General Information

Mission Information

Project name	19-058_110419
Processing date	2019-11-26 20:12:26
Mission date	2019-11-04 17:40:25
Mission duration	06:14:44.000
Processing mode	IN-Fusion Trimble RTX Nav

Rover Hardware Information

Product	POS AV 510 VER6 HW2.4-11
Serial number	S/N6310
IMU type	46
Receiver type	BD982
Antenna type	AV39

Project File List

Rover Data Files

File name	File type
191104_174006_AV510_5361.raw	POS Data

Input Files

File Name	File type
Ephm3080.19g	GLONASS Broadcast Ephemeris
Ephm3080.19n	GPS Broadcast Ephemeris
Ephm3090.19g	GLONASS Broadcast Ephemeris
Ephm3090.19n	GPS Broadcast Ephemeris
igl20780.sp3	GLONASS Precise Ephemeris
igl20781.sp3	GLONASS Precise Ephemeris
igl20782.sp3	GLONASS Precise Ephemeris
igs20780.sp3	GPS Precise Ephemeris
igs20781.sp3	GPS Precise Ephemeris
igs20782.sp3	GPS Precise Ephemeris

Output Files

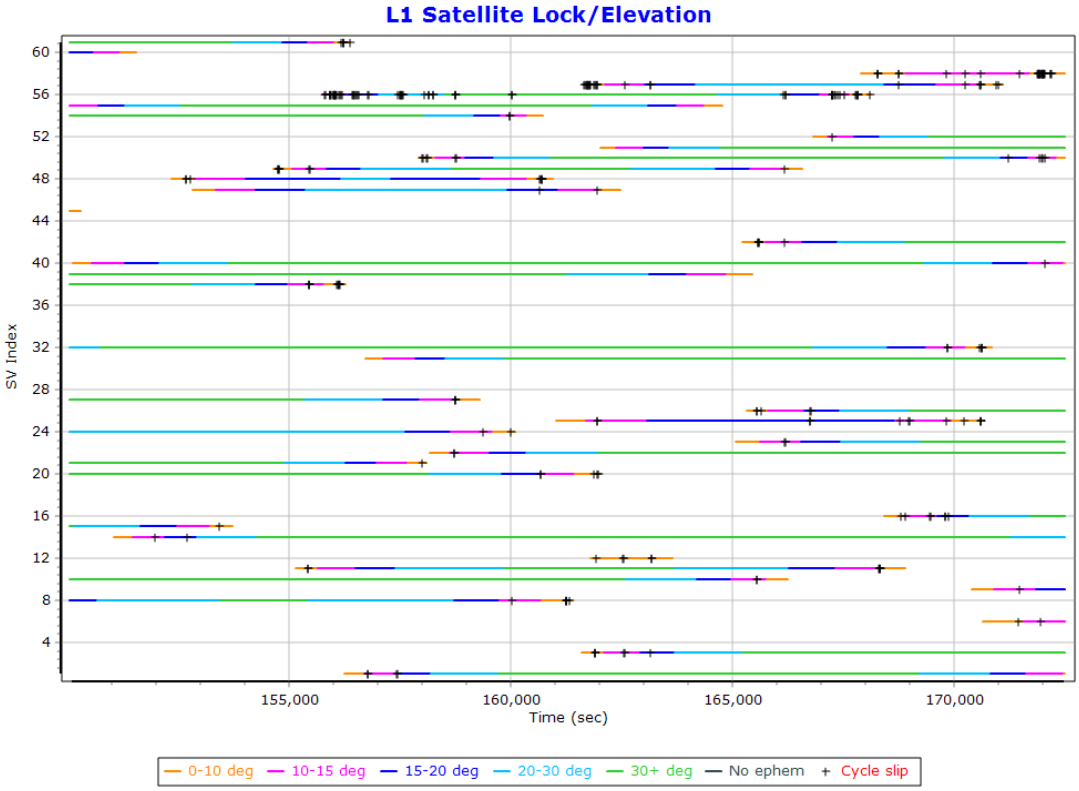
Filename	File type
sbet_19-058_110419.out	SBET Trajectory File

Rover Data Summary

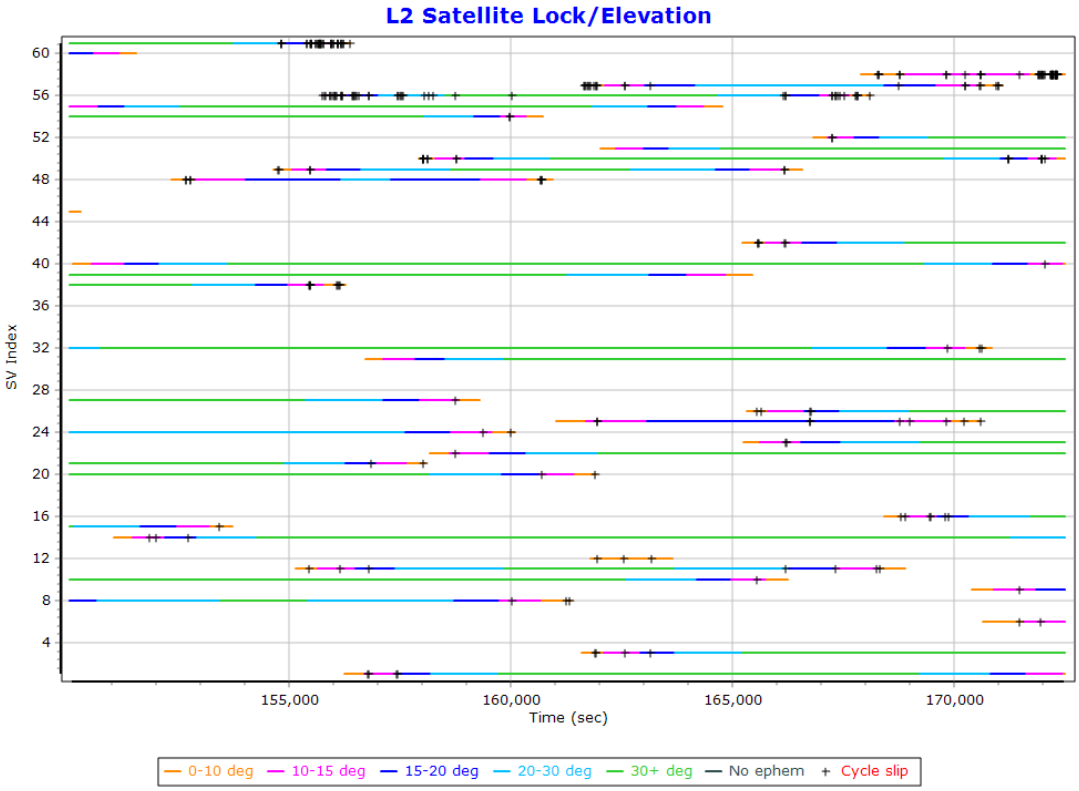
First raw data file	191104_174006_AV510_5361.raw		
Last raw data file	191104_174006_AV510_5361.raw		
Start GPS week	2078		
Start time	150006.830 (11/04/2019 17:40:06)		
End time	172483.875 (11/04/2019 23:54:43)		
Start of fine alignment	150025.252 (11/04/2019 17:40:25)		
Available subsystems	Primary GNSS, IMU		
POS Event Input	None		
Correction data	Trimble RTX		
IMU Installation Lever Arms & Mounting Angles			
Reference to IMU lever arm [m]	0.000	0.000	0.000
Reference to IMU mounting angles [deg]	0.000	0.000	0.000
Reference to Primary GNSS lever arm [m]	-0.011	0.039	-1.017
Reference to Primary GNSS lever arm std dev [m]	-1.000		
Aircraft to Reference mounting angles [deg]	0.000	0.000	0.000

Raw Data QC

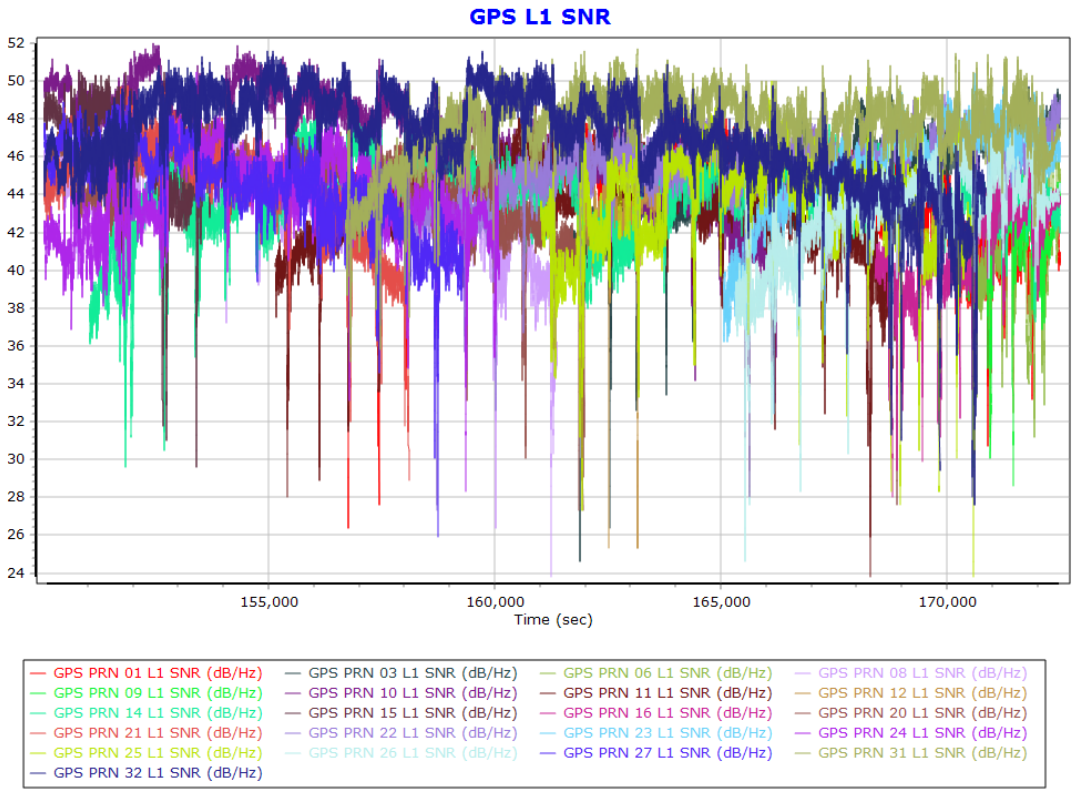
L1 Satellite Lock/Elevation



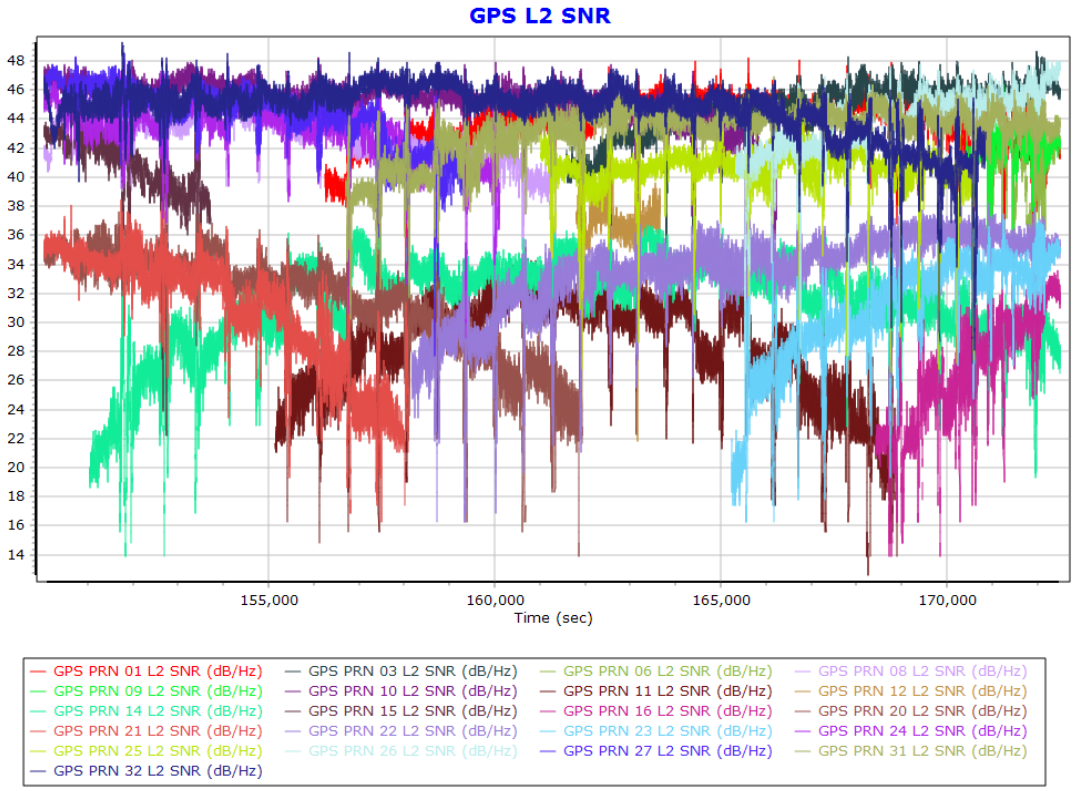
L2 Satellite Lock/Elevation



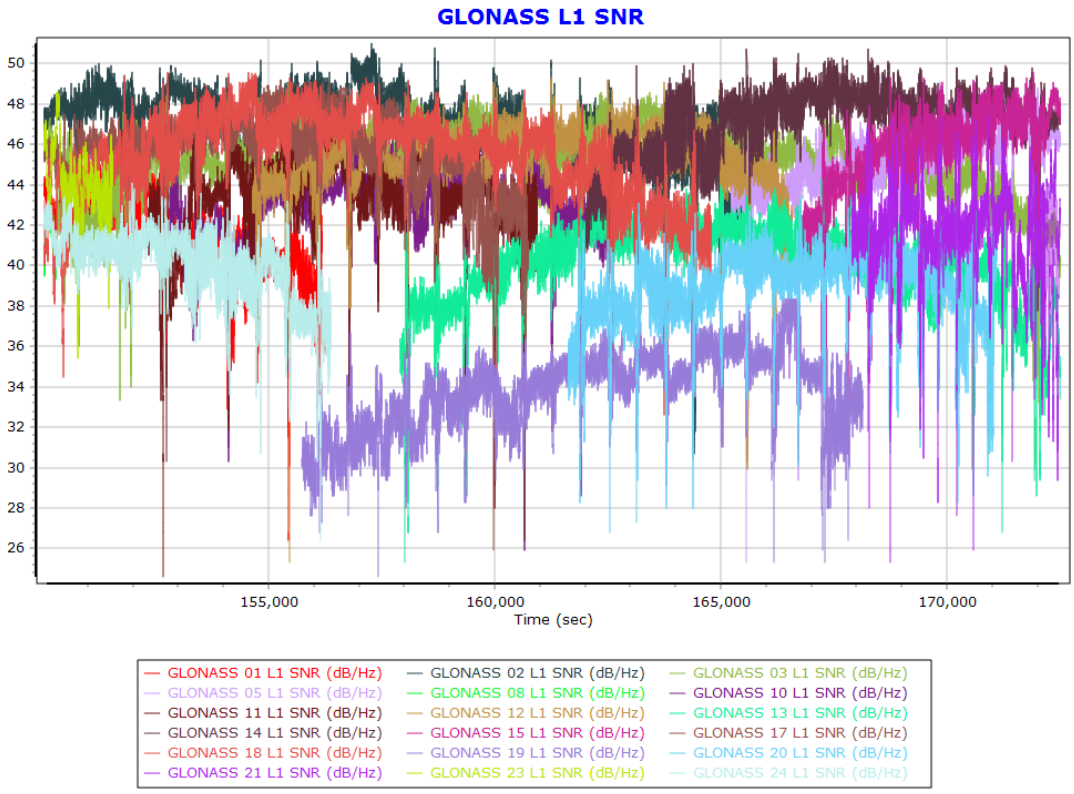
GPS L1 SNR



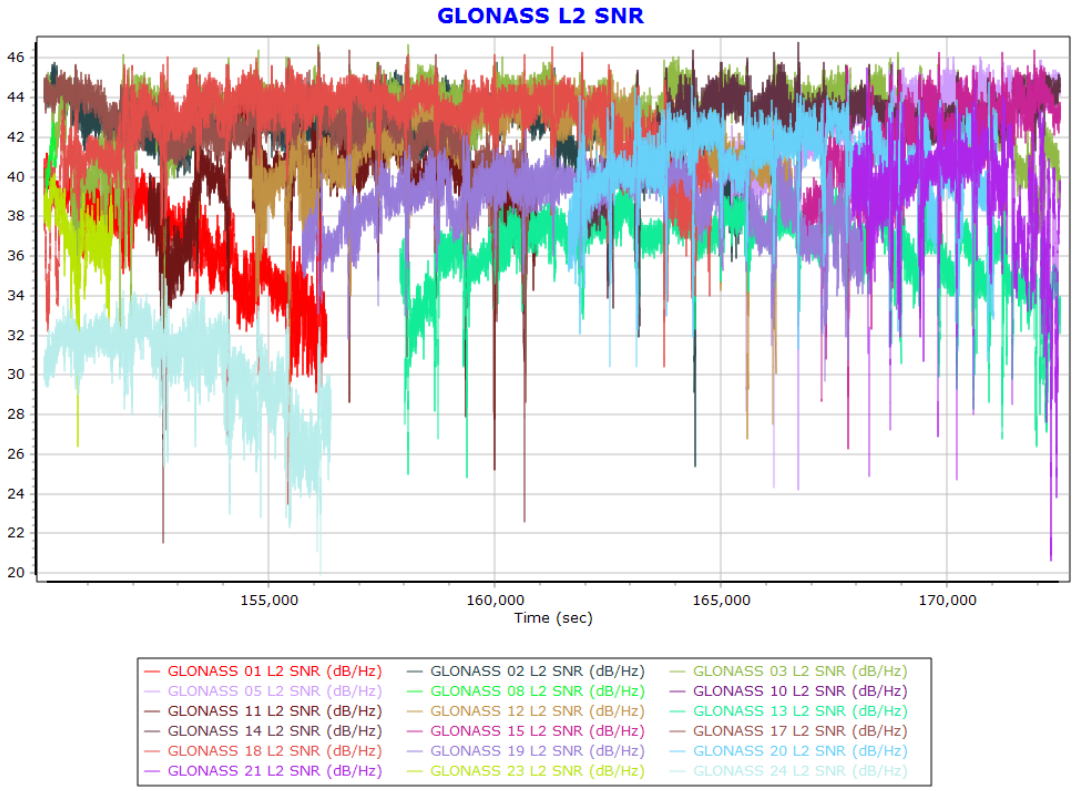
GPS L2 SNR



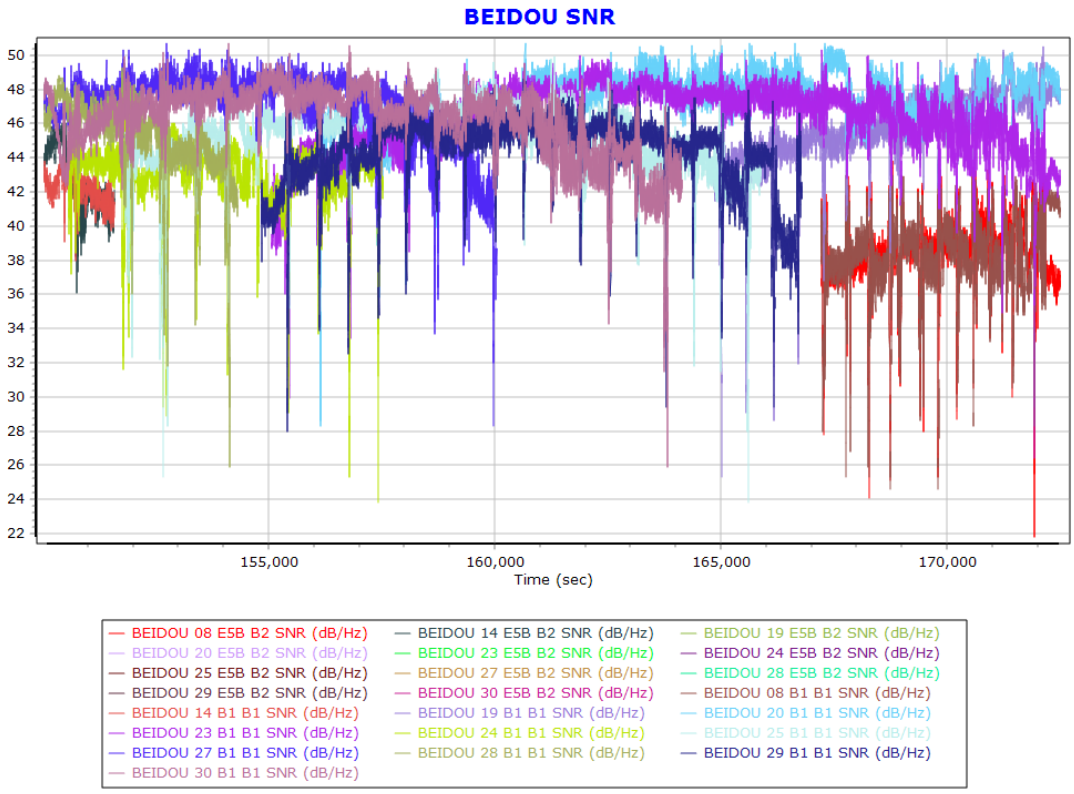
GLONASS L1 SNR



GLONASS L2 SNR

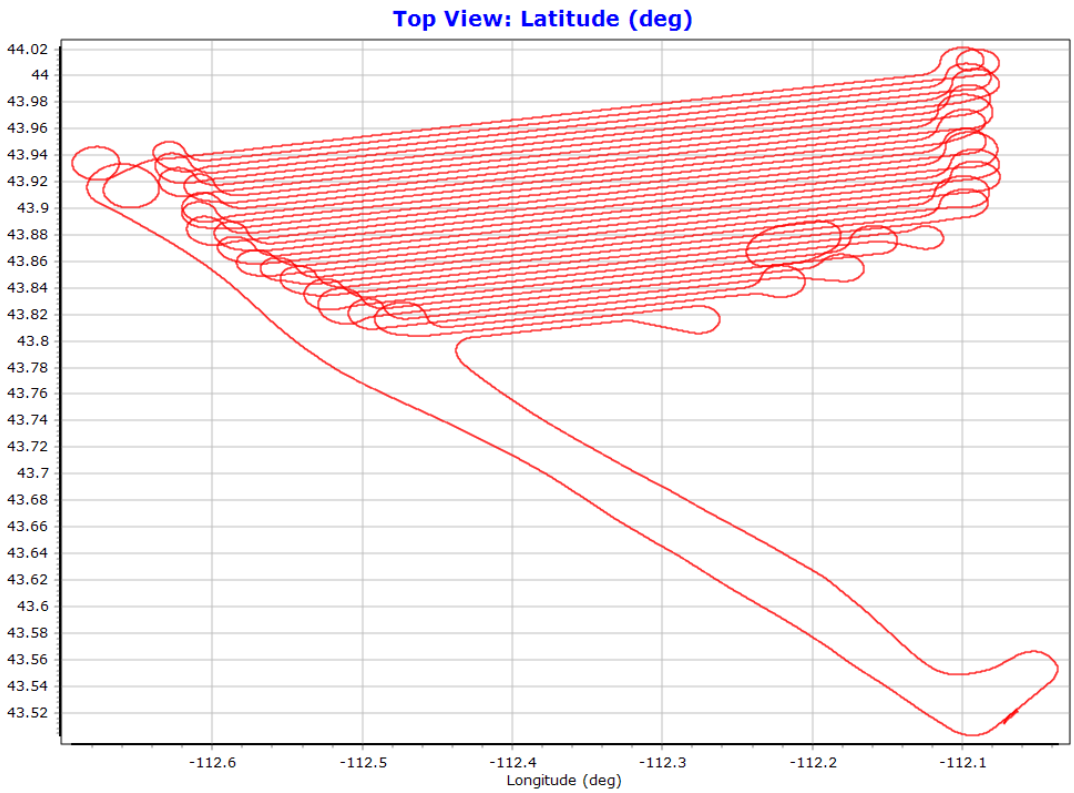


BEIDOU SNR

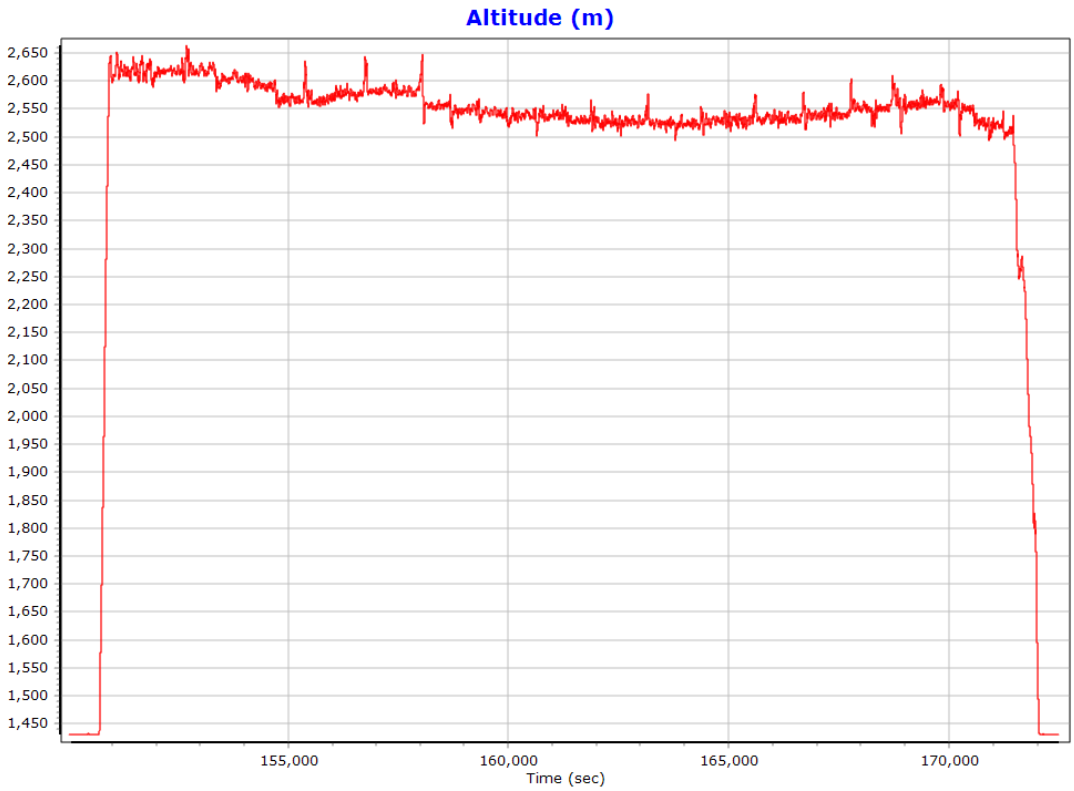

BEIDOU SNR
50
48
46
44
42
40
38
36
34
32
30
28
26
24
22
155,000
160,000
165,000
170,000
Time (sec)
BEIDOU 08 E5B B2 SNR (dB/Hz)
BEIDOU 14 E5B B2 SNR (dB/Hz)
BEIDOU 19 E5B B2 SNR (dB/Hz)
BEIDOU 20 E5B B2 SNR (dB/Hz)
BEIDOU 23 E5B B2 SNR (dB/Hz)
BEIDOU 24 E5B B2 SNR (dB/Hz)
BEIDOU 25 E5B B2 SNR (dB/Hz)
BEIDOU 27 E5B B2 SNR (dB/Hz)
BEIDOU 28 E5B B2 SNR (dB/Hz)
BEIDOU 29 E5B B2 SNR (dB/Hz)
BEIDOU 30 E5B B2 SNR (dB/Hz)
BEIDOU 08 B1 B1 SNR (dB/Hz)
BEIDOU 14 B1 B1 SNR (dB/Hz)
BEIDOU 19 B1 B1 SNR (dB/Hz)
BEIDOU 20 B1 B1 SNR (dB/Hz)
BEIDOU 23 B1 B1 SNR (dB/Hz)
BEIDOU 24 B1 B1 SNR (dB/Hz)
BEIDOU 25 B1 B1 SNR (dB/Hz)
BEIDOU 27 B1 B1 SNR (dB/Hz)
BEIDOU 28 B1 B1 SNR (dB/Hz)
BEIDOU 29 B1 B1 SNR (dB/Hz)
BEIDOU 30 B1 B1 SNR (dB/Hz)

Trajectory Information

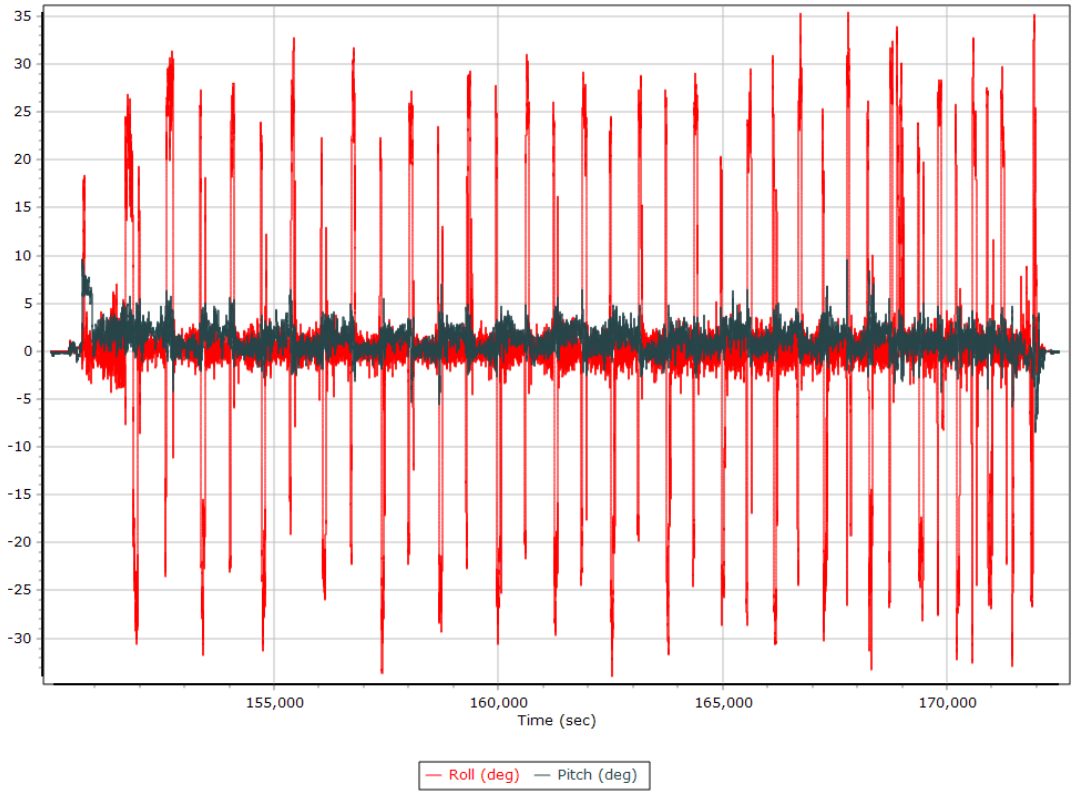
Top View



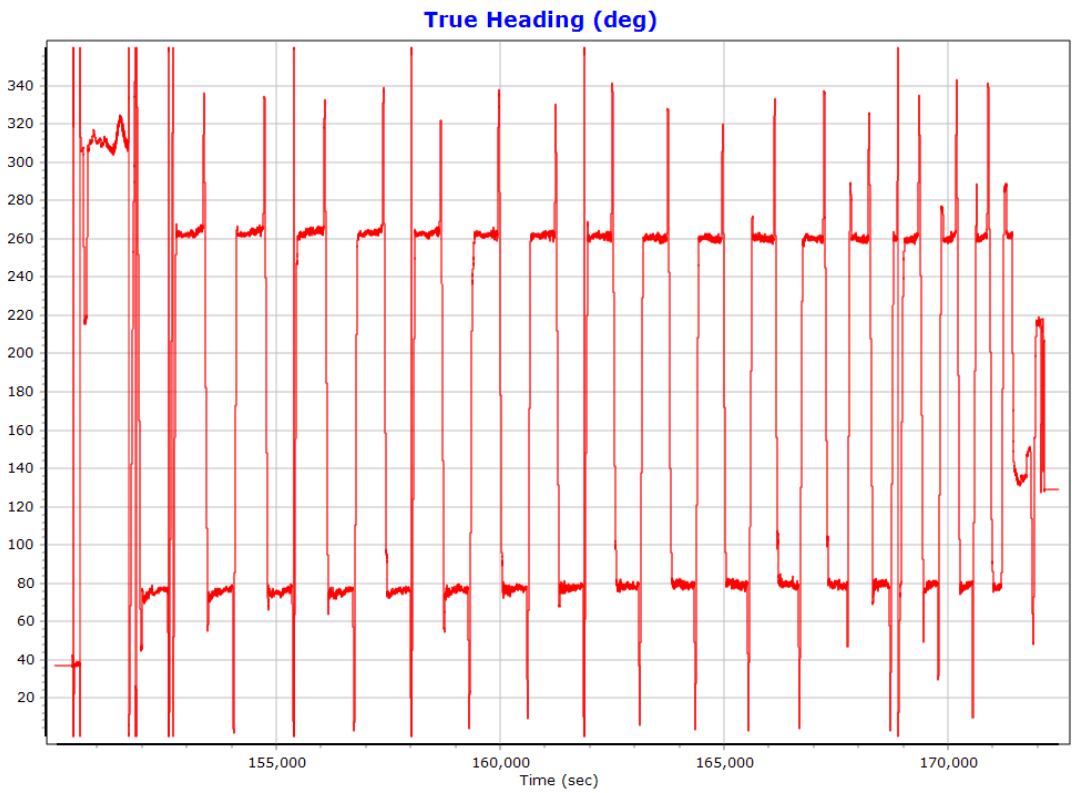
Altitude



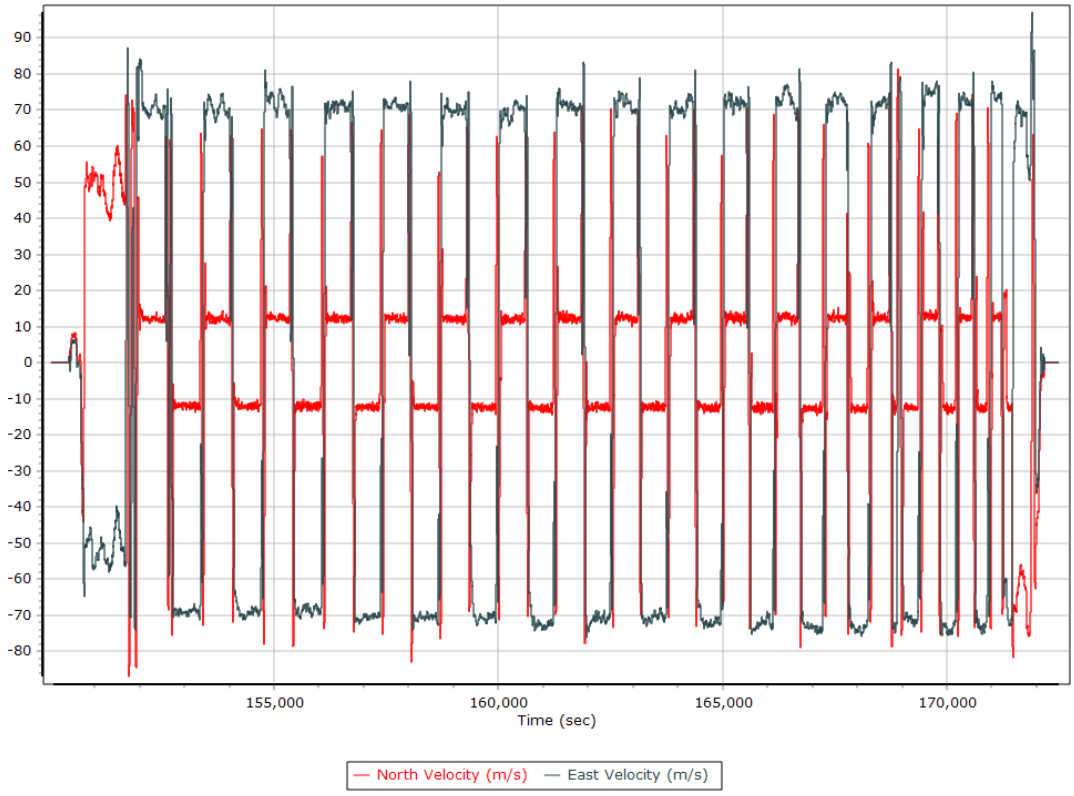
Roll/Pitch



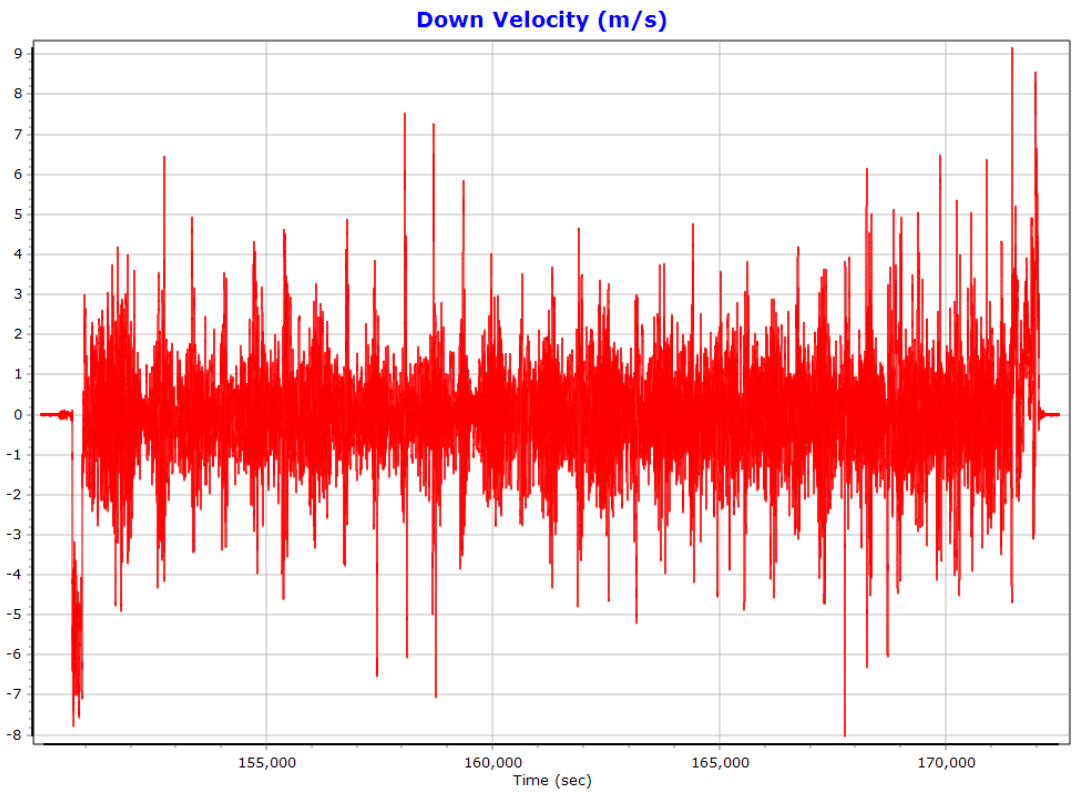
Heading



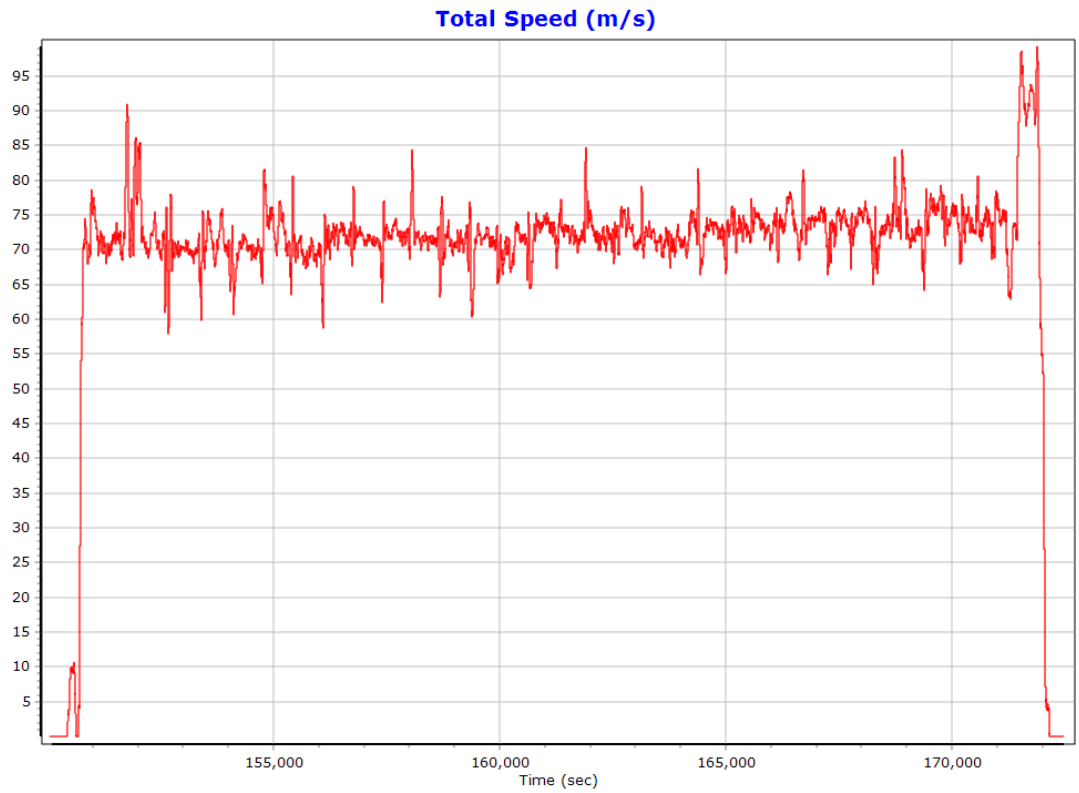
North/East Velocity



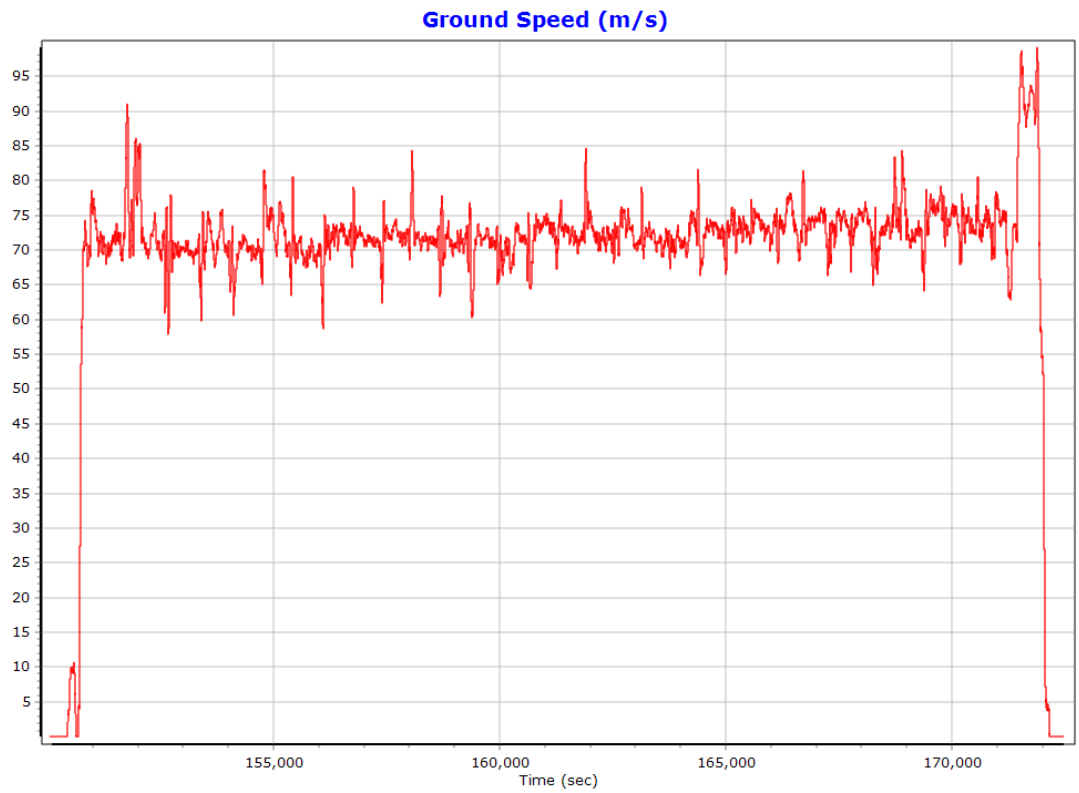
Down Velocity



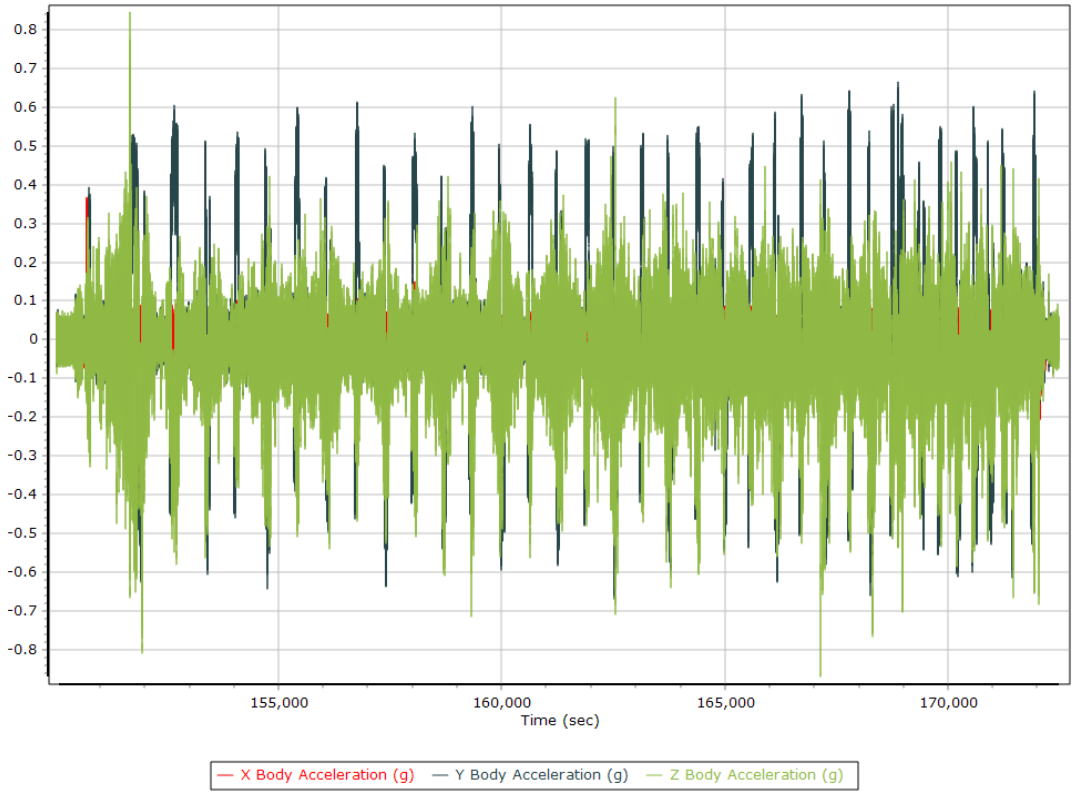
Total Speed



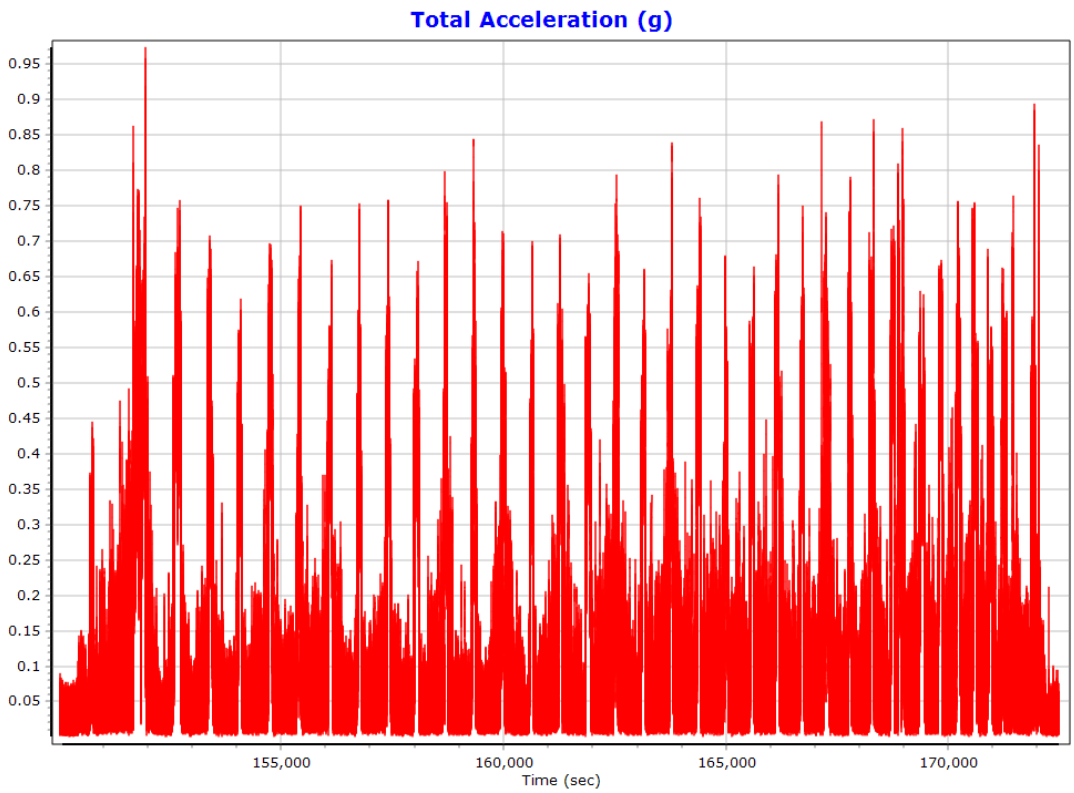
Ground Speed



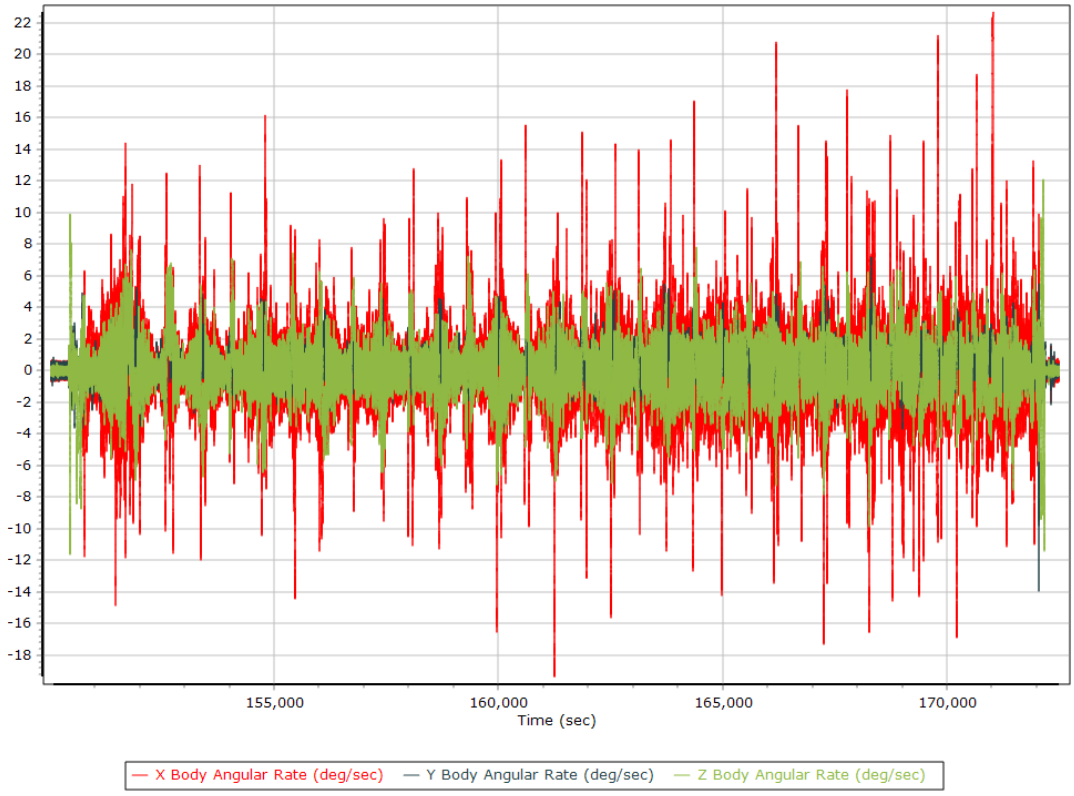
Body Acceleration



Total Body Acceleration



Body Angular Rate



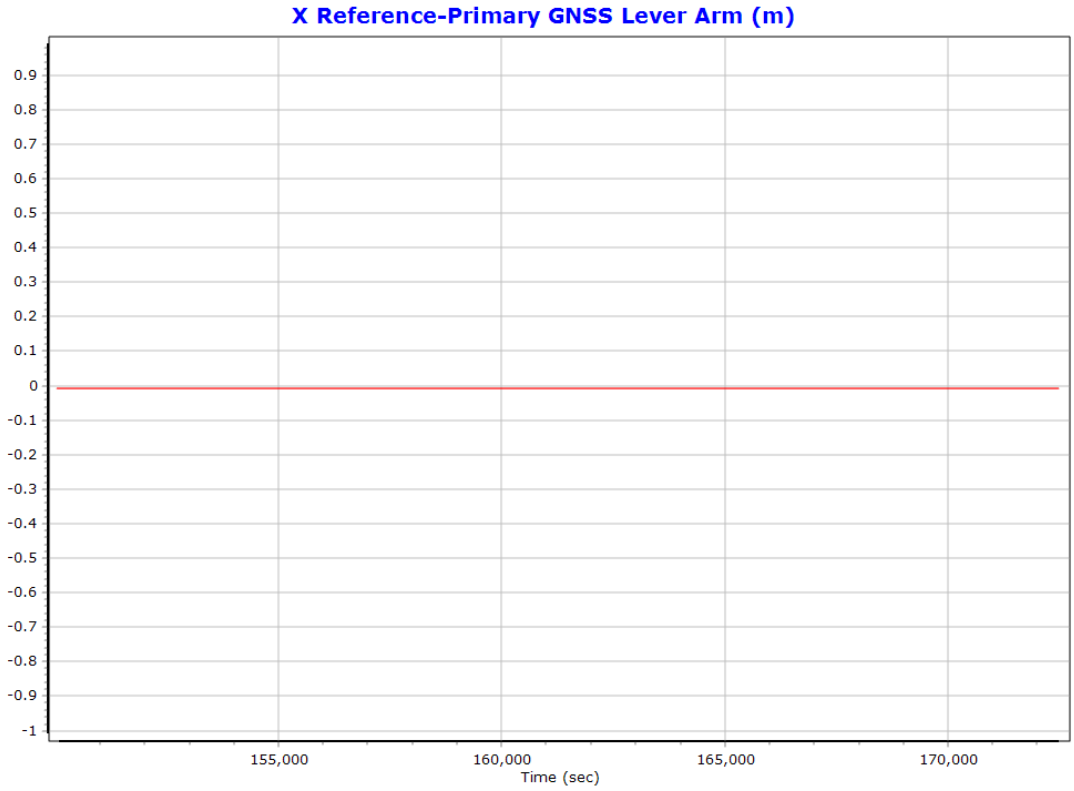
GNSS-Inertial Processor Configuration

Processing mode	IN-Fusion Trimble RTX Nav		
Stabilized mount	False		
Processing start time	150007.000 (11/04/2019 17:40:07)		
Processing end time	172491.000 (11/04/2019 23:54:51)		
Initial attitude source	Real-Time VNAV/RNAV Attitude		
IMU Sensor Context	Processing with Onboard IMU		
Reference to IMU lever arm [m]	0.000	0.000	0.000
Reference to IMU mounting angles [deg]	0.000	0.000	0.000
Reference to Primary GNSS lever arm [m]	-0.008	0.046	-1.014
Reference to Primary GNSS lever arm std dev [m]	0.030	0.030	0.030
Aircraft to Reference mounting angles [deg]	0.000	0.000	0.000

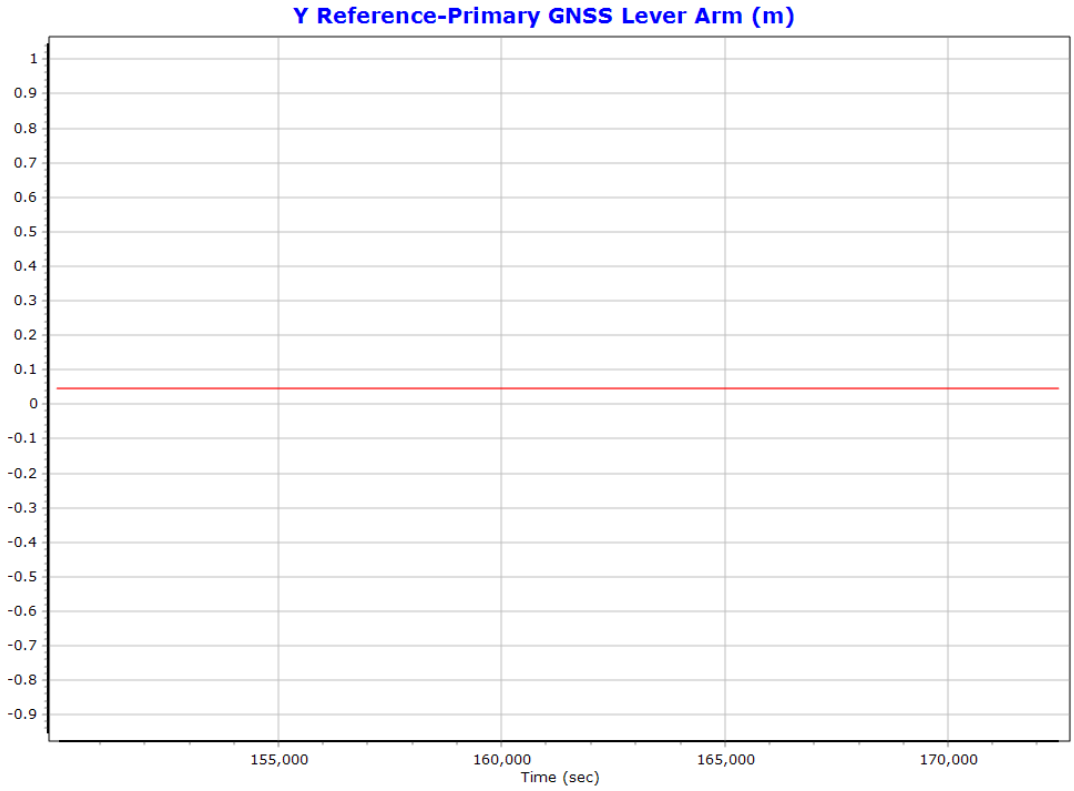
Calibrated Installation Parameters

Reference-Primary GNSS Lever Arm

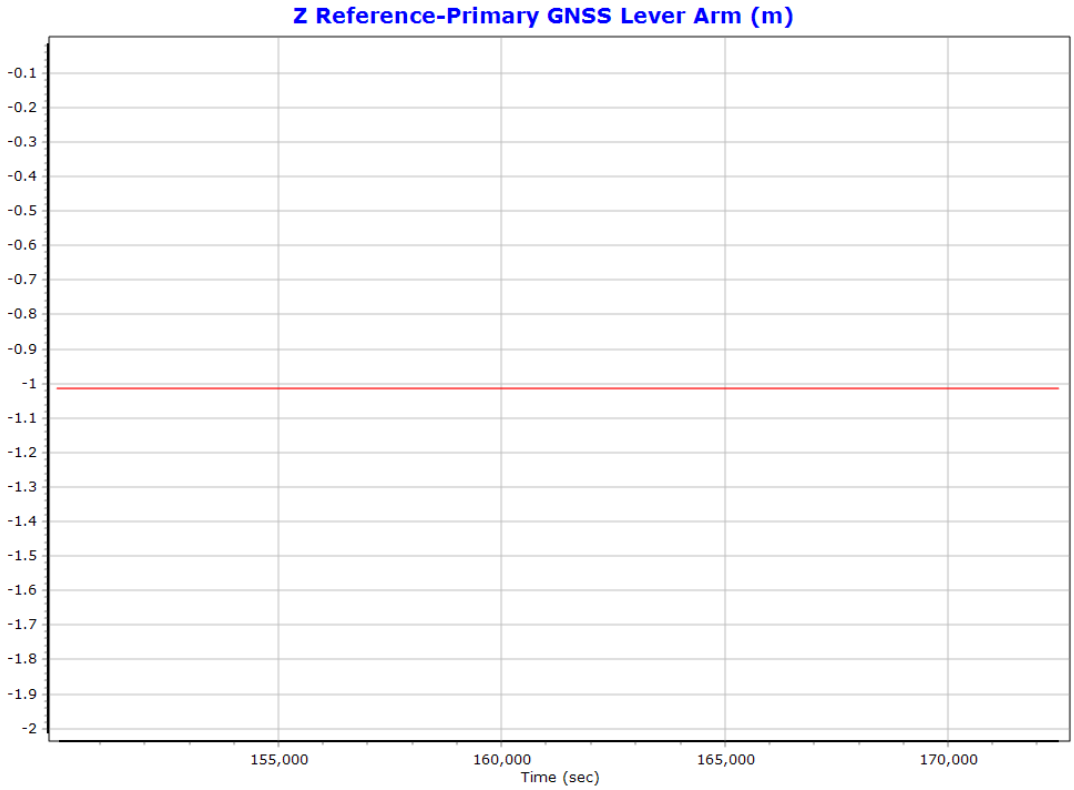
X Reference-Primary GNSS Lever Arm (m)



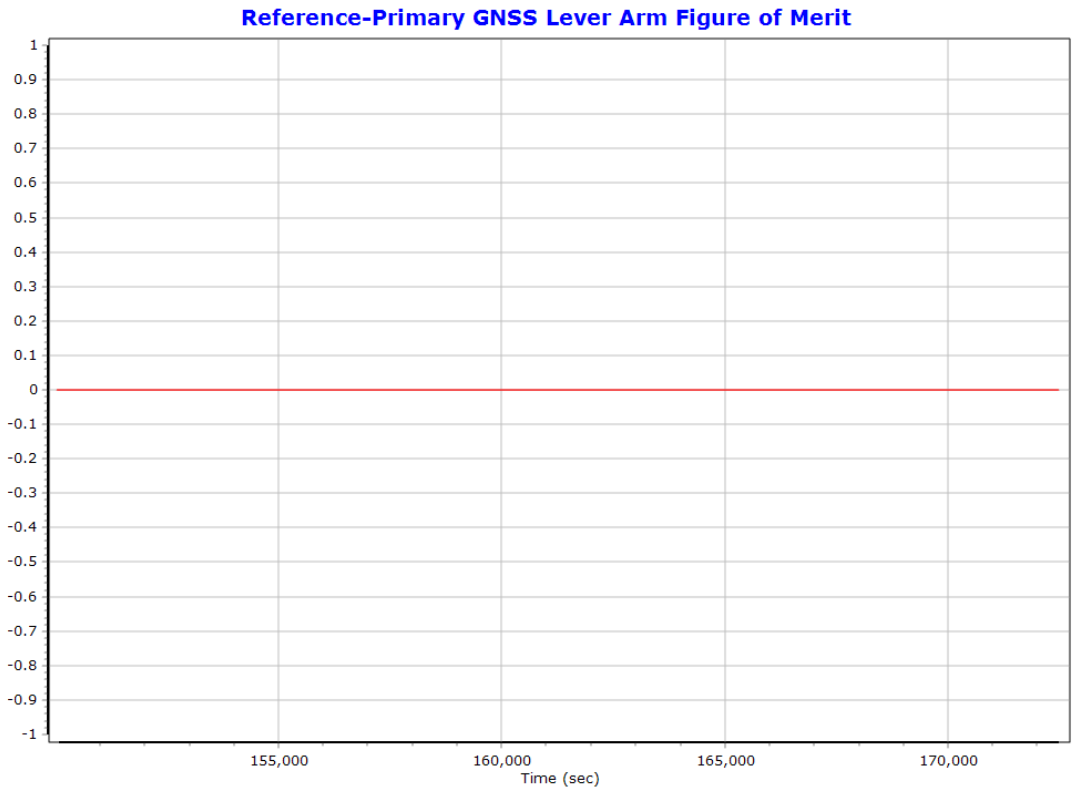
Y Reference-Primary GNSS Lever Arm (m)



Z Reference-Primary GNSS Lever Arm (m)



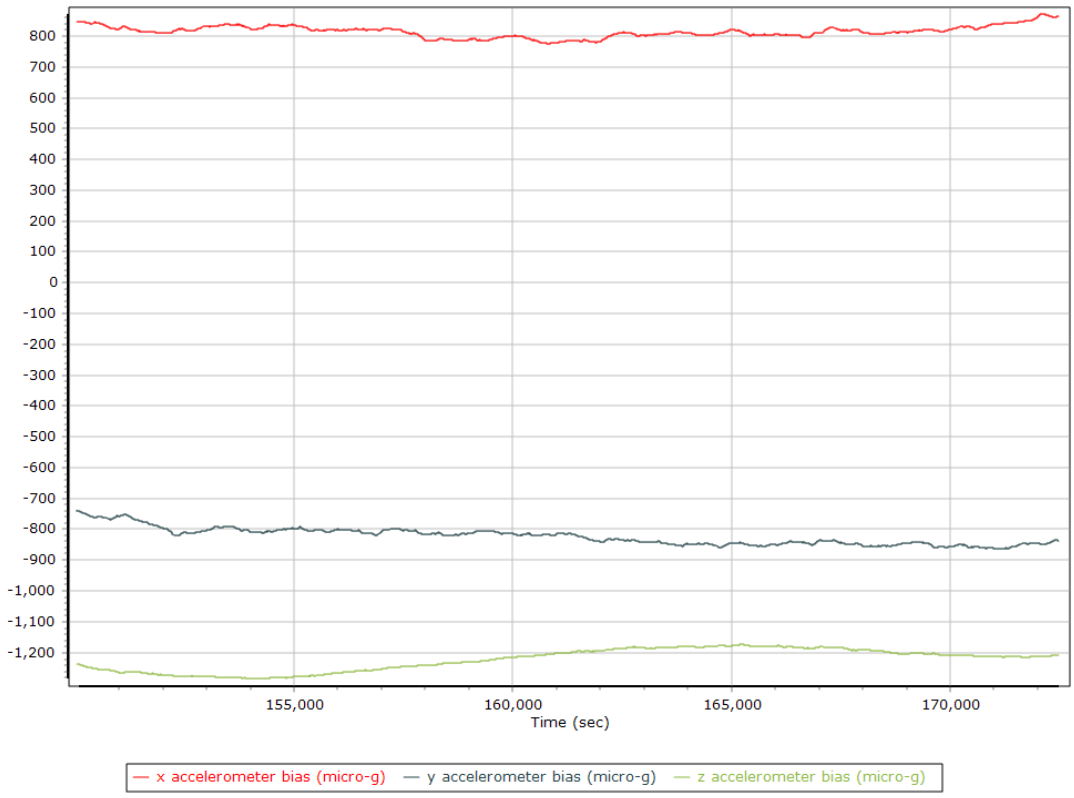
Reference-Primary GNSS Lever Arm Figure of Merit



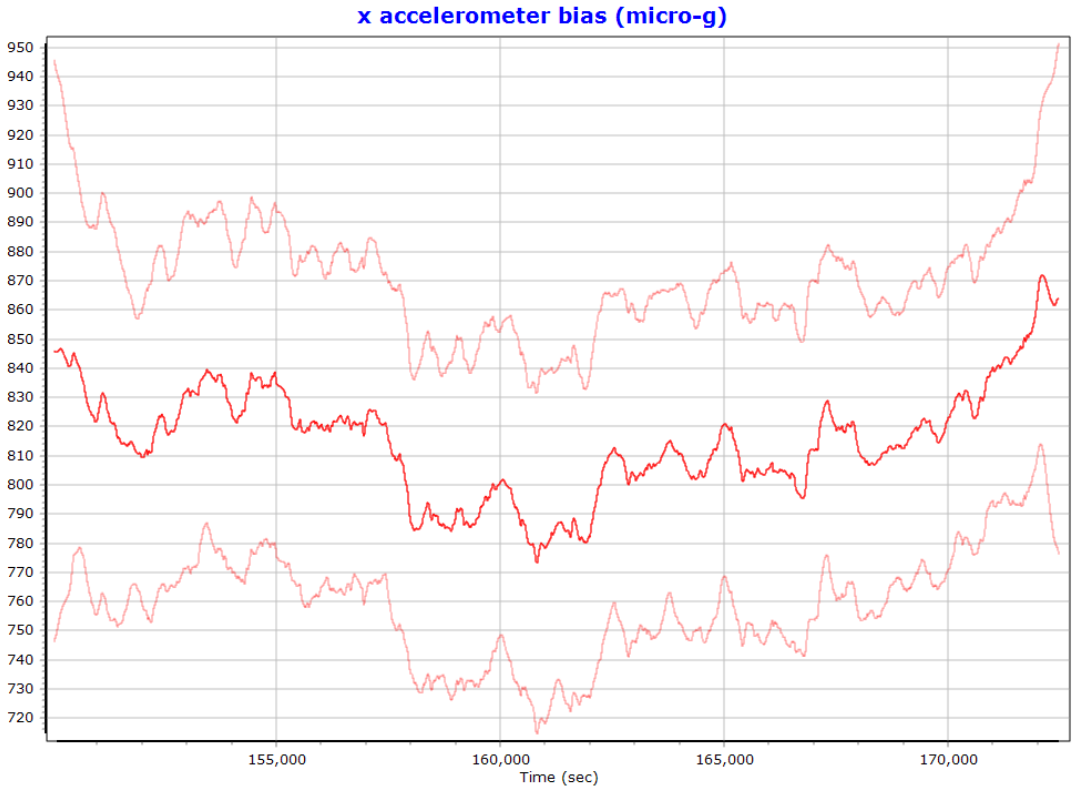
Smoothed IN-Fusion QC

Smoothed Estimated Errors, Reference Frame

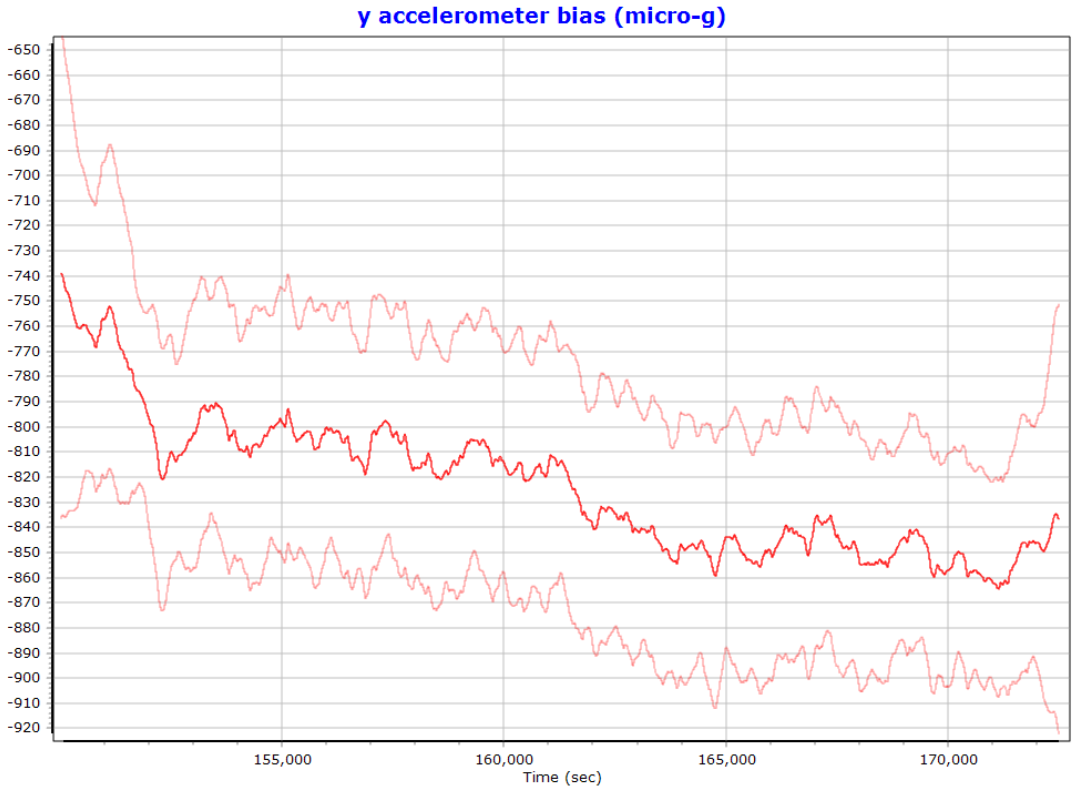
Accelerometer Bias (micro-g)



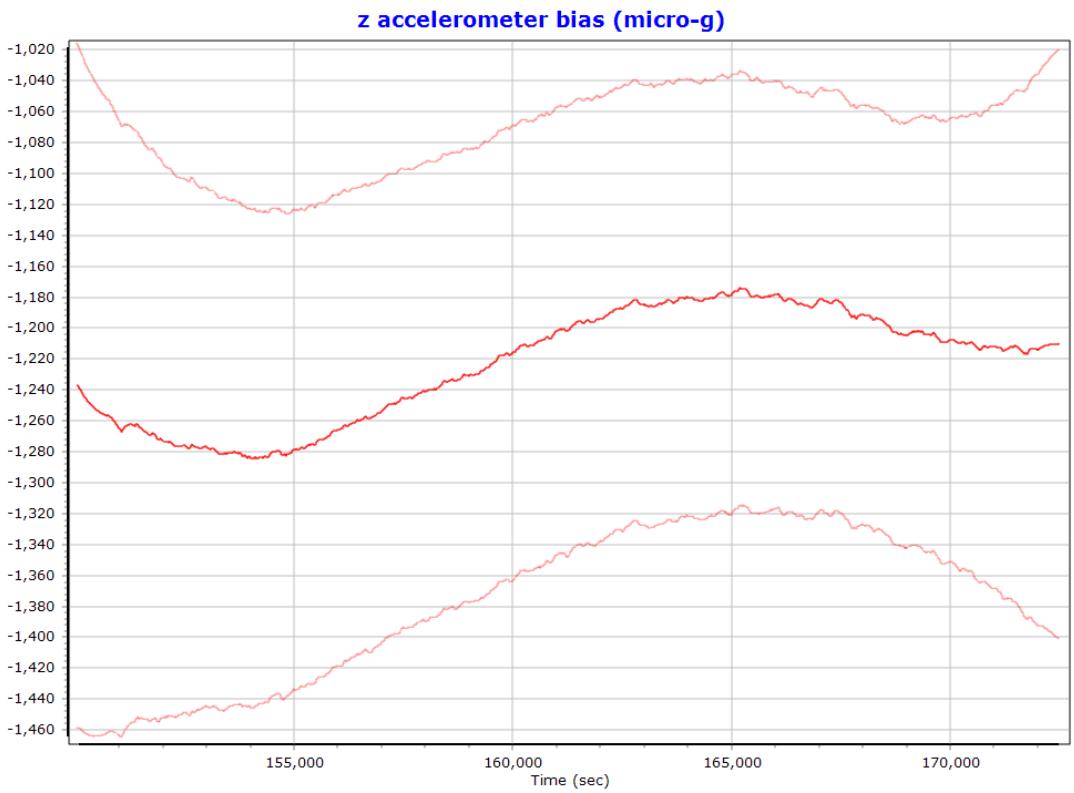
X Accelerometer Bias (micro-g)



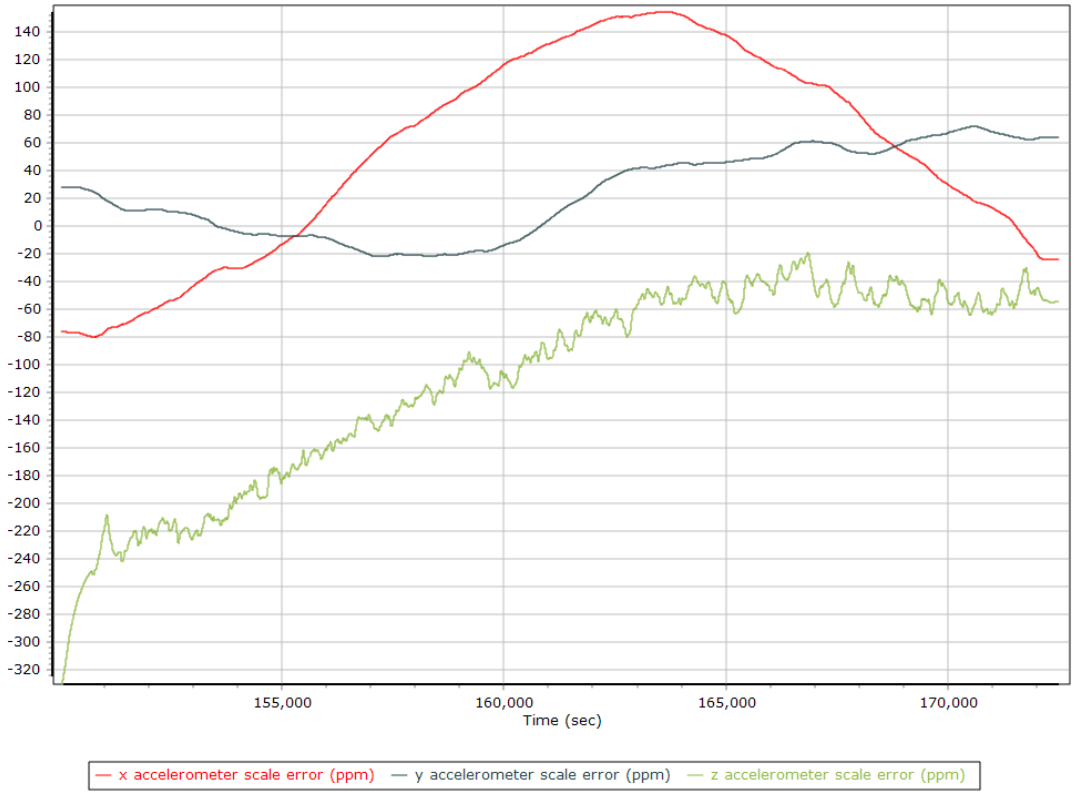
Y Accelerometer Bias (micro-g)



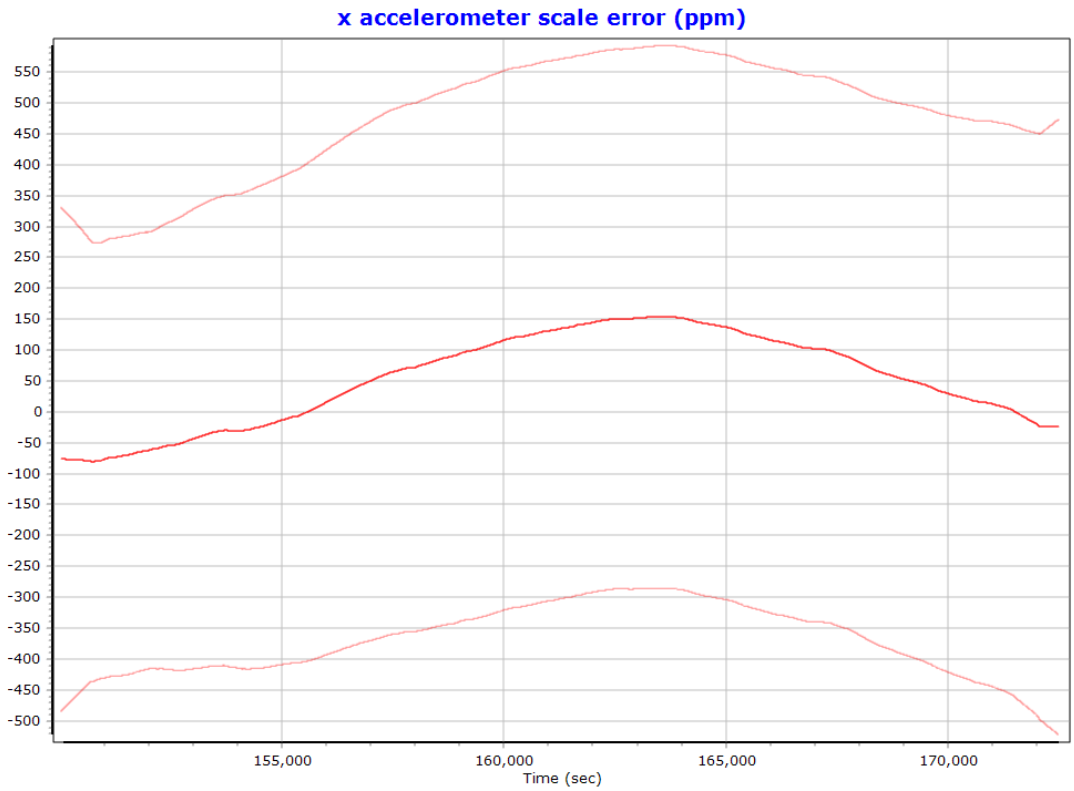
Z Accelerometer Bias (micro-g)



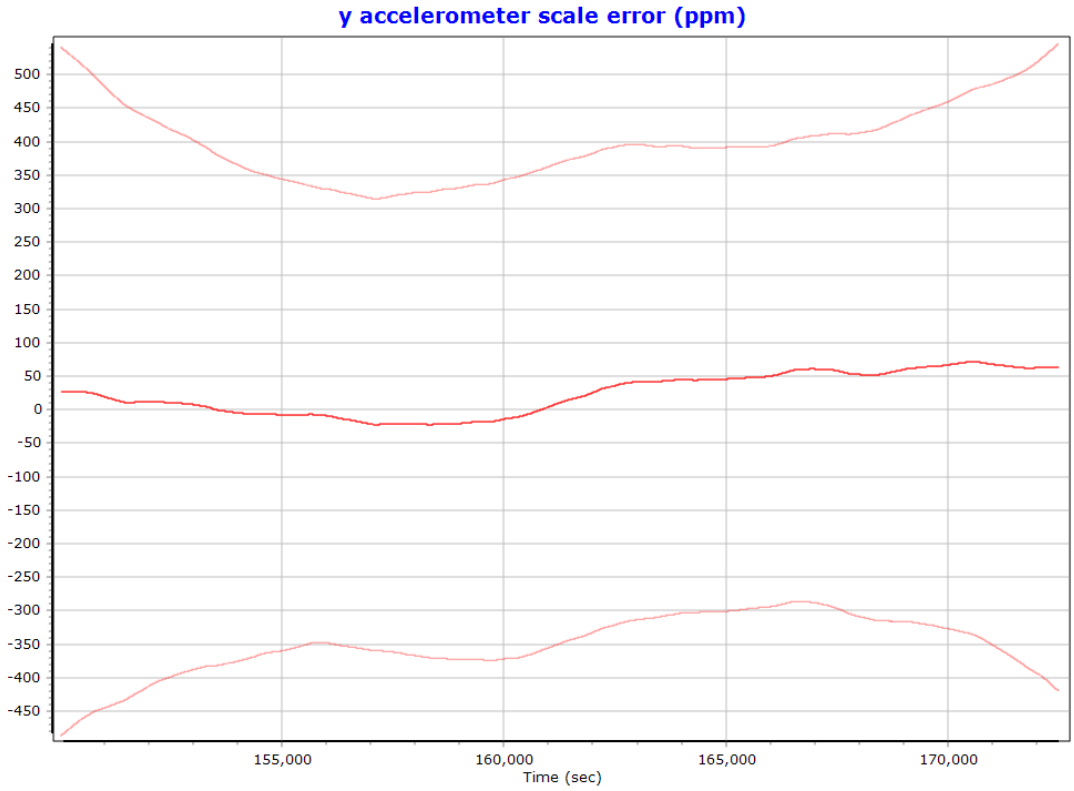
Accelerometer Scale Error (ppm)



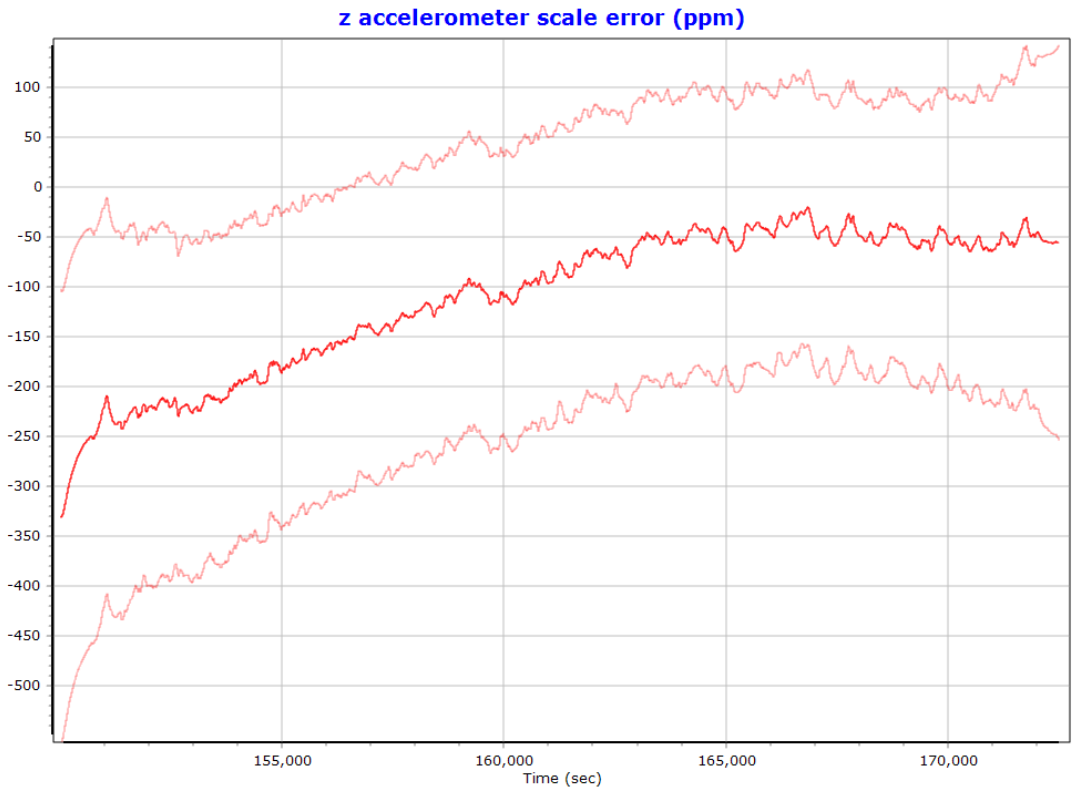
X Accelerometer Scale Error (ppm)



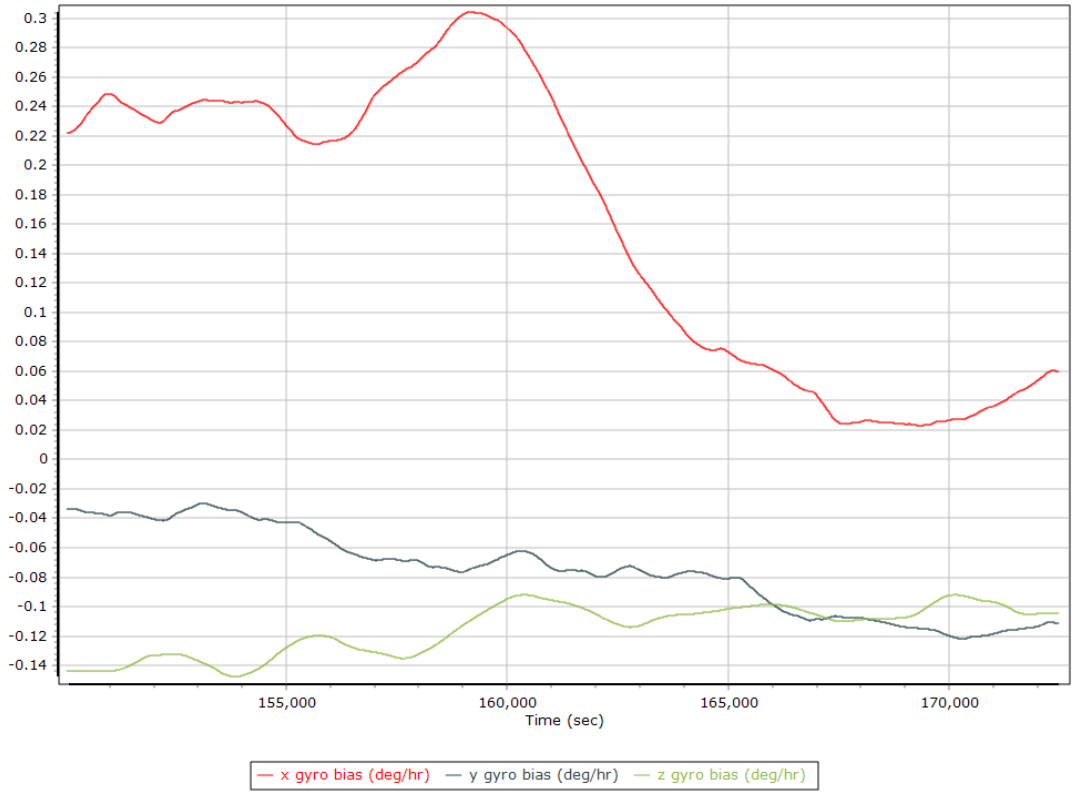
Y Accelerometer Scale Error (ppm)



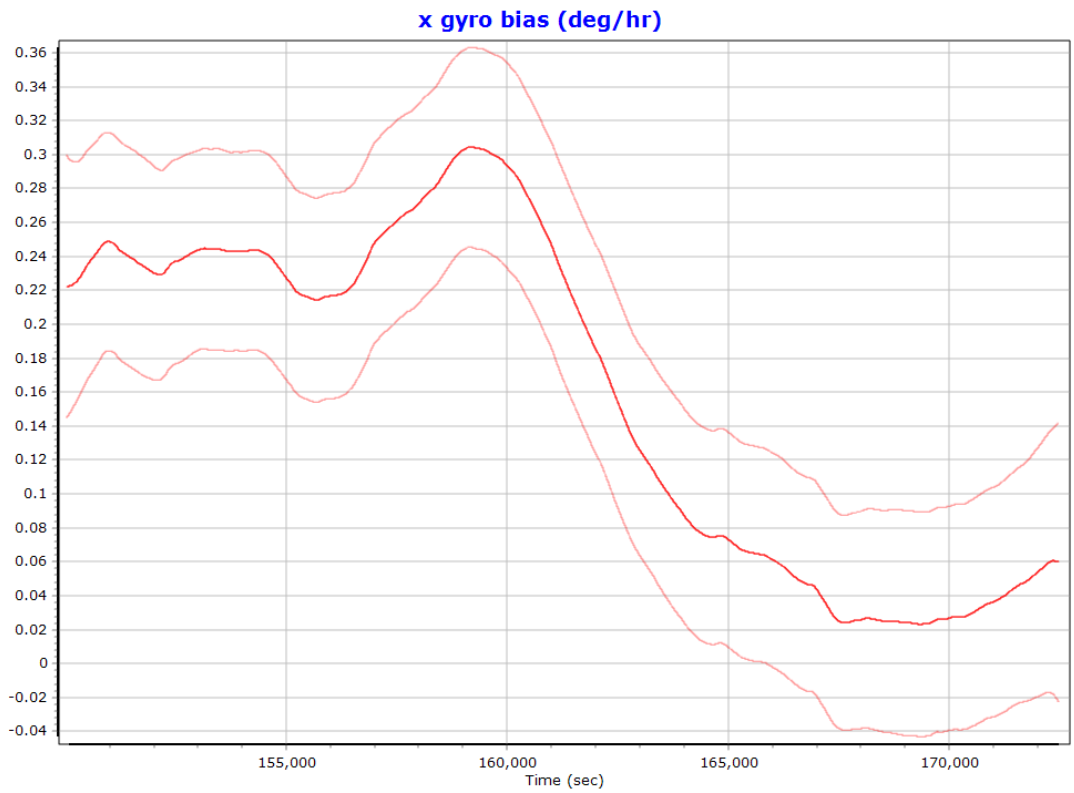
Z Accelerometer Scale Error (ppm)



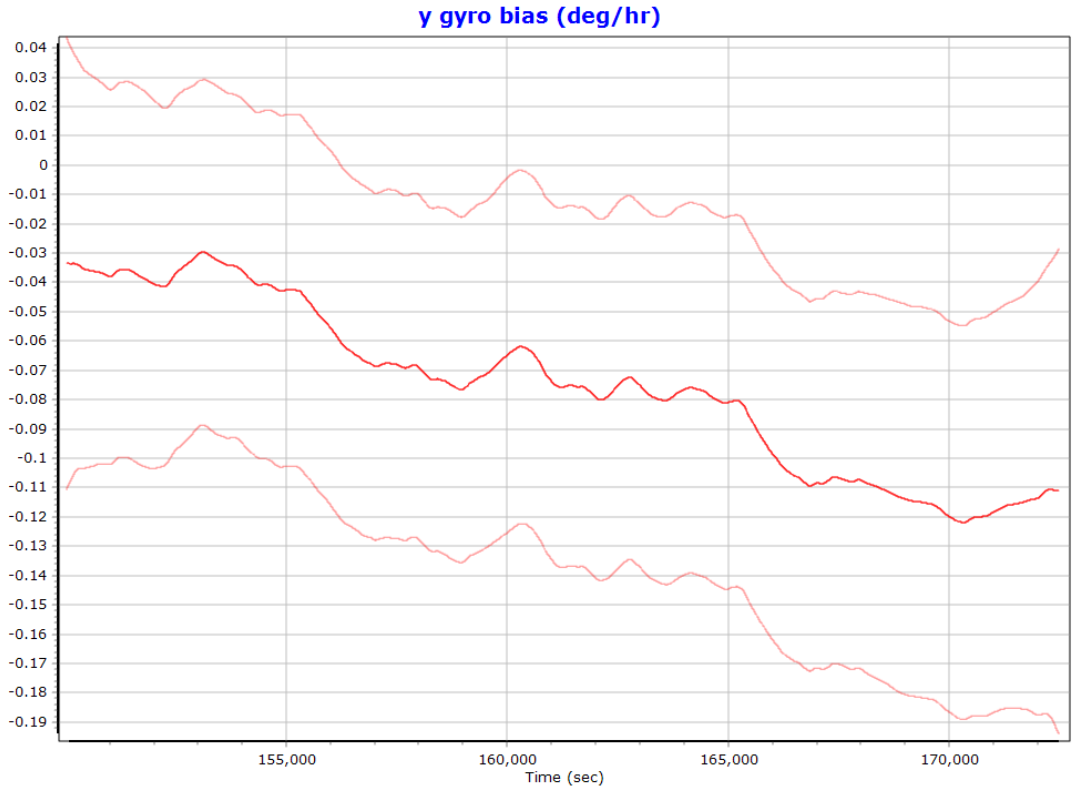
Gyro Bias (deg/h)



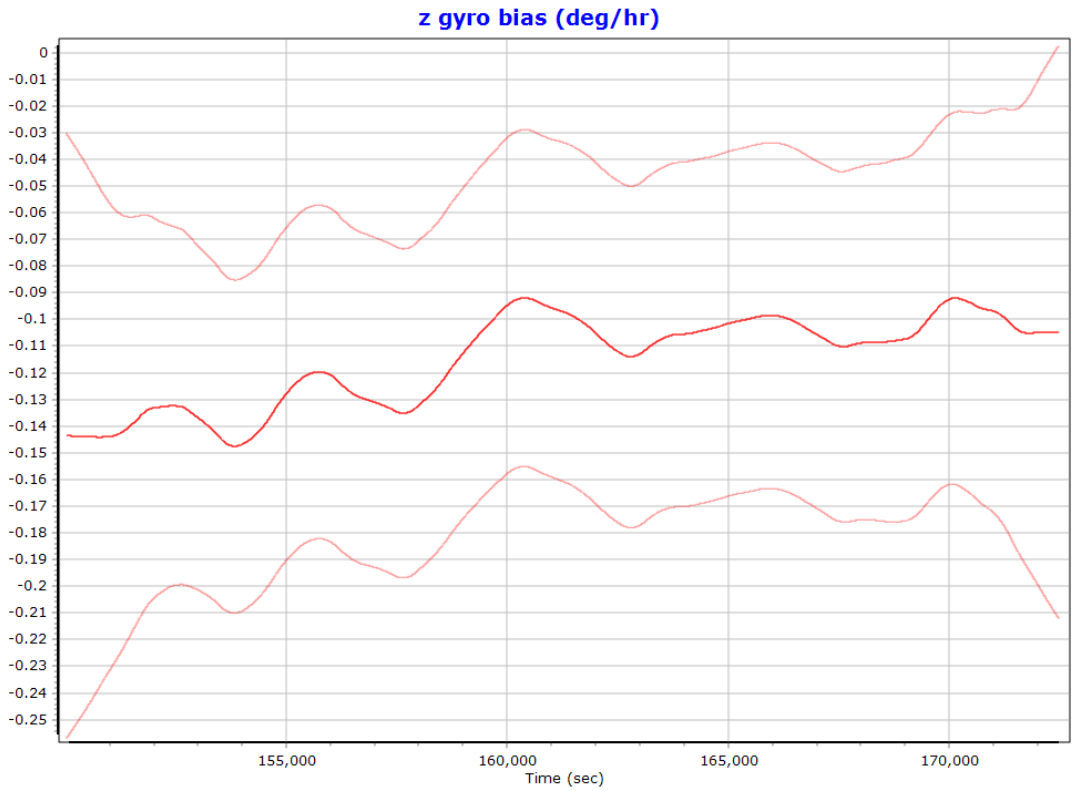
X Gyro Bias (deg/h)



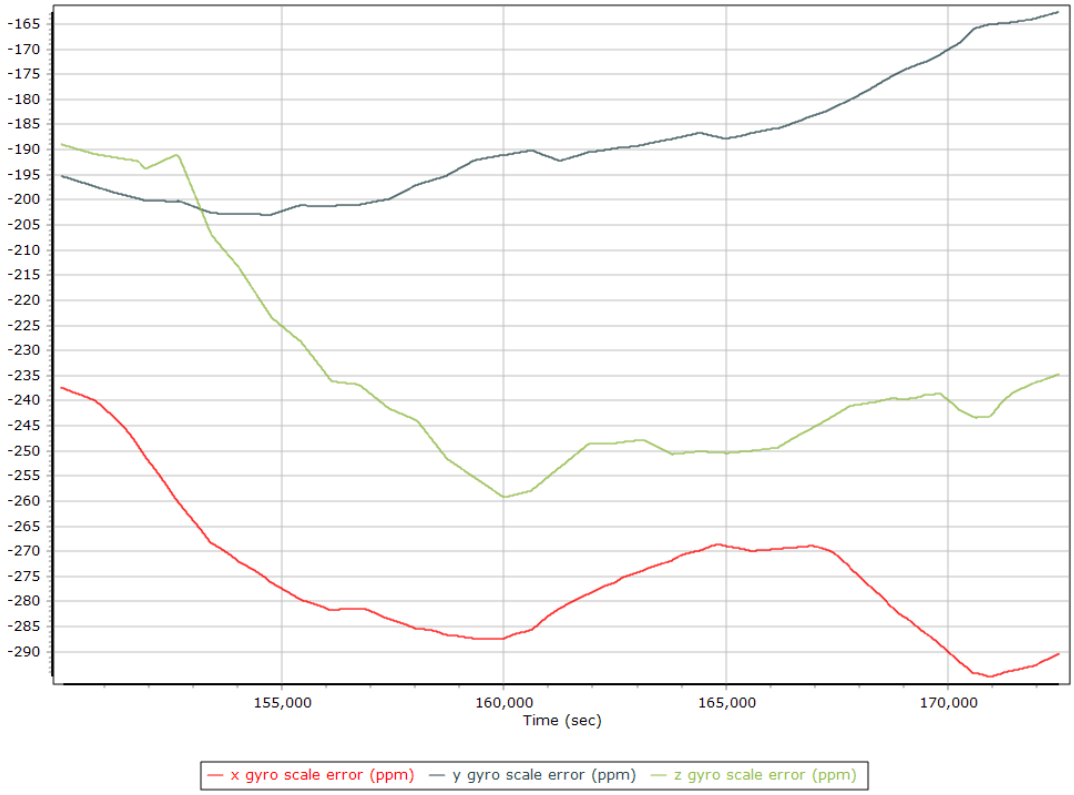
Y Gyro Bias (deg/h)



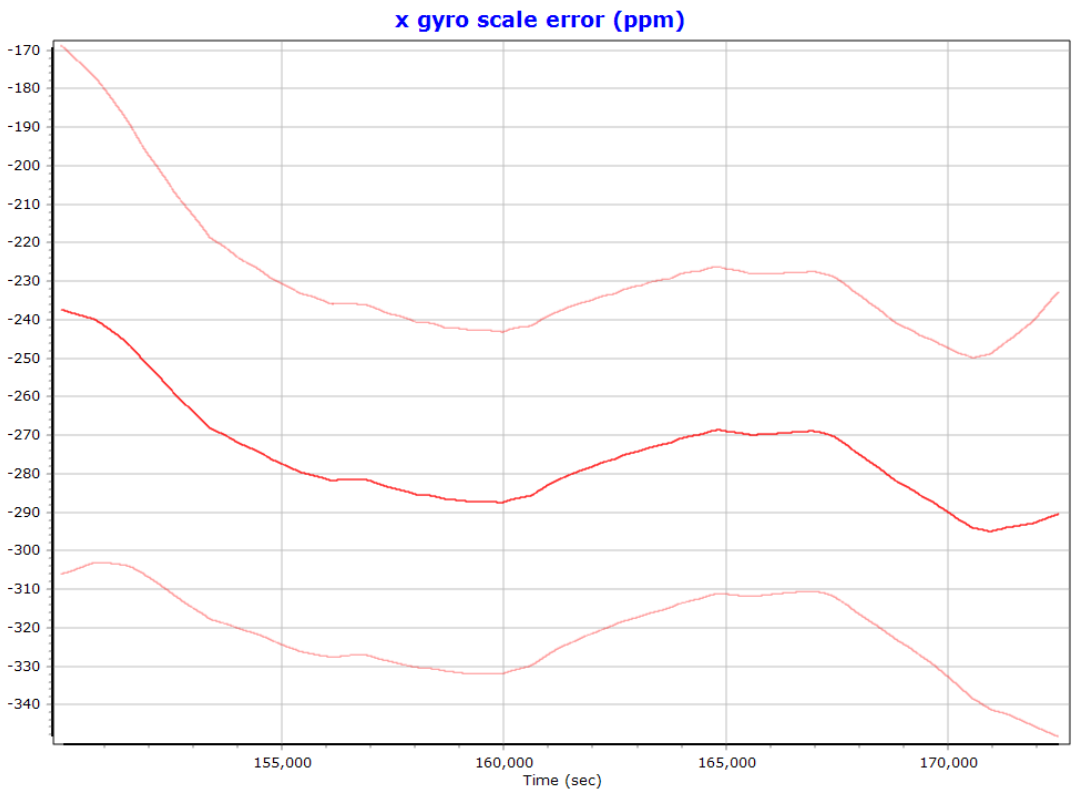
Z Gyro Bias (deg/h)



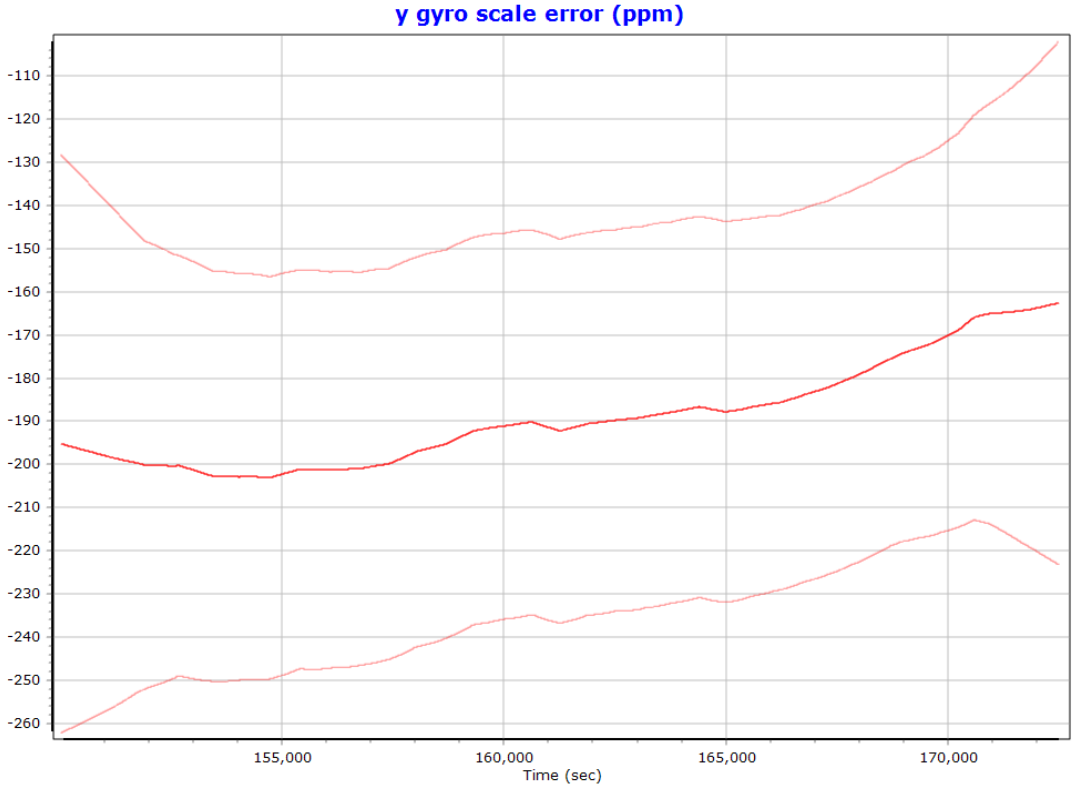
Gyro Scale Error (ppm)



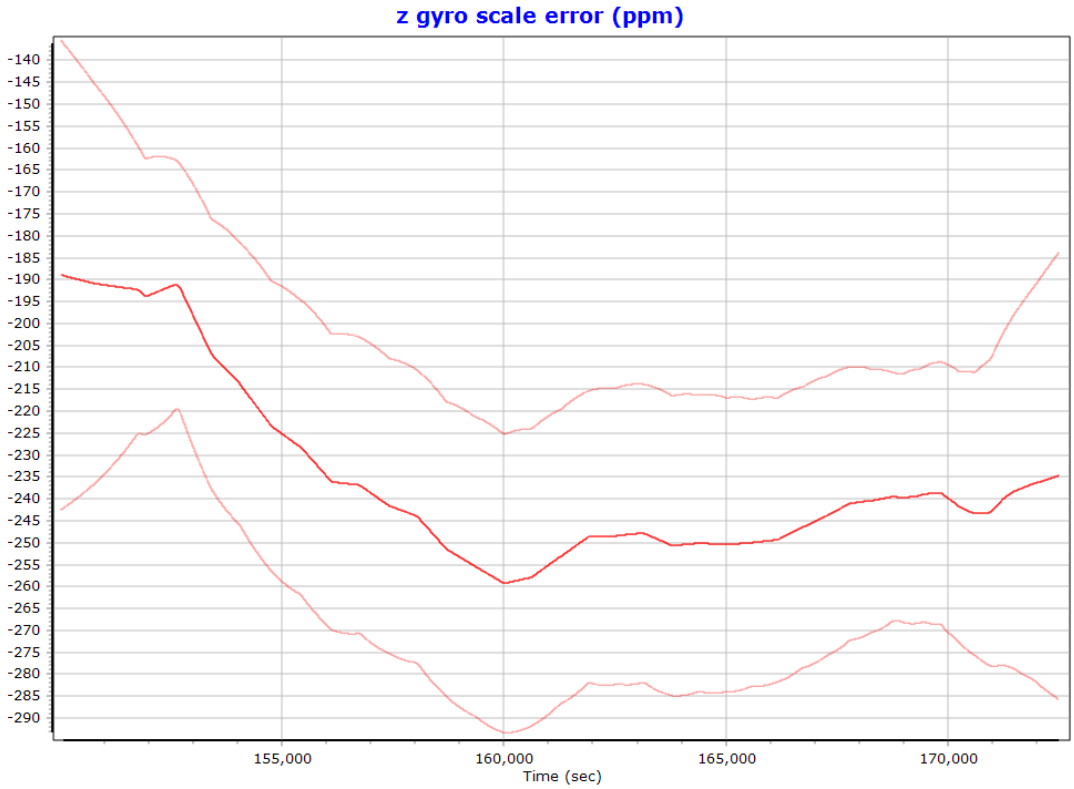
X Gyro Scale Error (ppm)



Y Gyro Scale Error (ppm)

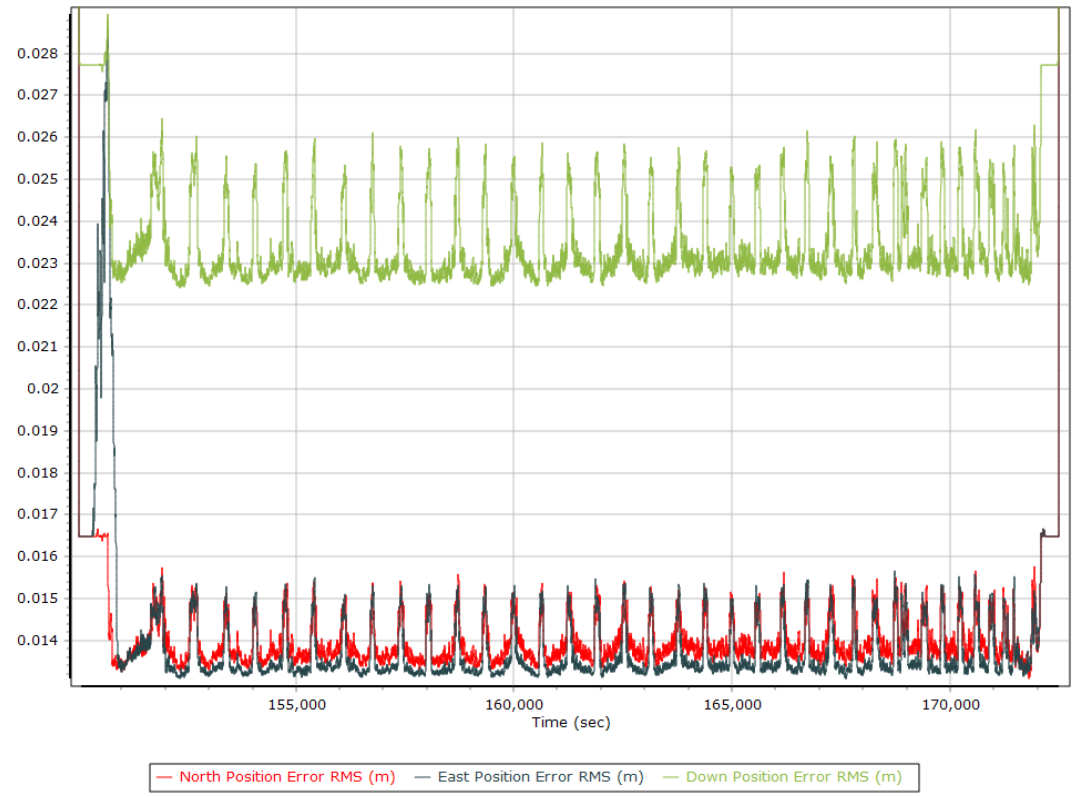


Z Gyro Scale Error (ppm)

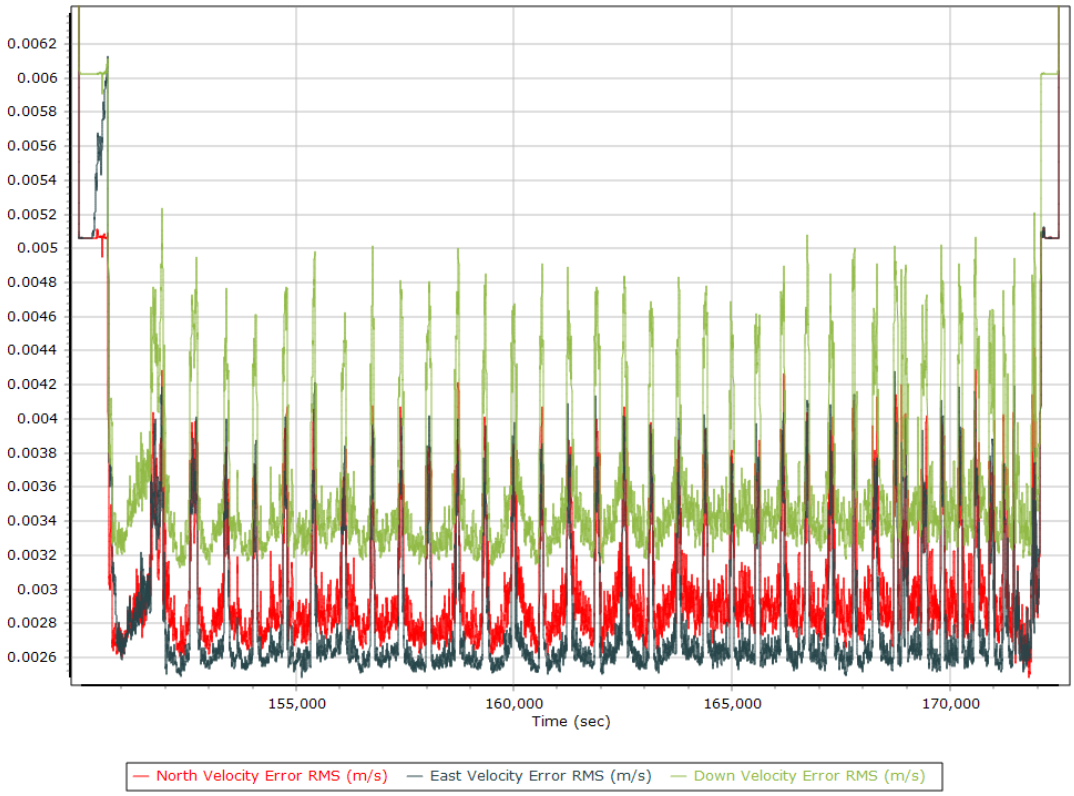


Smoothed Performance Metrics

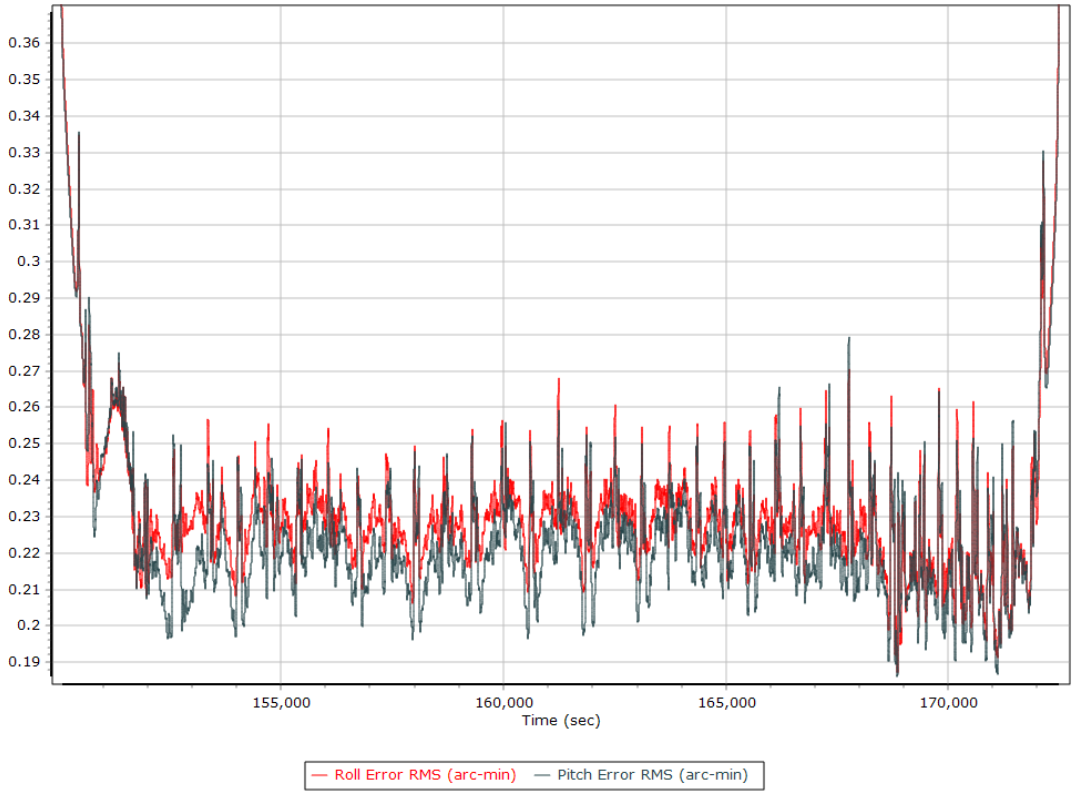
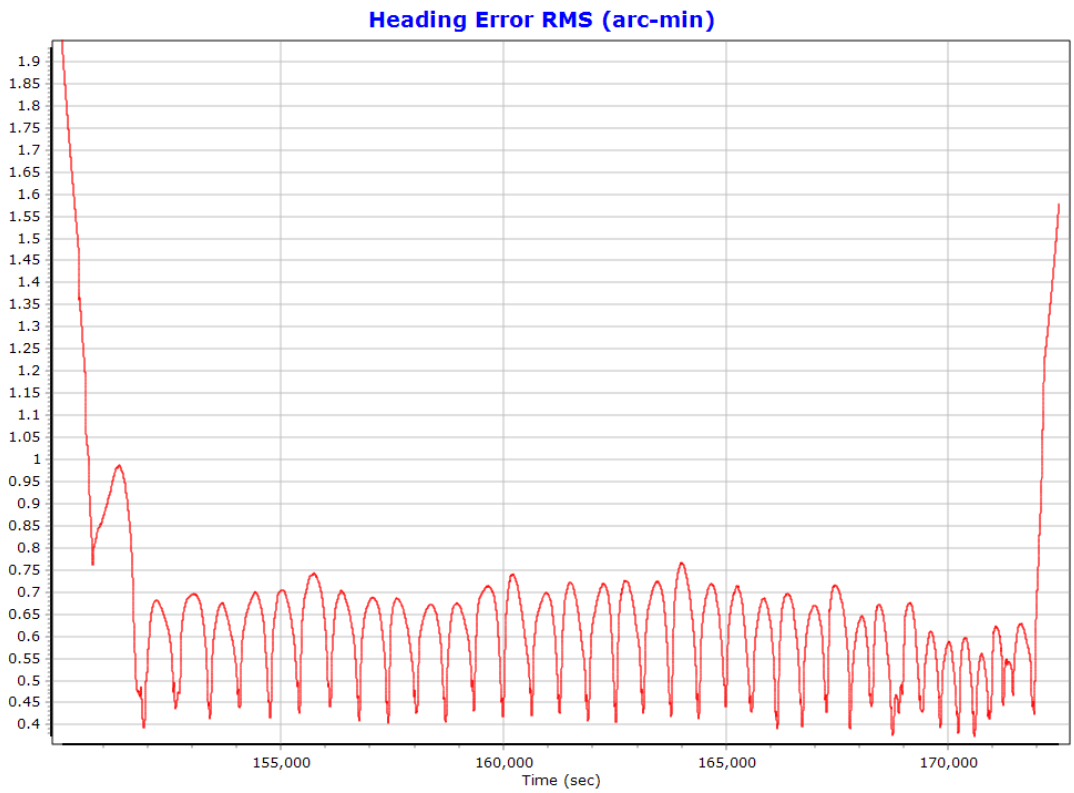
Position Error RMS (m)



Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)



Heading Error RMS (arc-min)