# LIDAR REMOTE SENSING DATA COLLECTION DEPARTMENT OF GEOLOGY AND MINERAL INDUSTRIES MALHEUR, OREGON

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Submitted to:

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Department of Geology and Mineral Industries 800 NE Oregon Street, Suite 965 Portland, OR 97232



Submitted by:

Watershed Sciences 529 SW 3<sup>rd</sup> Avenue, Suite 300 Portland, OR 97204



# LIDAR REMOTE SENSING DATA COLLECTION: DOGAMI, MALHEUR STUDY AREA

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## 1. Overview

### 1.1 Study Area (Malheur)

Watershed Sciences, Inc. is currently collecting Light Detection and Ranging (LiDAR) data of the Malheur study area for the Oregon Department of Geology and Mineral Industries (DOGAMI). The area of interest (AOI) totals 399 square miles (255,300 acres) and the total area to fly (TAF) covers 409 square miles (261,732 acres). The TAF acreage is greater than the original AOI acreage due to buffering and flight planning optimization (**Figure 1.1** below). The DOGAMI study area will be acquired and processed as logistical constraints and weather allow. This report will be amended to reflect new data and cumulative statistics for the overall LiDAR survey. DOGAMI data are *delivered* in OGIC(HARN): Projection: Oregon Statewide Lambert Conformal Conic; horizontal and vertical datums: NAD83 (HARN)/NAVD88(Geoid03); Units: International Feet.





For Delivery 1 of the Malheur study area, the AOI totals 132,104 acres (206 square miles) and the TAF totals 134,922 acres (211 square miles). Figure 1.2 below displays the TAF and AOI for Delivery 1.



Figure 1.2. Malheur study area, illustrating the portion delivered to date.



Figure 1.3. Malheur study area, illustrating TAF for the entire study area.



Figure 1.4. Actual flightlines for Delivery 1 including dates flown for the Malheur study area.



Figure 1.5. Base station and real time kinematic locations for the Malheur study area (Delivery 1).

**Table 1.1.** Base Station Surveyed Coordinates, (NAD83/NAVD88, OPUS corrected) used for kinematic post-processing of the aircraft GPS data for the Malheur study area.

	Datum	GRS80	
Base Station ID	Latitude (North)	Longitude (West)	Ellipsoid Height (m)
JDSW1	44 01 35.70835	118 55 58.47038	1379.296
JDNW1	44 09 21.26537	118 58 36.18625	1407.882

## 2. Accuracy

#### 2.1 Relative Accuracy Calibration Results

Relative accuracy statistics are based on the comparison of 201 flightlines and over 2 billion points for data acquired to date.

- Project Average = 0.07ft (0.02m)
- Median Relative Accuracy = 0.14ft (0.04m)
- $\circ$  1 $\sigma$  Relative Accuracy = 0.15ft (0.05m)
- $\circ$  2 $\sigma$  Relative Accuracy = 0.22ft (0.07m)







Figure 2.2. Percentage distribution of relative accuracies, non slope-adjusted.

#### 2.2 Absolute Accuracy

Absolute accuracy compares known Real Time Kinematic (RTK) ground survey points to the closest laser point. For the Malheur study area, 1,619 RTK points were collected. Accuracy statistics are reported in **Table 2.1** and shown in Figures **2.3-2.4**.

Table 2.1.	Absolute Accuracy -	Deviation between	laser points and RTM	survey points.
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Sample Size (n): 1,619			
Root Mean Square Error (RMSE): 0.10 feet			
Standard Deviations	Deviations		
<b>1 sigma (σ):</b> 0.10 feet	Minimum Δz: -0.31 feet		
<b>2 sigma (σ):</b> 0.19 feet	Maximum Δz: 0.31 feet		
	Average Δz: 0.08 feet		

Figure 2.3. Malheur Study area histogram statistics





Figure 2.4. Malheur study area point absolute deviation statistics.

# 3. Data Density/Resolution

Some types of surfaces (i.e., dense vegetation or water) may return fewer pulses than the laser originally emitted. Therefore, the delivered density can be less than the native density and vary according to distributions of terrain, land cover and water bodies. Density histograms and maps (Figures 3.1 - 3.4) have been calculated based on first return laser point density and ground-classified laser point density.

 Table 3.1. Average density statistics for Malheur data delivered to date.

Average Pulse	Average Pulse	Average Ground	Average Ground
Density	Density	Density	Density
(per square ft)	(per square m)	(per square ft)	(per square m)
0.73	7.87	0.15	

Figure 3.1. Histogram of first return laser point density for data delivered to date.



Figure 3.2. Image shows first return laser point per 0.75' USGS Quad for data delivered to date.



Ground classifications were derived from ground surface modeling. Supervised classifications were performed by reseeding of the ground model where it was determined that the ground model failed, usually under dense vegetation and/or at breaks in terrain, steep slopes and at bin boundaries.



Figure 3.3. Histogram of ground-classified laser point density for data delivered to date.

<u>Pts</u>

<u>Pts</u>





## 4. Selected Imagery

Selected imagery for the Malheur study area will be provided in the final data report.