

General Information

Mission Information

Project name	21-068_FFFC_210921
Processing date	2021-09-29 21:24:27
Mission date	2021-09-21 14:51:28
Mission duration	07:12:09.000
Processing mode	IN-Fusion Trimble RTX Nav

Rover Hardware Information

Product	POS AV 610 VER6 HW2.5-12
Serial number	S/N6675
IMU type	57
Receiver type	BD982
Antenna type	AV39

Project File List

Rover Data Files

File name	File type
210921_145112_POSAV610-6675.raw	POS Data

Input Files

File Name	File Type
Ephm2640.21g	GLONASS Broadcast Ephemeris
Ephm2640.21n	GPS Broadcast Ephemeris

Output Files

Filename	File type
sbet_21-081_FFFC_210921.out	SBET Trajectory File

Rover Data Summary

First raw data file	210921_145112_POSAV610-6675.raw		
Last raw data file	210921_145112_POSAV610-6675.raw		
Start GPS week	2176		
Start time	226269.312 (09/21/2021 14:51:09)		
End time	252195.331 (09/21/2021 22:03:15)		
Start of fine alignment	226816.449 (09/21/2021 15:00:16)		
Available subsystems	Primary GNSS, IMU		
POS Event Input	Event 1 Input		
Correction data	Trimble RTX		
IMU Installation Lever Arms & Mounting Angles			
Reference to IMU lever arm (m)	0.000	0.000	0.000
Reference to IMU mounting angles (deg)	0.000	0.000	0.000
Reference to Primary GNSS lever arm (m)	0.016	0.063	-0.958
Reference to Primary GNSS lever arm std dev (m)	-1.000		
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

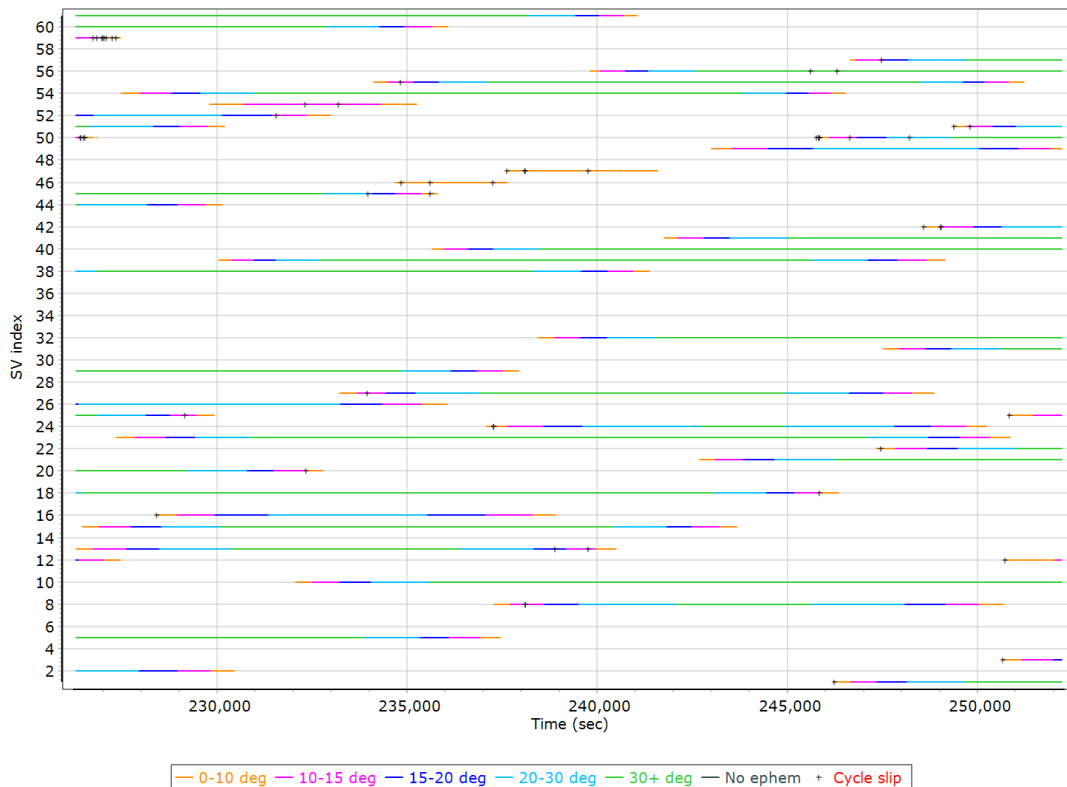
Rover Data QC

Raw IMU Import QC Summary

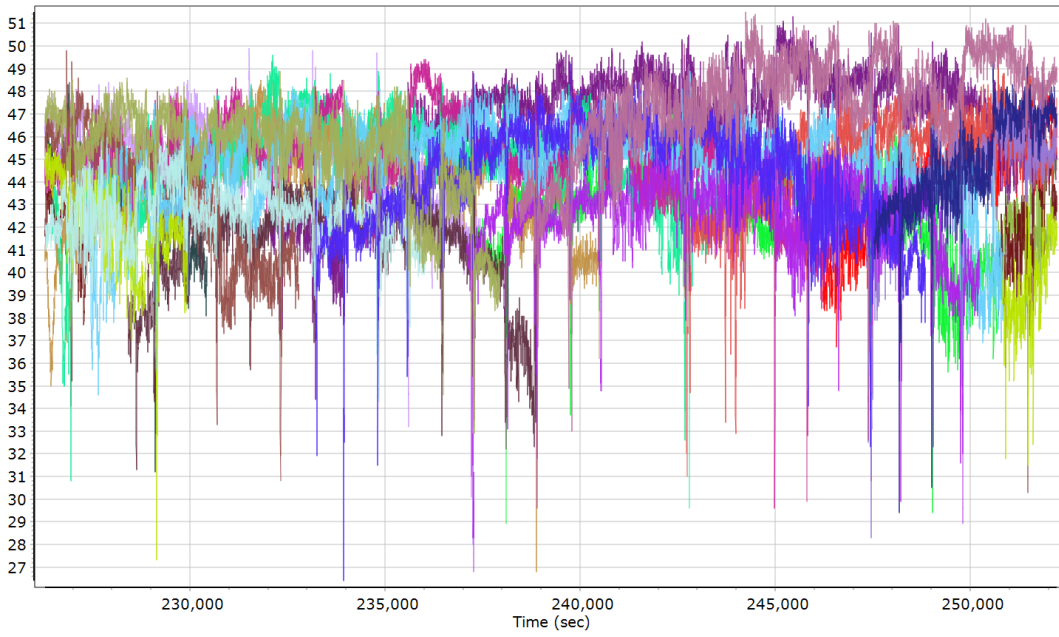
IMU data input file	imu_21-081_FFFC_210921.dat
IMU data check log file	imudt_21-081_FFFC_210921.log
IMU Records Processed	5184903
Termination Status	Normal
IMU Anomalies	0

Primary Observables & Satellite Data

GPS/GLONASS L1 Satellite Lock/Elevation

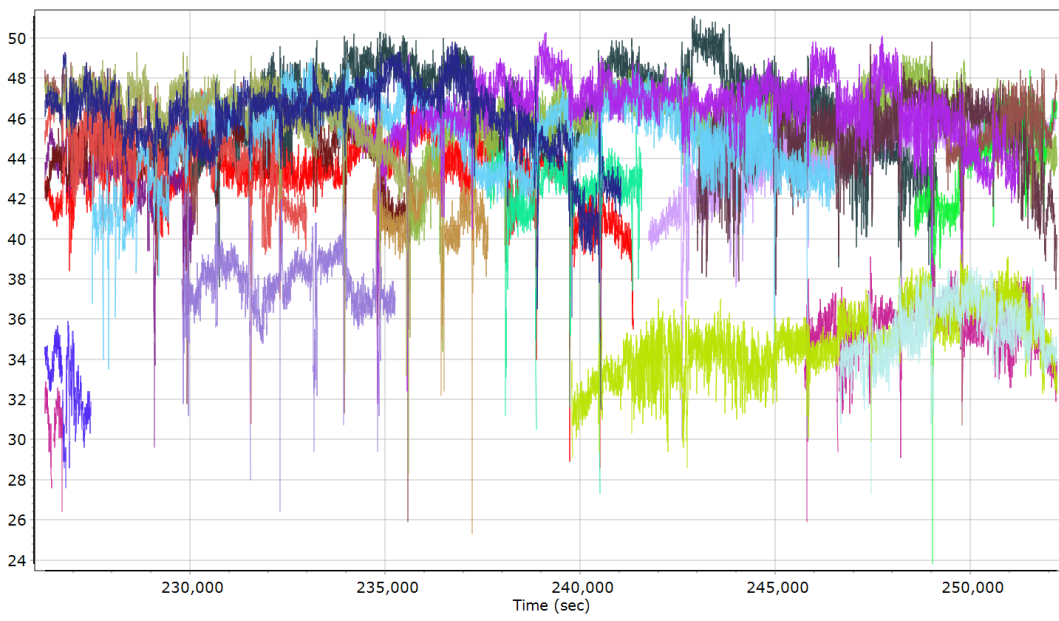


GPS L1 SNR



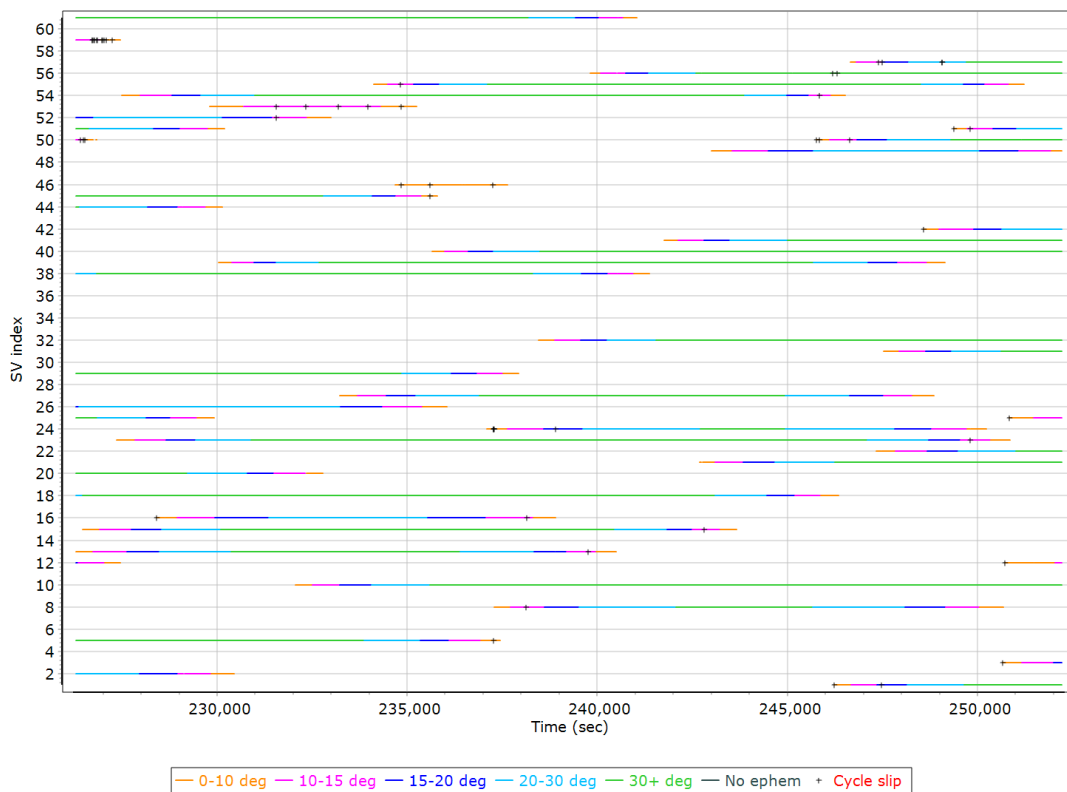
- | | | | |
|---------------------------|---------------------------|---------------------------|---------------------------|
| GPS PRN 01 L1 SNR (dB/Hz) | GPS PRN 02 L1 SNR (dB/Hz) | GPS PRN 03 L1 SNR (dB/Hz) | GPS PRN 05 L1 SNR (dB/Hz) |
| GPS PRN 08 L1 SNR (dB/Hz) | GPS PRN 10 L1 SNR (dB/Hz) | GPS PRN 12 L1 SNR (dB/Hz) | GPS PRN 13 L1 SNR (dB/Hz) |
| GPS PRN 15 L1 SNR (dB/Hz) | GPS PRN 16 L1 SNR (dB/Hz) | GPS PRN 18 L1 SNR (dB/Hz) | GPS PRN 20 L1 SNR (dB/Hz) |
| GPS PRN 21 L1 SNR (dB/Hz) | GPS PRN 22 L1 SNR (dB/Hz) | GPS PRN 23 L1 SNR (dB/Hz) | GPS PRN 24 L1 SNR (dB/Hz) |
| GPS PRN 25 L1 SNR (dB/Hz) | GPS PRN 26 L1 SNR (dB/Hz) | GPS PRN 27 L1 SNR (dB/Hz) | GPS PRN 29 L1 SNR (dB/Hz) |
| GPS PRN 31 L1 SNR (dB/Hz) | GPS PRN 32 L1 SNR (dB/Hz) | | |

GLONASS L1 SNR

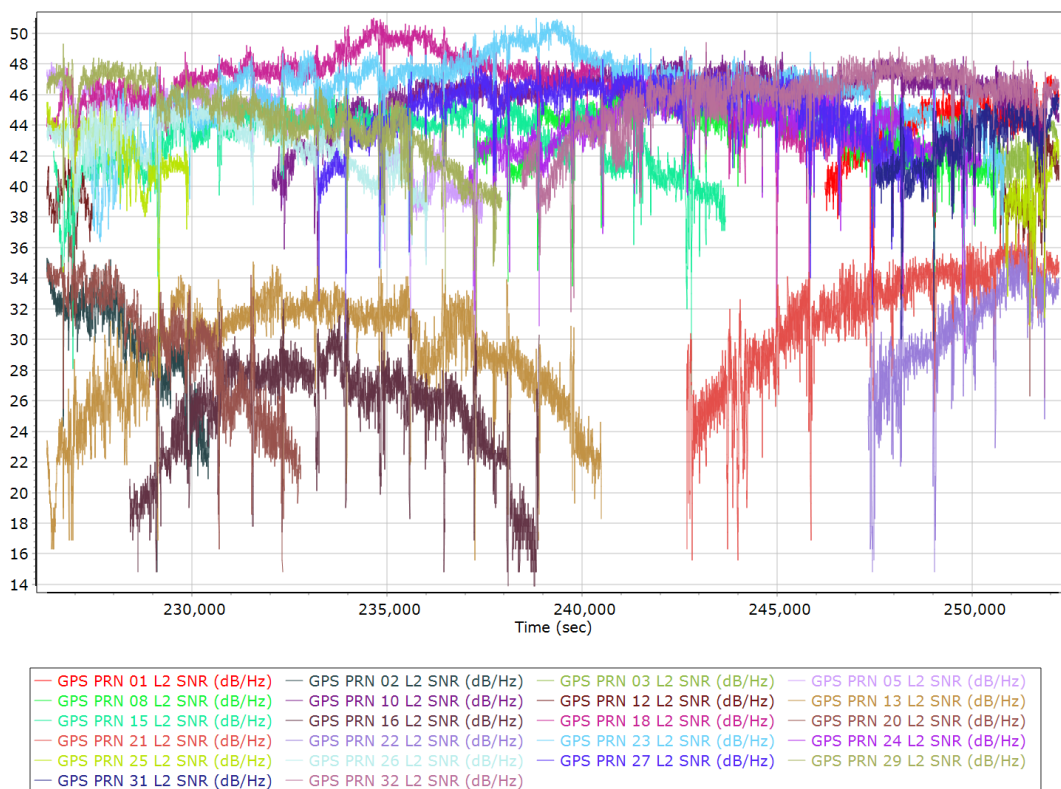


- | | | |
|---------------------------|---------------------------|---------------------------|
| GLONASS 01 L1 SNR (dB/Hz) | GLONASS 02 L1 SNR (dB/Hz) | GLONASS 03 L1 SNR (dB/Hz) |
| GLONASS 04 L1 SNR (dB/Hz) | GLONASS 05 L1 SNR (dB/Hz) | GLONASS 07 L1 SNR (dB/Hz) |
| GLONASS 08 L1 SNR (dB/Hz) | GLONASS 09 L1 SNR (dB/Hz) | GLONASS 10 L1 SNR (dB/Hz) |
| GLONASS 12 L1 SNR (dB/Hz) | GLONASS 13 L1 SNR (dB/Hz) | GLONASS 14 L1 SNR (dB/Hz) |
| GLONASS 15 L1 SNR (dB/Hz) | GLONASS 16 L1 SNR (dB/Hz) | GLONASS 17 L1 SNR (dB/Hz) |
| GLONASS 18 L1 SNR (dB/Hz) | GLONASS 19 L1 SNR (dB/Hz) | GLONASS 20 L1 SNR (dB/Hz) |
| GLONASS 22 L1 SNR (dB/Hz) | GLONASS 23 L1 SNR (dB/Hz) | GLONASS 24 L1 SNR (dB/Hz) |

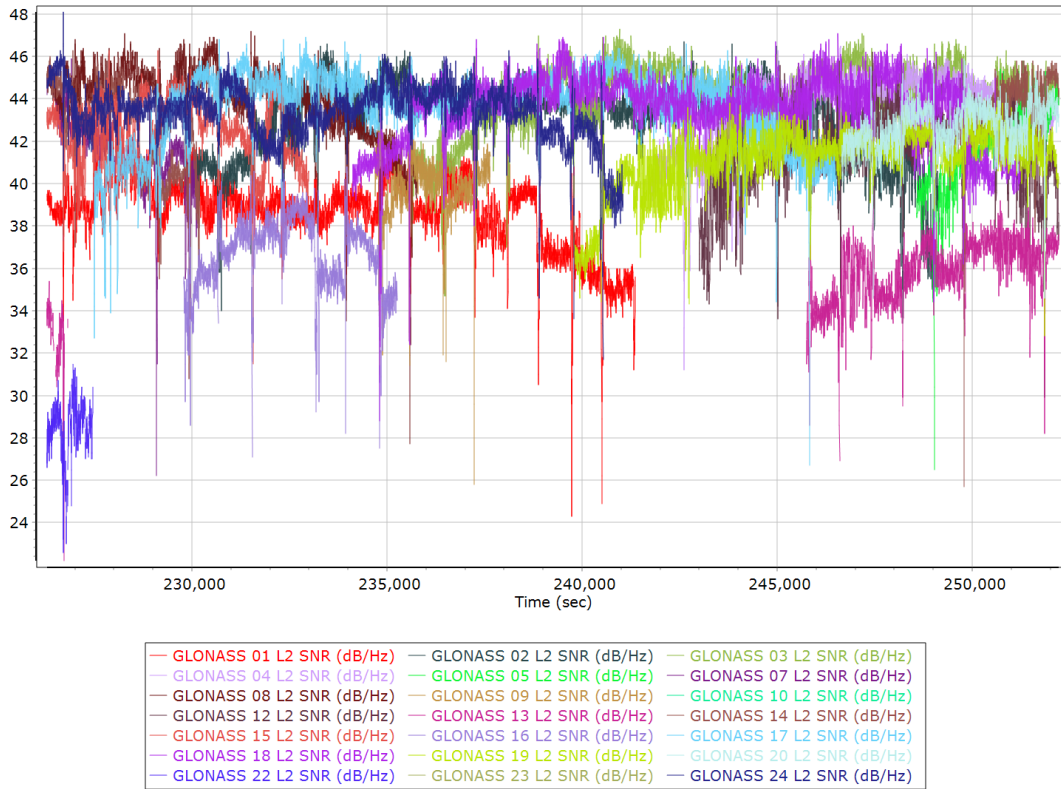
GPS/GLONASS L2 Satellite Lock/Elevation



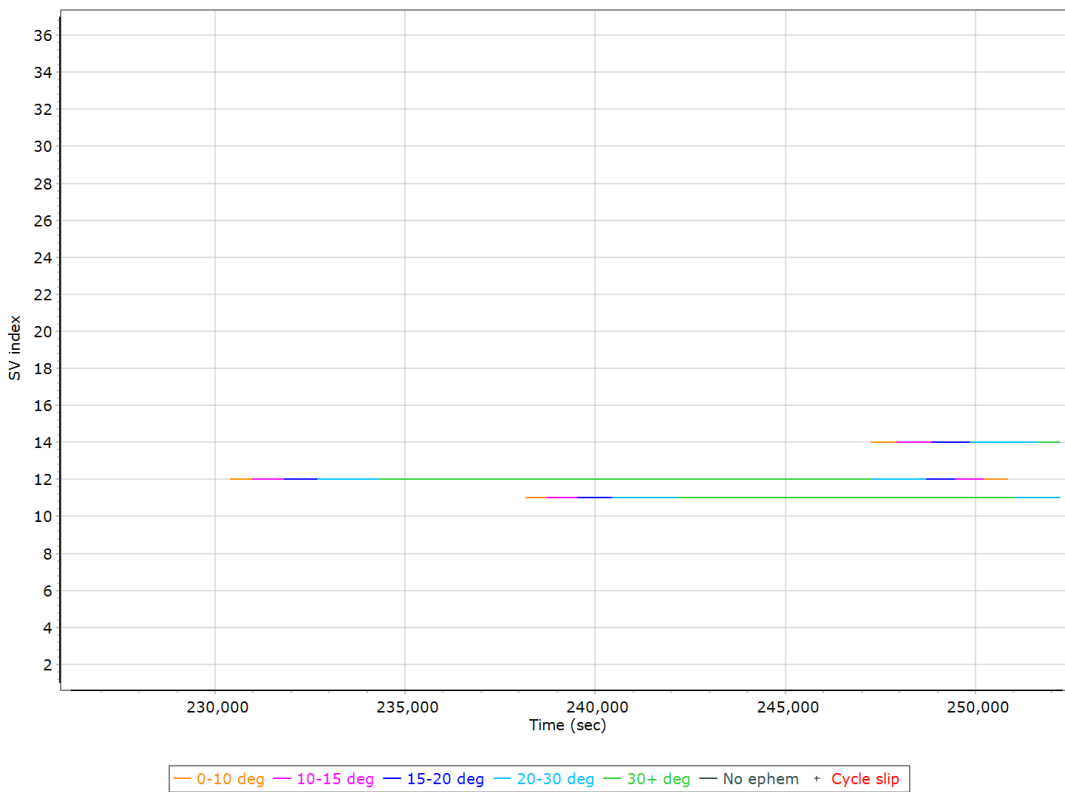
GPS L2 SNR



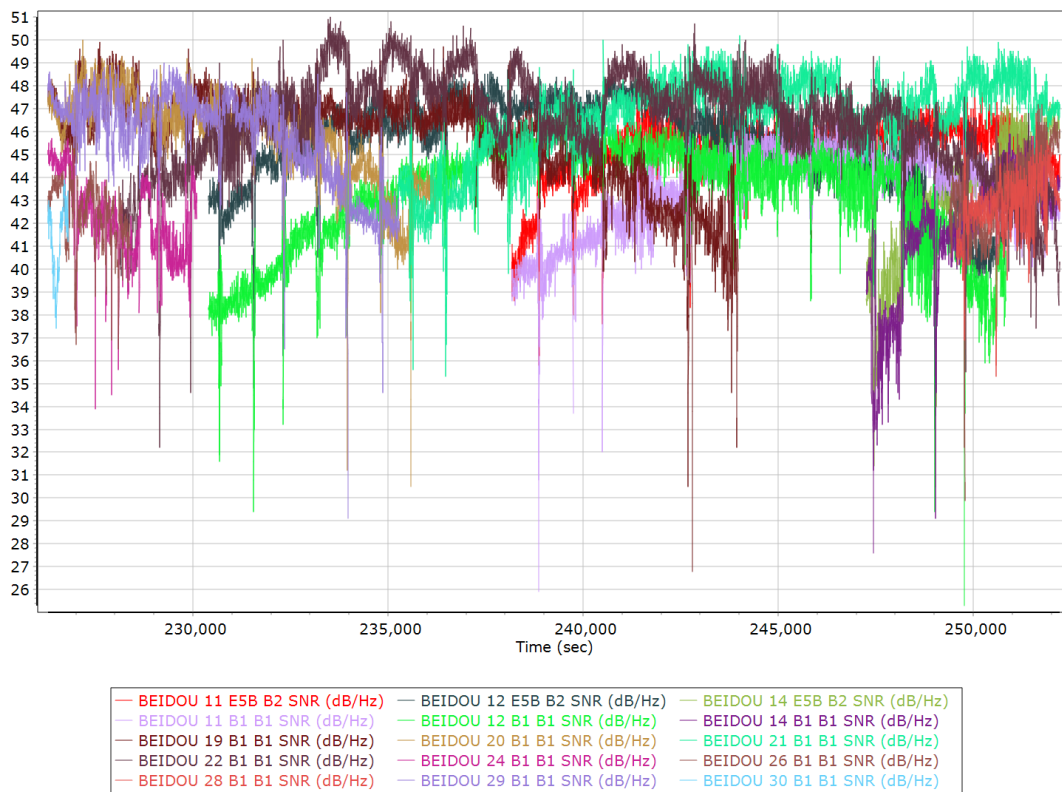
GLONASS L2 SNR



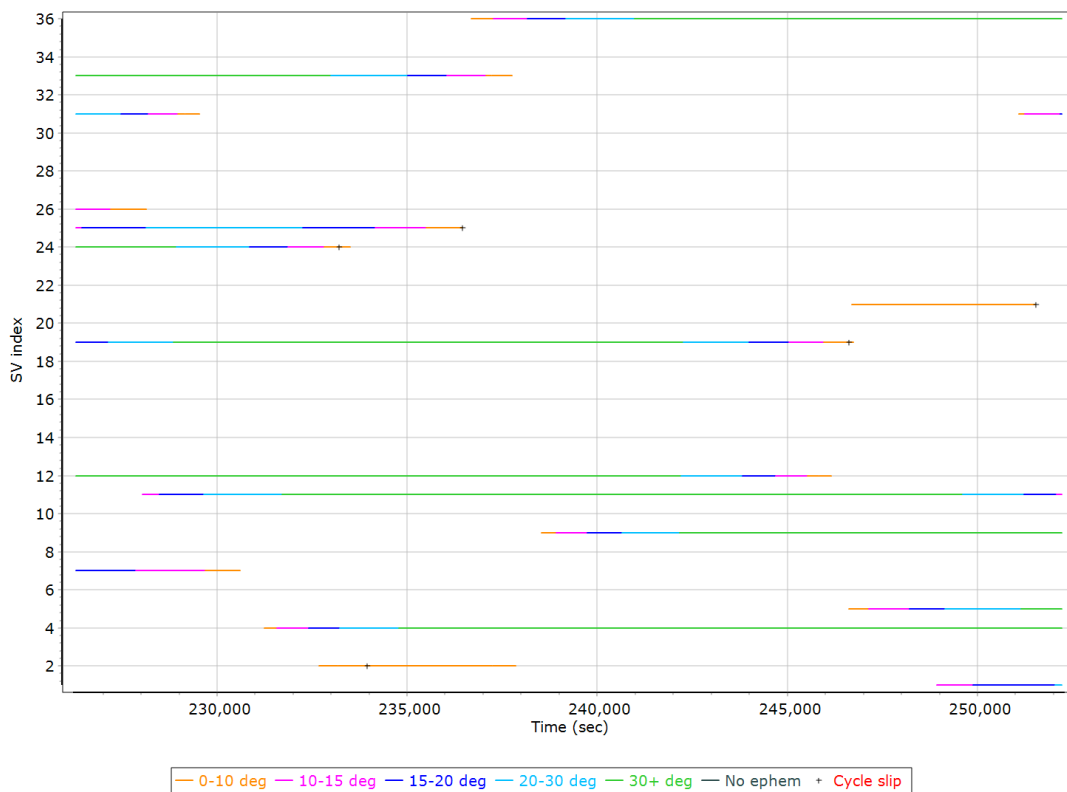
BEIDOU Satellite Lock/Elevation



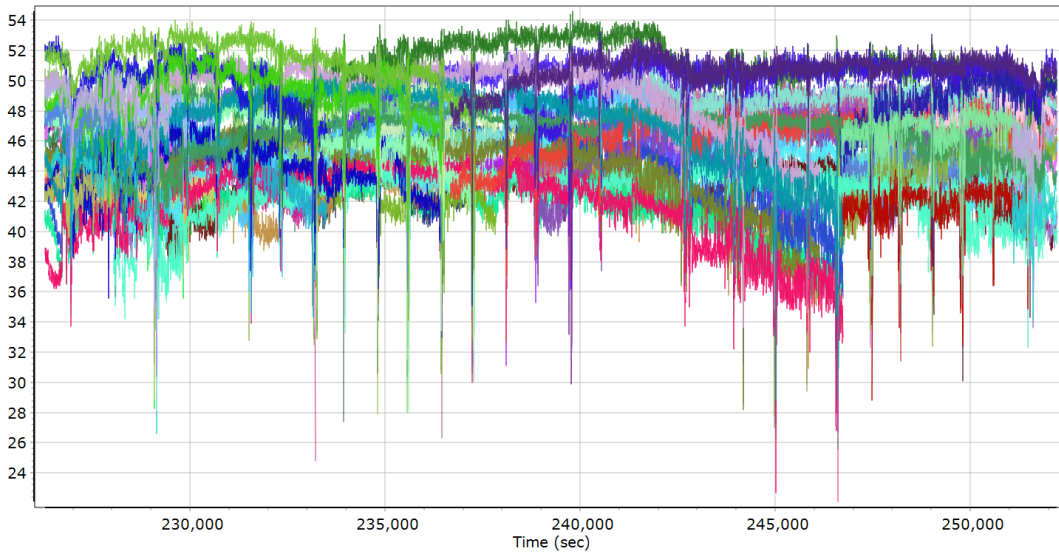
BEIDOU SNR



GALILEO Satellite Lock/Elevation



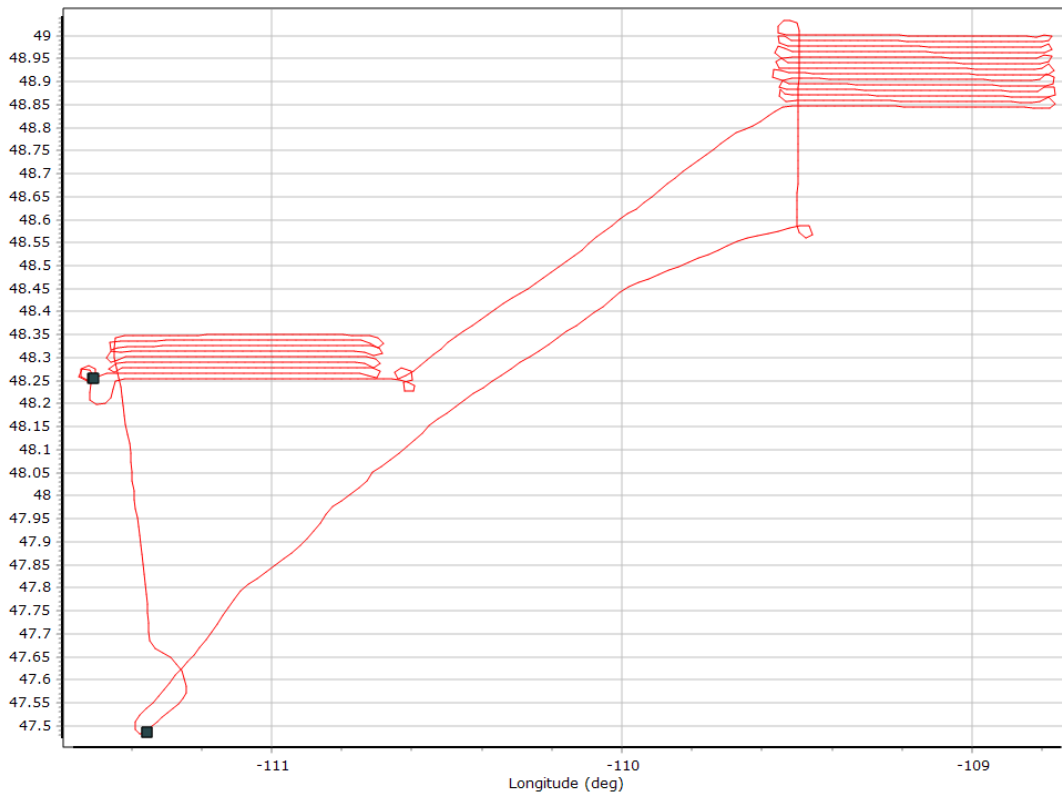
GALILEO SNR



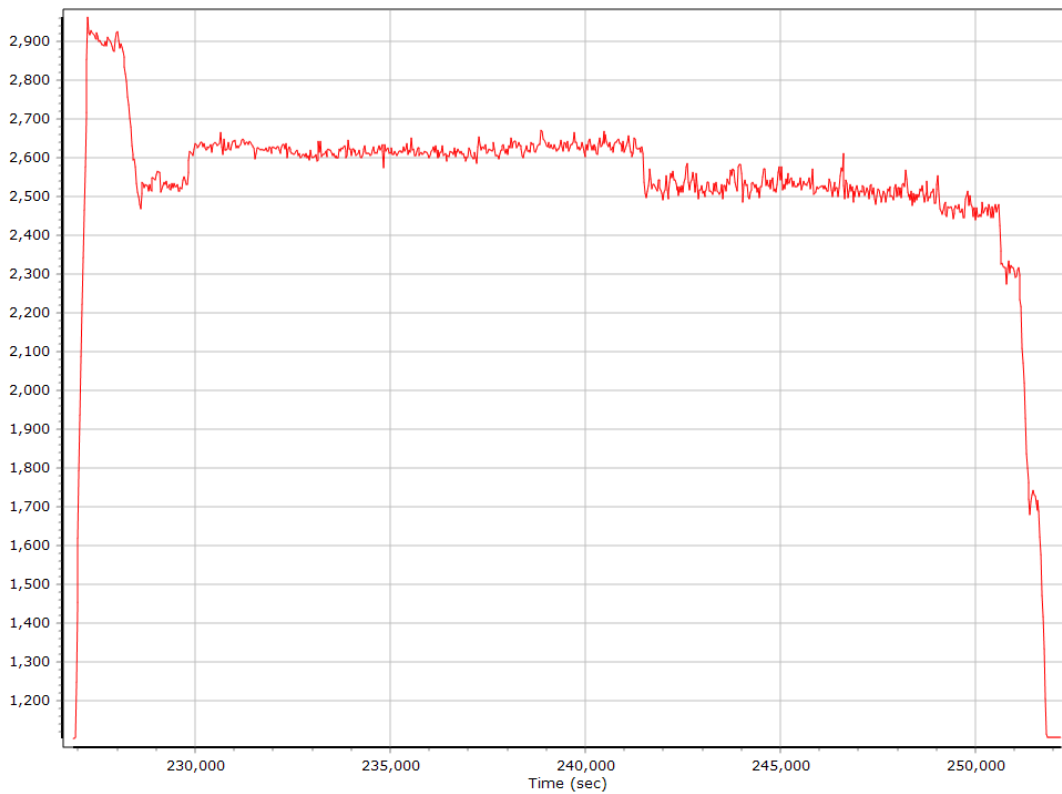
— GALILEO 01 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 02 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 04 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 05 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 07 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 09 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 11 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 12 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 19 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 21 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 24 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 25 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 26 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 31 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 33 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 36 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 01 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 02 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 04 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 05 L5E5A BPSK10_PD SNR (dB/Hz)

Smoothed Trajectory Information

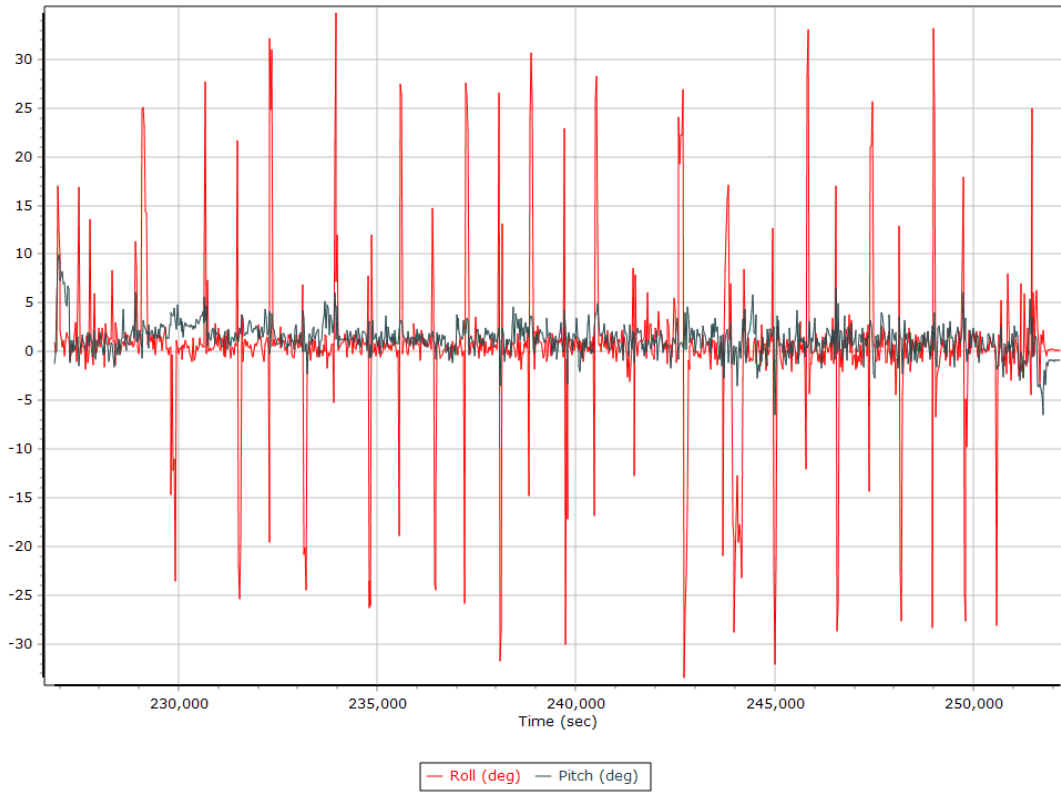
Top View



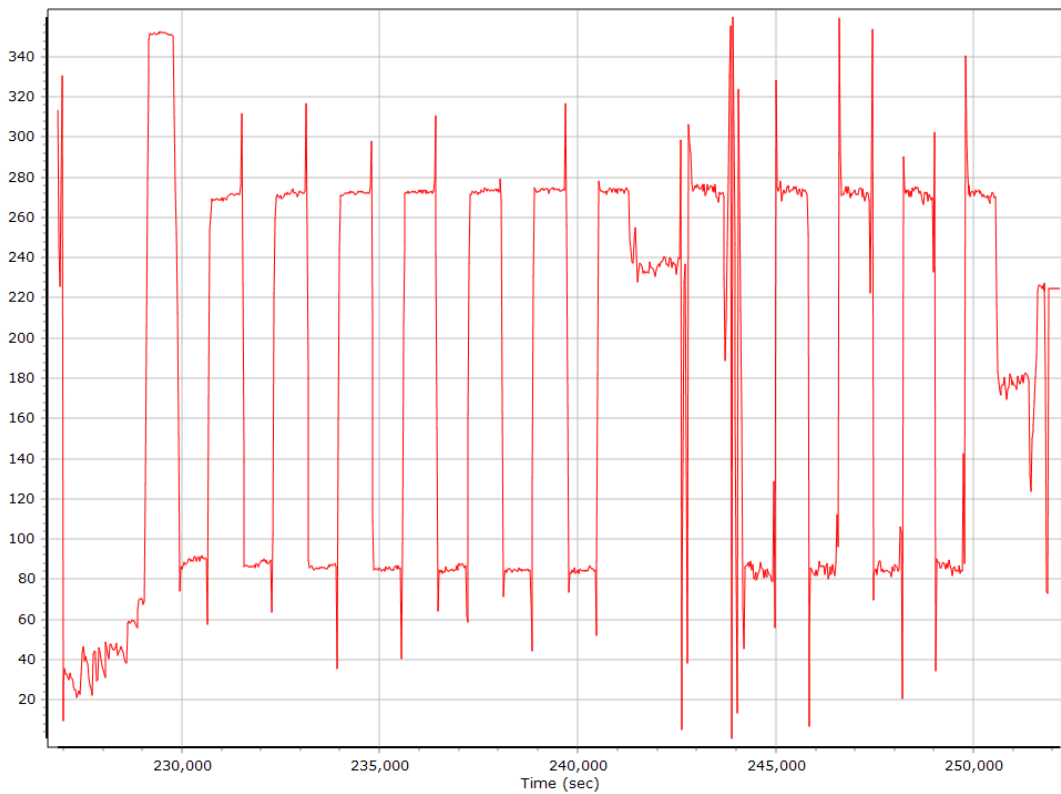
Altitude



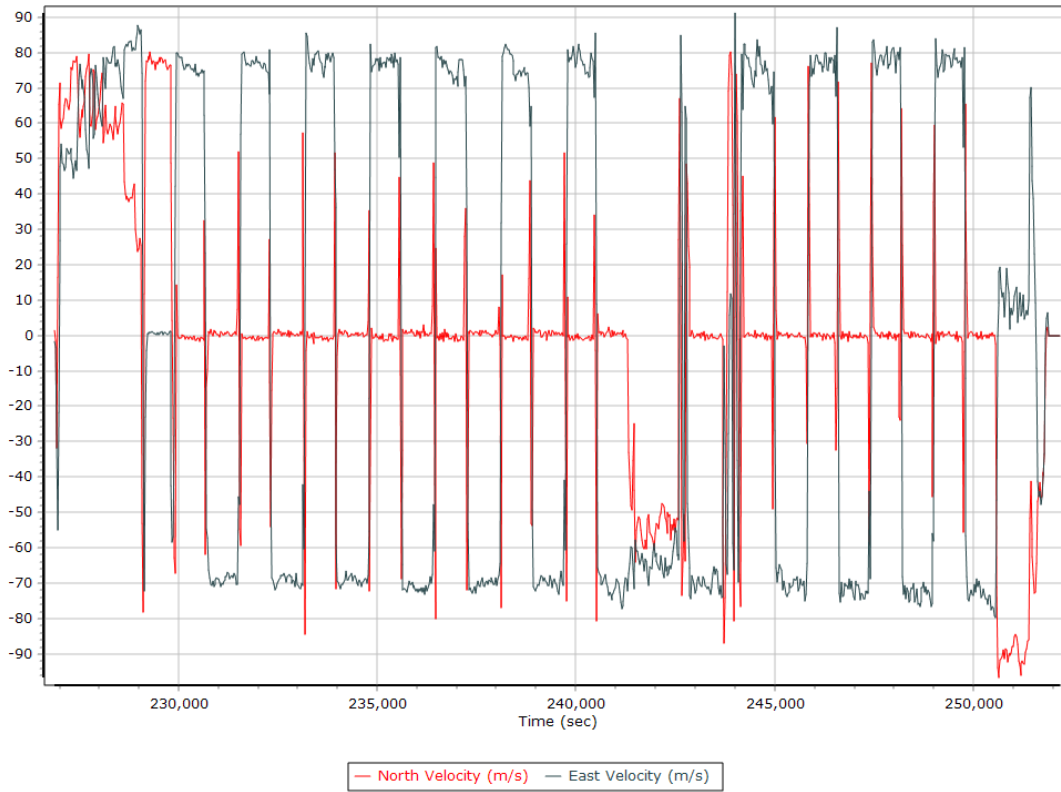
Roll/Pitch



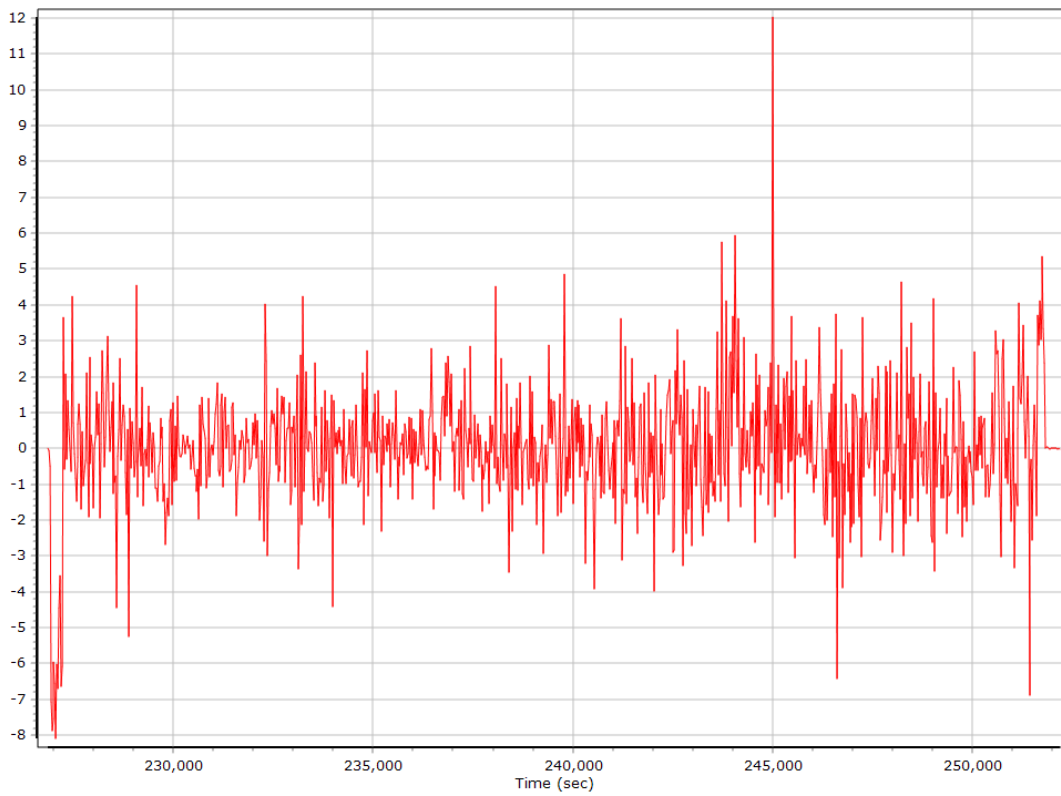
Heading



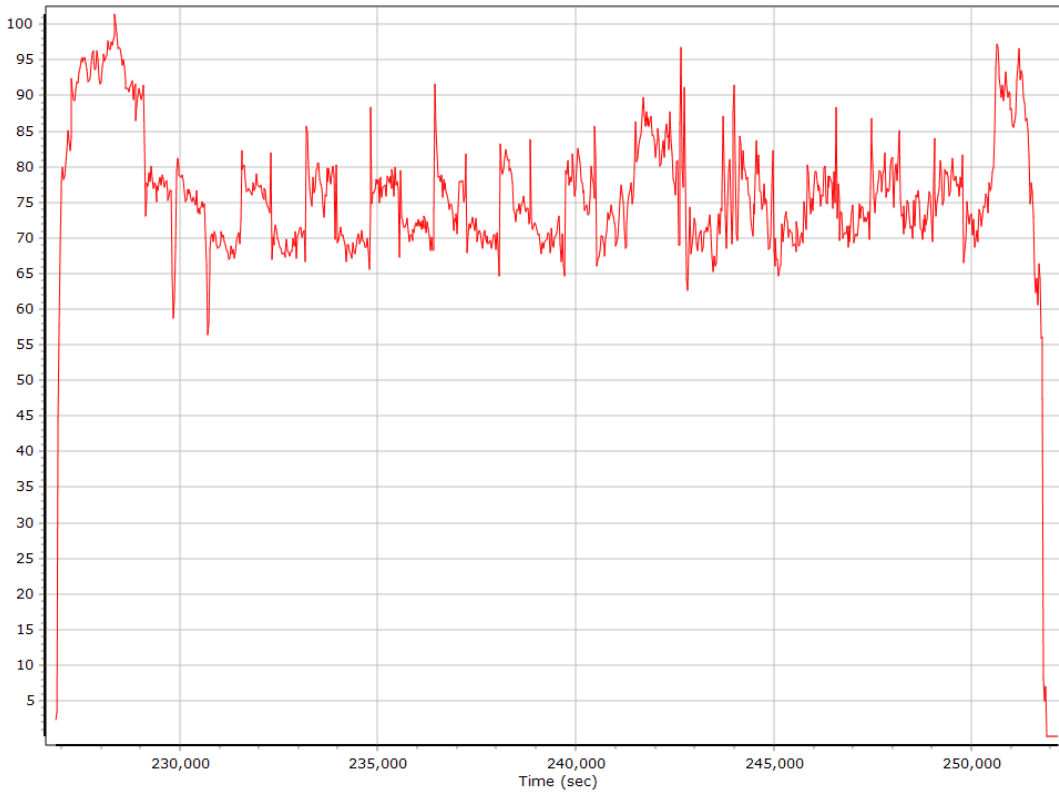
North/East Velocity



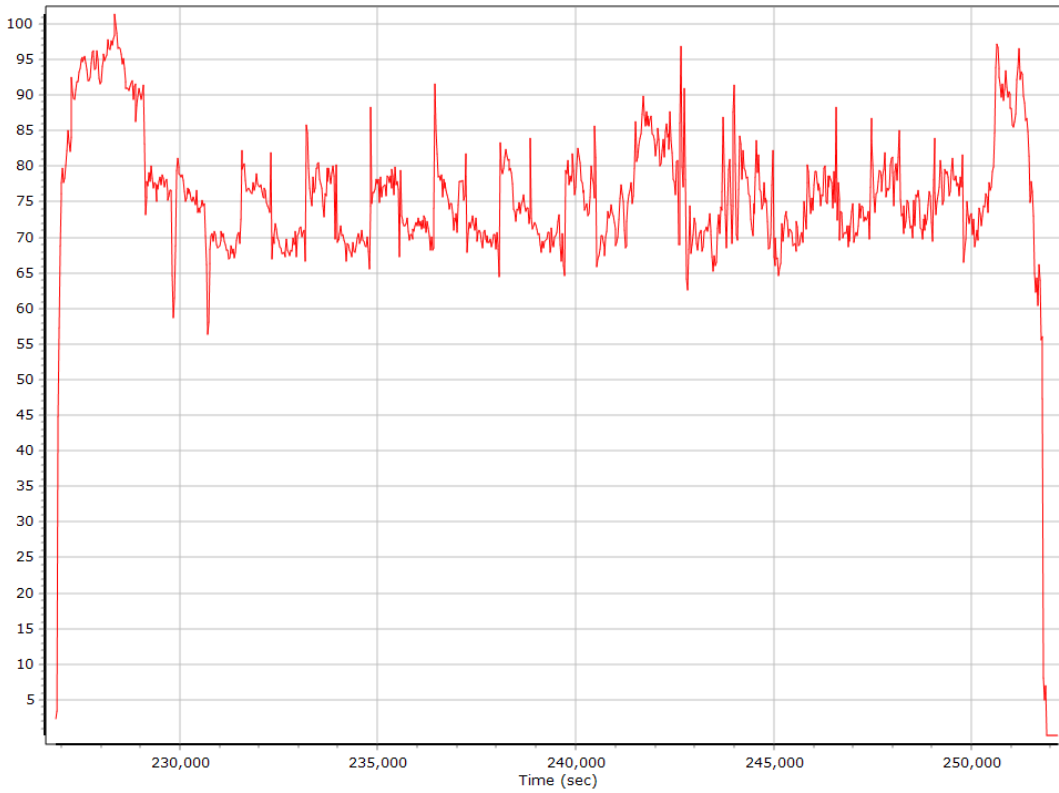
Down Velocity



Total Speed



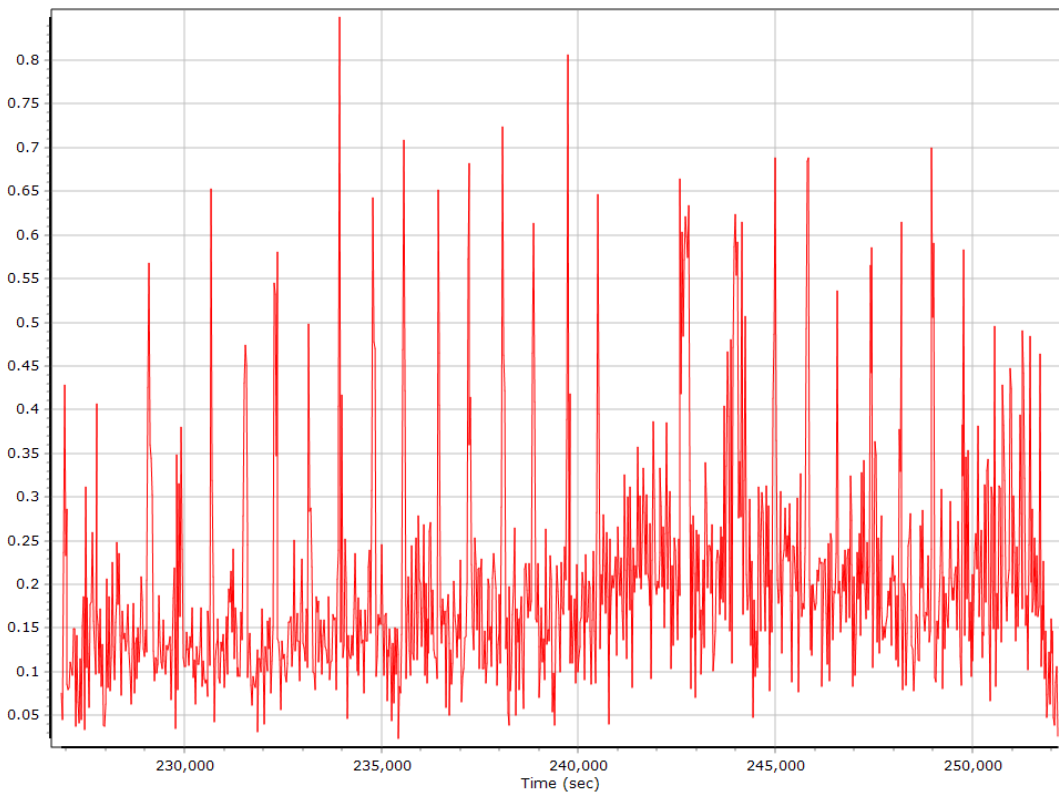
Ground Speed



Body Acceleration



Total Body Acceleration

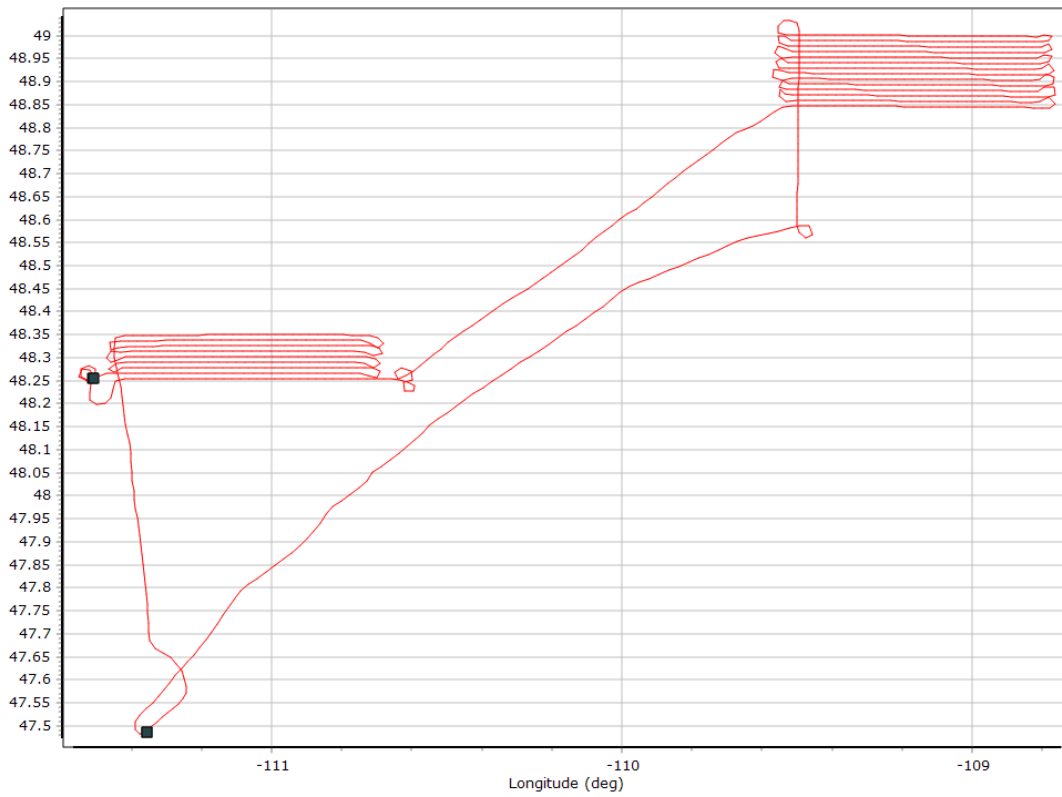


Body Angular Rate

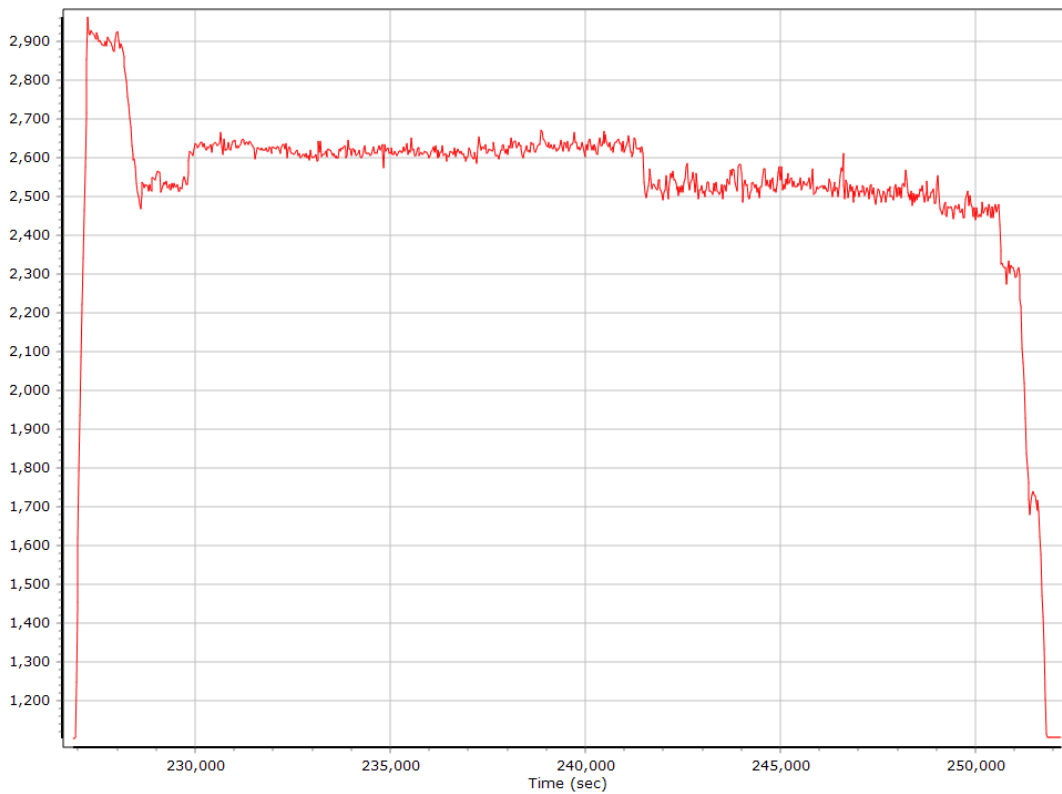


Forward Processed Trajectory Information

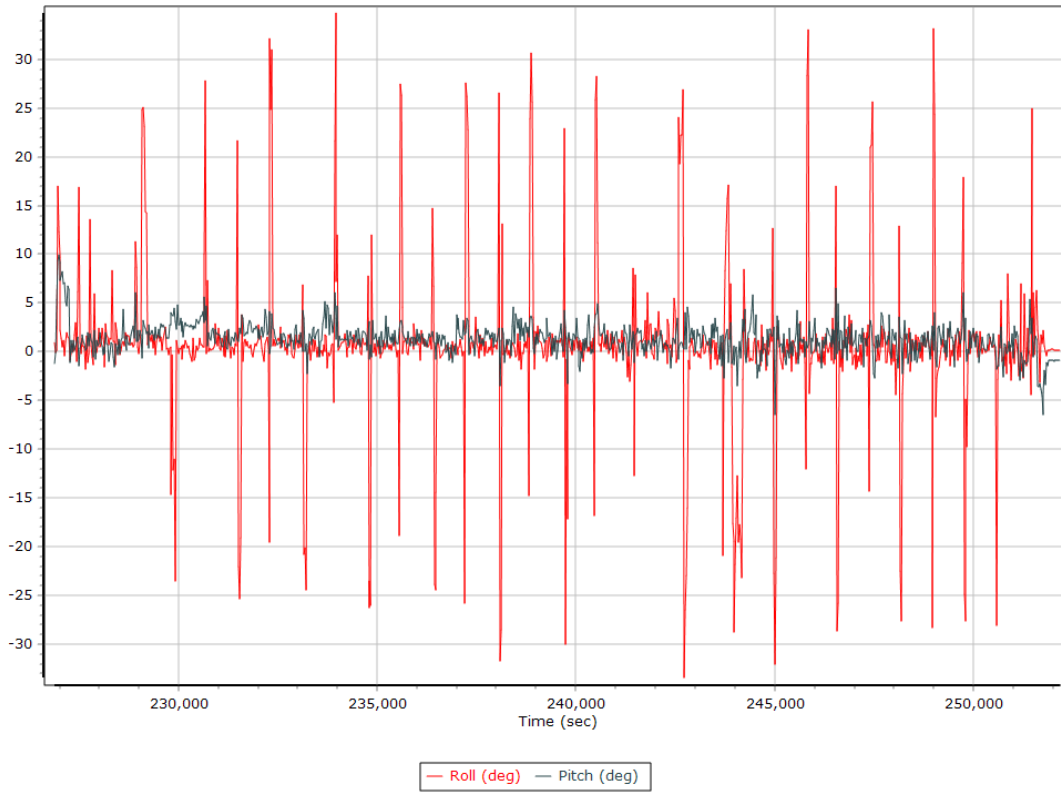
Top View



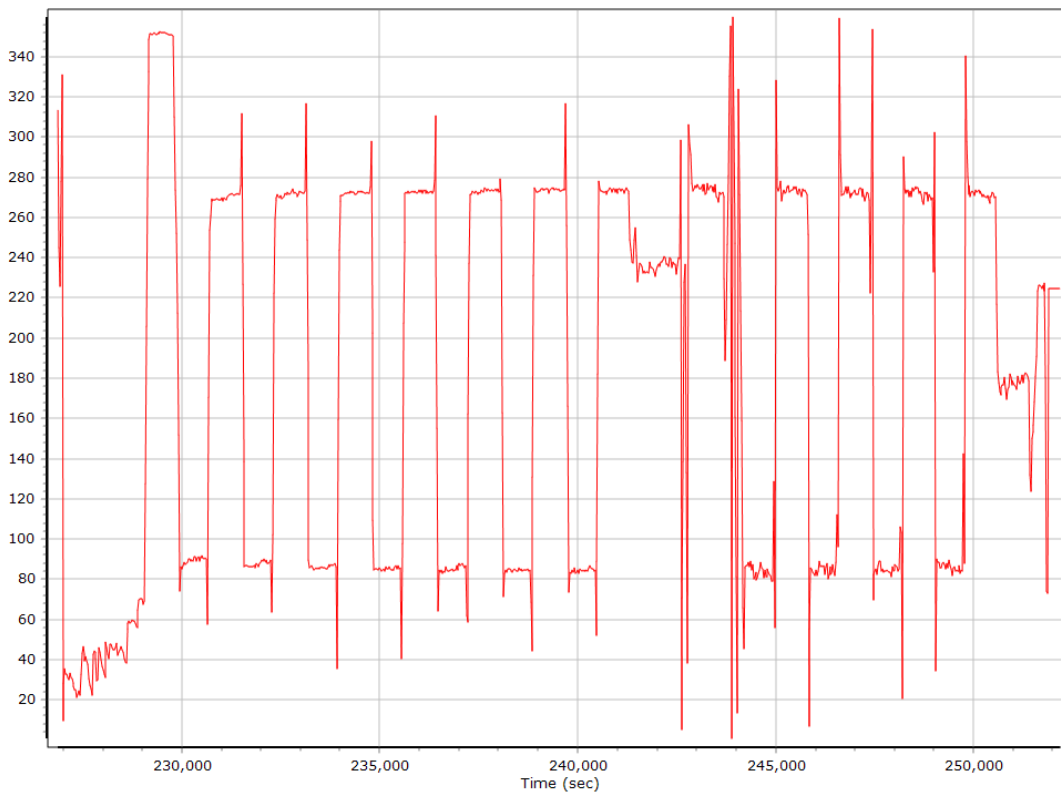
Altitude



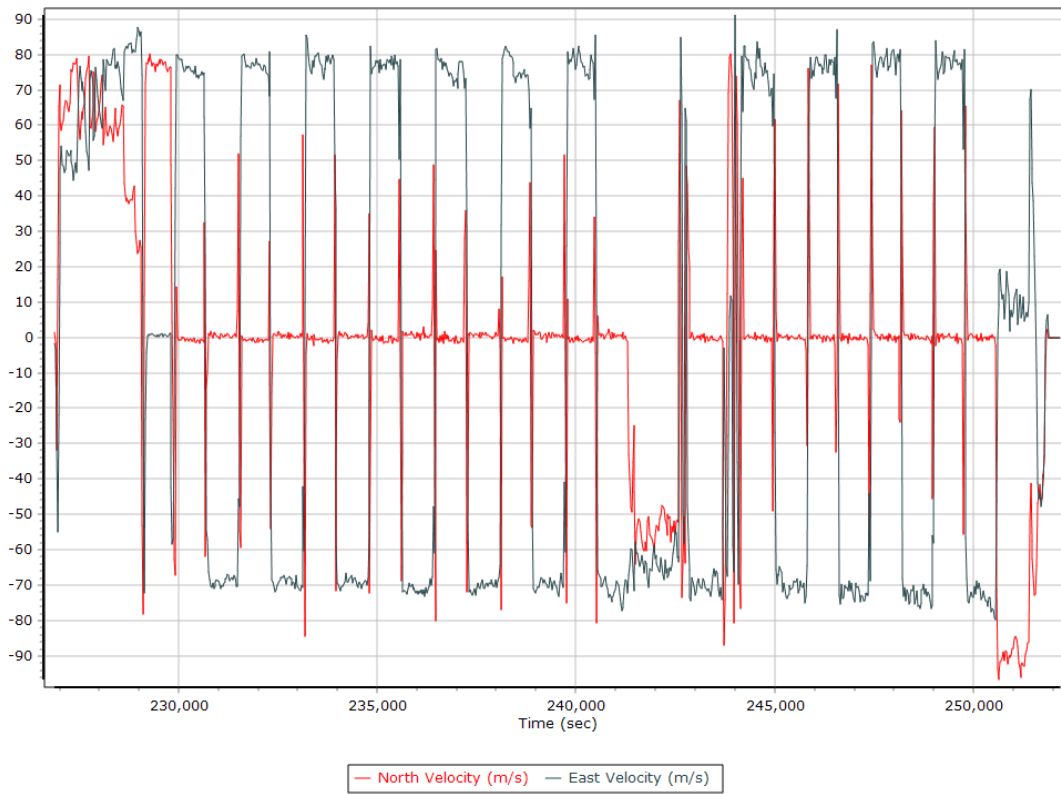
Roll/Pitch



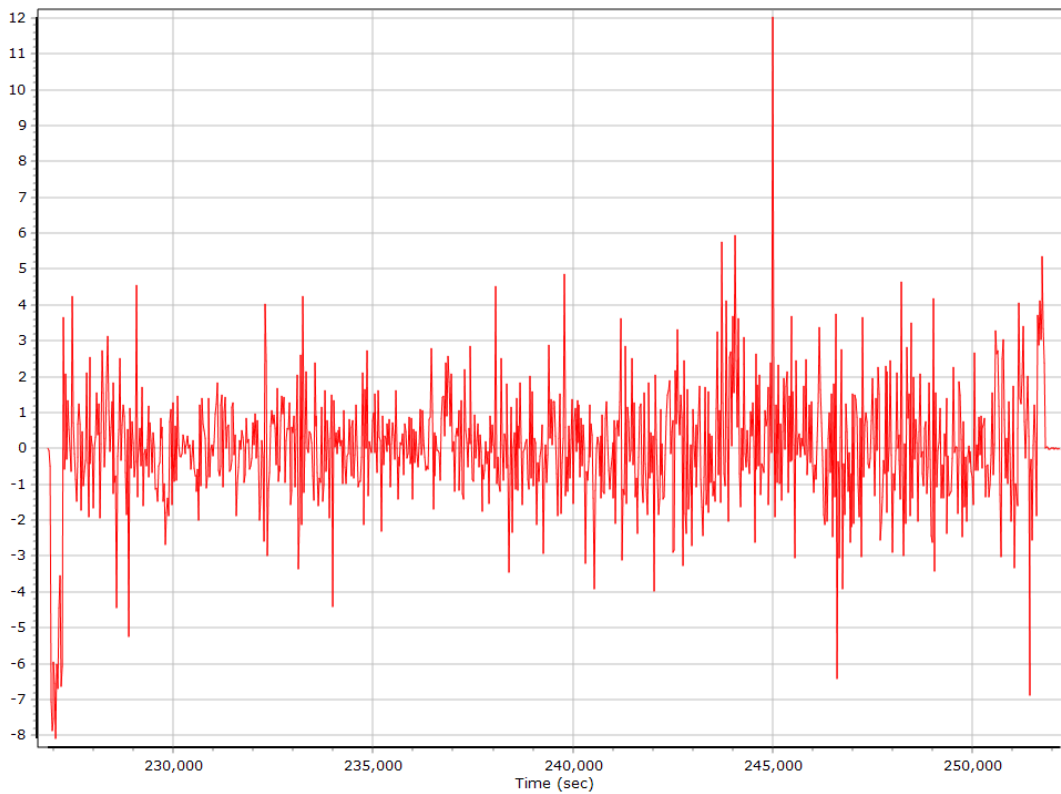
Heading



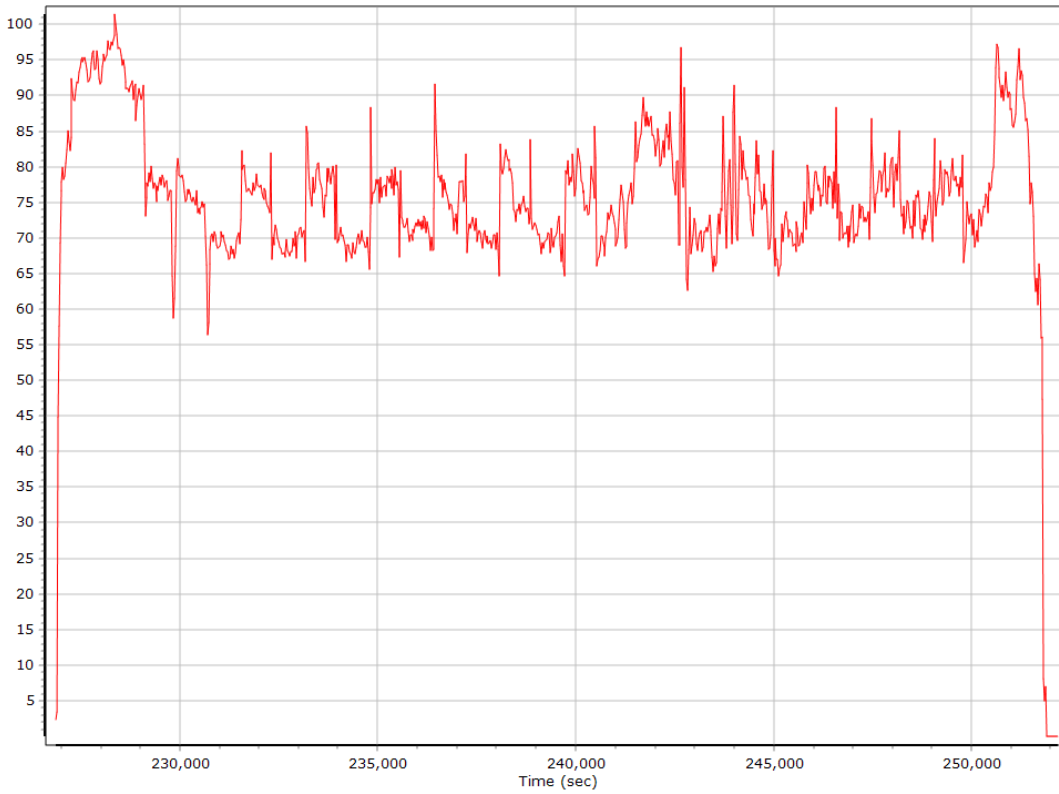
North/East Velocity



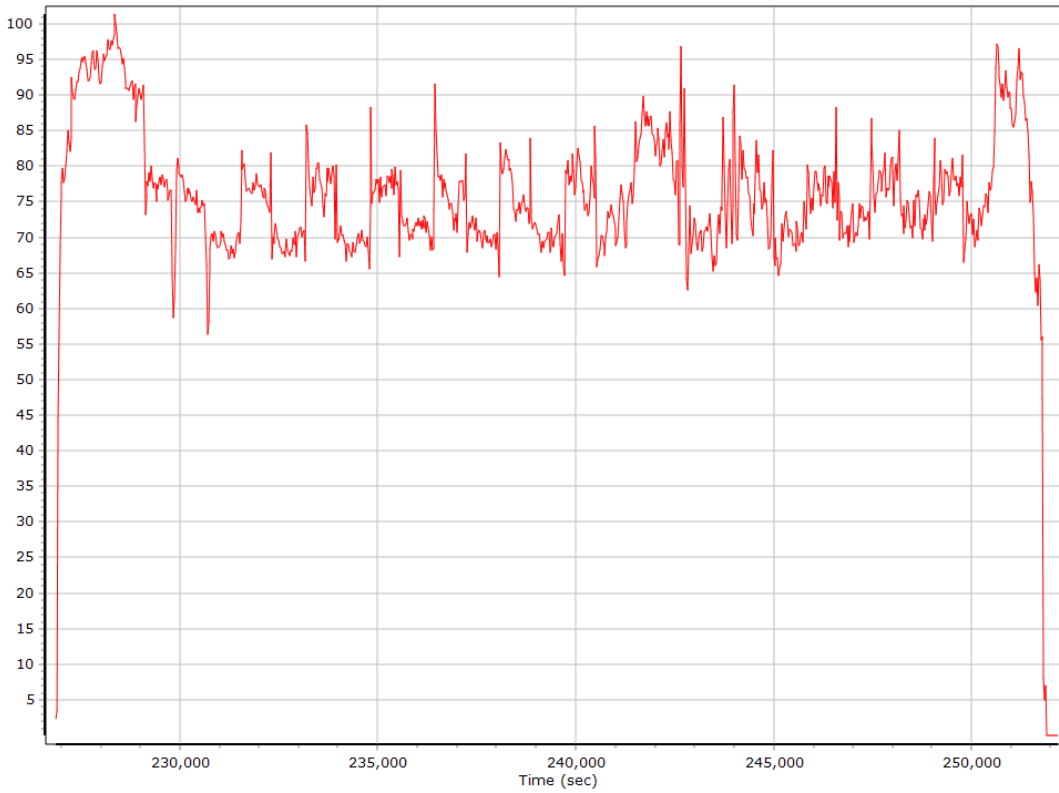
Down Velocity



Total Speed



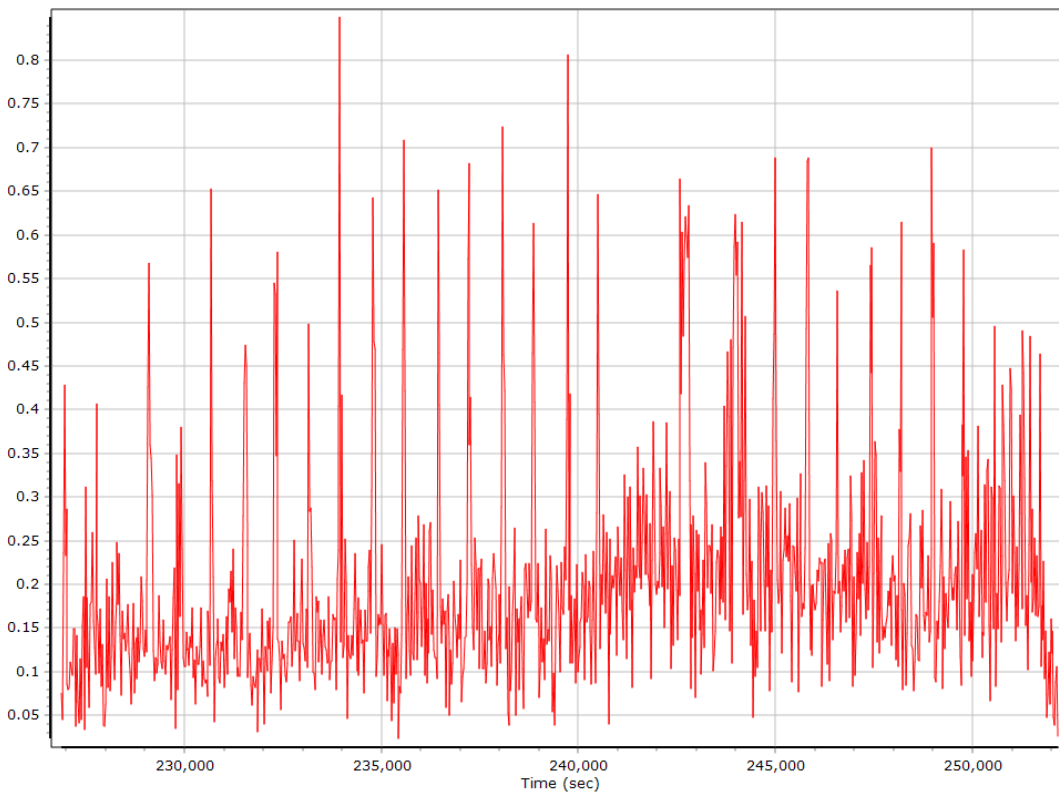
Ground Speed



Body Acceleration



Total Body Acceleration



Body Angular Rate



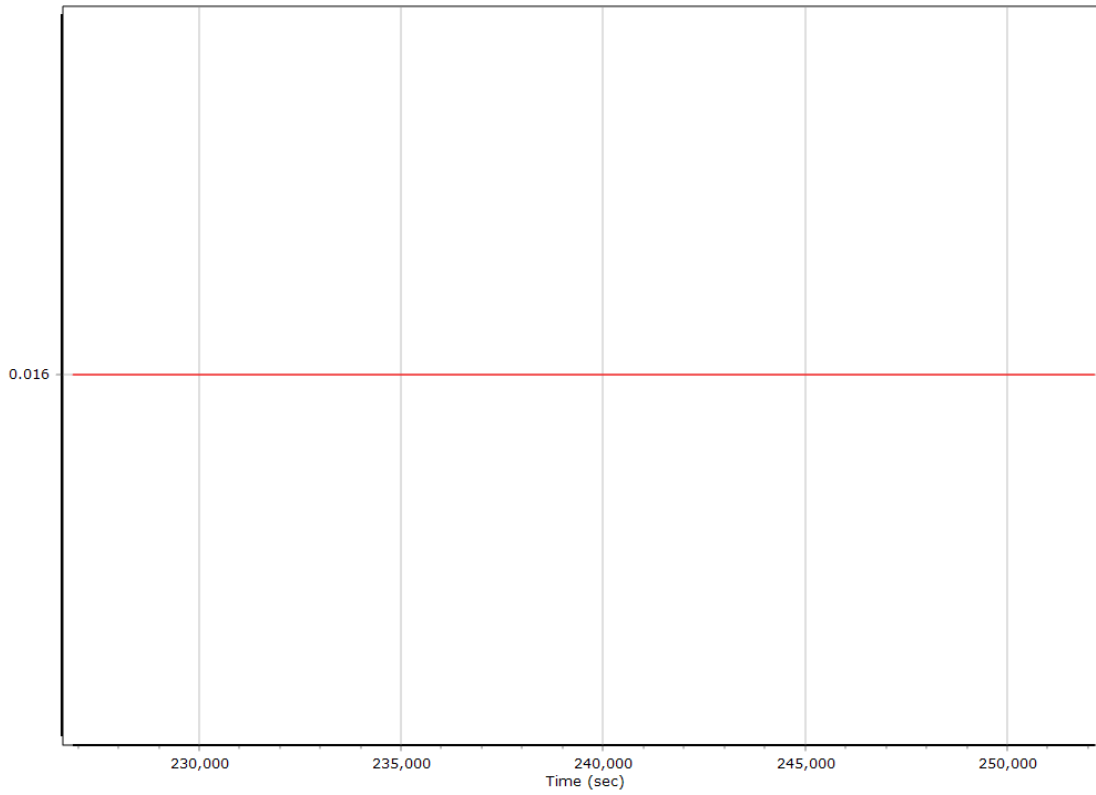
GNSS-Inertial Processor Configuration

Processing mode	IN-Fusion Trimble RTX Nav		
Stabilized mount	False		
Processing start time	226270.000 (09/21/2021 14:51:10)		
Processing end time	252199.000 (09/21/2021 22:03:19)		
Initial attitude source	Real-Time VNAV/RNAV Attitude		
IMU Sensor Context	Processing with Onboard IMU		
Reference to IMU lever arm (m)	0.000	0.000	0.000
Reference to IMU mounting angles (deg)	0.000	0.000	0.000
Reference to Primary GNSS lever arm (m)	0.016	0.063	-0.958
Reference to Primary GNSS lever arm std dev (m)	0.030	0.030	0.030
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

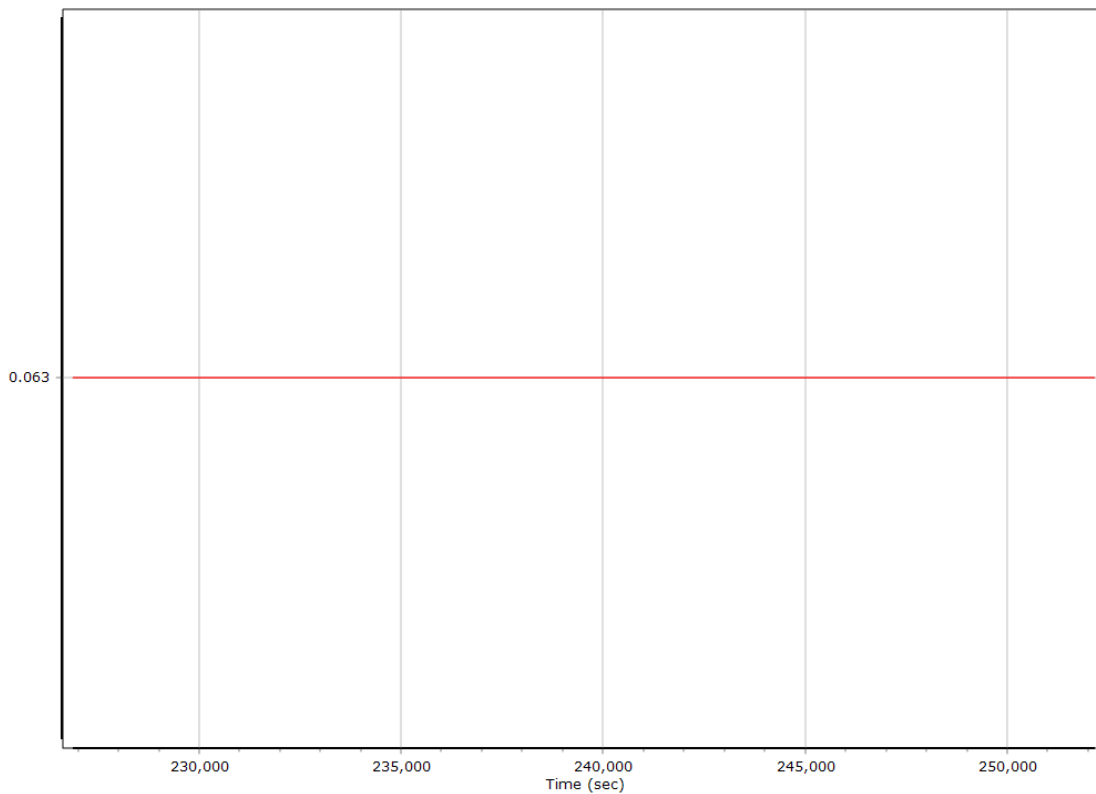
Calibrated Installation Parameters

Reference-Primary GNSS Lever Arm (m)

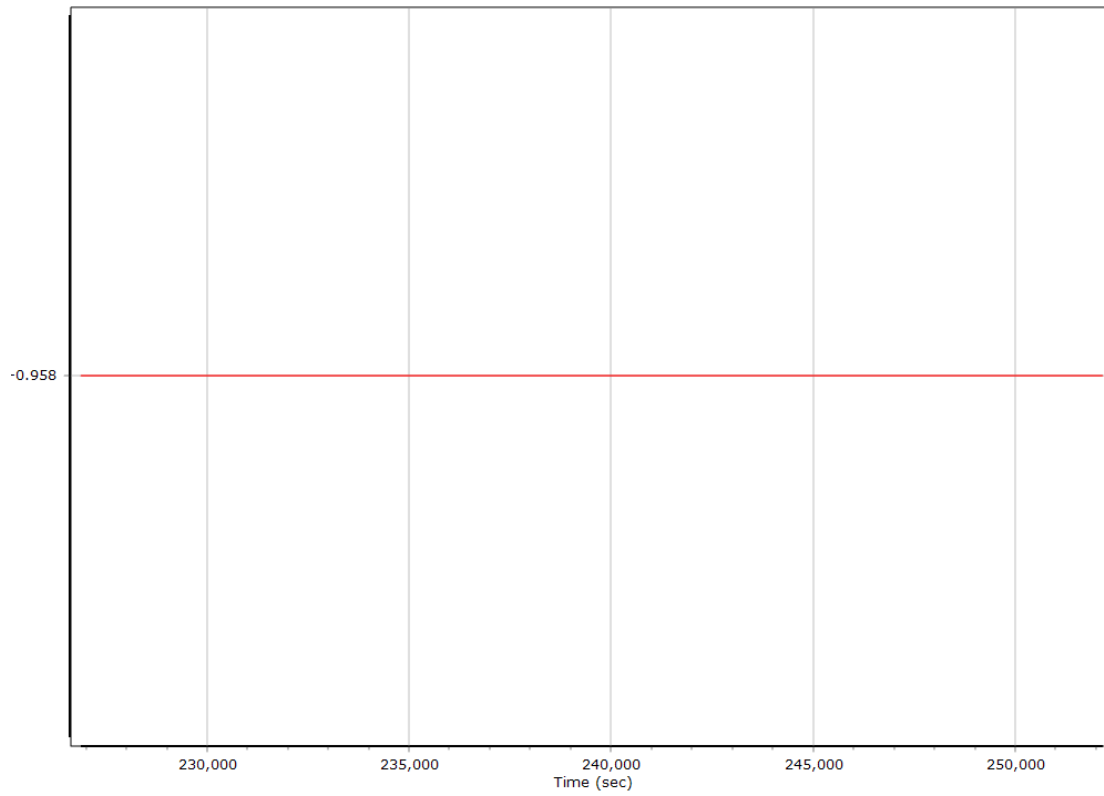
X Reference-Primary GNSS Lever Arm (m)



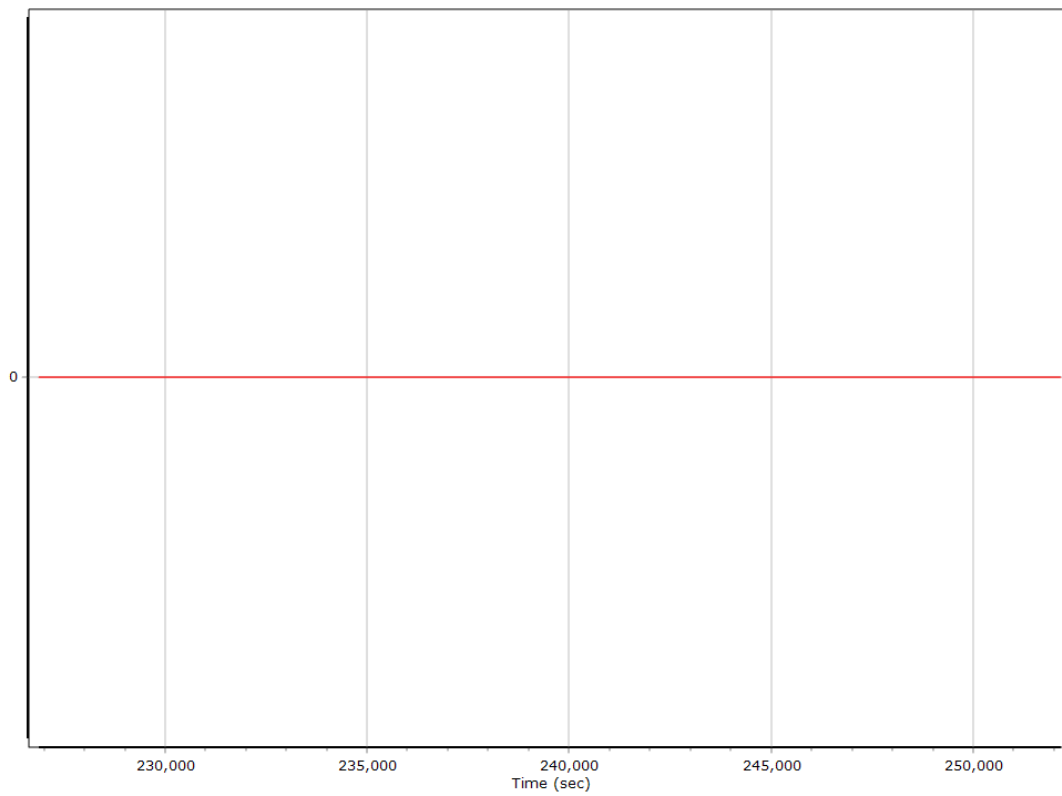
Y Reference-Primary GNSS Lever Arm (m)



Z Reference-Primary GNSS Lever Arm (m)



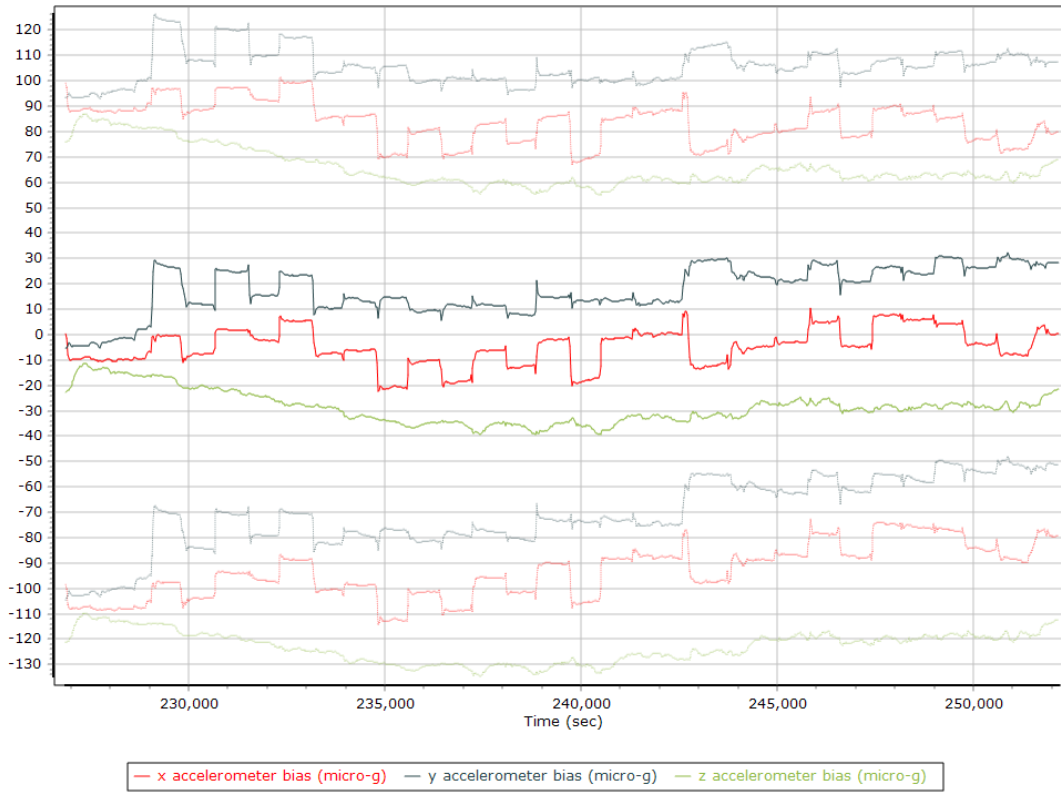
Reference-Primary GNSS Lever Arm Figure of Merit



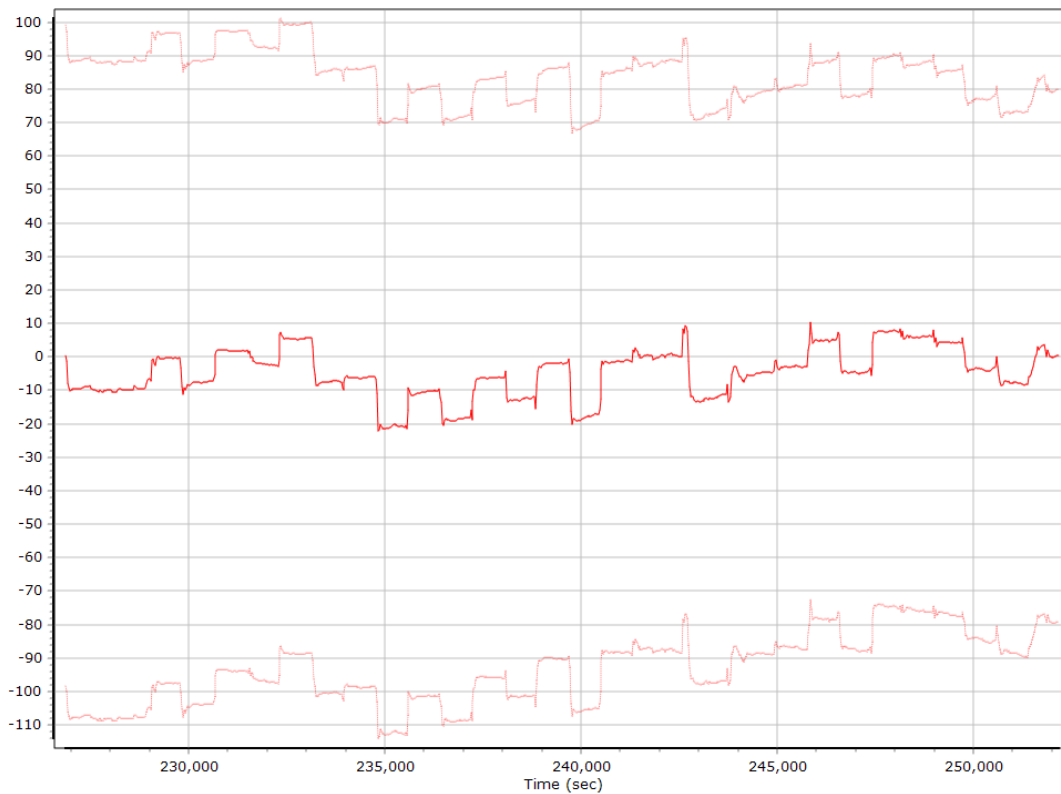
IN-Fusion QC

Forward Processed Estimated Errors, Reference Frame

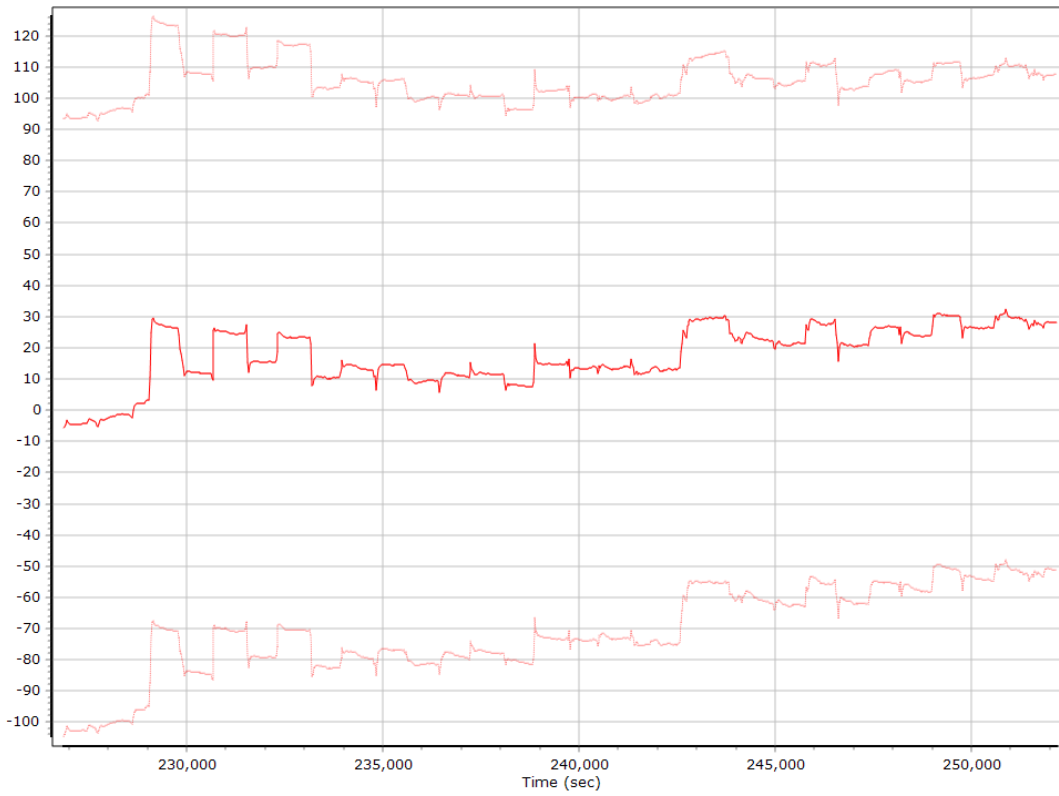
Accelerometer Bias (micro-g)



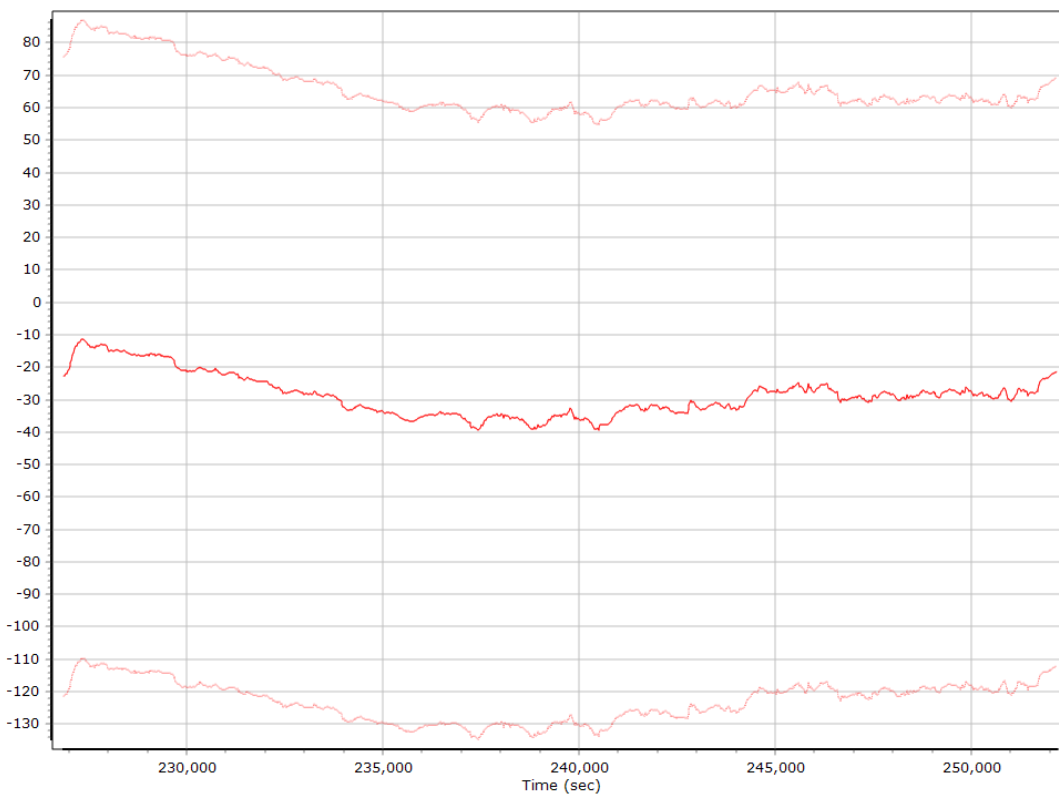
X Accelerometer Bias (micro-g)



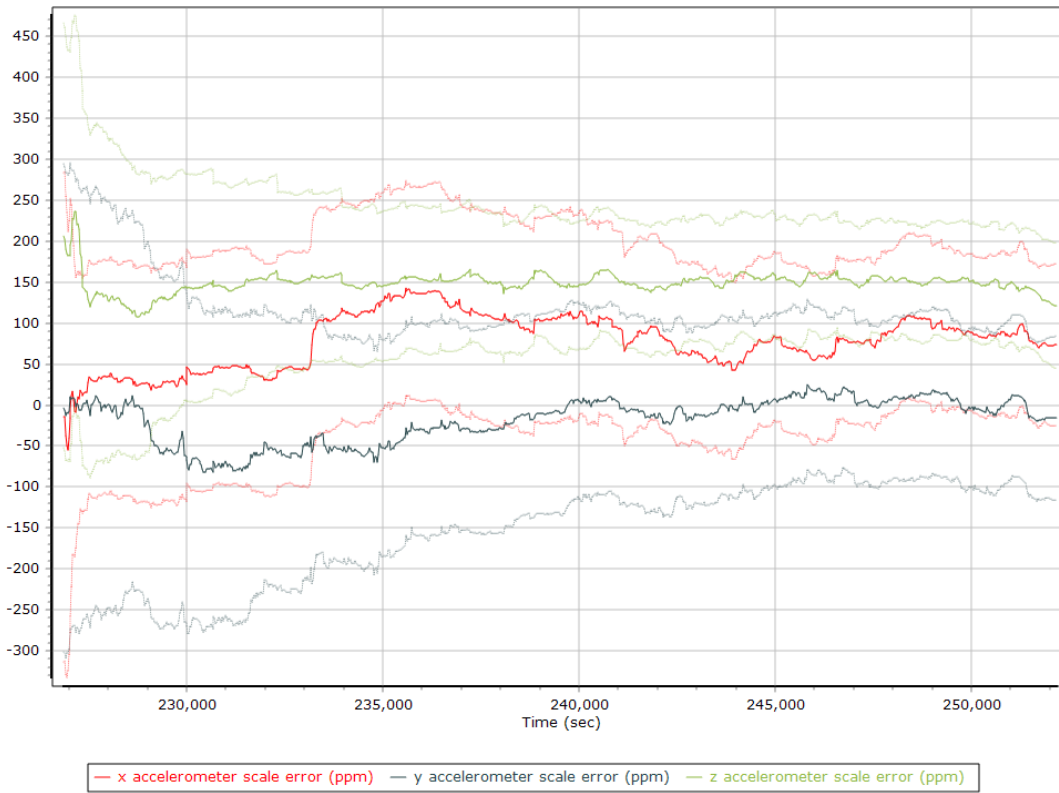
Y Accelerometer Bias (micro-g)



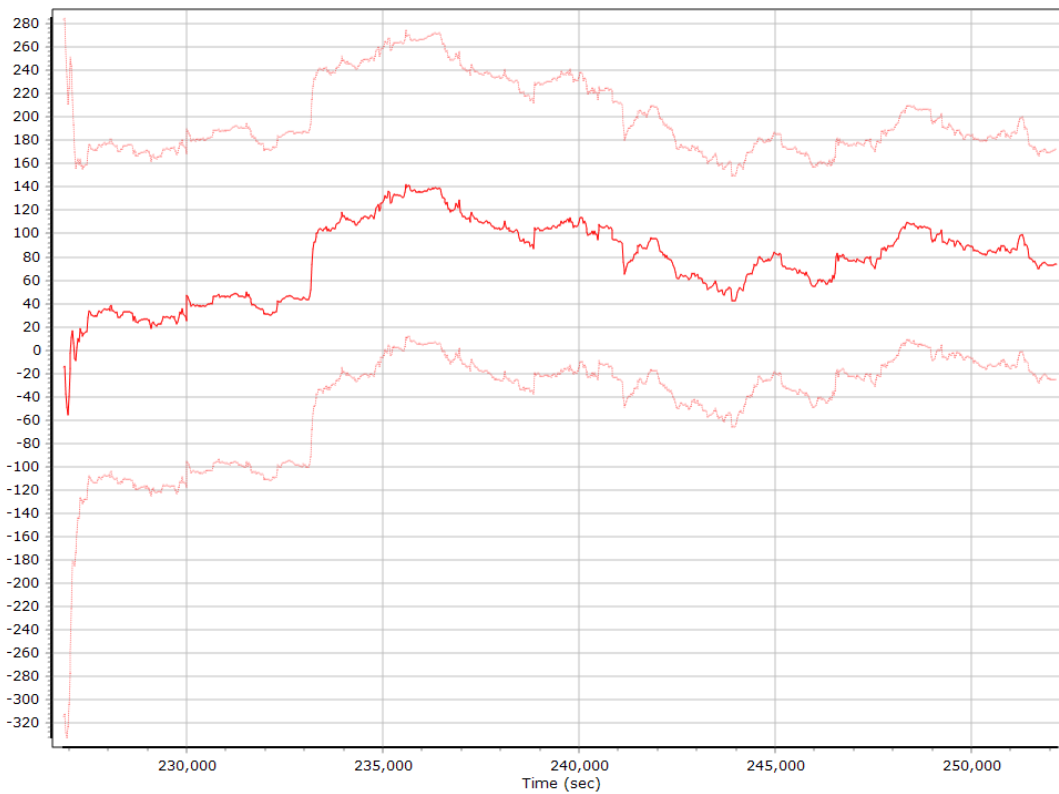
Z Accelerometer Bias (micro-g)



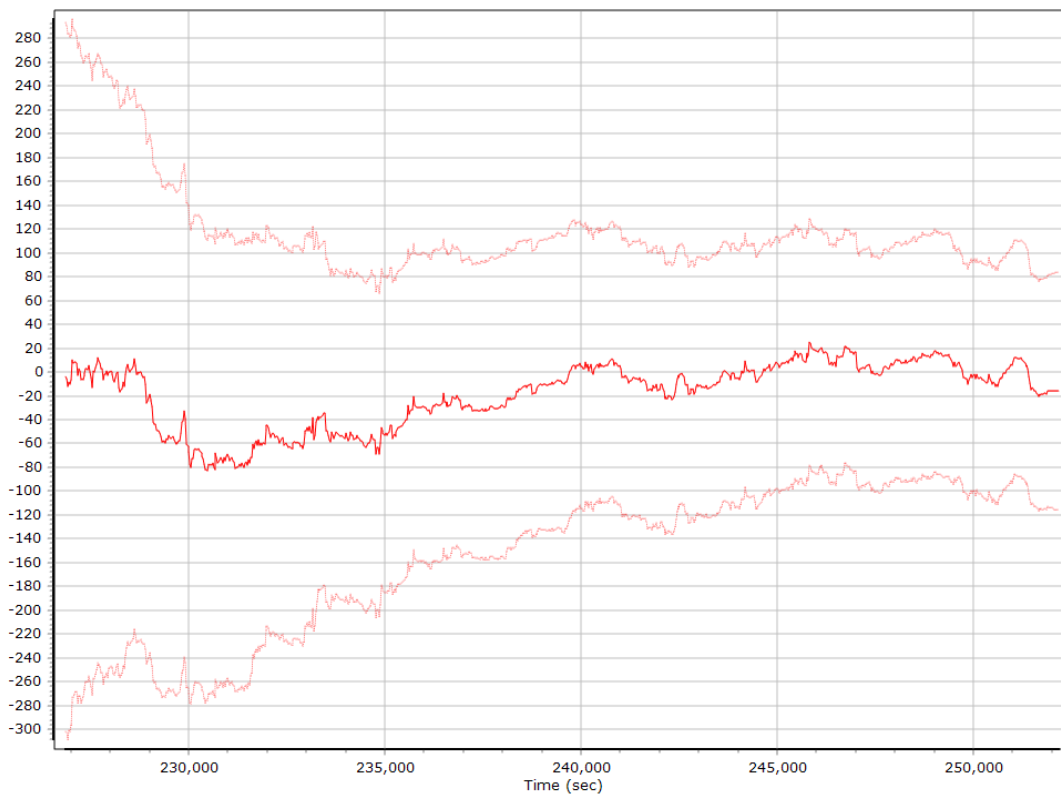
Accelerometer Scale Error (ppm)



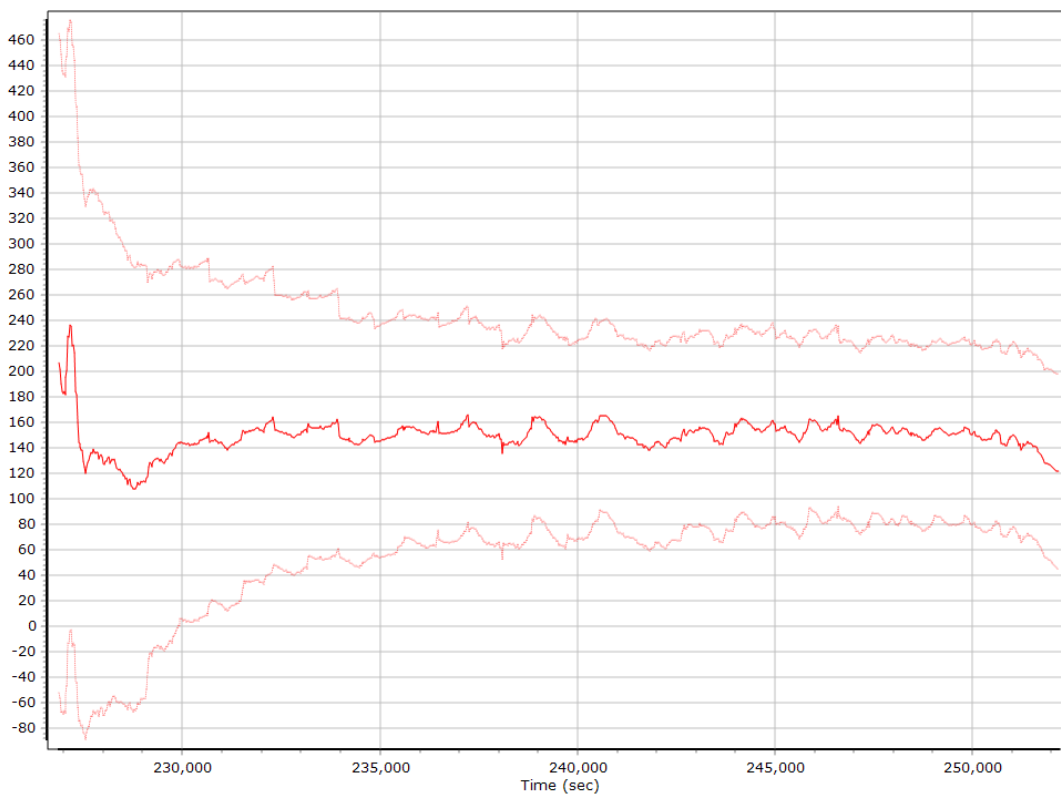
X Accelerometer Scale Error (ppm)



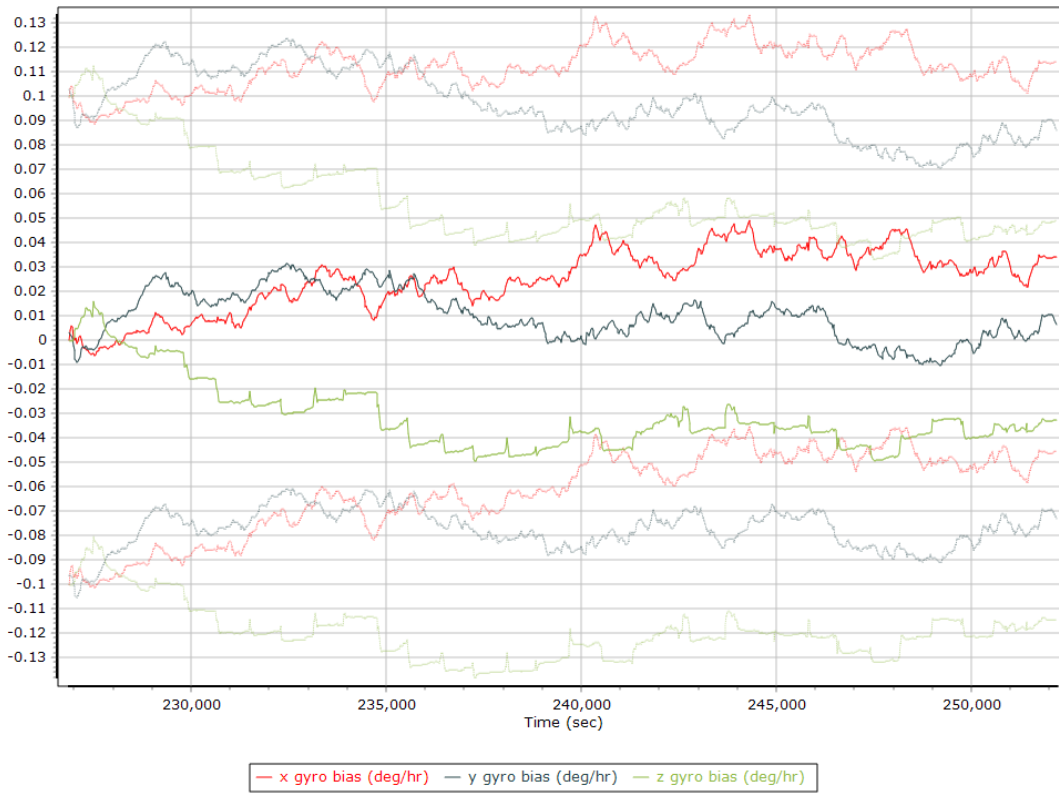
Y Accelerometer Scale Error (ppm)



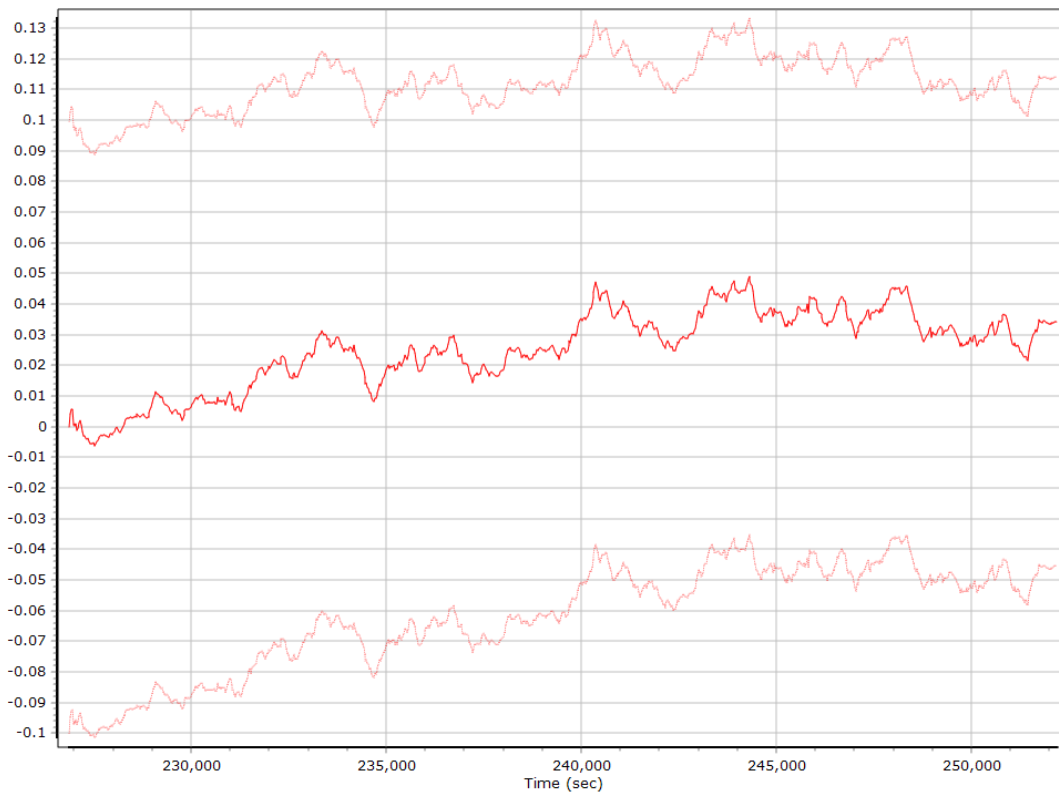
Z Accelerometer Scale Error (ppm)



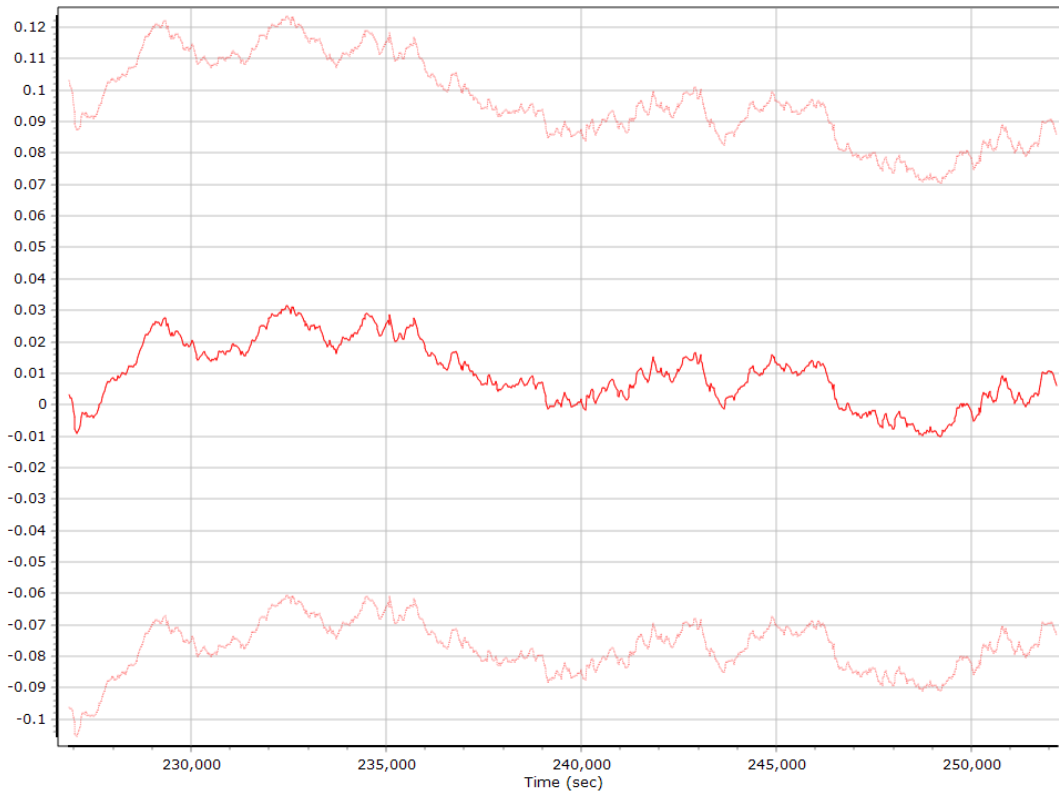
Gyro Bias (deg/h)



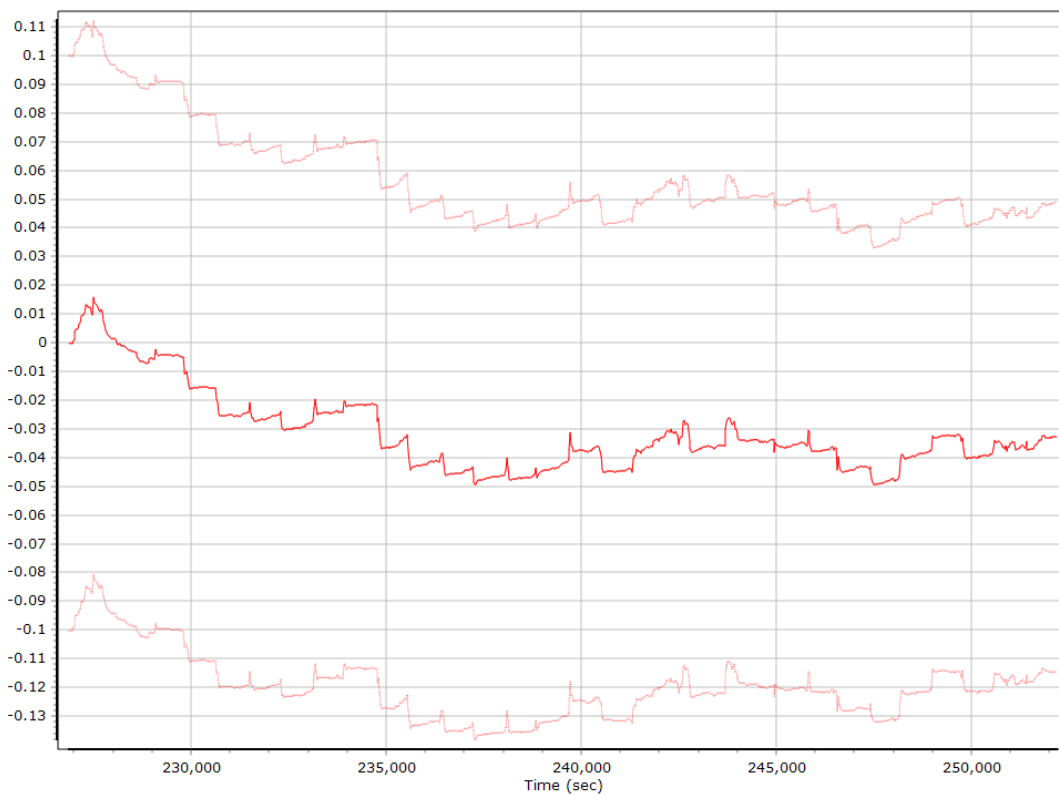
X Gyro Bias (deg/h)



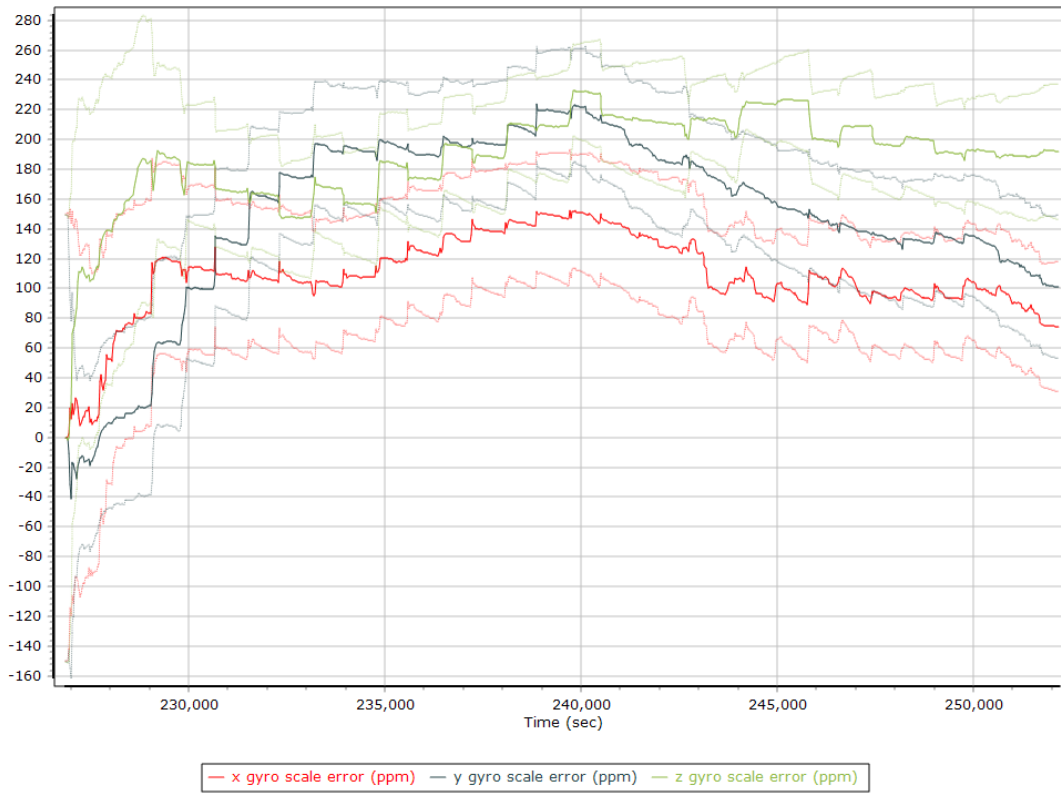
Y Gyro Bias (deg/h)



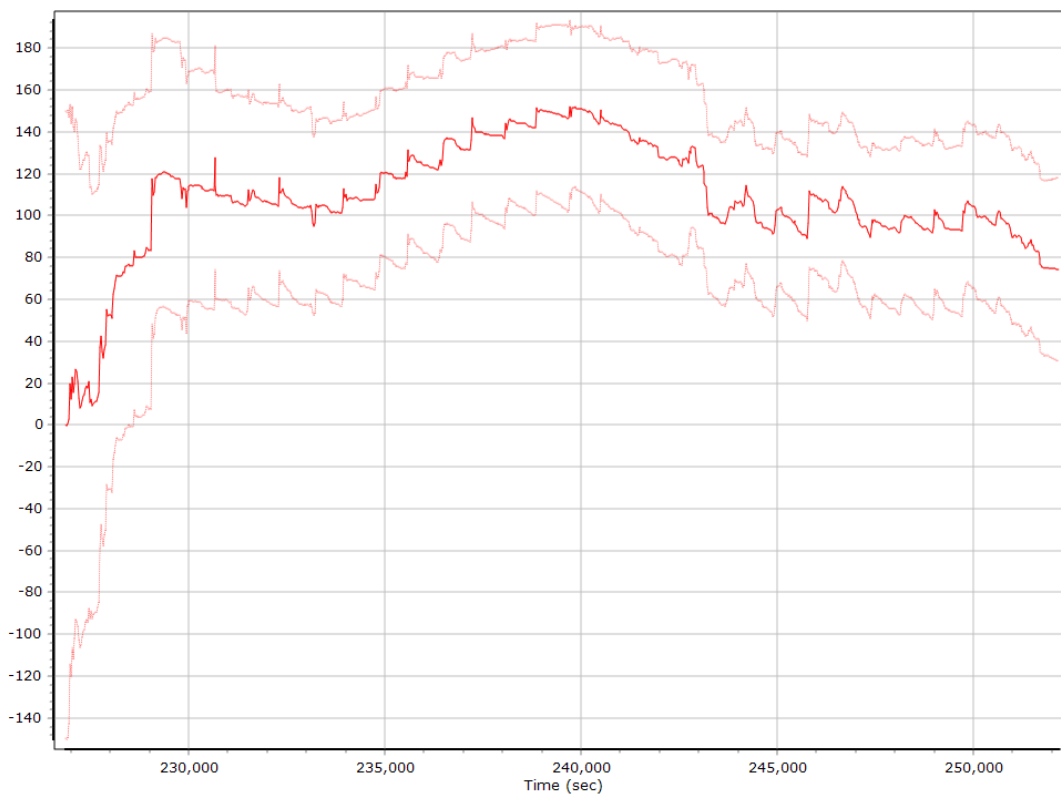
Z Gyro Bias (deg/h)



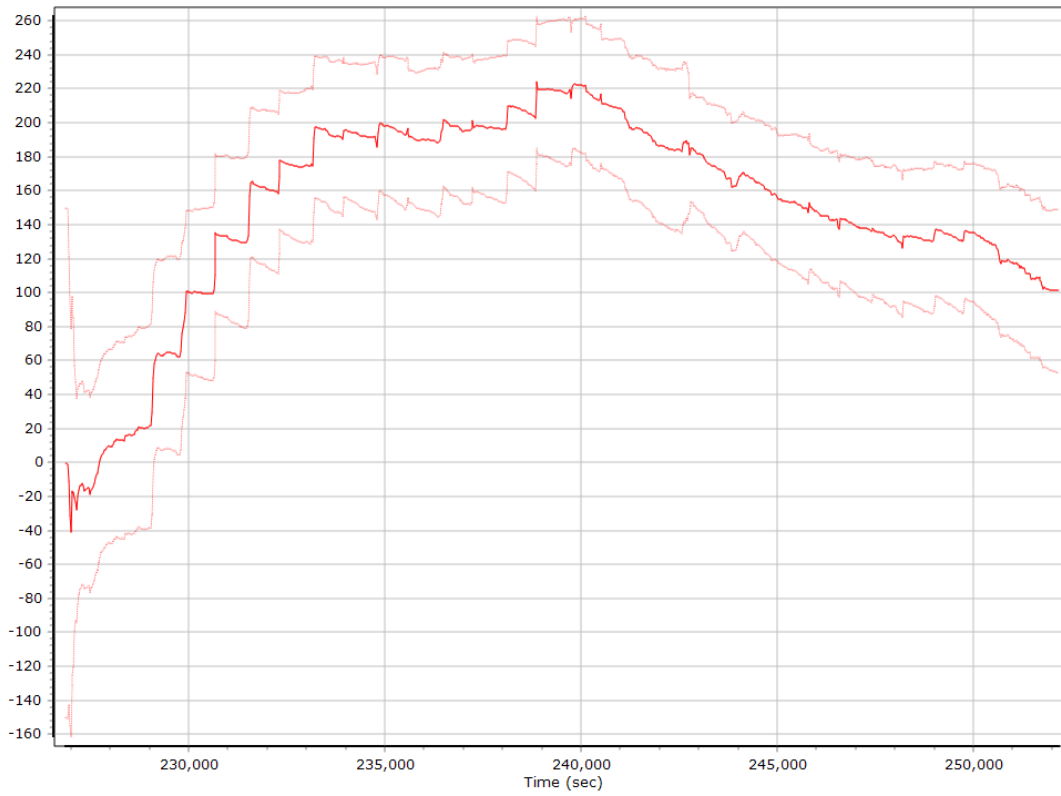
Gyro Scale Error (ppm)



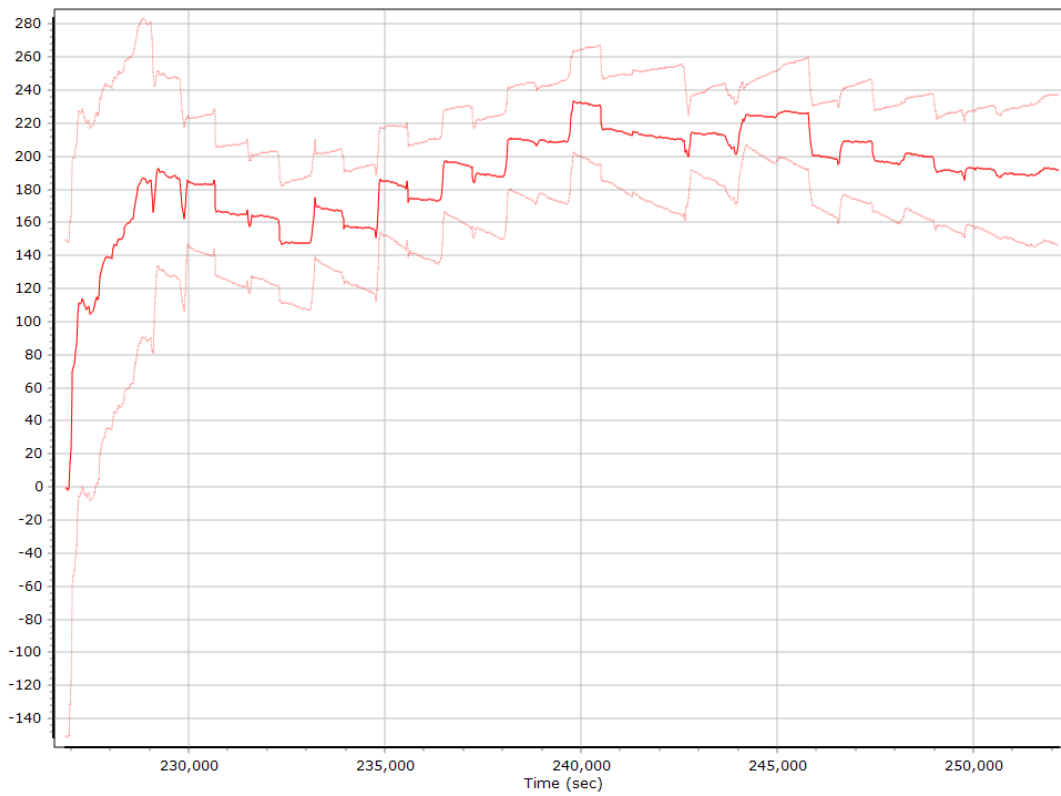
X Gyro Scale Error (ppm)



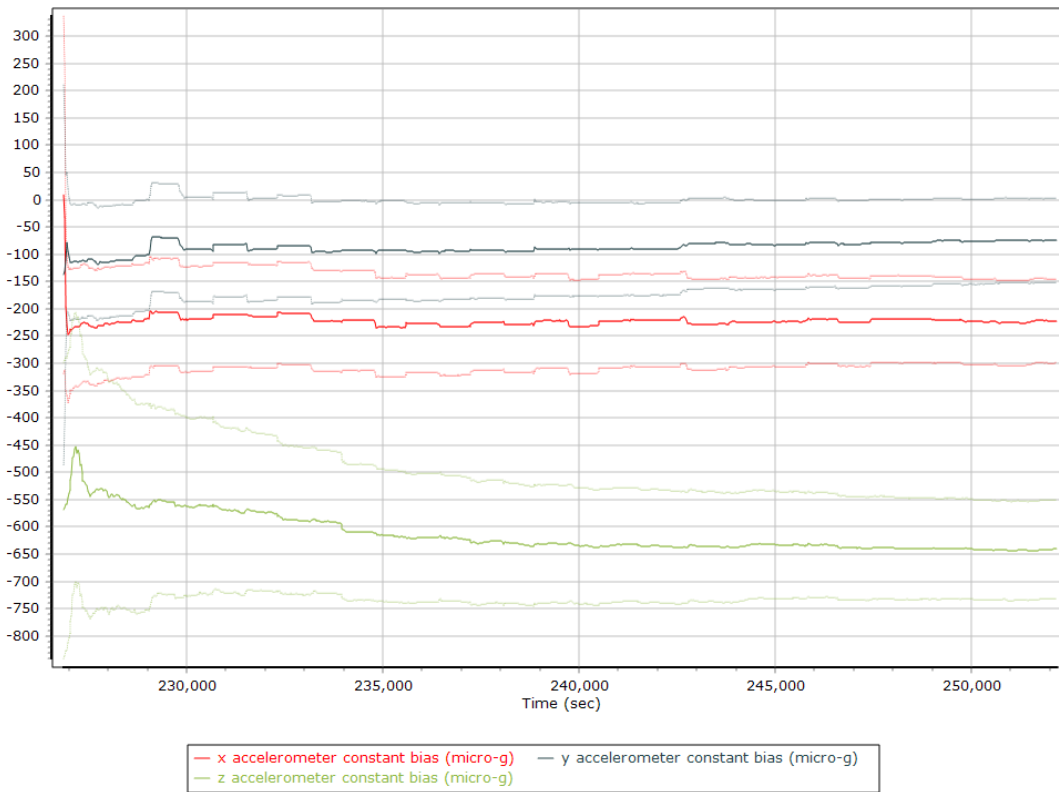
Y Gyro Scale Error (ppm)



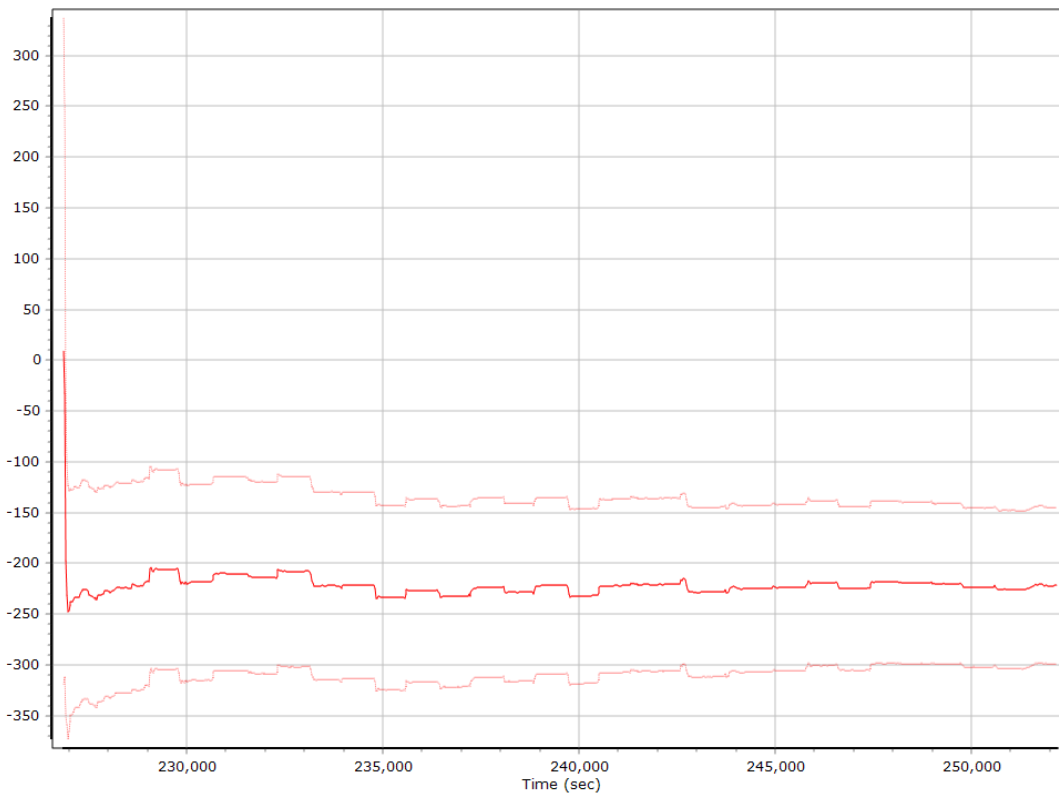
Z Gyro Scale Error (ppm)



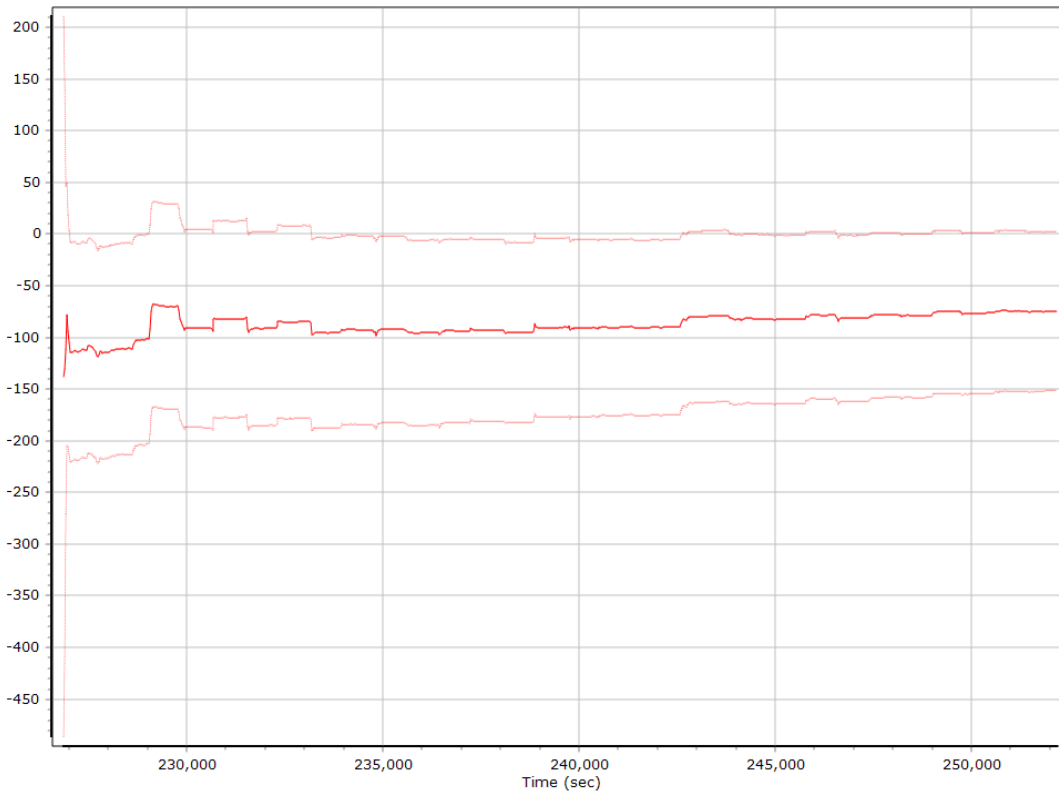
Forward Processed Estimated Constant Errors, Reference Frame Accelerometer Bias (micro-g)



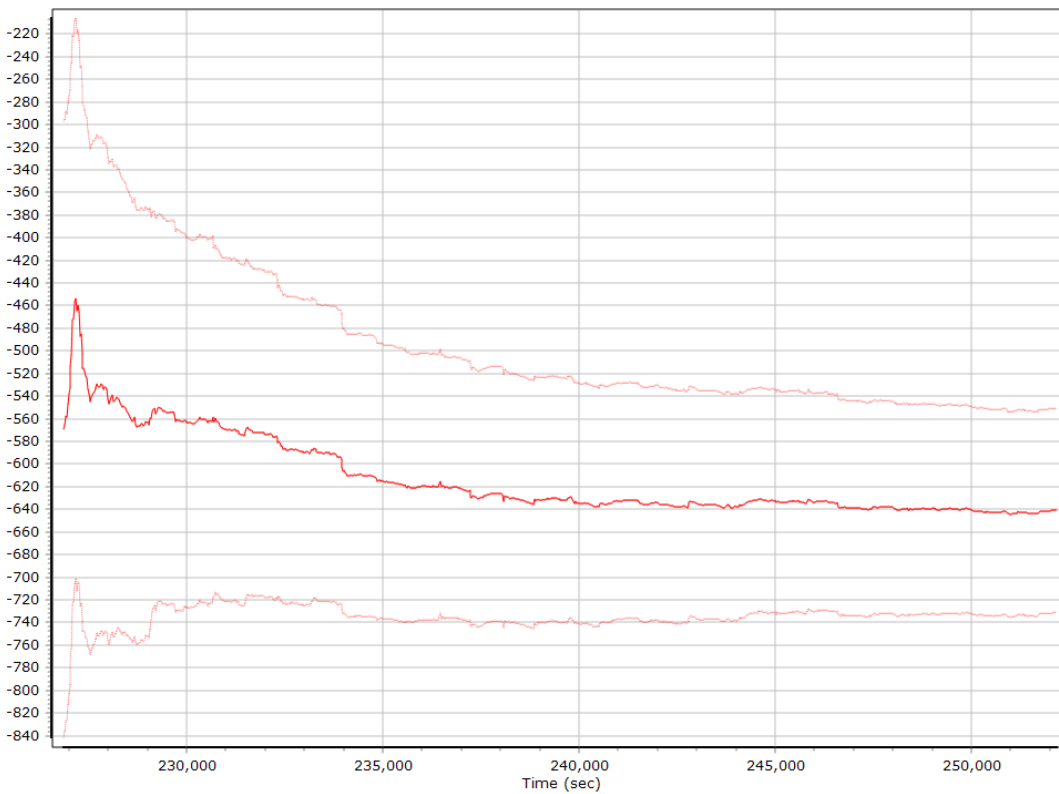
X Accelerometer Bias (micro-g)



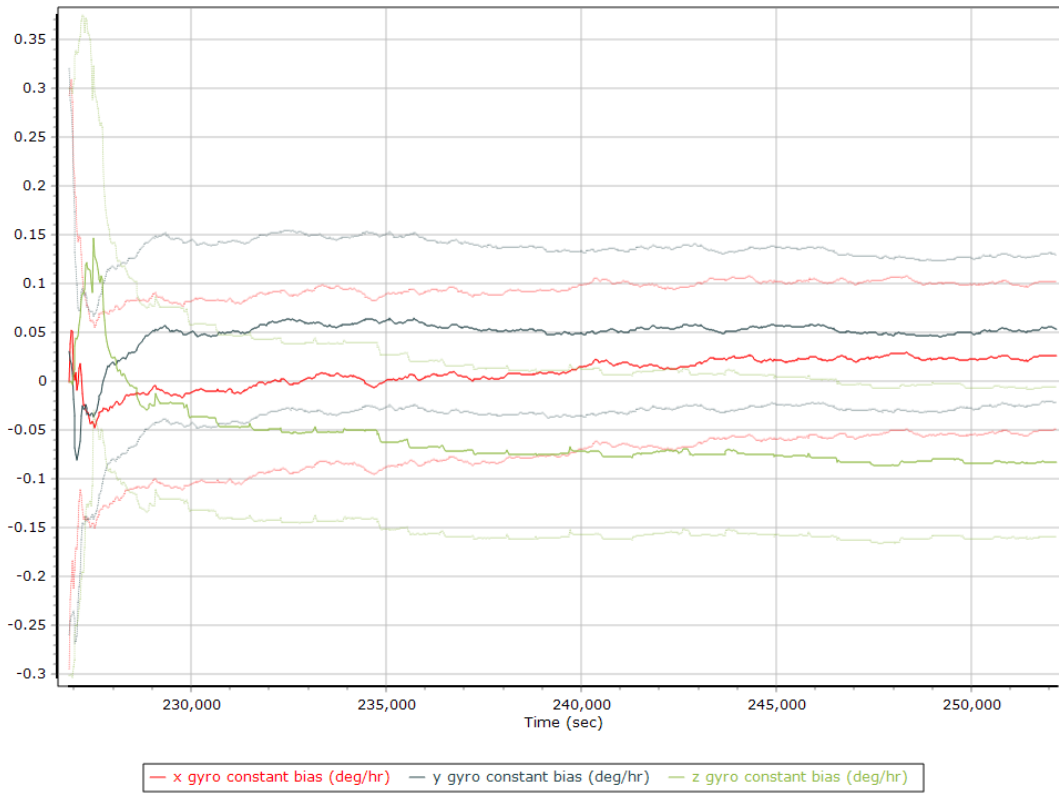
Y Accelerometer Bias (micro-g)



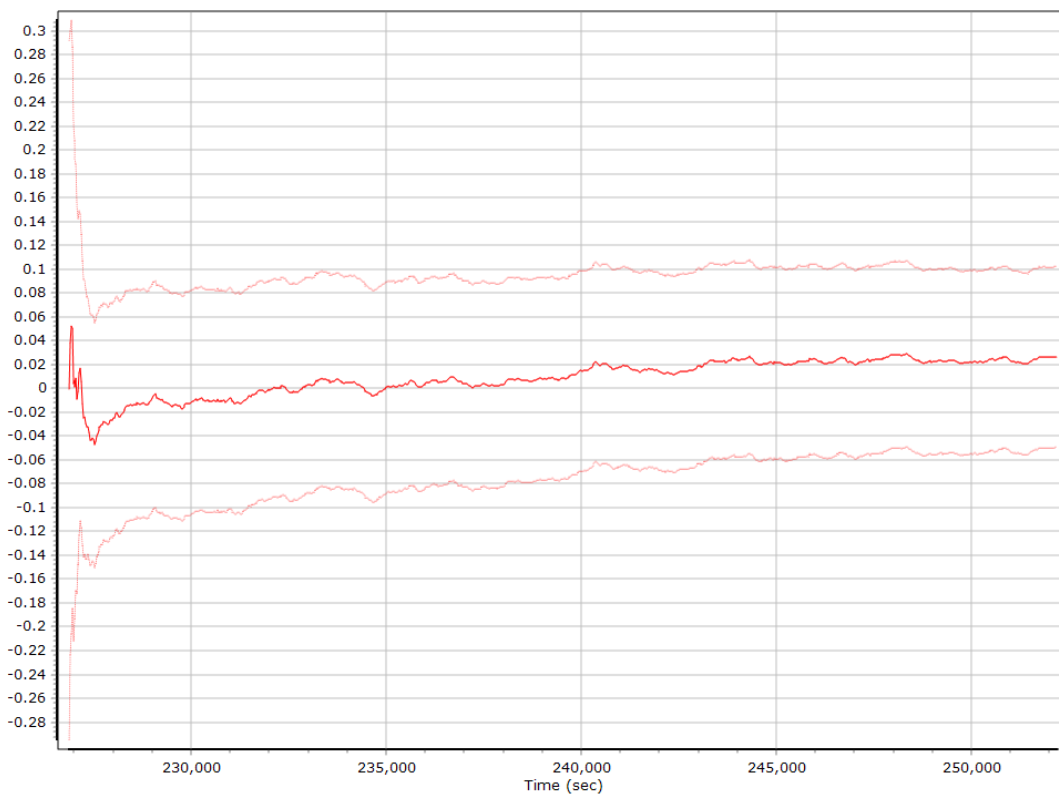
Z Accelerometer Bias (micro-g)



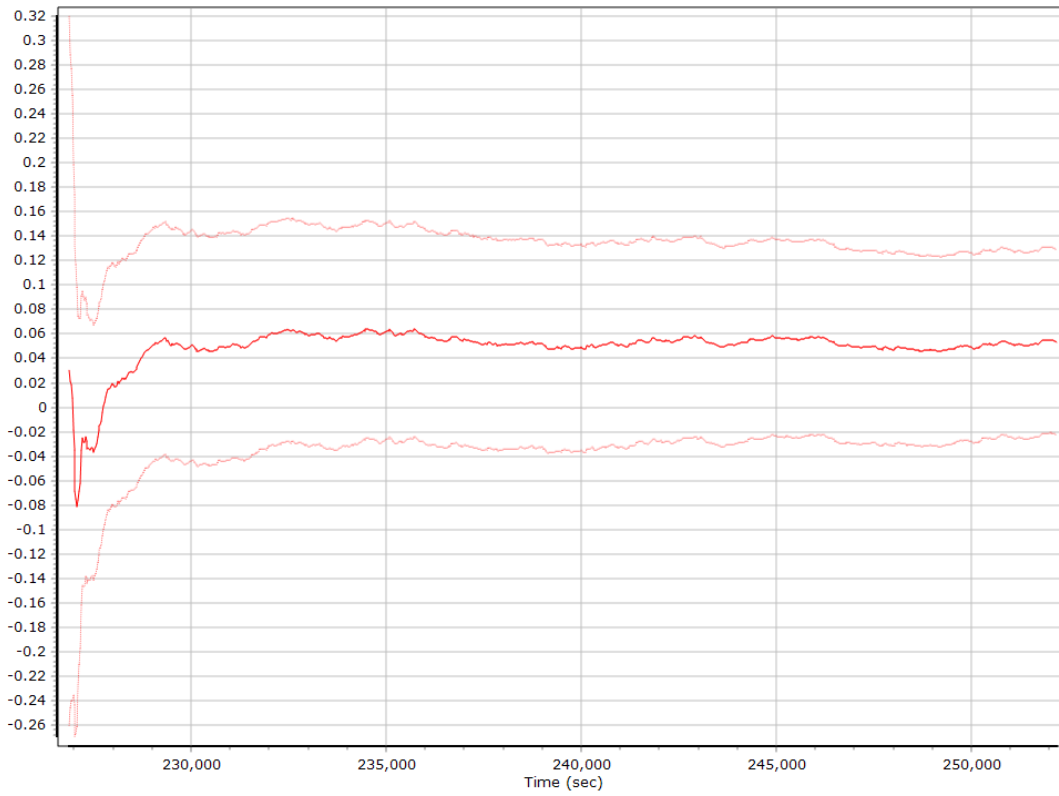
Gyro Bias (deg/h)



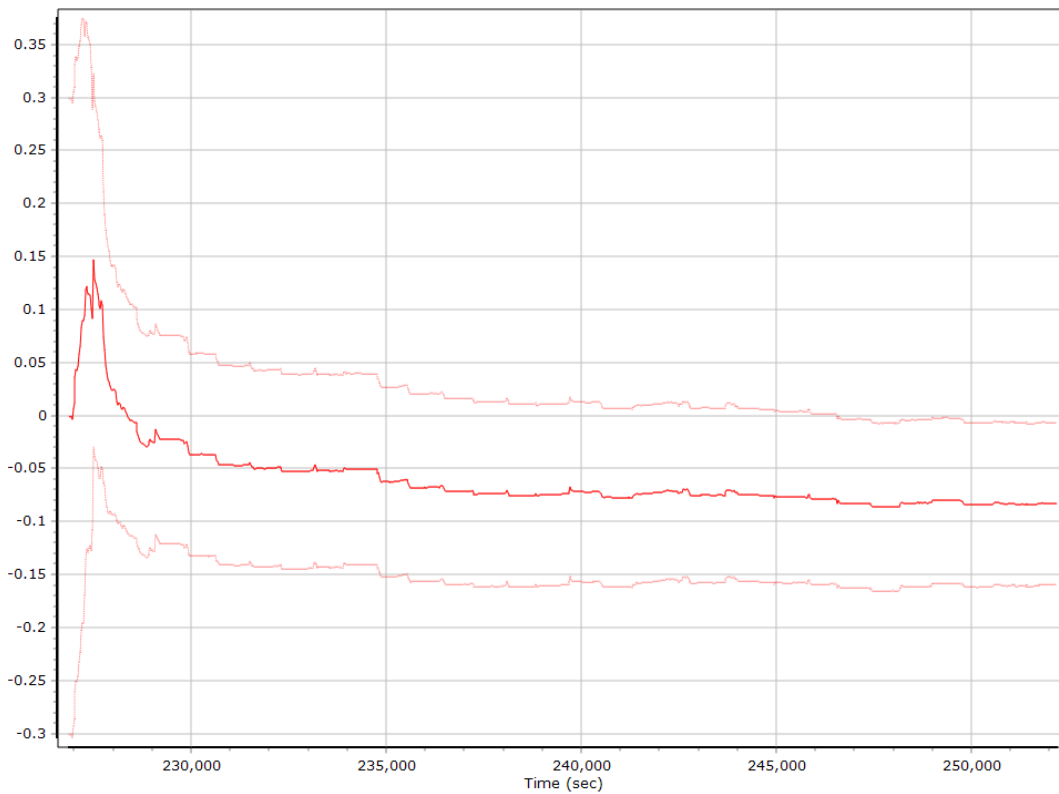
X Gyro Bias (deg/h)



Y Gyro Bias (deg/h)

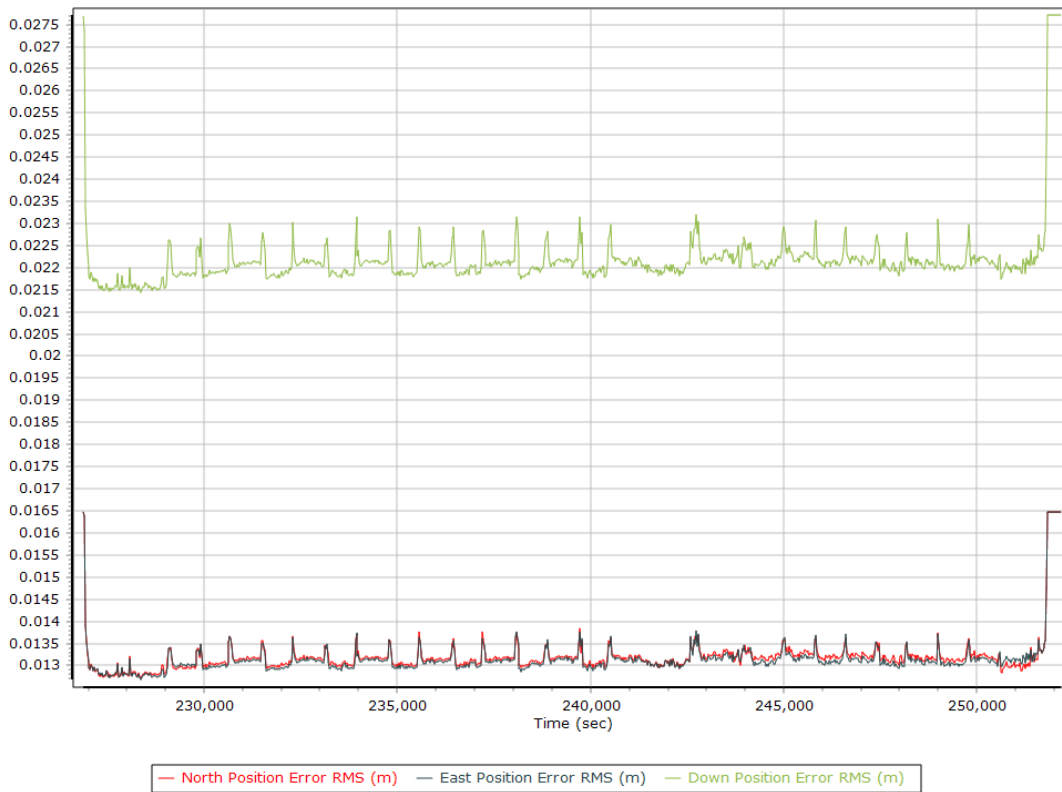


Z Gyro Bias (deg/h)

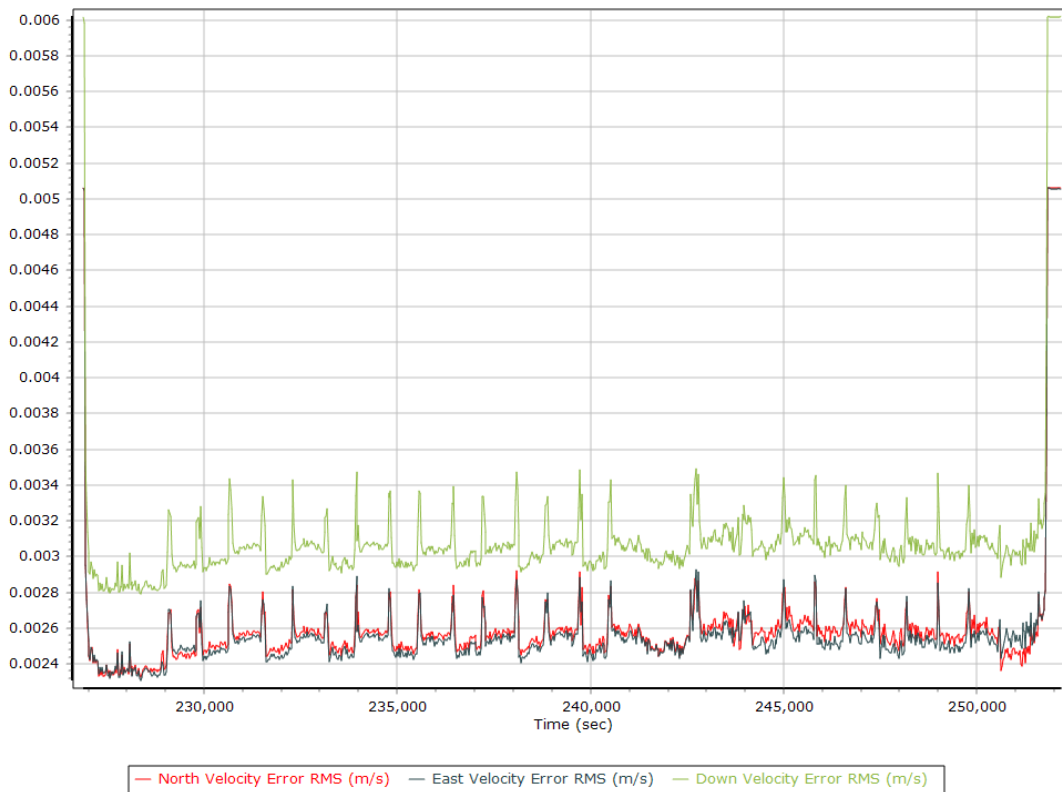


Smoothed Performance Metrics

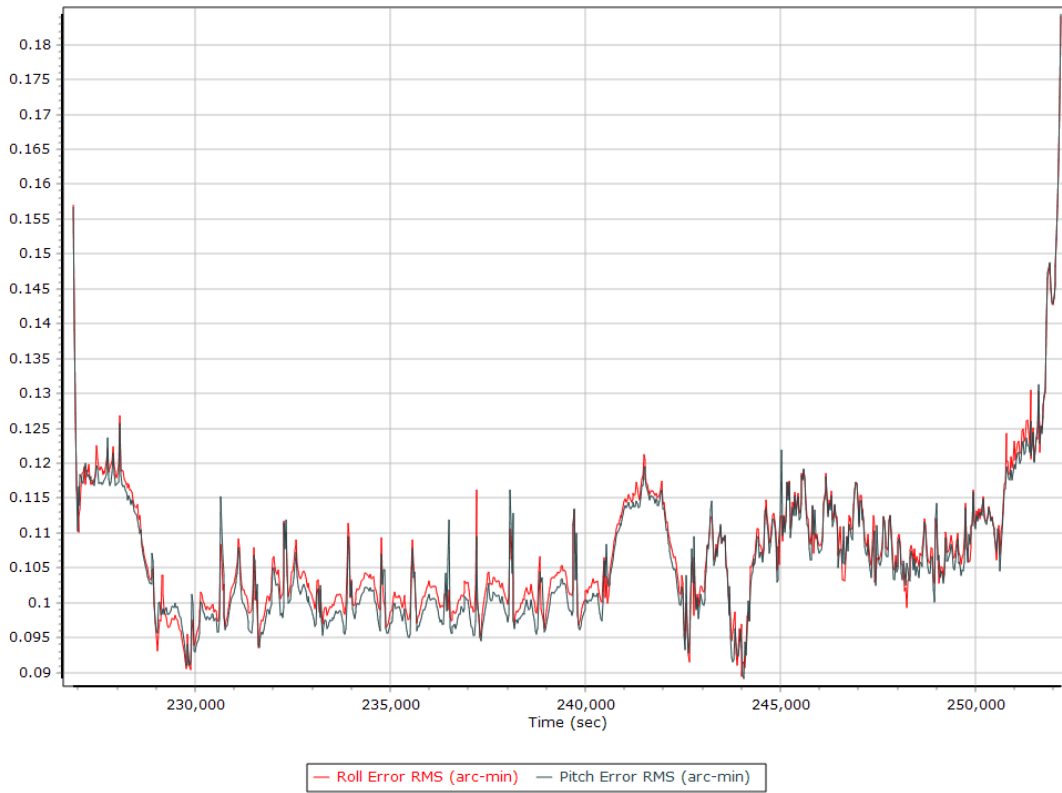
Position Error RMS (m)



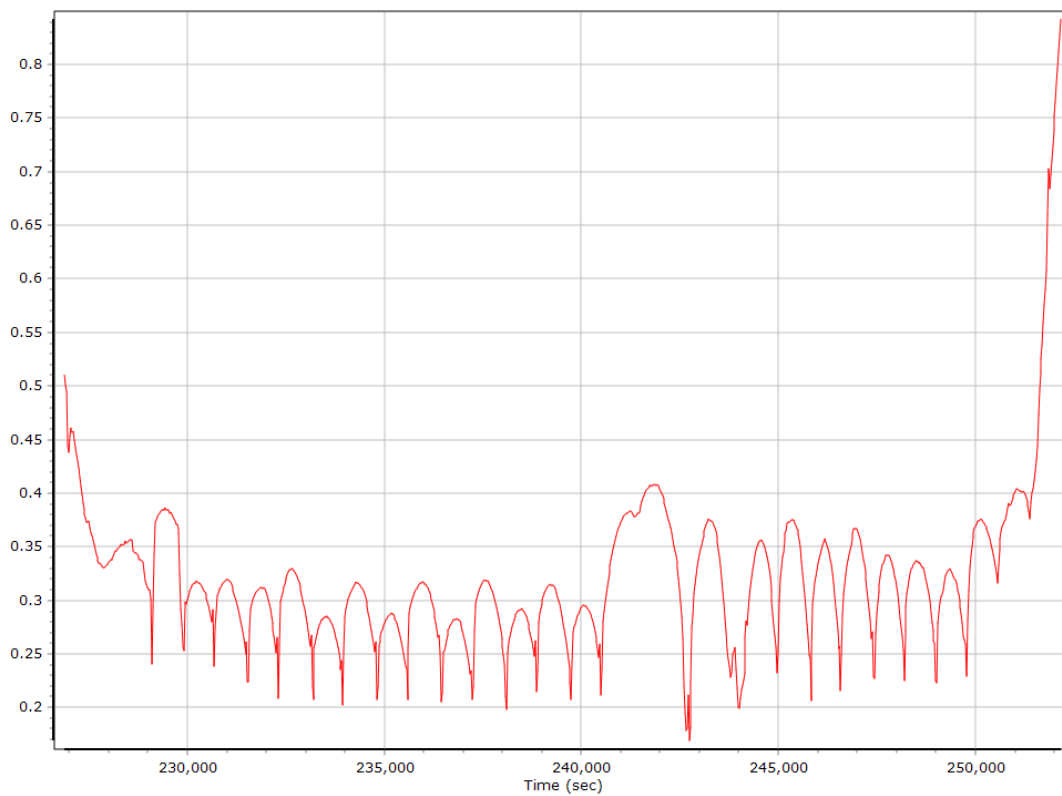
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

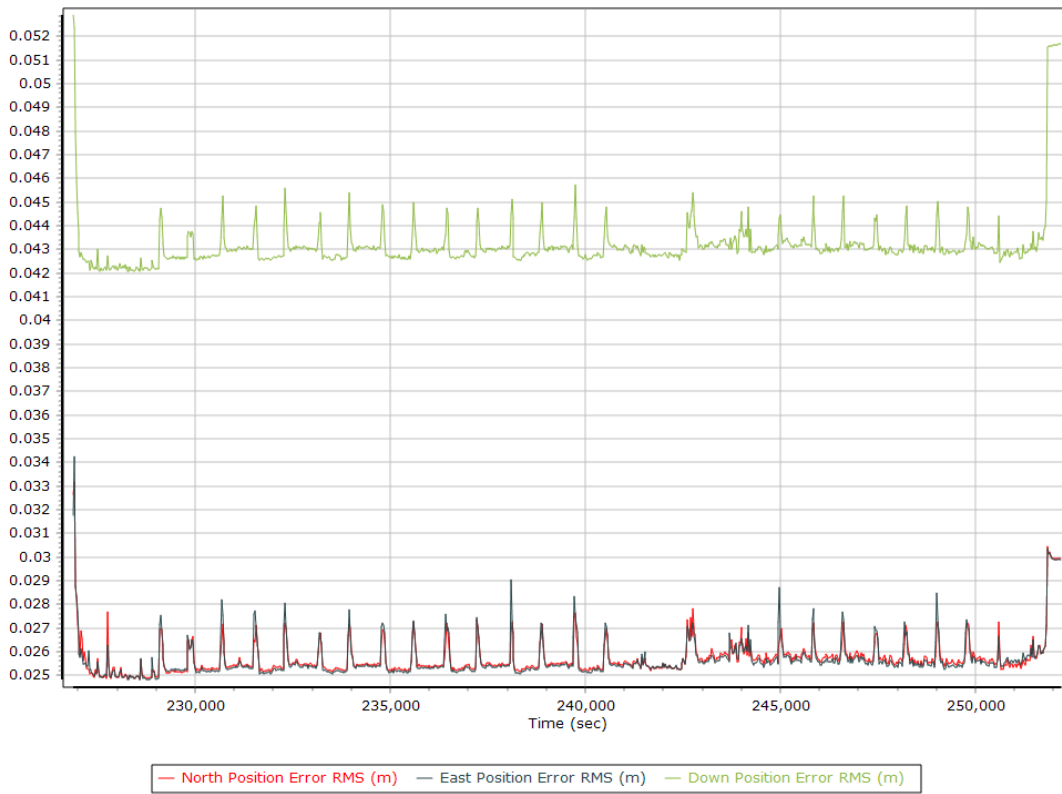


Heading Error RMS (arc-min)

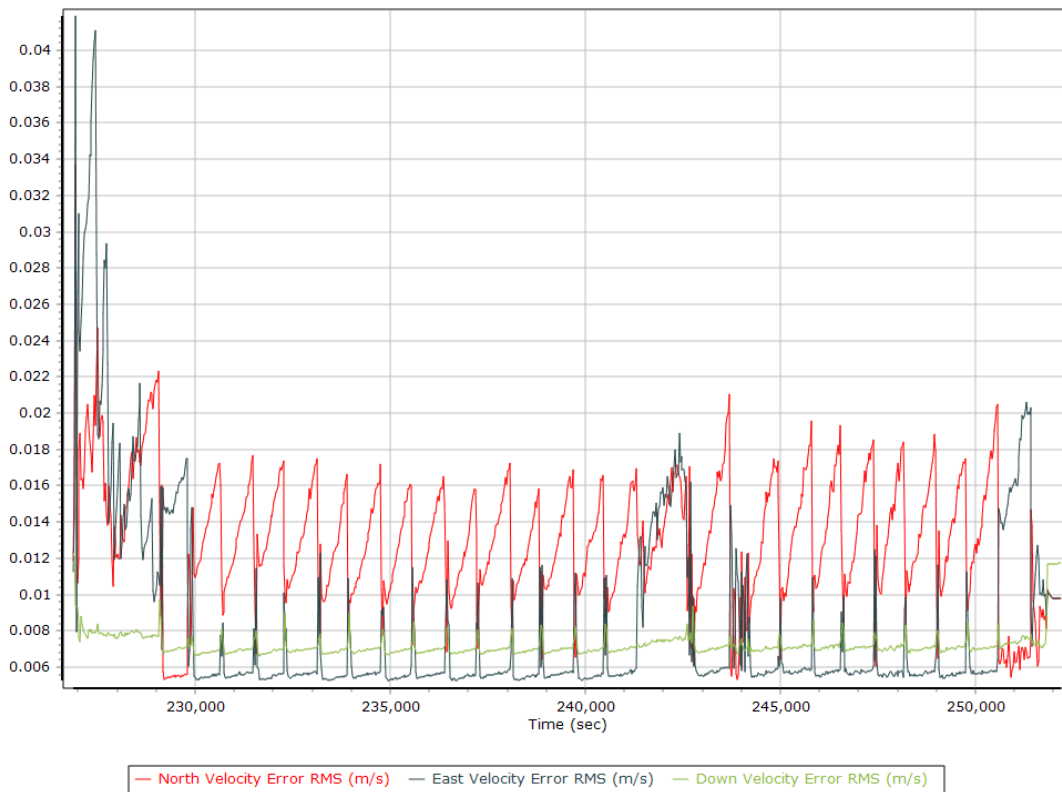


Forward Processed Performance Metrics

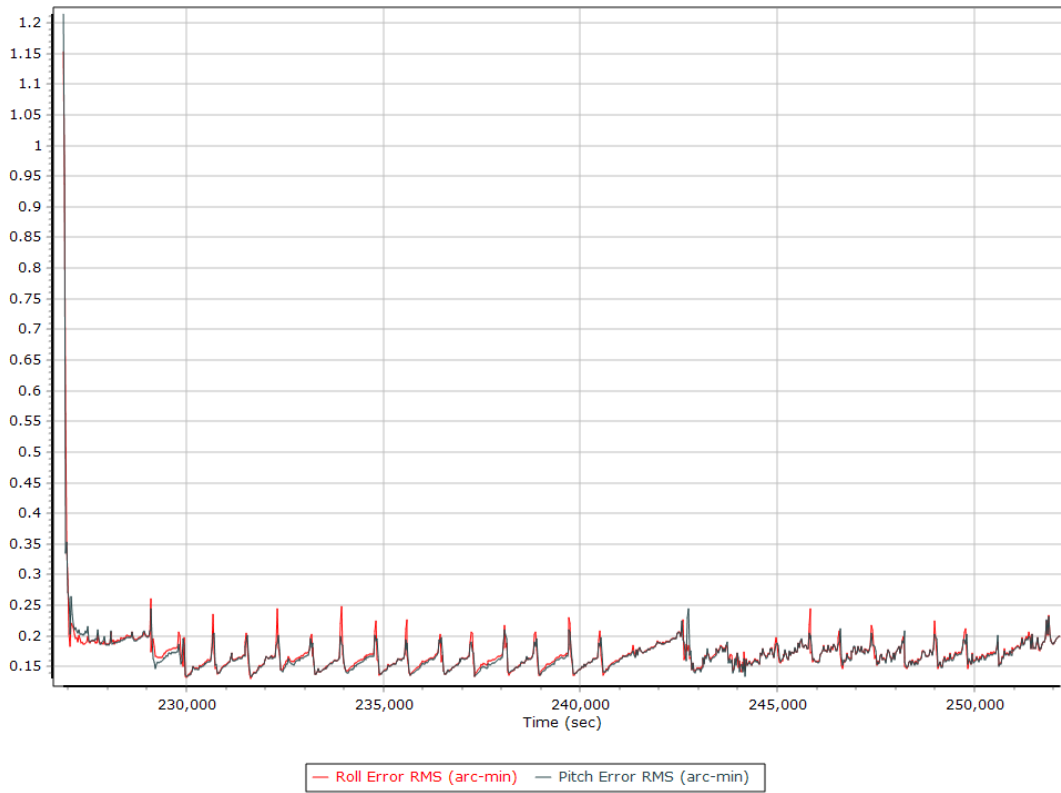
Position Error RMS (m)



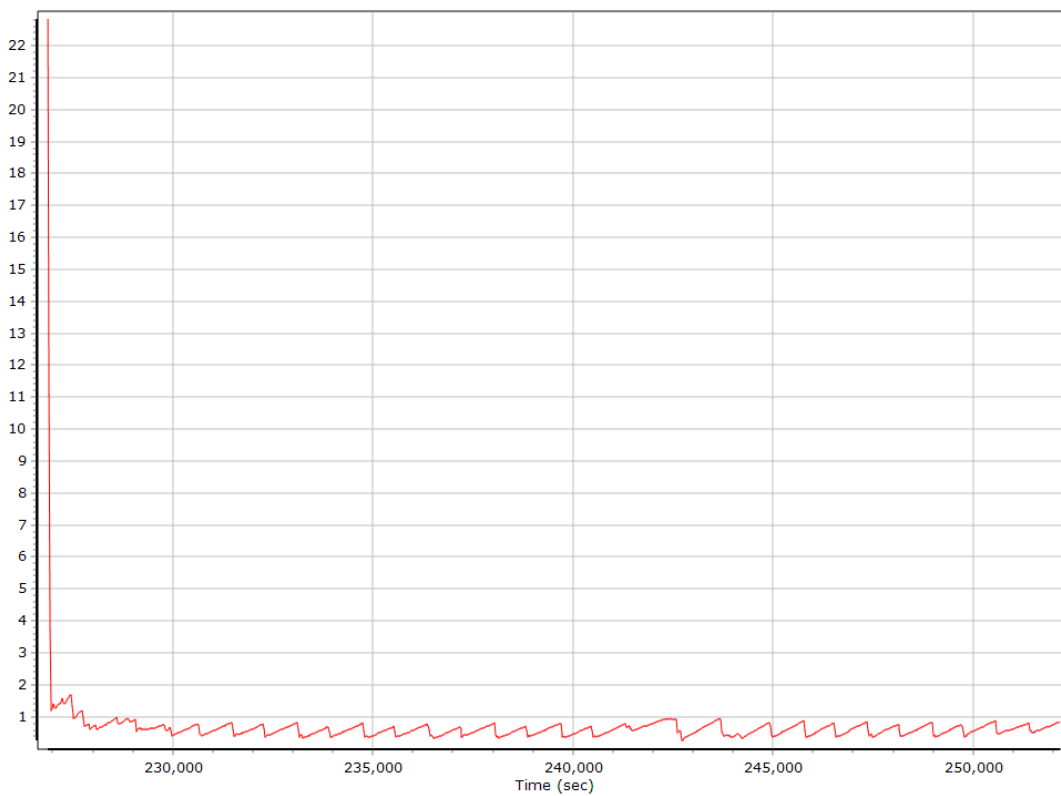
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

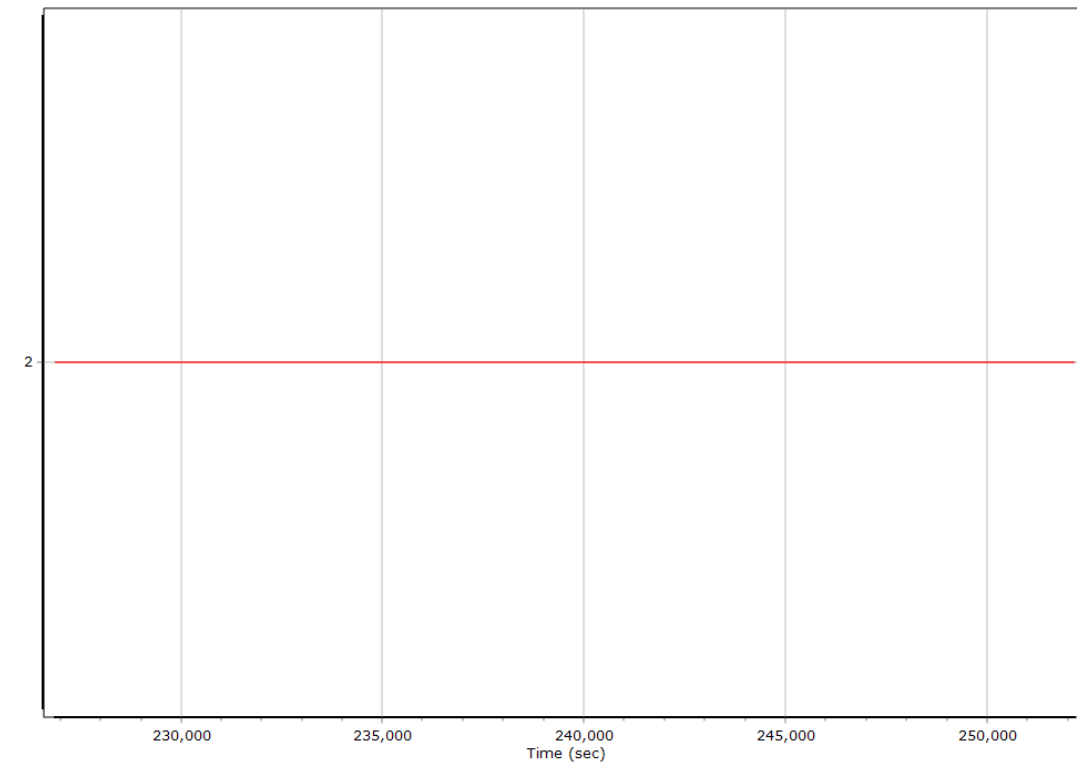


Heading Error RMS (arc-min)



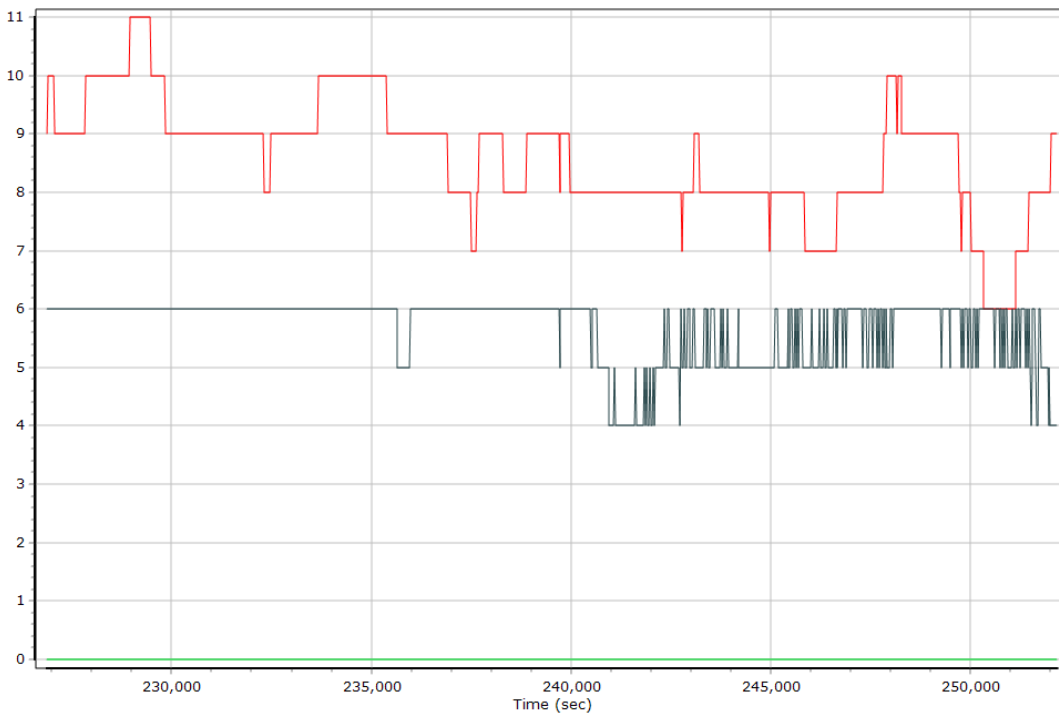
Forward Processed Solution Status

Processing Mode



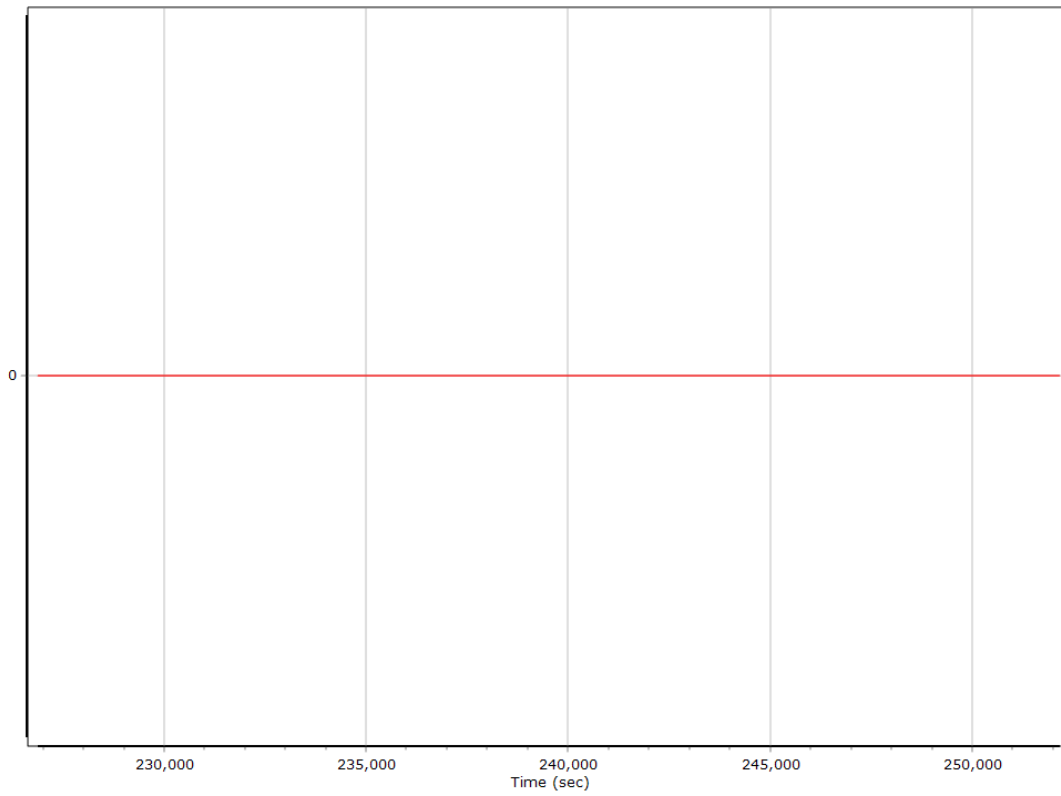
0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = C/A, 7 = GNSS Nav, 8 = DR

Number of Satellites



— Number of GPS Satellites — Number of GLONASS Satellites — Number of QZSS Satellites
 — Number of BEIDOU Satellites — Number of GALILEO Satellites

Baseline Length



General Information

Mission Information

Project name	21-081_FFFC_210922
Processing date	2021-09-29 21:44:47
Mission date	2021-09-22 15:15:07
Mission duration	06:40:16.957
Processing mode	IN-Fusion Trimble RTX Nav

Rover Hardware Information

Product	POS AV 610 VER6 HW2.5-12
Serial number	S/N6675
IMU type	57
Receiver type	BD982
Antenna type	AV39

Project File List

Rover Data Files

File name	File type
210922_151449_POSAV610-6675.raw	POS Data

Input Files

File Name	File Type
Ephm2650.21g	GLONASS Broadcast Ephemeris
Ephm2650.21n	GPS Broadcast Ephemeris

Output Files

Filename	File type
sbet_21-081_FFFC_210922.out	SBET Trajectory File

Rover Data Summary

First raw data file	210922_151449_POSAV610-6675.raw		
Last raw data file	210922_151449_POSAV610-6675.raw		
Start GPS week	2176		
Start time	314089.108 (09/22/2021 15:14:49)		
End time	338104.708 (09/22/2021 21:55:04)		
Start of fine alignment	314367.480 (09/22/2021 15:19:27)		
Available subsystems	Primary GNSS, IMU		
POS Event Input	Event 1 Input		
Correction data	Trimble RTX		
IMU Installation Lever Arms & Mounting Angles			
Reference to IMU lever arm (m)	0.000	0.000	0.000
Reference to IMU mounting angles (deg)	0.000	0.000	0.000
Reference to Primary GNSS lever arm (m)	0.016	0.063	-0.958
Reference to Primary GNSS lever arm std dev (m)	-1.000		
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

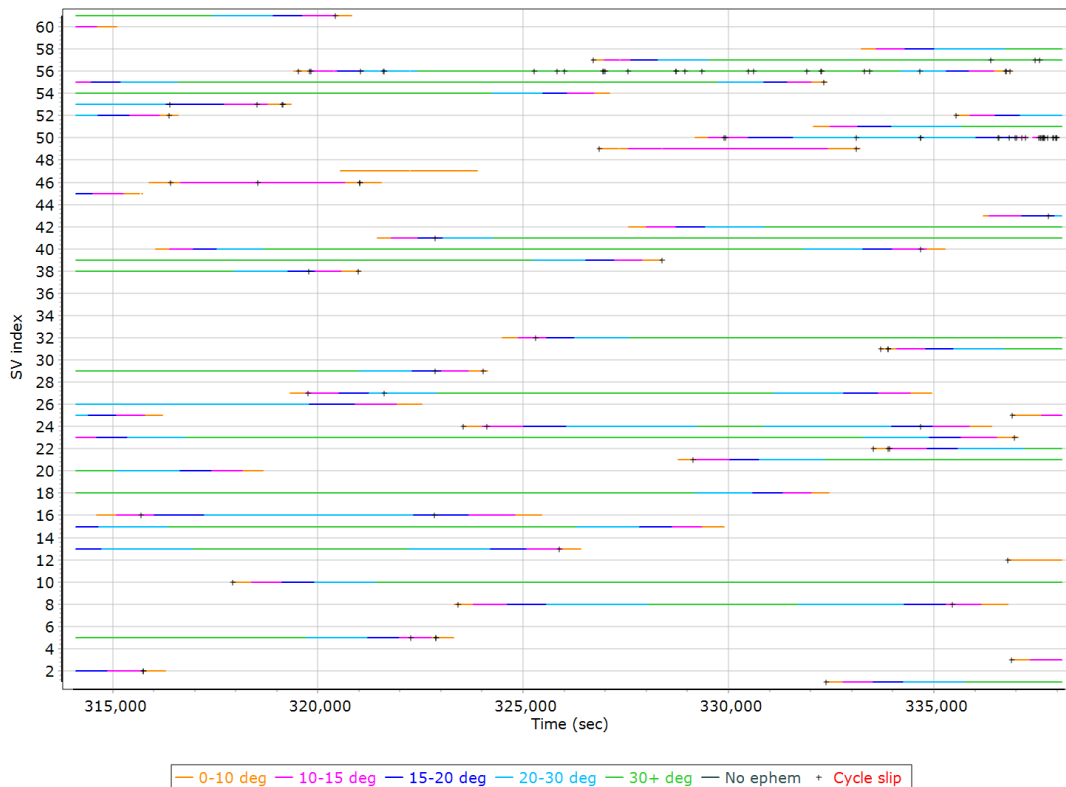
Rover Data QC

Raw IMU Import QC Summary

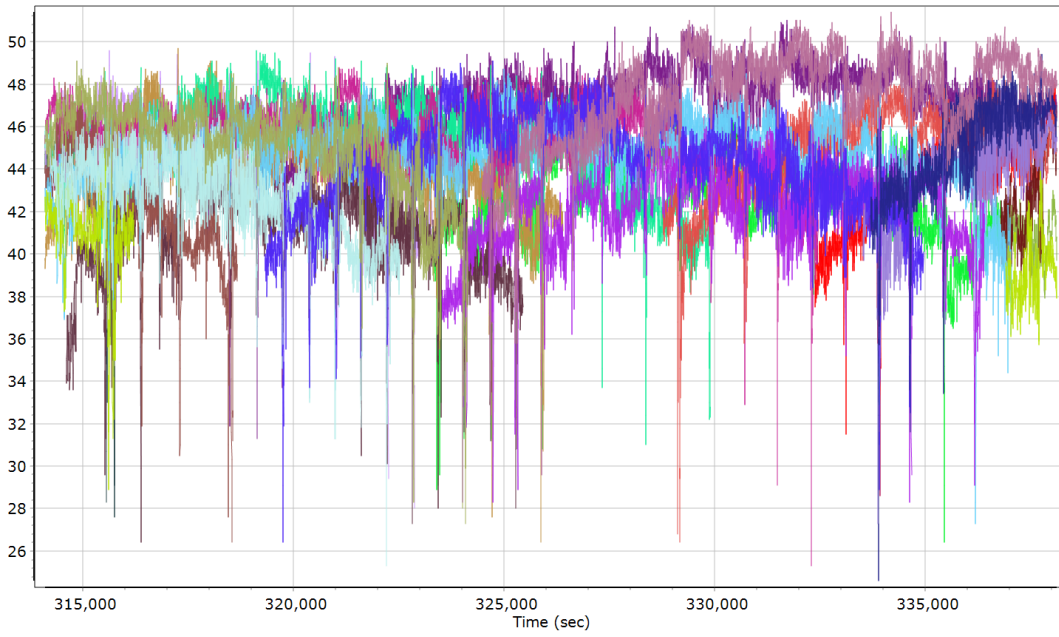
IMU data input file	imu_21-081_FFFC_210922.dat
IMU data check log file	imudt_21-081_FFFC_210922.log
IMU Records Processed	4802504
Termination Status	Normal
IMU Anomalies	0

Primary Observables & Satellite Data

GPS/GLONASS L1 Satellite Lock/Elevation

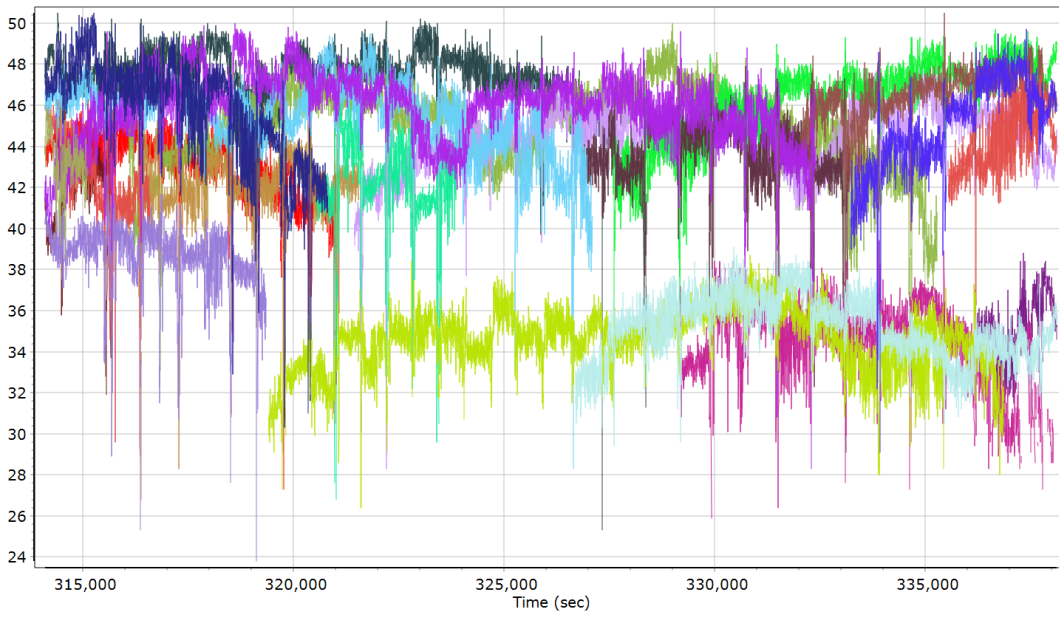


GPS L1 SNR



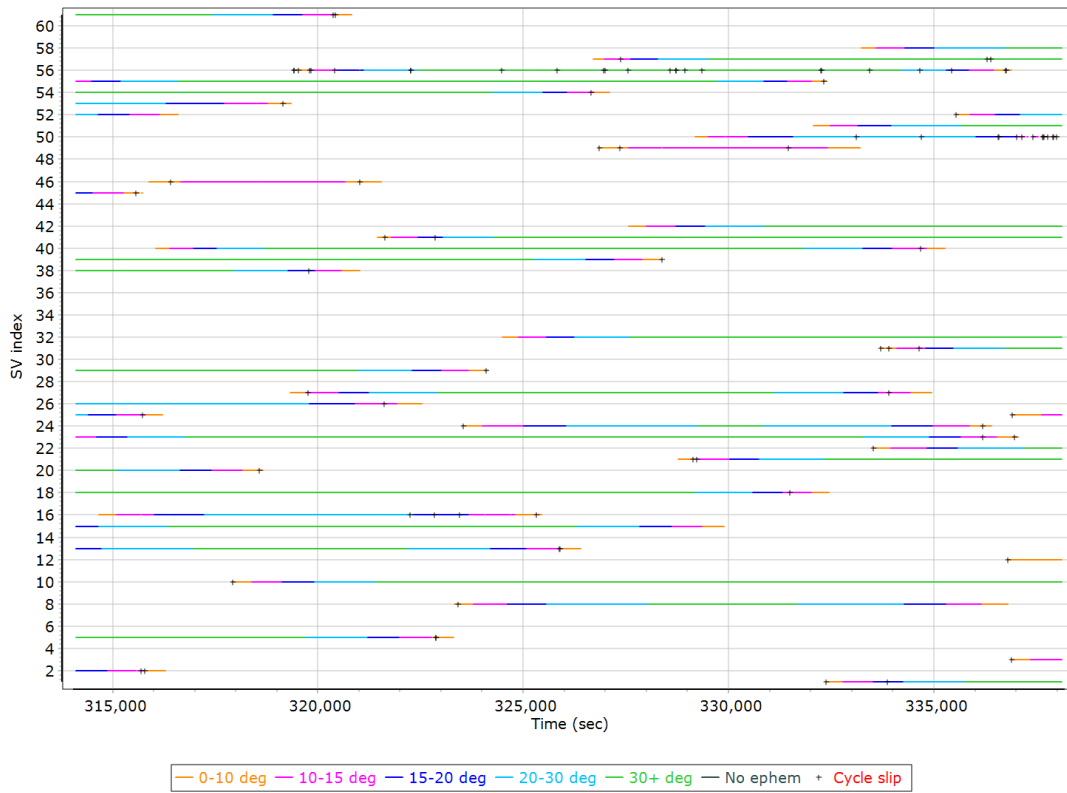
- | | | | |
|---------------------------|---------------------------|---------------------------|---------------------------|
| GPS PRN 01 L1 SNR (dB/Hz) | GPS PRN 02 L1 SNR (dB/Hz) | GPS PRN 03 L1 SNR (dB/Hz) | GPS PRN 05 L1 SNR (dB/Hz) |
| GPS PRN 08 L1 SNR (dB/Hz) | GPS PRN 10 L1 SNR (dB/Hz) | GPS PRN 12 L1 SNR (dB/Hz) | GPS PRN 13 L1 SNR (dB/Hz) |
| GPS PRN 15 L1 SNR (dB/Hz) | GPS PRN 16 L1 SNR (dB/Hz) | GPS PRN 18 L1 SNR (dB/Hz) | GPS PRN 20 L1 SNR (dB/Hz) |
| GPS PRN 21 L1 SNR (dB/Hz) | GPS PRN 22 L1 SNR (dB/Hz) | GPS PRN 23 L1 SNR (dB/Hz) | GPS PRN 24 L1 SNR (dB/Hz) |
| GPS PRN 25 L1 SNR (dB/Hz) | GPS PRN 26 L1 SNR (dB/Hz) | GPS PRN 27 L1 SNR (dB/Hz) | GPS PRN 29 L1 SNR (dB/Hz) |
| GPS PRN 31 L1 SNR (dB/Hz) | GPS PRN 32 L1 SNR (dB/Hz) | | |

GLONASS L1 SNR

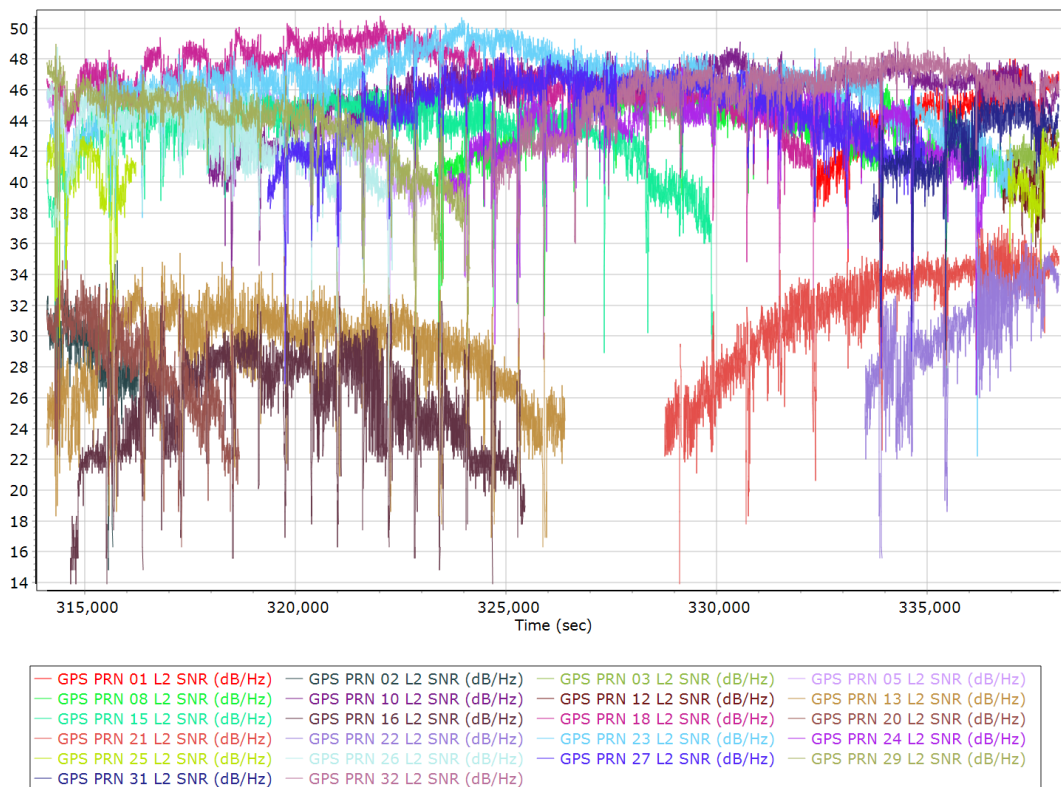


- | | | |
|---------------------------|---------------------------|---------------------------|
| GLONASS 01 L1 SNR (dB/Hz) | GLONASS 02 L1 SNR (dB/Hz) | GLONASS 03 L1 SNR (dB/Hz) |
| GLONASS 04 L1 SNR (dB/Hz) | GLONASS 05 L1 SNR (dB/Hz) | GLONASS 06 L1 SNR (dB/Hz) |
| GLONASS 08 L1 SNR (dB/Hz) | GLONASS 09 L1 SNR (dB/Hz) | GLONASS 10 L1 SNR (dB/Hz) |
| GLONASS 12 L1 SNR (dB/Hz) | GLONASS 13 L1 SNR (dB/Hz) | GLONASS 14 L1 SNR (dB/Hz) |
| GLONASS 15 L1 SNR (dB/Hz) | GLONASS 16 L1 SNR (dB/Hz) | GLONASS 17 L1 SNR (dB/Hz) |
| GLONASS 18 L1 SNR (dB/Hz) | GLONASS 19 L1 SNR (dB/Hz) | GLONASS 20 L1 SNR (dB/Hz) |
| GLONASS 21 L1 SNR (dB/Hz) | GLONASS 23 L1 SNR (dB/Hz) | GLONASS 24 L1 SNR (dB/Hz) |

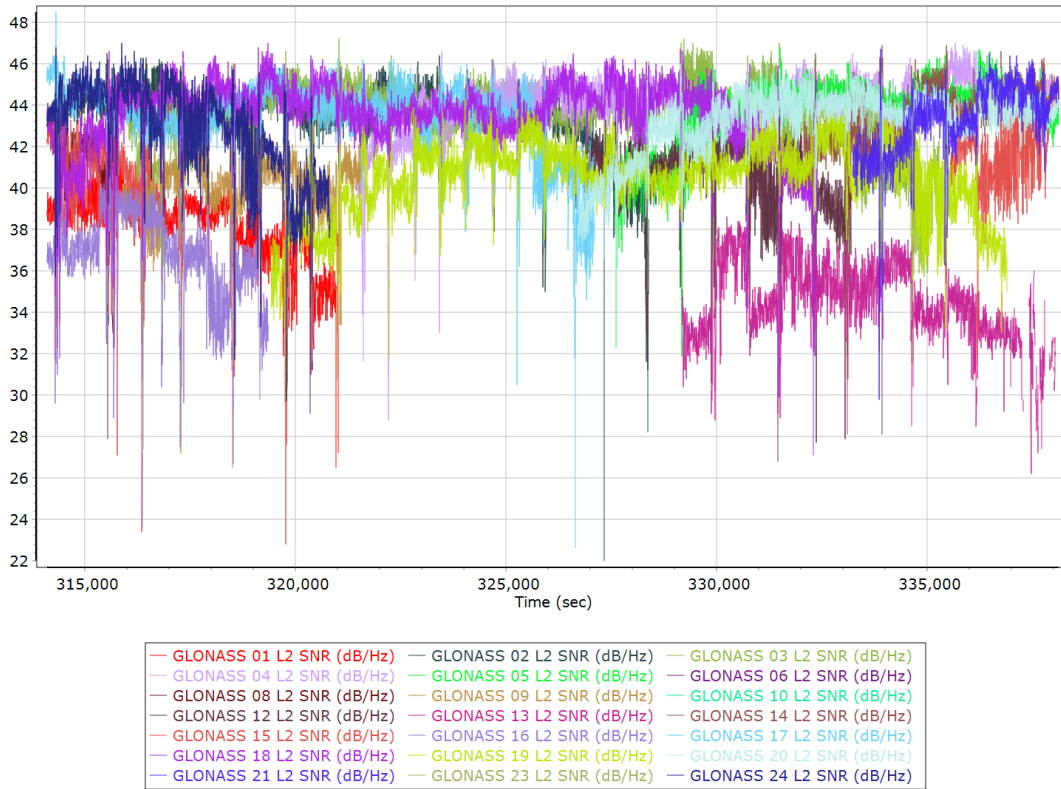
GPS/GLONASS L2 Satellite Lock/Elevation



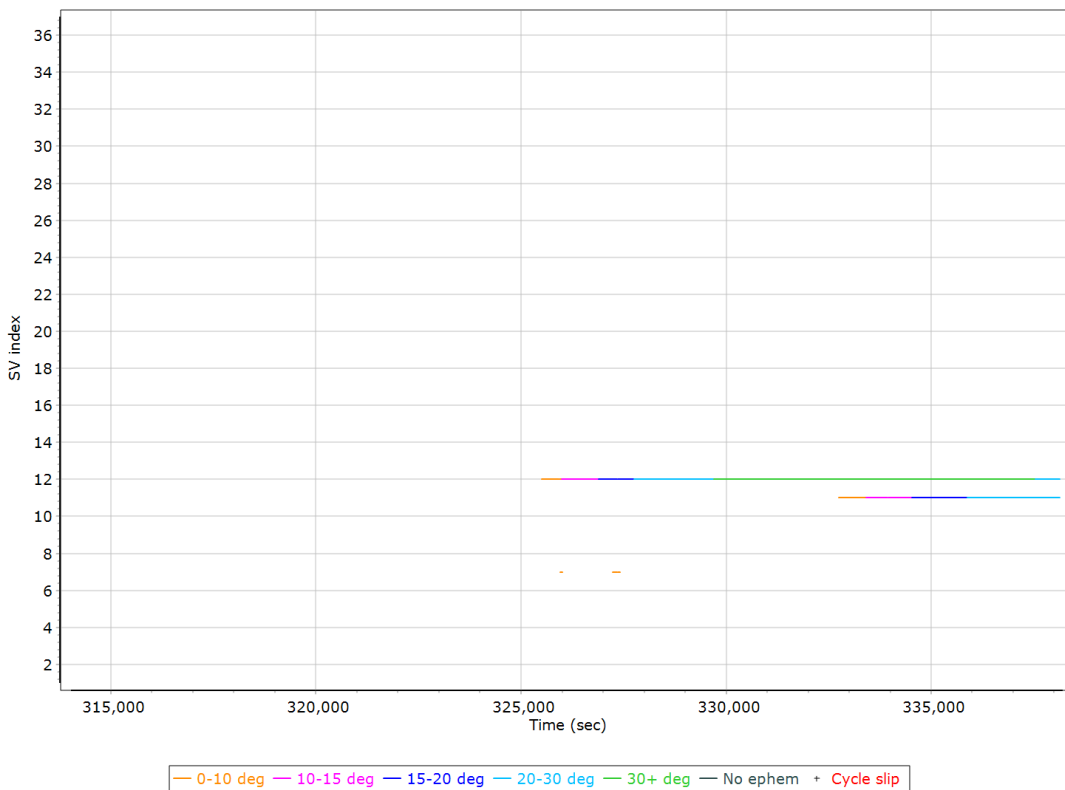
GPS L2 SNR



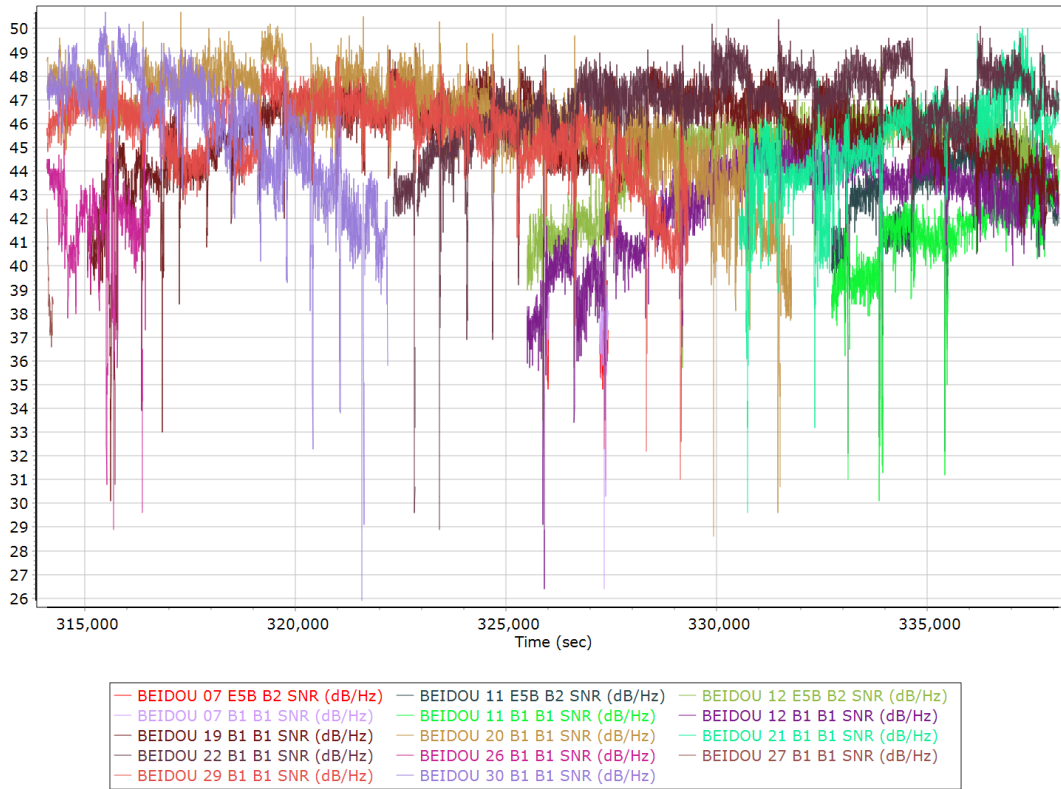
GLONASS L2 SNR



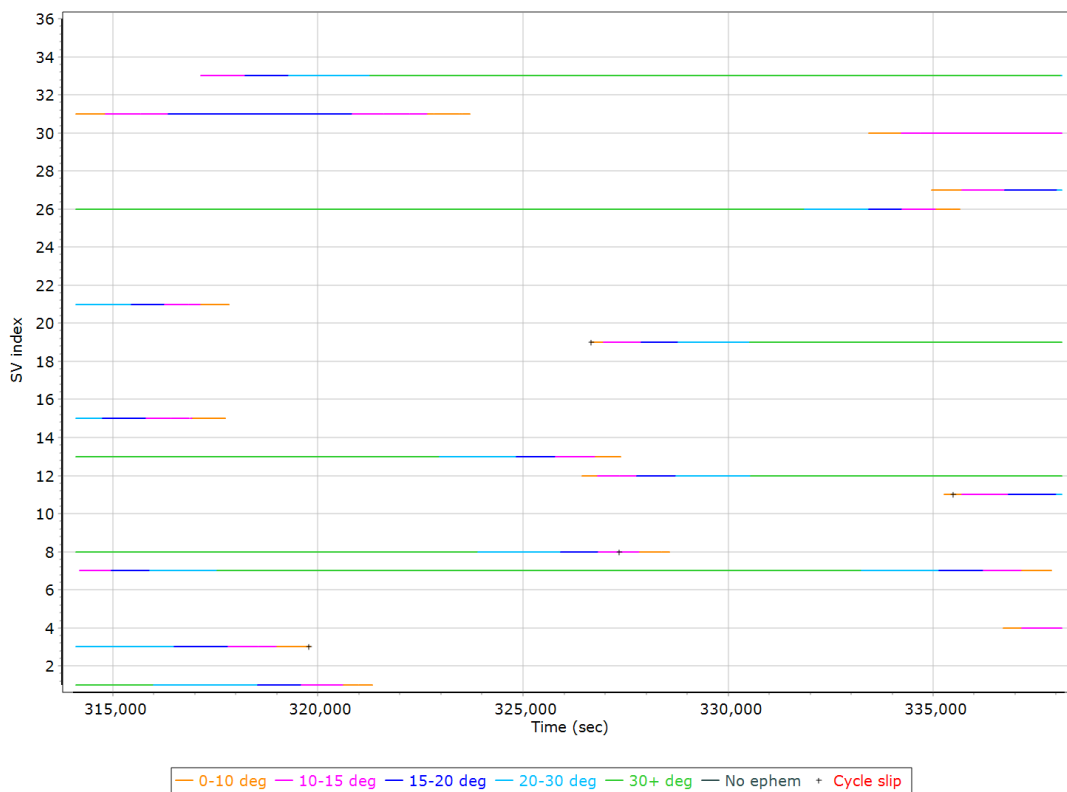
BEIDOU Satellite Lock/Elevation



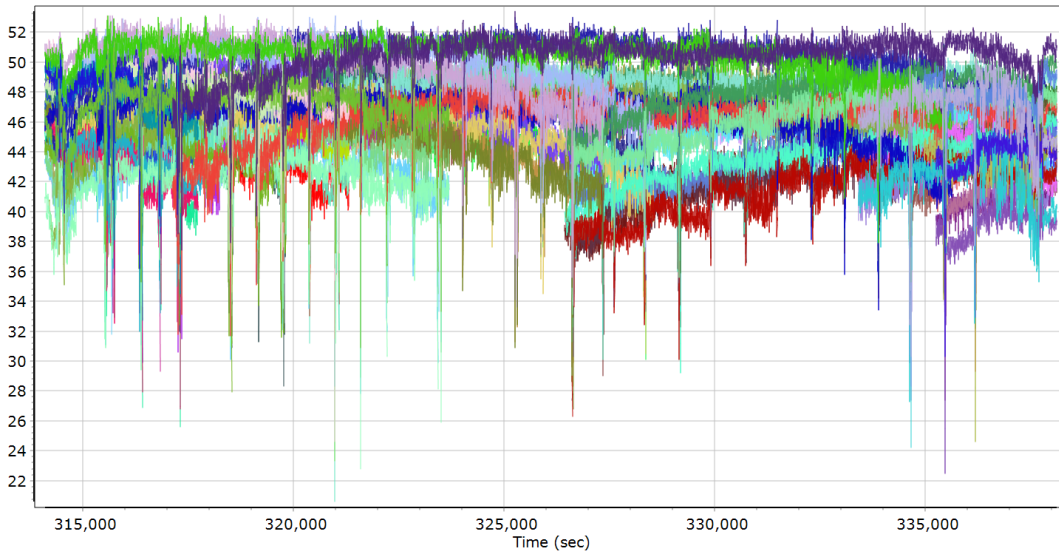
BEIDOU SNR



GALILEO Satellite Lock/Elevation



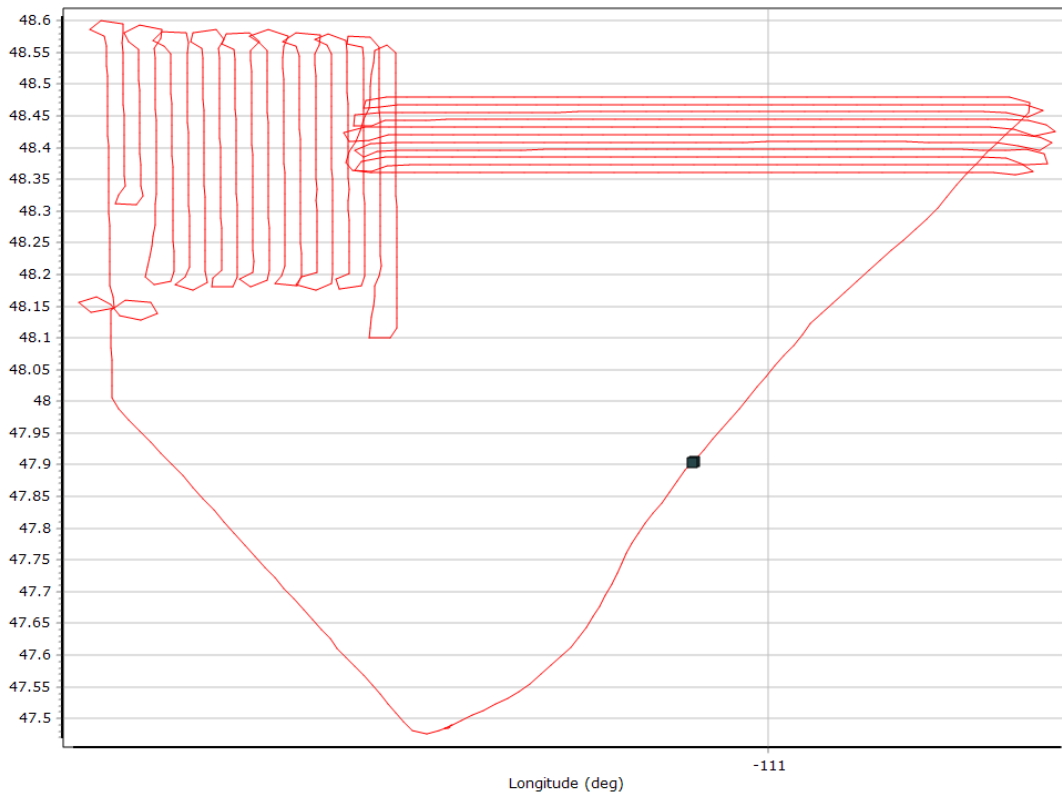
GALILEO SNR



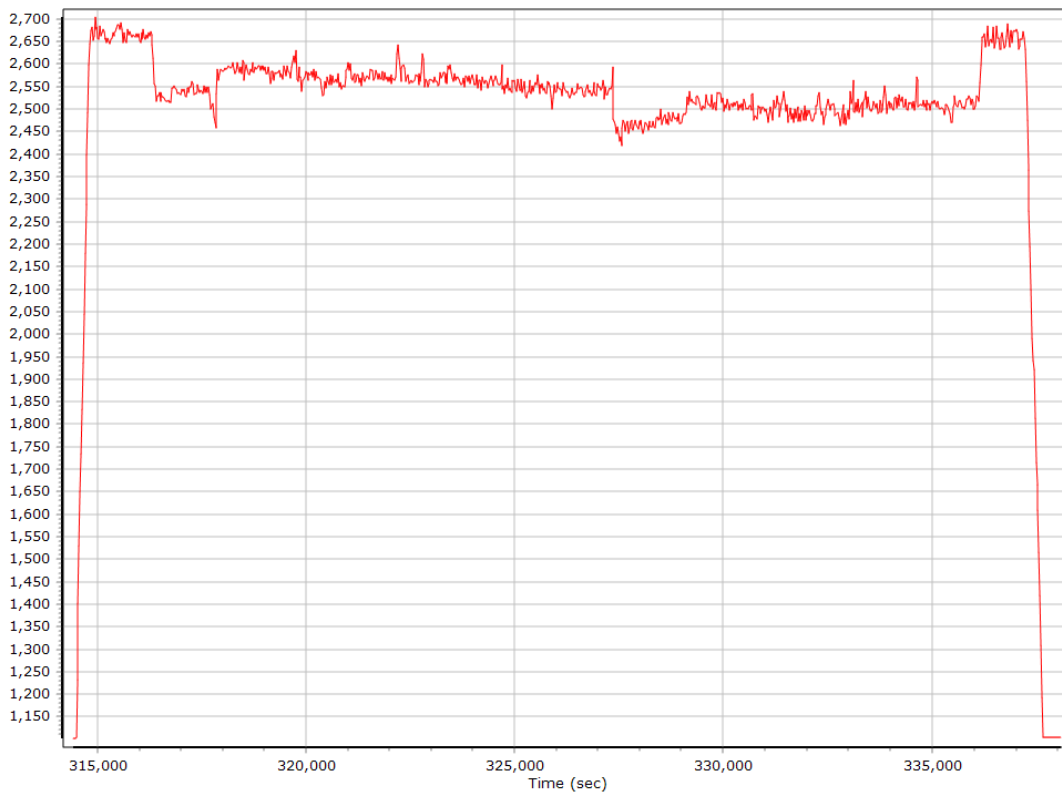
— GALILEO 01 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 03 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 04 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 07 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 08 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 11 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 12 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 13 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 15 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 19 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 21 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 26 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 27 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 30 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 31 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 33 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 01 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 03 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 04 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 07 L5E5A BPSK10_PD SNR (dB/Hz)

Smoothed Trajectory Information

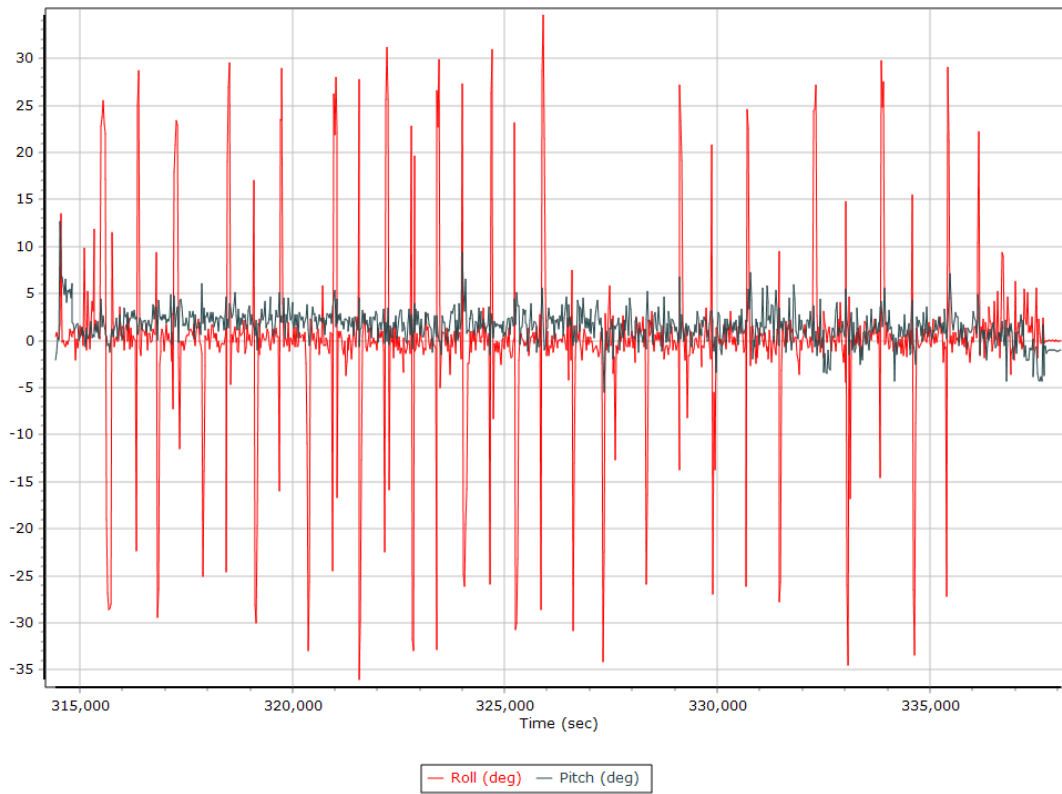
Top View



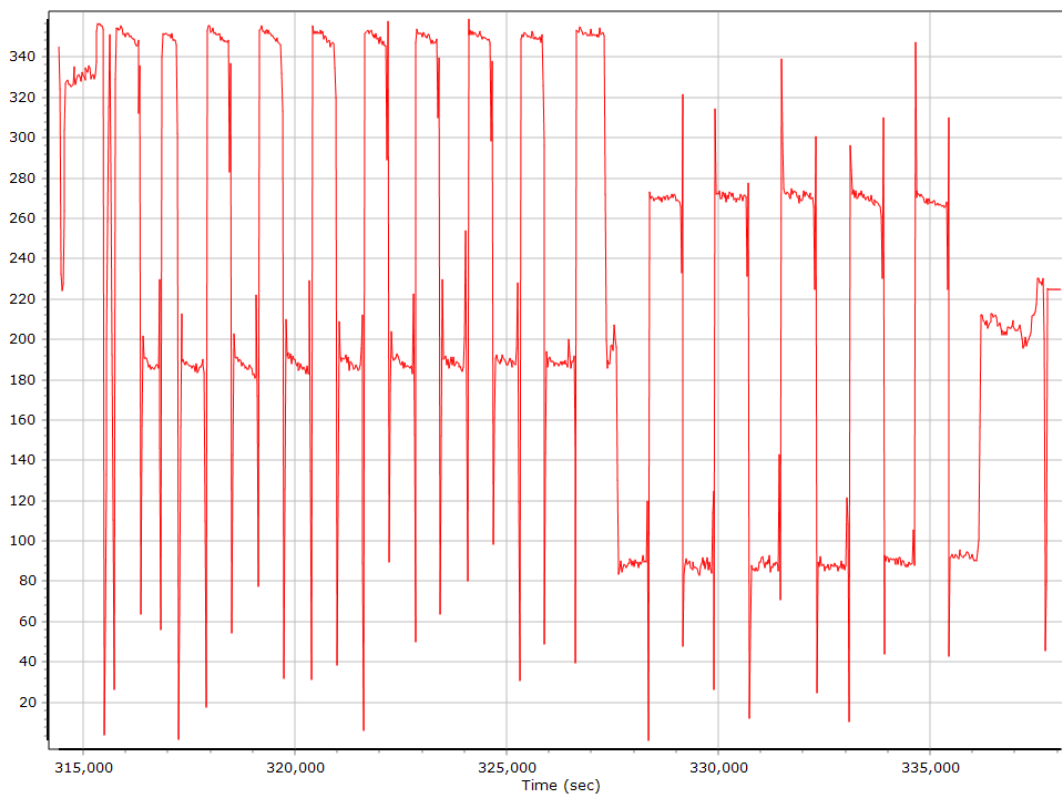
Altitude



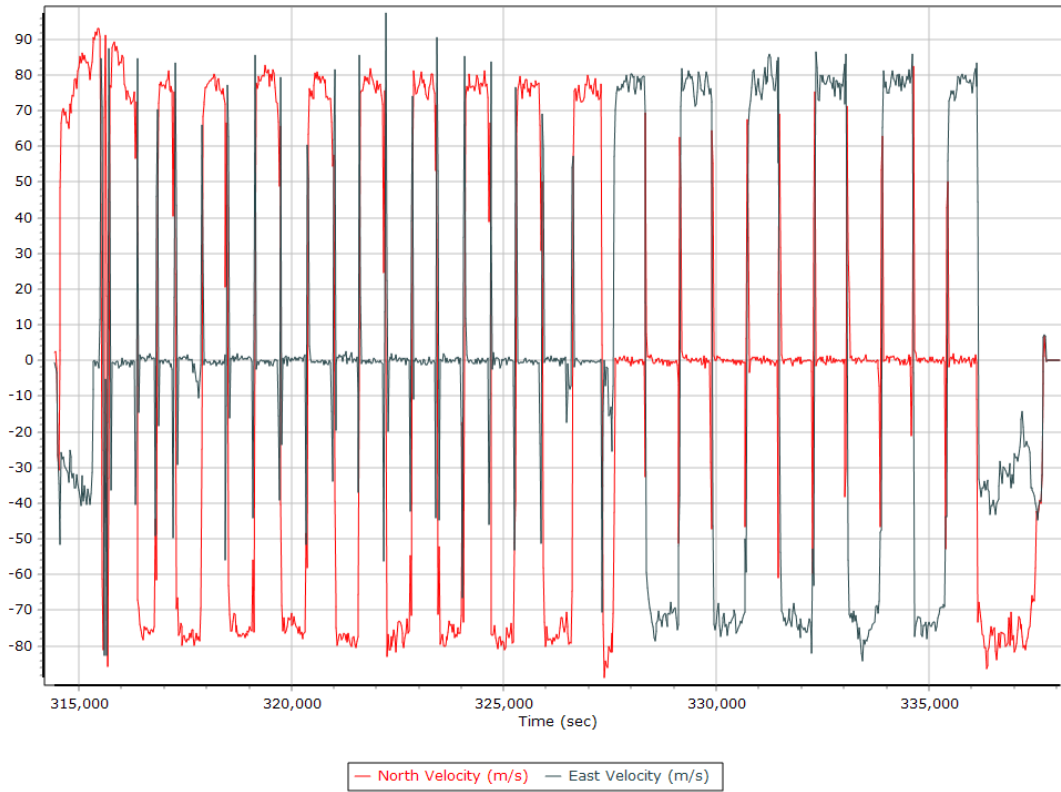
Roll/Pitch



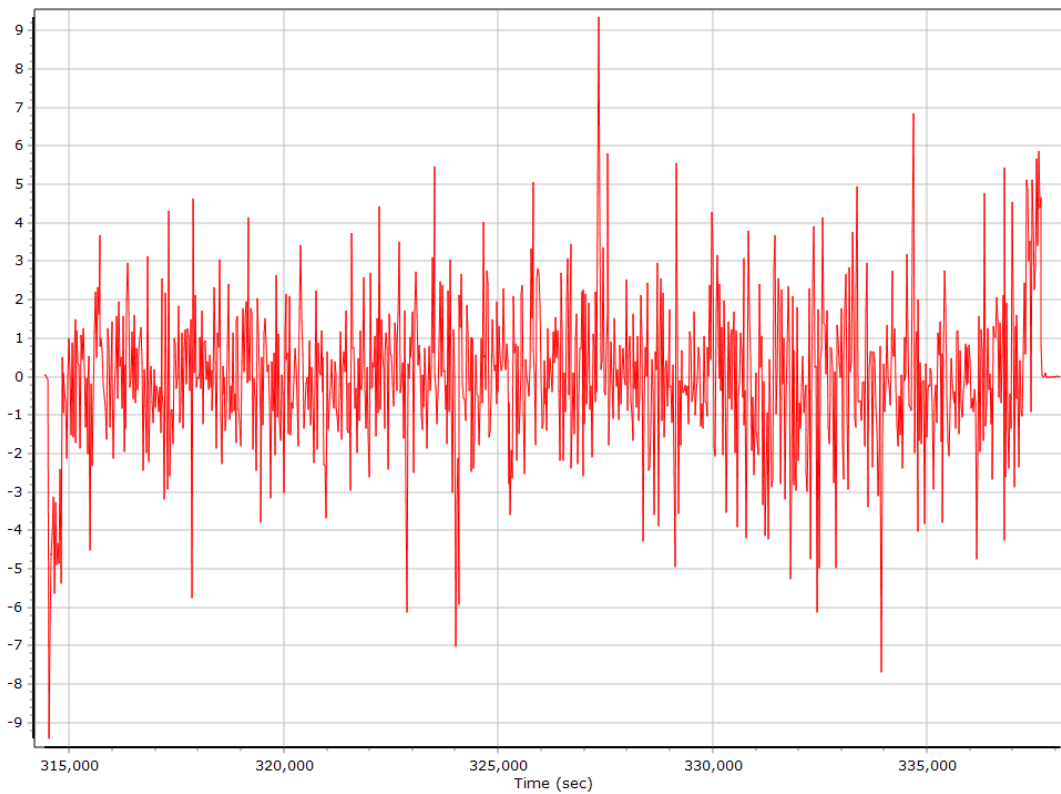
Heading



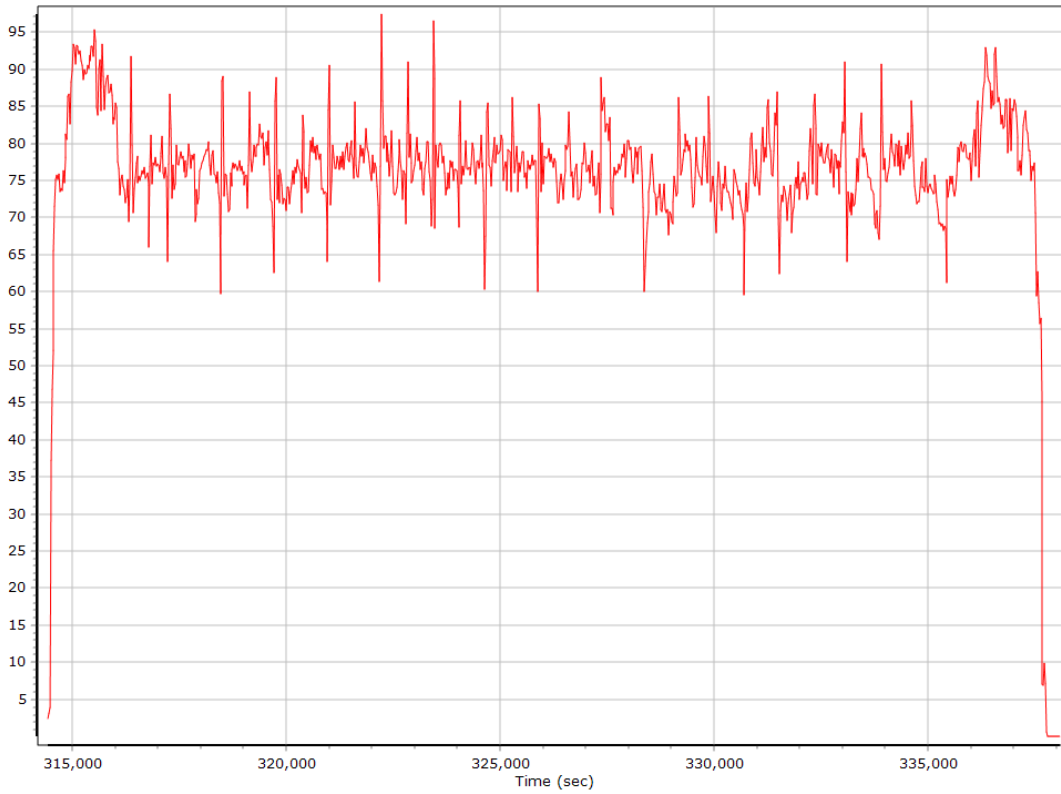
North/East Velocity



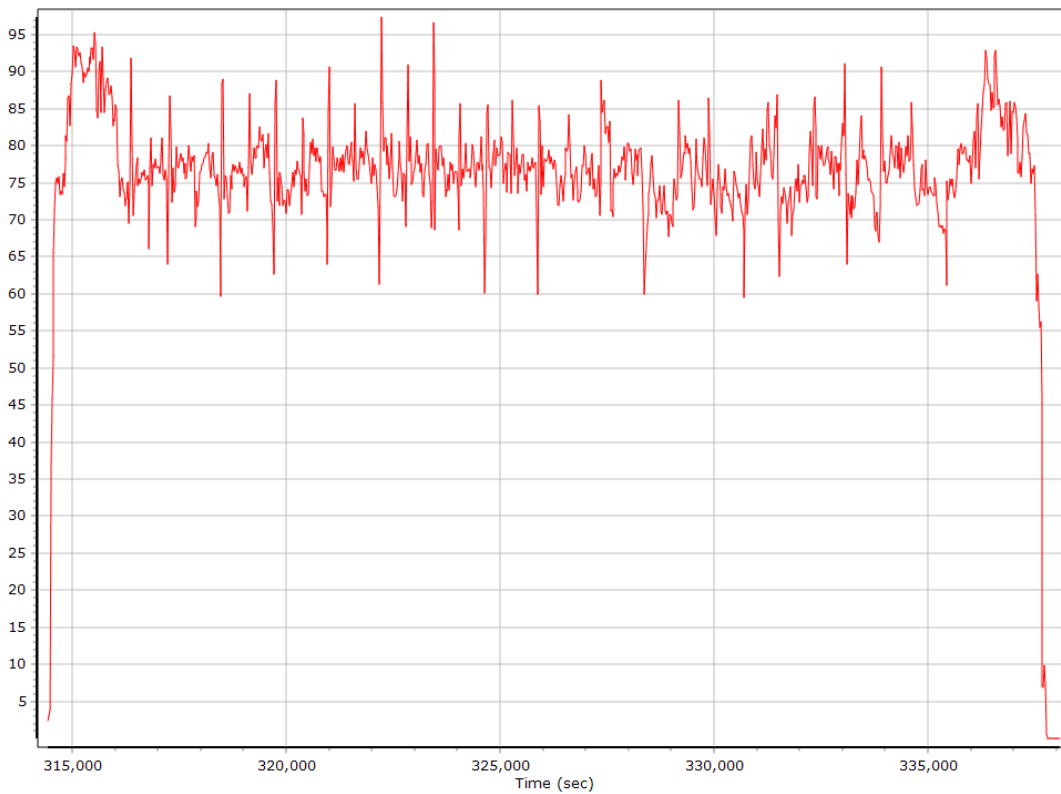
Down Velocity



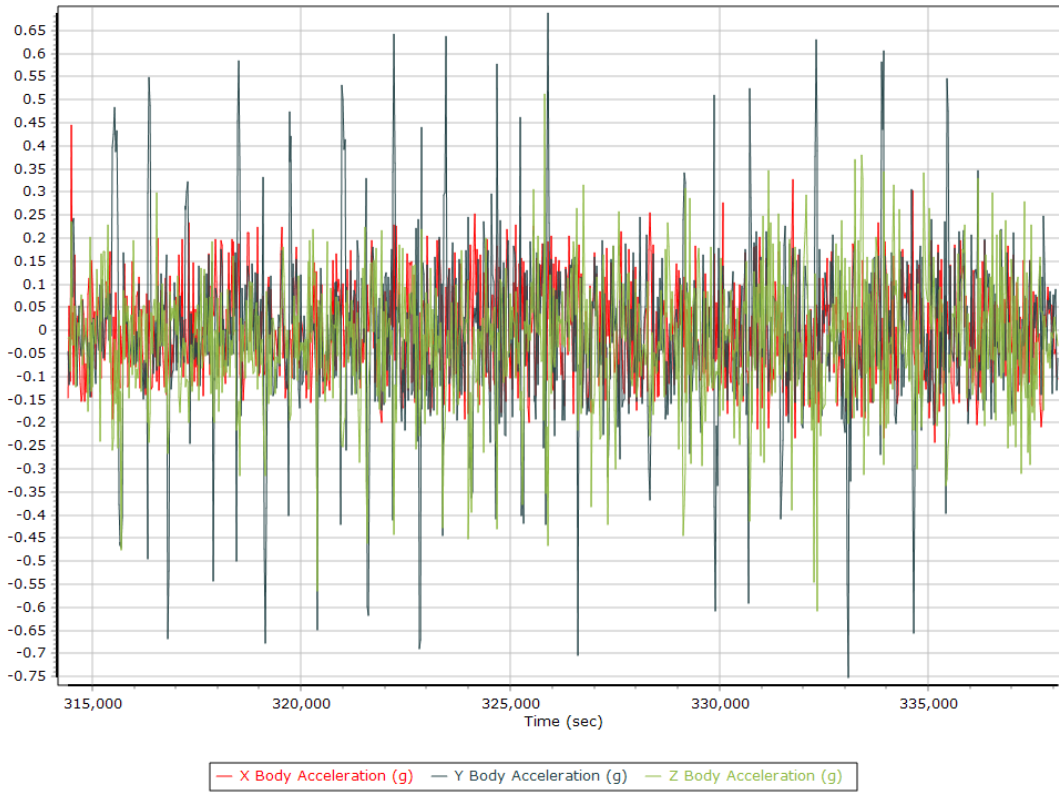
Total Speed



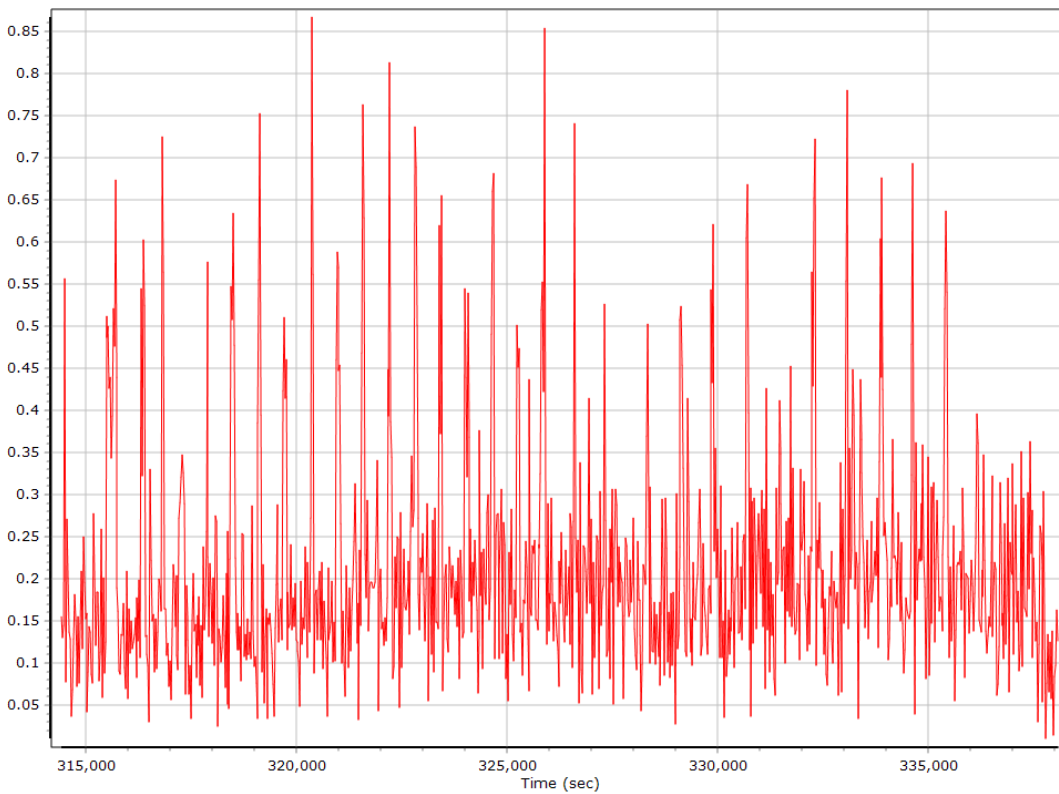
Ground Speed



Body Acceleration



Total Body Acceleration

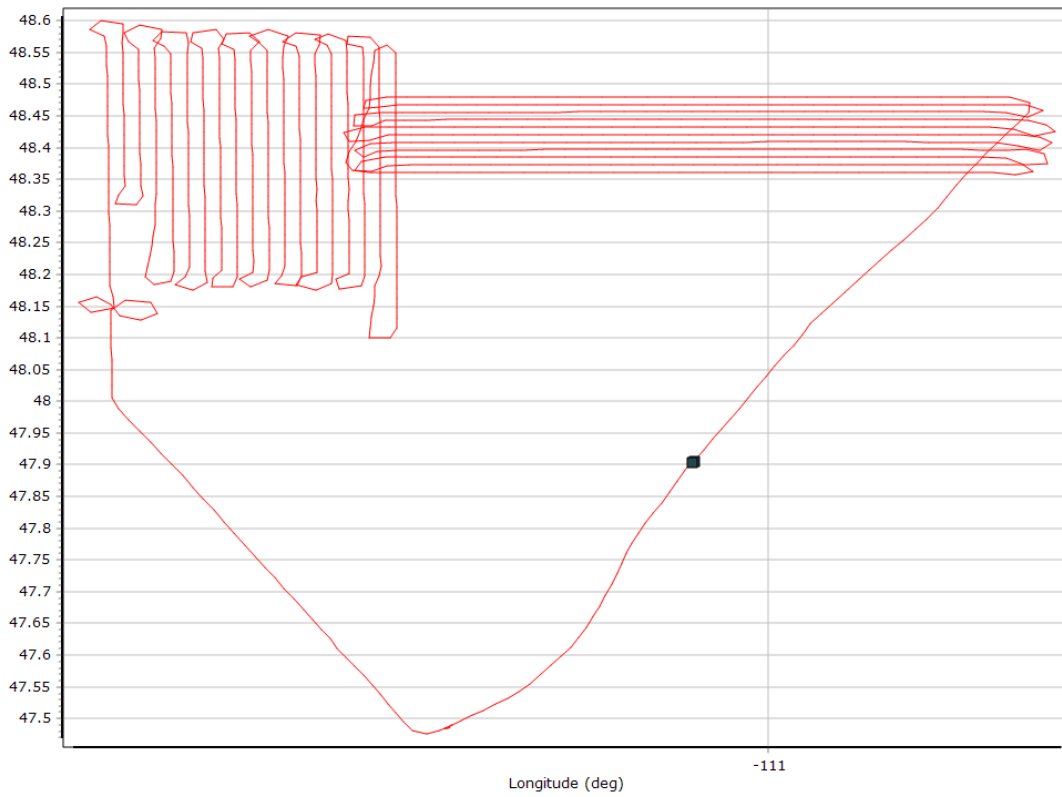


Body Angular Rate

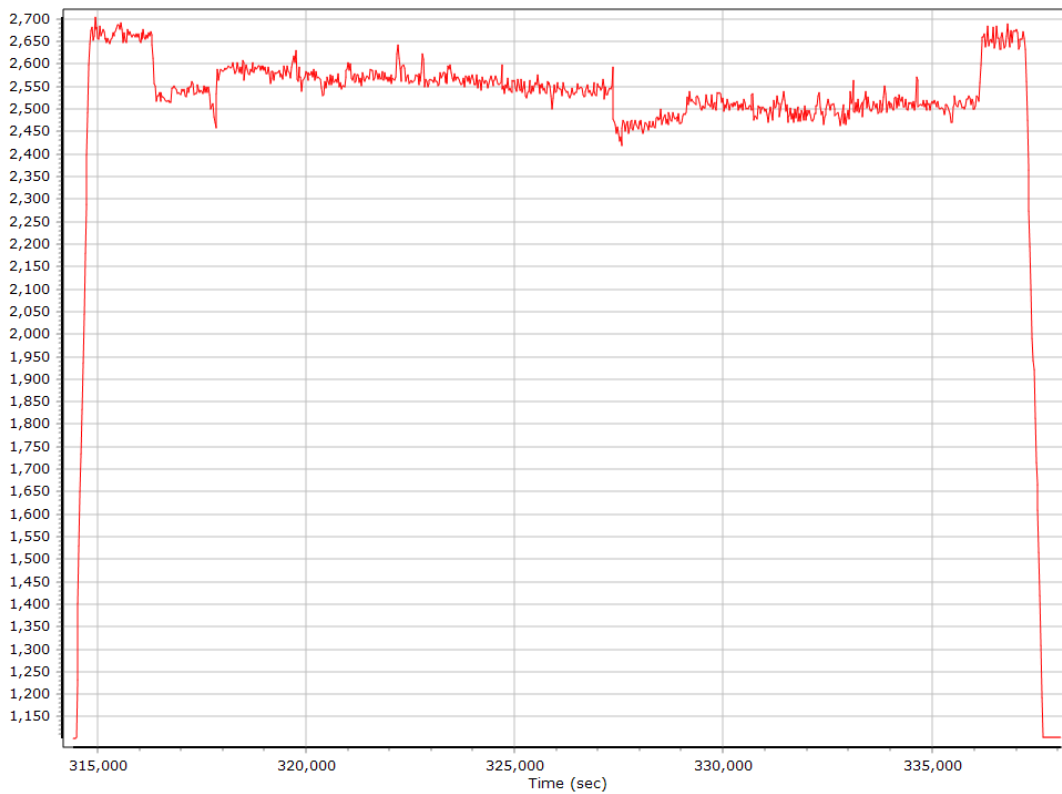


Forward Processed Trajectory Information

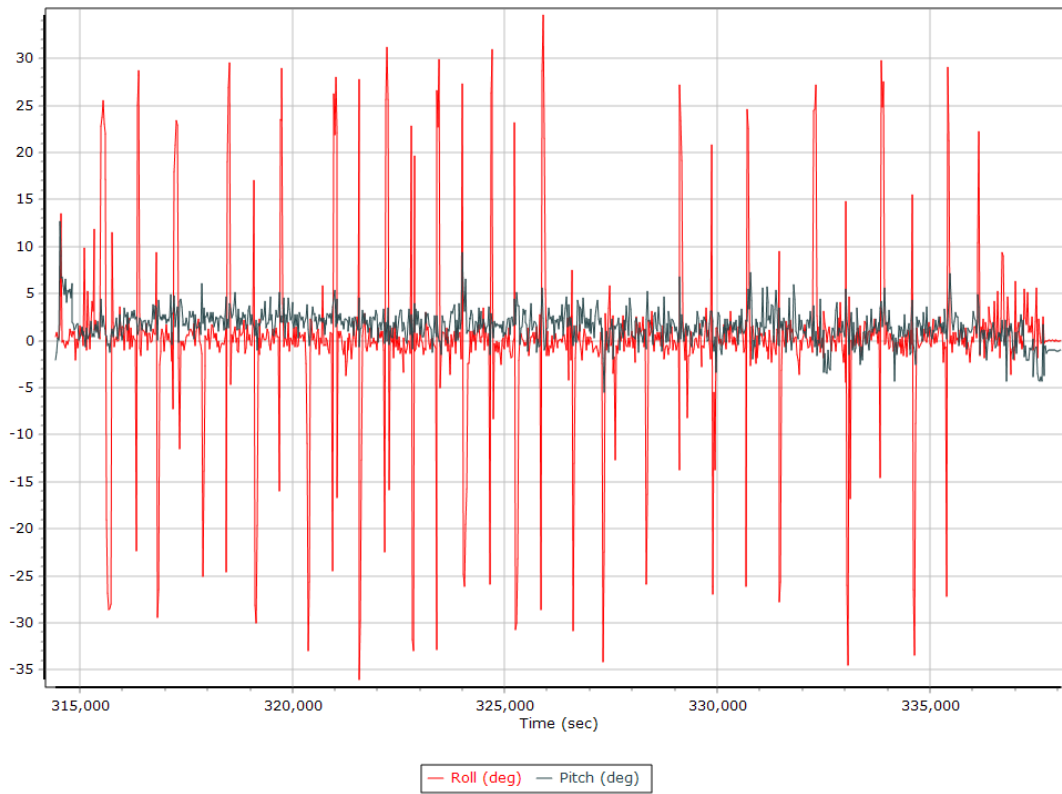
Top View



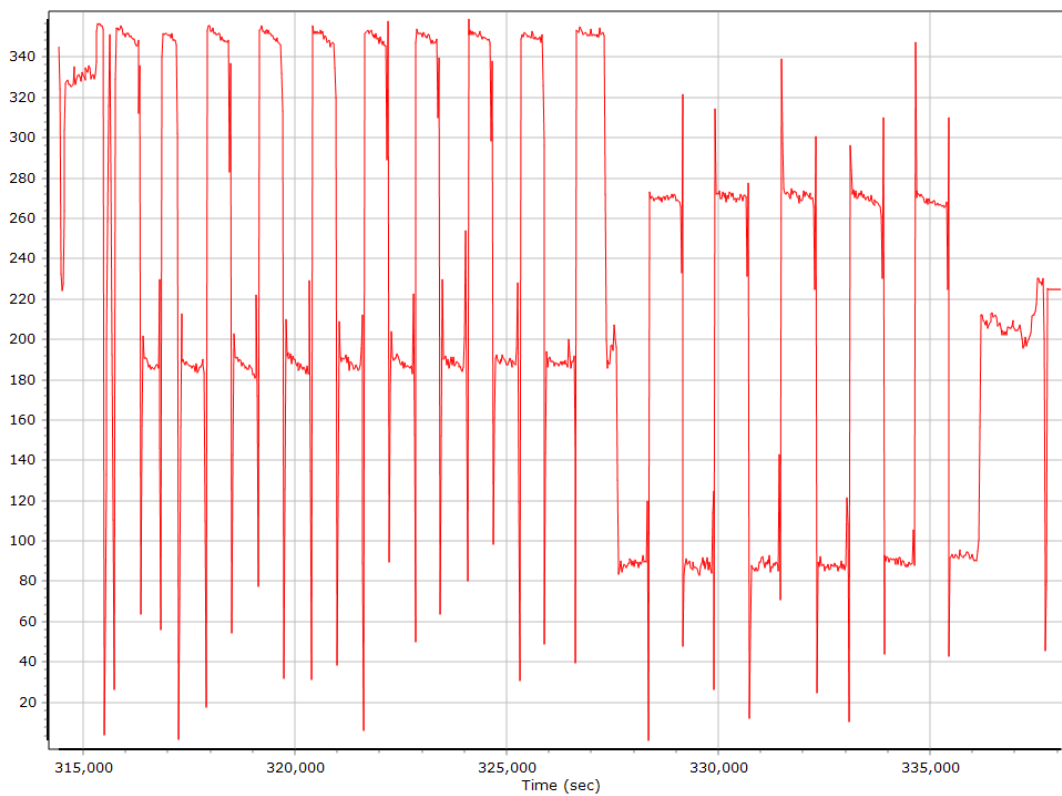
Altitude



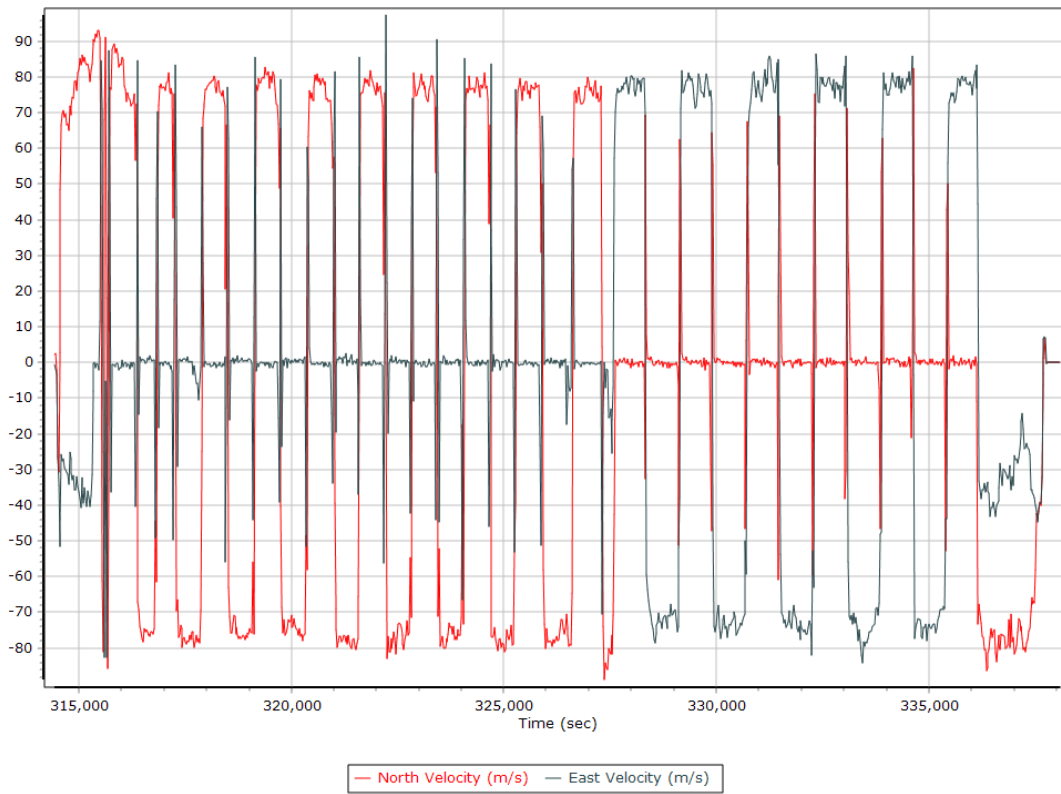
Roll/Pitch



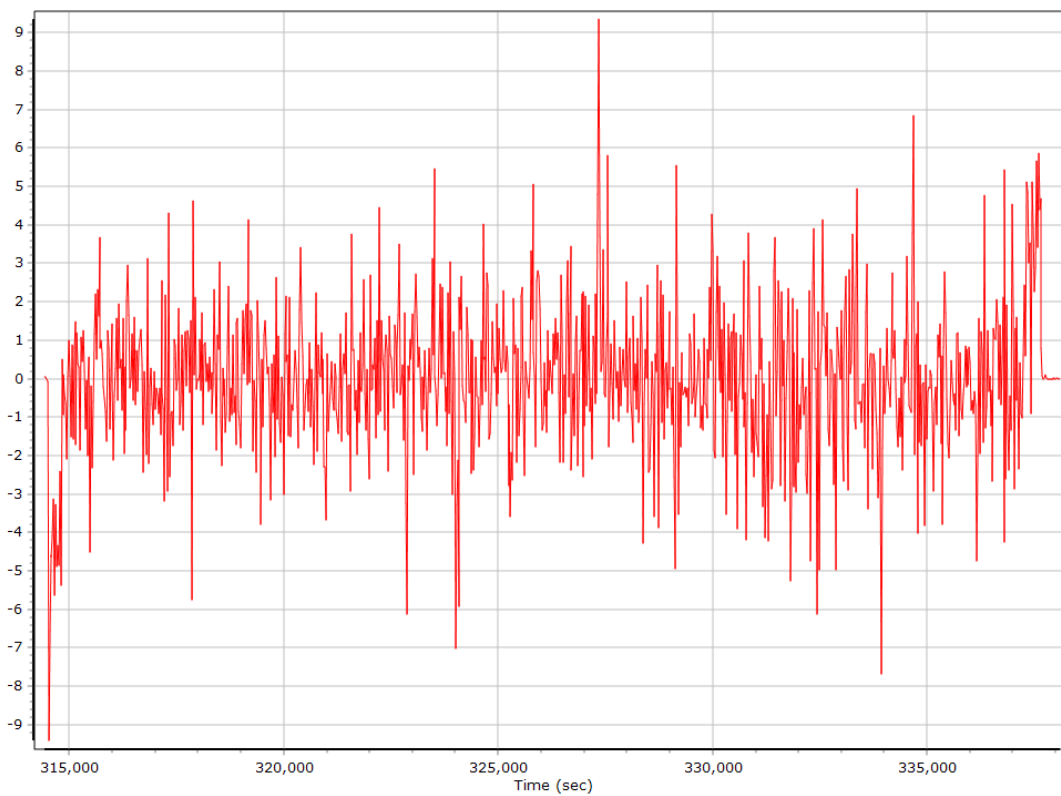
Heading



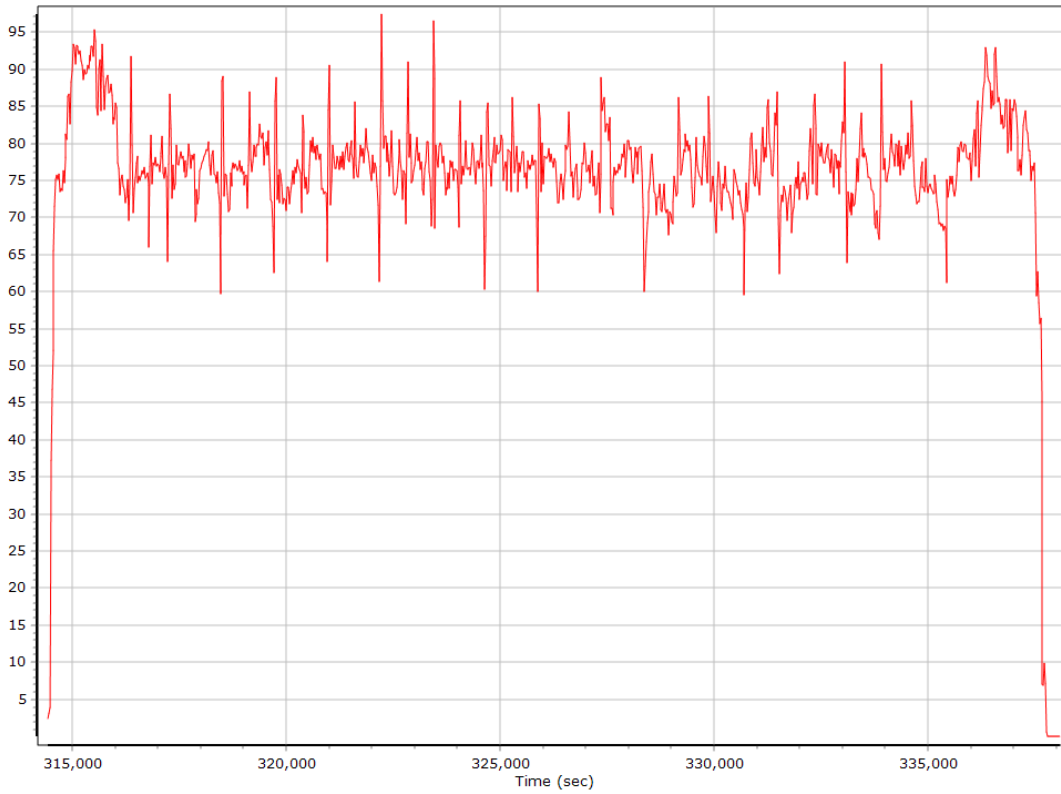
North/East Velocity



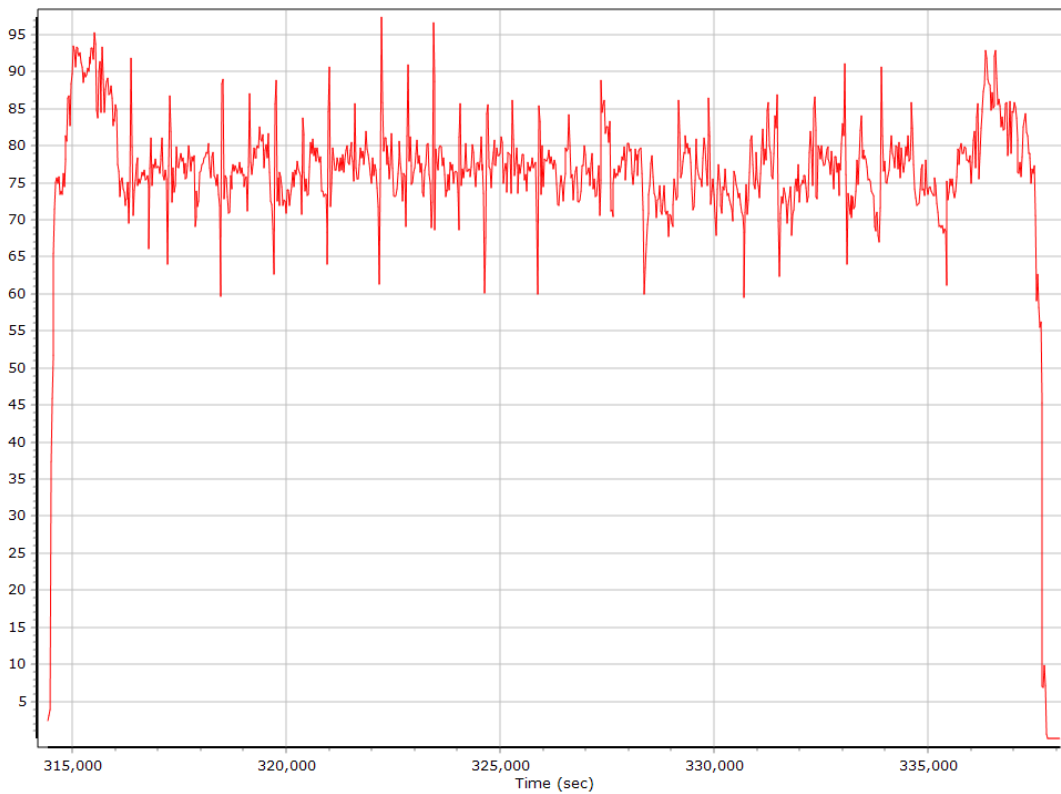
Down Velocity



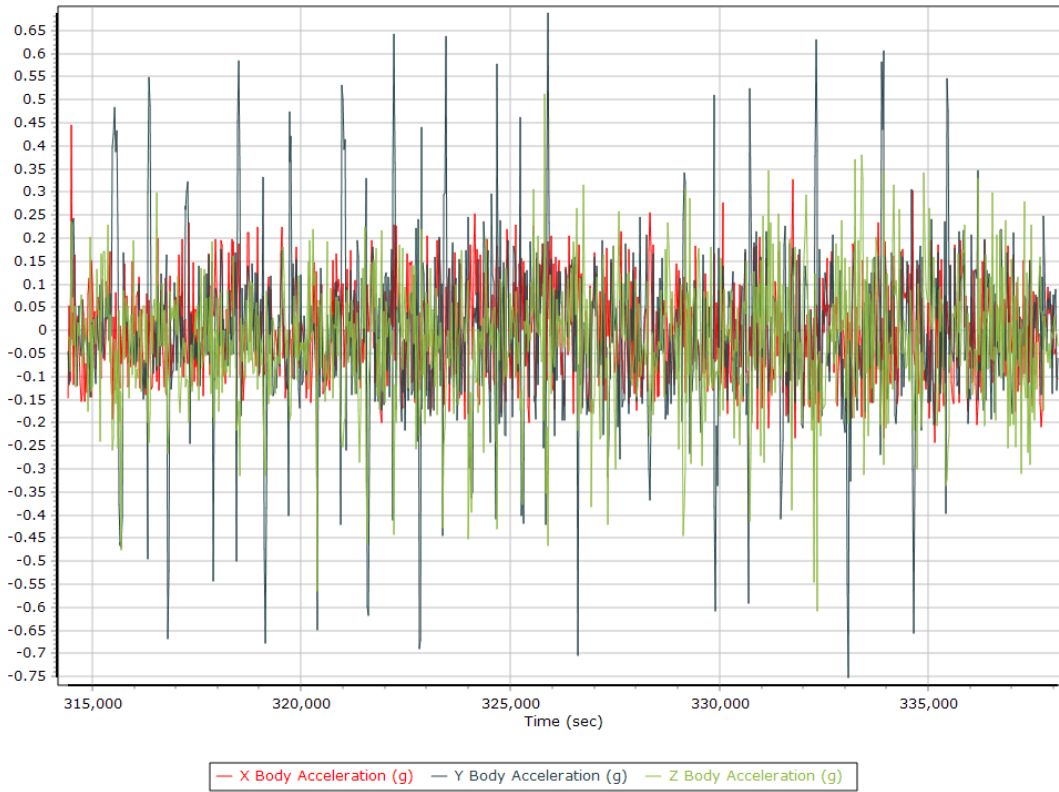
Total Speed



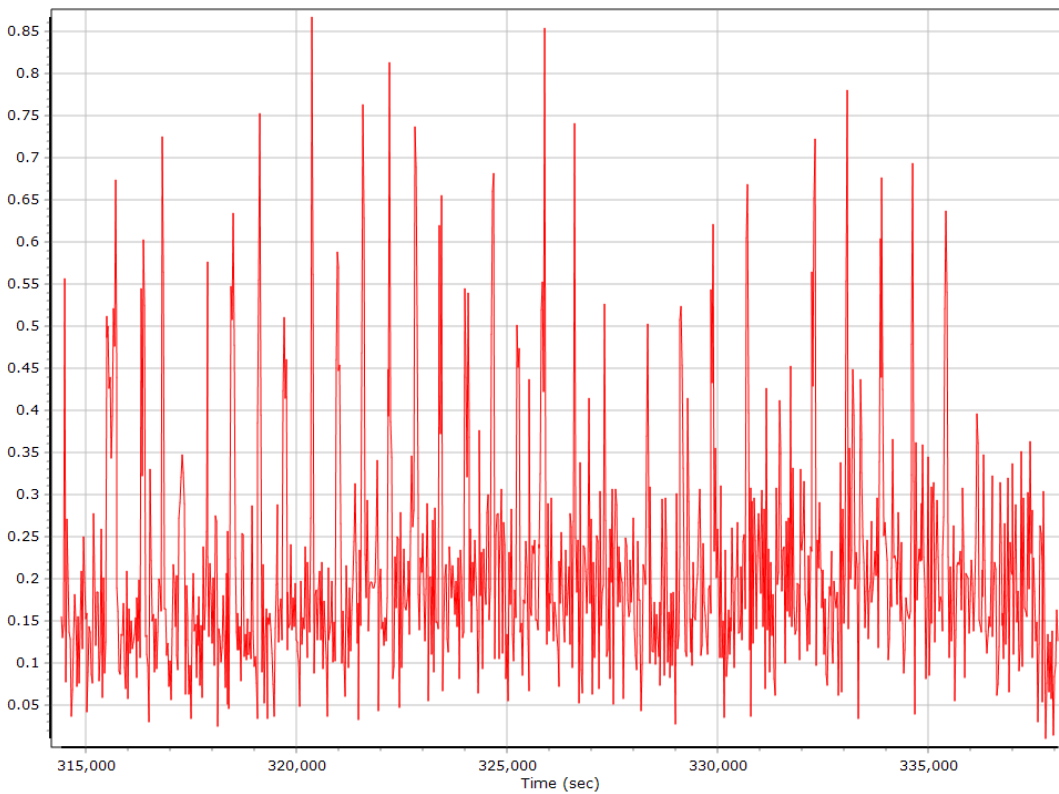
Ground Speed



Body Acceleration



Total Body Acceleration



Body Angular Rate



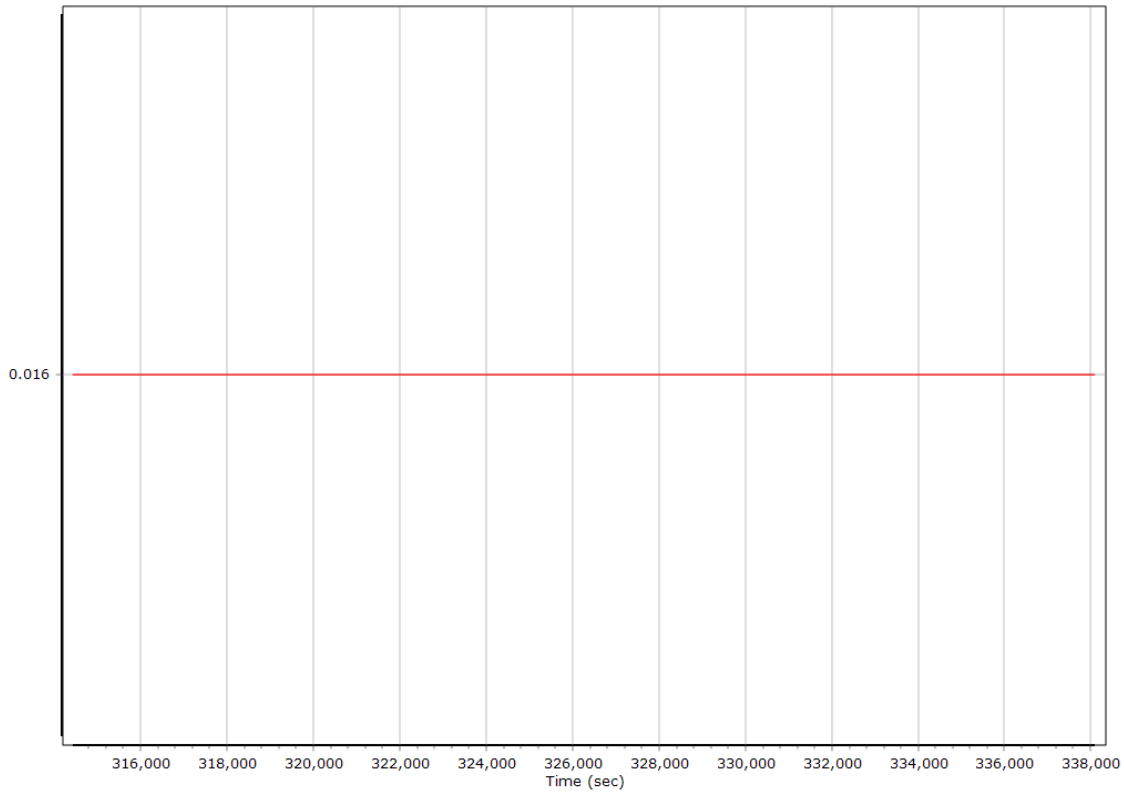
GNSS-Inertial Processor Configuration

Processing mode	IN-Fusion Trimble RTX Nav		
Stabilized mount	False		
Processing start time	314089.043 (09/22/2021 15:14:49)		
Processing end time	338106.000 (09/22/2021 21:55:06)		
Initial attitude source	Real-Time VNAV/RNAV Attitude		
IMU Sensor Context	Processing with Onboard IMU		
Reference to IMU lever arm (m)	0.000	0.000	0.000
Reference to IMU mounting angles (deg)	0.000	0.000	0.000
Reference to Primary GNSS lever arm (m)	0.016	0.063	-0.958
Reference to Primary GNSS lever arm std dev (m)	0.030	0.030	0.030
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

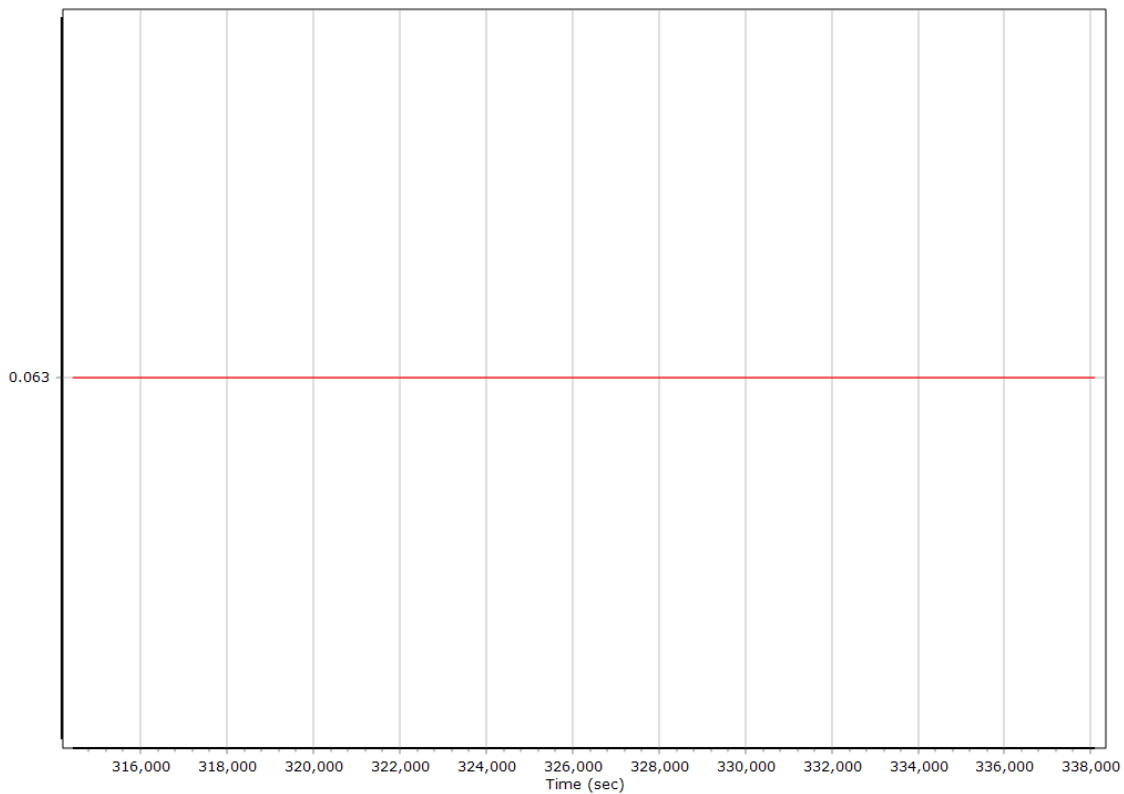
Calibrated Installation Parameters

Reference-Primary GNSS Lever Arm (m)

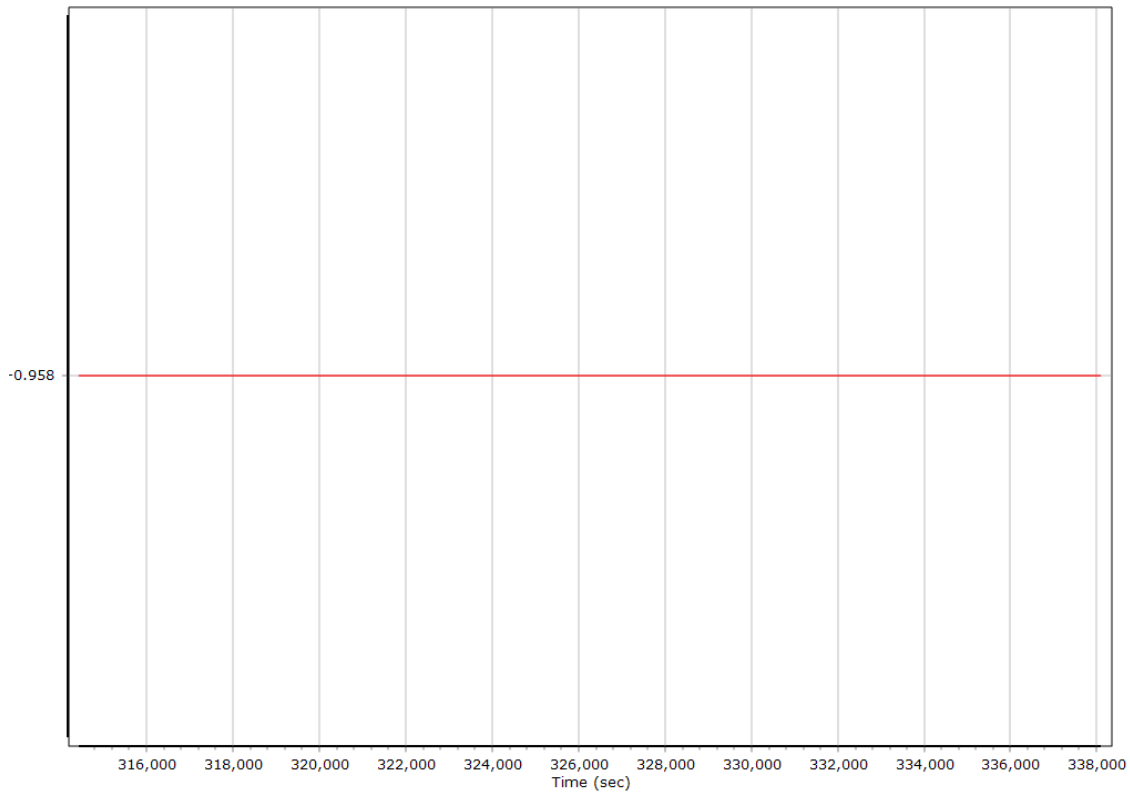
X Reference-Primary GNSS Lever Arm (m)



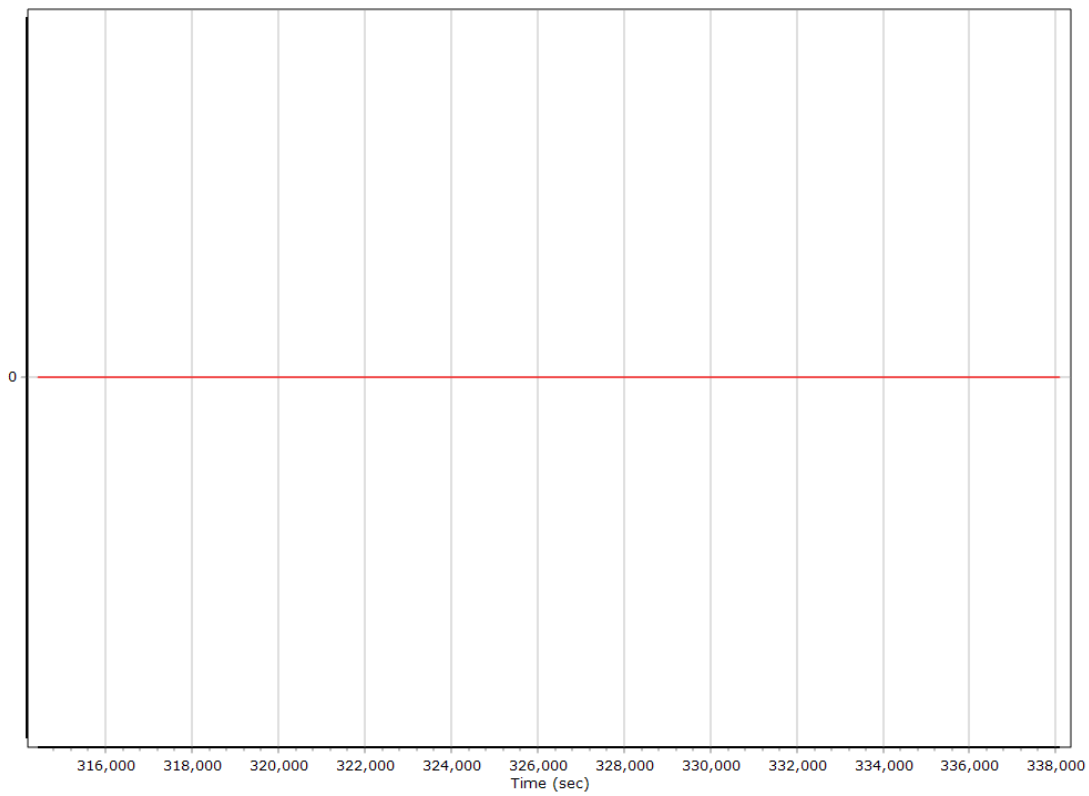
Y Reference-Primary GNSS Lever Arm (m)



Z Reference-Primary GNSS Lever Arm (m)



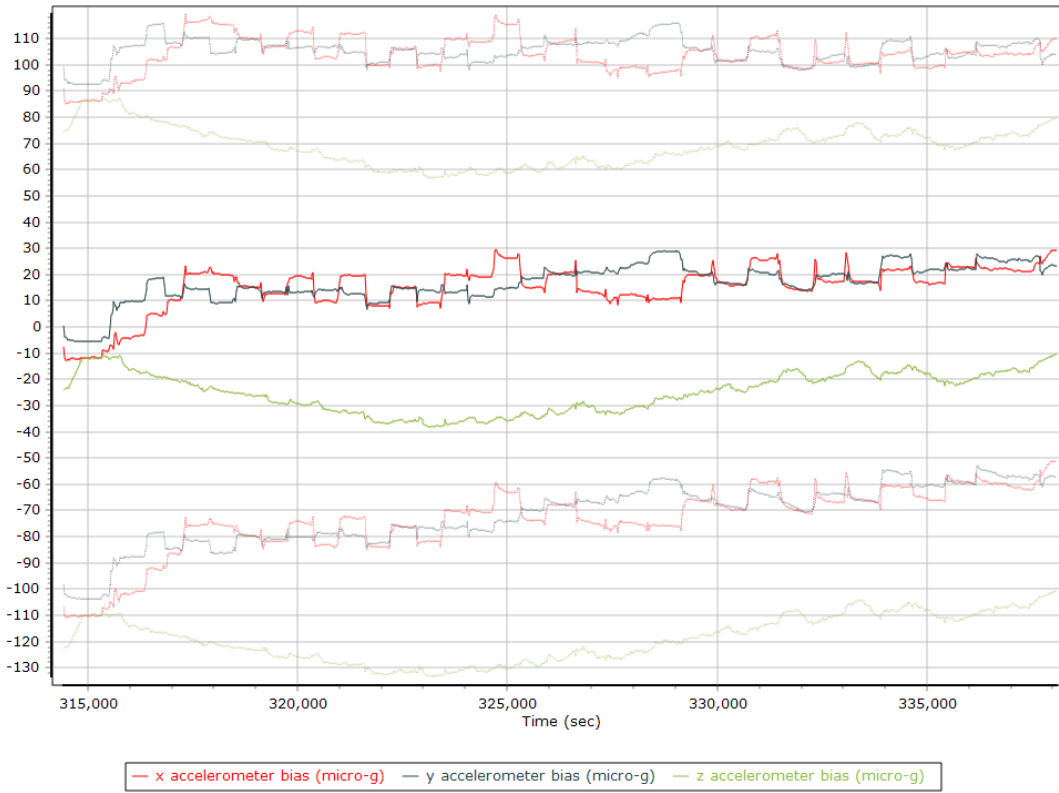
Reference-Primary GNSS Lever Arm Figure of Merit



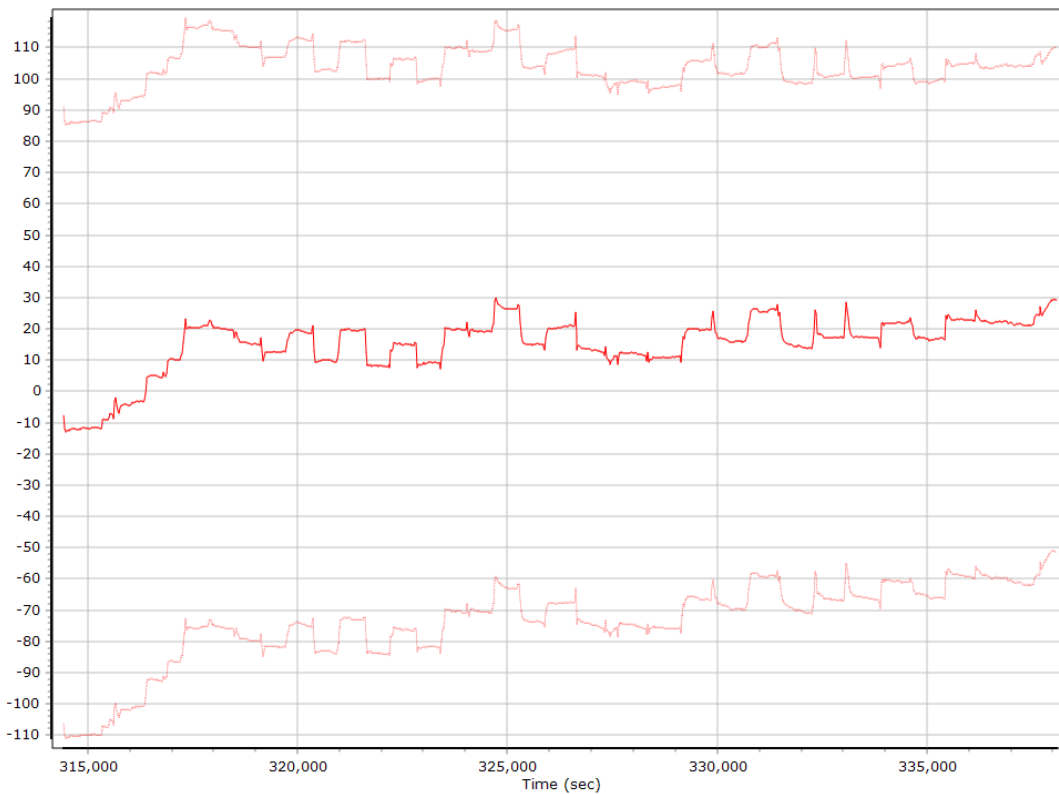
IN-Fusion QC

Forward Processed Estimated Errors, Reference Frame

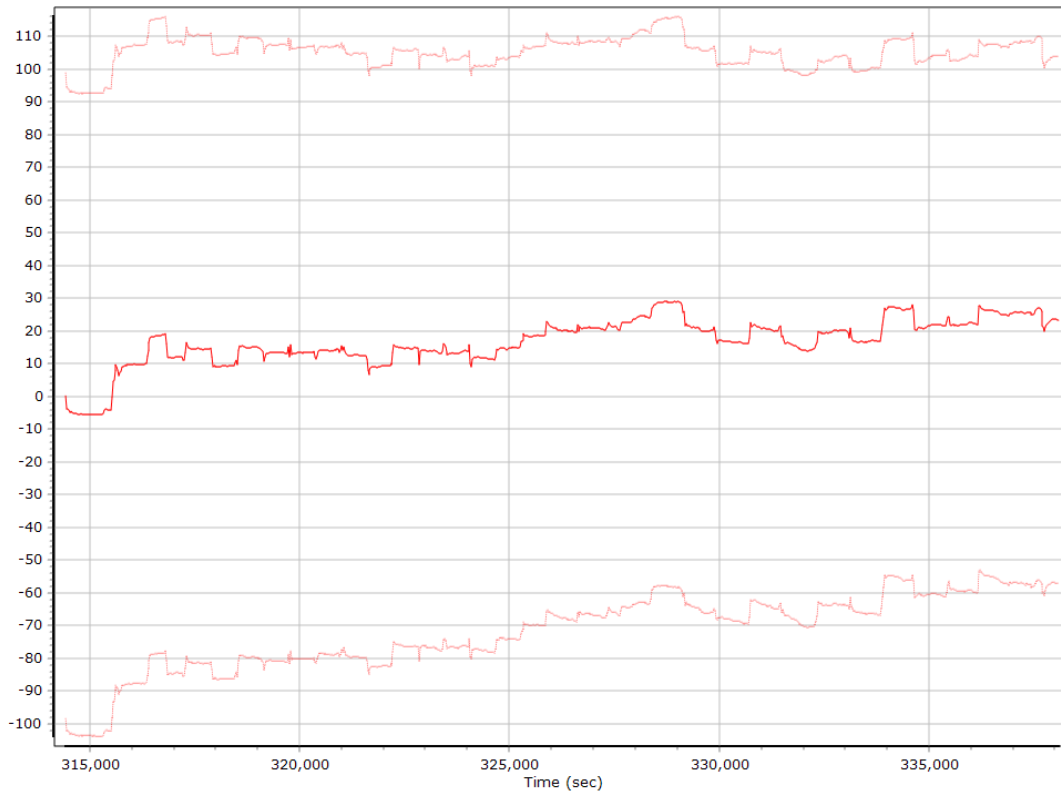
Accelerometer Bias (micro-g)



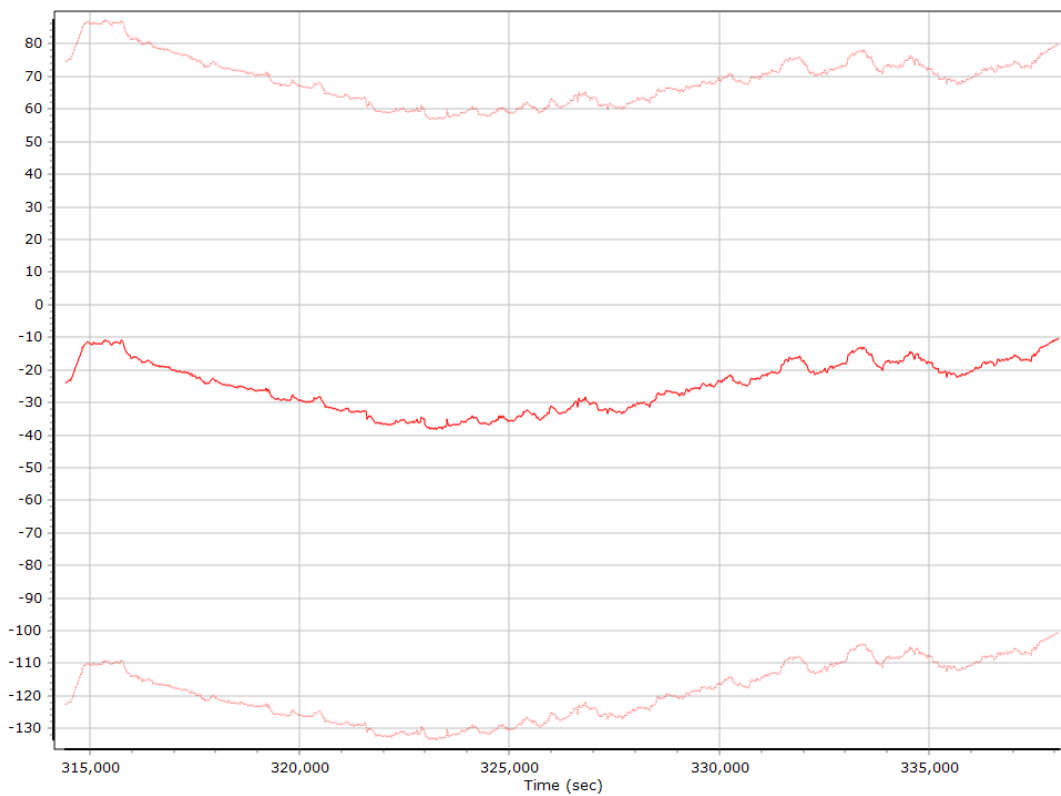
X Accelerometer Bias (micro-g)



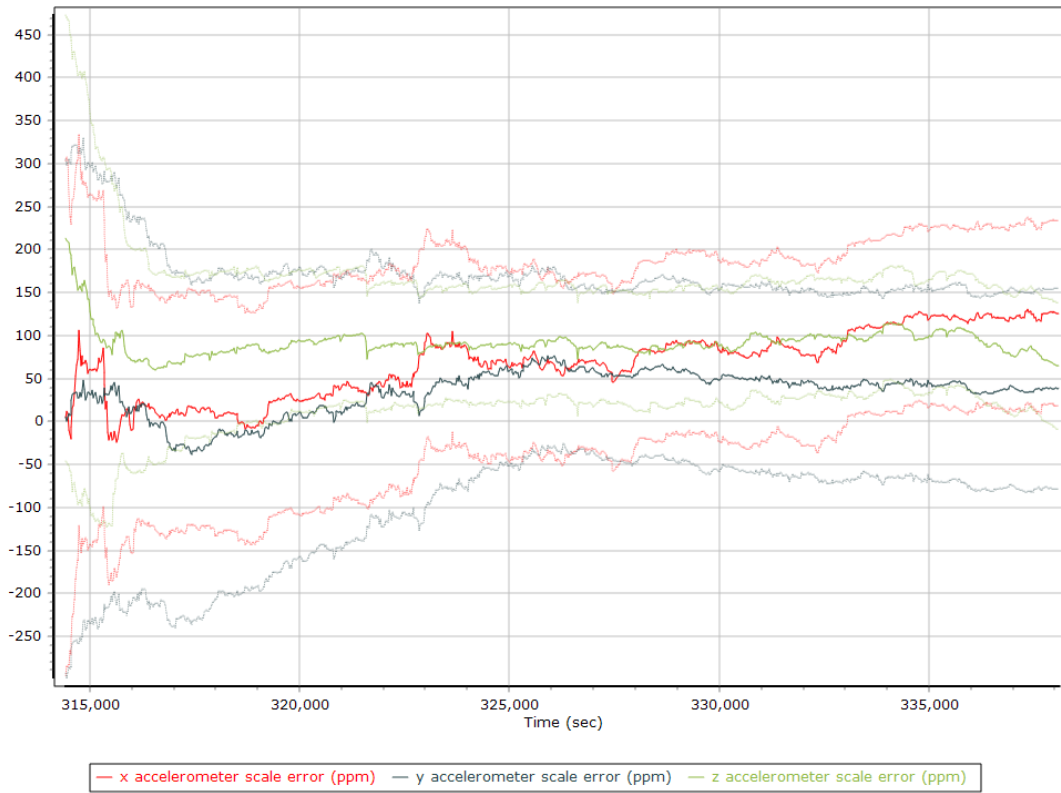
Y Accelerometer Bias (micro-g)



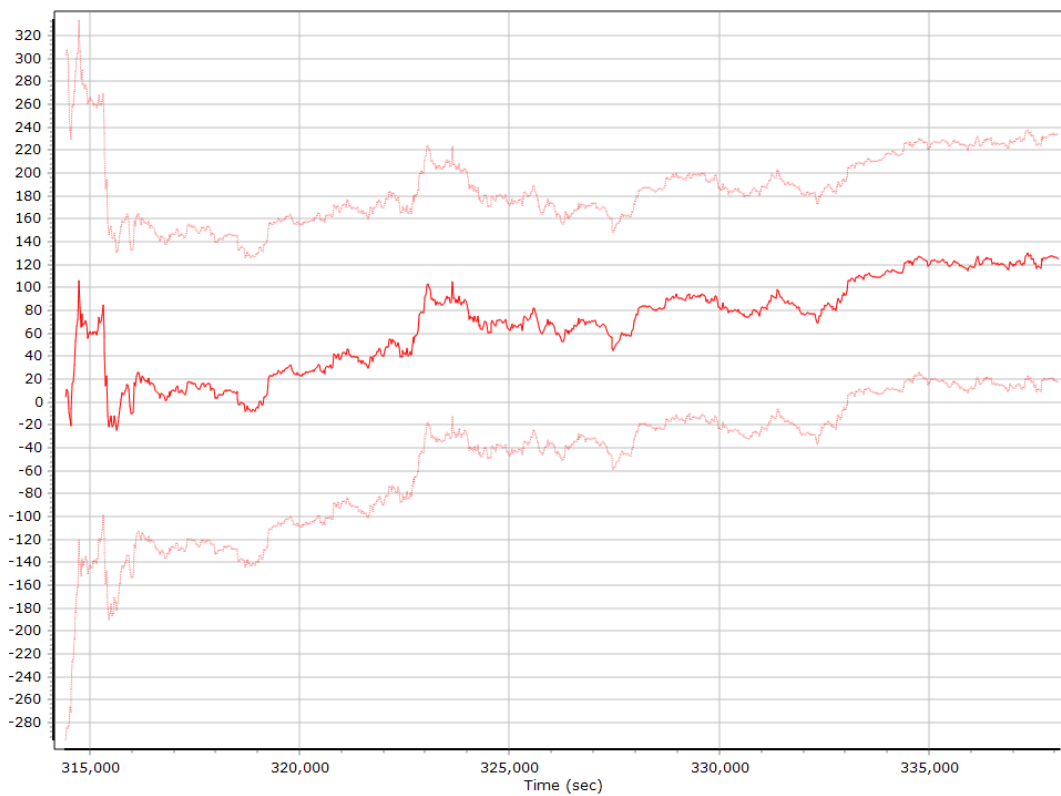
Z Accelerometer Bias (micro-g)



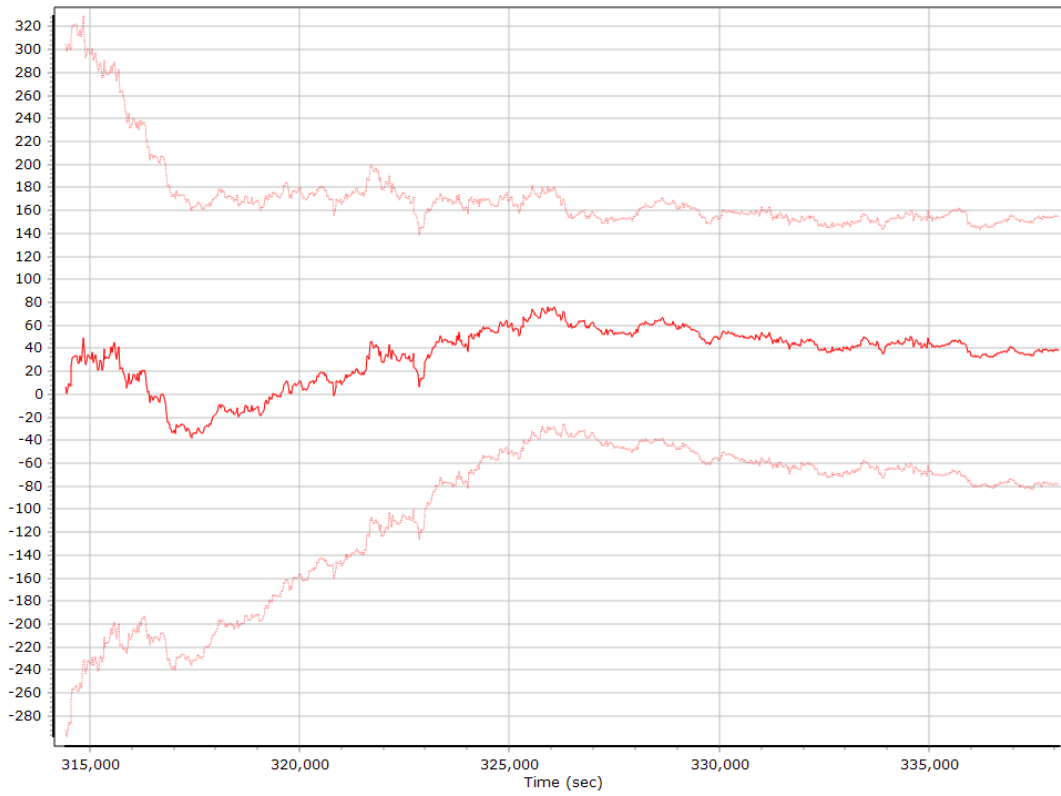
Accelerometer Scale Error (ppm)



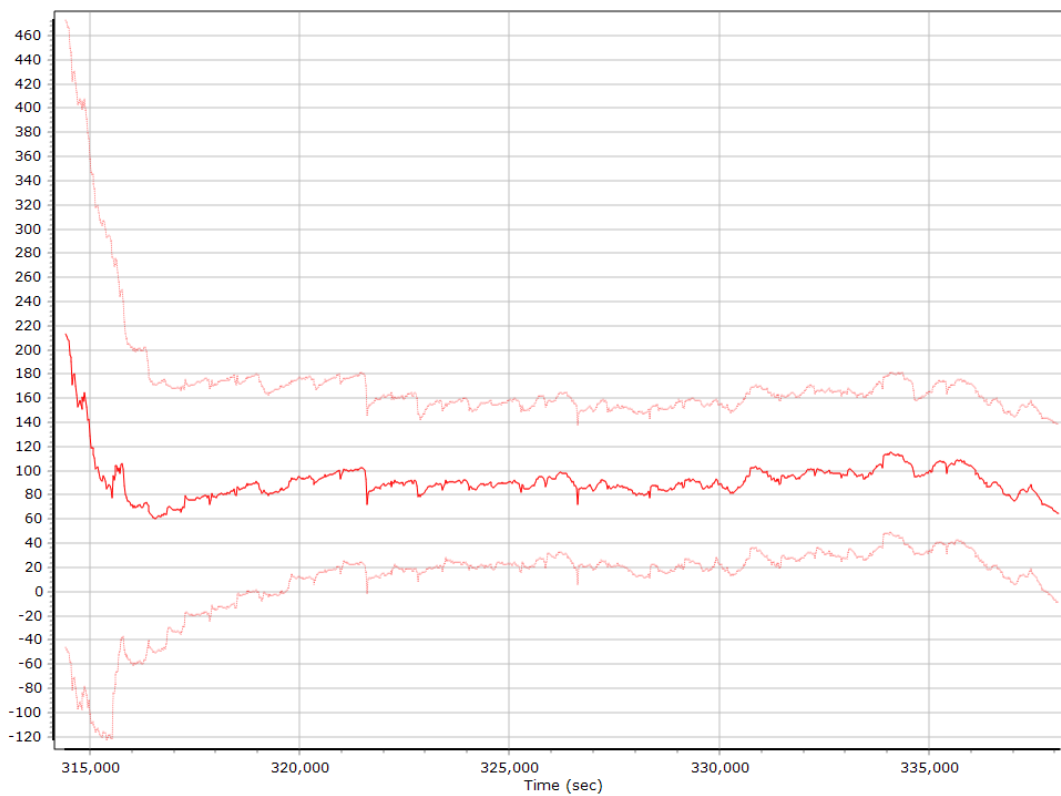
X Accelerometer Scale Error (ppm)



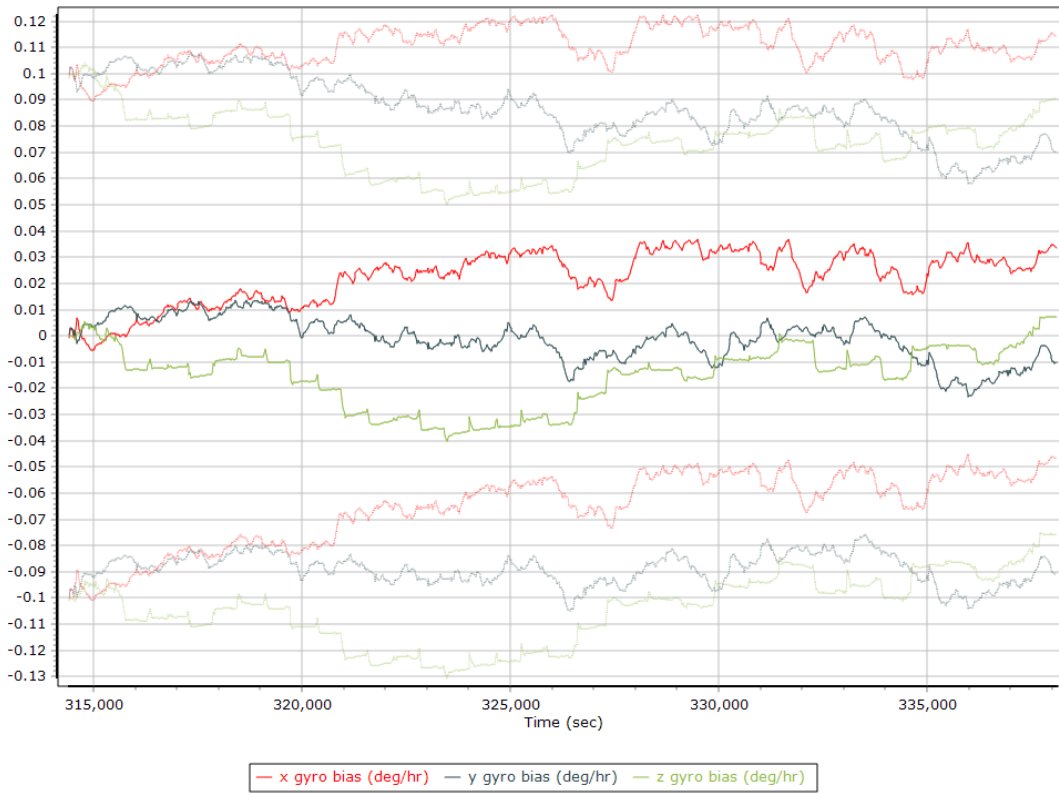
Y Accelerometer Scale Error (ppm)



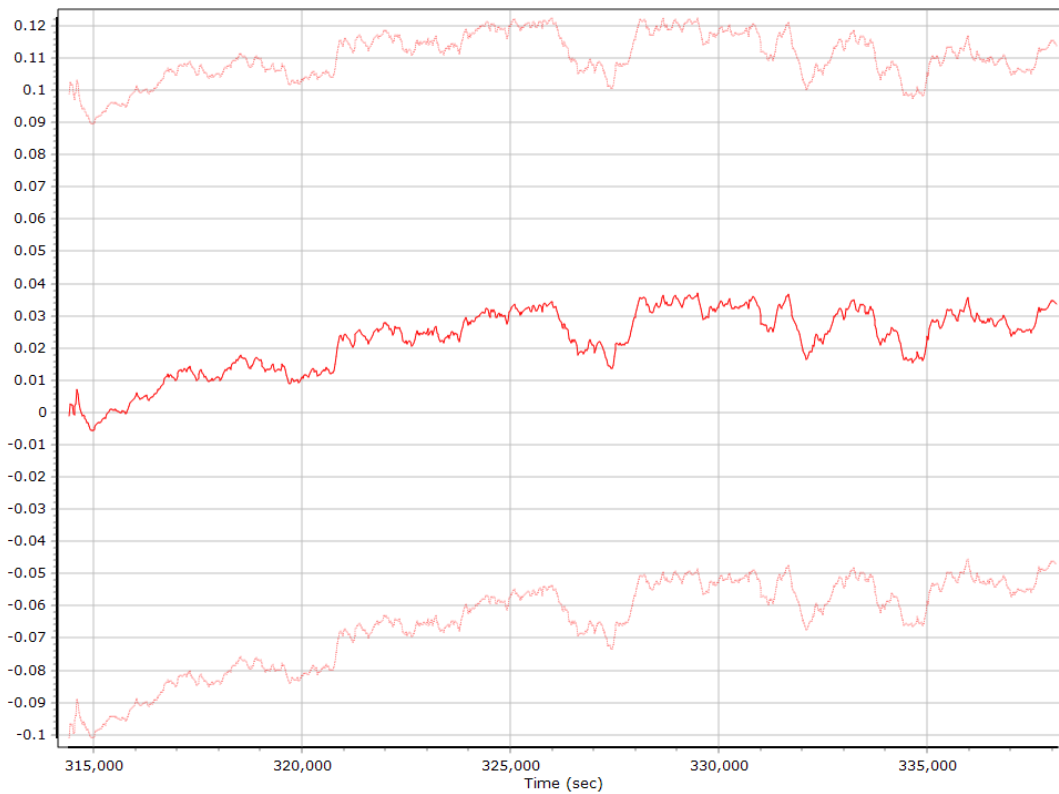
Z Accelerometer Scale Error (ppm)



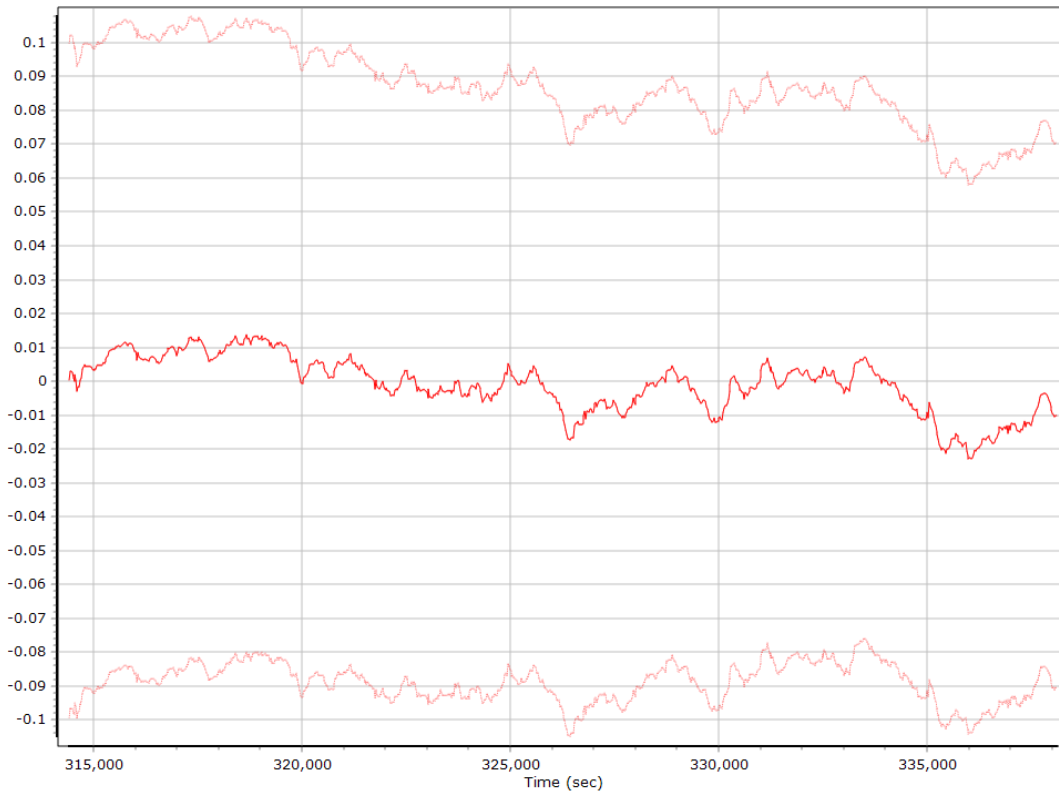
Gyro Bias (deg/h)



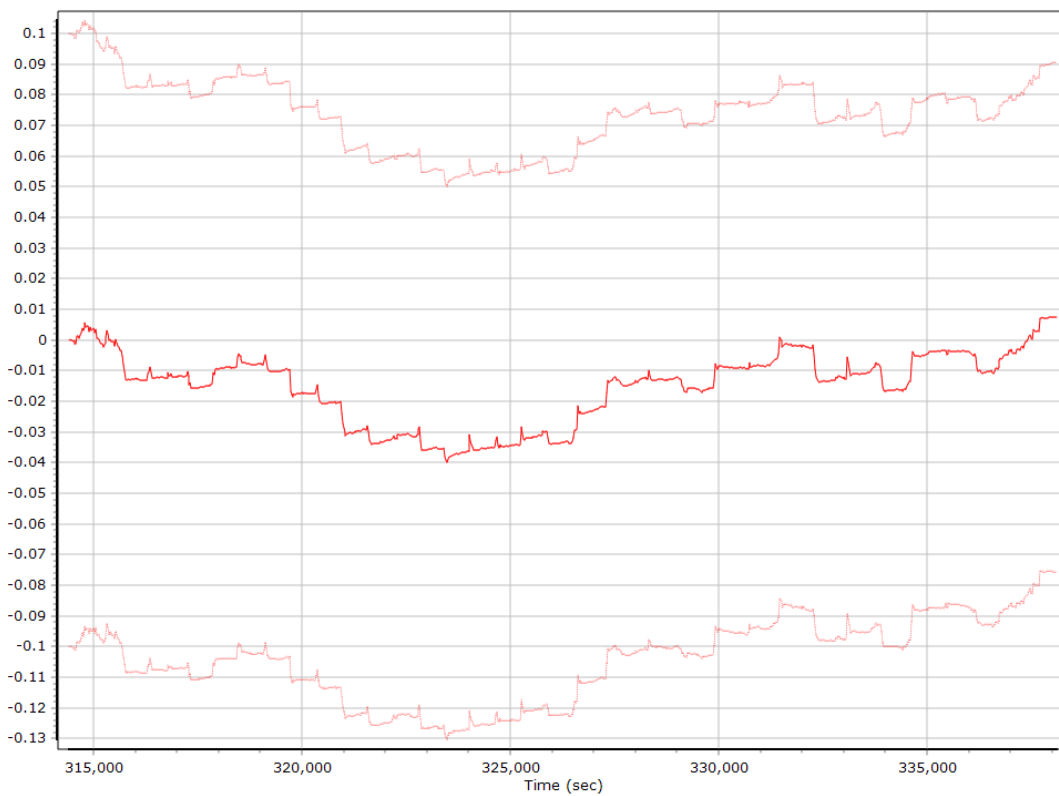
X Gyro Bias (deg/h)



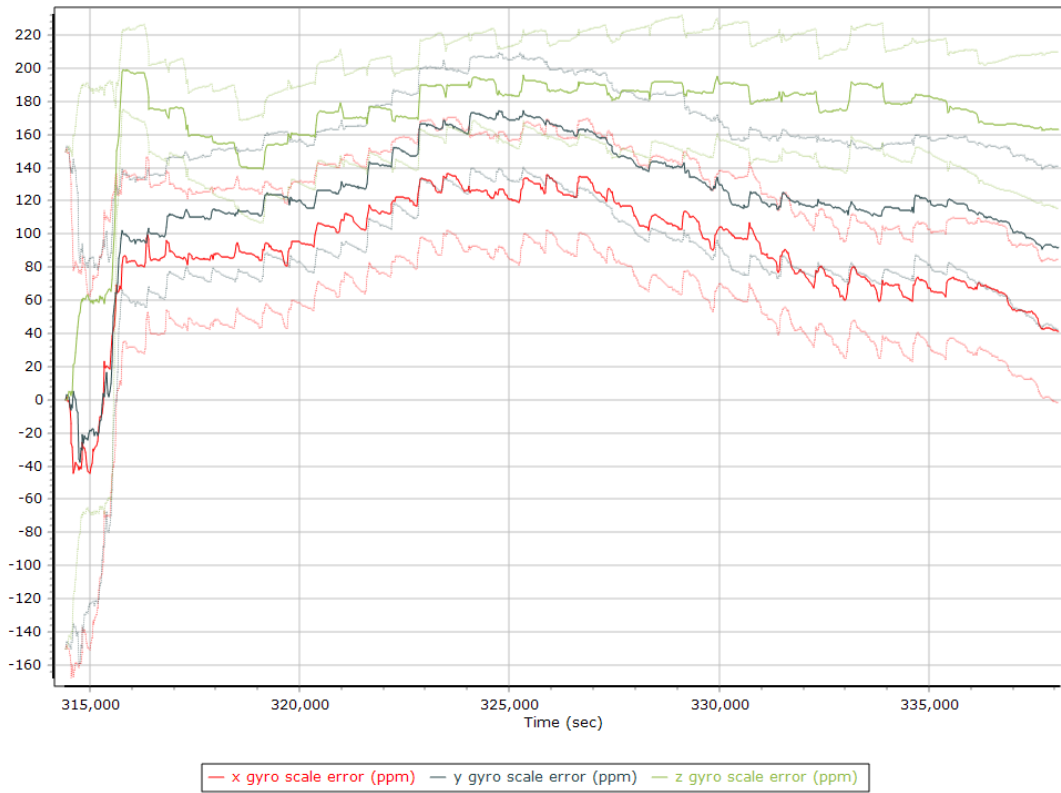
Y Gyro Bias (deg/h)



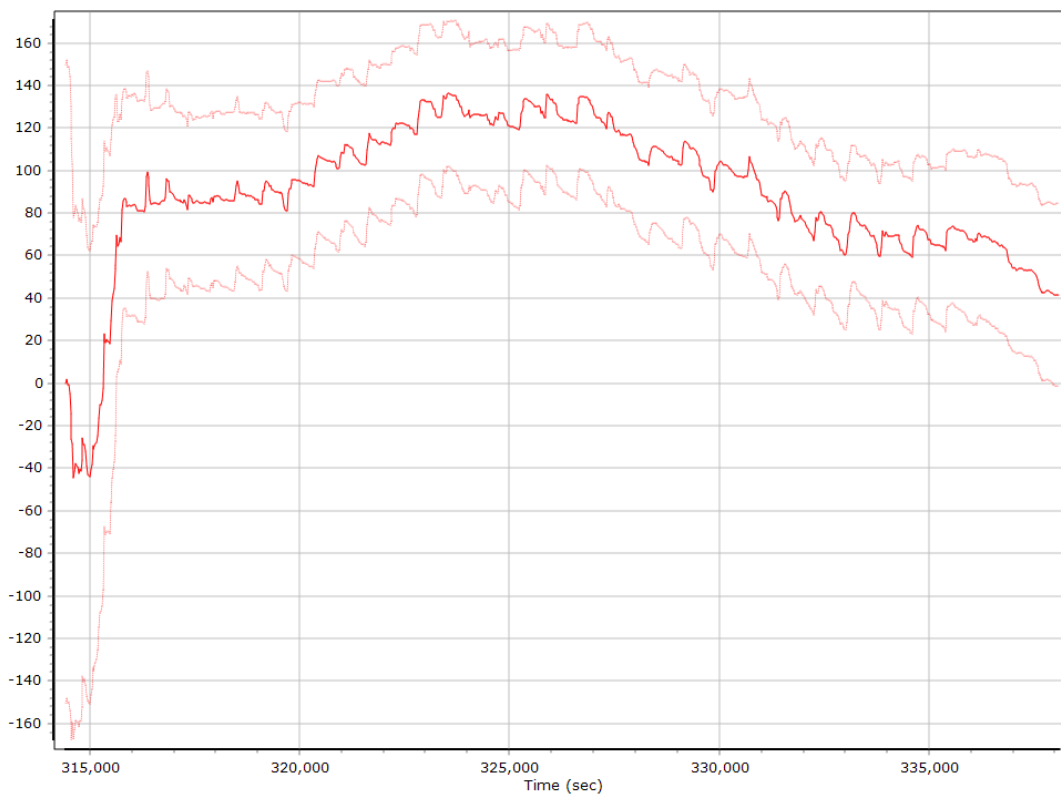
Z Gyro Bias (deg/h)



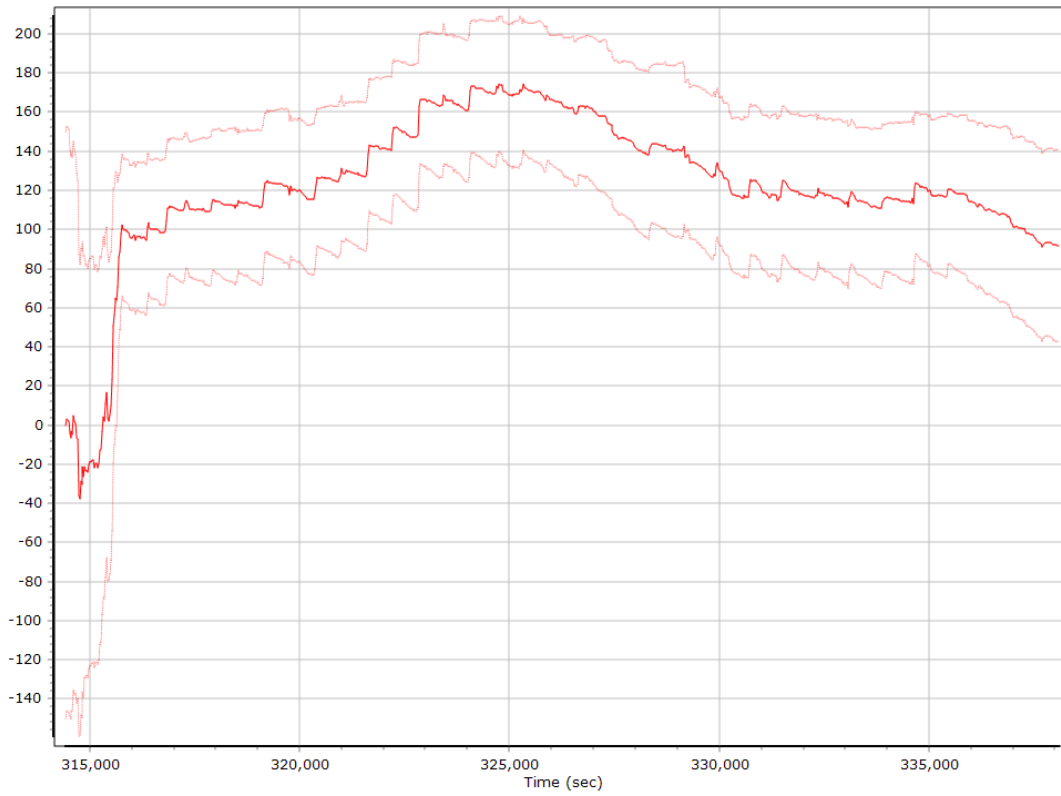
Gyro Scale Error (ppm)



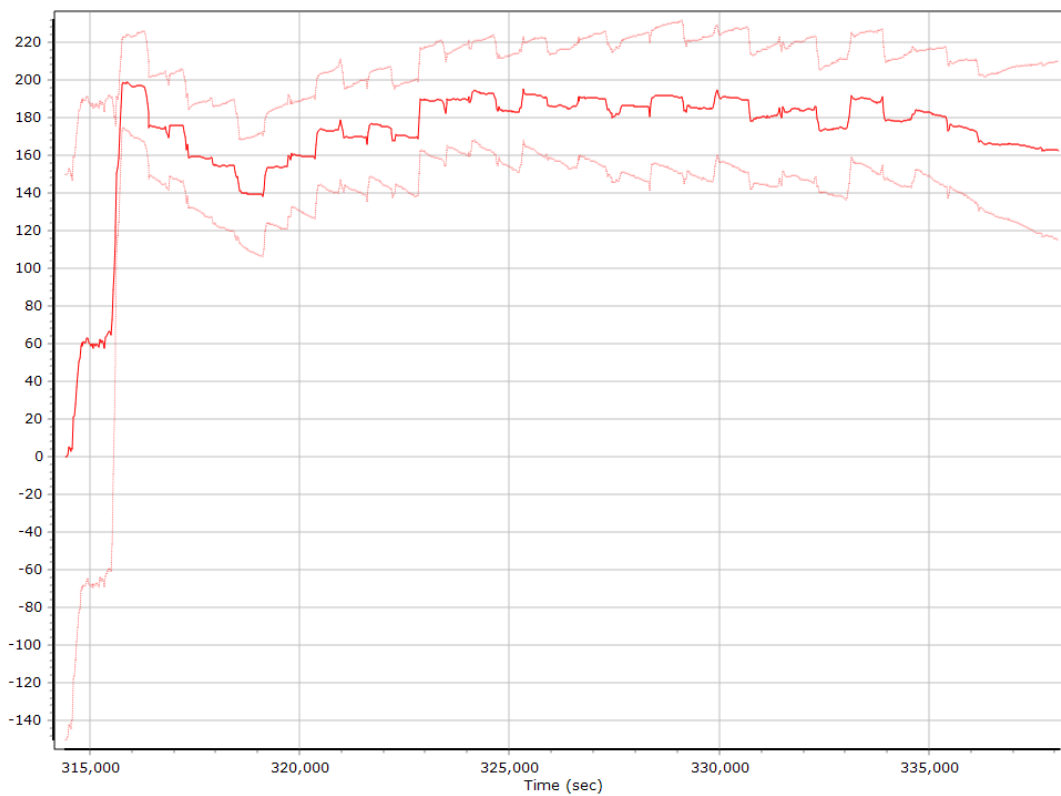
X Gyro Scale Error (ppm)



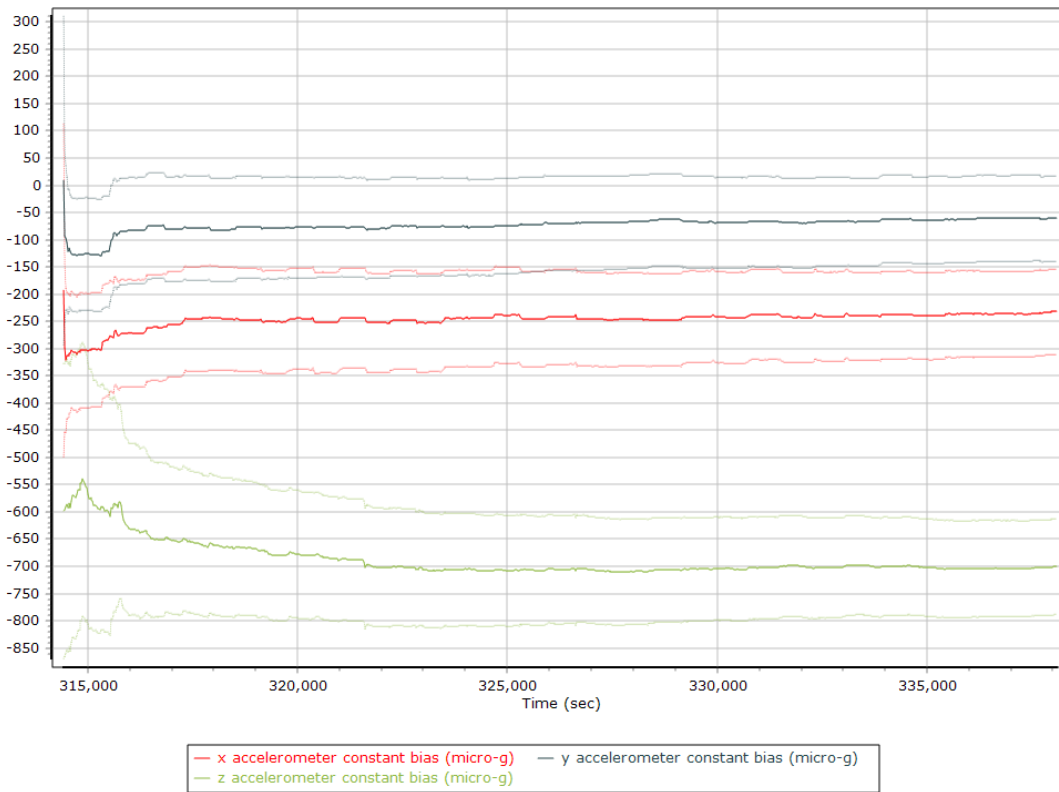
Y Gyro Scale Error (ppm)



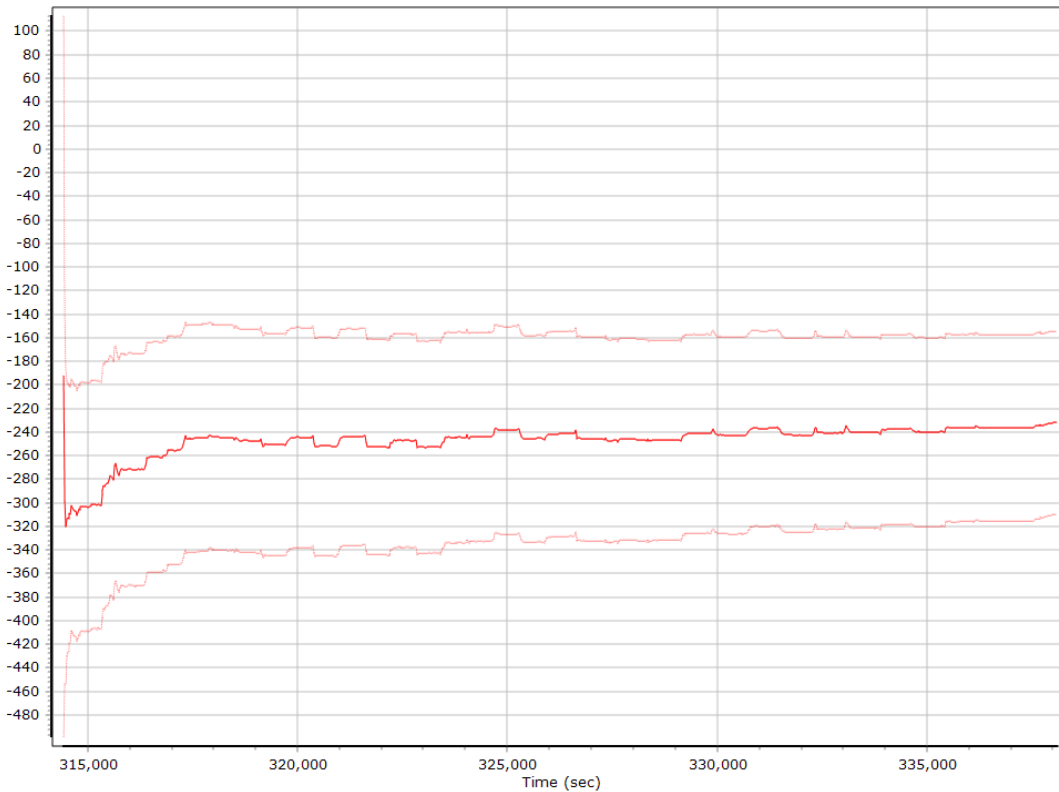
Z Gyro Scale Error (ppm)



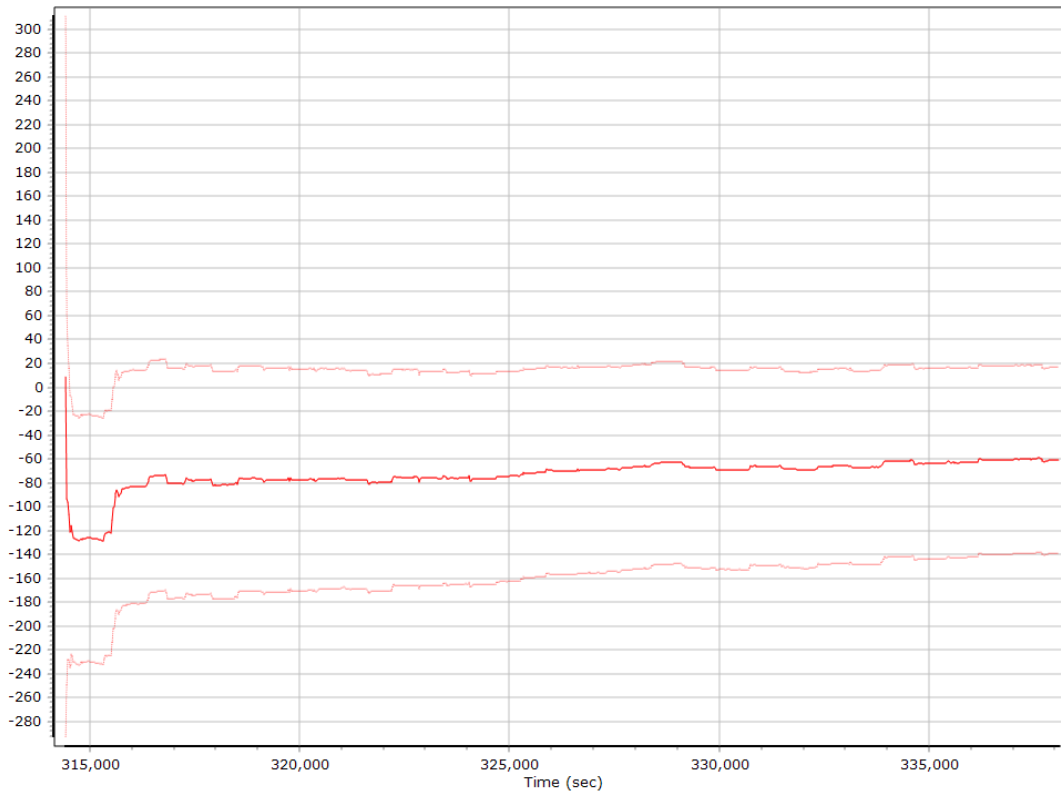
Forward Processed Estimated Constant Errors, Reference Frame Accelerometer Bias (micro-g)



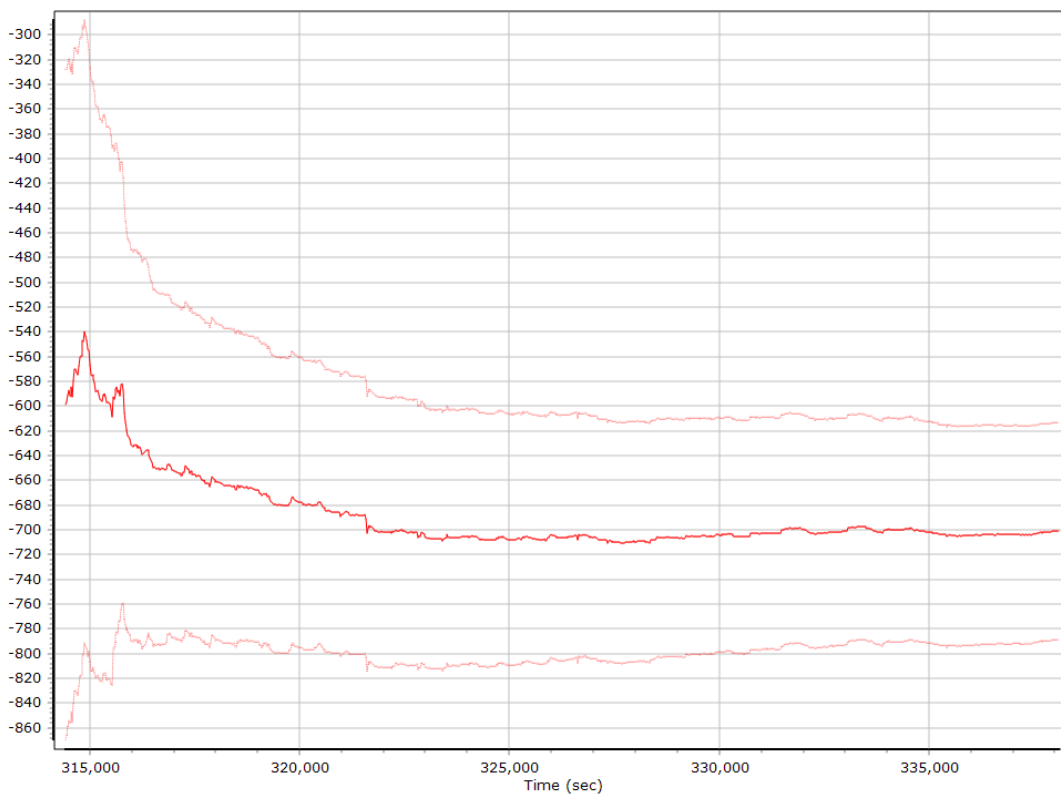
X Accelerometer Bias (micro-g)



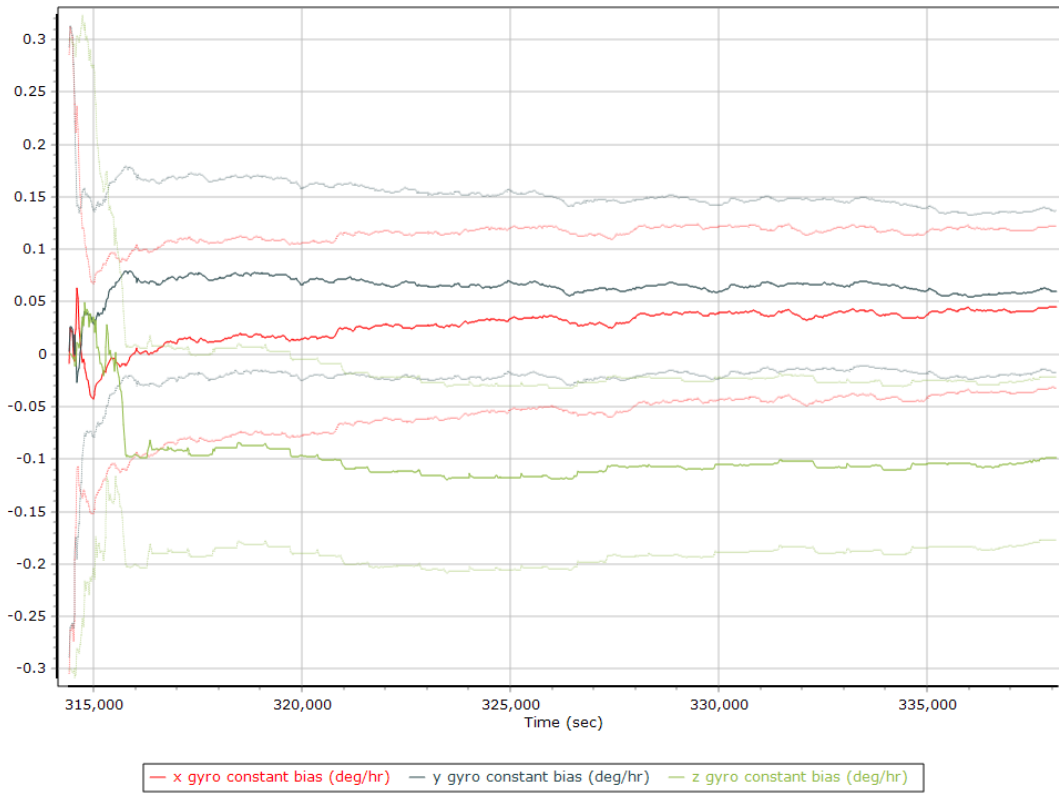
Y Accelerometer Bias (micro-g)



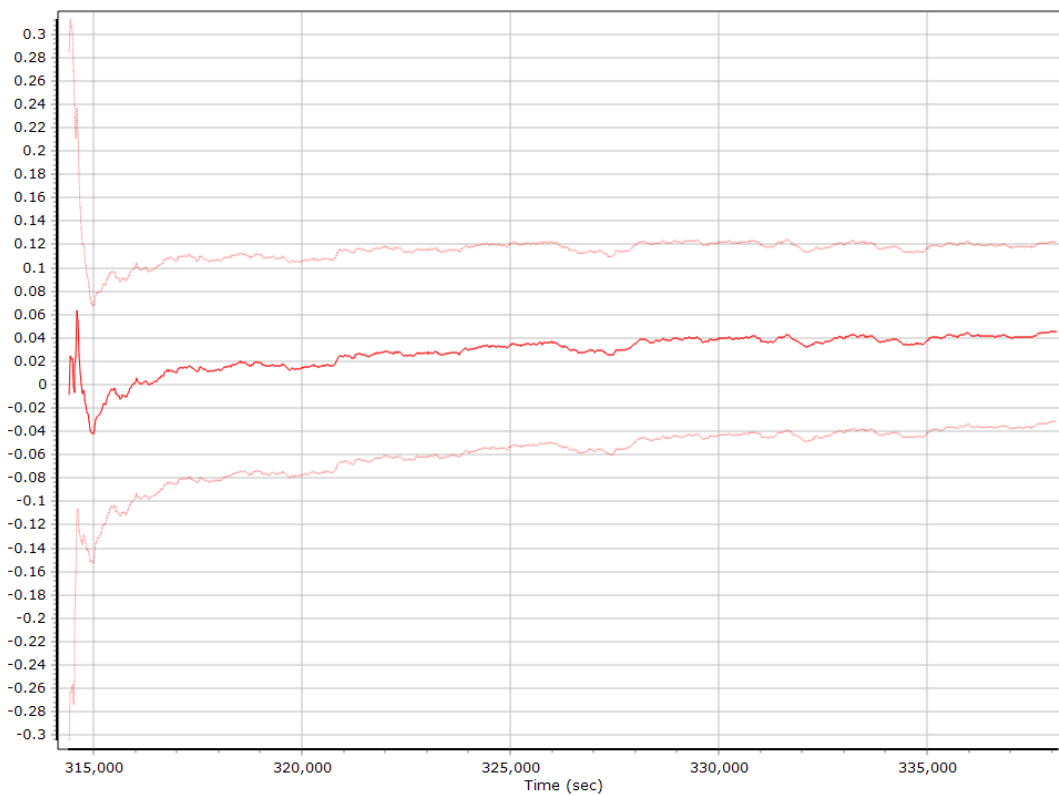
Z Accelerometer Bias (micro-g)



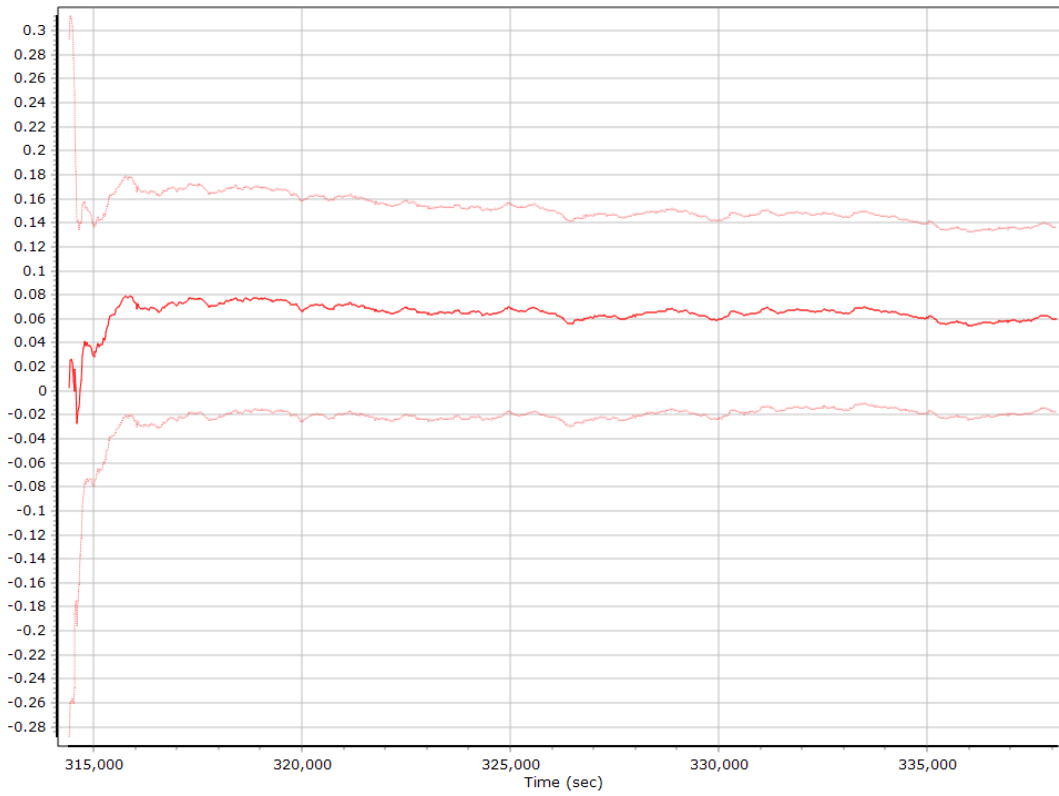
Gyro Bias (deg/h)



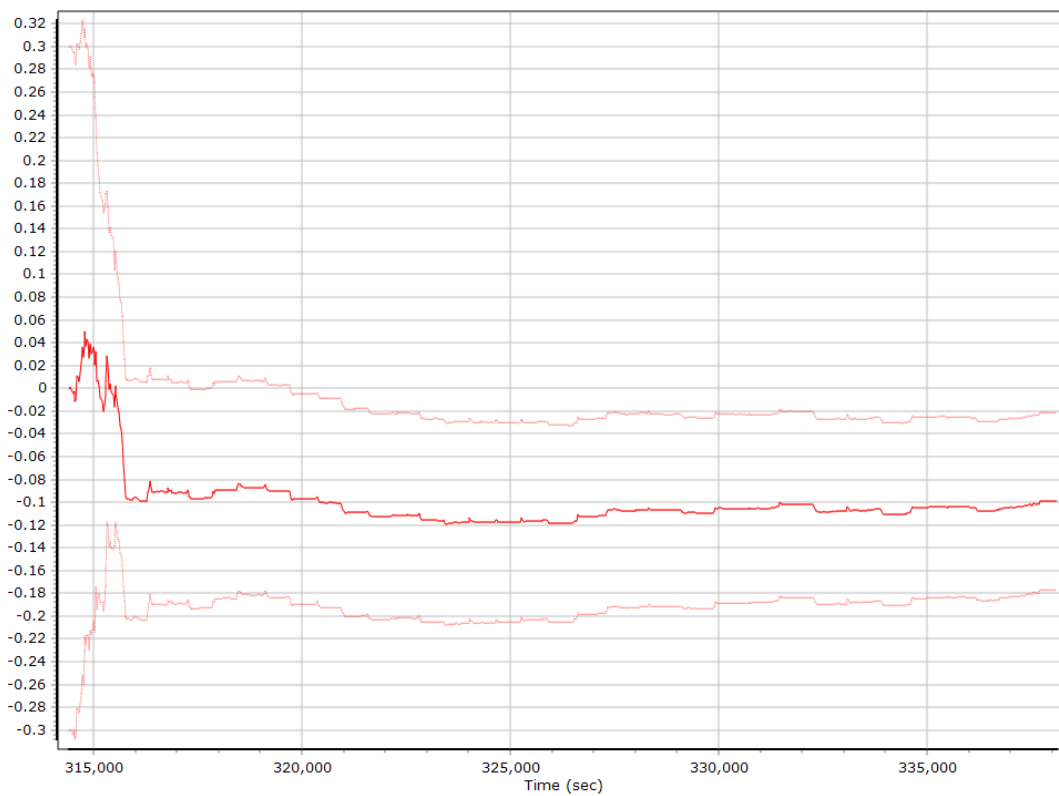
X Gyro Bias (deg/h)



Y Gyro Bias (deg/h)

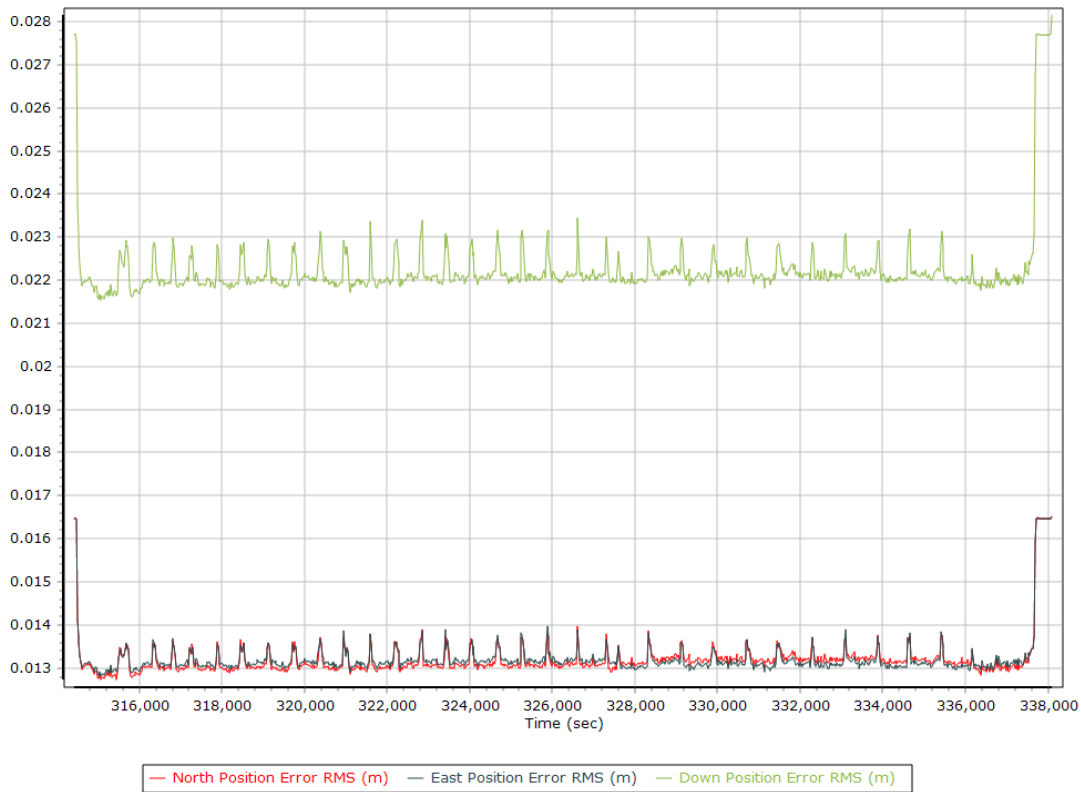


Z Gyro Bias (deg/h)

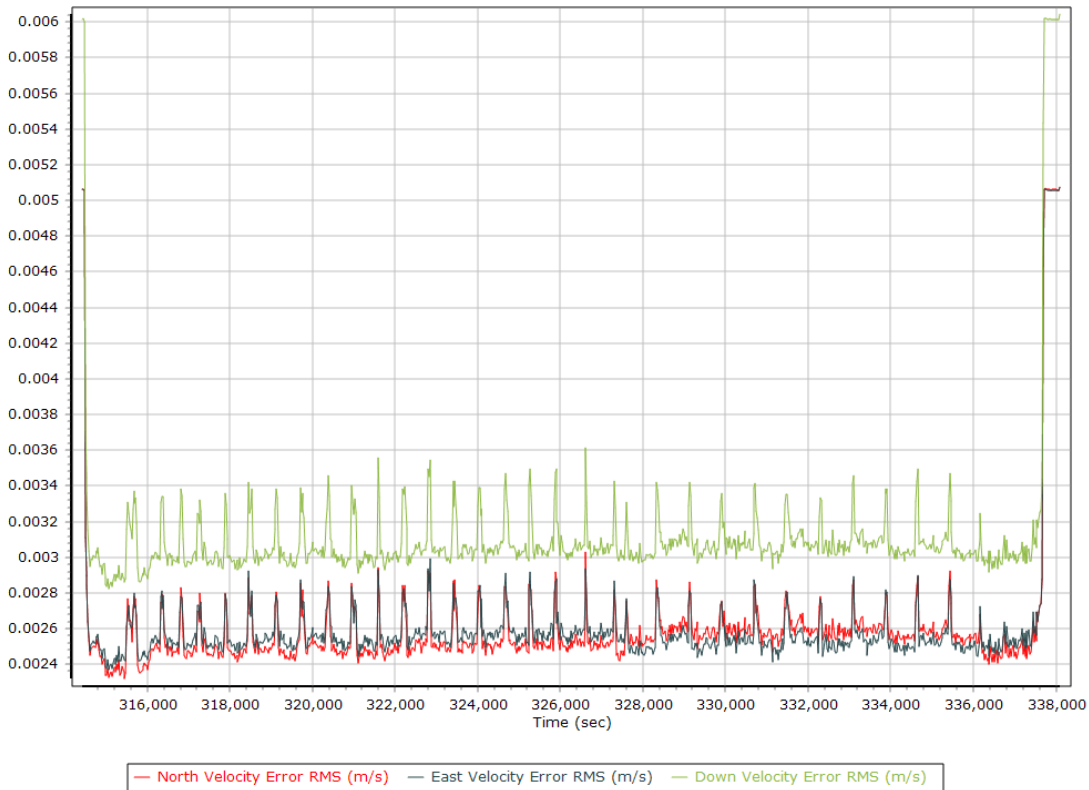


Smoothed Performance Metrics

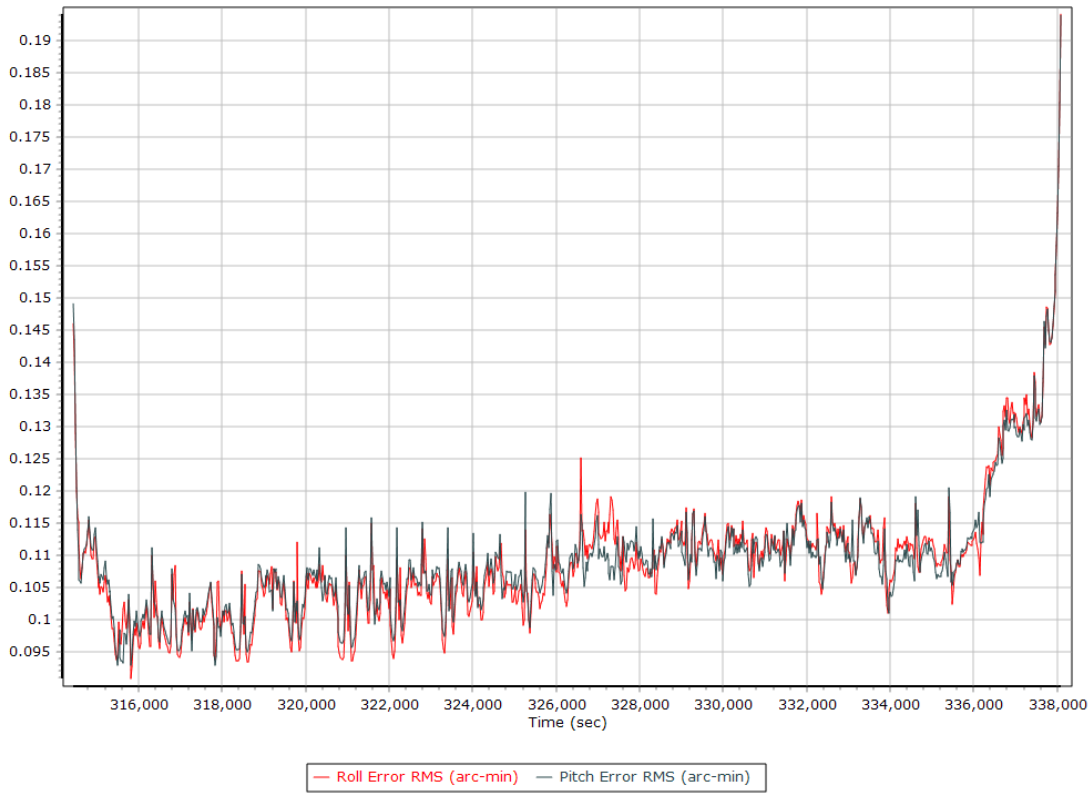
Position Error RMS (m)



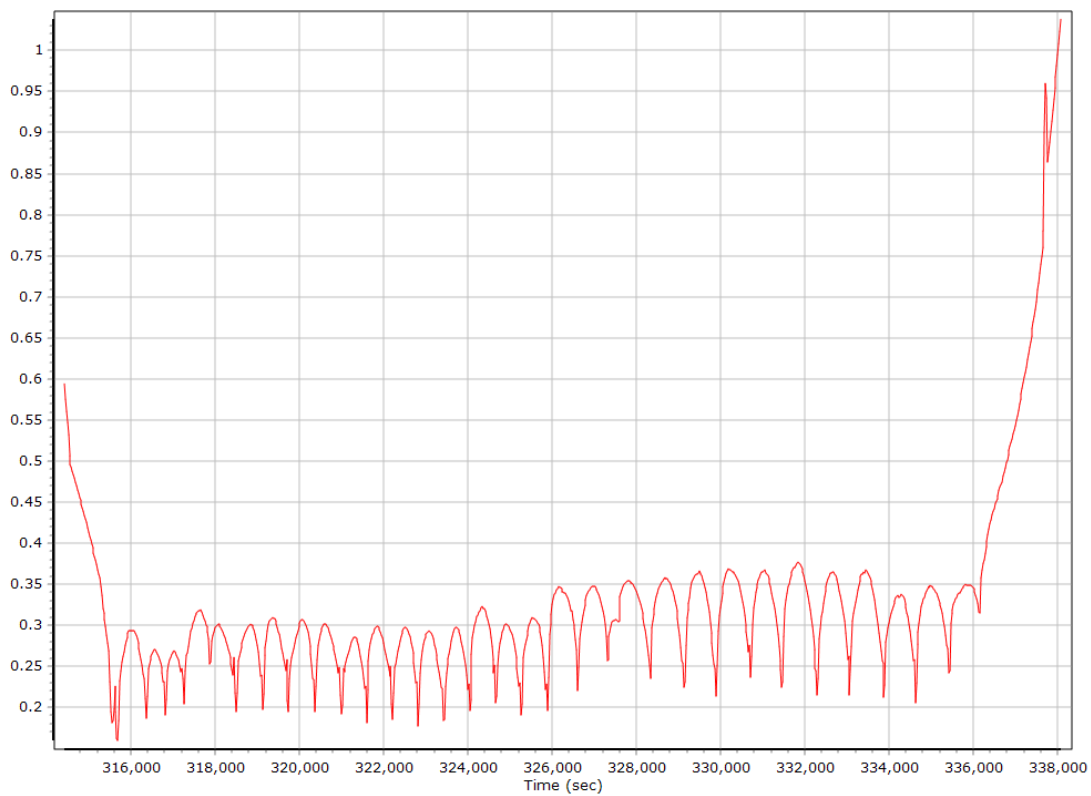
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

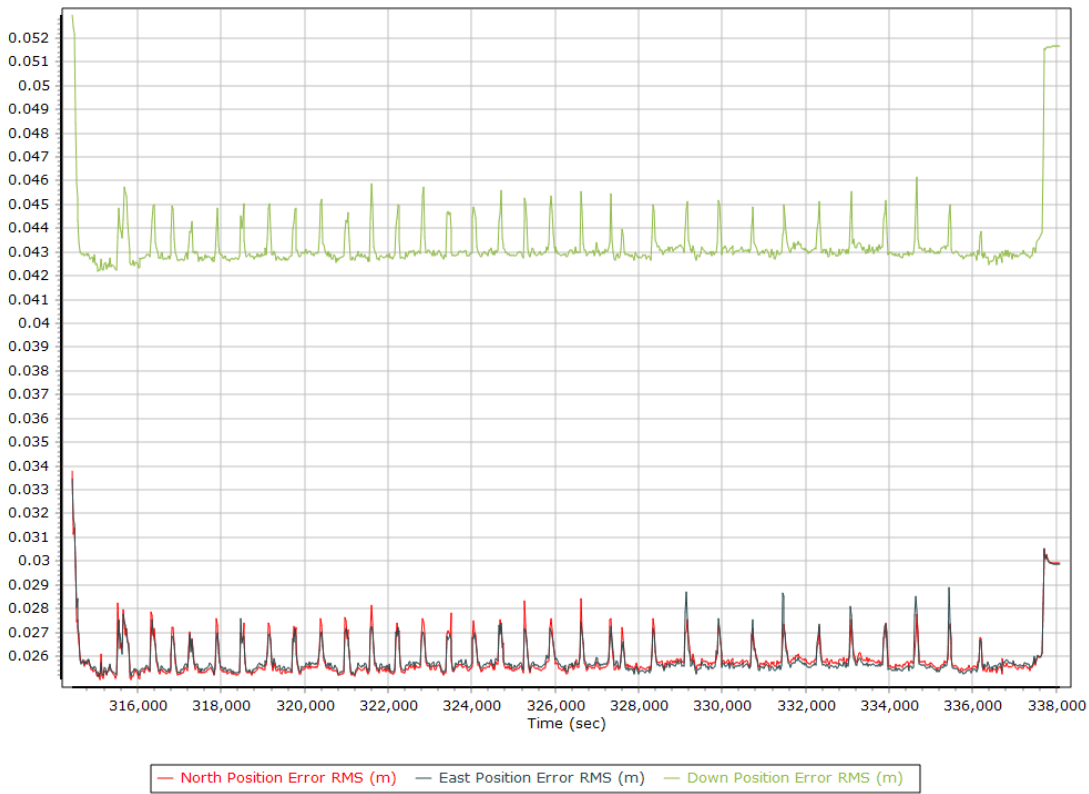


Heading Error RMS (arc-min)

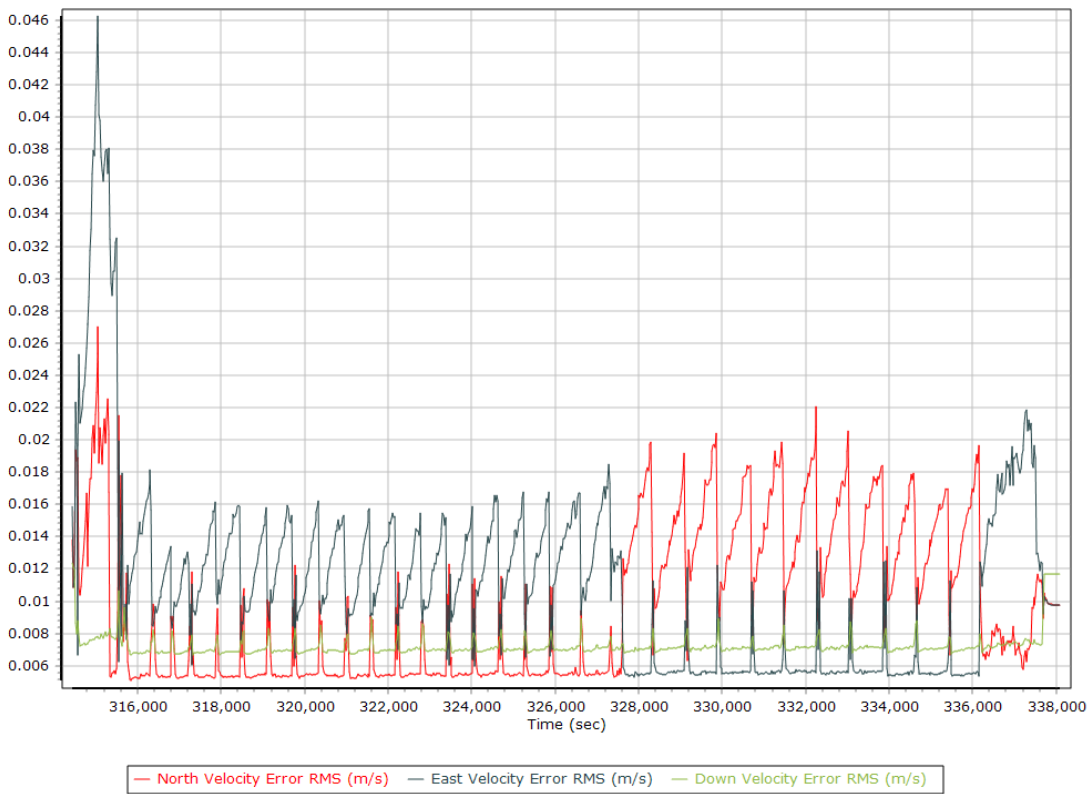


Forward Processed Performance Metrics

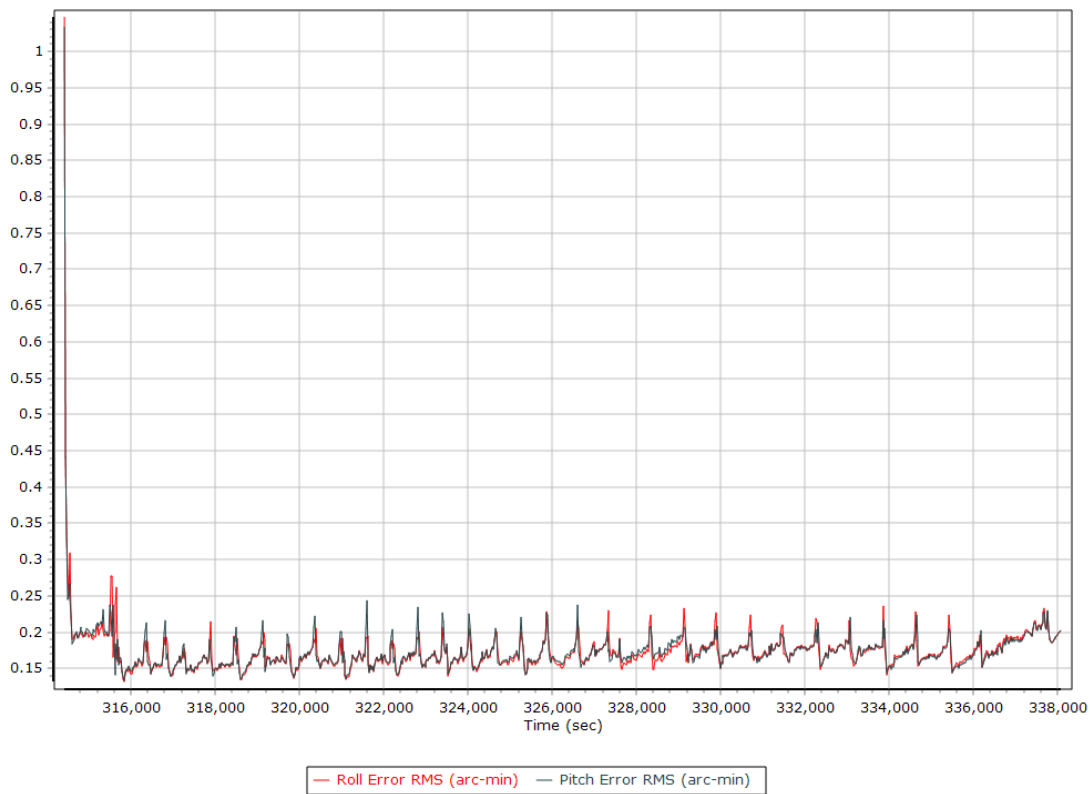
Position Error RMS (m)



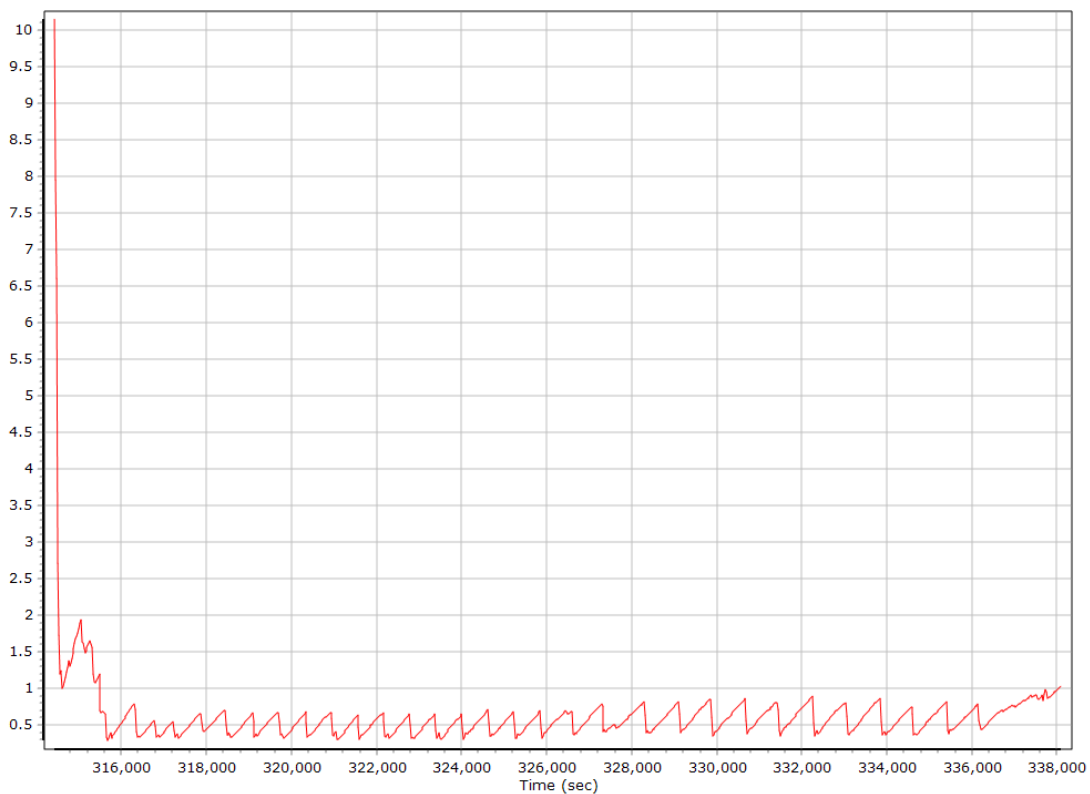
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

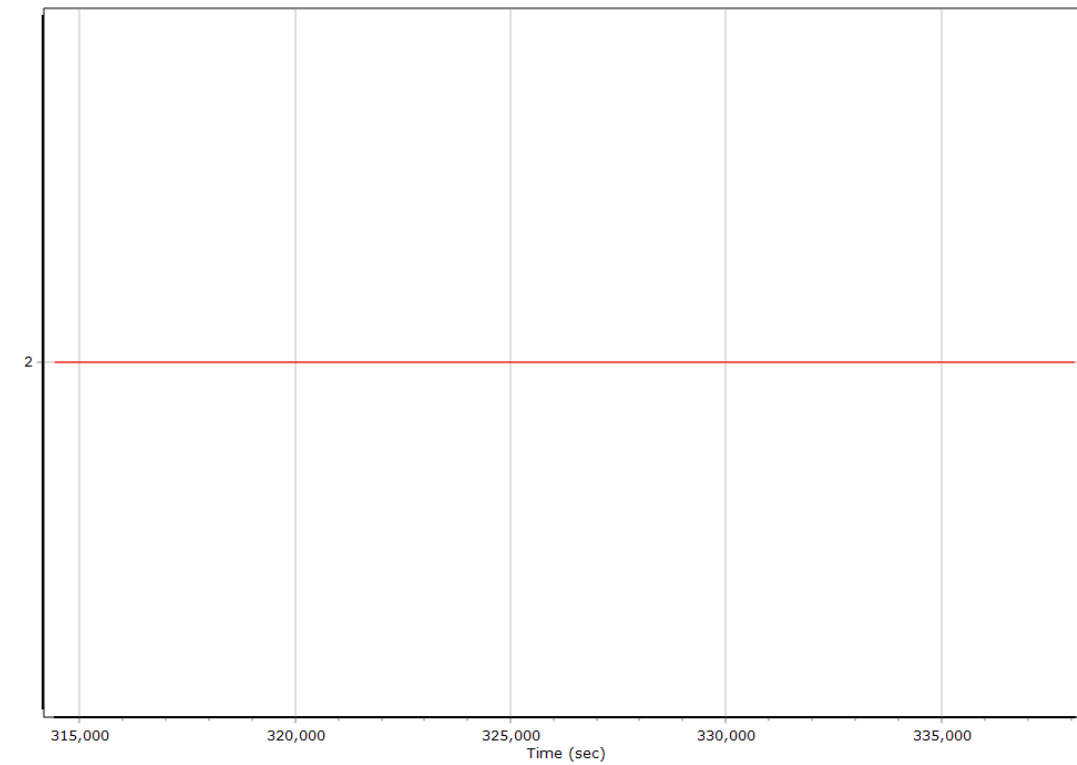


Heading Error RMS (arc-min)



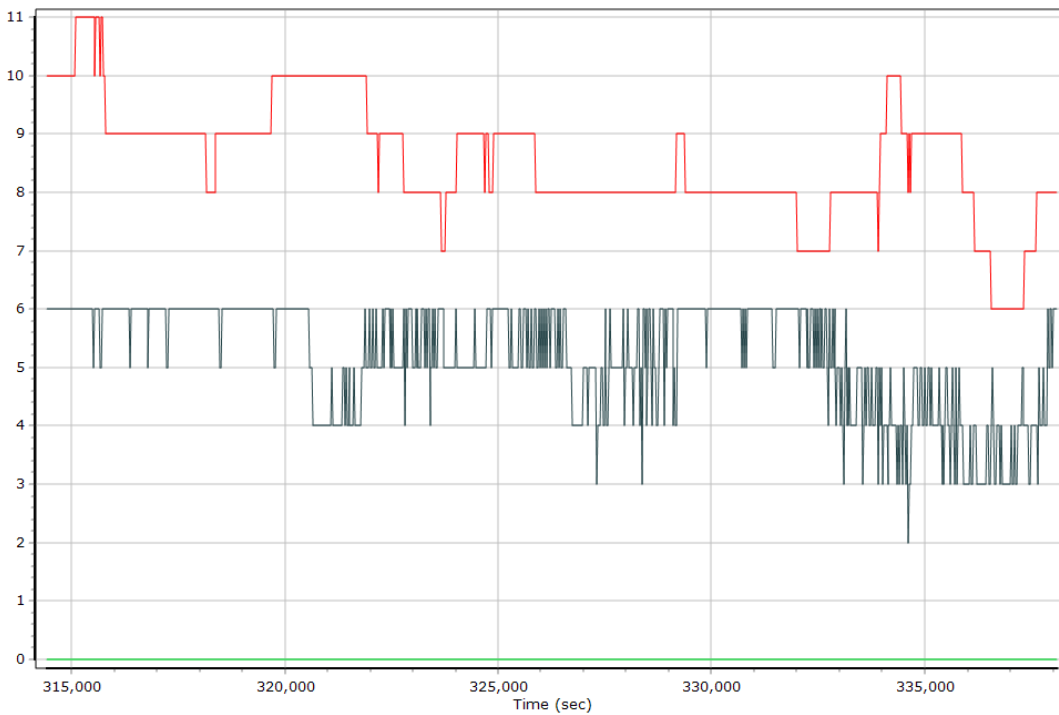
Forward Processed Solution Status

Processing Mode



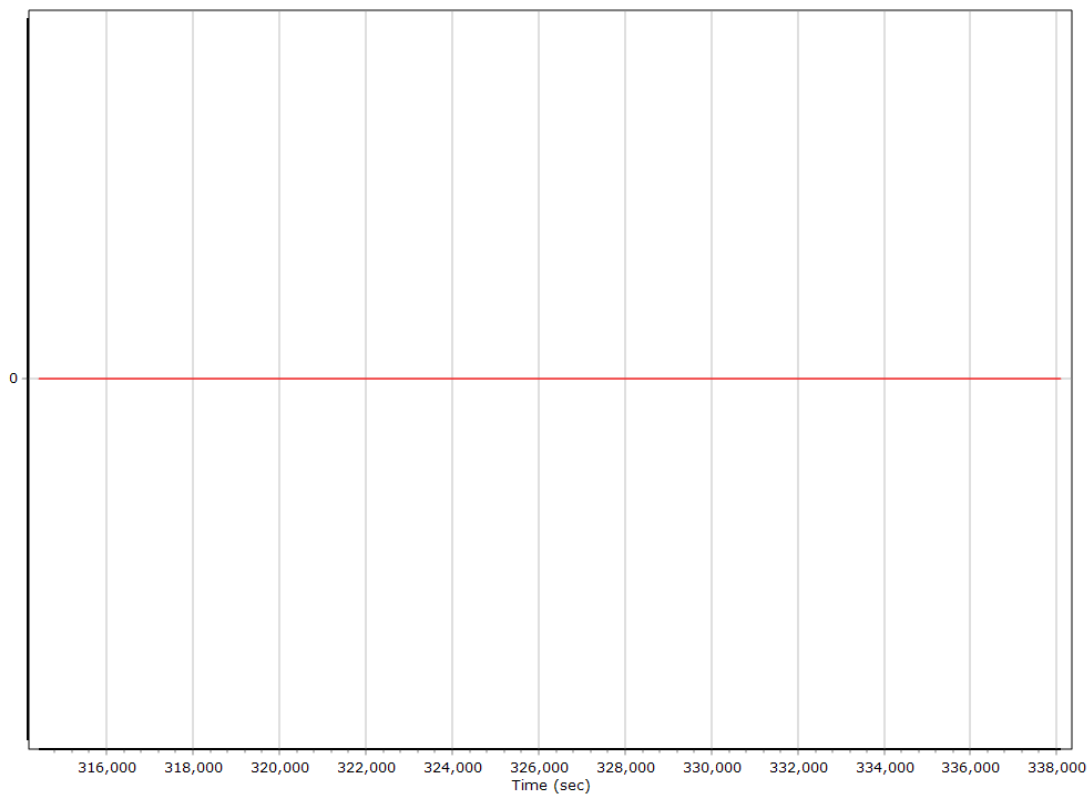
0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = C/A, 7 = GNSS Nav, 8 = DR

Number of Satellites



— Number of GPS Satellites
 — Number of GLONASS Satellites
 — Number of QZSS Satellites
— Number of BEIDOU Satellites
 — Number of GALILEO Satellites

Baseline Length



General Information

Mission Information

Project name	21-081_FFSL_210916
Processing date	2021-10-20 15:50:31
Mission date	2021-09-16 21:59:49
Mission duration	03:11:39.000
Processing mode	IN-Fusion Trimble RTX Nav

Rover Hardware Information

Product	POS AV 610 VER6 HW2.5-12
Serial number	S/N11651
IMU type	57
Receiver type	BD982
Antenna type	AV39

Project File List

Rover Data Files

File name	File type
210916_215930_INS-GPS_1.raw	POS Data

Input Files

File Name	File Type
Ephm2590.21g	GLONASS Broadcast Ephemeris
Ephm2590.21n	GPS Broadcast Ephemeris
Ephm2600.21g	GLONASS Broadcast Ephemeris
Ephm2600.21n	GPS Broadcast Ephemeris

Output Files

Filename	File type
sbet_21-081_210916.out	SBET Trajectory File

Rover Data Summary

First raw data file	210916_215930_INS-GPS_1.raw		
Last raw data file	210916_215930_INS-GPS_1.raw		
Start GPS week	2175		
Start time	424770.695 (09/16/2021 21:59:30)		
End time	436269.813 (09/17/2021 01:11:09)		
Start of fine alignment	424941.631 (09/16/2021 22:02:21)		
Available subsystems	Primary GNSS, Gimbal, IMU		
POS Event Input	None		
Correction data	Trimble RTX		
IMU Installation Lever Arms & Mounting Angles			
Gimbal to IMU lever arm (m)	-0.034	-0.010	-0.374
Gimbal to IMU mounting angles (deg)	0.000	0.000	0.000
Gimbal to Primary GNSS lever arm (m)	0.980	-0.102	-1.276
Gimbal to Primary GNSS lever arm std dev (m)	-1.000		
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

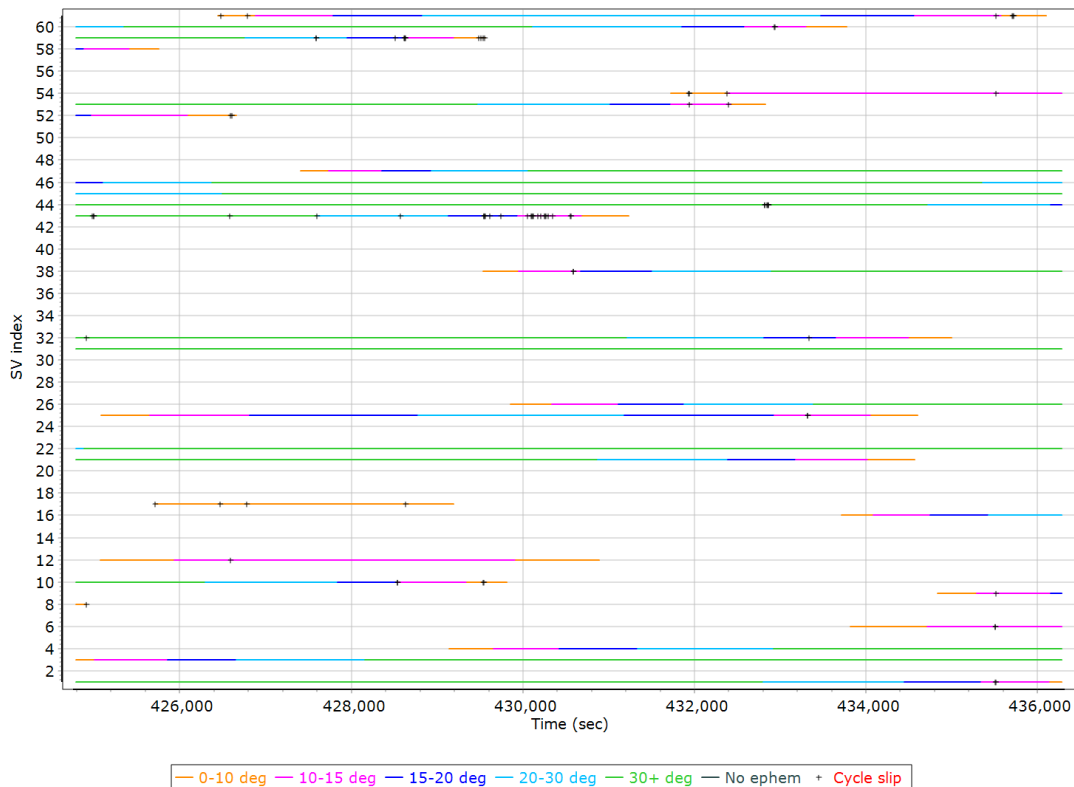
Rover Data QC

Raw IMU Import QC Summary

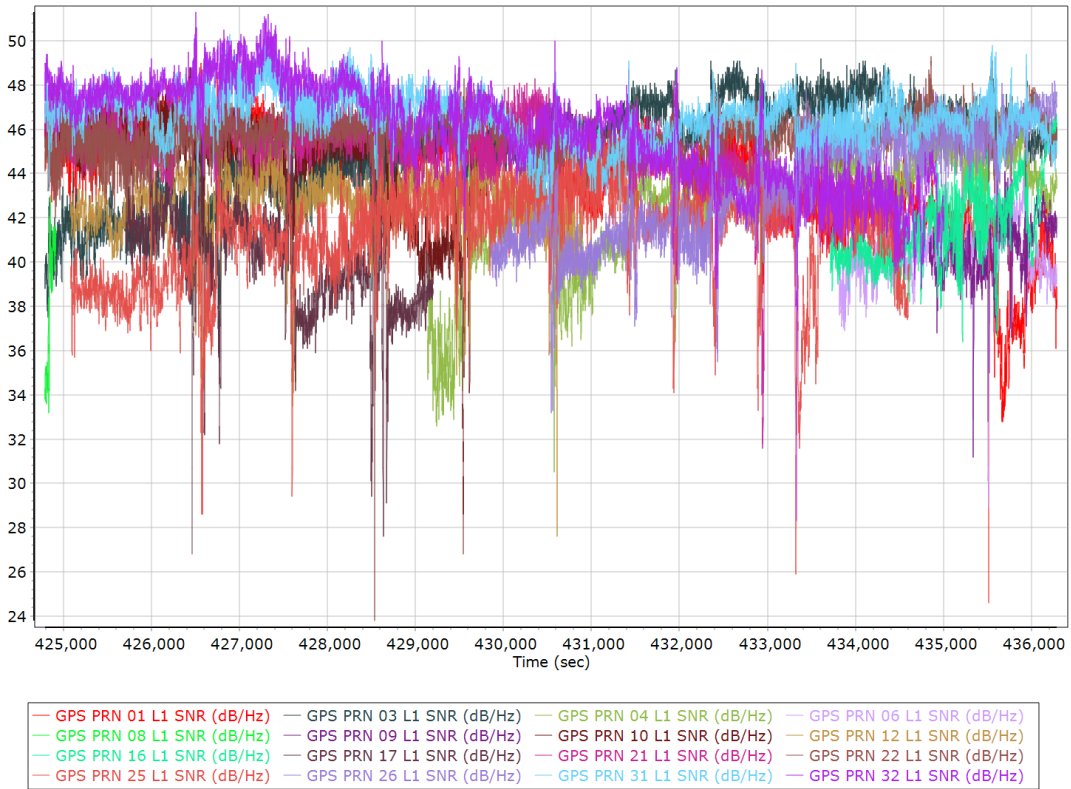
IMU data input file	imu_21-081_210916.dat
IMU data check log file	imudt_21-081_210916.log
IMU Records Processed	2299583
Termination Status	Normal
IMU Anomalies	0

Primary Observables & Satellite Data

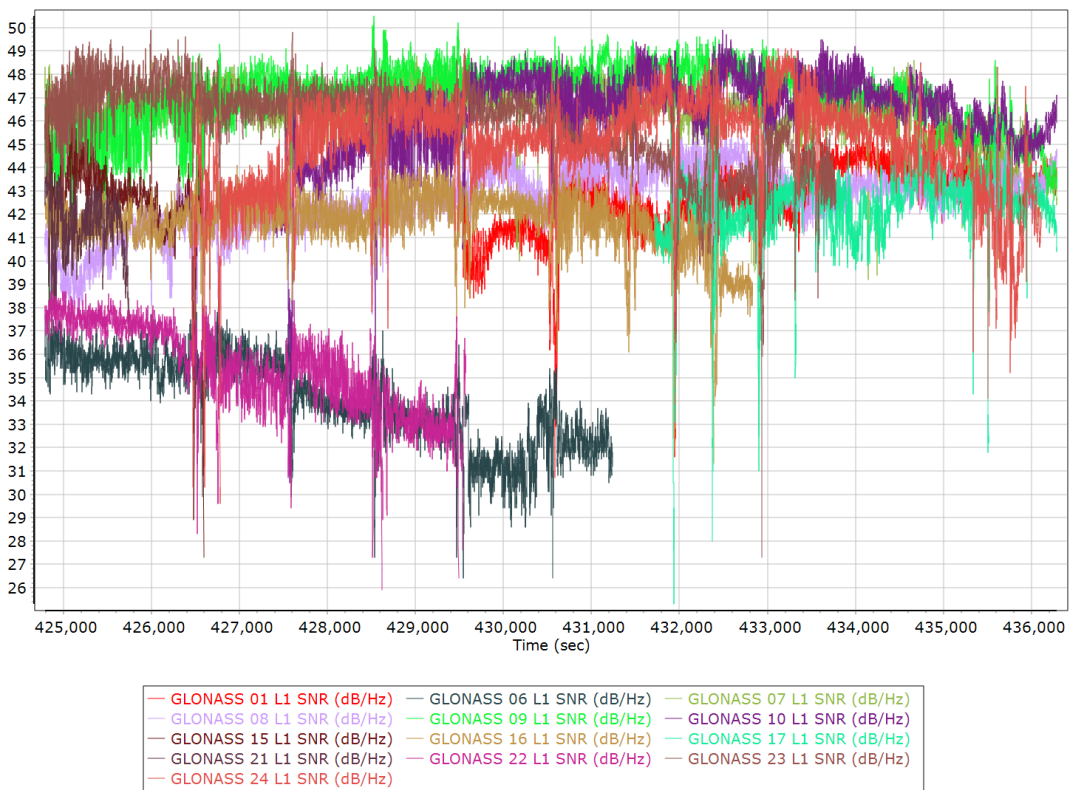
GPS/GLONASS L1 Satellite Lock/Elevation



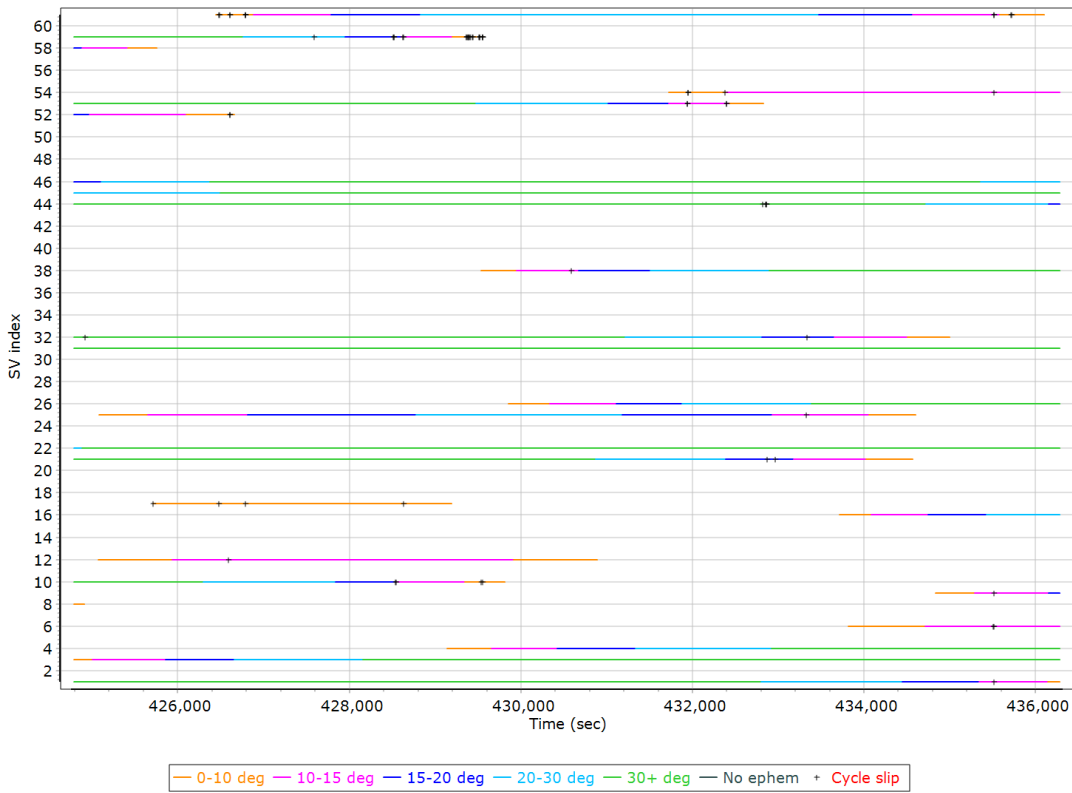
GPS L1 SNR



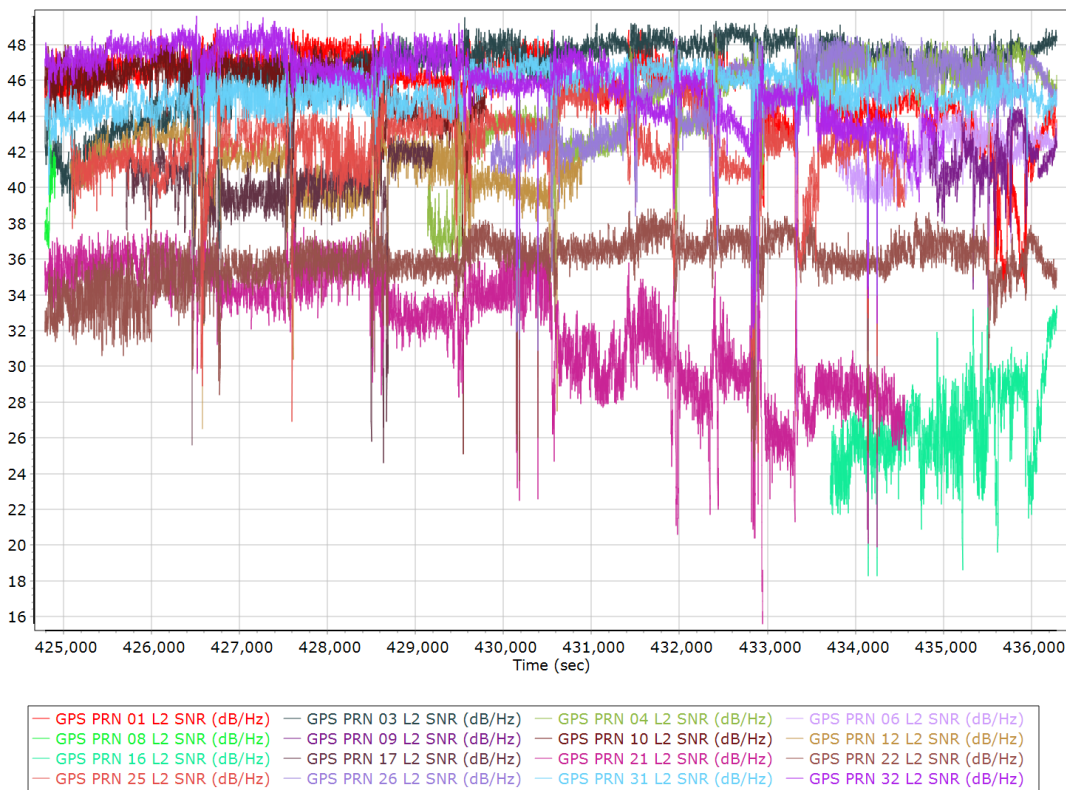
GLONASS L1 SNR



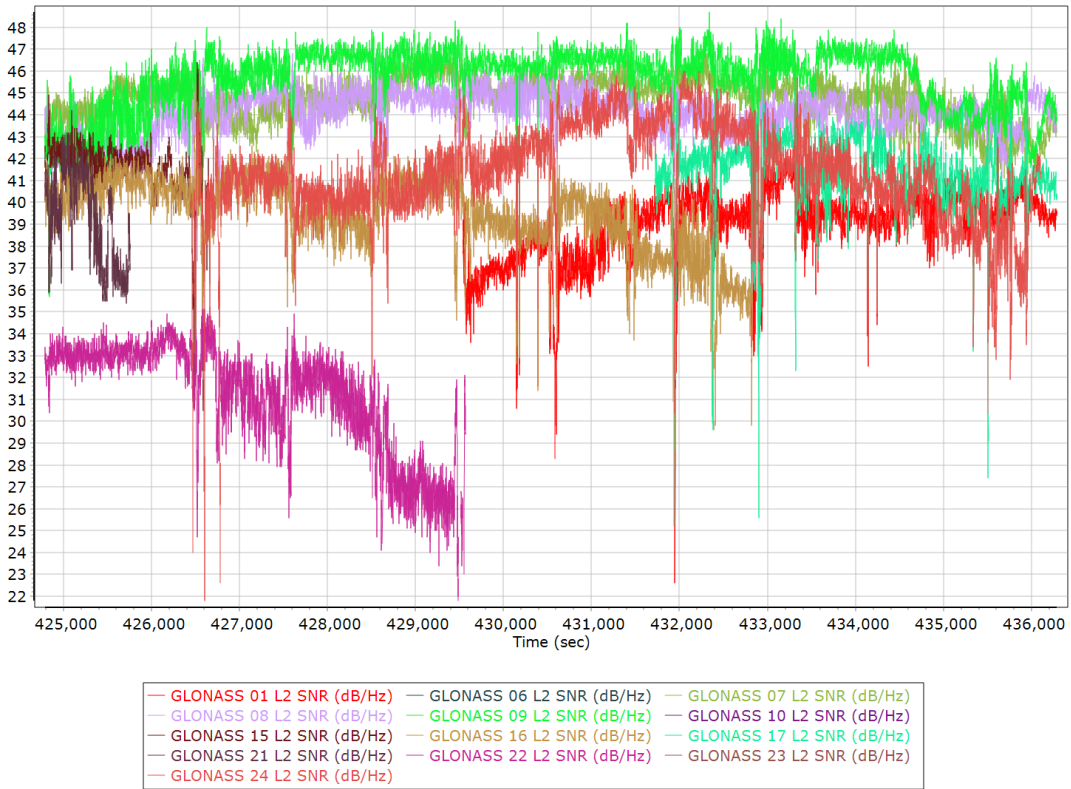
GPS/GLONASS L2 Satellite Lock/Elevation



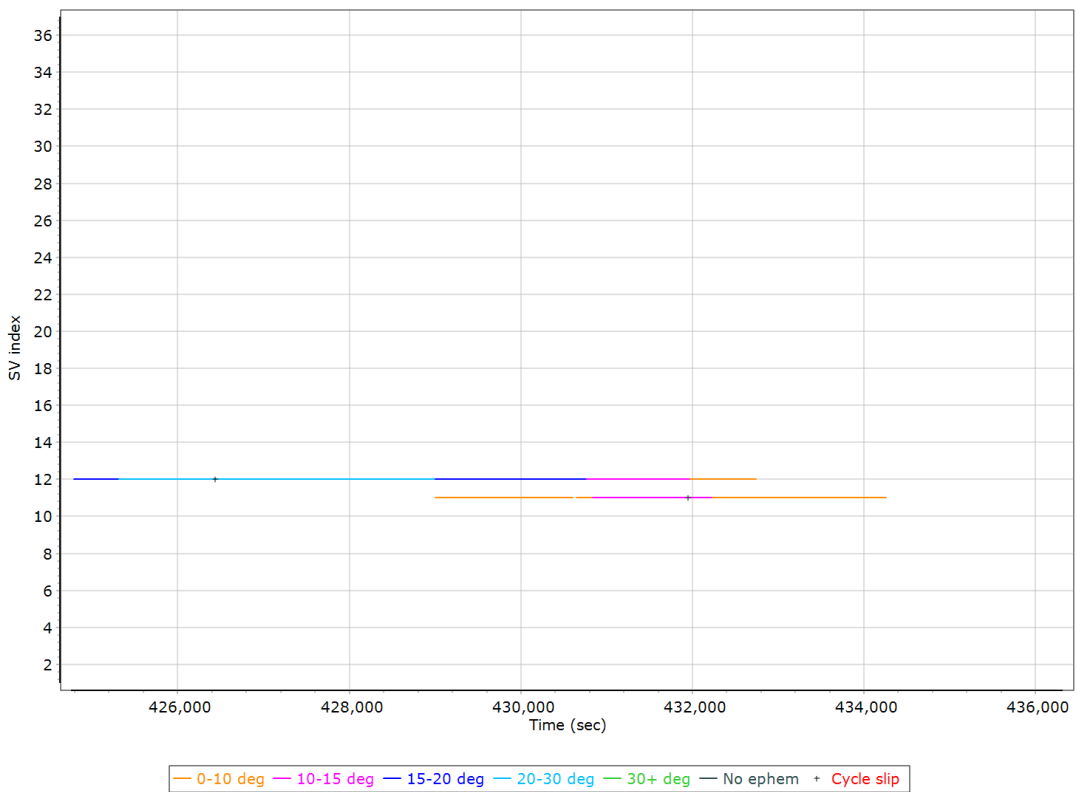
GPS L2 SNR



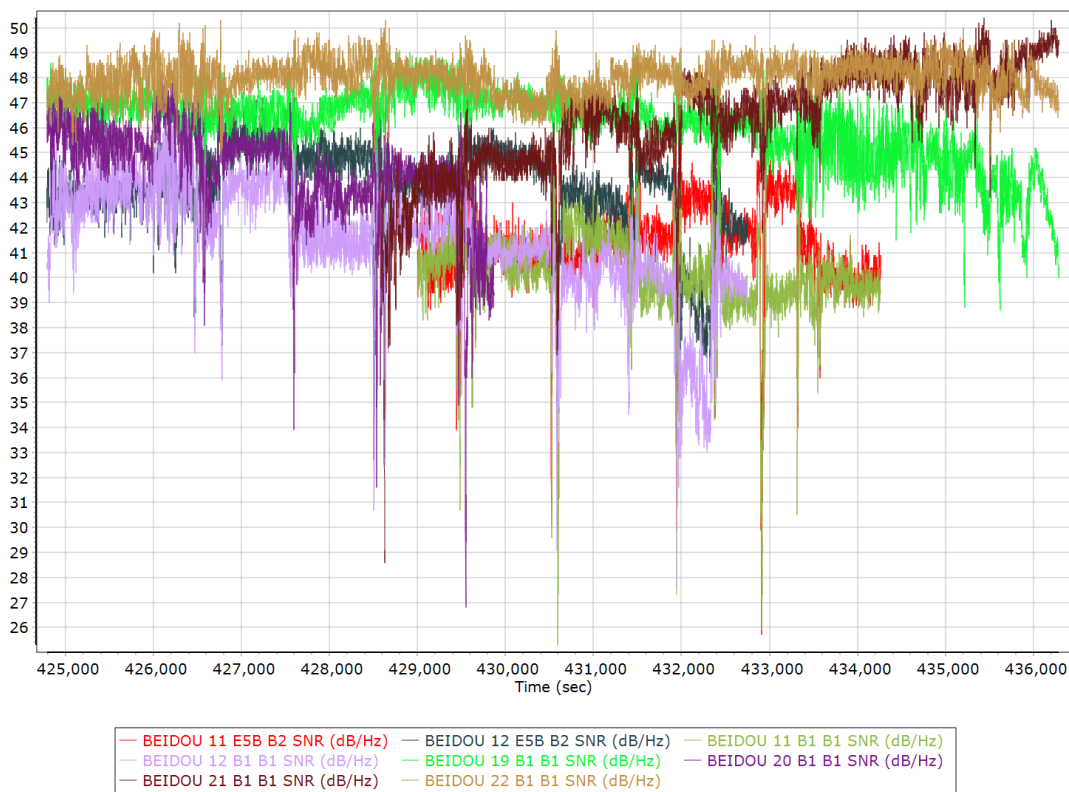
GLONASS L2 SNR



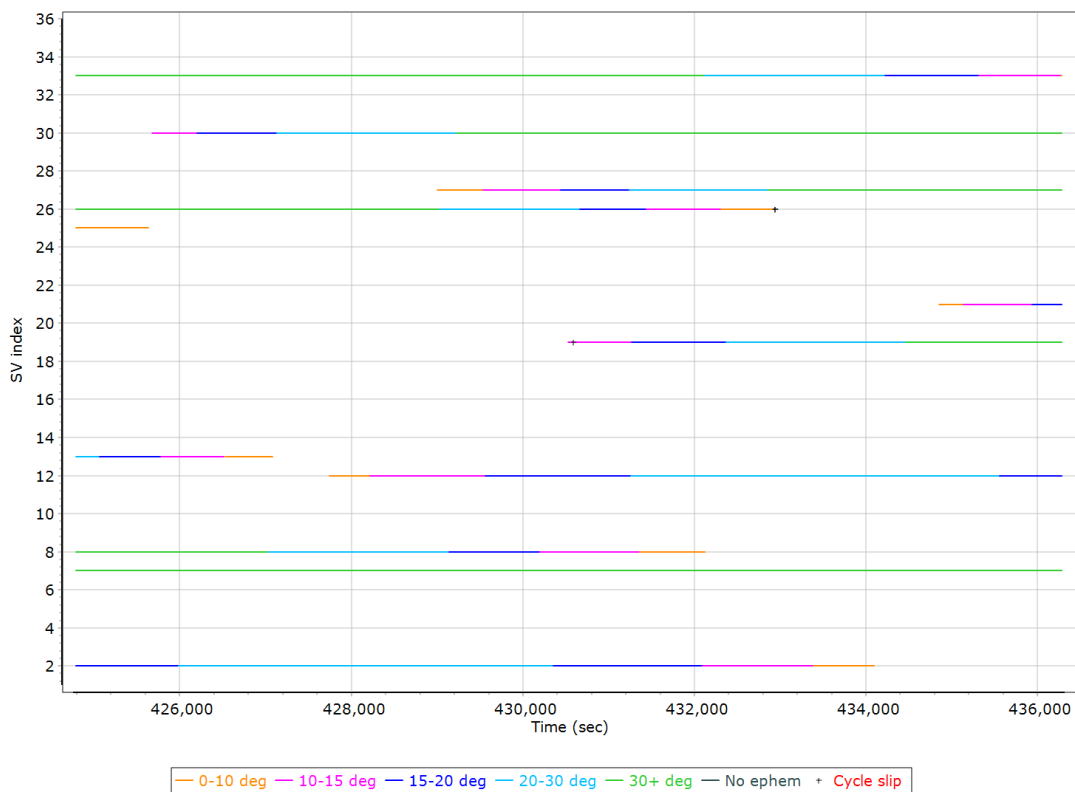
BEIDOU Satellite Lock/Elevation



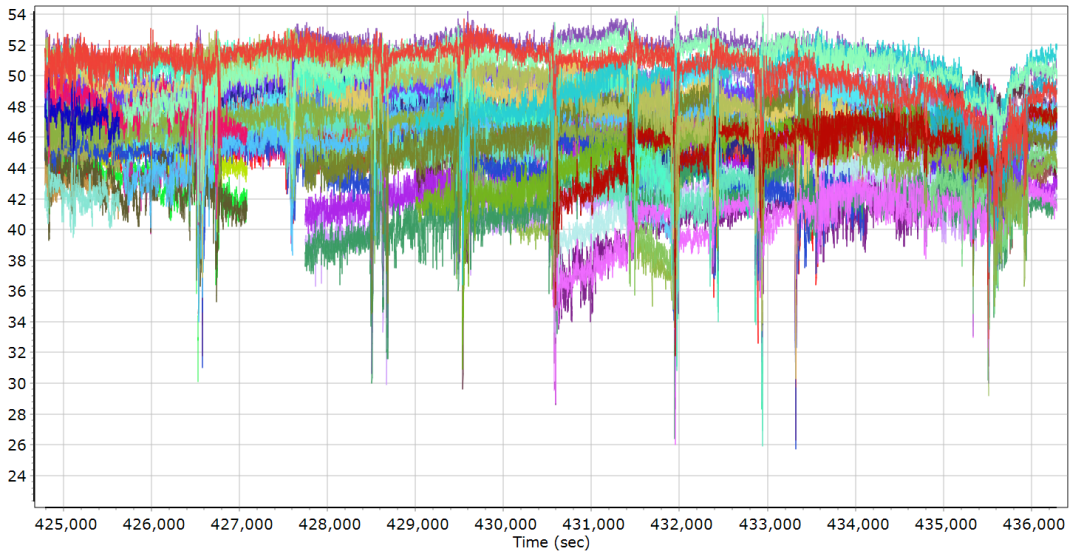
BEIDOU SNR



GALILEO Satellite Lock/Elevation



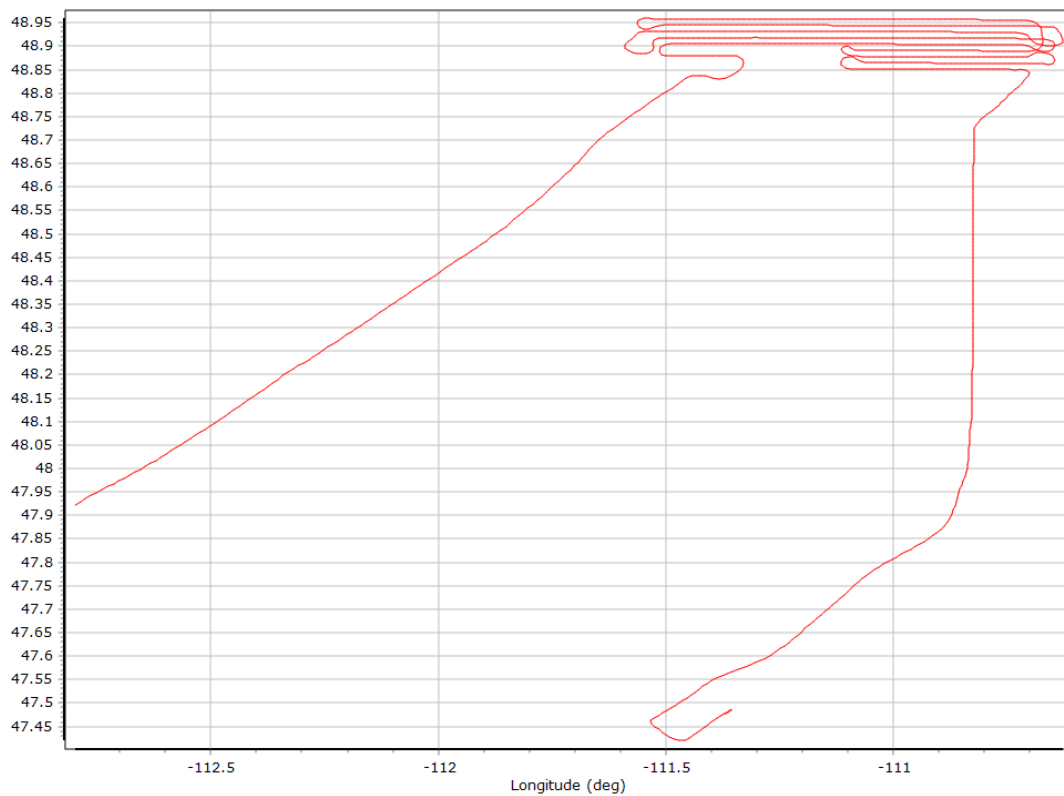
GALILEO SNR



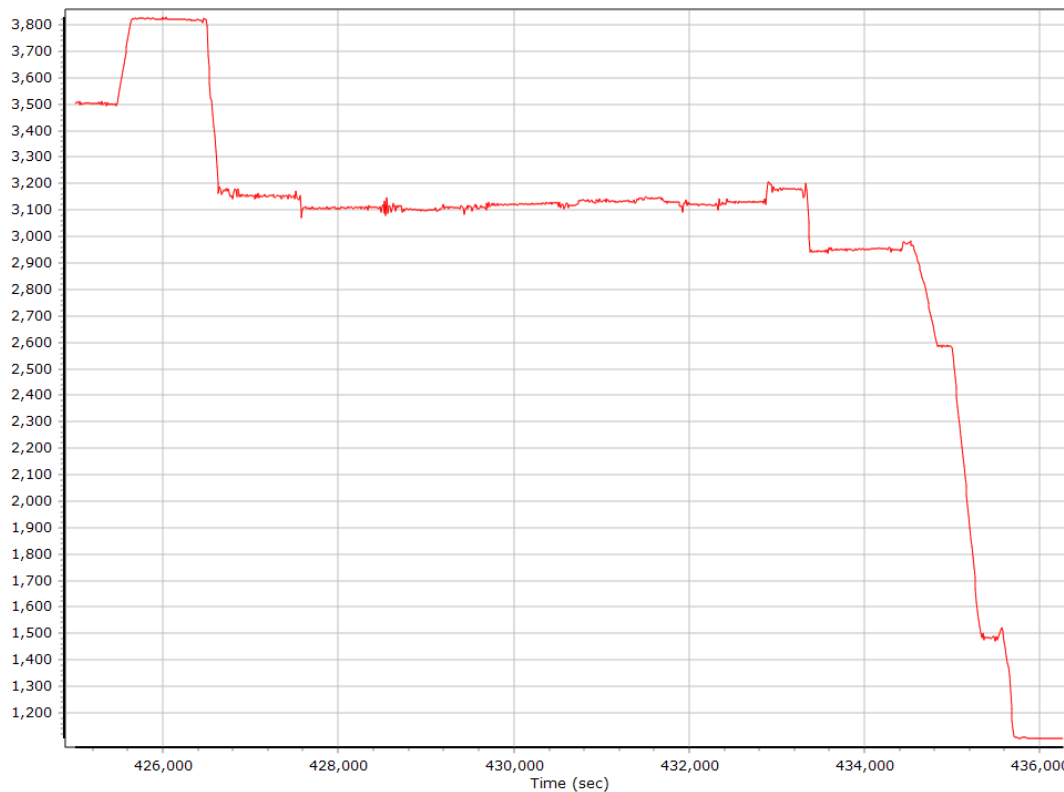
— GALILEO 02 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 07 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 08 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 12 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 13 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 19 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 21 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 25 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 26 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 27 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 30 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 33 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 02 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 07 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 08 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 12 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 13 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 19 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 21 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 25 L5E5A BPSK10_PD SNR (dB/Hz)

Smoothed Trajectory Information

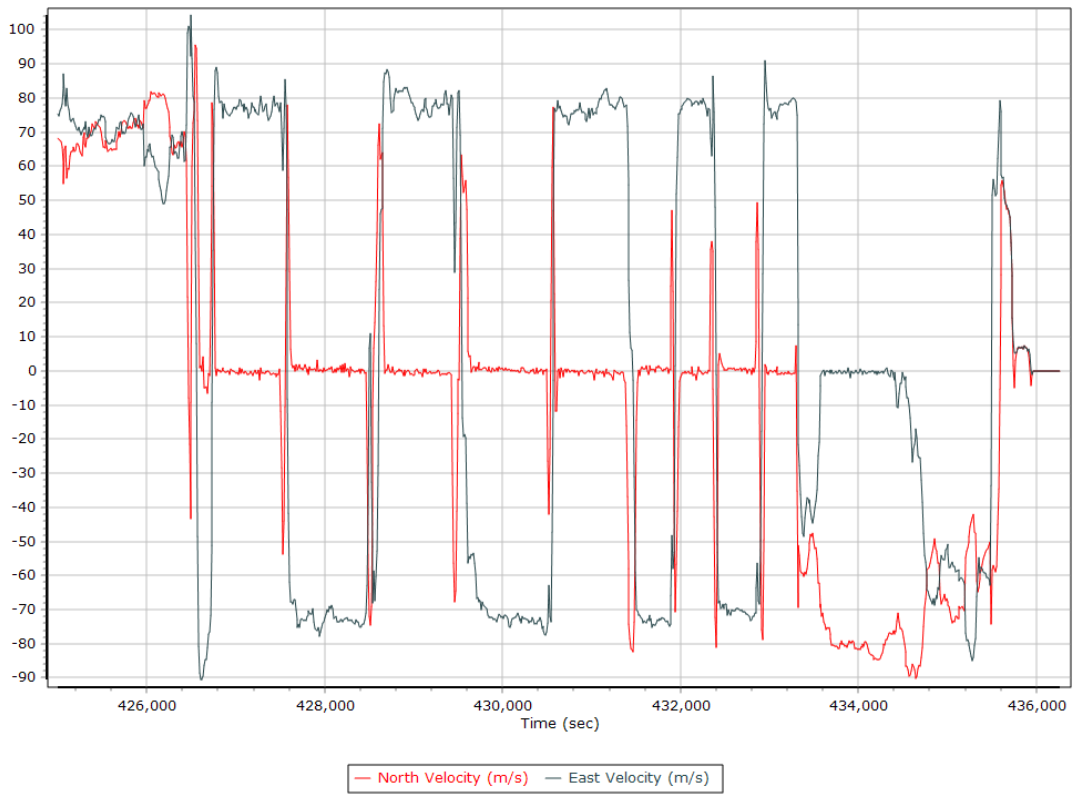
Top View



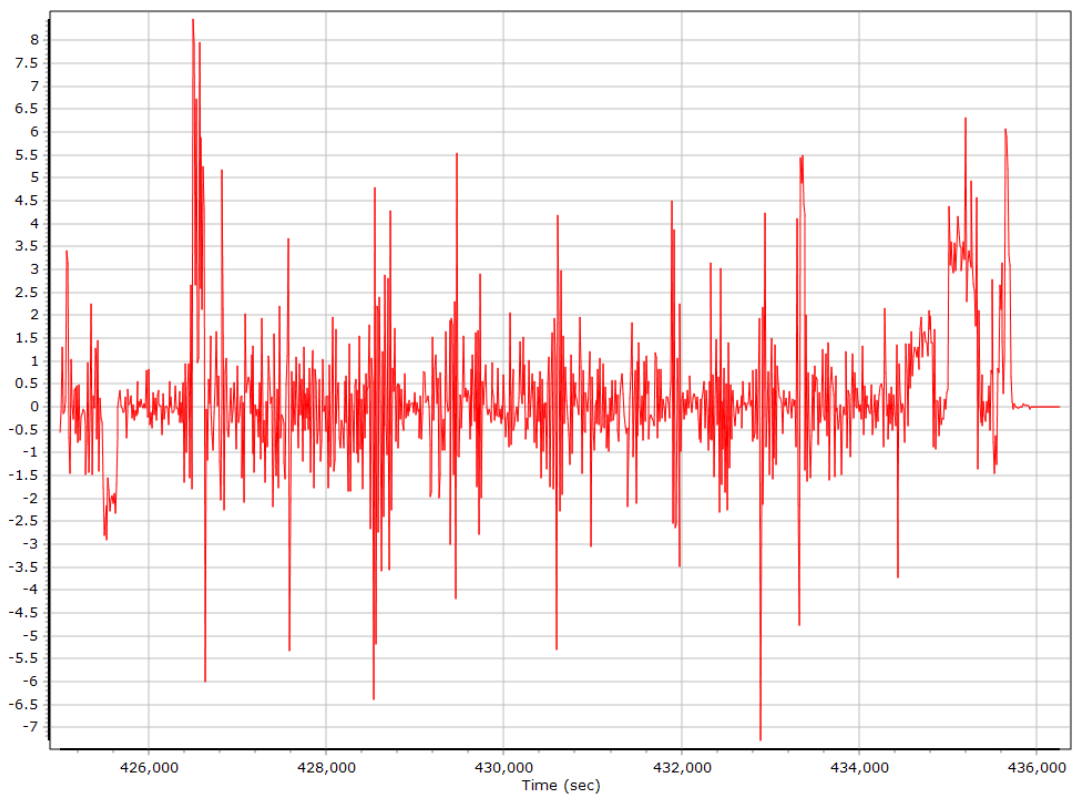
Altitude



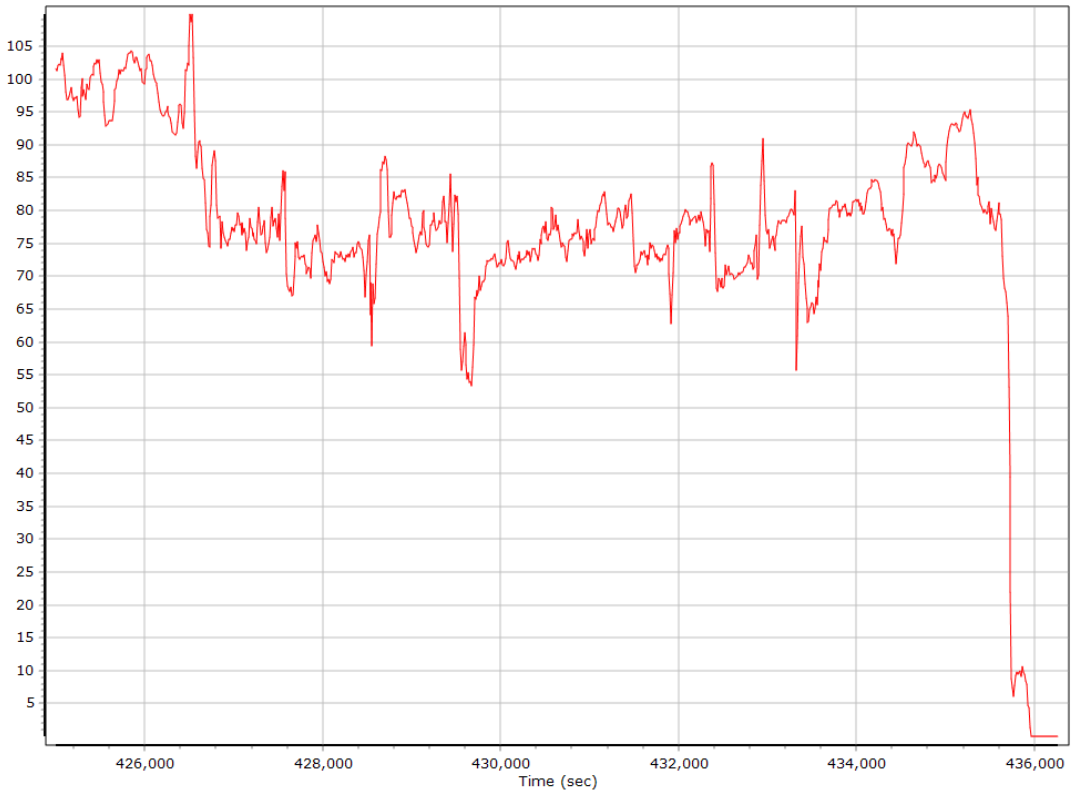
North/East Velocity



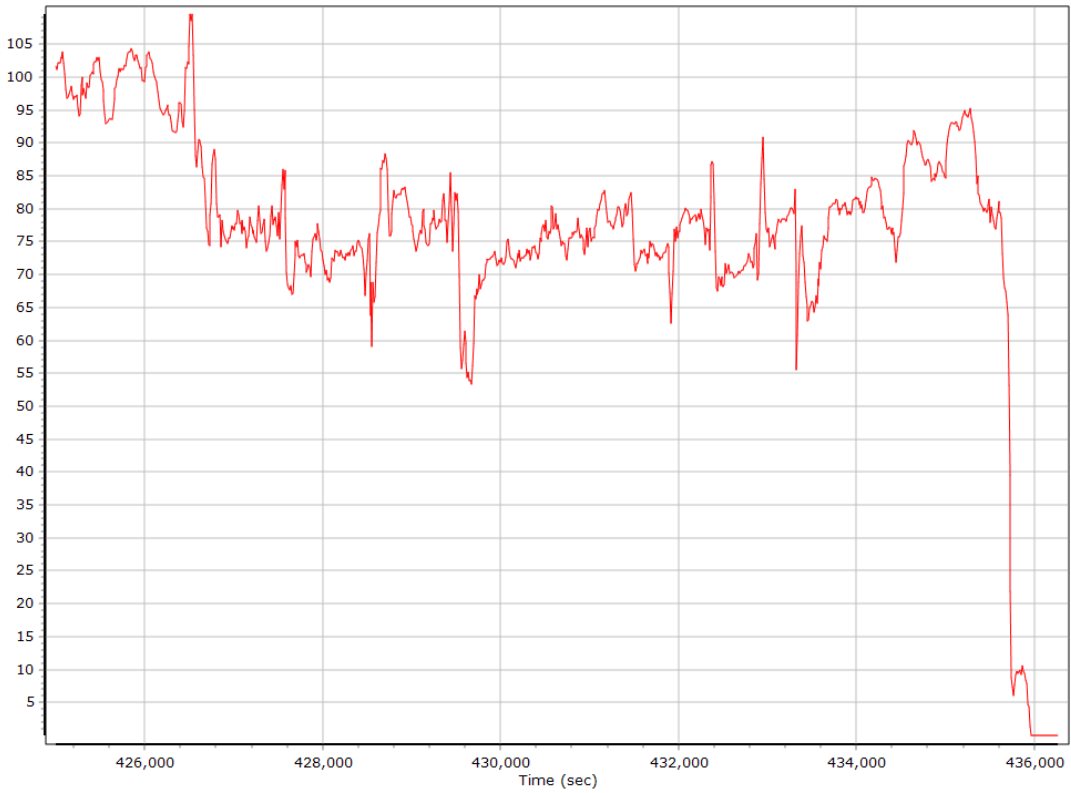
Down Velocity



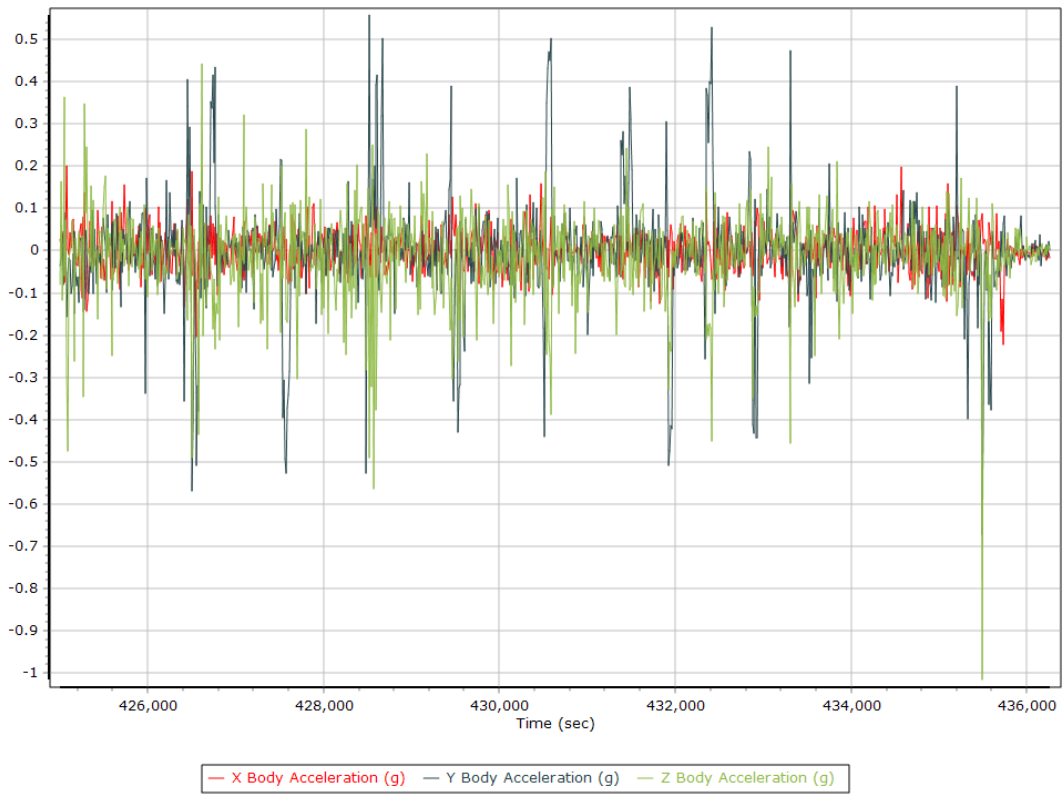
Total Speed



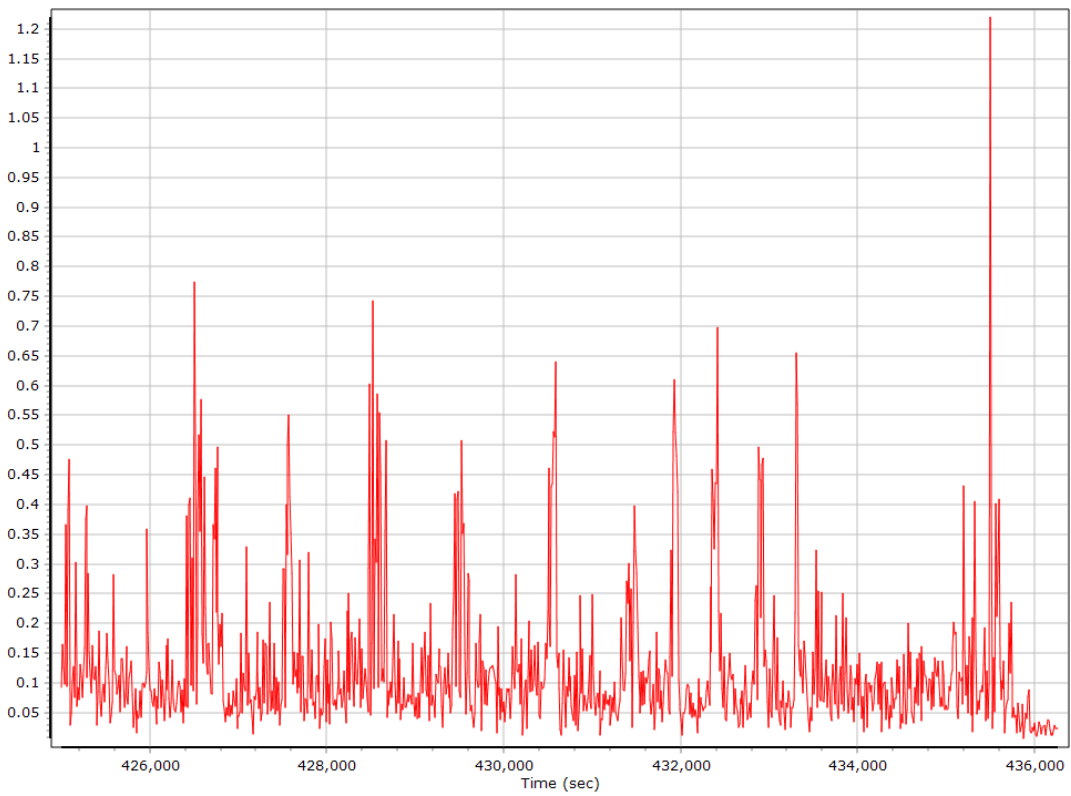
Ground Speed



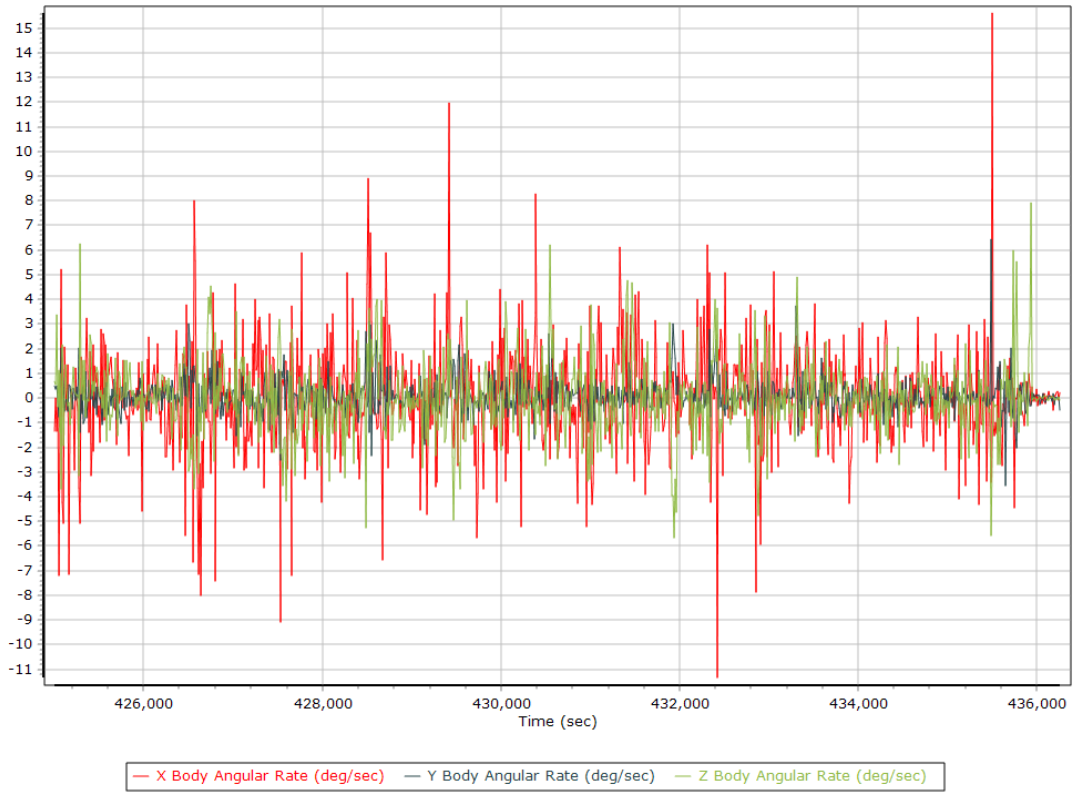
Body Acceleration



Total Body Acceleration

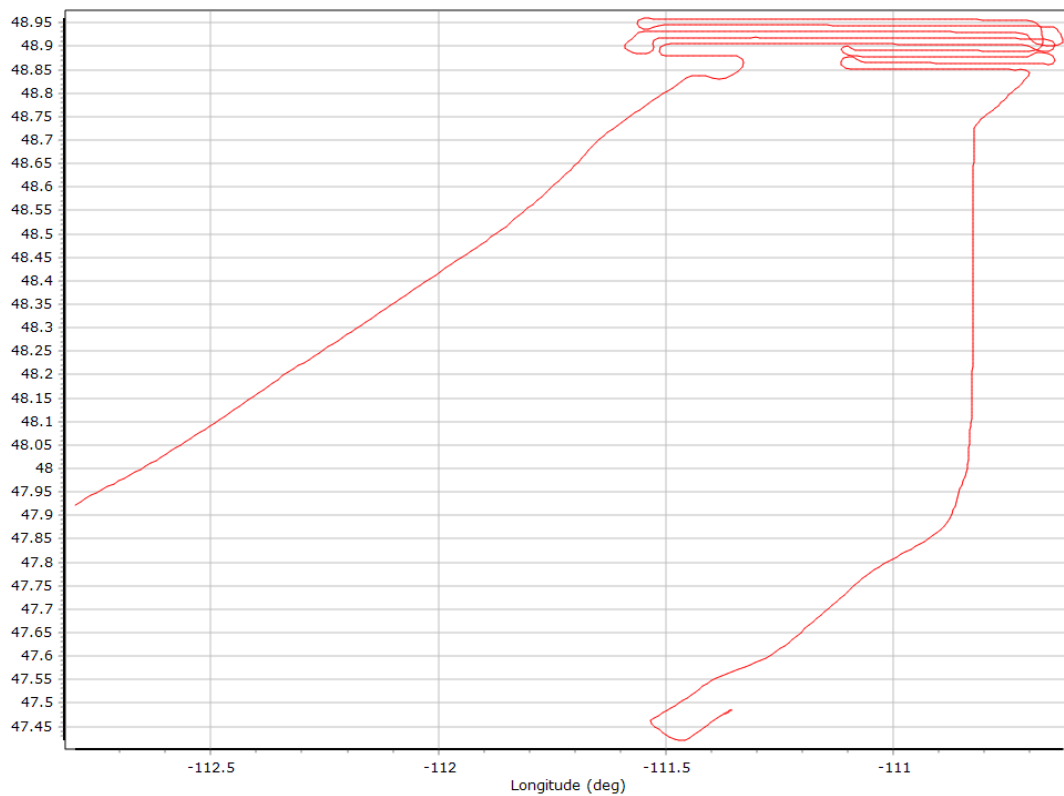


Body Angular Rate

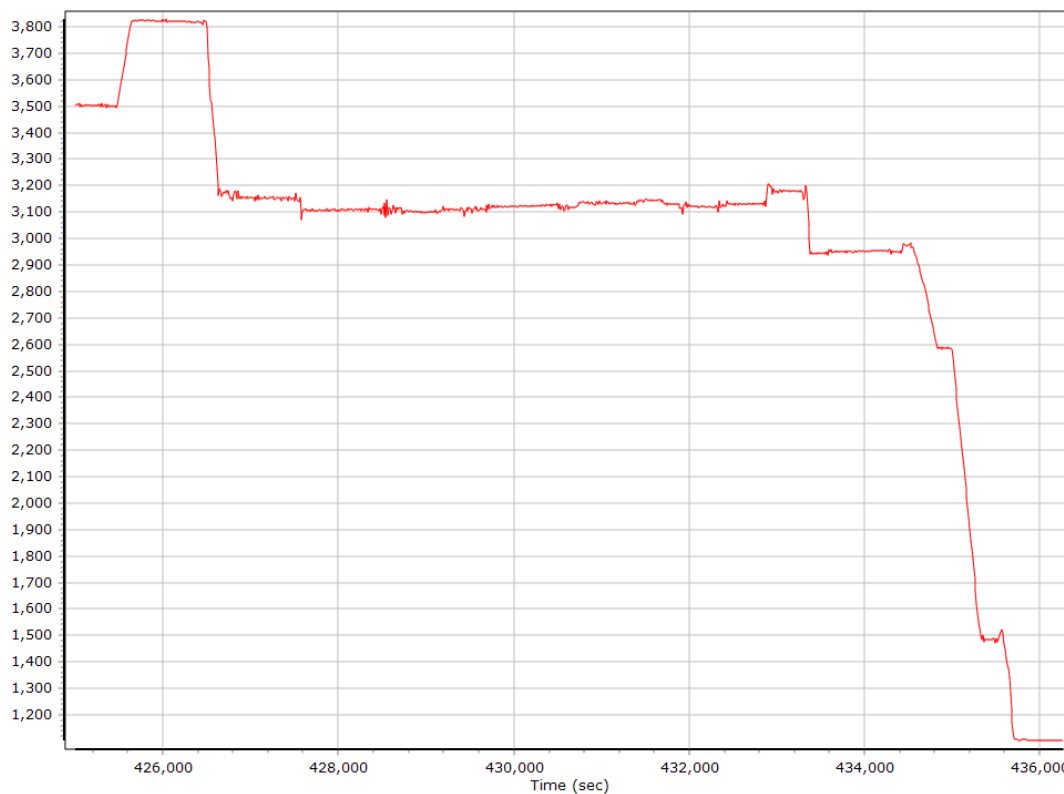


Forward Processed Trajectory Information

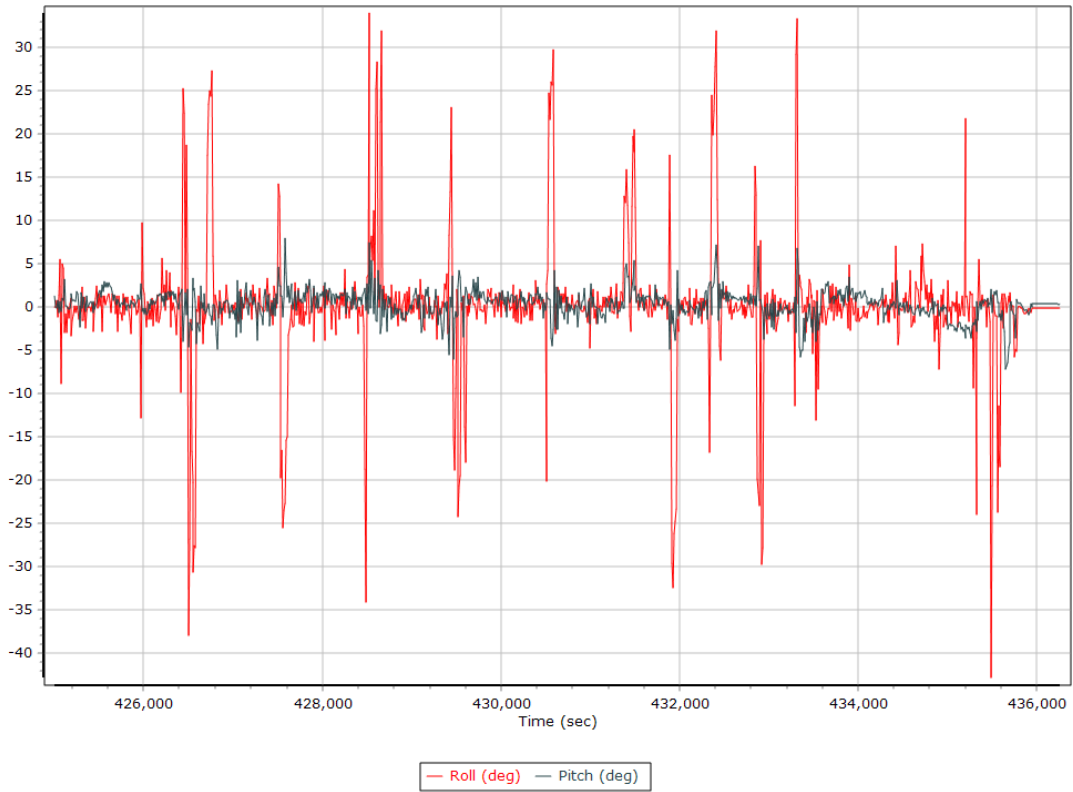
Top View



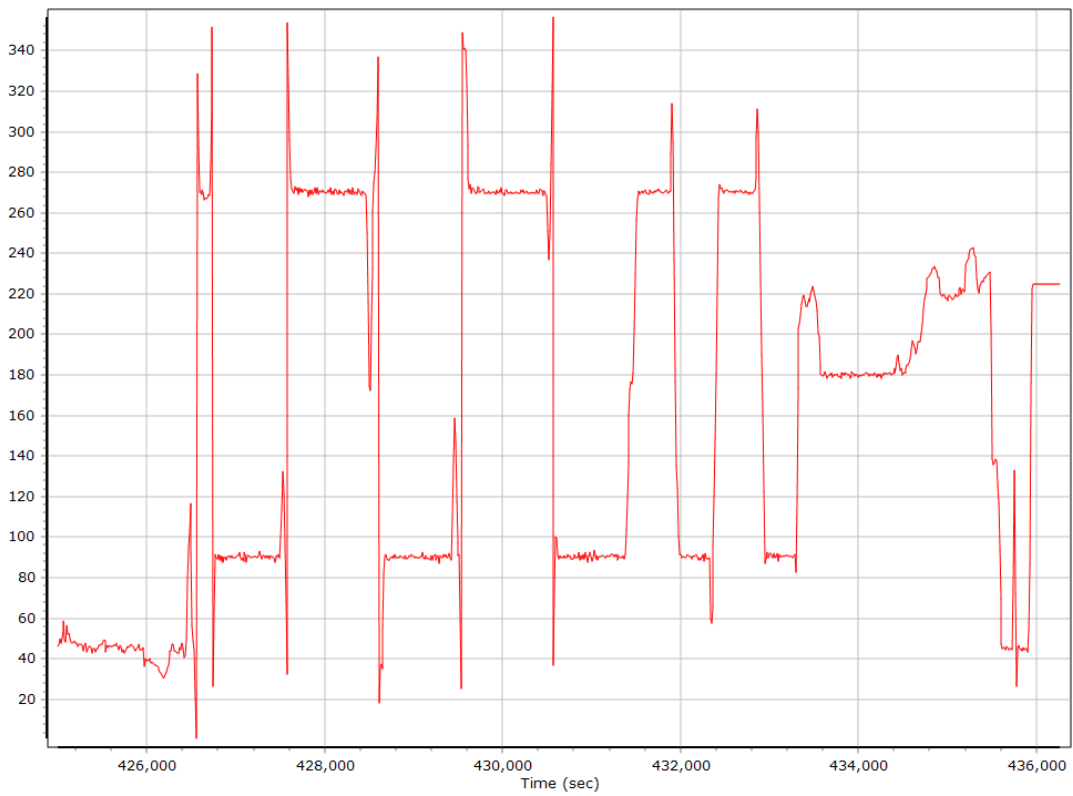
Altitude



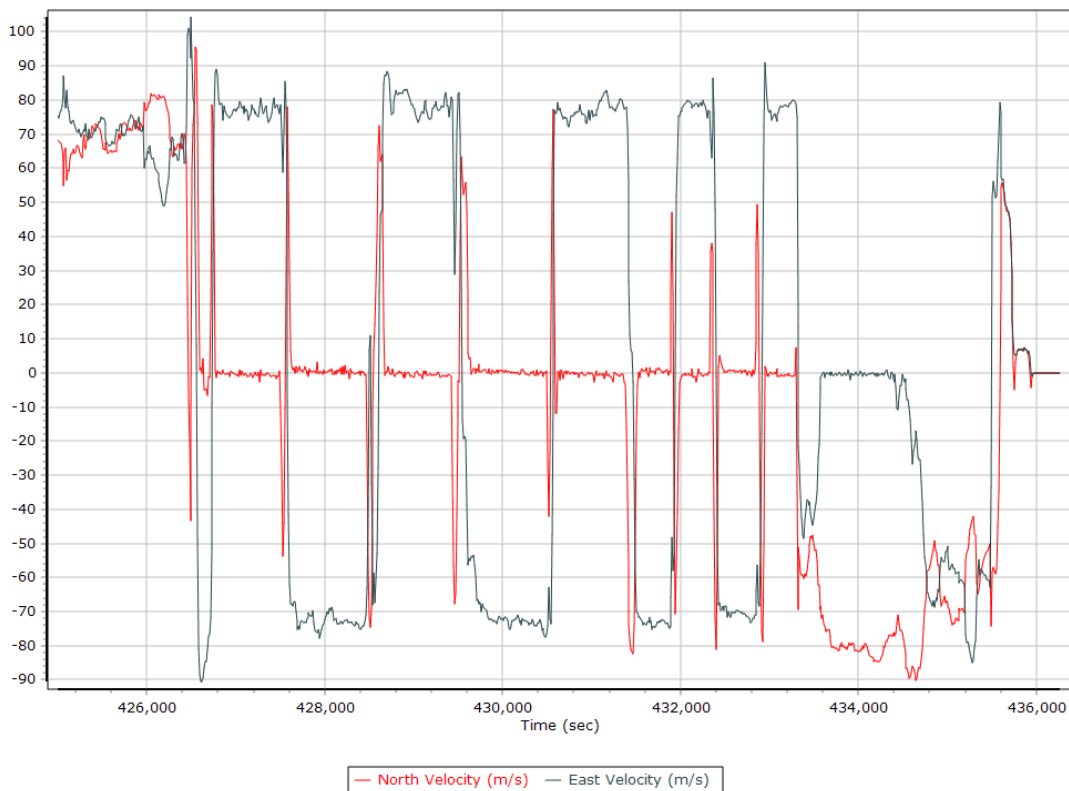
Roll/Pitch



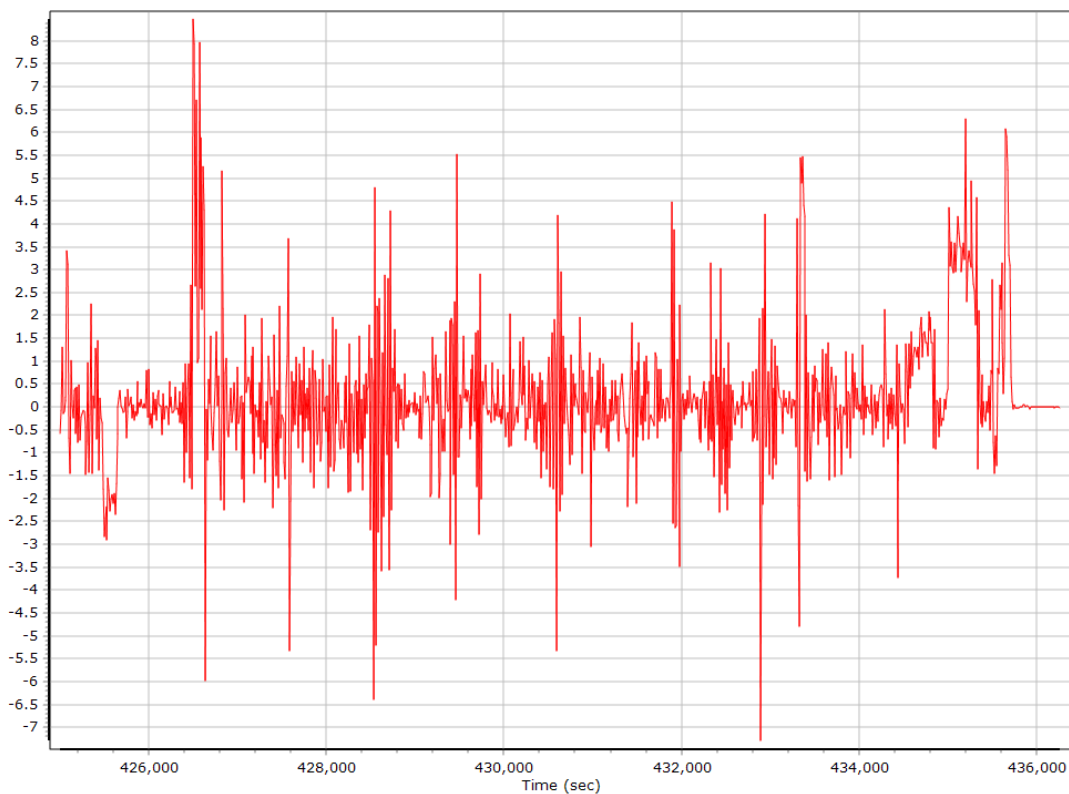
Heading



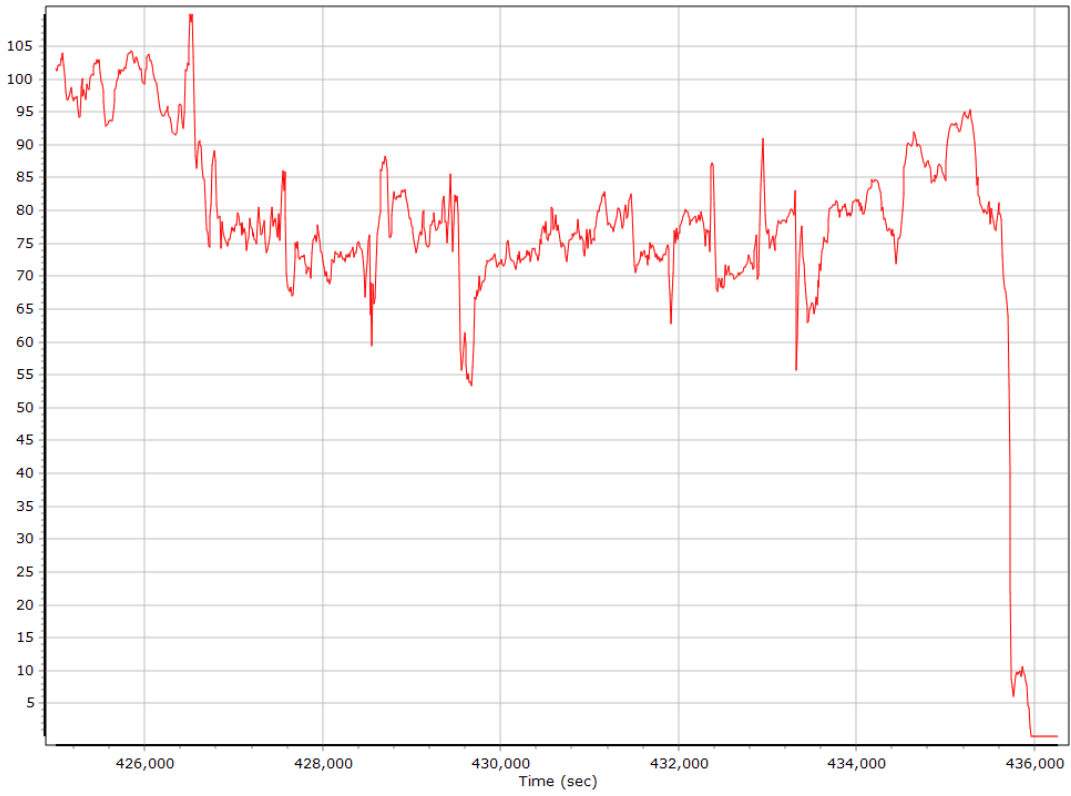
North/East Velocity



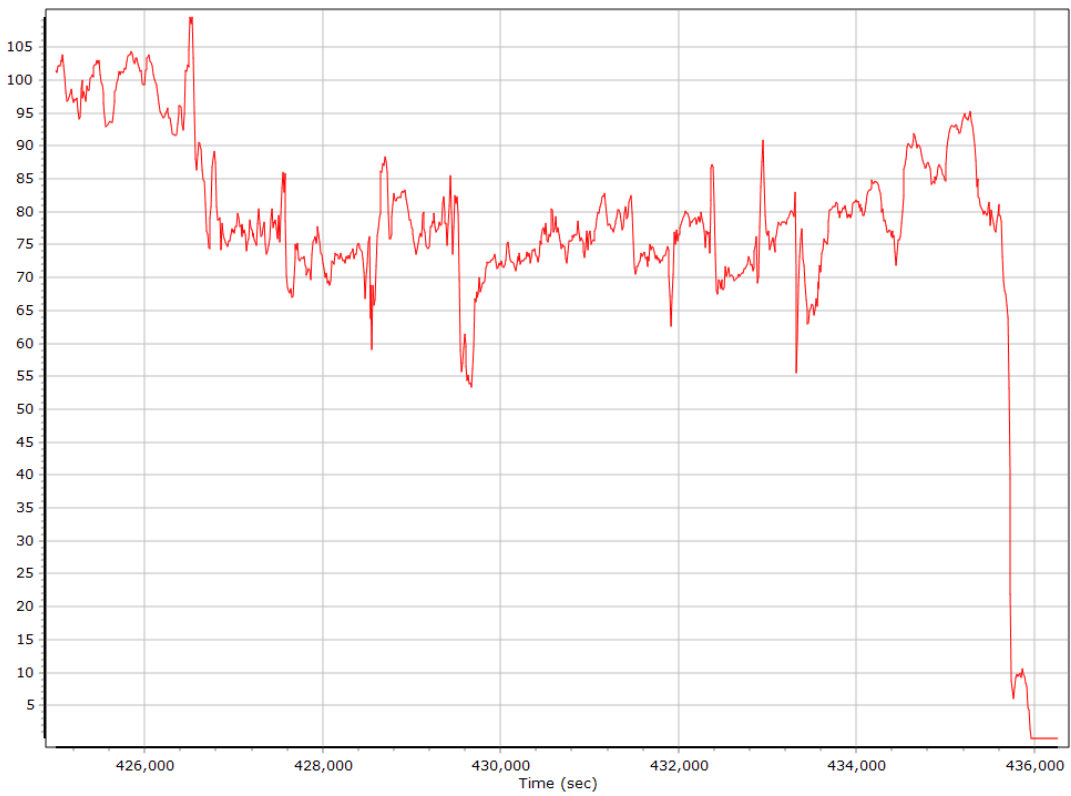
Down Velocity



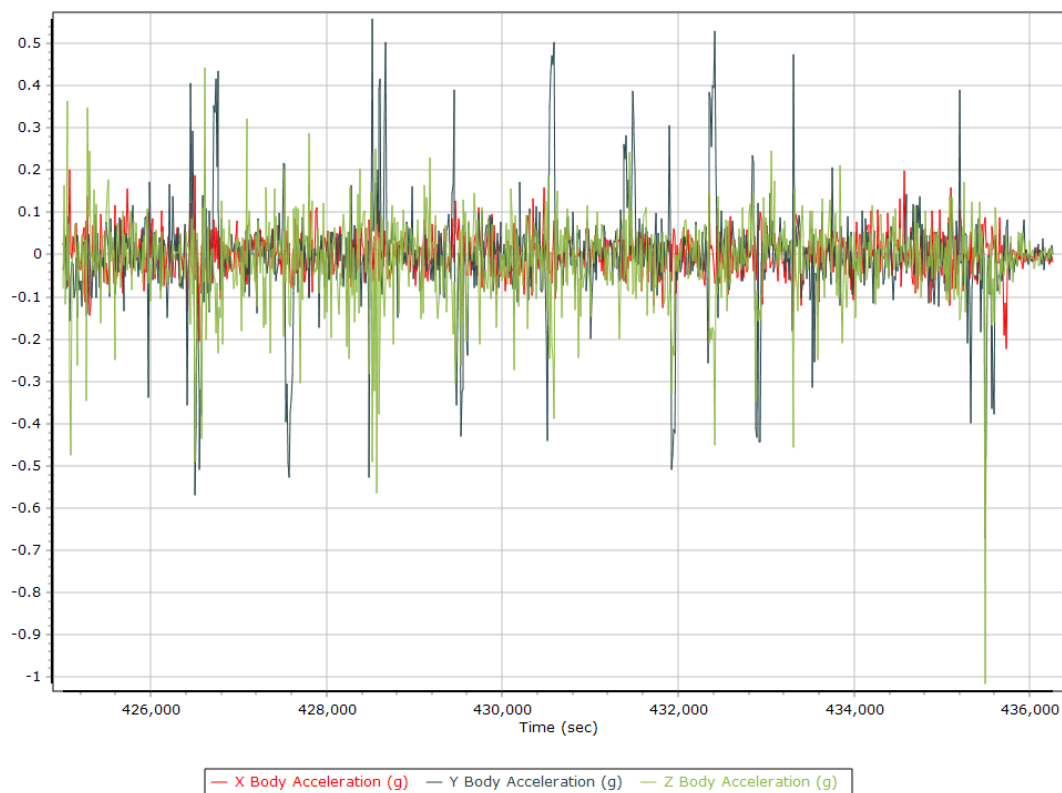
Total Speed



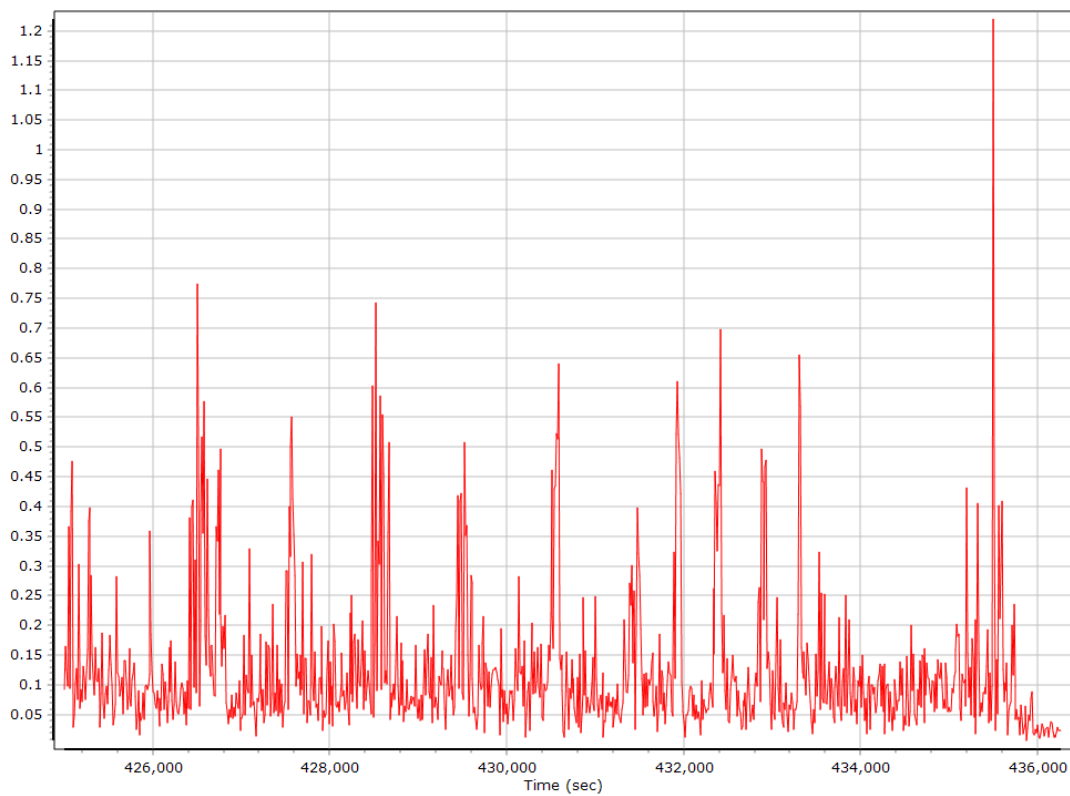
Ground Speed



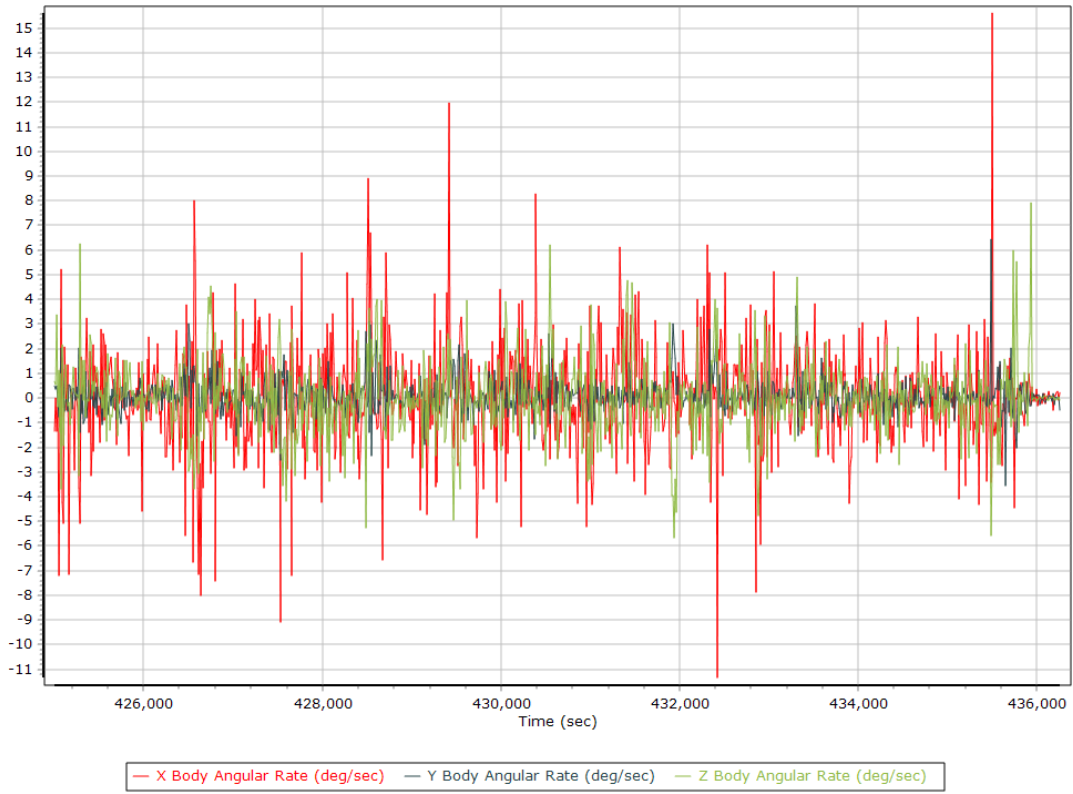
Body Acceleration



Total Body Acceleration



Body Angular Rate



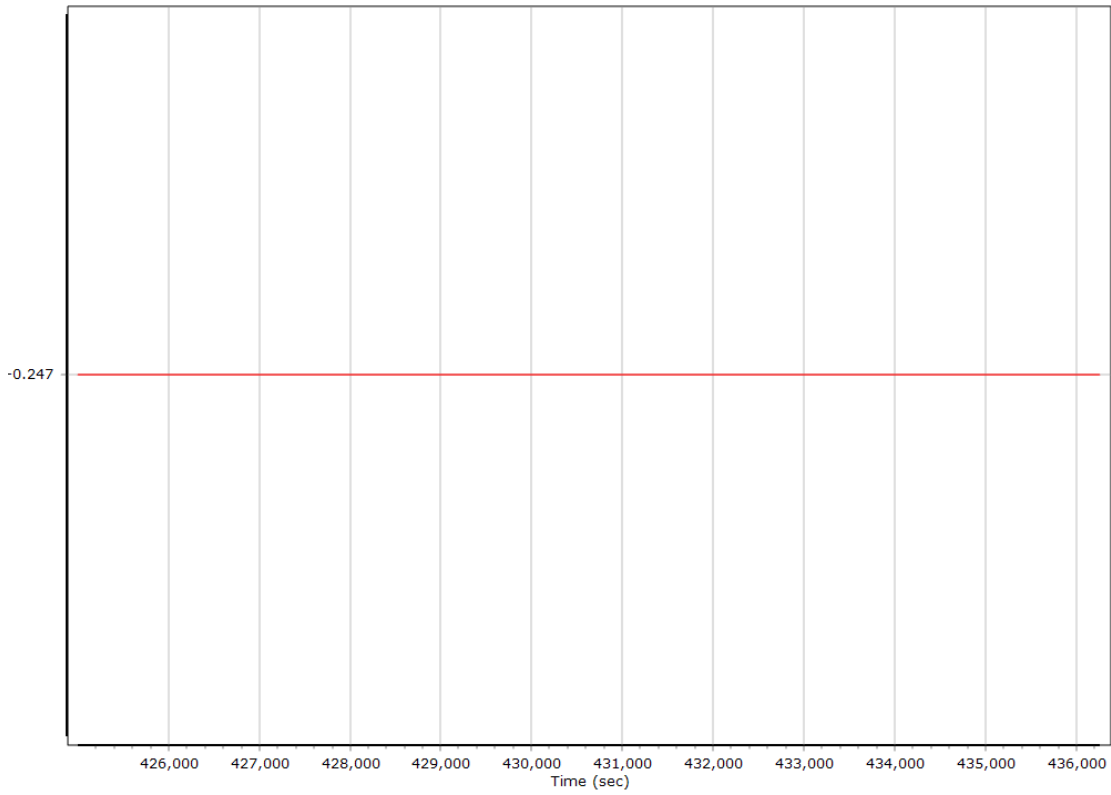
GNSS-Inertial Processor Configuration

Processing mode	IN-Fusion Trimble RTX Nav		
Stabilized mount	True		
Processing start time	424771.000 (09/16/2021 21:59:31)		
Processing end time	436270.000 (09/17/2021 01:11:10)		
Initial attitude source	Real-Time VNAV/RNAV Attitude		
IMU Sensor Context	Processing with Onboard IMU		
Gimbal to IMU lever arm (m)	-0.034	-0.010	-0.374
Gimbal to IMU mounting angles (deg)	0.000	0.000	0.000
Gimbal to Primary GNSS lever arm (m)	-0.247	-0.020	-1.300
Gimbal to Primary GNSS lever arm std dev (m)	0.030	0.030	0.030
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

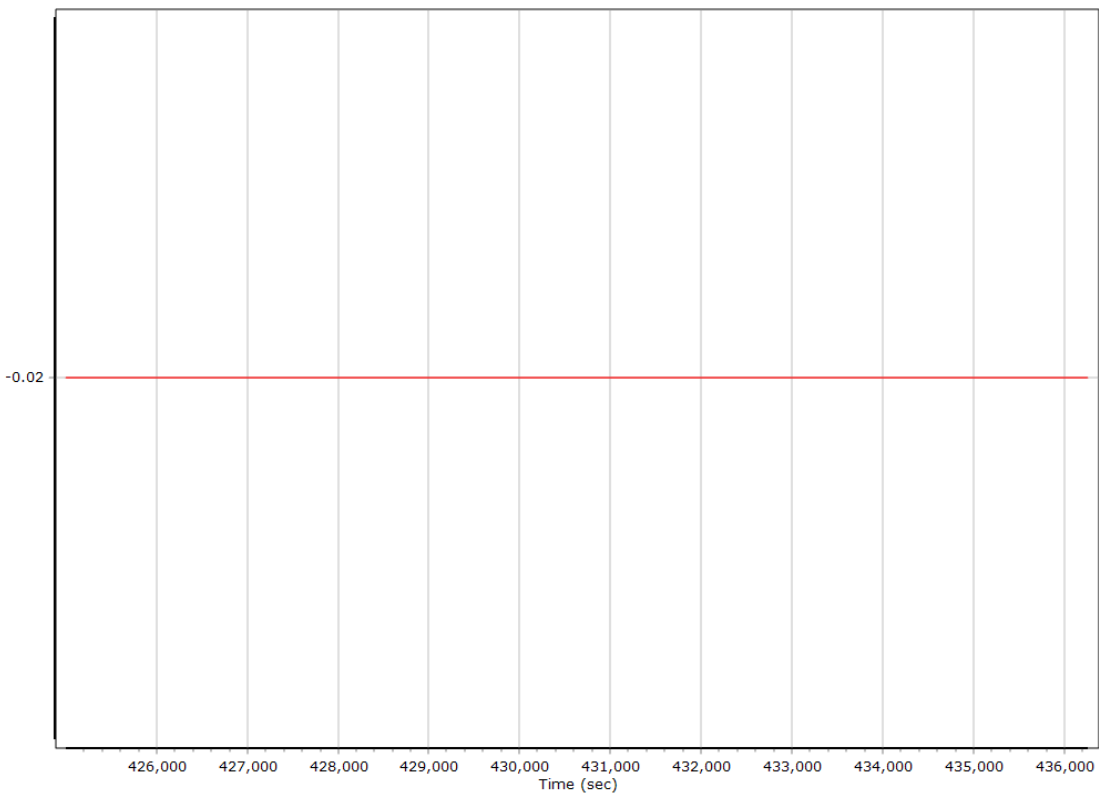
Calibrated Installation Parameters

Reference-Primary GNSS Lever Arm (m)

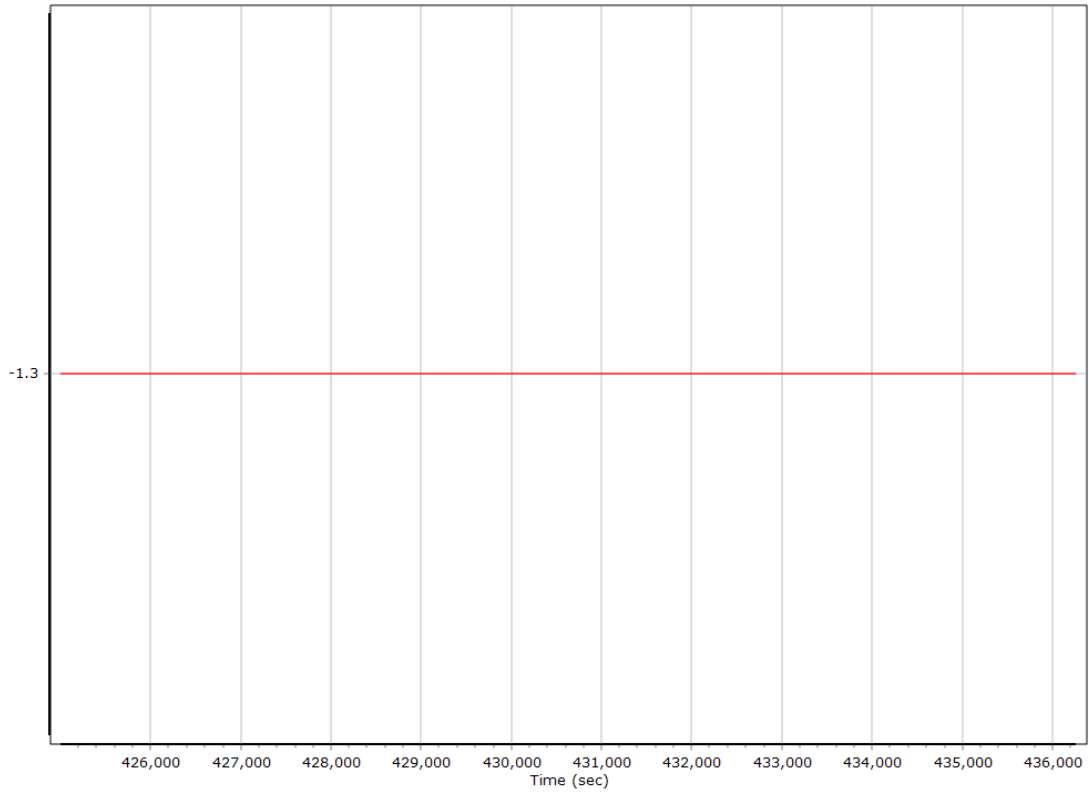
X Reference-Primary GNSS Lever Arm (m)



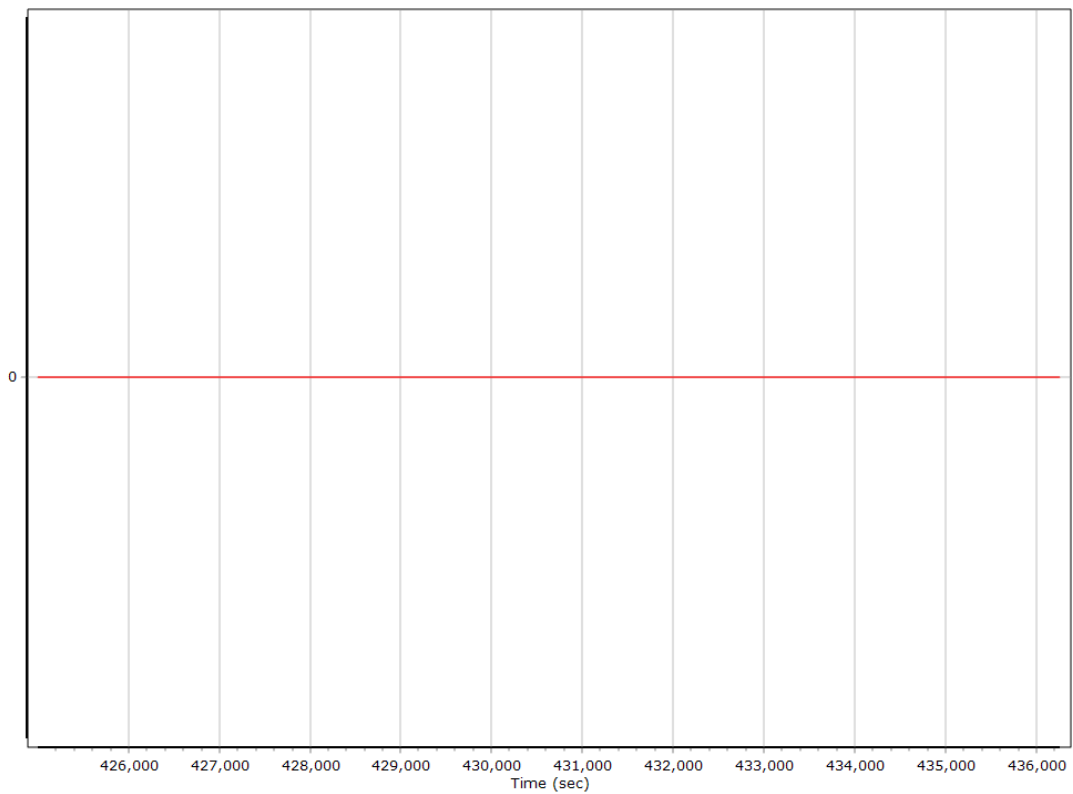
Y Reference-Primary GNSS Lever Arm (m)



Z Reference-Primary GNSS Lever Arm (m)



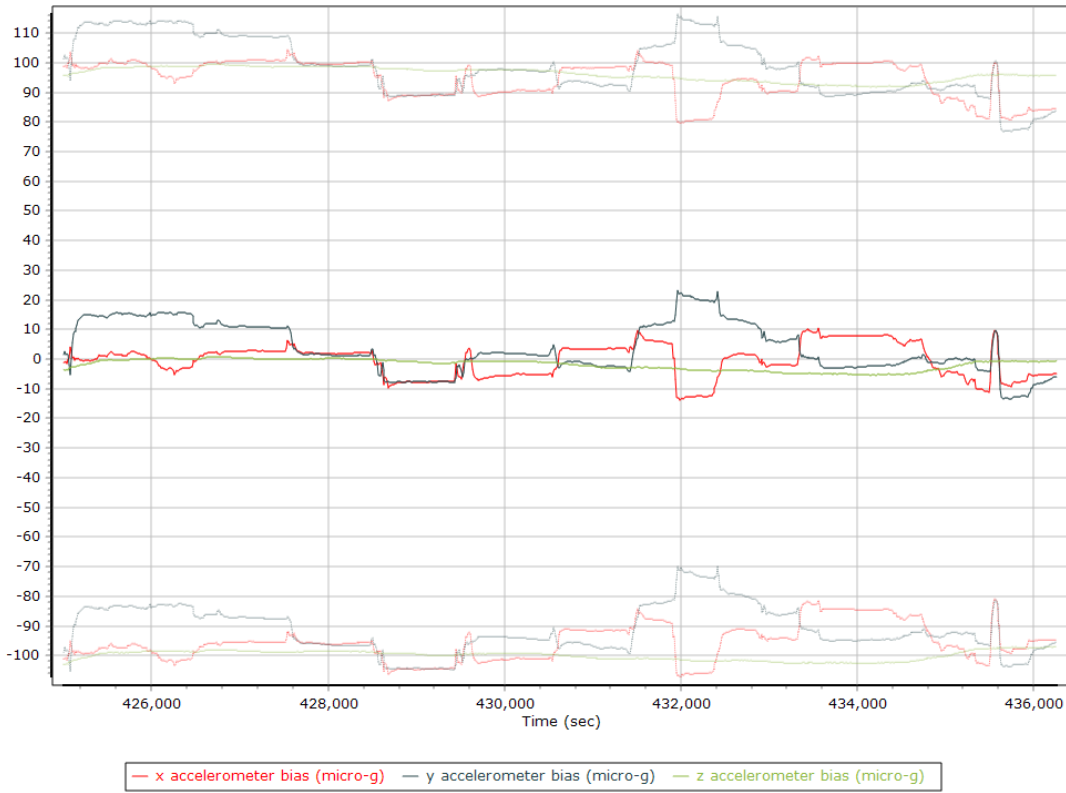
Reference-Primary GNSS Lever Arm Figure of Merit



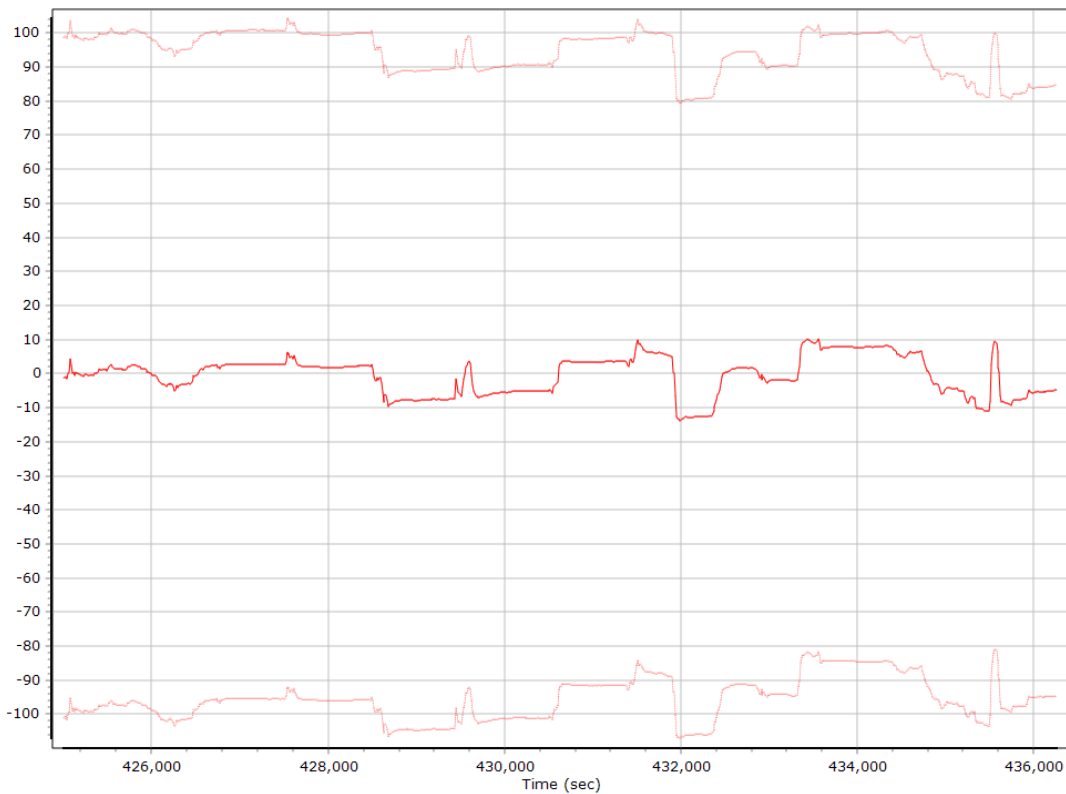
IN-Fusion QC

Forward Processed Estimated Errors, Reference Frame

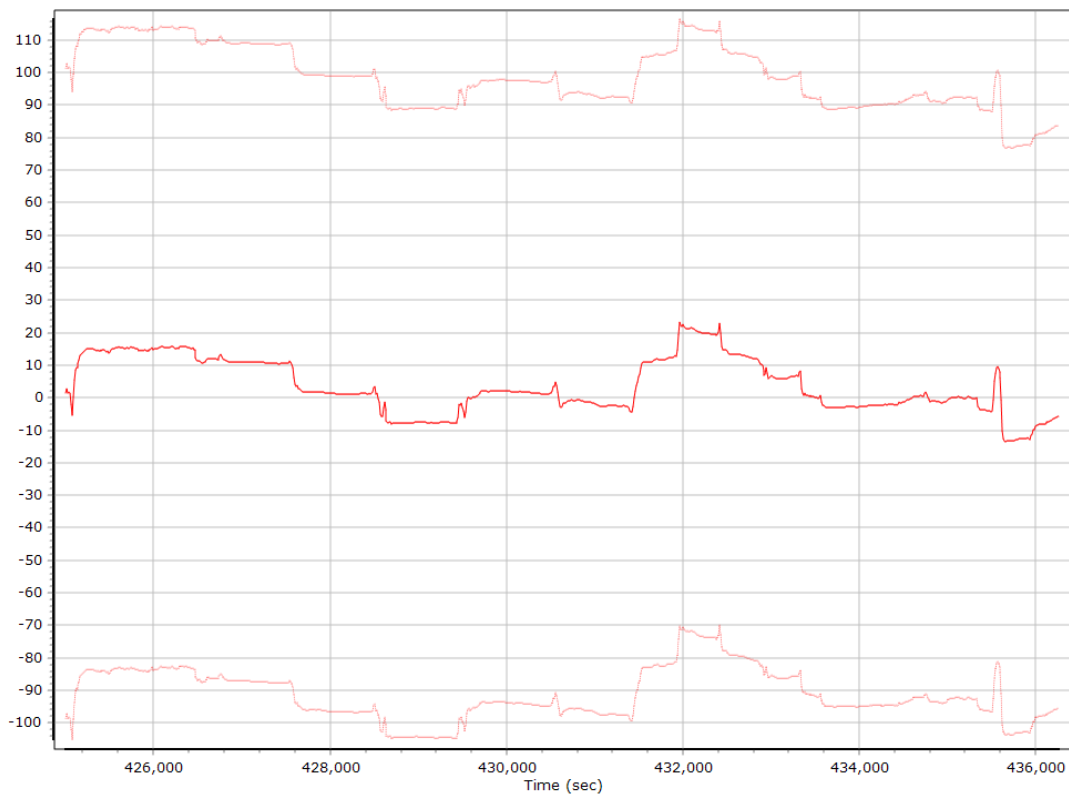
Accelerometer Bias (micro-g)



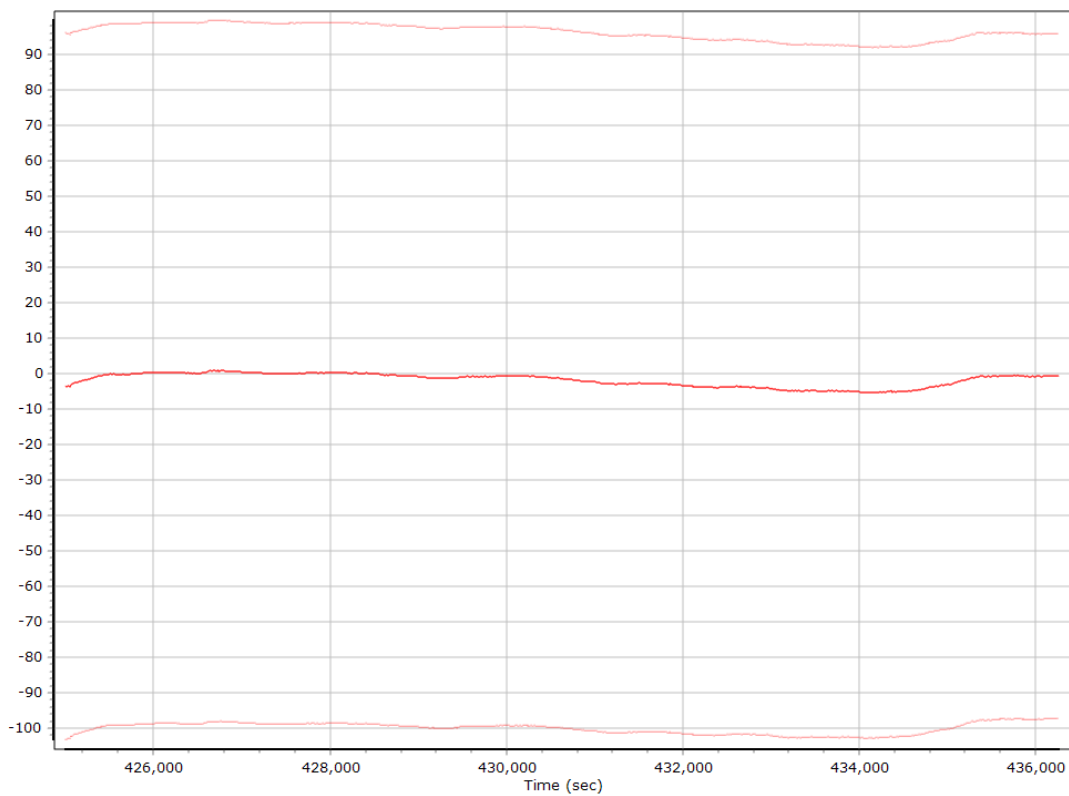
X Accelerometer Bias (micro-g)



Y Accelerometer Bias (micro-g)



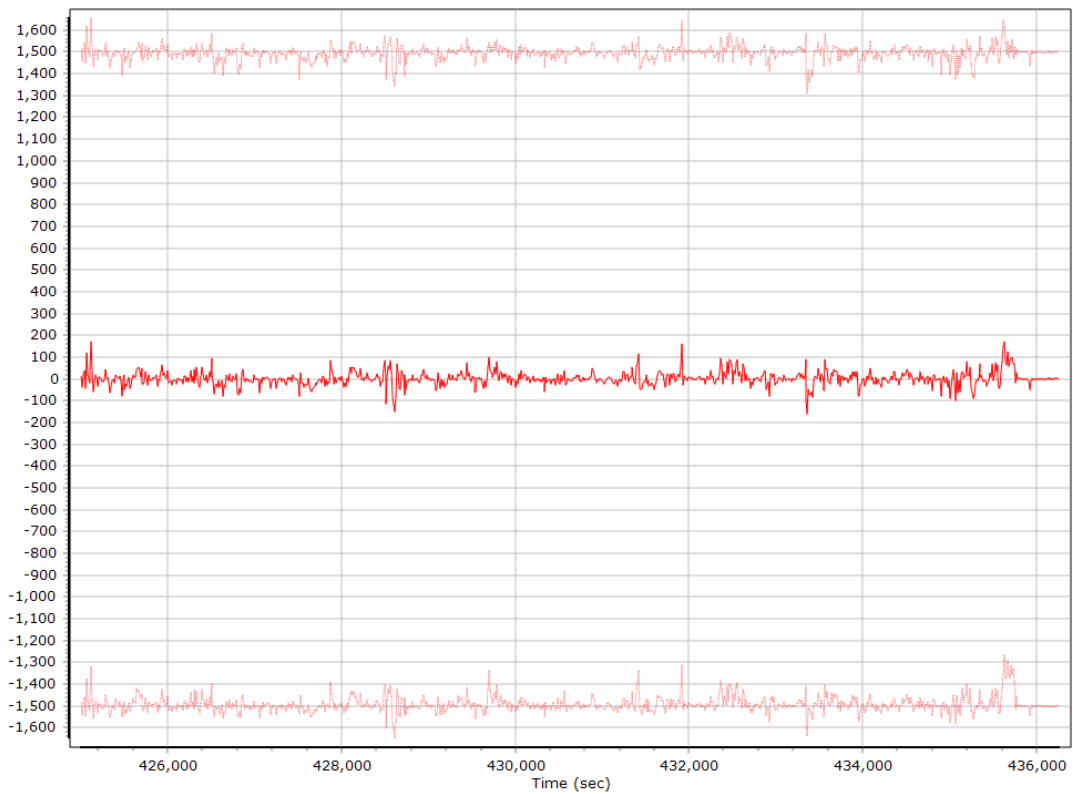
Z Accelerometer Bias (micro-g)



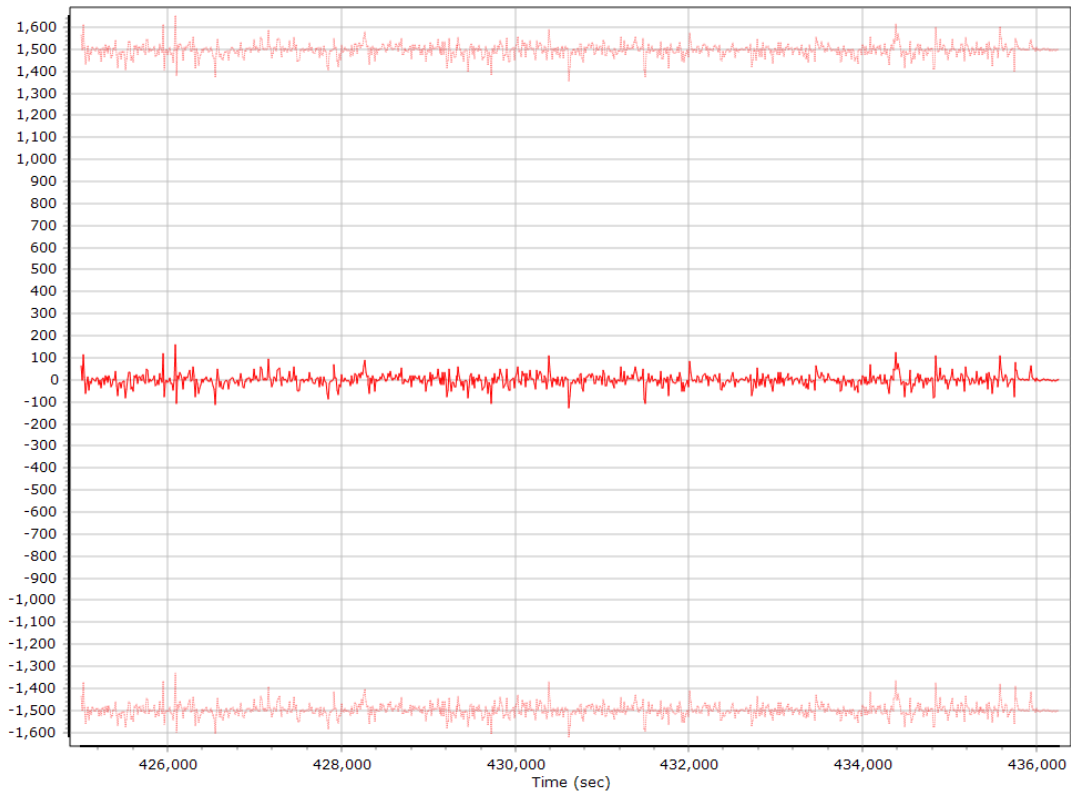
Accelerometer Scale Error (ppm)



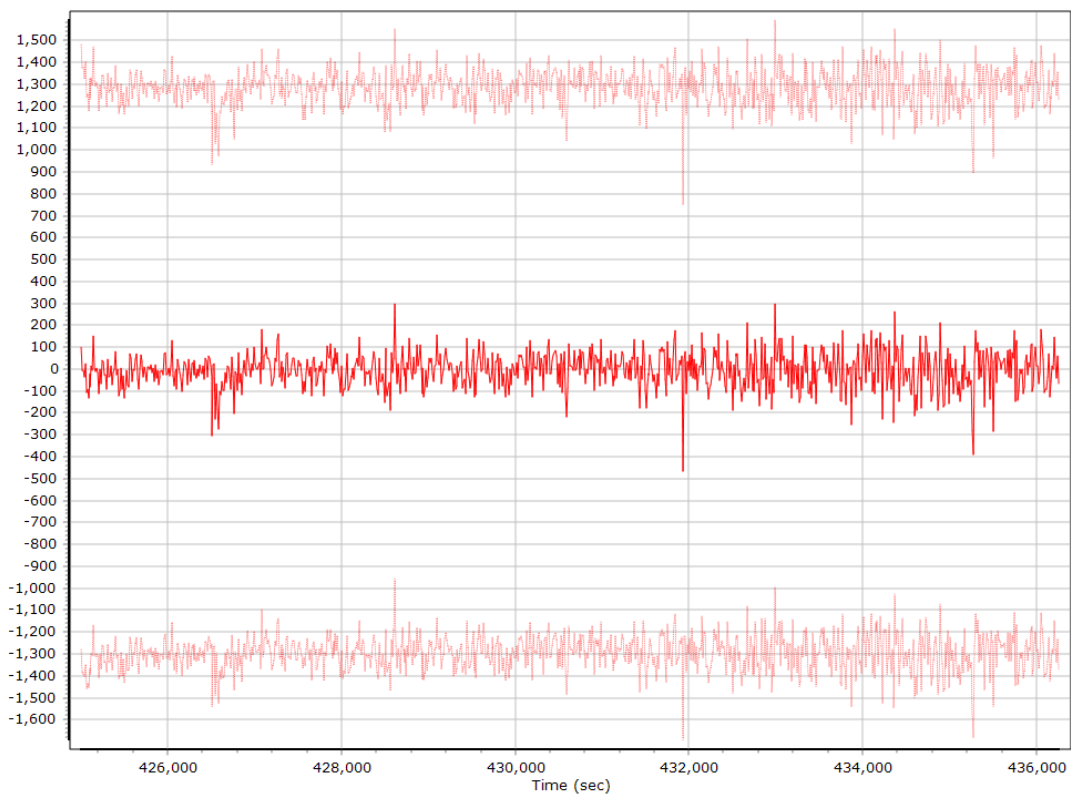
X Accelerometer Scale Error (ppm)



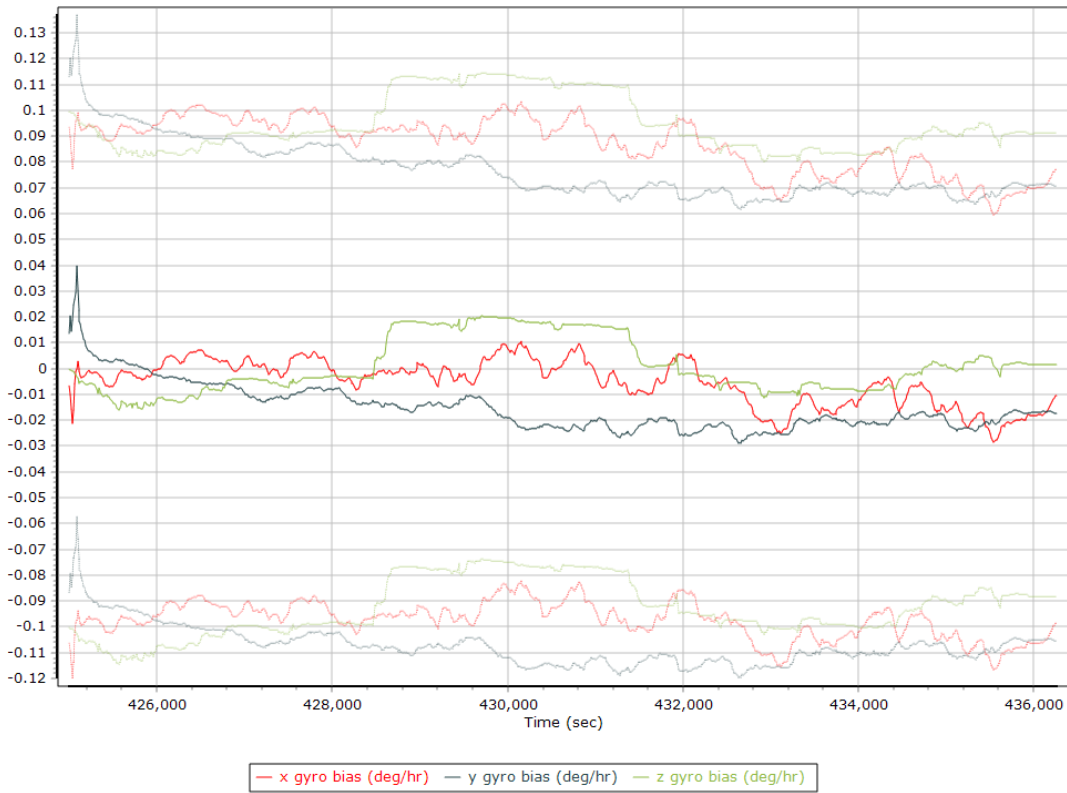
Y Accelerometer Scale Error (ppm)



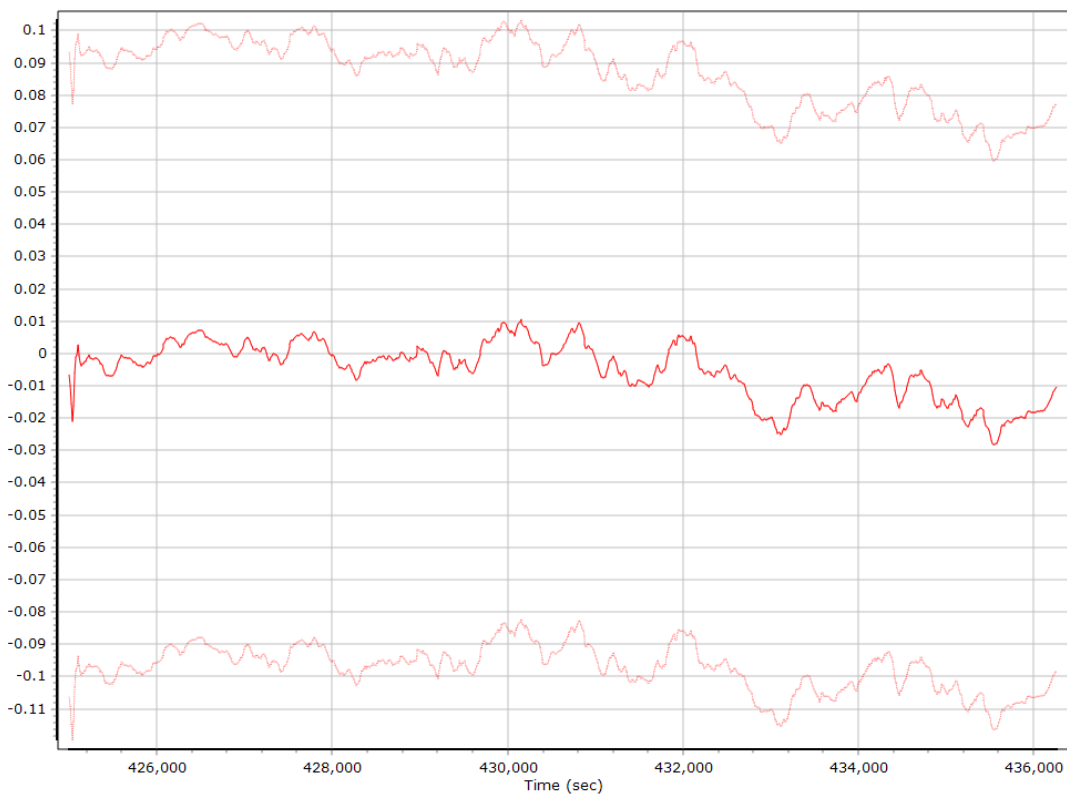
Z Accelerometer Scale Error (ppm)



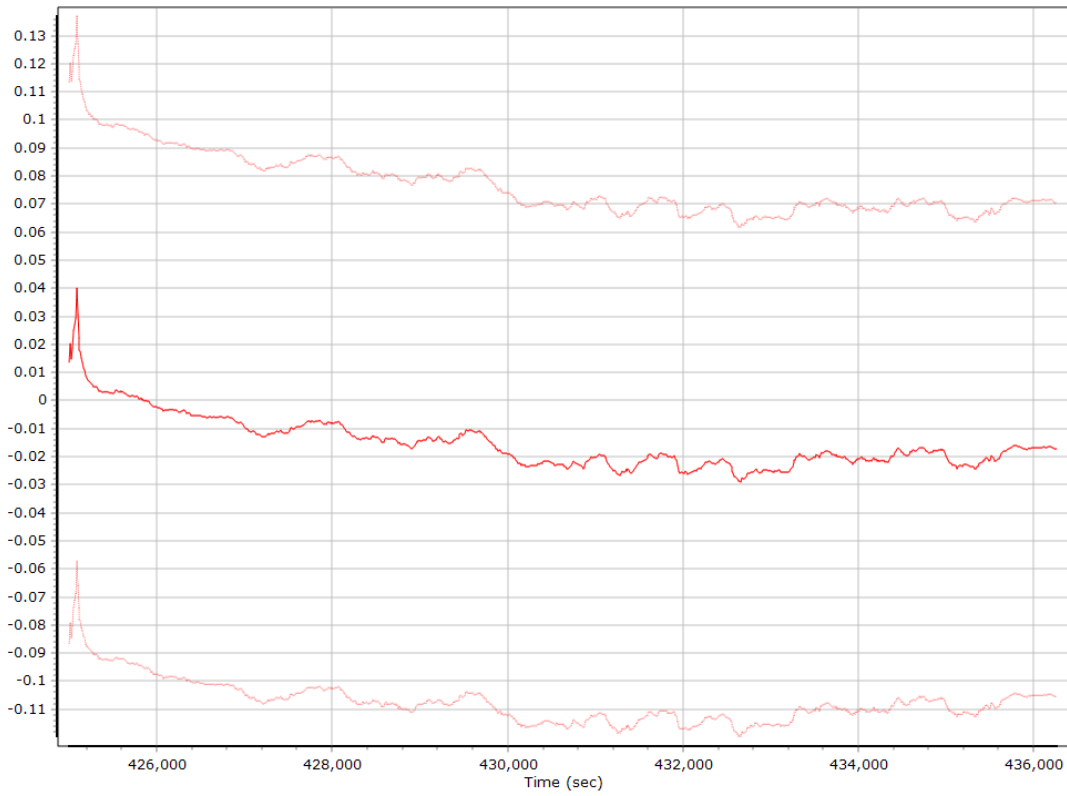
Gyro Bias (deg/h)



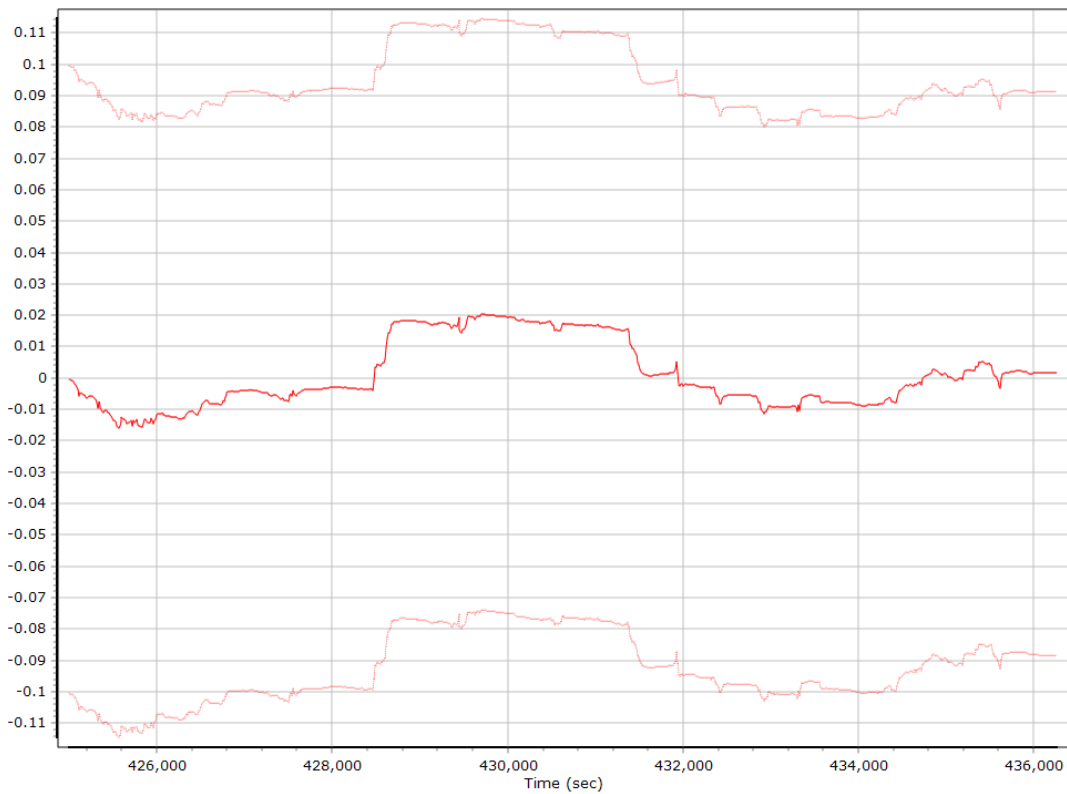
X Gyro Bias (deg/h)



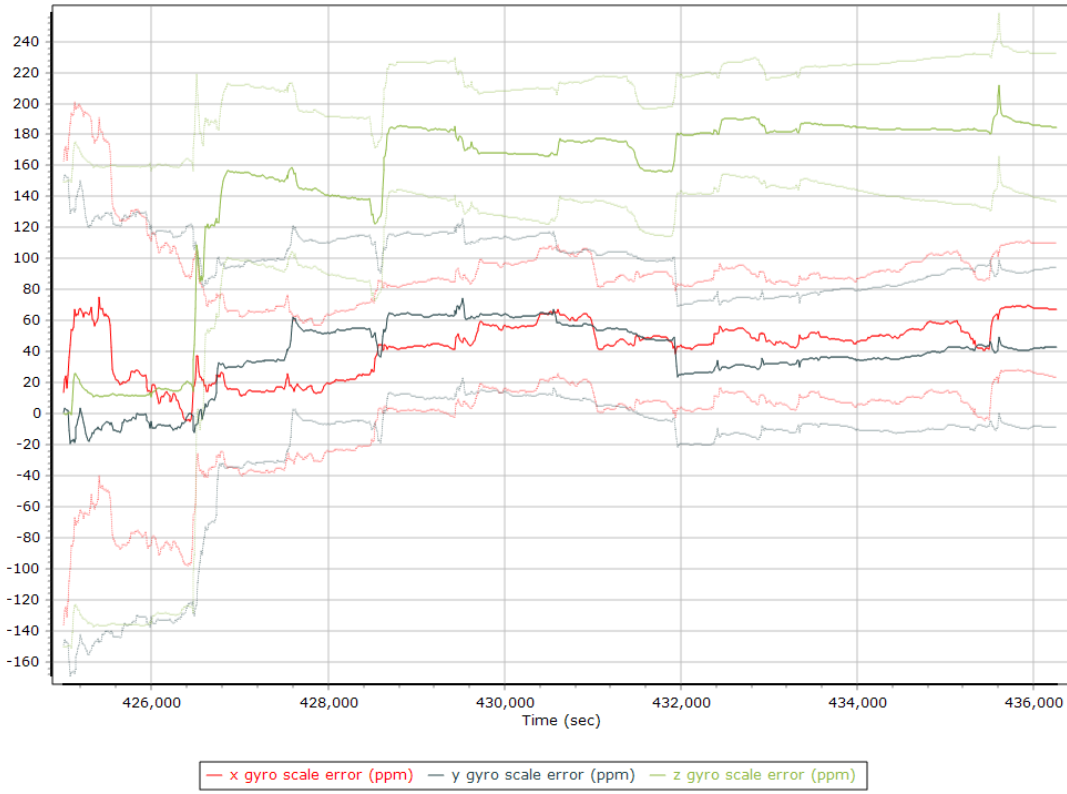
Y Gyro Bias (deg/h)



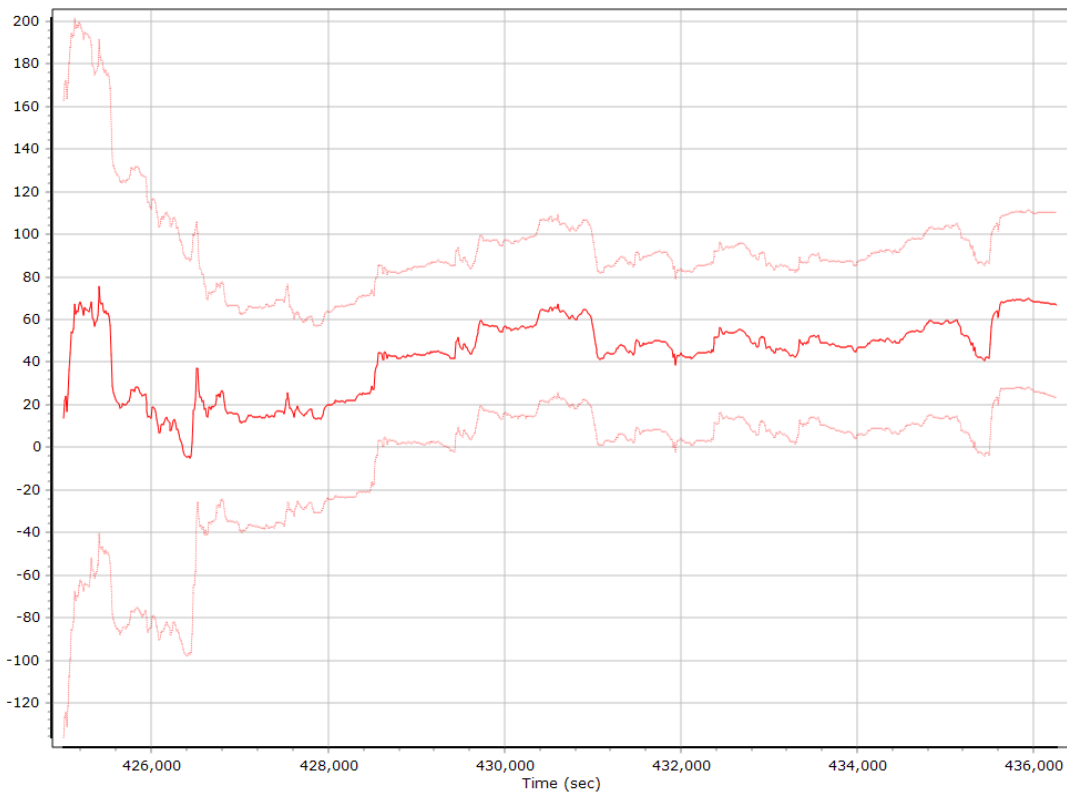
Z Gyro Bias (deg/h)



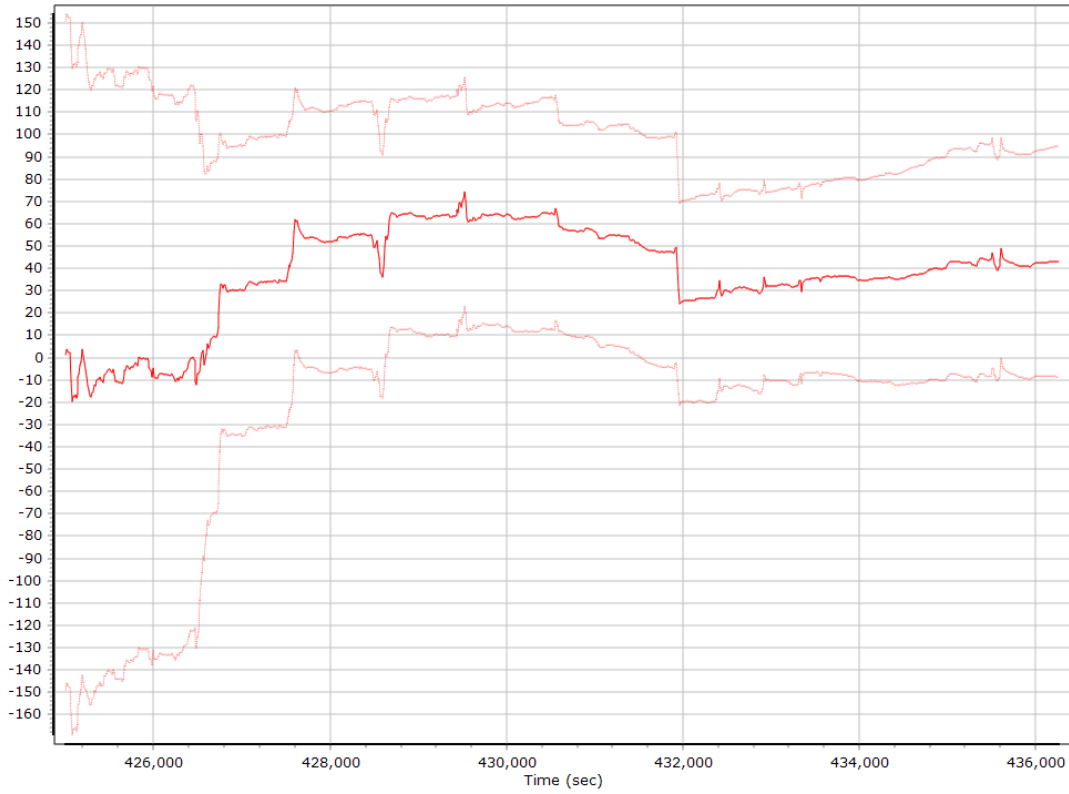
Gyro Scale Error (ppm)



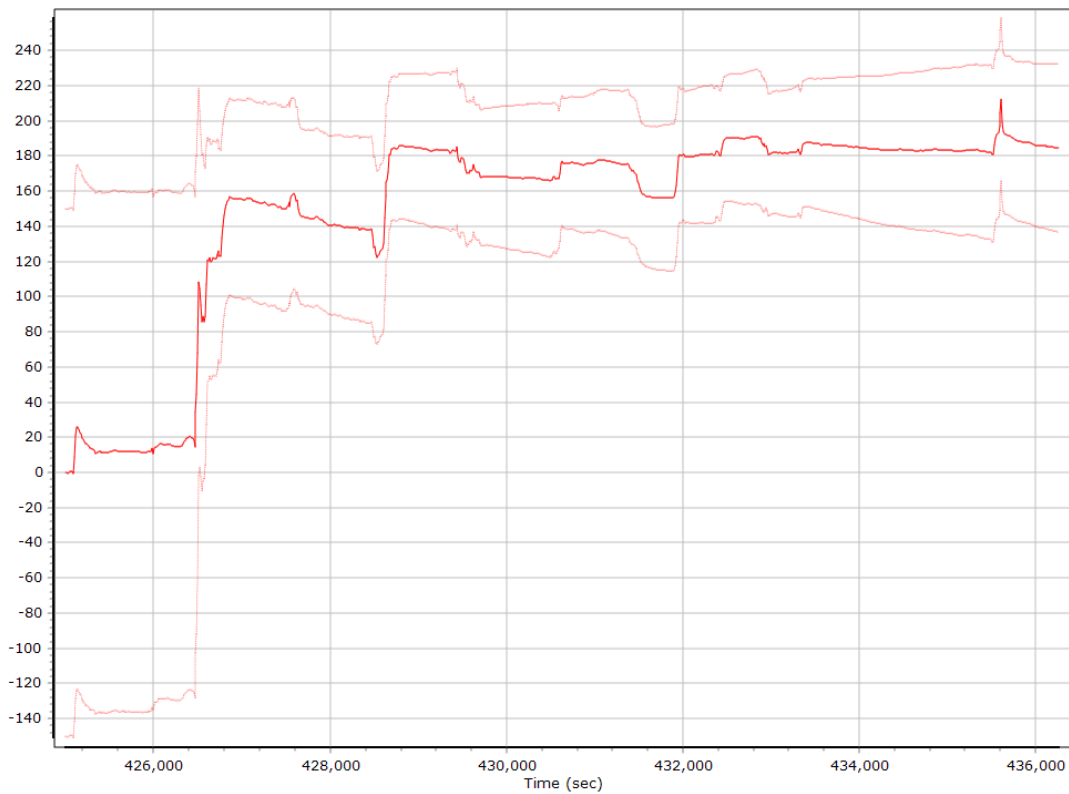
X Gyro Scale Error (ppm)



Y Gyro Scale Error (ppm)

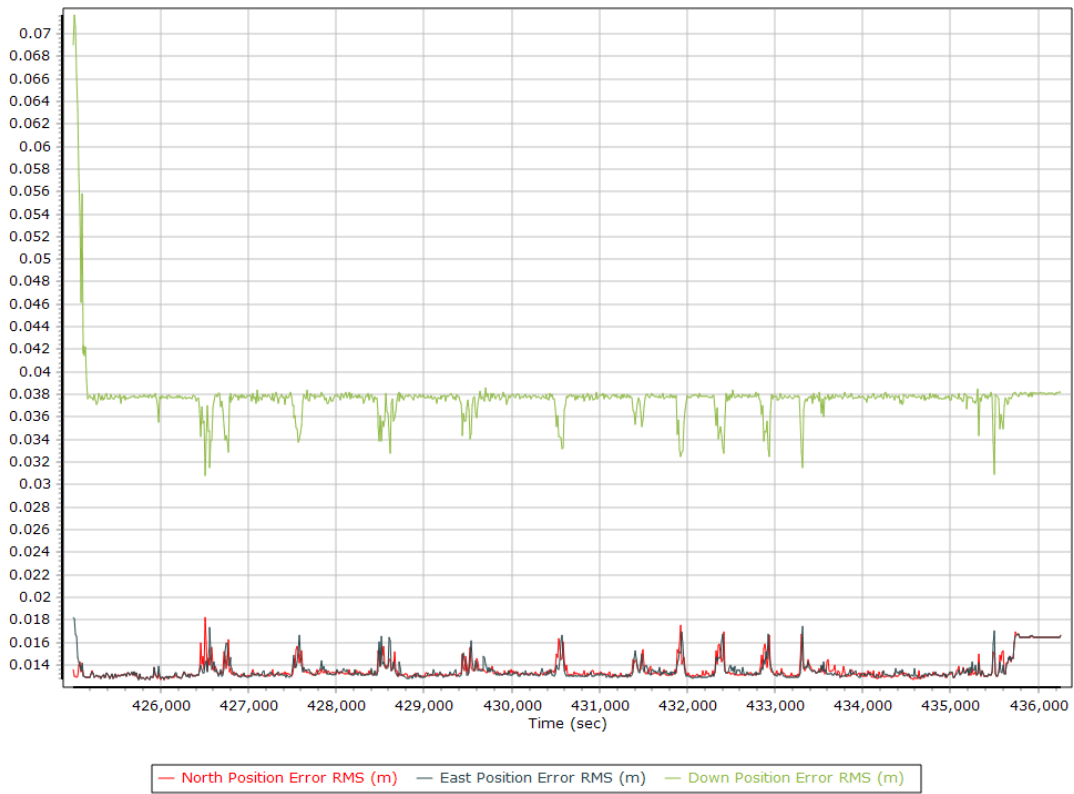


Z Gyro Scale Error (ppm)

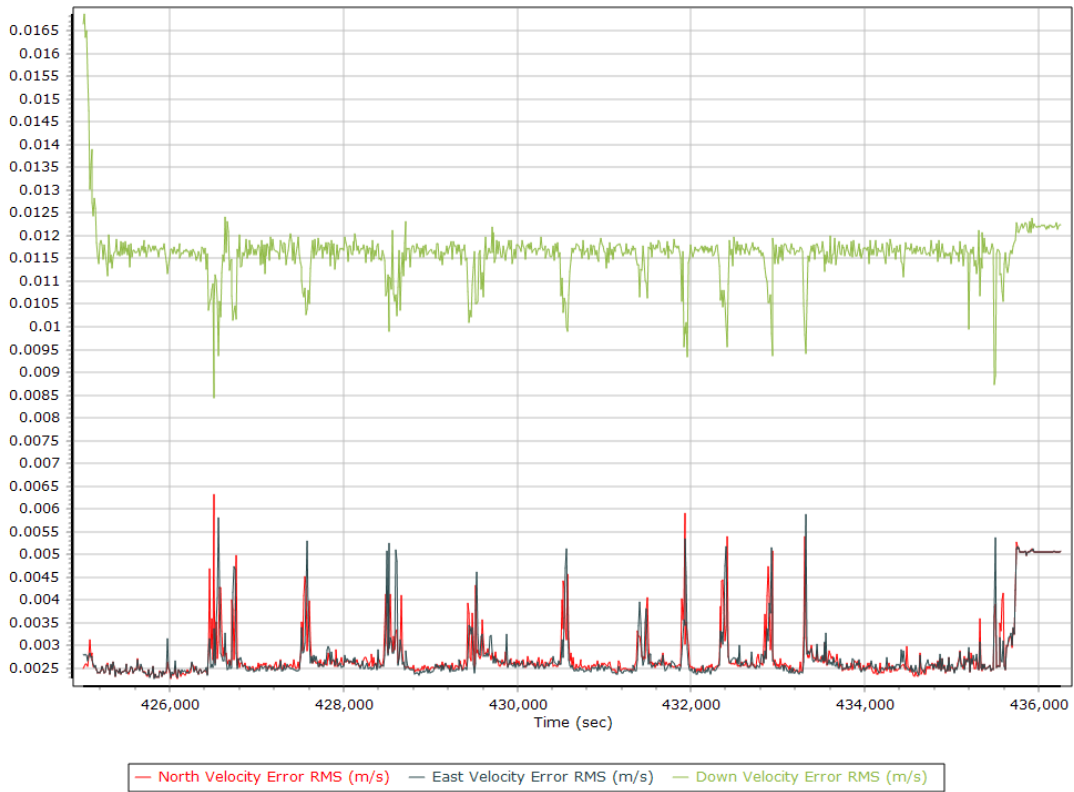


Smoothed Performance Metrics

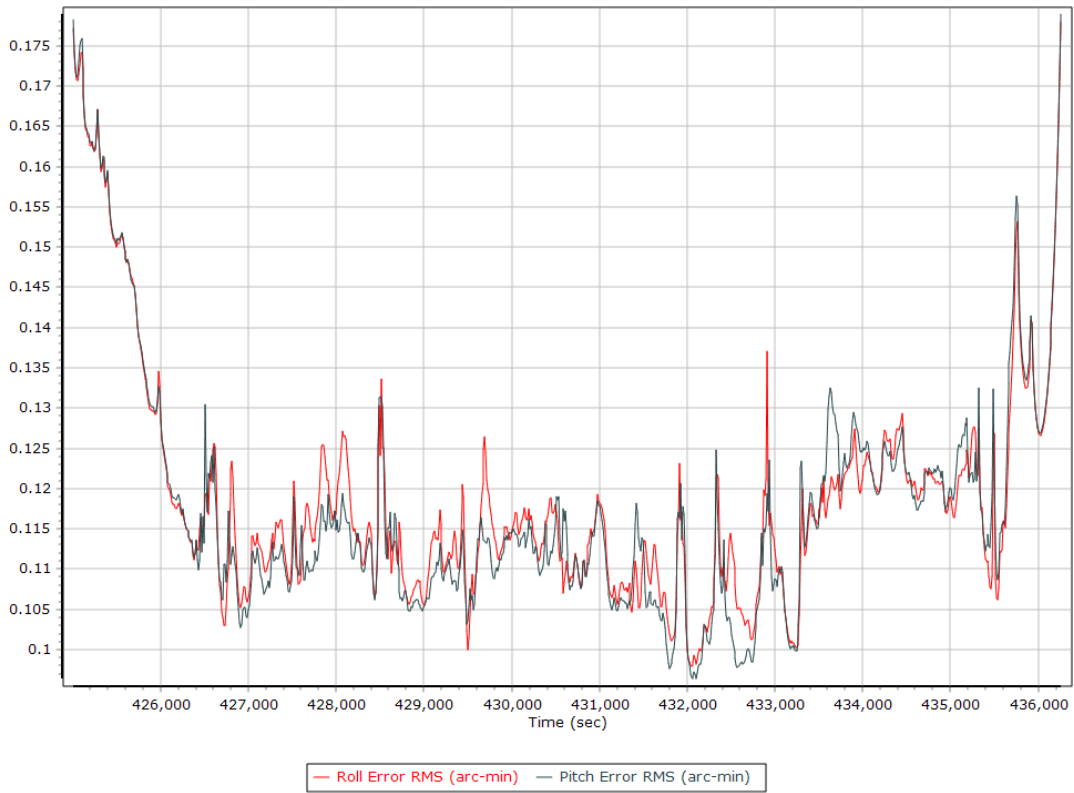
Position Error RMS (m)



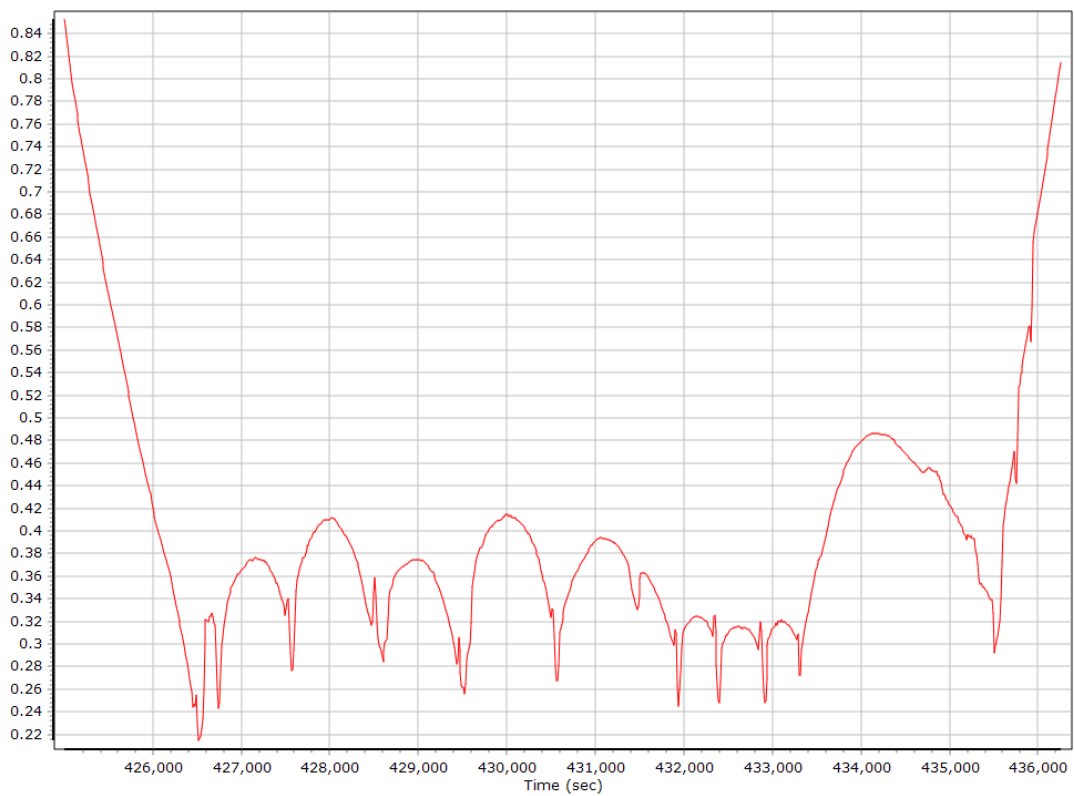
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

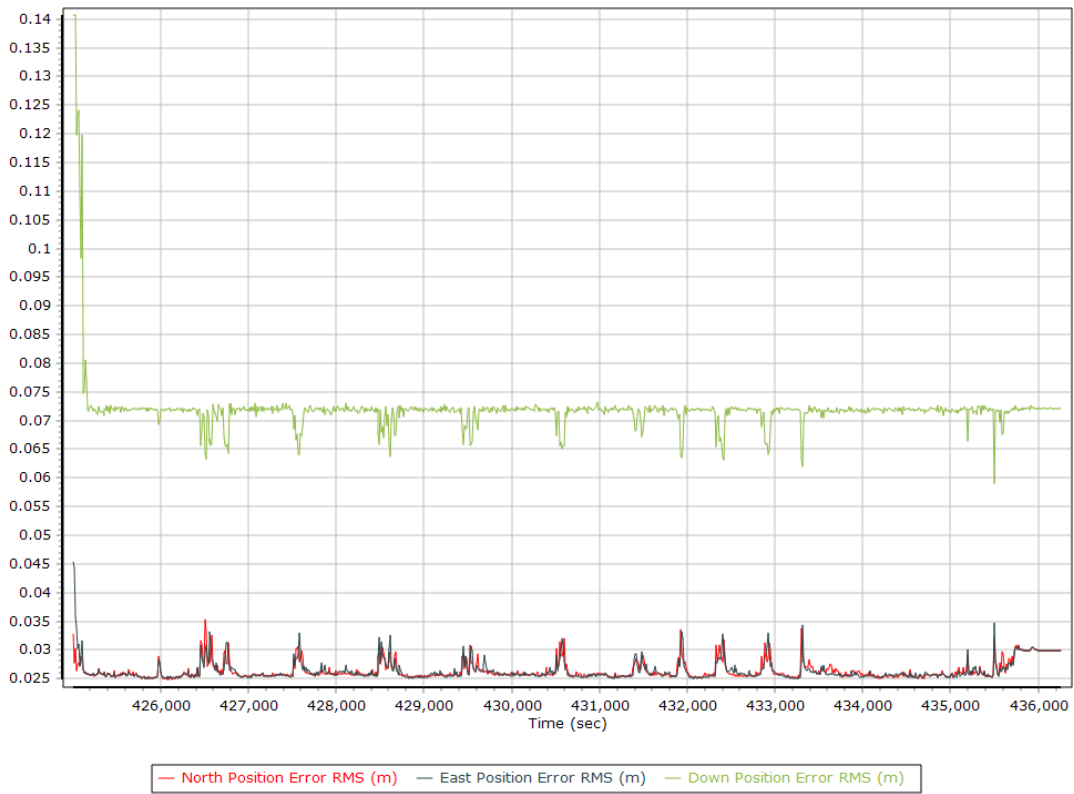


Heading Error RMS (arc-min)

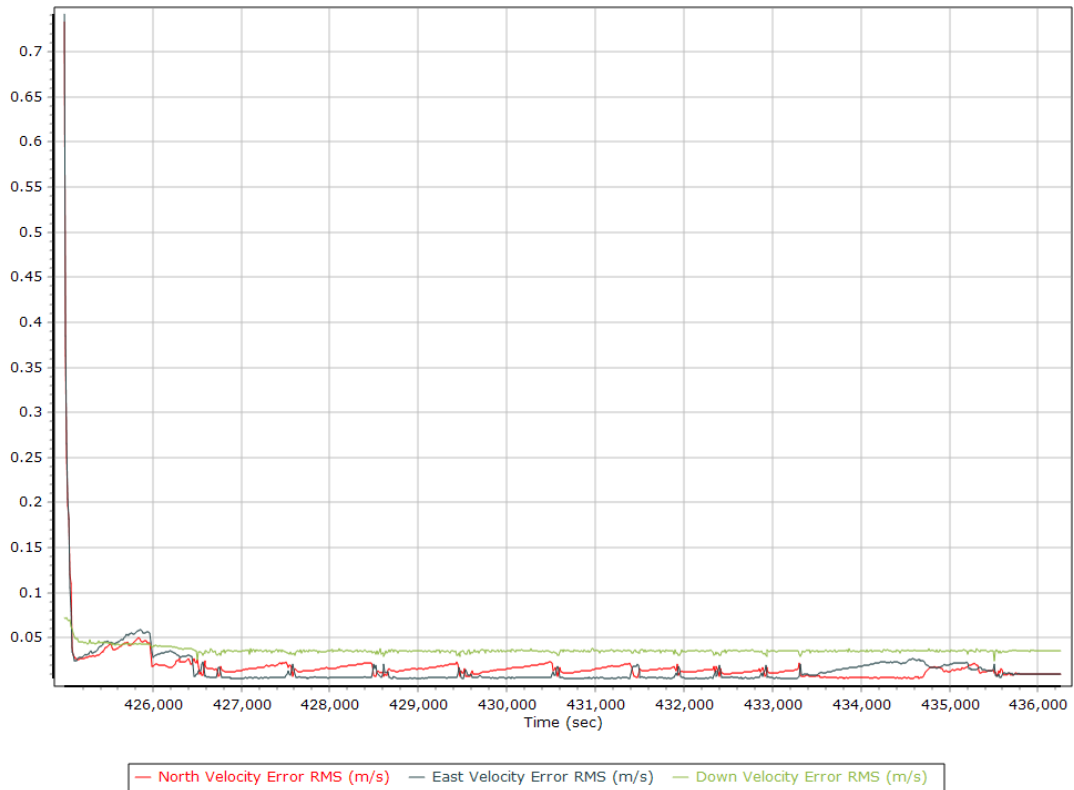


Forward Processed Performance Metrics

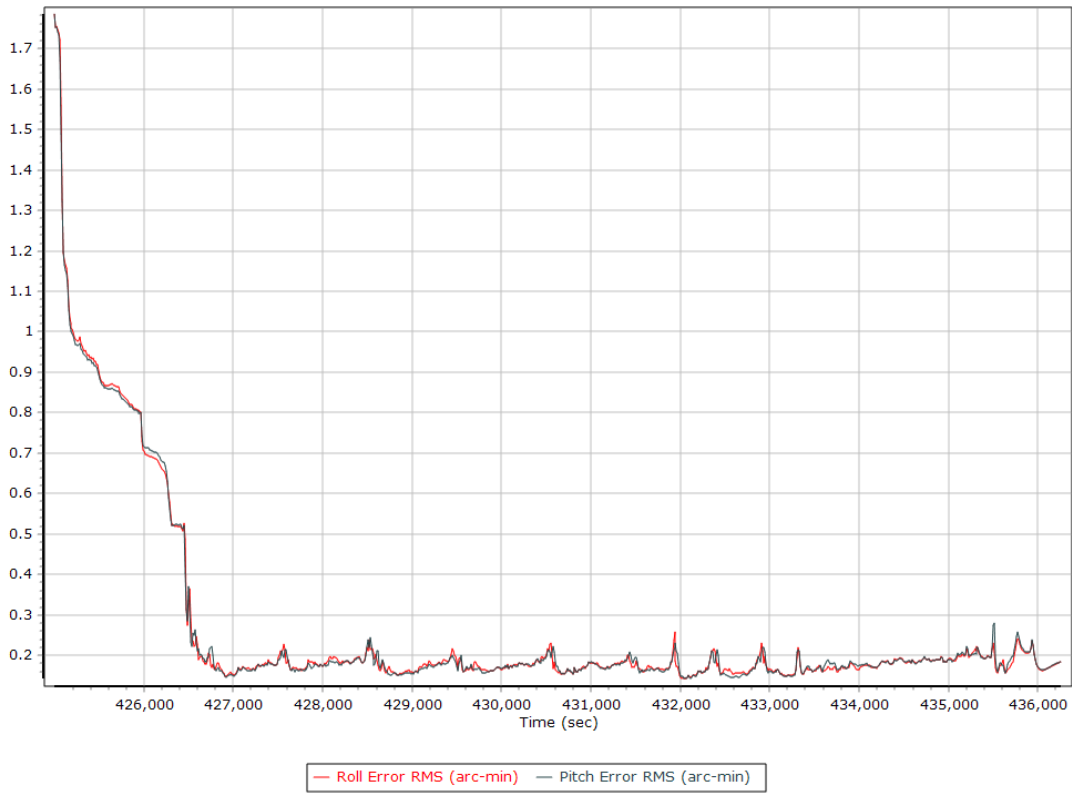
Position Error RMS (m)



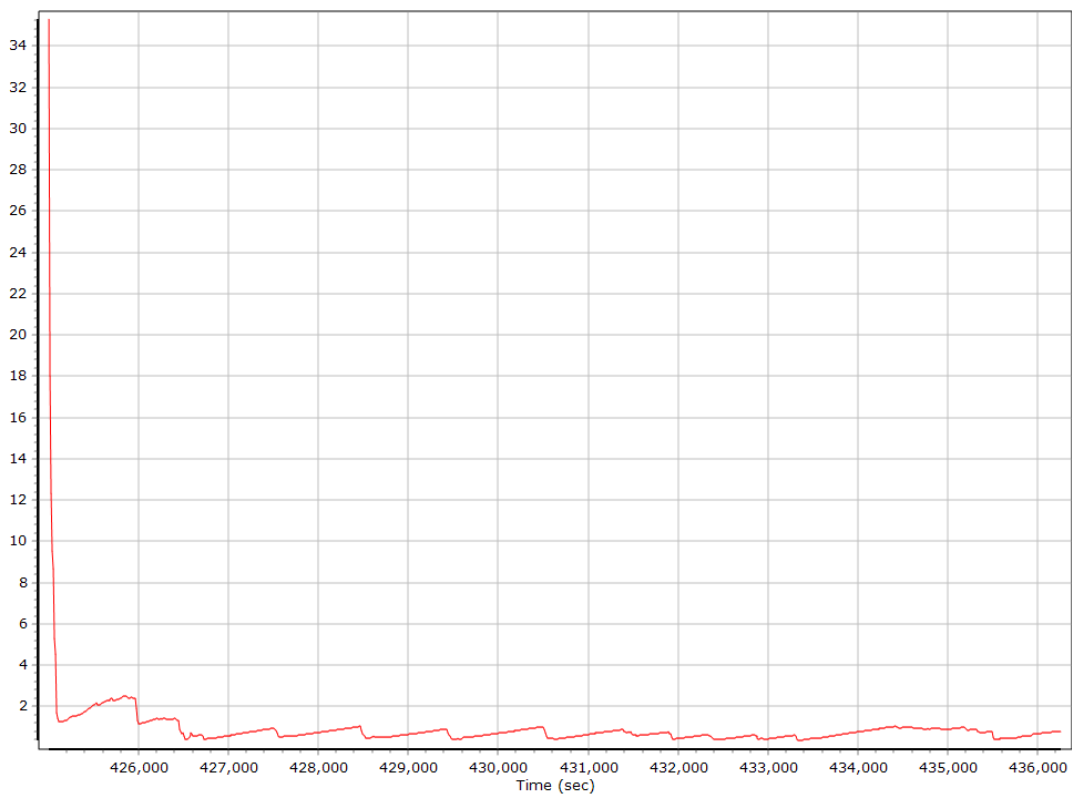
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

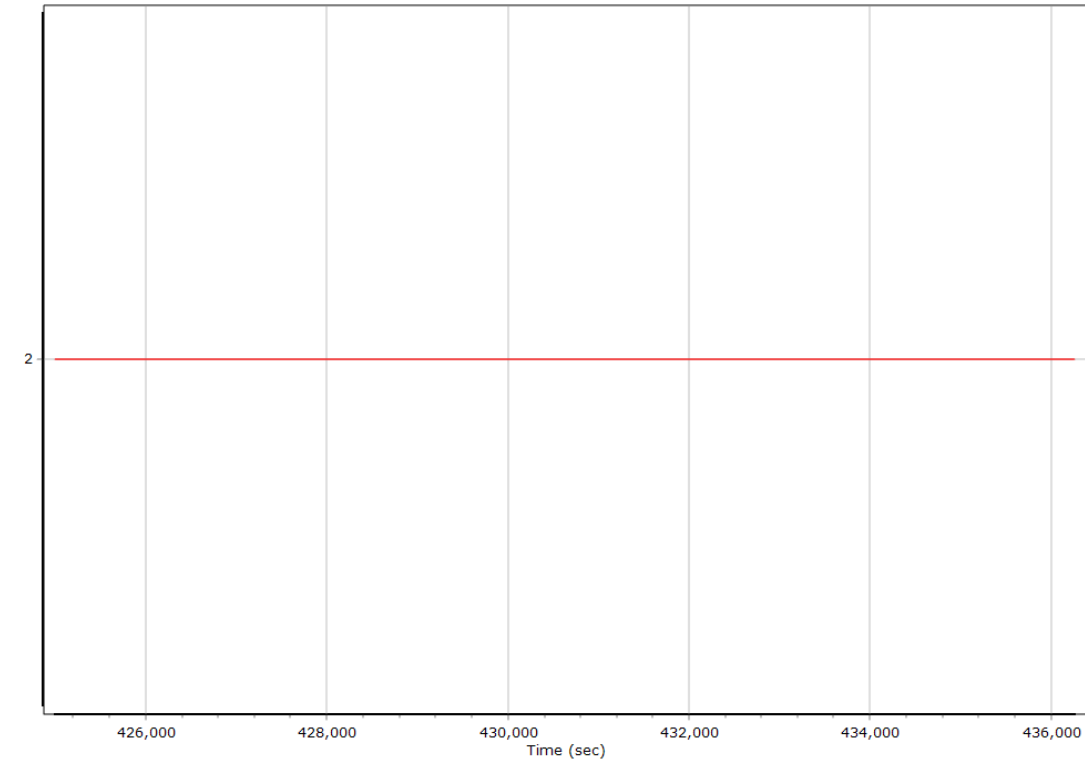


Heading Error RMS (arc-min)



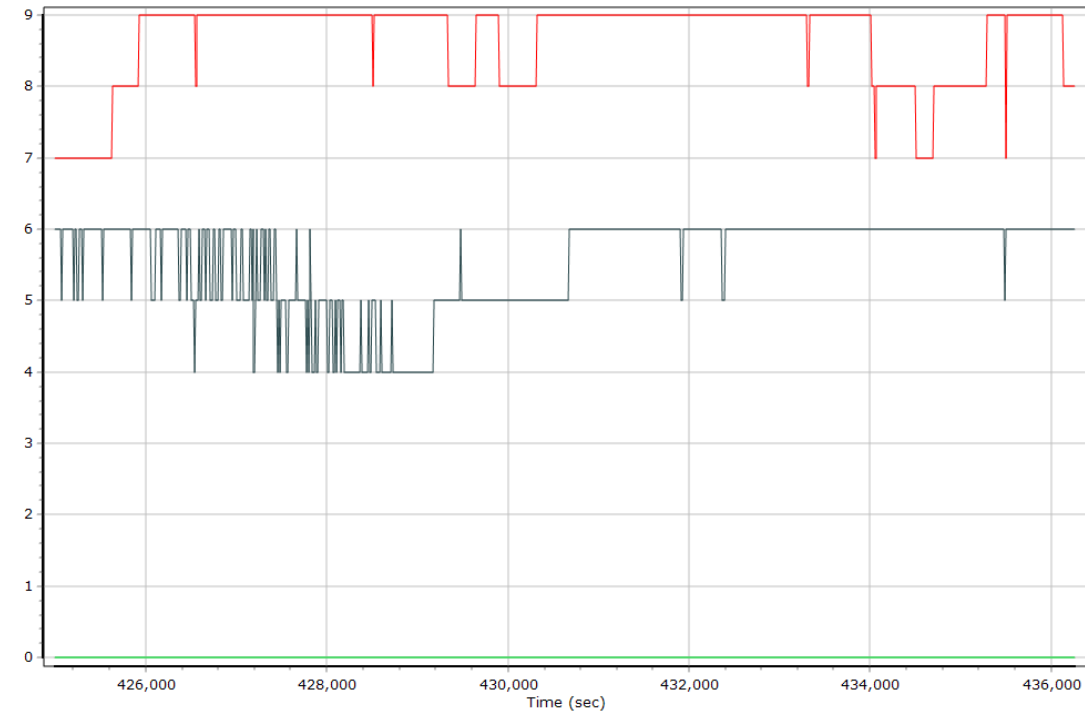
Forward Processed Solution Status

Processing Mode



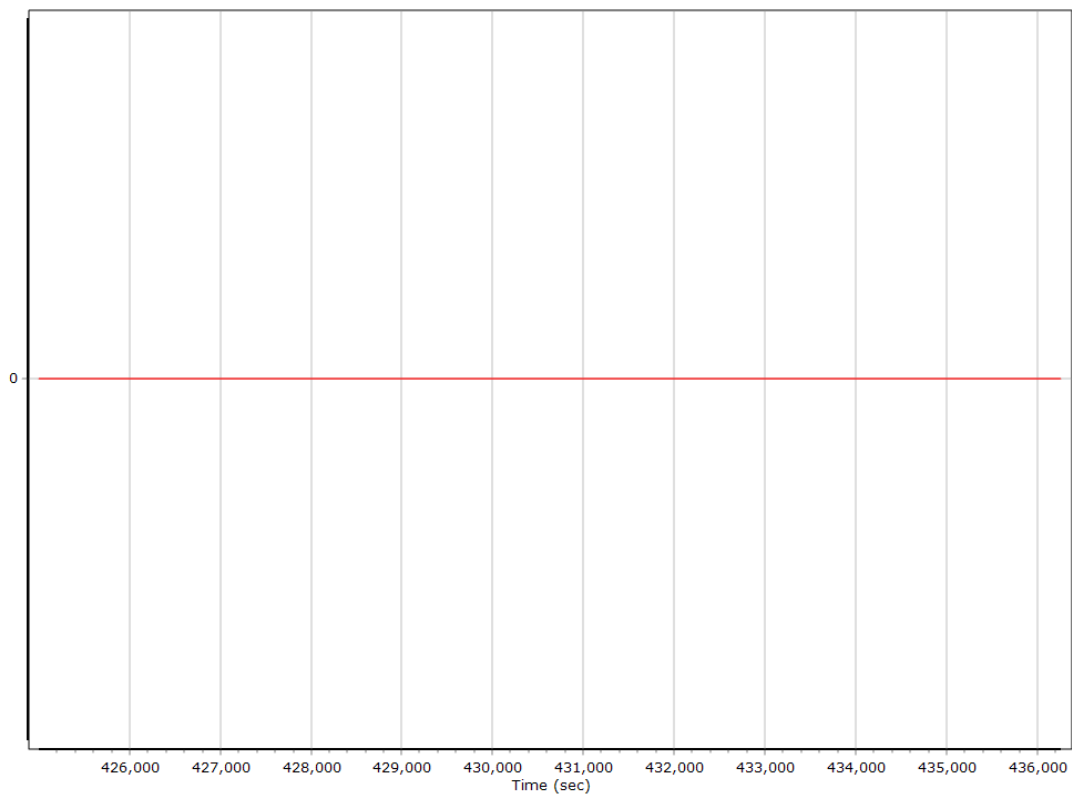
0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = C/A, 7 = GNSS Nav, 8 = DR

Number of Satellites



— Number of GPS Satellites — Number of GLONASS Satellites — Number of QZSS Satellites
 — Number of BEIDOU Satellites — Number of GALILEO Satellites

Baseline Length



General Information

Mission Information

Project name	21-081_FFSL_210917
Processing date	2021-10-18 15:45:23
Mission date	2021-09-17 15:29:01
Mission duration	07:09:38.000
Processing mode	IN-Fusion Trimble RTX Nav

Rover Hardware Information

Product	POS AV 610 VER6 HW2.5-12
Serial number	S/N11651
IMU type	57
Receiver type	BD982
Antenna type	AV39

Project File List

Rover Data Files

File name	File type
210917_152842_INS-GPS_1.raw	POS Data

Input Files

File Name	File Type
Ephm2600.21g	GLONASS Broadcast Ephemeris
Ephm2600.21n	GPS Broadcast Ephemeris

Output Files

Filename	File type
sbet_21-081_FFSL_210917.out	SBET Trajectory File
export_21-081_FFSL_210917.out	Custom Smoothed BET Export Output

Rover Data Summary

First raw data file	210917_152842_INS-GPS_1.raw		
Last raw data file	210917_152842_INS-GPS_1.raw		
Start GPS week	2175		
Start time	487722.647 (09/17/2021 15:28:42)		
End time	513497.416 (09/17/2021 22:38:17)		
Start of fine alignment	488125.222 (09/17/2021 15:35:25)		
Available subsystems	Primary GNSS, Gimbal, IMU		
POS Event Input	None		
Correction data	Trimble RTX		
IMU Installation Lever Arms & Mounting Angles			
Gimbal to IMU lever arm (m)	-0.034	-0.010	-0.374
Gimbal to IMU mounting angles (deg)	0.000	0.000	0.000
Gimbal to Primary GNSS lever arm (m)	0.980	-0.102	-1.276
Gimbal to Primary GNSS lever arm std dev (m)	-1.000		
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

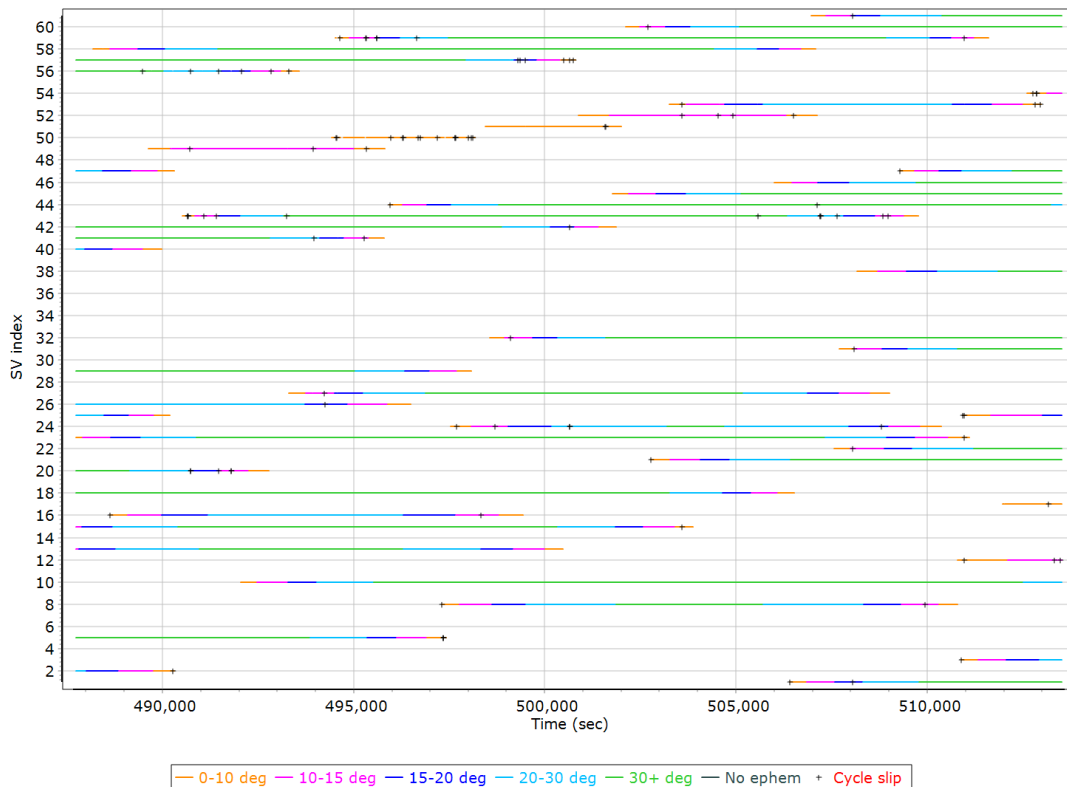
Rover Data QC

Raw IMU Import QC Summary

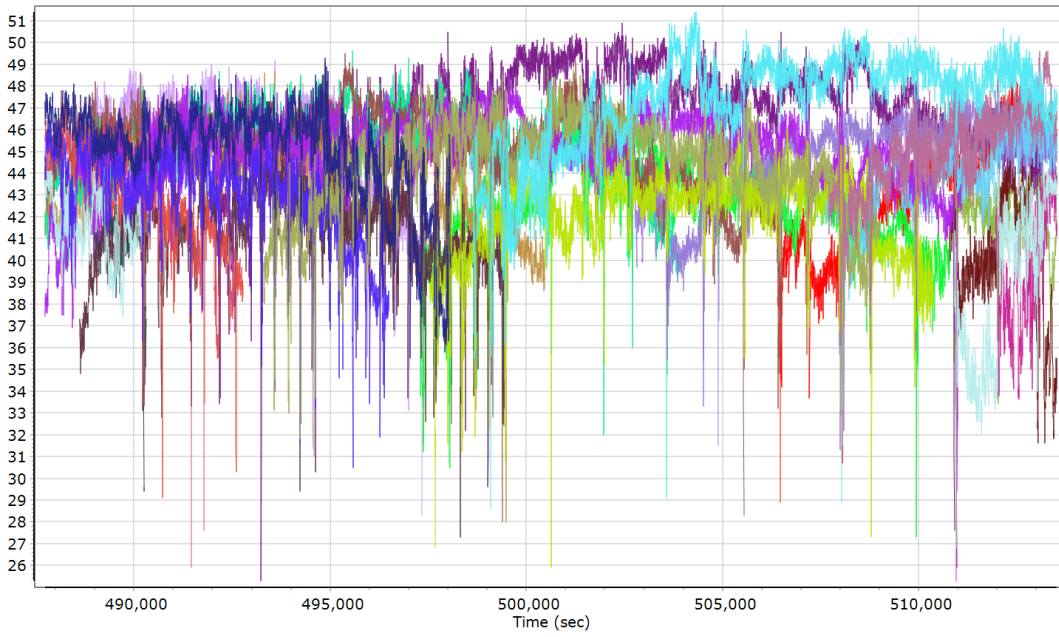
IMU data input file	imu_21-081_FFSL_210917.dat
IMU data check log file	imudt_21-081_FFSL_210917.log
IMU Records Processed	5154813
Termination Status	Normal
IMU Anomalies	0

Primary Observables & Satellite Data

GPS/GLONASS L1 Satellite Lock/Elevation

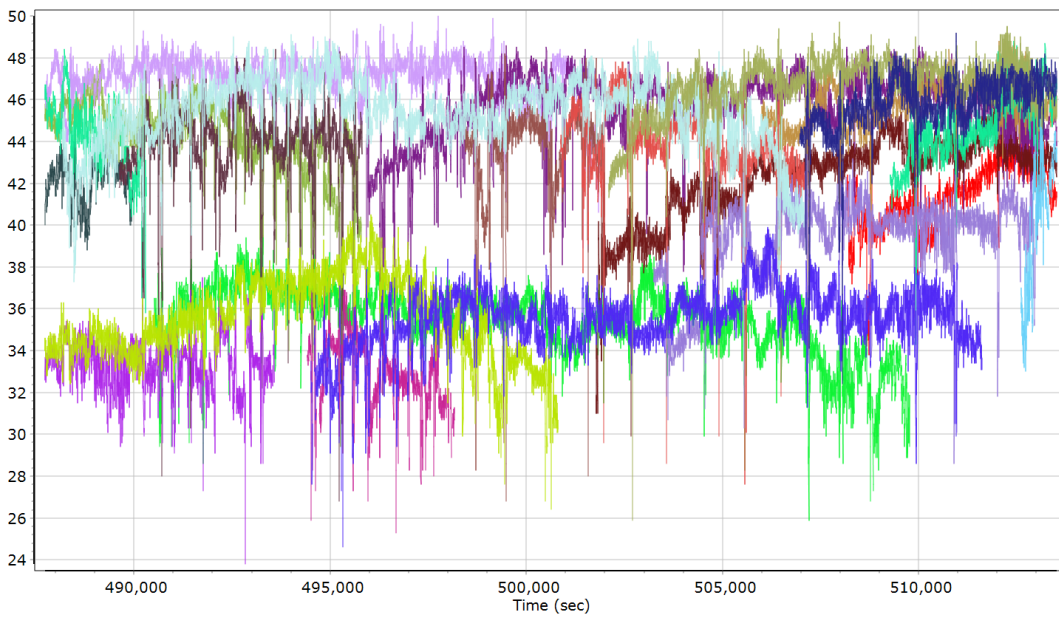


GPS L1 SNR



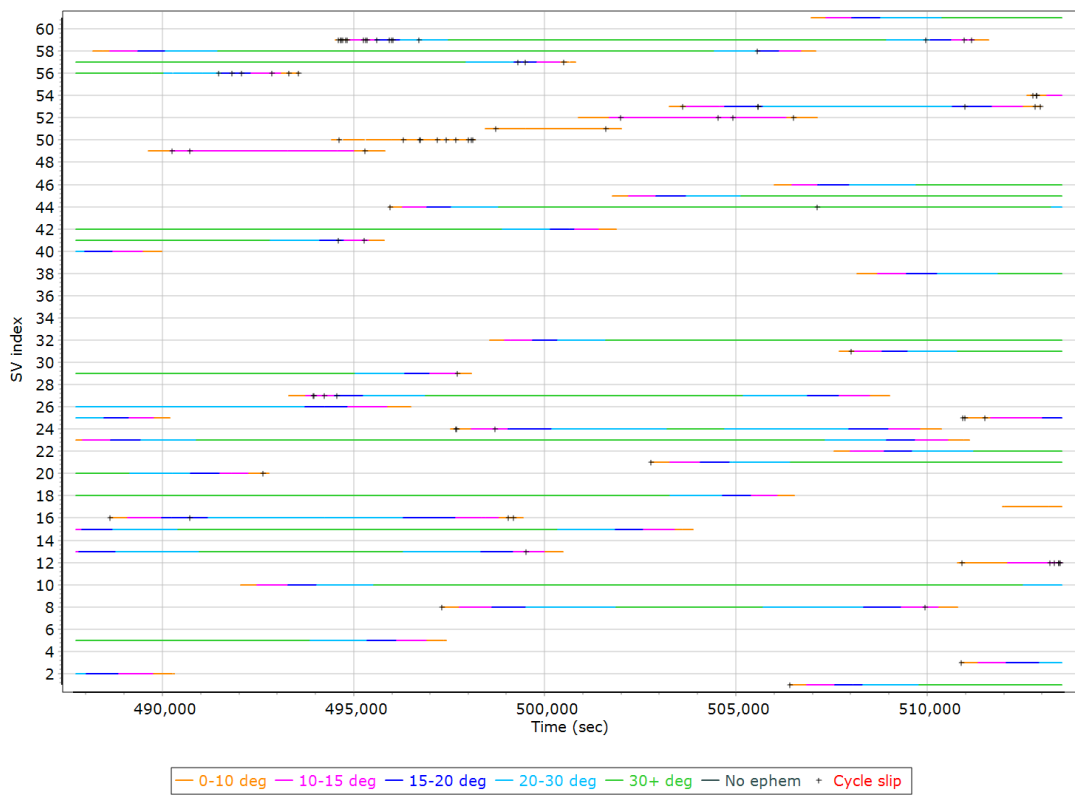
- | | | | |
|---------------------------|---------------------------|---------------------------|---------------------------|
| GPS PRN 01 L1 SNR (dB/Hz) | GPS PRN 02 L1 SNR (dB/Hz) | GPS PRN 03 L1 SNR (dB/Hz) | GPS PRN 05 L1 SNR (dB/Hz) |
| GPS PRN 08 L1 SNR (dB/Hz) | GPS PRN 10 L1 SNR (dB/Hz) | GPS PRN 12 L1 SNR (dB/Hz) | GPS PRN 13 L1 SNR (dB/Hz) |
| GPS PRN 15 L1 SNR (dB/Hz) | GPS PRN 16 L1 SNR (dB/Hz) | GPS PRN 17 L1 SNR (dB/Hz) | GPS PRN 18 L1 SNR (dB/Hz) |
| GPS PRN 20 L1 SNR (dB/Hz) | GPS PRN 21 L1 SNR (dB/Hz) | GPS PRN 22 L1 SNR (dB/Hz) | GPS PRN 23 L1 SNR (dB/Hz) |
| GPS PRN 24 L1 SNR (dB/Hz) | GPS PRN 25 L1 SNR (dB/Hz) | GPS PRN 26 L1 SNR (dB/Hz) | GPS PRN 27 L1 SNR (dB/Hz) |
| GPS PRN 29 L1 SNR (dB/Hz) | GPS PRN 31 L1 SNR (dB/Hz) | GPS PRN 32 L1 SNR (dB/Hz) | |

GLONASS L1 SNR

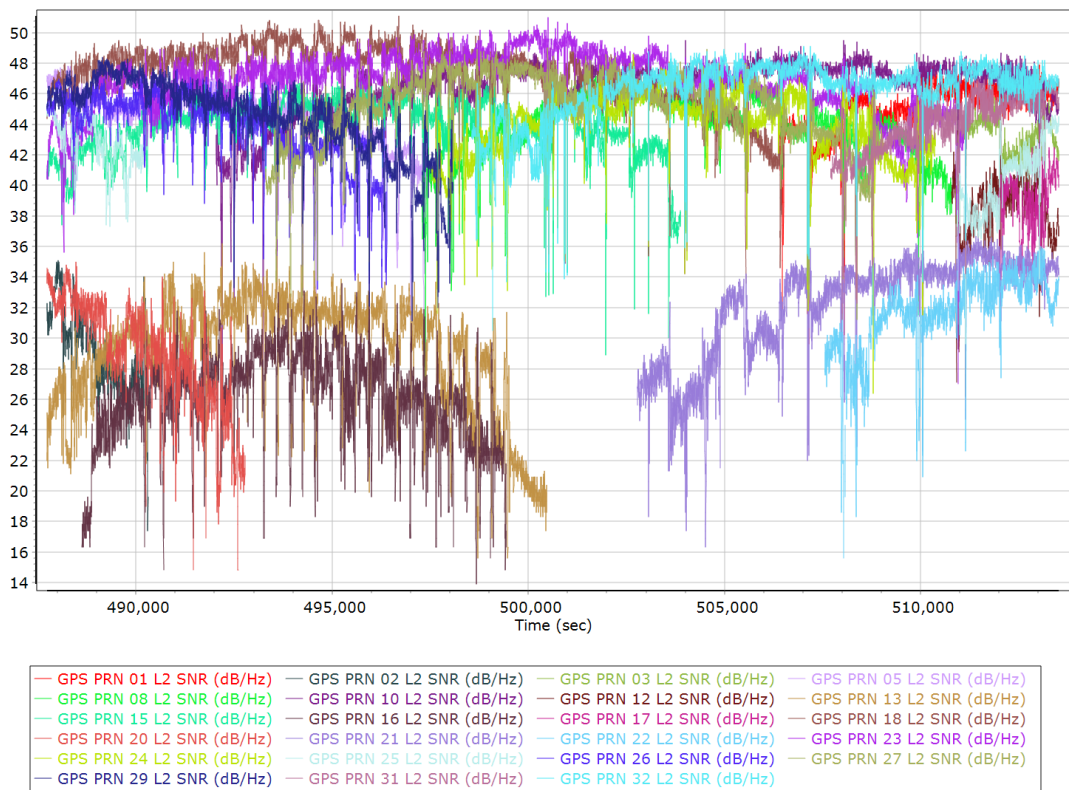


- | | | |
|---------------------------|---------------------------|---------------------------|
| GLONASS 01 L1 SNR (dB/Hz) | GLONASS 03 L1 SNR (dB/Hz) | GLONASS 04 L1 SNR (dB/Hz) |
| GLONASS 05 L1 SNR (dB/Hz) | GLONASS 06 L1 SNR (dB/Hz) | GLONASS 07 L1 SNR (dB/Hz) |
| GLONASS 08 L1 SNR (dB/Hz) | GLONASS 09 L1 SNR (dB/Hz) | GLONASS 10 L1 SNR (dB/Hz) |
| GLONASS 12 L1 SNR (dB/Hz) | GLONASS 13 L1 SNR (dB/Hz) | GLONASS 14 L1 SNR (dB/Hz) |
| GLONASS 15 L1 SNR (dB/Hz) | GLONASS 16 L1 SNR (dB/Hz) | GLONASS 17 L1 SNR (dB/Hz) |
| GLONASS 19 L1 SNR (dB/Hz) | GLONASS 20 L1 SNR (dB/Hz) | GLONASS 21 L1 SNR (dB/Hz) |
| GLONASS 22 L1 SNR (dB/Hz) | GLONASS 23 L1 SNR (dB/Hz) | GLONASS 24 L1 SNR (dB/Hz) |

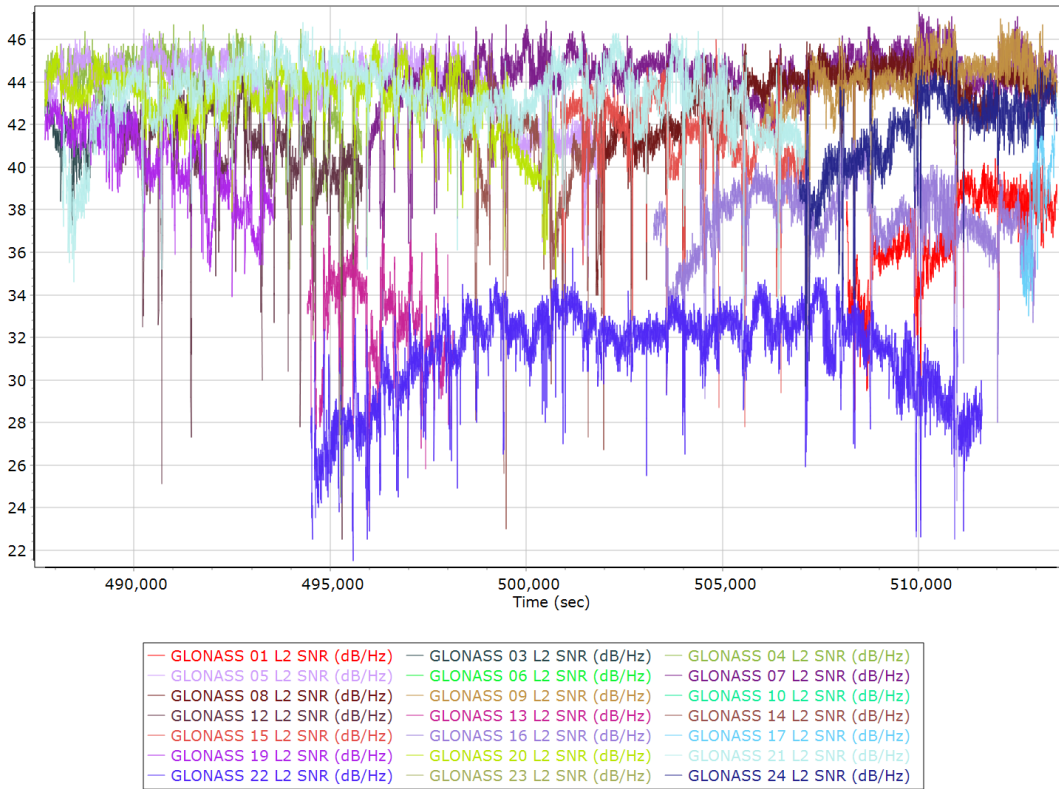
GPS/GLONASS L2 Satellite Lock/Elevation



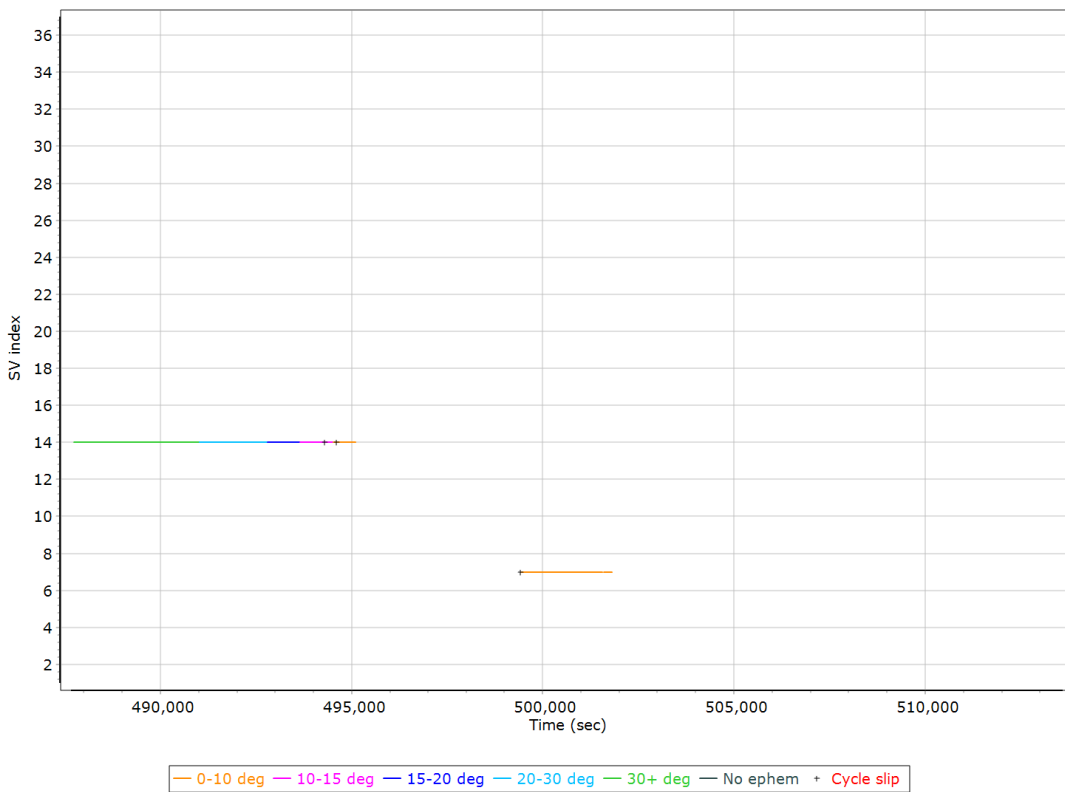
GPS L2 SNR



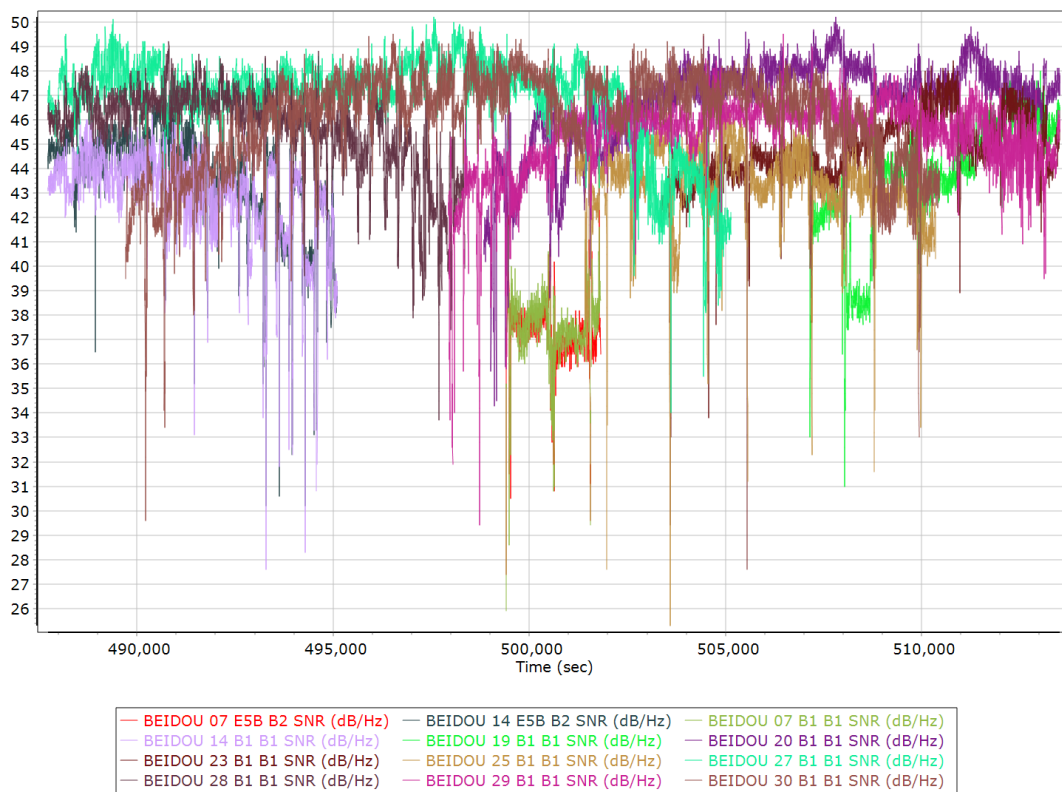
GLONASS L2 SNR



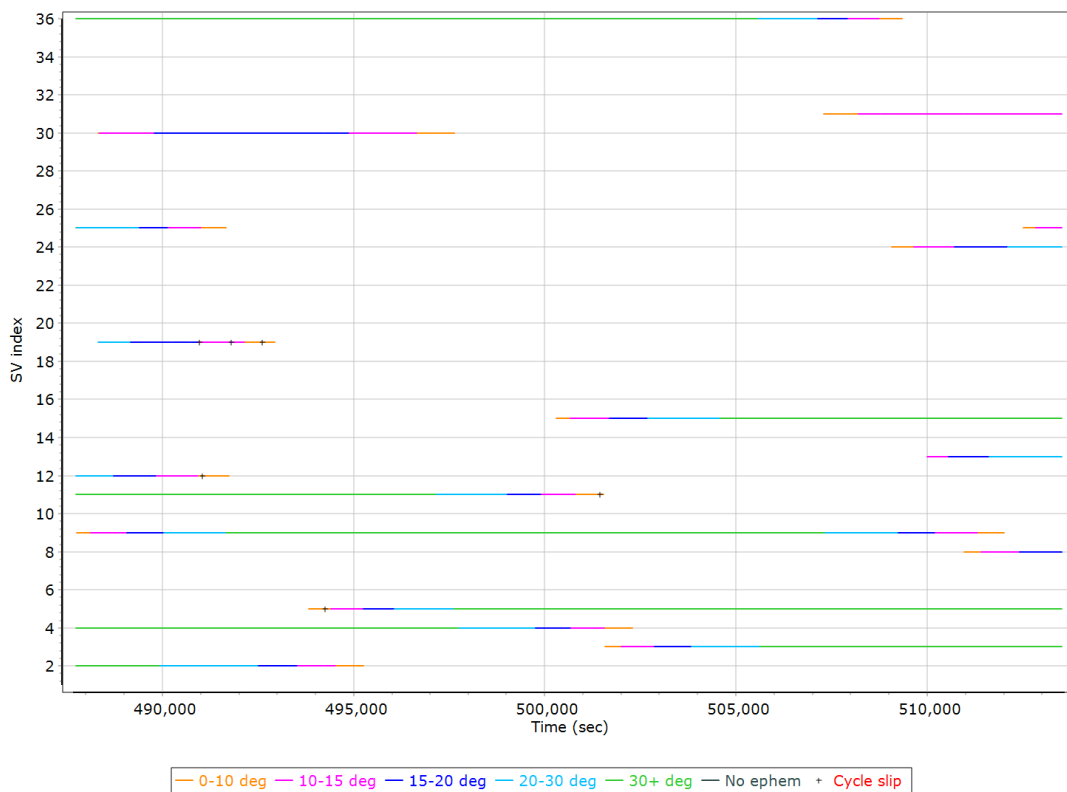
BEIDOU Satellite Lock/Elevation



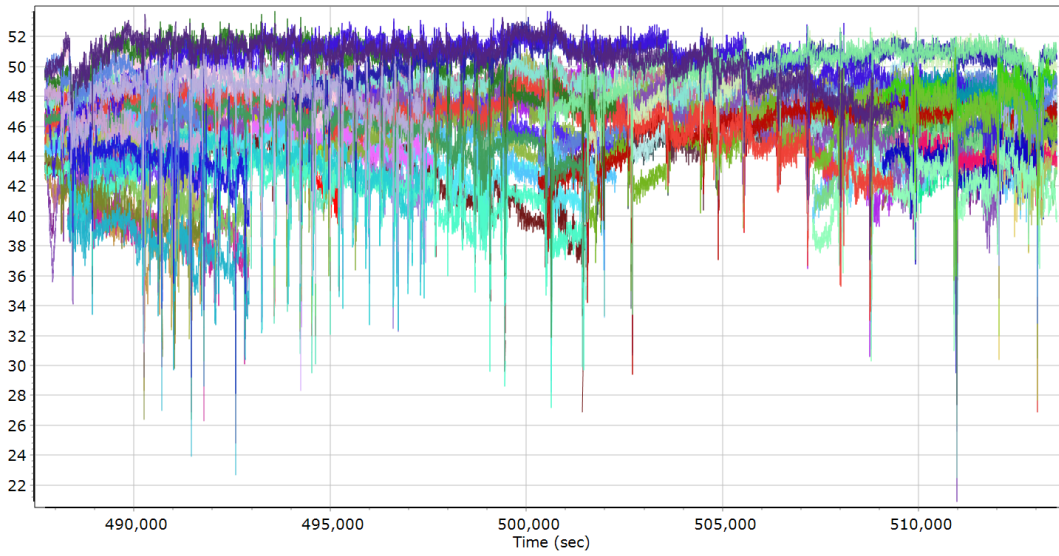
BEIDOU SNR



GALILEO Satellite Lock/Elevation



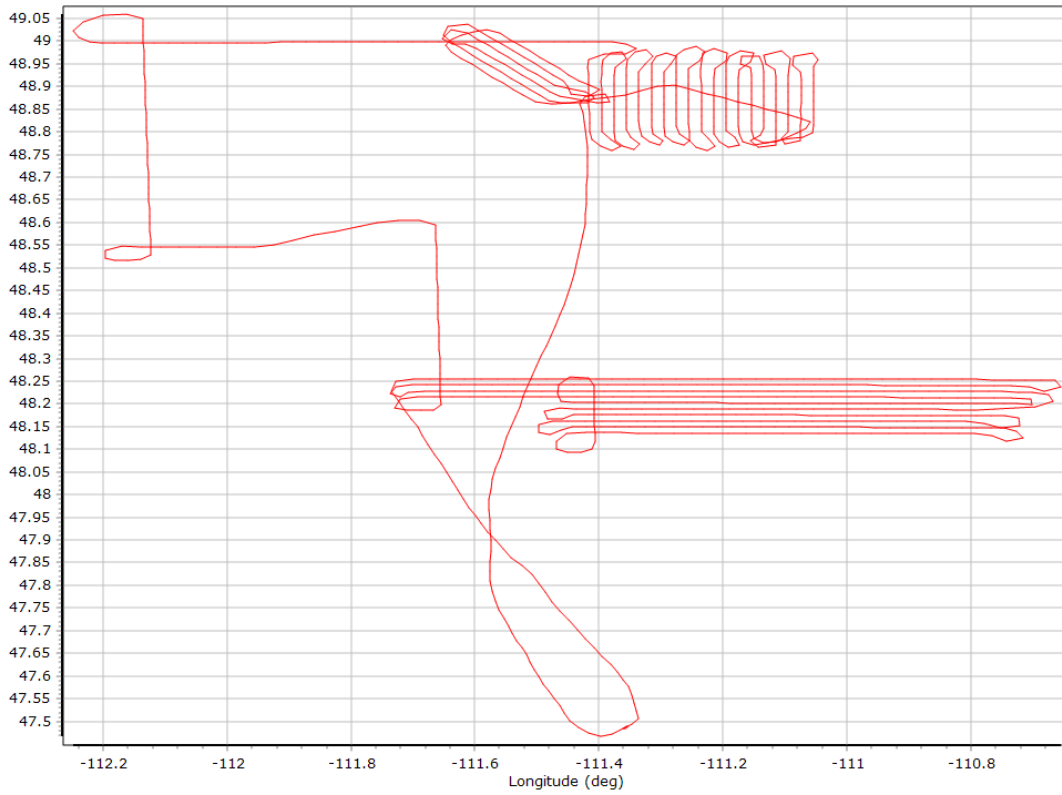
GALILEO SNR



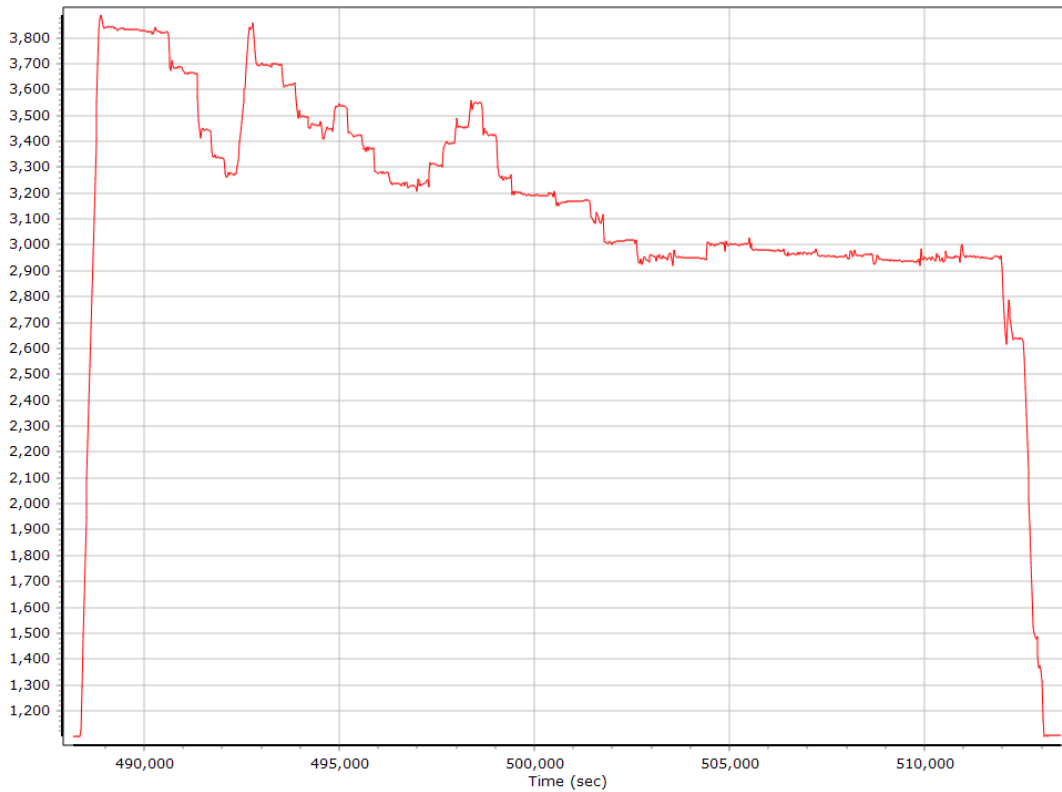
— GALILEO 02 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 03 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 04 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 05 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 08 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 09 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 11 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 12 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 13 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 15 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 19 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 24 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 25 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 30 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 31 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 36 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 02 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 03 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 04 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 05 L5E5A BPSK10_PD SNR (dB/Hz)

Smoothed Trajectory Information

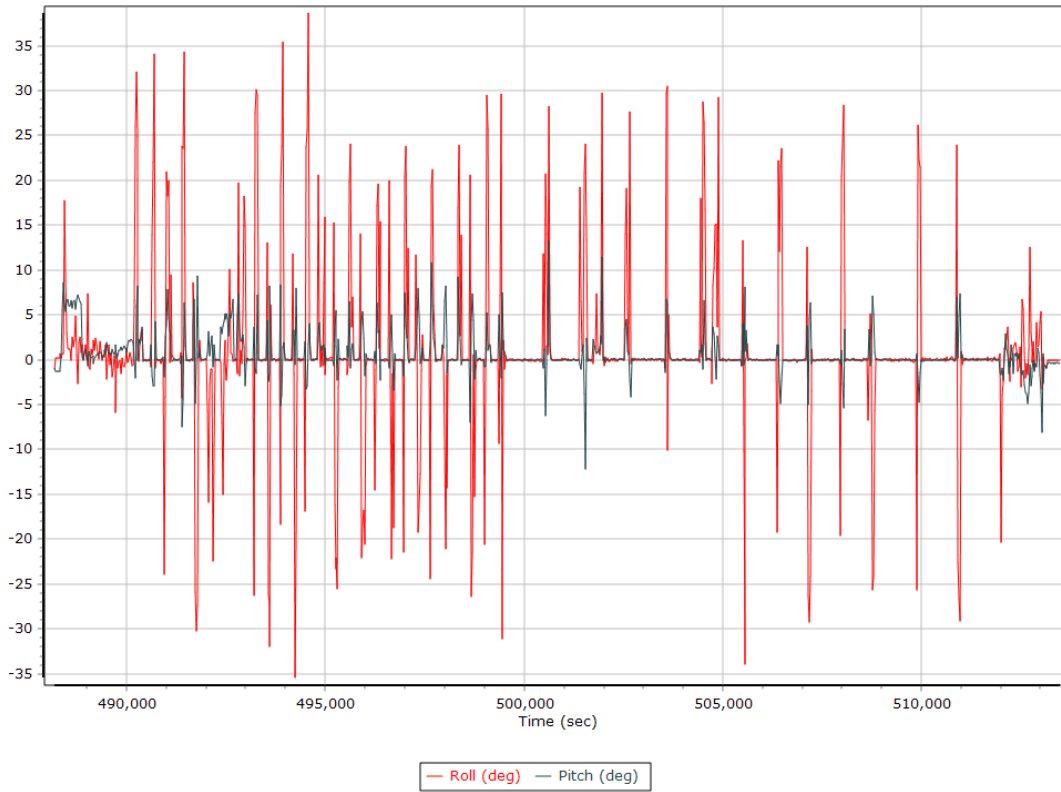
Top View



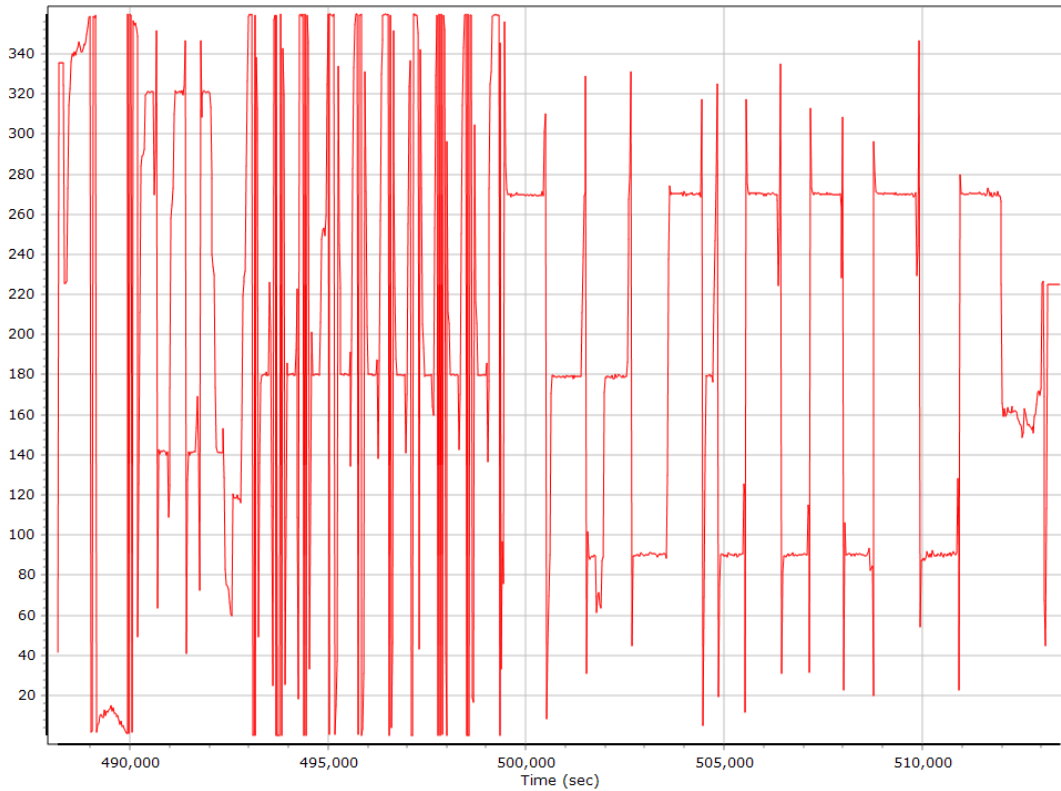
Altitude



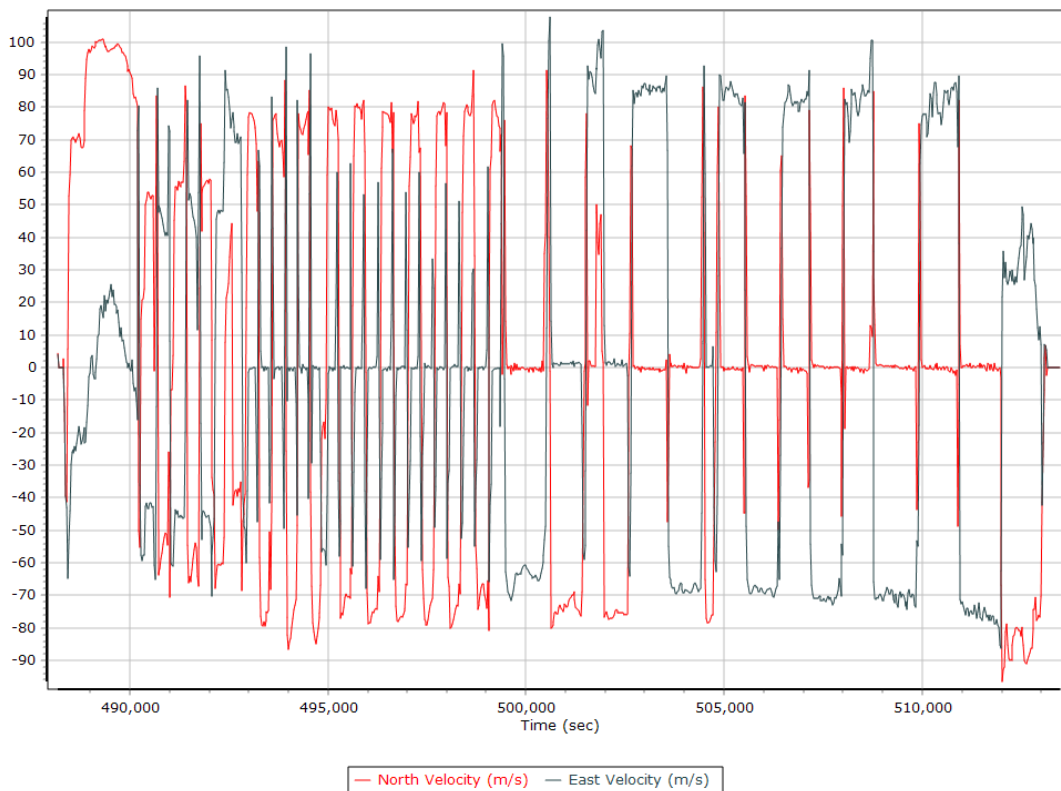
Roll/Pitch



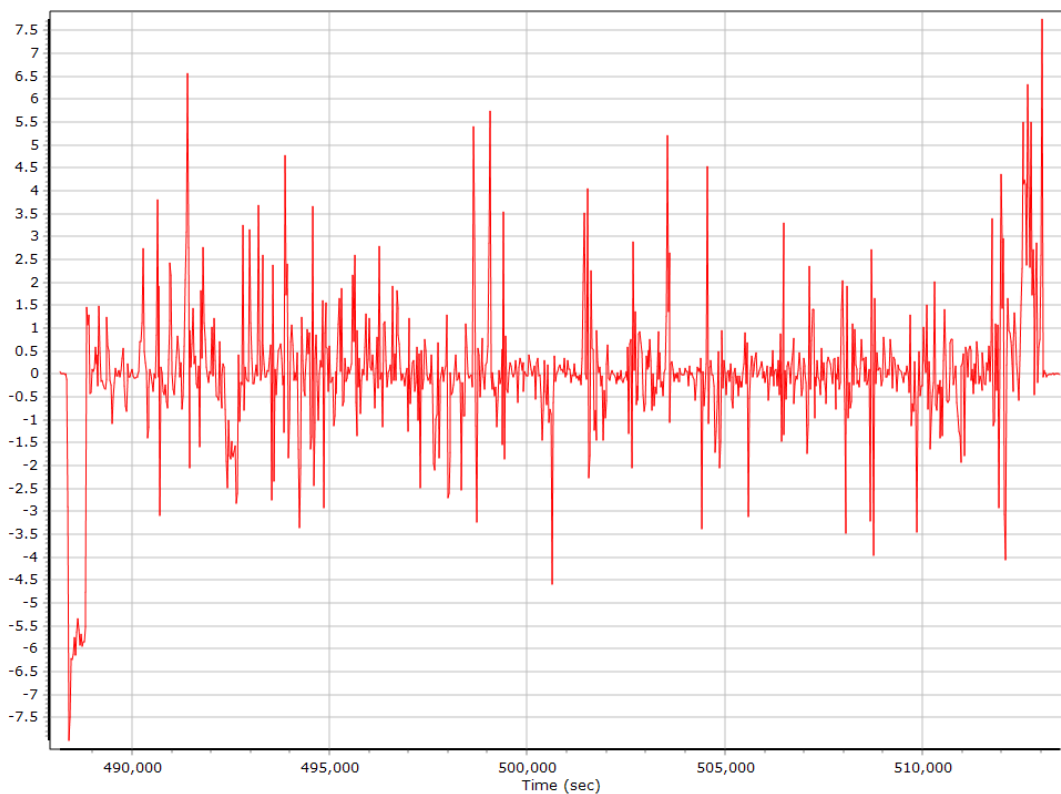
Heading



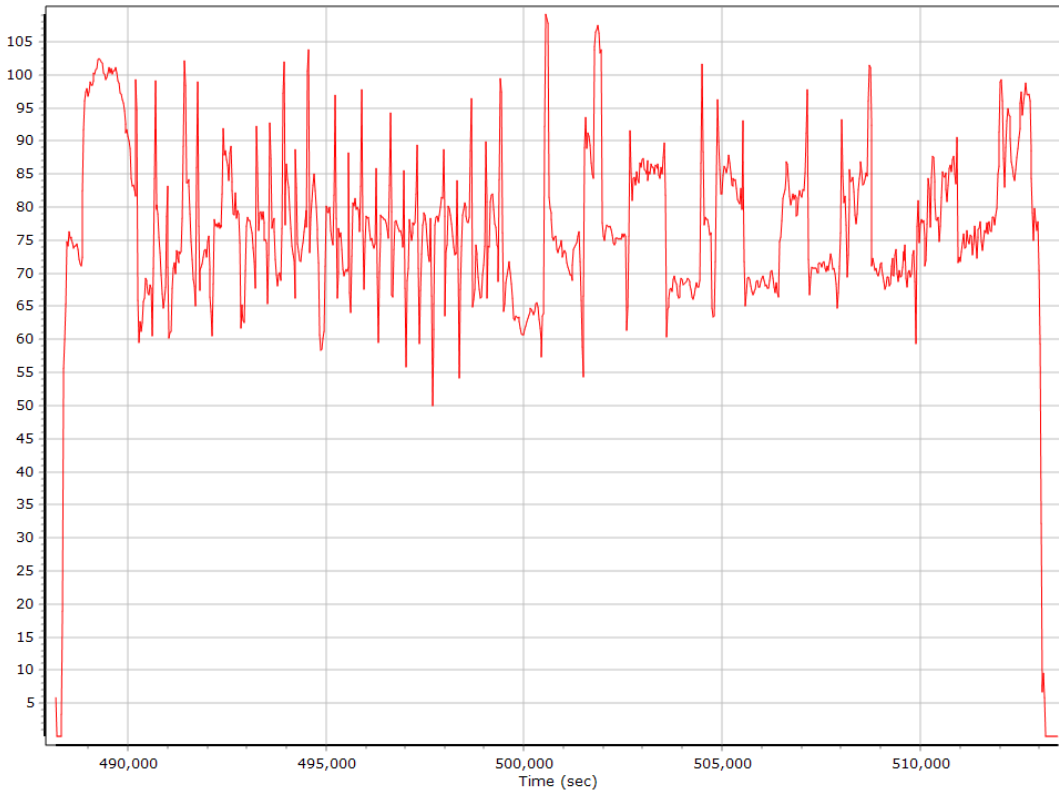
North/East Velocity



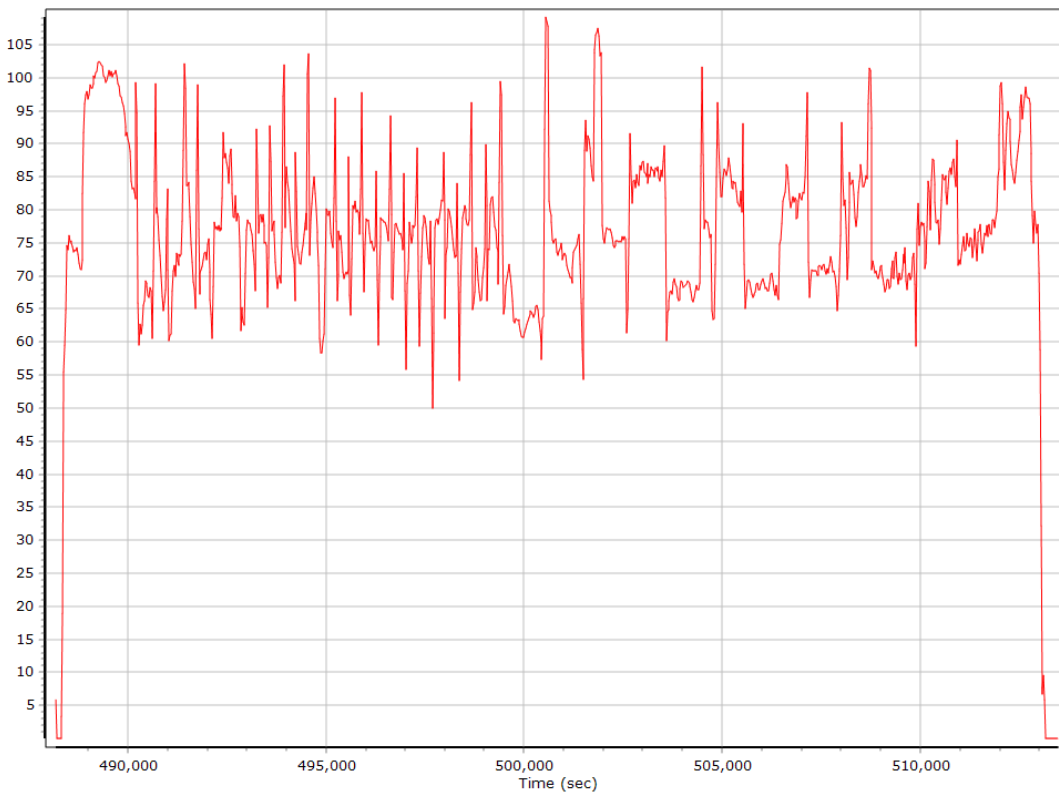
Down Velocity



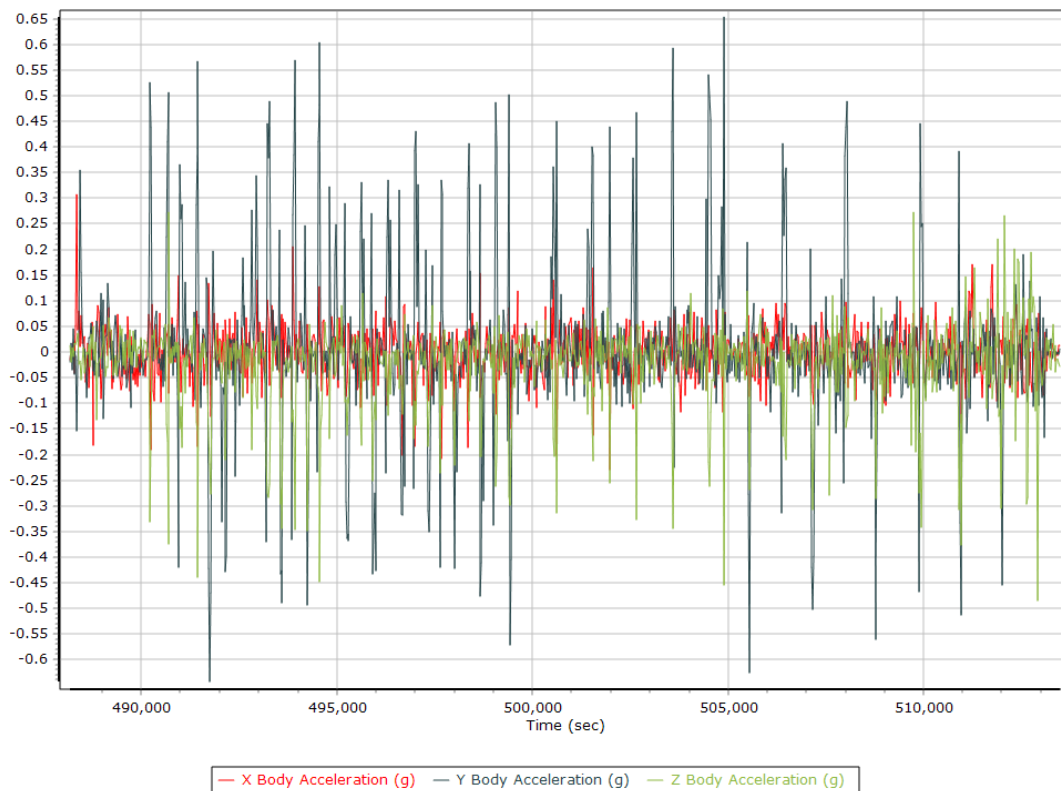
Total Speed



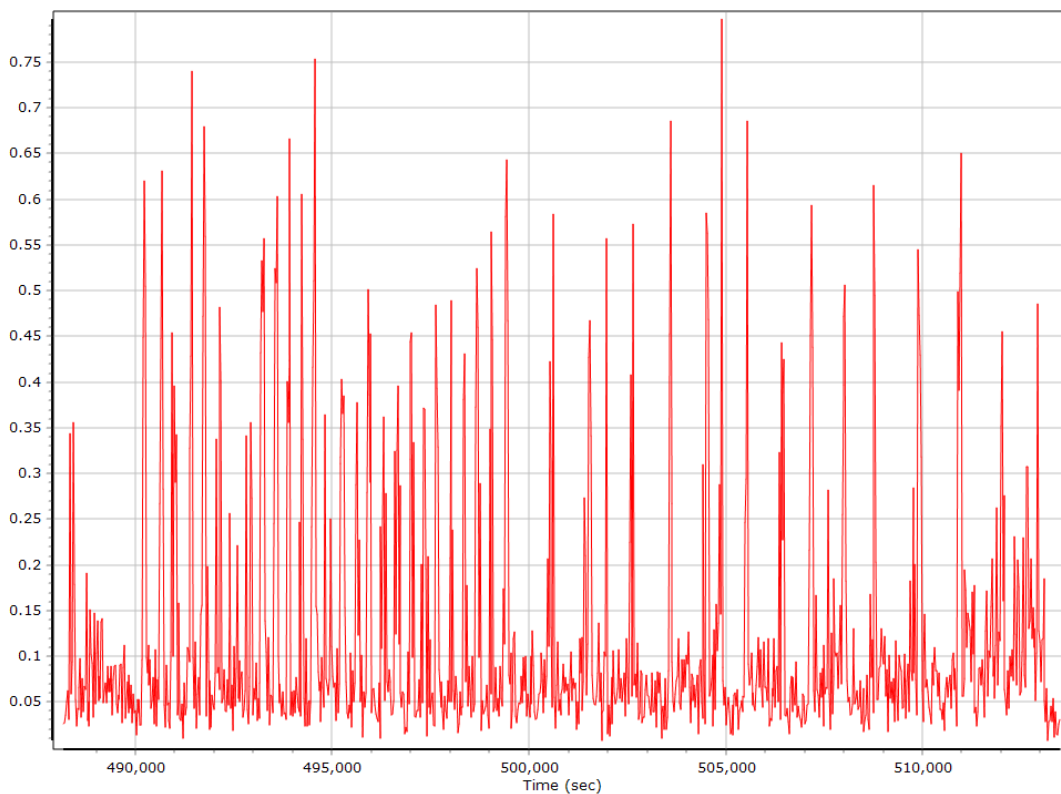
Ground Speed



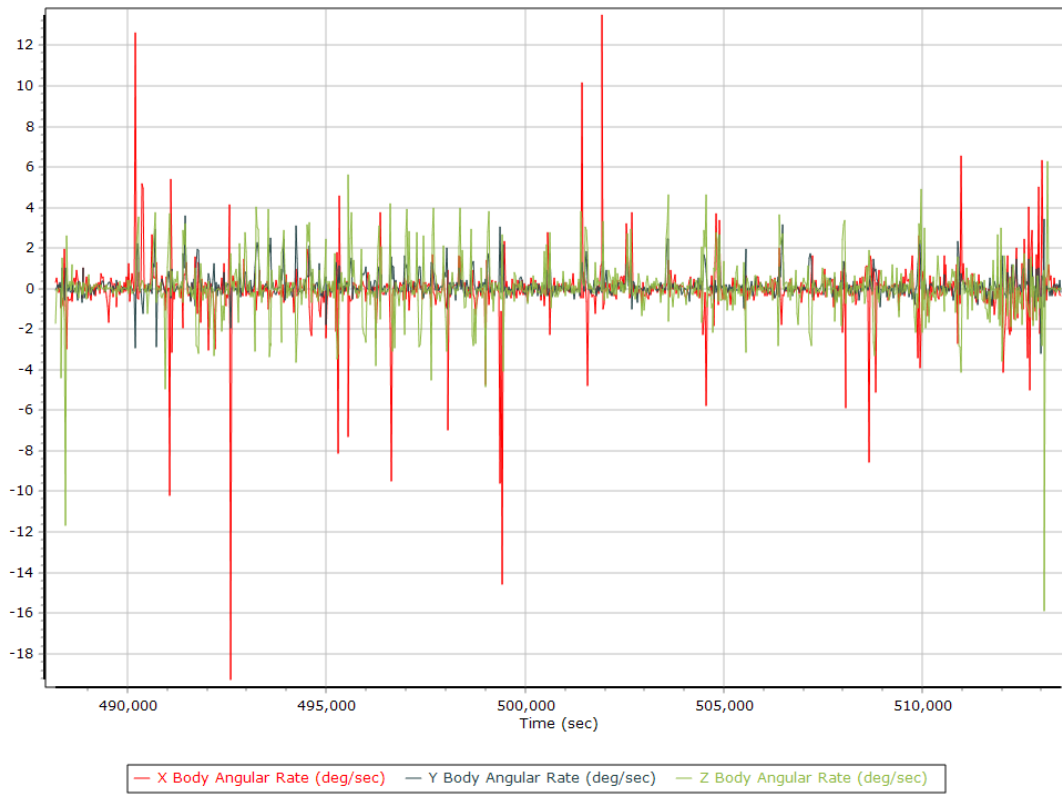
Body Acceleration



Total Body Acceleration

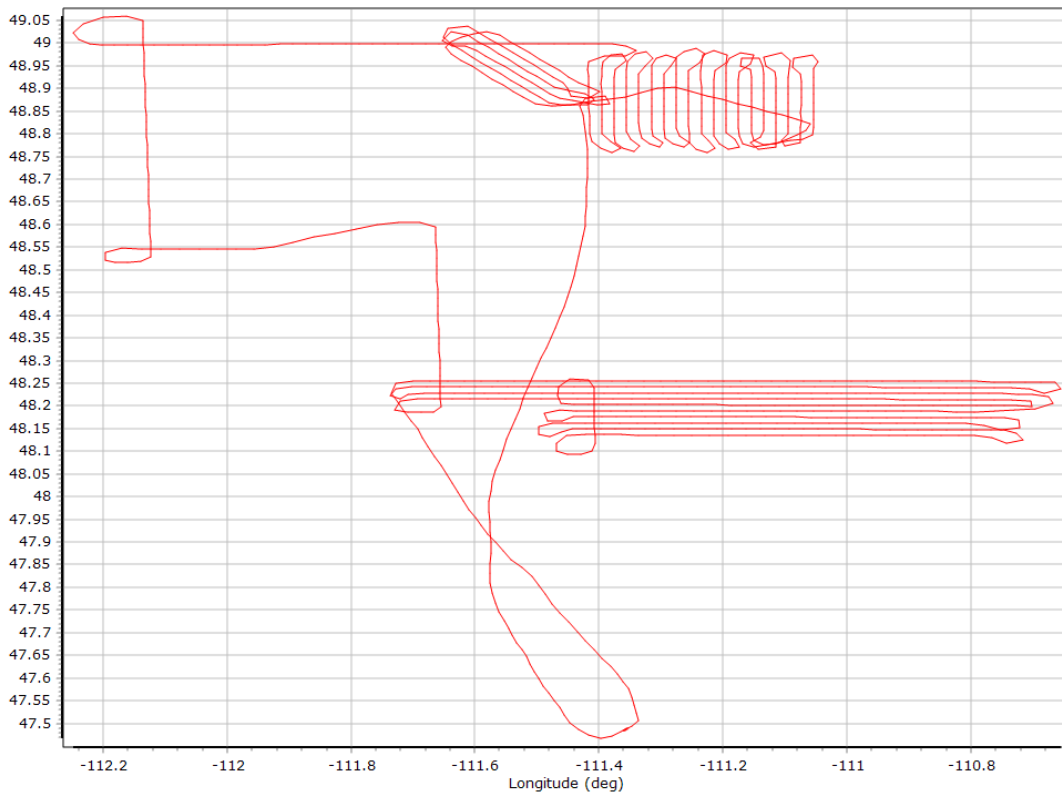


Body Angular Rate

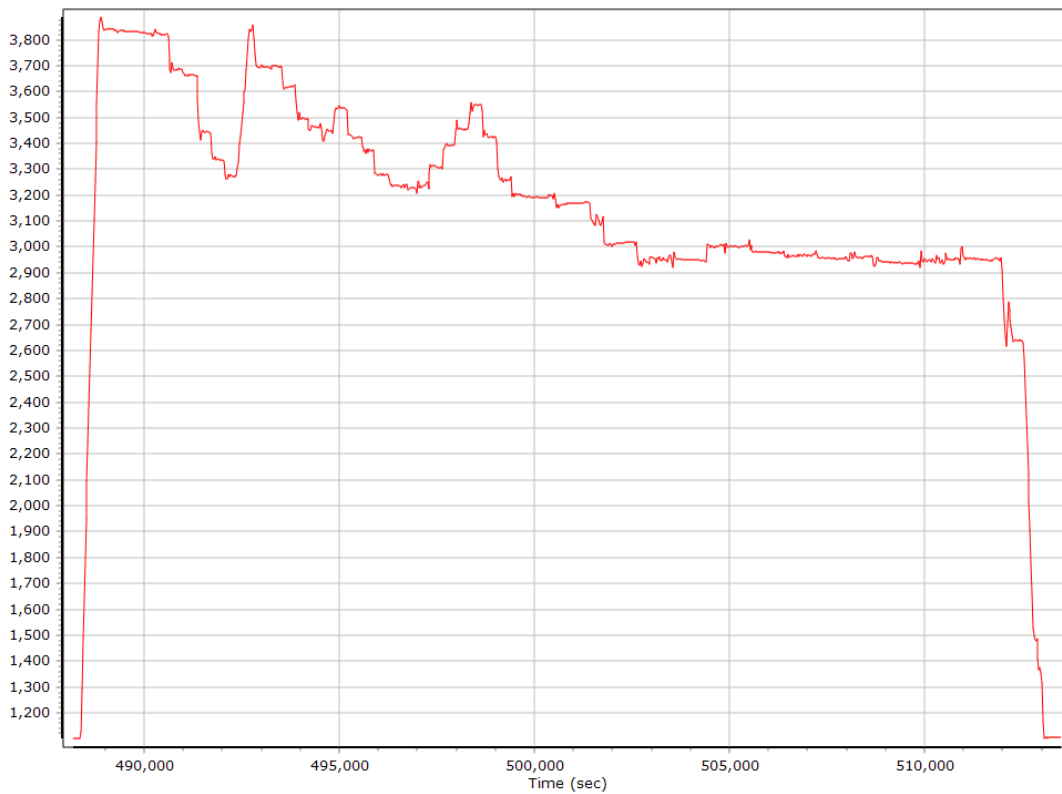


Forward Processed Trajectory Information

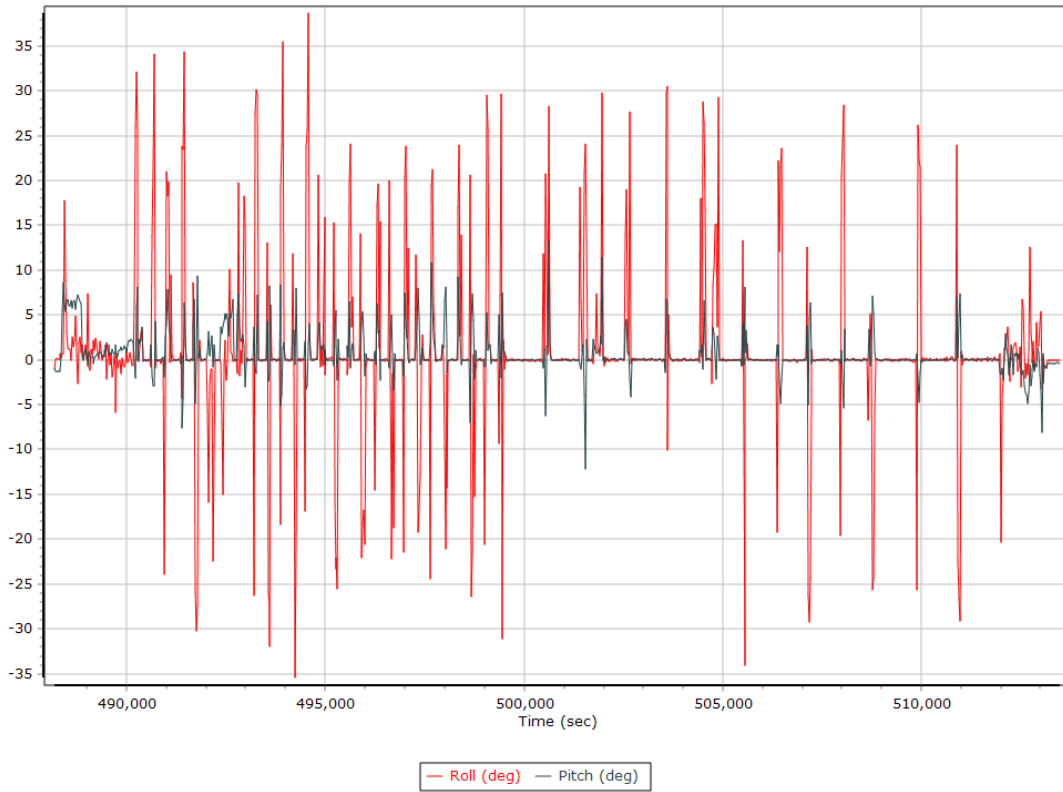
Top View



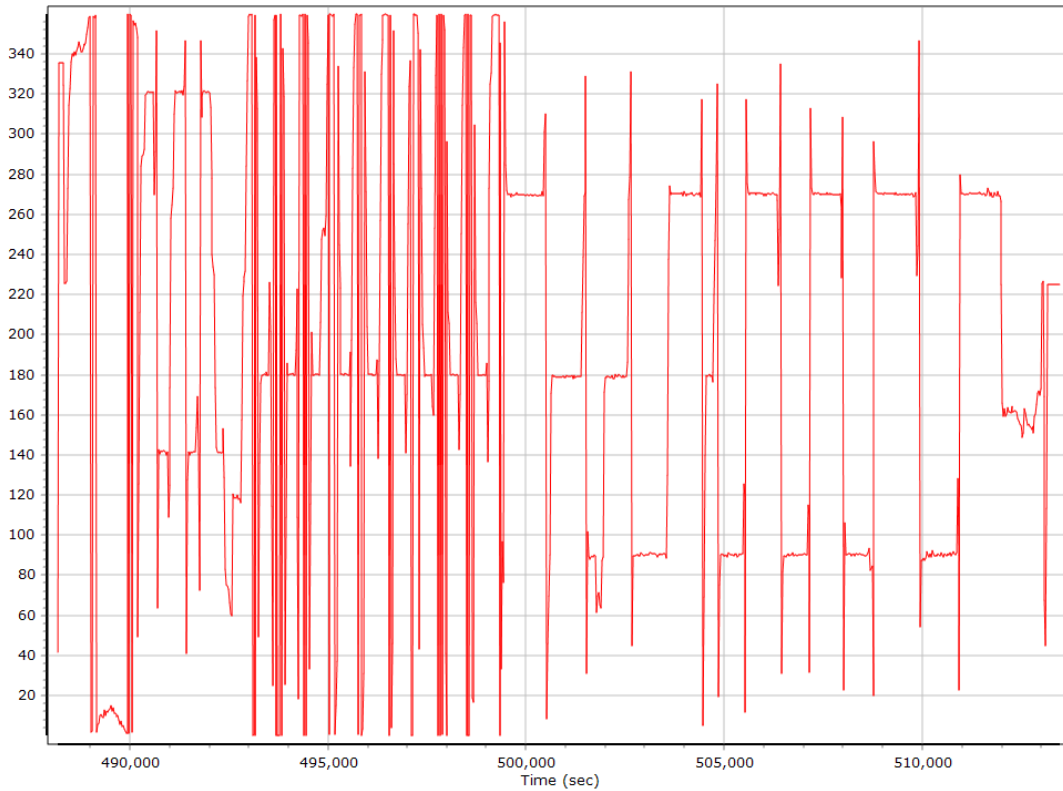
Altitude



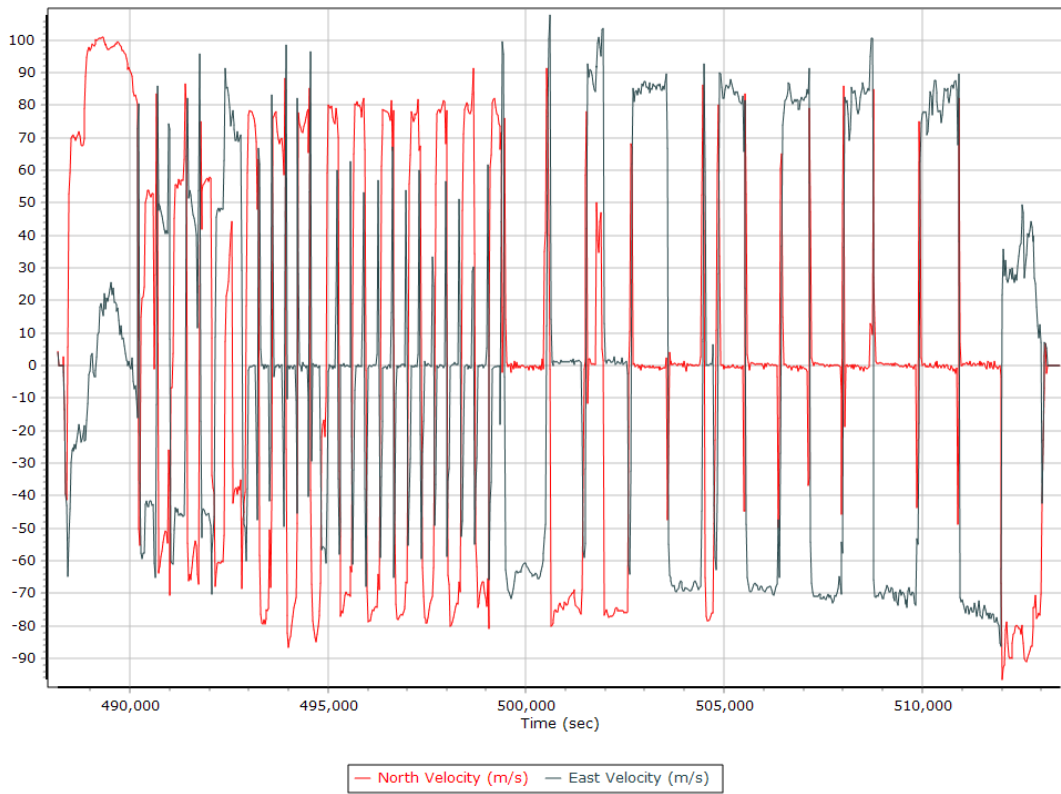
Roll/Pitch



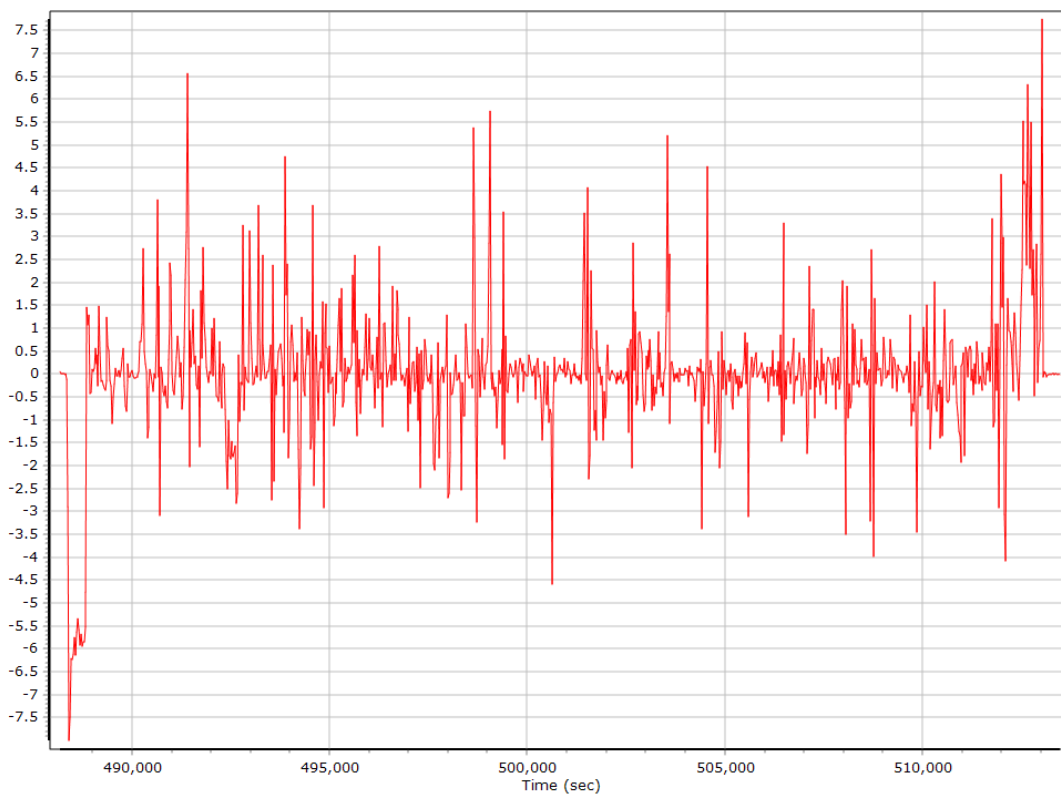
Heading



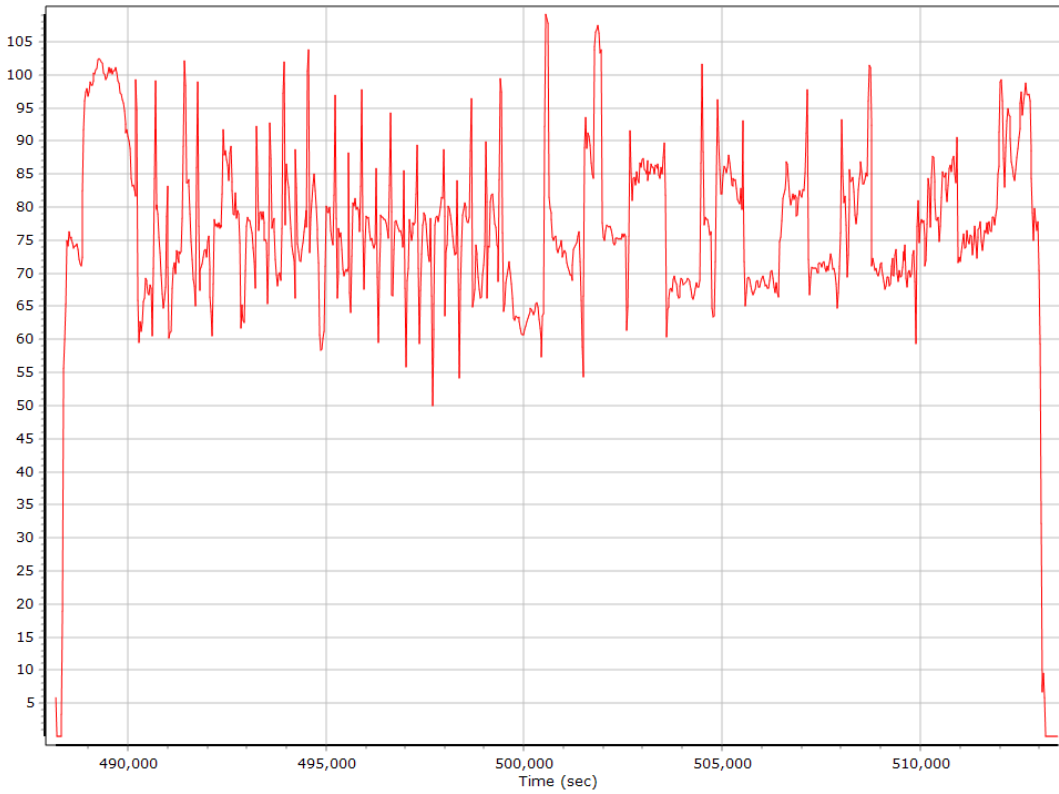
North/East Velocity



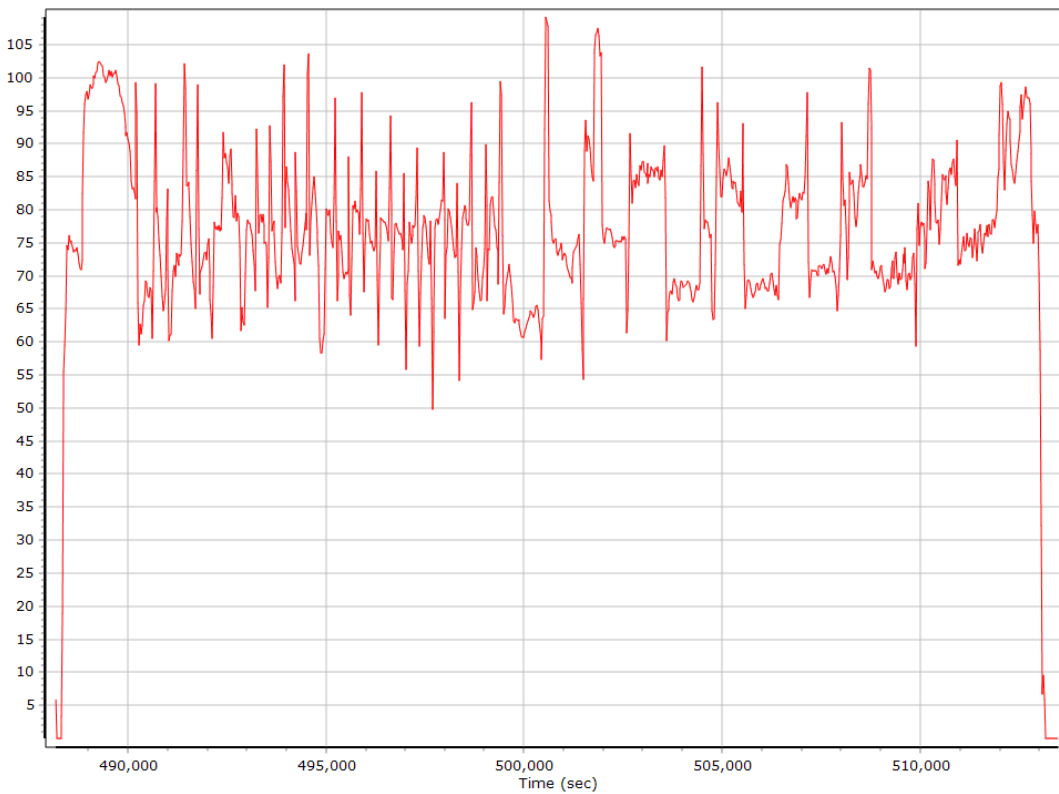
Down Velocity



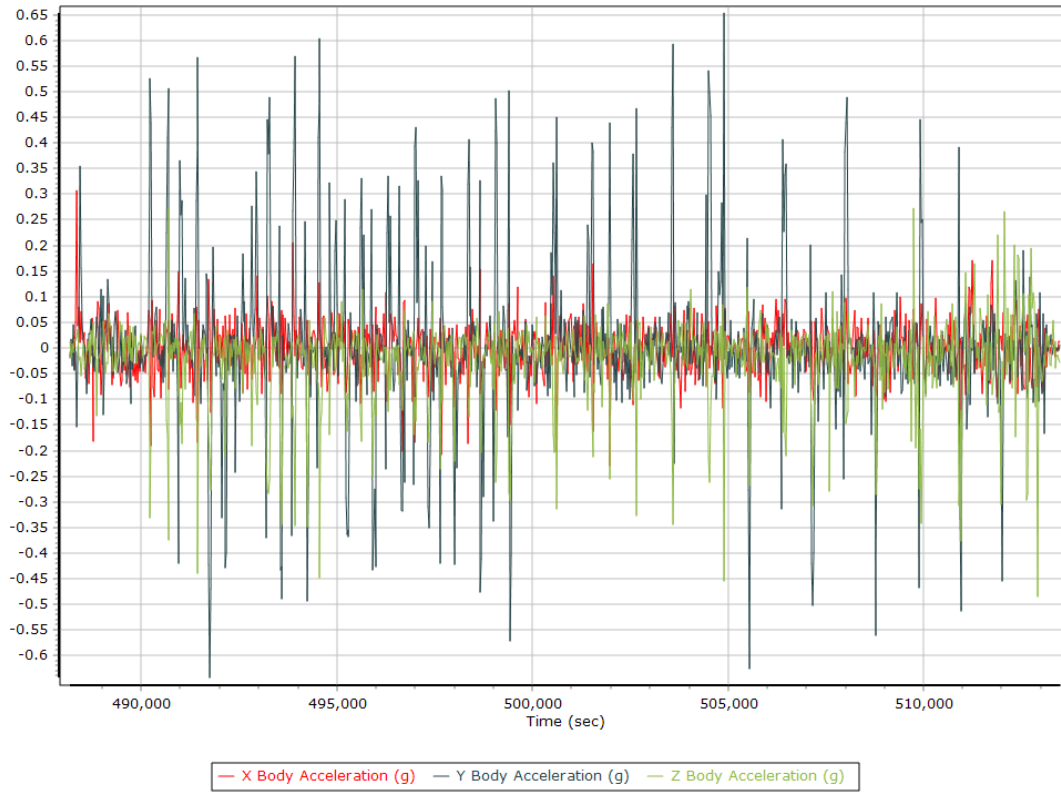
Total Speed



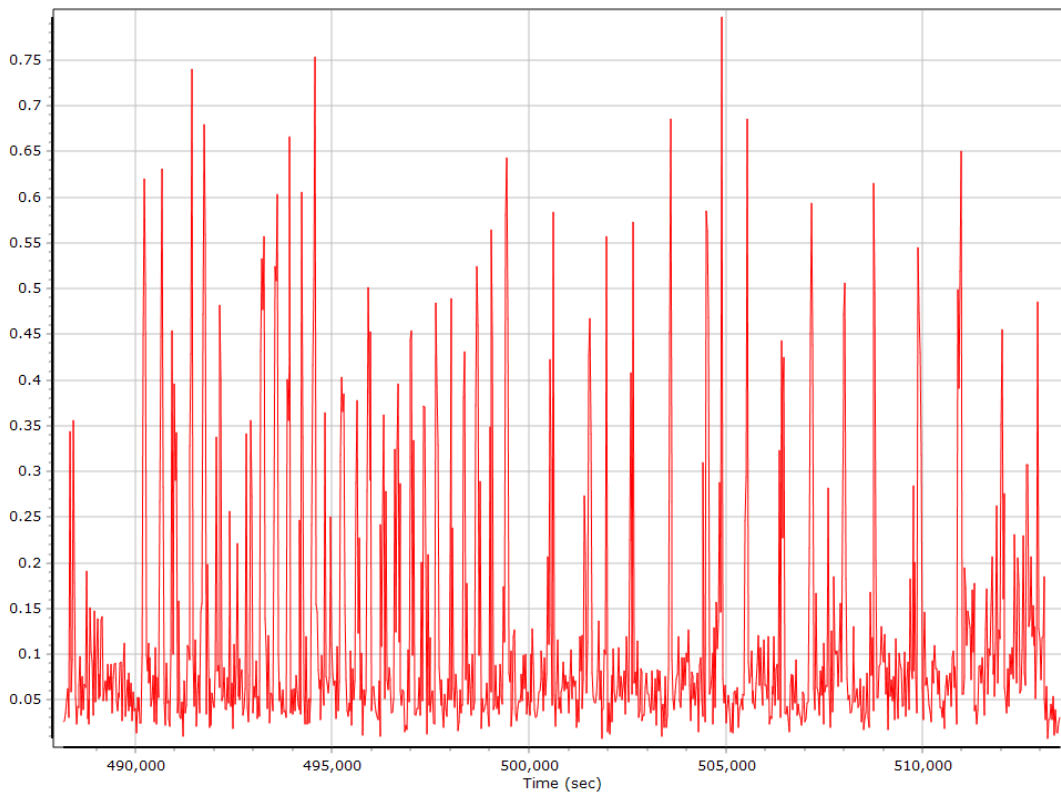
Ground Speed



Body Acceleration



Total Body Acceleration



Body Angular Rate



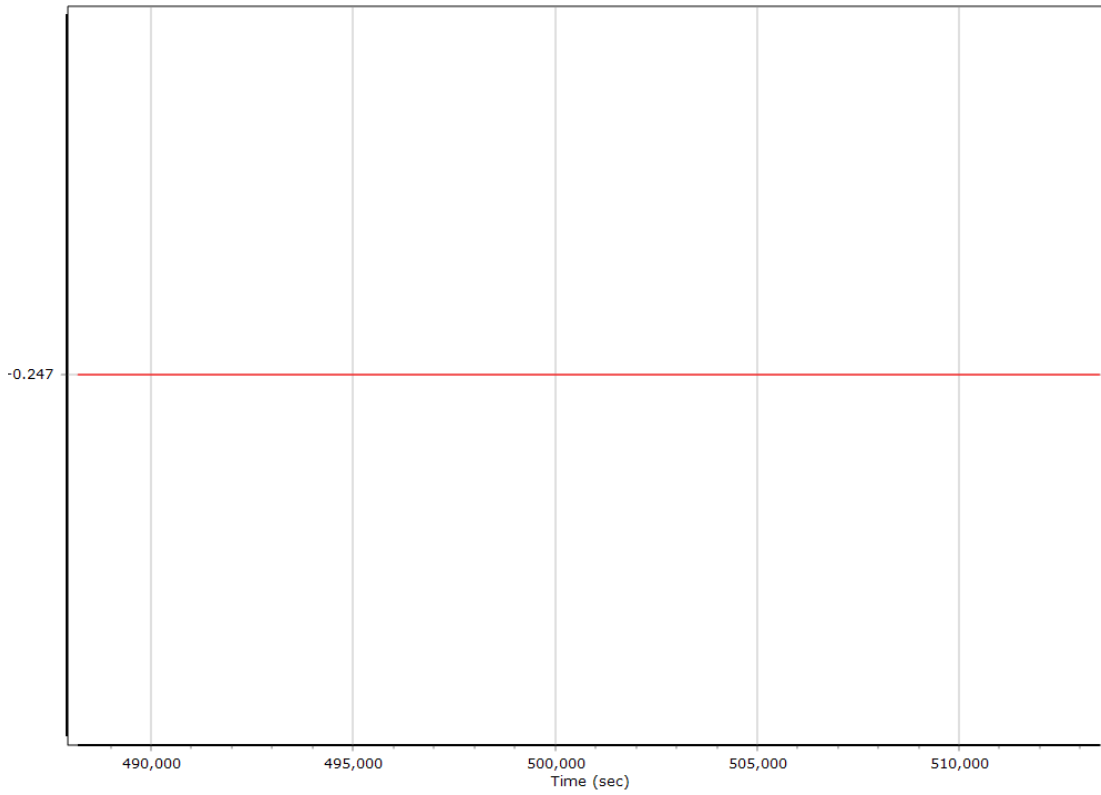
GNSS-Inertial Processor Configuration

Processing mode	IN-Fusion Trimble RTX Nav		
Stabilized mount	True		
Processing start time	487723.000 (09/17/2021 15:28:43)		
Processing end time	513501.000 (09/17/2021 22:38:21)		
Initial attitude source	Real-Time VNAV/RNAV Attitude		
IMU Sensor Context	Processing with Onboard IMU		
Gimbal to IMU lever arm (m)	-0.034	-0.010	-0.374
Gimbal to IMU mounting angles (deg)	0.000	0.000	0.000
Gimbal to Primary GNSS lever arm (m)	-0.247	-0.020	-1.300
Gimbal to Primary GNSS lever arm std dev (m)	0.030	0.030	0.030
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

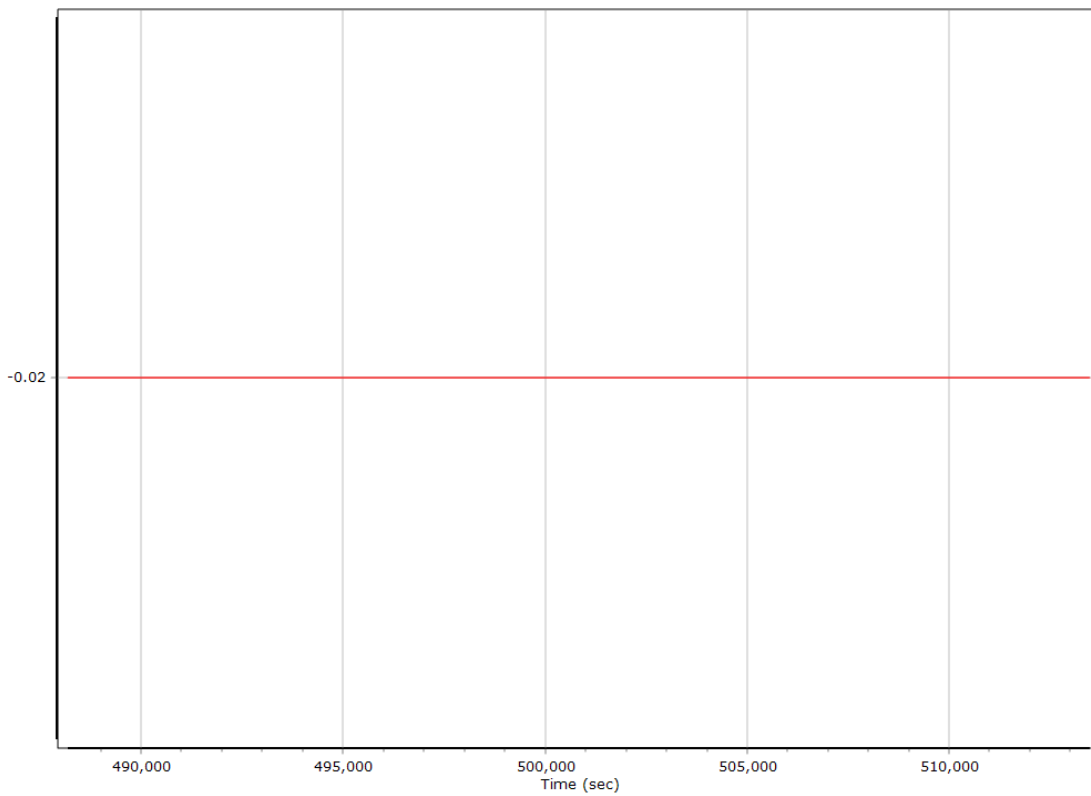
Calibrated Installation Parameters

Reference-Primary GNSS Lever Arm (m)

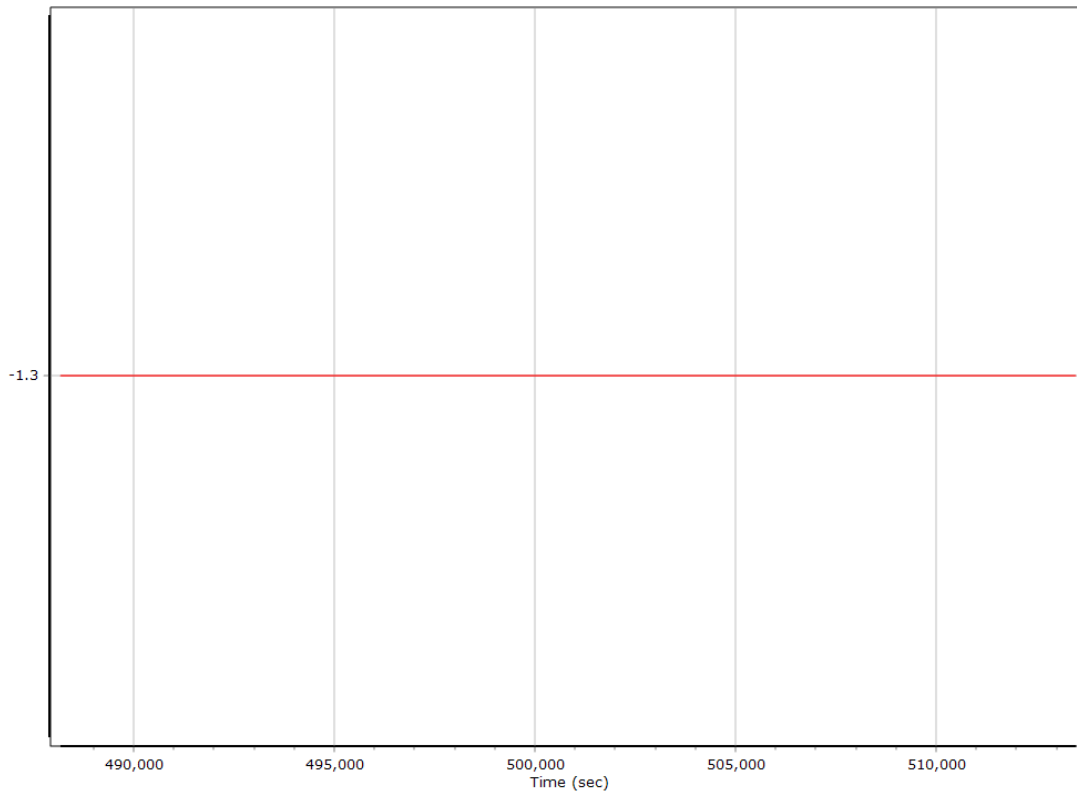
X Reference-Primary GNSS Lever Arm (m)



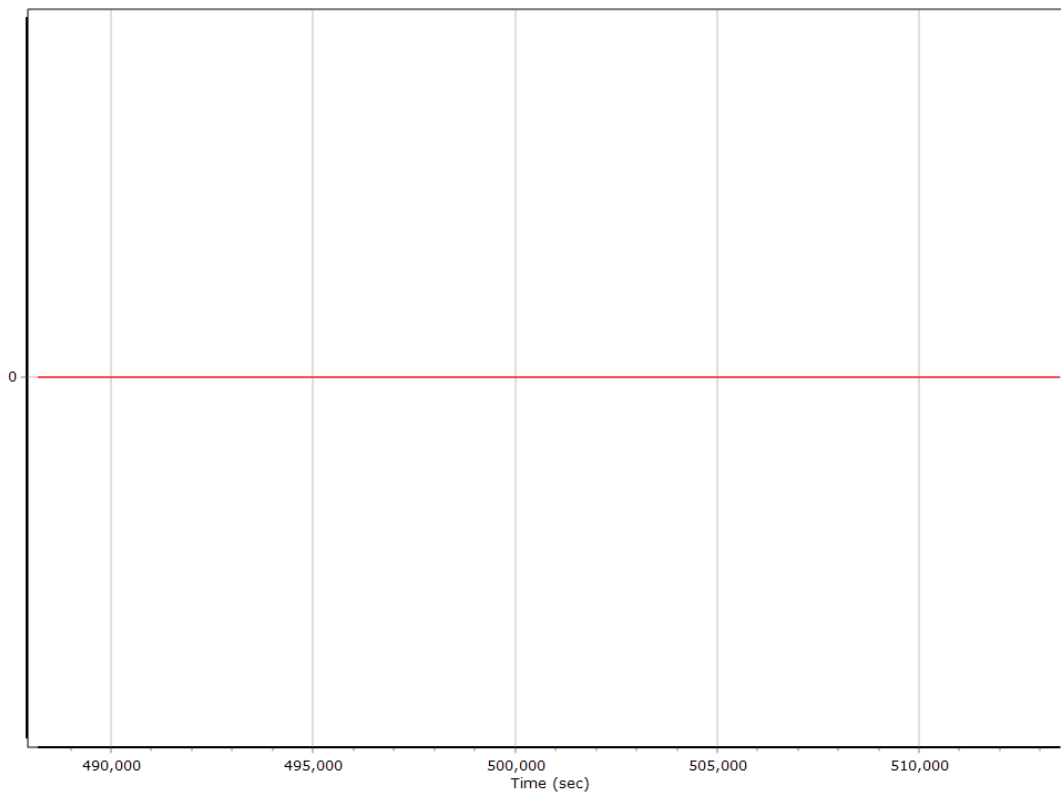
Y Reference-Primary GNSS Lever Arm (m)



Z Reference-Primary GNSS Lever Arm (m)



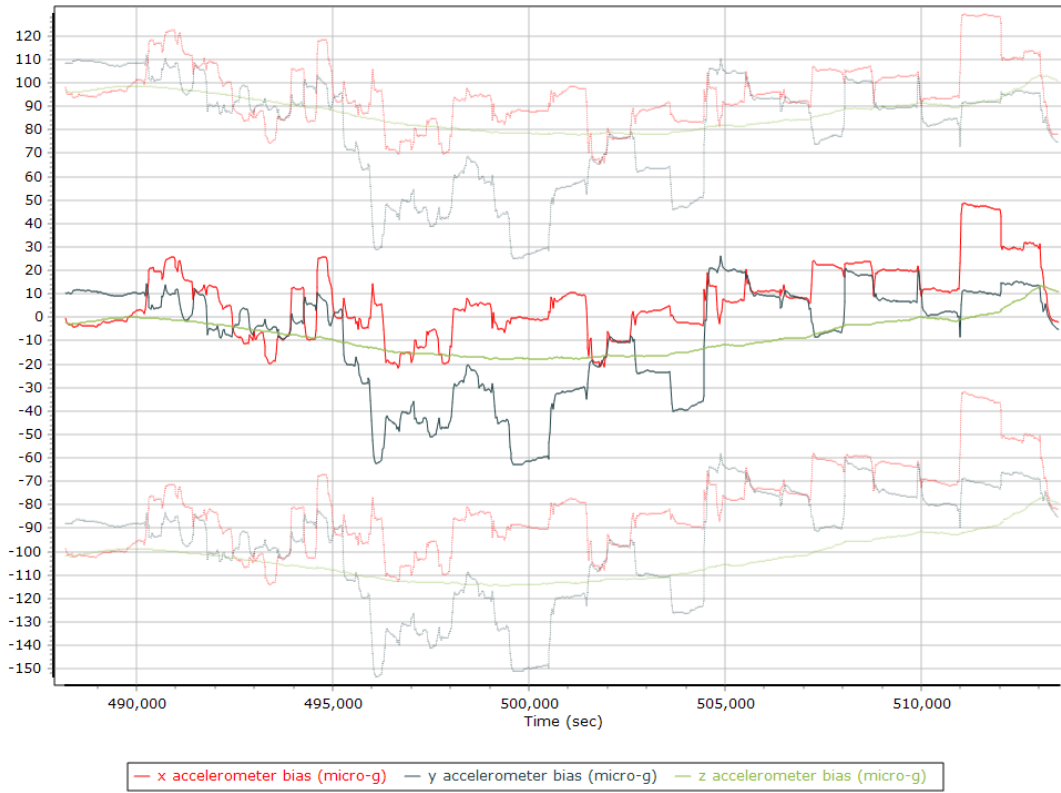
Reference-Primary GNSS Lever Arm Figure of Merit



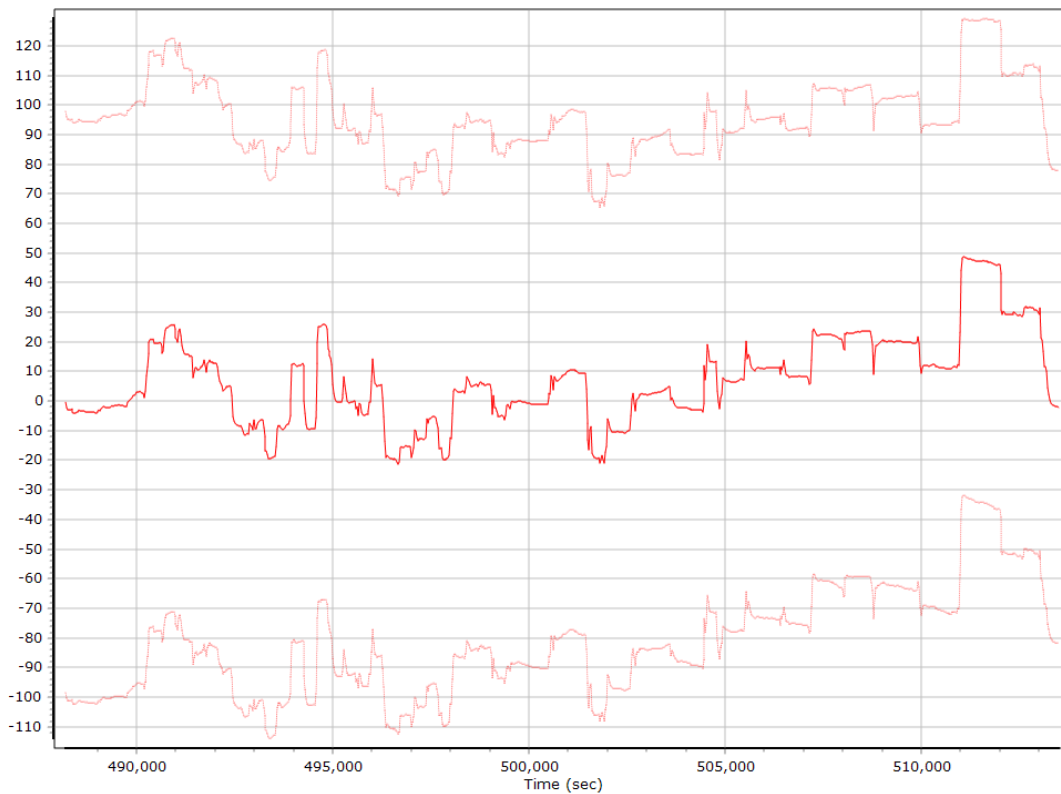
IN-Fusion QC

Forward Processed Estimated Errors, Reference Frame

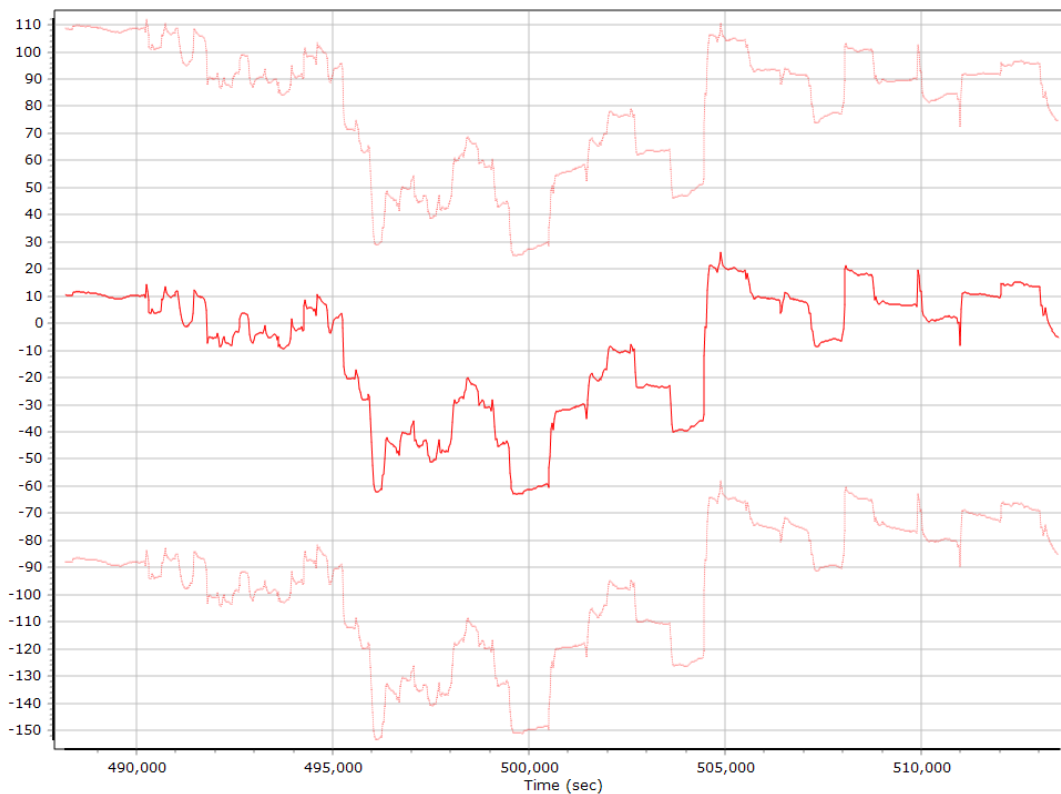
Accelerometer Bias (micro-g)



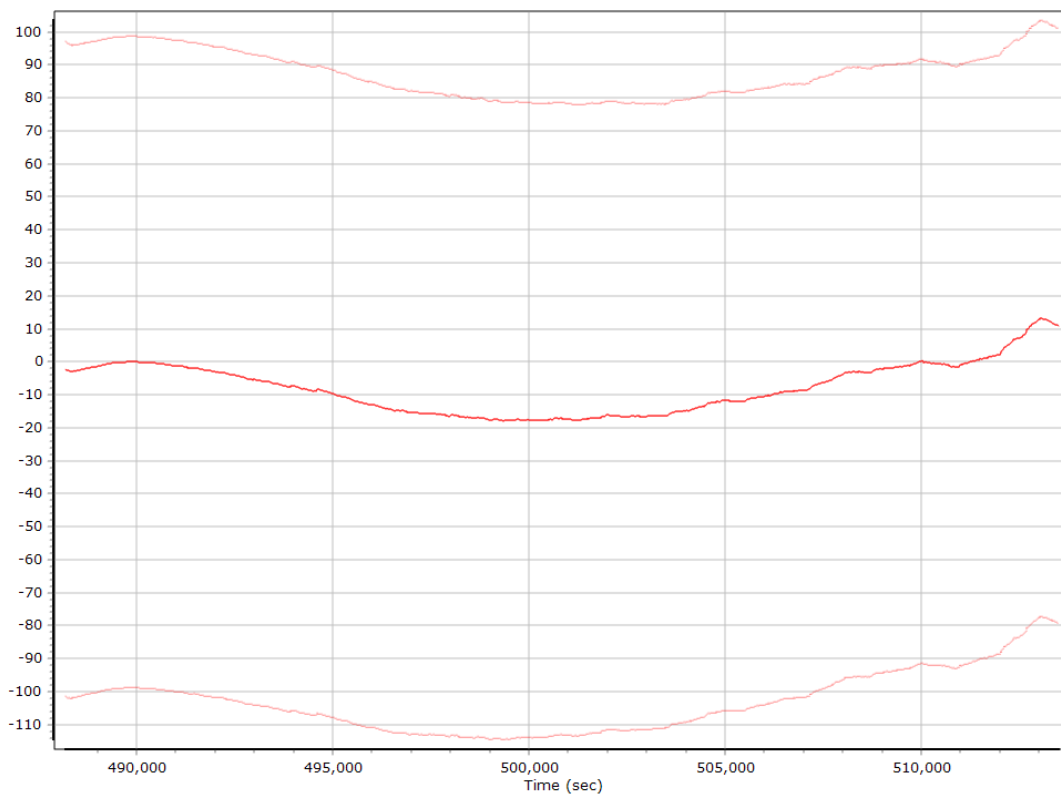
X Accelerometer Bias (micro-g)



Y Accelerometer Bias (micro-g)



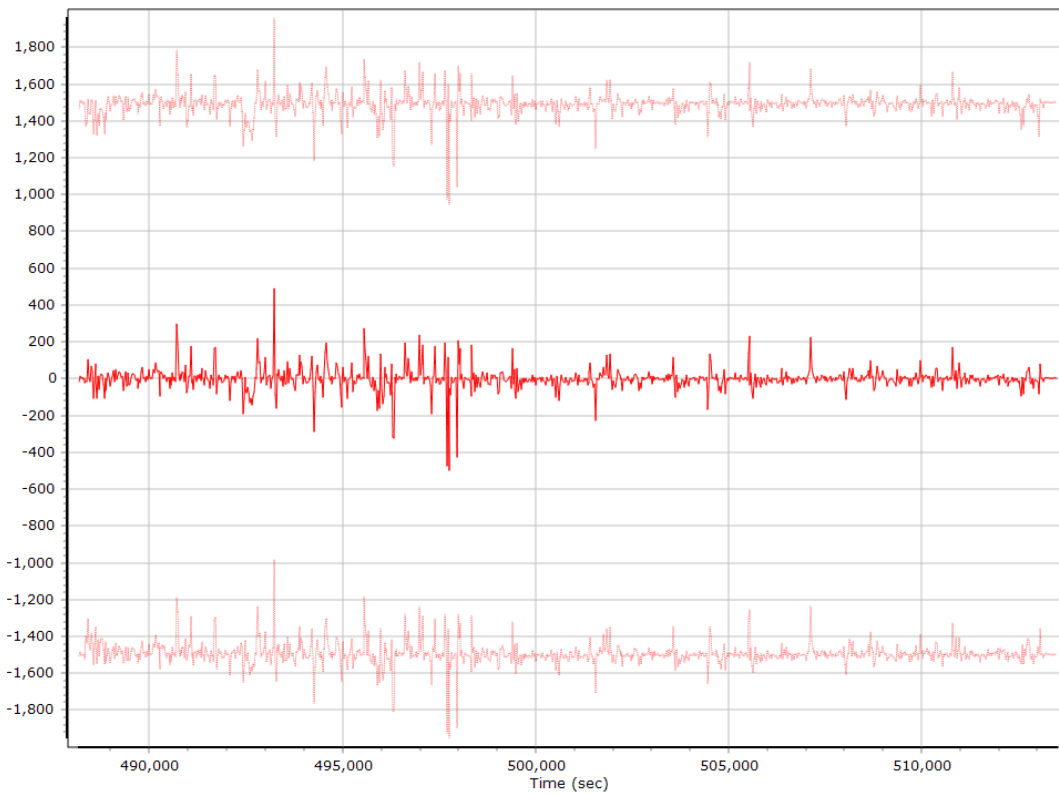
Z Accelerometer Bias (micro-g)



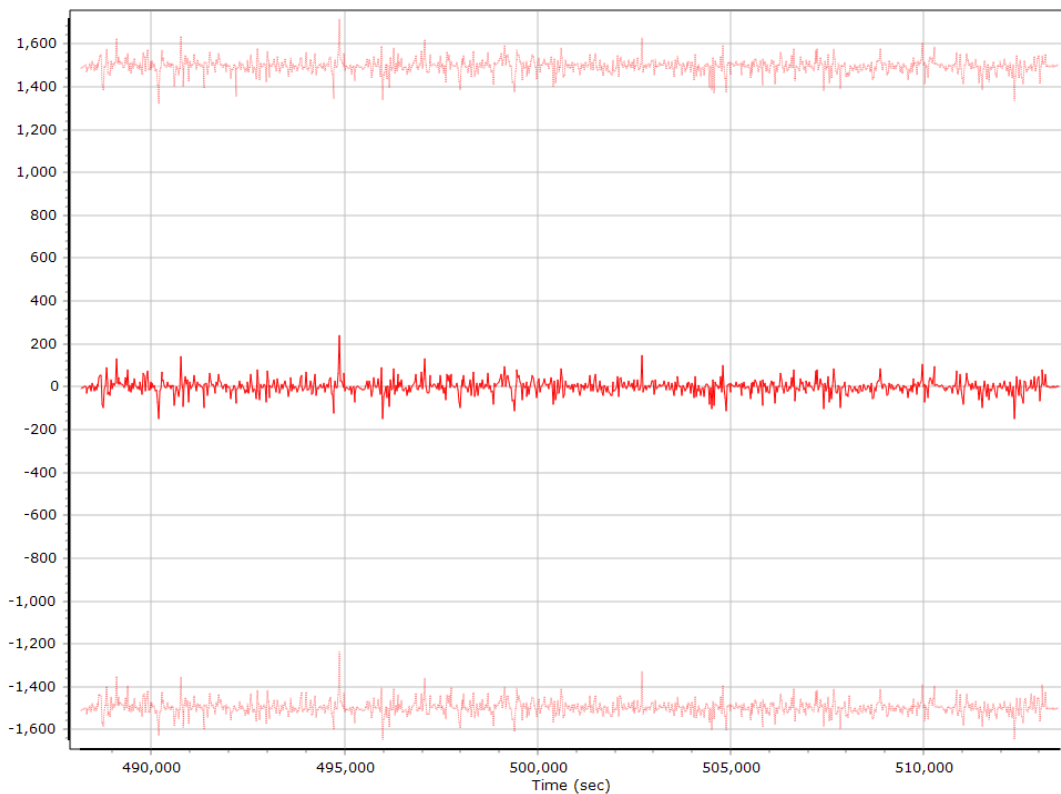
Accelerometer Scale Error (ppm)



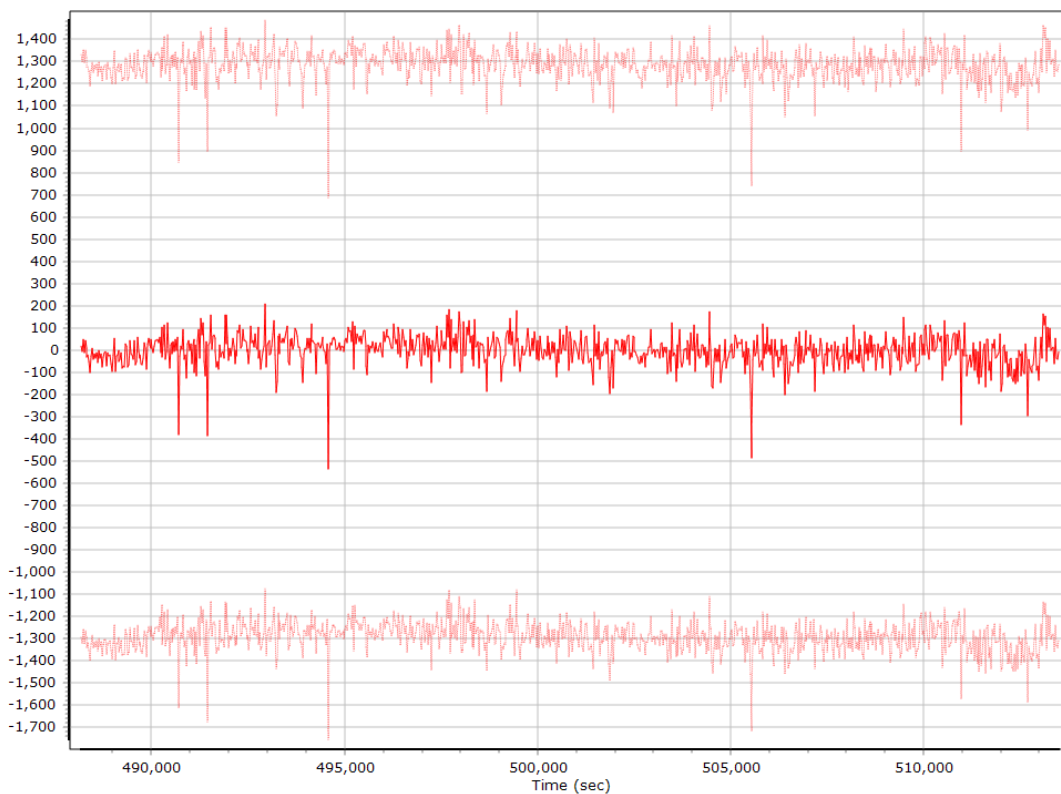
X Accelerometer Scale Error (ppm)



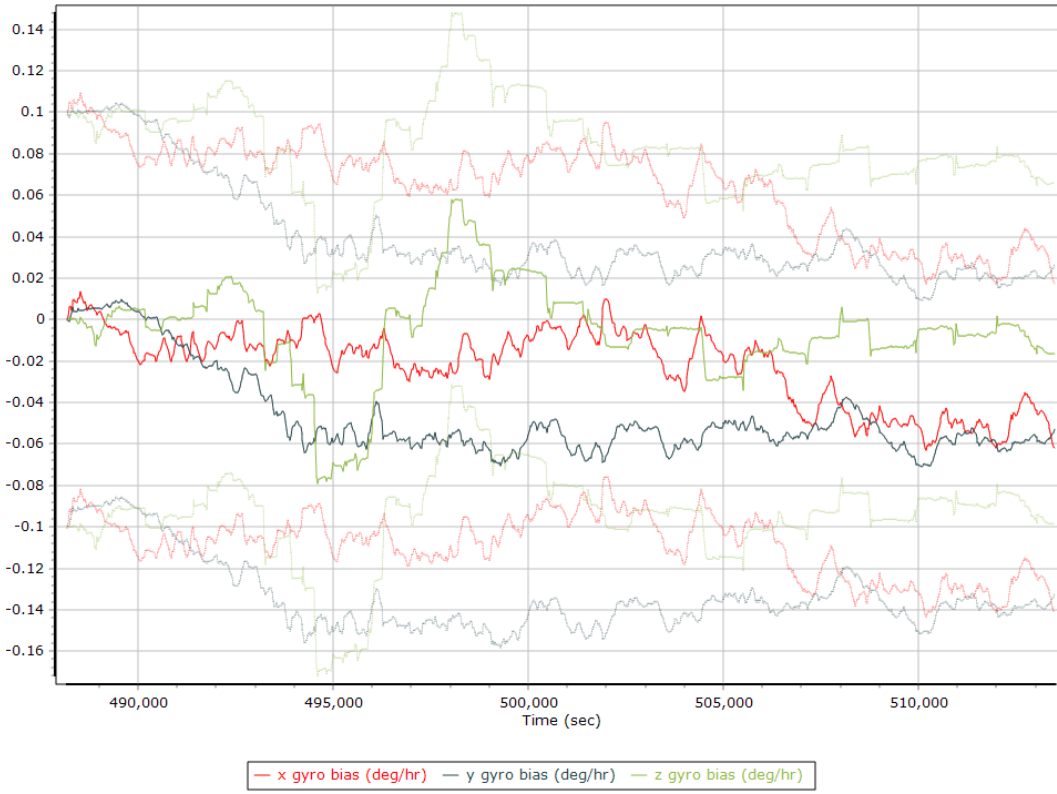
Y Accelerometer Scale Error (ppm)



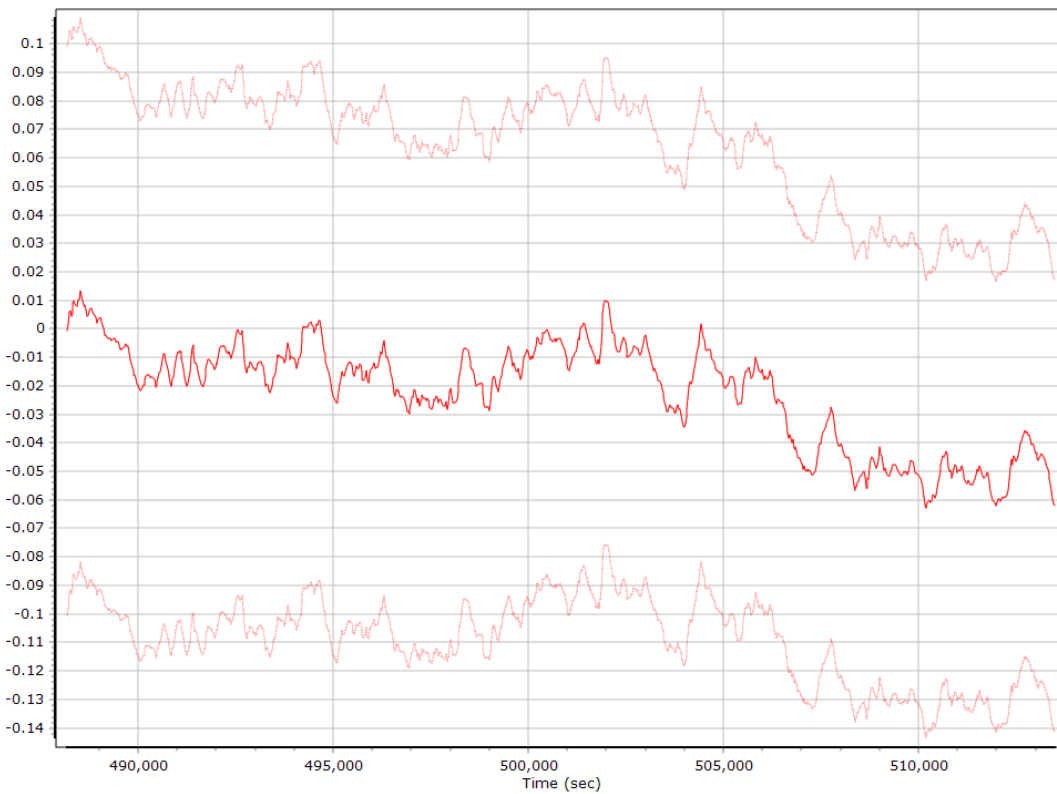
Z Accelerometer Scale Error (ppm)



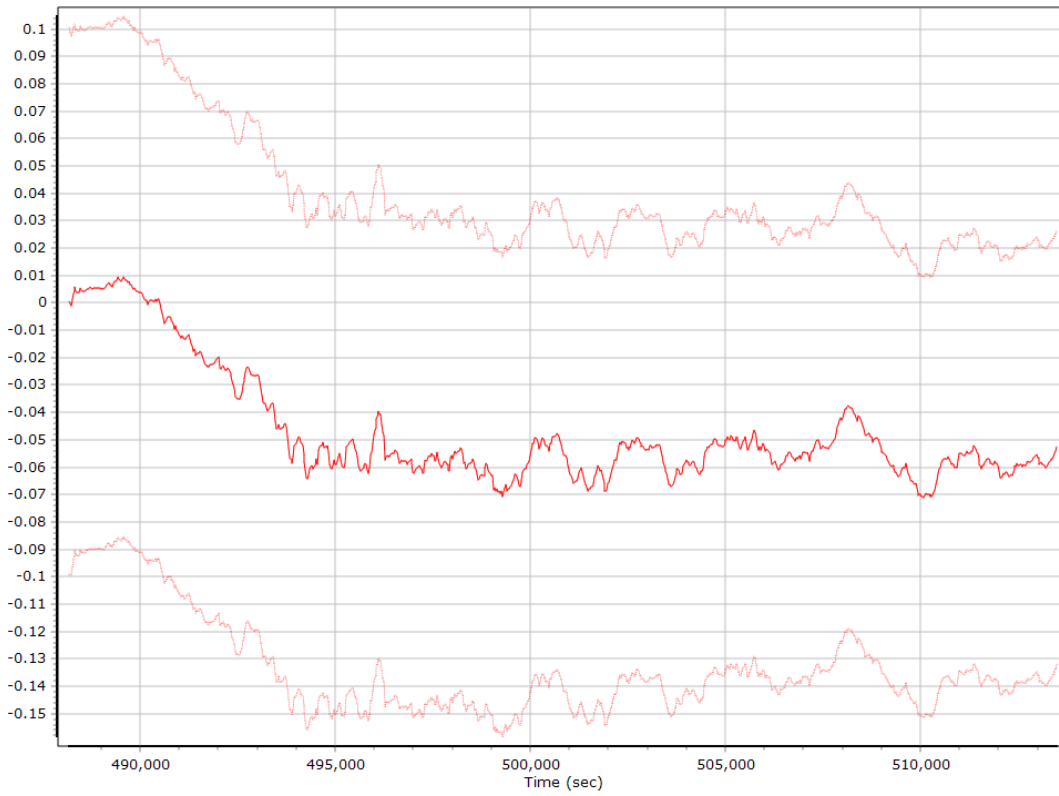
Gyro Bias (deg/h)



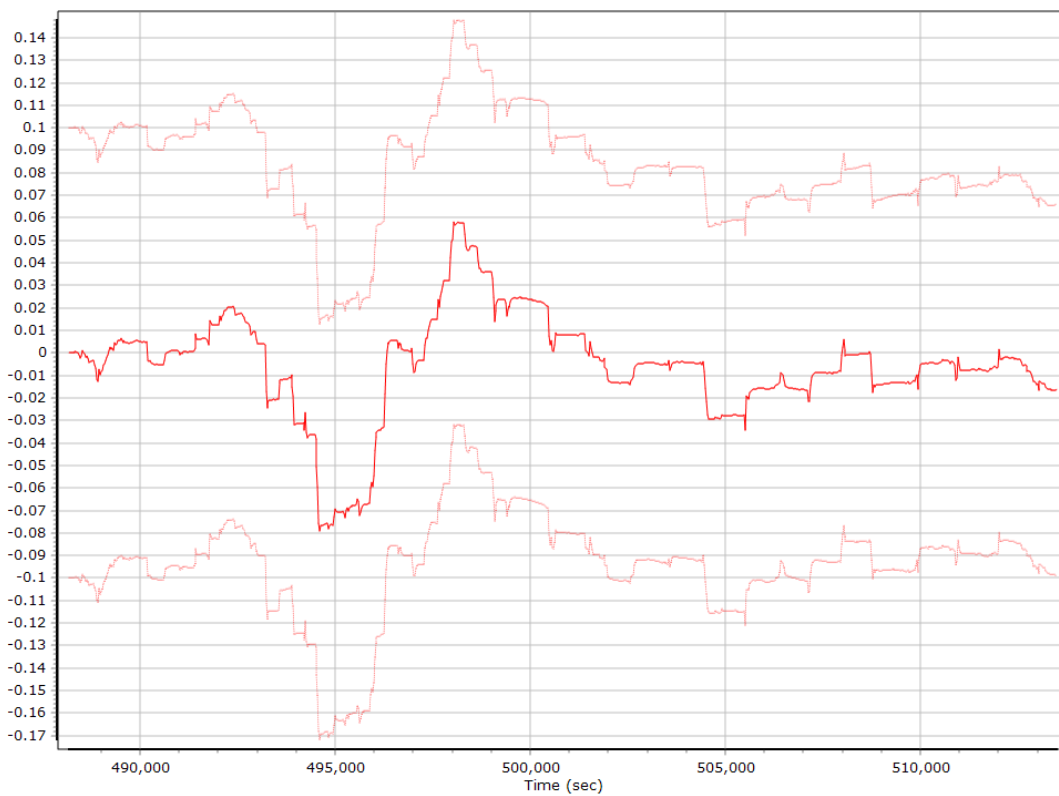
X Gyro Bias (deg/h)



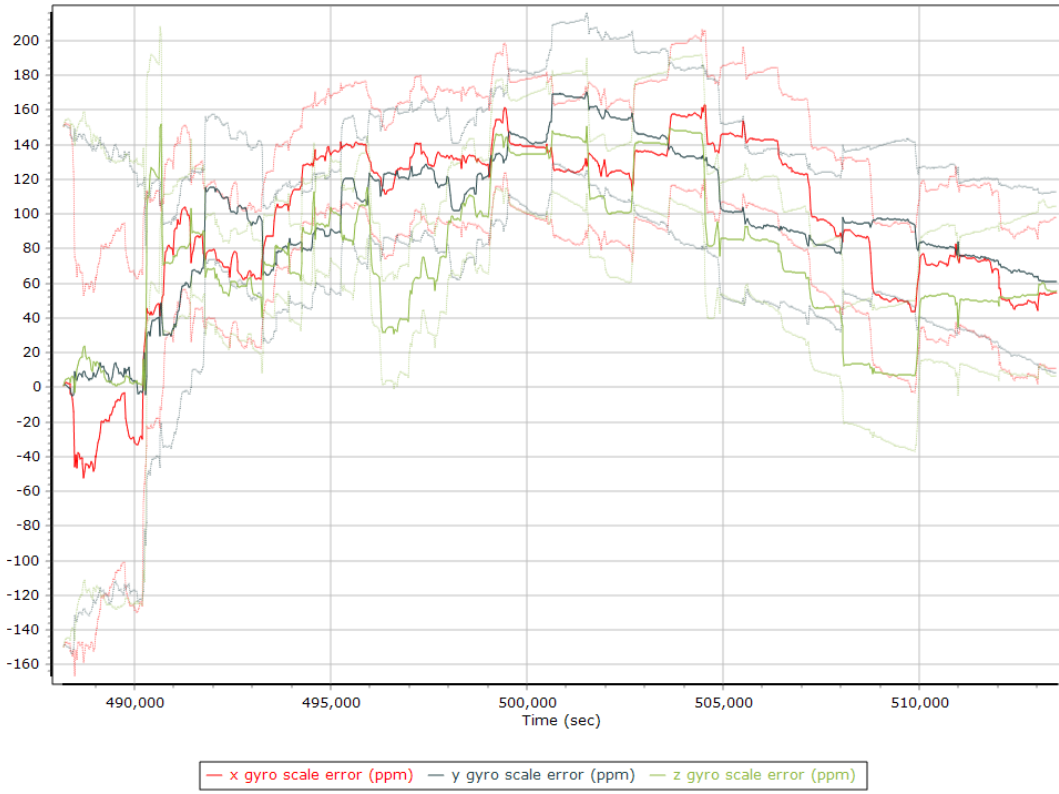
Y Gyro Bias (deg/h)



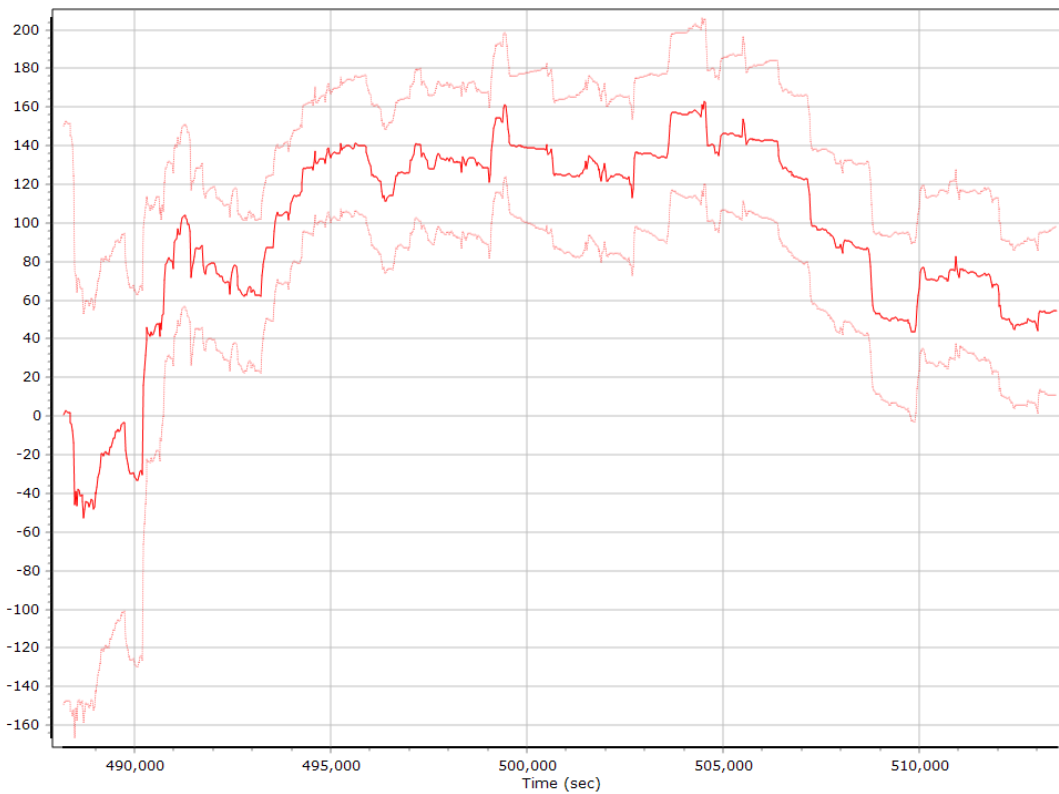
Z Gyro Bias (deg/h)



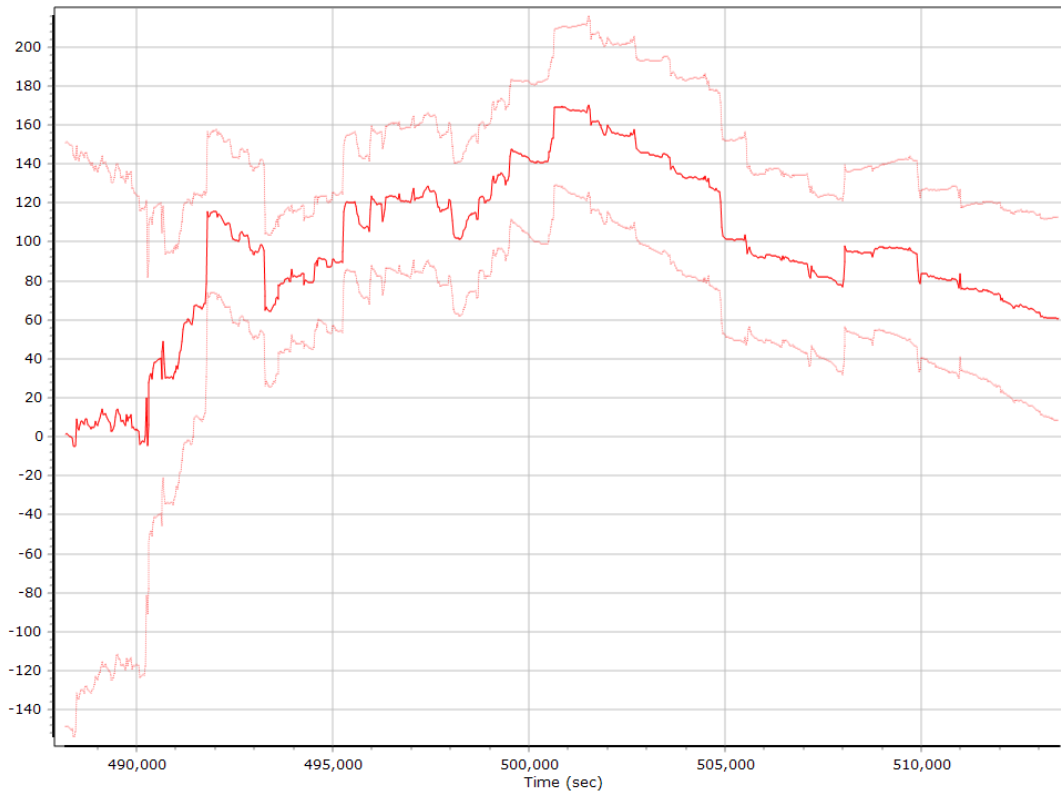
Gyro Scale Error (ppm)



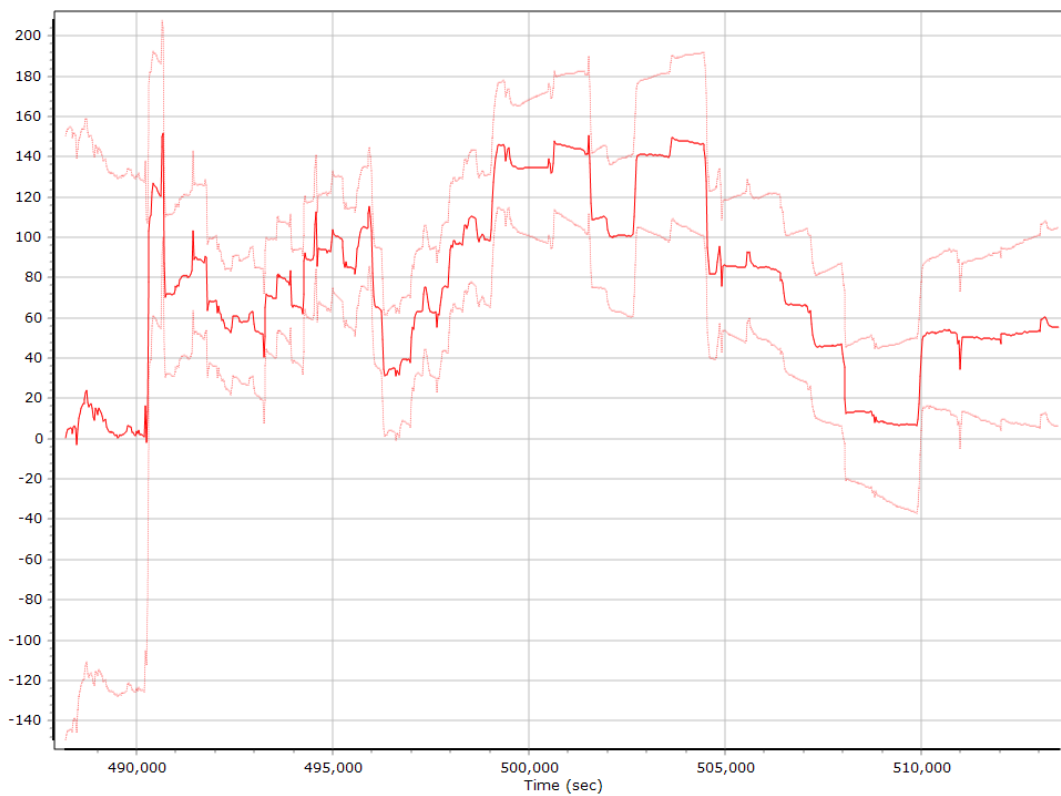
X Gyro Scale Error (ppm)



Y Gyro Scale Error (ppm)

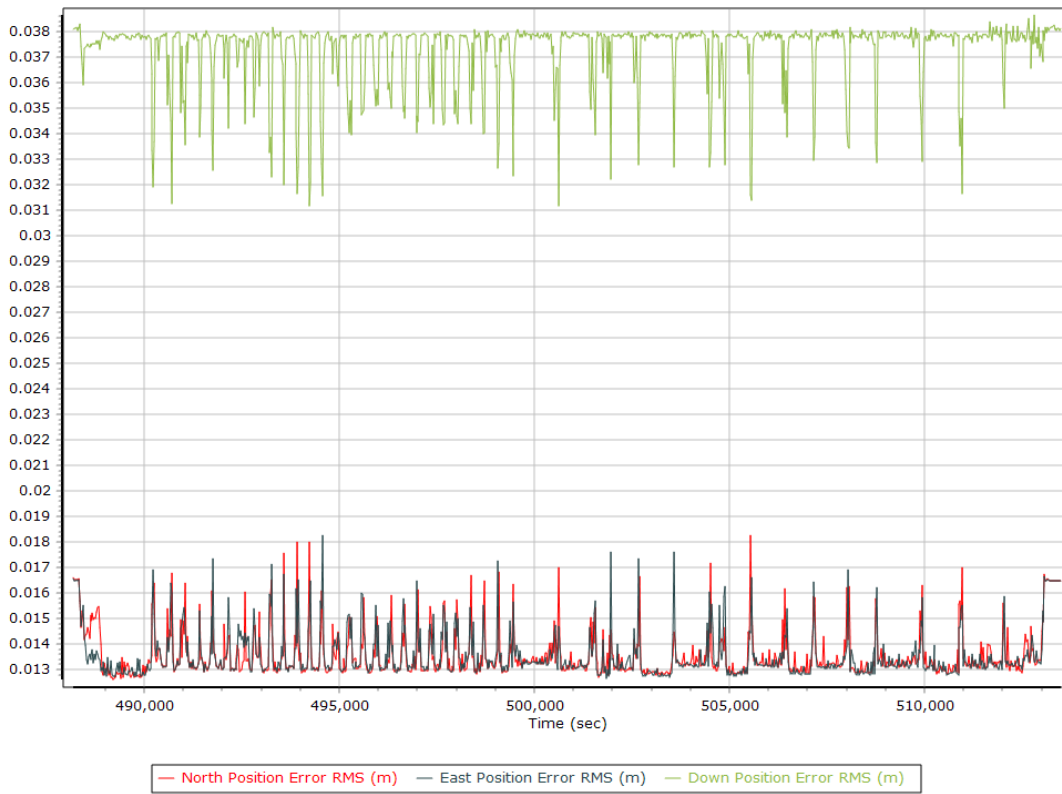


Z Gyro Scale Error (ppm)

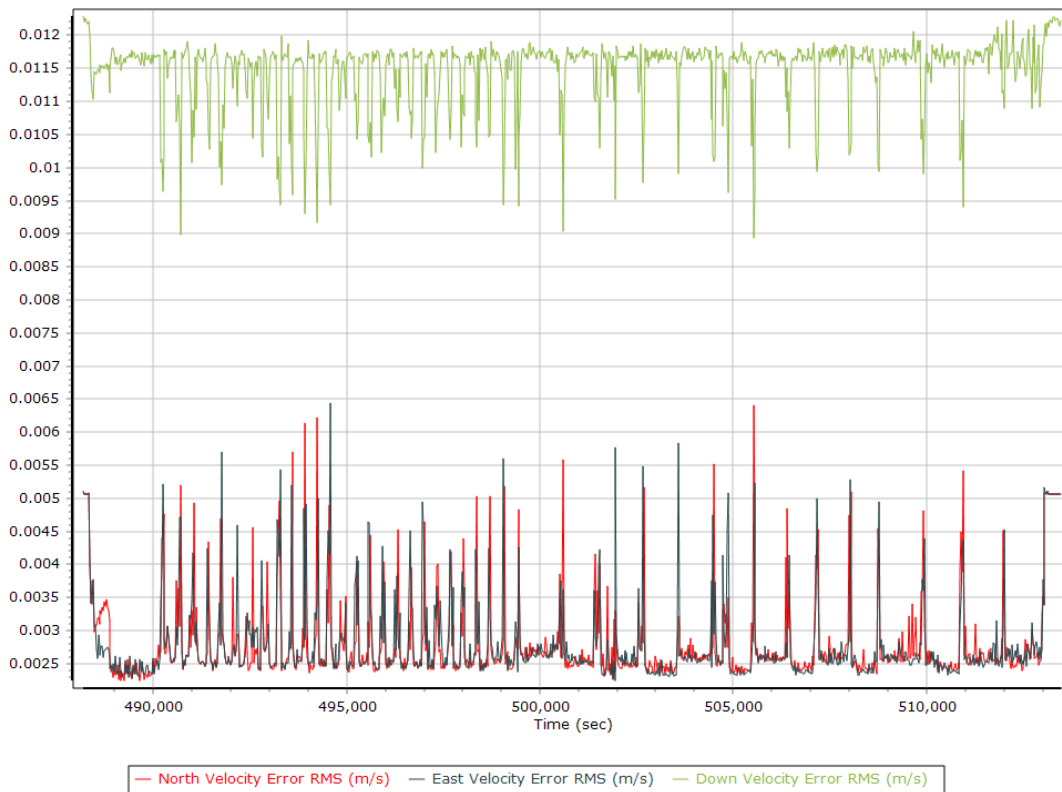


Smoothed Performance Metrics

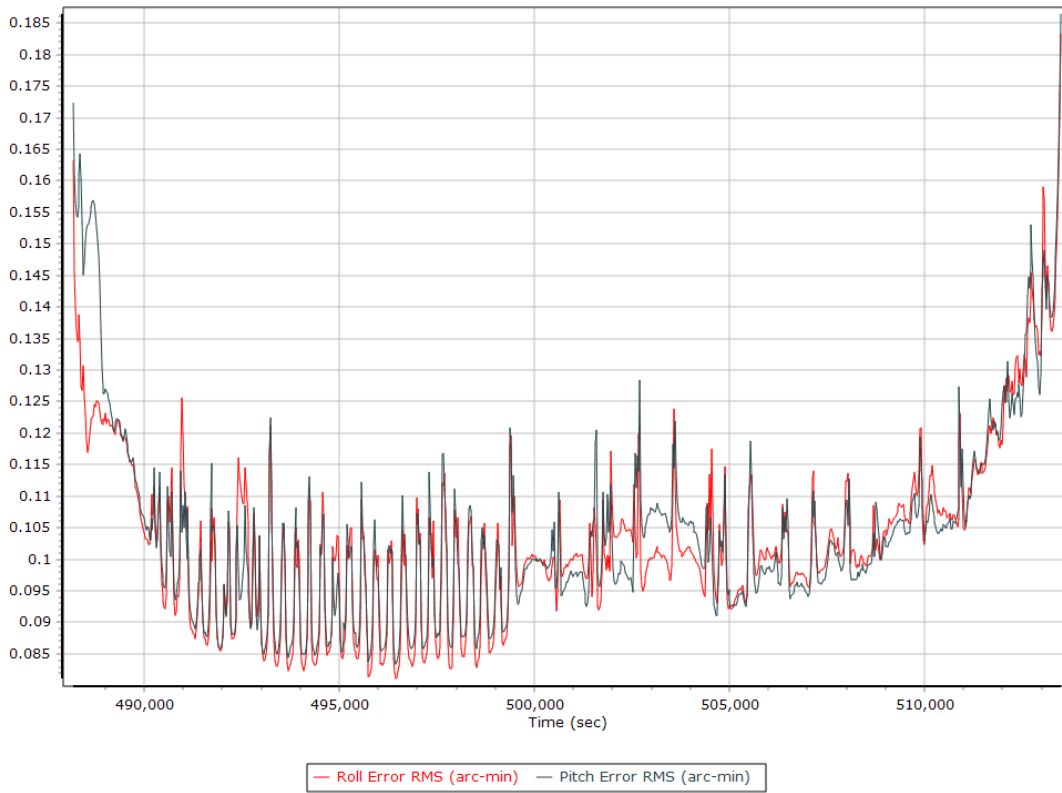
Position Error RMS (m)



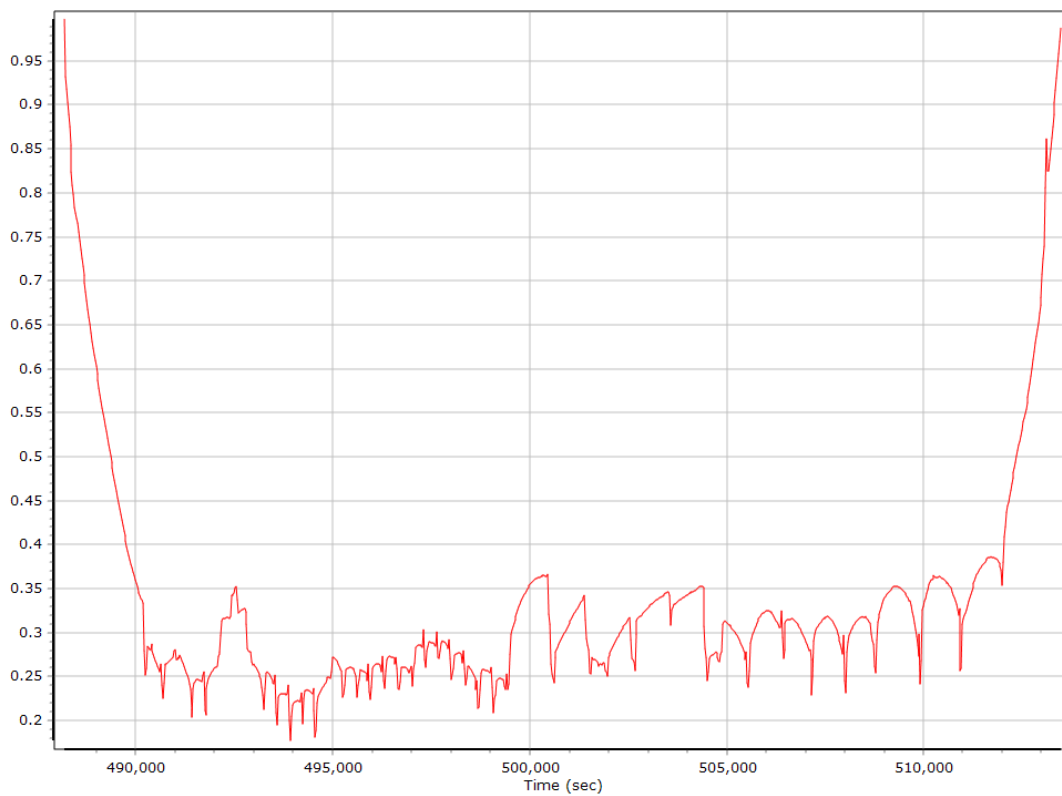
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

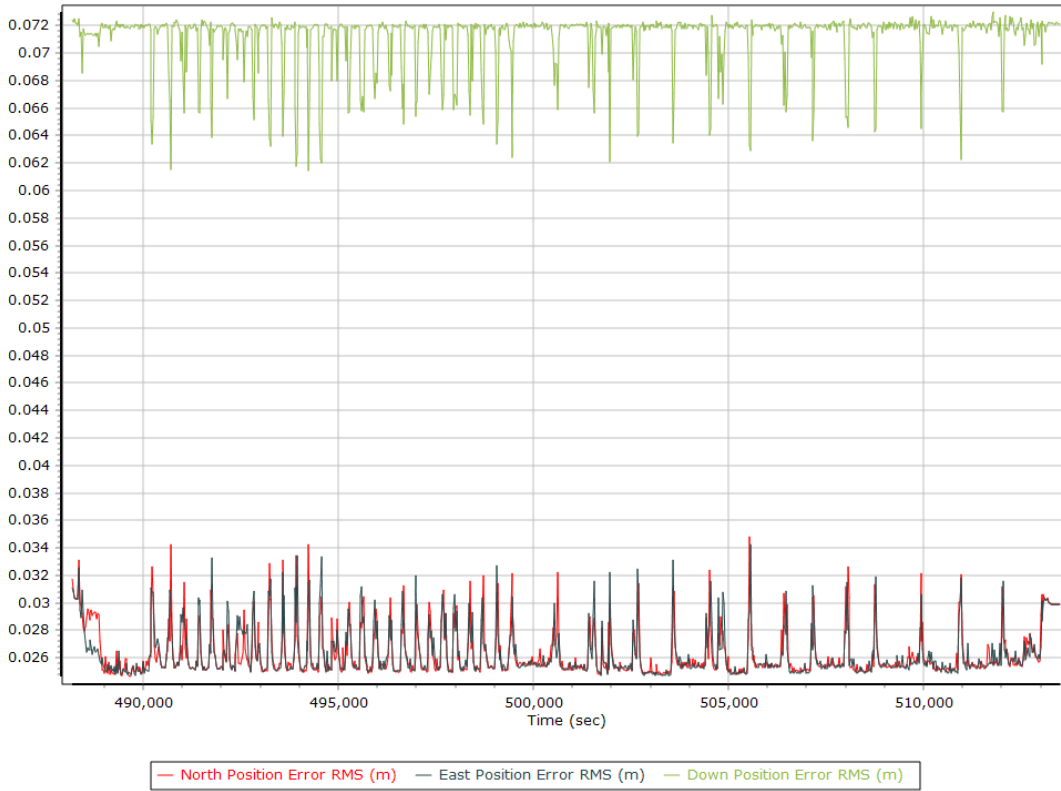


Heading Error RMS (arc-min)

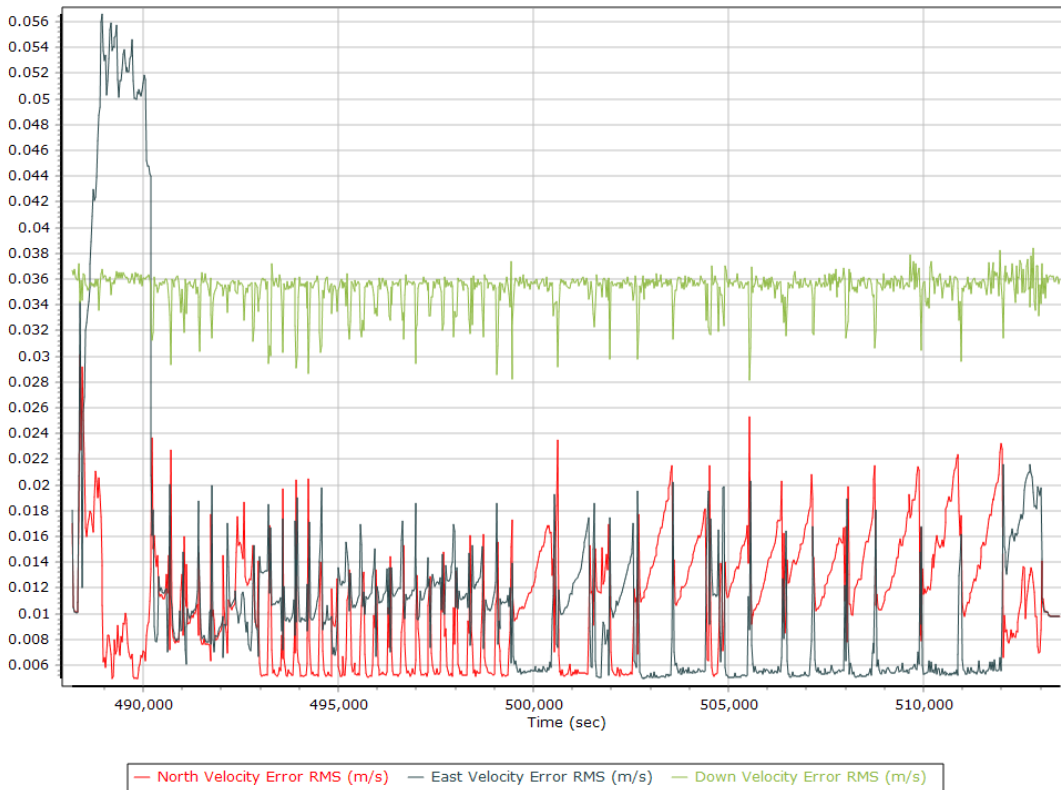


Forward Processed Performance Metrics

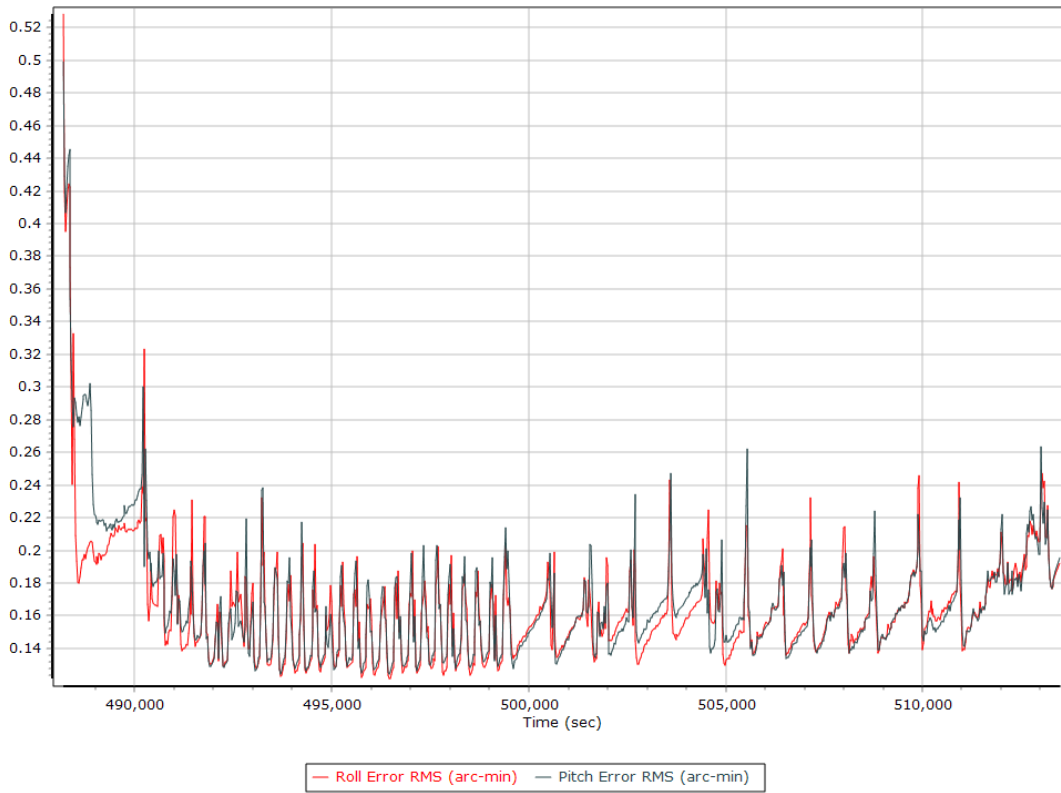
Position Error RMS (m)



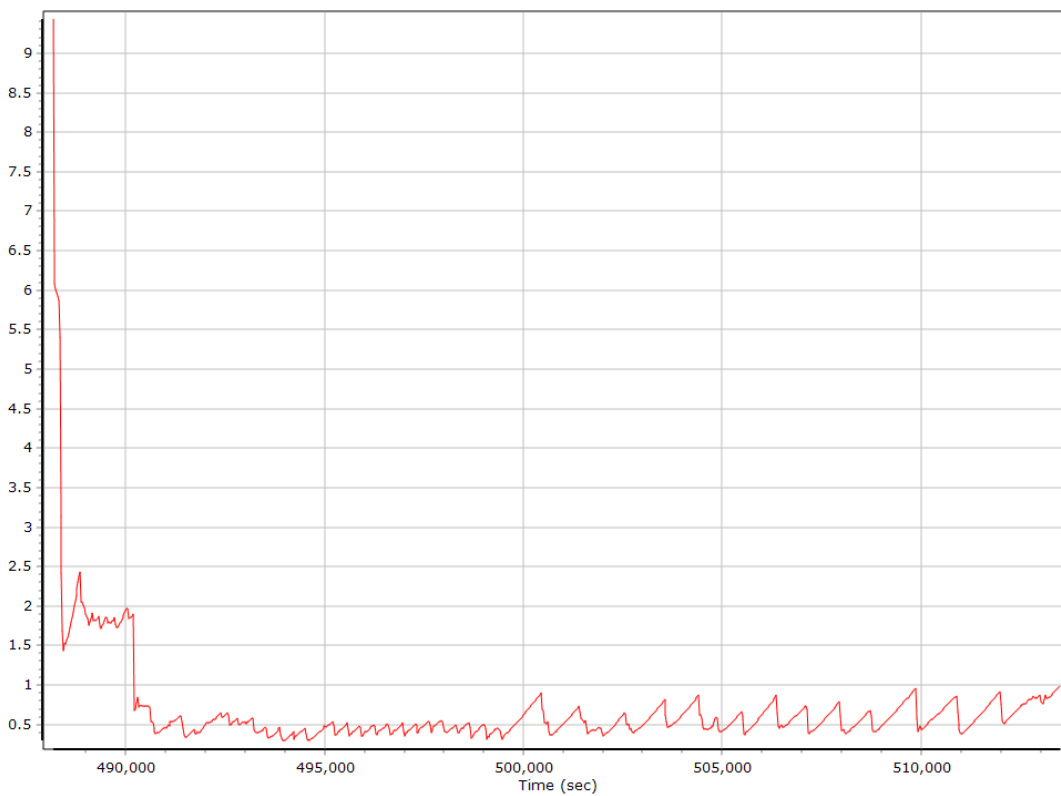
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

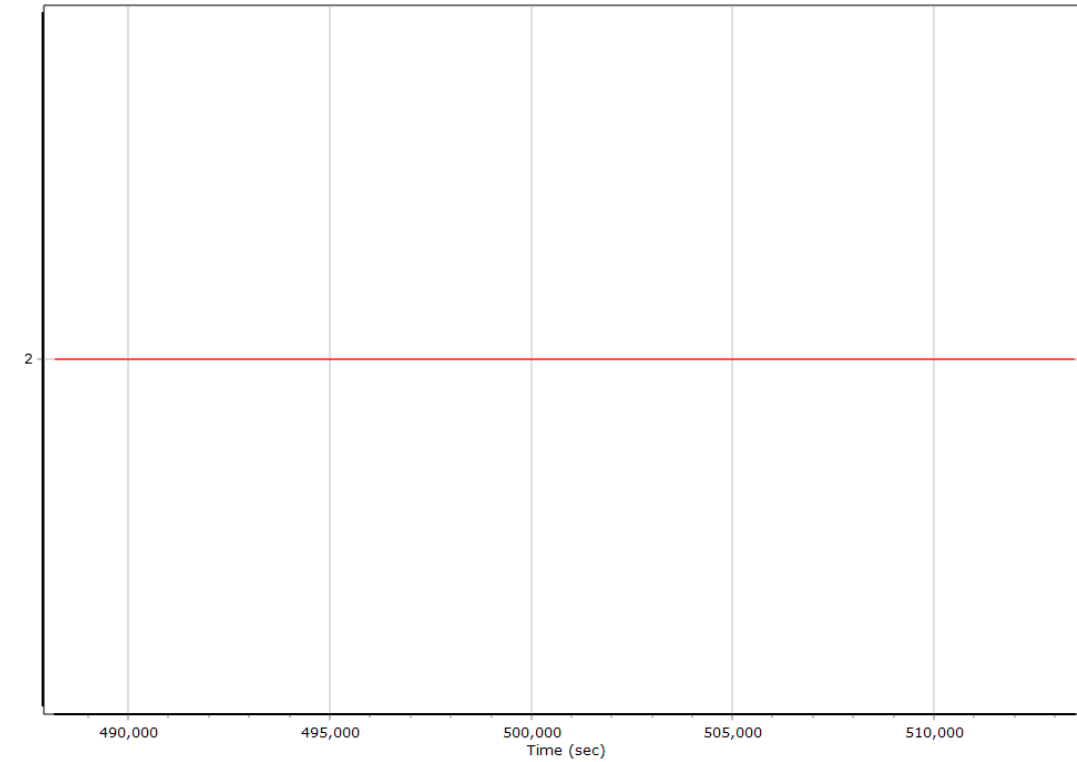


Heading Error RMS (arc-min)



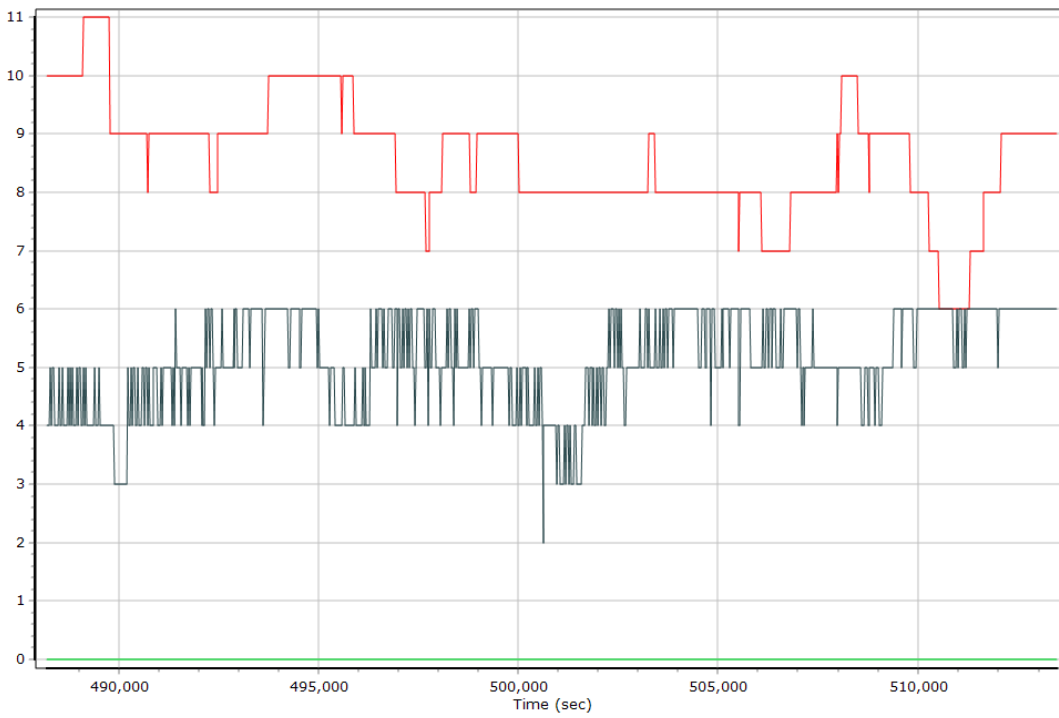
Forward Processed Solution Status

Processing Mode



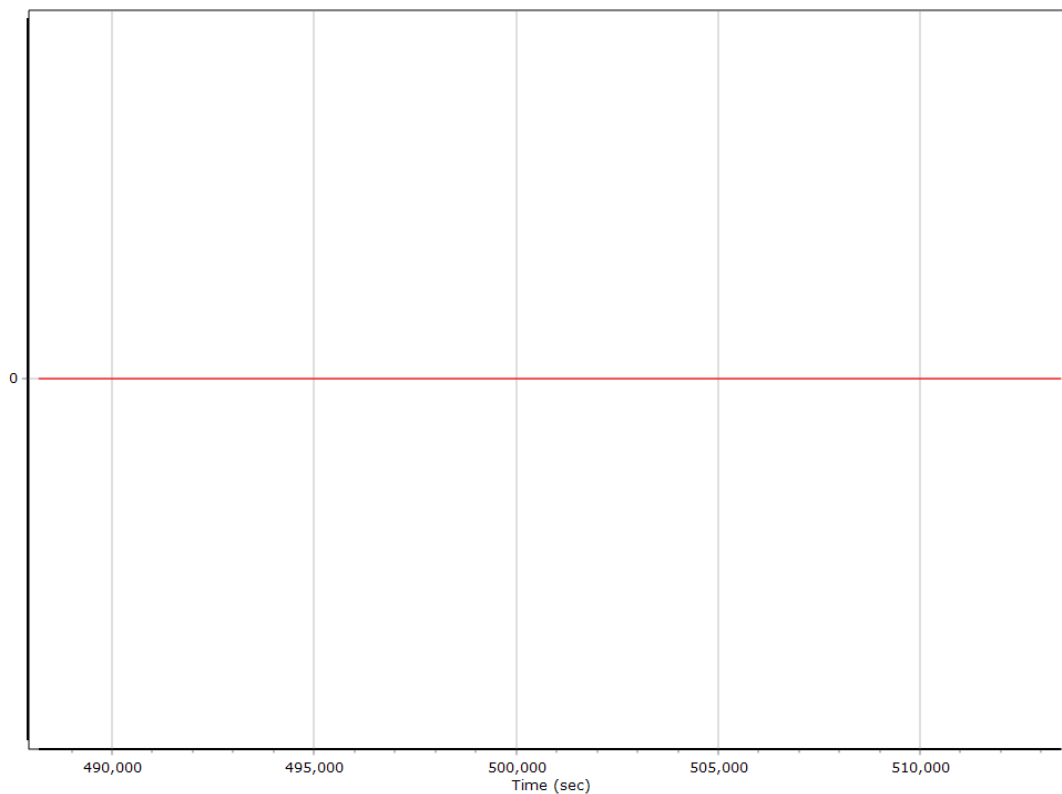
0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = C/A, 7 = GNSS Nav, 8 = DR

Number of Satellites



— Number of GPS Satellites — Number of GLONASS Satellites — Number of QZSS Satellites
— Number of BEIDOU Satellites — Number of GALILEO Satellites

Baseline Length



Export Summary

Export file	export_21-081_FFSL_210917.out		
Export format	Custom Smoothed BET		
Solution in use	Post-processed		
Output rate	All Records		
Reference to Output lever arm (m)	0.000	0.000	0.000
Reference mounting angles (deg)	0.000	0.000	0.000
Output units (Coordinate / Lat & Lon)	Meter	Deg Decimal	
Export start time	488127.003 (09/17/2021 15:35:27)		
Export end time	513497.416 (09/17/2021 22:38:17)		
Height option	Ellipsoid Height		
WGS84 height flag	False		
Grid	Universal Transverse Mercator		
Zone	UTM North 12 (114W to 108W)		
Datum	NAD83 (2011)		
Ellipsoid	GRS 1980		
Local Transformation	NONE		
Target Epoch	2010		

General Information

Mission Information

Project name	21-081_FFSL_210918_ALS
Processing date	2021-11-10 21:20:29
Mission date	2021-09-18 14:48:10
Mission duration	07:13:54.861
Processing mode	Un-Processed

Rover Hardware Information

Product	None assigned
Serial number	
IMU type	0
Receiver type	Unknown
Antenna type	Unknown External

Project File List

Rover Data Files

File name	File type
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Input Files

File Name	File Type
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Output Files

Filename	File type
sbet_Mission 1.out	SBET Trajectory File

Rover Data Summary

First raw data file			
Last raw data file			
Start GPS week	0		
Start time	571683.811 (1/12/1980 2:48:03 PM)		
End time	598228.762 (1/12/1980 10:10:28 PM)		
Start of fine alignment	572191.786 (1/12/1980 2:56:31 PM)		
Available subsystems	Primary GNSS, Gimbal, IMU		
POS Event Input	None		
Correction data	None		
IMU Installation Lever Arms & Mounting Angles			
Gimbal to IMU lever arm (m)	-0.034	-0.010	-0.374
Gimbal to IMU mounting angles (deg)	0.000	0.000	0.000
Gimbal to Primary GNSS lever arm (m)	0.980	-0.102	-1.276
Gimbal to Primary GNSS lever arm std dev (m)	-1.000		
Vehicle to Reference mounting angles (deg)	0.000	0.000	0.000

Rover Data QC

Raw IMU Import QC Summary

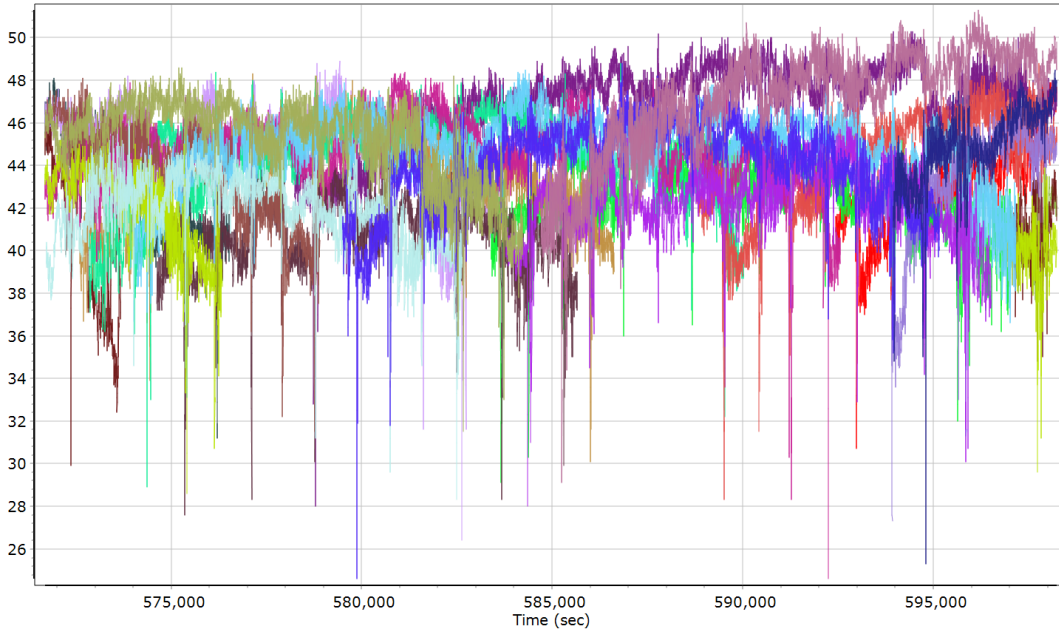
IMU data input file	imu_Mission 1.dat
IMU data check log file	imudt_Mission 1.log
IMU Records Processed	5311292
Termination Status	Warnings
IMU Anomalies	1
IMU Failure Messages	
571683.651 : WARNING : Gap of 571671.6951 seconds in CHECKDT input data	

Primary Observables & Satellite Data

GPS/GLONASS L1 Satellite Lock/Elevation

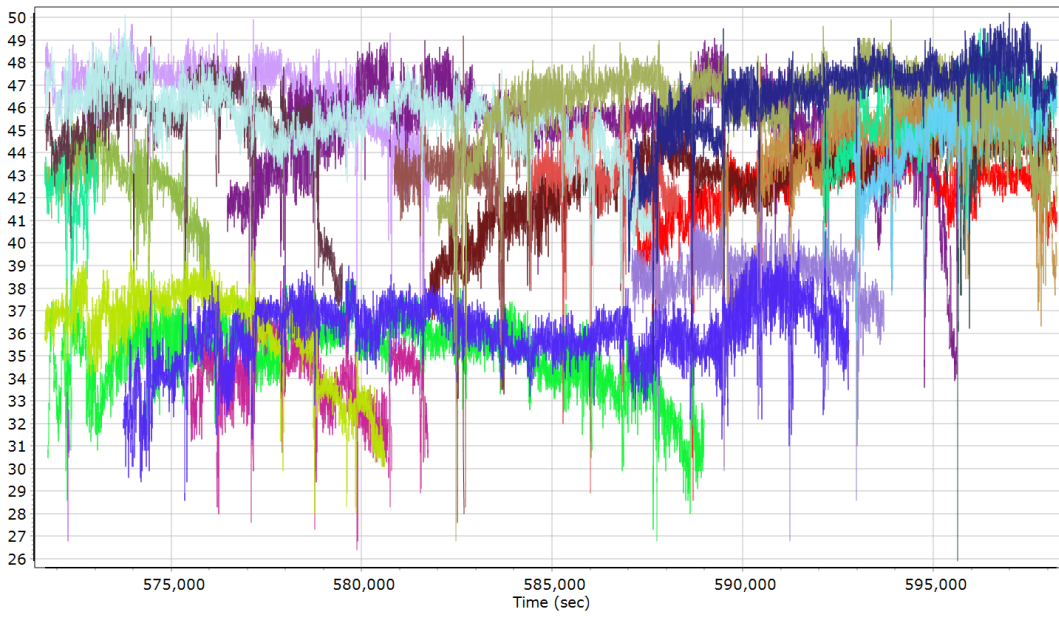


GPS L1 SNR



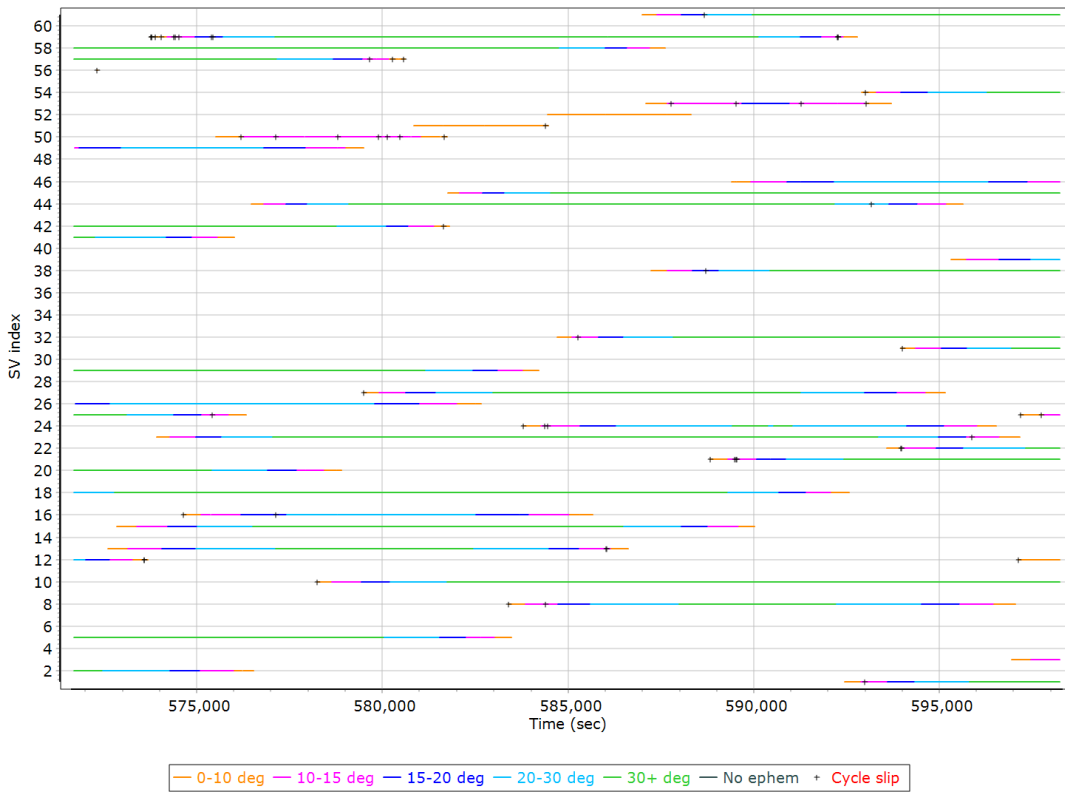
- | | | | |
|---------------------------|---------------------------|---------------------------|---------------------------|
| GPS PRN 01 L1 SNR (dB/Hz) | GPS PRN 02 L1 SNR (dB/Hz) | GPS PRN 03 L1 SNR (dB/Hz) | GPS PRN 05 L1 SNR (dB/Hz) |
| GPS PRN 08 L1 SNR (dB/Hz) | GPS PRN 10 L1 SNR (dB/Hz) | GPS PRN 12 L1 SNR (dB/Hz) | GPS PRN 13 L1 SNR (dB/Hz) |
| GPS PRN 15 L1 SNR (dB/Hz) | GPS PRN 16 L1 SNR (dB/Hz) | GPS PRN 18 L1 SNR (dB/Hz) | GPS PRN 20 L1 SNR (dB/Hz) |
| GPS PRN 21 L1 SNR (dB/Hz) | GPS PRN 22 L1 SNR (dB/Hz) | GPS PRN 23 L1 SNR (dB/Hz) | GPS PRN 24 L1 SNR (dB/Hz) |
| GPS PRN 25 L1 SNR (dB/Hz) | GPS PRN 26 L1 SNR (dB/Hz) | GPS PRN 27 L1 SNR (dB/Hz) | GPS PRN 29 L1 SNR (dB/Hz) |
| GPS PRN 31 L1 SNR (dB/Hz) | GPS PRN 32 L1 SNR (dB/Hz) | | |

GLONASS L1 SNR

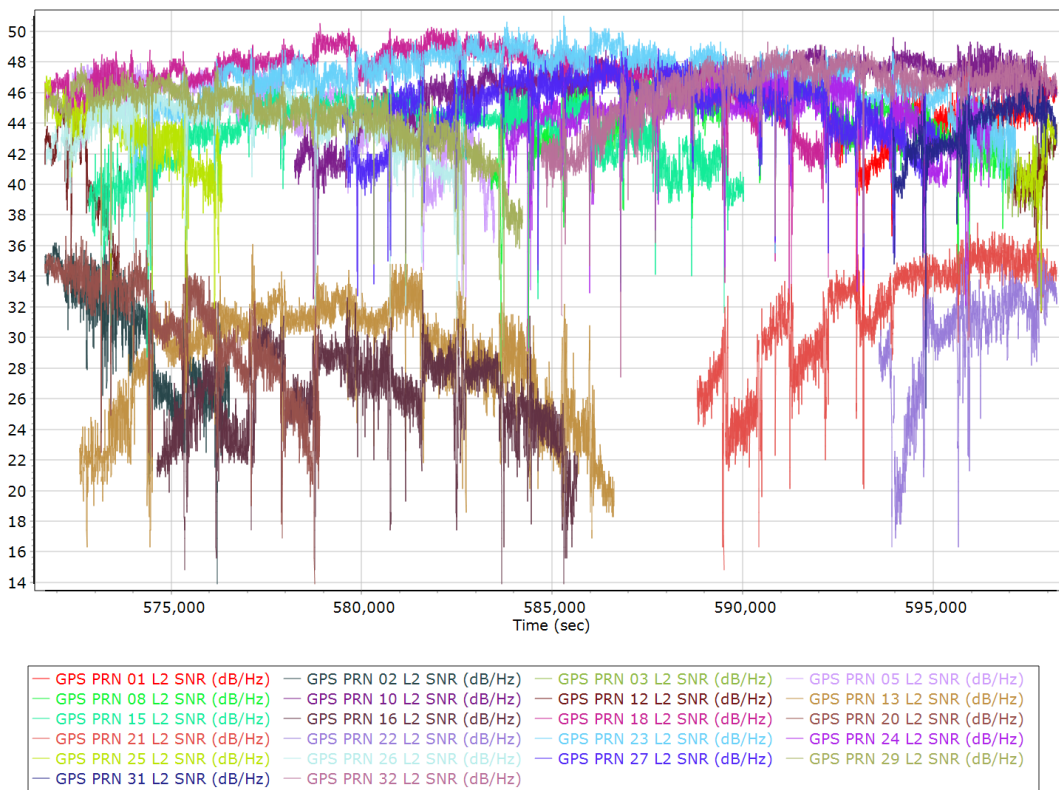


- | | | |
|---------------------------|---------------------------|---------------------------|
| GLONASS 01 L1 SNR (dB/Hz) | GLONASS 02 L1 SNR (dB/Hz) | GLONASS 04 L1 SNR (dB/Hz) |
| GLONASS 05 L1 SNR (dB/Hz) | GLONASS 06 L1 SNR (dB/Hz) | GLONASS 07 L1 SNR (dB/Hz) |
| GLONASS 08 L1 SNR (dB/Hz) | GLONASS 09 L1 SNR (dB/Hz) | GLONASS 10 L1 SNR (dB/Hz) |
| GLONASS 12 L1 SNR (dB/Hz) | GLONASS 13 L1 SNR (dB/Hz) | GLONASS 14 L1 SNR (dB/Hz) |
| GLONASS 15 L1 SNR (dB/Hz) | GLONASS 16 L1 SNR (dB/Hz) | GLONASS 17 L1 SNR (dB/Hz) |
| GLONASS 19 L1 SNR (dB/Hz) | GLONASS 20 L1 SNR (dB/Hz) | GLONASS 21 L1 SNR (dB/Hz) |
| GLONASS 22 L1 SNR (dB/Hz) | GLONASS 23 L1 SNR (dB/Hz) | GLONASS 24 L1 SNR (dB/Hz) |

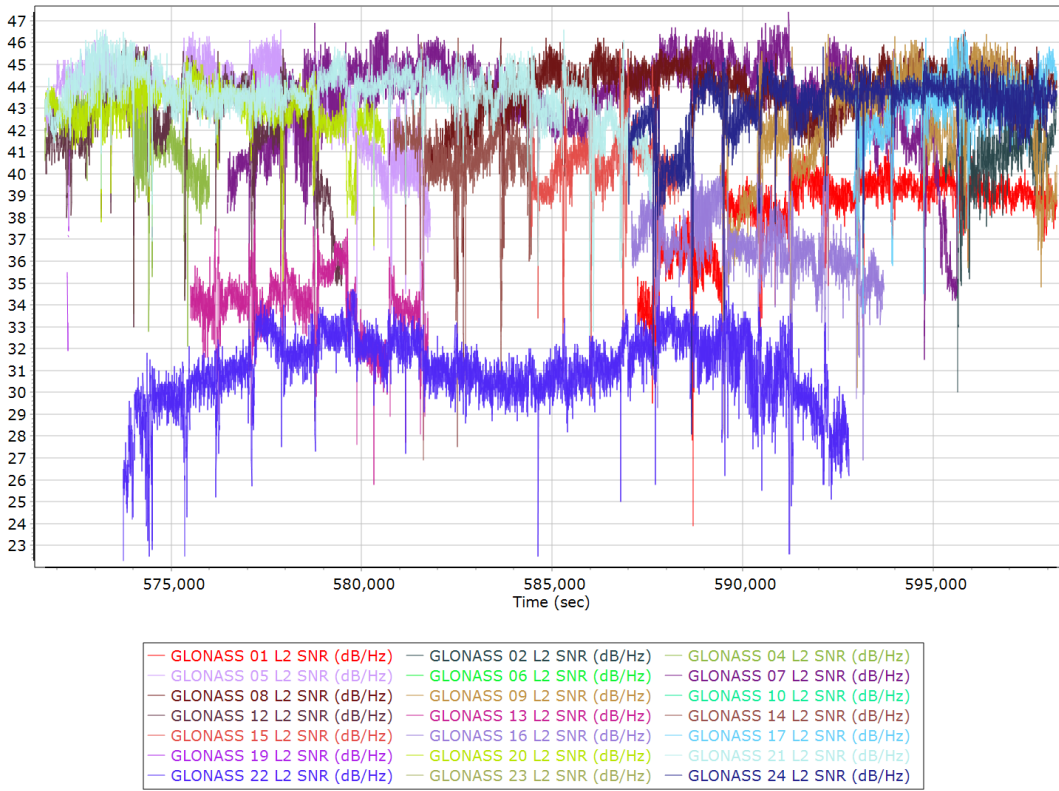
GPS/GLONASS L2 Satellite Lock/Elevation



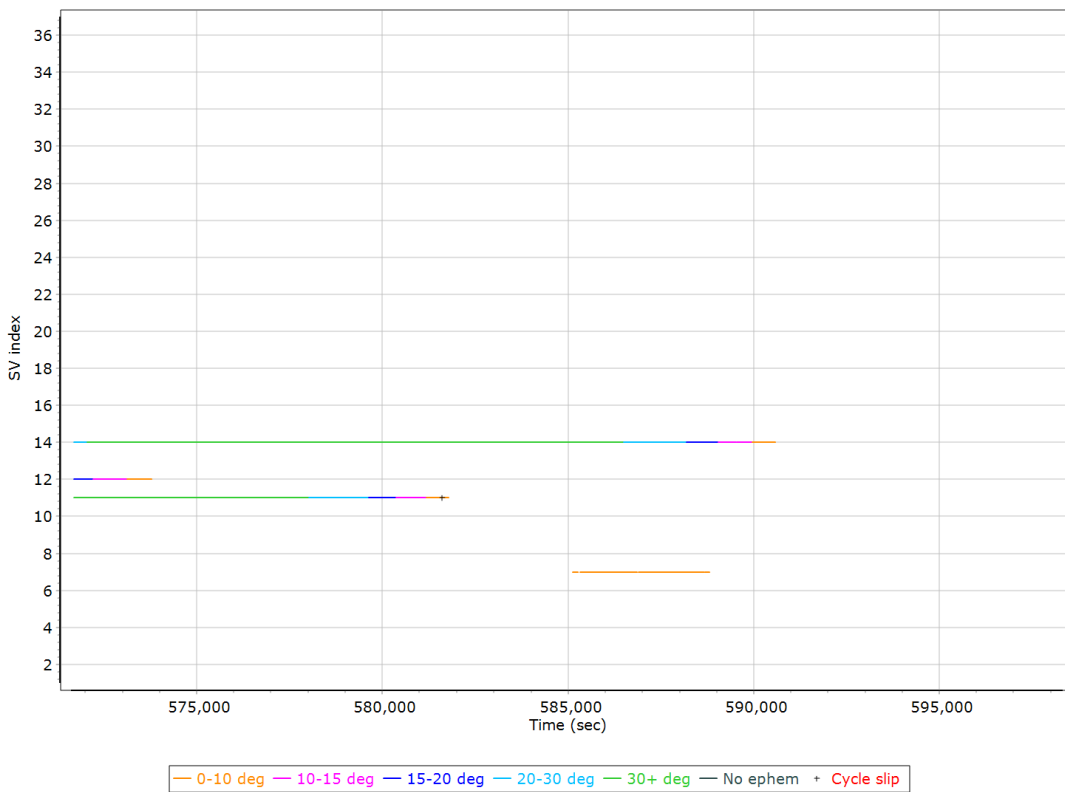
GPS L2 SNR



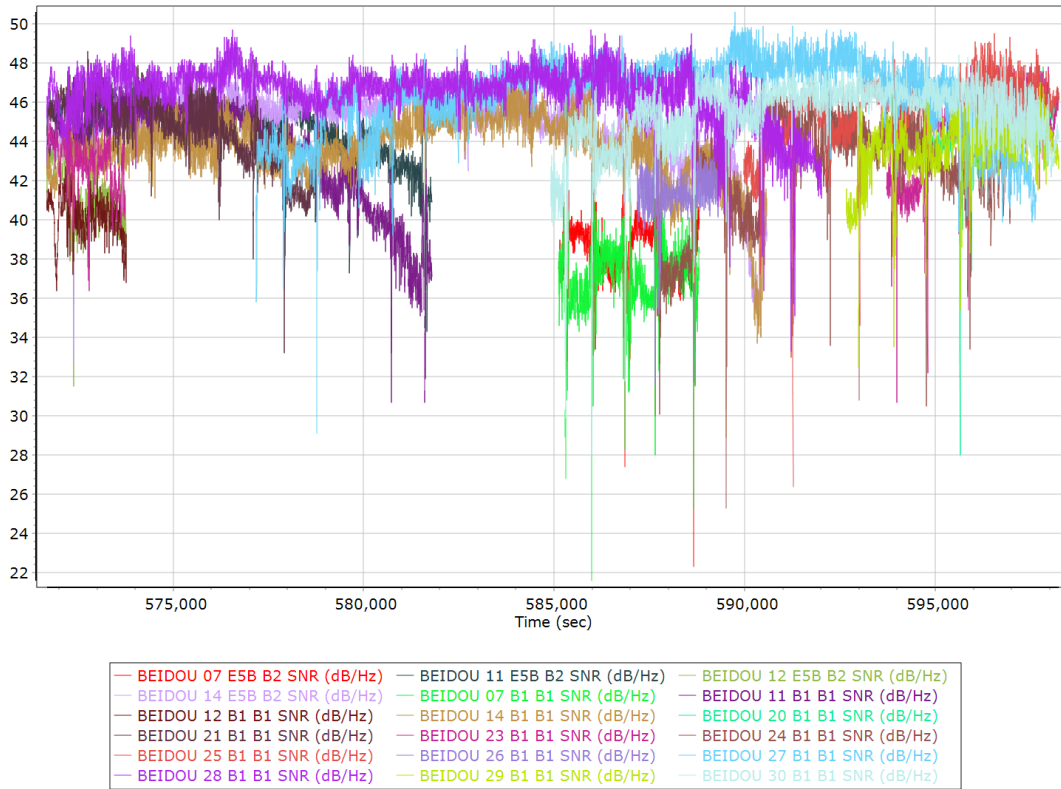
GLONASS L2 SNR



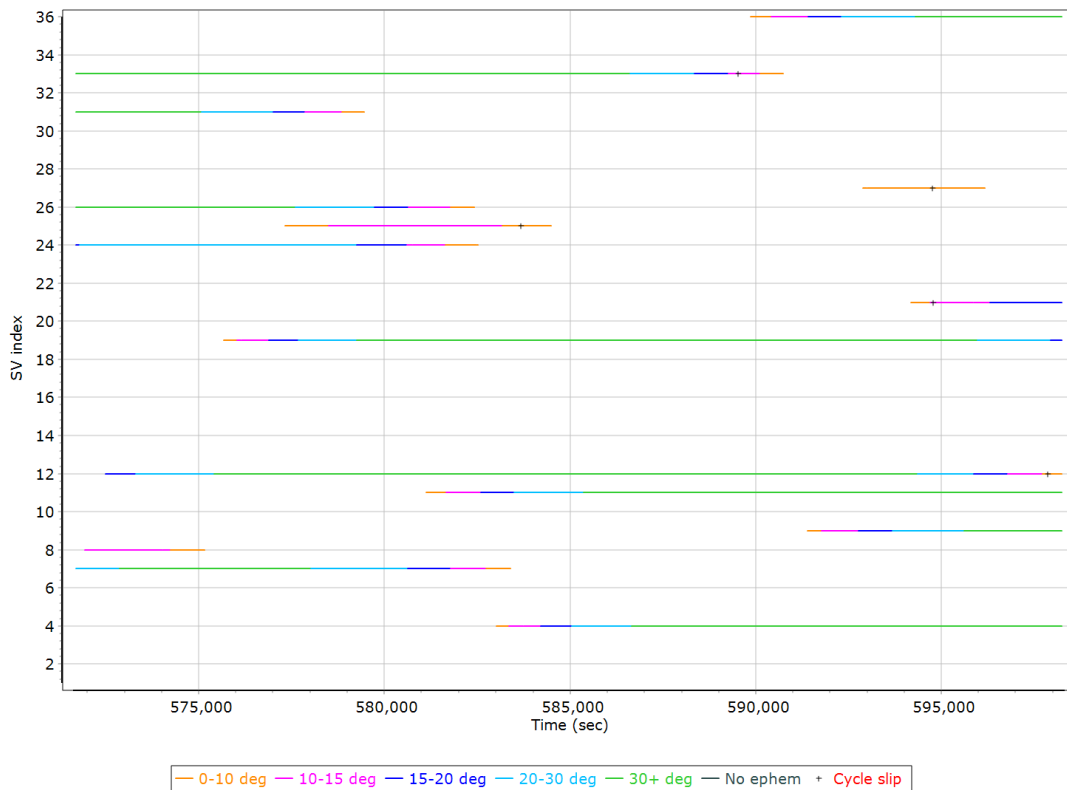
BEIDOU Satellite Lock/Elevation



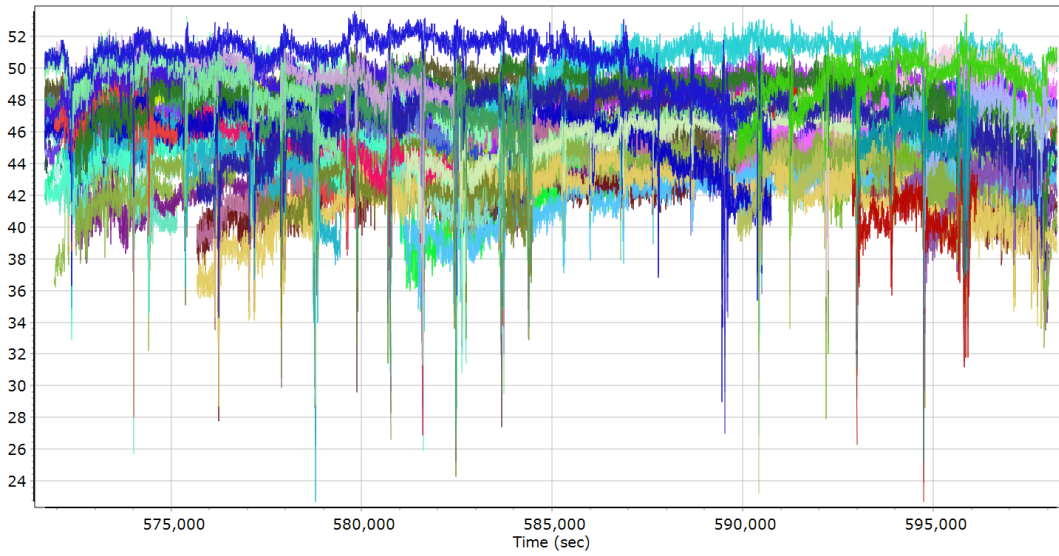
BEIDOU SNR



GALILEO Satellite Lock/Elevation



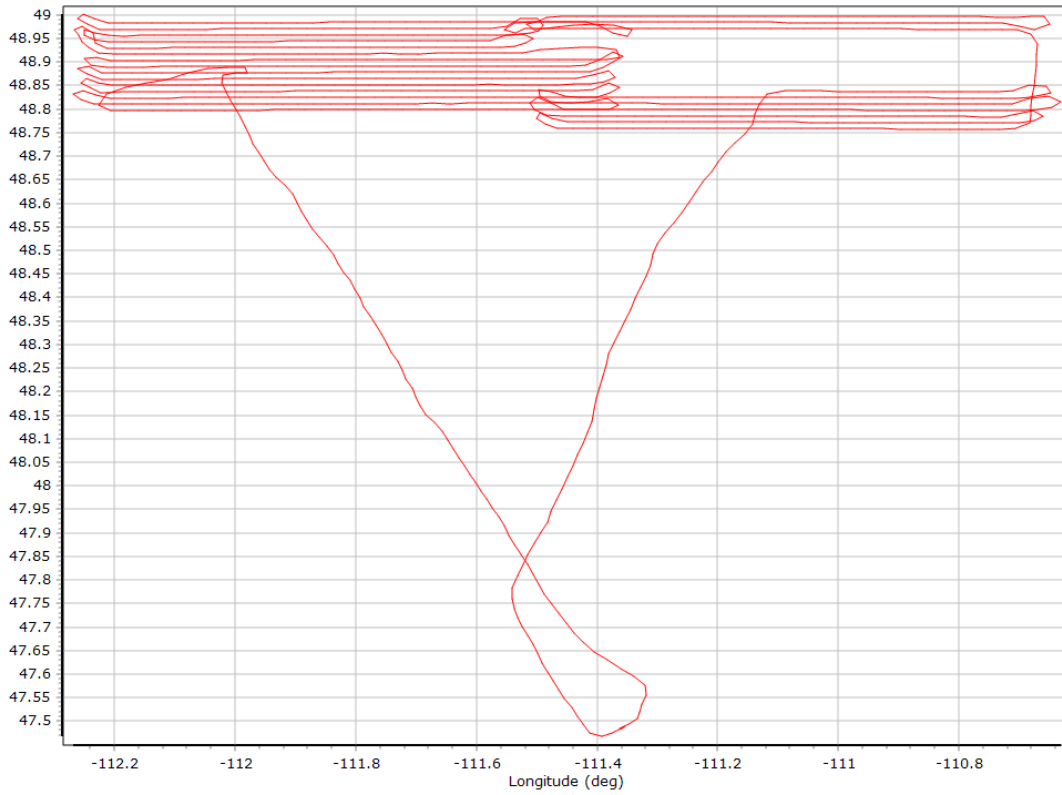
GALILEO SNR



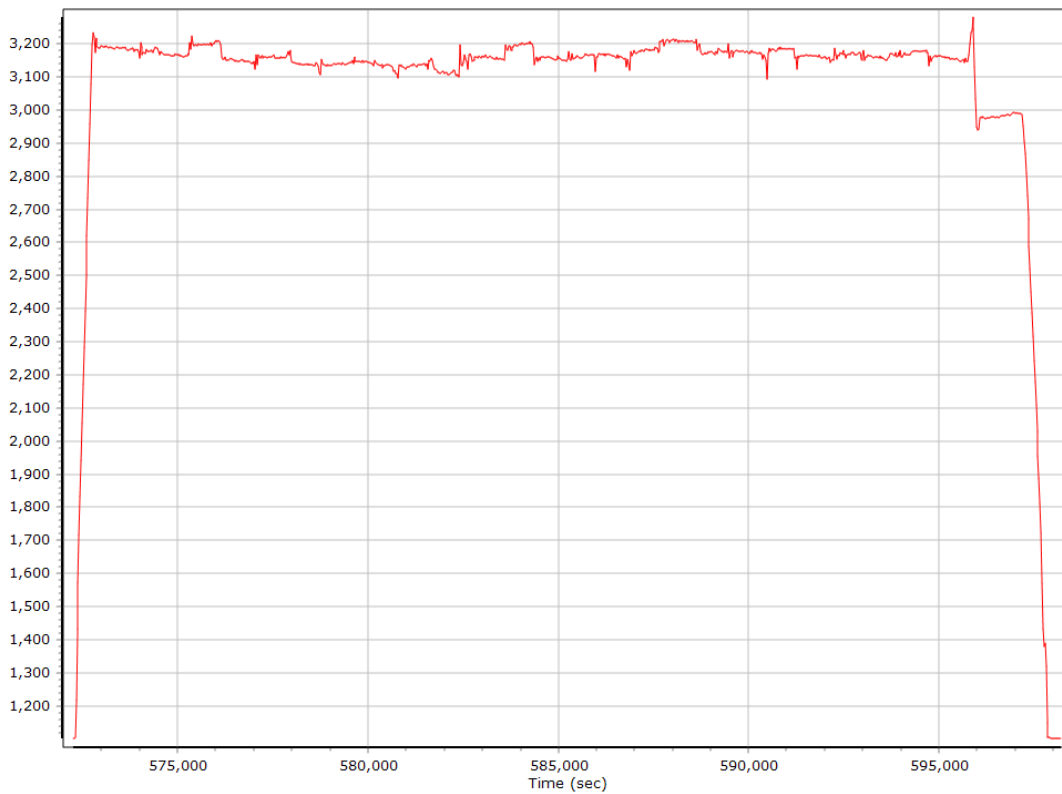
— GALILEO 04 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 07 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 08 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 09 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 11 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 12 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 19 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 21 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 24 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 25 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 26 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 27 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 31 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 33 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 36 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 04 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 07 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 08 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 09 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 11 L5E5A BPSK10_PD SNR (dB/Hz)

Smoothed Trajectory Information

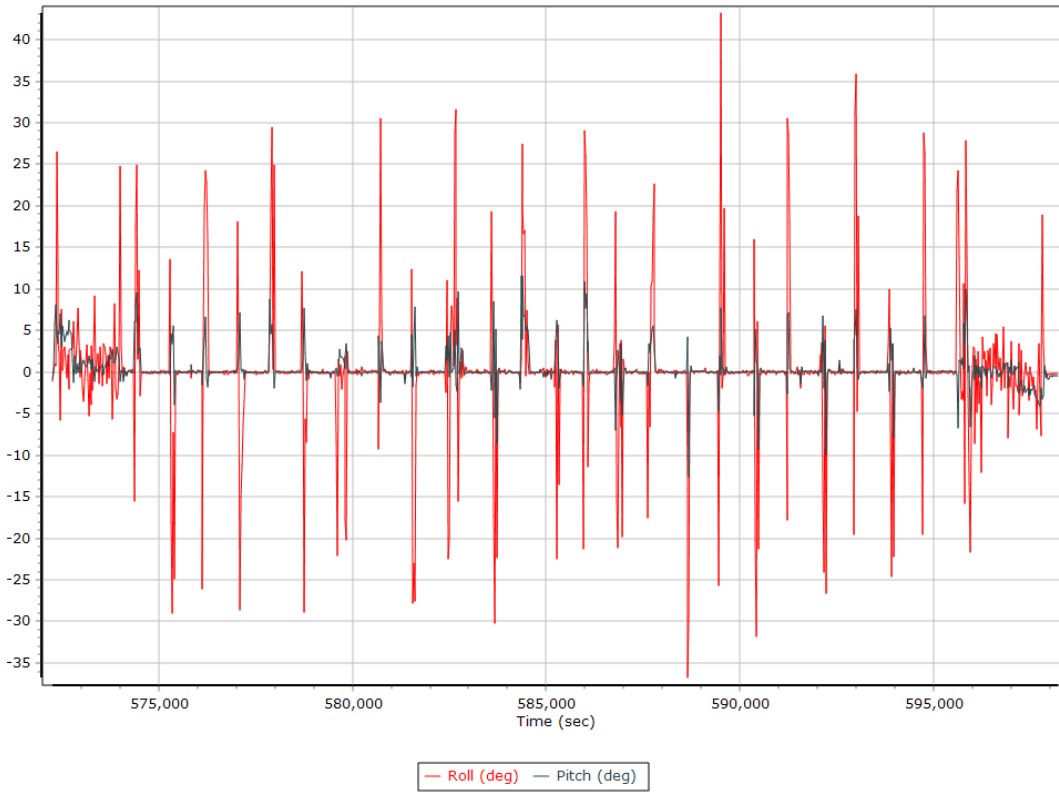
Top View



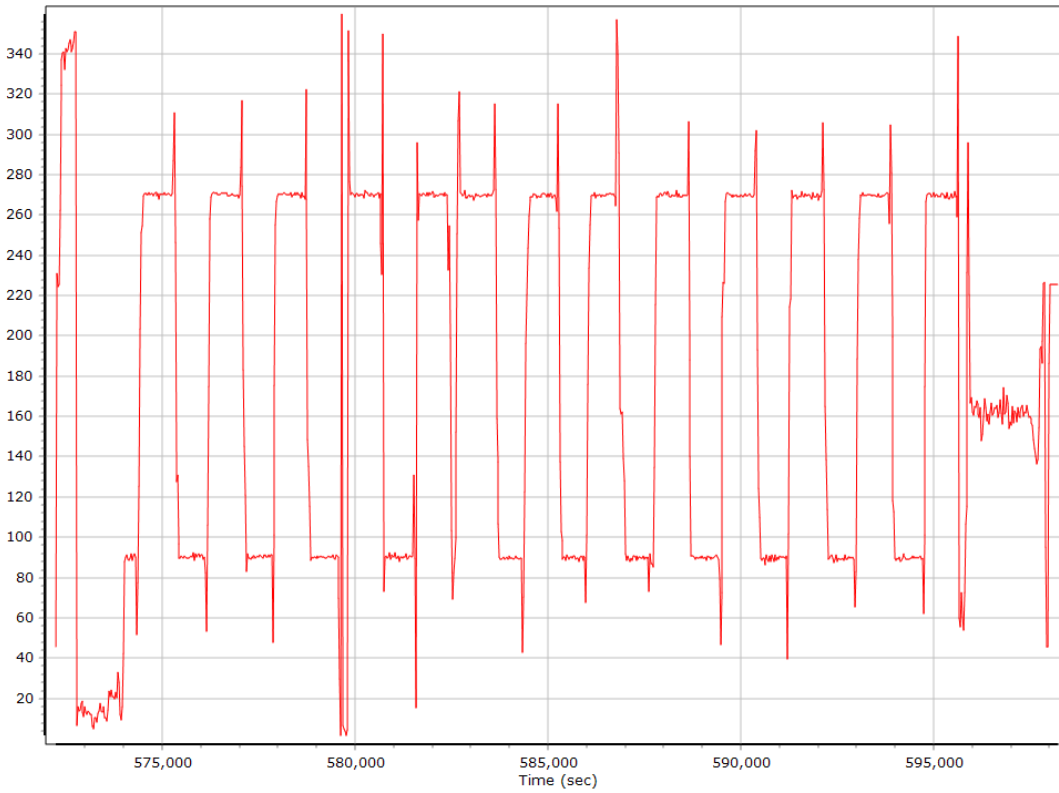
Altitude



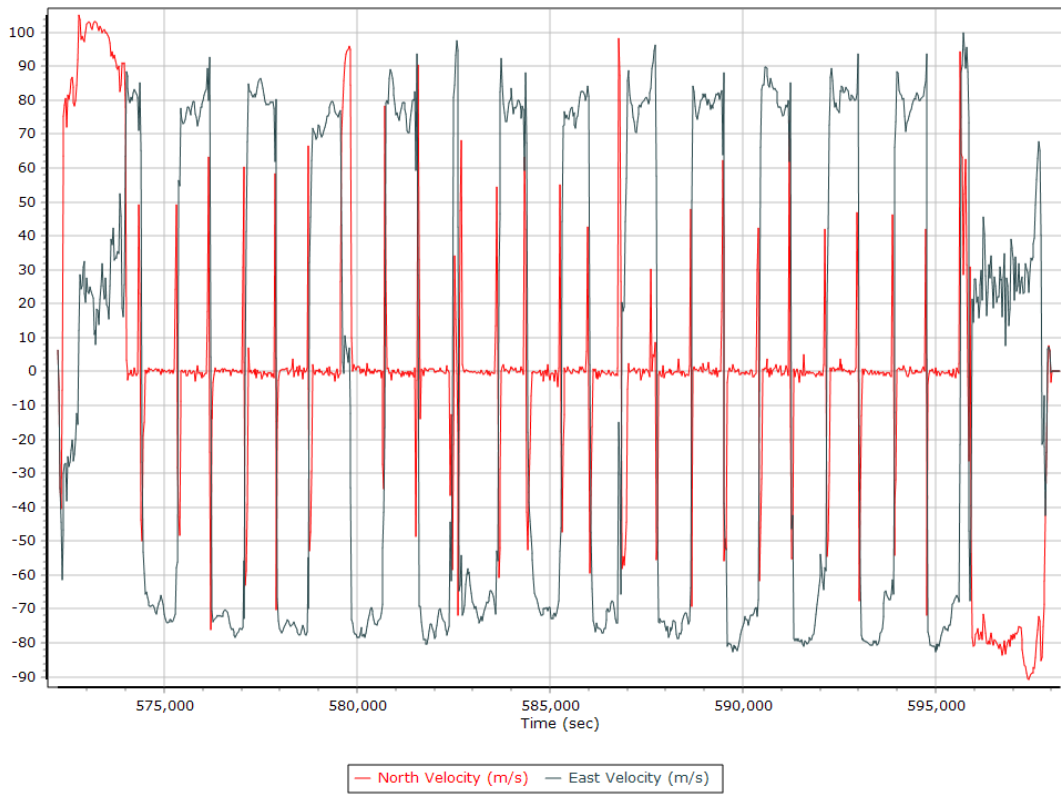
Roll/Pitch



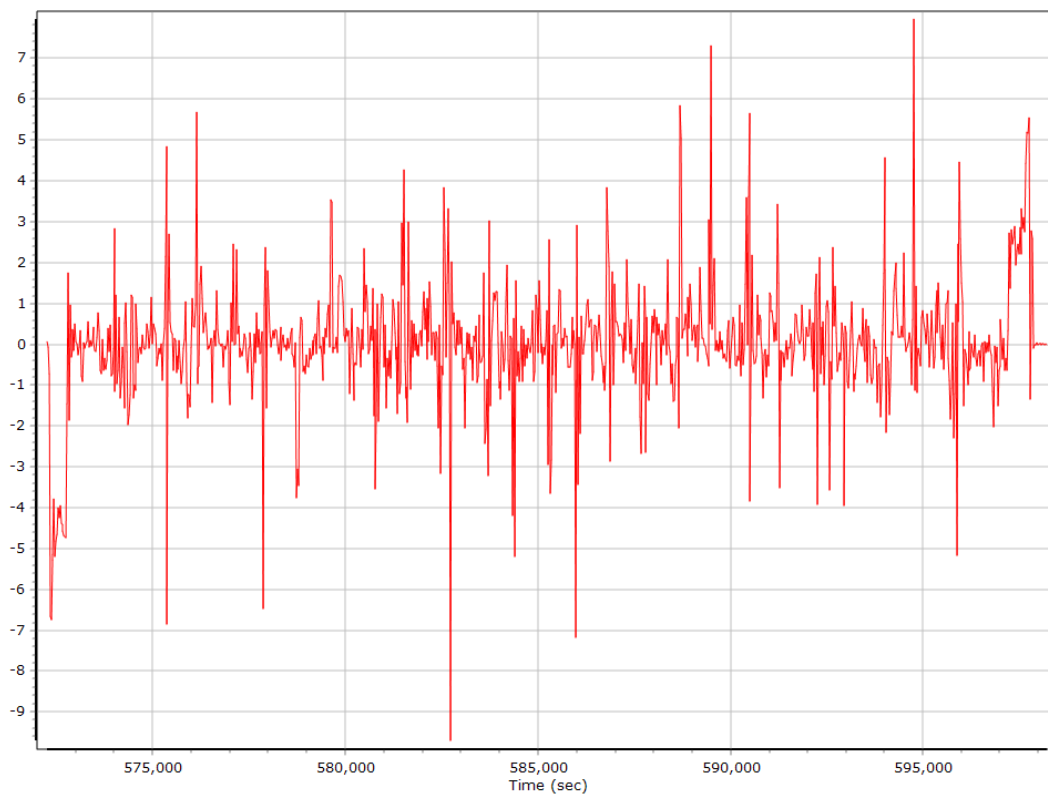
Heading



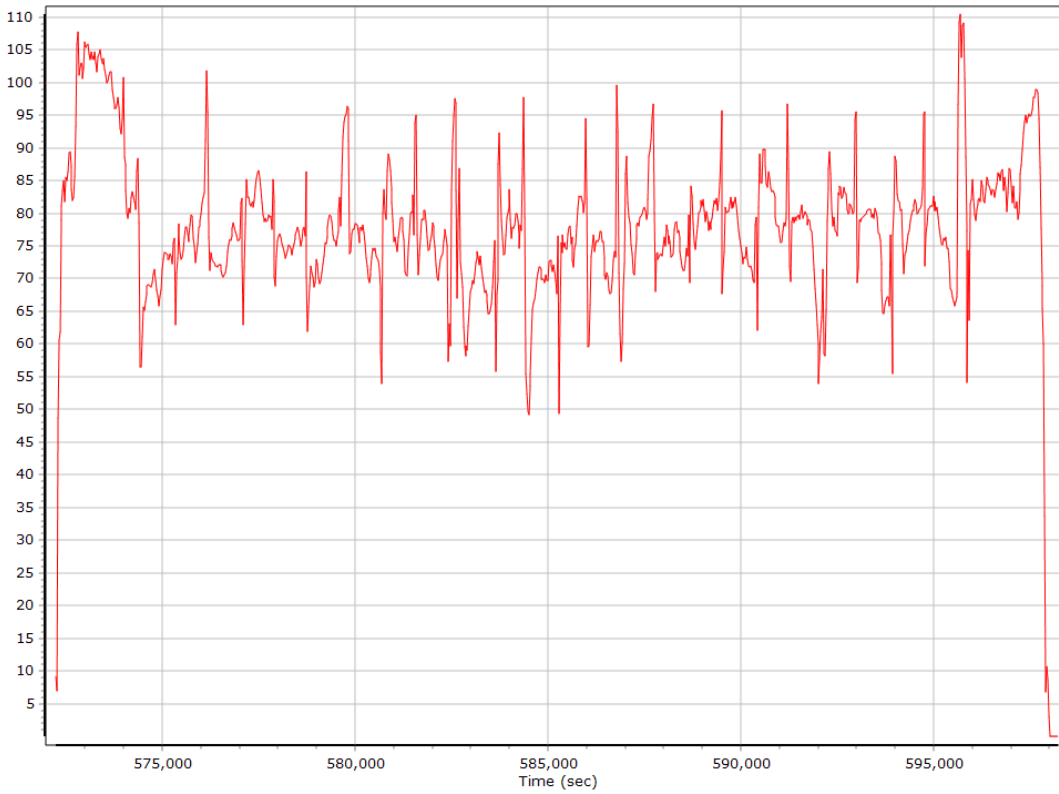
North/East Velocity



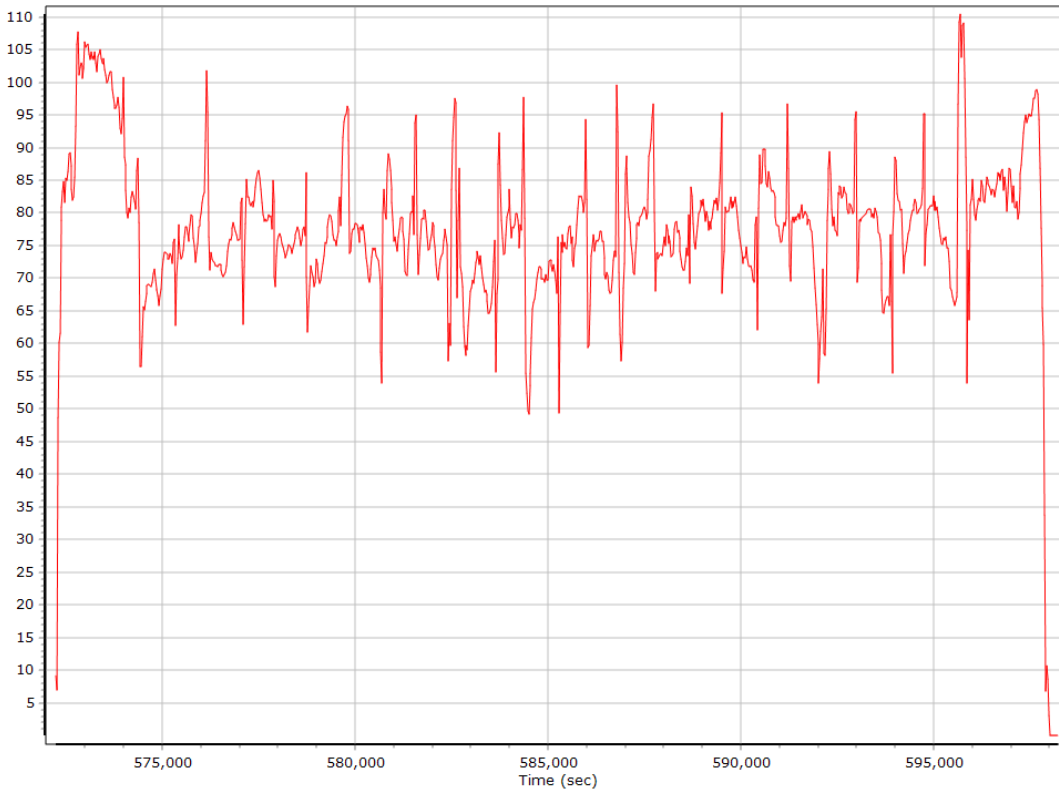
Down Velocity



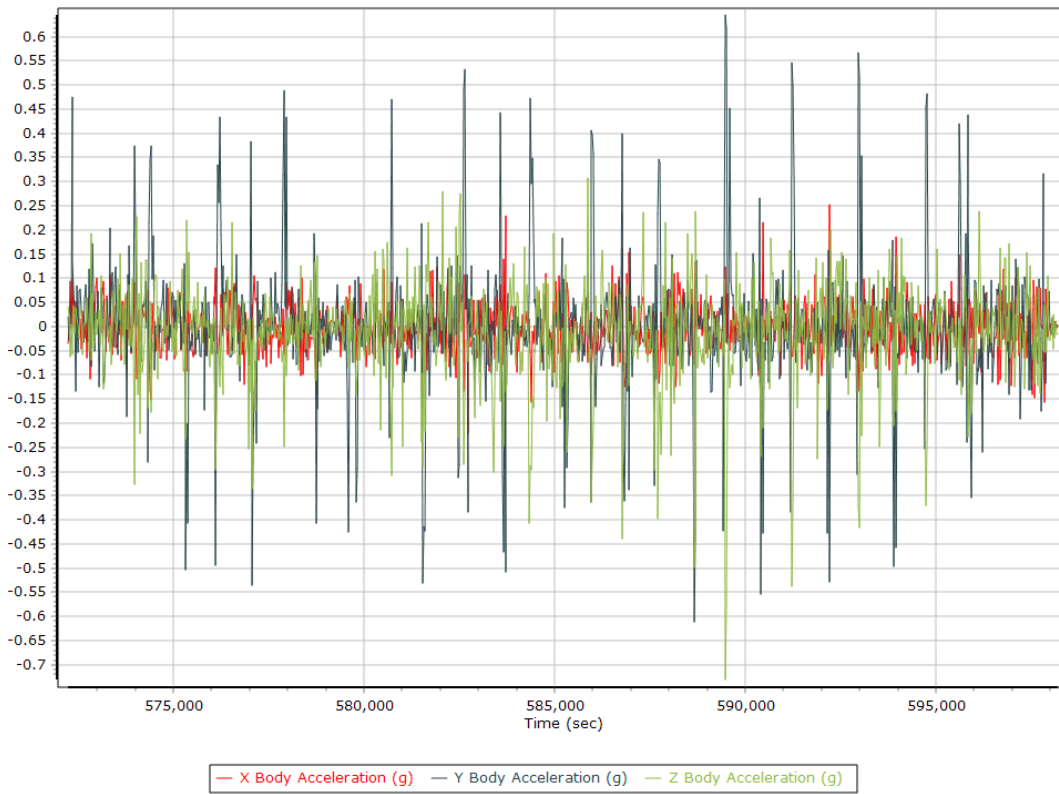
Total Speed



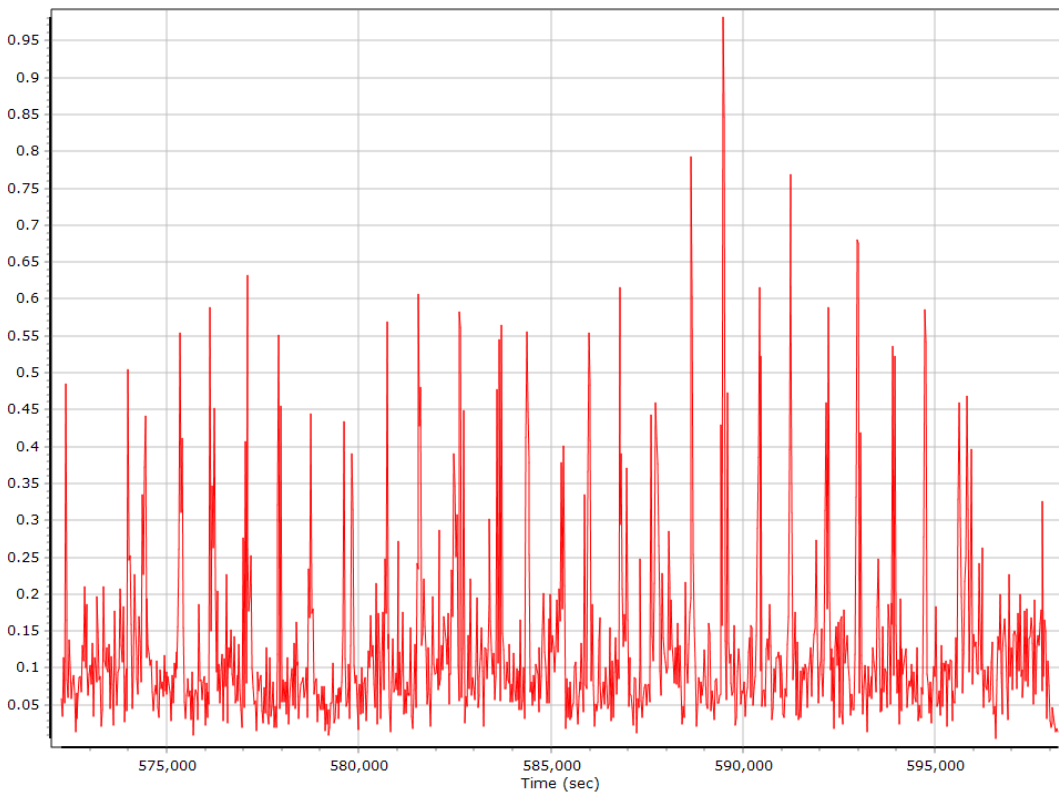
Ground Speed



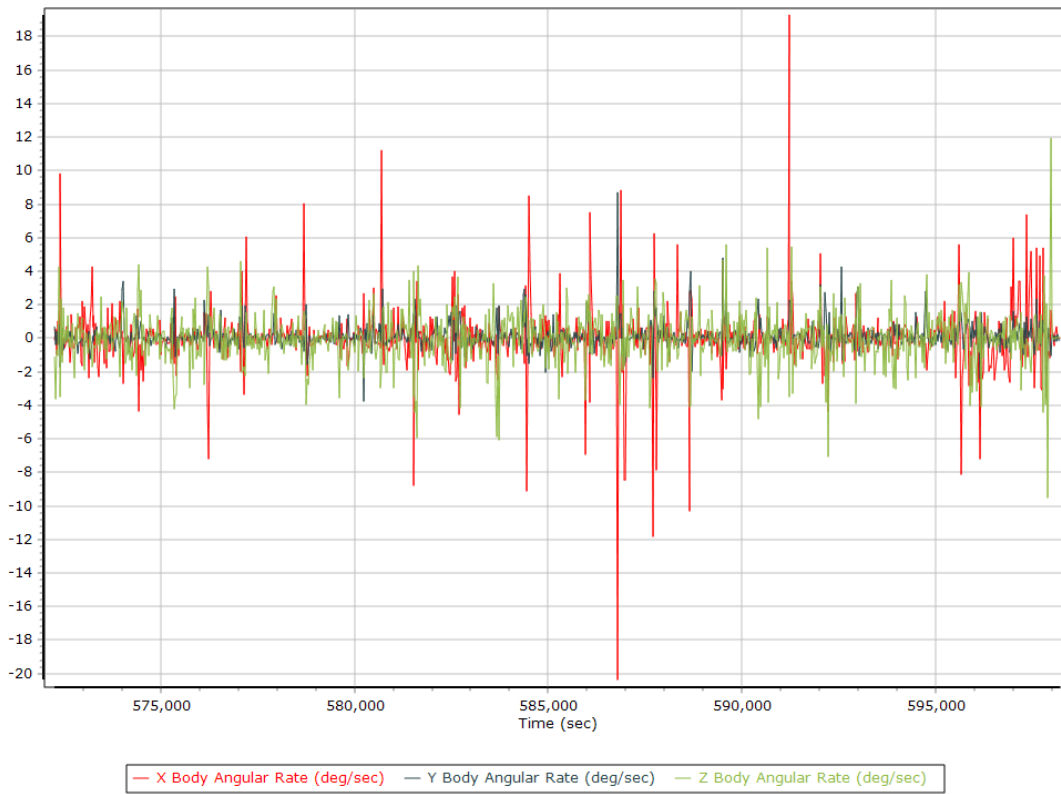
Body Acceleration



Total Body Acceleration

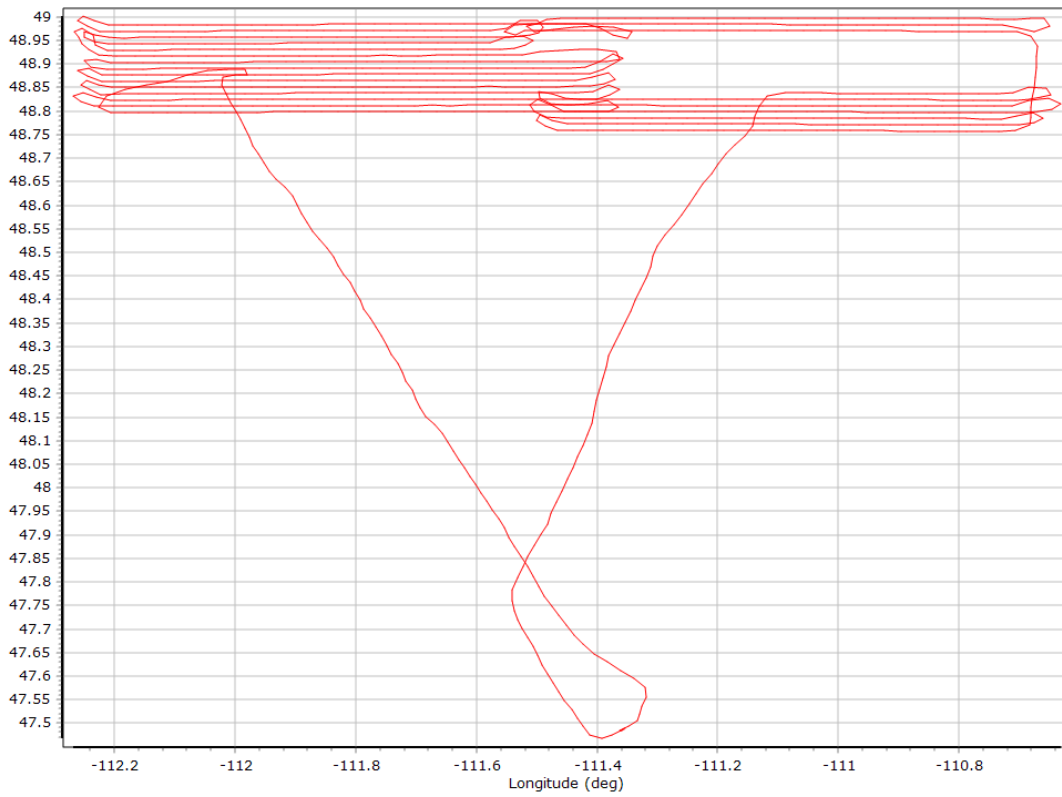


Body Angular Rate

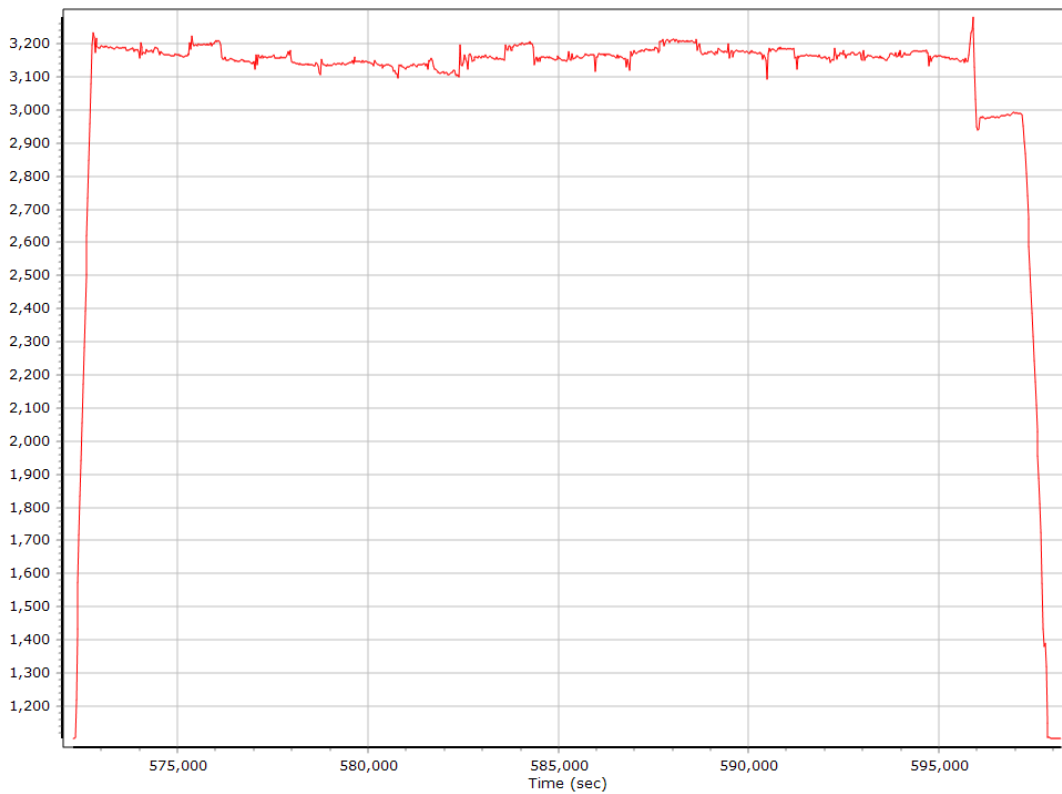


Forward Processed Trajectory Information

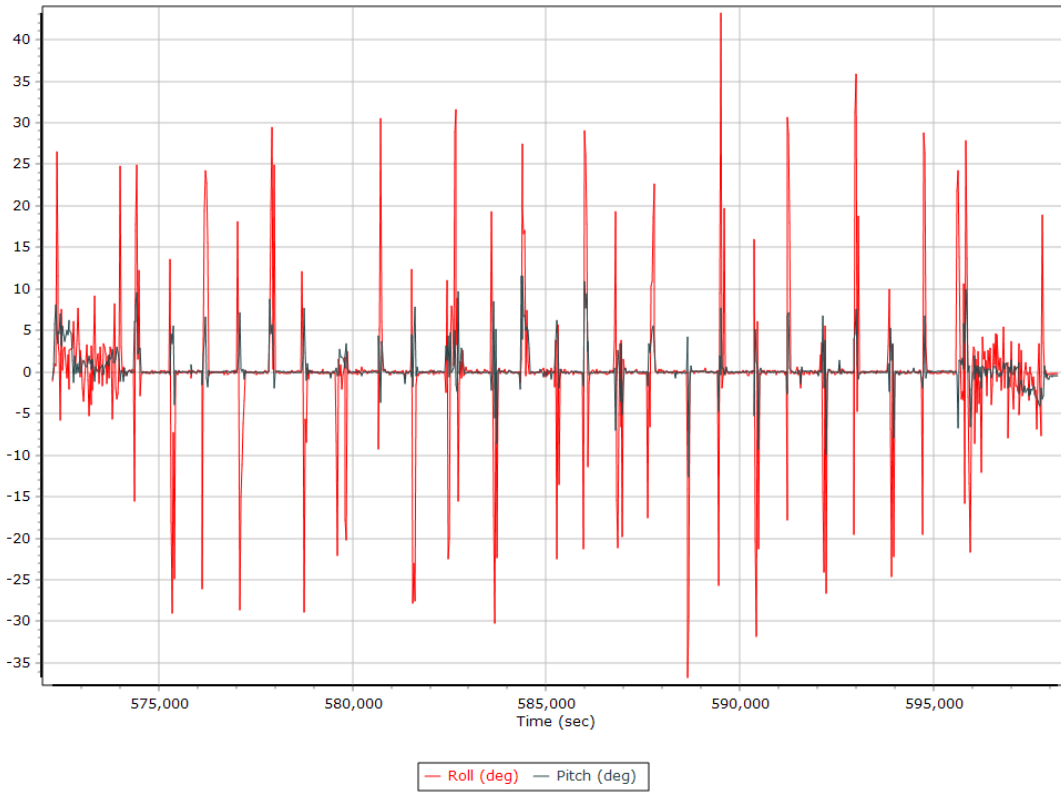
Top View



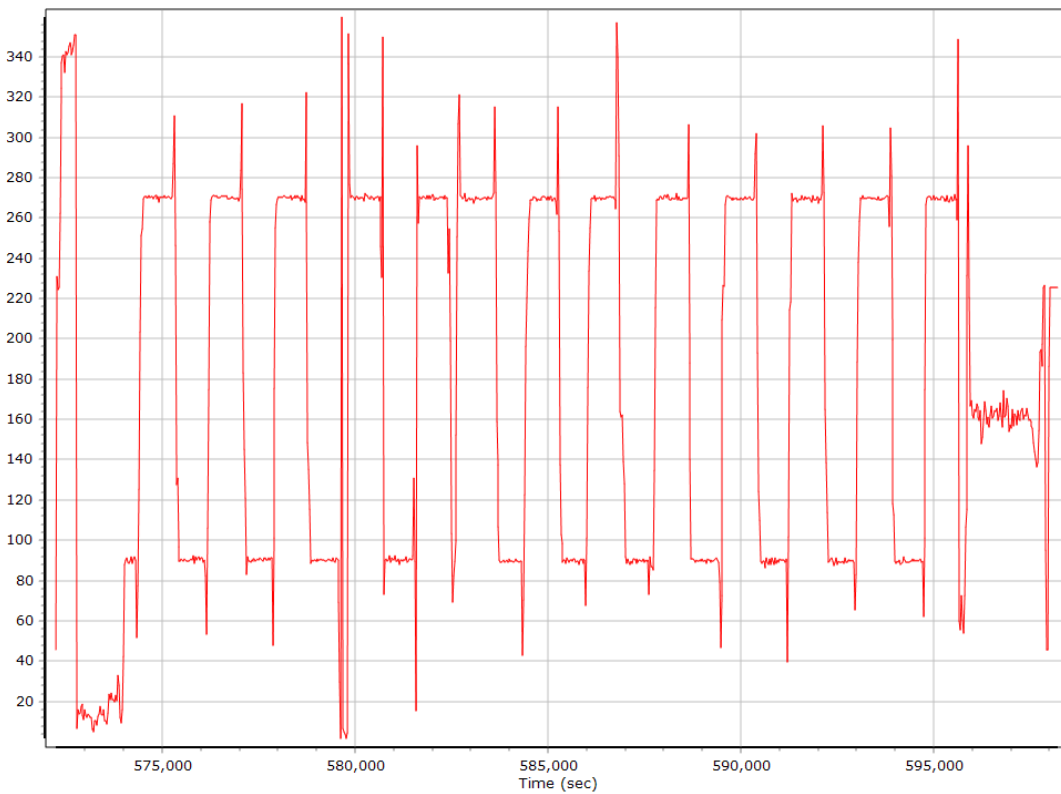
Altitude



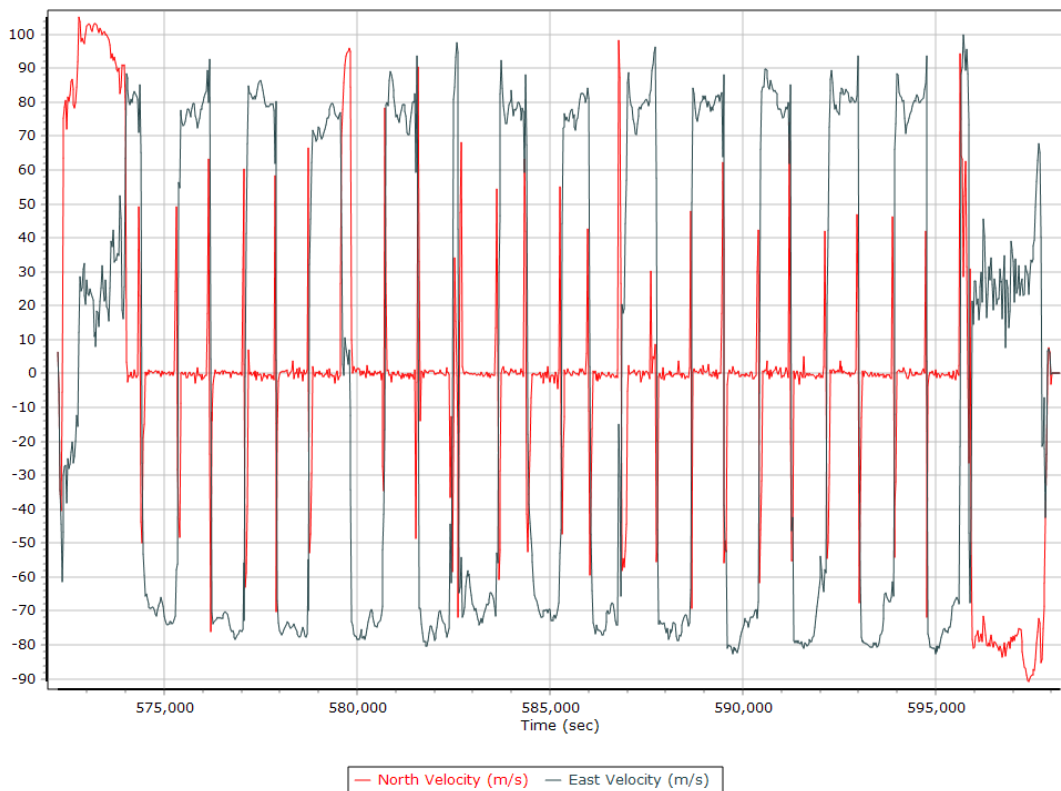
Roll/Pitch



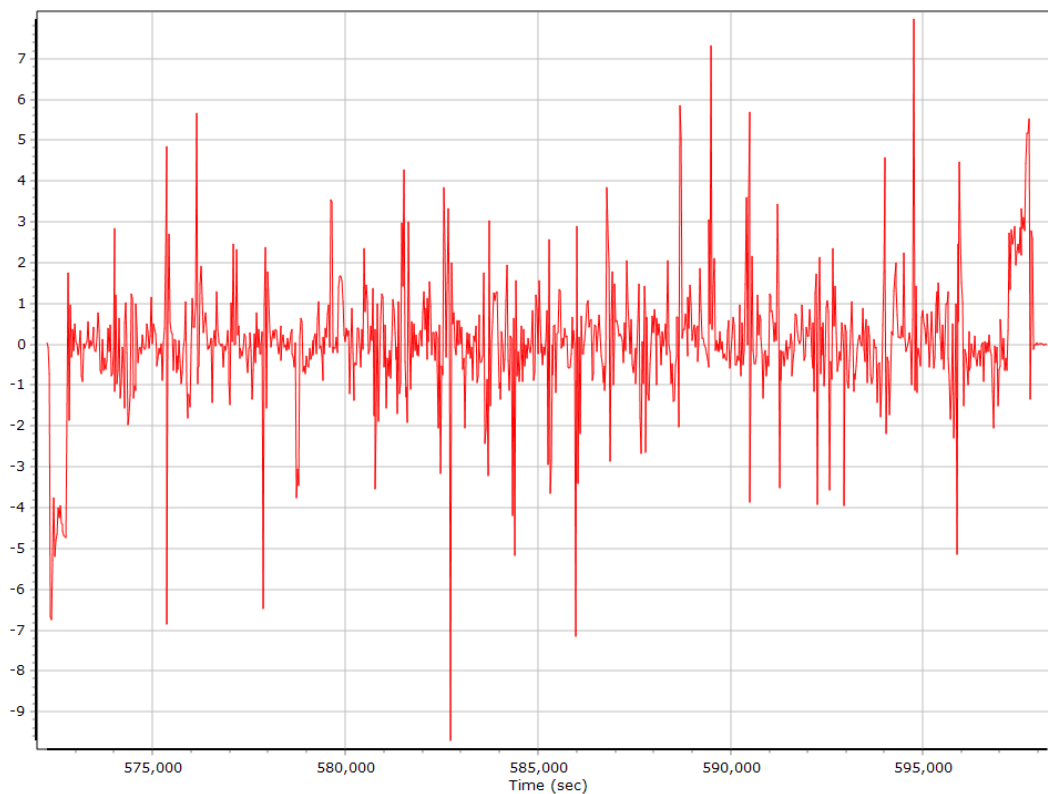
Heading



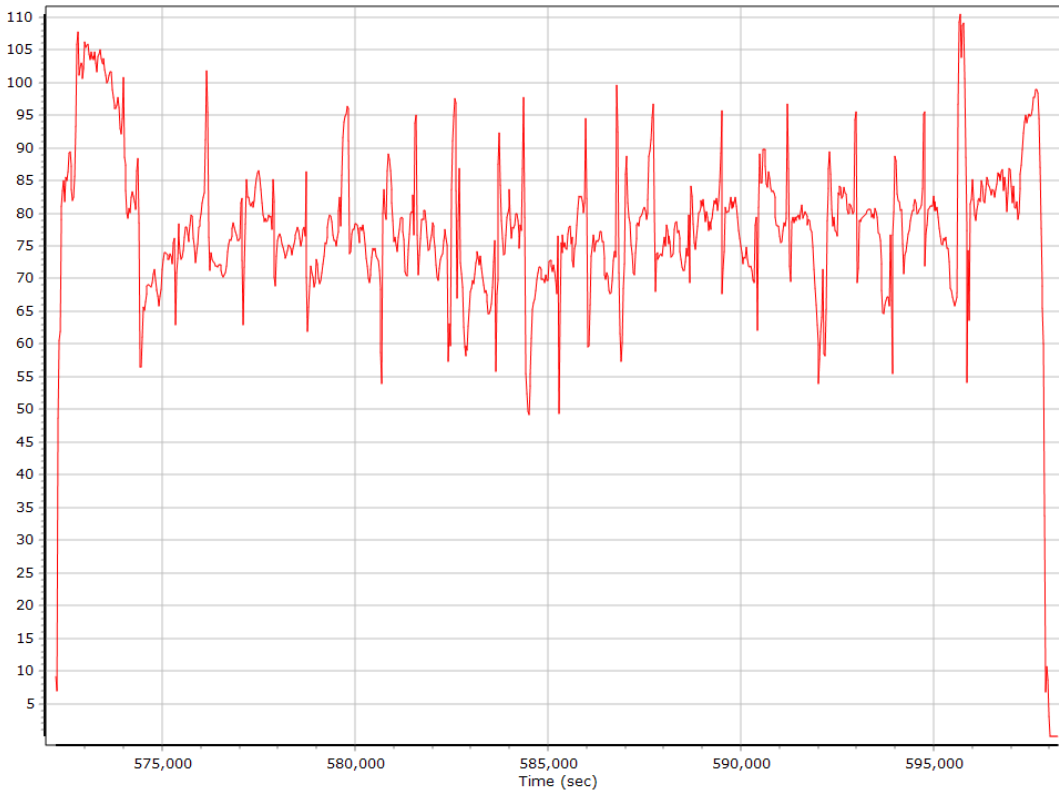
North/East Velocity



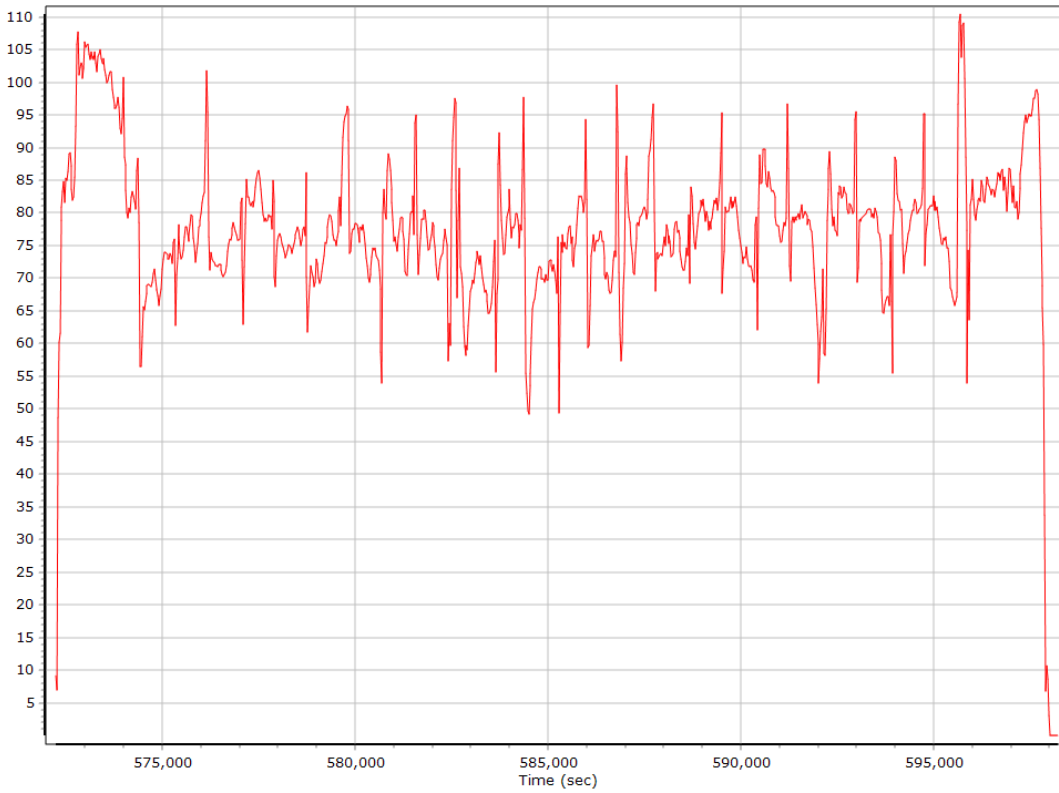
Down Velocity



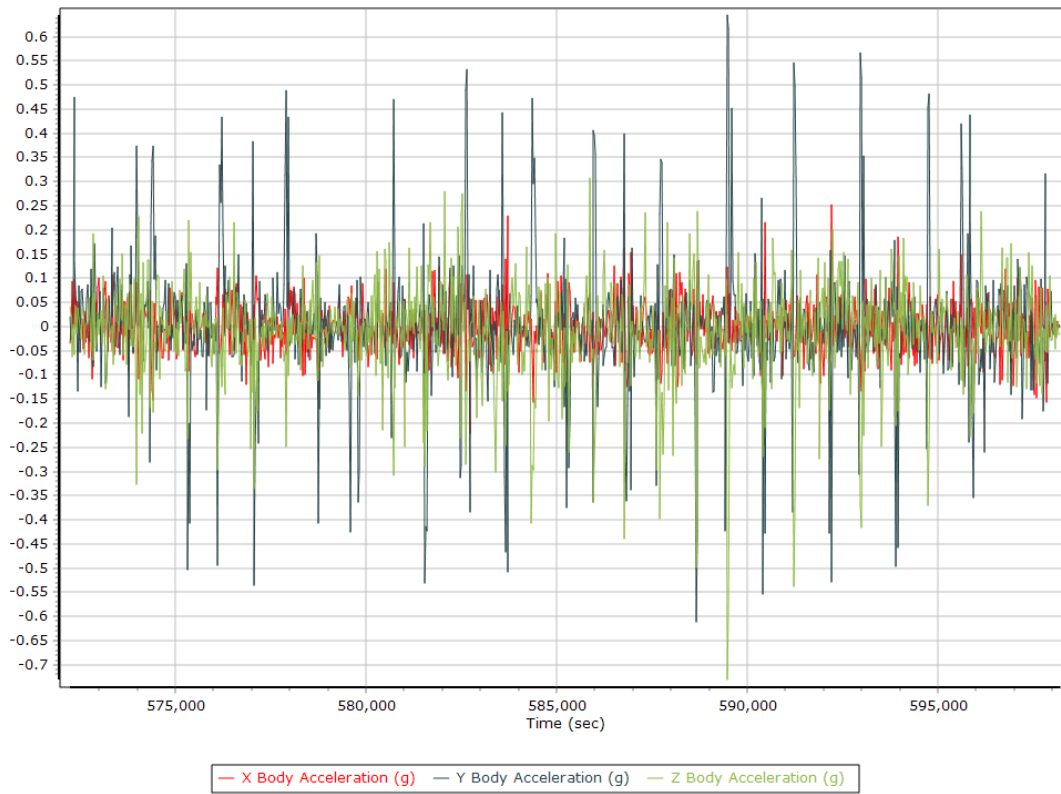
Total Speed



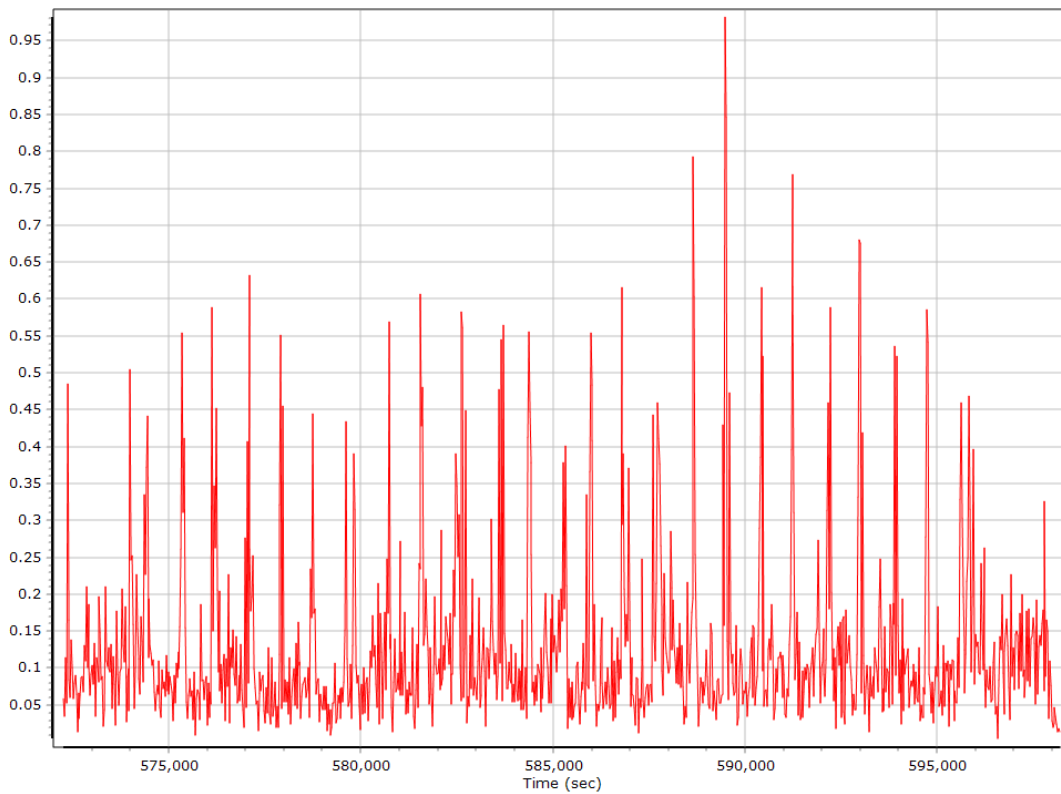
Ground Speed



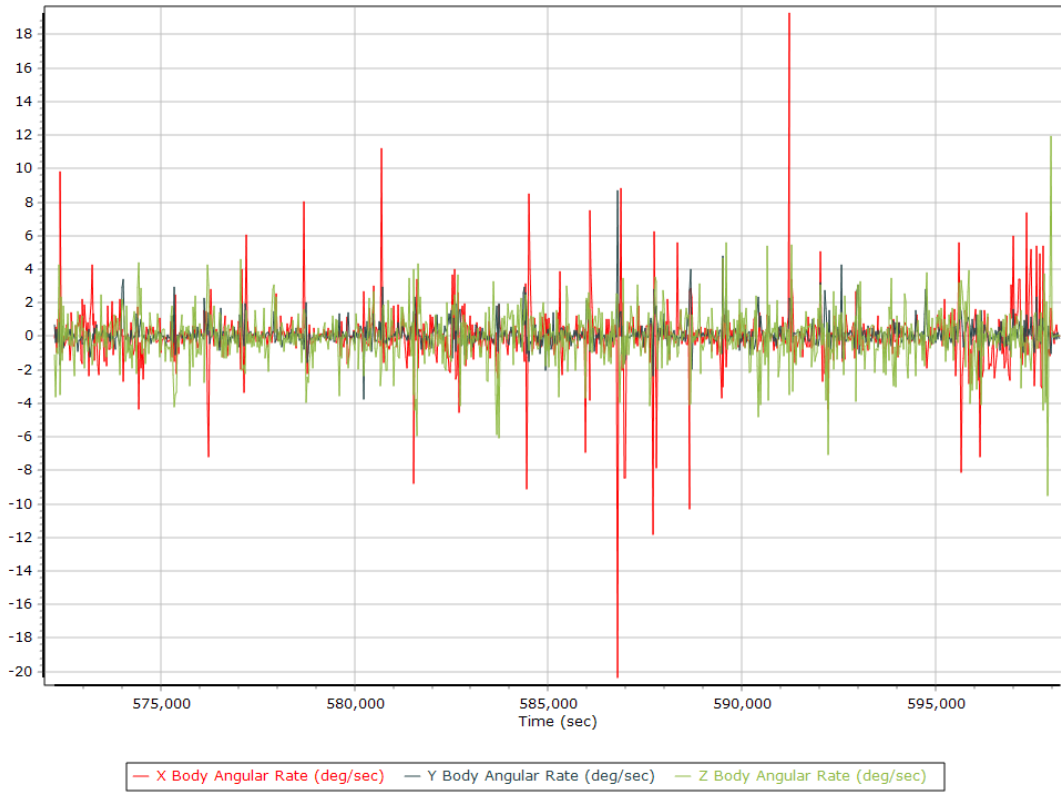
Body Acceleration



Total Body Acceleration



Body Angular Rate



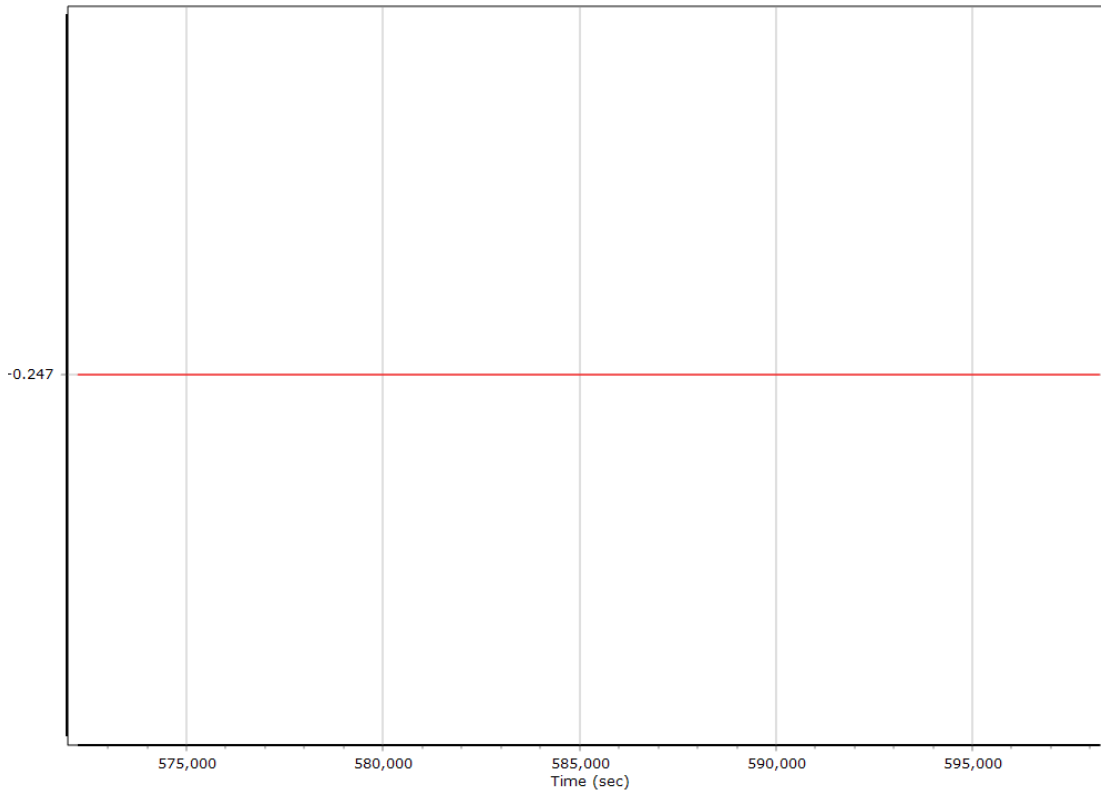
GNSS-Inertial Processor Configuration

Processing mode	No GNSS Aiding		
Stabilized mount	True		
Processing start time	572191.001 (1/12/1980 2:56:31 PM)		
Processing end time	598225.862 (1/12/1980 10:10:25 PM)		
Initial attitude source	GYRO Compass		
IMU Sensor Context	Processing with Onboard IMU		
Gimbal to IMU lever arm (m)	0.000	0.000	0.000
Gimbal to IMU mounting angles (deg)	0.000	0.000	0.000
Gimbal to Primary GNSS lever arm (m)	-0.250	-0.028	-1.296
Gimbal to Primary GNSS lever arm std dev (m)	0.030	0.030	0.030
Vehicle to Reference mounting angles (deg)	0.000	0.000	0.000

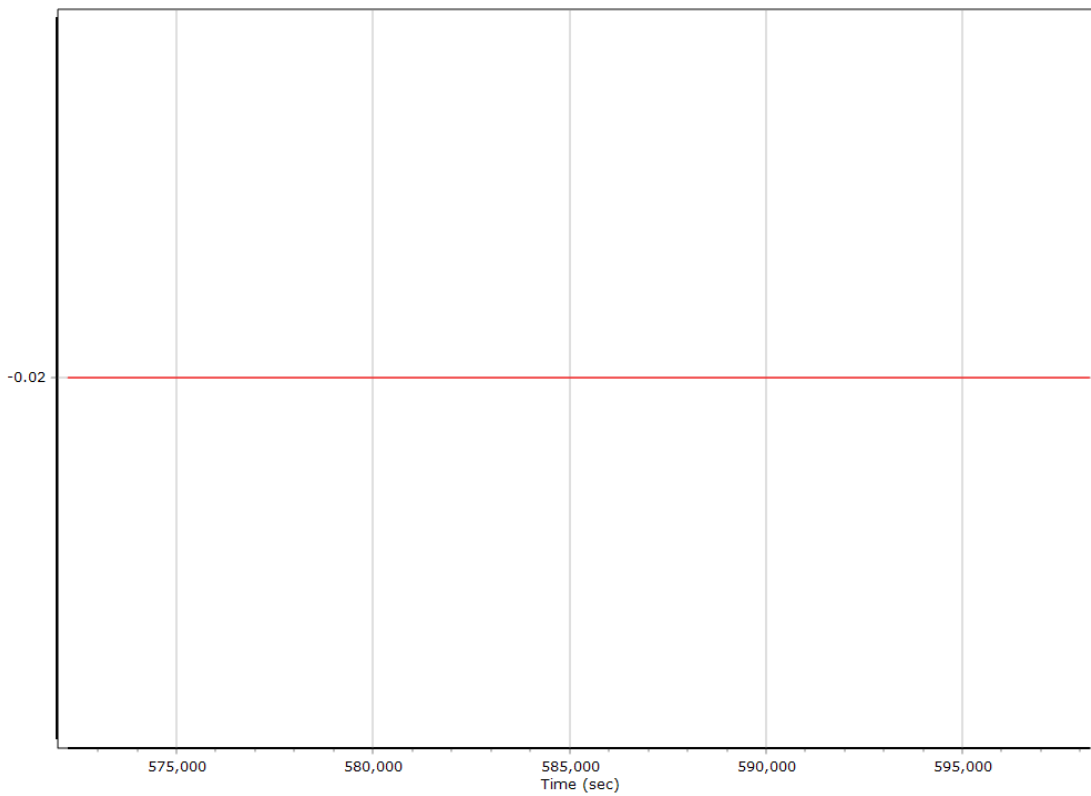
Calibrated Installation Parameters

Reference-Primary GNSS Lever Arm (m)

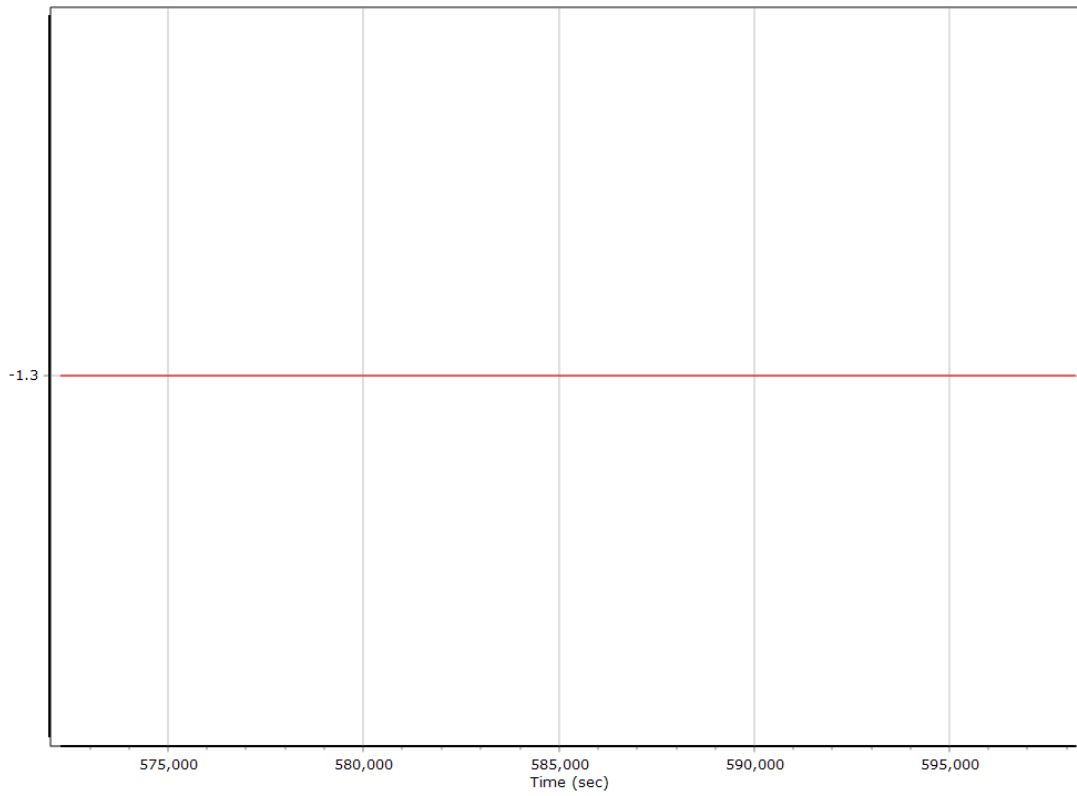
X Reference-Primary GNSS Lever Arm (m)



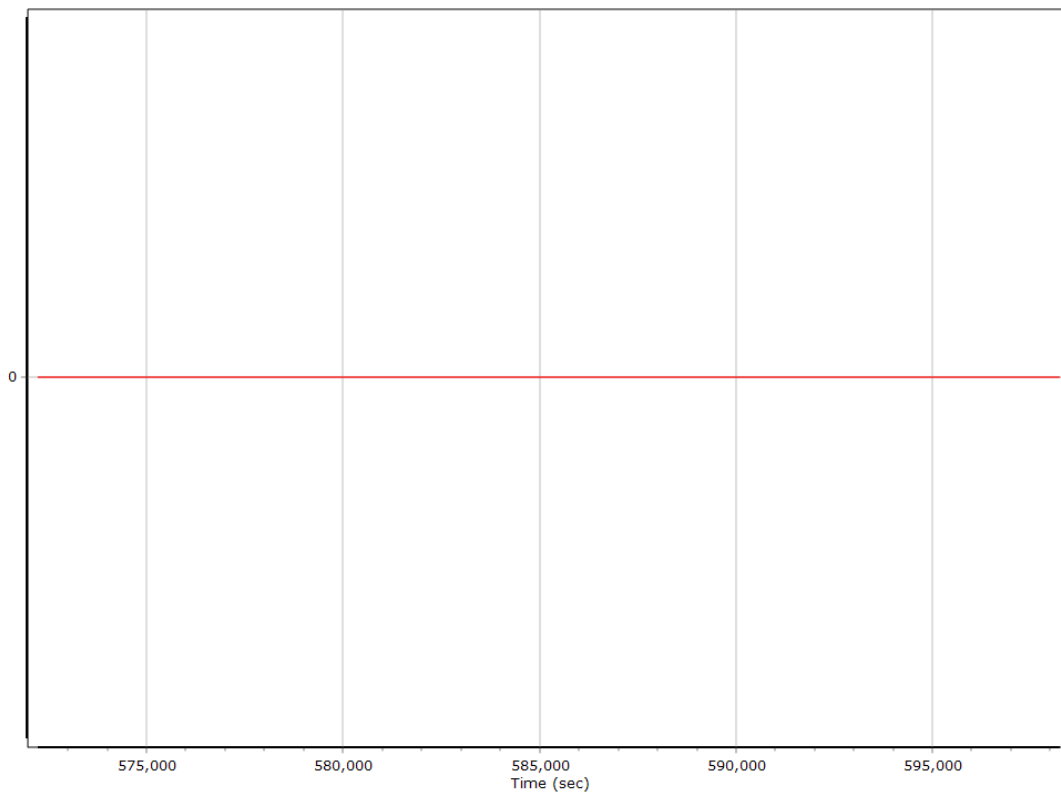
Y Reference-Primary GNSS Lever Arm (m)



Z Reference-Primary GNSS Lever Arm (m)



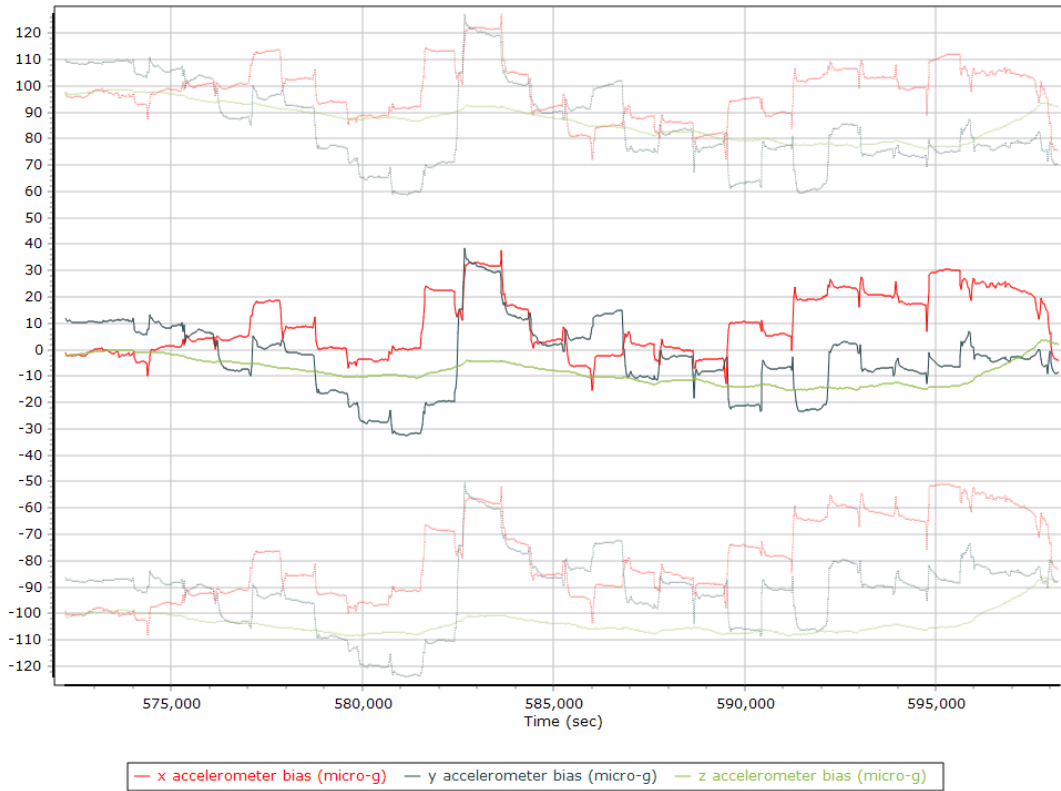
Reference-Primary GNSS Lever Arm Figure of Merit



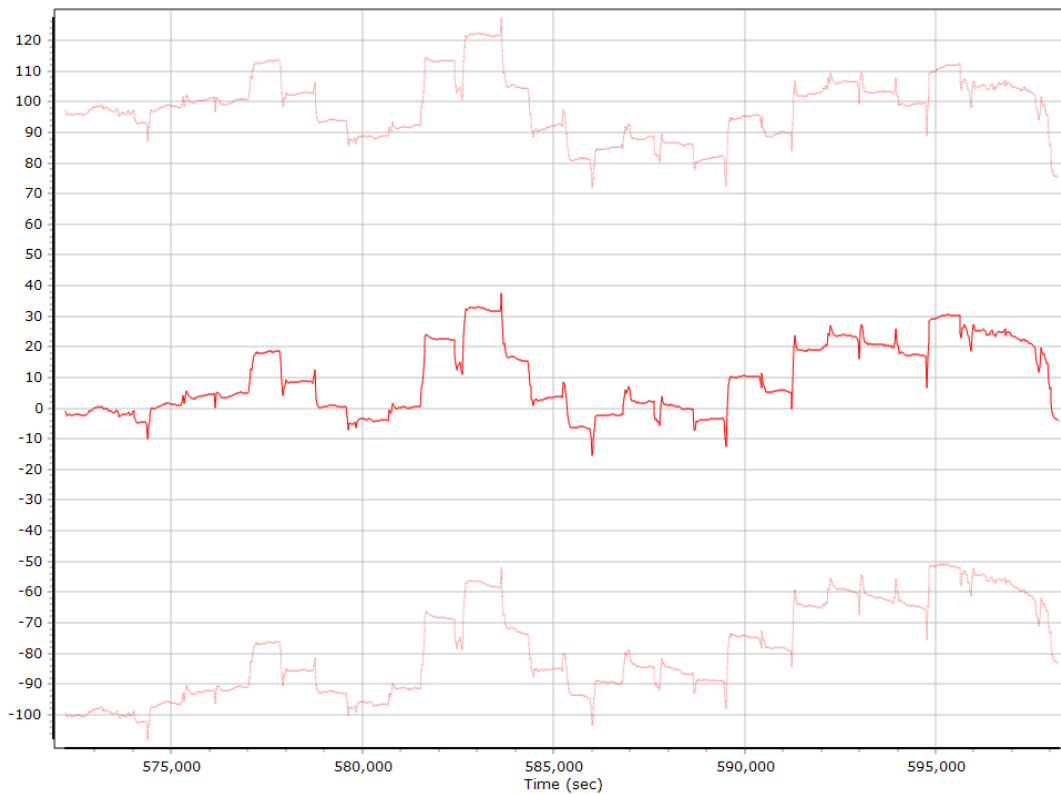
IN-Fusion QC

Forward Processed Estimated Errors, Reference Frame

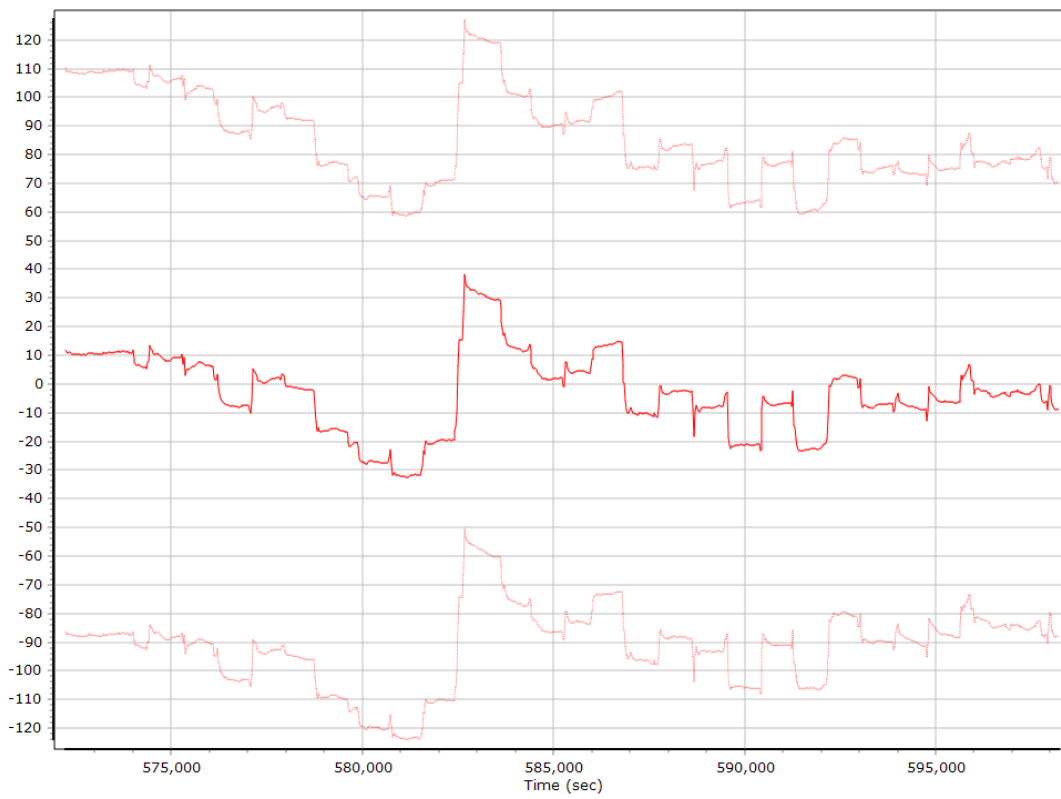
Accelerometer Bias (micro-g)



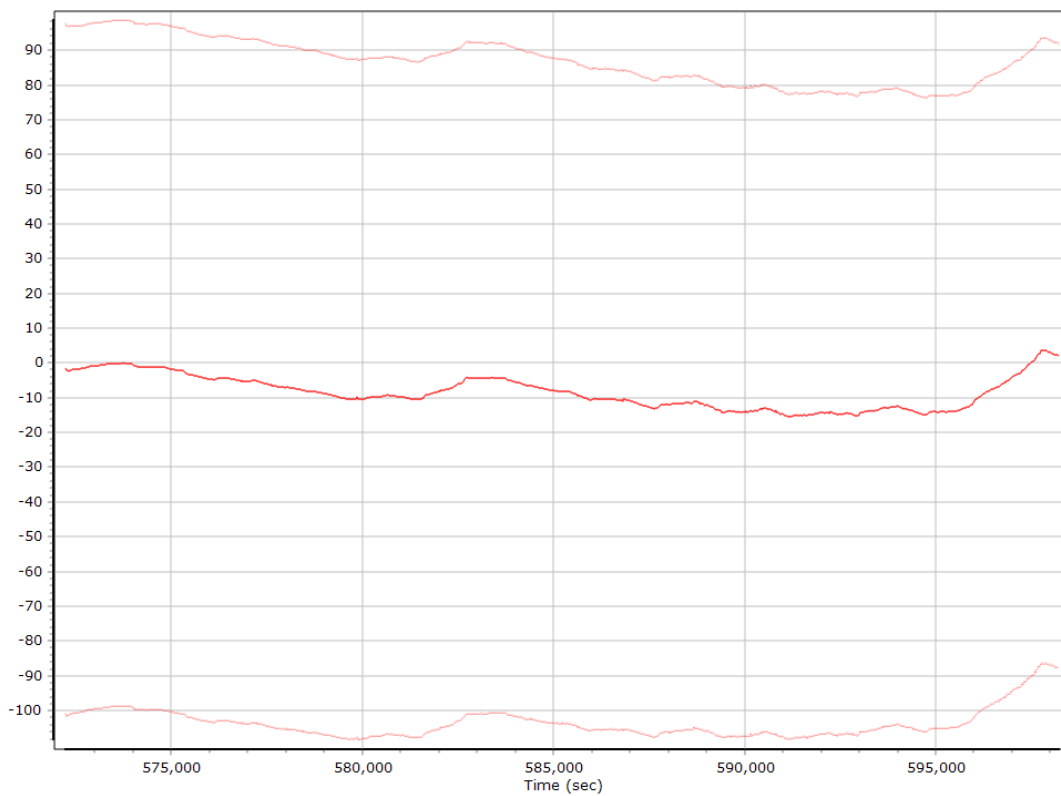
X Accelerometer Bias (micro-g)



Y Accelerometer Bias (micro-g)



Z Accelerometer Bias (micro-g)



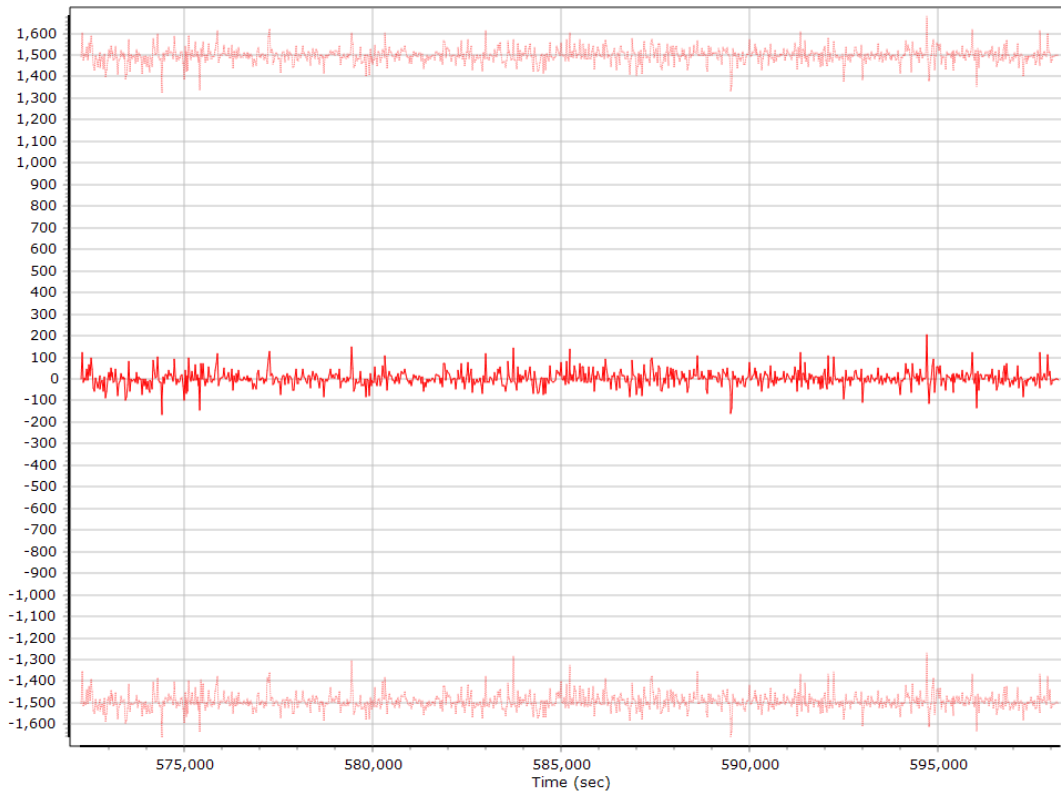
Accelerometer Scale Error (ppm)



X Accelerometer Scale Error (ppm)



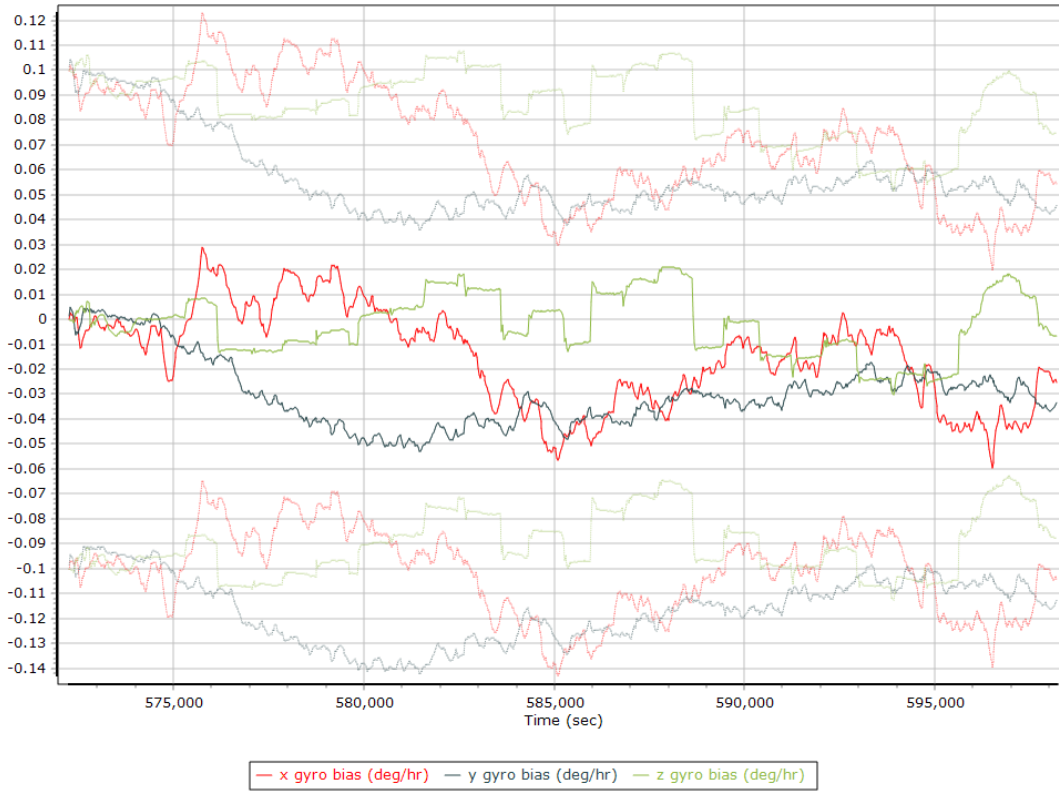
Y Accelerometer Scale Error (ppm)



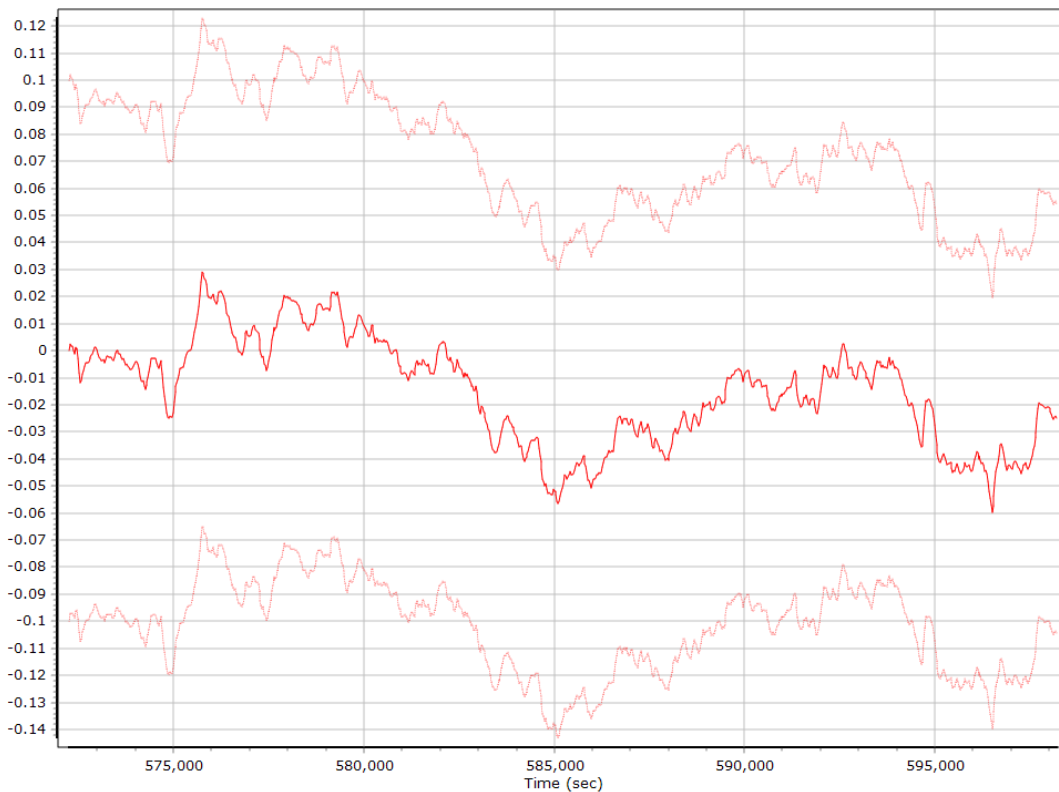
Z Accelerometer Scale Error (ppm)



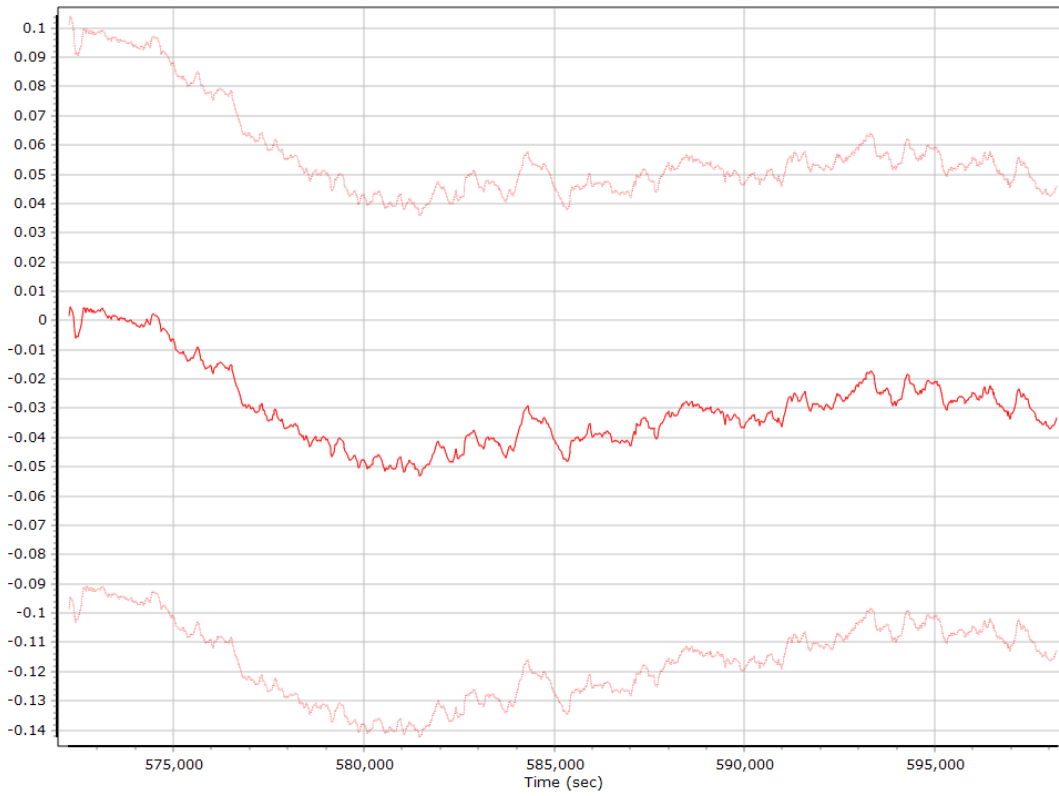
Gyro Bias (deg/h)



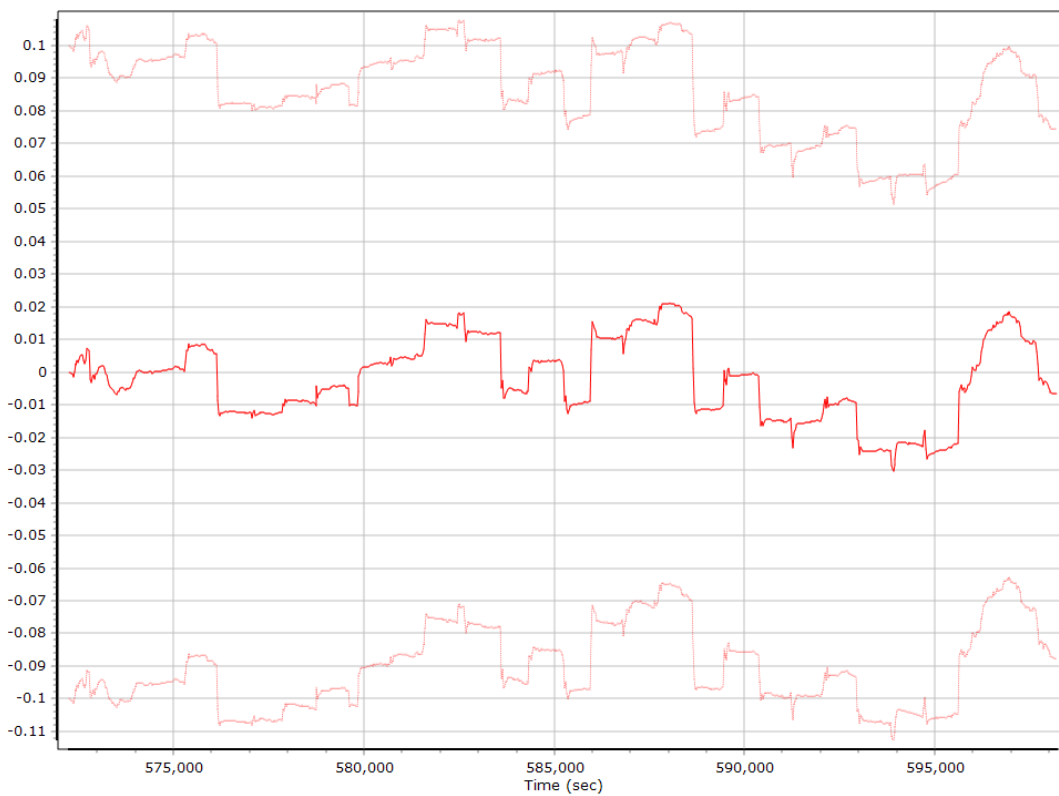
X Gyro Bias (deg/h)



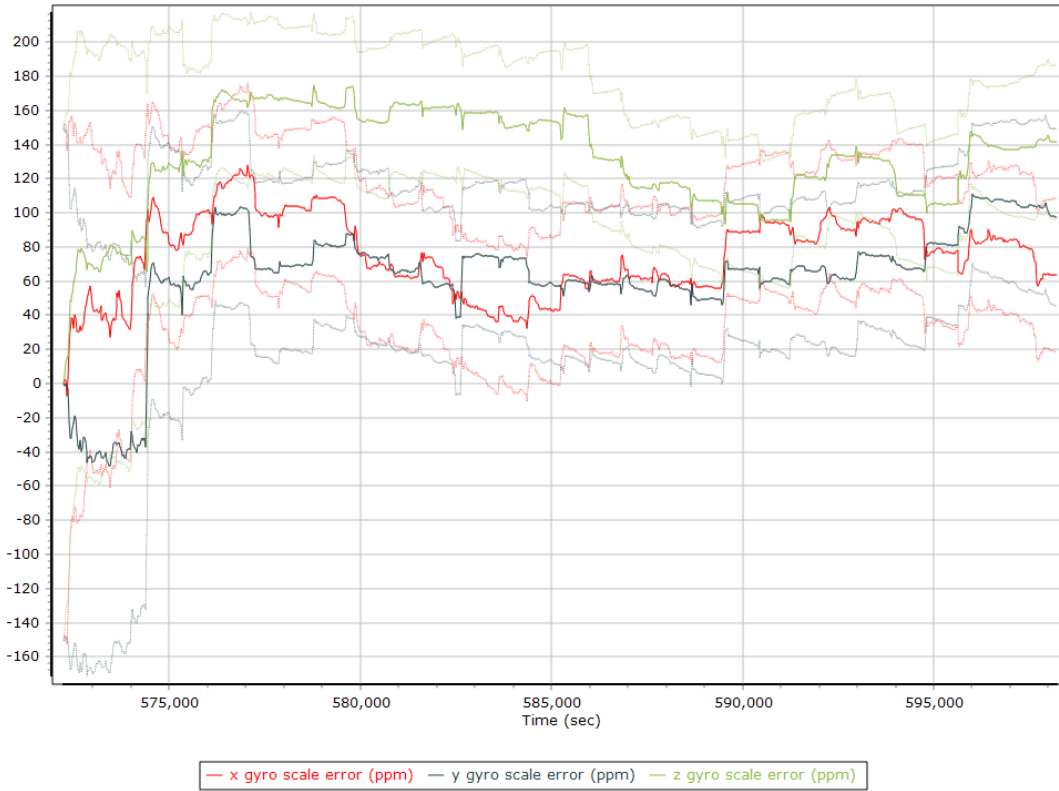
Y Gyro Bias (deg/h)



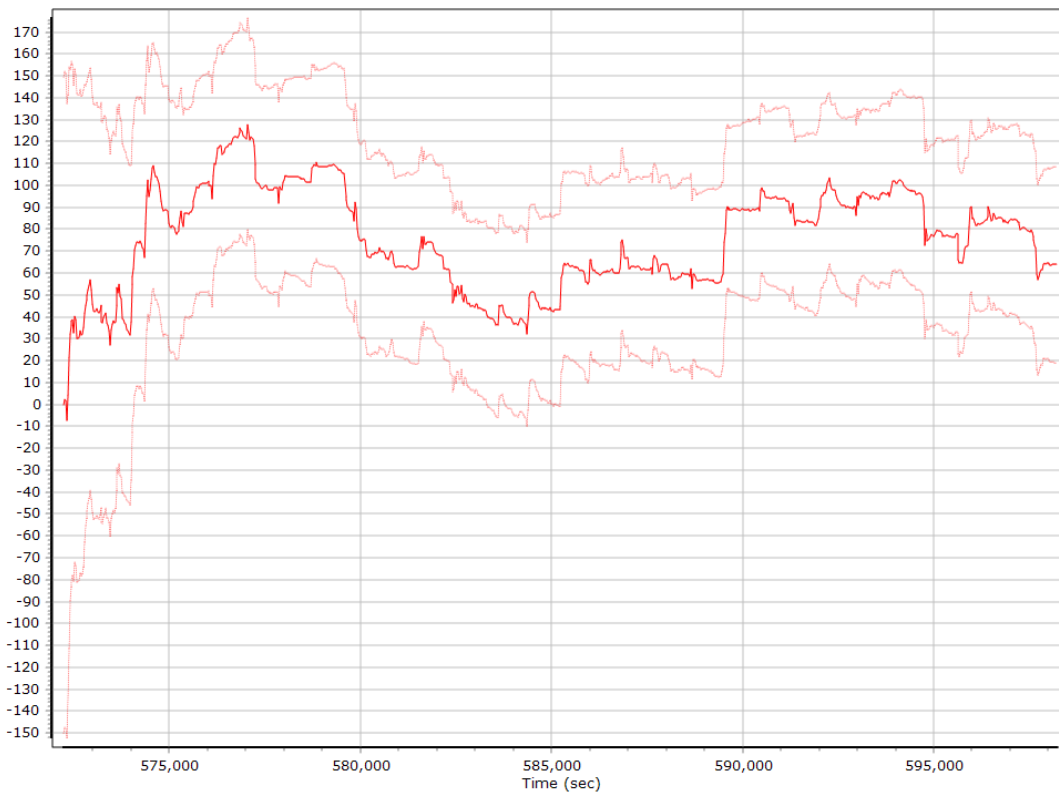
Z Gyro Bias (deg/h)



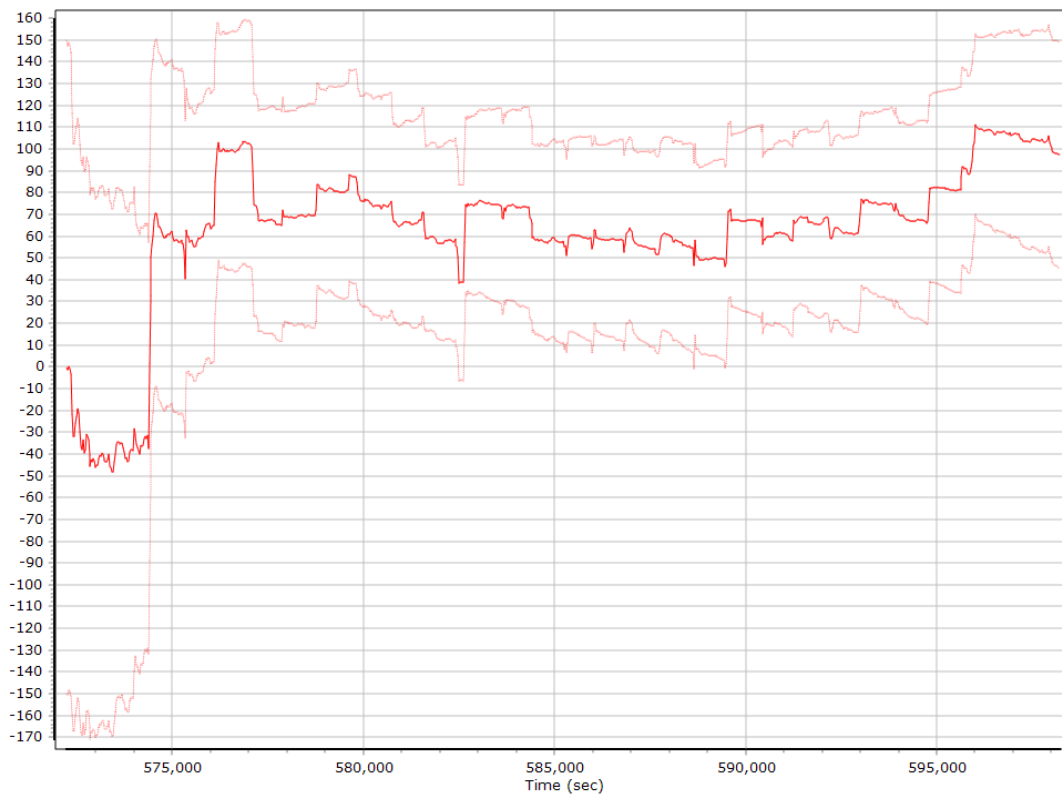
Gyro Scale Error (ppm)



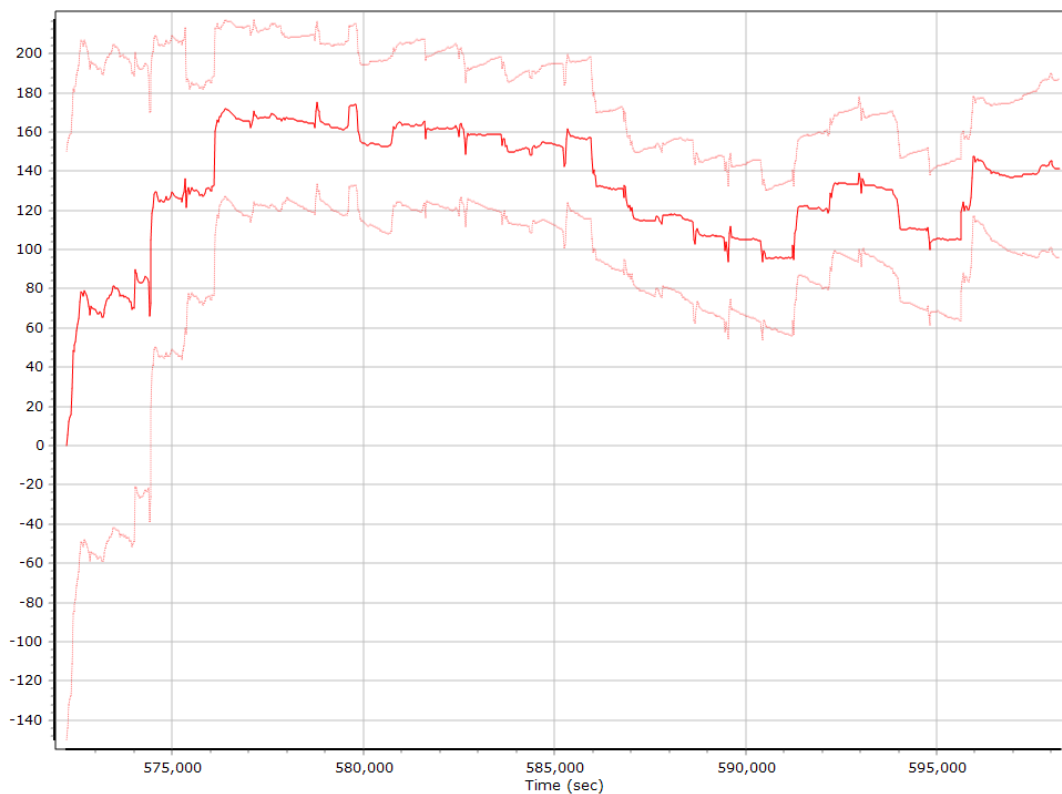
X Gyro Scale Error (ppm)



Y Gyro Scale Error (ppm)

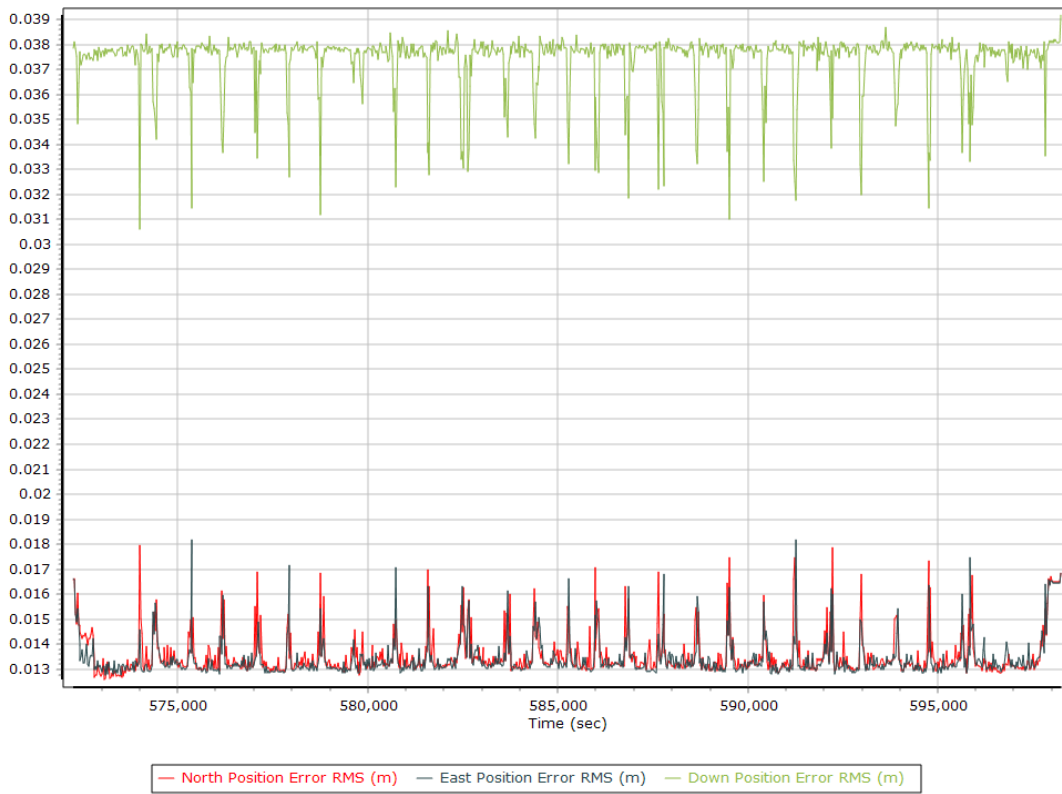


Z Gyro Scale Error (ppm)

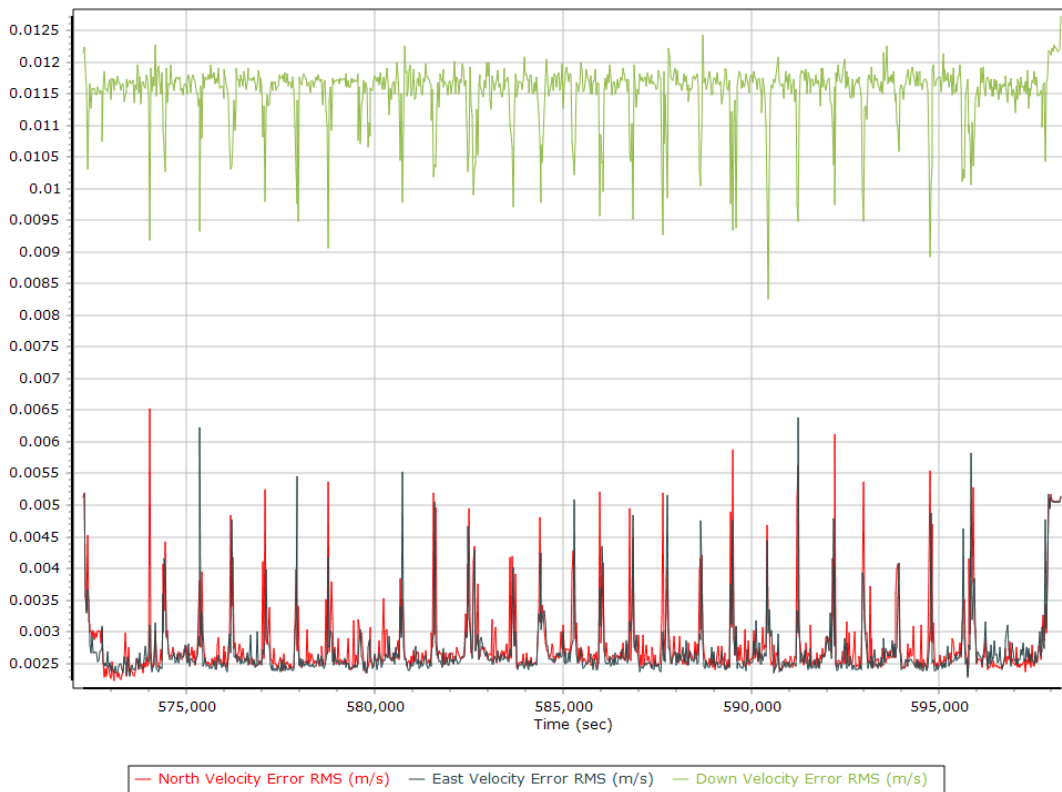


Smoothed Performance Metrics

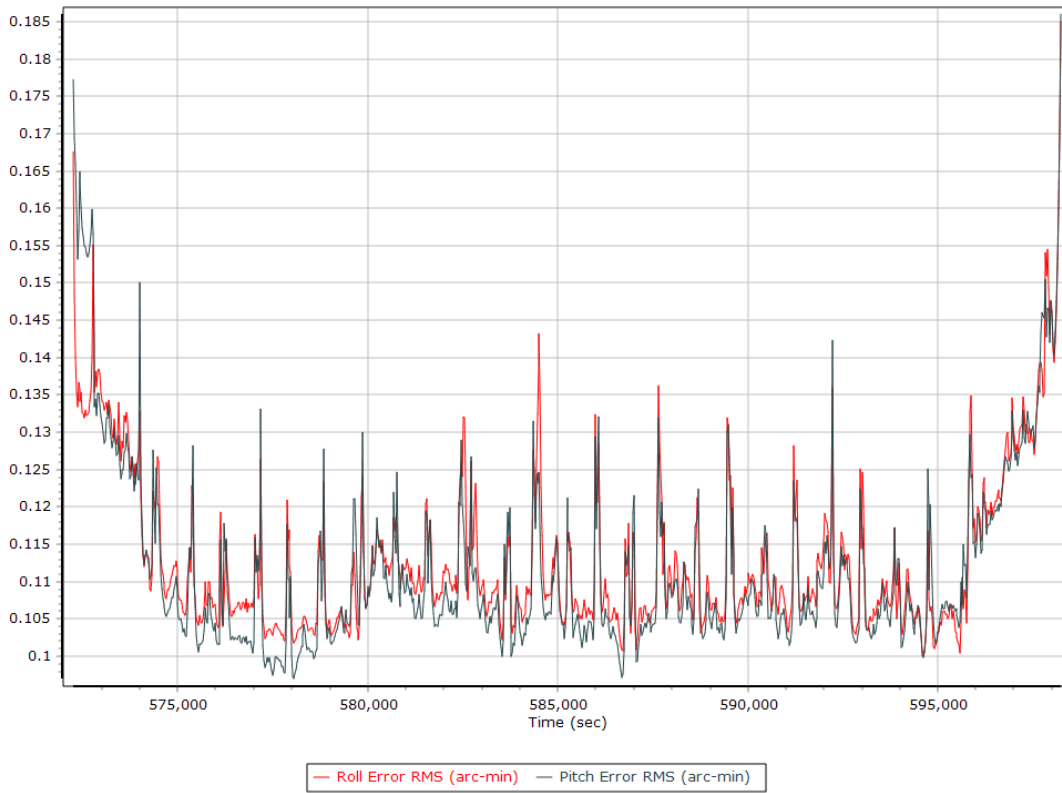
Position Error RMS (m)



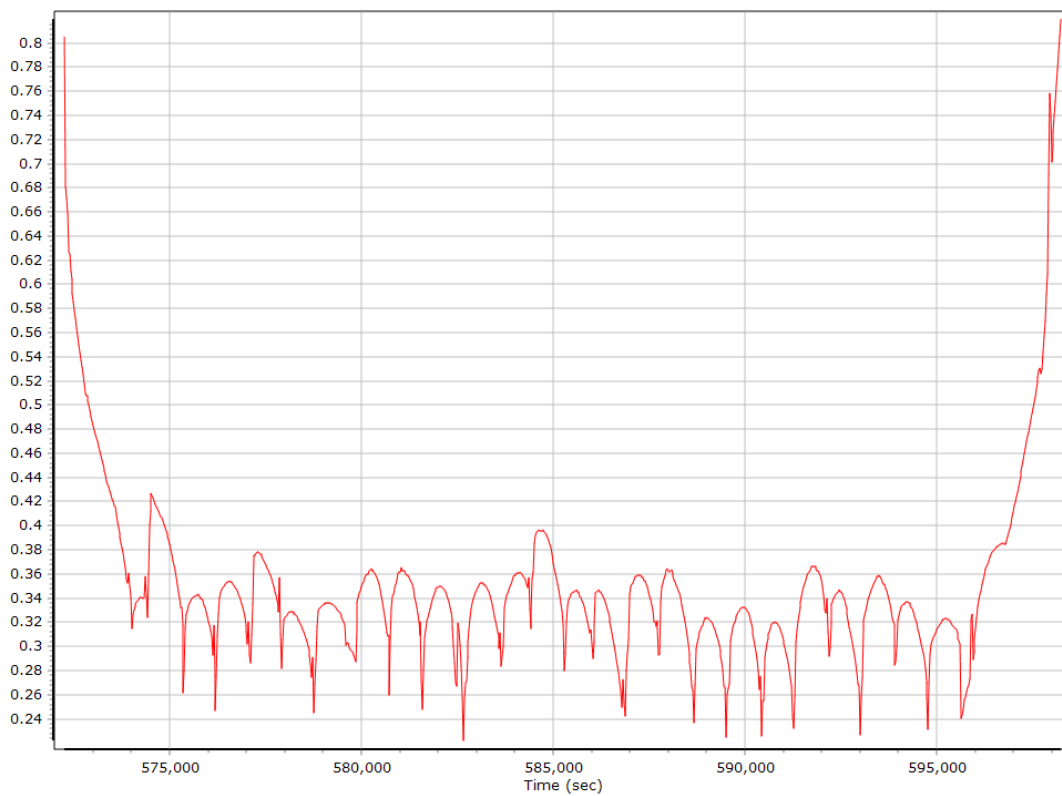
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

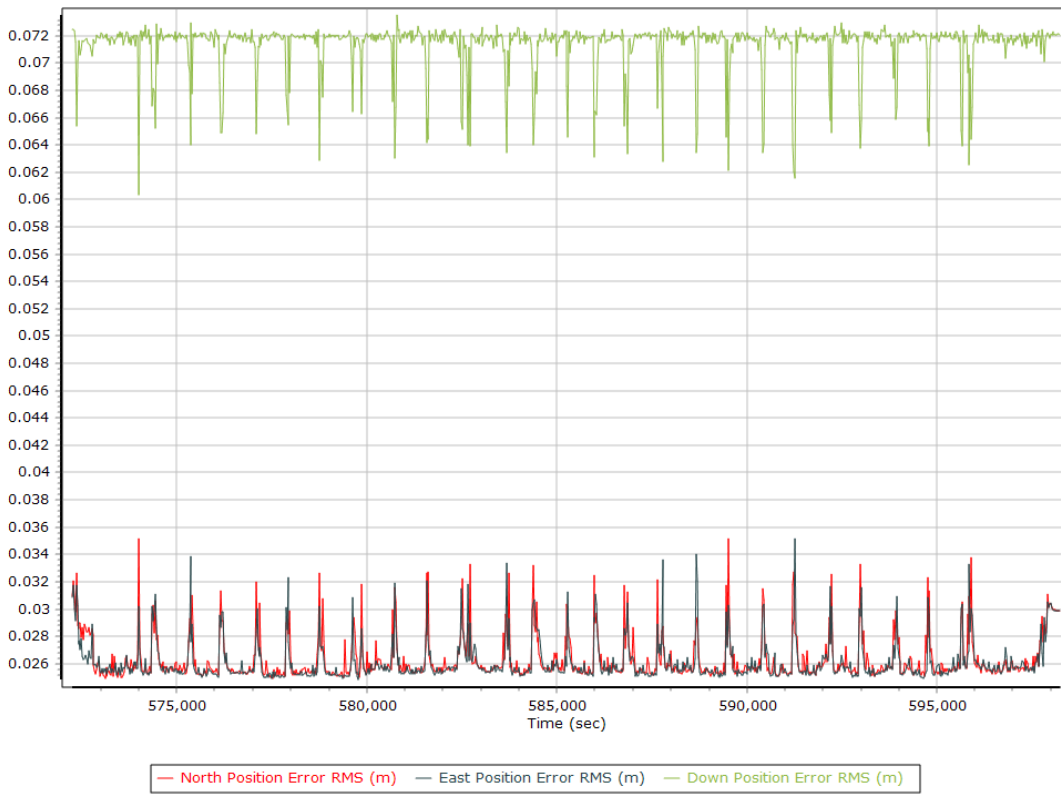


Heading Error RMS (arc-min)

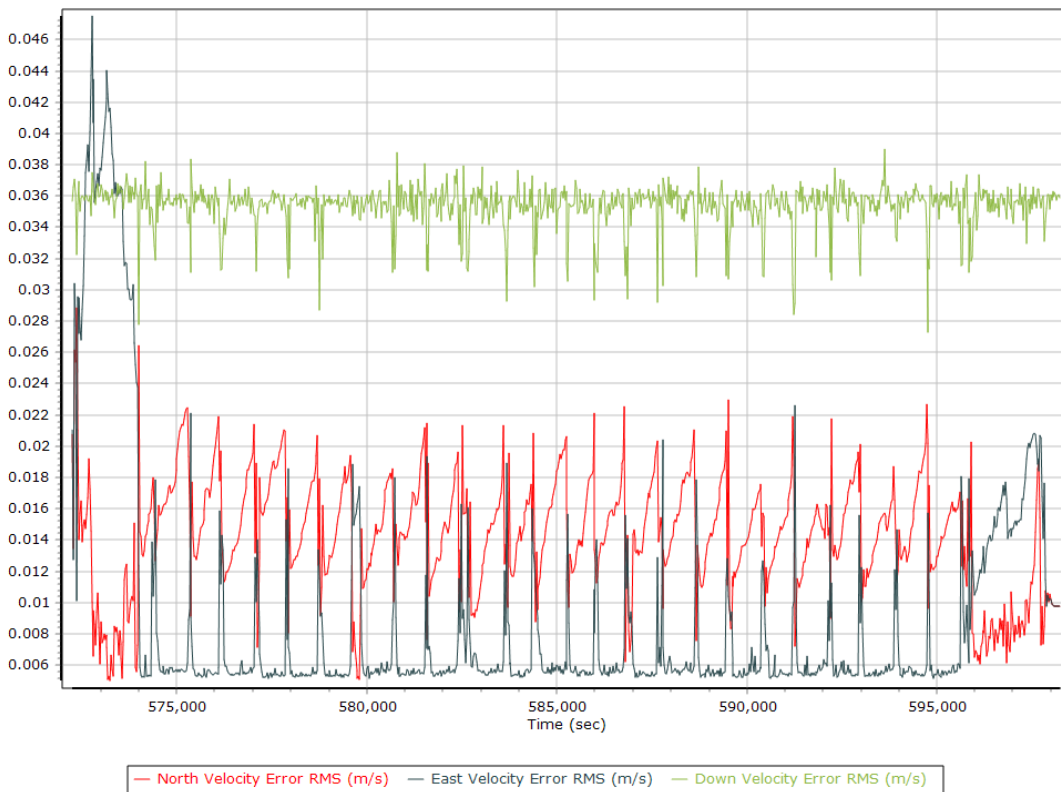


Forward Processed Performance Metrics

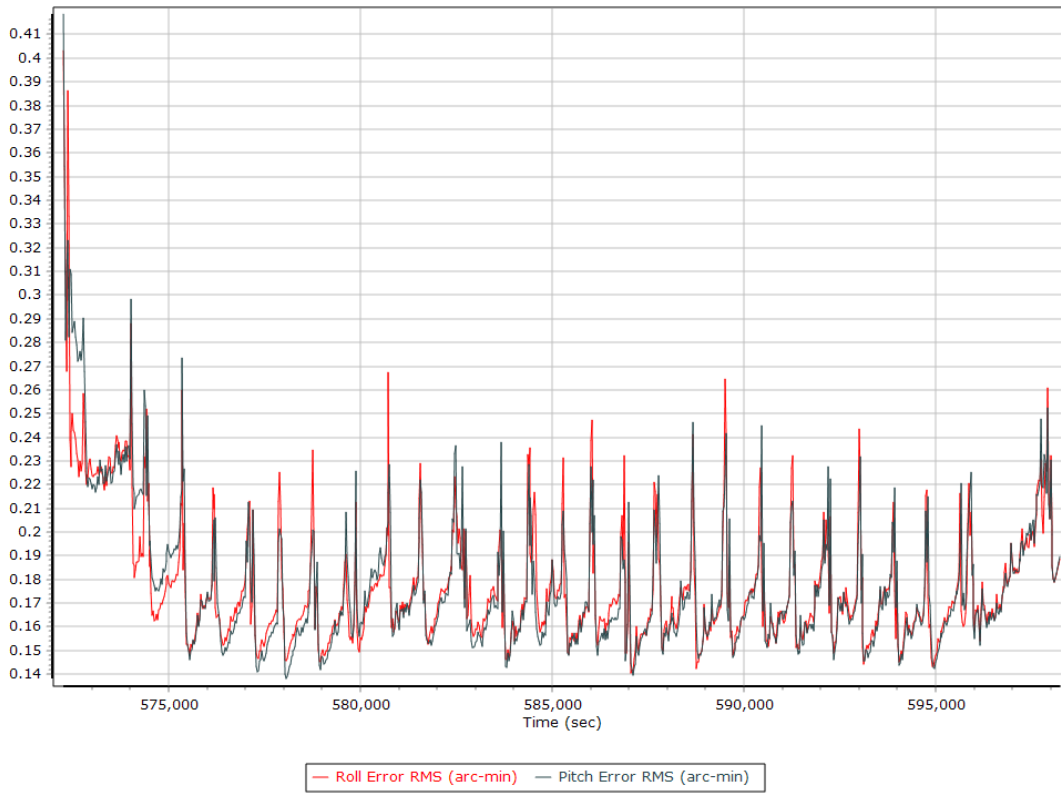
Position Error RMS (m)



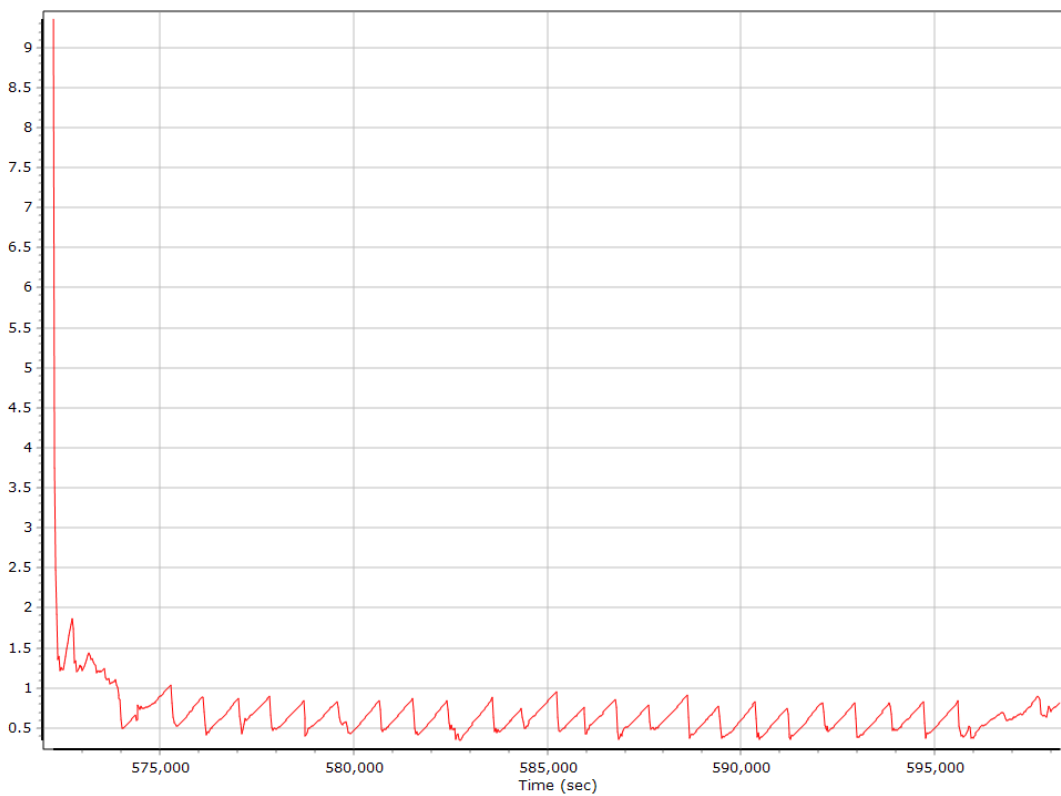
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

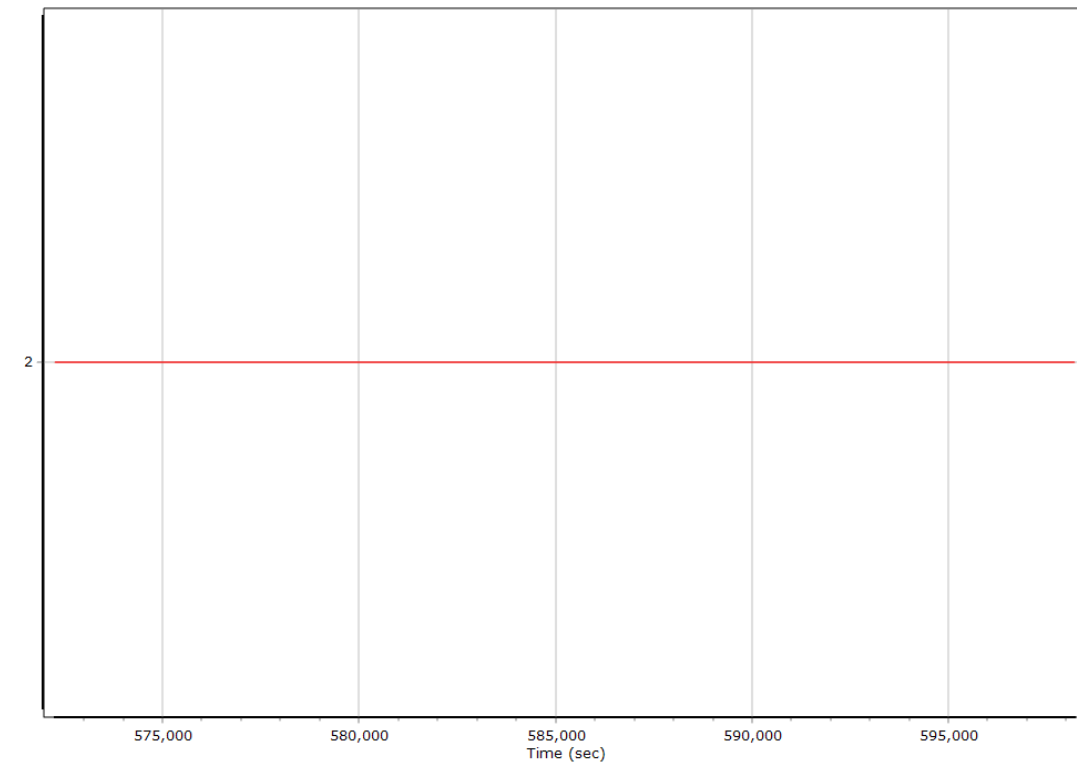


Heading Error RMS (arc-min)



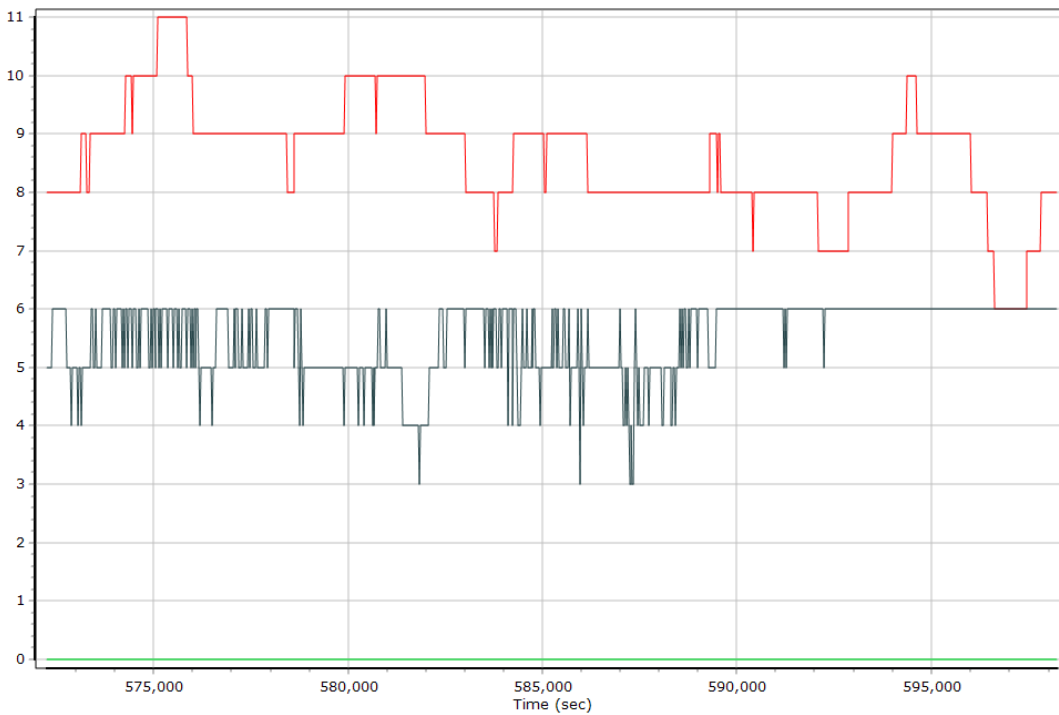
Forward Processed Solution Status

Processing Mode



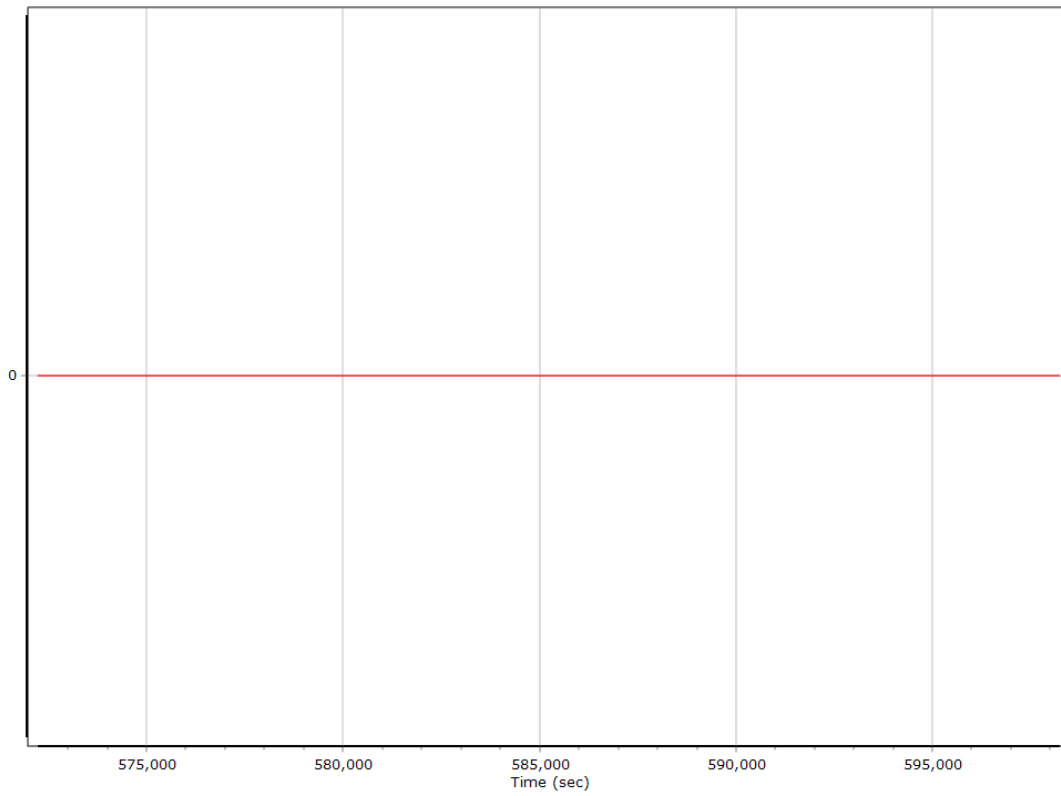
0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = C/A, 7 = GNSS Nav, 8 = DR

Number of Satellites



— Number of GPS Satellites — Number of GLONASS Satellites — Number of QZSS Satellites
 — Number of BEIDOU Satellites — Number of GALILEO Satellites

Baseline Length



General Information

Mission Information

Project name	21-081_FFSL_210921_ALS
Processing date	2021-11-16 17:23:55
Mission date	2021-09-21 14:45:19
Mission duration	02:43:41.000
Processing mode	IN-Fusion Trimble RTX Nav

Rover Hardware Information

Product	POS AV 610 VER6 HW2.5-12
Serial number	S/N11651
IMU type	57
Receiver type	BD982
Antenna type	AV39

Project File List

Rover Data Files

File name	File type
N62756.271	POS Data
N62756.272	POS Data
N62756.273	POS Data
N62756.274	POS Data
N62756.275	POS Data
N62756.276	POS Data
N62756.277	POS Data
N62756.278	POS Data
N62756.279	POS Data
N62756.280	POS Data
N62756.281	POS Data
N62756.282	POS Data
N62756.283	POS Data
N62756.284	POS Data
N62756.285	POS Data
N62756.286	POS Data
N62756.287	POS Data
N62756.288	POS Data
N62756.289	POS Data
N62756.290	POS Data
N62756.291	POS Data
N62756.292	POS Data
N62756.293	POS Data
N62756.294	POS Data
N62756.295	POS Data
N62756.296	POS Data
N62756.297	POS Data
N62756.298	POS Data
N62756.299	POS Data
N62756.300	POS Data
N62756.301	POS Data

Input Files

File Name	File Type
Ephm2640.21g	GLONASS Broadcast Ephemeris
Ephm2640.21n	GPS Broadcast Ephemeris
igl21761.sp3	GLONASS Precise Ephemeris
igl21762.sp3	GLONASS Precise Ephemeris
igl21763.sp3	GLONASS Precise Ephemeris
igs21761.sp3	GPS Precise Ephemeris
igs21762.sp3	GPS Precise Ephemeris
igs21763.sp3	GPS Precise Ephemeris

Output Files

Filename	File type
sbet_Mission 1.out	SBET Trajectory File

Rover Data Summary

First raw data file	N62756.271		
Last raw data file	N62756.301		
Start GPS week	2176		
Start time	225900.653 (9/21/2021 2:45:00 PM)		
End time	235722.375 (9/21/2021 5:28:42 PM)		
Start of fine alignment	226688.957 (9/21/2021 2:58:08 PM)		
Available subsystems	Primary GNSS, Gimbal, IMU		
POS Event Input	None		
Correction data	Trimble RTX		
IMU Installation Lever Arms & Mounting Angles			
Gimbal to IMU lever arm (m)	-0.034	-0.010	-0.374
Gimbal to IMU mounting angles (deg)	0.000	0.000	0.000
Gimbal to Primary GNSS lever arm (m)	0.980	-0.102	-1.276
Gimbal to Primary GNSS lever arm std dev (m)	-1.000		
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

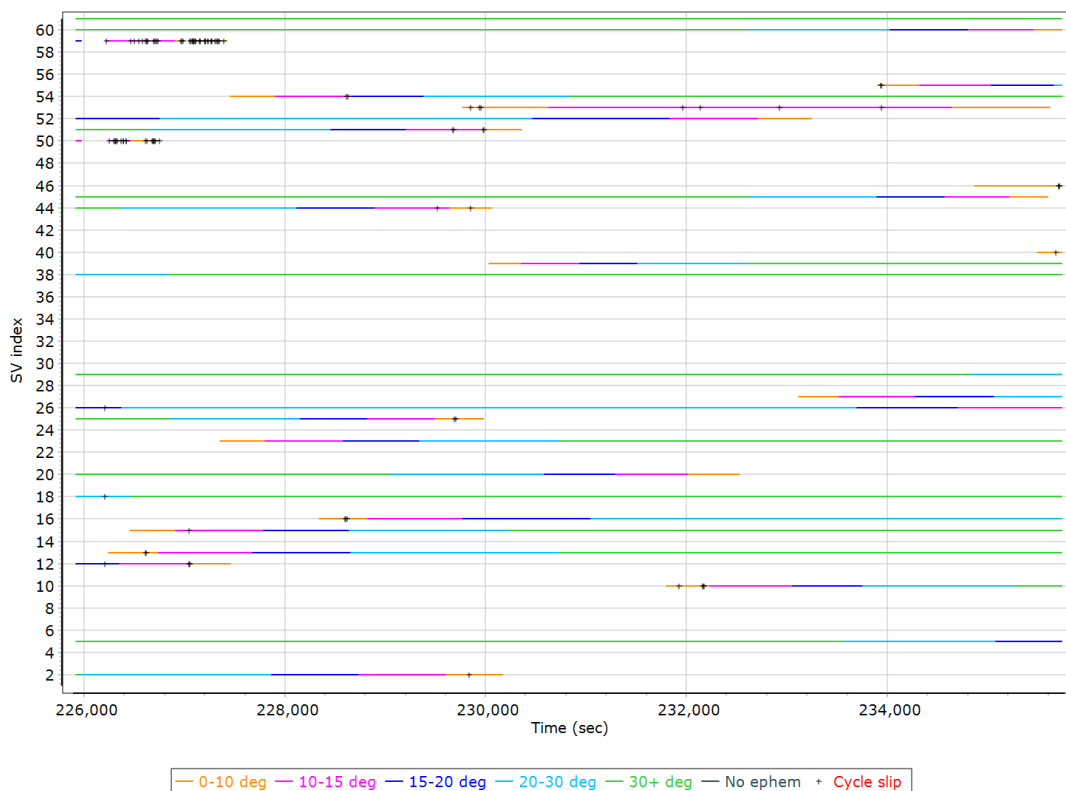
Rover Data QC

Raw IMU Import QC Summary

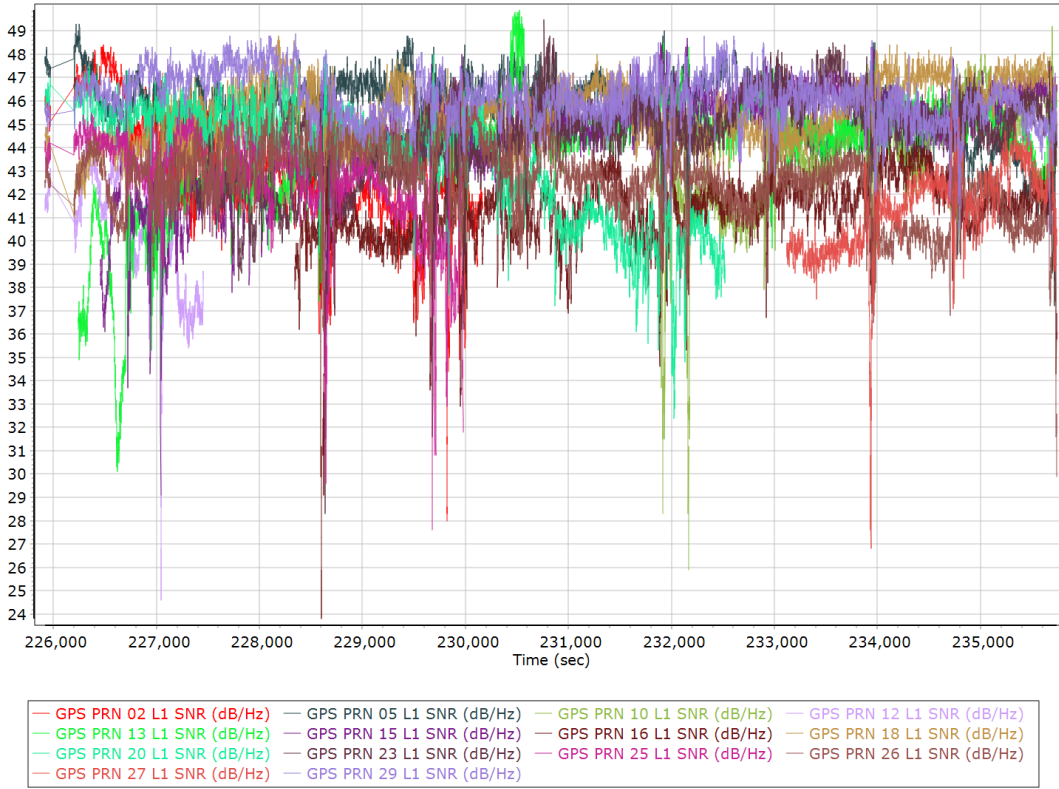
IMU data input file	imu_Mission 1.dat
IMU data check log file	imudt_Mission 1.log
IMU Records Processed	1918777
Termination Status	Warnings
IMU Anomalies	2
IMU Failure Messages	
226192.828 : WARNING : Gap of 226180.8719 seconds in CHECKDT input data	

Primary Observables & Satellite Data

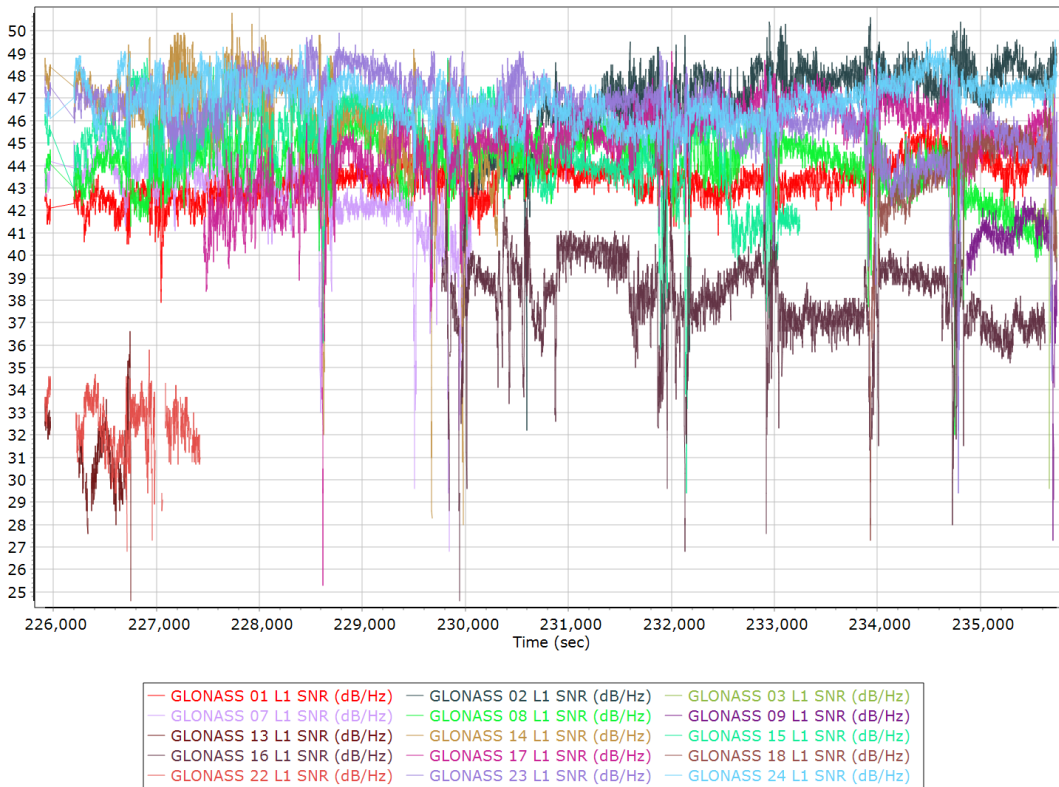
GPS/GLONASS L1 Satellite Lock/Elevation



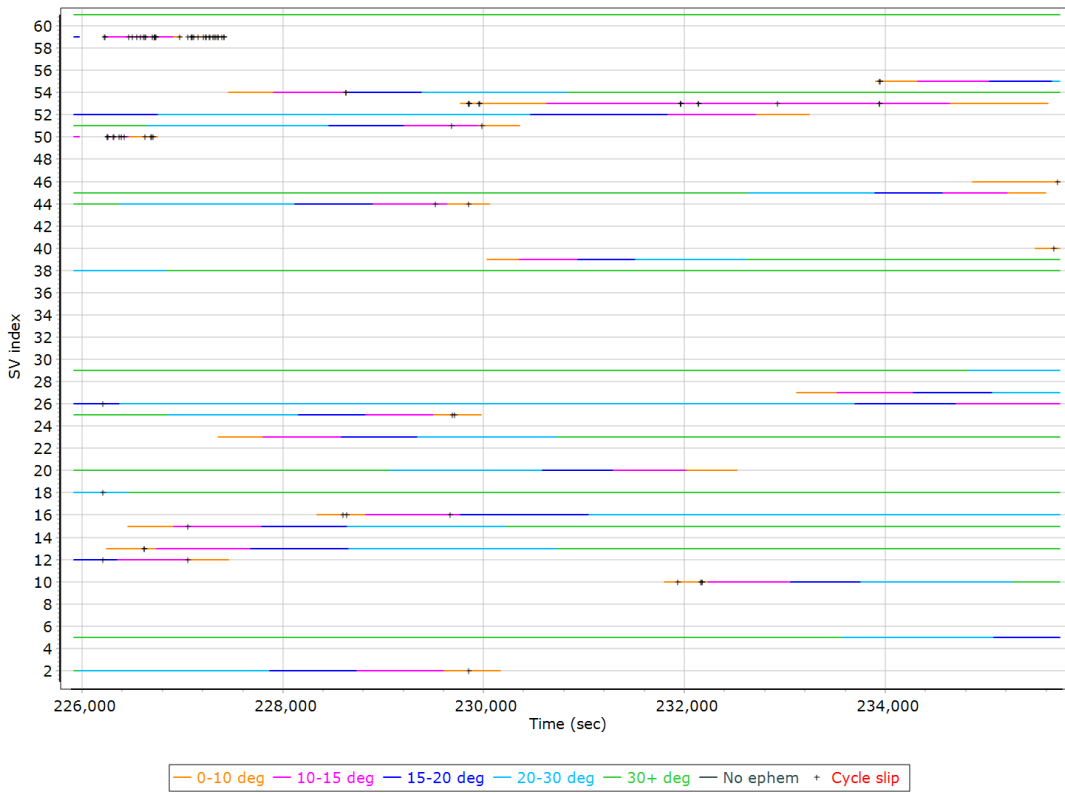
GPS L1 SNR



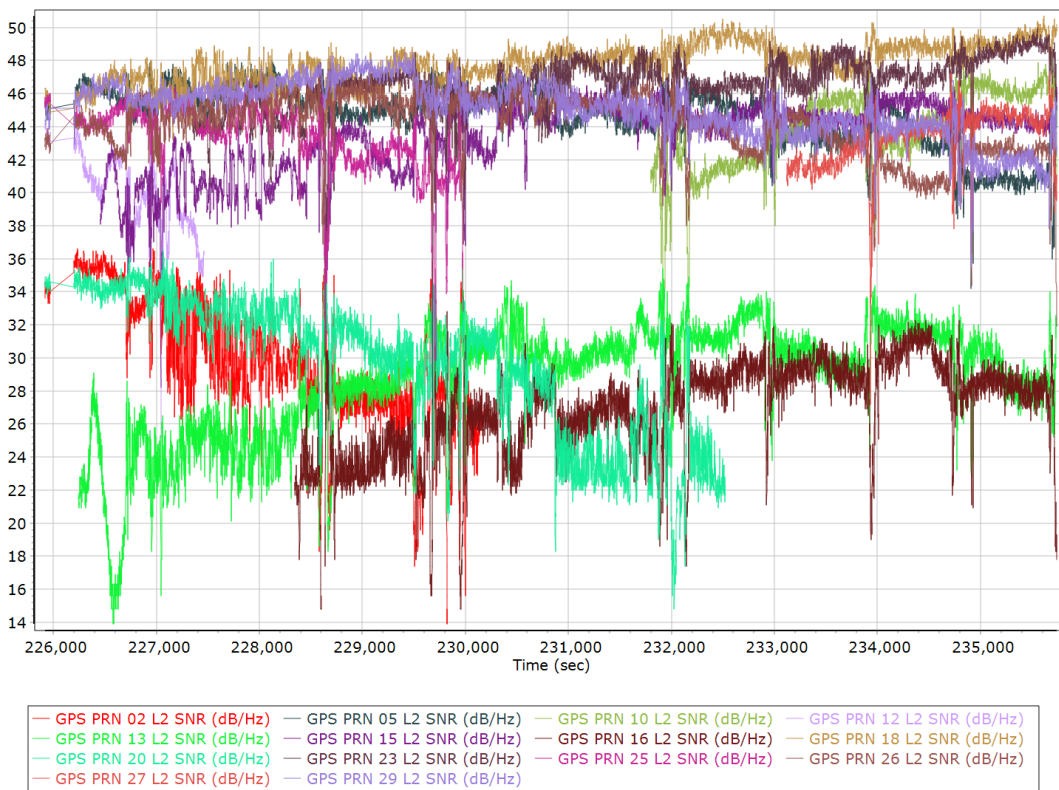
GLONASS L1 SNR



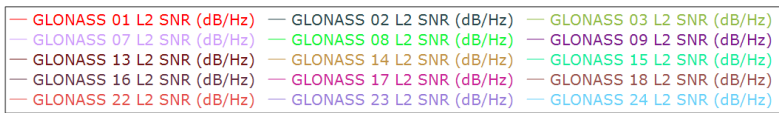
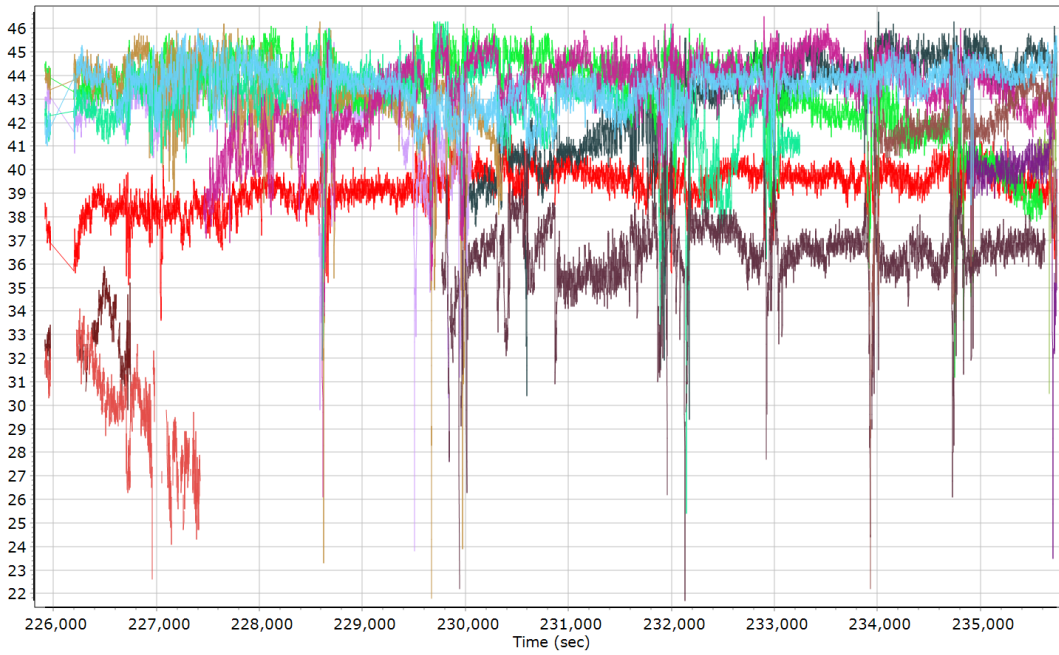
GPS/GLONASS L2 Satellite Lock/Elevation



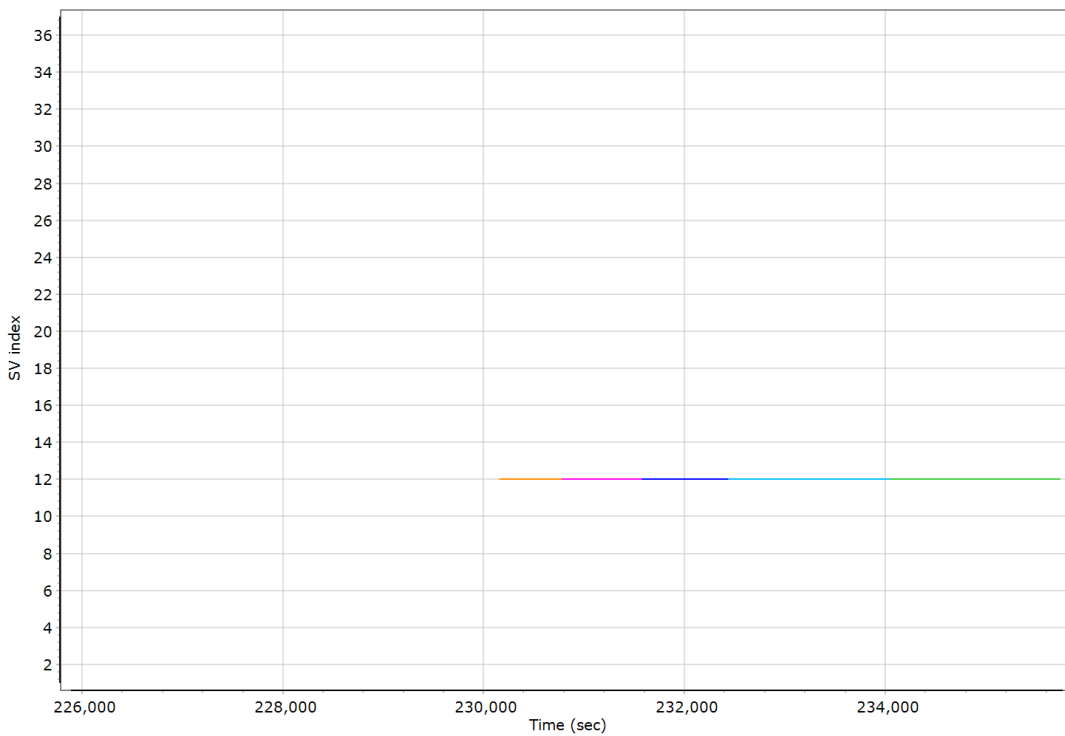
GPS L2 SNR



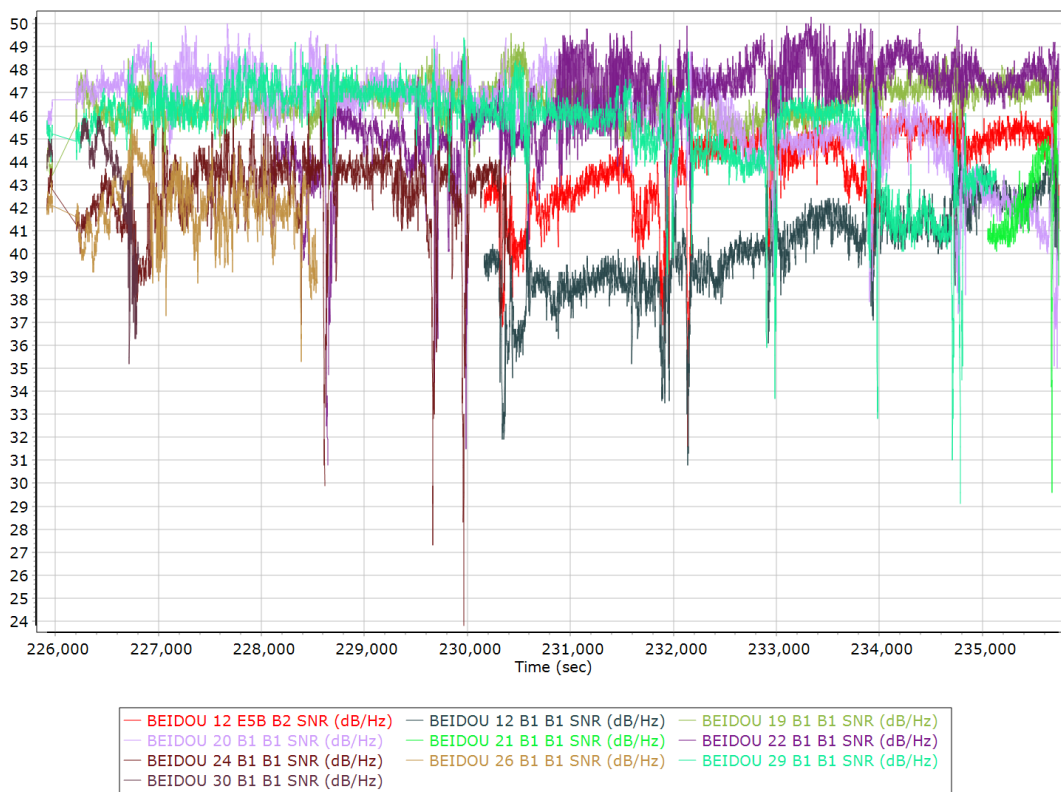
GLONASS L2 SNR



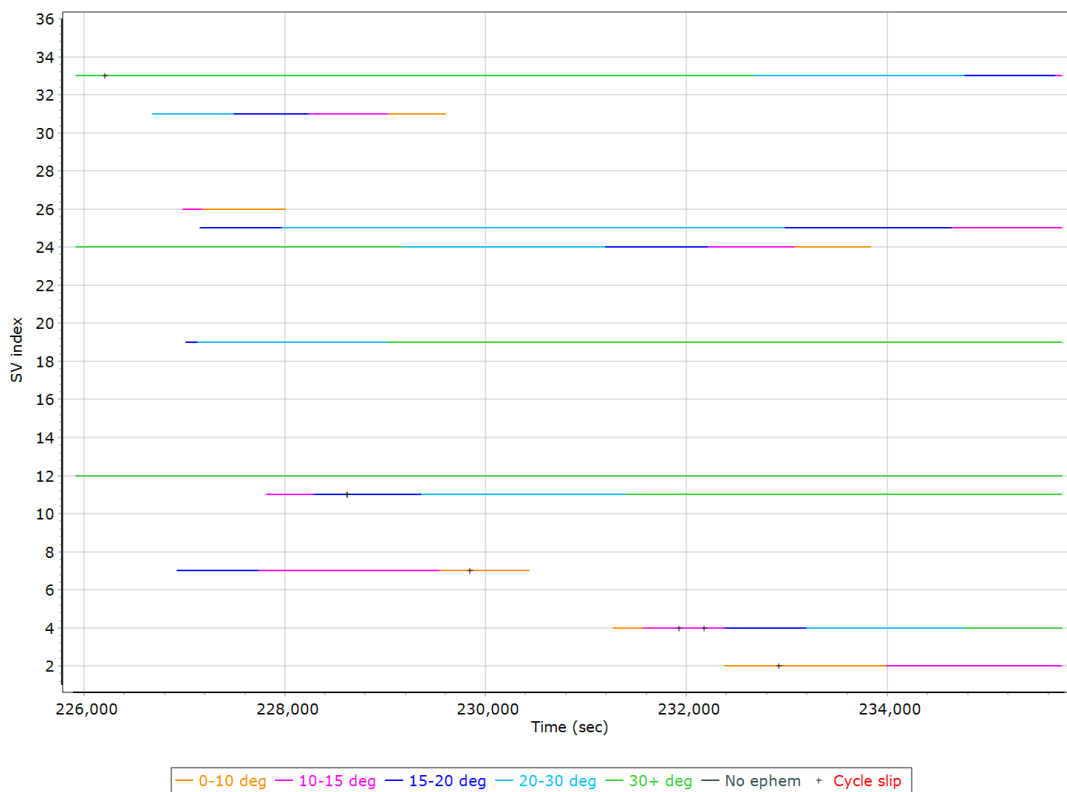
BEIDOU Satellite Lock/Elevation



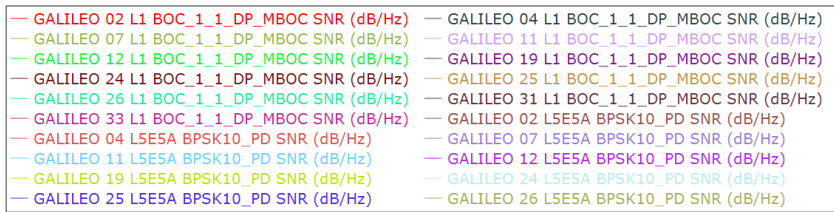
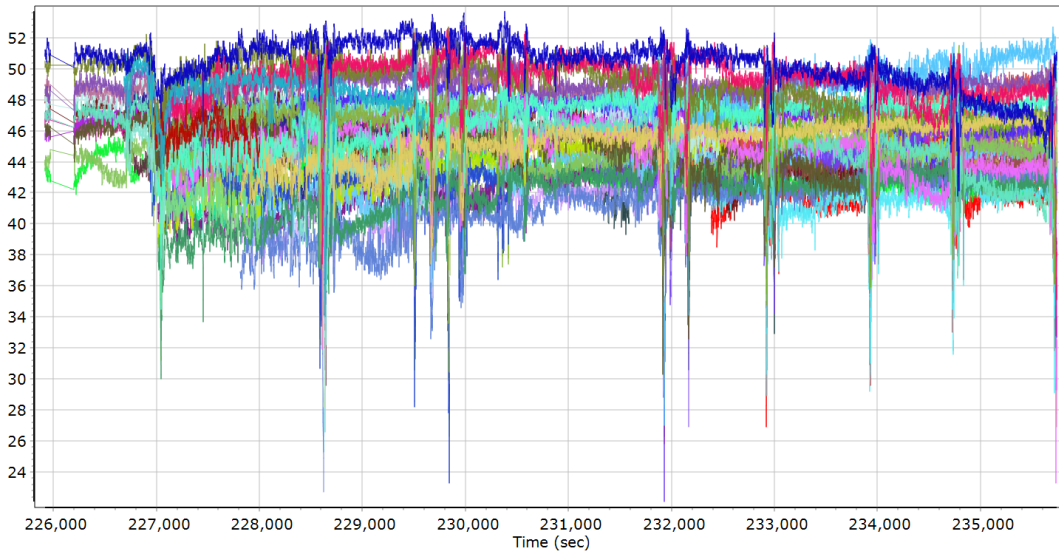
BEIDOU SNR



GALILEO Satellite Lock/Elevation

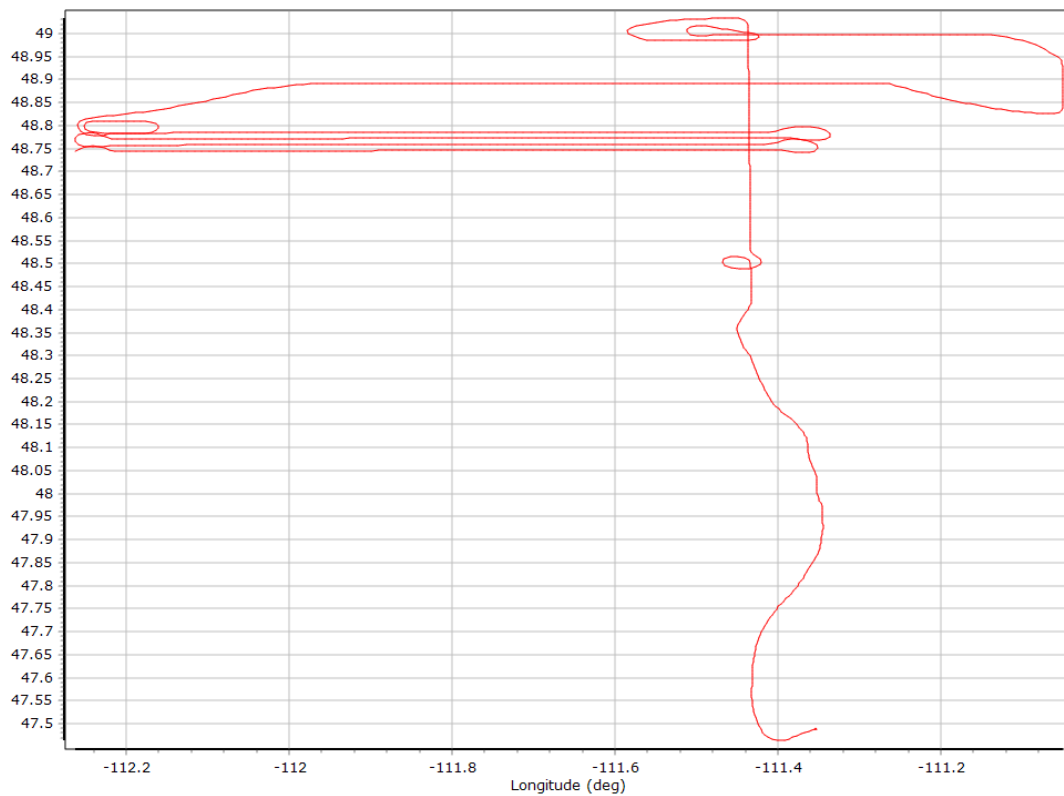


GALILEO SNR

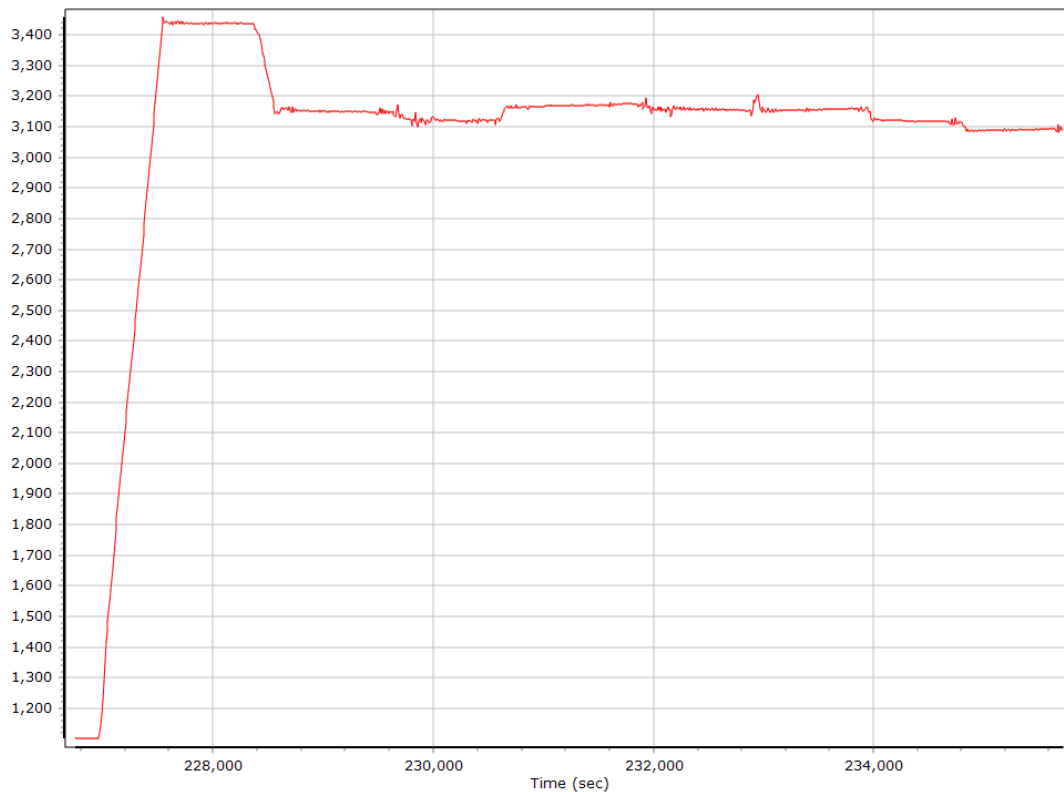


Smoothed Trajectory Information

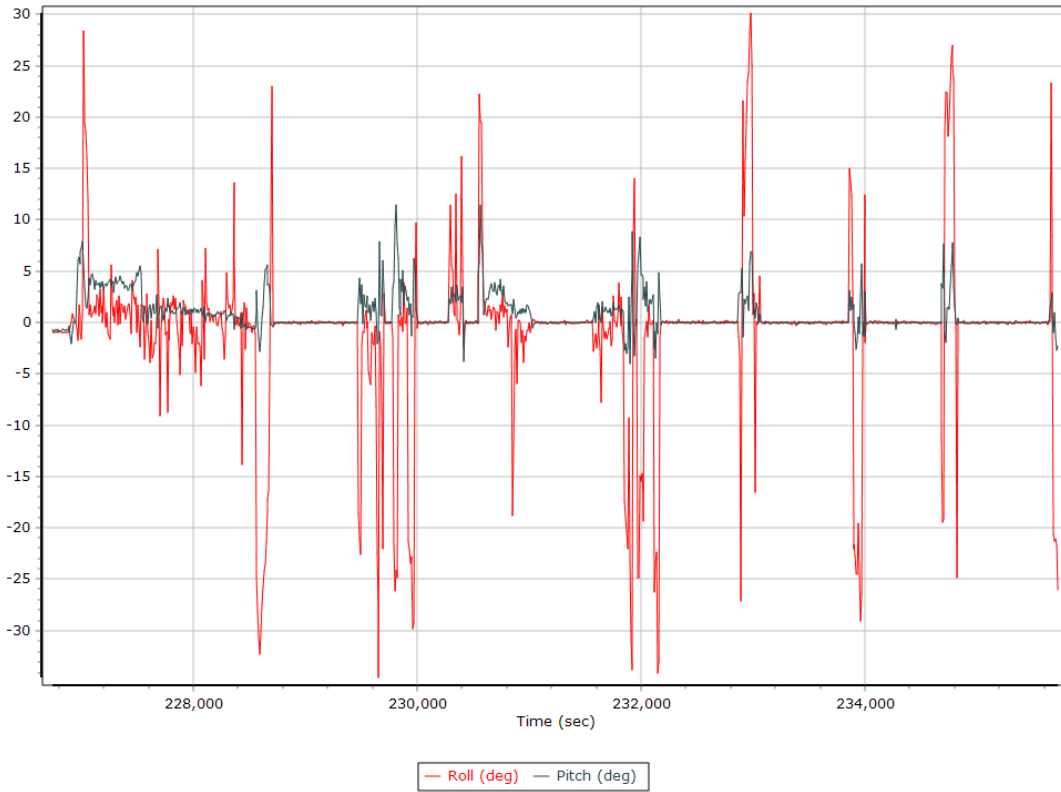
Top View



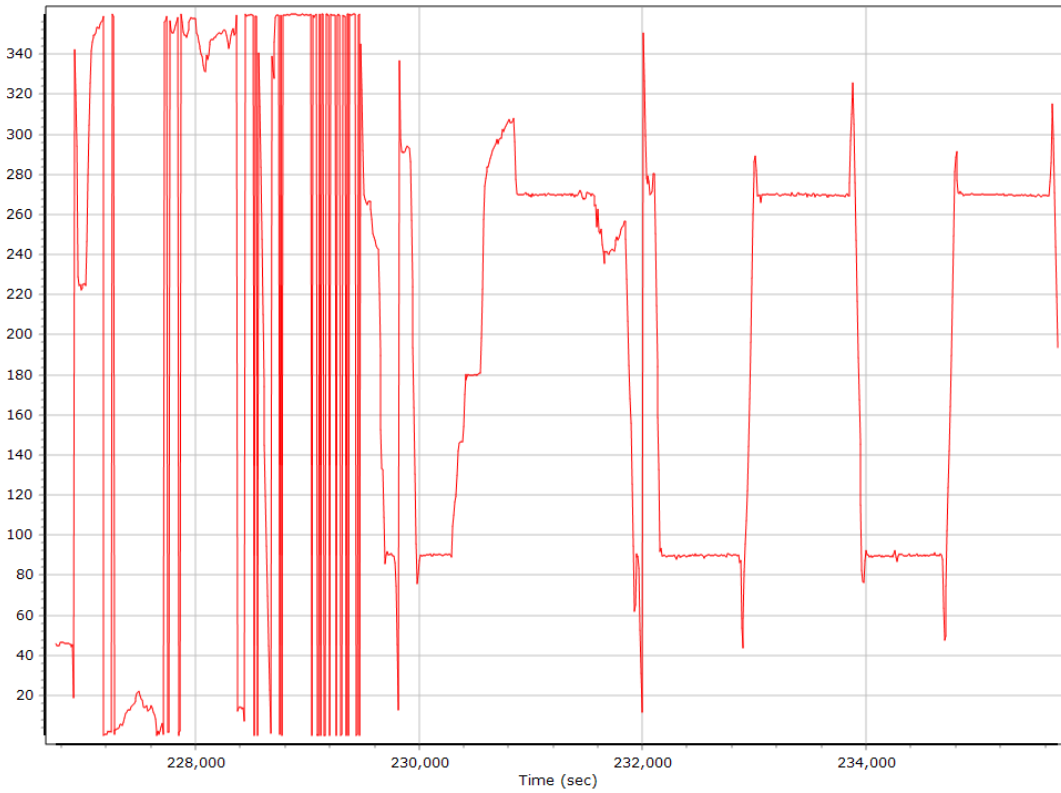
Altitude



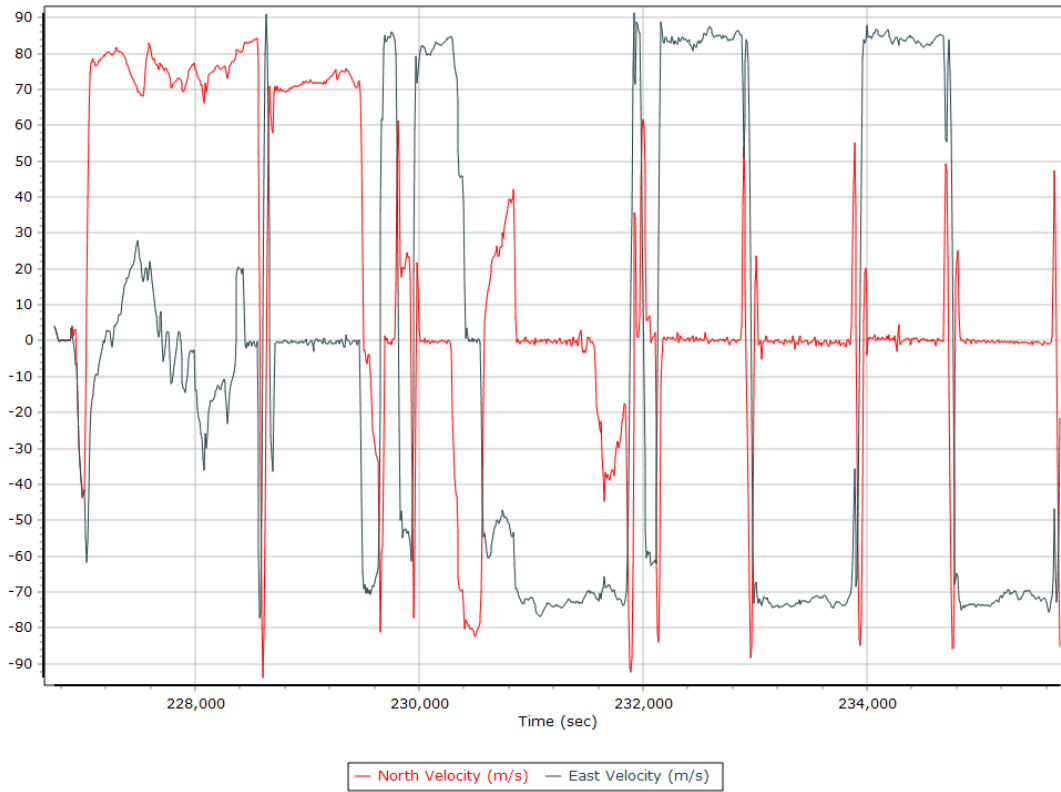
Roll/Pitch



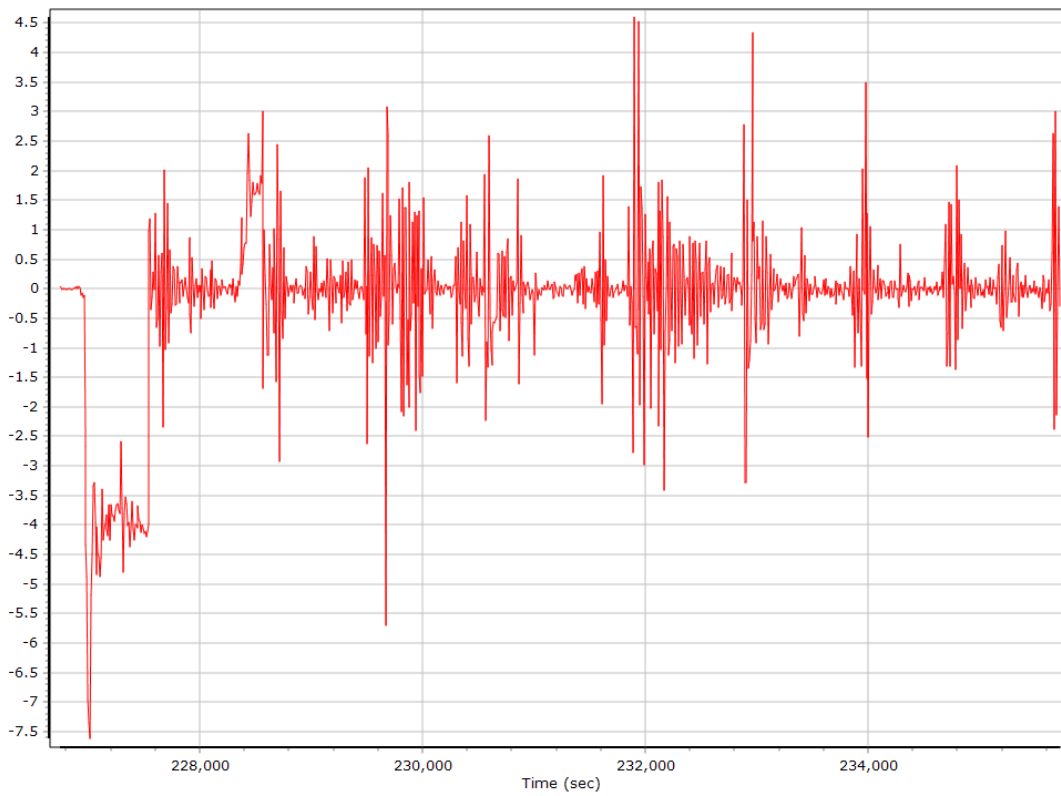
Heading



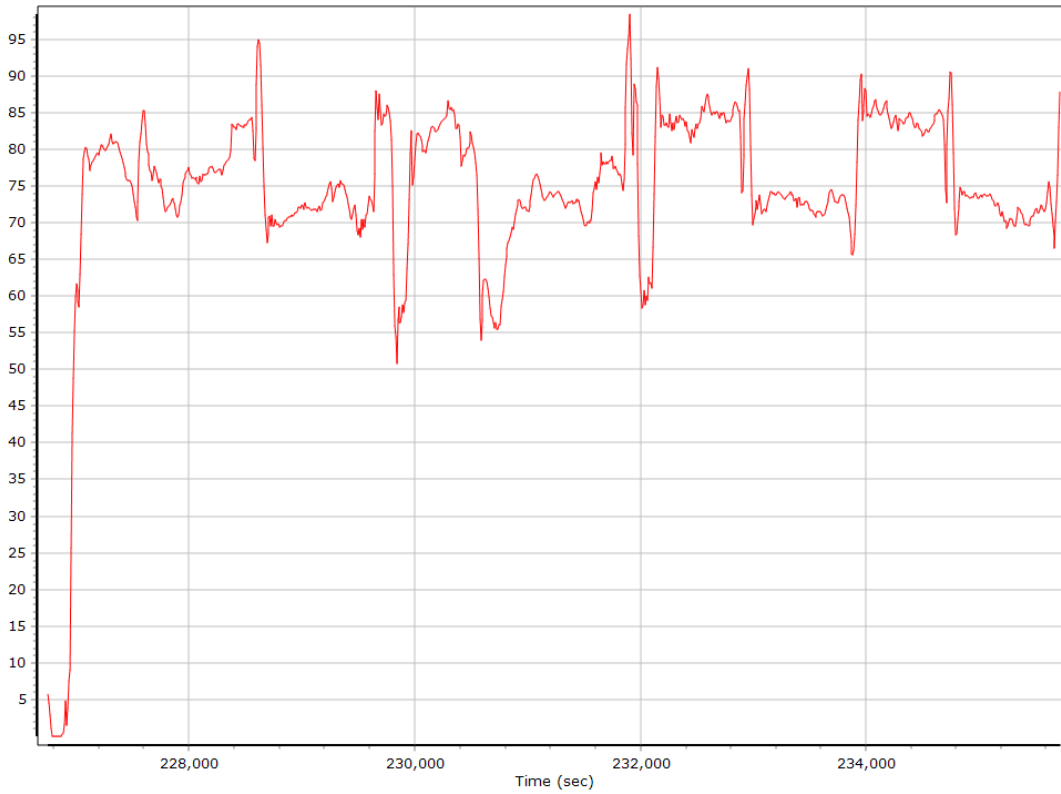
North/East Velocity



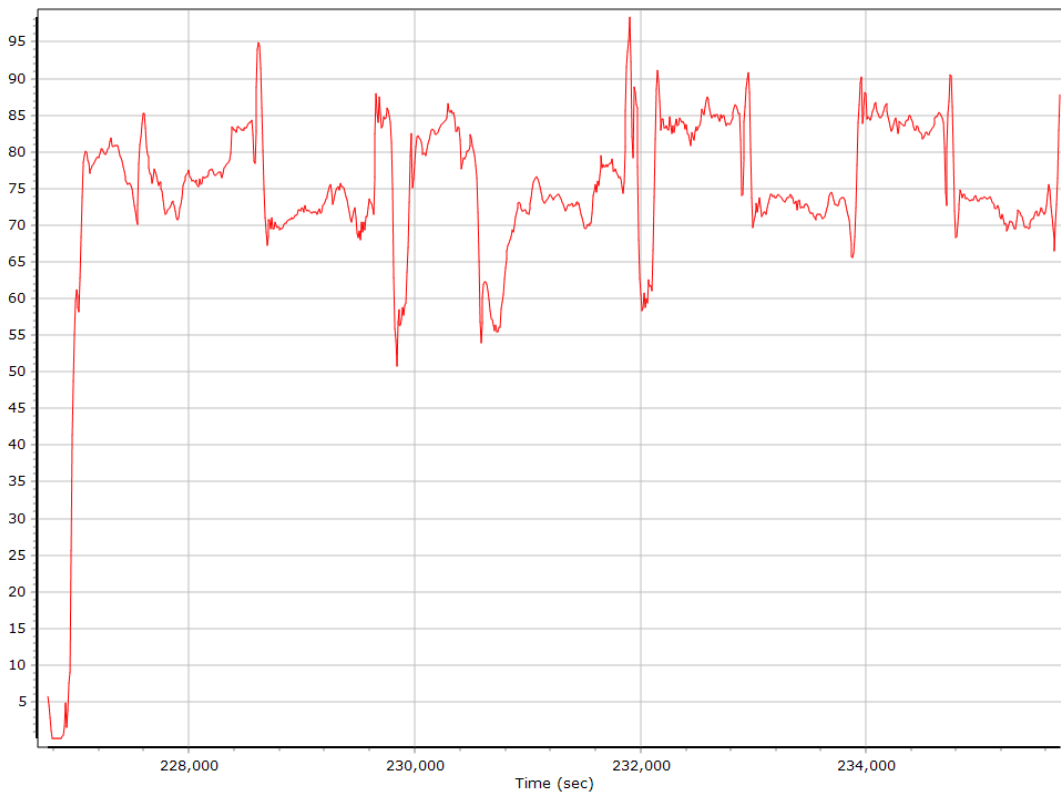
Down Velocity



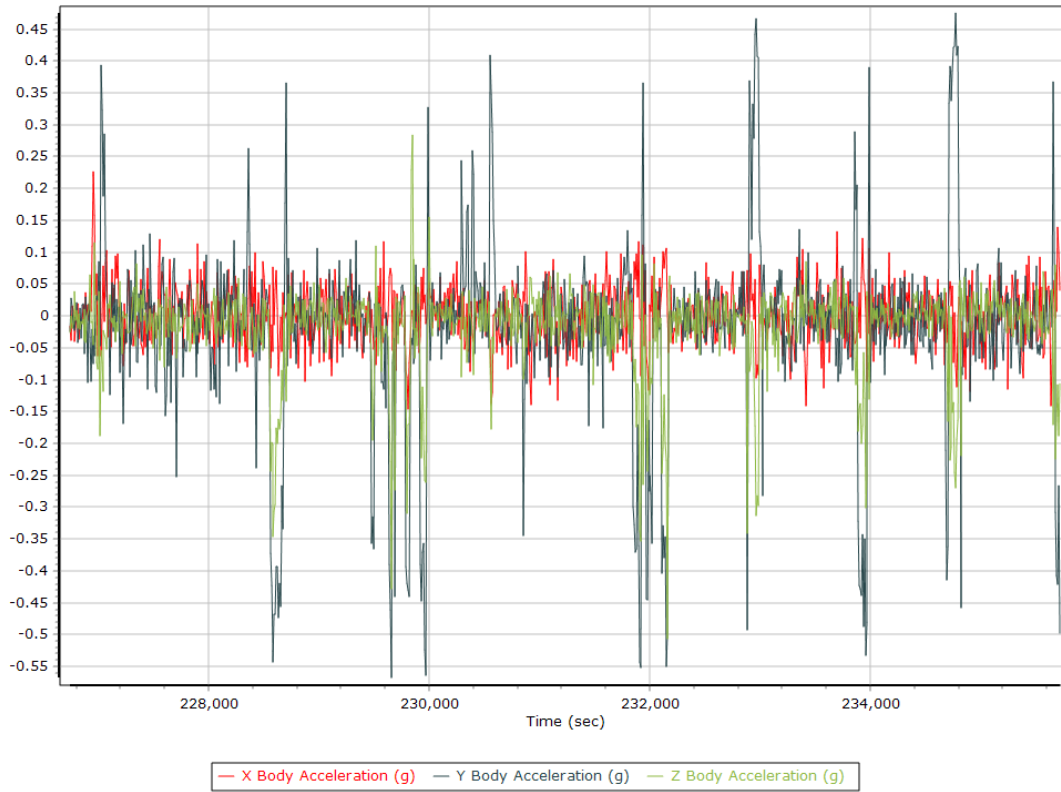
Total Speed



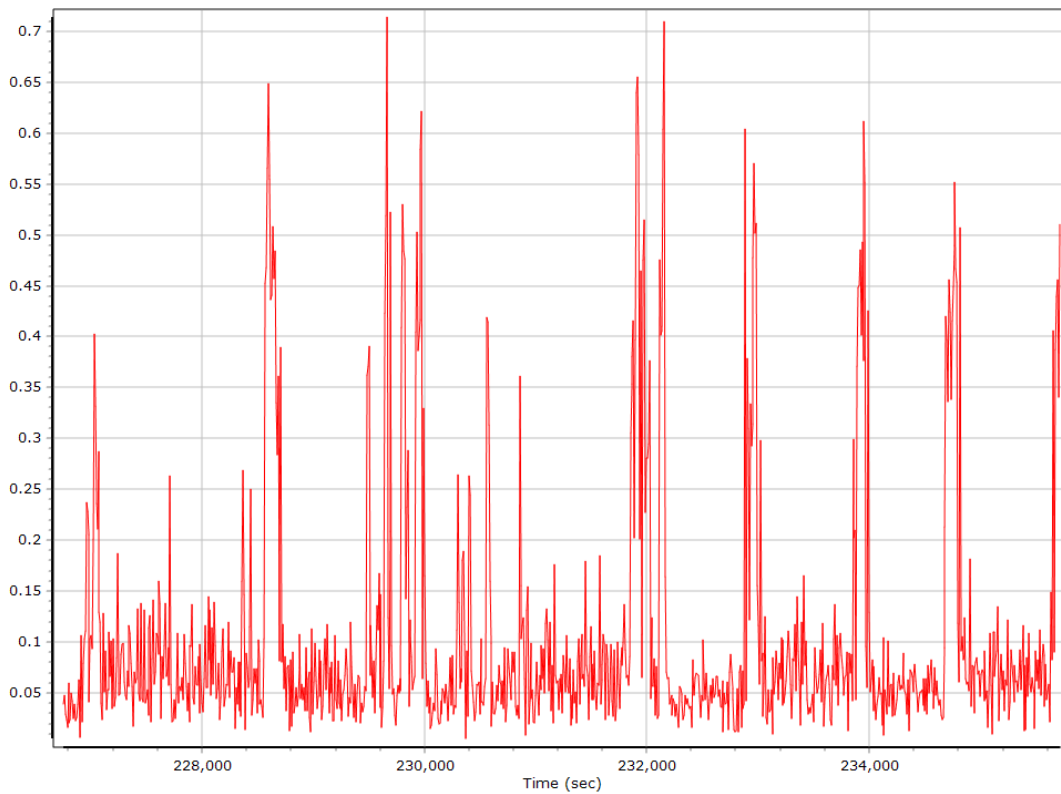
Ground Speed



Body Acceleration



Total Body Acceleration



Body Angular Rate

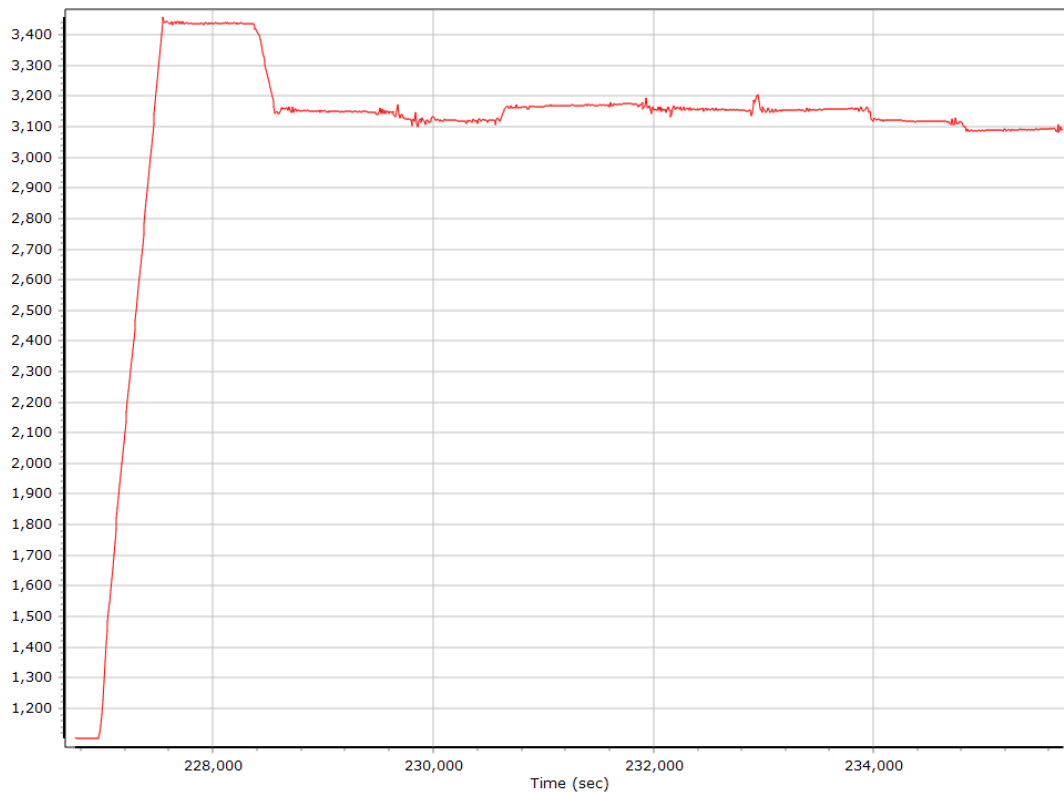


Forward Processed Trajectory Information

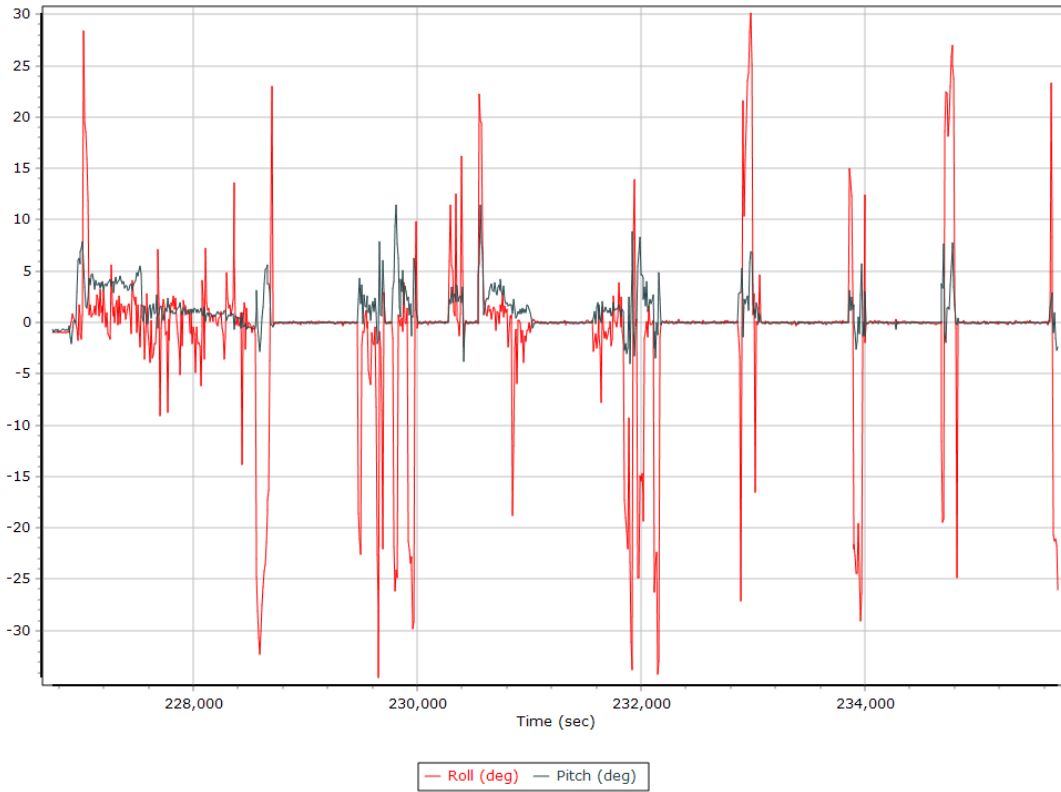
Top View



Altitude



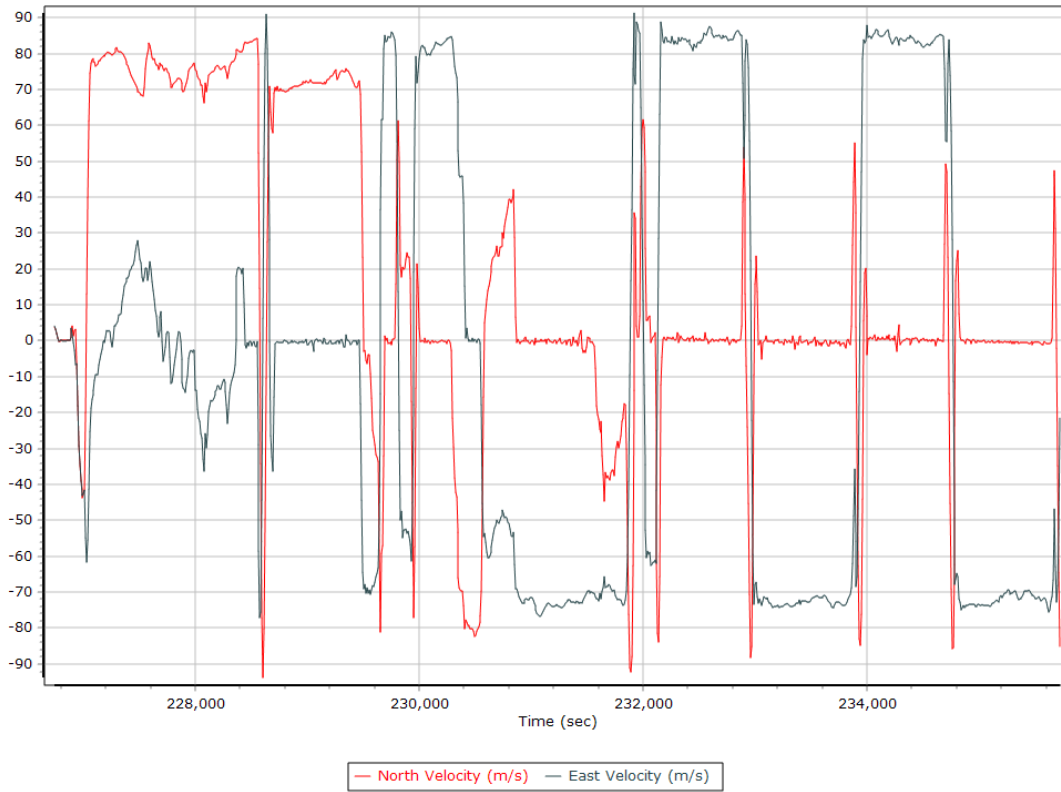
Roll/Pitch



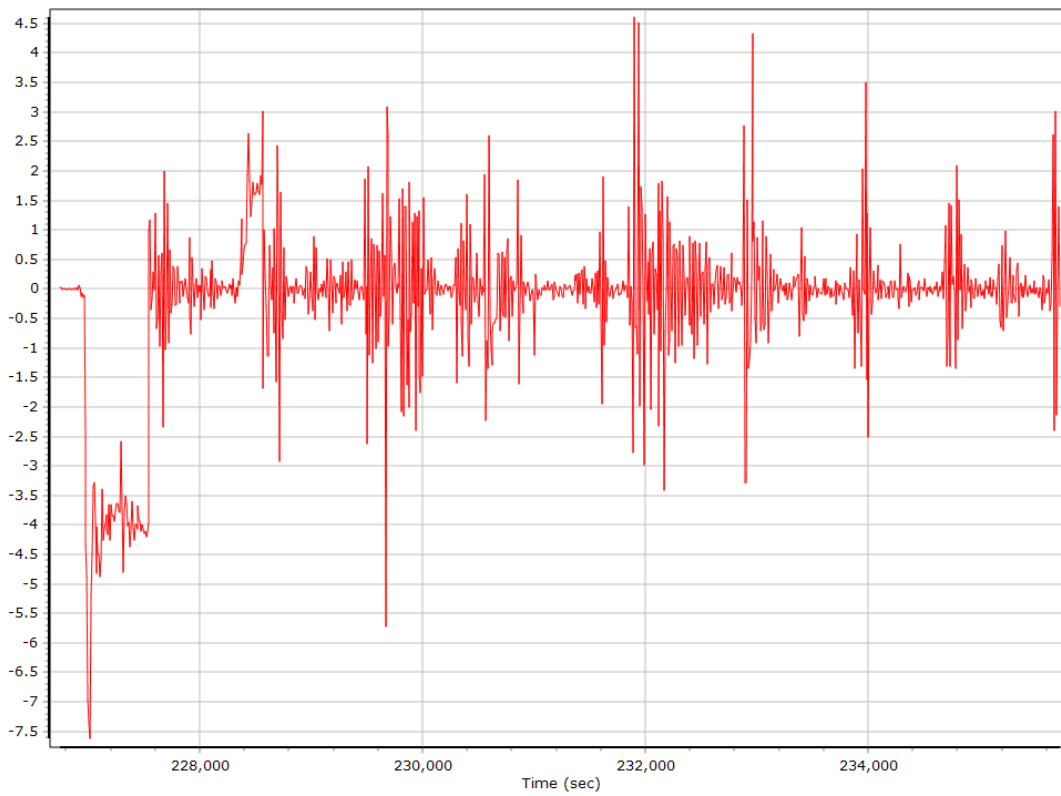
Heading



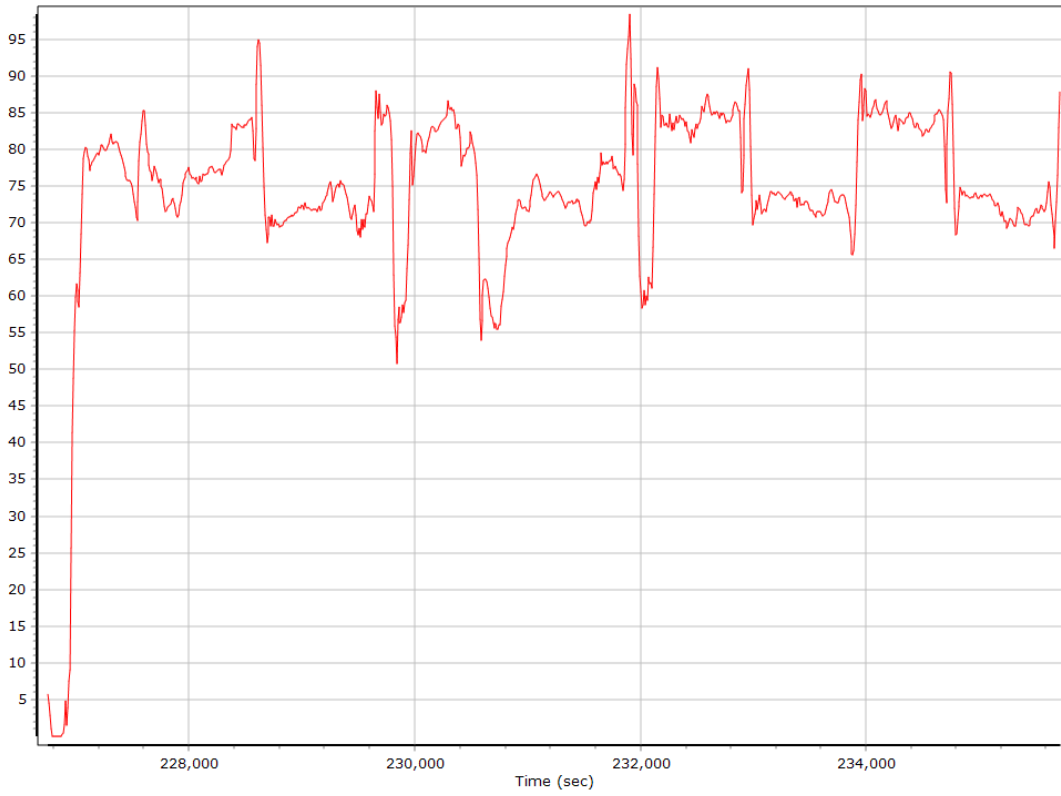
North/East Velocity



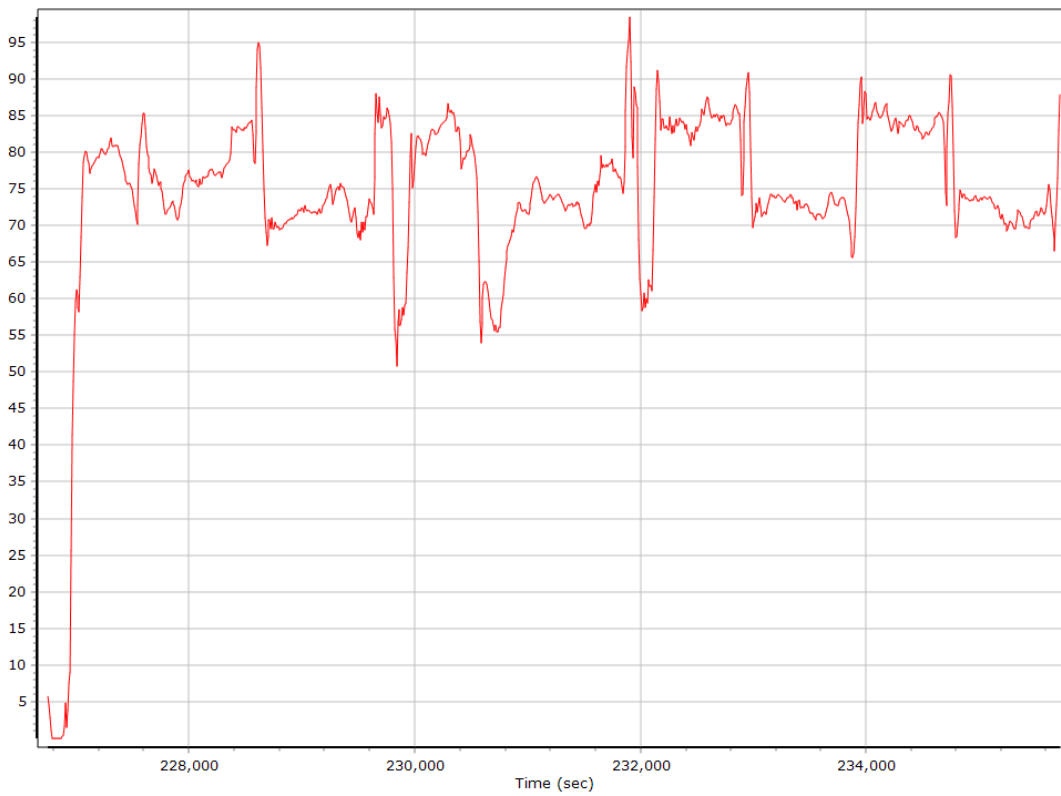
Down Velocity



Total Speed



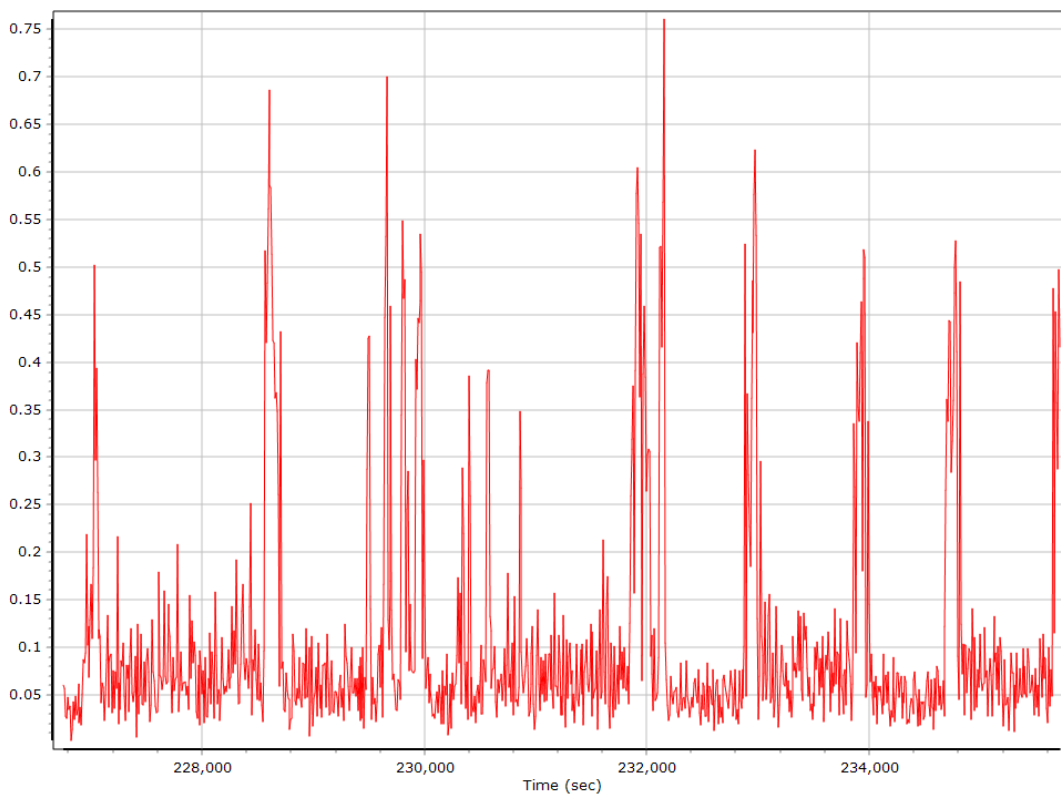
Ground Speed



Body Acceleration



Total Body Acceleration



Body Angular Rate



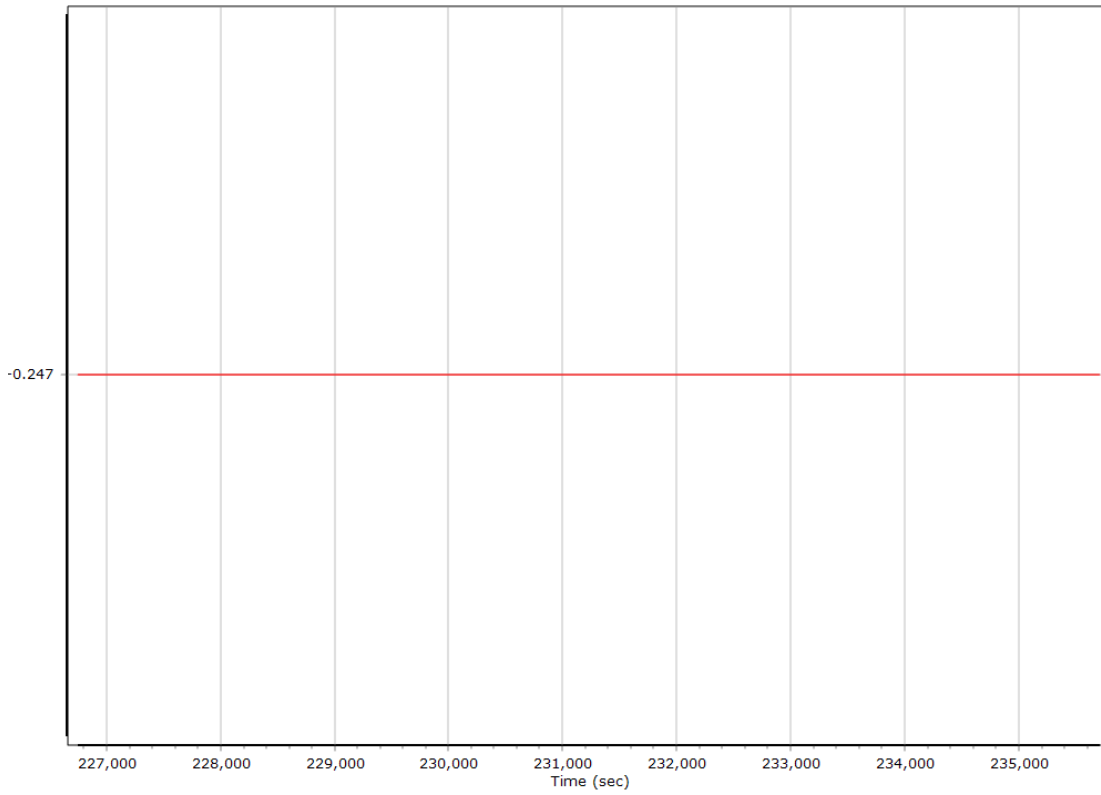
GNSS-Inertial Processor Configuration

Processing mode	IN-Fusion Trimble RTX Nav		
Stabilized mount	True		
Processing start time	225901.000 (9/21/2021 2:45:01 PM)		
Processing end time	235722.000 (9/21/2021 5:28:42 PM)		
Initial attitude source	Real-Time VNAV/RNAV Attitude		
IMU Sensor Context	Processing with Onboard IMU		
Gimbal to IMU lever arm (m)	-0.034	-0.010	-0.374
Gimbal to IMU mounting angles (deg)	0.000	0.000	0.000
Gimbal to Primary GNSS lever arm (m)	-0.247	-0.020	-1.300
Gimbal to Primary GNSS lever arm std dev (m)	0.030	0.030	0.030
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

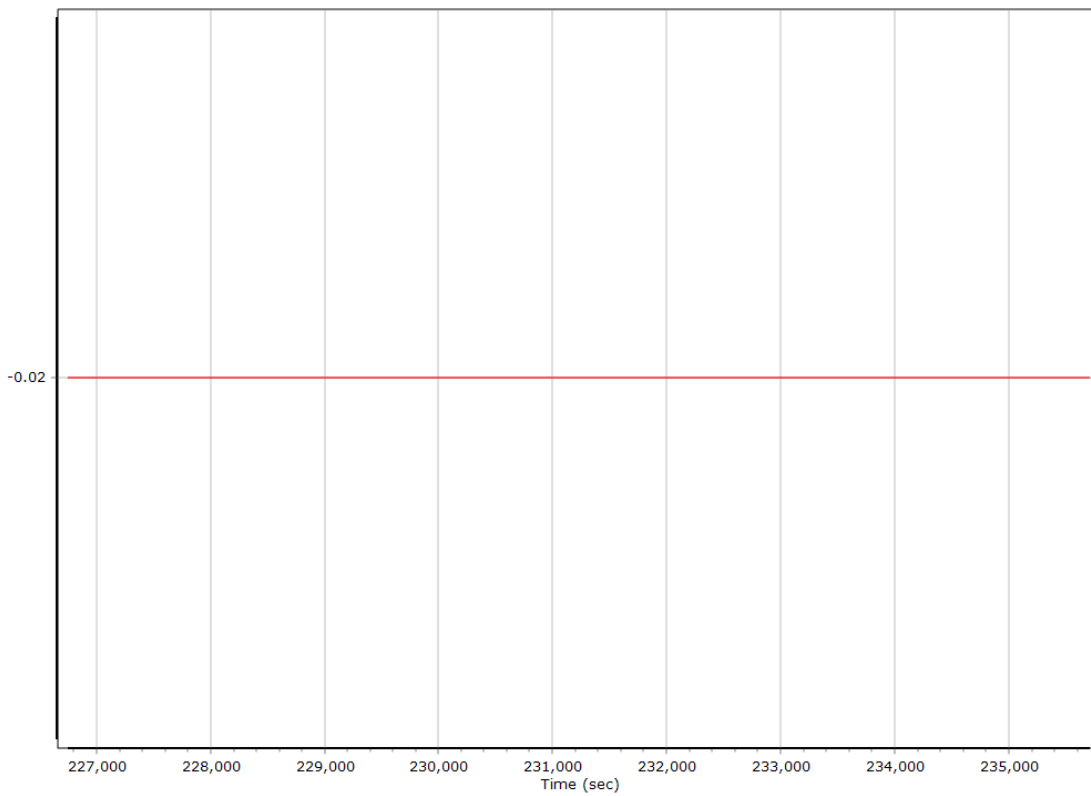
Calibrated Installation Parameters

Reference-Primary GNSS Lever Arm (m)

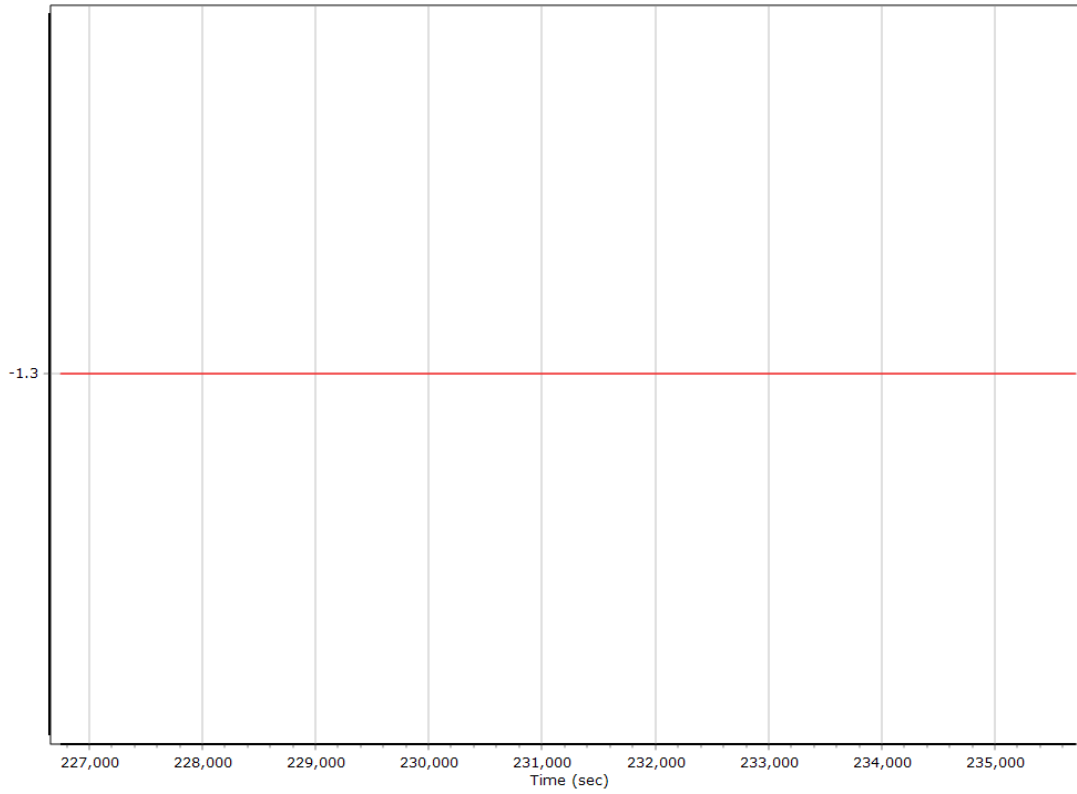
X Reference-Primary GNSS Lever Arm (m)



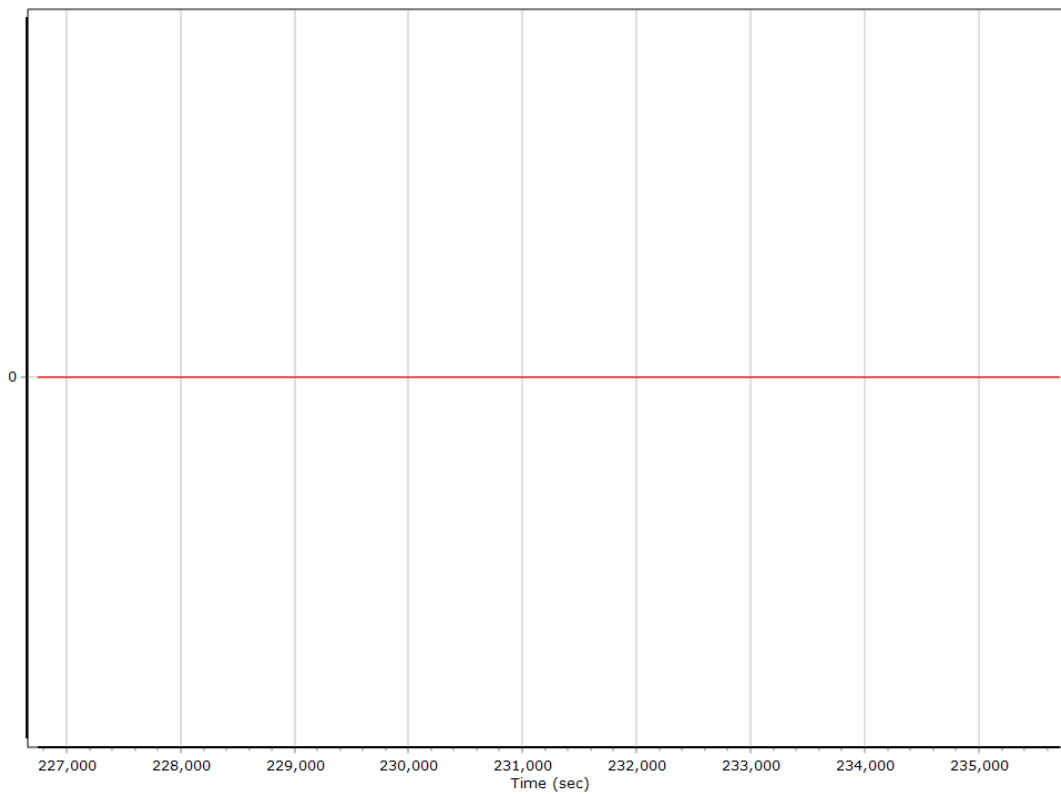
Y Reference-Primary GNSS Lever Arm (m)



Z Reference-Primary GNSS Lever Arm (m)



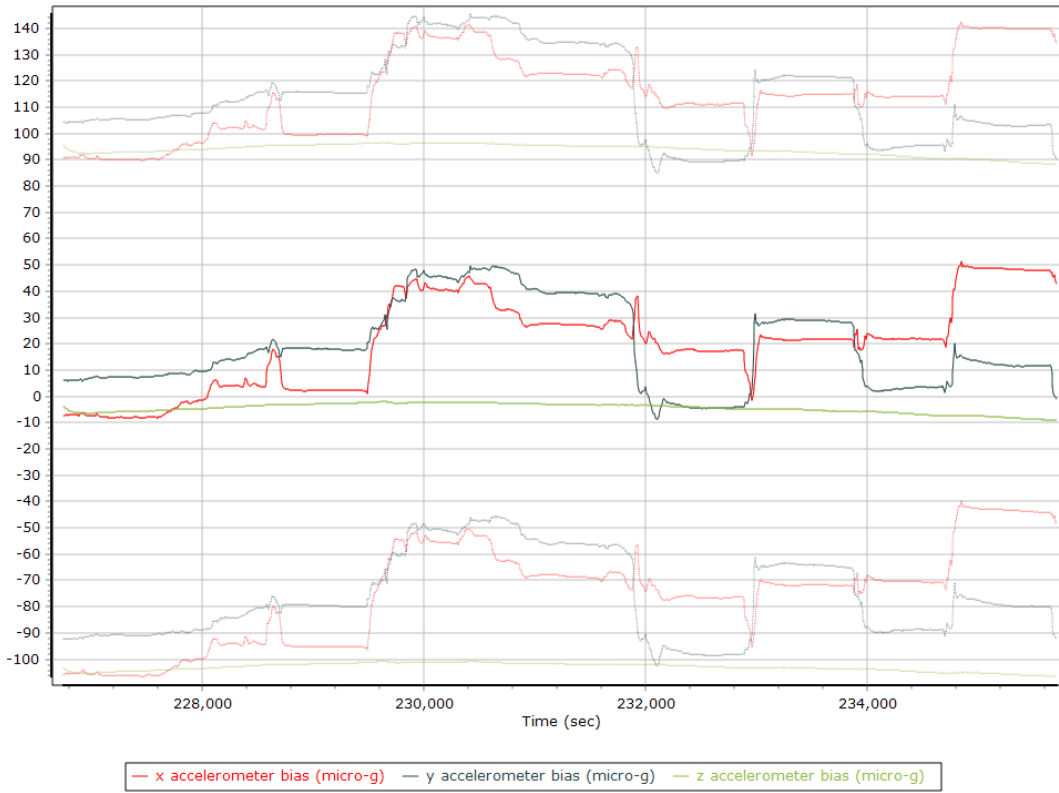
Reference-Primary GNSS Lever Arm Figure of Merit



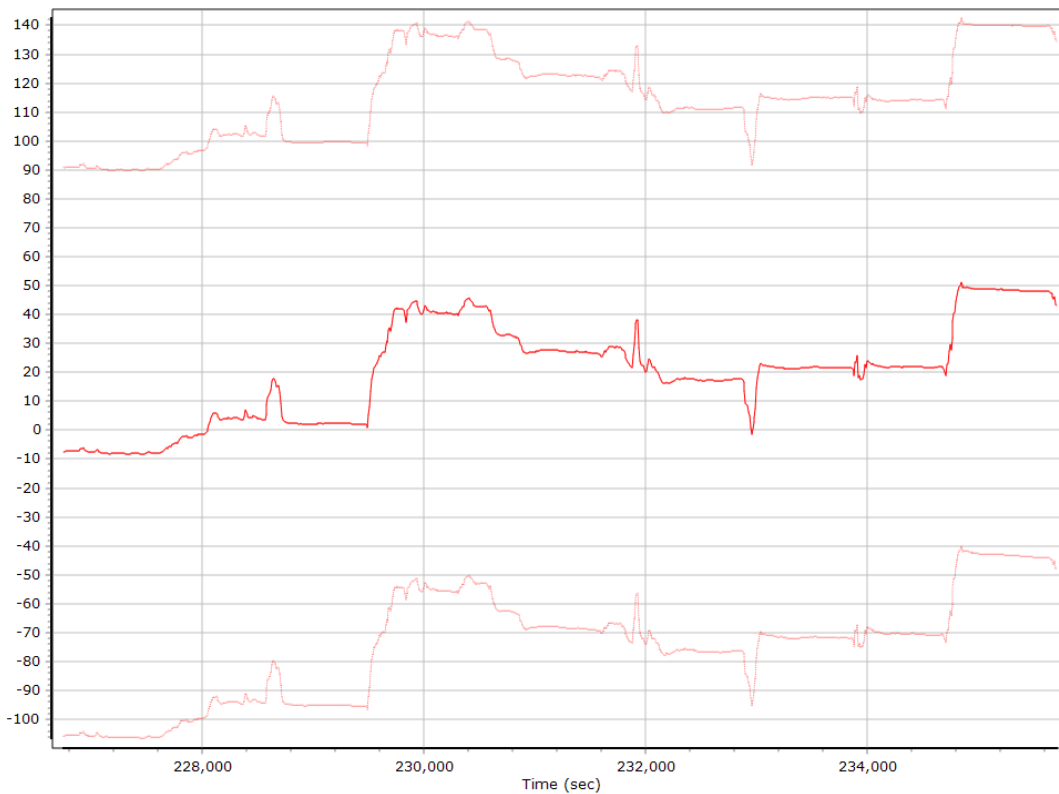
IN-Fusion QC

Forward Processed Estimated Errors, Reference Frame

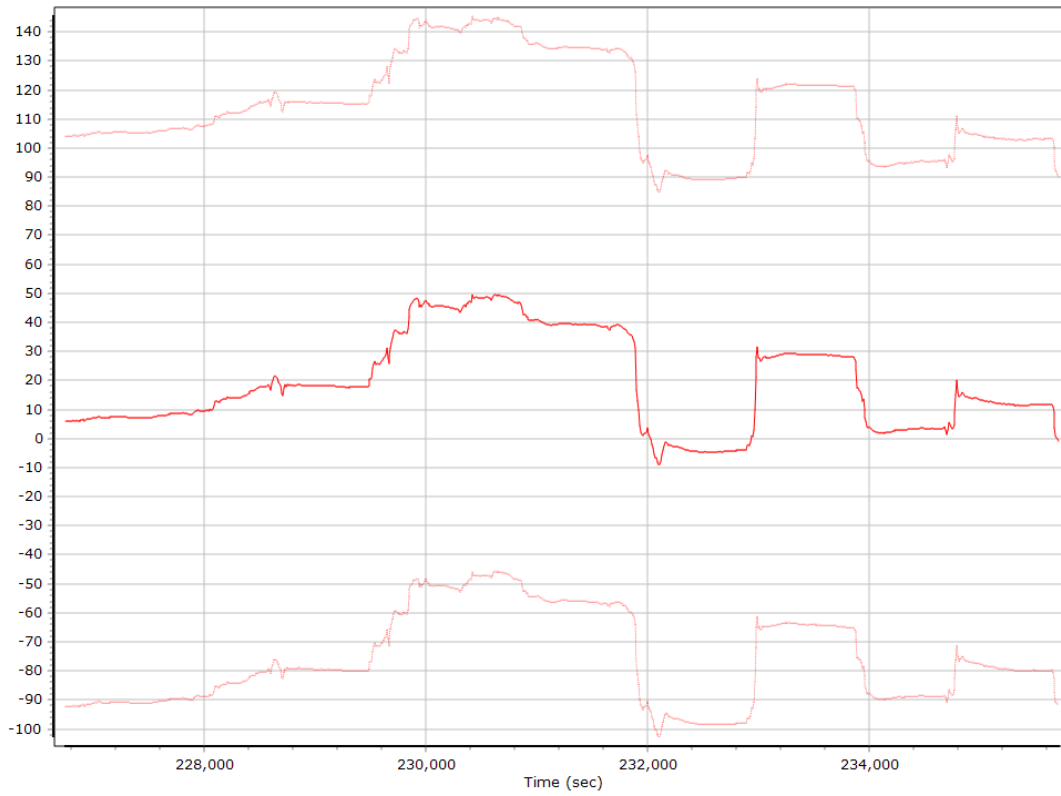
Accelerometer Bias (micro-g)



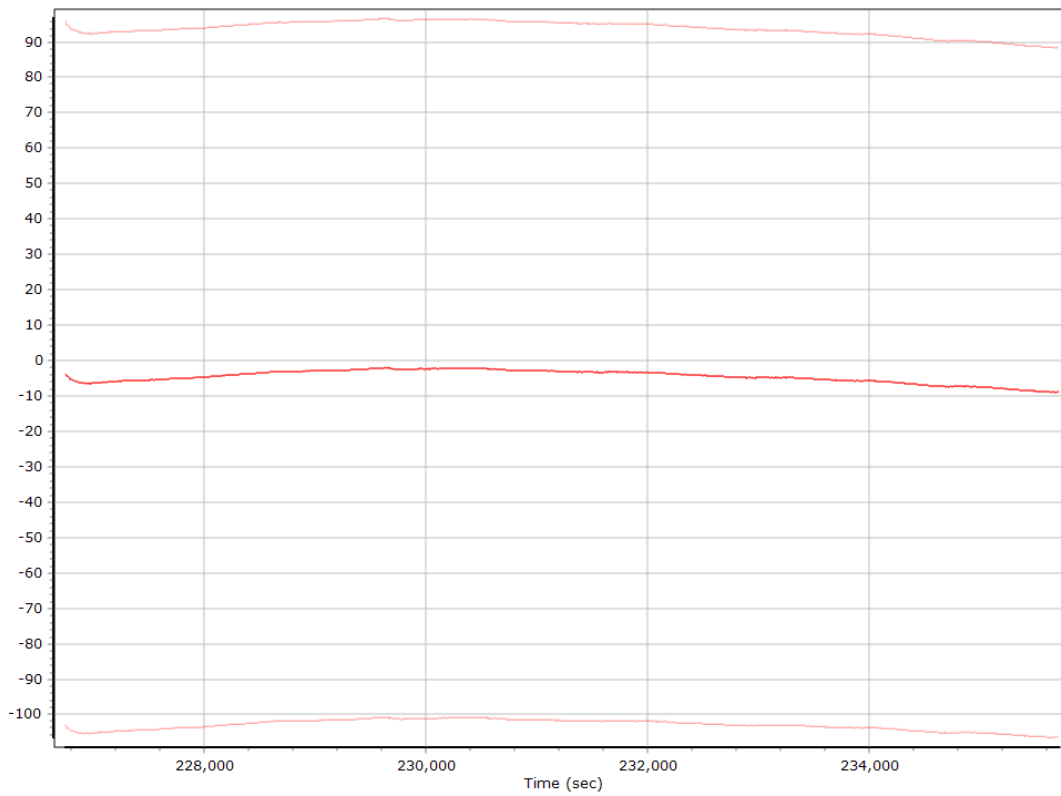
X Accelerometer Bias (micro-g)



Y Accelerometer Bias (micro-g)



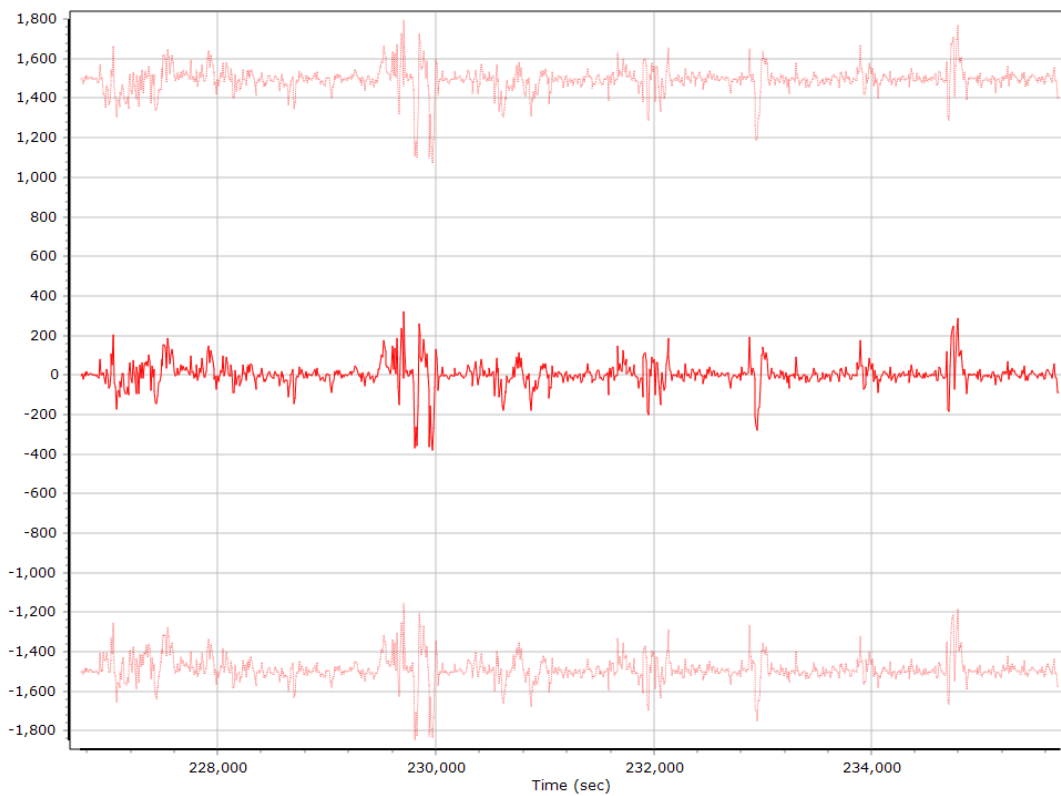
Z Accelerometer Bias (micro-g)



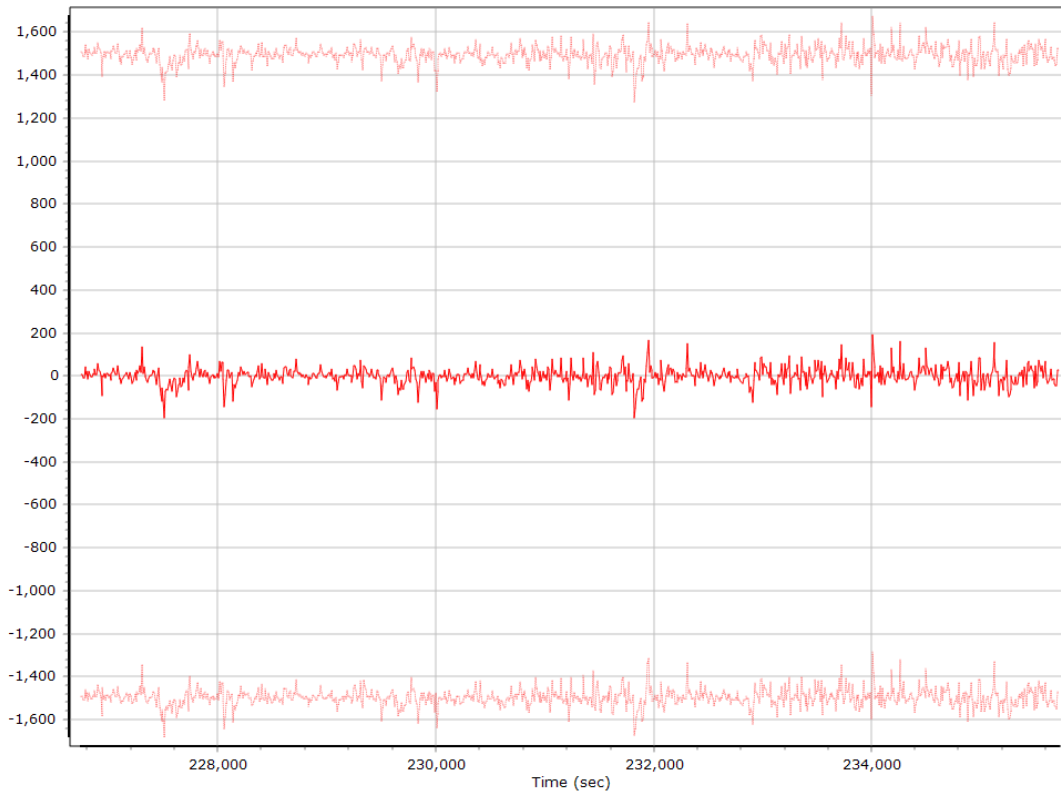
Accelerometer Scale Error (ppm)



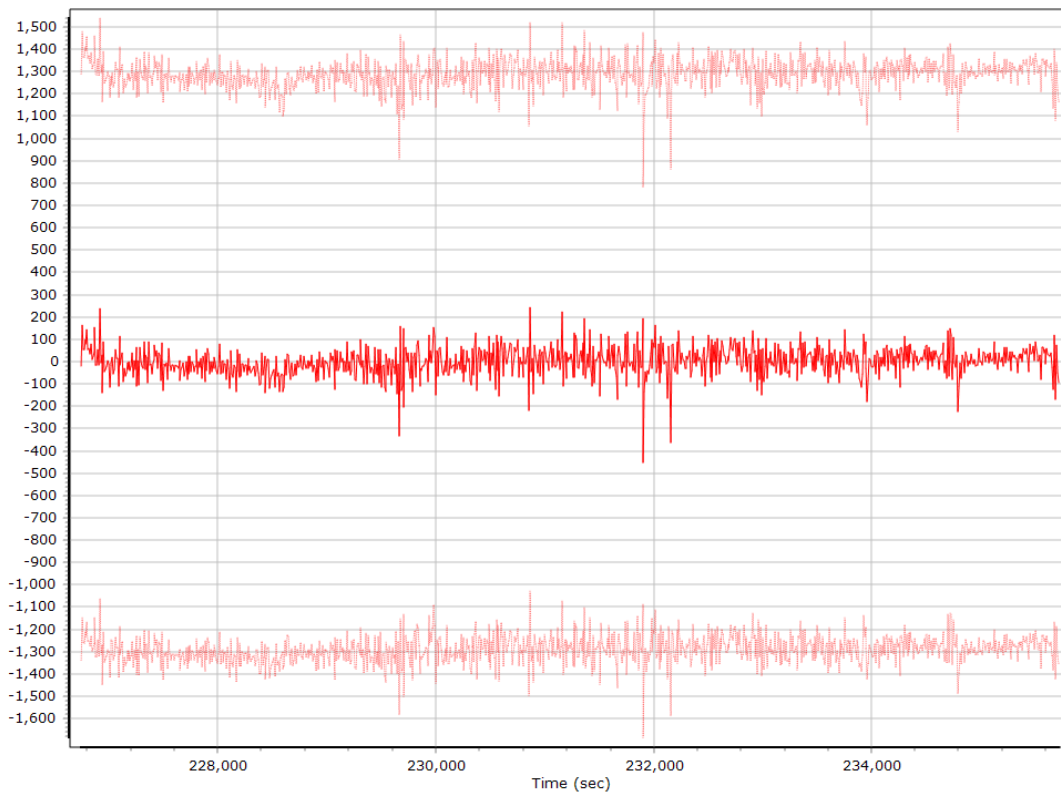
X Accelerometer Scale Error (ppm)



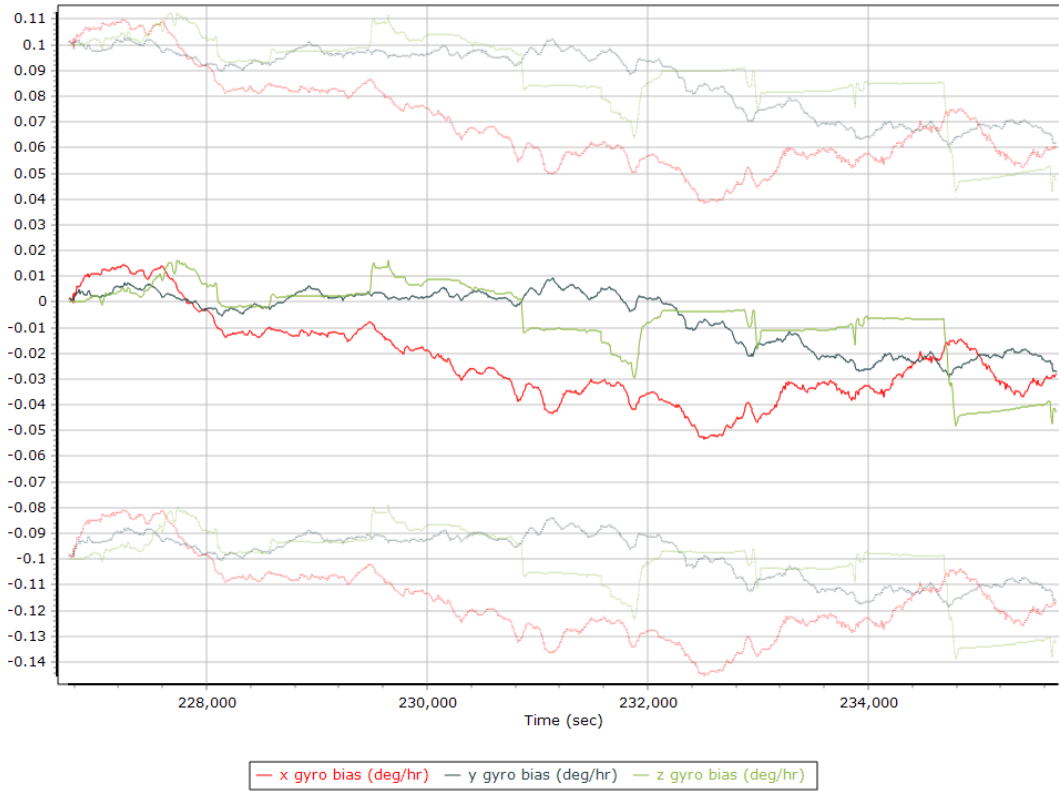
Y Accelerometer Scale Error (ppm)



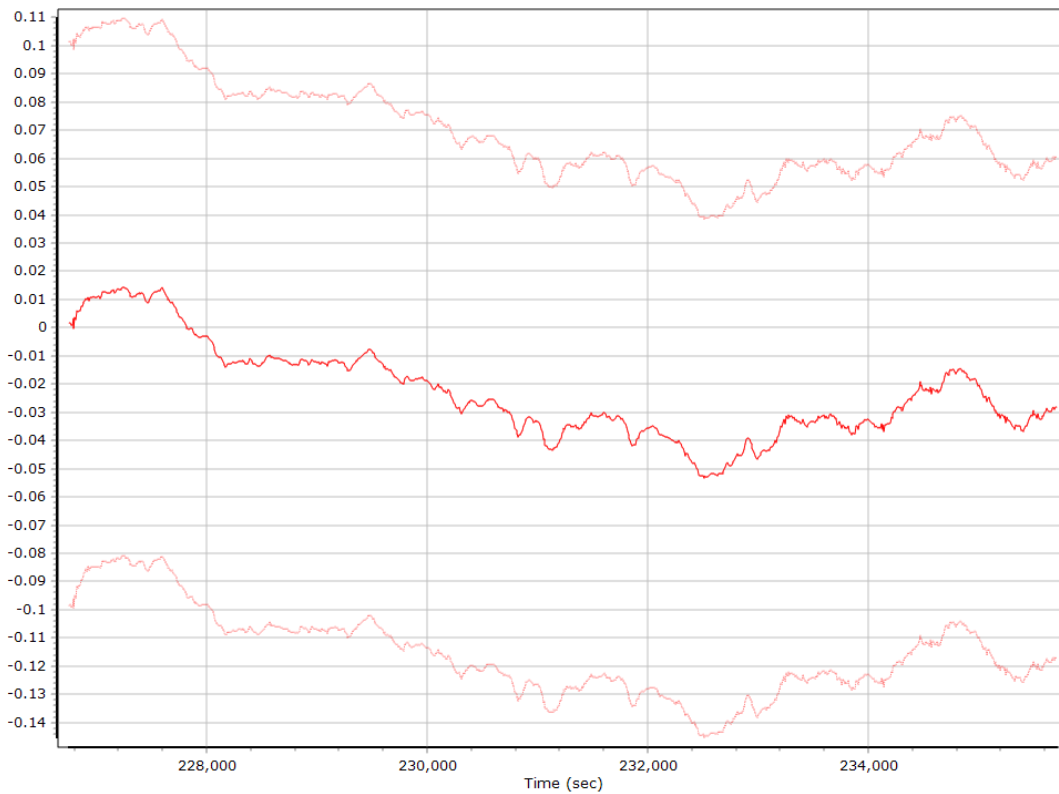
Z Accelerometer Scale Error (ppm)



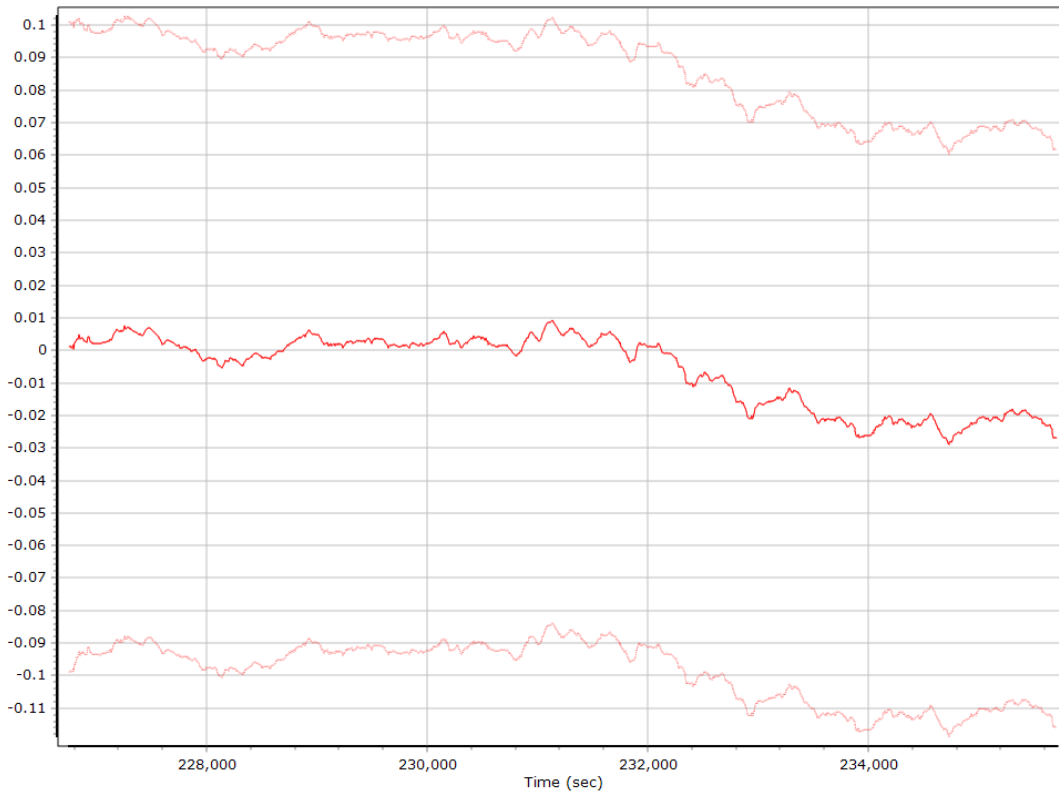
Gyro Bias (deg/h)



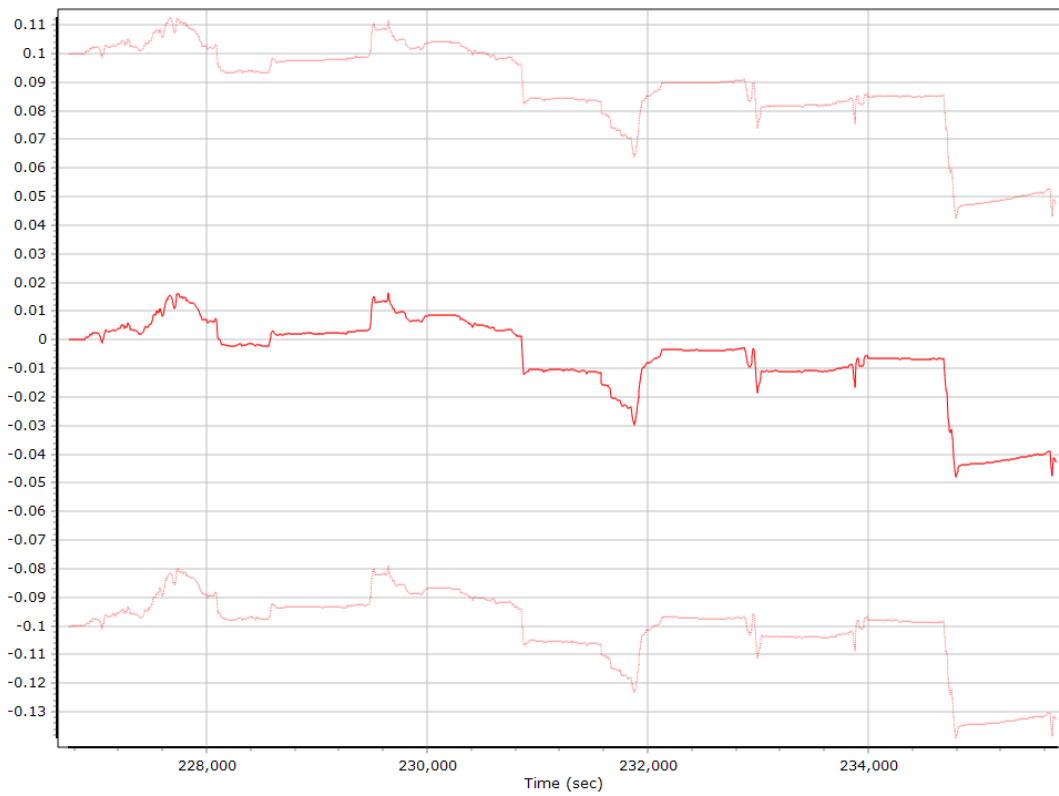
X Gyro Bias (deg/h)



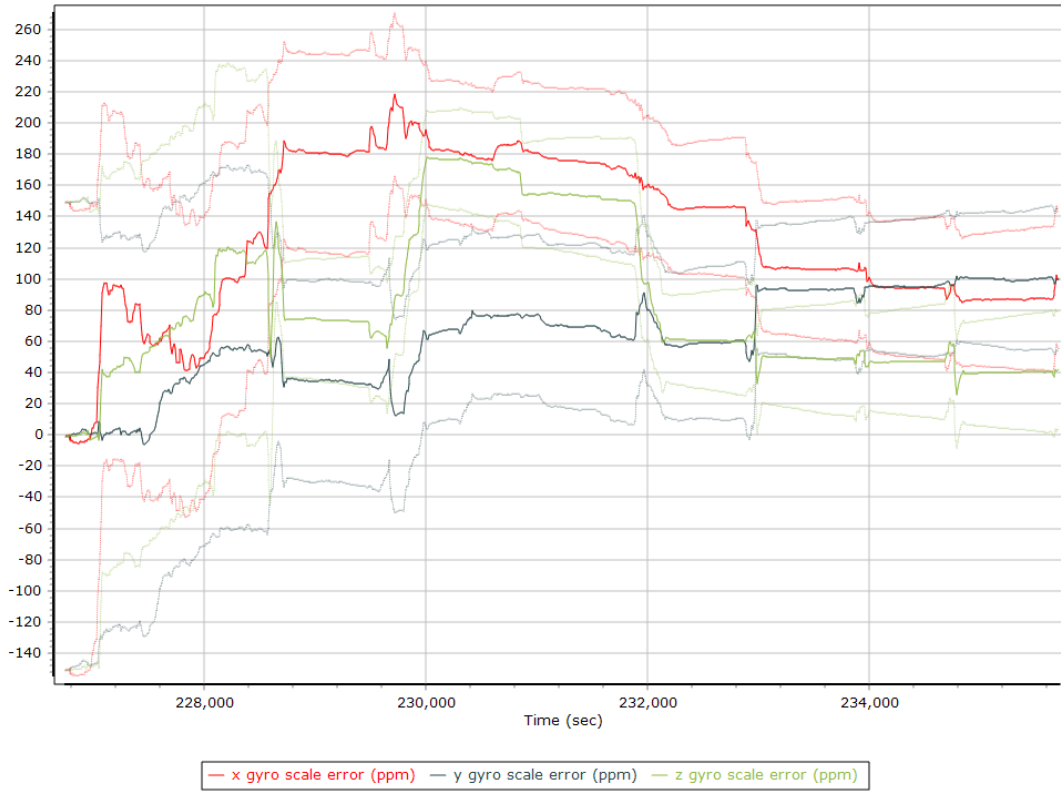
Y Gyro Bias (deg/h)



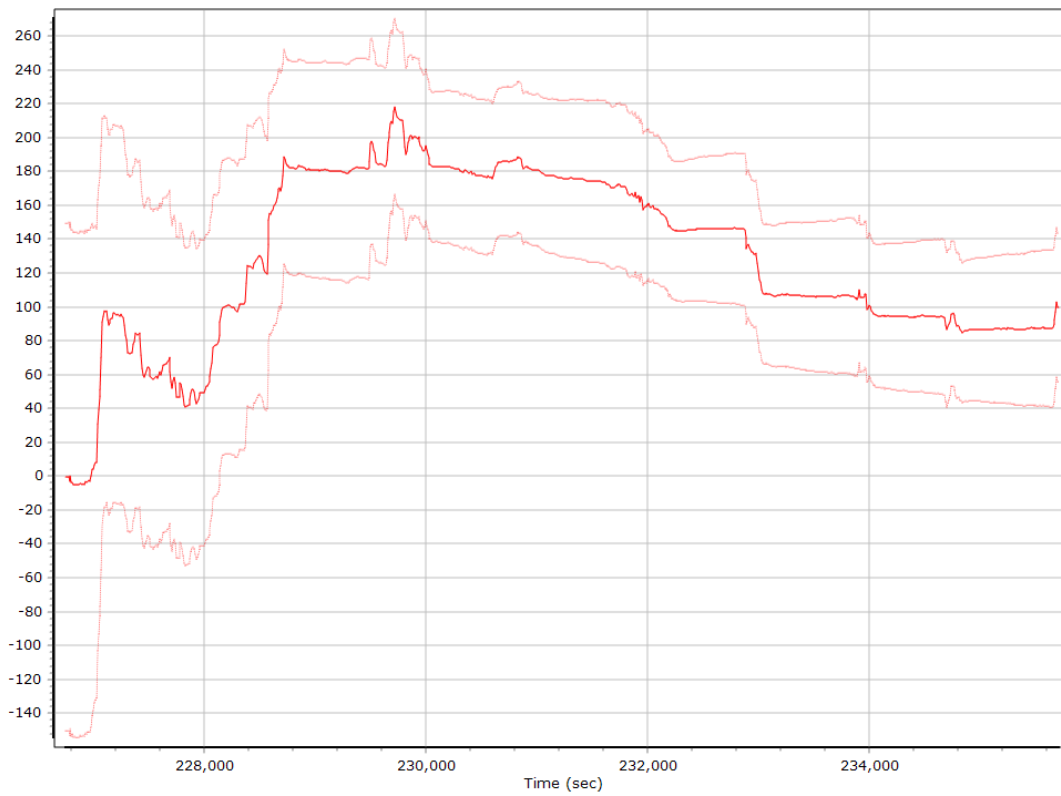
Z Gyro Bias (deg/h)



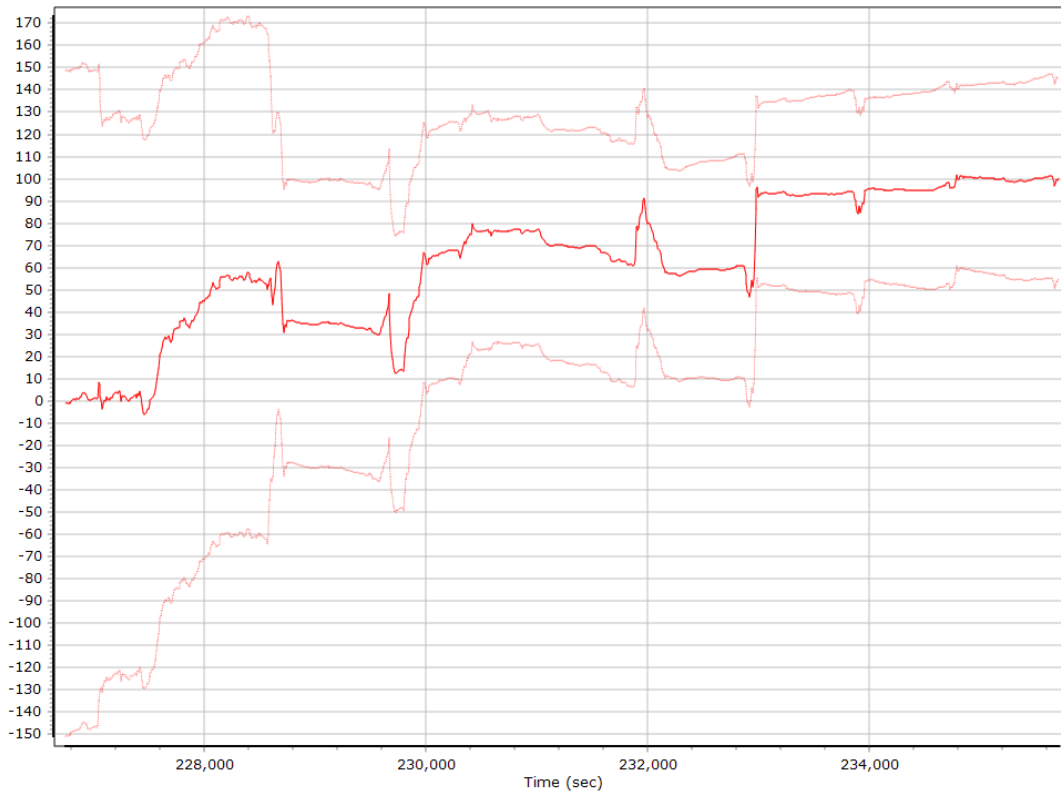
Gyro Scale Error (ppm)



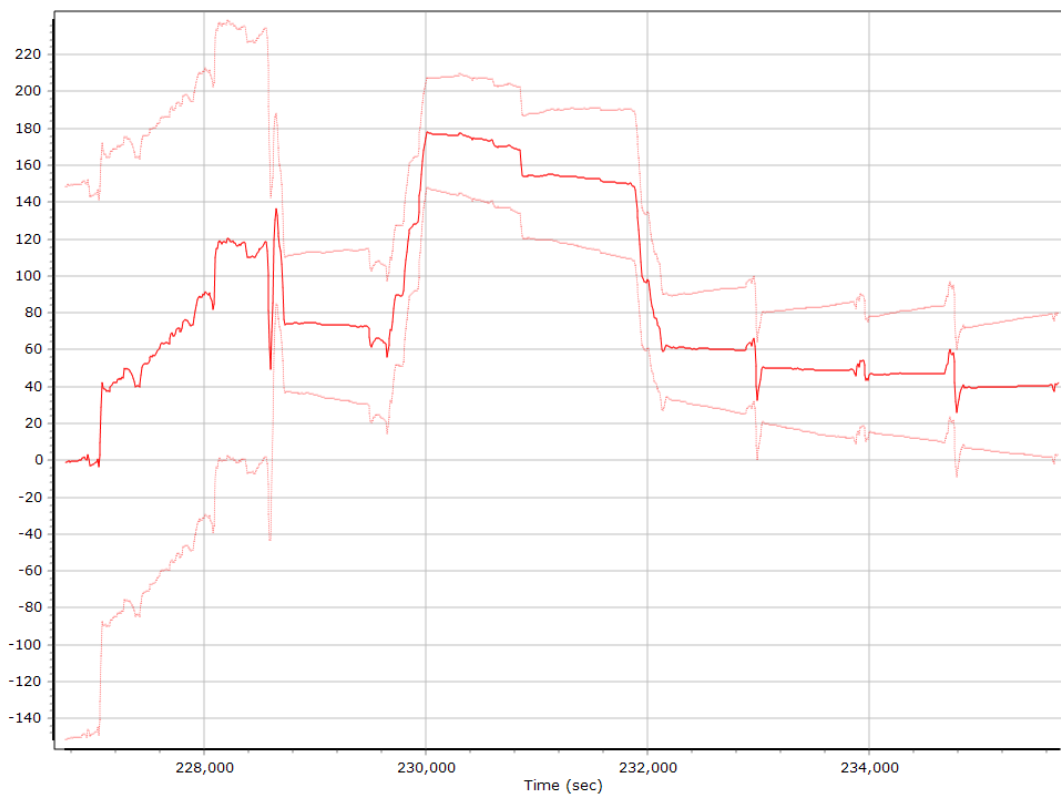
X Gyro Scale Error (ppm)



Y Gyro Scale Error (ppm)

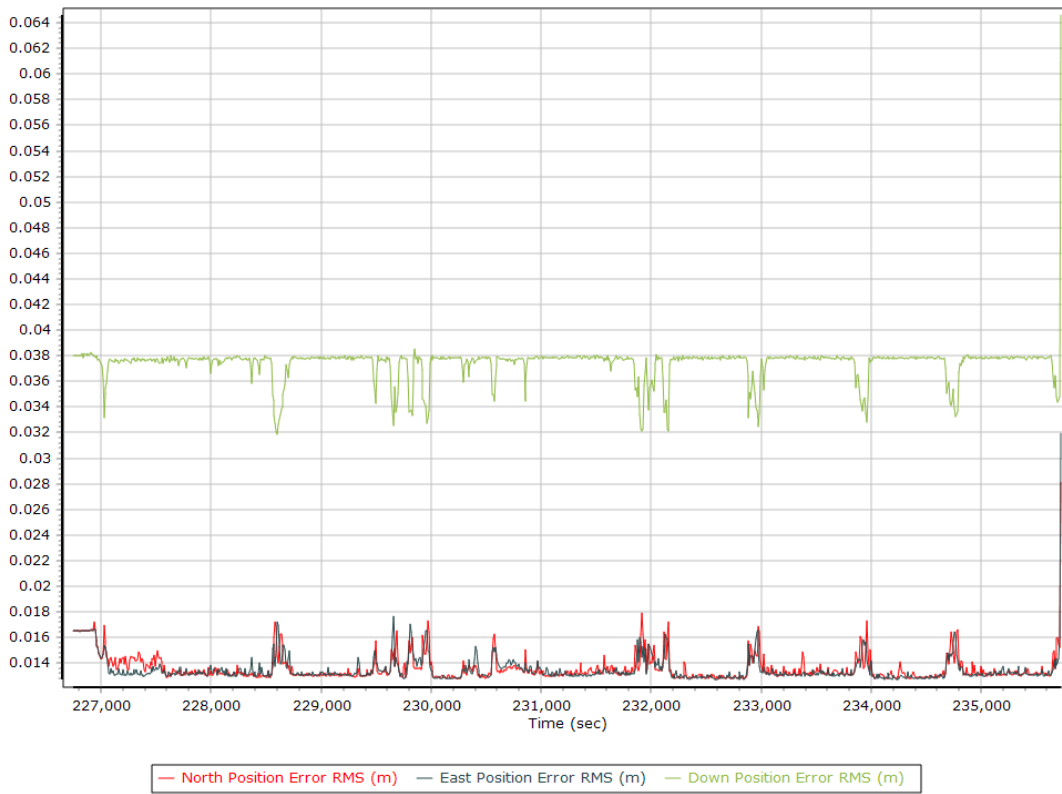


Z Gyro Scale Error (ppm)

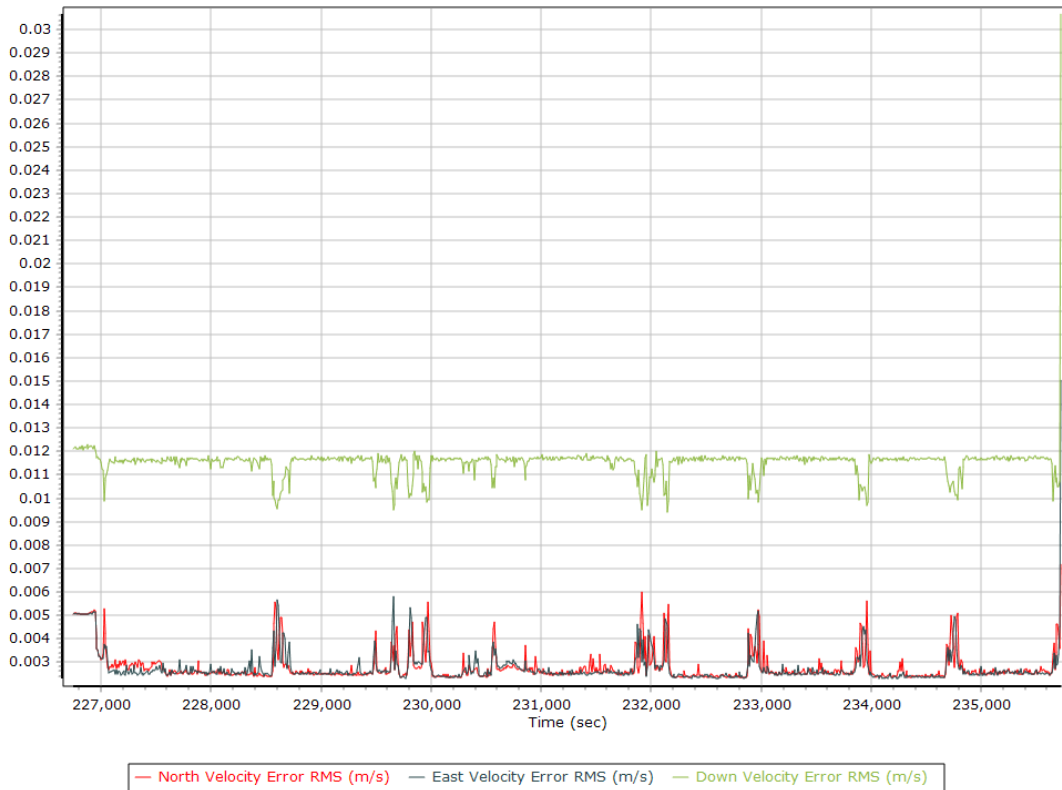


Smoothed Performance Metrics

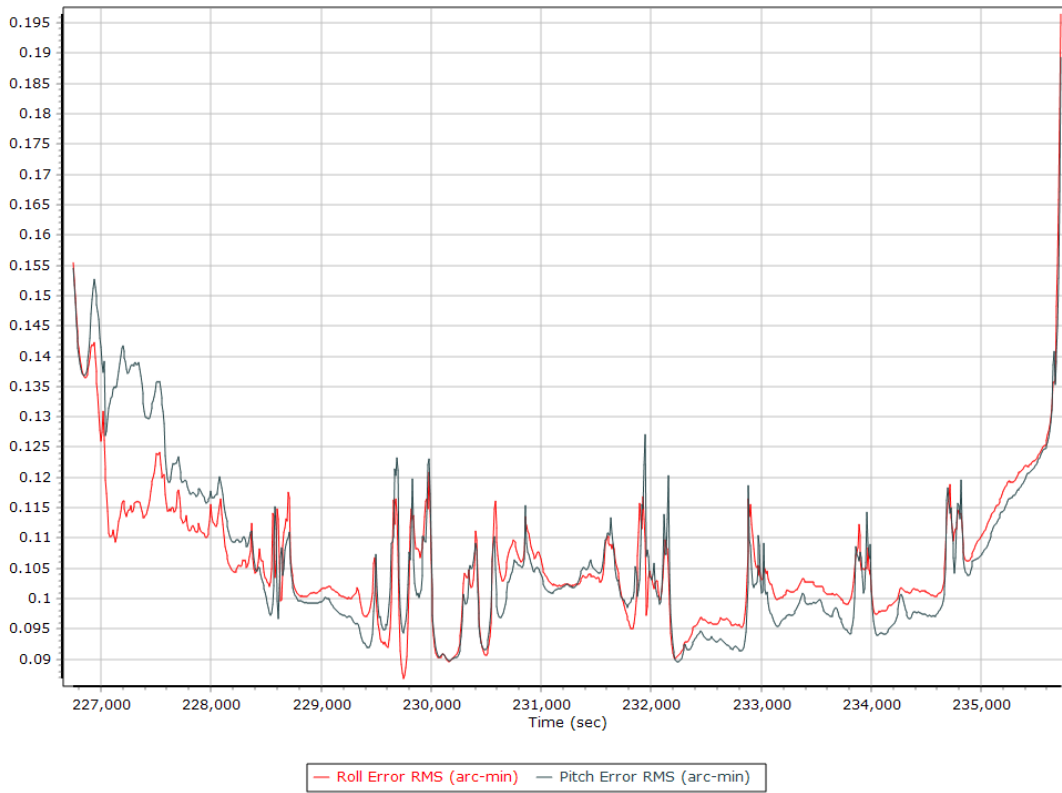
Position Error RMS (m)



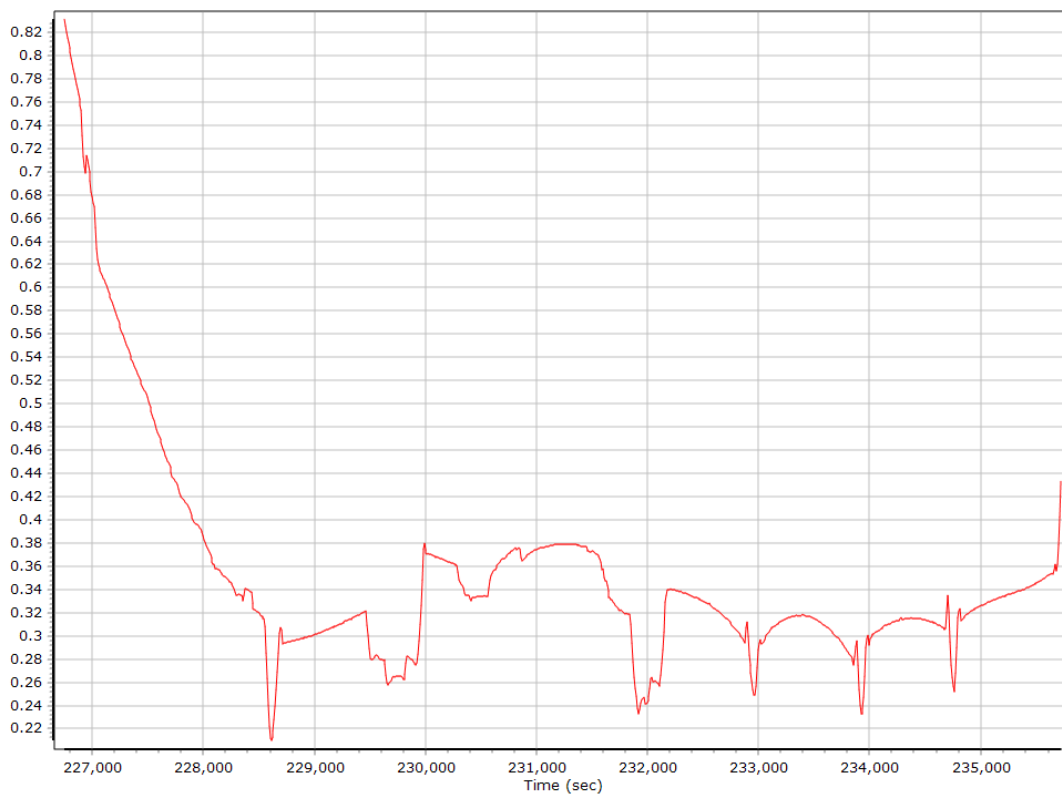
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

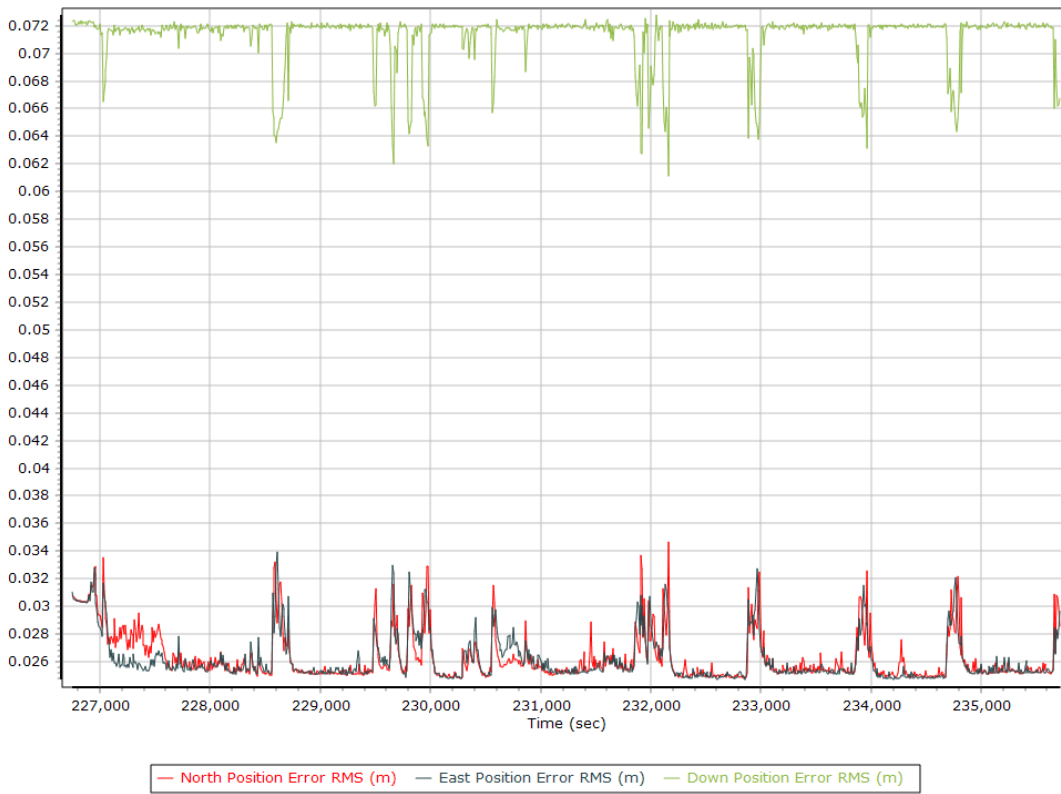


Heading Error RMS (arc-min)

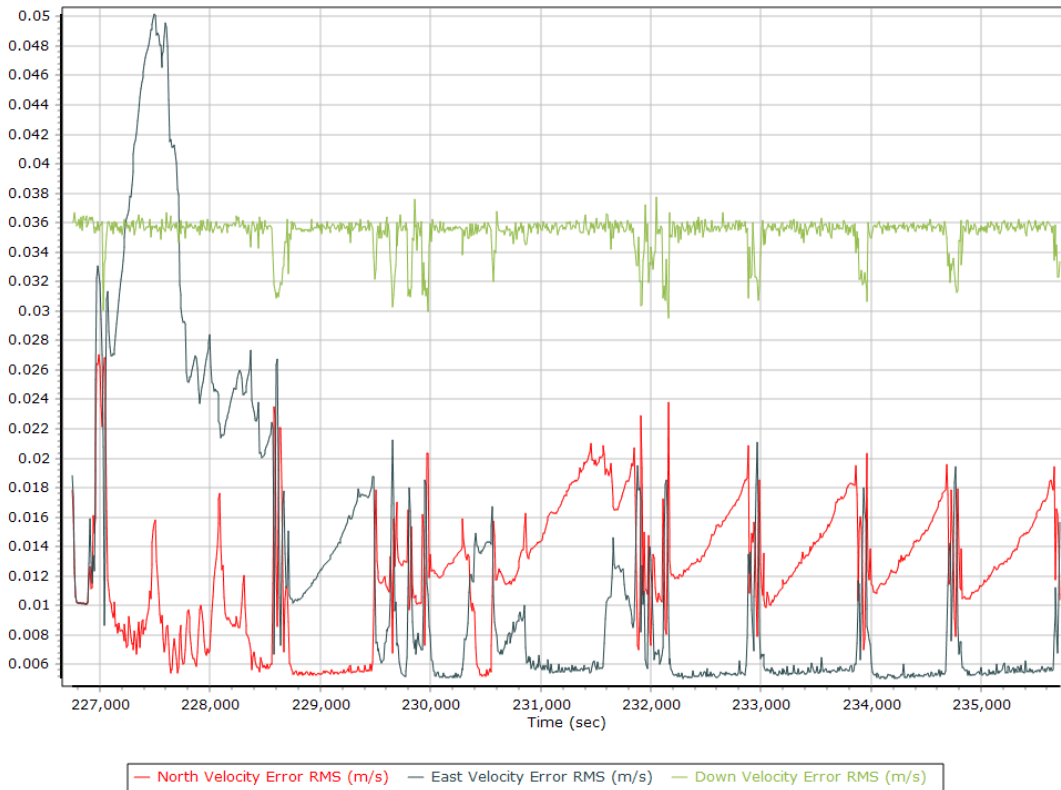


Forward Processed Performance Metrics

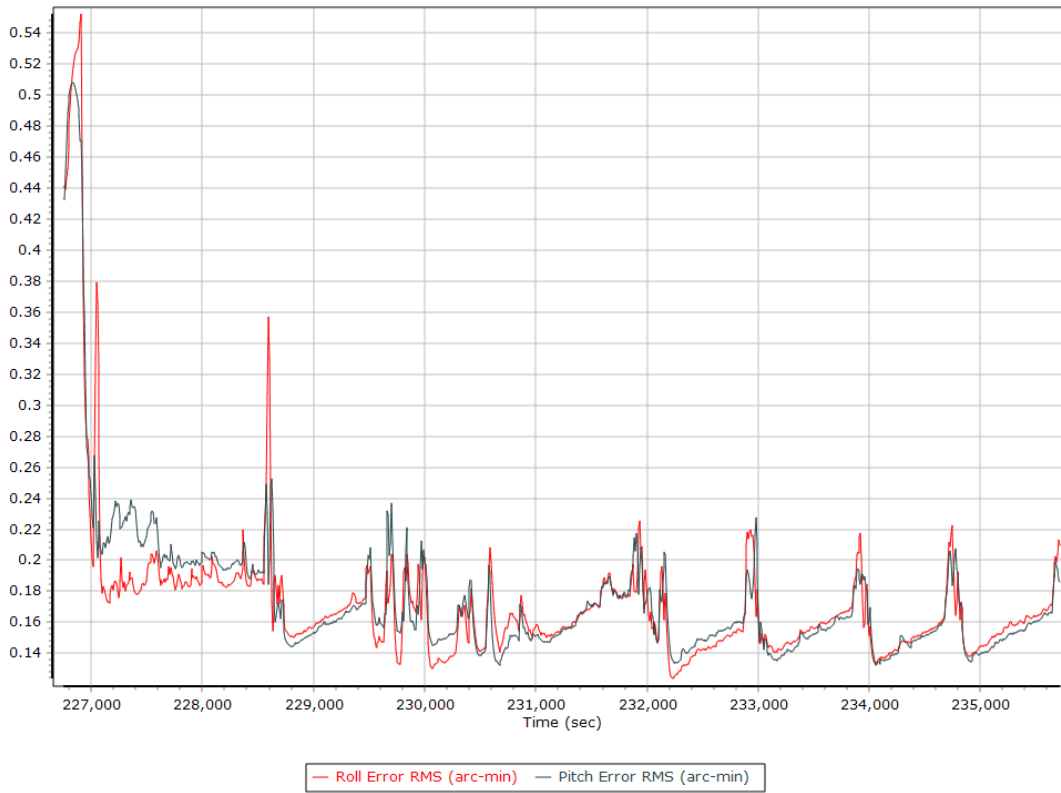
Position Error RMS (m)



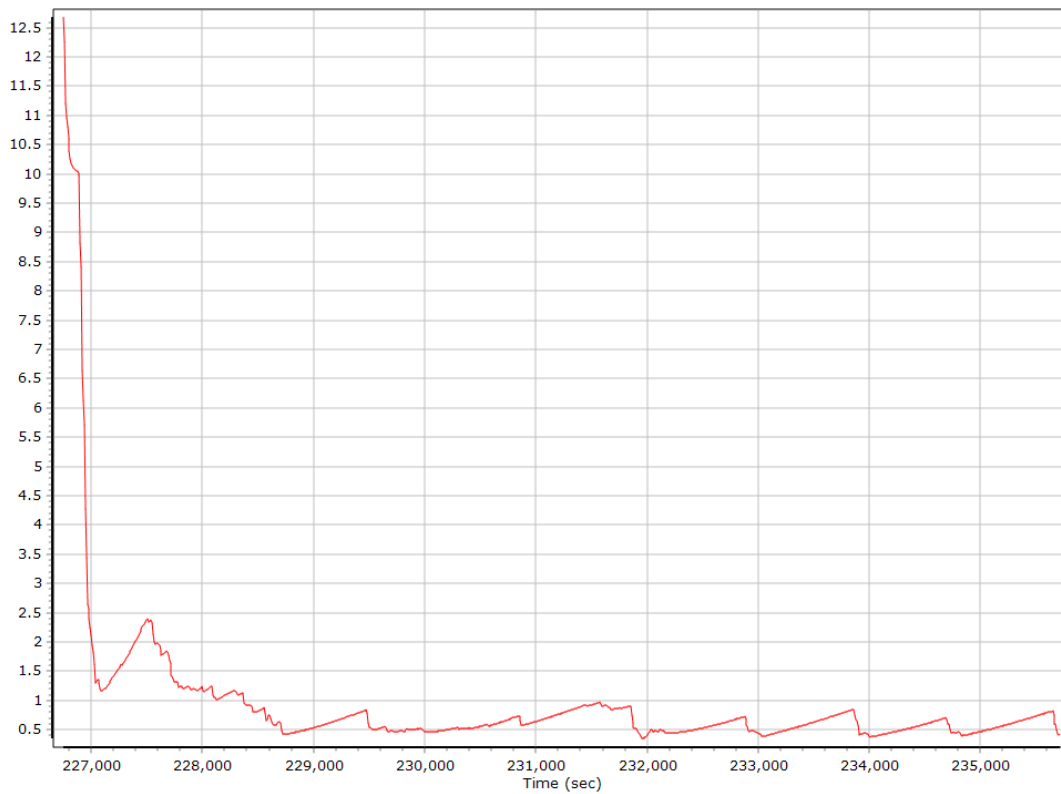
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

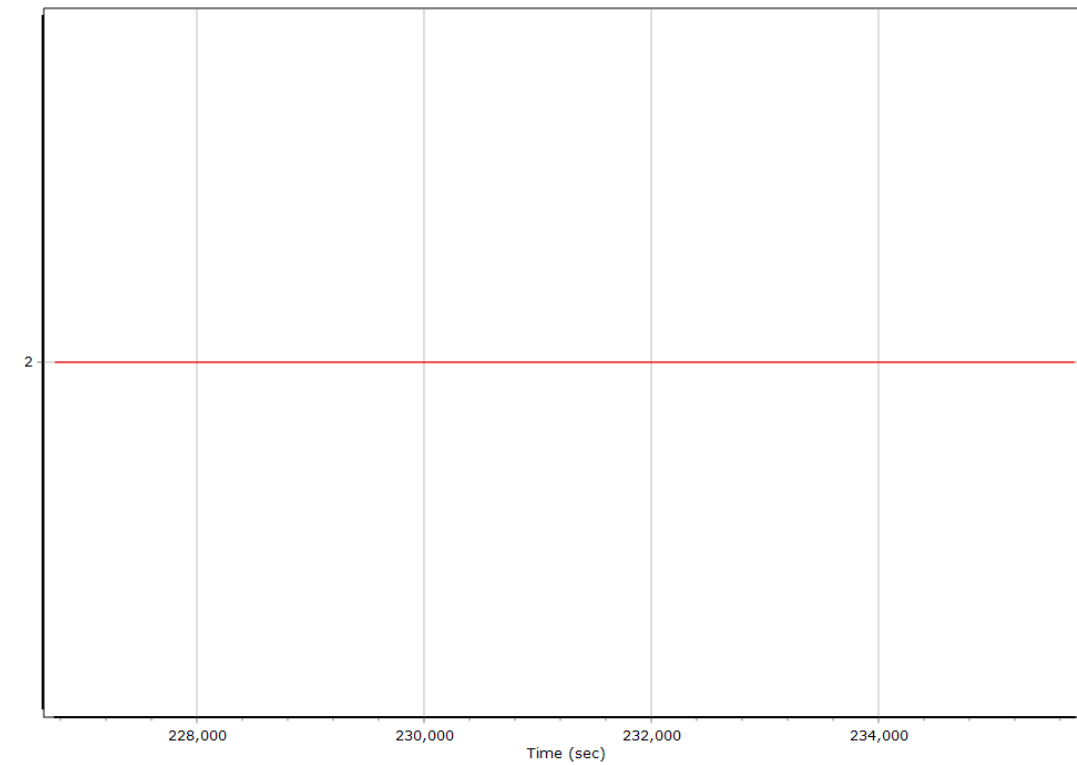


Heading Error RMS (arc-min)



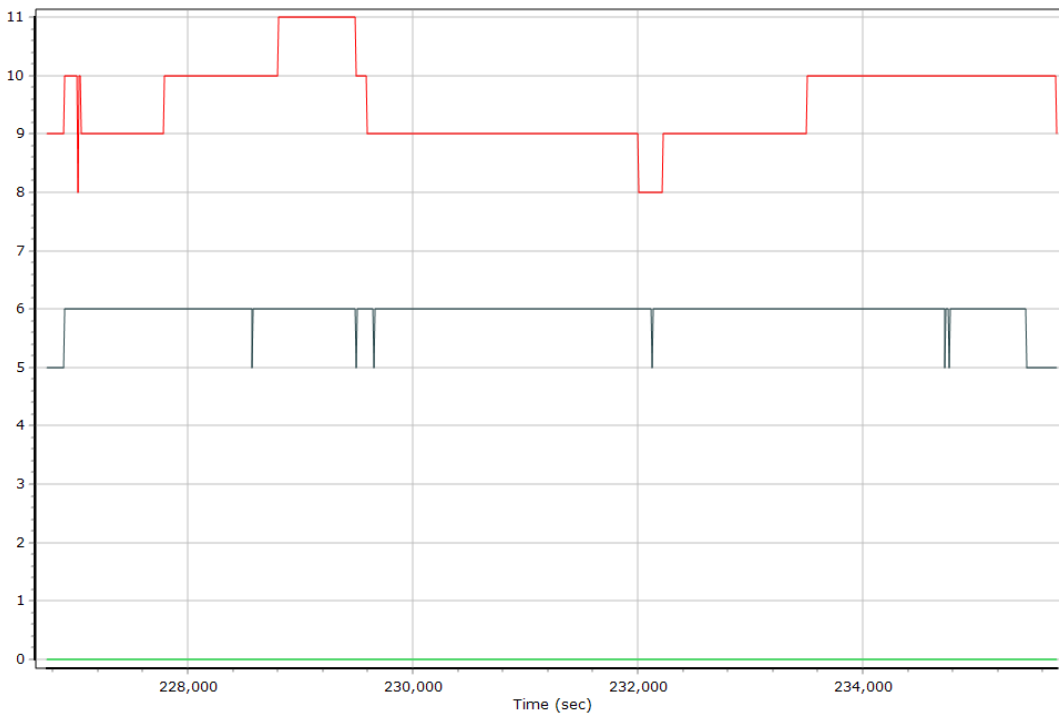
Forward Processed Solution Status

Processing Mode



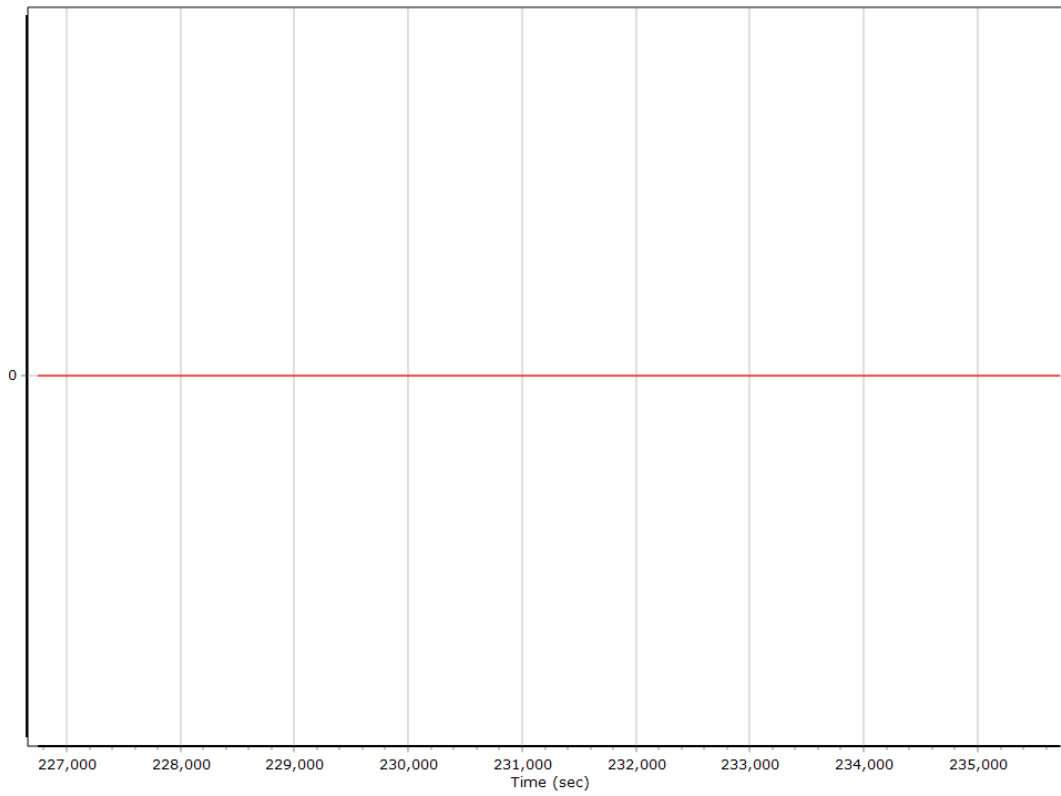
0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = C/A, 7 = GNSS Nav, 8 = DR

Number of Satellites



— Number of GPS Satellites — Number of GLONASS Satellites — Number of QZSS Satellites
 — Number of BEIDOU Satellites — Number of GALILEO Satellites

Baseline Length



General Information

Mission Information

Project name	21-081_210921b
Processing date	2021-10-20 17:02:02
Mission date	2021-09-21 17:42:43
Mission duration	04:13:37.000
Processing mode	IN-Fusion Trimble RTX Nav

Rover Hardware Information

Product	POS AV 610 VER6 HW2.5-12
Serial number	S/N11651
IMU type	57
Receiver type	BD982
Antenna type	AV39

Project File List

Rover Data Files

File name	File type
N62756.304	POS Data
N62756.305	
N62756.306	
N62756.307	
N62756.308	
N62756.309	
N62756.310	
N62756.311	
N62756.312	
N62756.313	
N62756.314	
N62756.315	
N62756.316	
N62756.317	
N62756.318	
N62756.319	
N62756.320	
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N62756.323	
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N62756.341	
N62756.342	
N62756.343	
N62756.344	
N62756.345	
N62756.346	
N62756.347	
N62756.348	
N62756.349	
N62756.350	
N62756.351	

Input Files

File Name	File Type
Ephm2640.21g	GLONASS Broadcast Ephemeris
Ephm2640.21n	GPS Broadcast Ephemeris
igl21761.sp3	GLONASS Precise Ephemeris
igl21762.sp3	GLONASS Precise Ephemeris
igl21763.sp3	GLONASS Precise Ephemeris
igs21761.sp3	GPS Precise Ephemeris
igs21762.sp3	GPS Precise Ephemeris
igs21763.sp3	GPS Precise Ephemeris

Output Files

Filename	File type
sbet_21-081_210921b.out	SBET Trajectory File

Rover Data Summary

First raw data file	N62756.304		
Last raw data file	N62756.351		
Start GPS week	2176		
Start time	236556.589 (09/21/2021 17:42:36)		
End time	251762.428 (09/21/2021 21:56:02)		
Start of fine alignment	236611.484 (09/21/2021 17:43:31)		
Available subsystems	Primary GNSS, Gimbal, IMU		
POS Event Input	None		
Correction data	Trimble RTX		
IMU Installation Lever Arms & Mounting Angles			
Gimbal to IMU lever arm (m)	-0.034	-0.010	-0.374
Gimbal to IMU mounting angles (deg)	0.000	0.000	0.000
Gimbal to Primary GNSS lever arm (m)	0.980	-0.102	-1.276
Gimbal to Primary GNSS lever arm std dev (m)	-1.000		
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

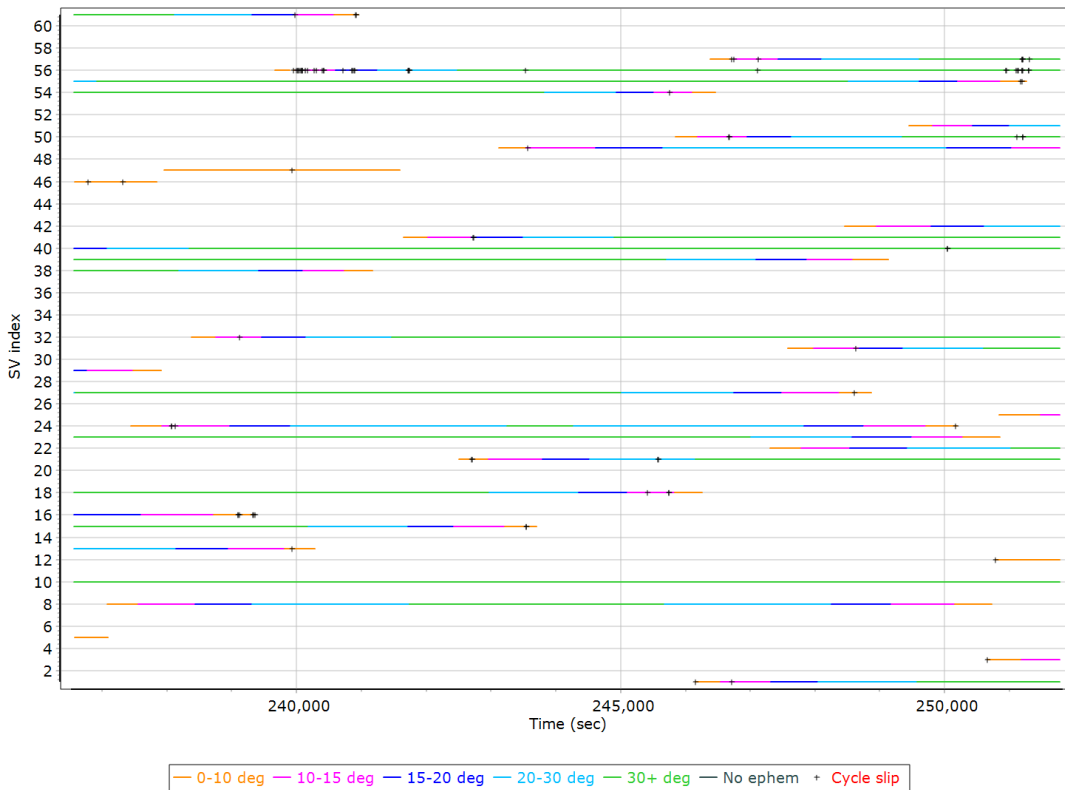
Rover Data QC

Raw IMU Import QC Summary

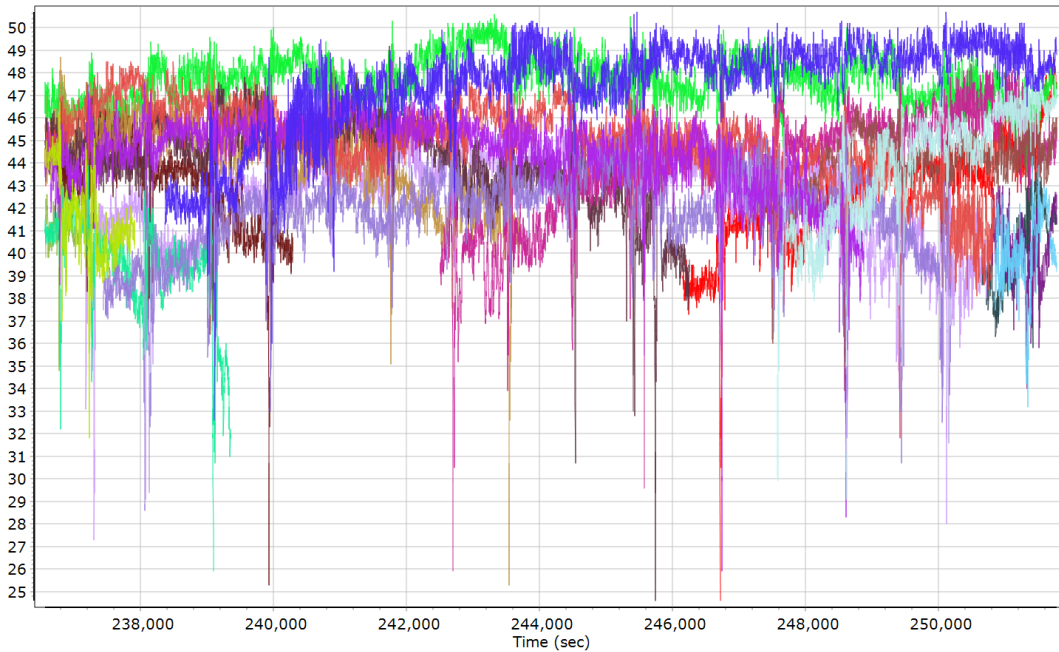
IMU data input file	imu_21-081_210921b.dat
IMU data check log file	imudt_21-081_210921b.log
IMU Records Processed	3043032
Termination Status	Warnings
IMU Anomalies	1
IMU Failure Messages	
236556.429 : WARNING : Gap of 236544.4726 seconds in CHECKDT input data	

Primary Observables & Satellite Data

GPS/GLONASS L1 Satellite Lock/Elevation

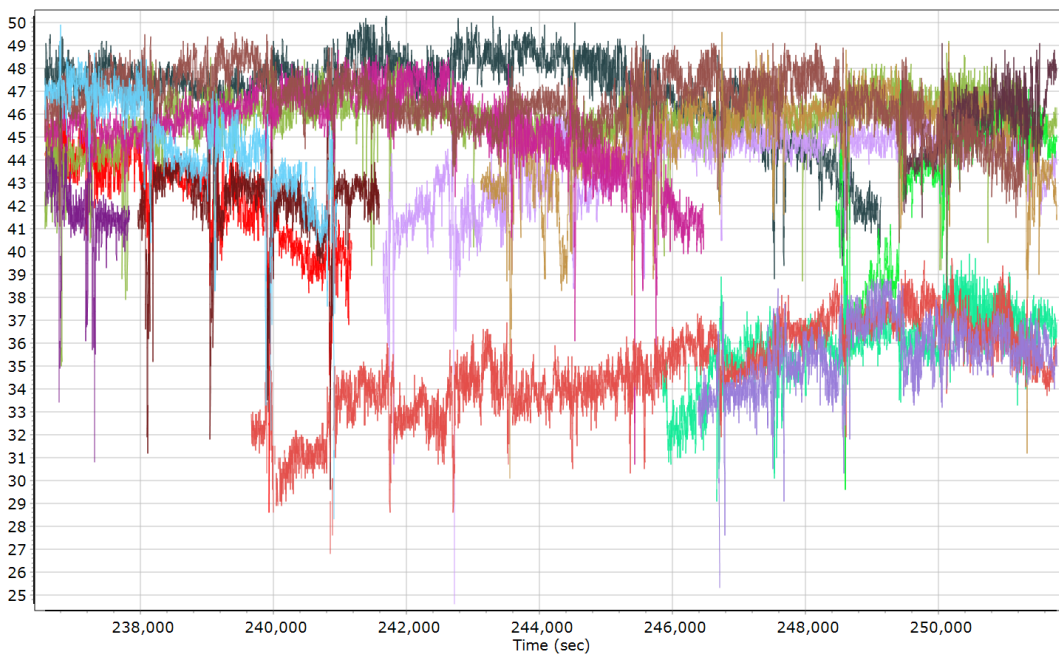


GPS L1 SNR



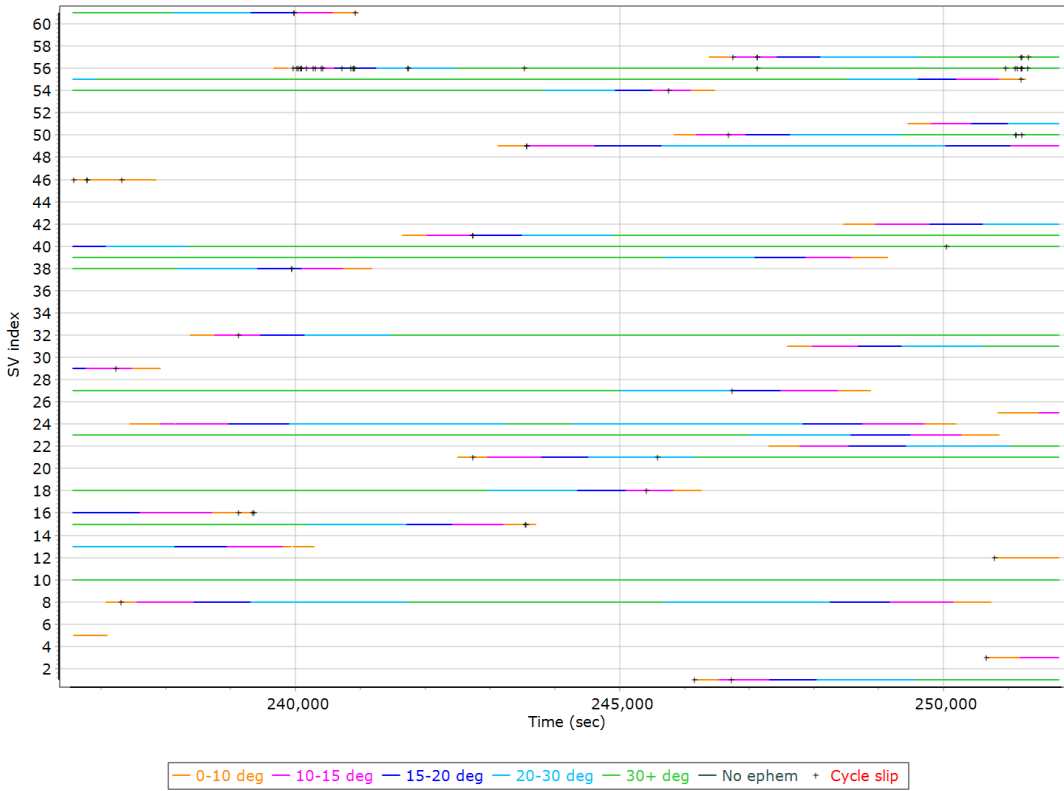
- | | | | |
|---------------------------|---------------------------|---------------------------|---------------------------|
| GPS PRN 01 L1 SNR (dB/Hz) | GPS PRN 03 L1 SNR (dB/Hz) | GPS PRN 05 L1 SNR (dB/Hz) | GPS PRN 08 L1 SNR (dB/Hz) |
| GPS PRN 10 L1 SNR (dB/Hz) | GPS PRN 12 L1 SNR (dB/Hz) | GPS PRN 13 L1 SNR (dB/Hz) | GPS PRN 15 L1 SNR (dB/Hz) |
| GPS PRN 16 L1 SNR (dB/Hz) | GPS PRN 18 L1 SNR (dB/Hz) | GPS PRN 21 L1 SNR (dB/Hz) | GPS PRN 22 L1 SNR (dB/Hz) |
| GPS PRN 23 L1 SNR (dB/Hz) | GPS PRN 24 L1 SNR (dB/Hz) | GPS PRN 25 L1 SNR (dB/Hz) | GPS PRN 27 L1 SNR (dB/Hz) |
| GPS PRN 29 L1 SNR (dB/Hz) | GPS PRN 31 L1 SNR (dB/Hz) | GPS PRN 32 L1 SNR (dB/Hz) | |

GLONASS L1 SNR

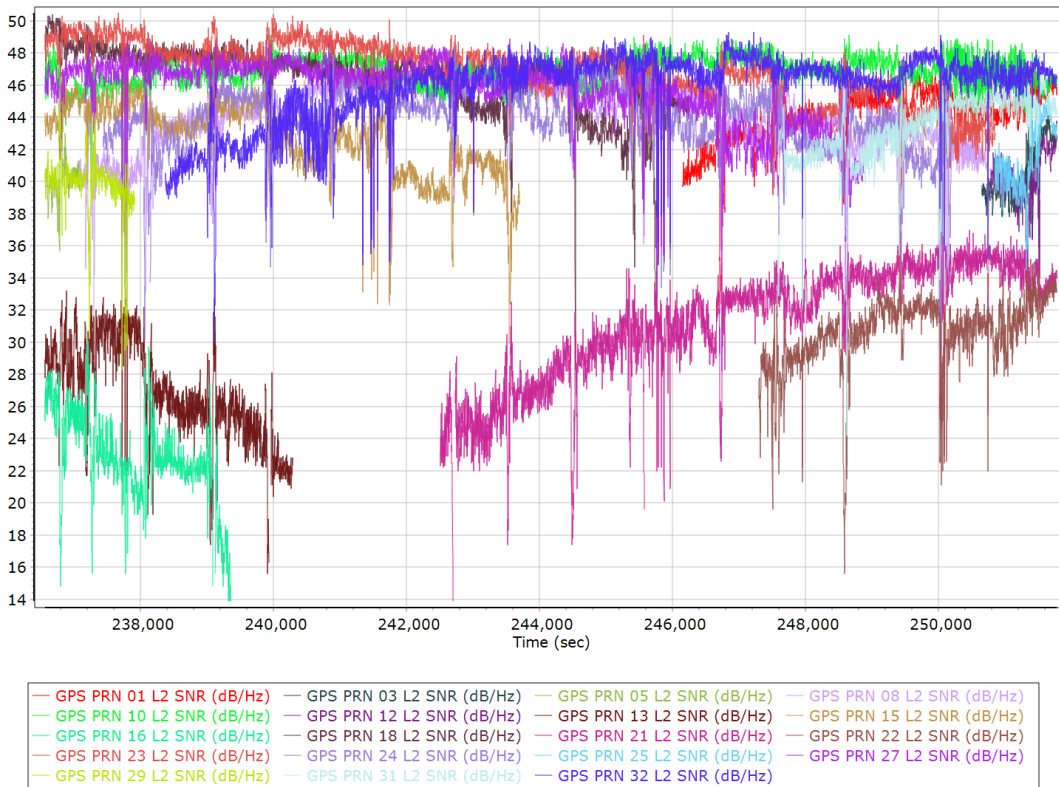


- | | | |
|---------------------------|---------------------------|---------------------------|
| GLONASS 01 L1 SNR (dB/Hz) | GLONASS 02 L1 SNR (dB/Hz) | GLONASS 03 L1 SNR (dB/Hz) |
| GLONASS 04 L1 SNR (dB/Hz) | GLONASS 05 L1 SNR (dB/Hz) | GLONASS 09 L1 SNR (dB/Hz) |
| GLONASS 10 L1 SNR (dB/Hz) | GLONASS 12 L1 SNR (dB/Hz) | GLONASS 13 L1 SNR (dB/Hz) |
| GLONASS 14 L1 SNR (dB/Hz) | GLONASS 17 L1 SNR (dB/Hz) | GLONASS 18 L1 SNR (dB/Hz) |
| GLONASS 19 L1 SNR (dB/Hz) | GLONASS 20 L1 SNR (dB/Hz) | GLONASS 24 L1 SNR (dB/Hz) |

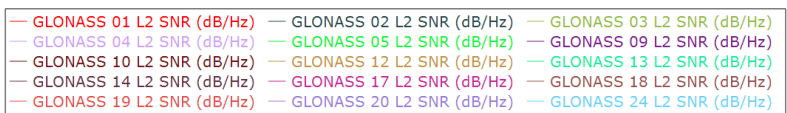
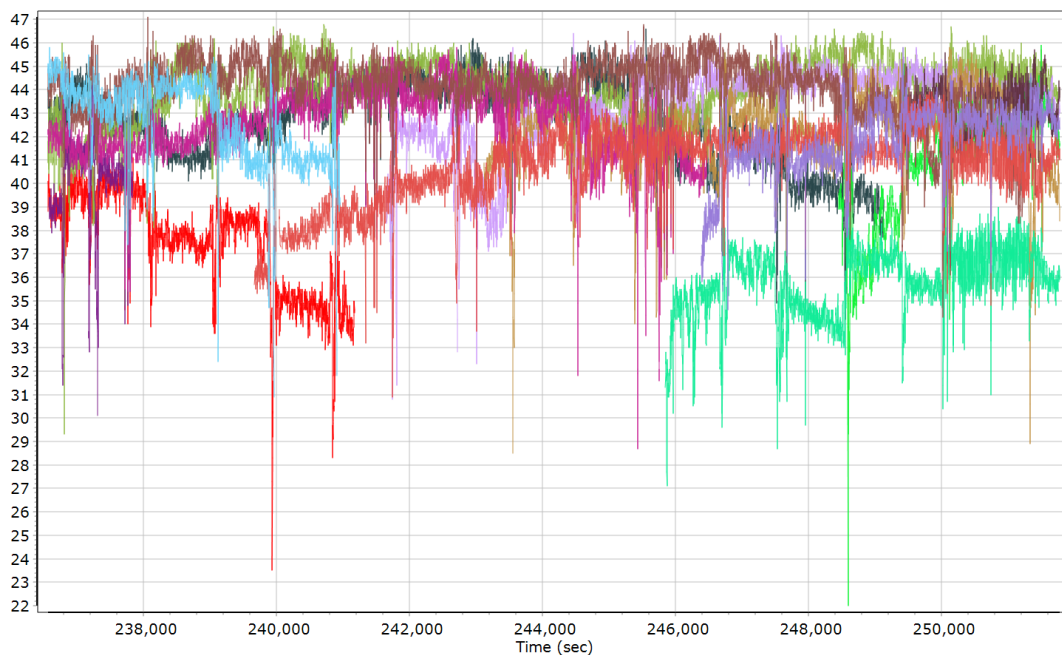
GPS/GLONASS L2 Satellite Lock/Elevation



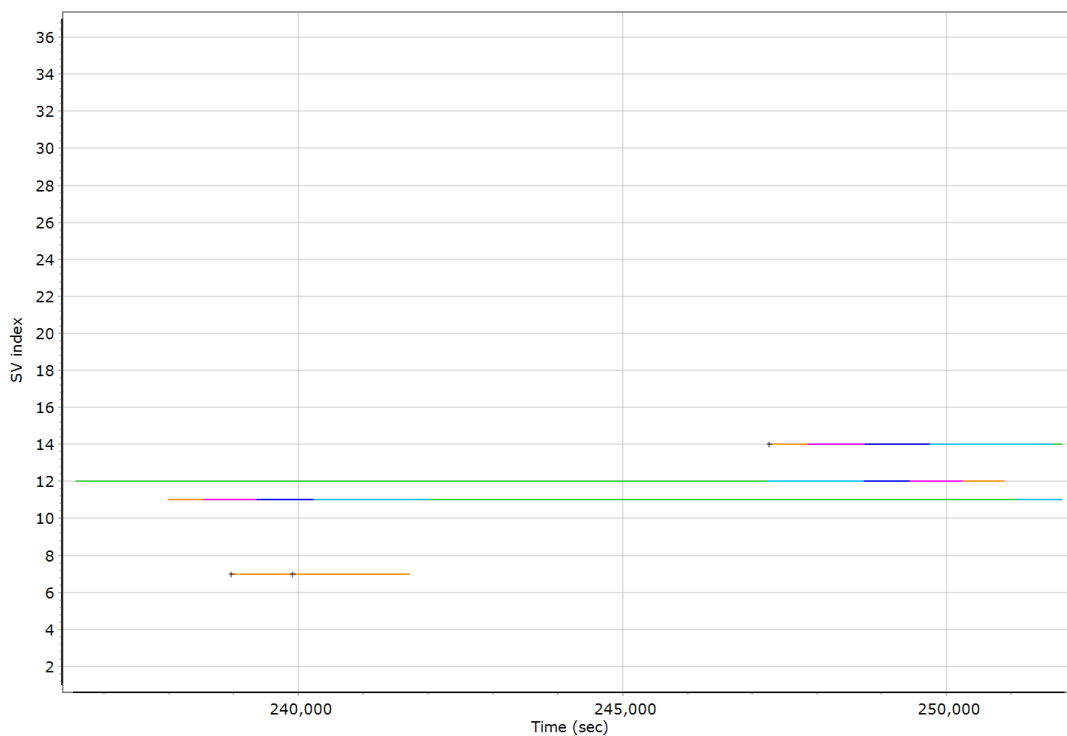
GPS L2 SNR



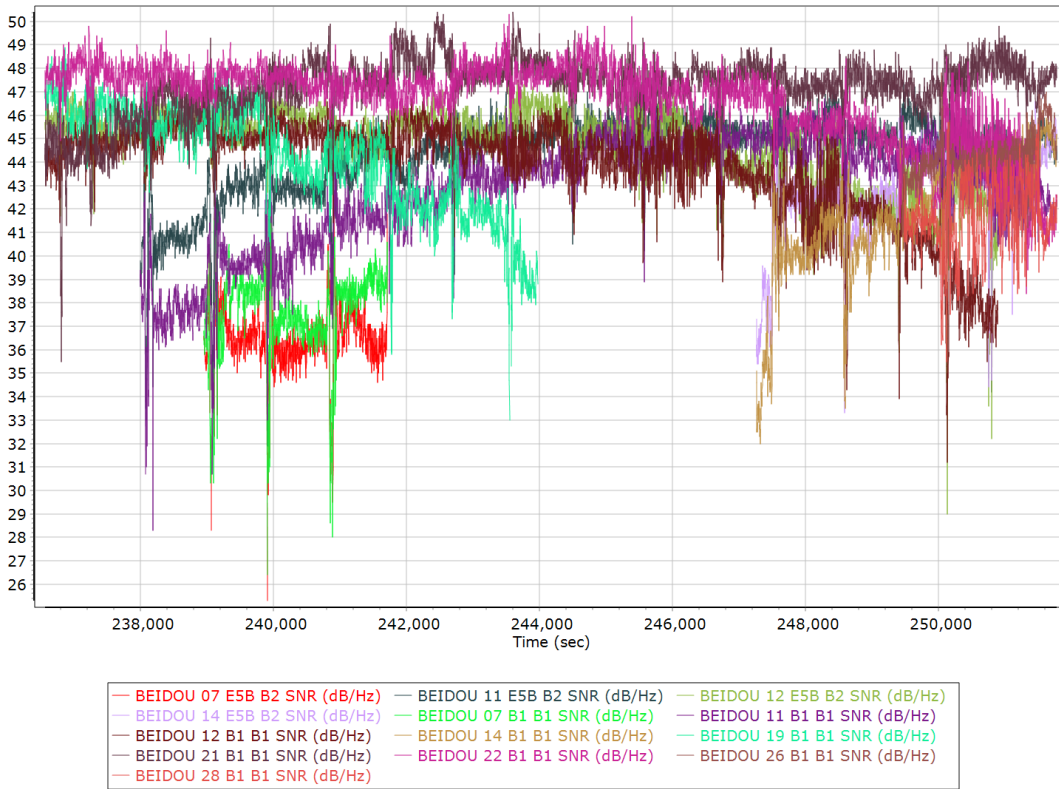
GLONASS L2 SNR



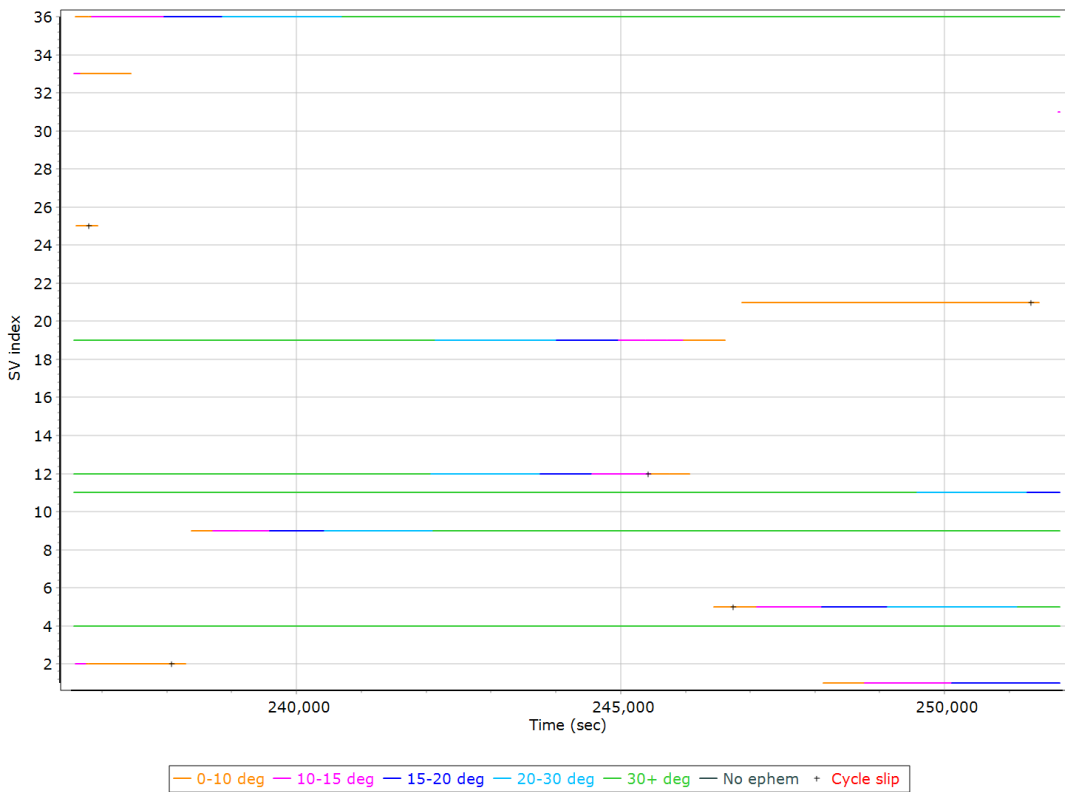
BEIDOU Satellite Lock/Elevation



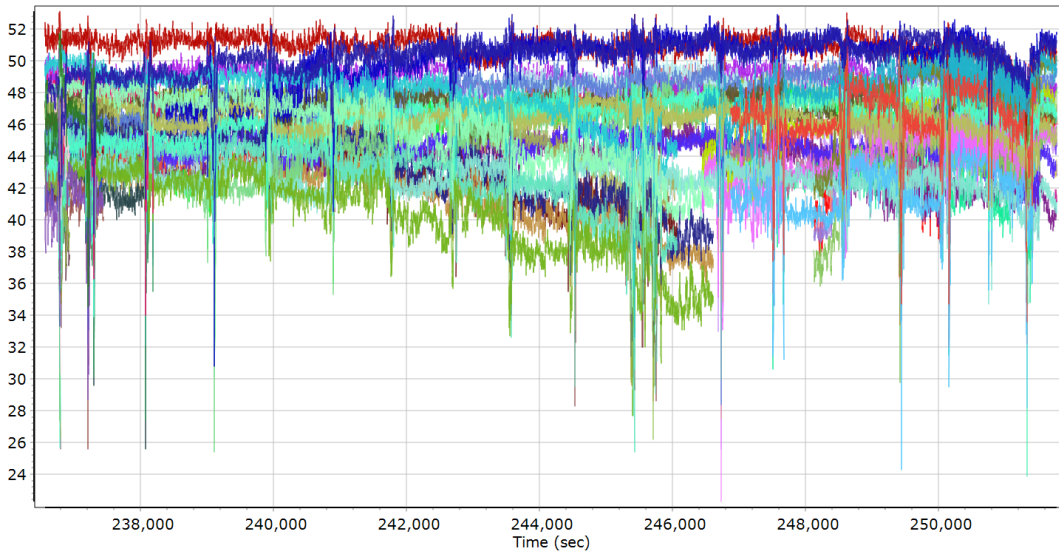
BEIDOU SNR



GALILEO Satellite Lock/Elevation



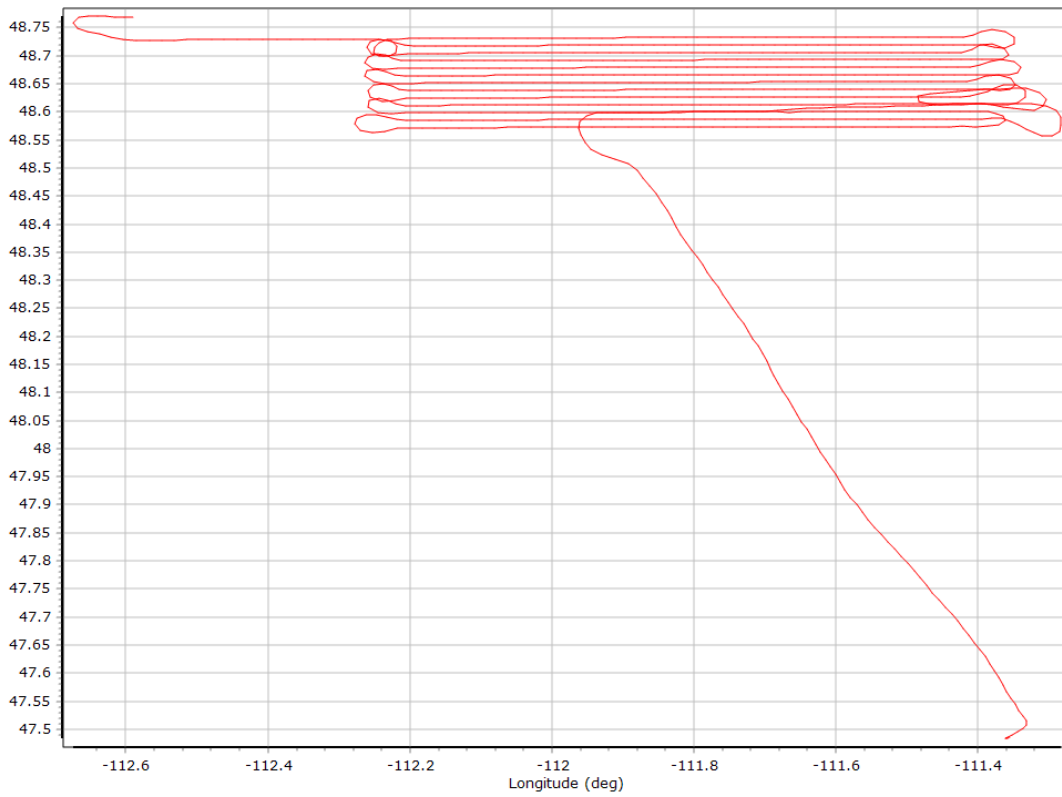
GALILEO SNR



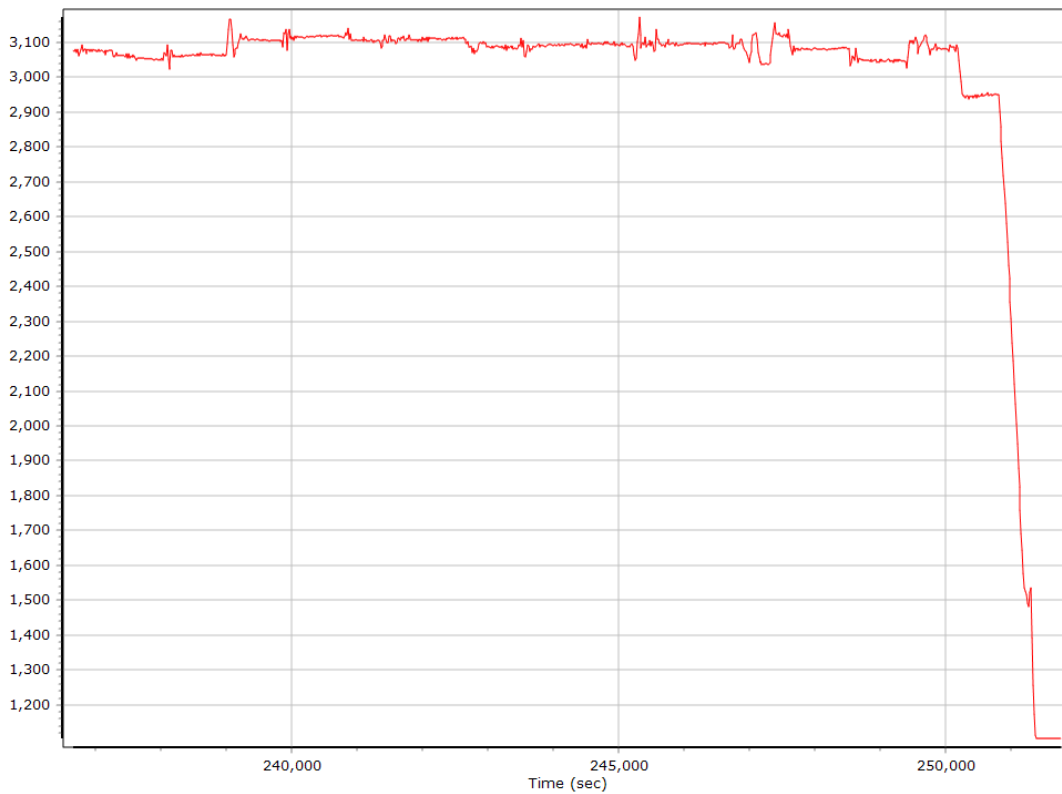
- | | |
|---|---|
| — GALILEO 01 L1 BOC_1_1_DP_MBOC SNR (dB/Hz) | — GALILEO 02 L1 BOC_1_1_DP_MBOC SNR (dB/Hz) |
| — GALILEO 04 L1 BOC_1_1_DP_MBOC SNR (dB/Hz) | — GALILEO 05 L1 BOC_1_1_DP_MBOC SNR (dB/Hz) |
| — GALILEO 09 L1 BOC_1_1_DP_MBOC SNR (dB/Hz) | — GALILEO 11 L1 BOC_1_1_DP_MBOC SNR (dB/Hz) |
| — GALILEO 12 L1 BOC_1_1_DP_MBOC SNR (dB/Hz) | — GALILEO 19 L1 BOC_1_1_DP_MBOC SNR (dB/Hz) |
| — GALILEO 21 L1 BOC_1_1_DP_MBOC SNR (dB/Hz) | — GALILEO 25 L1 BOC_1_1_DP_MBOC SNR (dB/Hz) |
| — GALILEO 31 L1 BOC_1_1_DP_MBOC SNR (dB/Hz) | — GALILEO 33 L1 BOC_1_1_DP_MBOC SNR (dB/Hz) |
| — GALILEO 36 L1 BOC_1_1_DP_MBOC SNR (dB/Hz) | — GALILEO 01 L5E5A BPSK10_PD SNR (dB/Hz) |
| — GALILEO 02 L5E5A BPSK10_PD SNR (dB/Hz) | — GALILEO 04 L5E5A BPSK10_PD SNR (dB/Hz) |
| — GALILEO 05 L5E5A BPSK10_PD SNR (dB/Hz) | — GALILEO 09 L5E5A BPSK10_PD SNR (dB/Hz) |
| — GALILEO 11 L5E5A BPSK10_PD SNR (dB/Hz) | — GALILEO 12 L5E5A BPSK10_PD SNR (dB/Hz) |

Smoothed Trajectory Information

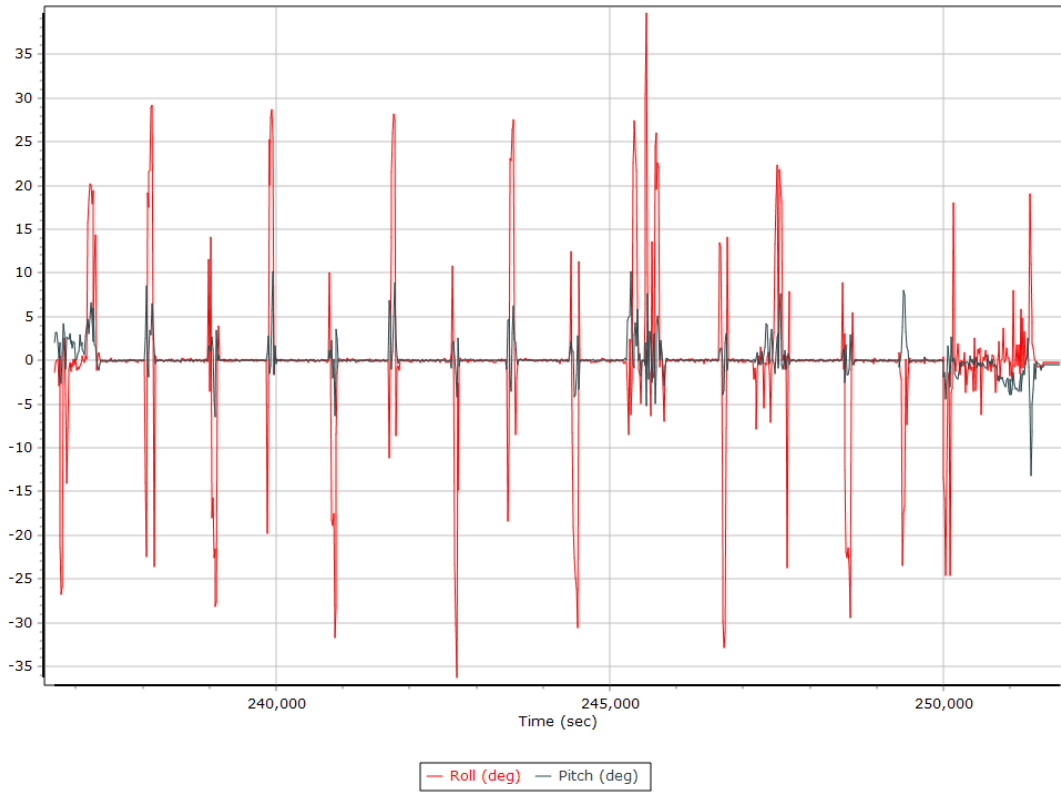
Top View



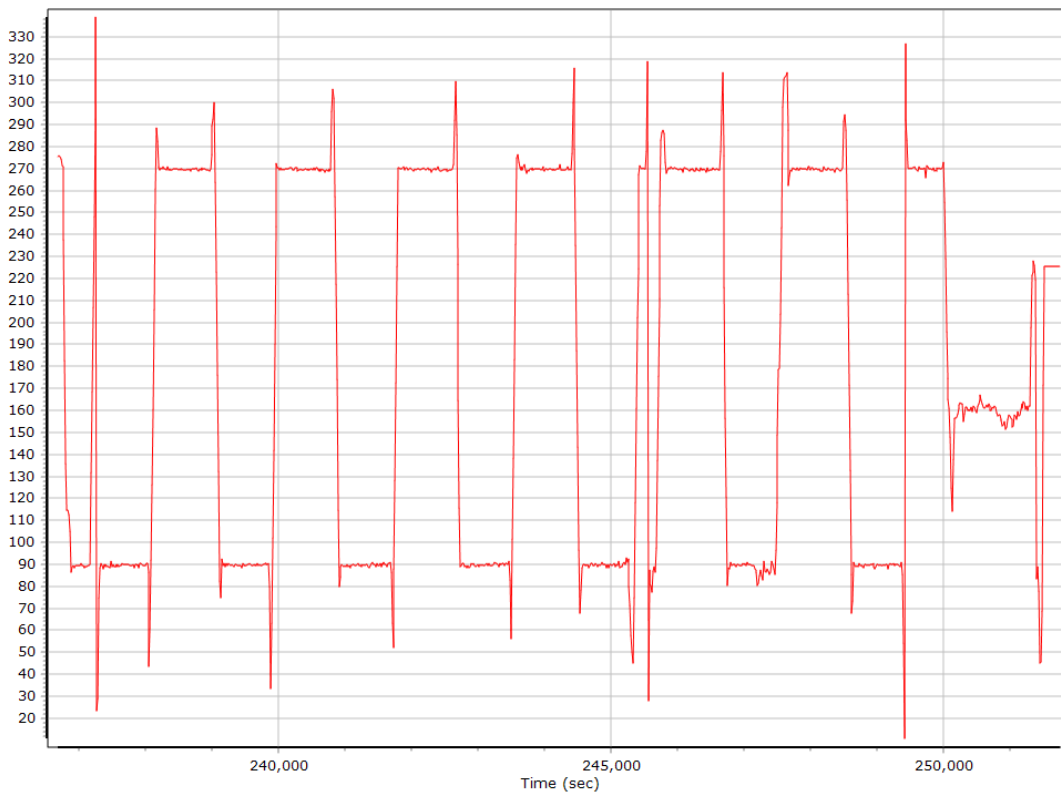
Altitude



Roll/Pitch



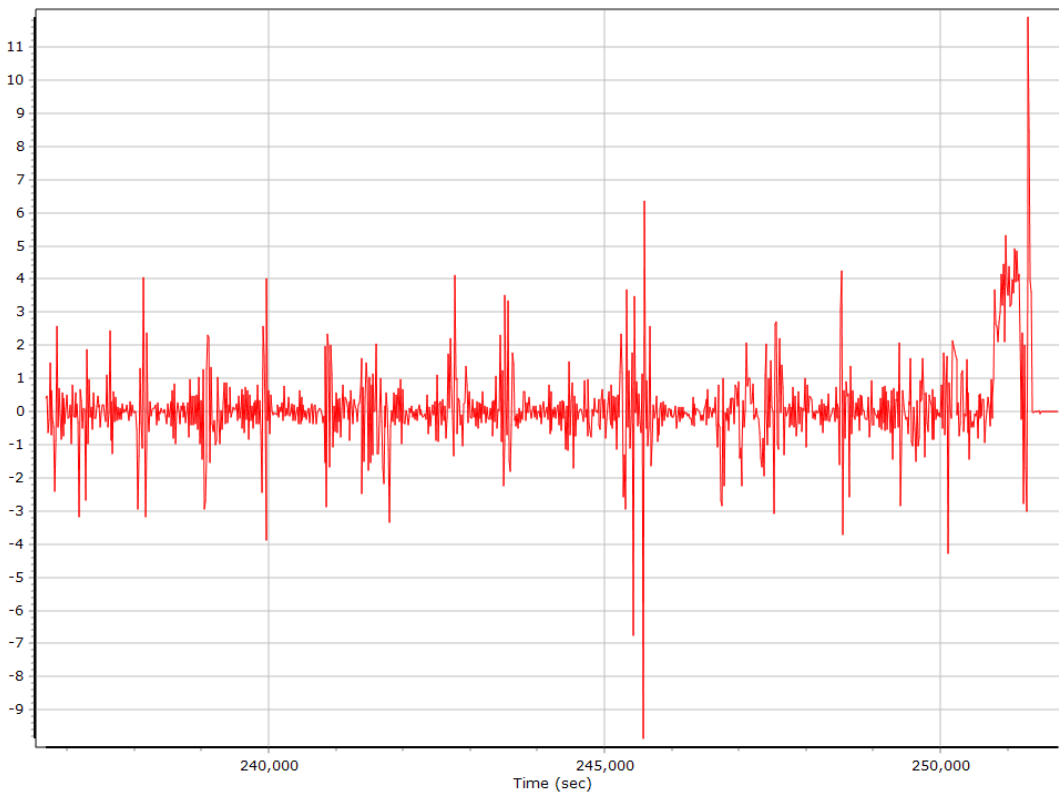
Heading



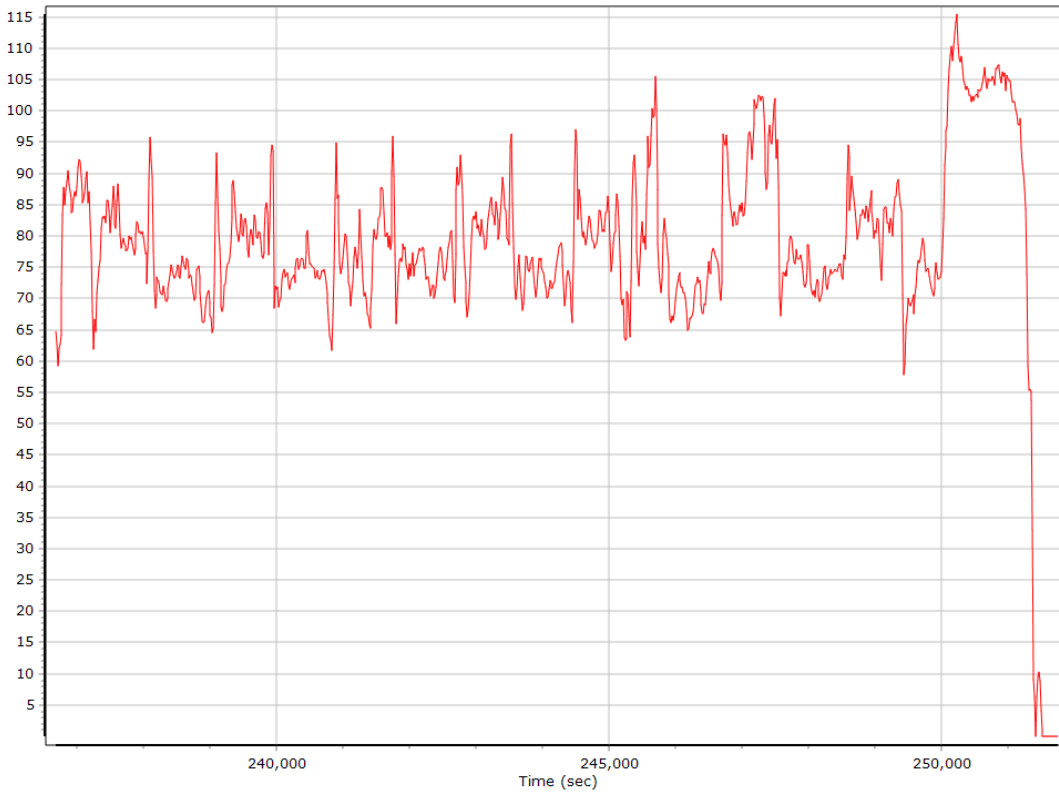
North/East Velocity



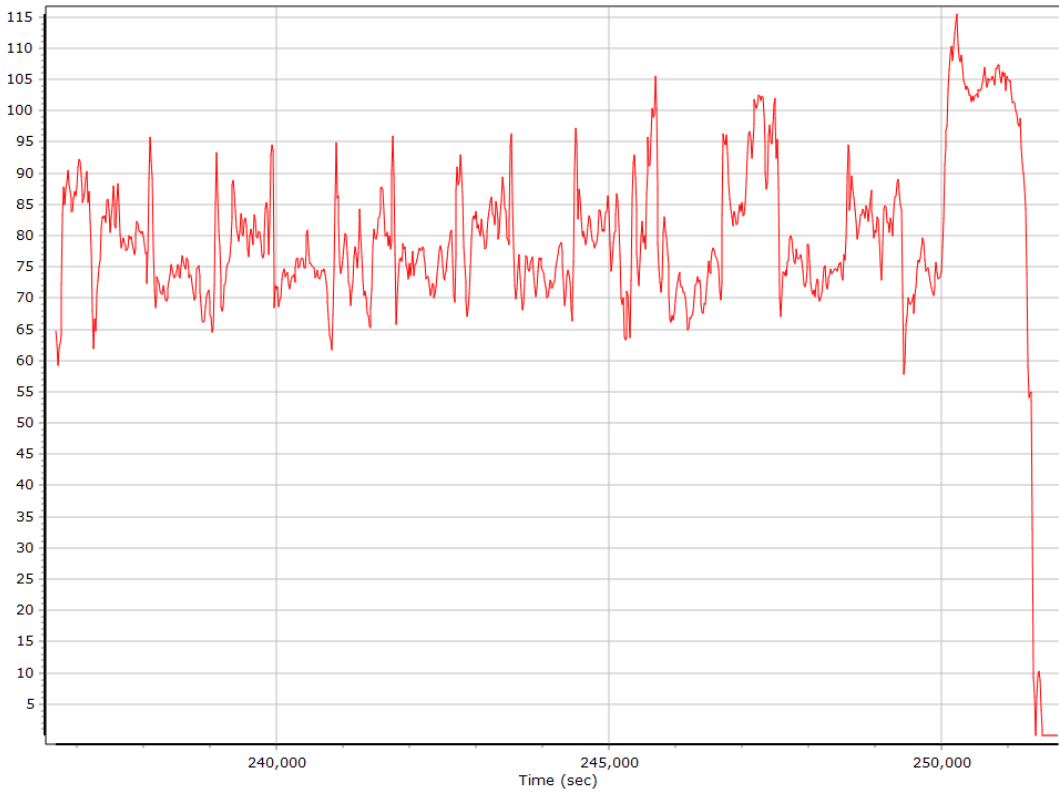
Down Velocity



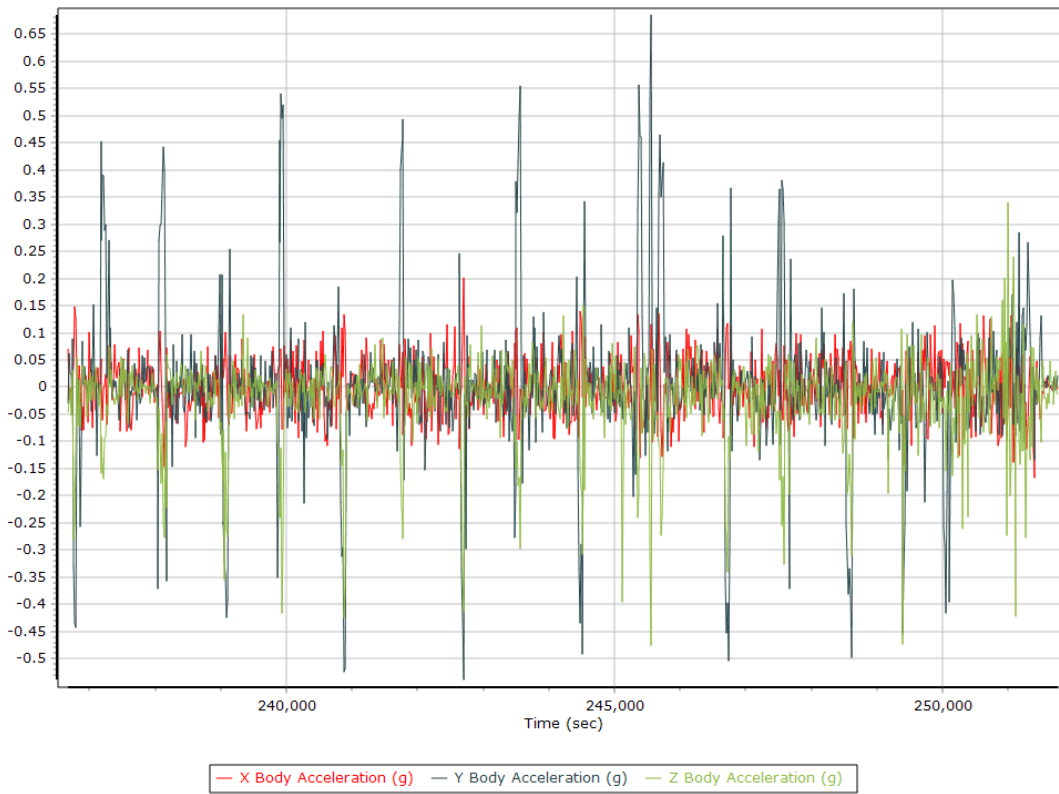
Total Speed



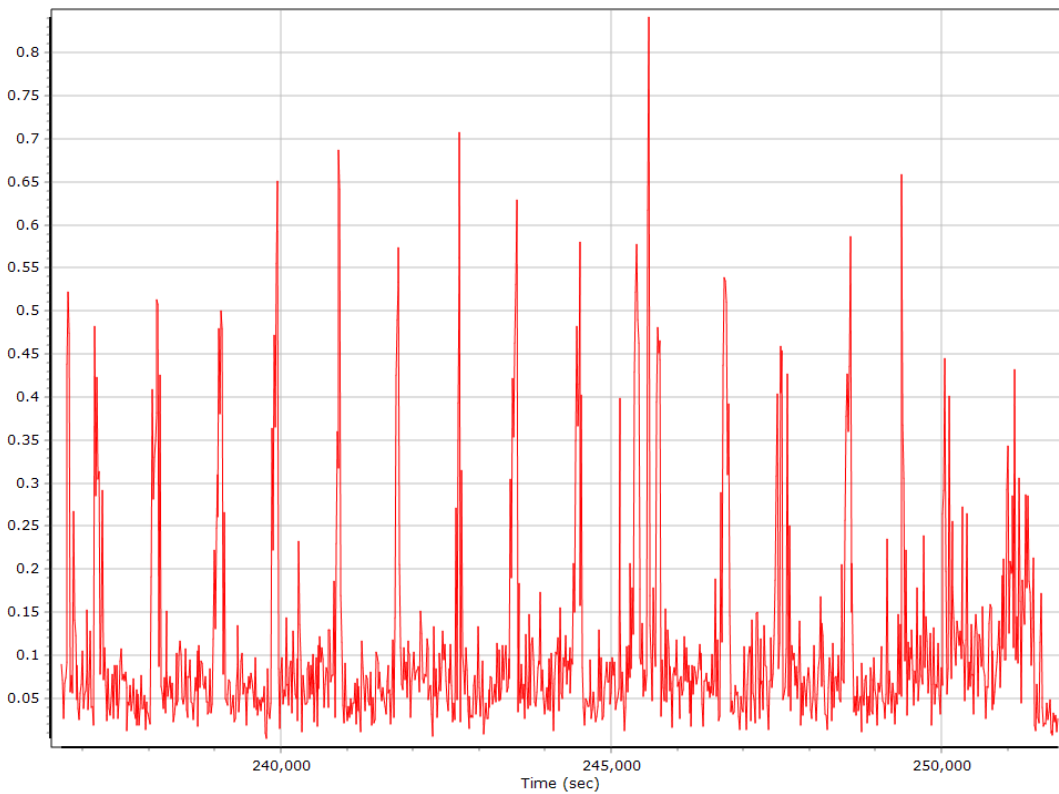
Ground Speed



Body Acceleration



Total Body Acceleration

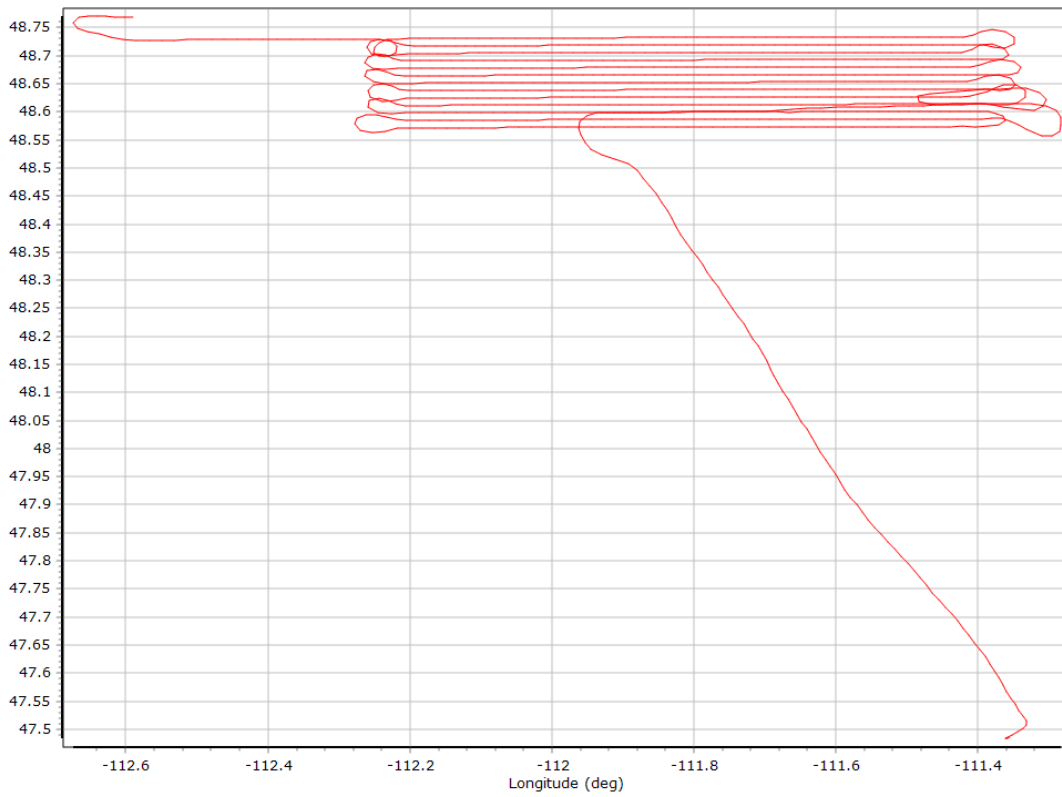


Body Angular Rate

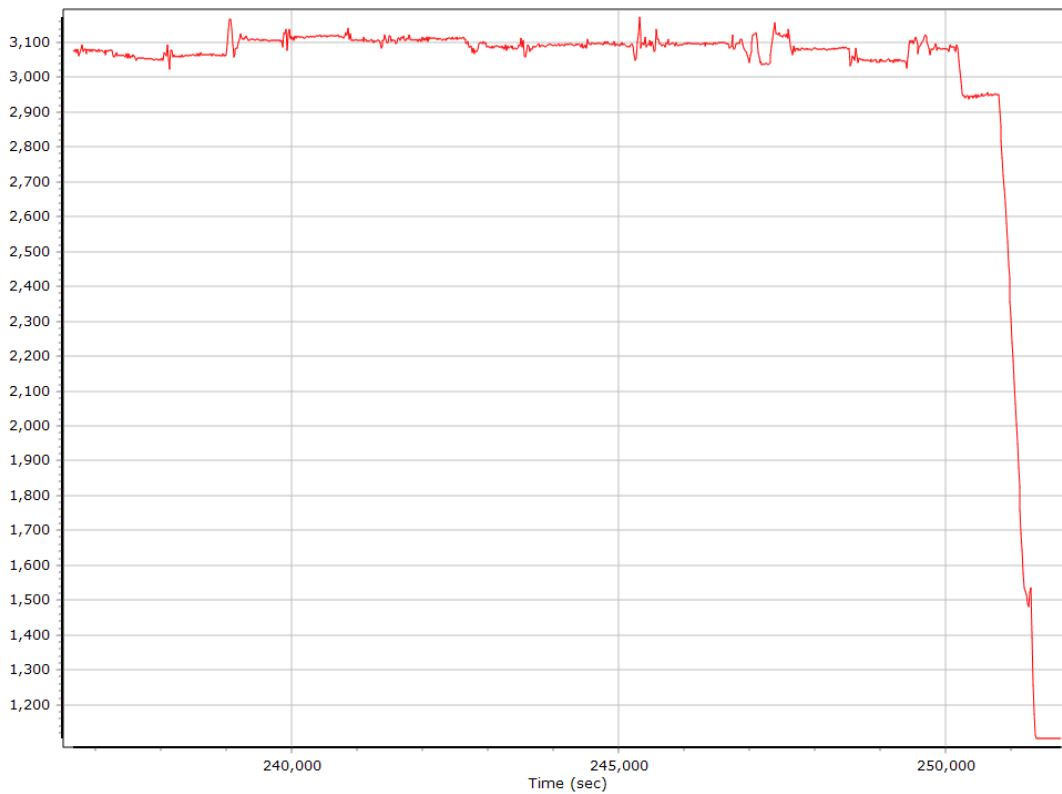


Forward Processed Trajectory Information

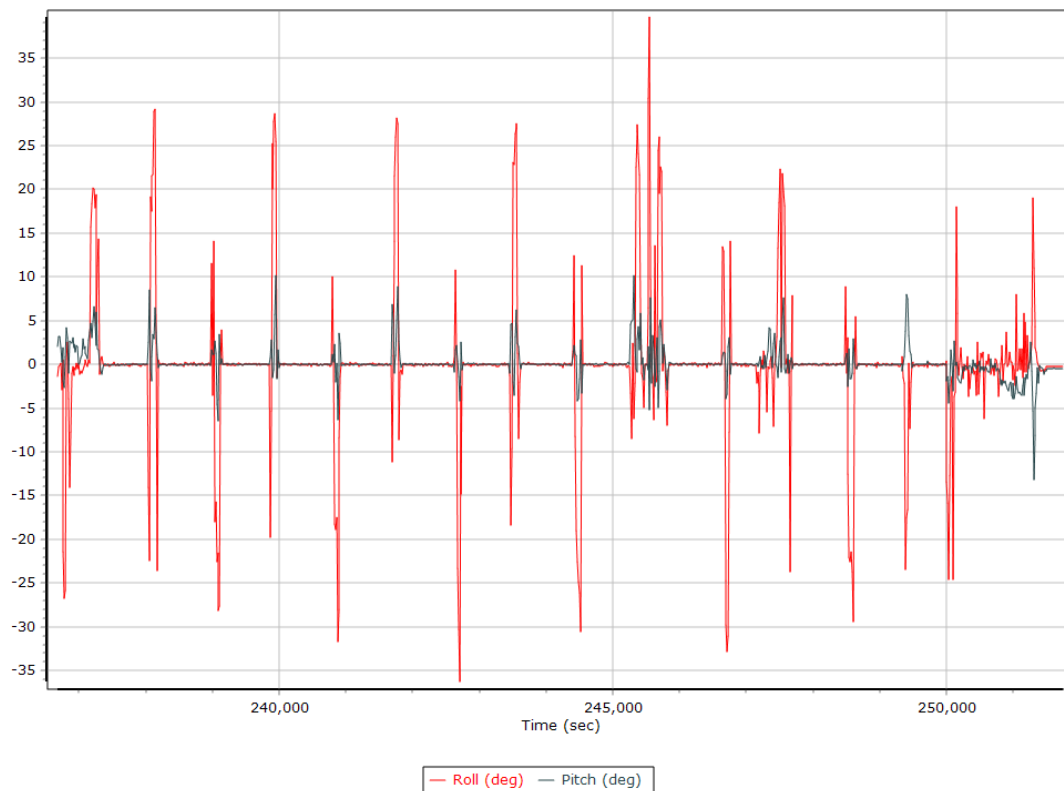
Top View



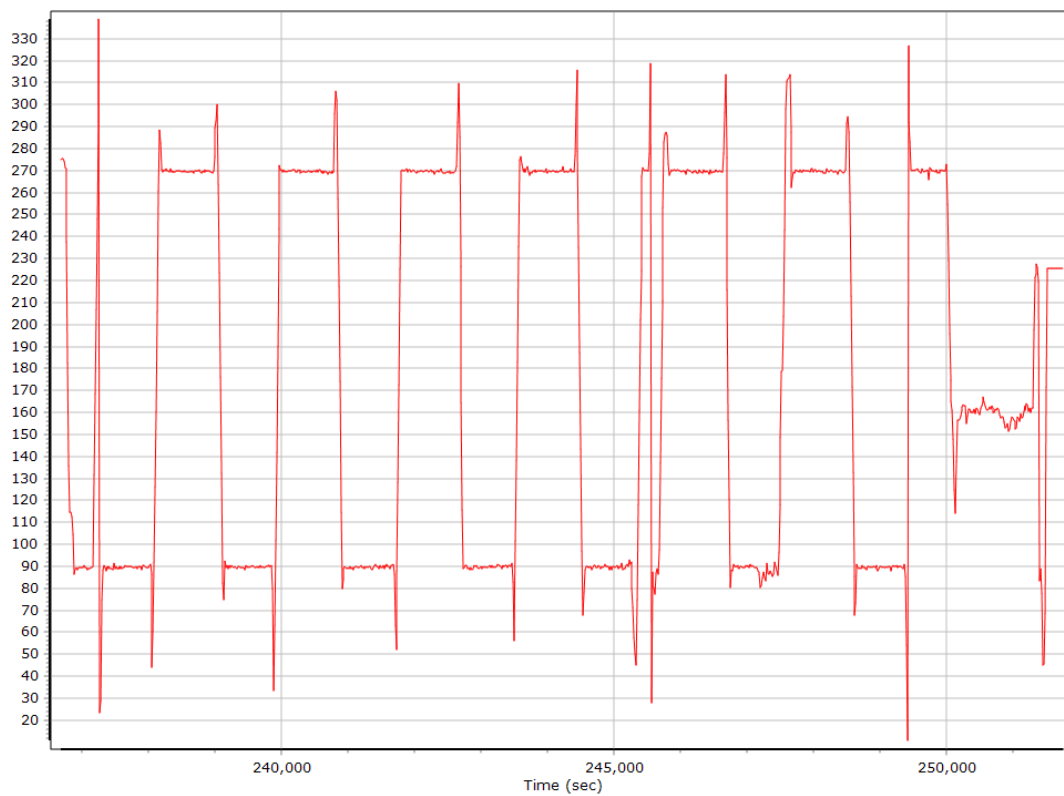
Altitude



Roll/Pitch



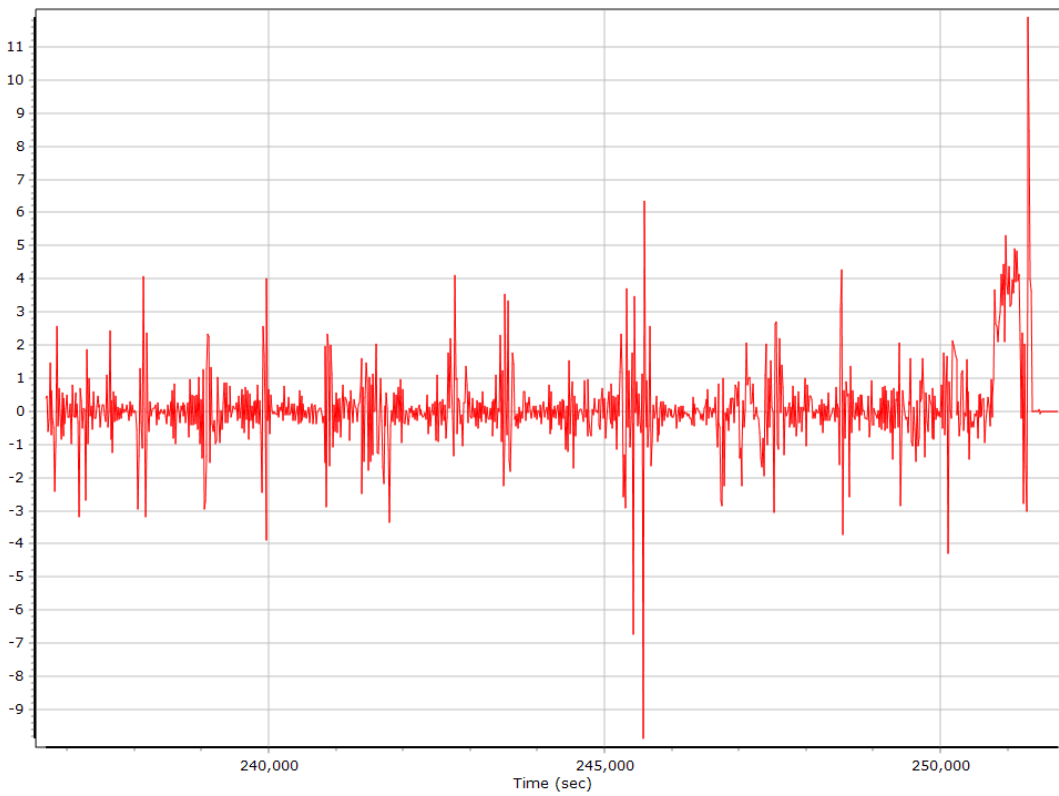
Heading



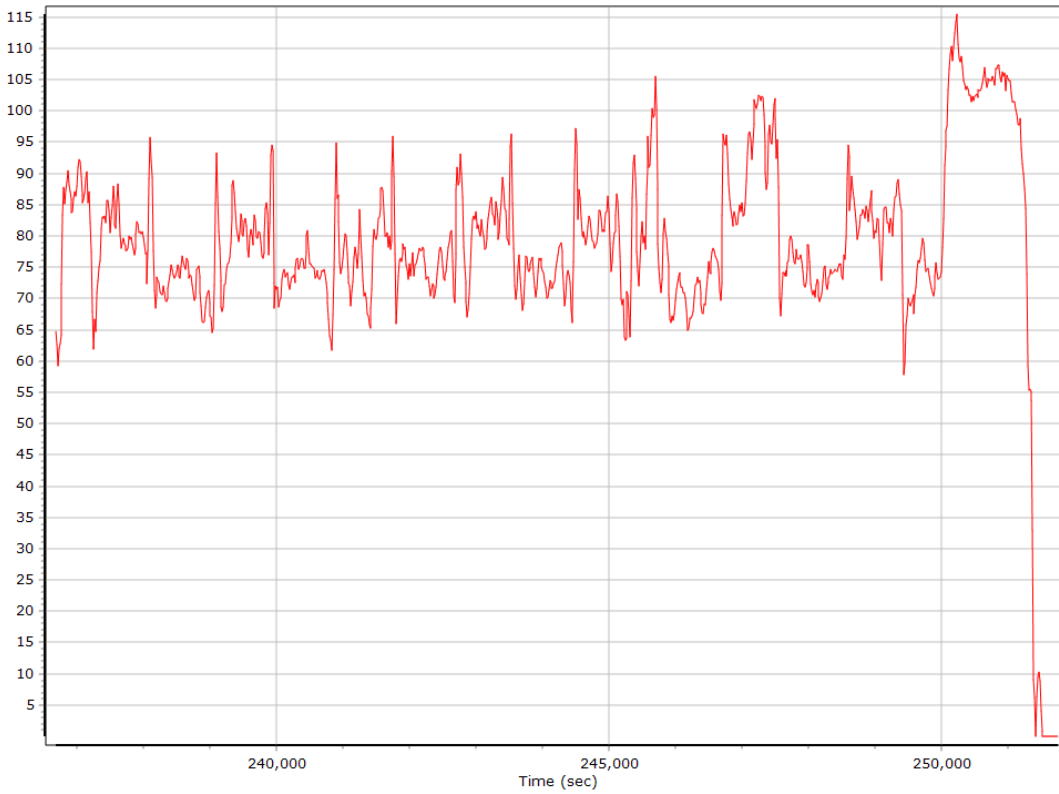
North/East Velocity



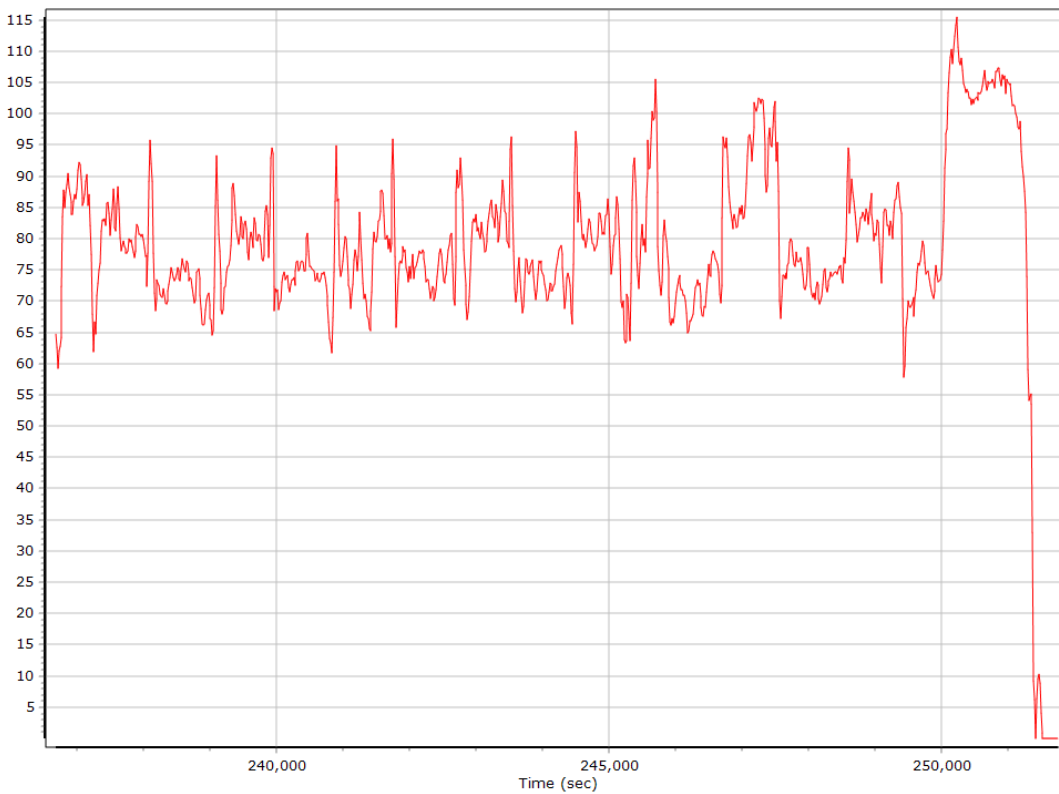
Down Velocity



Total Speed



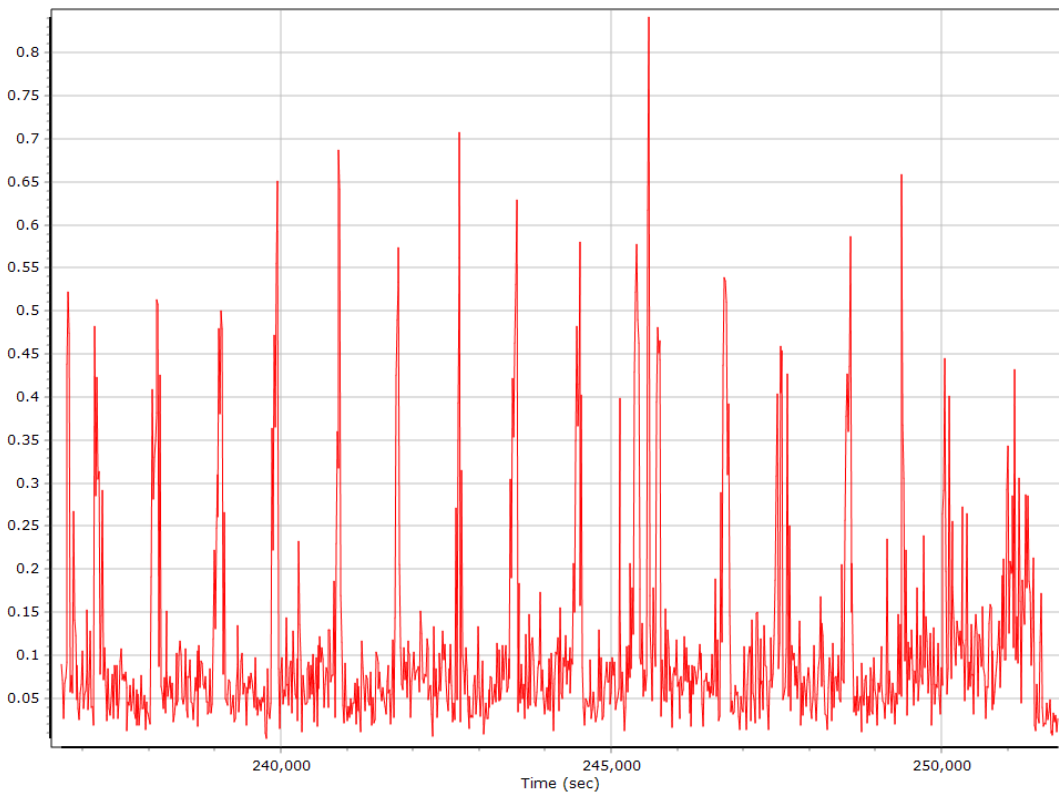
Ground Speed



Body Acceleration



Total Body Acceleration



Body Angular Rate



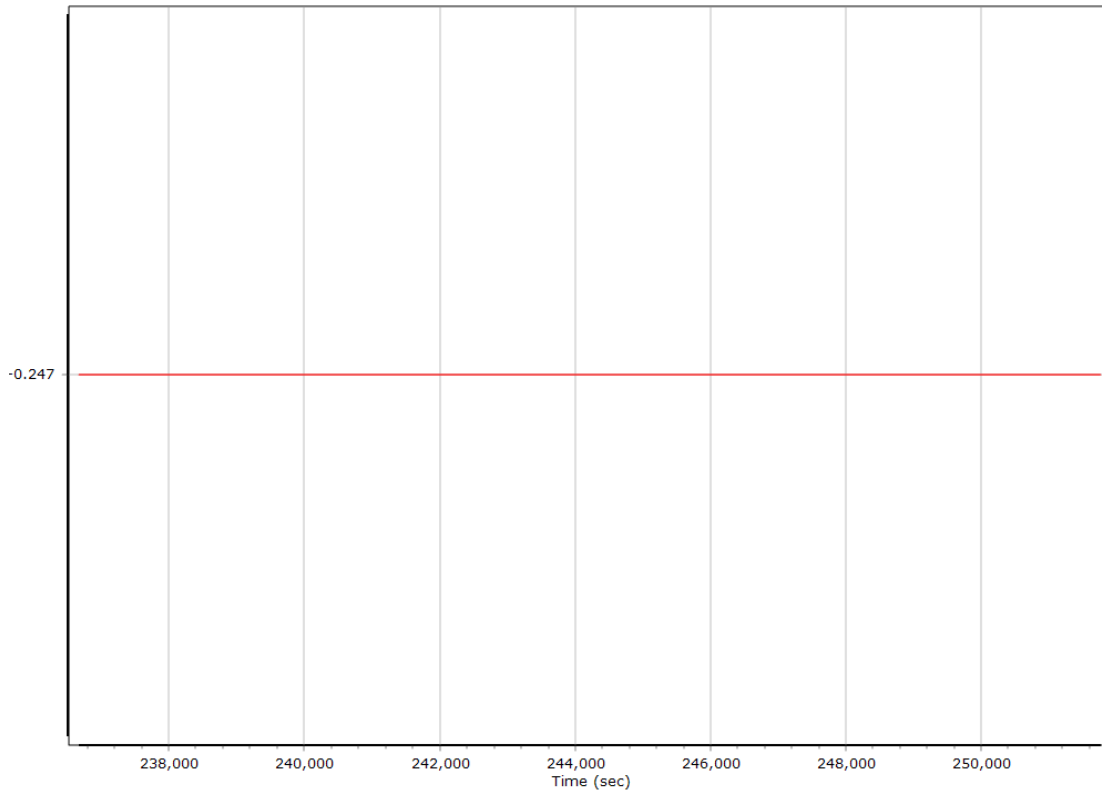
GNSS-Inertial Processor Configuration

Processing mode	IN-Fusion Trimble RTX Nav		
Stabilized mount	True		
Processing start time	236545.000 (09/21/2021 17:42:25)		
Processing end time	251762.000 (09/21/2021 21:56:02)		
Initial attitude source	Real-Time VNAV/RNAV Attitude		
IMU Sensor Context	Processing with Onboard IMU		
Gimbal to IMU lever arm (m)	-0.034	-0.010	-0.374
Gimbal to IMU mounting angles (deg)	0.000	0.000	0.000
Gimbal to Primary GNSS lever arm (m)	-0.247	-0.020	-1.300
Gimbal to Primary GNSS lever arm std dev (m)	0.030	0.030	0.030
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

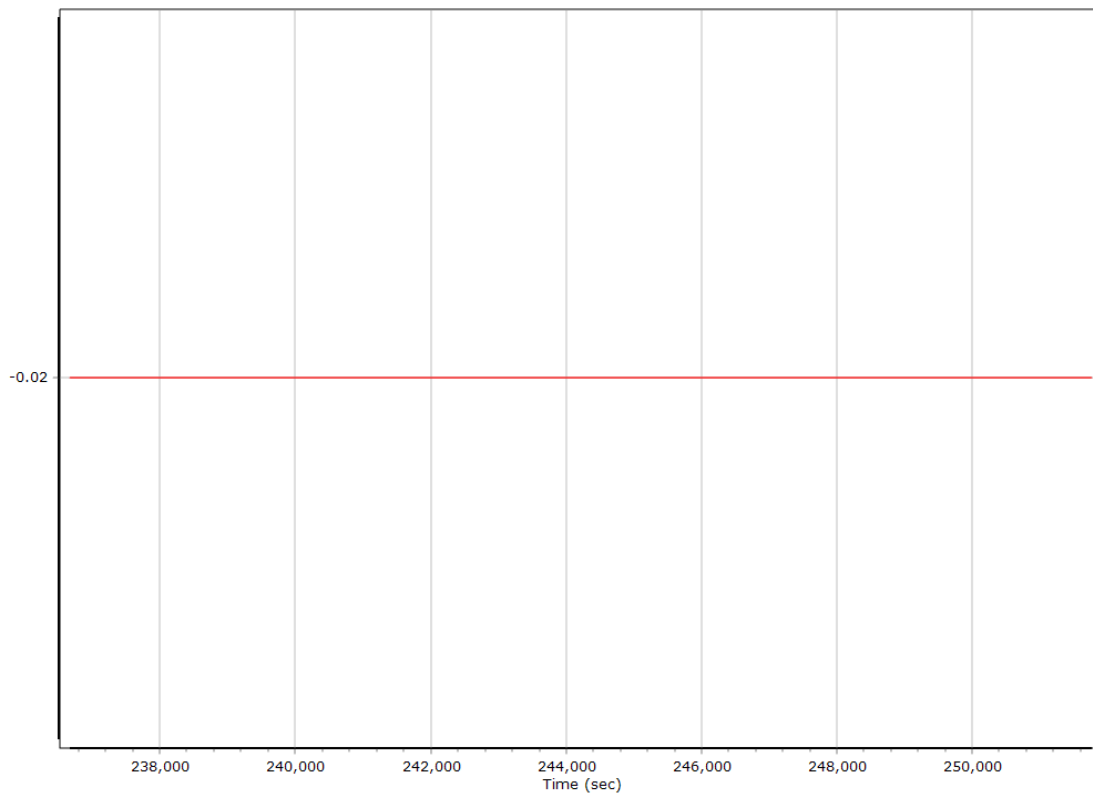
Calibrated Installation Parameters

Reference-Primary GNSS Lever Arm (m)

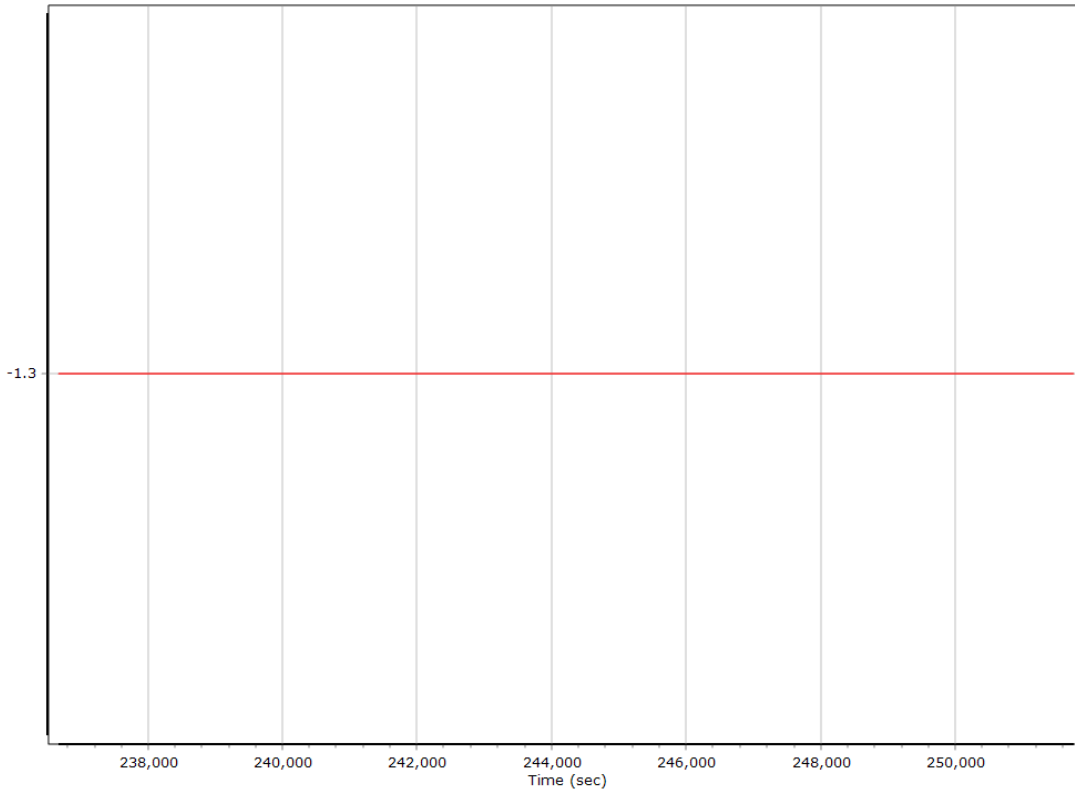
X Reference-Primary GNSS Lever Arm (m)



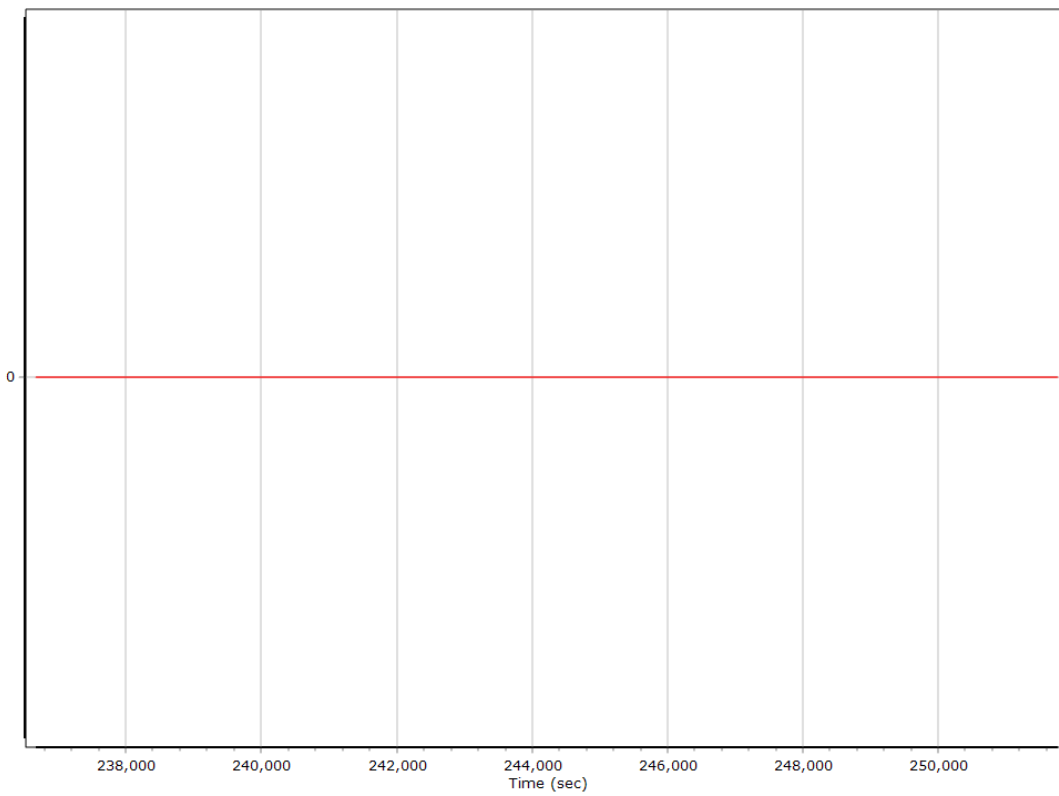
Y Reference-Primary GNSS Lever Arm (m)



Z Reference-Primary GNSS Lever Arm (m)



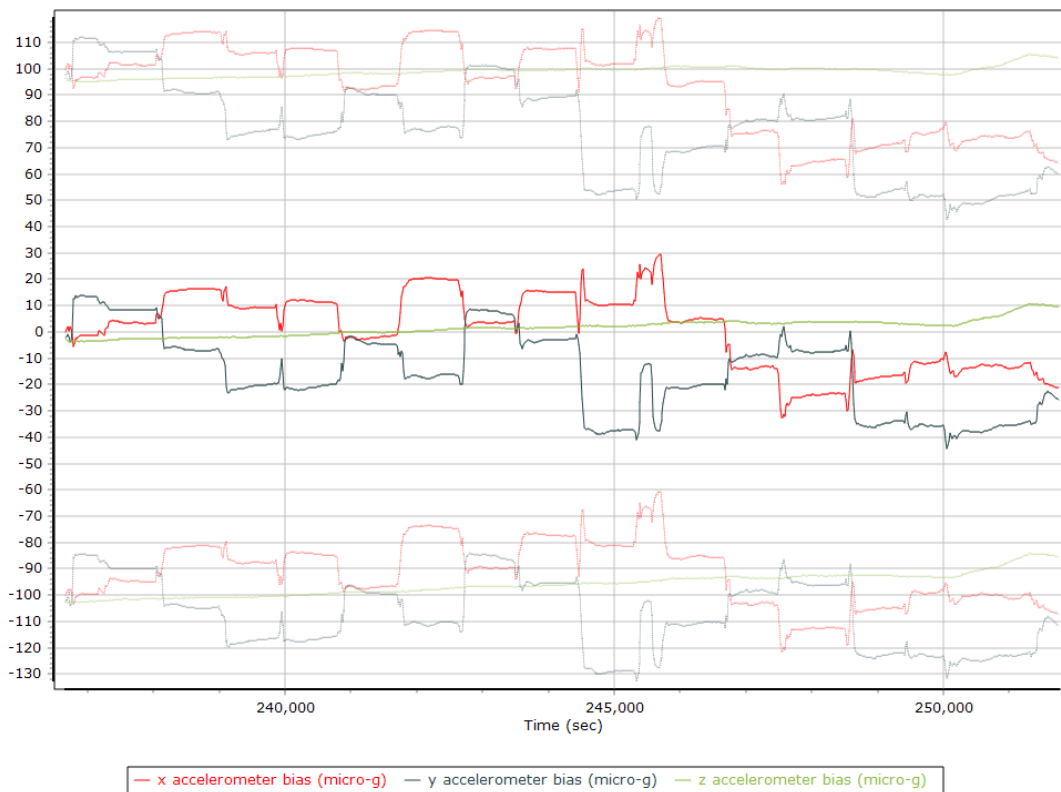
Reference-Primary GNSS Lever Arm Figure of Merit



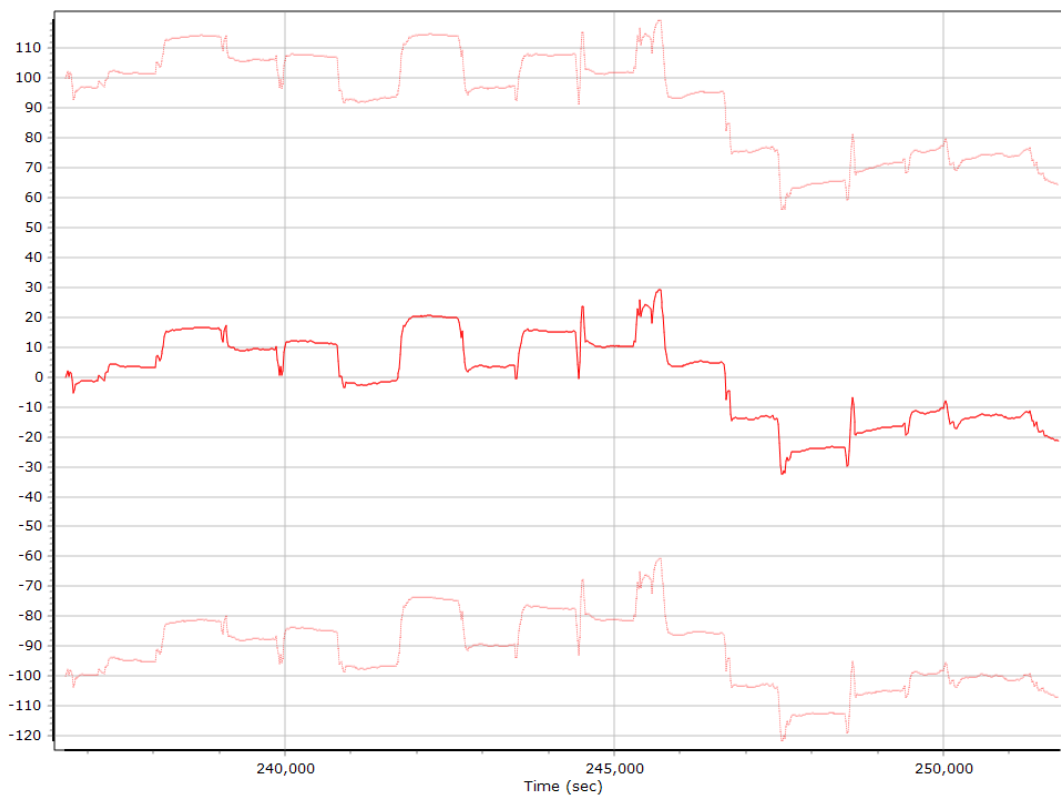
IN-Fusion QC

Forward Processed Estimated Errors, Reference Frame

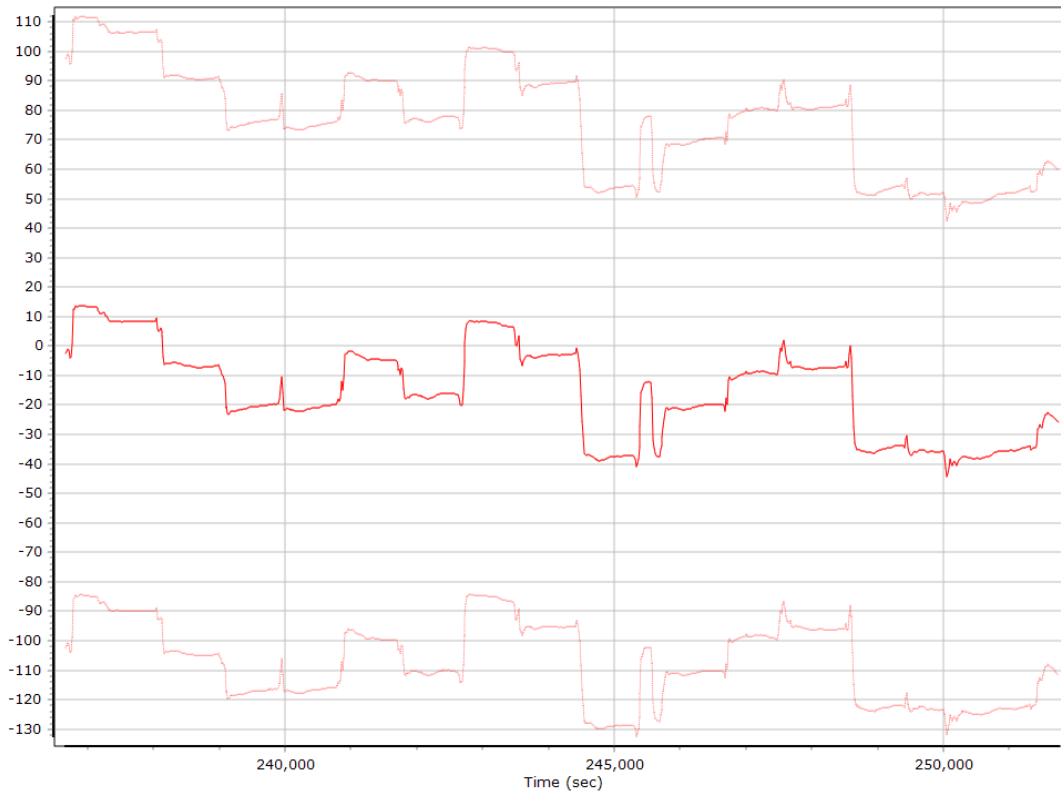
Accelerometer Bias (micro-g)



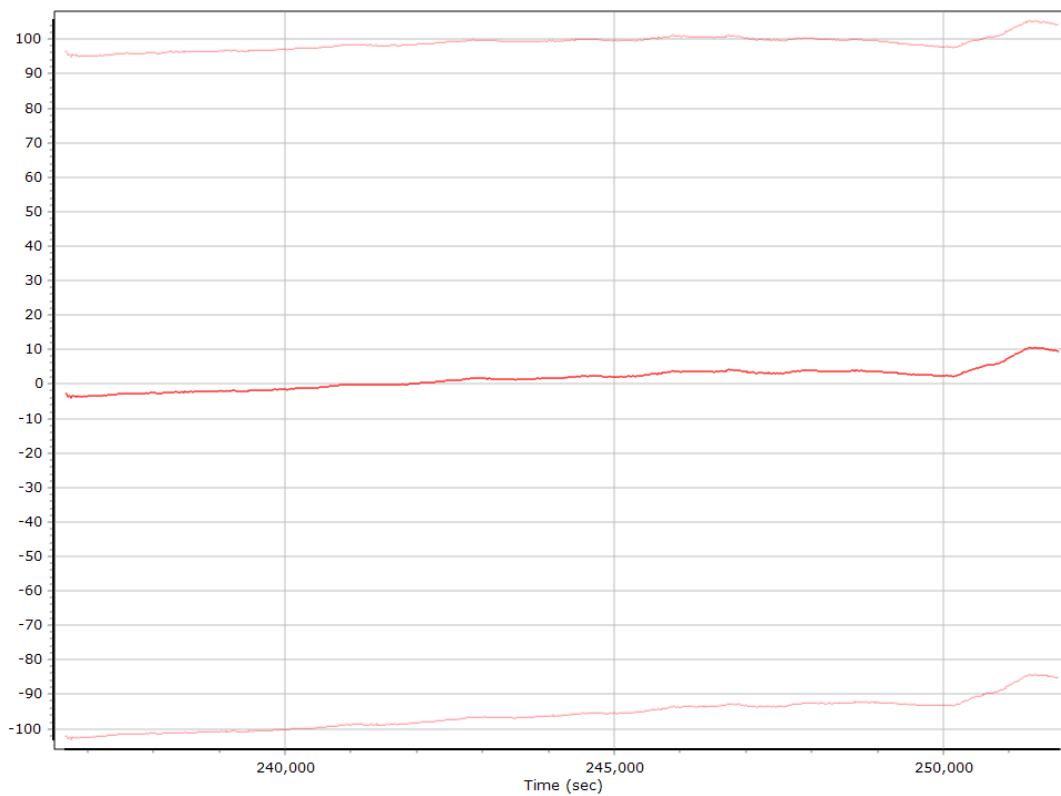
X Accelerometer Bias (micro-g)



Y Accelerometer Bias (micro-g)



Z Accelerometer Bias (micro-g)



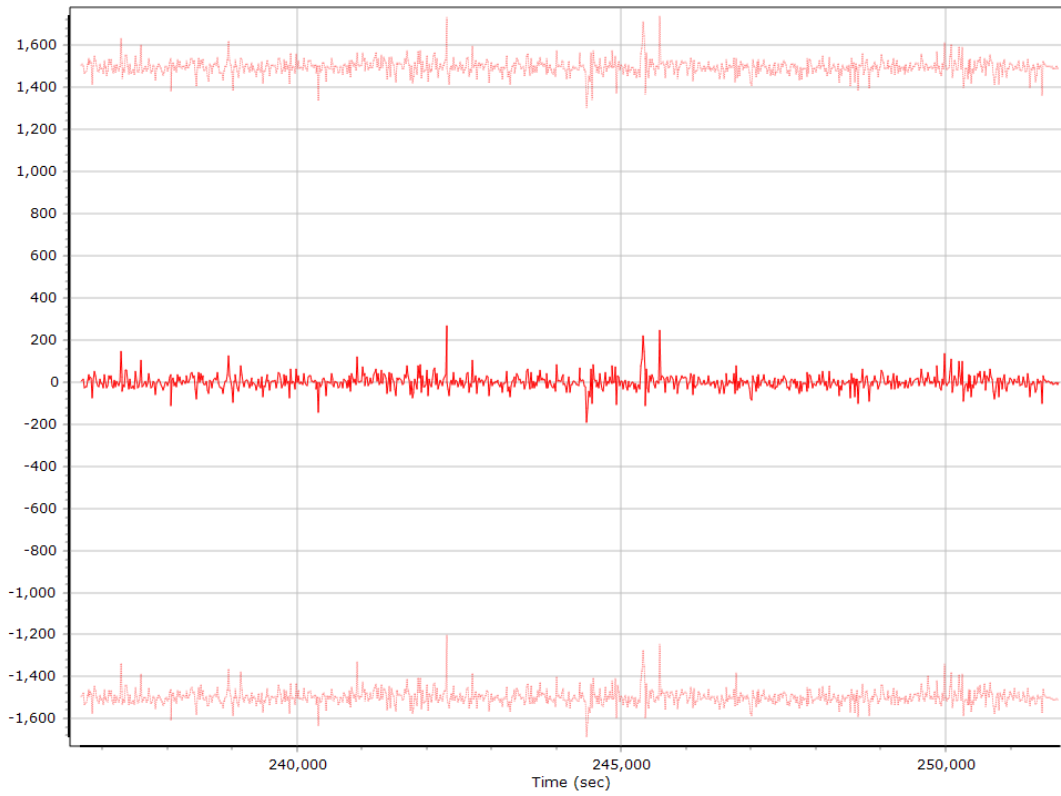
Accelerometer Scale Error (ppm)



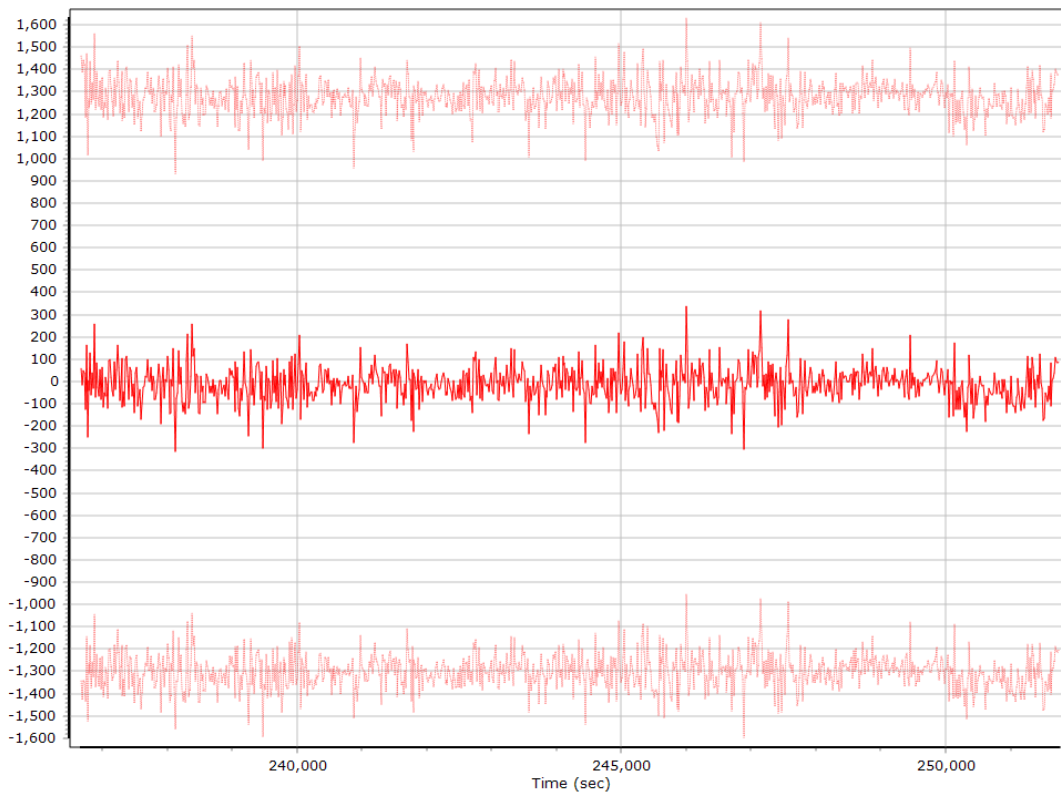
X Accelerometer Scale Error (ppm)



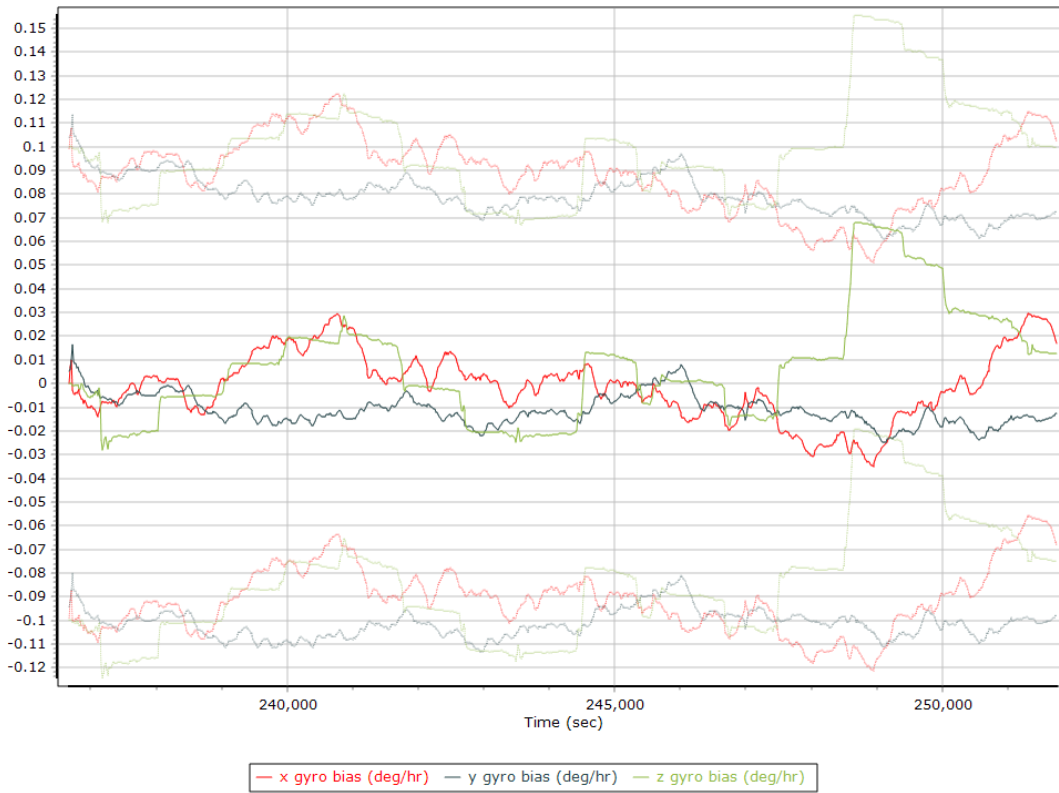
Y Accelerometer Scale Error (ppm)



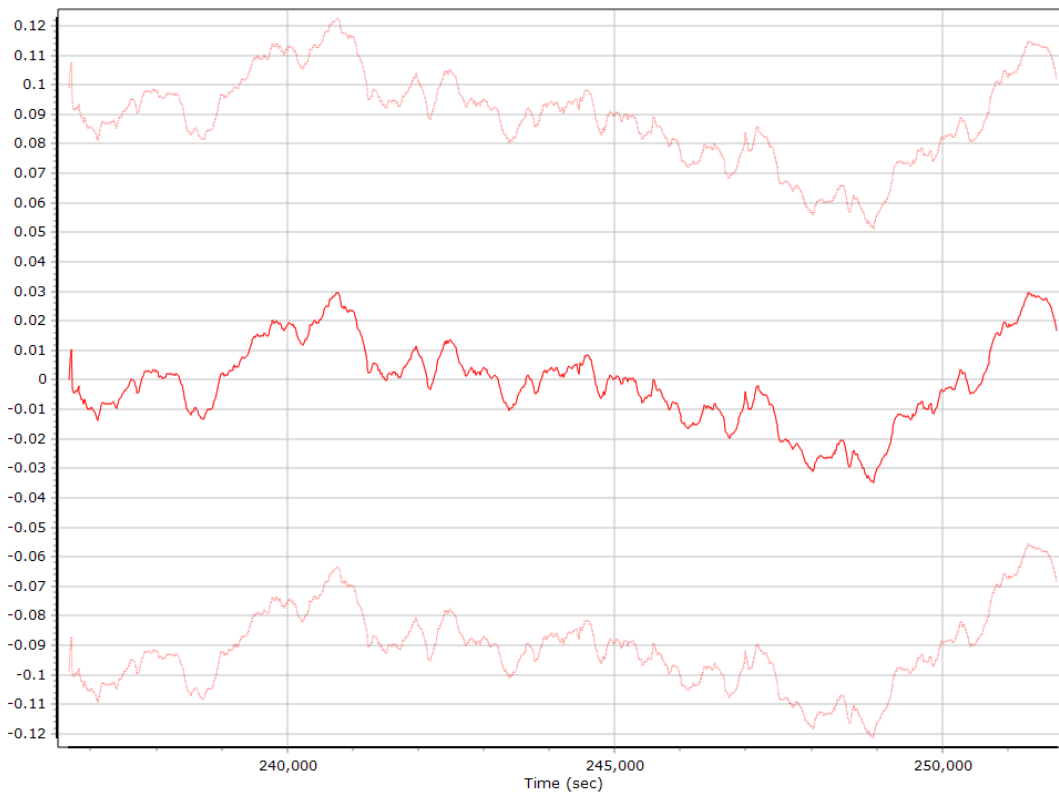
Z Accelerometer Scale Error (ppm)



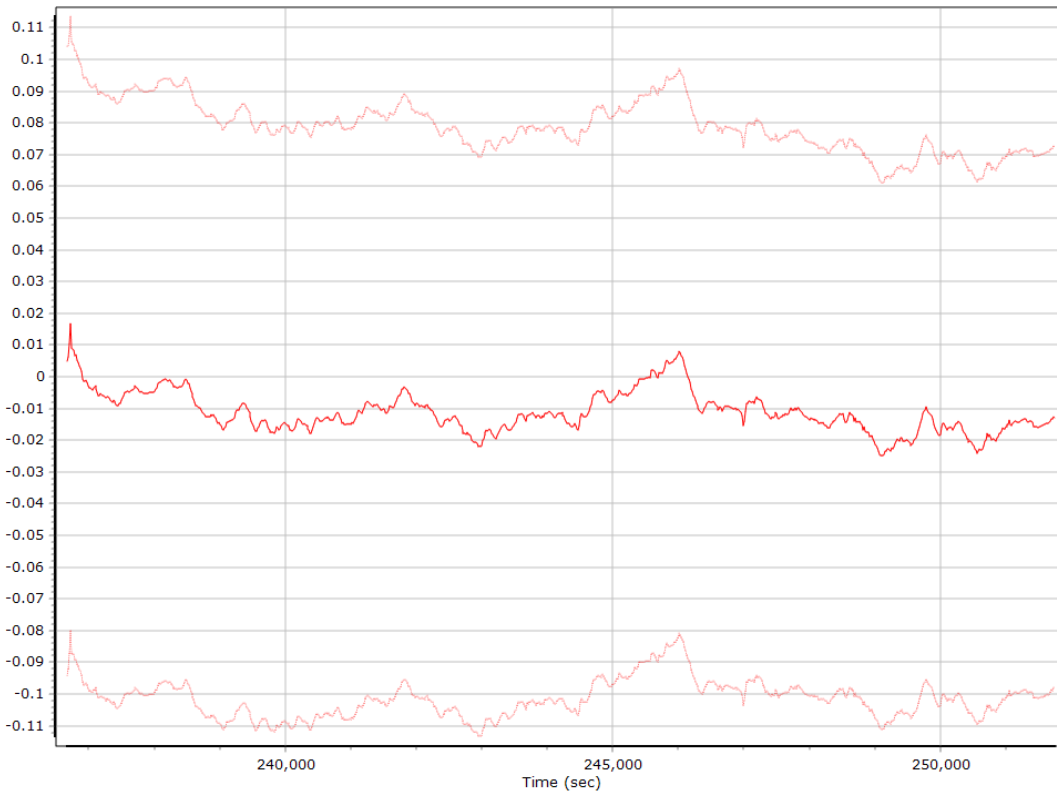
Gyro Bias (deg/h)



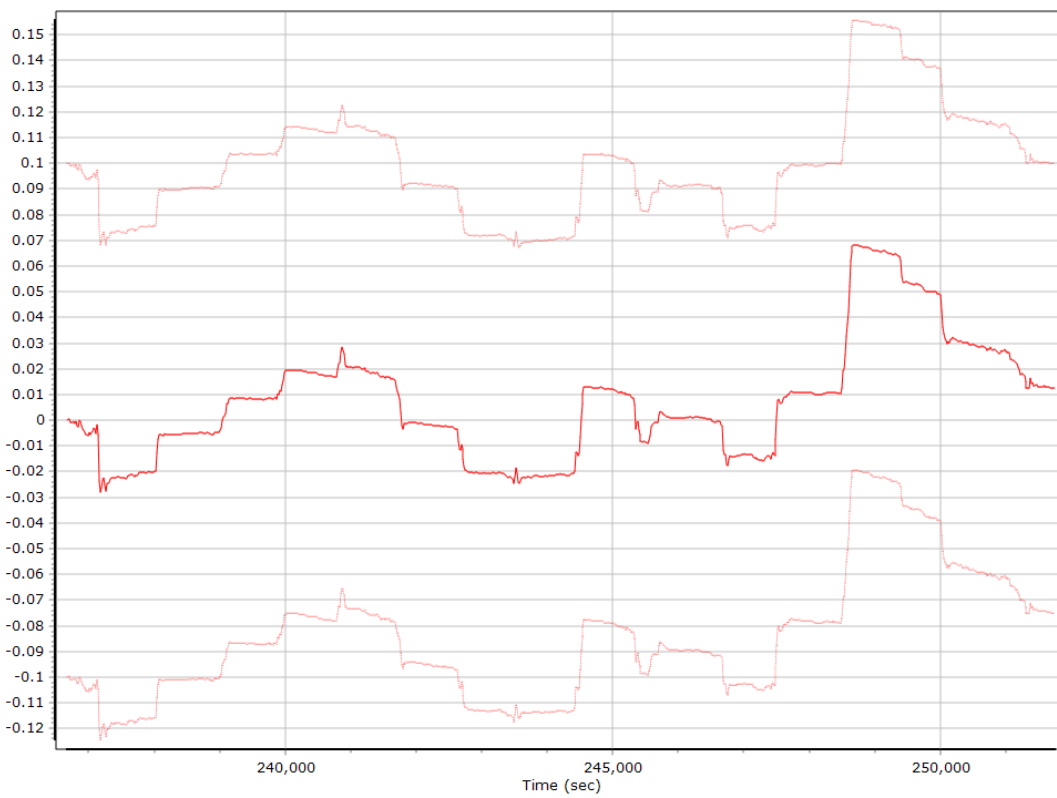
X Gyro Bias (deg/h)



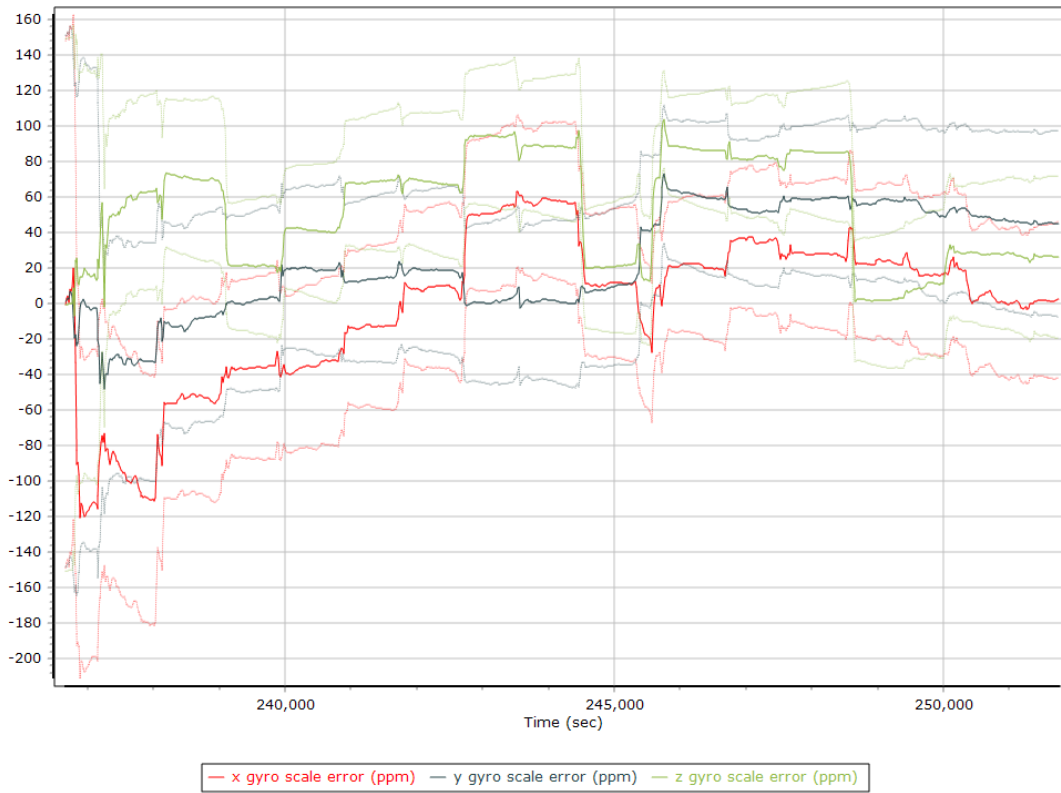
Y Gyro Bias (deg/h)



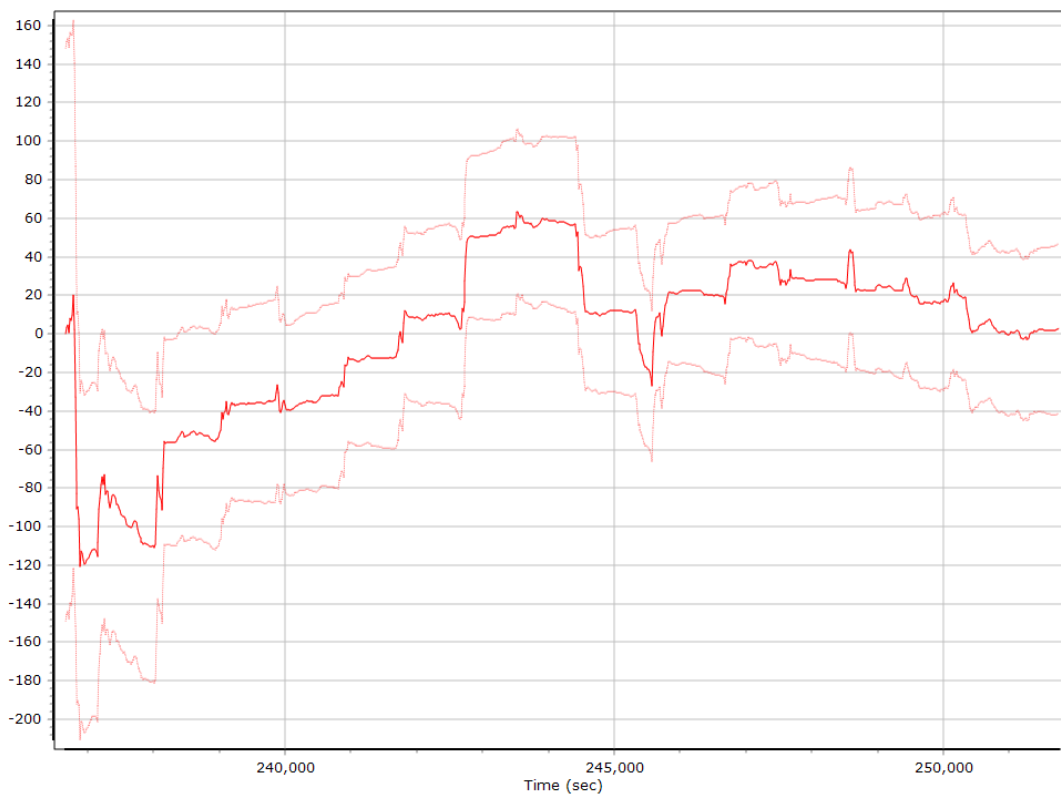
Z Gyro Bias (deg/h)



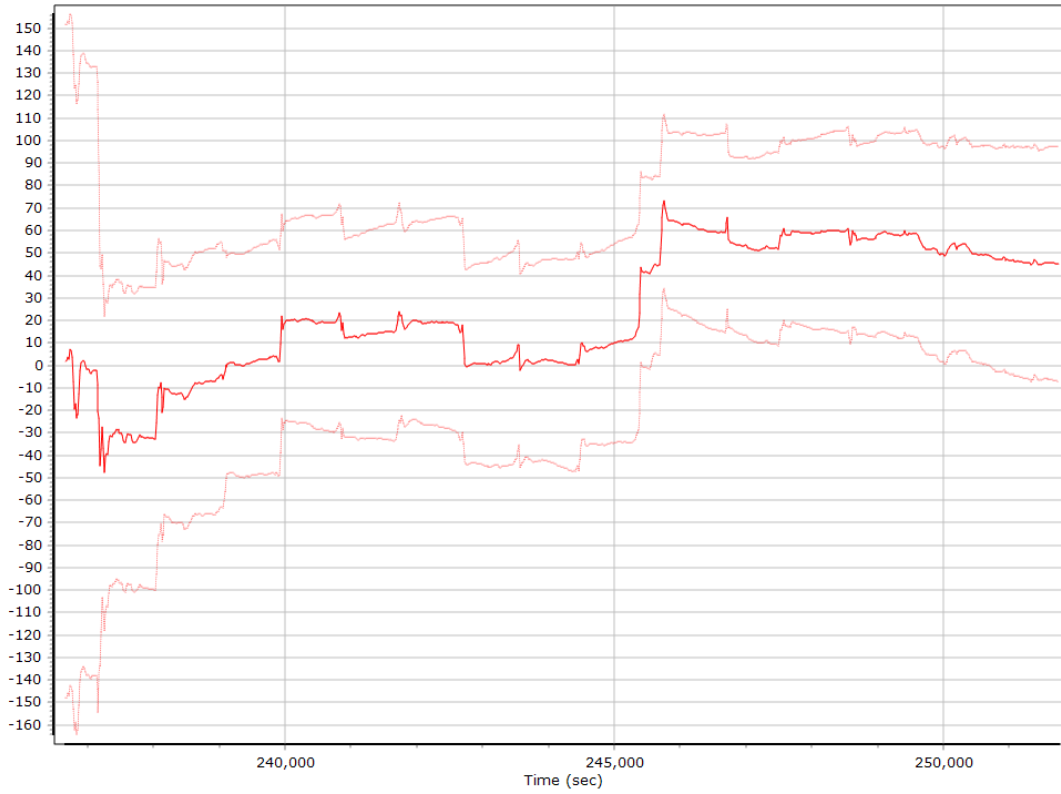
Gyro Scale Error (ppm)



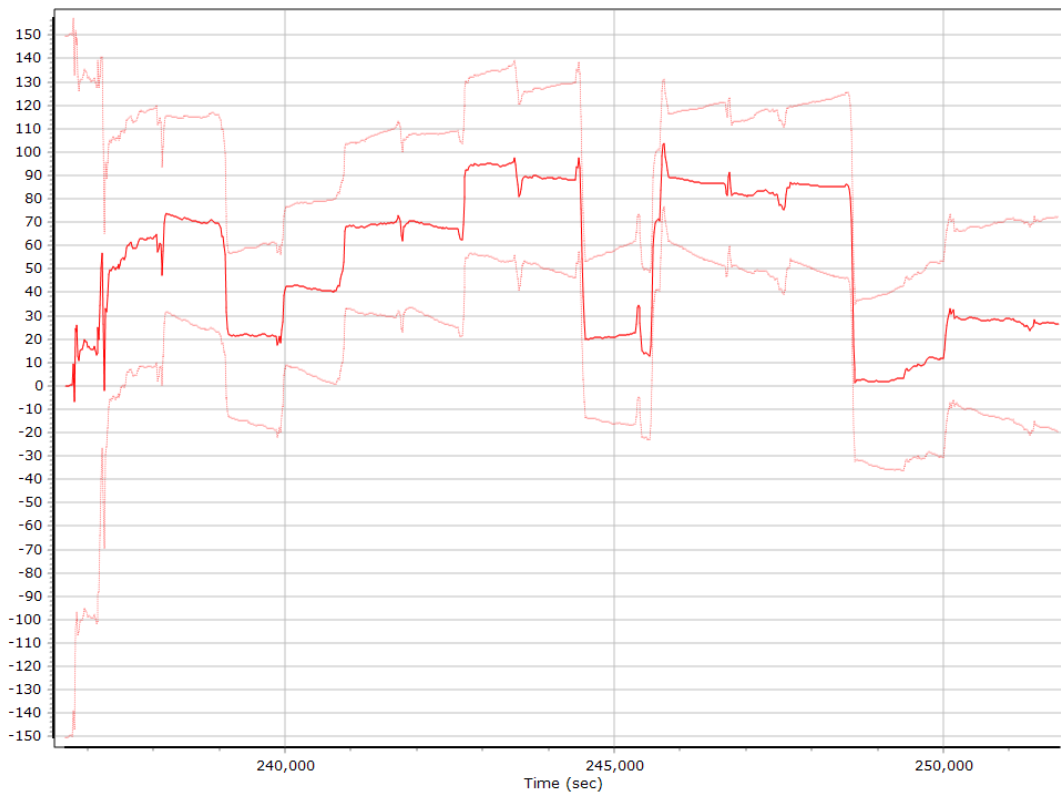
X Gyro Scale Error (ppm)



Y Gyro Scale Error (ppm)

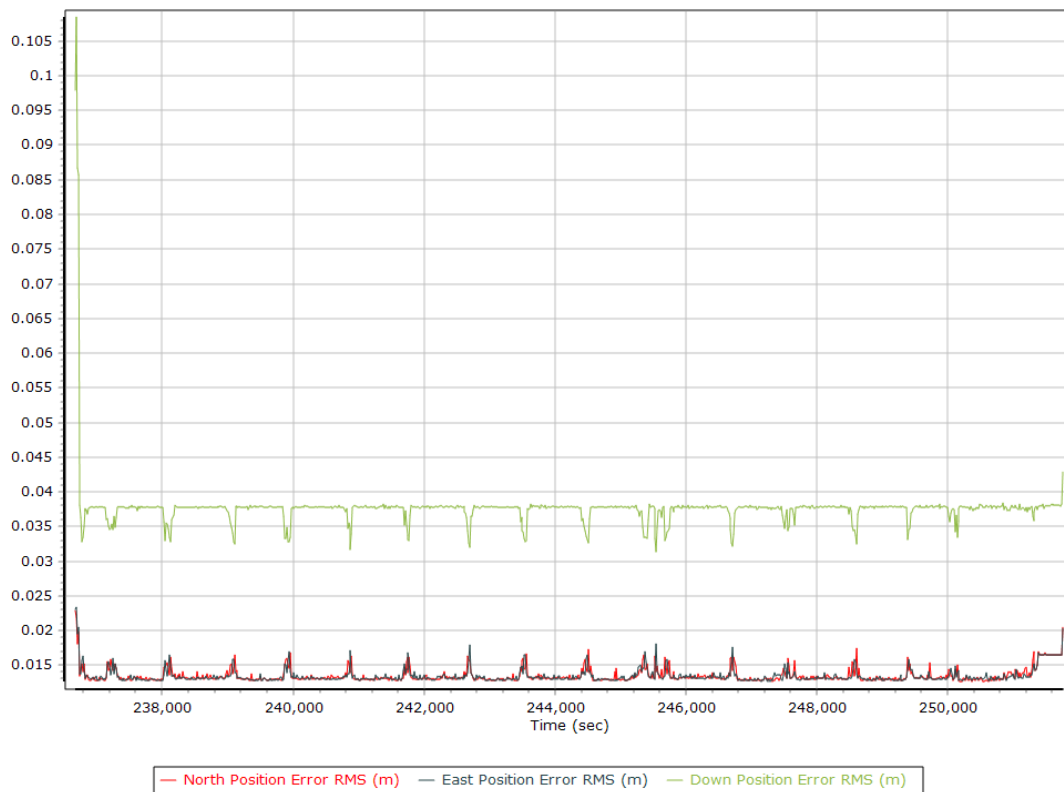


Z Gyro Scale Error (ppm)

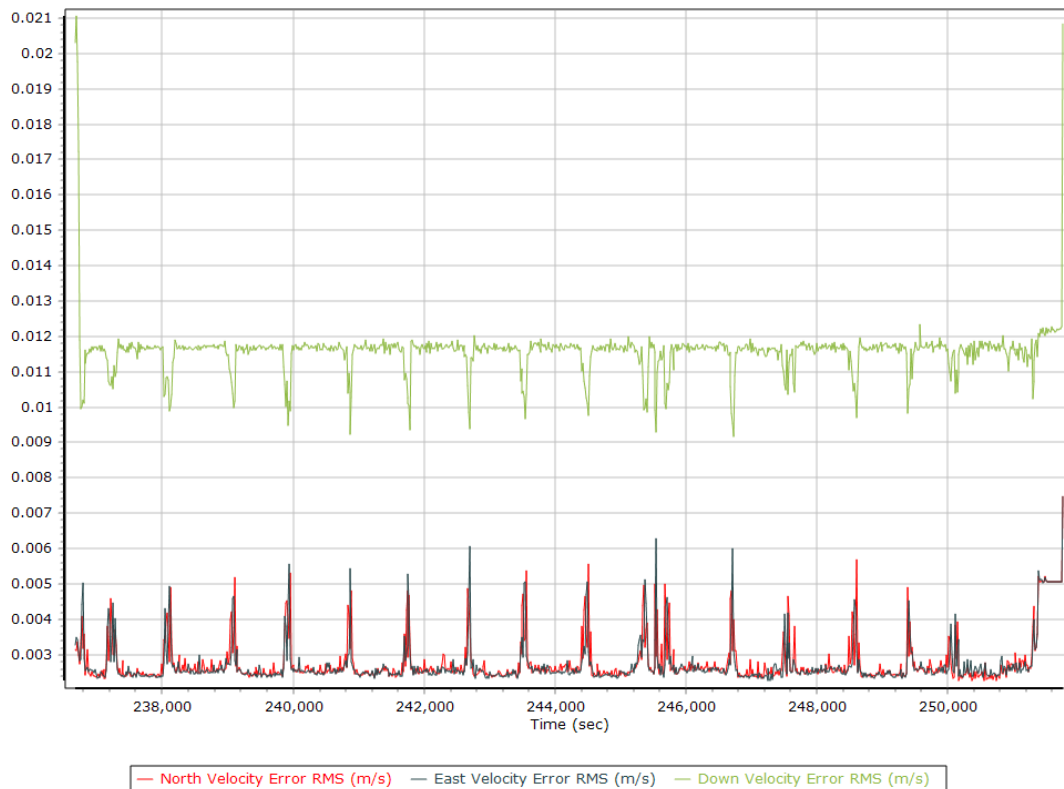


Smoothed Performance Metrics

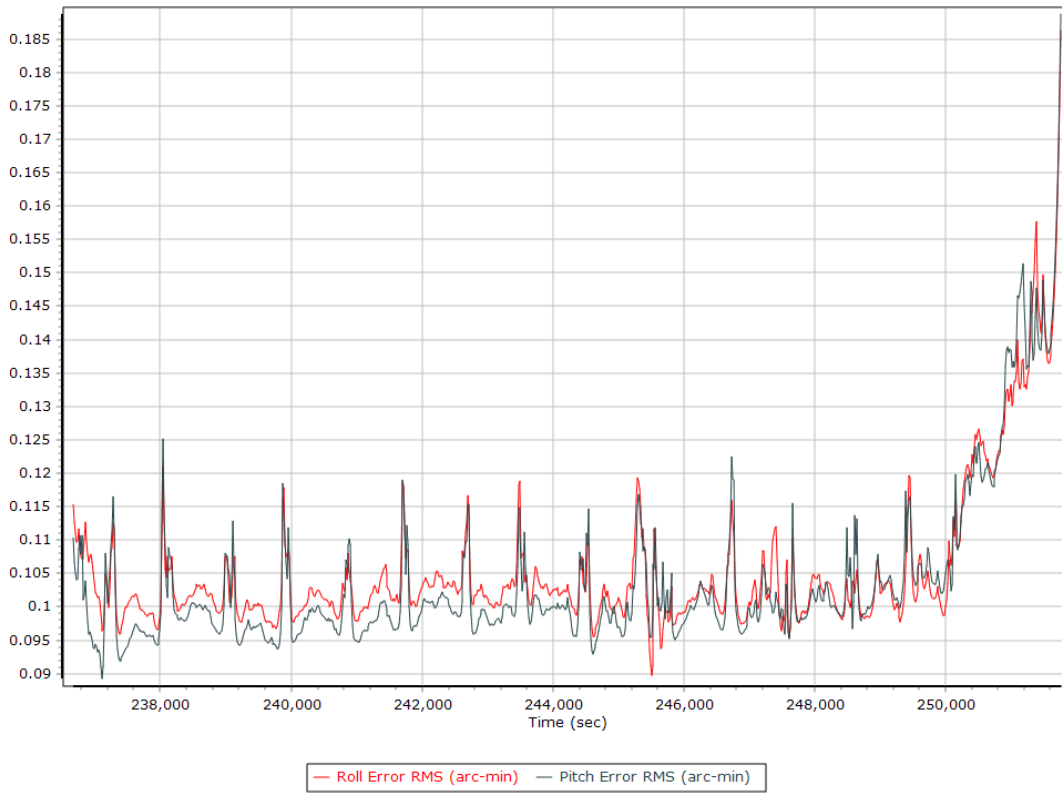
Position Error RMS (m)



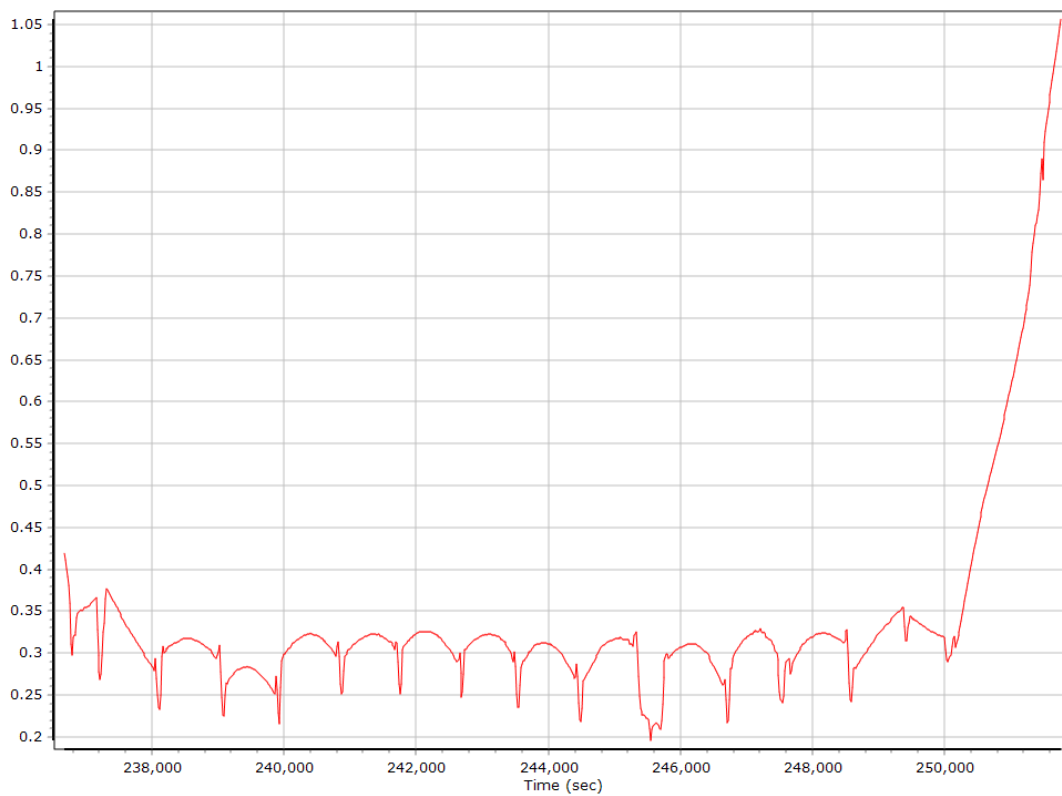
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

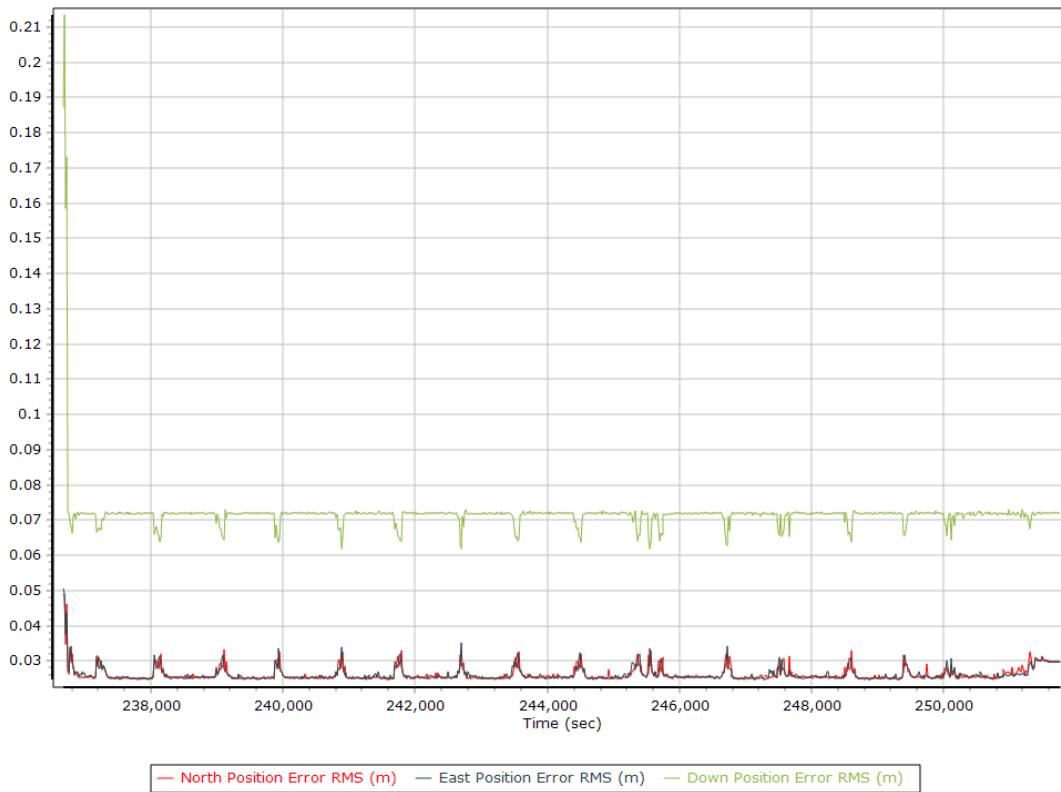


Heading Error RMS (arc-min)

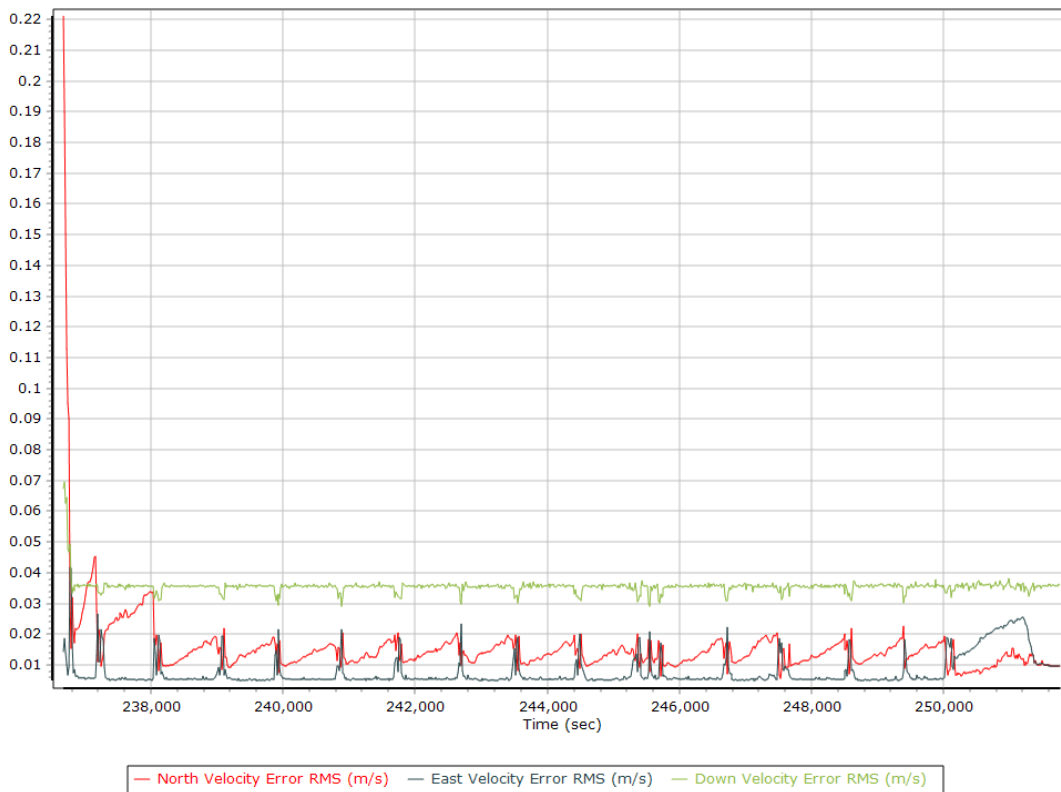


Forward Processed Performance Metrics

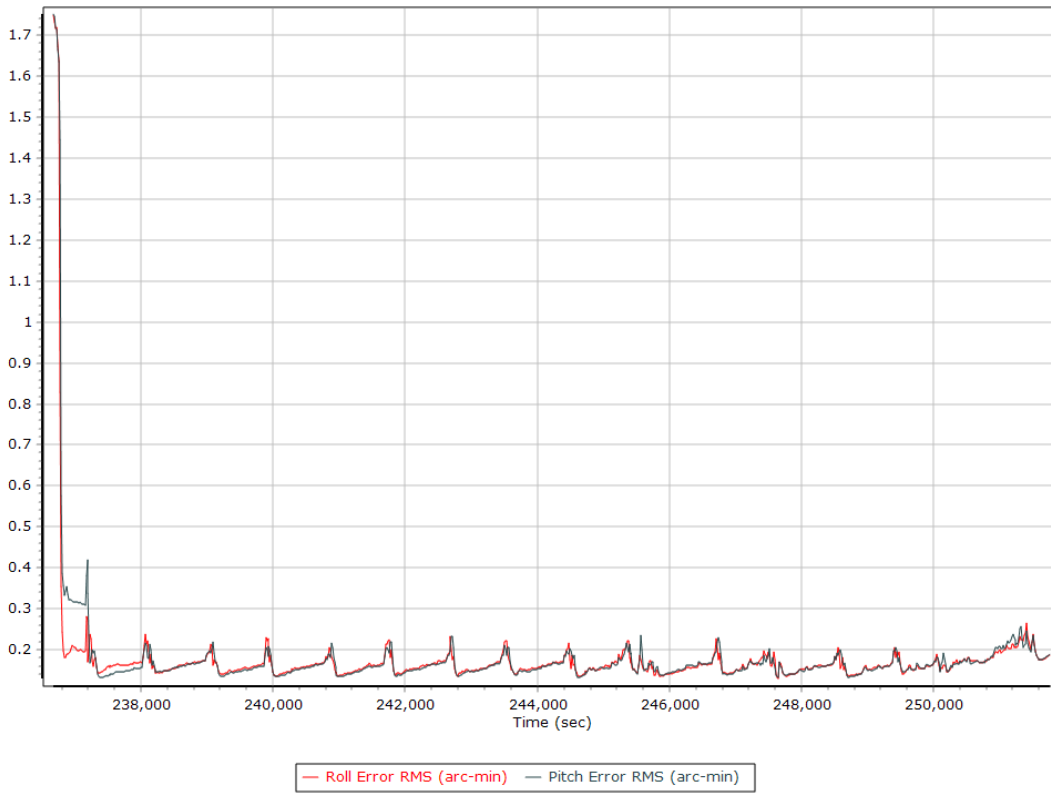
Position Error RMS (m)



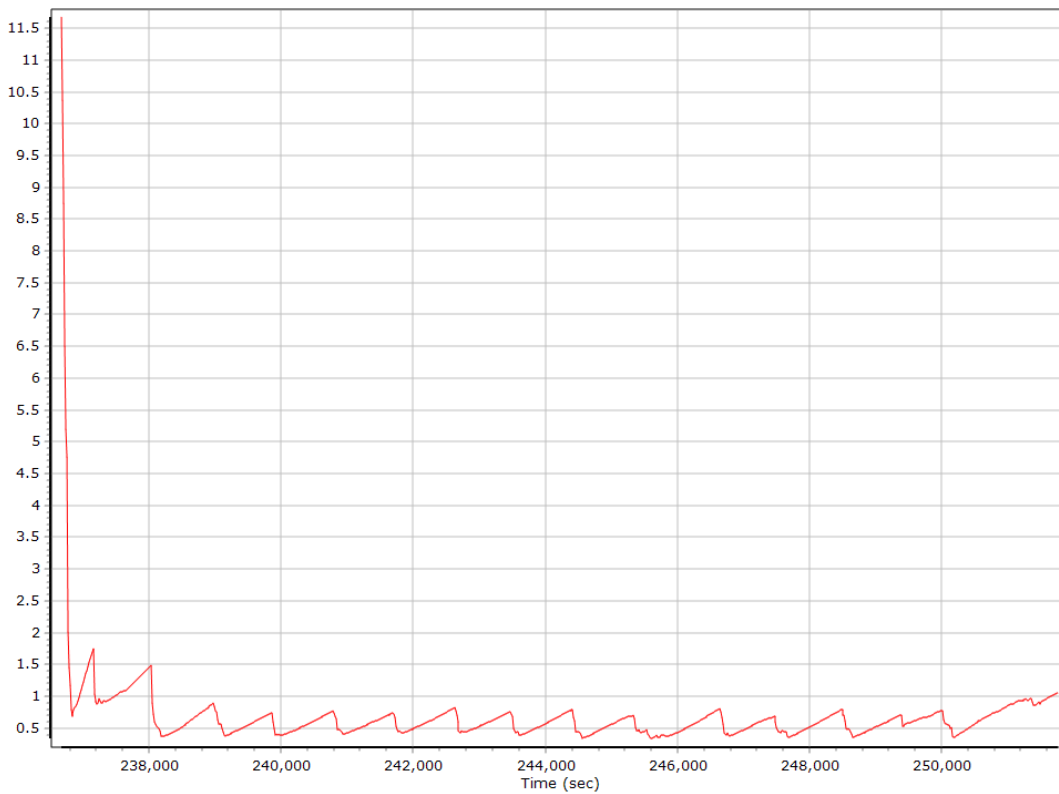
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

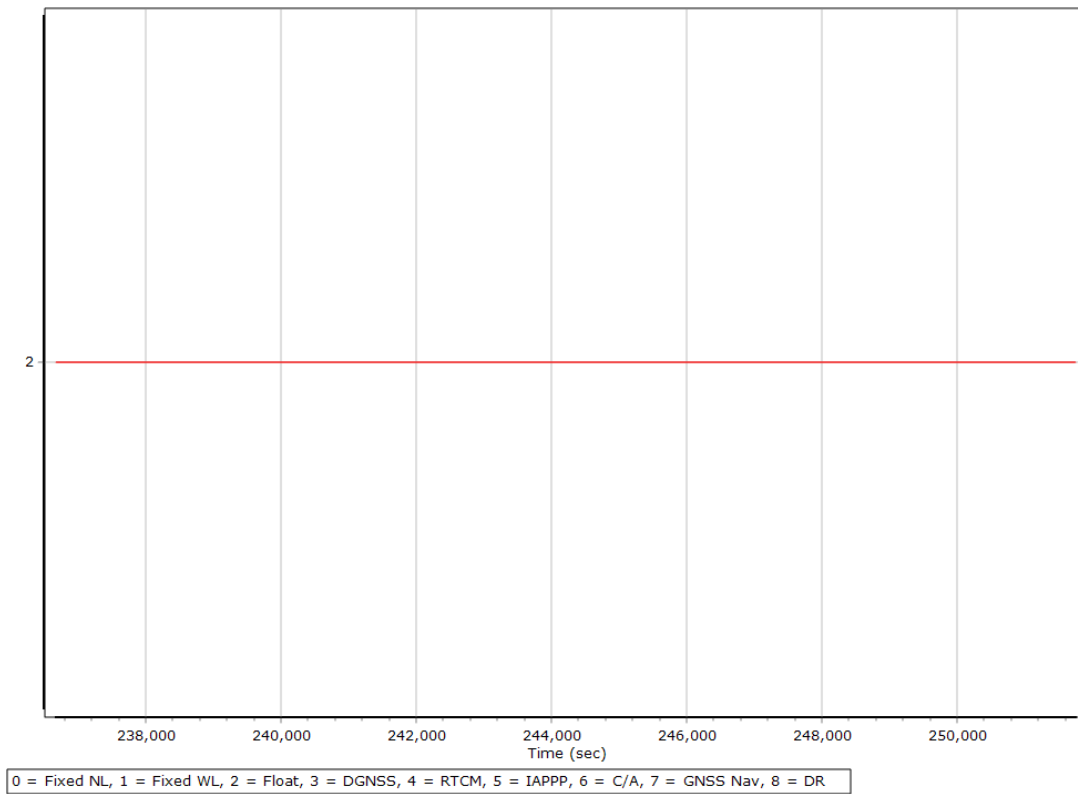


Heading Error RMS (arc-min)

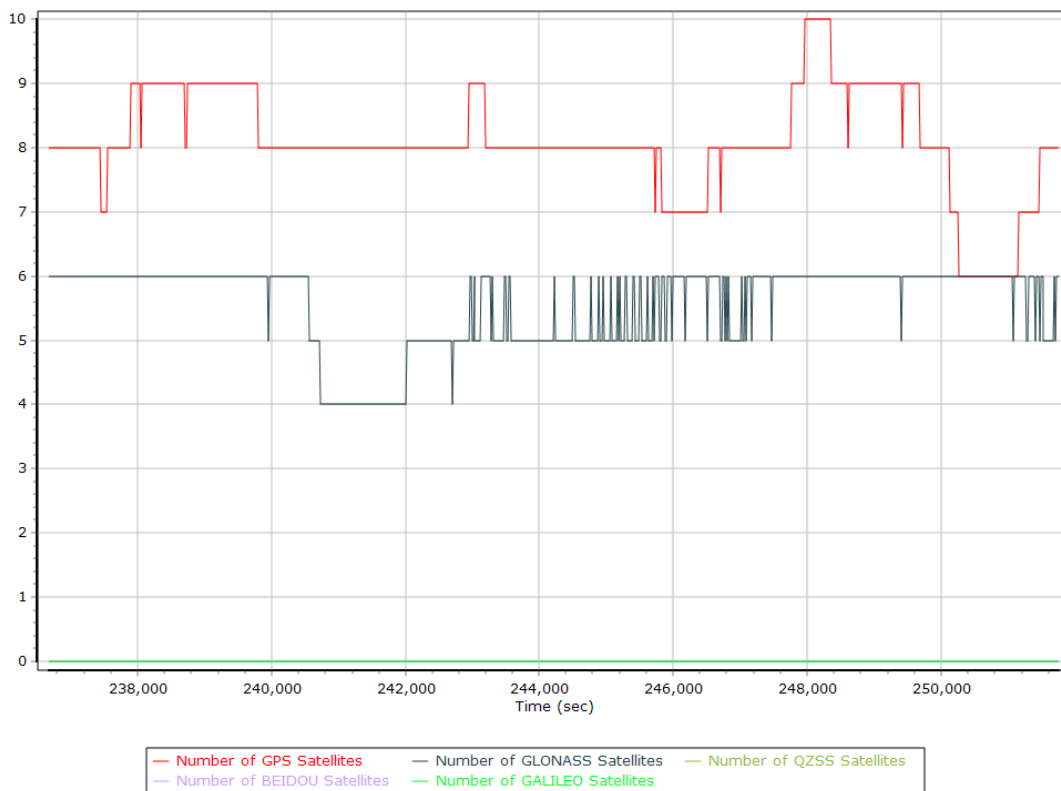


Forward Processed Solution Status

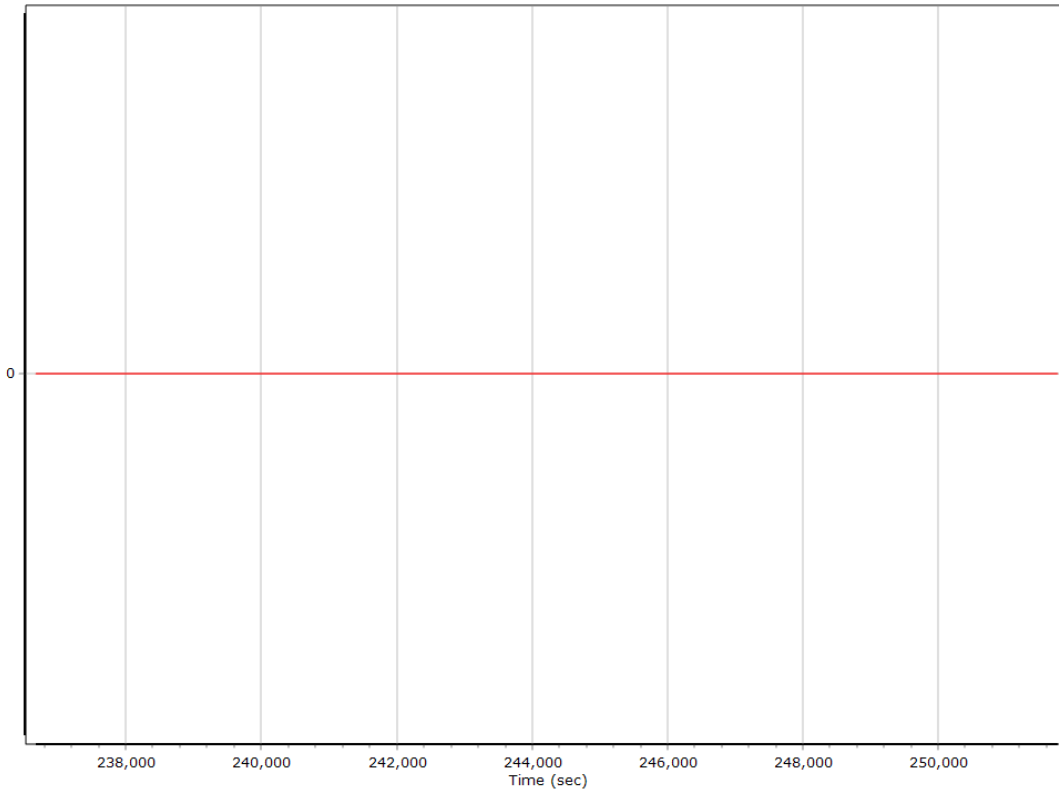
Processing Mode



Number of Satellites



Baseline Length



General Information

Mission Information

Project name	21-081_210922
Processing date	2021-10-20 17:14:28
Mission date	2021-09-22 15:24:17
Mission duration	06:42:15.000
Processing mode	IN-Fusion Trimble RTX Nav

Rover Hardware Information

Product	POS AV 610 VER6 HW2.5-12
Serial number	S/N11651
IMU type	57
Receiver type	BD982
Antenna type	AV39

Project File List

Rover Data Files

File name	File type
210922_152358_INS-GPS_1.raw	POS Data

Input Files

File Name	File Type
Ephm2650.21g	GLONASS Broadcast Ephemeris
Ephm2650.21n	GPS Broadcast Ephemeris
igl21762.sp3	GLONASS Precise Ephemeris
igl21763.sp3	GLONASS Precise Ephemeris
igl21764.sp3	GLONASS Precise Ephemeris
igs21762.sp3	GPS Precise Ephemeris
igs21763.sp3	GPS Precise Ephemeris
igs21764.sp3	GPS Precise Ephemeris

Output Files

Filename	File type
sbet_21-081_210922.out	SBET Trajectory File

Rover Data Summary

First raw data file	210922_152358_INS-GPS_1.raw		
Last raw data file	210922_152358_INS-GPS_1.raw		
Start GPS week	2176		
Start time	314638.530 (09/22/2021 15:23:58)		
End time	338773.005 (09/22/2021 22:06:13)		
Start of fine alignment	315068.810 (09/22/2021 15:31:08)		
Available subsystems	Primary GNSS, Gimbal, IMU		
POS Event Input	None		
Correction data	Trimble RTX		
IMU Installation Lever Arms & Mounting Angles			
Gimbal to IMU lever arm (m)	-0.034	-0.010	-0.374
Gimbal to IMU mounting angles (deg)	0.000	0.000	0.000
Gimbal to Primary GNSS lever arm (m)	0.980	-0.102	-1.276
Gimbal to Primary GNSS lever arm std dev (m)	-1.000		
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

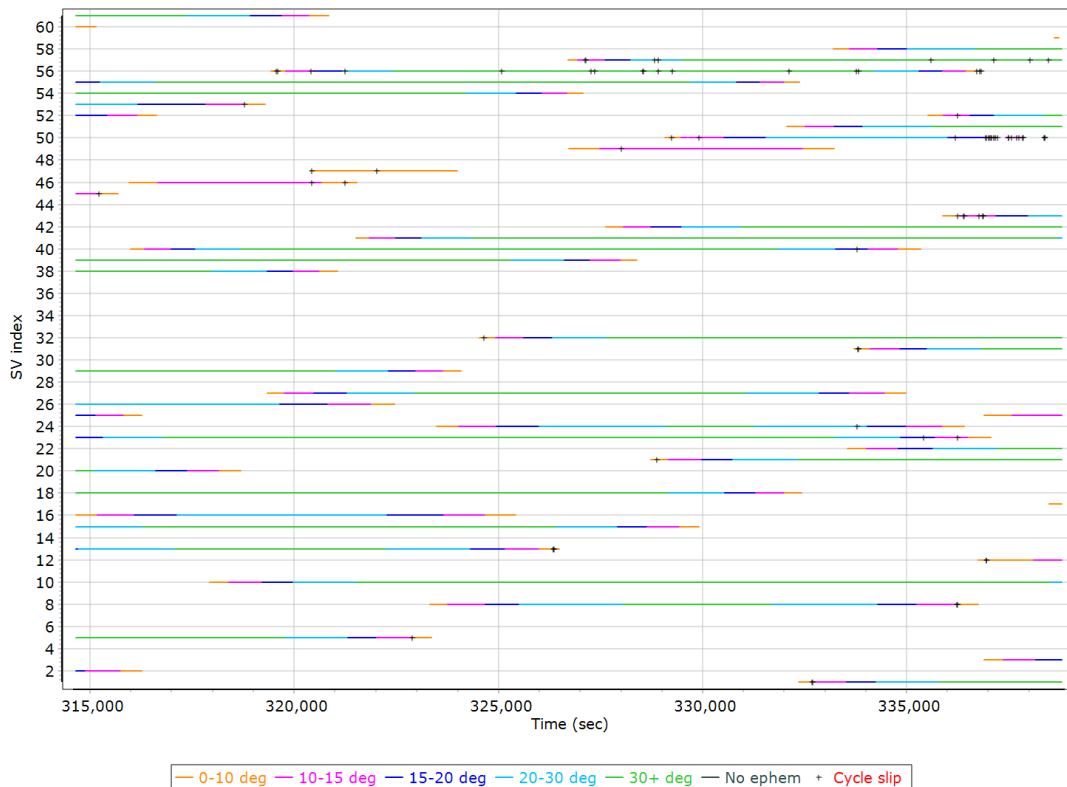
Rover Data QC

Raw IMU Import QC Summary

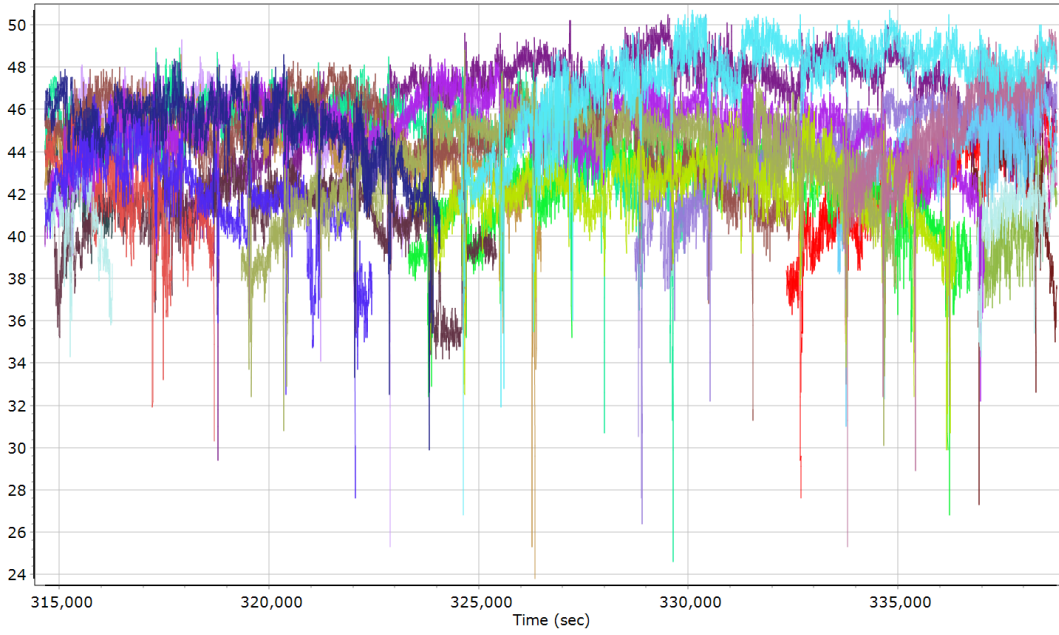
IMU data input file	imu_21-081_210922.dat
IMU data check log file	imudt_21-081_210922.log
IMU Records Processed	4826382
Termination Status	Normal
IMU Anomalies	0

Primary Observables & Satellite Data

GPS/GLONASS L1 Satellite Lock/Elevation

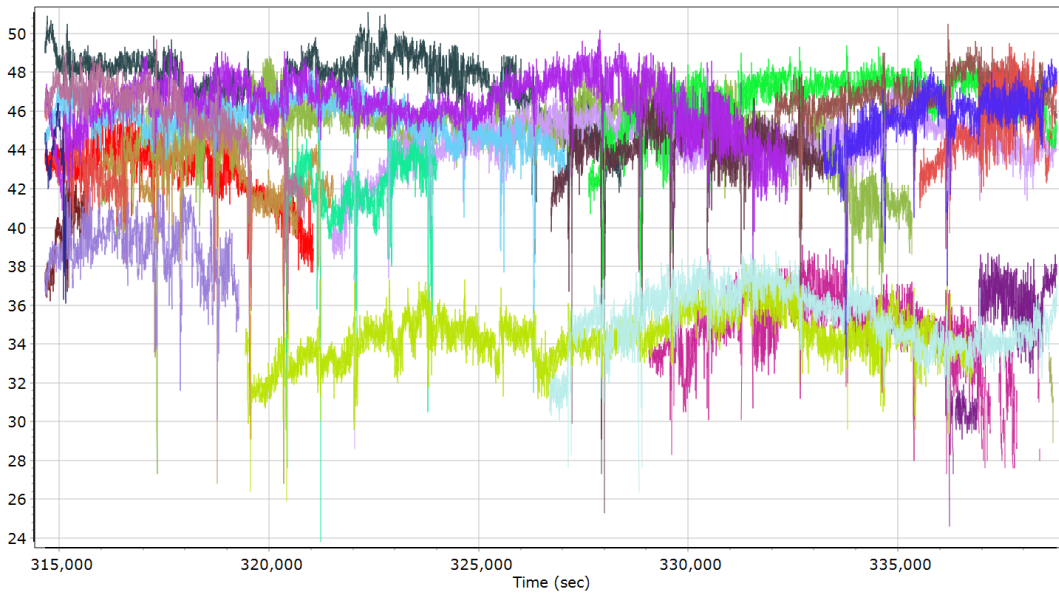


GPS L1 SNR



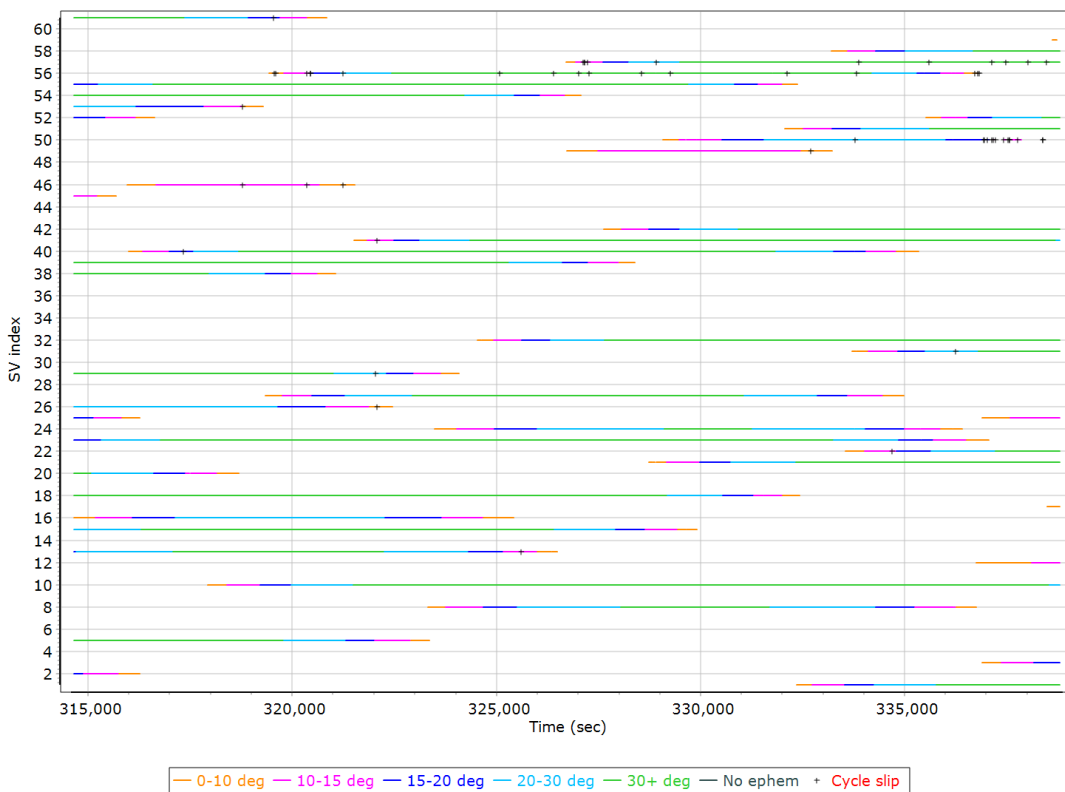
- | | | | |
|---------------------------|---------------------------|---------------------------|---------------------------|
| GPS PRN 01 L1 SNR (dB/Hz) | GPS PRN 02 L1 SNR (dB/Hz) | GPS PRN 03 L1 SNR (dB/Hz) | GPS PRN 05 L1 SNR (dB/Hz) |
| GPS PRN 08 L1 SNR (dB/Hz) | GPS PRN 10 L1 SNR (dB/Hz) | GPS PRN 12 L1 SNR (dB/Hz) | GPS PRN 13 L1 SNR (dB/Hz) |
| GPS PRN 15 L1 SNR (dB/Hz) | GPS PRN 16 L1 SNR (dB/Hz) | GPS PRN 17 L1 SNR (dB/Hz) | GPS PRN 18 L1 SNR (dB/Hz) |
| GPS PRN 20 L1 SNR (dB/Hz) | GPS PRN 21 L1 SNR (dB/Hz) | GPS PRN 22 L1 SNR (dB/Hz) | GPS PRN 23 L1 SNR (dB/Hz) |
| GPS PRN 24 L1 SNR (dB/Hz) | GPS PRN 25 L1 SNR (dB/Hz) | GPS PRN 26 L1 SNR (dB/Hz) | GPS PRN 27 L1 SNR (dB/Hz) |
| GPS PRN 29 L1 SNR (dB/Hz) | GPS PRN 31 L1 SNR (dB/Hz) | GPS PRN 32 L1 SNR (dB/Hz) | |

GLONASS L1 SNR

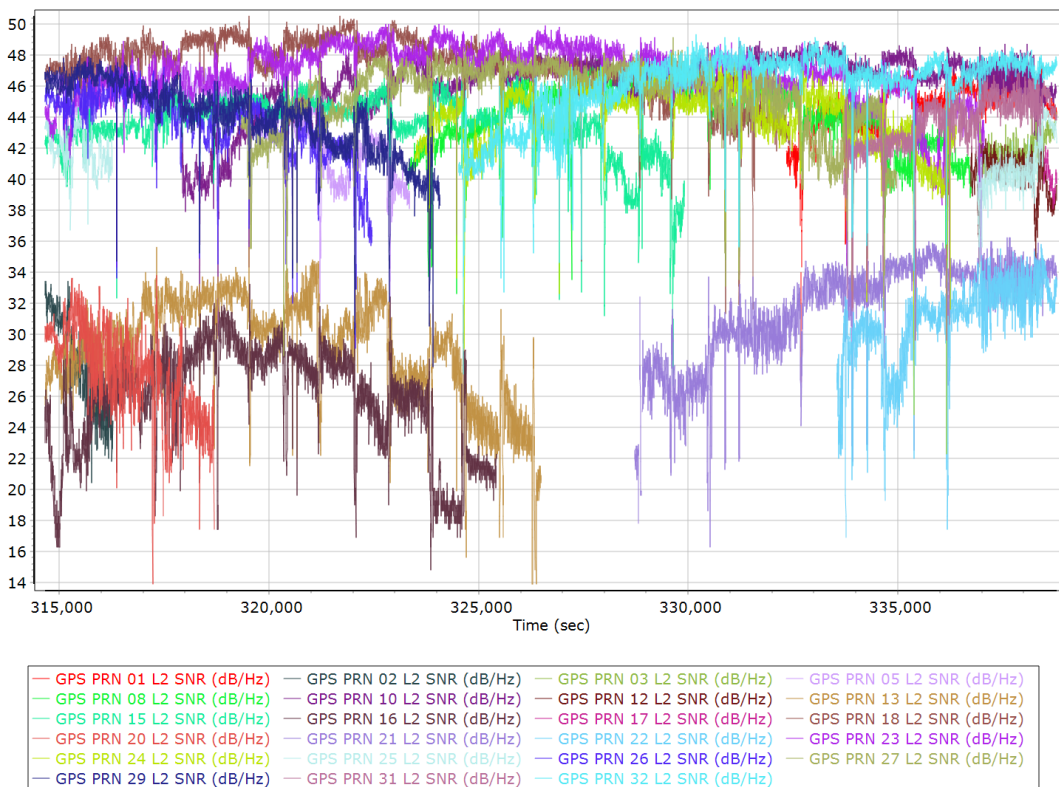


- | | | |
|---------------------------|---------------------------|---------------------------|
| GLONASS 01 L1 SNR (dB/Hz) | GLONASS 02 L1 SNR (dB/Hz) | GLONASS 03 L1 SNR (dB/Hz) |
| GLONASS 04 L1 SNR (dB/Hz) | GLONASS 05 L1 SNR (dB/Hz) | GLONASS 06 L1 SNR (dB/Hz) |
| GLONASS 08 L1 SNR (dB/Hz) | GLONASS 09 L1 SNR (dB/Hz) | GLONASS 10 L1 SNR (dB/Hz) |
| GLONASS 12 L1 SNR (dB/Hz) | GLONASS 13 L1 SNR (dB/Hz) | GLONASS 14 L1 SNR (dB/Hz) |
| GLONASS 15 L1 SNR (dB/Hz) | GLONASS 16 L1 SNR (dB/Hz) | GLONASS 17 L1 SNR (dB/Hz) |
| GLONASS 18 L1 SNR (dB/Hz) | GLONASS 19 L1 SNR (dB/Hz) | GLONASS 20 L1 SNR (dB/Hz) |
| GLONASS 21 L1 SNR (dB/Hz) | GLONASS 22 L1 SNR (dB/Hz) | GLONASS 23 L1 SNR (dB/Hz) |
| GLONASS 24 L1 SNR (dB/Hz) | | |

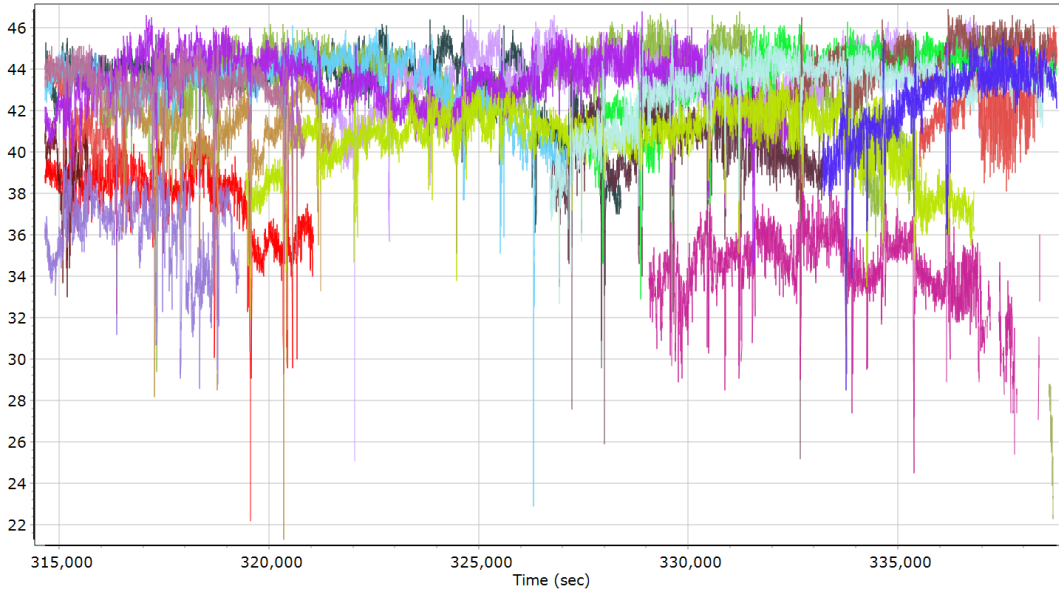
GPS/GLONASS L2 Satellite Lock/Elevation



GPS L2 SNR

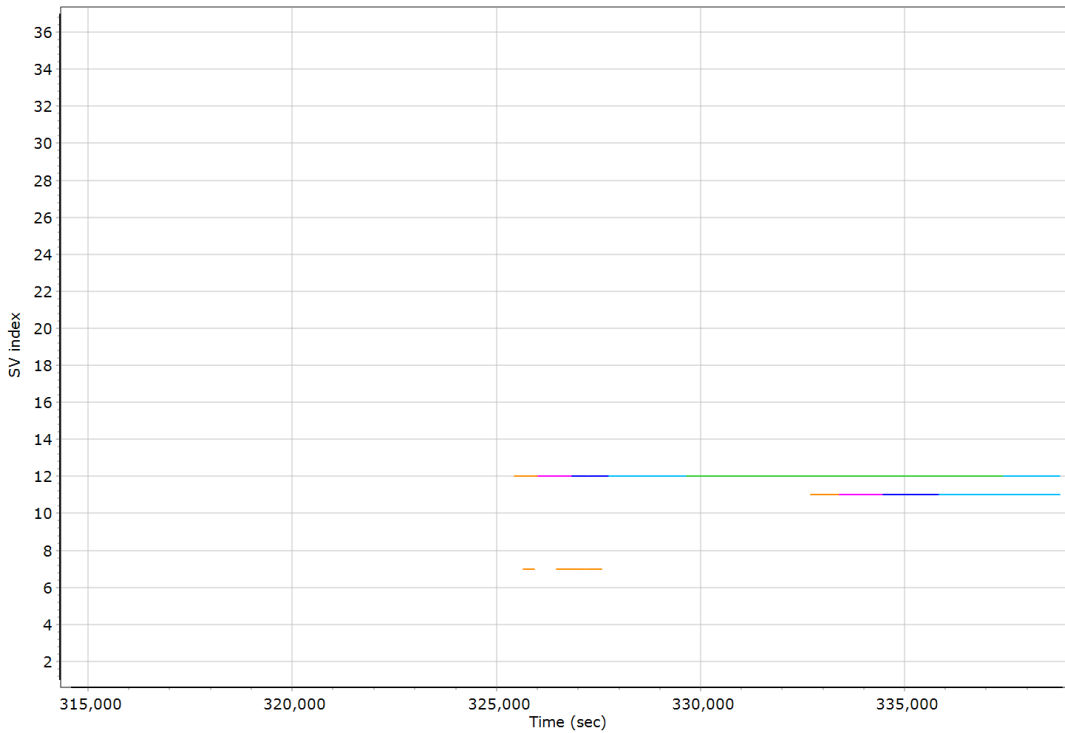


GLONASS L2 SNR



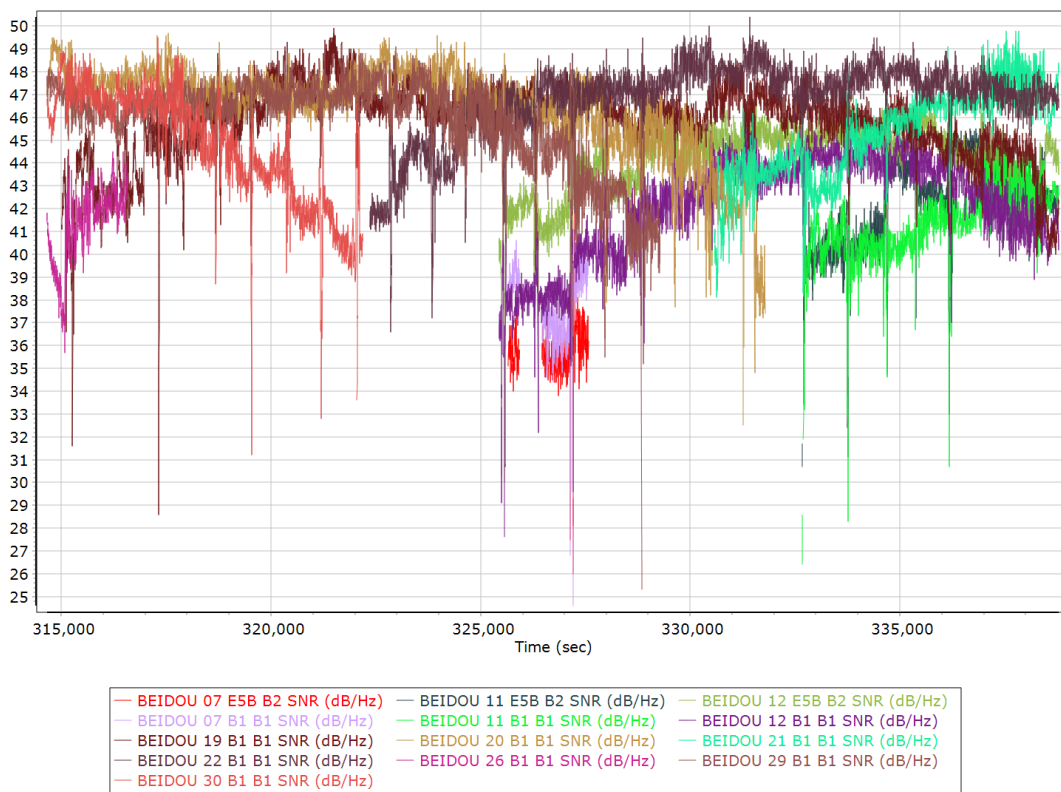
- GLONASS 01 L2 SNR (dB/Hz)
- GLONASS 02 L2 SNR (dB/Hz)
- GLONASS 03 L2 SNR (dB/Hz)
- GLONASS 04 L2 SNR (dB/Hz)
- GLONASS 05 L2 SNR (dB/Hz)
- GLONASS 06 L2 SNR (dB/Hz)
- GLONASS 08 L2 SNR (dB/Hz)
- GLONASS 09 L2 SNR (dB/Hz)
- GLONASS 10 L2 SNR (dB/Hz)
- GLONASS 12 L2 SNR (dB/Hz)
- GLONASS 13 L2 SNR (dB/Hz)
- GLONASS 14 L2 SNR (dB/Hz)
- GLONASS 15 L2 SNR (dB/Hz)
- GLONASS 16 L2 SNR (dB/Hz)
- GLONASS 17 L2 SNR (dB/Hz)
- GLONASS 18 L2 SNR (dB/Hz)
- GLONASS 19 L2 SNR (dB/Hz)
- GLONASS 20 L2 SNR (dB/Hz)
- GLONASS 21 L2 SNR (dB/Hz)
- GLONASS 22 L2 SNR (dB/Hz)
- GLONASS 23 L2 SNR (dB/Hz)
- GLONASS 24 L2 SNR (dB/Hz)

BEIDOU Satellite Lock/Elevation

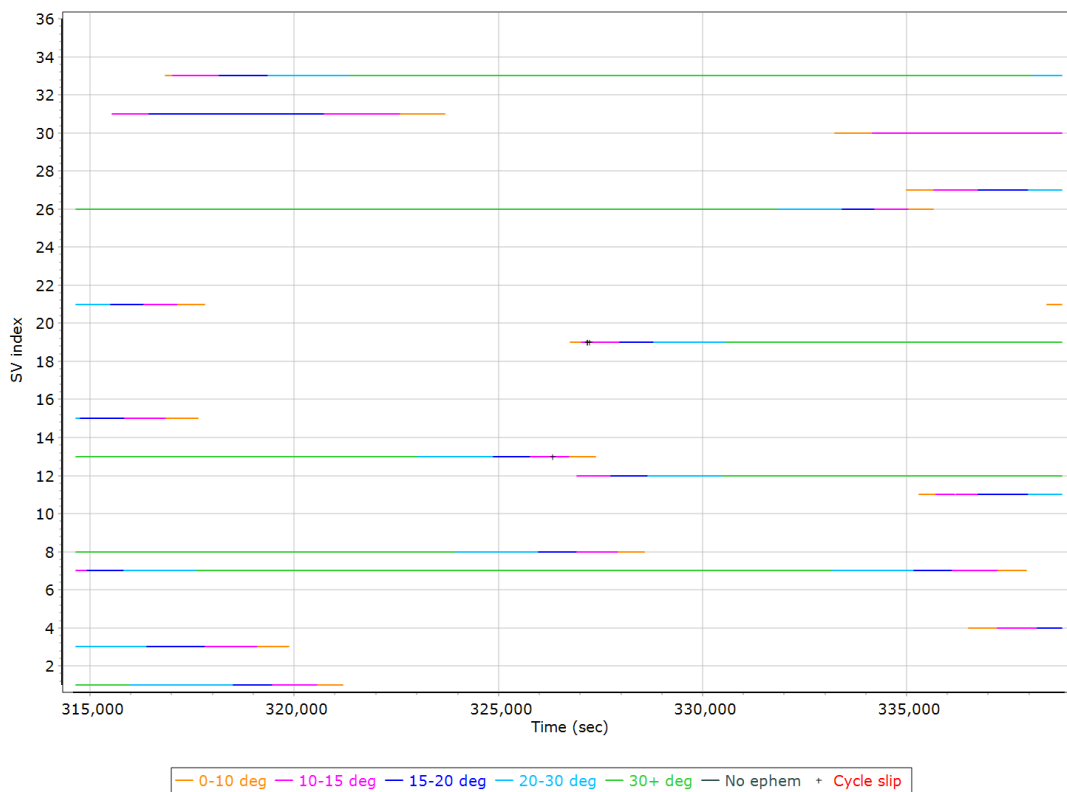


- 0-10 deg
- 10-15 deg
- 15-20 deg
- 20-30 deg
- 30+ deg
- No ephem
- + Cycle slip

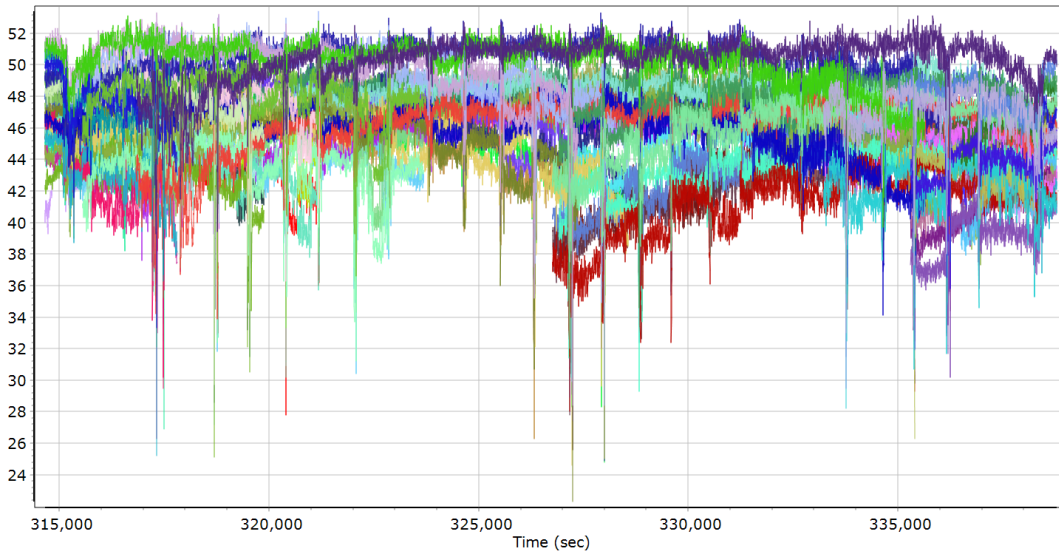
BEIDOU SNR



GALILEO Satellite Lock/Elevation



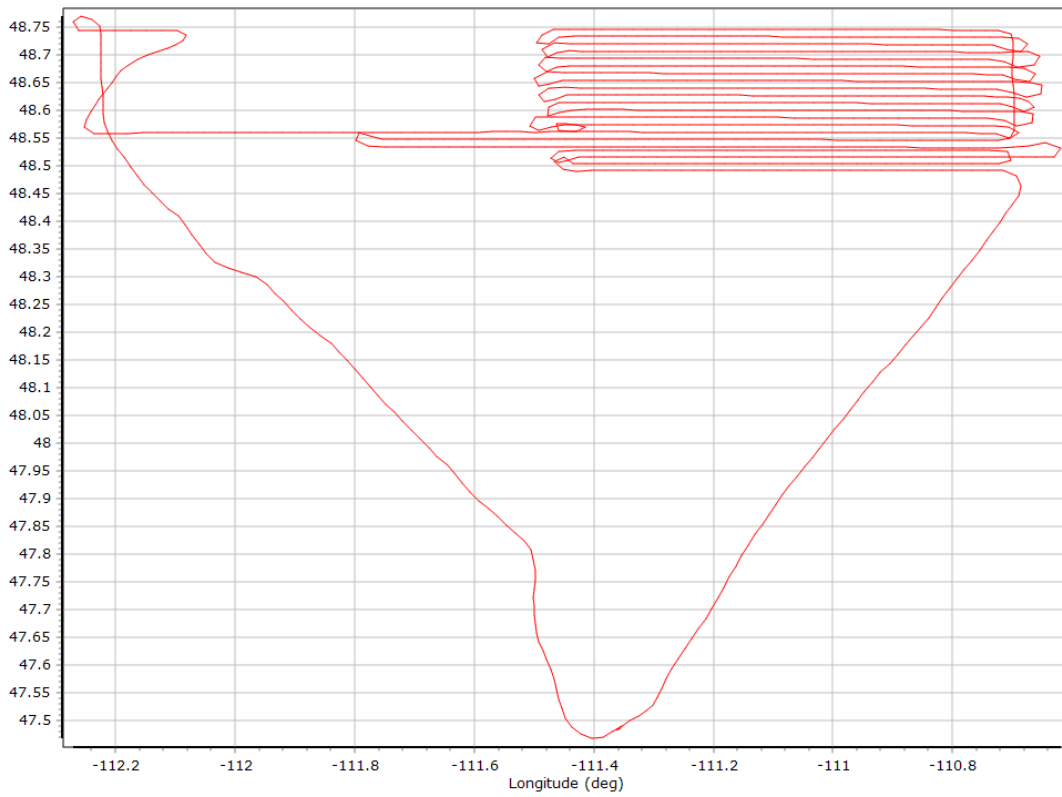
GALILEO SNR



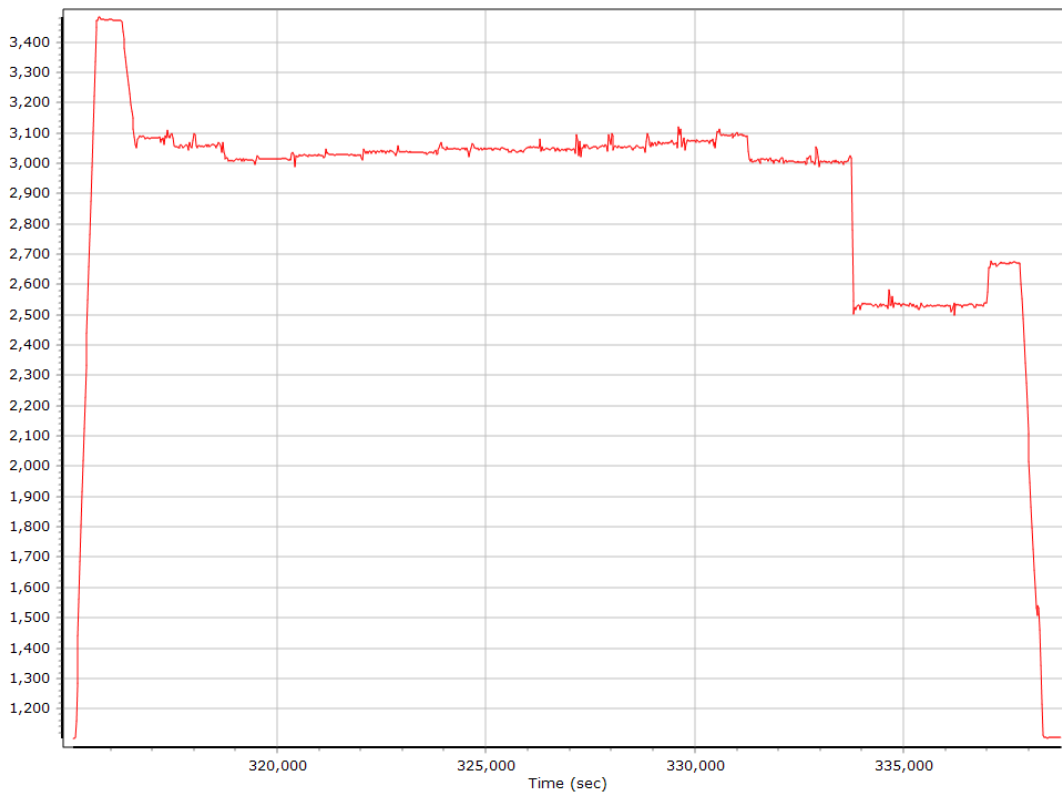
— GALILEO 01 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 03 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 04 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 07 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 08 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 11 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 12 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 13 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 15 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 19 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 21 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 26 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 27 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 30 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 31 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)	— GALILEO 33 L1 BOC_1_1_DP_MBOC SNR (dB/Hz)
— GALILEO 01 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 03 L5E5A BPSK10_PD SNR (dB/Hz)
— GALILEO 04 L5E5A BPSK10_PD SNR (dB/Hz)	— GALILEO 07 L5E5A BPSK10_PD SNR (dB/Hz)

Smoothed Trajectory Information

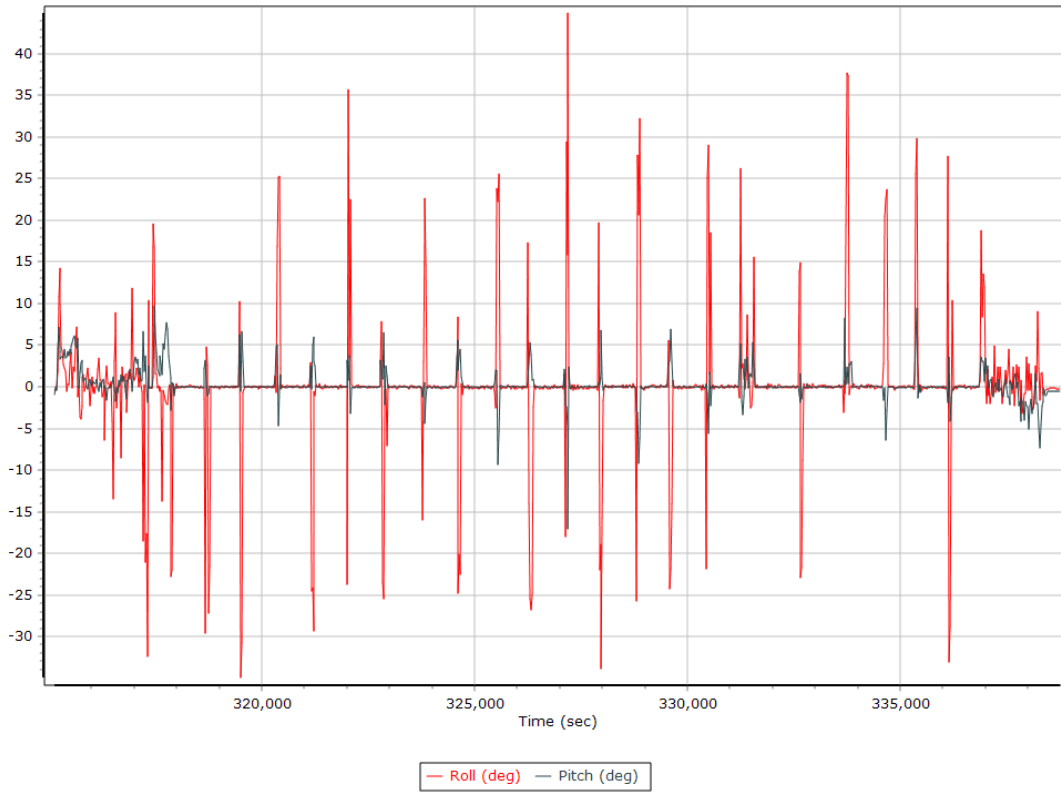
Top View



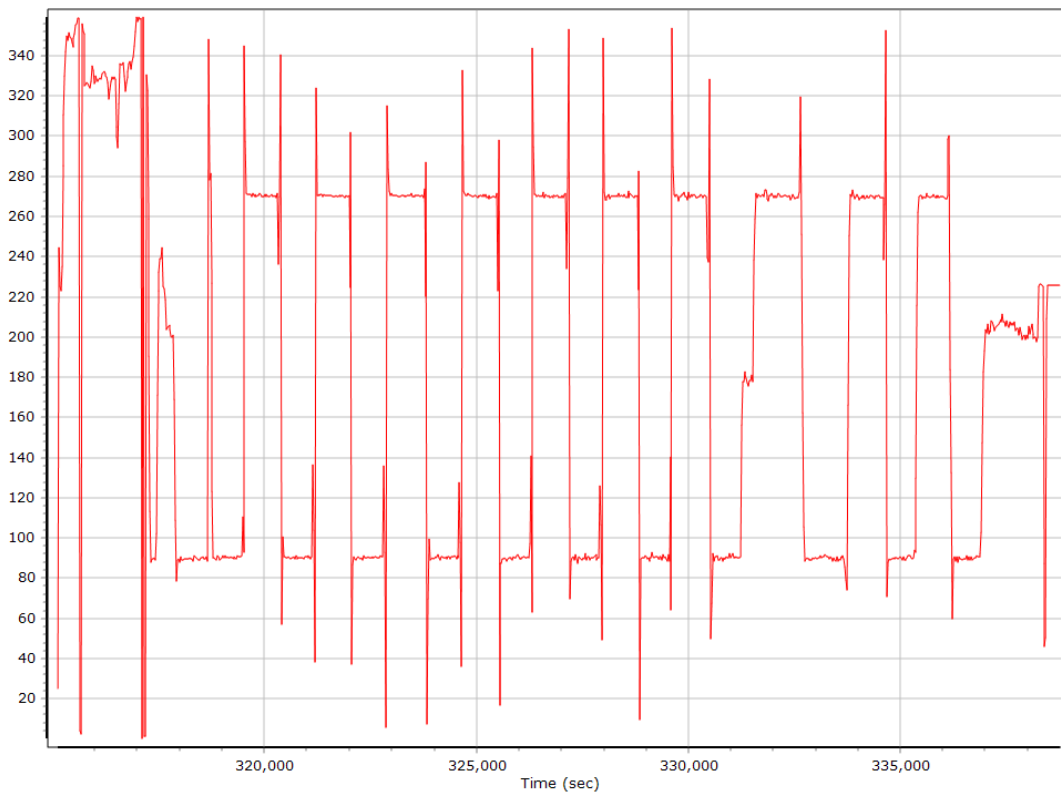
Altitude



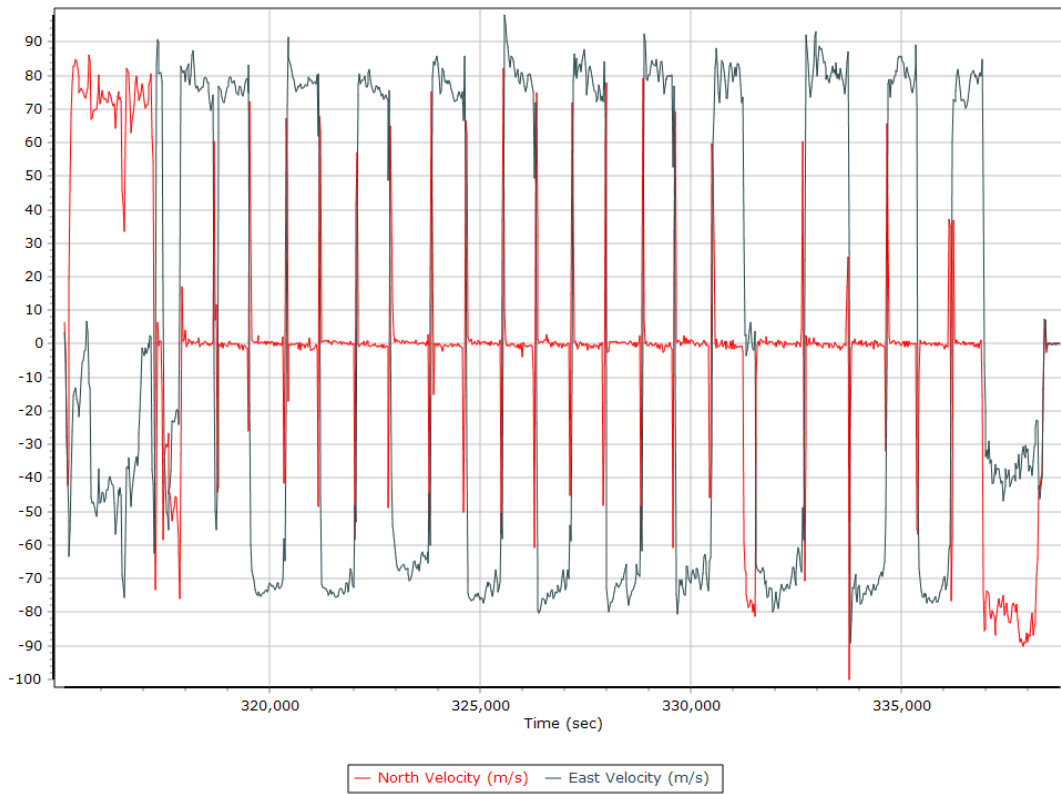
Roll/Pitch



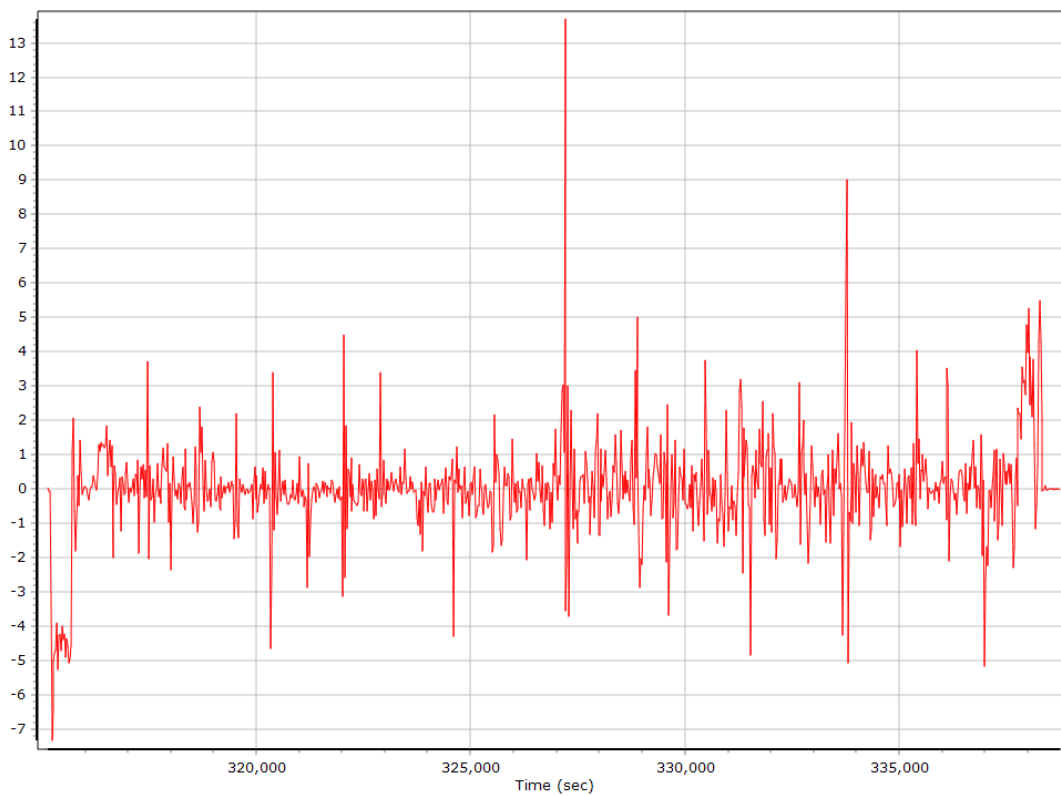
Heading



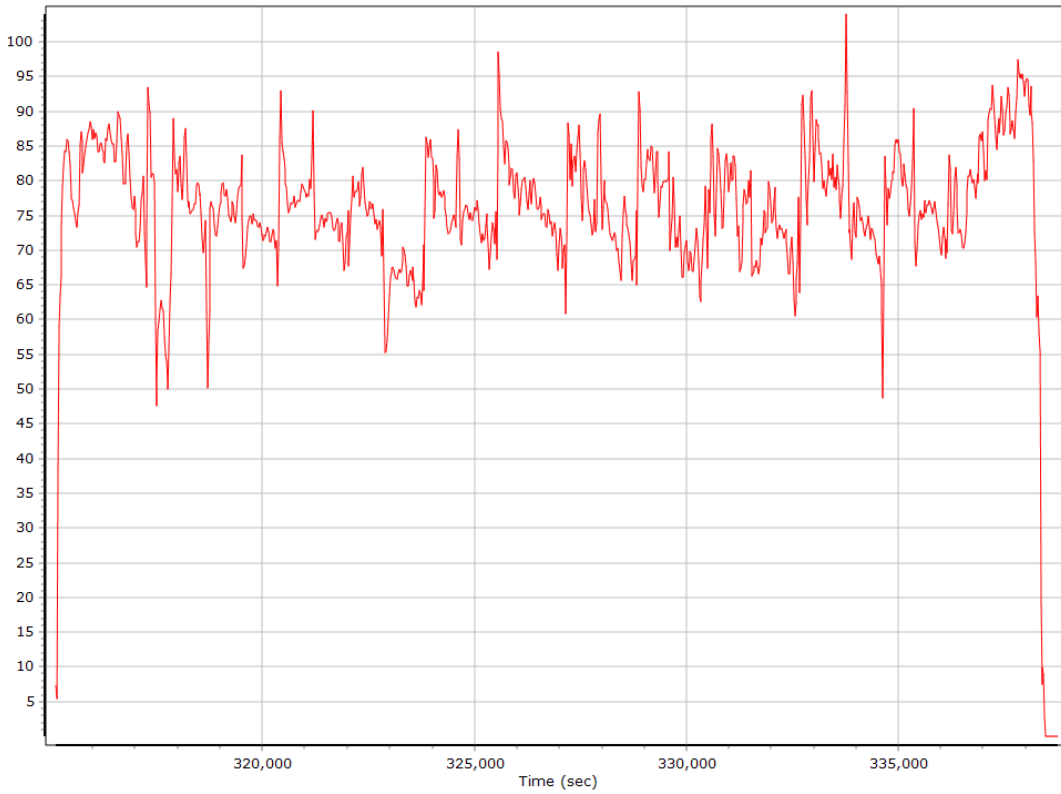
North/East Velocity



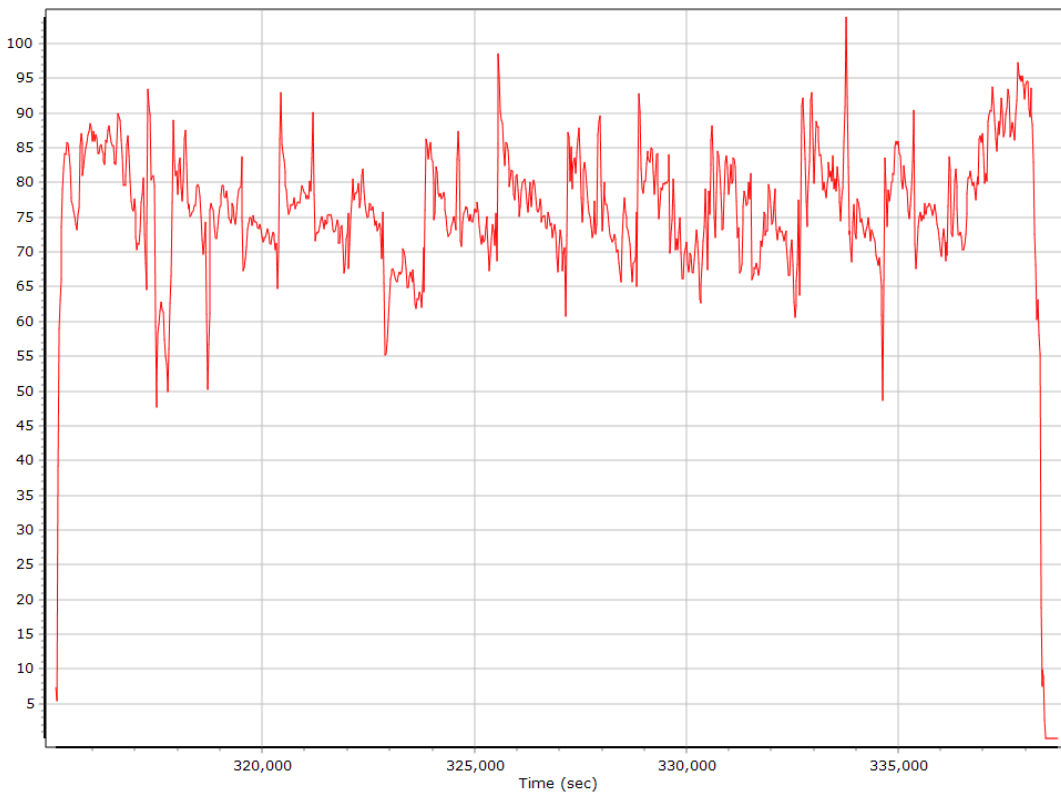
Down Velocity



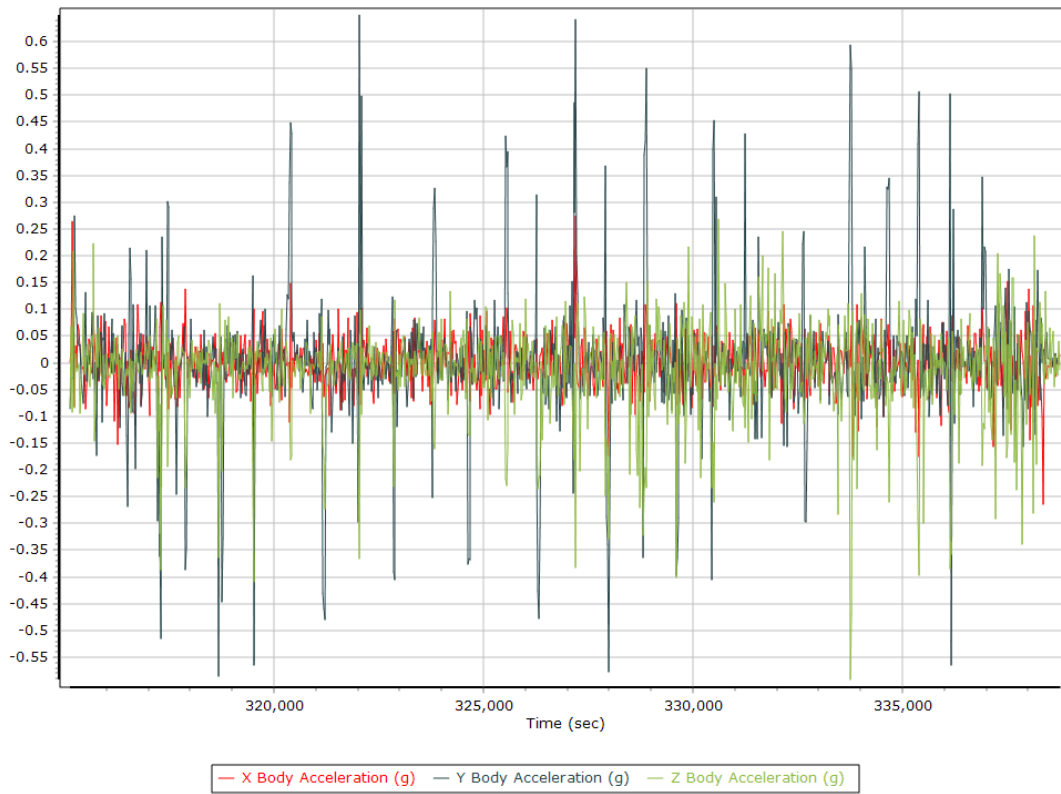
Total Speed



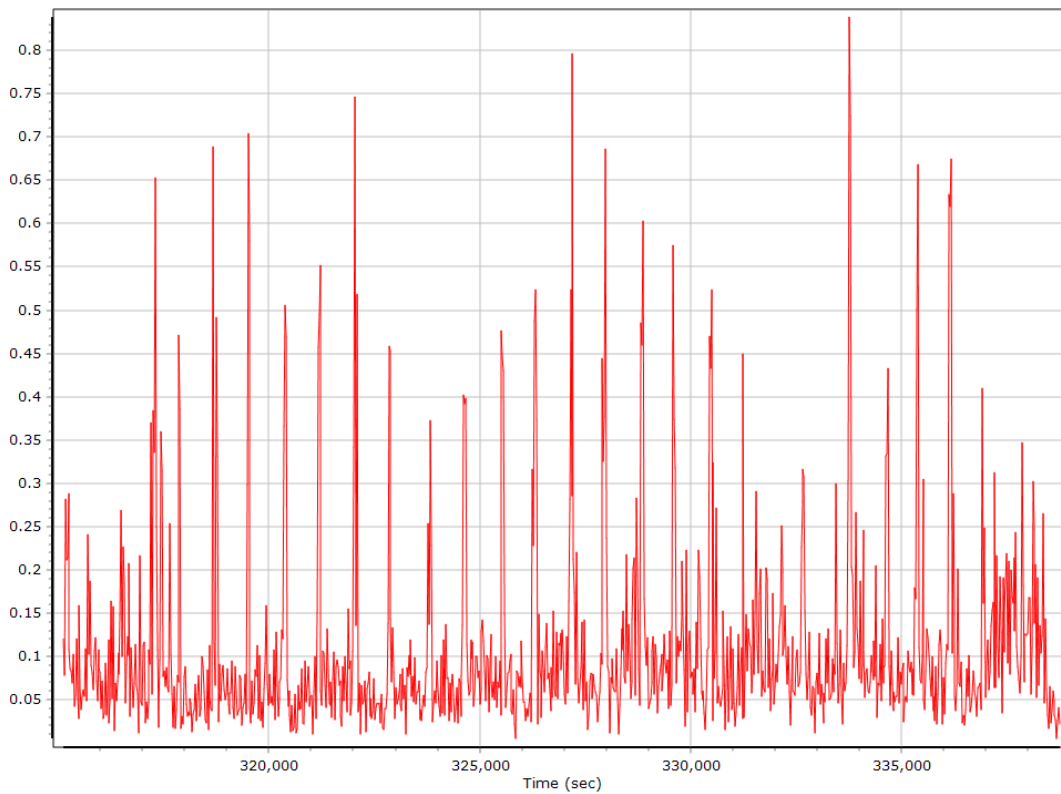
Ground Speed



Body Acceleration



Total Body Acceleration

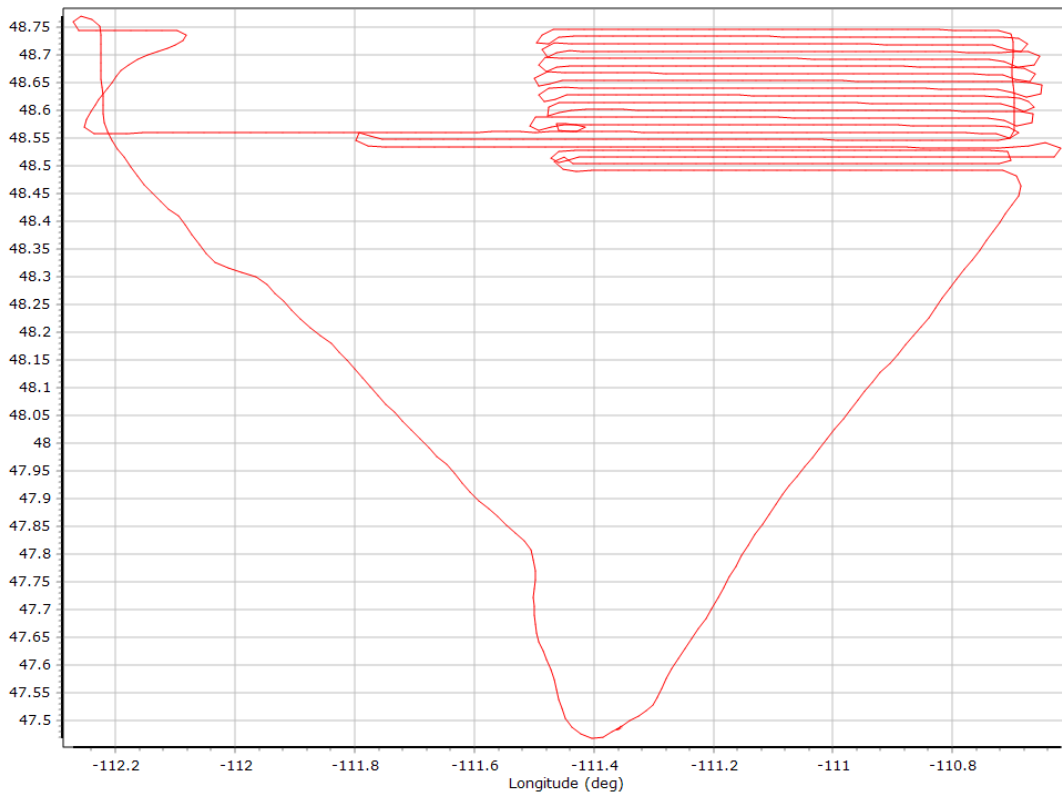


Body Angular Rate

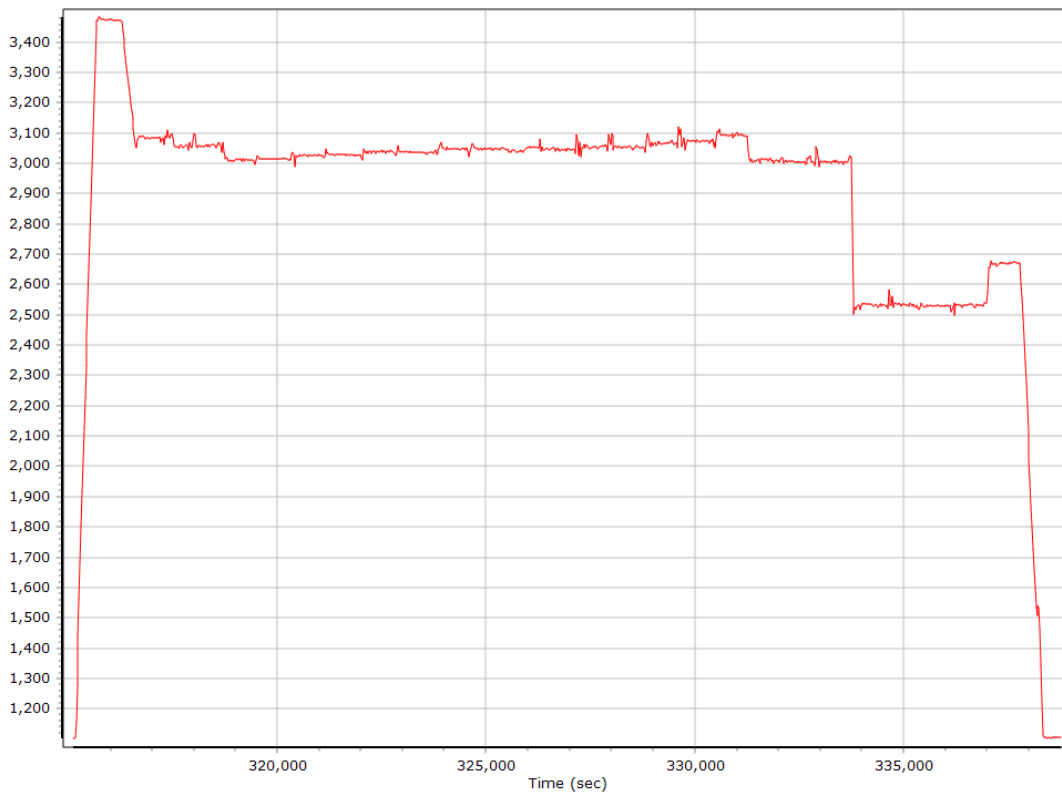


Forward Processed Trajectory Information

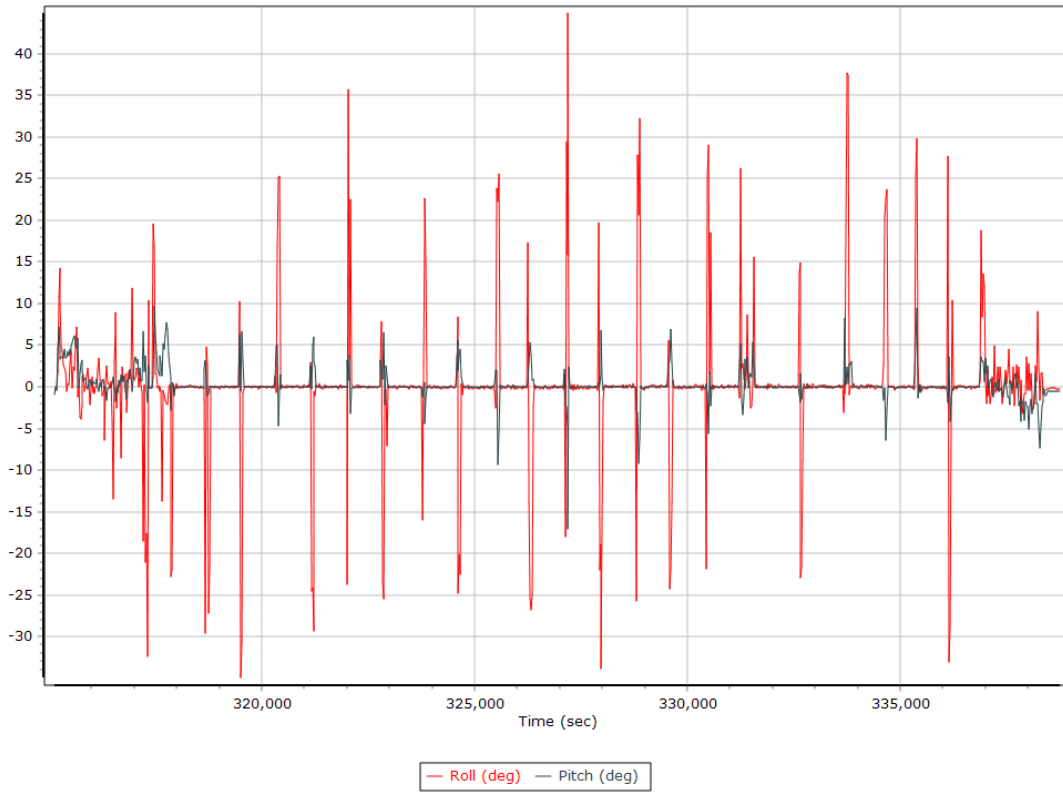
Top View



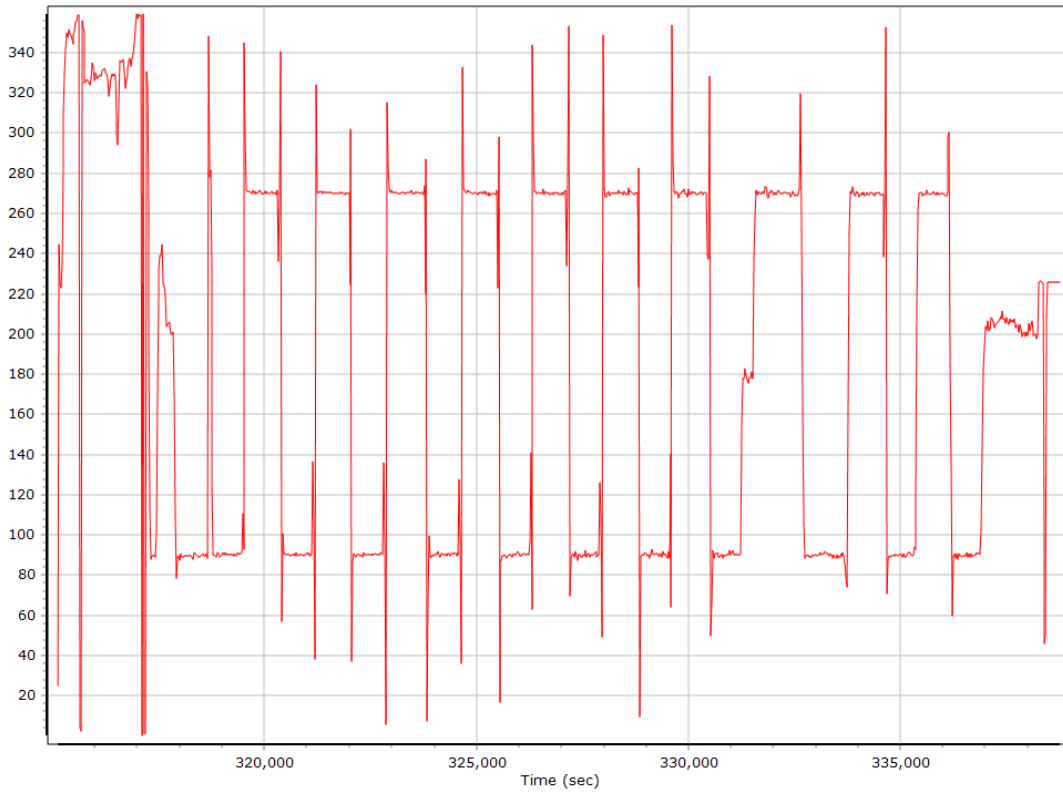
Altitude



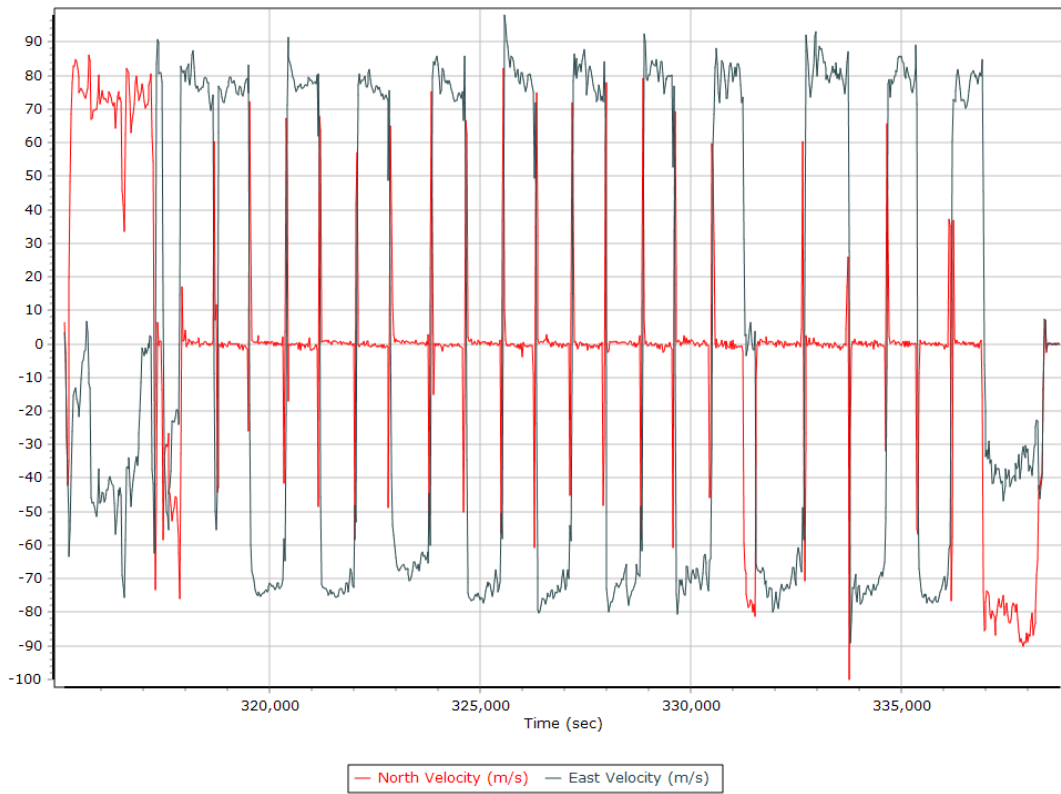
Roll/Pitch



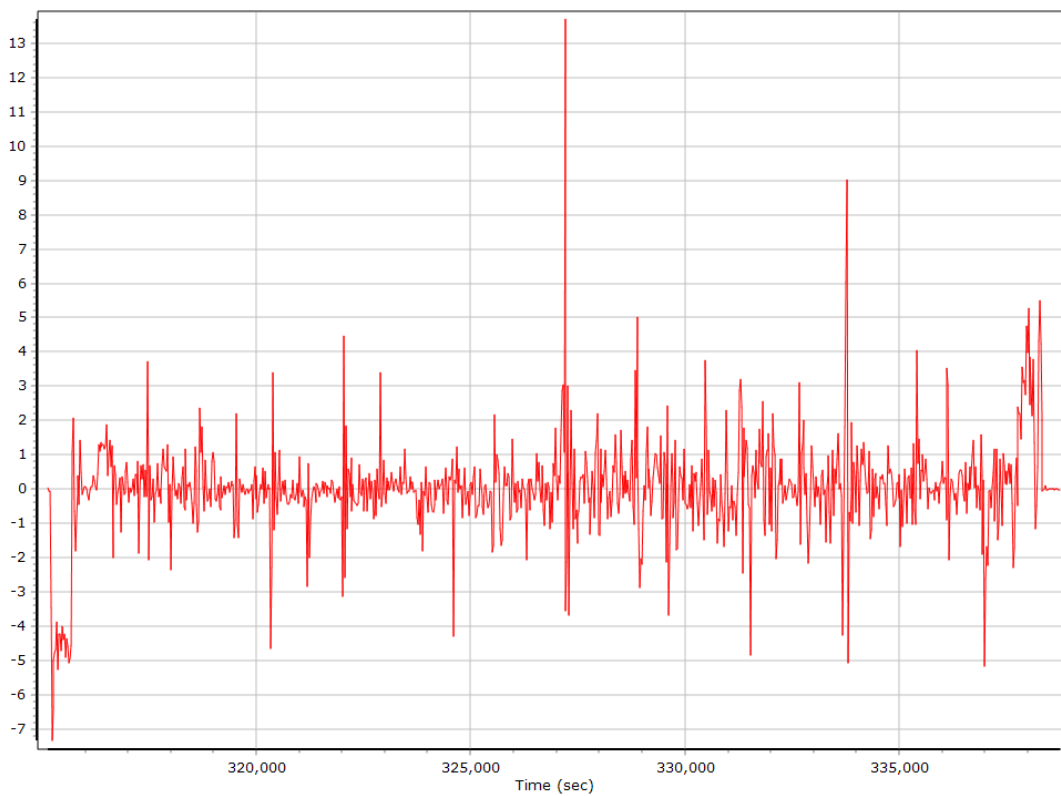
Heading



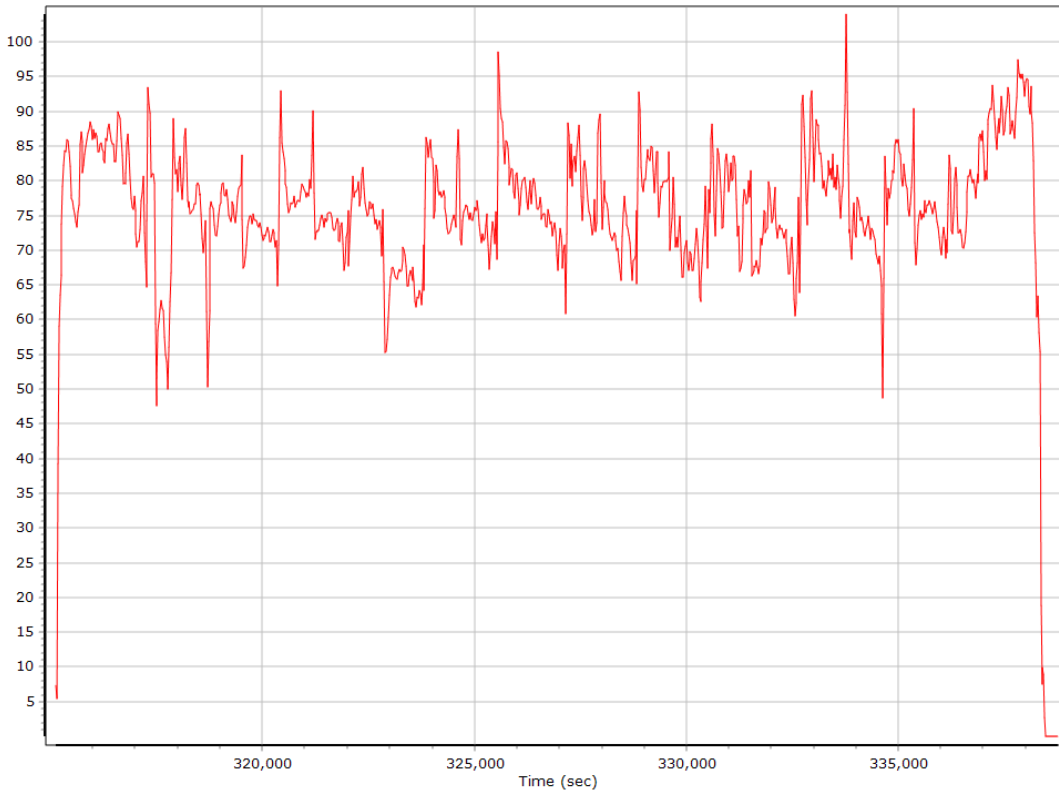
North/East Velocity



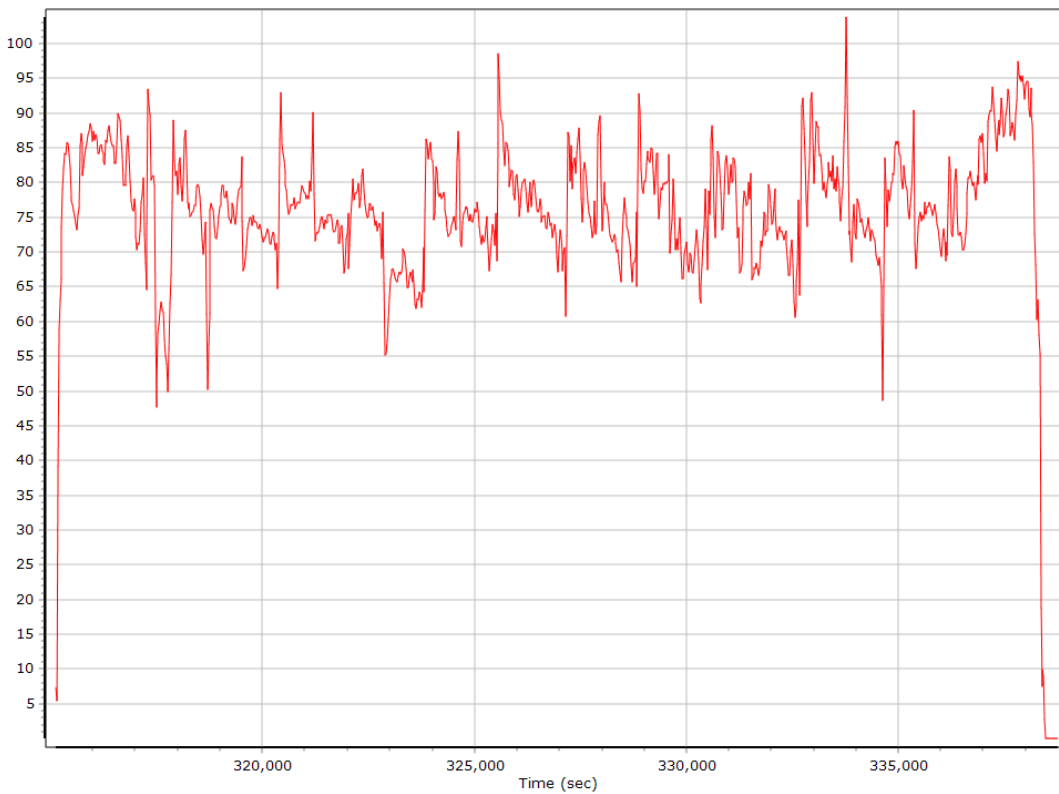
Down Velocity



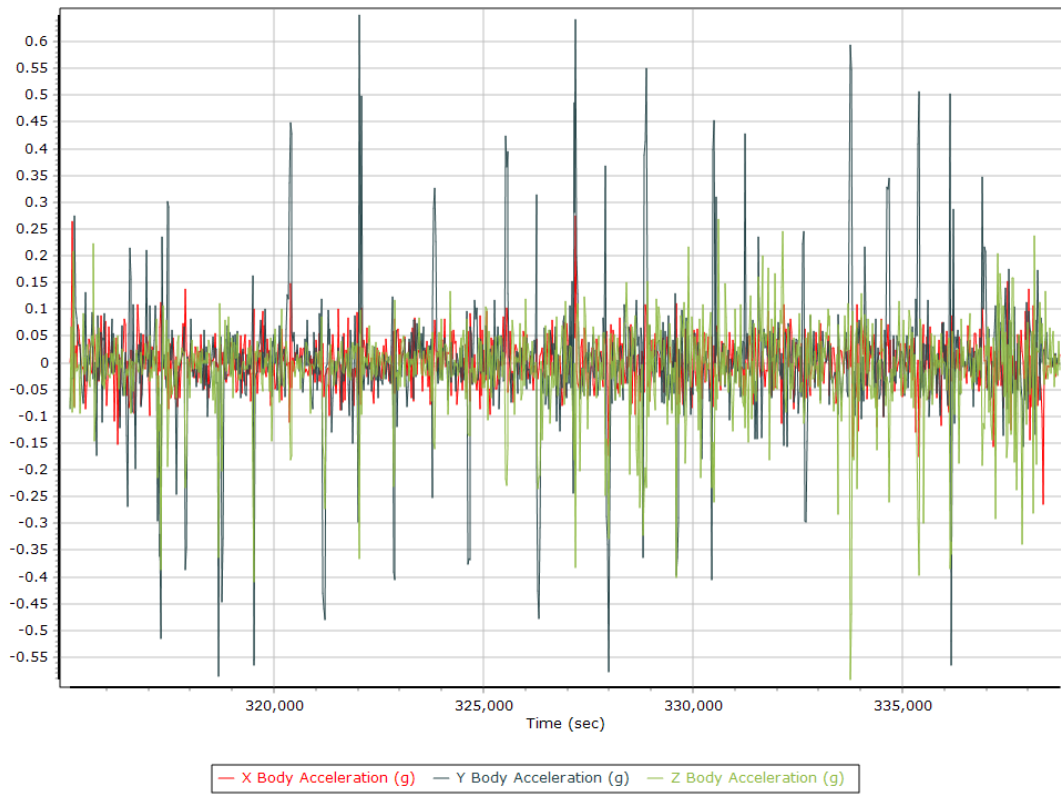
Total Speed



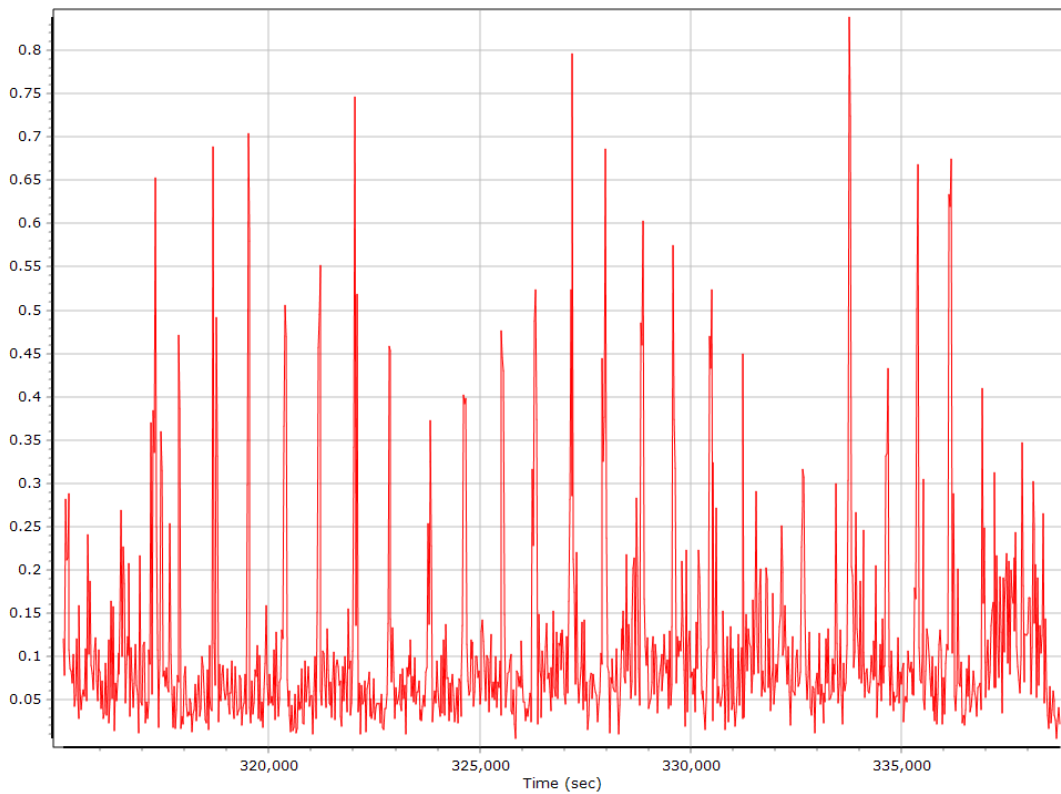
Ground Speed



Body Acceleration



Total Body Acceleration



Body Angular Rate



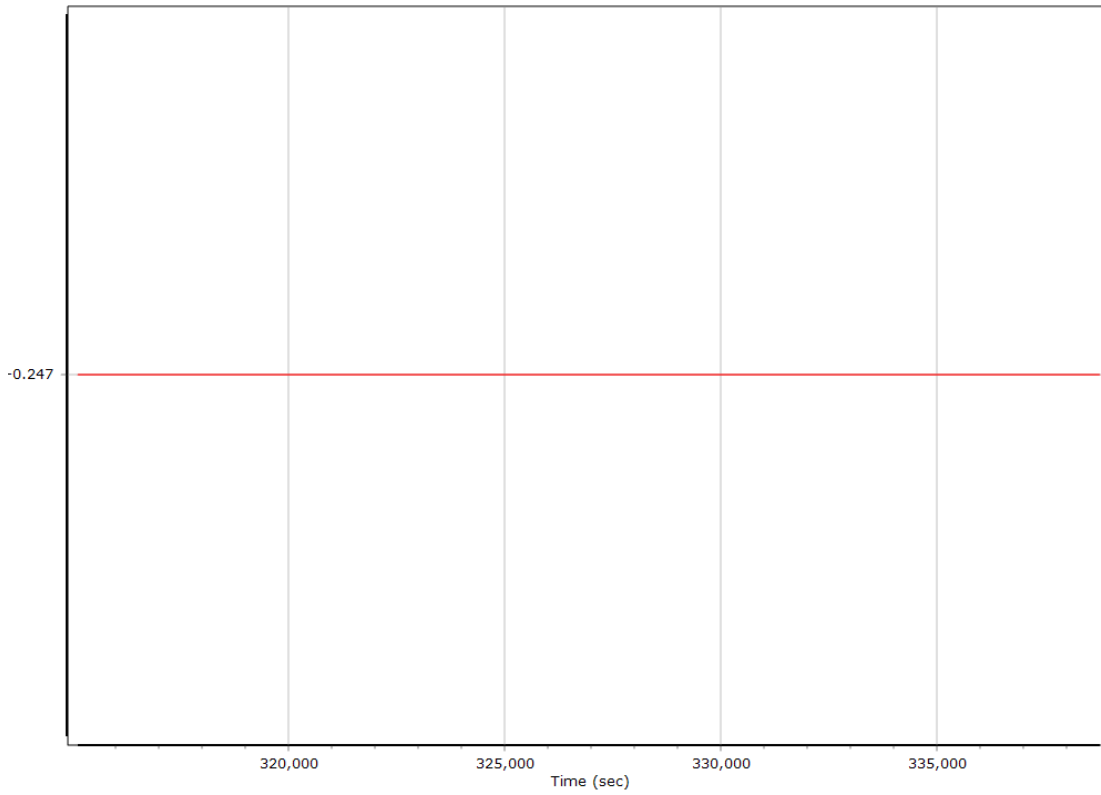
GNSS-Inertial Processor Configuration

Processing mode	IN-Fusion Trimble RTX Nav		
Stabilized mount	True		
Processing start time	314639.000 (09/22/2021 15:23:59)		
Processing end time	338774.000 (09/22/2021 22:06:14)		
Initial attitude source	Real-Time VNAV/RNAV Attitude		
IMU Sensor Context	Processing with Onboard IMU		
Gimbal to IMU lever arm (m)	-0.034	-0.010	-0.374
Gimbal to IMU mounting angles (deg)	0.000	0.000	0.000
Gimbal to Primary GNSS lever arm (m)	-0.247	-0.020	-1.300
Gimbal to Primary GNSS lever arm std dev (m)	0.030	0.030	0.030
Aircraft to Reference mounting angles (deg)	0.000	0.000	0.000

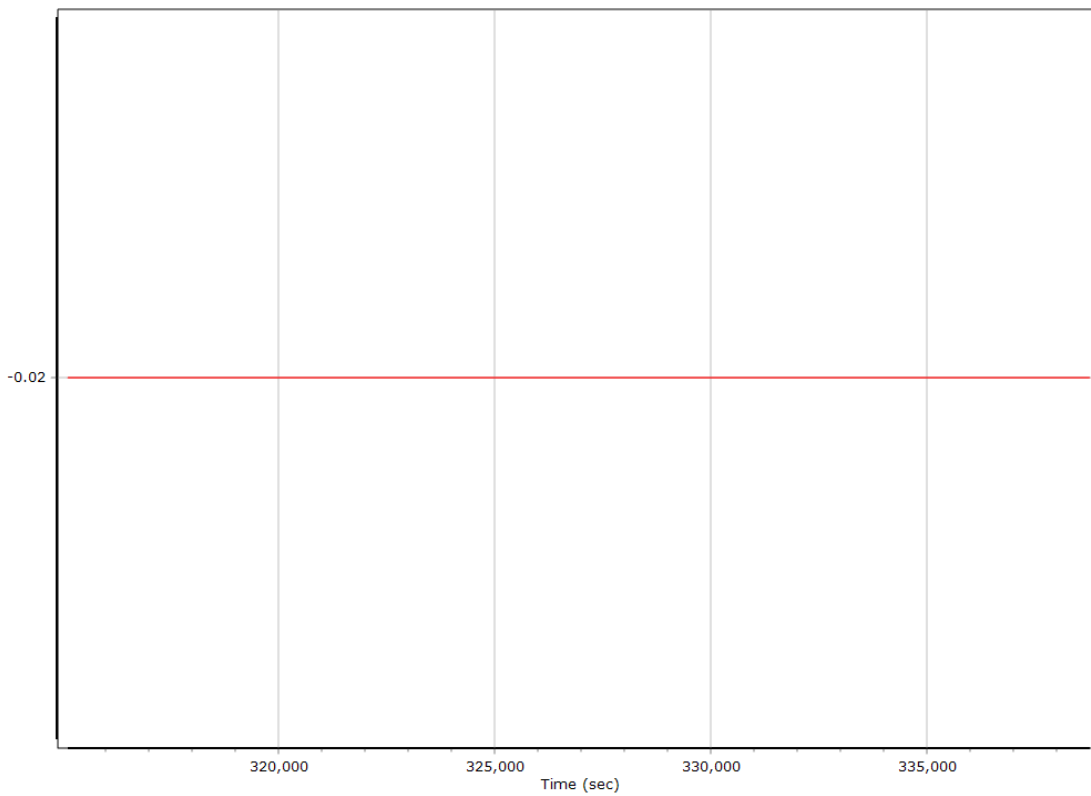
Calibrated Installation Parameters

Reference-Primary GNSS Lever Arm (m)

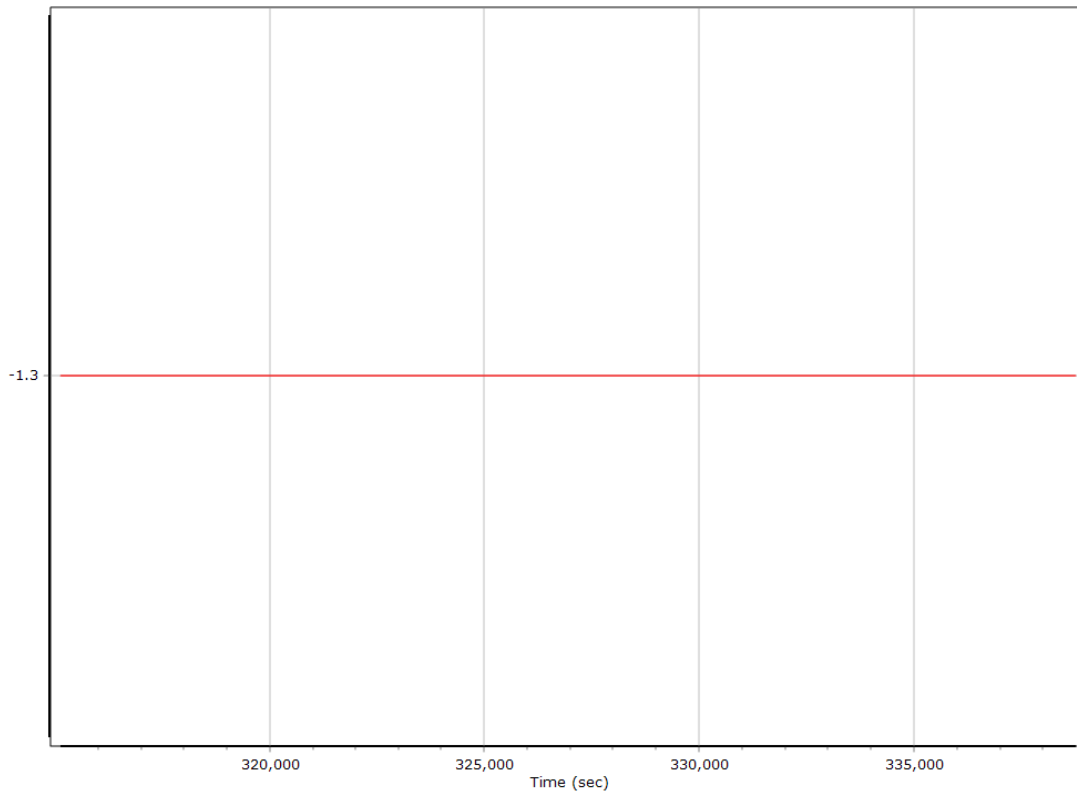
X Reference-Primary GNSS Lever Arm (m)



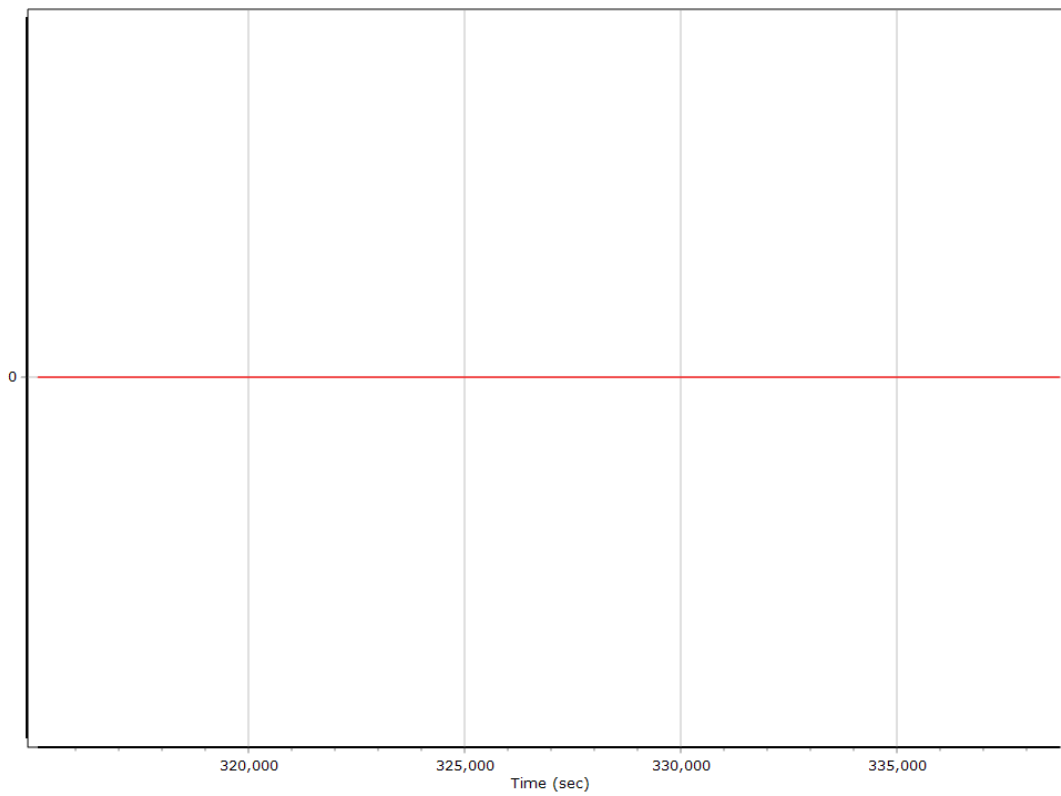
Y Reference-Primary GNSS Lever Arm (m)



Z Reference-Primary GNSS Lever Arm (m)



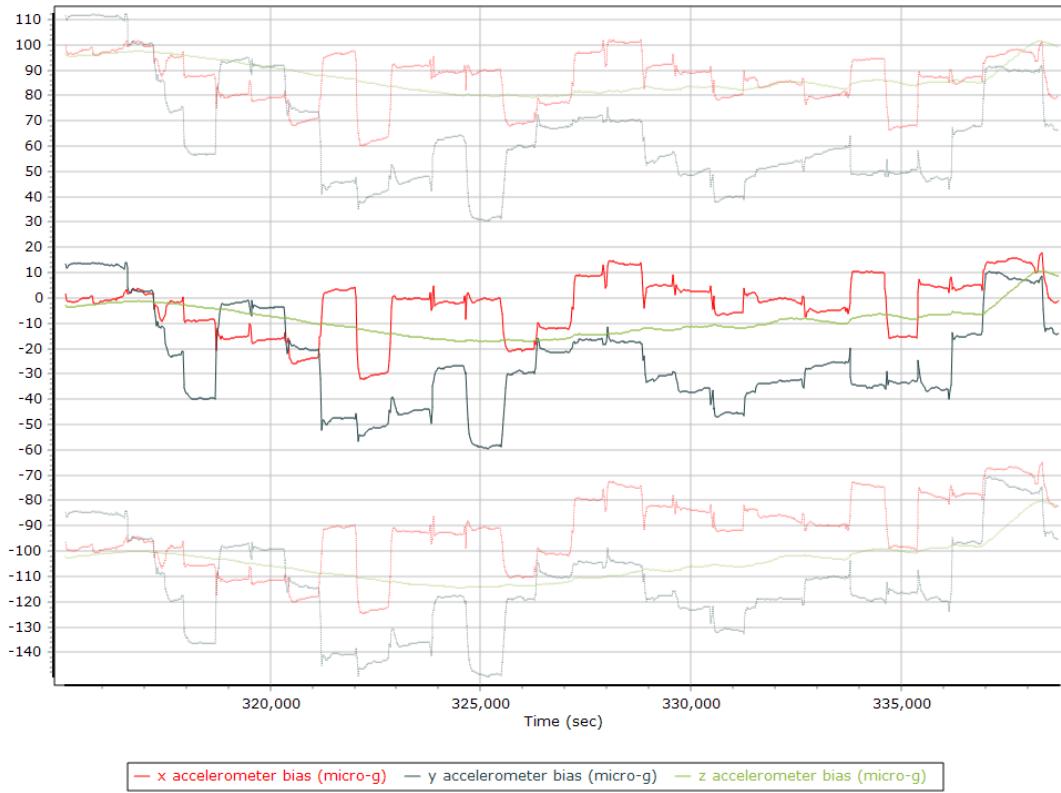
Reference-Primary GNSS Lever Arm Figure of Merit



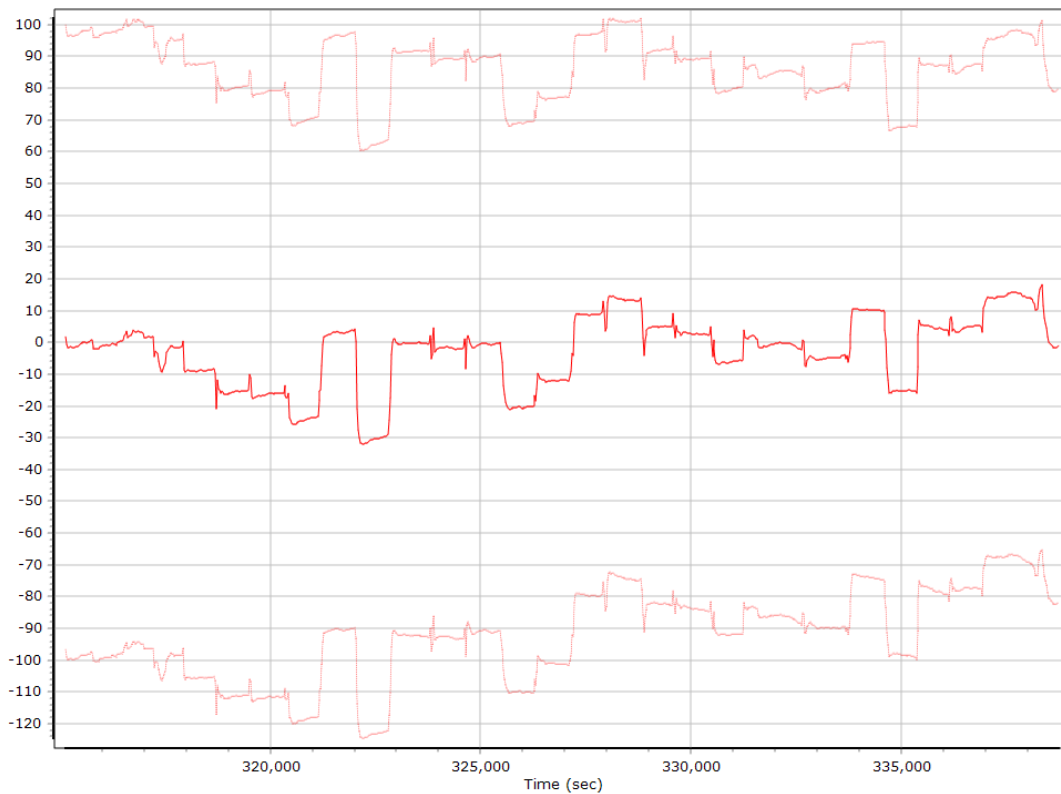
IN-Fusion QC

Forward Processed Estimated Errors, Reference Frame

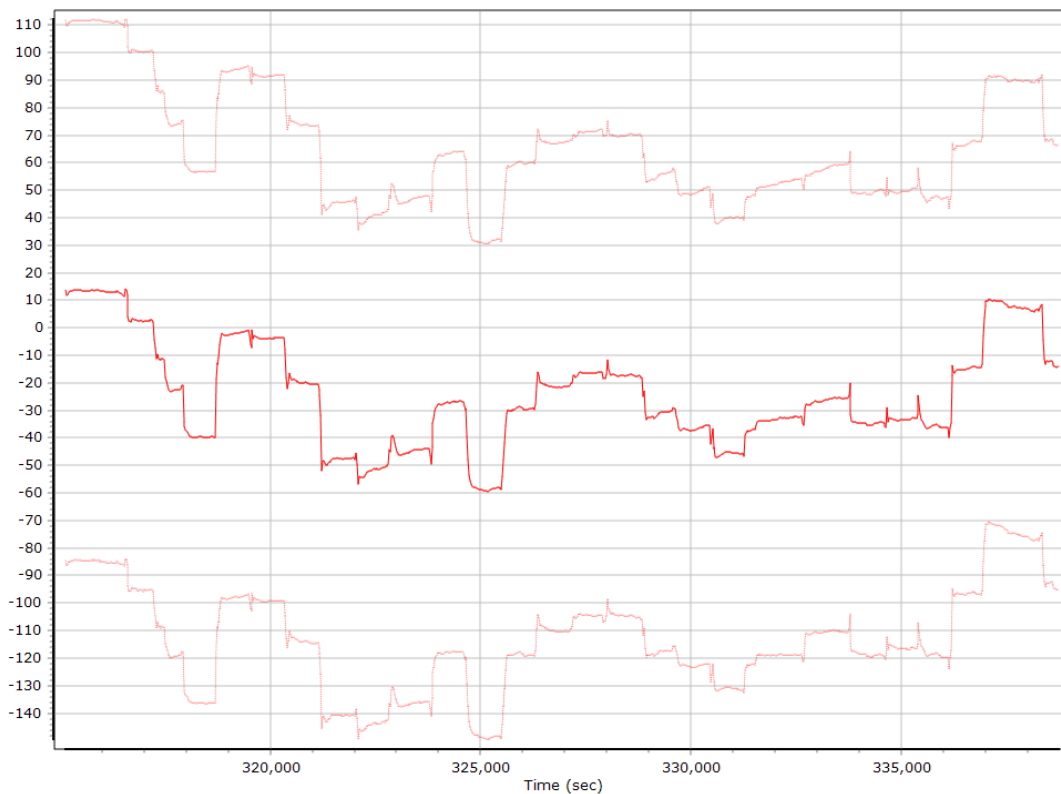
Accelerometer Bias (micro-g)



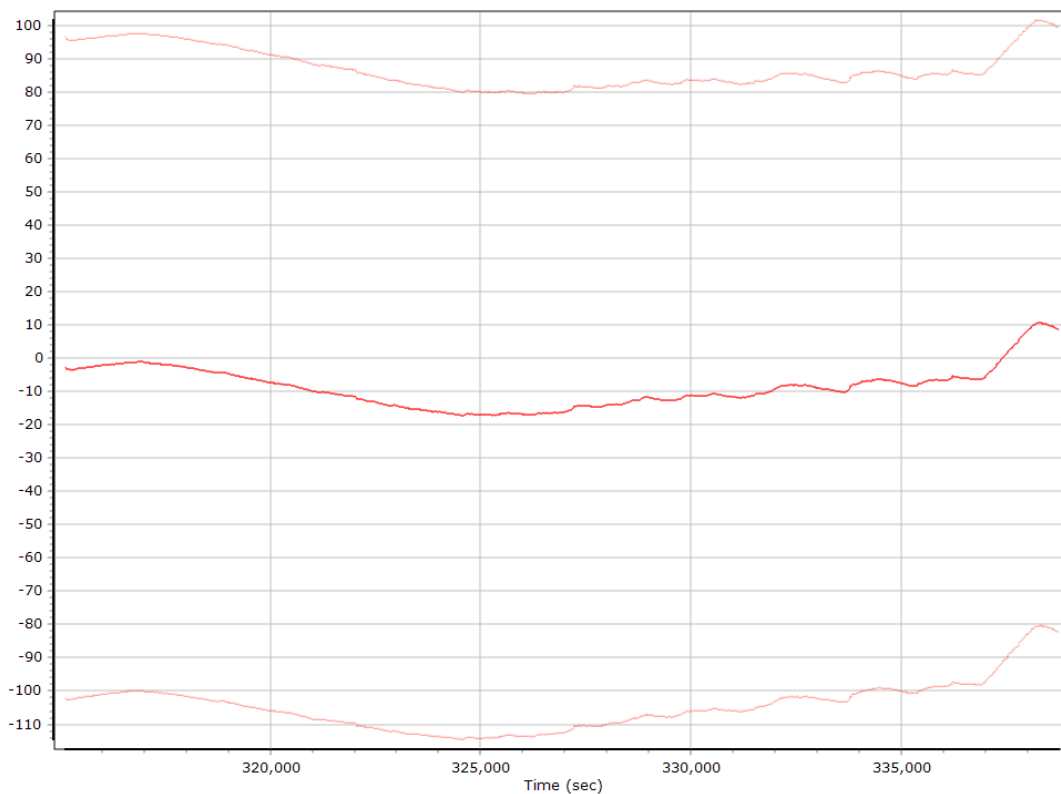
X Accelerometer Bias (micro-g)



Y Accelerometer Bias (micro-g)



Z Accelerometer Bias (micro-g)



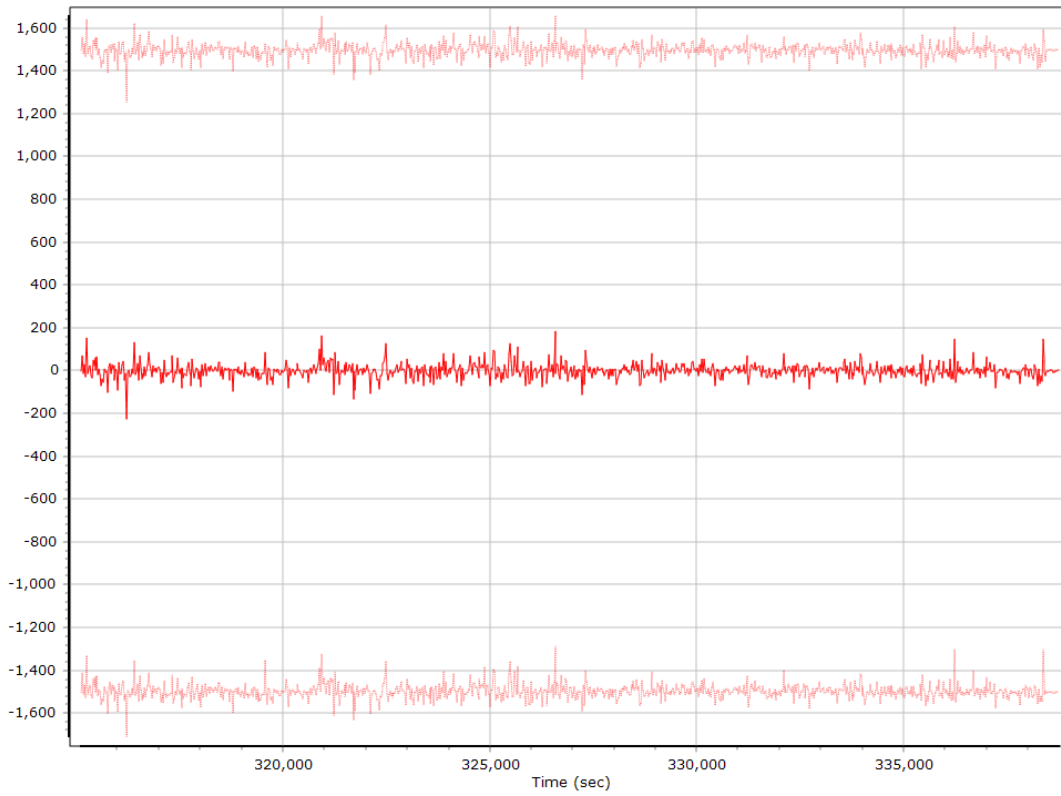
Accelerometer Scale Error (ppm)



X Accelerometer Scale Error (ppm)



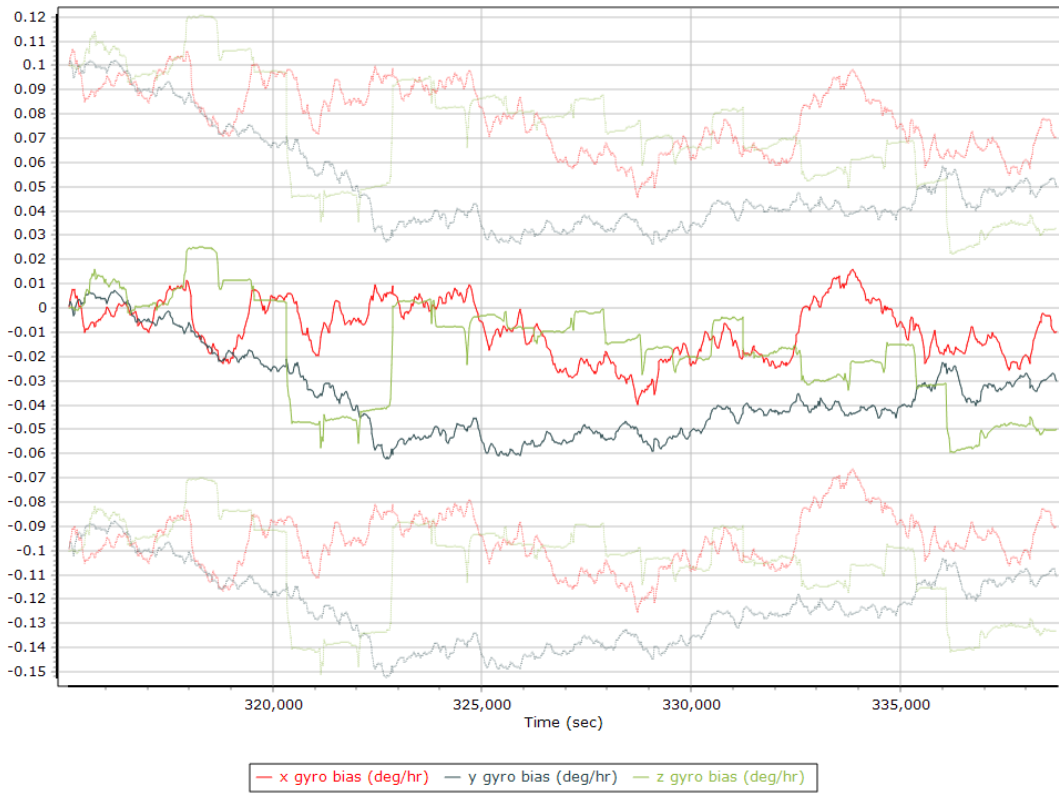
Y Accelerometer Scale Error (ppm)



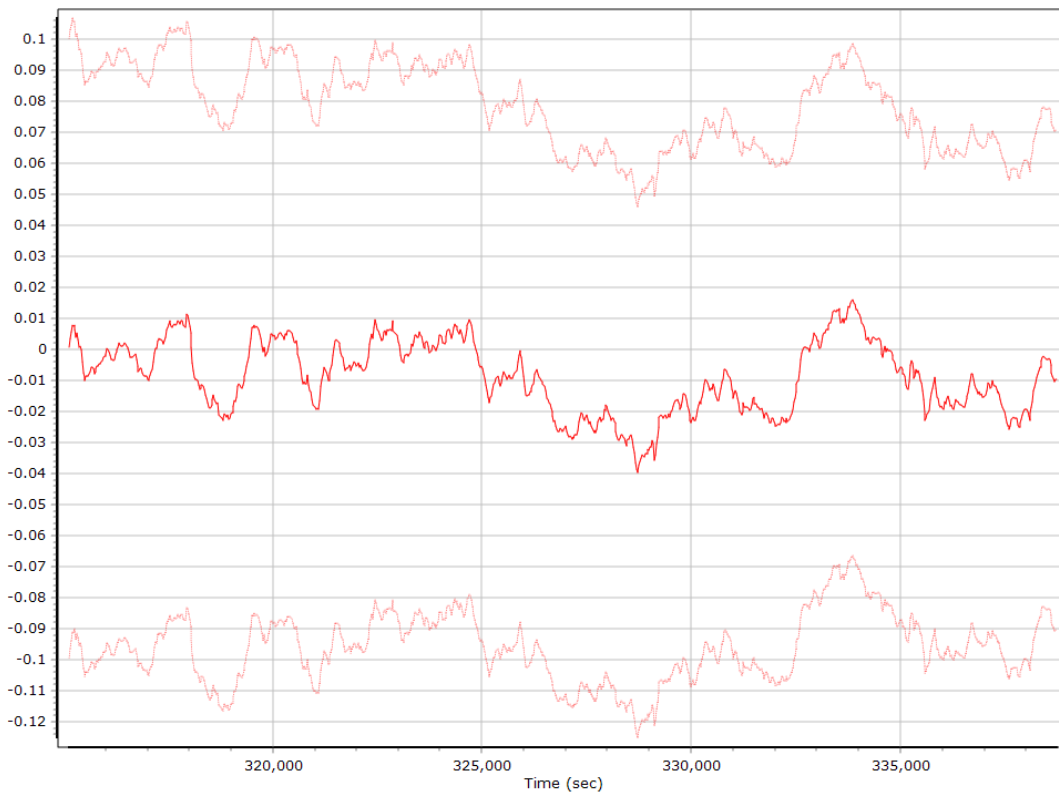
Z Accelerometer Scale Error (ppm)



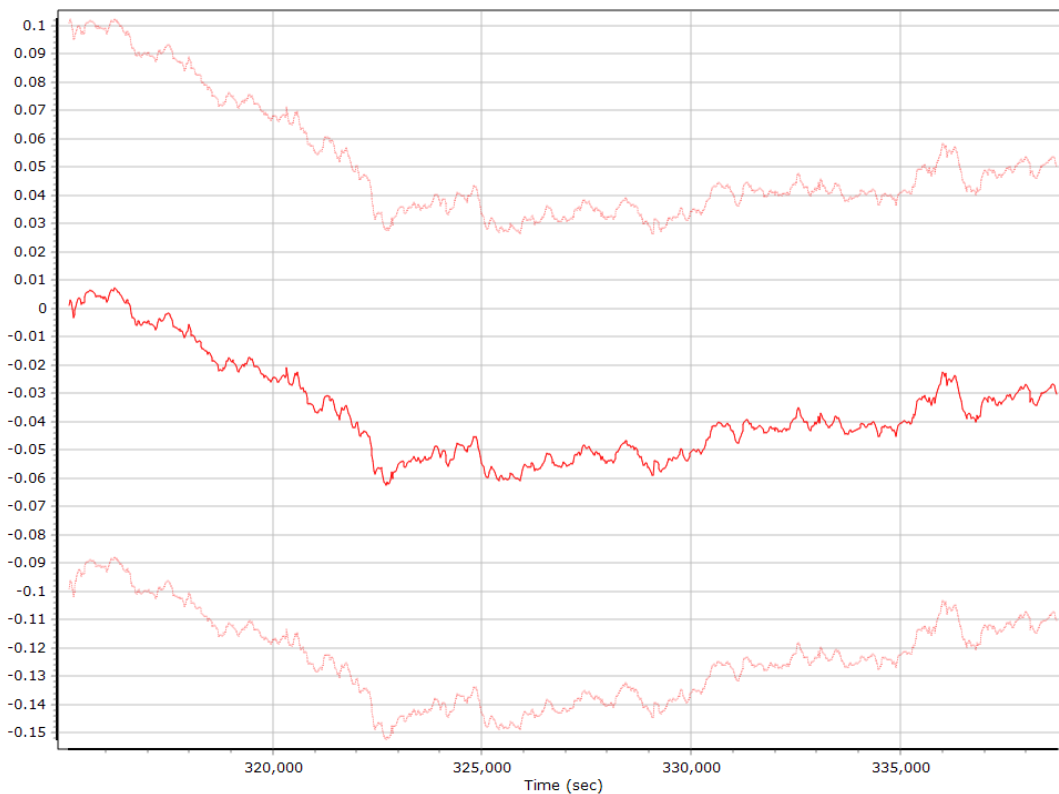
Gyro Bias (deg/h)



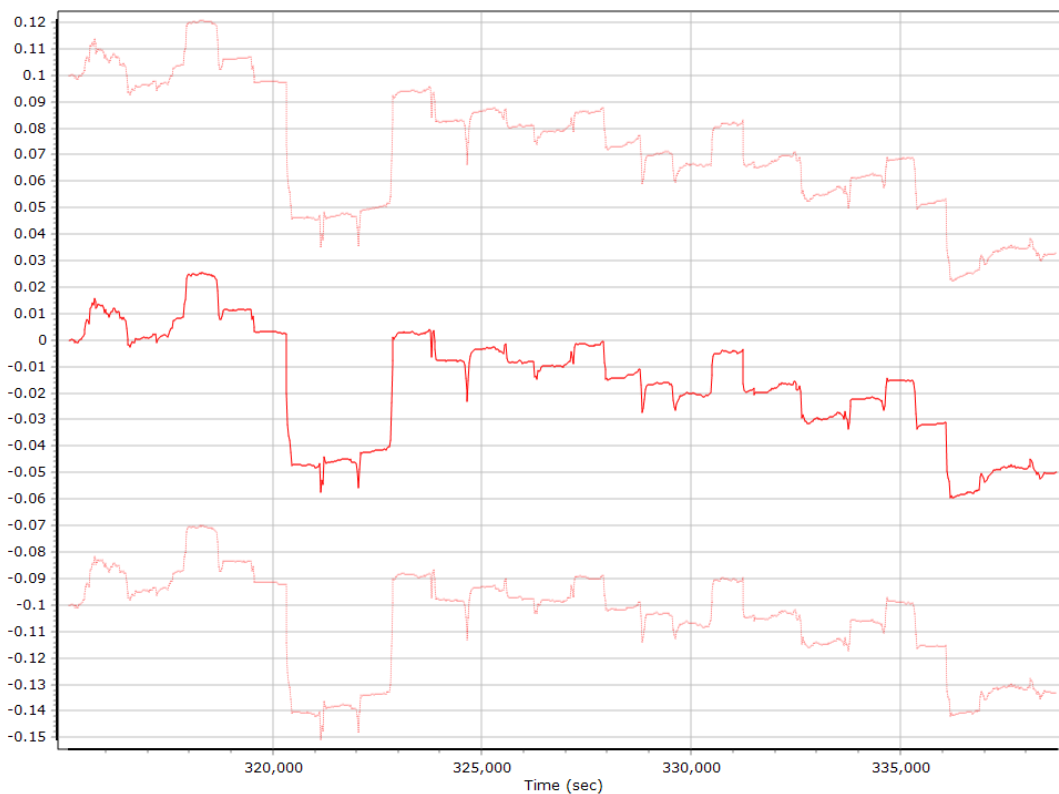
X Gyro Bias (deg/h)



Y Gyro Bias (deg/h)



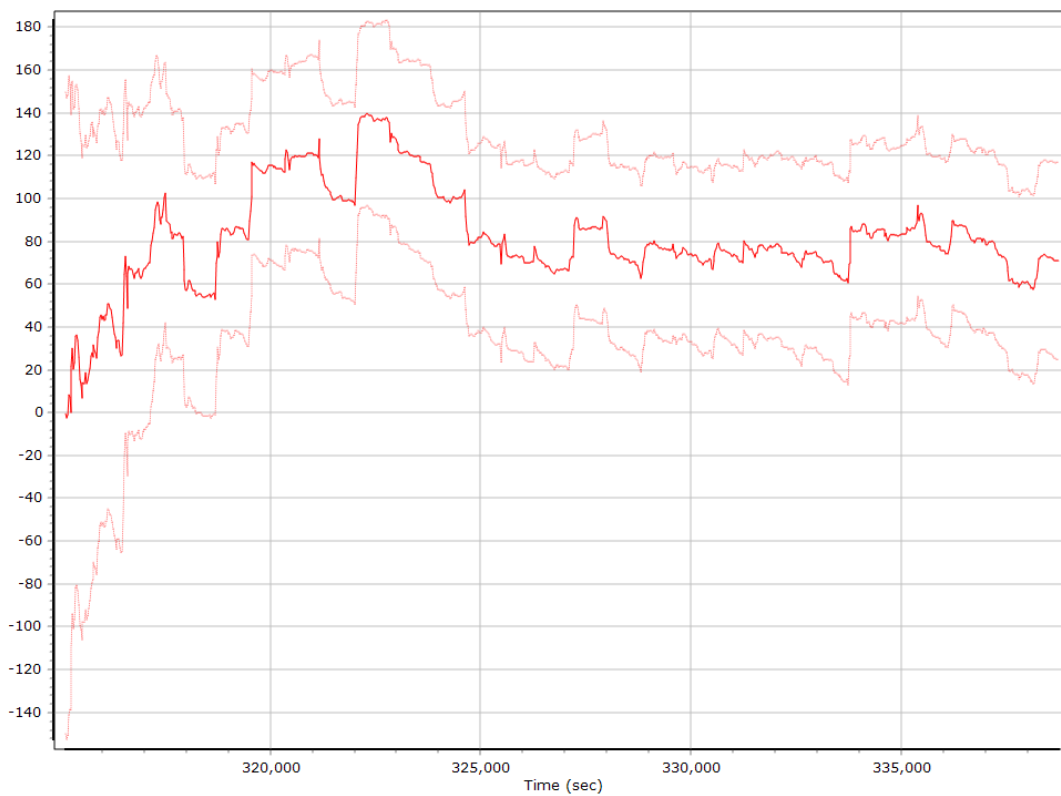
Z Gyro Bias (deg/h)



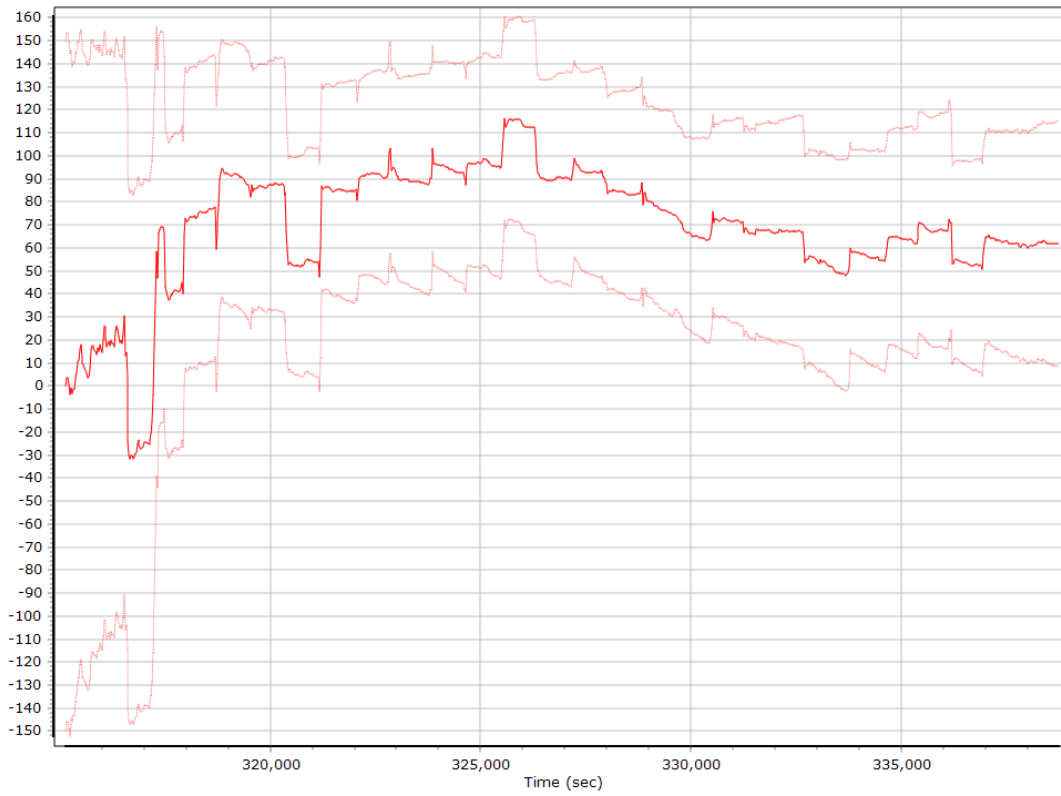
Gyro Scale Error (ppm)



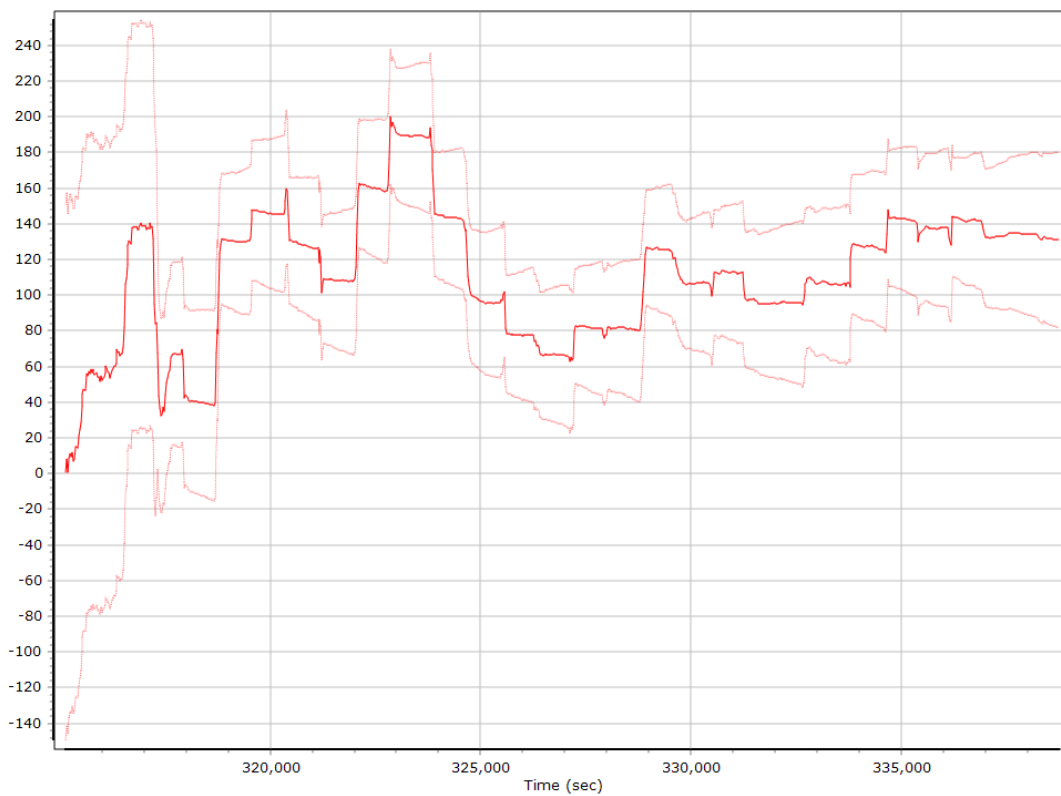
X Gyro Scale Error (ppm)



Y Gyro Scale Error (ppm)

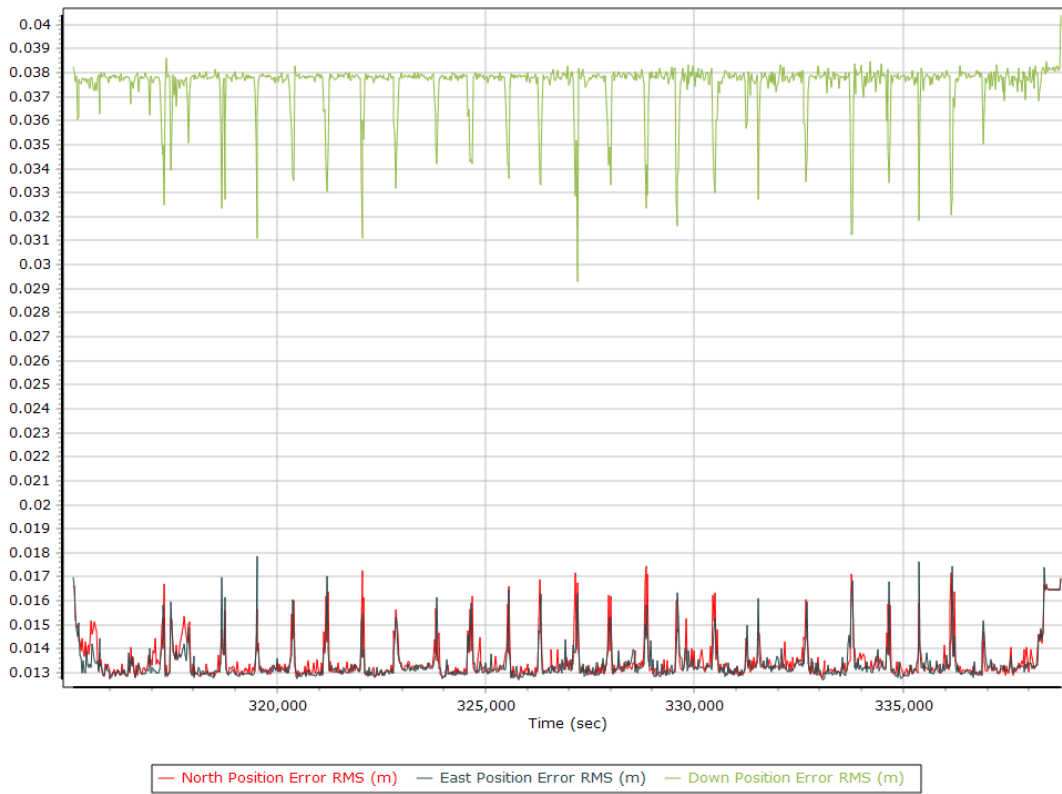


Z Gyro Scale Error (ppm)

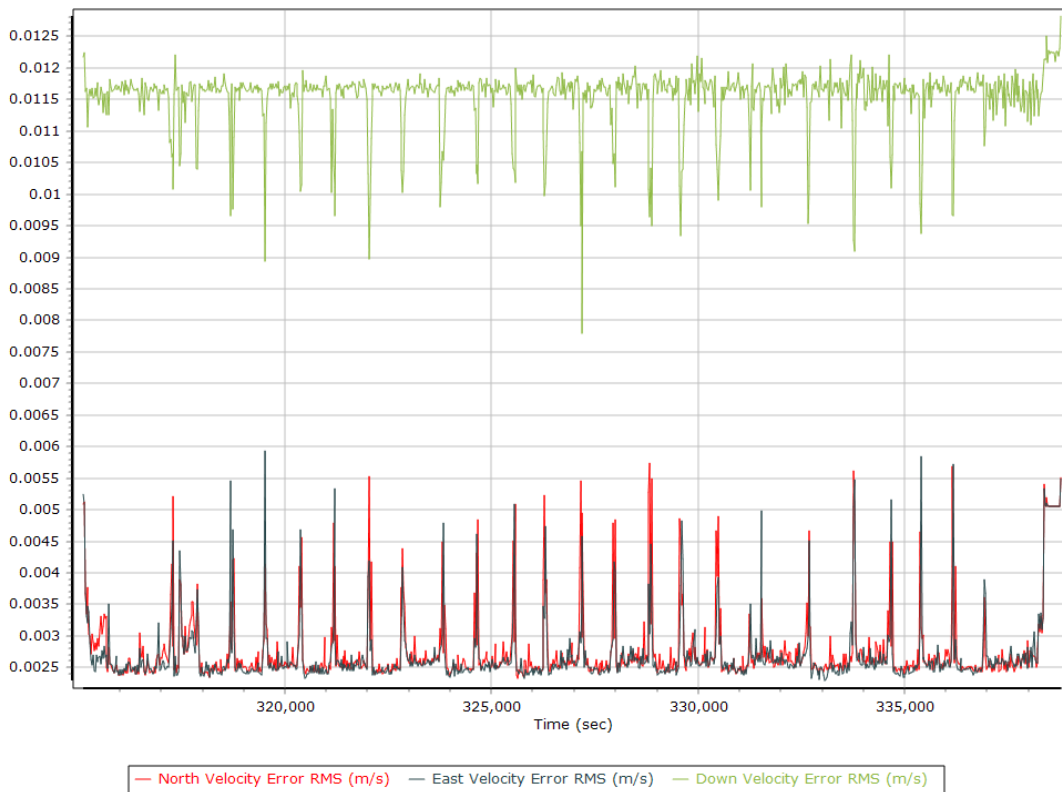


Smoothed Performance Metrics

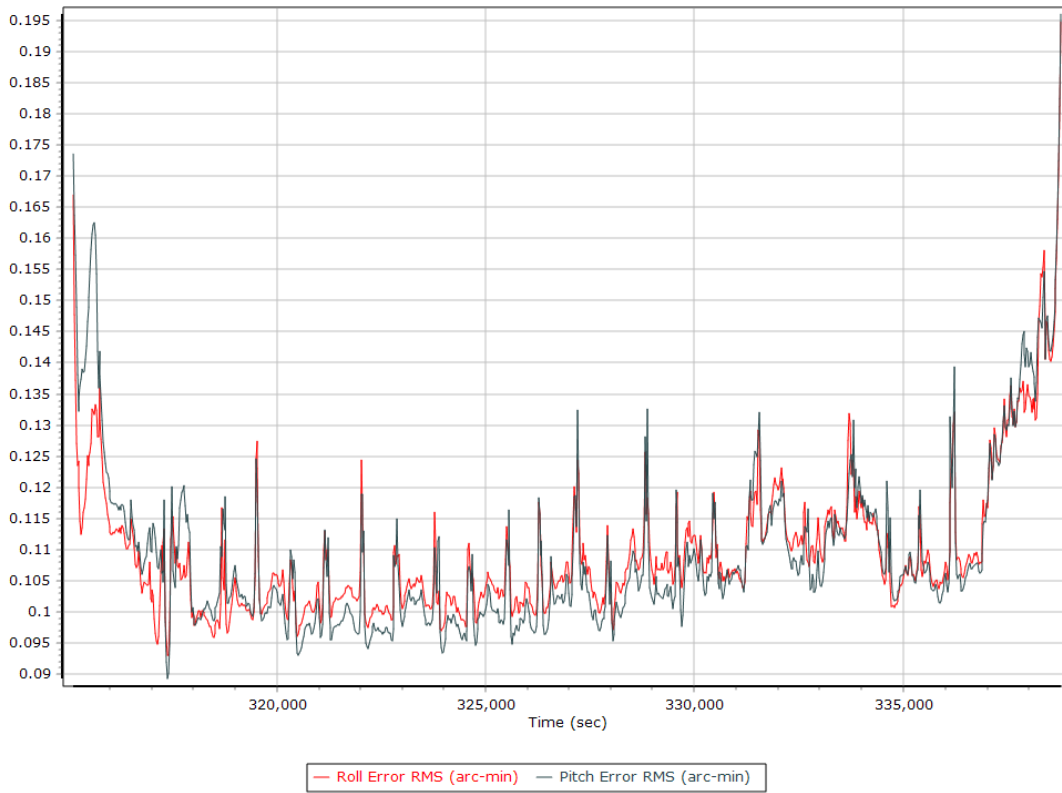
Position Error RMS (m)



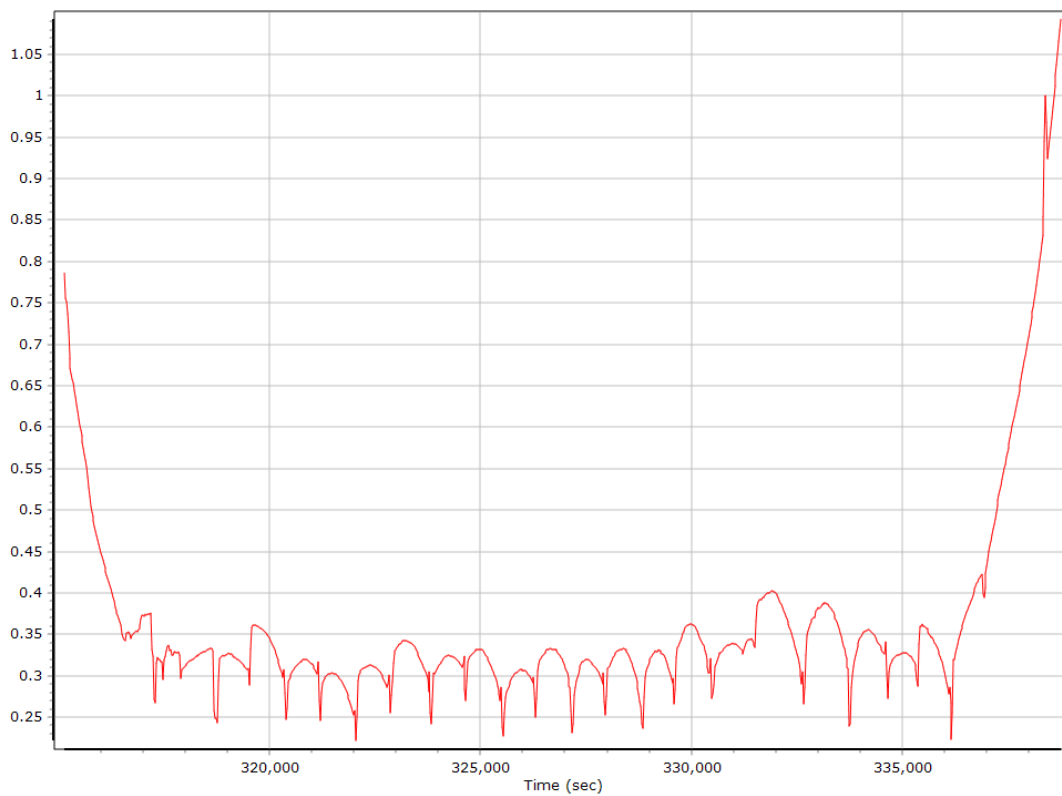
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

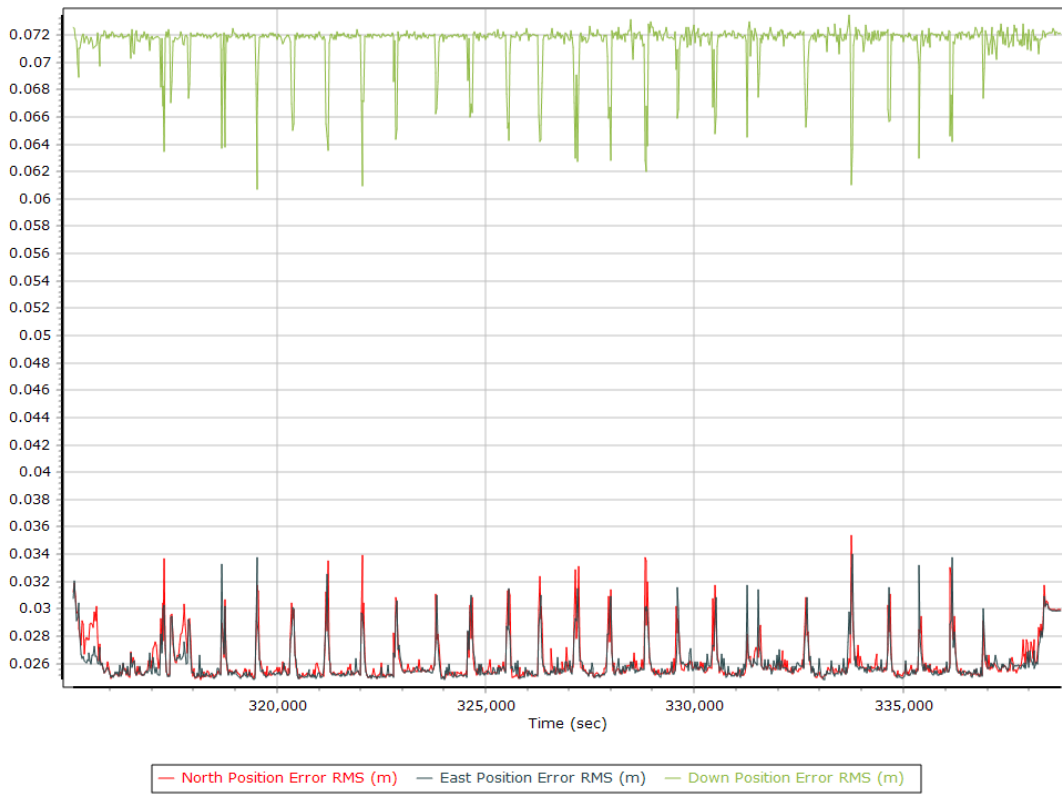


Heading Error RMS (arc-min)

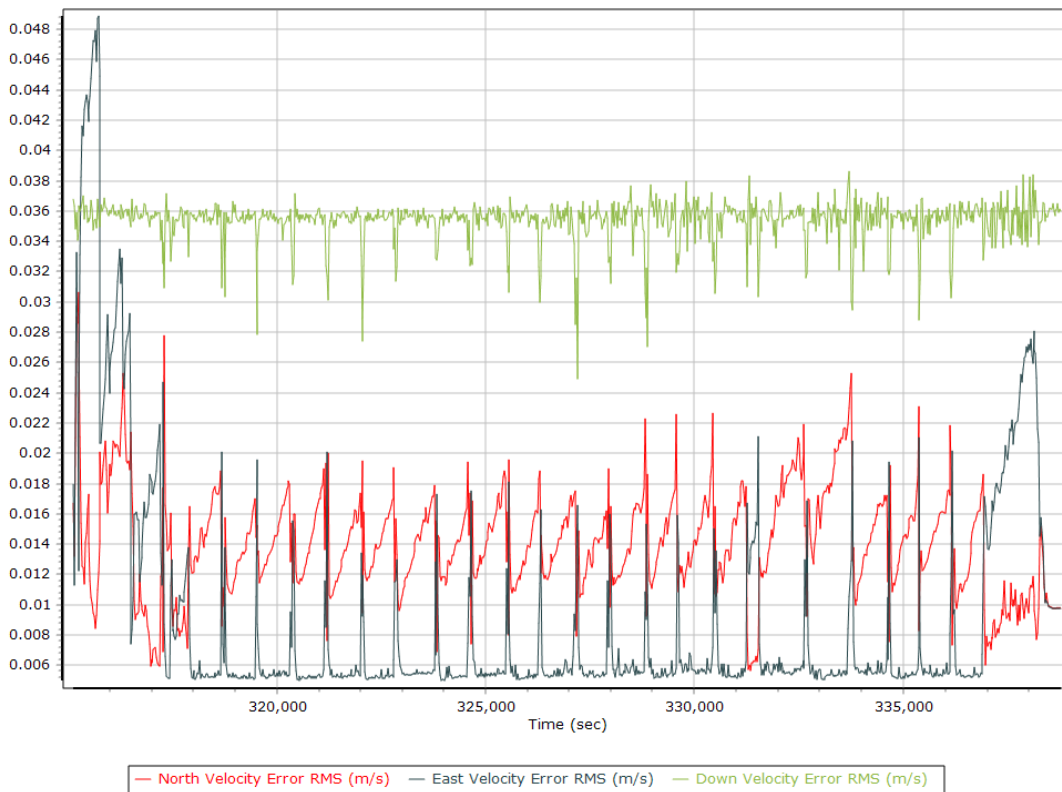


Forward Processed Performance Metrics

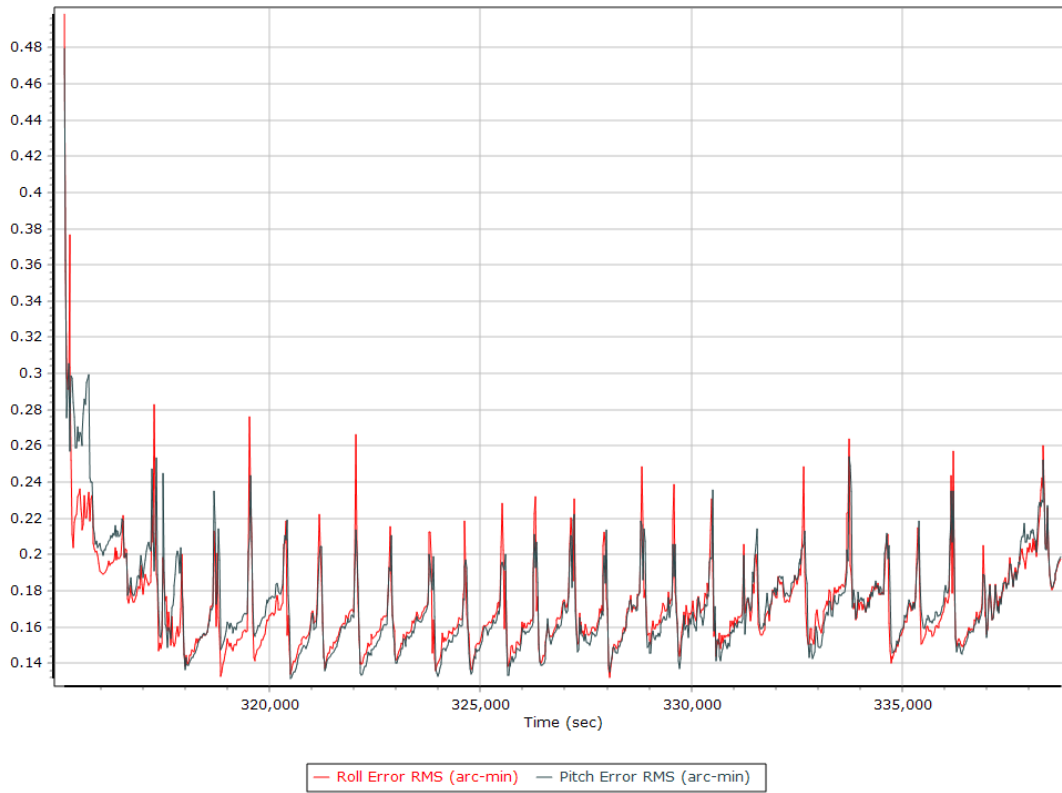
Position Error RMS (m)



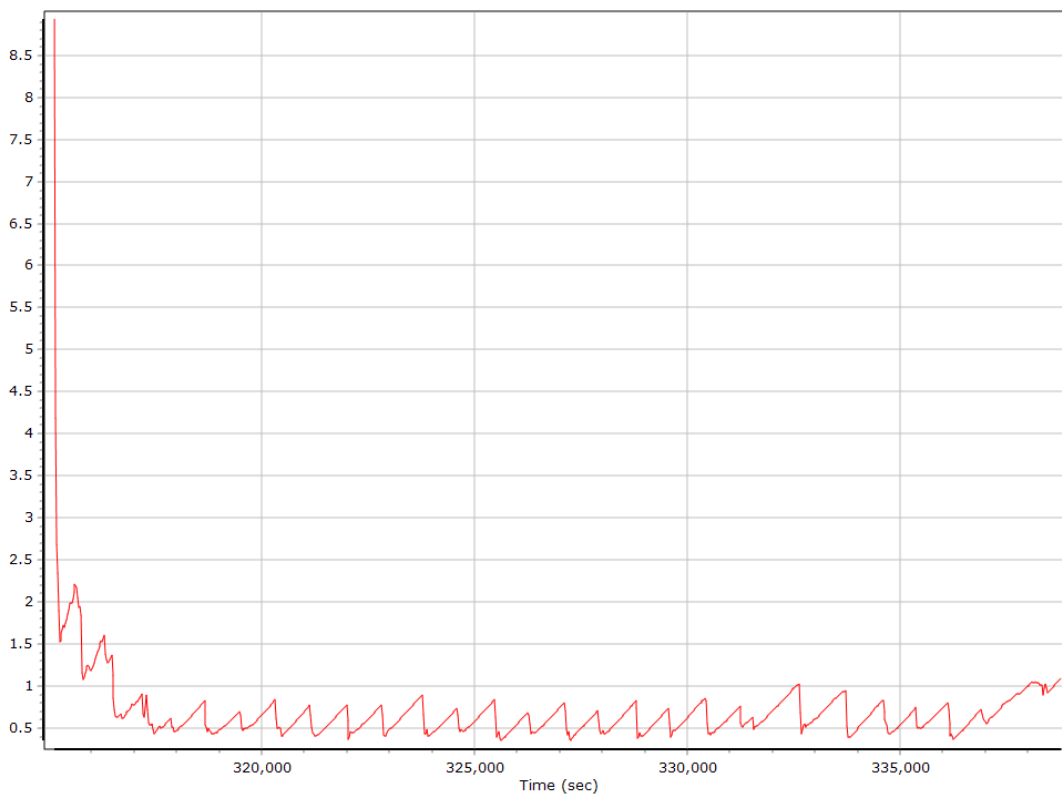
Velocity Error RMS (m/s)



Roll/Pitch Error RMS (arc-min)

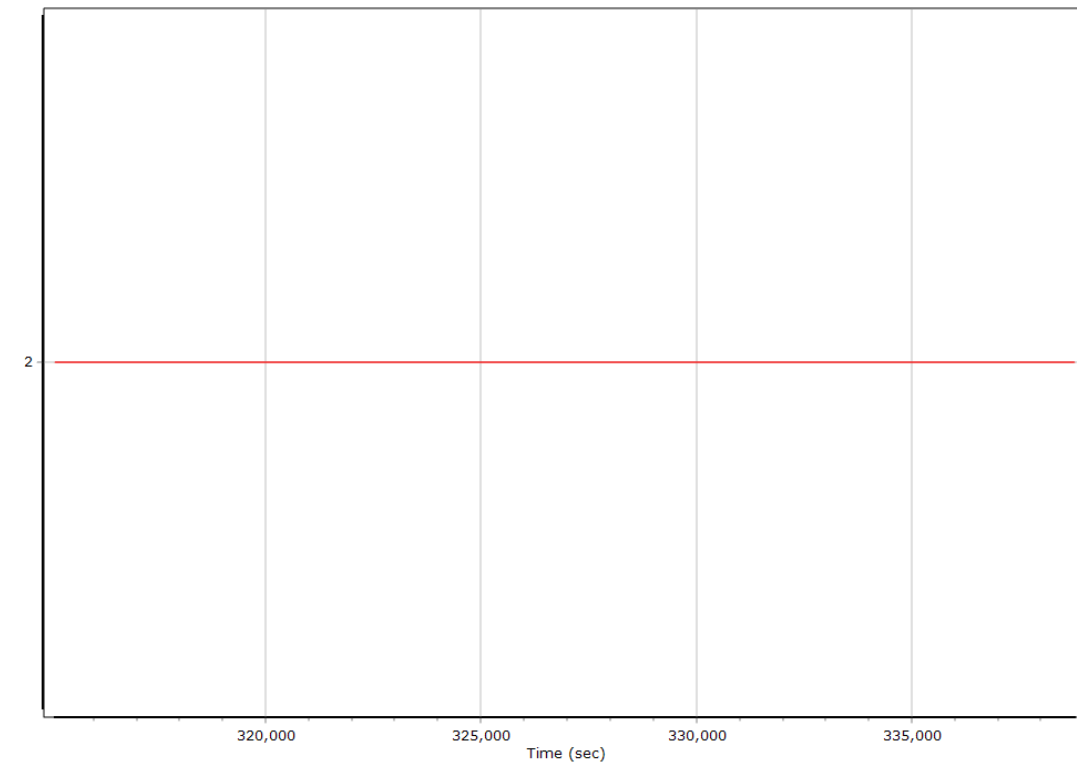


Heading Error RMS (arc-min)



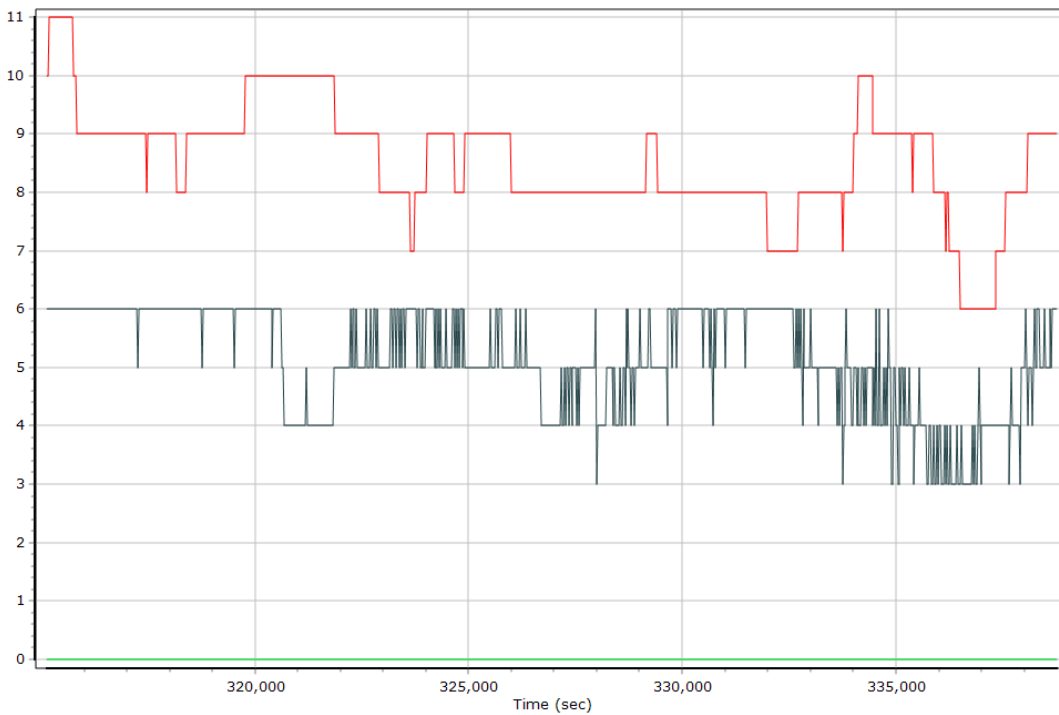
Forward Processed Solution Status

Processing Mode



0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = C/A, 7 = GNSS Nav, 8 = DR

Number of Satellites



— Number of GPS Satellites — Number of GLONASS Satellites — Number of QZSS Satellites
 — Number of BEIDOU Satellites — Number of GALILEO Satellites

Baseline Length

