

AIRBORNE LIDAR REPORT



NRCS DICKINSON COUNTY, MICHIGAN LIDAR

Task Order Number: G12PD00721
Woolpert Project Number: 72637
June 2013



AIRBORNE LIDAR TASK ORDER REPORT

NRCS DICKINSON COUNTY, MICHIGAN LIDAR

WOOLPERT PROJECT #72637

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SECTION 1: OVERVIEW

PROJECT NAME: NRCS DICKINSON COUNTY, MICHIGAN LIDAR

WOOLPERT PROJECT #72637

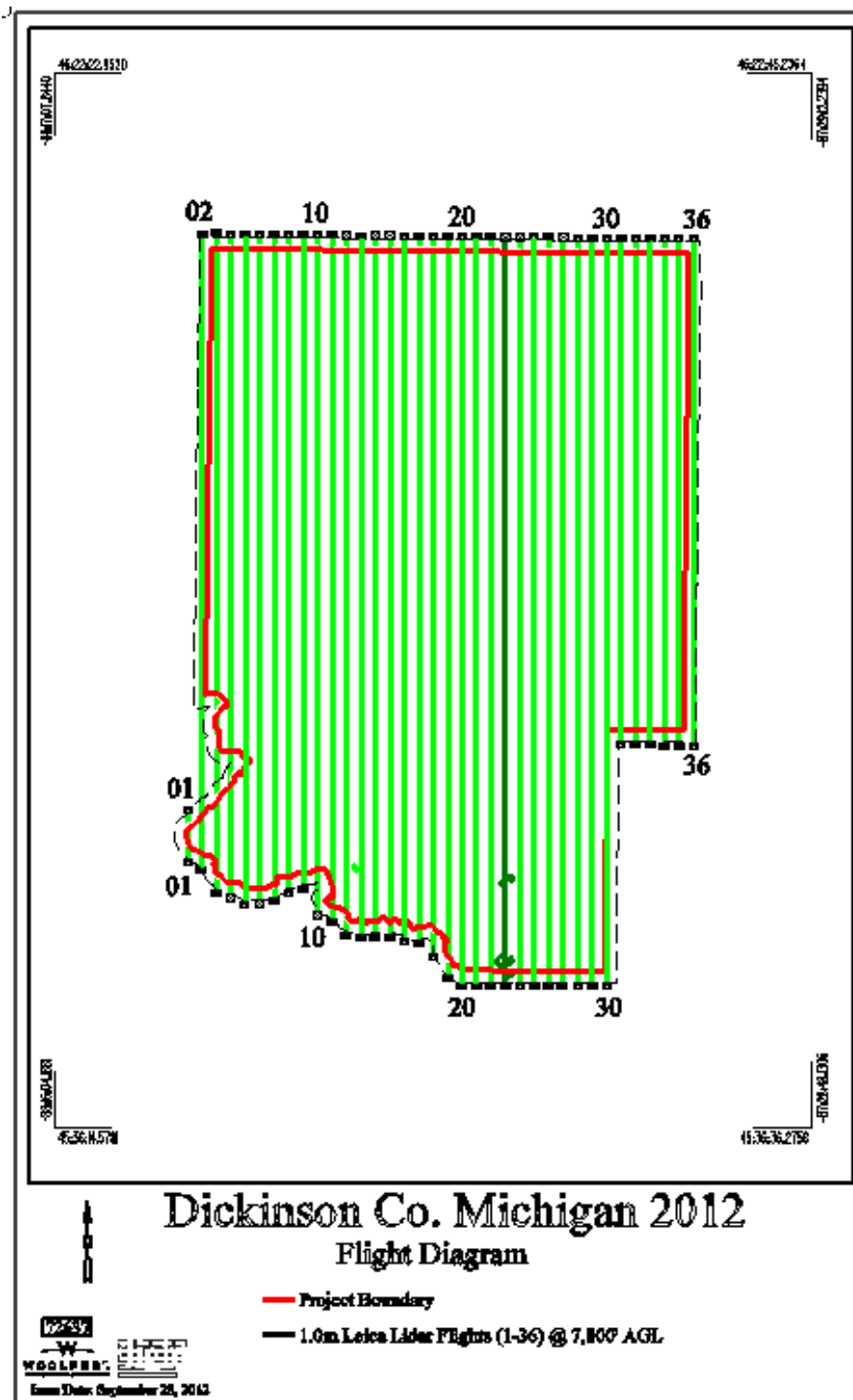
This report contains a comprehensive outline of the airborne LiDAR data acquisition consisting of a 776 square mile area for all of Dickinson County in Michigan for the United States Geological Survey (USGS). The LiDAR was collected and processed to meet a maximum Nominal Post Spacing (NPS) of 1 meter. The NPS assessment is made against single swath, first return data located within the geometrically usable center portion (typically ~90%) of each swath.

The data was collected using a Leica ALS70 500 kHz Multiple Pulses in Air (MPIA) LiDAR sensor system installed in a shock isolator sled mount. The sensors collect up to four returns (echoes) per pulse, recording attributes such as time stamp and intensity data, for the first three returns. If a fourth return was captured, the system does not record an associated intensity value. The aerial LiDAR was collected at the following sensor specifications:

Post Spacing (Minimum):	3.28 ft / 1 m
AGL (Above Ground Level) average flying height:	7,800 ft / 2,377 m
MSL (Mean Sea Level) average flying height:	8,620 ft / 2,627 m
Average Ground Speed:	150 knots / 173 mph
Field of View (full):	40 degrees
Pulse Rate:	230.0 kHz
Scan Rate:	35.5 Hz
Side Lap (Minimum):	25%

LiDAR data was processed and projected in UTM, Zone 16, North American Datum of 1983 (NAD83) in units of meters. The vertical datum used for the task order was referenced to NAVD 1988, meters, GEOID12A

Figure 1.1: Task Order and LiDAR Flight Layout - Dickinson County, MI



SECTION 2: ACQUISITION

The LiDAR data was acquired with a Leica ALS70 Multiple Pulses in Air (MPiA) LiDAR sensor system, on board a Cessna 404. This LiDAR system, developed by Leica Geosystems of Heerbrugg, Switzerland, includes the simultaneous first, intermediate and last pulse data capture module, the extended altitude range module, and the target signal intensity capture module. The system software is operated on an OC50 Operation Controller aboard the aircraft.

The ALS70 500 kHz Multiple Pulses in Air (MPiA) LiDAR System has the following specifications:

Table 2.1: ALS70 LiDAR System Specifications	
Specification	
Operating Altitude	200 - 3,500 meters
Scan Angle	0 to 75° (variable)
Swath Width	0 to 1.5 X altitude (variable)
Scan Frequency	0 - 200 Hz (variable based on scan angle)
Maximum Pulse Rate	500 kHz (Effective)
Range Resolution	Better than 1 cm
Elevation Accuracy	7 - 16 cm single shot (one standard deviation)
Horizontal Accuracy	5 - 38 cm (one standard deviation)
Number of Returns per Pulse	7 (infinite)
Number of Intensities	3 (first, second, third)
Intensity Digitization	8 bit intensity + 8 bit AGC (Automatic Gain Control) level
MPiA (Multiple Pulses in Air)	8 bits @ 1nsec interval @ 50kHz
Laser Beam Divergence	0.22 mrad @ $1/e^2$ (-0.15 mrad @ $1/e$)
Laser Classification	Class IV laser product (FDA CFR 21)
Eye Safe Range	400m single shot depending on laser repetition rate
Roll Stabilization	Automatic adaptive, range = 75 degrees minus current FOV
Power Requirements	28 VDC @ 25A
Operating Temperature	0-40°C
Humidity	0-95% non-condensing
Supported GNSS Receivers	Ashtech Z12, Trimble 7400, Novatel Millenium

Prior to mobilizing to the task order site, Woolpert flight crews coordinated with the necessary Air Traffic Control personnel to ensure airspace access.

Woolpert survey crews were onsite, operating a Global Navigation Satellite System (GNSS) Base Station at NGS-PID-AA8108 for the airborne GPS support on both mission days. Coordinates: 45°48'12.78402' (N), 88°07'05.64416" (W), Ellipsoid Height 310.552 meters.

The LiDAR data was collected in (2) missions.

An initial quality control process was performed immediately on the LiDAR data to review the data coverage, airborne GPS data, and trajectory solution. Any gaps found in the LiDAR data were relayed to the flight crew, and the area was re-flown. Data from delivery tile 16TDR170985 has a small void caused by smoke from a factory.

Table 2.2: Airborne LiDAR Acquisition Flight Summary			
Airborne LiDAR Acquisition Flight Summary			
Date of Mission/Sensor	Lines Flown	Mission Time (UTC) Wheels Up/ Wheels Down	Mission Time (Local = EST) Wheels Up/ Wheels Down
Nov 15, 2012 - S/N 7177	1-10, 31-36	20:35 - 00:22	02:35 PM - 06:22 PM
Nov 16, 2012 - S/N 7177	11-30	13:59 - 19:46	07:59 AM - 01:46 PM

SECTION 3: LIDAR DATA PROCESSING

APPLICATIONS AND WORK FLOW OVERVIEW

1. Resolved kinematic corrections for three subsystems: inertial measurement unit (IMU), sensor orientation information and airborne GPS data. Developed a blending post-processed aircraft position with attitude data using Kalman filtering technology or the smoothed best estimate trajectory (SBET).
Software: POSPac Software v. 5.3, IPAS Pro v.1.35.
2. Calculated laser point position by associating the SBET position to each laser point return time, scan angle, intensity, etc. Created raw laser point cloud data for the entire survey in .LAS format. Automated line-to-line calibrations were then performed for system attitude parameters (pitch, roll, heading), mirror flex (scale) and GPS/IMU drift.
Software: ALS Post Processing Software v.2.70, Proprietary Software, TerraMatch v. 12.01.
3. Imported processed .LAS point cloud data into the task order tiles. Resulting data were classified as ground and non-ground points with additional filters created to meet the task order classification specifications. Statistical absolute accuracy was assessed via direct comparisons of ground classified points to ground RTK survey data. Based on the statistical analysis, the LiDAR data was then adjusted to reduce the vertical bias when compared to the survey ground control.
Software: TerraScan v. 13.003.
4. The .LAS files were evaluated through a series of manual QA/QC steps to eliminate remaining artifacts and small undulations from the ground class.
Software: TerraScan v. 13.003.
5. All water bodies greater than two acres and all rivers with a nominal 100 foot width or larger were hydro-flattened using stereo compilation methods.
Software: LP360, proprietary tools, Microstation v8, TerraScan v.13.003.

GLOBAL NAVIGATION SATELLITE SYSTEM (GNSS)-INERTIAL MEASUREMENT UNIT (IMU) TRAJECTORY PROCESSING

EQUIPMENT

Flight navigation during the LiDAR data acquisition mission is performed using IGI CCNS (Computer Controlled Navigation System). The pilots are skilled at maintaining their planned trajectory, while holding the aircraft steady and level. If atmospheric conditions are such that the trajectory, ground speed, roll, pitch and/or heading cannot be properly maintained, the mission is aborted until suitable conditions occur.

The aircraft are all configured with a NovAtel Millennium 12-channel, L1/L2 dual frequency Global Navigation Satellite System (GNSS) receivers collecting at 2 Hz.

All Woolpert aerial sensors are equipped with a Litton LN200 series Inertial Measurement Unit (IMU) operating at 200 Hz.

A base-station unit was mobilized for each acquisition mission, and was operated by a member of the Woolpert survey crew. Each base-station setup consisted of one Trimble 4000 - 5000 series dual

frequency receiver, one Trimble Compact L1/L2 dual frequency antenna, one 2-meter fixed-height tripod, and essential battery power and cabling. Ground planes were used on the base-station antennas. Data was collected at 1 or 2 Hz.

Woolpert survey crews were onsite, operating a Global Navigation Satellite System (GNSS) Base Station for the airborne GPS support. The GNSS base station operated during the LiDAR acquisition missions is listed below:

Station	Latitude	Longitude	Ellipsoid Height (L1 Phase Center)
Name	(DMS)	(DMS)	(Meters)
NGS-PID-AA8108	N 45° 48' 50.78"	W 88° 07' 05.64"	310.552

DATA PROCESSING

All airborne GNSS and IMU data was post-processed and quality controlled using Applanix 5.3 MMS software. GNSS data was processed at a 1 and 2 Hz data capture rate and the IMU data was processed at 200 Hz.

TRAJECTORY QUALITY

The GNSS Trajectory, along with high quality IMU data are key factors in determining the overall positional accuracy of the final sensor data. See Figure 3.1 for the flight trajectory.

Flight Trajectory

Figure 3.1: Representative Graph from Day320: N475RC



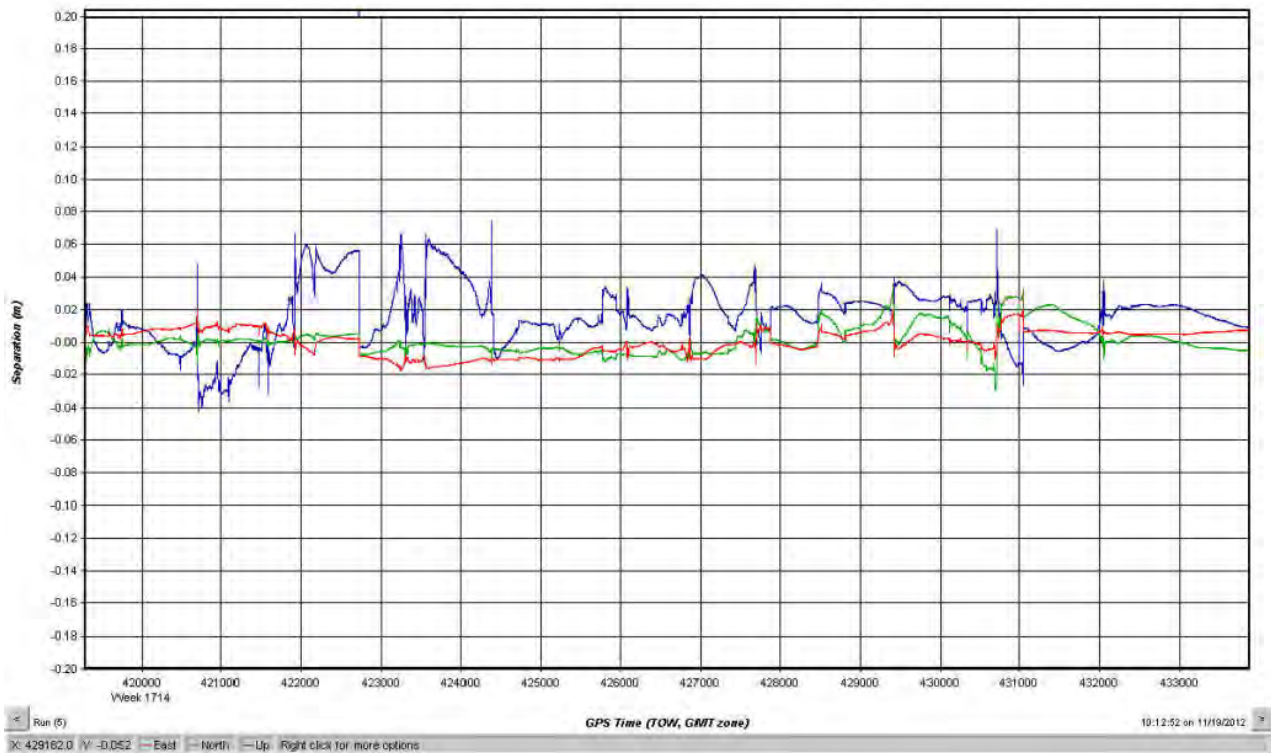
Within the trajectory processing, there are many factors that affect the overall quality, but the most indicative are the Combined Separation, the Estimated Positional Accuracy, and the Positional Dilution of Precision (PDOP).

Combined Separation

The Combined Separation is a measure of the difference between the forward run and the backward run solution of the trajectory. The Kalman filter is processed in both directions to remove the combined directional anomalies. In general, when these two solutions match closely, an optimally accurate reliable solution is achieved.

Woolpert's goal is to maintain a Combined Separation Difference of less than ten (10) centimeters. In most cases we achieve results below this threshold. See Figure 3.2 for the combined separation graph.

Figure 3.2: Representative Graph from Day320 of Combined Separation

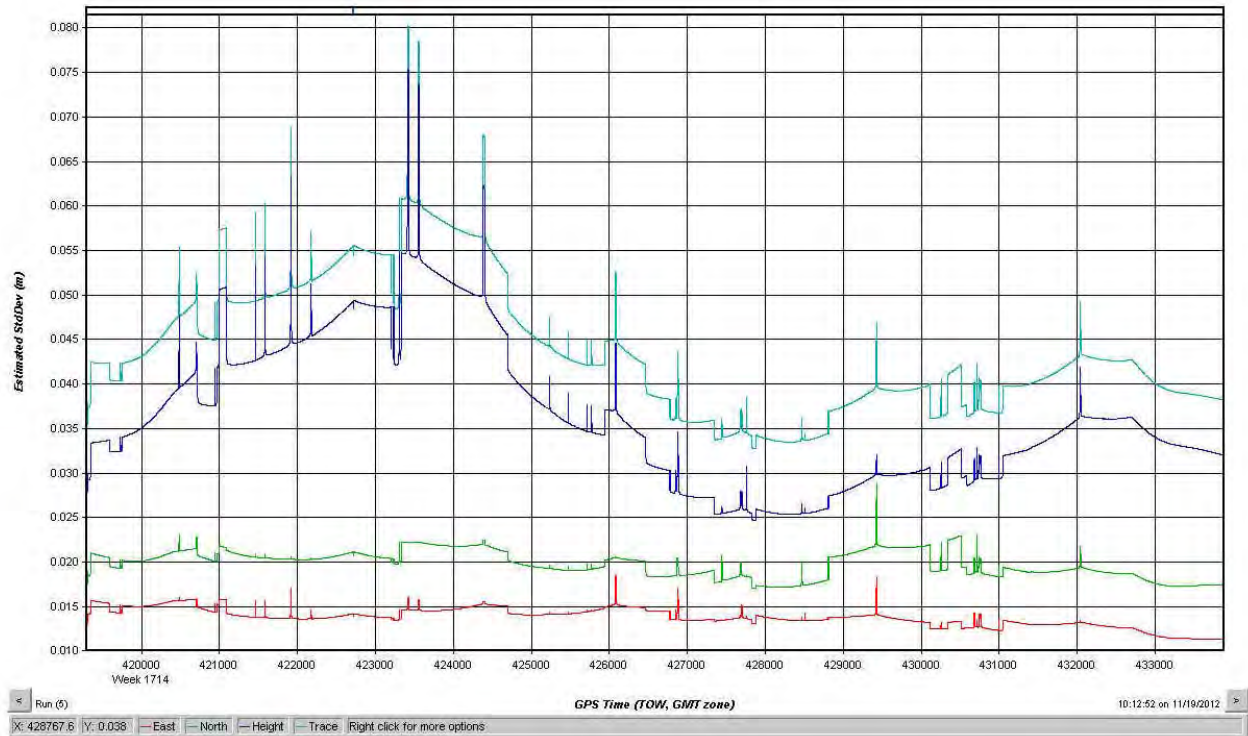


Estimated Positional Accuracy

The Estimated Positional Accuracy plots the standard deviations of the east, north, and vertical directions along a time scale of the trajectory. It illustrates loss of satellite lock issues, as well as issues arising from long baselines, noise, and/or other atmospheric interference.

Woolpert's goal is to maintain an Estimated Positional Accuracy of less than ten (10) centimeters, often achieving results well below this threshold.

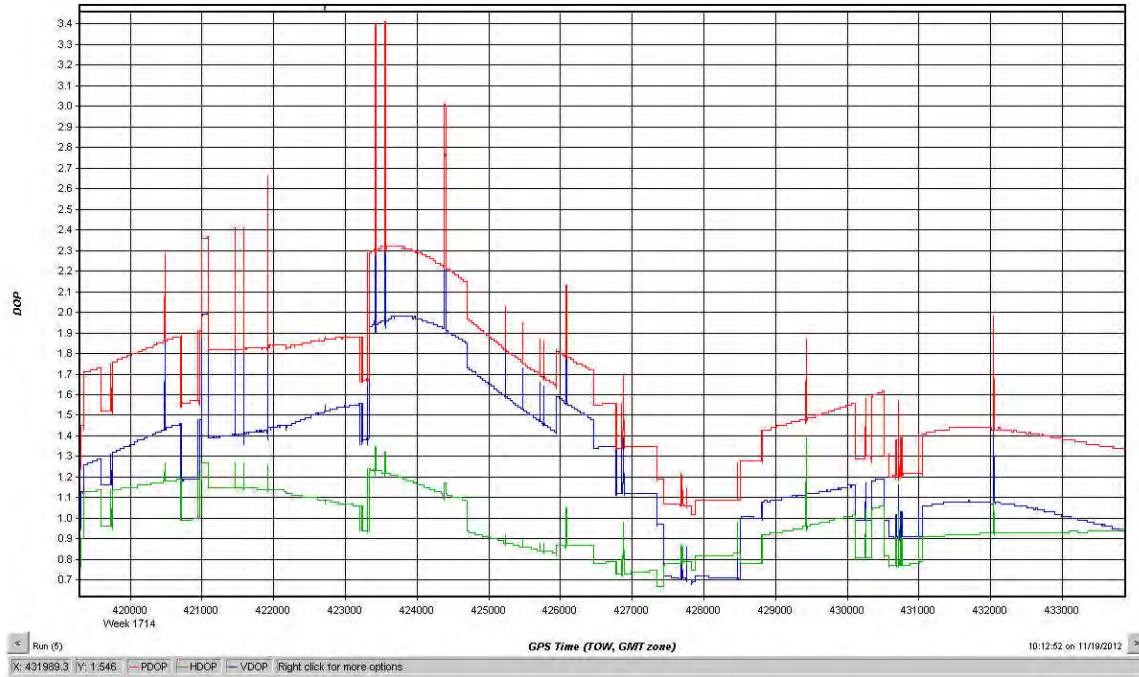
Figure 3.3: Representative Graph from Day320 of Positional Accuracy



PDOP

Position Dilution of precision (DOP) is a measure of the quality of the GPS data being received from the satellites. Woolpert's goal is to maintain an average PDOP of 3 or less.

Figure 3.4: Representative Graph from Day 320 of PDOP



LIDAR DATA PROCESSING

When the sensor calibration, data acquisition, and GPS processing phases were complete, the formal data reduction processes by Woolpert LiDAR specialists included:

- Processed individual flight lines to derive a raw “Point Cloud” LAS file. Matched overlapping flight lines, generated statistics for evaluation comparisons, and made the necessary adjustments to remove any residual systematic error.
- Calibrated LAS files were imported into the task order tiles and initially filtered to create a ground and non-ground class. Then additional classes were filtered as necessary to meet client specified classes.
- Once all of the task order data was imported and classified, cross flights and survey ground control data was imported and calculated for an accuracy assessment. As a QA/QC measure, Woolpert has developed a routine to generate accuracy statistical reports by comparison among LiDAR points, ground control, and TINs. The LiDAR is adjusted accordingly to reduce any vertical bias to meet or exceed the vertical accuracy requirements.
- The LiDAR tiles were reviewed using a series of proprietary QA/QC procedures to ensure it fulfills the task order requirements. A portion of this requires a manual step to ensure anomalies have been removed from the ground class.
- The bare earth DEM surface was hydrologically flattened for water body features that were greater than 2 acres and rivers and streams of 30.5 meters (100 feet) and greater nominal width.
- The LiDAR LAS files for this task order have been classified into the Default (Class 1), Ground (Class 2), Noise (Class 7), Model Key Point (Class 8), Water (Class 9) Ignored Ground (Class 10), Overlap Default (Class 17), and Overlap Ground (Class 18).
- FGDC Compliant metadata was developed for the task order in .xml format for the final data products.
- The horizontal datum used for the task order was referenced to UTM 16N, North American Datum of 1983. Coordinate positions were specified in units meters for Dickinson County. The vertical datum used for the task order was referenced to NAVD 1988, meters, GEOID12A.

SECTION 4: HYDROLOGIC FLATTENING AND FINAL QUALITY CONTROL

HYDROLOGIC FLATTENING OF LIDAR DEM DATA

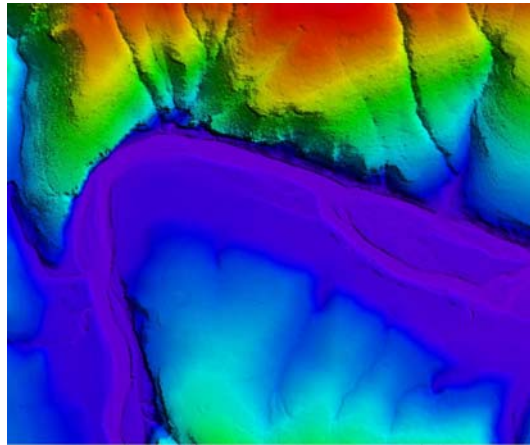
This task required the compilation of breaklines defining water bodies and rivers. The breaklines were used to perform the hydrologic flattening of water bodies, and gradient hydrologic flattening of double line streams and rivers. Lakes, reservoirs and ponds, at a minimum size of 2-acres or greater, were compiled as closed polygons. The closed water bodies were collected at a constant elevation. Rivers and streams, at a nominal minimum width of 30.5 meters (100 feet) were compiled in the direction of flow with both sides of the stream maintaining an equal gradient elevation.

LIDAR DATA REVIEW AND PROCESSING

Woolpert utilized the following steps to hydrologically flatten the water bodies and for gradient hydrologic flattening of the double line streams within the existing LiDAR data.

1. Woolpert used the newly acquired LiDAR data to manually draw the hydrologic features in a 2D environment using the LiDAR intensity and bare earth surface. Google Earth was used as reference when necessary.
2. Woolpert utilizes an integrated software approach to combine the LiDAR data and 2D breaklines. This process “drapes” the 2D breaklines onto the 3D LiDAR surface model to assign an elevation. A monotonic process is performed to ensure the streams are consistently flowing in a gradient manner. A secondary step within the program verifies an equally matching elevation of both stream edges. The breaklines that characterize the closed water bodies are draped onto the 3D LiDAR surface and assigned a constant elevation at or just below ground elevation.
3. The lakes, reservoirs and ponds, at a minimum size of 2-acres or greater, were compiled as closed polygons. **Figure 4.1** illustrates a good example of 2-acre lakes and 30.5 meters (100 feet) nominal streams identified and defined with hydrologic breaklines. During the collection of linework, the technical staff used a program that displayed the polygon measurement area as a reference to identify lakes larger than 2-acres. The breaklines defining rivers and streams, at a nominal minimum width of 30.5 meters (100 feet) were draped with both sides of the stream maintaining an equal gradient elevation.

Figure 4.1



4. All ground points were reclassified from inside the hydrologic feature polygons to water, class nine (9).
5. All ground points were reclassified from within a 1.5 meter (5 feet) buffer along the hydrologic feature breaklines to buffered ground, class ten (10).
6. The LiDAR ground points and hydrologic feature breaklines were used to generate a new digital elevation model (DEM).

Figure 4.2



Figure 4.3



Figure 4.2 reflects a DEM generated from original LiDAR bare earth point data prior to the hydrologic flattening process. Note the "tinning" across the lake surface.

Figure 4.3 reflects a DEM generated from LiDAR with breaklines compiled to define the hydrologic features. This figure illustrates the results of adding the breaklines to hydrologically flatten the DEM data. Note the smooth appearance of the lake surface in the DEM.

Terrascan was used to add the hydrologic breakline vertices and export the lattice models. The hydrologically flattened DEM data was provided to USGS in ERDAS .img format at a 1-meter cell size.

The hydrologic breaklines compiled as part of the flattening process were provided to USGS as an ESRI shapefile. The breaklines defining the water bodies greater than 2-acres were provided as a PolygonZ file. The breaklines compiled for the gradient flattening of all rivers and streams at a nominal minimum width of 30.5 meters (100 feet) were provided as a PolylineZ file.

DATA QA/QC

Initial QA/QC for this task order was performed in Global Mapper v14, by reviewing the grids and hydrologic breakline features.

Edits and corrections were addressed individually by tile. If a water body breakline needed to be adjusted to improve the flattening of the IMG DEM, the area was cross referenced by tile number, corrected accordingly, a new IMG DEM was regenerated and then reviewed in Global Mapper.

SECTION 5: FINAL ACCURACY ASSESSMENT

FINAL VERTICAL ACCURACY ASSESSMENT

The vertical accuracy statistics were calculated by comparison of the LiDAR bare earth points to the ground surveyed QA/QC points.

Statistic	Value	Unit
Average error	-0.016	meters
Minimum error	-0.119	meters
Maximum error	0.076	meters
Average magnitude	0.041	meters
Root mean square	0.05	meters
Standard deviation	0.048	meters

Point ID	Easting (UTM meters)	Northing (UTM meters)	Elevation (meters)	Dz (meters)
2000	415721.327	5110511.95	430.454	-0.074
2001	415739.784	5110480.862	430.62	-0.05
2002	415774.284	5110487.753	431.142	-0.022
2003	415803.89	5110508.569	430.274	0.016
2004	415792.125	5110547.335	429.389	-0.119
2005	426274.585	5087710.727	329.621	0.019
2006	426271.677	5087748.762	327.987	-0.047
2007	425368.641	5087148.227	321.717	0.023
2008	425332.328	5087163.382	323.269	-0.069
2009	425351.31	5087198.705	323.182	-0.012
2010	425384.172	5087224.032	322.926	-0.036
2011	425395.152	5087185.75	322.389	-0.069
2015	419535.042	5093061.695	370.109	-0.079
2016	423259.668	5100884.779	393.199	-0.059
2017	416008.473	5104356.154	452.66	-0.1
2018	418295.447	5115621.374	430.802	0.068

Table 5.2: QA/QC Analysis, UTM 16N, NAD83, Dickinson County, MI

Point ID	Easting (UTM meters)	Northing (UTM meters)	Elevation (meters)	Dz (meters)
2019	430480.447	5109193.352	363.804	0.076
2020	424538.409	5079631.655	313.793	0.037
2021	415190.634	5076891.448	343.159	0.011
2500	441724.435	5114129.874	371.794	-0.034
2501	437999.173	5119583.938	406.603	0.047
2502	446833.208	5115268.815	353.169	0.031
2503	449488.347	5121253.125	361.508	-0.088
2504	439949.125	5108877.511	374.71	0
2505	442014.056	5111785.378	354.599	0.011
2506	442381.439	5090571.347	313.915	0.035
2508	446578.552	5094387.82	324.583	-0.033
2509	435636.068	5090606.661	359.734	0.026
2510	438269.014	5085415.492	298.206	-0.036
2511	434063.178	5082373.599	321.652	-0.072
2512	434225.086	5076460.449	316.537	-0.047
2513	433289.473	5073517.169	300.425	-0.025
2514	429259.155	5069071.348	297.41	0.04
2515	433035.684	5067130.931	255.692	-0.012
2516	442066.389	5068272.285	283.437	-0.027
2517	441245.729	5080885.677	294.72	-0.03
2518	440169.723	5076161.979	298.08	0
2520	450517.367	5103506.883	338.94	0.03
2521	434511.923	5096451.97	351.592	0.038
4507	448822.458	5099589.501	364.603	-0.003

VERTICAL ACCURACY CONCLUSIONS

LAS Swath Fundamental Vertical Accuracy (FVA) Tested 0.098 meters fundamental vertical accuracy at a 95 percent confidence level, derived according to NSSDA, in open terrain using (RMSEz) x 1.96000 Tested against the TIN using independent check points.

Bare-Earth DEM Fundamental Vertical Accuracy (FVA) Tested 0.097 meters fundamental vertical accuracy at a 95 percent confidence level, derived according to NSSDA, in open terrain using (RMSEz) x 1.96000 Tested against the DEM using independent check points.

SUPPLEMENTAL VERTICAL ACCURACY ASSESSMENTS

Point ID	Easting (UTM meters)	Northing (UTM meters)	Elevation (meters)	Absolute Dz (meters)
2000	415721.327	5110511.95	430.454	0.064
2001	415739.784	5110480.862	430.62	0.04
2002	415774.284	5110487.753	431.142	0.032
2003	415803.89	5110508.569	430.274	0.006
2004	415792.125	5110547.335	429.389	0.129
2005	426274.585	5087710.727	329.621	0.019
2006	426271.677	5087748.762	327.987	0.047
2007	425368.641	5087148.227	321.717	0.023
2008	425332.328	5087163.382	323.269	0.069
2009	425351.31	5087198.705	323.182	0.002
2010	425384.172	5087224.032	322.926	0.036
2011	425395.152	5087185.75	322.389	0.079
2015	419535.042	5093061.695	370.109	0.069
2016	423259.668	5100884.779	393.199	0.039
2017	416008.473	5104356.154	452.66	0.1
2018	418295.447	5115621.374	430.802	0.068
2019	430480.447	5109193.352	363.804	0.076
2020	424538.409	5079631.655	313.793	0.037

Table 5.3: QA/QC Analysis, Bare Earth and Open Terrain, UTM 16N, NAD83, Dickinson County, MI

Point ID	Easting (UTM meters)	Northing (UTM meters)	Elevation (meters)	Absolute Dz (meters)
2021	415190.634	5076891.448	343.159	0.011
2500	441724.435	5114129.874	371.794	0.034
2501	437999.173	5119583.938	406.603	0.047
2502	446833.208	5115268.815	353.169	0.021
2503	449488.347	5121253.125	361.508	0.088
2504	439949.125	5108877.511	374.71	0.01
2505	442014.056	5111785.378	354.599	0.001
2506	442381.439	5090571.347	313.915	0.035
2508	446578.552	5094387.82	324.583	0.033
2509	435636.068	5090606.661	359.734	0.056
2510	438269.014	5085415.492	298.206	0.056
2511	434063.178	5082373.599	321.652	0.062
2512	434225.086	5076460.449	316.537	0.037
2513	433289.473	5073517.169	300.425	0.025
2514	429259.155	5069071.348	297.41	0.03
2515	433035.684	5067130.931	255.692	0.012
2516	442066.389	5068272.285	283.437	0.017
2517	441245.729	5080885.677	294.72	0.04
2518	440169.723	5076161.979	298.08	0.01
2520	450517.367	5103506.883	338.94	0.01
2521	434511.923	5096451.97	351.592	0.048
4507	448822.458	5099589.501	364.603	0.003

ACCURACY CONCLUSIONS

Bare Earth/Open Terrain Land Cover Classification Supplemental Vertical Accuracy (SVA) Tested 0.099 meters supplemental vertical accuracy at the 95th percentile in Bare Earth/Open Terrain. Tested against the DEM. Errors larger than 95th percentile include:

- Point 2004, Easting 415792.125, Northing 5110547.335, Z-Error 0.129 meters

Point ID	Easting (UTM meters)	Northing (UTM meters)	Elevation (meters)	Absolute Dz (meters)
5000	418374.761	5081401.753	358.803	0.047
5001	418394.787	5081395.403	358.379	0.051
5002	418366.774	5081368.194	358.255	0.095
5003	418343.655	5081353.583	358.264	0.056
5004	418380.288	5081458.423	358.602	0.018
5005	421863.927	5121066.555	437.991	0.109
5006	421896.693	5121050.096	437.93	0.06
5007	421932.494	5121046.426	437.429	0.131
5008	421958.786	5121023.672	435.95	0.02
5009	421939.495	5120986.274	435.381	0.089
5010	421897.177	5120983.957	435.506	0.024
5011	421855.855	5120980.156	435.473	0.037
5015	421185.939	5085426.44	372.979	0.179
5016	421194.076	5085414.6	373.269	0.111
5017	417615.852	5101088.429	412.725	0.135
5018	429399.455	5109158.058	368.119	0.021
5500	446831.909	5115241.009	353.572	0.058
5501	453146.009	5114503.945	354.639	0.029
5502	450104.866	5120690.269	358.041	0.119
5503	442275.196	5101888.084	382.075	0.065

Table 5.4: QA/QC Analysis, Brush Lands and Trees, UTM 16N, NAD83, Dickinson County, MI				
Point ID	Easting (UTM meters)	Northing (UTM meters)	Elevation (meters)	Absolute Dz (meters)
5504	436467.696	5099134.417	348.037	0.023
5505	436493.2	5099149.404	347.947	0.083
5506	428984.689	5095139.643	361.965	0.065
5507	447586.574	5098064.011	359.429	0.041
5508	438317.864	5085329.893	297.916	0.174
5509	434261.324	5084873.814	322.006	0.044
5510	443751.561	5075692.261	293.302	0.022
5511	442344.892	5080055.179	306.961	0.039
5512	428248.128	5074760.309	332.492	0.028
5513	441917.477	5112063.114	357.5	0.15
5514	441147.603	5116232.211	368.002	0.008
5515	440456.42	5092448.398	331.252	0.038

ACCURACY CONCLUSIONS

Brush Lands and Trees Land Cover Classification Supplemental Vertical Accuracy (SVA) Tested 0.176 meters supplemental vertical accuracy at the 95th percentile in Brush Lands and Trees. Tested against the DEM. Brush Lands and Trees Errors larger than 95th percentile include:

- Point 5015, Easting 421185.939, Northing 5085426.44, Z-Error 0.179 meters

Table 5.5: QA/QC Analysis, Forested and Fully Grown, UTM 16N, NAD83, Dickinson County, MI				
Point ID	Easting (UTM meters)	Northing (UTM meters)	Elevation (meters)	Absolute Dz (meters)
6000	437333.566	5101644.488	370.631	0.111
6001	437302.533	5101644.689	370.574	0.054
6002	437271.54	5101644.929	370.045	0.095
6003	437263.46	5101681.28	371.865	0.125

Table 5.5: QA/QC Analysis, Forested and Fully Grown, UTM 16N, NAD83, Dickinson County, MI

Point ID	Easting (UTM meters)	Northing (UTM meters)	Elevation (meters)	Absolute Dz (meters)
6004	437299.267	5101691.531	372.712	0.062
6005	437338.356	5101693.611	373.346	0.006
6006	425135.721	5114748.54	409.091	0.091
6007	425132.047	5114778.934	409.398	0.068
6008	425129.131	5114808.239	409.237	0.017
6009	425159.815	5114823.318	409.787	0.047
6010	425159.363	5114793.329	409.461	0.019
6011	425150.815	5114759.409	409.332	0.002
6012	425840.942	5077812.445	328.379	0.081
6013	425808.903	5077810.693	329.574	0.084
6014	425773.895	5077812.363	330.563	0.103
6015	425769.313	5077844.919	329.545	0.105
6016	425806.637	5077849.95	328.876	0.166
6017	425842.142	5077851.02	328.258	0.088
6018	443318.072	5079146.389	310.774	0.006
6019	443288.051	5079144.243	311.48	0.08
6020	443256.326	5079140.087	313.311	0.011
6021	443229.266	5079141.868	313.655	0.015
6022	443194.41	5079139.627	314.188	0.022
6023	443175.388	5079138.56	314.637	0.087
6025	416082.683	5093809.445	381.206	0.254
6500	441982.131	5113752.141	378.567	0.037

ACCURACY CONCLUSIONS

Forested and Fully Grown Land Cover Classification Supplemental Vertical Accuracy (SVA) Tested 0.223 meters supplemental vertical accuracy at the 95th percentile in Forested and Fully Grown. Tested against the DEM. Forested and Fully Grown Errors larger than 95th percentile include:

- Point 6025, Easting 416082.683, Northing 5093809.445 Z-Error 0.254 meters

Point ID	Easting (UTM meters)	Northing (UTM meters)	Elevation (meters)	Absolute Dz (meters)
4000	420356.644	5082306.151	373.606	0.034
4001	420321.337	5082309.943	373.661	0.049
4002	420286.727	5082316.895	372.796	0.084
4003	418382.371	5081439.489	358.592	0.068
4004	418368.325	5081405.394	358.868	0.012
4005	425442.092	5108658.085	405.129	0.141
4006	425468.227	5108666.276	404.969	0.111
4007	425610.653	5108697.838	404.286	0.084
4008	425626.718	5108720.184	405.65	0.13
4009	425641.776	5108774.747	409.598	0.092
4010	425656.859	5108756.44	407.636	0.034
4011	417315.094	5073355.939	346.28	0
4015	422905.268	5085751.498	367.748	0.052
4016	417766.916	5095069.071	384.263	0.077
4017	422253.42	5120914.895	431.502	0.048
4500	443896.123	5104203.392	363.683	0.087
4501	436058.887	5106621.313	351.392	0.088
4502	436077.386	5106623.445	351.399	0.001
4503	434950.999	5106696.101	354.223	0.027
4504	434919.973	5106706.318	354.488	0.072

Table 5.6: QA/QC Analysis, Tall Weeds and Crops, UTM 16N, NAD83, Dickinson County, MI				
Point ID	Easting (UTM meters)	Northing (UTM meters)	Elevation (meters)	Absolute Dz (meters)
4505	434981.279	5106698.317	354.116	0.074
4506	448734.343	5099392.865	368.3	0.03
4507	433312.152	5073525.673	300.633	0.107
4508	432824.069	5067169.49	256.194	0.076
4509	436809.32	5069306.935	280.336	0.164
4510	442035.21	5068255.955	283.441	0.129
4511	443860.332	5068283.933	313.564	0.136
4513	443564.178	5082116.406	311.7	0.09
4514	449966.686	5088189.23	326.26	0.07
4515	435918.421	5093879.932	352.954	0.216

ACCURACY CONCLUSIONS

Tall Weeds/Crops Land Cover Classification Supplemental Vertical Accuracy (SVA) Tested 0.187 meters supplemental vertical accuracy at the 95th percentile in Tall Weeds/Crops. Tested against the DEM. Tall Weeds/Crops Errors larger than 95th percentile include:

- Point 4515, Easting 435918.421, Northing 5093879.932, Z-Error 0.216 meters

Table 5.7: QA/QC Analysis, Urban, UTM 16N, NAD83, Dickinson County, MI				
Point ID	Easting (UTM meters)	Northing (UTM meters)	Elevation (meters)	Absolute Dz (meters)
3000	416853.012	5104249.497	436.596	0.116
3001	416884.079	5104247.409	436.646	0.056
3002	416917.197	5104249.786	436.555	0.015
3003	416947.516	5104264.204	436.654	0.064
3004	416948.728	5104299.224	436.82	0.03
3005	417300.501	5073406.91	346.442	0.022
3006	417298.452	5073371.15	346.402	0.022
3007	417282.574	5073349.367	346.394	0.064

Table 5.7: QA/QC Analysis, Urban, UTM 16N, NAD83, Dickinson County, MI

Point ID	Easting (UTM meters)	Northing (UTM meters)	Elevation (meters)	Absolute Dz (meters)
3008	417281.22	5073320.357	346.392	0.032
3009	417280.821	5073285.437	346.042	0.018
3010	417280.369	5073257.611	345.861	0.001
3011	419466.226	5073561.745	349.969	0.021
3012	419485.05	5073536.121	349.375	0.025
3500	439468.134	5106463.139	347.066	0.004
3501	439403.708	5106430.876	347.094	0.016
3502	439391.017	5106148.539	347.504	0.006
3503	439368.733	5106025.345	347.643	0.047
3504	439390.205	5106005.337	348.196	0.004
3505	439383.384	5106231.93	347.262	0.038
3506	435757.73	5093980.206	356.818	0.072
3507	436061.05	5094011.147	362.079	0.061
3508	436151.586	5093985.102	364.078	0.008
3509	429065.048	5071048.096	284.812	0.002
3510	432185.809	5070150.608	287.76	0.03
3511	436600.845	5069761.375	272.128	0.002

ACCURACY CONCLUSIONS


Urban Land Cover Classification Supplemental Vertical Accuracy (SVA) Tested 0.103 meters supplemental vertical accuracy at the 95th percentile in Urban. Tested against the DEM. Urban Errors larger than 95th percentile include:

- Point 3000, Easting 416853.012, Northing 5104249.497, Z-Error 0.116 meters

CONSOLIDATED ACCURACY CONCLUSIONS

Consolidated Vertical Accuracy (CVA) Tested 0.144 meters consolidated vertical accuracy at the 95th percentile level, derived according to ASPRS Guidelines for Vertical Accuracy Reporting for LiDAR Data. The data set was tested against the DEM using independent test points, based on the 95th percentile error in all land cover categories combined.

- Point 5513, Easting 441917.477, Northing 5112063.114, Z-Error 0.150 meters
- Point 4509, Easting 436809.320, Northing 5069306.935, Z-Error 0.164 meters
- Point 6016, Easting 425806.637, Northing 5077849.950, Z-Error 0.166 meters
- Point 5508, Easting 438317.864, Northing 5085329.893, Z-Error 0.174 meters
- Point 5015, Easting 421185.939, Northing 5085426.440Z-Error 0.179 meters
- Point 4515, Easting 435918.421, Northing 5093879.932 Z-Error 0.216 meters
- Point 6025, Easting 416082.683, Northing 5093809.445 Z-Error 0.254 meters

Approved By:			
Title	Name	Signature	Date
Associate LiDAR Specialist Certified Photogrammetrist #1281	Qian Xiao		June 1, 2013

SECTION 6: FINAL DELIVERABLES

FINAL DELIVERABLES

The final LiDAR deliverables are listed below:

- LAS v1.2 classified point cloud
- LAS v1.2 raw unclassified point cloud flight line strips no greater than 2GB (long swaths greater than 2GB will be split into segments)
- Hydrologically flattened Polygon z and Polyline z shapefiles
- Hydrologically flattened bare earth 1-meter DEM in ERDAS .img format
- Tile Layout and data extent provided as ESRI shapefile
- Control points provided as ESRI shapefile
- FGDC compliant metadata per product in XML format
- LiDAR processing report in pdf format
- Survey report in pdf format



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