General Information

Mission Information

Project name	200703_A_5060380_nad2011_FINAL
Processing date	2020-07-06 14:22:43
Mission date	2020-07-03 13:16:20
Mission duration	05:30:11.000
Processing mode	IN-Fusion PP-RTX

Rover Hardware Information

Product	POS AV 610 VER6 HW2.5-12
Serial number	S/N7769
IMU type	57
Receiver type	BD982
Antenna type	AV39

Project File List

Rover Data Files

File name	File type
200703_a.025	POS Data
200703_a.026	POS Data
200703_a.027	POS Data
200703_a.028	POS Data
200703_a.029	POS Data
200703_a.030	POS Data
200703_a.031	POS Data
200703_a.032	POS Data
200703_a.033	POS Data
200703_a.034	POS Data
200703_a.035	POS Data
200703_a.036	POS Data
200703_a.037	POS Data
200703_a.038	POS Data
200703_a.039	POS Data
200703_a.040	POS Data
200703_a.041	POS Data
200703_a.042	POS Data
200703_a.043	POS Data
200703_a.044	POS Data
200703_a.045	POS Data
200703_a.046	POS Data
200703_a.047	POS Data
200703_a.048	POS Data
200703_a.049	POS Data
200703_a.050	POS Data
200703_a.051	POS Data
200703_a.052	POS Data
200703_a.053	POS Data
200703_a.054	POS Data
200703_a.055	POS Data

Input Files

File Name	File Type
Ephm1850.20g	GLONASS Broadcast Ephemeris
Ephm1850.20n	GPS Broadcast Ephemeris

Output Files

Filename	File type
sbet_200703_A_5060380_nad2011_FINAL.out	SBET Trajectory File
sbet_200703_A_5060380_nad2011_FINAL.shp	Shapefile Export Output

Rover Data Summary

First raw data file	200703_a.025		
Last raw data file	200703_a.055		
Start GPS week	2112		
Start time	479784.694 (07/03/2020 13:16:24)		
End time	499588.412 (07/03/2020 18:46:28)		
Start of fine alignment	480056.509 (07/03/2020 13:20:56)		
Available subsystems	Primary GNSS, IMU		
POS Event Input	Event 1 Input		
Correction data	None		
IMU Installation Lever Arms & Mounting Angles			
Reference to IMU lever arm (m)	0.000	0.000	0.000
Reference to IMU mounting angles (deg)	0.000	0.000	180.000
Reference to Primary GNSS lever arm (m)	0.556	-0.429	-0.965
Reference to Primary GNSS lever arm std dev (m)	-1.000		
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

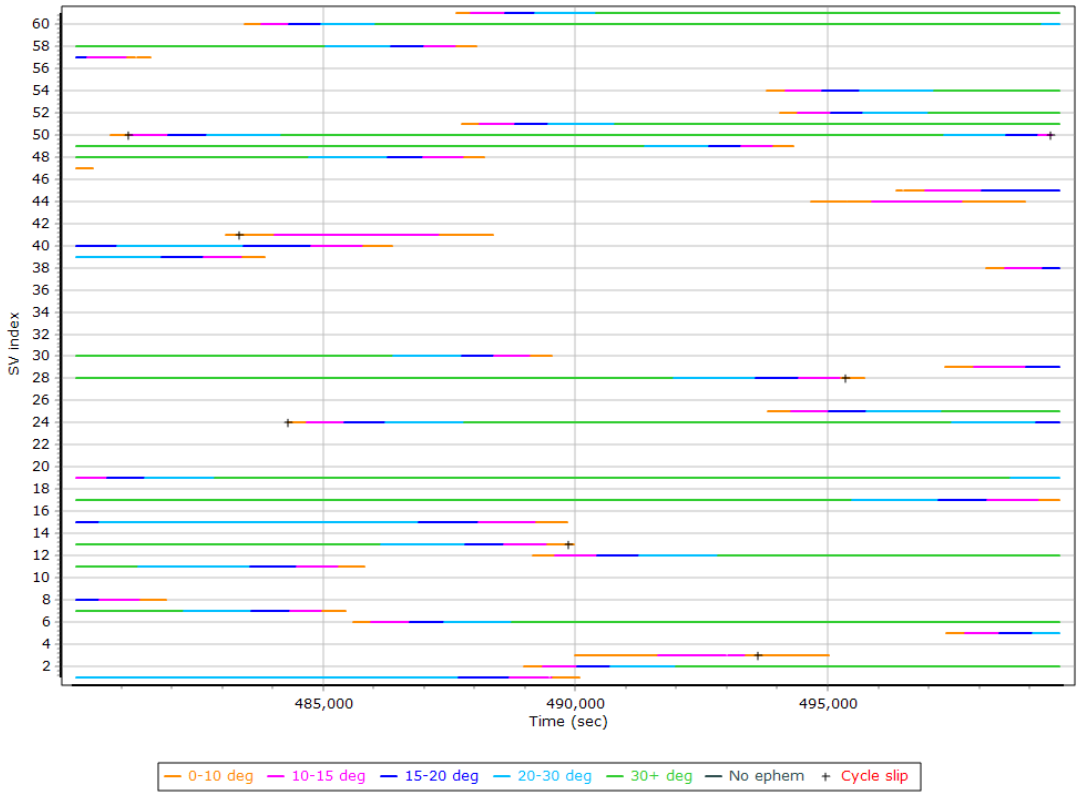
Rover Data QC

Raw IMU Import QC Summary

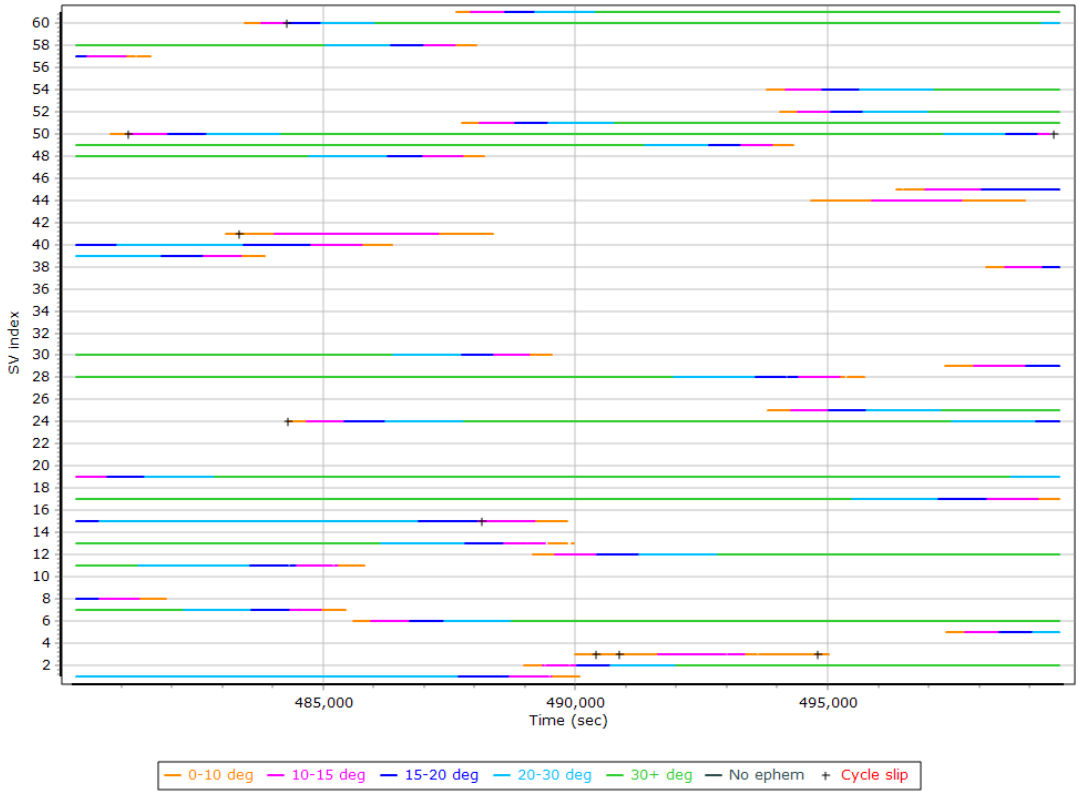
IMU data input file	imu_200703_A_5060380_nad2011_FINAL.dat
IMU data check log file	imudt_200703_A_5060380_nad2011_FINAL.log
IMU Records Processed	3961963
Termination Status	Warnings
IMU Anomalies	1
IMU Failure Messages	
479784.449 : WARNING : Gap of 479762.4564 seconds in CHECKDT input data	

Primary Observables & Satellite Data

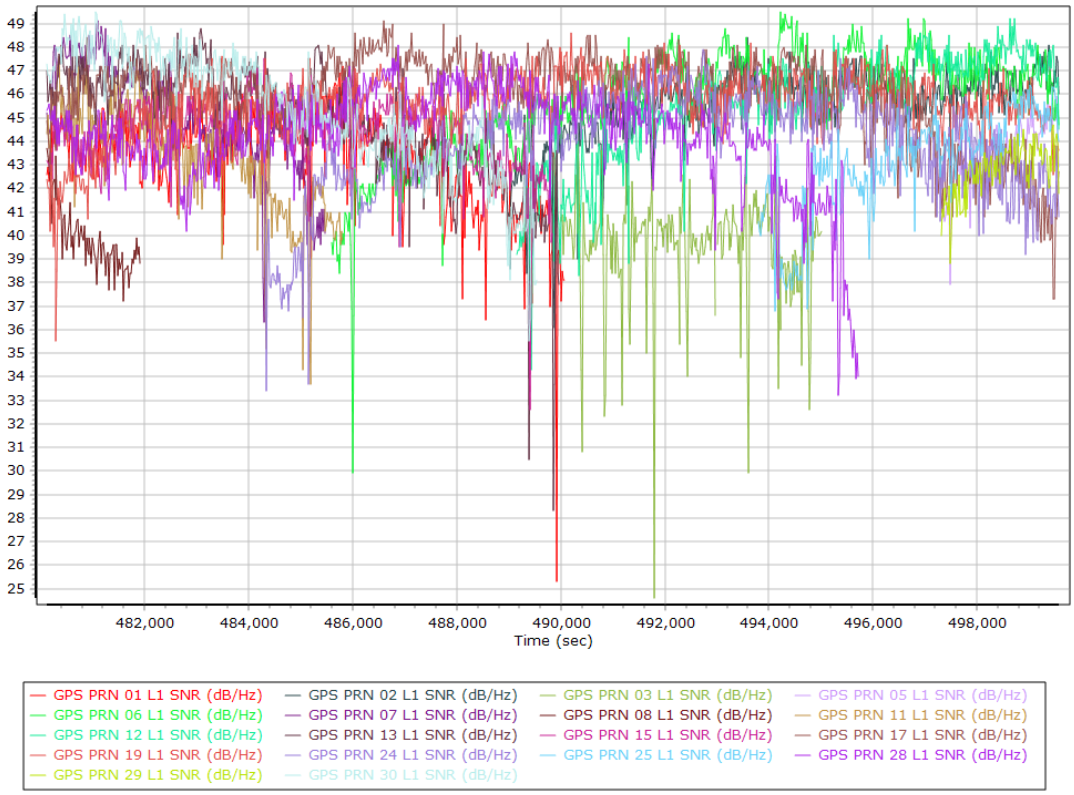
L1 Satellite Lock/Elevation



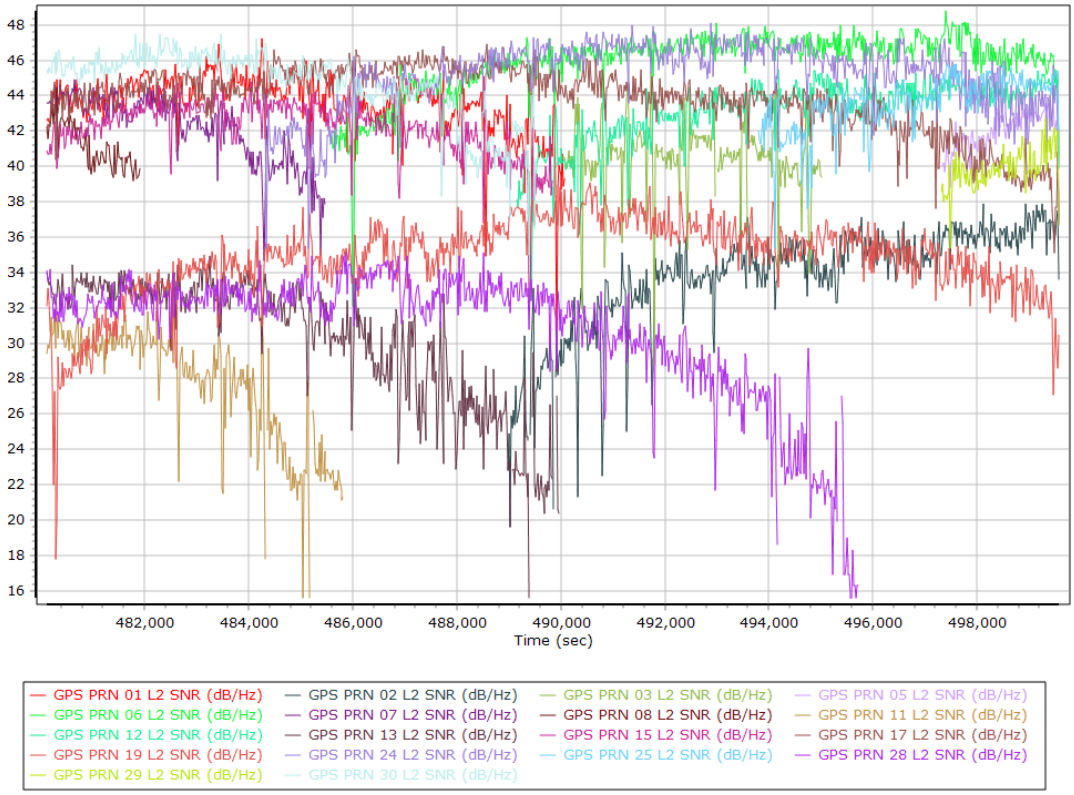
L2 Satellite Lock/Elevation



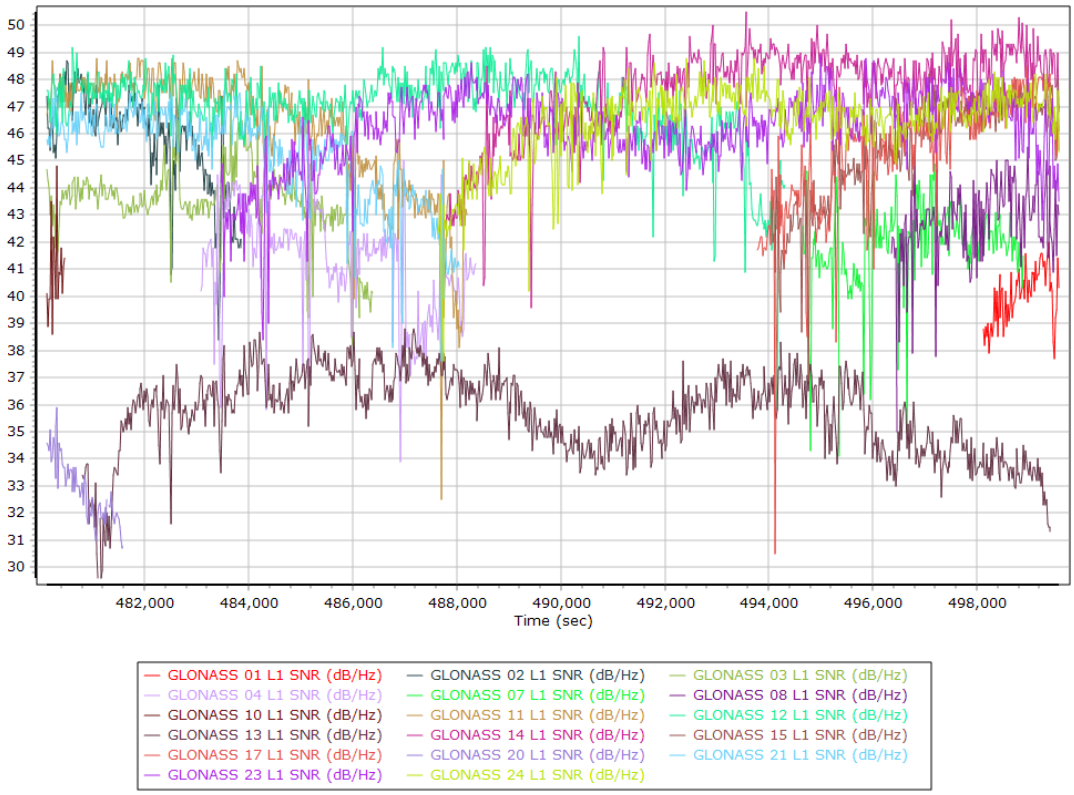
GPS L1 SNR



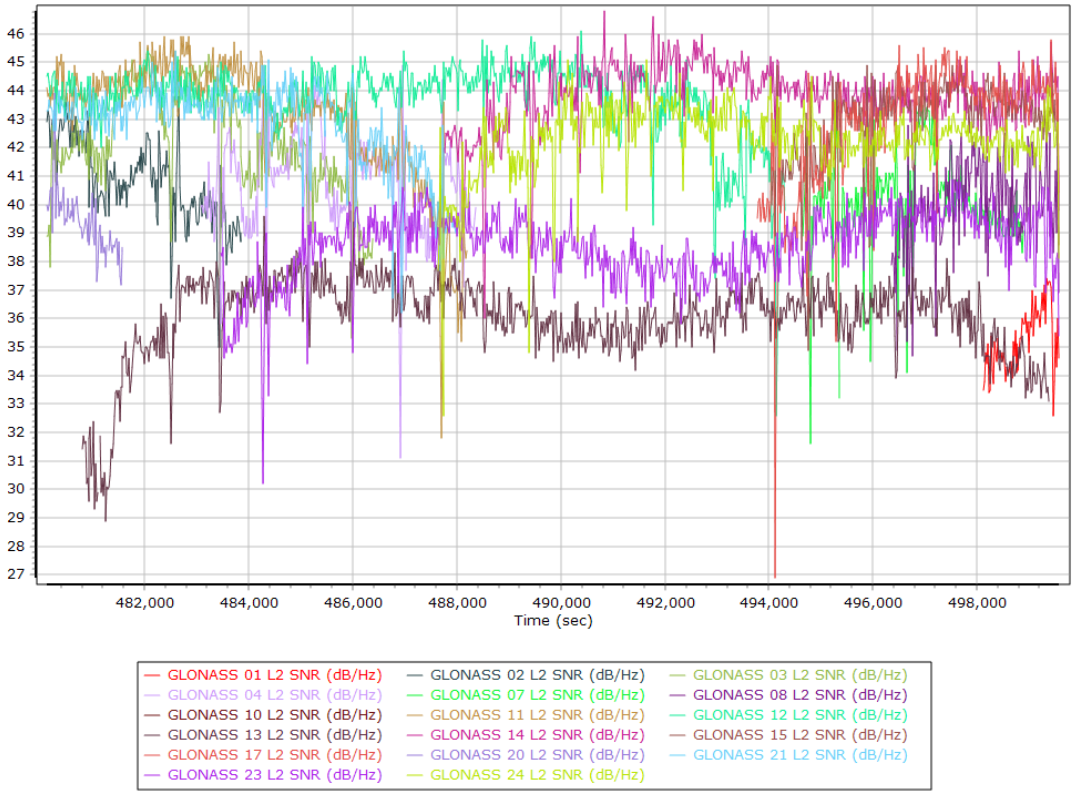
GPS L2 SNR



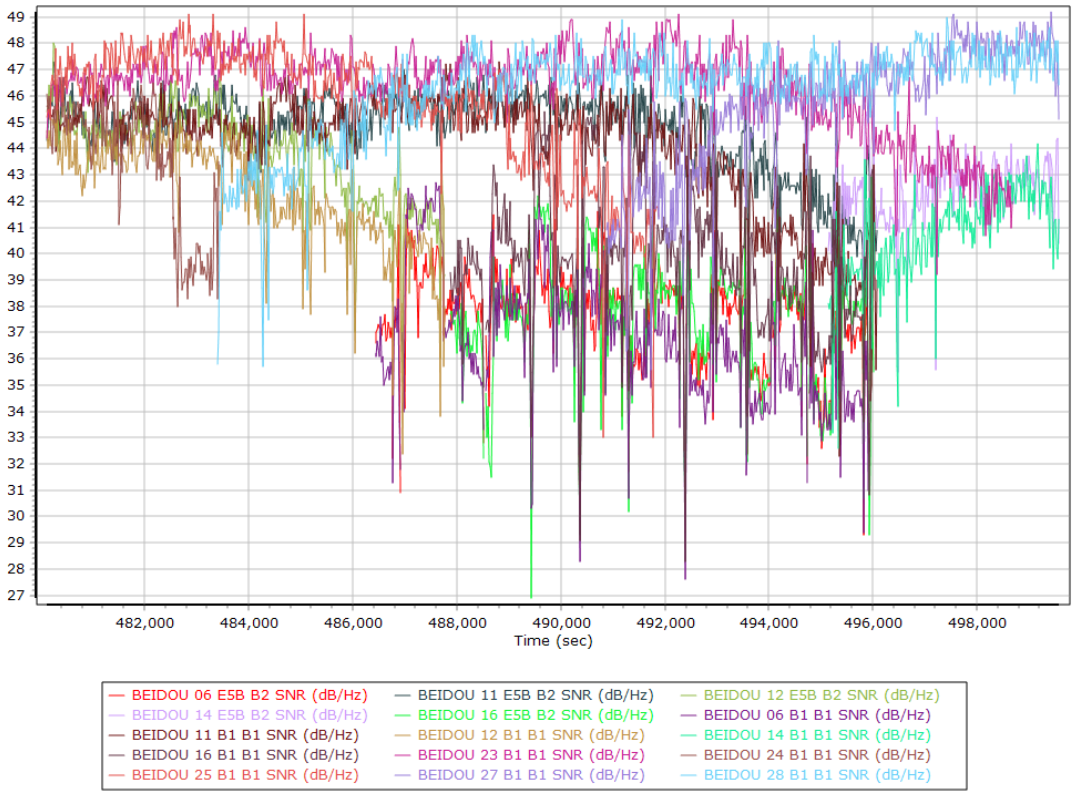
GLONASS L1 SNR



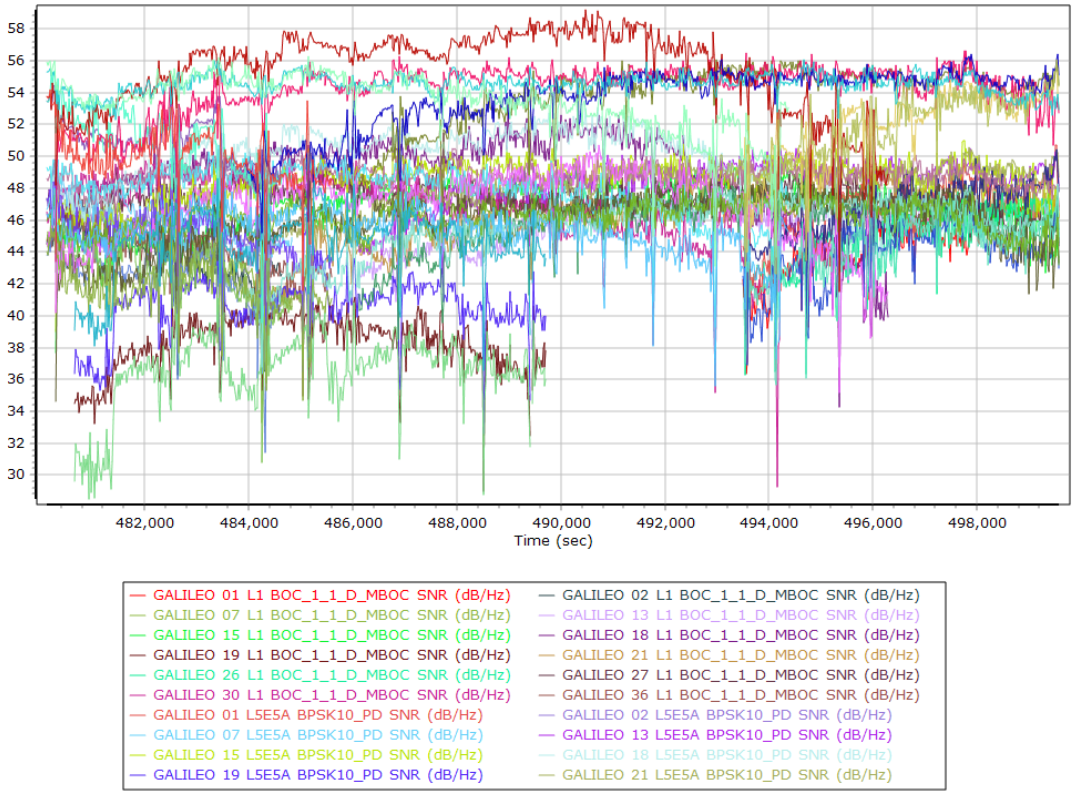
GLONASS L2 SNR



BEIDOU SNR



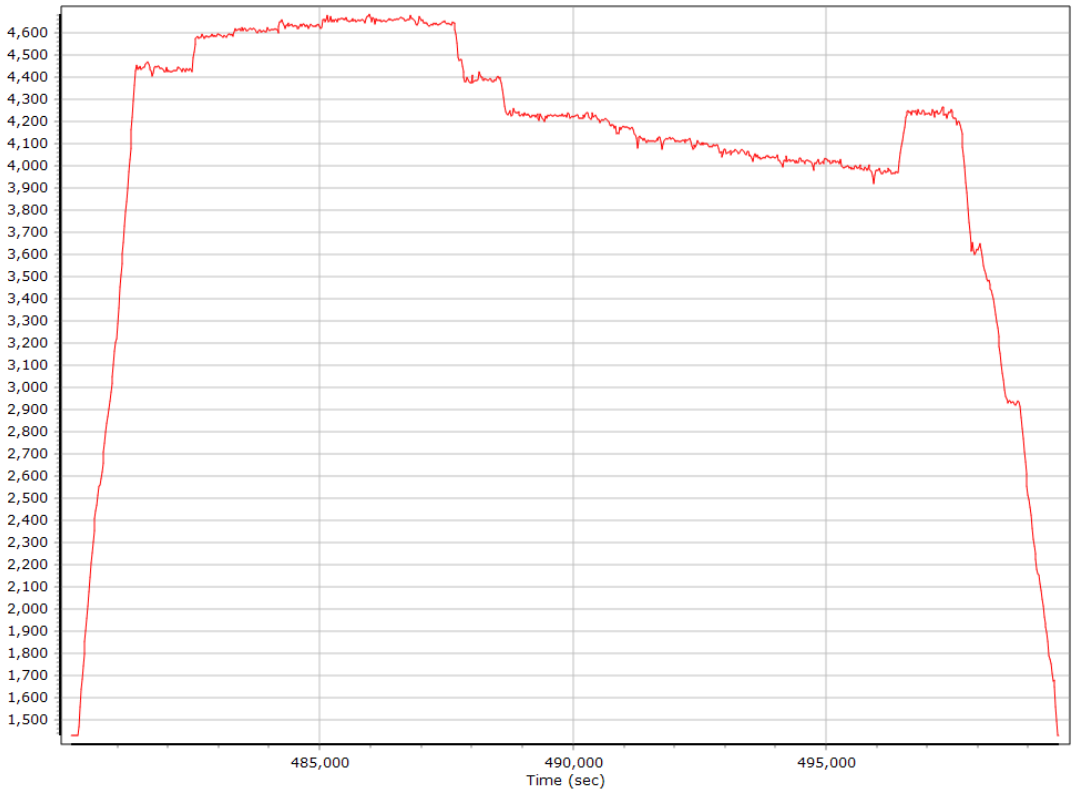
GALILEO SNR


58
56
54
52
50
48
46
44
42
40
38
36
34
32
30
482,000
484,000
486,000
488,000
490,000
492,000
494,000
496,000
498,000
Time (sec)
GALILEO 01 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 02 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 07 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 13 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 15 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 18 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 19 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 21 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 26 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 27 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 30 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 36 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 01 L5E5A BPSK10_PD SNR (dB/Hz)
GALILEO 02 L5E5A BPSK10_PD SNR (dB/Hz)
GALILEO 07 L5E5A BPSK10_PD SNR (dB/Hz)
GALILEO 13 L5E5A BPSK10_PD SNR (dB/Hz)
GALILEO 15 L5E5A BPSK10_PD SNR (dB/Hz)
GALILEO 18 L5E5A BPSK10_PD SNR (dB/Hz)
GALILEO 19 L5E5A BPSK10_PD SNR (dB/Hz)
GALILEO 21 L5E5A BPSK10_PD SNR (dB/Hz)

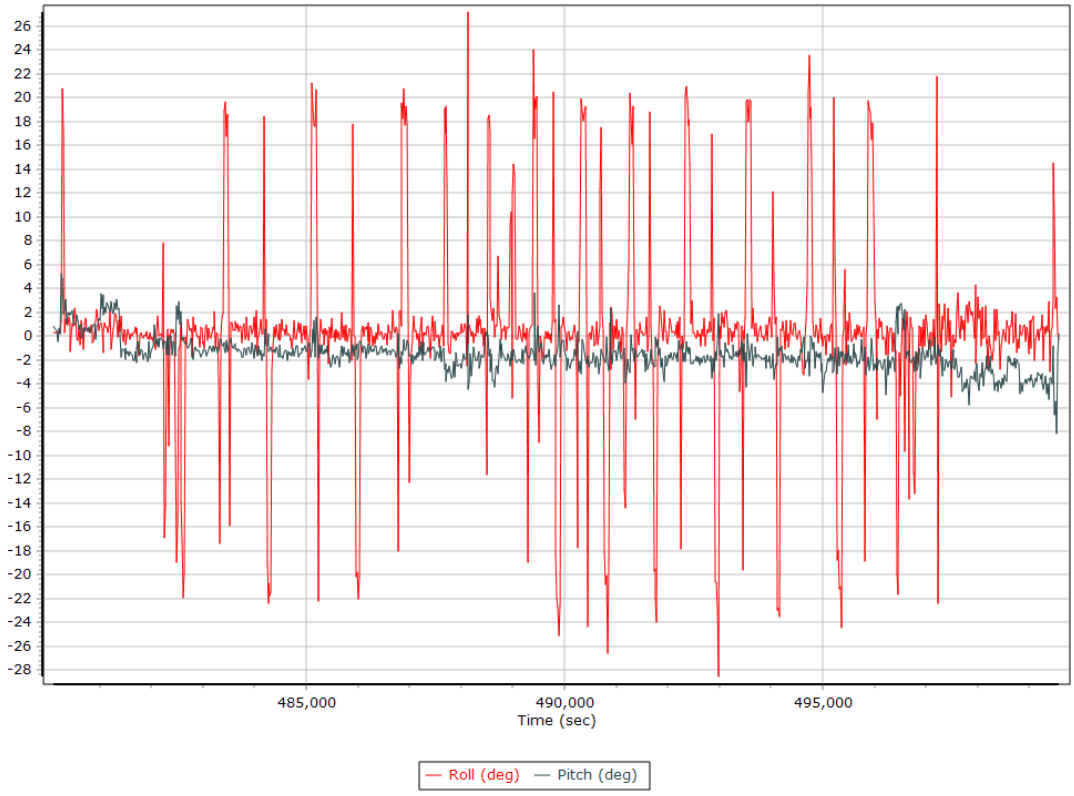
Smoothed Trajectory Information

Top View

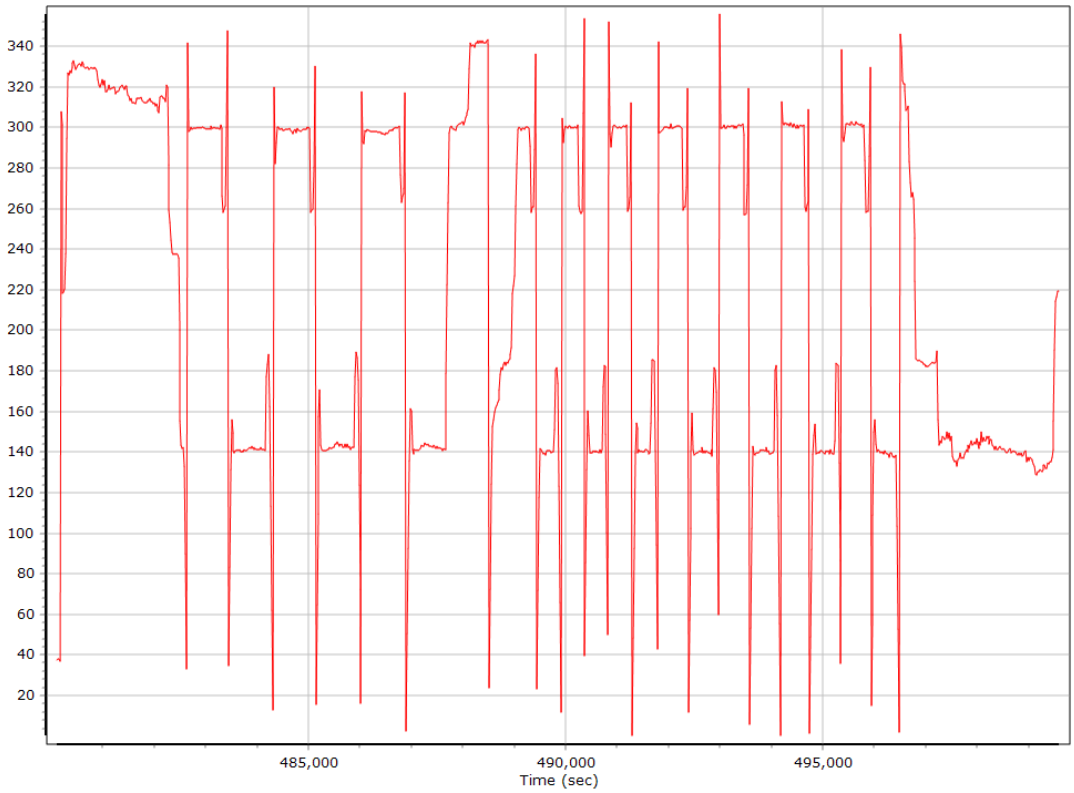
Altitude



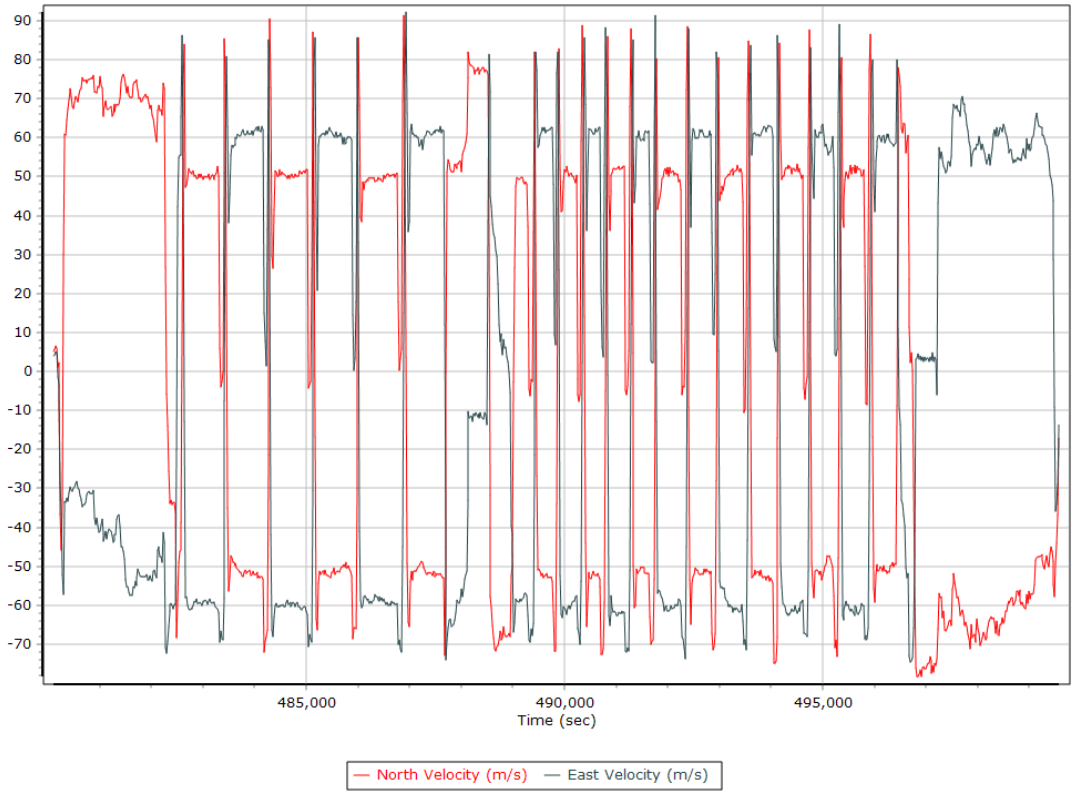
Roll/Pitch



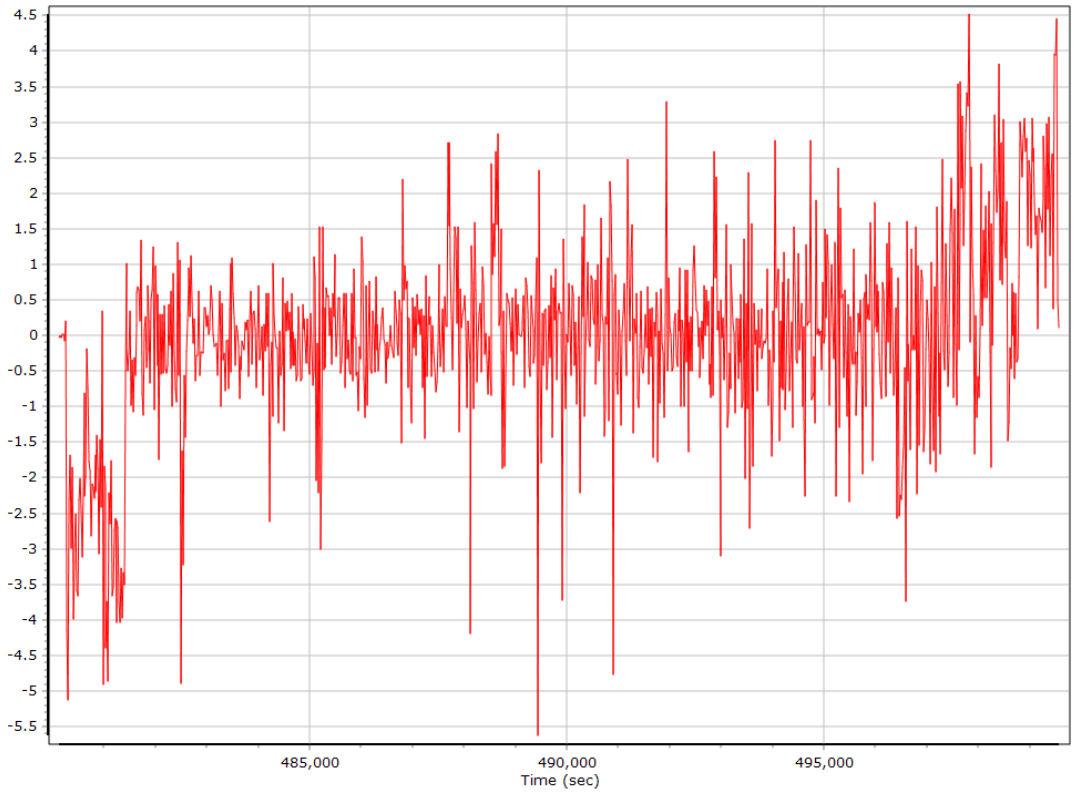
Heading



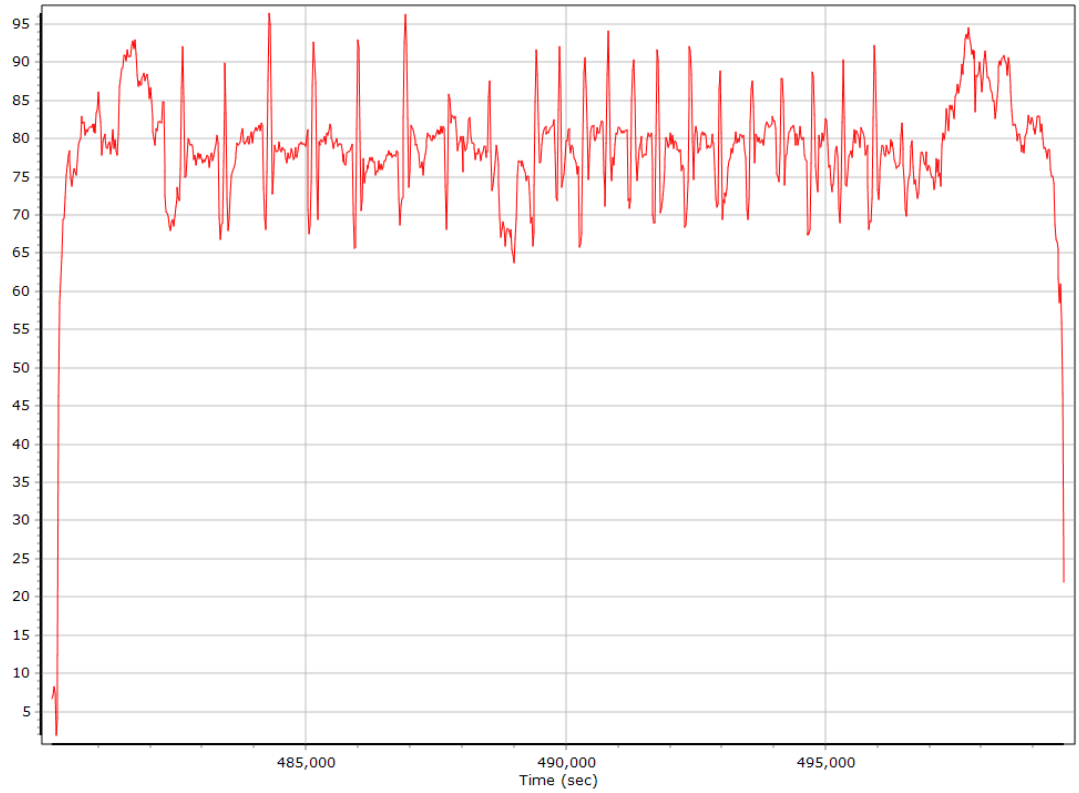
North/East Velocity



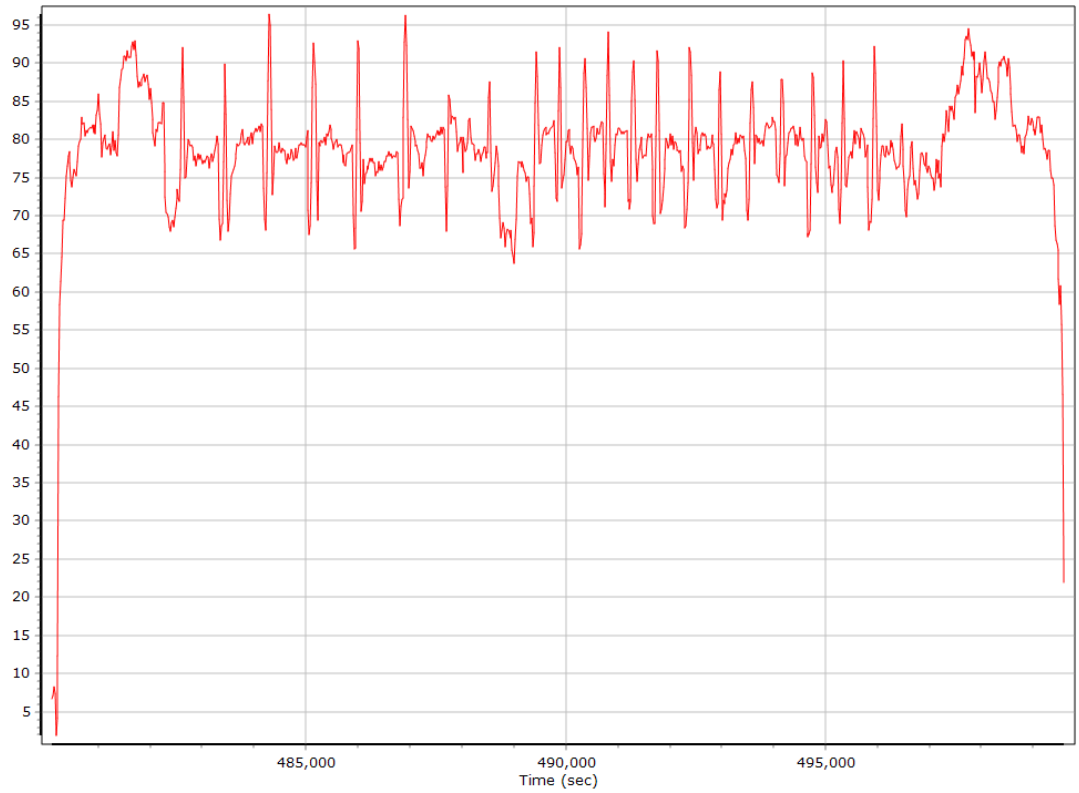
Down Velocity



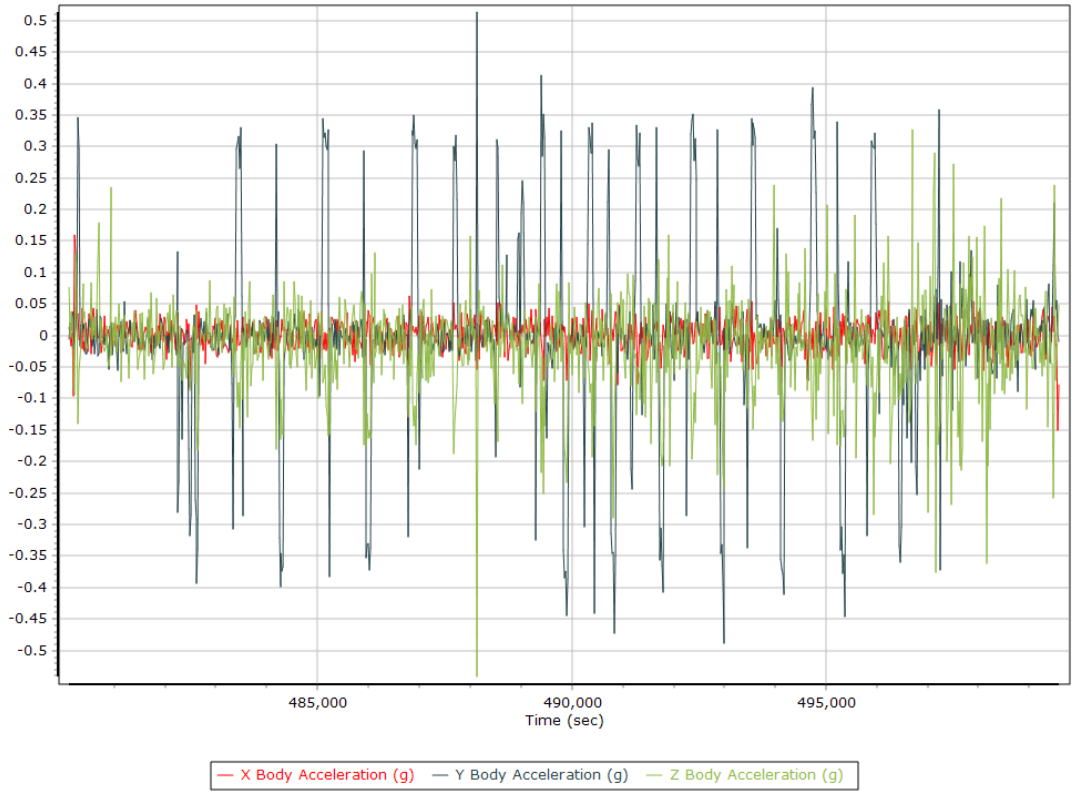
Total Speed



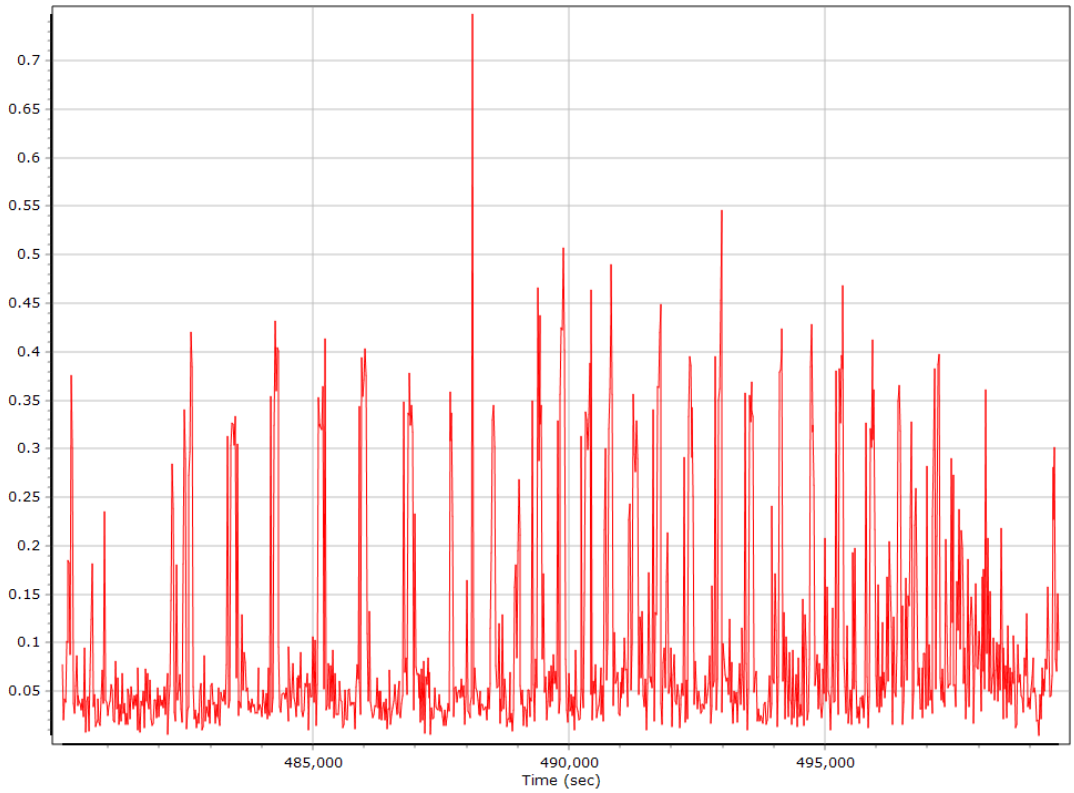
Ground Speed



Body Acceleration



Total Body Acceleration

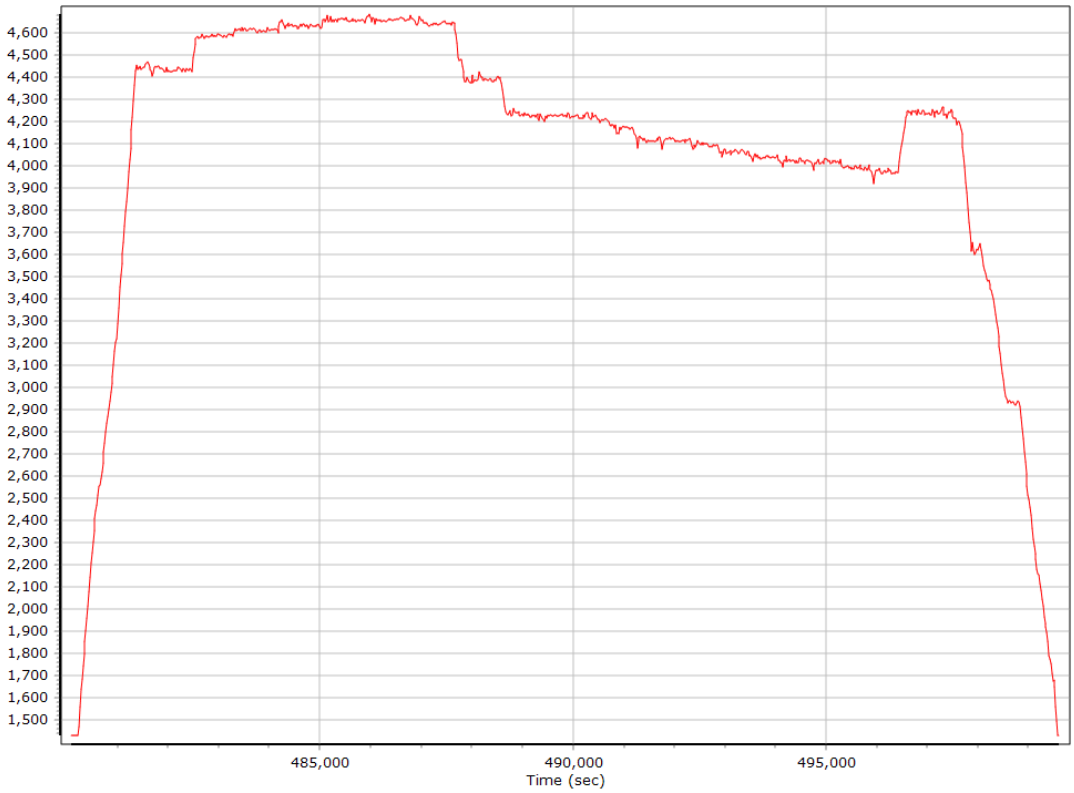


Body Angular Rate

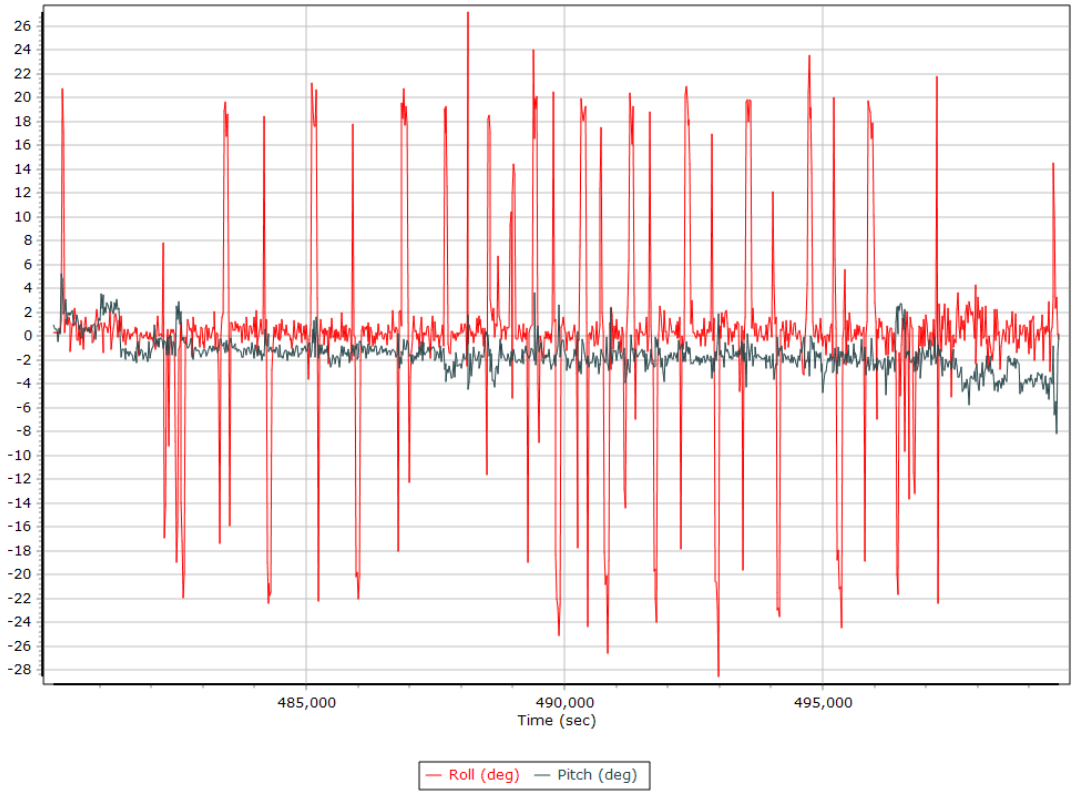
Forward Processed Trajectory Information

Top View

Altitude



Roll/Pitch



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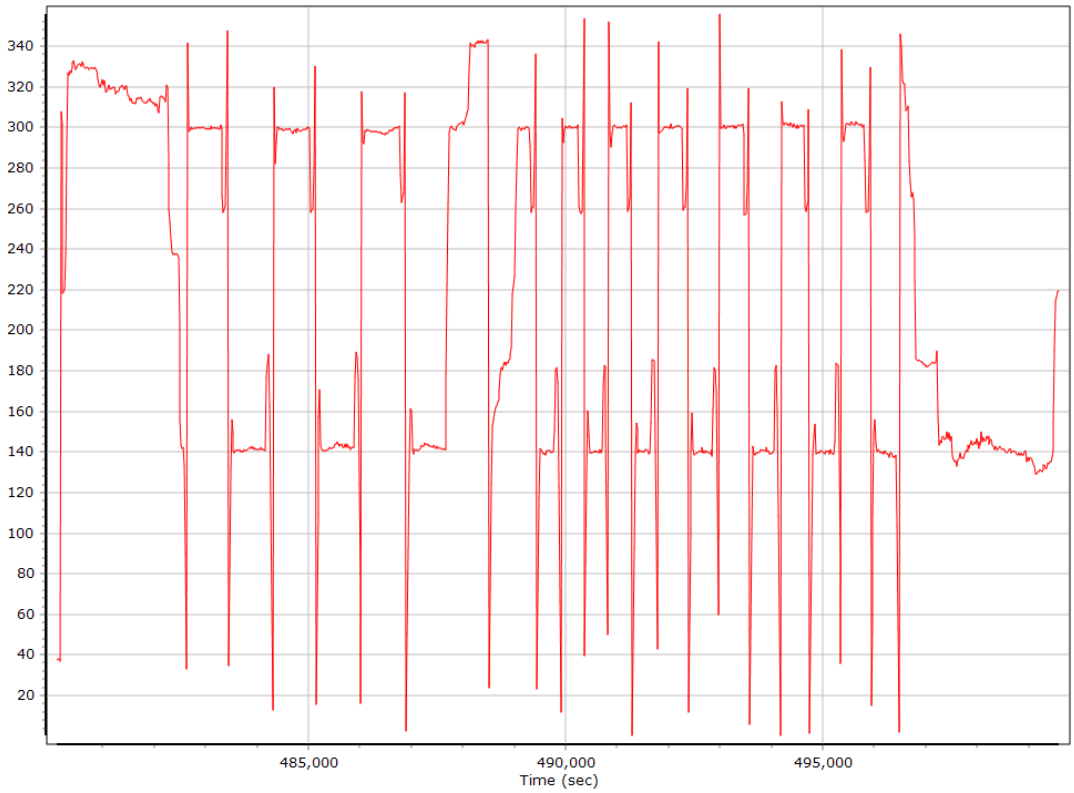
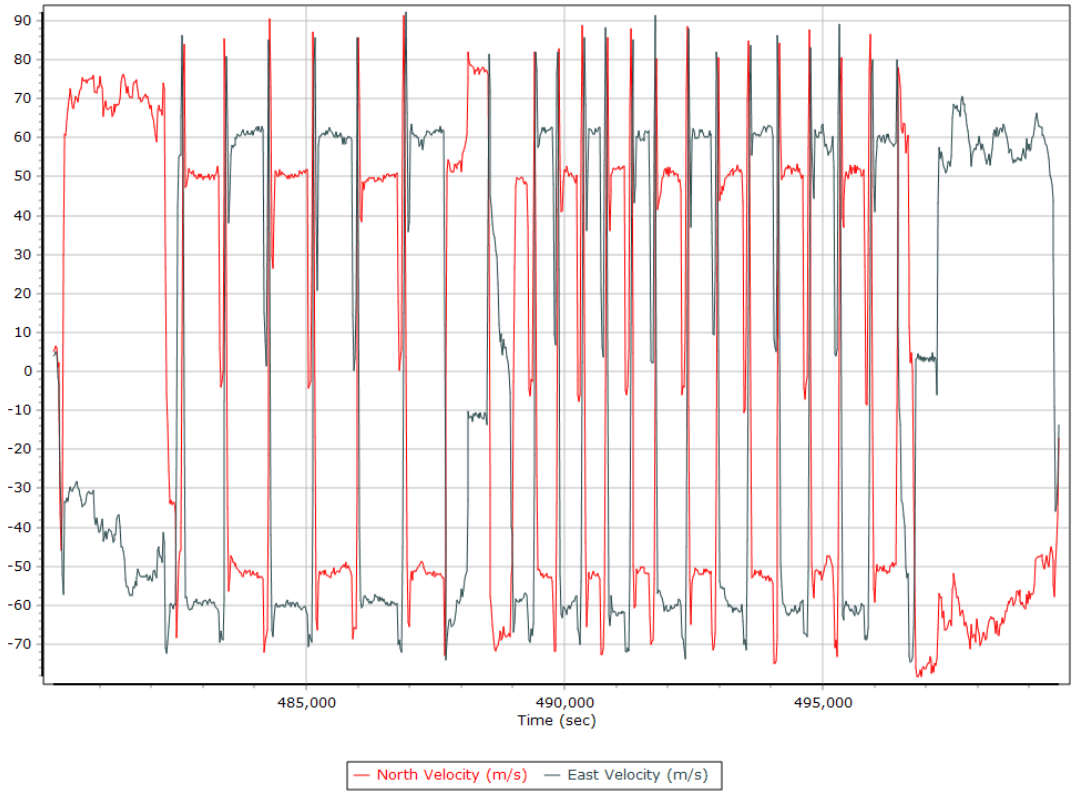
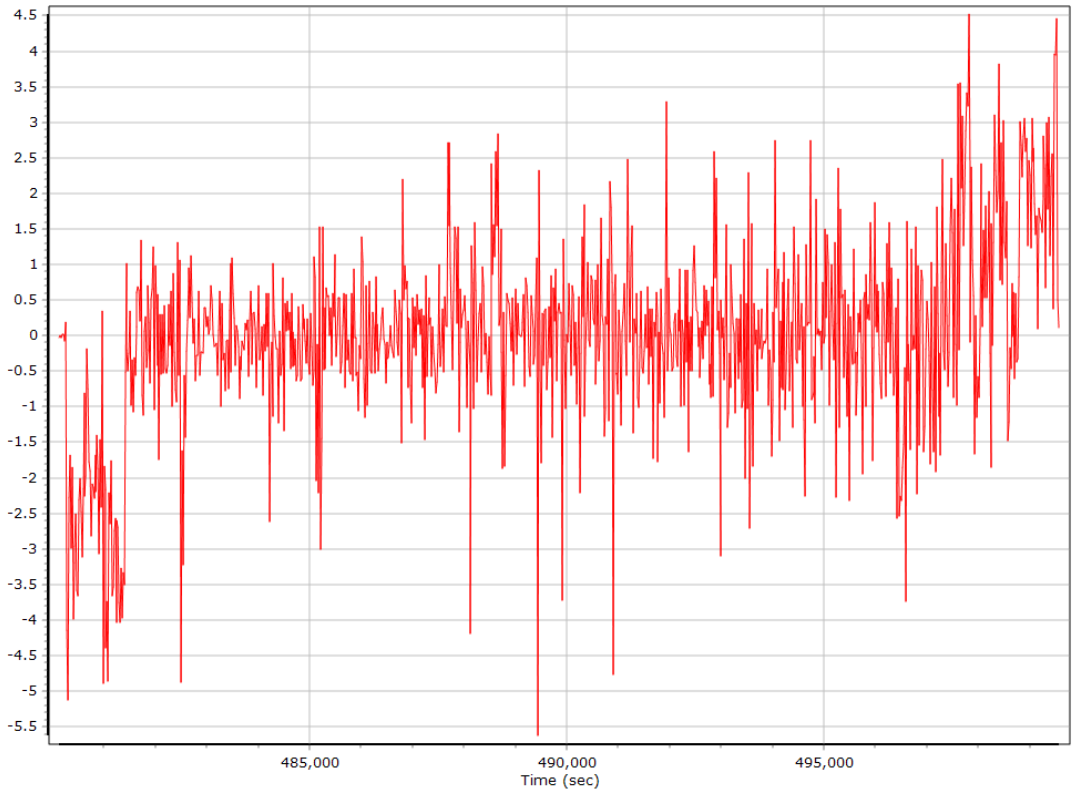


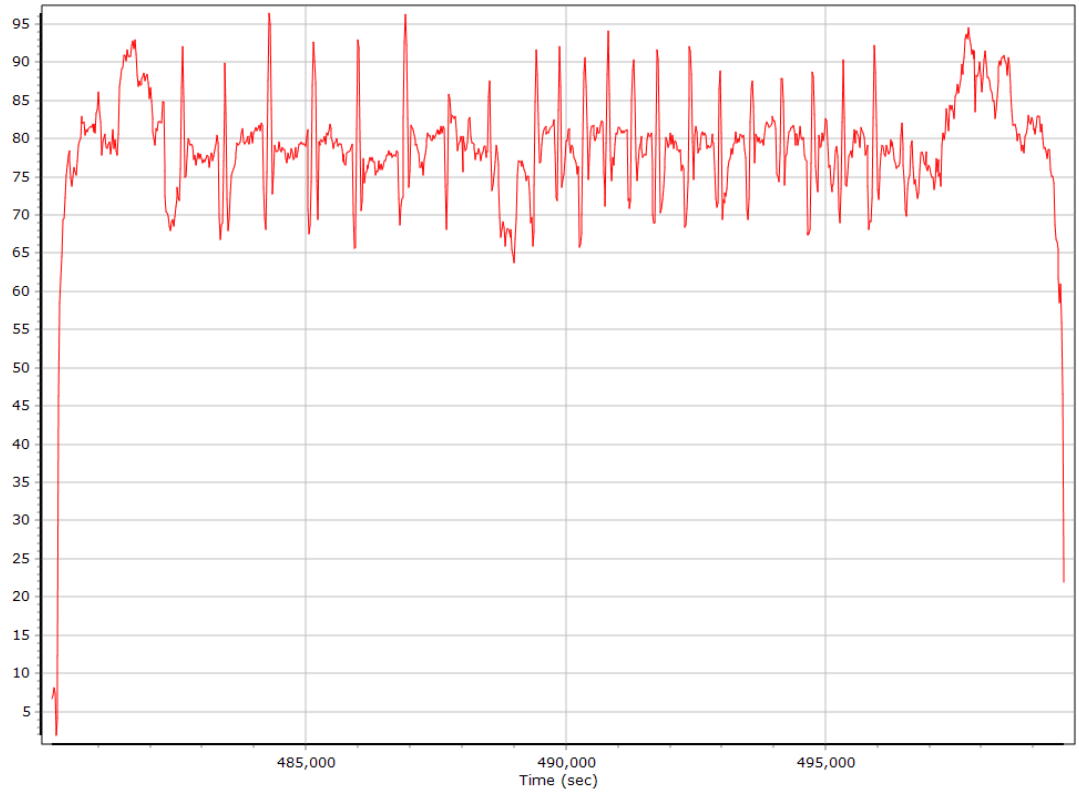
North/East Velocity



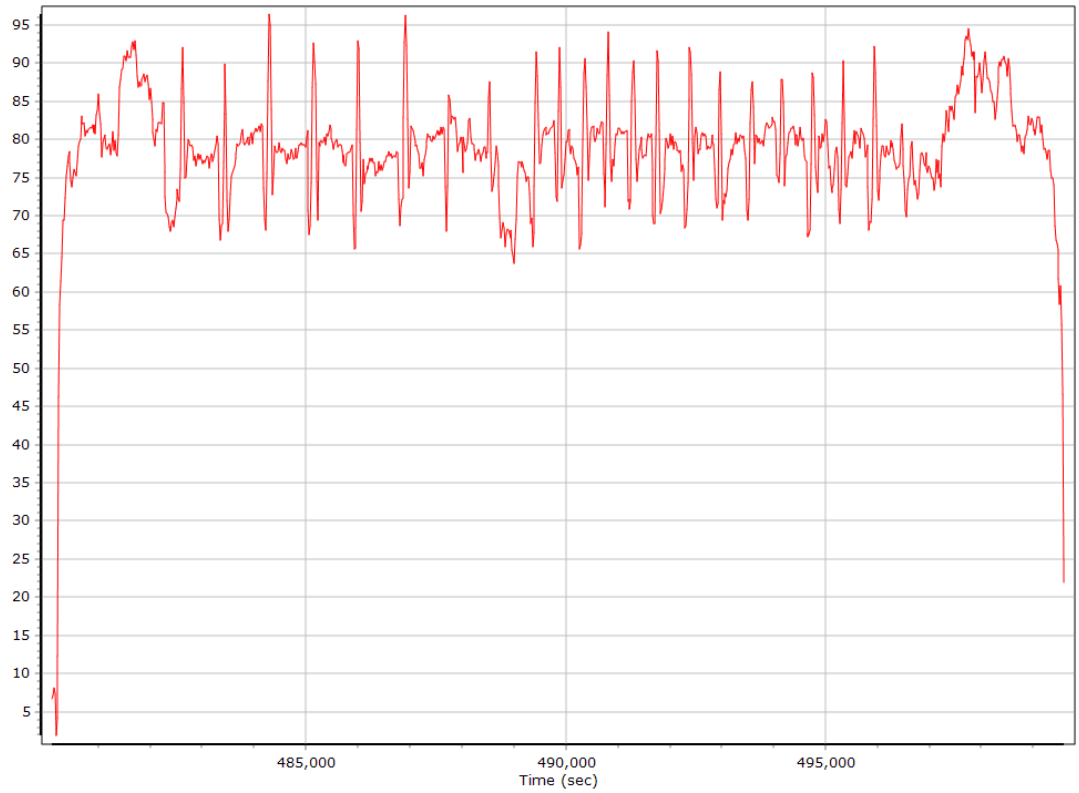
Down Velocity



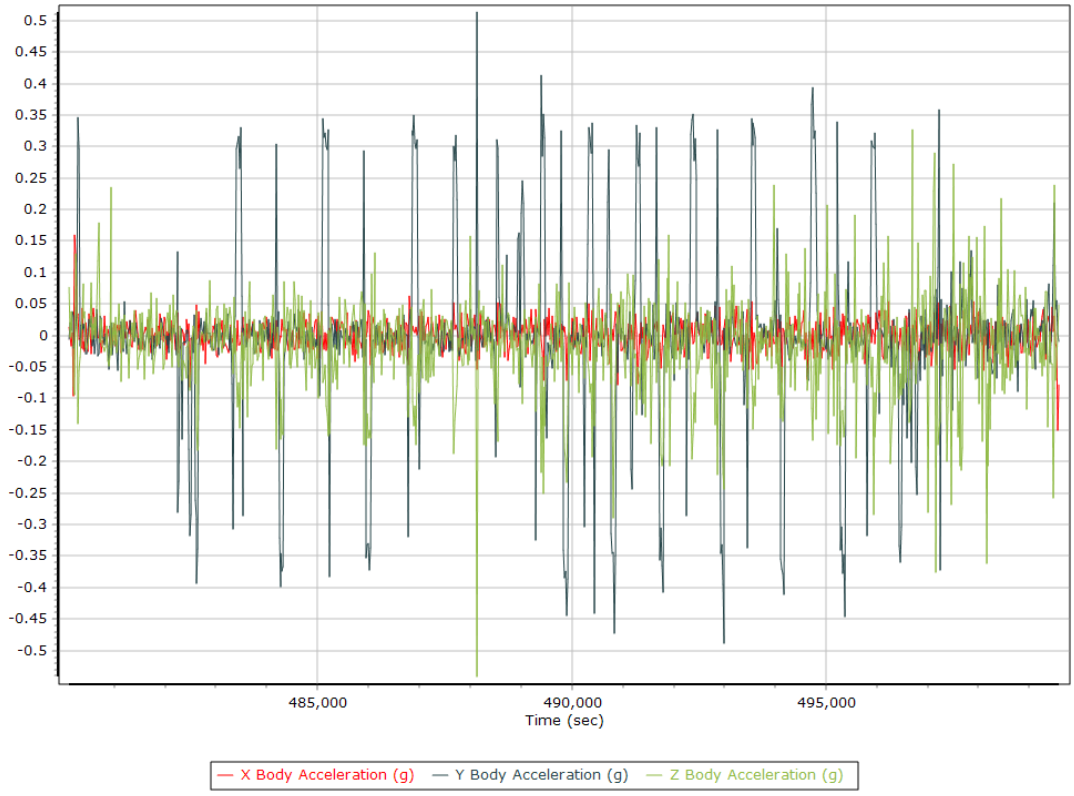
Total Speed



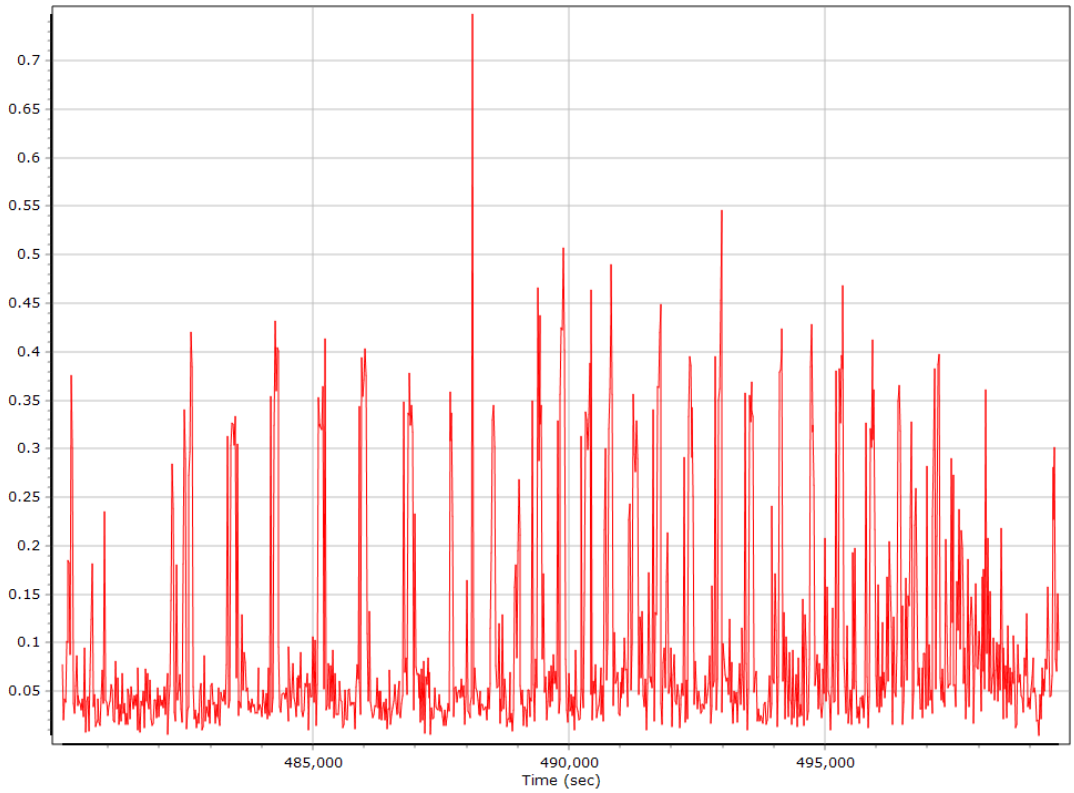
Ground Speed



Body Acceleration



Total Body Acceleration



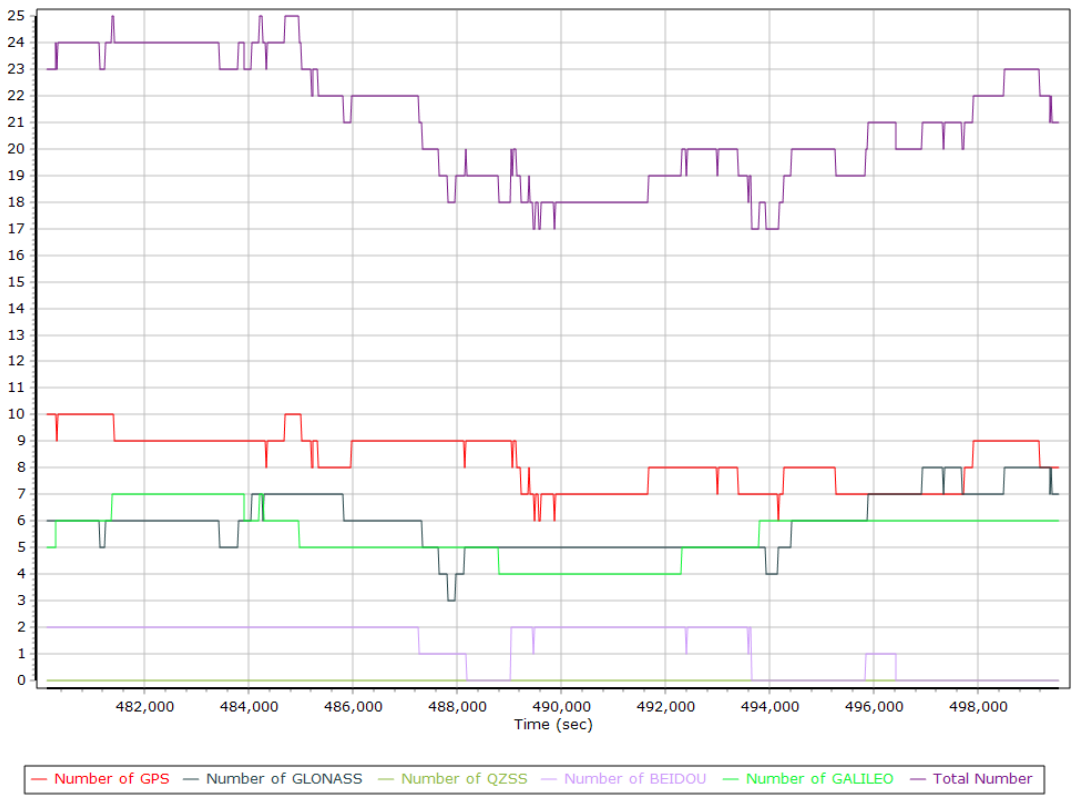
Body Angular Rate

GNSS QC

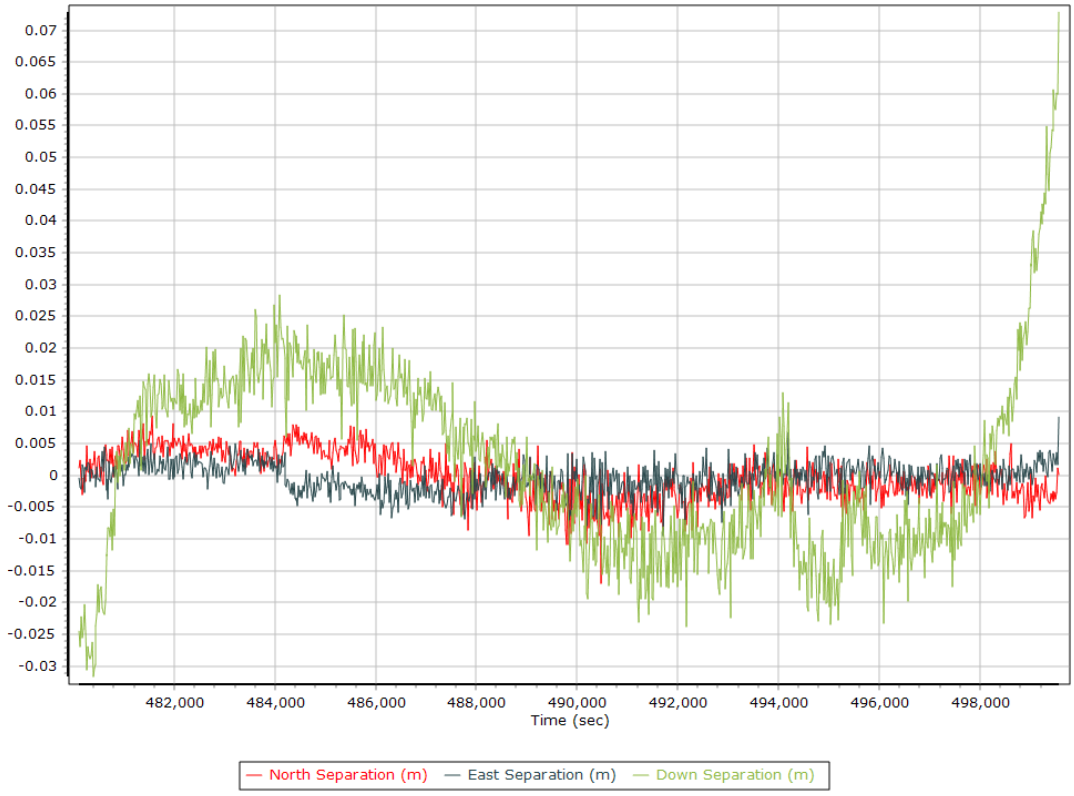
GNSS QC Statistics

Statistics	Min	Max	Mean
Baseline length (km)	0.00	0.00	
Number of GPS SV	4	10	8
Number of GLONASS SV	0	8	6
Number of QZSS SV	0	0	0
Number of BEIDOU SV	0	2	1
Number of GALILEO SV	0	7	5
Total number of SV	11	25	21
PDOP	0.96	2.20	1.17
QC Solution Gaps	0.00	0.00	
Solution Type	Fixed	Float	No solution
Epoch (sec)	19792.00	0.00	0.00
Percentage	100.00	0.00	0.00

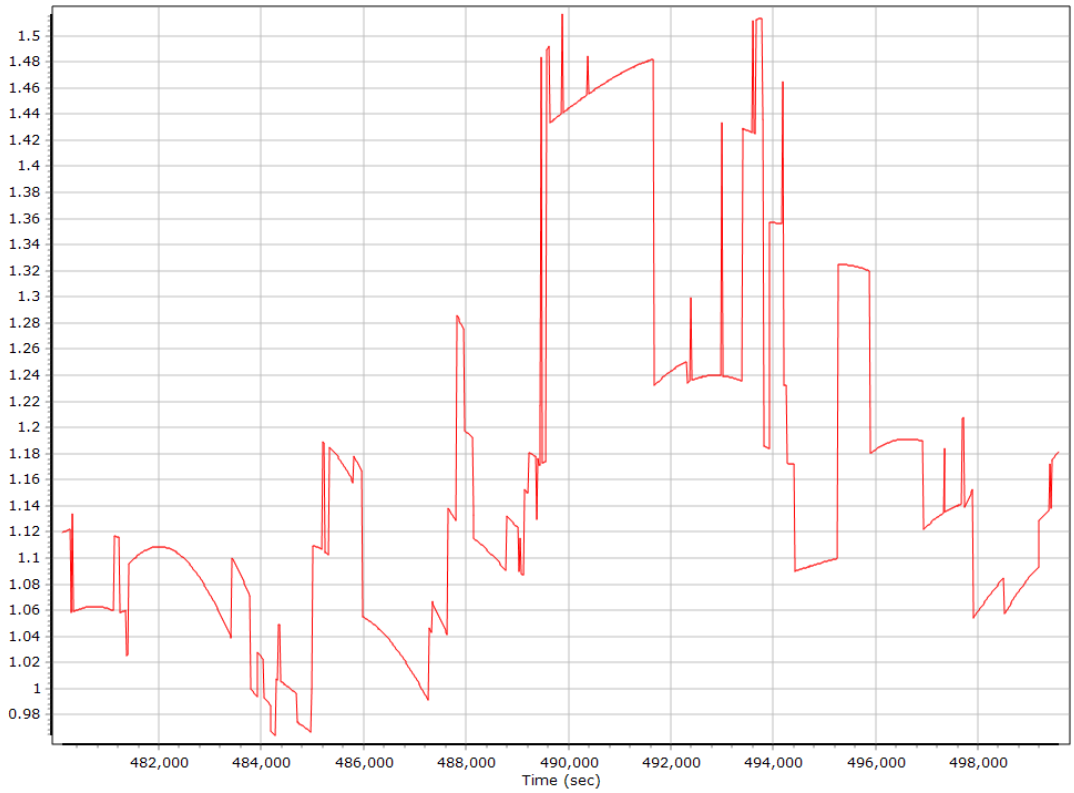
Num SVs in solution



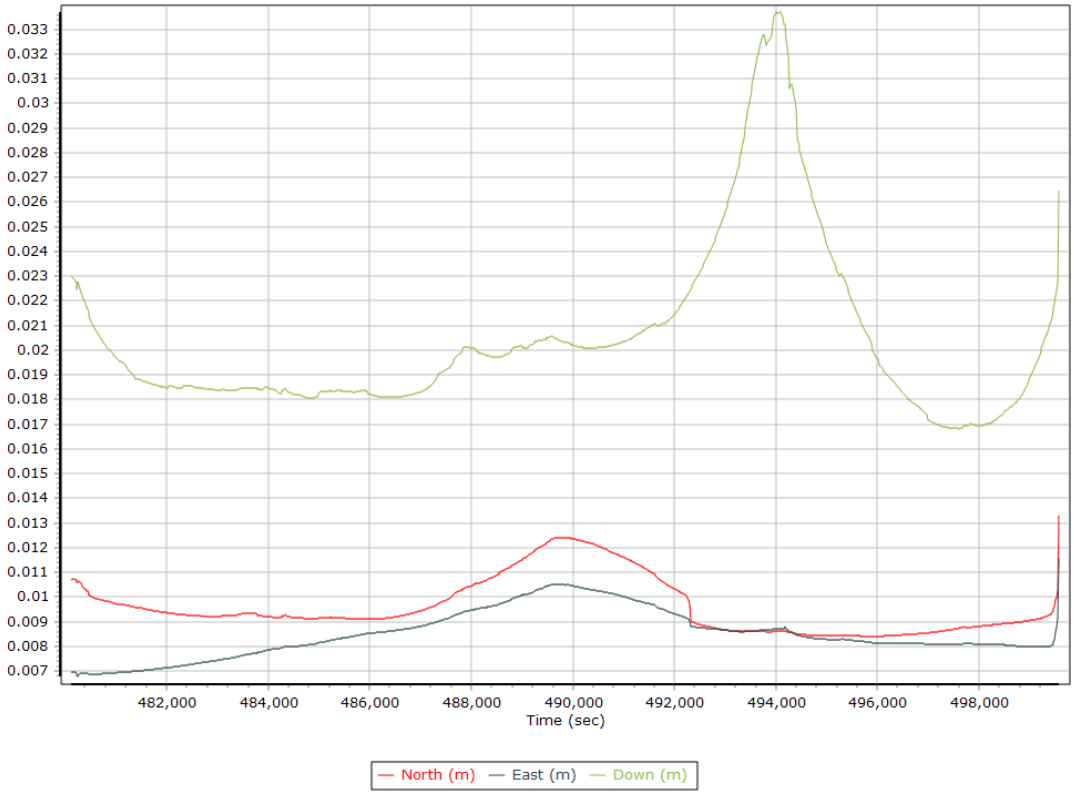
Forward/Reverse Separation



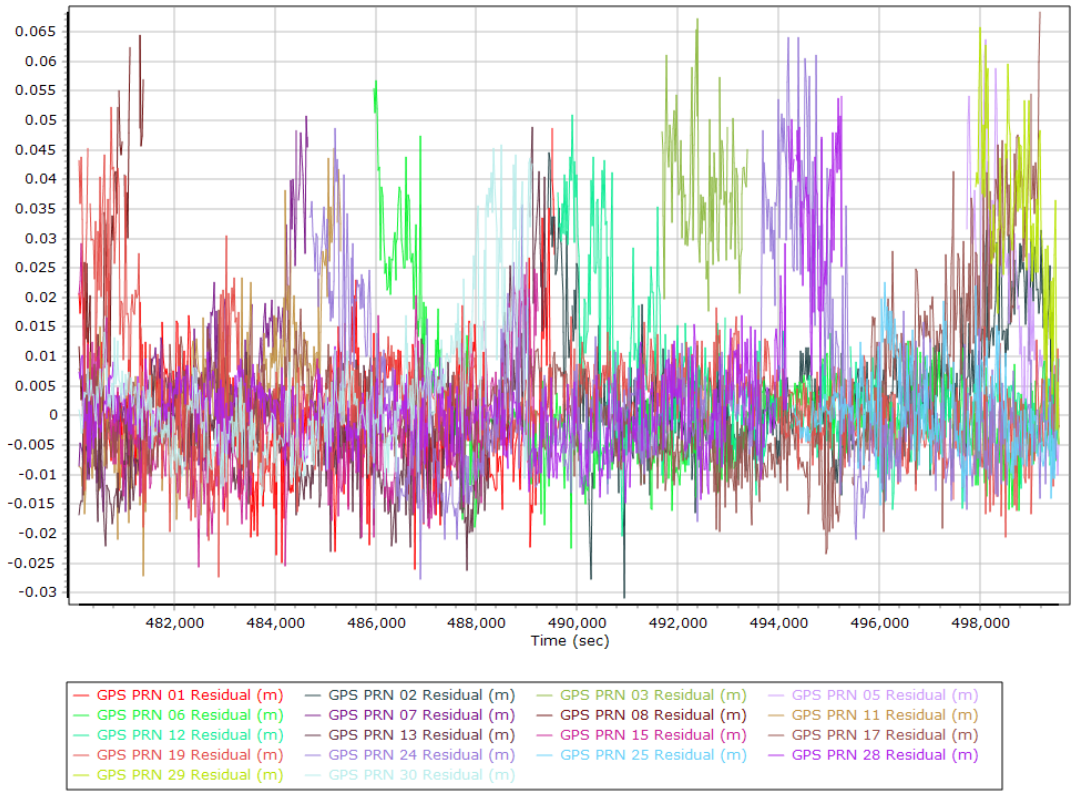
PDOP



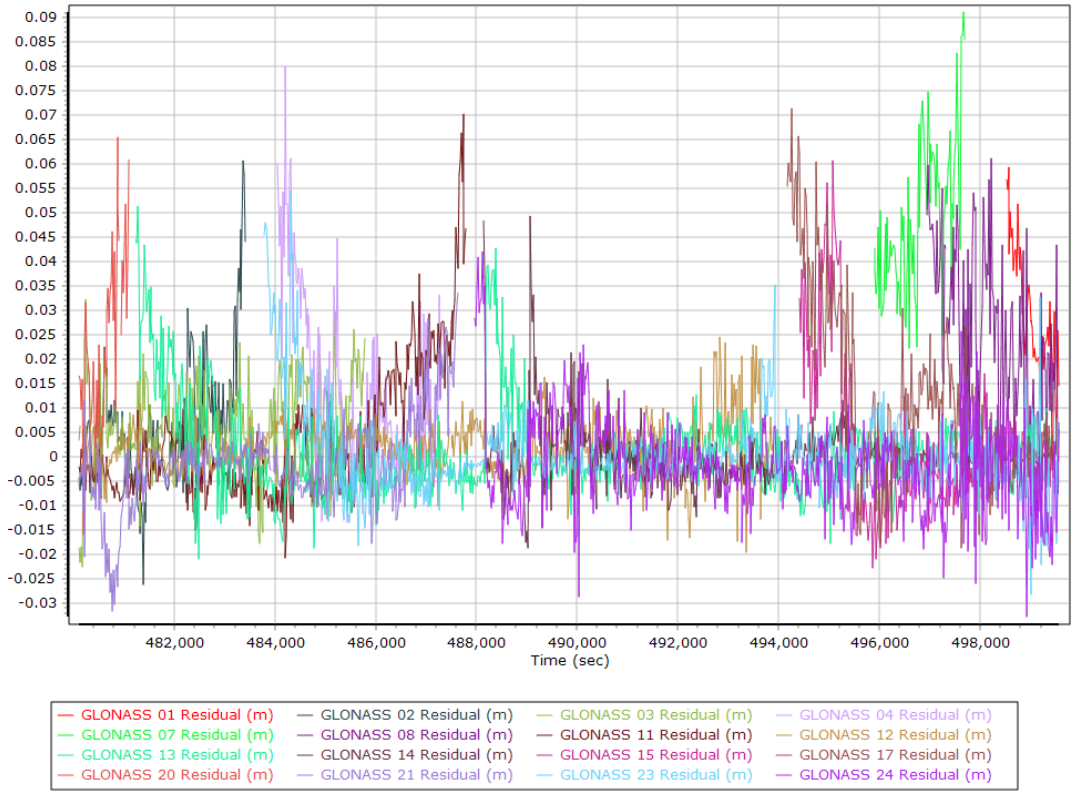
Estimated Position Accuracy



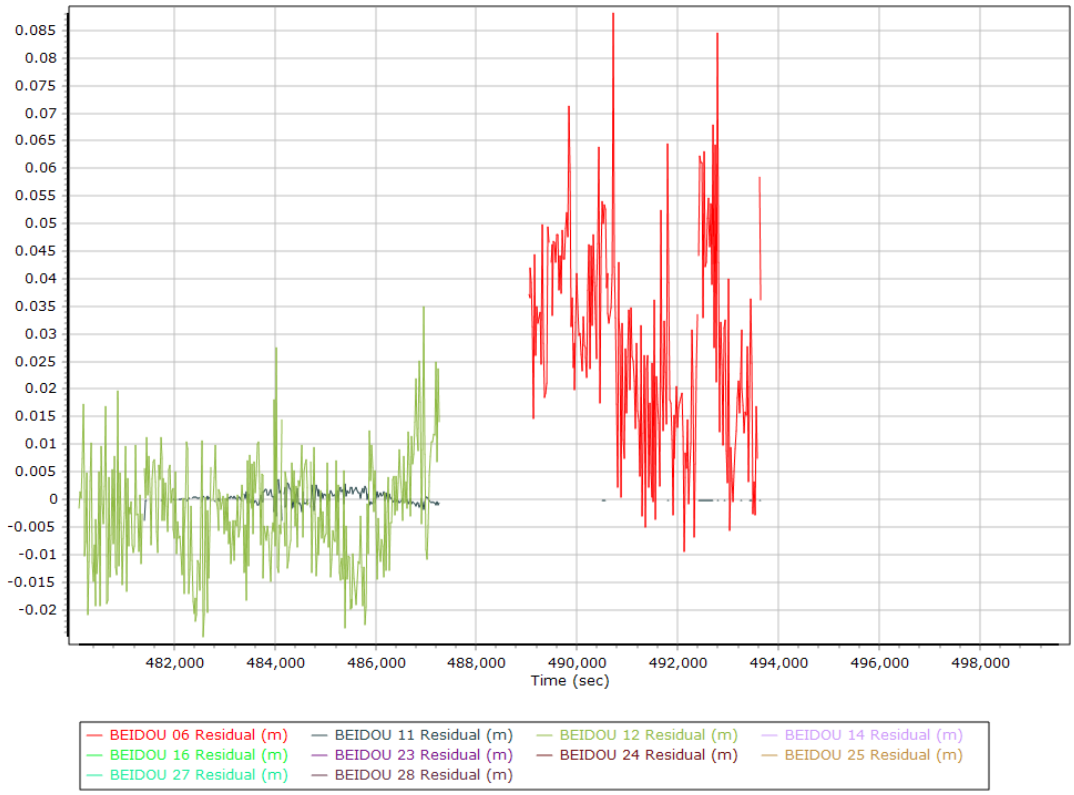
GPS Residuals



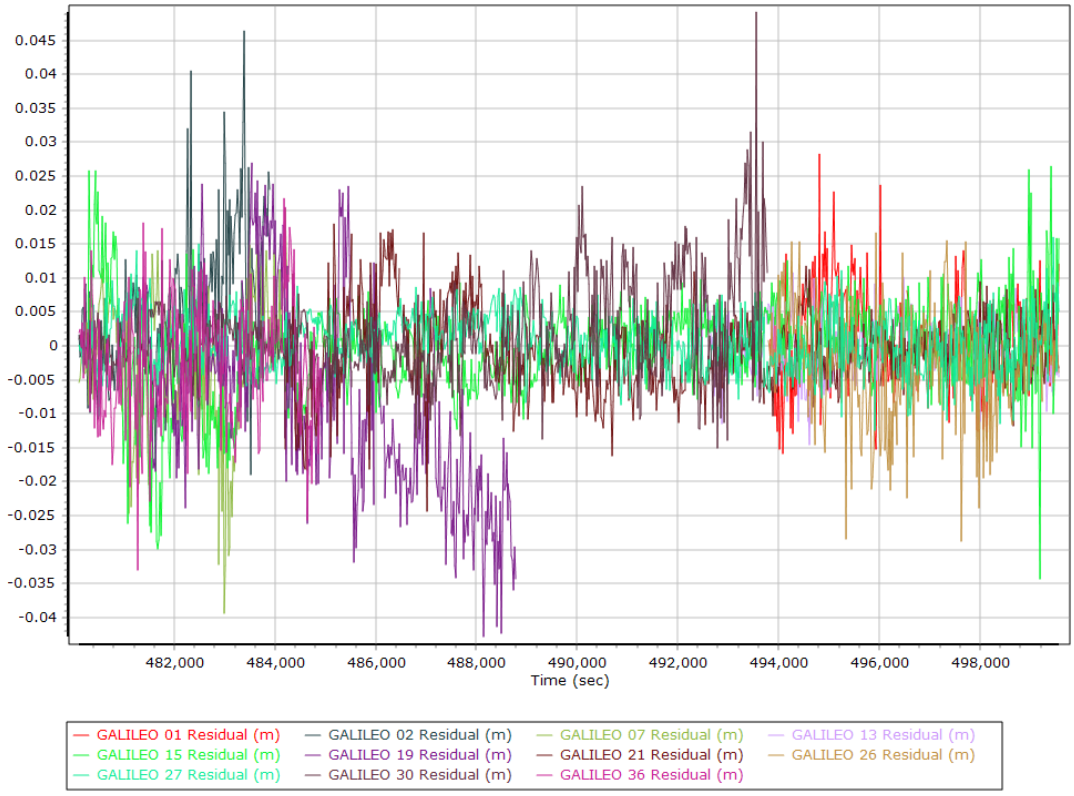
GLONASS Residuals



BEIDOU Residuals



GALILEO Residuals



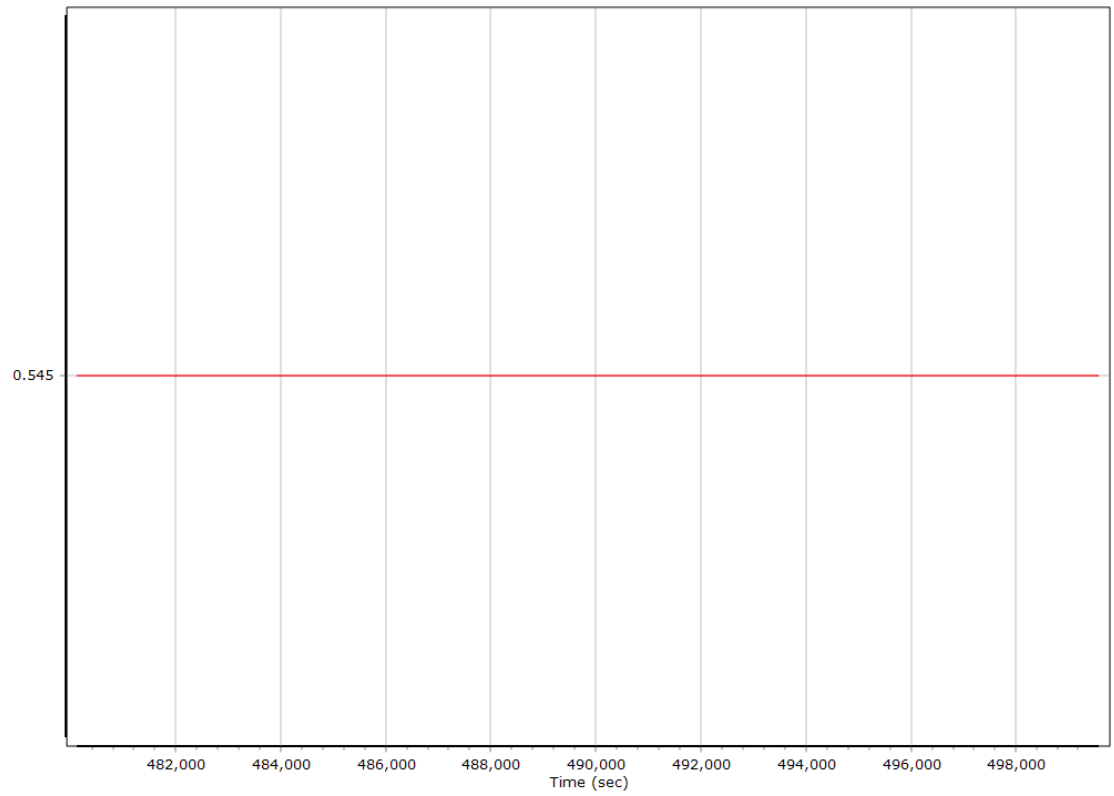
GNSS-Inertial Processor Configuration

Processing mode	IN-Fusion PP-RTX		
Stabilized mount	False		
Processing start time	479780.000 (07/03/2020 13:16:20)		
Processing end time	499591.000 (07/03/2020 18:46:31)		
Initial attitude source	Real-Time VNAV/RNAV Attitude		
IMU Sensor Context	Processing with Onboard IMU		
Reference to IMU lever arm (m)	0.000	0.000	0.000
Reference to IMU mounting angles (deg)	0.000	0.000	180.000
Reference to Primary GNSS lever arm (m)	0.545	-0.439	-0.967
Reference to Primary GNSS lever arm std dev (m)	0.030	0.030	0.030
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

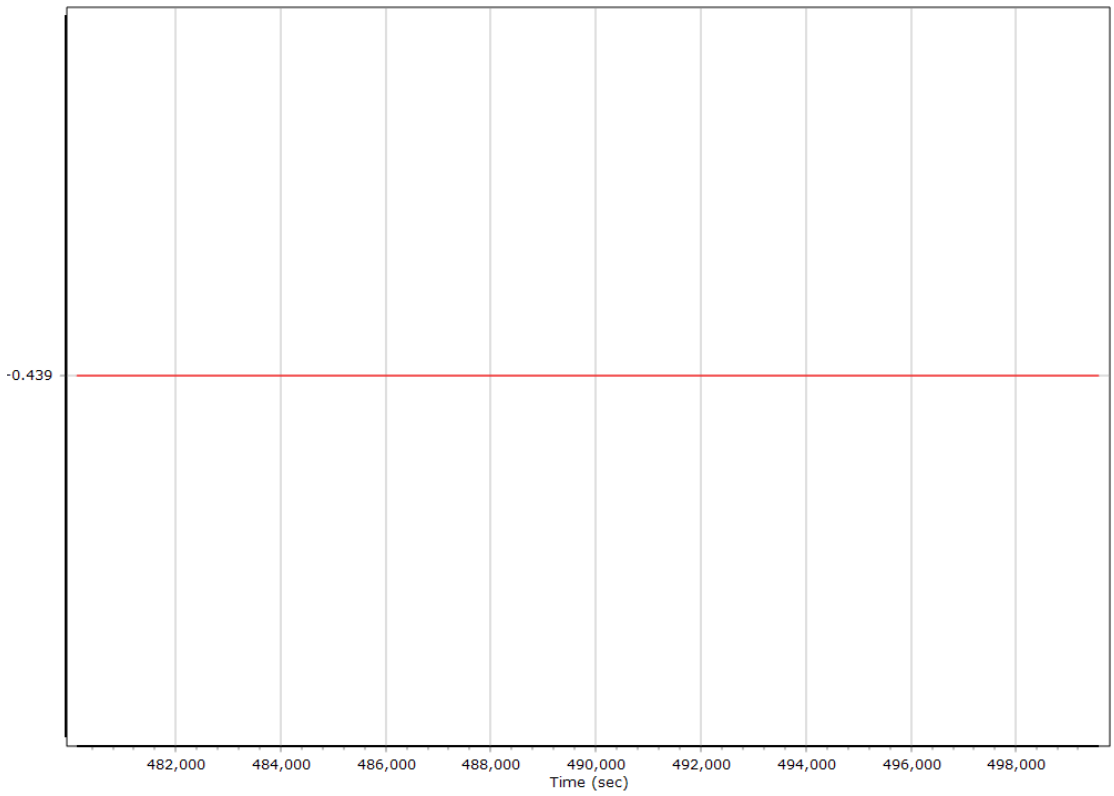
Calibrated Installation Parameters

Reference-Primary GNSS Lever Arm (m)

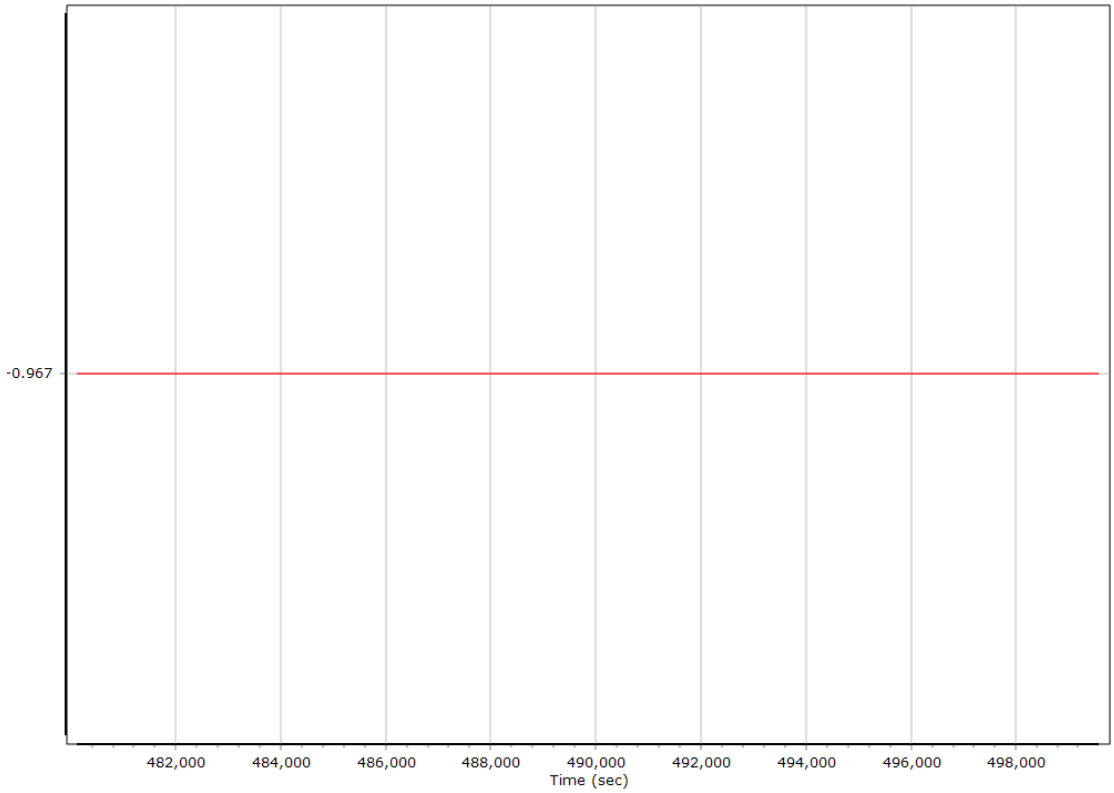
X Reference-Primary GNSS Lever Arm (m)



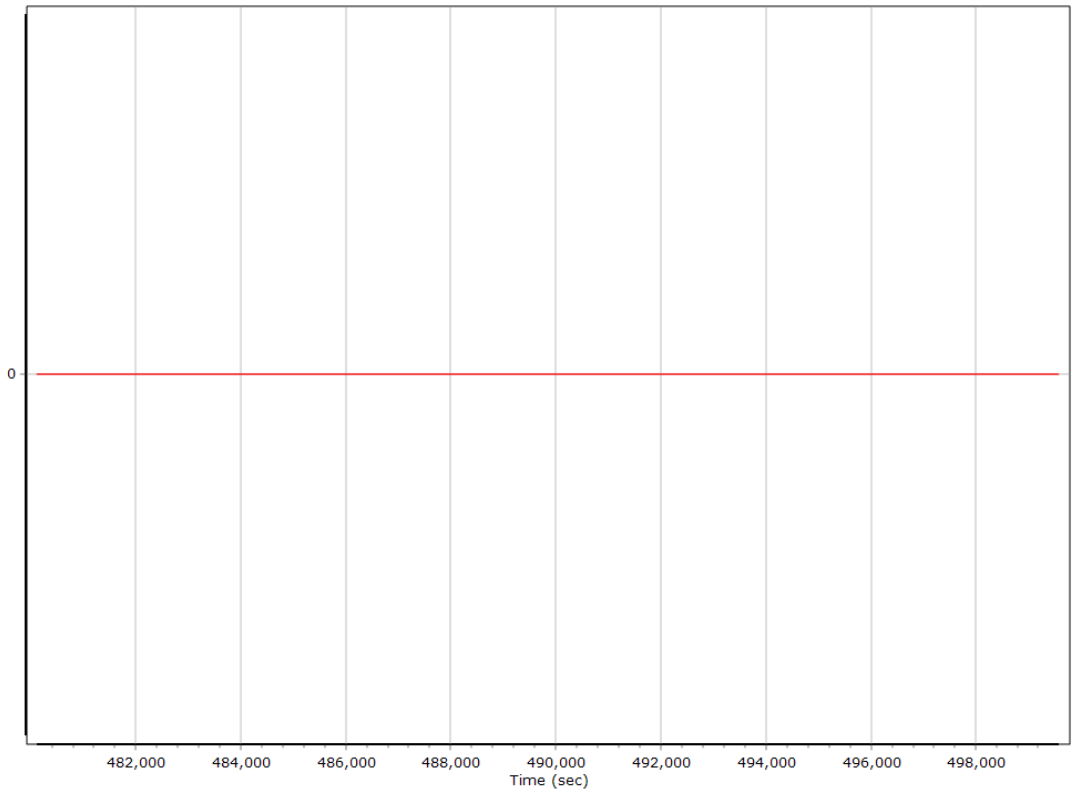
Y Reference-Primary GNSS Lever Arm (m)



Z Reference-Primary GNSS Lever Arm (m)



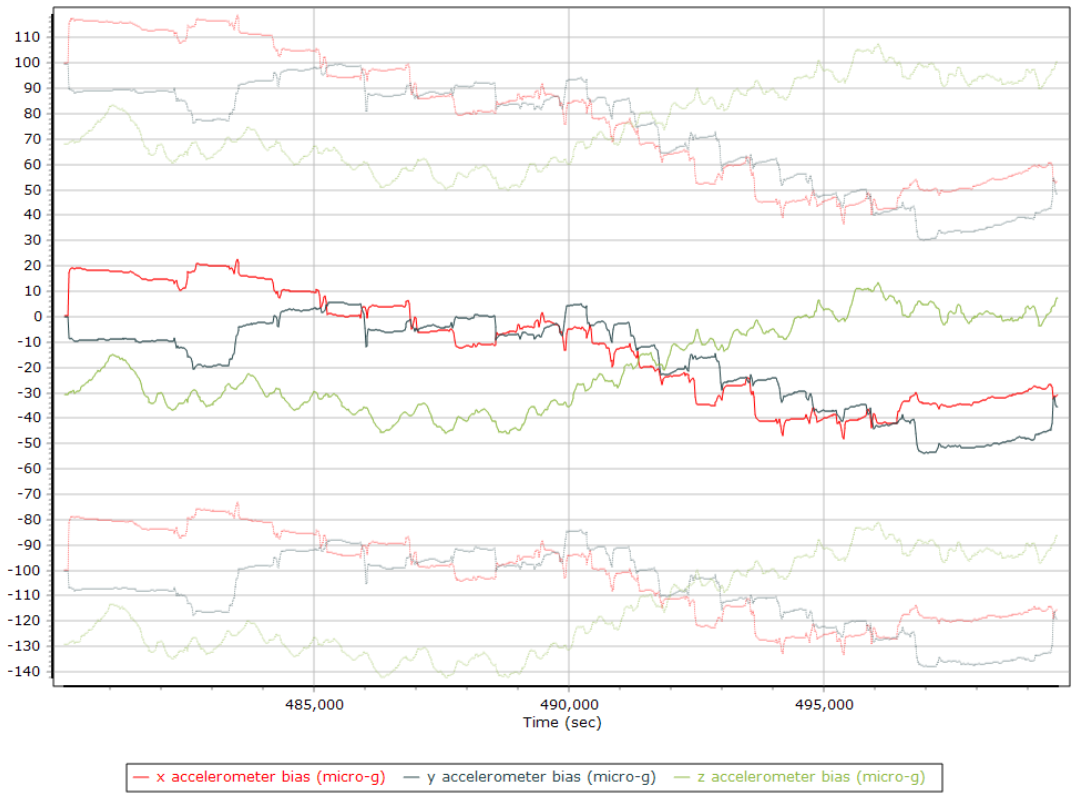
Reference-Primary GNSS Lever Arm Figure of Merit



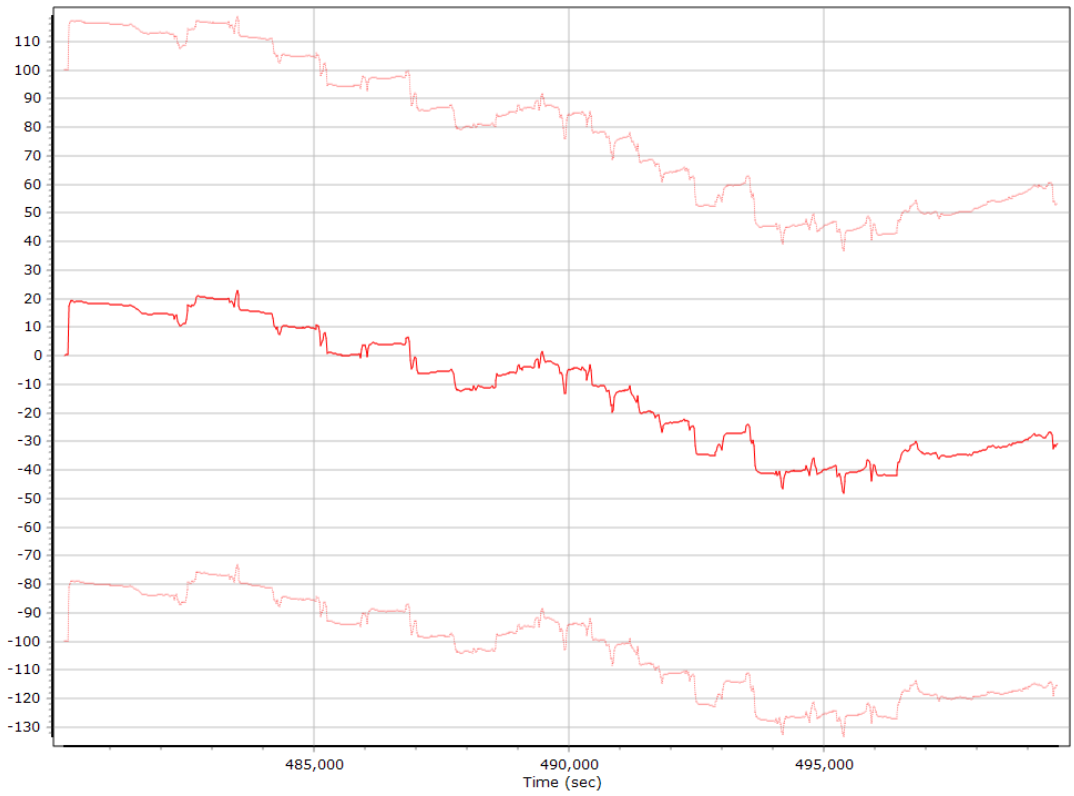
IN-Fusion QC

Forward Processed Estimated Errors, Reference Frame

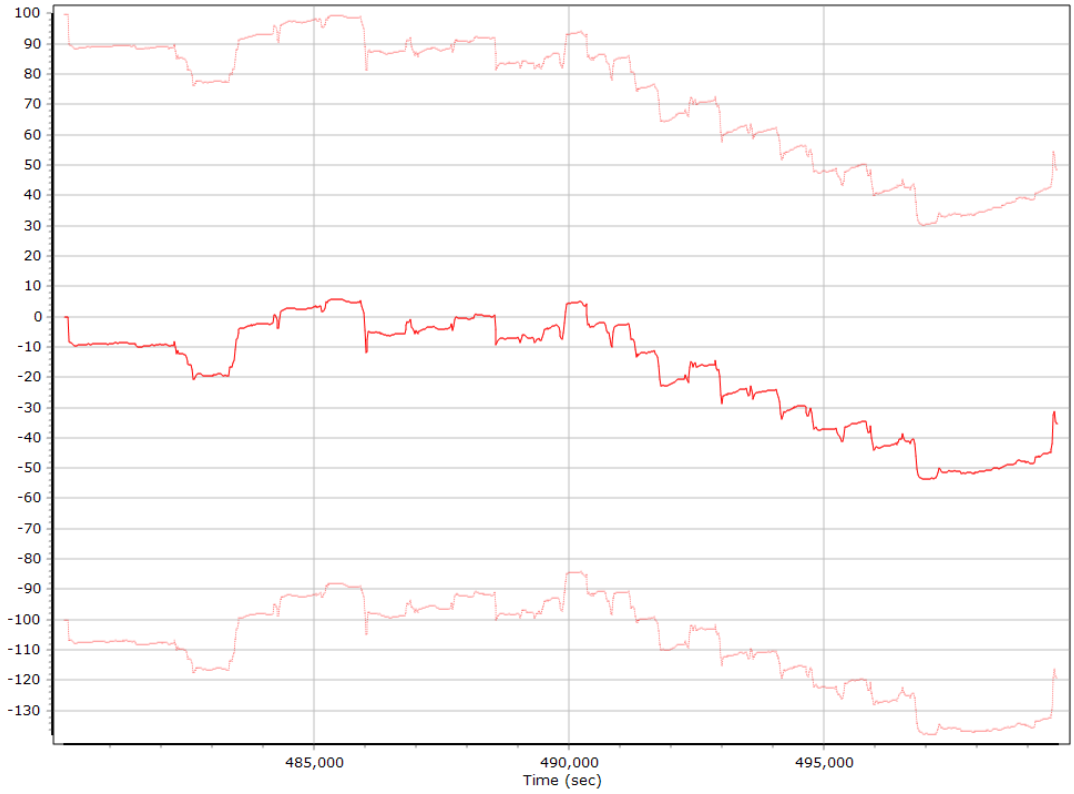
Accelerometer Bias (micro-g)



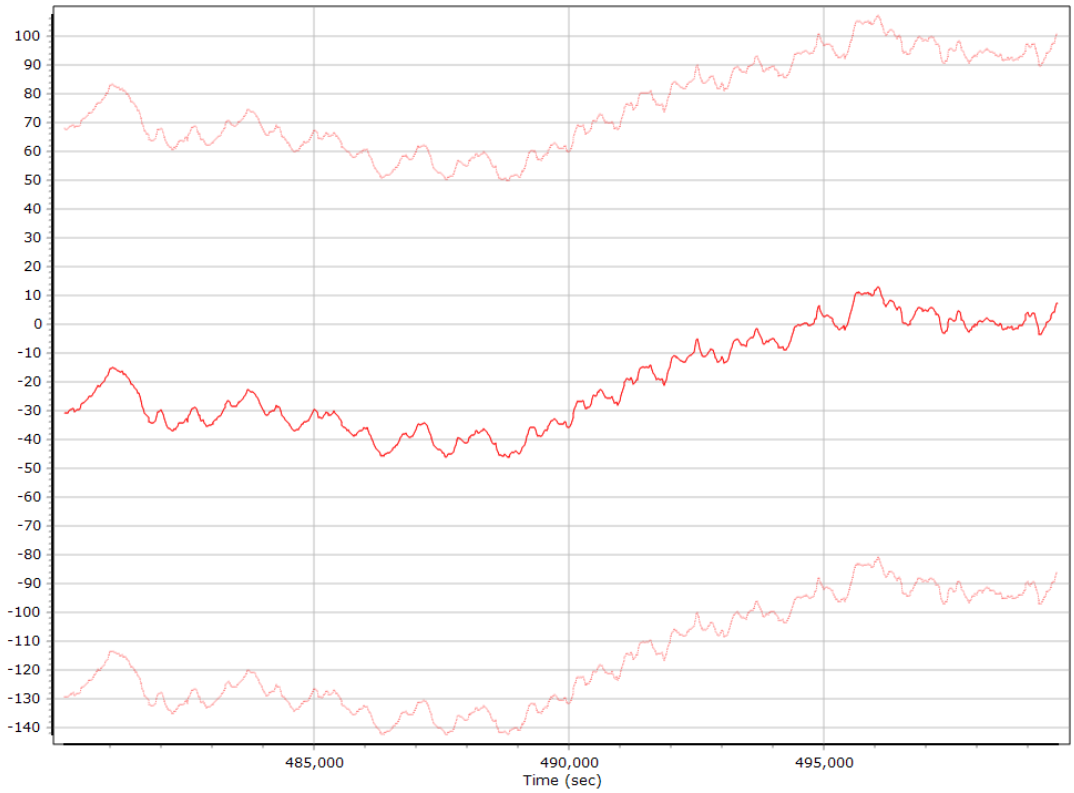
X Accelerometer Bias (micro-g)



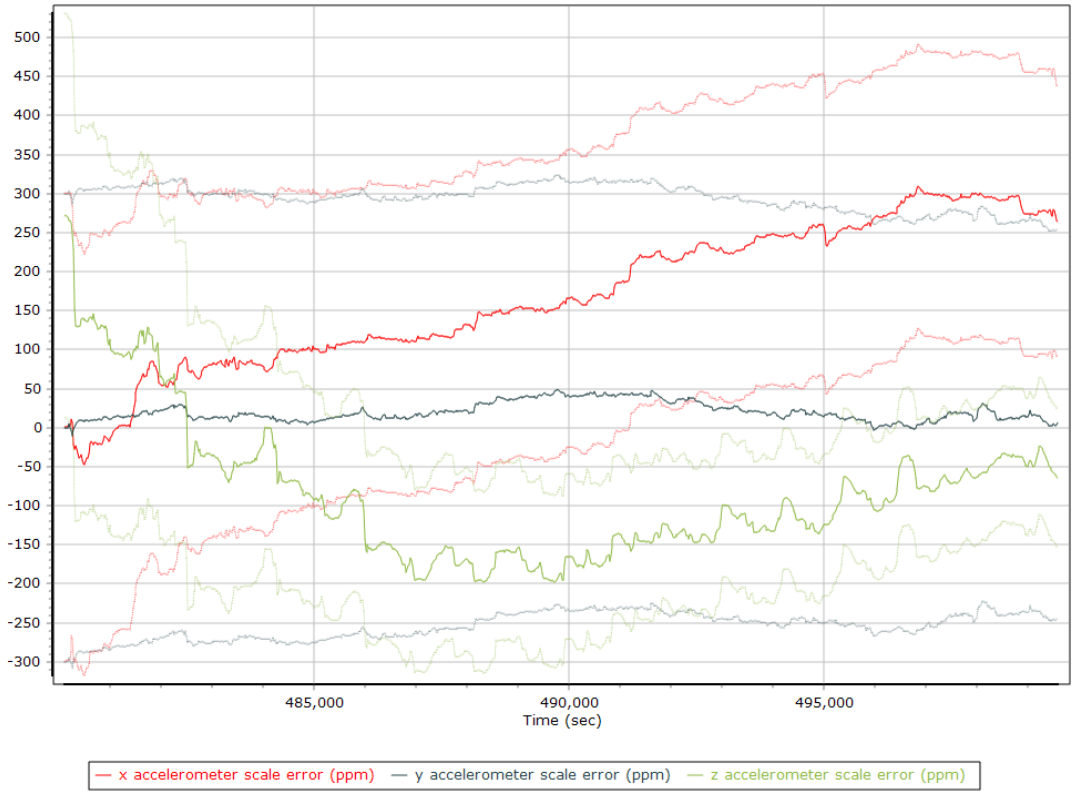
Y Accelerometer Bias (micro-g)



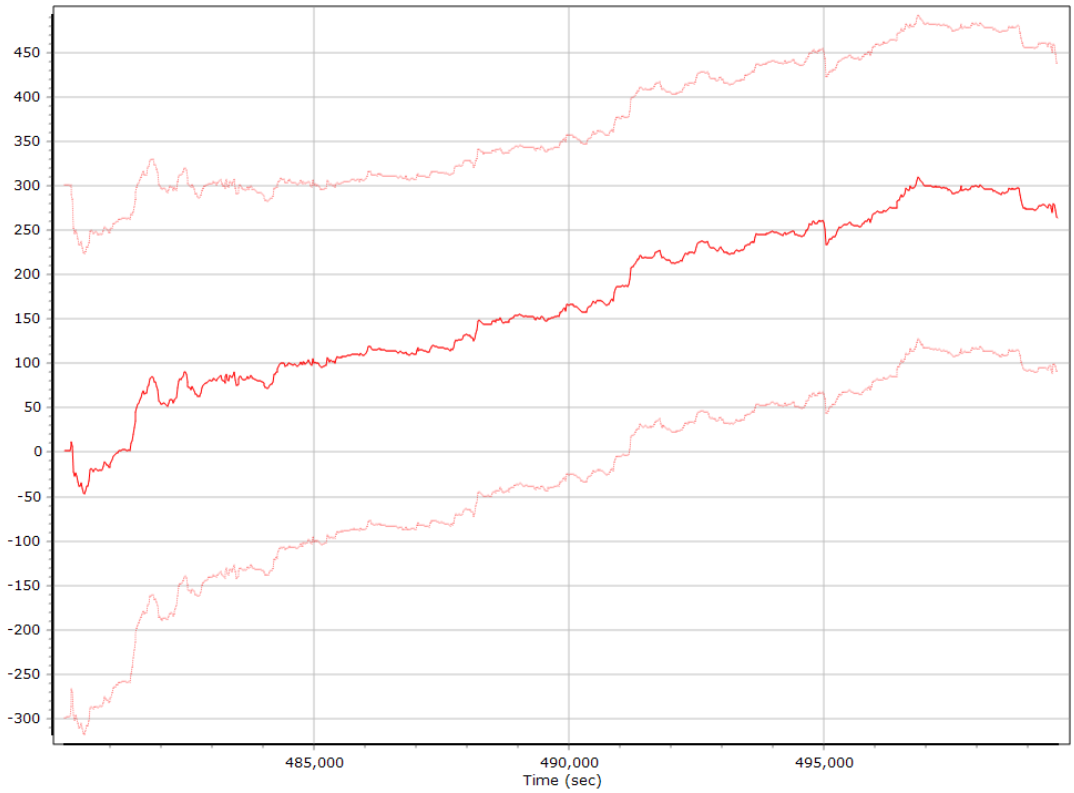
Z Accelerometer Bias (micro-g)



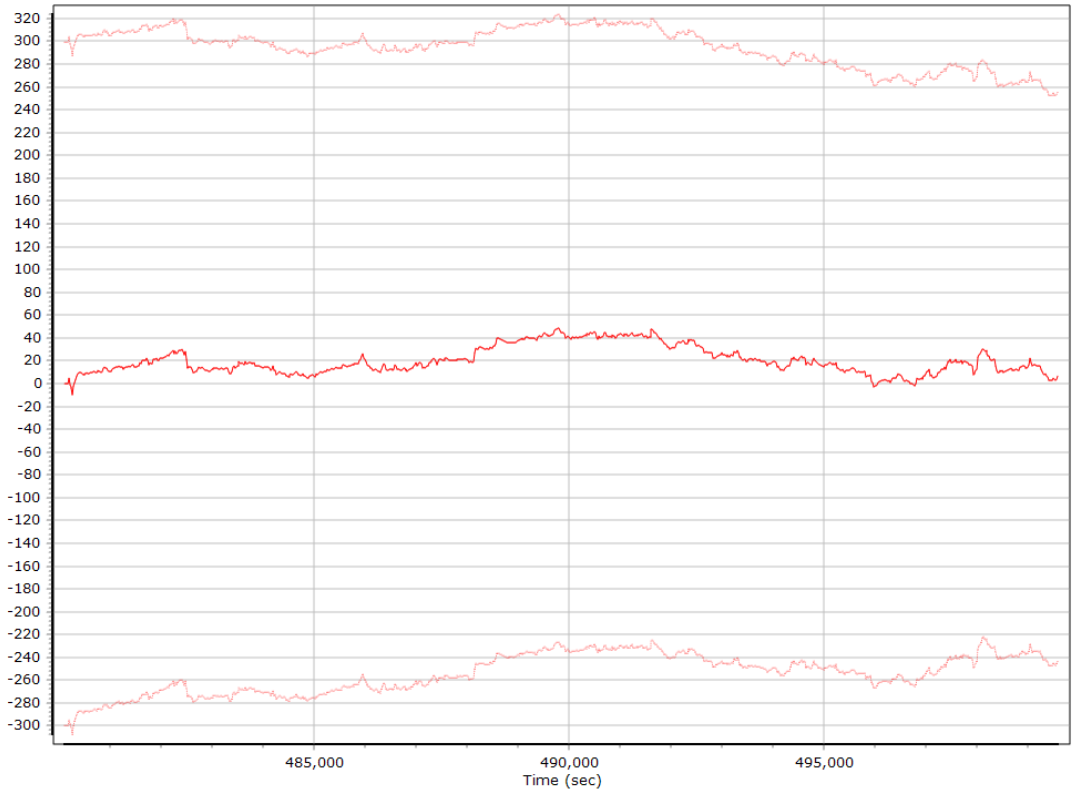
Accelerometer Scale Error (ppm)



X Accelerometer Scale Error (ppm)

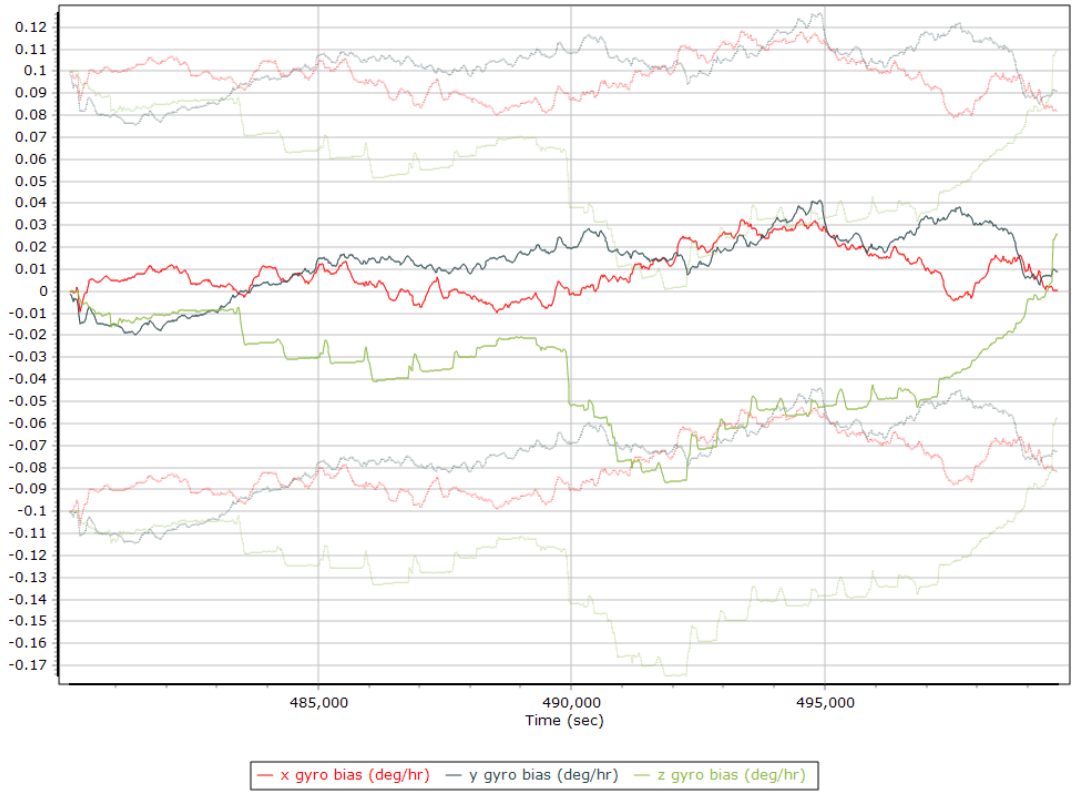


Y Accelerometer Scale Error (ppm)

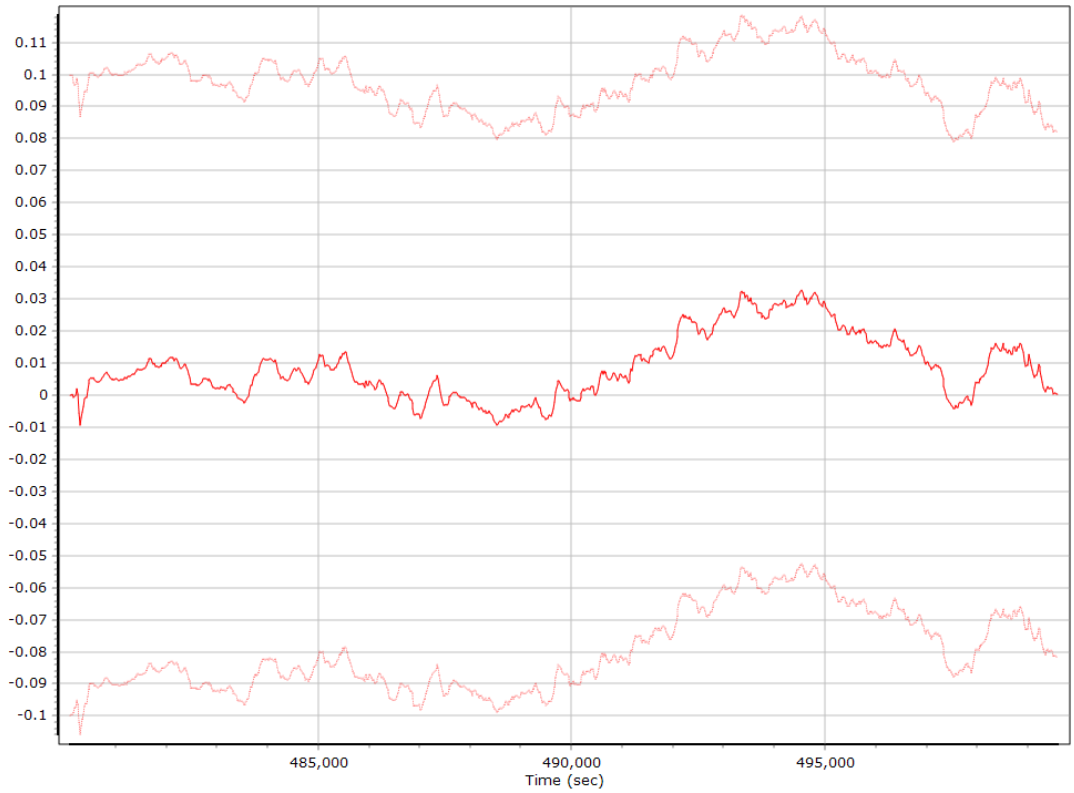


Z Accelerometer Scale Error (ppm)

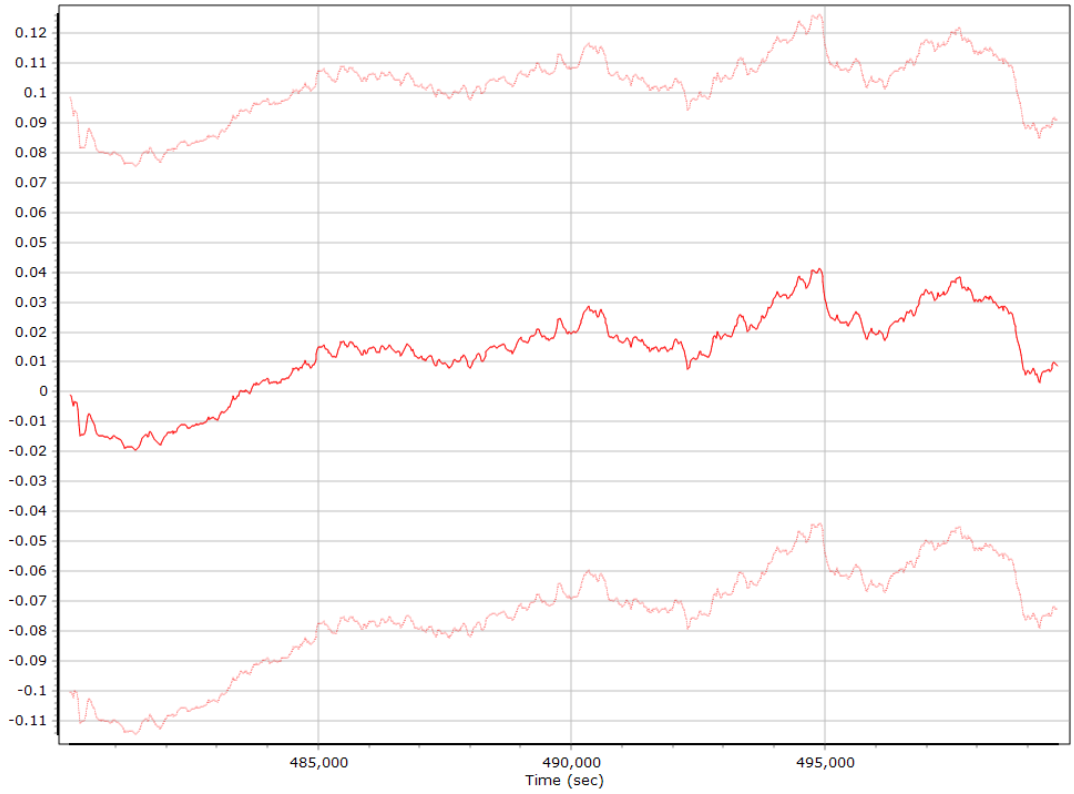
Gyro Bias (deg/h)



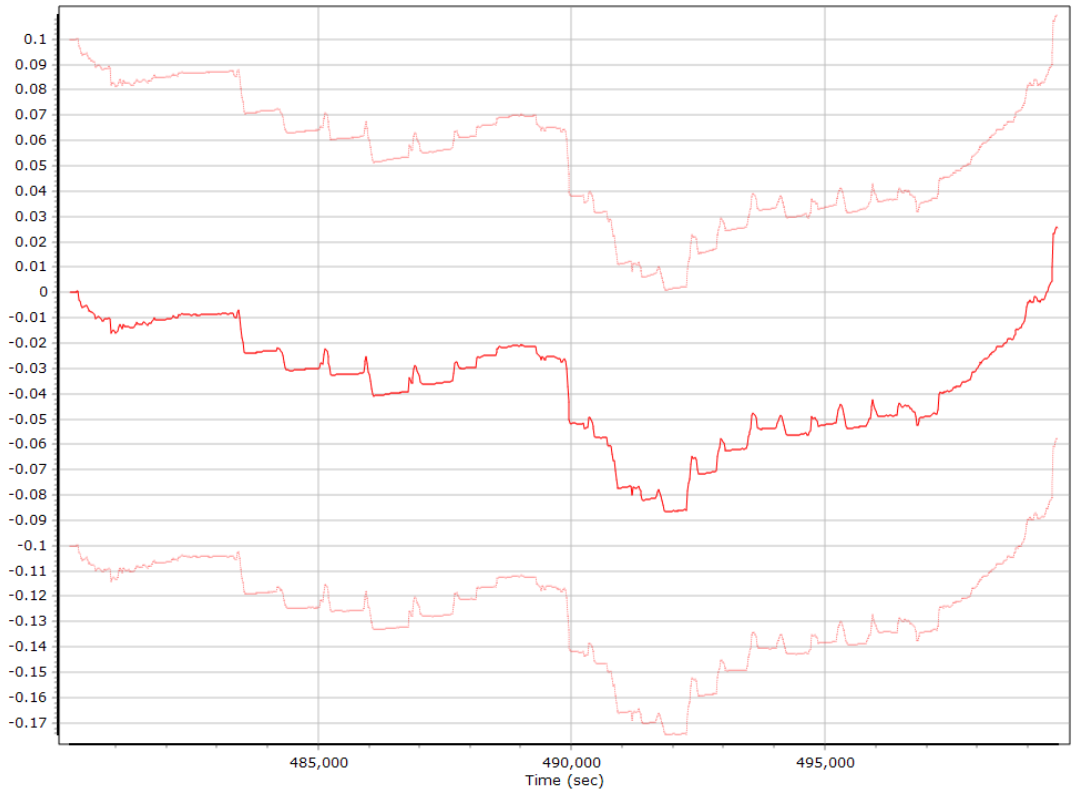
X Gyro Bias (deg/h)



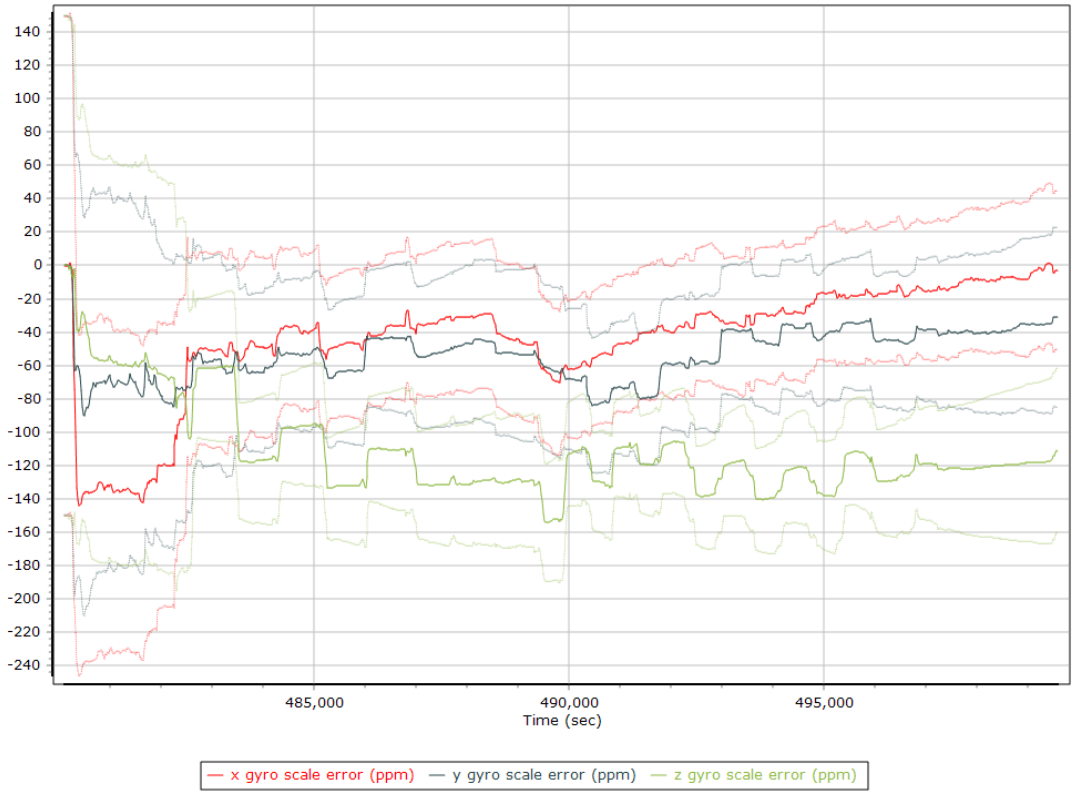
Y Gyro Bias (deg/h)



Z Gyro Bias (deg/h)



Gyro Scale Error (ppm)



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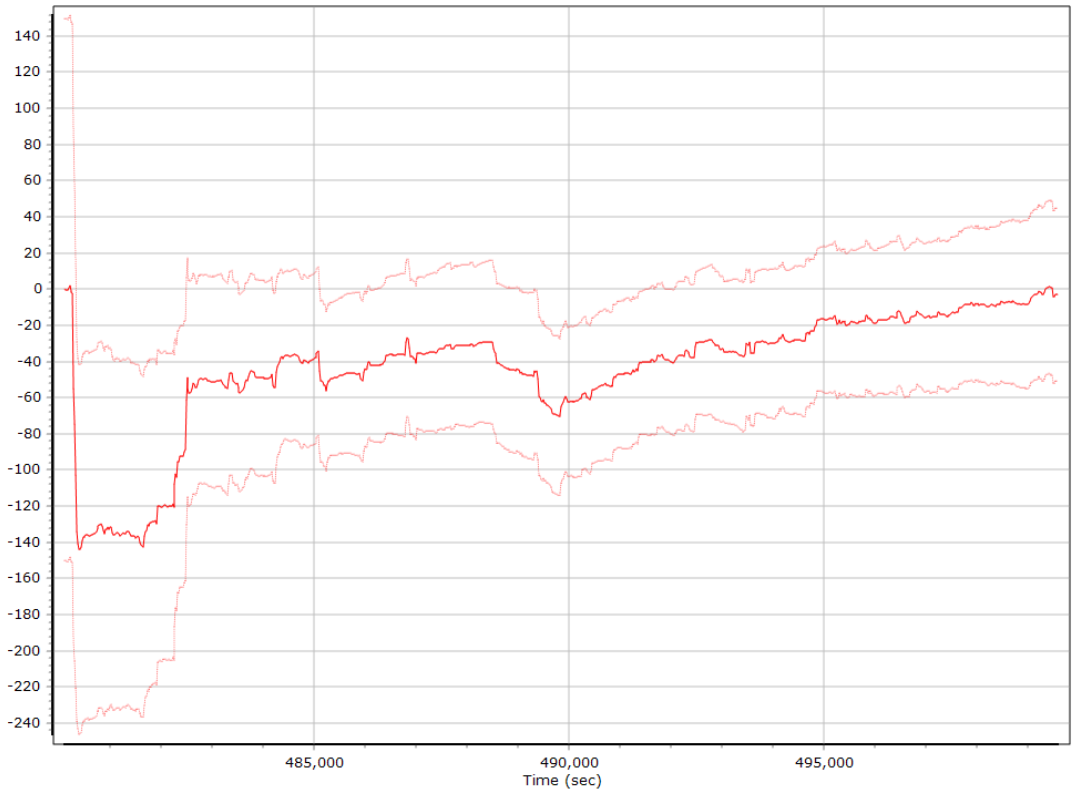
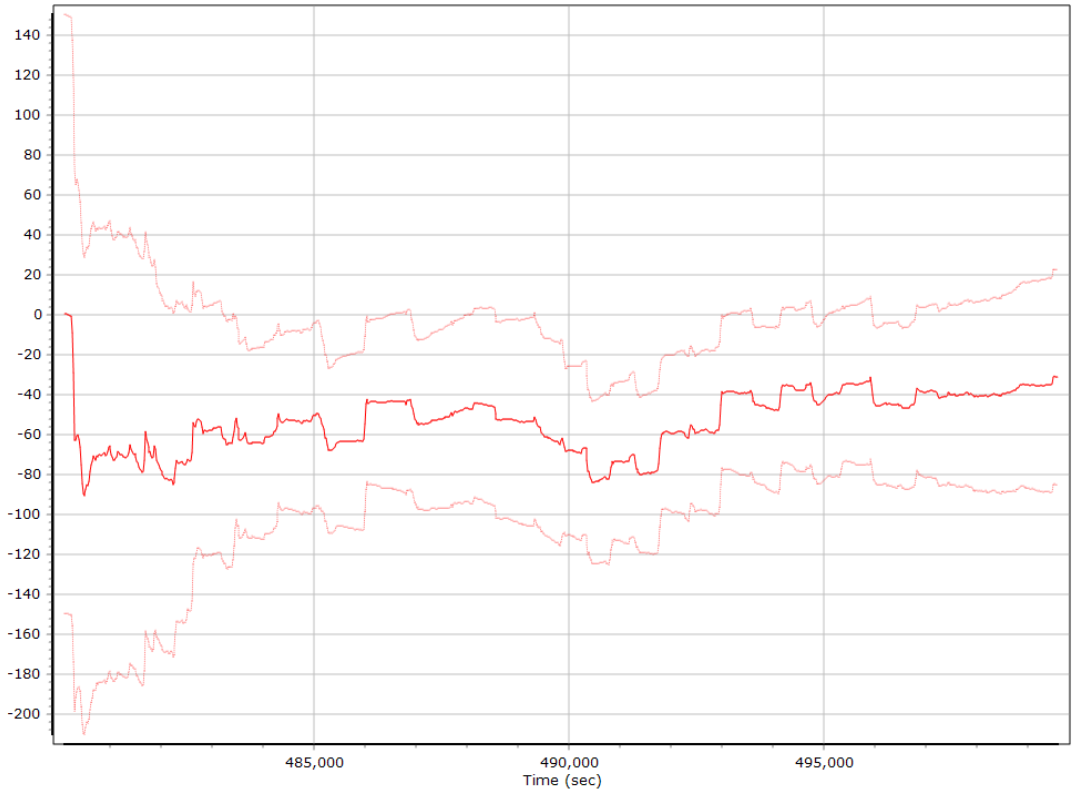
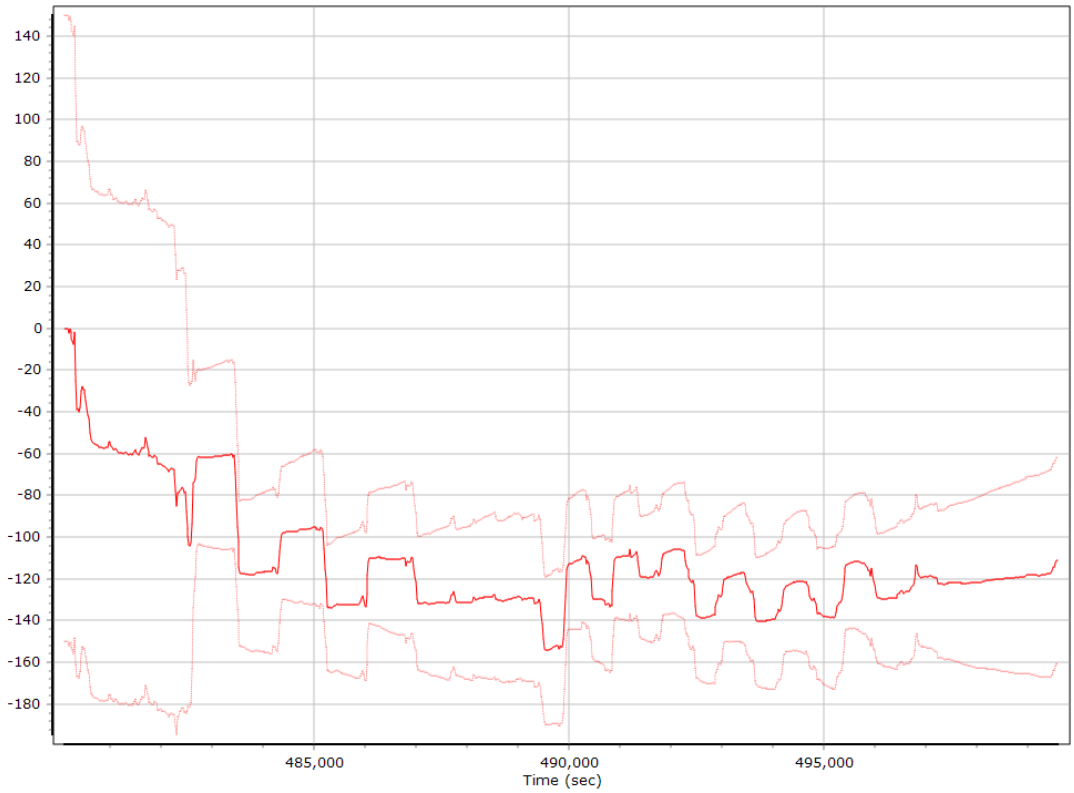


Y Gyro Scale Error (ppm)

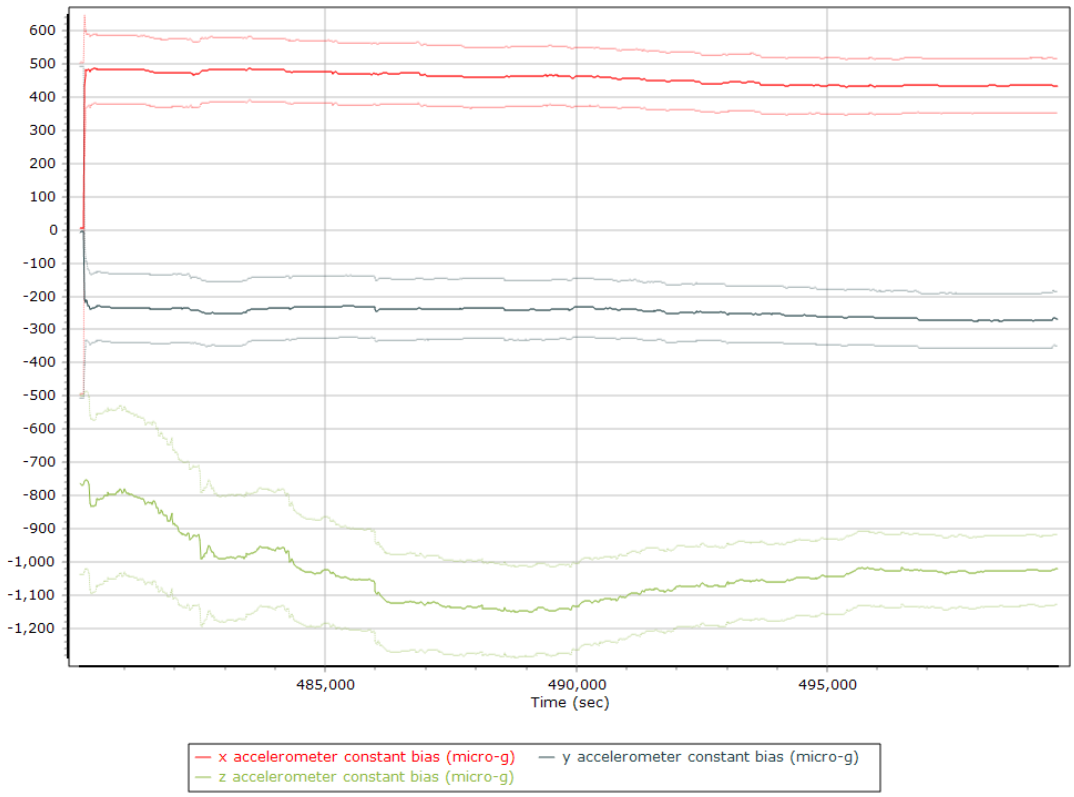


Z Gyro Scale Error (ppm)

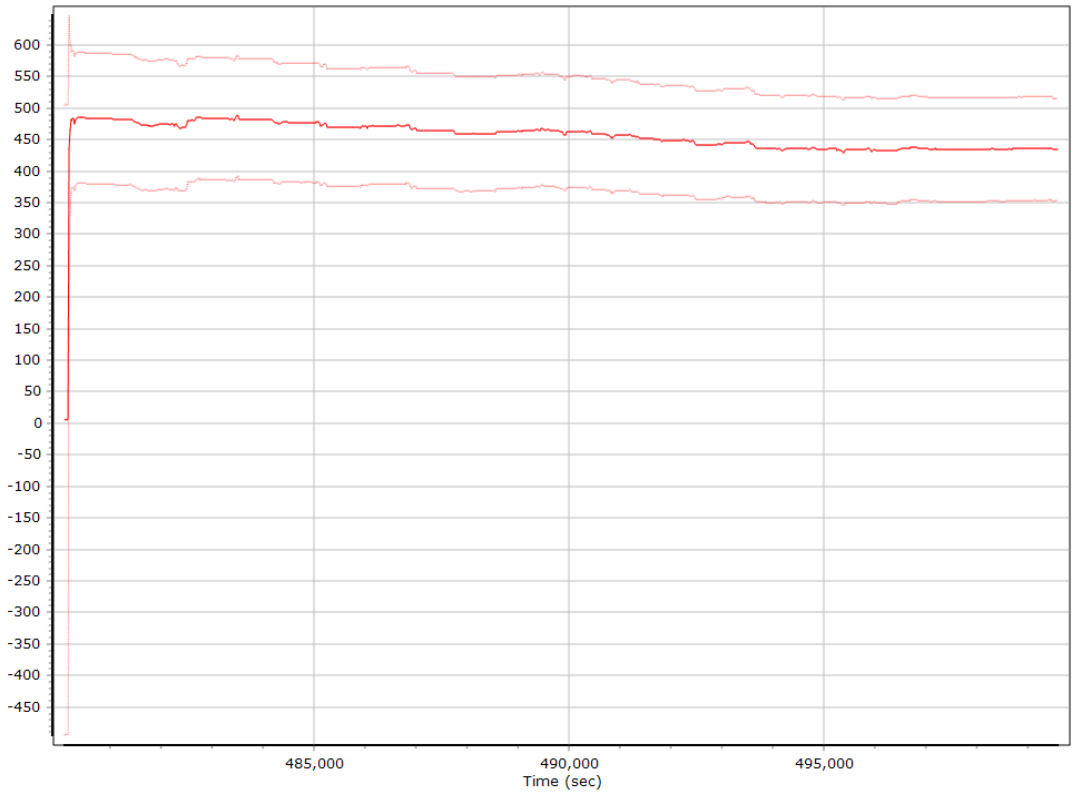


Forward Processed Estimated Constant Errors, Reference Frame

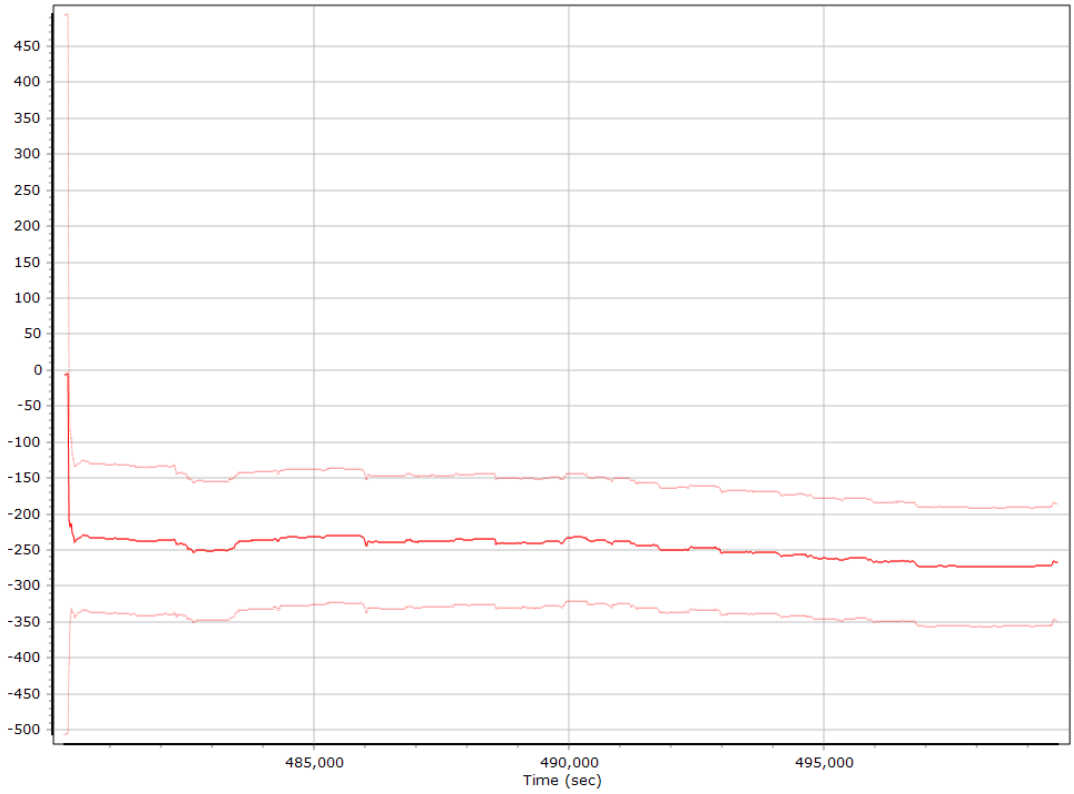
Accelerometer Bias (micro-g)



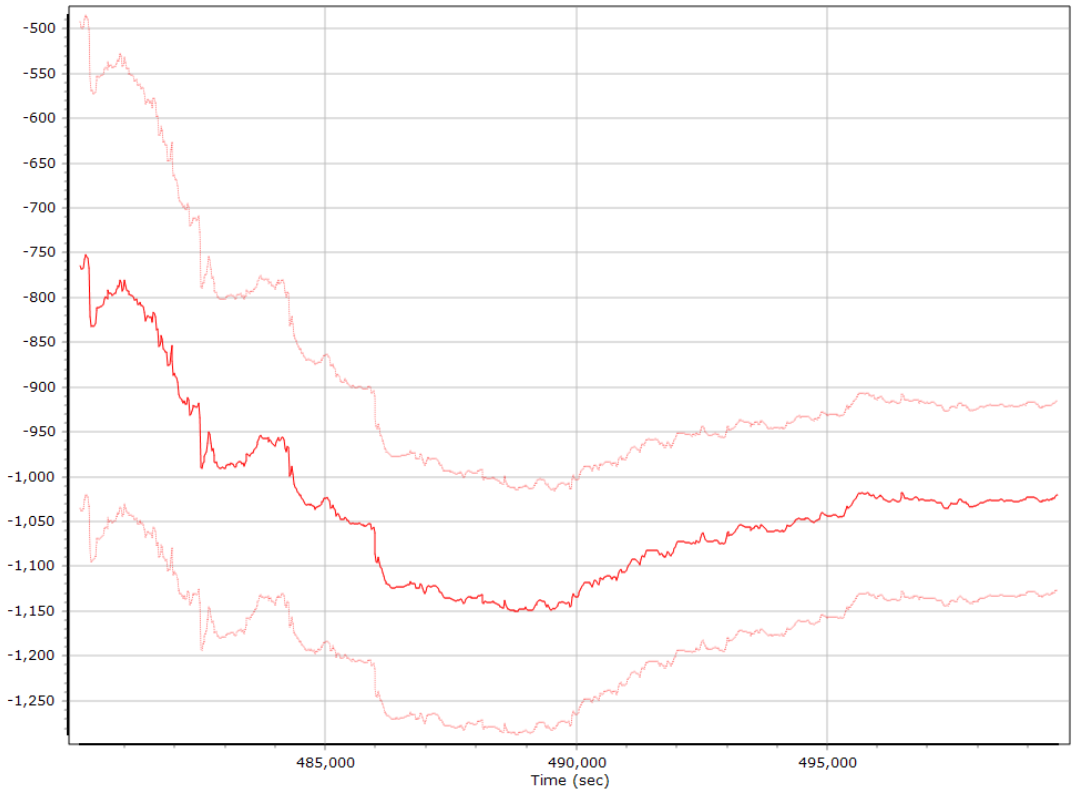
X Accelerometer Bias (micro-g)



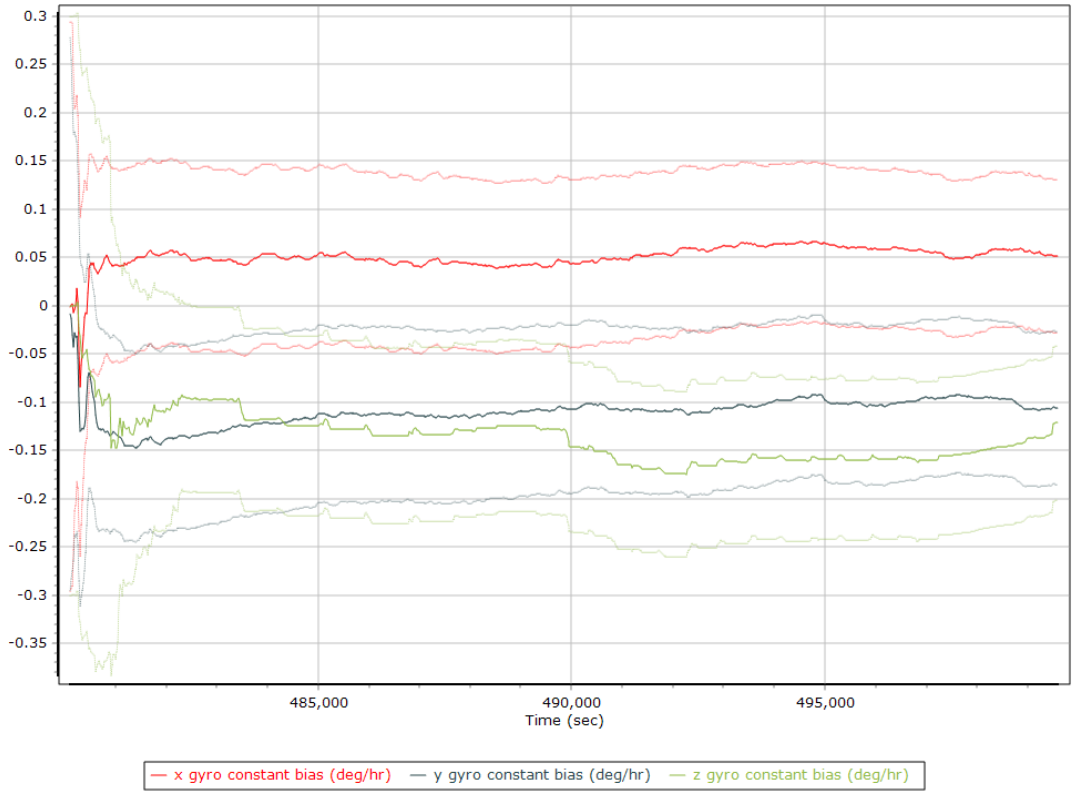
Y Accelerometer Bias (micro-g)



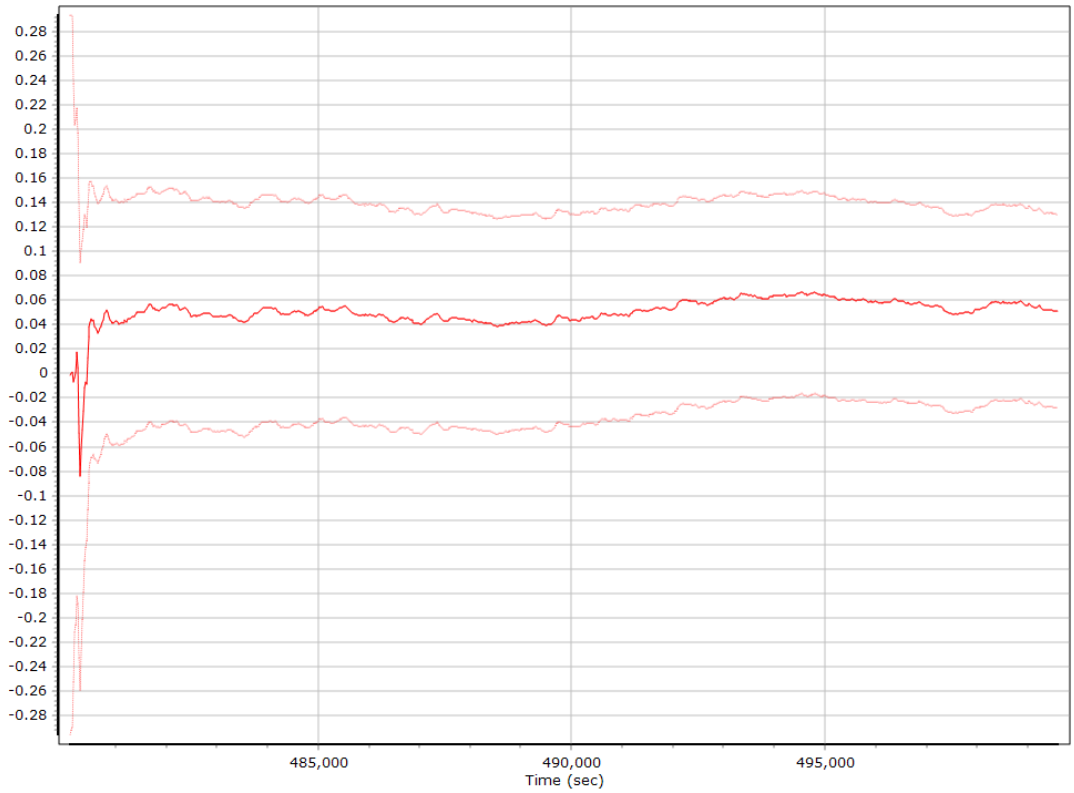
Z Accelerometer Bias (micro-g)



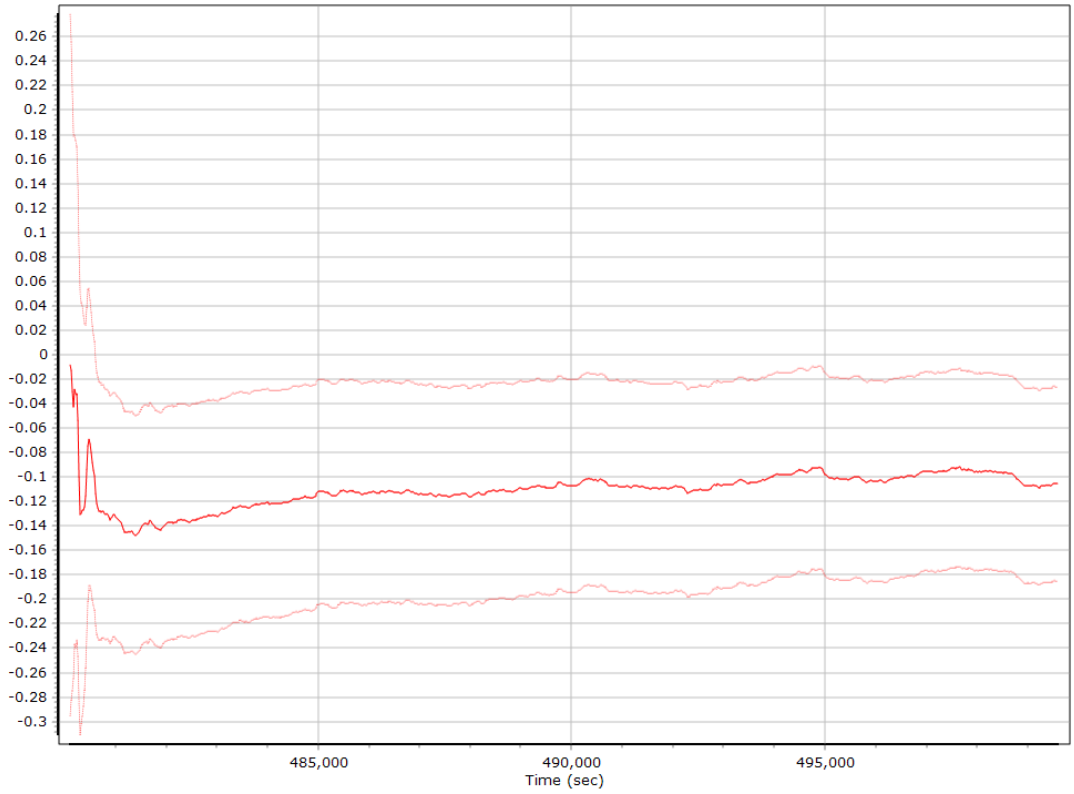
Gyro Bias (deg/h)



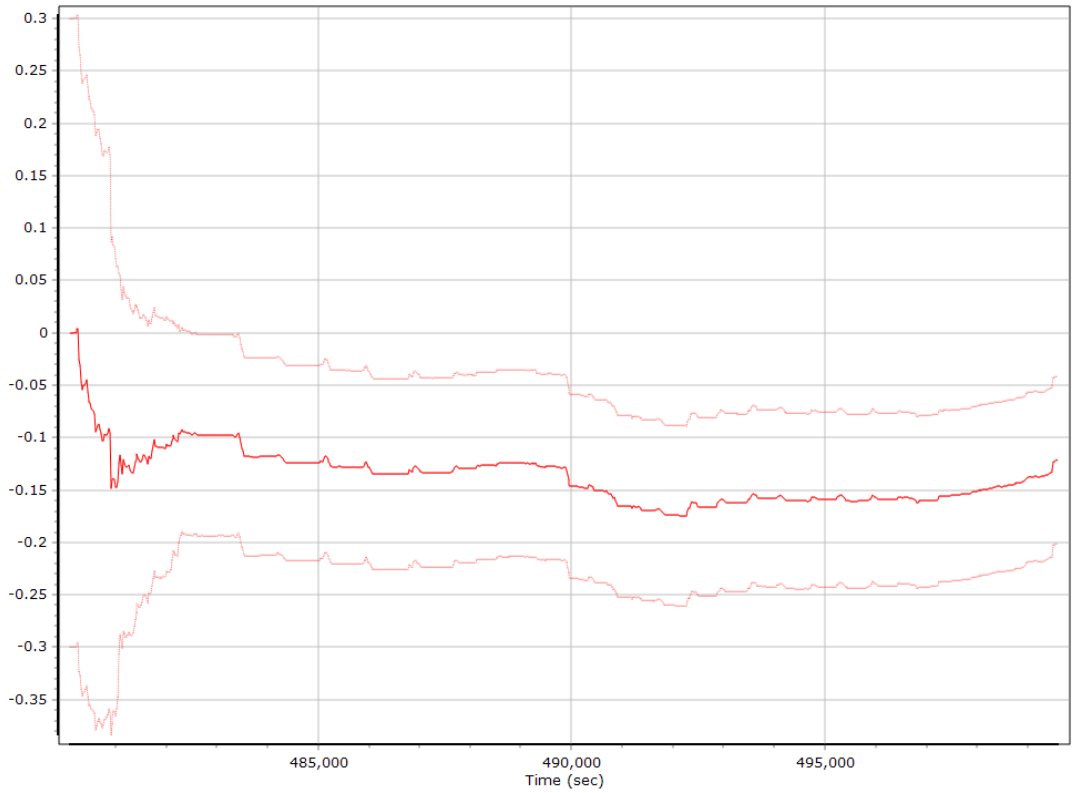
X Gyro Bias (deg/h)



Y Gyro Bias (deg/h)

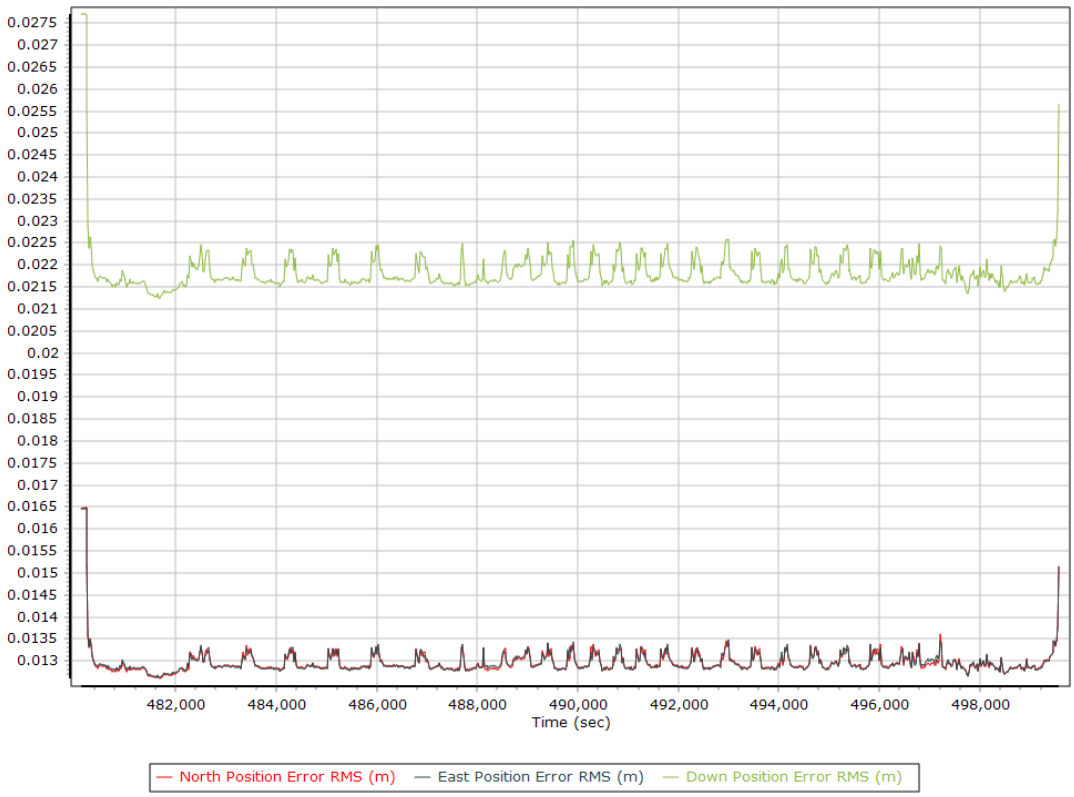


Z Gyro Bias (deg/h)

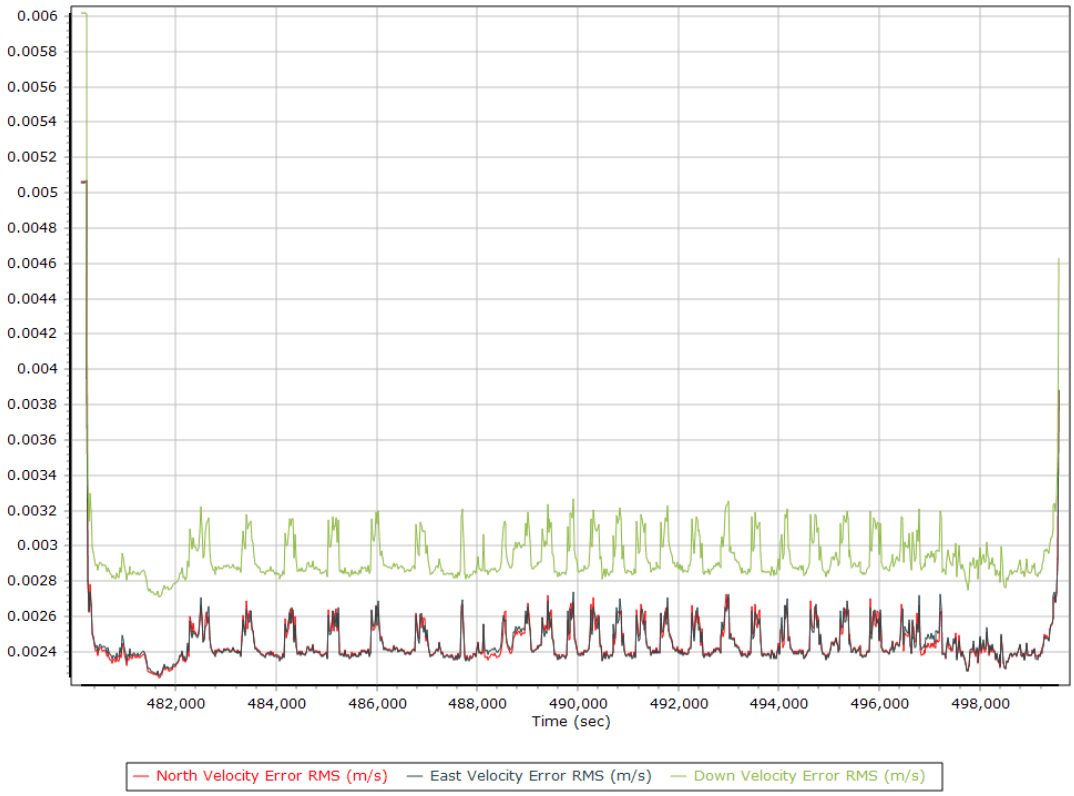


Smoothed Performance Metrics

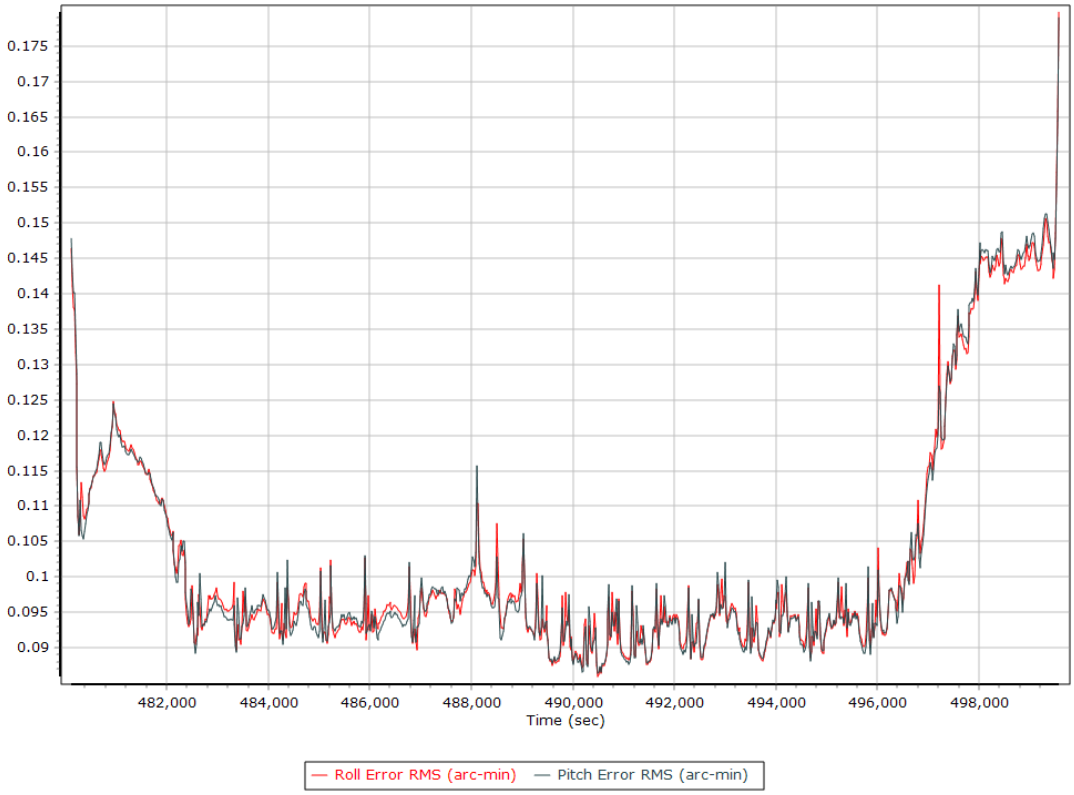
Position Error RMS (m)



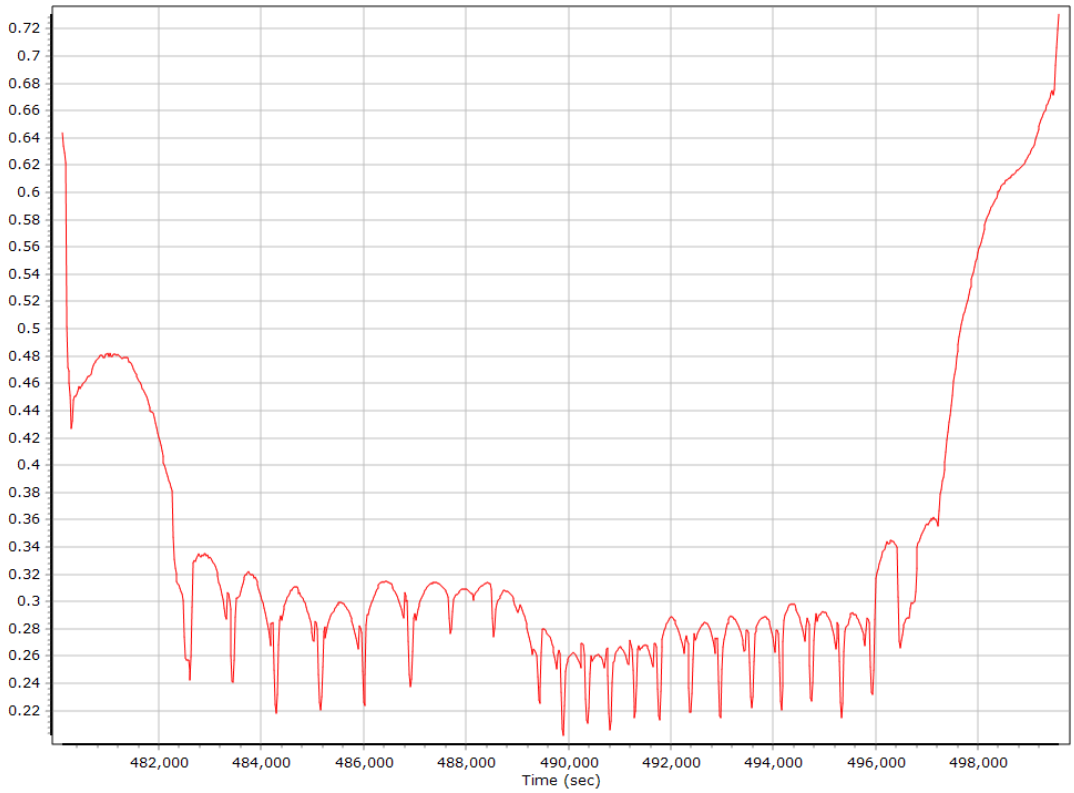
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

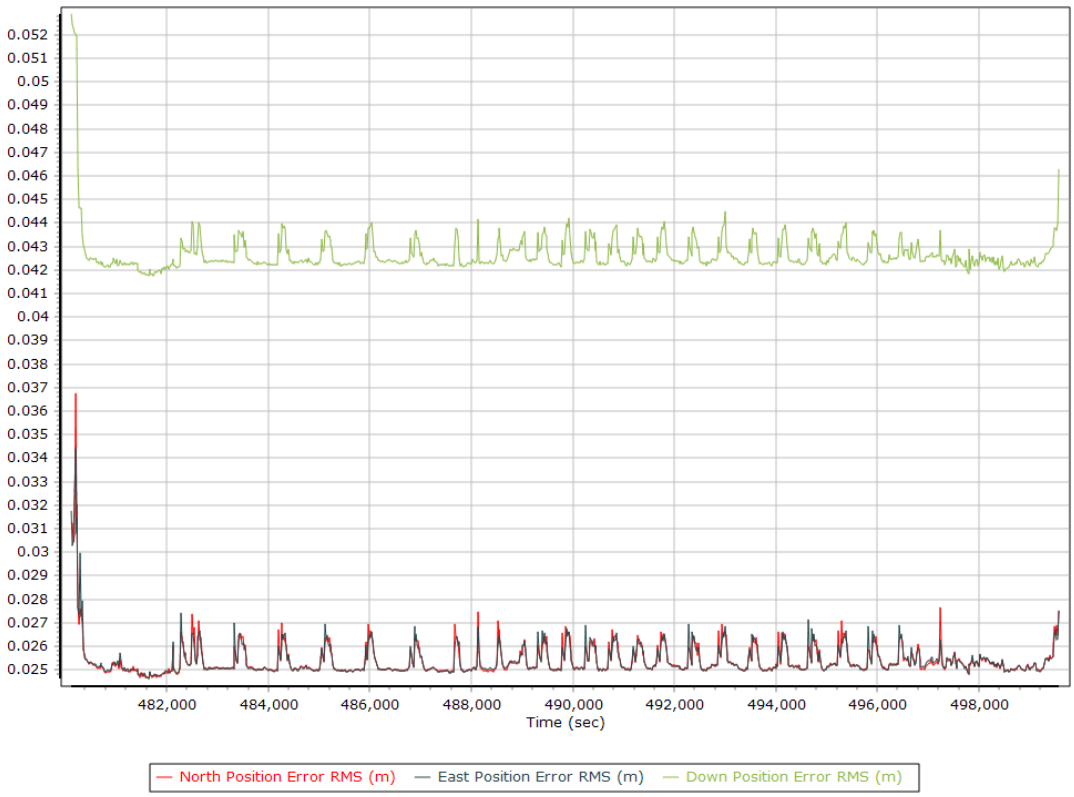


Heading Error RMS (arc-min)

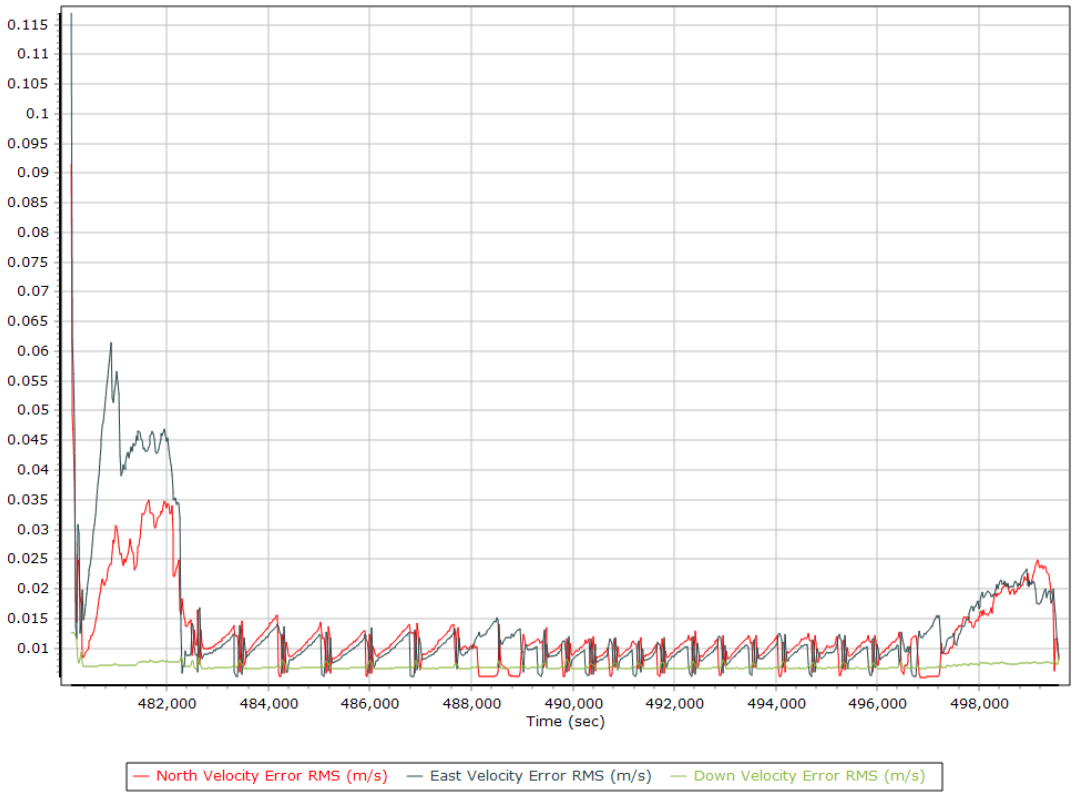


Forward Processed Performance Metrics

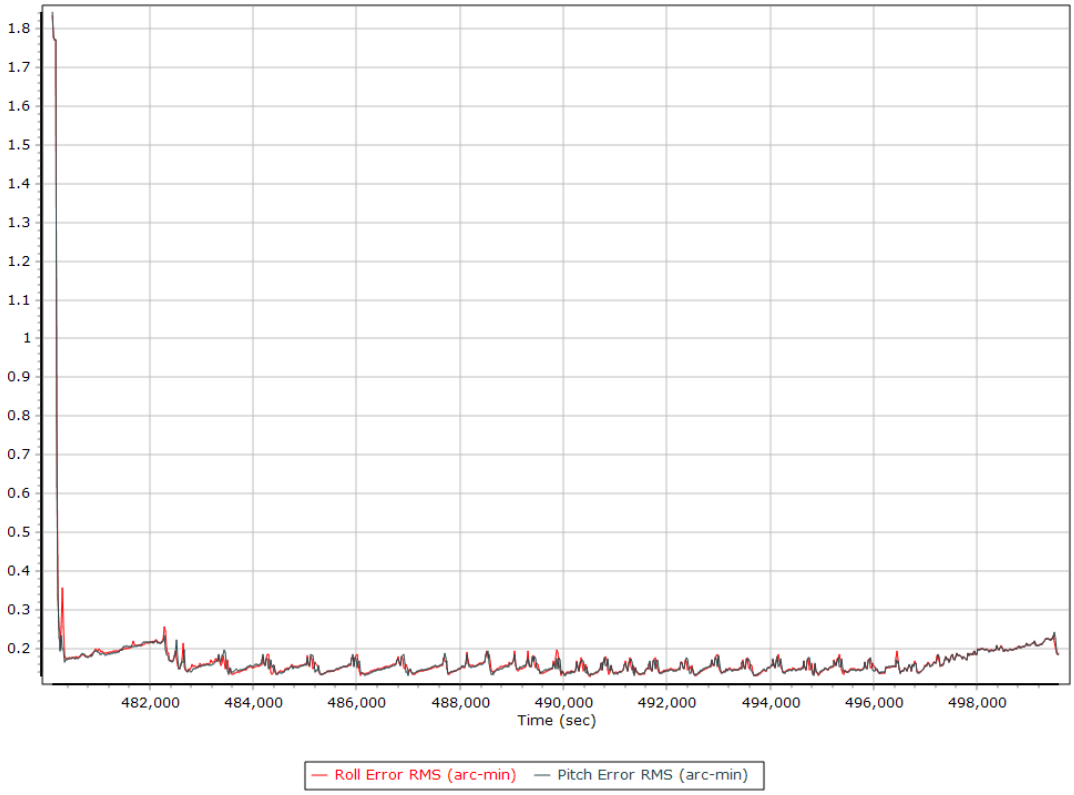
Position Error RMS (m)



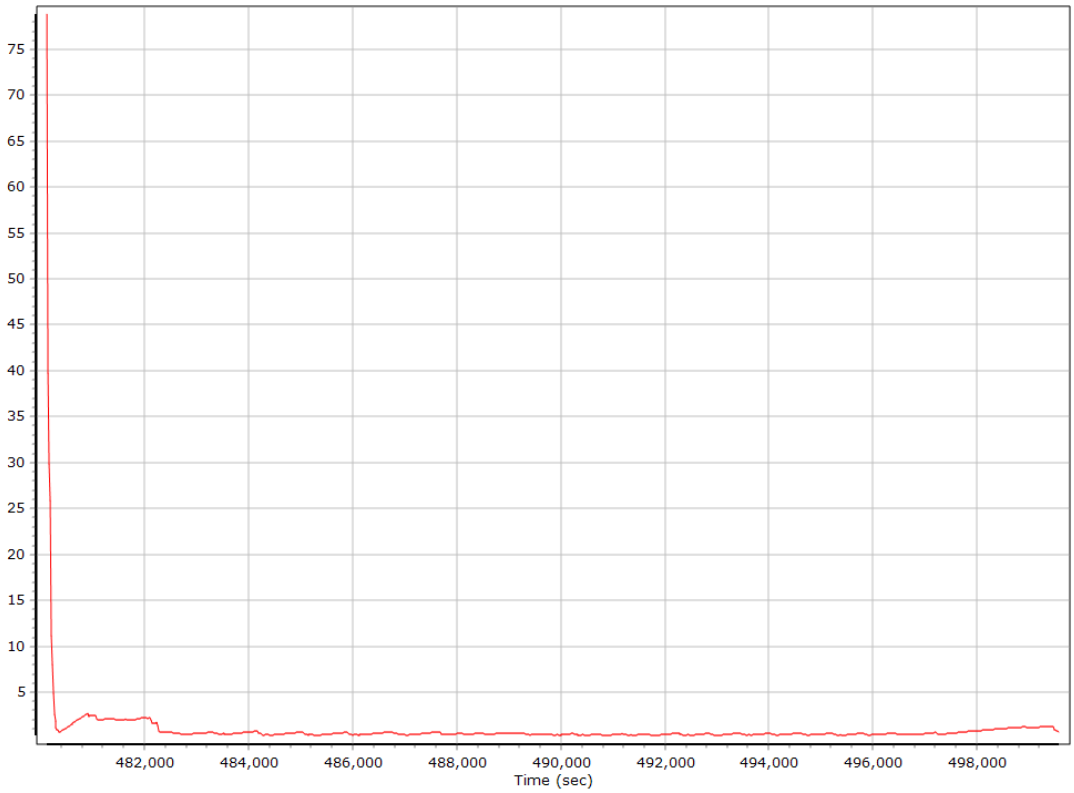
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

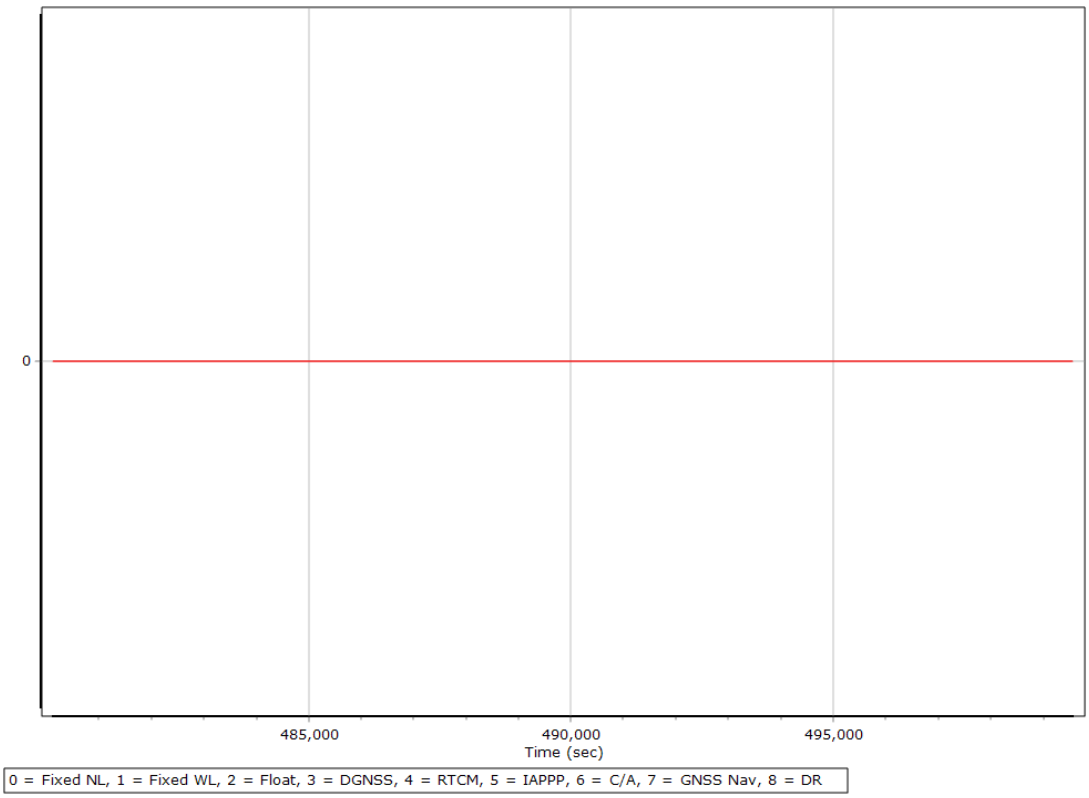


Heading Error RMS (arc-min)

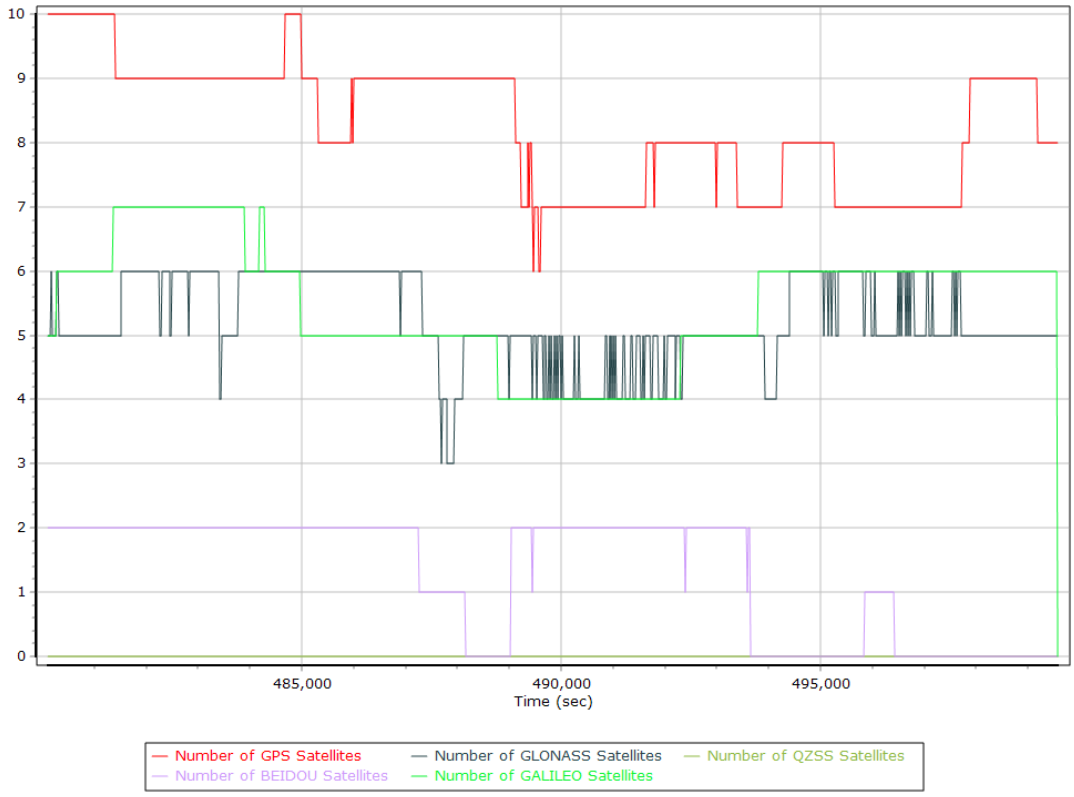


Forward Processed Solution Status

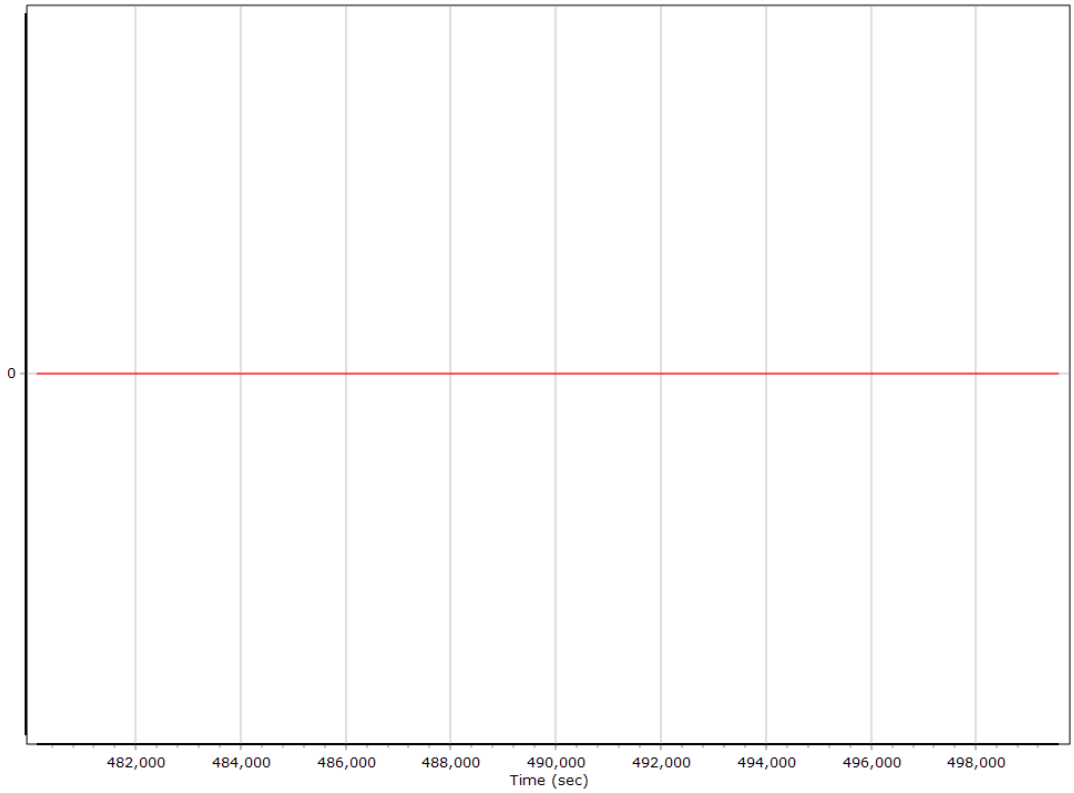
Processing Mode



Number of Satellites



Baseline Length



Export Summary

Export file	sbet_200703_A_5060380_nad2011_FINAL.shp		
Export format	Shapefile		
Solution in use	Post-processed		
Output rate	Specified Distance Interval		
Distance Interval (m)	10.000		
Reference to Output lever arm (m)	0.000	0.000	0.000
Reference mounting angles (deg)	0.000	0.000	0.000
Output units (Coordinate / Lat & Lon)	Meter	Deg Decimal	
Export start time	480058.005 (07/03/2020 13:20:58)		
Export end time	499591.002 (07/03/2020 18:46:31)		
Height option	Ellipsoid Height		
WGS84 height flag	False		
Grid	CONUS Albers		
Zone	CONUS Albers		
Datum	NAD83 (2011)		
Ellipsoid	GRS 1980		
Local Transformation	NONE		
Target Epoch	2010		