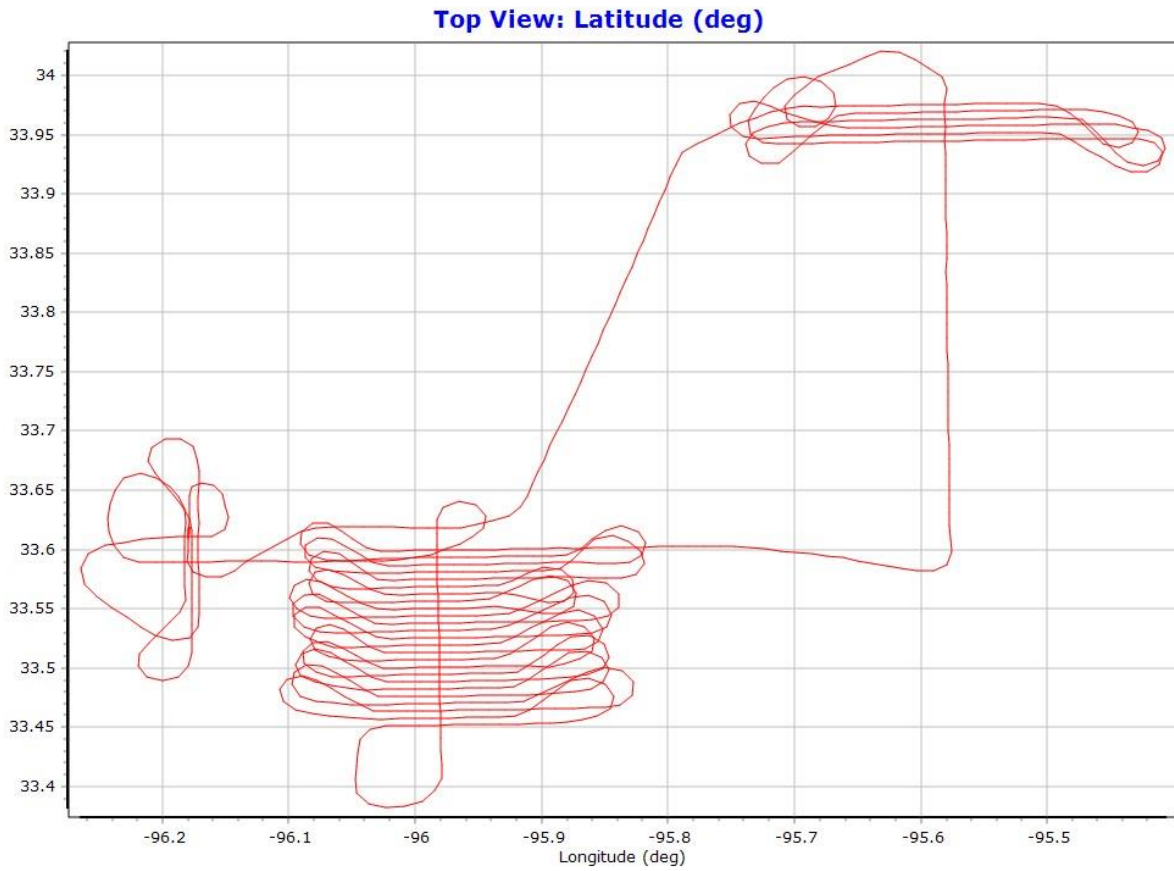


Appendix H: GPS Processing Blocks 15, UTM 15

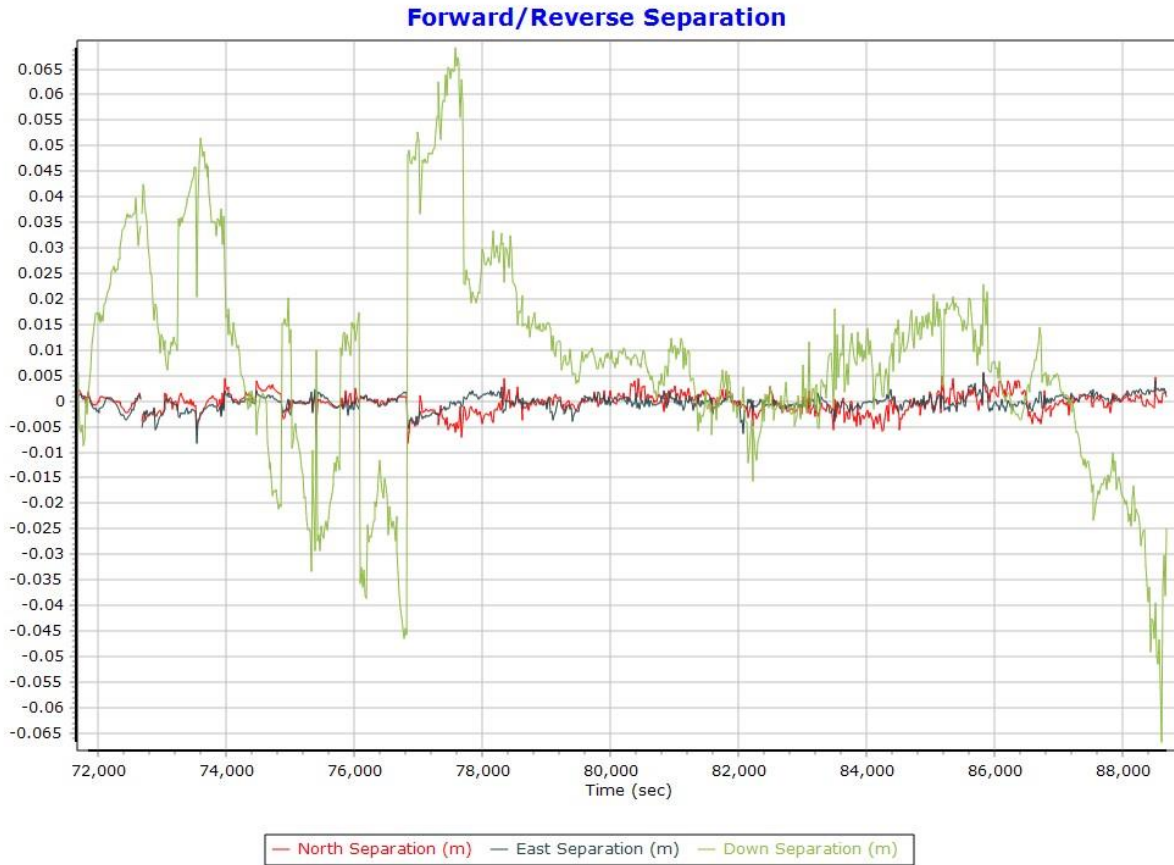
Flight 1

Trajectory Information

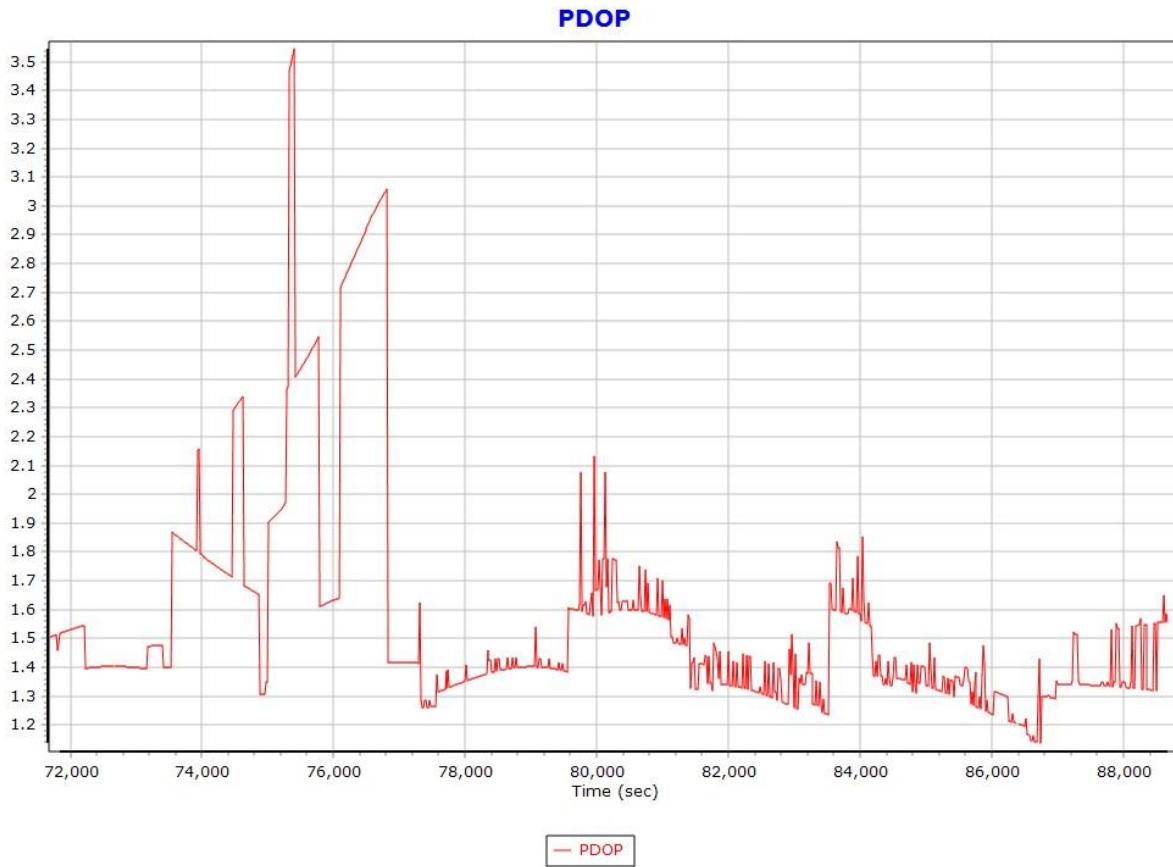
Top View



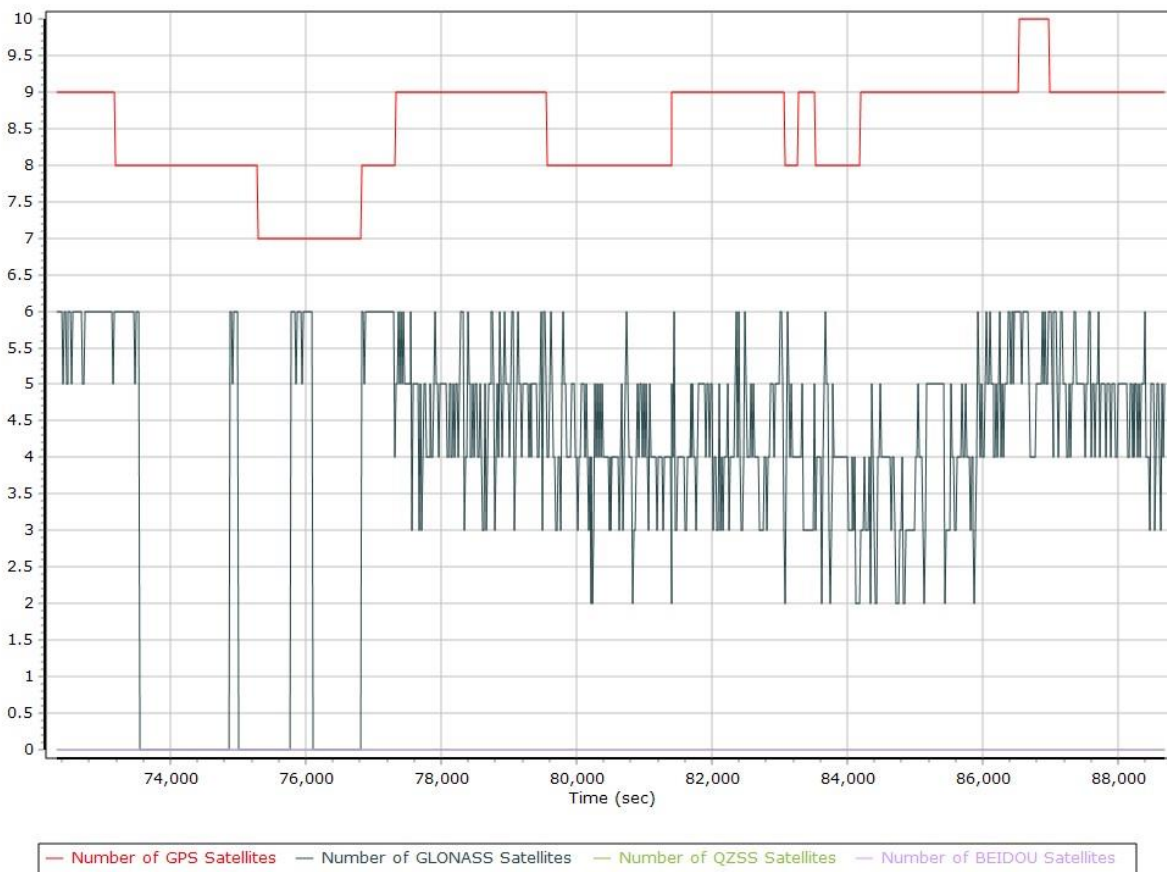
Forward/ Reverse Separation



PDOP



Number of Satellites



Processing Summary Information

Version: 4.30.3108 POSpac MMS 8.2
Project: flight1

Solution Type: Combined Fwd/Rev

Number of Epochs:

Total in GPB file: 3456188
No processed position: N/A
Missing Fwd or Rev: N/A With
bad C/A code: N/A
With bad L1 Phase: N/A

Project: Task Order # 7 TX West Central

Date: 07.11.2019

Appendix A: GPS and IMU Processing Reports for Flight 1 Page
5 of 18

Measurement RMS Values:

L1 Phase: N/A

C/A Code: N/A

L1 Doppler: N/A

Fwd/Rev Separation RMS Values:

East: Averages from the forward/reverse plot

North: Averages from the forward/reverse plot

Height: Averages from the forward/reverse plot

Fwd/Rev Sep

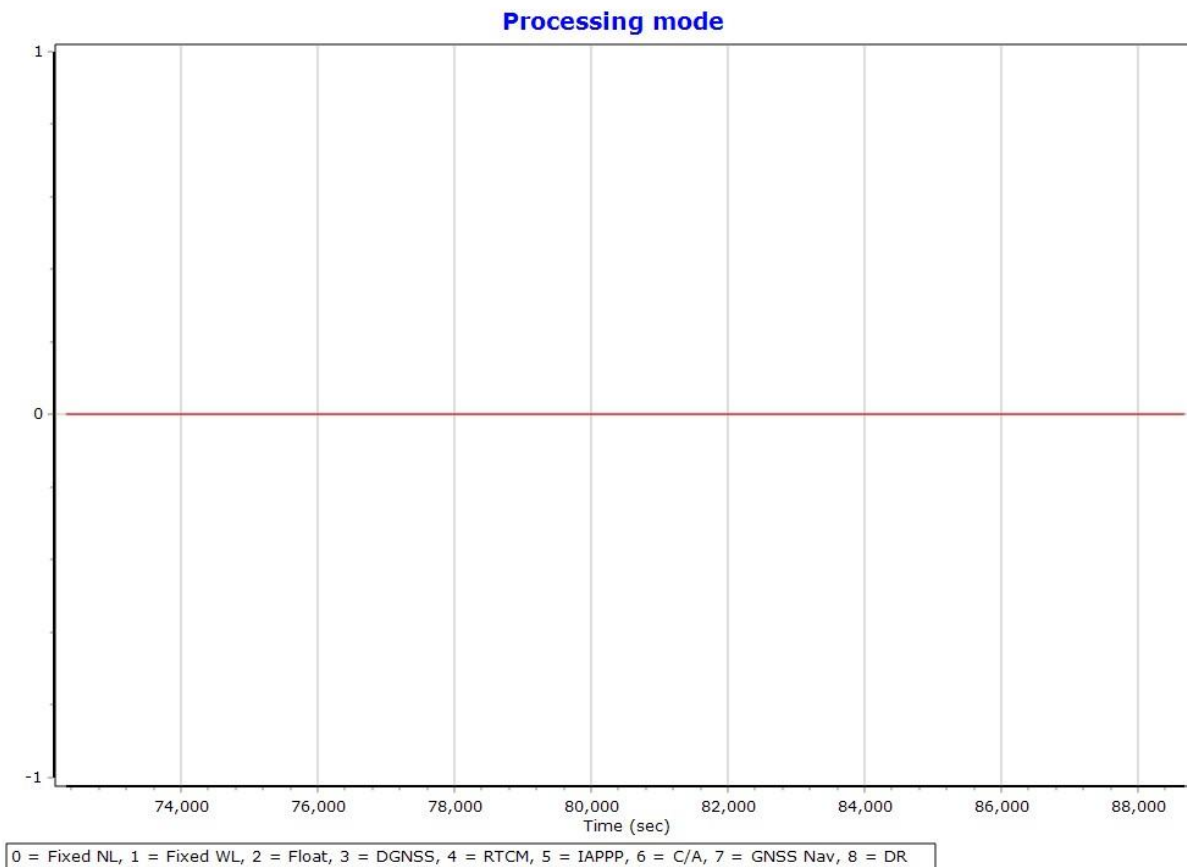
East: N/A

North: N/A

Height: N/A

Smoothed Solution Status

Processing Mode



Q 1 "Fixed NL": 100% Q

Q 2 "Fixed WL": 0%

Q 3 "Float": 0% Q

Q 4 "DGNSS": 0% Q

Q 5 "RTCM": 0%

Q 6 "IAPPP": 0%

Q 7 "C/A": 0%

Q 8 "GNSS Nav": 0%

Q 9 "DR": 0%

Position Standard Deviation Percentages:

0.00 - 0.10 m: 100.0 %

0.10 - 0.30 m: 0.0 % 0.30

- 1.00 m: 0.0 %

1.00 - 5.00 m: 0.0 %

5.00 m + over: 0.0 %

Project: Task Order # 7 TX West Central

Date: 07.11.2019

Appendix A: GPS and IMU Processing Reports for Flight 1 Page
7 of 18

Percentages of epochs with DD_DOP over 10.00: 0.0%.

DOP over Tol: 0.0 %

Baseline Distances:

Maximum: 35.834 (km)

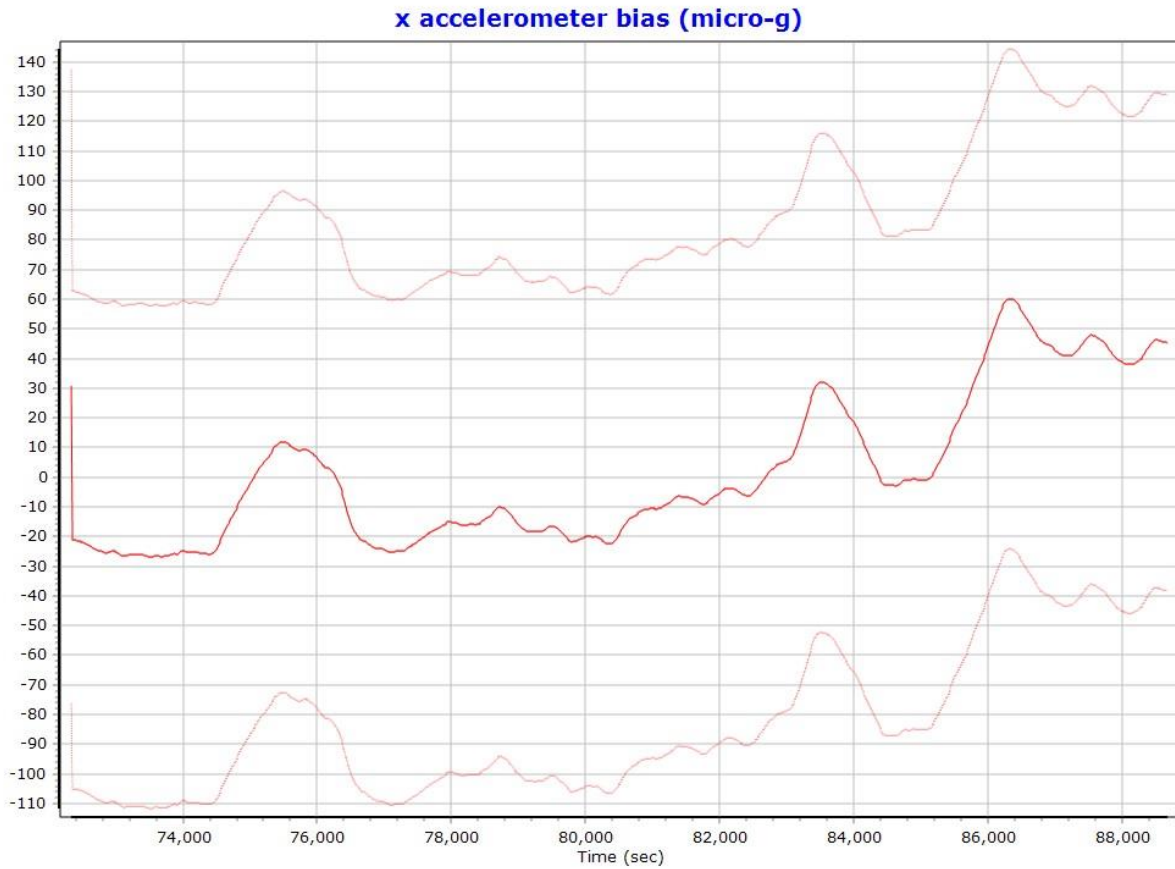
Minimum: 0.392 (km) Average:

~20 (km)

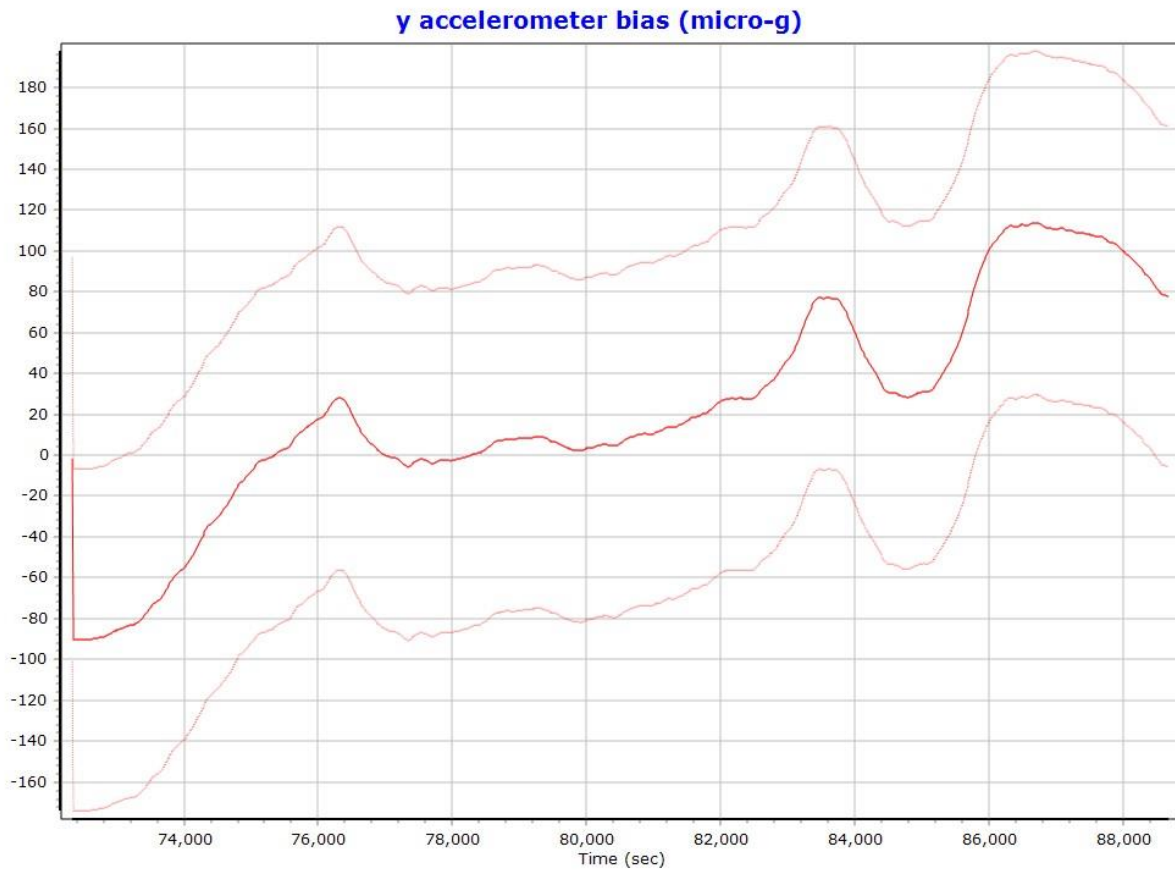
First Epoch: 0.746 (km) Last

Epoch: 0.600 (km)

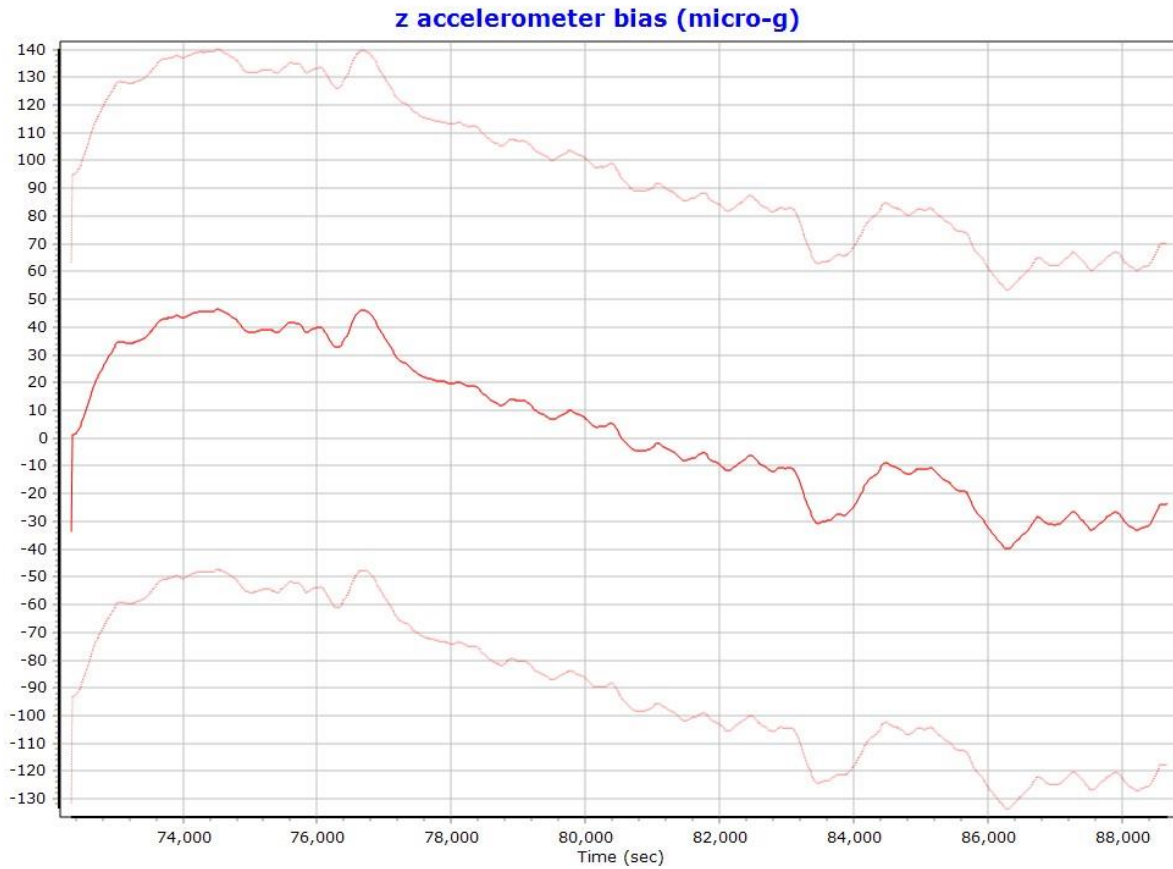
Sensor Errors X Accelerometer Bias (micro-g)



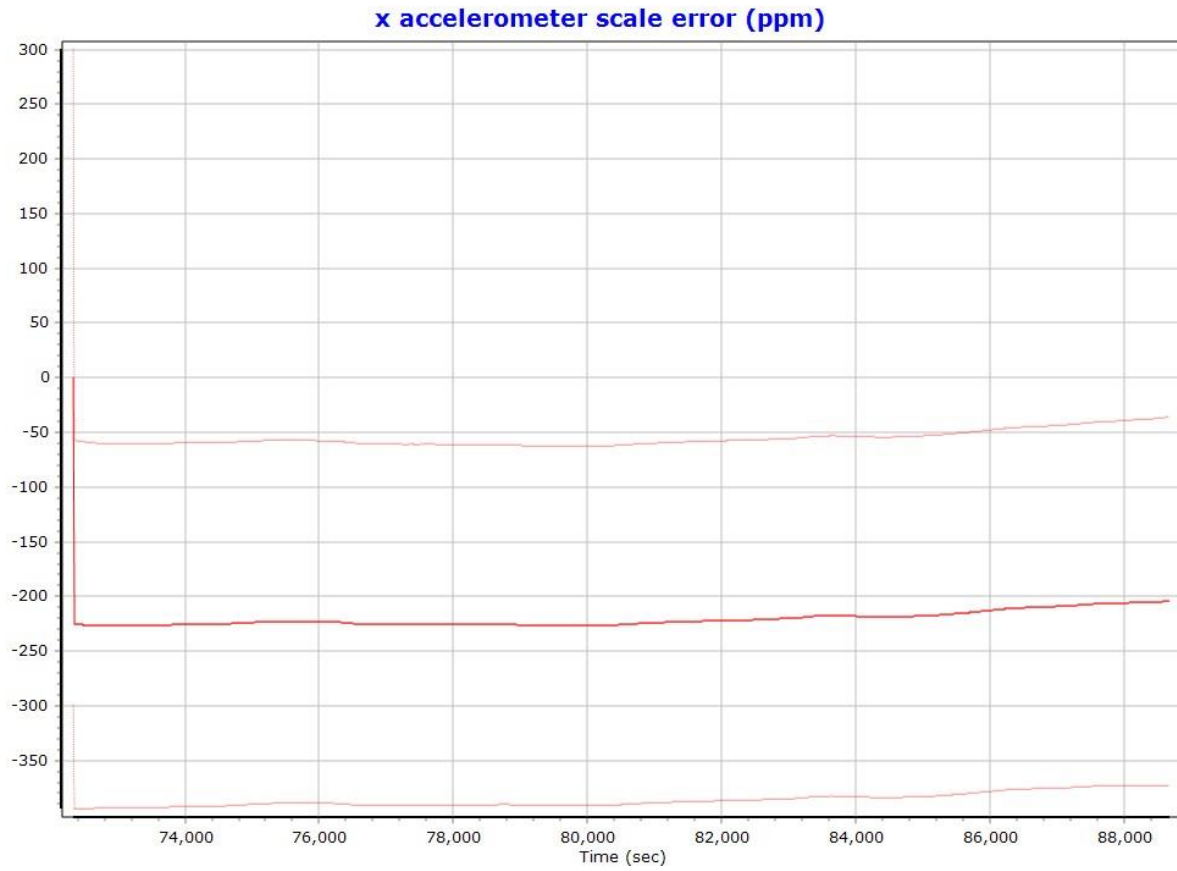
Y Accelerometer Bias (micro-g)



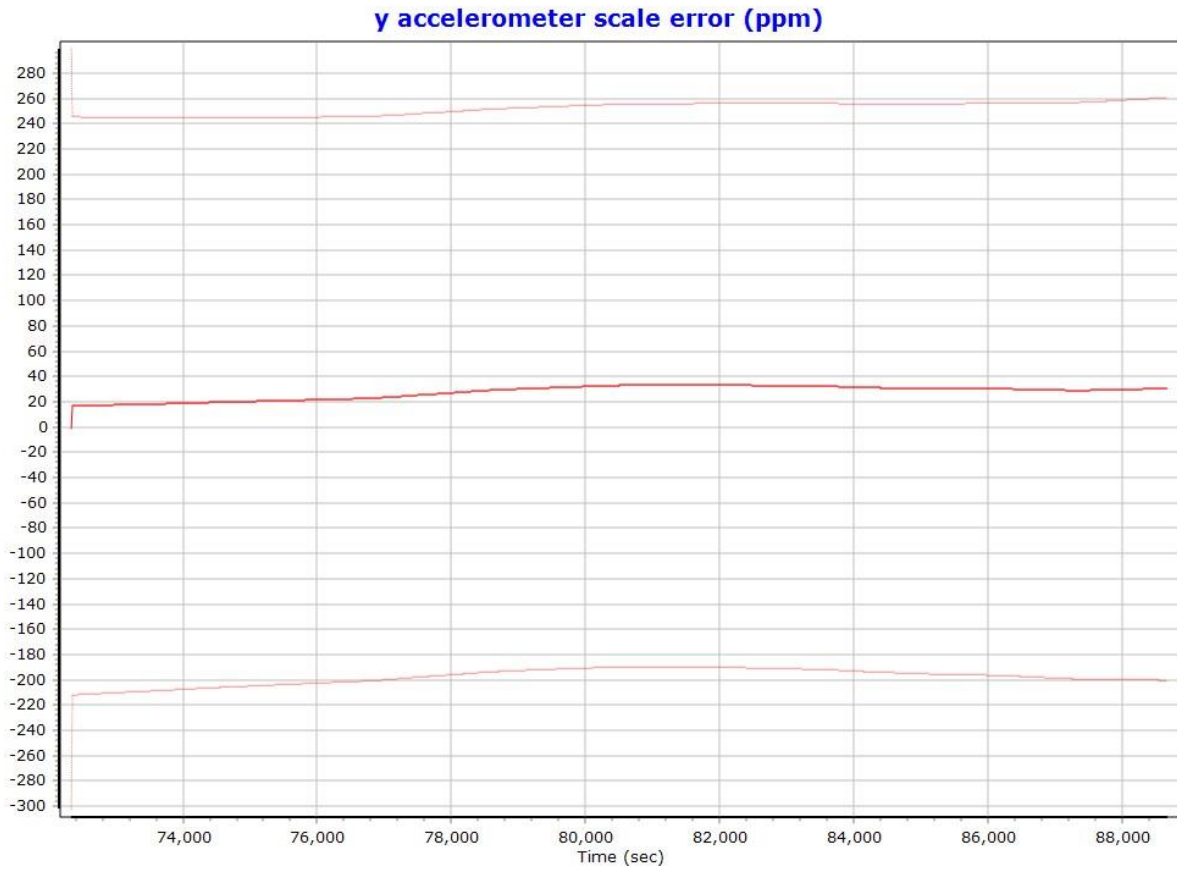
Z Accelerometer Bias (micro-g)



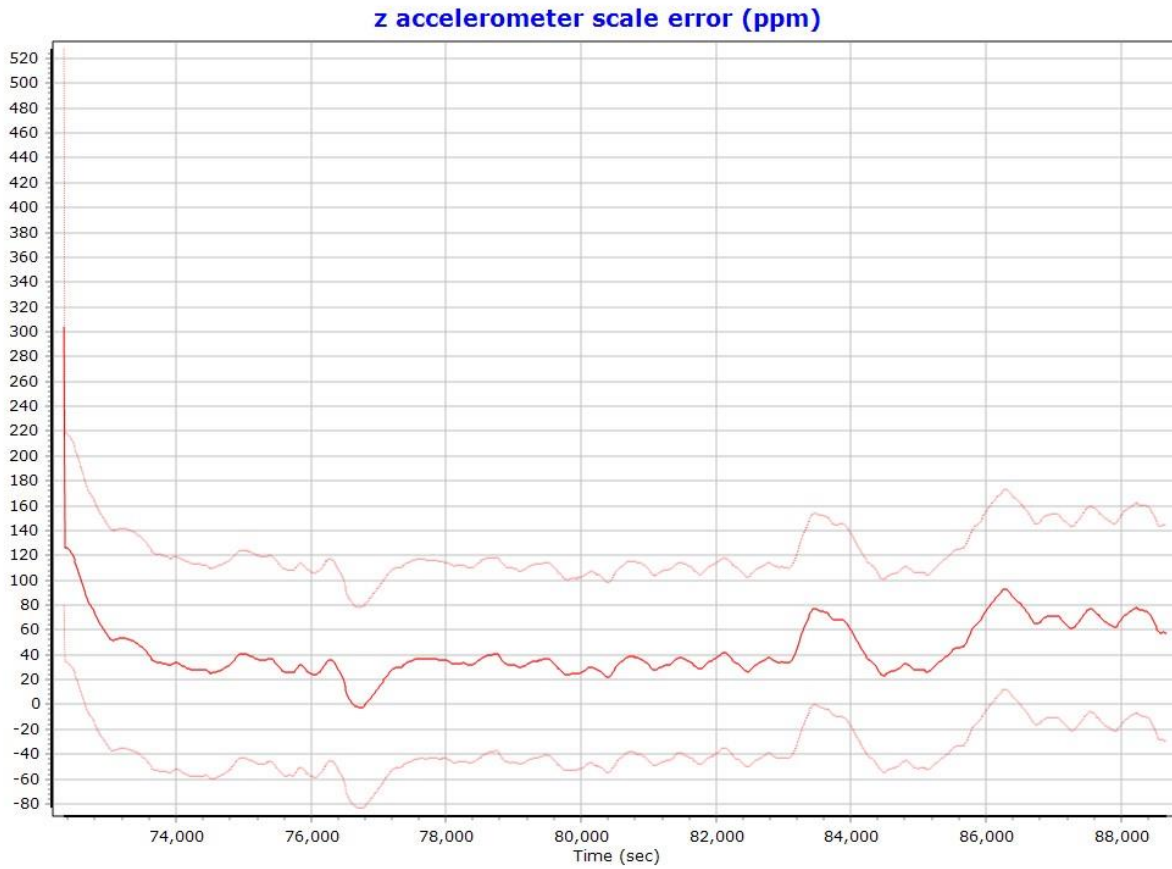
X Accelerometer Scale Error (ppm)



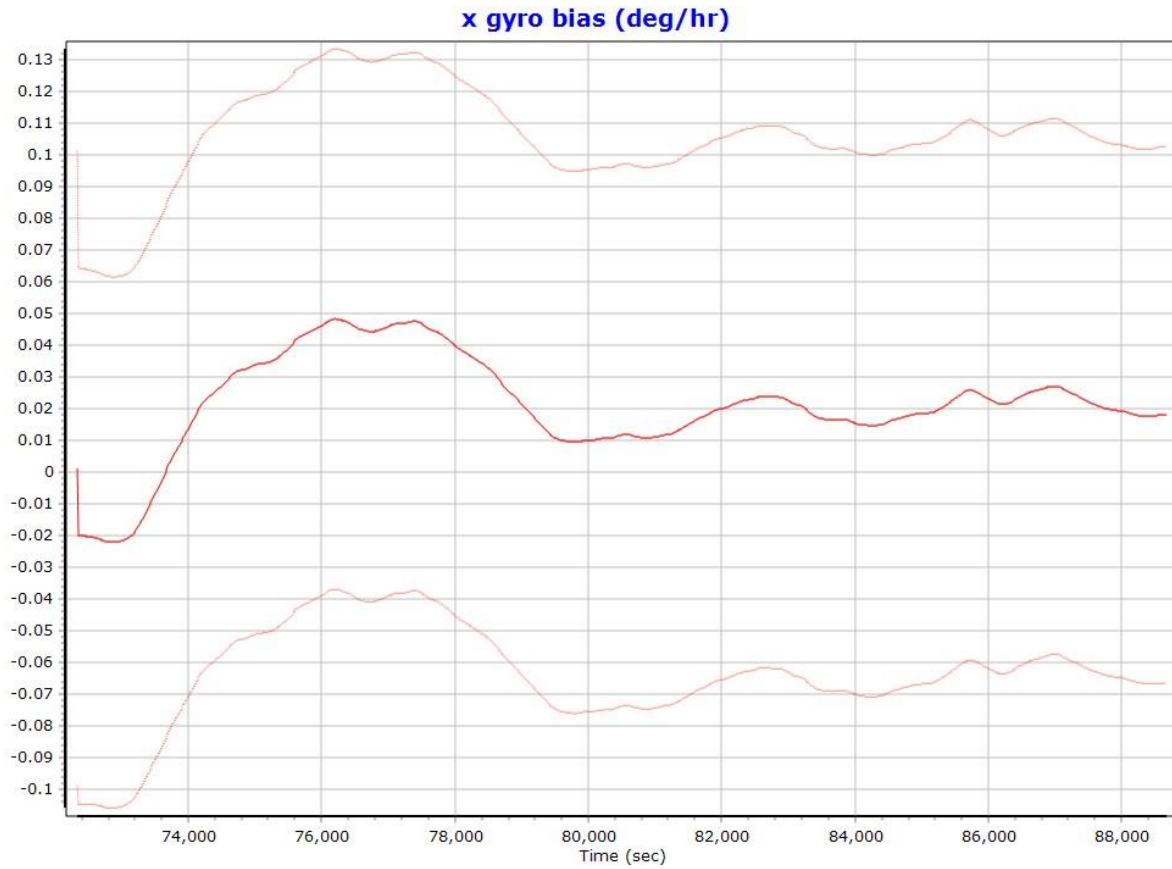
Y Accelerometer Scale Error (ppm)



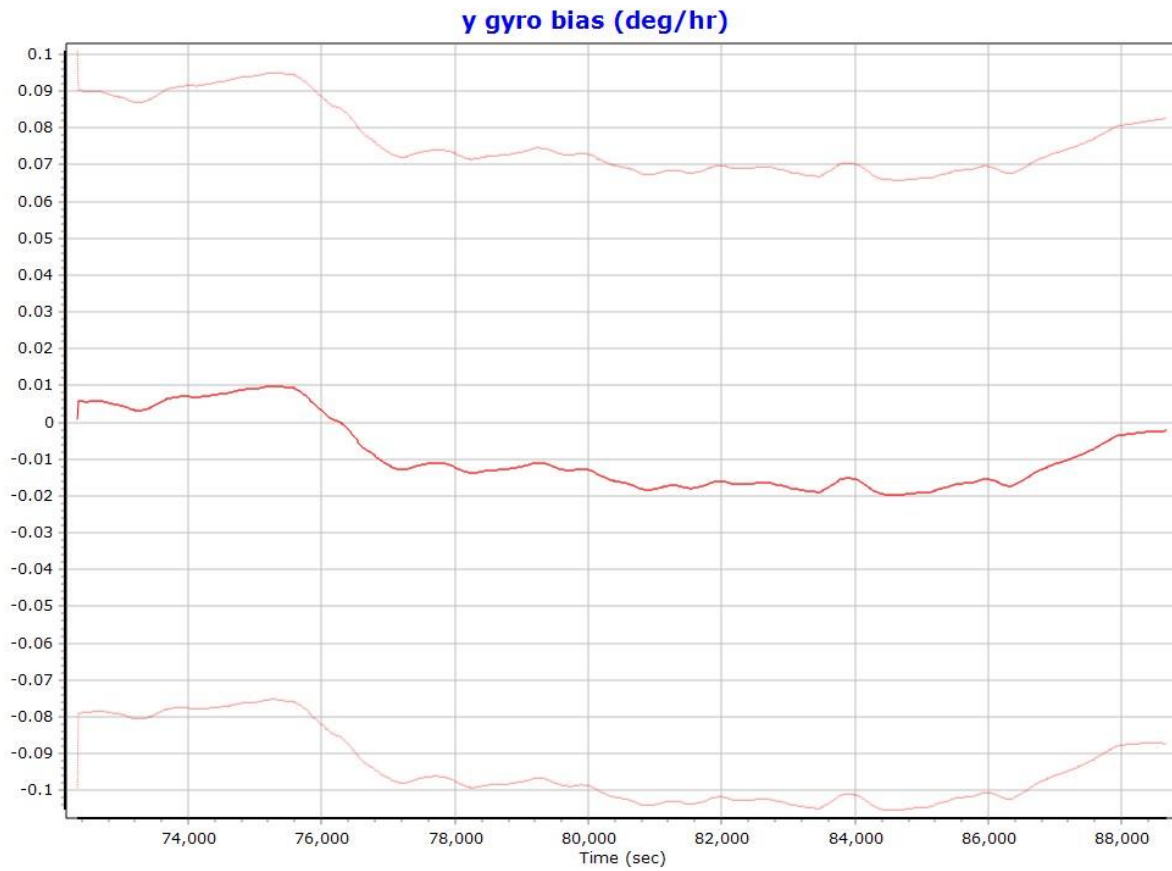
Z Accelerometer Scale Error (ppm)



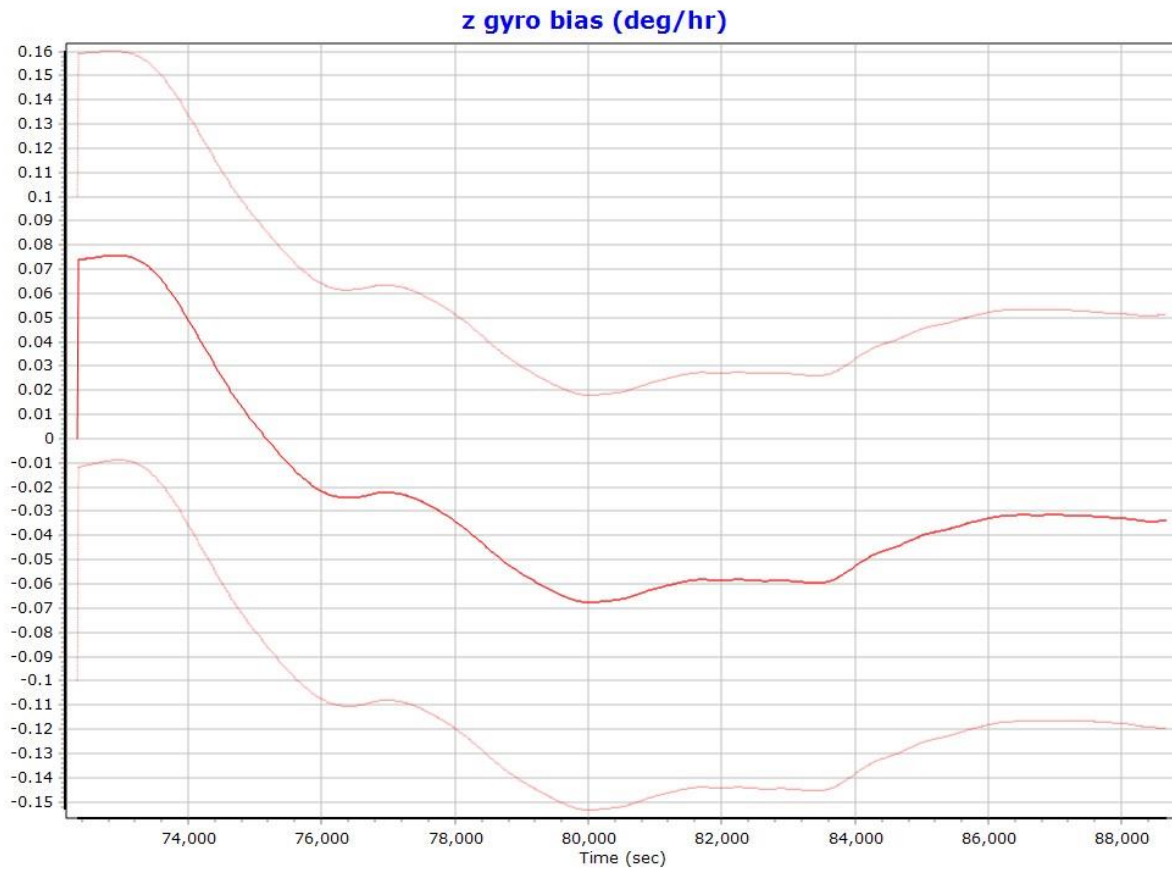
X Gyro Bias (deg/h)



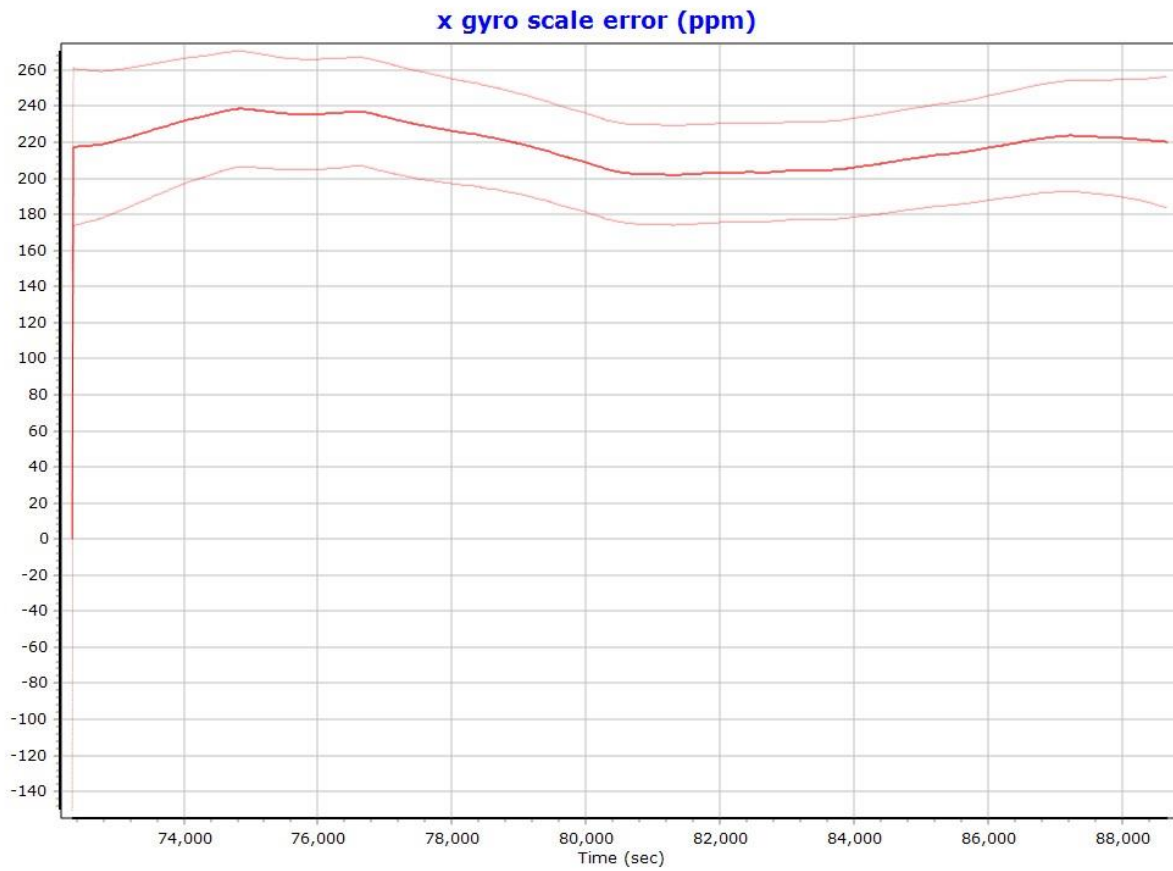
Y Gyro Bias (deg/h)



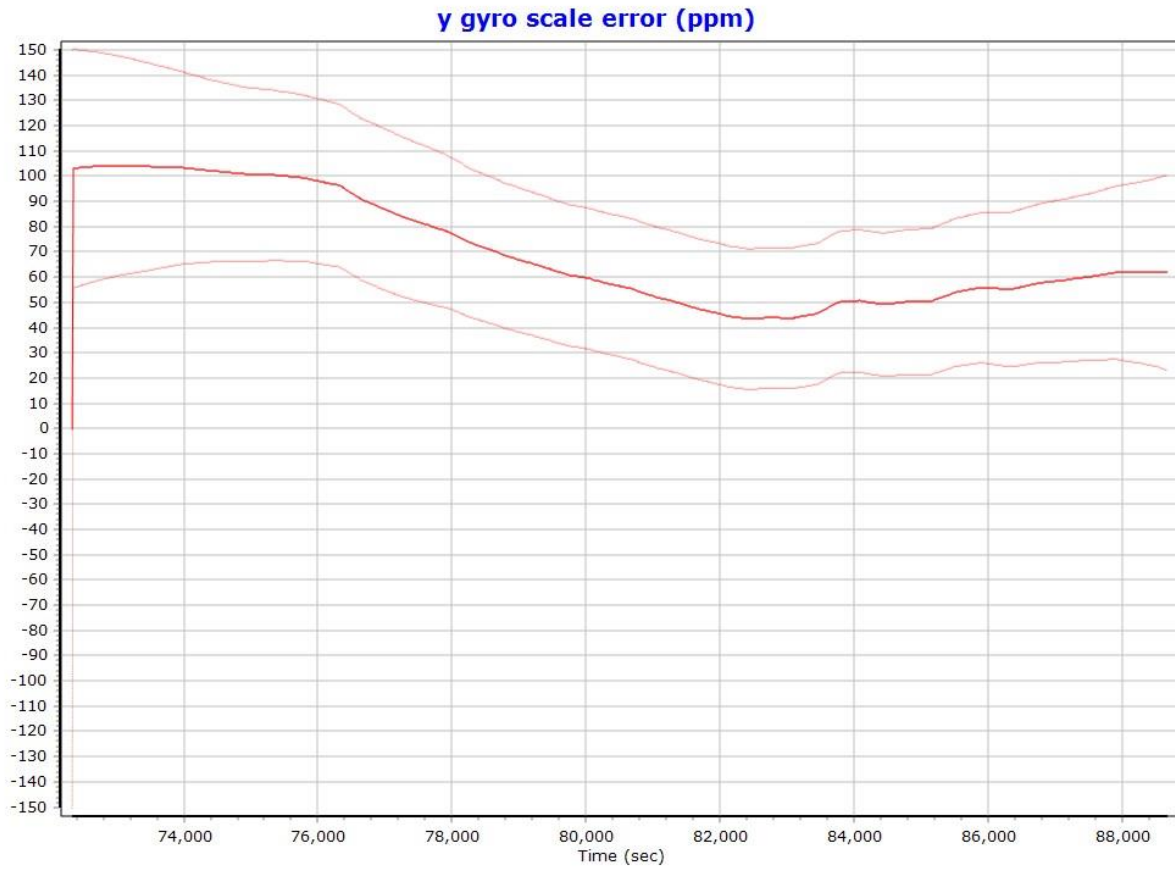
Z Gyro Bias (deg/h)



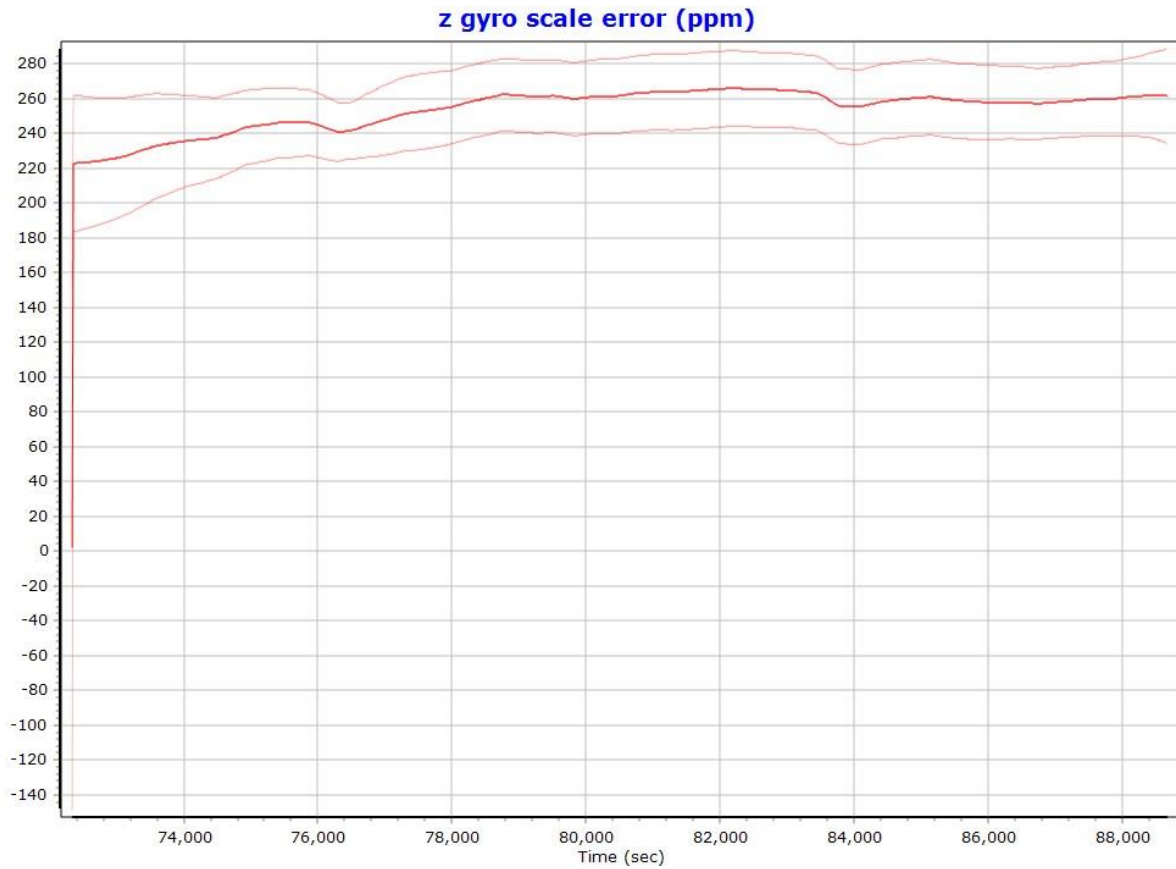
X Gyro Scale Error (ppm)



Y Gyro Scale Error (ppm)



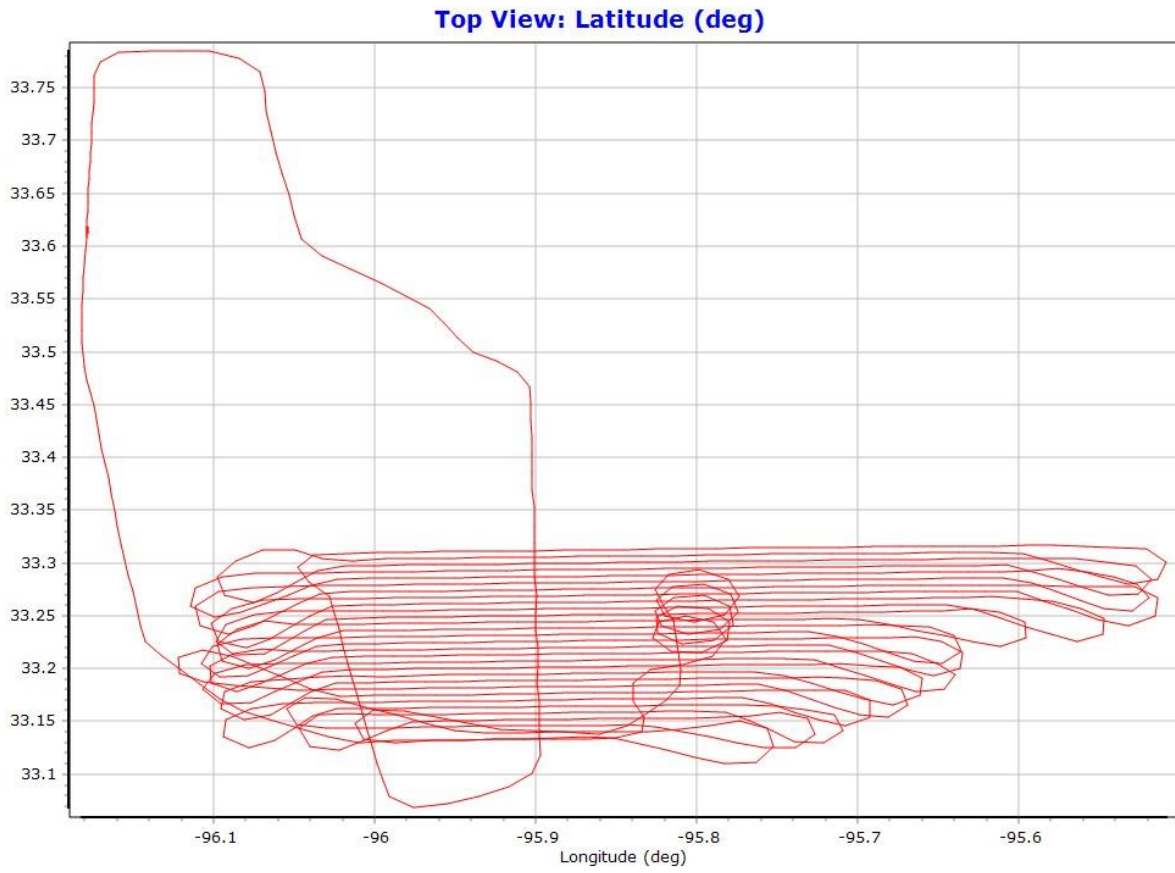
Z Gyro Scale Error (ppm)



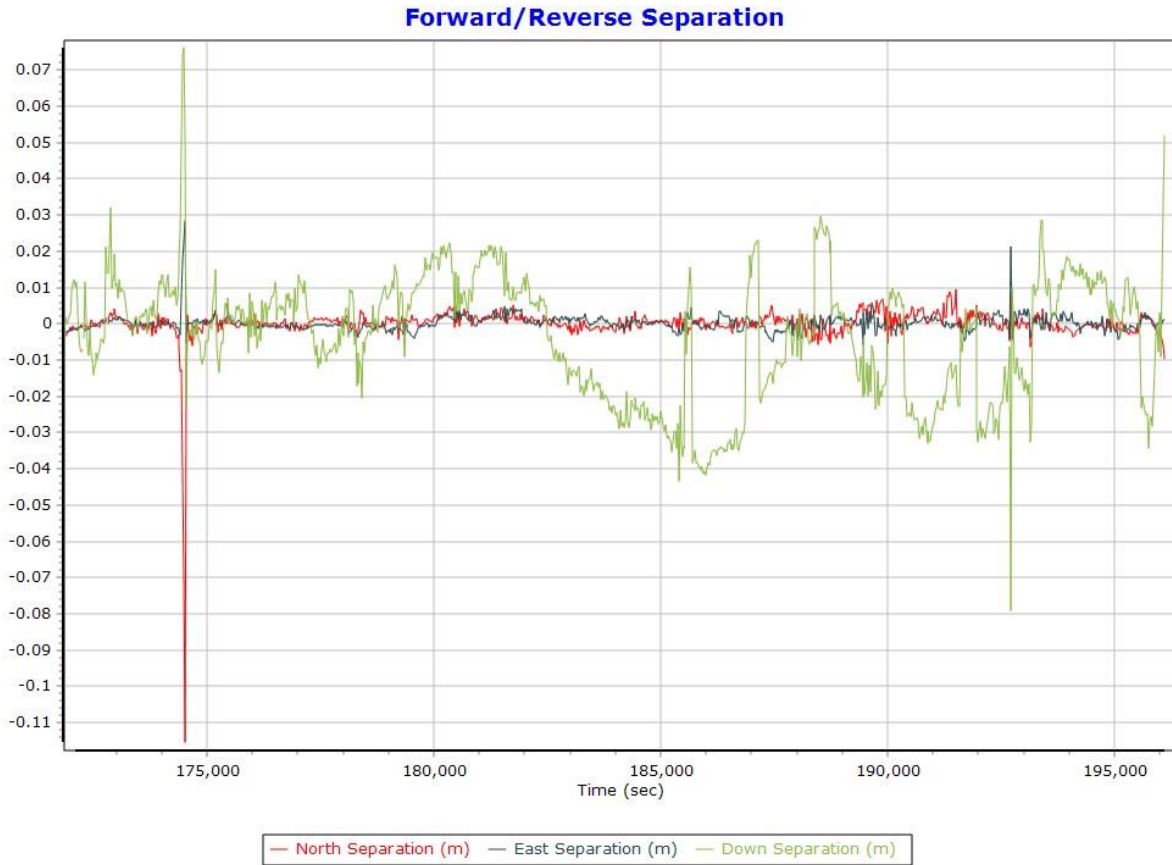
Flight 2

Trajectory Information

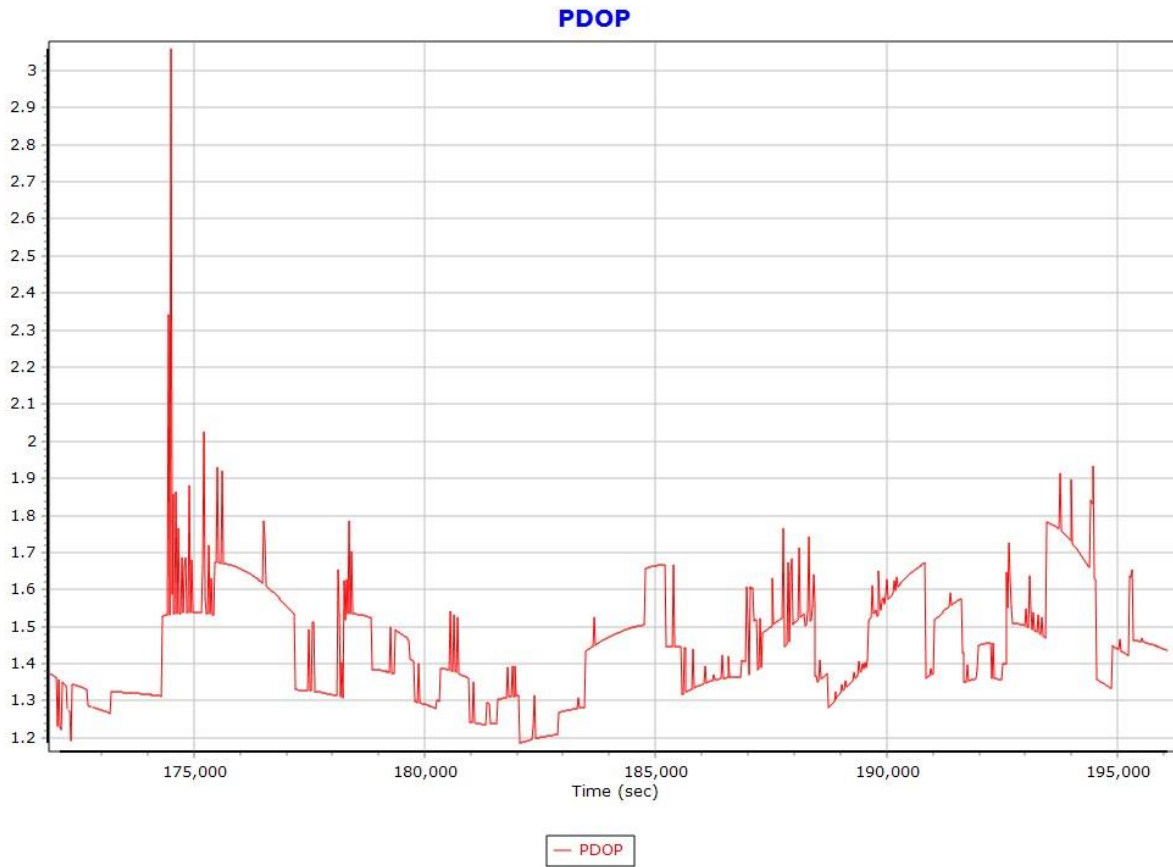
Top View



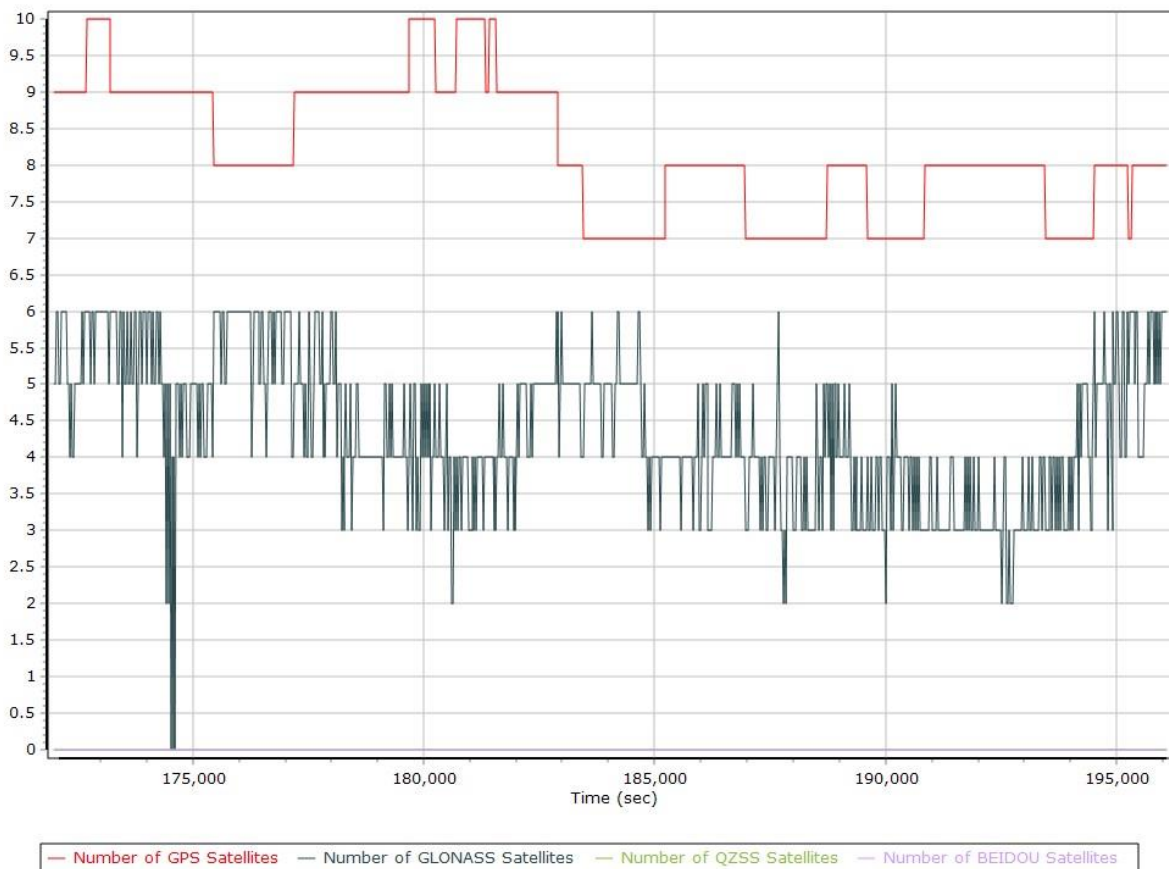
Forward/ Reverse Separation



PDOP



Number of Satellites



Processing Summary Information

Version: 4.30.3108 POSpac MMS 8.2 Project:
flight2
Solution Type: Combined Fwd/Rev

Number of Epochs:

Total in GPB file: 4872613
No processed position: N/A
Missing Fwd or Rev: N/A With
bad C/A code: N/A
With bad L1 Phase: N/A

Project: Task Order # 7 TX West Central

Date: 07.11.2019

Appendix A: GPS and IMU Processing Reports for Flight 2 Page
5 of 18

Measurement RMS Values:

L1 Phase: N/A

C/A Code: N/A

L1 Doppler: N/A

Fwd/Rev Separation RMS Values:

East: Averages from the forward/reverse plot

North: Averages from the forward/reverse plot

Height: Averages from the forward/reverse plot

Fwd/Rev Sep

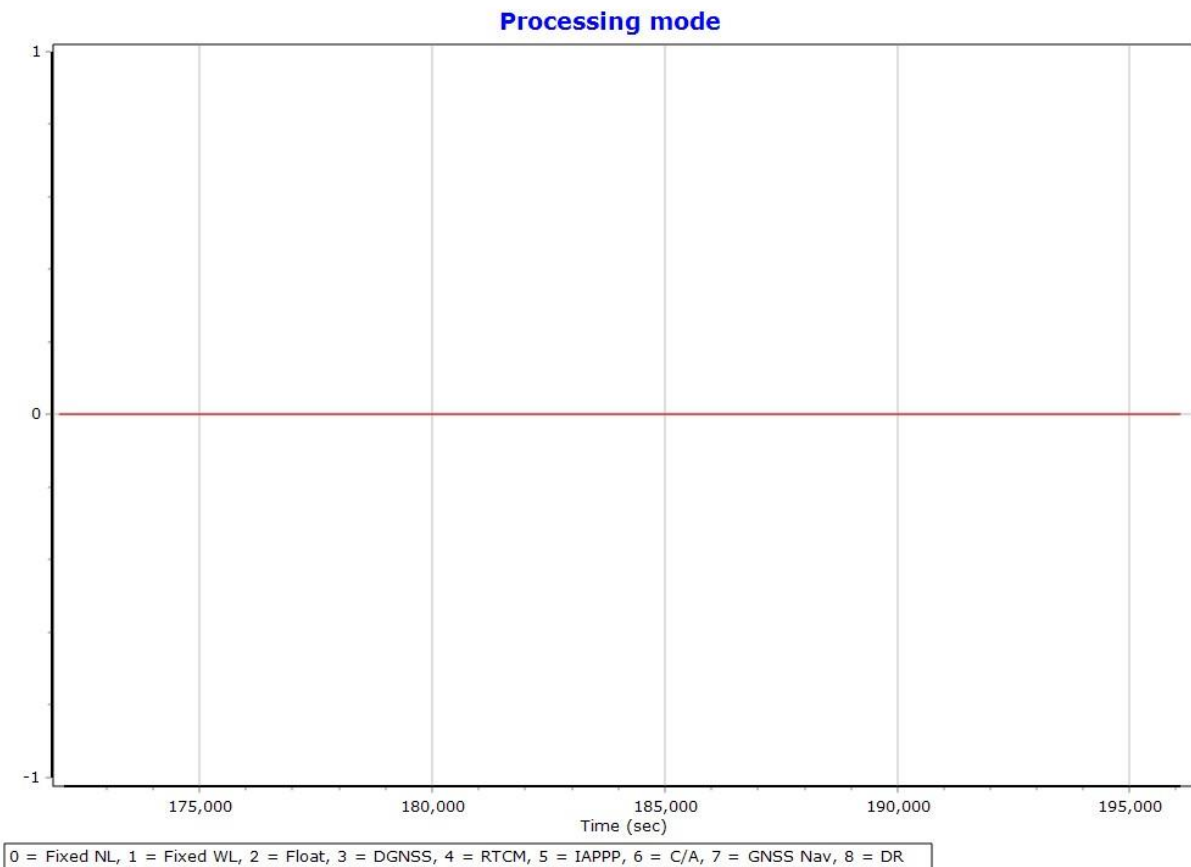
East: N/A

North: N/A

Height: N/A

Smoothed Solution Status

Processing Mode



- Q 1 "Fixed NL": 100% Q
- Q 2 "Fixed WL": 0%
- Q 3 "Float": 0% Q
- Q 4 "DGNSS": 0% Q
- Q 5 "RTCM": 0%
- Q 6 "IAPPP": 0%
- Q 7 "C/A": 0%
- Q 8 "GNSS Nav": 0%
- Q 9 "DR": 0%

Position Standard Deviation Percentages:

- 0.00 - 0.10 m: 100.0 %
- 0.10 - 0.30 m: 0.0 % 0.30
- 1.00 m: 0.0 %
- 1.00 - 5.00 m: 0.0 %
- 5.00 m + over: 0.0 %

Project: Task Order # 7 TX West Central

Date: 07.11.2019

Appendix A: GPS and IMU Processing Reports for Flight 2 Page
7 of 18

Percentages of epochs with DD_DOP over 10.00: 0.0%.

DOP over Tol: 0.0 %

Baseline Distances:

Maximum: 43.693 (km)

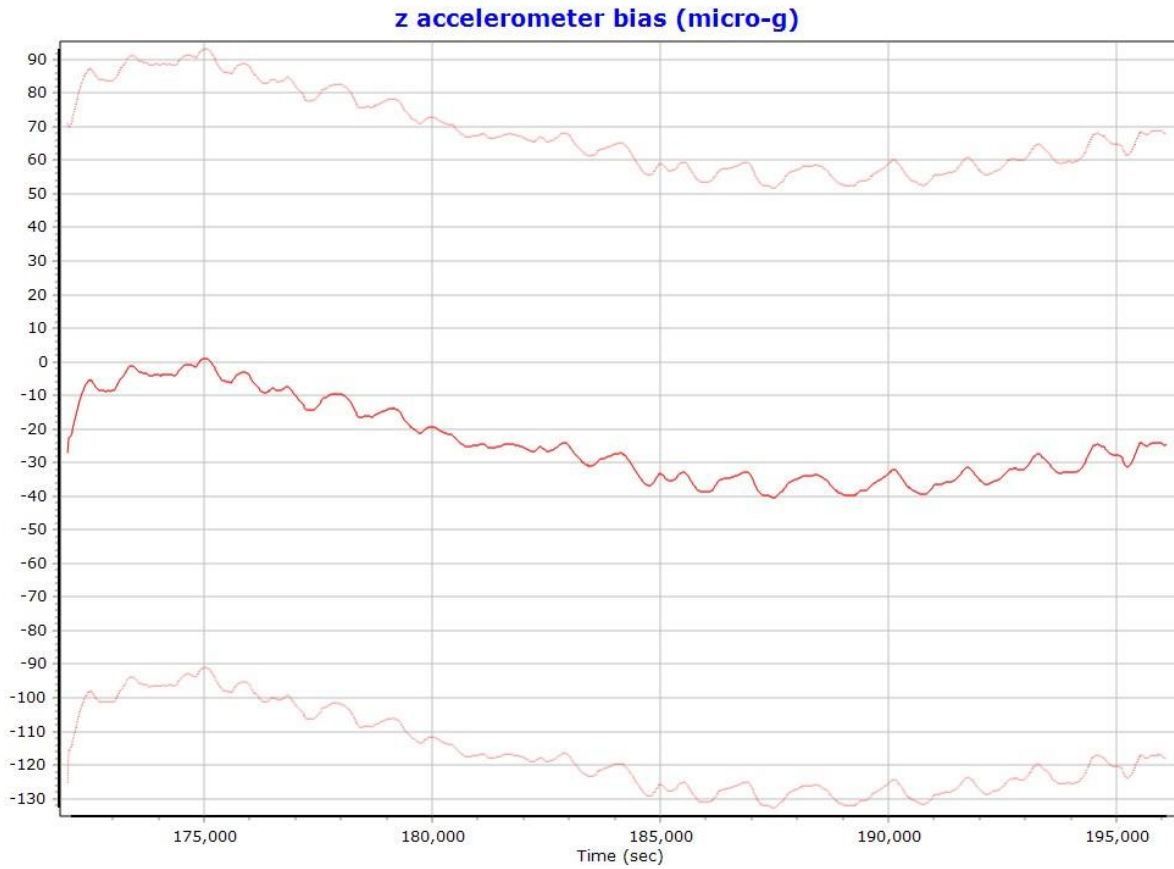
Minimum: 0.395 (km) Average:

~22 (km)

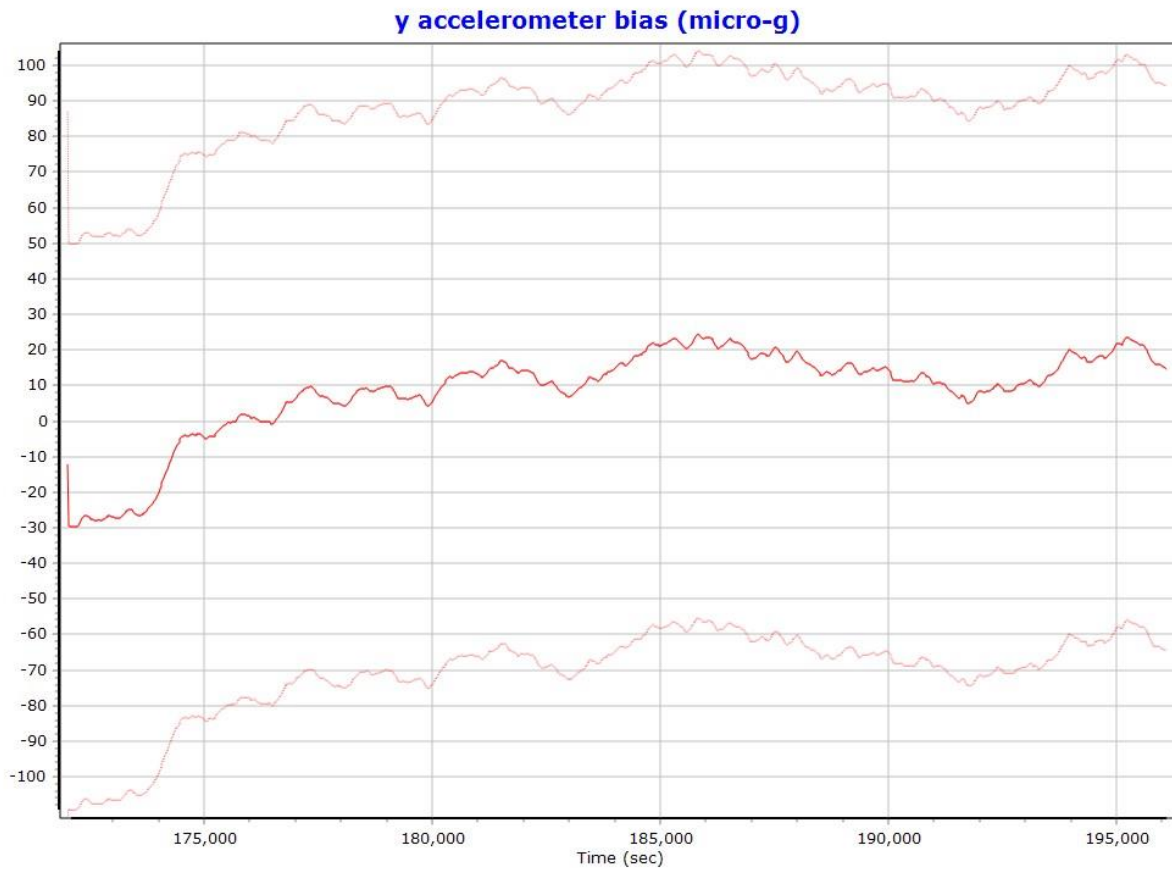
First Epoch: 0.738 (km) Last

Epoch: 0.569 (km)

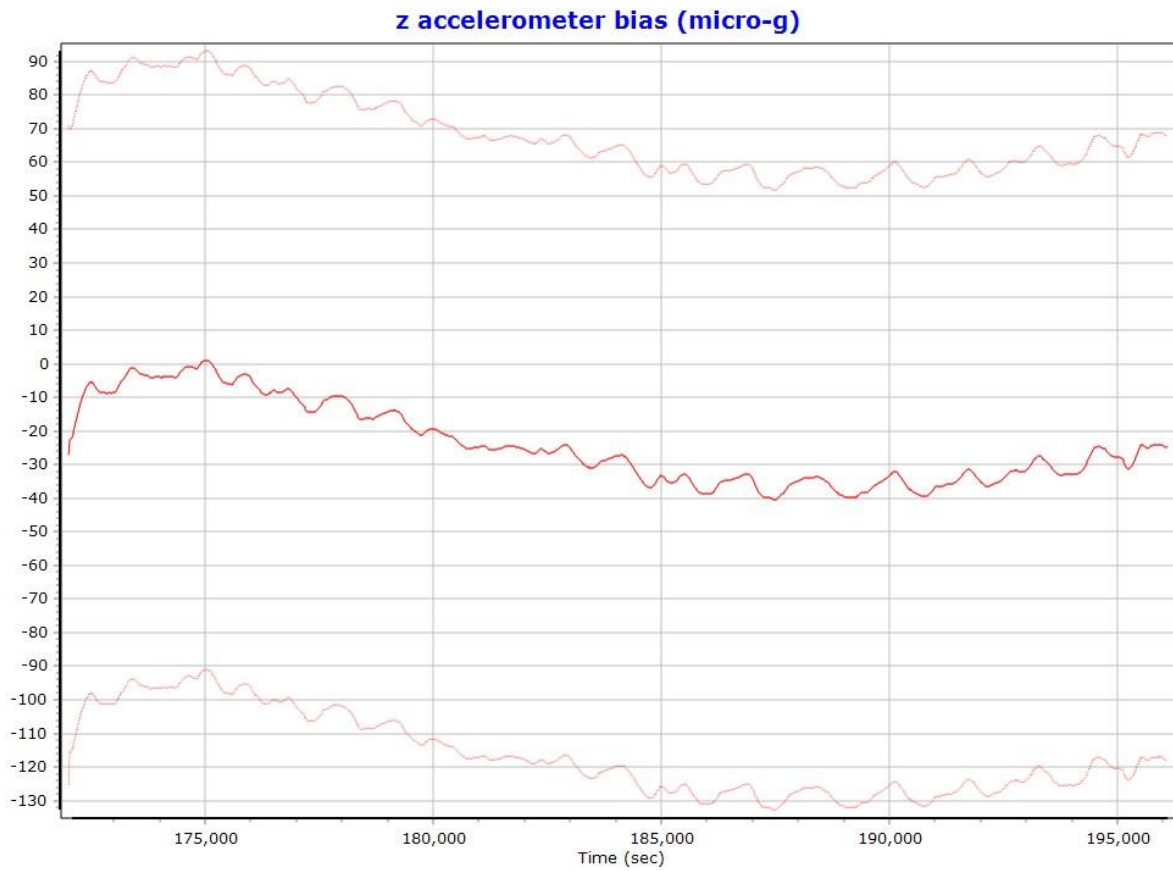
Sensor Errors X Accelerometer Bias (micro-g)



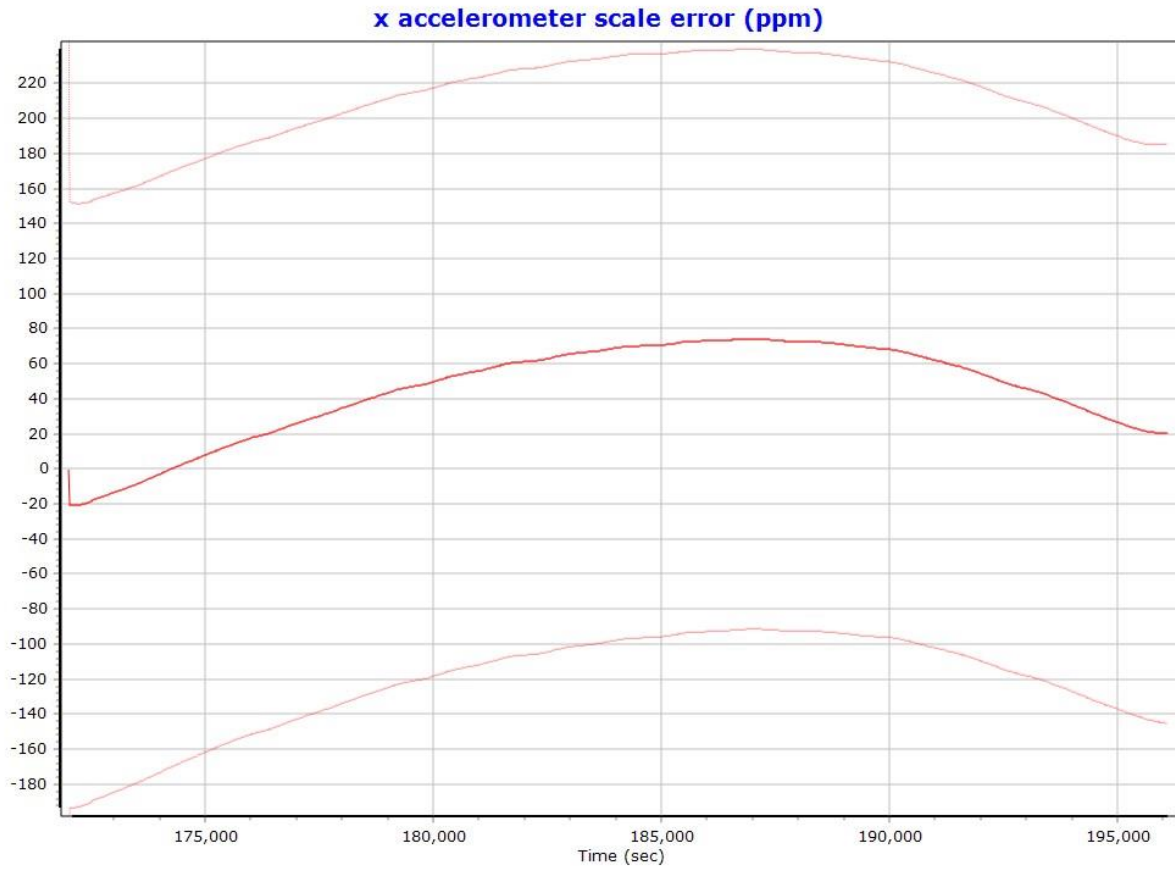
Y Accelerometer Bias (micro-g)



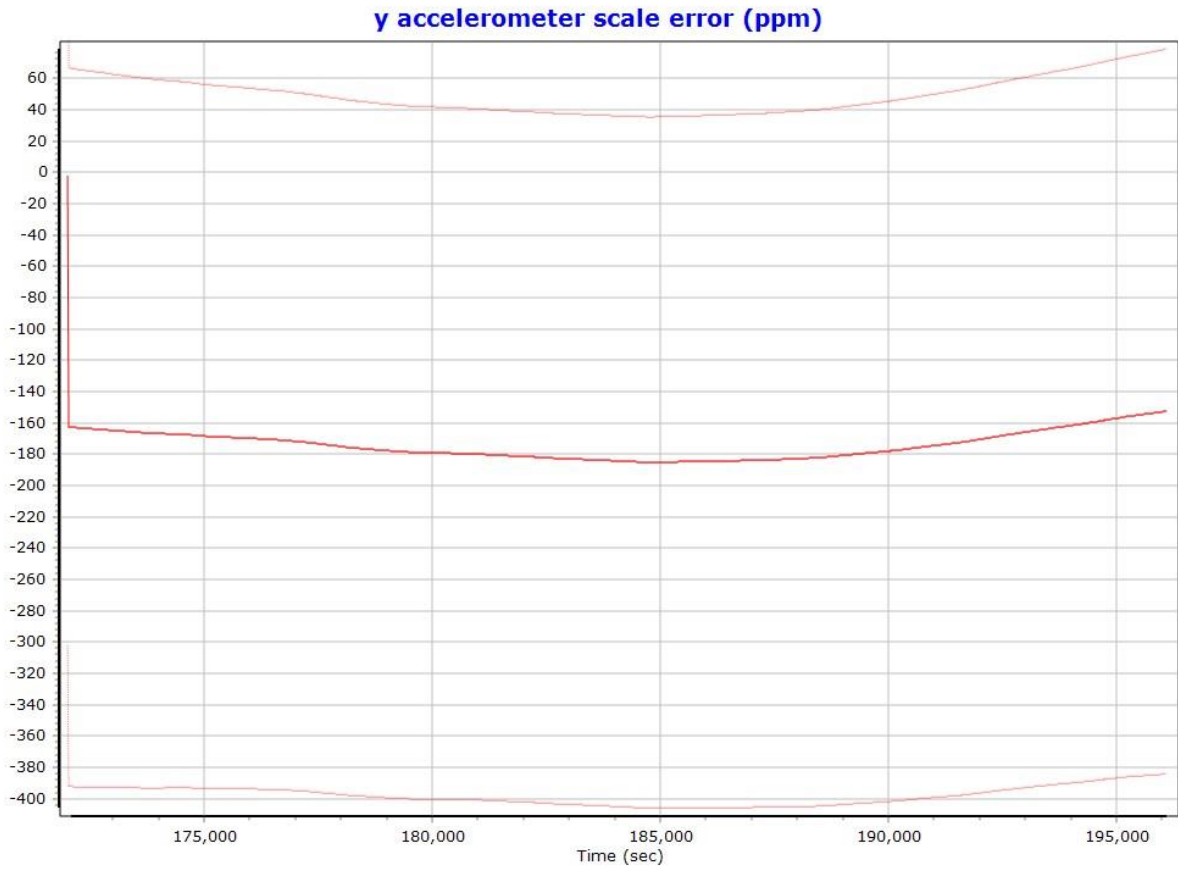
Z Accelerometer Bias (micro-g)



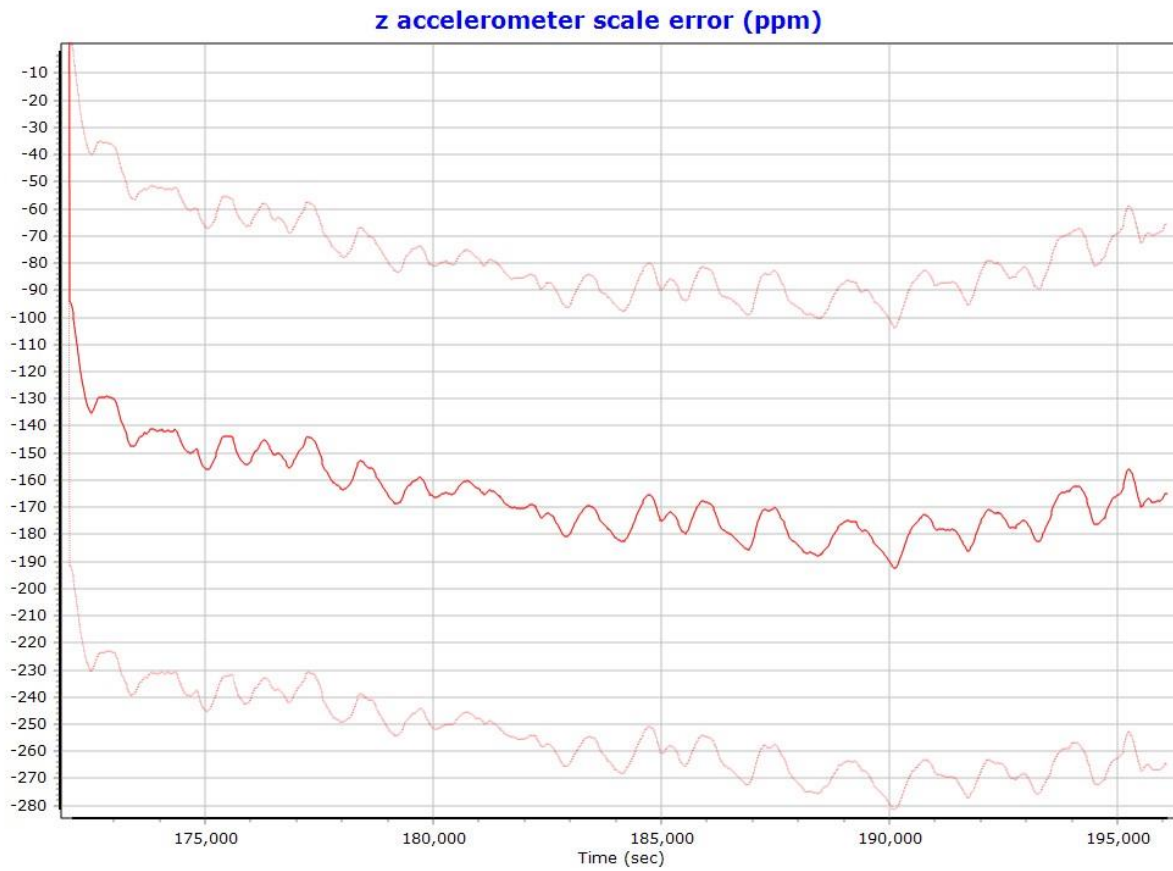
X Accelerometer Scale Error (ppm)



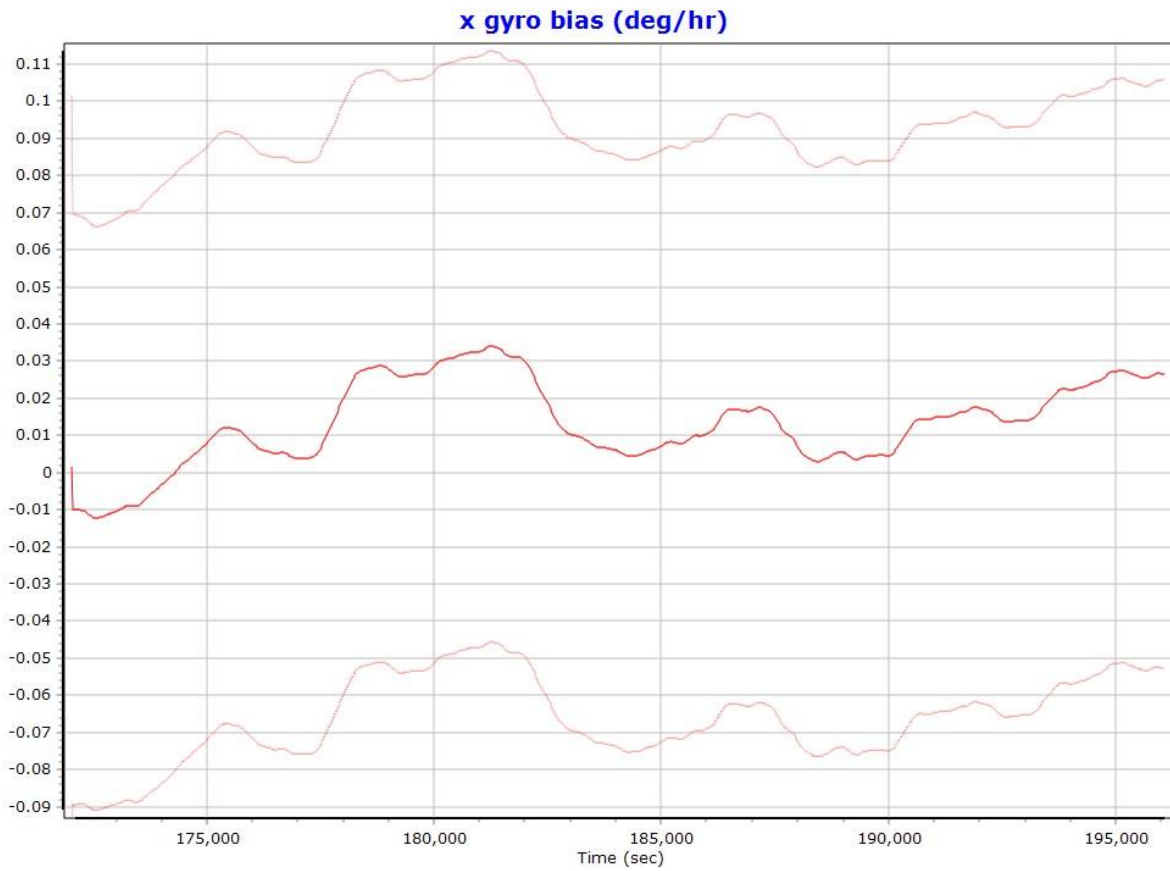
Y Accelerometer Scale Error (ppm)



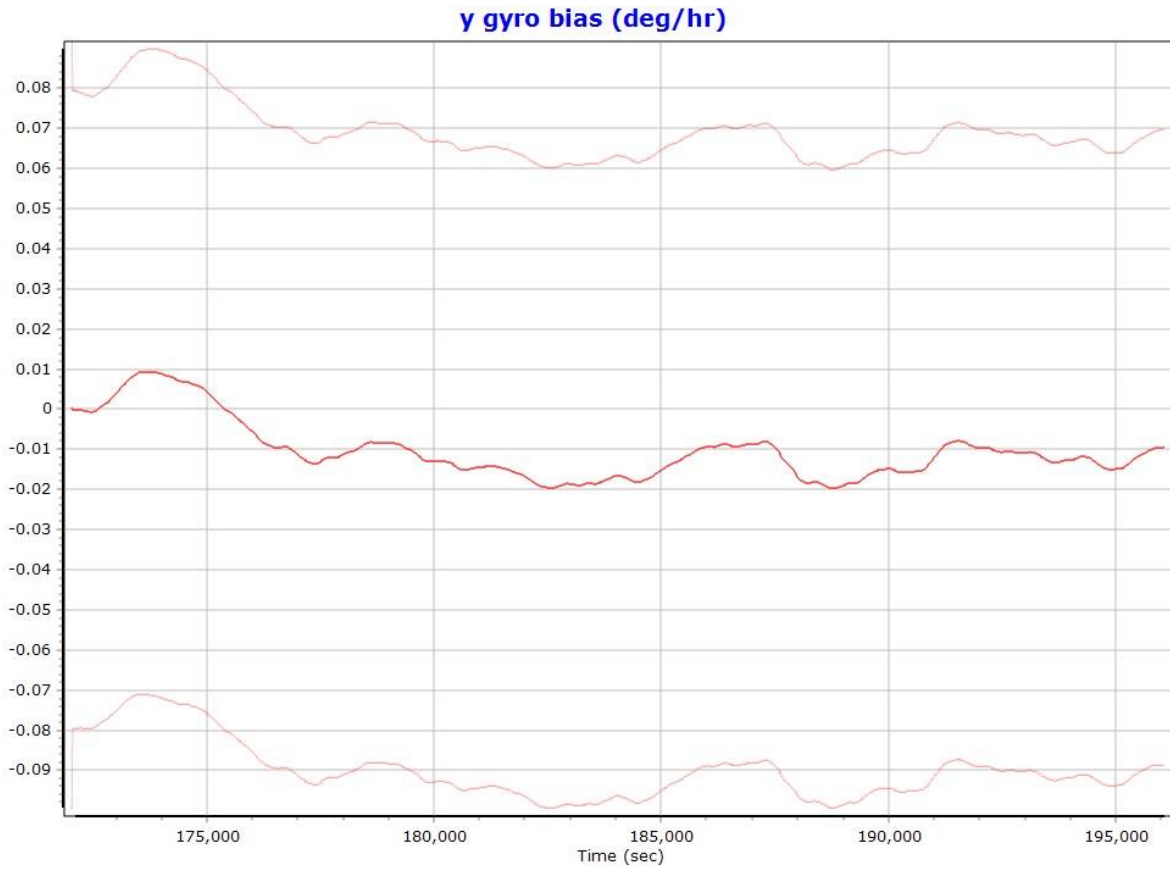
Z Accelerometer Scale Error (ppm)



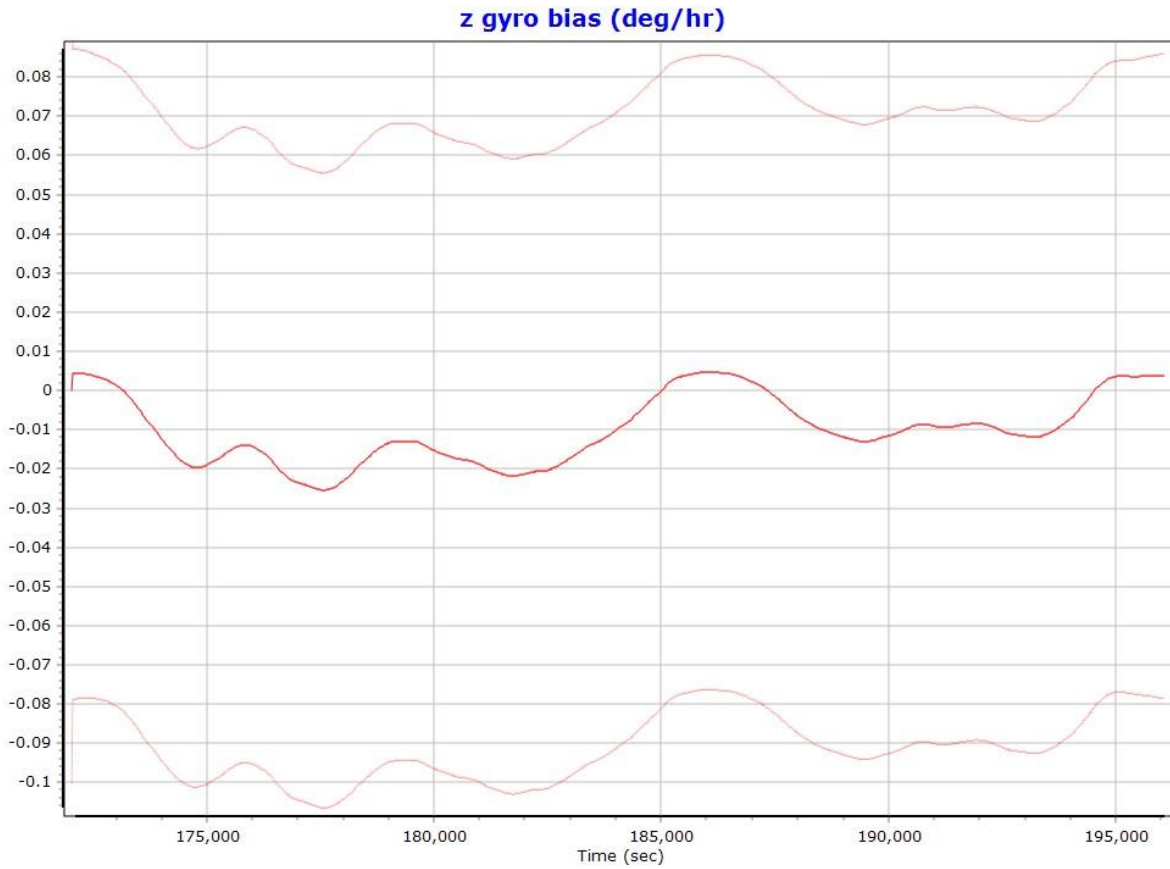
X Gyro Bias (deg/h)



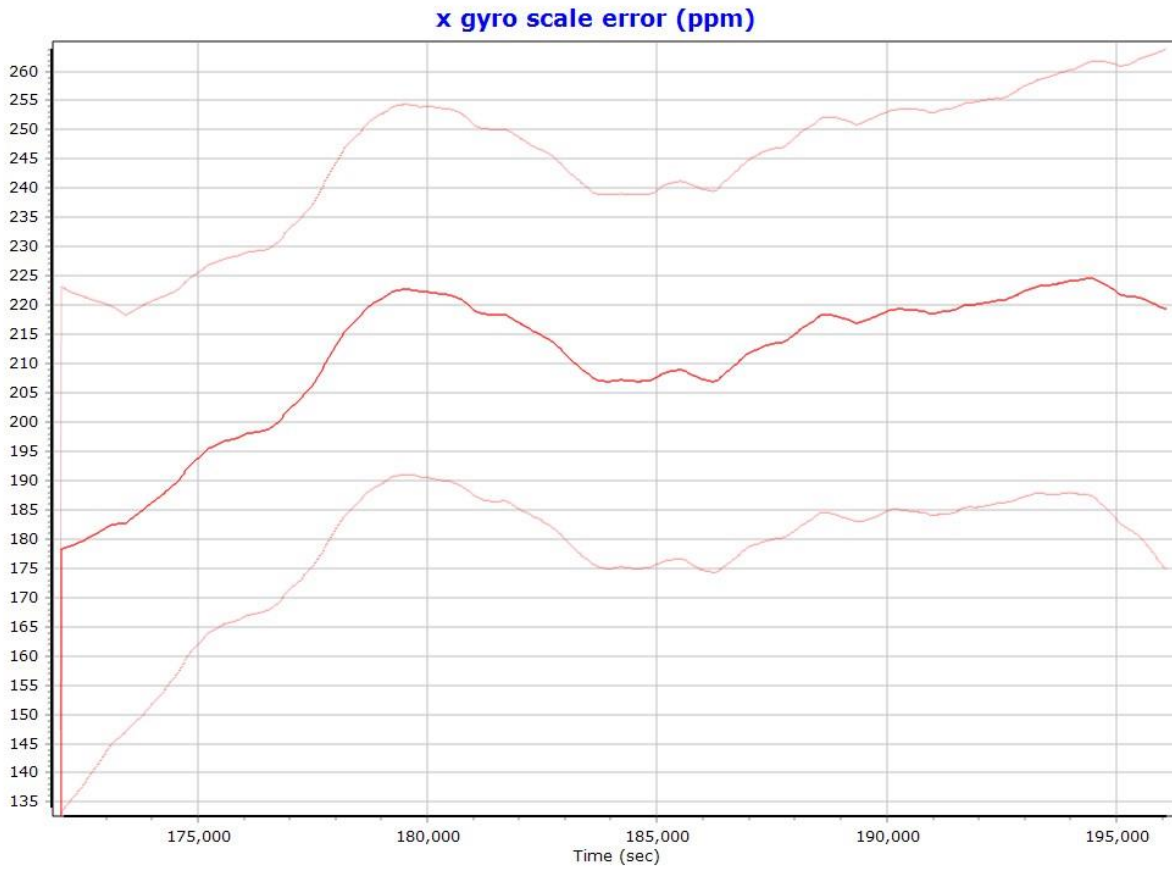
Y Gyro Bias (deg/h)



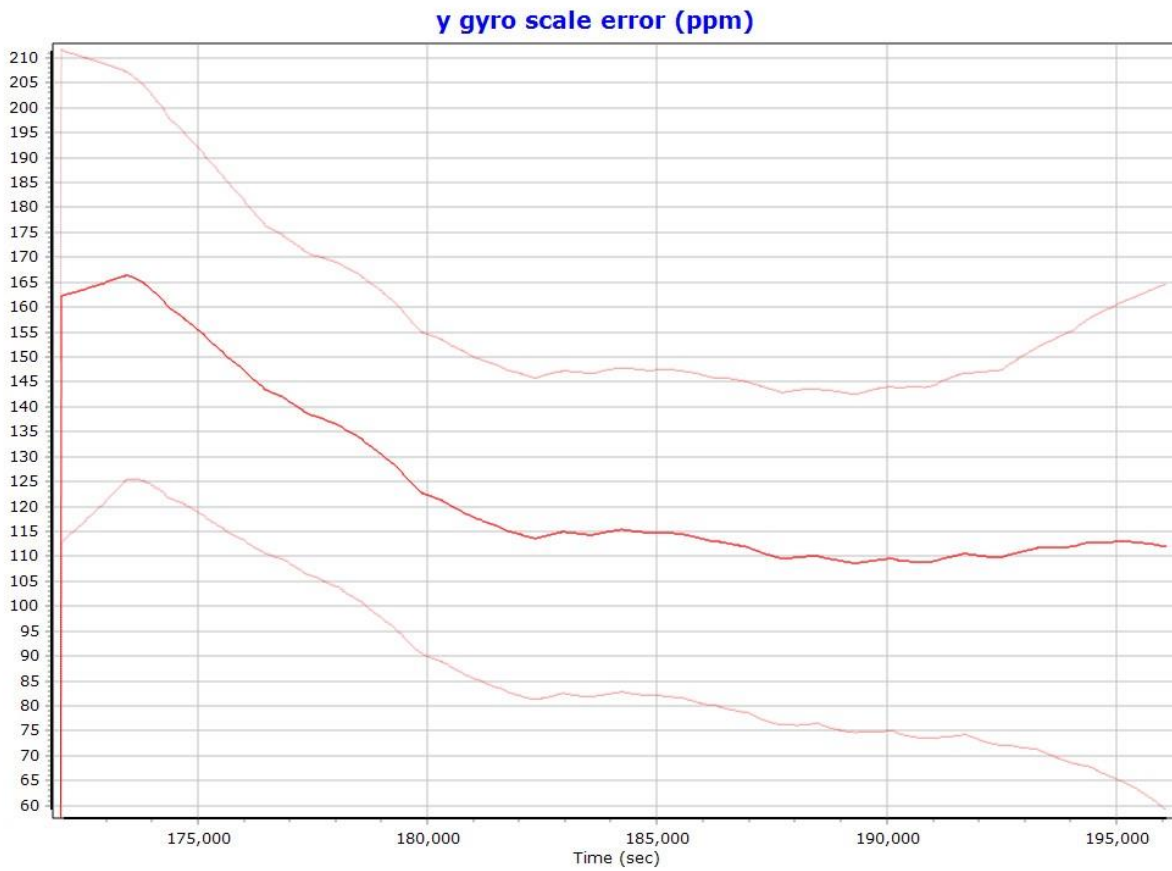
Z Gyro Bias (deg/h)



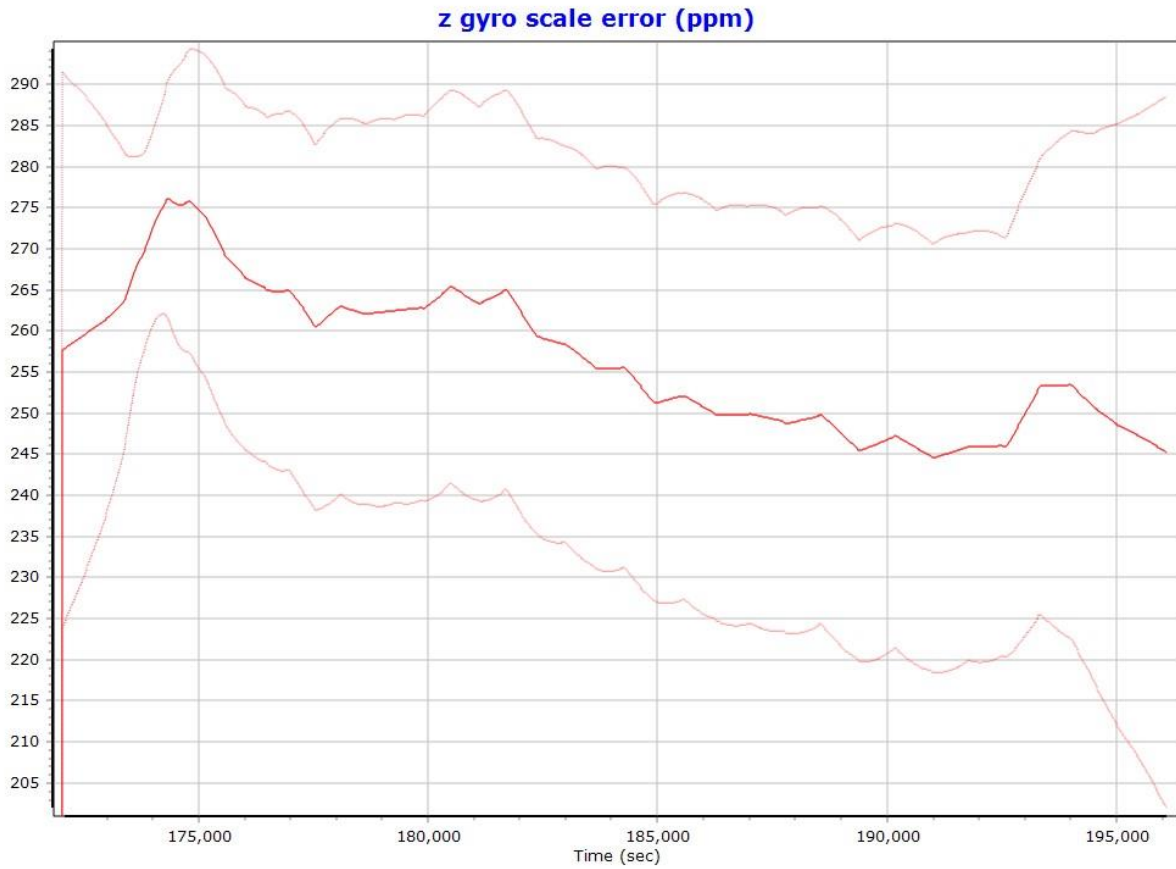
X Gyro Scale Error (ppm)



Y Gyro Scale Error (ppm)



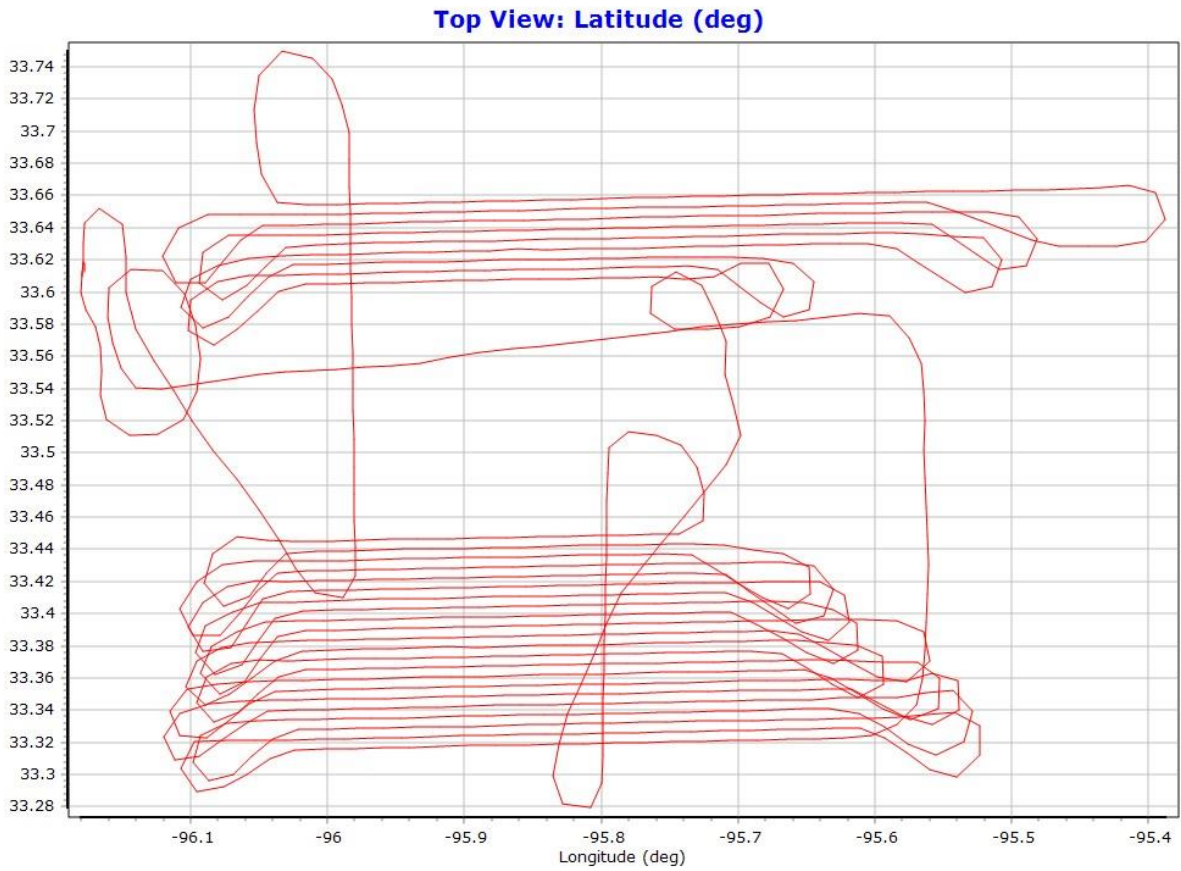
Z Gyro Scale Error (ppm)



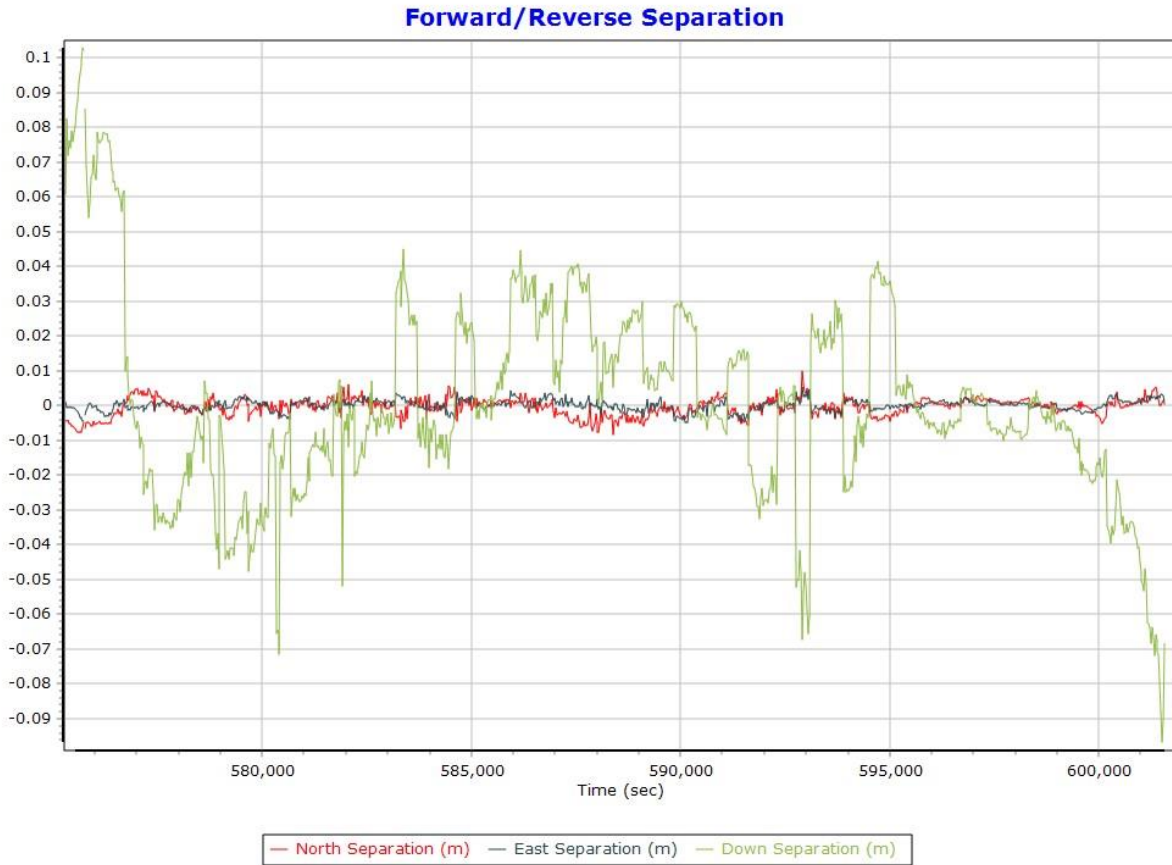
Flight 3

Trajectory Information

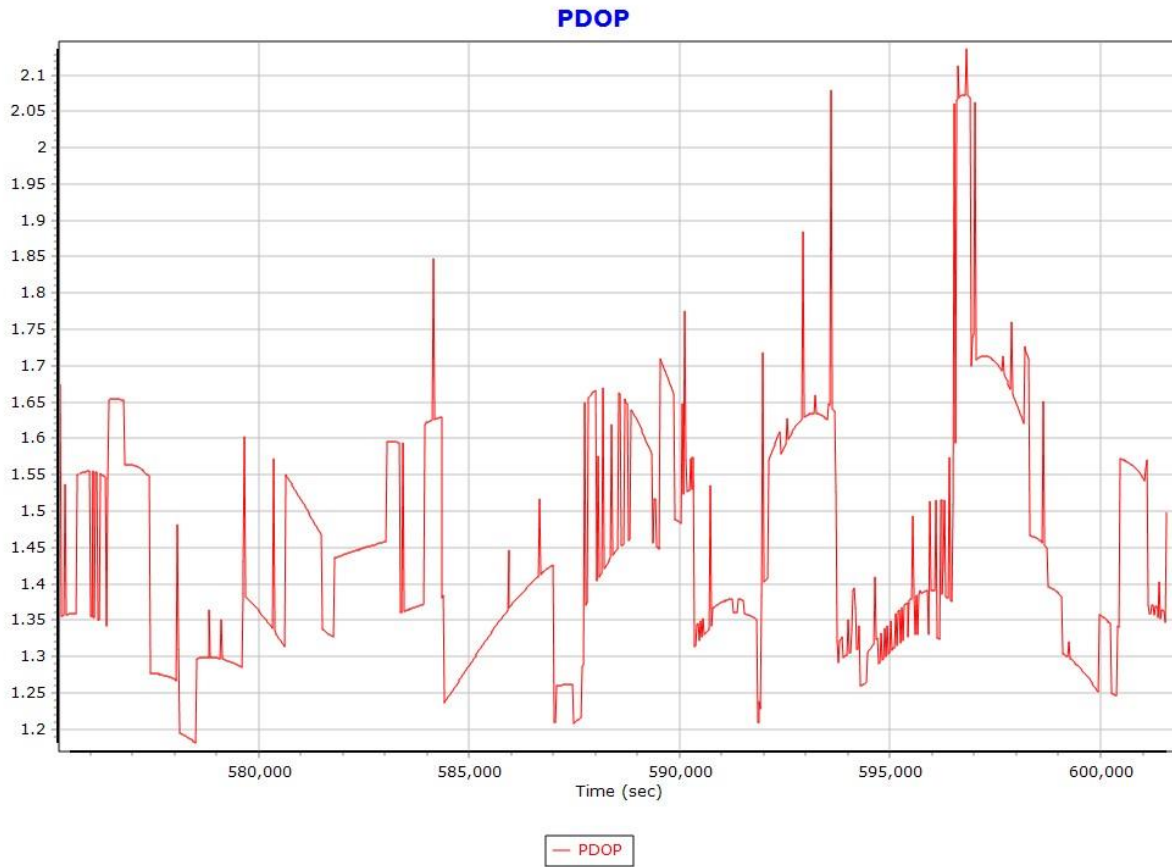
Top View



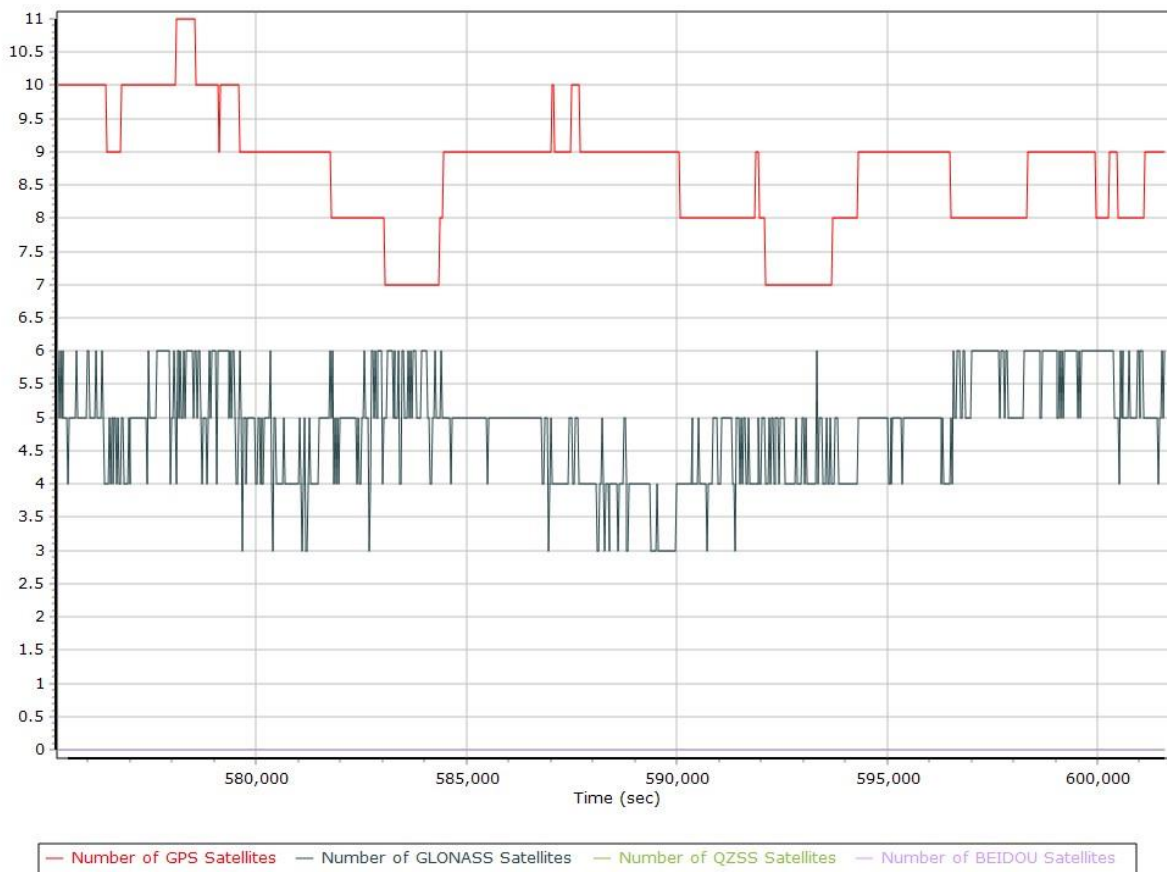
Forward/ Reverse Separation



PDOP



Number of Satellites



Processing Summary Information

Version: 4.30.3108 POSpac MMS 8.2
Project: flight3
Solution Type: Combined Fwd/Rev

Number of Epochs:

Total in GPB file: 5267538
No processed position: N/A
Missing Fwd or Rev: N/A With
bad C/A code: N/A
With bad L1 Phase: N/A

Project: Task Order # 7 TX West Central

Date: 07.11.2019

Appendix A: GPS and IMU Processing Reports for Flight 3 Page
5 of 18

Measurement RMS Values:

L1 Phase: N/A

C/A Code: N/A

L1 Doppler: N/A

Fwd/Rev Separation RMS Values:

East: Averages from the forward/reverse plot

North: Averages from the forward/reverse plot

Height: Averages from the forward/reverse plot

Fwd/Rev Sep

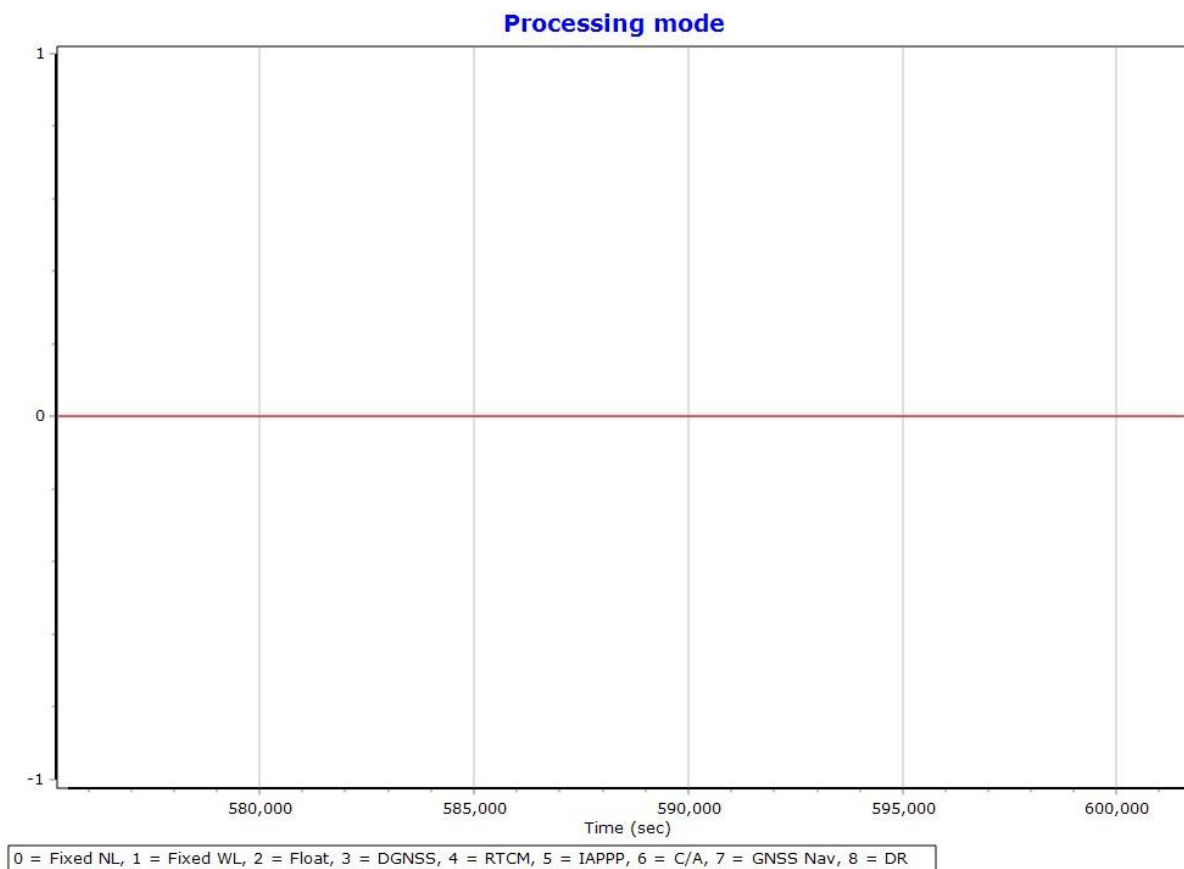
East: N/A

North: N/A

Height: N/A

Smoothed Solution Status

Processing Mode



Q 1 "Fixed NL": 100% Q

Q 2 "Fixed WL": 0%

Q 3 "Float": 0% Q

Q 4 "DGNSS": 0% Q

Q 5 "RTCM": 0%

Q 6 "IAPPP": 0%

Q 7 "C/A": 0%

Q 8 "GNSS Nav": 0%

Q 9 "DR": 0%

Position Standard Deviation Percentages:

0.00 - 0.10 m: 100.0 %

0.10 - 0.30 m: 0.0 % 0.30

- 1.00 m: 0.0 %

1.00 - 5.00 m: 0.0 %

5.00 m + over: 0.0 %

Project: Task Order # 7 TX West Central

Date: 07.11.2019

Appendix A: GPS and IMU Processing Reports for Flight 3 Page
7 of 18

Percentages of epochs with DD_DOP over 10.00: 0.0%.

DOP over Tol: 0.0 %

Baseline Distances:

Maximum: 41.928 (km)

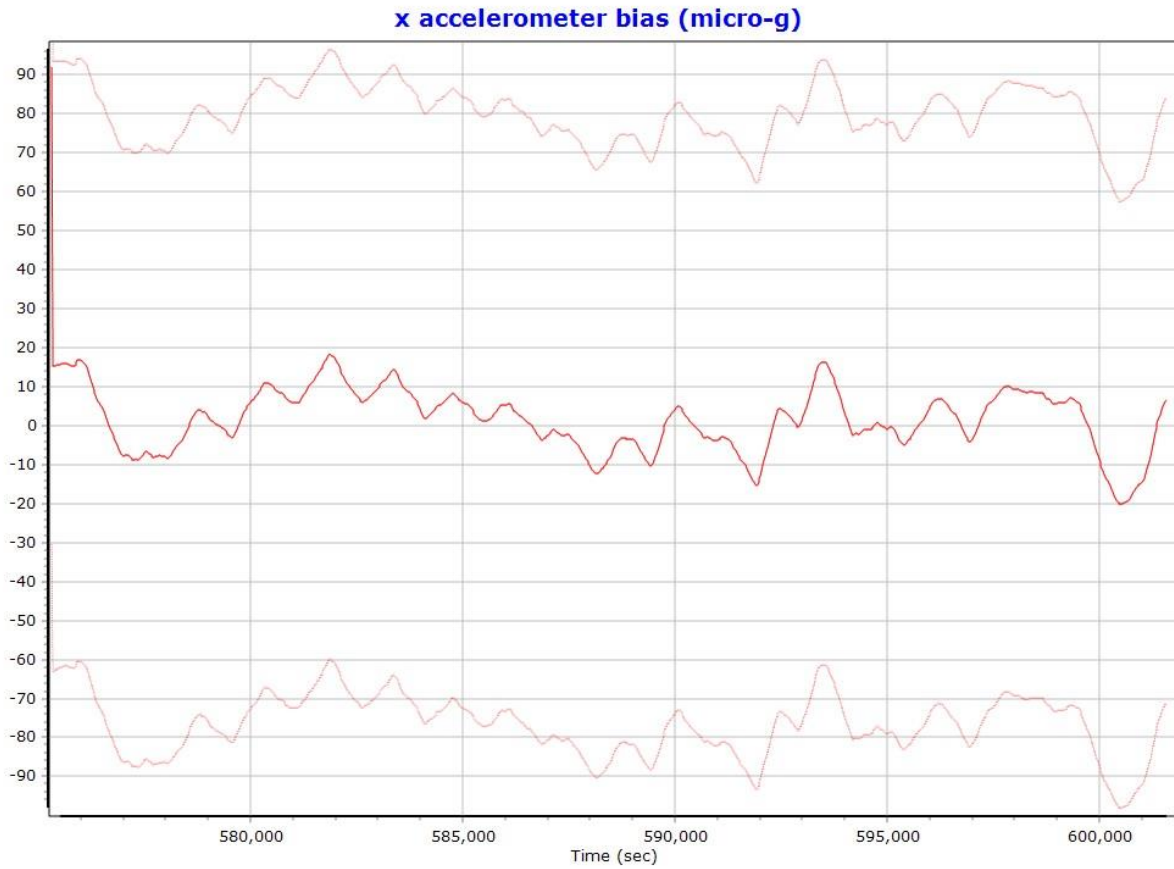
Minimum: 0.406 (km) Average:

~30 (km)

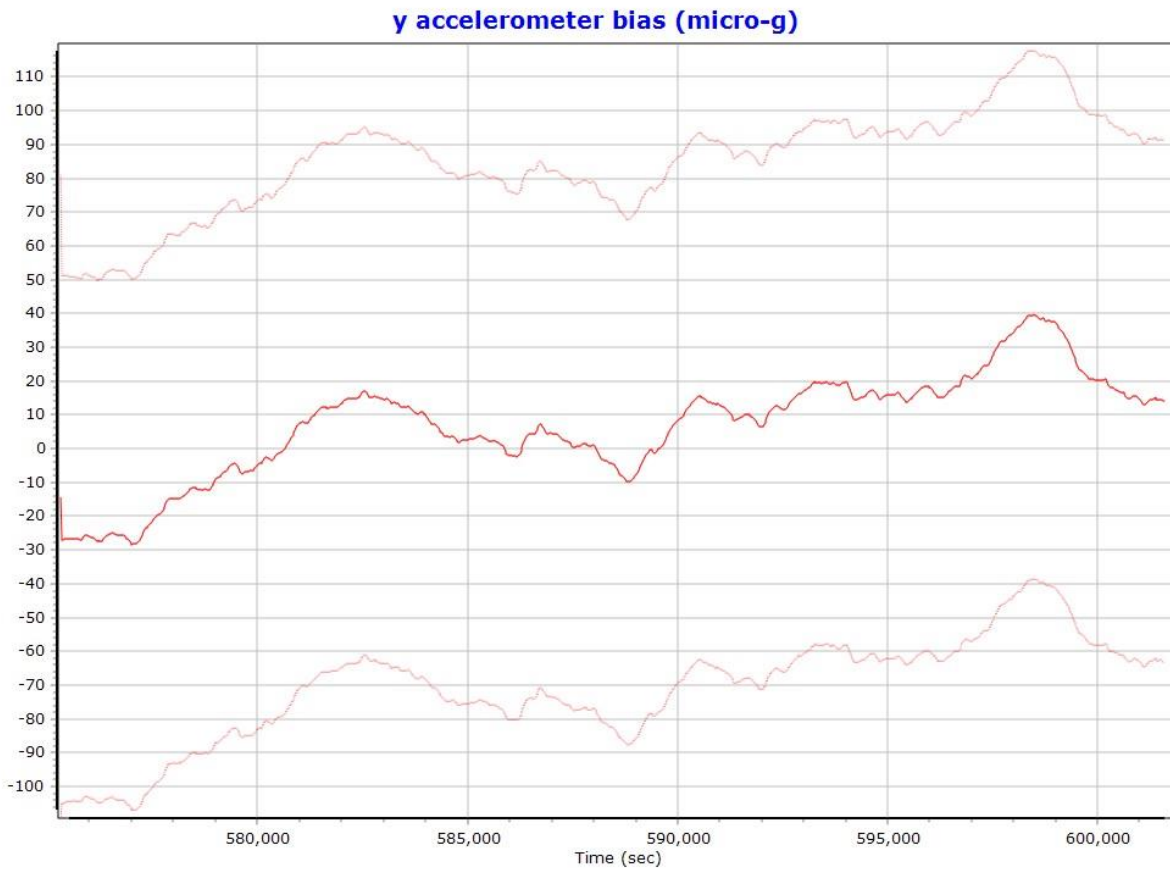
First Epoch: 0.720 (km) Last

Epoch: 0.680 (km)

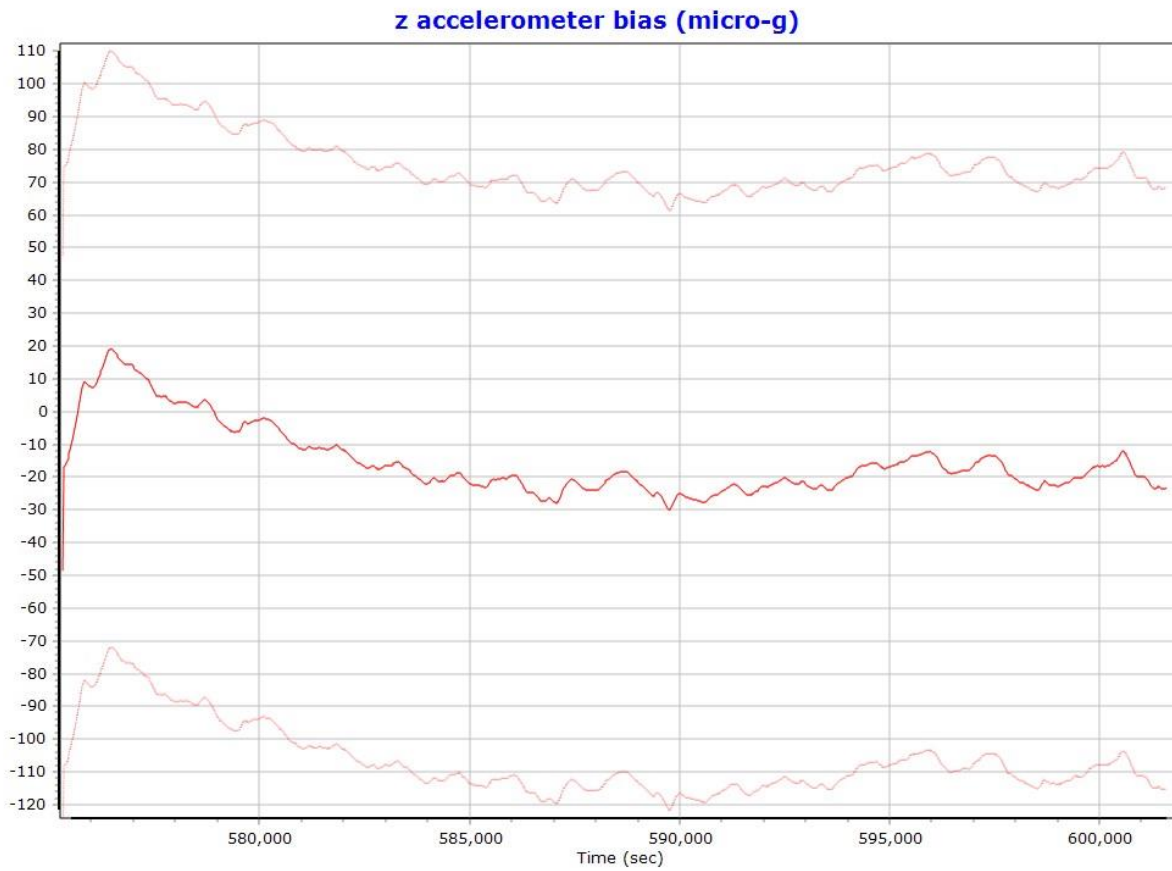
Sensor Errors X Accelerometer Bias (micro-g)



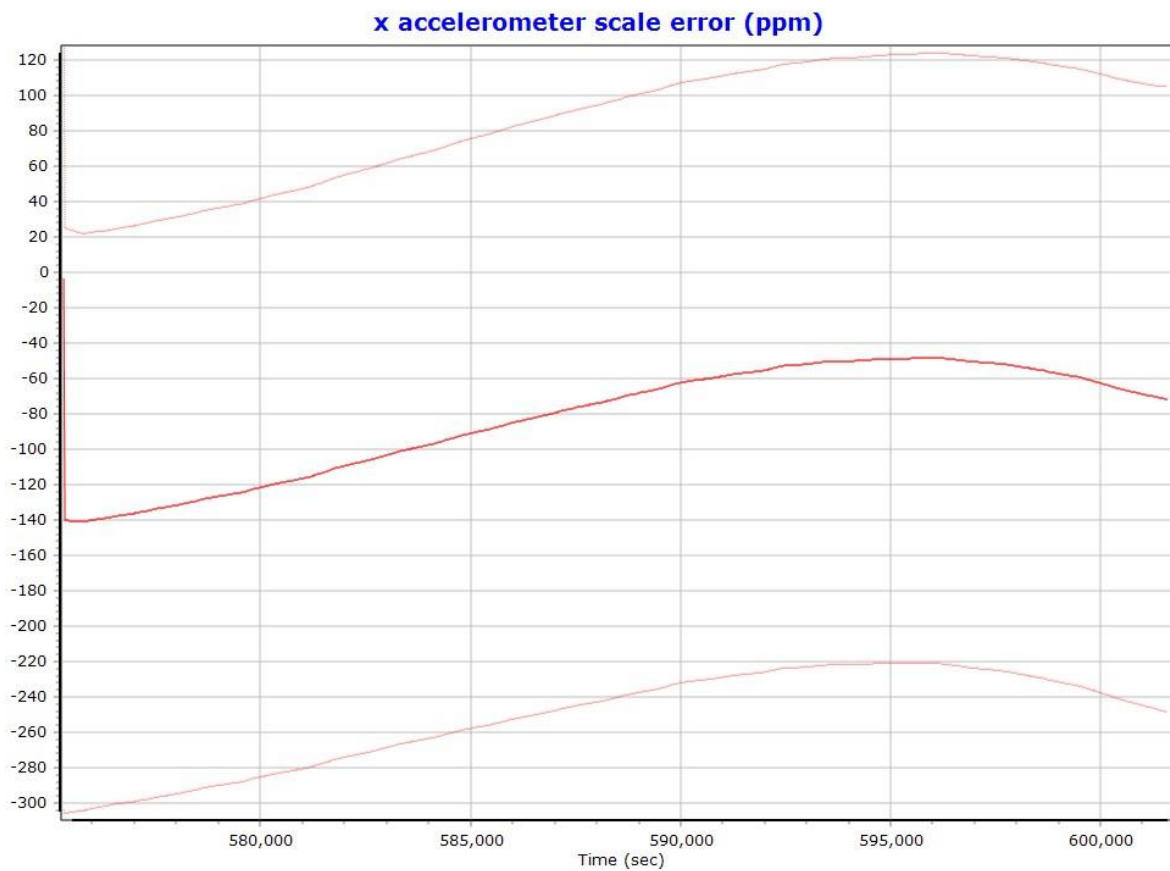
Y Accelerometer Bias (micro-g)



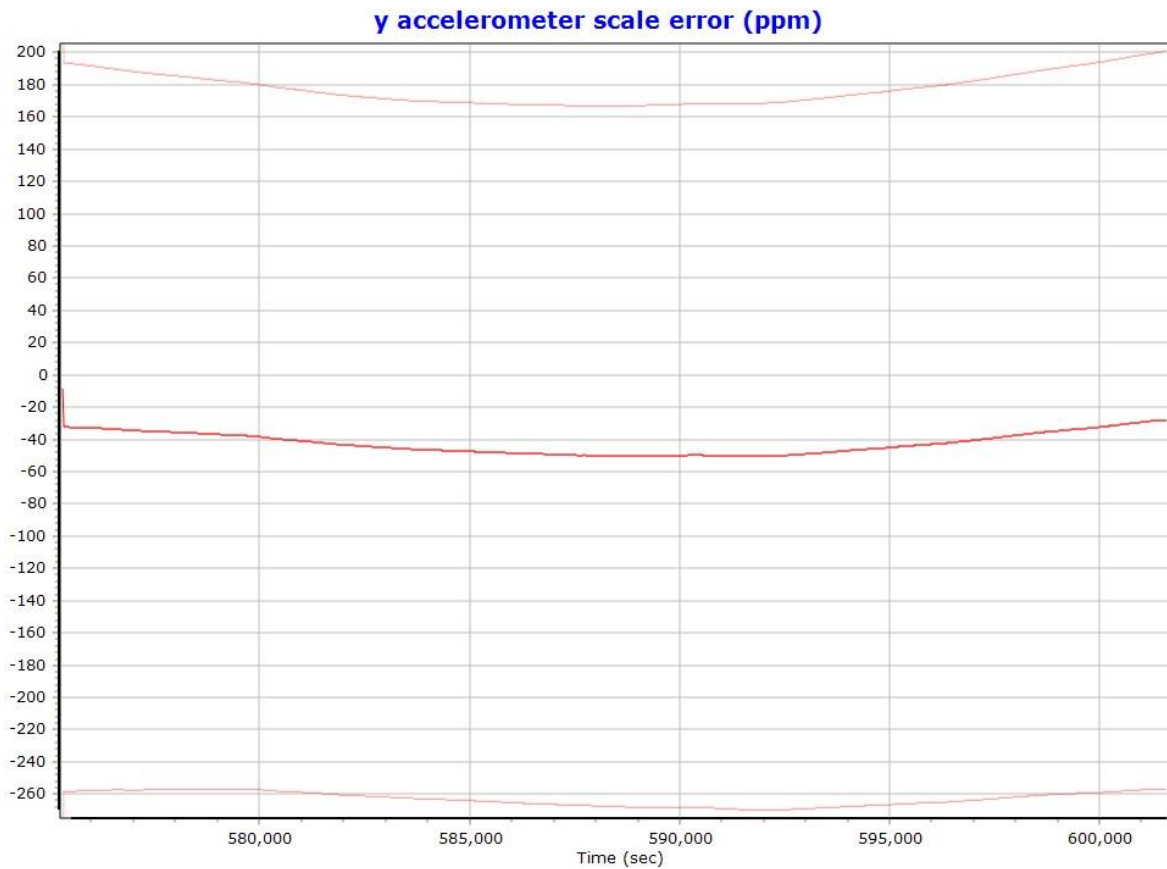
Z Accelerometer Bias (micro-g)



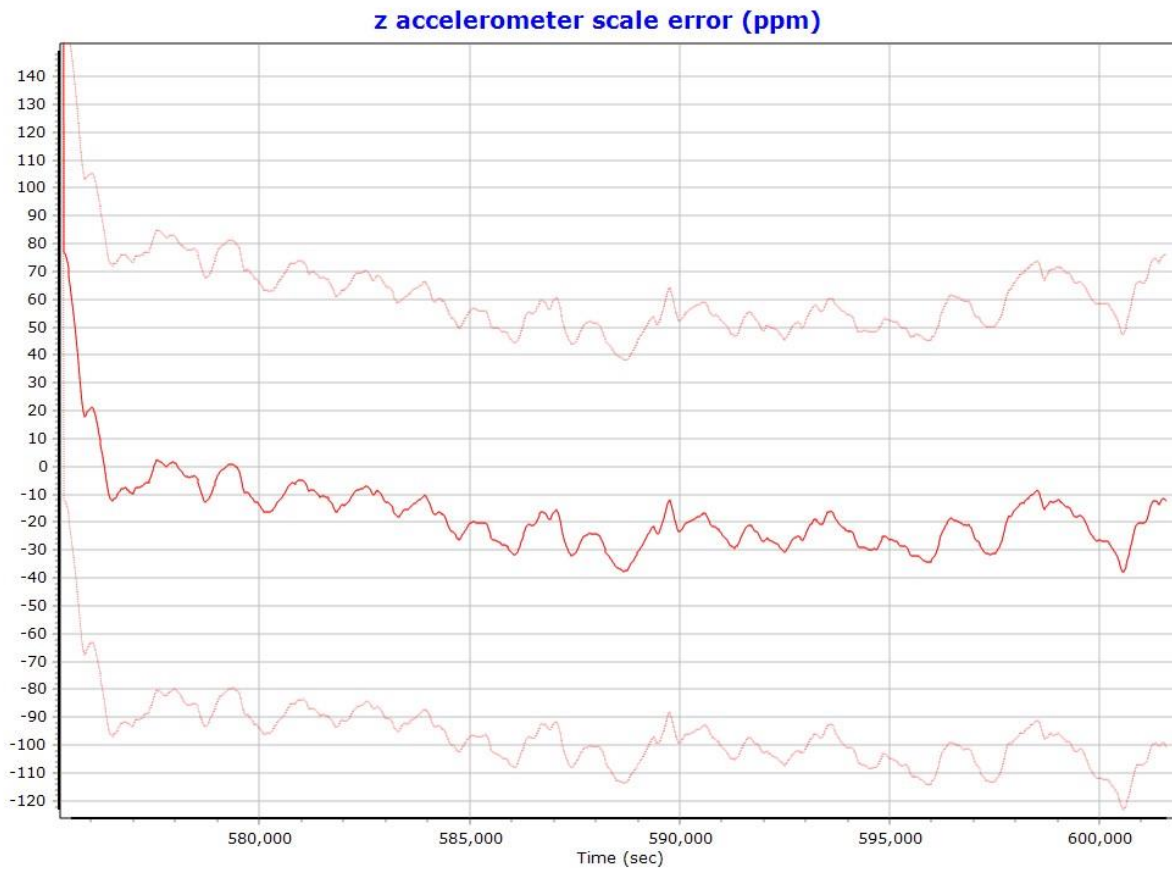
X Accelerometer Scale Error (ppm)



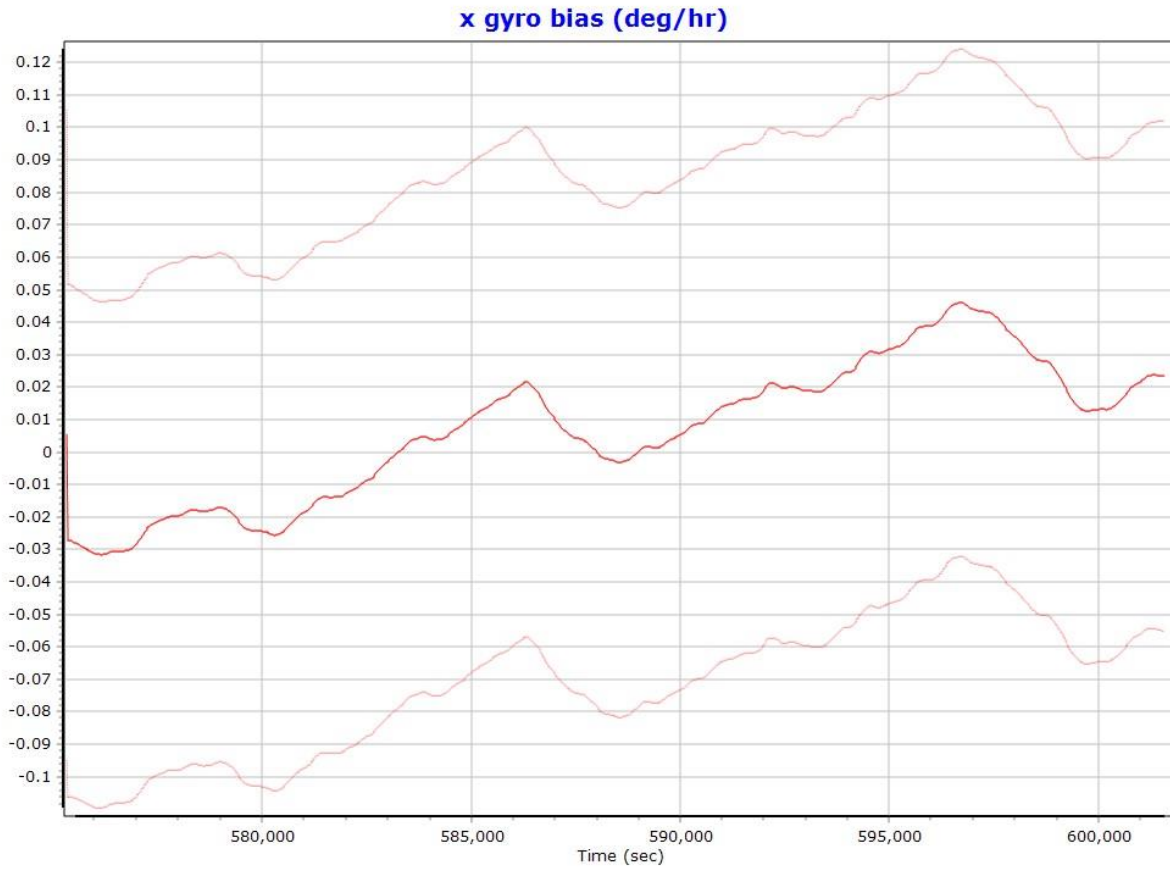
Y Accelerometer Scale Error (ppm)



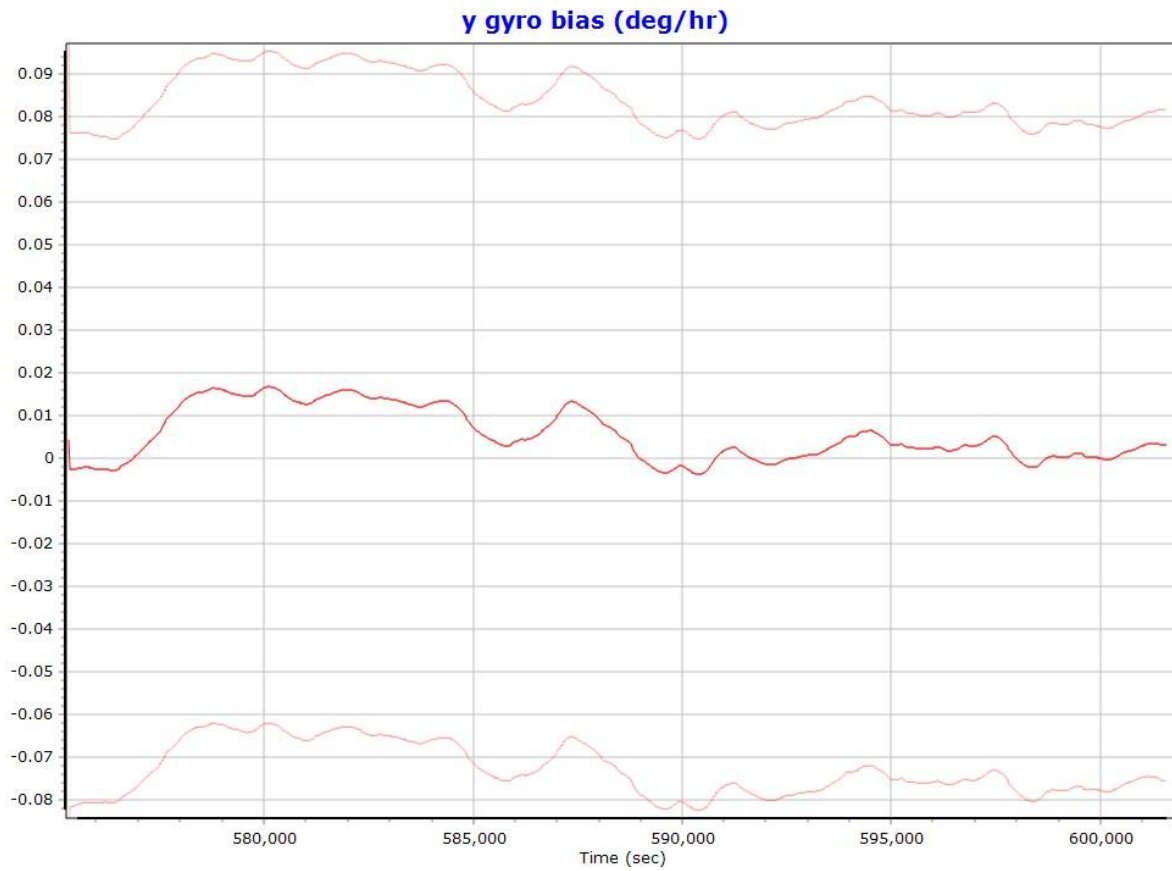
Z Accelerometer Scale Error (ppm)



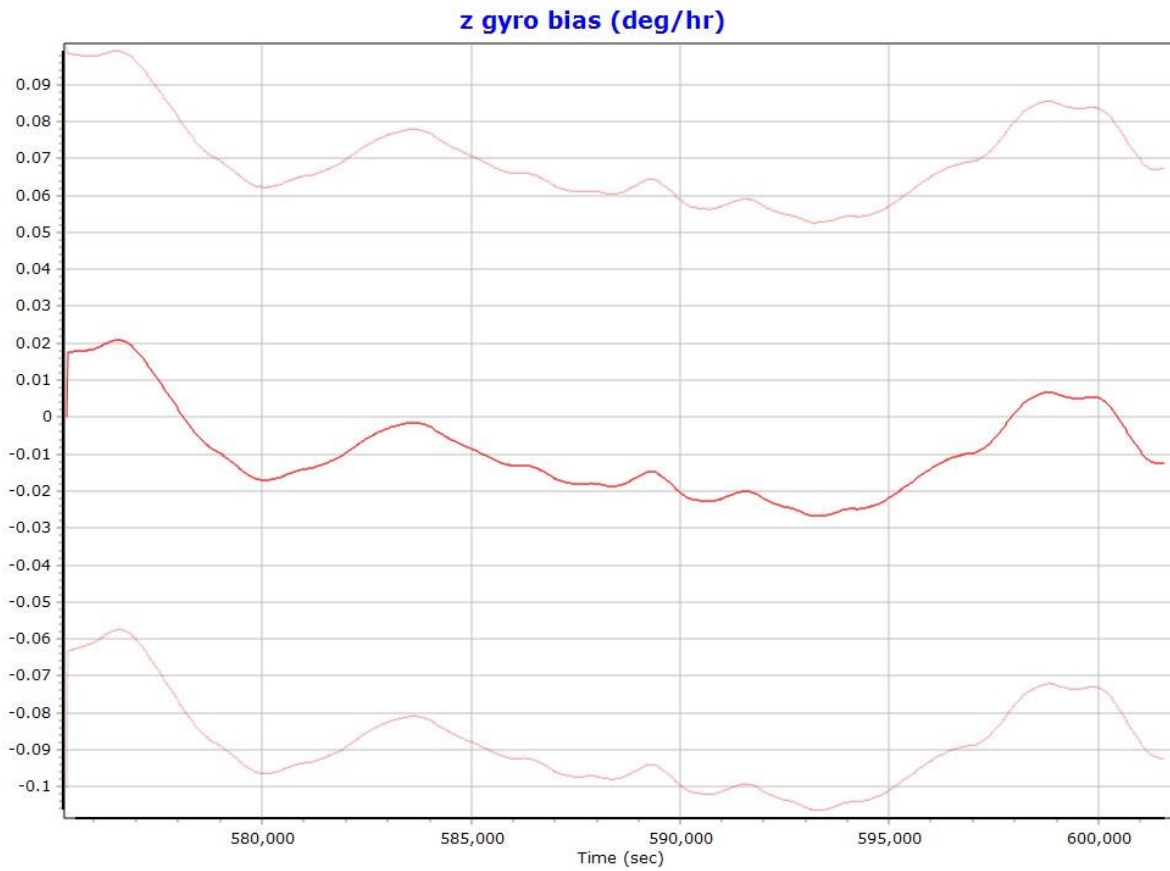
X Gyro Bias (deg/h)



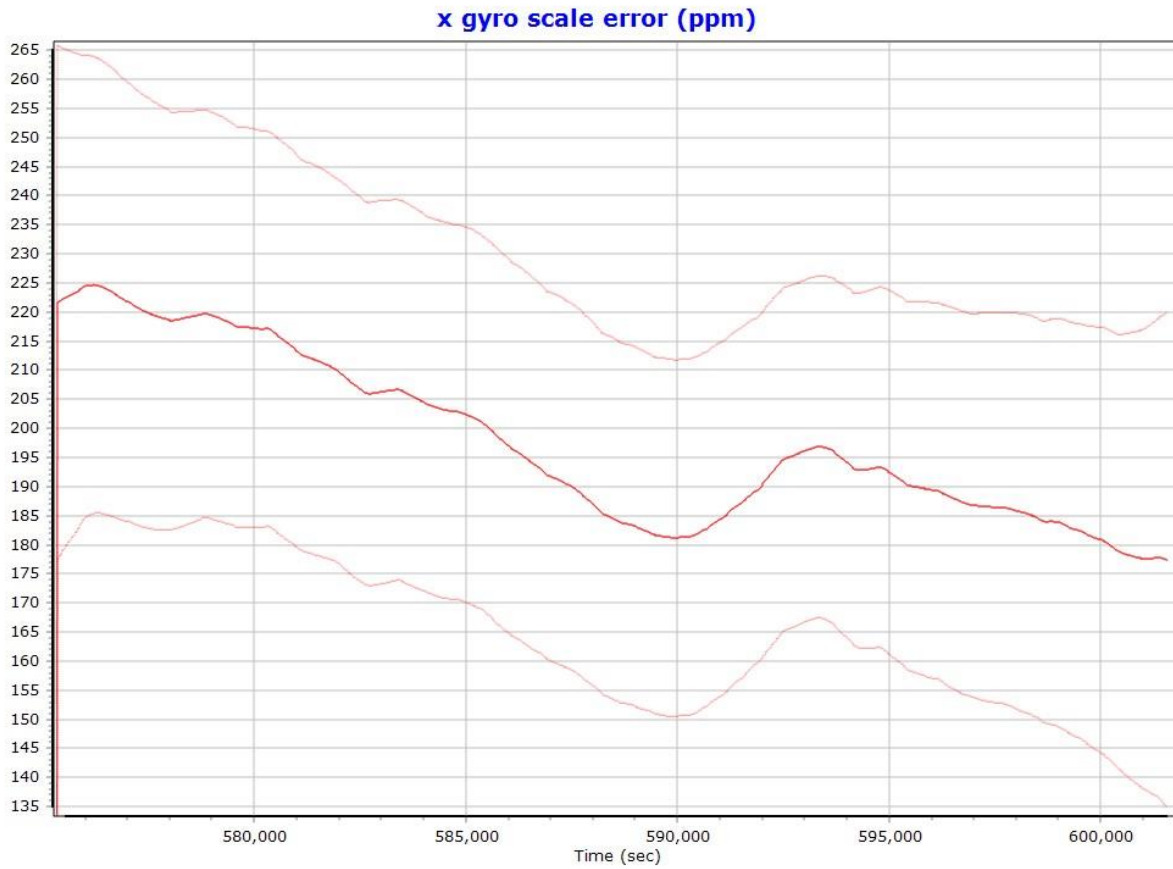
Y Gyro Bias (deg/h)



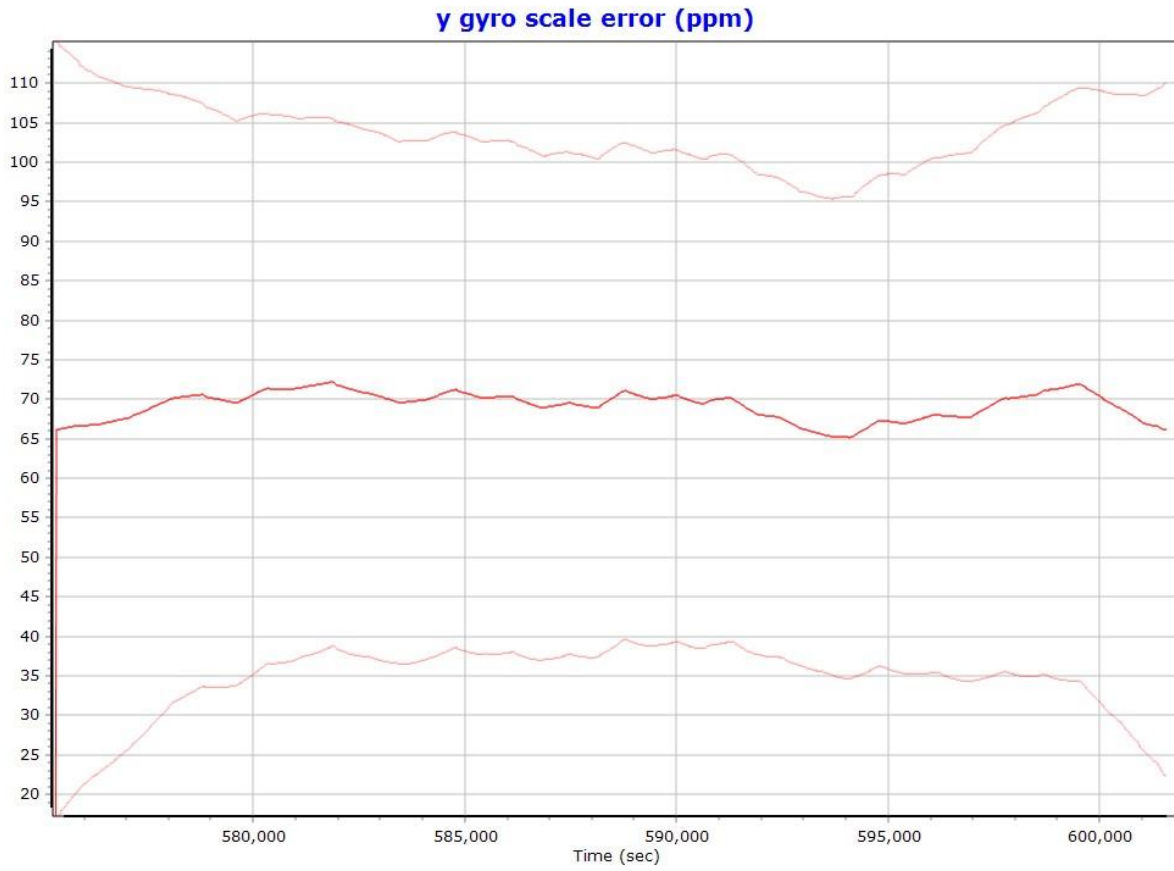
Z Gyro Bias (deg/h)



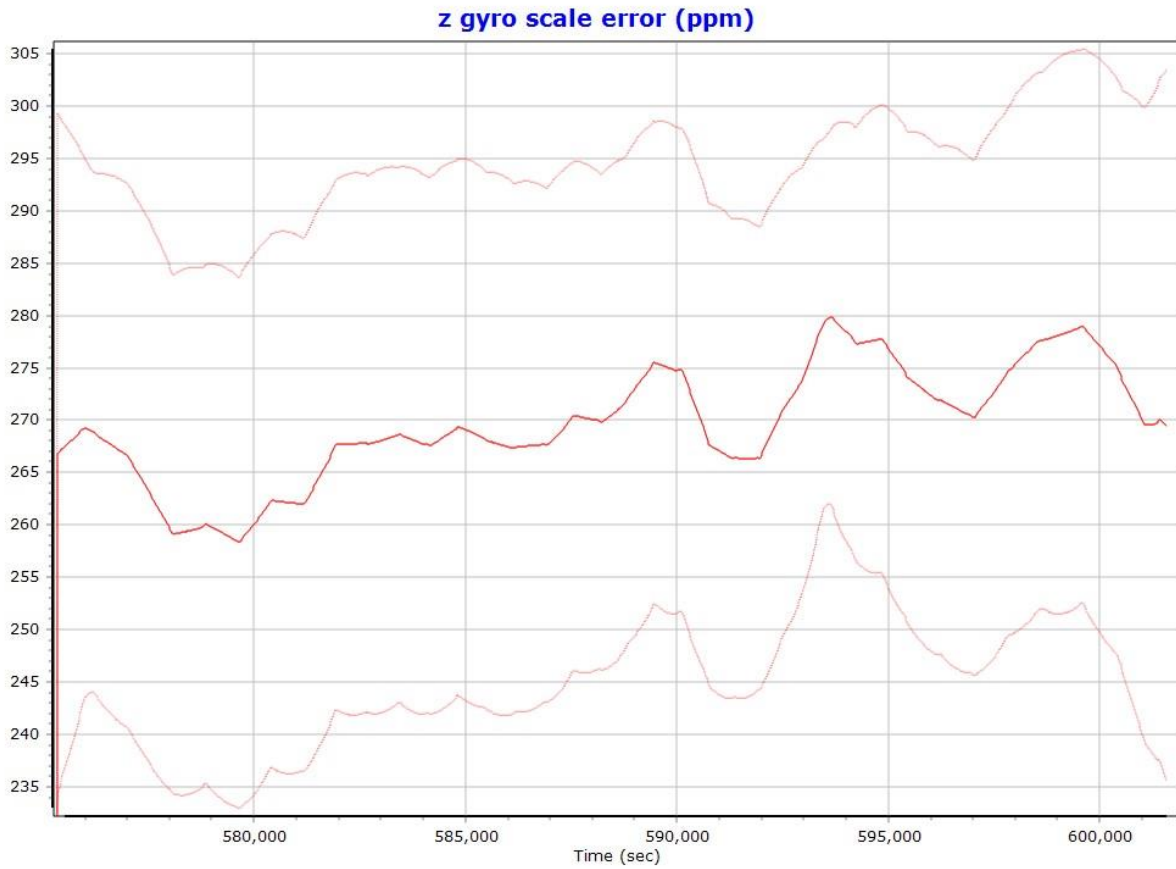
X Gyro Scale Error (ppm)



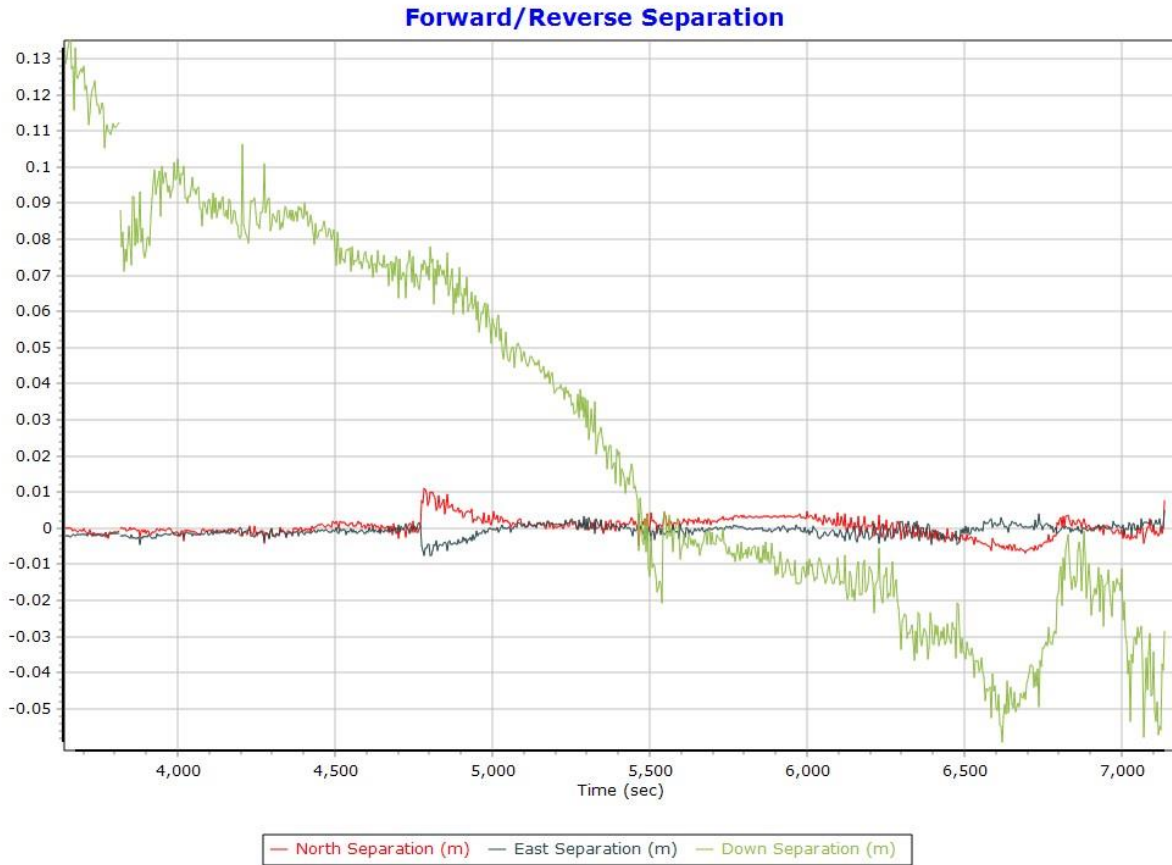
Y Gyro Scale Error (ppm)



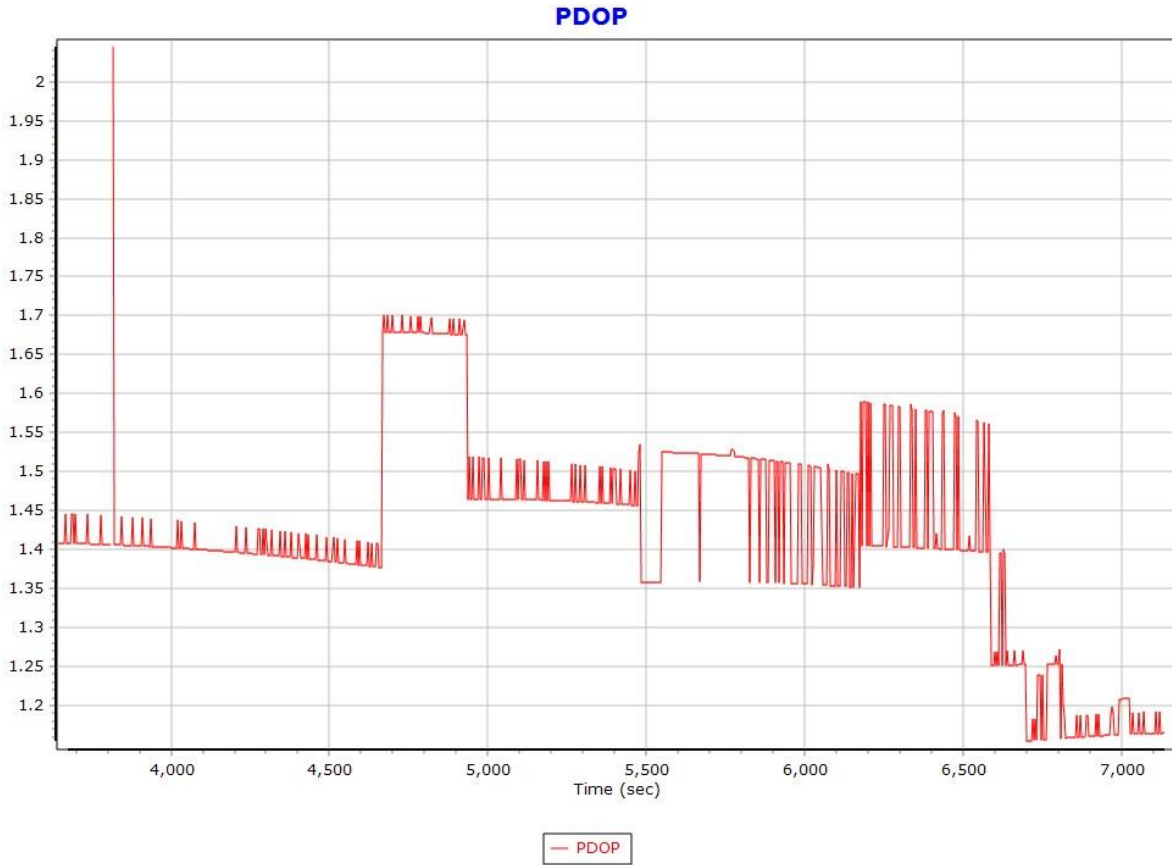
Z Gyro Scale Error (ppm)



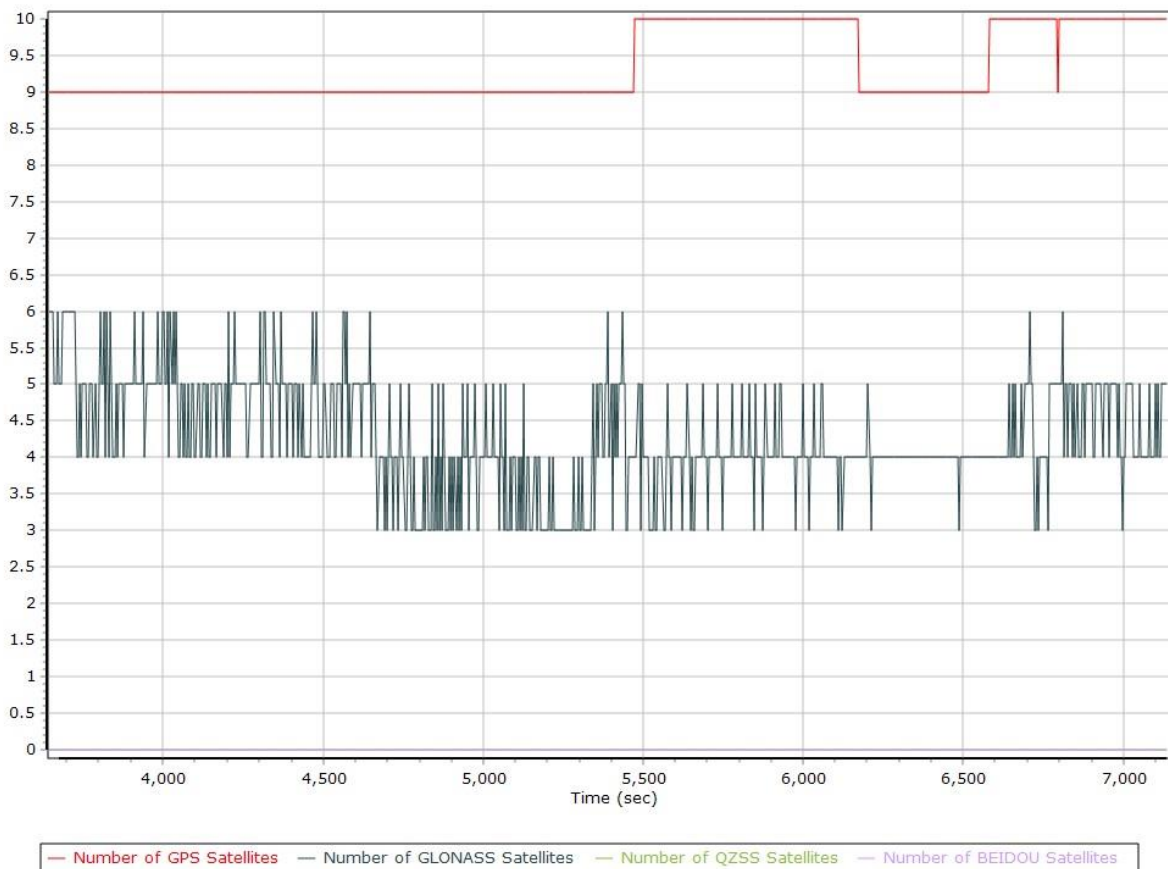
Forward/ Reverse Separation



PDOP



Number of Satellites



Processing Summary Information

Version: 4.30.3108 POSpac MMS 8.2
Project: flight4
Solution Type: Combined Fwd/Rev

Number of Epochs:

Total in GPB file: 763534
No processed position: N/A
Missing Fwd or Rev: N/A With
bad C/A code: N/A
With bad L1 Phase: N/A

Project: Task Order # 7 TX West Central

Date: 07.11.2019

Appendix A: GPS and IMU Processing Reports for Flight 4 Page
5 of 18

Measurement RMS Values:

L1 Phase: N/A

C/A Code: N/A

L1 Doppler: N/A

Fwd/Rev Separation RMS Values:

East: Averages from the forward/reverse plot

North: Averages from the forward/reverse plot

Height: Averages from the forward/reverse plot

Fwd/Rev Sep

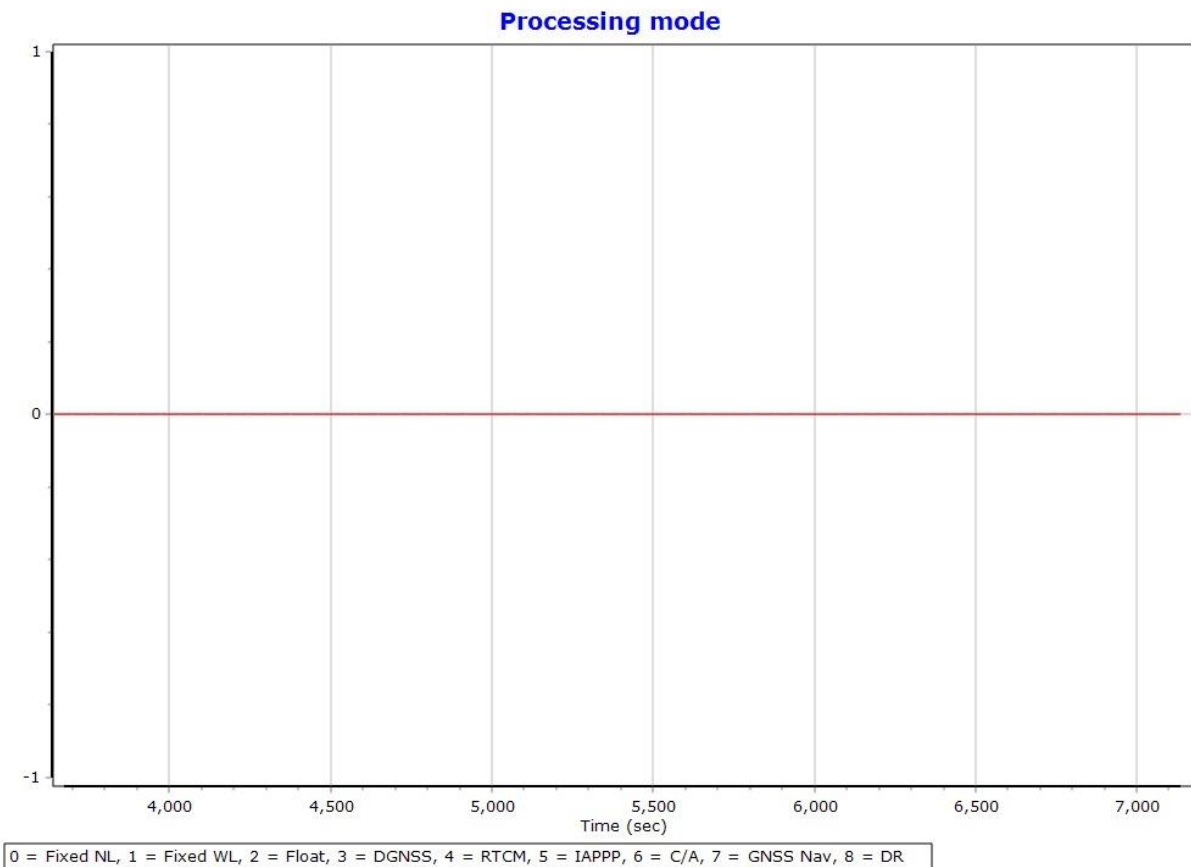
East: N/A

North: N/A

Height: N/A

Smoothed Solution Status

Processing Mode



- Q 1 "Fixed NL": 100% Q
- Q 2 "Fixed WL": 0%
- Q 3 "Float": 0% Q
- Q 4 "DGNSS": 0% Q
- Q 5 "RTCM": 0%
- Q 6 "IAPPP": 0%
- Q 7 "C/A": 0%
- Q 8 "GNSS Nav": 0%
- Q 9 "DR": 0%

Position Standard Deviation Percentages:

- 0.00 - 0.10 m: 100.0 %
- 0.10 - 0.30 m: 0.0 % 0.30
- 1.00 m: 0.0 %
- 1.00 - 5.00 m: 0.0 %
- 5.00 m + over: 0.0 %

Project: Task Order # 7 TX West Central

Date: 07.11.2019

Appendix A: GPS and IMU Processing Reports for Flight 4 Page
7 of 18

Percentages of epochs with DD_DOP over 10.00: 0.0%.

DOP over Tol: 0.0 %

Baseline Distances:

Maximum: 30.194 (km)

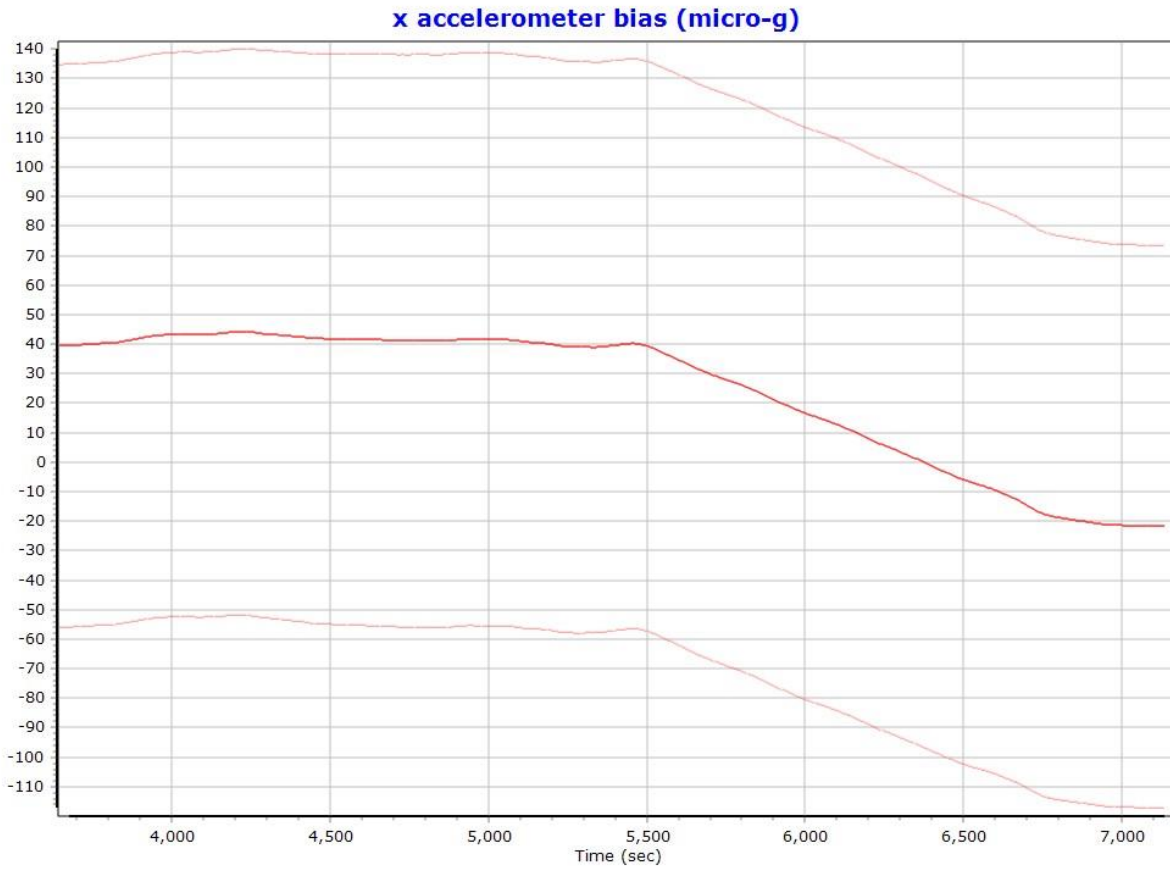
Minimum: 0.393 (km) Average:

~14 (km)

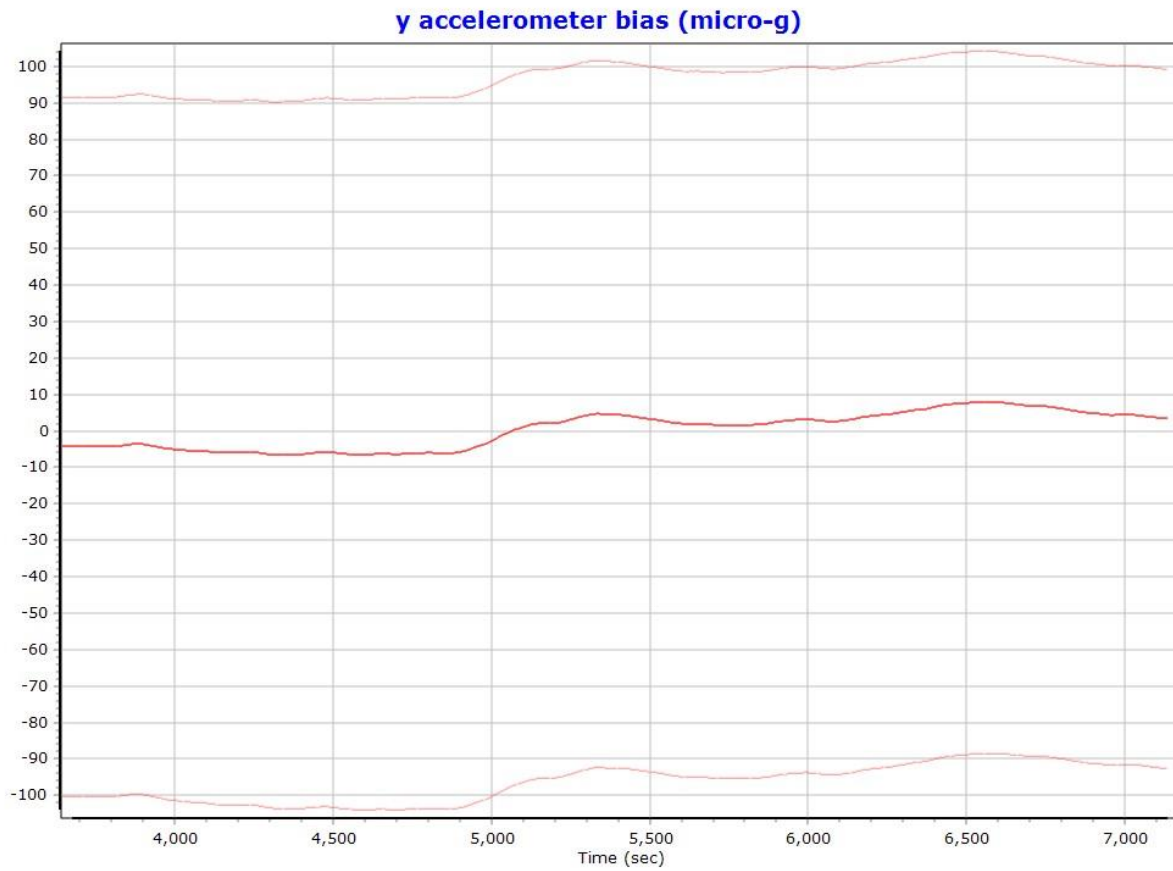
First Epoch: 0.7380 (km) Last

Epoch: 6.743 (km)

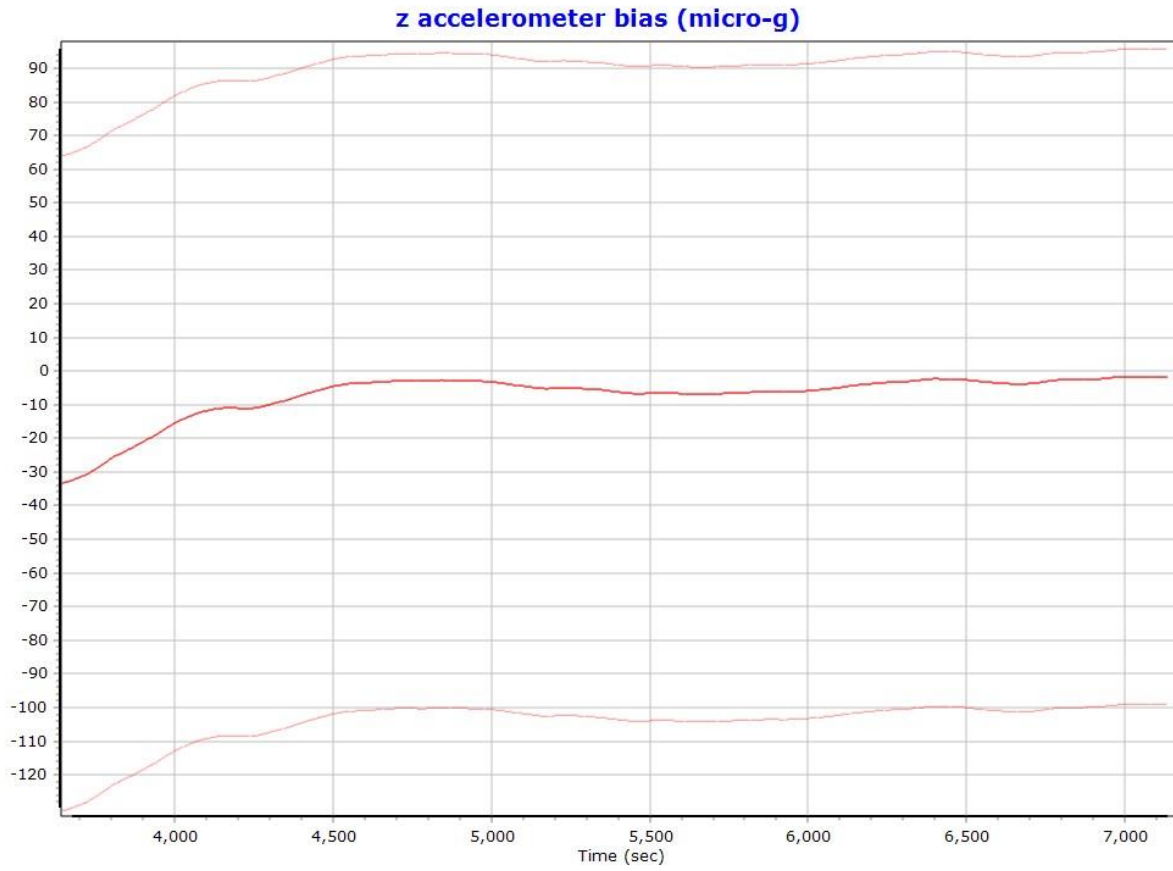
Sensor Errors X Accelerometer Bias (micro-g)



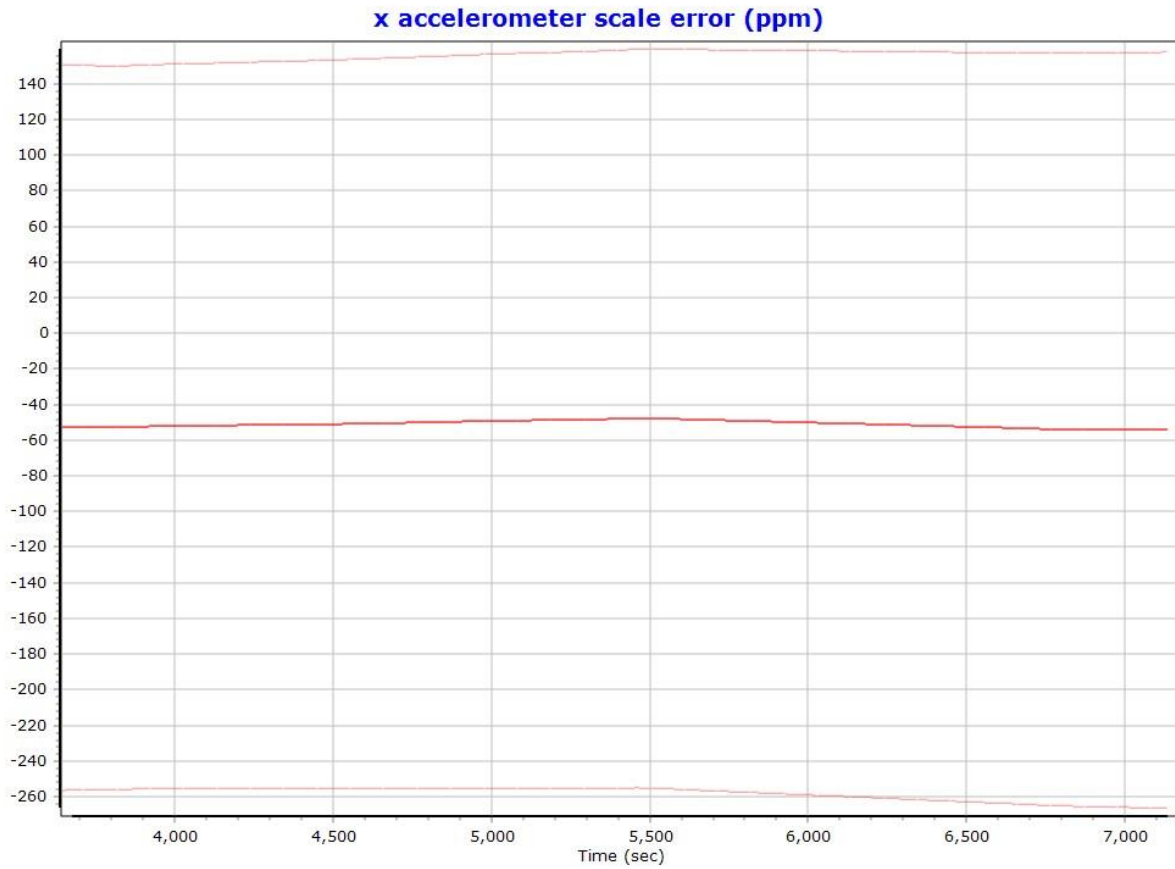
Y Accelerometer Bias (micro-g)



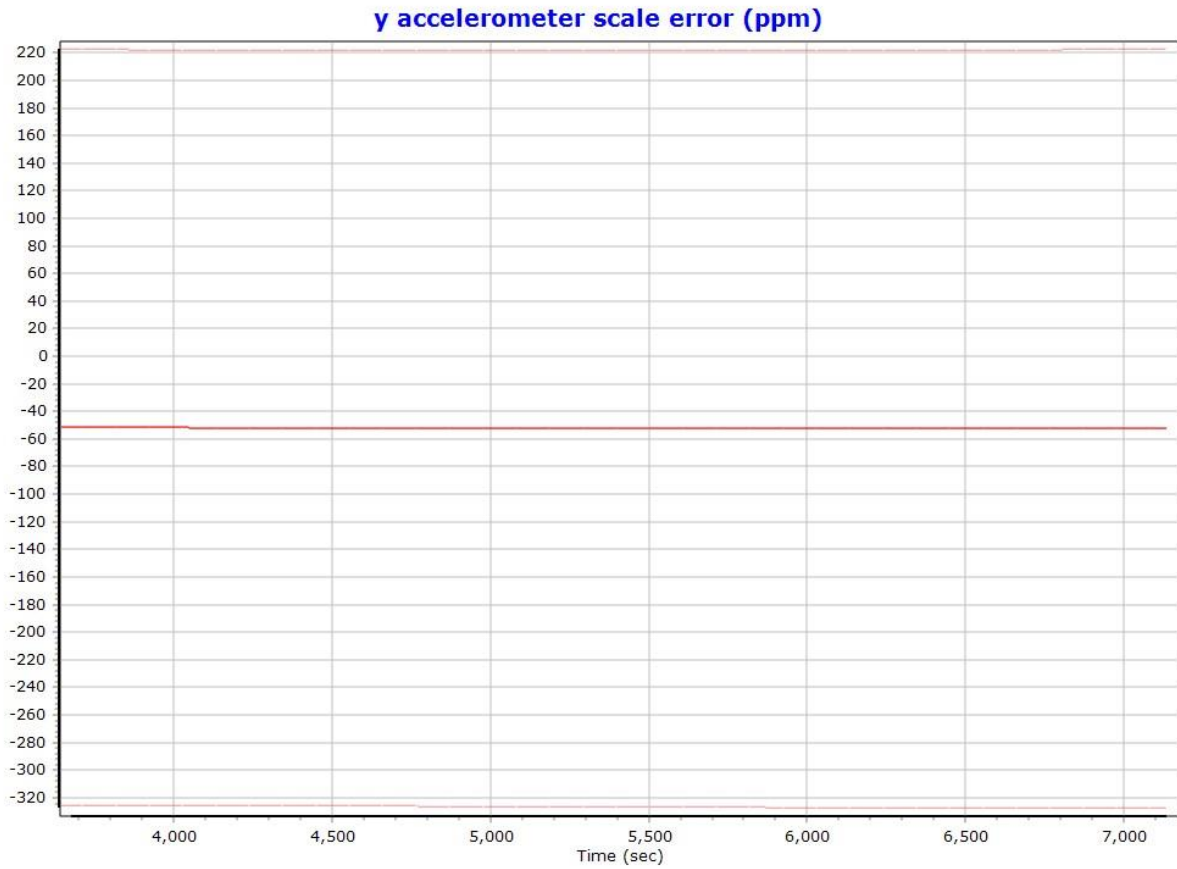
Z Accelerometer Bias (micro-g)



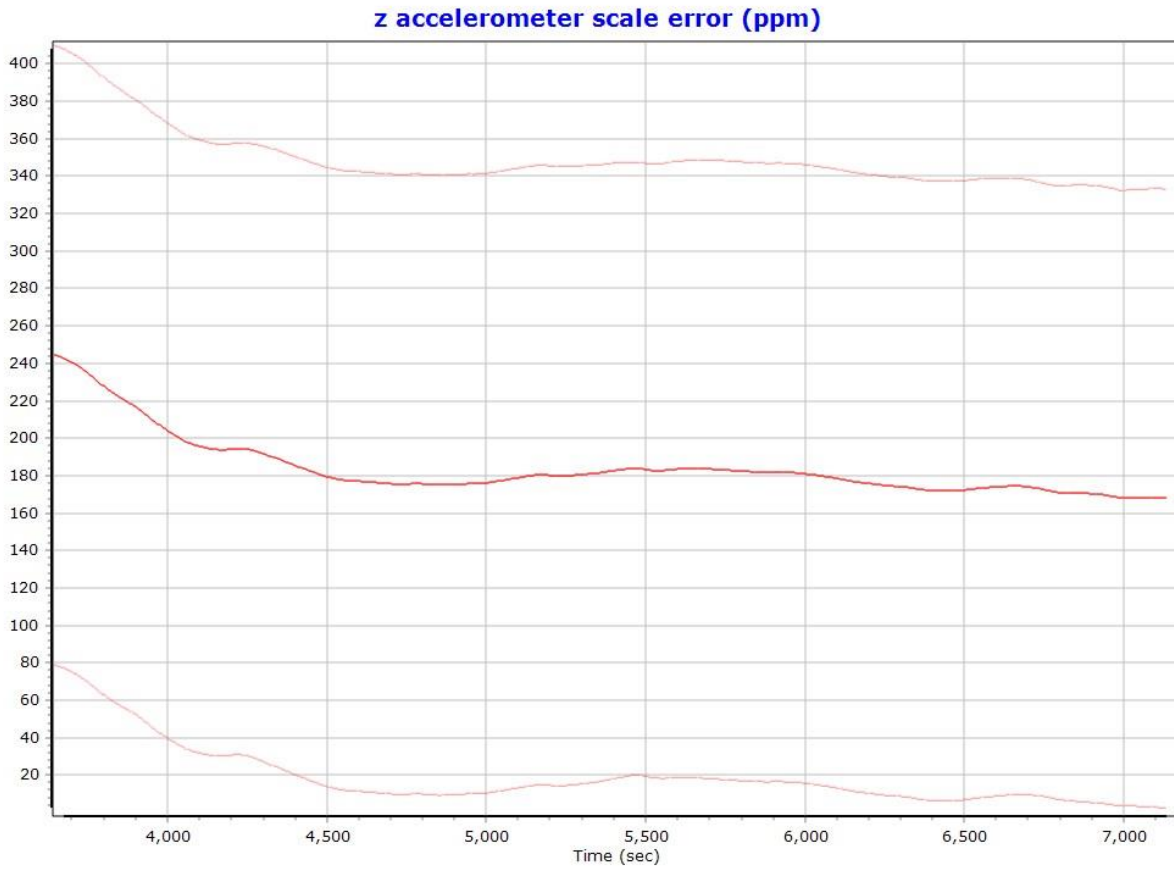
X Accelerometer Scale Error (ppm)



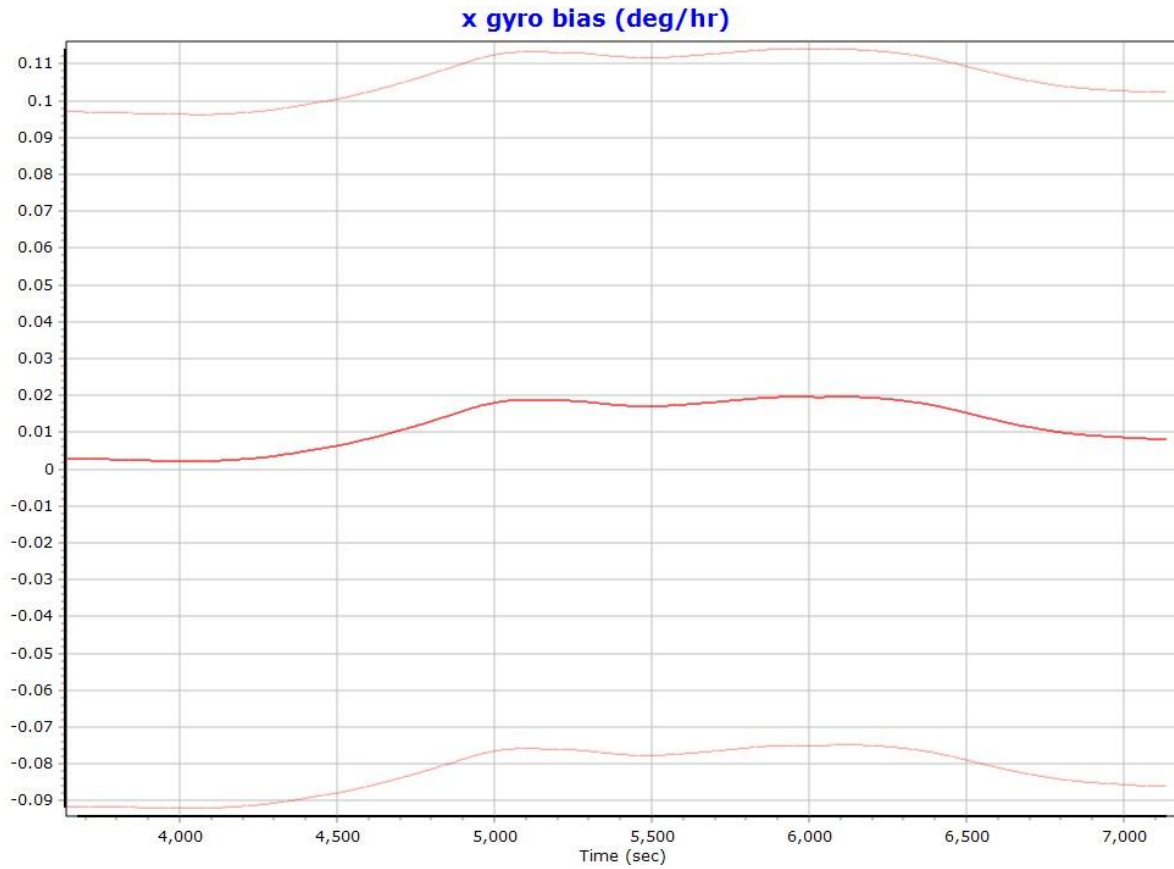
Y Accelerometer Scale Error (ppm)



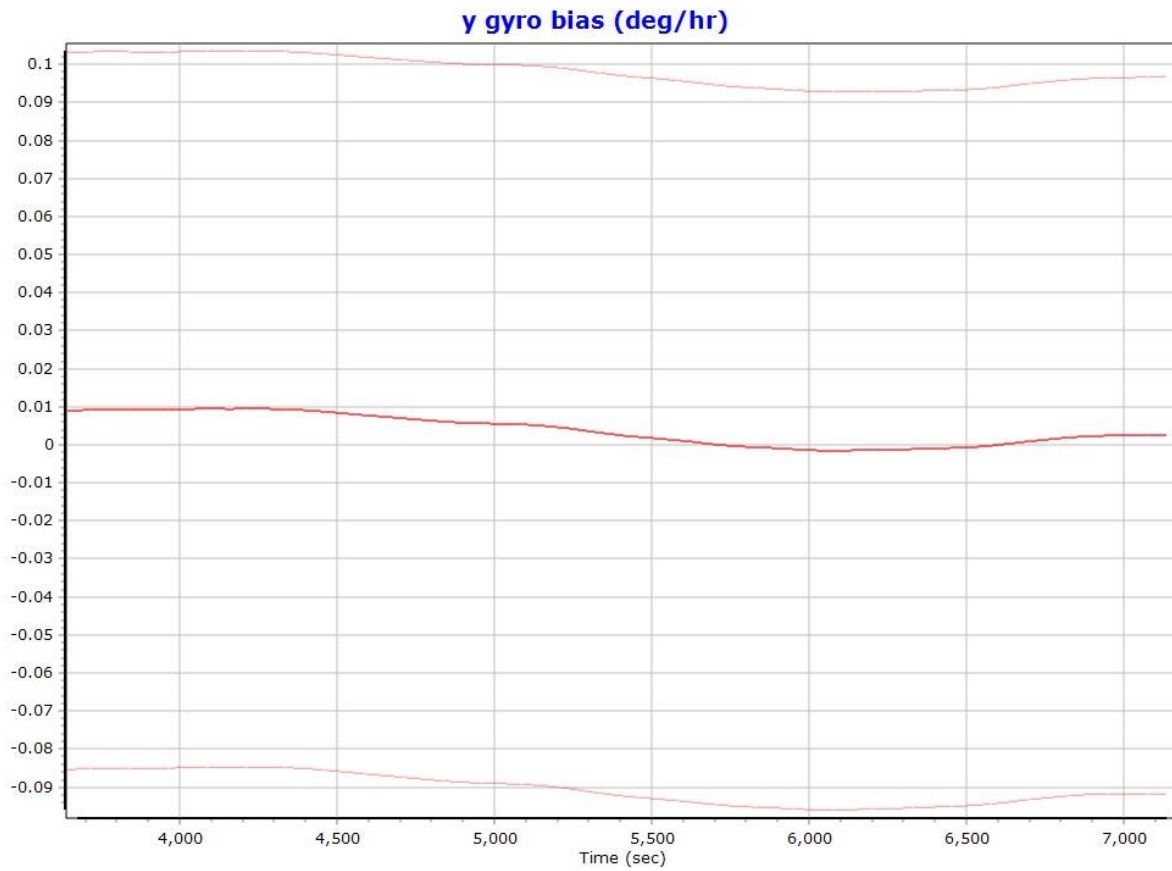
Z Accelerometer Scale Error (ppm)



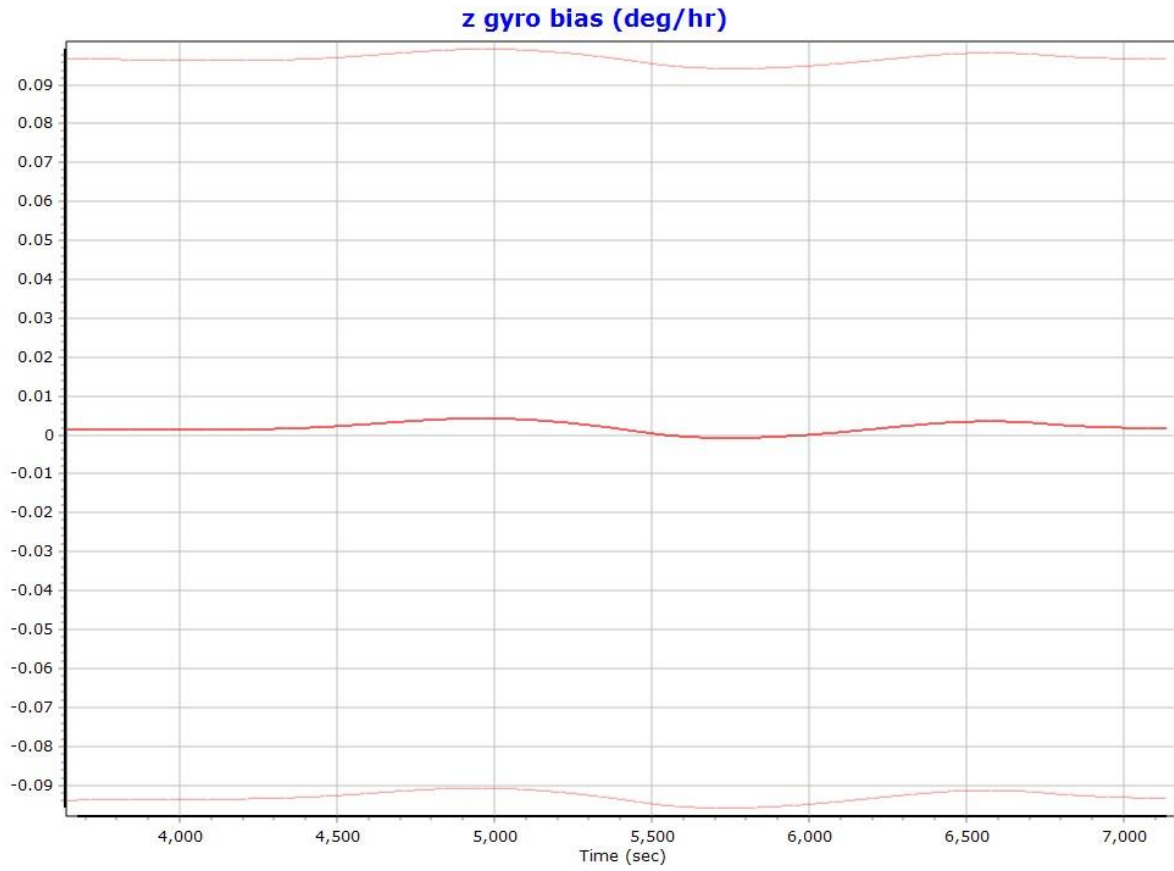
X Gyro Bias (deg/h)



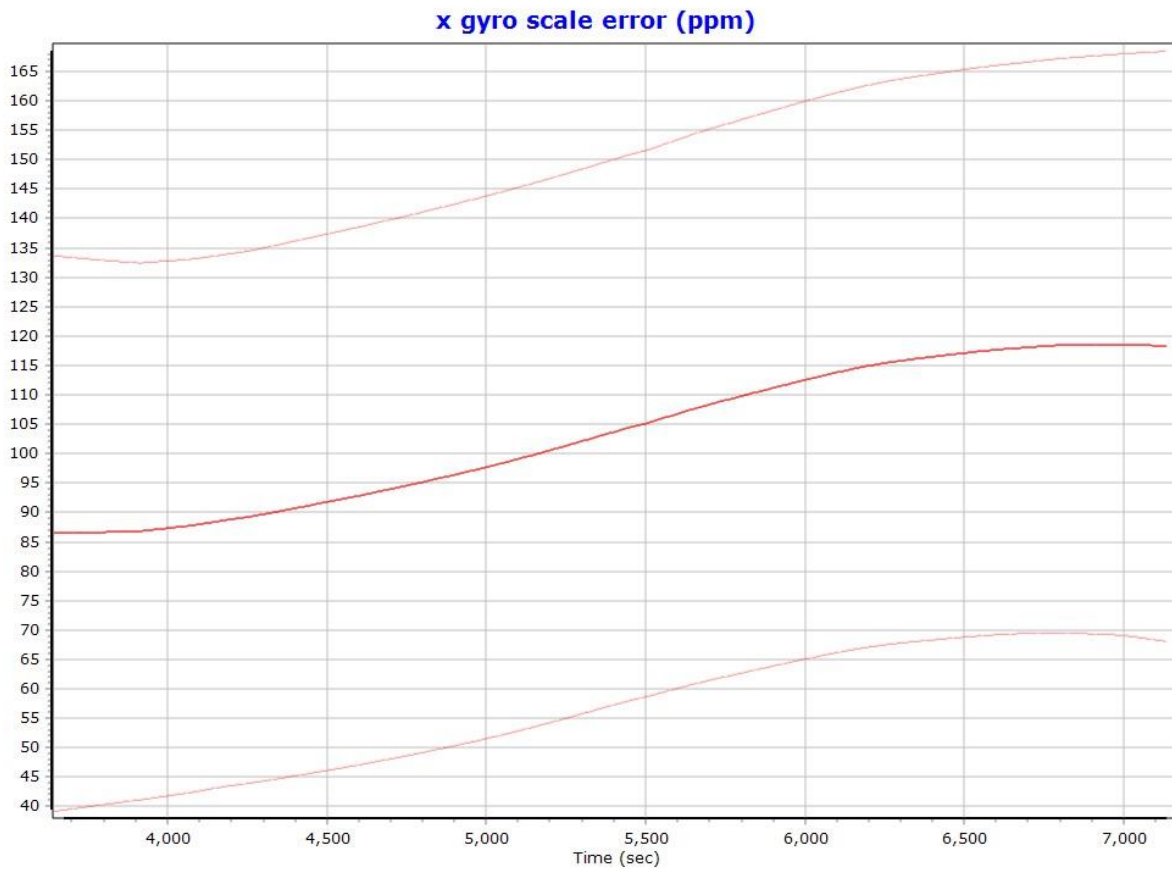
Y Gyro Bias (deg/h)



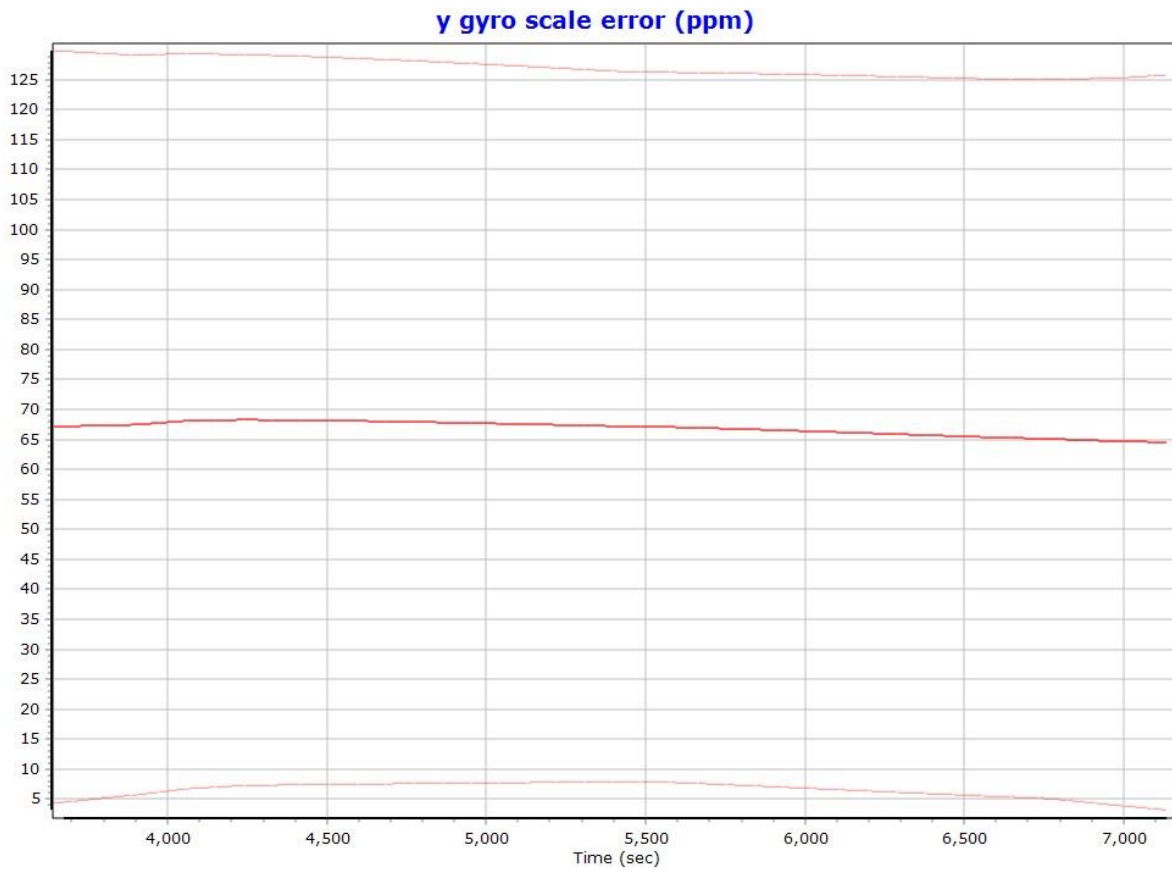
Z Gyro Bias (deg/h)



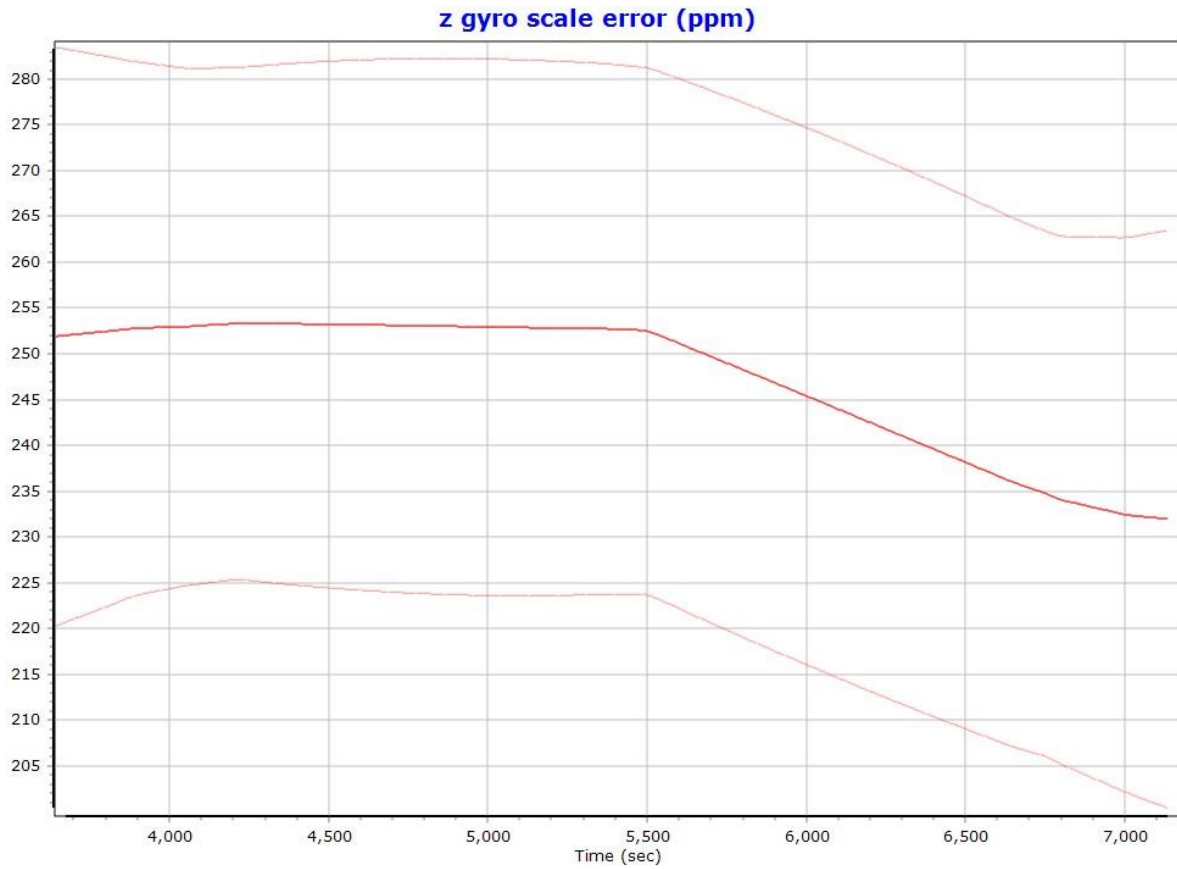
X Gyro Scale Error (ppm)



Y Gyro Scale Error (ppm)



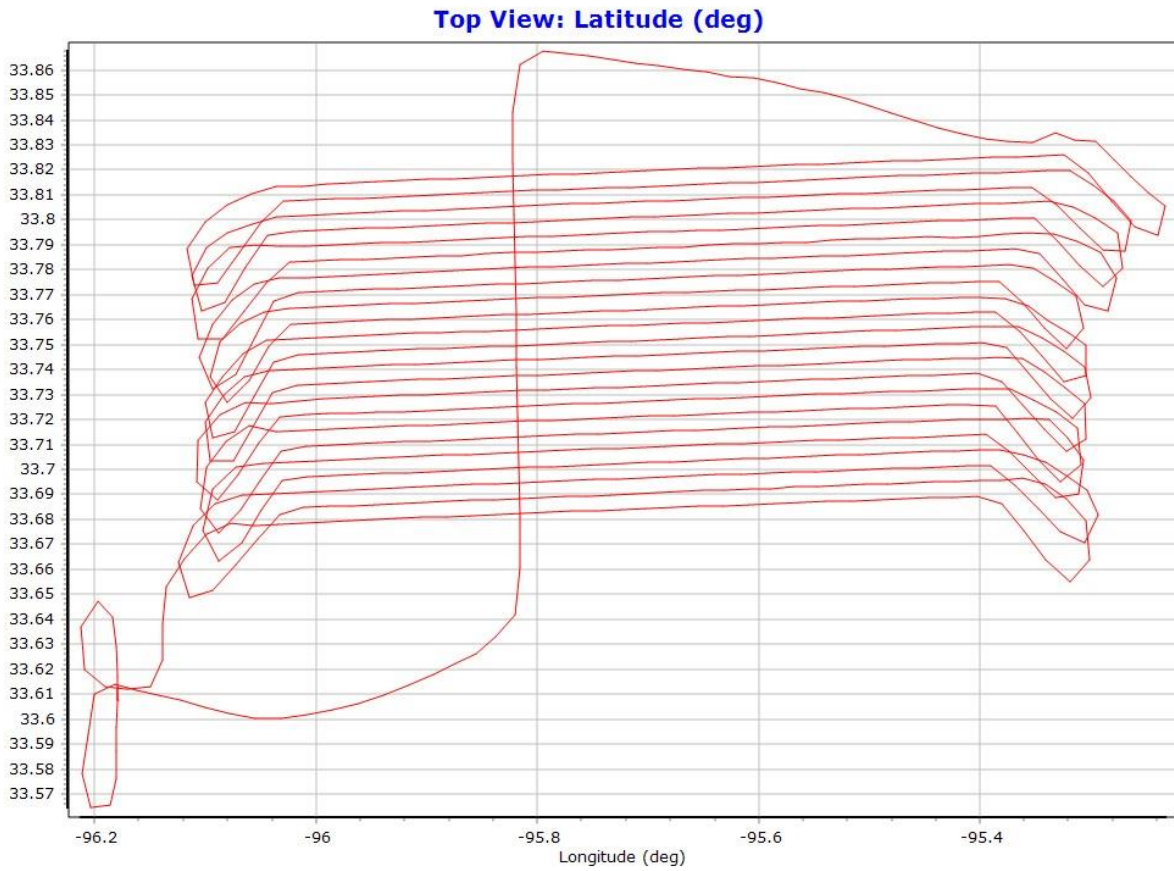
Z Gyro Scale Error (ppm)



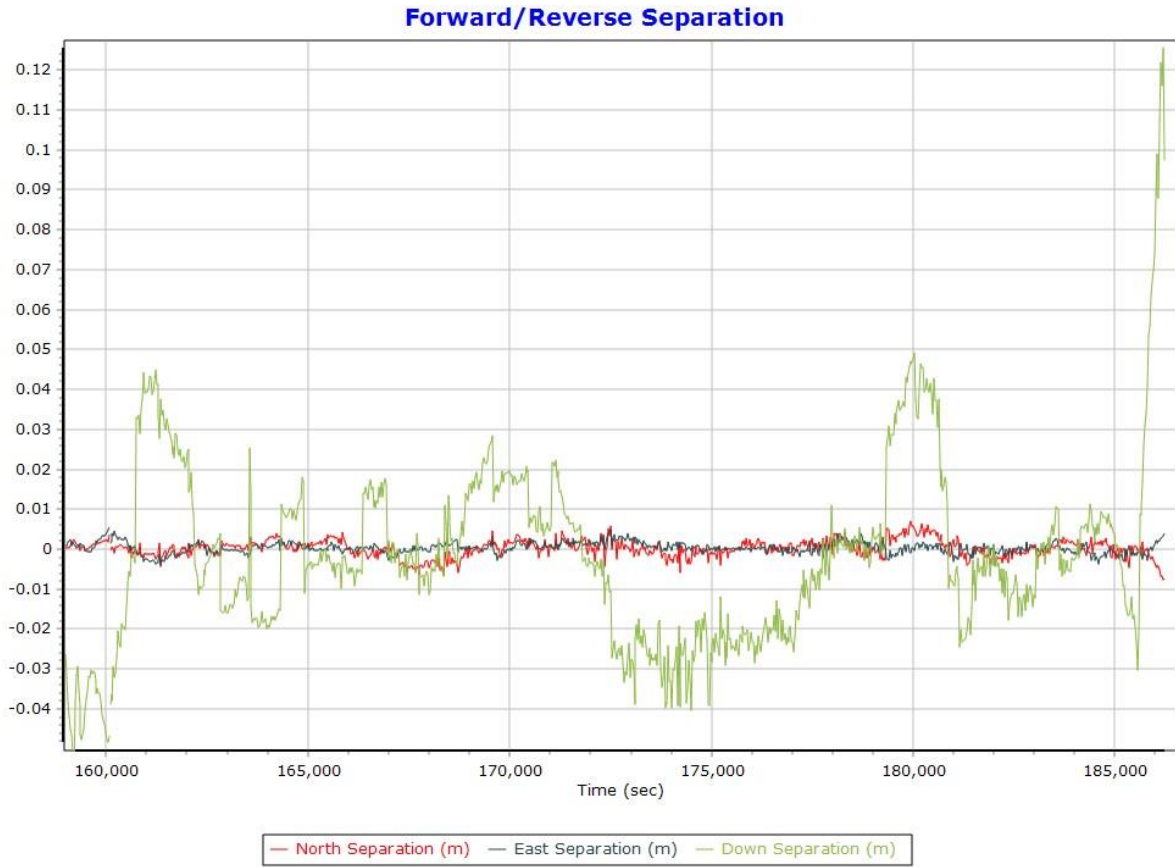
Flight 5

Trajectory Information

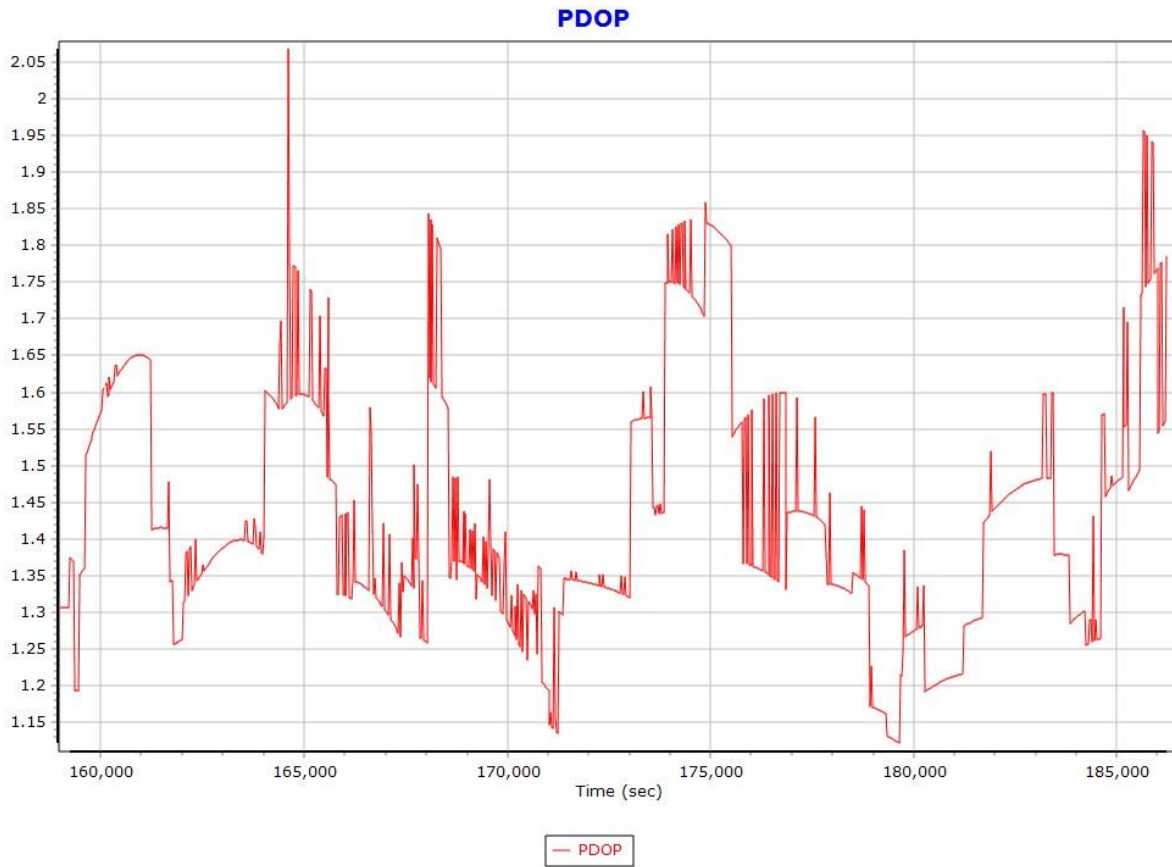
Top View



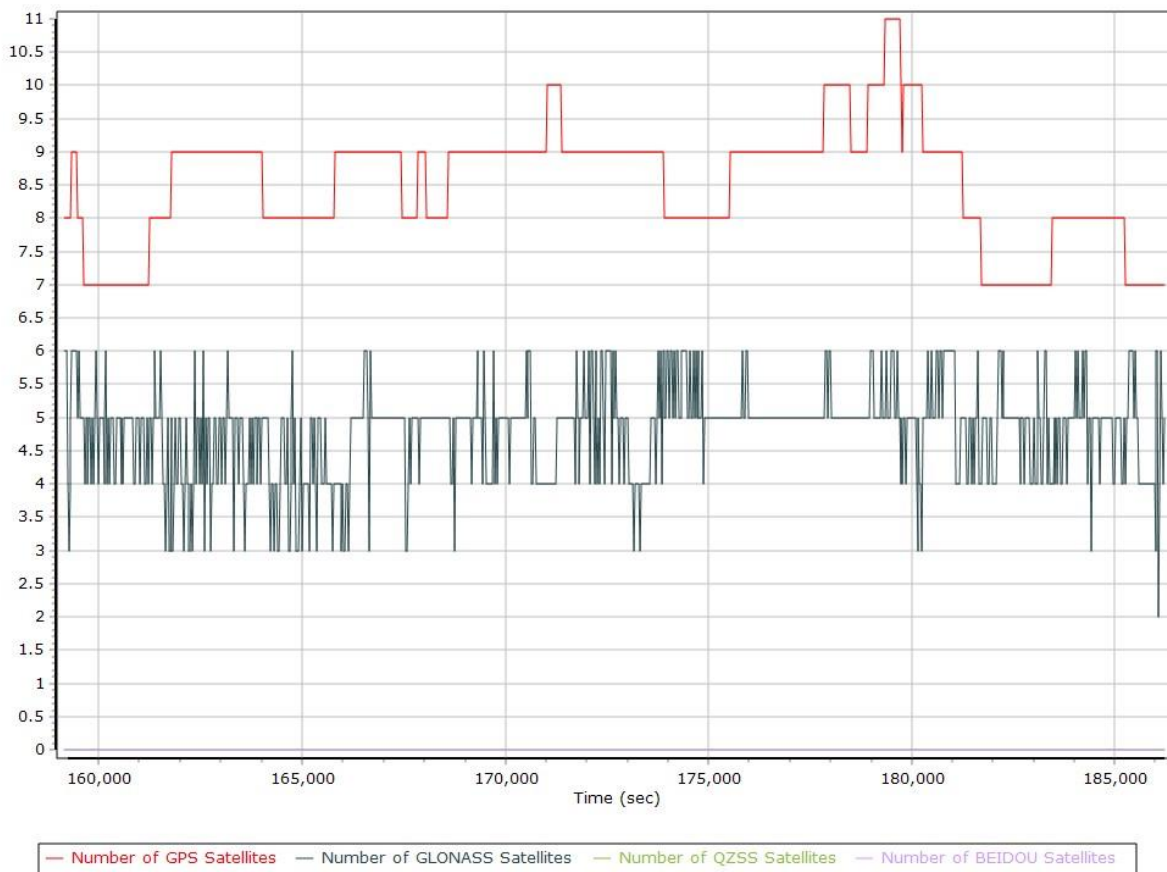
Forward/ Reverse Separation



PDOP



Number of Satellites



Processing Summary Information

Version: 4.30.3108 POSpac MMS 8.2
Project: flight5
Solution Type: Combined Fwd/Rev

Number of Epochs:

Total in GPB file: 5458273
No processed position: N/A
Missing Fwd or Rev: N/A With
bad C/A code: N/A
With bad L1 Phase: N/A

Project: Task Order # 7 TX West Central

Date: 07.11.2019

Appendix A: GPS and IMU Processing Reports for Flight 5 Page
5 of 18

Measurement RMS Values:

L1 Phase: N/A

C/A Code: N/A

L1 Doppler: N/A

Fwd/Rev Separation RMS Values:

East: Averages from the forward/reverse plot

North: Averages from the forward/reverse plot

Height: Averages from the forward/reverse plot

Fwd/Rev Sep

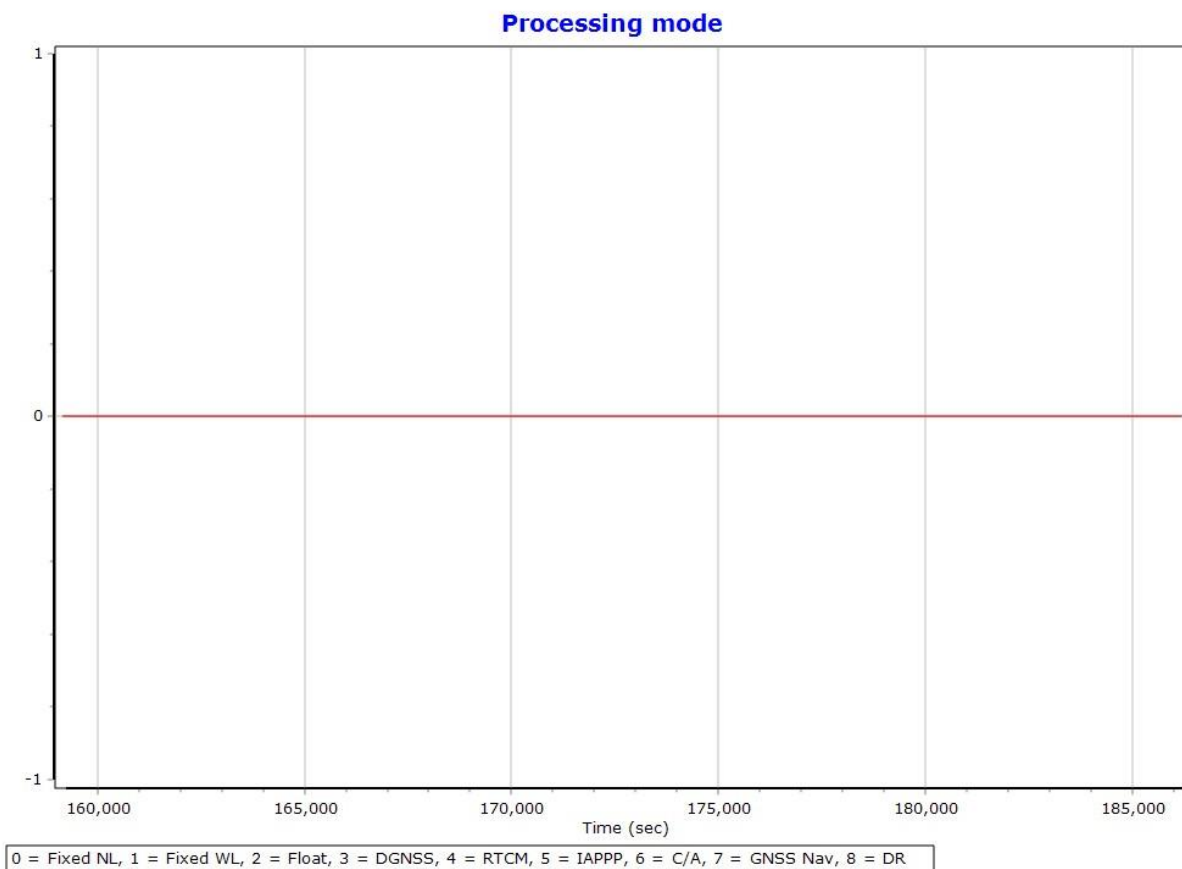
East: N/A

North: N/A

Height: N/A

Smoothed Solution Status

Processing Mode



- Q 1 "Fixed NL": 100% Q
- Q 2 "Fixed WL": 0%
- Q 3 "Float": 0% Q
- Q 4 "DGNSS": 0% Q
- Q 5 "RTCM": 0%
- Q 6 "IAPPP": 0%
- Q 7 "C/A": 0%
- Q 8 "GNSS Nav": 0%
- Q 9 "DR": 0%

Position Standard Deviation Percentages:

- 0.00 - 0.10 m: 100.0 %
- 0.10 - 0.30 m: 0.0 % 0.30
- 1.00 m: 0.0 %
- 1.00 - 5.00 m: 0.0 %
- 5.00 m + over: 0.0 %

Project: Task Order # 7 TX West Central

Date: 07.11.2019

Appendix A: GPS and IMU Processing Reports for Flight 5 Page
7 of 18

Percentages of epochs with DD_DOP over 10.00: 0.0%.

DOP over Tol: 0.0 %

Baseline Distances:

Maximum: 35.932 (km)

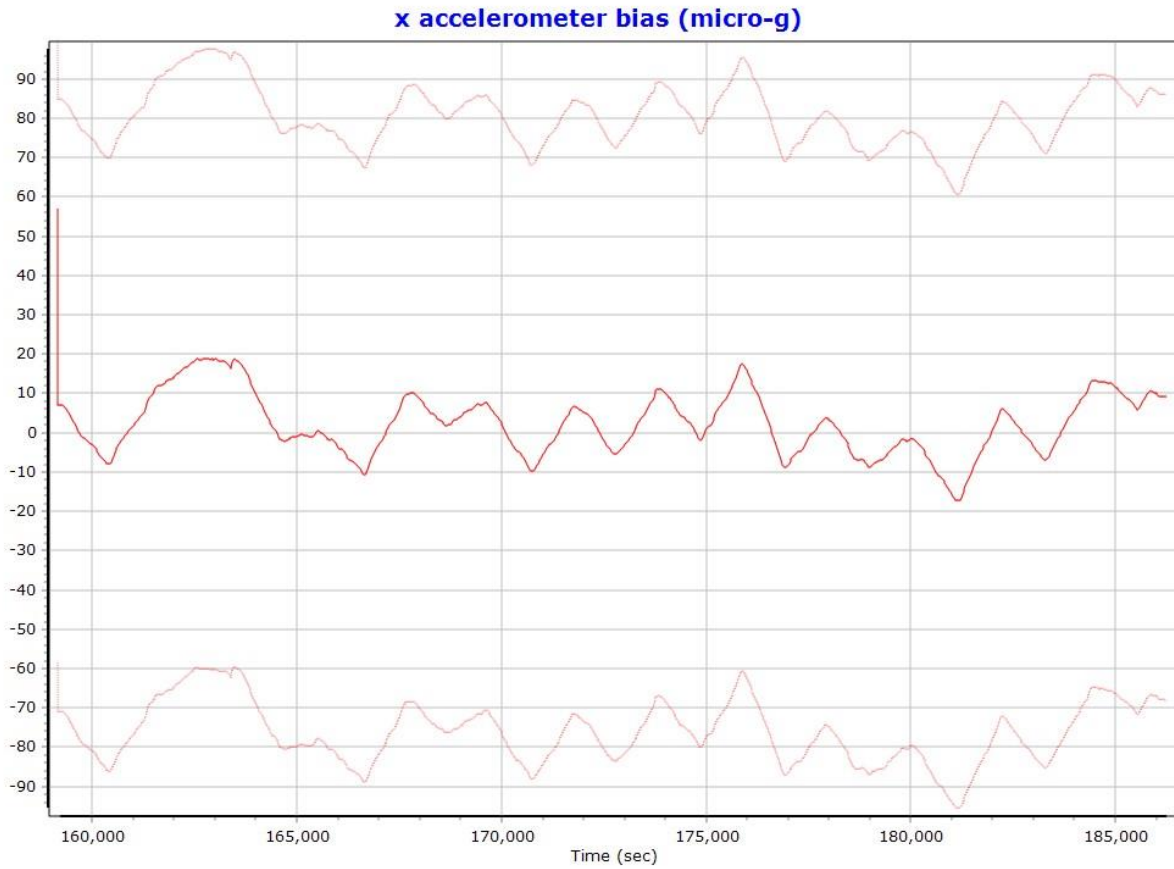
Minimum: 0.321 (km) Average:

~18 (km)

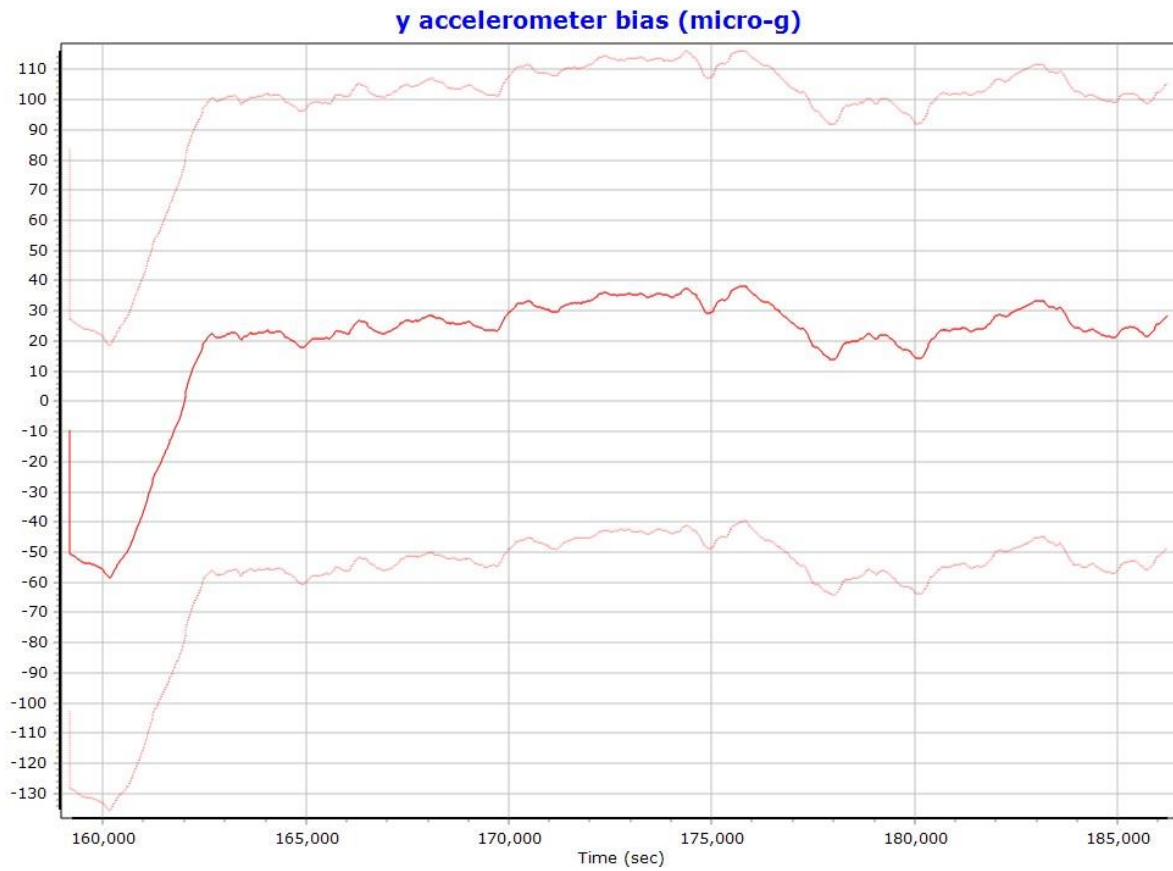
First Epoch: 0.720 (km) Last

Epoch: 1.226 (km)

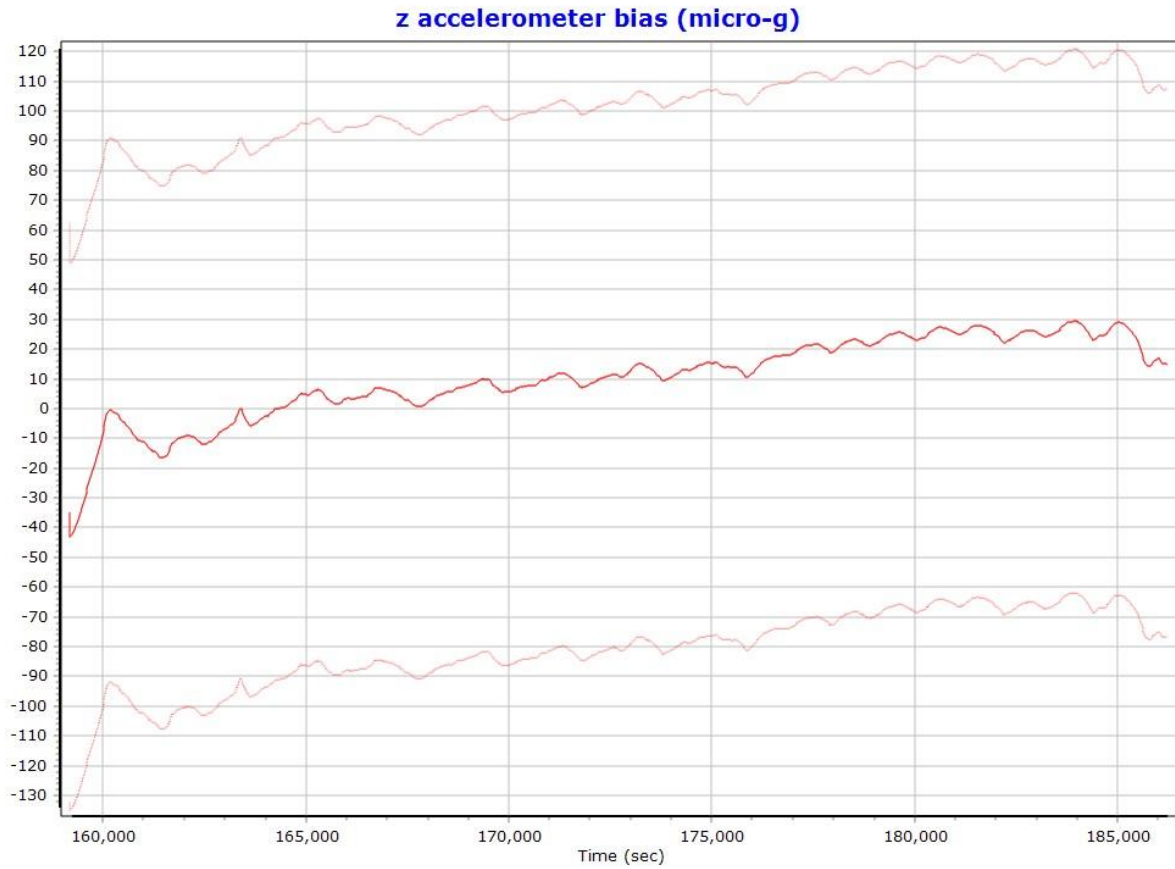
Sensor Errors X Accelerometer Bias (micro-g)



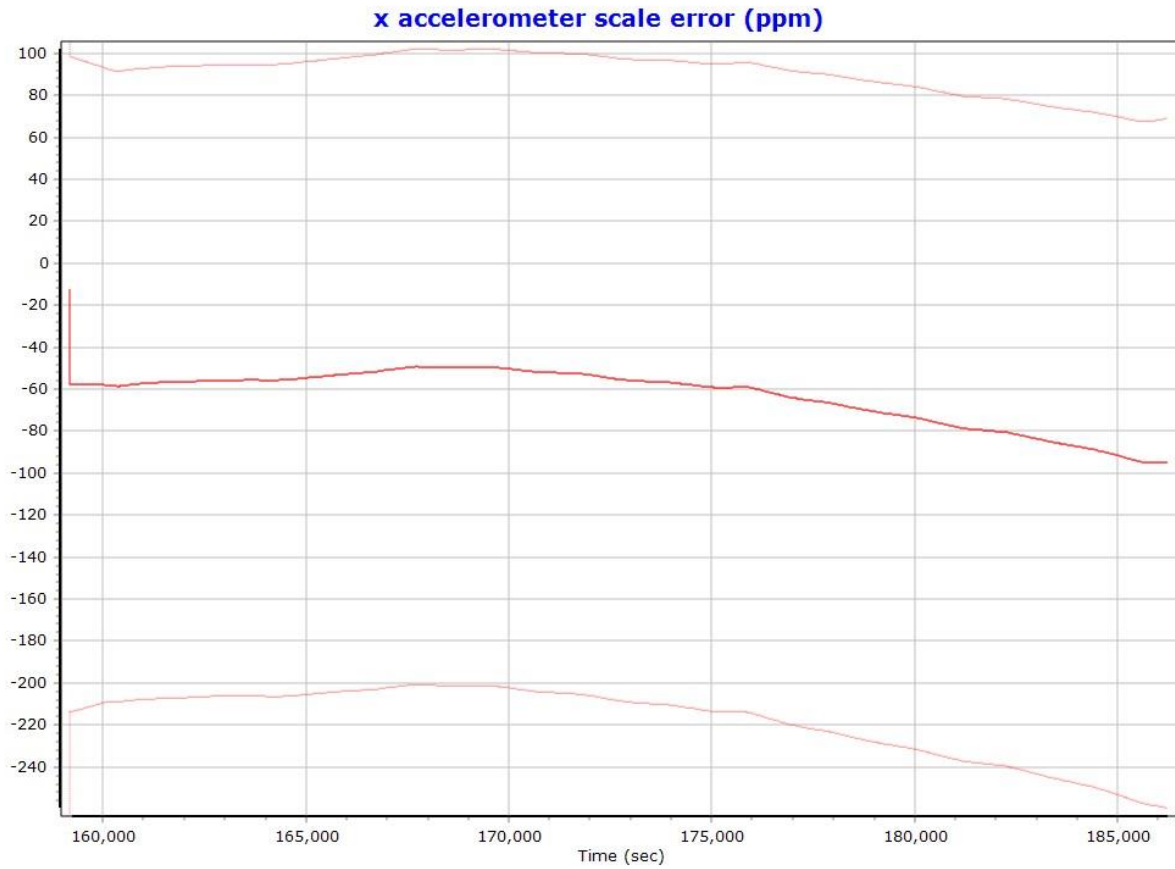
Y Accelerometer Bias (micro-g)



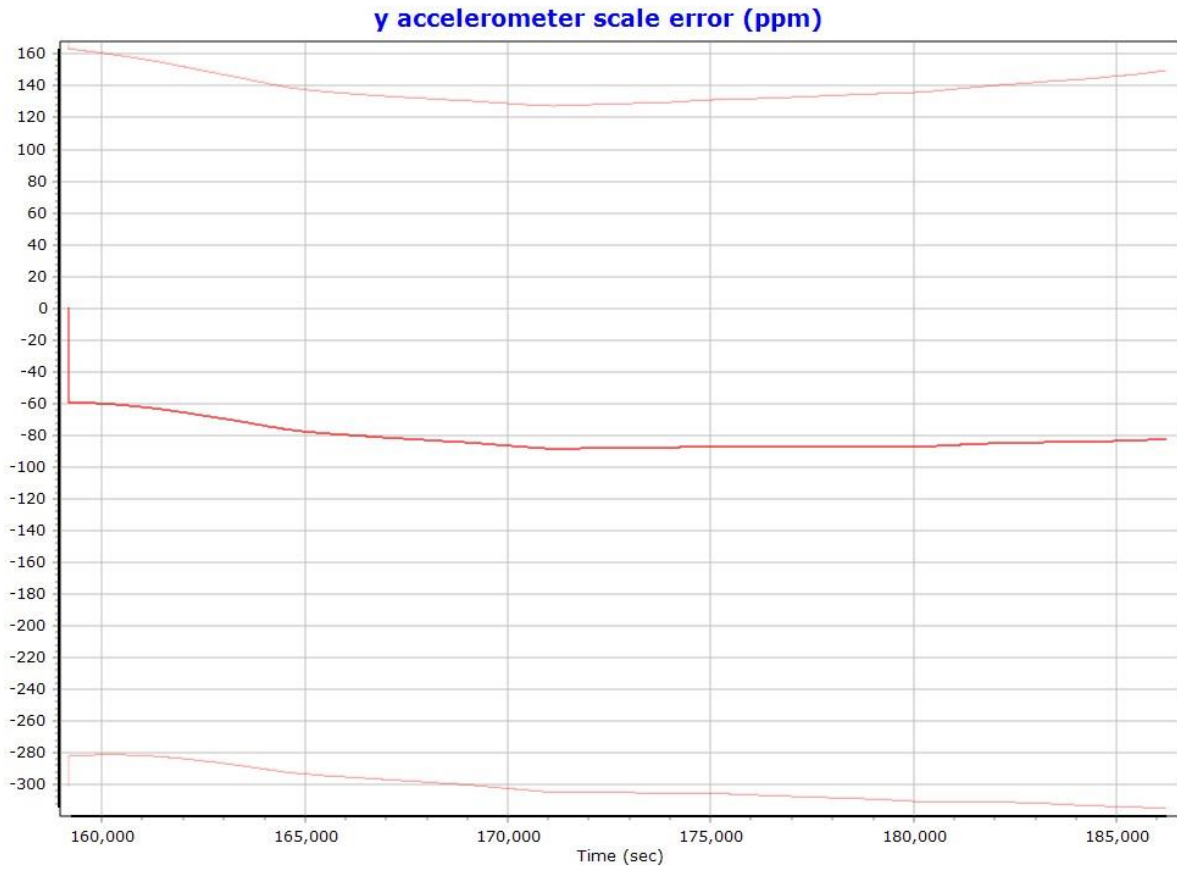
Z Accelerometer Bias (micro-g)



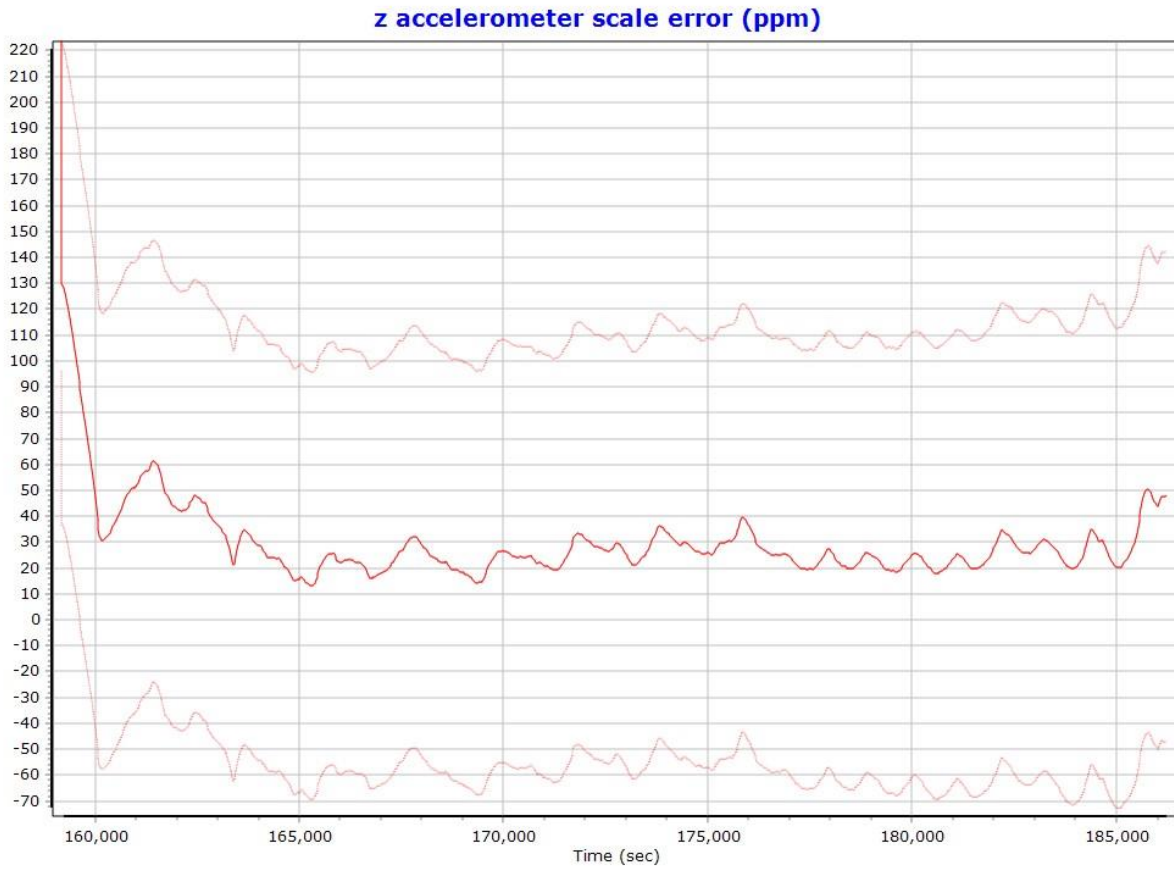
X Accelerometer Scale Error (ppm)



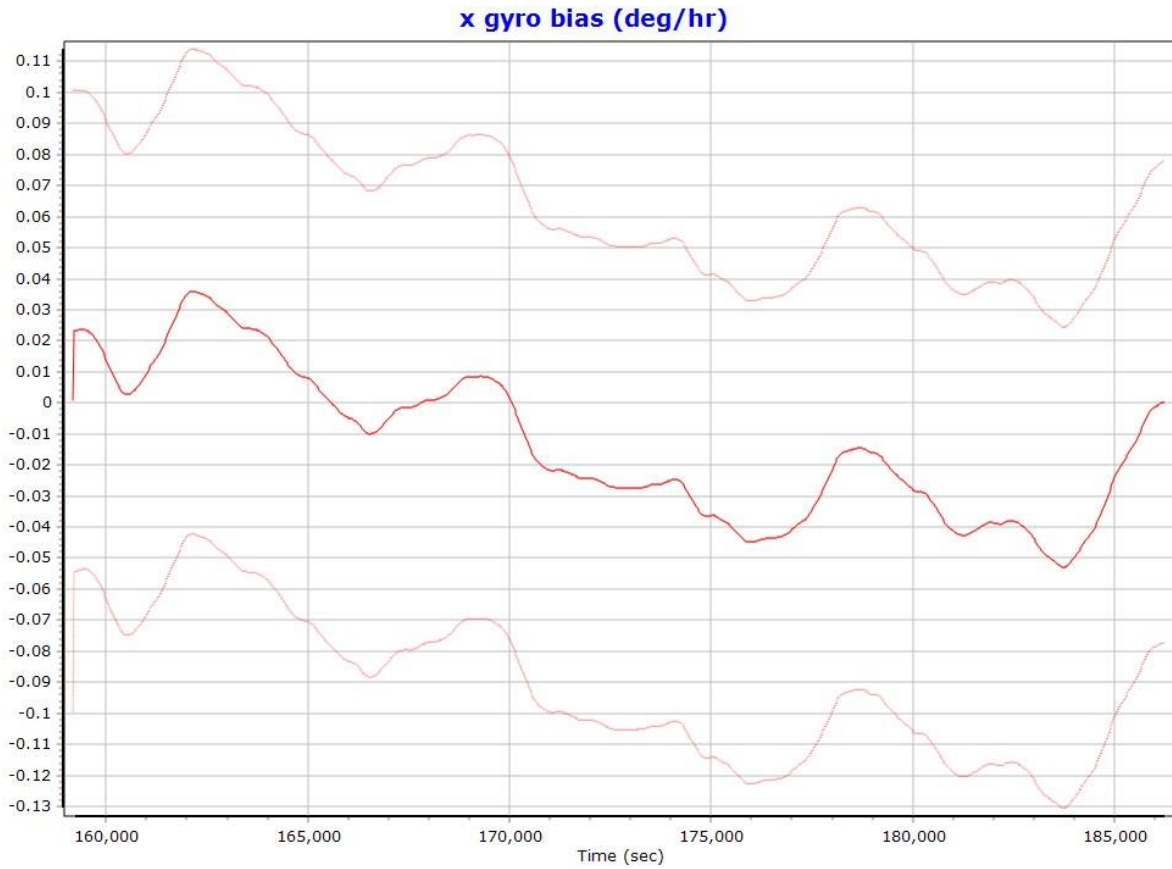
Y Accelerometer Scale Error (ppm)



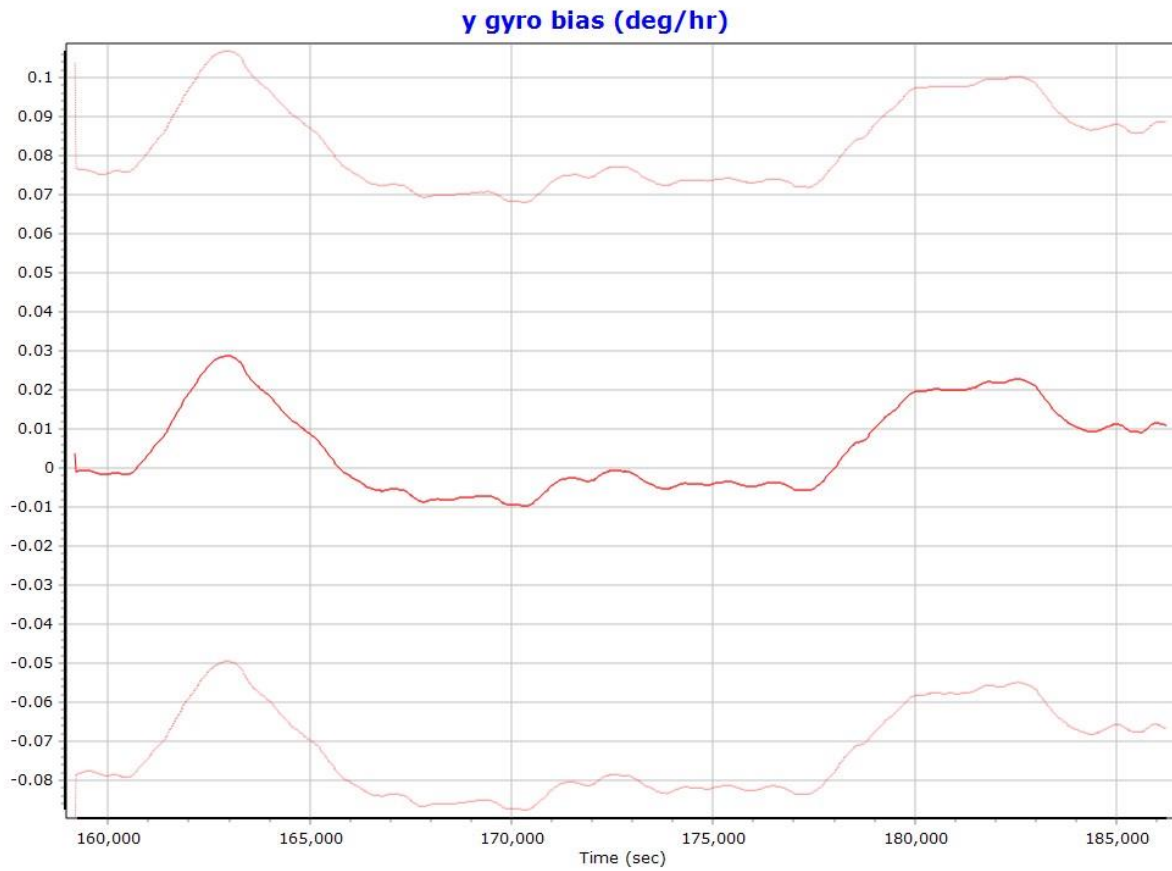
Z Accelerometer Scale Error (ppm)



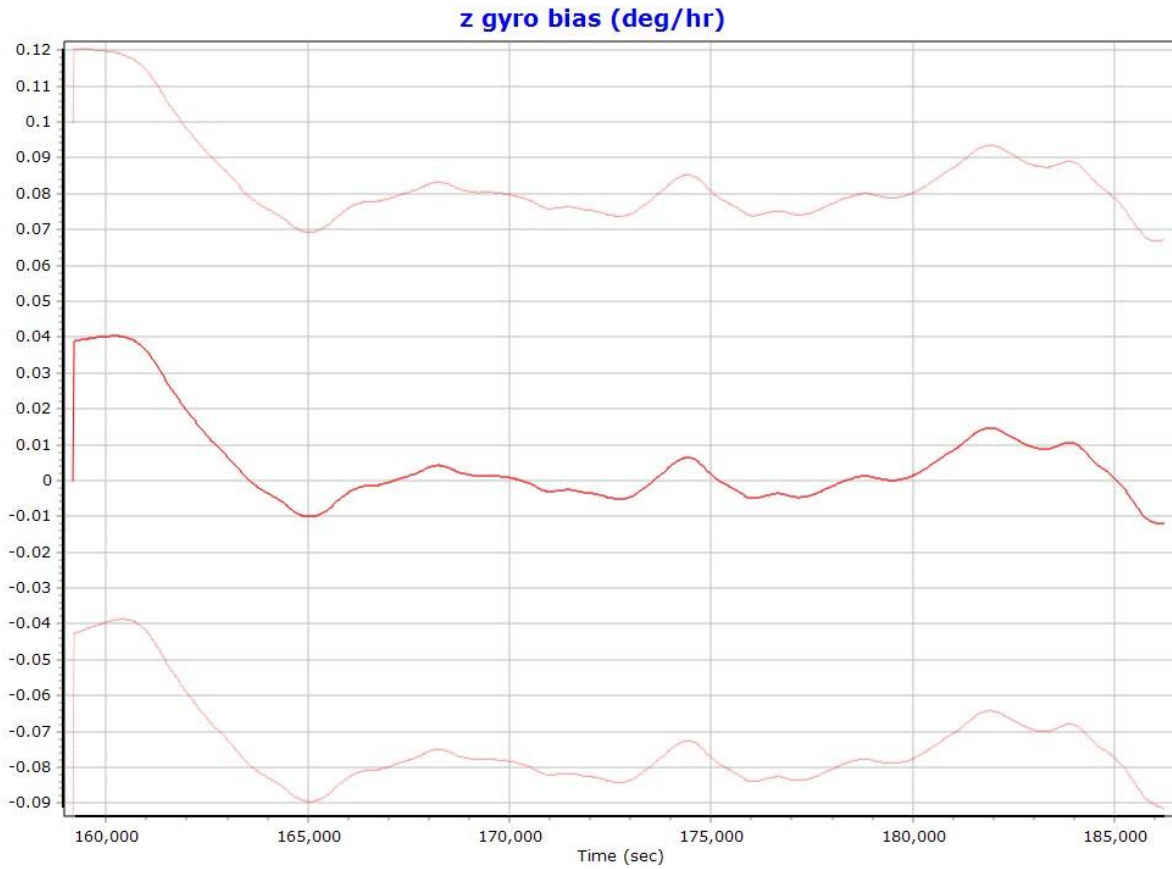
X Gyro Bias (deg/h)



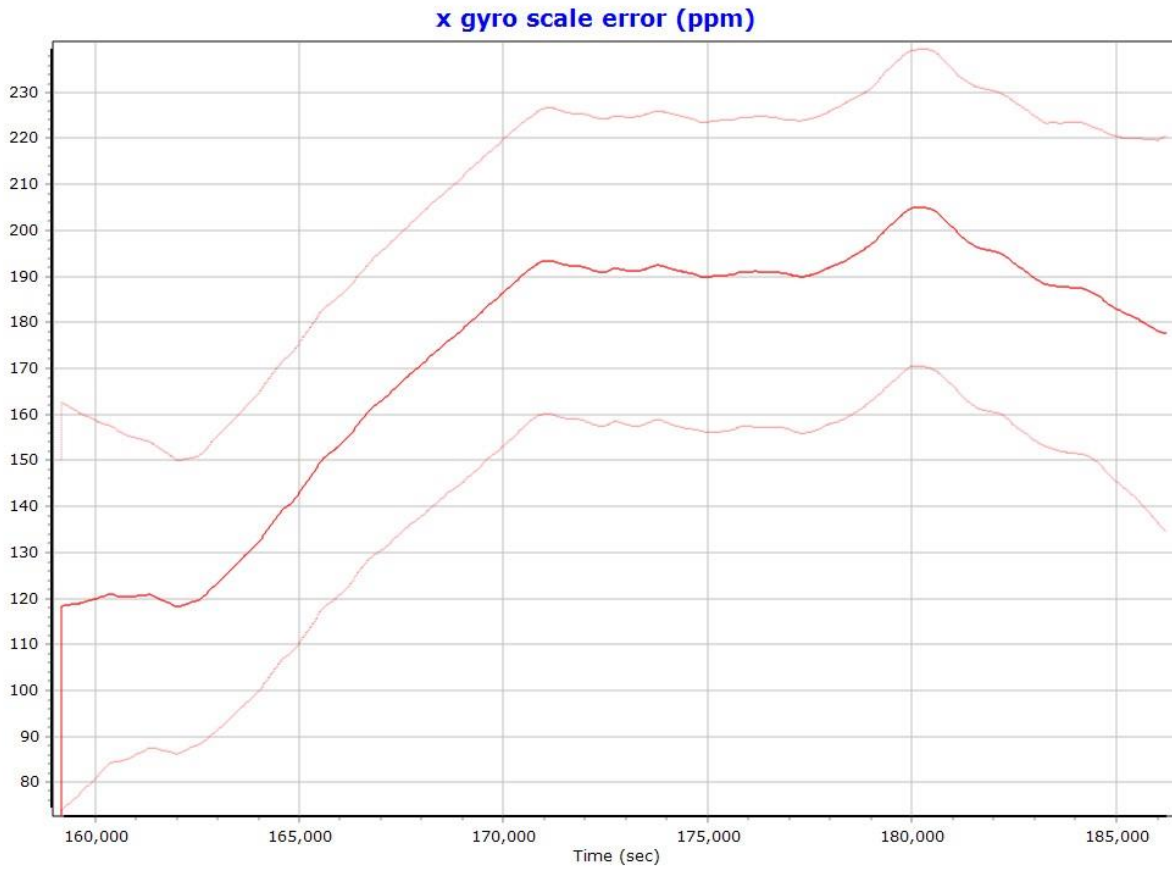
Y Gyro Bias (deg/h)



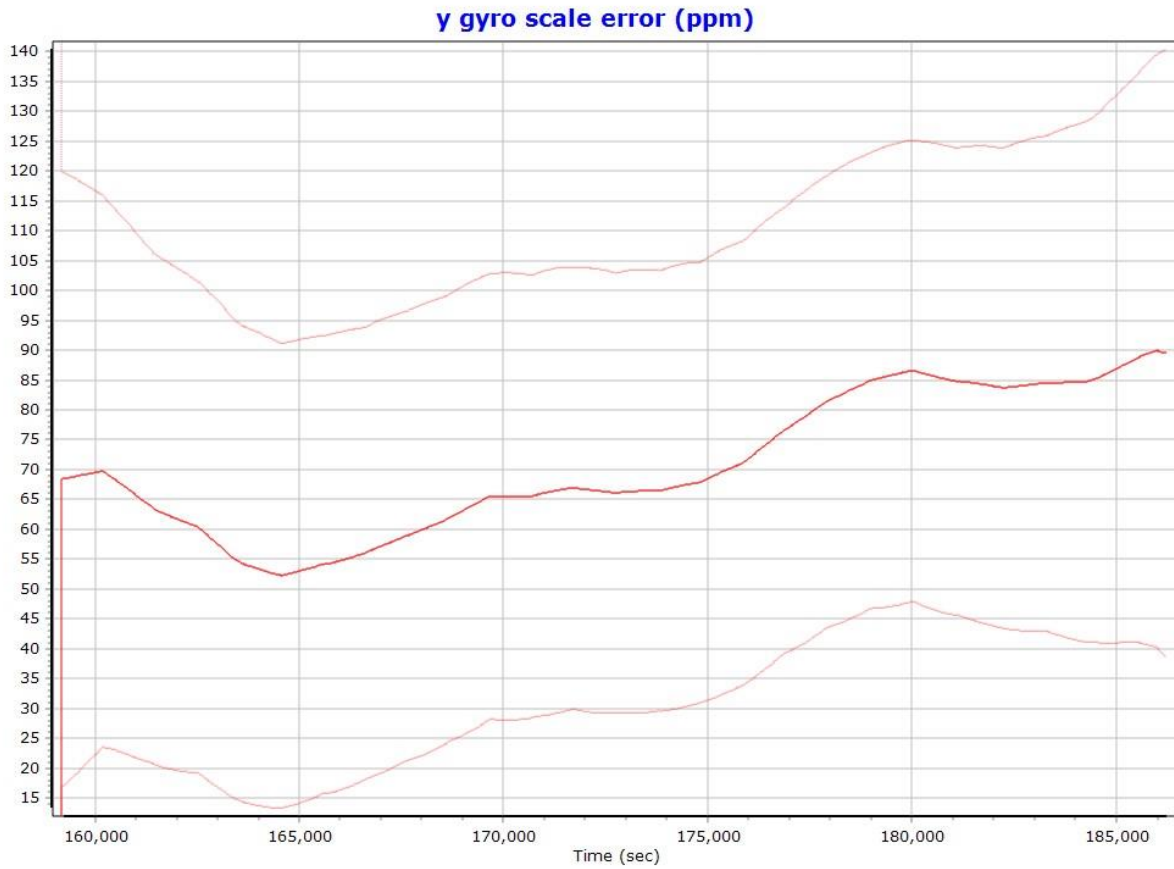
Z Gyro Bias (deg/h)



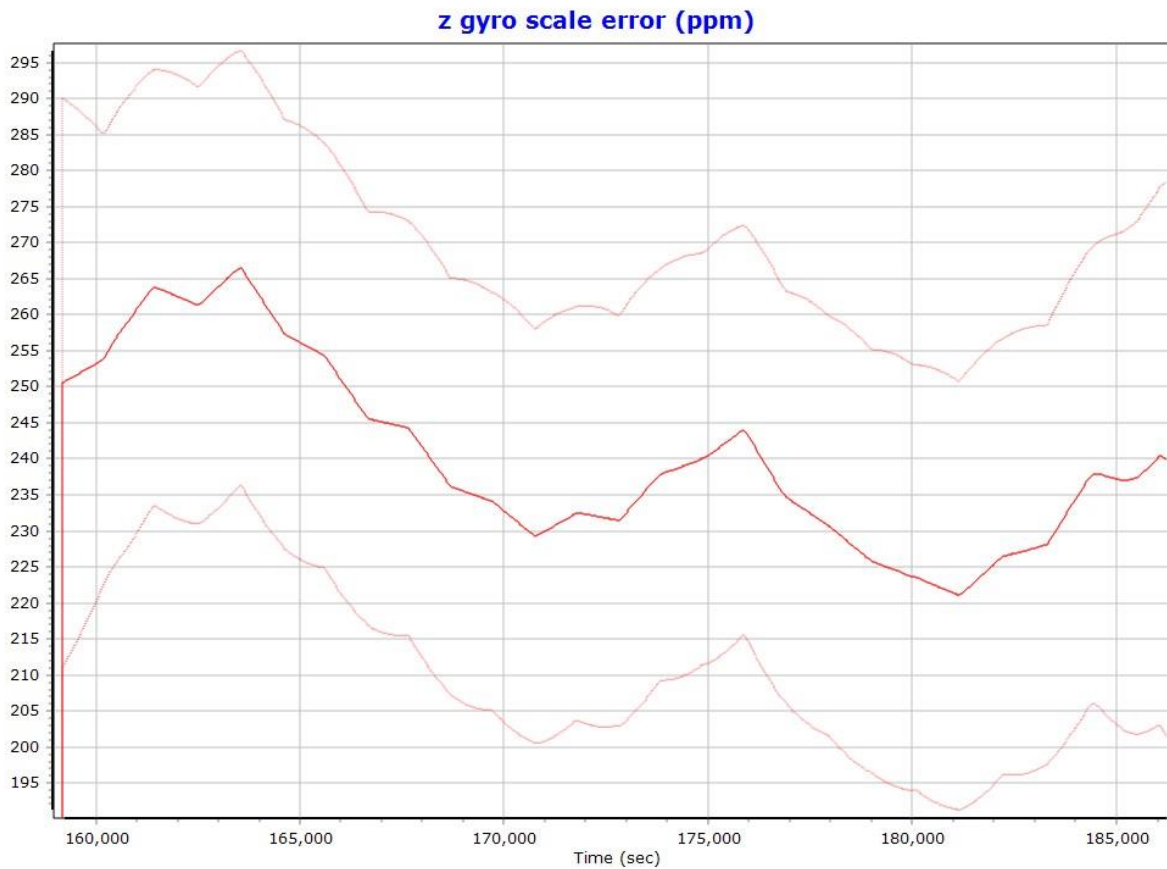
X Gyro Scale Error (ppm)



Y Gyro Scale Error (ppm)



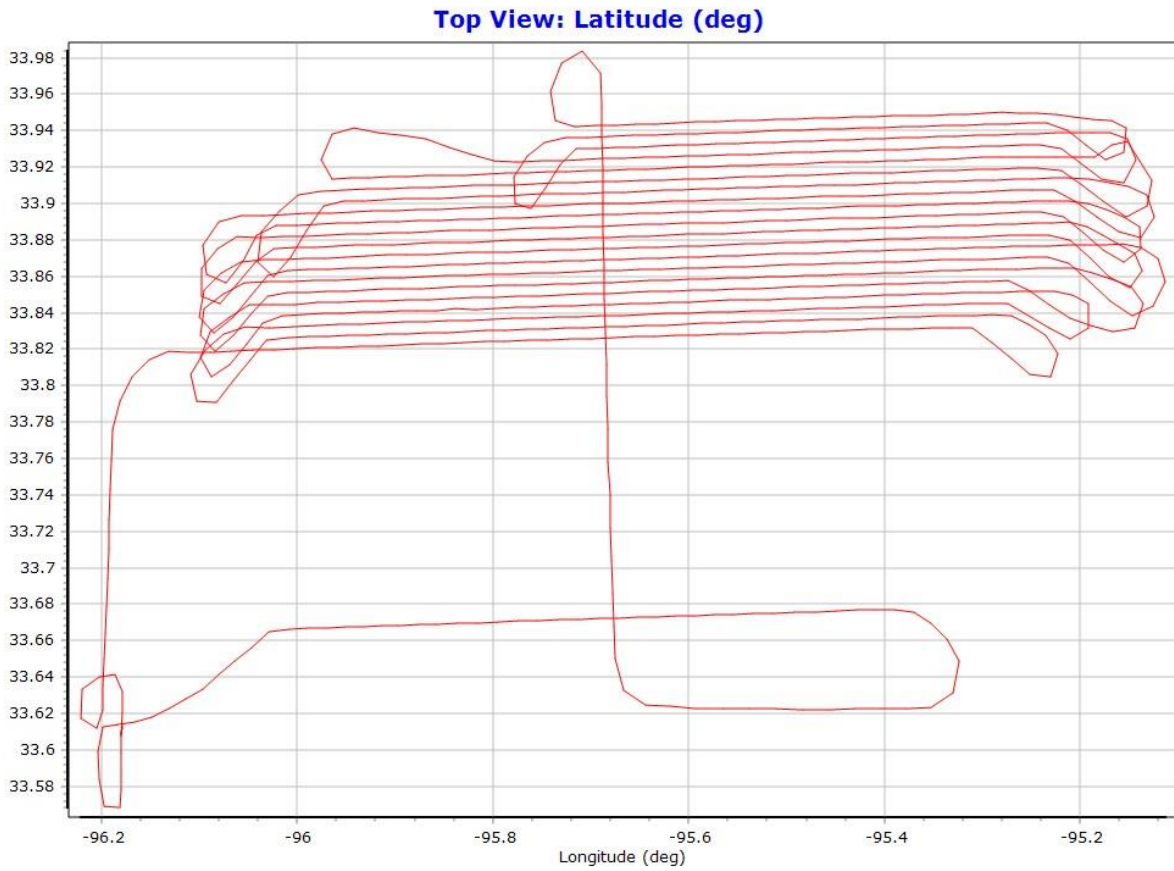
Z Gyro Scale Error (ppm)



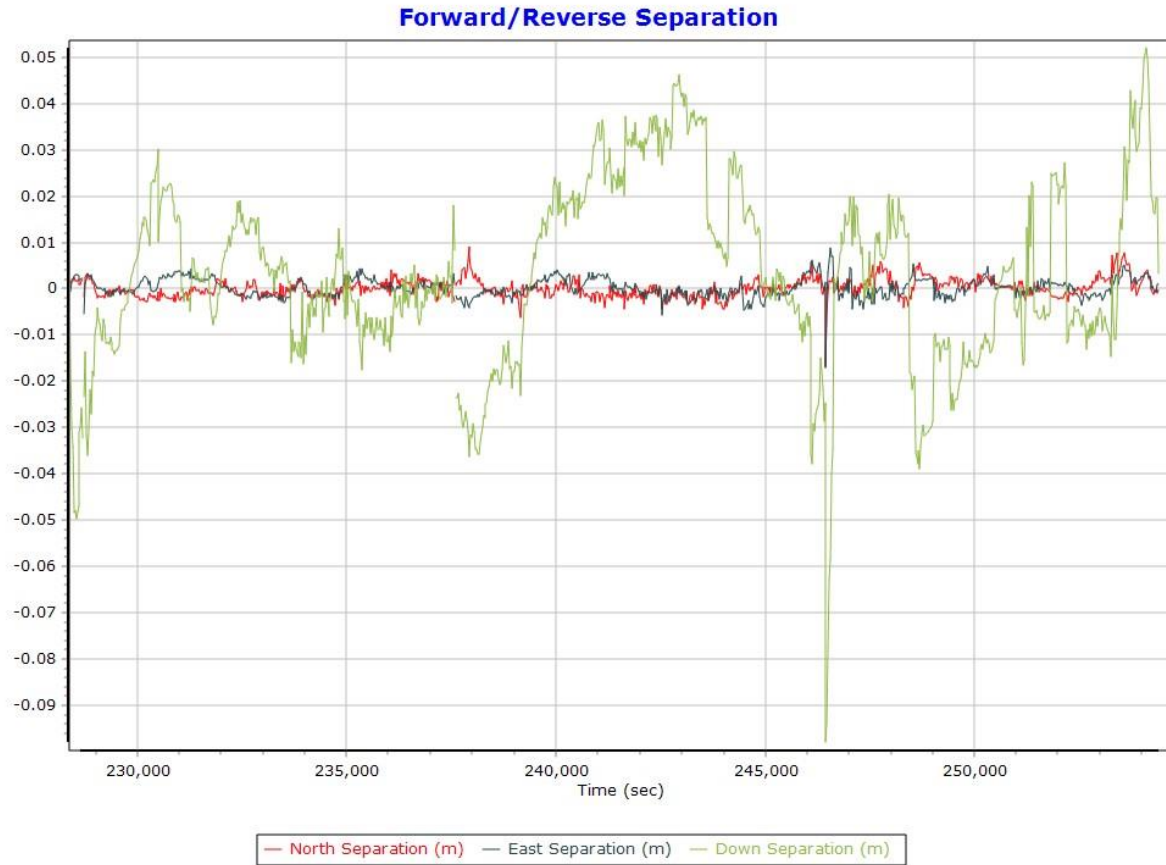
Flight 6

Trajectory Information

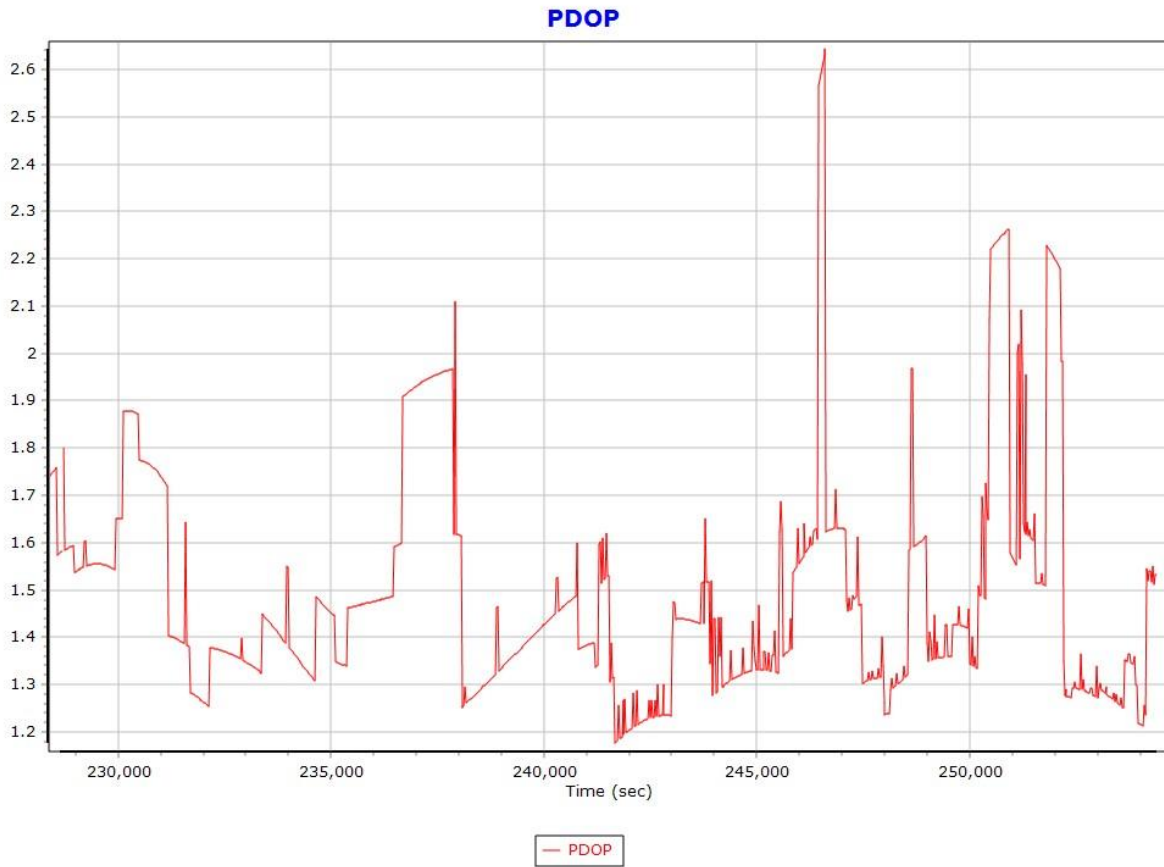
Top View



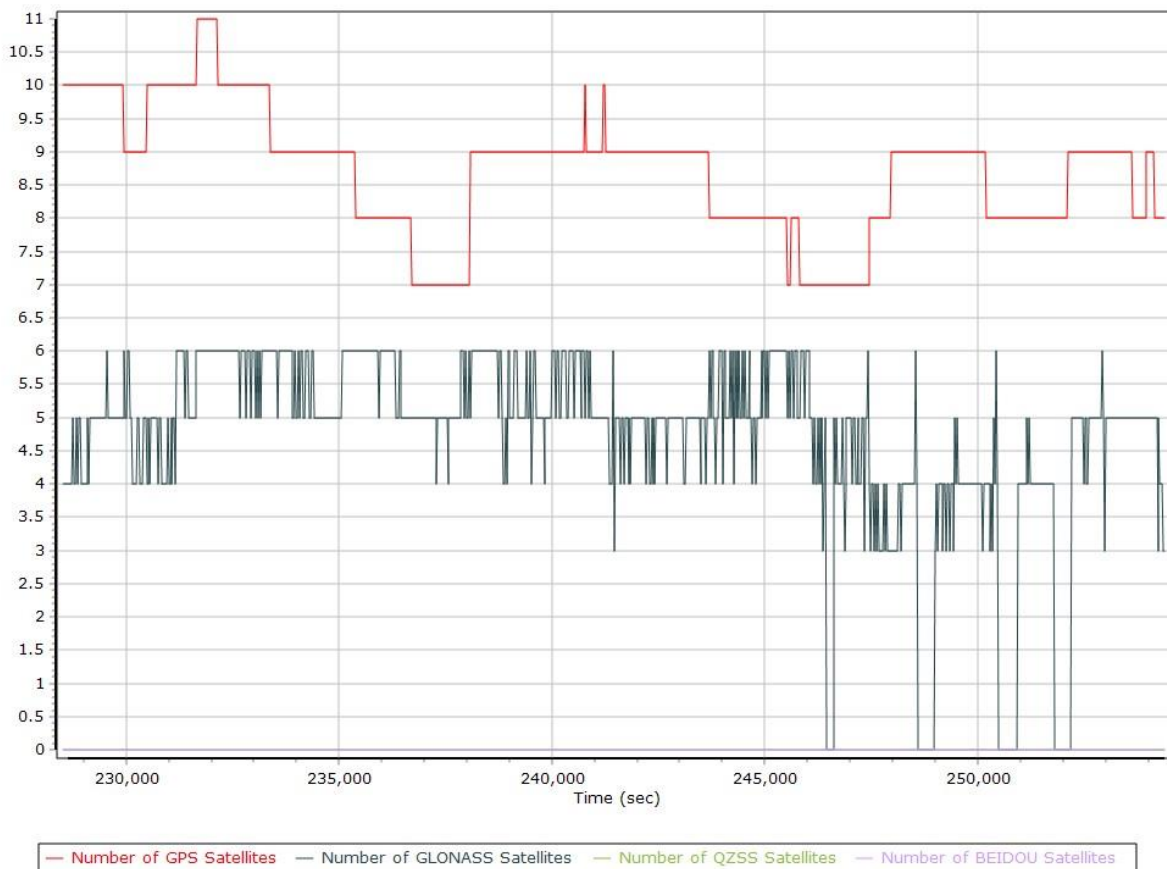
Forward/ Reverse Separation



PDOP



Number of Satellites



Processing Summary Information

Version: 4.30.3108 POSpac MMS 8.2 Project:
flight6
Solution Type: Combined Fwd/Rev

Number of Epochs:

Total in GPB file: 5214754
No processed position: N/A
Missing Fwd or Rev: N/A With
bad C/A code: N/A
With bad L1 Phase: N/A

Project: Task Order # 7 TX West Central

Date: 07.11.2019

Appendix A: GPS and IMU Processing Reports for Flight 6 Page
5 of 18

Measurement RMS Values:

L1 Phase: N/A

C/A Code: N/A

L1 Doppler: N/A

Fwd/Rev Separation RMS Values:

East: Averages from the forward/reverse plot

North: Averages from the forward/reverse plot

Height: Averages from the forward/reverse plot

Fwd/Rev Sep

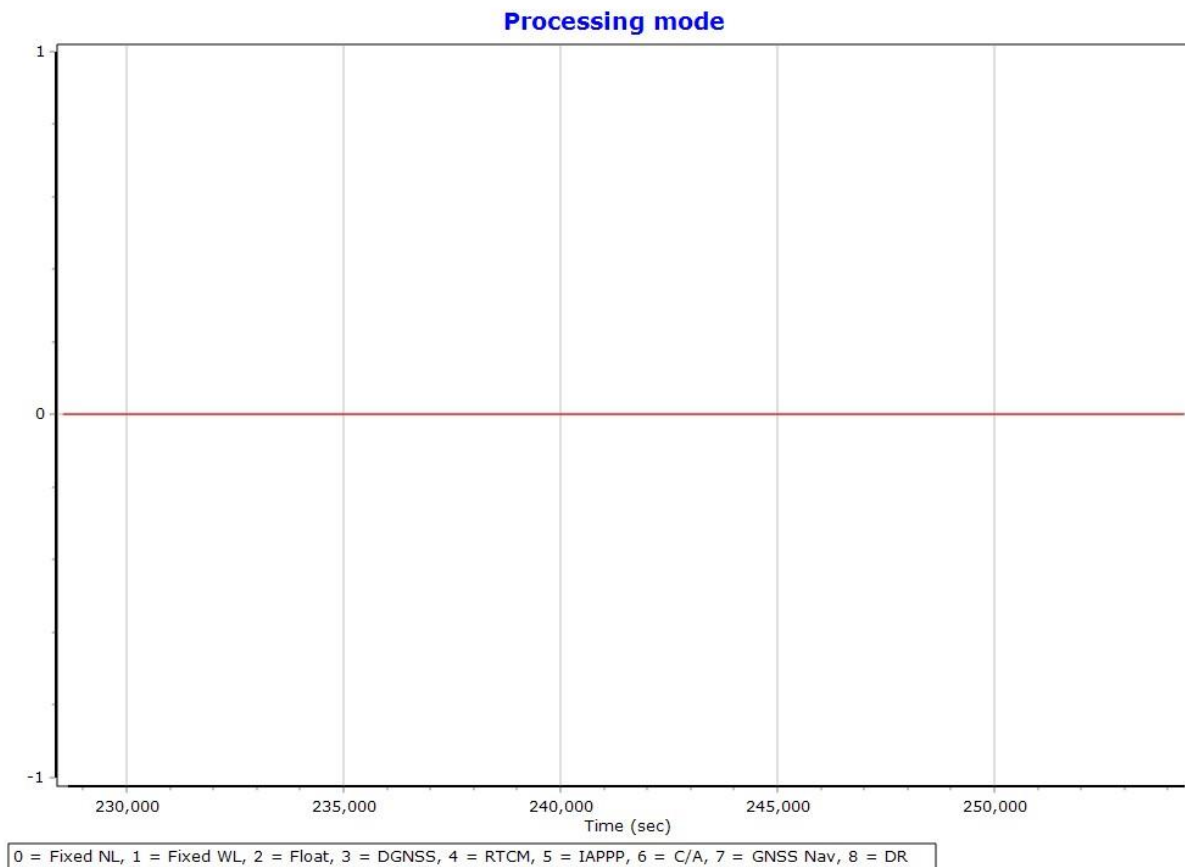
East: N/A

North: N/A

Height: N/A

Smoothed Solution Status

Processing Mode



- Q 1 "Fixed NL": 100% Q
- Q 2 "Fixed WL": 0%
- Q 3 "Float": 0% Q
- Q 4 "DGNSS": 0% Q
- Q 5 "RTCM": 0%
- Q 6 "IAPPP": 0%
- Q 7 "C/A": 0%
- Q 8 "GNSS Nav": 0%
- Q 9 "DR": 0%

Position Standard Deviation Percentages:

- 0.00 - 0.10 m: 100.0 %
- 0.10 - 0.30 m: 0.0 % 0.30
- 1.00 m: 0.0 %
- 1.00 - 5.00 m: 0.0 %
- 5.00 m + over: 0.0 %

Project: Task Order # 7 TX West Central

Date: 07.11.2019

Appendix A: GPS and IMU Processing Reports for Flight 6 Page
7 of 18

Percentages of epochs with DD_DOP over 10.00: 0.0%.

DOP over Tol: 0.0 %

Baseline Distances:

Maximum: 43.287 (km)

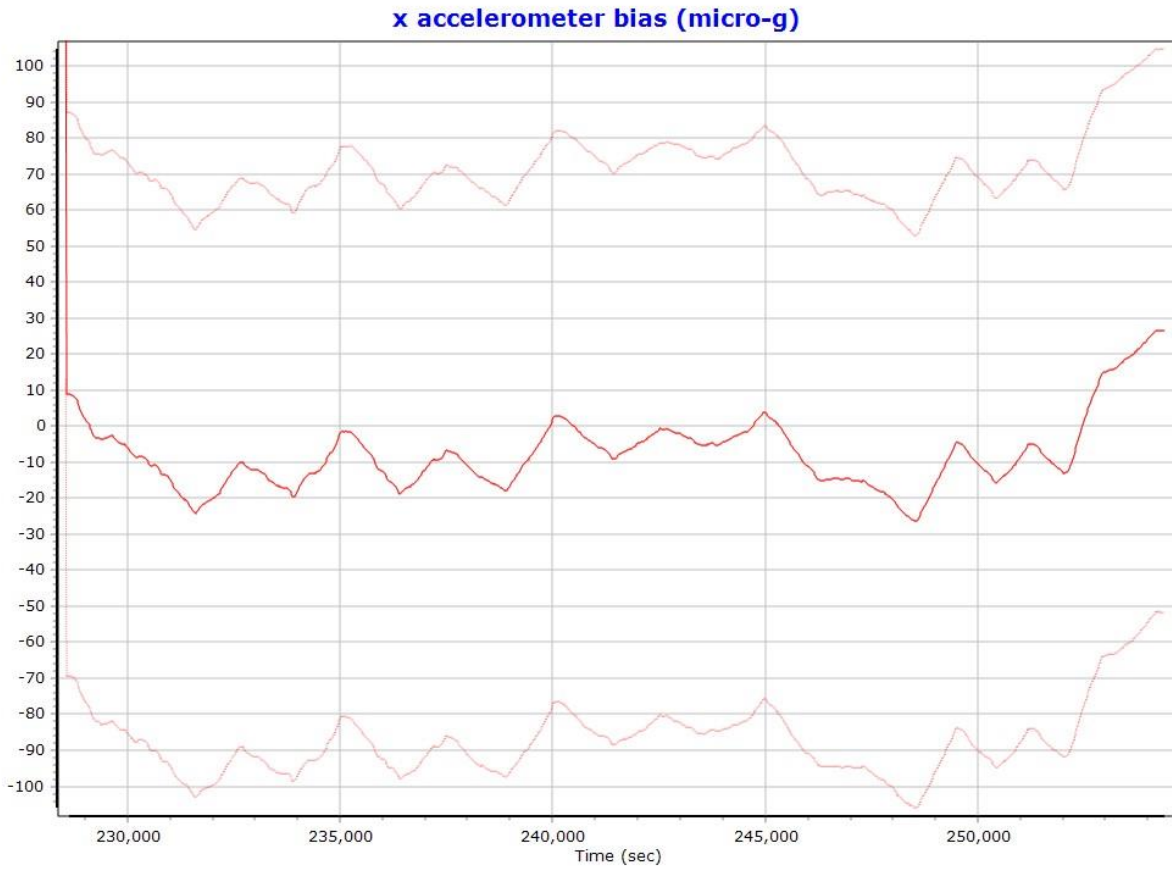
Minimum: 0.391 (km) Average:

~30 (km)

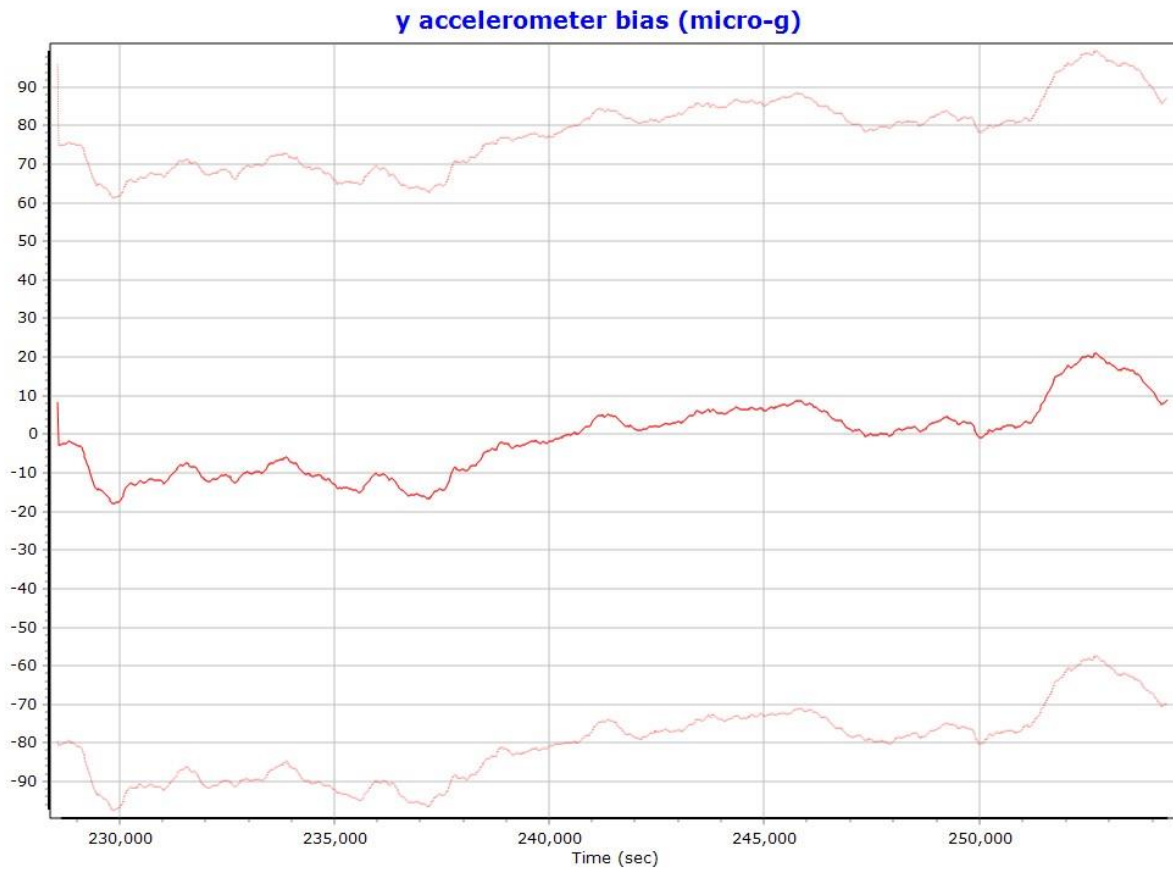
First Epoch: 0.707 (km) Last

Epoch: 1.348 (km)

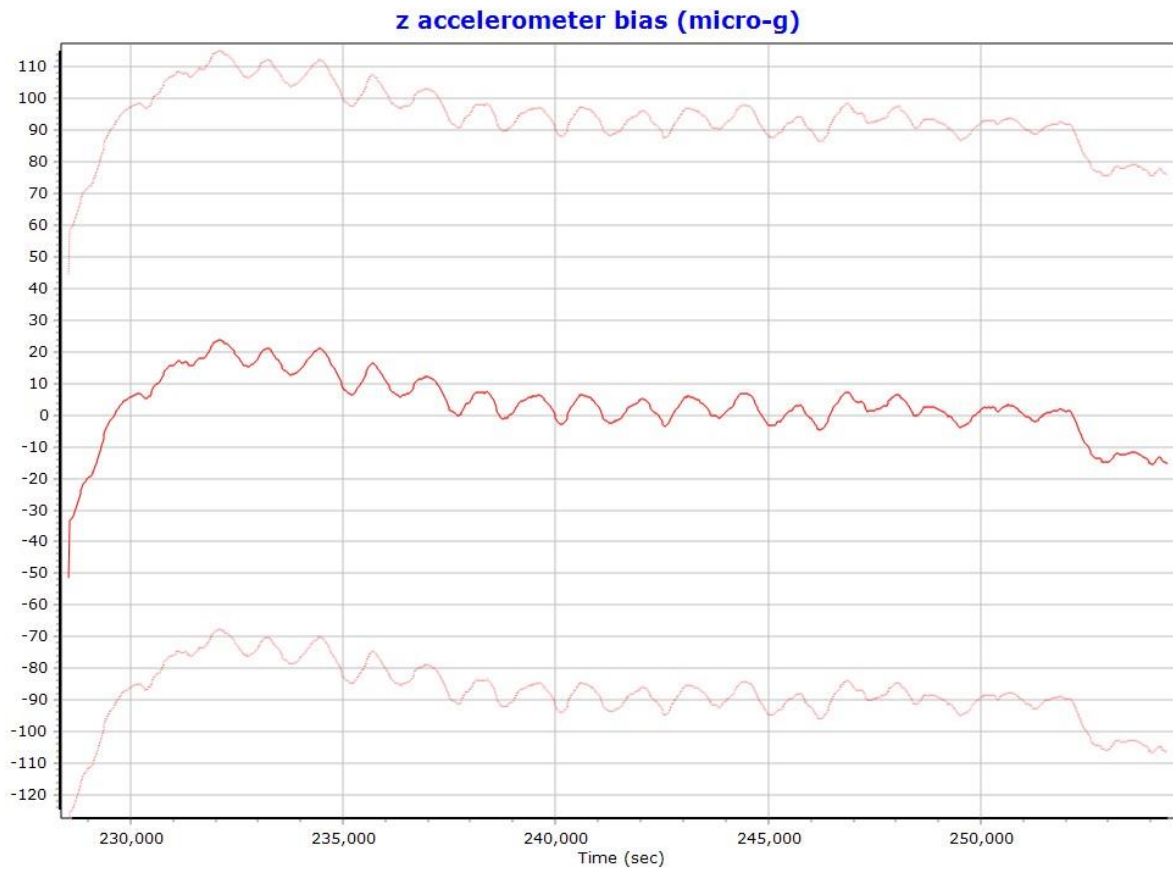
Sensor Errors X Accelerometer Bias (micro-g)



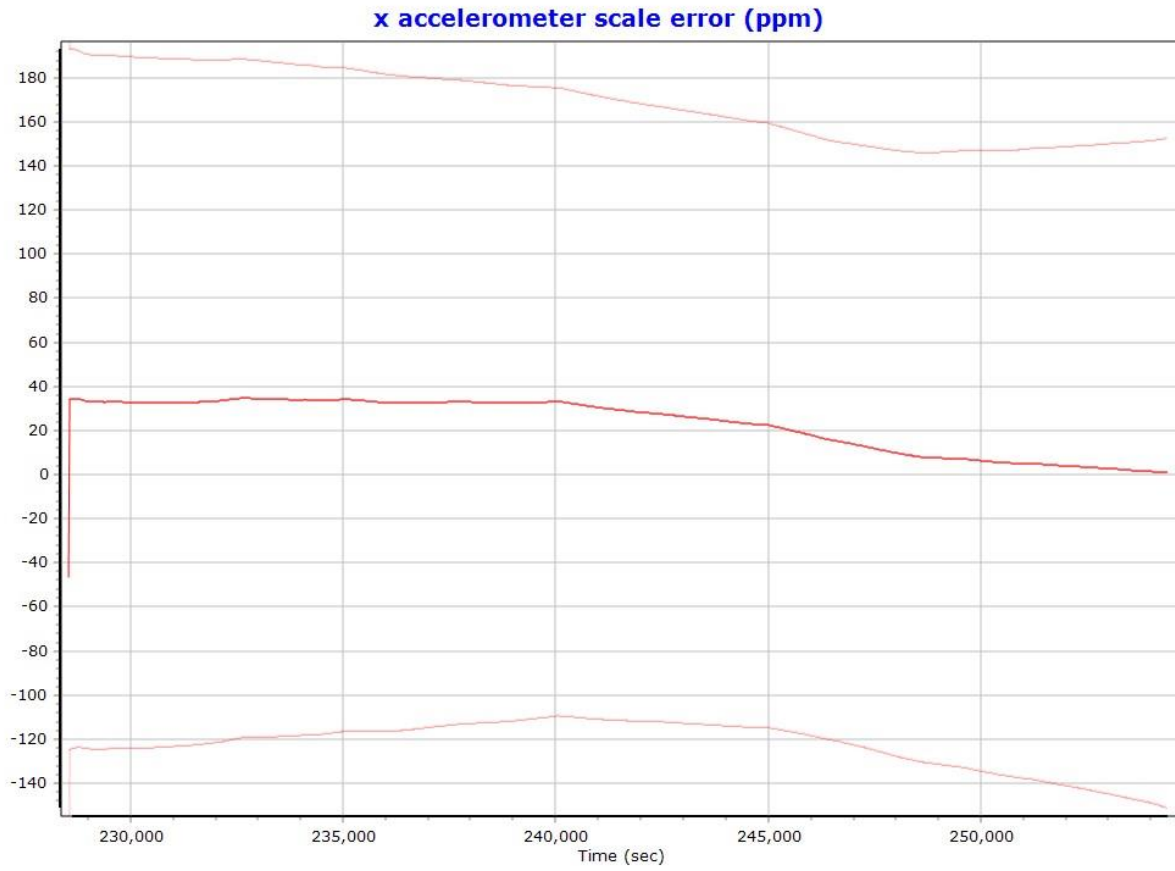
Y Accelerometer Bias (micro-g)



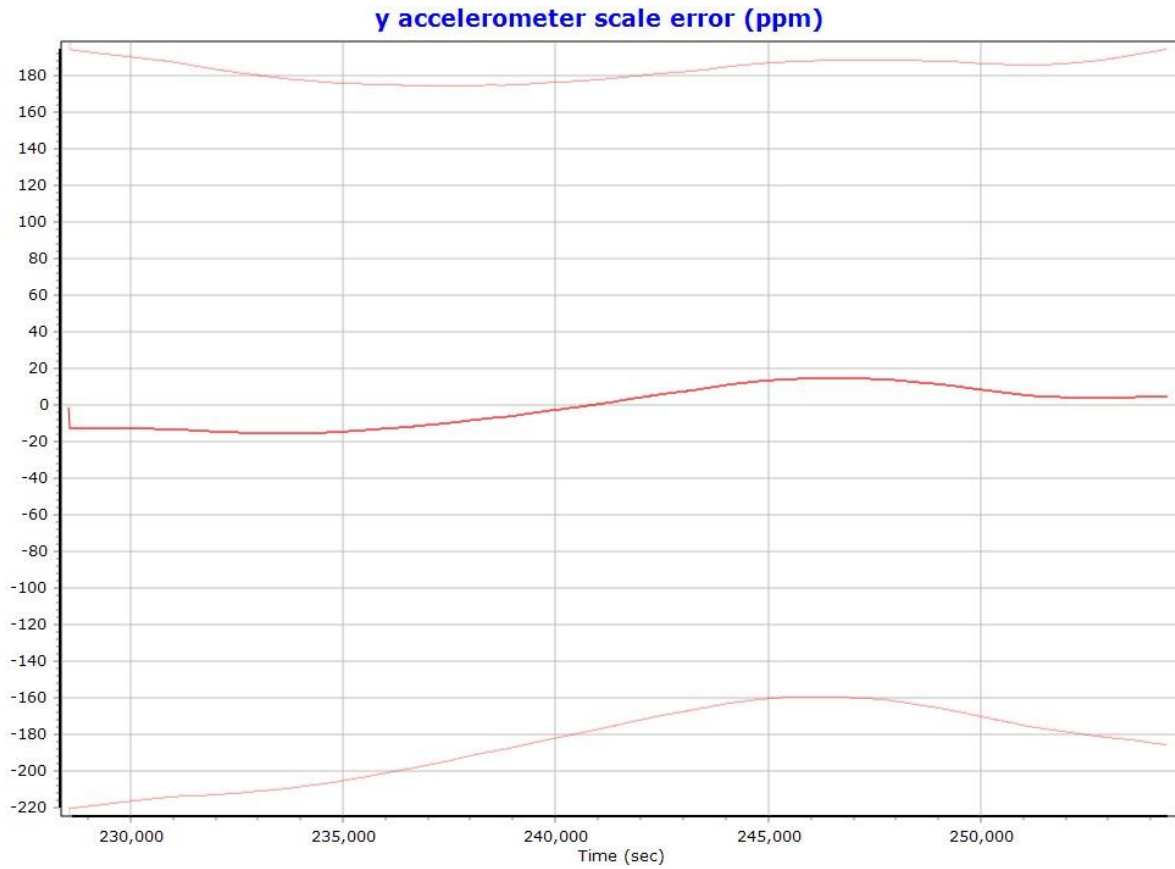
Z Accelerometer Bias (micro-g)



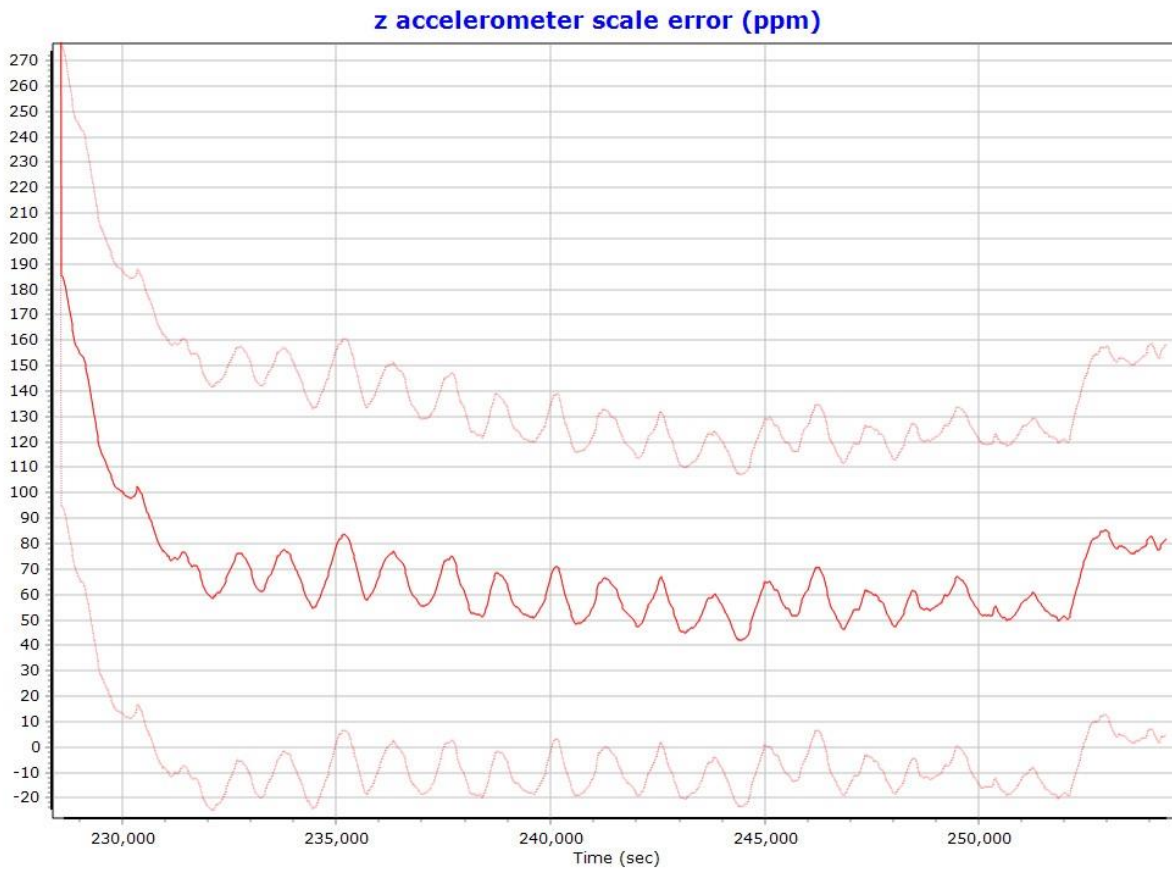
X Accelerometer Scale Error (ppm)



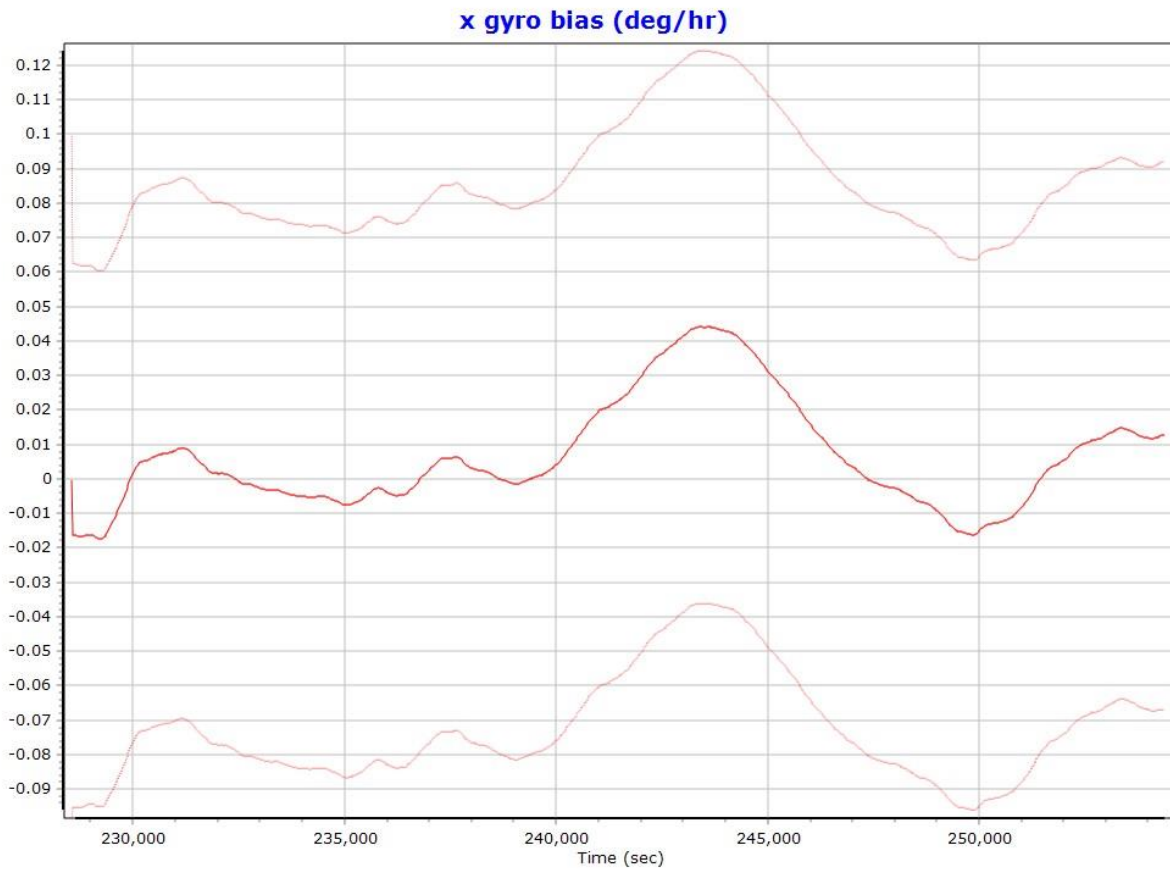
Y Accelerometer Scale Error (ppm)



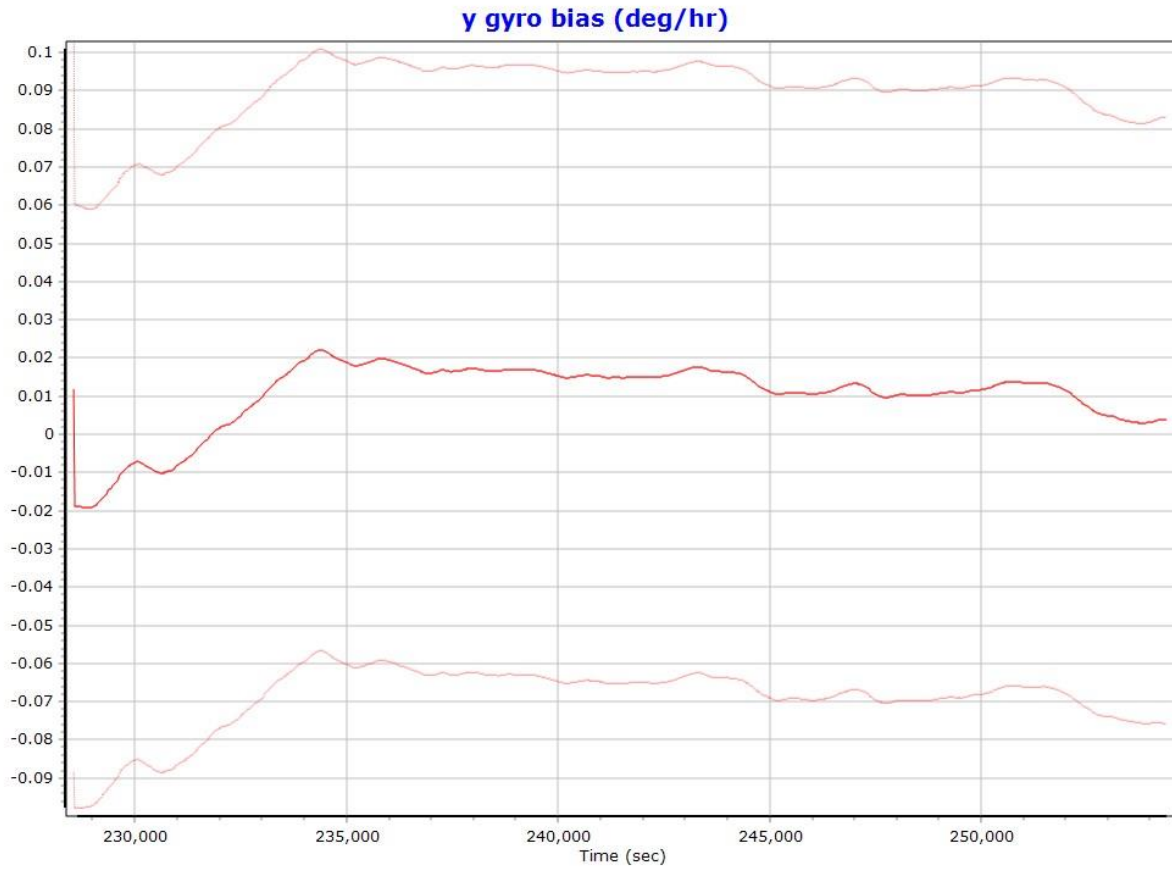
Z Accelerometer Scale Error (ppm)



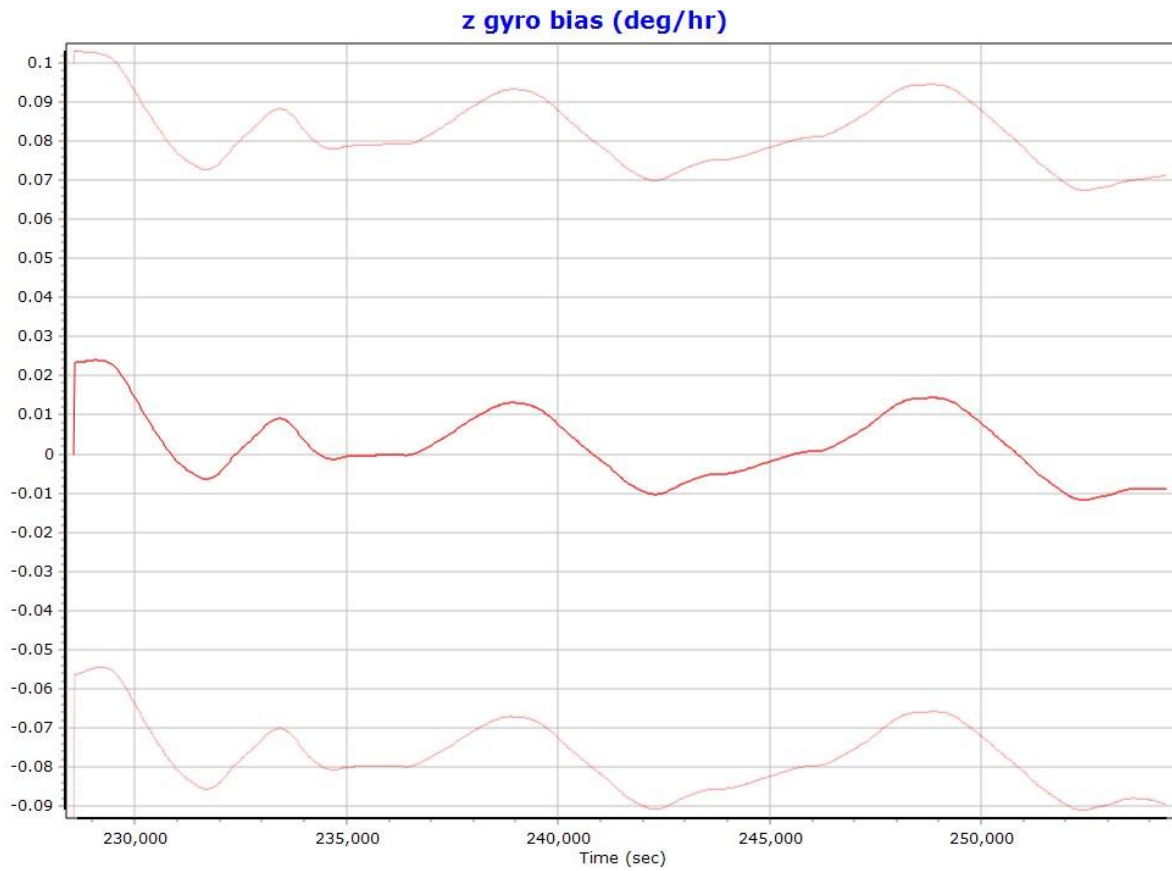
X Gyro Bias (deg/h)



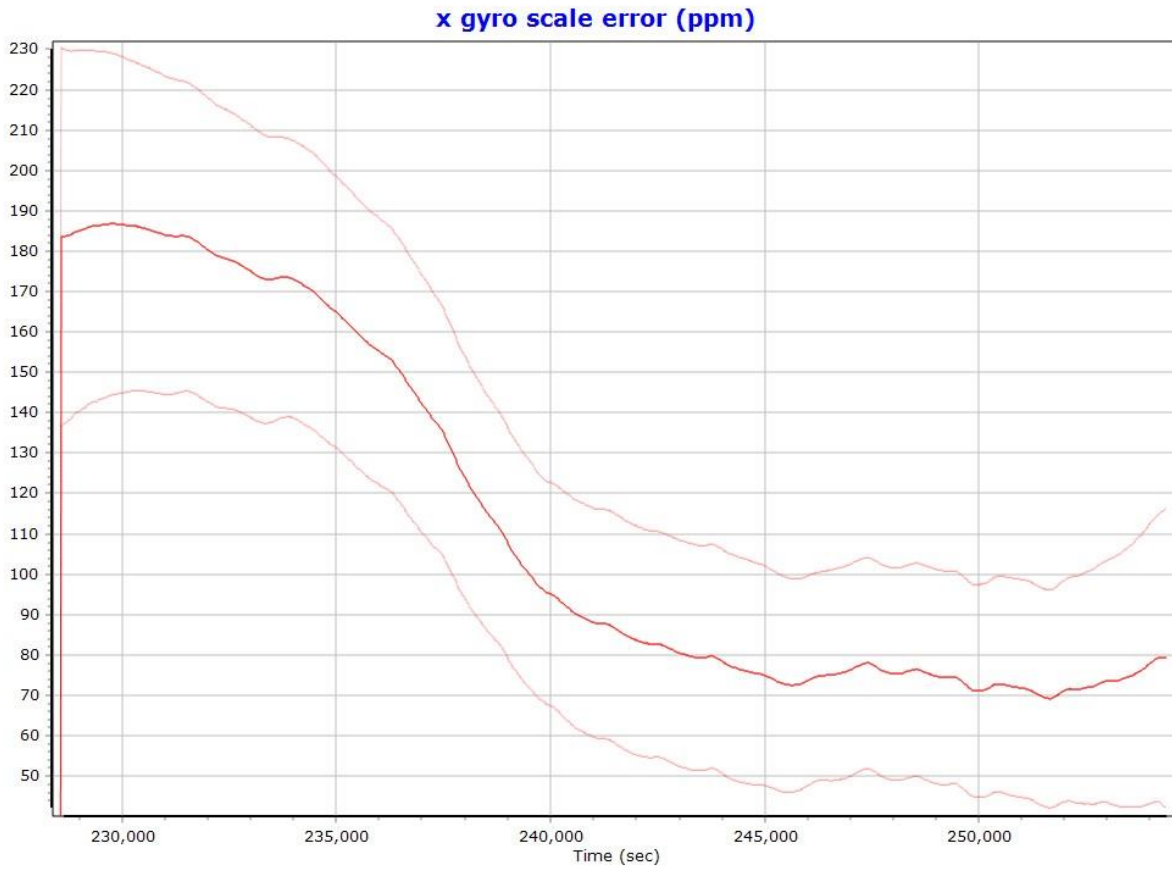
Y Gyro Bias (deg/h)



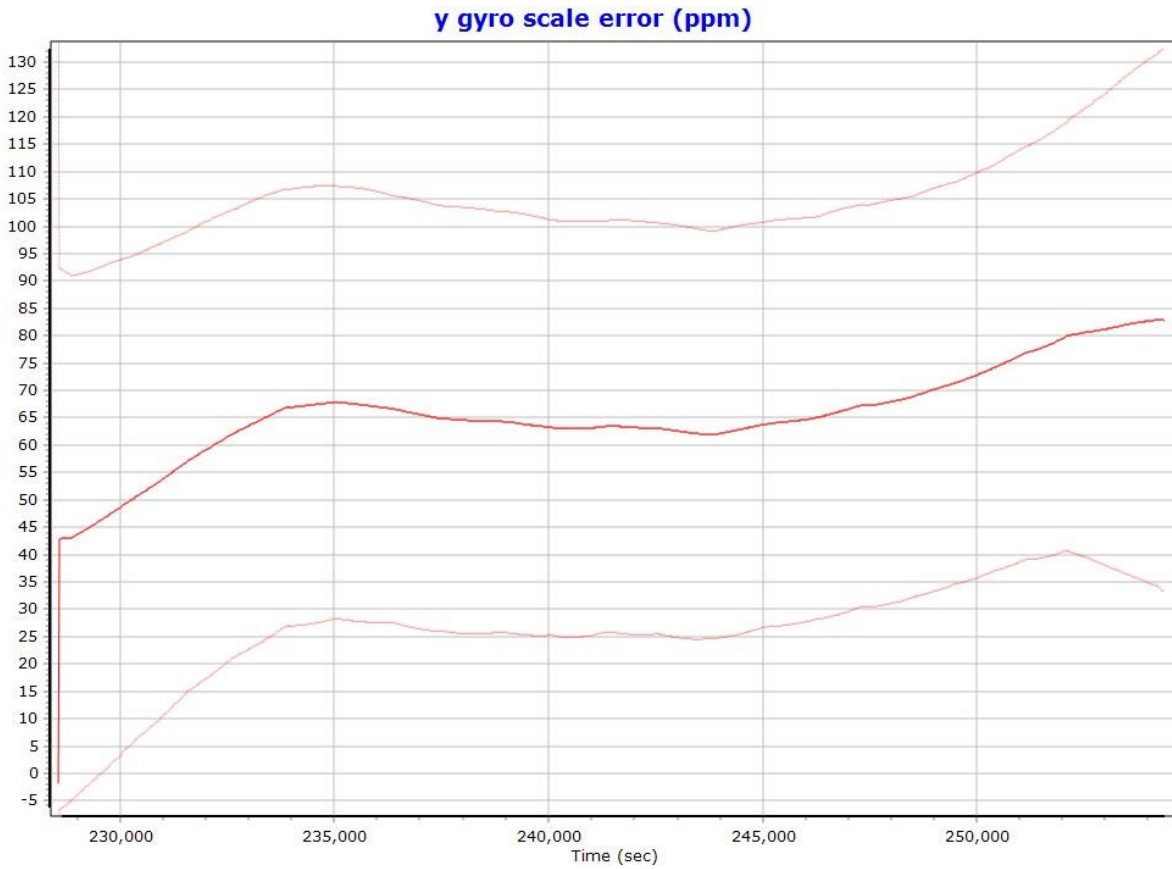
Z Gyro Bias (deg/h)



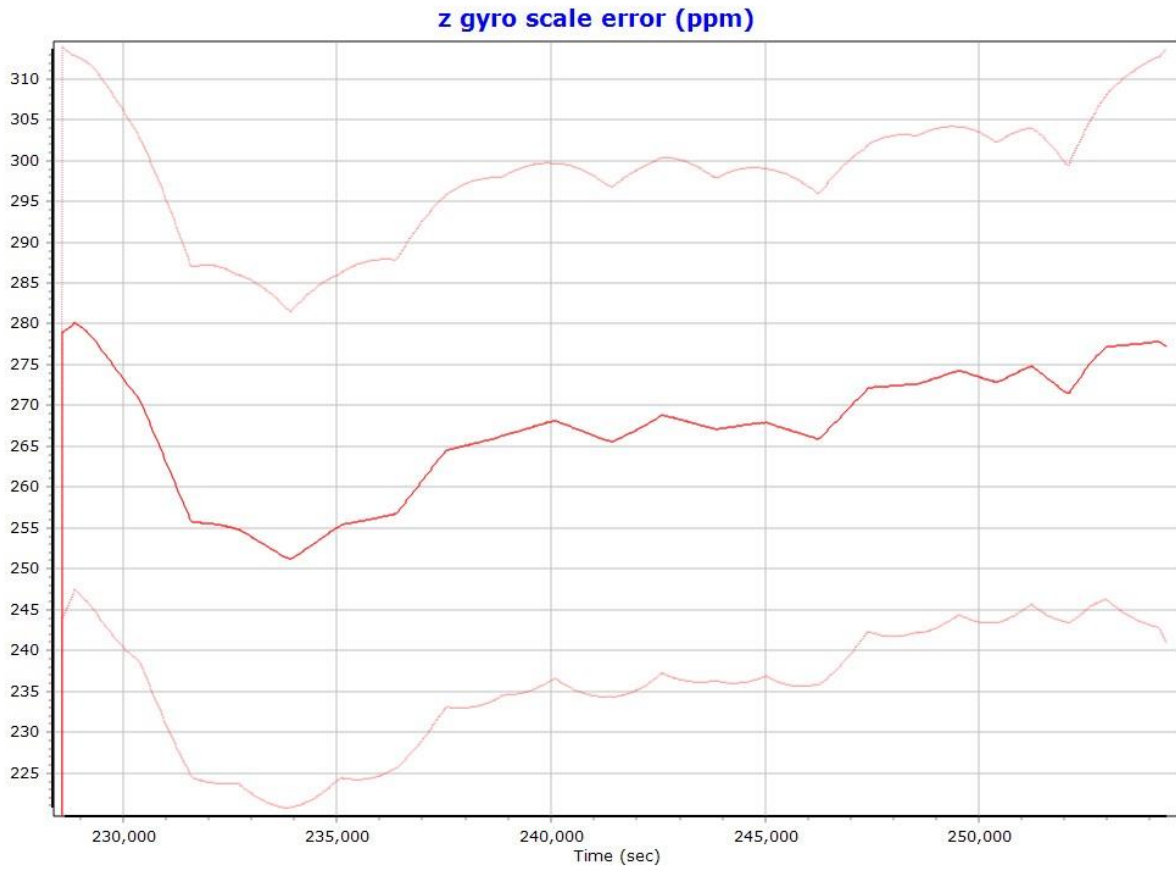
X Gyro Scale Error (ppm)



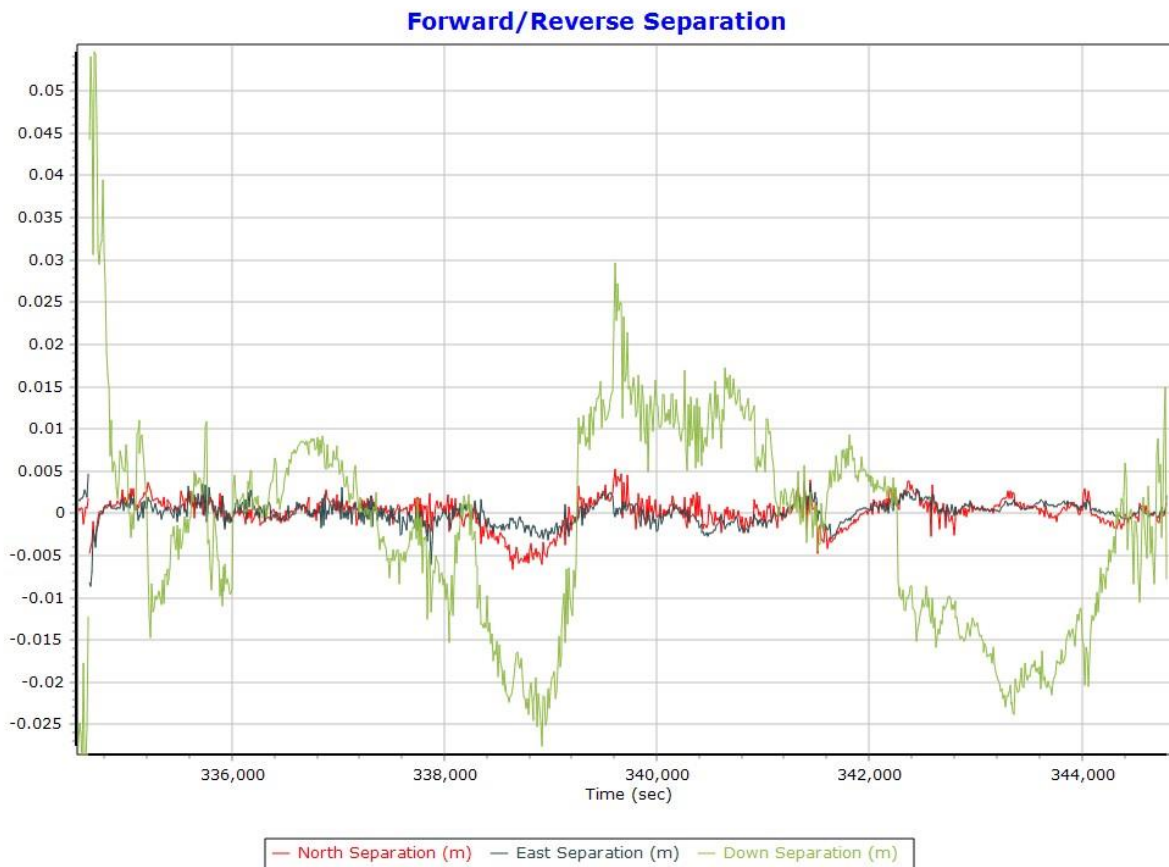
Y Gyro Scale Error (ppm)



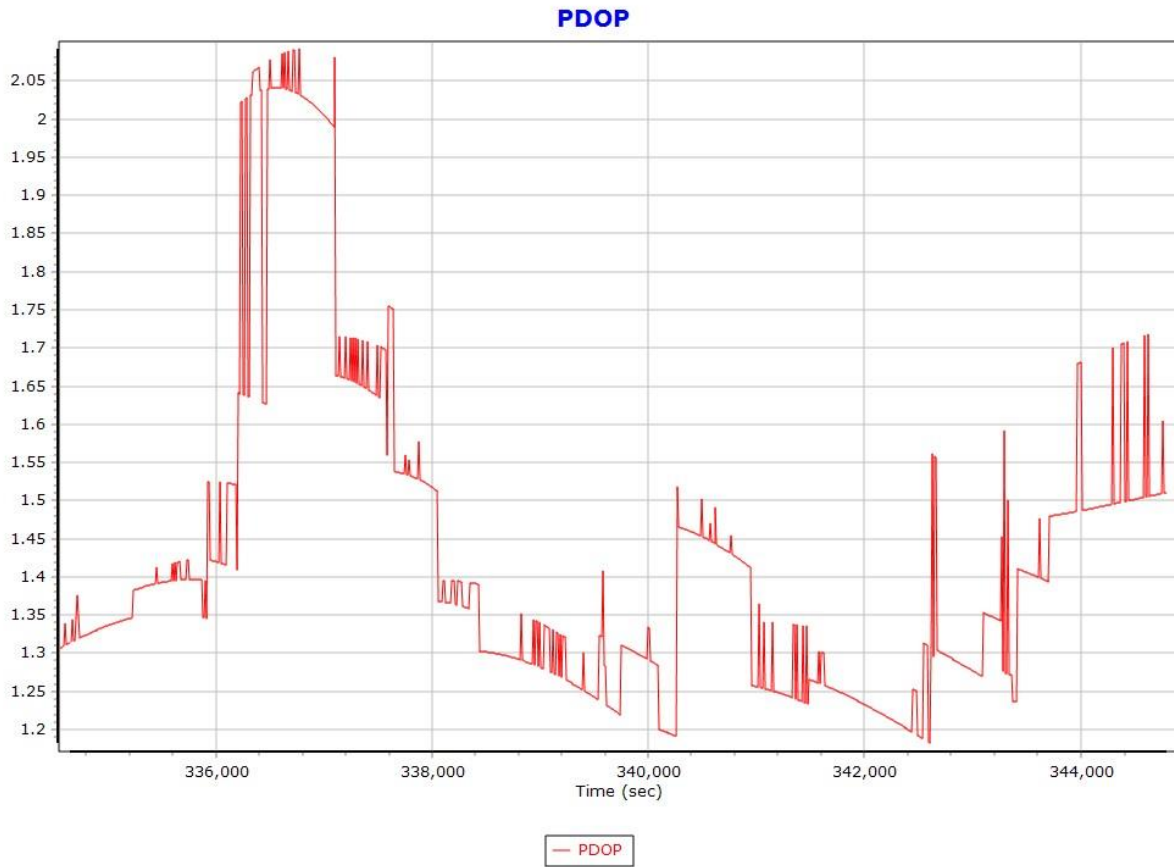
Z Gyro Scale Error (ppm)



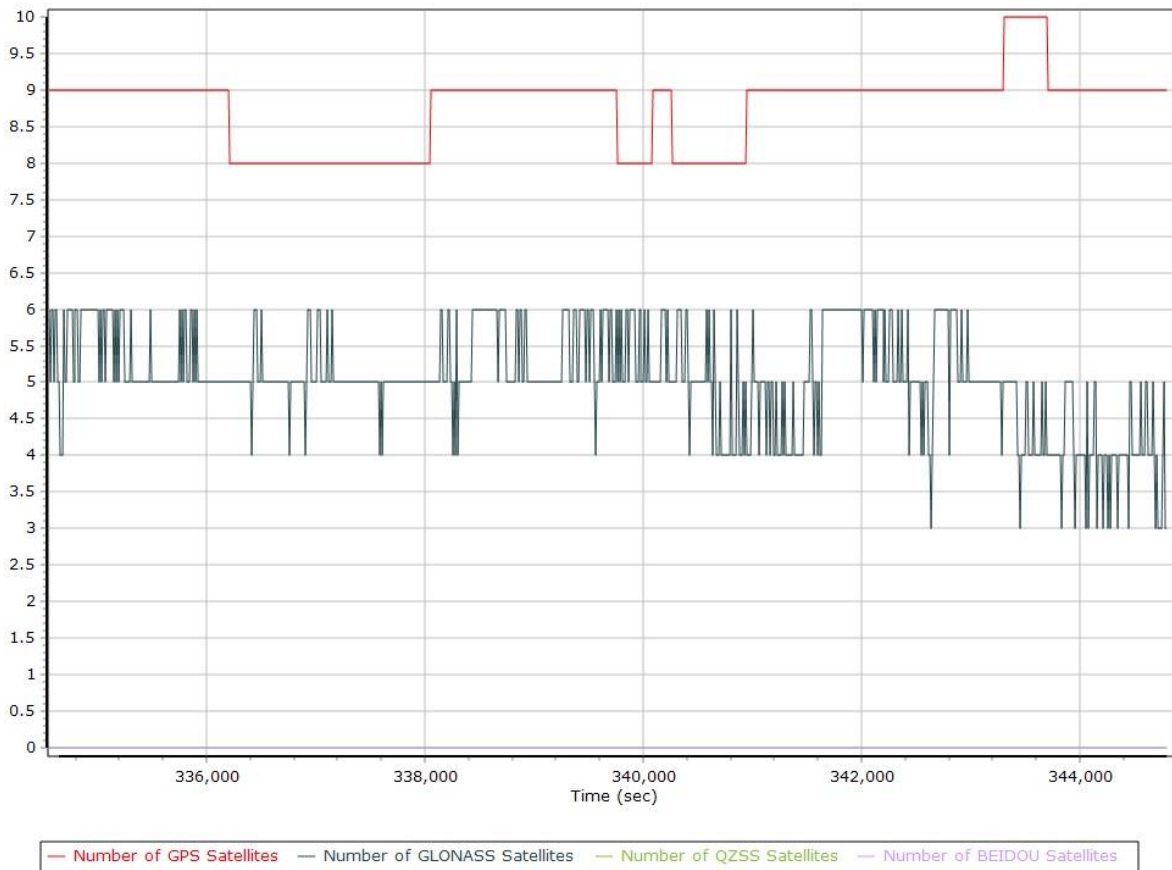
Forward/ Reverse Separation



PDOP



Number of Satellites



Processing Summary Information

Version: 4.30.3108 POSpac MMS 8.2 Project:
flight7
Solution Type: Combined Fwd/Rev

Number of Epochs:

Total in GPB file: 2095293
No processed position: N/A
Missing Fwd or Rev: N/A With
bad C/A code: N/A
With bad L1 Phase: N/A

Project: Task Order # 7 TX West Central

Date: 07.11.2019

Appendix A: GPS and IMU Processing Reports for Flight 7 Page
5 of 18

Measurement RMS Values:

L1 Phase: N/A

C/A Code: N/A

L1 Doppler: N/A

Fwd/Rev Separation RMS Values:

East: Averages from the forward/reverse plot

North: Averages from the forward/reverse plot

Height: Averages from the forward/reverse plot

Fwd/Rev Sep

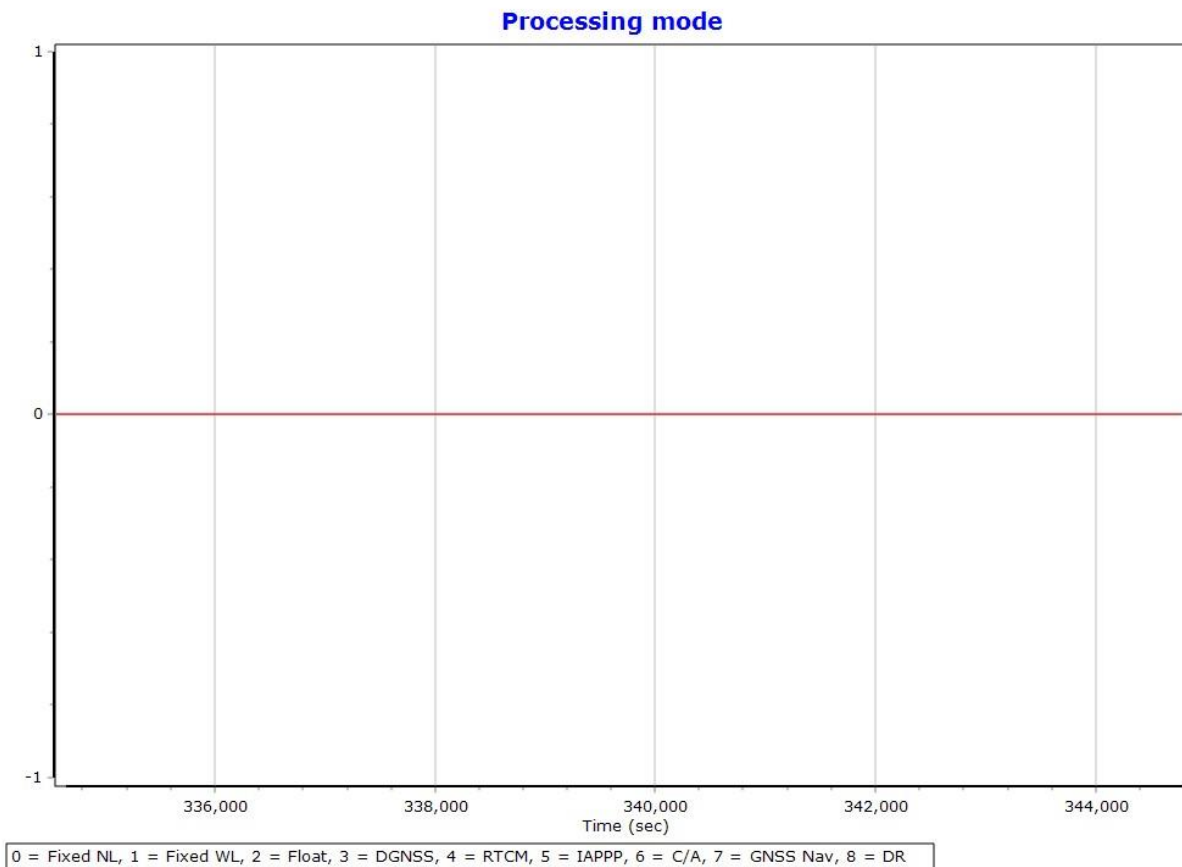
East: N/A

North: N/A

Height: N/A

Smoothed Solution Status

Processing Mode



Q 1 "Fixed NL": 100% Q

Q 2 "Fixed WL": 0%

Q 3 "Float": 0% Q

Q 4 "DGNSS": 0% Q

Q 5 "RTCM": 0%

Q 6 "IAPPP": 0%

Q 7 "C/A": 0%

Q 8 "GNSS Nav": 0%

Q 9 "DR": 0%

Position Standard Deviation Percentages:

0.00 - 0.10 m: 100.0 %

0.10 - 0.30 m: 0.0 % 0.30

- 1.00 m: 0.0 %

1.00 - 5.00 m: 0.0 %

5.00 m + over: 0.0 %

Project: Task Order # 7 TX West Central

Date: 07.11.2019

Appendix A: GPS and IMU Processing Reports for Flight 7 Page
7 of 18

Percentages of epochs with DD_DOP over 10.00: 0.0%.

DOP over Tol: 0.0 %

Baseline Distances:

Maximum: 43.471 (km)

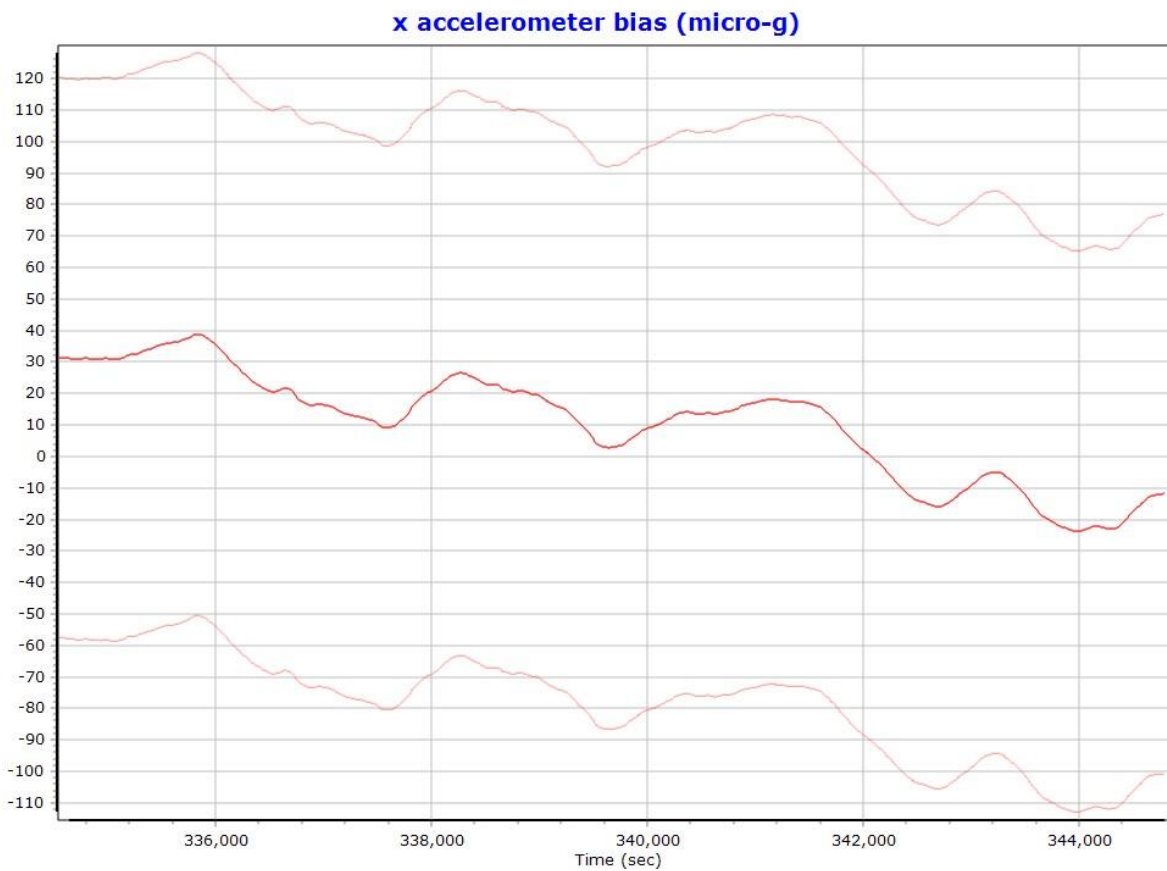
Minimum: 0.394 (km) Average:

~26 (km)

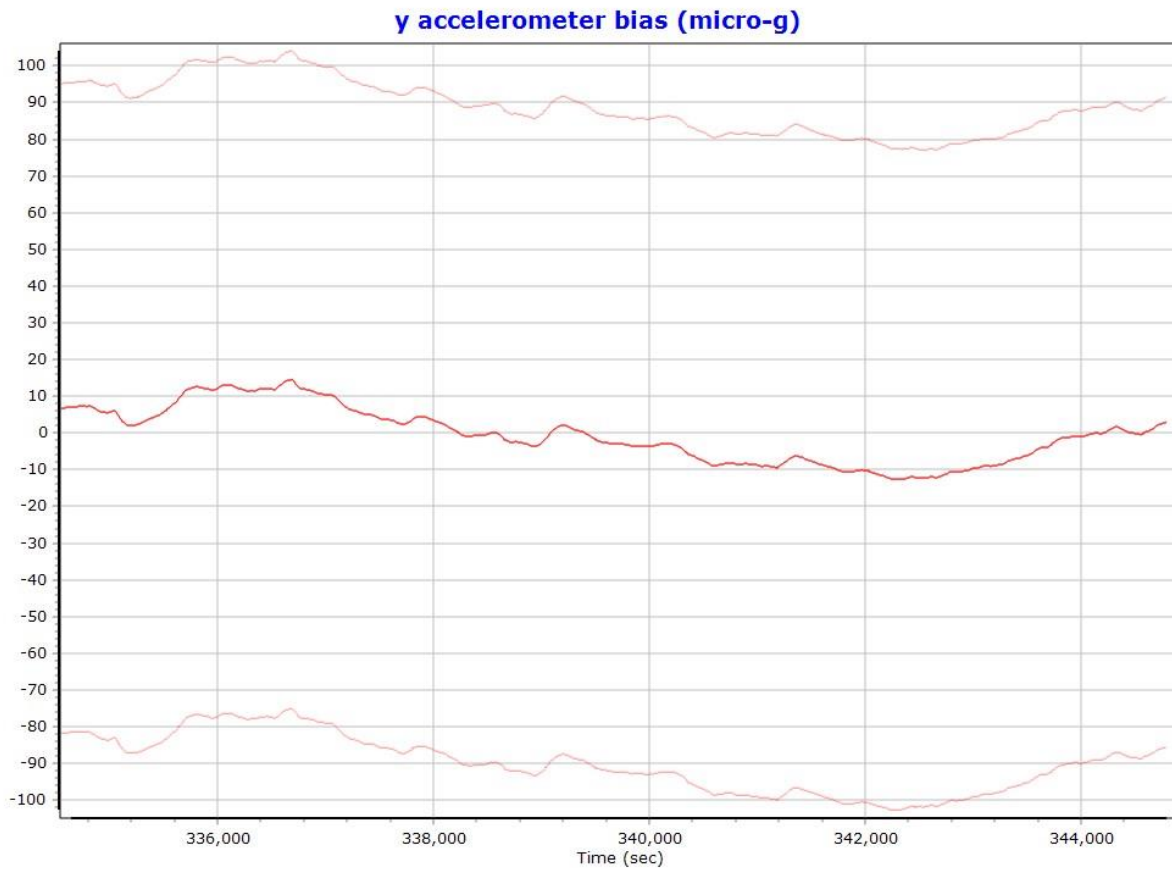
First Epoch: 0.733 (km) Last

Epoch: 1.351 (km)

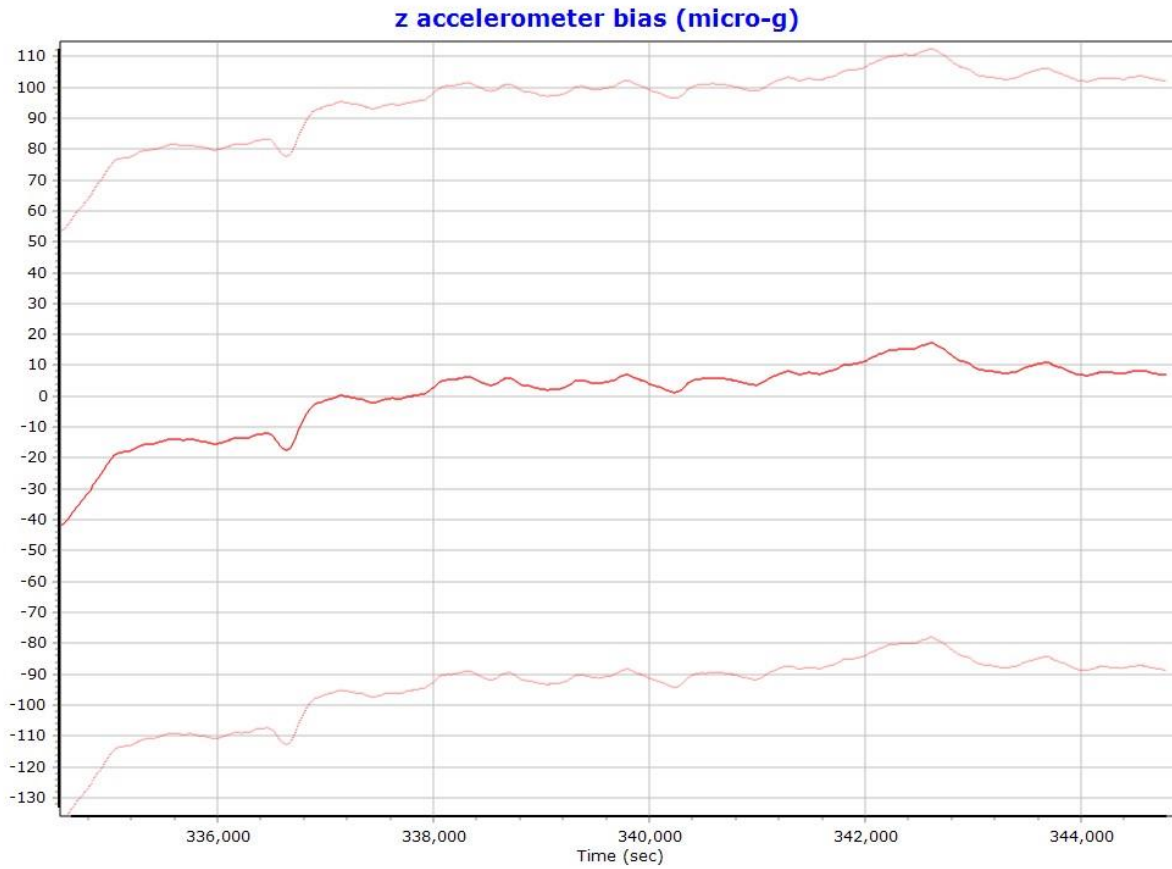
Sensor Errors X Accelerometer Bias (micro-g)



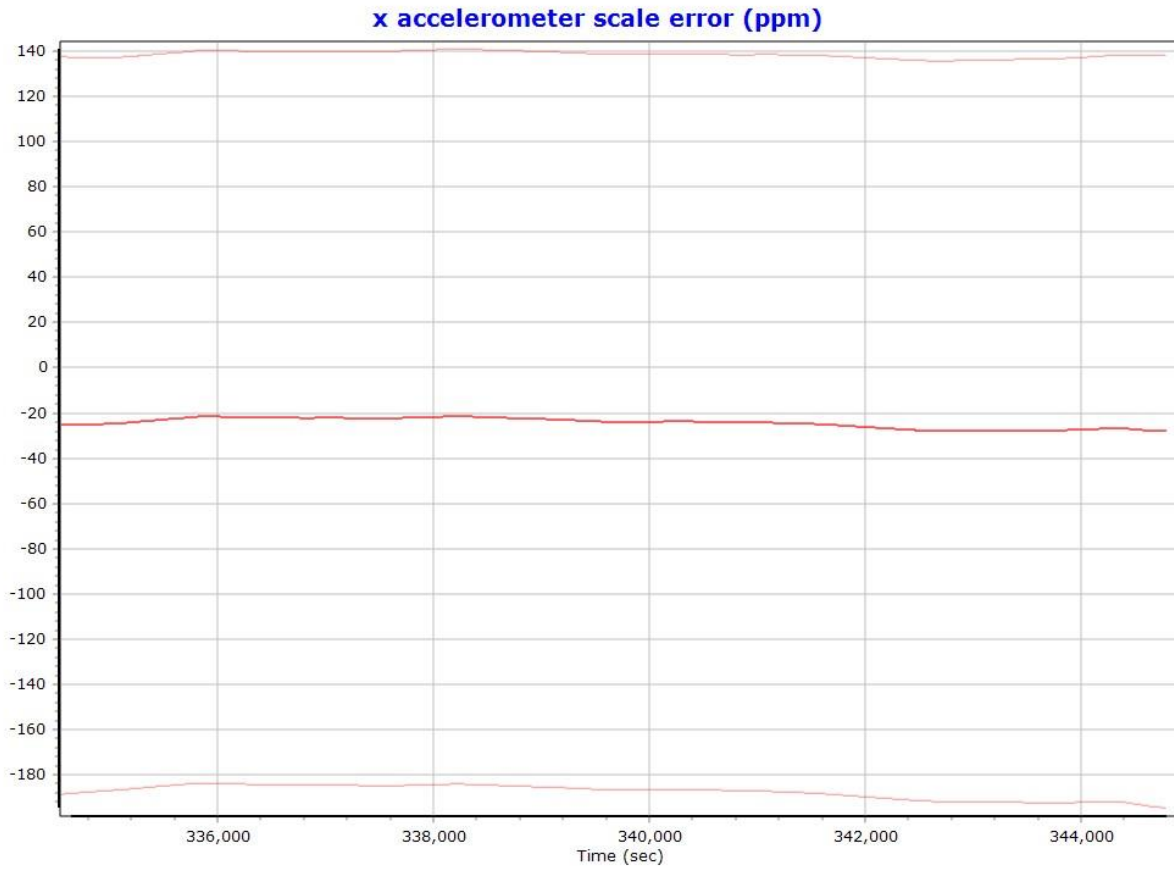
Y Accelerometer Bias (micro-g)



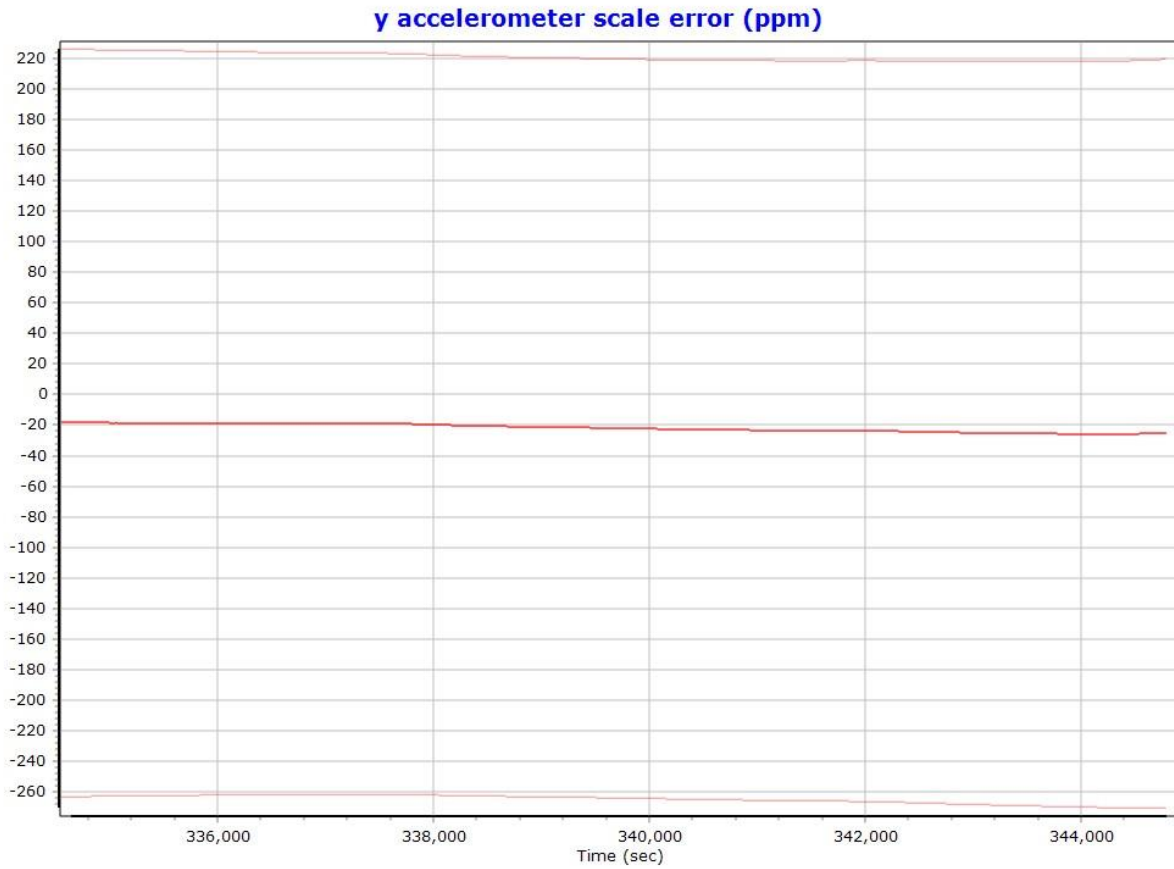
Z Accelerometer Bias (micro-g)



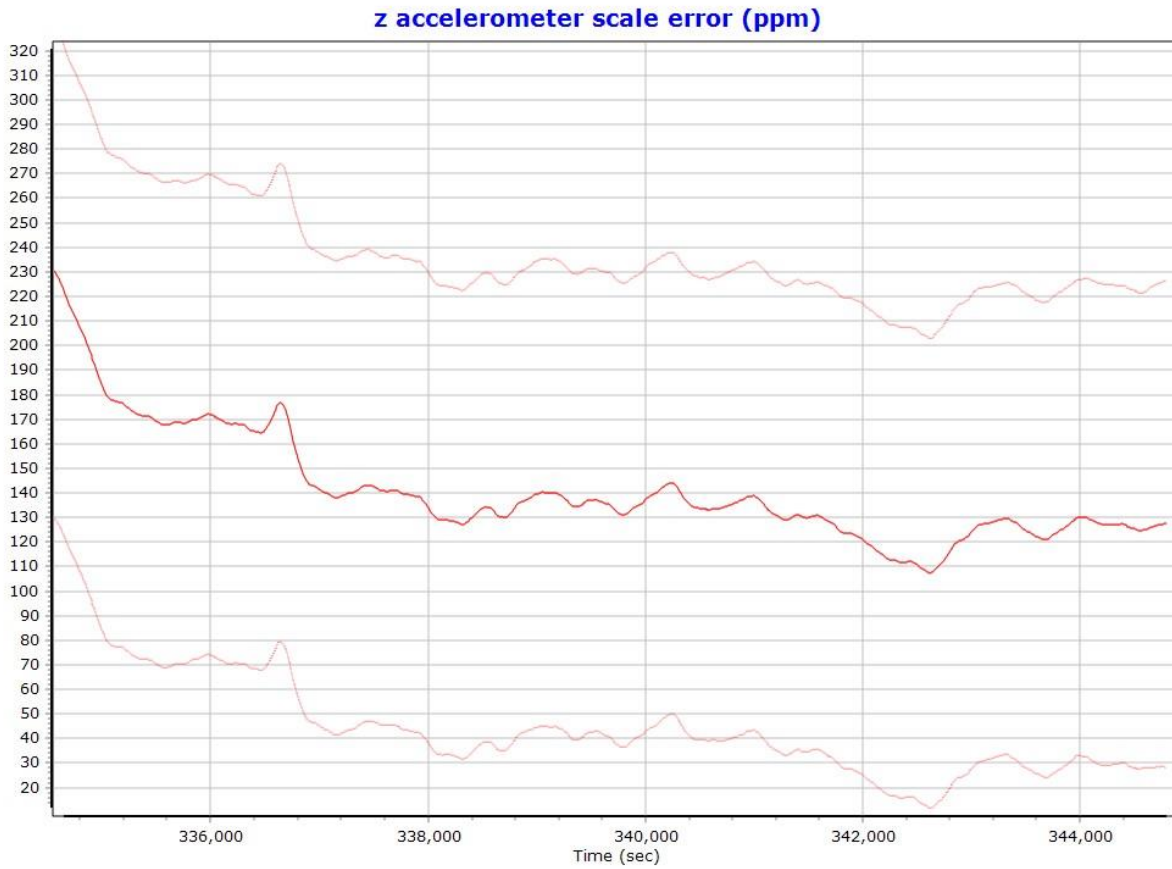
X Accelerometer Scale Error (ppm)



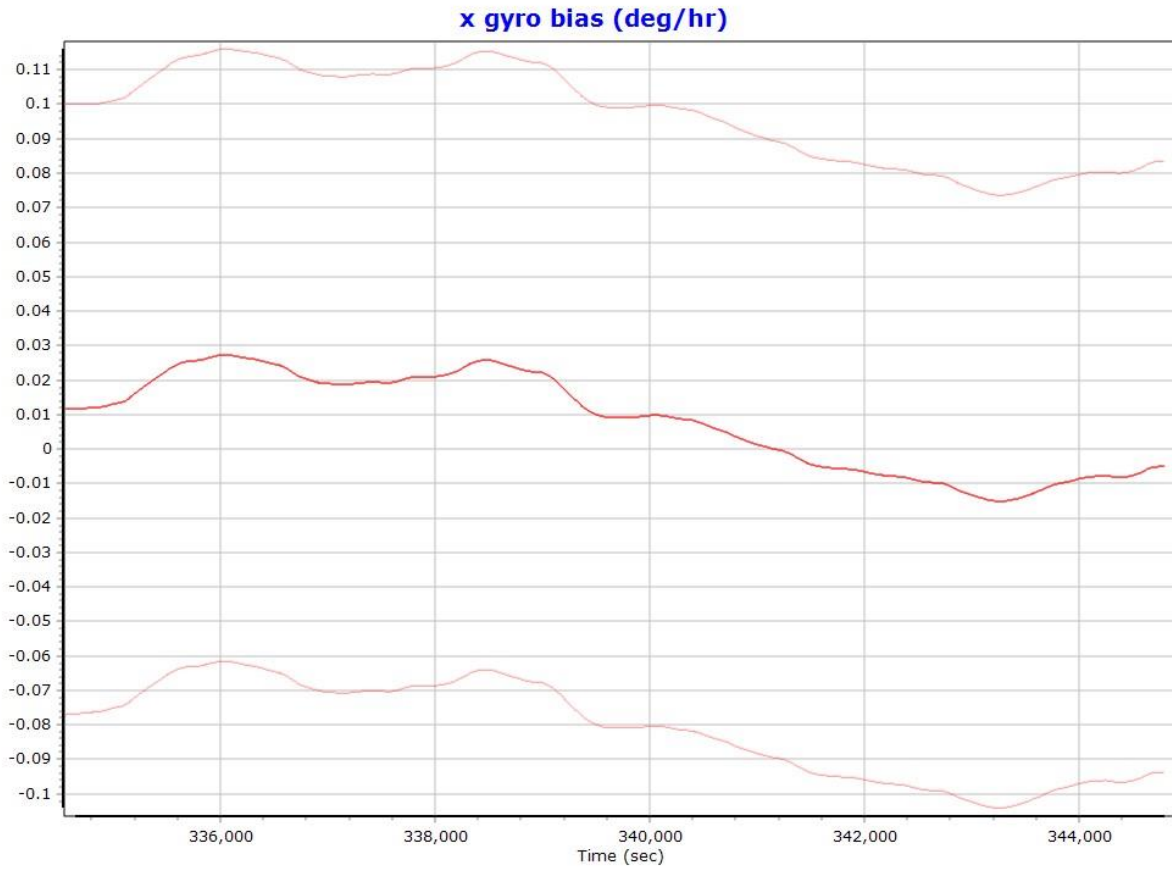
Y Accelerometer Scale Error (ppm)



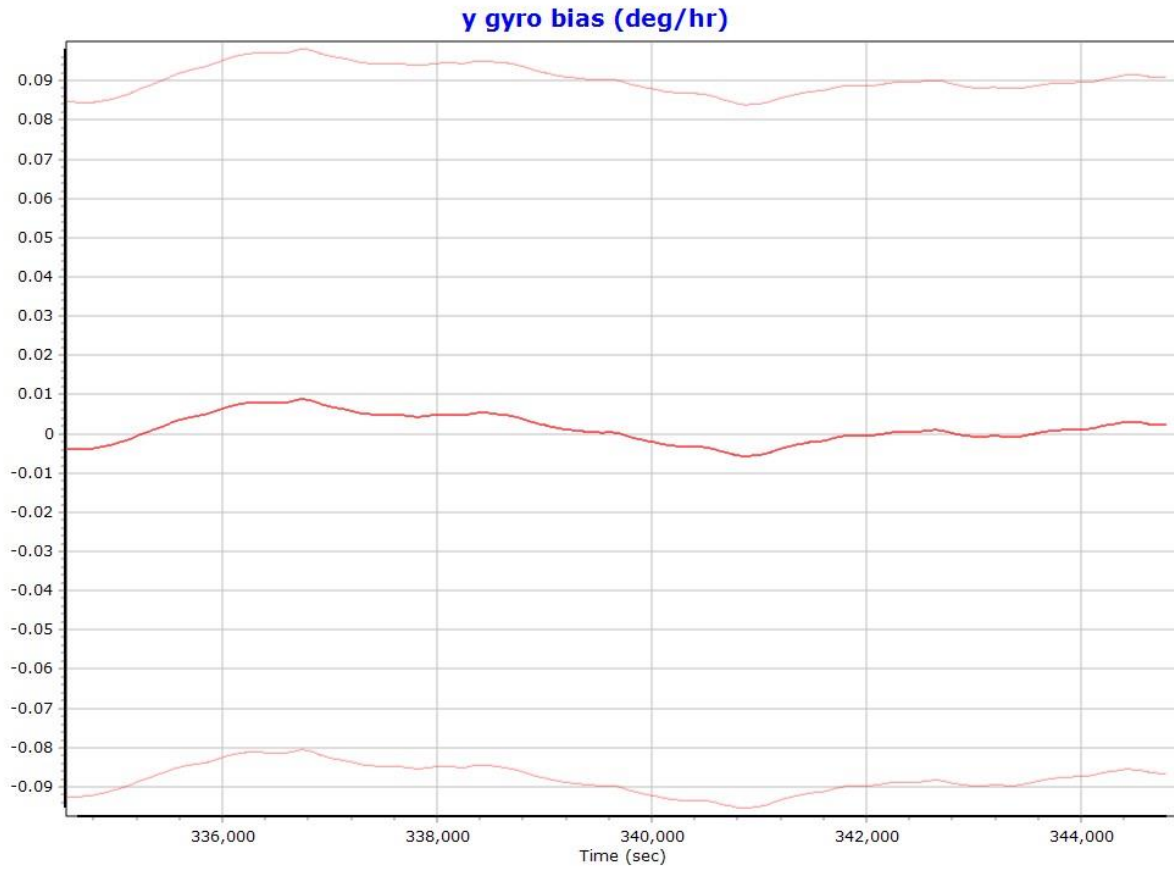
Z Accelerometer Scale Error (ppm)



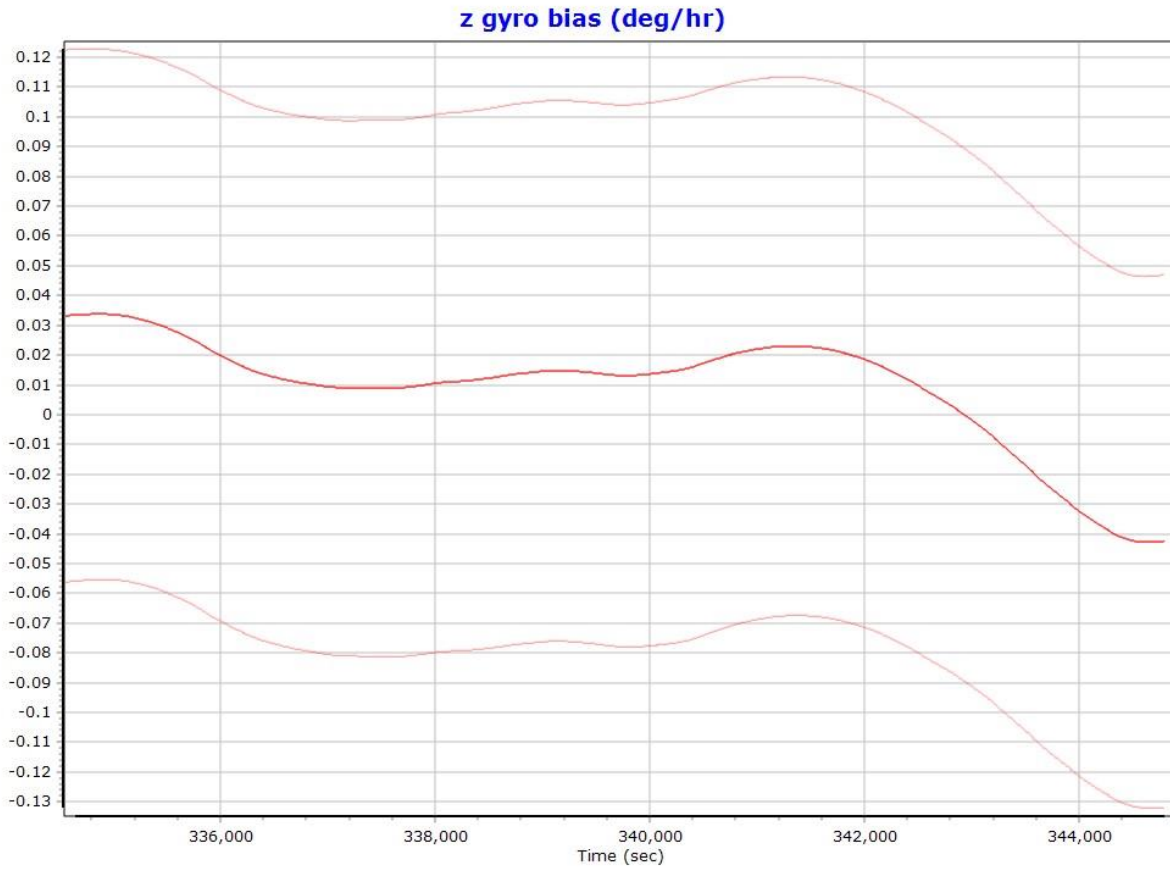
X Gyro Bias (deg/h)



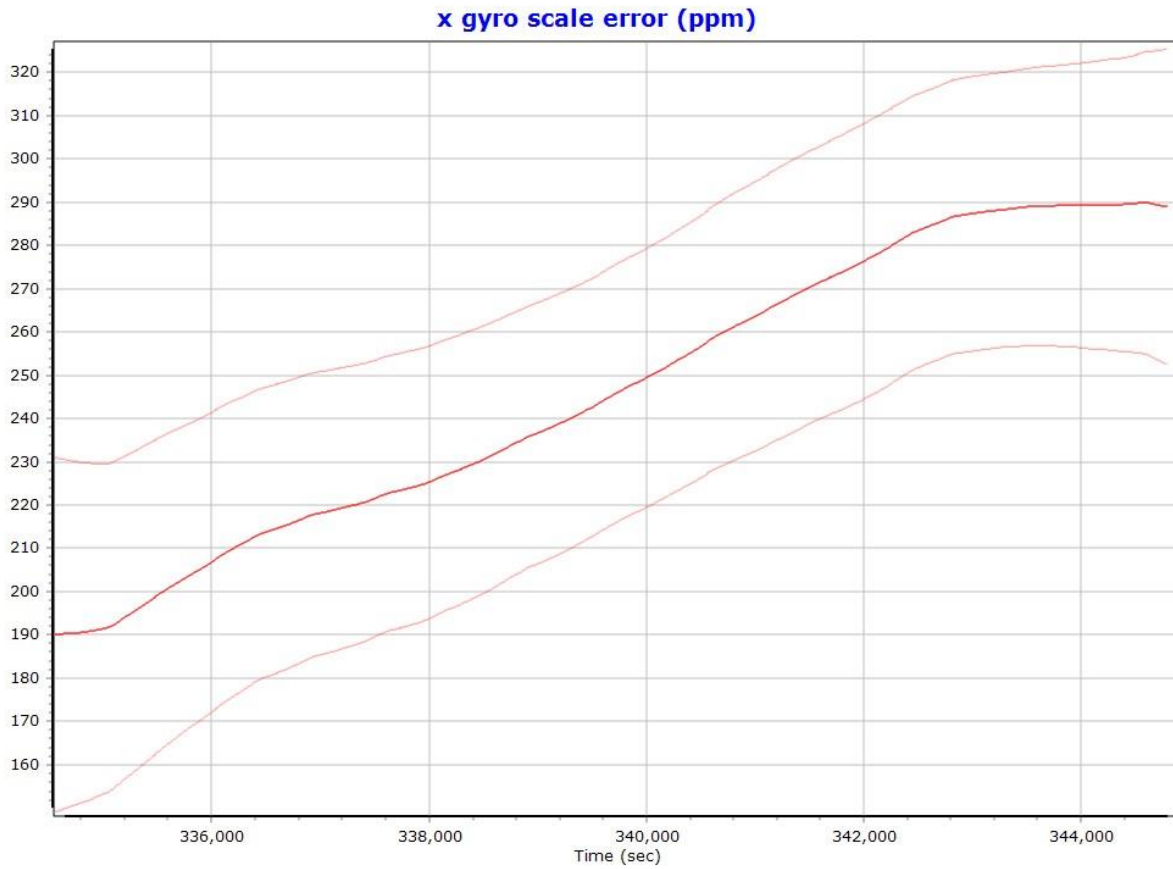
Y Gyro Bias (deg/h)



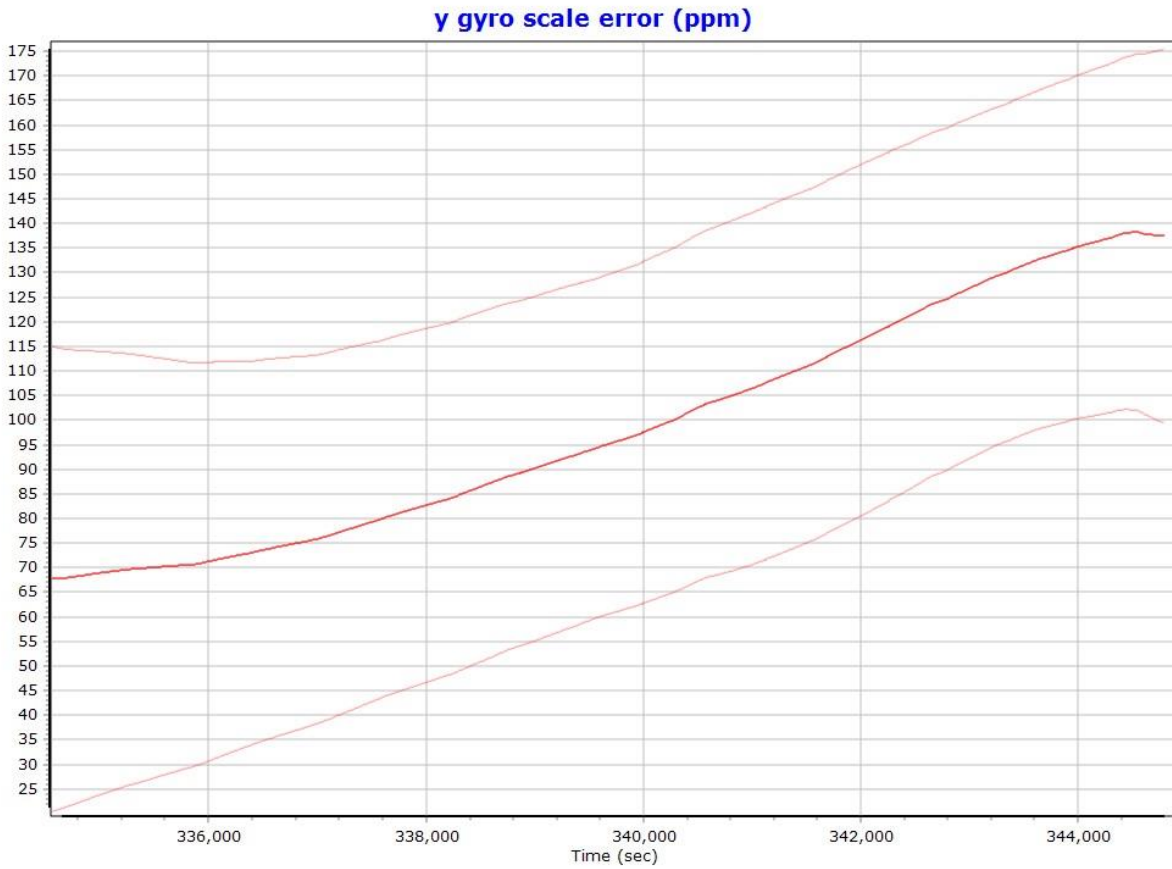
Z Gyro Bias (deg/h)



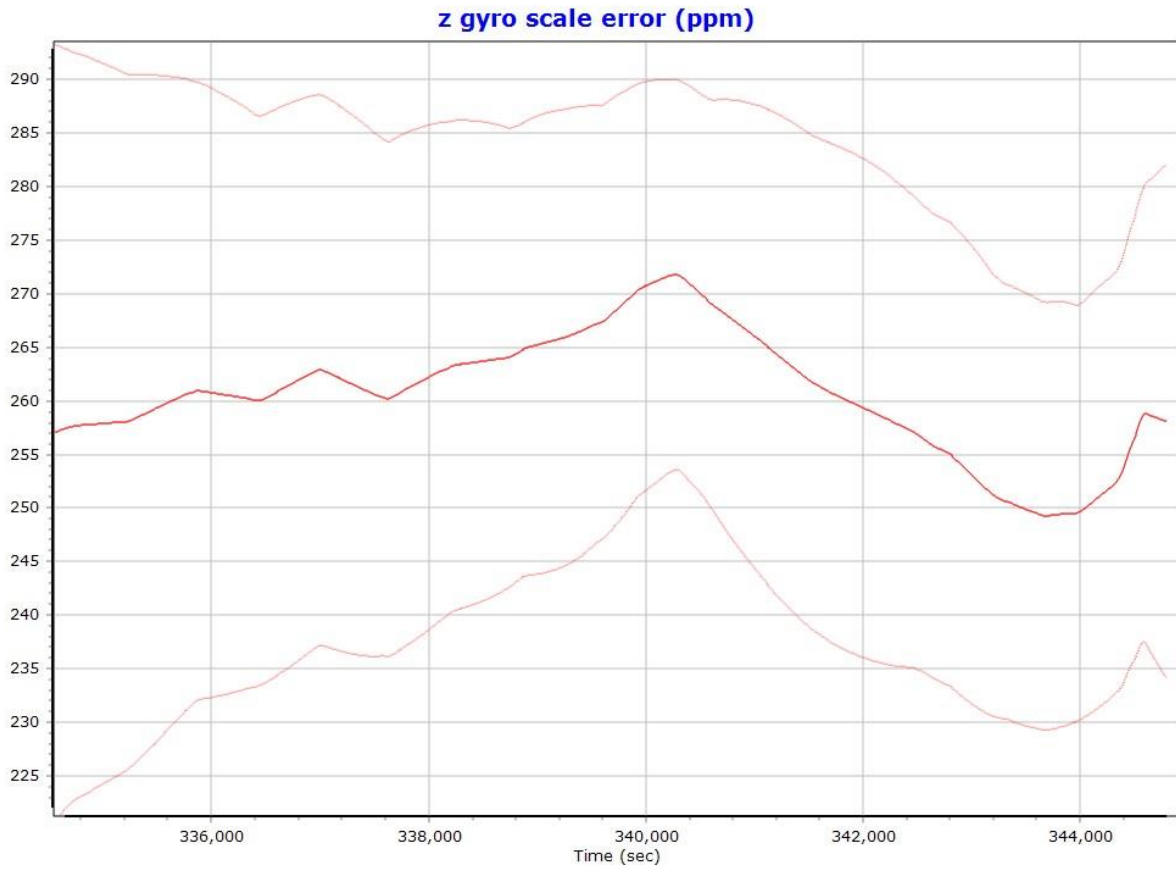
X Gyro Scale Error (ppm)



Y Gyro Scale Error (ppm)



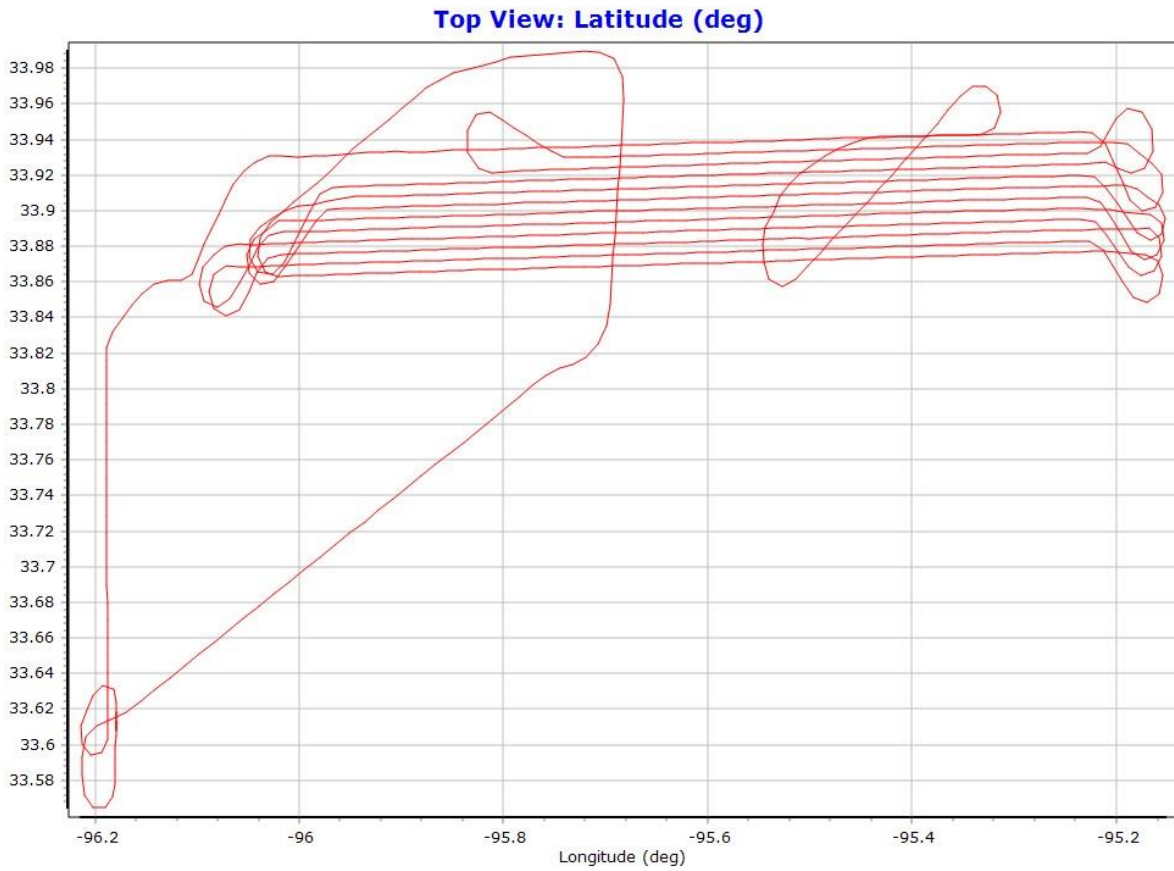
Z Gyro Scale Error (ppm)



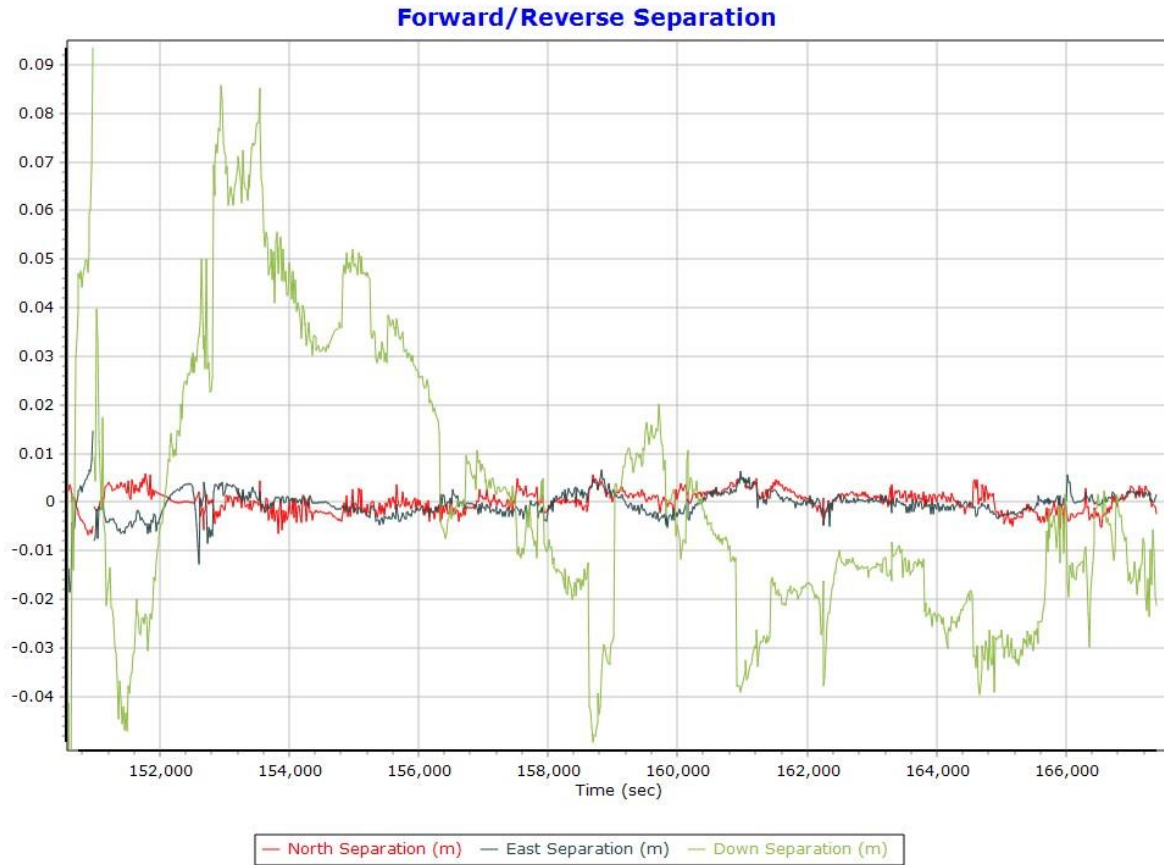
Flight 8

Trajectory Information

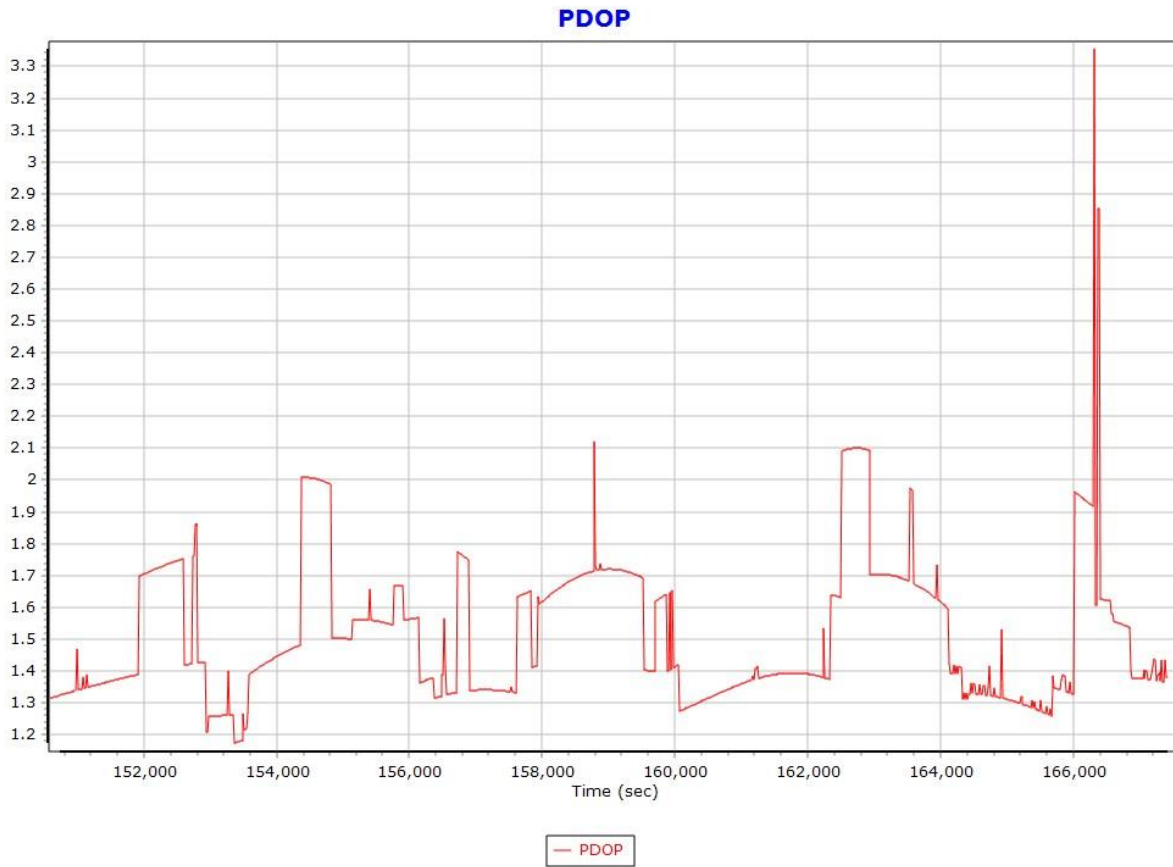
Top View



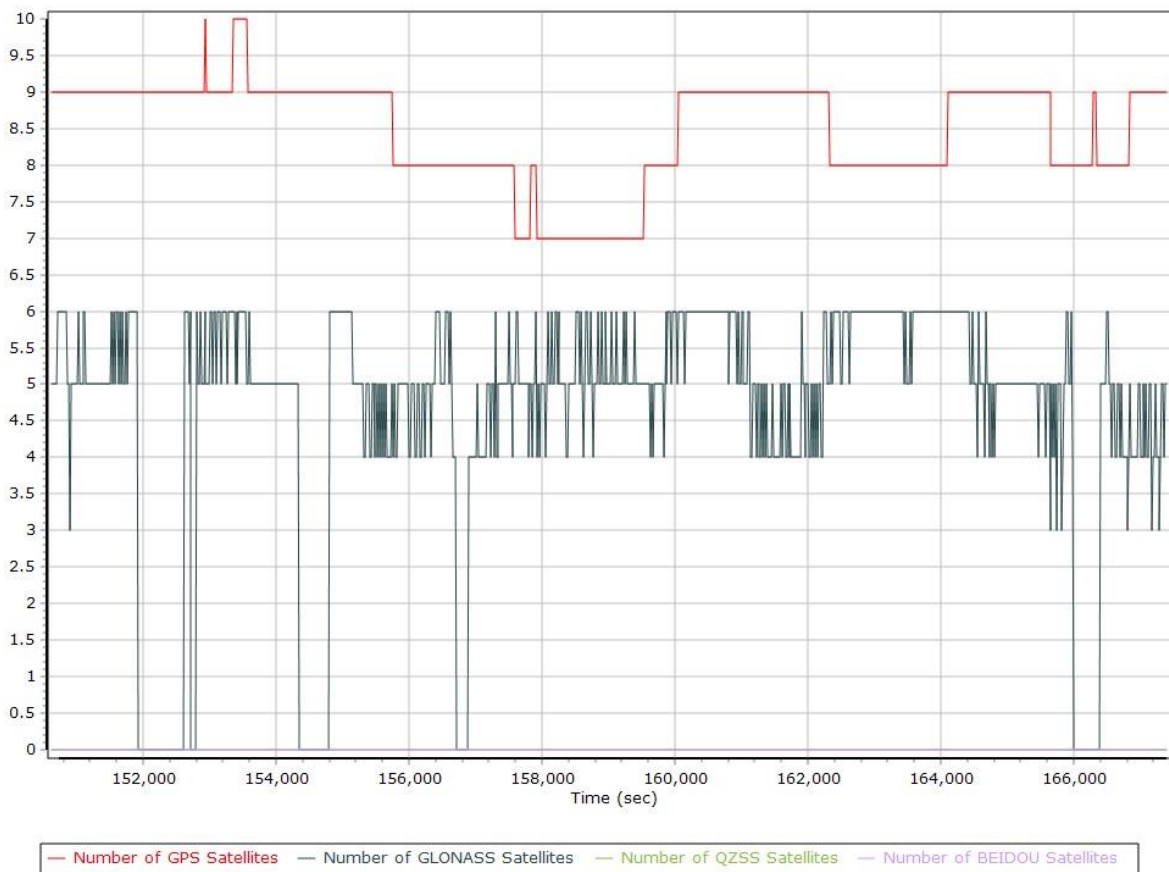
Forward/ Reverse Separation



PDOP



Number of Satellites



Processing Summary Information

Version: 4.30.3108 POSpac MMS 8.2 Project:
flight8
Solution Type: Combined Fwd/Rev

Number of Epochs:

Total in GPB file: 3386100
No processed position: N/A
Missing Fwd or Rev: N/A With
bad C/A code: N/A
With bad L1 Phase: N/A

Project: Task Order # 7 TX West Central

Date: 07.11.2019

Appendix A: GPS and IMU Processing Reports for Flight 8 Page
5 of 18

Measurement RMS Values:

L1 Phase: N/A

C/A Code: N/A

L1 Doppler: N/A

Fwd/Rev Separation RMS Values:

East: Averages from the forward/reverse plot

North: Averages from the forward/reverse plot

Height: Averages from the forward/reverse plot

Fwd/Rev Sep

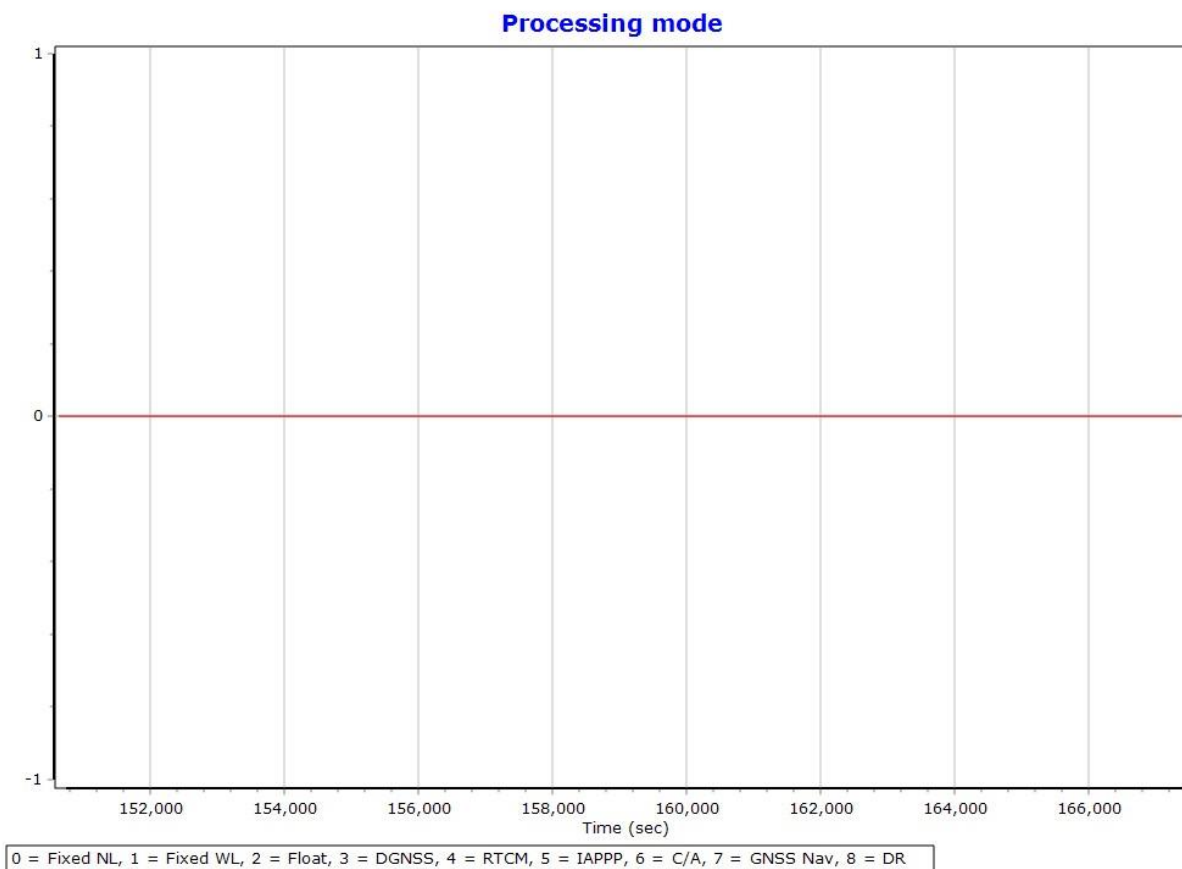
East: N/A

North: N/A

Height: N/A

Smoothed Solution Status

Processing Mode



- Q 1 "Fixed NL": 100% Q
- Q 2 "Fixed WL": 0%
- Q 3 "Float": 0% Q
- Q 4 "DGNSS": 0% Q
- Q 5 "RTCM": 0%
- Q 6 "IAPPP": 0%
- Q 7 "C/A": 0%
- Q 8 "GNSS Nav": 0%
- Q 9 "DR": 0%

Position Standard Deviation Percentages:

- 0.00 - 0.10 m: 100.0 %
- 0.10 - 0.30 m: 0.0 % 0.30
- 1.00 m: 0.0 %
- 1.00 - 5.00 m: 0.0 %
- 5.00 m + over: 0.0 %

Project: Task Order # 7 TX West Central

Date: 07.11.2019

Appendix A: GPS and IMU Processing Reports for Flight 8 Page
7 of 18

Percentages of epochs with DD_DOP over 10.00: 0.0%.

DOP over Tol: 0.0 %

Baseline Distances:

Maximum: 43.266 (km)

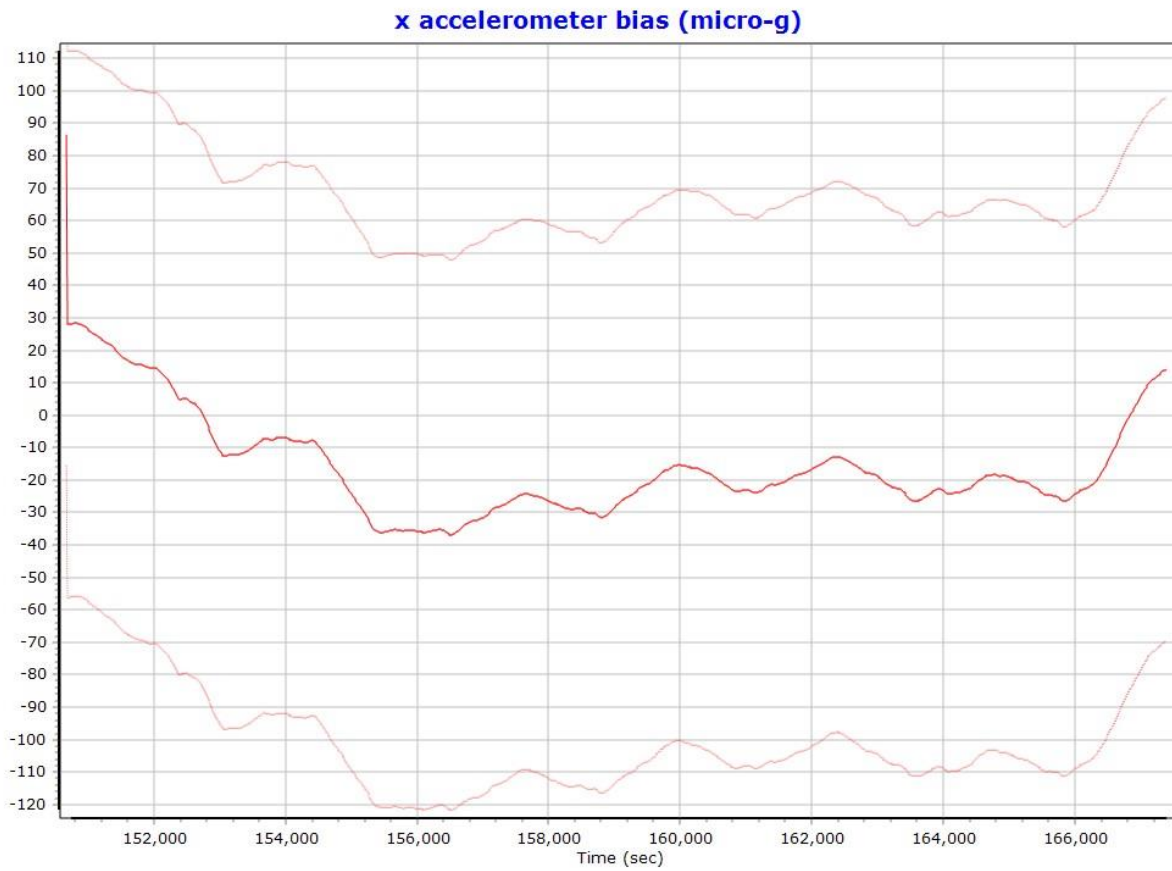
Minimum: 0.391 (km) Average:

~34 (km)

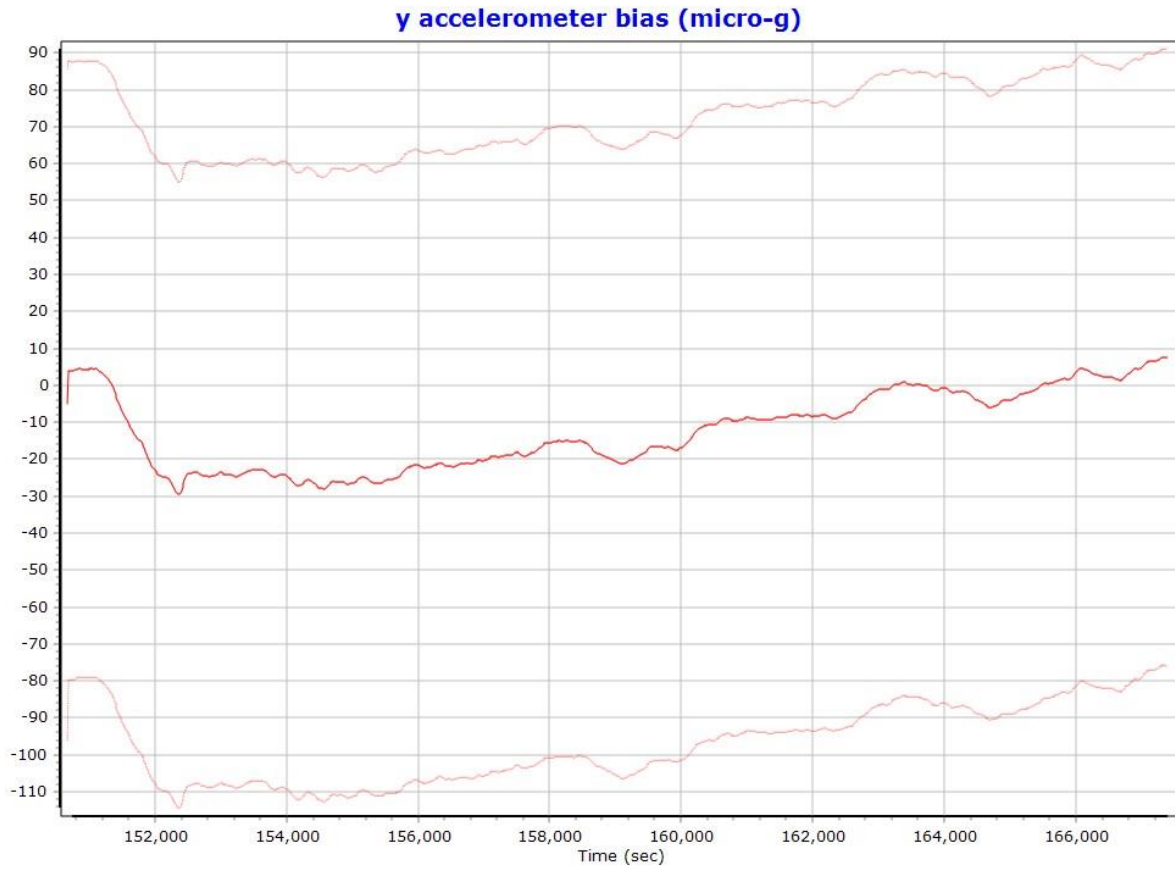
First Epoch: 0.714 (km) Last

Epoch: 1.083 (km)

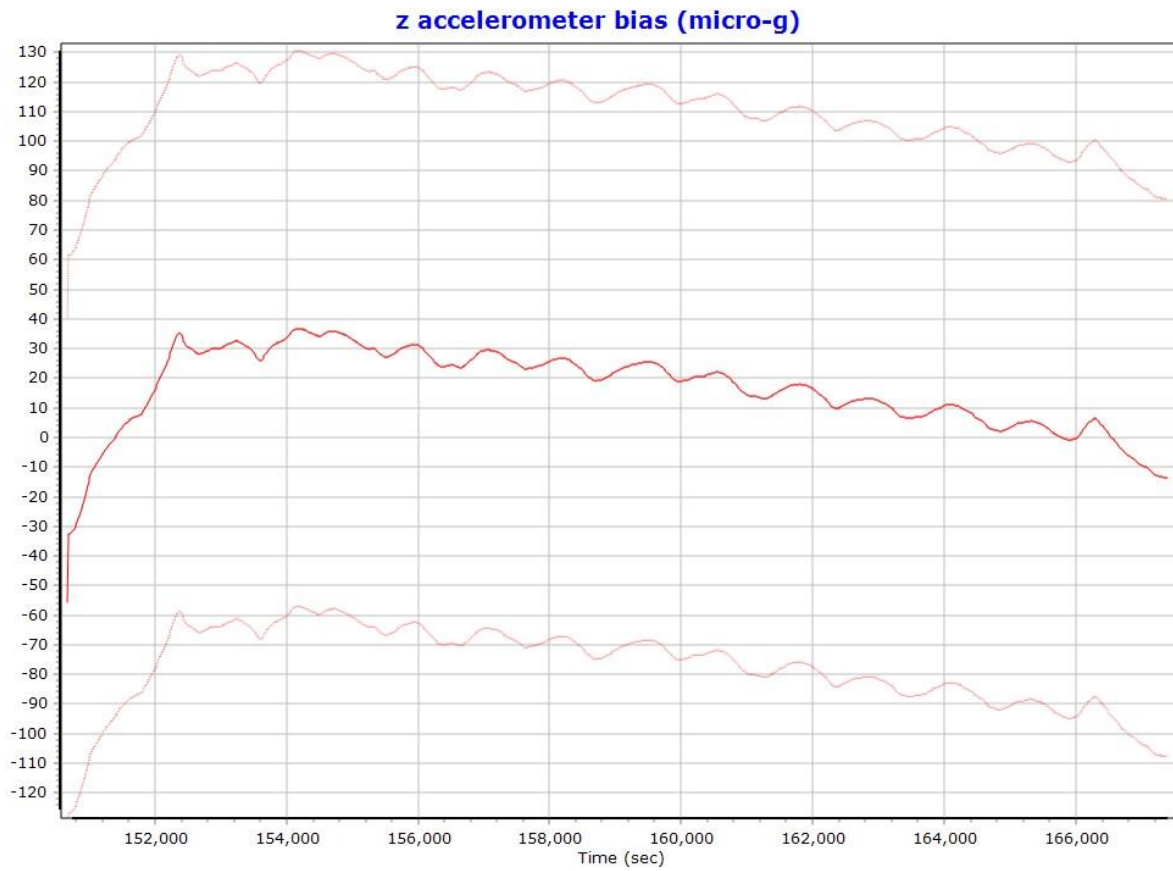
Sensor Errors X Accelerometer Bias (micro-g)



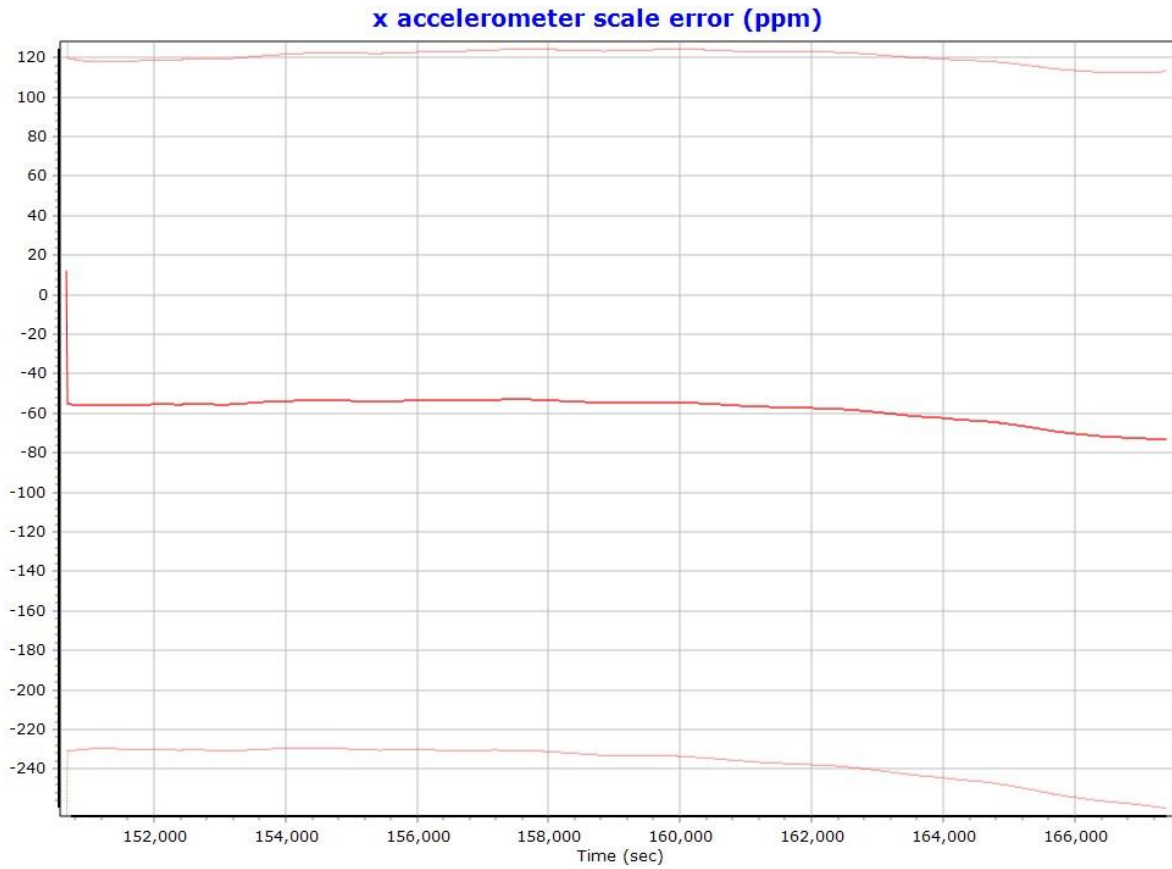
Y Accelerometer Bias (micro-g)



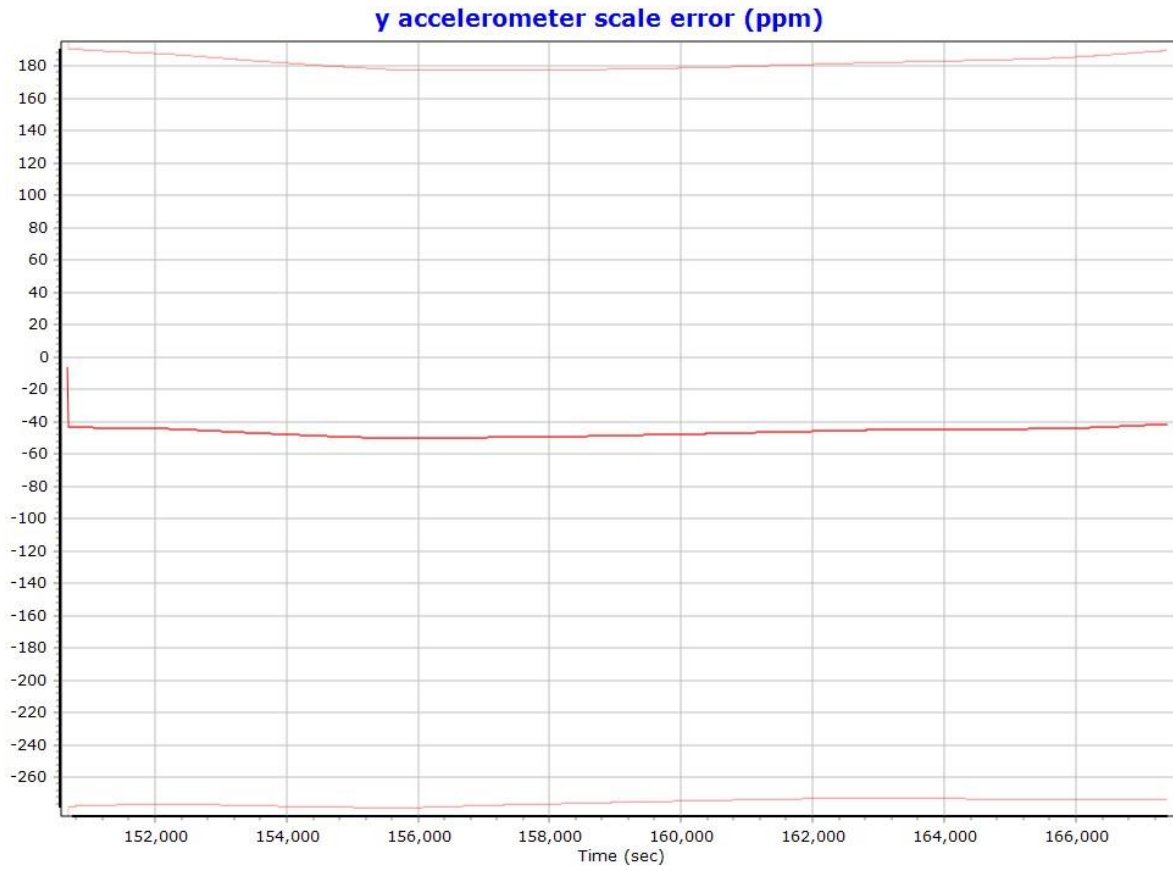
Z Accelerometer Bias (micro-g)



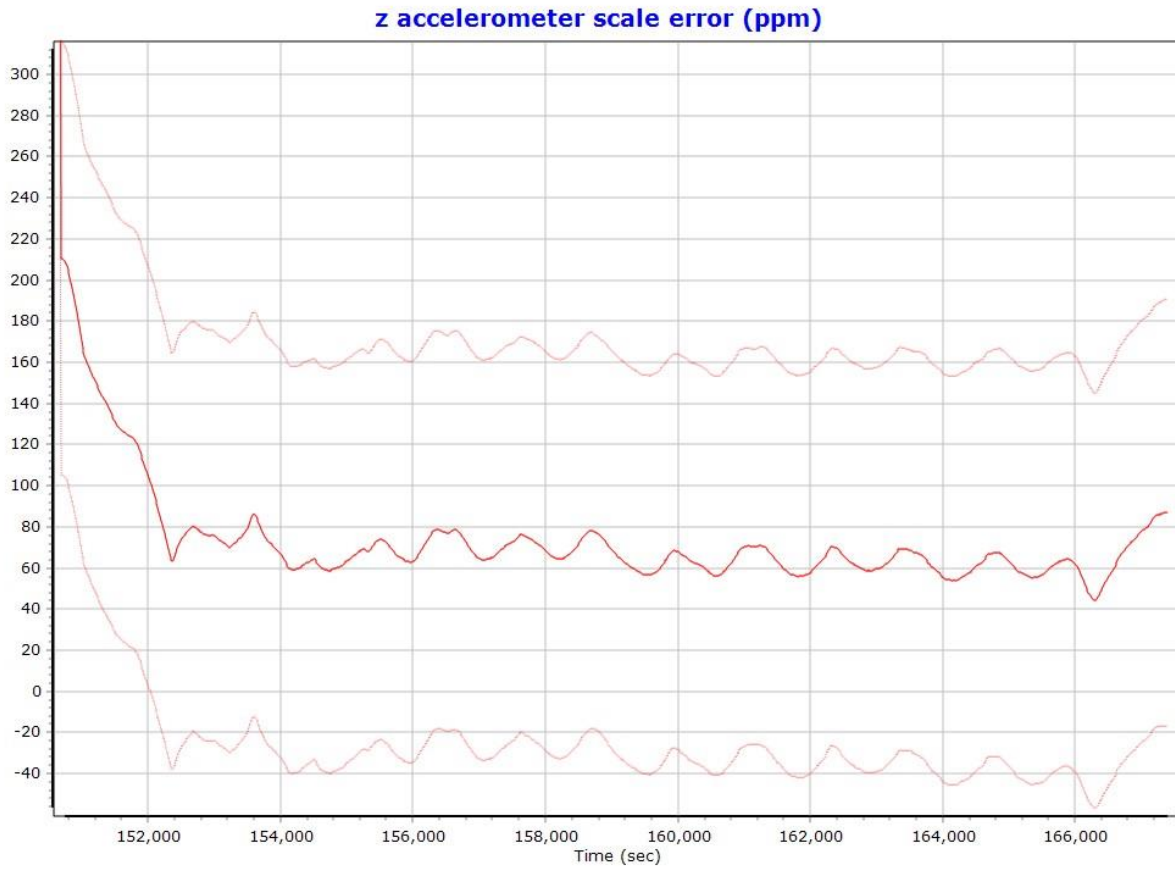
X Accelerometer Scale Error (ppm)



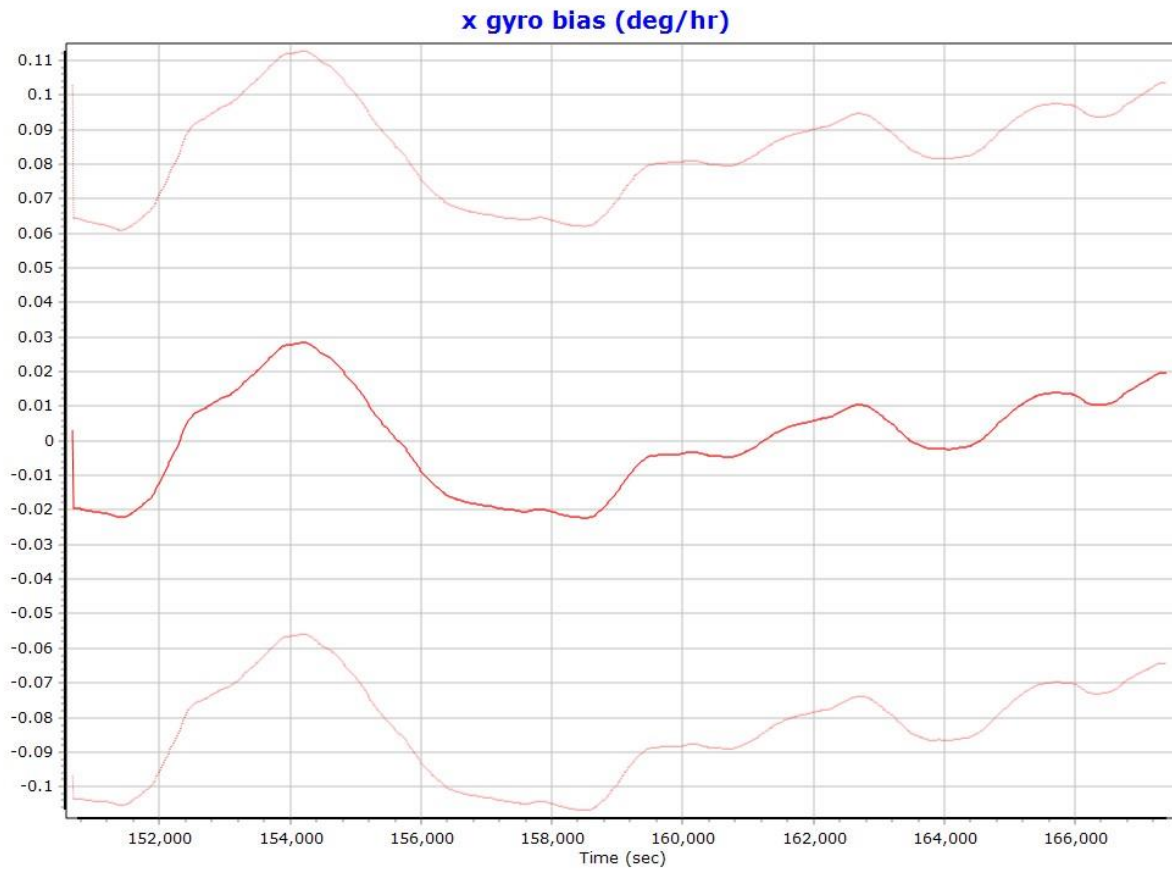
Y Accelerometer Scale Error (ppm)



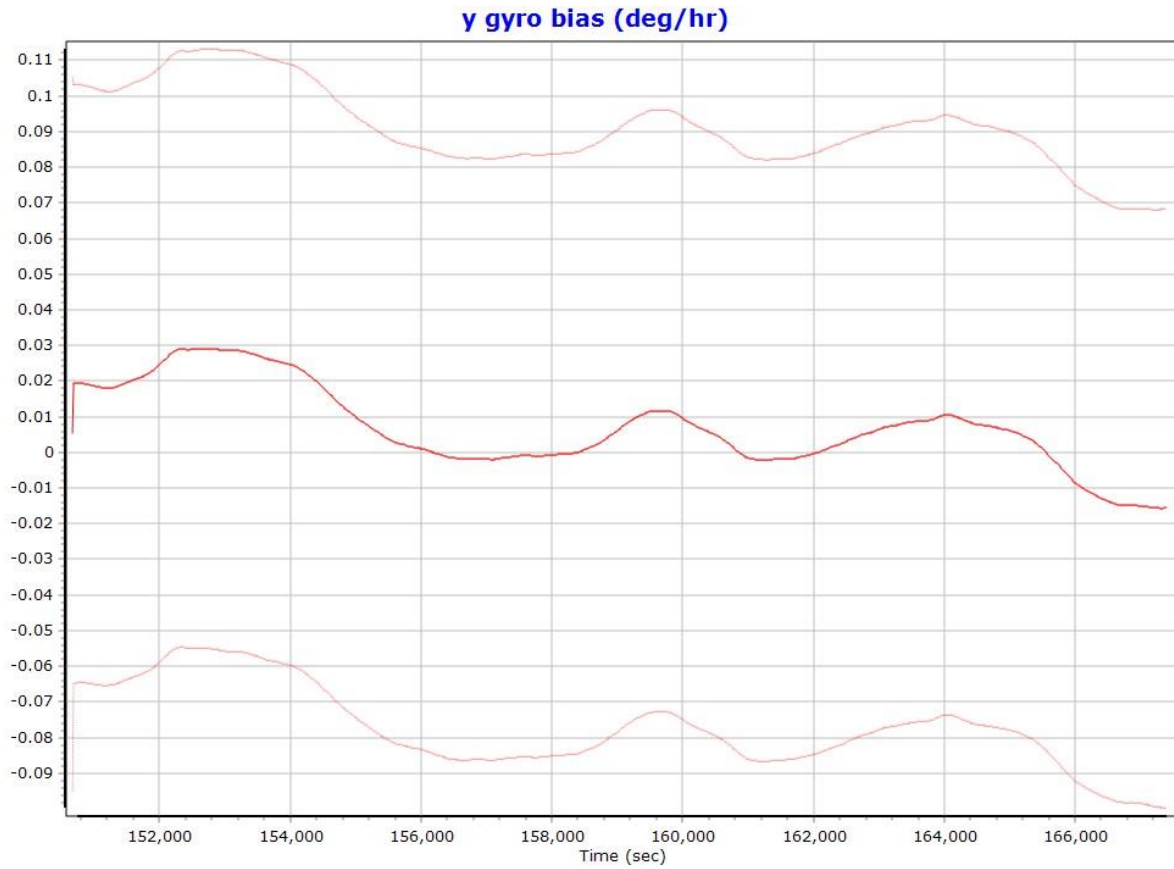
Z Accelerometer Scale Error (ppm)



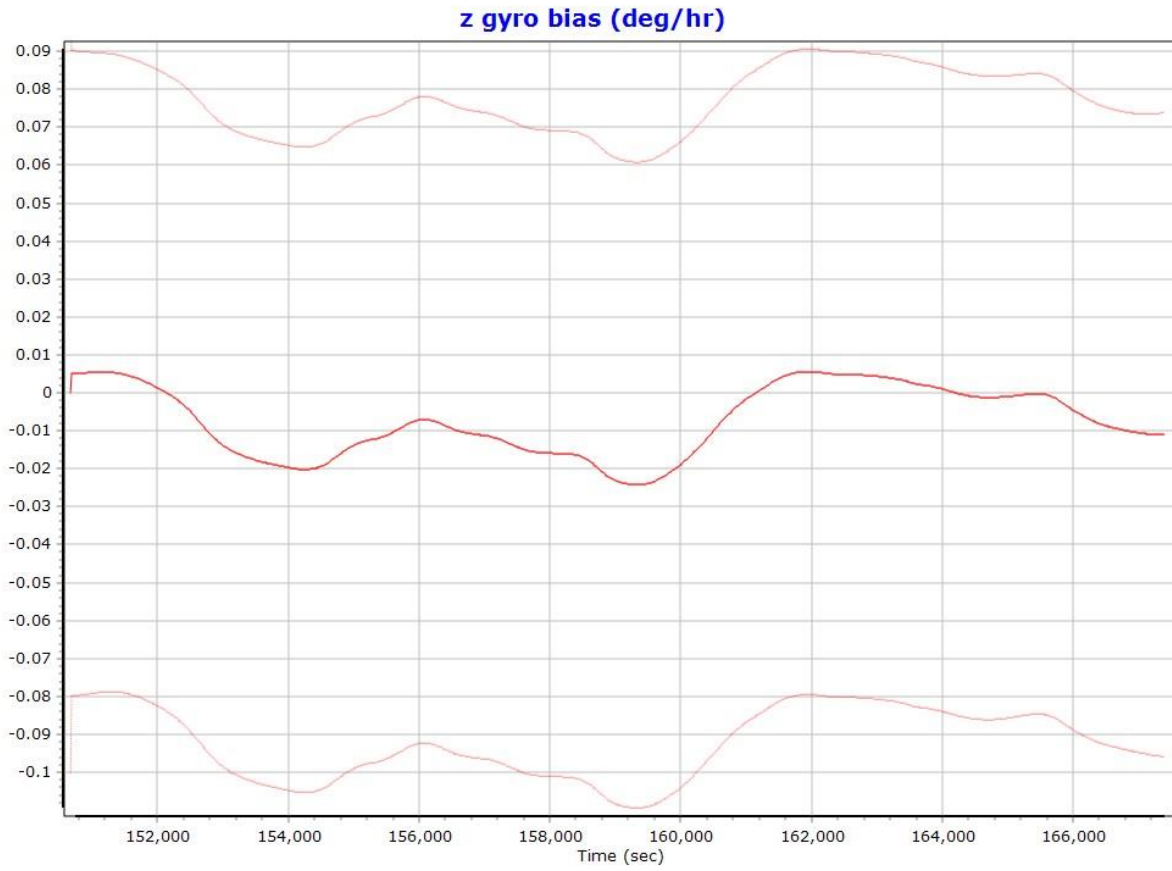
X Gyro Bias (deg/h)



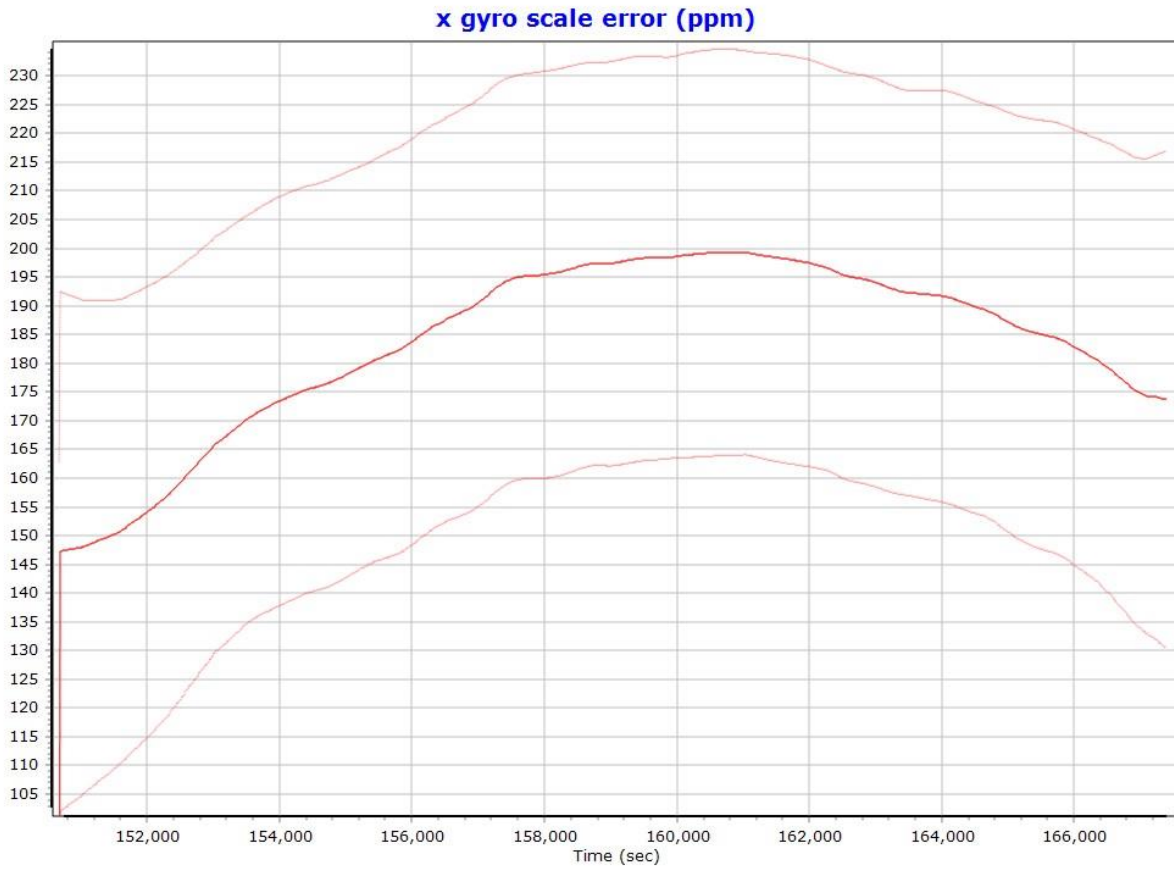
Y Gyro Bias (deg/h)



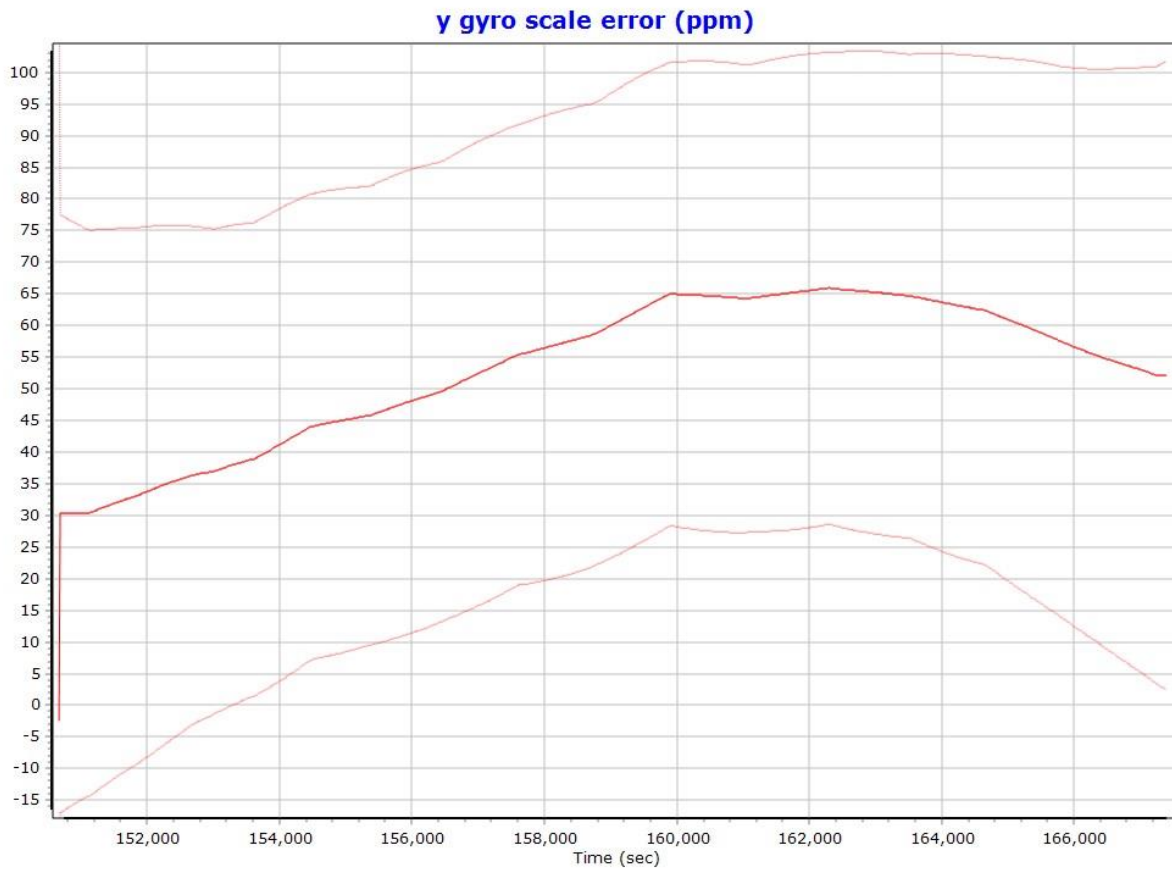
Z Gyro Bias (deg/h)



X Gyro Scale Error (ppm)



Y Gyro Scale Error (ppm)



Z Gyro Scale Error (ppm)

