

## General Information

### Mission Information

Project name	13284-1805_20181114
Processing date	2018-11-15 16:45:24
Mission date	2018-11-14 19:32:20
Mission duration	01:47:44.000
Processing mode	IN-Fusion SmartBase
GPS Station	ASB

### Rover Hardware Information

Product	POS AV 610 VER6 HW2.5-12
Serial number	S/N9865
IMU type	57
Receiver type	BD982
Antenna type	AV37

## Project File List

### Rover Data Files

File name	File type
181114_193201_INS-GPS_1.raw	POS Data

### Input Files

File Name	File type
Ephm3180.18g	GLONASS Broadcast Ephemeris
Ephm3180.18n	GPS Broadcast Ephemeris
ls083180.18o	GNSS SingleBase
PAGW318A.18o	GNSS SingleBase
WVBR318A.18o	GNSS SingleBase
WVCV318A.18o	GNSS SingleBase
WVFL318A.18o	GNSS SingleBase
WVGB318A.18o	GNSS SingleBase
WVHA318A.18o	GNSS SingleBase
WVNR318A.18o	GNSS SingleBase
WVTA318A.18o	GNSS SingleBase
PAGW318A.18g	GLONASS Broadcast Ephemeris
PAGW318A.18n	GPS Broadcast Ephemeris
WVBR318A.18g	GLONASS Broadcast Ephemeris
WVBR318A.18n	GPS Broadcast Ephemeris
WVCV318A.18g	GLONASS Broadcast Ephemeris
WVCV318A.18n	GPS Broadcast Ephemeris
WVFL318A.18g	GLONASS Broadcast Ephemeris
WVFL318A.18n	GPS Broadcast Ephemeris
WVGB318A.18g	GLONASS Broadcast Ephemeris
WVGB318A.18n	GPS Broadcast Ephemeris
WVHA318A.18g	GLONASS Broadcast Ephemeris
WVHA318A.18n	GPS Broadcast Ephemeris
WVNR318A.18g	GLONASS Broadcast Ephemeris
WVNR318A.18n	GPS Broadcast Ephemeris
WVTA318A.18g	GLONASS Broadcast Ephemeris
WVTA318A.18n	GPS Broadcast Ephemeris
igu20272_00.sp3	GPS Precise Ephemeris
igu20272_06.sp3	GPS Precise Ephemeris
igu20272_12.sp3	GPS Precise Ephemeris
igu20272_18.sp3	GPS Precise Ephemeris
igu20273_00.sp3	GPS Precise Ephemeris
igu20273_06.sp3	GPS Precise Ephemeris
igu20273_12.sp3	GPS Precise Ephemeris
igu20273_18.sp3	GPS Precise Ephemeris
igu20274_00.sp3	GPS Precise Ephemeris
igu20274_06.sp3	GPS Precise Ephemeris
igu20274_12.sp3	GPS Precise Ephemeris

### Output Files

Filename	File type
sbet_Mission 1.out	SBET Trajectory File

## Rover Data Summary

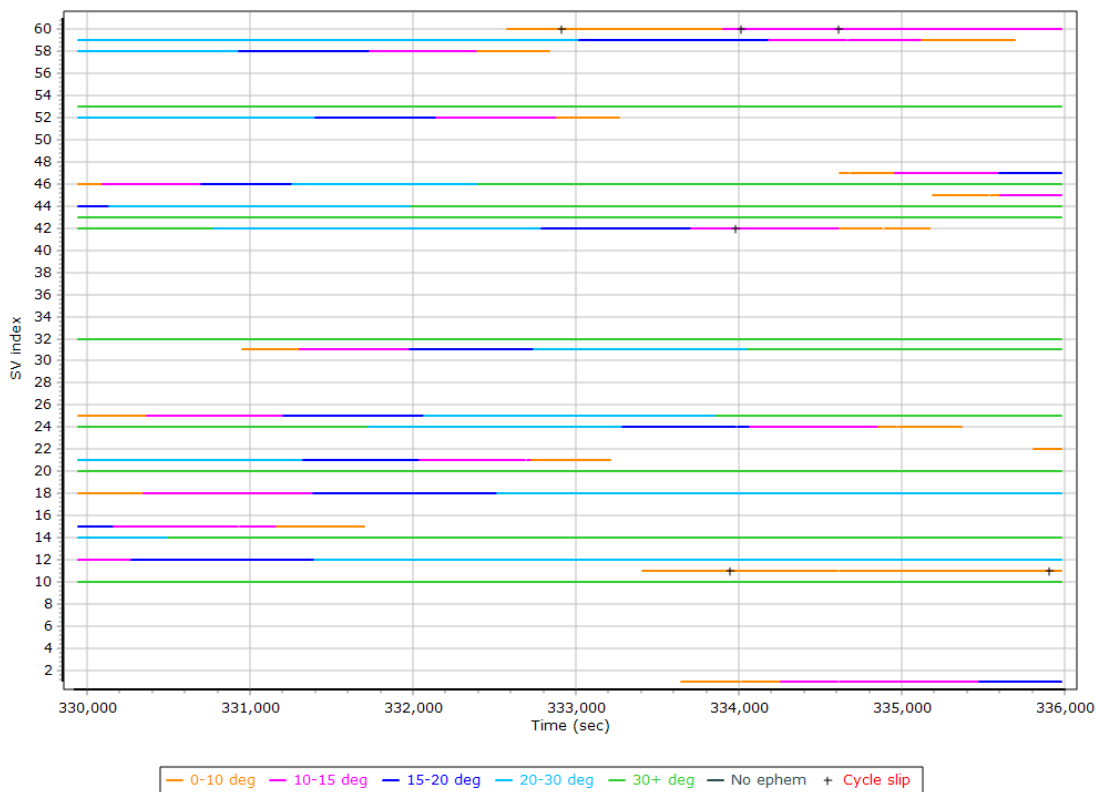
First raw data file	181114_193201_INS-GPS_1.raw		
Last raw data file	181114_193201_INS-GPS_1.raw		
Start GPS week	2027		
Start time	329521.977 (11/14/2018 7:32:01 PM)		
End time	335985.536 (11/14/2018 9:19:45 PM)		
Start of fine alignment	329886.473 (11/14/2018 7:38:06 PM)		
Available subsystems	Primary GNSS, Gimbal, IMU		
POS Event Input	Event 1 Input, Event 2 Input, Event 3 Input, Event 4 Input, Event 5 Input, Event 6 Input		
Correction data	None		
<b>IMU Installation Lever Arms &amp; Mounting Angles</b>			
Gimbal to IMU lever arm [m]	0.000	0.000	0.000
Gimbal to IMU mounting angles [deg]	0.000	0.000	0.000
Gimbal to Primary GNSS lever arm [m]	0.000	0.000	0.000
Gimbal to Primary GNSS lever arm std dev [m]	-1.000		
Aircraft to Reference mounting angles [deg]	0.000	0.000	0.000

# Raw Data QC

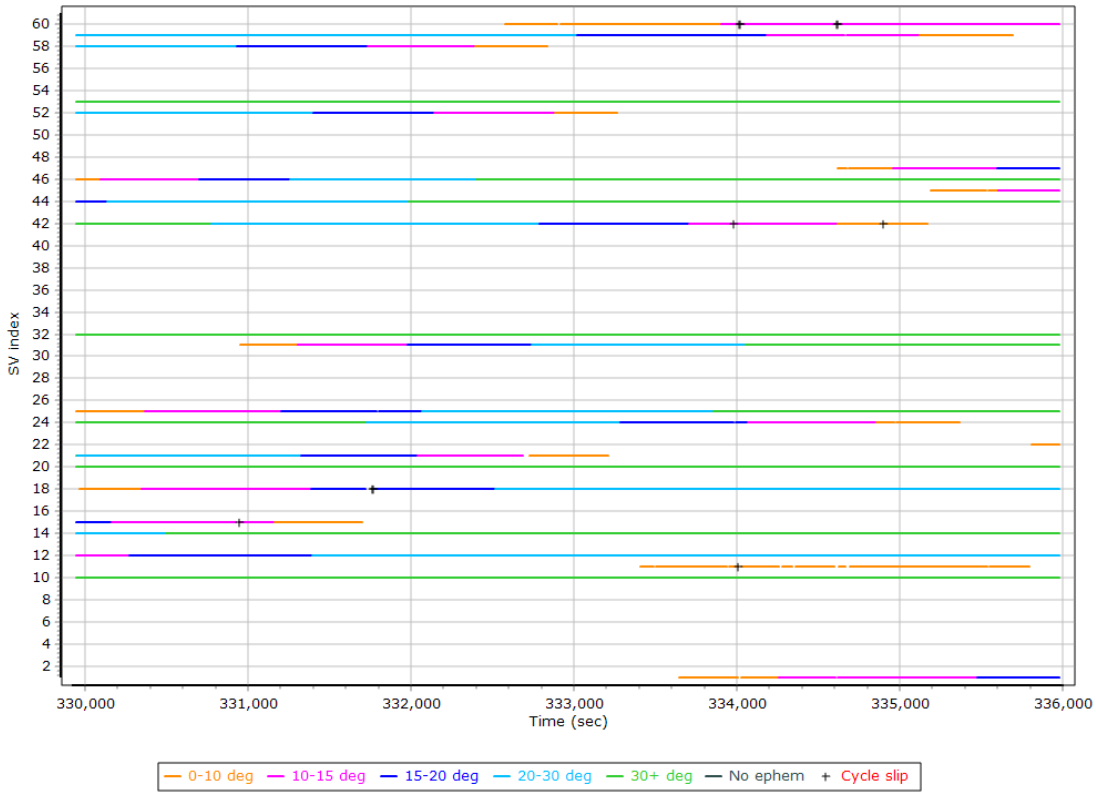
## Raw IMU Import QC Summary

IMU data input file	imu_Mission 1.dat
IMU data check log file	imudt_Mission 1.log
IMU Records Processed	1292554
Termination Status	Normal
IMU Anomalies	0

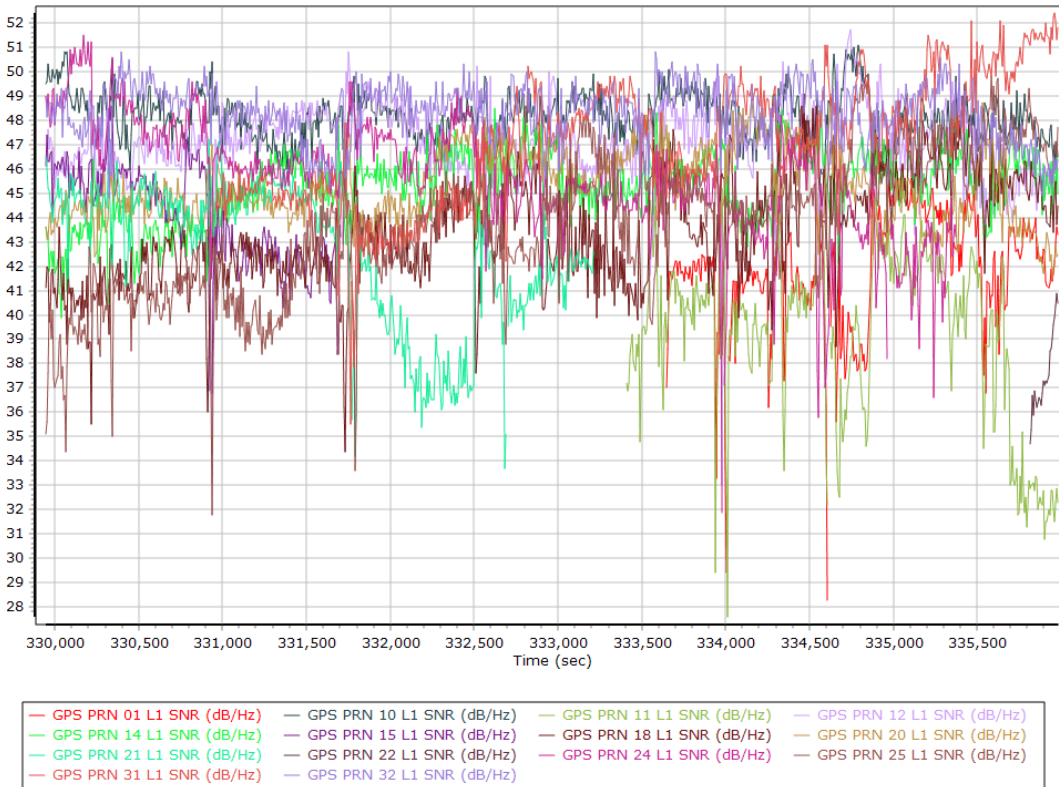
### L1 Satellite Lock/Elevation



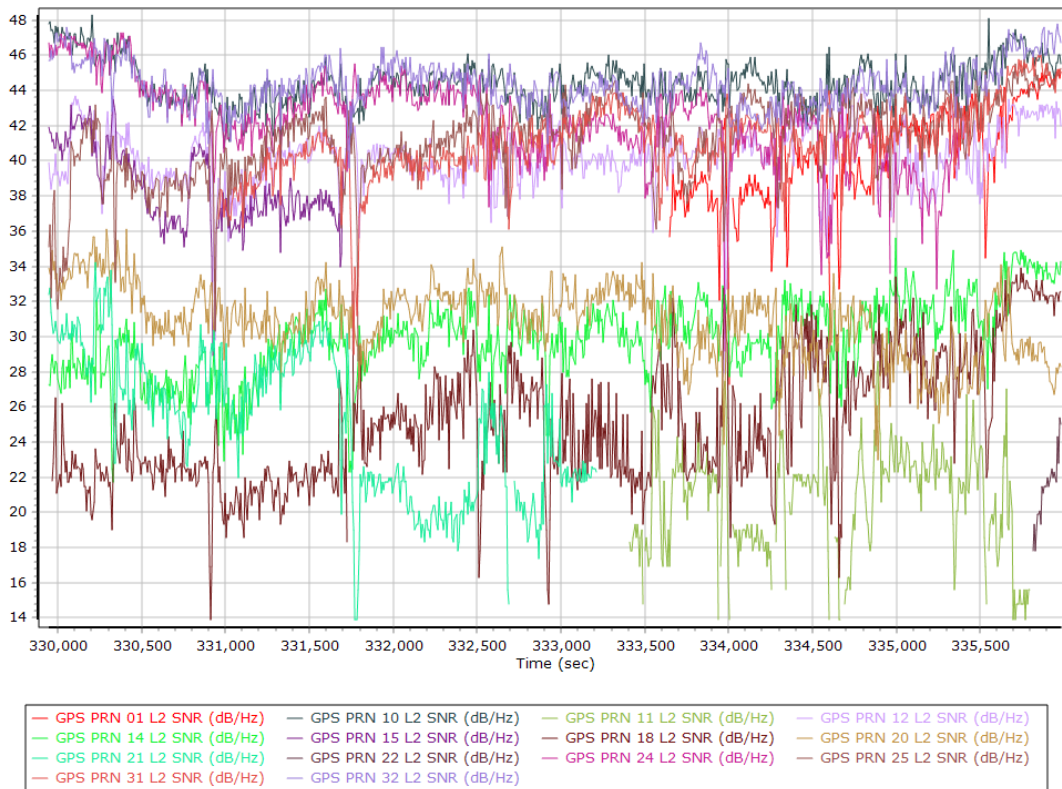
## L2 Satellite Lock/Elevation



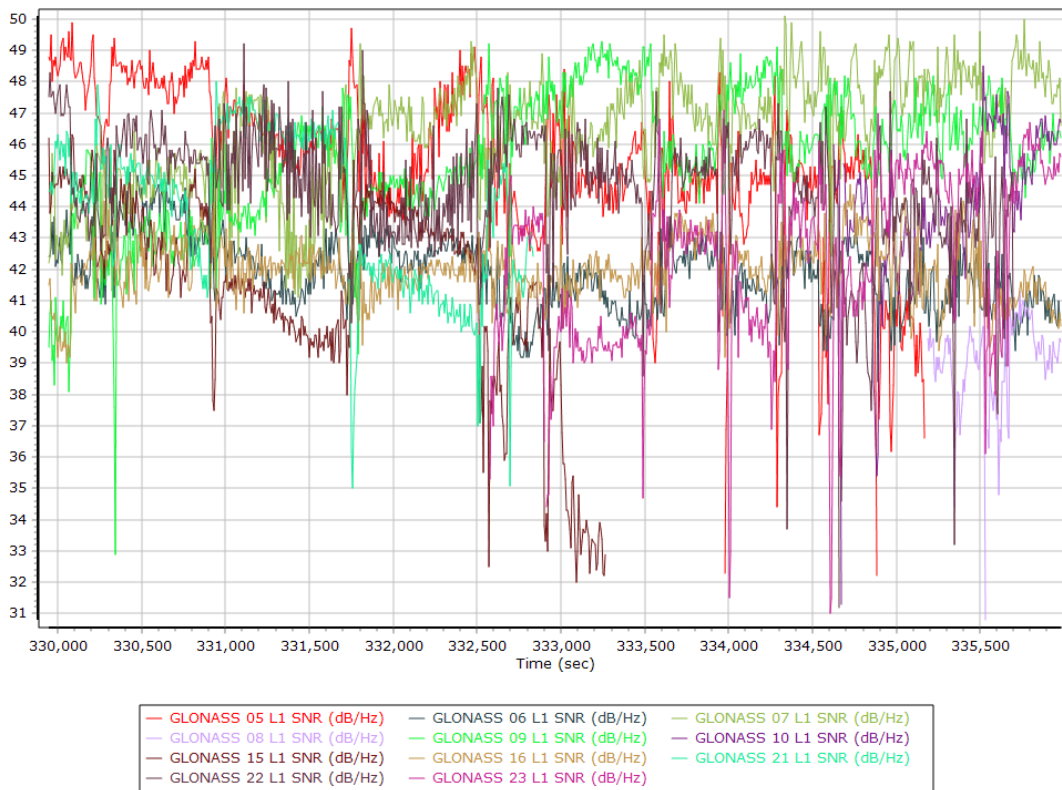
## GPS L1 SNR



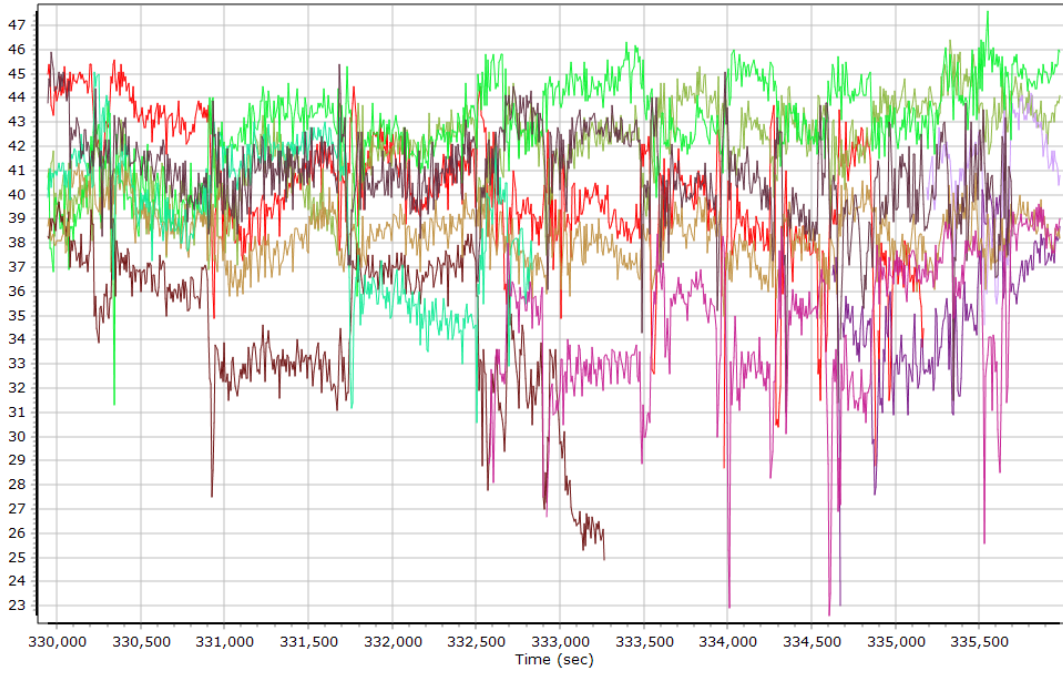
### GPS L2 SNR



### GLONASS L1 SNR

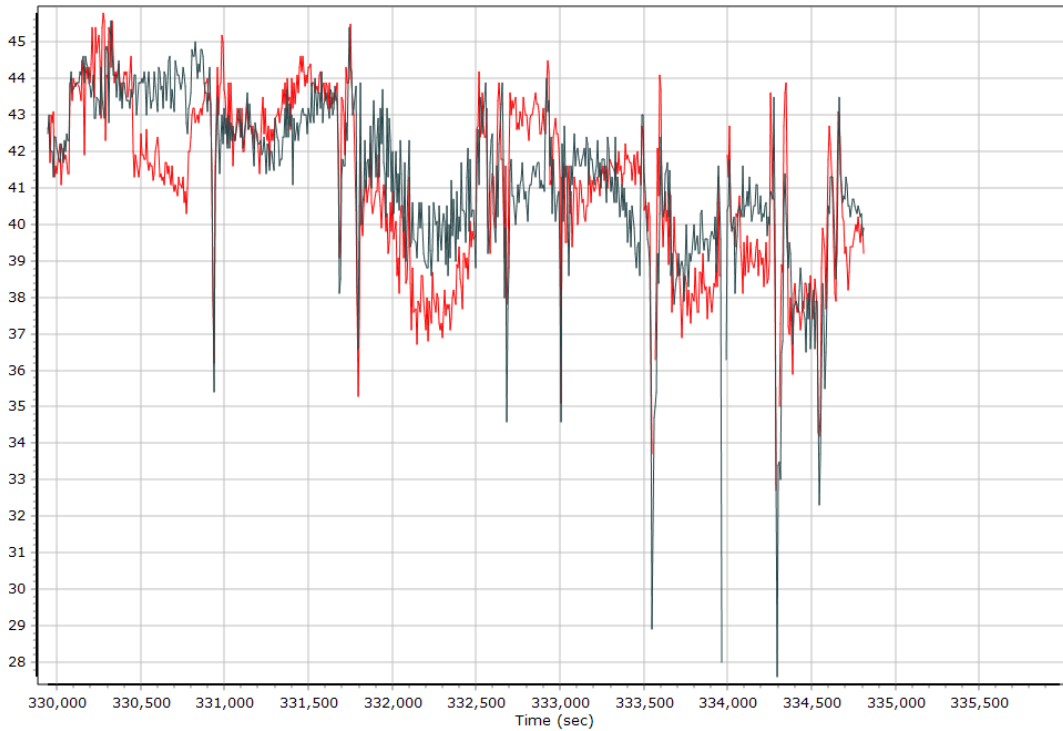


### GLONASS L2 SNR



- GLONASS 05 L2 SNR (dB/Hz)
- GLONASS 06 L2 SNR (dB/Hz)
- GLONASS 07 L2 SNR (dB/Hz)
- GLONASS 08 L2 SNR (dB/Hz)
- GLONASS 09 L2 SNR (dB/Hz)
- GLONASS 10 L2 SNR (dB/Hz)
- GLONASS 15 L2 SNR (dB/Hz)
- GLONASS 16 L2 SNR (dB/Hz)
- GLONASS 21 L2 SNR (dB/Hz)
- GLONASS 22 L2 SNR (dB/Hz)
- GLONASS 23 L2 SNR (dB/Hz)

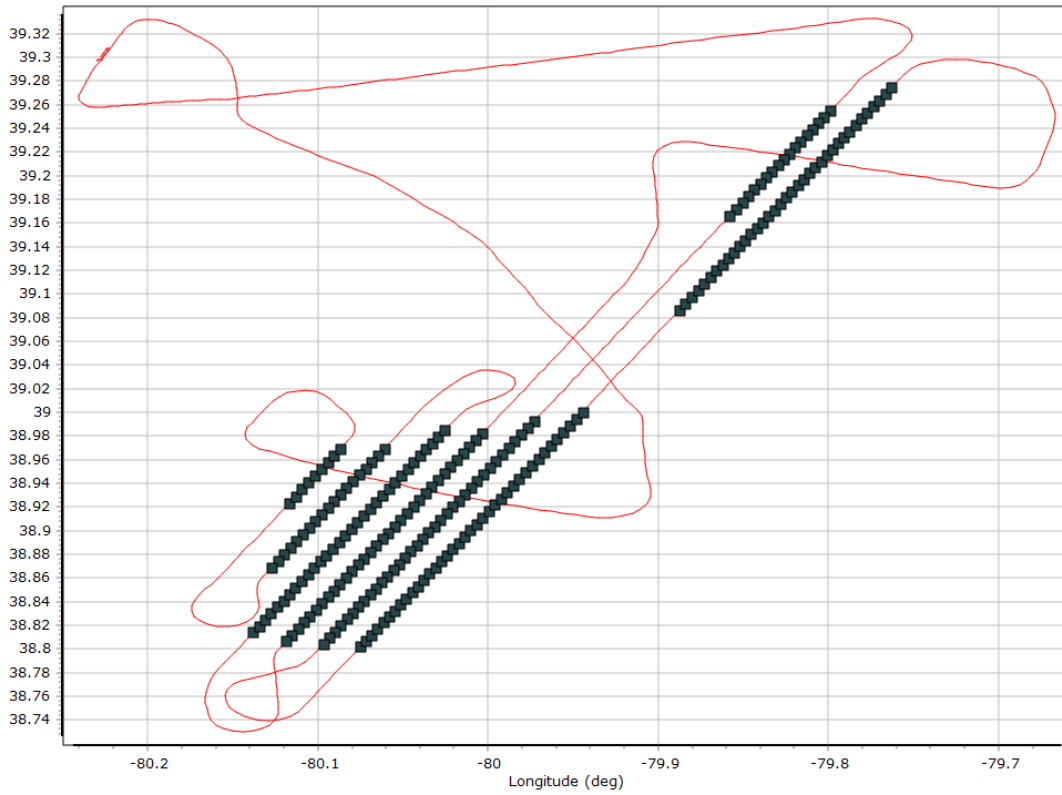
### BEIDOU SNR



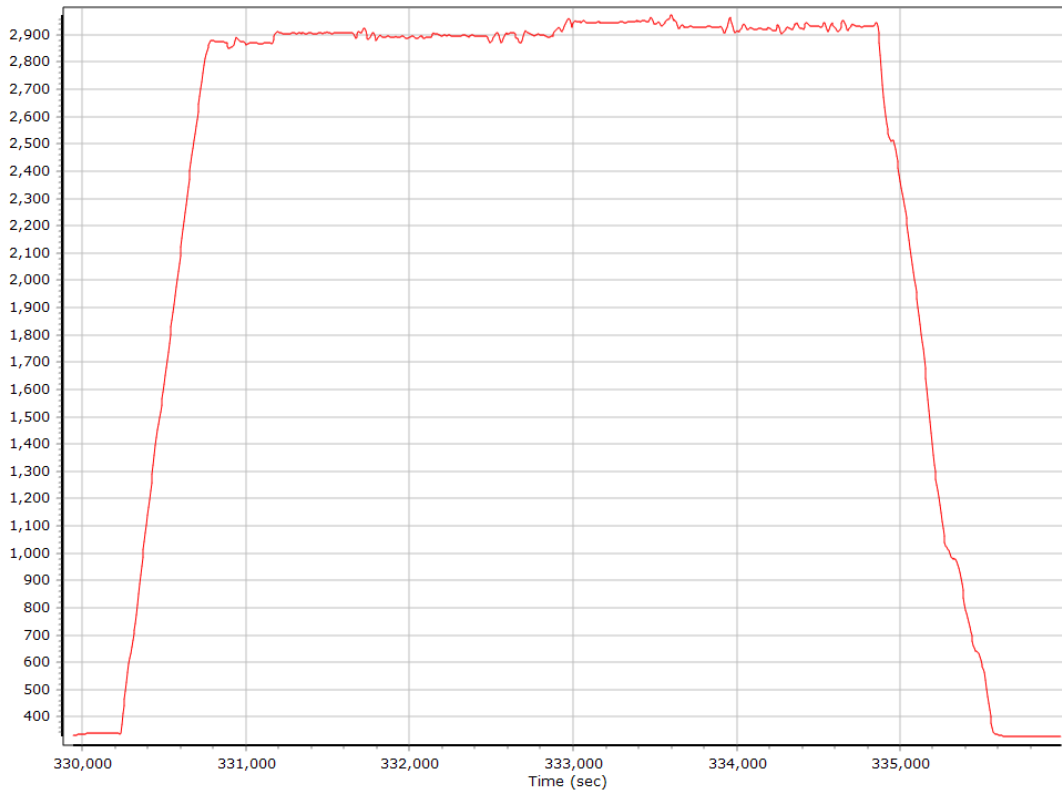
- BEIDOU 14 E5B B2 SNR (dB/Hz)
- BEIDOU 14 B1 B1 SNR (dB/Hz)

## Trajectory Information

### Top View

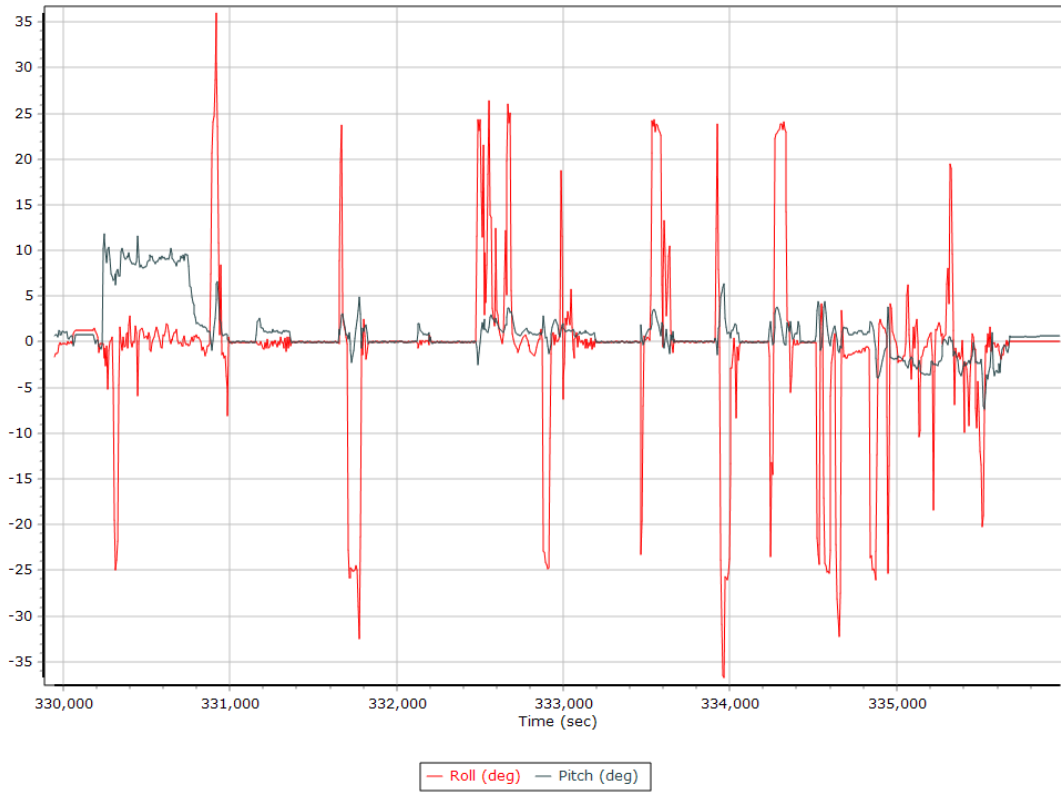


### Altitude

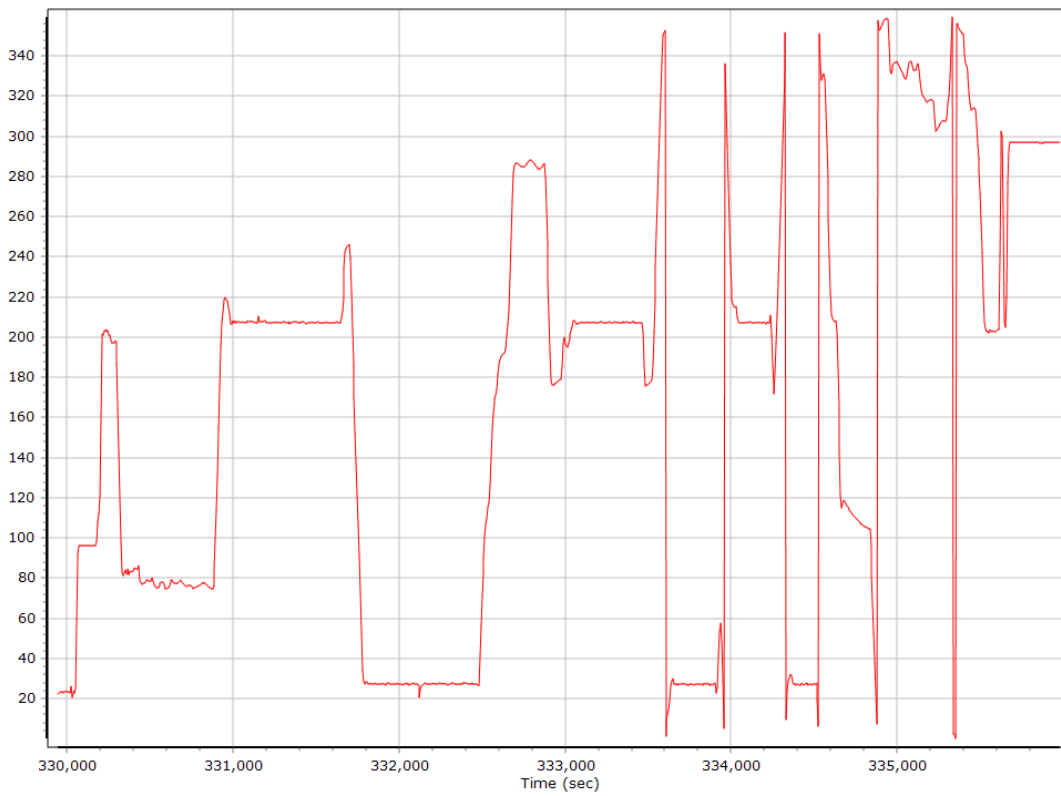




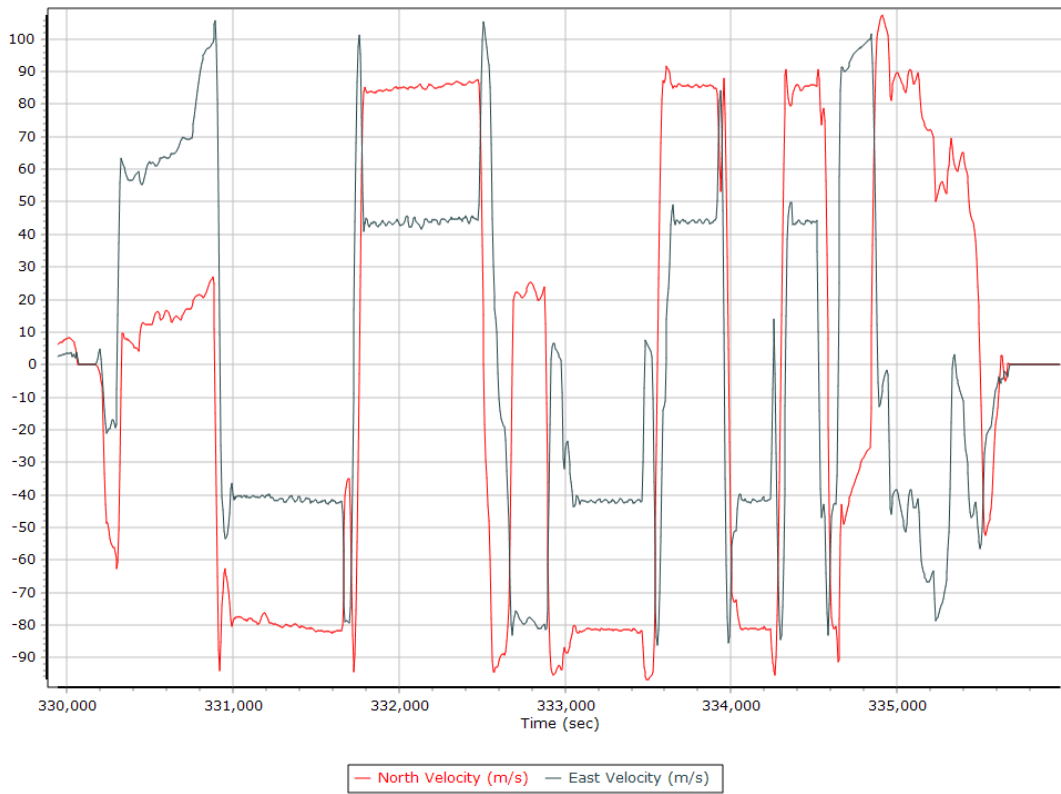
## Roll/Pitch



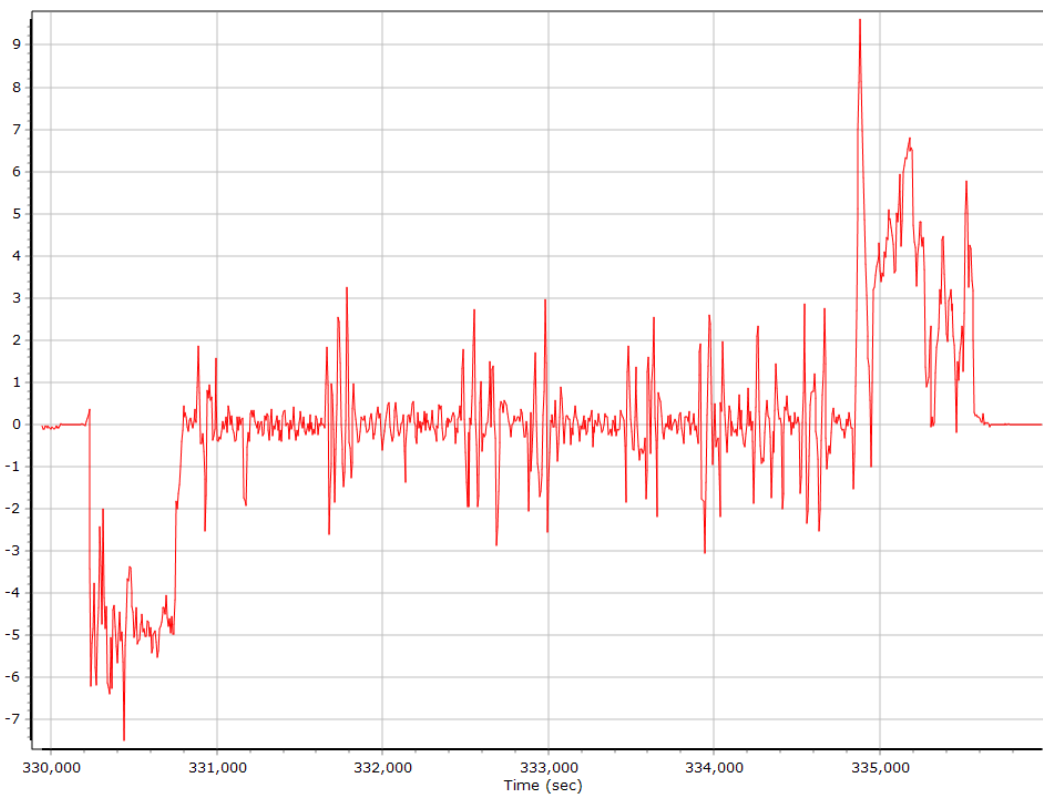
## Heading



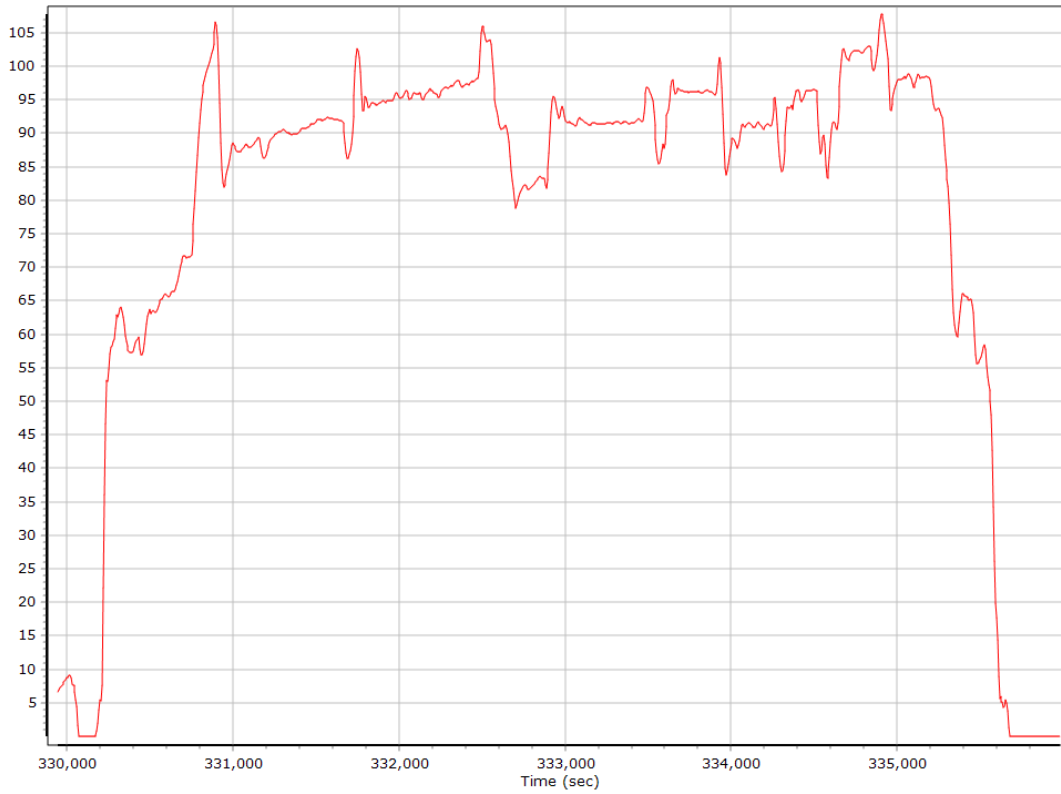
## North/East Velocity



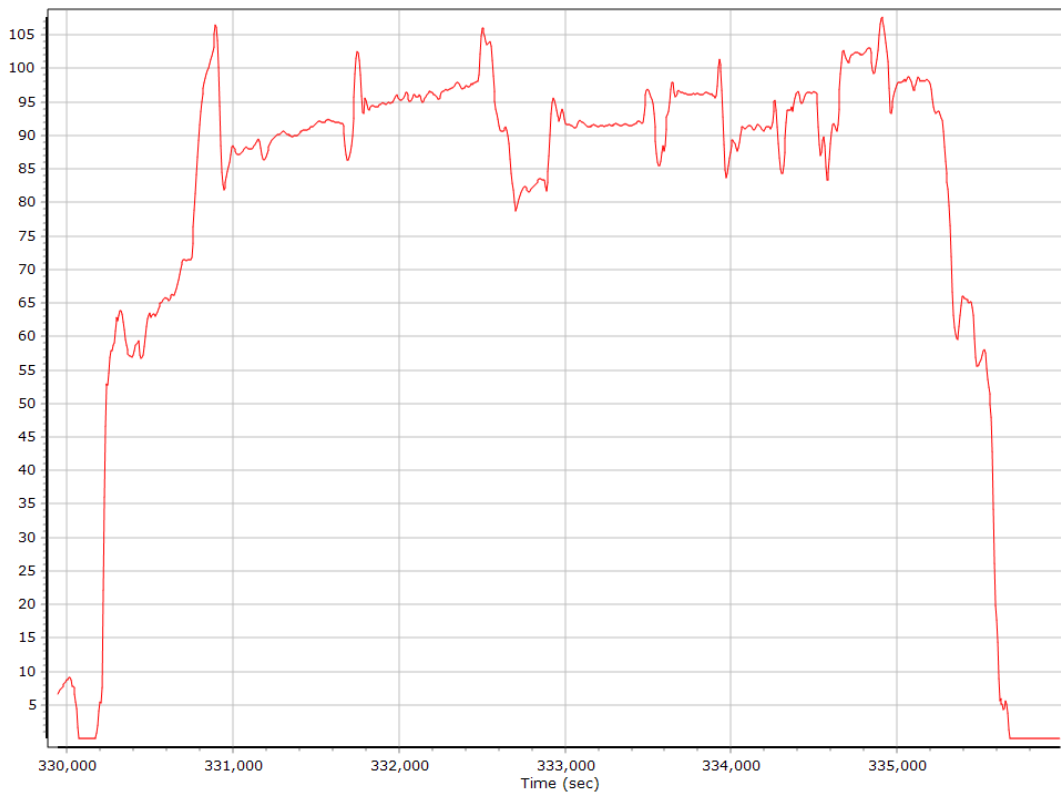
## Down Velocity



## Total Speed



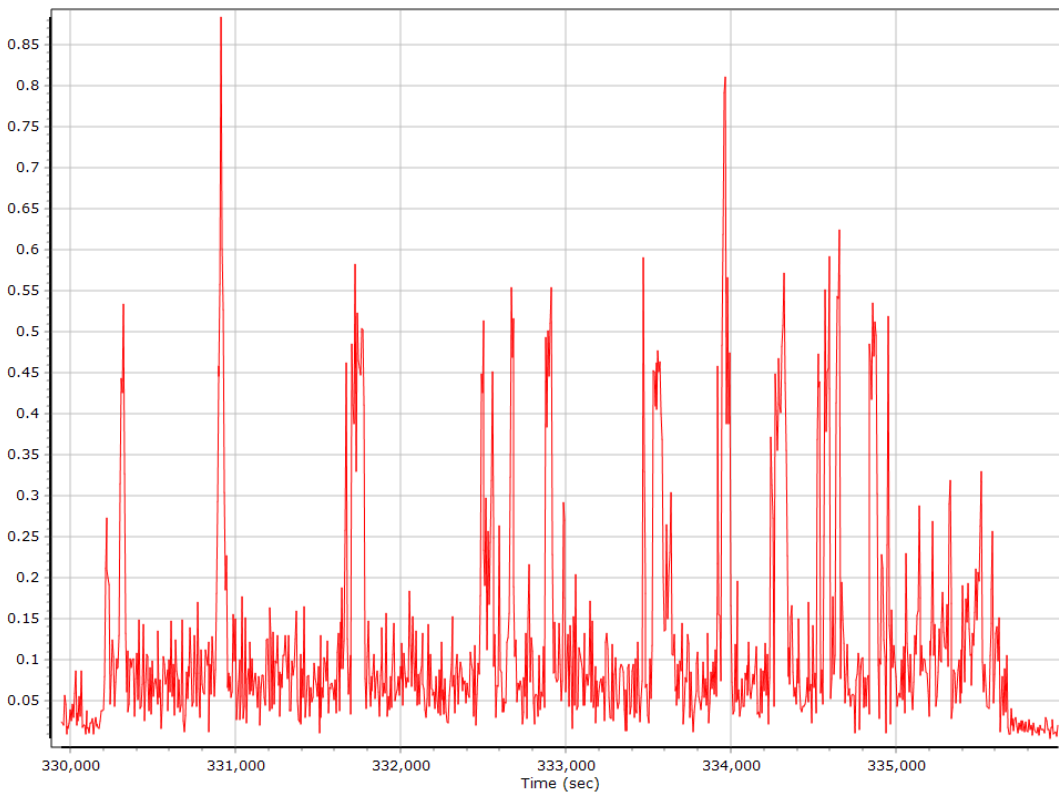
## Ground Speed



## Body Acceleration



## Total Body Acceleration



## Body Angular Rate



## SmartBase Processing Summary

### Smart Select Options

Archive enabled	False
User database enabled	False
Include high-rate data sites	False
Target GNSS Selection	GNSS

### Basestation Selection

Date	ID	Dist	Data Type	Rate	Service	Database	Status
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### SmartBase Results

SmartBase status	
Primary station Id	
Primary station data rate [sec]	0.0
VRS/ASB generation rate [sec]	0.0
VRS/ASB timespan	
Number of reference stations	0
Primary station GPS measurement usage [%]	0.0
Average number of satellites per epoch	0.0
Max number of GPS stations used	0
Min number of GPS stations used	0
Total full data gap [sec]	0
Total individual satellite data gap [sec]	0
GPS precise vs. broadcast ephemeris used	0.0 % / 0.0 %
Termination Status	

## **SmartBase Quality Check**

## GNSS QC

### GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length [km]	5.13	42.27	
Number of GPS SV	6	10	9
Number of GLONASS SV	0	6	5
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	0	0
Total number of SV	7	16	14
PDOP	1.27	2.35	1.45
QC Solution Gaps	1.00	1.00	
Solution Type	Fixed	Float	No solution
Epoch (s)	6426.00	0.00	1.00
Percentage	99.98	0.00	0.02



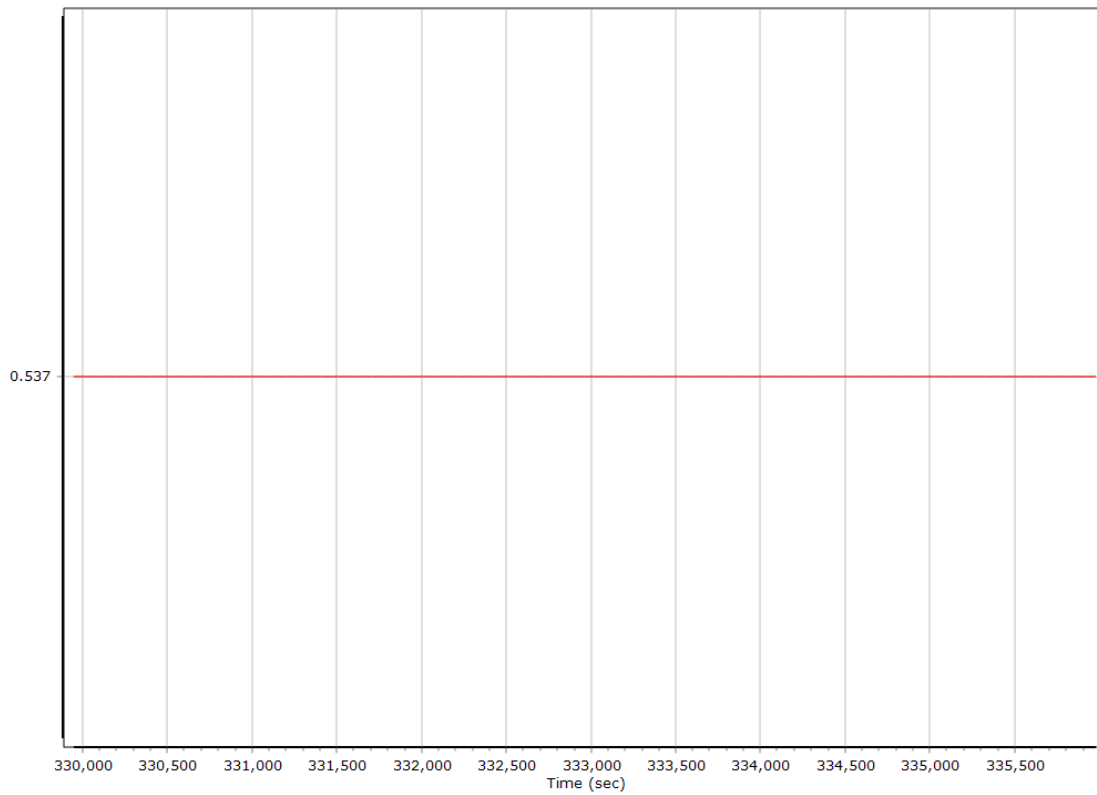
## GNSS-Inertial Processor Configuration

Processing mode	IN-Fusion SmartBase		
Stabilized mount	True		
Base station	ASB		
Processing start time	329522.000 (11/14/2018 7:32:02 PM)		
Processing end time	335986.000 (11/14/2018 9:19:46 PM)		
Initial attitude source	Real-Time VNAV/RNAV Attitude		
IMU Sensor Context	Processing with Onboard IMU		
Gimbal to IMU lever arm [m]	0.000	0.000	0.000
Gimbal to IMU mounting angles [deg]	0.000	0.000	0.000
Gimbal to Primary GNSS lever arm [m]	0.537	-0.083	-0.916
Gimbal to Primary GNSS lever arm std dev [m]	0.030	0.030	0.030
Aircraft to Reference mounting angles [deg]	0.000	0.000	0.000

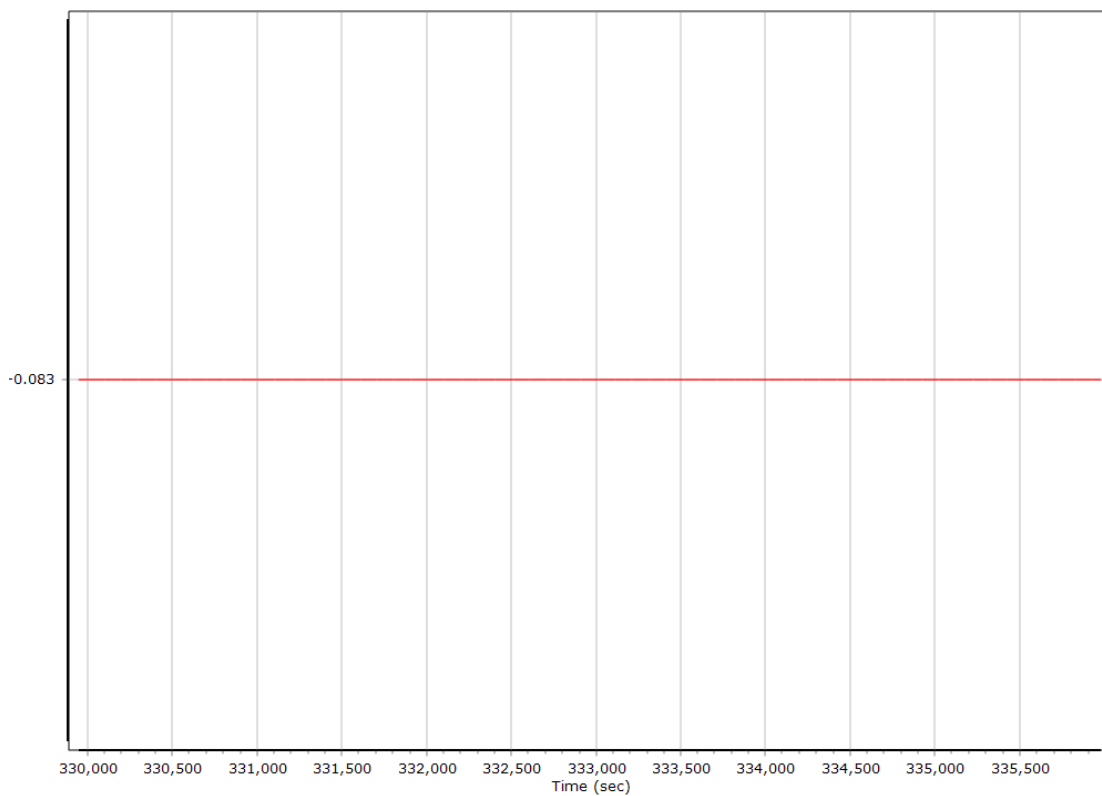
## Calibrated Installation Parameters

### Reference-Primary GNSS Lever Arm

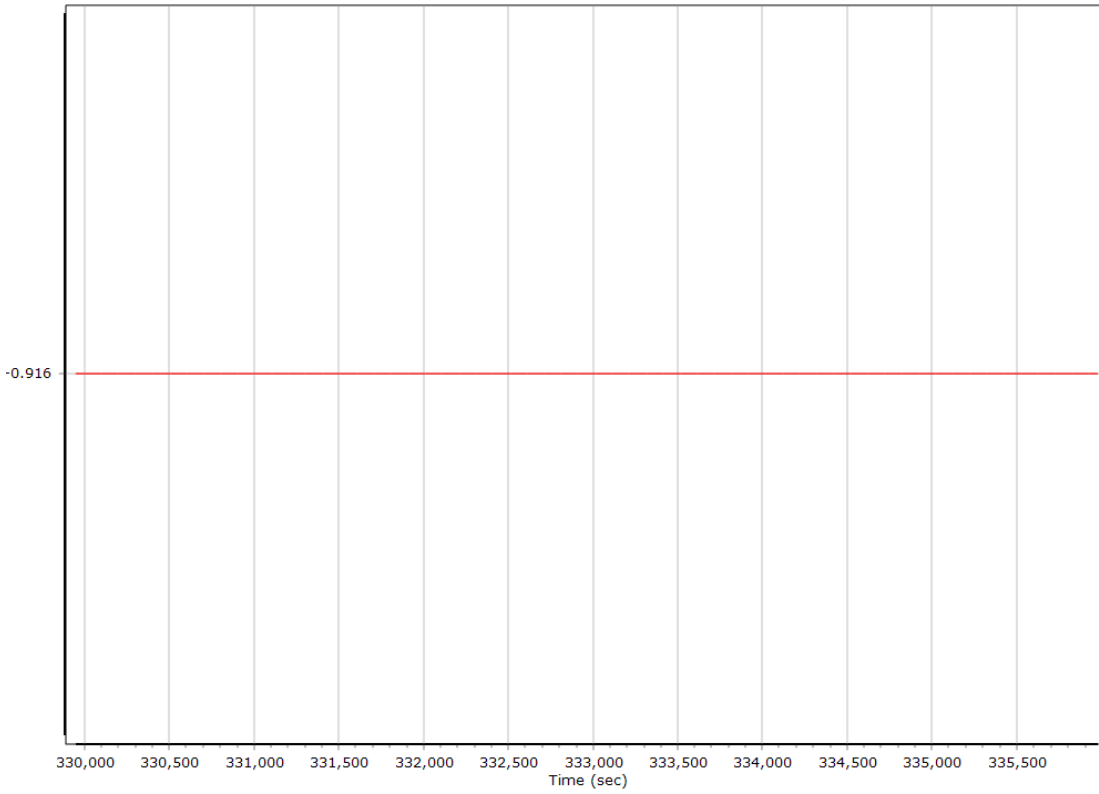
#### X Reference-Primary GNSS Lever Arm (m)



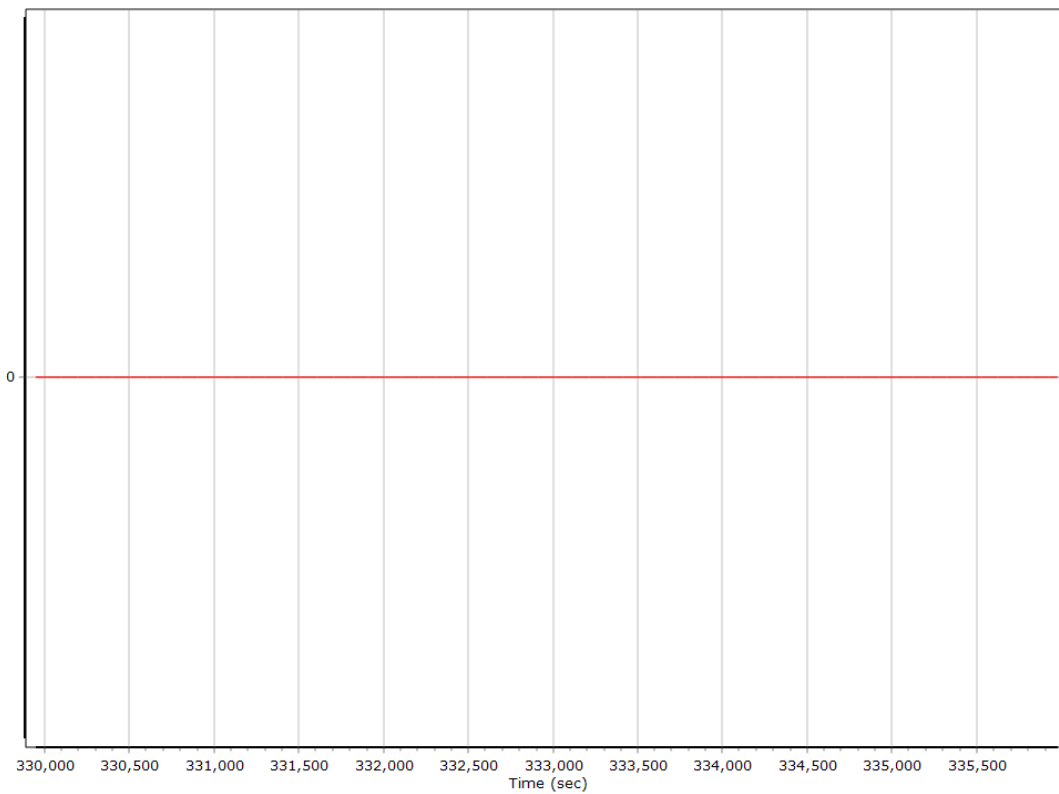
#### Y Reference-Primary GNSS Lever Arm (m)



### Z Reference-Primary GNSS Lever Arm (m)



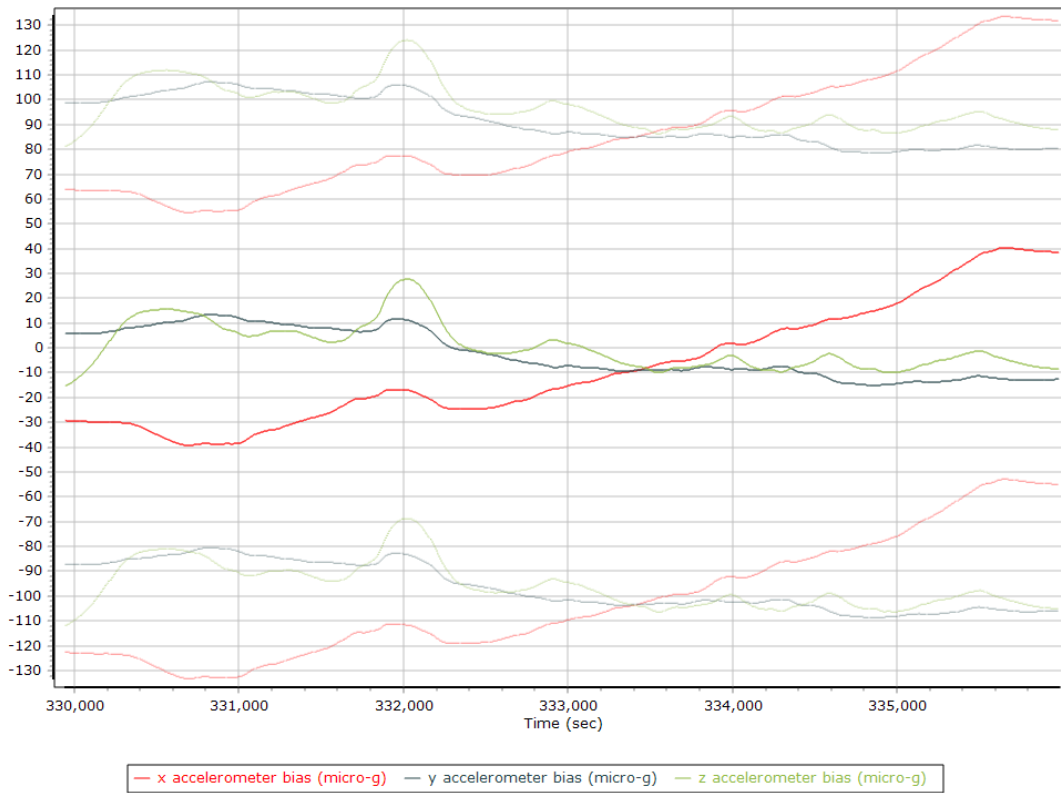
### Reference-Primary GNSS Lever Arm Figure of Merit



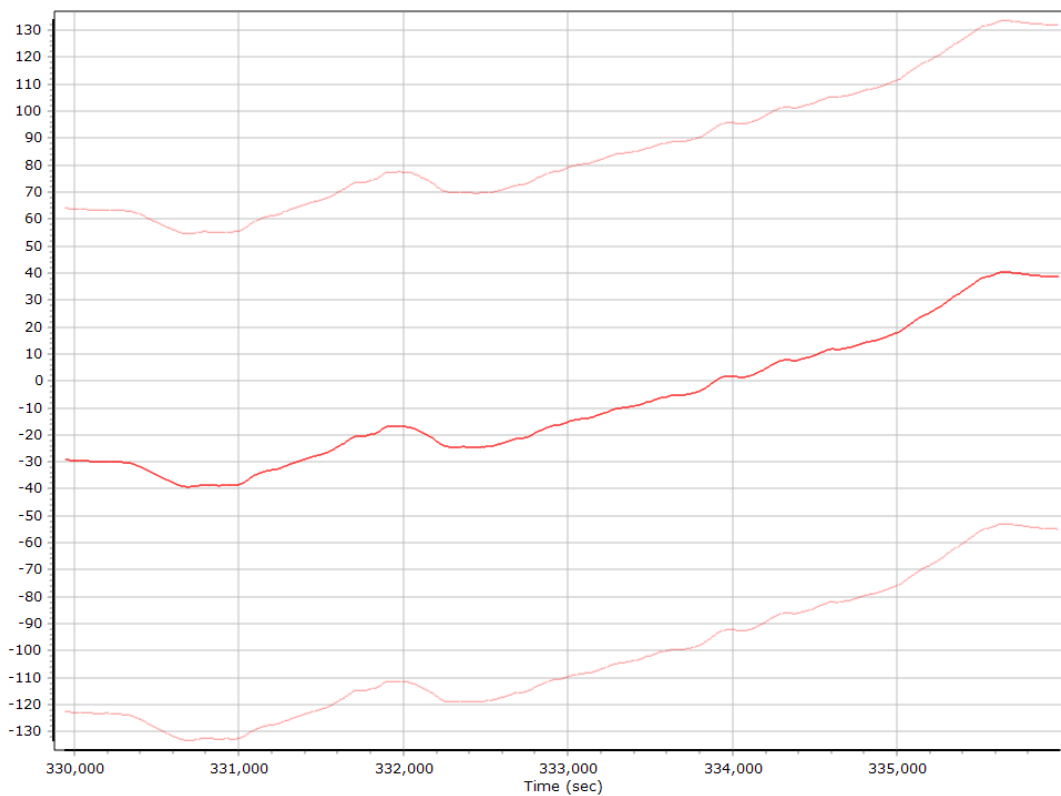
## Smoothed IN-Fusion QC

### Smoothed Estimated Errors, Reference Frame

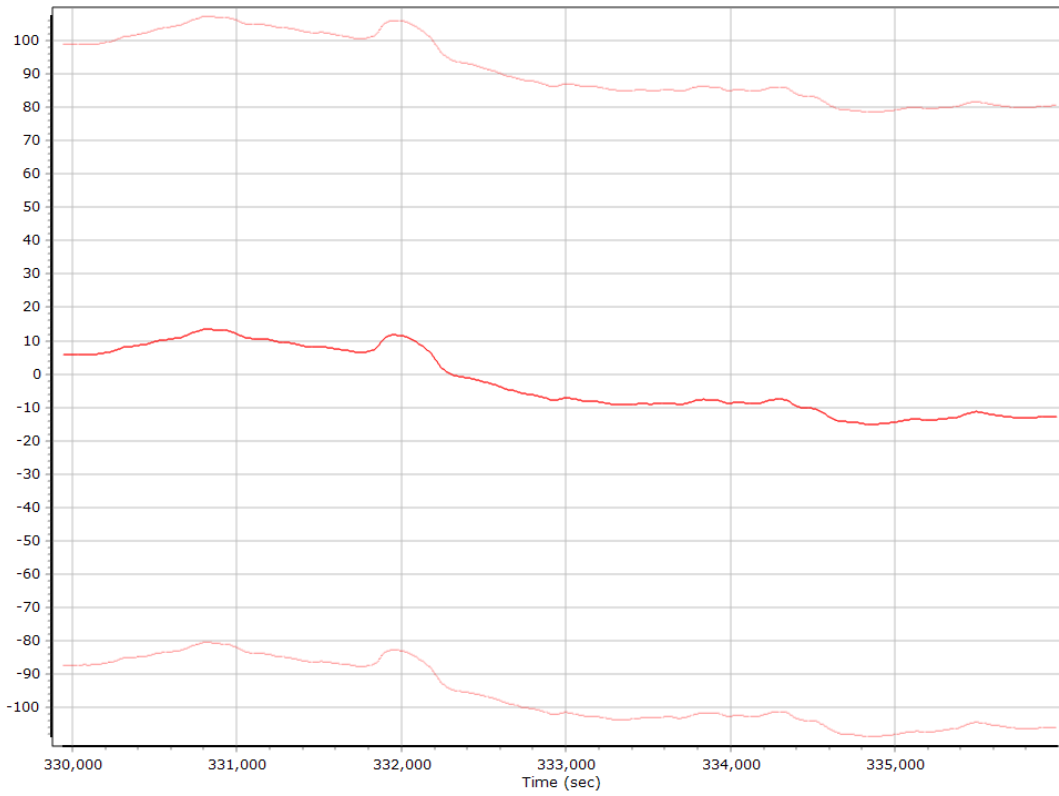
#### Accelerometer Bias (micro-g)



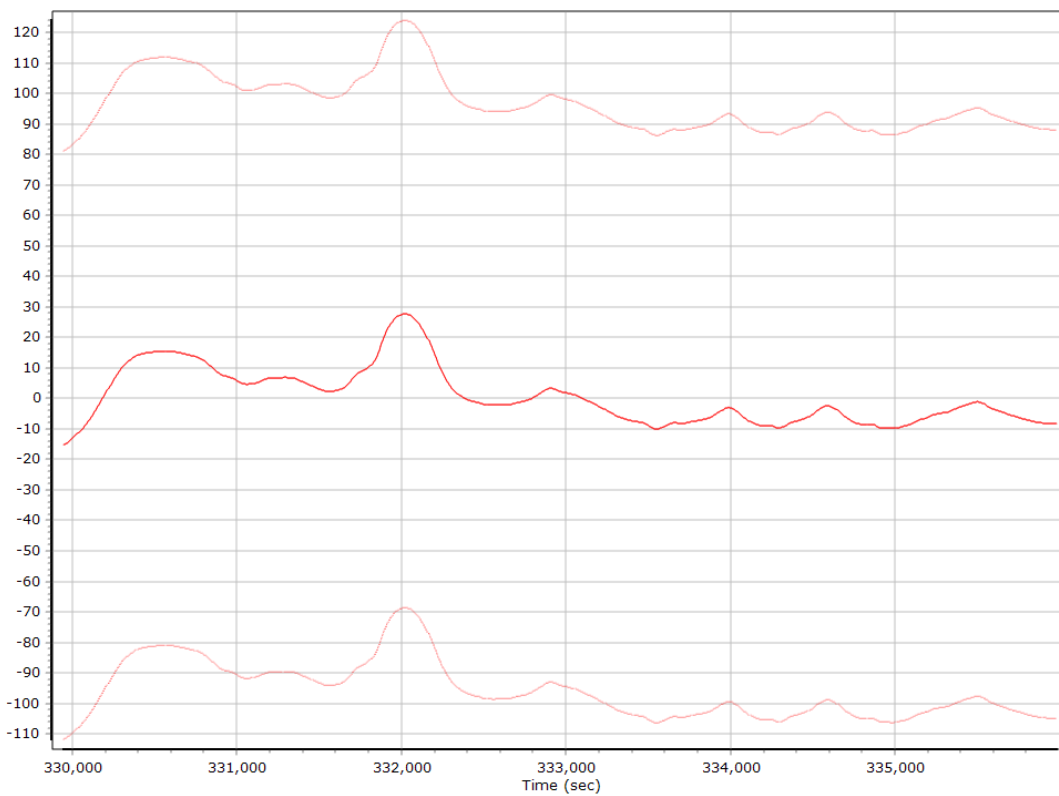
#### X Accelerometer Bias (micro-g)



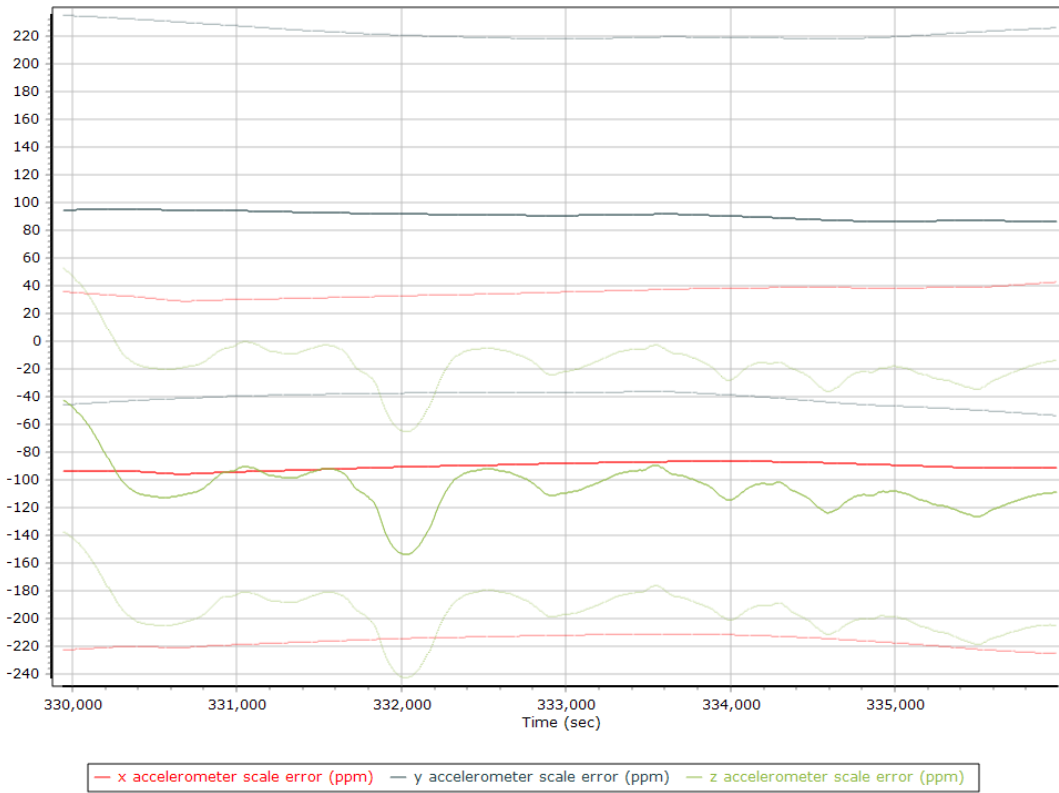
### Y Accelerometer Bias (micro-g)



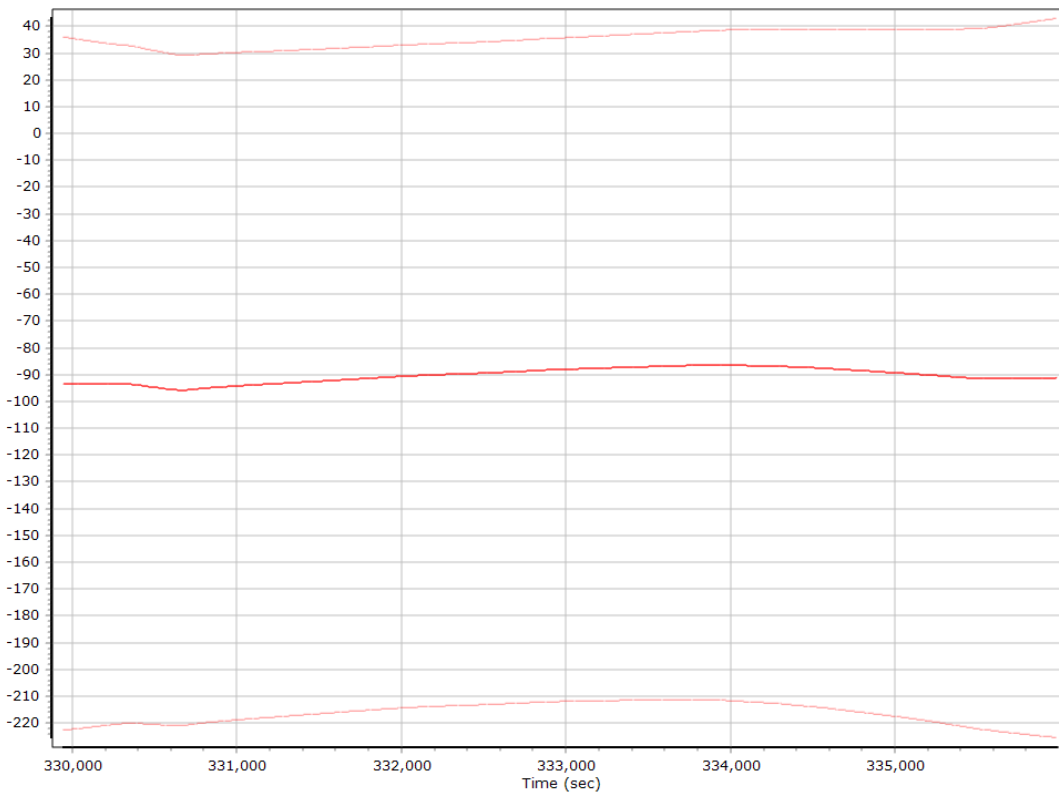
### Z Accelerometer Bias (micro-g)



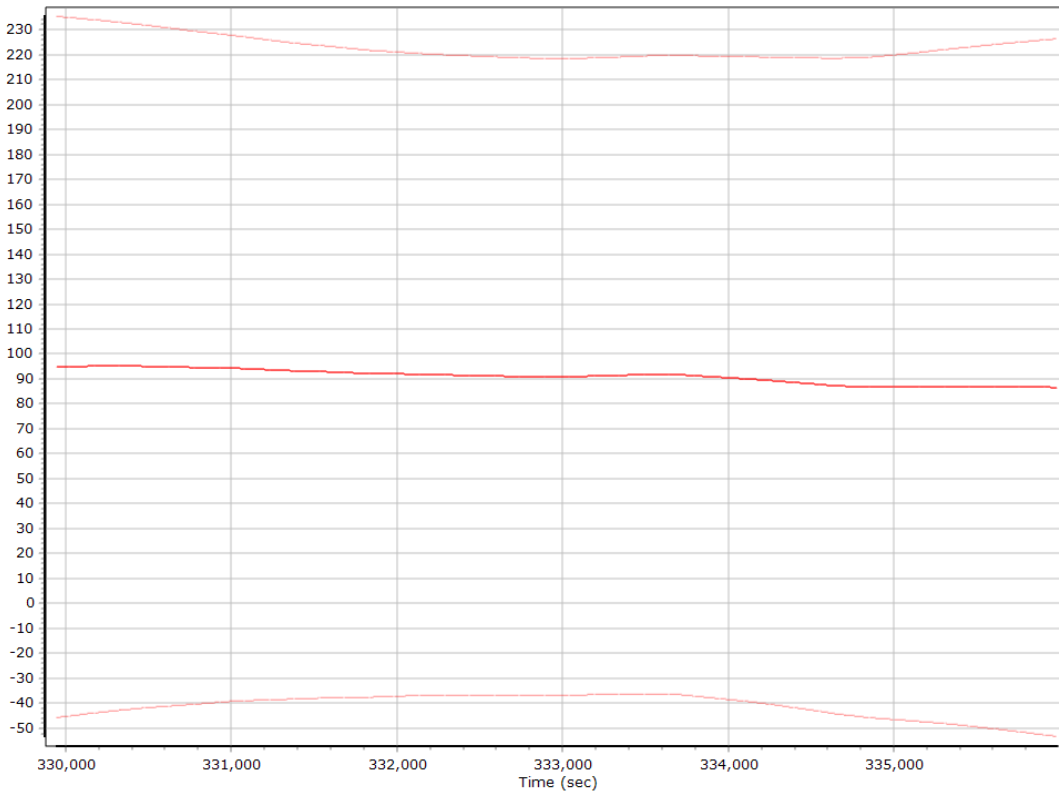
### Accelerometer Scale Error (ppm)



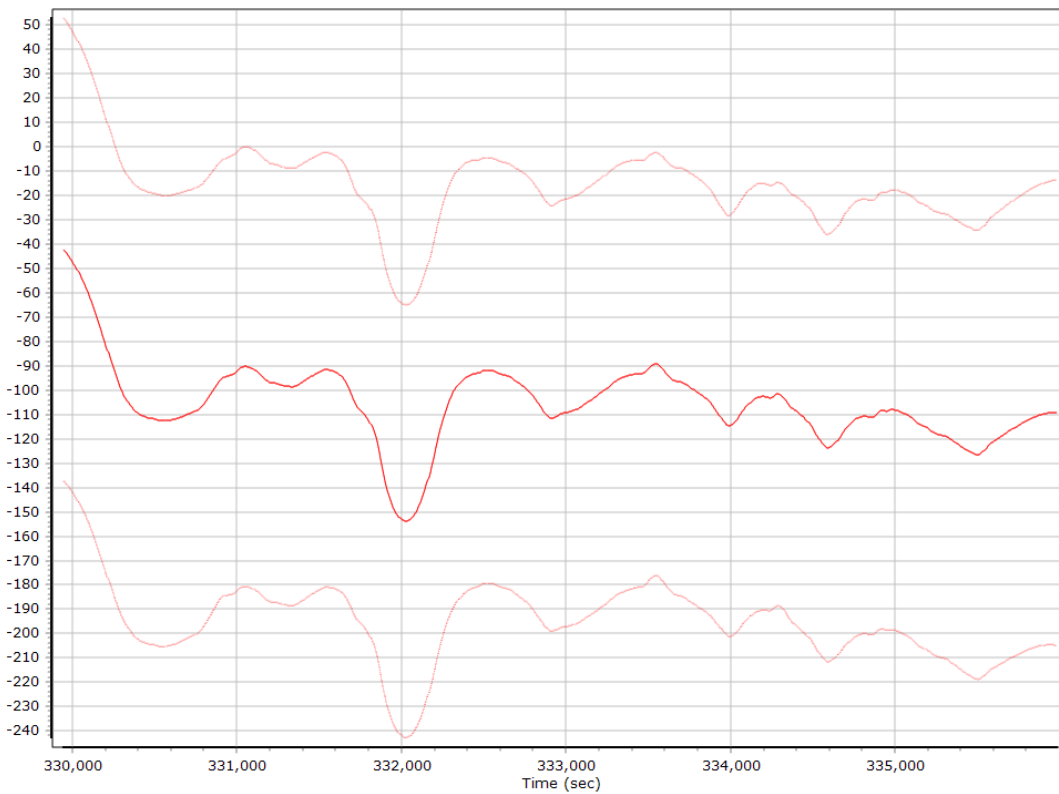
### X Accelerometer Scale Error (ppm)



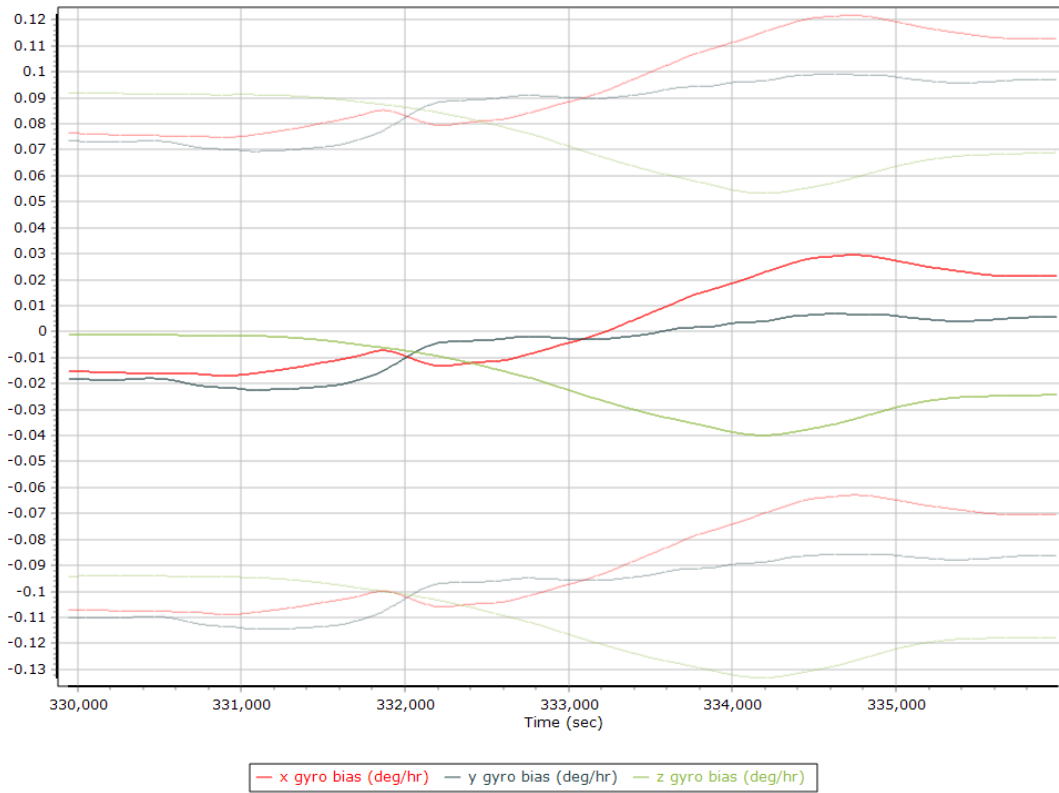
### Y Accelerometer Scale Error (ppm)



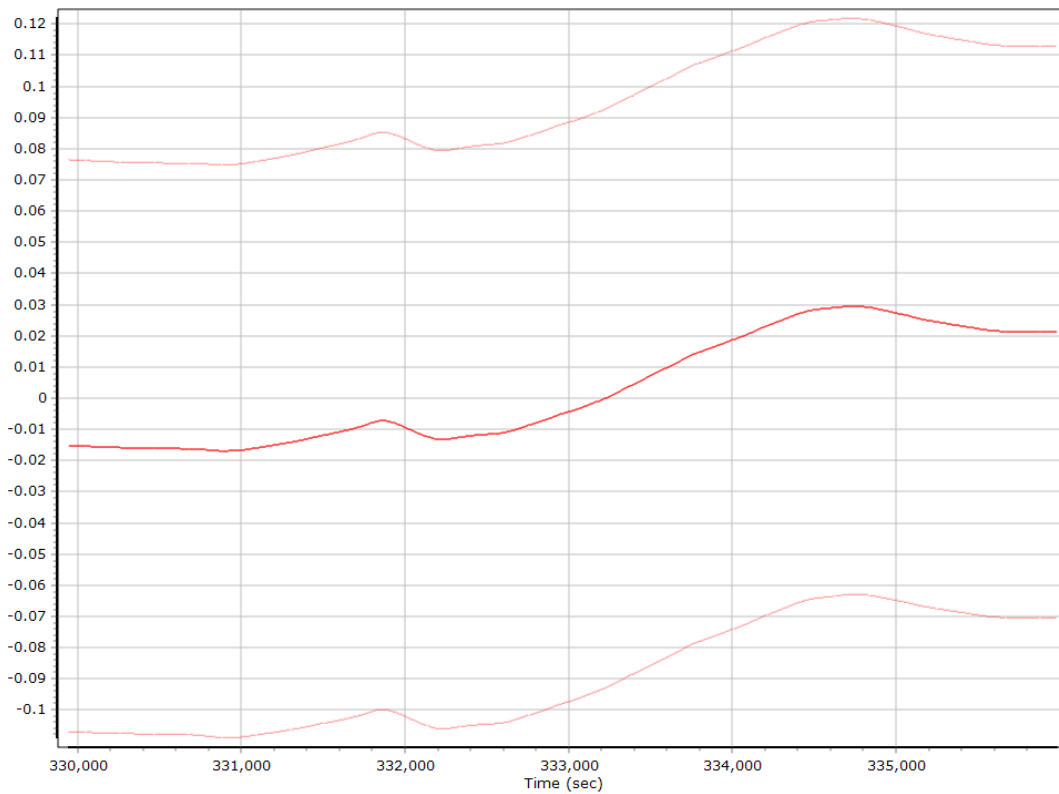
### Z Accelerometer Scale Error (ppm)



### Gyro Bias (deg/h)

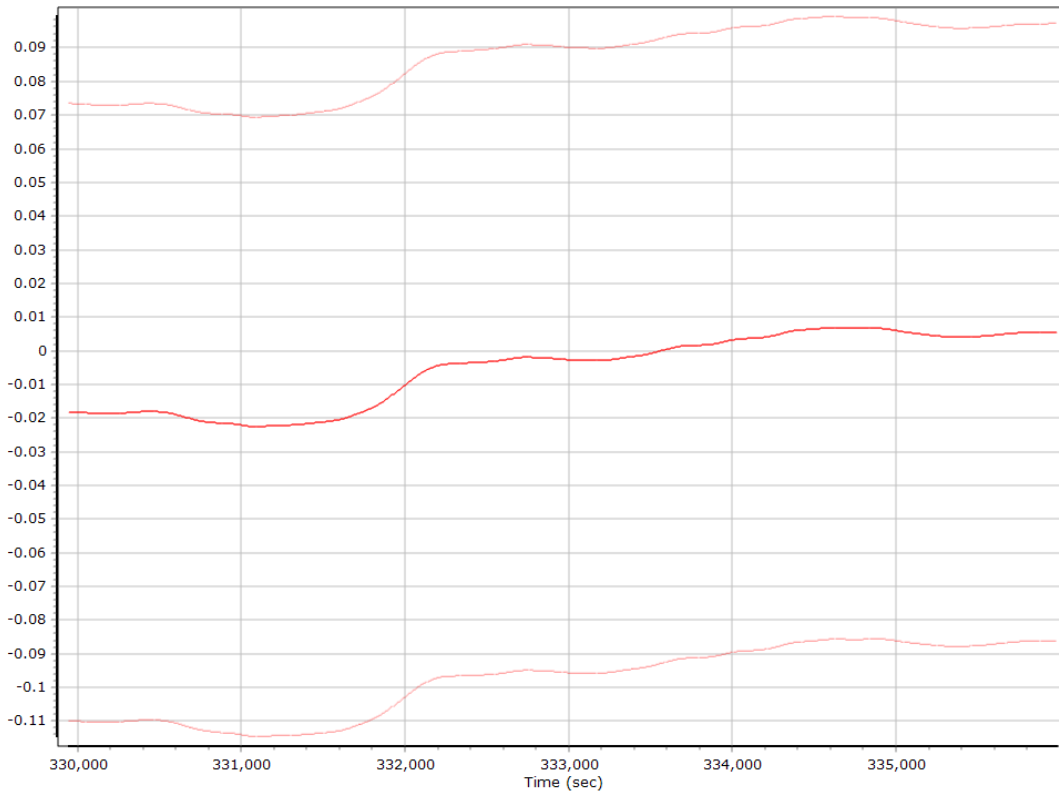


### X Gyro Bias (deg/h)

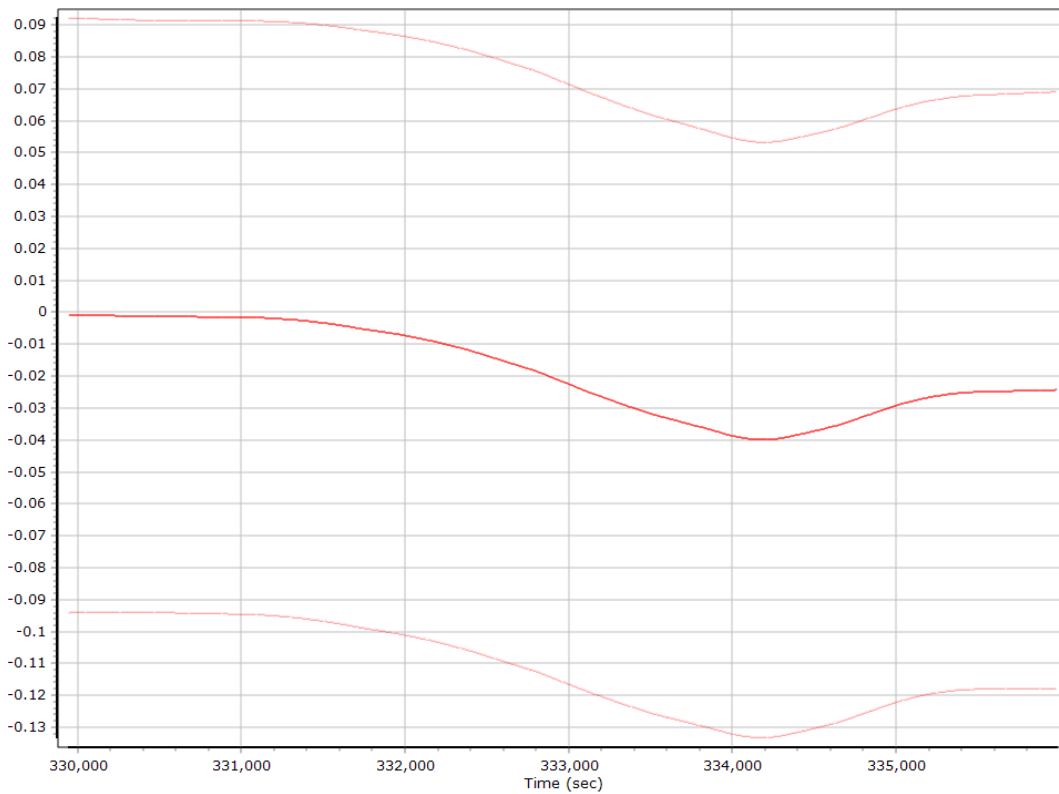




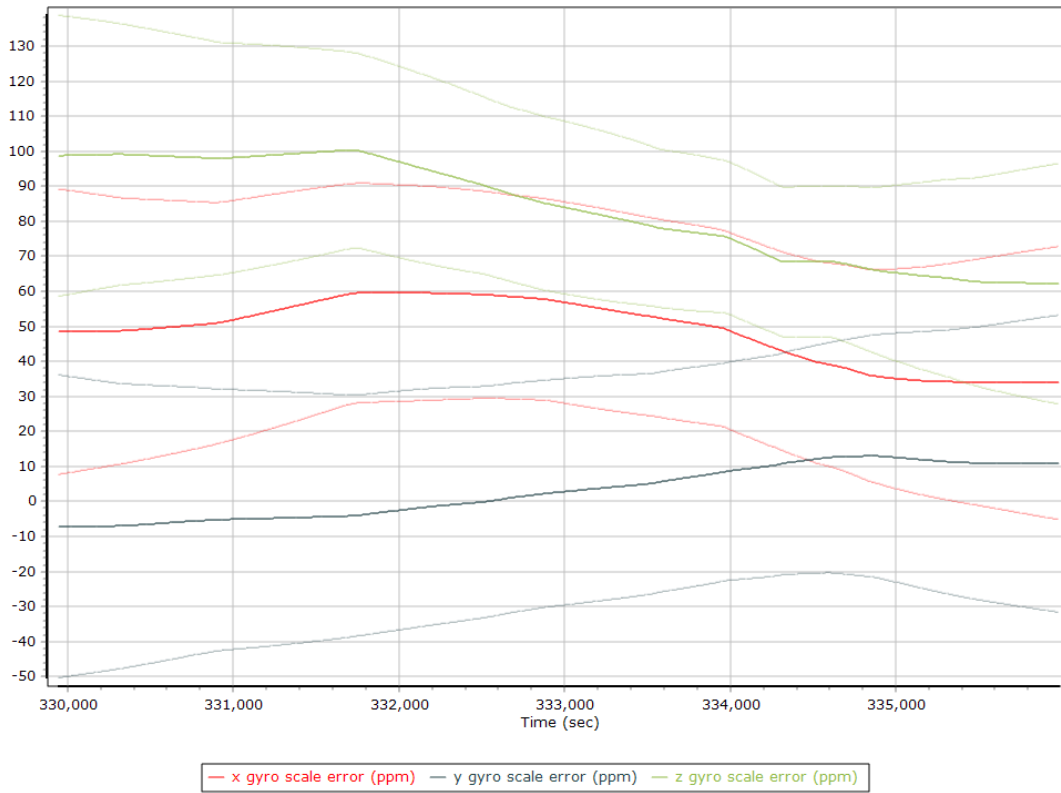
### Y Gyro Bias (deg/h)



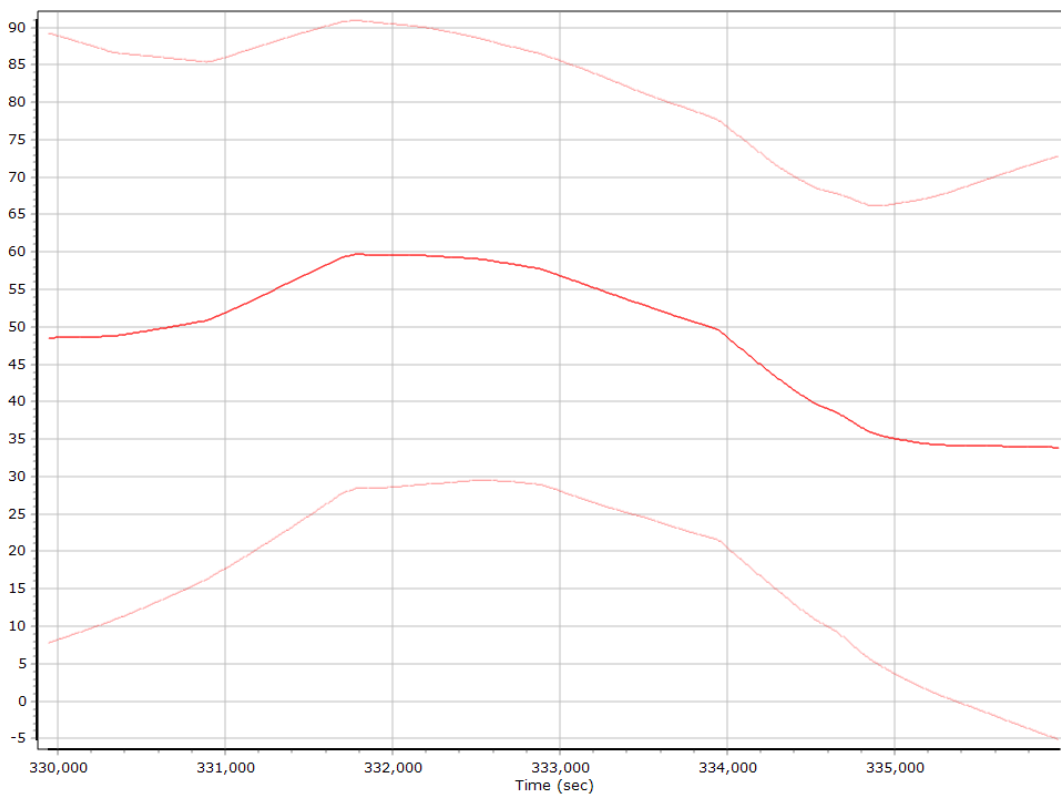
### Z Gyro Bias (deg/h)



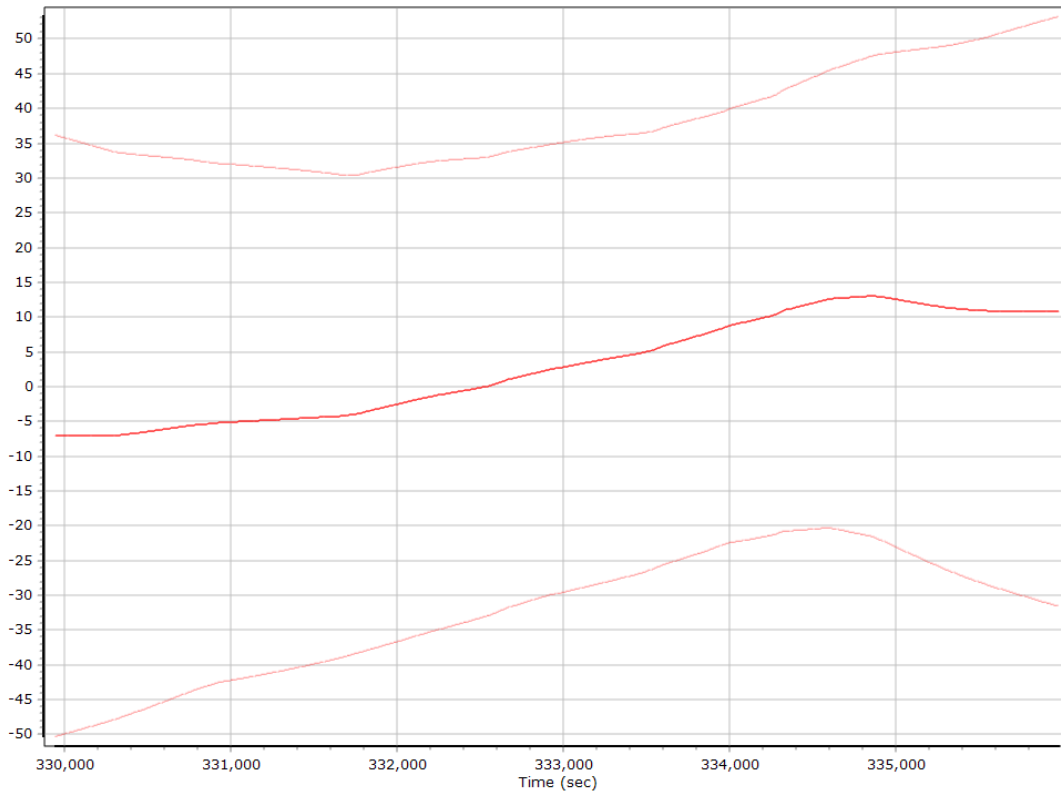
### Gyro Scale Error (ppm)



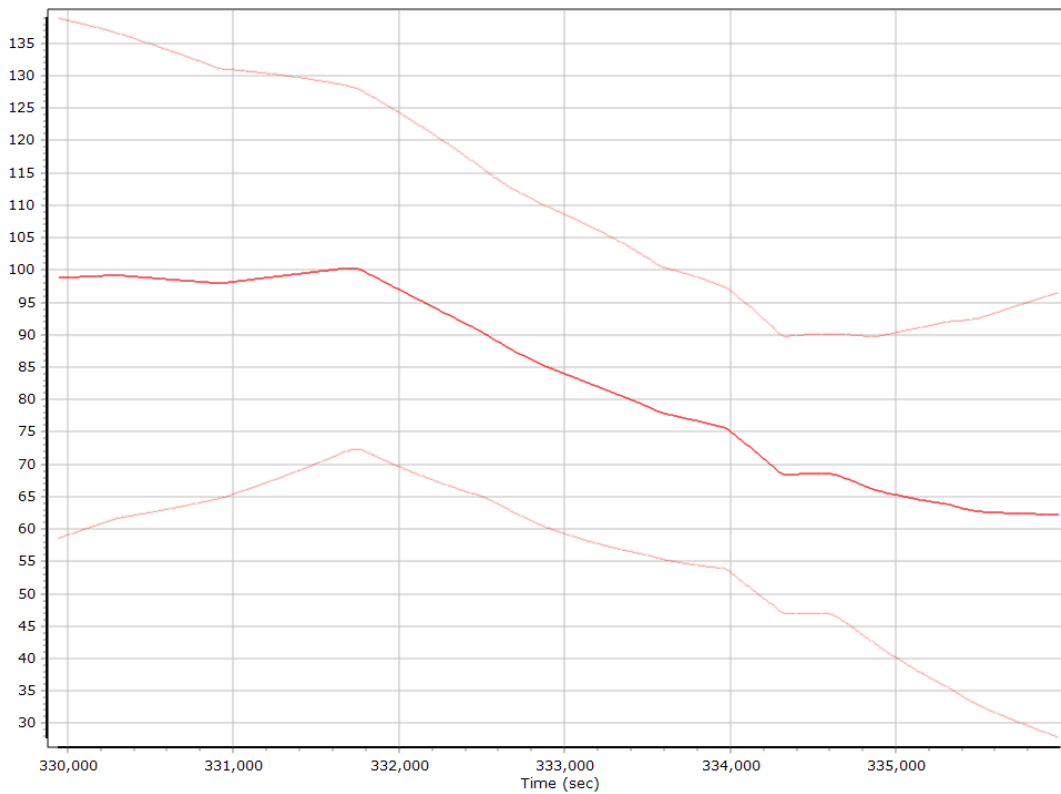
### X Gyro Scale Error (ppm)



### Y Gyro Scale Error (ppm)

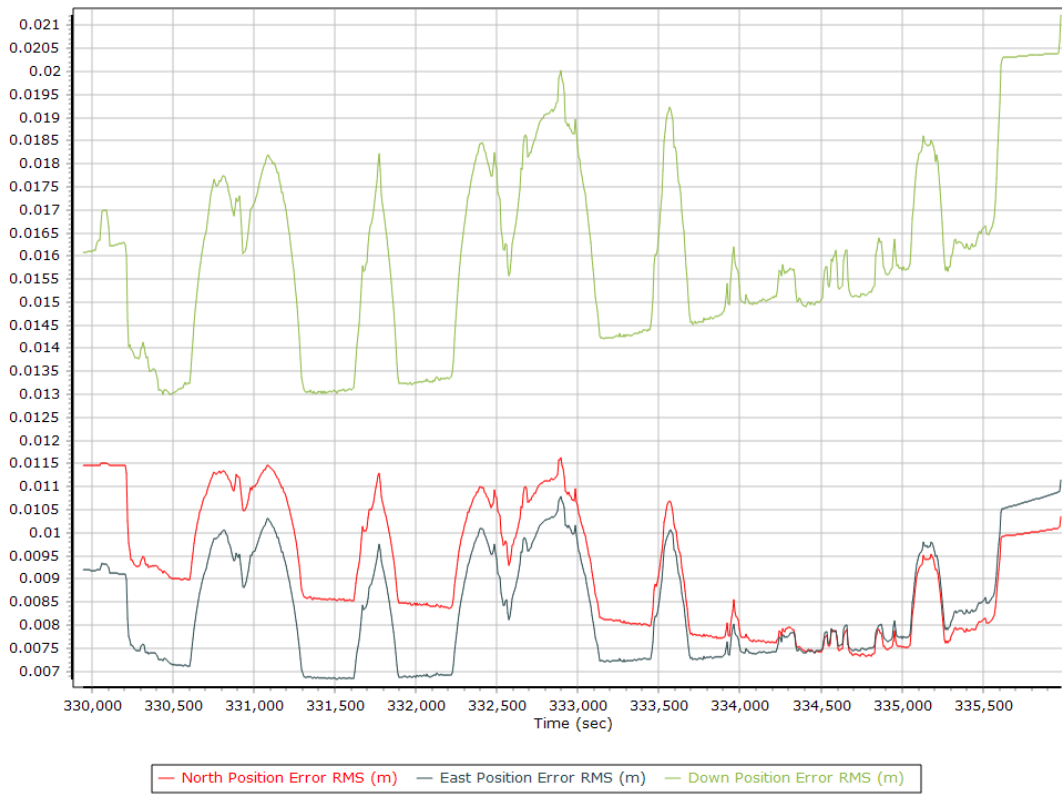


### Z Gyro Scale Error (ppm)

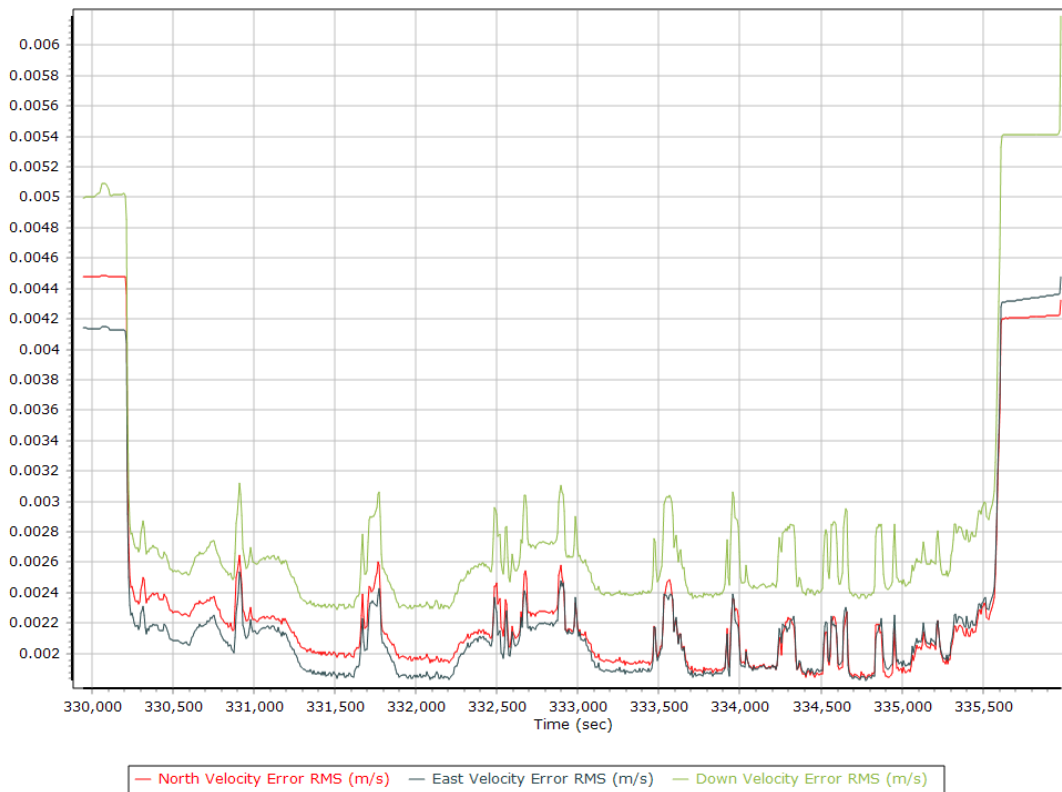


## Smoothed Performance Metrics

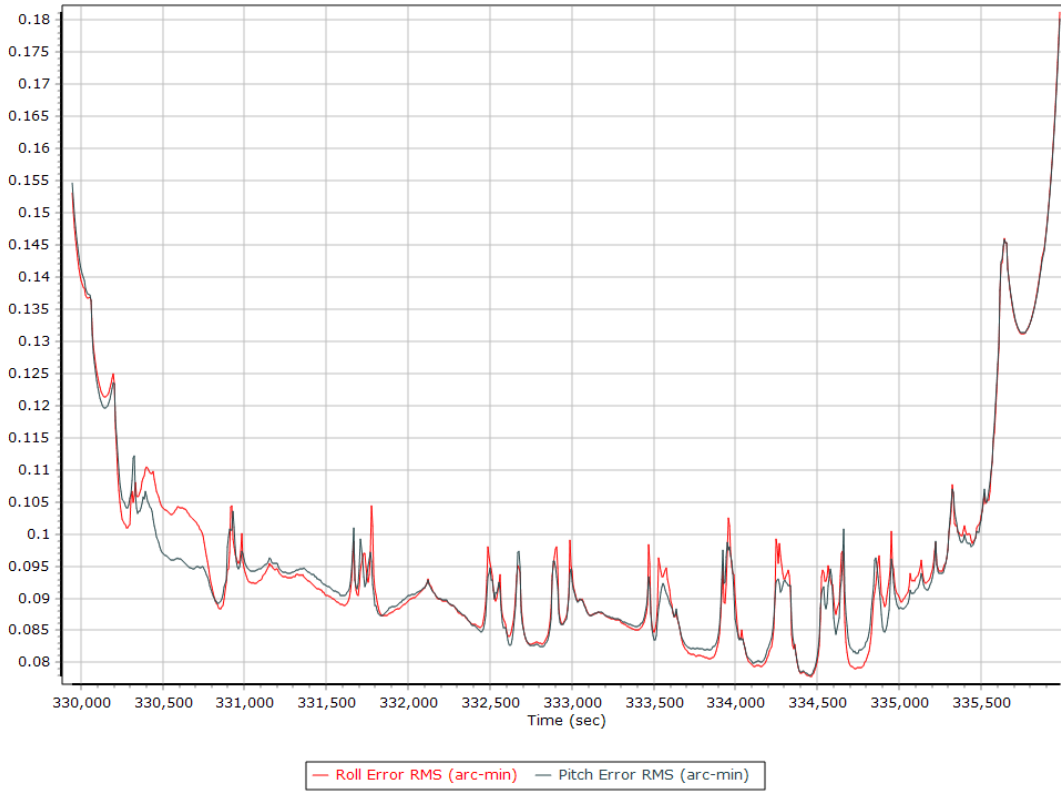
### Position Error RMS (m)



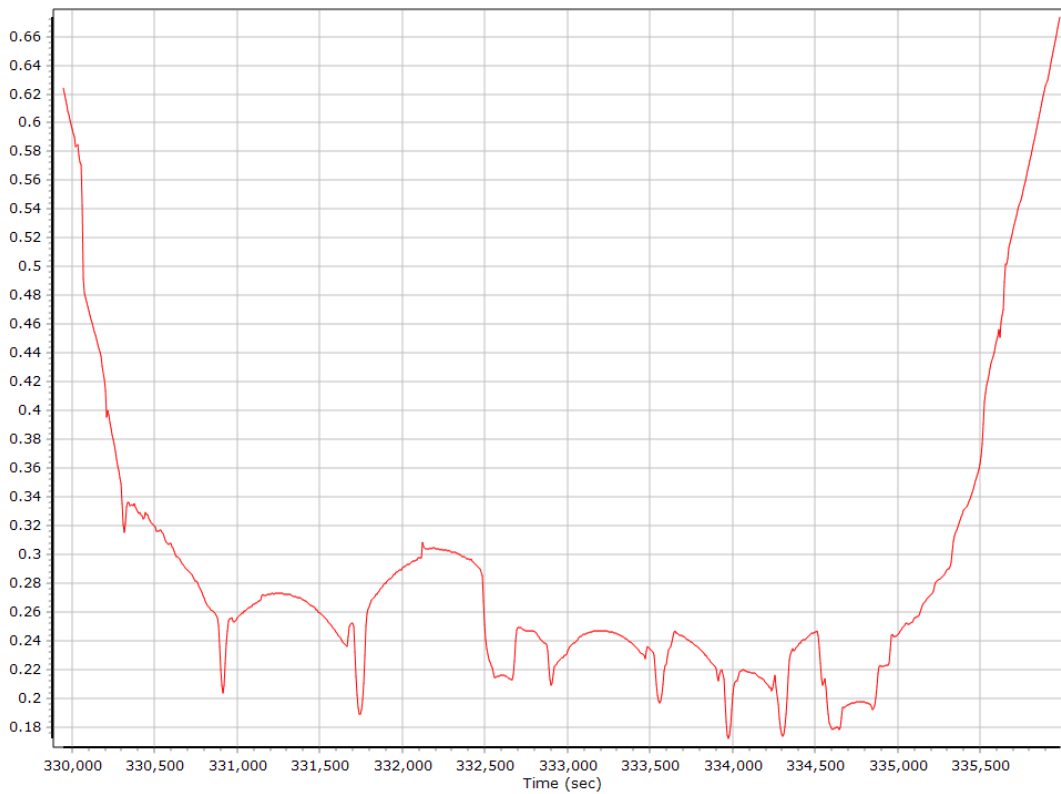
### Velocity Error RMS (m/s)



### Roll/Pitch Error RMS (arc-min)

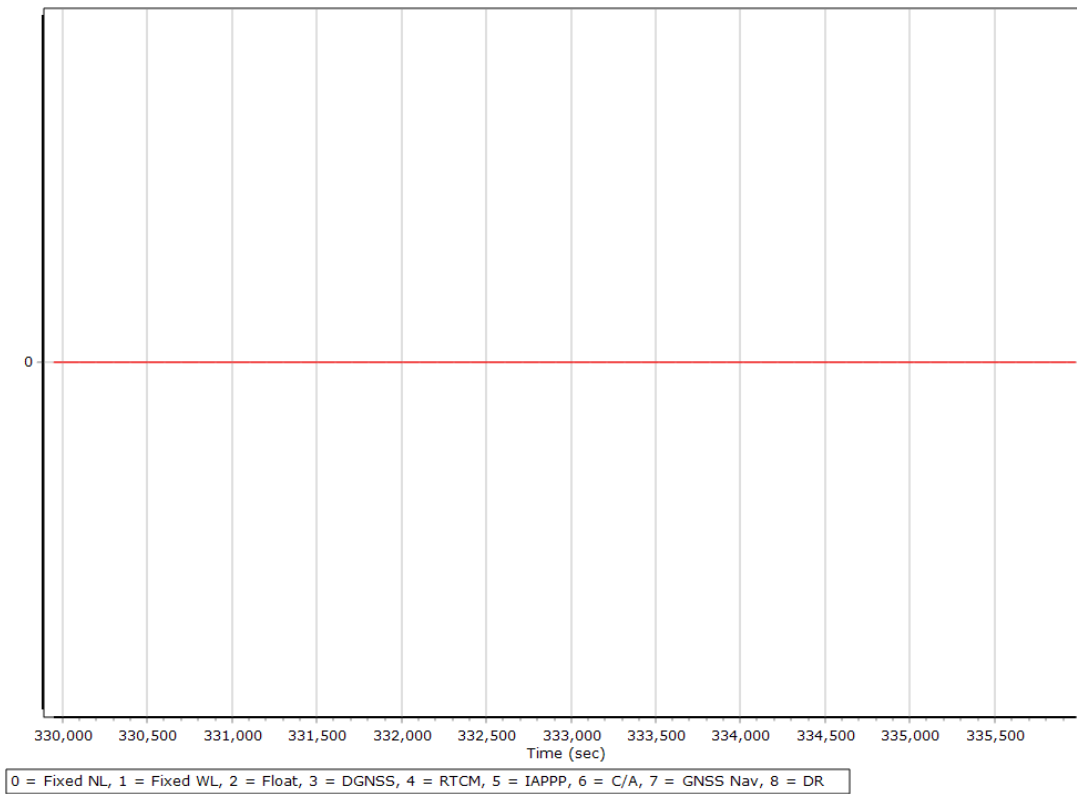


### Heading Error RMS (arc-min)

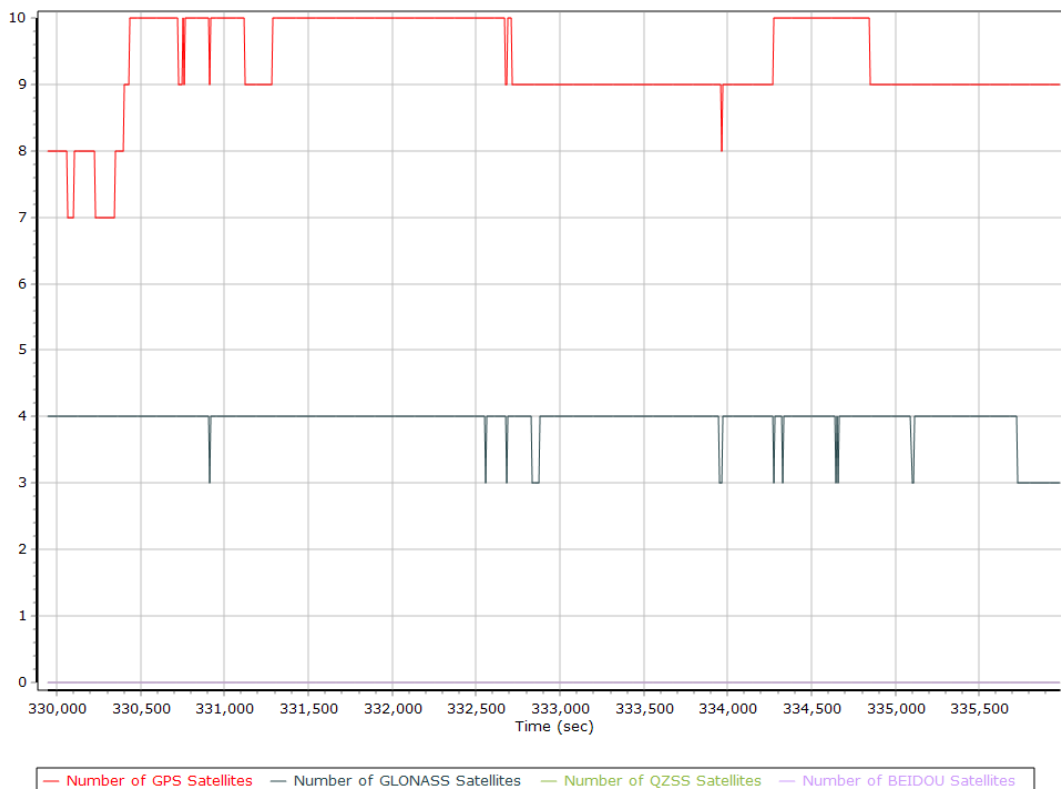


## Smoothed Solution Status

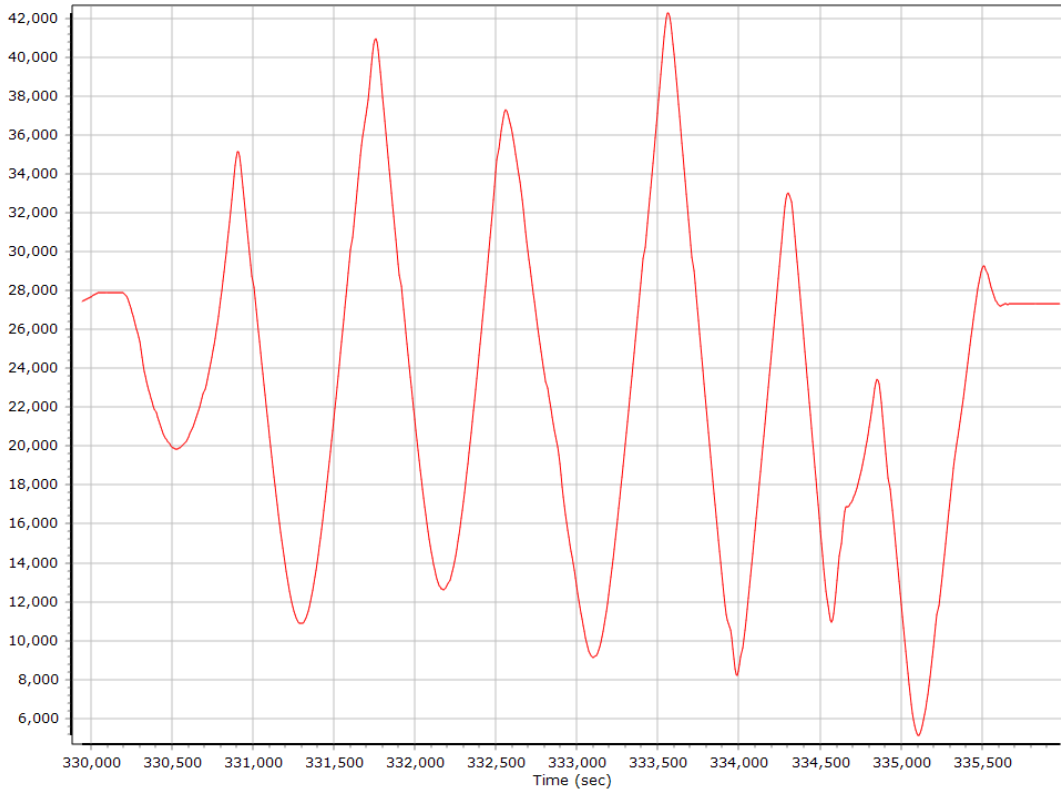
### Processing Mode



### Number of Satellites



### Baseline Length



### SBET IAkar Separation

