

LiDAR Workflow and Quality Control Plan - Oneida County, WI 2013

LiDAR Quality Control/Quality Assurance Procedures

Quality Assurance/Quality Control (QA/QC) is an integral part of all aspects of any project. QA/QC begins at the proposal and mission planning stages, and continues through the field operations and data processing/data delivery in the office. It also includes assuring successful delivery of required materials and follow-up with the client to assure satisfaction.

Cooperative quality control is the coordinated effort that takes place when the project's technical project managers works in concert with County staff to quality-check and organize project deliverables, develop related documentation, and execute the final partnership deliveries.

Quality checks of the data should use a redundant approach with Oneida County and the Ayres Associates/AeroMetric team examining the data in parallel. It is critical that the parallel QC processes be coordinated so issues can be addressed efficiently as they arise. Communication is crucial for correctly addressing issues so impacts to the overall delivery time frame are minimized.

Although every project performed by Ayres Associates and AeroMetric has different specifications that necessitate different technical solutions, the team employs a proven project approach which has been refined over years of experience with each other. The sequential phases of this approach are:

- Detailed Project Planning
- LiDAR Acquisition
- Data Processing and Mapping
- · Final QA/QC, documentation, and delivery

In addition, throughout the complete project lifecycle, two key activities are executed: Project Management (including client communications and feedback, subcontractor coordination, as well as schedule and budget monitoring) and Quality Assurance & Quality Control (QA/QC) to ensure that all final specifications will be met. Using this integrated approach, the Ayres Associates/AeroMetric team will assure that all project specifications are met, and that all deliverables are received by Oneida County on time.

QA/QC Management

Ayres Associates' LiDAR supervisor, Matt Vinopal, will be responsible for the LiDAR QA/QC. In that capacity, he will work with Mr. Contrucci and Mr. Stroub to fulfill our team's commitment to providing quality products and services. In his role, our supervisor has a number of specific technical workflows. The first step in the LiDAR QA/QC process is to review mission logs and examine mission parameters. The second step is an automated/manual edit of the raw data. This process will ensure the removal of extraneous points and artifacts. Additionally, it will determine that all desired features have been retained within the data set. Filtered and edited data are subjected to rigorous QA/QC according to the Ayres Associates Quality Control Plan. A series of quantitative and visual procedures is employed to validate the accuracy and consistency of the filtered and edited data.

Initial OC

For this phase of the project, the following specifications are checked against the actual data collection and quality results:

- Nominal Pulse Spacing (NPS), or point density and points per square meter (PPSM) for first return data.
- Spatial distribution of points is uniform and free from clustering.
- Flight planning and data acquired encompass a 500-foot buffer surrounding project boundary.
- Multiple returns from any given pulse are stored in order and point families remain intact.
- Each return includes: easting, northing, elevation, intensity, order of return (i.e. first-return, second-return), classification, GPS week, GPS second. Easting, northing, and elevation must be recorded to the



nearest 0.01 meter and GPS second reported to the nearest microsecond (or better). May include additional attributes but no duplicate entries.

- Minimum 50% overlap on adjoining swaths.
- No voids between swaths.
- Must be cloud, smoke, dust, and fog-free between the aircraft and ground.
- At least two (2) GPS reference stations in operation during all missions, sampling positions at 1 Hz or higher frequently. Differential GPS baseline lengths shall not exceed 30 km. Differential GPS unit in aircraft shall sample position at 2 Hz or more frequently.

After our technicians establish the smoothed best estimate of trajectory (SBET), they apply the solution to the dataset in order to adjust each point based on aircraft position and orientation during LiDAR acquisition. To correct angular misalignments (roll, pitch, and heading errors), a manual bore sight calibration is employed before each day's mission to fine-tune the bore sight angles. It is at this point, as part of our LiDAR QA/QC procedure, that a review of the mission logs and mission parameters are performed.

Classified LAS Point Clouds

LiDAR data processing for the point cloud deliverable consists of classifying the LiDAR using a combination of automated classification and manual edit/reclassification processes. On most projects the automated classification routines will correctly classify 90-95% of the LiDAR points. The remaining 5-10% must undergo manual edit and reclassification.

Because the classified points serve as the foundation for the Terrain, DEM and breakline products, it is necessary for the QA/QC supervisor to review the completed point cloud deliverables prior to the production of any additional products.

The following workflow steps are followed for **automated** LiDAR classification:

- Lead technicians review the group of LiDAR tiles to determine which automated classification
 routines will achieve the best results. Factors such as vegetation density, cultural features, and terrain
 can affect the accuracy of the automated classification. The lead technicians have the ability to edit or
 tailor specific routines in order to accommodate the factors mentioned above, and achieve the best
 results and address errors.
- 2. Distributive processing is used to maximize the available hardware resources and speed up the automated processing as this is a resource-intensive process.
- 3. Once the results of the automated classification have been reviewed and passed consistent checks, the supervisor then approves the data tiles for manual classification.

The following workflow steps are followed for **manual edits** of the LiDAR classifications:

- 1. LiDAR technicians review each tile for errors made by the automated routines and correctly address errors any points that are in the wrong classification. By methodically panning through each tile, the technicians view the LiDAR points in profile, with a TIN surface, and as a point cloud.
- 2. Any ancillary data available, such as Google Earth, is used to identify any features that may not be identifiable as points so that the technician can make the determination to which classification the feature belongs.

The QA/QC processes for the LiDAR processing phase consist of:

1. The lead technician reviews all automated classification results and adjust the macros as necessary to achieve the optimal efficiency. This is an iterative process, and the technician may need to make



- several adjustments to the macros, depending upon the complexity of the features in the area being processed.
- 2. During the manual editing process, the LiDAR technicians use a system of QA, whereby they check each other's edits. This results in several benefits to the process:
- 3. There is a greater chance of catching minor blunders
- 4. It increases communication between technicians on technique and appearance
- 5. Solutions to problems are communicated efficiently
- 6. To ensure consistency across the project area, the supervisor reviews the data once the manual editing is complete.

For this phase of a project, the following specifications are checked against:

- Point cloud all points must be classified according to the ASPRS classification standard for LAS. The all-return point cloud must be delivered in fully-compliant LAS version 1.2.
- LAS files will use the Spatial Reference Framework according to project specification and all files shall be projected and defined.
- General Point classifications:
 - Class 1. Non Ground
 - Class 2. Bare-earth Ground
 - ➤ Class 3. Low Vegetation
 - Class 4. Medium Vegetation
 - Class 5. High Vegetation
 - Class 6. Buildings
 - Class 7. Low Point (Noise)
 - Class 9 Water.
 - Class 10 Ignored ground (Breakline proximity)
 - ➤ Class 11 Withheld
 - Class 12 Overlap
 - ➤ Class 13 Bridge
 - Class 14 Dam
- Outliers, noise, blunders, duplicates, geometrically unreliable points near the extreme edge of the swath, and other points deemed unusable are to be identified using the "Withheld" flag. This applies primarily to points which are identified during pre-processing or through automated post-processing routines.
 Subsequently identified noise points may be assigned to the standard Noise Class (Class7), regardless of whether the noise is lower or higher relative to the ground.
- Classification accuracy within any 1 km x 1 km area, no more than 2% of non-withheld points in the classes listed above will possess a demonstrably erroneous classification value. This includes Unclassified points (Class 1) that should be correctly included in a different class as required by this specification.
- Point classification shall be consistent across the entire project. Noticeable variations in the character, texture, or quality of the classification between tiles, swaths, lifts, or other non-natural divisions will be cause for rejection.
- Once the data is imported into GeoCue and has undergone and passed the QC process, the strip data will be tiled to the 5000' x 5000' tiling scheme.



Low Confidence Polygons

To ensure point spacing meets projects specifications, a one meter grid will be used to check that areas one acre and greater have appropriate coverage. In one acre areas or greater where the point spacing is not achieved, the area will be considered 'low confidence'. An ESRI shapefile will be collected in areas given the 'low confidence' attribute, and the shapefile will be delivered to the County.

Breaklines

Once the classified point clouds have been reviewed and approved, the LiDAR can be used to generate the hydro-flattening breaklines. Once the breaklines are developed, they will also be used to hydro-enforce ESRI Terrains and Digital Elevation Model (DEM) products.

The following process steps are used to generate hydro-flattening breaklines:

- 1. The technician visualizes the LiDAR point cloud by intensity.
- 2. The technician then creates the hydro-breaklines using Terrasolid software, as well as ancillary sources (such as Google Earth) as a reference in areas where the features appear ambiguous.
- 3. Once the breaklines are completed, they are separated into layers containing polygonal breaklines and line features.
- 4. To further differentiate the type of water, the polygonal breaklines are then separated or classified as ponded water or flowing water.
- 5. Flowing water: Using downhill conflation rules, stream and river centerlines are digitized to enforce the hydrological representation of water flow. Once this is done, polygons are digitized to represent the stream or river banks. The elevation from the steam centerlines are then applied to the polygons so that each side of the bank has the same elevation.
- 6. Ponded water: is digitized using Terrasolid's conflation rule. Terrasolid determines the average elevation of the water represented by the polygon, conflates the breakline, and then classifies the LiDAR points inside of the polygon to water.
- 7. Breaklines representing ponds and rivers will be smooth and continuous, and monotonic, and represent the water surface without any stair steps except for dams and rapids.
- 8. The breaklines are then converted to the product deliverable format

The product undergoes QC by the supervisor and is reviewed for any omissions or blunders.

For this phase of the project, the following Statement of Work specifications are checked against:

- All breaklines developed for use in hydro-flattening shall be delivered as a non-tiled Esri feature class
 for the project area and/or polyline shapefile or geodatabase format. Water bodies (ponds, lakes, and
 reservoirs), wide streams and rivers ("double-line"), and other non-tidal water bodies are to be hydroflattened within the DEM, resulting in a flat and level bank-to-bank gradient. The entire water surface
 edge must be at or below the immediately surrounding terrain.
- Breakline feature class will use the Spatial Reference Framework according to project specifications and shall be projected and defined.
- Hydro-flattening shall be applied to all streams that are nominally wider than 8 feet, and to all non-tidal boundary waters bordering the project area regardless of size.
- Hydro-flattening shall be applied to all water impoundments, natural or man-made, that are nominally larger than 2 acres in area (equivalent to a round pond ~350' in diameter).
- Stream channels should break at road crossings (culvert locations). These road fills should not be removed from the DEM. However, streams and rivers should NOT break at elevated bridges. Bridges should be removed from the DEM (see 'Artifacts' under Bare Earth LiDAR/DEM Raster). When the



identification of a feature such as a bridge or culvert cannot be made reliably, the feature should be regarded as a culvert.

Surface Models and Intensity Images

Digital Elevation Model (DEM)

A bare earth DEM will be provided for this project. To develop that dataset, the TIN's surface is referenced to determine the elevation for a highly dense set of points. The point sets will then be divided into cells. Each cell's elevation will then be determined by an average of all the elevations sampled within its extent. The County prefers a DEM cell size that is 3.125 feet, such that the cells will exactly match the boundaries of each tile.

This process will be carried out for large overlapping blocks across the project area. The blocks will overlap to ensure consistency. After the countywide DEM dataset has been created, the large DEM files will be cut up into tiles based on the tiling scheme file and exported to ESRI Grid files or another format if preferred.

Once the DEM is created, visual inspection in Global Mapper is performed for artifacts (tension lines, voids, edge effects) and for hydro-enforcement of waterbody, hydrographic, island and soft features. If any artifacts appear in the DEM, the point sets will be reviewed to determine the cause of the problem. In addition, visual inspection will be performed on the DEM using Global Mapper and LP360 looking for floating breaklines in the surface.

Lastly, the DEM is inspected using Global Mapper and LP360 for .LAS filtering consistency, any remaining systematic issues, and to ensure vegetation has been removed from the surface.

Digital Surface Model (DSM)

Ayres Associates will generate a DSM for the County using the processed LiDAR data. The surface will be generated using TerraSolid and/or ESRI software, depending on the output format selected by the County. We will work with the County to determine the format that is best suited for the current GIS and mapping applications.

The processing technique for the DSM will be the same as described above for the DEM. Visual inspection is performed in Global Mapper and LP360 on the first return data to ensure that no "short range" data exists within the DSM.

Intensity Images

LiDAR pulse return intensity images are created utilizing the GeoCue LiDAR 1 Cuepac. Intensity is modulated within the "intensity" field of the .LAS file to create images that are quite similar to normal image-based orthos and can be used for planimetric feature compilation. Intensity images will be delivered by tile in GeoTIFF format (we can work with the County to produce alternative formats as needed). An automated script is used to validate that intensity values are integers ranging between 0 and 255. Another automated script is used to validate the header information on all of the GeoTiffs.

Visual inspection is performed in Global Mapper to identify any data voids and pixel gaps. Global Mapper is also used to check GeoTIFF header information to ensure the Oneida County projection information is applied to each image correctly.

Contour Generation

Once all other base deliverable products have undergone the QA/QC process, have been completed, and have been approved by the county, the contour data set will be prepared. It is understood that Oneida County requires two-foot contours.



Model keypoints will be generated as a subset of the bare earth surface. Model keypoints are files derived from the bare earth ground points using an intelligent data decimation algorithm. The algorithm works by thinning out the data in areas of little relief while keeping more points near breaks and variations in terrain. More information is retained using this method than compared to using a regularly-spaced grid, yet the process results in more manageable file sizes.

The hydro-flattened breaklines in combination with the model keypoints will be used to generate two-foot contours. All contours products will be produced using a combination of Terrasolid's TerraModeler and ESRI ArcGIS software and exported to AutoCAD and ESRI formats for delivery.

QA/QC project tracking and reporting

Ayres Associates utilizes Project Manager & Project Dashboard software modules as part of its production workflow.

Project Manager is used to:

- Review top level information about a project and its status
- Assign individual technicians at the checklist step level to project entities
- Assign planned task execution times at the checklist step level
- Review detailed project statistics such as actual technician, actual production times and so forth

Project Dashboard is a web-application that allows the QA/QC supervisor to aggregate entities that are managed within a project into a project summary view.

Project Dashboard includes:

- Iconic display of project status
- Alternate display modes such as Phase variance, Phase schedule, External Financial System comparison
- User-settable alerts for Warning and Error conditions
- Microsoft Excel Import and Export of project definitions and status

QA/QC standard tests and checks

Data QA/QC results are verified using survey checkpoints as well as any vertical checkpoints provided by the client to conduct an internal blind test of the vertical accuracy. The test within GeoCue is called a "z-probe". The z-probe results are reviewed by the Supervisor as well as a Certified Photogrammetrist to ensure that the vertical accuracy of the data meets or exceeds the specification. Any anomalies detected in the results are immediately investigated to determine the root cause, and corrective action is taken to mitigate any impact on schedule or quality.

In addition to the data being compared against survey checkpoints, various types of lidar derived images are created for terrain visualization. Examples of these include the following: delta elevation ortho (dz), which is used to assess the relative vertical accuracy of the flight lines. A second image is called color by flight line ortho, which is used to visualize the true ground coverage by flight line.

Metadata

All data produced by the Ayres Associates team will comply with the Federal Geographic Data Committee's (FGDC) Data Content and Process Standards. The FGDC, as lead entity in coordinating the National Spatial Data Infrastructure, has developed a set of standards that include specifications on description of processes, data content, classification, symbology, transfer and usability, and process standards. These standards include data collection, storage, and presentation of geospatial digital data.

To further ensure the compliance of the metadata produced by Ayres Associates, each file is processed through a third-party geospatial metadata validation service before it is finalized and delivered to the client.



LiDAR QA/QC Checklist			
Milestone	Production	Peer Review	Supervisor Review
Flight plan and ground control	Troudction	- Neview	X
LiDAR data check-in			7
As-flown coverage checks			х
Data density, overlap checks			X
GPS data checks			x
Accuracy Checks on LiDAR data			
Terrain visualization checks (dz ortho, color by flight line)			х
Internal blind test for vertical accuracy (z-probe)			х
Review and pass for Automated Classification			х
Automated Classification Routine			
Review terrain for best automated routine	х		
Review classification results for accuracy and consistency	Х	х	х
Review and pass for Manual Classification			х
Manual Classification Routine			
Review Auto Classification for mis-classifications	х	х	
Correct mis-classifications through manual edits	х	х	
Review and pass full classification	х	х	х
QA checks for point cloud classification			
Check point cloud compliancy with ASPRS LAS v1.2			х
Check against project-specific point classes			х
Check classification accuracy			х
All files projected and defined using Spatial Reference Framework			х
Breakline development and checks			
Breakline differentiation review (linear vs. polygonal)	х	Х	
Hydro breakline classification (ponds, rivers)	х	Х	
Hydro breakline checks for smooth, continuous, monotonic	х	Х	
Breakline review and pass for deliverable export			х
Contour generation and checks			
All base deliverables have passed QA/QC and client review			х
Model key points and hydro-flattened breaklines properly applied	Х	х	
Contour smoothing routine properly applied	Х	х	
Review and pass for deliverable export			х
Final QA/QC			
Deliverables all pass individual QA/QC review			х
Deliverables exported to proper file format			х
Deliverables in proper coordinate reference system			х



Check and Test descriptions and expected results

As-flown coverage: Review as-flown flight line and coverage on the ground to ensure approximately 50% sidelap was achieved on each mission, extending to the 500-ft buffer around the County boundary.

Data density check: Review data density as collected throughout the project area to ensure it meets project specifications.

GPS data check: Review GPS data to make sure continuous coverage has been achieved within 30 km baseline length, remove any PDOP spikes above acceptable ranges, review satellite constellation and satellites in solution, review GPS timestamps for continuous data collection.

DZ ortho: Check vertical differences between flight lines to ensure line by line accuracy. The DZ ortho graphically represents relative accuracy within and between swaths at 5, 10, and 15 cm increments. Any swaths that show a significant difference compared to adjacent flight lines are investigated and adjusted.

Color by flight line: This particular display is used as part of a qualitative workflow that helps better visualize and better understand the scan pattern, flight line orientation, flight coverage, and gives an additional confirmation that all point classes are present and seem to logically represent the terrain.

Z-probe: This process will compare any known (i.e surveyed) point or elevation data to the bare earth lidar surface. The survey checkpoint's XY location is overlaid on the TIN and the interpolated Z value is recorded. This interpolated Z value is then compared with the survey checkpoint Z value and this difference represents the amount of error between the measurements.

Point Cloud Classification: This process will ensure the removal of extraneous points and artifacts. Additionally, it will determine that all desired features have been retained within the data set. Filtered and edited data are subjected to rigorous QA/QC. A series of quantitative and visual procedures is employed to validate the accuracy and consistency of the filtered and edited data.

After the automated and manual edits are complete, the resulting accuracy of the data will be as follows:

- 98% of Artifacts will be removed
- 98% of Outliers will be removed
- 98% of buildings will be removed
- 95% of vegetation will be removed

Breakline checks: Breaklines representing ponds and rivers will be smooth and continuous, and monotonic, and represent the water surface without any stair steps except for dams and rapids.

Contour smoothing: The default filtering parameters are applied for point spacing and smoothing. A check is then done to ensure the contour smoothing routine properly applied. Lastly, a check is done to ensure model key points and hydro-flattened breaklines were properly applied.

DEM check: Visual inspection in Global Mapper is performed for artifacts (tension lines, voids, edge effects) and for hydro-enforcement of waterbody, hydrographic, island and soft features. If any artifacts appear in the DEM, the point sets will be reviewed to determine the cause of the problem.

DSM check: Visual inspection is performed in Global Mapper and LP360 on the first return data to ensure that no "short range" data exists within the DSM.



Scope of Work Deliverables

LiDAR Data Deliverables

- Final classified point cloud LiDAR points, LAS v1.2 and shapefile format
- Raw LiDAR points, LAS v1.2 and shapefile format
- Breaklines, ESRI PolylineZ files
- Flight and Ground Control plan will be delivered prior to flight
- QA/QC plan as described in the Quality Assurance and Quality Control sections on page 11 and 12 will be delivered at the start of the project.

2-foot Interval Contours

• Countywide 2-foot contours, ESRI PolylineZ files

Other LiDAR Products and Deliverables

- DEM. ESRI GRID
- DSM, ESRI GRID
- Intensity Images
- SBET trajectory files for each raw point cloud swath, including calibration swaths and cross ties DZ ortho that graphically represents relative accuracy within and between swaths, at 5, 10, and 15 cm increments.
- ESRI shapefile with areas considered 'low confidence' (if applicable)
- Pilot Area covering 10 tiles in no more than two different areas as selected by the County (a complete set of deliverables will be produced for each pilot area for the County's review)
- Interim Deliveries: After the Pilot Area is accepted, there will be two interim deliveries, each covering approximately half the County. The interim deliveries will not include the DEMs.
- QC forms: each interim delivery will include QC forms from internal processing.

Product Documentation and Reports

• Flight Plans and Proposed Ground Control: The Ayres Associates/Aerometric team will submit flight plans and ground control locations to the County in ESRI shapefile format prior to the flight. The County will review and approve the plans prior to flight.

ABGPS Processing Report

• An ABGPS processing report will be delivered. This report will include a project overview and history, base stations used during the flight (name, latitude, longitude, and ellipsoid elevation), and data sheets detailing processing results from each GPS base station by date.

Flightline Plans

• Plans will be provided that delineate the path of the LiDAR unit over the project area. The report will include parameters for each acquisition mission undertaken, such as flight altitude, point spacing, pulse rate, scan angle, scan frequency, airspeed, swath width, cross track resolution, and down track resolution.

Ground Control Report

• The ground control report will contain a summary of the approach as well as a general discussion of the project workflow and results. It will contain a statement outlining the specifications followed and a list of points with coordinates in both latitude/longitude and County coordinates. A plot of the project area will show the distribution of points, while control point locations will be shown in great detail within individual log sheets for each of the GPS locations. The GPS adjustment report will be included to show the final point solutions.

FEMA Accuracy Report

 As part of this LiDAR delivery, the County will provide independent ground control points – sufficient in number and appropriately placed so they serve as a compliant independent dataset with which Ayres Associates can test the LiDAR surface. After the analysis has been conducted by Ayres Associates, a FEMA accuracy report will be generated. The report will provide information about each survey point



(location, ground type, etc.); a table showing each points elevation variance from the surface at that xy location; and the summary statistics (e.g., sum, average, and RMSE) that are the result of the test.

FGDC Metadata

All data produced by the Ayres Associates team will comply with the Federal Geographic Data
Committee's (FGDC) Data Content and Process Standards. The FGDC, as lead entity in coordinating the
National Spatial Data Infrastructure, has developed a set of standards that include specifications on
description of processes, data content, classification, symbology, transfer and usability, and process
standards. These standards include data collection, storage, and presentation of geospatial digital data.

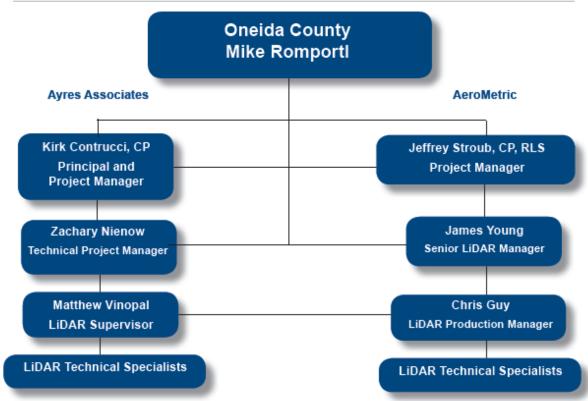
Certification

 A Certified Photogrammetrist or Registered Land Surveyor will provide documentation that the project was completed under his direct supervision and that the LiDAR data and derivative products meet project specifications.



Project Organizational Chart and Key Contacts

Organization Chart



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