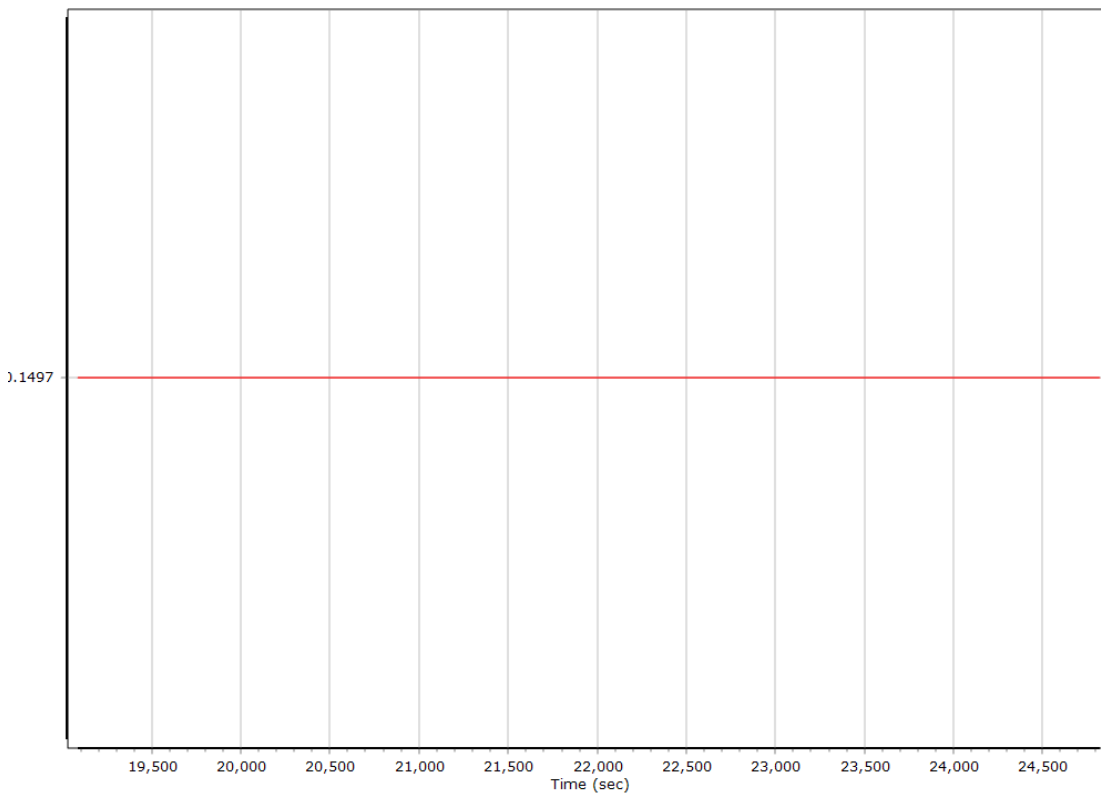
Calibrated Installation Parameters

Reference-Primary GNSS Lever Arm (m)

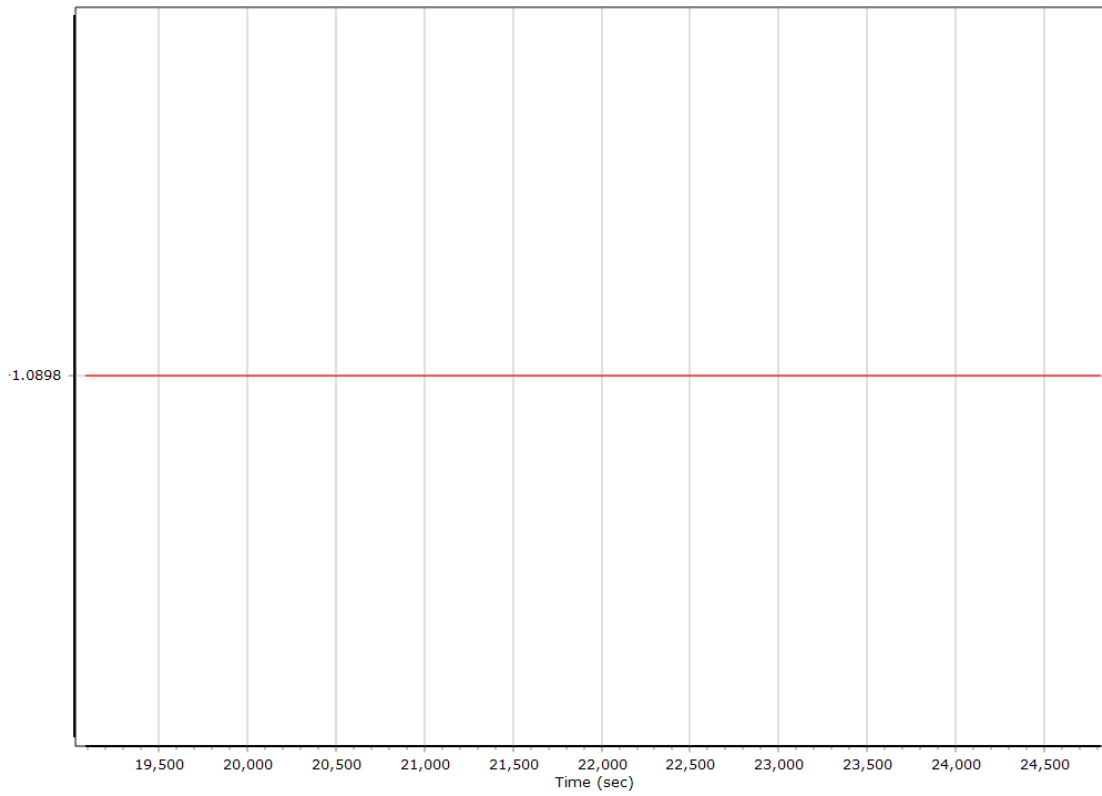
X Reference-Primary GNSS Lever Arm (m)



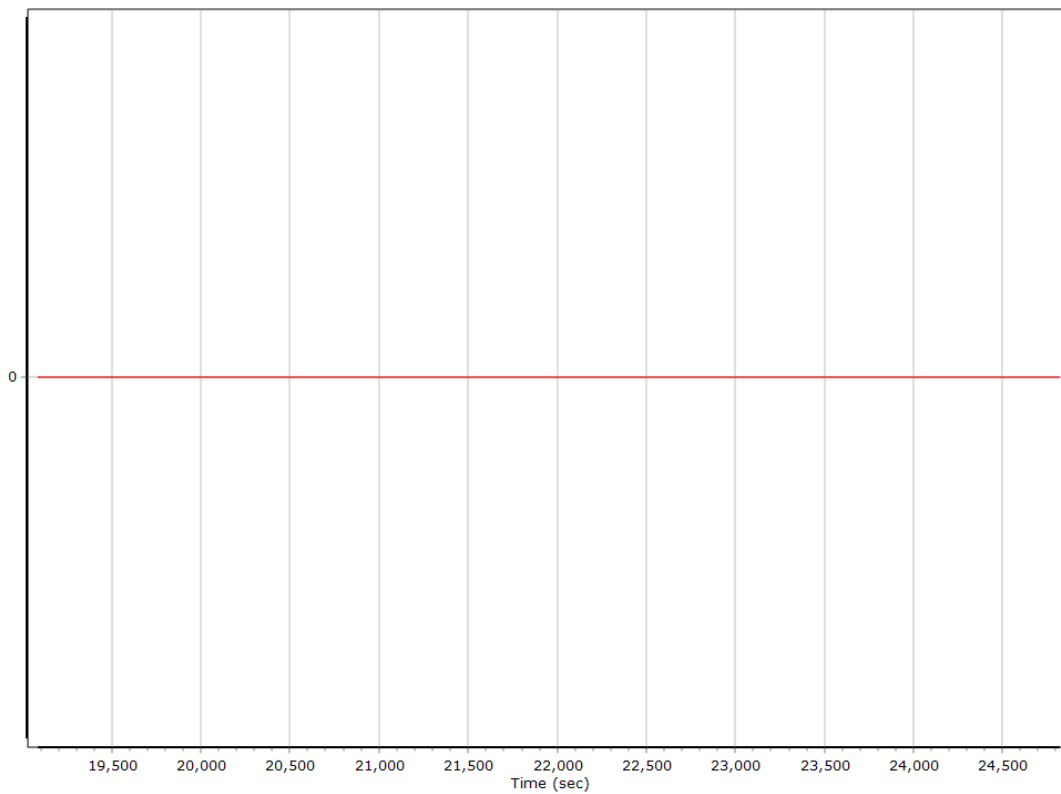
Y Reference-Primary GNSS Lever Arm (m)



Z Reference-Primary GNSS Lever Arm (m)



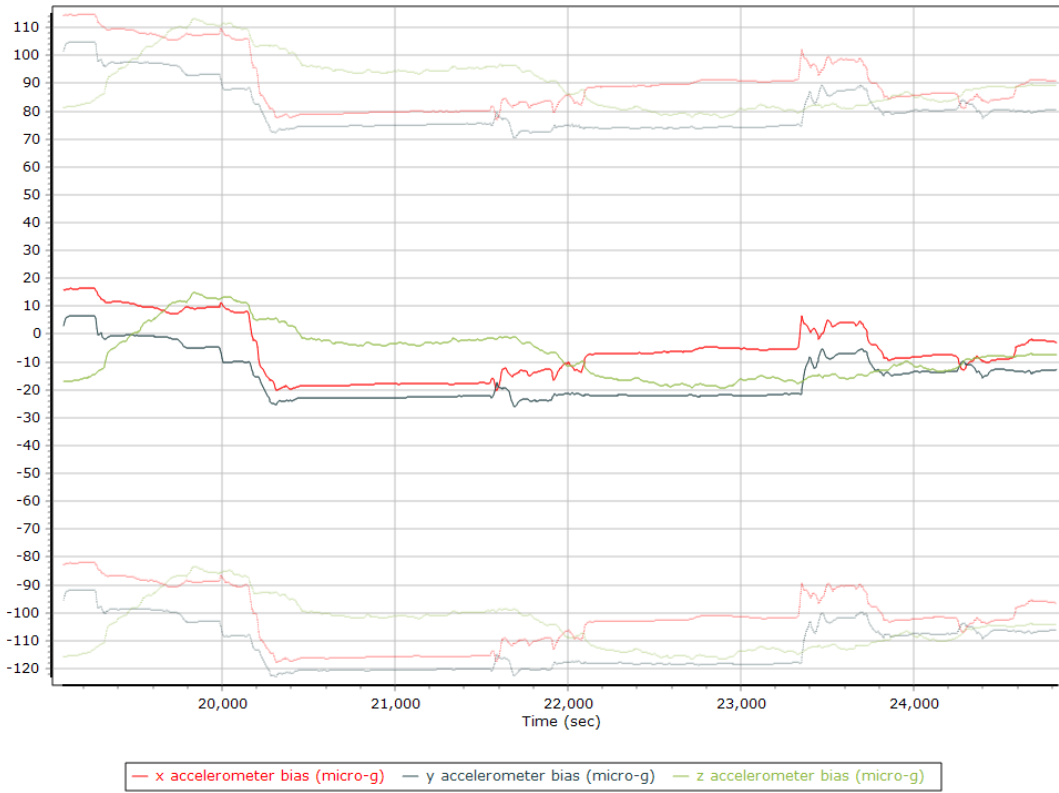
Reference-Primary GNSS Lever Arm Figure of Merit



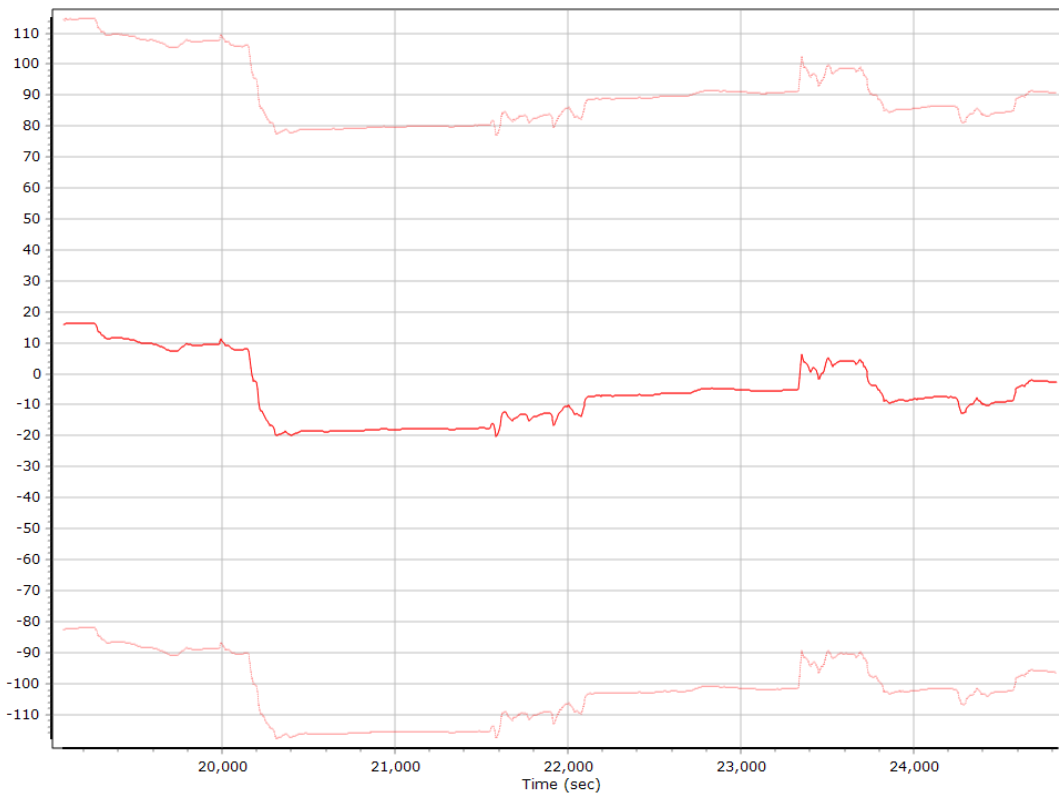
IN-Fusion QC

Forward Processed Estimated Errors, Reference Frame

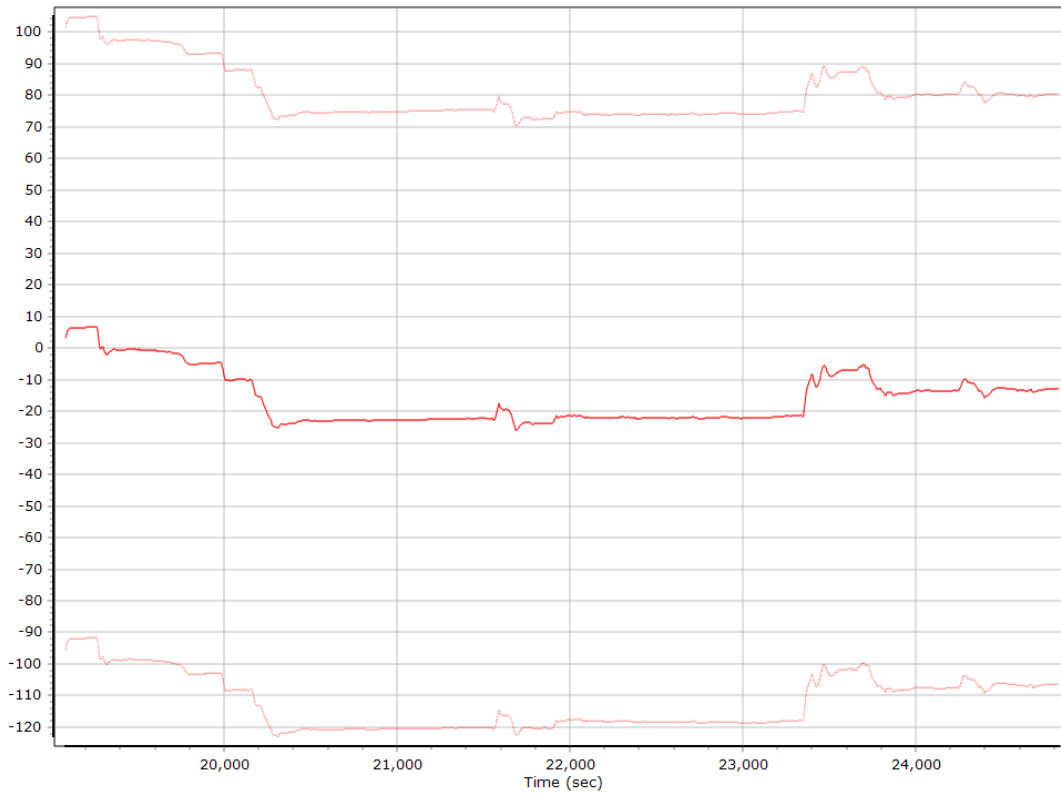
Accelerometer Bias (micro-g)



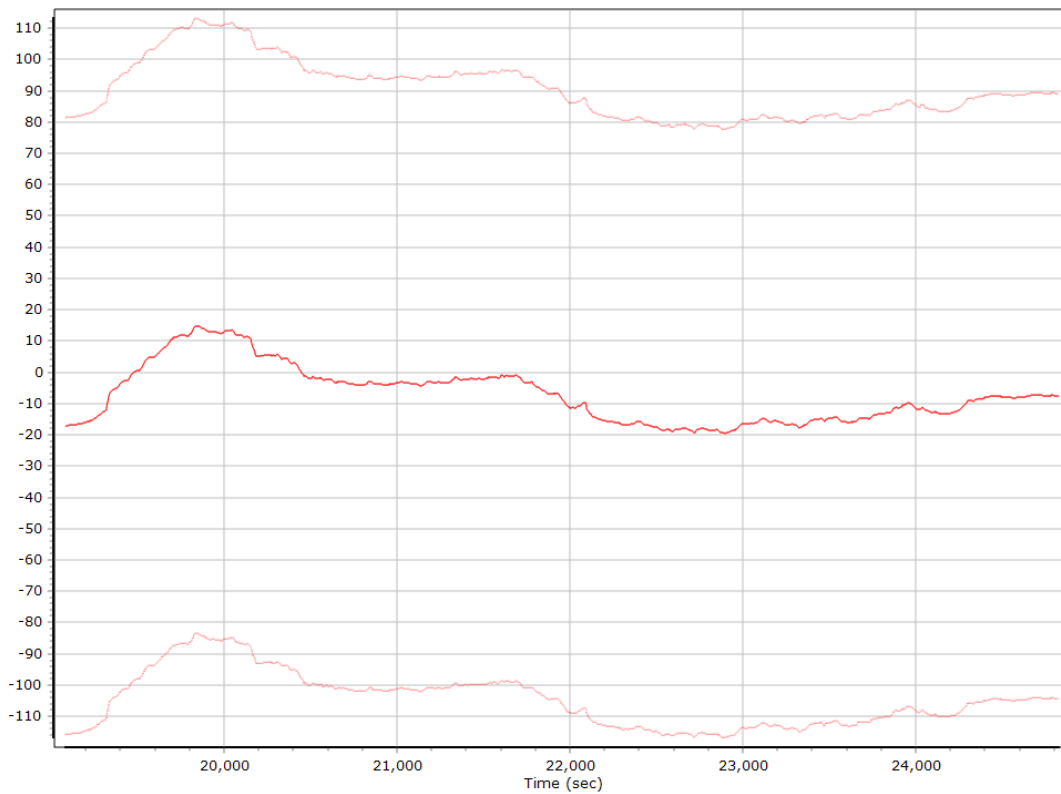
X Accelerometer Bias (micro-g)



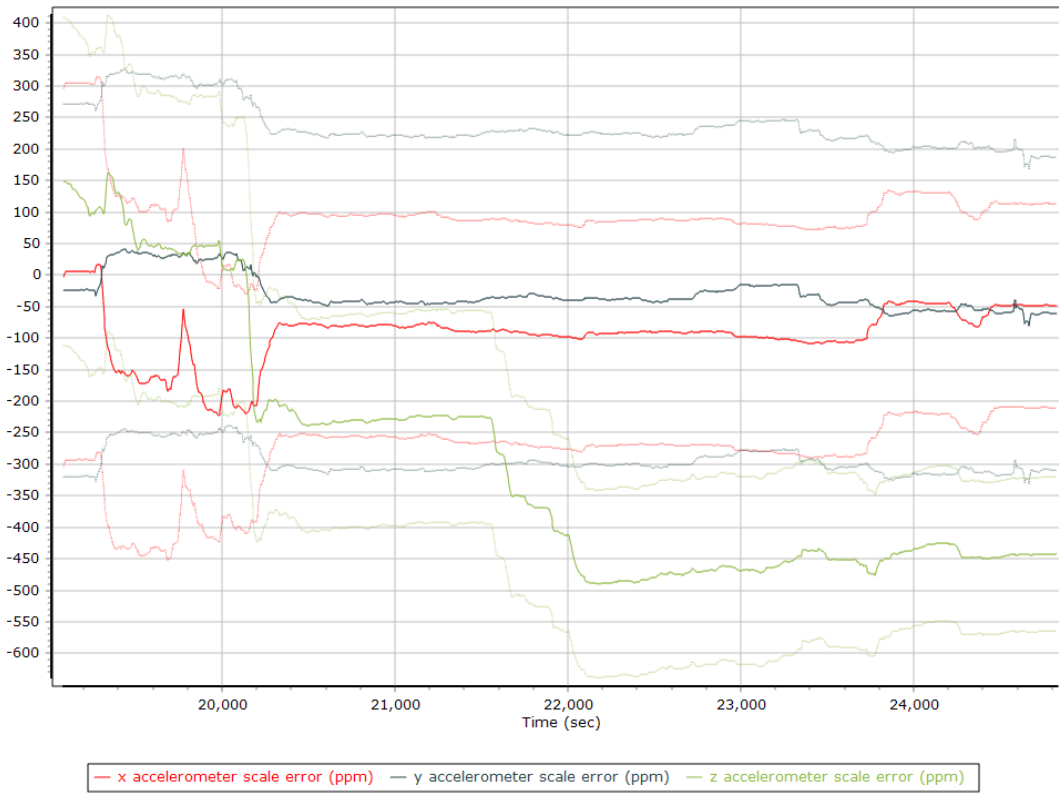
Y Accelerometer Bias (micro-g)



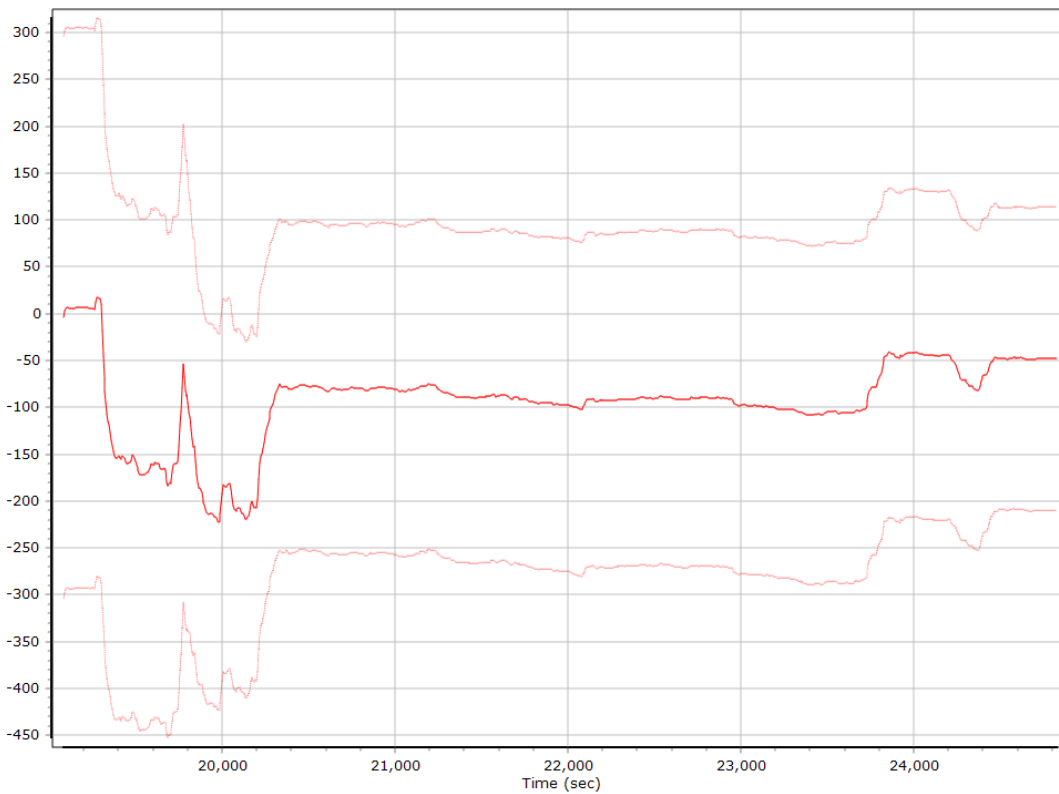
Z Accelerometer Bias (micro-g)



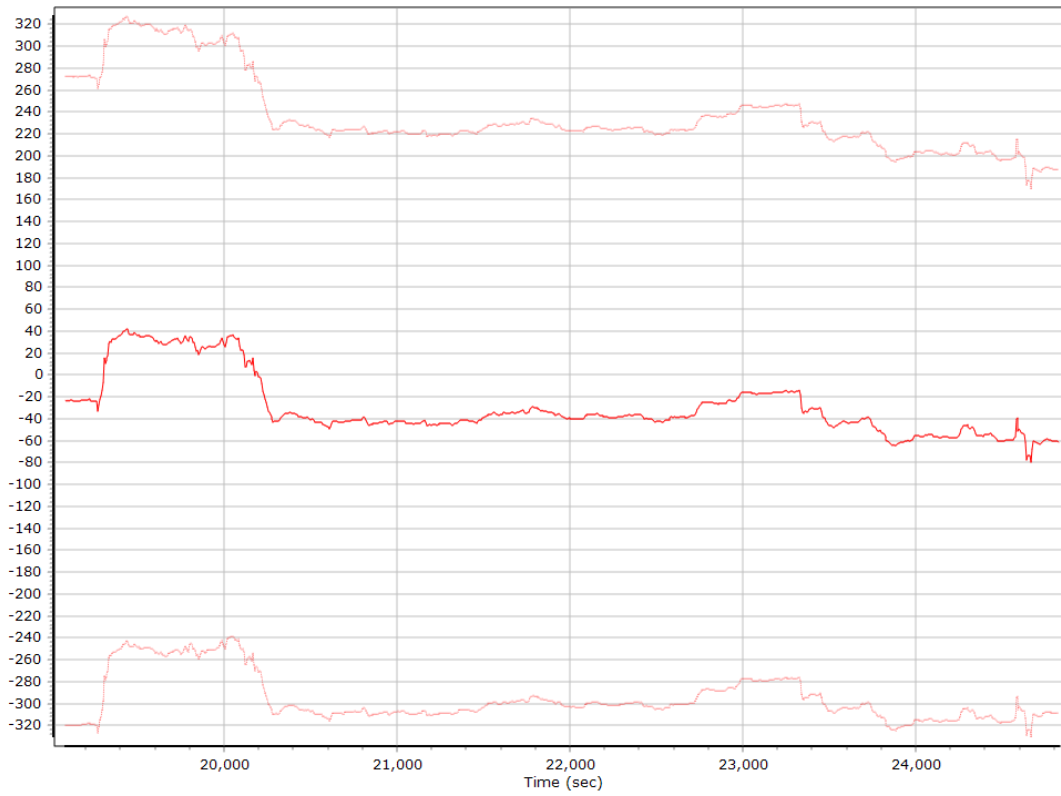
Accelerometer Scale Error (ppm)



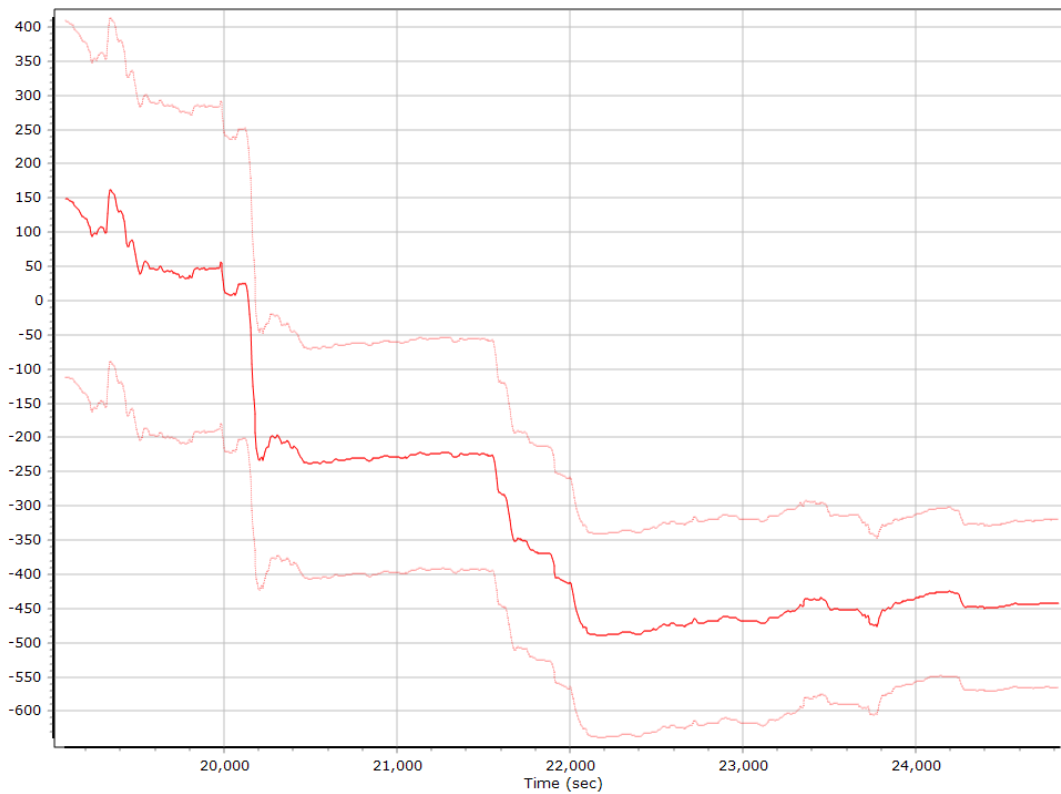
X Accelerometer Scale Error (ppm)



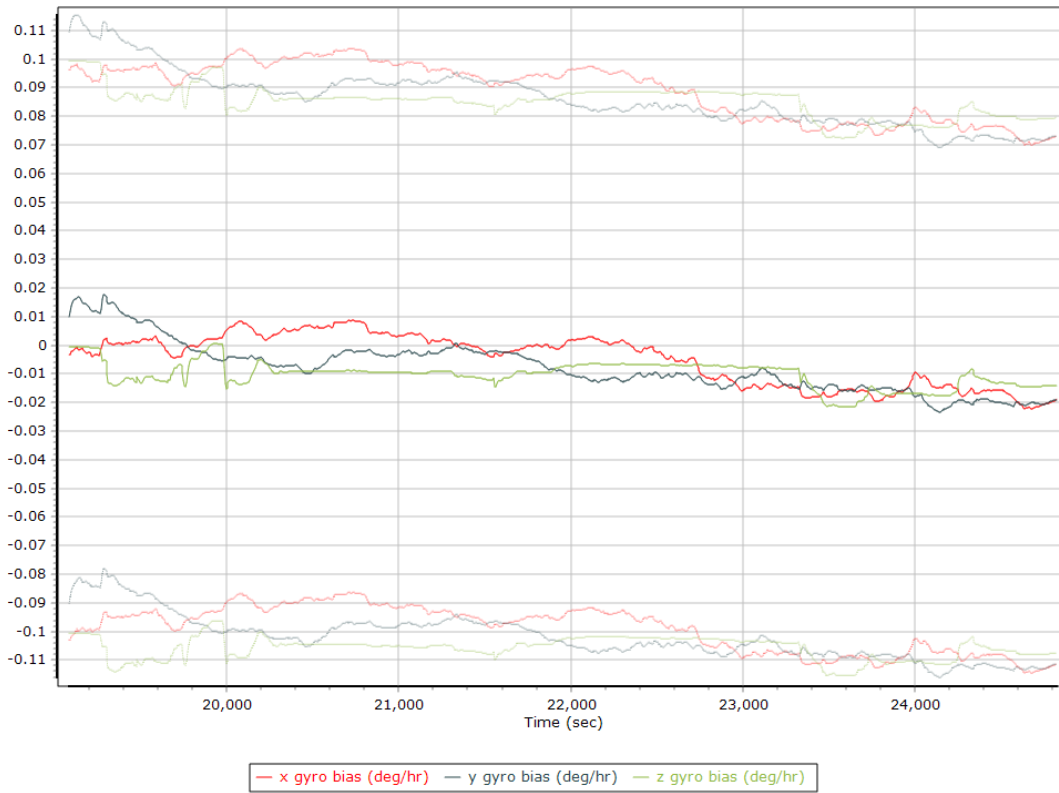
Y Accelerometer Scale Error (ppm)



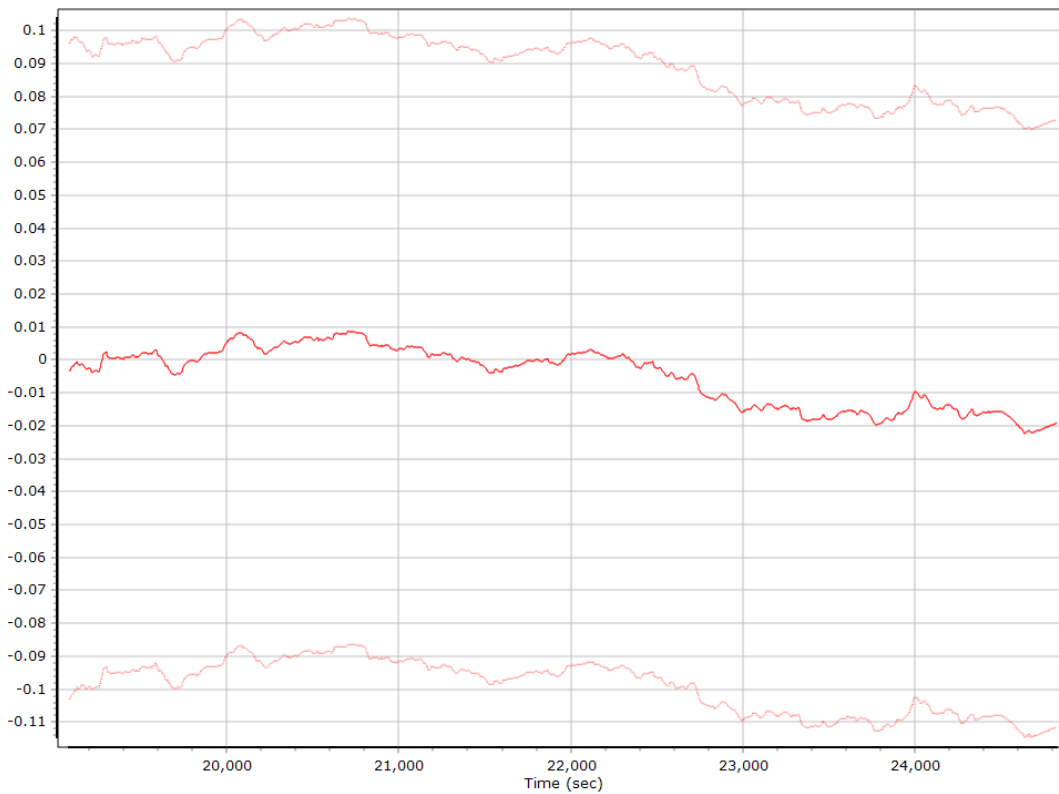
Z Accelerometer Scale Error (ppm)



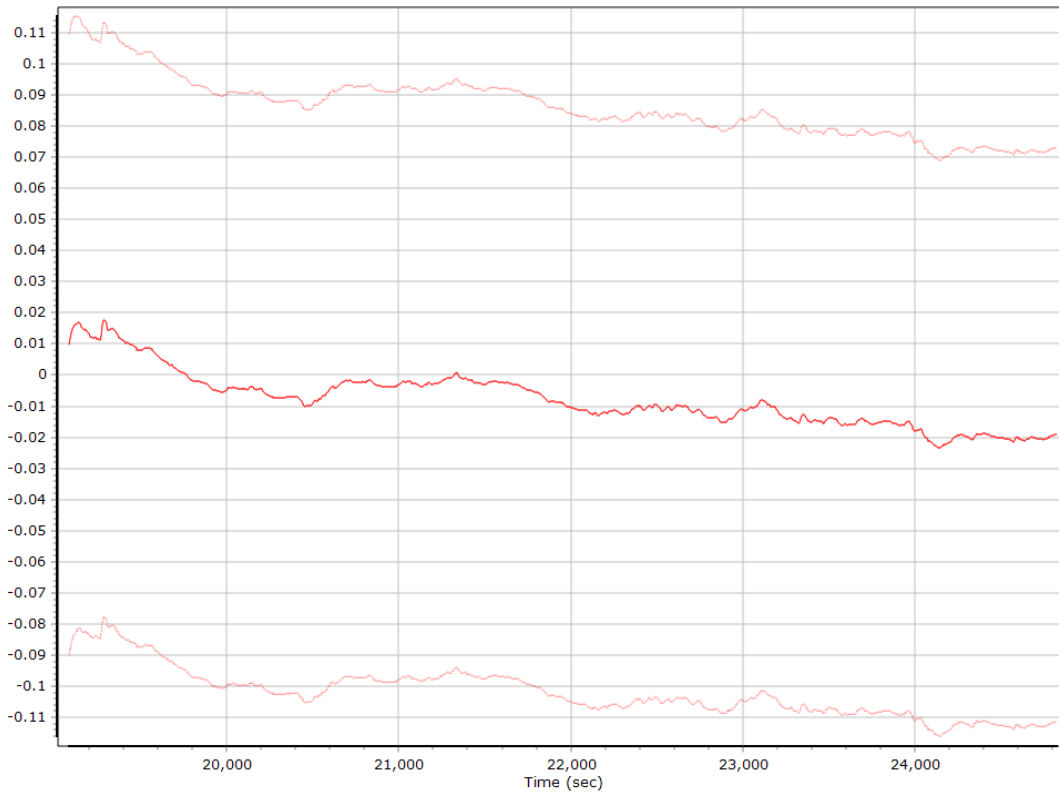
Gyro Bias (deg/h)



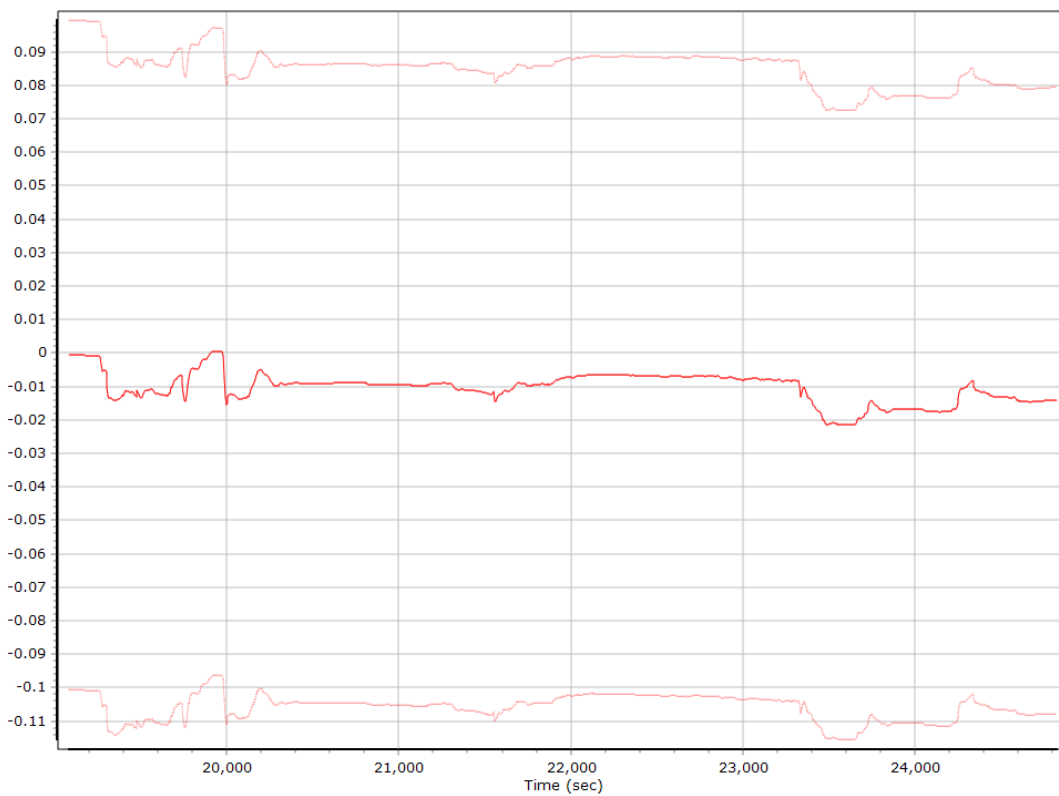
X Gyro Bias (deg/h)



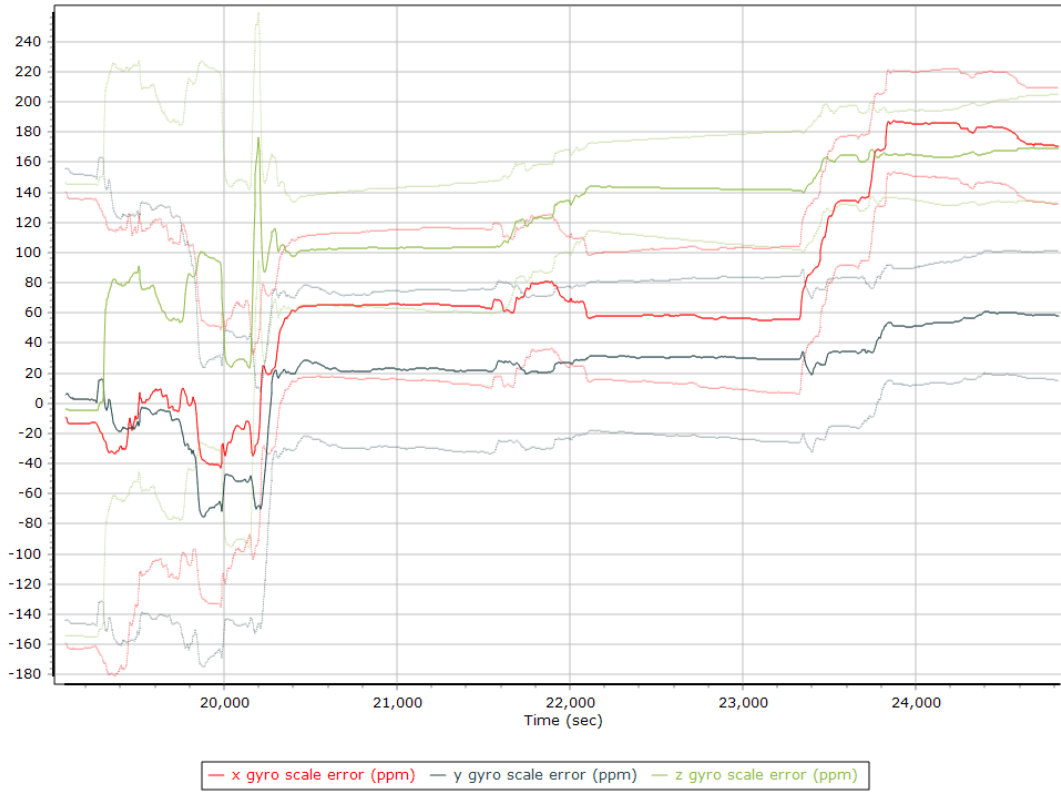
Y Gyro Bias (deg/h)



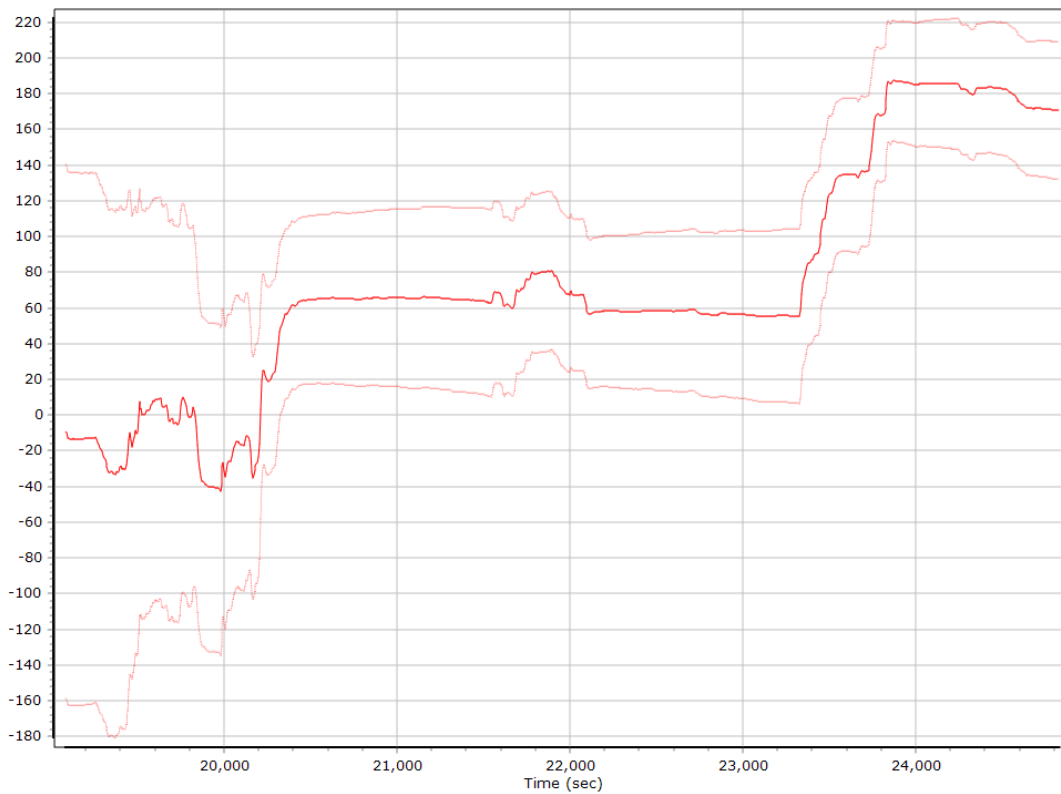
Z Gyro Bias (deg/h)



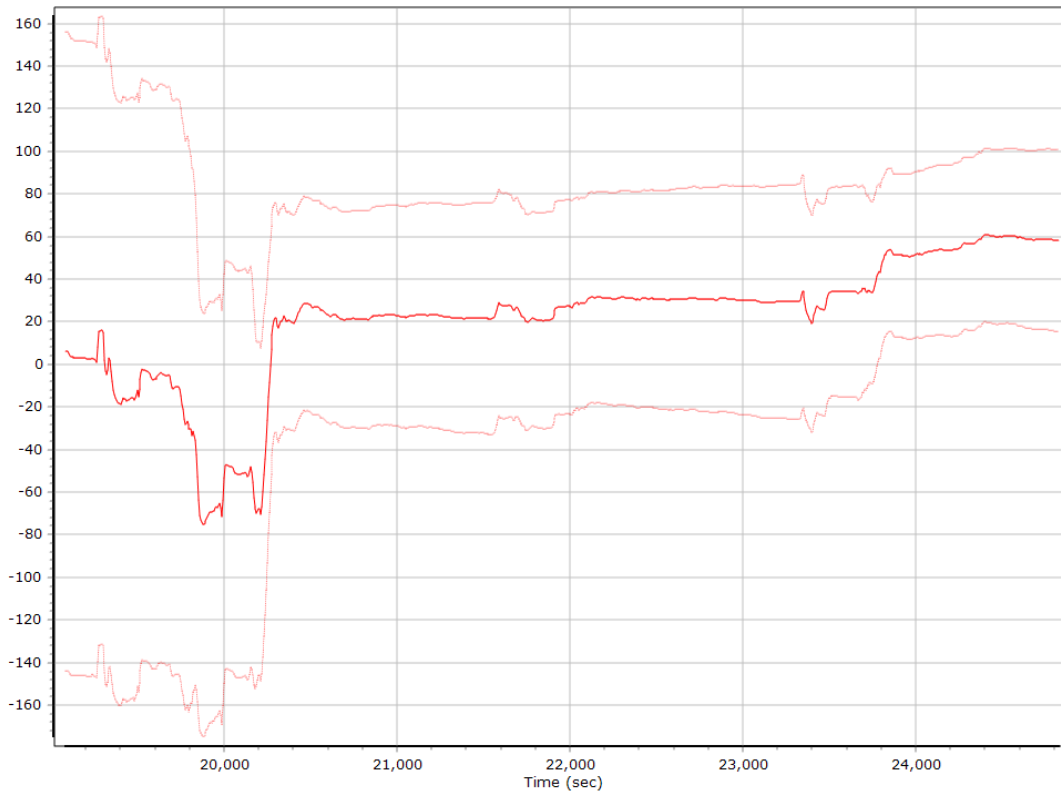
Gyro Scale Error (ppm)



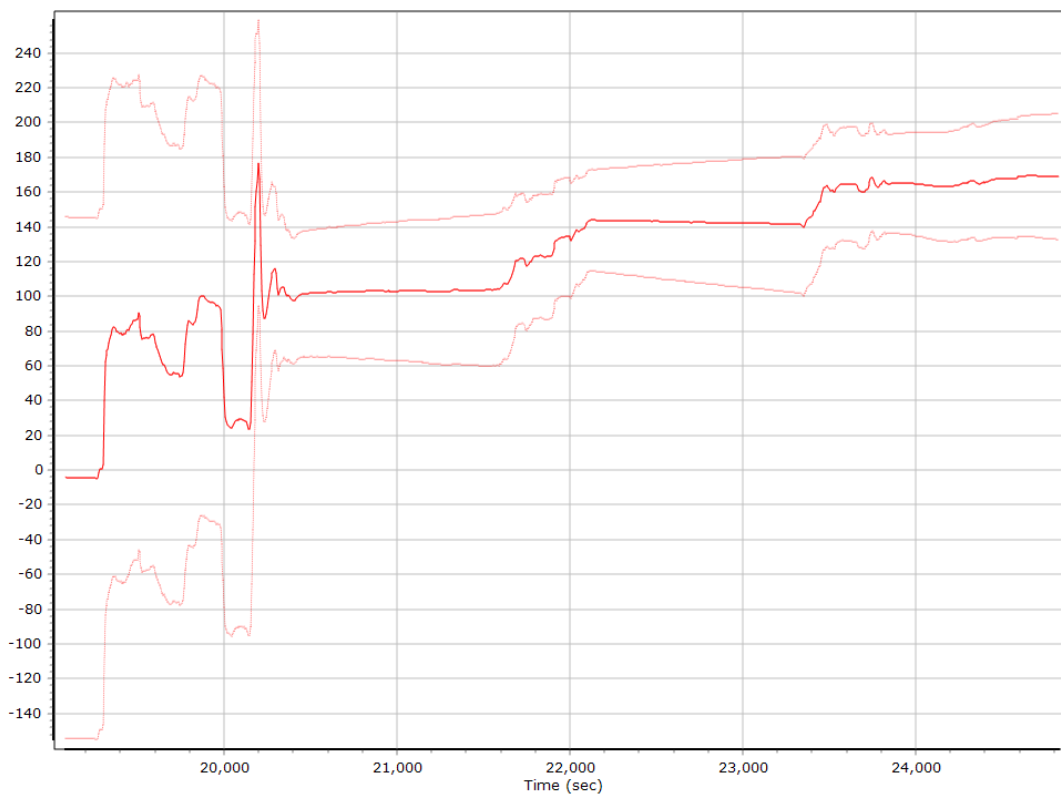
X Gyro Scale Error (ppm)



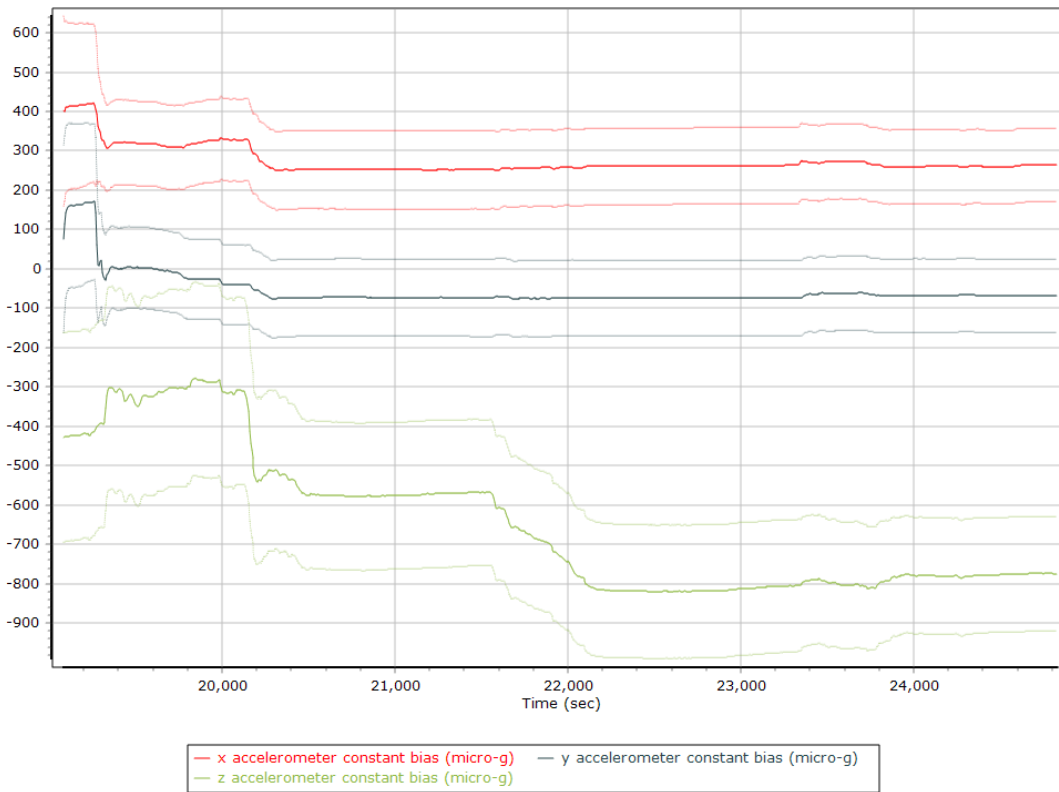
Y Gyro Scale Error (ppm)



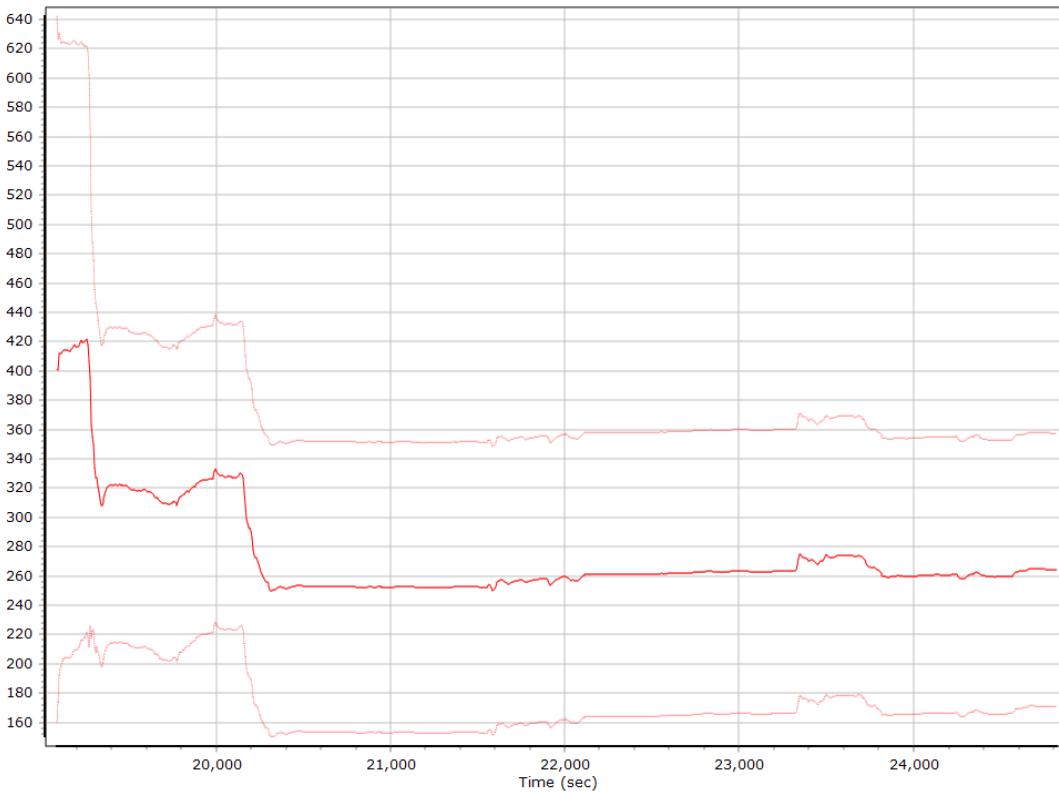
Z Gyro Scale Error (ppm)



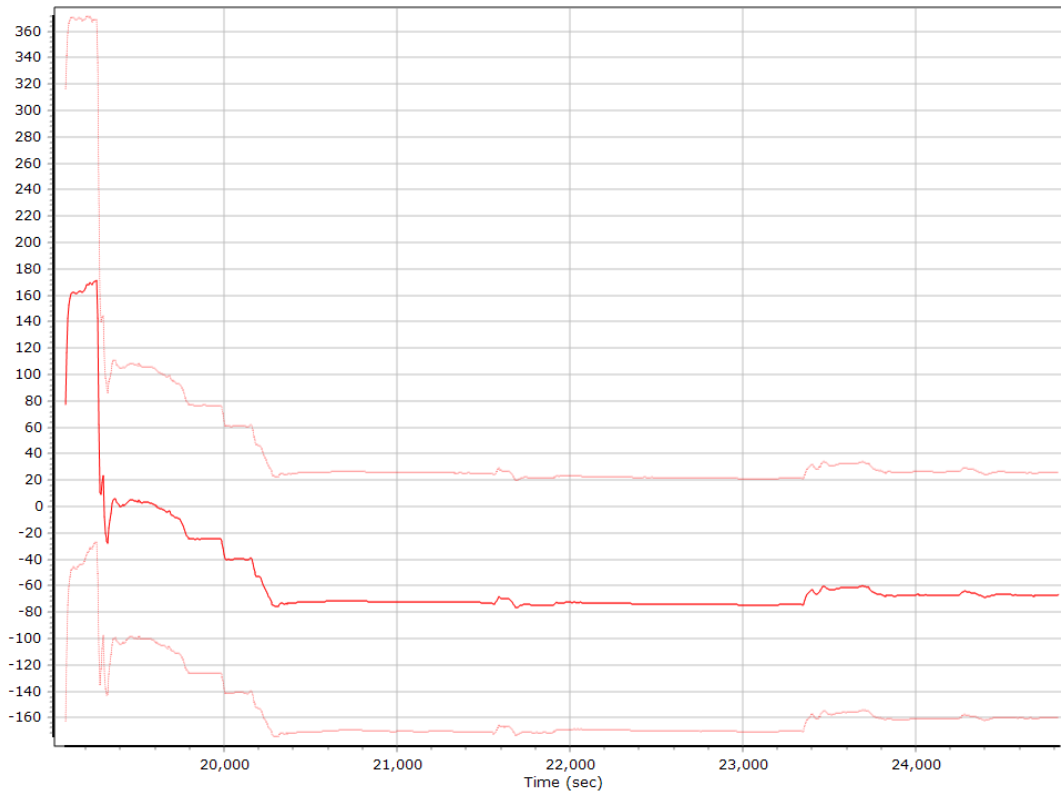
Forward Processed Estimated Constant Errors, Reference Frame Accelerometer Bias (micro-g)



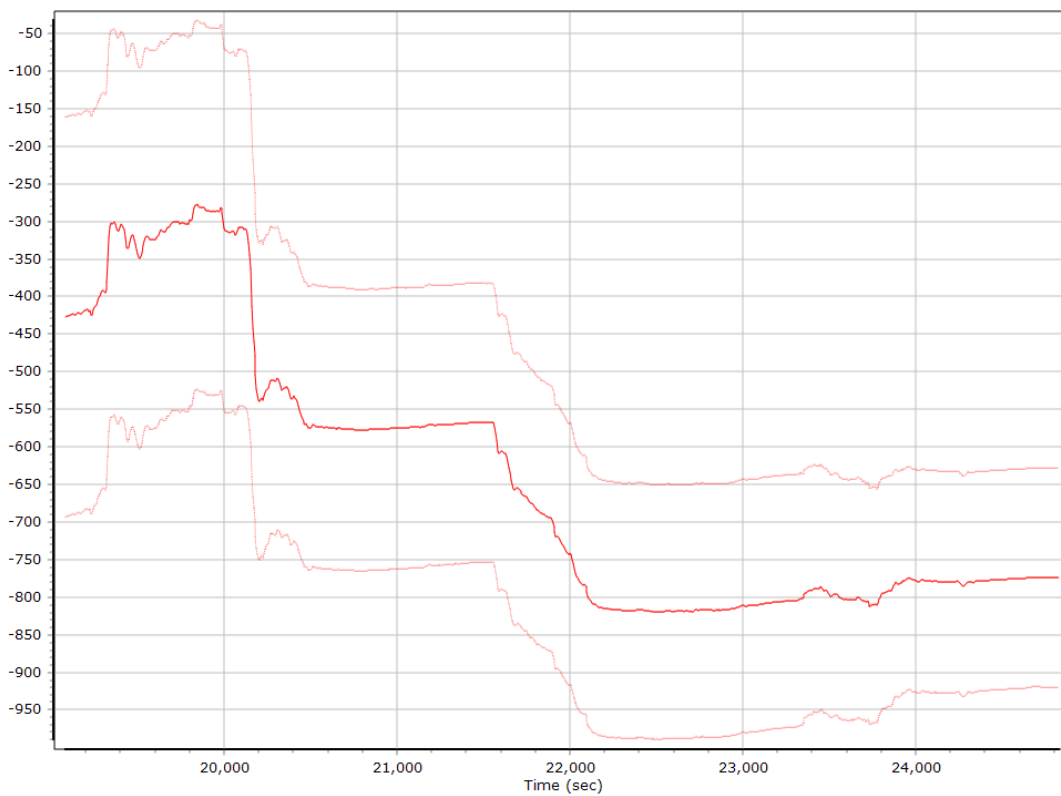
X Accelerometer Bias (micro-g)



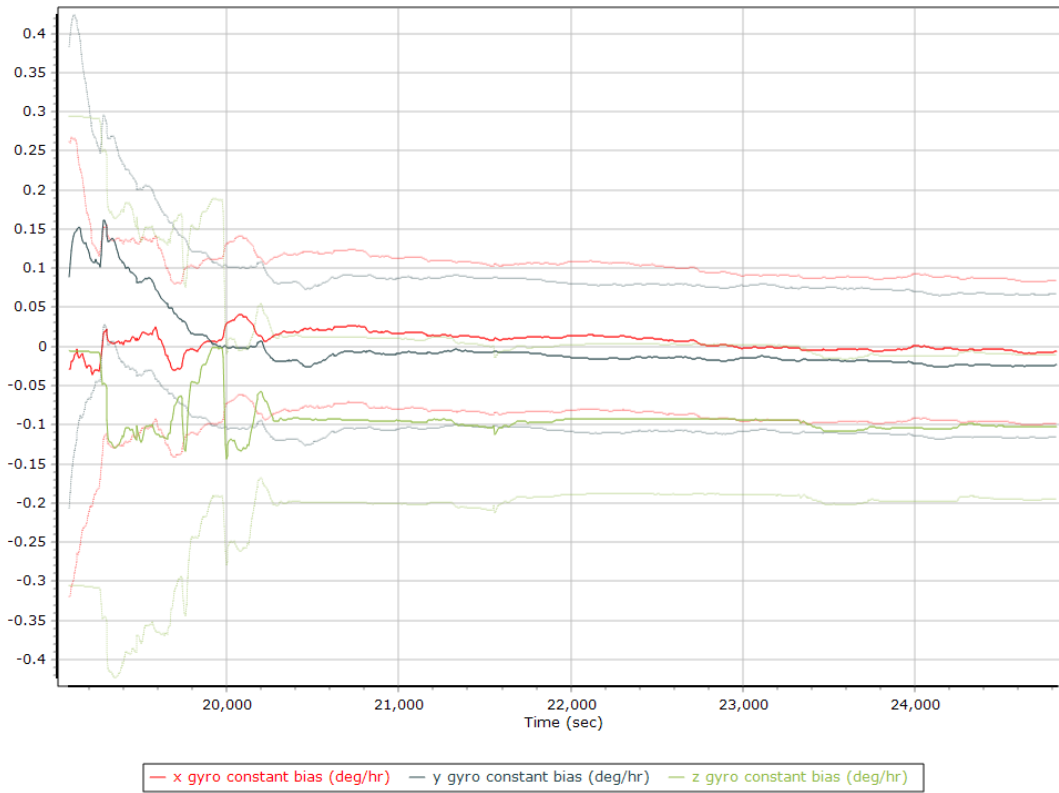
Y Accelerometer Bias (micro-g)



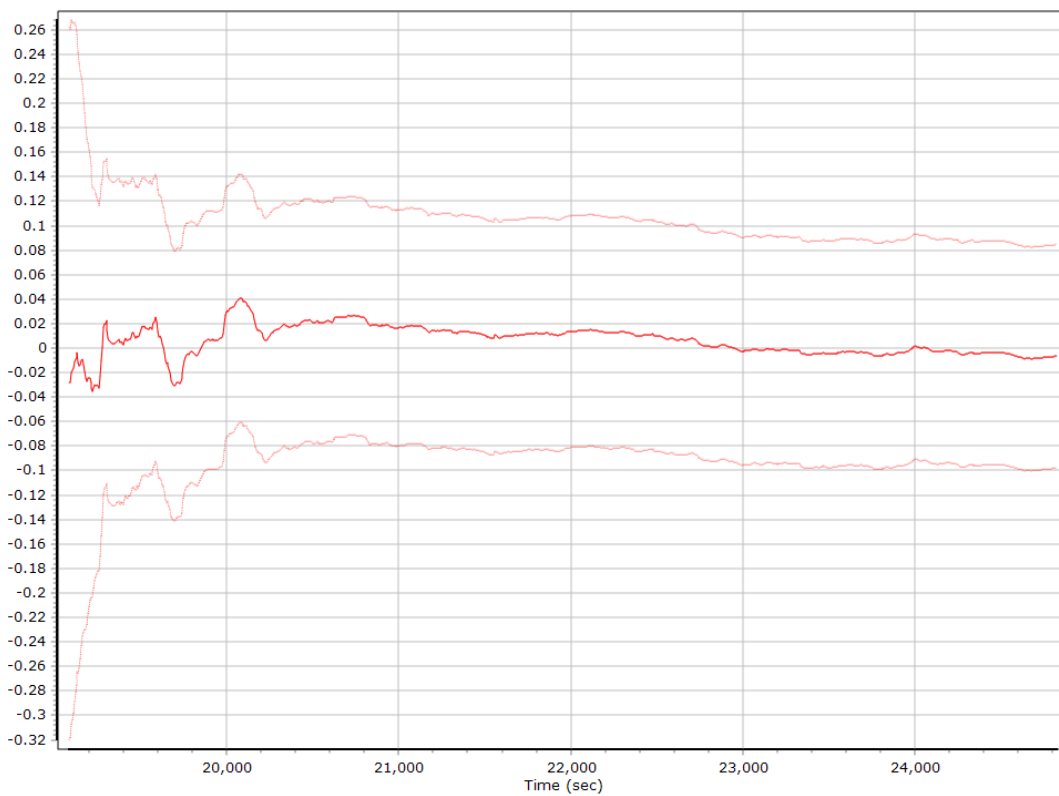
Z Accelerometer Bias (micro-g)



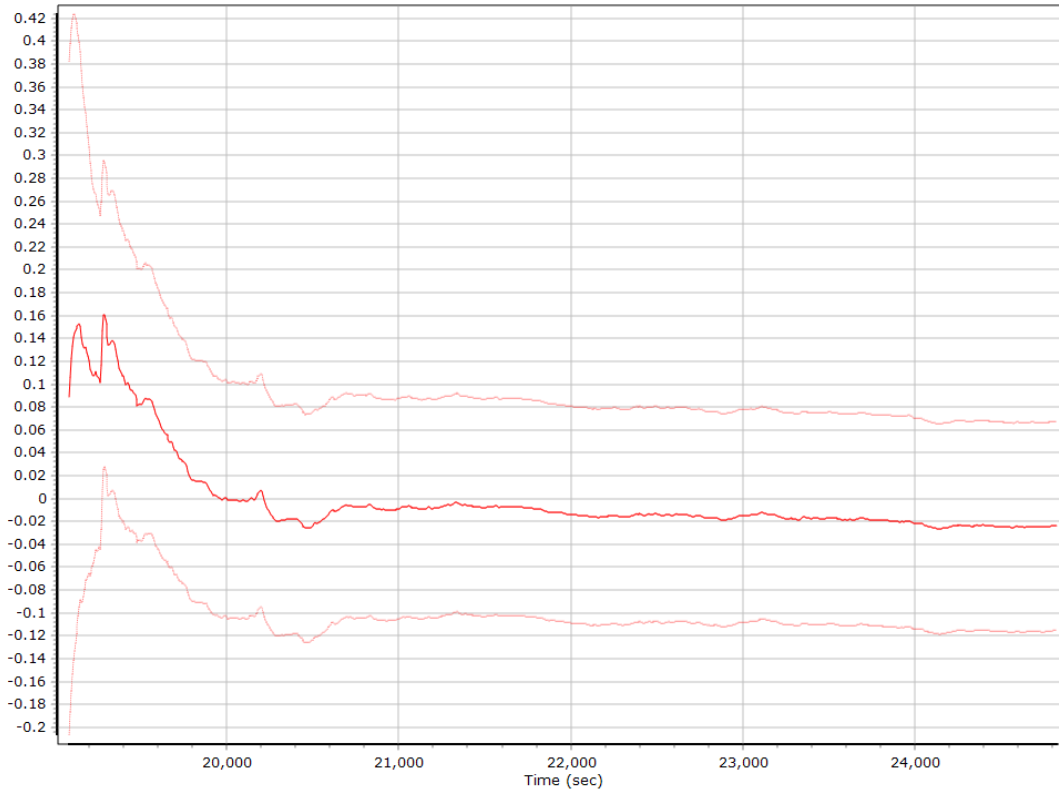
Gyro Bias (deg/h)



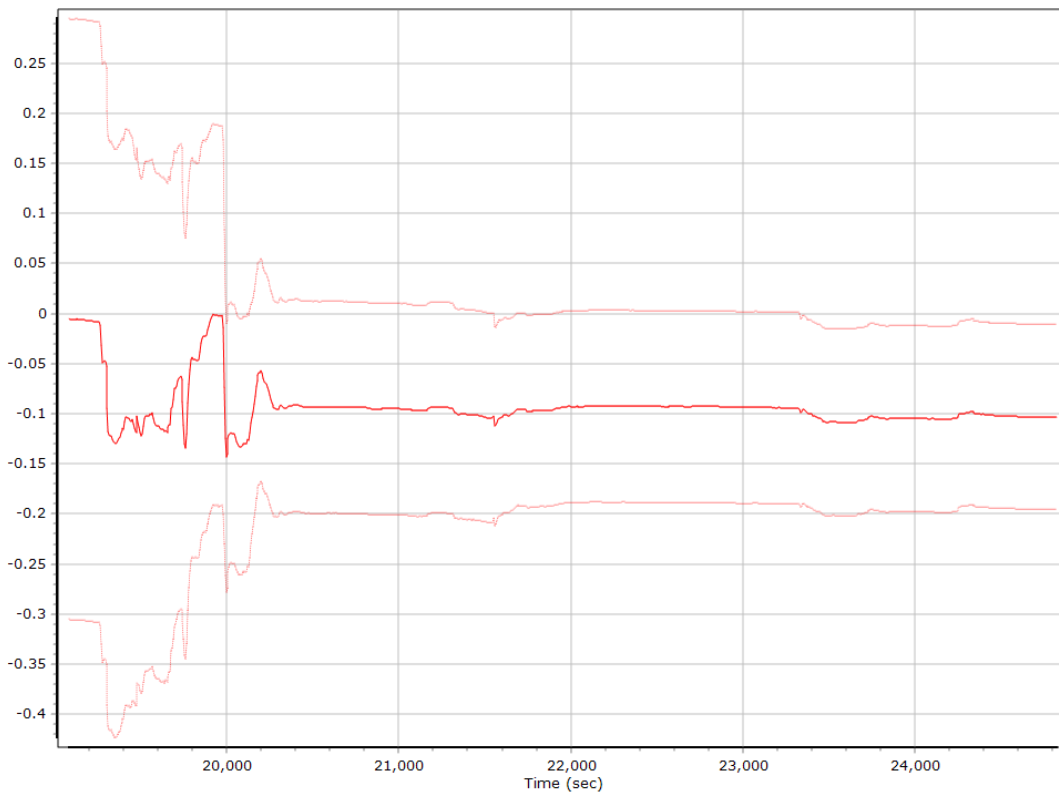
X Gyro Bias (deg/h)



Y Gyro Bias (deg/h)

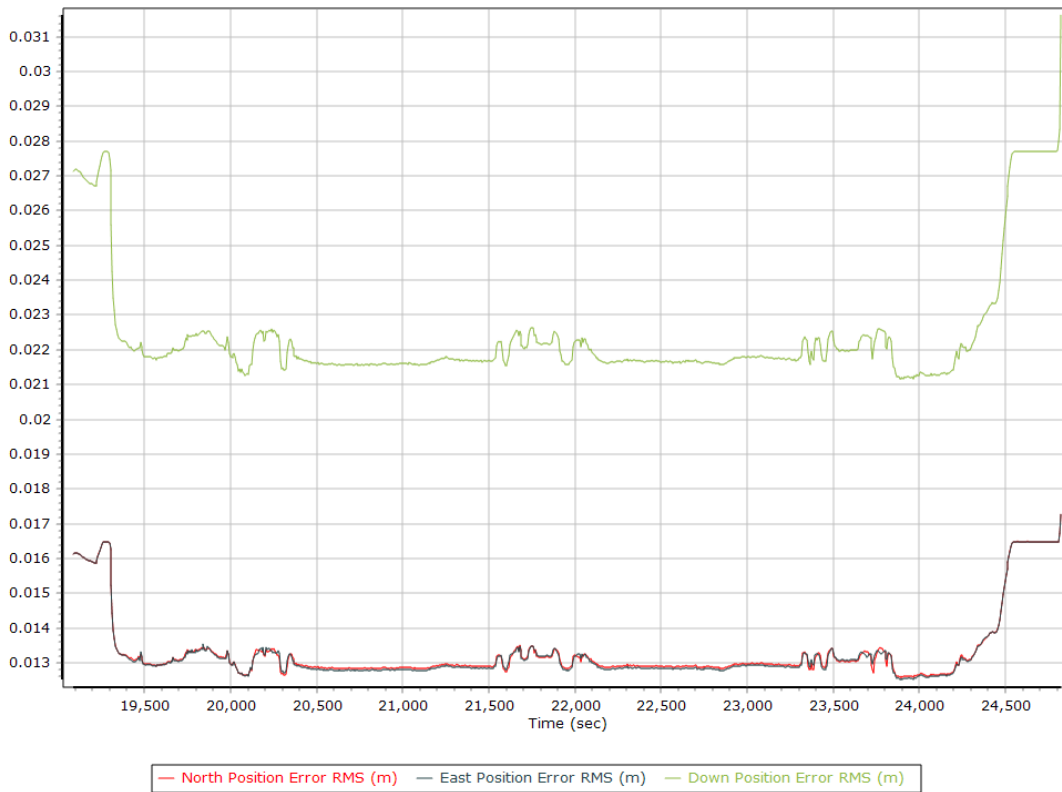


Z Gyro Bias (deg/h)

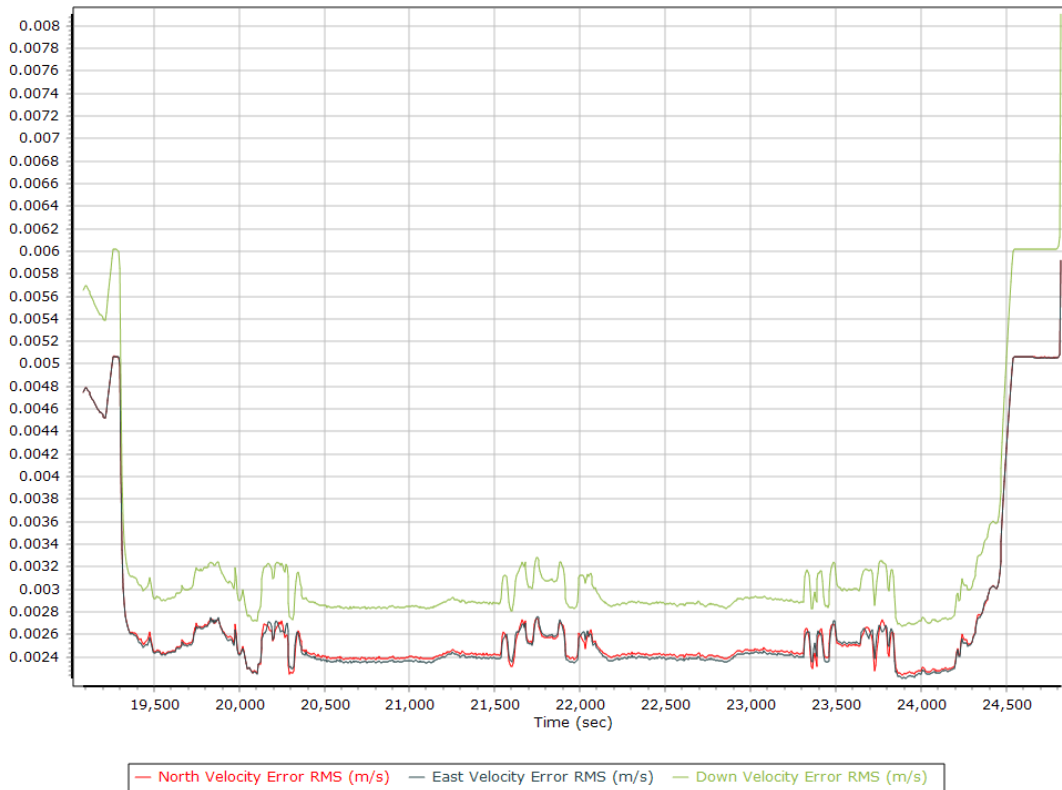


Smoothed Performance Metrics

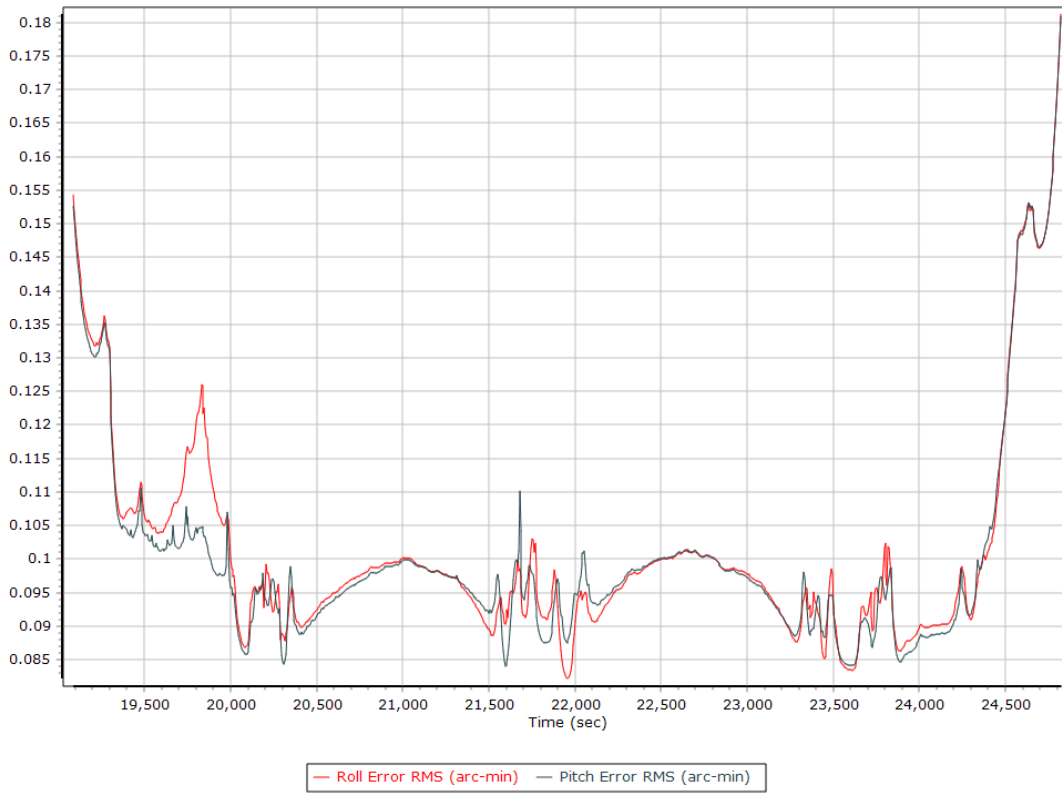
Position Error RMS (m)



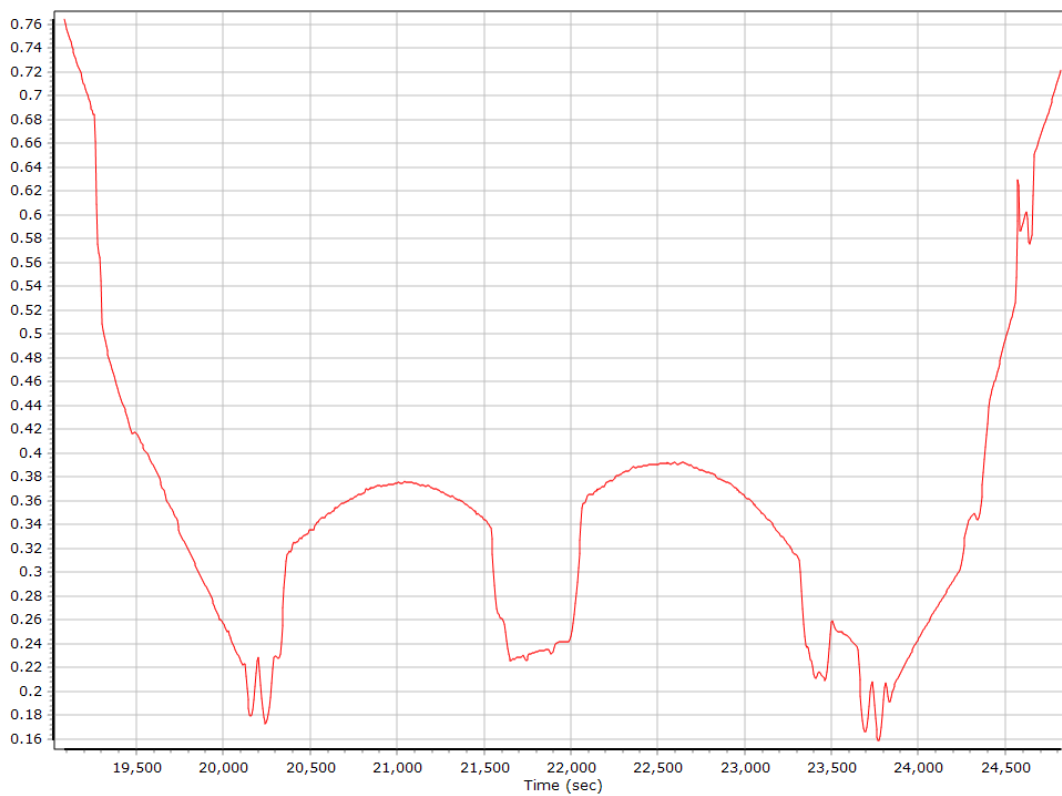
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

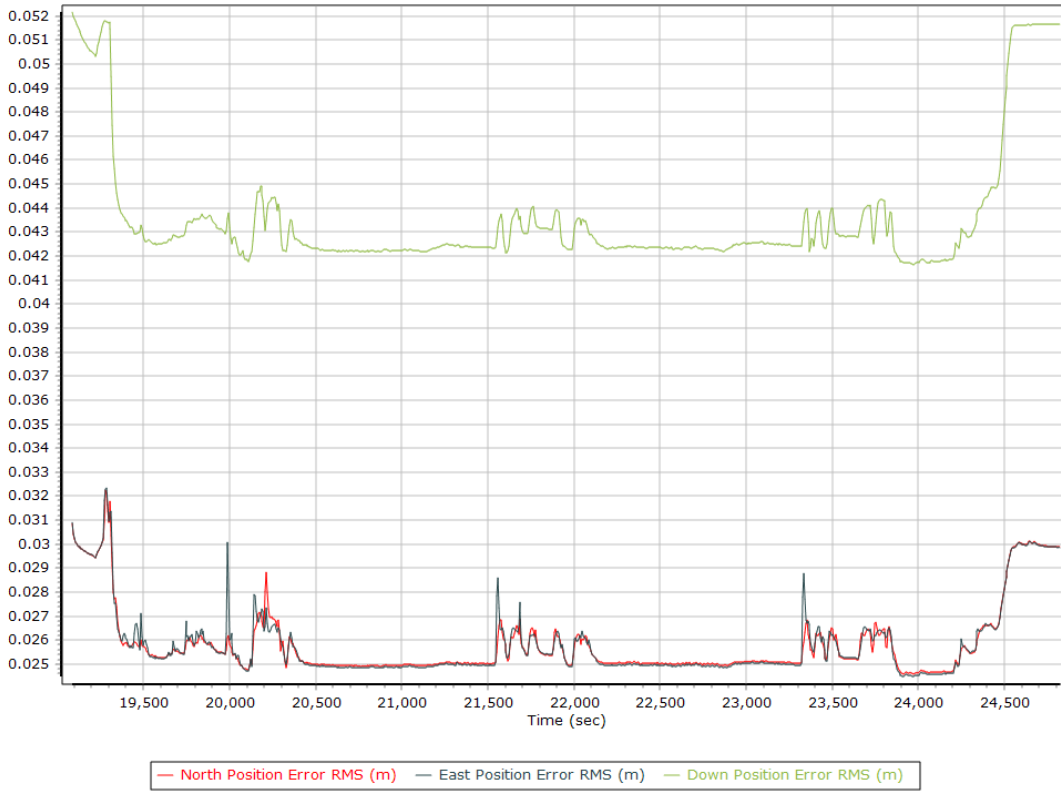


Heading Error RMS (arc-min)

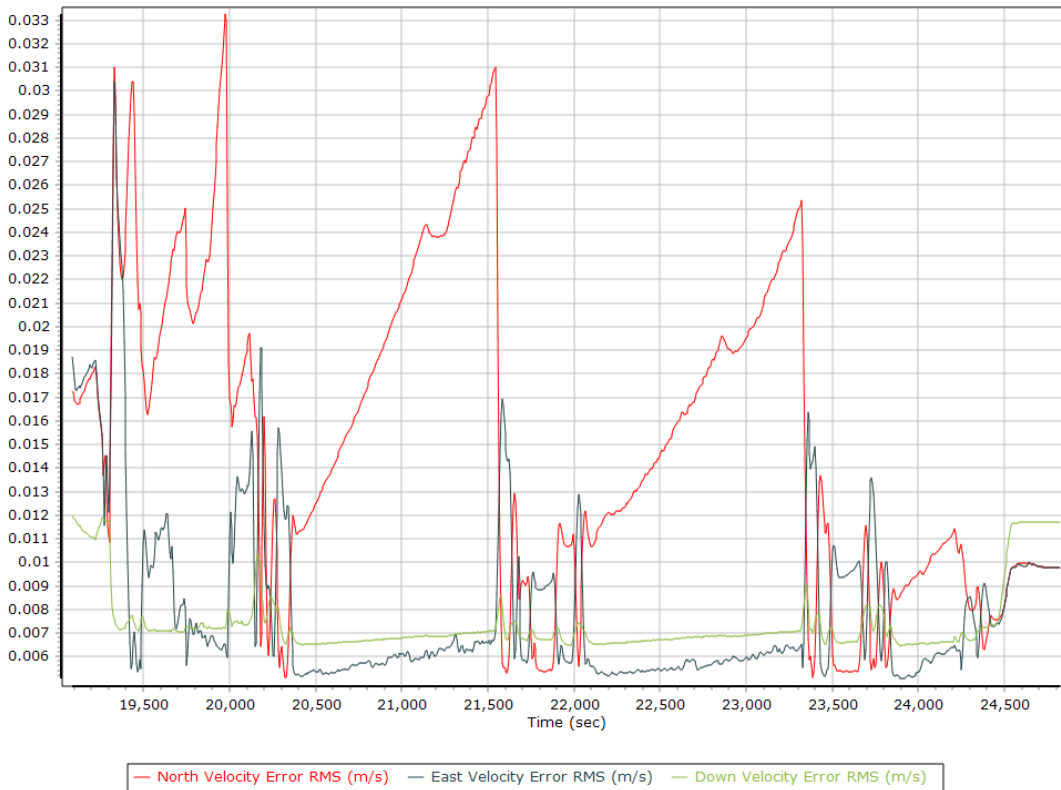


Forward Processed Performance Metrics

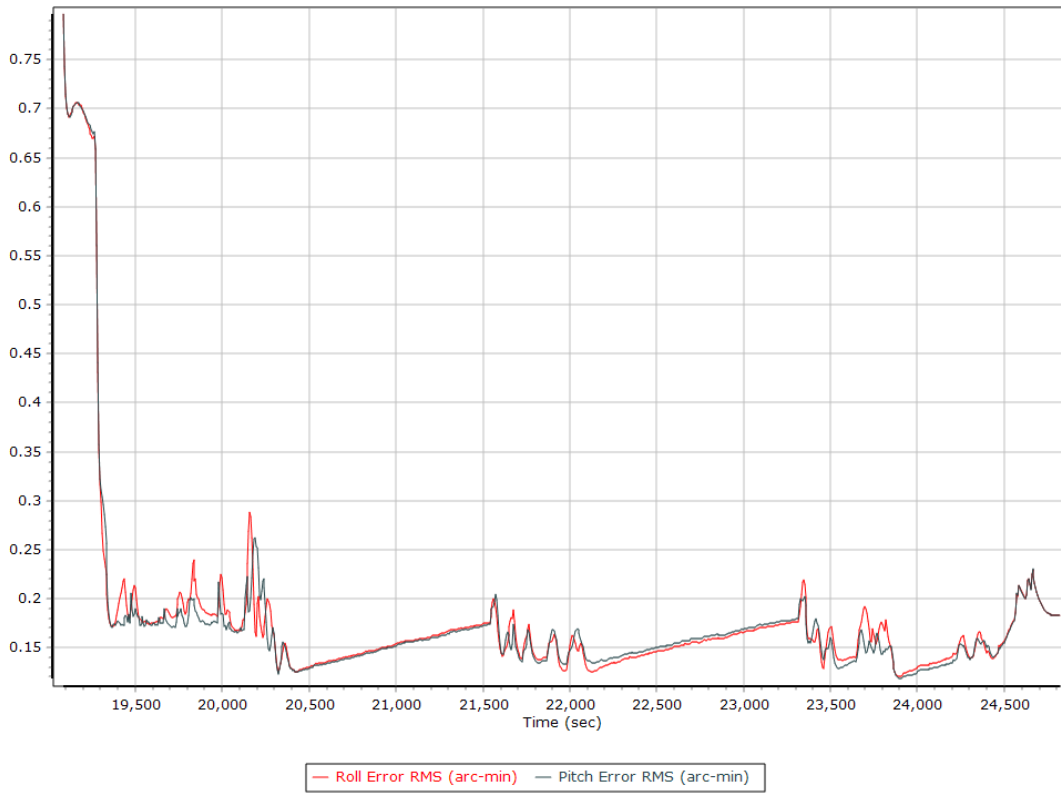
Position Error RMS (m)



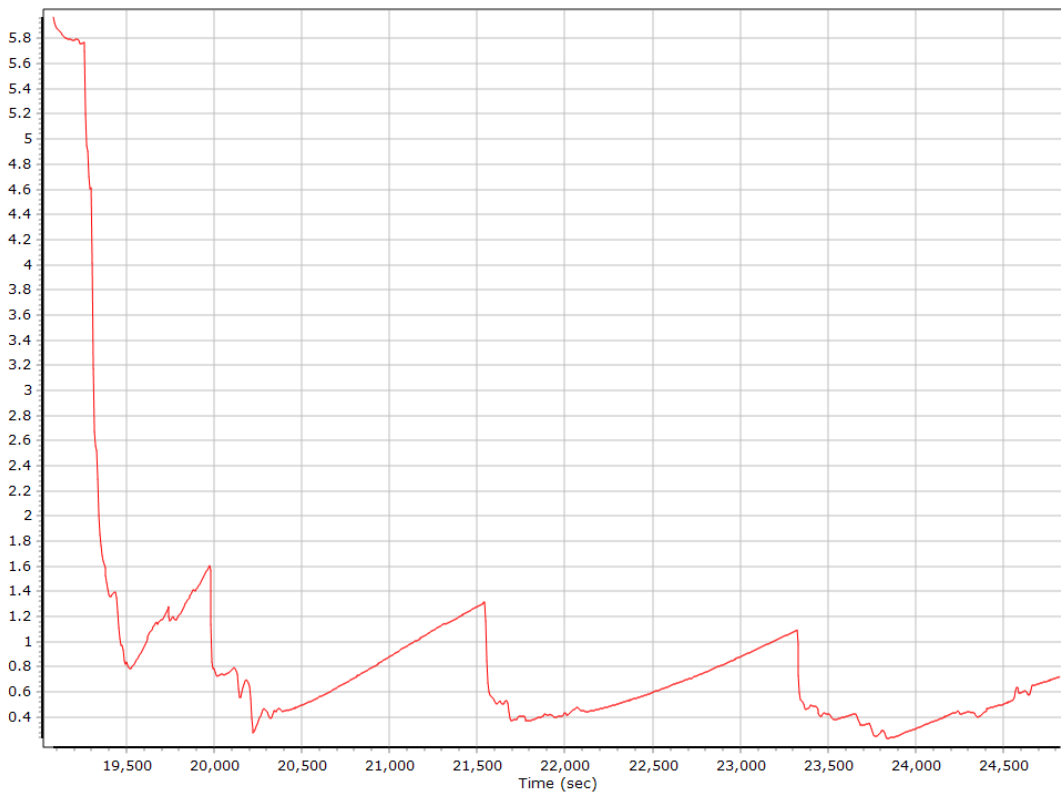
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

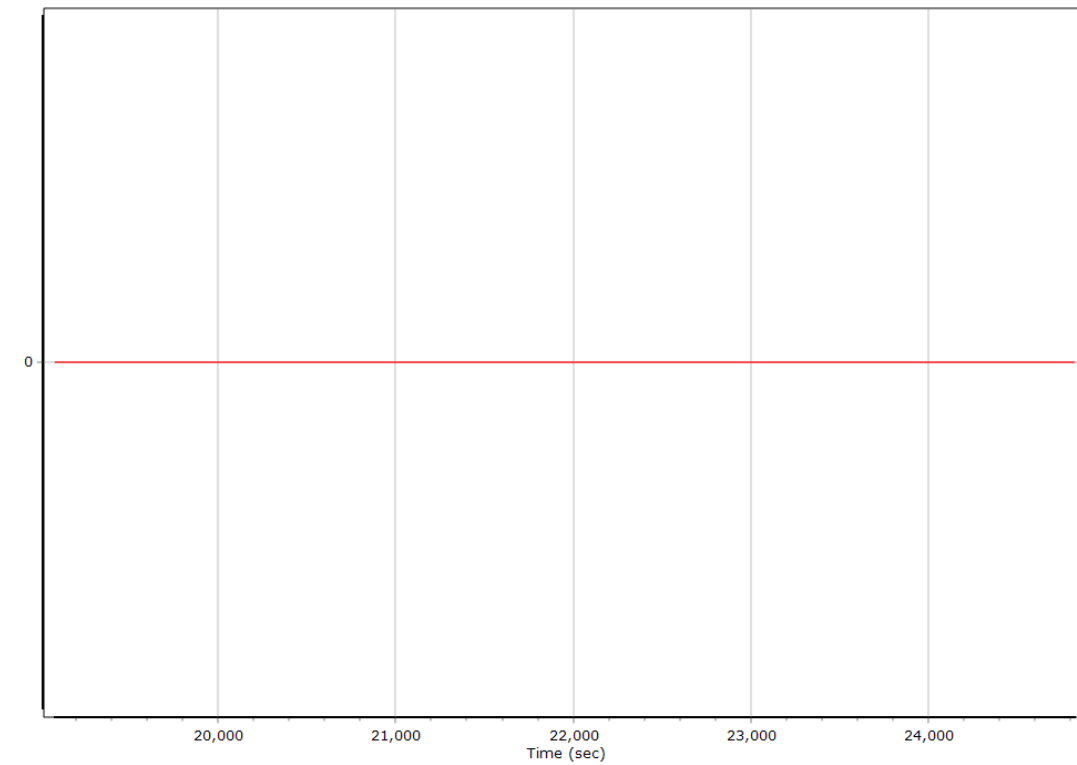


Heading Error RMS (arc-min)



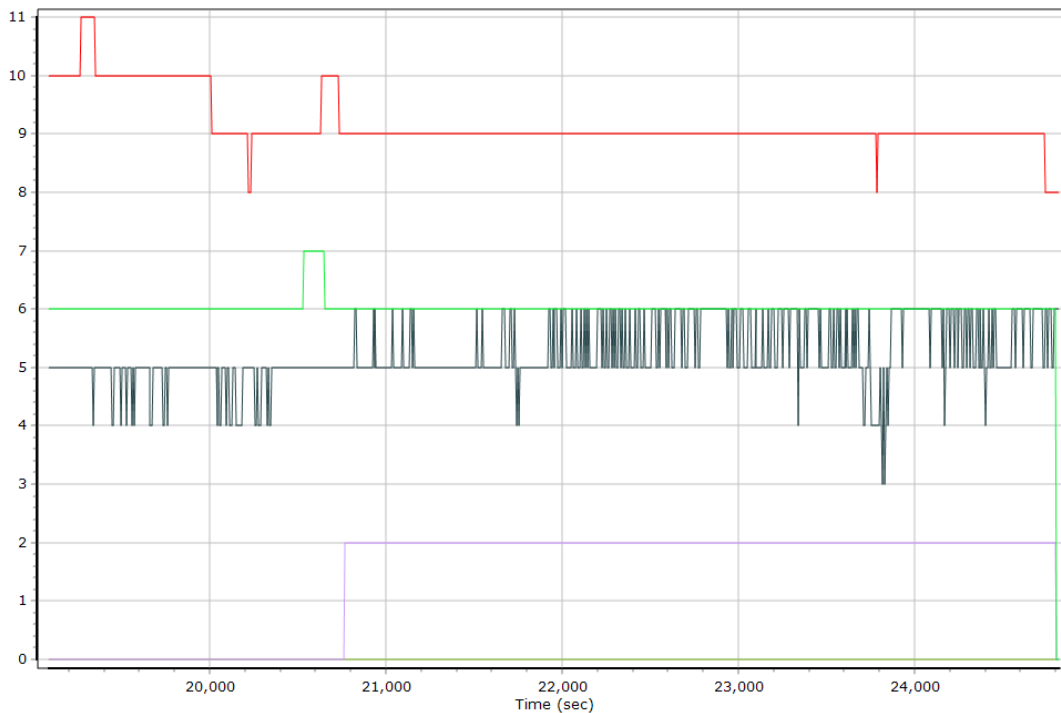
Forward Processed Solution Status

Processing Mode



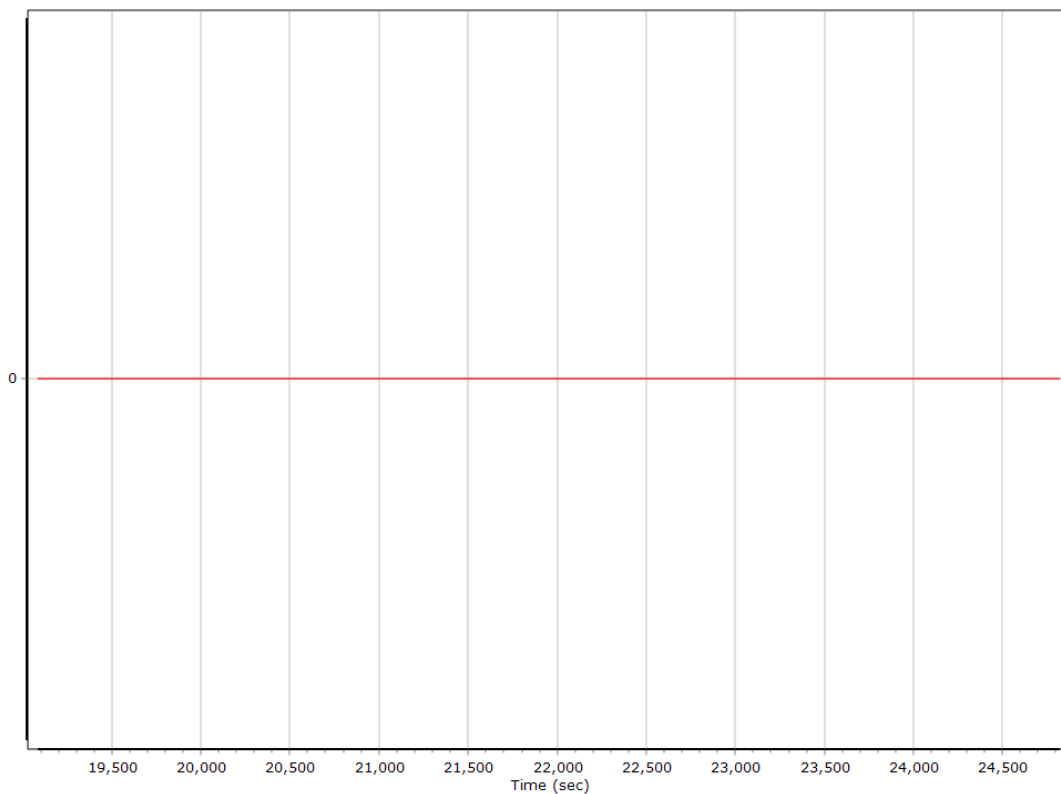
0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = C/A, 7 = GNSS Nav, 8 = DR

Number of Satellites



— Number of GPS Satellites — Number of GLONASS Satellites — Number of QZSS Satellites
— Number of BEIDOU Satellites — Number of GALILEO Satellites

Baseline Length



Export Summary Section 1

Export file	sbet_11888_NAD83(2011).out		
Export format	Custom Smoothed BET		
Solution in use	Post-processed		
Output rate	All Records		
Reference to Output lever arm (m)	0.000	0.000	0.000
Reference mounting angles (deg)	0.000	0.000	0.000
Output units (Coordinate / Lat & Lon)	Meter	Meter	
Export start time	19026.004 (12/06/2020 05:17:06)		
Export end time	24825.000 (12/06/2020 06:53:45)		
Height option	Ellipsoid Height		
WGS84 height flag	False		
Grid			
Zone			
Datum	NAD83 (2011)		
Ellipsoid	GRS 1980		
Local Transformation			
Target Epoch	2010		

Export Summary Section 2

Export file	lever_arm_values.txt		
Export format	ReferenceToPrimaryLeverArms		
Solution in use	Post-processed		
Output rate	All Records		
Reference to Output lever arm (m)	0.000	0.000	0.000
Reference mounting angles (deg)	0.000	0.000	0.000
Output units (Coordinate / Lat & Lon)	Meter	Meter	
Export start time	19026.004 (12/06/2020 05:17:06)		
Export end time	24825.000 (12/06/2020 06:53:45)		
Height option	Ellipsoid Height		
WGS84 height flag	False		
Grid	Universal Transverse Mercator		
Zone	UTM North 14 (102W to 96W)		
Datum	WGS84		
Ellipsoid	WGS84		
Local Transformation	NONE		
Target Epoch	2010		

EO Summary Section 1

EO file			
EO format	ZI Imaging		
Lever arm (m)	0.000	0.000	0.000
Boresight angles (arcmin)	0.0000	0.0000	0.0000
Output rate	All Records		
Rotation sequence	x omega	y phi	z kappa
Local shift (m)	0.000	0.000	0.000
Output units (coordinate / angle / lat & lon)	Meter	Degree	Deg Decimal
Height option	Ellipsoid Height		
WGS84 height flag	False		
Scale height option	False		
Kappa cardinal rotation (deg)	0		
Solution in use	Post-processed		
EO start time	19026.004 (12/06/2020 05:17:06)		
EO end time	24825.000 (12/06/2020 06:53:45)		
Grid	Universal Transverse Mercator		
Zone	UTM North 14 (102W to 96W)		
Datum	NAD83 (2011)		
Ellipsoid	GRS 1980		
Local Transformation	NONE		
Target Epoch	2010		