

General Information

Mission Information

Project name	13284-1805_20181111b
Processing date	2018-11-12 23:00:32
Mission date	2018-11-11 19:01:11
Mission duration	03:22:21.000
Processing mode	IN-Fusion SmartBase
GPS Station	ASB

Rover Hardware Information

Product	POS AV 610 VER6 HW2.5-12
Serial number	S/N9865
IMU type	57
Receiver type	BD982
Antenna type	AV37

Project File List

Rover Data Files

File name	File type
181111_190052_INS-GPS_1.raw	POS Data

Input Files

File Name	File type
Ephm3150.18g	GLONASS Broadcast Ephemeris
Ephm3150.18n	GPS Broadcast Ephemeris
igu20266_00.sp3	GPS Precise Ephemeris
igu20266_06.sp3	GPS Precise Ephemeris
igu20266_12.sp3	GPS Precise Ephemeris
igu20266_18.sp3	GPS Precise Ephemeris
igu20270_00.sp3	GPS Precise Ephemeris
igu20270_06.sp3	GPS Precise Ephemeris
igu20270_12.sp3	GPS Precise Ephemeris
igu20270_18.sp3	GPS Precise Ephemeris
igu20271_00.sp3	GPS Precise Ephemeris
igu20271_06.sp3	GPS Precise Ephemeris
igu20271_12.sp3	GPS Precise Ephemeris
WVBR315A.18o	GNSS SingleBase
WVBU315A.18o	GNSS SingleBase
WVCL315A.18o	GNSS SingleBase
WVCV315A.18o	GNSS SingleBase
WVFL315A.18o	GNSS SingleBase
WVFR315A.18o	GNSS SingleBase
WVGB315A.18o	GNSS SingleBase
WVHA315A.18o	GNSS SingleBase
WVLE315A.18o	GNSS SingleBase
WVMF315A.18o	GNSS SingleBase
WVMZ315A.18o	GNSS SingleBase
WVNR315A.18o	GNSS SingleBase
WVOH315A.18o	GNSS SingleBase
WVTA315A.18o	GNSS SingleBase
WVBR315A.18g	GLONASS Broadcast Ephemeris
WVBR315A.18n	GPS Broadcast Ephemeris
WVBU315A.18g	GLONASS Broadcast Ephemeris
WVBU315A.18n	GPS Broadcast Ephemeris
WVCL315A.18g	GLONASS Broadcast Ephemeris
WVCL315A.18n	GPS Broadcast Ephemeris
WVCV315A.18g	GLONASS Broadcast Ephemeris
WVCV315A.18n	GPS Broadcast Ephemeris
WVFL315A.18g	GLONASS Broadcast Ephemeris
WVFL315A.18n	GPS Broadcast Ephemeris
WVFR315A.18g	GLONASS Broadcast Ephemeris
WVFR315A.18n	GPS Broadcast Ephemeris
WVGB315A.18g	GLONASS Broadcast Ephemeris
WVGB315A.18n	GPS Broadcast Ephemeris
WVHA315A.18g	GLONASS Broadcast Ephemeris
WVHA315A.18n	GPS Broadcast Ephemeris
WVLE315A.18g	GLONASS Broadcast Ephemeris
WVLE315A.18n	GPS Broadcast Ephemeris
WVMF315A.18g	GLONASS Broadcast Ephemeris
WVMF315A.18n	GPS Broadcast Ephemeris
WVMZ315A.18g	GLONASS Broadcast Ephemeris
WVMZ315A.18n	GPS Broadcast Ephemeris
WVNR315A.18g	GLONASS Broadcast Ephemeris
WVNR315A.18n	GPS Broadcast Ephemeris
WVOH315A.18g	GLONASS Broadcast Ephemeris
WVOH315A.18n	GPS Broadcast Ephemeris
WVTA315A.18g	GLONASS Broadcast Ephemeris
WVTA315A.18n	GPS Broadcast Ephemeris

Output Files

Filename	File type
sbet_Mission 1.out	SBET Trajectory File

Rover Data Summary

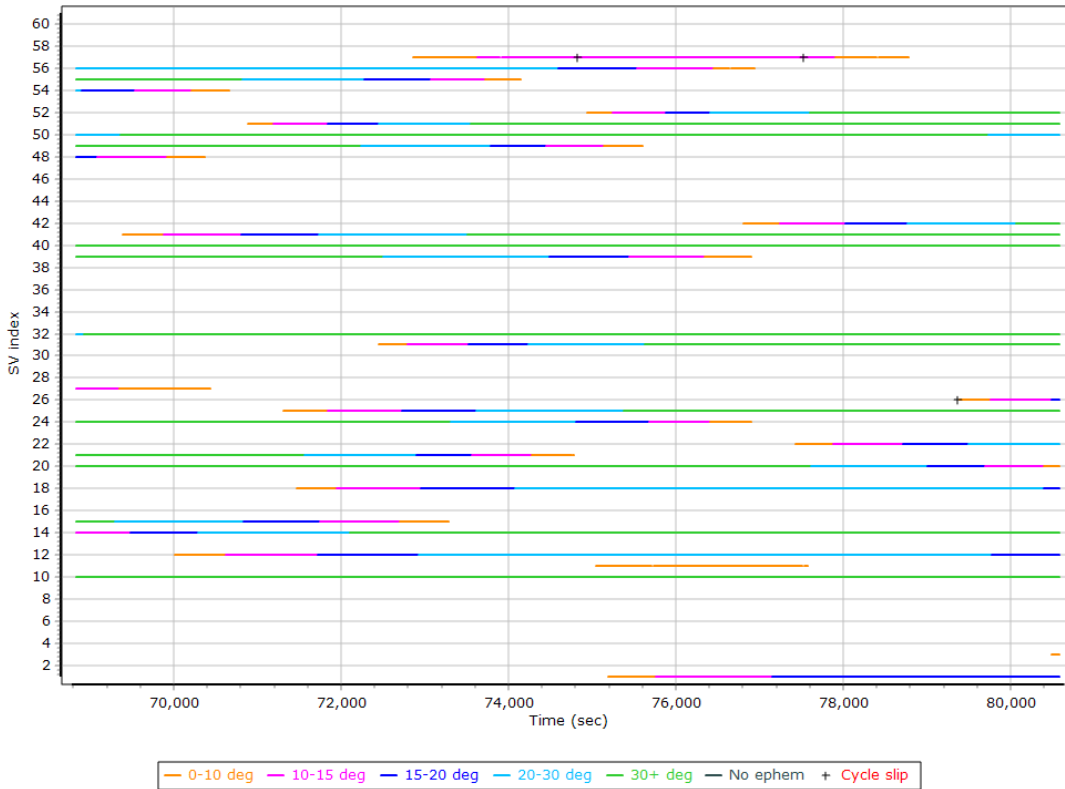
First raw data file	181111_190052_INS-GPS_1.raw		
Last raw data file	181111_190052_INS-GPS_1.raw		
Start GPS week	2027		
Start time	68452.078 (11/11/2018 7:00:52 PM)		
End time	80594.014 (11/11/2018 10:23:14 PM)		
Start of fine alignment	68776.564 (11/11/2018 7:06:16 PM)		
Available subsystems	Primary GNSS, Gimbal, IMU		
POS Event Input	Event 1 Input, Event 2 Input, Event 3 Input, Event 4 Input, Event 5 Input, Event 6 Input		
Correction data	None		
IMU Installation Lever Arms & Mounting Angles			
Gimbal to IMU lever arm [m]	0.000	0.000	0.000
Gimbal to IMU mounting angles [deg]	0.000	0.000	0.000
Gimbal to Primary GNSS lever arm [m]	0.000	0.000	0.000
Gimbal to Primary GNSS lever arm std dev [m]	-1.000		
Aircraft to Reference mounting angles [deg]	0.000	0.000	0.000

Raw Data QC

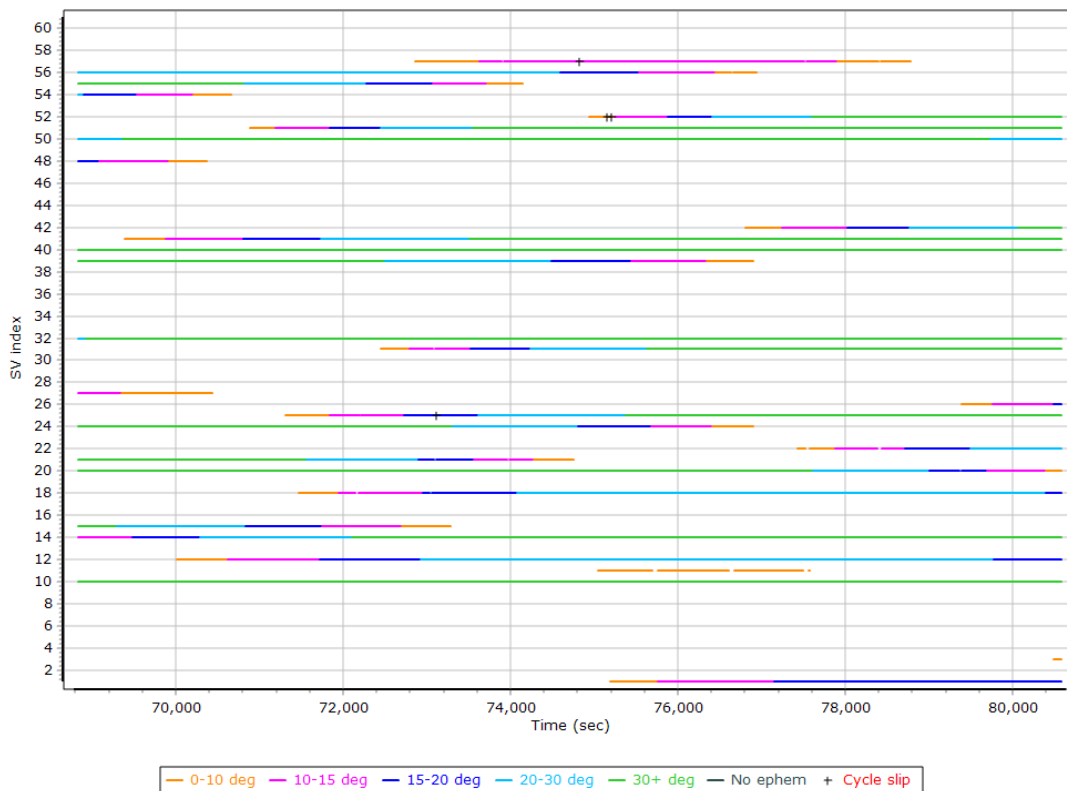
Raw IMU Import QC Summary

IMU data input file	imu_Mission 1.dat
IMU data check log file	imudt_Mission 1.log
IMU Records Processed	2427906
Termination Status	Normal
IMU Anomalies	0

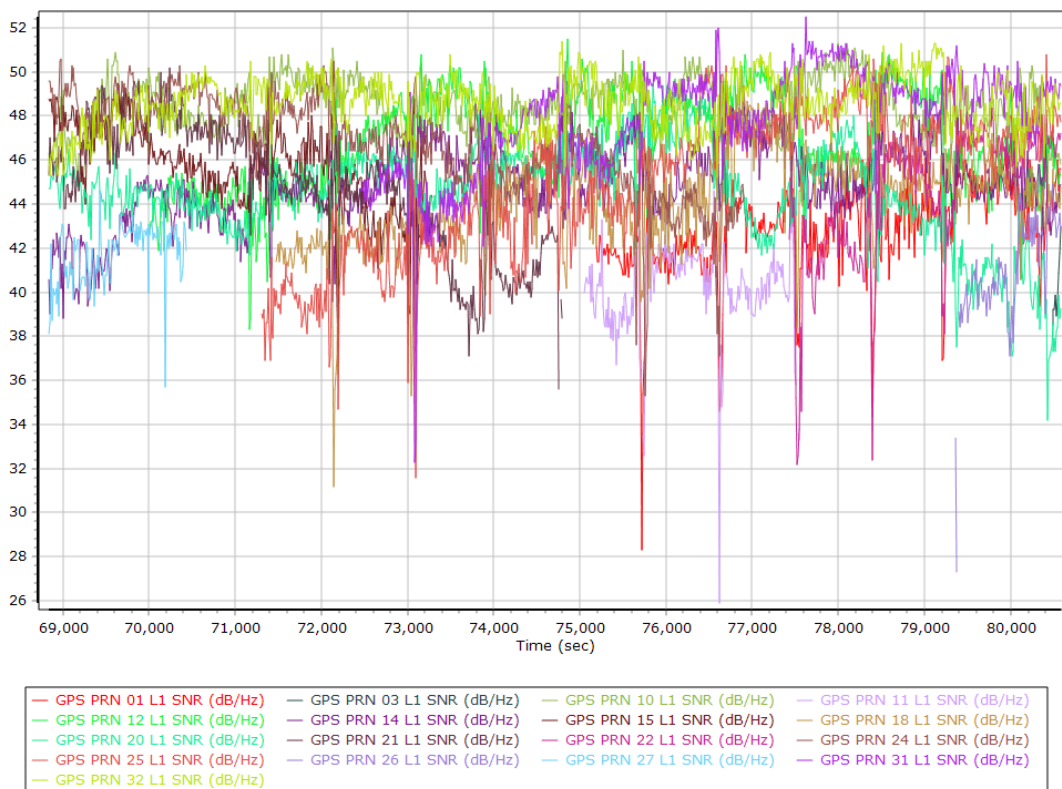
L1 Satellite Lock/Elevation



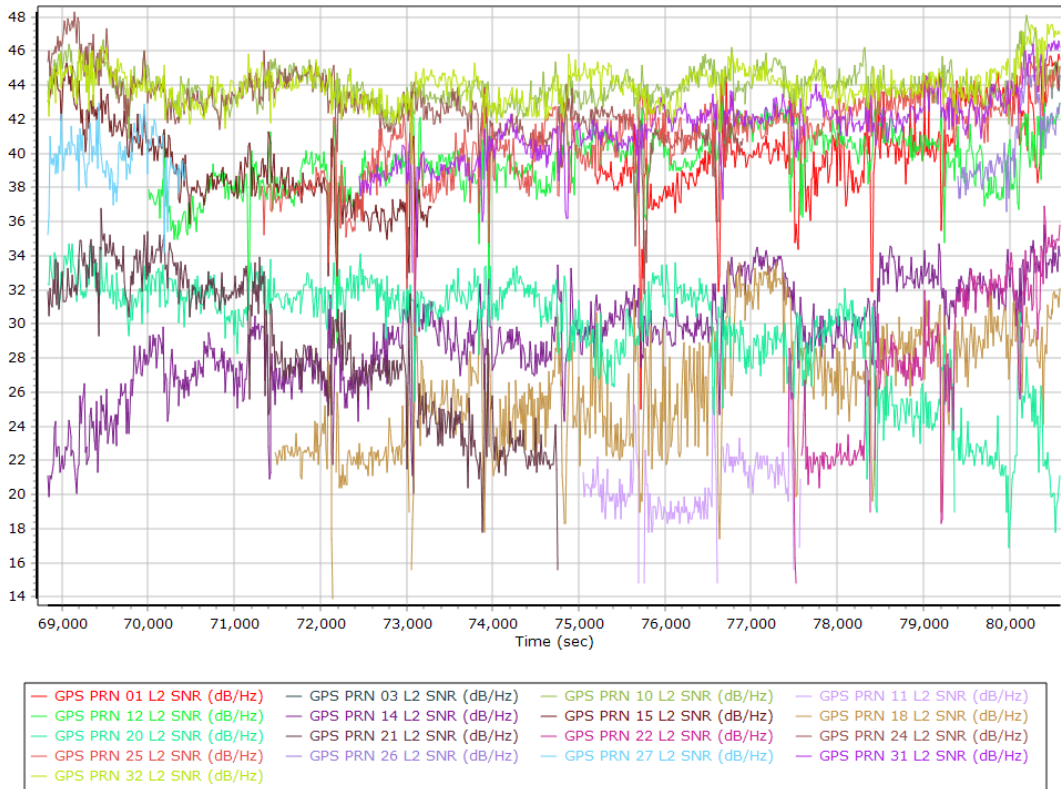
L2 Satellite Lock/Elevation



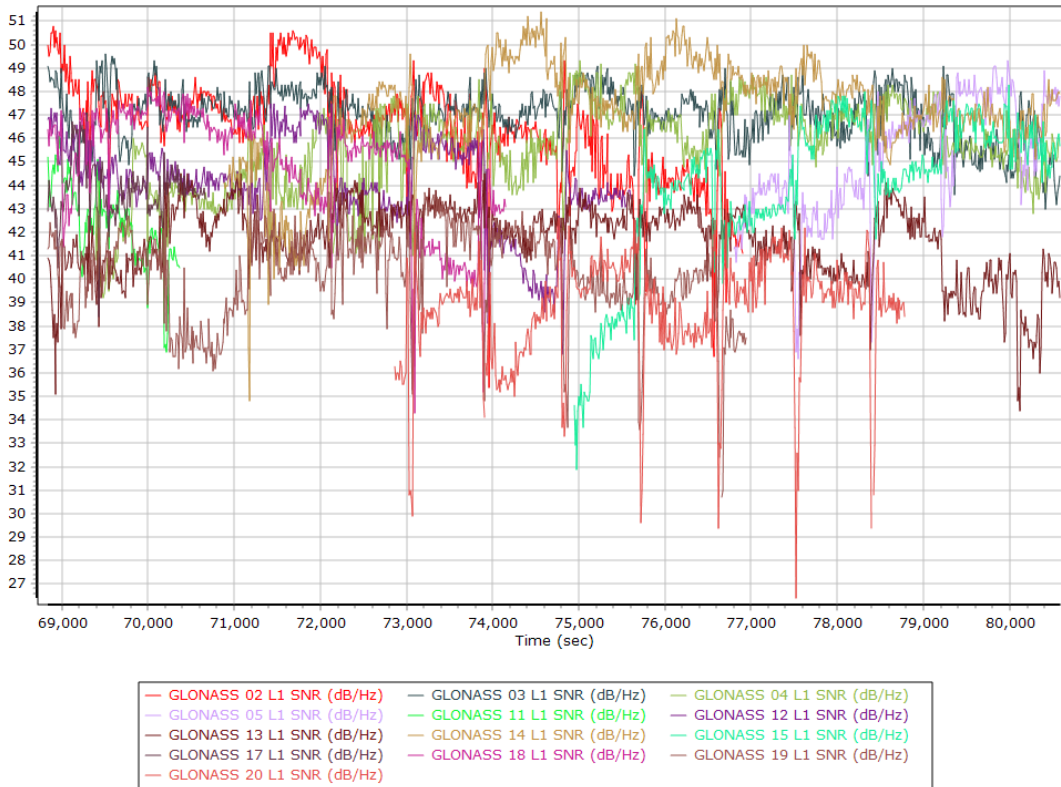
GPS L1 SNR



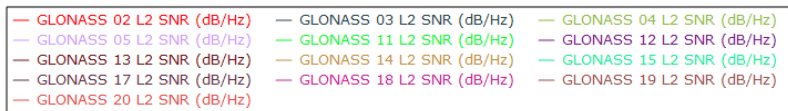
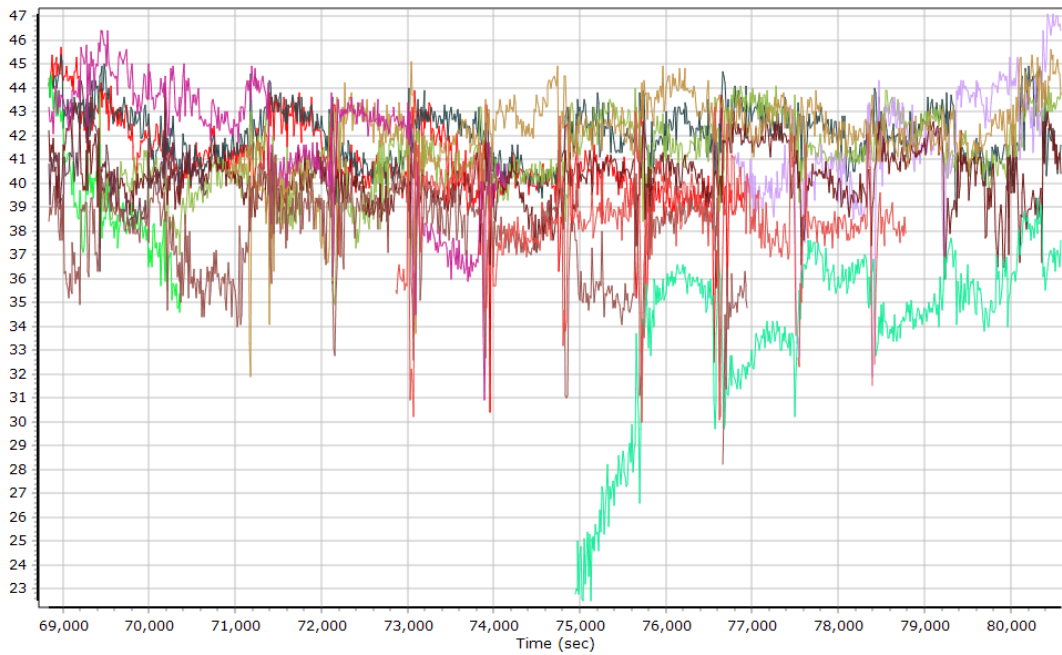
GPS L2 SNR



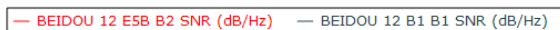
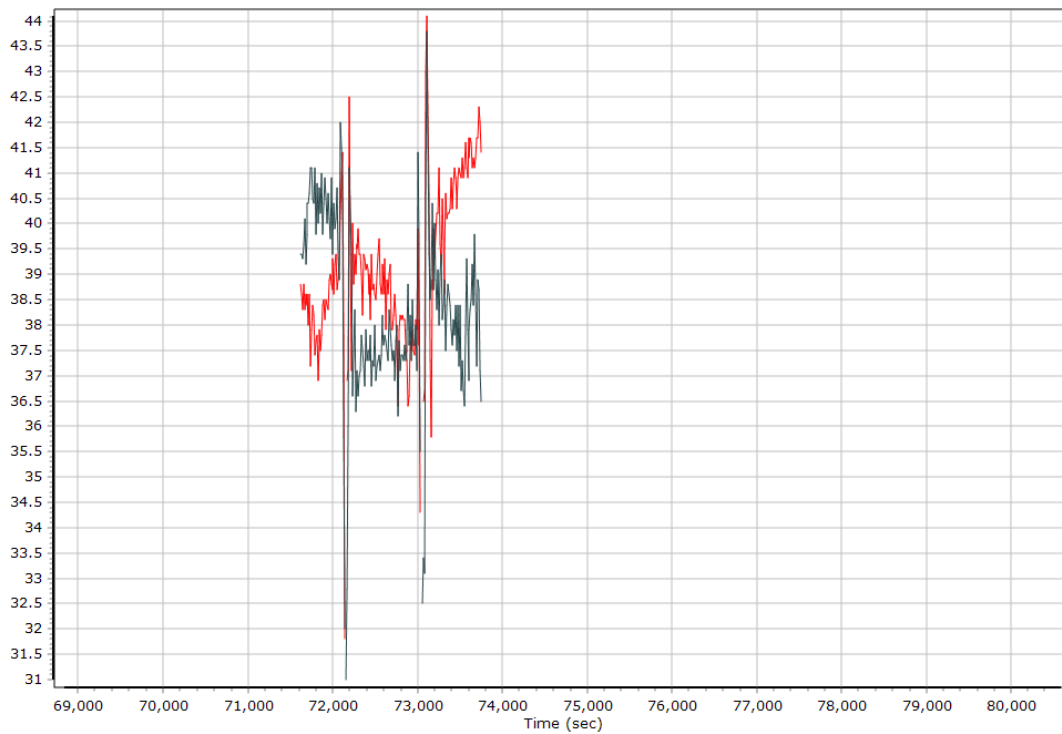
GLONASS L1 SNR



GLONASS L2 SNR

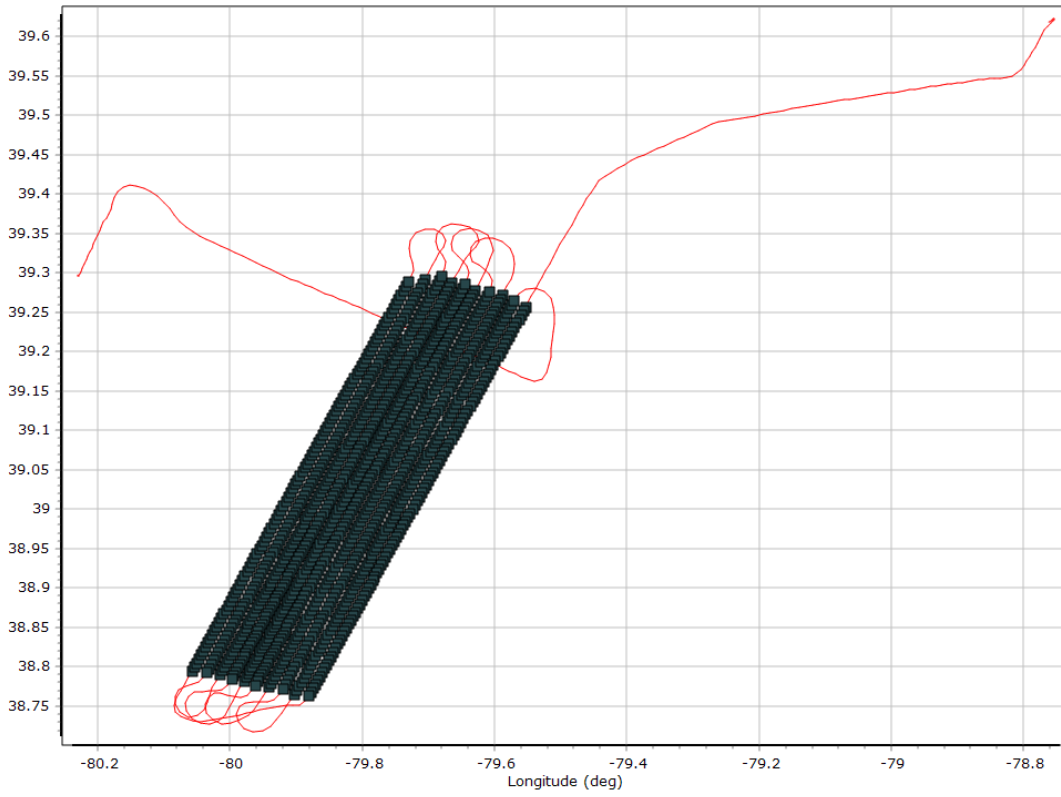


BEIDOU SNR

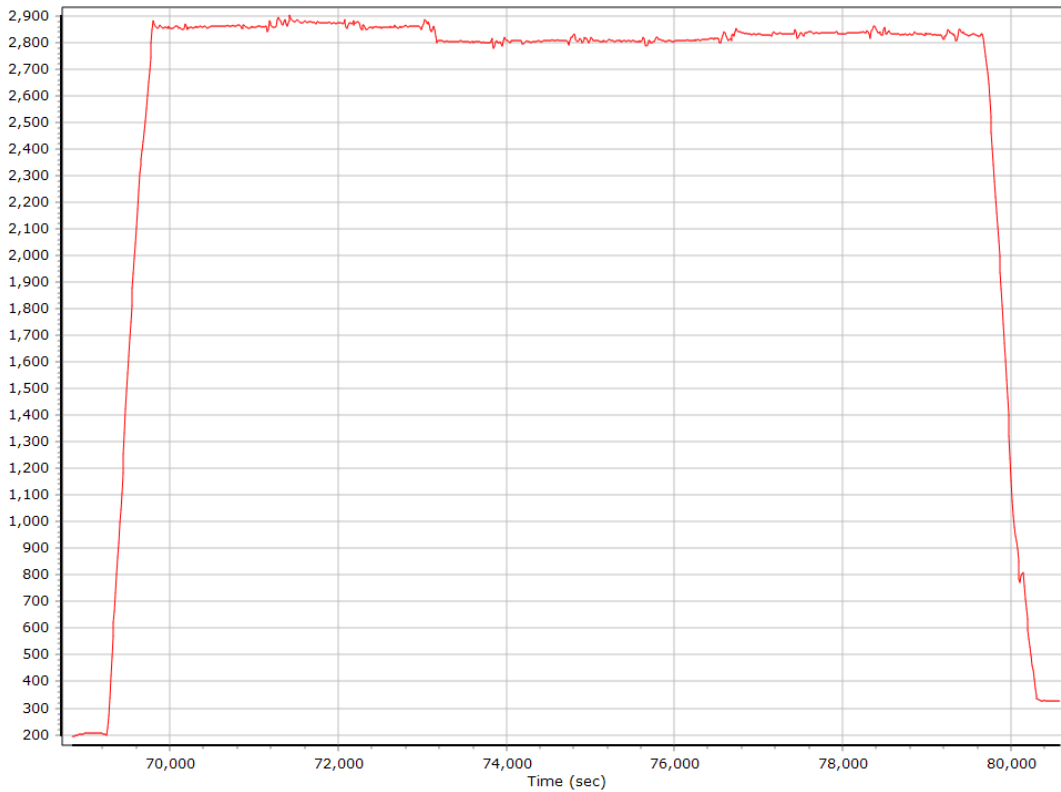


Trajectory Information

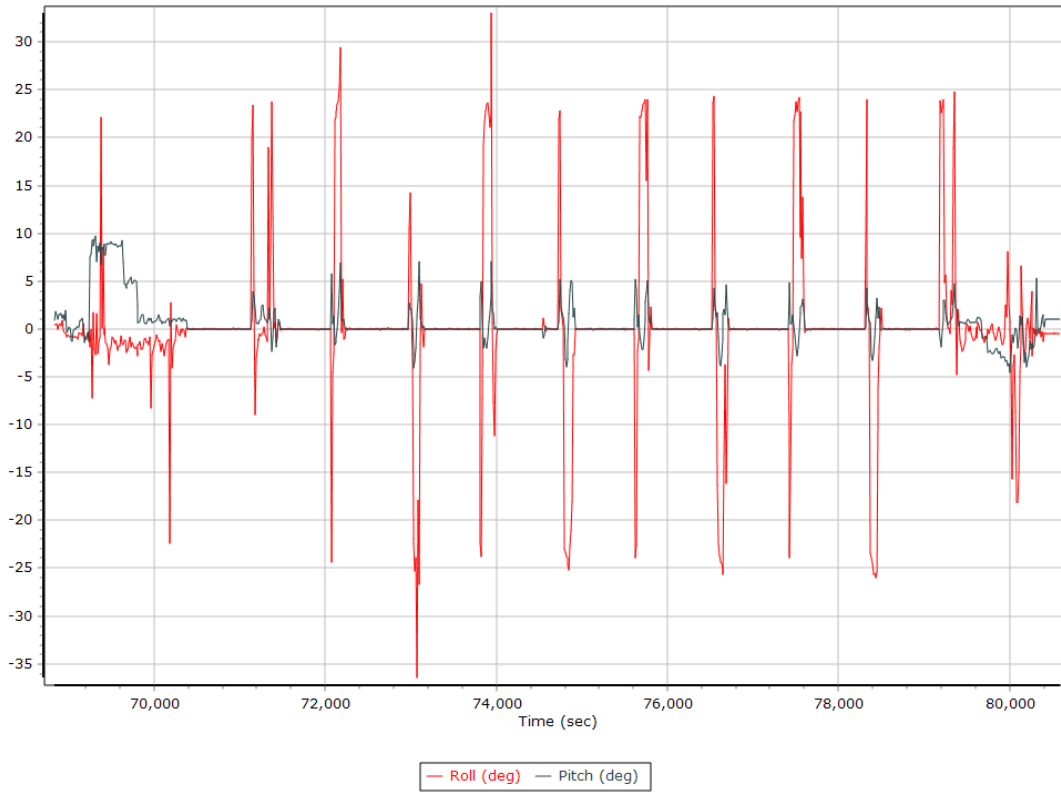
Top View



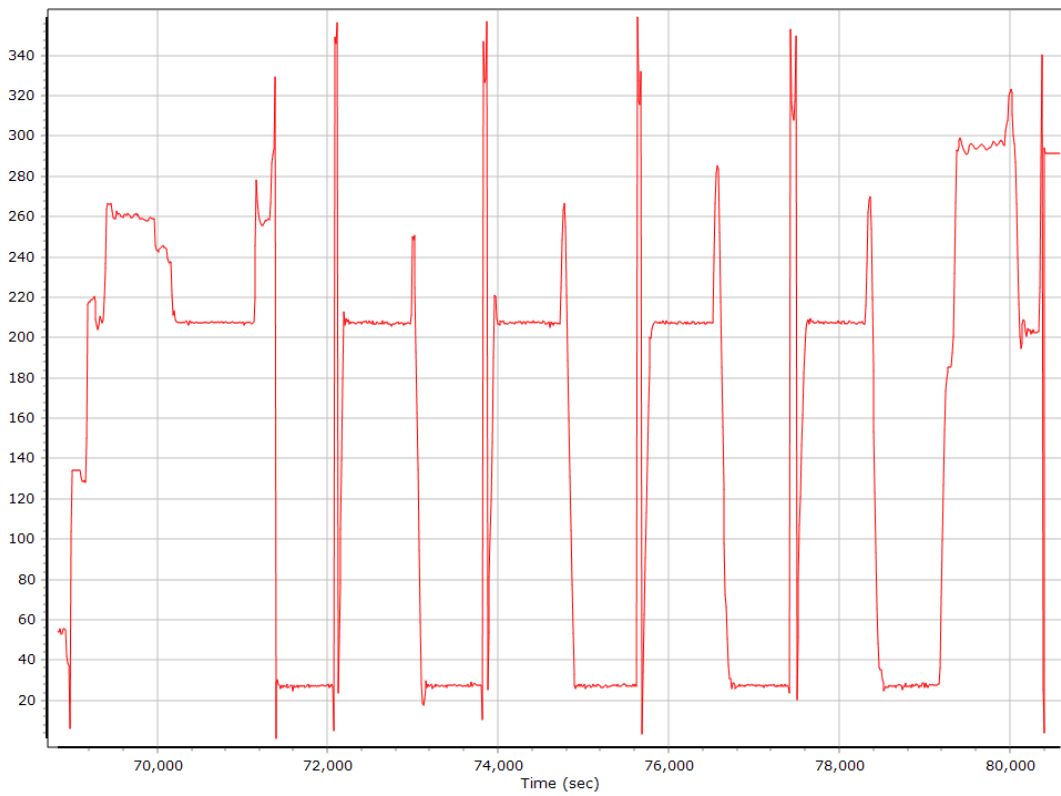
Altitude



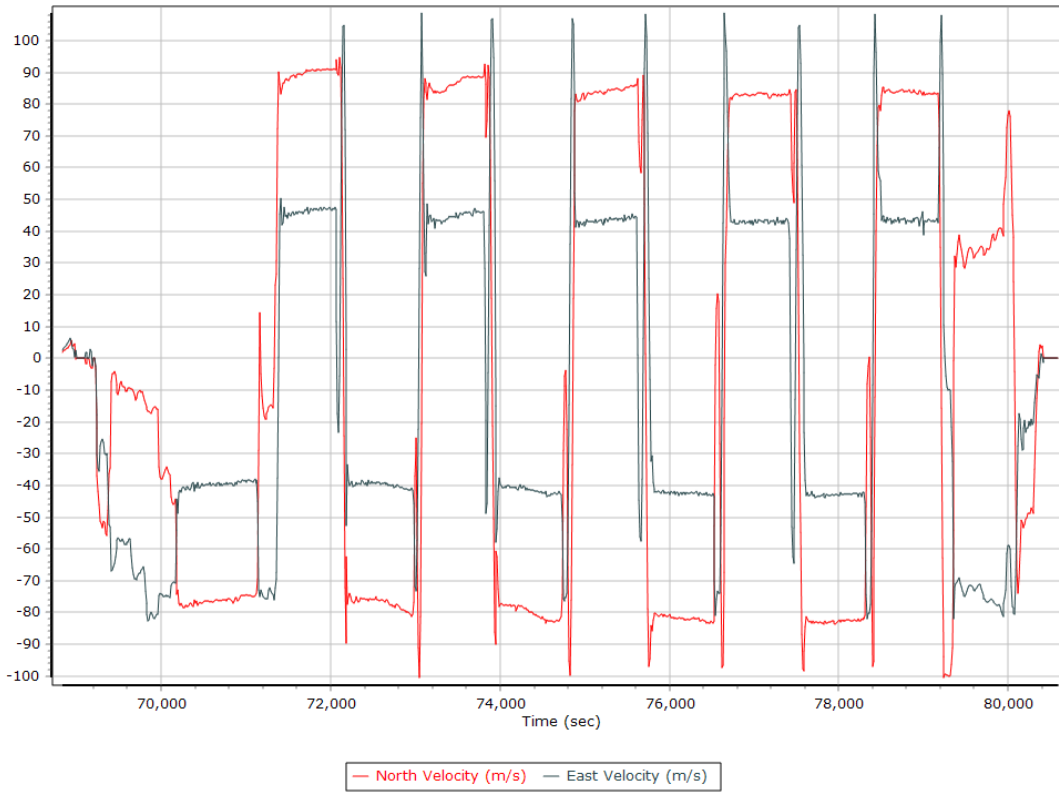
Roll/Pitch



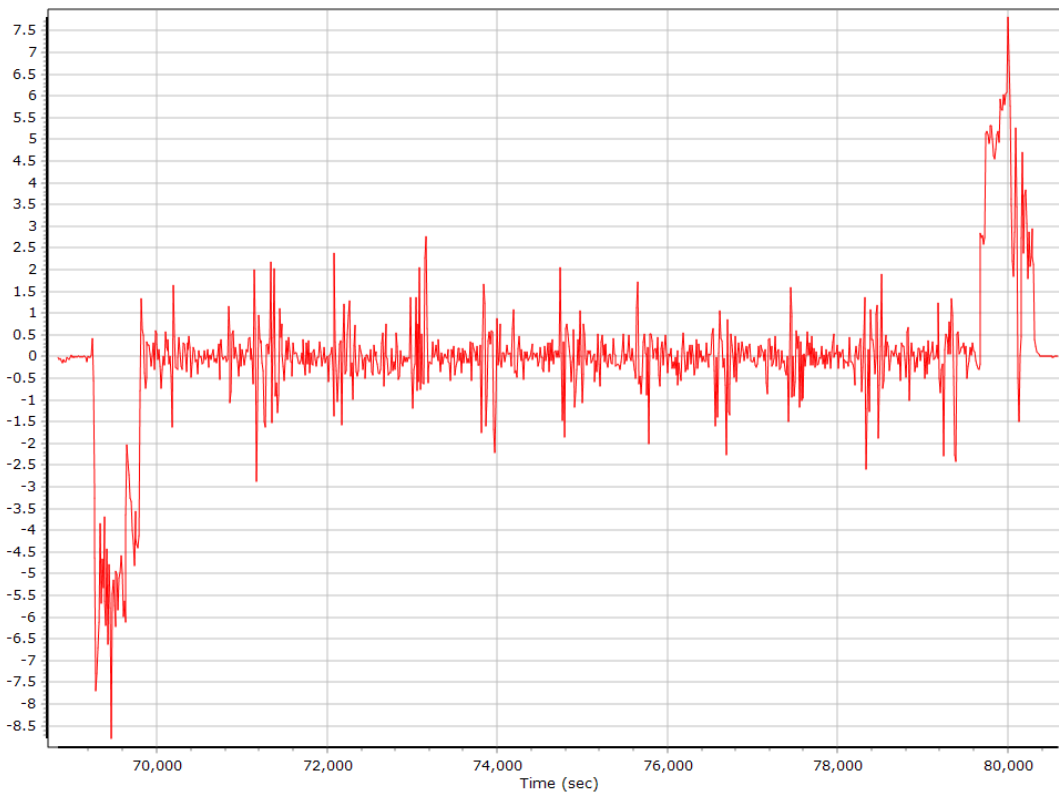
Heading



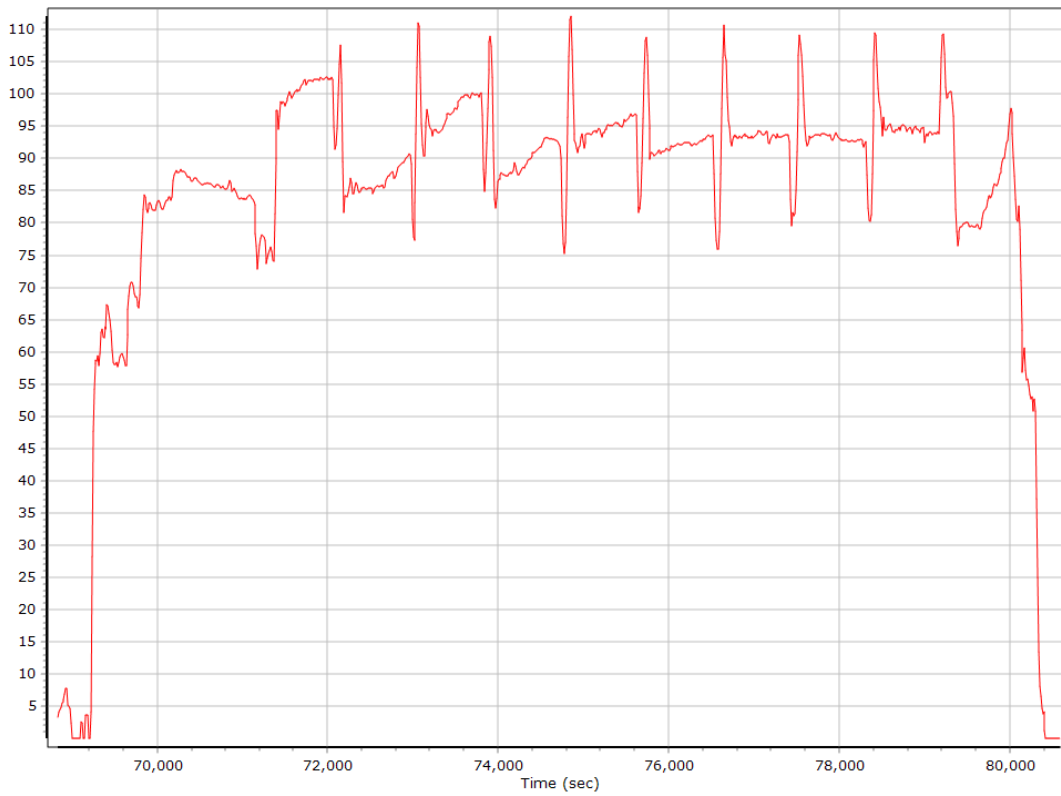
North/East Velocity



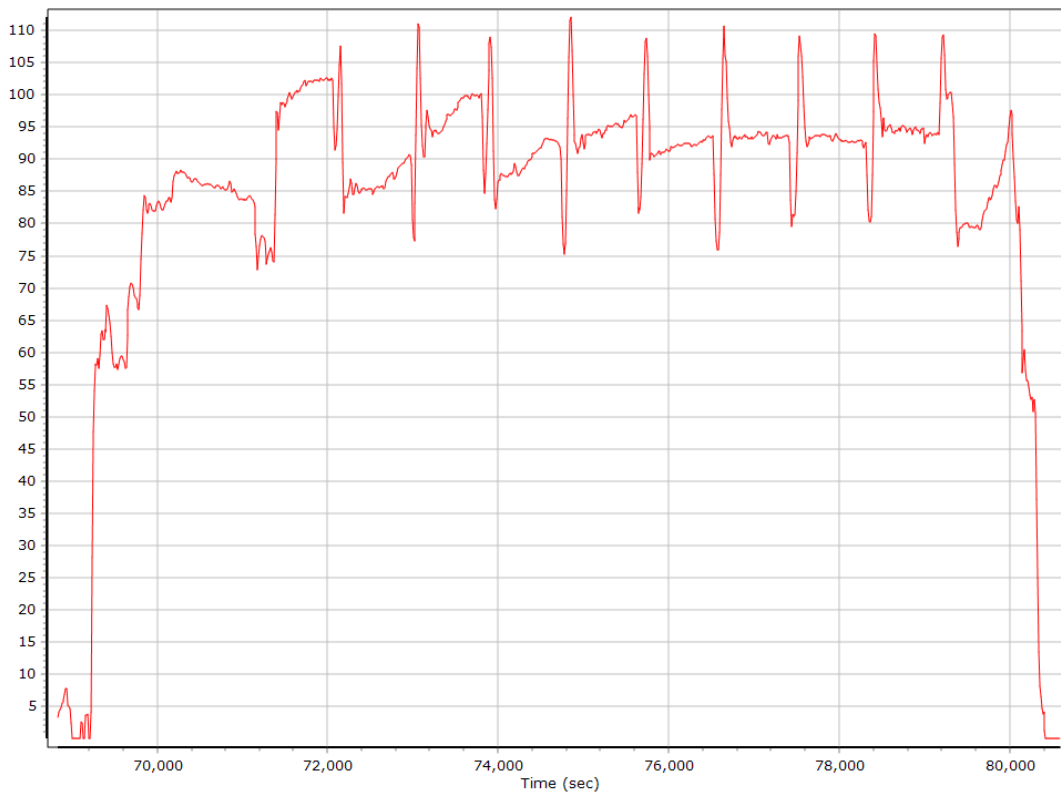
Down Velocity



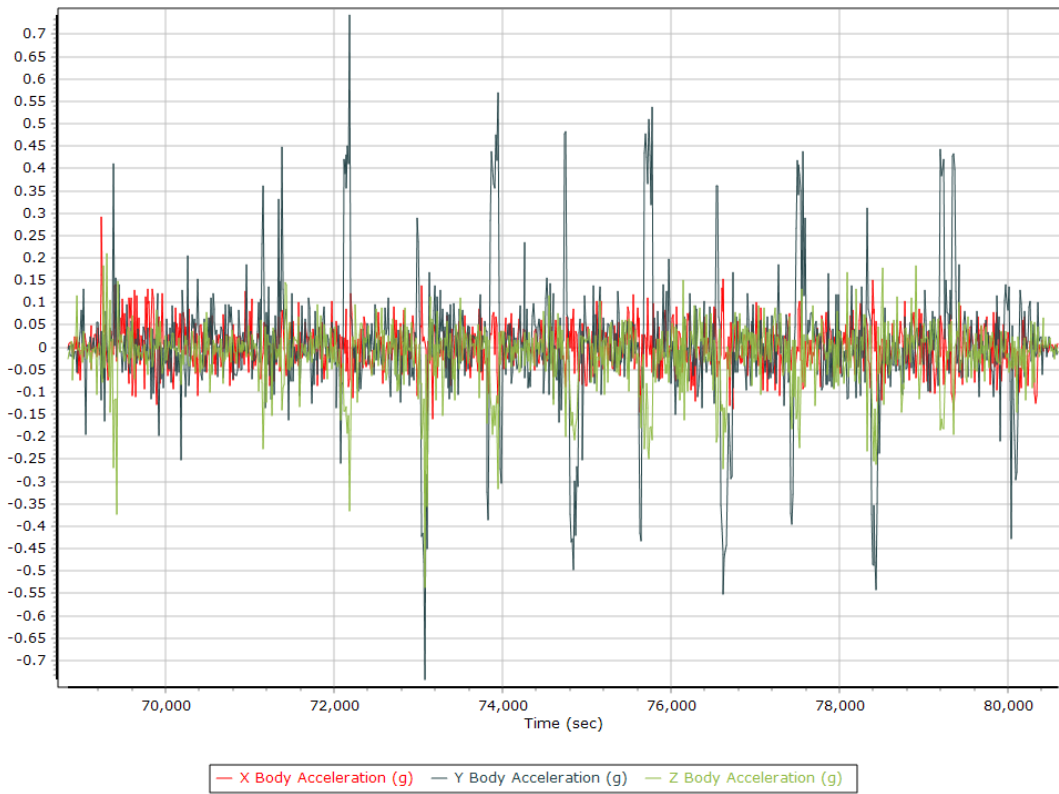
Total Speed



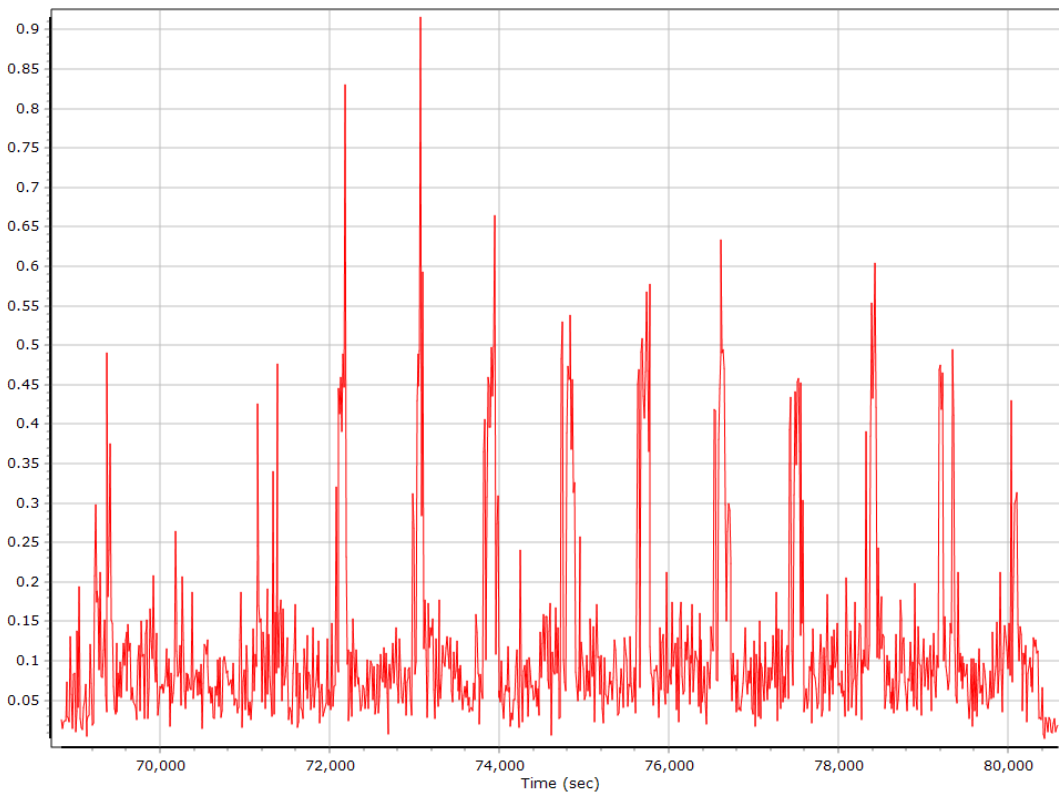
Ground Speed



Body Acceleration



Total Body Acceleration



Body Angular Rate



SmartBase Processing Summary

Smart Select Options

Archive enabled	False
User database enabled	False
Include high-rate data sites	False
Target GNSS Selection	GNSS

Basestation Selection

Date	ID	Dist	Data Type	Rate	Service	Database	Status
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SmartBase Results

SmartBase status	
Primary station Id	
Primary station data rate [sec]	0.0
VRS/ASB generation rate [sec]	0.0
VRS/ASB timespan	
Number of reference stations	0
Primary station GPS measurement usage [%]	0.0
Average number of satellites per epoch	0.0
Max number of GPS stations used	0
Min number of GPS stations used	0
Total full data gap [sec]	0
Total individual satellite data gap [sec]	0
GPS precise vs. broadcast ephemeris used	0.0 % / 0.0 %
Termination Status	

SmartBase Quality Check

GNSS QC

GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length [km]	1.95	97.36	
Number of GPS SV	6	11	9
Number of GLONASS SV	0	8	7
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	0	0
Total number of SV	8	18	16
PDOP	1.08	2.05	1.33
QC Solution Gaps	1.00	1.00	
Solution Type	Fixed	Float	No solution
Epoch (s)	12115.00	0.00	1.00
Percentage	99.99	0.00	0.01

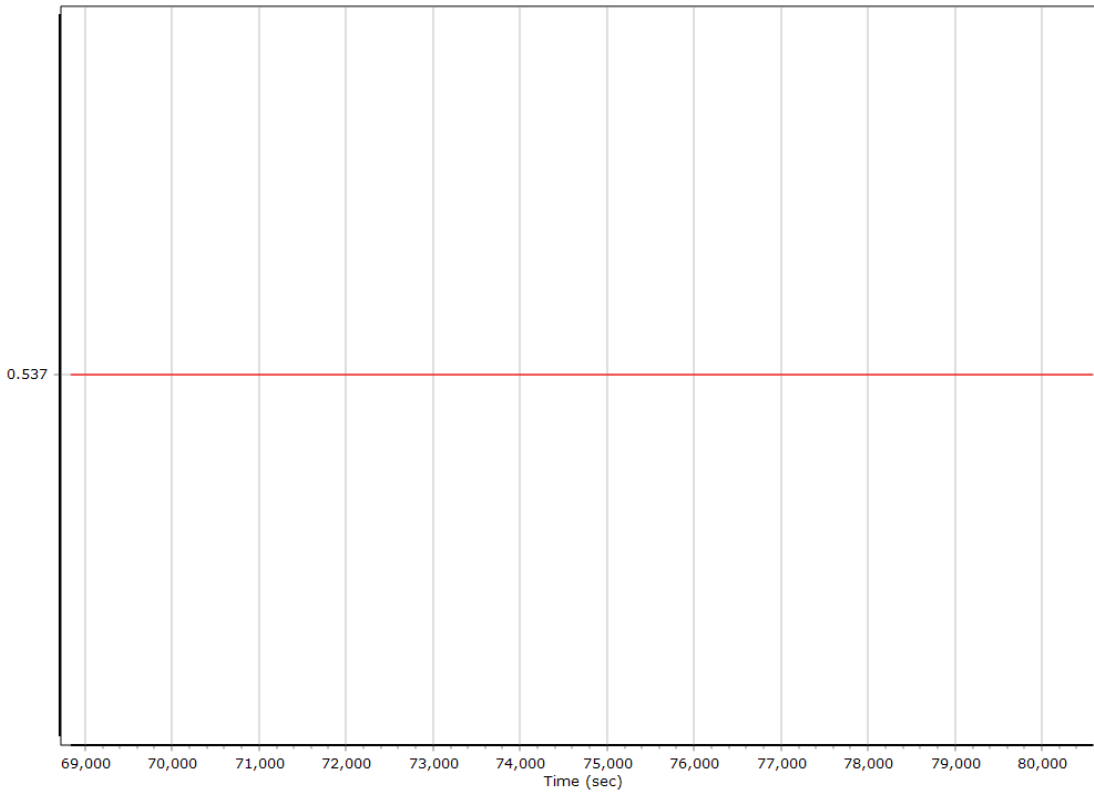
GNSS-Inertial Processor Configuration

Processing mode	IN-Fusion SmartBase		
Stabilized mount	True		
Base station	ASB		
Processing start time	68453.000 (11/11/2018 7:00:53 PM)		
Processing end time	80594.000 (11/11/2018 10:23:14 PM)		
Initial attitude source	Real-Time VNAV/RNAV Attitude		
IMU Sensor Context	Processing with Onboard IMU		
Gimbal to IMU lever arm [m]	0.000	0.000	0.000
Gimbal to IMU mounting angles [deg]	0.000	0.000	0.000
Gimbal to Primary GNSS lever arm [m]	0.537	-0.083	-0.916
Gimbal to Primary GNSS lever arm std dev [m]	0.030	0.030	0.030
Aircraft to Reference mounting angles [deg]	0.000	0.000	0.000

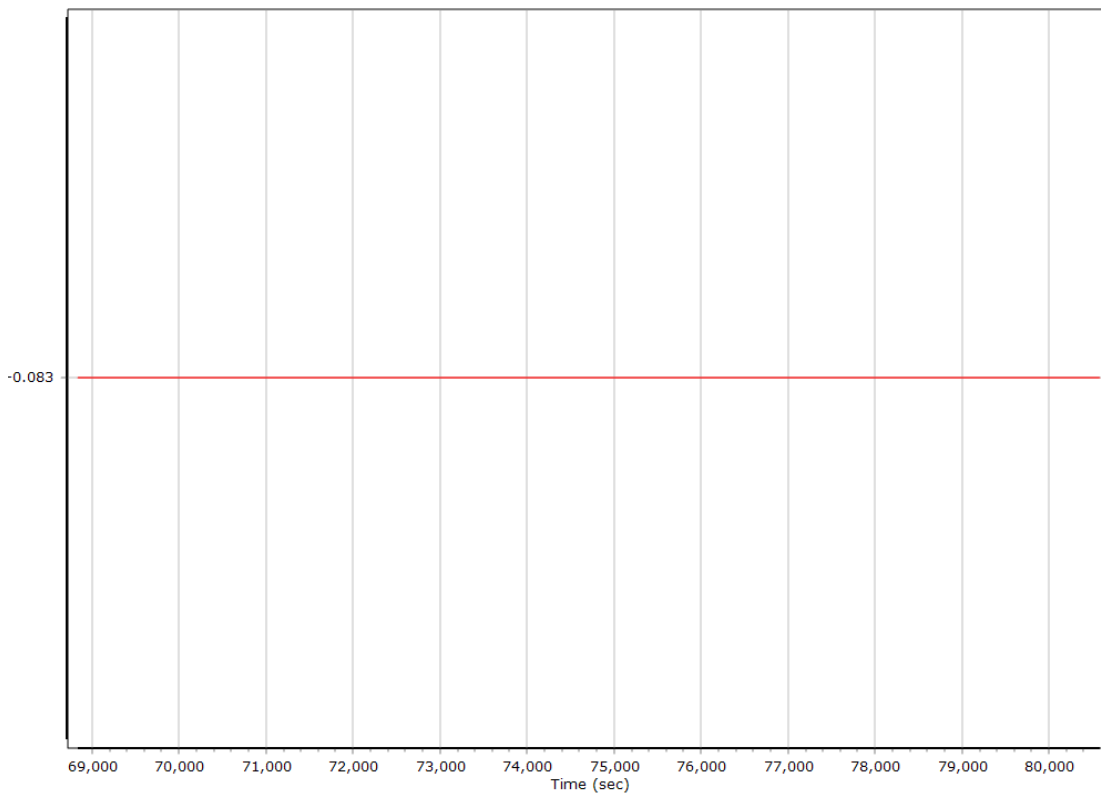
Calibrated Installation Parameters

Reference-Primary GNSS Lever Arm

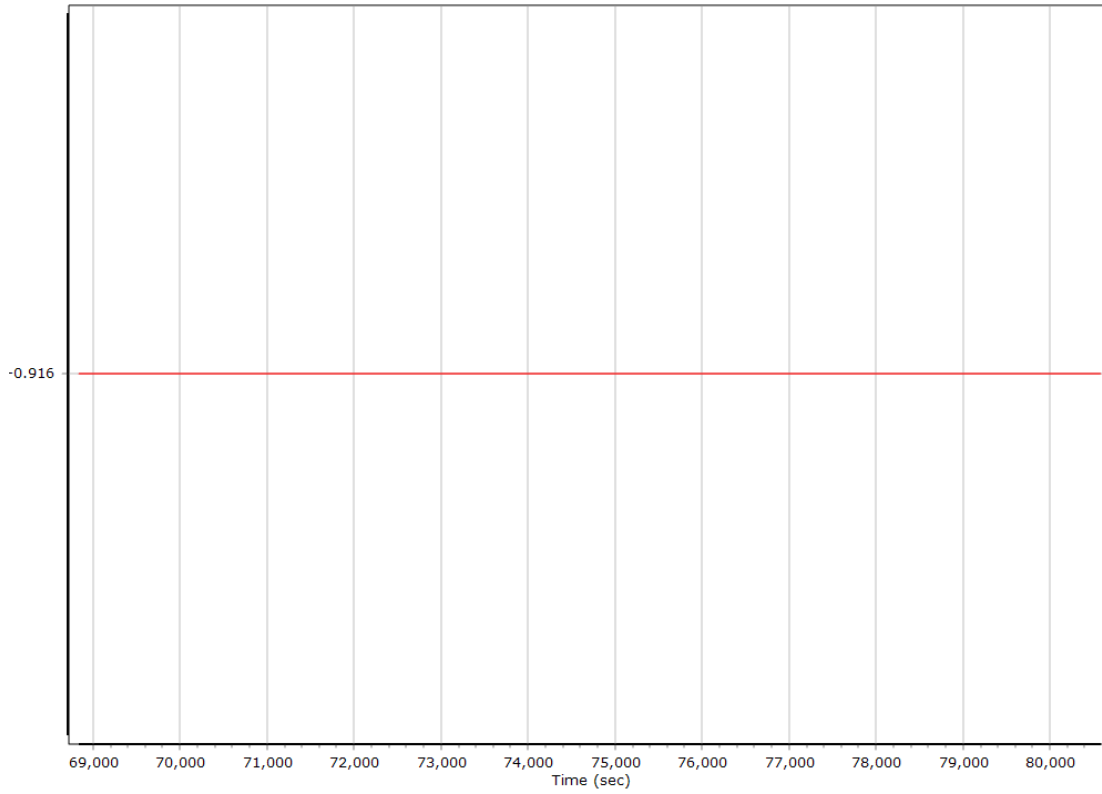
X Reference-Primary GNSS Lever Arm (m)



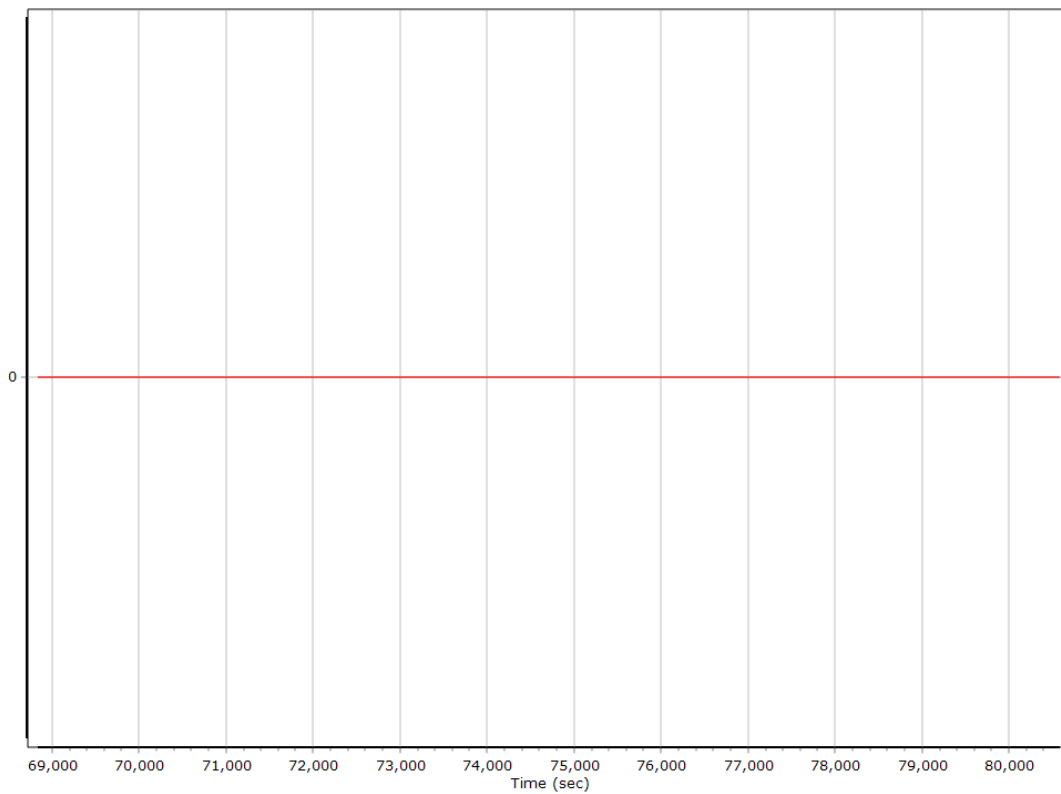
Y Reference-Primary GNSS Lever Arm (m)



Z Reference-Primary GNSS Lever Arm (m)



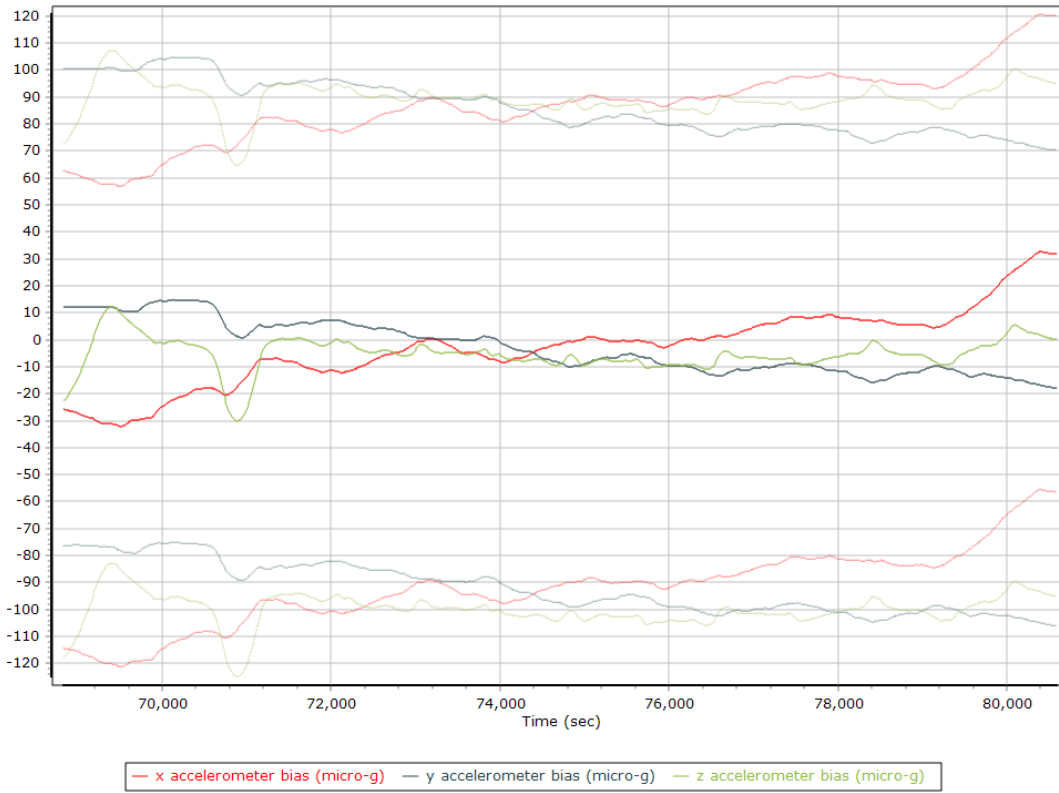
Reference-Primary GNSS Lever Arm Figure of Merit



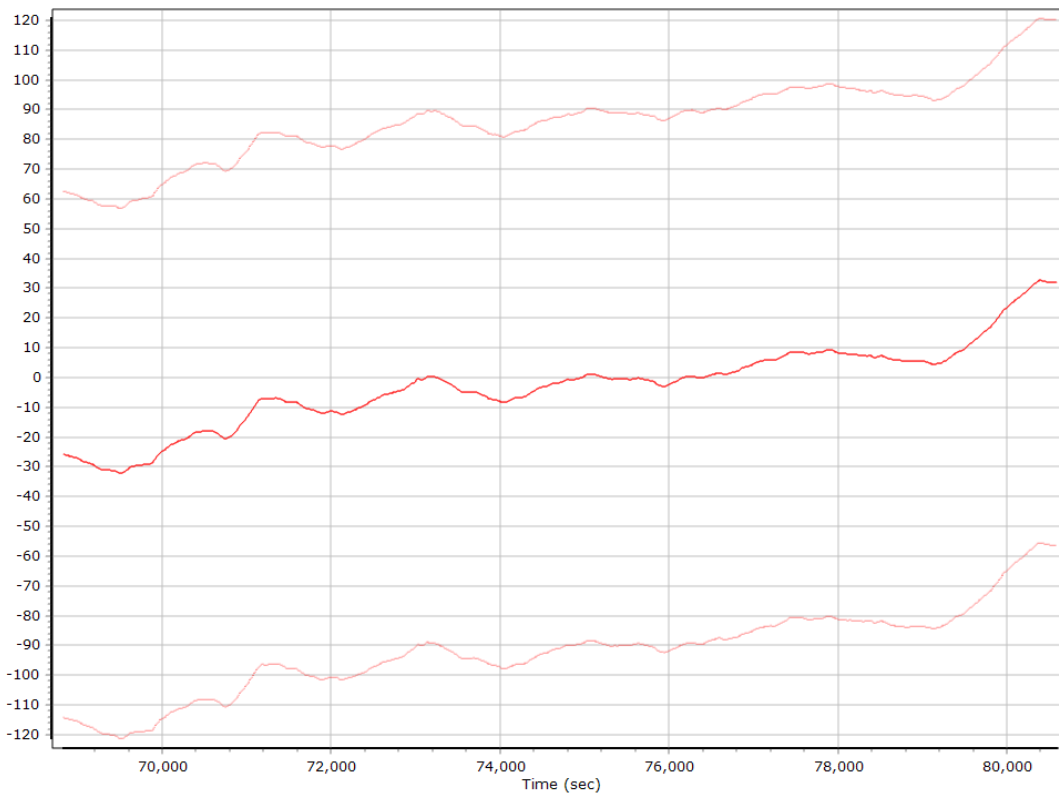
Smoothed IN-Fusion QC

Smoothed Estimated Errors, Reference Frame

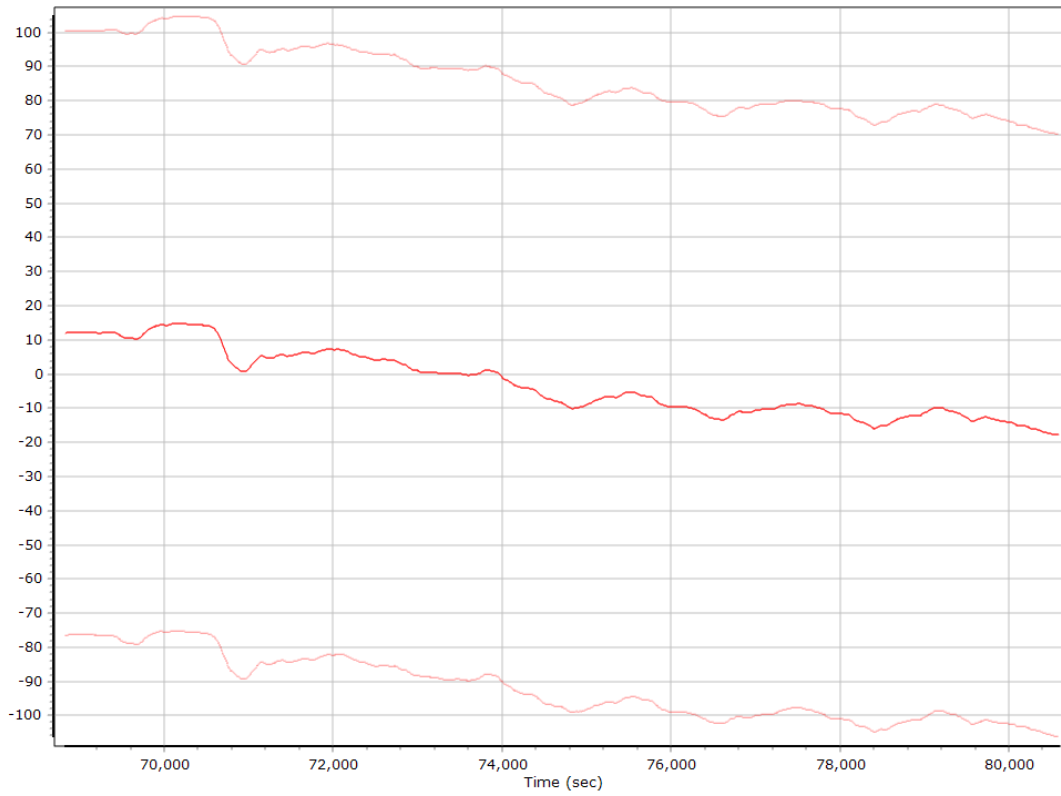
Accelerometer Bias (micro-g)



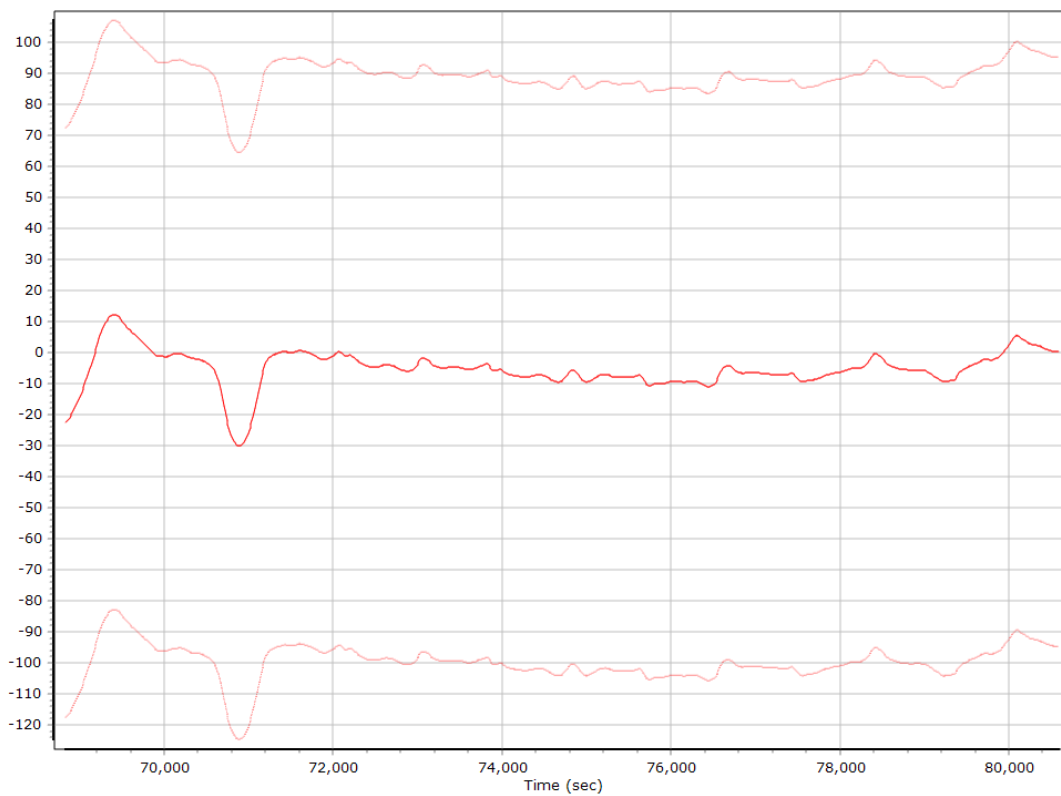
X Accelerometer Bias (micro-g)



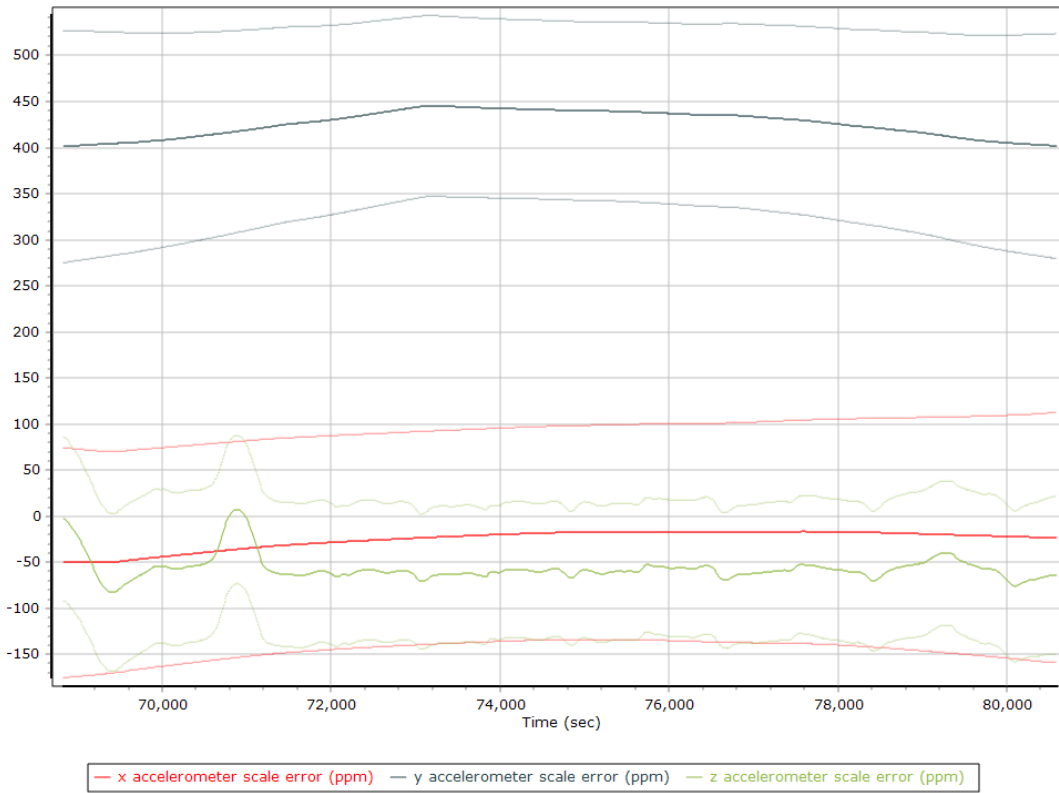
Y Accelerometer Bias (micro-g)



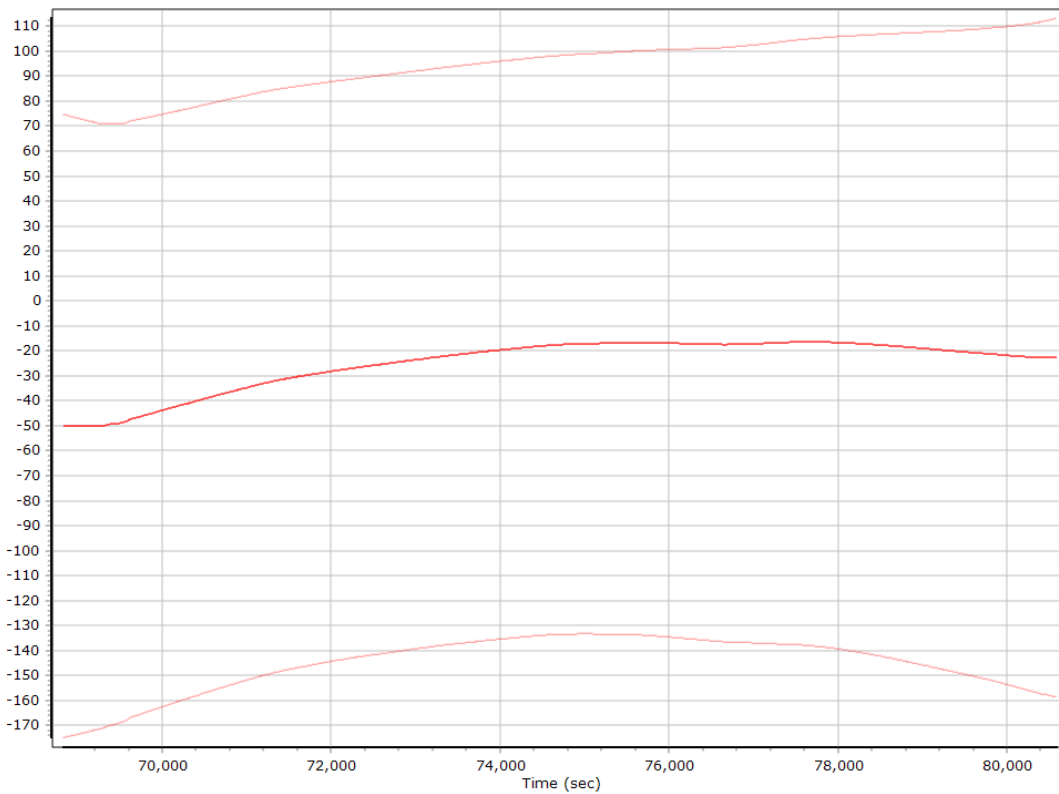
Z Accelerometer Bias (micro-g)



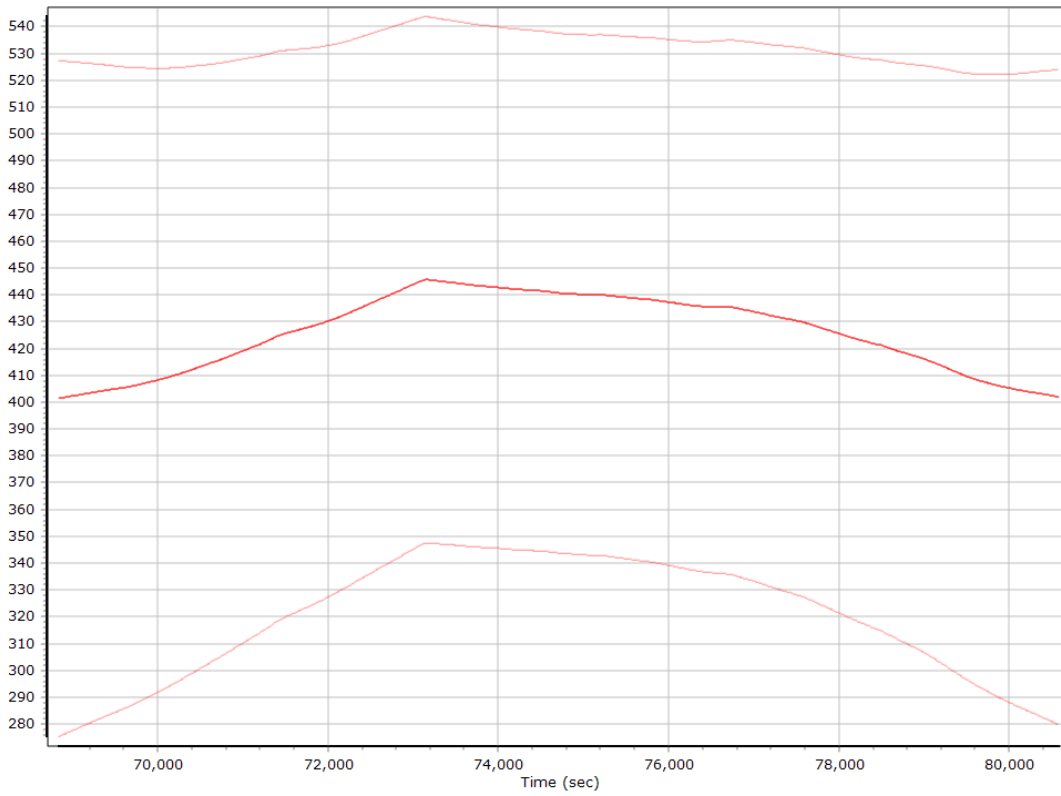
Accelerometer Scale Error (ppm)



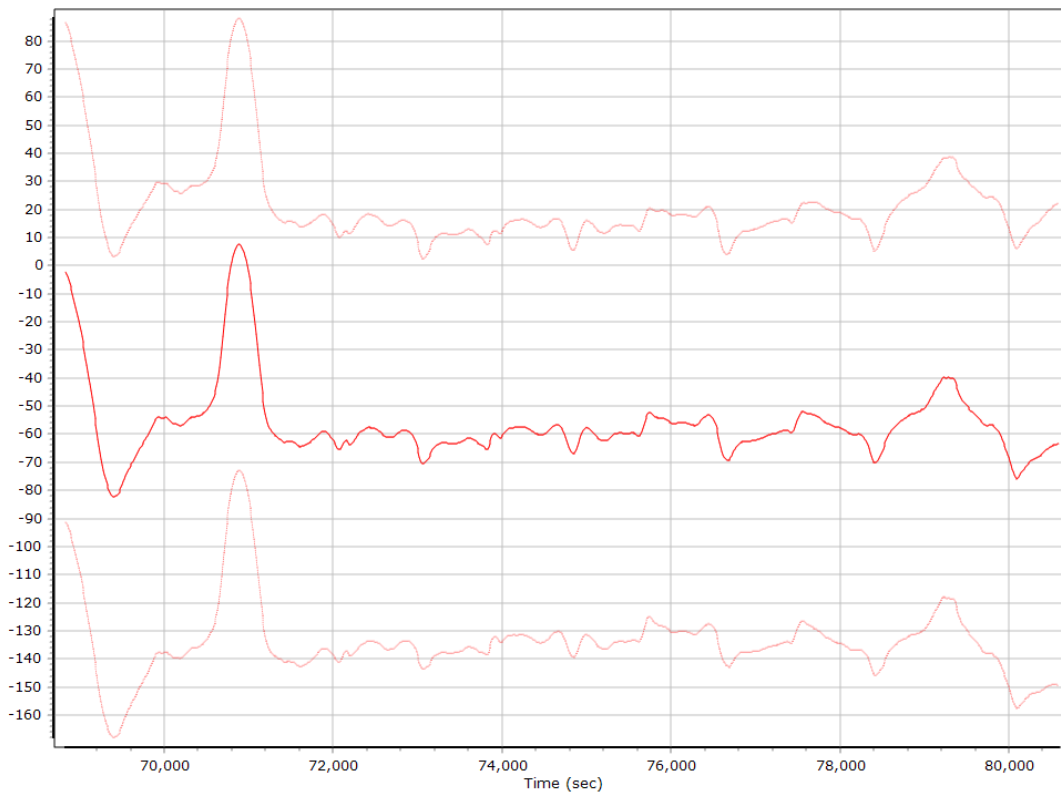
X Accelerometer Scale Error (ppm)



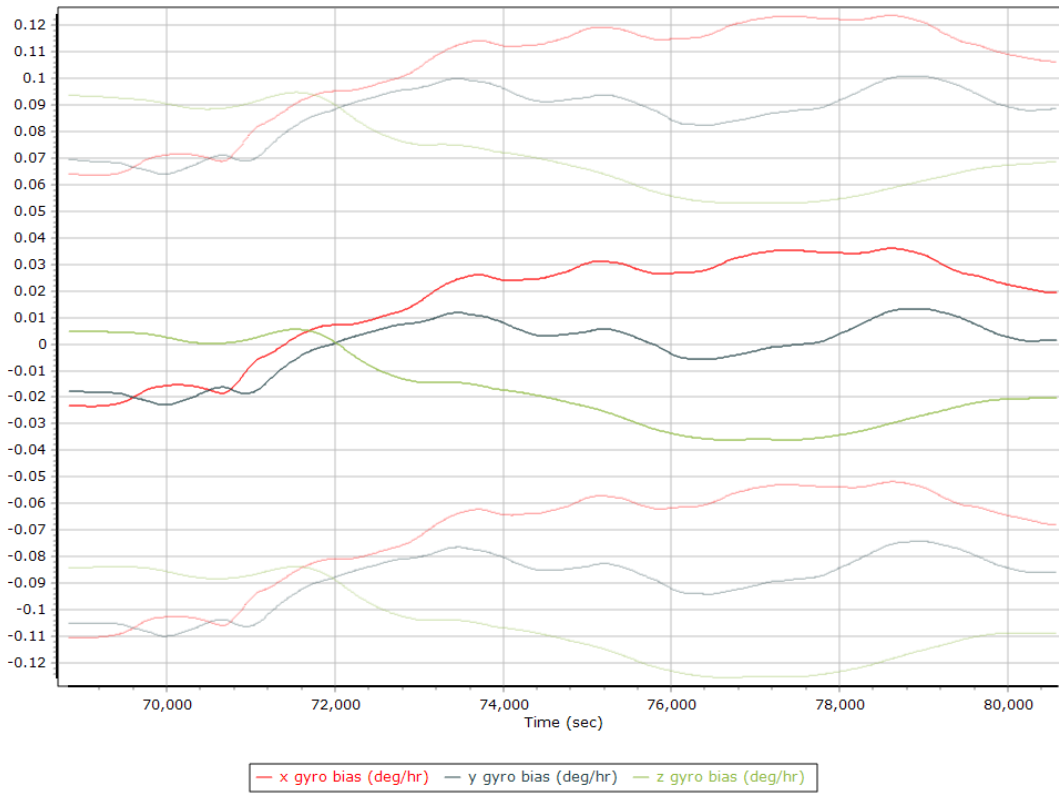
Y Accelerometer Scale Error (ppm)



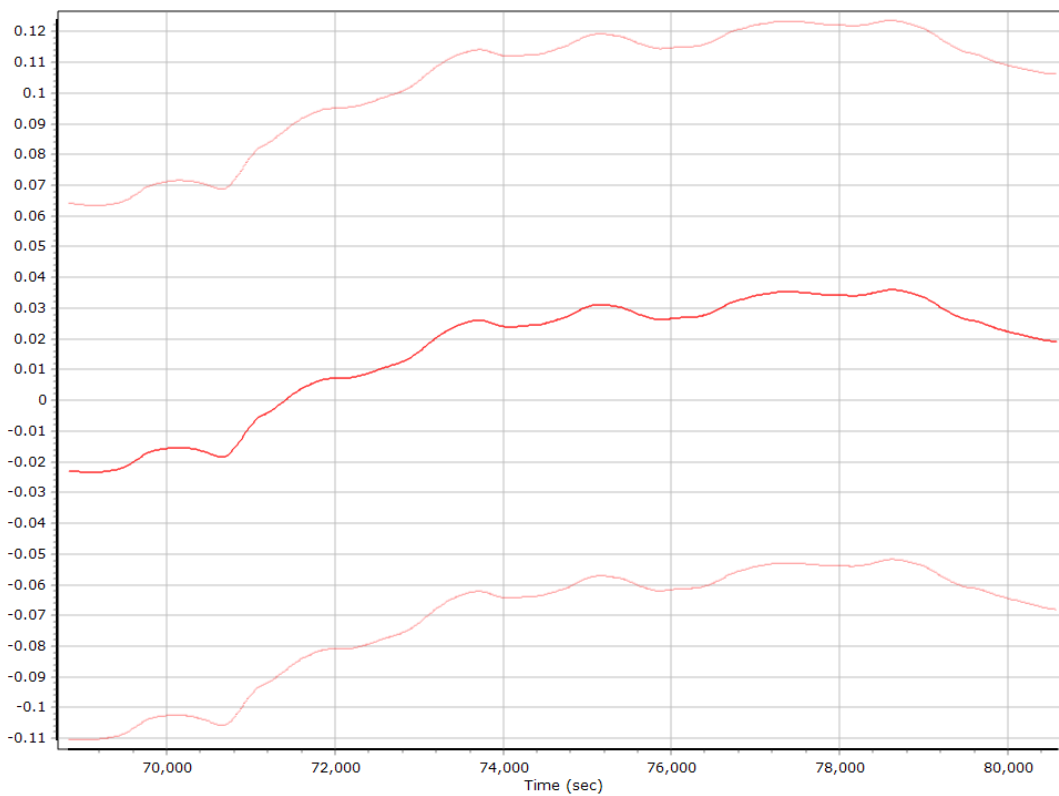
Z Accelerometer Scale Error (ppm)



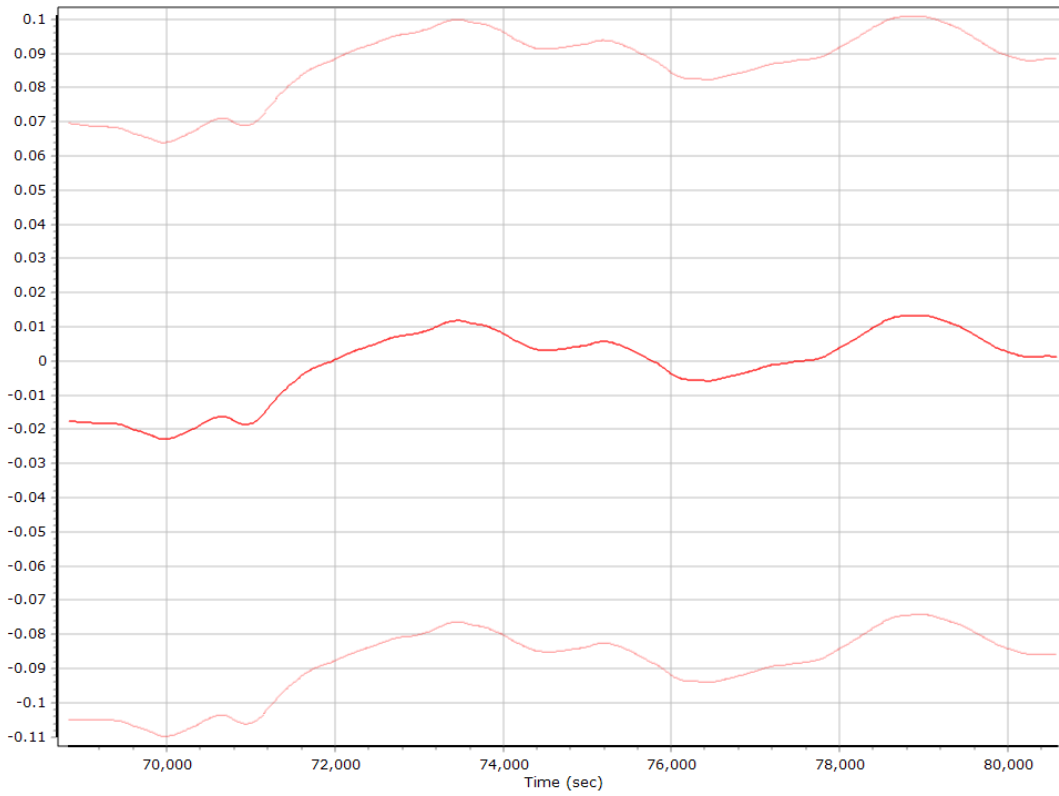
Gyro Bias (deg/h)



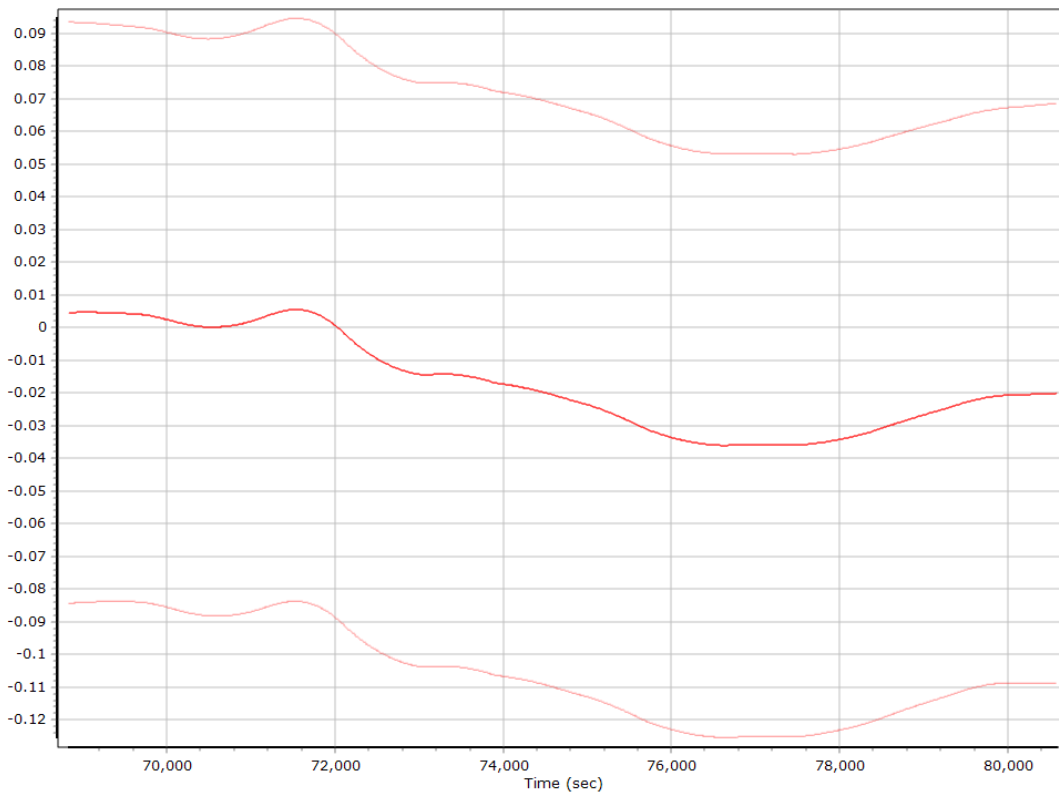
X Gyro Bias (deg/h)



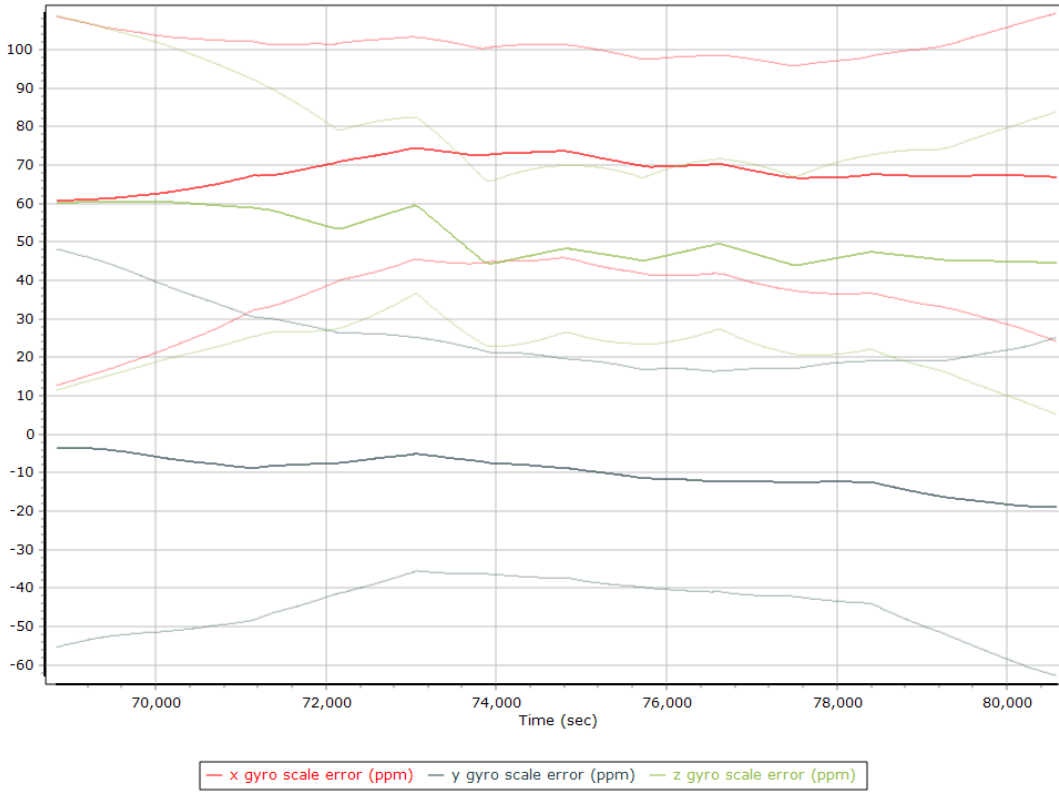
Y Gyro Bias (deg/h)



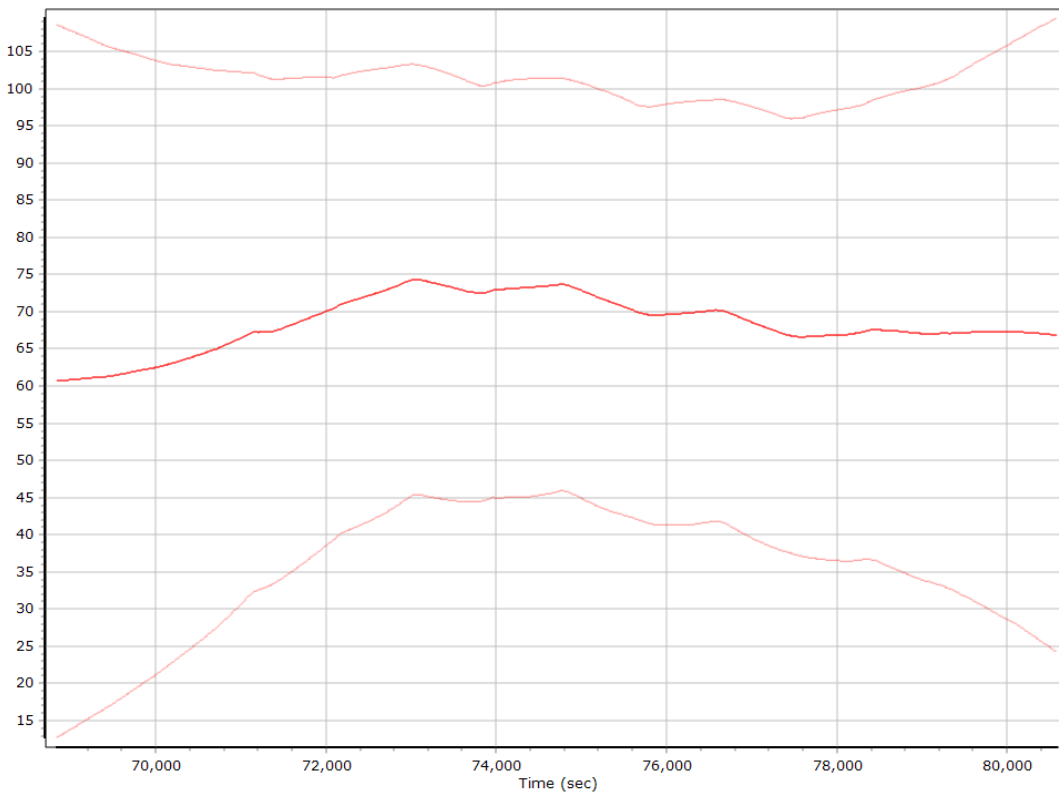
Z Gyro Bias (deg/h)



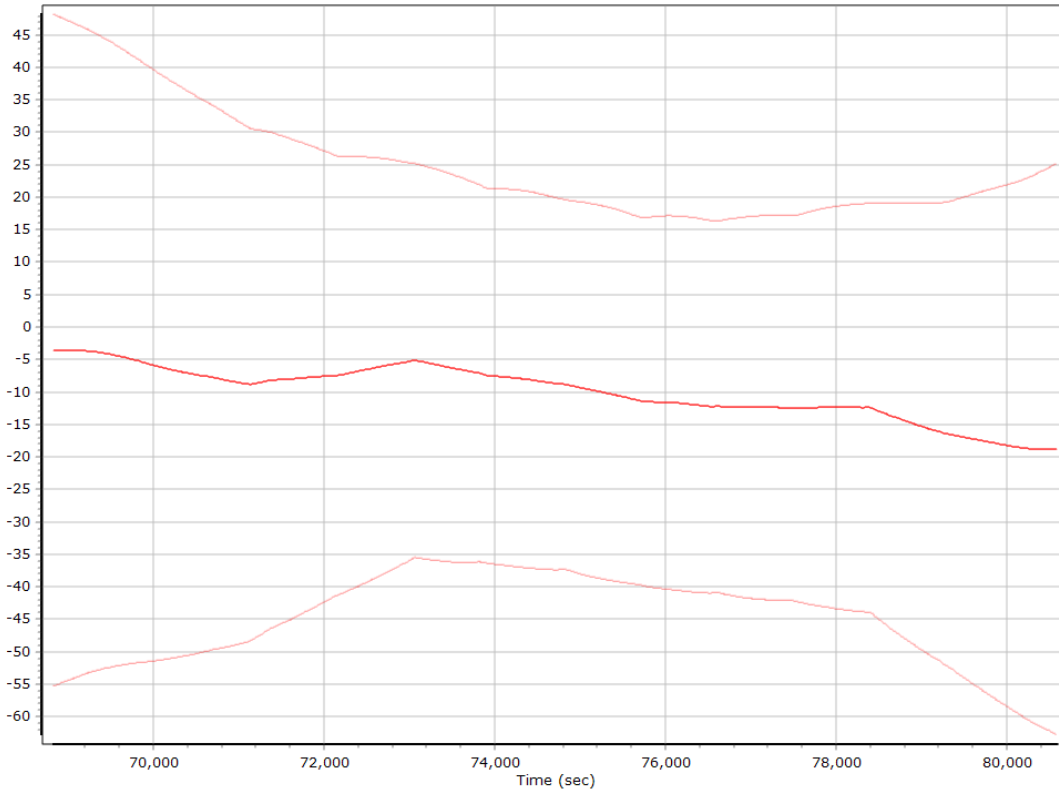
Gyro Scale Error (ppm)



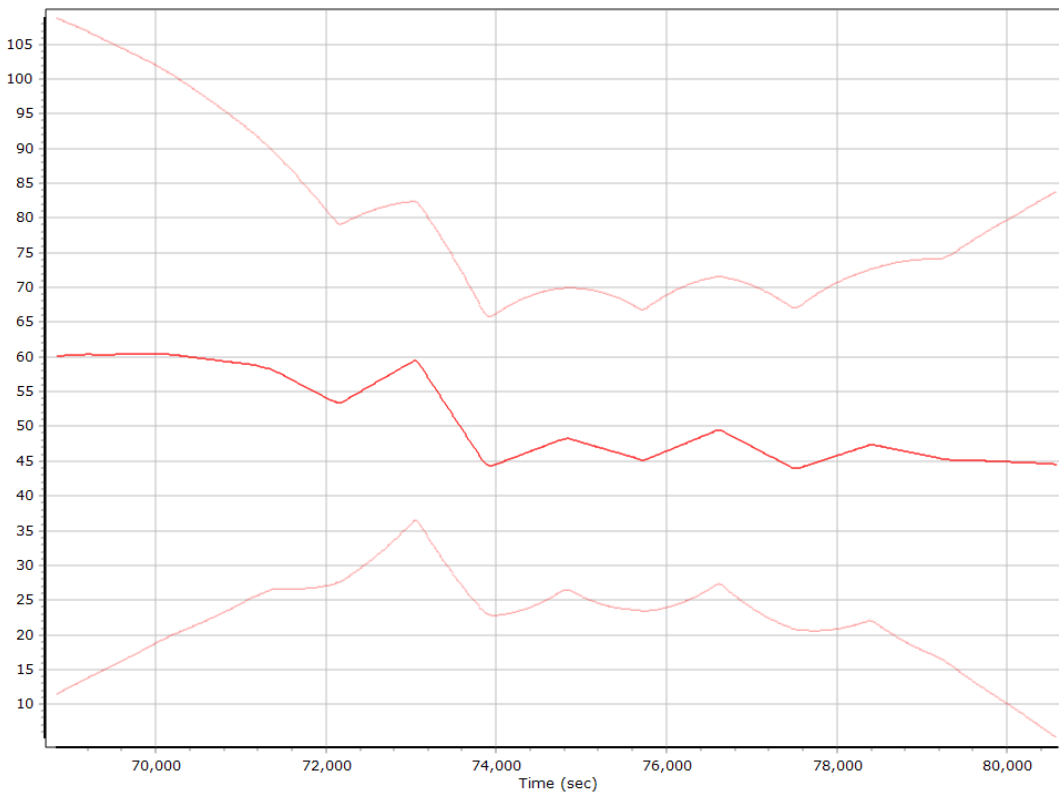
X Gyro Scale Error (ppm)



Y Gyro Scale Error (ppm)

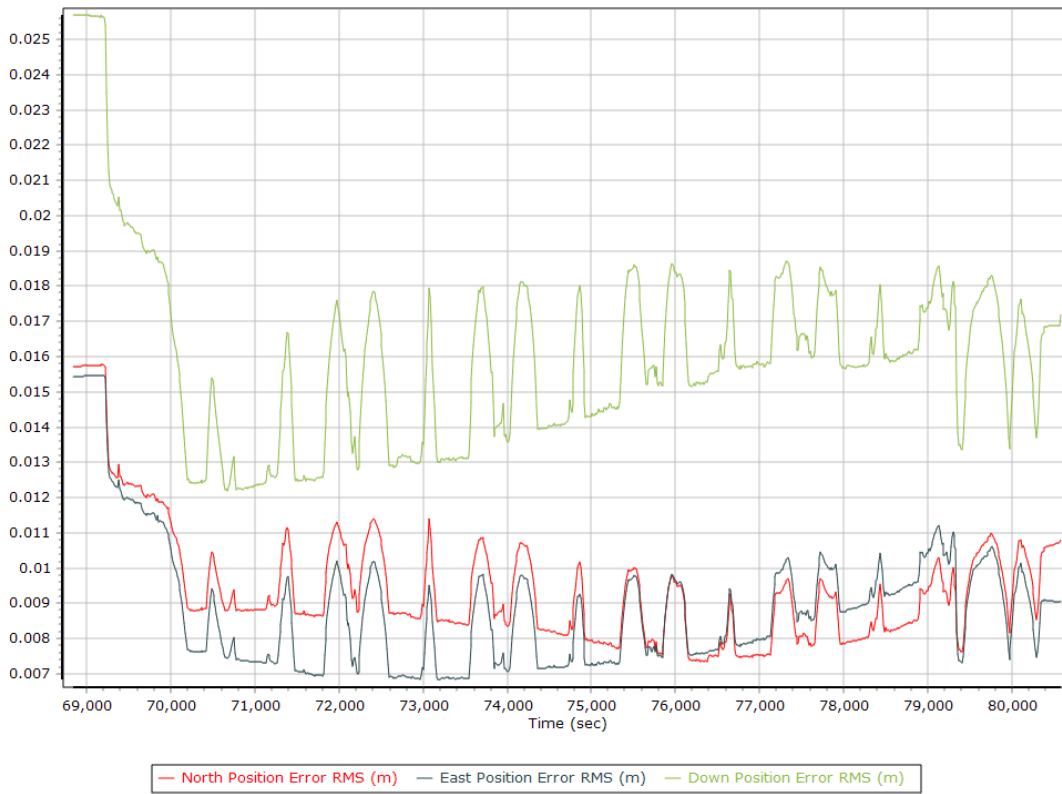


Z Gyro Scale Error (ppm)

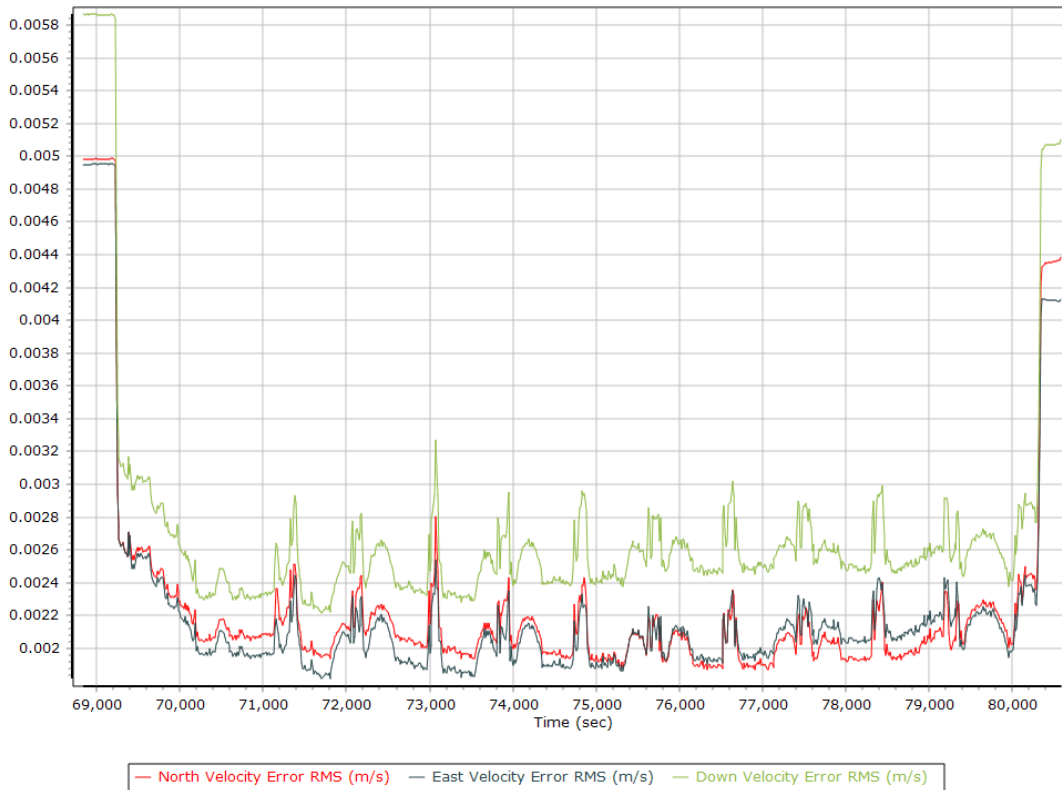


Smoothed Performance Metrics

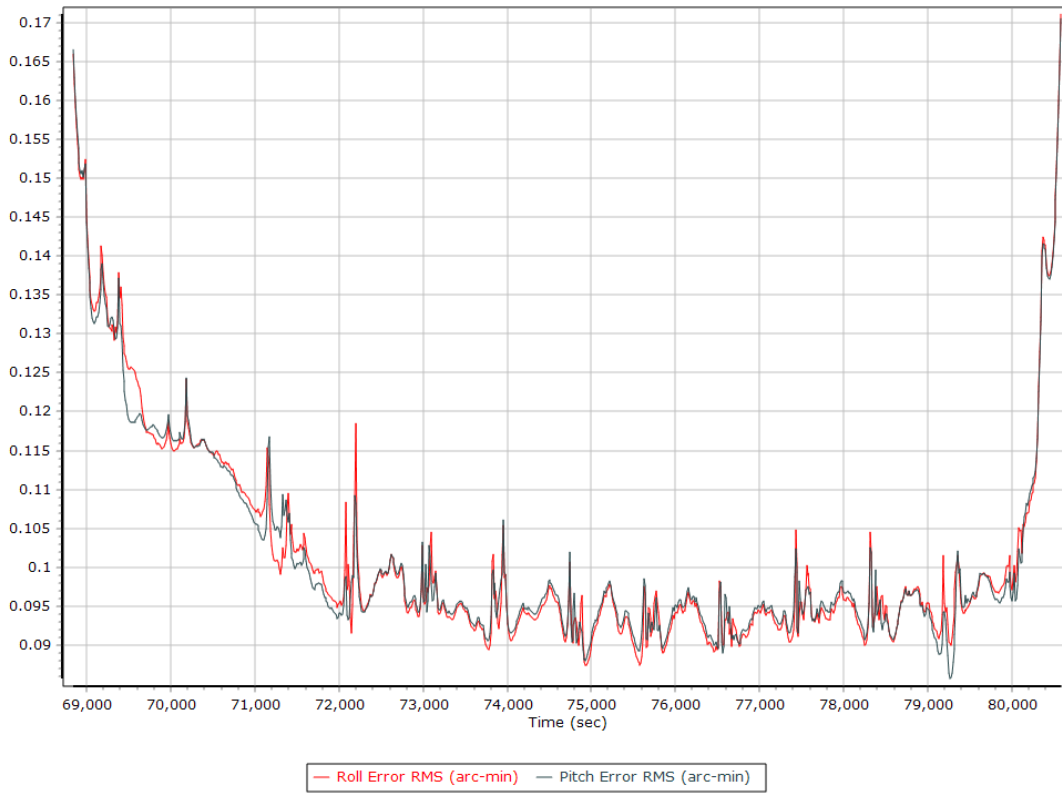
Position Error RMS (m)



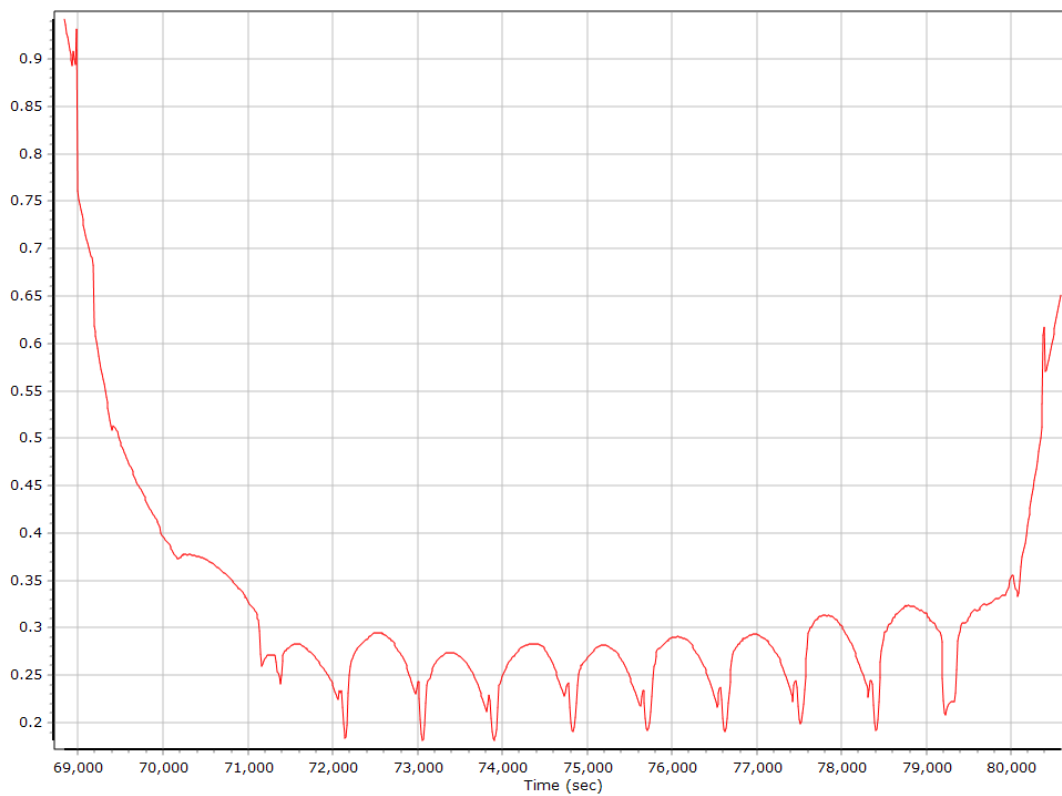
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

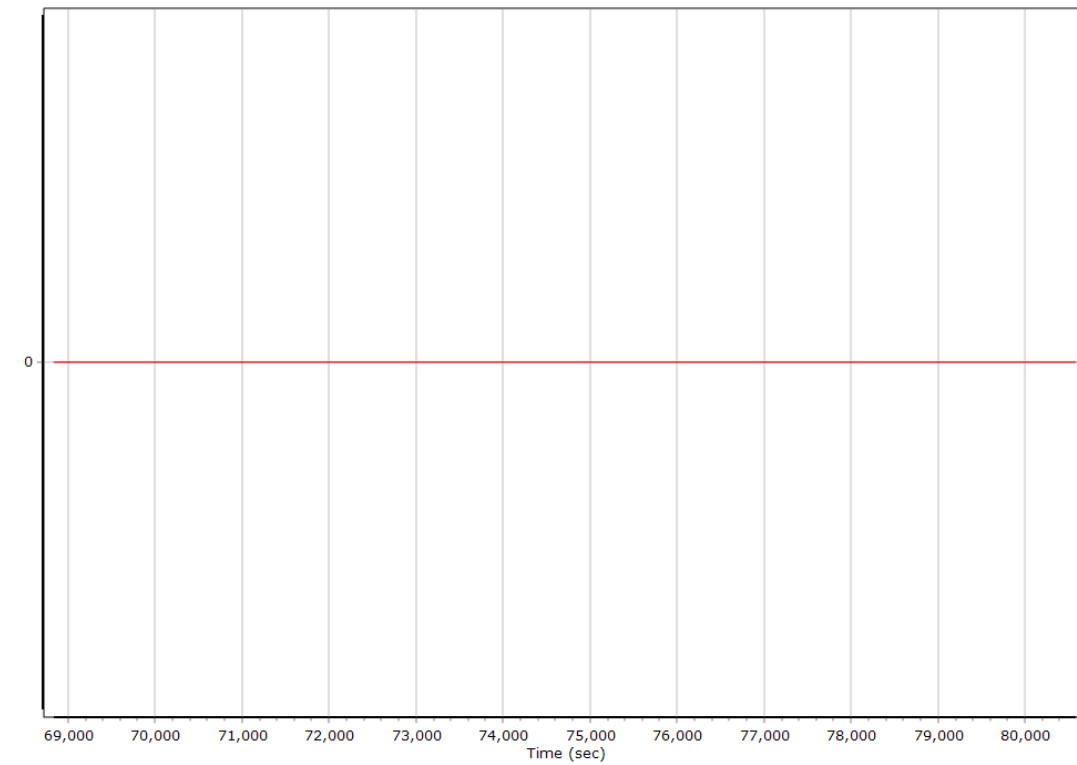


Heading Error RMS (arc-min)



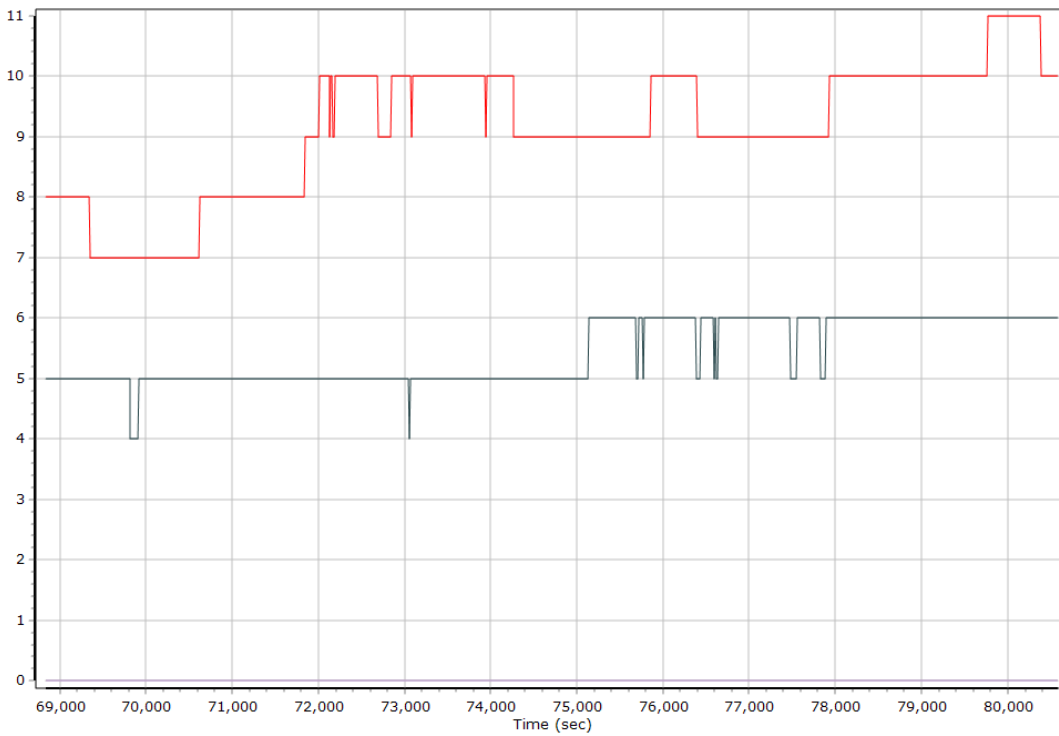
Smoothed Solution Status

Processing Mode



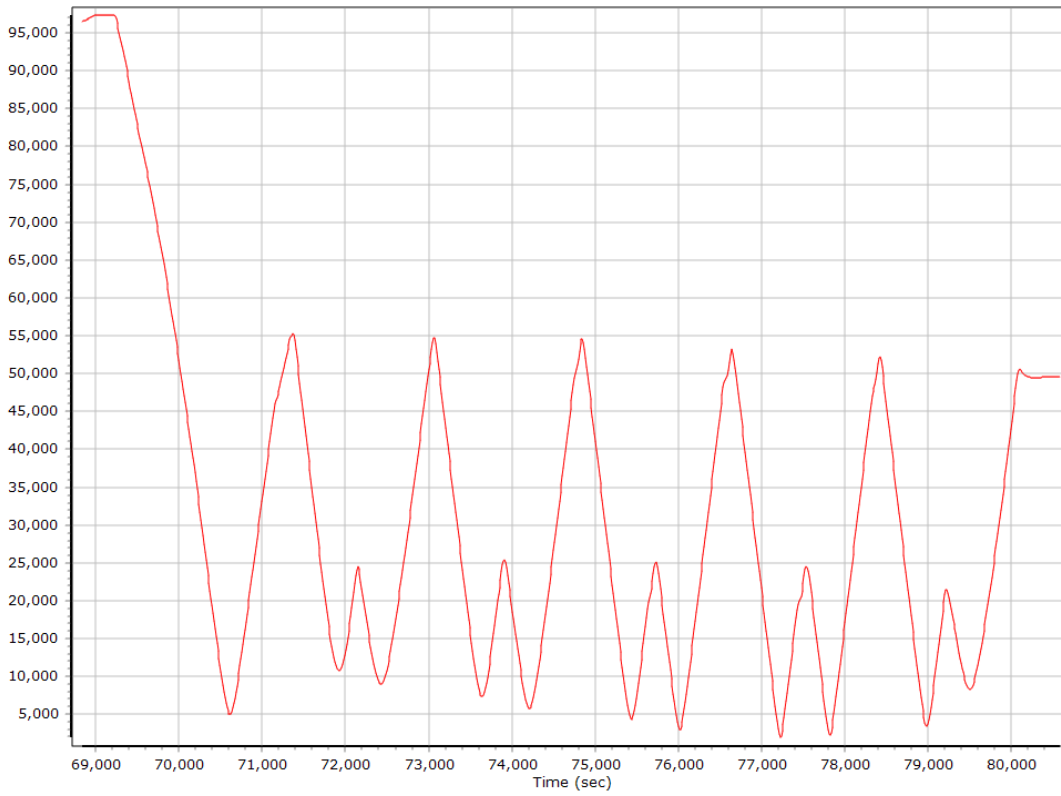
0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = C/A, 7 = GNSS Nav, 8 = DR

Number of Satellites



— Number of GPS Satellites — Number of GLONASS Satellites — Number of QZSS Satellites — Number of BEIDOU Satellites

Baseline Length



SBET IAKAR Separation

