

General Information

Mission Information

Project name	11892
Processing date	2020-12-08 18:08:55
Mission date	2020-12-06 17:08:52
Mission duration	04:19:32.472
Processing mode	IN-Fusion PP-RTX

Rover Hardware Information

Product	POS AV 610 VER6 HW2.5-12
Serial number	S/N10633
IMU type	57
Receiver type	BD982
Antenna type	AV39

Project File List

Rover Data Files

File name	File type
20201206F1DAY.408	POS Data
20201206F1DAY.409	POS Data
20201206F1DAY.410	POS Data
20201206F1DAY.411	POS Data
20201206F1DAY.412	POS Data
20201206F1DAY.413	POS Data
20201206F1DAY.414	POS Data
20201206F1DAY.415	POS Data
20201206F1DAY.416	POS Data
20201206F1DAY.417	POS Data
20201206F1DAY.418	POS Data
20201206F1DAY.419	POS Data
20201206F1DAY.420	POS Data
20201206F1DAY.421	POS Data
20201206F1DAY.422	POS Data
20201206F1DAY.423	POS Data
20201206F1DAY.424	POS Data
20201206F1DAY.425	POS Data
20201206F1DAY.426	POS Data
20201206F1DAY.427	POS Data
20201206F1DAY.428	POS Data
20201206F1DAY.429	POS Data
20201206F1DAY.430	POS Data
20201206F1DAY.431	POS Data
20201206F1DAY.432	POS Data
20201206F1DAY.433	POS Data
20201206F1DAY.434	POS Data
20201206F1DAY.435	POS Data
20201206F1DAY.436	POS Data
20201206F1DAY.437	POS Data
20201206F1DAY.438	POS Data
20201206F1DAY.439	POS Data
20201206F1DAY.440	POS Data

Input Files

File Name	File Type
Ephm3410.20g	GLONASS Broadcast Ephemeris
Ephm3410.20n	GPS Broadcast Ephemeris

Output Files

Filename	File type
sbet_11892.out	SBET Trajectory File
eo_11892.txt	ZI Imaging POSEO Output
sbet_11892_NAD83(2011).out	Custom Smoothed BET Export Output
lever_arm_values.txt	ReferenceToPrimaryLeverArms Export Output

Rover Data Summary

First raw data file	20201206F1DAY.408		
Last raw data file	20201206F1DAY.440		
Start GPS week	2135		
Start time	61731.363 (12/06/2020 17:08:51)		
End time	77303.835 (12/06/2020 21:28:23)		
Start of fine alignment	62074.166 (12/06/2020 17:14:34)		
Available subsystems	Primary GNSS, IMU		
POS Event Input	None		
Correction data	None		
IMU Installation Lever Arms & Mounting Angles			
Reference to IMU lever arm (m)	0.000	0.000	0.000
Reference to IMU mounting angles (deg)	0.000	0.000	180.000
Reference to Primary GNSS lever arm (m)	-0.485	-0.379	-1.087
Reference to Primary GNSS lever arm std dev (m)	-1.000		
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

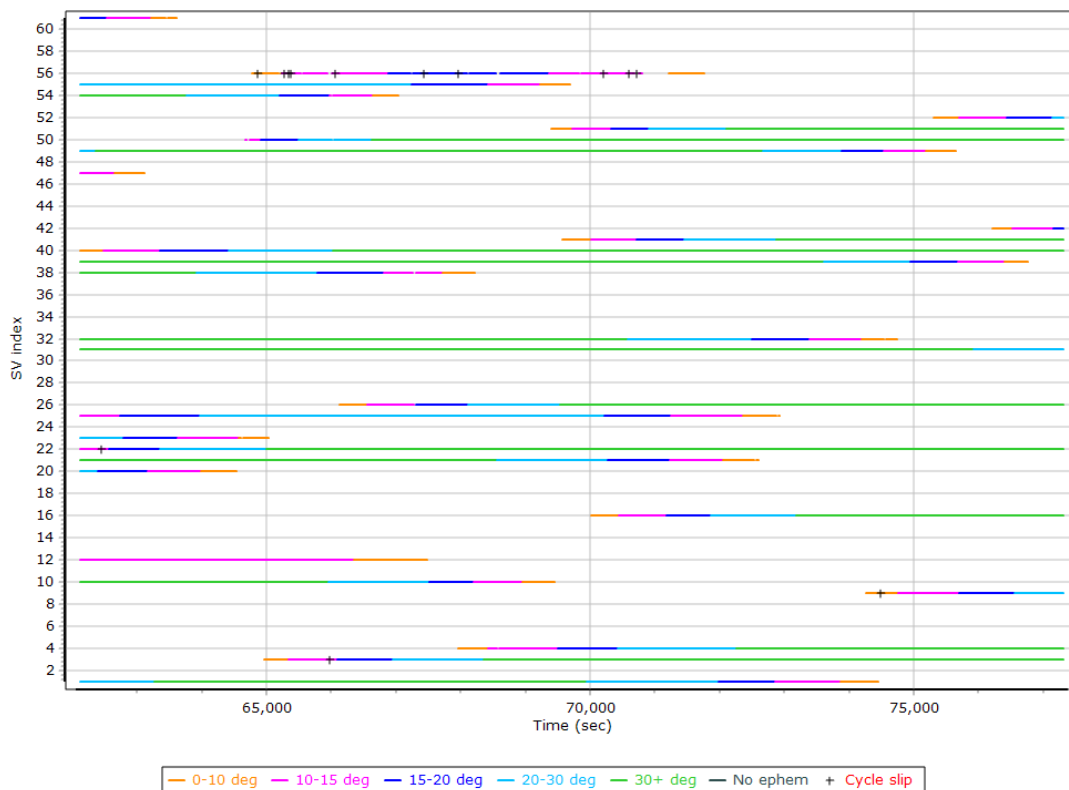
Rover Data QC

Raw IMU Import QC Summary

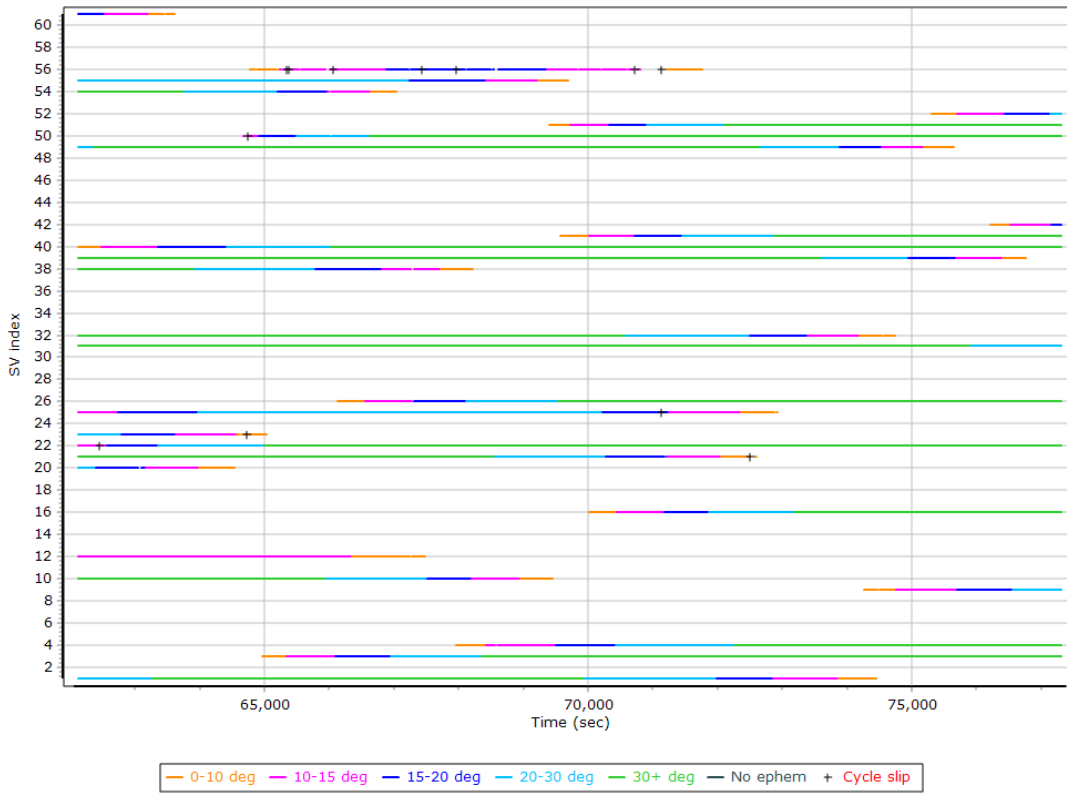
IMU data input file	imu_11892.dat
IMU data check log file	imudt_11892.log
IMU Records Processed	3113943
Termination Status	Normal
IMU Anomalies	0

Primary Observables & Satellite Data

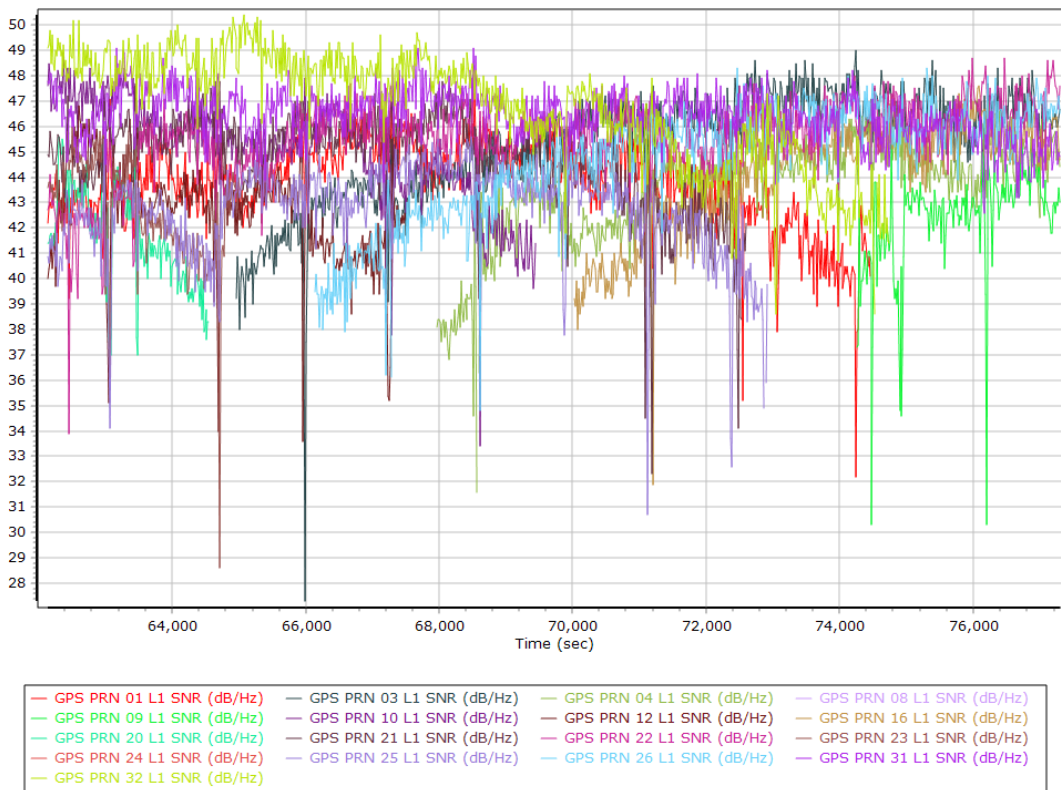
L1 Satellite Lock/Elevation



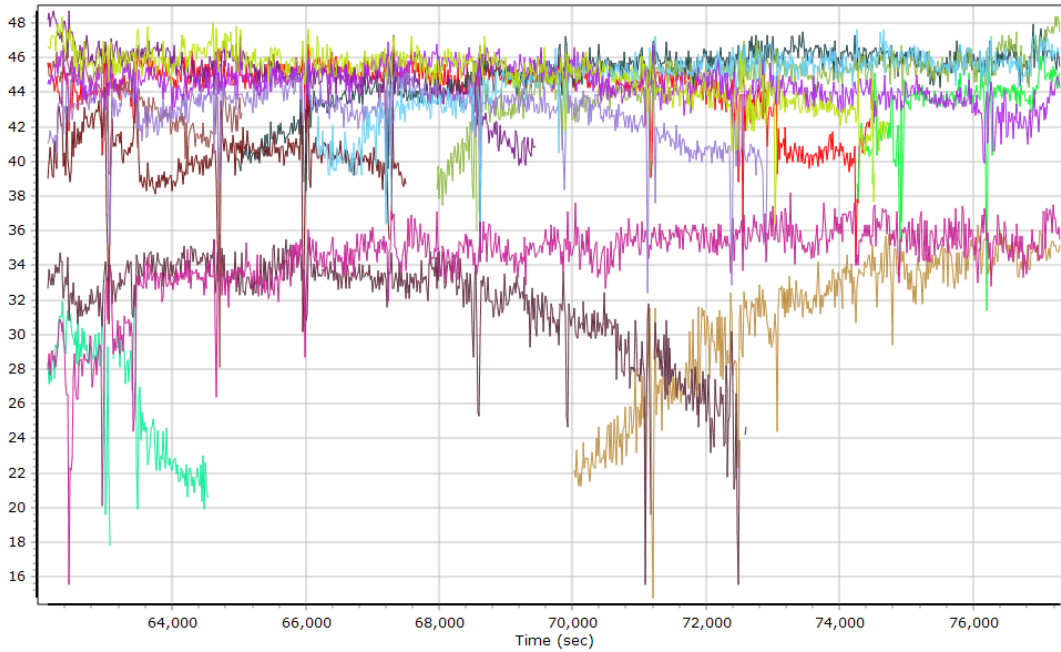
L2 Satellite Lock/Elevation



GPS L1 SNR

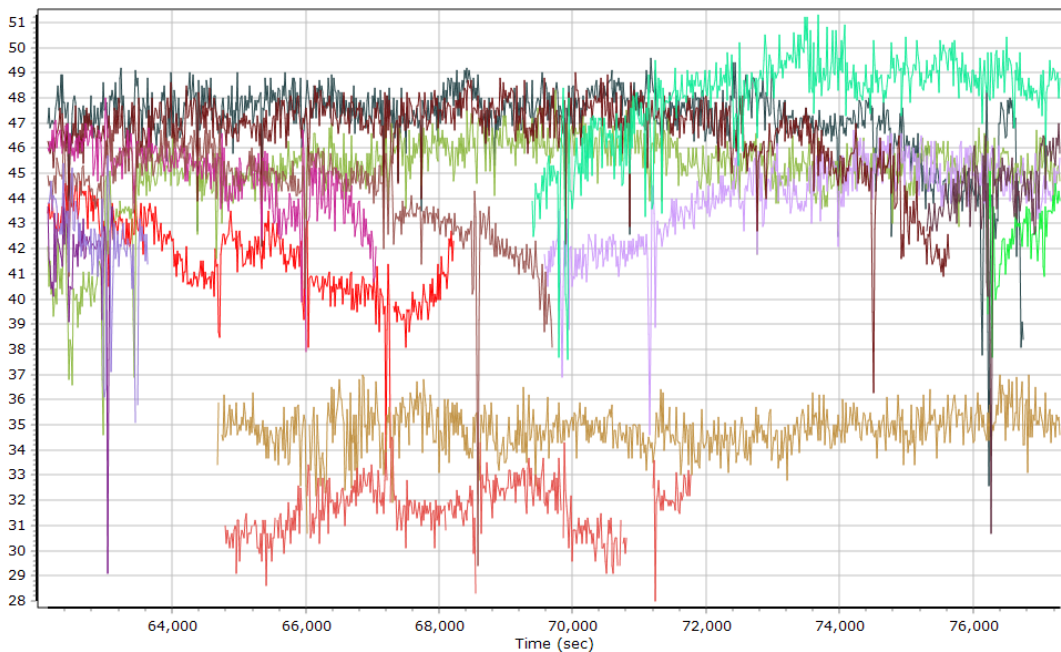


GPS L2 SNR



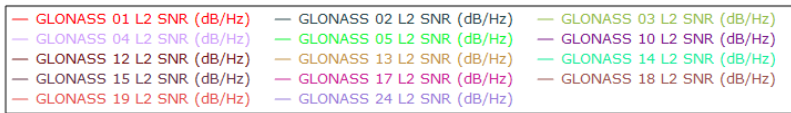
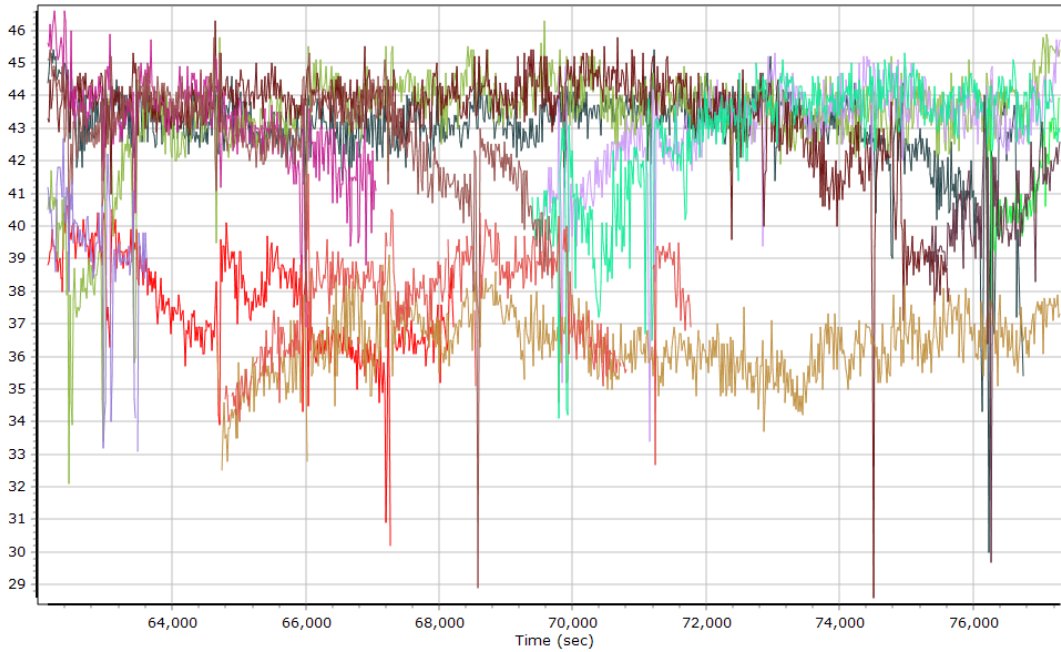
- | | | | |
|---------------------------|---------------------------|---------------------------|---------------------------|
| GPS PRN 01 L2 SNR (dB/Hz) | GPS PRN 03 L2 SNR (dB/Hz) | GPS PRN 04 L2 SNR (dB/Hz) | GPS PRN 08 L2 SNR (dB/Hz) |
| GPS PRN 09 L2 SNR (dB/Hz) | GPS PRN 10 L2 SNR (dB/Hz) | GPS PRN 12 L2 SNR (dB/Hz) | GPS PRN 16 L2 SNR (dB/Hz) |
| GPS PRN 20 L2 SNR (dB/Hz) | GPS PRN 21 L2 SNR (dB/Hz) | GPS PRN 22 L2 SNR (dB/Hz) | GPS PRN 23 L2 SNR (dB/Hz) |
| GPS PRN 24 L2 SNR (dB/Hz) | GPS PRN 25 L2 SNR (dB/Hz) | GPS PRN 26 L2 SNR (dB/Hz) | GPS PRN 31 L2 SNR (dB/Hz) |
| GPS PRN 32 L2 SNR (dB/Hz) | | | |

GLONASS L1 SNR

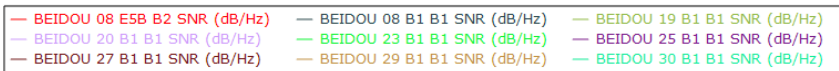
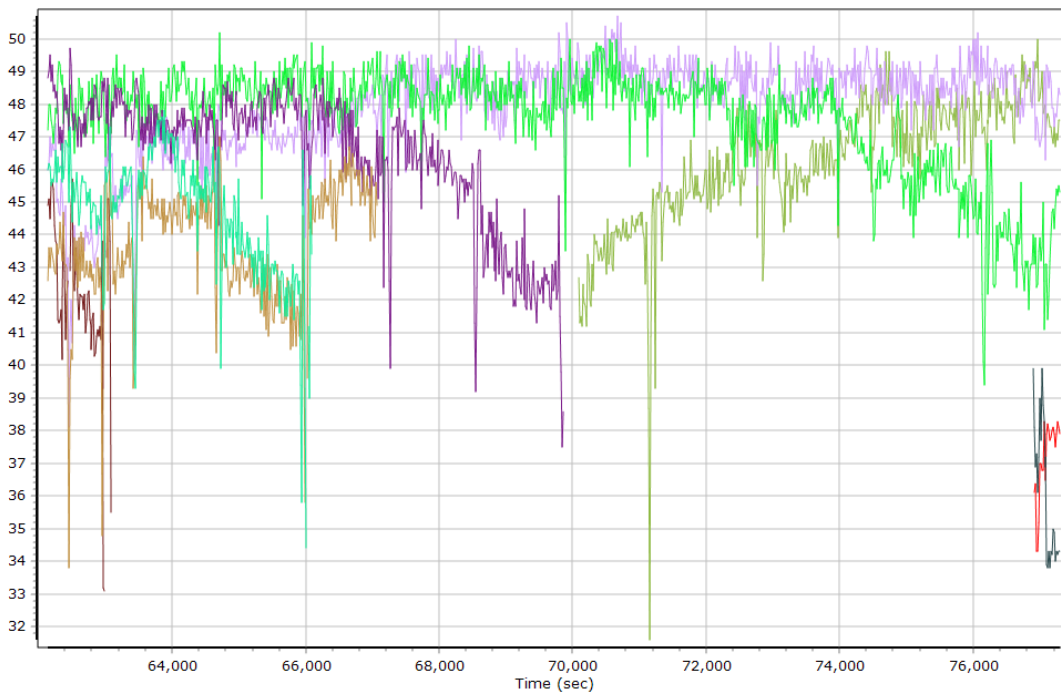


- | | | |
|---------------------------|---------------------------|---------------------------|
| GLONASS 01 L1 SNR (dB/Hz) | GLONASS 02 L1 SNR (dB/Hz) | GLONASS 03 L1 SNR (dB/Hz) |
| GLONASS 04 L1 SNR (dB/Hz) | GLONASS 05 L1 SNR (dB/Hz) | GLONASS 10 L1 SNR (dB/Hz) |
| GLONASS 12 L1 SNR (dB/Hz) | GLONASS 13 L1 SNR (dB/Hz) | GLONASS 14 L1 SNR (dB/Hz) |
| GLONASS 15 L1 SNR (dB/Hz) | GLONASS 17 L1 SNR (dB/Hz) | GLONASS 18 L1 SNR (dB/Hz) |
| GLONASS 19 L1 SNR (dB/Hz) | GLONASS 24 L1 SNR (dB/Hz) | |

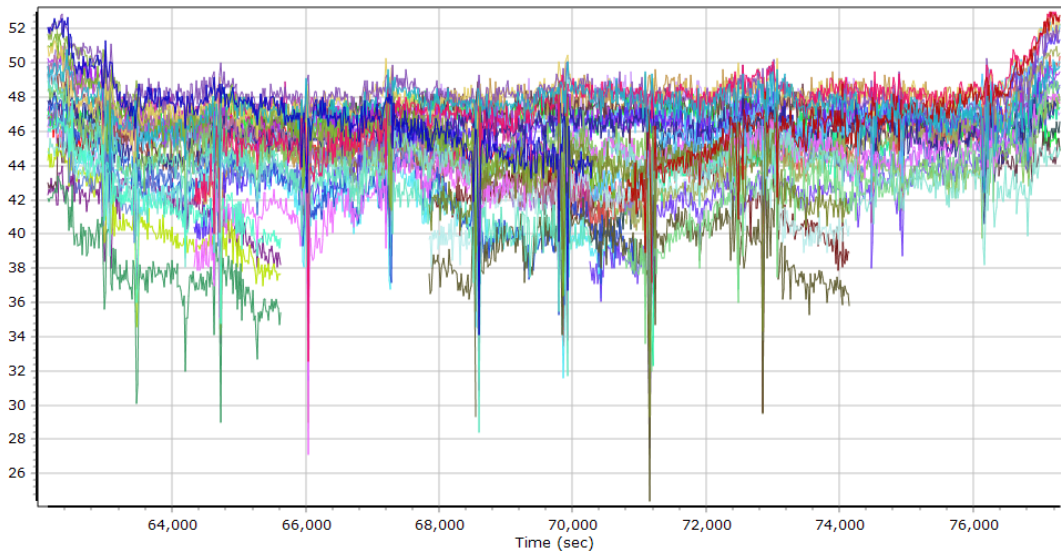
GLONASS L2 SNR



BEIDOU SNR



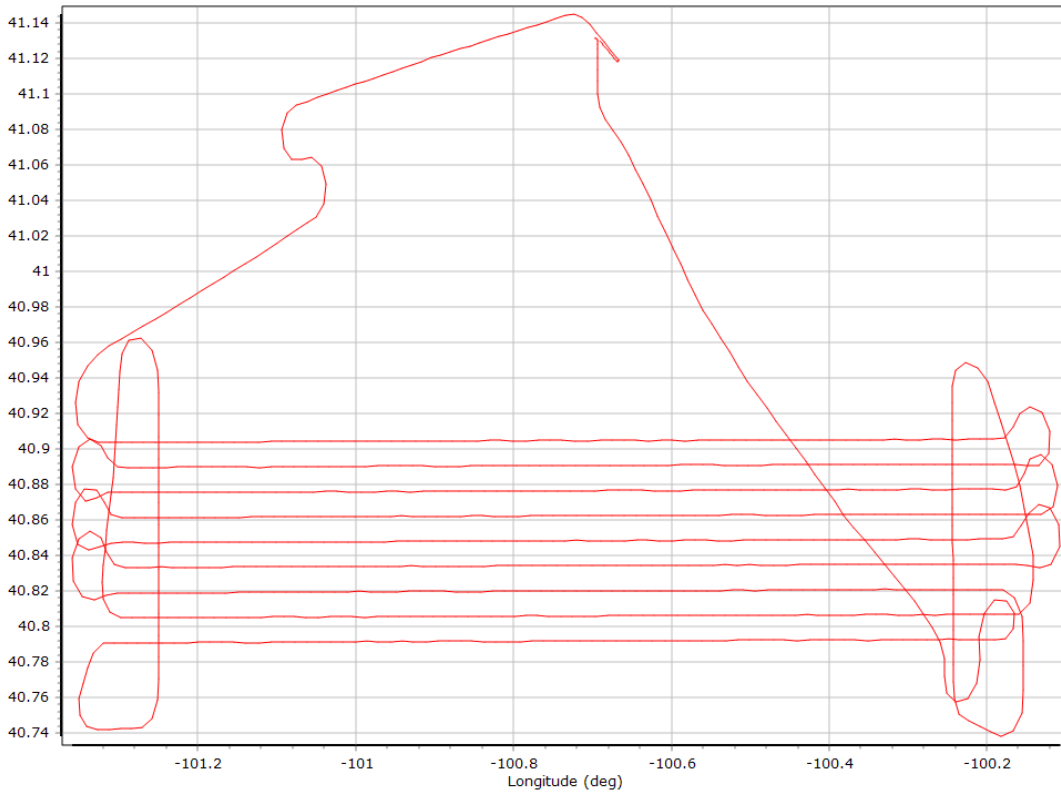
GALILEO SNR



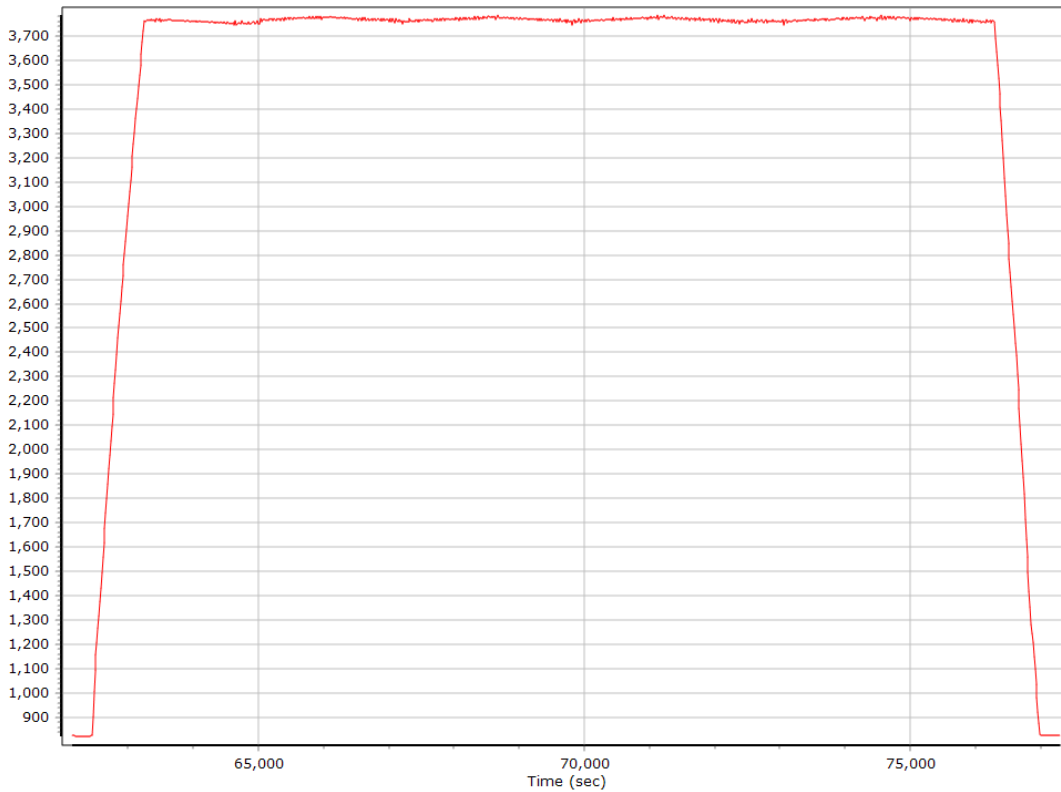
- | | |
|--|--|
| — GALILEO 01 L1 BOC_1_1_D_MBOC SNR (dB/Hz) | — GALILEO 03 L1 BOC_1_1_D_MBOC SNR (dB/Hz) |
| — GALILEO 04 L1 BOC_1_1_D_MBOC SNR (dB/Hz) | — GALILEO 05 L1 BOC_1_1_D_MBOC SNR (dB/Hz) |
| — GALILEO 09 L1 BOC_1_1_D_MBOC SNR (dB/Hz) | — GALILEO 11 L1 BOC_1_1_D_MBOC SNR (dB/Hz) |
| — GALILEO 15 L1 BOC_1_1_D_MBOC SNR (dB/Hz) | — GALILEO 24 L1 BOC_1_1_D_MBOC SNR (dB/Hz) |
| — GALILEO 25 L1 BOC_1_1_D_MBOC SNR (dB/Hz) | — GALILEO 31 L1 BOC_1_1_D_MBOC SNR (dB/Hz) |
| — GALILEO 36 L1 BOC_1_1_D_MBOC SNR (dB/Hz) | — GALILEO 01 L5E5A BPSK10_PD SNR (dB/Hz) |
| — GALILEO 03 L5E5A BPSK10_PD SNR (dB/Hz) | — GALILEO 04 L5E5A BPSK10_PD SNR (dB/Hz) |
| — GALILEO 05 L5E5A BPSK10_PD SNR (dB/Hz) | — GALILEO 09 L5E5A BPSK10_PD SNR (dB/Hz) |
| — GALILEO 11 L5E5A BPSK10_PD SNR (dB/Hz) | — GALILEO 15 L5E5A BPSK10_PD SNR (dB/Hz) |
| — GALILEO 24 L5E5A BPSK10_PD SNR (dB/Hz) | — GALILEO 25 L5E5A BPSK10_PD SNR (dB/Hz) |

Smoothed Trajectory Information

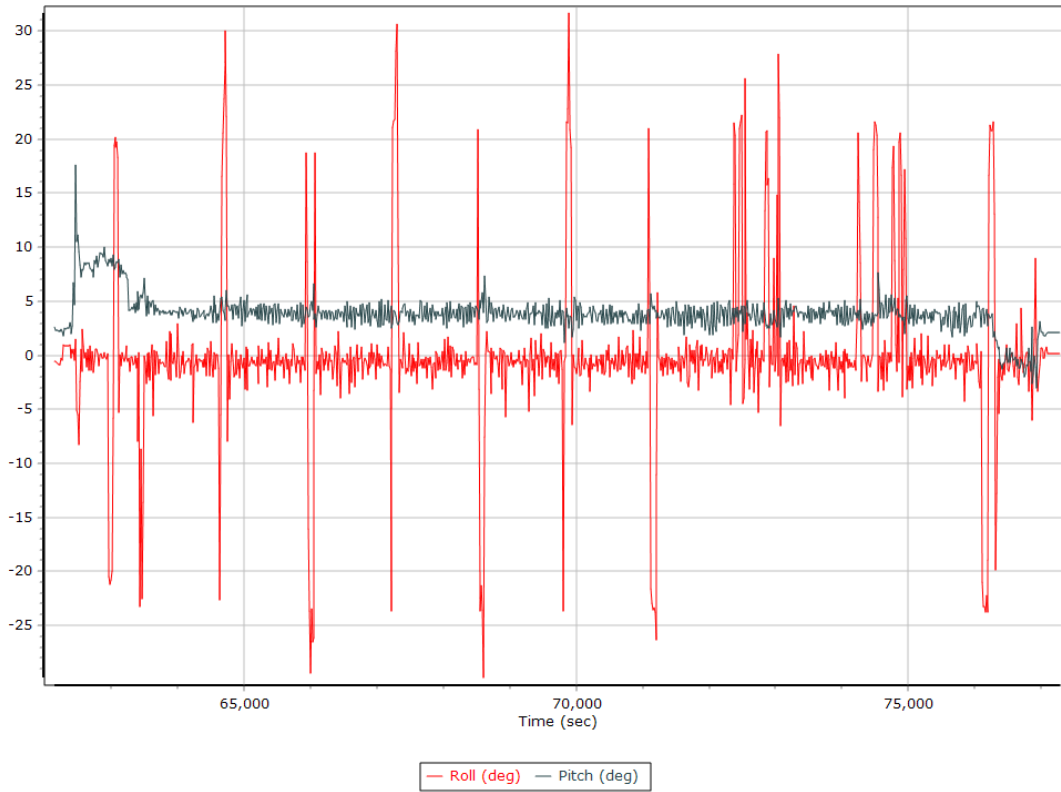
Top View



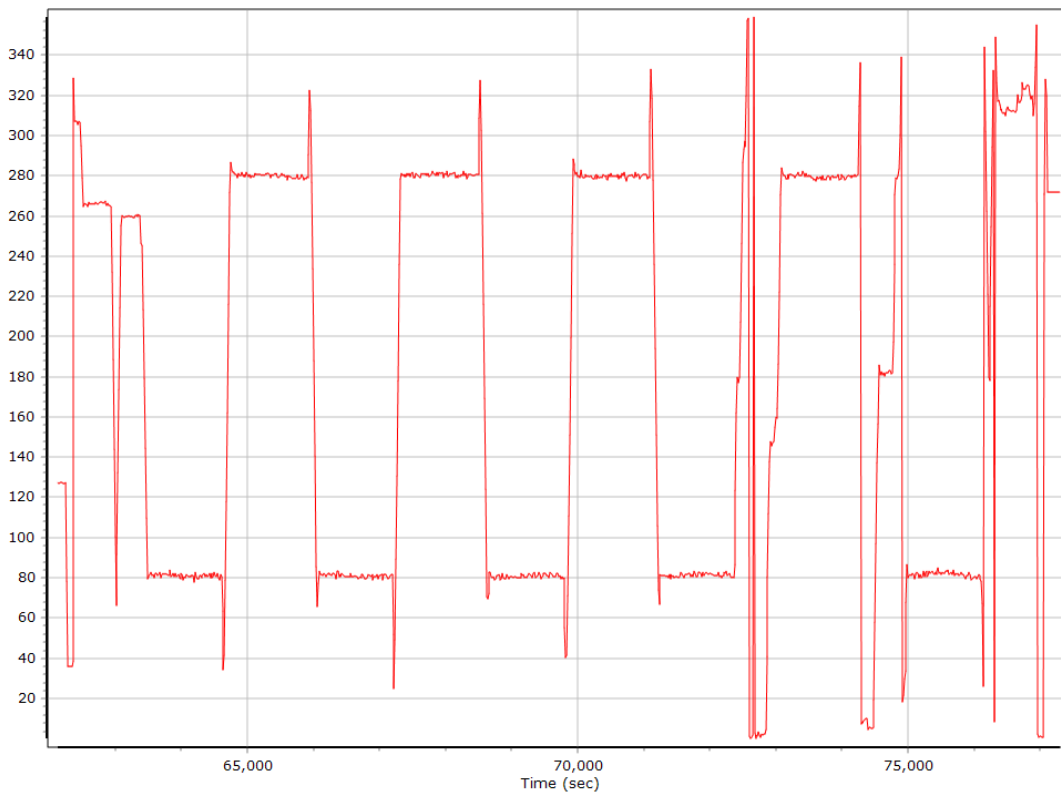
Altitude



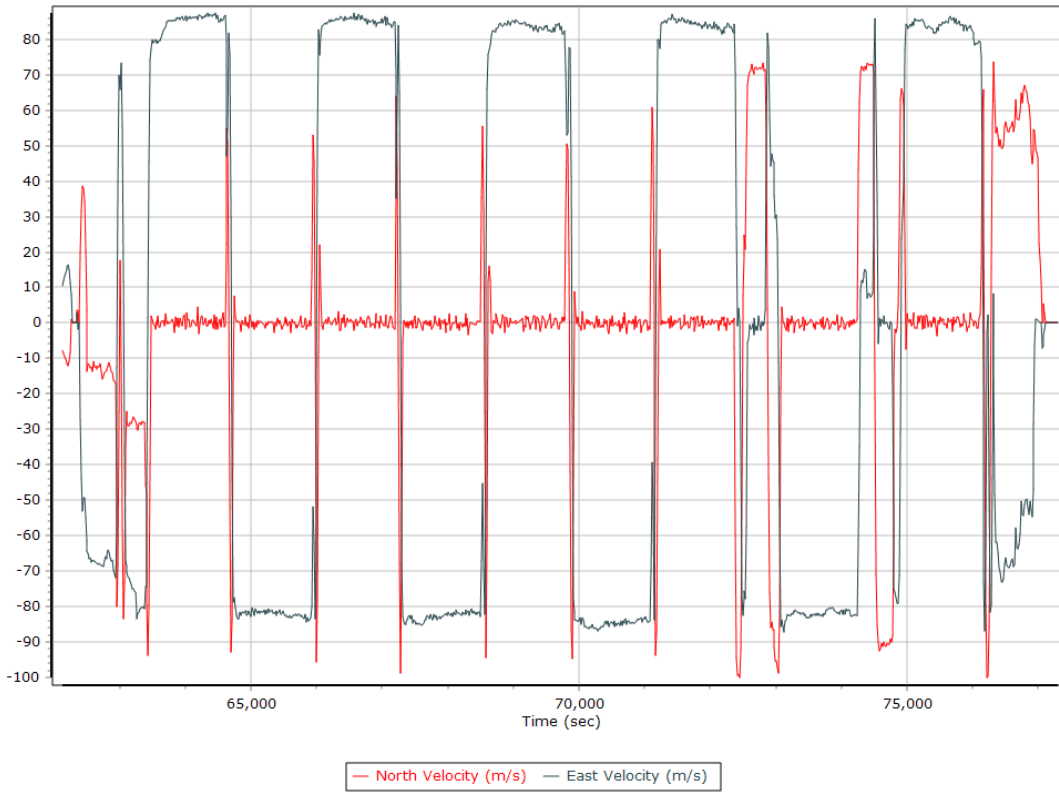
Roll/Pitch



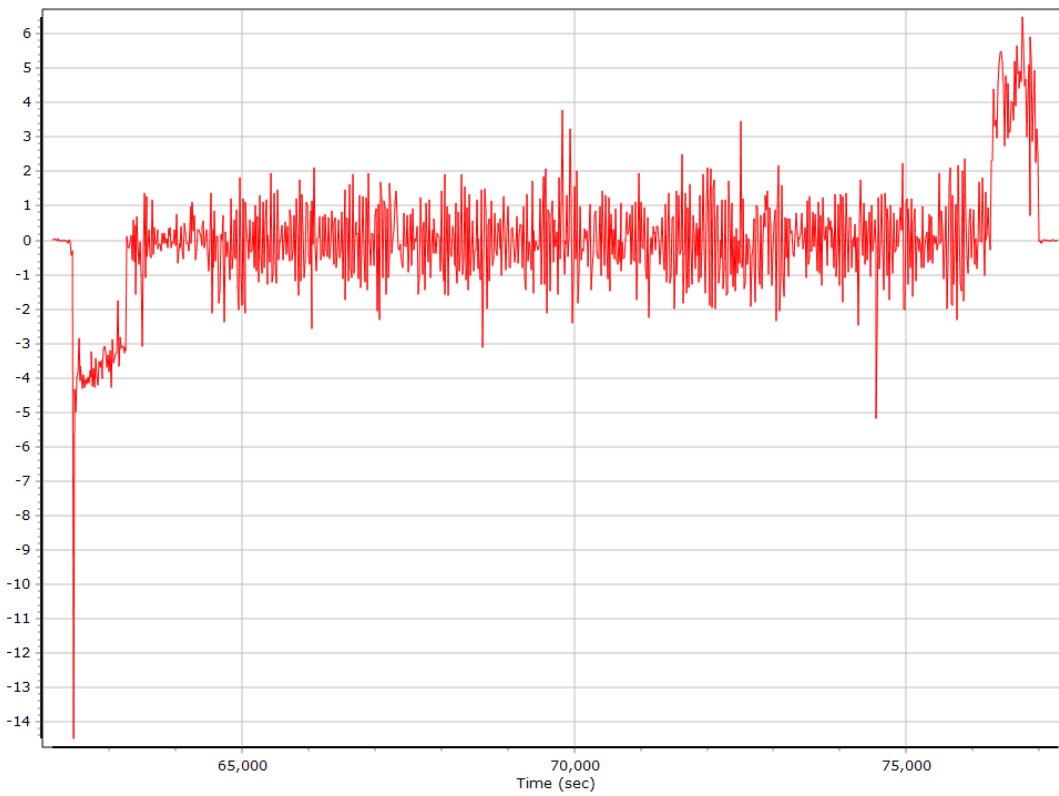
Heading



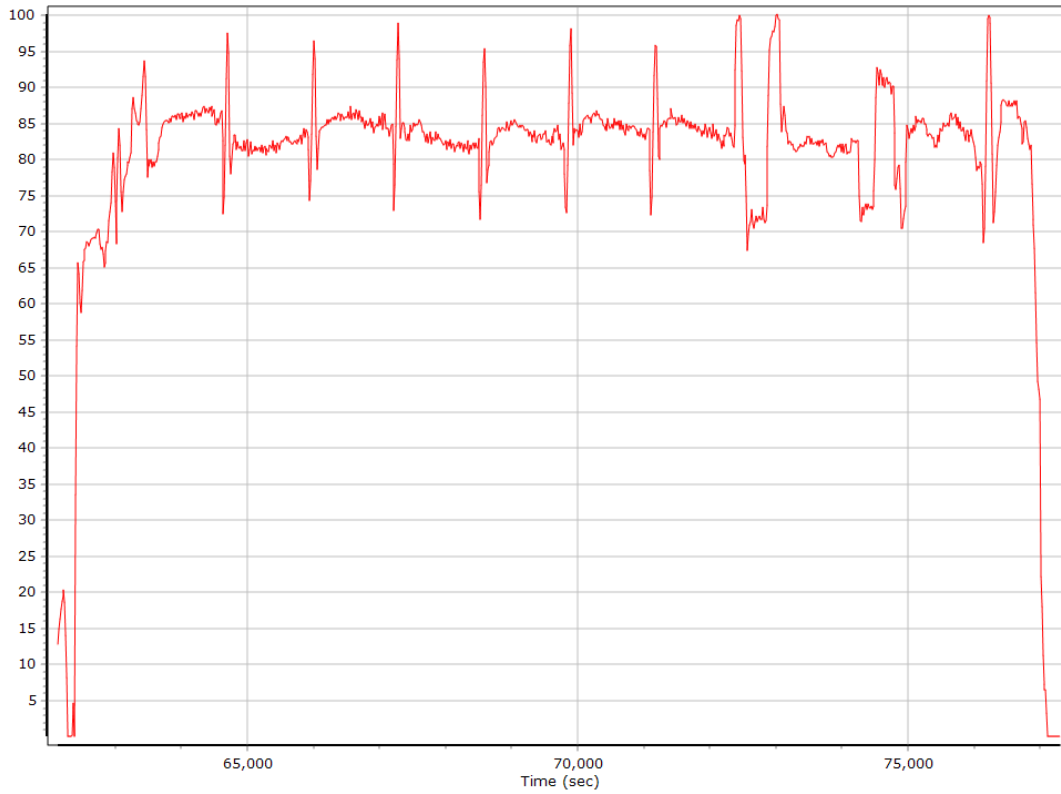
North/East Velocity



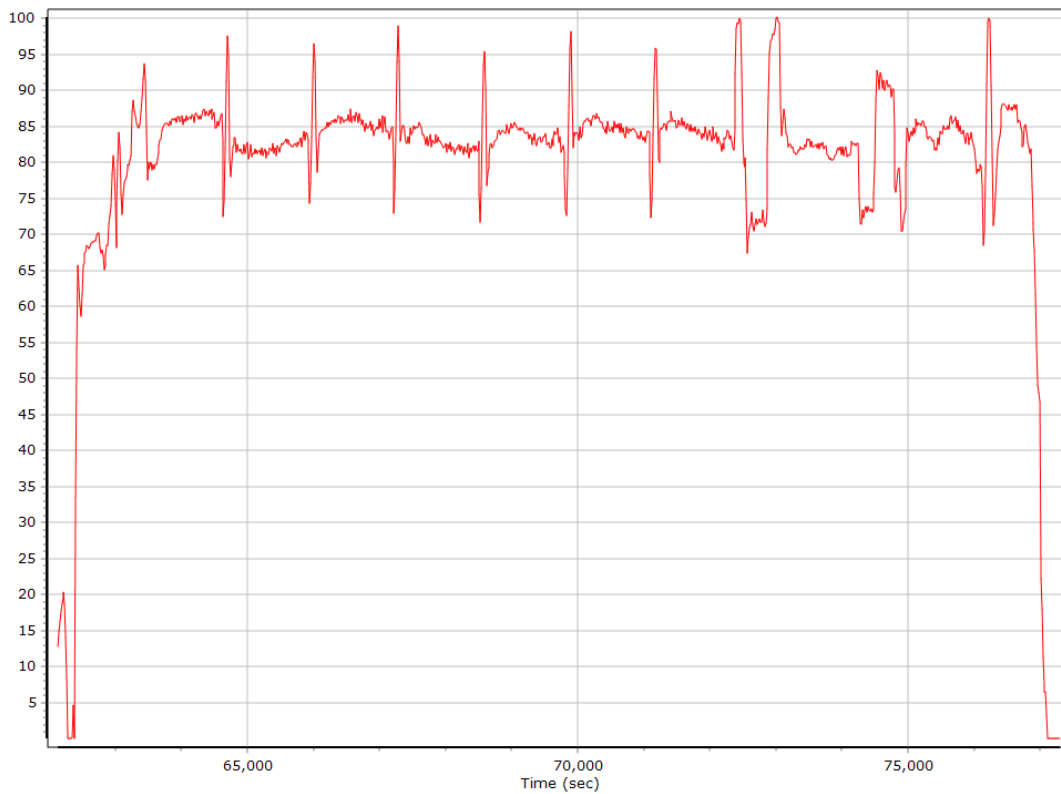
Down Velocity



Total Speed



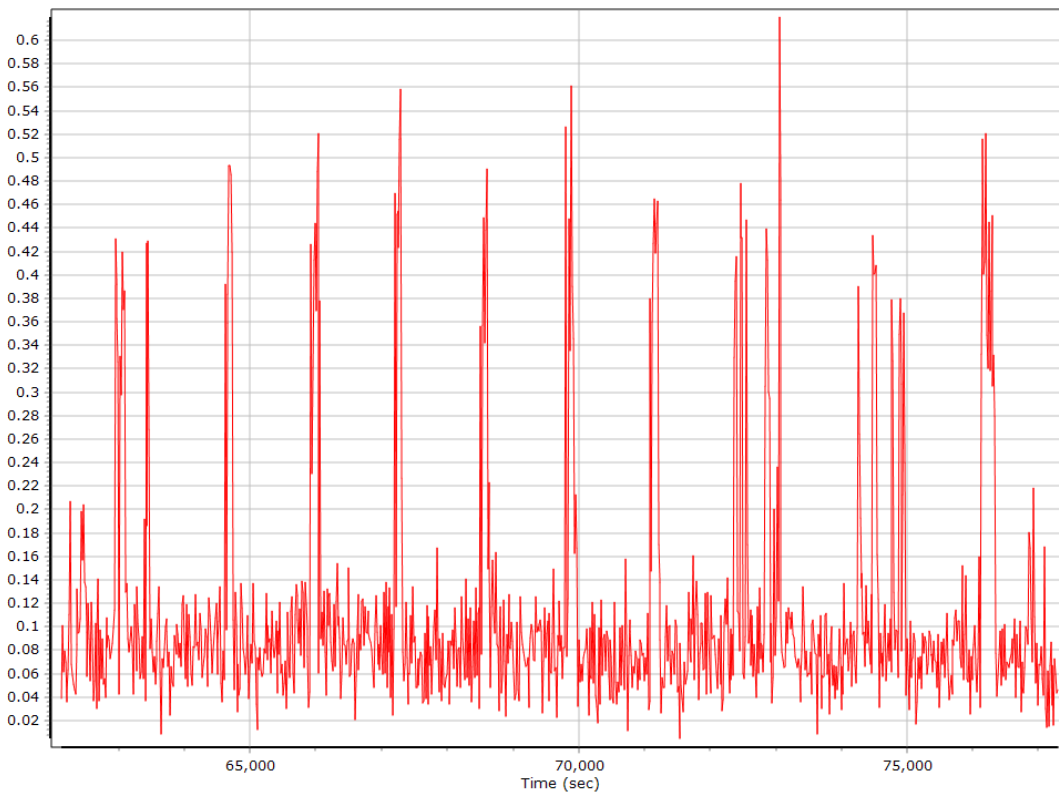
Ground Speed



Body Acceleration



Total Body Acceleration

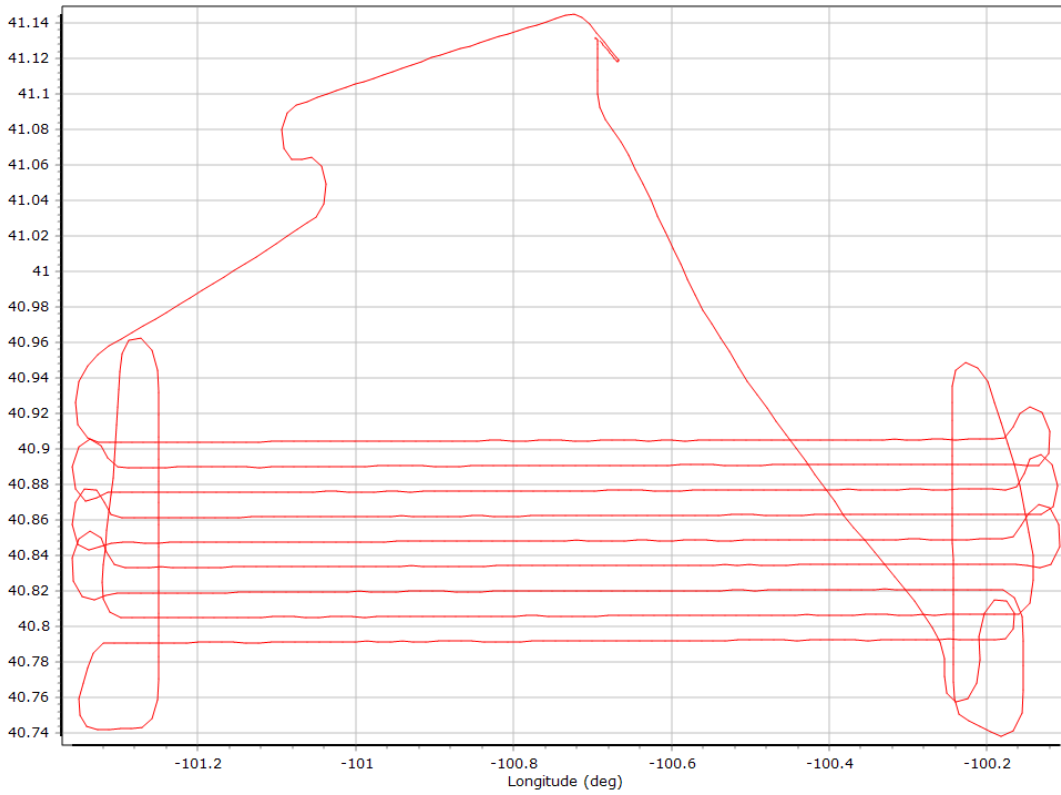


Body Angular Rate

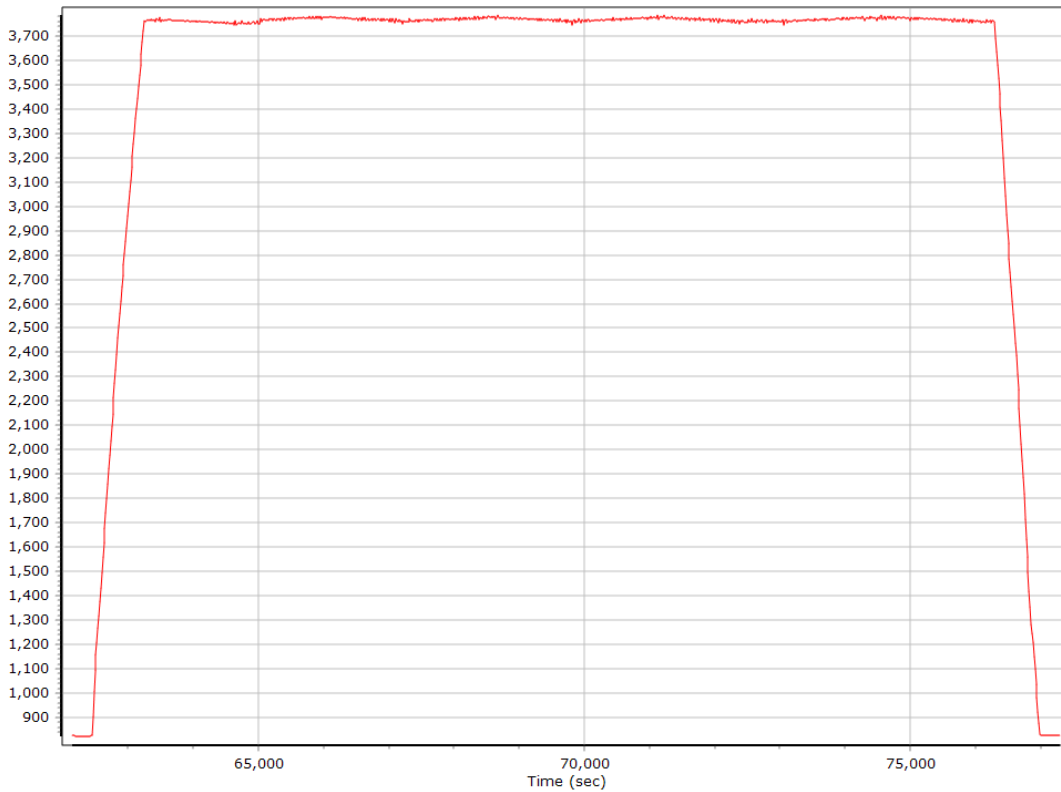


Forward Processed Trajectory Information

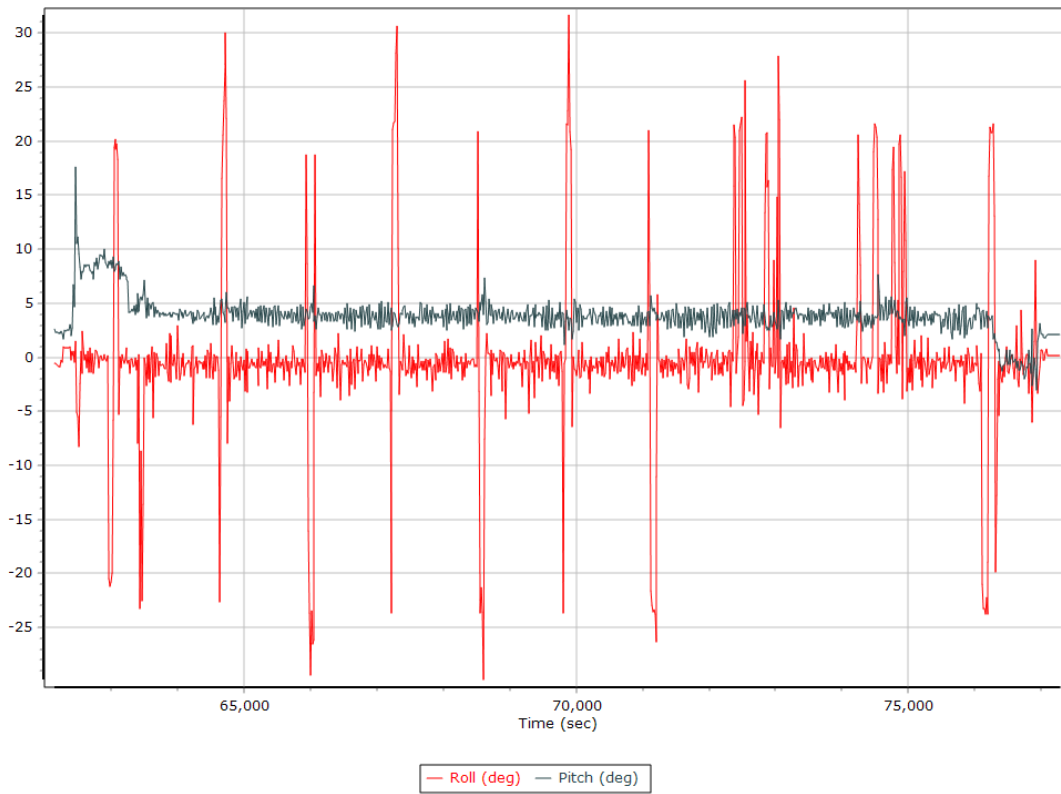
Top View



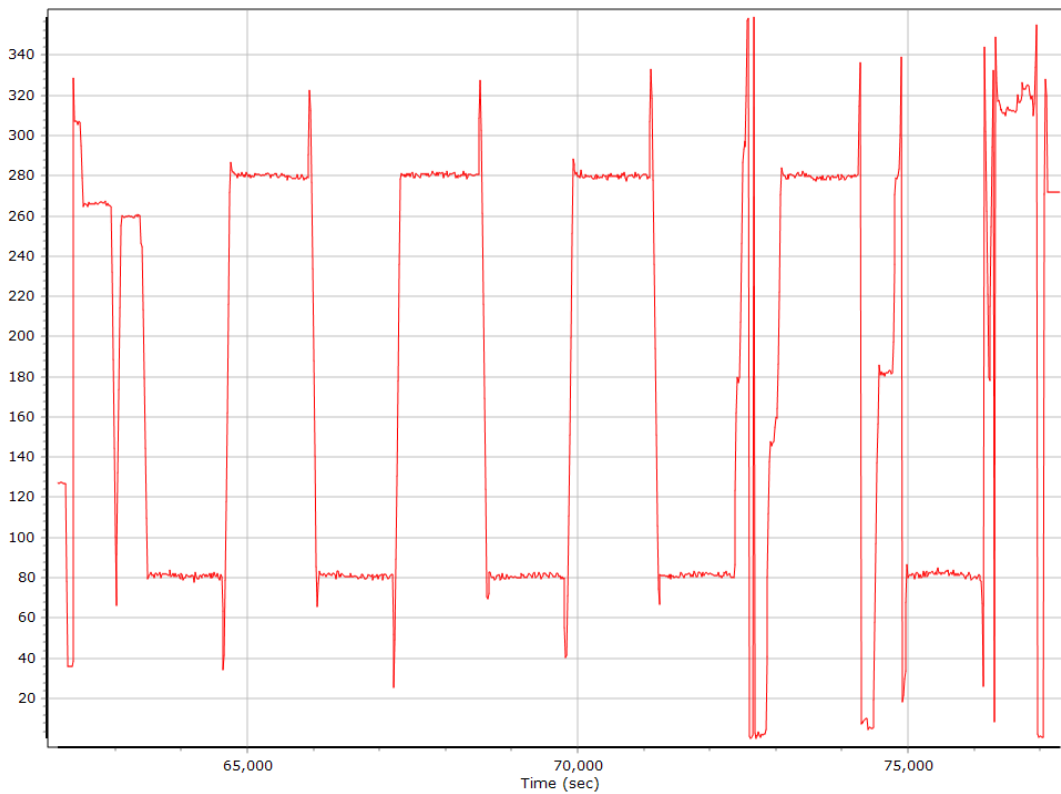
Altitude



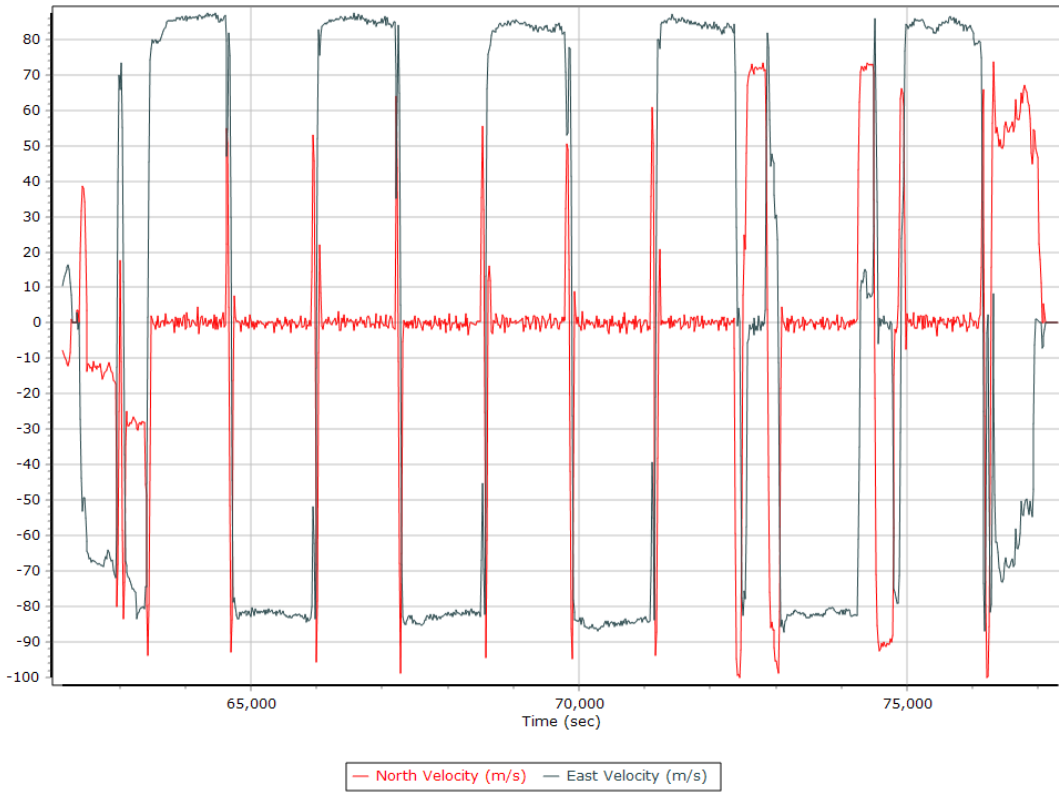
Roll/Pitch



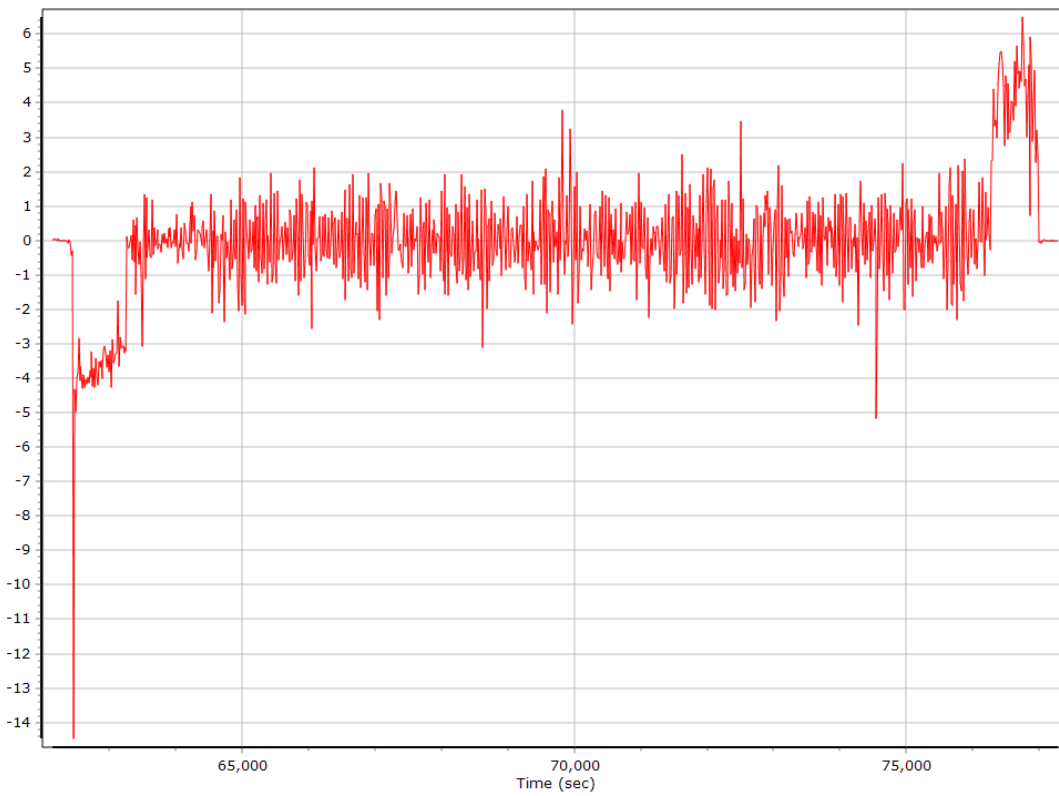
Heading



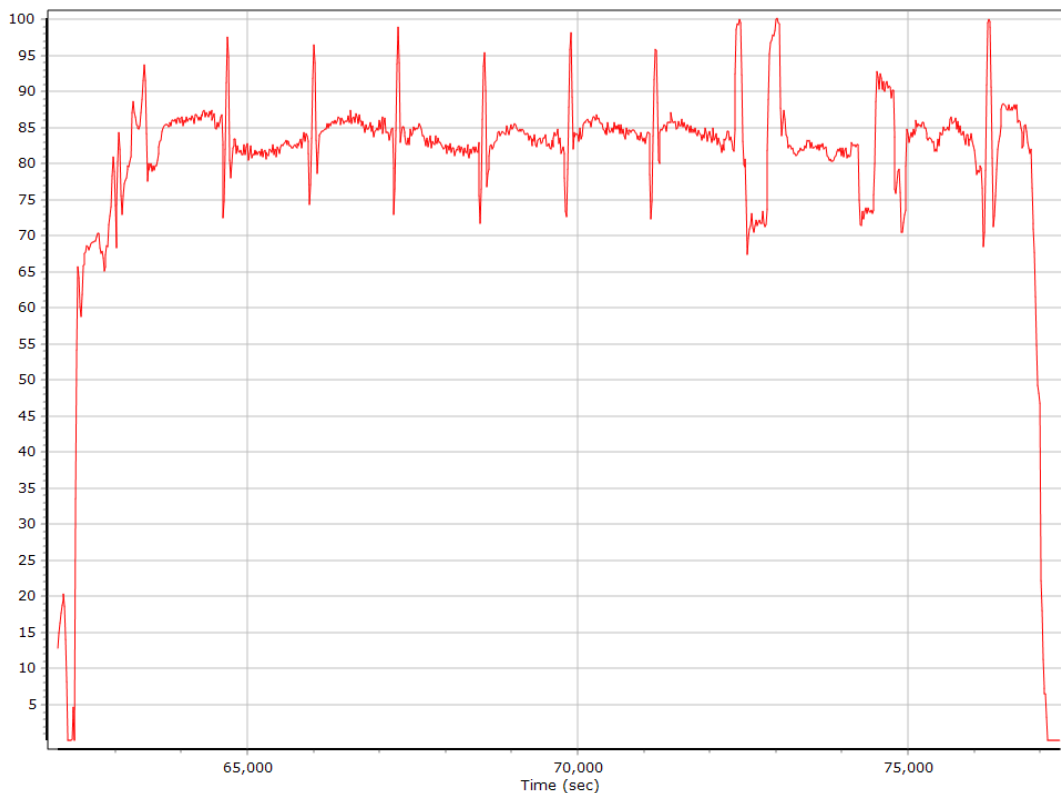
North/East Velocity



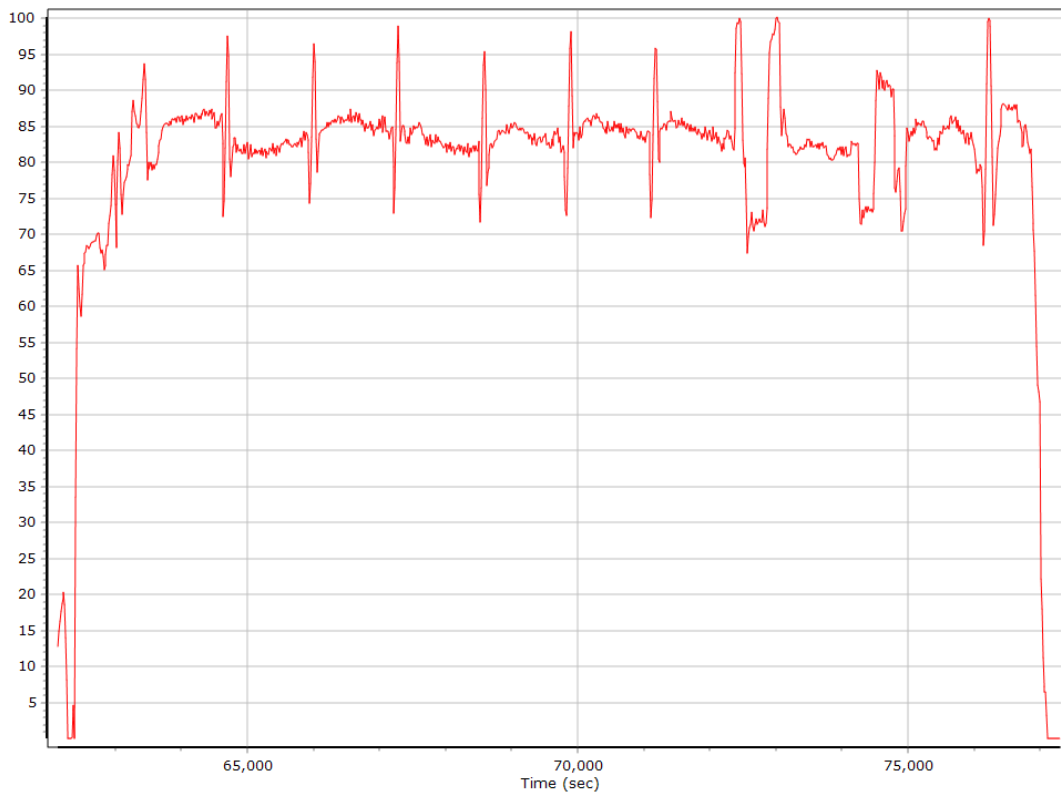
Down Velocity



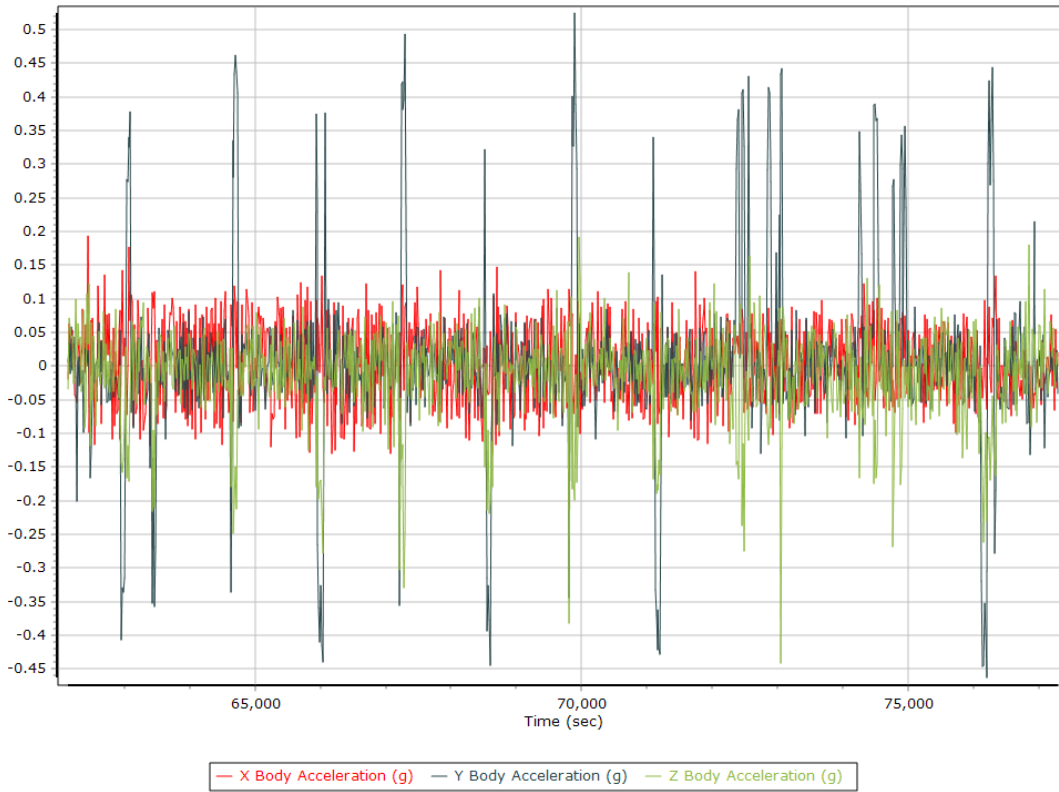
Total Speed



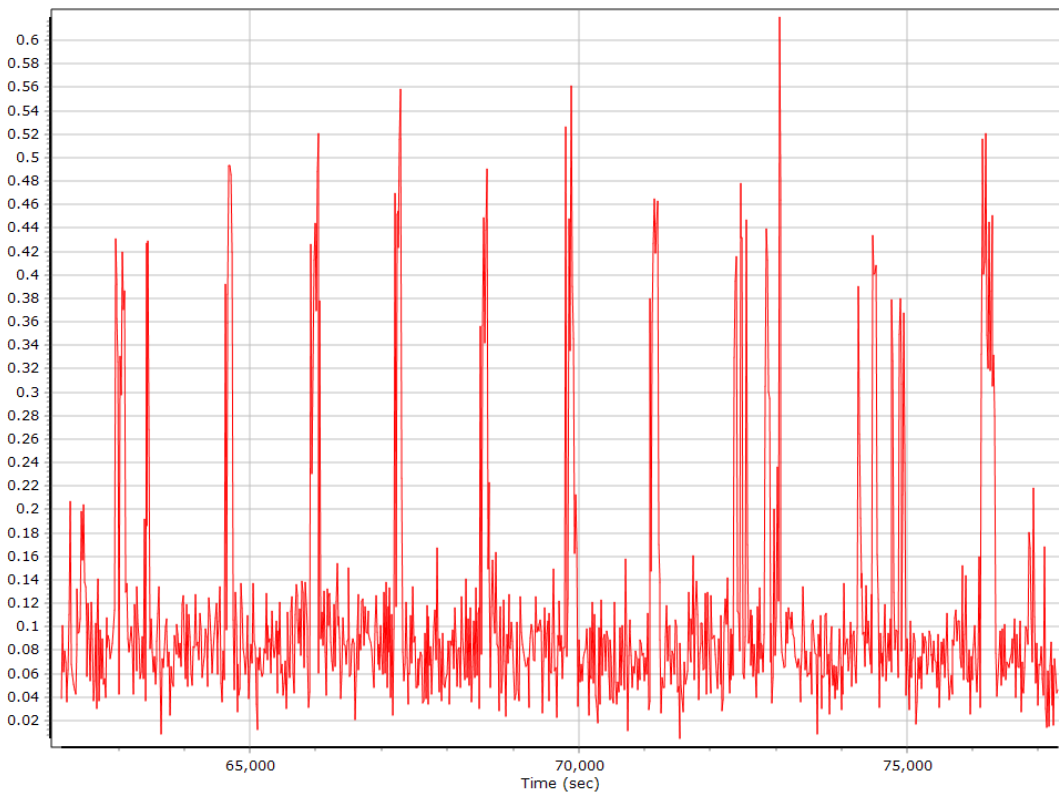
Ground Speed



Body Acceleration



Total Body Acceleration



Body Angular Rate

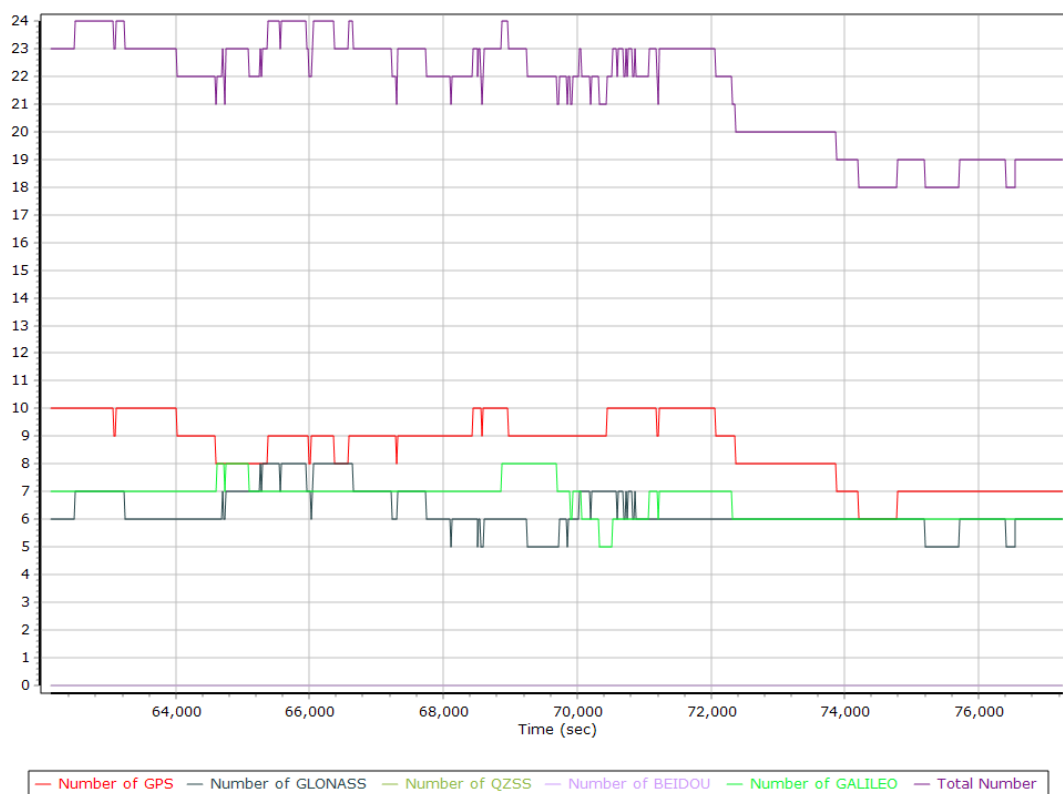


GNSS QC

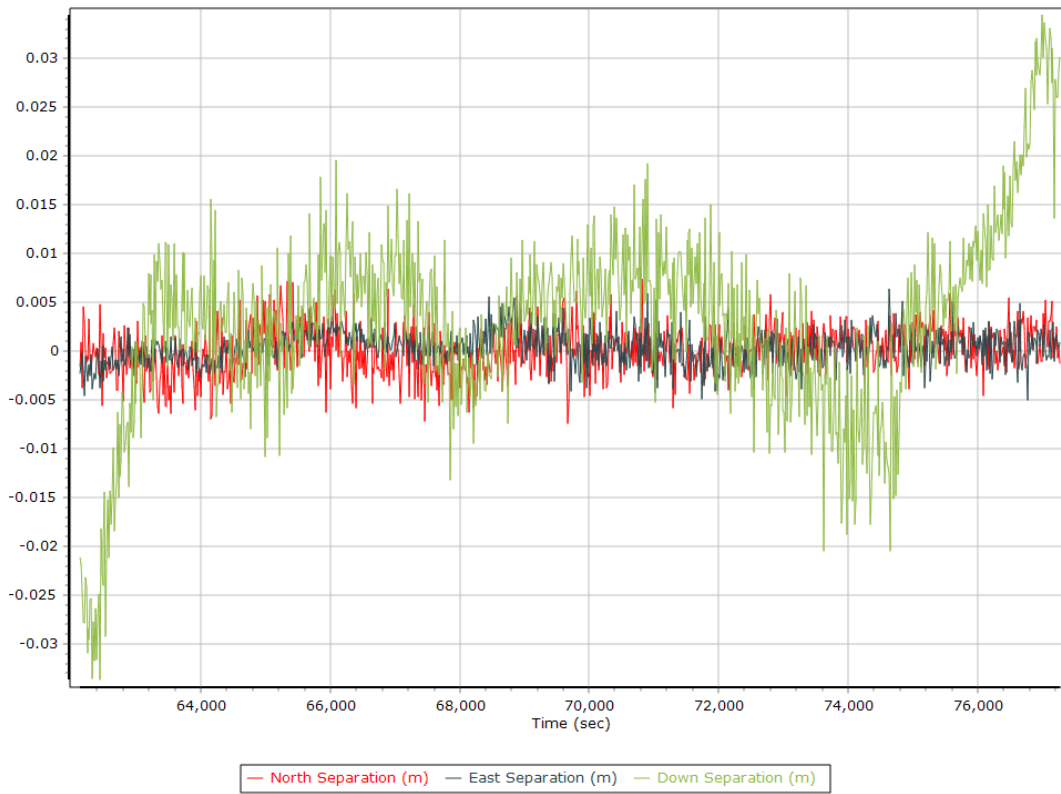
GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	6	10	9
Number of GLONASS SV	4	8	6
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	0	0
Number of GALILEO SV	5	8	7
Total number of SV	18	24	22
PDOP	0.98	1.41	1.14
QC Solution Gaps	0.00	0.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	15525.00	0.00	0.00
Percentage	100.00	0.00	0.00

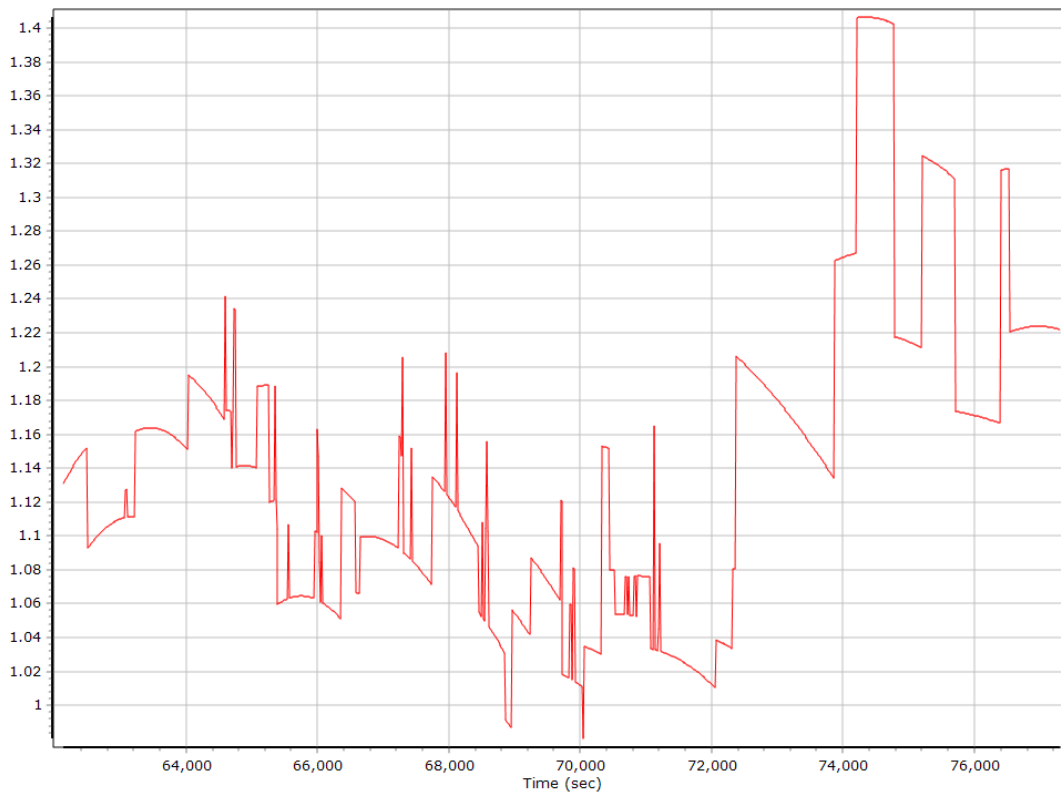
Num SVs in solution



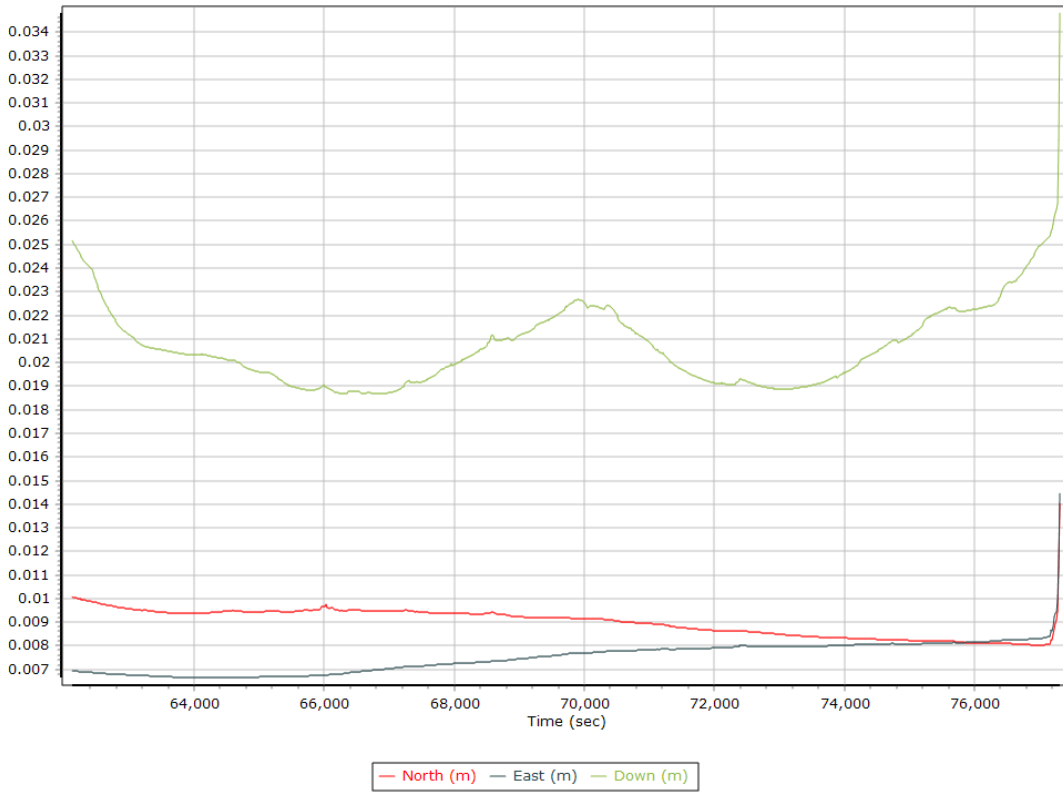
Forward/Reverse Separation



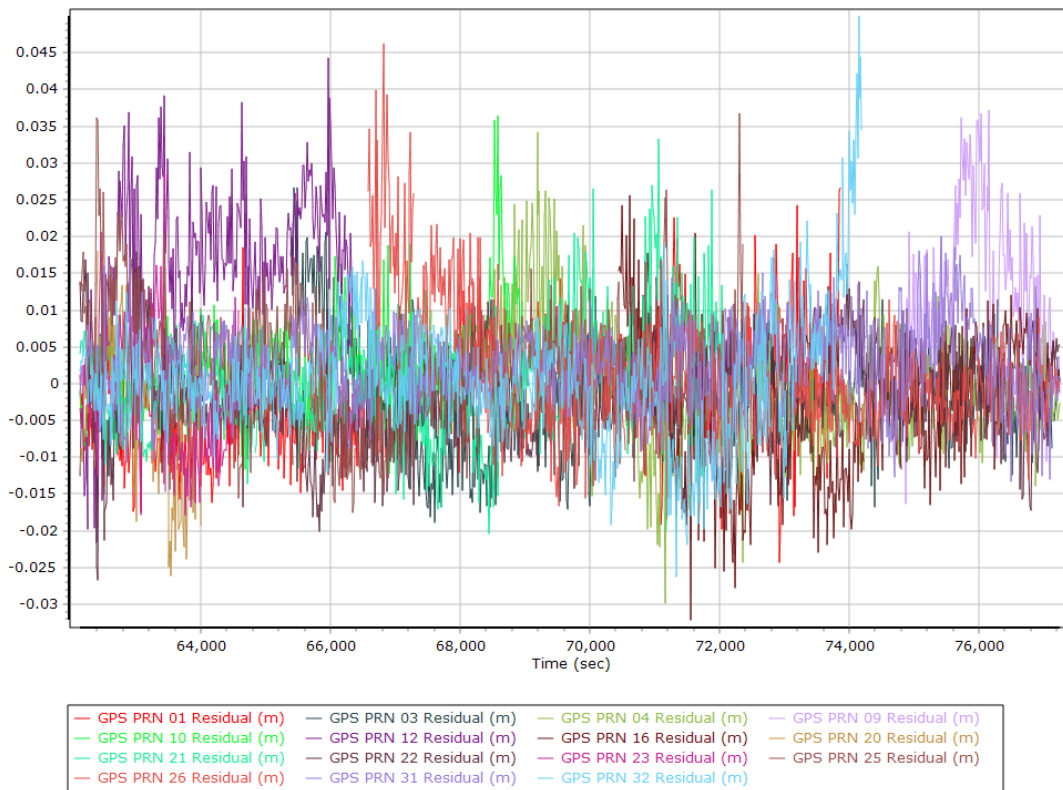
PDOP



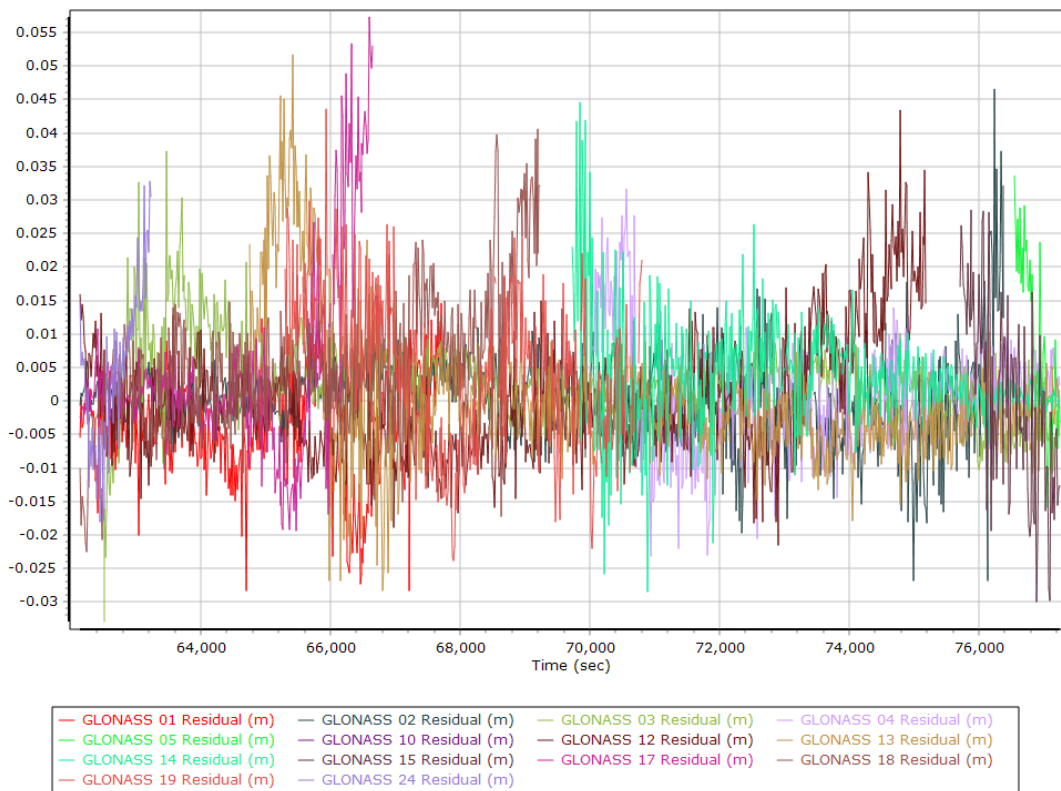
Estimated Position Accuracy



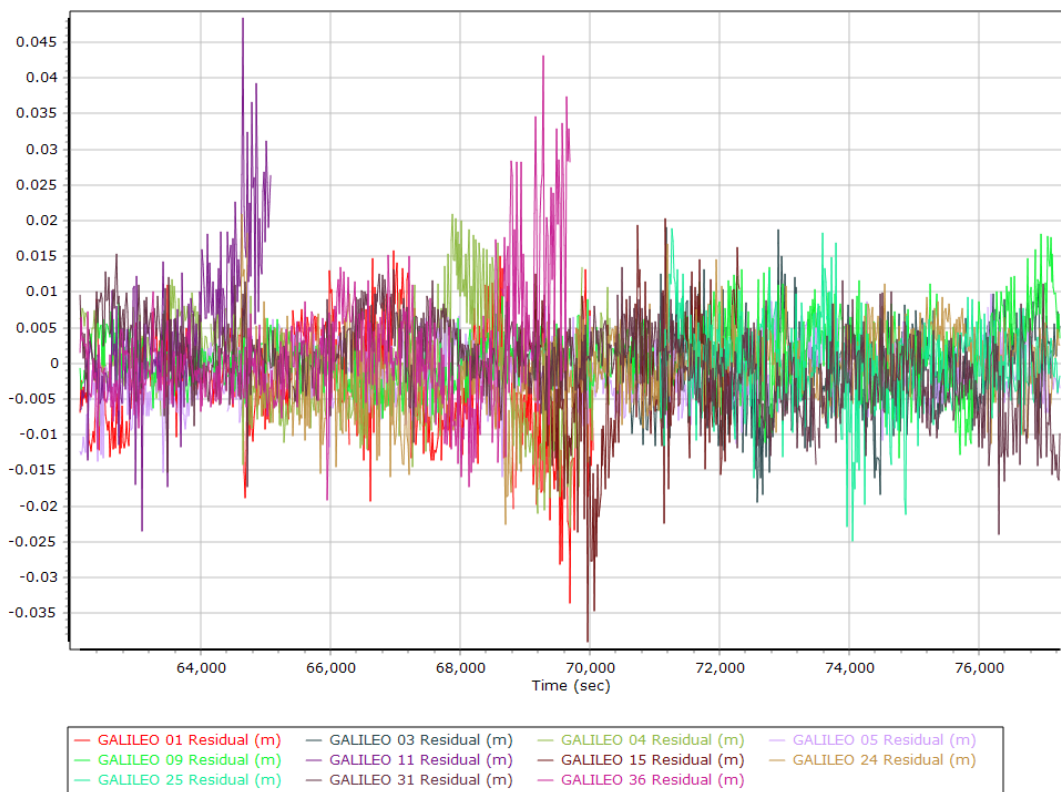
GPS Residuals



GLONASS Residuals



GALILEO Residuals



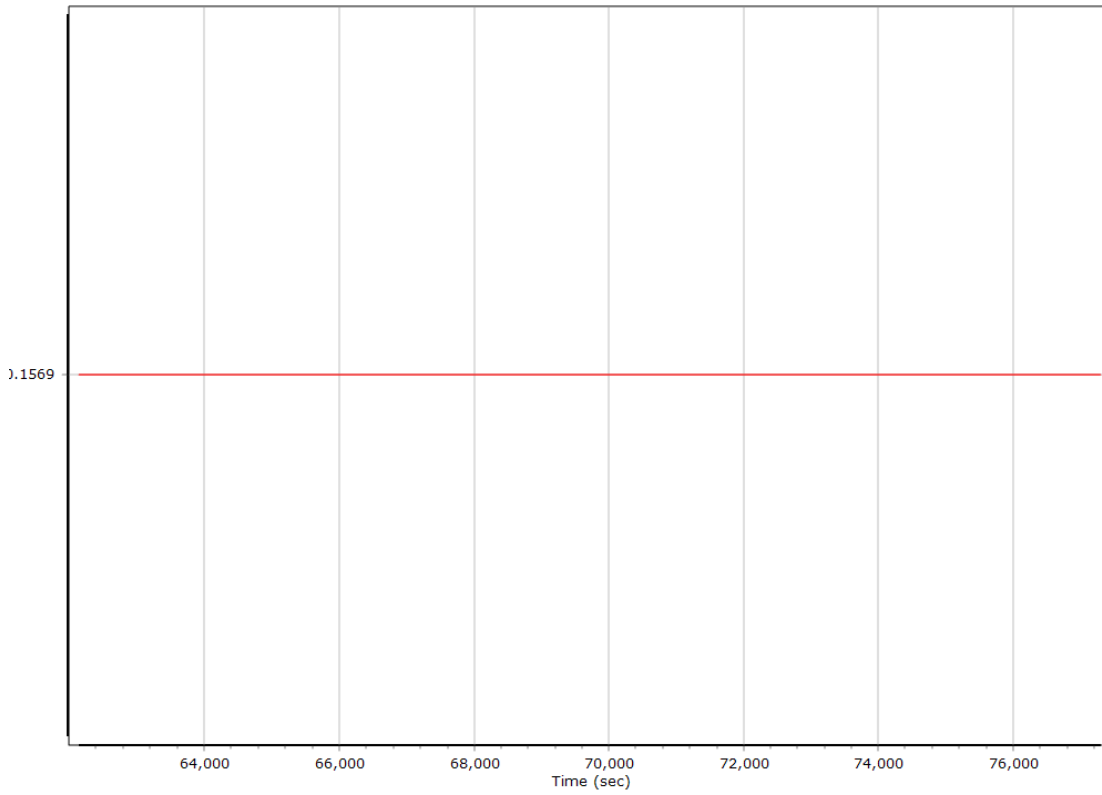
GNSS-Inertial Processor Configuration

Processing mode	IN-Fusion PP-RTX		
Stabilized mount	False		
Processing start time	61732.000 (12/06/2020 17:08:52)		
Processing end time	77304.000 (12/06/2020 21:28:24)		
Initial attitude source	Real-Time VNAV/RNAV Attitude		
IMU Sensor Context	Processing with Onboard IMU		
Reference to IMU lever arm (m)	0.000	0.000	0.000
Reference to IMU mounting angles (deg)	0.000	0.000	180.000
Reference to Primary GNSS lever arm (m)	0.157	-0.150	-1.090
Reference to Primary GNSS lever arm std dev (m)	0.030	0.030	0.030
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

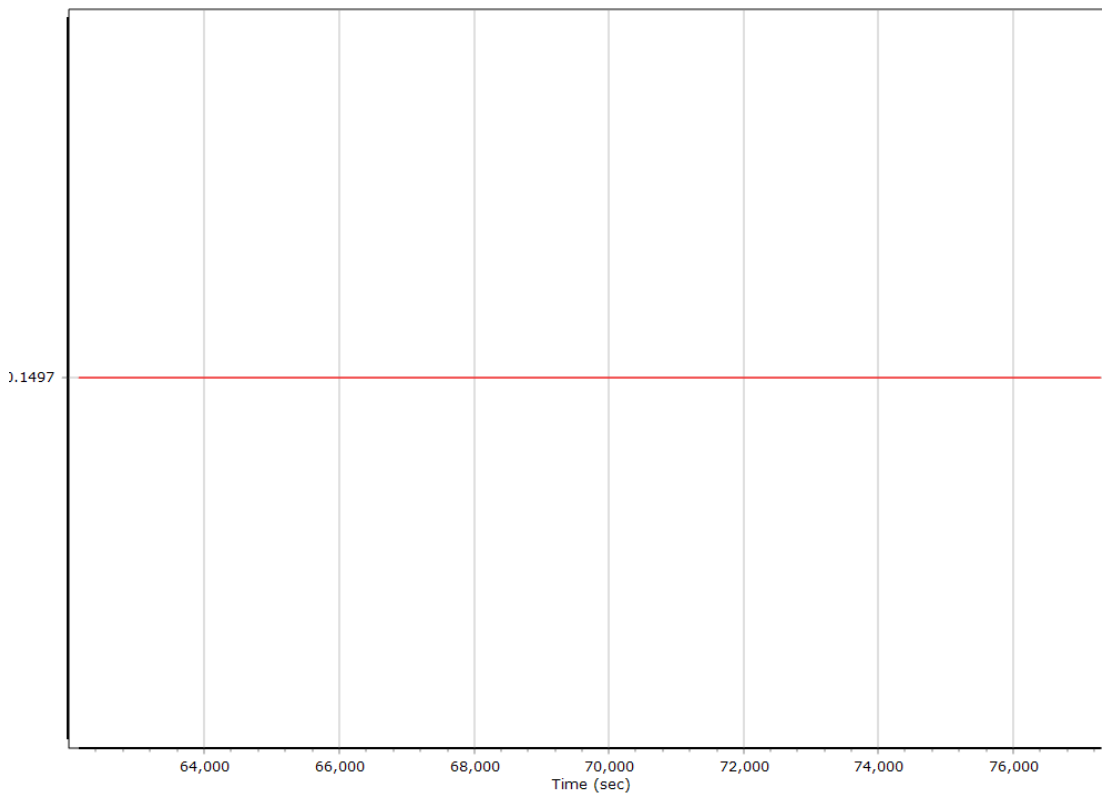
Calibrated Installation Parameters

Reference-Primary GNSS Lever Arm (m)

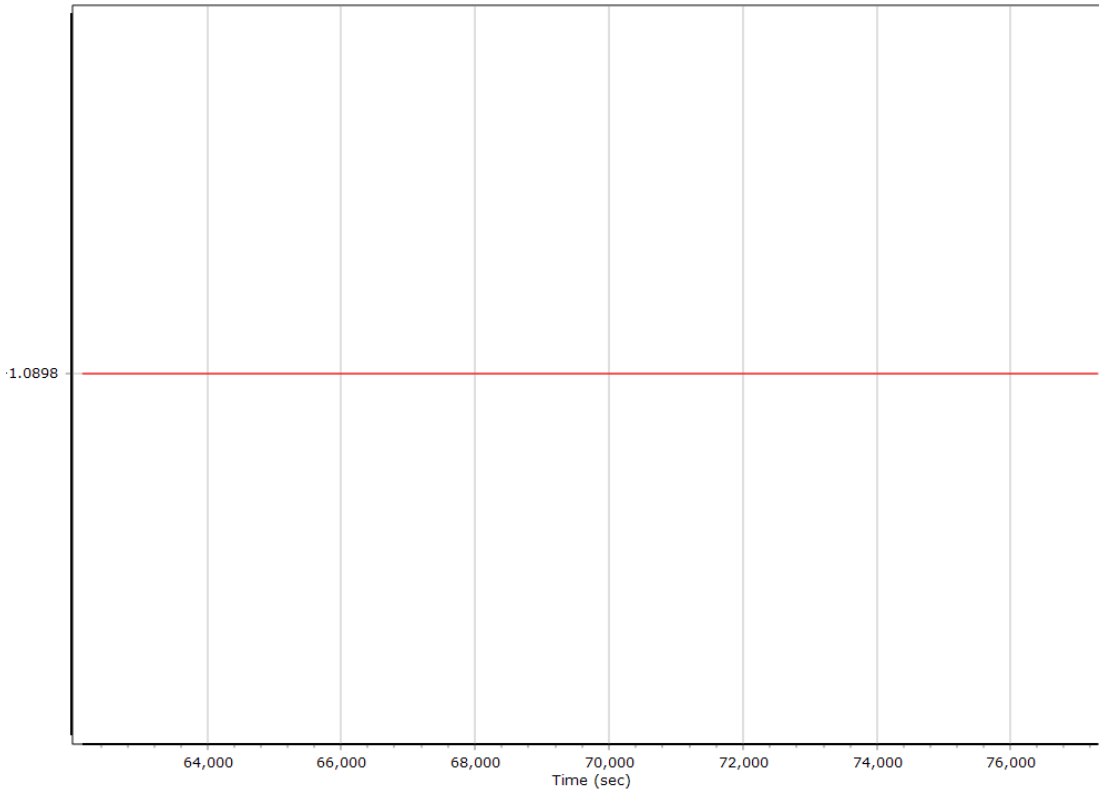
X Reference-Primary GNSS Lever Arm (m)



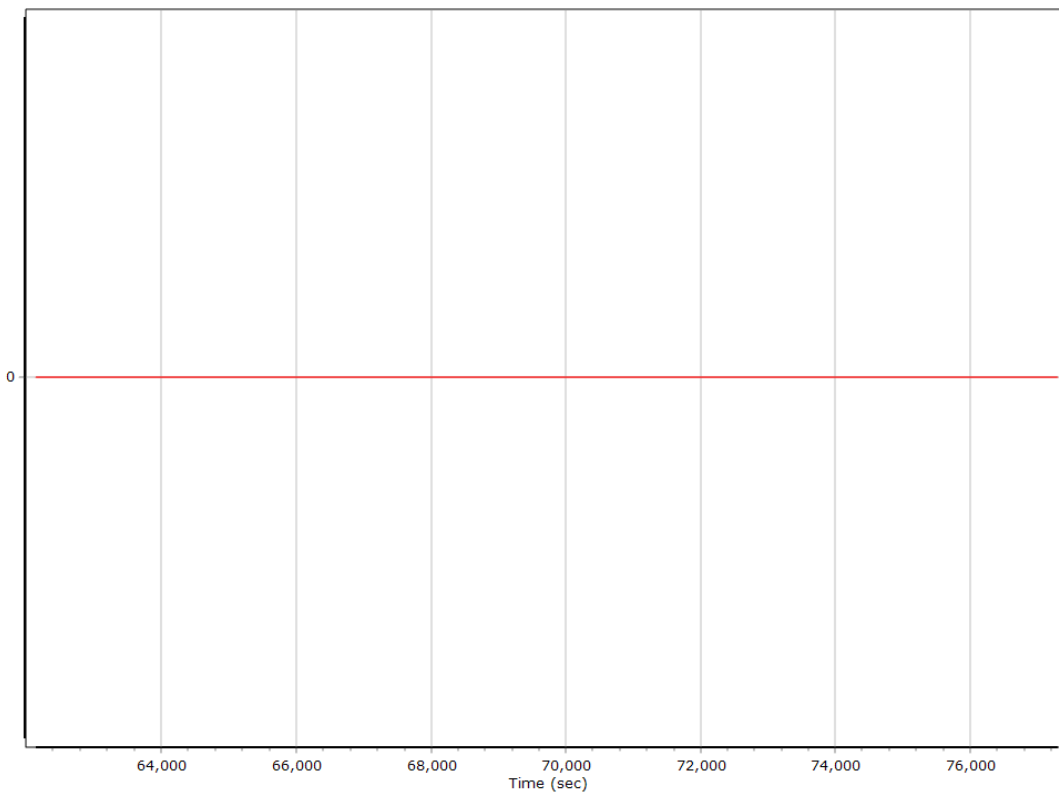
Y Reference-Primary GNSS Lever Arm (m)



Z Reference-Primary GNSS Lever Arm (m)



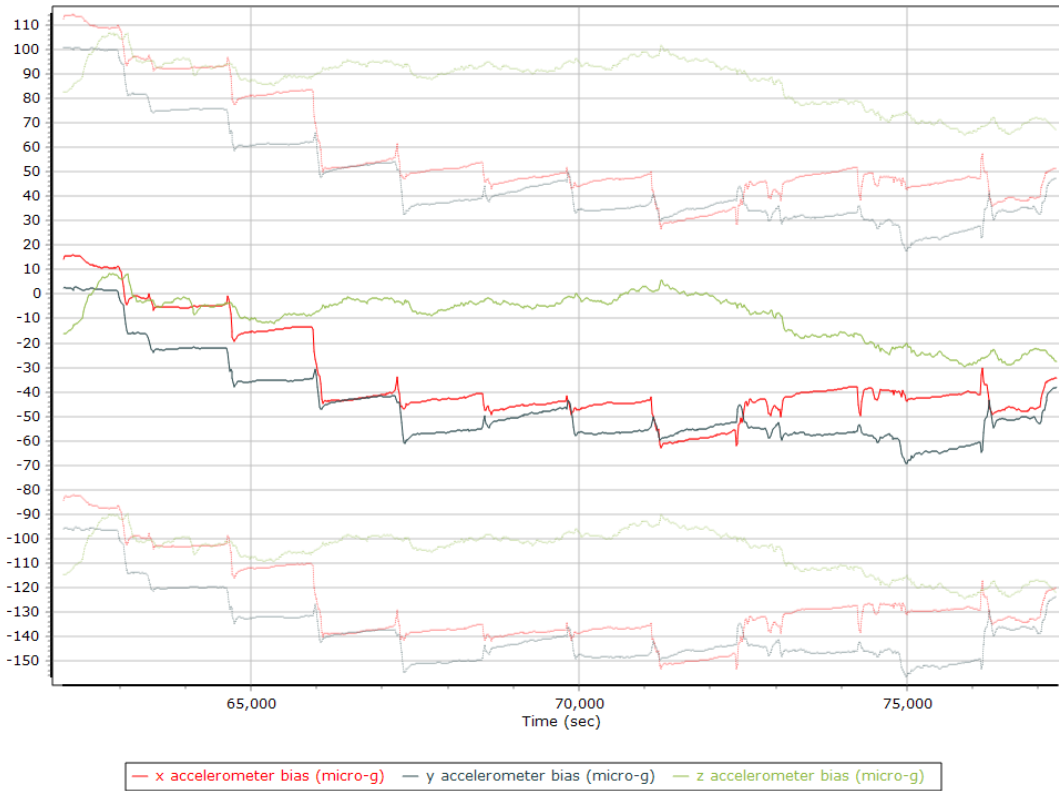
Reference-Primary GNSS Lever Arm Figure of Merit



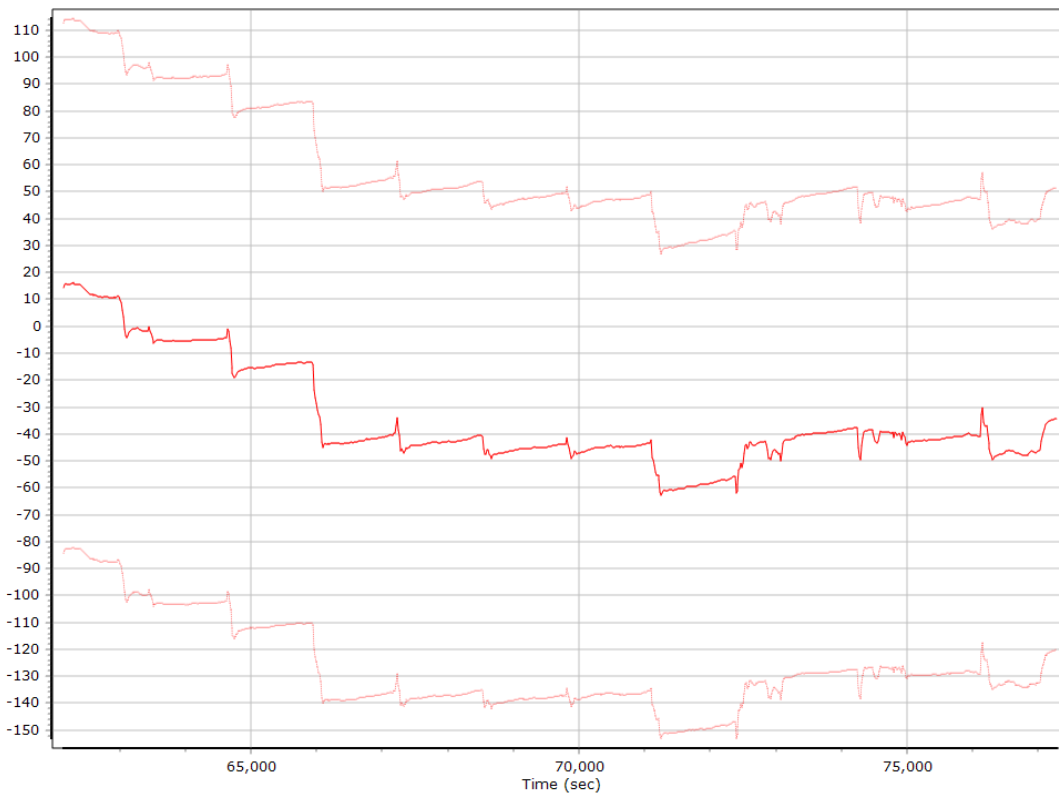
IN-Fusion QC

Forward Processed Estimated Errors, Reference Frame

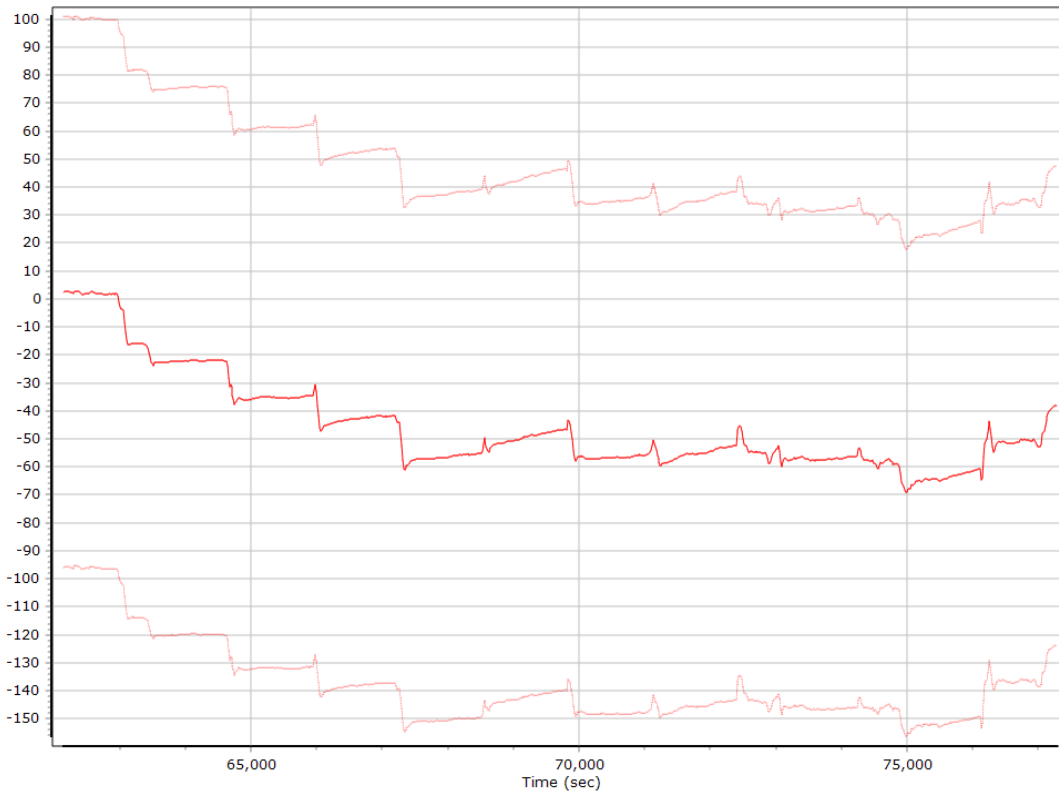
Accelerometer Bias (micro-g)



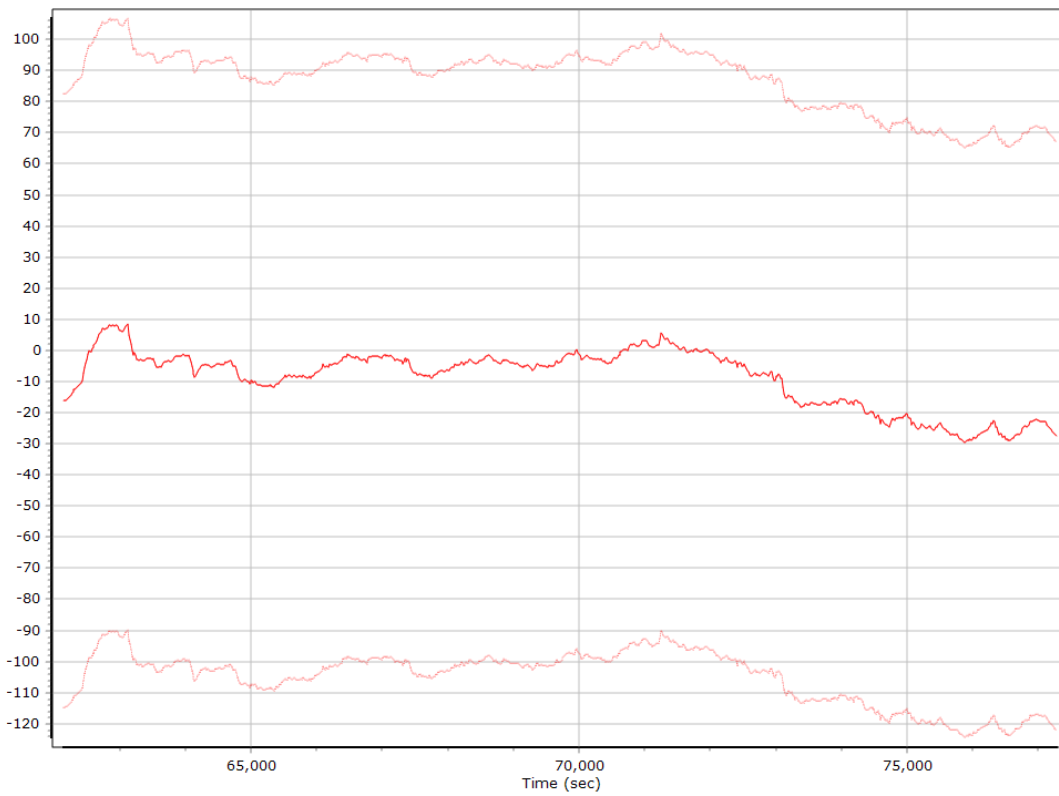
X Accelerometer Bias (micro-g)



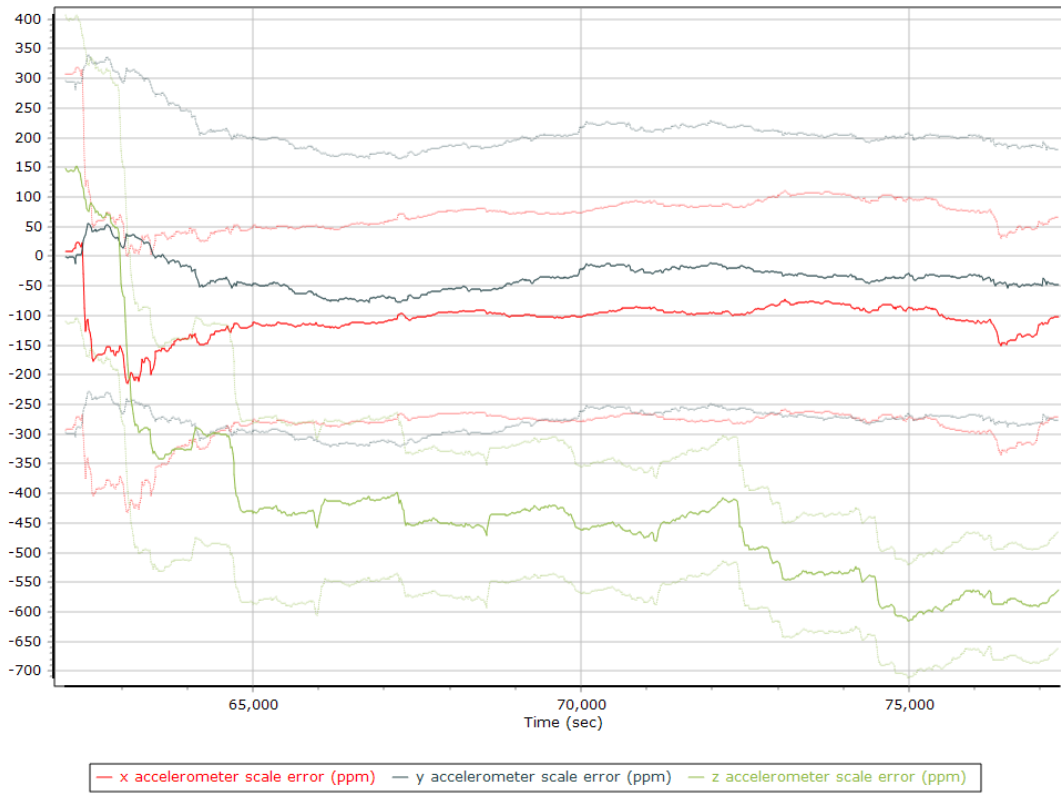
Y Accelerometer Bias (micro-g)



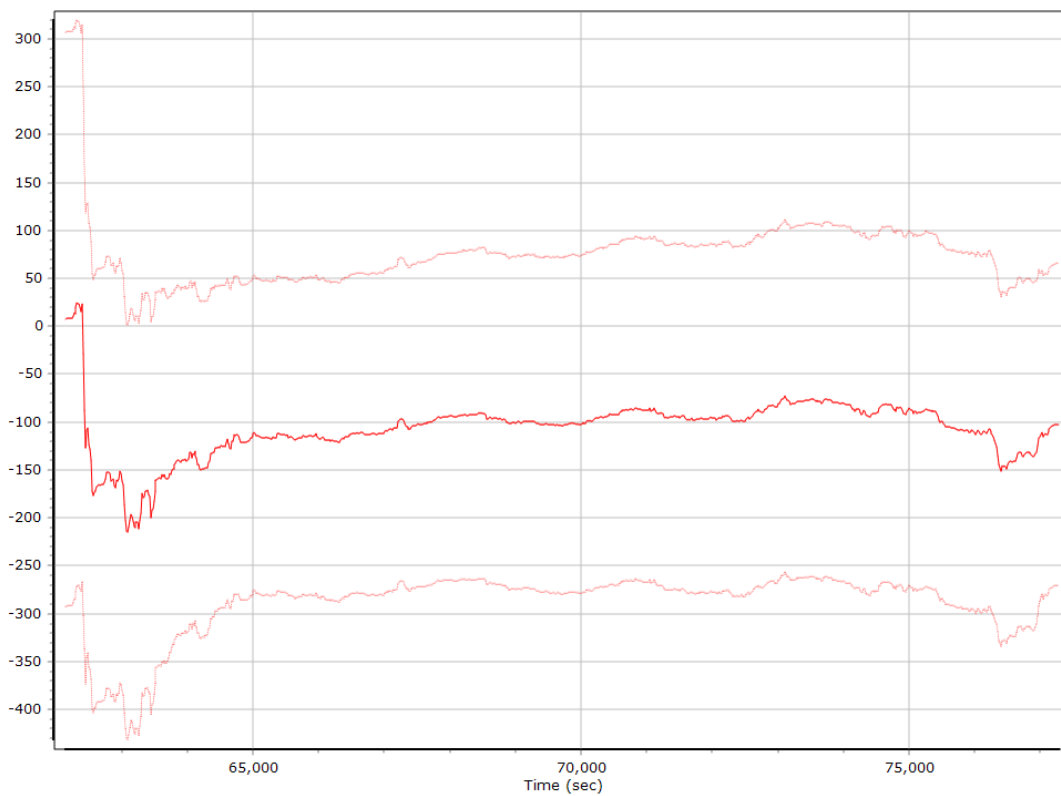
Z Accelerometer Bias (micro-g)



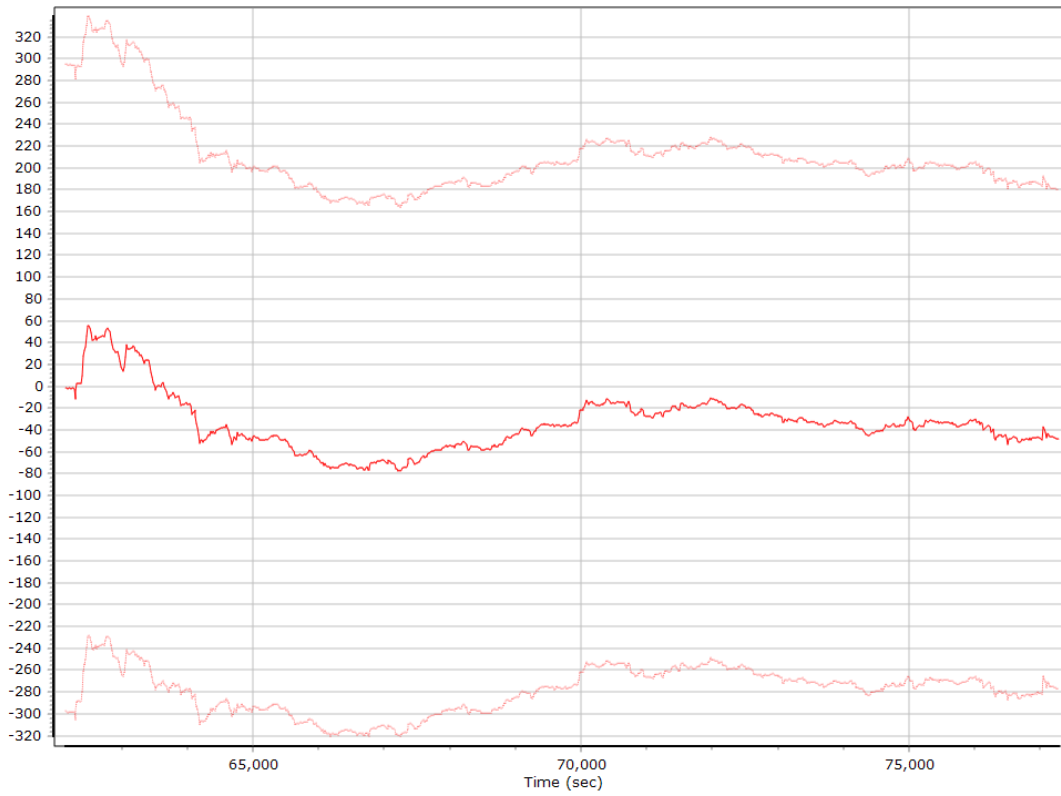
Accelerometer Scale Error (ppm)



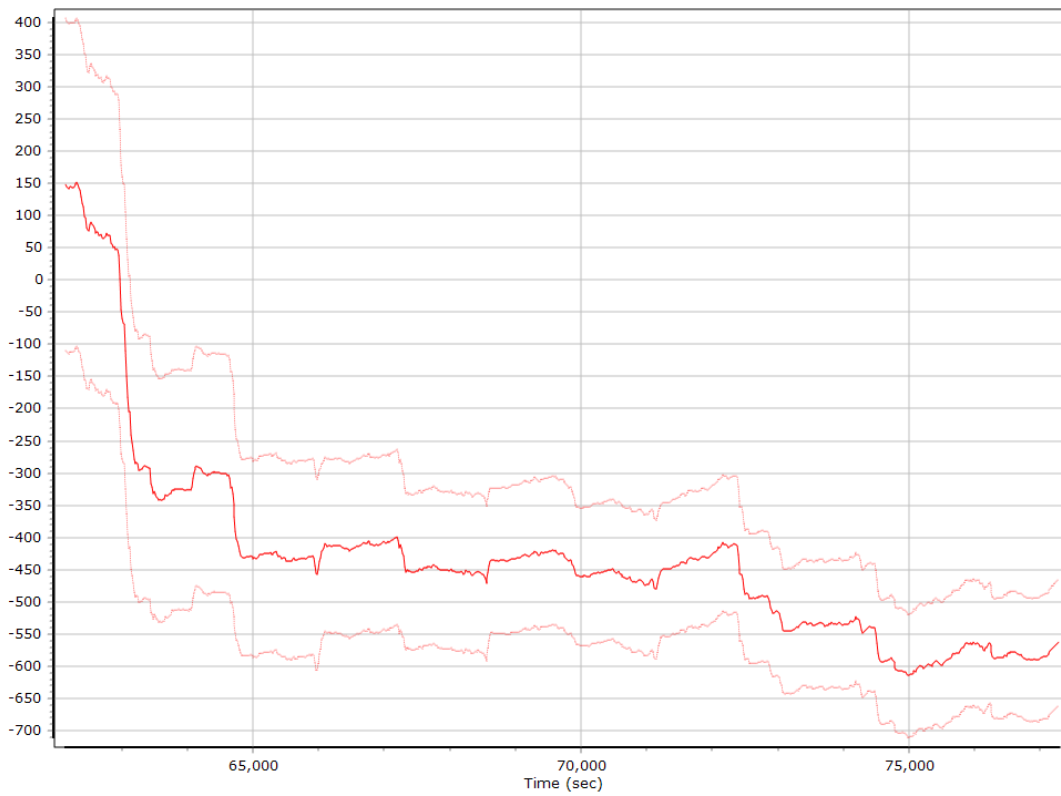
X Accelerometer Scale Error (ppm)



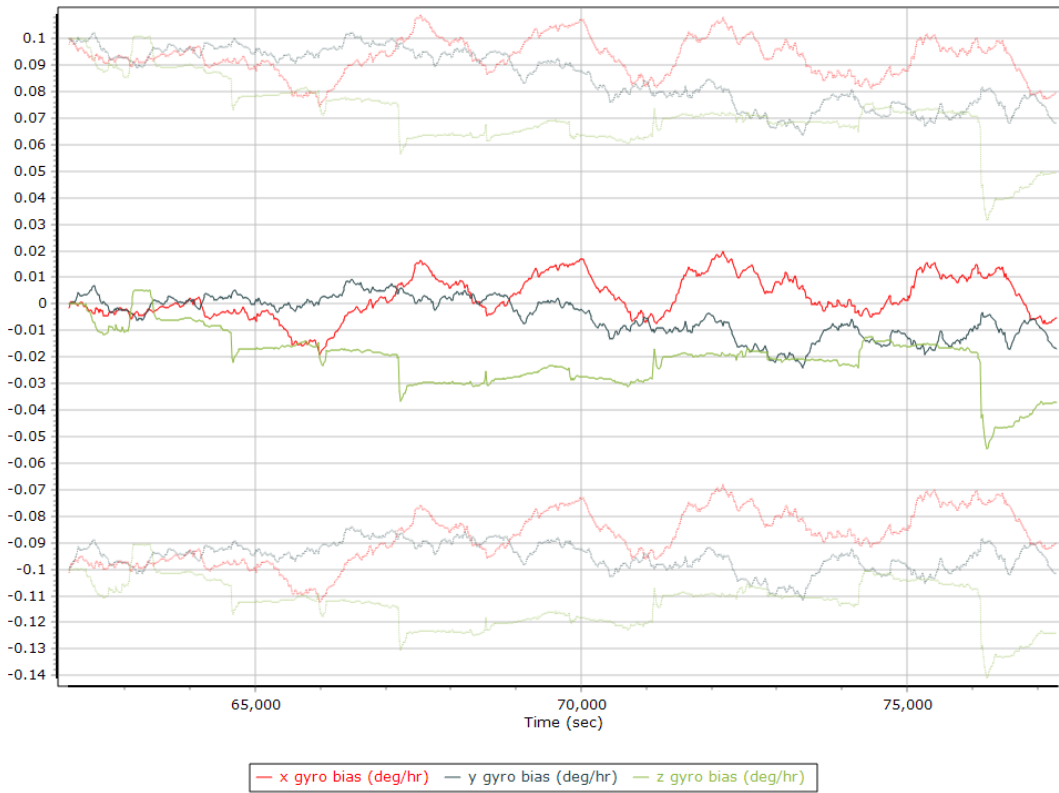
Y Accelerometer Scale Error (ppm)



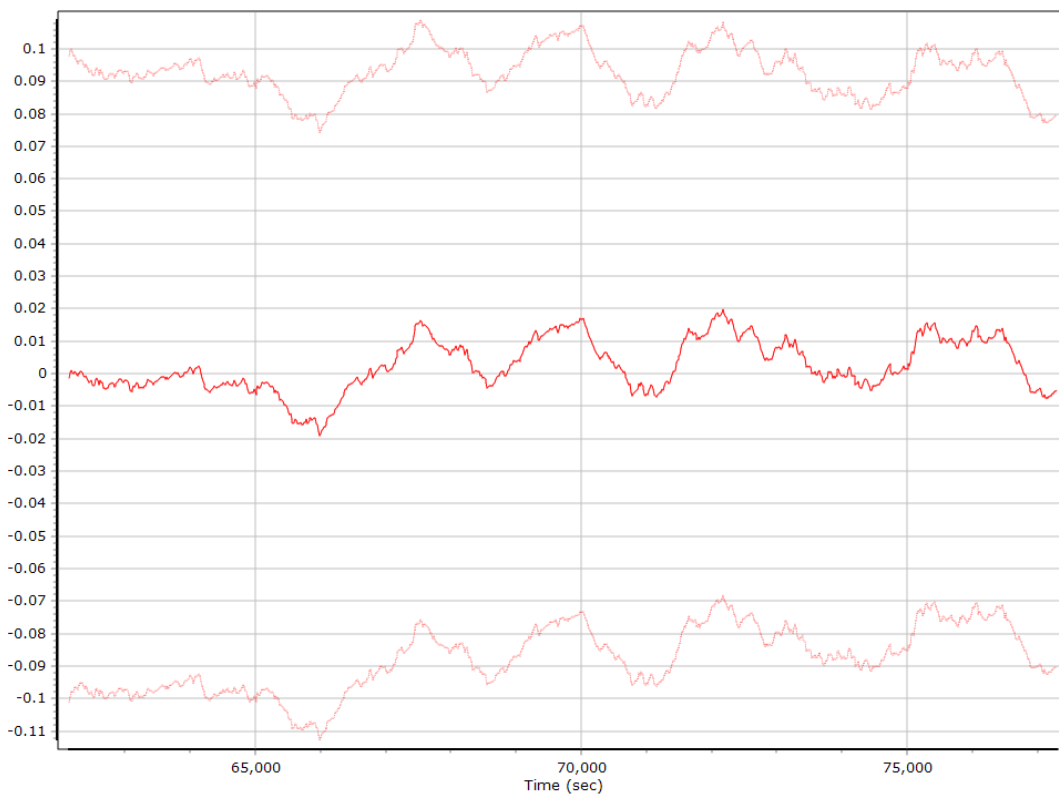
Z Accelerometer Scale Error (ppm)



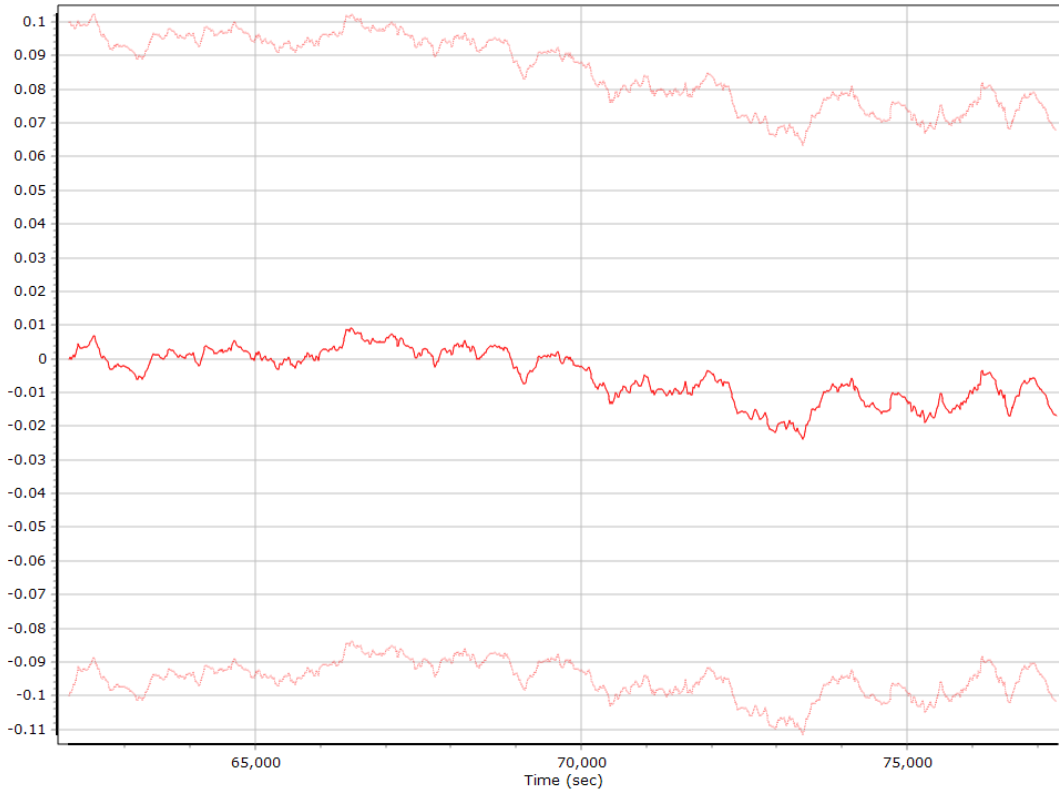
Gyro Bias (deg/h)



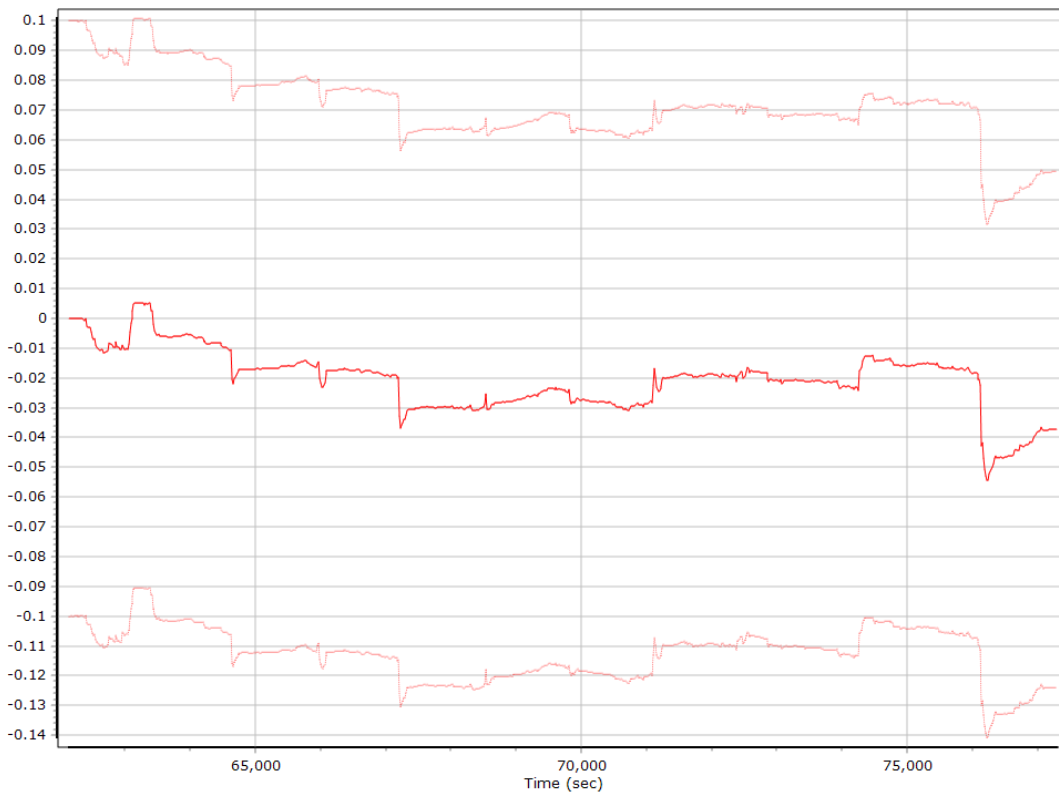
X Gyro Bias (deg/h)



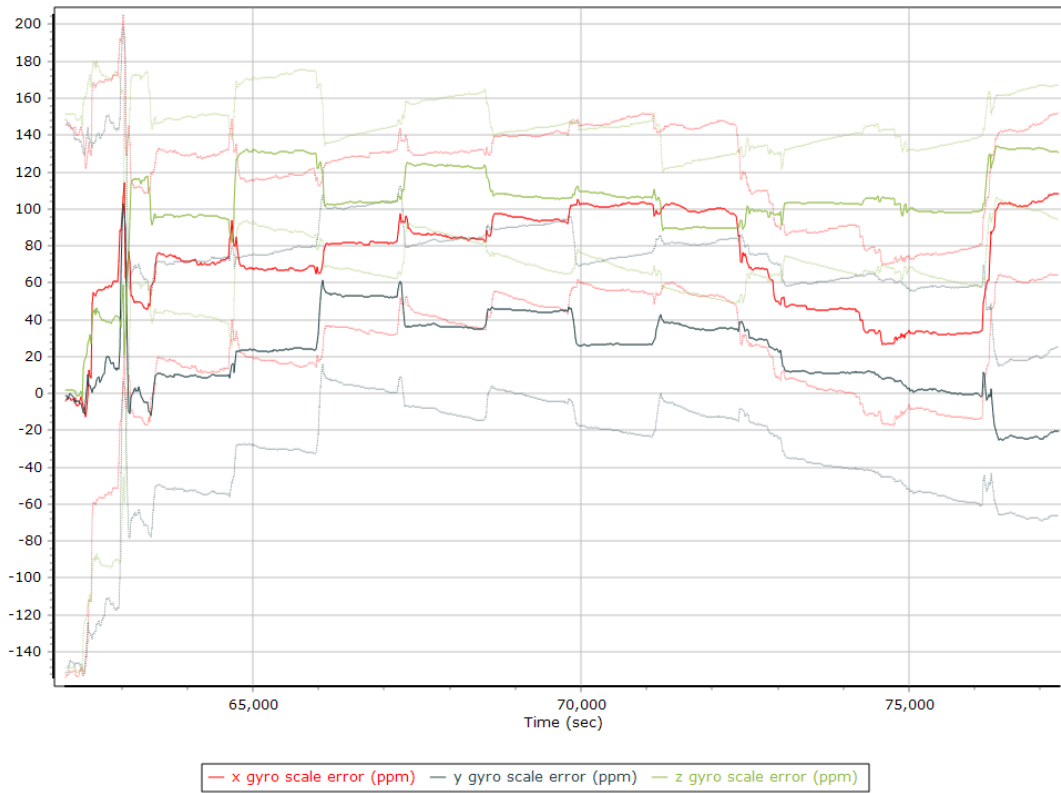
Y Gyro Bias (deg/h)



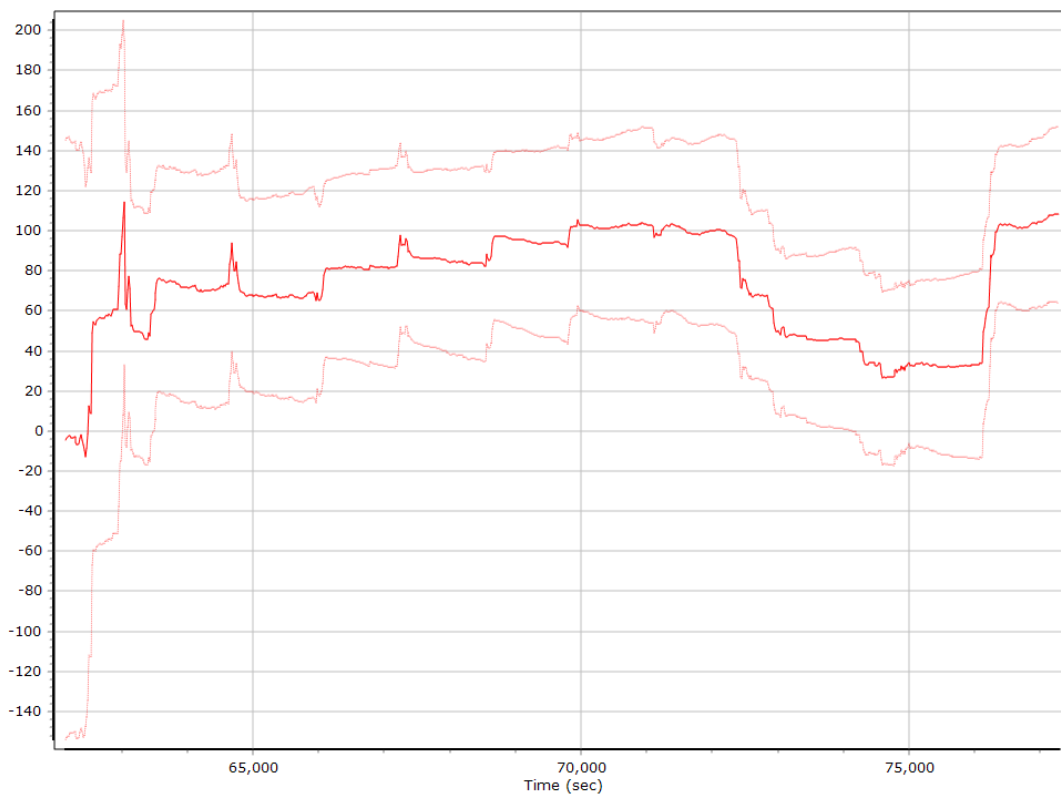
Z Gyro Bias (deg/h)



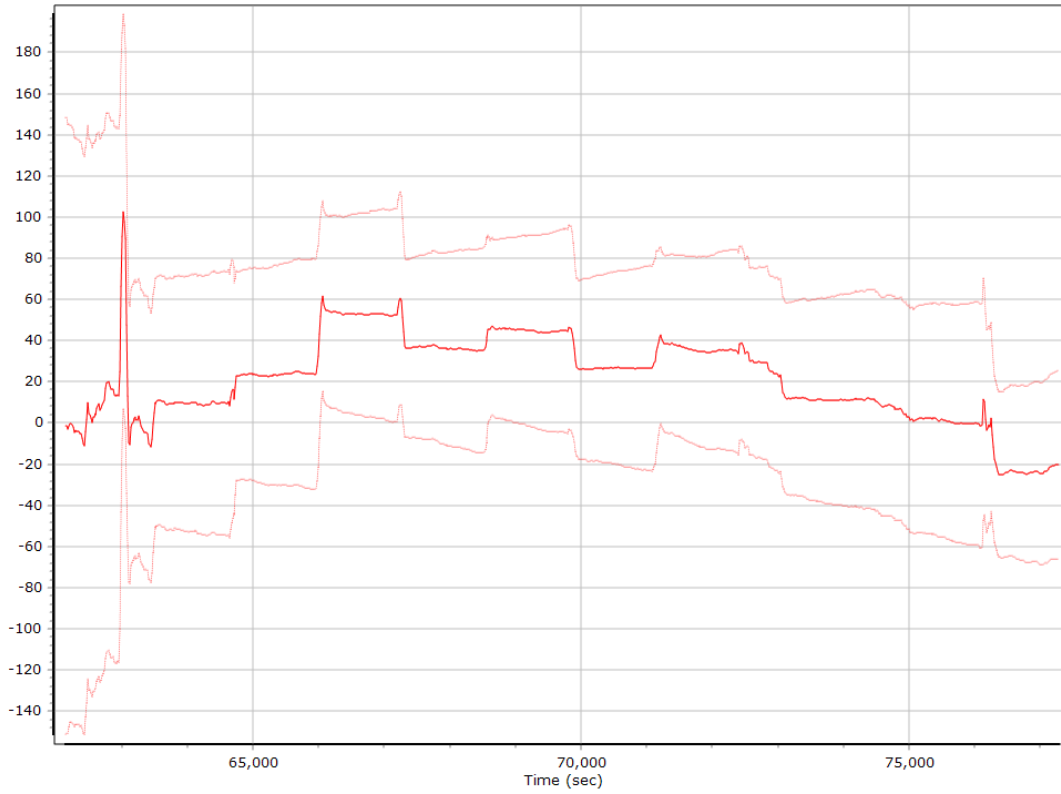
Gyro Scale Error (ppm)



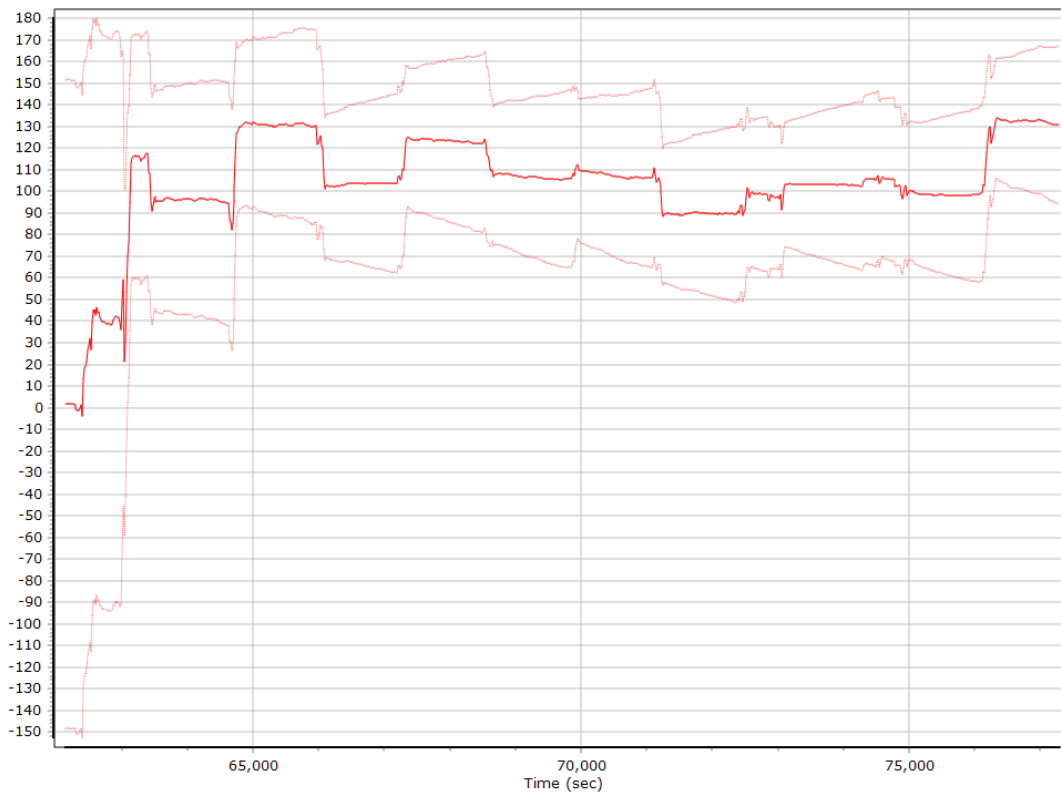
X Gyro Scale Error (ppm)



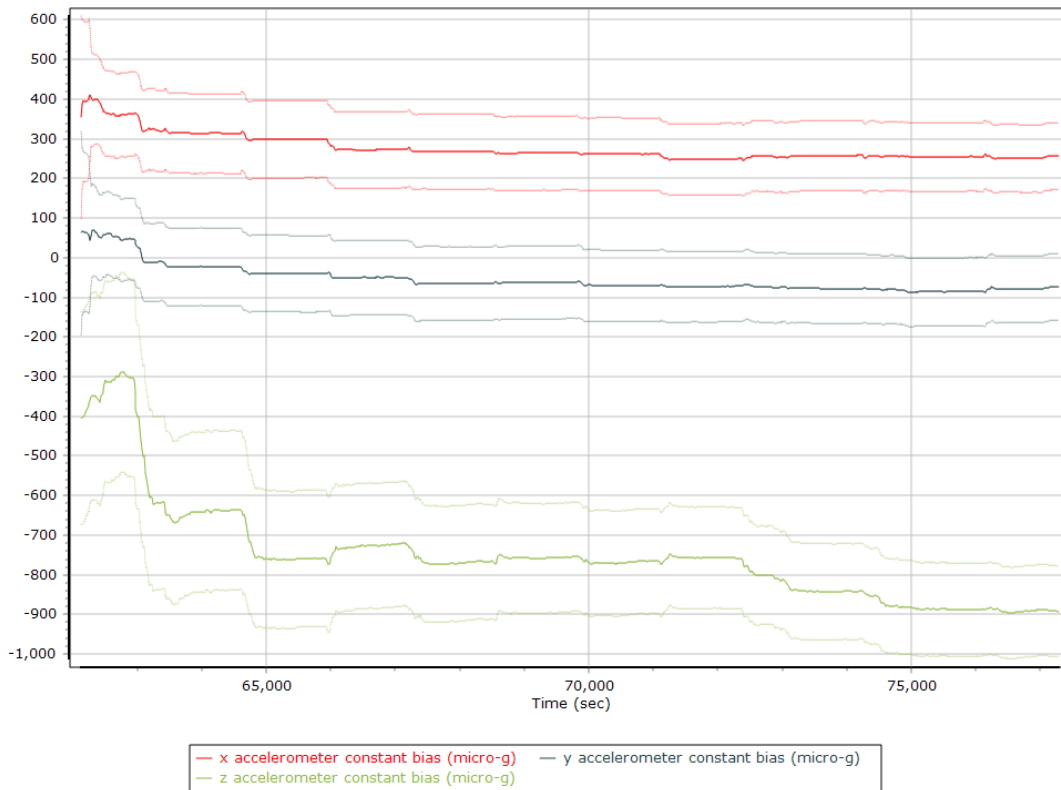
Y Gyro Scale Error (ppm)



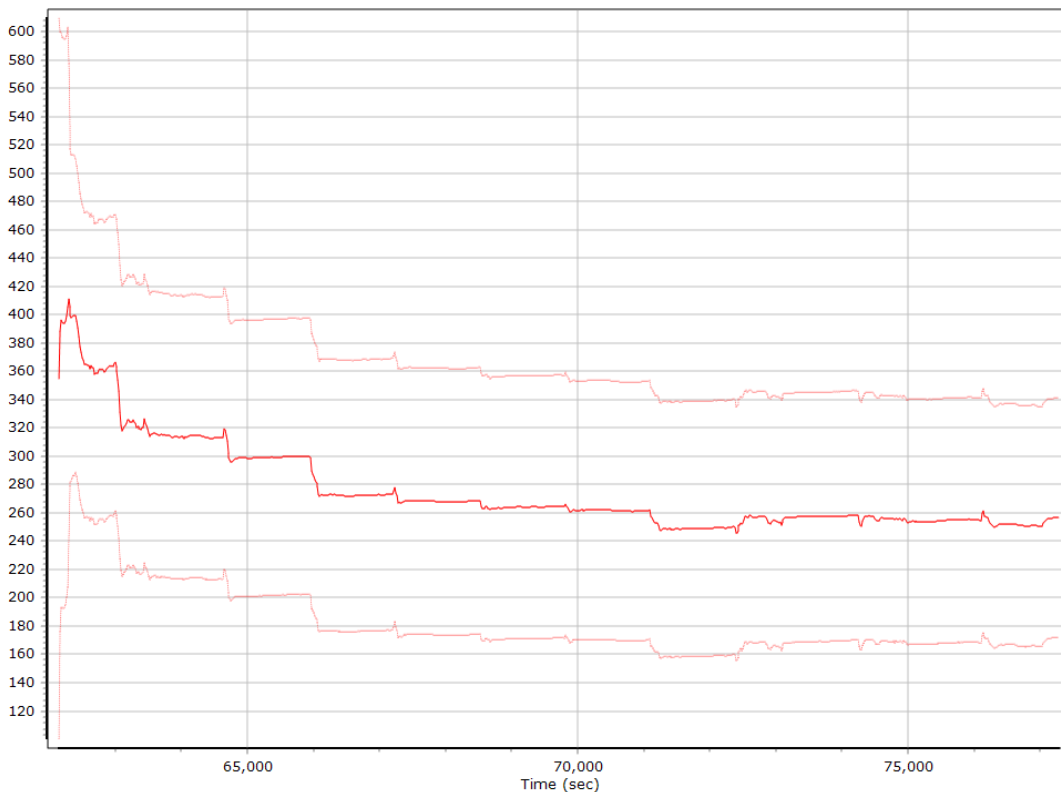
Z Gyro Scale Error (ppm)



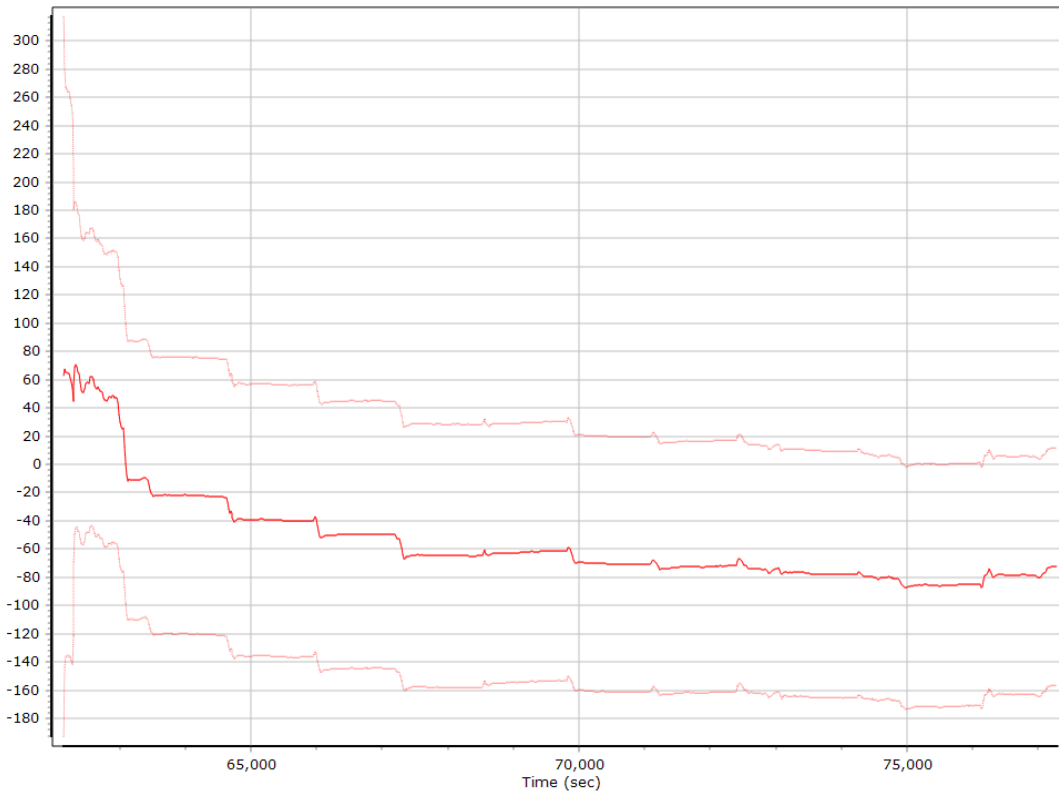
Forward Processed Estimated Constant Errors, Reference Frame Accelerometer Bias (micro-g)



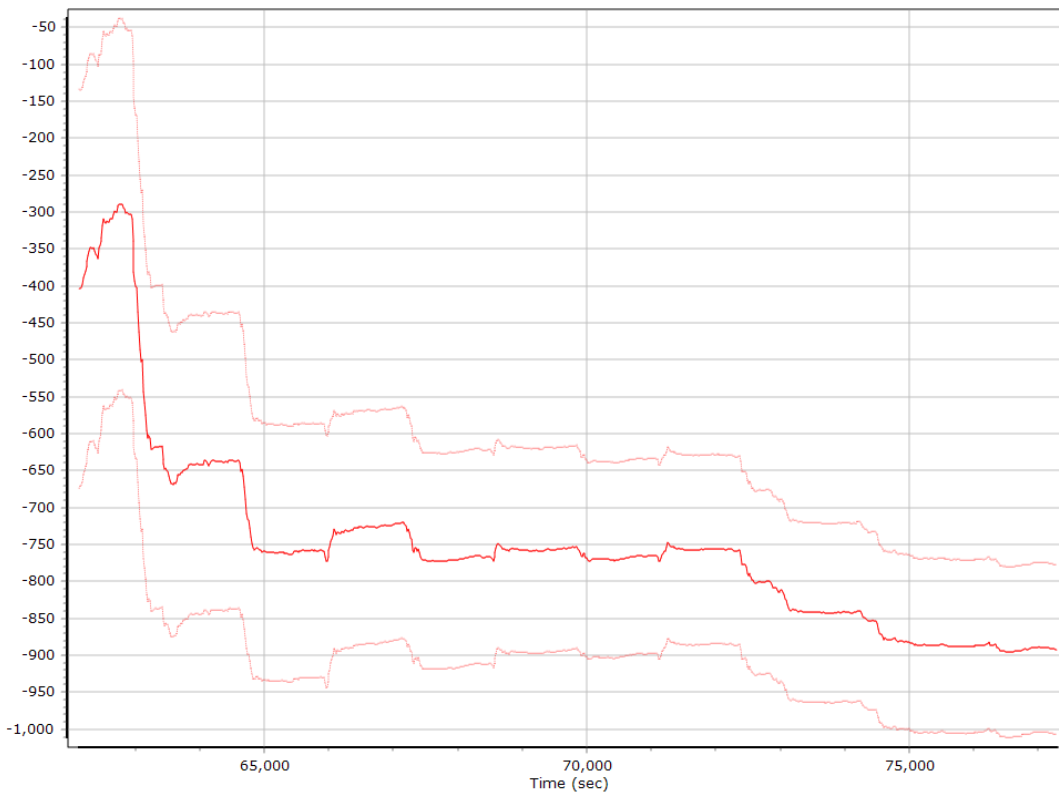
X Accelerometer Bias (micro-g)



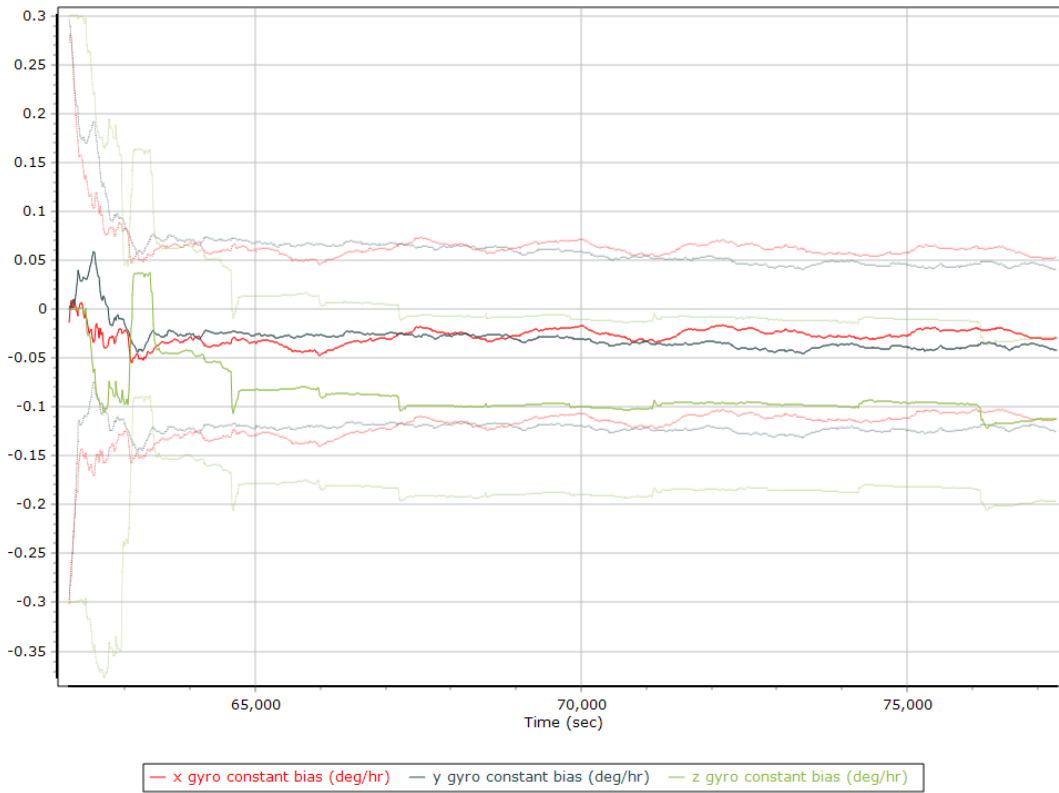
Y Accelerometer Bias (micro-g)



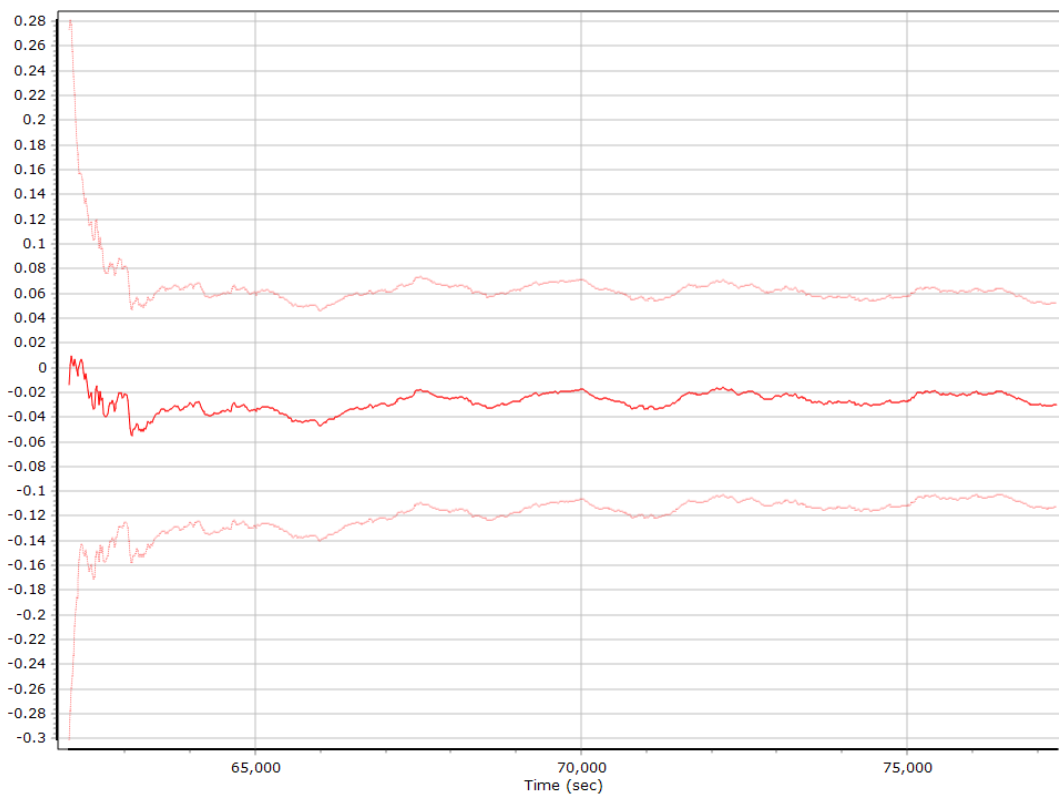
Z Accelerometer Bias (micro-g)



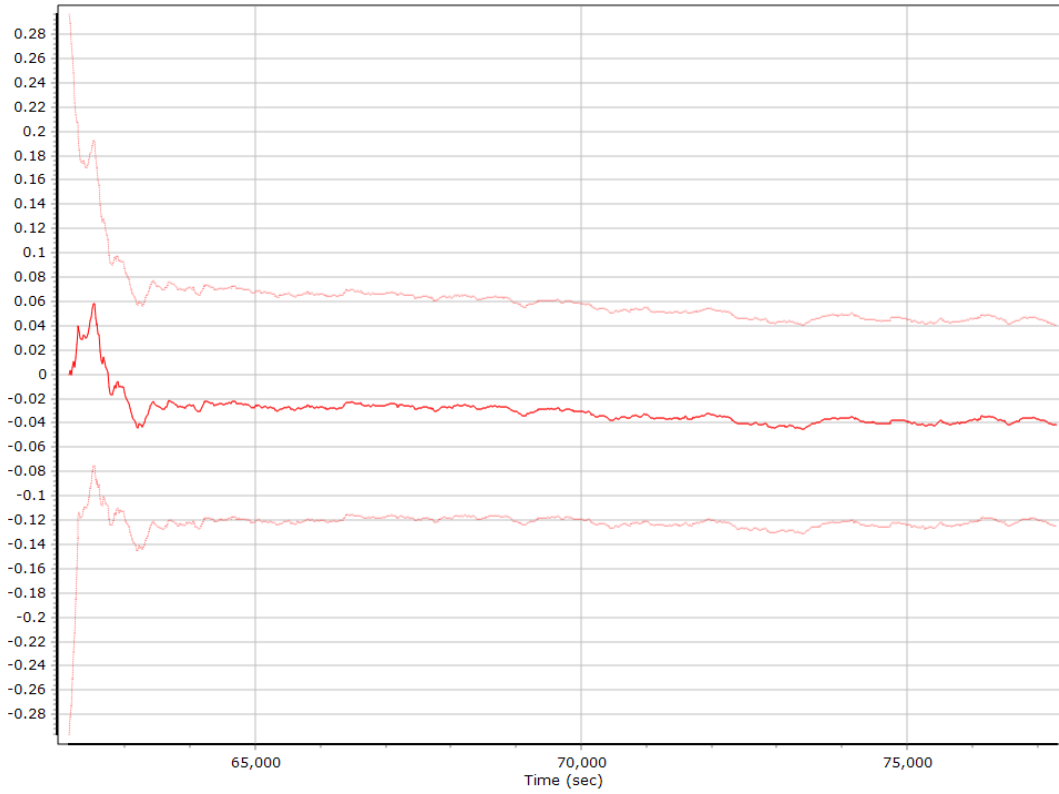
Gyro Bias (deg/h)



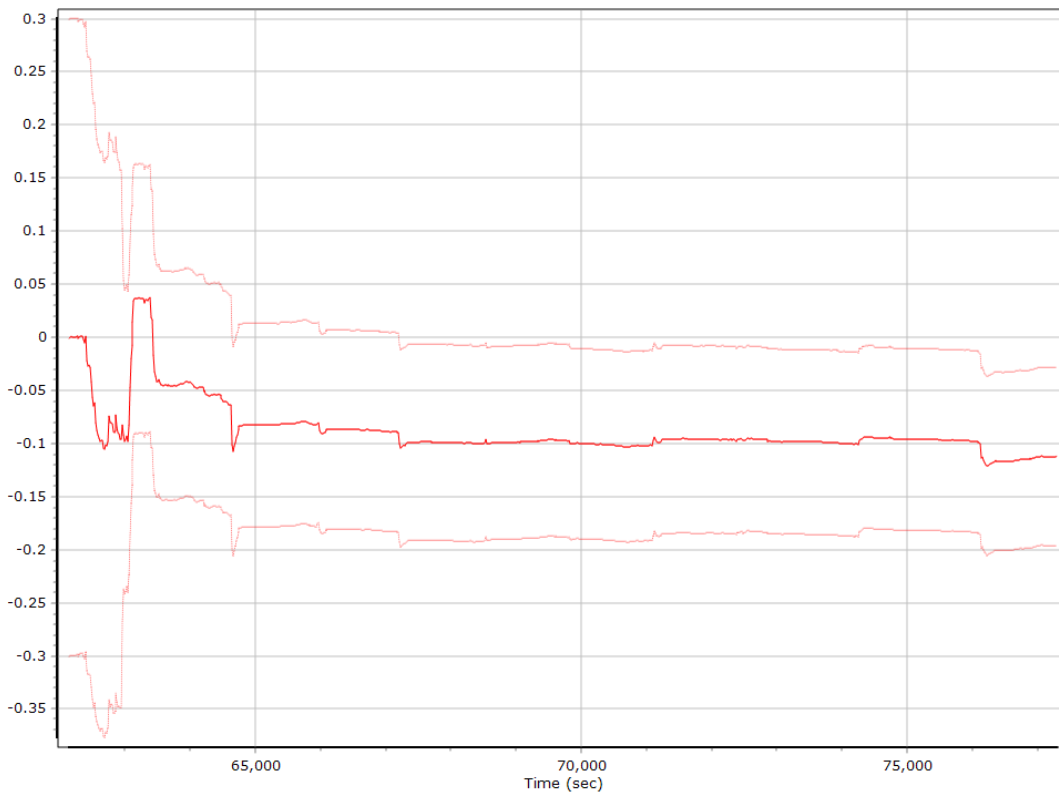
X Gyro Bias (deg/h)



Y Gyro Bias (deg/h)

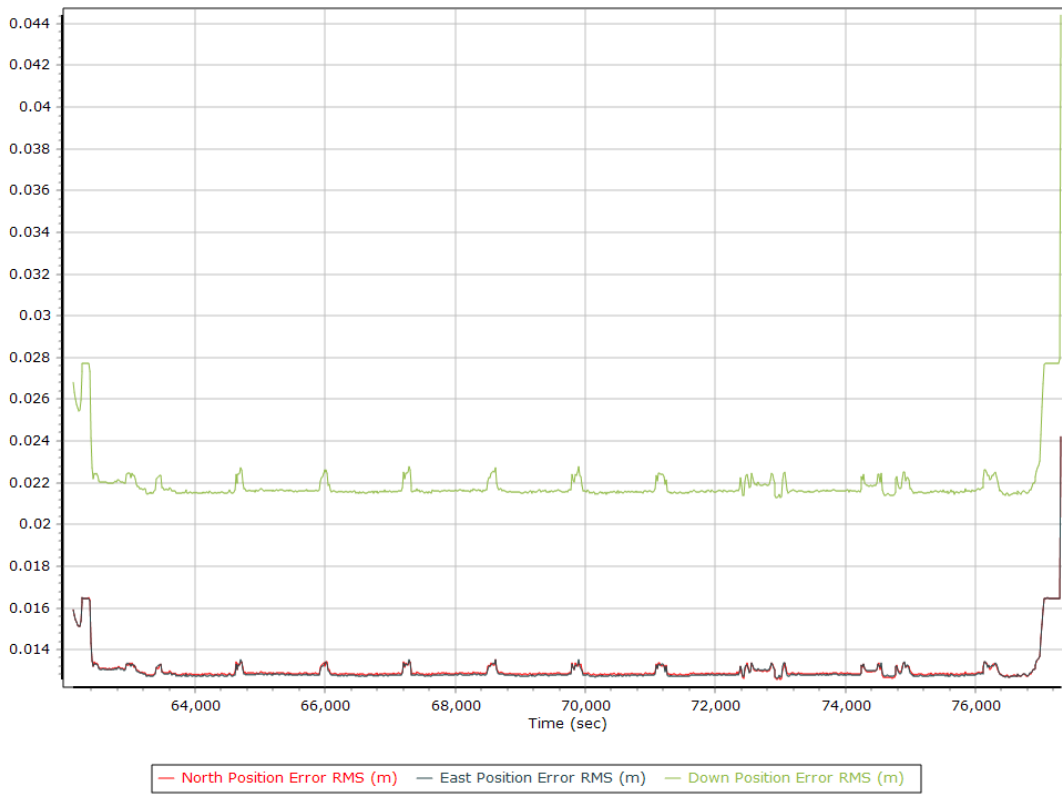


Z Gyro Bias (deg/h)

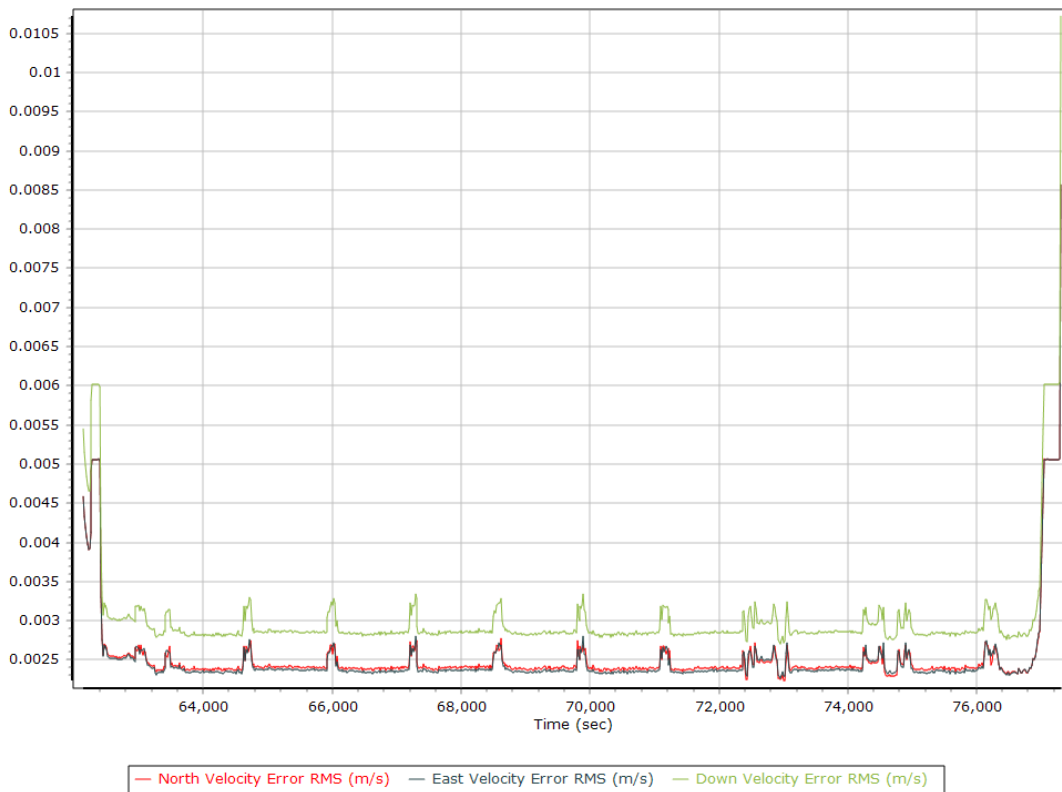


Smoothed Performance Metrics

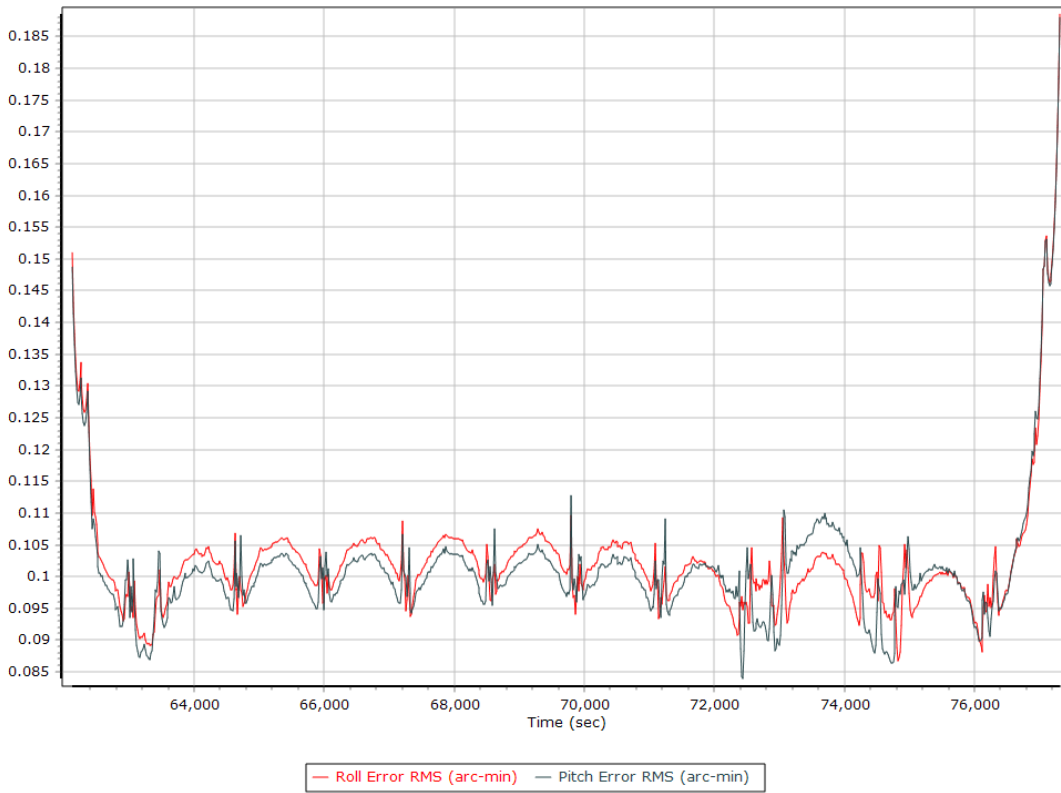
Position Error RMS (m)



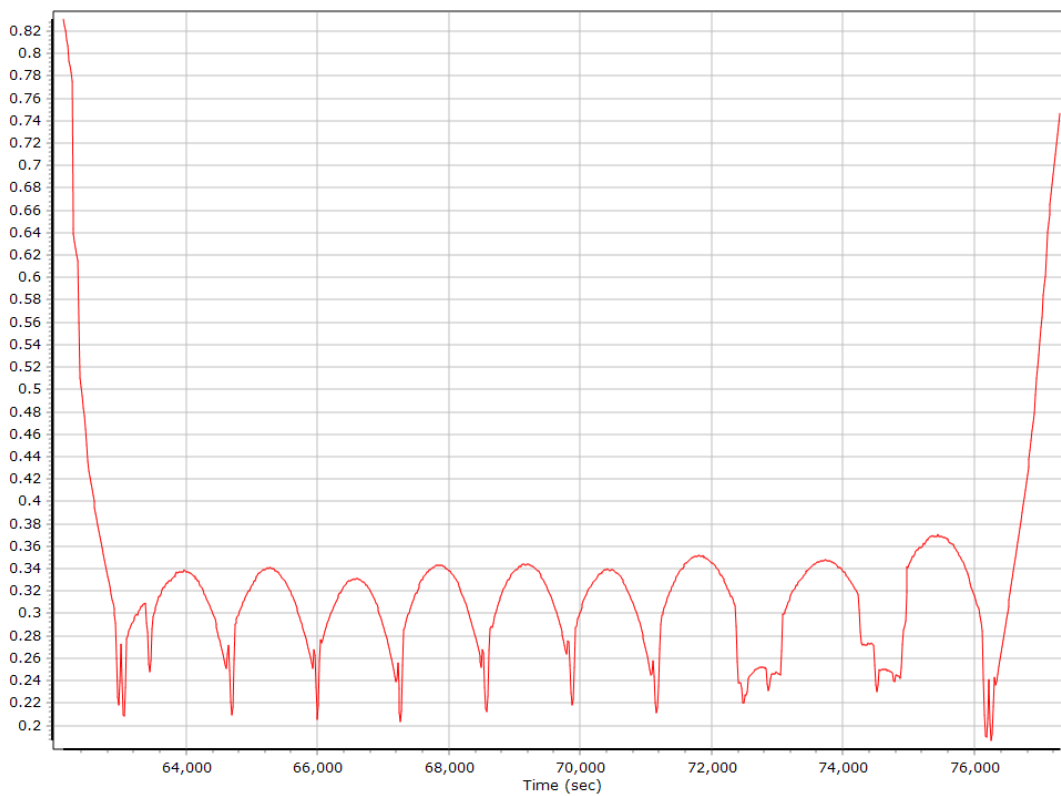
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

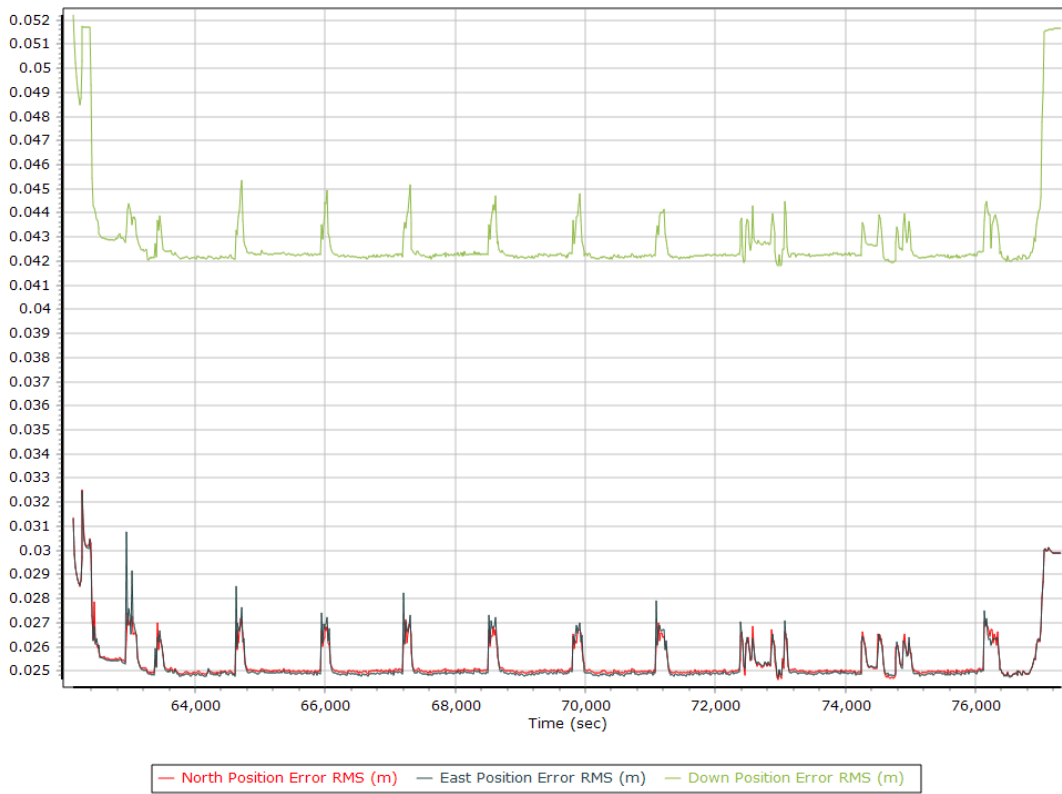


Heading Error RMS (arc-min)

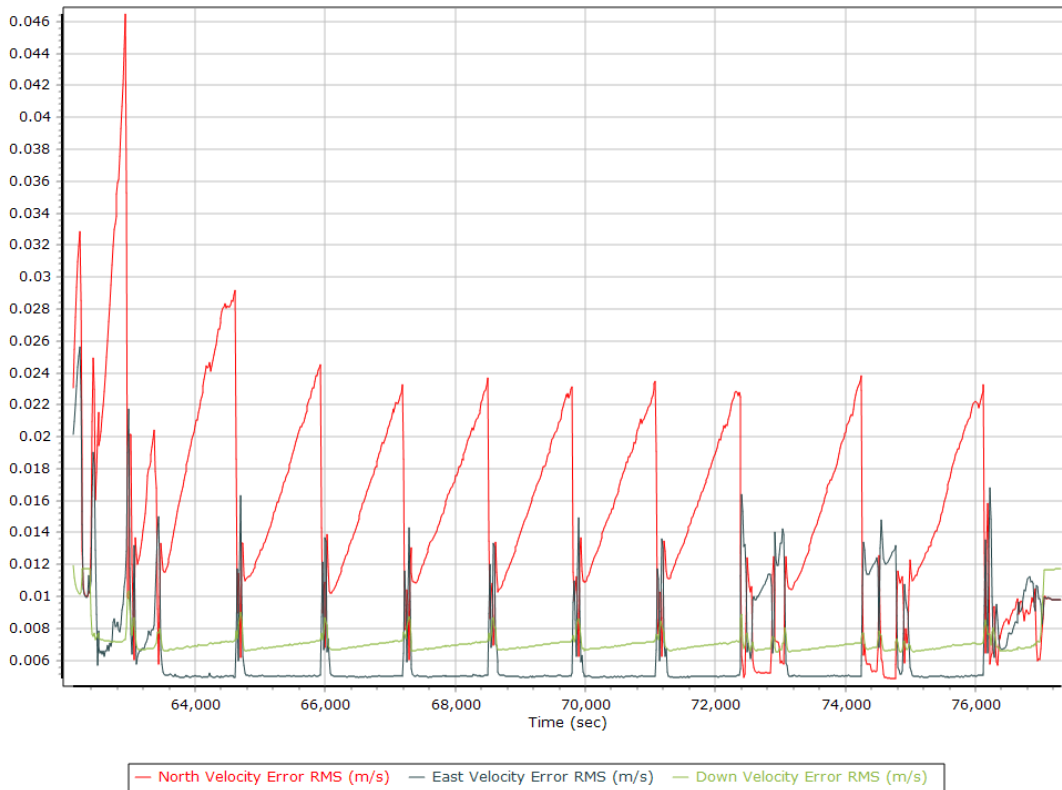


Forward Processed Performance Metrics

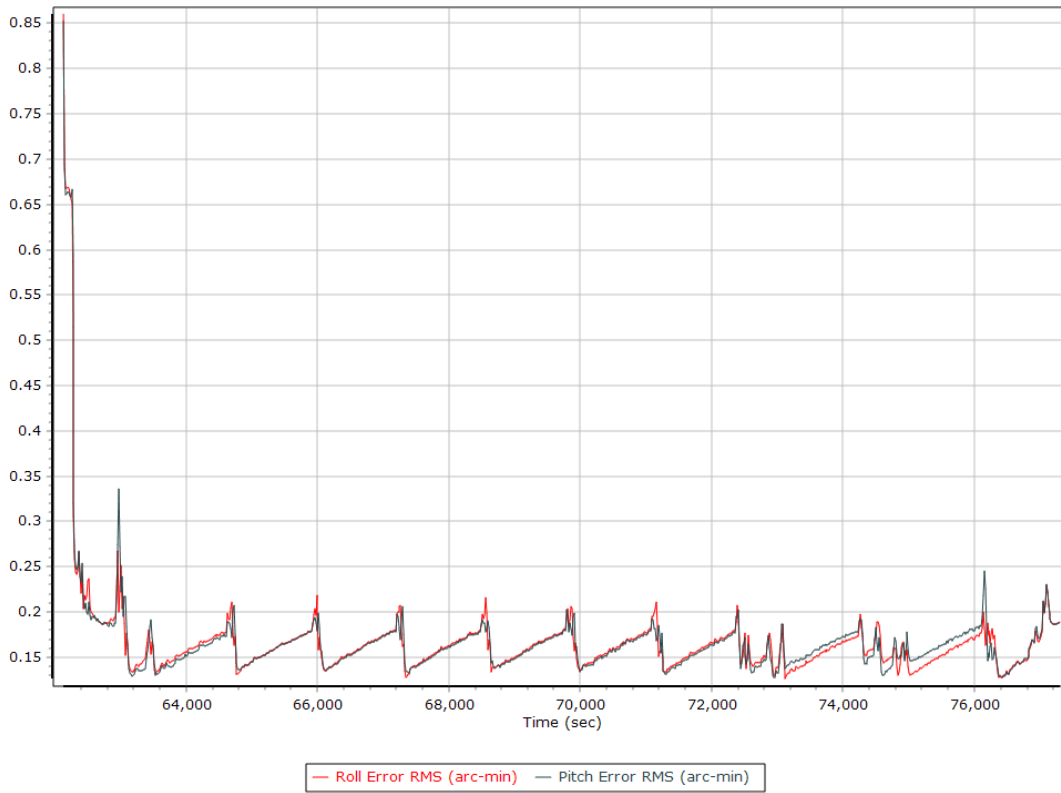
Position Error RMS (m)



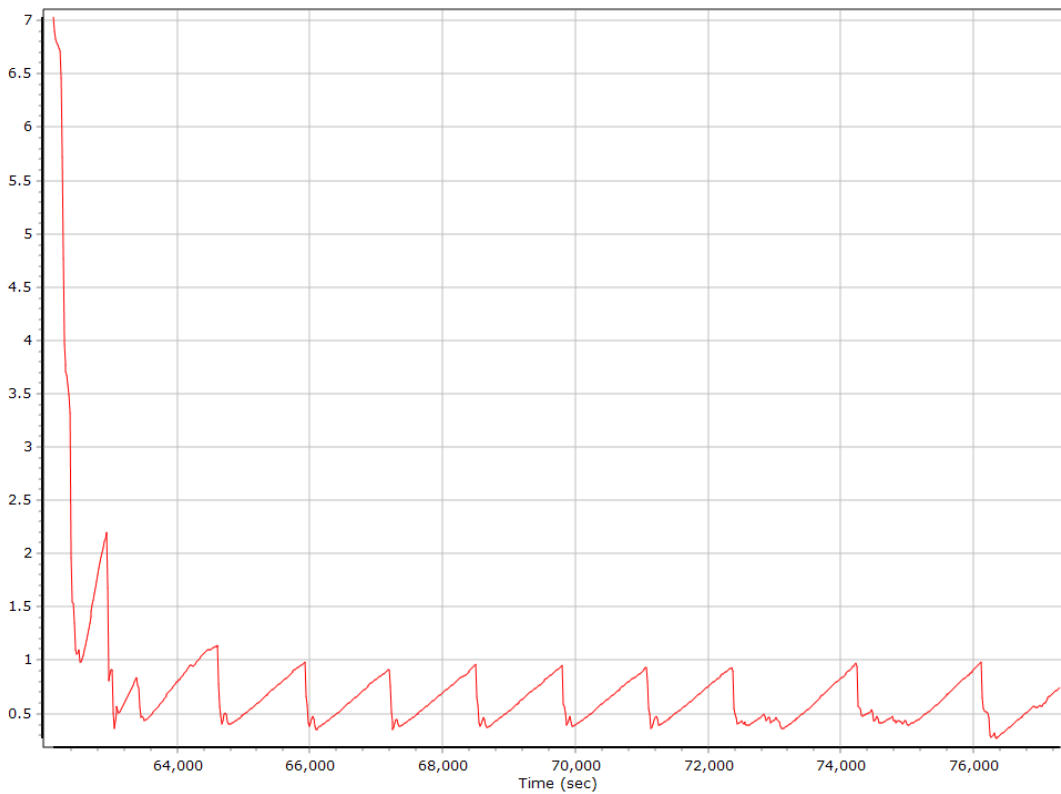
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

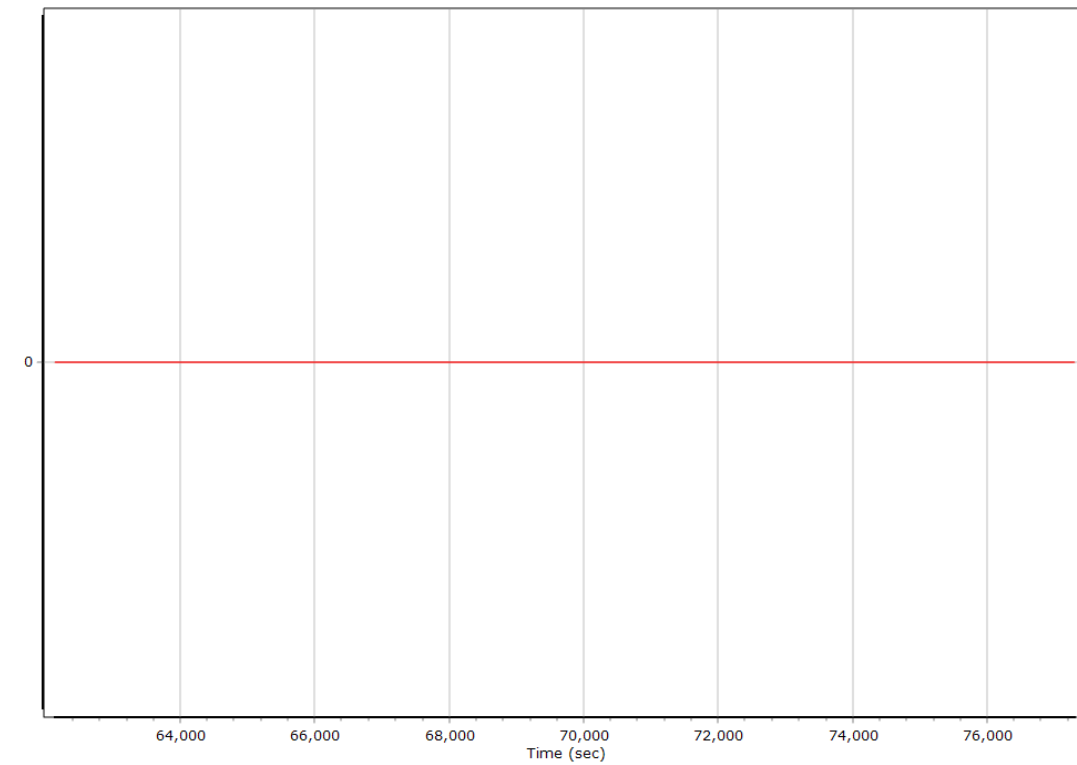


Heading Error RMS (arc-min)



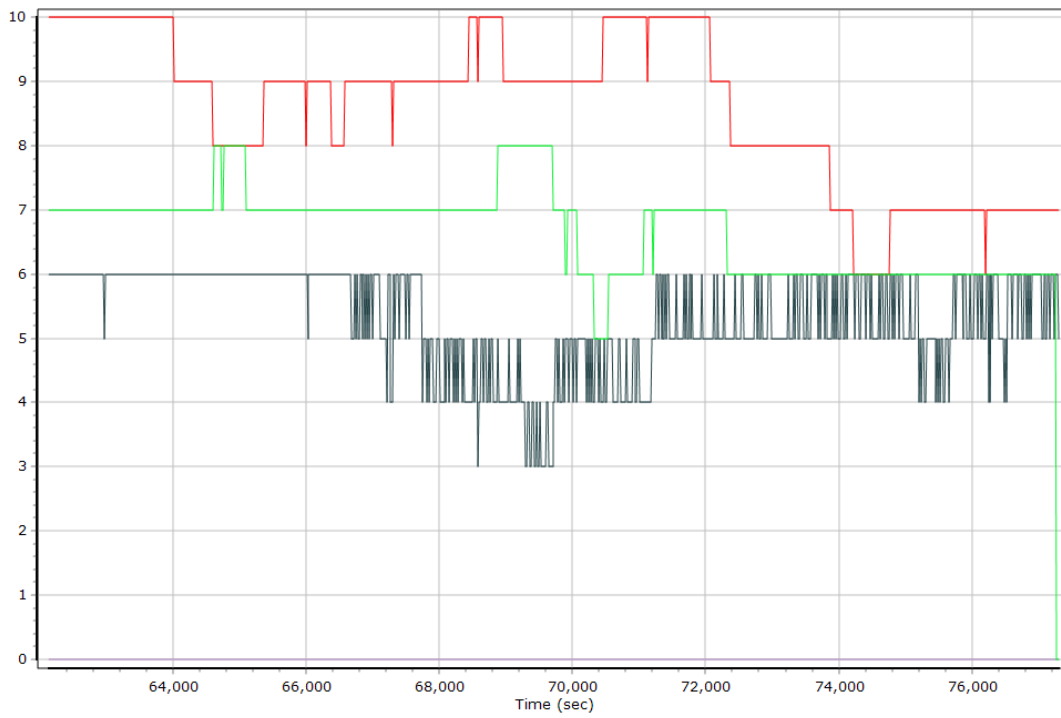
Forward Processed Solution Status

Processing Mode



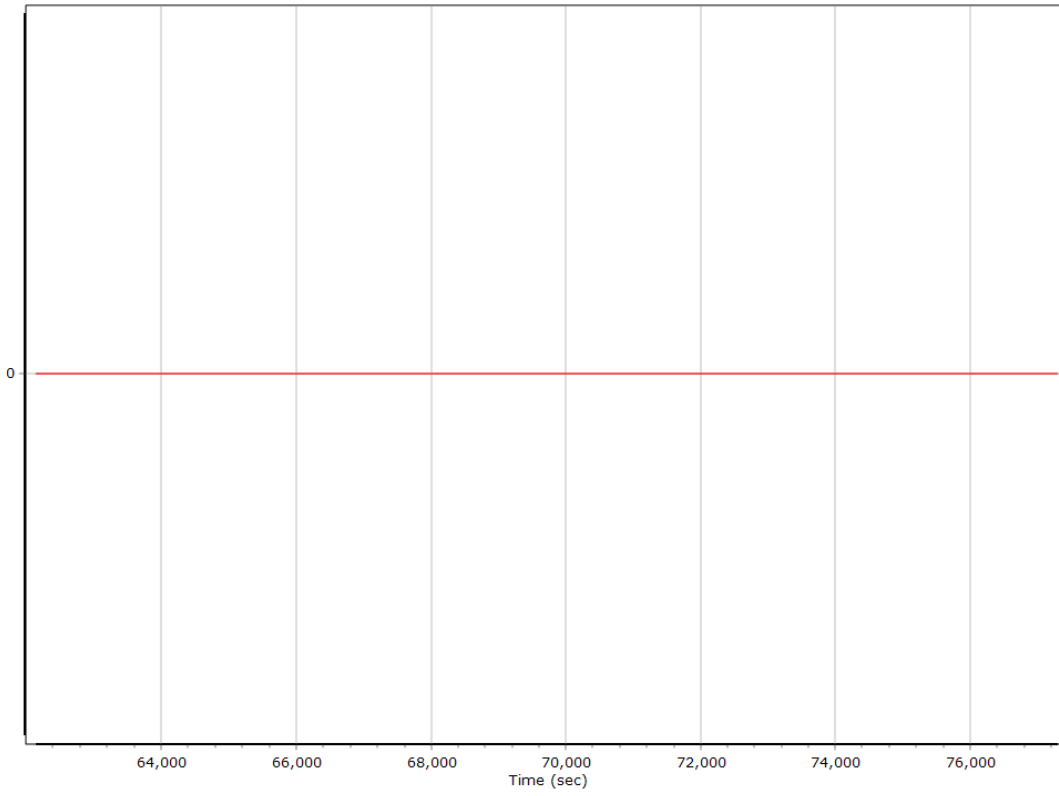
0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = C/A, 7 = GNSS Nav, 8 = DR

Number of Satellites



— Number of GPS Satellites — Number of GLONASS Satellites — Number of QZSS Satellites
— Number of BEIDOU Satellites — Number of GALILEO Satellites

Baseline Length



Export Summary Section 1

Export file	sbet_11892_NAD83(2011).out		
Export format	Custom Smoothed BET		
Solution in use	Post-processed		
Output rate	All Records		
Reference to Output lever arm (m)	0.000	0.000	0.000
Reference mounting angles (deg)	0.000	0.000	0.000
Output units (Coordinate / Lat & Lon)	Meter	Meter	
Export start time	62076.002 (12/06/2020 17:14:36)		
Export end time	77304.000 (12/06/2020 21:28:24)		
Height option	Ellipsoid Height		
WGS84 height flag	False		
Grid			
Zone			
Datum	NAD83 (2011)		
Ellipsoid	GRS 1980		
Local Transformation			
Target Epoch	2010		

Export Summary Section 2

Export file	lever_arm_values.txt		
Export format	ReferenceToPrimaryLeverArms		
Solution in use	Post-processed		
Output rate	All Records		
Reference to Output lever arm (m)	0.000	0.000	0.000
Reference mounting angles (deg)	0.000	0.000	0.000
Output units (Coordinate / Lat & Lon)	Meter	Meter	
Export start time	62076.002 (12/06/2020 17:14:36)		
Export end time	77304.000 (12/06/2020 21:28:24)		
Height option	Ellipsoid Height		
WGS84 height flag	False		
Grid	Universal Transverse Mercator		
Zone	UTM North 14 (102W to 96W)		
Datum	WGS84		
Ellipsoid	WGS84		
Local Transformation	NONE		
Target Epoch	2010		

EO Summary Section 1

EO file			
EO format	ZI Imaging		
Lever arm (m)	0.000	0.000	0.000
Boresight angles (arcmin)	0.0000	0.0000	0.0000
Output rate	All Records		
Rotation sequence	x omega	y phi	z kappa
Local shift (m)	0.000	0.000	0.000
Output units (coordinate / angle / lat & lon)	Meter	Degree	Deg Decimal
Height option	Ellipsoid Height		
WGS84 height flag	False		
Scale height option	False		
Kappa cardinal rotation (deg)	0		
Solution in use	Post-processed		
EO start time	62076.002 (12/06/2020 17:14:36)		
EO end time	77304.000 (12/06/2020 21:28:24)		
Grid	Universal Transverse Mercator		
Zone	UTM North 14 (102W to 96W)		
Datum	NAD83 (2011)		
Ellipsoid	GRS 1980		
Local Transformation	NONE		
Target Epoch	2010		