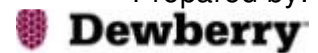


LiDAR Quality Assurance (QA) Report
2010 South Carolina Consortium Project
Lexington County
December 6, 2011

Submitted to:
South Carolina Department of Natural Resources

Prepared by:



Executive Summary

The following LiDAR quality assurance report documents Dewberry’s review of LiDAR data and derived products for Lexington County, South Carolina. This is the first review of the Lexington data. The data was flown by Sanborn for the 2010 SC LiDAR Consortium Project. The figure below shows Lexington County and the adjoining South Carolina counties (Figure 1).

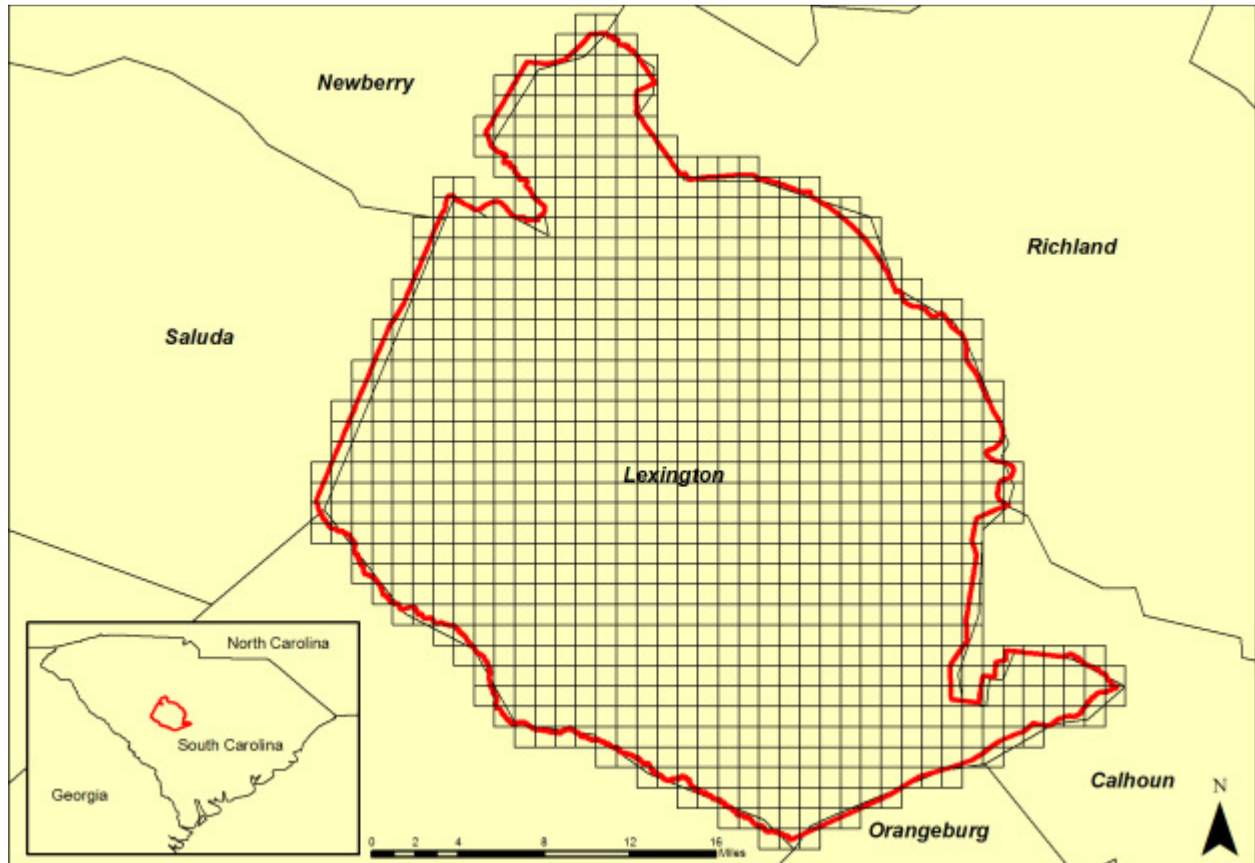


Figure 1 - Location of Lexington County overlaid by delivered LAS grid.

Lexington County is approximately 759 square miles which amounts to 940 LAS tiles (5000’ x 5000’). The delivered LAS files provide full coverage to the extent of the county as illustrated in the figure above. Each tile contains LAS point cloud data classified according to the ASPRS classification scheme.

The final deliverables also include an ESRI Geodatabase containing hydrographic breaklines and terrain, a DEM in Arc GRID format, and individual intensity images per tile.

The LiDAR data has been classified to contain the appropriate classes:

- Required Classes
- ~~AWZAC~~ Class 1 (Unclassified)
- ~~AWZAC~~ Class 2 (Bare Earth)
- ~~AWZAC~~ Class 7 (Noise)
- ~~AWZAC~~ Class 8 (Model Key Points)
- ~~AWZAC~~ Class 9 (Water)
- ~~AWZAC~~ Class 10 (Points removed from Bridges and Culverts)
- ~~AWZAC~~ Class 11 (Ignored Ground)

LiDAR Quantitative Review

One of the first steps in assessing the quality of the LiDAR is a vertical accuracy analysis of the ground models in comparison to surveyed checkpoints. South Carolina Geodetic Survey provided 138 checkpoints for the county area.

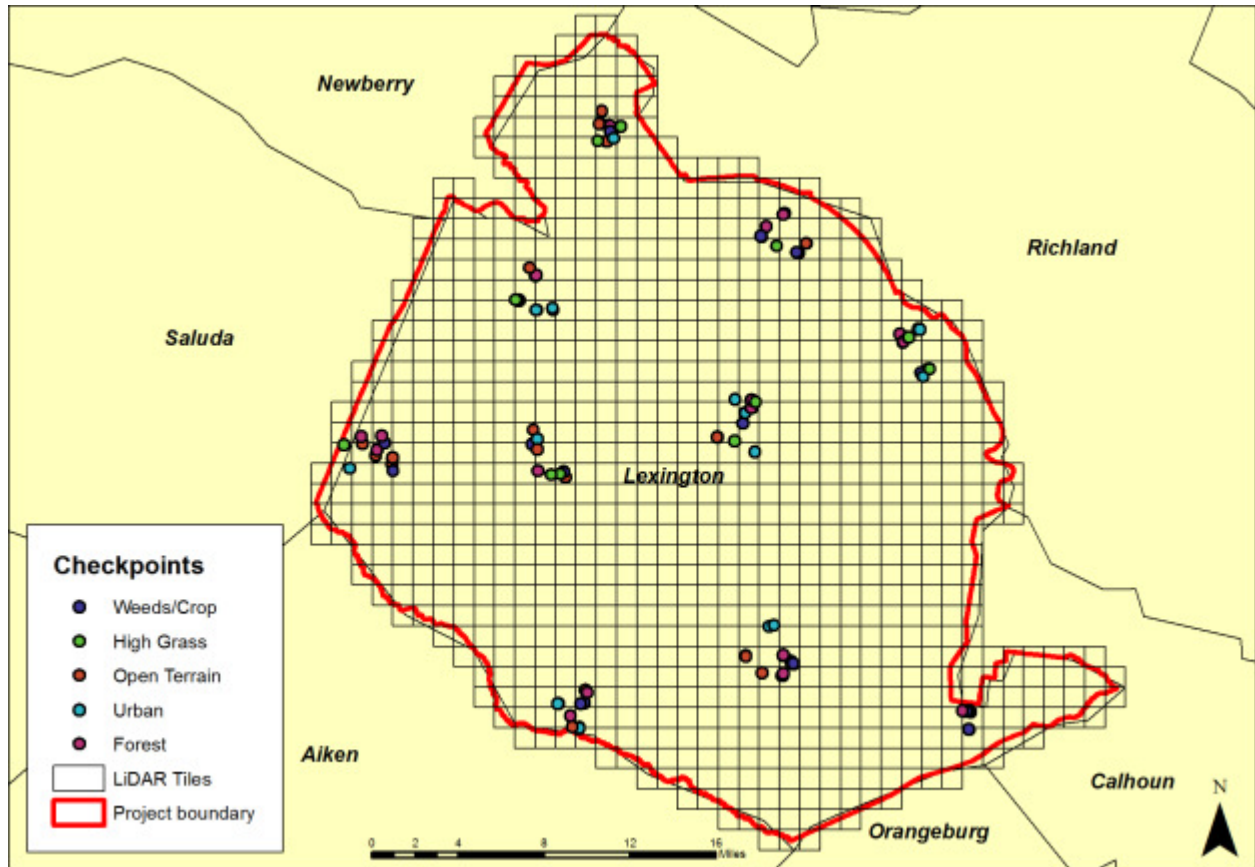


Figure 3 - Checkpoint Distribution of Lexington County, SC.

The vertical accuracy assessment compares the measured survey checkpoint elevations with those of the TIN as generated from the bare-earth LiDAR. The X/Y locations of the survey checkpoints are overlaid on the TIN and the interpolated Z values of the LiDAR are recorded. These interpolated Z values are then compared with the survey checkpoint Z values and this difference represents the amount of error between the measurements. Once all the Z values are recorded, the Root Mean Square Error (RMSE) is calculated and the vertical accuracy scores are interpolated from the RMSE value. The RMSE equals the square root of the

