General Information

Mission Information

Project name	19118_DewberryID_1003
Processing date	2020-10-22 22:58:42
Mission date	2019-10-03 15:15:39
Mission duration	03:47:26.000
Processing mode	IN-Fusion PP-RTX

Rover Hardware Information

Product	POS AV 610 VER6 HW2.5-12
Serial number	S/N10659
IMU type	57
Receiver type	BD982
Antenna type	Unknown External

Project File List

Rover Data Files

File name	File type
20191003b.150	POS Data
20191003b.151	POS Data
20191003b.152	POS Data
20191003b.153	POS Data
20191003b.154	POS Data
20191003b.155	POS Data
20191003b.156	POS Data
20191003b.157	POS Data
20191003b.158	POS Data
20191003b.159	POS Data
20191003b.160	POS Data
20191003b.161	POS Data
20191003b.162	POS Data
20191003b.163	POS Data
20191003b.164	POS Data
20191003b.165	POS Data
20191003b.166	POS Data
20191003b.167	POS Data
20191003b.168	POS Data
20191003b.169	POS Data
20191003b.170	POS Data
20191003b.171	POS Data
20191003b.172	POS Data
20191003b.173	POS Data
20191003b.174	POS Data
20191003b.175	POS Data
20191003b.176	POS Data
20191003b.177	POS Data
20191003b.178	POS Data
20191003b.179	POS Data

Input Files

File Name	File Type
Ephm2760.19g	GLONASS Broadcast Ephemeris
Ephm2760.19n	GPS Broadcast Ephemeris

Output Files

Filename	File type
sbet_Mission 1.out	SBET Trajectory File

Rover Data Summary

First raw data file	20191003b.150		
Last raw data file	20191003b.179		
Start GPS week	2073		
Start time	400538.728 (10/3/2019 3:15:38 PM)		
End time	414185.970 (10/3/2019 7:03:05 PM)		
Start of fine alignment	400786.341 (10/3/2019 3:19:46 PM)		
Available subsystems	Primary GNSS, IMU		
POS Event Input	None		
Correction data	None		
IMU Installation Lever Arms & Mounting Angles			
Reference to IMU lever arm (m)	0.000	0.000	0.000
Reference to IMU mounting angles (deg)	0.000	0.000	180.000
Reference to Primary GNSS lever arm (m)	0.326	-0.406	-1.087
Reference to Primary GNSS lever arm std dev (m)	-1.000		
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

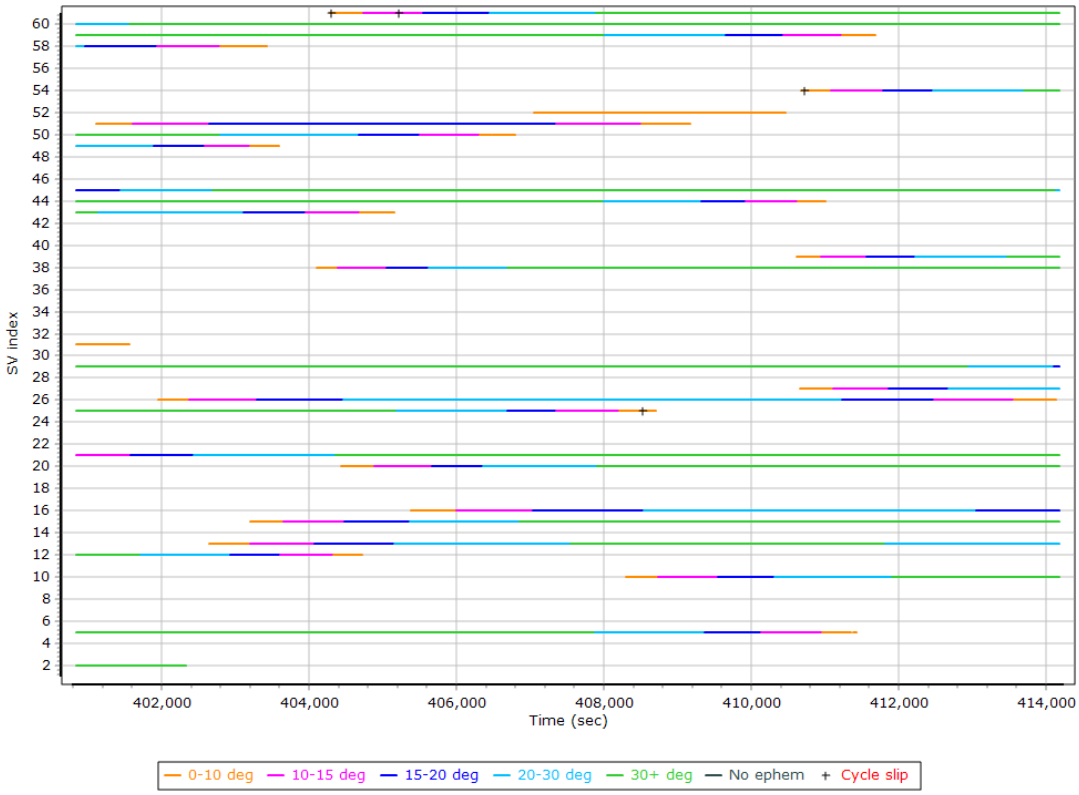
Rover Data QC

Raw IMU Import QC Summary

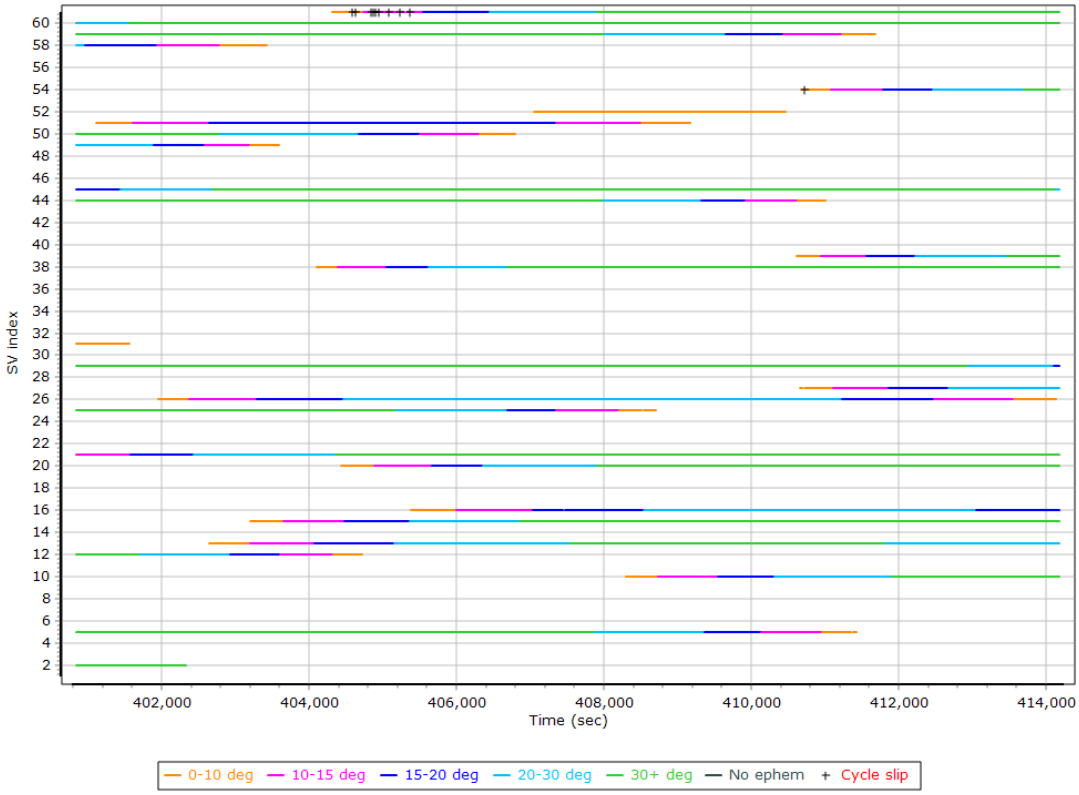
IMU data input file	imu_Mission 1.dat
IMU data check log file	imudt_Mission 1.log
IMU Records Processed	2728885
Termination Status	Normal
IMU Anomalies	0

Primary Observables & Satellite Data

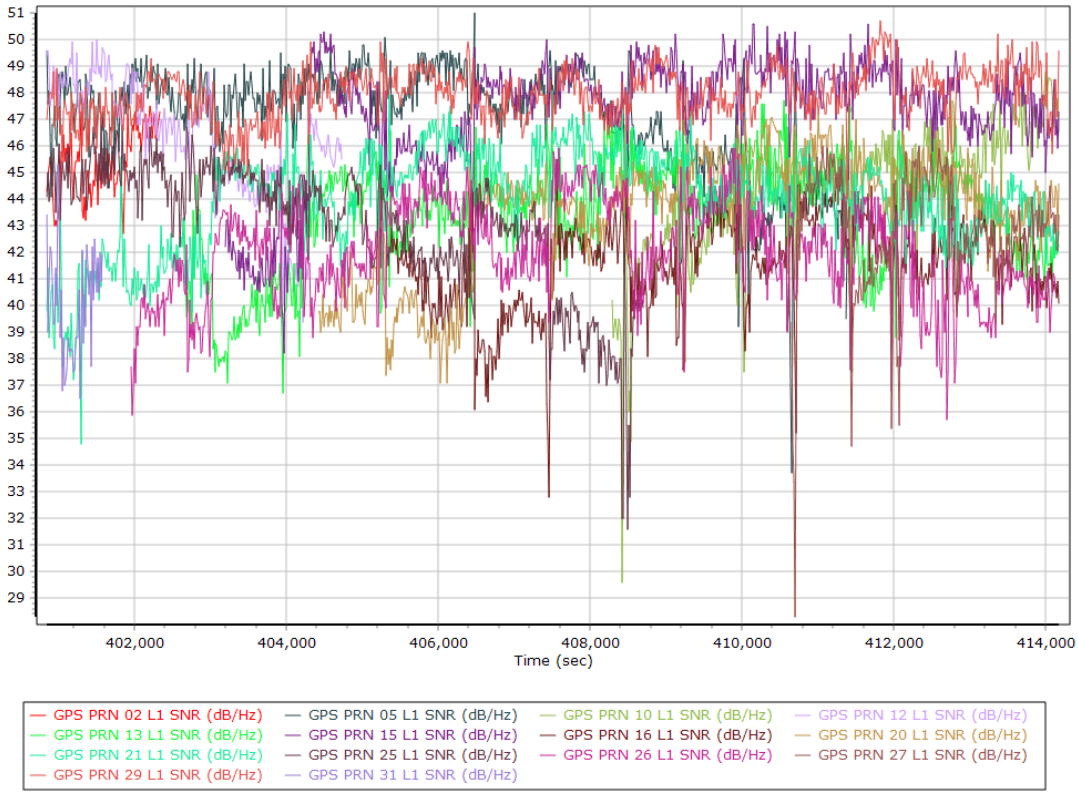
L1 Satellite Lock/Elevation



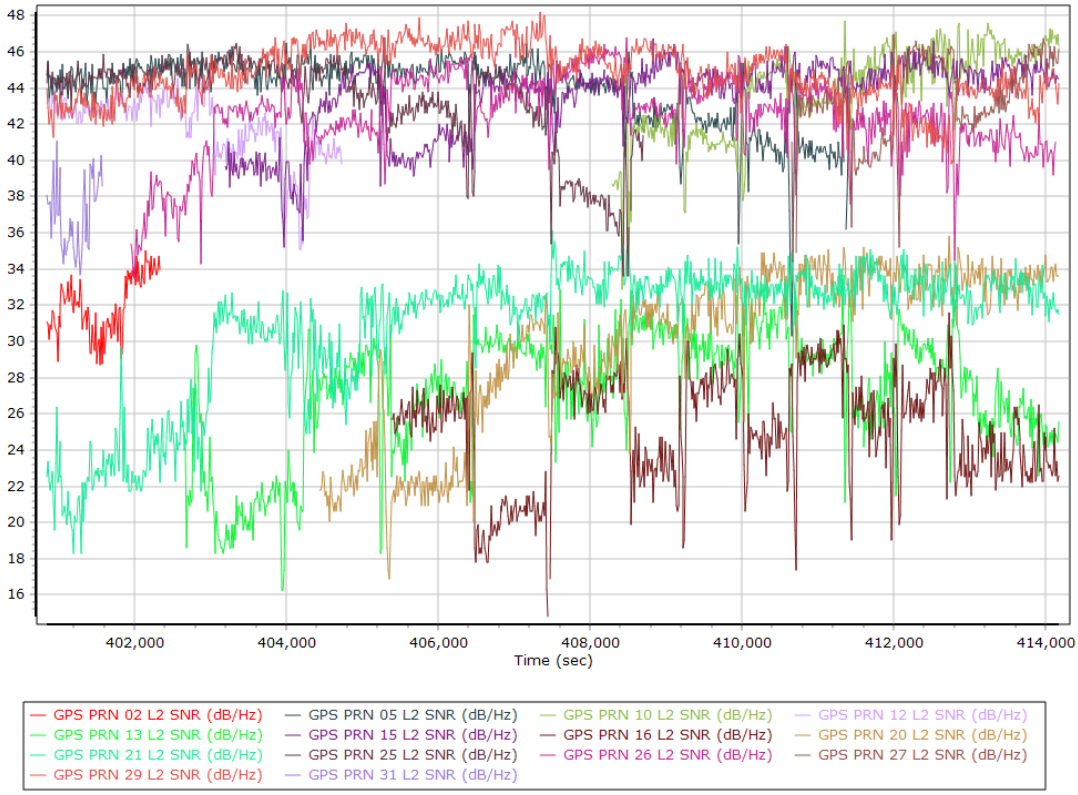
L2 Satellite Lock/Elevation



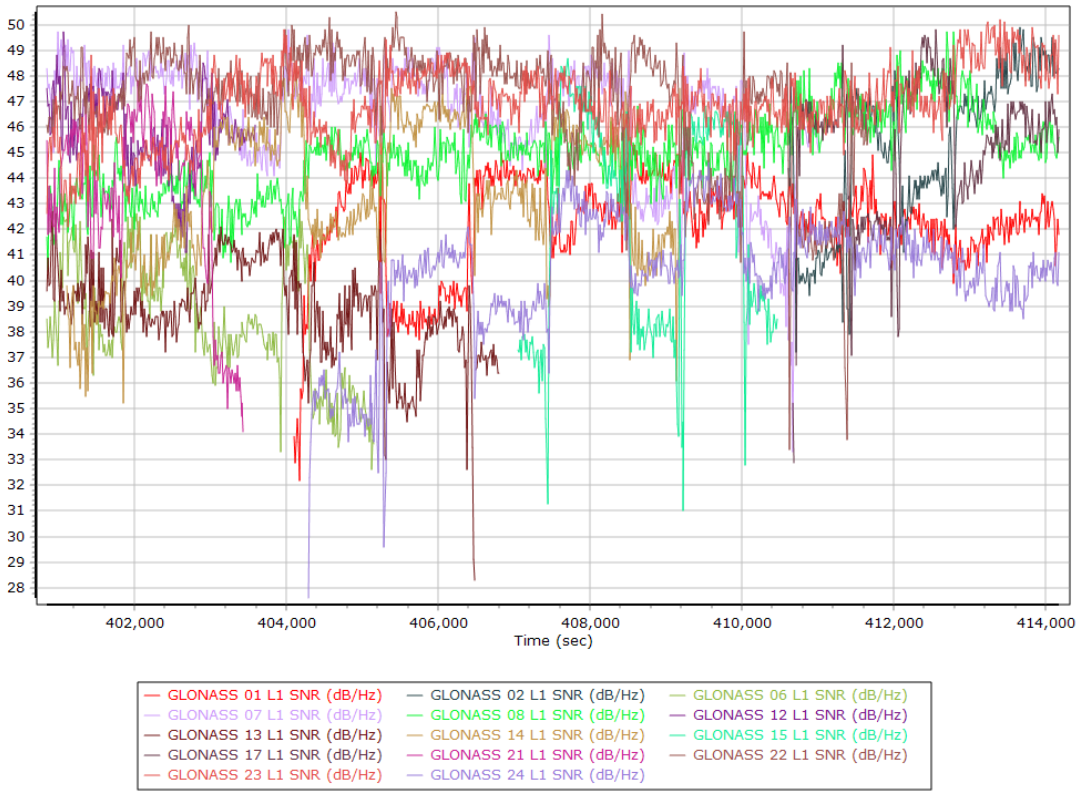
GPS L1 SNR



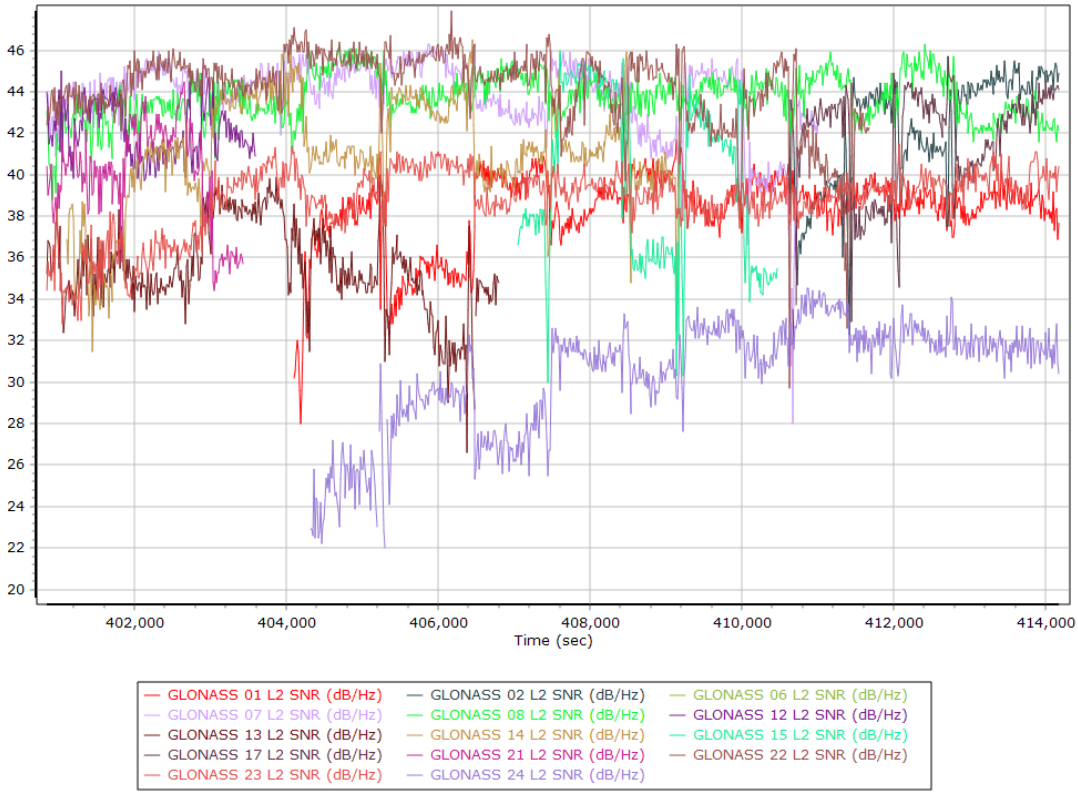
GPS L2 SNR



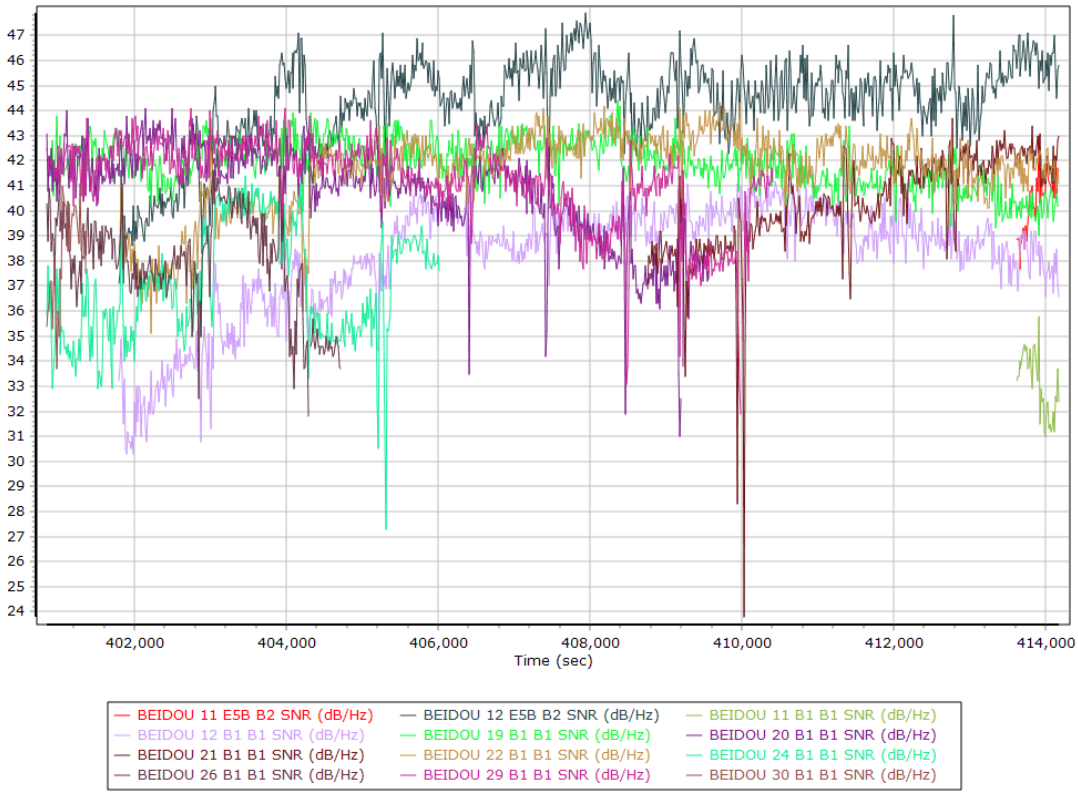
GLONASS L1 SNR



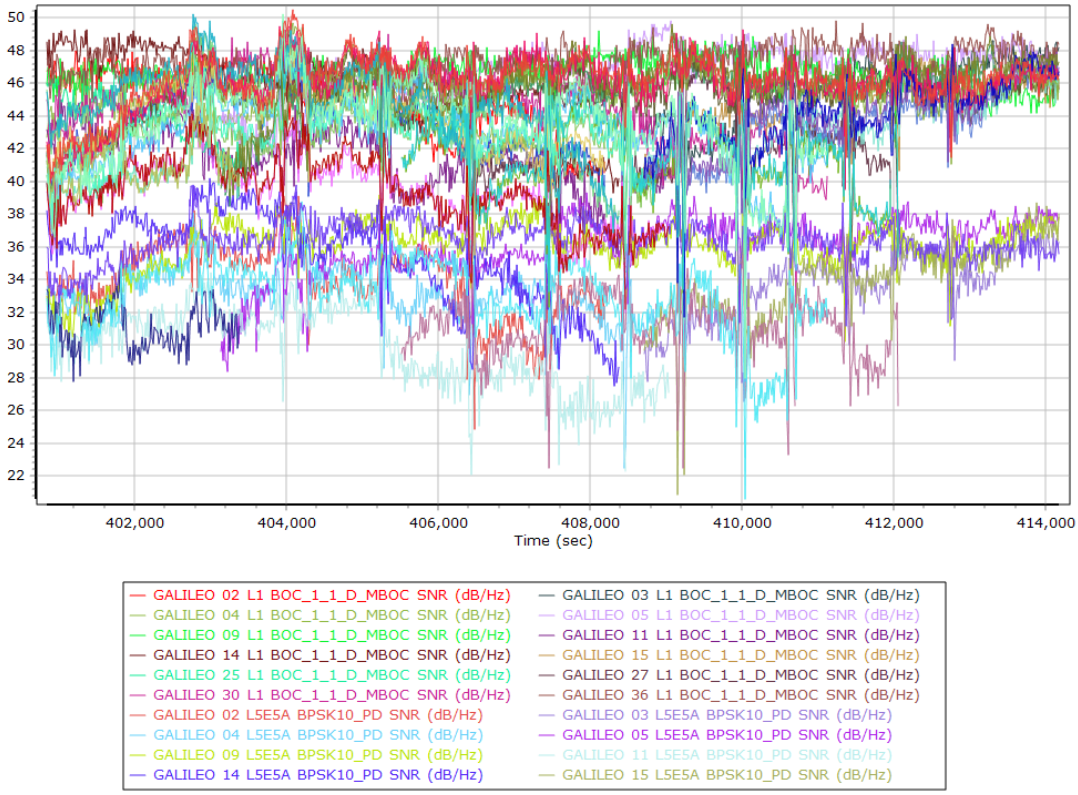
GLONASS L2 SNR



BEIDOU SNR

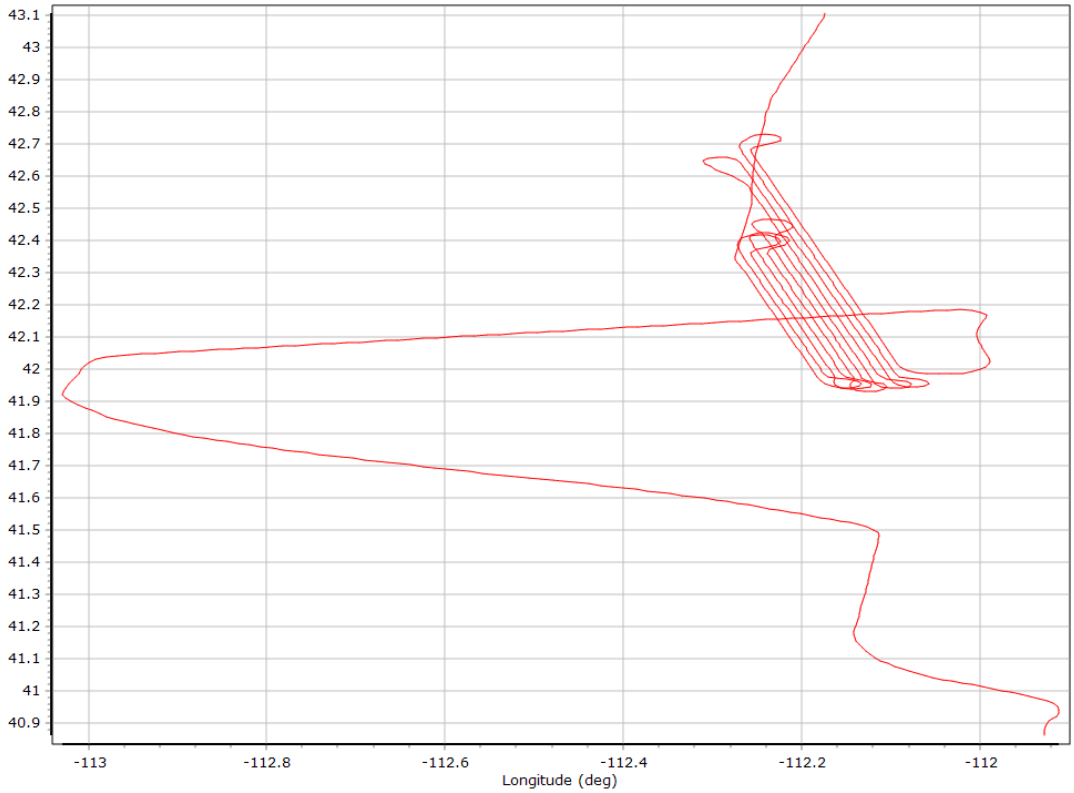


GALILEO SNR

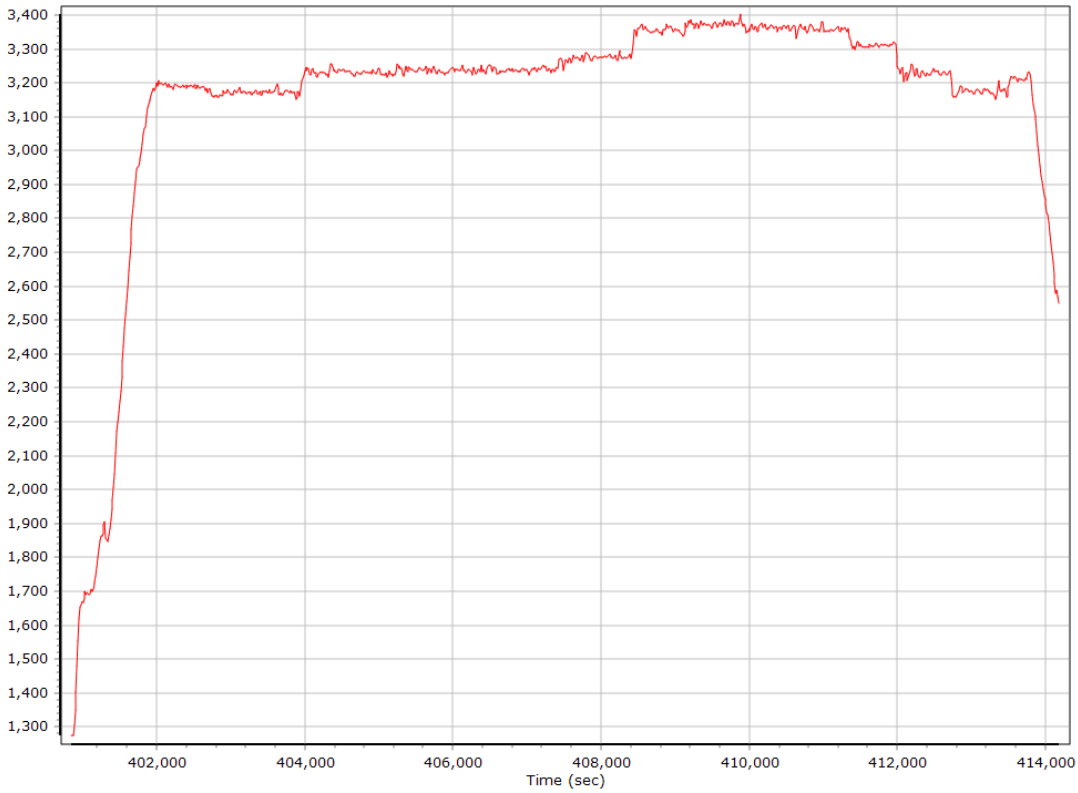

50
48
46
44
42
40
38
36
34
32
30
28
26
24
22
402,000
404,000
406,000
408,000
410,000
412,000
414,000
Time (sec)
GALILEO 02 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 03 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 04 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 05 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 09 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 11 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 14 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 15 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 25 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 27 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 30 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 36 L1 BOC_1_1_D_MBOC SNR (dB/Hz)
GALILEO 02 L5E5A BPSK10_PD SNR (dB/Hz)
GALILEO 03 L5E5A BPSK10_PD SNR (dB/Hz)
GALILEO 04 L5E5A BPSK10_PD SNR (dB/Hz)
GALILEO 05 L5E5A BPSK10_PD SNR (dB/Hz)
GALILEO 09 L5E5A BPSK10_PD SNR (dB/Hz)
GALILEO 11 L5E5A BPSK10_PD SNR (dB/Hz)
GALILEO 14 L5E5A BPSK10_PD SNR (dB/Hz)
GALILEO 15 L5E5A BPSK10_PD SNR (dB/Hz)

Smoothed Trajectory Information

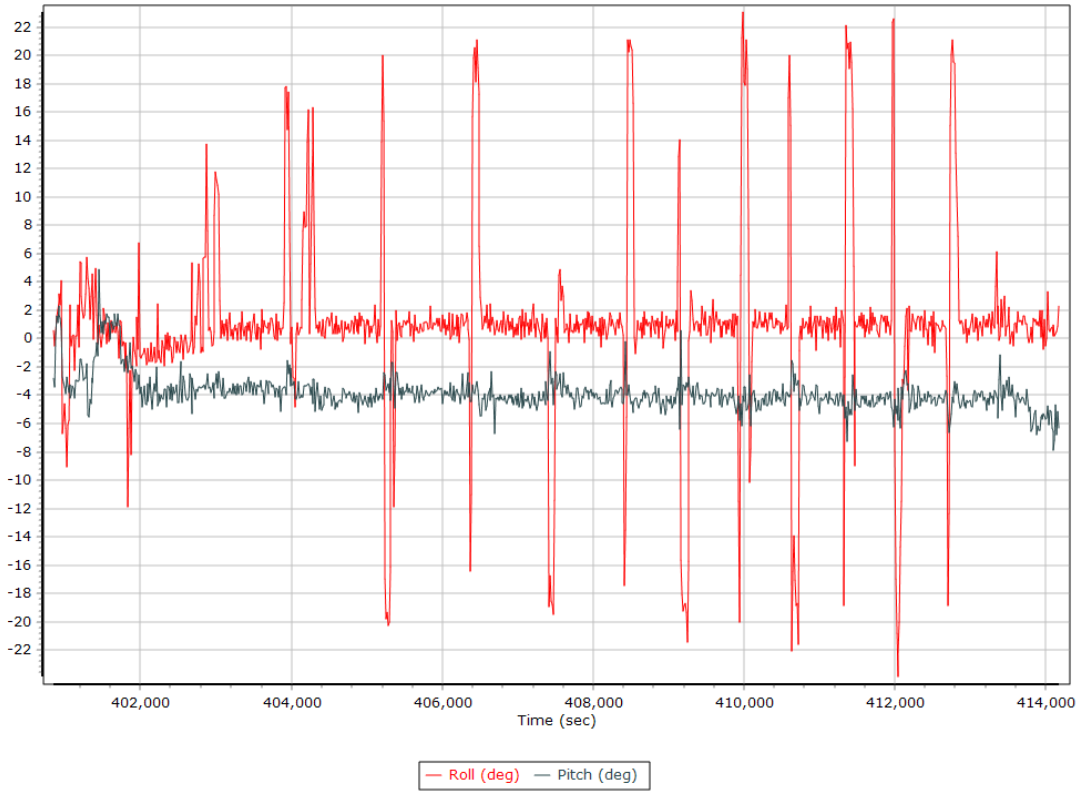
Top View



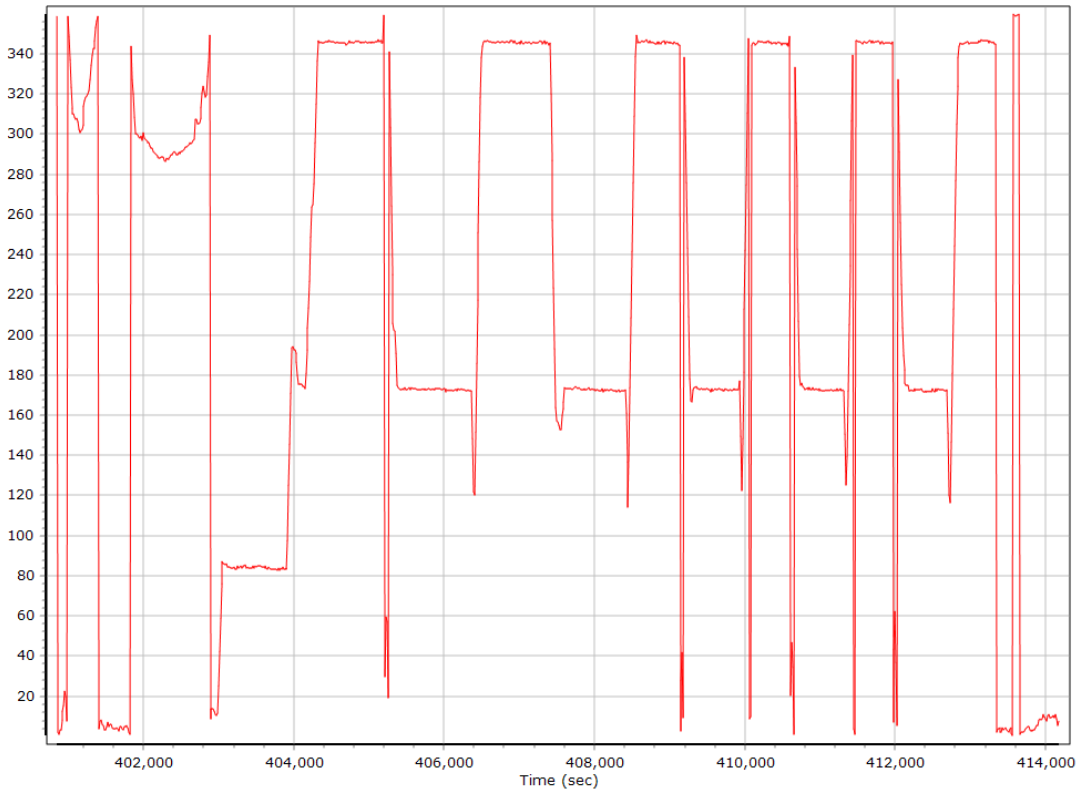
Altitude



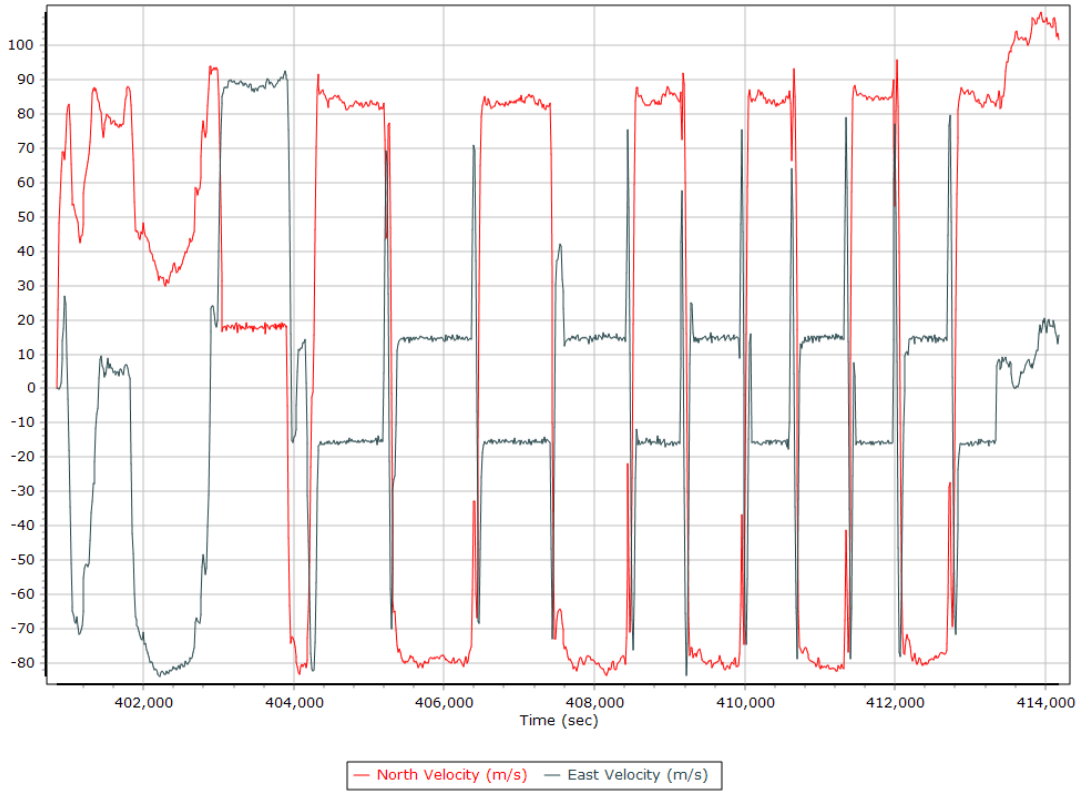
Roll/Pitch



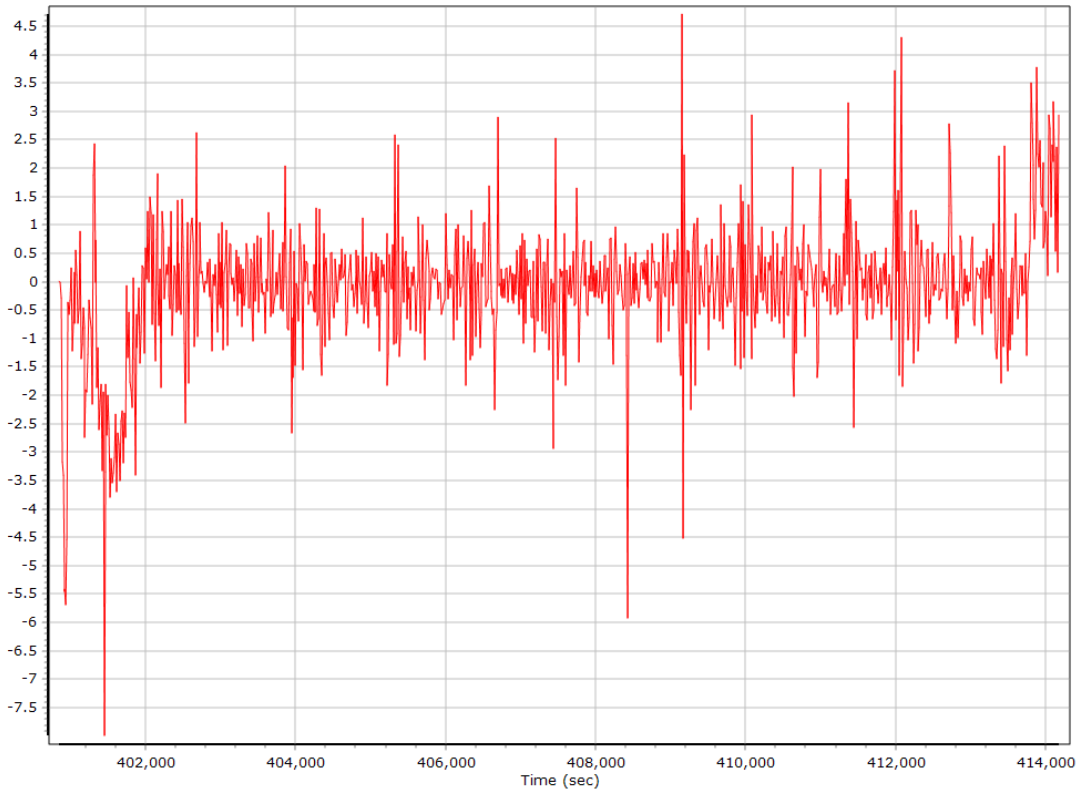
Heading



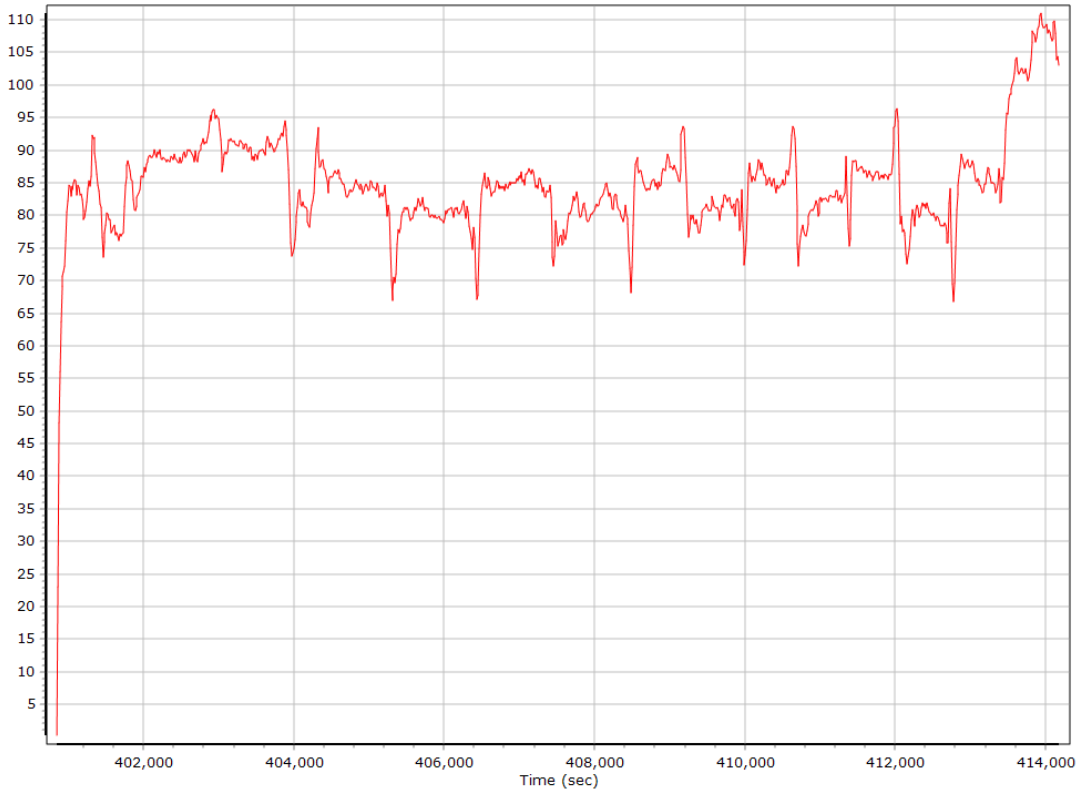
North/East Velocity



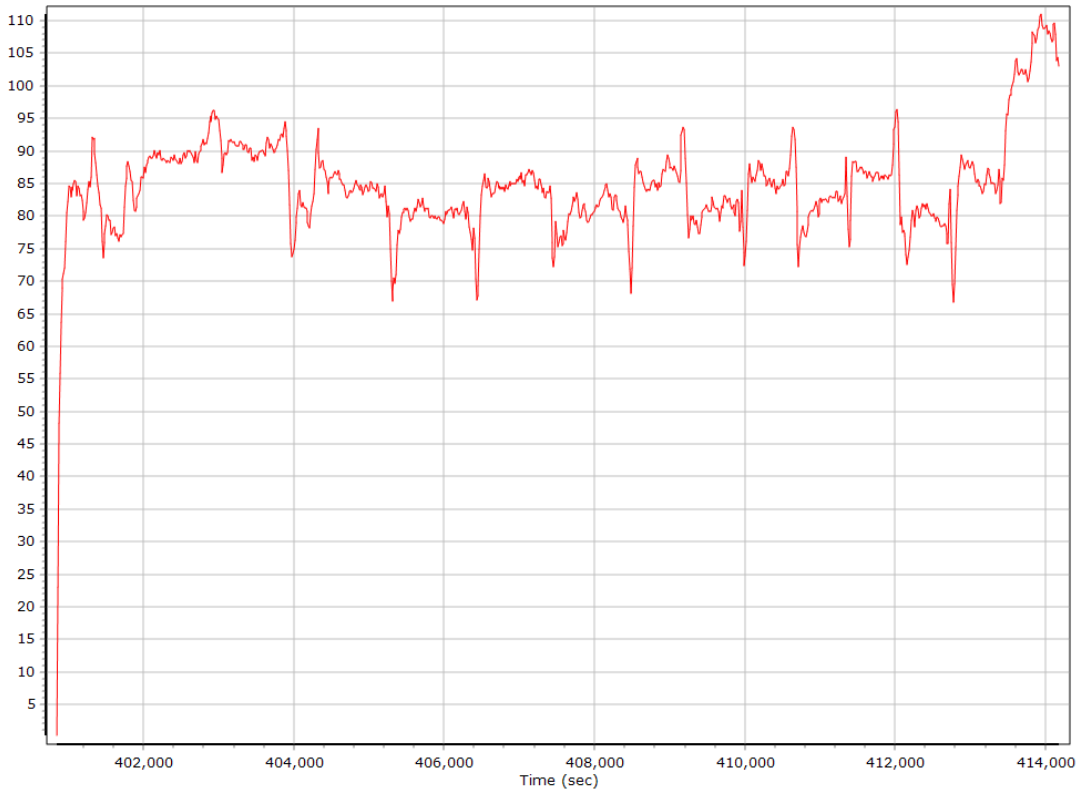
Down Velocity



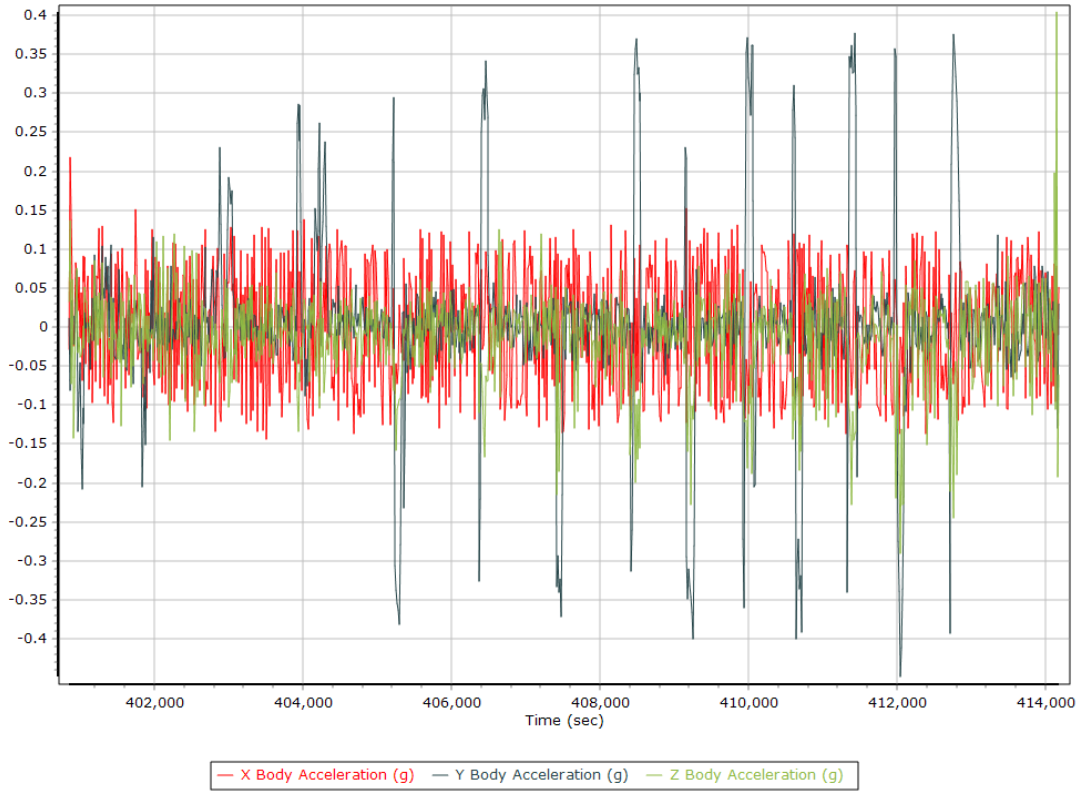
Total Speed



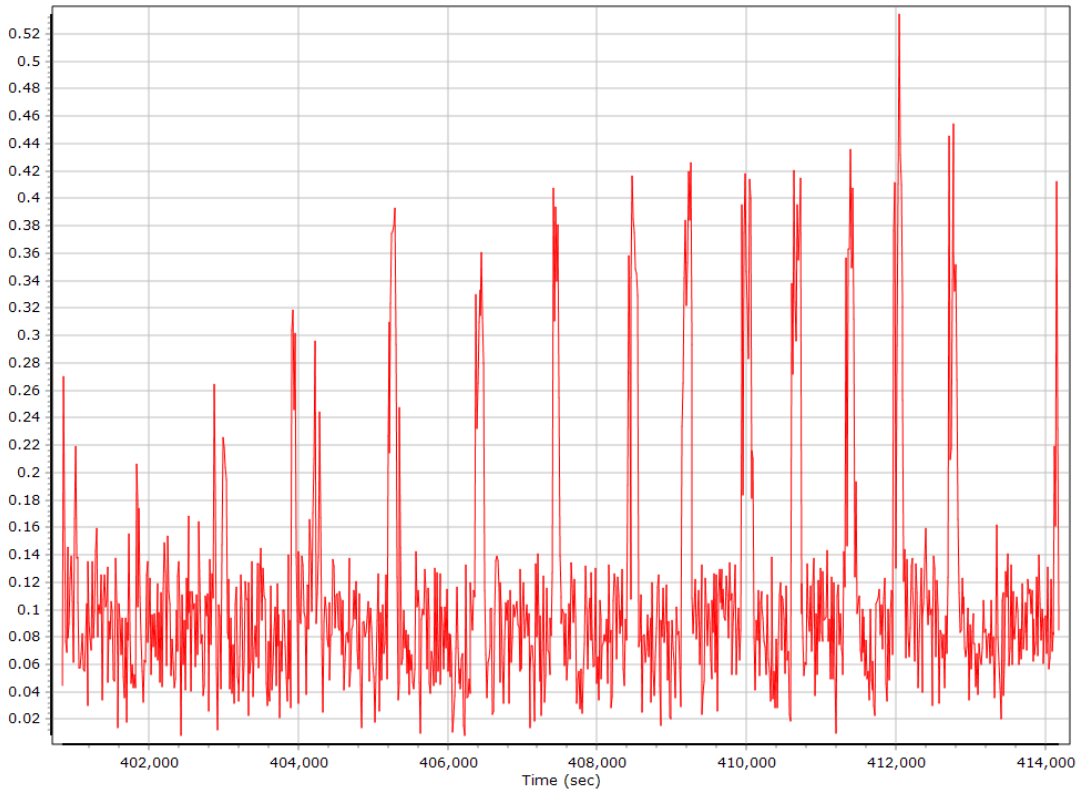
Ground Speed



Body Acceleration



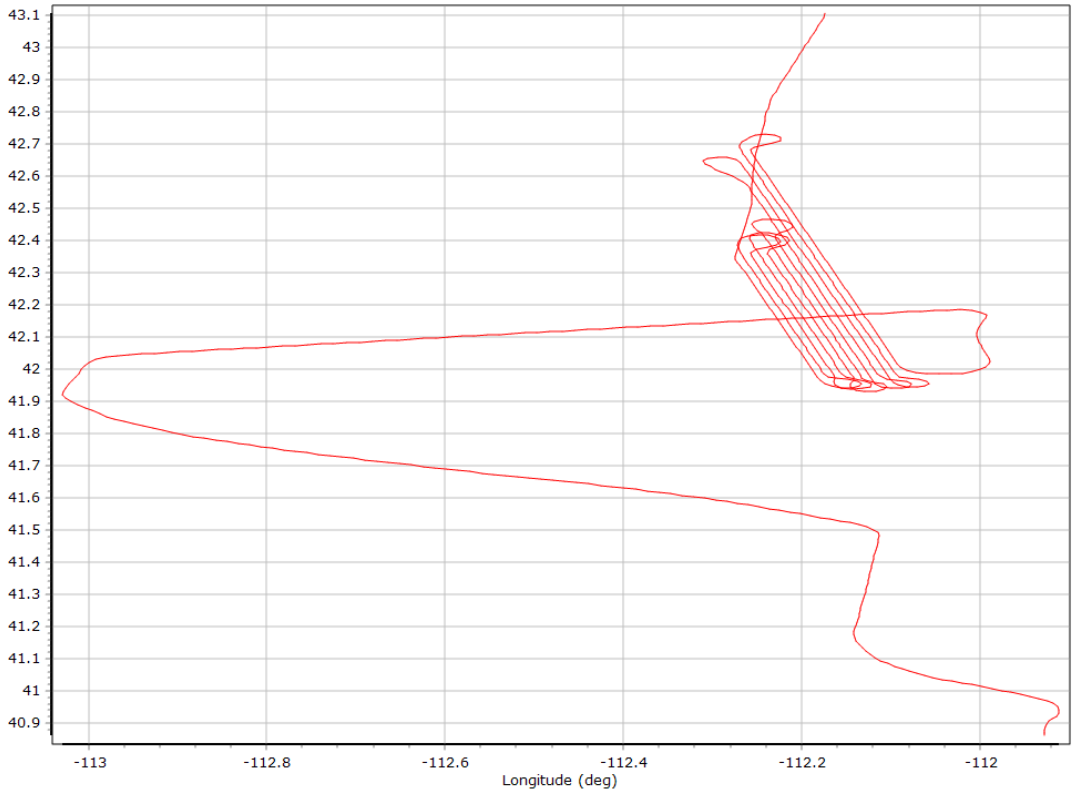
Total Body Acceleration



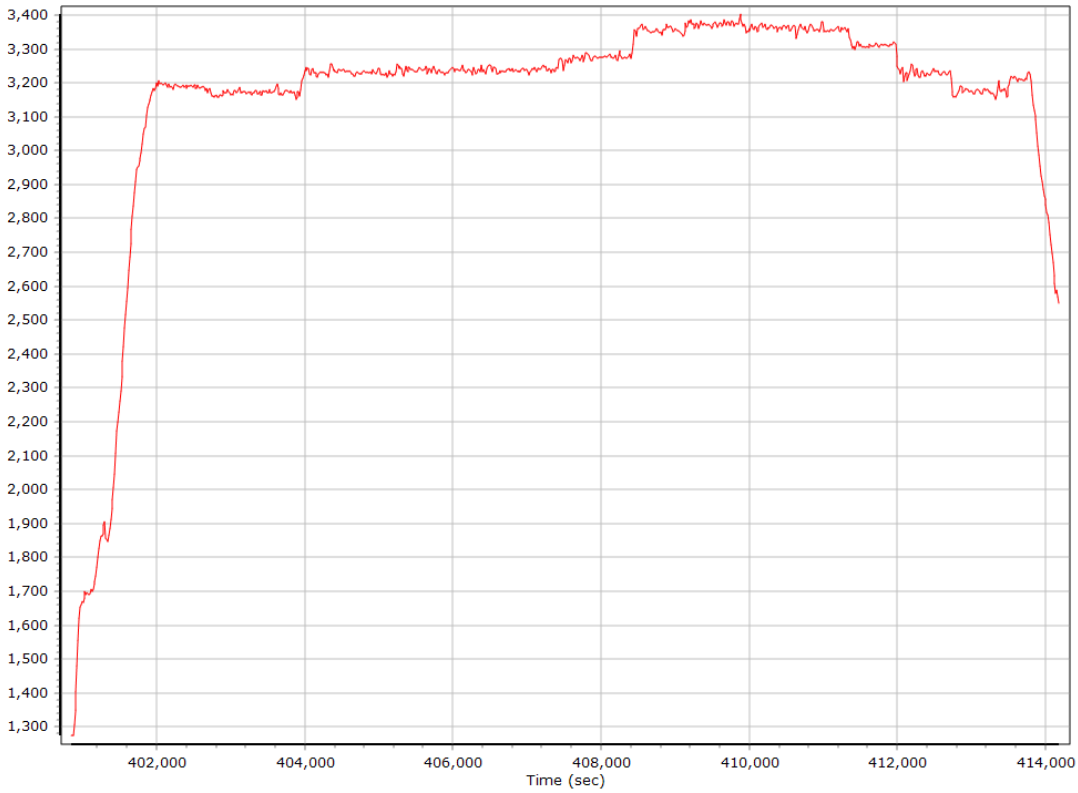
Body Angular Rate

Forward Processed Trajectory Information

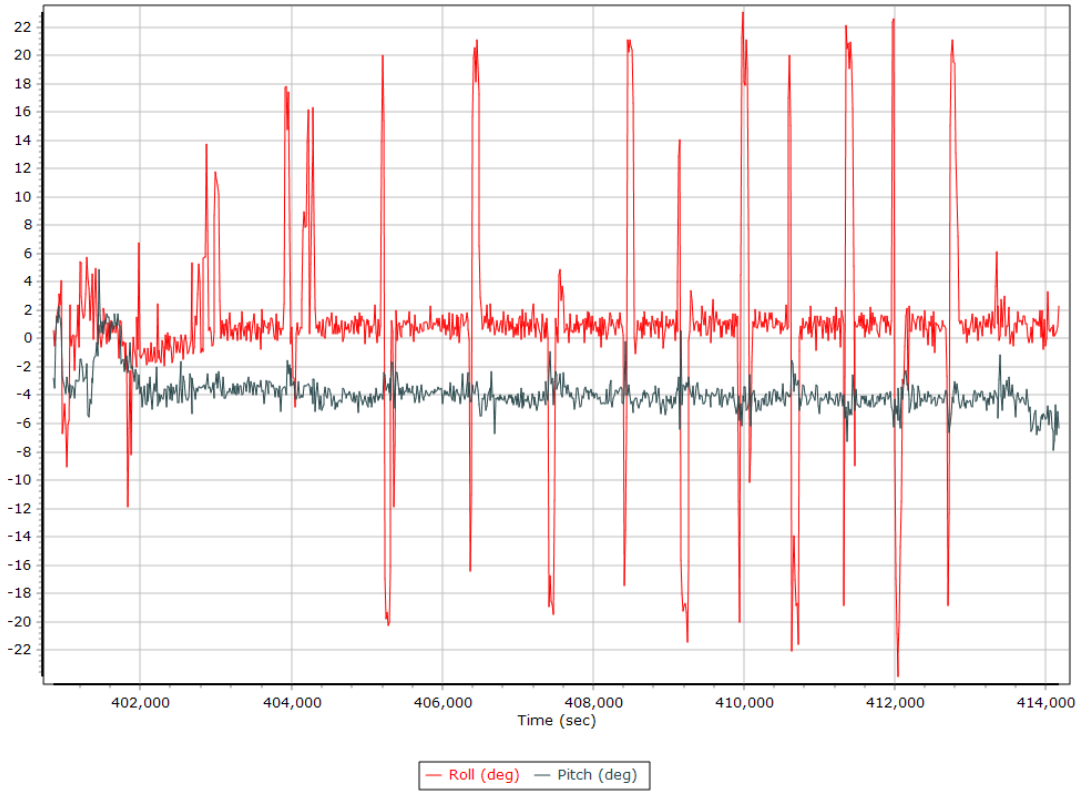
Top View



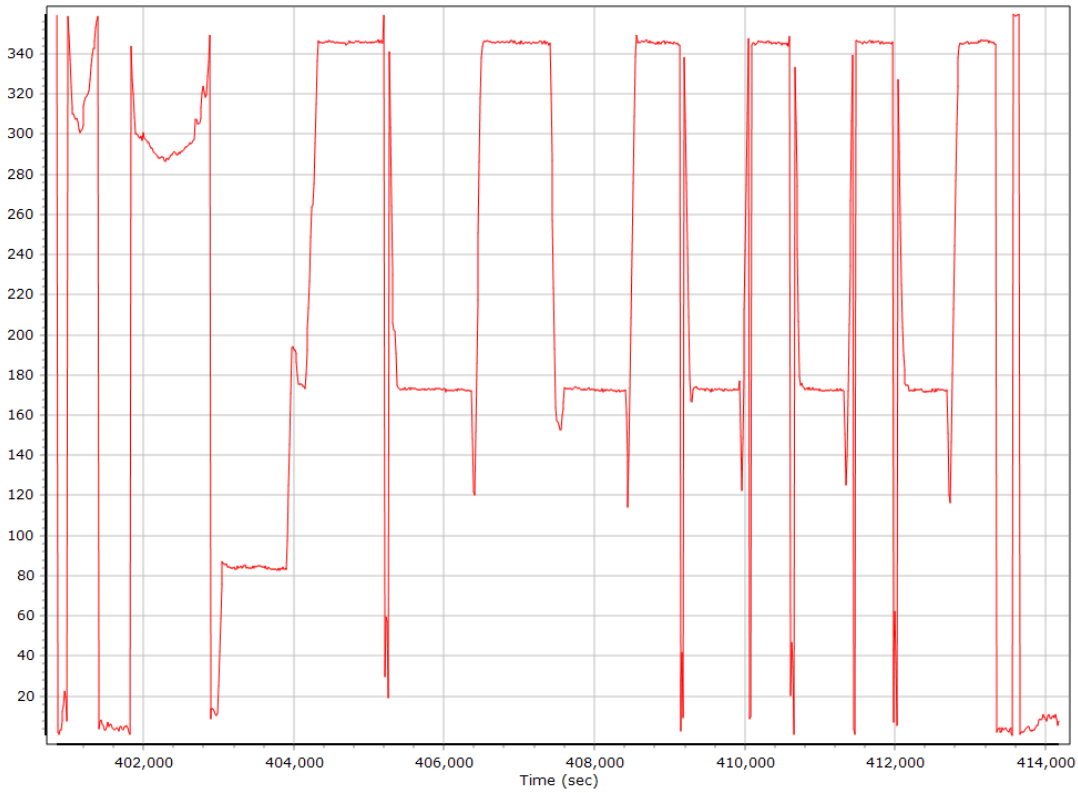
Altitude



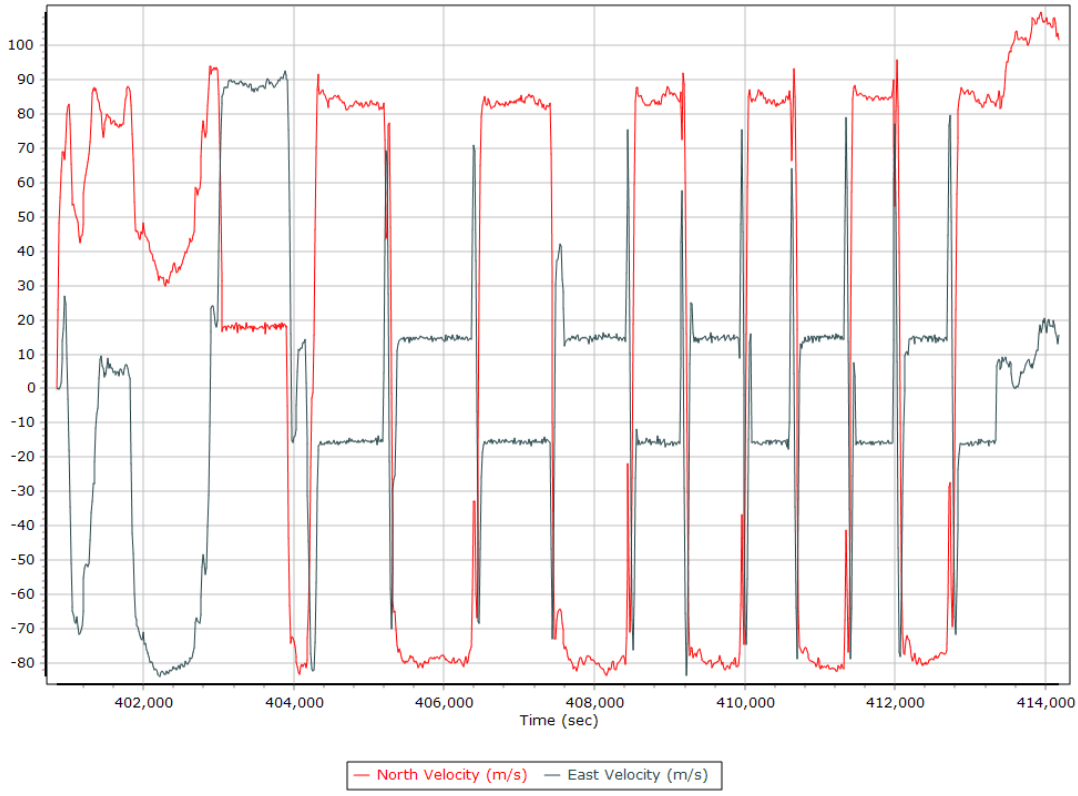
Roll/Pitch



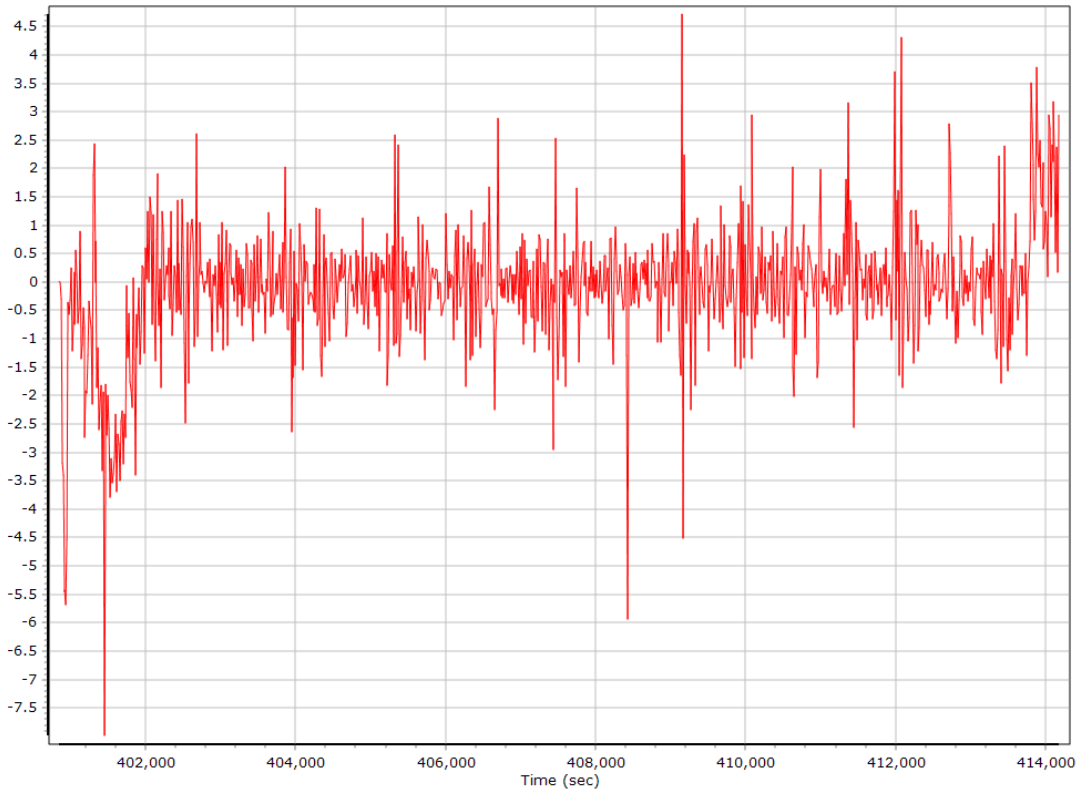
Heading



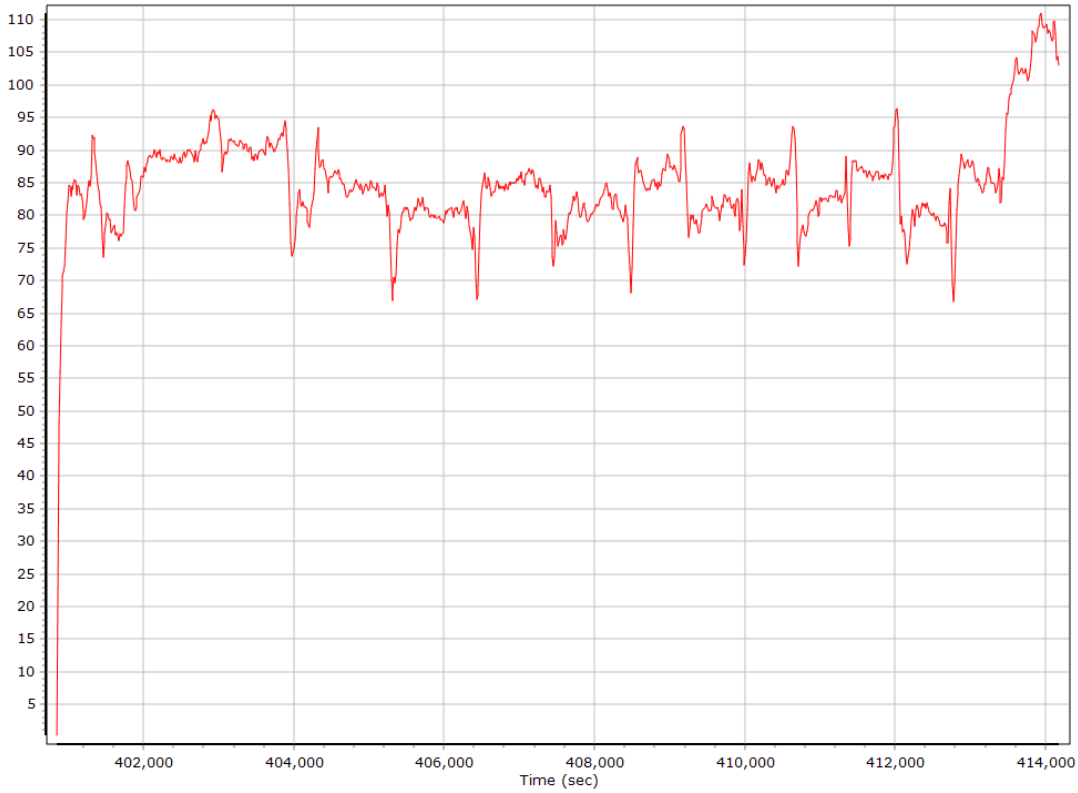
North/East Velocity



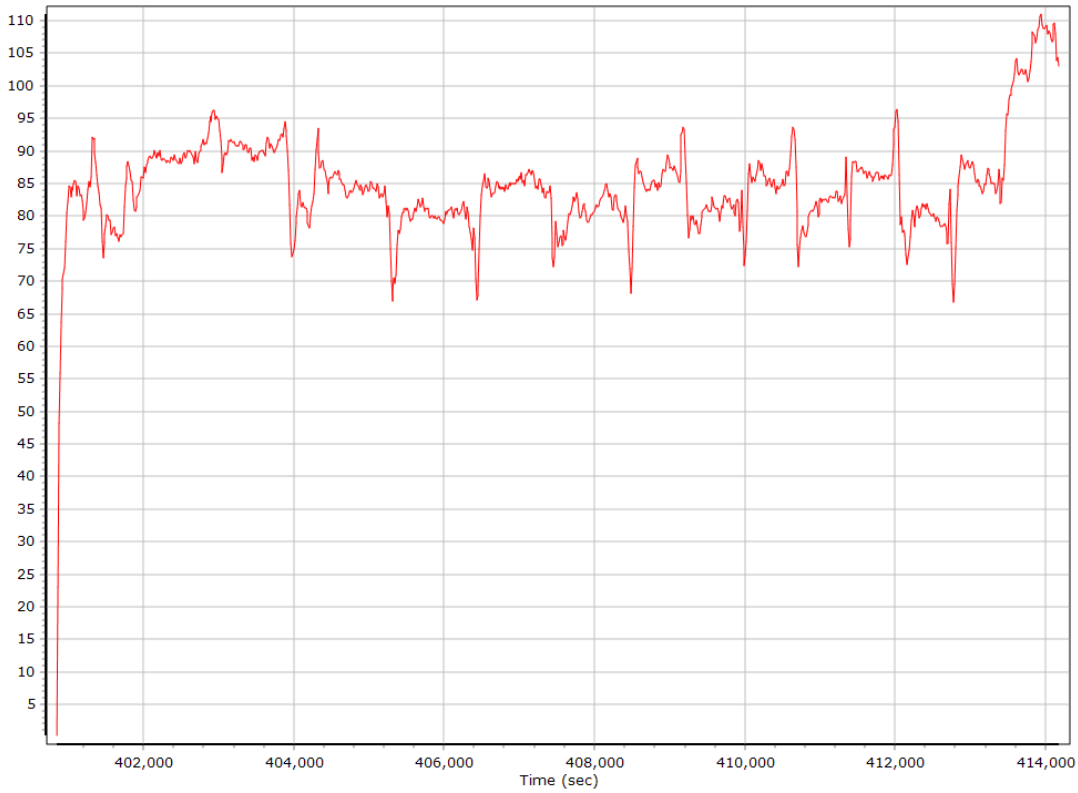
Down Velocity



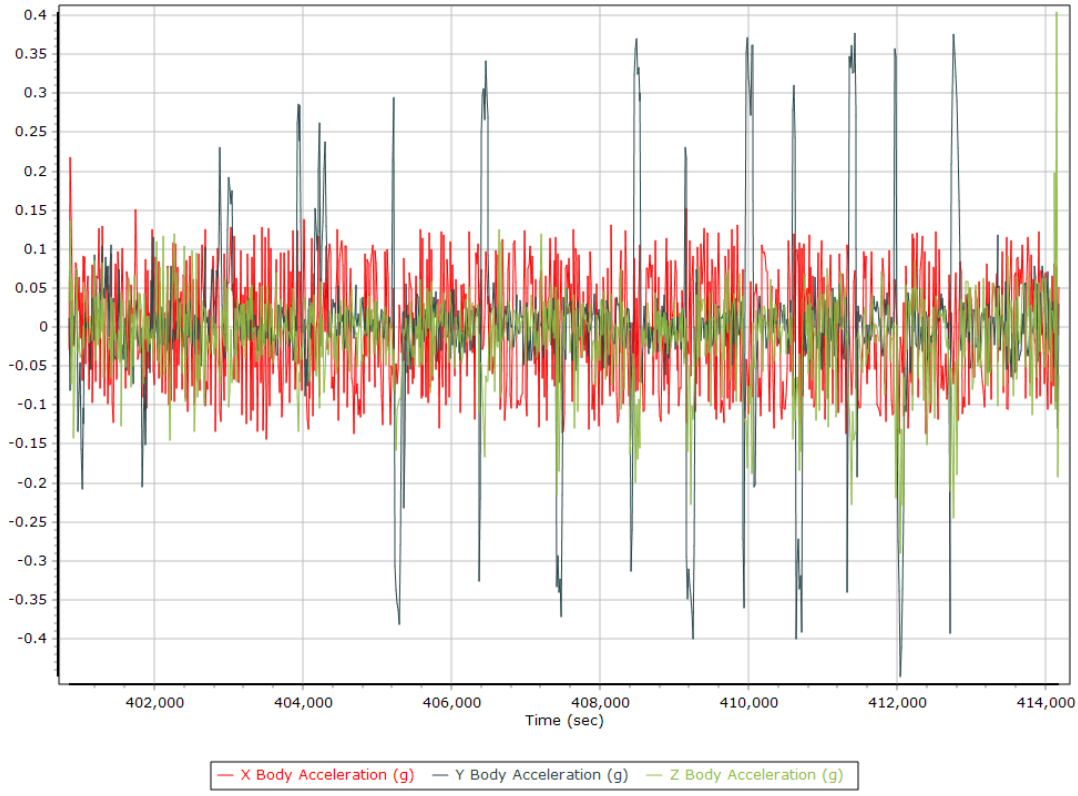
Total Speed



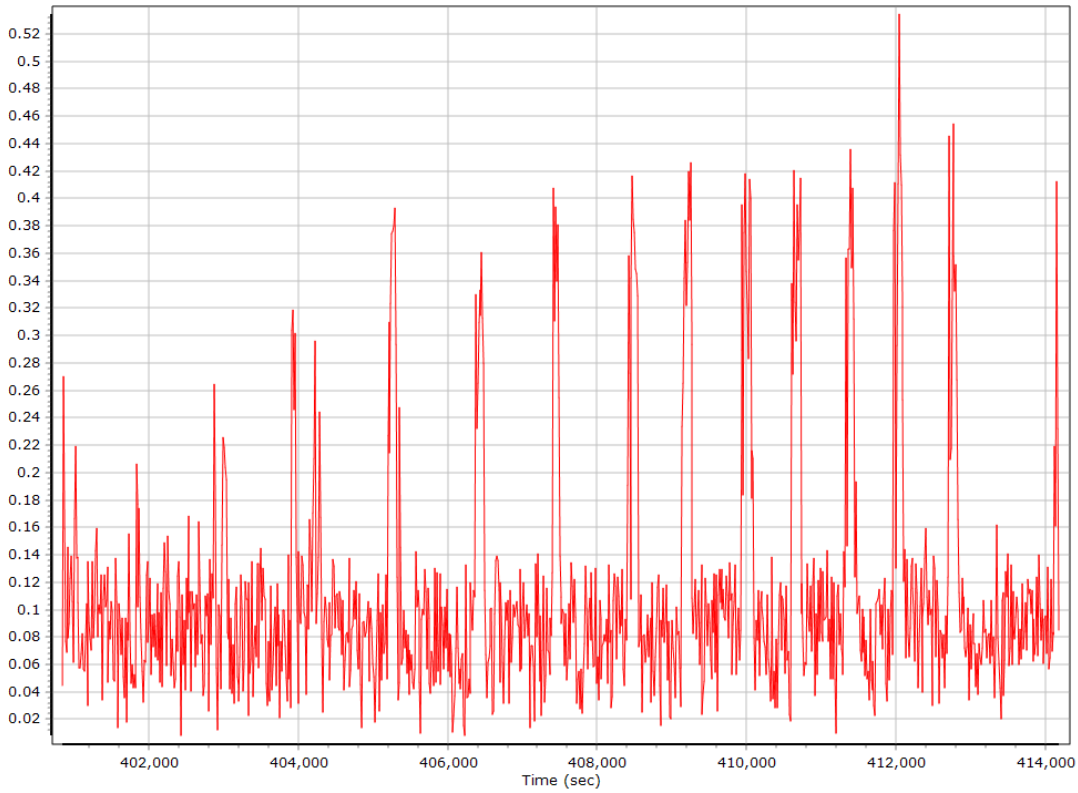
Ground Speed



Body Acceleration



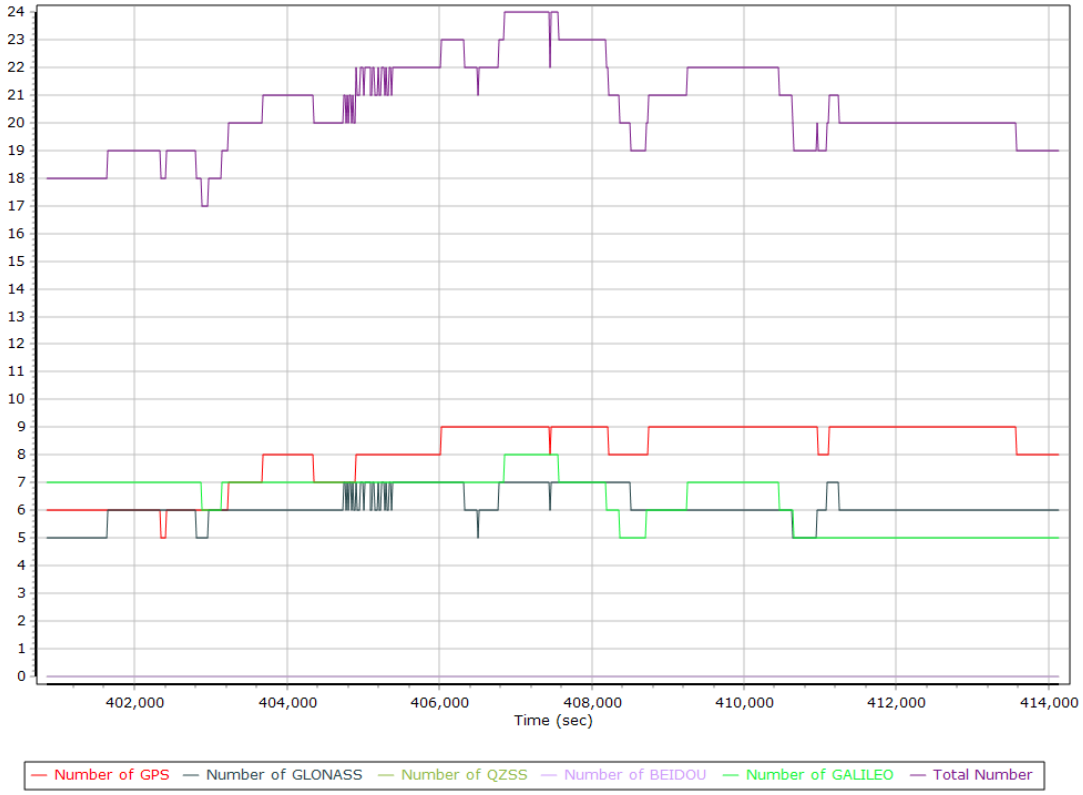
Total Body Acceleration



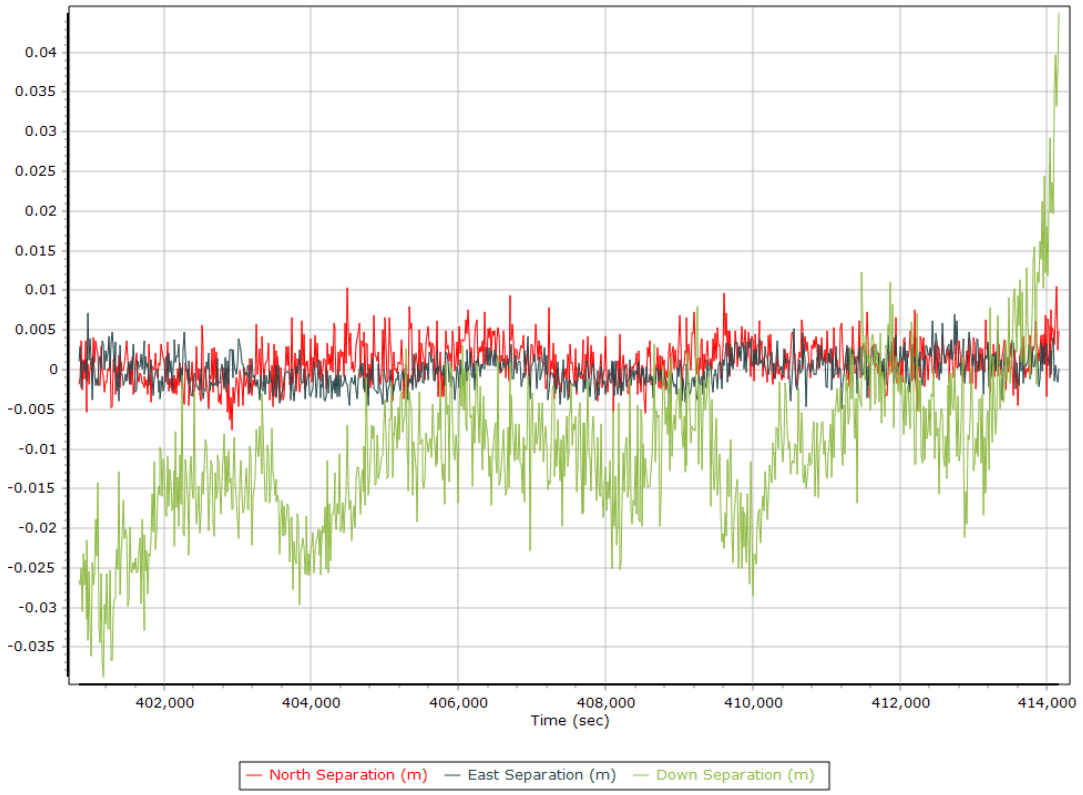
Body Angular Rate

GNSS QC

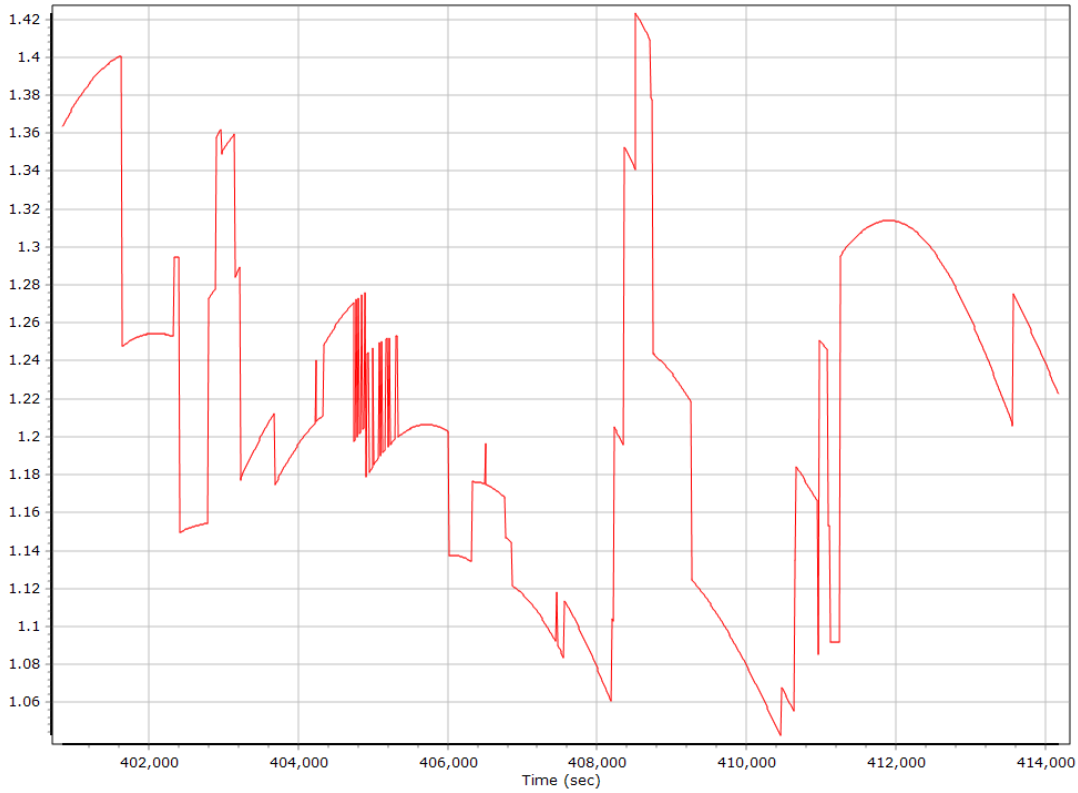
Num SVs in solution



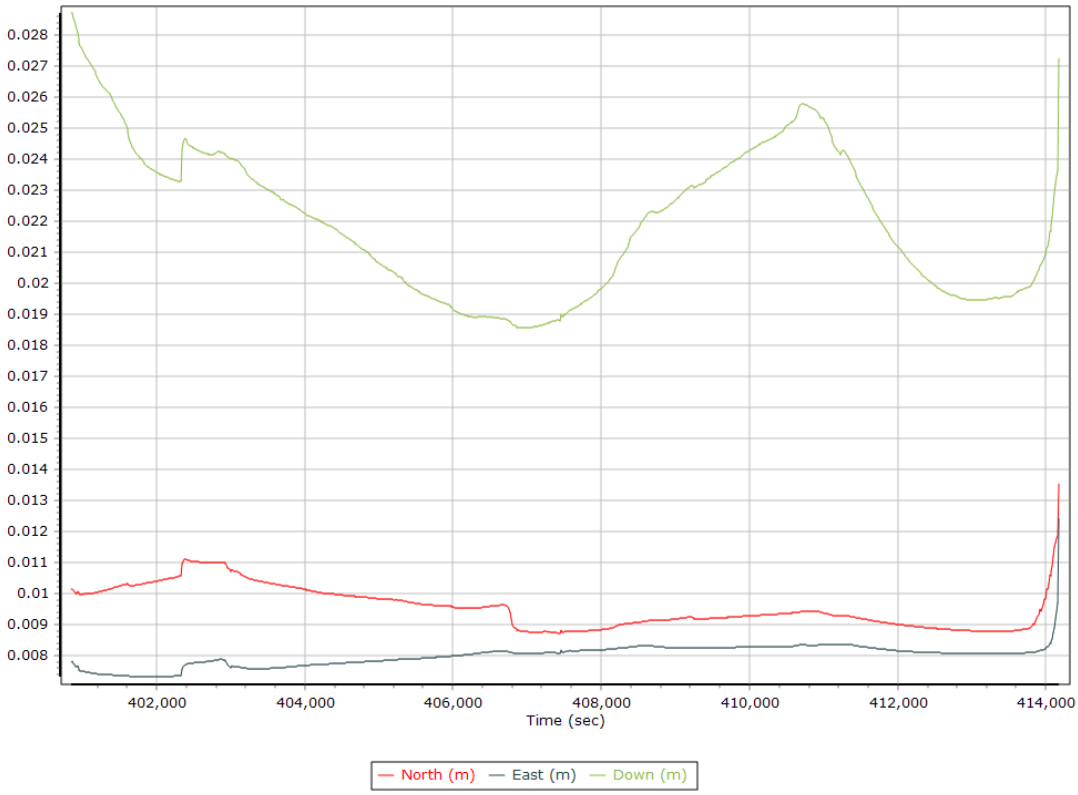
Forward/Reverse Separation



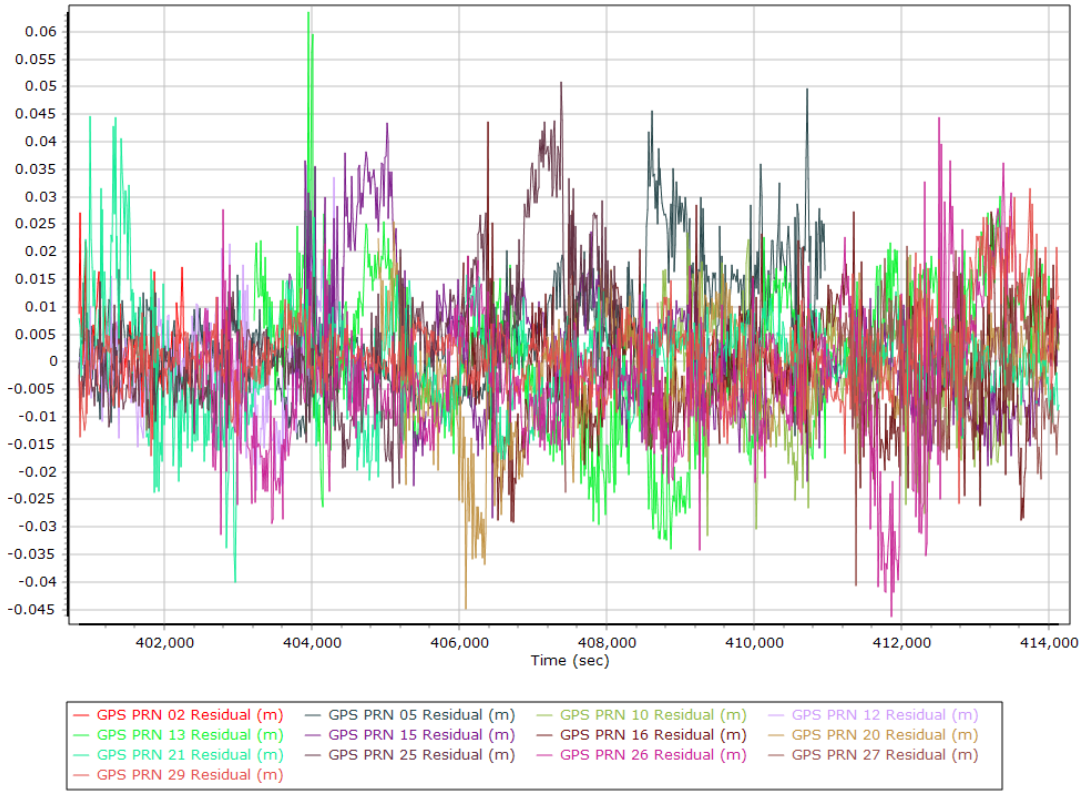
PDOP



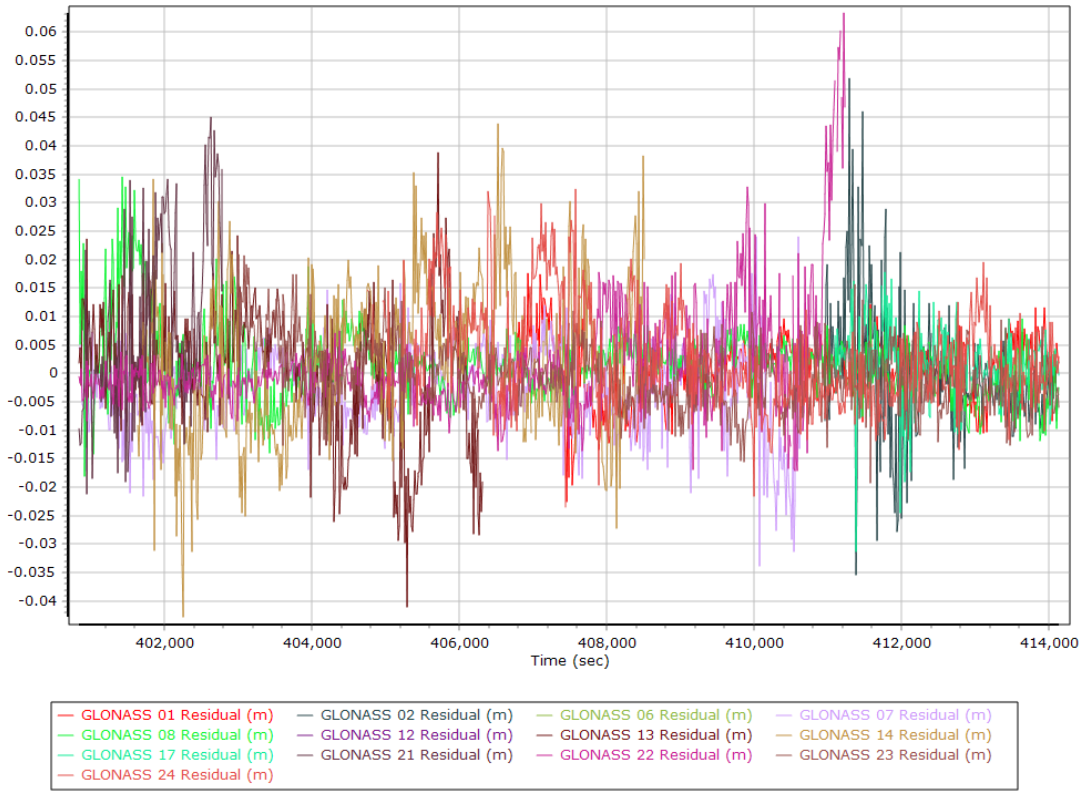
Estimated Position Accuracy



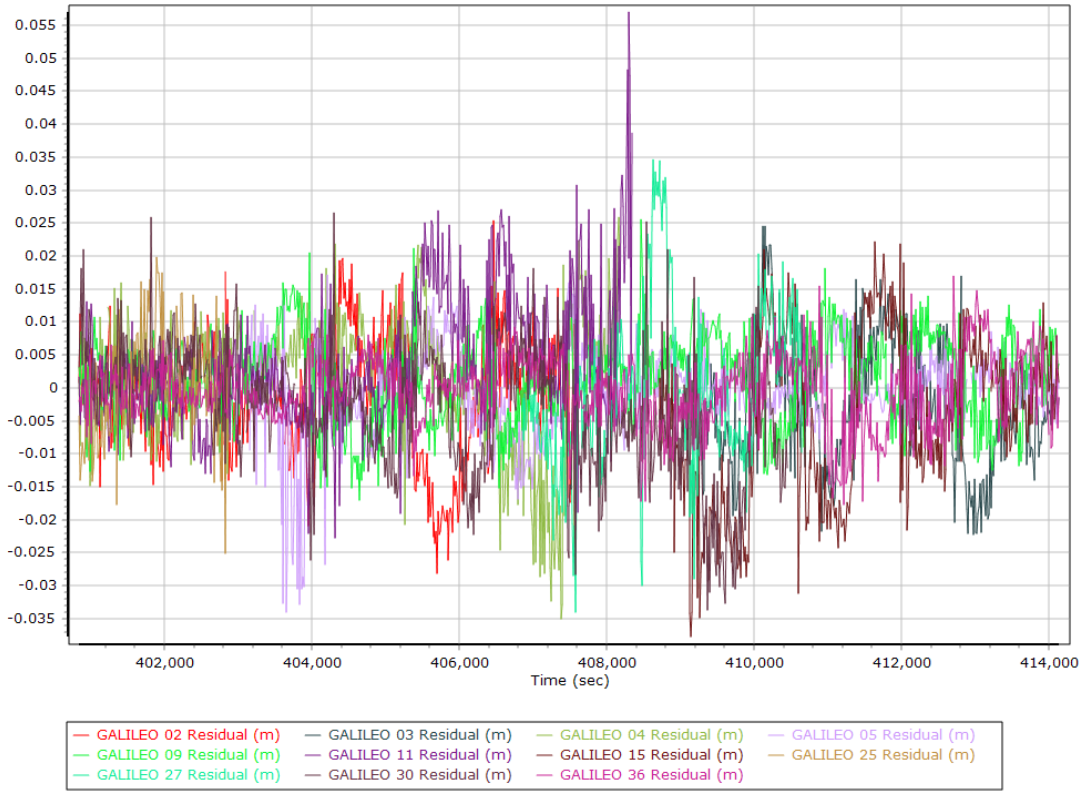
GPS Residuals



GLONASS Residuals



GALILEO Residuals



GNSS-Inertial Processor Configuration

Processing mode	IN-Fusion PP-RTX		
Stabilized mount	False		
Processing start time	400539.000 (10/3/2019 3:15:39 PM)		
Processing end time	414185.000 (10/3/2019 7:03:05 PM)		
Initial attitude source	Real-Time VNAV/RNAV Attitude		
IMU Sensor Context	Processing with Onboard IMU		
Reference to IMU lever arm (m)	0.000	0.000	0.000
Reference to IMU mounting angles (deg)	0.000	0.000	180.000
Reference to Primary GNSS lever arm (m)	0.310	-0.156	-0.942
Reference to Primary GNSS lever arm std dev (m)	0.030	0.030	0.030
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

Calibrated Installation Parameters

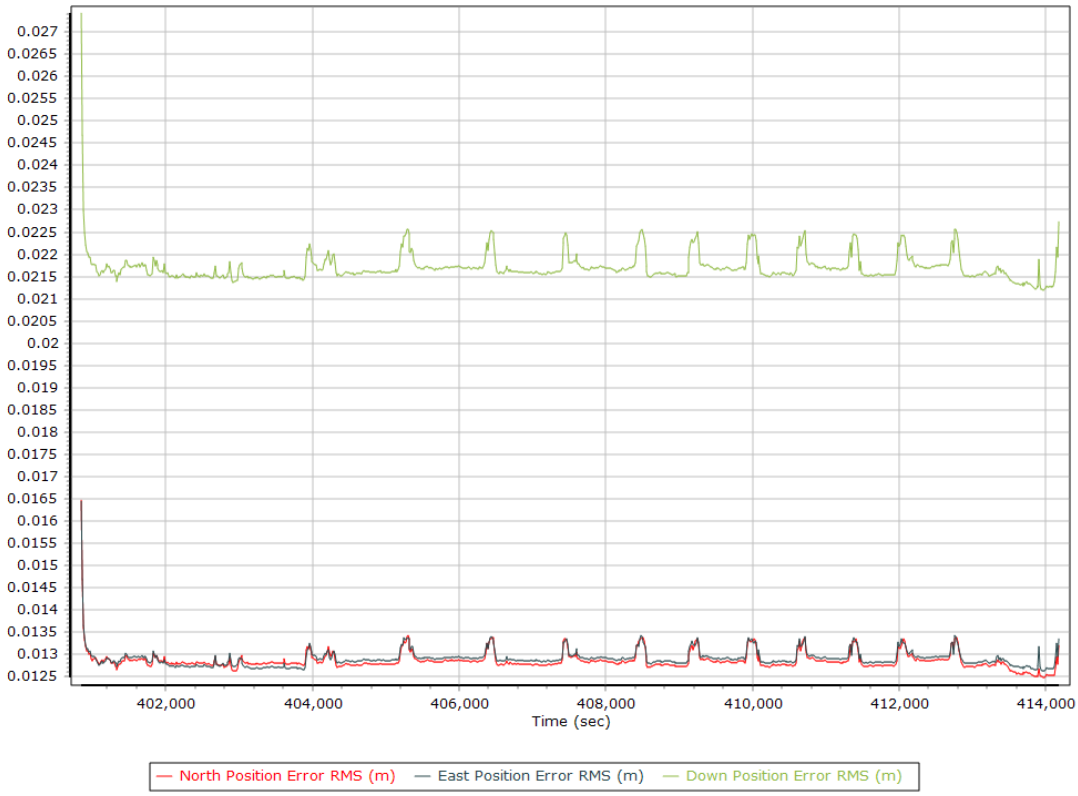
Reference-Primary GNSS Lever Arm (m)

IN-Fusion QC

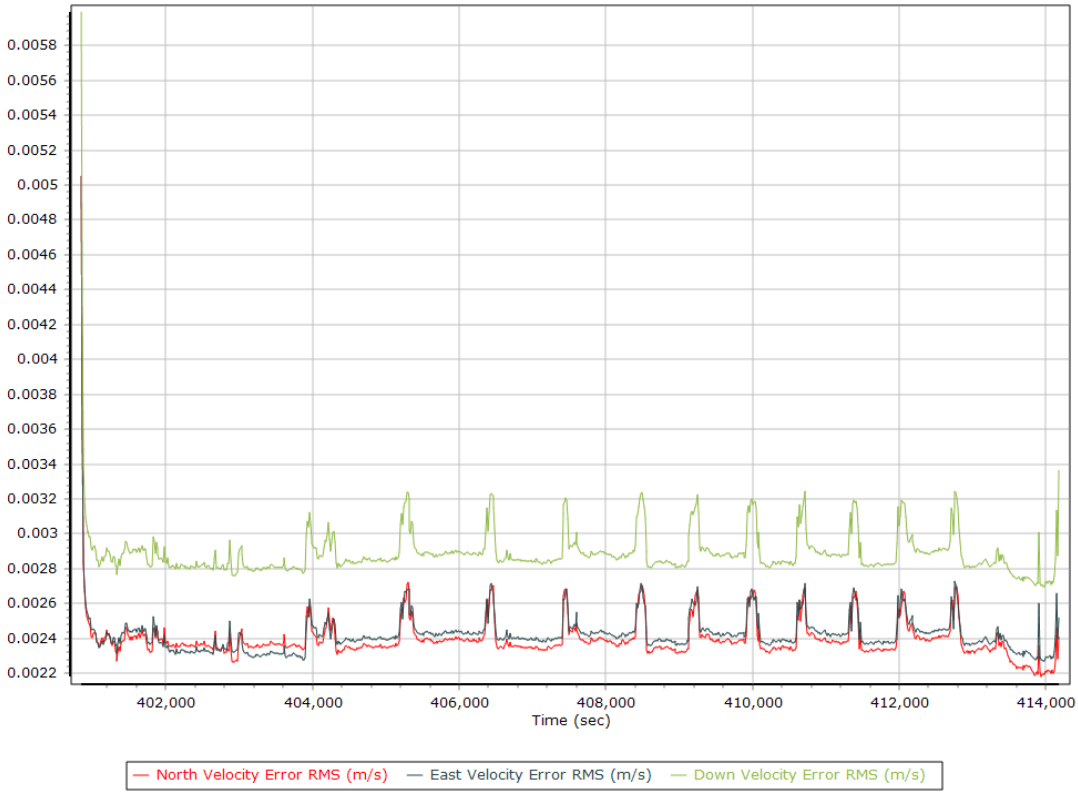
Forward Processed Estimated Errors, Reference Frame

Smoothed Performance Metrics

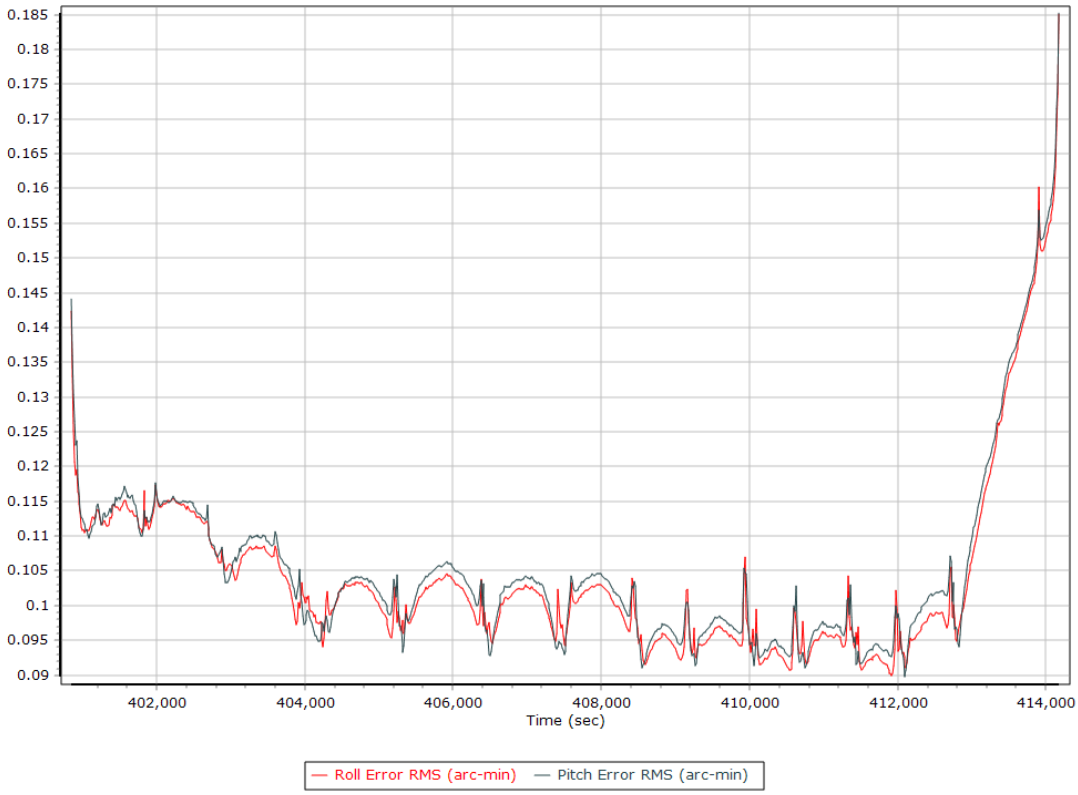
Position Error RMS (m)



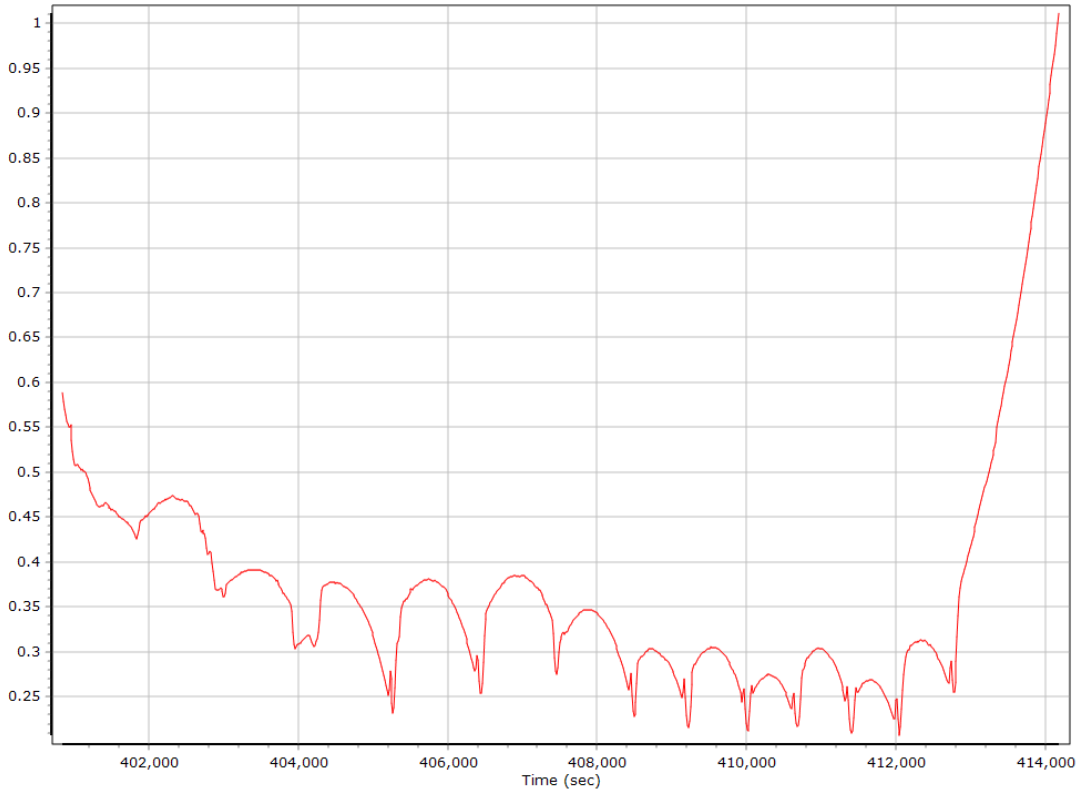
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

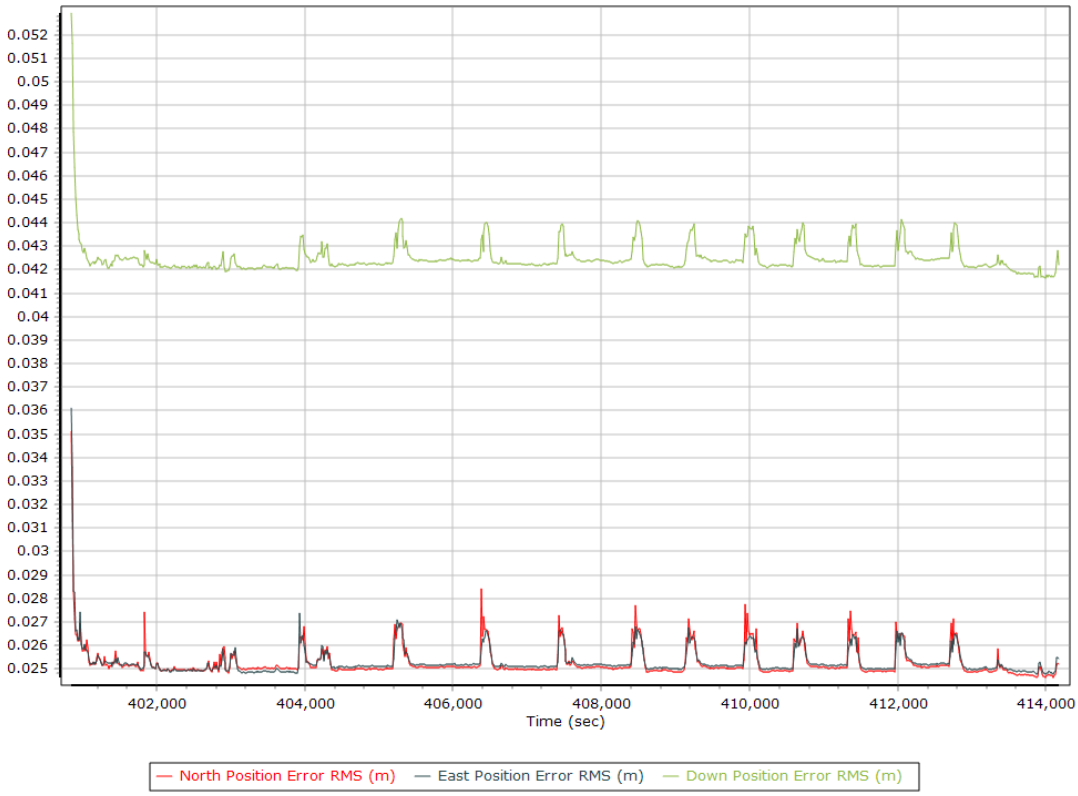


Heading Error RMS (arc-min)

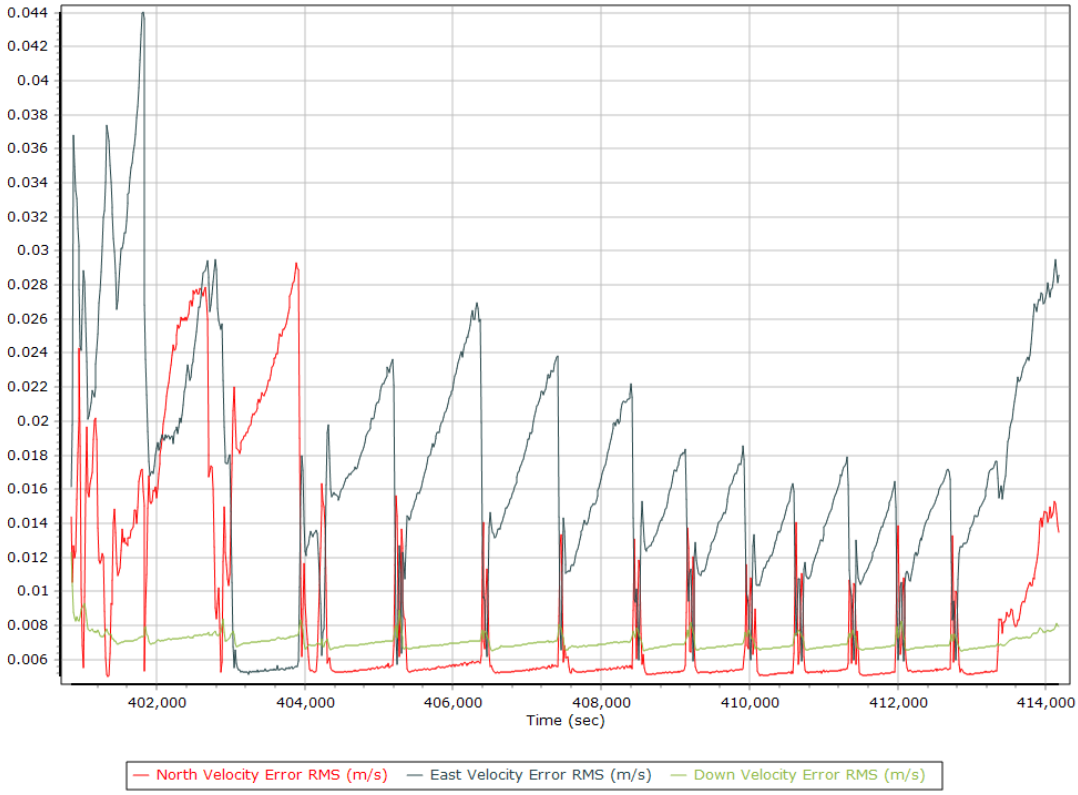


Forward Processed Performance Metrics

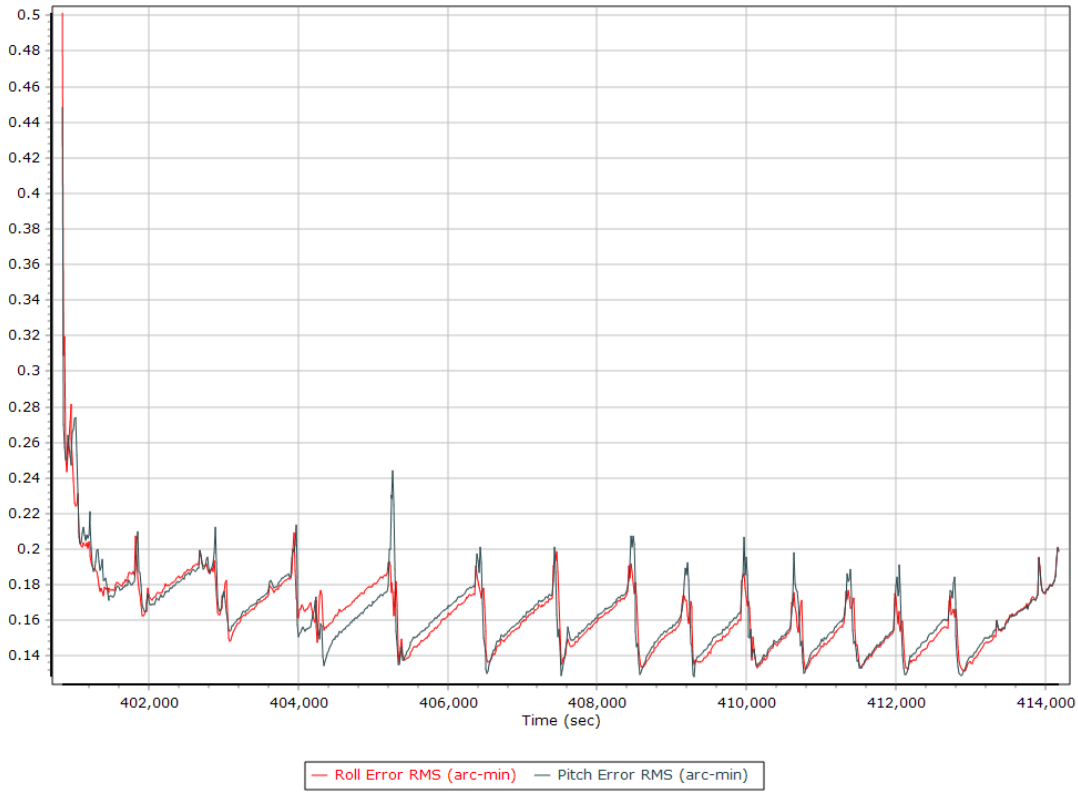
Position Error RMS (m)



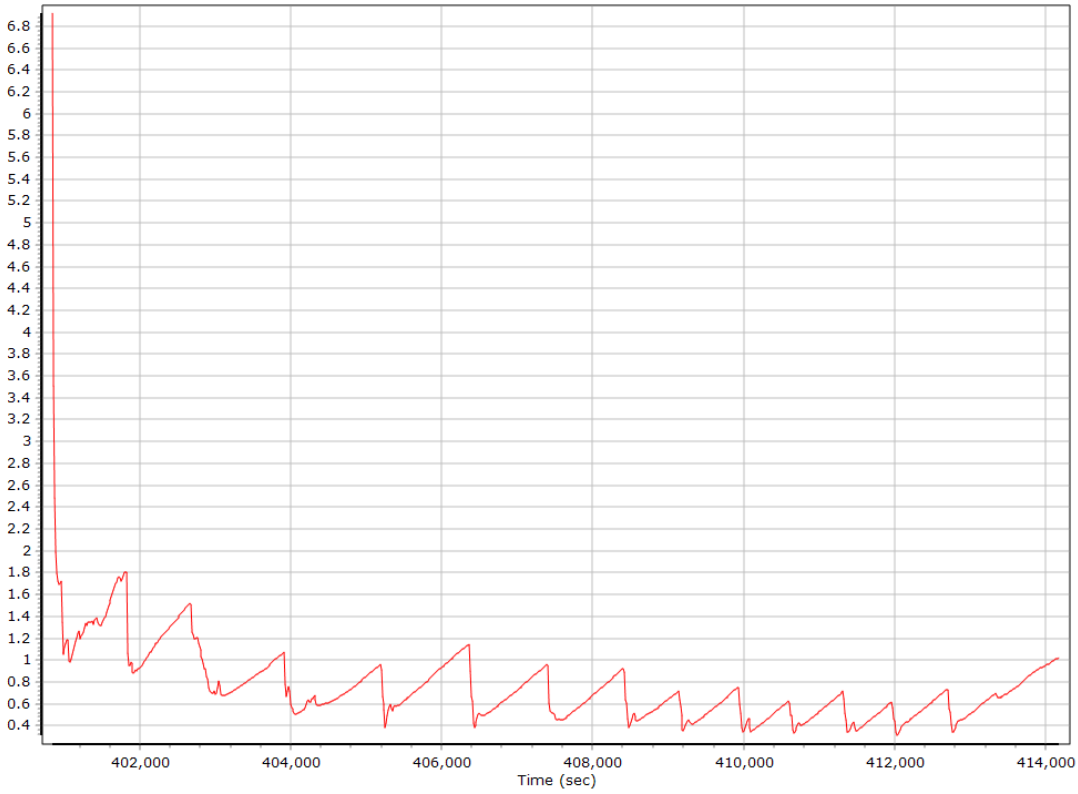
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

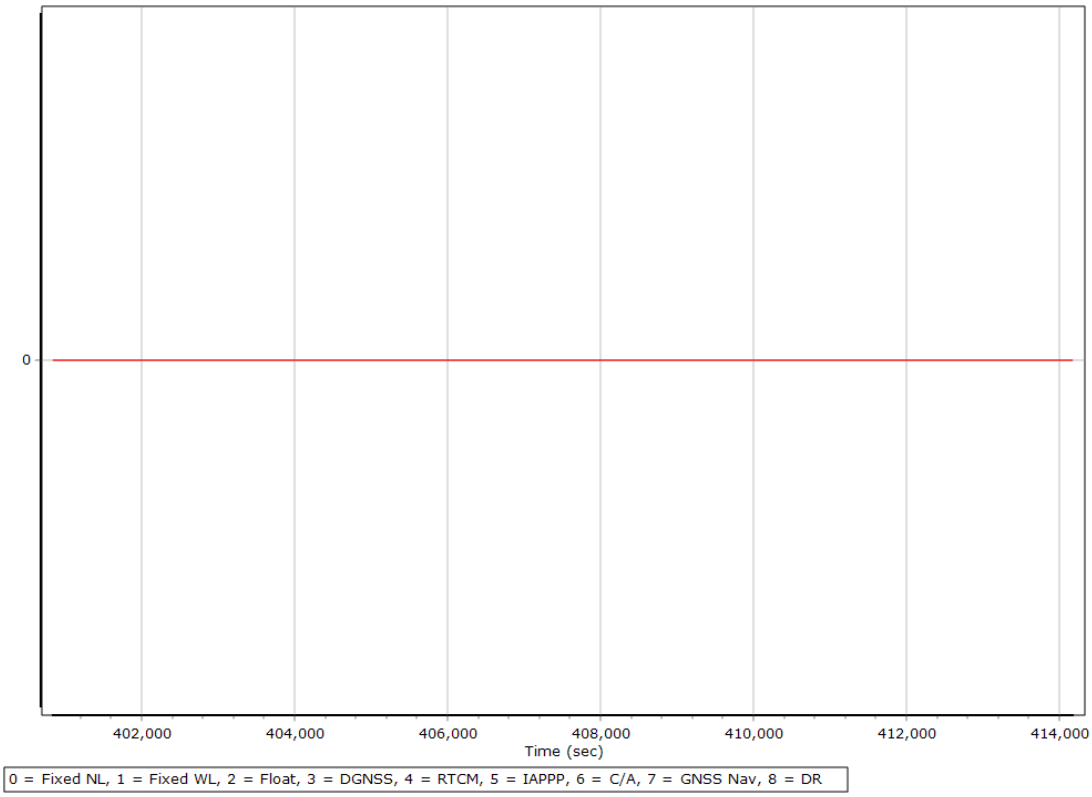


Heading Error RMS (arc-min)

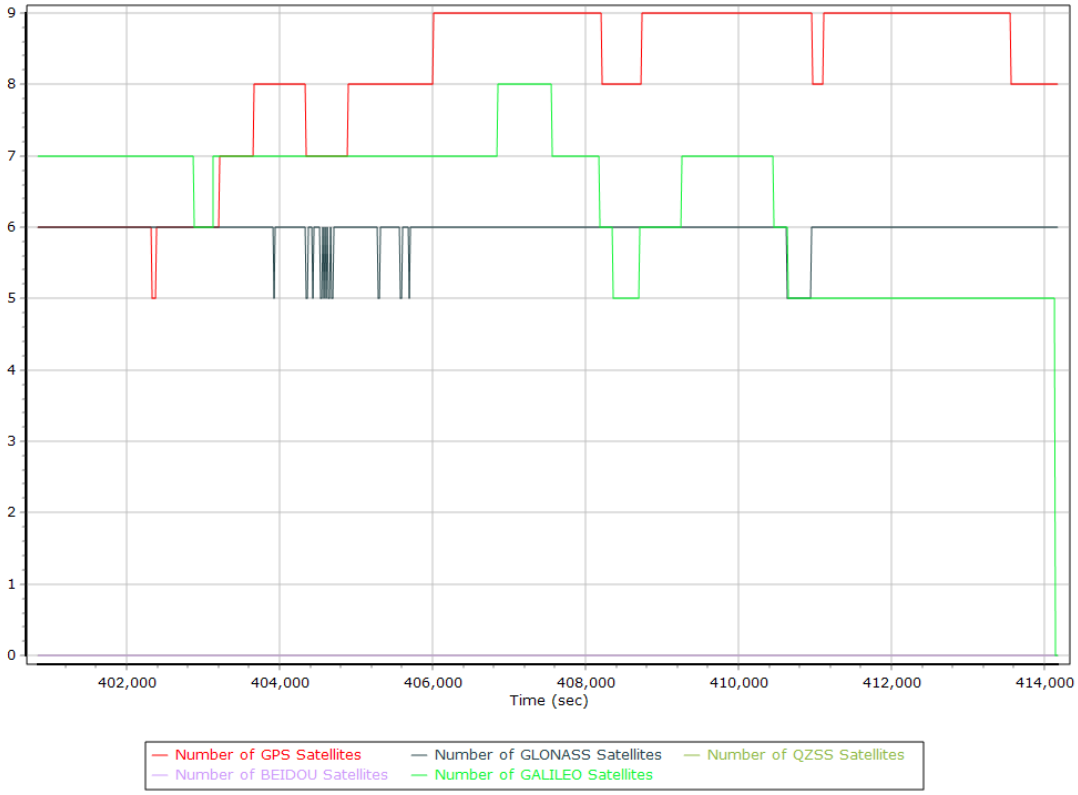
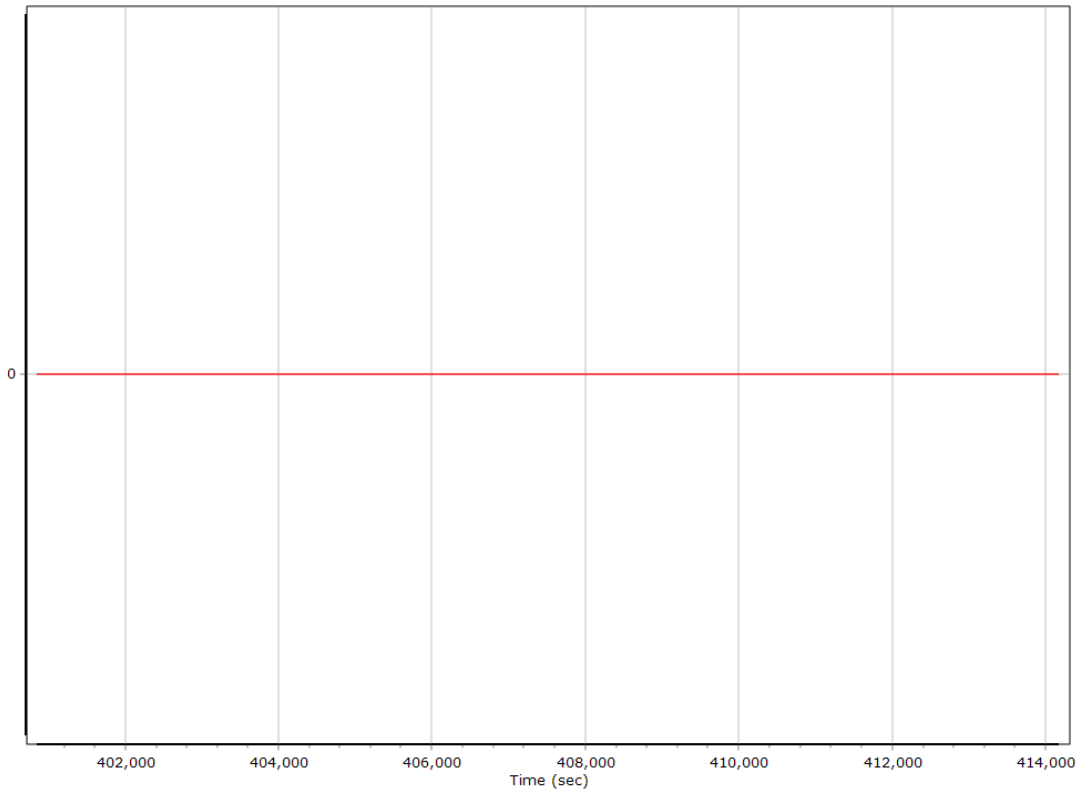


Forward Processed Solution Status

Processing Mode



Number of Satellites



Baseline Length