

## General Information

### Mission Information

Project name	201126_A_5060380_nad2011_FINAL
Processing date	2020-11-30 18:32:59
Mission date	2020-11-26 13:55:39
Mission duration	04:17:54.000
Processing mode	IN-Fusion PP-RTX

### Rover Hardware Information

Product	POS AV 610 VER6 HW2.5-12
Serial number	S/N7769
IMU type	57
Receiver type	BD982
Antenna type	AV39

## Project File List

### Rover Data Files

File name	File type
201126a.072	POS Data
201126a.073	POS Data
201126a.074	POS Data
201126a.075	POS Data
201126a.076	POS Data
201126a.077	POS Data
201126a.078	POS Data
201126a.079	POS Data
201126a.080	POS Data
201126a.081	POS Data
201126a.082	POS Data
201126a.083	POS Data
201126a.084	POS Data
201126a.085	POS Data
201126a.086	POS Data
201126a.087	POS Data
201126a.088	POS Data
201126a.089	POS Data
201126a.090	POS Data
201126a.091	POS Data
201126a.092	POS Data
201126a.093	POS Data
201126a.094	POS Data
201126a.095	POS Data

### Input Files

File Name	File Type
Ephm3310.20g	GLONASS Broadcast Ephemeris
Ephm3310.20n	GPS Broadcast Ephemeris

### Output Files

Filename	File type
sbet_201126_A_5060380_nad2011_FINAL.out	SBET Trajectory File

## Rover Data Summary

First raw data file	201126a.072		
Last raw data file	201126a.095		
Start GPS week	2133		
Start time	395743.063 (11/26/2020 1:55:43 PM)		
End time	411213.876 (11/26/2020 6:13:33 PM)		
Start of fine alignment	395942.863 (11/26/2020 1:59:02 PM)		
Available subsystems	Primary GNSS, IMU		
POS Event Input	None		
Correction data	None		
<b>IMU Installation Lever Arms &amp; Mounting Angles</b>			
Reference to IMU lever arm (m)	0.000	0.000	0.000
Reference to IMU mounting angles (deg)	0.000	0.000	180.000
Reference to Primary GNSS lever arm (m)	0.548	-0.432	-0.960
Reference to Primary GNSS lever arm std dev (m)	-1.000		
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

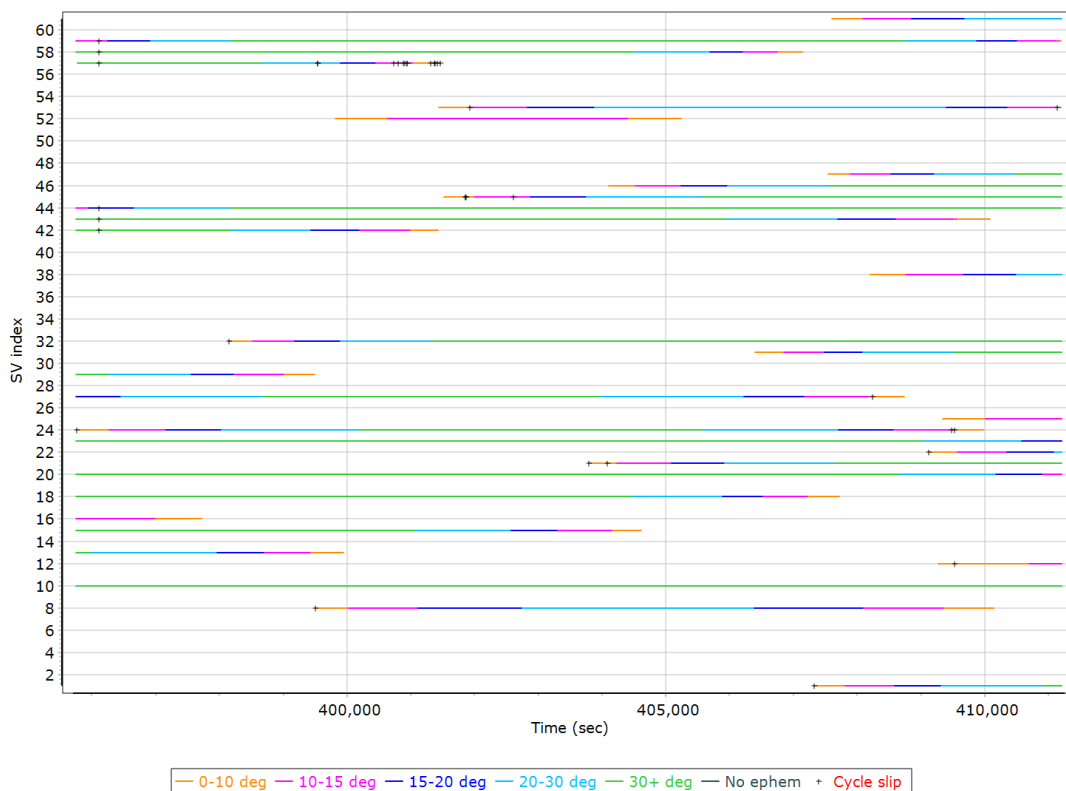
## Rover Data QC

### Raw IMU Import QC Summary

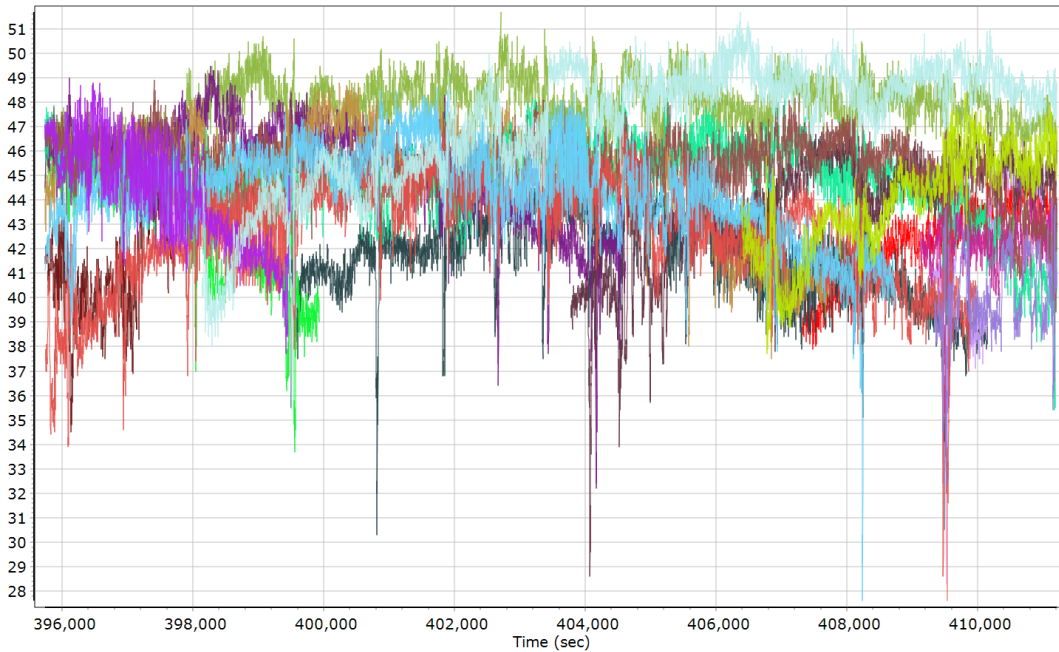
IMU data input file	imu_201126_A_5060380_nad2011_FINAL.dat
IMU data check log file	imudt_201126_A_5060380_nad2011_FINAL.log
IMU Records Processed	3094693
Termination Status	Warnings
IMU Anomalies	1
<b>IMU Failure Messages</b>	
395742.818 : WARNING : Gap of 395720.8249 seconds in CHECKDT input data	

## Primary Observables & Satellite Data

### GPS/GLONASS L1 Satellite Lock/Elevation

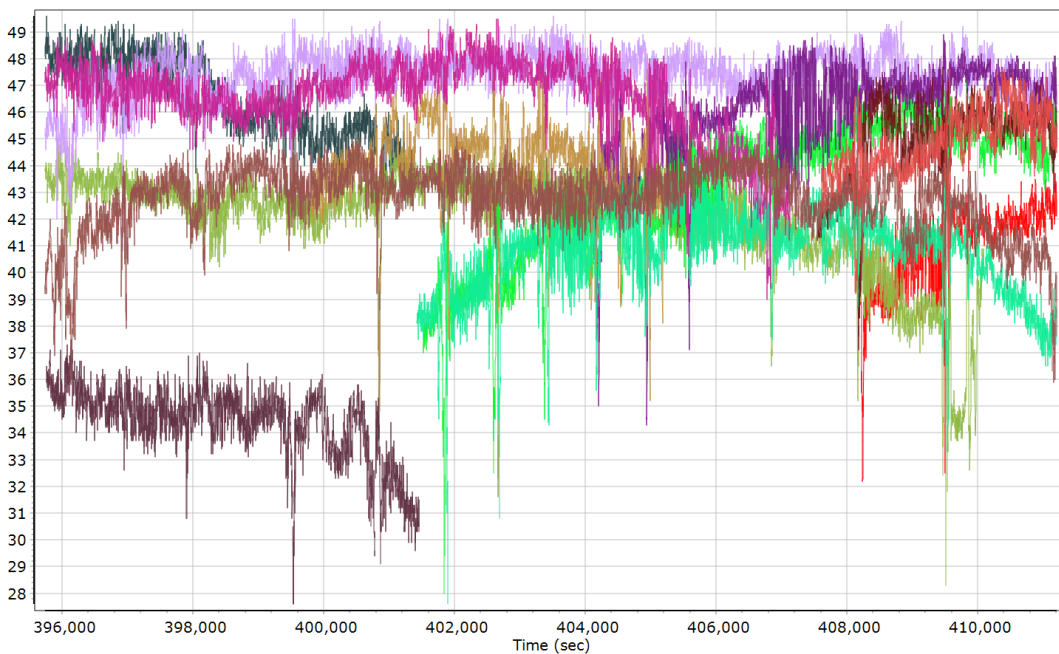


### GPS L1 SNR



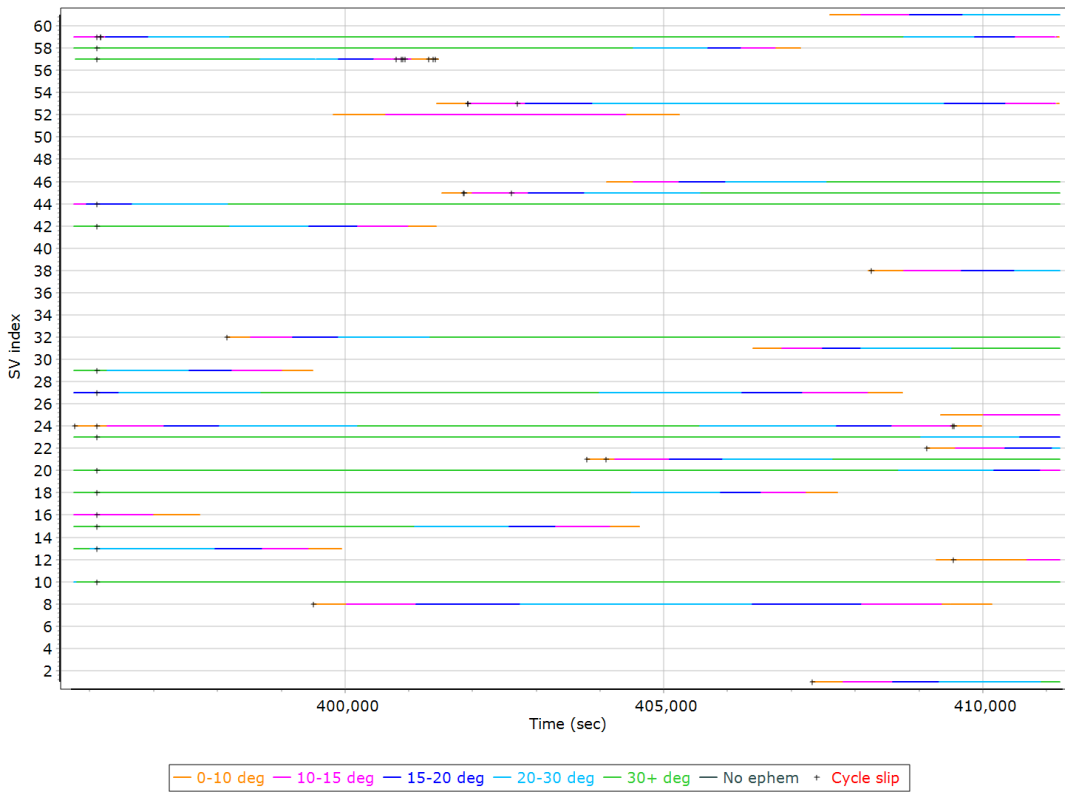
- |                           |                           |                           |                           |
|---------------------------|---------------------------|---------------------------|---------------------------|
| GPS PRN 01 L1 SNR (dB/Hz) | GPS PRN 08 L1 SNR (dB/Hz) | GPS PRN 10 L1 SNR (dB/Hz) | GPS PRN 12 L1 SNR (dB/Hz) |
| GPS PRN 13 L1 SNR (dB/Hz) | GPS PRN 15 L1 SNR (dB/Hz) | GPS PRN 16 L1 SNR (dB/Hz) | GPS PRN 18 L1 SNR (dB/Hz) |
| GPS PRN 20 L1 SNR (dB/Hz) | GPS PRN 21 L1 SNR (dB/Hz) | GPS PRN 22 L1 SNR (dB/Hz) | GPS PRN 23 L1 SNR (dB/Hz) |
| GPS PRN 24 L1 SNR (dB/Hz) | GPS PRN 25 L1 SNR (dB/Hz) | GPS PRN 27 L1 SNR (dB/Hz) | GPS PRN 29 L1 SNR (dB/Hz) |
| GPS PRN 31 L1 SNR (dB/Hz) | GPS PRN 32 L1 SNR (dB/Hz) |                           |                           |

### GLONASS L1 SNR

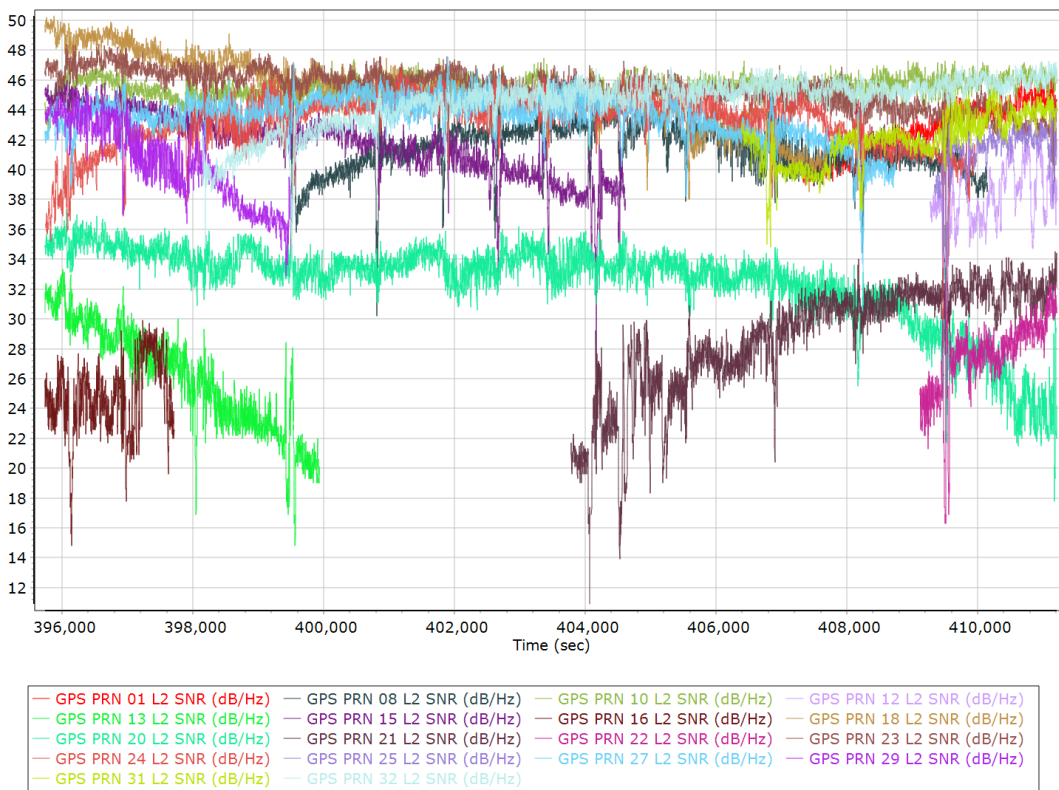


- |                           |                           |                           |
|---------------------------|---------------------------|---------------------------|
| GLONASS 01 L1 SNR (dB/Hz) | GLONASS 05 L1 SNR (dB/Hz) | GLONASS 06 L1 SNR (dB/Hz) |
| GLONASS 07 L1 SNR (dB/Hz) | GLONASS 08 L1 SNR (dB/Hz) | GLONASS 09 L1 SNR (dB/Hz) |
| GLONASS 10 L1 SNR (dB/Hz) | GLONASS 15 L1 SNR (dB/Hz) | GLONASS 16 L1 SNR (dB/Hz) |
| GLONASS 20 L1 SNR (dB/Hz) | GLONASS 21 L1 SNR (dB/Hz) | GLONASS 22 L1 SNR (dB/Hz) |
| GLONASS 24 L1 SNR (dB/Hz) |                           |                           |

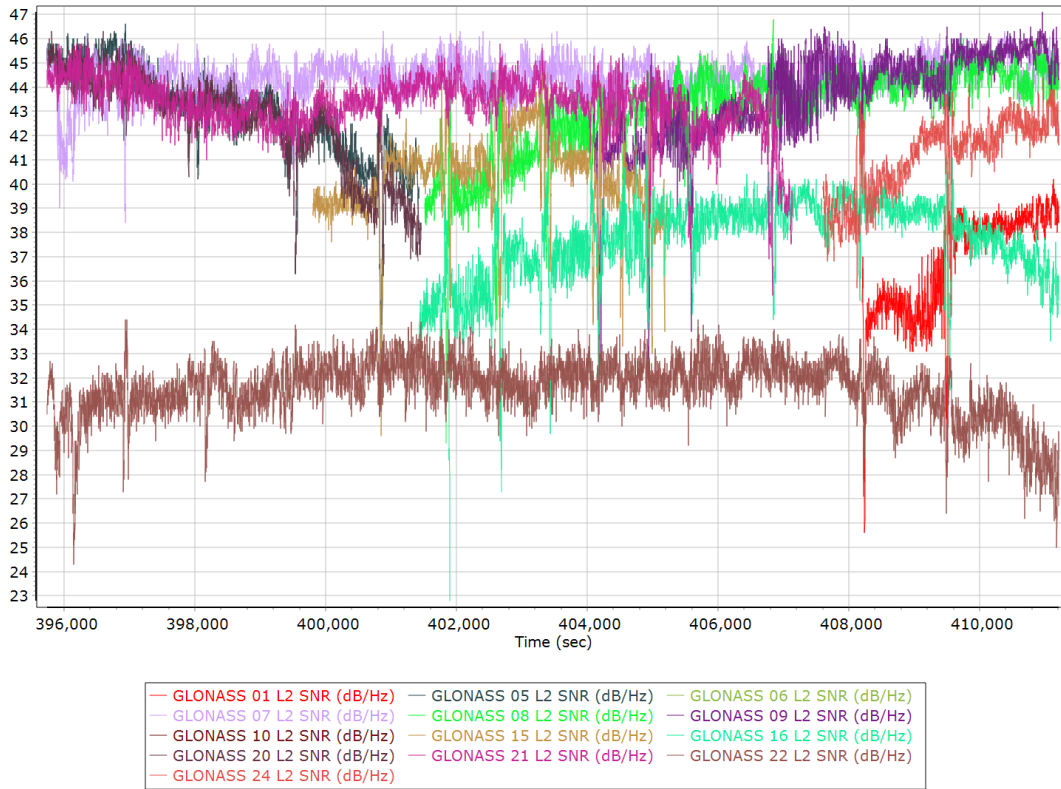
### GPS/GLONASS L2 Satellite Lock/Elevation



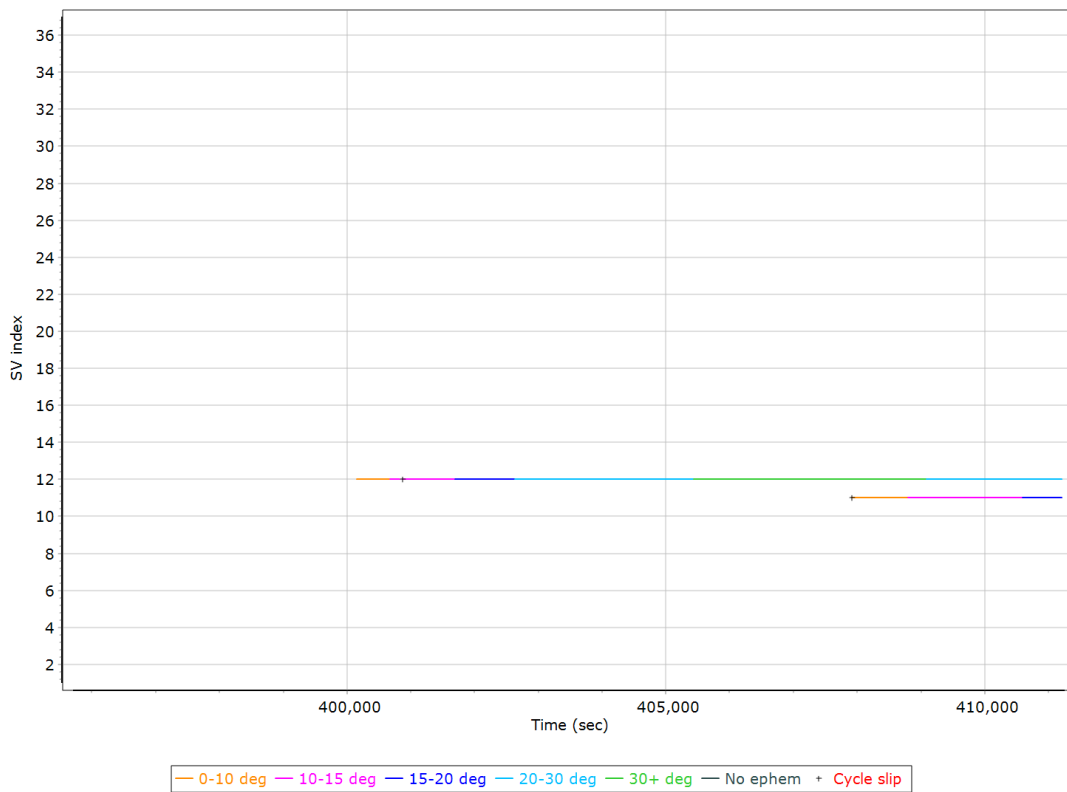
### GPS L2 SNR



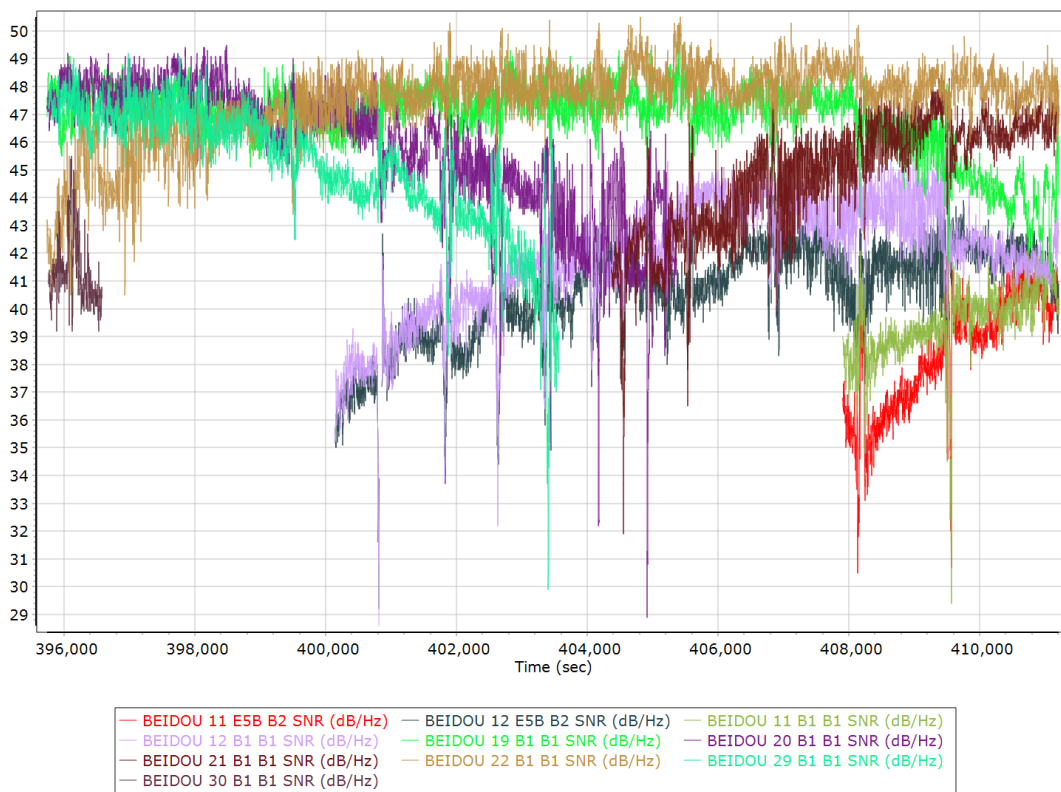
### GLONASS L2 SNR



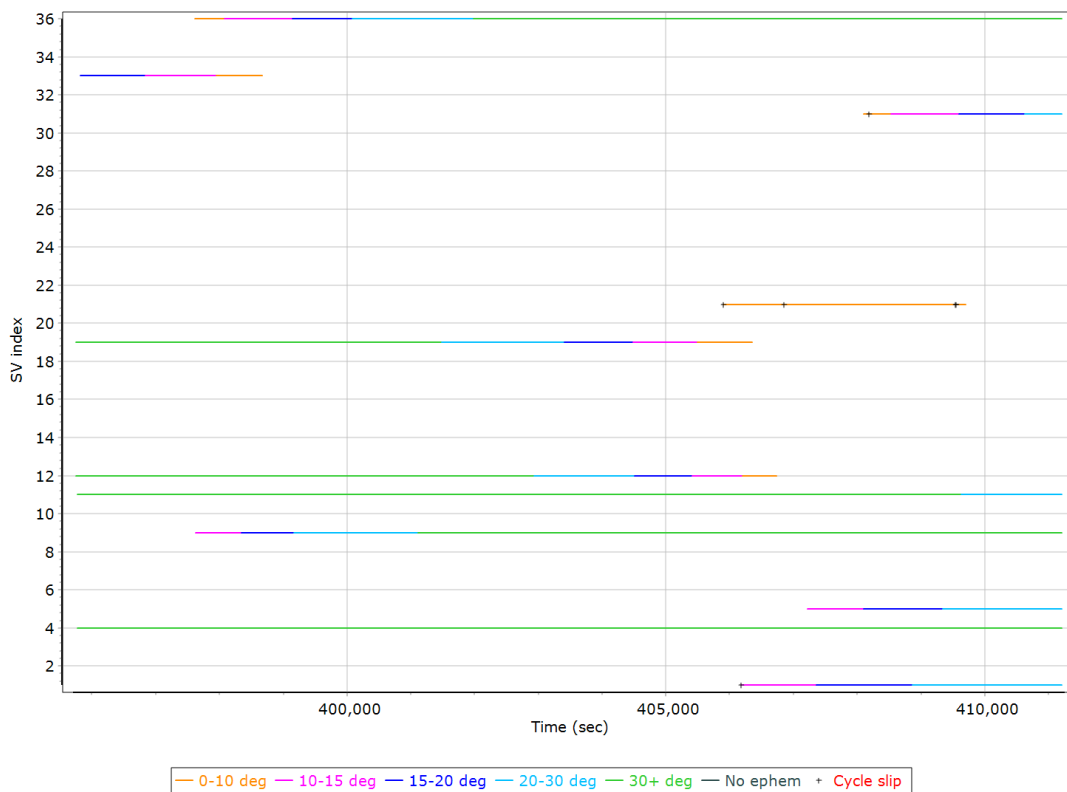
### BEIDOU Satellite Lock/Elevation



### BEIDOU SNR

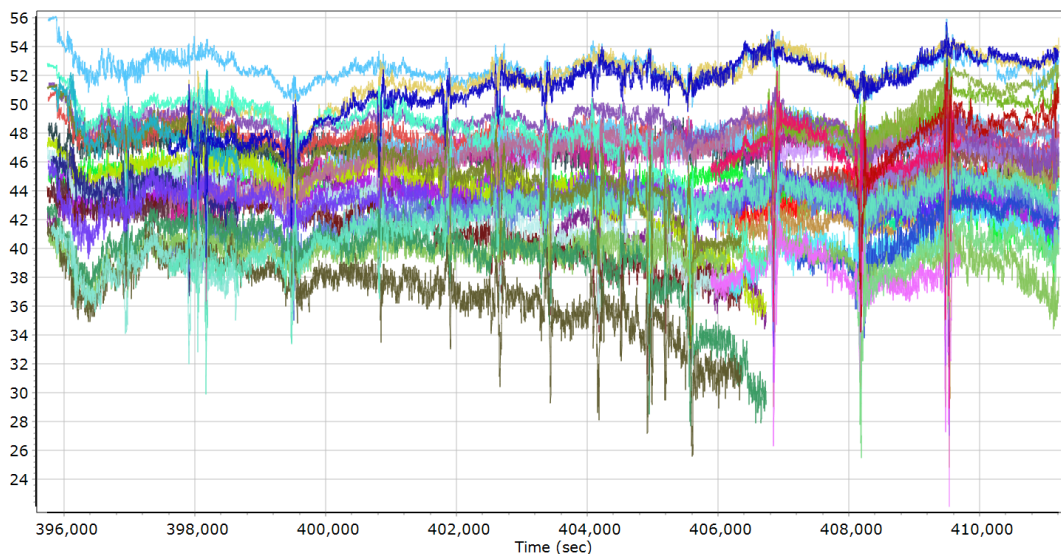


### GALILEO Satellite Lock/Elevation





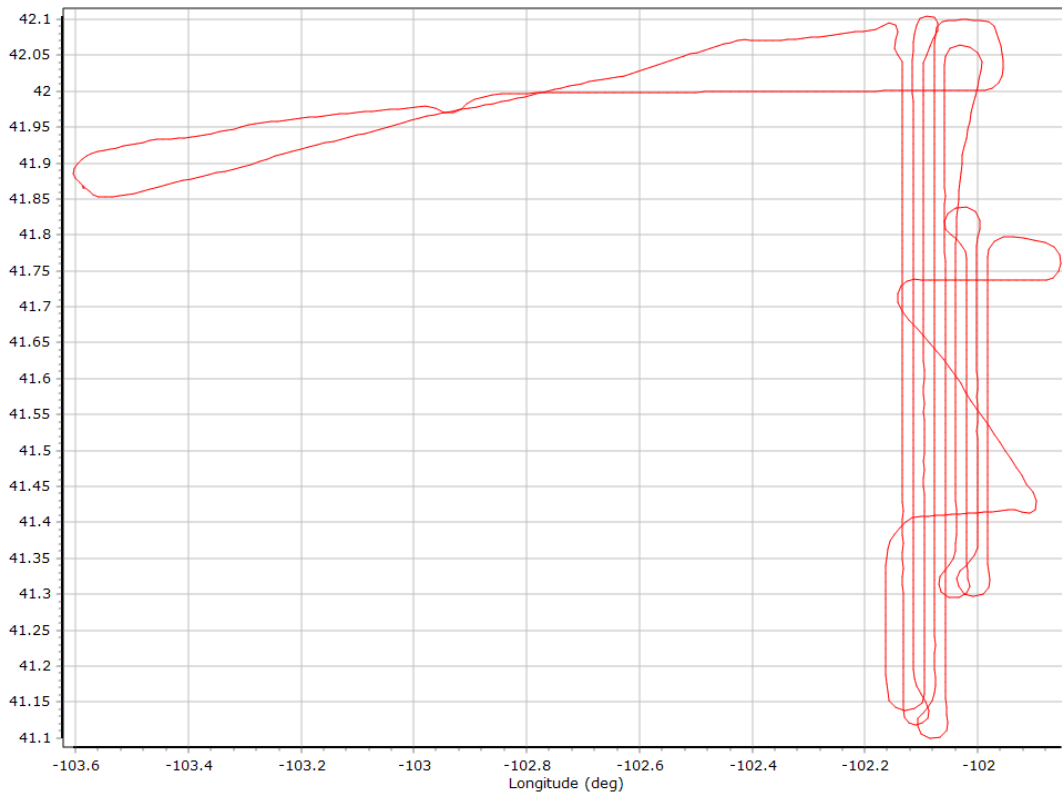
## GALILEO SNR



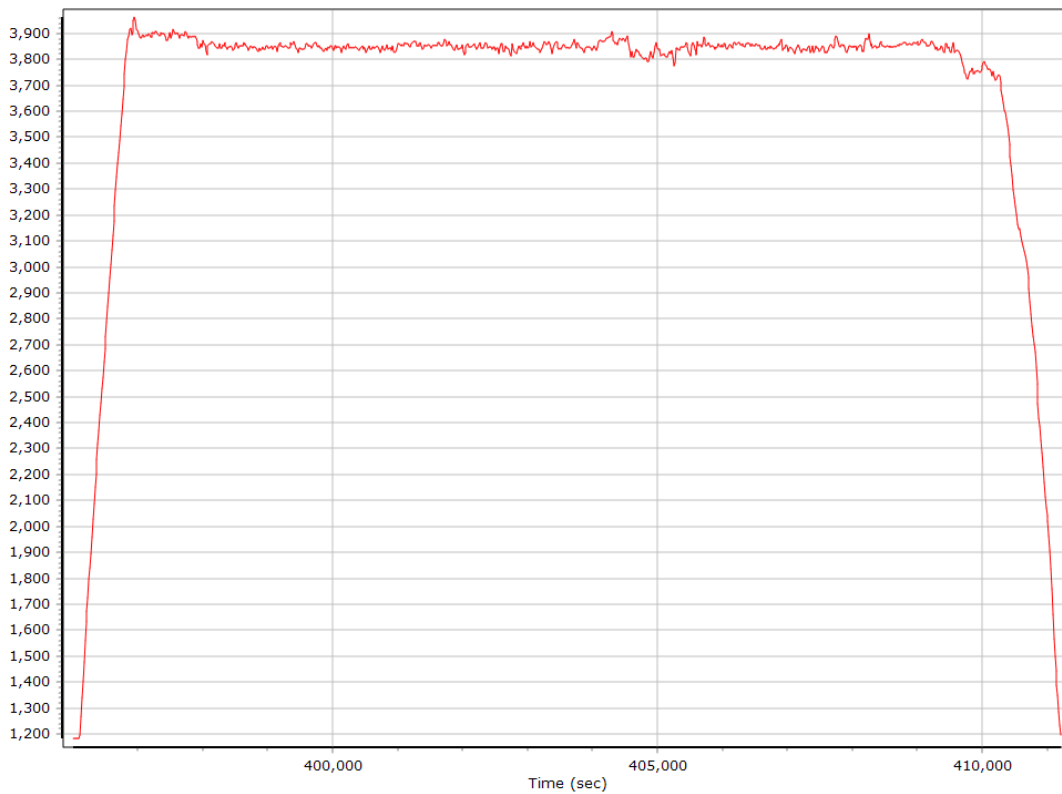
— GALILEO 01 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 04 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 05 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 09 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 11 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 12 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 19 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 21 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 31 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 33 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 36 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 01 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 04 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 05 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 09 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 11 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 12 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 19 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 21 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 31 L5E5A BPSK10_PD SNR (dB/Hz)

## Smoothed Trajectory Information

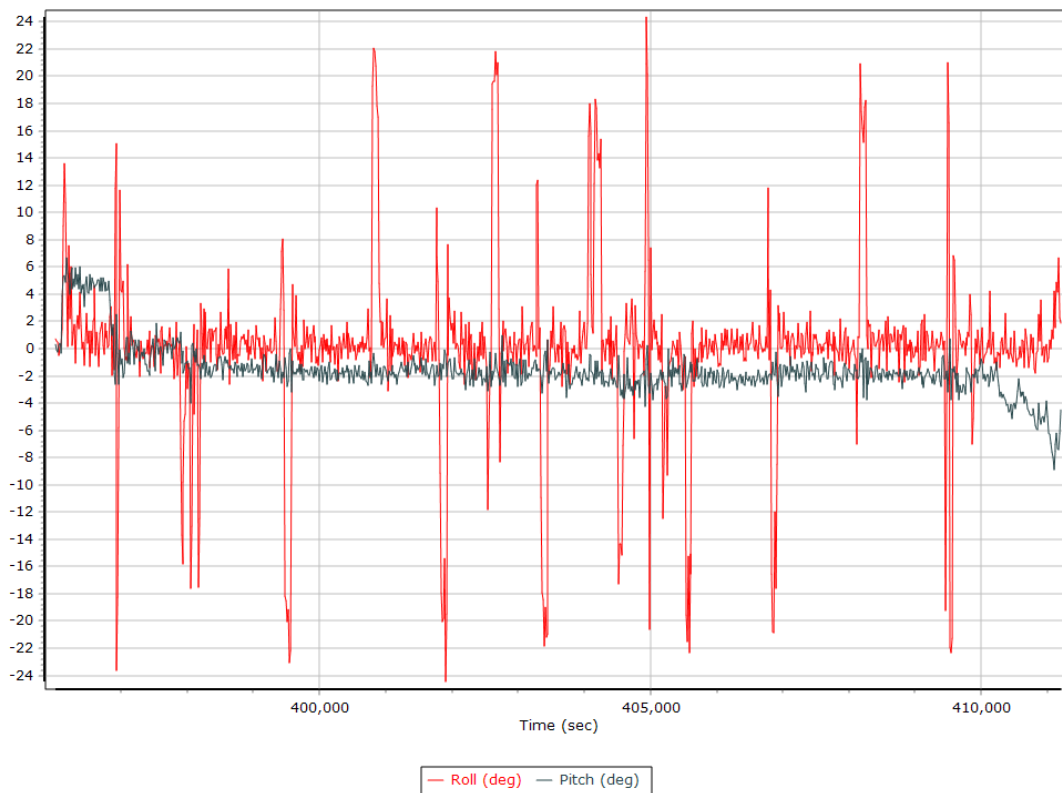
### Top View



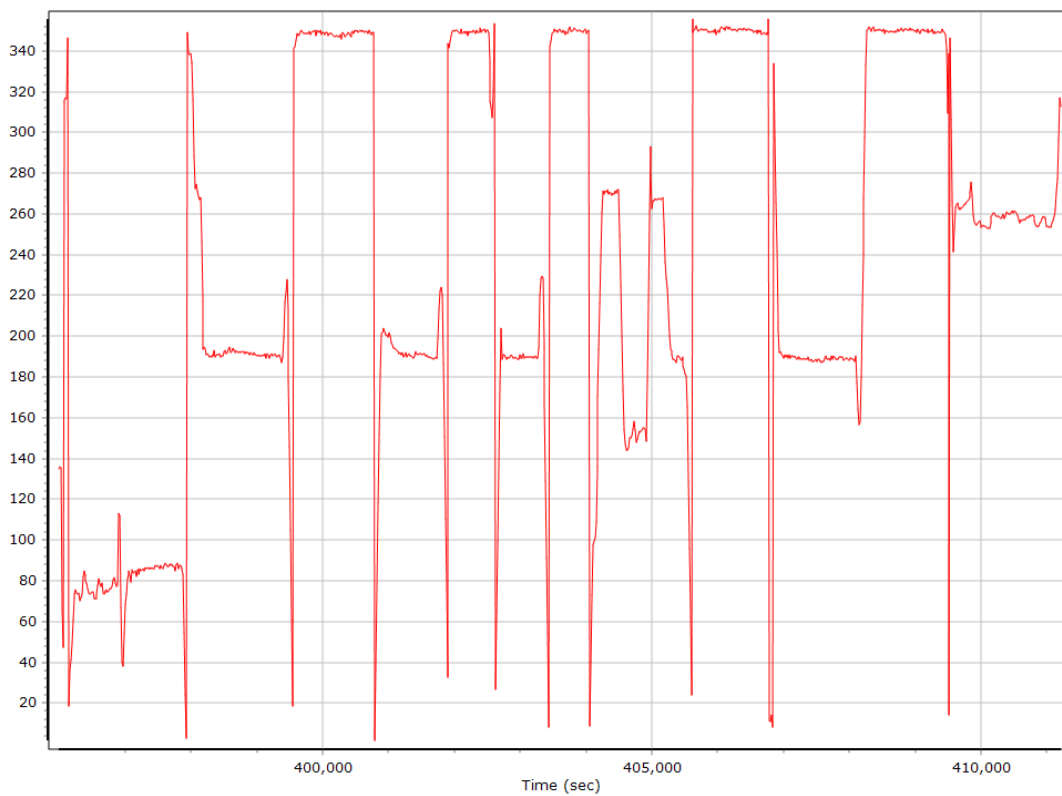
### Altitude



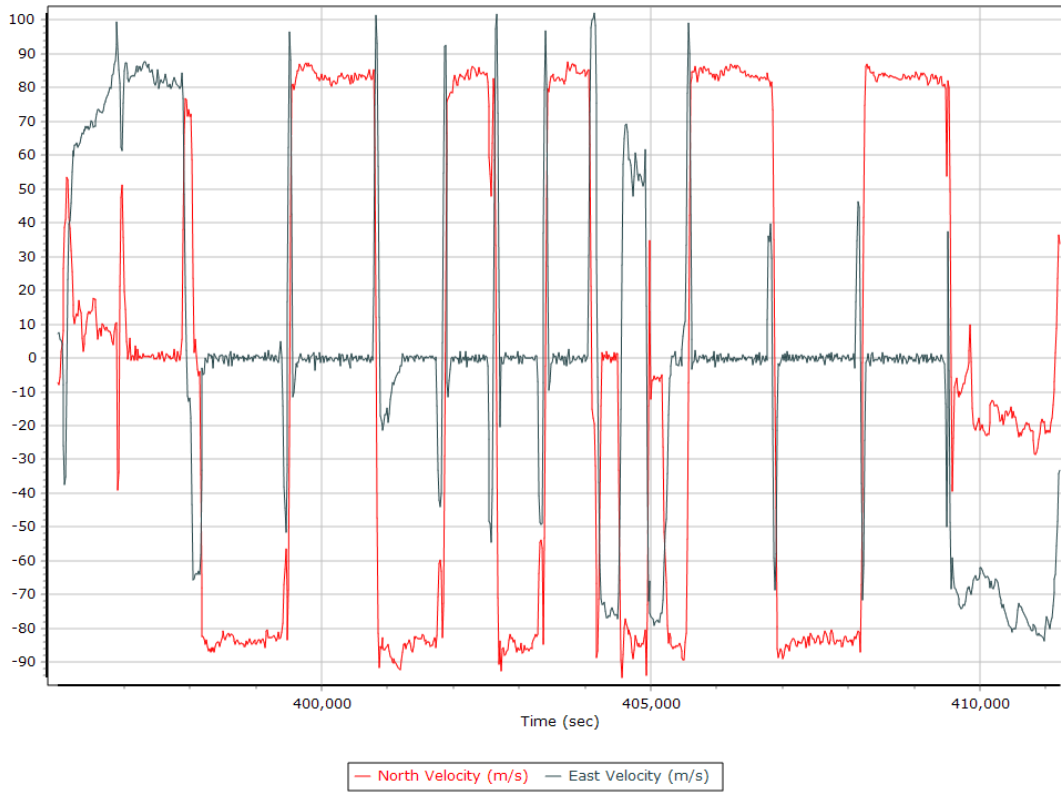
## Roll/Pitch



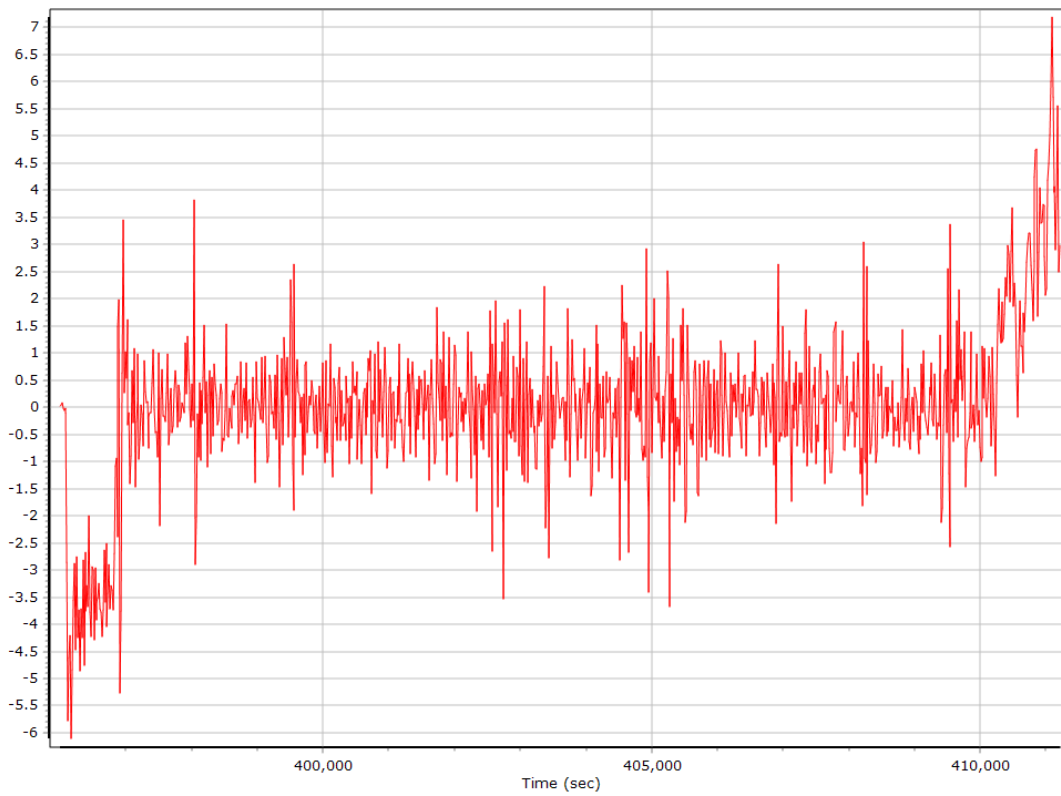
## Heading



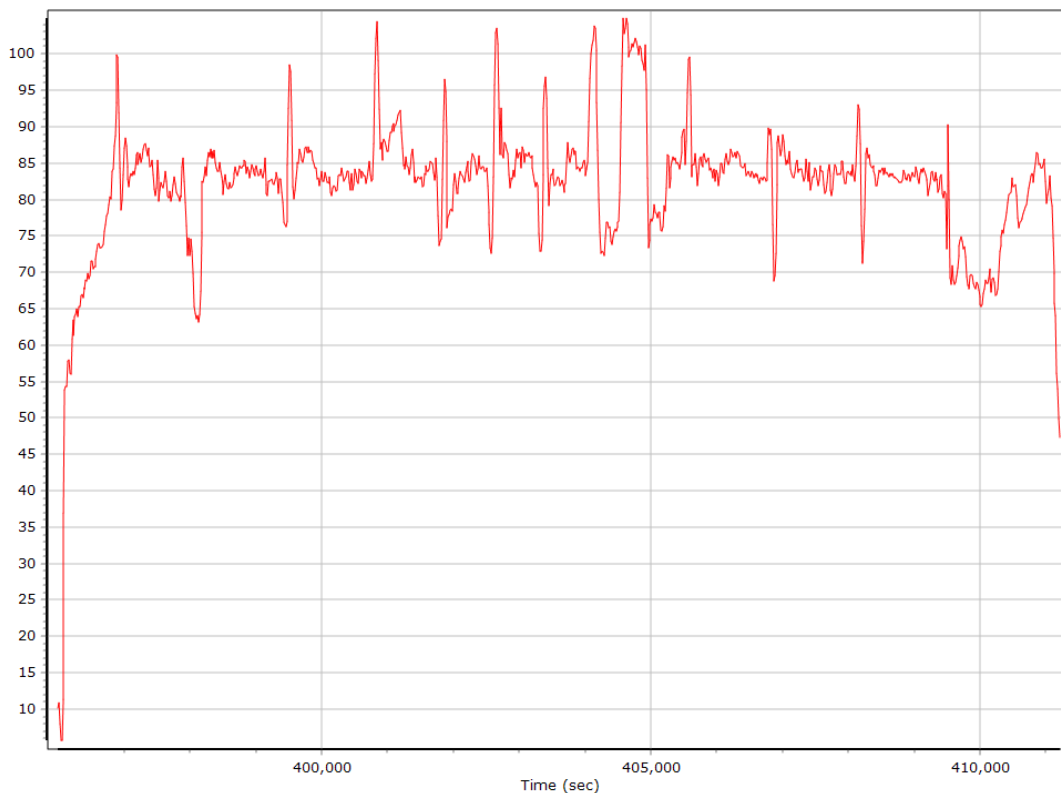
## North/East Velocity



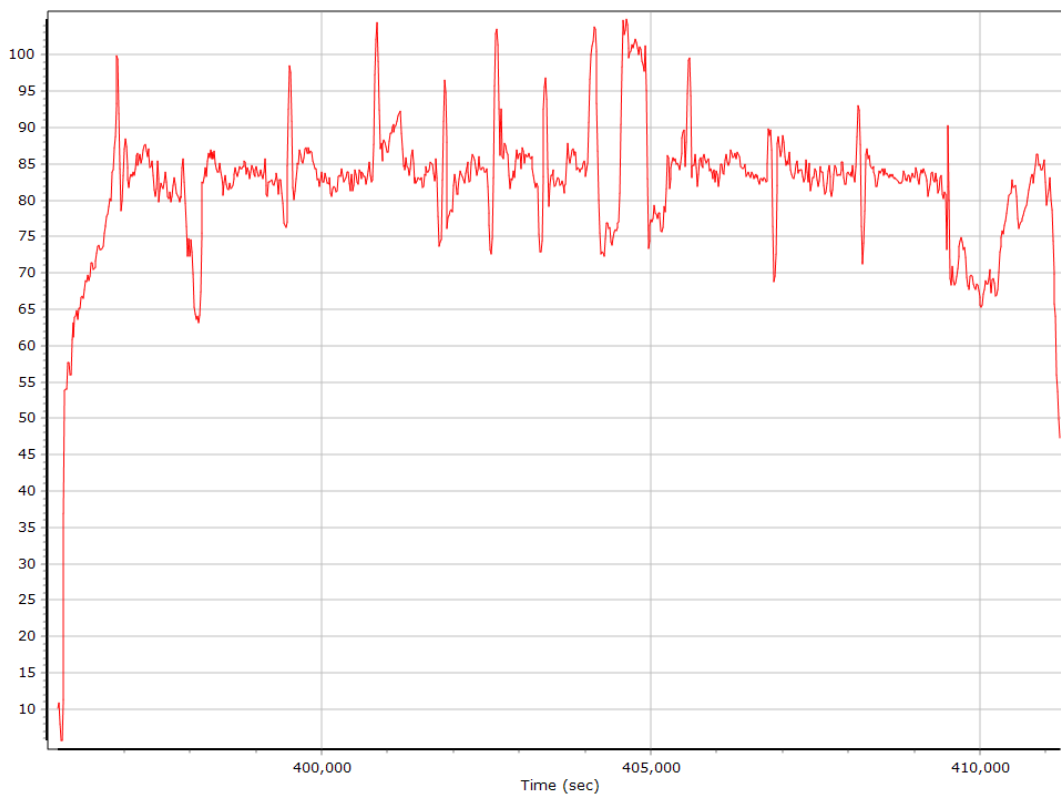
## Down Velocity



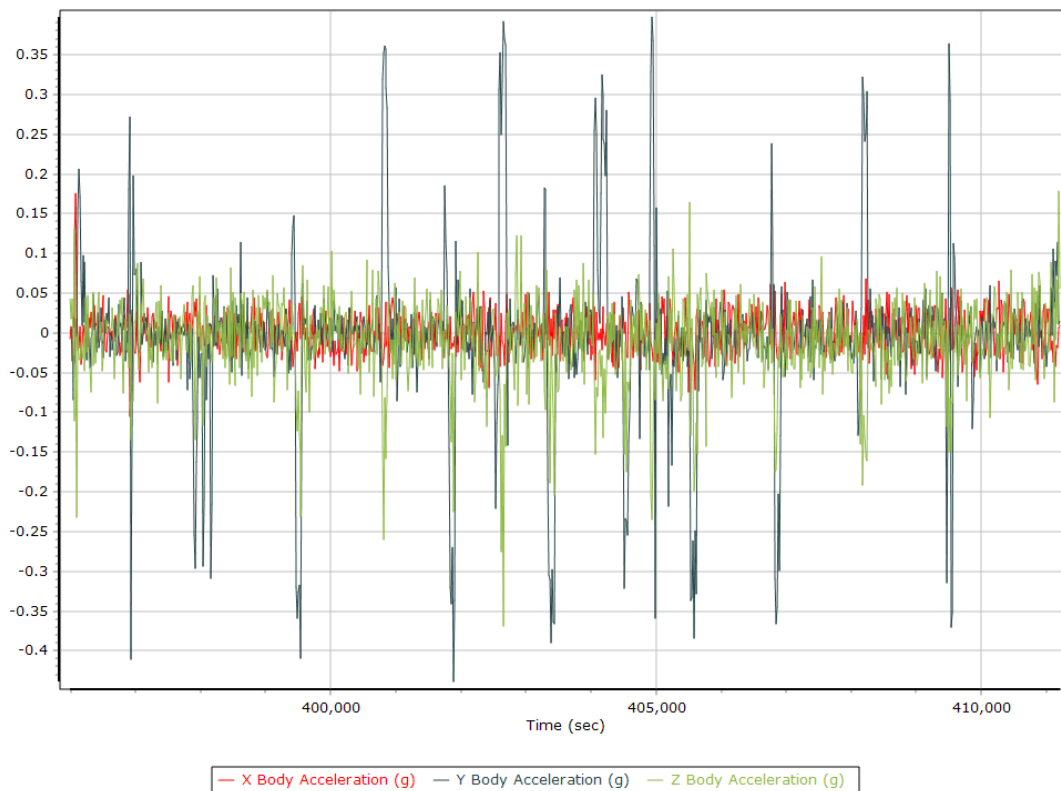
### Total Speed



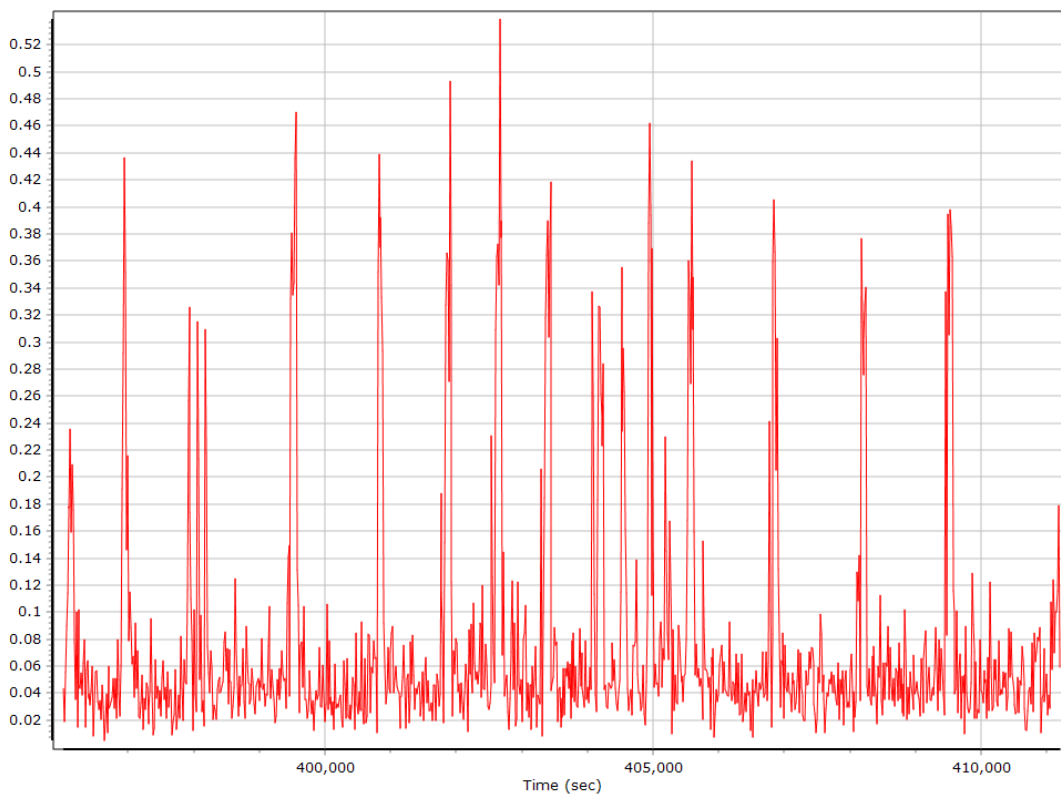
### Ground Speed



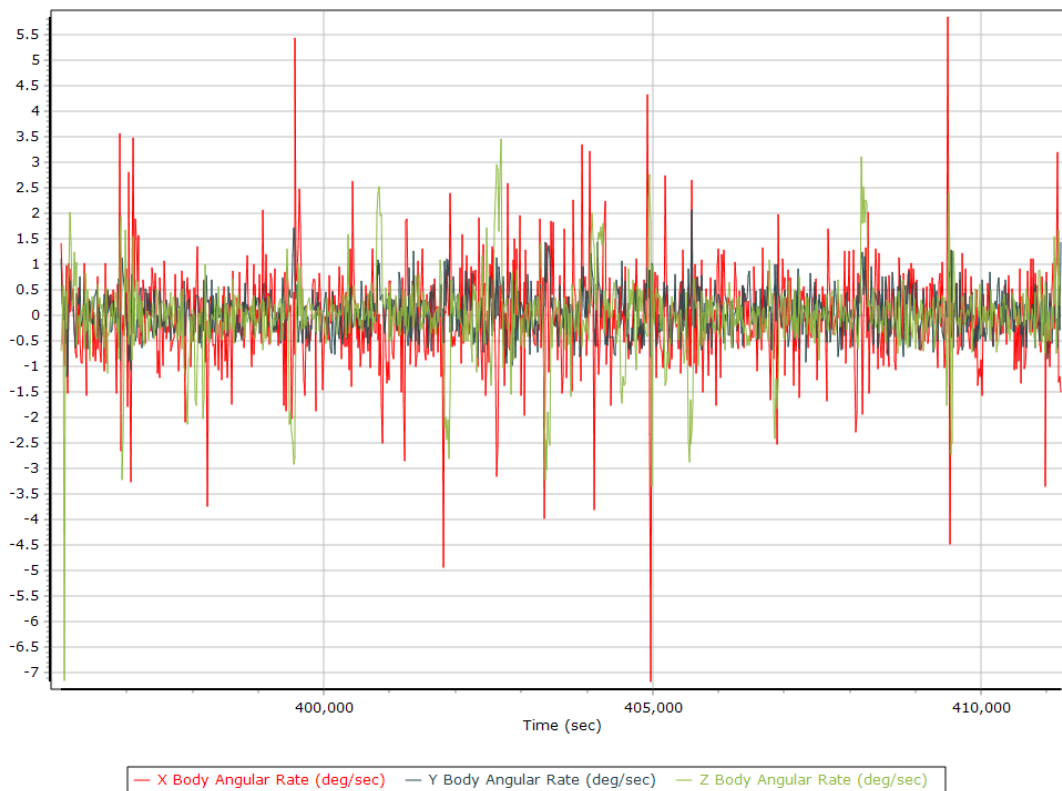
## Body Acceleration



## Total Body Acceleration

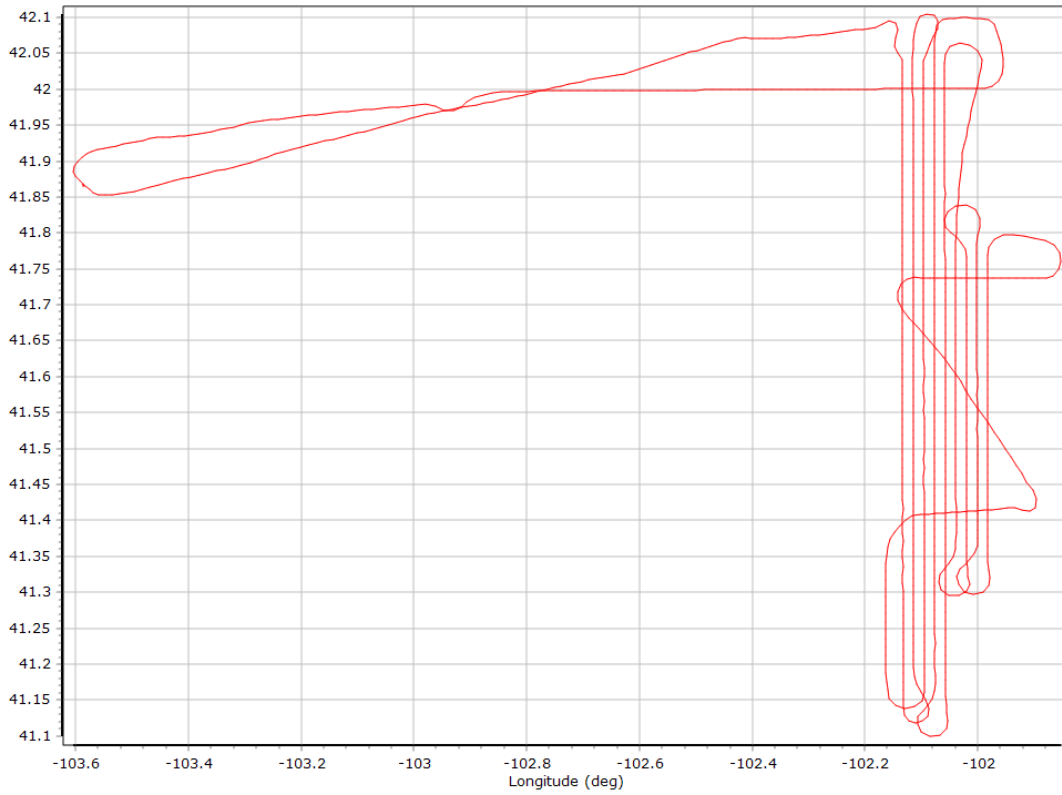


## Body Angular Rate

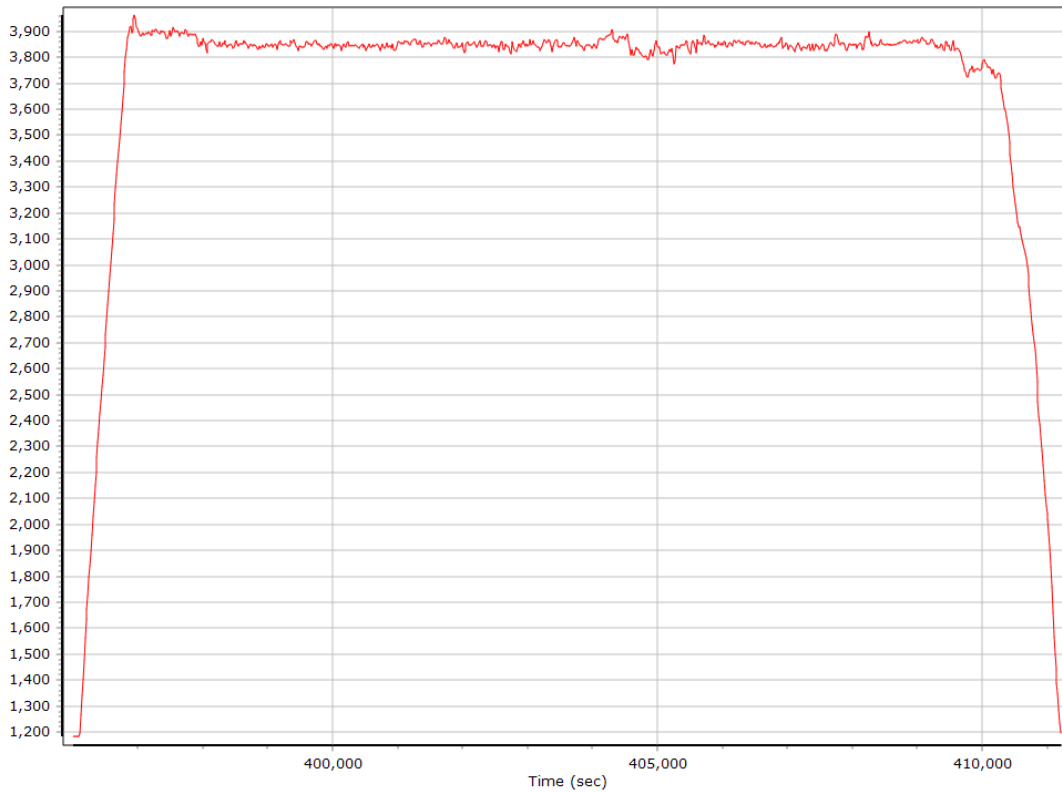


## Forward Processed Trajectory Information

### Top View

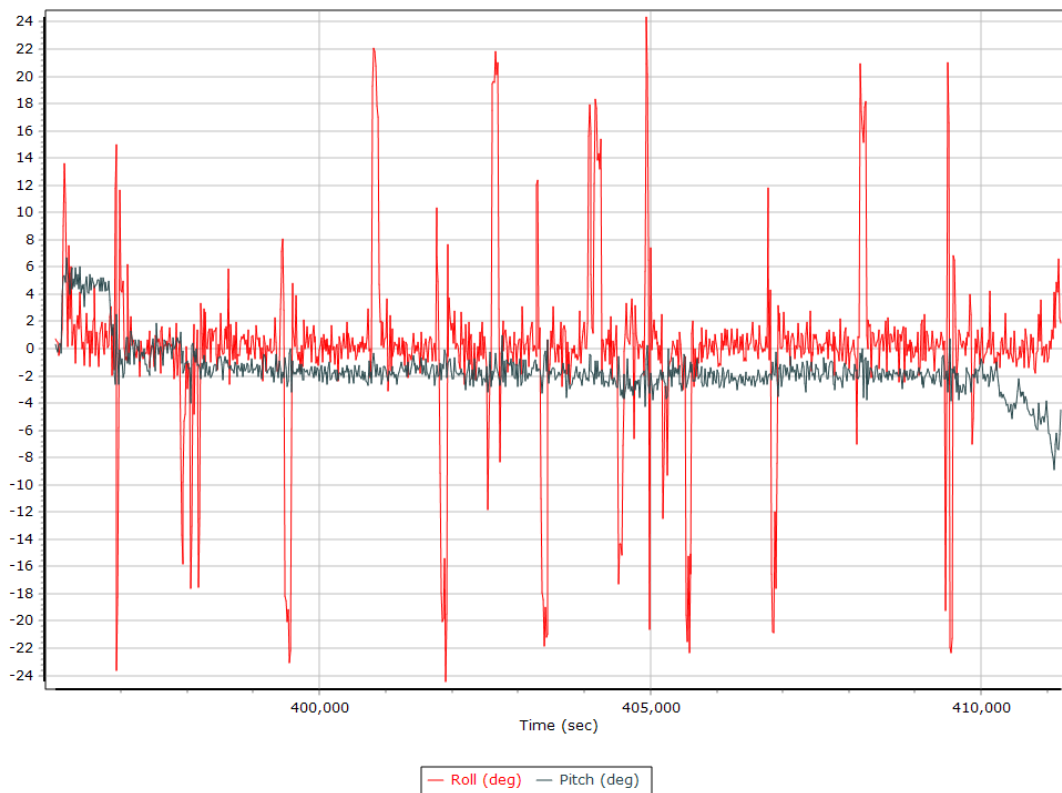


### Altitude

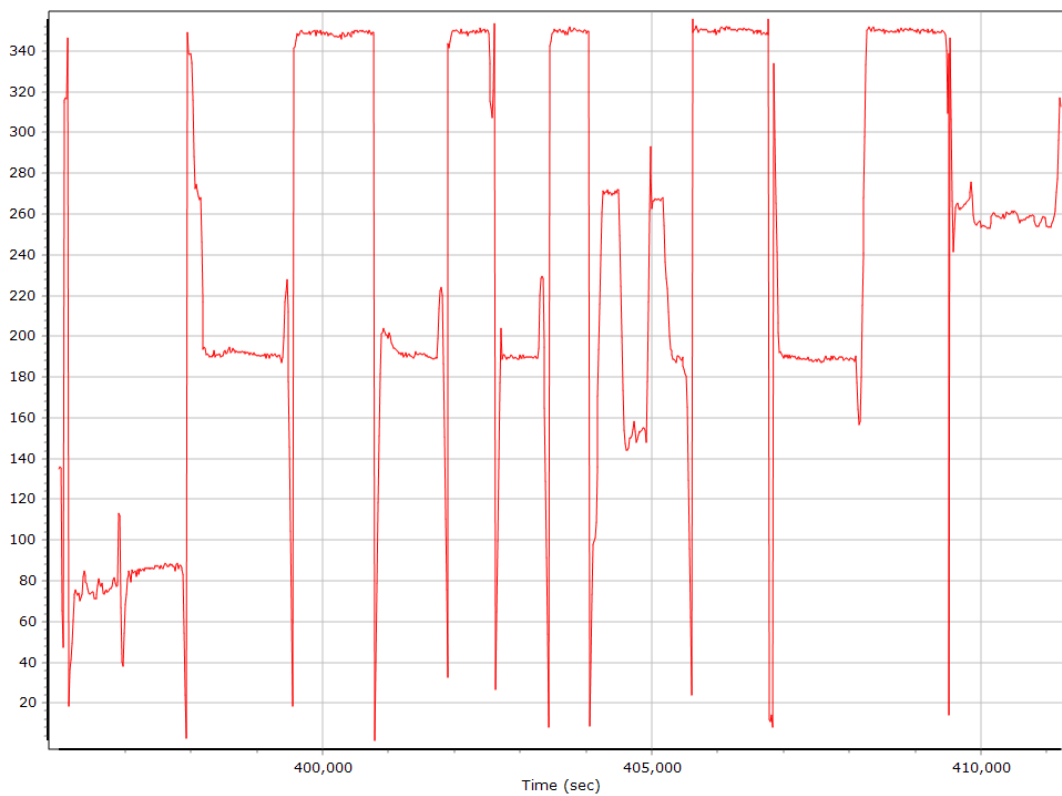




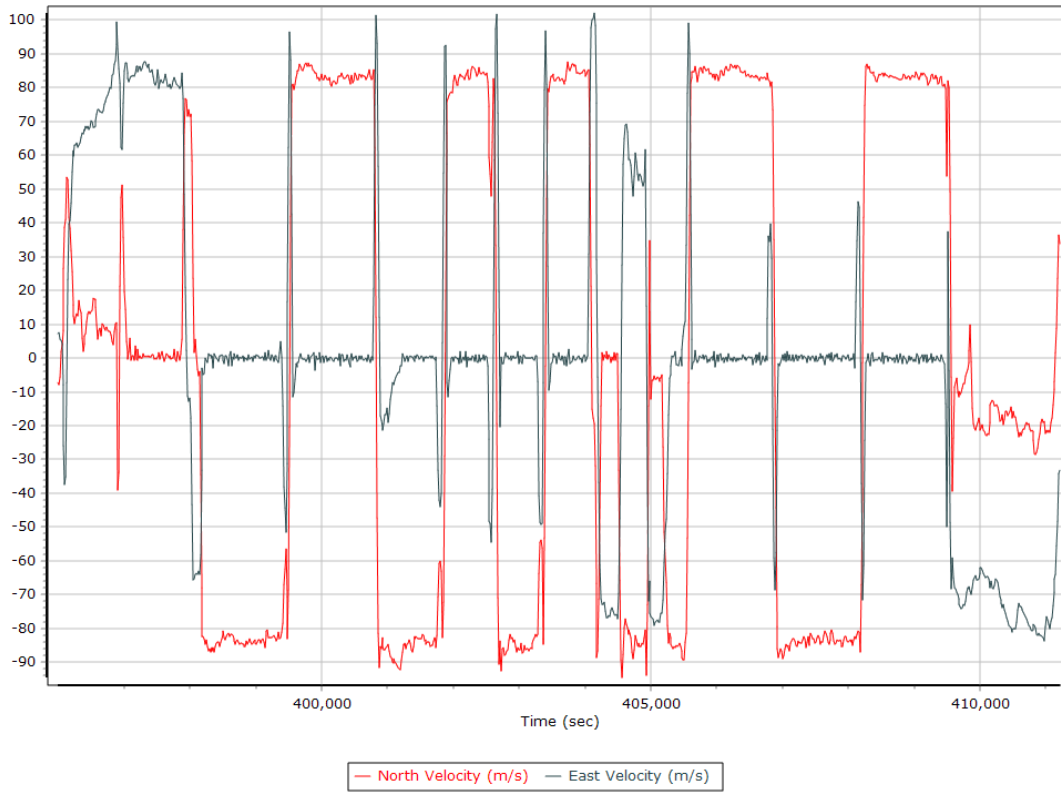
## Roll/Pitch



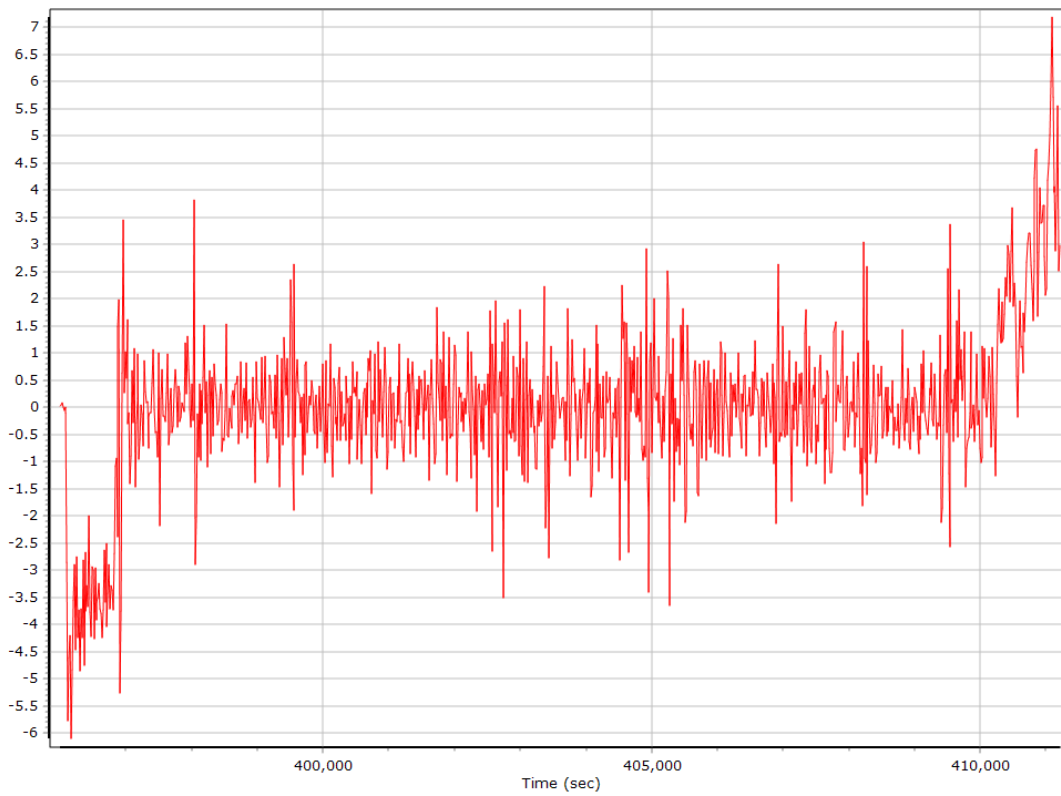
## Heading



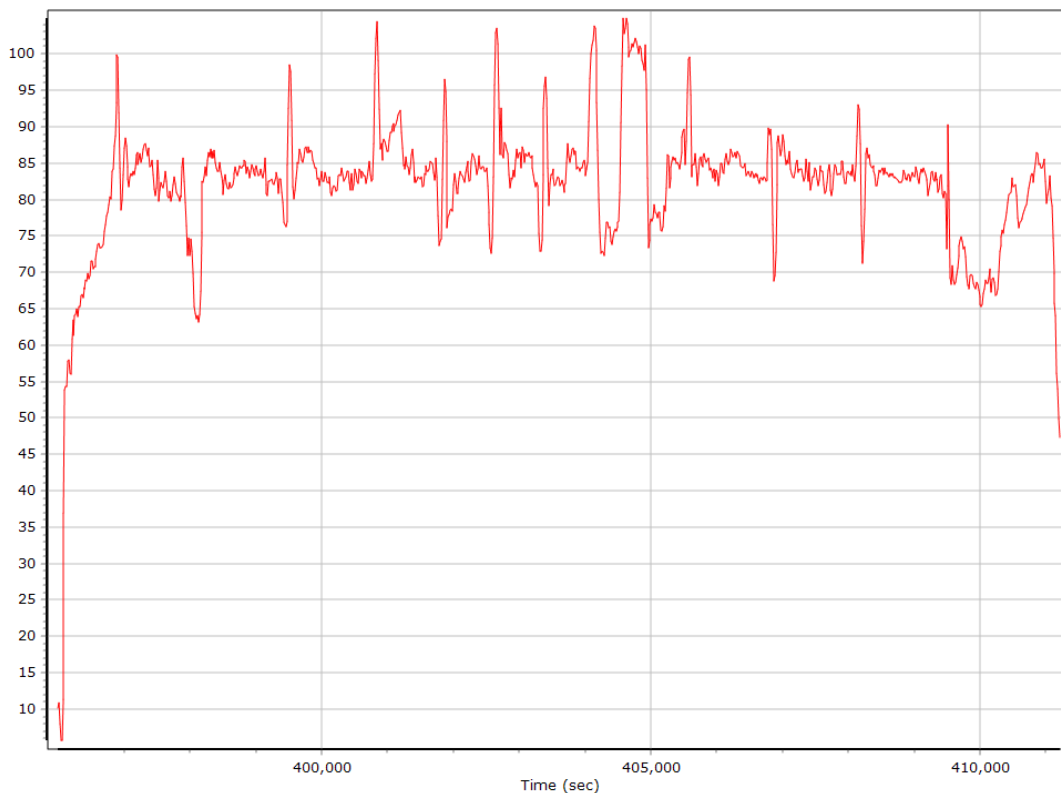
## North/East Velocity



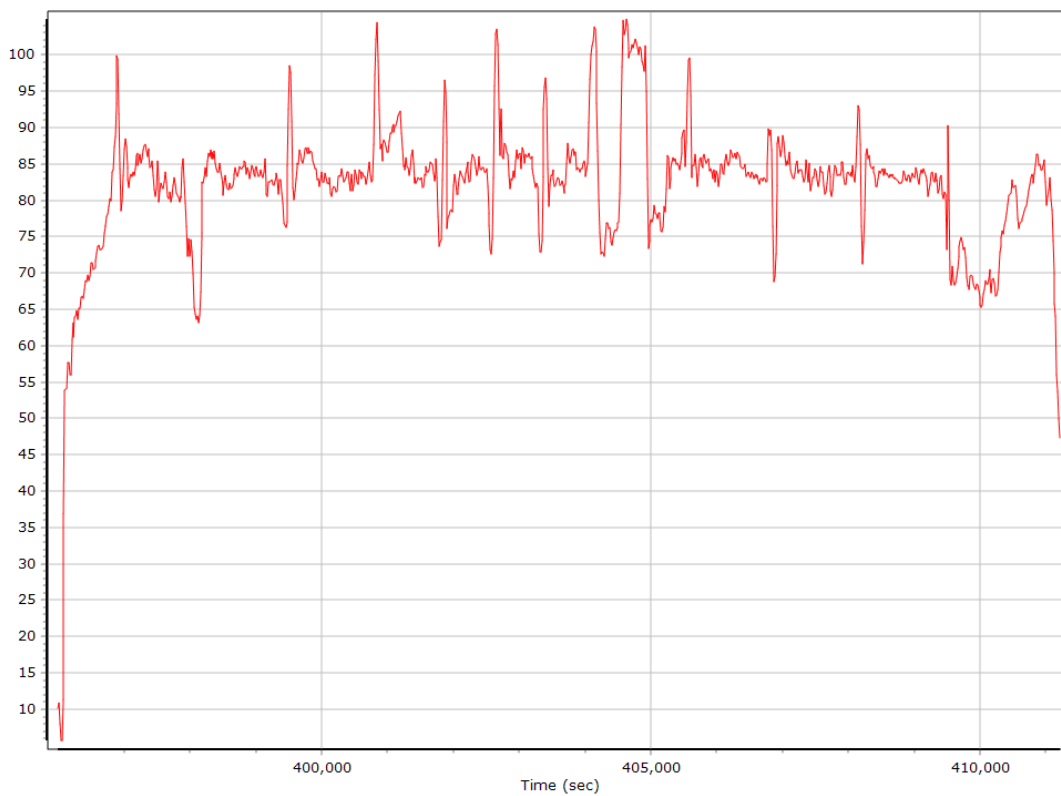
## Down Velocity



### Total Speed



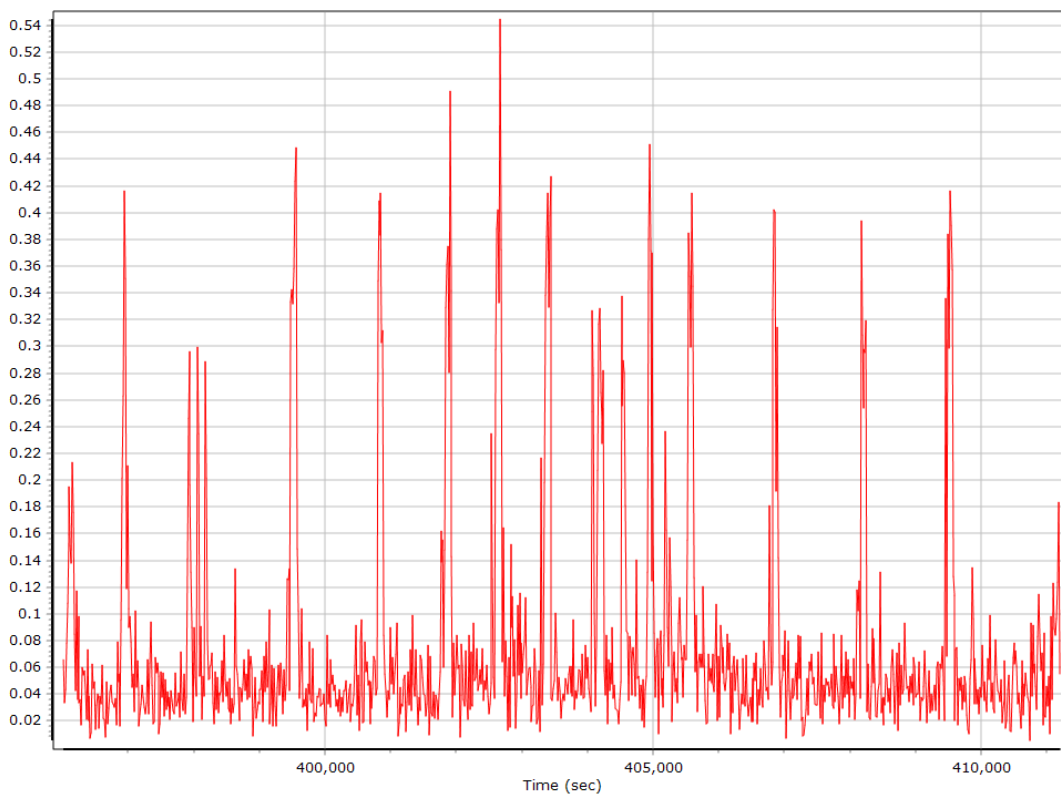
### Ground Speed



## Body Acceleration



## Total Body Acceleration



## Body Angular Rate

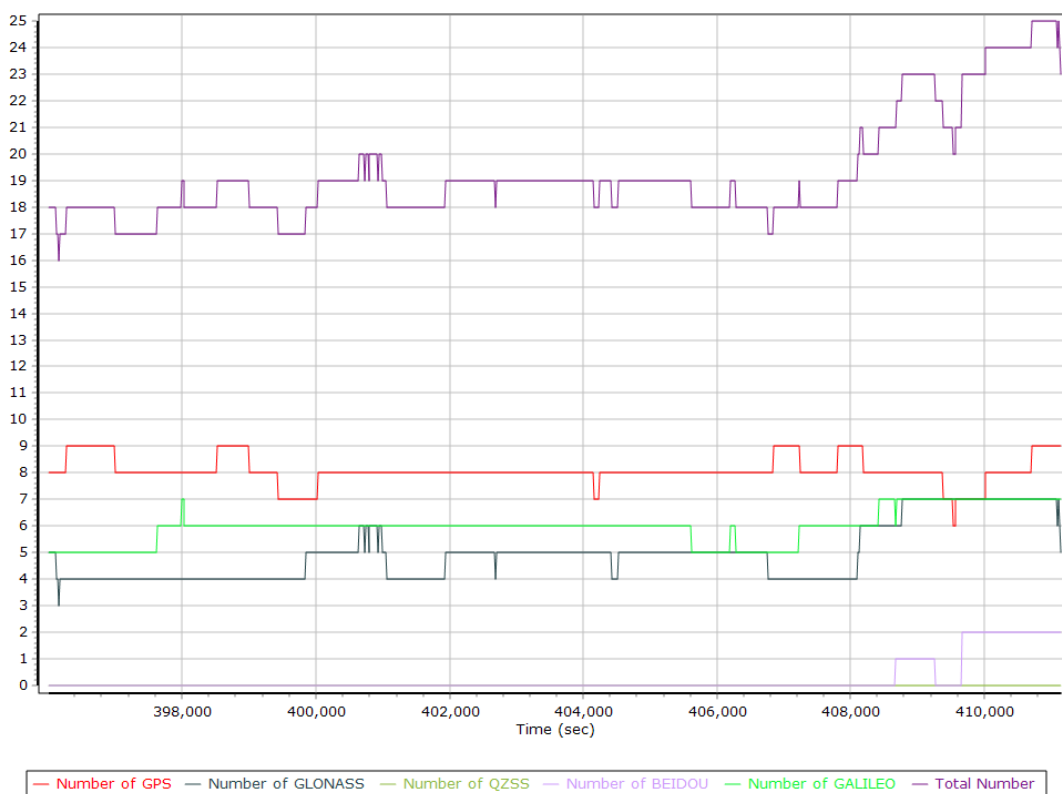


## GNSS QC

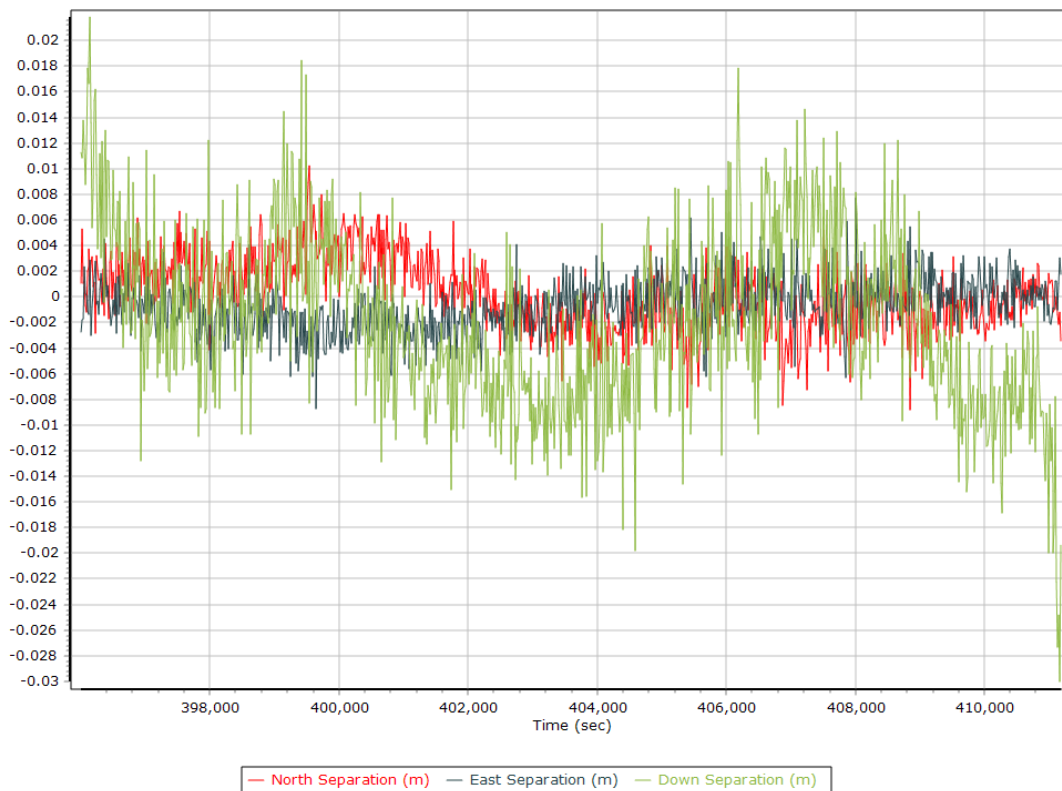
### GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	6	9	8
Number of GLONASS SV	0	7	5
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	2	0
Number of GALILEO SV	0	7	6
Total number of SV	12	25	19
PDOP	1.02	1.54	1.17
QC Solution Gaps	1.00	1.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	15411.00	0.00	9.00
Percentage	99.94	0.00	0.06

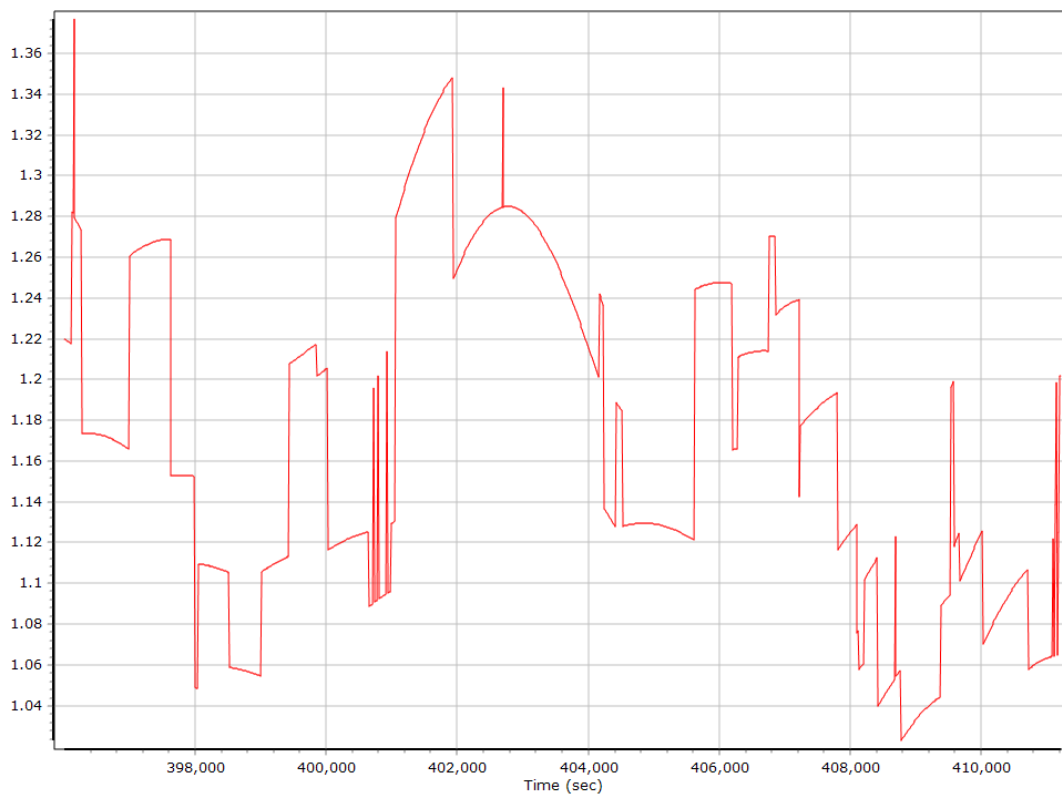
### Num SVs in solution



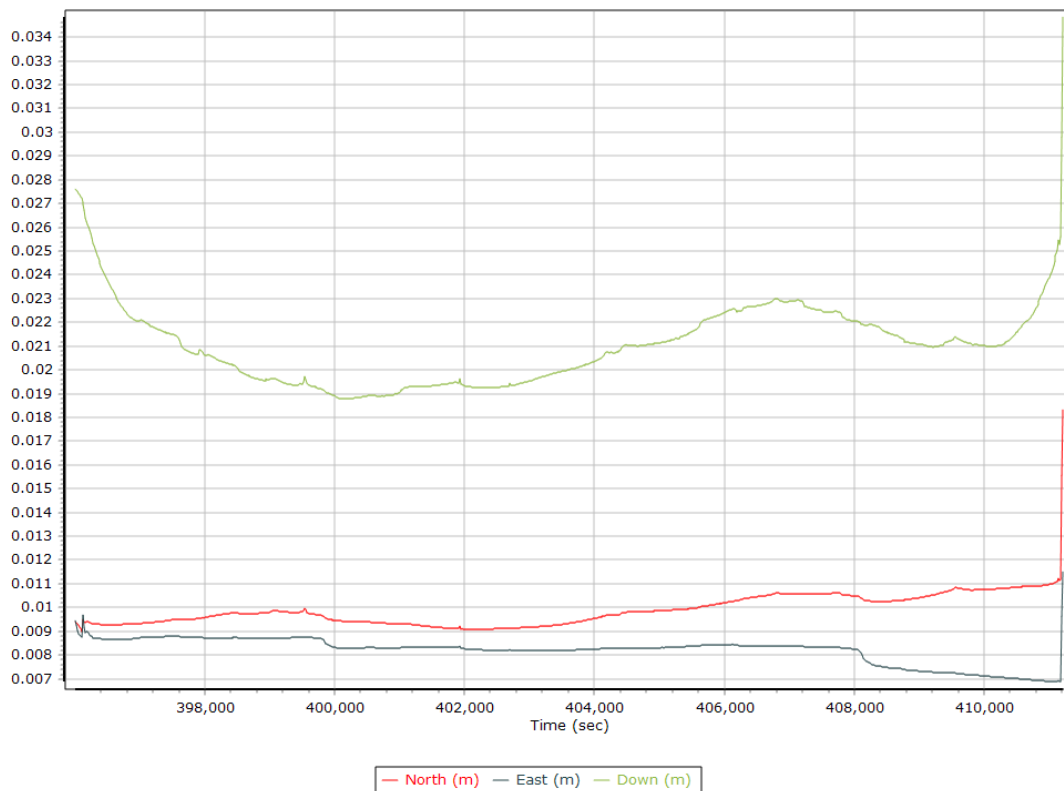
### Forward/Reverse Separation



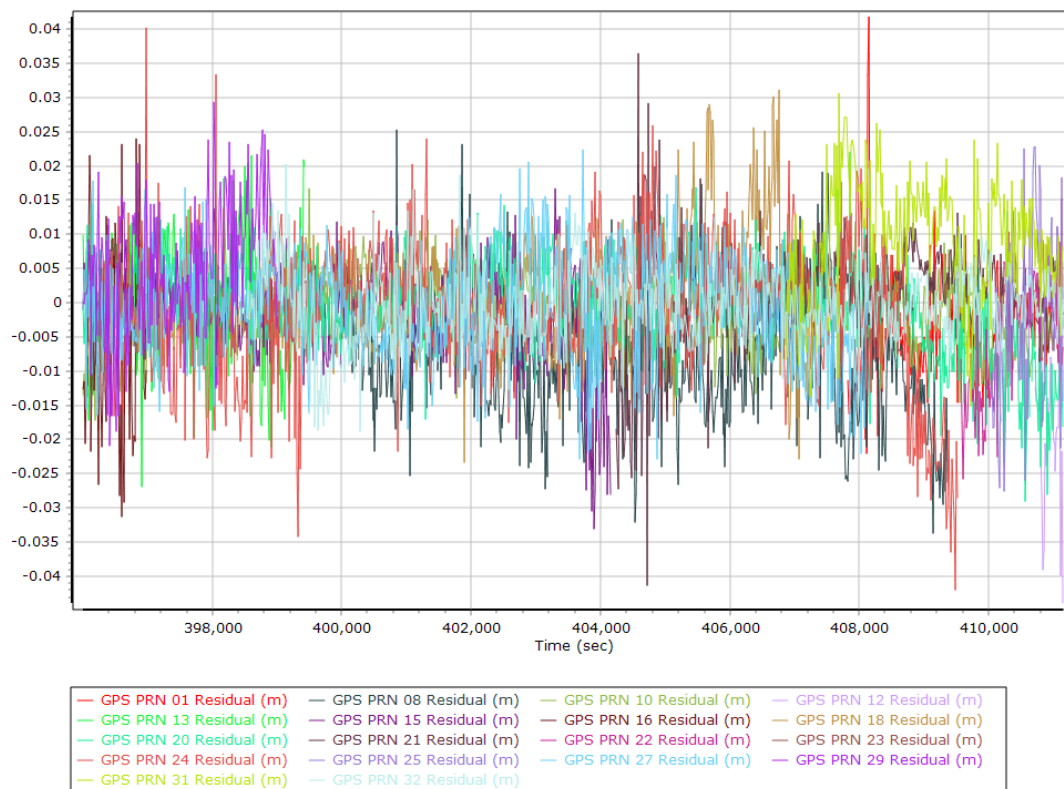
### PDOP



## Estimated Position Accuracy

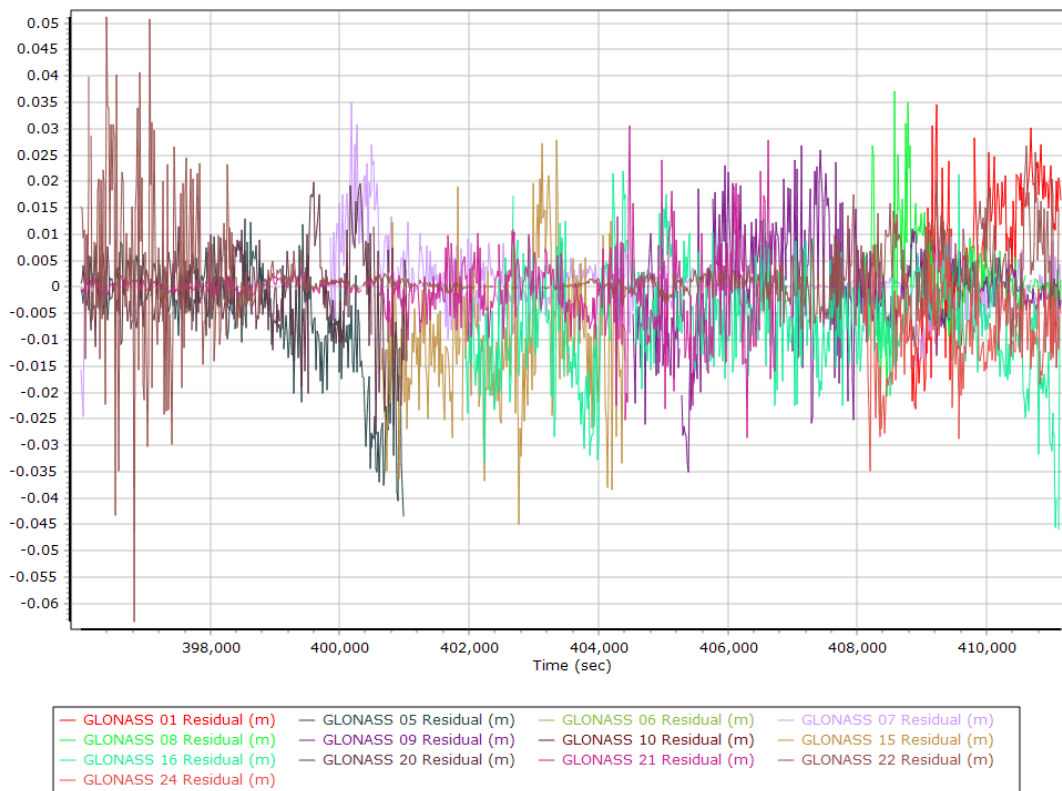


## GPS Residuals

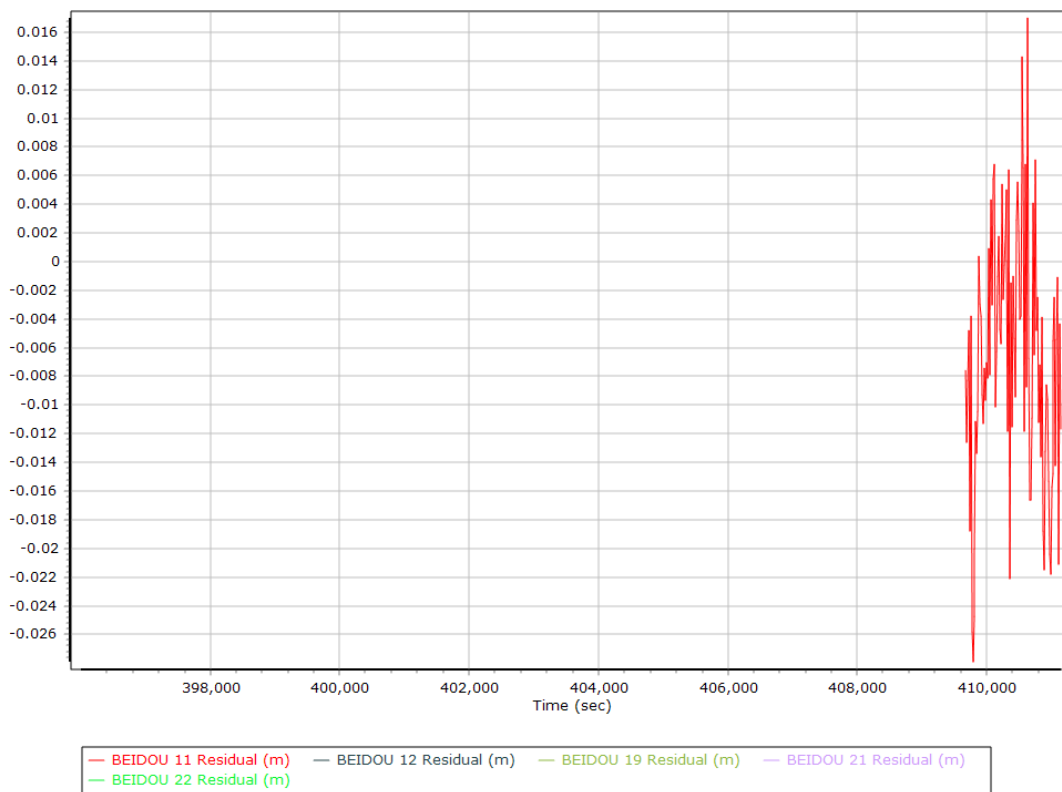




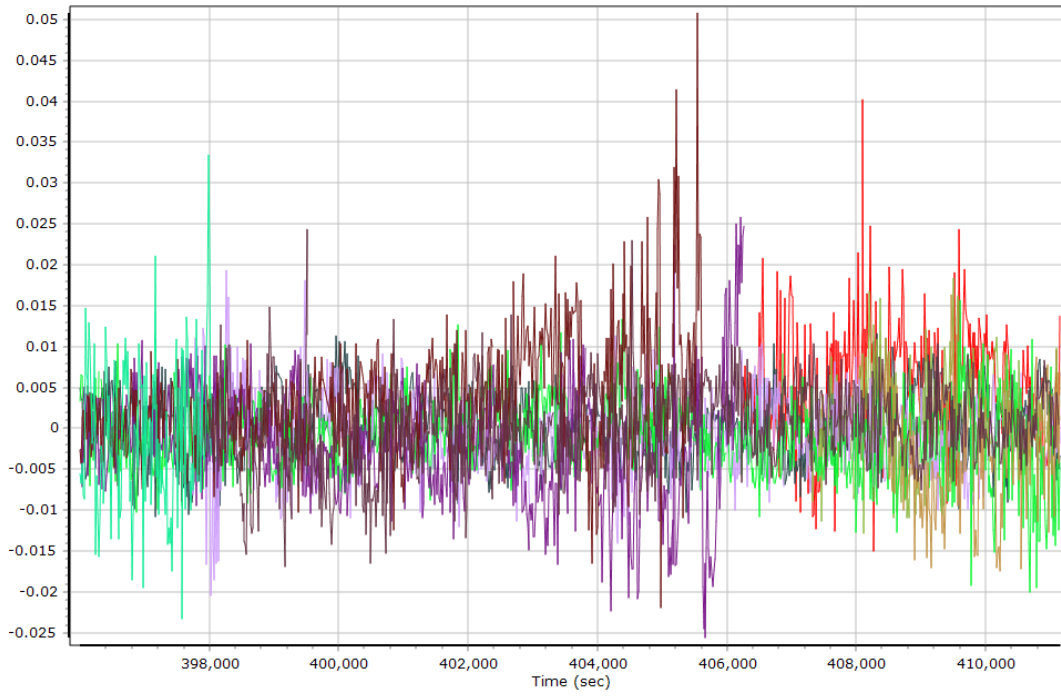
## GLONASS Residuals



## BEIDOU Residuals



## GALILEO Residuals



- |                         |                         |                         |                         |
|-------------------------|-------------------------|-------------------------|-------------------------|
| GALILEO 01 Residual (m) | GALILEO 04 Residual (m) | GALILEO 05 Residual (m) | GALILEO 09 Residual (m) |
| GALILEO 11 Residual (m) | GALILEO 12 Residual (m) | GALILEO 19 Residual (m) | GALILEO 31 Residual (m) |
| GALILEO 33 Residual (m) | GALILEO 36 Residual (m) |                         |                         |

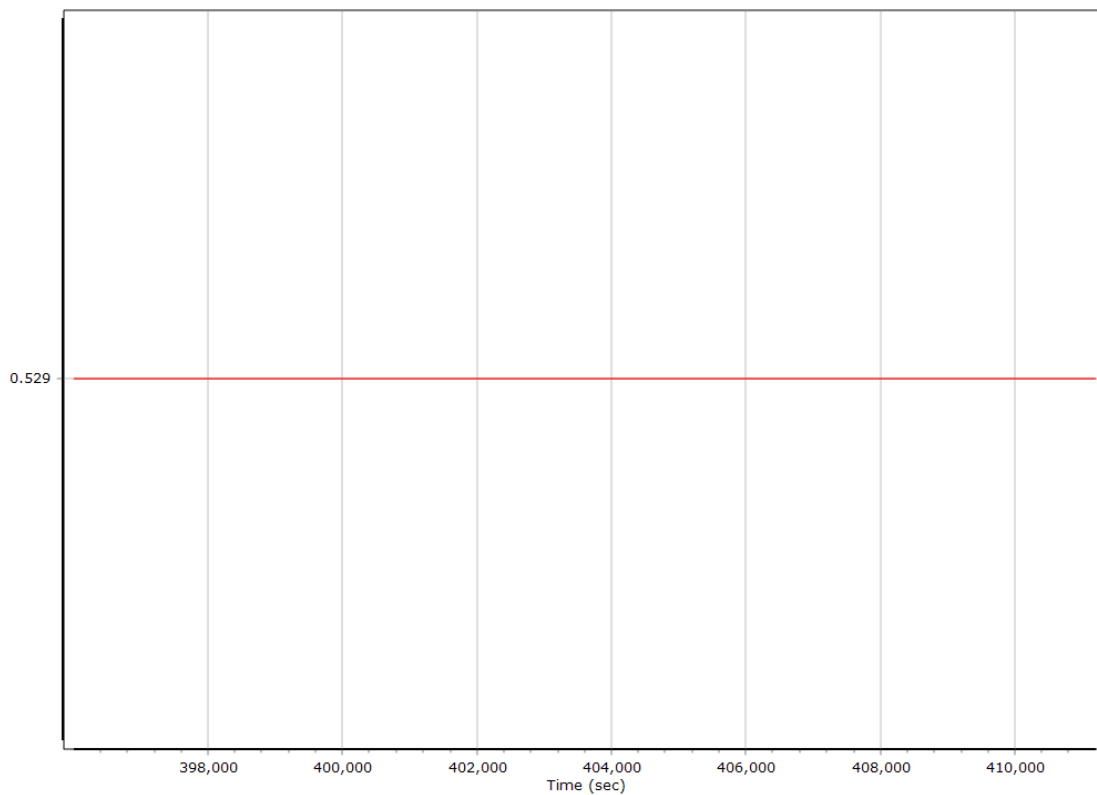
## GNSS-Inertial Processor Configuration

Processing mode	IN-Fusion PP-RTX		
Stabilized mount	False		
Processing start time	395739.000 (11/26/2020 1:55:39 PM)		
Processing end time	411213.000 (11/26/2020 6:13:33 PM)		
Initial attitude source	Real-Time VNAV/RNAV Attitude		
IMU Sensor Context	Processing with Onboard IMU		
Reference to IMU lever arm (m)	0.000	0.000	0.000
Reference to IMU mounting angles (deg)	0.000	0.000	180.000
Reference to Primary GNSS lever arm (m)	0.529	-0.432	-0.963
Reference to Primary GNSS lever arm std dev (m)	0.030	0.030	0.030
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

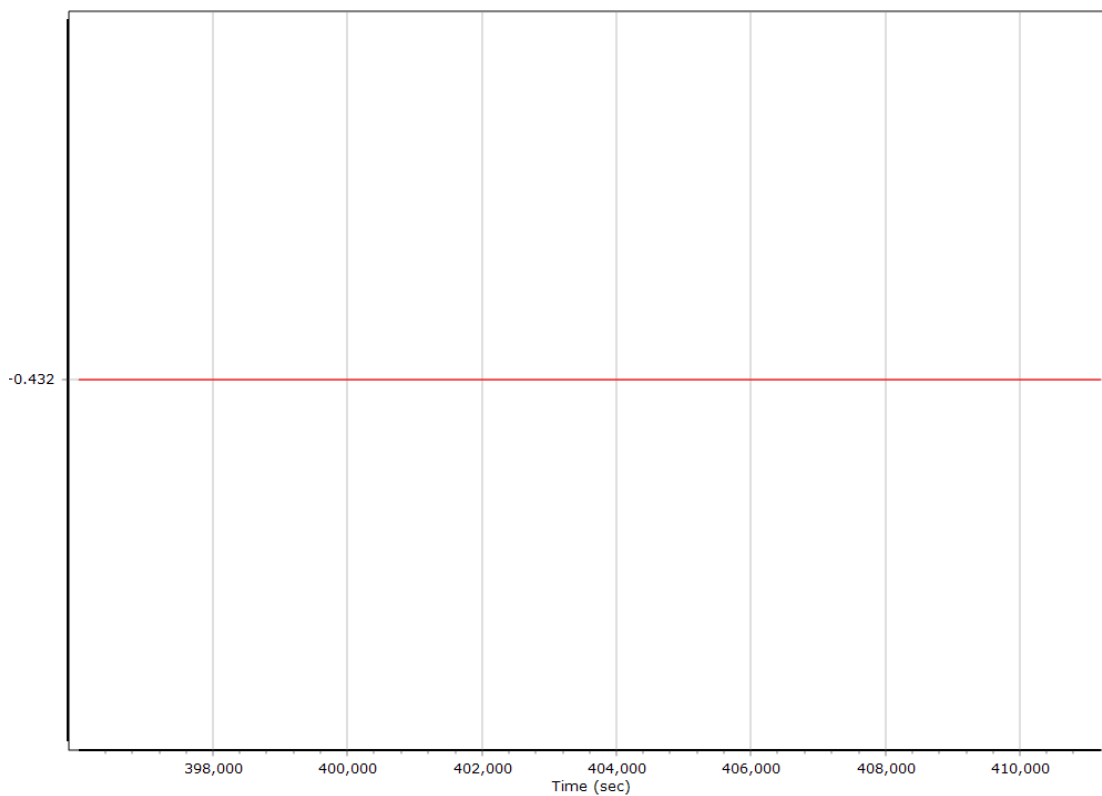
## Calibrated Installation Parameters

### Reference-Primary GNSS Lever Arm (m)

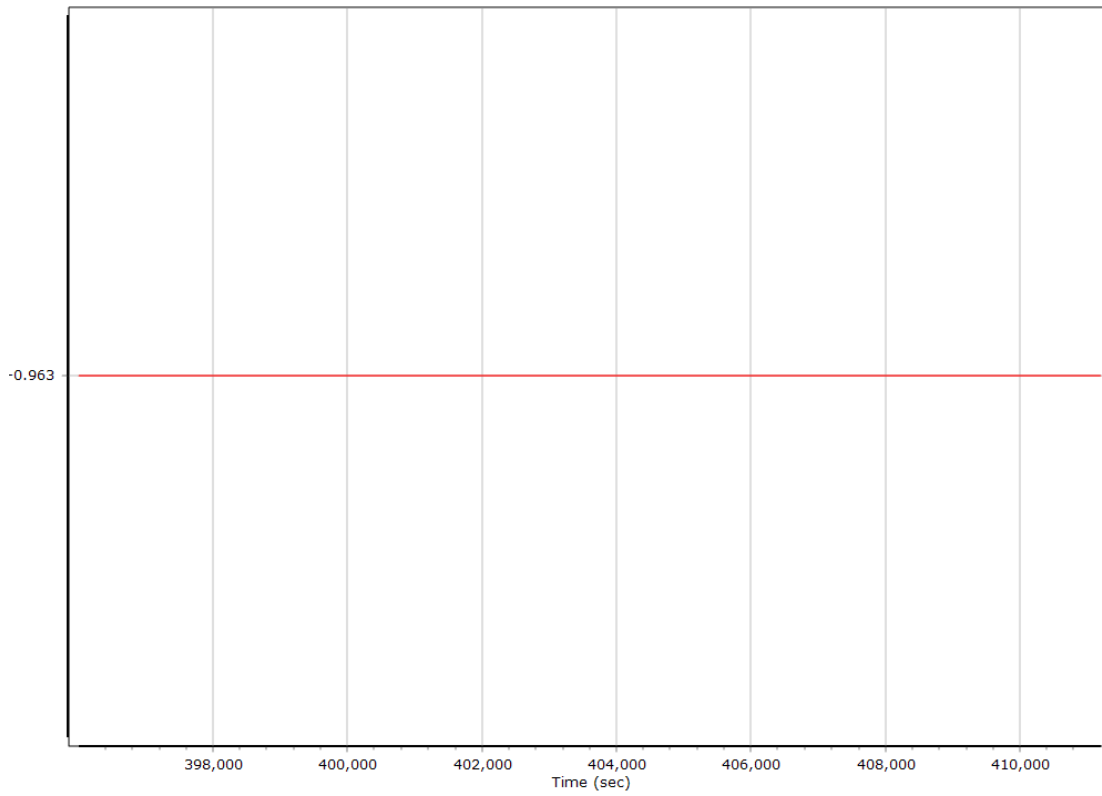
#### X Reference-Primary GNSS Lever Arm (m)



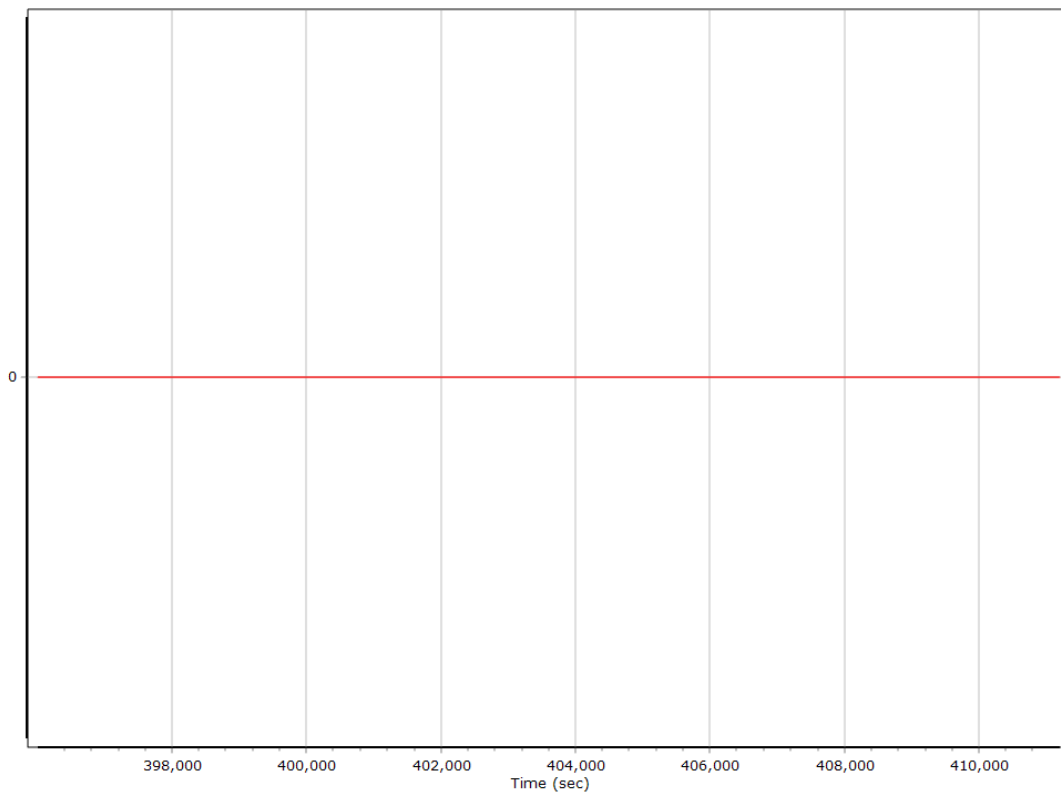
#### Y Reference-Primary GNSS Lever Arm (m)



### Z Reference-Primary GNSS Lever Arm (m)



### Reference-Primary GNSS Lever Arm Figure of Merit

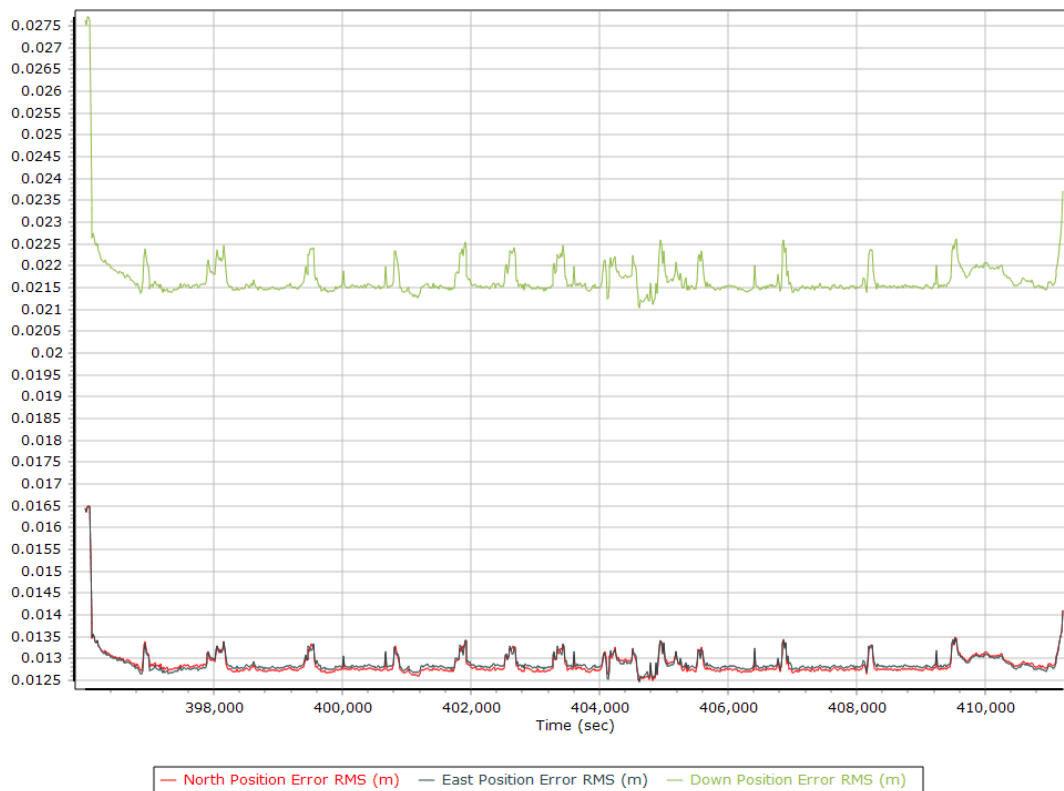


## IN-Fusion QC

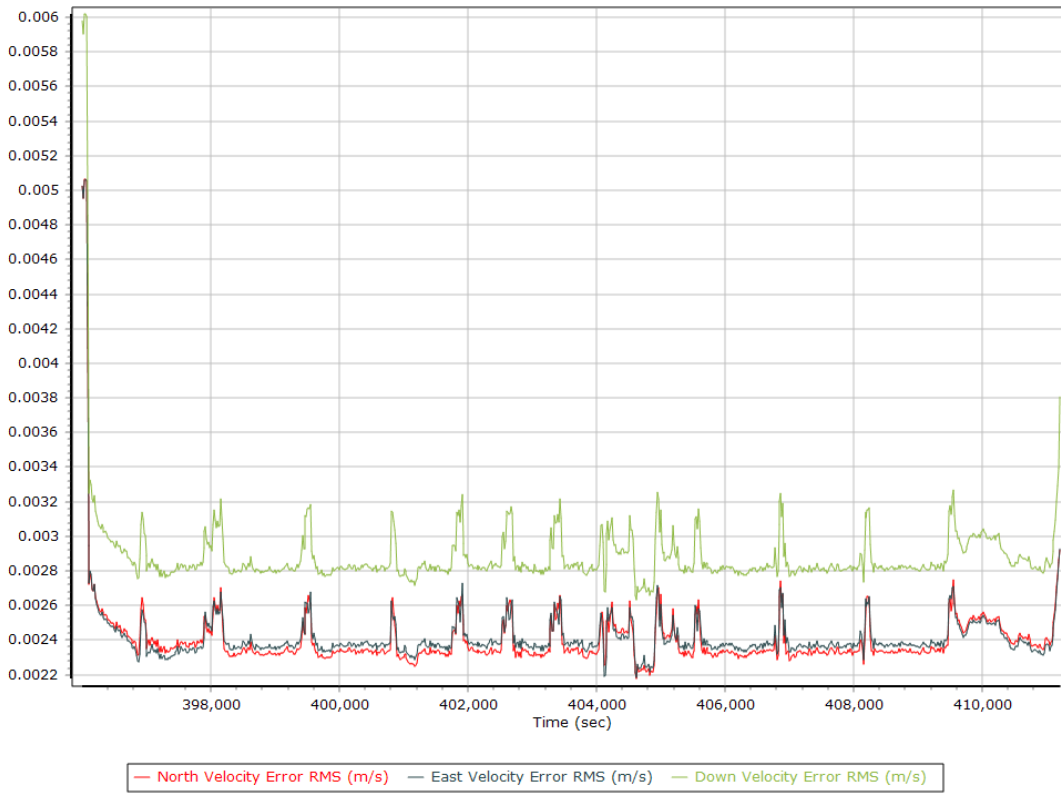
### Forward Processed Estimated Errors, Reference Frame

### Smoothed Performance Metrics

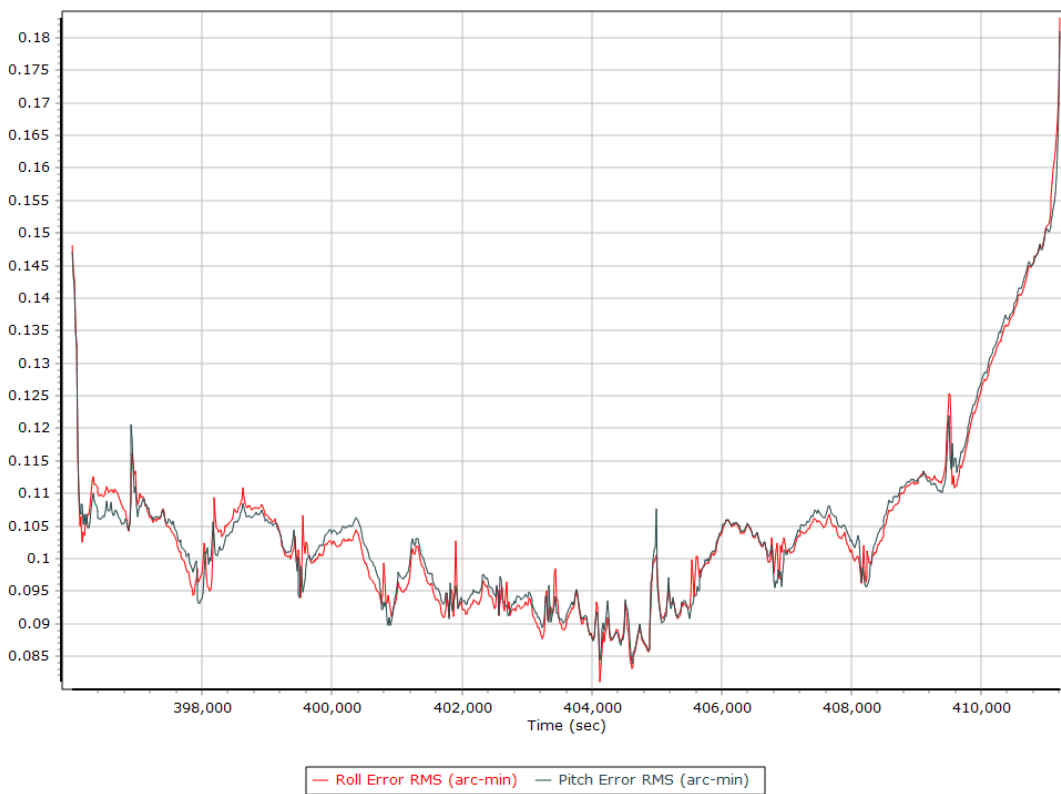
#### Position Error RMS (m)



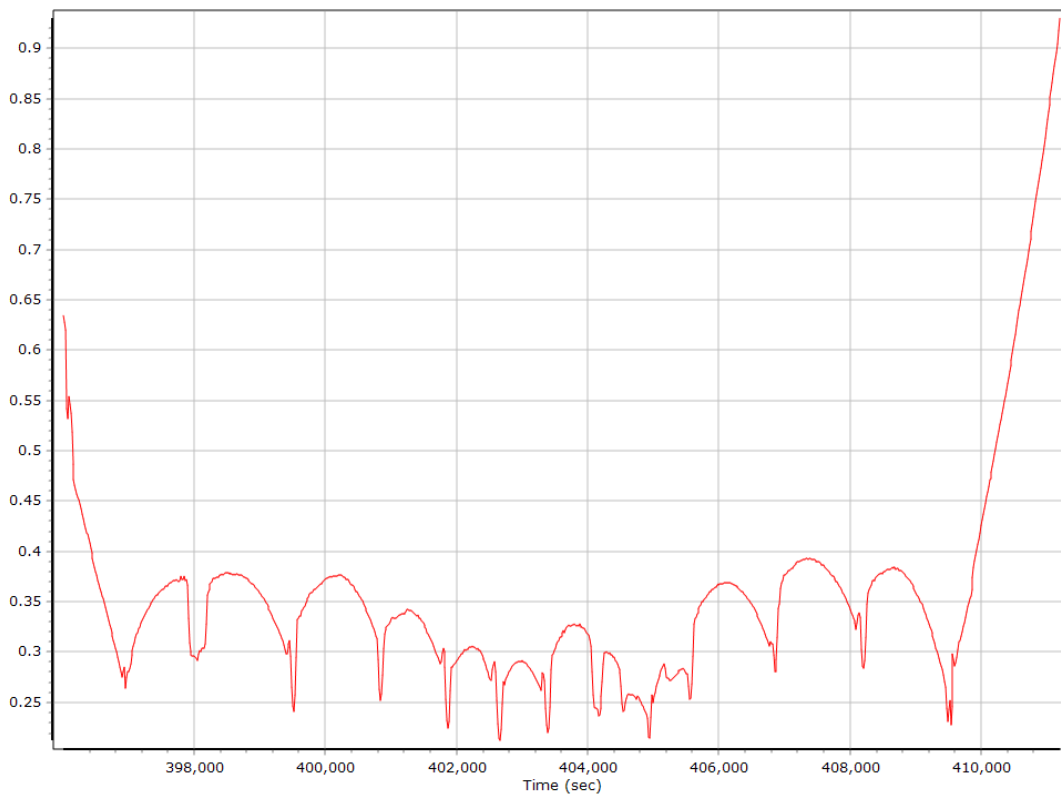
### Velocity Error RMS (m/s)



### Roll/Pitch Error RMS (arc-min)

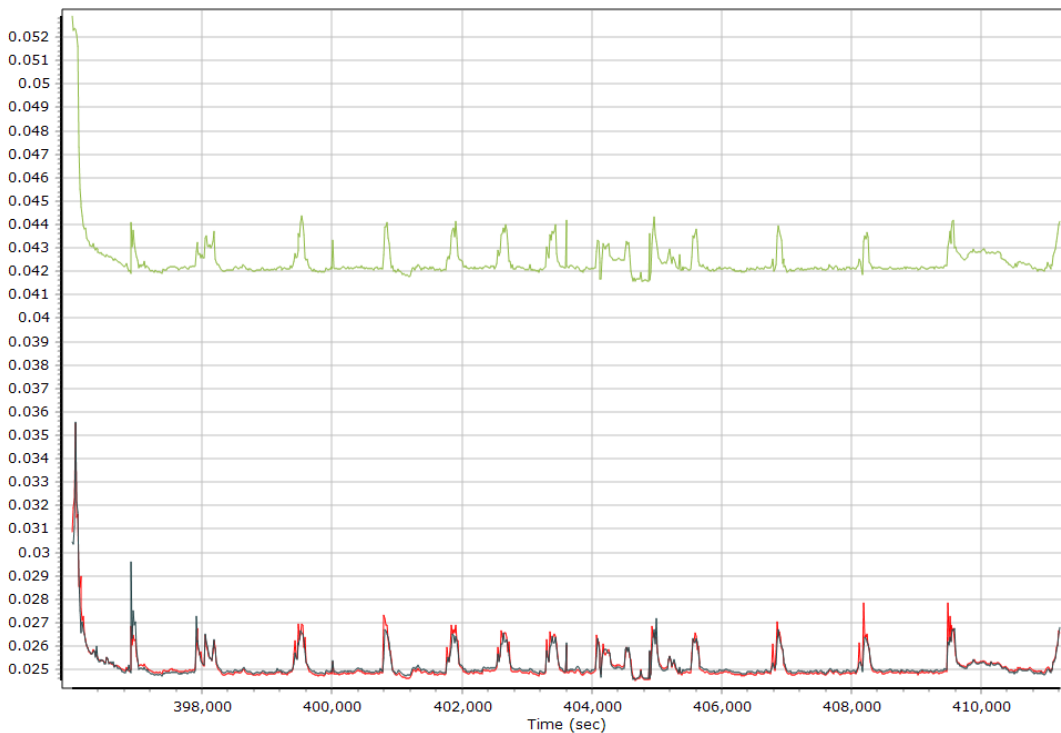


### Heading Error RMS (arc-min)



### Forward Processed Performance Metrics

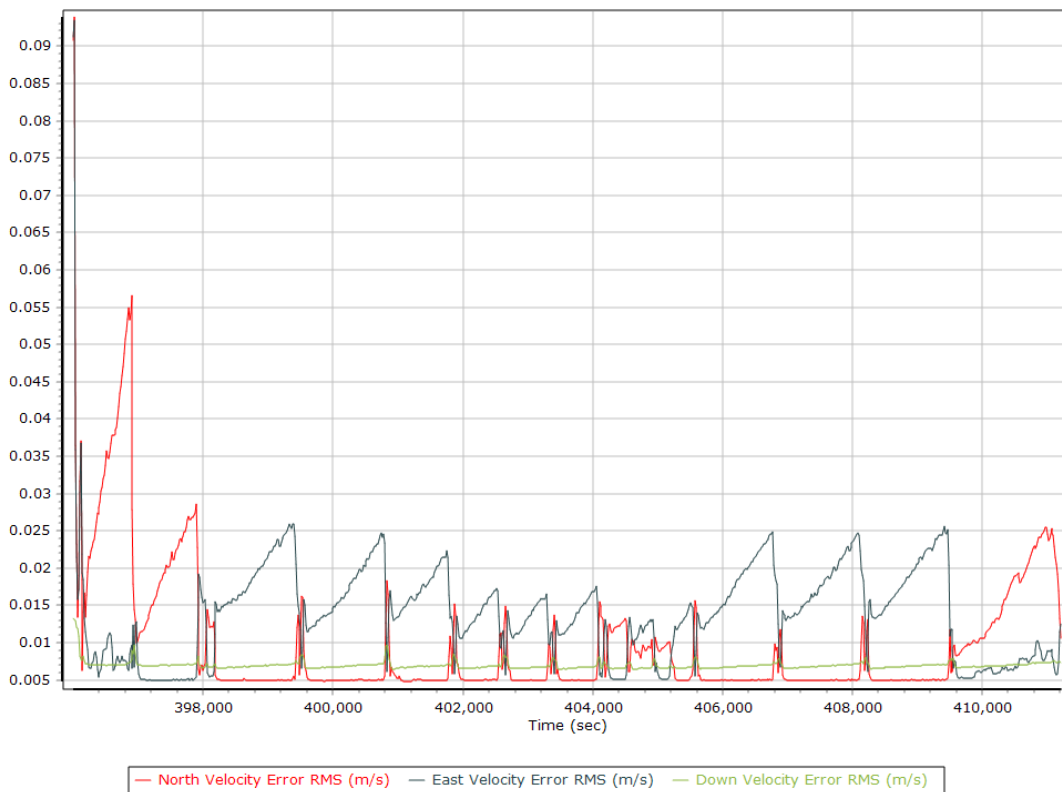
#### Position Error RMS (m)



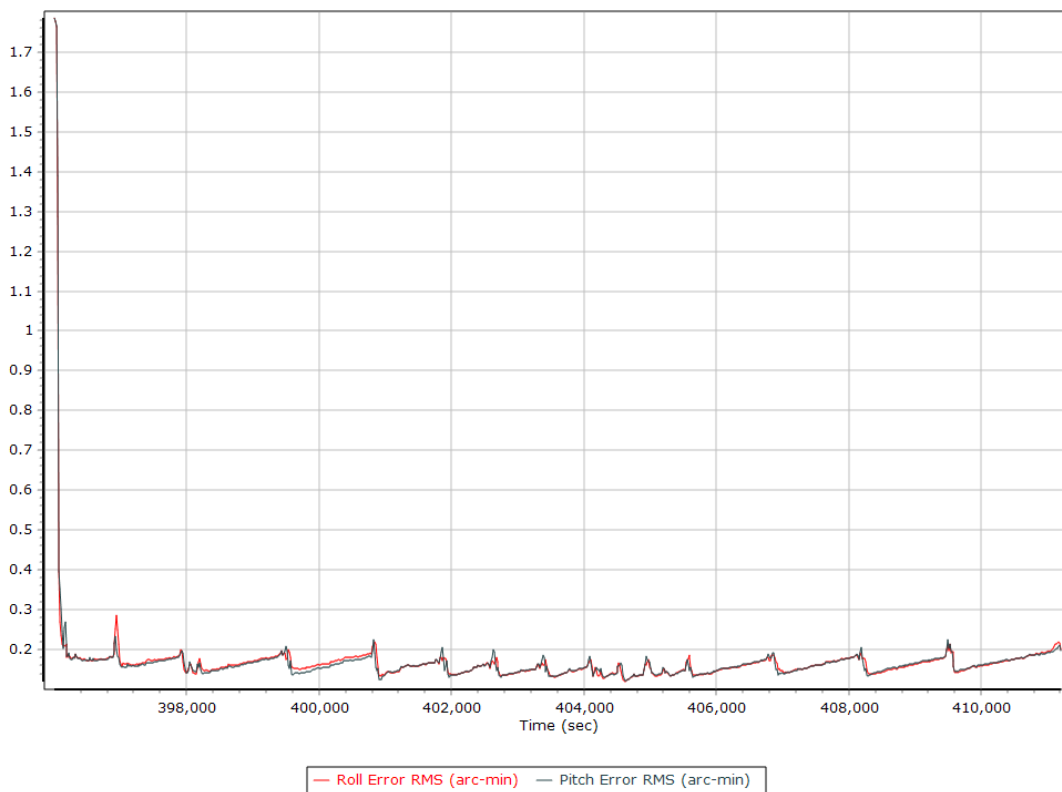
— North Position Error RMS (m) — East Position Error RMS (m) — Down Position Error RMS (m)



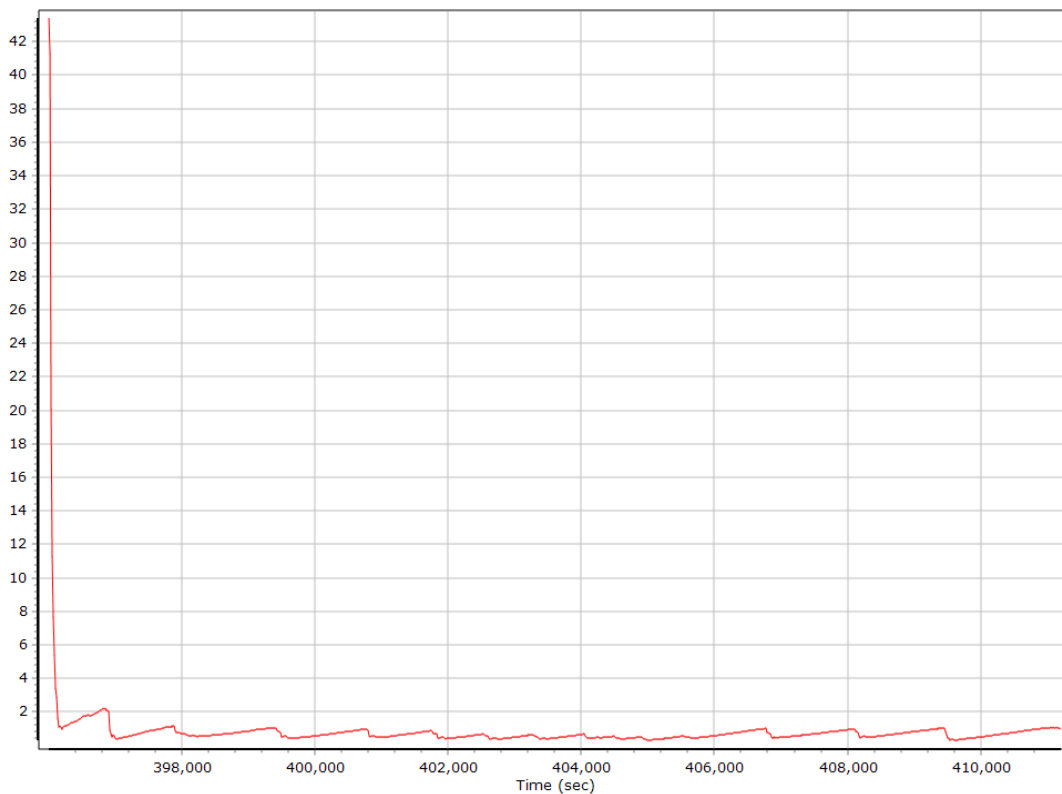
### Velocity Error RMS (m/s)



### Roll/Pitch Error RMS (arc-min)

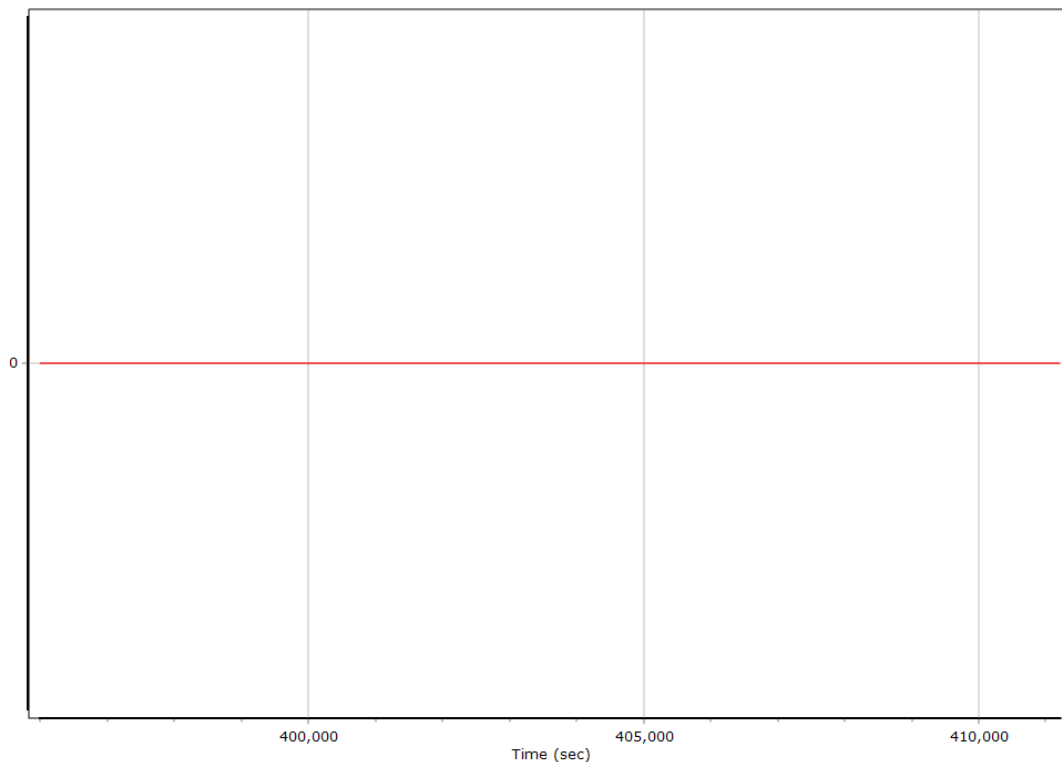


### Heading Error RMS (arc-min)



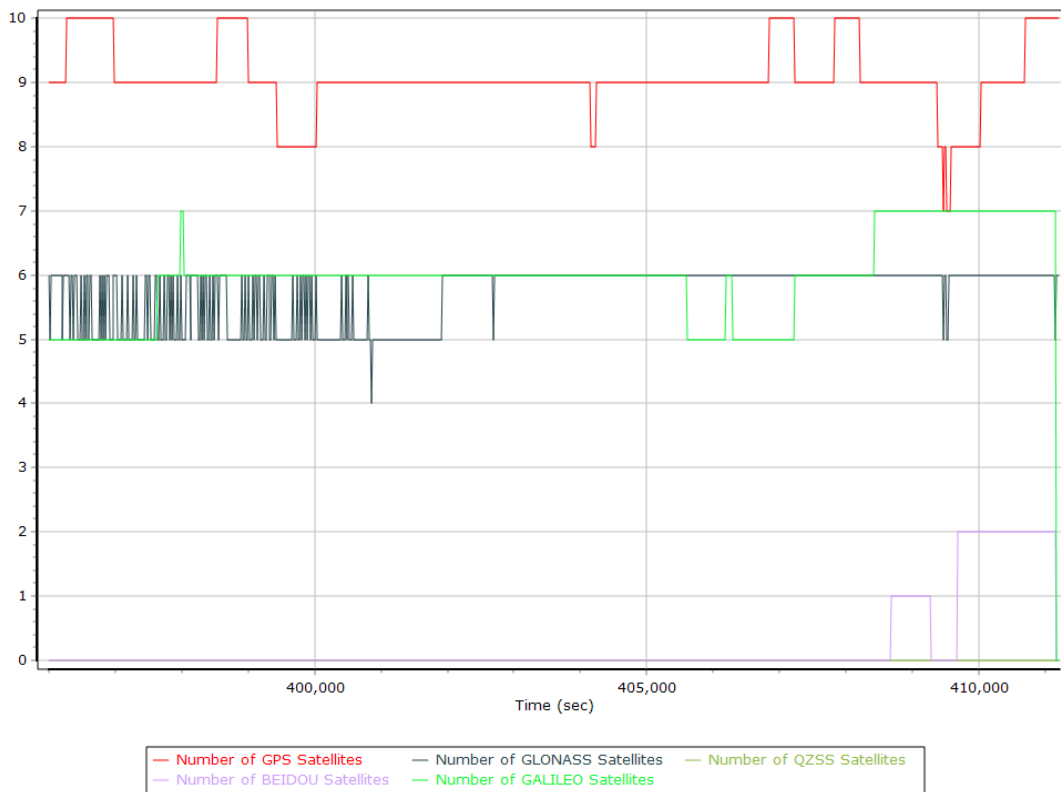
### Forward Processed Solution Status

#### Processing Mode



0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = C/A, 7 = GNSS Nav, 8 = DR

### Number of Satellites



### Baseline Length

