

General Information

Mission Information

Project name	220711_A_5060492_nad2011_FINAL
Processing date	2022-07-14 15:25:32
Mission date	2022-07-11 13:09:03
Mission duration	03:47:03.000
Processing mode	IN-Fusion PP-RTX

Rover Hardware Information

Product	POS AV 610 VER6 HW2.5-12
Serial number	S/N12686
IMU type	57
Receiver type	BD982
Antenna type	AV39

Project File List

Rover Data Files

File name	File type
220711a.135	POS Data
220711a.136	POS Data
220711a.137	POS Data
220711a.138	POS Data
220711a.139	POS Data
220711a.140	POS Data
220711a.141	POS Data
220711a.142	POS Data
220711a.143	POS Data
220711a.144	POS Data
220711a.145	POS Data
220711a.146	POS Data
220711a.147	POS Data
220711a.148	POS Data
220711a.149	POS Data
220711a.150	POS Data
220711a.151	POS Data
220711a.152	POS Data
220711a.153	POS Data
220711a.154	POS Data
220711a.155	POS Data
220711a.156	POS Data
220711a.157	POS Data
220711a.158	POS Data
220711a.159	POS Data
220711a.160	POS Data
220711a.161	POS Data
220711a.162	POS Data
220711a.163	POS Data
220711a.164	POS Data

Input Files

File Name	File Type
Ephm1920.22g	GLONASS Broadcast Ephemeris
Ephm1920.22n	GPS Broadcast Ephemeris

Output Files

Filename	File type
sbet_220711_A_5060492_nad2011_FINAL.out	SBET Trajectory File
sbet_220711_A_5060492_nad2011_FINAL.shp	Shapefile Export Output

Rover Data Summary

First raw data file	220711a.135		
Last raw data file	220711a.164		
Start GPS week	2218		
Start time	133742.364 (07/11/2022 13:09:02)		
End time	147365.924 (07/11/2022 16:56:05)		
Start of fine alignment	134019.995 (07/11/2022 13:13:39)		
Available subsystems	Primary GNSS, IMU		
POS Event Input	None		
Correction data	None		
IMU Installation Lever Arms & Mounting Angles			
Reference to IMU lever arm (m)	0.000	0.000	0.000
Reference to IMU mounting angles (deg)	0.000	0.000	180.000
Reference to Primary GNSS lever arm (m)	0.361	-0.429	-0.945
Reference to Primary GNSS lever arm std dev (m)	-1.000		
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

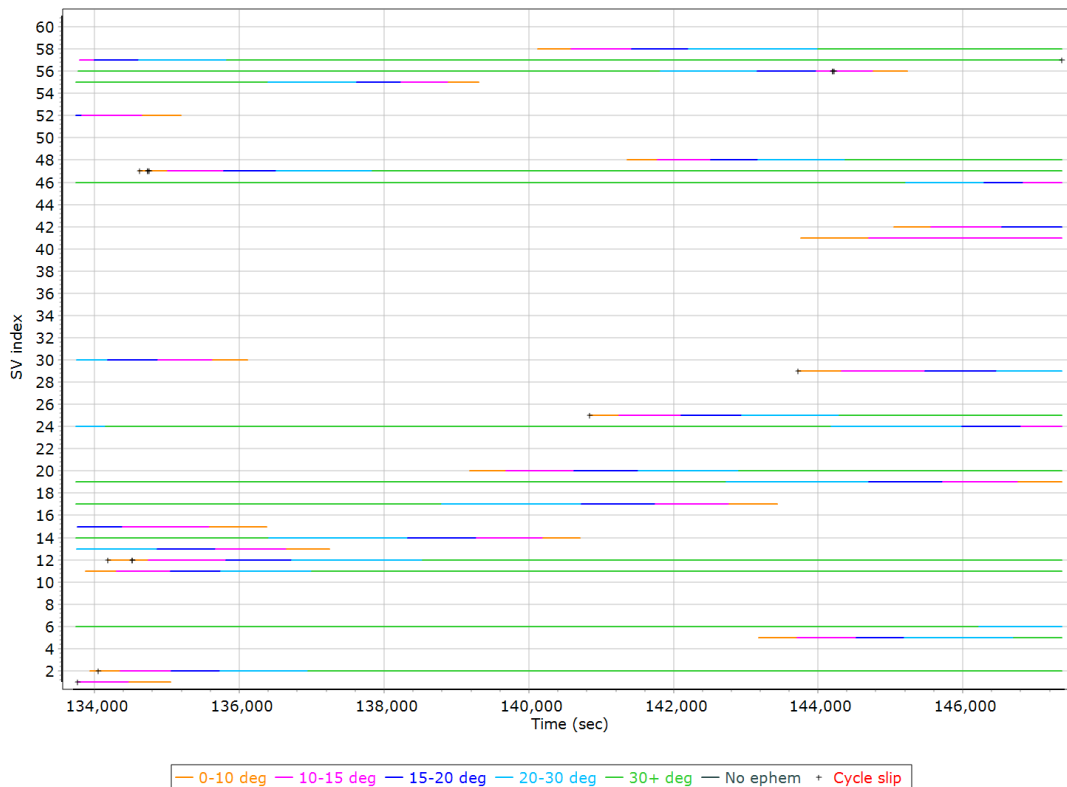
Rover Data QC

Raw IMU Import QC Summary

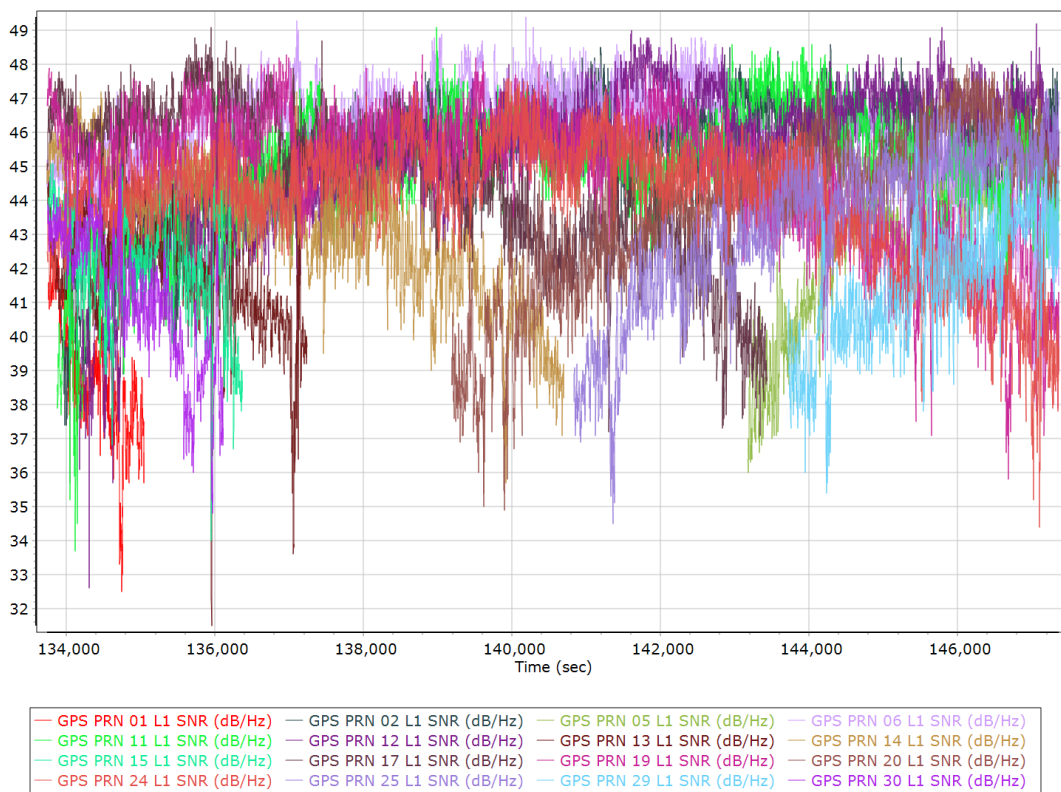
IMU data input file	imu_220711_A_5060492_nad2011_FINAL.dat
IMU data check log file	imudt_220711_A_5060492_nad2011_FINAL.log
IMU Records Processed	2724305
Termination Status	Normal
IMU Anomalies	0

Primary Observables & Satellite Data

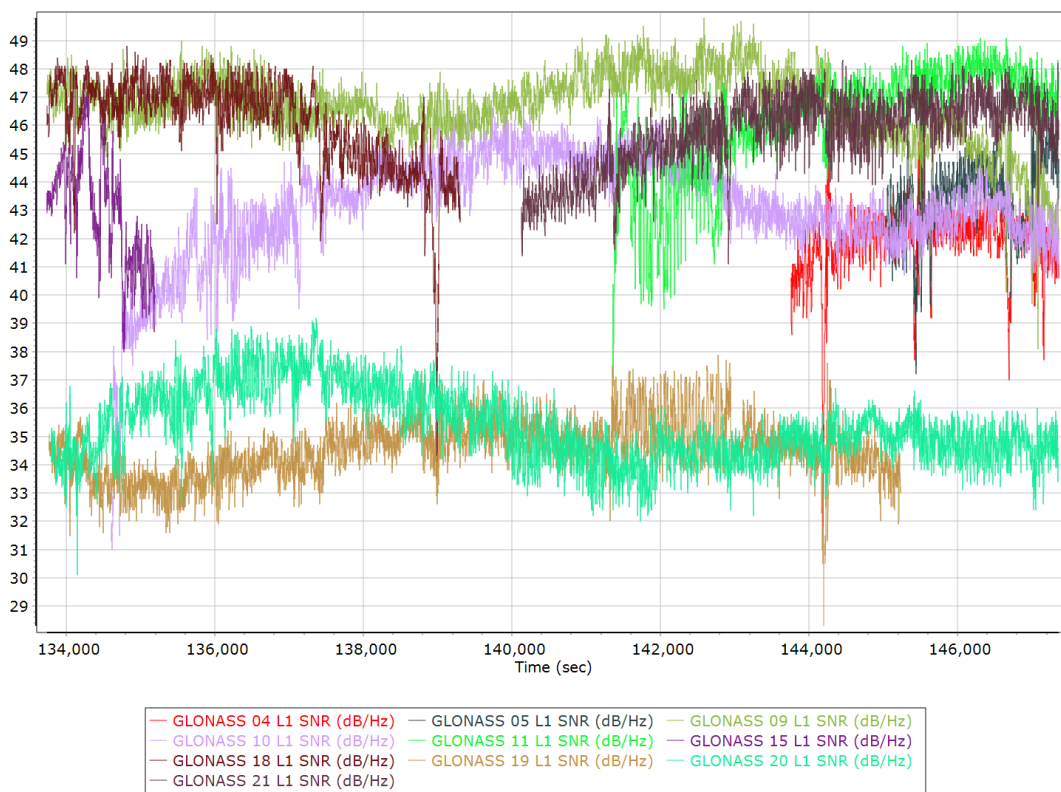
GPS/GLONASS L1 Satellite Lock/Elevation



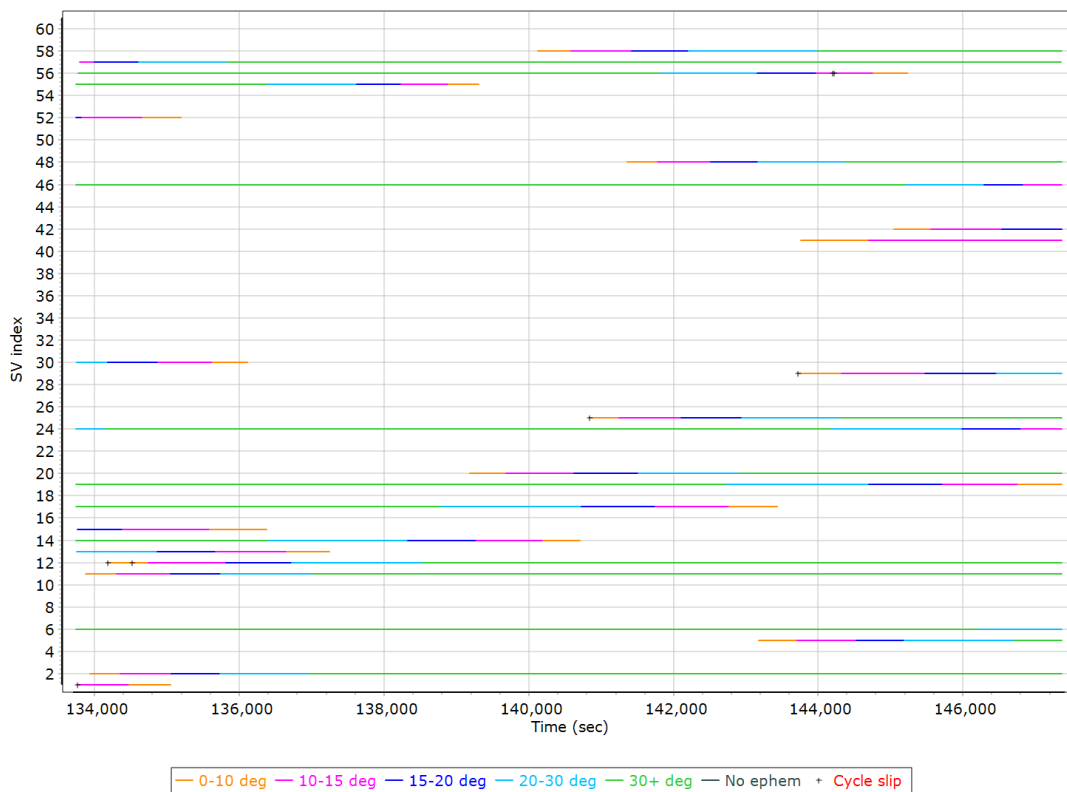
GPS L1 SNR



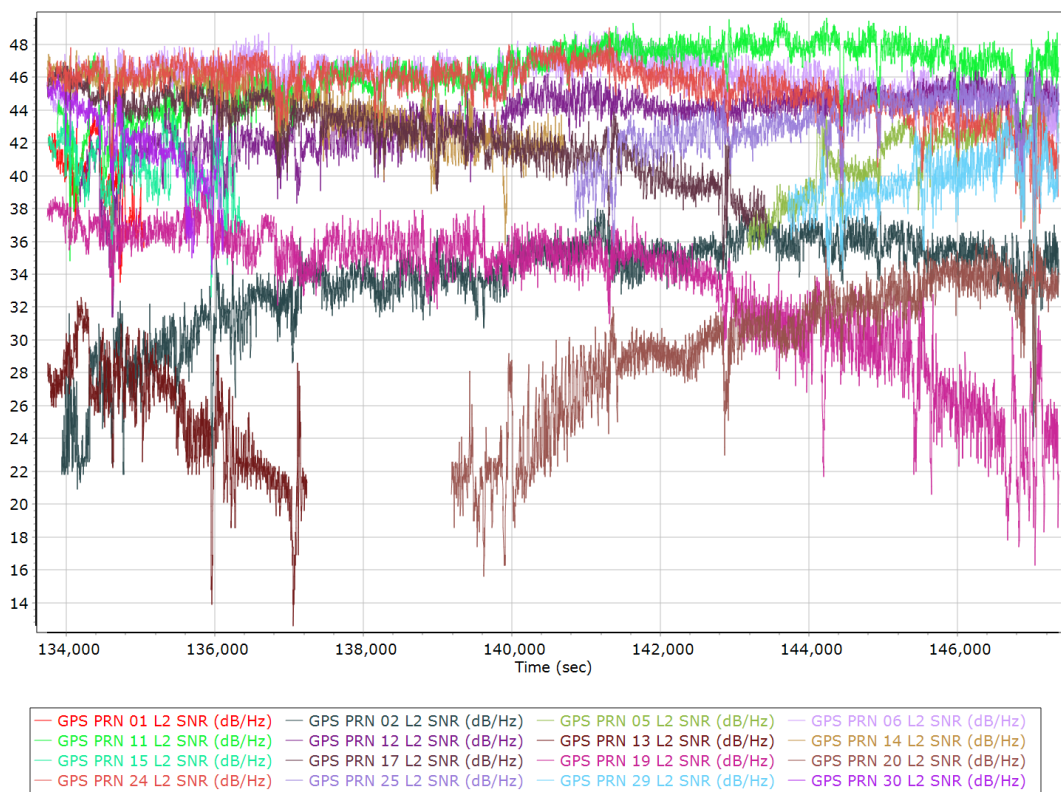
GLONASS L1 SNR



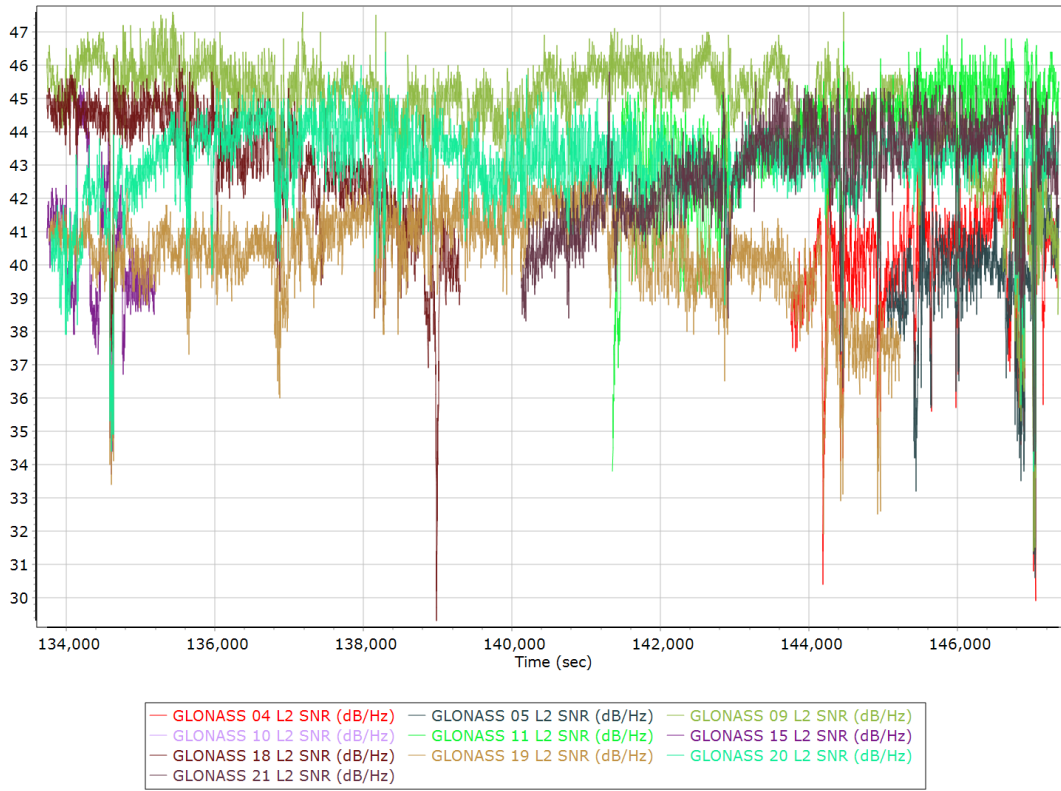
GPS/GLONASS L2 Satellite Lock/Elevation



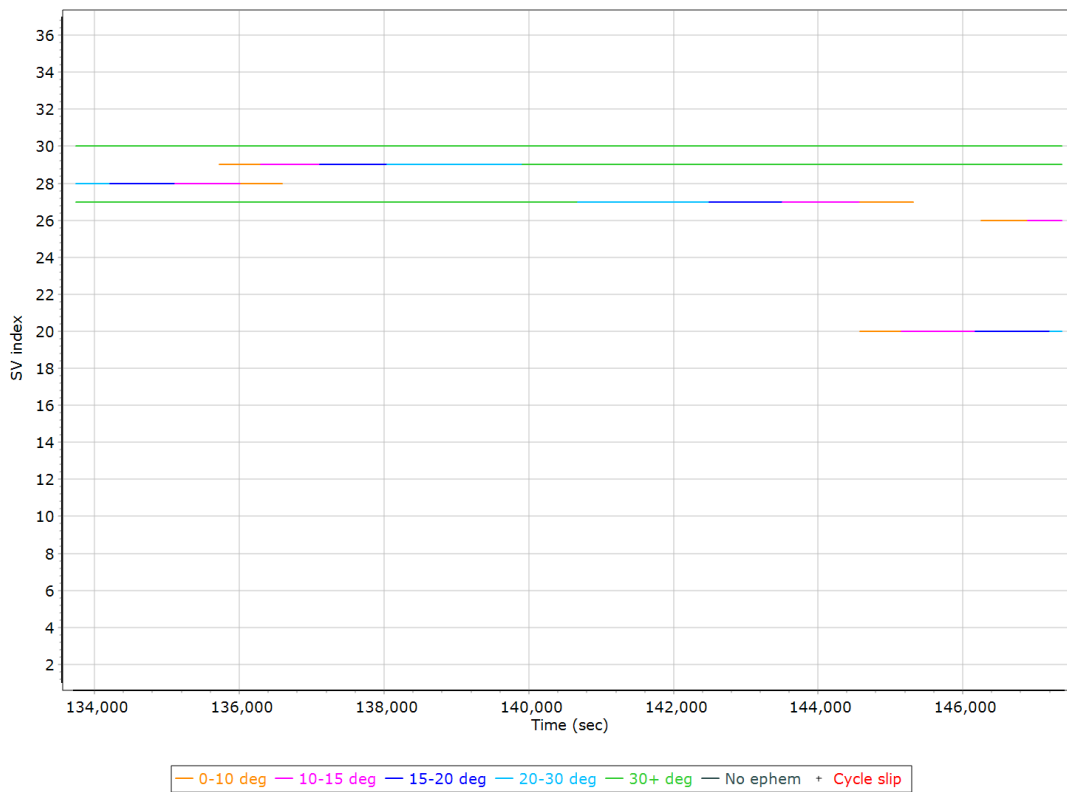
GPS L2 SNR



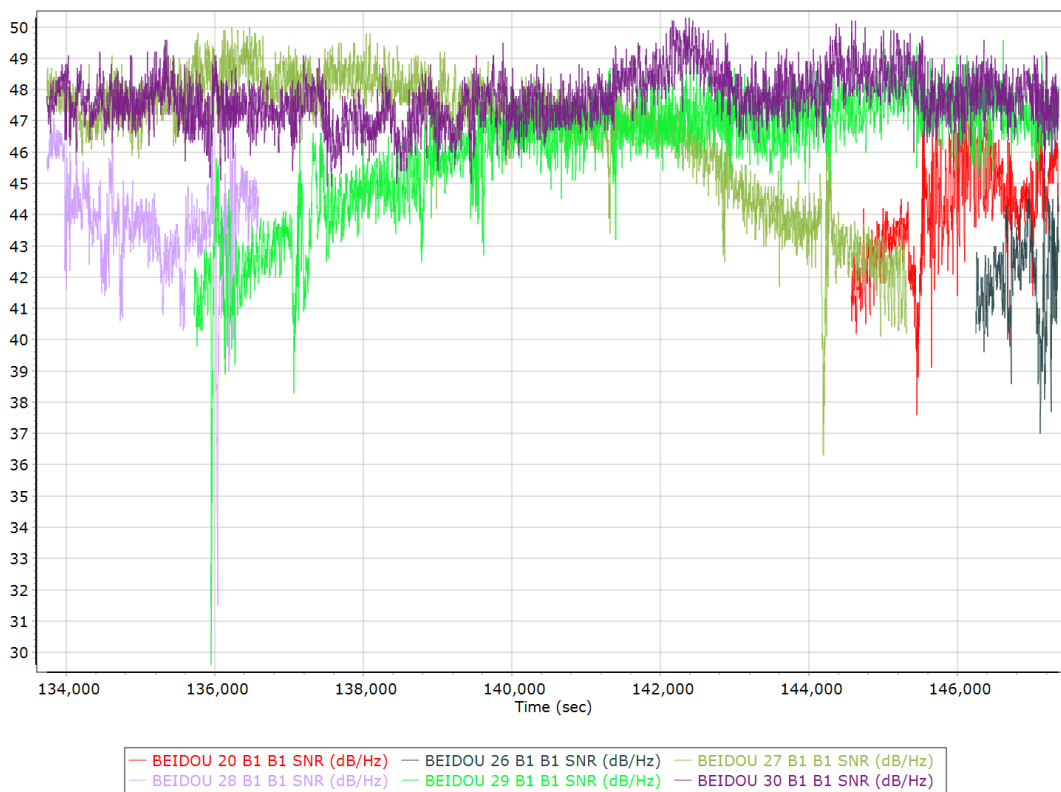
GLONASS L2 SNR



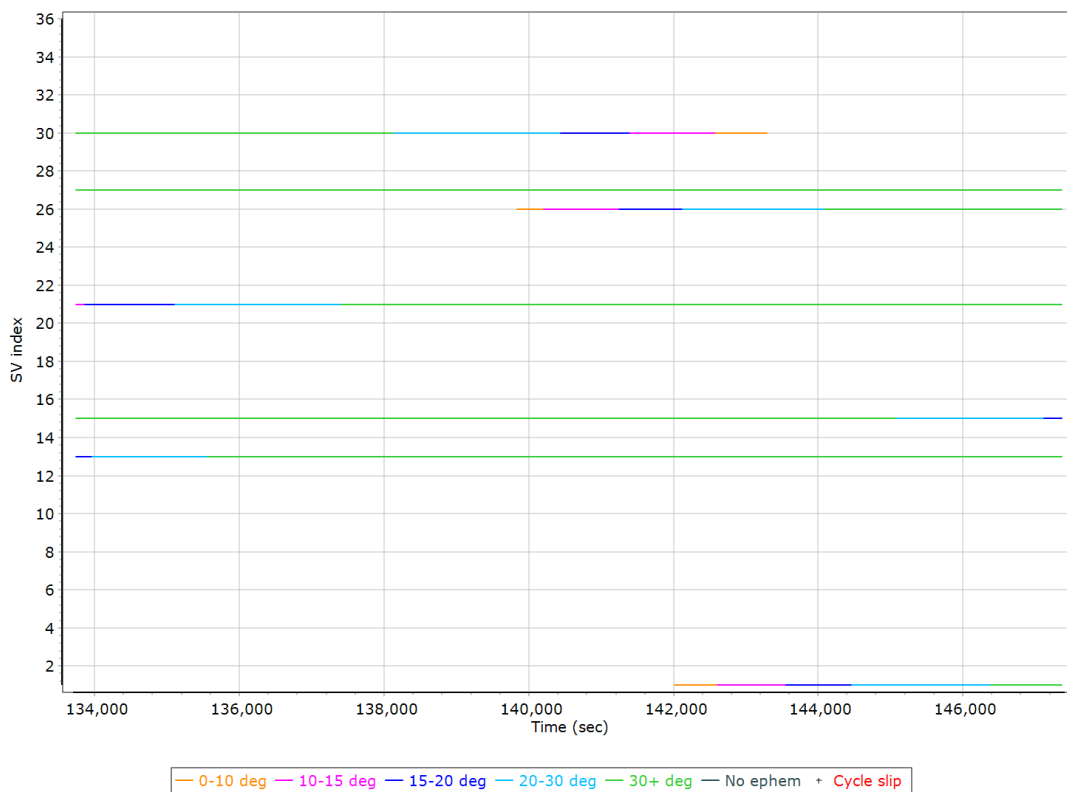
BEIDOU Satellite Lock/Elevation



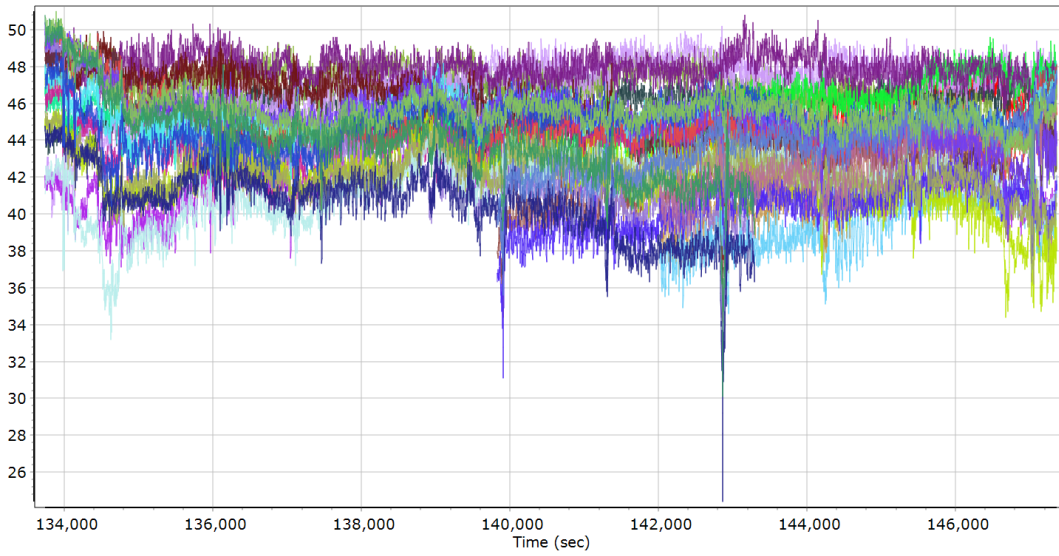
BEIDOU SNR



GALILEO Satellite Lock/Elevation

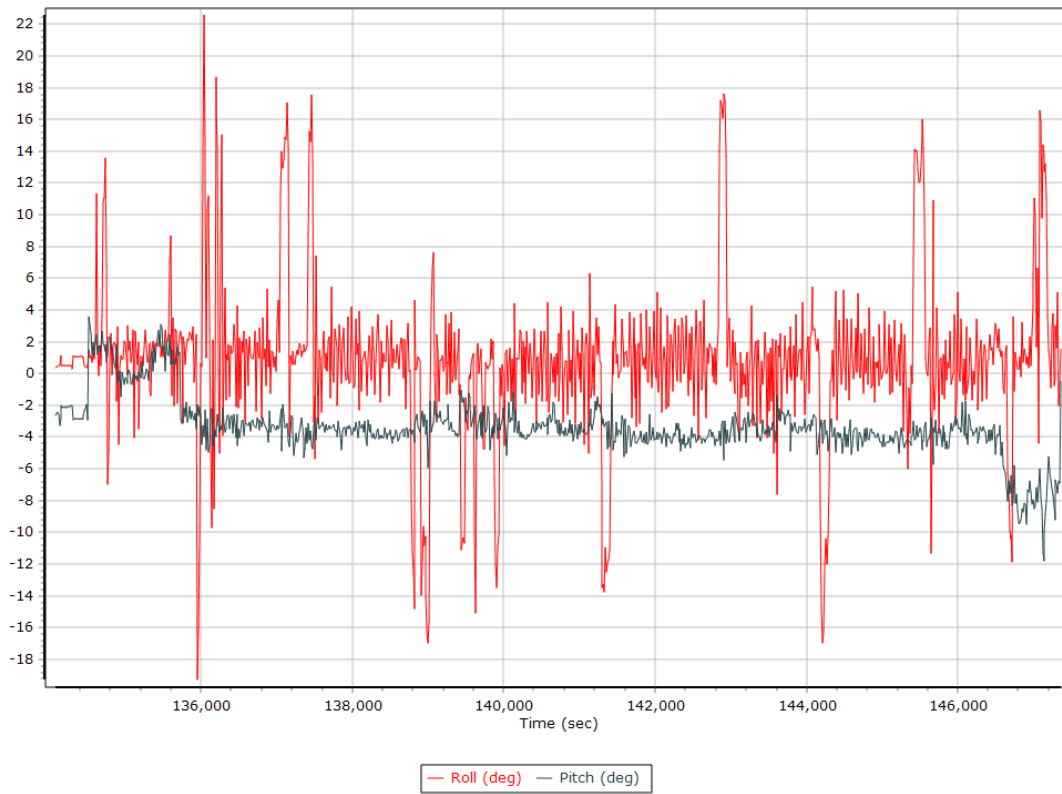


GALILEO SNR

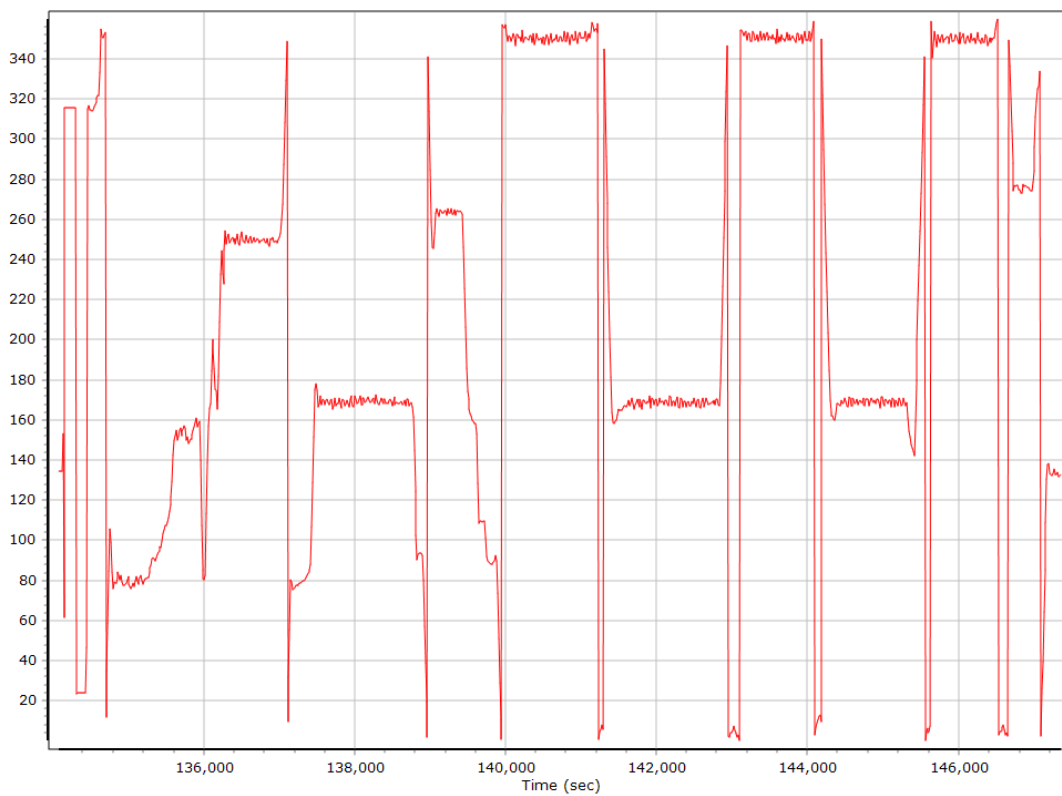


— GALILEO 01 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 13 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 15 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 21 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 26 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 27 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 30 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 01 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 13 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 15 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 21 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 26 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 27 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 30 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 01 E5B BPSK10_PD SNR (dB/Hz)	— GALILEO 13 E5B BPSK10_PD SNR (dB/Hz)
— GALILEO 15 E5B BPSK10_PD SNR (dB/Hz)	— GALILEO 21 E5B BPSK10_PD SNR (dB/Hz)
— GALILEO 26 E5B BPSK10_PD SNR (dB/Hz)	— GALILEO 27 E5B BPSK10_PD SNR (dB/Hz)

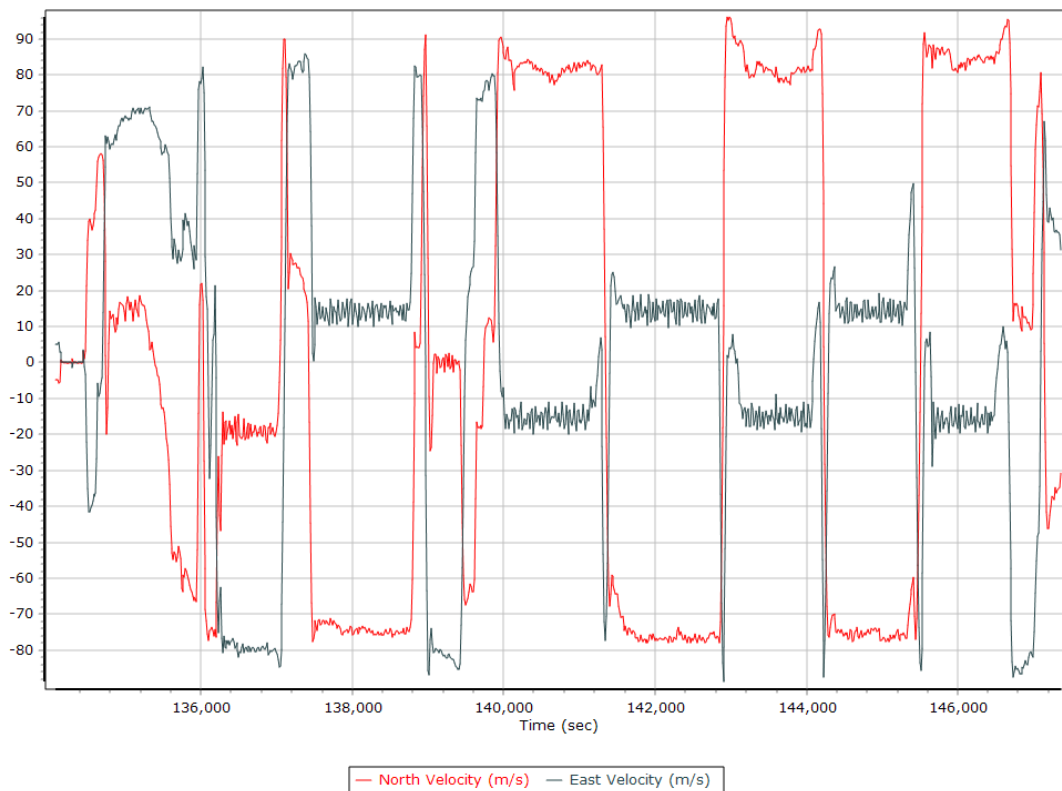
Roll/Pitch



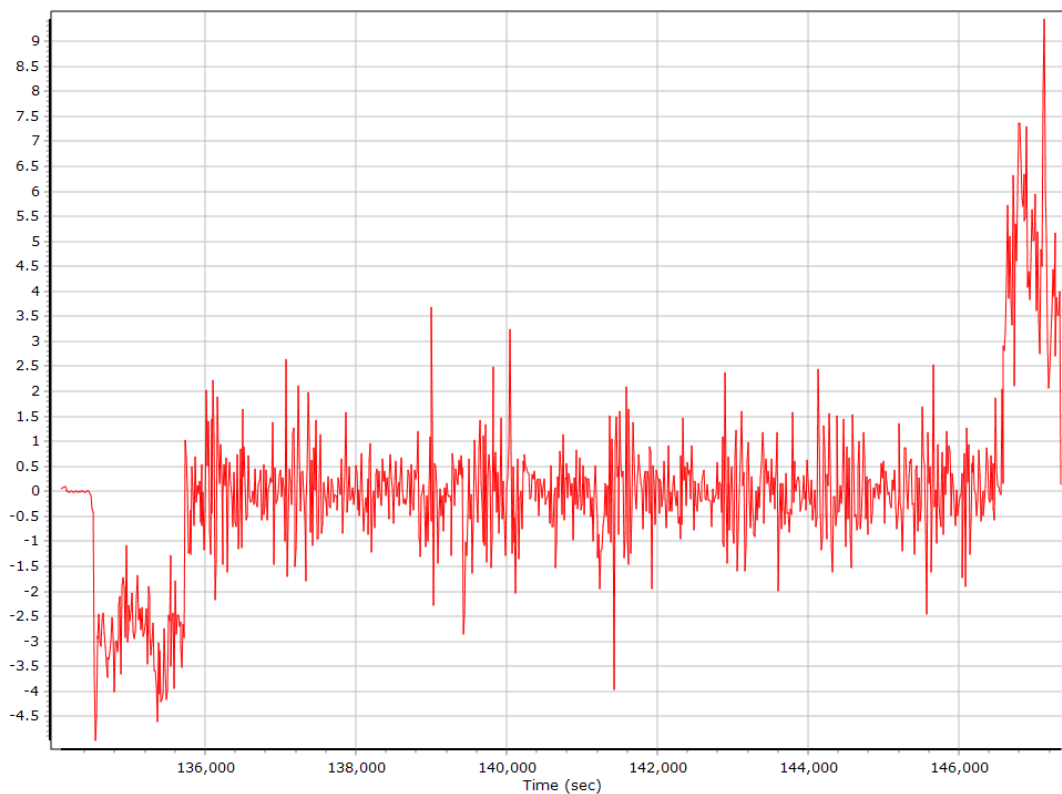
Heading



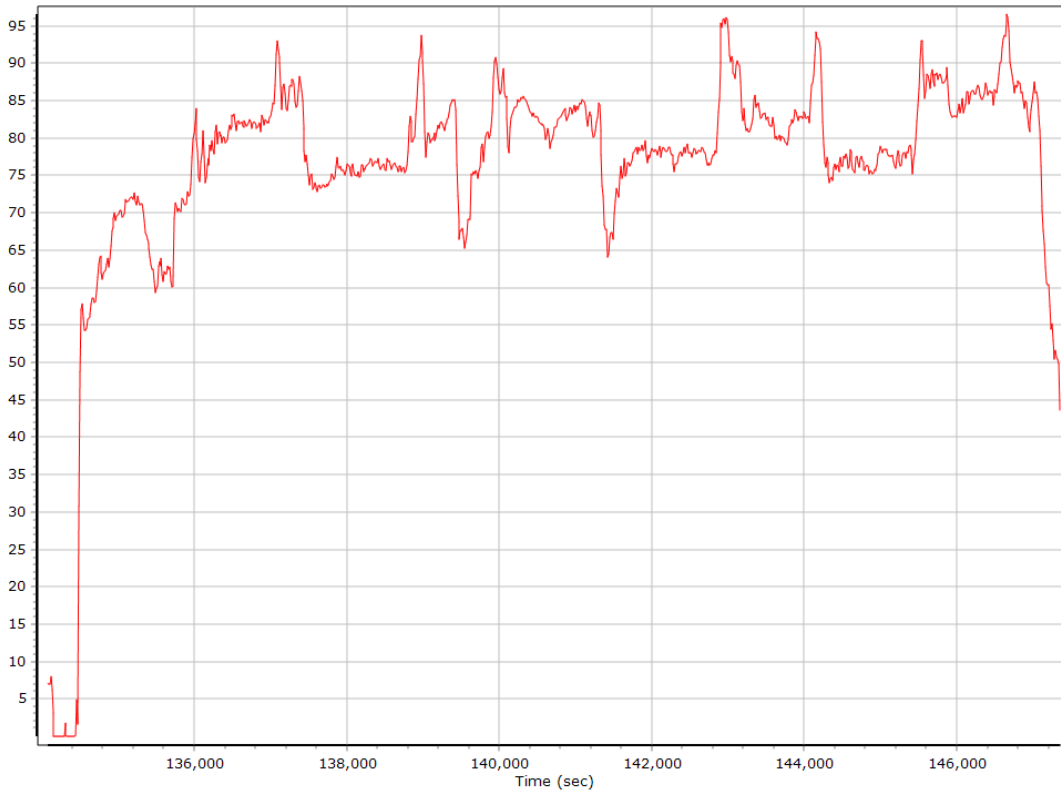
North/East Velocity



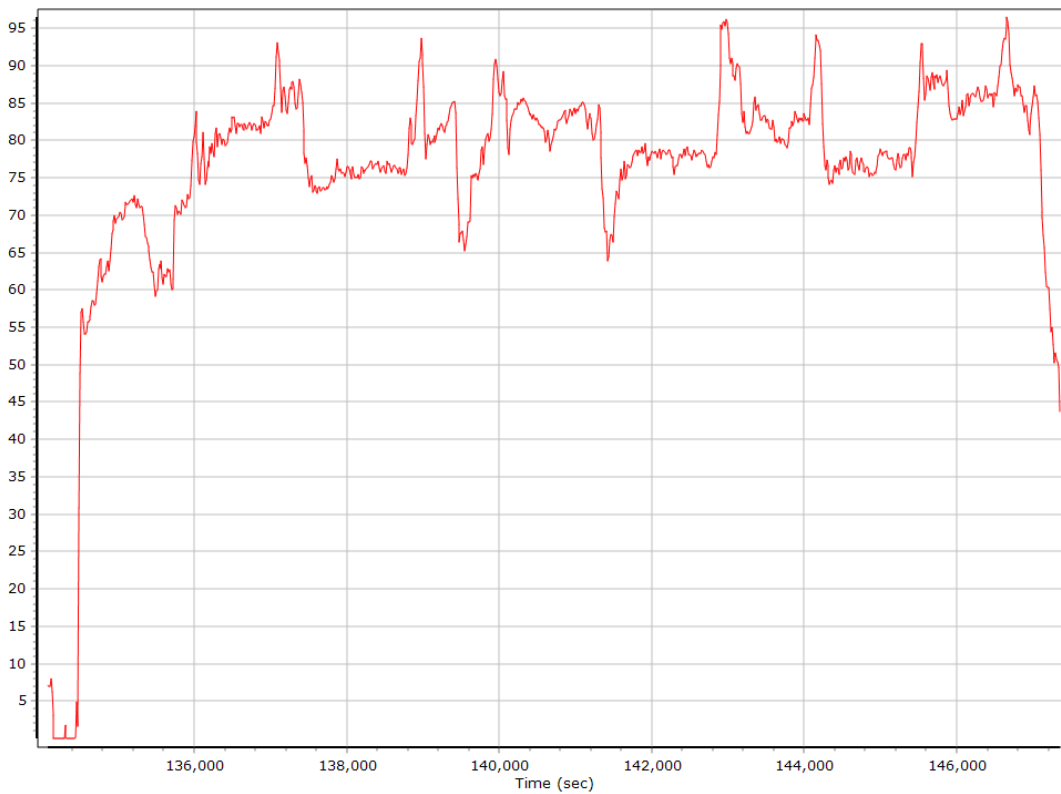
Down Velocity



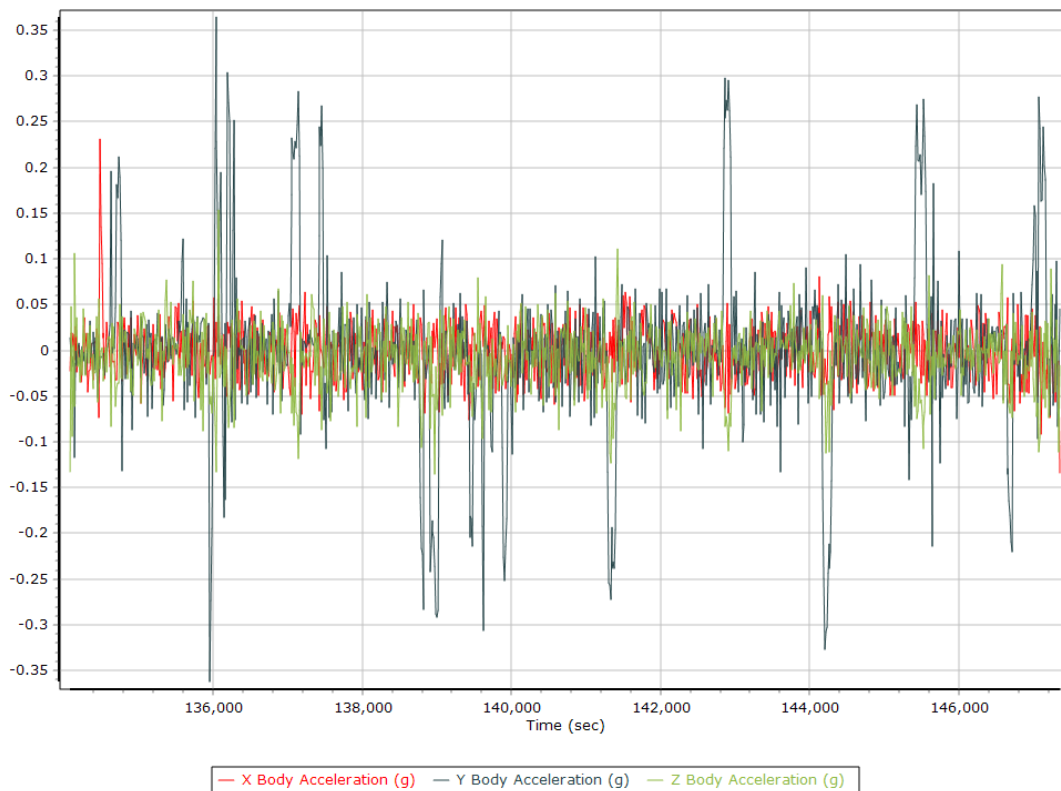
Total Speed



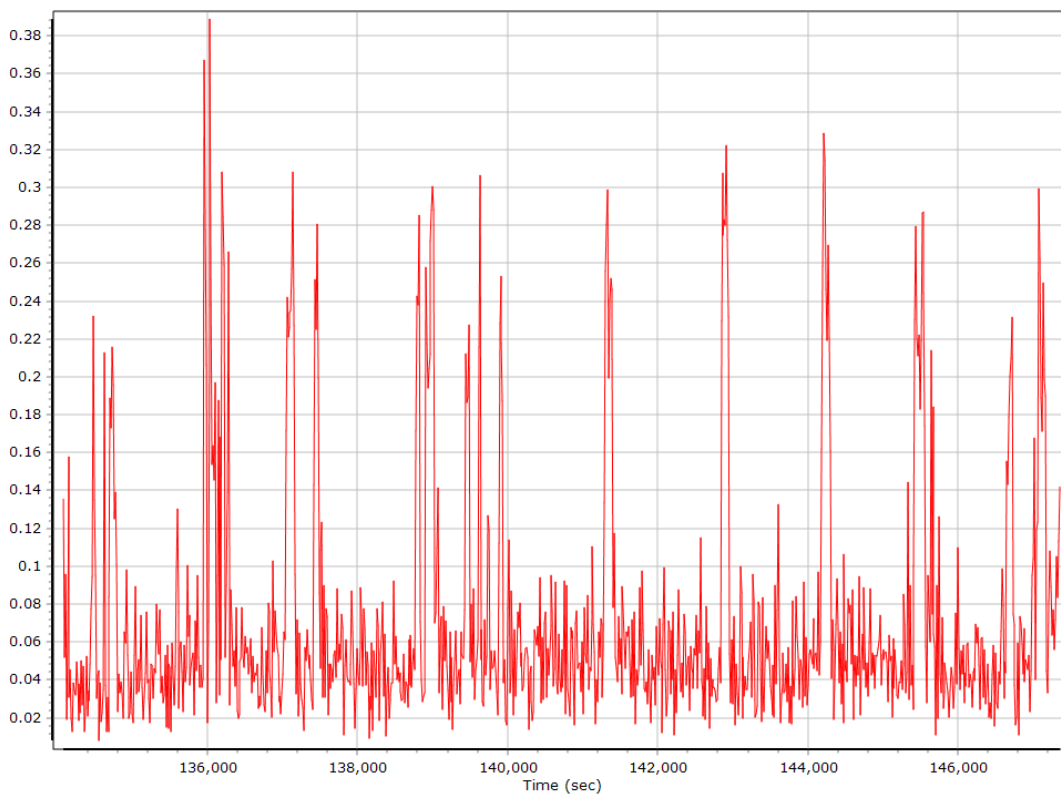
Ground Speed



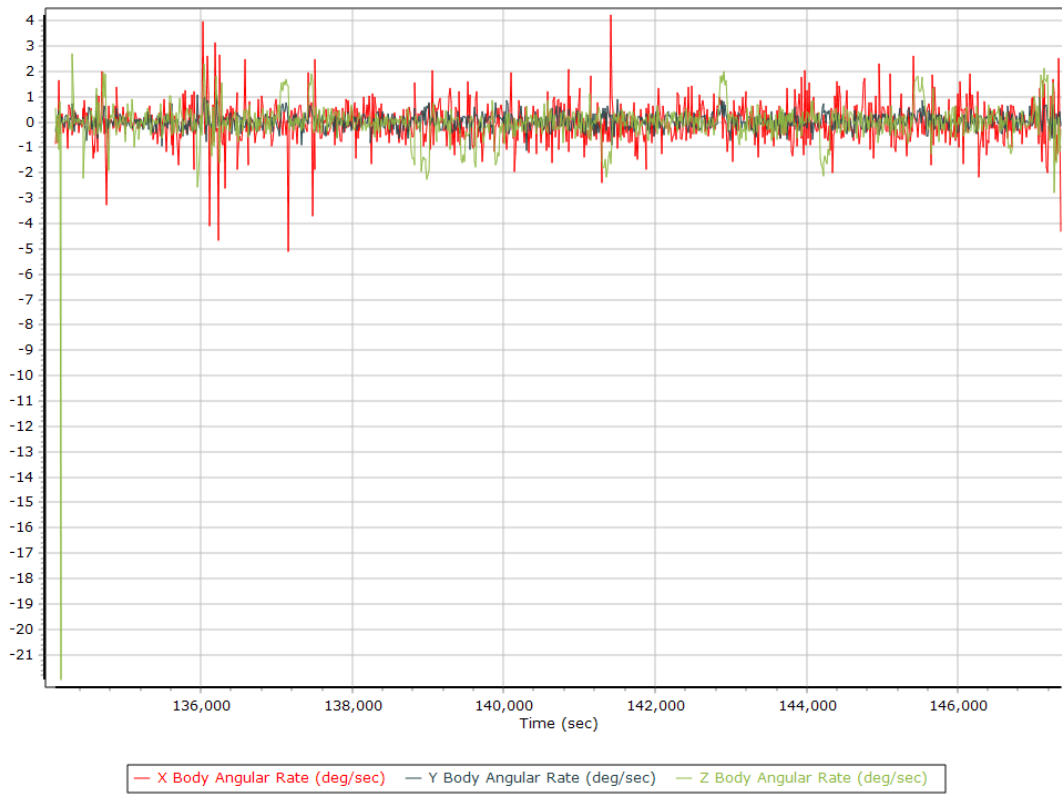
Body Acceleration



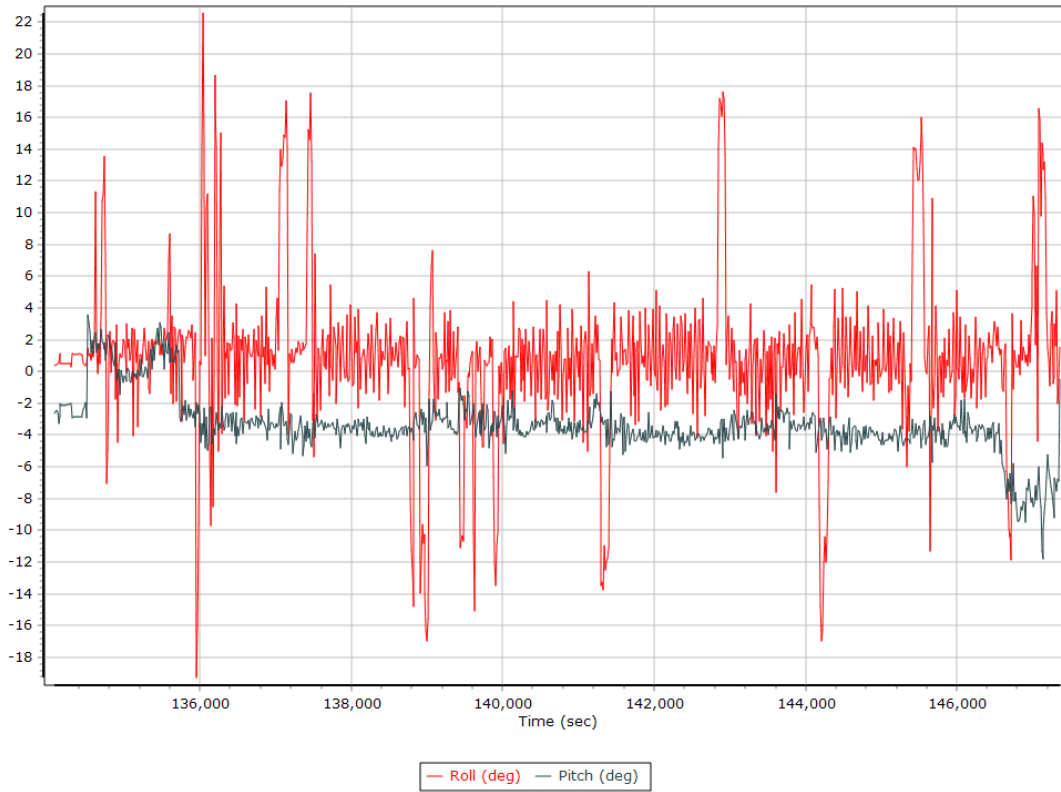
Total Body Acceleration



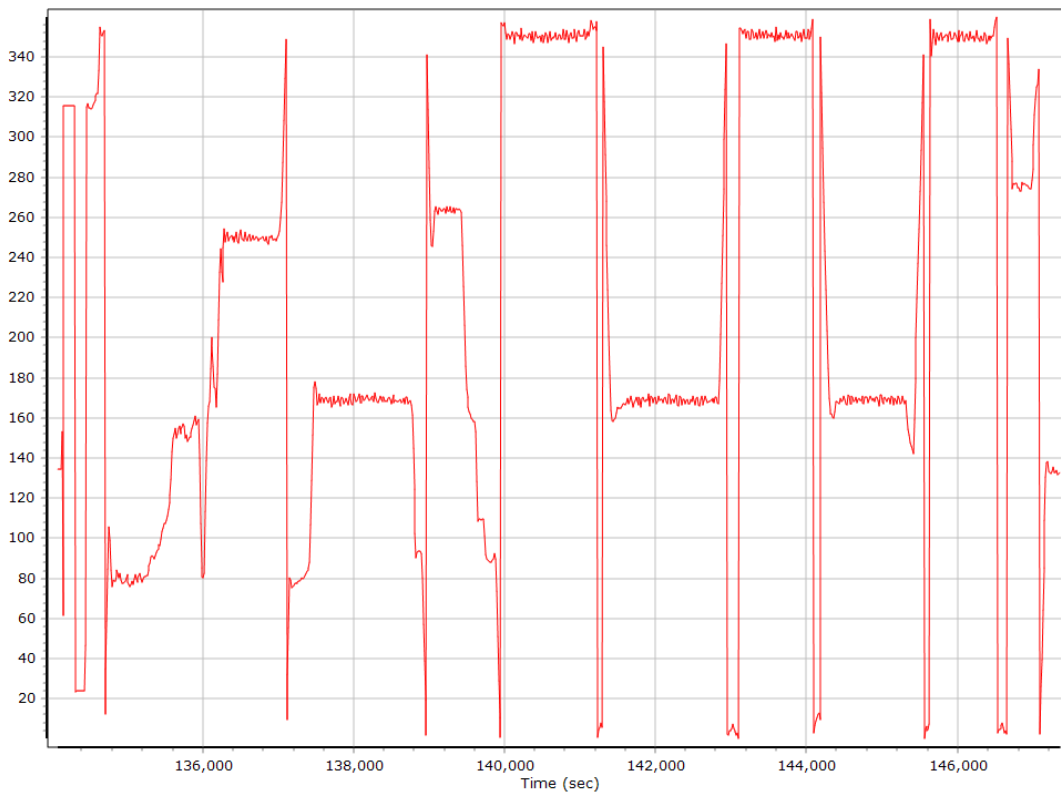
Body Angular Rate



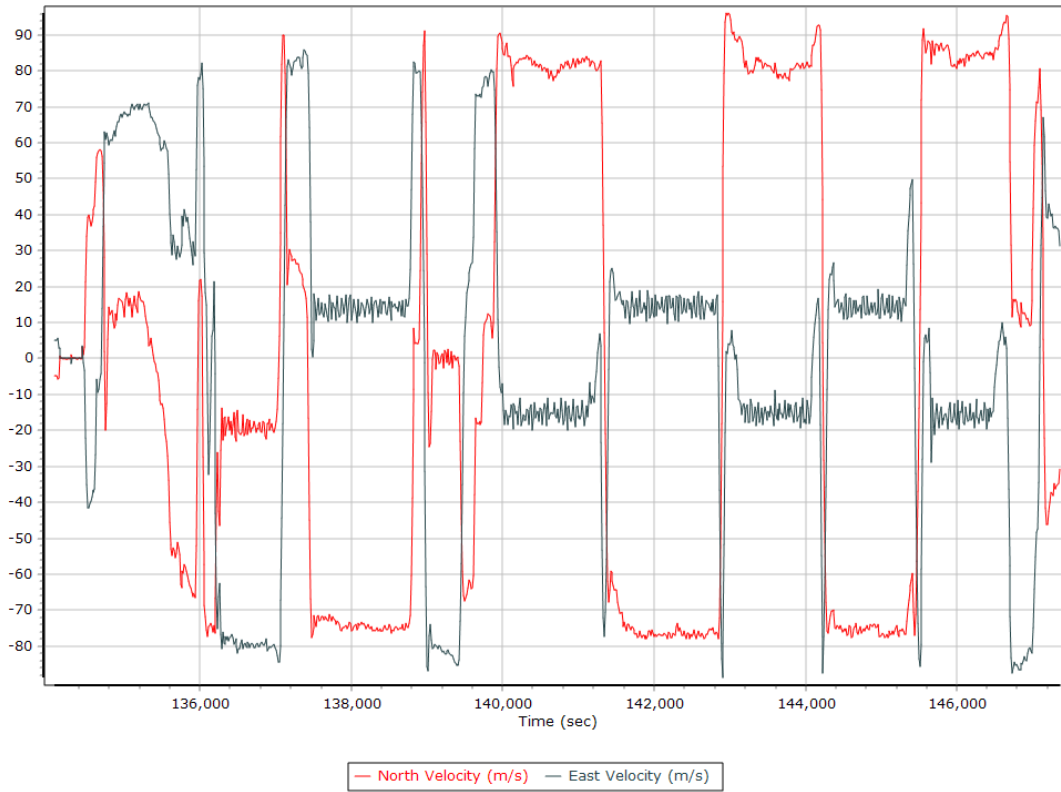
Roll/Pitch



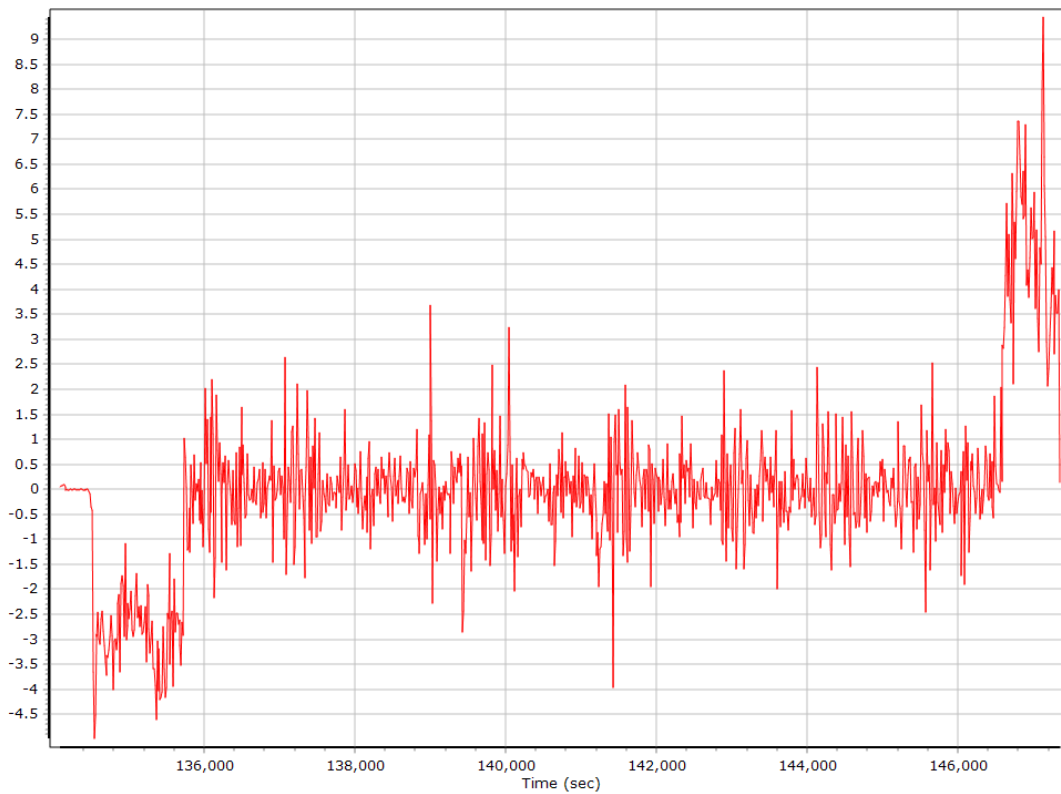
Heading



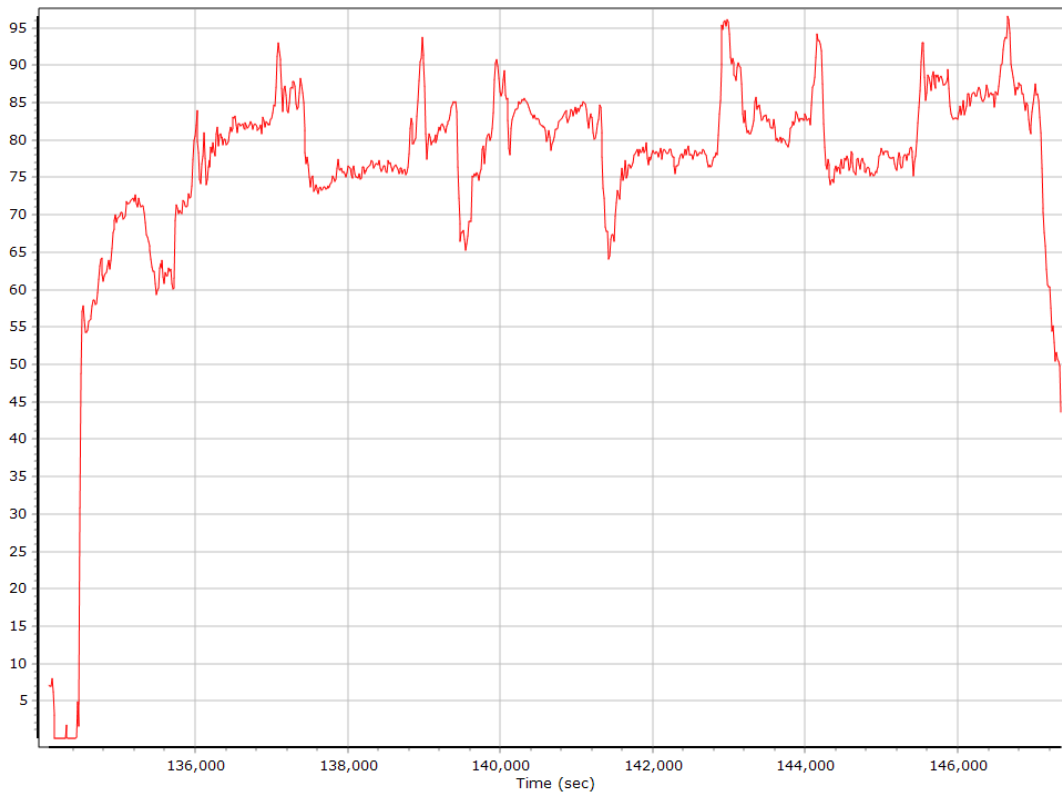
North/East Velocity



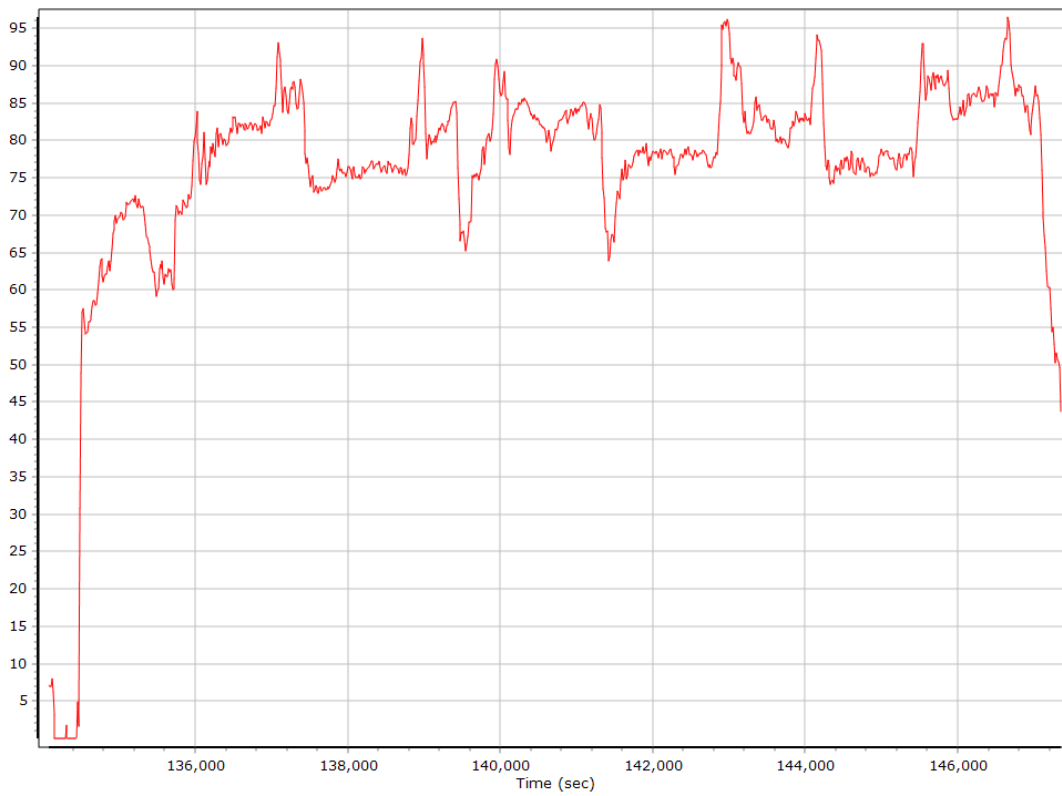
Down Velocity



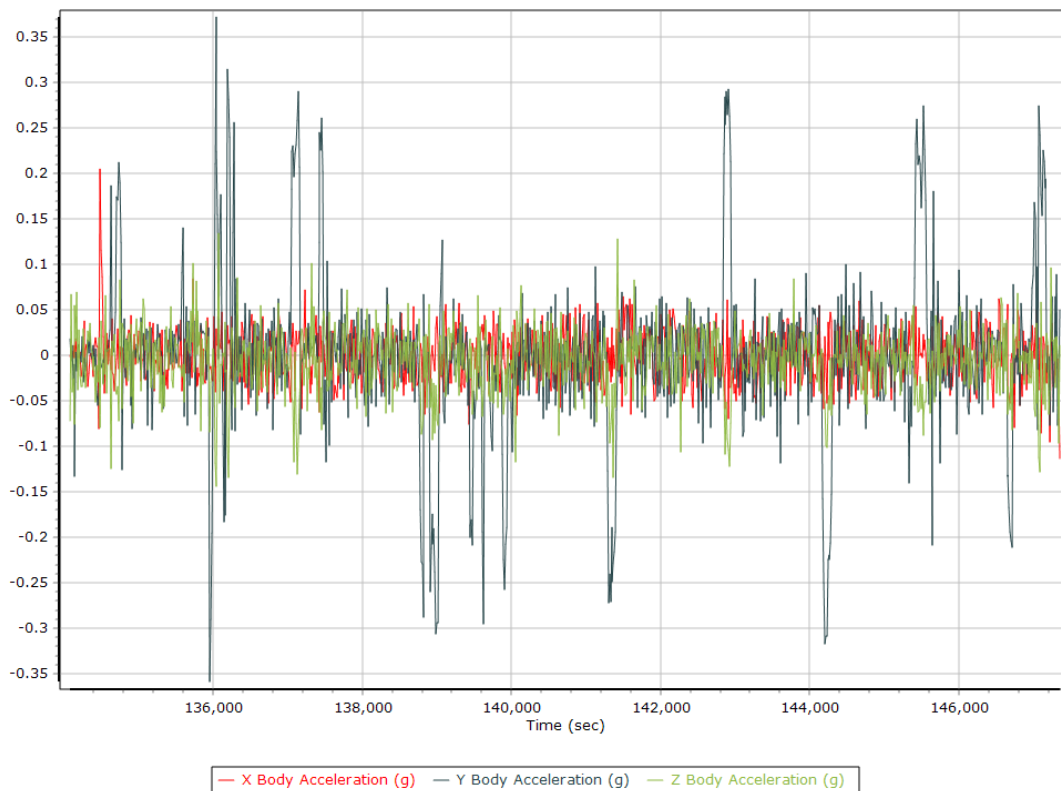
Total Speed



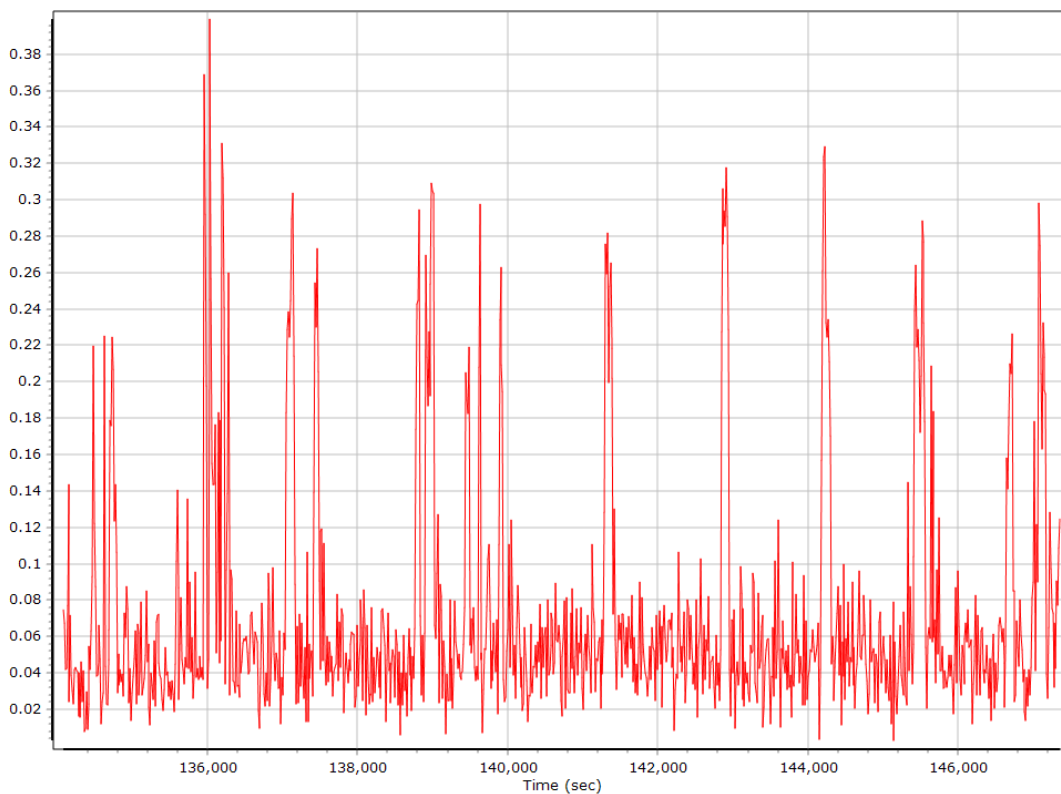
Ground Speed



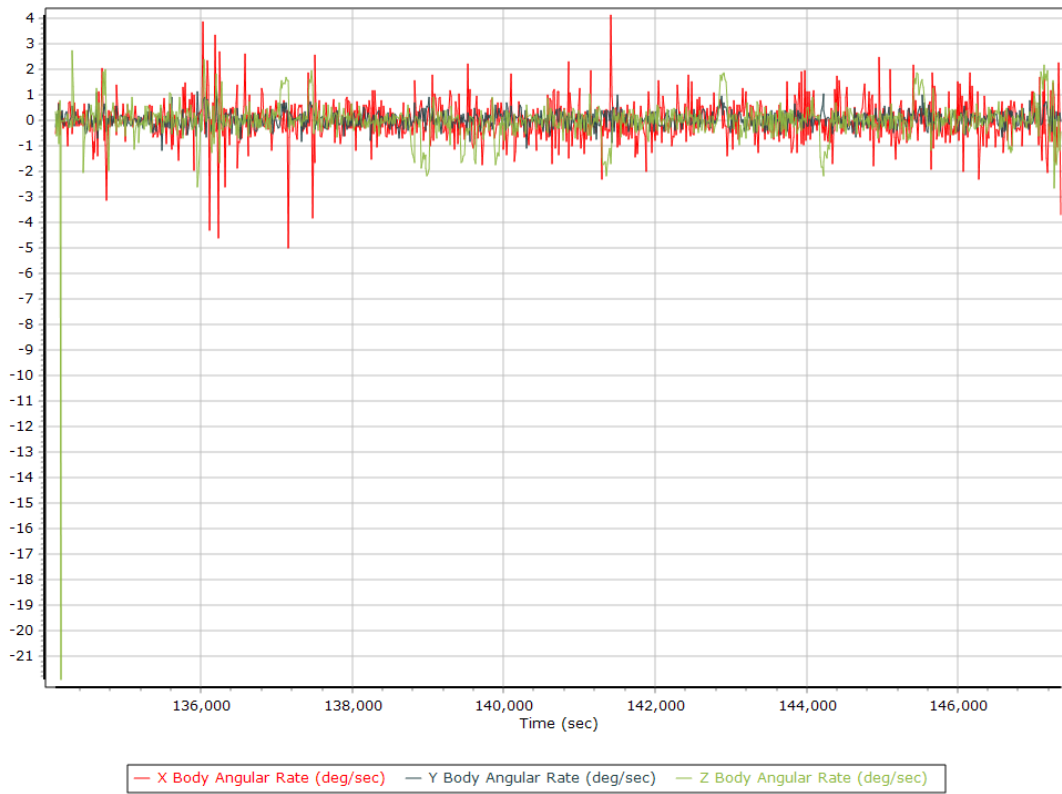
Body Acceleration



Total Body Acceleration



Body Angular Rate

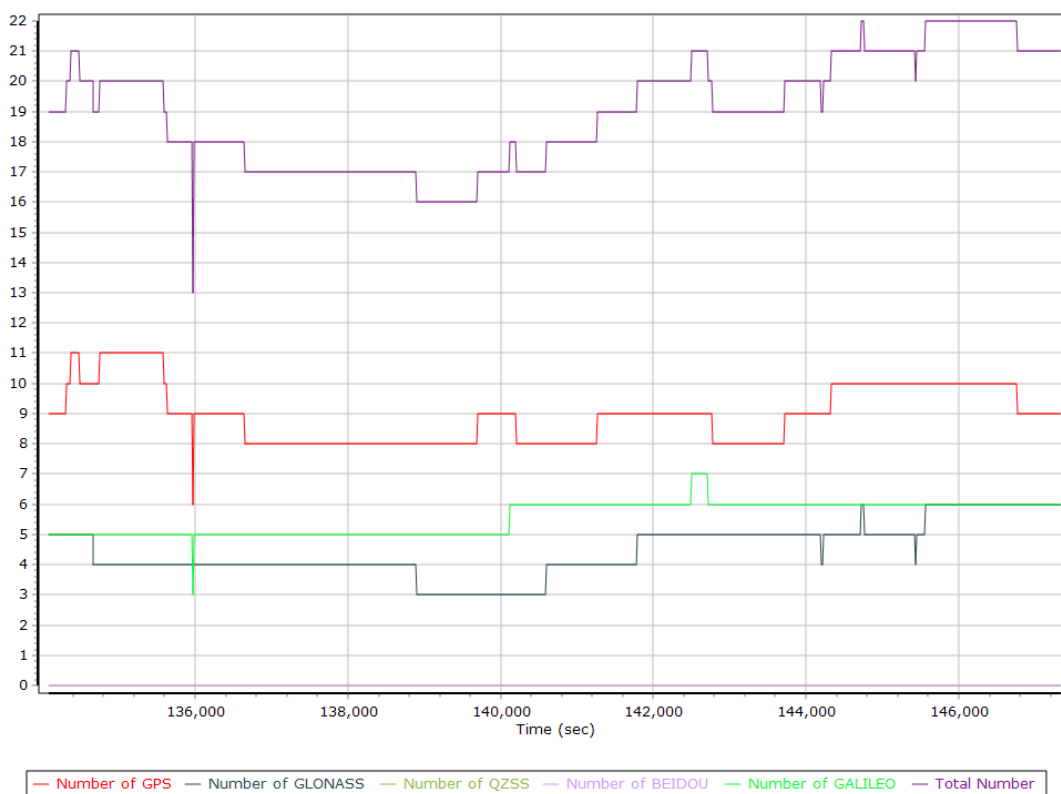


GNSS QC

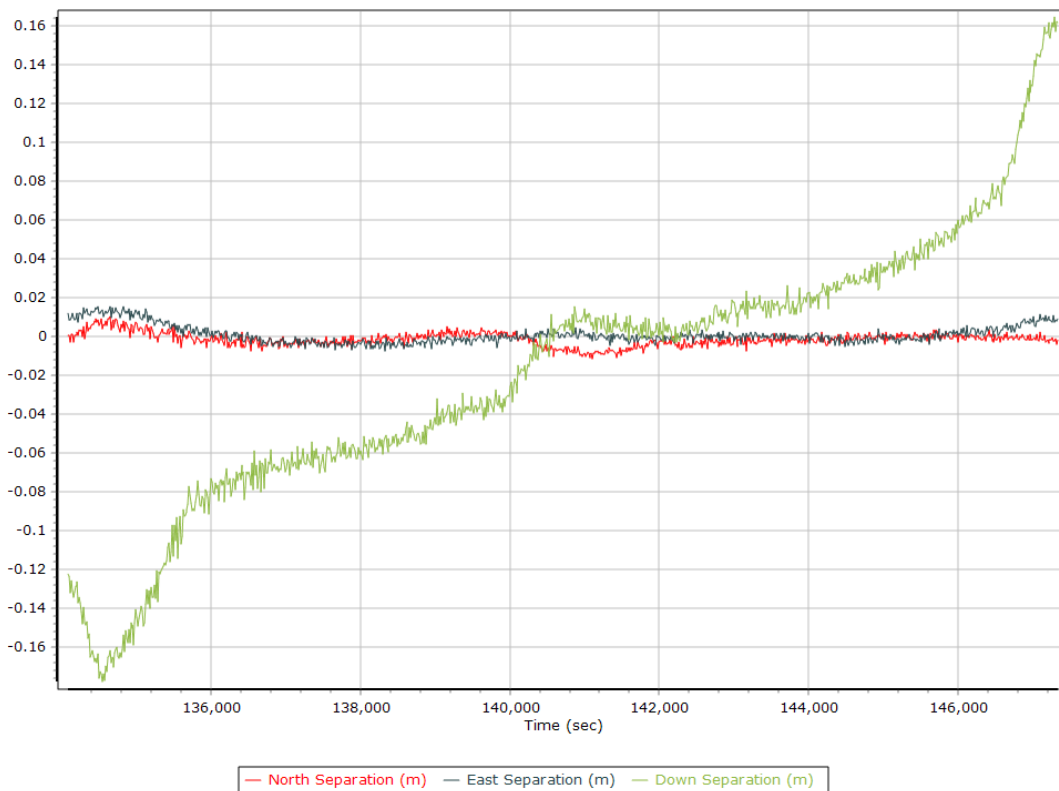
GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	2	11	9
Number of GLONASS SV	3	6	4
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	0	0
Number of GALILEO SV	3	7	6
Total number of SV	8	22	19
PDOP	0.98	3.72	1.26
QC Solution Gaps	0.00	0.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	13591.00	0.00	0.00
Percentage	100.00	0.00	0.00

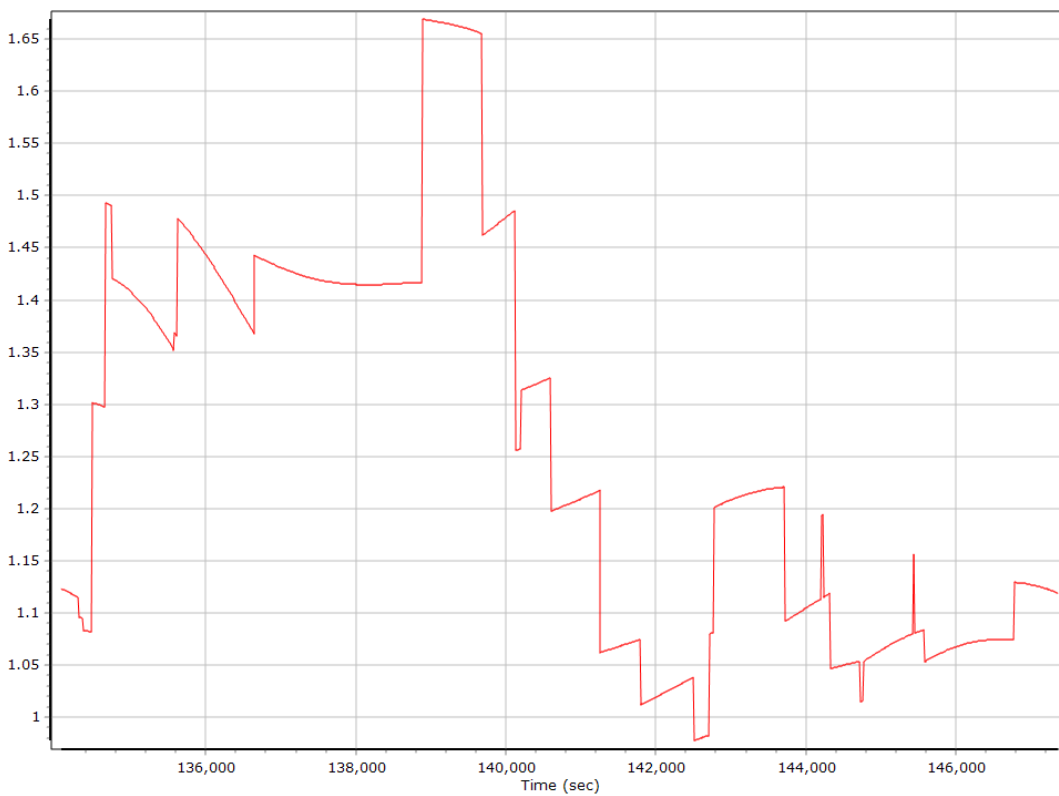
Num SVs in solution



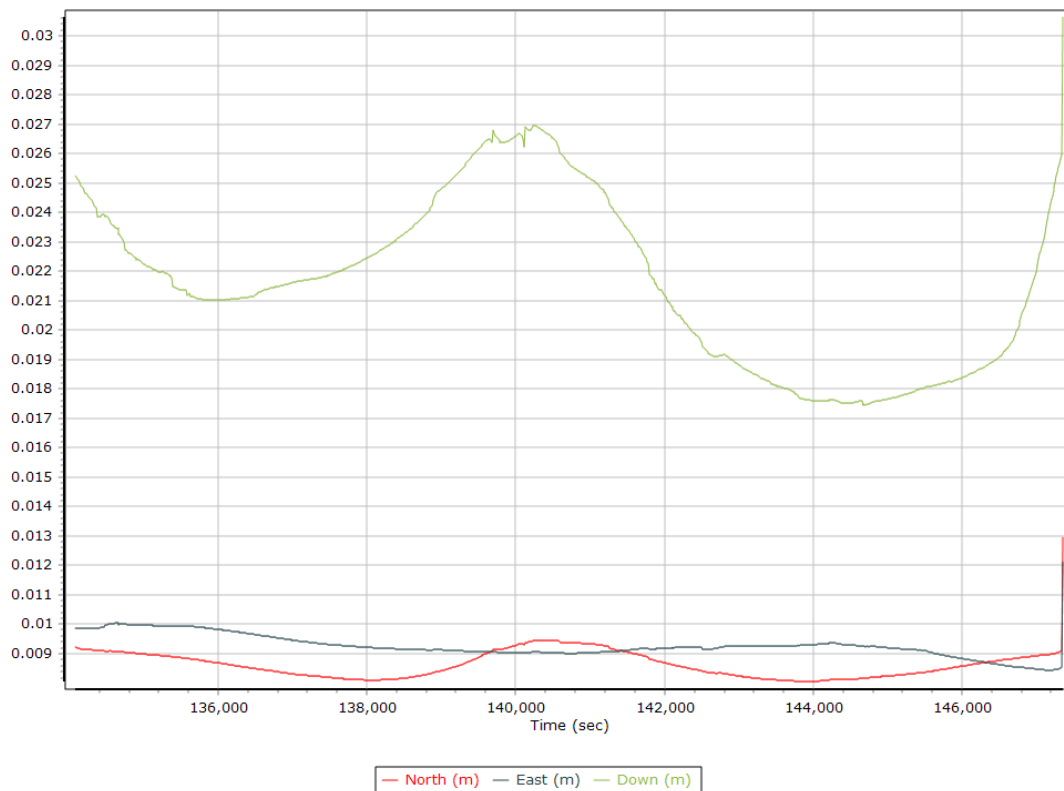
Forward/Reverse Separation



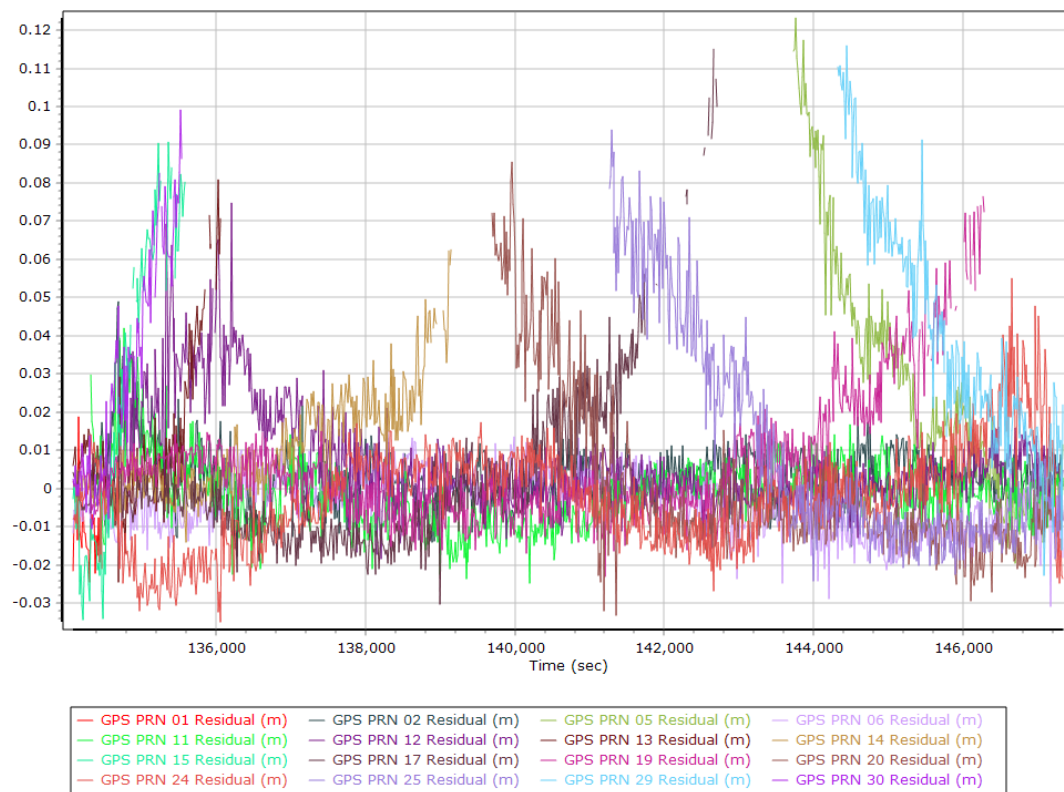
PDOP



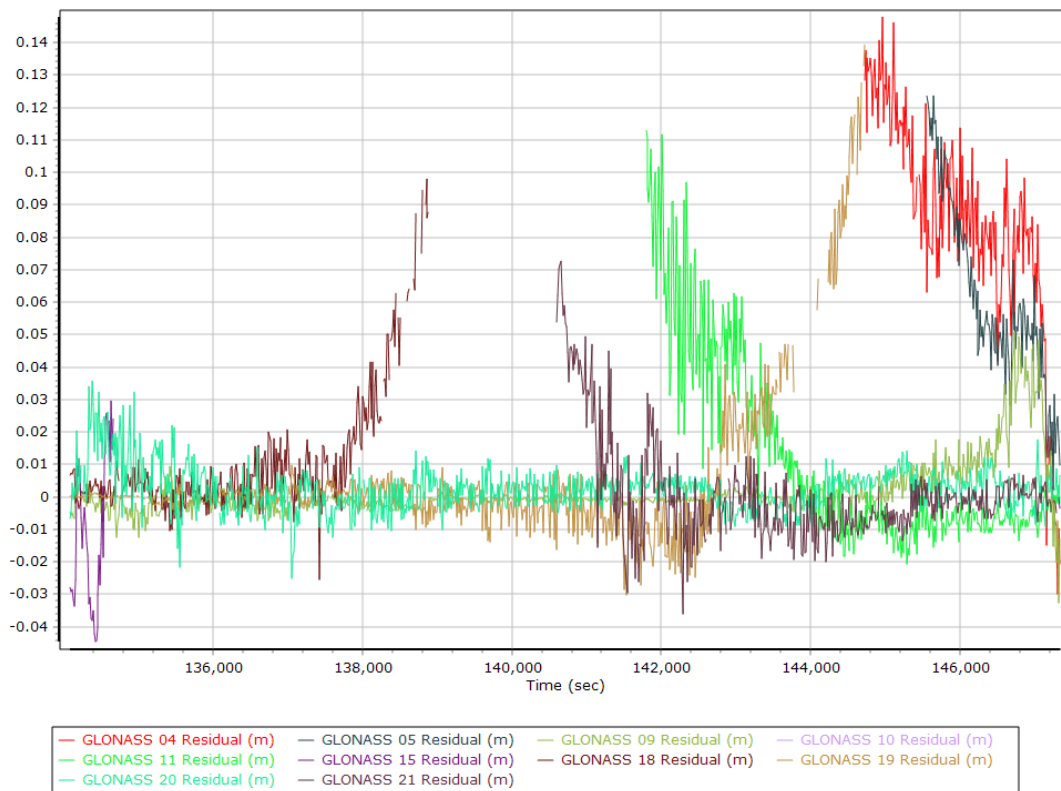
Estimated Position Accuracy



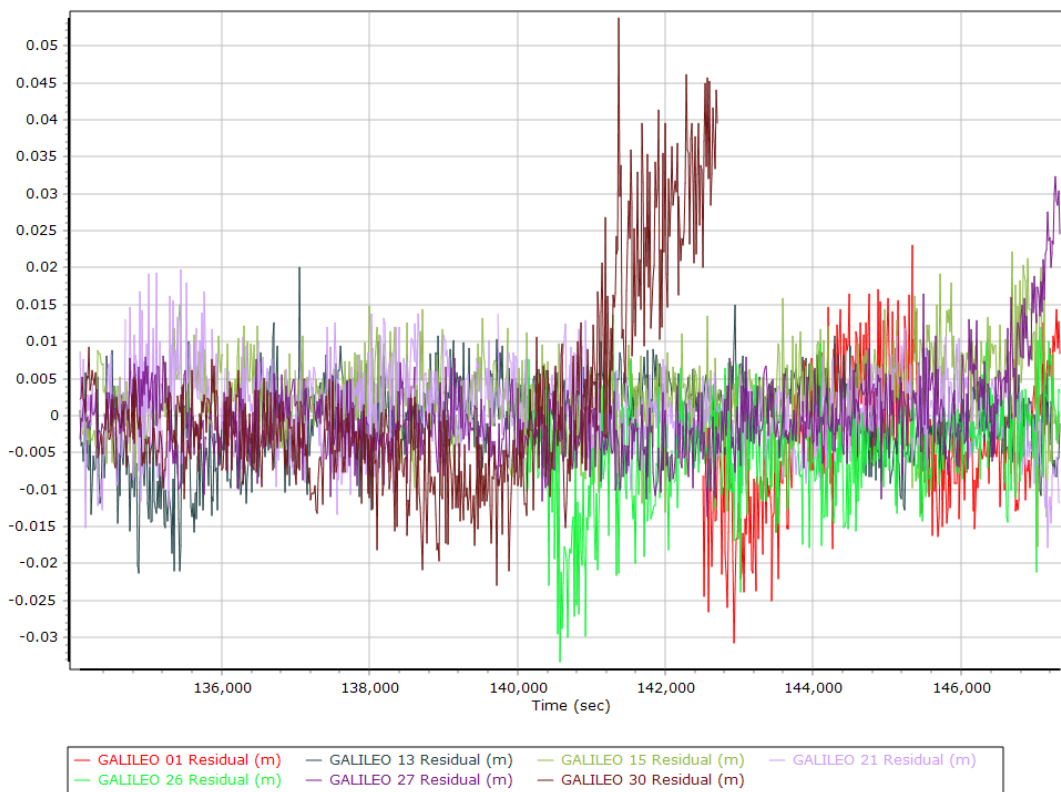
GPS Residuals



GLONASS Residuals



GALILEO Residuals



GNSS-Inertial Processor Configuration

Processing mode	IN-Fusion PP-RTX		
Stabilized mount	False		
Processing start time	133743.000 (07/11/2022 13:09:03)		
Processing end time	147366.000 (07/11/2022 16:56:06)		
Initial attitude source	Real-Time VNAV/RNAV Attitude		
IMU Sensor Context	Processing with Onboard IMU		
Reference to IMU lever arm (m)	0.000	0.000	0.000
Reference to IMU mounting angles (deg)	0.000	0.000	180.000
Reference to Primary GNSS lever arm (m)	0.391	-0.429	-1.092
Reference to Primary GNSS lever arm std dev (m)	0.030	0.030	0.030
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

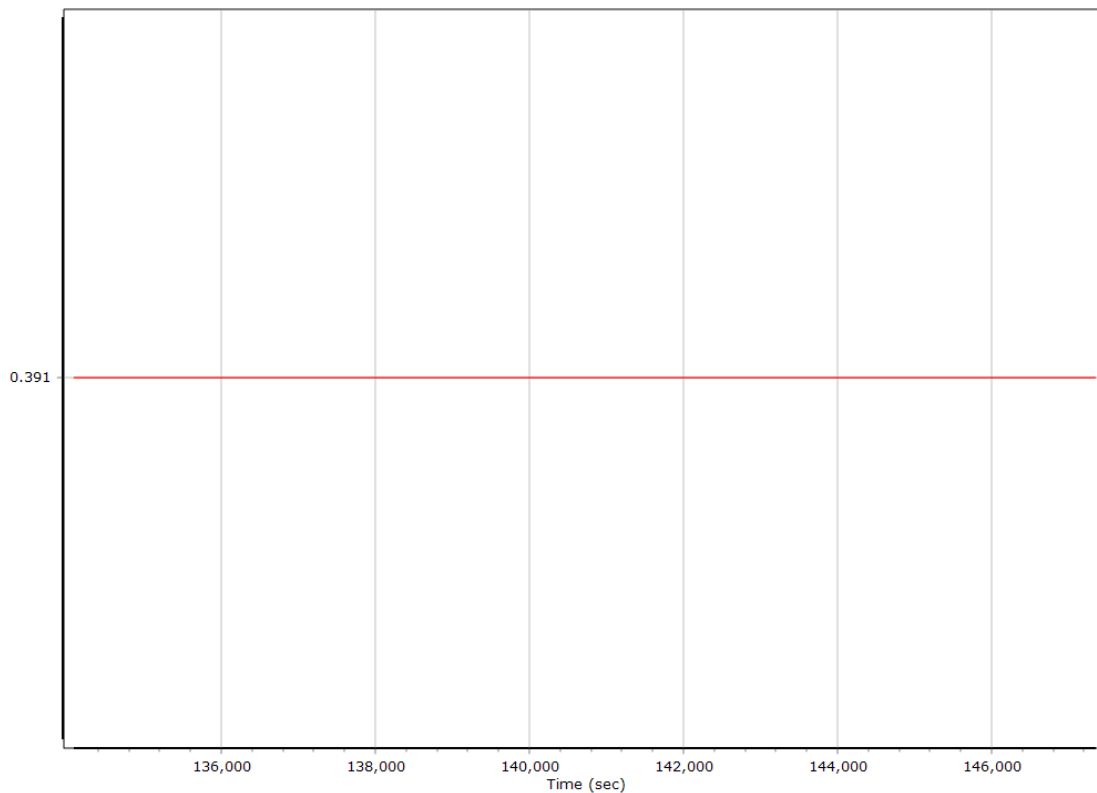
Calibrated Installation Parameters

Reference-Primary GNSS Lever Arm (m)

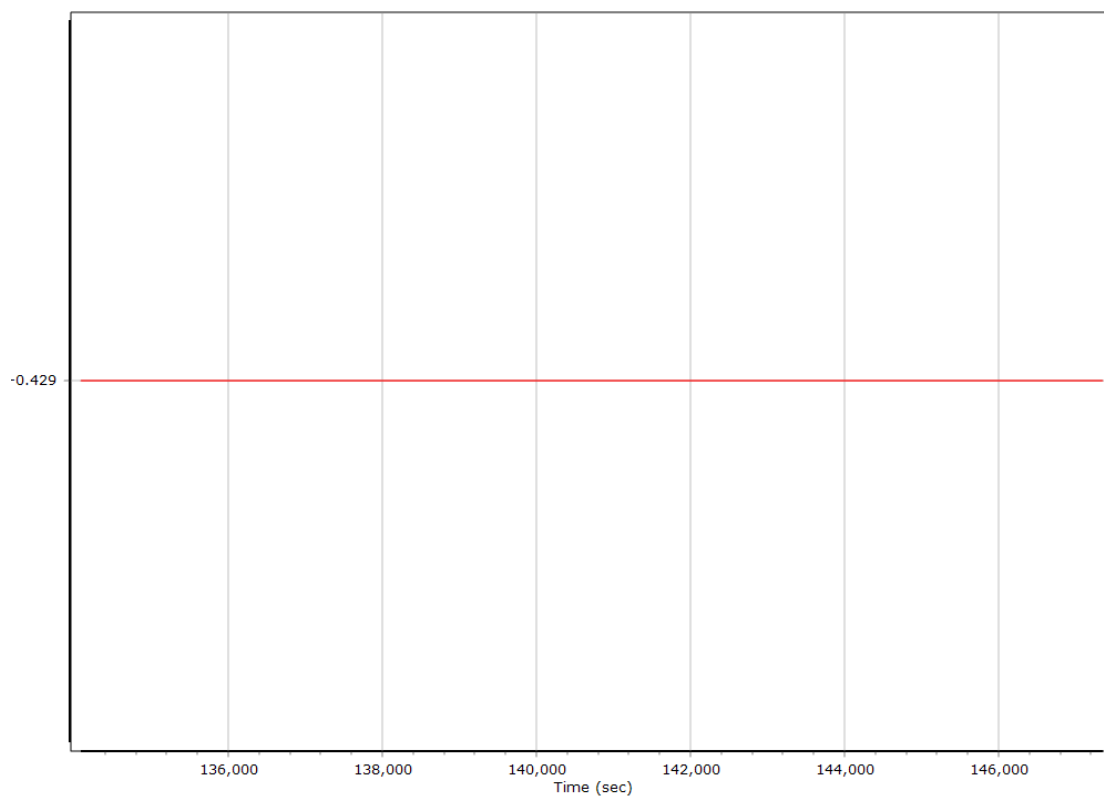
Reference-Primary GNSS Lever Arm Automatic Calibration Results

Original Reference to Primary GNSS lever arm (m)	0.361	-0.429	-0.945
Iteration 1 Reference to Primary GNSS lever arm (m)	0.390	-0.428	-1.090
Iteration 2 Reference to Primary GNSS lever arm (m)	0.391	-0.429	-1.092
Primary GNSS Lever Arm In use	Iteration 2		

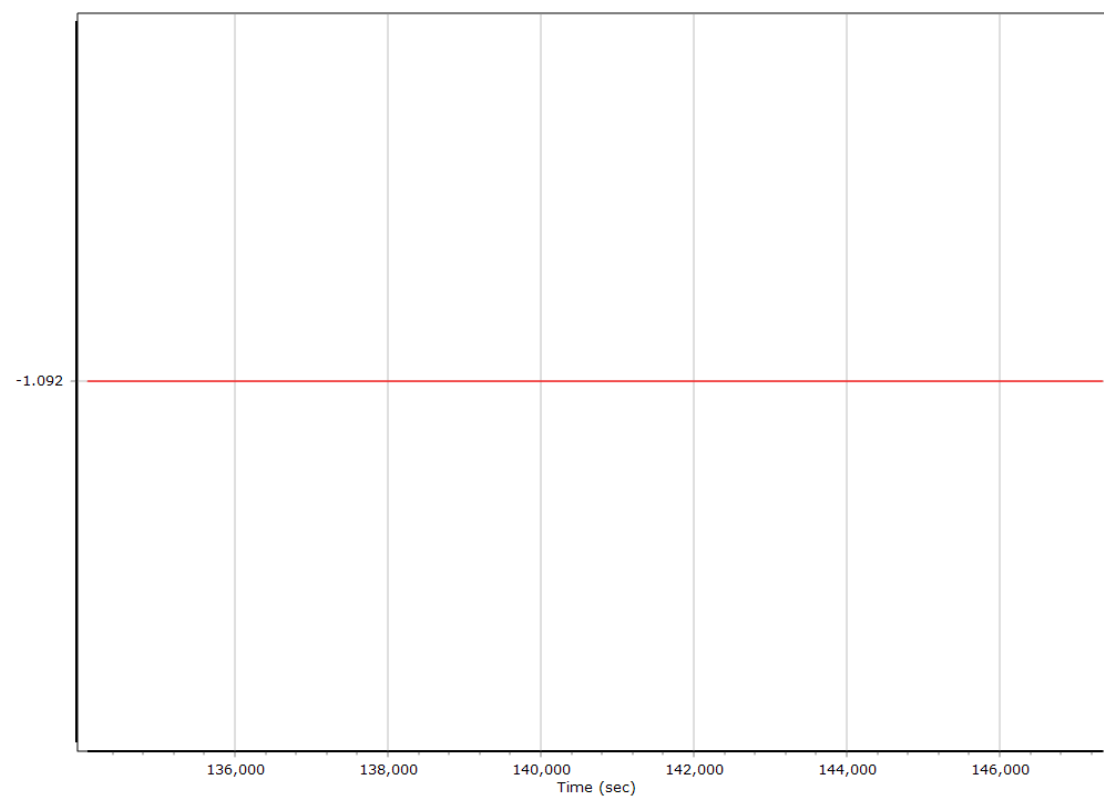
X Reference-Primary GNSS Lever Arm (m)



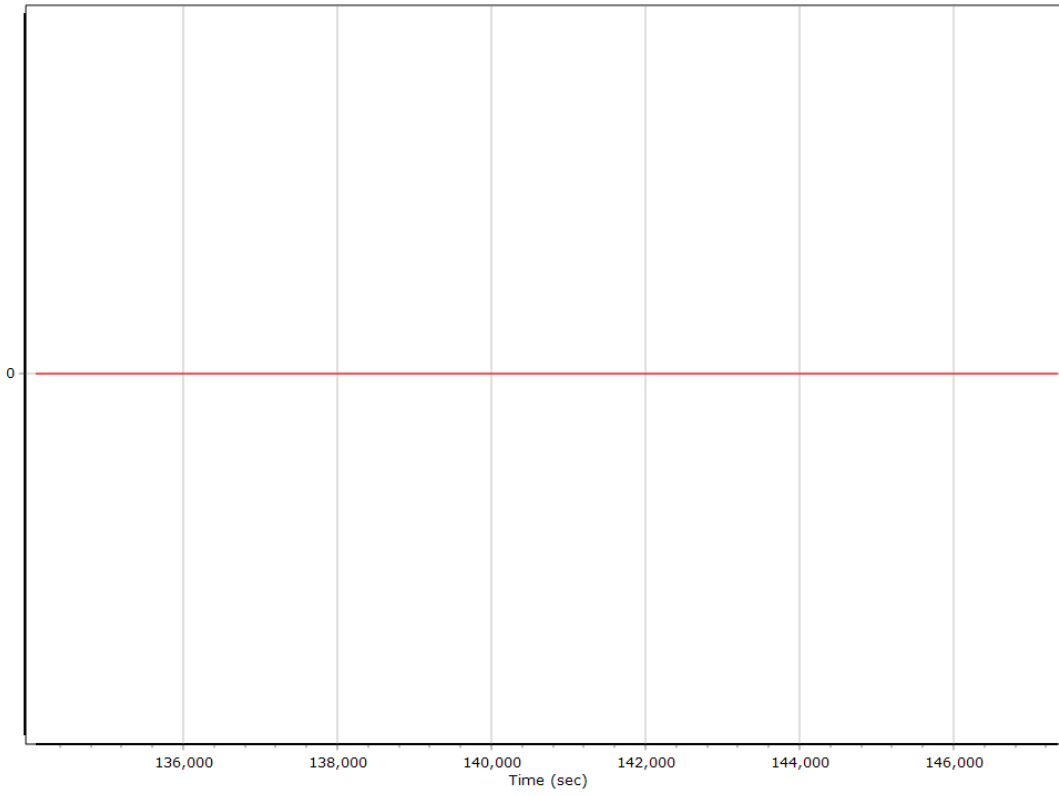
Y Reference-Primary GNSS Lever Arm (m)



Z Reference-Primary GNSS Lever Arm (m)



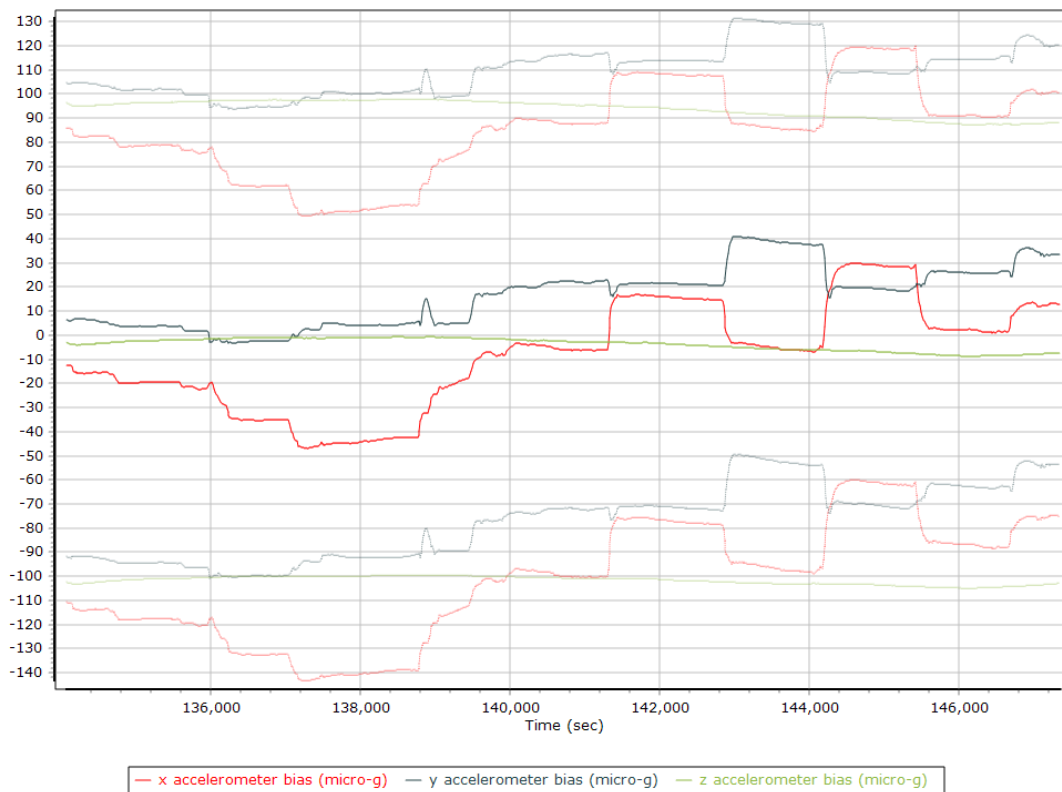
Reference-Primary GNSS Lever Arm Figure of Merit



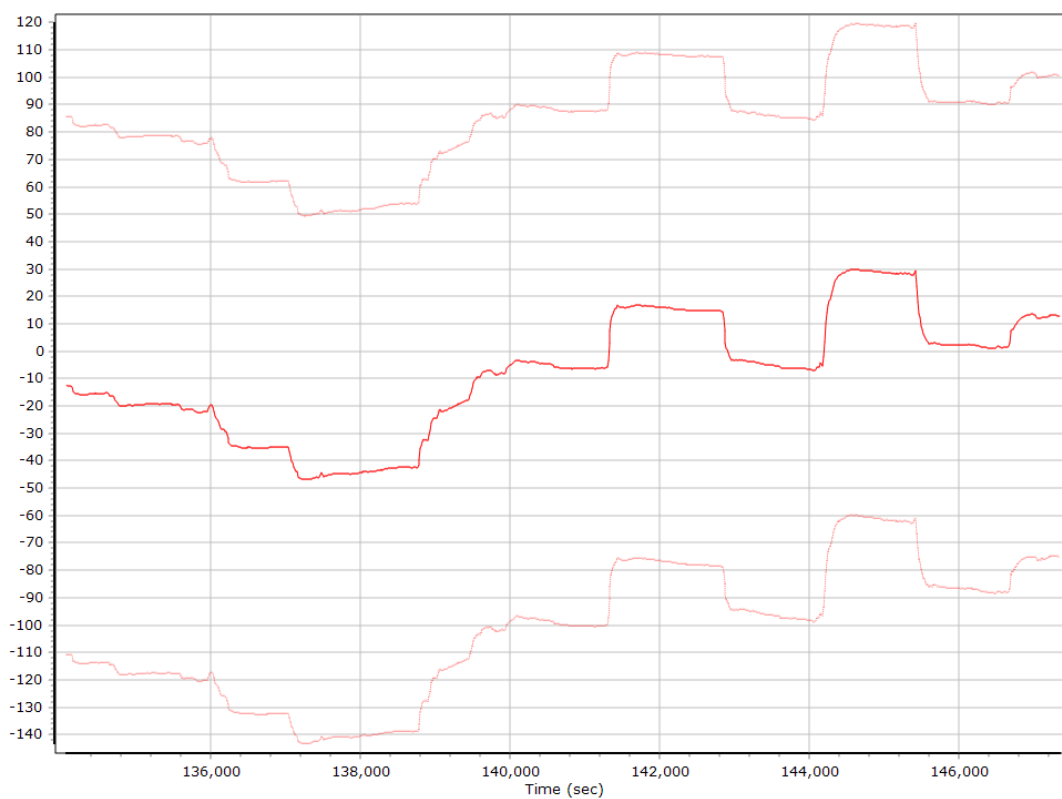
IN-Fusion QC

Forward Processed Estimated Errors, Reference Frame

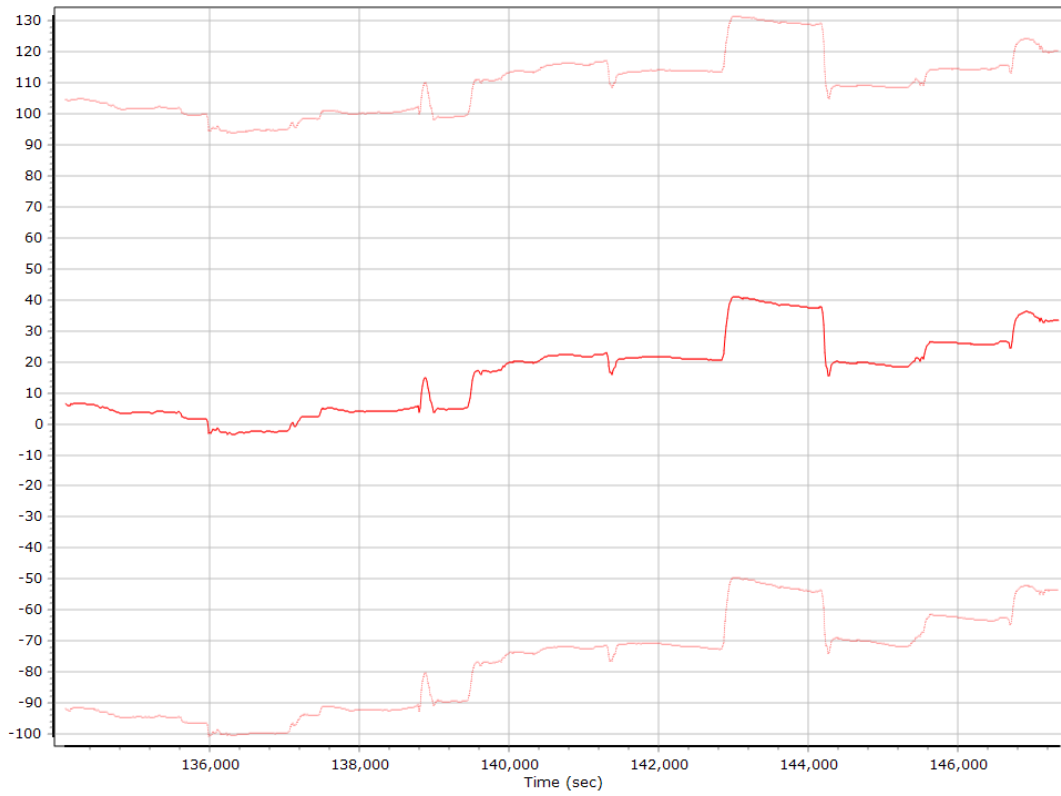
Accelerometer Bias (micro-g)



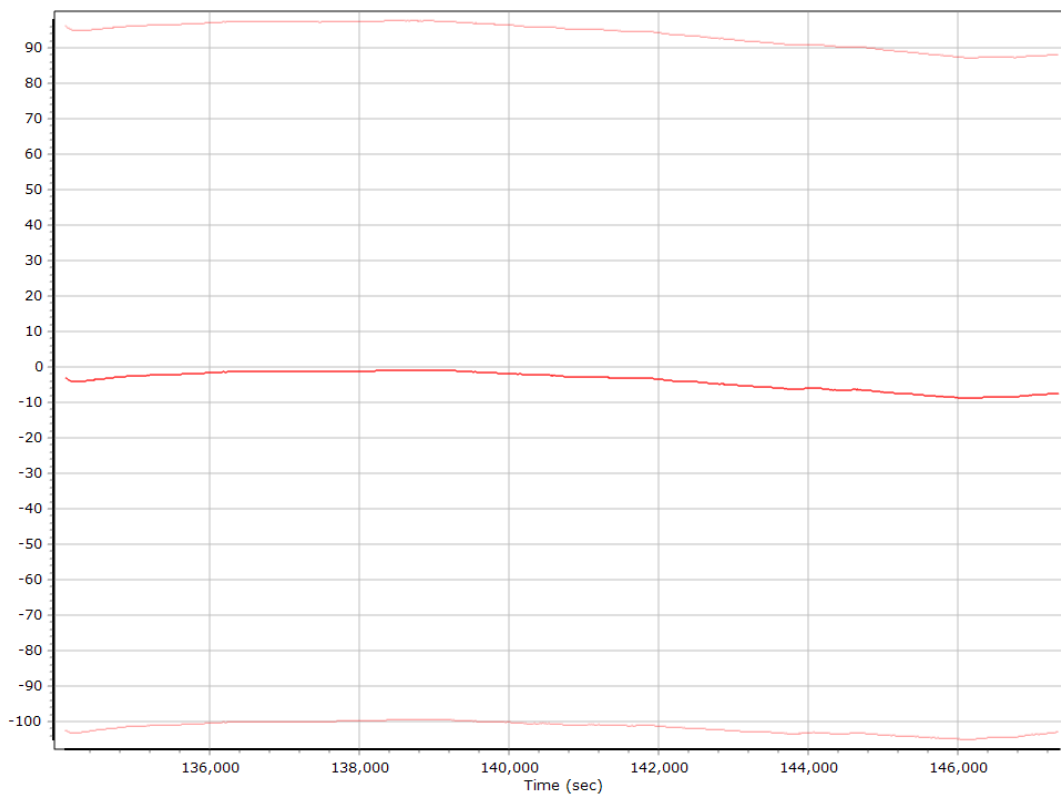
X Accelerometer Bias (micro-g)



Y Accelerometer Bias (micro-g)



Z Accelerometer Bias (micro-g)



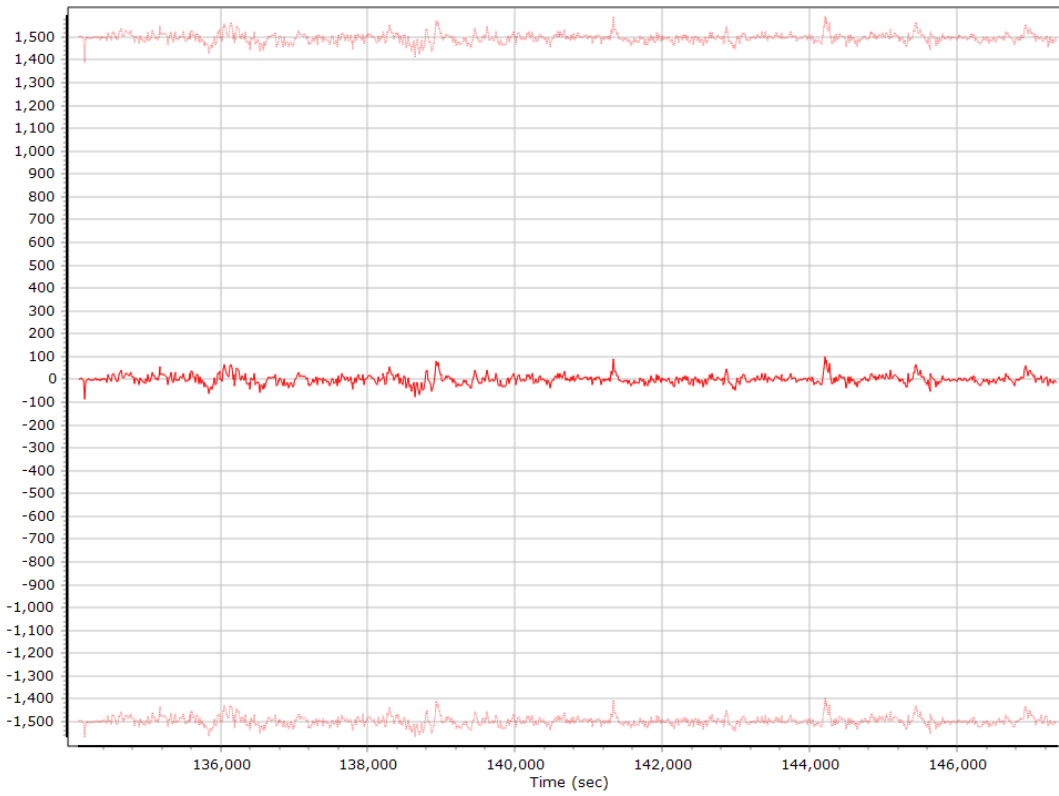
Accelerometer Scale Error (ppm)



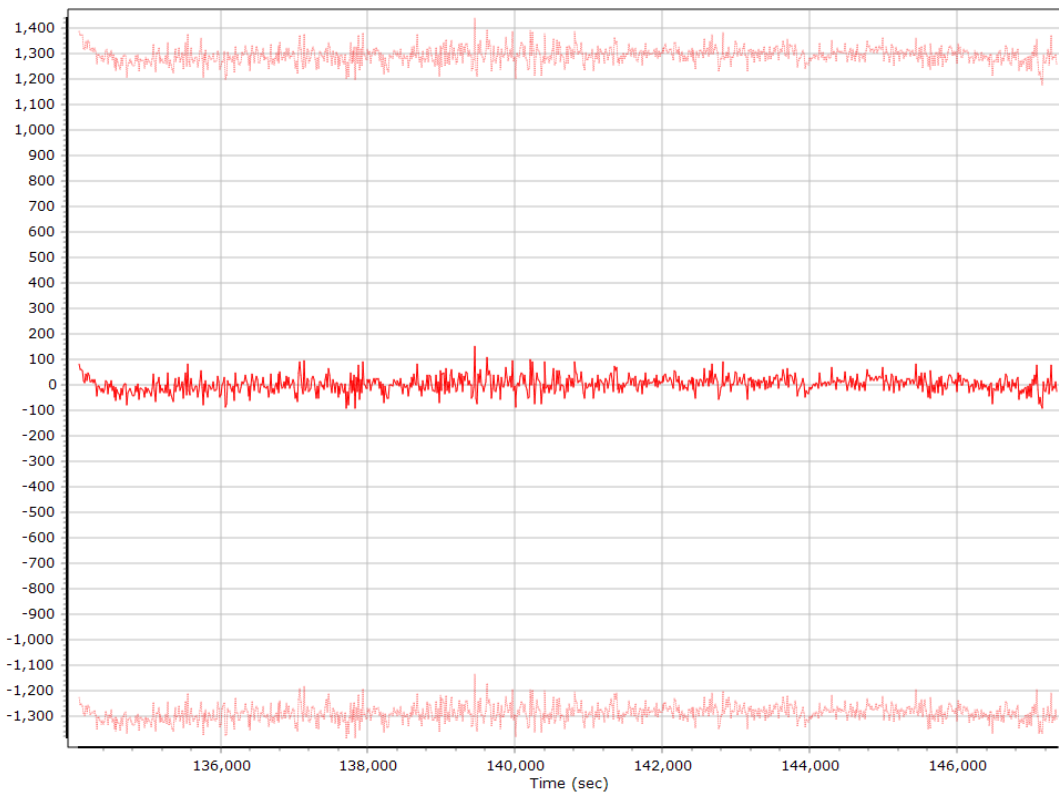
X Accelerometer Scale Error (ppm)



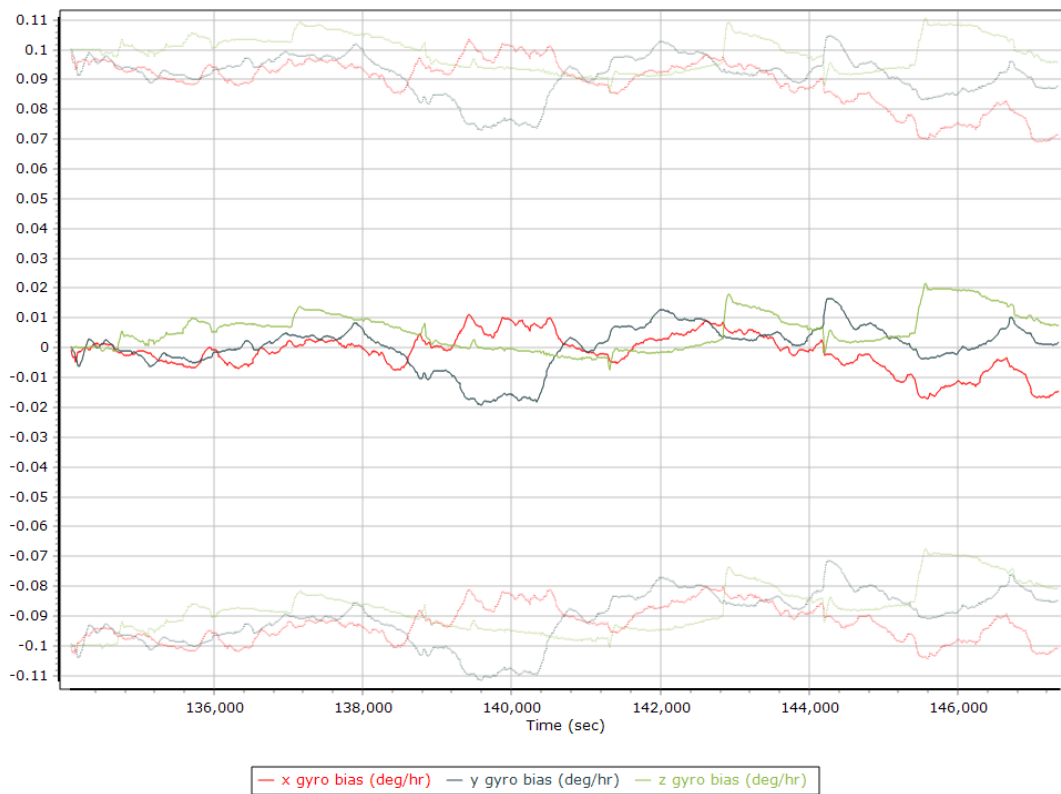
Y Accelerometer Scale Error (ppm)



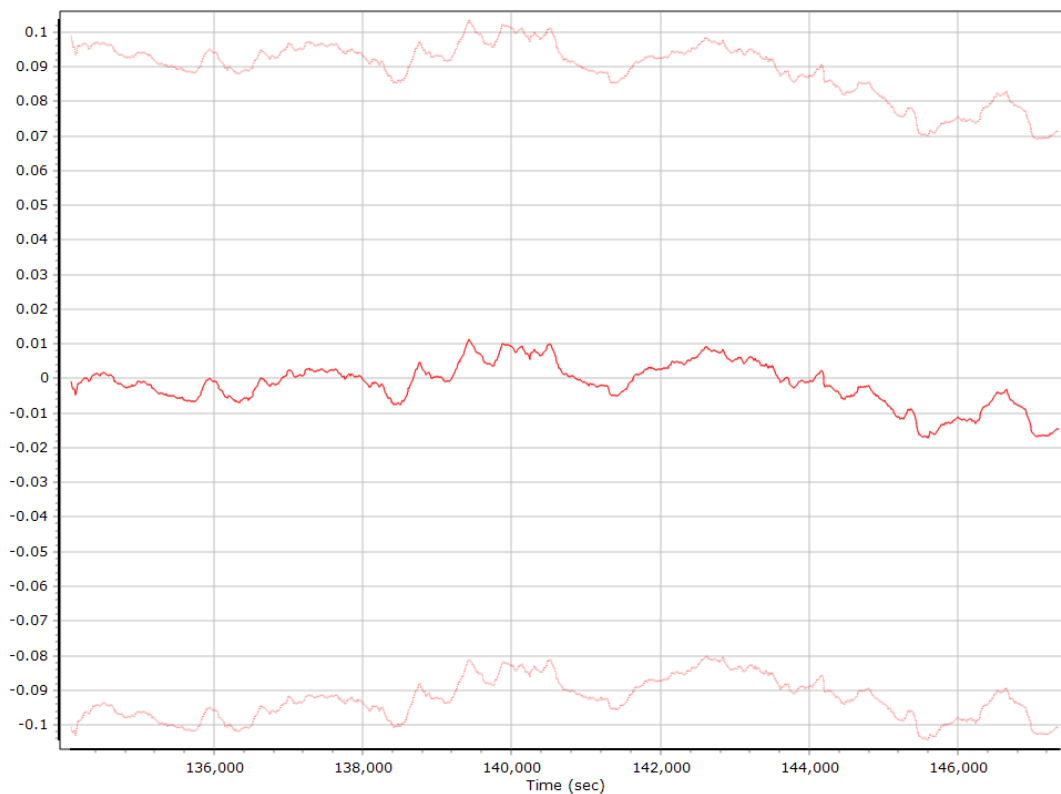
Z Accelerometer Scale Error (ppm)



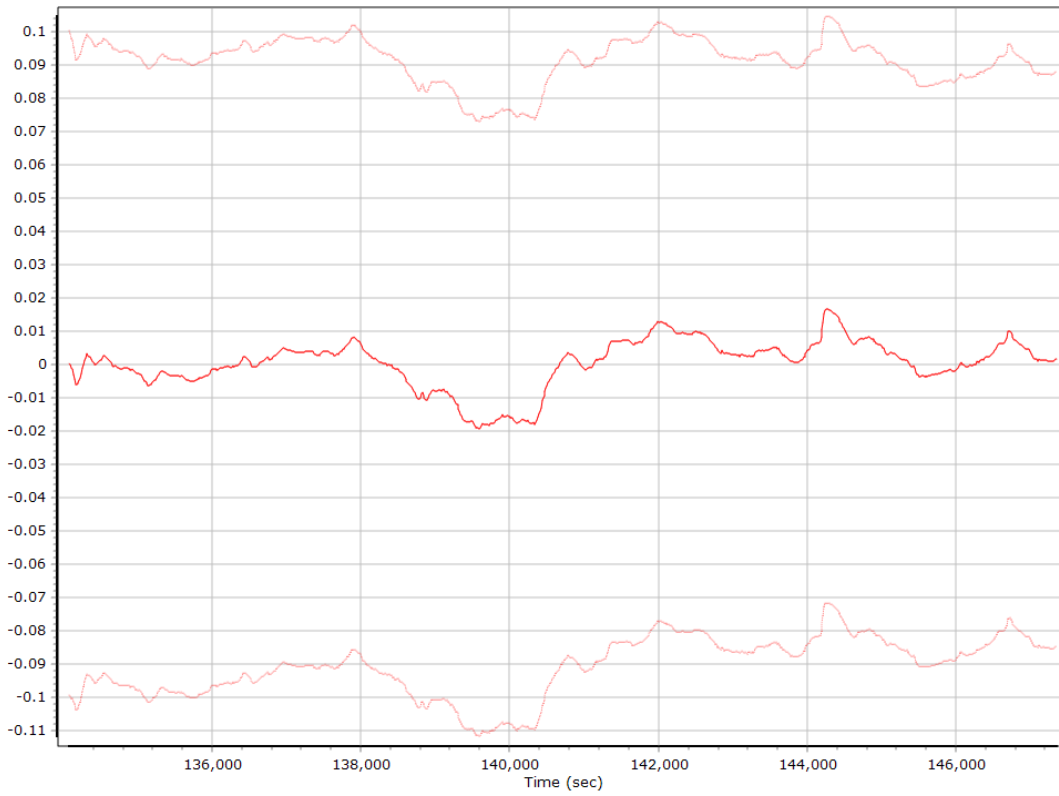
Gyro Bias (deg/h)



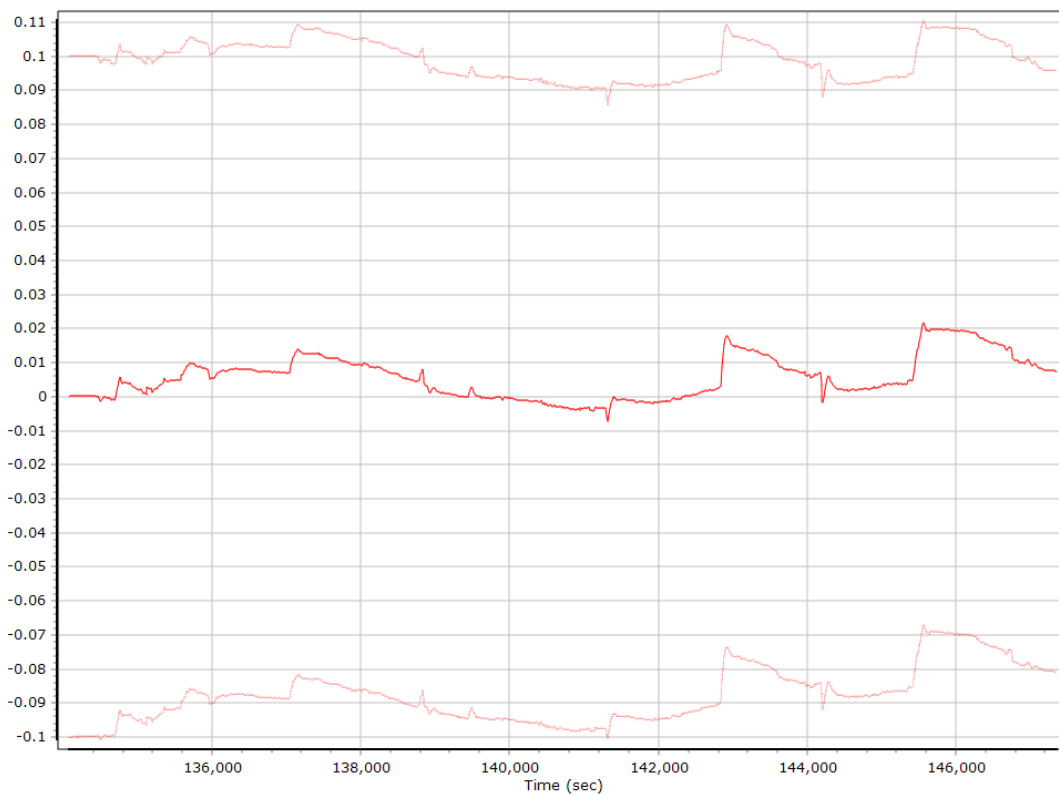
X Gyro Bias (deg/h)



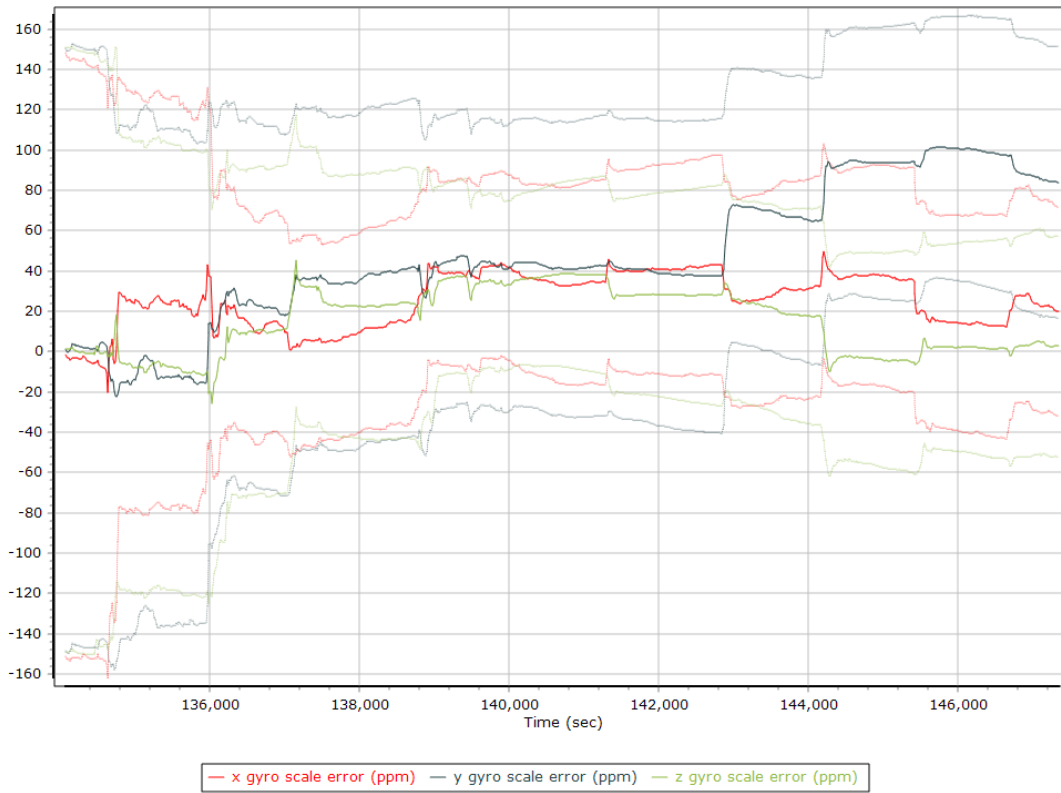
Y Gyro Bias (deg/h)



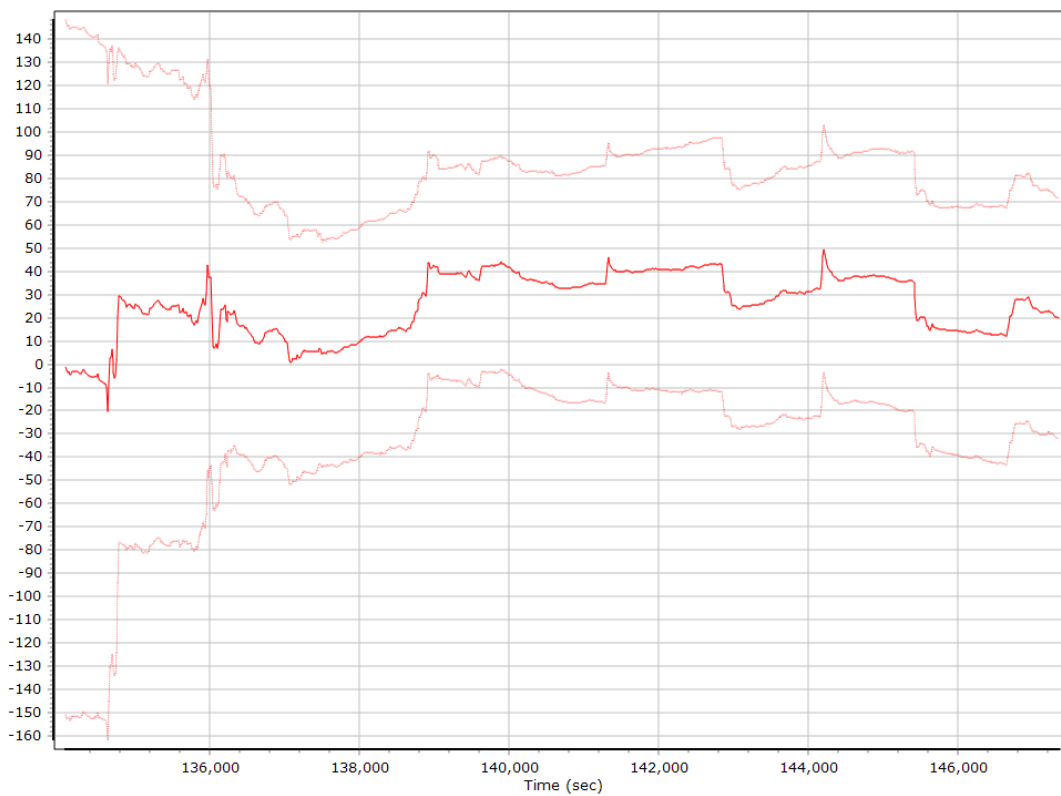
Z Gyro Bias (deg/h)



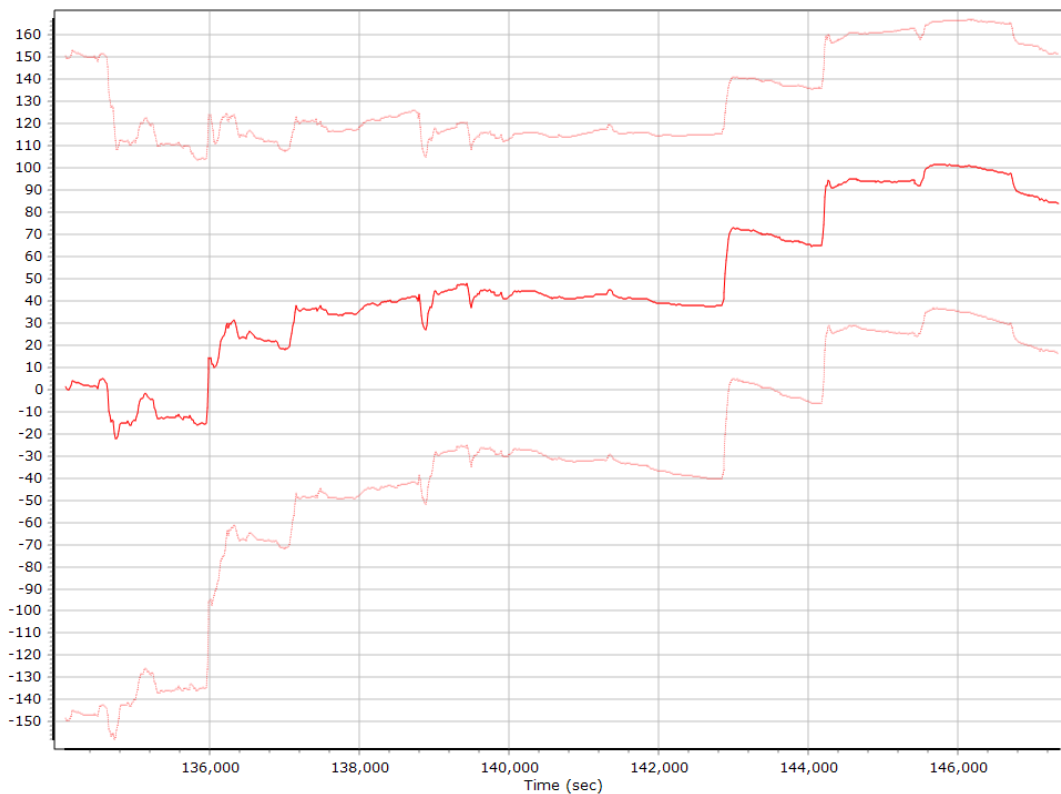
Gyro Scale Error (ppm)



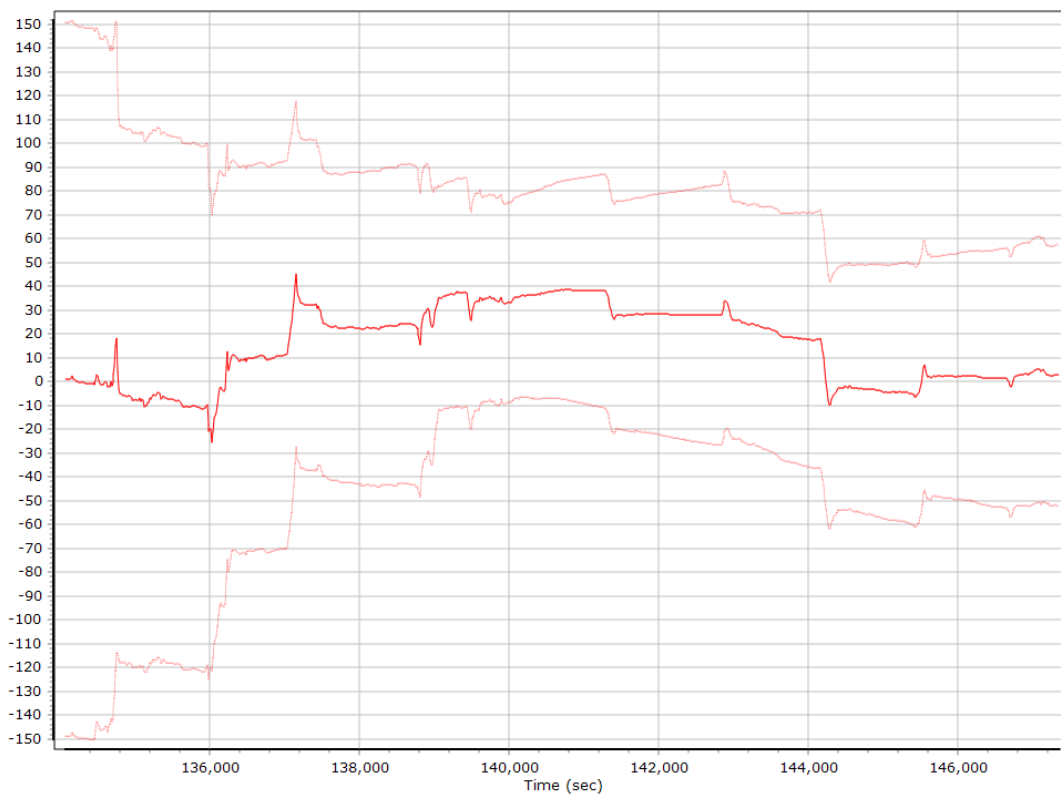
X Gyro Scale Error (ppm)



Y Gyro Scale Error (ppm)

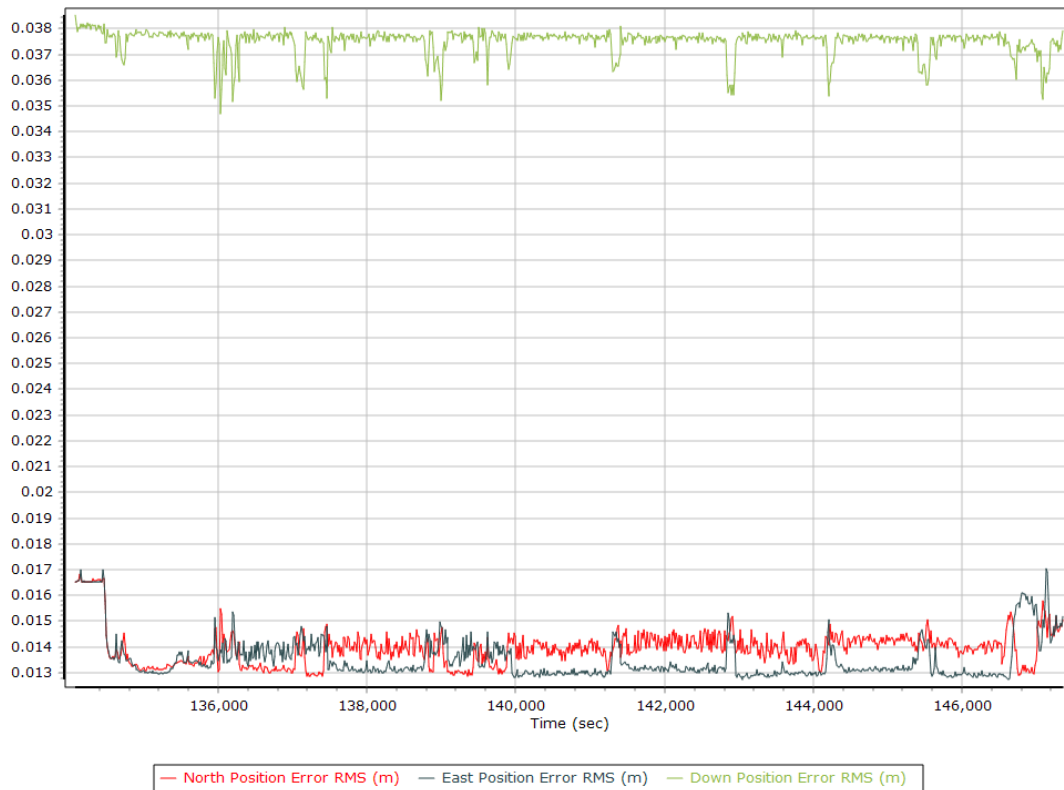


Z Gyro Scale Error (ppm)

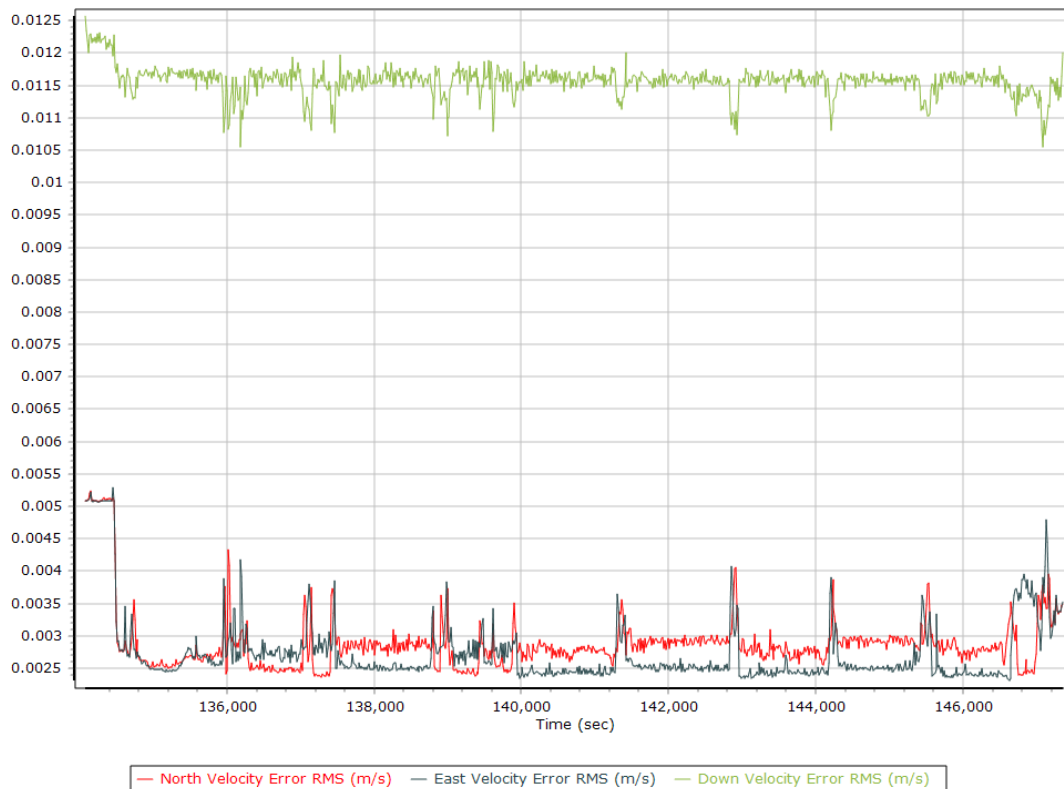


Smoothed Performance Metrics

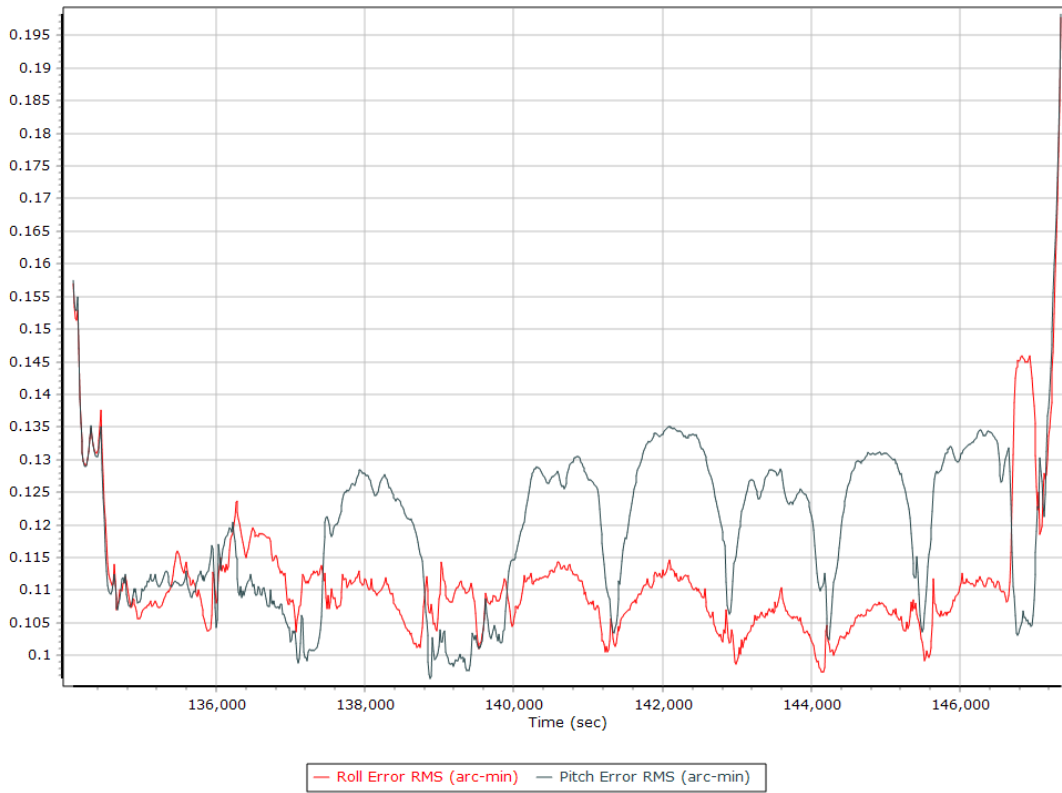
Position Error RMS (m)



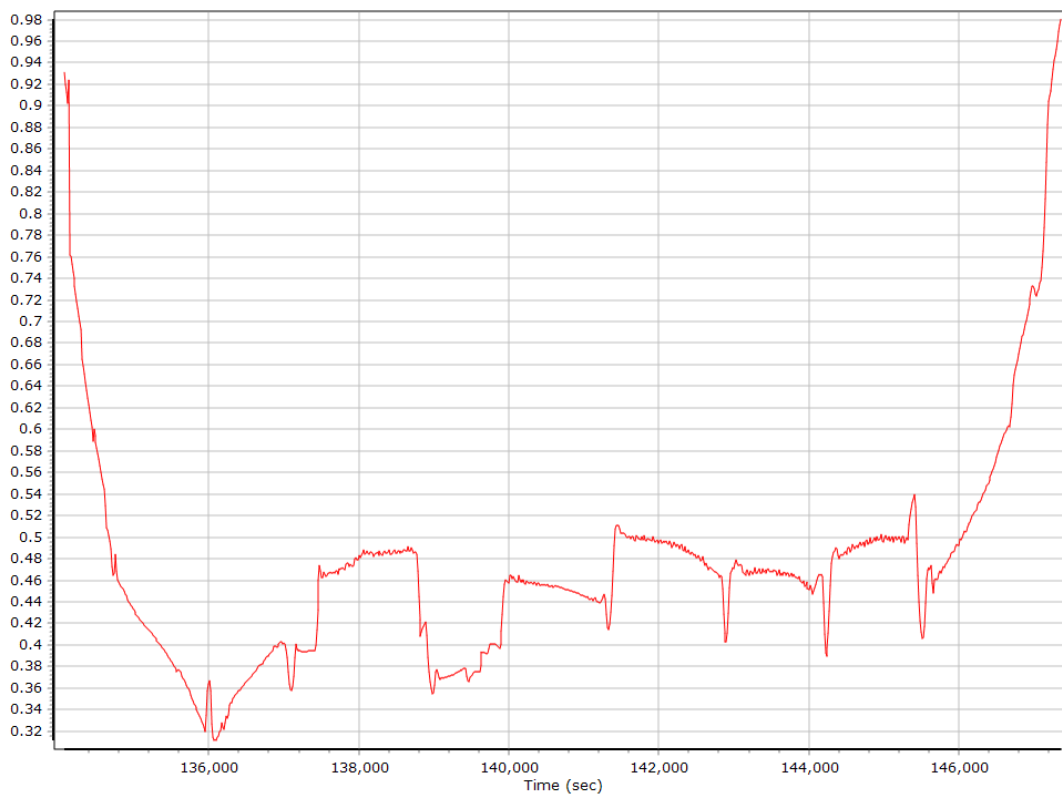
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

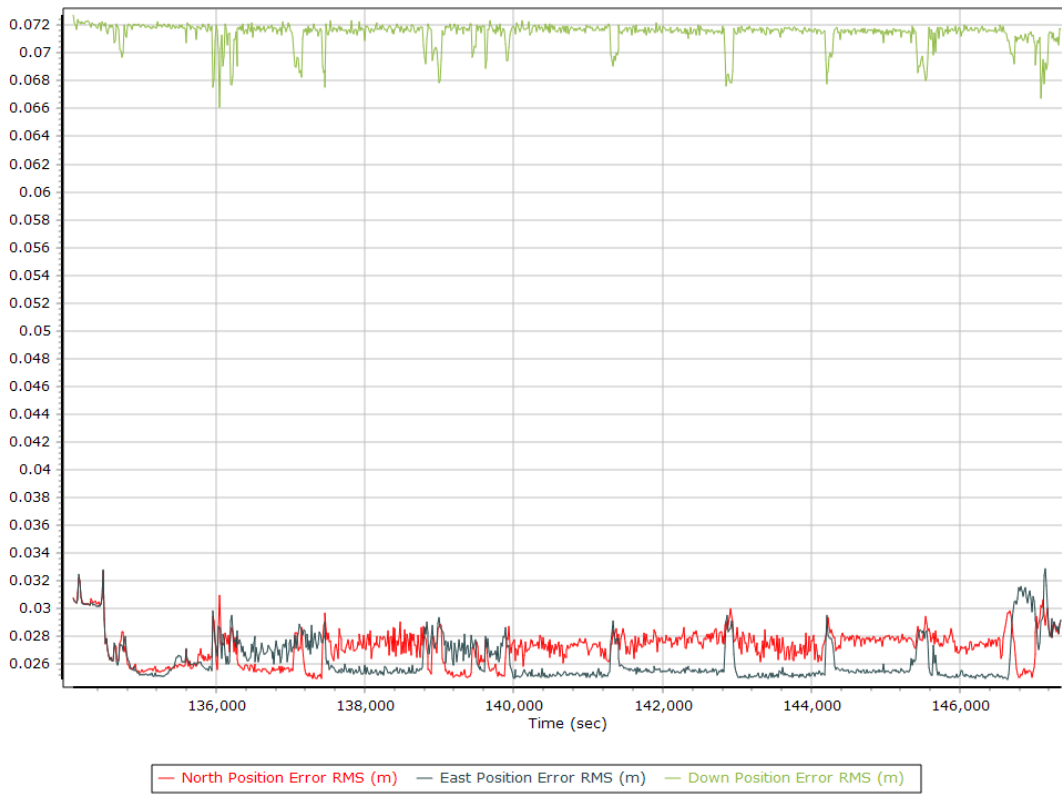


Heading Error RMS (arc-min)

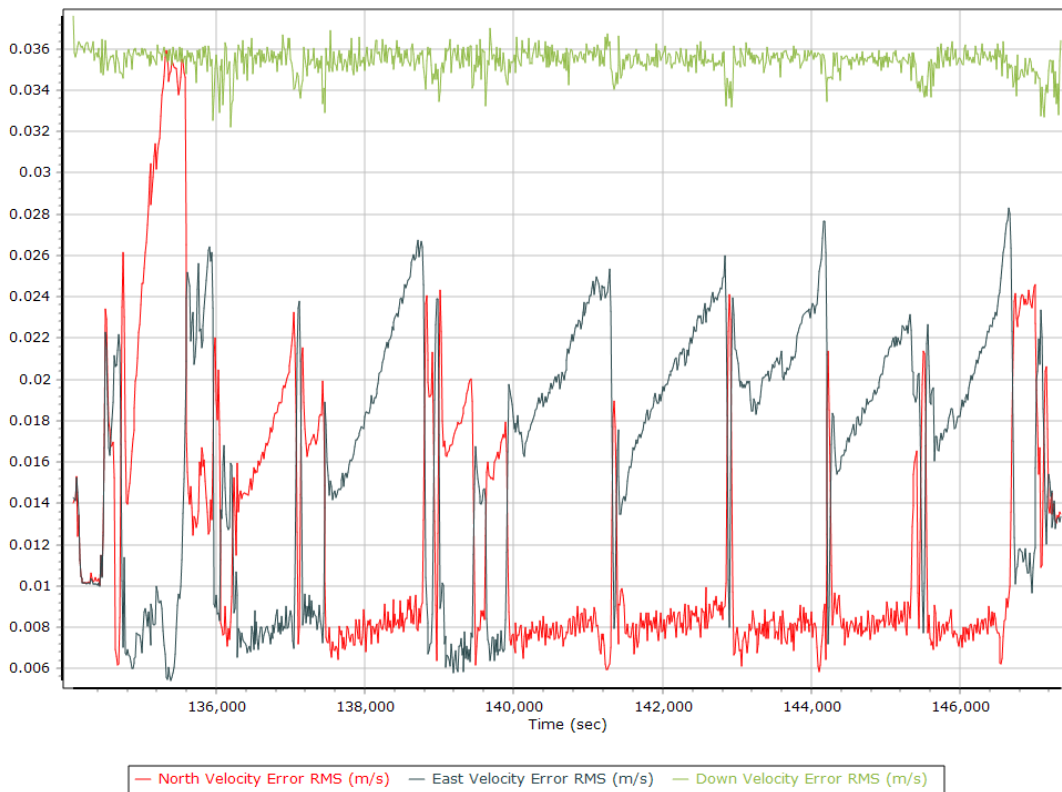


Forward Processed Performance Metrics

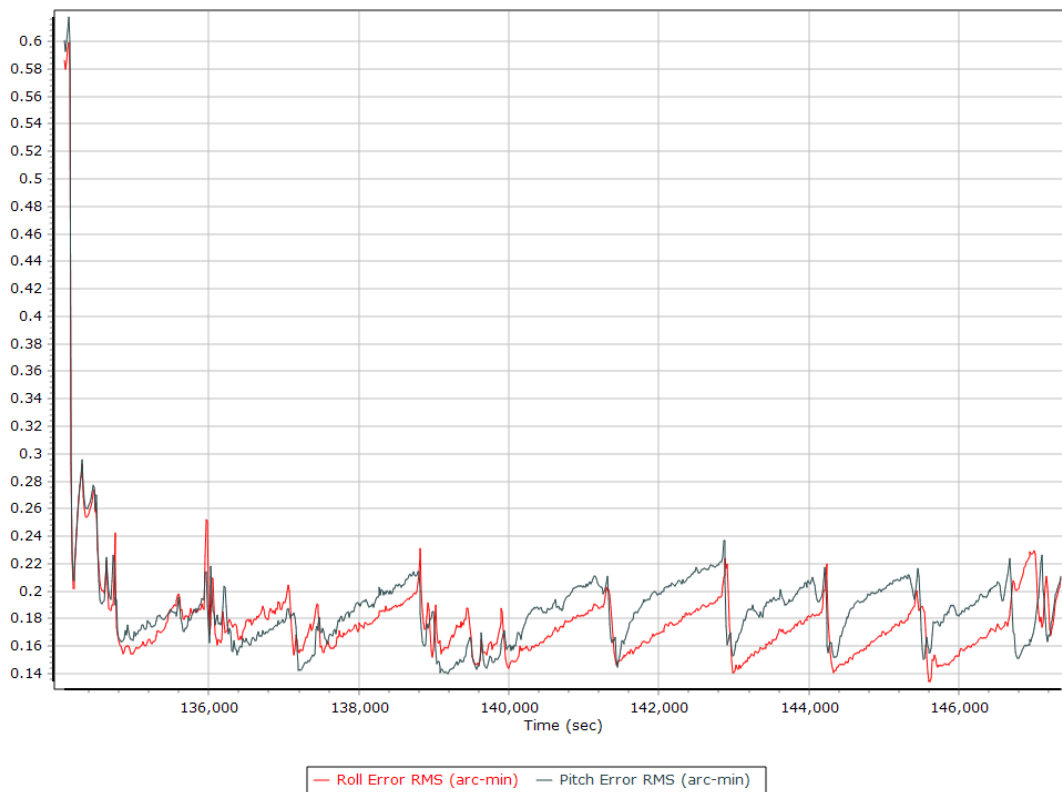
Position Error RMS (m)



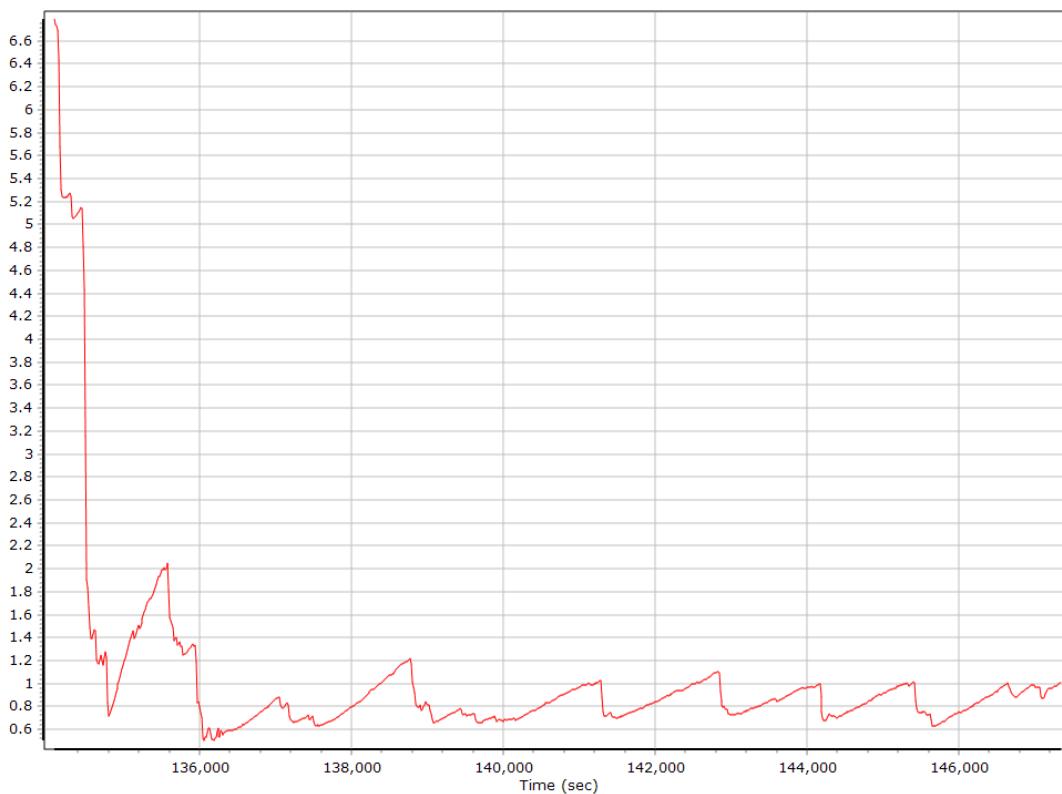
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

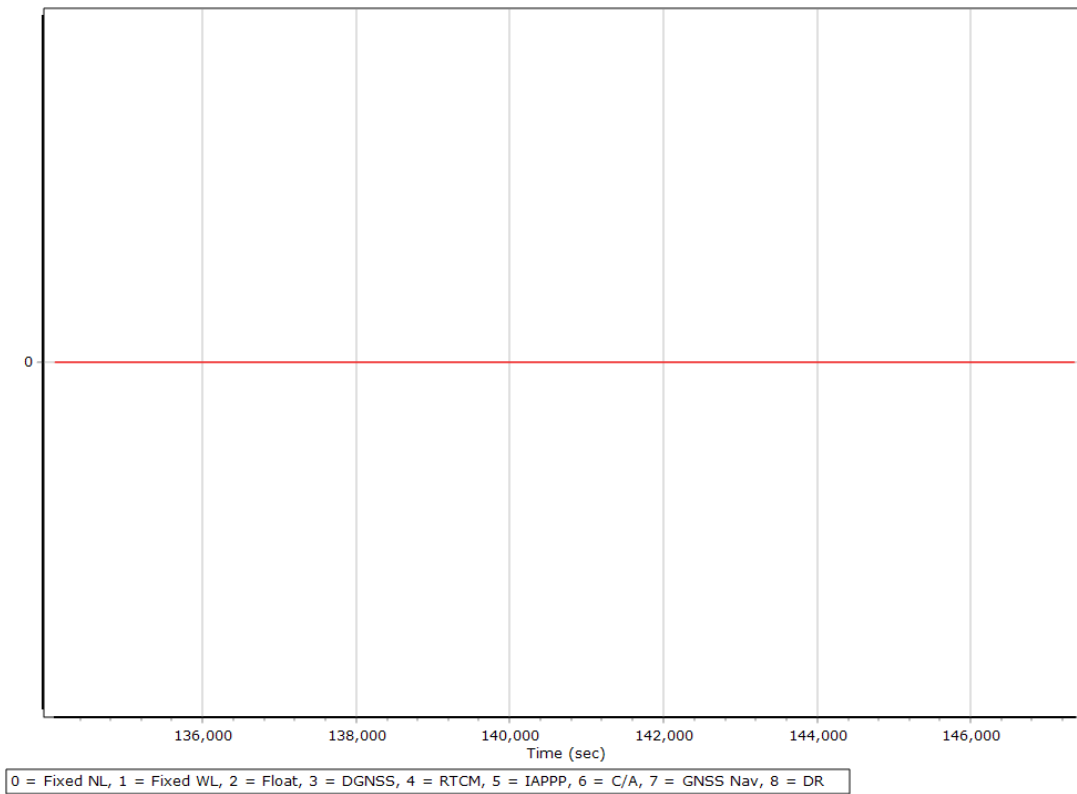


Heading Error RMS (arc-min)

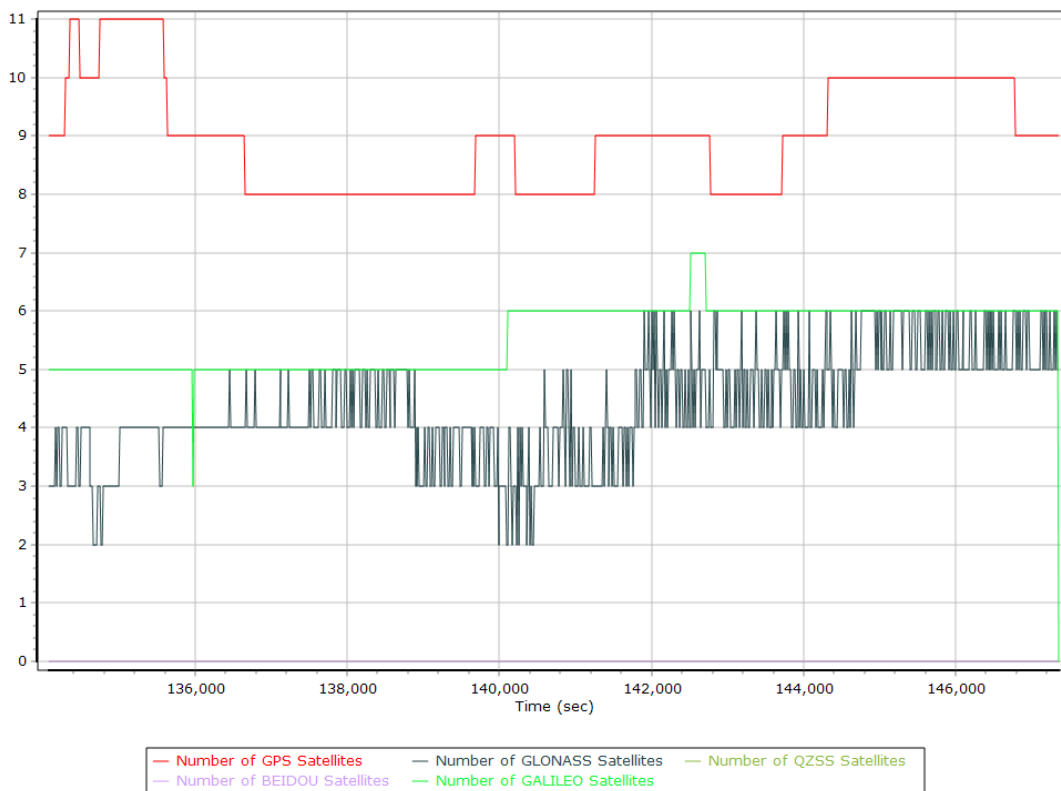


Forward Processed Solution Status

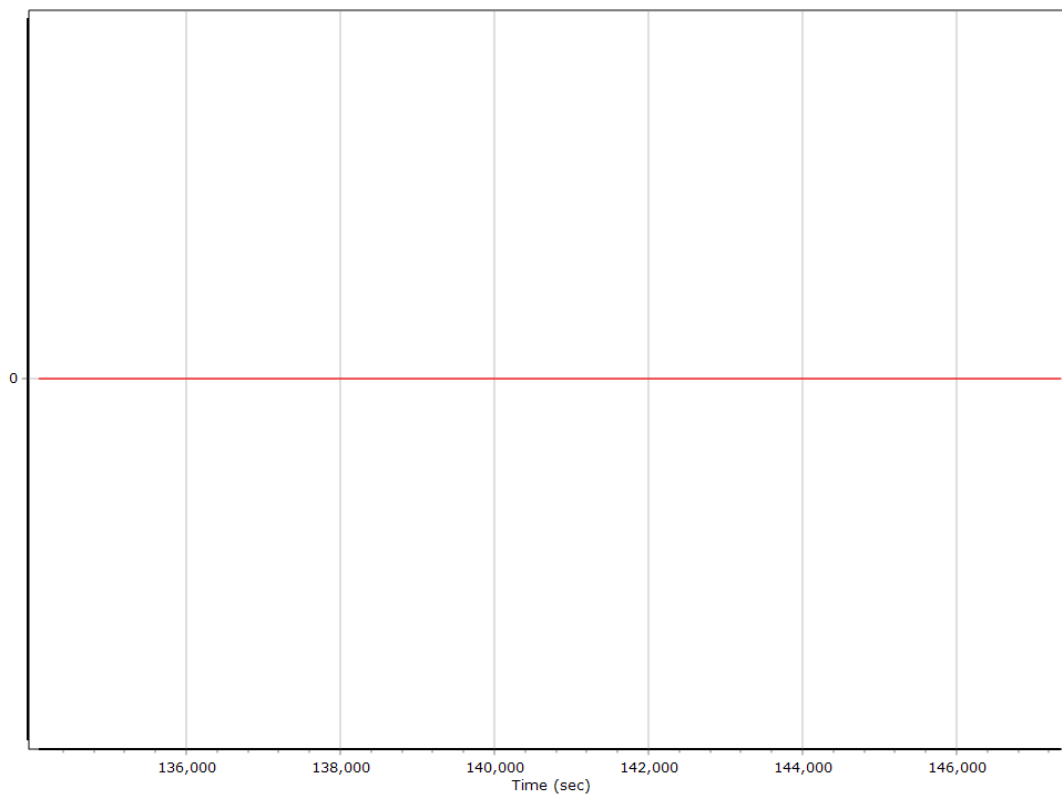
Processing Mode



Number of Satellites



Baseline Length



Export Summary

Export file	sbet_220711_A_5060492_nad2011_FINAL.shp		
Export format	Shapefile		
Solution in use	Post-processed		
Output rate	Specified Distance Interval		
Distance Interval (m)	10.000		
Reference to Output lever arm (m)	0.000	0.000	0.000
Reference mounting angles (deg)	0.000	0.000	0.000
Output units (Coordinate / Lat & Lon)	Meter	Deg Decimal	
Export start time	134022.001 (07/11/2022 13:13:42)		
Export end time	147366.004 (07/11/2022 16:56:06)		
Height option	Ellipsoid Height		
WGS84 height flag	False		
Grid	Universal Transverse Mercator		
Zone	UTM North 11 (120W to 114W)		
Datum	NAD83 (2011)		
Ellipsoid	GRS 1980		
Local Transformation	NONE		
Target Epoch	2022.523288		