

Ground Control Report

WISCONSIN WROC - 3DEP | CALUMET COUNTY LIDAR 2018

1.1 GROUND CONTROL DESIGN AND METHODOLOGY

The ground control network and design used for the Calumet County lidar acquisition was made up of calibration points, GPS base stations, NGS base stations, and independent check points from the vertical accuracy ground control survey. This report will focus on the lidar calibration points that were collected at 12 locations in and around the Calumet County project area. The control points are used for QC checks and calibration of the raw point cloud and for additional vertical checks against the processed bare earth surface.

The ground control calibration survey was done in Wisconsin County Coordinate System-Calumet County, NAD83 (2011), US survey feet; NAVD88 (Geoid 12B), US survey feet. The field work was conducted by Ayres Associates surveyors. All field work was completed between May 31, 2018, and October 29, 2018.

CONTROL SUMMARY AND METHODOLOGY

Control Summary							
Horizontal Datum:	NAD83 (2011)						
Vertical Datum:	NAVD88 (2012), Wisconsin GEOID12B						
Rectangular Coordinate System:	WCCS-Calumet County						
Used NGS Control?	Yes No						
List any NGS control points used:	See field notes.						
Summary of control checks and calibration (if applicable):	(See Field Notes for control checks on NGS monuments – No calibration was needed)						
Survey Methods Used:	RTK-GPS using WISCORS Network through VRS connection were used for direct observations and to set control pairs for Robotic Total Station shots under canopy, etc						
Equipment Used:	GPS Trimble R8-3 GNSS S/N 5004413097 – (Ayres #74.58) Total station Trimble S 6 S/N 93410182 – (Ayres #75.38) Data Collector Trimble TSC 3 S/N RSONC10841 (Ayres #75.20)						

Crew Chief Notes

Set PK nails or spikes at control points used for total station measurements and for calibration points.

Recorded appropriate: NVA (Bare Earth & Urban) and VVA (Forested, Swamp/Wetland, Tall Weed/Crop). Took (4) pictures of each point – one from each cardinal direction.



Survey Methods (continued)

All work was performed in and referenced to NAD83 (2011), NAVD 88(2012), Geoid 12B, Wisconsin County Coordinate System-Calumet County in US Survey Feet.

Established horizontal and vertical coordinate values on the points by a minimum of two – 90 epoch observations with separate initializations using RTK GPS and the WISCORS network. The resultant coordinates and elevations provided in the deliverables are an average of the two observations.

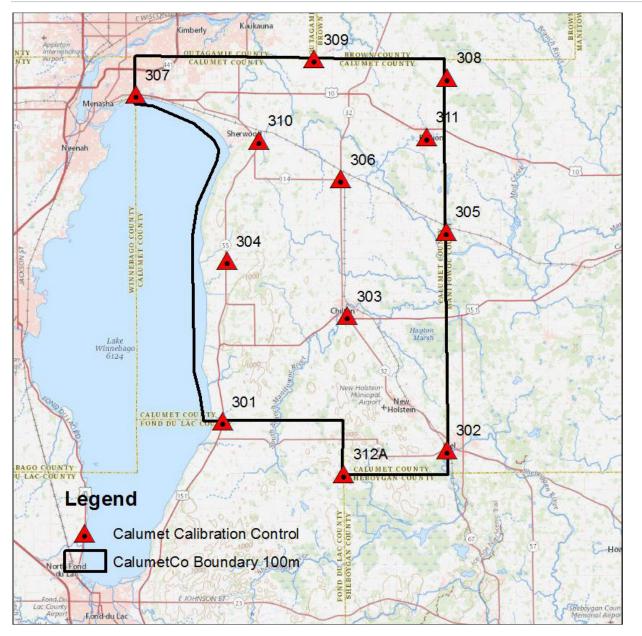
Check shots were taken on numerous NGS control points (see field notes) to verify that the values obtained are consistent with the datum/adjustment as described herein and meet the ±3 centimeter vertical accuracy requirement at the 95% confidence level.

Points not able to be directly occupied by GPS means were measured using Total Station methods from control point pairs set utilizing GPS methods outlined above.



1.1.2 CONTROL LAYOUT

The locations were selected around the outer geometry of the project boundary and on major roads within the project area. This layout design is preferred when the calibration points will be used to check different areas across a large flight block. The control survey was conducted with a Trimble R-8 GPS receiver and a VRS connection with a TSC3 data collector.



1.1.2.1 MAP OF CALUMET COUNTY CALIBRATION POINTS

1.1.3 CALUMET COUNTY LIDAR, CALIBRATION POINT STATISTICS

The final step in using the calibration points is to run a statistical comparison against the bare earth ground surface to confirm that the vertical accuracy is within specification. The follow results indicate that the overall RMSEz of the calibration points is 0.096'. This is a separate check as compared to the Vertical Accuracy Survey QA/QC report. These points are used in the calibration of the raw point cloud, and therefore are not an independent set of checkpoints like those used in the vertical accuracy testing.



1.1.3.1 STATISTICAL REPORT FOR CALIBRATION POINTS

Root Mean Square

Std Deviation

NUMBER	EASTING	Northing	Known Z	LASER Z	Dz	
301	854882.536	443569.536	801.043	801.170	+0.127	
302	923851.618	434856.625	910.175	910.170	-0.005	
303	893254.144	476102.967	909.209	909.000	-0.209	
304	856167.984	493019.396	829.127	829.080	-0.047	
305	923667.010	502007.741	832.992	832.910	-0.082	
306	891257.432	518230.125	837.224	837.270	+0.046	
307	828153.385	544284.323	751.255	751.350	+0.095	
308	923990.790	549465.507	944.088	944.200	+0.112	
309	883027.792	555194.580	799.551	799.480	-0.071	
310	866001.758	530057.903	889.702	889.710	+0.008	
311	917642.088	531233.675	827.073	827.160	+0.087	
312A	312A 892108.463		950.643	950.570	-0.073	
Average Dz		-0.001 ft				
	Minimum Dz	-0.209 ft				
	Maximum Dz	0.127 ft				

0.096 ft

0.100 ft



1.1.4 FIELD NOTES

CURVE FORMULAS														
$ \begin{array}{cccc} \Gamma &= R \ tan \ \frac{1}{2} \ I \\ \Gamma &= \frac{50 \ tan \ \frac{1}{2} \ I}{\text{Sin.} \ \frac{1}{2} \ D} \end{array} & \begin{array}{c} R =T \ cot. \ \frac{1}{2} I \\ R = \frac{50}{2} \ cot. \ \frac{1}{2} I \\ R = \frac{50}{2} \ cot. \ \frac{1}{2} I \end{array} $	$def. = \frac{chord^2}{R}$	ALUM	ET	co	G	ROL	NK	T	RU	t H	IN	G		
$\frac{1}{12} \frac{1}{12} \frac{1}{12} D = \frac{50}{12} \frac{1}{12} \frac{1}{$		12-02												
R EnRey sec 1/1		vecs.			ET	C								
$\frac{1}{T} = \frac{1}{T} = \frac{1}{T} = \frac{1}{T} \tan \frac{1}{4} I$			CIL			-	1							1
The square of any distance, divided by twice the he distance from tangent to curve, very nearly.		- au pres		T-										1
To find angle for a given distance and deflection Rule 1. Multiply the given distance by .01745 (d	n. f. for 1º for 1 ft.)	PS:TR		-	DO	~		00	114	1 7	29	71	74 4	
nd divide given deflection by the product. Rule 2. Multiply given deflection by 57.3, and d	ride the product		IMBO	10	KO	3/	N, 3	500	97	1 5	0 1	10	1	1
y the given distance. To find deflection for a given angle and distance. M	-	S					01				٢,	4 -		1
by .01745, and the product by the distance.	, ,	C: TRI	MBL	E	TS	CS	3/1	VIES	77	D2	5/	7 8		
GENERAL DATA	i da harani a dha									-		++		4
RIGHT ANGLE TRIANGLES. Square the altitude, di base. Add quotient to base for hypotenuse.						++				+	-	++-	-	+
Given Base 100, Alt. 10.10 ² +200-5, 100+5=100.5 Given Hyp. 100, Alt. 25.25 ² +200=3.125. 100-3. Error in first example, .002; in last, .0	nyp. 5=96.875=Base.											++		+
to find tons of Kall in one mile of track: multiply	5. weight per yard			\square								++-		+
by II, and divide by 7.											-		-	+
LEVELING. The correction for curvature and refra decimals of feet is equal to 0.574 d ² , where d is the c	stance in miles.													4
The correction for curvature alone is closely, ¾d². The rection is negative.	e combined cor-													4
PROBABLE ERROR. If d_1 , d_2 , d_3 , etc. are the discrep	ancies of various					_	++-							-
results from the mean, and if Σd^2 =the sum of the squa ences and n=the number of observations, then the p	es of these differ- robable error of												-	4
the mean= $\pm 0.6745 \sqrt{\frac{\Sigma d^2}{n(n-1)}}$												4		4
MINUTES IN DECIMALS OF A DEGREE												4	4	-
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	5833 51' .8500 7000 52 .8667 7167 53 .8833										4		4	4
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	883 5.1' .8500 9000 52 .8667 7167 53 .8833 333 54 .9000 500 55 .9167 6667 56 .9333 833 57 .9500 9000 59 .9667 3167 .9667										1			
$\begin{array}{cccccccccccccccccccccccccccccccccccc$	167 53 .8833 333 54 .9000 5500 55 .9167 7667 56 .9333 833 57 .9500 9000 58 .9667 1167 59 .9833 3333 60 1.0000											4		
	3107 39 .9833 3333 60 1.0000										Ш	4		
INCHES IN DECIMALS OF A FOOT 1/16 3/32 1/4 3/16 1/4 3/16 1/4 1/16	³ / ₄ ³ / ₄ ⁷ / ₈ 521 .0625 .0729											4		
	9 10 11 500 .8333 .9167													
Elan Publishing Co., Inc. Meredith, N.H. 03253														
4														
T# NGS MONUMENT AN A		1111	1 1 1	1 1	1 1		1	-	11			1-1-1		-
0 KAUKAUNA GPS -0.007 -0.														
BROTHERTOWNGPS 0.008 0.2	19 -0.013							1-						
2 CHARLESTOWN WGB0.022 - 0.	0.028							1						
3 BRILLION 5 GPS -0,003 -0,	DIZ													

PT#	NGS MONUMENT	ΔN	ΔE	82
510	KAUKAUNA GPS	-0.007	- 0,029	-0.067
511	BROTHERTOWNGPS	0.008	0.019	-0.013
512	CHARLES TOWN WGB	0.022	-0.00	+0.028
513	BRILLION 5 GPS	-0,003	-0,012	~
514	4K16	-	-	-0,064
515	MAPLE GROVE WGE	0, 020	-0.025	-

307	PID	2M	TIPNS	· CENTER OF 19 MANHOLE EAST OF 19 ORANGE
				MANHOLE ON EASTERN SIDE OF KWK TRIP PARKINGLOT.
309	PID	24	THEN.N	SW CORNER OF COMERCIE OF DR VEWAY FOR
201	FID	211	1.6719.14	BRUSE WHZ CITAKK



1.1.4 FIELD NOTES (CONTINUED)

: AM-	2700			
	114,1	PARTLY CLOUD'S		
		RTLY CLOUDY, BREEZEY		
CODE	DEIGHT	Ρματος	DEELBURTING	
				IL MARY RD
			TO THE.SE OF POST OFFICE.	
P/D	2 M	тів, м. Е	· EAST CORNER OF 55 INLET ON 5	
		•	OF LAKE ST NEAR INTERSECTION OF AND CHURCH ST.	E LAKE ST
PID	2 M	TIP, N, W	• NE CORNER OF SS INLET ON S OF CTH WHH EAST OF STH ISI	COUTH SIDE
PID	2 M	TIP,N,W		INE ON
PID	ZM	TIP,NE	·CENTER OF MANHALE ON WASHIN	VISTON ST.
PID	2 M	TIP, N, W	·CENTER OF MANHOLE ON CAK	L ST, 15t
	 PID P/D PID PID 	 PID 2 М 	$P/D = 2M = \pi P_{N,N}E$ $P/D = 2M = \pi P_{N,N}$ $P/D = 2M = \pi P_{N,N}$ $P/D = 2M = \pi P_{N,N}E$	PID 2M TIPN,S .SE CORNER OF SS INIET NM TO THE.SE OF POST OF FICE PID 2M TIPN,E .EAST CORNER OF SS INLET ON SS PID 2M TIPN,E .EAST CORNER OF SS INLET ON SS PID 2M TIPN,W .EAST CORNER OF SS INLET ON SS PID 2M TIPN,W .NE CORNER OF SS INLET ON SS PID 2M TIPN,W .NE CORNER OF SS INLET ON SS PID 2M TIPN,W .SW CORNER OF NORTHERM FOC L PID 2M TIPNE .CENTER OF NORM RD WEST OF 8 TH ST

PTH	CODE	HEIGHT	PHOTOS	DESCRIPTION
305	PID	2M	TIPNE	SE CORNER OF SOUTHERN FOG LINE ON CTH
CREW:		HROEPE	n •	
DATE:	06-01-	2018		
WEATHER	: AM- 57	PF, OVER	CAST	
PT#	CODE	HEIGHT	PHOTOS	DESCRIPTION
306			TIPN W	EAST OF 8TH ST.
7.11	RID	2 M	- IRNIS	· SE CORNER OF SS INLET ON WEST SIDE
311	FID	211	TIPNS	OF CLEVELAND ST NORTH OF E WATER ST.
308	PID	7 M	TIPNE	NE CORNER OF DASHED CENTERLINE ON
000	110	2.		CTH K, NORTH OF FIELD ENTERANCE AND
				WEST OF HOUSE 24204

1



1.15 FIELD PHOTOS



Point 301



Point 302



Point 303



Point 304



Point 305

Point 306



FIELD PHOTOS (CONTINUED)







Point 308



Point 309



Point 310



Point 311



Point 312A