

Lidar Mapping Report

Acquisition, Processing, and Delivery of Airborne Lidar Elevation Data and Orthoimagery for NE_NRCS OrthoLidar-2017_D18 Project

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Glossary of Terms

Term	Description
AGL	Above Ground Level
AGPS	Airborne Global Positioning System
ANPD	Aggregate Nominal Pulse Density
ANPS	Aggregate Nominal Pulse Spacing
ASPRS	American Society of Photogrammetry and Remote Sensing
AT	Aerial Triangulation
CD	Compact Disk
CMS	Certified Mapping Scientist
CORS	Continuous Operating Reference Station
CP	Certified Photogrammetrist
CVA	Consolidated Vertical Accuracy
DACS™	Digital Airborne Camera System
DEM	Digital Elevation Model
DFIRM	Digital Flood Insurance Rate Maps
DSM	Digital Surface Model
DTM	Digital Terrain Model
DVD	Digital Versatile Disk / Digital Video Disk
DXF	Data Exchange Format / Drawing Interchange
FIRM	Flood Insurance Rate Maps
FEMA	Federal Emergency Management
FGDC	Federal Geographic Data Committee
FVA	Fundamental Vertical Accuracy
FY	Fiscal Year
GIS	Geographic Information System
GISP	Geographic Information System Professional
GNSS	Global Navigation Satellite System
GPS	Global Positioning System
GSD	Ground Sample Distance
HARN	High Accuracy Reference Network
HDD	Hard Drive Disk
HPGN	High Precision Geodetic Network
IMU	Inertial Measurement Unit
INS	Inertial Navigation System
LAS	(or .las) – industry accepted LIDAR data exchange file format
LB	License Business
LS	Land Surveyor
LIDAR	(or Lidar) Light Detection And Ranging
MARS®	Merrick Advanced Remote Sensing
Merrick	Merrick & Company
MSL	Mean Sea Level
NAD	North American Datum
NDEP	National Digital Elevation Program
NGP	National Geospatial Program
NGS	National Geodetic Survey
NMAS	National Map Accuracy Standards
No.	Number
NPS	Nominal Point Spacing

NSRS	National Spatial Reference System
NSSDA	National Standard for Spatial Data
NVA	Non-vegetated Vertical Accuracy
OPUS	Online Positioning User Service
PDOP	Positional Dilution Of Precision
PLS	Professional Land Surveyor
PLSS	Public Land Survey System
ppsm	Points (or pulses) per square meter
PSM	Professional Surveyor and Mapper
QL1	Quality Level One
QL2	Quality Level Two
RLS	Registered Land Surveyor
RGB	Red, Green, Blue (i.e., three-band image)
RGBNIR	Red, Green, Blue, Near Infra-Red (i.e., four-band image)
RMSE	Root Mean Square Error
SBET	Smoothed Best Estimated Trajectory
SHA	Secured Hash Standard
SPCS	State Plane Coordinate System
SVA	Supplemental Vertical Accuracy
TIN	Triangular Irregular Network
USGS	United State Geological Survey
VVA	Vegetated Vertical Accuracy
XML	eXtensible Markup Language

Project Summary

Merrick-Surdex Joint Venture, LLP (“Merrick-Surdex JV”) was awarded the NE_NRCS_OrthoLiDAR_2017_D18 project to provide high resolution elevation data derived from QL2 lidar over 11,110 square miles to include the Nebraska counties of Lincoln, Hayes, Frontier, Gosper, Red Willow, Furnas, Saunders, Butler, Platte, Colfax, Dodge, Fillmore, Saline, York, Seward, Otoe, Johnson, Nemaha, Pawnee and Richardson. Leaf-off, 4-band color and color near infrared imagery was captured at 60cm GSD, full DOQQ coverage or approximately 8,923 square miles for the Nebraska counties of Saunders, Butler, Platte, Colfax, Dodge, Fillmore, Saline, York, Seward, Otoe, Johnson, Nemaha, Pawnee and Richardson. This lidar data and leaf-off imagery will assist NE-NRCS in conservation planning, design, research, delivery, floodplain mapping, dam safety assessments, and hydrological modeling.

The lidar mapping requirements and deliverables meet Quality Level Two (QL2) standards for final deliverables as outlined in the USGS-NGP Lidar Base Specifications, Techniques and Methods 11–B4, Version **1.2**, November 2014 (TM11-B4). QL2 lidar specifications suggest a pulse density of greater than or equal to two pulses per square meter (≥ 2 ppsm) Aggregate Nominal Pulse Density (ANPD), and pulse spacing of less than or equal to seventy-one centimeters (≤ 0.71 m) Aggregate Nominal Pulse Spacing (ANPS). The orthoimagery horizontal accuracy meets or exceeds ≤ 4.0 m at the 95% confidence level (2.31m RMSEr or 1.64m Horizontal Accuracy Class [RMSEx and RMSEy]).

The vertical accuracy requirements of the lidar data meets or exceeds the following:

Vertical accuracy (absolute for the Non-Vegetated Vertical Accuracy [NVA])

- ≤ 10 cm RMSEz
- ≤ 19.6 cm at the 95% confidence level (AccuracyZ)
- Vegetated Vertical Accuracy (VVA) ≤ 29.4 cm at the 95% percentile

Relative accuracy

- ≤ 6 cm Smooth surface repeatability
- ≤ 8 cm RMSDz
- ± 16 cm maximum difference

This data set was produced to meet ASPRS “Positional Accuracy Standards for Digital Geospatial Data” (2014) for a 17.5 cm RMSEx / RMSEy Horizontal Accuracy Class which equates to Positional Horizontal Accuracy = +/- 42.8 cm at a 95% confidence level.

Project Spatial Reference

- Horizontal Datum – North American Datum of 1983 (NAD 83)
- Epoch – National Adjustment of 2011 (NA2011) (epoch 2010.00)
- Vertical Datum – North American Vertical Datum of 1988 (NAVD 88)
- Geoid – GEOID 12B
- Projection – UTM Zones 14N and 15N
- Units - Meters

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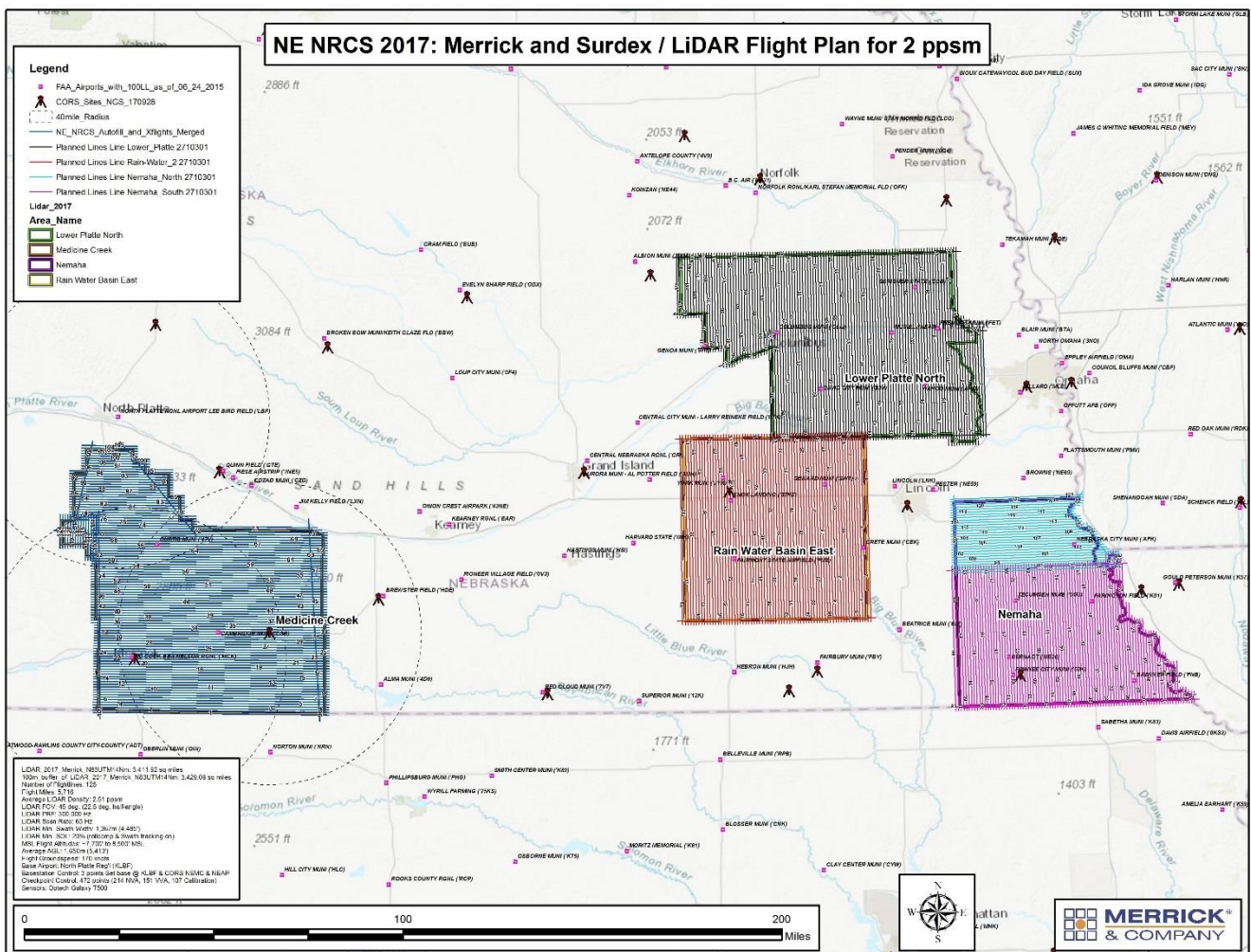
Project Report

The contents of this report summarize the methods used to calibrate and classify the lidar data as well as the results of these methods for the project NE_NRCS_OrthoLiDAR_2017_D18.

Lidar Flight Information

The acquisition area for the NE_NRCS_OrthoLiDAR_2017_D18 project is delineated by the extent of the client-approved Esri shapefiles (*Lidar_2017.shp*) and covers 11,110 square miles. Merrick-Surdex JV acquired the lidar point cloud utilizing an Optech Galaxy lidar sensors. The Galaxy is a high performance 550 kHz lidar sensor capable of collecting large areas efficiently.

Merrick-Surdex JV planned an acquisition area of approximately 11,110 square miles, to include a proper flight line orientation and numbers for accurate sensor calibration. See below illustration of the proposed lidar flight plan.



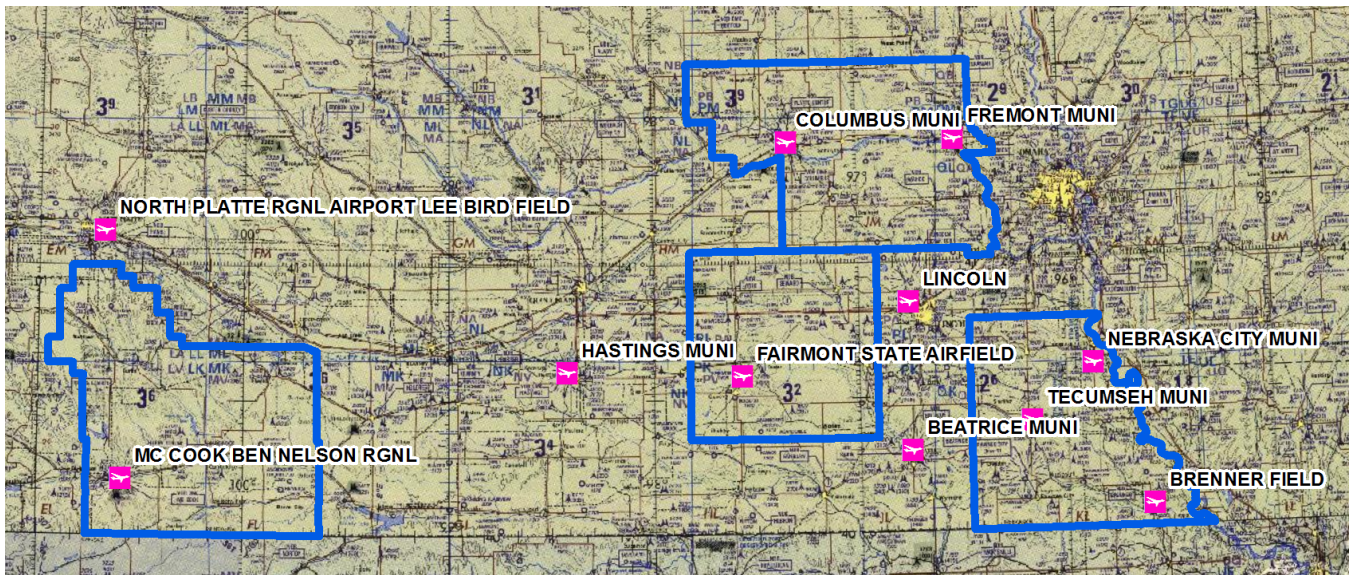
Aerial Mission(s)

The lidar acquisition was collected using fixed wing aircraft and Optech Galaxy lidar sensors. Data collection for the project was accomplished between March 1, 2018 and May 7, 2018 using a variety of airports. Each mission represents a lift of the aircraft and system from the ground, collects data, and lands again. Multiple lifts within a day are represented by Mission A, B, C, and D. The table below relates each mission to the date collected, the sensor and serial number used, and the average MSL in meters.

Mission(s)	Date	Sensor S/N	Actual Avg. MSL (m)
180301_A	March 1, 2018	5060382	2275
180302_A	March 2, 2018	5060382	2300
180303_A	March 3, 2018	5060382	2300
180308_A	March 8, 2018	5060382	1918
180313_A	March 13, 2018	5060407	1919
180314_A	March 14, 2018	5060407	2349
180315_A	March 15, 2018	5060407	2391
180316_A	March 16, 2018	5060407	2151
180318_A	March 18, 2018	5060407	2167
180327_A	March 27, 2018	5060386	2550
180328_A	March 28, 2018	5060386	2500
180328_B	March 28, 2018	5060386	2580
180330_A	March 30, 2018	5060386	2470
180330_B	March 30, 2018	5060386	2460
180403_A	April 3, 2018	5060386	2456
180404_A	April 4, 2018	5060386	2432
180404_B	April 4, 2018	5060386	2420
180404_C	April 4, 2018	5060386	2400
180405_A	April 5, 2018	5060386	2380
180405_B	April 5, 2018	5060386	2394
180417_A	April 17, 2018	5060386	2402
180418_A	April 18, 2018	5060386	2420
180418_B	April 18, 2018	5060386	2400
180418_C	April 19, 2018	5060386	2458
180419_A	April 19, 2018	5060386	2450
180420_A	April 20, 2018	5060406	2333
180422_A	April 22, 2018	5060406	2403
180423_A	April 23, 2018	5060406	2341
180423_A	April 23, 2018	5060407	2334
180424_A	April 24, 2018	5060406	2424
180424_A	April 24, 2018	5060407	2479
180426_A	April 26, 2018	5060407	2512
180426_A	April 26, 2018	5060406	2439

180427_A	April 27, 2018	5060382	2509
180427_A	April 27, 2018	5060406	2459
180427_A	April 27, 2018	5060407	2483
180428_A	April 28, 2018	5060406	2334
180428_A	April 28, 2018	5060407	2485
180428_A	April 28, 2018	5060382	2509
180429_A	April 29, 2018	5060406	2382
180504_A	May 4, 2018	5060407	2460
180504_A	May 4, 2018	5060406	2452
180505_A	May 5, 2018	5060406	2421
180505_A	May 5, 2018	5060407	2526
180505_A	May 5, 2018	5060382	2473
180506_A	May 6, 2018	5060406	2427
180506_A	May 6, 2018	5060382	2471
180506_A	May 6, 2018	5060407	2495
180507_A	May 7, 2018	5060406	2462
180507_A	May 7, 2018	5060407	2447

Airports Used



GNSS / IMU Data

A five-minute INS initialization is conducted on the ground, with the aircraft engines running, prior to flight, to establish fine-alignment of the INS. GPS ambiguities are resolved by flying within ten kilometers of the base stations. During the data collection, the operator recorded information on log sheets which includes weather conditions, lidar operation parameters, and flight line statistics. Near the end of the mission, GPS ambiguities were again resolved by flying within ten kilometers of the base stations to aid in post-processing. Data is sent

back to the main office for preliminary processing to check overall quality of GPS / INS data and to ensure sufficient overlap between flight lines. Any problematic data may be re-flown immediately as required.

The airborne GPS data was post-processed using Applanix POSPac Mobile Mapping Suite version 8.x. A fixed-bias carrier phase solution was computed in both the forward and reverse chronological directions. Whenever practical, lidar acquisition was limited to periods when the PDOP was less than 4.0. PDOP indicates satellite geometry relating to position. Generally, PDOP's of 4.0 or less result in a good quality solution, however PDOP's between 4.0 and 5.0 can still yield good results most of the time. PDOP's over 6.0 are of questionable results and PDOP's of over 7.0 usually result in a poor solution. Usually as the number of satellites increase the PDOP decreases. Other quality control checks used for the GPS include analyzing the combined separation of the forward and reverse GPS processing from one base station and the results of the combined separation when processed from two different base stations. An analysis of the number of satellites, present during the flight and data collection times, is also performed.

The GPS trajectory was combined with the raw IMU data and post-processed using POSPac Mobile Mapping Suite version 8.x. The SBET and refined attitude data are then utilized in the LMS Post Processor to compute the laser point-positions – the trajectory is combined with the attitude data and laser range measurements to produce the 3-dimensional coordinates of the mass points. Up to four return values are produced within the Optech LMS processor software for each pulse which ensures the greatest chance of ground returns in a heavily forested area.

GPS Controls

Ground GNSS Base Stations were set up to control the lidar airborne flight lines. In addition, CORS are at times used to further enhance the airborne solution. The ground GNSS Base Stations coordinates were obtained from NGS OPUS solutions. CORS coordinates were obtained from NGS datasheets.

Lidar Calibration – see appendix 1 for a more detailed workflow description

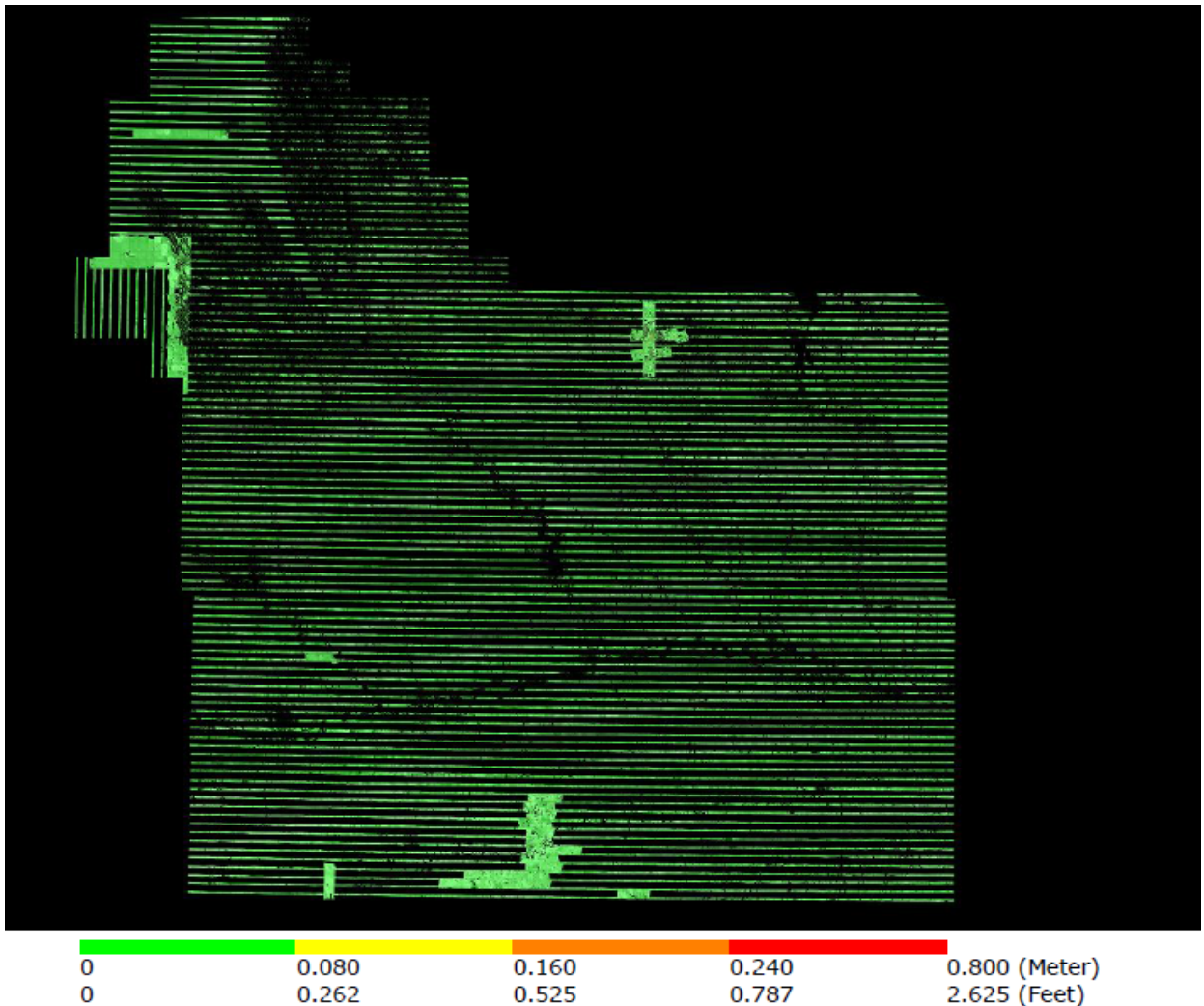
Merrick-Surdex JV takes great care to ensure all lidar acquisition missions are carried out in a manner conducive to post-processing an accurate data set. This begins in the flight-planning stage with attention to GPS baseline distances and GPS satellite constellation geometry and outages. Proper AGPS surveying techniques are always followed including pre- and post-mission static initializations. In-air IMU alignments (figure-eights) are performed both before and after on-site collection to ensure proper calibration of the IMU accelerometers and gyros.

A minimum of one cross-flight is planned throughout the project area across all flightlines and over roadways where possible. The cross-flight provides a common control surface used to remove any vertical discrepancies in the lidar data between flightlines. The cross-flight is critical to ensure flightline ties across the project area. The areas of overlap between flightlines are used to boresight (calibrate) the lidar point cloud to achieve proper flightline to flightline alignment in all three axes. This includes adjustment of both IMU and scanner-related variables such as roll, pitch, heading, timing interval (range), and torsion. Each lidar mission flown is accompanied by a hands-on boresight in the office.

After boresighting is complete a detailed statistical report is generated to check relative and absolute accuracies before filtering of lidar begins.

Relative Accuracy – flight line to flight line

The project representative flight line separation raster example (below) depicts the vertical separation of flight lines by thematically coloring the separation magnitude on a color ramp based on relative distance.



Survey – Lidar / Imagery Control

CompassData, Inc. surveyors established lidar control points, lidar checkpoints and photo identifiable points spatially distributed across the project AOI as the method to validate absolute vertical accuracy of the lidar and radial horizontal accuracy of the imagery.

See appendix 3 – Survey Report.

Unfiltered Lidar Control Point Report

The following tables illustrate the results of the lidar data compared to the lidar control points post-calibration. The listing is sorted by the Z Error column showing, in ascending order, the vertical difference between the lidar points and the 124 surveyed ground points (110 control points within UTM14 / 14 control points within UTM15) used for lidar calibration.

UTM 14 Control

Project Data Unit: Meter
 Vertical Accuracy Class tested: 10.0-cm
 Elevation Calculation Method: Interpolated from TIN
 LiDAR Classifications Included: 2/0 Ground (All)/0W

Check Points in Report: 110
 Check Points with LiDAR Coverage: 110
 Check Points (NVA): 110
 Check Points (VVA): 0
 Average Vertical Error Reported: -0.002 Meter
 Maximum (highest) Vertical Error Reported: 0.081 Meter
 Median Vertical Error Reported: 0.002 Meter
 Minimum (lowest) Vertical Error Reported: -0.202 Meter
 Standard deviation of Vertical Error: 0.039 Meter
 Skewness of Vertical Error: -1.730
 Kurtosis of Vertical Error: 6.410
 Non-vegetated Vertical Accuracy (NVA) RMSE(z): 3.871cm PASS
 Non-vegetated Vertical Accuracy (NVA) at the 95% Confidence Level +/-: 7.587cm PASS
 FGDC/NSSDA Vertical Accuracy at the 95% Confidence Level +/-: 7.587cm
 Non-vegetated Vertical Accuracy (NVA) RMSE(z) (DEM): 4.193cm PASS
 Non-vegetated Vertical Accuracy (NVA) at the 95% Confidence Level +/- (DEM): 8.219cm PASS

This data set was tested to meet ASPRS Positional Accuracy Standard for Digital Geospatial Data (2014) for a 10.0-cm RMSEz Vertical Accuracy Class. Actual NVA accuracy was found to be RMSEz = 3.871cm, equating to +/- 7.587cm at the 95% confidence level.

Check Point Id	Check Point X	Check Point Y	Coverage	Check Point Z	Z from LiDAR	Z Error
CAL3005	667416.801	4561114.577	Yes	509.642	509.649	0.007
CAL3008	656594.838	4569821.799	Yes	496.807	496.788	-0.019
CAL3008_alt	656664.505	4569600.391	Yes	496.163	496.181	0.018
CAL3029	666340.051	4549967.753	Yes	495.378	495.235	-0.143
CAL3111	642965.786	4562472.168	Yes	483.569	483.566	-0.003
CAL3002	662080.932	4589443.538	Yes	412.212	412.246	0.034
CAL3007	674516.863	4607206.849	Yes	462.557	462.589	0.032
CAL3021	649077.179	4595420.032	Yes	451.028	451.041	0.013
CAL3022	656077.24	4620664.619	Yes	464.769	464.803	0.034
CAL_COLFAX_EXTRA	661773.175	4605319.462	Yes	457.372	457.339	-0.033
CAL3004	685381.923	4593165.005	Yes	387.691	387.62	-0.071
CAL3009	675961.589	4620917.03	Yes	427.078	427.145	0.067
CAL3012	707732.237	4623144.461	Yes	397.157	397.151	-0.006
CAL3015	711868.624	4589352.769	Yes	359.018	359.088	0.07
CAL3019	694412.965	4614849.195	Yes	381.65	381.579	-0.071
CAL3027	711004.609	4601199.272	Yes	366.64	366.659	0.019
CAL_DODGE_EXTRA	691568.236	4601962.038	Yes	410.247	410.265	0.018
CAL3003	619281.234	4615177.049	Yes	525.532	525.52	-0.012
CAL3011	640599.128	4616203.153	Yes	500.515	500.534	0.019
CAL3017	625892.02	4583313.994	Yes	456.783	456.818	0.035
CAL3020	616766.884	4592552.447	Yes	464.531	464.568	0.037
CAL3024	608607.956	4605992.393	Yes	535.067	535.089	0.022
CAL3028	635731.749	4588623.154	Yes	441.899	441.697	-0.202
CAL_extra_platte	627728.172	4620847.869	Yes	506.6	506.629	0.029

CAL3006	718101.445	4568714.486	Yes	356.072	356.076	0.004
CAL3010	697061.77	4548048.91	Yes	380.77	380.752	-0.018
CAL3013	700221.22	4574515.918	Yes	381.2	381.112	-0.088
CAL3014	709818.31	4548392.541	Yes	373.417	373.413	-0.004
CAL3016	716114.571	4555022.368	Yes	350.049	350.04	-0.009
CAL3023	686063.094	4583287.547	Yes	407.894	407.892	-0.002
CAL3025	685121.847	4559104.39	Yes	420.721	420.734	0.013
CAL3108	721186.751	4546793.916	Yes	329.088	329.017	-0.071
CAL_EXTRA_SAU	698593.744	4561103.559	Yes	387.538	387.58	0.042
CAL3034	606065.813	4486732.136	Yes	509.654	509.683	0.029
CAL3036	618909.943	4486894.638	Yes	500.931	500.901	-0.03
CAL3038	631286.863	4500427.906	Yes	489.788	489.81	0.022
CAL3043	608299.548	4474970.732	Yes	502.495	502.518	0.023
CAL3047	602684.937	4498013.685	Yes	510.871	510.897	0.026
CAL3051	620768.091	4469251.703	Yes	486.638	486.653	0.015
CAL3030	659407.143	4501386.554	Yes	452.533	452.524	-0.009
CAL3031	672737.85	4483712.205	Yes	405.394	405.391	-0.003
CAL3040	653205.702	4473009.202	Yes	455.218	455.209	-0.009
CAL3042	676070.544	4473810.558	Yes	394.026	393.999	-0.027
CAL3042_alt	676277.753	4473841.213	Yes	393.179	393.174	-0.005
CAL3046	674675.309	4500835.445	Yes	442.314	442.249	-0.065
CAL3048	644755.545	4501424.085	Yes	474.235	474.246	0.011
CAL3049	641266.292	4475585.445	Yes	489.276	489.289	0.013
CAL3049_alt	641158.85	4475545.866	Yes	489.113	489.14	0.027
CAL3001	663378.608	4541263.909	Yes	475.402	475.433	0.031
CAL3018	638734.138	4545279.45	Yes	494.482	494.563	0.081
CAL3032	663876.835	4515409.457	Yes	450.413	450.422	0.009
CAL3033	669593.297	4534555.984	Yes	480.038	480.08	0.042
CAL3035	644937.607	4515595.32	Yes	445.789	445.758	-0.031
CAL3039	639062.755	4527803.941	Yes	483.643	483.676	0.033
CAL3045	659294.224	4529996.02	Yes	439.366	439.415	0.049
CAL3109	650794.425	4545481.826	Yes	457.685	457.67	-0.015
CAL3110	673978.234	4545941.814	Yes	444.285	444.287	0.002
CAL_extra_sew	674268.027	4534671.783	Yes	449.676	449.678	0.002
CAL3037	618781.515	4524927.766	Yes	487.606	487.629	0.023
CAL3041	634339.585	4542991.279	Yes	492.327	492.31	-0.017
CAL3044	606704.677	4539866.952	Yes	528.472	528.511	0.039
CAL3050	600553.467	4515315.223	Yes	523.819	523.806	-0.013
CAL_extra_york	618095.128	4520039.281	Yes	502.659	502.598	-0.061
CAL3052	360195.02	4479229.163	Yes	862.2	862.213	0.013
CAL3055	407068.083	4472171.017	Yes	725.404	725.355	-0.049
CAL3062	361209.138	4501939.753	Yes	864.135	864.122	-0.013
CAL3068	381723.323	4504789.334	Yes	861.476	861.46	-0.016
CAL3070	387678.987	4479152.406	Yes	785.137	785.108	-0.029
CAL3071	407479.145	4502821.811	Yes	813.436	813.435	-0.001

CAL3074	408797.299	4483742.365	Yes	766.757	766.716	-0.041
CAL3076	376753.914	4500009.425	Yes	815.35	815.365	0.015
CAL3082	395878.986	4488357.913	Yes	784.974	785.001	0.027
CAL3054	417723.323	4462367.604	Yes	669.755	669.747	-0.008
CAL3063	445550.108	4449085.271	Yes	686.967	686.971	0.004
CAL3066	437512.146	4429851.649	Yes	690.814	690.843	0.029
CAL3069	411195.948	4440535.034	Yes	693.349	693.317	-0.032
CAL3077	402974.822	4431553.6	Yes	754.548	754.523	-0.025
CAL3078	433674.84	4462389.587	Yes	686.478	686.489	0.011
CAL3080	423922.947	4437990.42	Yes	715.972	715.951	-0.021
CAL3058	426234.5	4491327.595	Yes	779.069	779.044	-0.025
CAL3072	424804.167	4481592.172	Yes	737.544	737.575	0.031
CAL3073	443971.402	4494334.986	Yes	756.654	756.66	0.006
CAL3084	443808.71	4470116.512	Yes	711.096	711.121	0.025
CAL3075	336066.579	4503706.775	Yes	889.967	889.98	0.013
CAL3059	352400.922	4534859.009	Yes	928.523	928.555	0.032
CAL3061	369990.252	4524831.682	Yes	921.738	921.717	-0.021
CAL3064	355614.223	4509680.507	Yes	873.353	873.332	-0.021
CAL3065	380780.298	4517214.337	Yes	903.708	903.711	0.003
CAL3053	367504.497	4430742.083	Yes	802.952	802.95	-0.002
CAL3056	352265.775	4430578.838	Yes	881.146	881.174	0.028
CAL3057	381715.726	4441742.437	Yes	807.947	807.945	-0.002
CAL3060	359670.898	4460283.163	Yes	834.101	834.144	0.043
CAL3067	361158.944	4446271.021	Yes	767.38	767.405	0.025
CAL3079	351775.823	4453212.571	Yes	775.148	775.183	0.035
CAL3081	387908.305	4434341.233	Yes	735.637	735.632	-0.005
CAL3083	390281.426	4456650.822	Yes	709.32	709.285	-0.035
CAL3086	722338.717	4482676.762	Yes	377.866	377.866	0
CAL3102	719158.678	4468119.691	Yes	391.408	391.432	0.024
CAL3114	744079.729	4463539.449	Yes	329.028	329.045	0.017
CAL3098	754741.01	4477877.984	Yes	376.979	376.946	-0.033
CAL3087	752232.338	4490996.408	Yes	301.621	301.617	-0.004
CAL3095	718103.415	4514727.992	Yes	396.222	396.198	-0.024
CAL3099	738395.317	4504515.557	Yes	338.54	338.527	-0.013
CAL3100	738178.864	4515804.218	Yes	362.461	362.462	0.001
CAL3105	752777.065	4512687.947	Yes	355.391	355.345	-0.046
CAL3112	729278.003	4489318.046	Yes	349.816	349.807	-0.009
CAL3085	720231.639	4457919.89	Yes	445.709	445.665	-0.044
CAL3092	742523.222	4444000.589	Yes	365.9	365.911	0.011
CAL3096	751876.585	4435650.717	Yes	323.967	323.951	-0.016
CAL3107	719565.347	4435887.619	Yes	425.371	425.333	-0.038

UTM 15 Control

Project Data Unit: Meter
 Vertical Accuracy Class tested: 10.0-cm
 Elevation Calculation Method: Interpolated from TIN
 LiDAR Classifications Included: 2/0 Ground (All)/0W

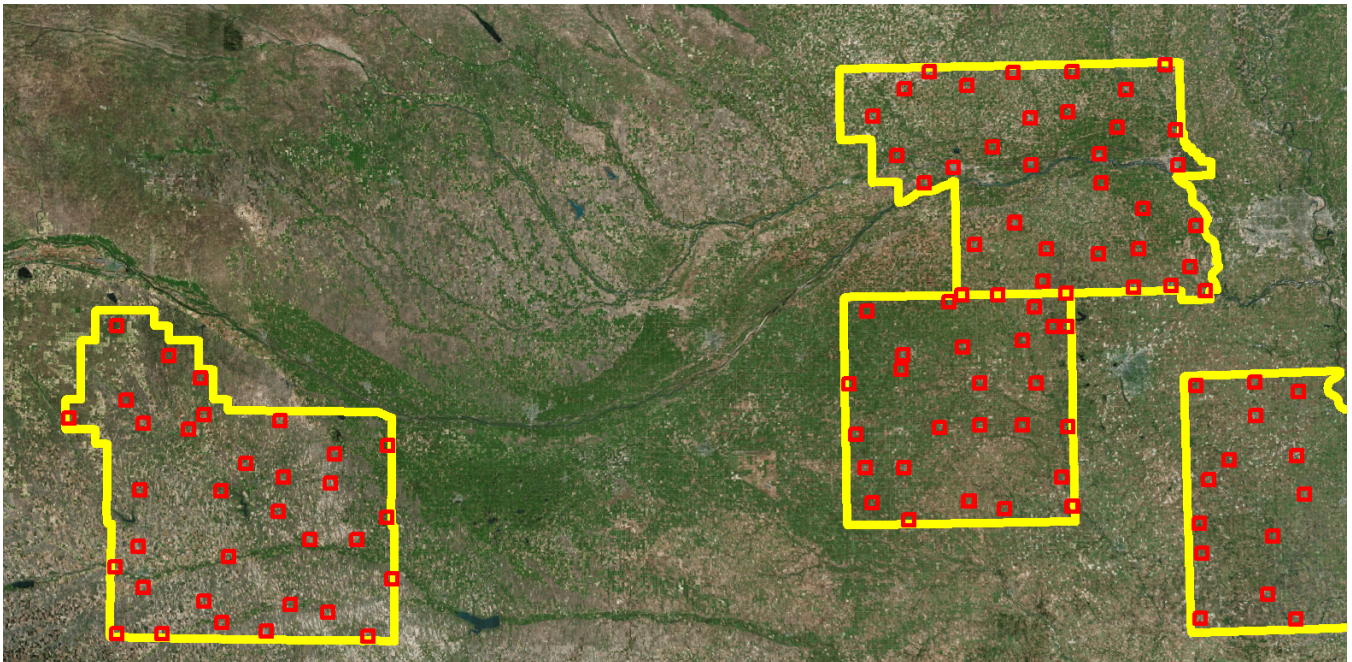
Check Points in Report: 14
 Check Points with LiDAR Coverage: 14
 Check Points (NVA): 14
 Check Points (VVA): 0
 Average Vertical Error Reported: -0.011 Meter
 Maximum (highest) Vertical Error Reported: 0.062 Meter
 Median Vertical Error Reported: -0.011 Meter
 Minimum (lowest) Vertical Error Reported: -0.066 Meter
 Standard deviation of Vertical Error: 0.039 Meter
 Skewness of Vertical Error: 0.331
 Kurtosis of Vertical Error: -1.056
 Non-vegetated Vertical Accuracy (NVA) RMSE(z): 3.951cm PASS
 Non-vegetated Vertical Accuracy (NVA) at the 95% Confidence Level +/-: 7.745cm PASS
 FGDC/NSSDA Vertical Accuracy at the 95% Confidence Level +/-: 7.745cm
 Non-vegetated Vertical Accuracy (NVA) RMSE(z) (DEM): 4.751cm PASS
 Non-vegetated Vertical Accuracy (NVA) at the 95% Confidence Level +/- (DEM): 9.312cm PASS

This data set was tested to meet ASPRS Positional Accuracy Standard for Digital Geospatial Data (2014) for a 10.0-cm RMSEz Vertical Accuracy Class. Actual NVA accuracy was found to be RMSEz = 3.951cm, equating to +/- 7.745cm at the 95% confidence level.

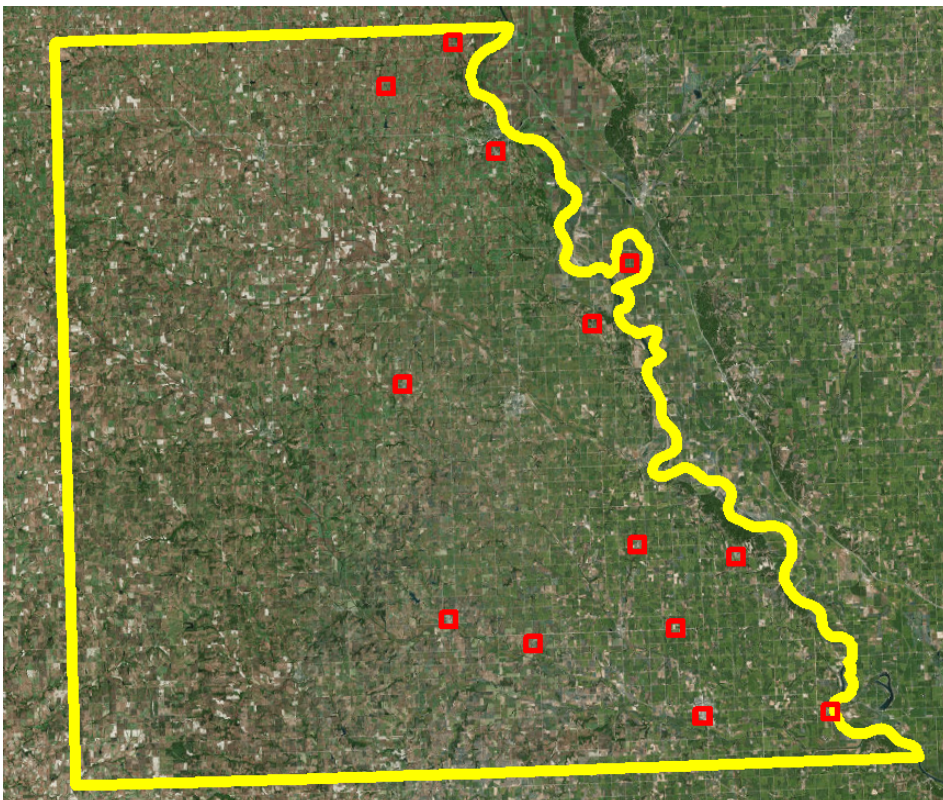
Check Point Id	Check Point X	Check Point Y	Coverage	Check Point Z	Z from LiDAR	Z Error
CAL3098	245640.847	4477865.01	Yes	376.979	376.946	-0.033
CAL3101	268235.859	4483377.538	Yes	334.84	334.879	0.039
CAL3113	273131.346	4490116.178	Yes	276.053	276.048	-0.005
CAL3094	258320.466	4504308.325	Yes	320.741	320.702	-0.039
CAL3103	254261.71	4517266.11	Yes	332.087	332.035	-0.052
CAL3105	246051.673	4512727.997	Yes	355.391	355.345	-0.046
CAL3088	271753.215	4457266.815	Yes	342.796	342.858	0.062
CAL3090	275624.765	4447237.837	Yes	311.072	311.077	0.005
CAL3091	278036.156	4436781.307	Yes	287.212	287.146	-0.066
CAL3091_alt	278061.362	4436760.551	Yes	285.504	285.451	-0.053
CAL3093	293024.25	4436356.333	Yes	270.734	270.73	-0.004
CAL3097	249199.771	4450089.697	Yes	312.133	312.163	0.03
CAL3104	258830.482	4446616.447	Yes	318.683	318.667	-0.016
CAL3106	283262.665	4455134.453	Yes	343.278	343.304	0.026

Lidar Control Point Layout

UTM 14



UTM 15



Lidar Filtering and Classification

The lidar filtering process encompasses a series of automated and manual steps to classify the boresighted point cloud data set. Each project represents unique characteristics in terms of cultural features (urbanized vs. rural areas), terrain type and vegetation coverage. These characteristics are thoroughly evaluated at the onset of the project to ensure that the appropriate automated filters are applied and that subsequent manual filtering yields correctly classified data. Data is most often classified by ground and “unclassified”, but specific project applications can include a wide variety of classifications including but not limited to buildings, vegetation, power lines, etc. MARS® software is used for the auto-filtering, manual filtering and QC of the classified data.

Merrick-Surdex JV used the ASPRS LAS Specification Version 1.4 – R13, 15 July 2013, Point Data Record Format 6 for this project and classified the lidar point cloud in accordance with the following classification classes and bitflags. The following outlines project specific requirements.

- Class 1 = Unclassified
- Class 2 = Bare-earth Ground
- Class 7 = Low point (noise)
- Class 9 = Water
- Class 10 = Ignored ground (near a breakline)
- Class 17 = Bridge decks
- Class 18 = High noise
- Bitflags
 - Withheld: Within the LAS file specification, a single bit flag indicating that the associated lidar point is geometrically anomalous or unreliable and should be ignored for all normal processes.
 - Traditional Class 8 (Model Keypoints) points moved to Class 2, and are flagged using the bit flags.
 - Overlap points will be flagged using bit flags.

Merrick-Surdex JV has developed several customized automated filters that are applied to the lidar data set based on project specifications, terrain, and vegetation characteristics. A filtering macro, which may contain one or more filtering algorithms, is executed to derive LAS files separated into the different classification groups as defined in the ASPRS classification table. The macros are tested in several portions of the project area to verify the appropriateness of the filters. Often, there is a combination of several filter macros that optimize the filtering based on the unique characteristics of the project. Automatic filtering generally yields a ground surface that is 85-90% valid, so additional editing (hand-filtering) is required to produce a more robust ground surface.

Lidar data is next taken into a graphic environment using MARS® to manually re-classify (or hand-filter) “noise” and other features that may remain in the ground classification after auto filter. A cross-section of the post auto-filtered surface is viewed to assist in the reclassification of non-ground data artifacts. The following is an example of re-classification of the non-ground points (elevated features) that need to be excluded from the true ground surface. Certain features such as berms, hilltops, cliffs and other features may have been aggressively auto-filtered and points will need to be re-classified into the ground classification. Data in the profile view displays non-ground (Unclassified, class 1) in grey and ground in brown/tan (Class 2). In figure 1, a small building was not auto-filtered and needs to be manually re-classified. Note that figure 2 has the building points reclassified to unclassified from the true ground surface.

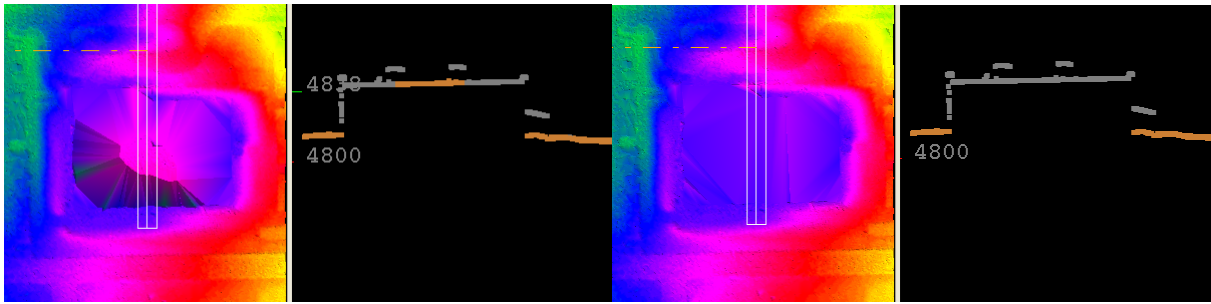


Figure 1

Figure 2

A combination of automated and semi-automated routines to classify buildings and vegetation. We expect that the classified buildings will meet a filtering criterion in the range of 90-95%.

At this point, individual lidar points from the original point cloud have now been parsed into separate classifications.

Filtered Lidar Checkpoint Report

After hand-filtering has been completed and quality checked, a Checkpoint Report is generated to validate that the accuracy of the ground surface is within the defined accuracy specifications. Each surveyed ground check point is compared to the lidar surface by interpolating an elevation from a Triangulated Irregular Network (TIN) of the surface. The MARS® derived report provides an in-depth statistical report, including an RMSE of the vertical errors; a primary component in most accuracy standards and a statistically valid assessment of the overall accuracy of the ground surface.

The below lidar check point reports provide statistics for 391 ground survey points used to validate the final filtered lidar surface.

Project Data Unit: Meter
 Vertical Accuracy Class tested: 10.0-cm
 Elevation Calculation Method: Interpolated from TIN
 LIDAR Classifications Included: 2,8/0 Ground (All)/0W

Check Points in Report: 391
 Check Points with LiDAR Coverage: 391
 Check Points (NVA): 231
 Check Points (VVA): 160
 Average Vertical Error Reported: 0.003 Meter
 Maximum (highest) Vertical Error Reported: 0.136 Meter
 Median Vertical Error Reported: 0.004 Meter
 Minimum (lowest) Vertical Error Reported: -0.135 Meter
 Standard deviation of Vertical Error: 0.037 Meter
 Skewness of Vertical Error: -0.381
 Kurtosis of Vertical Error: 1.192
 Non-vegetated Vertical Accuracy (NVA) RMSE(z): 3.742cm PASS
 Non-vegetated Vertical Accuracy (NVA) at the 95% Confidence Level +/-: 7.335cm PASS
 Vegetated Vertical Accuracy (VVA) at the 95th Percentile +/-: 14.250cm PASS
 FGDC/NSSDA Vertical Accuracy at the 95% Confidence Level +/-: 7.335cm
 Non-vegetated Vertical Accuracy (NVA) RMSE(z) (DEM): 3.856cm PASS
 Non-vegetated Vertical Accuracy (NVA) at the 95% Confidence Level +/- (DEM): 7.558cm PASS
 Vegetated Vertical Accuracy (VVA) at the 95th Percentile +/- (DEM): 13.440cm PASS

This data set was tested to meet ASPRS Positional Accuracy Standard for Digital Geospatial Data (2014) for a 10.0-cm RMSEz Vertical Accuracy Class. Actual NVA accuracy was found to be RMSEz = 3.742cm, equating to +/- 7.335cm at the 95% confidence level. Actual VVA accuracy was found to be +/- 14.250cm at the 95th percentile.

Checkpoint Id	Checkpoint X	Checkpoint Y	Checkpoint Z	Z from lidar	Z Error	Type
NVA_COLFAX_EXTRA	661876.733	4602027.806	433.48	433.439	-0.041	NVA
NVA_DODGE_EXTRA	691584.12	4600727.402	391.487	391.507	0.02	NVA
NVA_EXTRA_SAU	698571.333	4562777.689	380.164	380.22	0.056	NVA
NVA1001	708058.685	4609581.785	370.399	370.43	0.031	NVA
NVA1002	666137.828	4550001.516	495.715	495.613	-0.102	NVA
NVA1003	678507.181	4565438.184	457.384	457.457	0.073	NVA
NVA1004	626415.176	4599776.804	476.169	476.213	0.044	NVA
NVA1005	669788.233	4602227.012	437.393	437.289	-0.104	NVA
NVA1006	682120.492	4549957.904	399.071	399.08	0.009	NVA
NVA1007	667599.348	4560281.948	508.398	508.389	-0.009	NVA
NVA1008	713846.537	4577522.16	368.916	368.976	0.06	NVA
NVA1009	715530.693	4552478.319	335.332	335.468	0.136	NVA
NVA1010	640729.608	4588930.649	437.305	437.356	0.051	NVA
NVA1011	695063.253	4614971.549	381.124	381.129	0.005	NVA
NVA1012	636369.747	4618490.926	501.34	501.377	0.037	NVA
NVA1013	683889.093	4619501.598	410.741	410.742	0.001	NVA
NVA1014	708682.536	4591894.728	363.972	363.964	-0.008	NVA
NVA1015	636076.522	4601633.928	493.925	493.929	0.004	NVA
NVA1016	700279.239	4574721.609	379.864	379.729	-0.135	NVA
NVA1017	718059.113	4568540.542	356.847	356.843	-0.004	NVA
NVA1018	605424.797	4605922.804	518.924	518.968	0.044	NVA
NVA1019	650692.635	4595439.694	449.732	449.761	0.029	NVA
NVA1020	638514.944	4554941.969	493.589	493.639	0.05	NVA
NVA1021	674476.761	4608801.671	462.968	463.027	0.059	NVA
NVA1022	655777.794	4577744.069	437.078	437.045	-0.033	NVA
NVA1023	700419.816	4601368.132	401.049	401.03	-0.019	NVA
NVA1024	656572.954	4621061.342	453.064	453.053	-0.011	NVA
NVA1025	642421.609	4606567.054	480.605	480.582	-0.023	NVA
NVA1026	707505.443	4623083.144	390.137	390.113	-0.024	NVA
NVA1027	626002.586	4583196.41	455.648	455.68	0.032	NVA
NVA1028	710327.219	4567242.158	368.001	367.913	-0.088	NVA
NVA1029	687689.61	4583357.009	413.938	413.938	0	NVA
NVA1030	646586.404	4619074.314	512.861	512.809	-0.052	NVA
NVA1031	617052.814	4592334.328	464.308	464.314	0.006	NVA
NVA1032	656866.397	4608434.47	482.022	482.051	0.029	NVA
NVA1033	666869.786	4582879.539	427.35	427.332	-0.018	NVA
NVA1034	672810.637	4586743.167	407.018	407.054	0.036	NVA

NVA1035	662617.415	4590856.099	411.589	411.58	-0.009	NVA
NVA1036	697781.181	4548112.337	378.866	378.838	-0.028	NVA
NVA1037	699637.619	4564253.966	363.662	363.65	-0.012	NVA
NVA1038	685064.815	4592432.964	388.156	388.18	0.024	NVA
NVA1039	598864.924	4612241.84	572.769	572.82	0.051	NVA
NVA1040	619288.691	4615321.52	524.595	524.582	-0.013	NVA
NVA1041	662247.032	4573090.61	460.507	460.509	0.002	NVA
NVA1042	665883.138	4621434.044	445.71	445.771	0.061	NVA
NVA1043	650945.01	4548299.482	469.582	469.642	0.06	NVA
NVA1044	670940.468	4572276.475	455.476	455.417	-0.059	NVA
NVA1045	719683.278	4546609.526	336.387	336.442	0.055	NVA
NVA1047	699613.85	4585285.305	393.815	393.784	-0.031	NVA
NVA1048	653038.039	4553569.297	463.071	463.09	0.019	NVA
NVA1049	688959.303	4562563.822	383.021	382.918	-0.103	NVA
NVA1050	656279.462	4568523.398	491.552	491.593	0.041	NVA
NVA1051	599189.121	4599040.134	517.322	517.386	0.064	NVA
NVA1052	627473.688	4617674.12	516.133	516.168	0.035	NVA
NVA1053	608491.719	4616950.036	505.616	505.62	0.004	NVA
NVA1054	721601.363	4589018.782	351.884	351.78	-0.104	NVA
NVA1055	634476.101	4593059.832	468.126	468.202	0.076	NVA
NVA1056	711137.784	4601165.996	365.591	365.546	-0.045	NVA
NVA1057	690817.55	4570894.603	384.969	384.983	0.014	NVA
NVA1058	708278.665	4548369.111	379.949	380.036	0.087	NVA
VVA2001	707718.856	4564525.684	362.398	362.417	0.019	VVA
VVA2002	643090.385	4587338.24	432.094	432.071	-0.023	VVA
VVA2003	678501.21	4565424.401	455.79	455.892	0.102	VVA
VVA2004	706984.573	4620683.082	383.522	383.614	0.092	VVA
VVA2005	675976.529	4608822.112	442.097	442.275	0.178	VVA
VVA2005_ALT	674512.388	4608775.242	464.495	464.611	0.116	VVA
VVA2006	625476.953	4604676.685	482.091	482.141	0.05	VVA
VVA2007	642401.02	4606530.417	478.203	478.241	0.038	VVA
VVA2008	691990.975	4572183.746	412.207	412.363	0.156	VVA
VVA2009	699162.585	4591619.831	374.27	374.231	-0.039	VVA
VVA2010	677257.182	4552374.387	444.014	444.085	0.071	VVA
VVA2011	685223.567	4598169.03	388.732	388.611	-0.121	VVA
VVA2012	676664.833	4587023.113	433.485	433.554	0.069	VVA
VVA2013	658209.281	4621162.357	470.798	470.964	0.166	VVA
VVA2014	638565.983	4554991.894	493.435	493.443	0.008	VVA
VVA2015	695785.941	4613782.17	378.737	378.739	0.002	VVA
VVA2016	621832.191	4587485.957	460.767	460.741	-0.026	VVA

VVA2017	646777.376	4546191.548	482.767	482.821	0.054	VVA
VVA2018	686841.486	4554375.832	415.723	415.722	-0.001	VVA
VVA2019	649550.553	4568399.298	482.575	482.632	0.057	VVA
VVA2020	683950.023	4618908.51	400.879	400.927	0.048	VVA
VVA2021	688093.879	4583372.9	413.542	413.483	-0.059	VVA
VVA2022	706522.115	4607738.39	393.339	393.434	0.095	VVA
VVA2023	716123.923	4554195.993	345.87	345.863	-0.007	VVA
VVA2024	599539.37	4598677.65	516.816	516.984	0.168	VVA
VVA2025	627775.801	4619164.879	494.657	494.694	0.037	VVA
VVA2026	664308.623	4573137.289	503.199	503.286	0.087	VVA
VVA2027	632987.164	4593219.847	470.359	470.422	0.063	VVA
VVA2028	657754.24	4608467.703	451.33	451.426	0.096	VVA
VVA2029	665722.534	4562969.75	494.283	494.356	0.073	VVA
VVA2030	656654.771	4577771.93	434.046	434.101	0.055	VVA
VVA2031	700424.515	4601740.663	402.07	402.02	-0.05	VVA
VVA2032	718168.908	4568036.369	349.169	349.185	0.016	VVA
VVA2033	713893.251	4576517.998	382.051	382.115	0.064	VVA
VVA2034	721582.657	4589055.248	351.009	351.131	0.122	VVA
VVA2035	653021.442	4553547.365	462.159	462.314	0.155	VVA
VVA2035_alt	653077.483	4552776.064	467.082	467.163	0.081	VVA
VVA2036	612137.268	4592878.344	476.354	476.41	0.056	VVA
VVA2037	605390.26	4605928.587	519.301	519.384	0.083	VVA
VVA2038	649847.505	4595409.303	453.087	453.149	0.062	VVA
VVA2039	636037.243	4603265.564	503.403	503.338	-0.065	VVA
VVA2040	697709.923	4547989.831	372.13	372.115	-0.015	VVA
VVA2041	619638.588	4617488.139	526.128	526.15	0.022	VVA
NVA_extra_sew	639079.775	4525946.874	482.766	482.766	0	NVA
NVA_extra_york	629267.843	4536958.309	477.792	477.77	-0.022	NVA
NVA1059	618677.11	4527599.376	505.907	505.95	0.043	NVA
NVA1060	645491.174	4501725.87	472.842	472.854	0.012	NVA
NVA1061	641161.407	4475370.394	488.405	488.421	0.016	NVA
NVA1061_alt	641052.216	4475488.965	489.01	488.993	-0.017	NVA
NVA1062	604455.643	4486718.482	512.486	512.505	0.019	NVA
NVA1063	670106.571	4498565.621	419.995	419.951	-0.044	NVA
NVA1063_alt	670096.552	4498603.777	418.953	418.972	0.019	NVA
NVA1064	608173.057	4475448.226	503.433	503.446	0.013	NVA
NVA1065	650234.241	4521377.953	471.124	471.162	0.038	NVA
NVA1066	672097.821	4482572.429	423.226	423.209	-0.017	NVA
NVA1067	627679.987	4536919.151	477.238	477.251	0.013	NVA
NVA1068	638882.306	4537234.569	477.352	477.354	0.002	NVA

NVA1069	628354.682	4495125.943	492.796	492.79	-0.006	NVA
NVA1070	620726.473	4474074.08	490.557	490.598	0.041	NVA
NVA1071	675937.433	4507311.3	429.233	429.251	0.018	NVA
NVA1072	624840.98	4513560.238	468.735	468.735	0	NVA
NVA1073	676421.904	4473638.577	393.494	393.484	-0.01	NVA
NVA1073_alt	676910.942	4473356.962	393.844	393.88	0.036	NVA
NVA1074	634452.954	4515357.723	456.989	456.937	-0.052	NVA
NVA1075	608846.716	4498156.214	515.984	515.973	-0.011	NVA
NVA1076	662999.5	4471641.368	414.425	414.398	-0.027	NVA
NVA1077	636498.38	4484683.439	487.425	487.455	0.03	NVA
NVA1078	652283.534	4505210.653	463.171	463.165	-0.006	NVA
NVA1079	619585.675	4487228.306	501.411	501.457	0.046	NVA
NVA1080	618784.574	4511423.807	473.498	473.533	0.035	NVA
NVA1081	605087.912	4539844.684	530.917	530.932	0.015	NVA
NVA1082	650964.073	4490700.337	480.119	480.12	0.001	NVA
NVA1083	674336.155	4517653.938	404.134	404.171	0.037	NVA
NVA1084	661425.414	4532538.083	444.933	444.979	0.046	NVA
NVA1085	605658.31	4526504.486	522.96	523.025	0.065	NVA
NVA1086	599895.821	4514750.441	524.499	524.483	-0.016	NVA
NVA1087	667989.874	4528088.673	472.743	472.786	0.043	NVA
NVA1088	619275.177	4499281.438	500.448	500.49	0.042	NVA
NVA1089	660473.284	4494066.35	437.866	437.828	-0.038	NVA
NVA1090	639319.146	4528201.568	483.175	483.217	0.042	NVA
NVA1091	653056.191	4472676.073	454.237	454.281	0.044	NVA
NVA1092	631288.014	4500935.085	489.858	489.848	-0.01	NVA
NVA1093	626314.28	4522413.97	475.917	475.919	0.002	NVA
NVA1094	617331.653	4540378.984	514.909	514.95	0.041	NVA
NVA1095	631225.776	4475038.773	484.583	484.558	-0.025	NVA
NVA1095_alt	631229.541	4475024.468	484.346	484.312	-0.034	NVA
NVA1096	634121.785	4543030.168	493.495	493.477	-0.018	NVA
NVA1097	601414.393	4472180.266	509.616	509.577	-0.039	NVA
NVA1098	653834.051	4537517.186	451.155	451.161	0.006	NVA
NVA1099	645183.837	4515202.135	443.109	443.15	0.041	NVA
NVA1100	664789.432	4515118.626	435.216	435.257	0.041	NVA
NVA1101	610188.314	4519965.254	516.275	516.316	0.041	NVA
NVA1102	674121.187	4540276.737	424.592	424.624	0.032	NVA
VVA2042	644102.68	4514673.264	444.761	444.922	0.161	VVA
VVA2043	622066.486	4486937.573	496.205	496.262	0.057	VVA
VVA2044	598964.89	4526885.848	528.916	528.93	0.014	VVA
VVA2045	666057.336	4545468.404	475.097	475.223	0.126	VVA

VVA2046	667424.636	4500680.744	440.485	440.556	0.071	VVA
VVA2047	658312.331	4529379.248	438.492	438.629	0.137	VVA
VVA2048	649778.755	4476142.205	473.801	473.753	-0.048	VVA
VVA2049	632333.709	4543265.377	486.411	486.455	0.044	VVA
VVA2050	640583.131	4526823.609	481.593	481.735	0.142	VVA
VVA2051	668819.747	4487753.061	414.619	414.622	0.003	VVA
VVA2052	629770.395	4504882.474	484.666	484.759	0.093	VVA
VVA2053	668501.091	4528104.808	464.728	464.776	0.048	VVA
VVA2054	604525.415	4485785.857	510.553	510.607	0.054	VVA
VVA2055	628384.718	4494387.653	491.928	492.062	0.134	VVA
VVA2056	672560.552	4476603.788	414.551	414.531	-0.02	VVA
VVA2057	620722.07	4474058.19	490.309	490.391	0.082	VVA
VVA2058	648480.679	4536923.734	455.421	455.458	0.037	VVA
VVA2059	613987.043	4499532.984	502.233	502.29	0.057	VVA
VVA2060	652064.498	4521337.299	469.336	469.351	0.015	VVA
VVA2061	665846.455	4470632.339	418.34	418.335	-0.005	VVA
VVA2062	637980.038	4500581.135	475.795	475.818	0.023	VVA
VVA2063	630271.704	4479106.437	481.504	481.538	0.034	VVA
VVA2063_alt	630326.637	4479649.325	479.473	479.511	0.038	VVA
VVA2064	605130.077	4538267.631	532.524	532.539	0.015	VVA
VVA2065	618557.435	4527984.797	504.75	504.845	0.095	VVA
VVA2066	609414.07	4475229.397	500.561	500.585	0.024	VVA
VVA2067	652280.309	4504784.963	455.339	455.375	0.036	VVA
VVA2068	602539.372	4499531.191	509.508	509.569	0.061	VVA
VVA2069	601410.676	4470590.025	509.383	509.364	-0.019	VVA
VVA2070	675459.179	4507321.423	442.985	443.007	0.022	VVA
VVA2071	638845.199	4537200.772	476.681	476.737	0.056	VVA
VVA2072	605467.215	4517283.457	514.666	514.778	0.112	VVA
NVA1103	387653.576	4478820.572	780.153	780.128	-0.025	NVA
NVA1105	376854.296	4501794.959	828.488	828.478	-0.01	NVA
NVA1115	412020.052	4483401.606	759.749	759.771	0.022	NVA
NVA1116	360212.67	4480857.38	853.838	853.826	-0.012	NVA
NVA1118	368487.87	4494027.604	853.155	853.128	-0.027	NVA
NVA1119	406254.568	4472146.176	723.04	723.012	-0.028	NVA
NVA1124	379565.455	4486343.926	801.64	801.623	-0.017	NVA
NVA1130	388865.624	4498699.494	836.548	836.577	0.029	NVA
NVA1131	355445.784	4485848.76	879.289	879.284	-0.005	NVA
NVA1135	408660.485	4506011.314	835.961	835.988	0.027	NVA
NVA1137	399092.439	4481983.674	775.499	775.538	0.039	NVA
NVA1151	371379.298	4472539.171	826.773	826.768	-0.005	NVA

NVA1156	395190.666	4491788.125	805.509	805.523	0.014	NVA
NVA1160	406443.723	4491441.272	778.081	778.087	0.006	NVA
NVA1161	379224.01	4467646.649	805.281	805.265	-0.016	NVA
NVA1164	355634.03	4497236.369	887.751	887.724	-0.027	NVA
NVA1167	399273.377	4504578.826	860.908	860.888	-0.02	NVA
NVA1168	352072.798	4473783.681	839.828	839.84	0.012	NVA
NVA1104	409615.067	4459221.215	680.42	680.398	-0.022	NVA
NVA1109	417733.267	4463909.187	674.382	674.382	0	NVA
NVA1112	427133.543	4437947.604	695.44	695.38	-0.06	NVA
NVA1121	422427.116	4452513.194	722.864	722.783	-0.081	NVA
NVA1122	436742.604	4443664.074	640.772	640.789	0.017	NVA
NVA1123	417517.226	4434838.192	718.307	718.339	0.032	NVA
NVA1128	402999.806	4433359.115	765.129	765.071	-0.058	NVA
NVA1139	445591.989	4449896.236	682.487	682.47	-0.017	NVA
NVA1142	411236.704	4444623.692	730.875	730.897	0.022	NVA
NVA1144	432055.405	4462279.529	672.657	672.649	-0.008	NVA
NVA1145	437482.694	4431474.564	671.186	671.199	0.013	NVA
NVA1152	441563.269	4458850.36	661.04	661.053	0.013	NVA
NVA1162	445722.208	4429752.227	689.912	689.912	0	NVA
NVA1106	426870.151	4493314.473	815.693	815.678	-0.015	NVA
NVA1133	427576.485	4481574.588	749.683	749.733	0.05	NVA
NVA1134	420221.502	4504249.914	789.189	789.168	-0.021	NVA
NVA1140	428105.34	4493338.708	805.652	805.666	0.014	NVA
NVA1143	432733.061	4470245.067	713.568	713.578	0.01	NVA
NVA1146	416782.441	4476869.229	726.207	726.181	-0.026	NVA
NVA1148	445394.566	4471754.066	718.841	718.89	0.049	NVA
NVA1150	437622.437	4499243.806	760.705	760.72	0.015	NVA
NVA1153	439186.691	4486336.084	779.453	779.474	0.021	NVA
NVA1157	444958.019	4494308.063	754.604	754.614	0.01	NVA
NVA1107	336047.088	4501154.605	881.241	881.214	-0.027	NVA
NVA1129	344721.96	4503808.48	934.085	934.145	0.06	NVA
NVA1110	371925.291	4524894.489	863.728	863.686	-0.042	NVA
NVA1117	380258.778	4517013.934	925.239	925.234	-0.005	NVA
NVA1125	345802.844	4526252.284	918.092	918.07	-0.022	NVA
NVA1132	371503.9	4511351.637	865.235	865.239	0.004	NVA
NVA1136	356814.657	4507394.409	905.304	905.303	-0.001	NVA
NVA1149	347587.784	4511823.078	924.764	924.745	-0.019	NVA
NVA1159	352473.042	4539031.509	937.727	937.745	0.018	NVA
NVA1163	358578.128	4526021.355	919.589	919.601	0.012	NVA
NVA1165	358900.338	4538880.833	905.981	906.031	0.05	NVA

NVA1108	399565.955	4456014.453	703.831	703.796	-0.035	NVA
NVA1111	390263.679	4462489.981	757.577	757.569	-0.008	NVA
NVA1113	352556.594	4443142.318	791.834	791.846	0.012	NVA
NVA1114	396702.915	4443123.664	768.374	768.388	0.014	NVA
NVA1120	372714.715	4459673.129	780.808	780.778	-0.03	NVA
NVA1126	382204.14	4441725.499	811.113	811.132	0.019	NVA
NVA1127	388603.998	4431906.648	768.216	768.199	-0.017	NVA
NVA1138	361967.509	4447898.817	757.945	757.953	0.008	NVA
NVA1141	372633.317	4450096.733	762.852	762.803	-0.049	NVA
NVA1147	351763.886	4462352.944	834.382	834.346	-0.036	NVA
NVA1154	359832.636	4462737.644	829.463	829.439	-0.024	NVA
NVA1155	365894.711	4430229.59	808.224	808.215	-0.009	NVA
NVA1158	353099.655	4432248.465	890.844	890.882	0.038	NVA
NVA1166	382931.042	4453485.252	724.326	724.256	-0.07	NVA
VVA2073	357459.527	4506756.552	891.616	891.661	0.045	VVA
VVA2075	387671.377	4478833.775	780.681	780.665	-0.016	VVA
VVA2080	388851.105	4499068.116	840.343	840.361	0.018	VVA
VVA2083	376243.823	4485565.817	832.936	832.956	0.02	VVA
VVA2092	376777.475	4500038.713	814.007	814.063	0.056	VVA
VVA2099	406432.438	4491415.73	777.552	777.627	0.075	VVA
VVA2102	399252.088	4504542.838	860.257	860.319	0.062	VVA
VVA2106	351584.652	4472931.477	834.313	834.329	0.016	VVA
VVA2113	355461.451	4484634.607	879.767	879.812	0.045	VVA
VVA2116	355812.381	4496440.75	881.946	882.029	0.083	VVA
VVA2084	426634.473	4493325.622	817.955	817.998	0.043	VVA
VVA2089	431061.319	4470229.778	693.66	693.727	0.067	VVA
VVA2096	416798.778	4475718.366	706.111	706.178	0.067	VVA
VVA2098	444011.02	4494015.307	755.424	755.474	0.05	VVA
VVA2117	437567.357	4498389.025	759.094	759.156	0.062	VVA
VVA2118	439135.442	4486348.42	778.182	778.271	0.089	VVA
VVA2103	336089.38	4501042.206	880.793	880.805	0.012	VVA
VVA2108	344746.579	4503833.077	932.915	933.089	0.174	VVA
VVA2076	352371.042	4537378.242	934.518	934.603	0.085	VVA
VVA2078	345829.334	4526219.831	917.941	917.988	0.047	VVA
VVA2085	357034.464	4526070.917	913.989	914.04	0.051	VVA
VVA2088	347647.068	4511831.928	923.506	923.509	0.003	VVA
VVA2093	380314.779	4517022.835	926.533	926.519	-0.014	VVA
VVA2110	357237.255	4538895.93	916.656	916.783	0.127	VVA
VVA2112	371461.791	4511360.566	864.776	864.779	0.003	VVA
VVA2077	382960.045	4453451.837	725.729	725.828	0.099	VVA

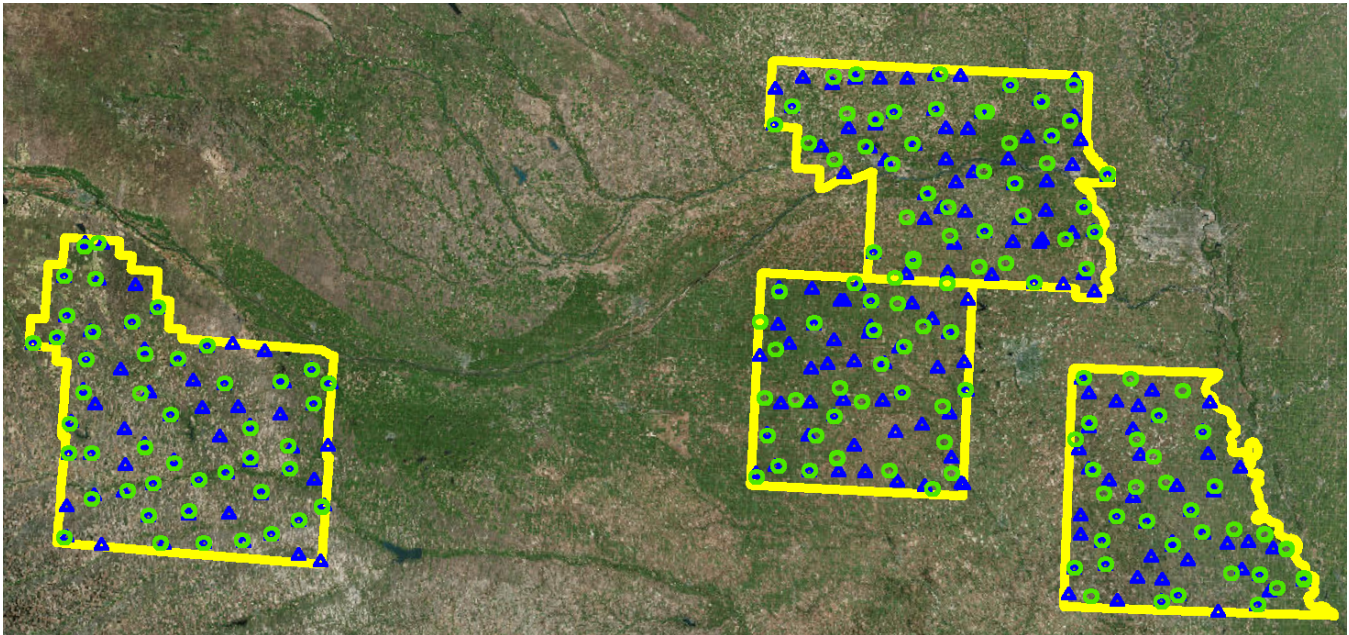
VVA2081	399727.09	4455973.464	703.312	703.345	0.033	VVA
VVA2082	360058.354	4462732.818	827.61	827.605	-0.005	VVA
VVA2094	396690.076	4444132.337	766.321	766.473	0.152	VVA
VVA2095	352290.721	4431531.207	880.874	880.941	0.067	VVA
VVA2097	382218.586	4441712.641	810.497	810.562	0.065	VVA
VVA2101	373960.045	4450055.609	763.035	763.064	0.029	VVA
VVA2104	379239.891	4466062.482	806.247	806.275	0.028	VVA
VVA2105	361117.076	4446223.393	766.898	766.996	0.098	VVA
VVA2107	351751.851	4462352.539	832.787	832.89	0.103	VVA
VVA2109	387073.259	4431911.815	763.217	763.284	0.067	VVA
VVA2111	390247.446	4461174.704	739.957	740.038	0.081	VVA
VVA2074	427081.88	4438002.61	692.001	692.001	0	VVA
VVA2079	422378.851	4453064.015	718.648	718.647	-0.001	VVA
VVA2086	432016.575	4462033.783	675.577	675.647	0.07	VVA
VVA2087	409060.707	4459172.837	681.319	681.293	-0.026	VVA
VVA2090	402939.44	4432984.817	753.893	753.906	0.013	VVA
VVA2091	444769.068	4449050.435	669.351	669.425	0.074	VVA
VVA2091_alt	444731.777	4449036.086	671.587	671.64	0.053	VVA
VVA2100	436692.76	4443552.901	641.825	641.871	0.046	VVA
VVA2114	416558.713	4434849.709	718.83	718.891	0.061	VVA
VVA2115	417723.748	4465187.63	704.007	704.099	0.092	VVA
NVA1169	780325.6716	4449114.779	292.546	292.611	0.065	NVA
NVA1171	774505.2884	4458261.721	307.809	307.821	0.012	NVA
NVA1173	772874.6049	4433201.483	340.284	340.302	0.018	NVA
NVA1179	765341.6574	4490414.251	311.345	311.344	-0.001	NVA
NVA1179_alt	765332.7137	4490418.378	310.973	310.974	0.001	NVA
NVA1180	754596.8635	4477793.553	376.888	376.862	-0.026	NVA
NVA1181	802990.5265	4446640.348	273.407	273.467	0.06	NVA
NVA1182	790902.8856	4441917.481	300.447	300.462	0.015	NVA
NVA1182_alt	790903.277	4441981.458	299.742	299.787	0.045	NVA
NVA1183	782179.0801	4459447.419	343.877	343.873	-0.004	NVA
NVA1183_alt	782178.3548	4459464.731	343.449	343.439	-0.01	NVA
NVA1185	758146.123	4438393.215	313.532	313.549	0.017	NVA
NVA1189	791181.1231	4457584.823	339.596	339.64	0.044	NVA
NVA1191	762568.3666	4498447.432	331.612	331.618	0.006	NVA
NVA1192	765393.4466	4461433.62	330.157	330.156	-0.001	NVA
NVA1194	760336.0144	4469242.445	323.844	323.82	-0.024	NVA
NVA1197	764688.5107	4508977.431	309.822	309.802	-0.02	NVA
NVA1202	786793.6829	4447735.187	300.915	300.911	-0.004	NVA
NVA1206	786617.1461	4436431.72	293.629	293.649	0.02	NVA

NVA1207	768292.2629	4476817.6	283.493	283.508	0.015	NVA
NVA1210	760534.8859	4451314.739	320.037	320.032	-0.005	NVA
NVA1213	777147.6899	4486241.953	289.492	289.497	0.005	NVA
NVA1213_alt	777289.2667	4486209.799	286.816	286.821	0.005	NVA
VVA2119	762612.5119	4498036.221	335.166	335.182	0.016	VVA
VVA2122	764884.7207	4461445.226	337.443	337.541	0.098	VVA
VVA2123	754467.772	4512482.395	365.916	365.996	0.08	VVA
VVA2125	793424.0519	4443193.143	285.256	285.292	0.036	VVA
VVA2127	776336.6301	4447372.829	303.488	303.488	0	VVA
VVA2128	776454.606	4463521.413	319.475	319.492	0.017	VVA
VVA2128_alt	776409.4004	4463515.957	321.174	321.195	0.021	VVA
VVA2131	787021.2688	4436494.46	281.334	281.391	0.057	VVA
VVA2132	757823.7184	4438090.136	323.174	323.194	0.02	VVA
VVA2137	786786.0352	4447748.561	301.492	301.513	0.021	VVA
VVA2137_alt	786829.6155	4447392.439	289.154	289.211	0.057	VVA
VVA2140	802993.3959	4446656.408	272.336	272.43	0.094	VVA
VVA2140_alt	802925.2709	4447477.343	297.045	297.107	0.062	VVA
VVA2143	787572.3724	4462293.244	336.826	336.876	0.05	VVA
VVA2143_alt	787783.7669	4462283.785	336.395	336.433	0.038	VVA
VVA2145	768325.6118	4478564.52	281.035	281.041	0.006	VVA
VVA2146	760286.5581	4469268.599	325.795	325.833	0.038	VVA
VVA2150	796034.0073	4457188.205	315.698	315.734	0.036	VVA
VVA2150_alt	795832.916	4457646.687	335.494	335.545	0.051	VVA
NVA1170	717323.751	4514710.396	383.583	383.539	-0.044	NVA
NVA1170_alt	717318.573	4514643.874	387.555	387.548	-0.007	NVA
NVA1172	735758.441	4434728.19	387.202	387.198	-0.004	NVA
NVA1174	743124.945	4512128.943	351.111	351.043	-0.068	NVA
NVA1175	738950.861	4472734.895	353.861	353.918	0.057	NVA
NVA1176	754370.987	4457355.884	364.602	364.6	-0.002	NVA
NVA1176_alt	754420.213	4456243.98	345.89	345.888	-0.002	NVA
NVA1177	728746.588	4455919.598	398.02	397.961	-0.059	NVA
NVA1178	719274.509	4445567.339	424.768	424.736	-0.032	NVA
NVA1184	742563.95	4443553.516	361.148	361.12	-0.028	NVA
NVA1186	720280.878	4464935.676	423.522	423.533	0.011	NVA
NVA1187	737072.914	4497633.406	347.218	347.2	-0.018	NVA
NVA1188	718062.388	4488772.013	398.942	398.938	-0.004	NVA
NVA1190	730530.447	4507277.679	349.268	349.211	-0.057	NVA
NVA1190_alt	730512.642	4507258.94	349.244	349.205	-0.039	NVA
NVA1193	720848.877	4457958.966	446.869	446.887	0.018	NVA
NVA1193_alt	720844.834	4457931.275	446.961	446.968	0.007	NVA

NVA1195	721053.177	4497076.614	385.094	385.124	0.03	NVA
NVA1196	730509.587	4447495.428	398.298	398.333	0.035	NVA
NVA1198	717967.385	4435834.763	434.582	434.548	-0.034	NVA
NVA1199	738533.271	4505997.264	347.619	347.627	0.008	NVA
NVA1200	729874.733	4478445.466	352.069	352.104	0.035	NVA
NVA1201	722375.3	4482010.598	361.217	361.277	0.06	NVA
NVA1203	740551.265	4488225.585	326.769	326.775	0.006	NVA
NVA1204	744339.61	4463700.969	346.804	346.771	-0.033	NVA
NVA1205	720322.636	4509364.124	366.037	365.977	-0.06	NVA
NVA1208	746996.011	4451573.435	328.884	328.906	0.022	NVA
NVA1209	746343.377	4502792.843	367.725	367.762	0.037	NVA
NVA1211	751545.731	4443722.493	366.233	366.225	-0.008	NVA
NVA1212	751730.908	4435765.728	327.854	327.886	0.032	NVA
NVA1212_alt	751651.196	4435784.285	327.083	327.07	-0.013	NVA
NVA1214	733275.211	4465290.064	401.652	401.657	0.005	NVA
VVA2120	750701.566	4478740.715	357.025	357.086	0.061	VVA
VVA2121	726082.505	4435580.512	449.7	449.714	0.014	VVA
VVA2124	739811.279	4476375.096	394.604	394.682	0.078	VVA
VVA2126	754446.799	4456270.368	345.54	345.568	0.028	VVA
VVA2129_rec	718125.348	4514738.958	395.584	395.572	-0.012	VVA
VVA2130	738813.298	4493781.585	316.534	316.584	0.05	VVA
VVA2133	730534.176	4447411.305	395.833	395.863	0.03	VVA
VVA2134	720989.701	4498480.698	379.633	379.663	0.03	VVA
VVA2135	728170.425	4473206.904	373.893	373.867	-0.026	VVA
VVA2136	751857.536	4435143.885	312.967	313.014	0.047	VVA
VVA2138	728754.148	4456247.133	405.958	405.944	-0.014	VVA
VVA2139	723441.166	4481683.981	357.532	357.556	0.024	VVA
VVA2141	733257.332	4465138.227	404.377	404.361	-0.016	VVA
VVA2142	734968.234	4515335.653	394.277	394.304	0.027	VVA
VVA2144	745312.596	4487786.103	329.893	329.862	-0.031	VVA
VVA2147	746364.21	4502796.922	365.506	365.574	0.068	VVA
VVA2148	716348.816	4492177.839	427	427.04	0.04	VVA
VVA2149	719292.643	4445542.849	425.219	425.225	0.006	VVA
VVA2151	744550.822	4464089.01	345.456	345.489	0.033	VVA

Checkpoint Layout

- ▲ NVA
- VVA



Hydro-flattening Breakline Collection

Hydro- flattening breaklines are captured per the USGS National Geospatial Program Lidar Base Specification Version 1.2. Final hydro-flattened breaklines features are appropriately turned into polygons (flat elevations) and polylines (decreasing by elevation) and are used to reclassify ground points in water to Water (Class 9). The lidar points around the breaklines are reclassified to Ignored Ground (Class 10) based on predetermined buffer.

Linear hydrographic features

To collect hydrographic features, Merrick-Surdex JV uses a methodology that directly interacts with the lidar bare-earth data to collect drainage breaklines. To determine the alignment of a drainageway, the technician first views the area as a TIN of bare-earth points using a color ramp to depict varying elevations. In areas of extremely flat terrain, the technician may need to determine the direction of flow based on measuring lidar bare-earth points at each end of the drain. The operator will then use the color ramped TIN to digitize the drainage in 2D with the elevation being attributed directly from the bare-earth LAS data. MARS® software has the capability of “flipping” views between the elevation TIN, Intensity and imagery, as necessary, to further assist in the determination of the drainage. All drainage breaklines are collected in a downhill direction. For each point collected, the software uses a five-foot (5’) search radius to identify the lowest point within that proximity. Within each radius, if a bare-earth point is not found that is lower than the previous point, the elevation for subsequent point remains the same as the previous point. This forces the drain to always flow in a downhill direction. Waterbodies that are embedded along a drainageway are validated to ensure consistency with the downhill direction of flow.

This methodology may differ from those of other vendors in that Merrick-Surdex JV relies on the bare-earth data to attribute breakline elevations. As a result of our methodology, there is no mismatch between lidar bare-earth data and breaklines that might otherwise be collected in stereo 3D as a separate process. This is particularly

important in densely vegetated areas where breaklines collected in 3D from imagery will most likely not match (either horizontally or vertically), the more reliable lidar bare-earth data.

Merrick-Surdex JV has the capability of “draping” 2D breaklines to a bare-earth elevation model to attribute the “z” as opposed to the forced downhill attribution methodology described above. However, the problem with this process is the “pooling” effect or depressions along the drainageway caused by a lack of consistent penetration in densely vegetated areas.

Criteria of linear hydrographic breaklines are as follows:

- Linear hydrographic features (e.g., visible streams, rivers, shorelines, canals, etc.) greater than one hundred feet (100’) wide will be captured as a double-lined polygon
 - linear hydrographic features must be flat and level bank-to-bank (perpendicular to the apparent flow centerline) with gradient following the immediately surrounding terrain
 - water surface edge must be at or just below the immediately surrounding terrain
 - streams should break at road crossings (e.g., culverts), and streams and rivers should not break at bridges

Waterbodies

Waterbodies are digitized from the color ramped TIN, similar to the process described above. The elevation attribute is determined as the technician collects the hydro feature by using the lowest bare-earth point within the polygon.

Criteria of waterbody breaklines are as follows:

- Waterbodies (e.g., lakes, ponds, reservoirs) greater than two (2) acres in size are surrounded by a water breakline (i.e., closed polygon)
 - waterbodies must be flat and level with a single elevation for every bank vertex
 - water surface edge must be at or just below the immediately surrounding terrain
 - long impoundments, such as reservoirs or inlets, whose water surface elevations drop when moving downstream should be treated as rivers

Color cycles provide a clear indication of where breaklines are to be collected, especially hydrographic breaklines. Figure 3 demonstrates no breaklines, where Figure 4 is breakline enforced displayed using color cycles within the MARS® software environment.

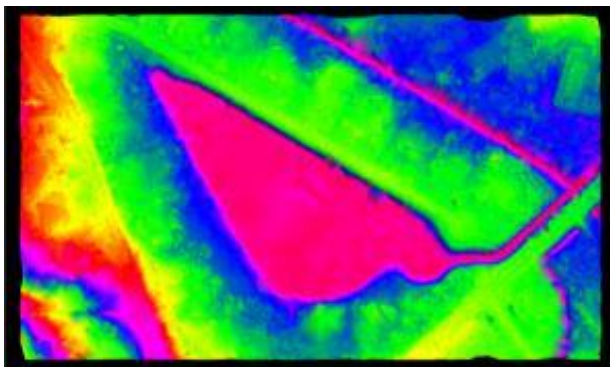


Figure 3

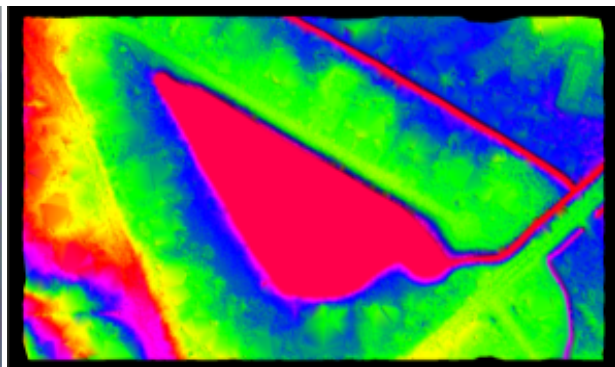


Figure 4

Contour Generation

Contours are generated using MARS® proprietary software at the desired contour interval in which the lidar will accurately support. Topology QC checks are completed to ensure topography is logical and complete. Additional QC checks for dangles and appropriate attribution are also verified to comply with project requirements before delivery to the client.

List of Deliverables

Classified lidar point cloud

- Fully compliant ASPRS LAS 1.4, point record format 6
- By tile
- Intensity values normalized (rescaled) to 16-bit
- FGDC-compliant metadata

Bare-earth DEM

- 1m cell size 32-bit floating point raster in ERDAS IMG format
- Bare-earth (hydro-flattened)
 - Culverts not be removed from the DEMs
 - Bridges removed from the DEMs
- By tile
- FGDC-compliant metadata

First Return Digital Surface Model (DSM)

- 1m cell size 32-bit floating point raster in ERDAS IMG format
- By tile and by county
- FGDC-compliant metadata

Hillshades

- 1m cell size in ERDAS IMG format
- By county
- FGDC-compliant metadata

Hydro-flattened breaklines

- Project-wide Esri feature class(es) for insertion into file geodatabase
 - PolylineZ
 - PolygonZ
- FGDC-compliant metadata

Intensity Images

- 1m cell size 8-bit, 256 color gray scale in GeoTIFF format
- By tile
- FGDC-compliant metadata

Two-foot (2') contours

- Esri feature class(es) for insertion into file geodatabase
- By county

- FGDC-compliant metadata

Control

- Survey report
- Esri shapefile format
- FGDC-compliant metadata

FGDC-compliant metadata (project level)

Detailed Lidar Mapping / Project Report

4-Band Ortho Imagery

- DOQQ-formatted 60cm pixel resolution 4-band (R,G,B,NIR) 32-bit (8-bit per band) orthoimagery in GeoTIFF format
- DOQQ tile index in Esri shapefile format
- Imagery (mosaic) seamlines in Esri shapefile format
- Compressed 4-band (R,G,B,NIR) CCM orthoimagery in MrSID format using a 60:1 compression ratio
- FGDC-compliant metadata
- Imagery Project Report detailing acquisition, processing and accuracy assessment

Appendix 1

Following is a more detailed lidar calibration workflow description.

LIDAR CALIBRATION AND BLOCK LAS OUTPUT

Note: All figures represented on the following pages are for general illustration purposes, and are not examples derived from the project.

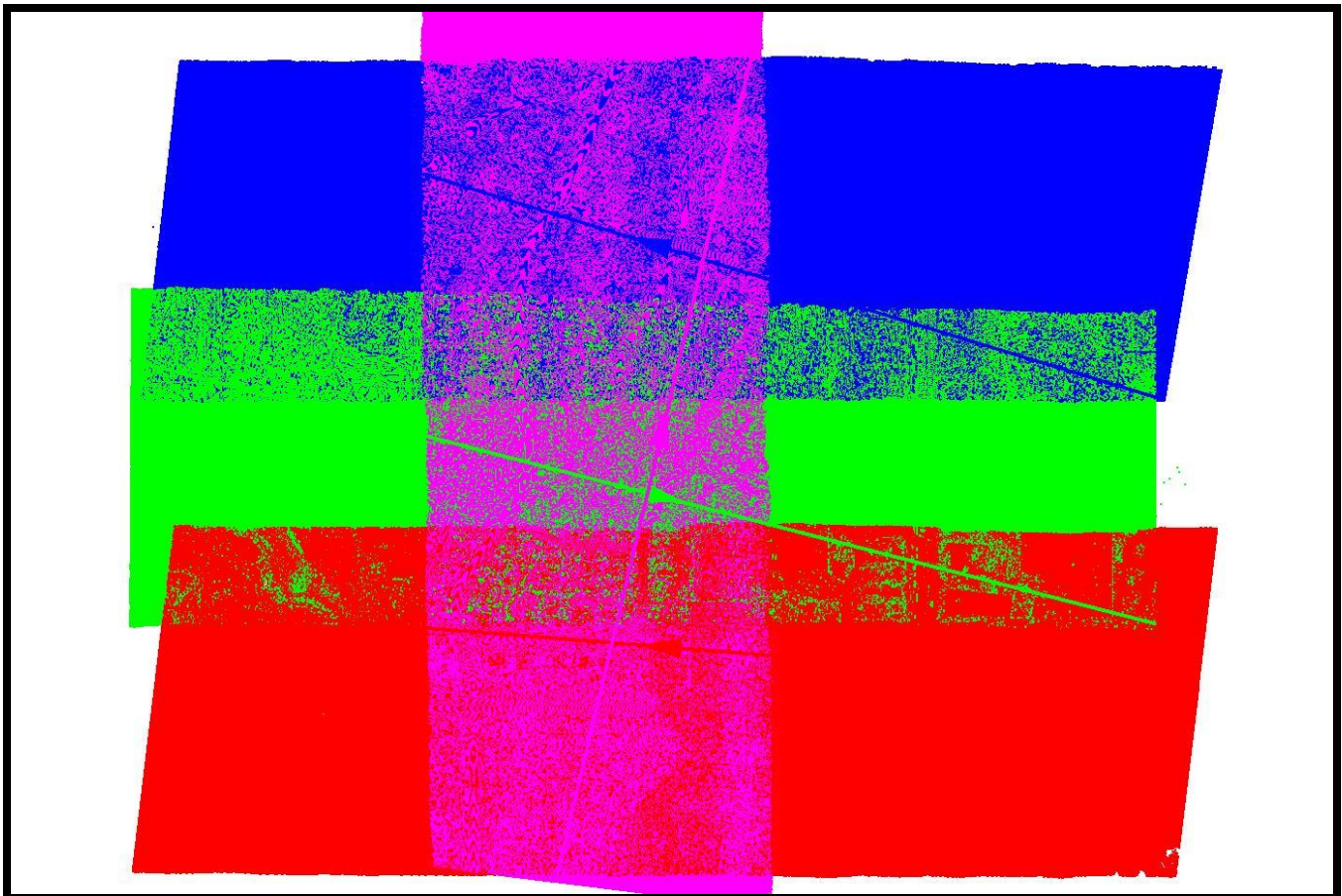
Initial Processing

Lidar data is output as LAS point data using Optech's Lidar Mapping Suite (LMS). LMS matches ground and roof planes plus roof lines to self-calibrate and correct system biases. These biases occur within the hardware of the laser scanning systems, within the Inertial Measurement Unit (IMU) and because of environmental conditions which affect the refraction of light. The systemic biases that are corrected for include scale, roll, pitch, and heading.

In addition to the self-calibration mode LMS runs a "production" mode which applies the self-calibration parameters and then analyzes each individual flight line and applies small adjustments to each line to tie overlapping lidar points even more tightly together.

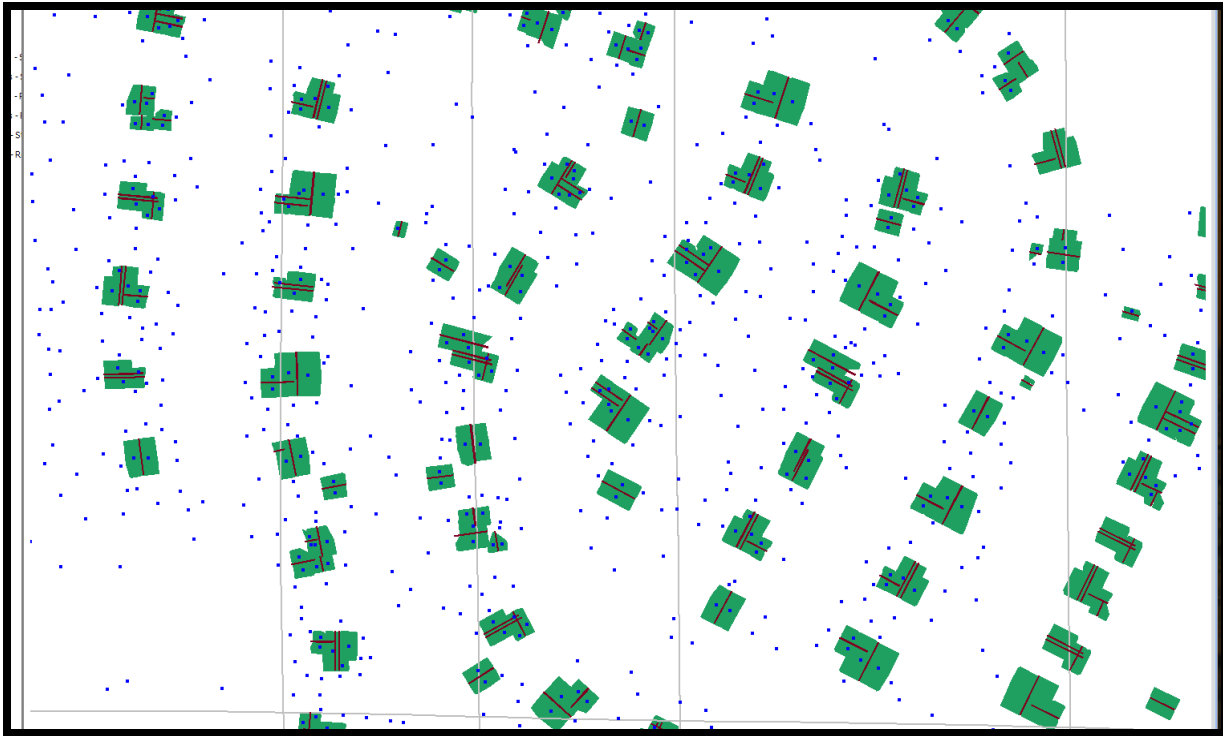
Boresight Self-Calibration Processing Procedures

An LMS boresight calibration is performed on an as-needed basis to correct scale, roll, pitch and heading biases. A minimum of three overlapping flights are flown in opposing directions with one cross flight.



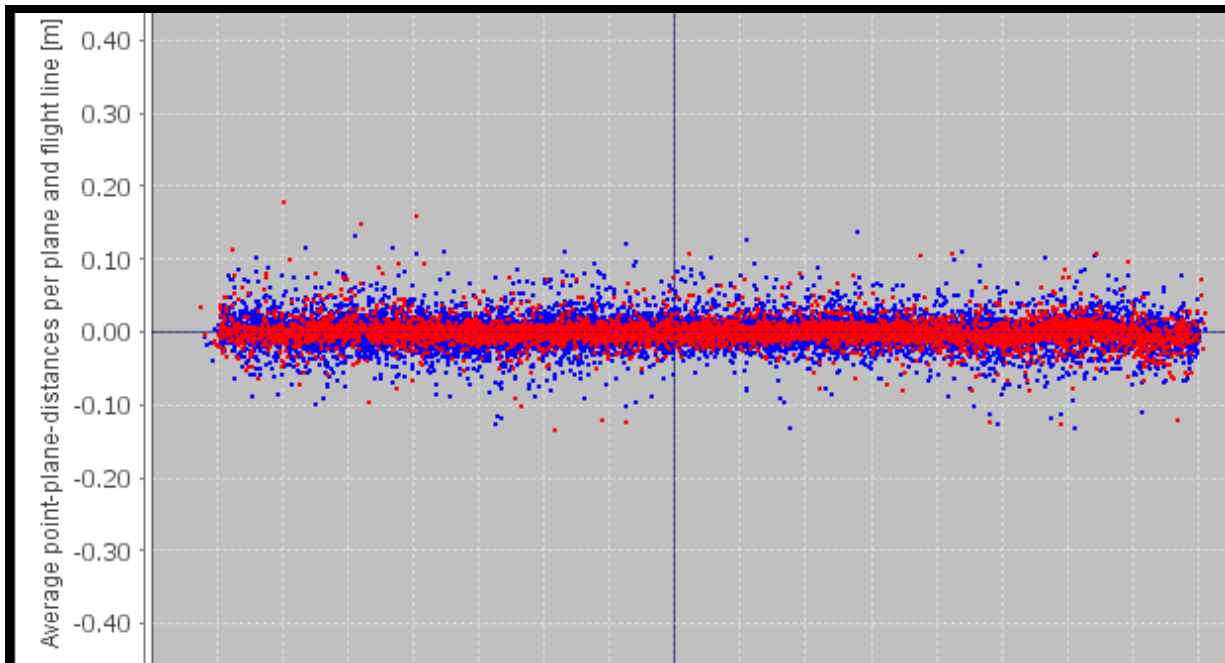
The Boresighting module frees scan angle scale, scan angle lag, XYZ boresight corrections and elevation position corrections while locking scan angle offset and XY position corrections.

The picked calibration site will have a good distribution of buildings for the self-calibration software to match ground planes, roof planes and roof lines.

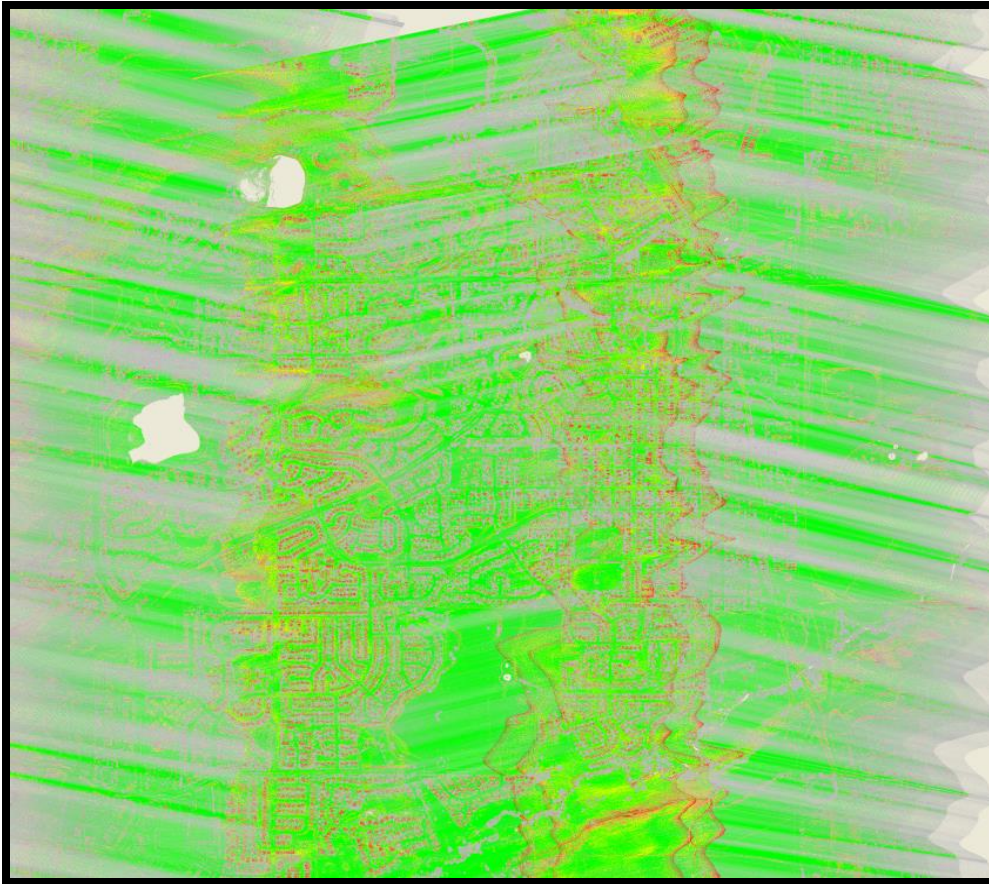


At the conclusion of the self-calibration run the data is quality checked with LMS plots

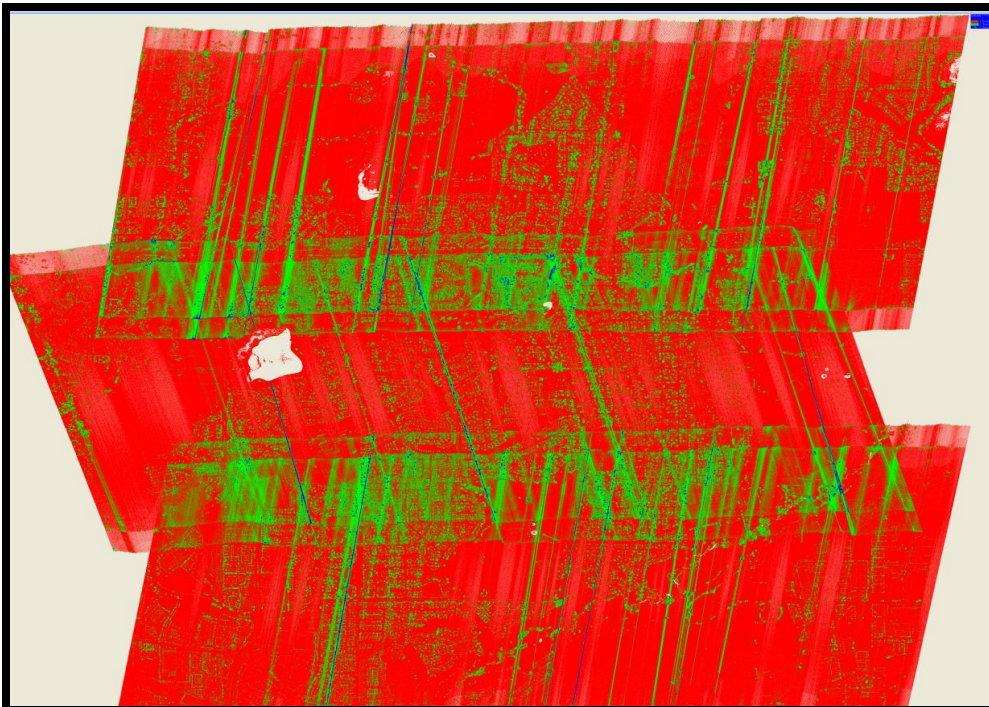
Plot of plane vertical distances from datum plane.



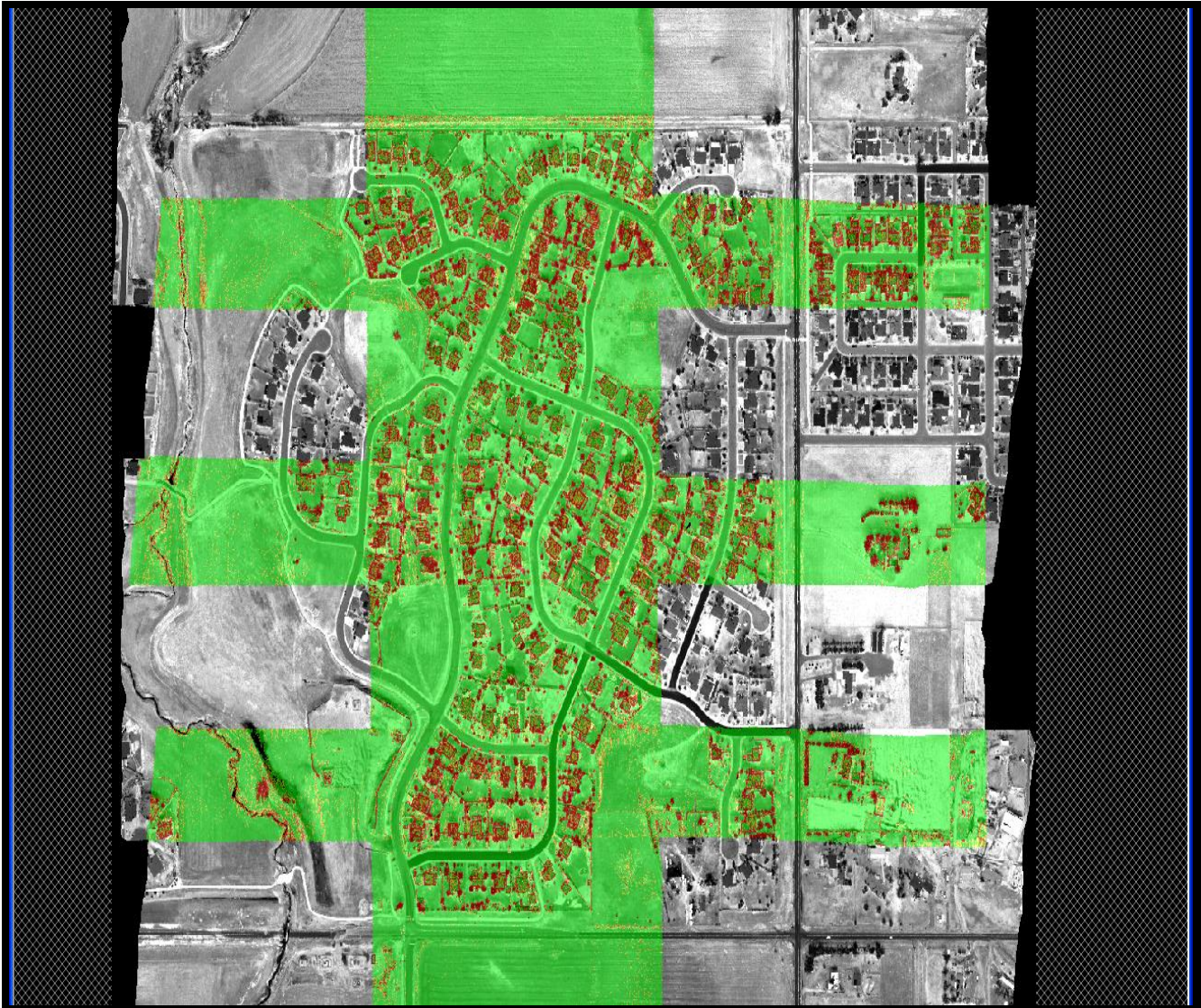
Plot of height differenced between flight lines. (Green=less than 5cm).



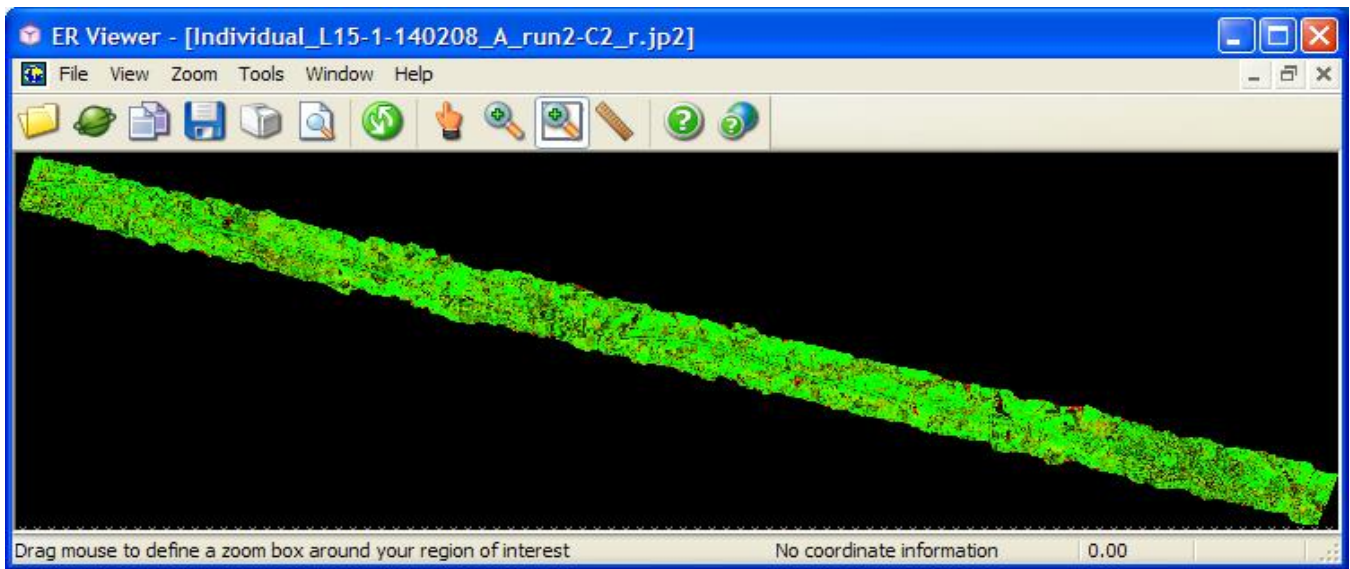
Plot of point densities. (Red=5-9 points per cell, green 10+ points per cell).



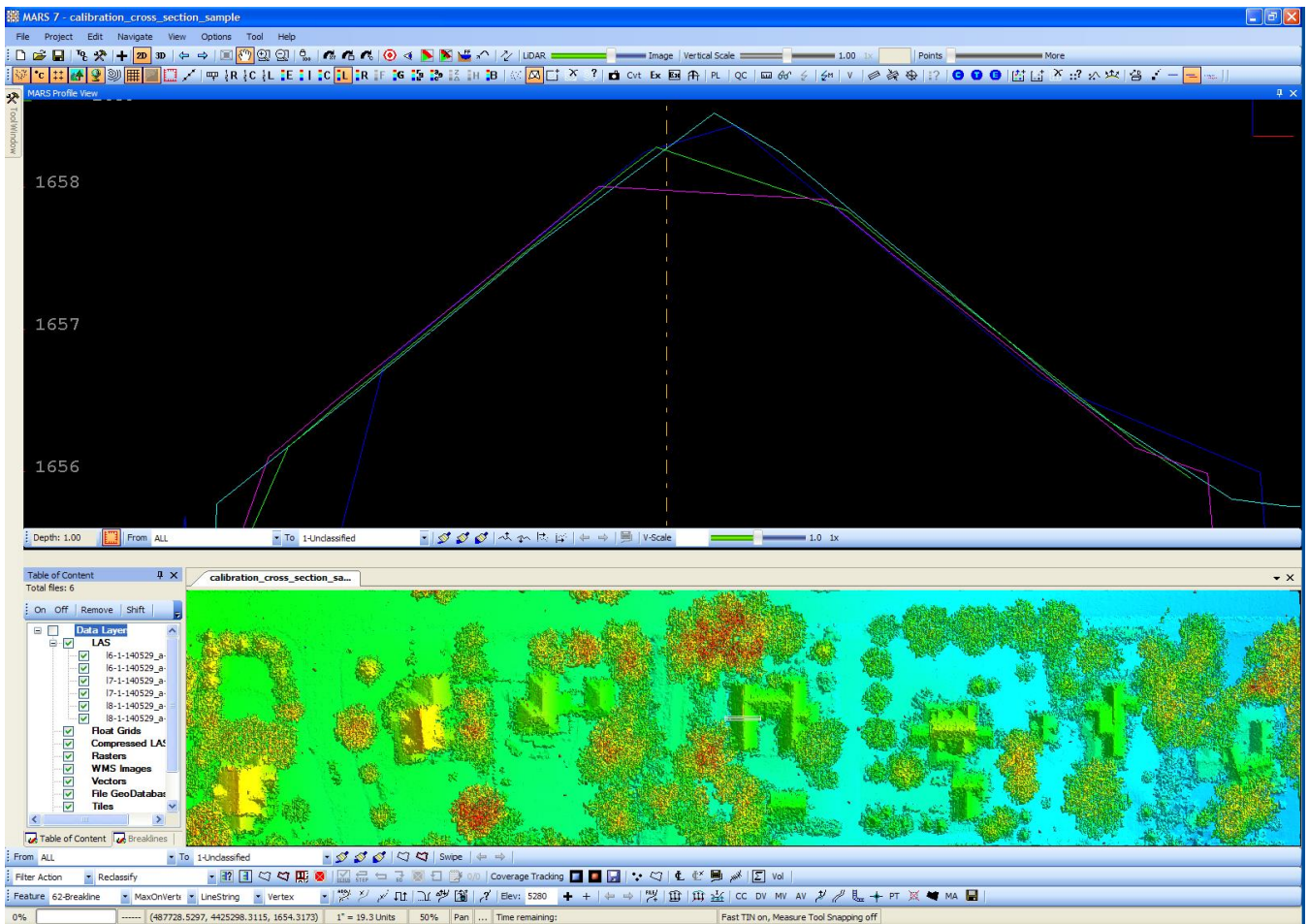
A Flight Line Separation Raster image is generated in Merrick Advanced Remote Sensing Software (MARS®), in this example ground returns from multiple flight lines that are fitting within 3 centimeters are colored green.



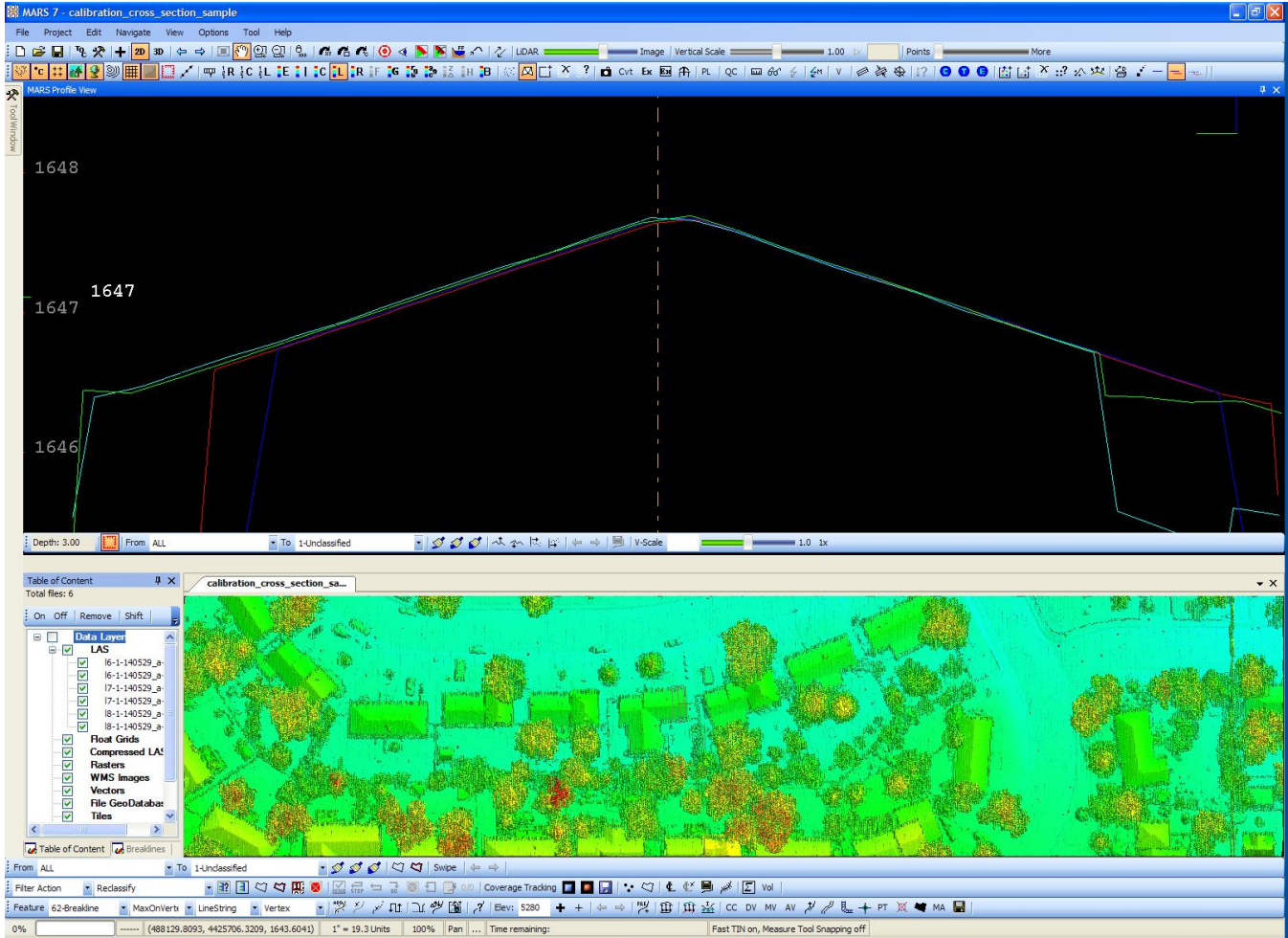
MARS® tests for internal relative vertical accuracy using inbound and outbound scan values. Again, Green is showing inbound and outbound scan data fitting to 3 centimeters.



Building cross sections are checked for good alignment. Pitch and heading are checked on roof planes parallel to the flight direction.



Roll and scale are checked on roof planes perpendicular to the flight direction.

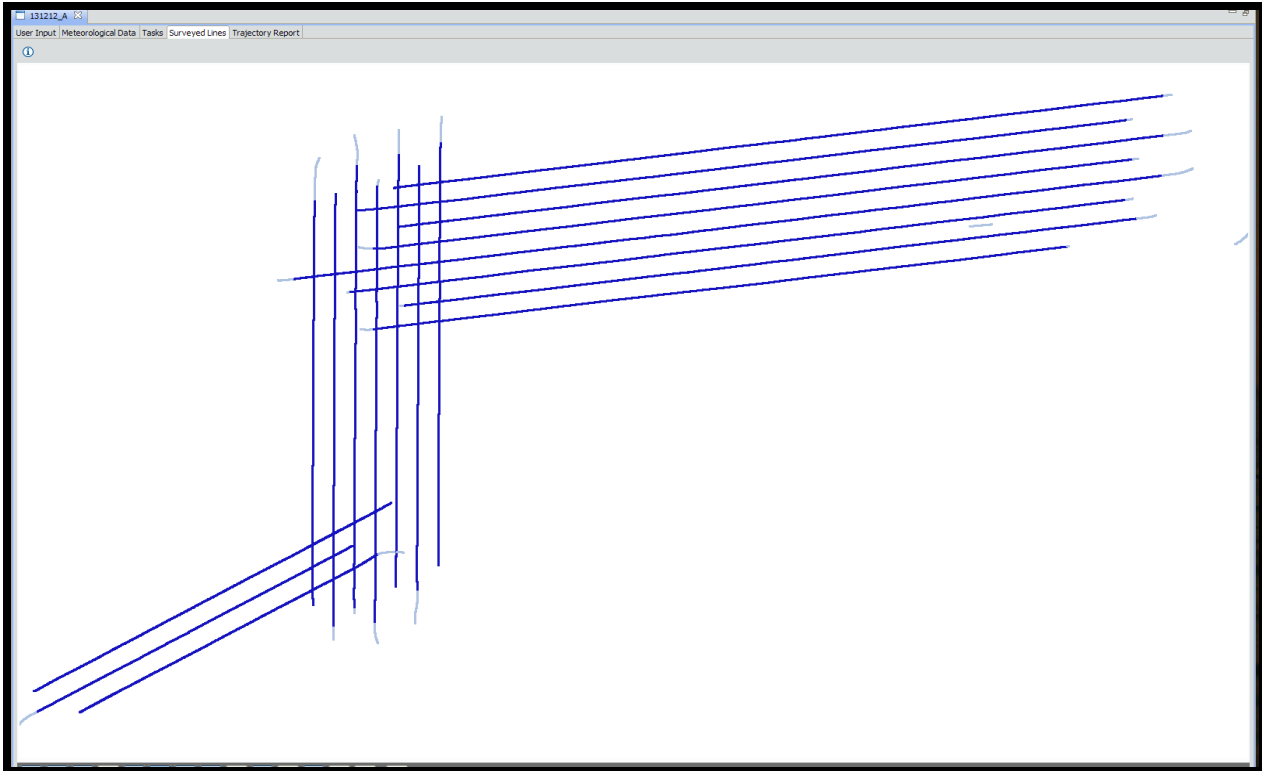


The LMS program outputs a "LCP" file with all the correction parameters. The calibration process may be run several times until the boresight adjustments are acceptable. When the boresight solution is acceptable the LCP file adjustments are saved and also applied to subsequent projects. Each new project is again analyzed and when the adjustment biases show too much drift a new boresight calibration is run. The LCP file may hold calibration tolerances for several projects.

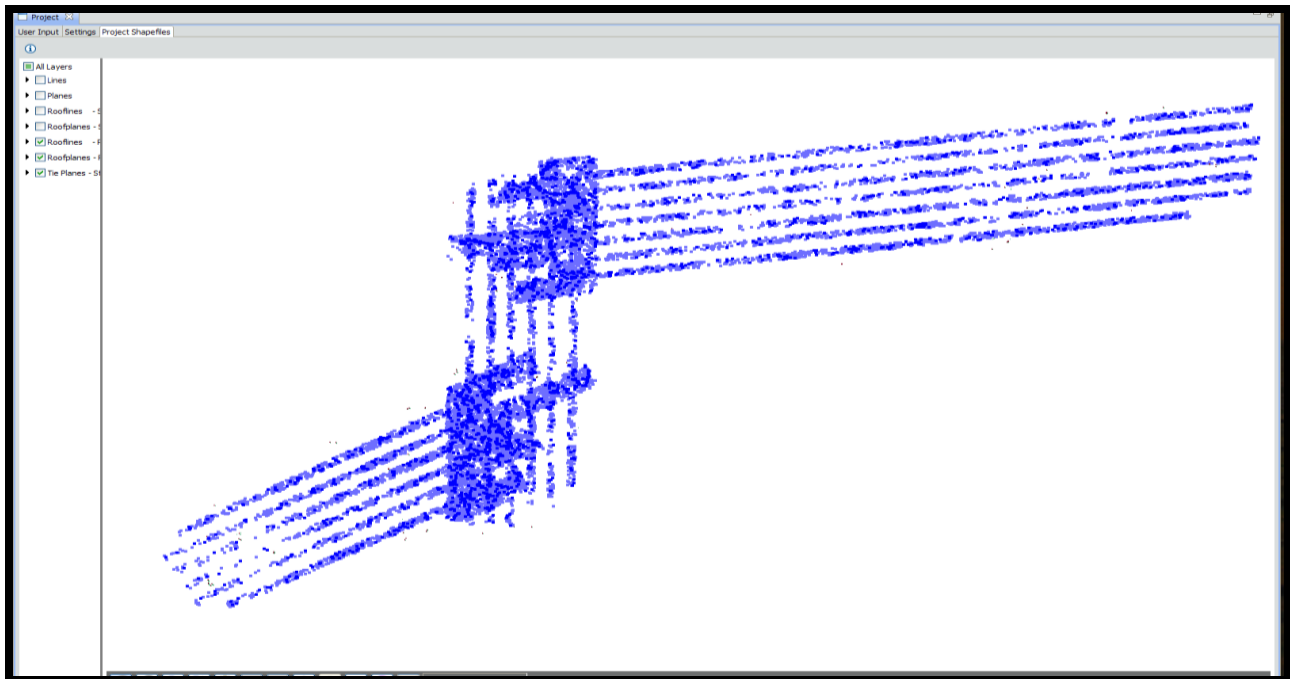
Block LAS Production Processing Procedures

The LMS production mode is run on each flight line to further tie the final lidar LAS flight line files tightly together. Production settings allow scan angle scale, scan angle lag to float and allows elevation to move slightly during flight line to flight line comparison thus further tying flight lines together. A cross flight with locked elevation data is used for controlling flight line elevations.

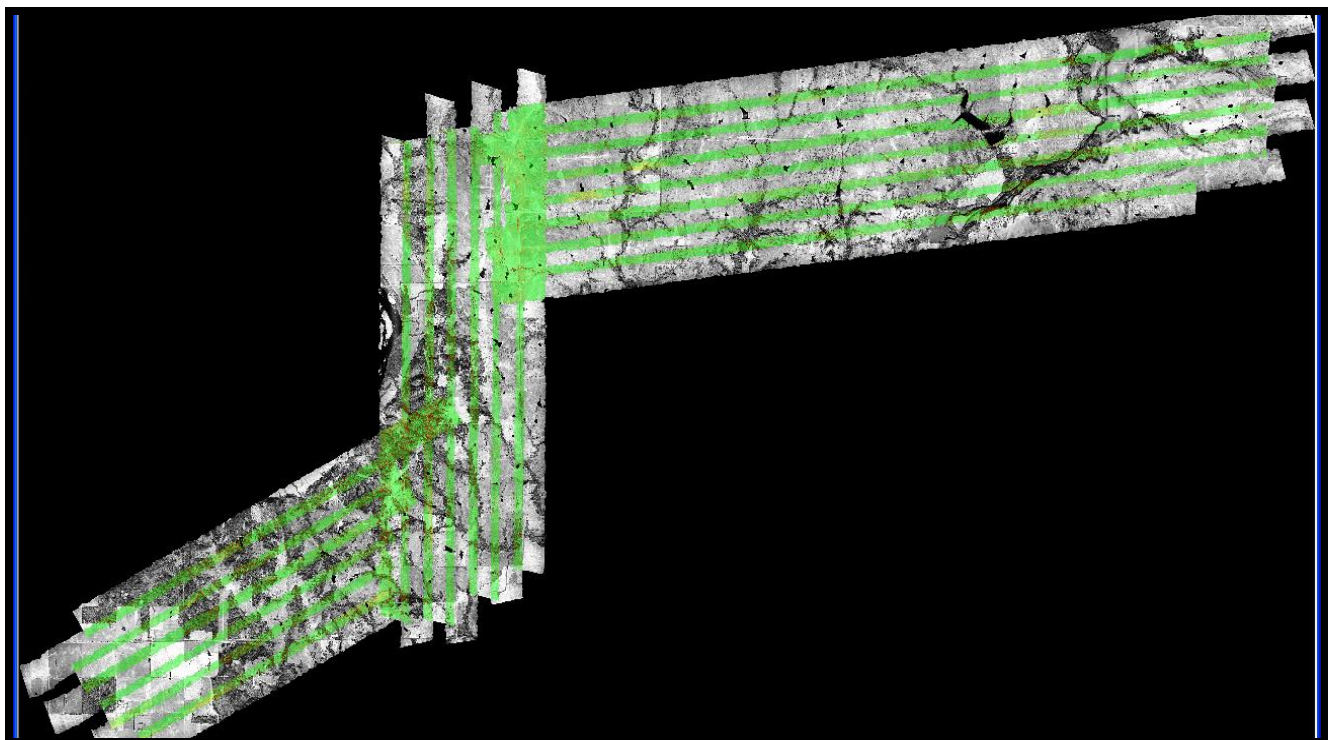
A block of data is selected to process with LMS production settings. Data collected during turns at the ends of flight lines is deselected (light blue lines).



As in self-calibration the LMS production program analyses ground, roof planes and rooflines. One cross flight is locked in elevation and all other lines are adjusted to it. Unlike the calibration site the distribution of roof planes is usually much less dense. Here matched ground tie planes are blue.

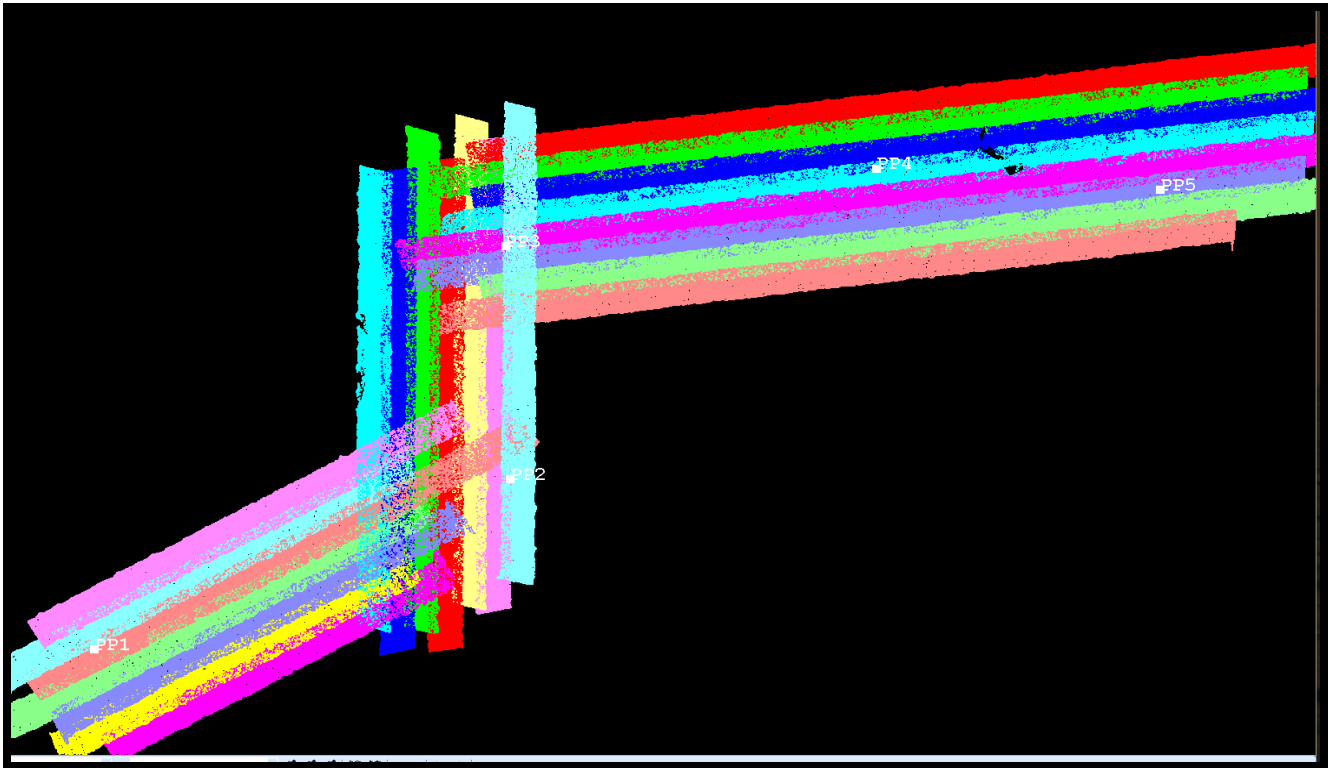


The same quality control outputs used to check self-calibrations are available to analyze the production run. Output plots are again available in LMS and cross sections plus a Flight Line Separation Raster are generated in MARS® to check coverage and quality.



Correcting the Final Elevation

After all the lines are tied together a ground control network is imported into MARS®. The ground control network may be pre-existing or collected by a licensed surveyor.



The next step is to match the ground control elevations to the lidar data set. A control report is run and the data set is shifted slightly to zero out the average elevation error and points checked for quality.

The final step before boresighted, leveled LAS files are ready for filtering is to run the MARS® QC Module on the block data. The Boresighted lidar QC Report outputs individual reports on Point Density, Nominal Pulse Spacing, Data Voids, Spatial Distribution, Scan Angles, Control Report, Flight Line Separation, Flight Line Overlap, Buffered Boundary, LAS Formats, Datums and Coordinates.

These reports are checked with the required specifications in the Project Management Plan.

Appendix 2

Following is a more detailed orthoimagery project report (AT and Horizontal Accuracy).

Aerial Triangulation Report

2018

014G01218F0028-NE_NRCS

Ortho LiDAR-2017_D18 project

Merrick-Surdex JV- Project Number J65219751

January 7, 2019



1.0 Overview

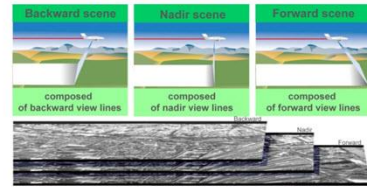
In the Spring of 2018, Merrick-Surdex JV performed aerial triangulation on ADS100 imagery collected from multiple Leica ADS100 aerial sensor systems as part of this mapping project the United States Geological Survey. All aerial imagery was collected with the support a GNSS/IMU data collection device that collected precision AirBorne GNSS

(ABGPS) exposure station control and precision angular values. The GNSS/IMU data was post processed with the Waypoint Inertial Explorer software to develop precision sensor position and attitude values. All aerial triangulation functions were performed utilizing the latest version of the Leica XPRO software.

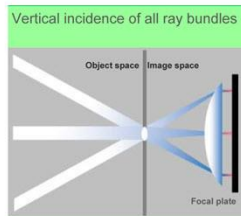
ADS 100 camera and accessories
(Courtesy of Leica Geosystems).



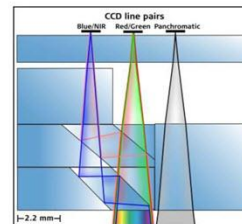
Pushbroom camera acquisition concept
(Courtesy of Leica Geosystems).



Telecentric lens concept
(Courtesy of Leica Geosystems).



Beam splitting to direct light to separate arrays
(Courtesy of Leica Geosystems).



for

of

The 60cm leaf off imagery was flown at approximately 24,000' above mean terrain with flight lines spaced with 30% side overlap. The area encompasses approximately 8,925 square miles and is Platte, Colfax, Dodge, Butler, Saunders, York, Seward, Fillmore, Saline, Otter, Johnson, Nemaha, Richardson and Pawnee counties in Nebraska. The products will include 4 band files at 60 cm pixel orthoimagery tiles in TIF fomats. The image below presents the general layout of the leaf off imagery.

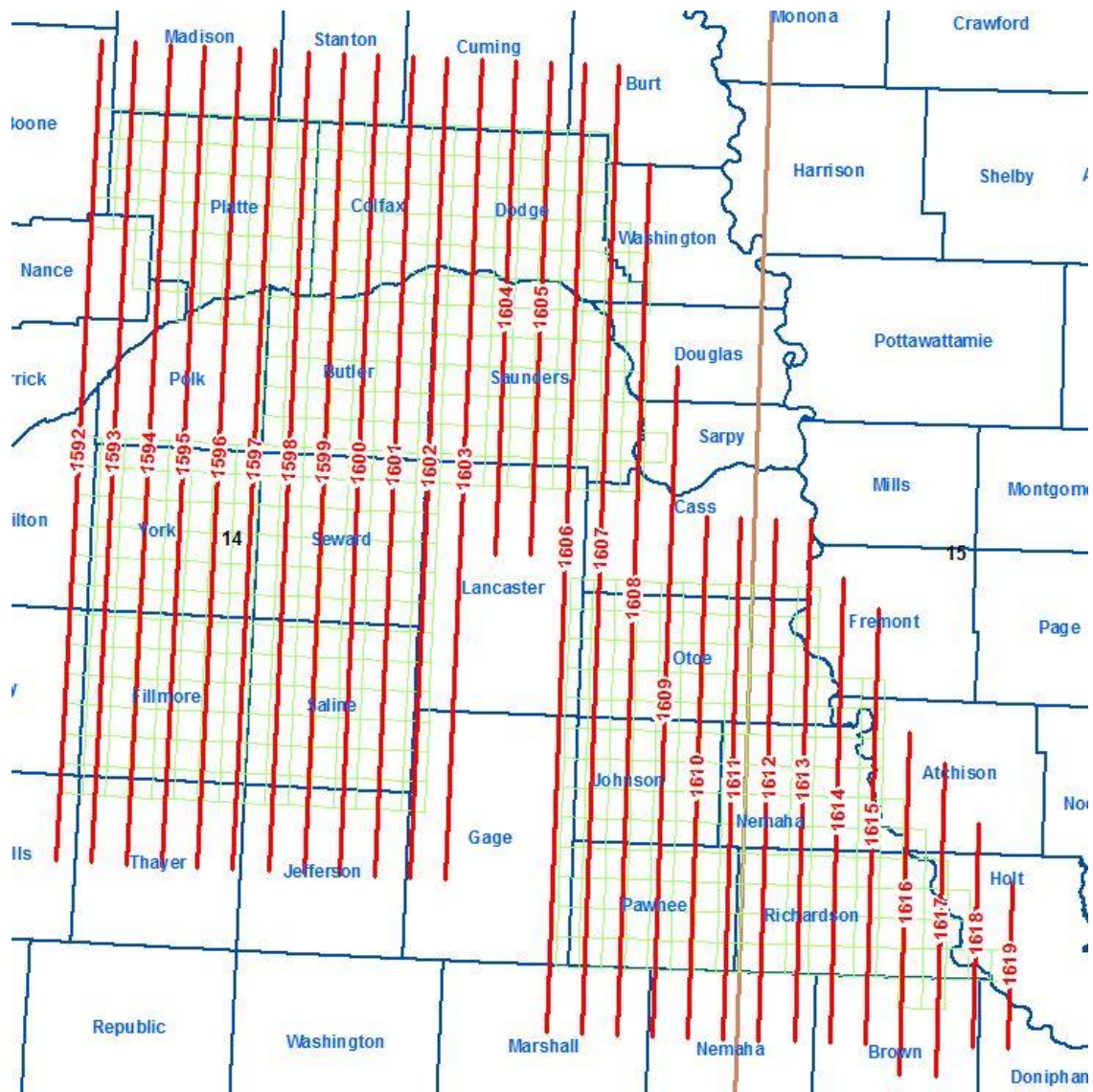


Figure 1: 60 cm ADS100 Flight Lines

2.0 Ground Control

The ground control for the ortho imagery phase of the project consisted of approximately 58 points distributed throughout the area of interest. The ortho control was a combination of photo identifiable points surveyed after the acquisition of the aerial photography. The graphic below represents layout of the ground control points used for this aerial triangulation. The points were all surveyed by GNSS techniques and processed against NGS monuments in the project area. The final coordinates were derived in UTM14(2011) and UTM15(2011) meters and NAVD88 elevations.

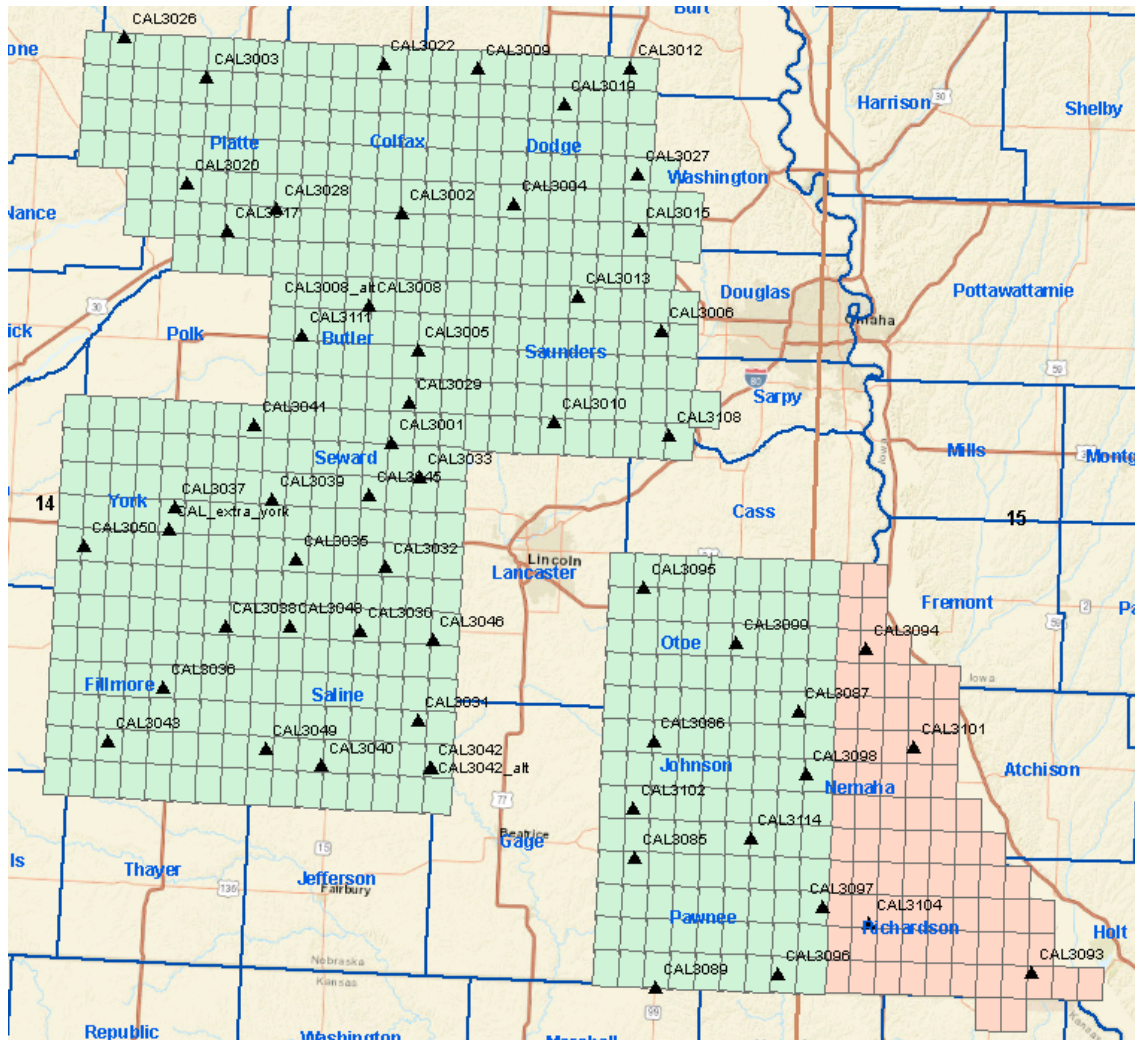


Figure 2: Ground Control Point Distribution

3.0 Aerial Triangulation

Aerial triangulation was performed on the 60 cm imagery as one block in the Leica XPro software. The product accuracy requirement of the color digital orthophotography produced under this project is a limiting RMSE in X or Y of 115 cm or less. The following sections of this report summarize the triangulation process.

The horizontal accuracy requirement of the color digital orthophotography produced under this project are defined to meet 4.0 meters of true ground at a 95% confidence level as defined by FGDC-STD-007.3-1998. This accuracy specification at the 95% level can be decomposed into a limiting RMSE in X and Y. These limiting RMSE values are computed to be 115 centimeters. Based upon these product accuracy standards, we would desire the triangulation results to be under ½ the product horizontal accuracy requirement and equal to the horizontal accuracy requirement of the product in Z (this requirement is derived from section 7.7 of the ASPRS Positional Accuracy Standards for Digital Geospatial Data published in November of 2014). Table 1 below presents the limiting triangulation accuracy values for this project.

Table 1
Triangulation Accuracy Limiting Values

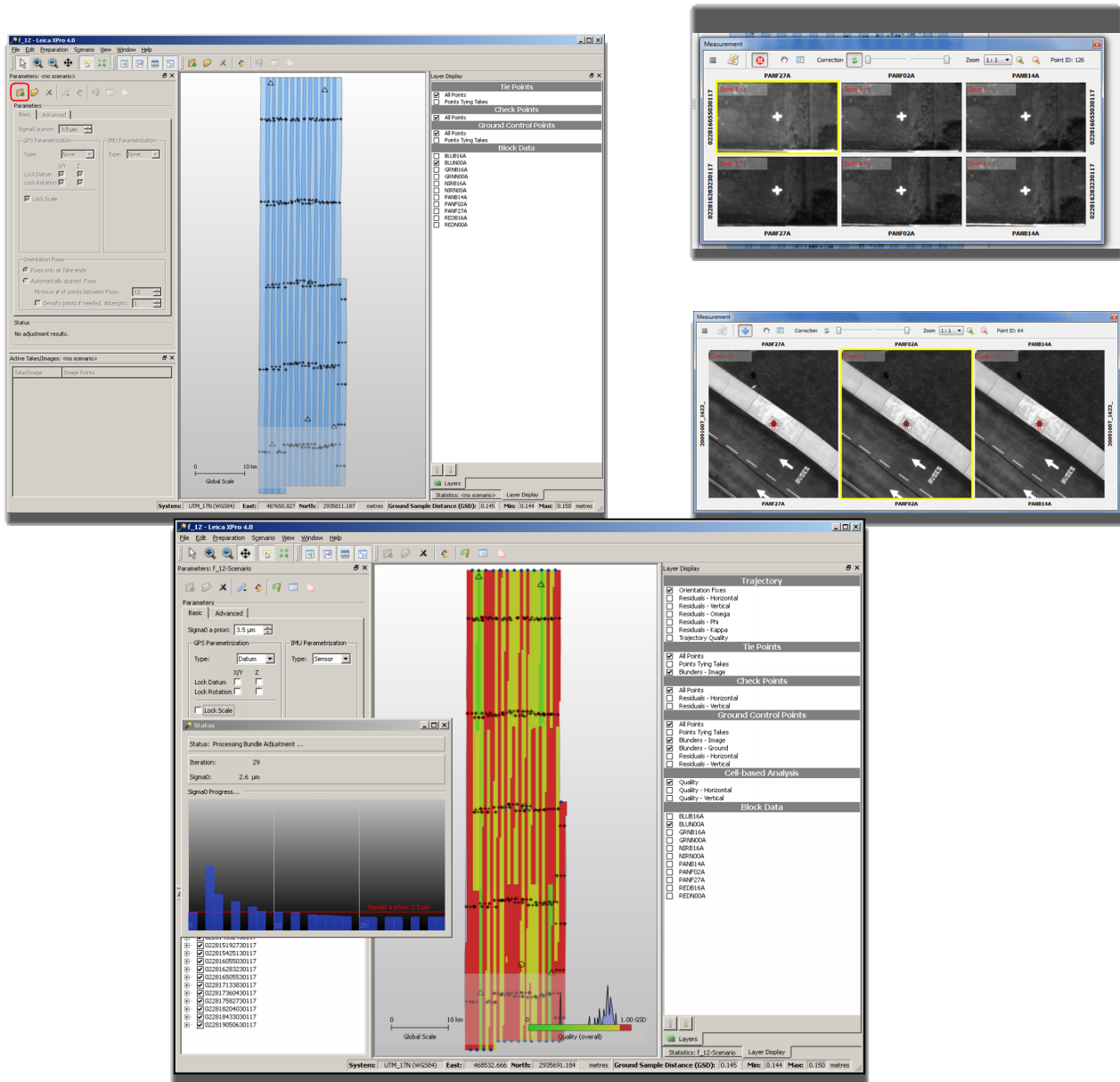
Product Resolution	Product Accuracy RMSE x or y	AT Limiting Accuracy RMSE x or y	AT Limiting Accuracy RMSEz
60 cm	115 cm	57.5 cm	115 cm

3.1 60 cm Imagery Aerial Triangulation

The required ground control points, images and GNSS/IMU support data was loaded into XPro. Once in XPro the block was setup with the appropriate parameters weights and initial point measurements were performed. Once completed, the software measured points were run through an ORIMA adjustment. In this adjustment weak and blundered points are automatically removed from the solution. The outcome of this relative adjustment is a set of corrected sensor position and attitude values the accurately model the sensor condition during imagery.

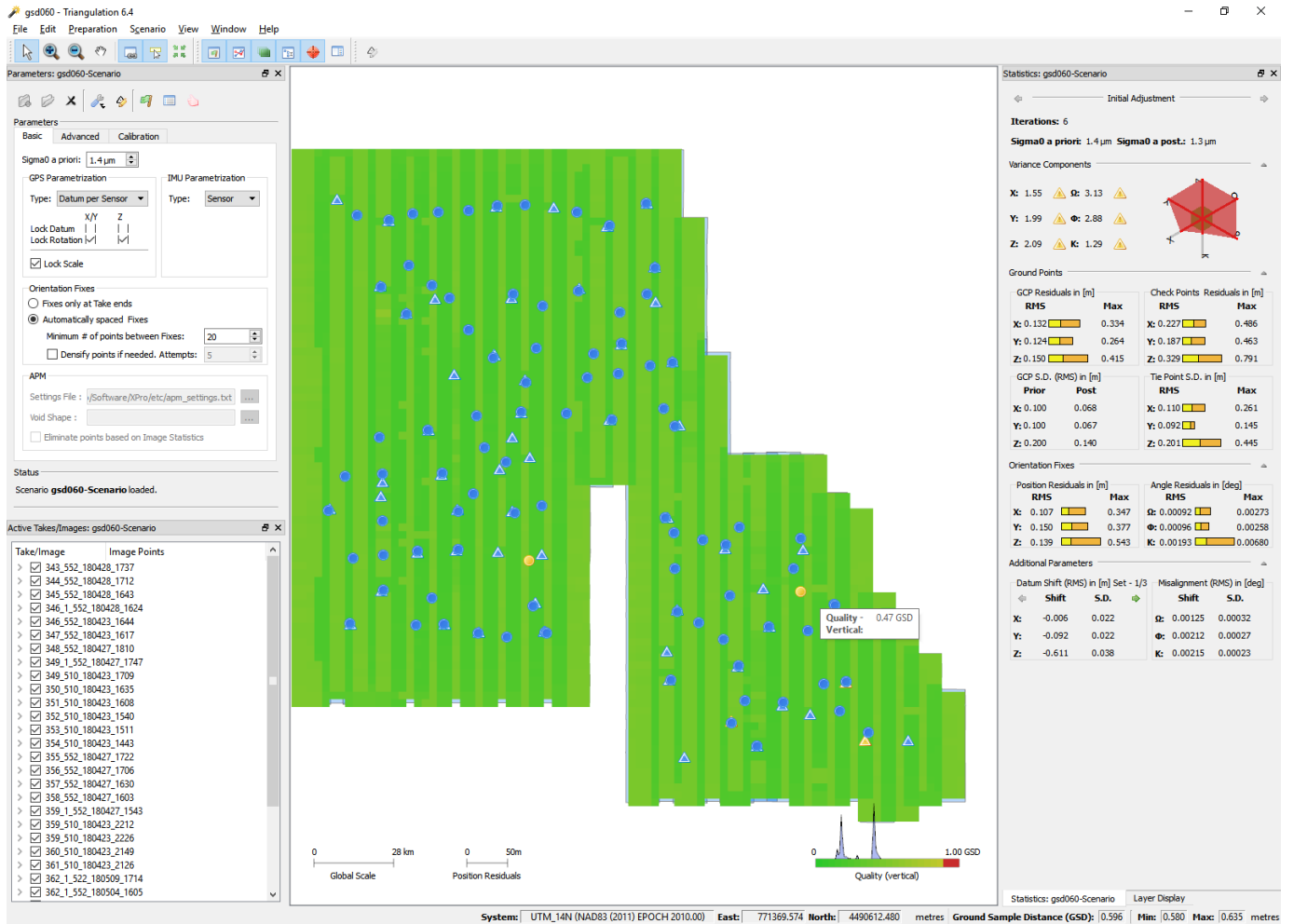
In addition to a textual presentation of the measured points, XPro presents numerous graphical presentations that allow the technicians to refine the triangulation. The graphic below presents several of these graphic displays.

Leica XPro aerial triangulation software interface.



3.1.1 60-cm Final Imagery Aerial Triangulation

The aerial triangulation of this project was completed in one block tied together by ground control points. The graphics below present that block and its corresponding results. The triangulation concept is to assure that the imagery is adjusted to the ground control within the block. By accomplishing this, the final overall aerial triangulation will meet the project accuracy specifications. Block solution results are illustrated below.



The key statistics from the aerial triangulation process are summarized in the Table 2 below. All values are meters.

Table 2
Final Aerial Triangulation Statistics

Block ID	Image Residuals (μm)	RMSE Control Points (m)			RMS GNSS Positions (m)			RMS IMU Attitude (deg)		
		δX	δY	δZ	δX	δY	δZ	$\delta \Omega$	$\delta \Phi$	δK
Main	1.3	0.132	0.124	0.150	0.107	0.150	0.139	0.00092	0.00096	0.00193

The block contained 94 Quality Control (QC) points that were also measured in the triangulation. The fit of these points coming out of the triangulation represent an independent assessment of the triangulation accuracy. Table 3 presents a summary of these QC points residuals after the triangulation process.

Table 3
QC Point Statistical Summary

Statistic	X Residuals (m)	Y-Residuals (m)	Z-Residuals (m)
N	94	94	94
Minimum	-0.47	-0.45	-0.79
Maximum	0.49	0.42	0.78
Average	-0.03	0.02	0.01
Standard Deviation	0.23	0.19	0.33
RMSE	0.23	0.19	0.33

In Table 1 of this report we established the limiting RMSE of the triangulation to meet our mapping standards. Table 4 below presents these requirements again and compares them to the computed accuracy from the aerial triangulation QC points provided in Table 3 above.

Table 4
Triangulation Accuracy Assessment

Component	Specification Limiting RMSE	QC Point RMSE	Status
X	57.5 cm	23 cm	Passed
Y	57.5 cm	19 cm	Passed
Z	115 cm	33 cm	Passed

Based on these limiting values and the observed QC point residuals in the triangulation, it is my assessment that this aerial triangulation meets the accuracy requirements to support further production of digital orthophotography to NSSDA accuracy standards of a 4 meter accuracy at the 95% confidence level.

Respectfully submitted,

Steven M. Kasten



Steven M. Kasten CP, PLS
January 7, 2019

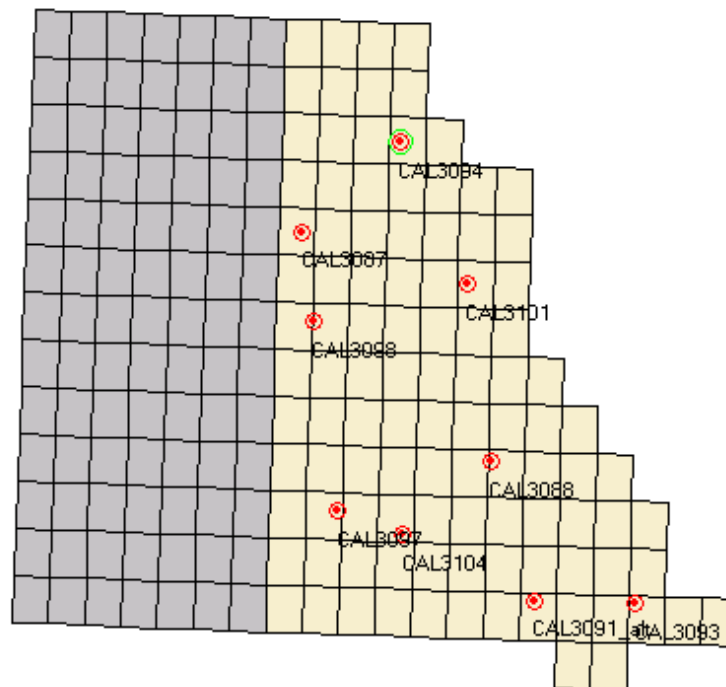
Project Information

Prepared By: JG
Project Name: **Nebraska 60cm**
Sensor Info: **ADS100**
Sensor Resolution: 0.6
Vendor Name: **Merrick-Surdex JV**
Date of Aquisition: Start: 8/6/2018 Finish: 8/6/2018

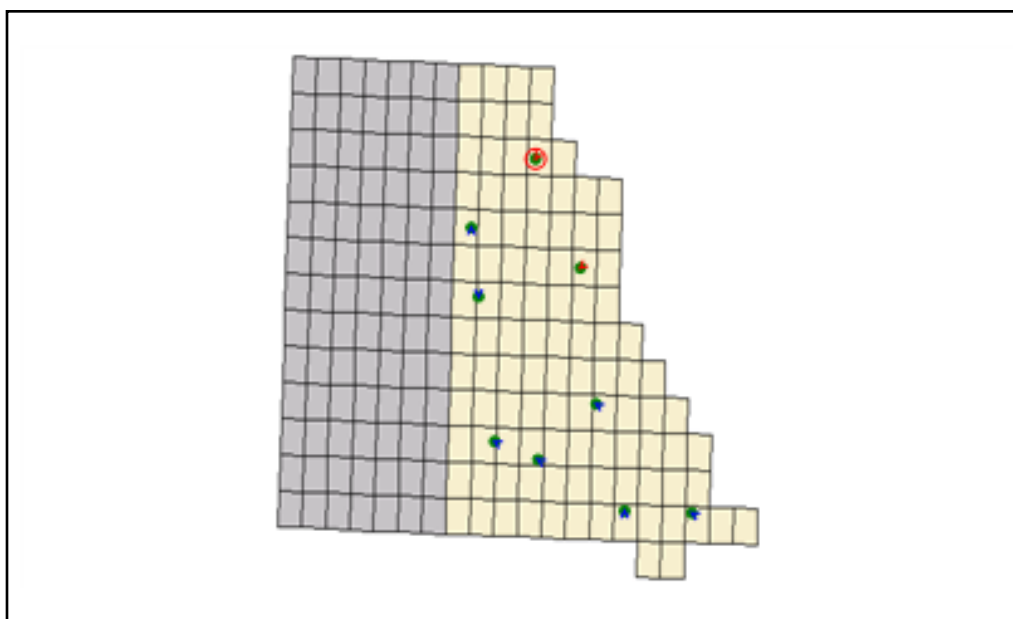
Metadata Information

Index File Name: AA_SHP_tile.shp
of Polygons: 222
of Matching Images: 131
Polygon ID: Name
Units: Meters
Image Folder Path: I:\2800105\product_tiles\Client_SE_UTM15_hr4\Delivery\2018-08-03_112458
Threshold: CE90: 0.349
Scaling Used: 1:800

Tiled-Image Area

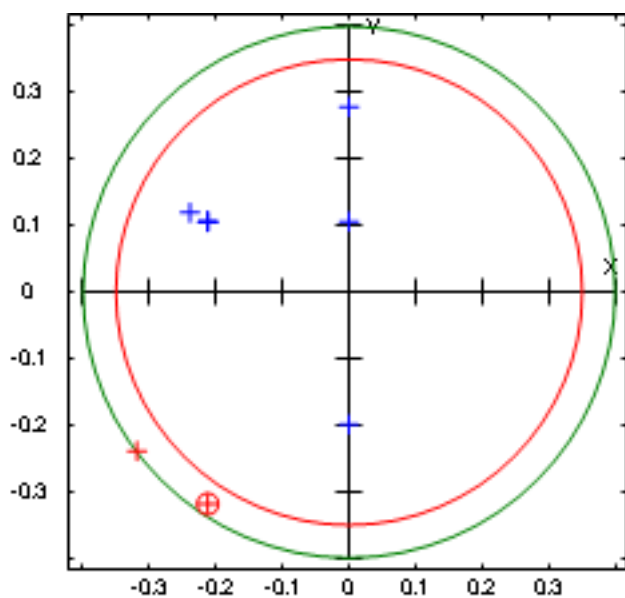


Vector Offset



Scaling Factor: 200

Circular Error



Error Statistics

Min ΔX :	-0.318	CE 95:	0.398
Min ΔY :	-0.318	Skew ΔX :	0.525
Max ΔX :	0	Skew ΔY :	-0.622
Max ΔY :	0.278	Horiz. Bias:	0.156
Mean ΔX :	-0.156	SRMSE H:	0.054
Mean ΔY :	0.007	CI:	0.106
RmseX:	0.193		
RmseY:	0.192		
RmseH:	0.273		
NSSDA:	0.472		
No. Obs.:	9		
SX:	0.122		
SY:	0.204		
SH:	0.163		
CE 90:	0.349		

Coordinates and Offsets of Analyzed Locations

	ID	Survey X	Survey Y	Photo X	Photo Y	ΔX	ΔY
1)	<input checked="" type="checkbox"/> CAL3098						
		245640.85	4477865.01	245640.847	4477864.812	0	-0.198
2)	<input checked="" type="checkbox"/> CAL3101						
		268235.86	4483377.538	268235.541	4483377.3	-0.318	-0.238
3)	<input checked="" type="checkbox"/> CAL3087						
		244029.42	4491123.726	244029.421	4491124.004	0	0.278
4)	<input checked="" type="checkbox"/> CAL3094						
		258320.47	4504308.325	258320.254	4504308.007	-0.212	-0.318
5)	<input checked="" type="checkbox"/> CAL3088						
		271753.22	4457266.815	271753.003	4457266.921	-0.212	0.106
6)	<input checked="" type="checkbox"/> CAL3091_alt						
		278061.36	4436760.551	278061.362	4436760.657	0	0.106
7)	<input checked="" type="checkbox"/> CAL3093						
		293024.25	4436356.333	293024.038	4436356.439	-0.212	0.106
8)	<input checked="" type="checkbox"/> CAL3097						
		249199.77	4450089.697	249199.533	4450089.816	-0.238	0.119
9)	<input checked="" type="checkbox"/> CAL3104						
		258830.48	4446616.447	258830.27	4446616.553	-0.212	0.106

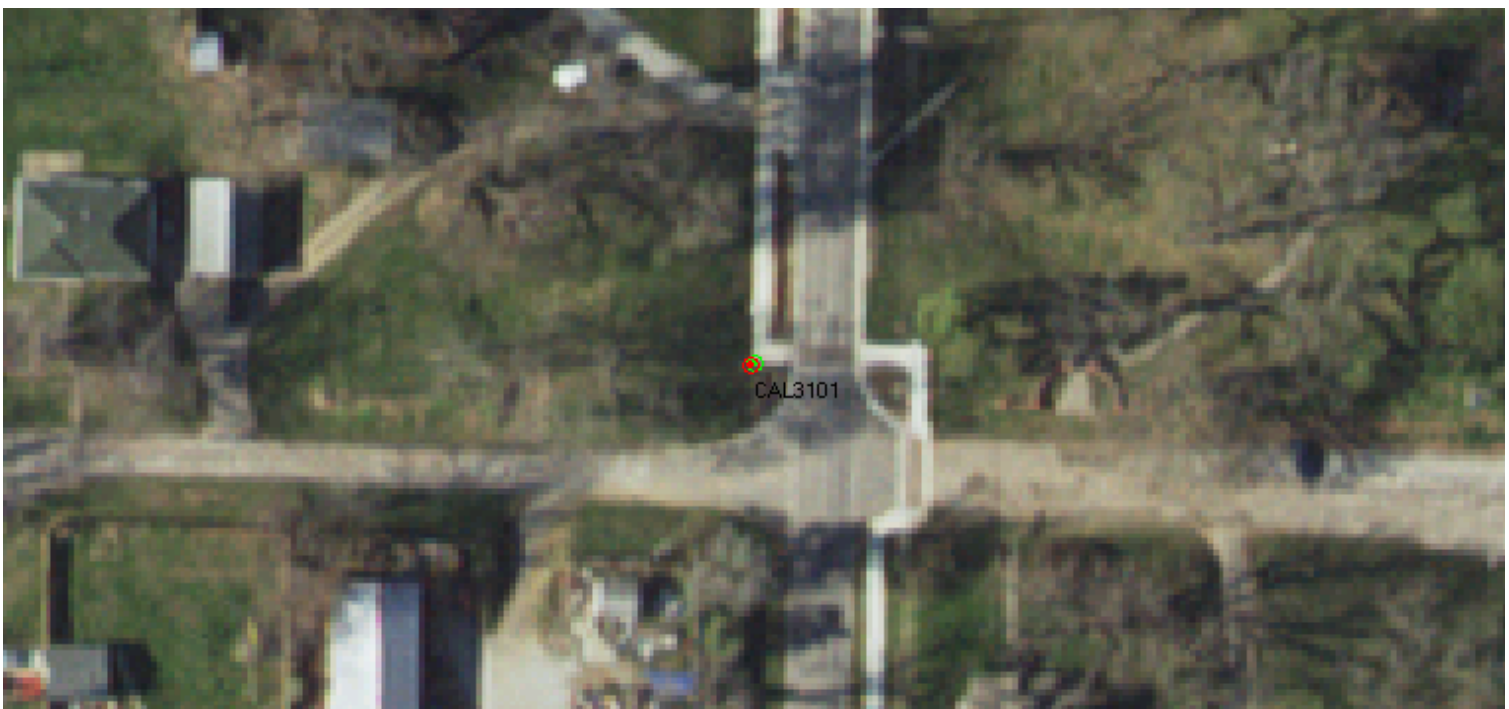
Point CAL3098:

X1: 245640.847 Y1: 4477865.01 X2: 245640.847 Y2: 4477864.812 Delta X: 0 Delta Y: -0.198



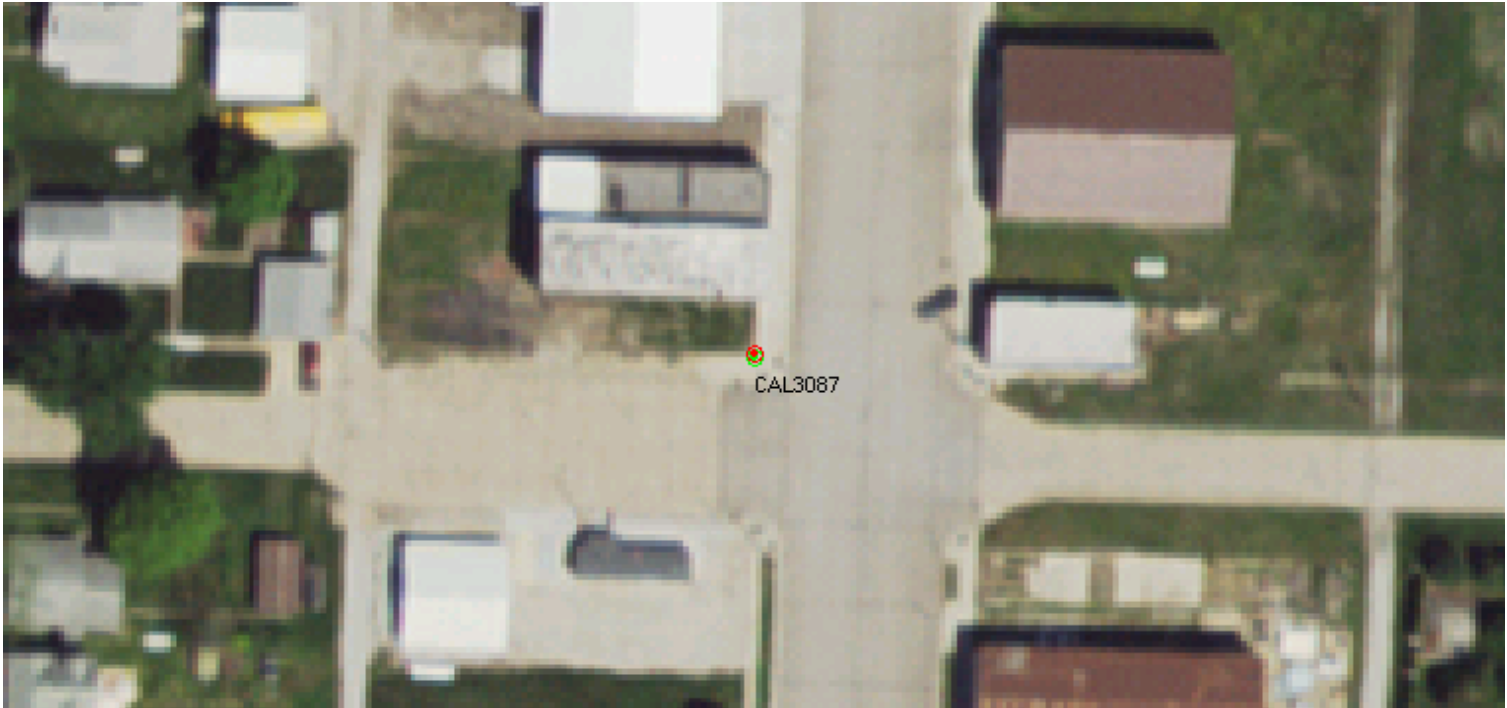
Point CAL3101:

X1: 268235.859 Y1: 4483377.538 X2: 268235.541 Y2: 4483377.3 Delta X: -0.318 Delta Y: -0.238



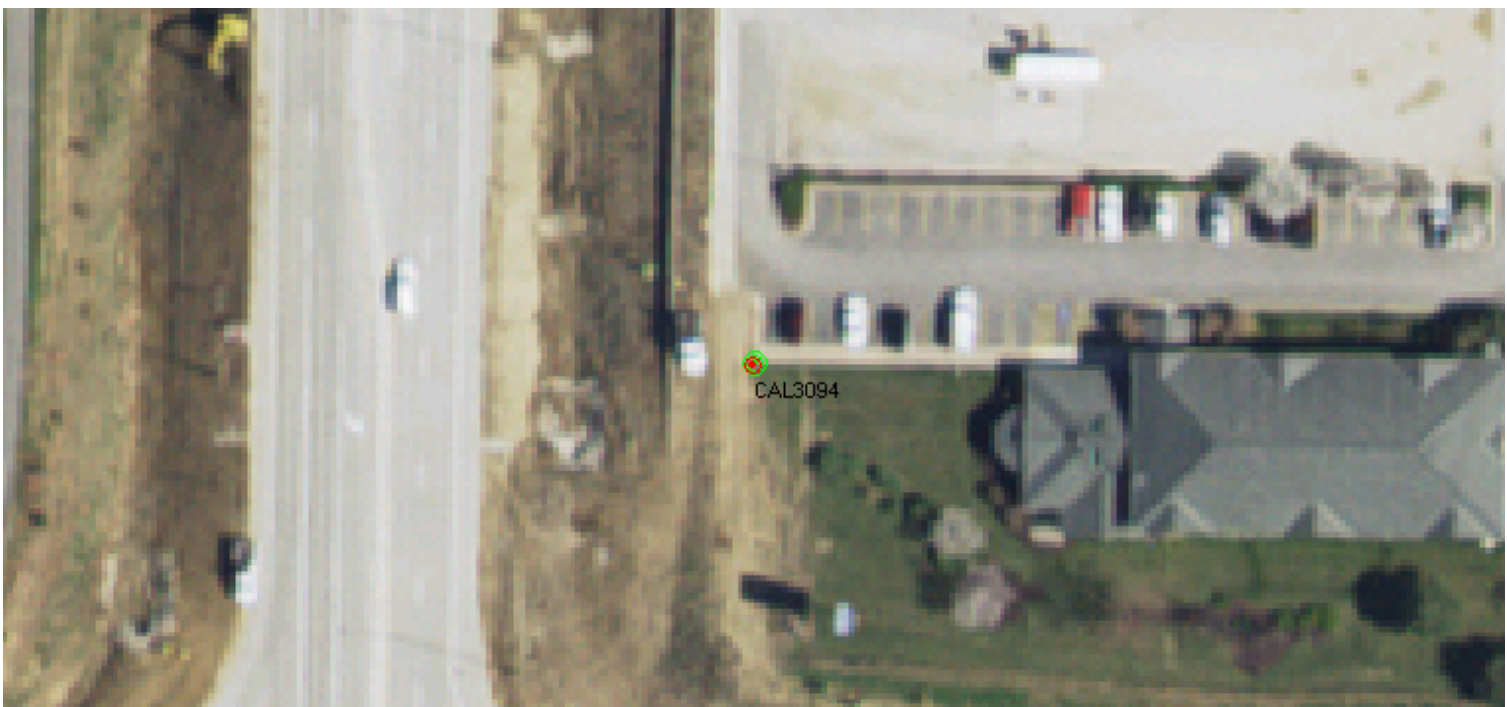
Point CAL3087:

X1: 244029.421 Y1: 4491123.726 X2: 244029.421 Y2: 4491124.004 Delta X: 0 Delta Y: 0.278



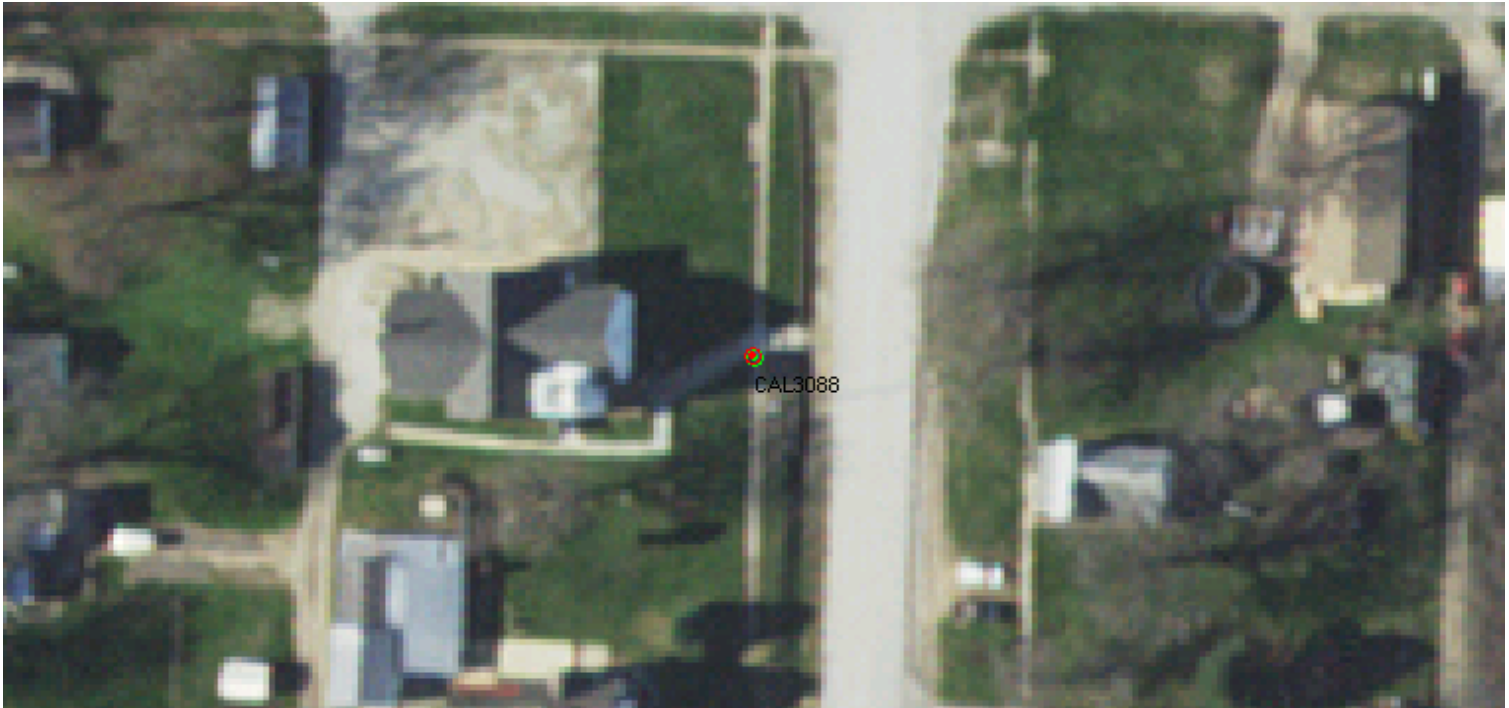
Point CAL3094:

X1: 258320.466 Y1: 4504308.325 X2: 258320.254 Y2: 4504308.007 Delta X: -0.212 Delta Y: -0.318



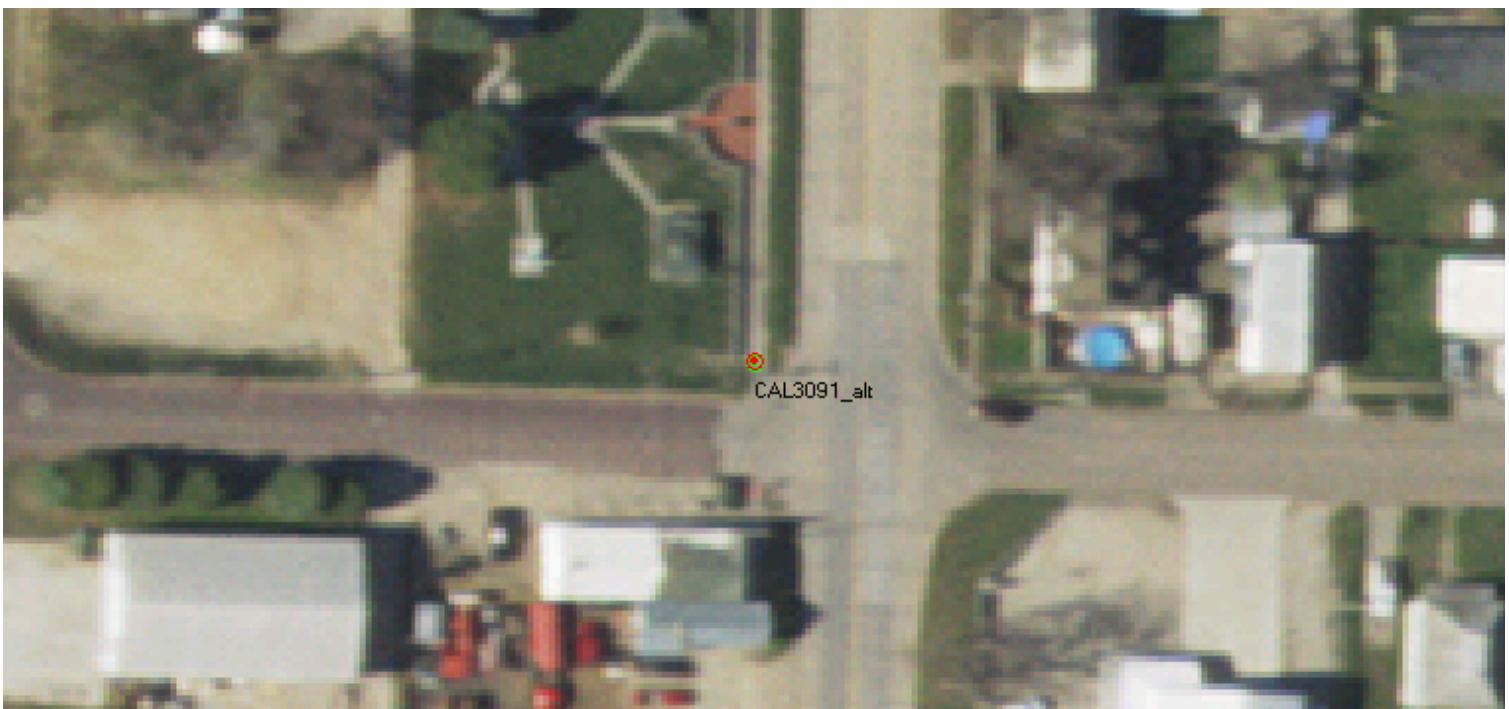
Point CAL3088:

X1: 271753.215 Y1: 4457266.815 X2: 271753.003 Y2: 4457266.921 Delta X: -0.212 Delta Y: 0.106



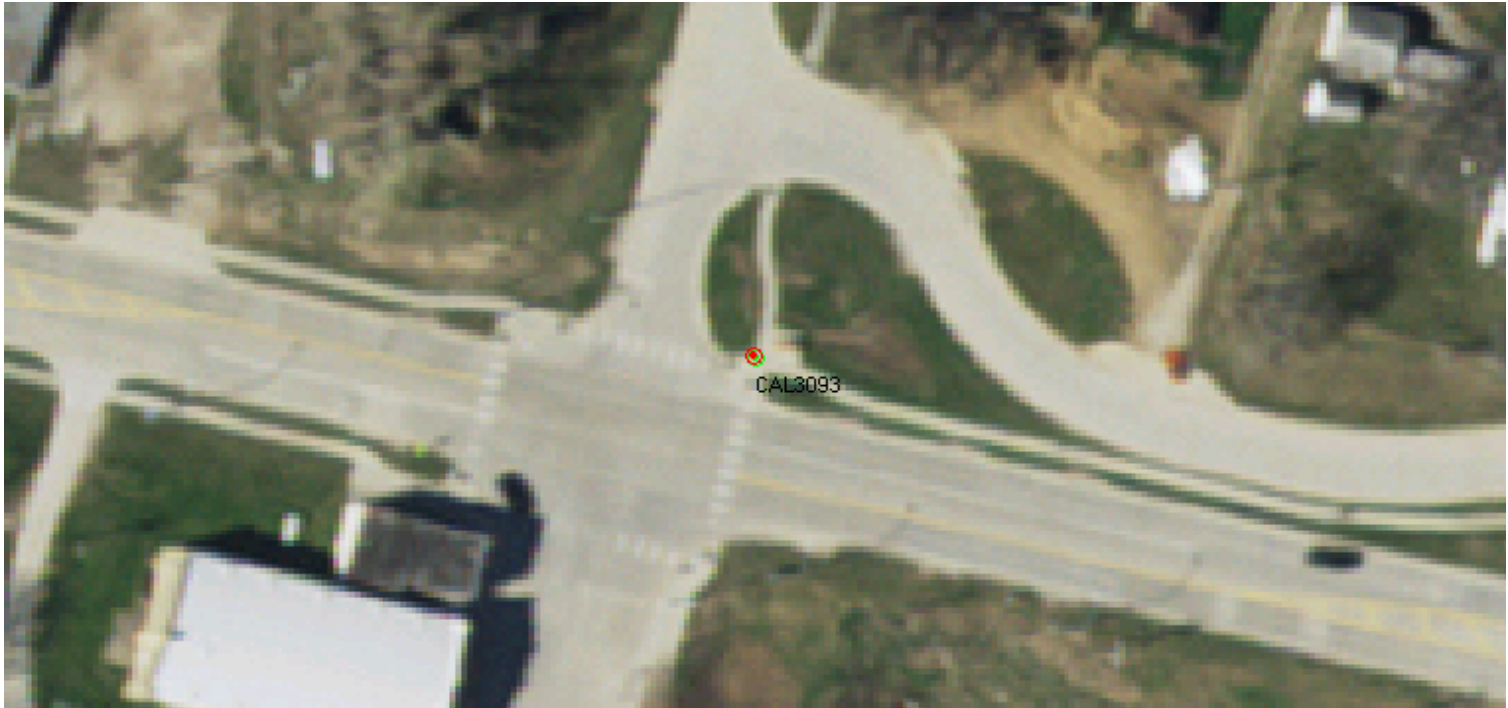
Point CAL3091_ult:

X1: 278061.362 Y1: 4436760.551 X2: 278061.362 Y2: 4436760.657 Delta X: 0 Delta Y: 0.106



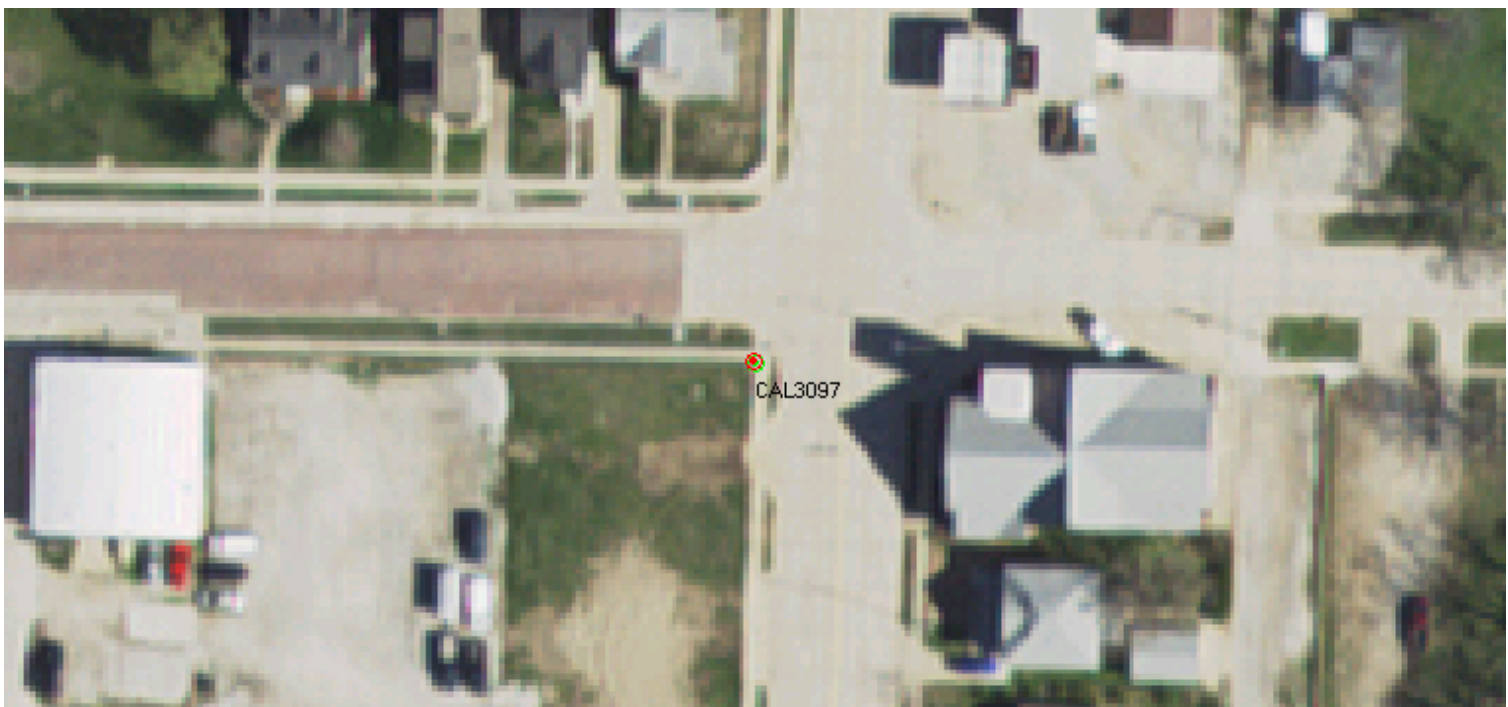
Point CAL3093:

X1: 293024.25 Y1: 4436356.333 X2: 293024.038 Y2: 4436356.439 Delta X: -0.212 Delta Y: 0.106



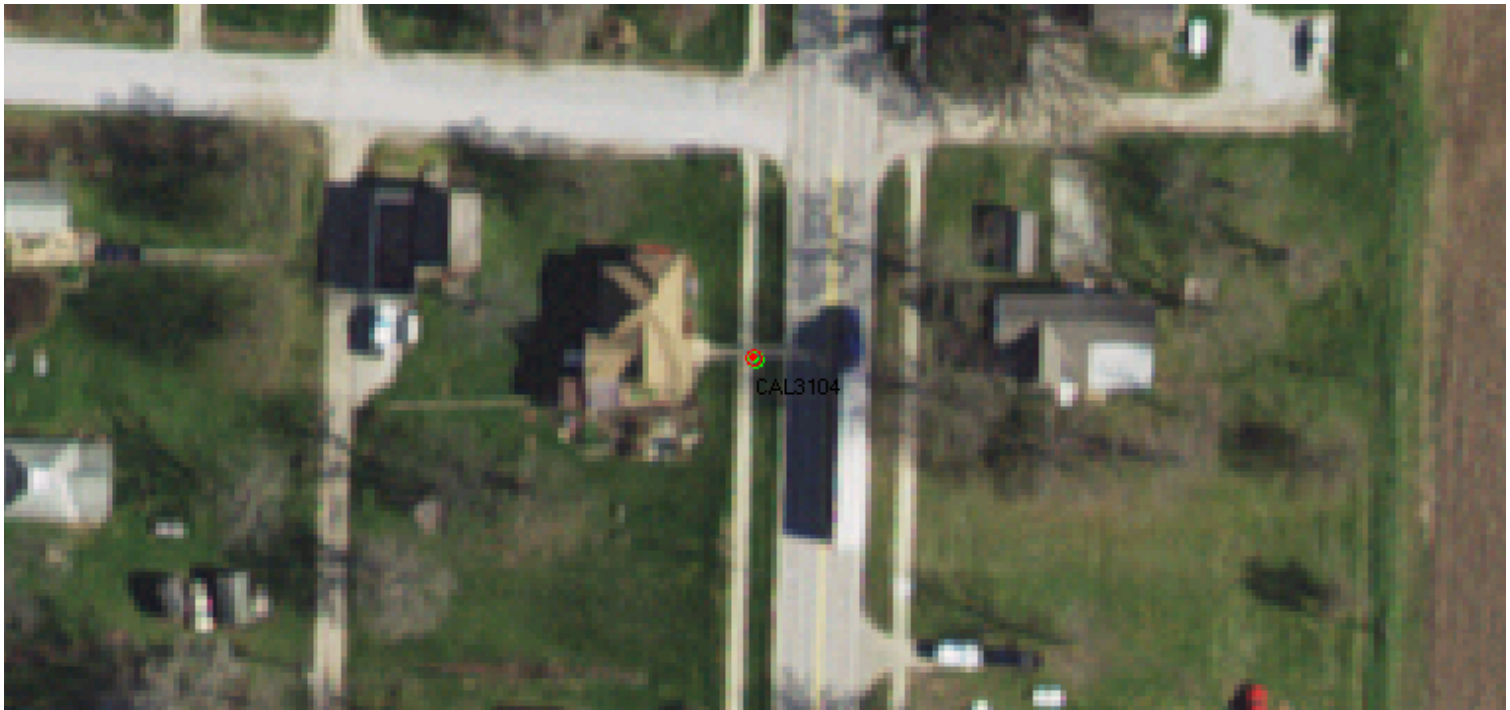
Point CAL3097:

X1: 249199.771 Y1: 4450089.697 X2: 249199.533 Y2: 4450089.816 Delta X: -0.238 Delta Y: 0.119



Point CAL3104:

X1: 258830.482 Y1: 4446616.447 X2: 258830.27 Y2: 4446616.553 Delta X: -0.212 Delta Y: 0.106

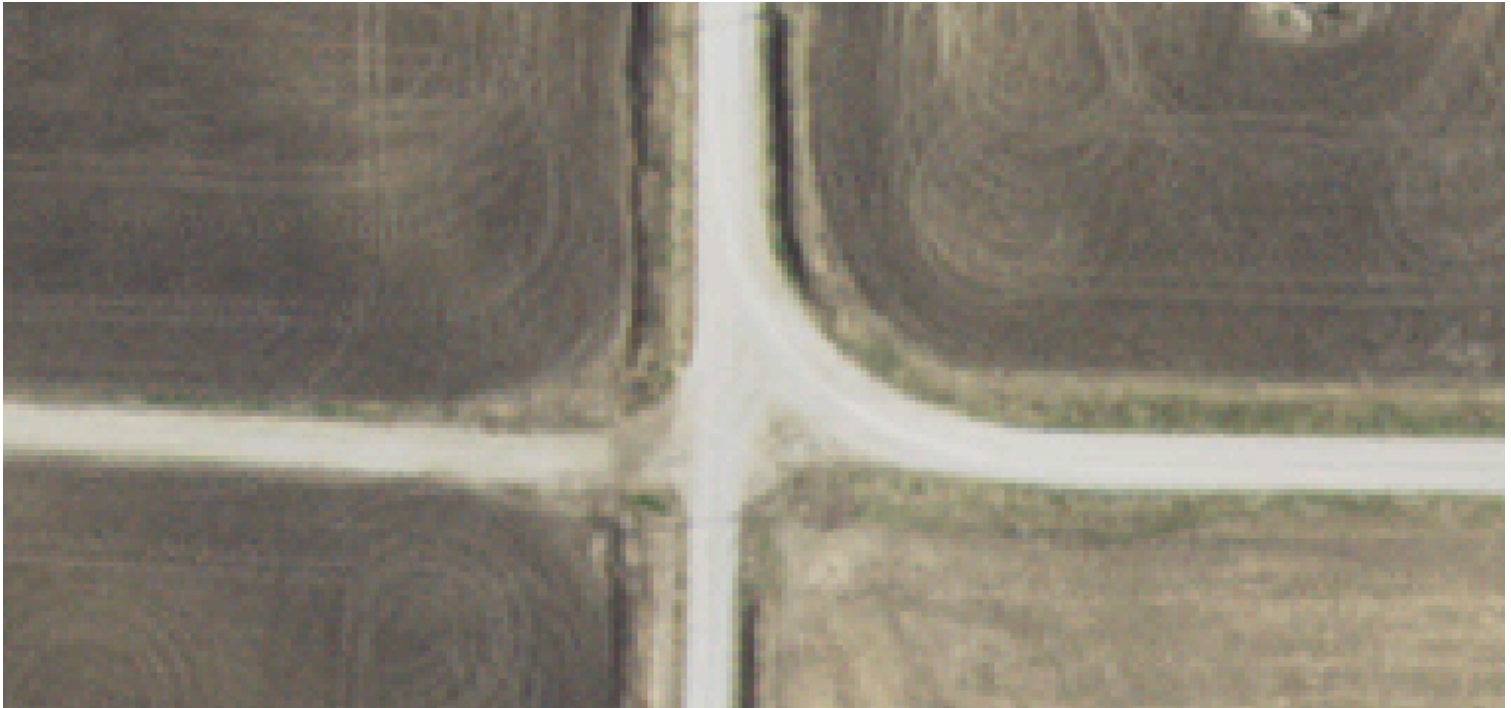


Coordinates and Offsets of Unanalyzed Locations

ID				
		Survey X	Survey Y	Reason For Exclusion
1)	<input type="checkbox"/> CAL3113			
		273131.346	4490116.178	Ambigious Location
2)	<input type="checkbox"/> CAL3103			
		254261.71	4517266.11	
3)	<input type="checkbox"/> CAL3105			
		246051.673	4512727.997	Ambigious Location
4)	<input type="checkbox"/> CAL3090			
		275624.765	4447237.837	Ambigious Location
5)	<input type="checkbox"/> CAL3091			
		278036.156	4436781.307	Obscure Location
6)	<input type="checkbox"/> CAL3106			
		283262.665	4455134.453	Obscure Location

Point CAL3113:

X1: 273131.346 Y1: 4490116.178 Reason For Exclusion: Ambiguous Location



Point CAL3103:

X1: 254261.71 Y1: 4517266.11 Reason For Exclusion:



Point CAL3105:

X1: 246051.673 Y1: 4512727.997 Reason For Exclusion: Ambiguous Location



Point CAL3090:

X1: 275624.765 Y1: 4447237.837 Reason For Exclusion: Ambiguous Location



Point CAL3091:

X1: 278036.156 Y1: 4436781.307 Reason For Exclusion: Obscure Location



Point CAL3106:

X1: 283262.665 Y1: 4455134.453 Reason For Exclusion: Obscure Location



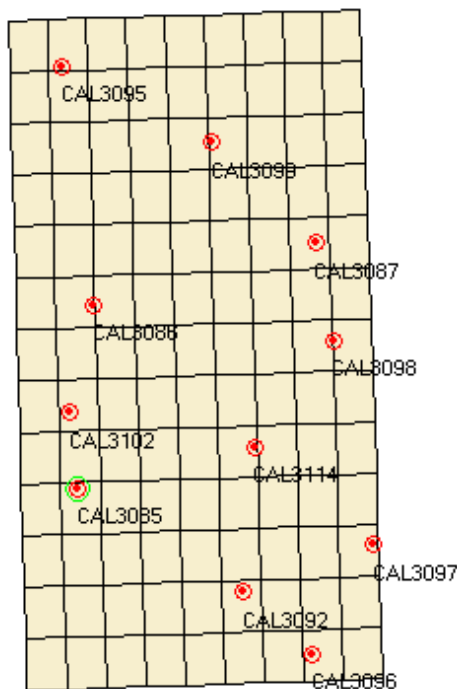
Project Information

Prepared By: JG
Project Name: **Nebraska 60cm**
Sensor Info: **ADS100**
Sensor Resolution: 0.6
Vendor Name: **Merrick-Surdex JV**
Date of Aquisition: Start: 8/6/2018 Finish: 8/6/2018

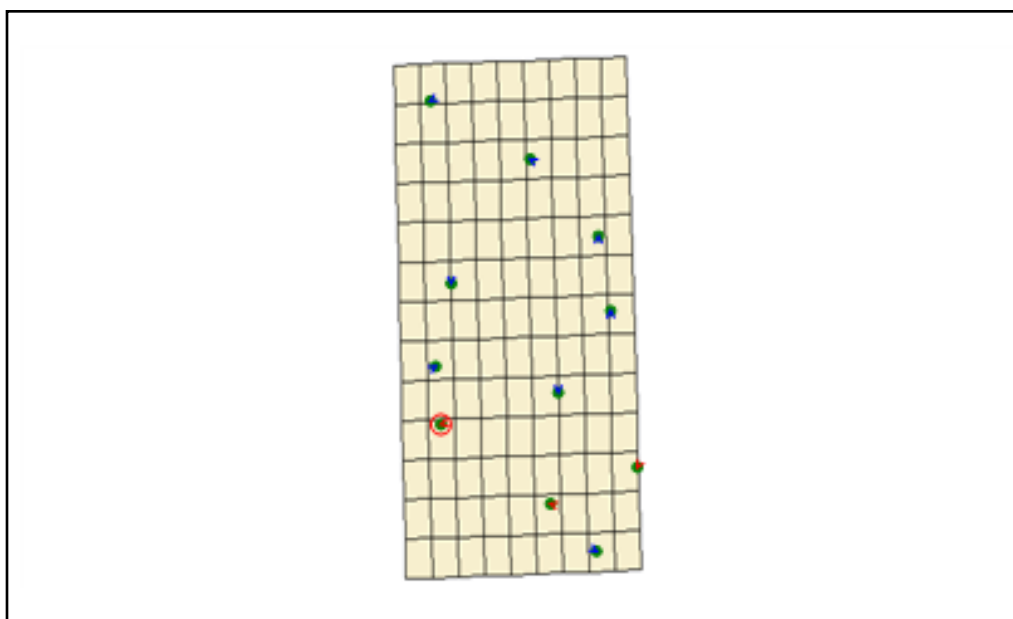
Metadata Information

Index File Name: SE_Block_doqqqs_UTM14.shp
of Polygons: 117
of Matching Images: 117
Polygon ID: Name
Units: Meters
Image Folder Path: I:\2800105\product_tiles\Client_SE_UTM14_hr4\Delivery\2018-08-03_112441
Threshold: CE90: 0.427
Scaling Used: 1:900

Tiled-Image Area

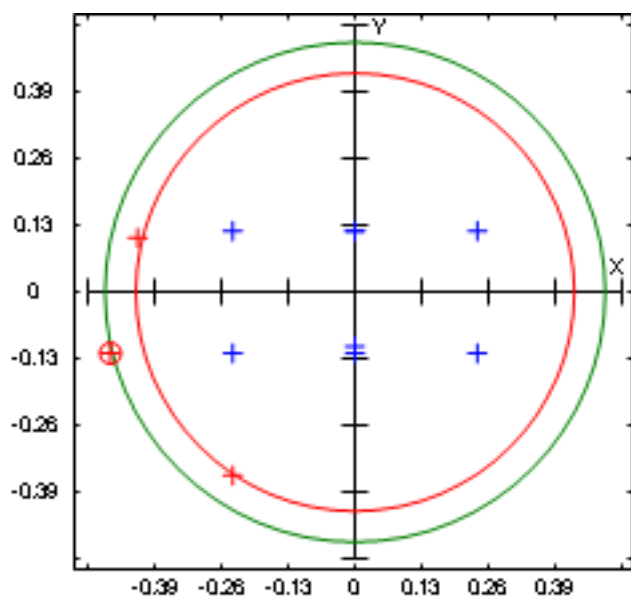


Vector Offset



Scaling Factor: 200

Circular Error



Error Statistics

Min ΔX :	-0.476	CE 95:	0.487
Min ΔY :	-0.357	Skew ΔX :	-0.069
Max ΔX :	0.238	Skew ΔY :	-0.632
Max ΔY :	0.119	Horiz. Bias:	0.108
Mean ΔX :	-0.103	SRMSE H:	0.06
Mean ΔY :	-0.032	CI:	0.118
RmseX:	0.25		
RmseY:	0.155		
RmseH:	0.294		
NSSDA:	0.509		
No. Obs.:	11		
SX:	0.239		
SY:	0.159		
SH:	0.199		
CE 90:	0.427		

Coordinates and Offsets of Analyzed Locations

	ID						
		Survey X	Survey Y	Photo X	Photo Y	ΔX	ΔY
1)	<input checked="" type="checkbox"/> CAL3086						
		722338.72	4482676.762	722338.717	4482676.656	0	-0.106
2)	<input checked="" type="checkbox"/> CAL3102						
		719158.68	4468119.691	719158.916	4468119.81	0.238	0.119
3)	<input checked="" type="checkbox"/> CAL3114						
		744079.73	4463539.449	744079.729	4463539.33	0	-0.119
4)	<input checked="" type="checkbox"/> CAL3098						
		754741.01	4477877.984	754741.01	4477878.103	0	0.119
5)	<input checked="" type="checkbox"/> CAL3087						
		752232.34	4490996.408	752232.338	4490996.527	0	0.119
6)	<input checked="" type="checkbox"/> CAL3095						
		718103.42	4514727.992	718103.177	4514727.873	-0.238	-0.119
7)	<input checked="" type="checkbox"/> CAL3099						
		738395.32	4504515.557	738395.079	4504515.676	-0.238	0.119
8)	<input checked="" type="checkbox"/> CAL3085						
		720231.64	4457919.89	720231.163	4457919.771	-0.476	-0.119
9)	<input checked="" type="checkbox"/> CAL3092						
		742523.22	4444000.589	742522.799	4444000.695	-0.423	0.106
10)	<input checked="" type="checkbox"/> CAL3096						
		751876.59	4435650.717	751876.823	4435650.598	0.238	-0.119

	ID						
		Survey X	Survey Y	Photo X	Photo Y	ΔX	ΔY
11)	<input checked="" type="checkbox"/>	CAL3097					
		760172.317	4450406.491	760172.079	4450406.134	-0.238	-0.357

Point CAL3086:

X1: 722338.717 Y1: 4482676.762 X2: 722338.717 Y2: 4482676.656 Delta X: 0 Delta Y: -0.106



Point CAL3102:

X1: 719158.678 Y1: 4468119.691 X2: 719158.916 Y2: 4468119.81 Delta X: 0.238 Delta Y: 0.119



Point CAL3114:

X1: 744079.729 Y1: 4463539.449 X2: 744079.729 Y2: 4463539.33 Delta X: 0 Delta Y: -0.119



Point CAL3098:

X1: 754741.01 Y1: 4477877.984 X2: 754741.01 Y2: 4477878.103 Delta X: 0 Delta Y: 0.119



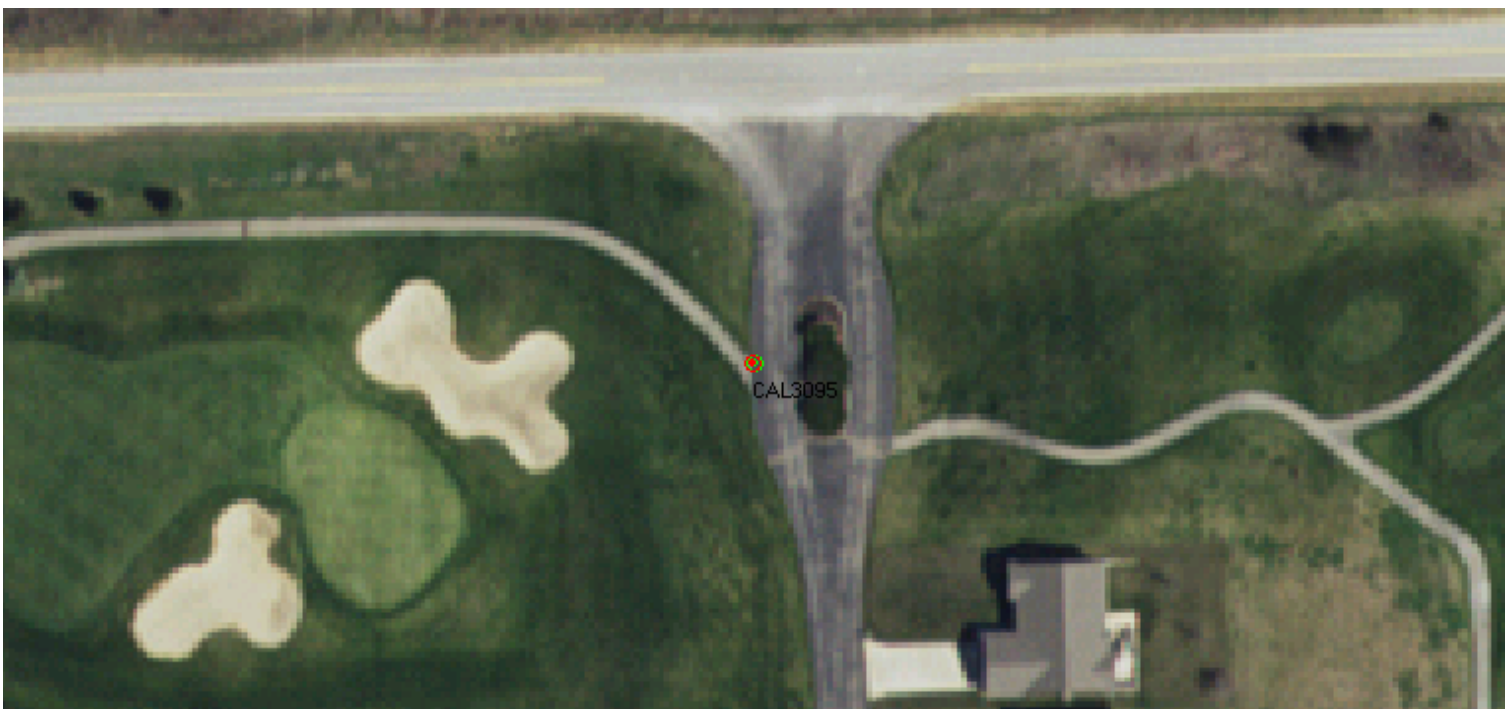
Point CAL3087:

X1: 752232.338 Y1: 4490996.408 X2: 752232.338 Y2: 4490996.527 Delta X: 0 Delta Y: 0.119



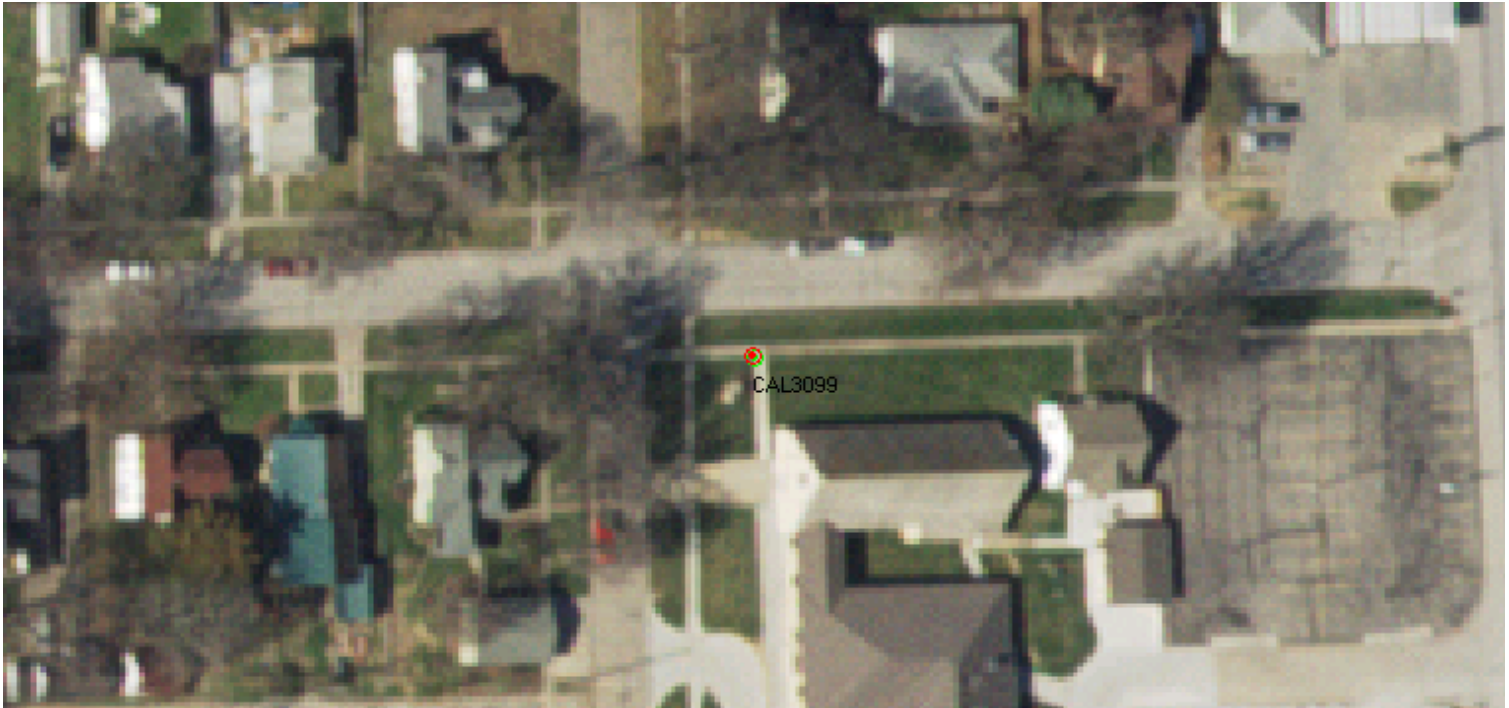
Point CAL3095:

X1: 718103.415 Y1: 4514727.992 X2: 718103.177 Y2: 4514727.873 Delta X: -0.238 Delta Y: -0.119



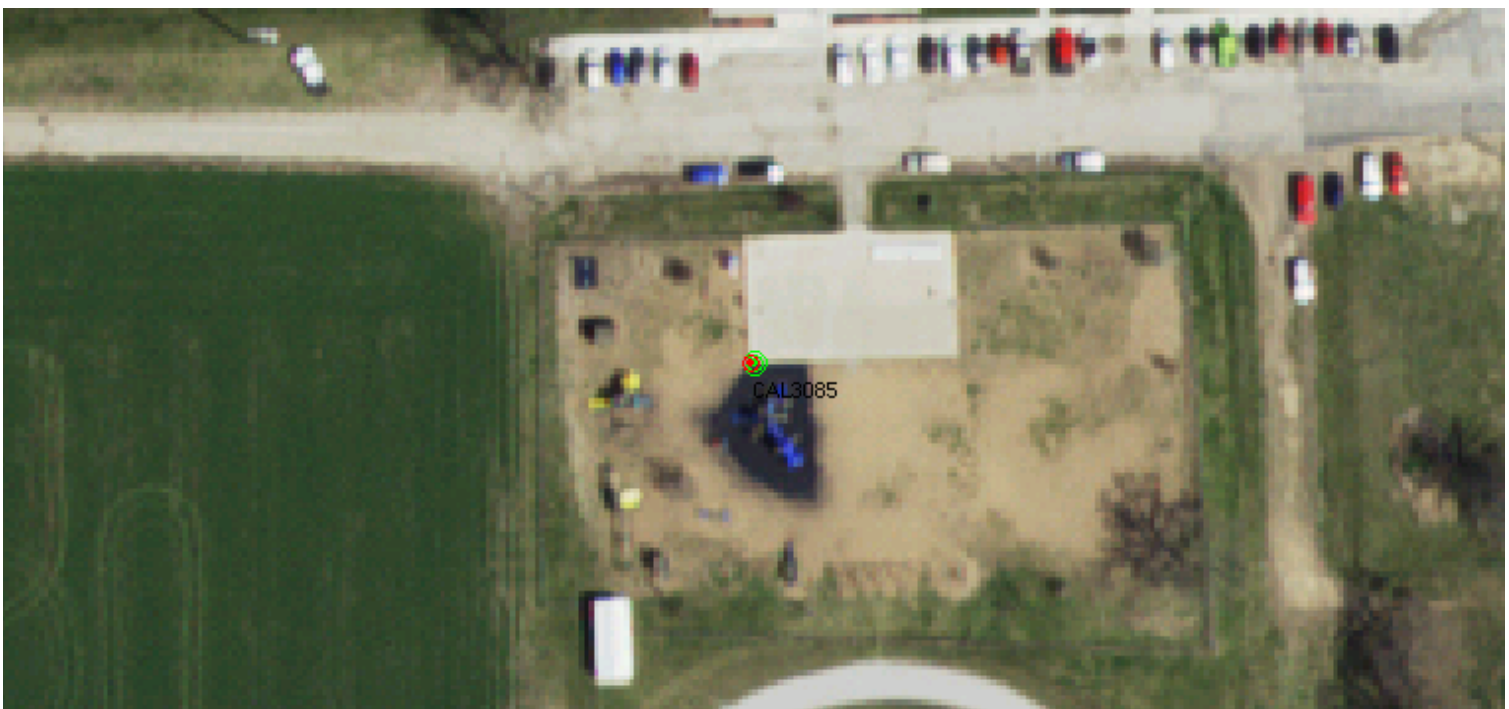
Point CAL3099:

X1: 738395.317 Y1: 4504515.557 X2: 738395.079 Y2: 4504515.676 Delta X: -0.238 Delta Y: 0.119



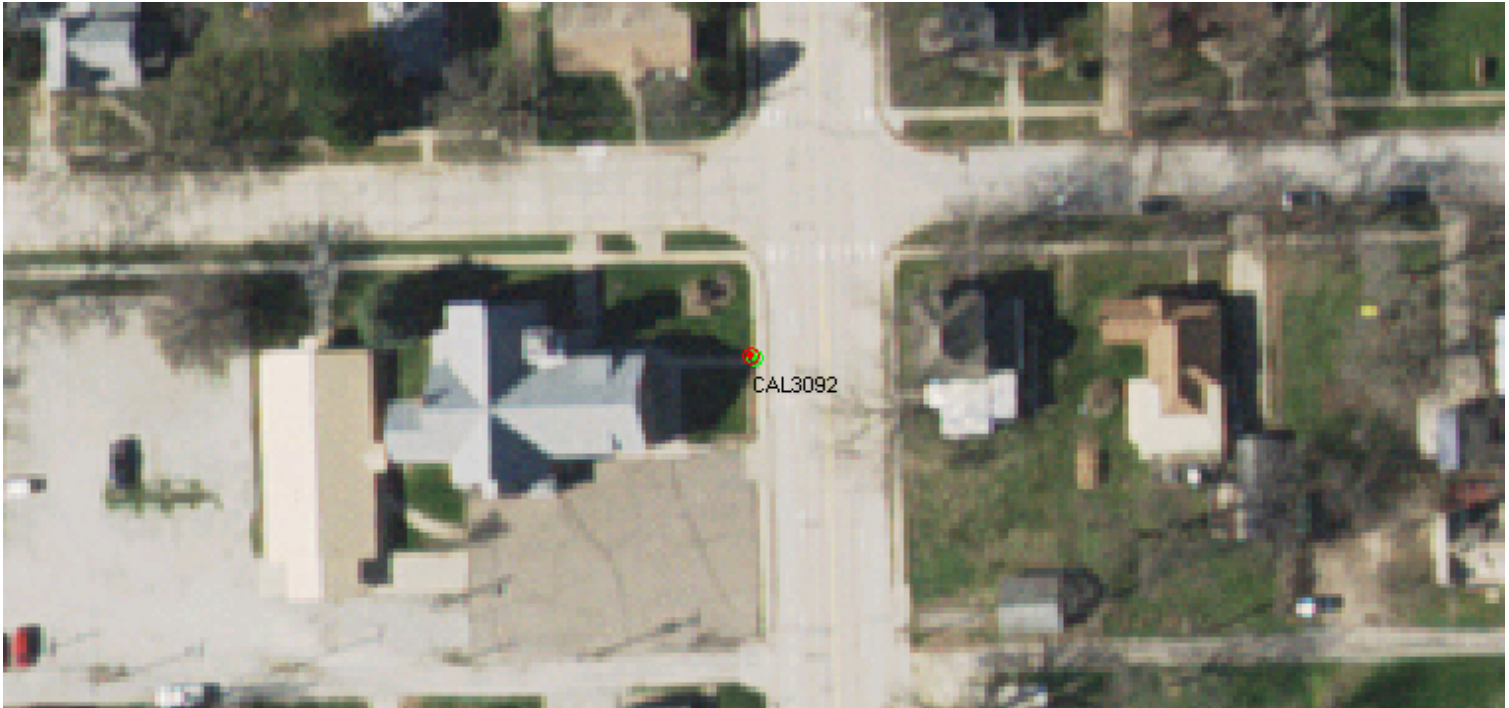
Point CAL3085:

X1: 720231.639 Y1: 4457919.89 X2: 720231.163 Y2: 4457919.771 Delta X: -0.476 Delta Y: -0.119



Point CAL3092:

X1: 742523.222 Y1: 4444000.589 X2: 742522.799 Y2: 4444000.695 Delta X: -0.423 Delta Y: 0.106



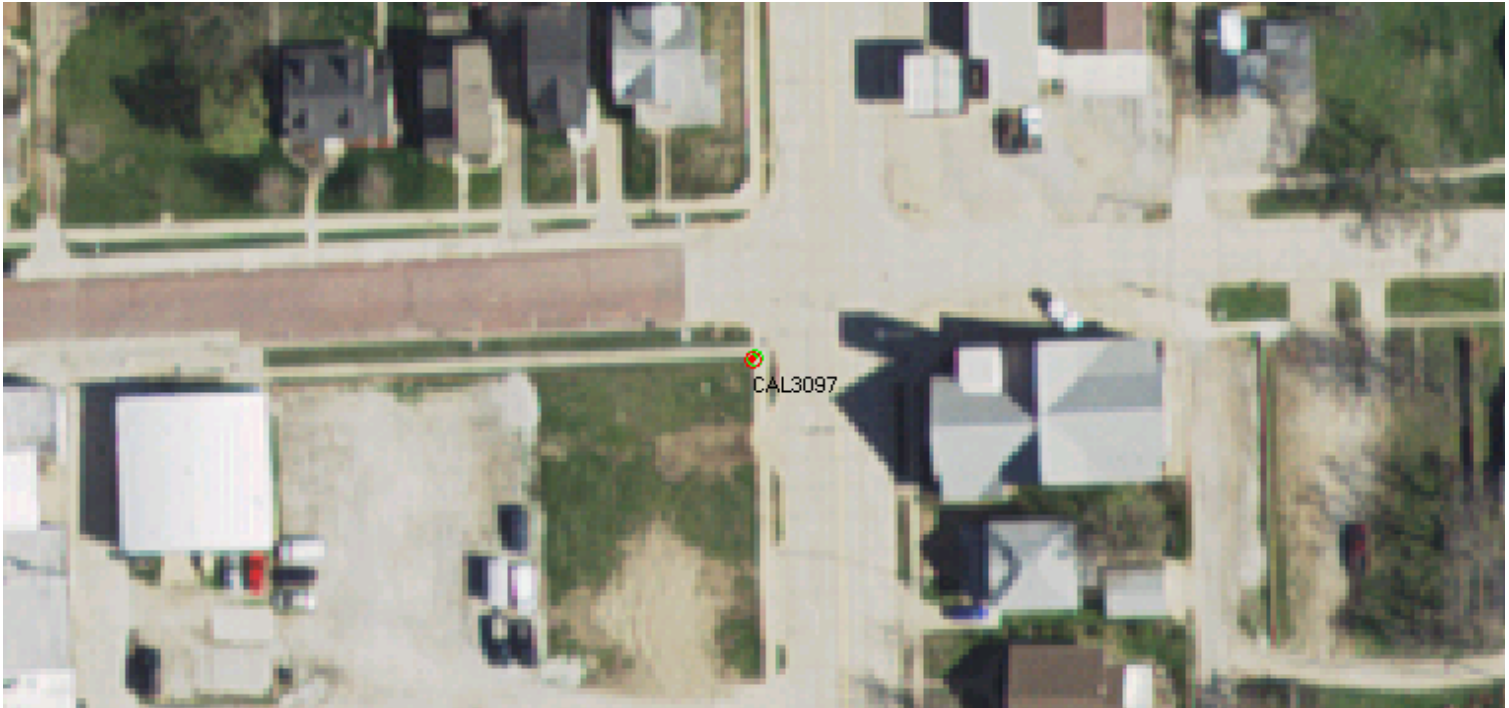
Point CAL3096:

X1: 751876.585 Y1: 4435650.717 X2: 751876.823 Y2: 4435650.598 Delta X: 0.238 Delta Y: -0.119



Point CAL3097:

X1: 760172.317 Y1: 4450406.491 X2: 760172.079 Y2: 4450406.134 Delta X: -0.238 Delta Y: -0.357

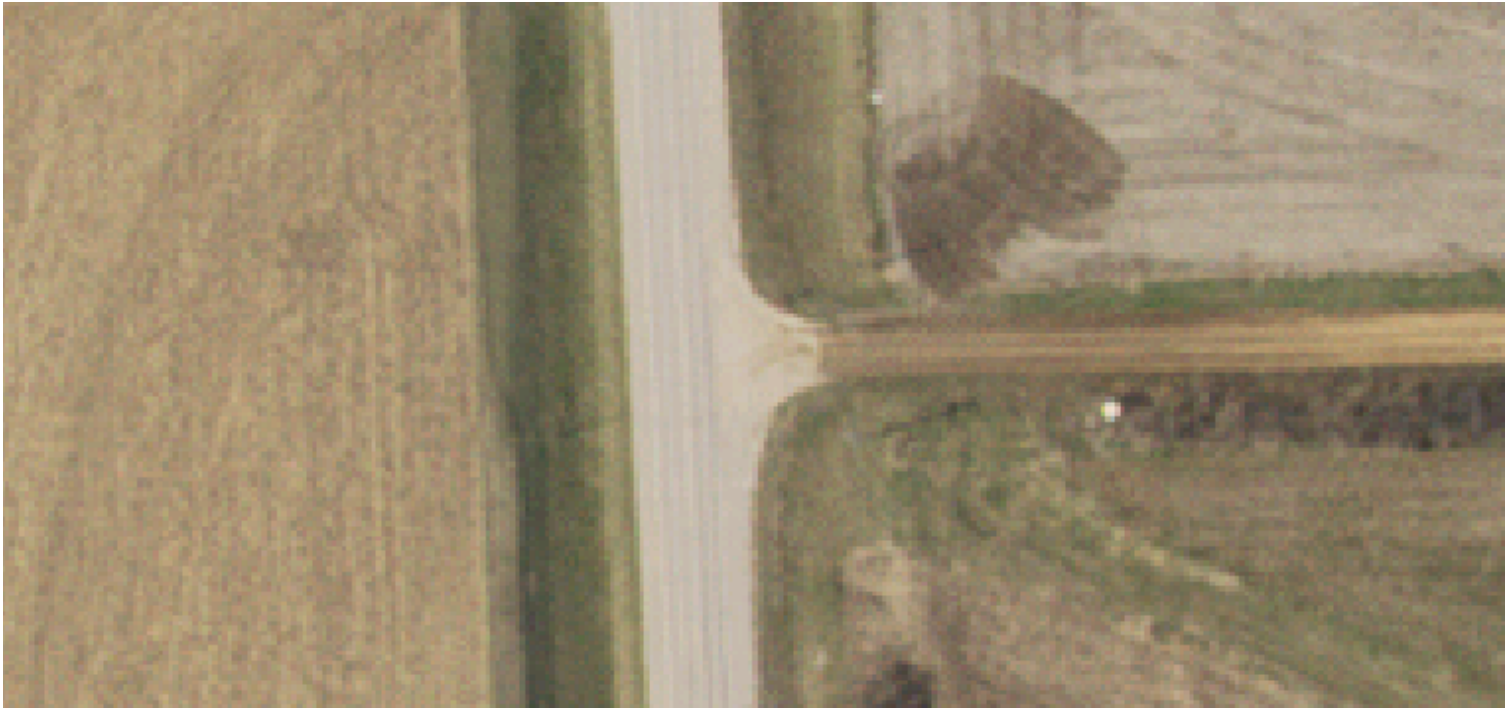


Coordinates and Offsets of Unanalyzed Locations

		ID		
		Survey X	Survey Y	Reason For Exclusion
1)	<input type="checkbox"/> CAL3100			
		738178.864	4515804.218	Ambigious Location
2)	<input type="checkbox"/> CAL3105			
		752777.065	4512687.947	Ambigious Location
3)	<input type="checkbox"/> CAL3112			
		729278.003	4489318.046	Ambigious Location
4)	<input type="checkbox"/> CAL3107			
		719565.347	4435887.619	Ambigious Location

Point CAL3100:

X1: 738178.864 Y1: 4515804.218 Reason For Exclusion: Ambiguous Location



Point CAL3105:

X1: 752777.065 Y1: 4512687.947 Reason For Exclusion: Ambiguous Location



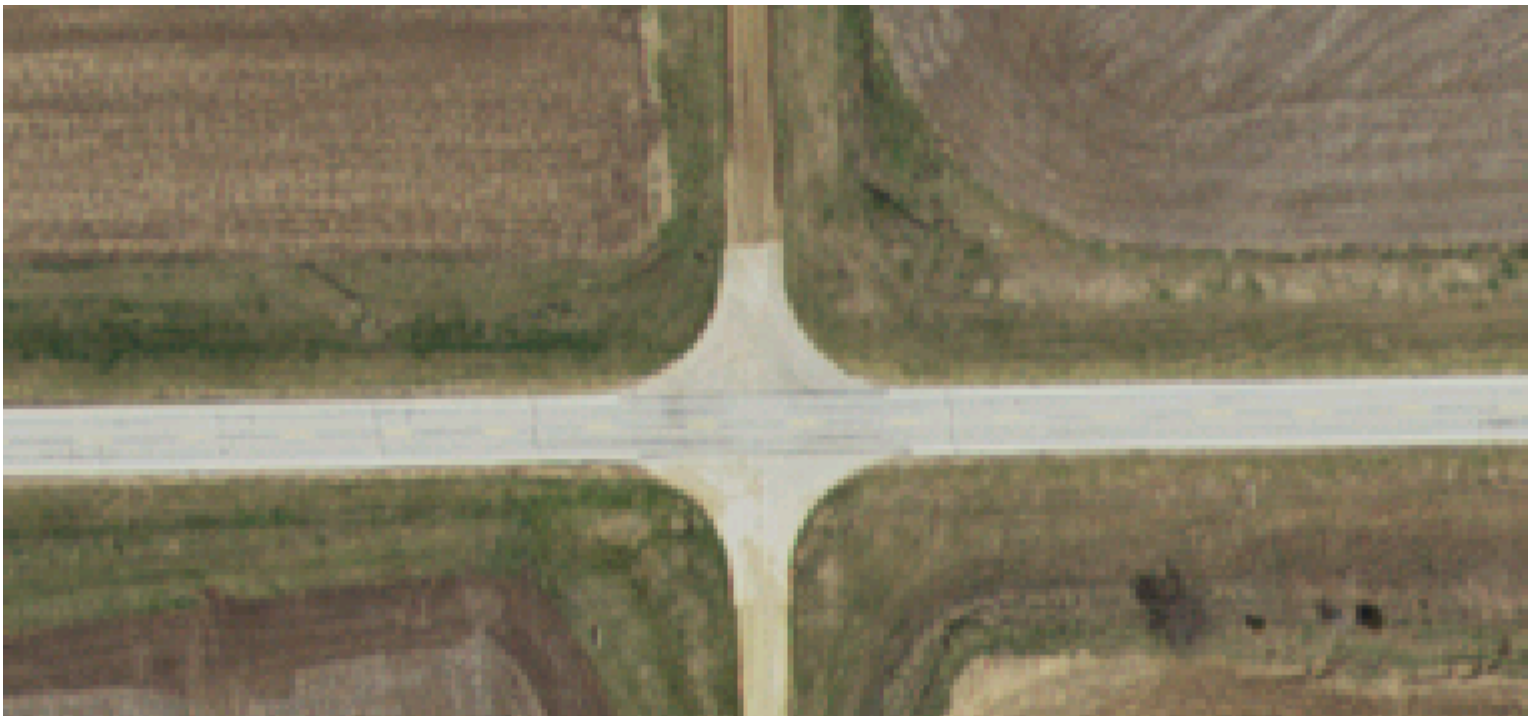
Point CAL3112:

X1: 729278.003 Y1: 4489318.046 Reason For Exclusion: Ambiguous Location



Point CAL3107:

X1: 719565.347 Y1: 4435887.619 Reason For Exclusion: Ambiguous Location



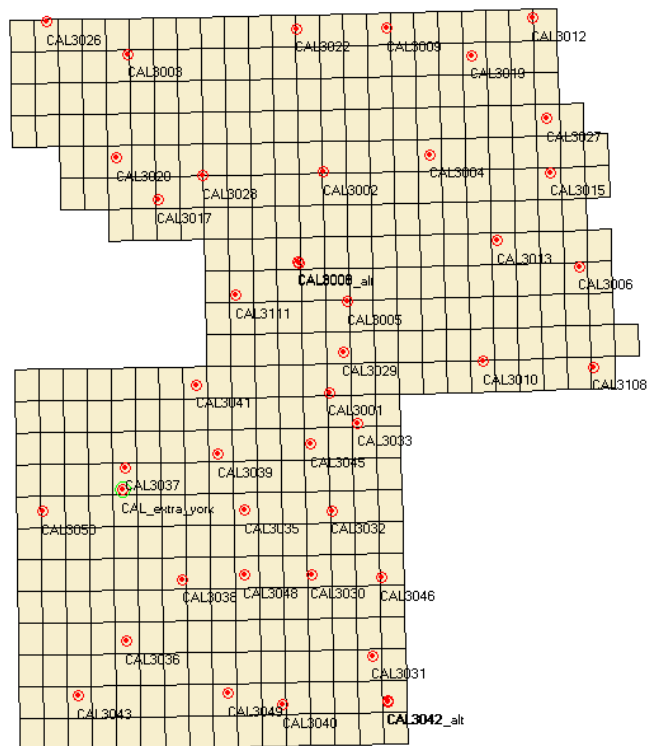
Project Information

Prepared By: JG
Project Name: Nebraska 60cm Block 3 and 4
Sensor Info: ADS100
Sensor Resolution: 0.6
Vendor Name: **Merrick-Surdex JV**
Date of Aquisition: Start: 12/7/2018 Finish: 12/7/2018

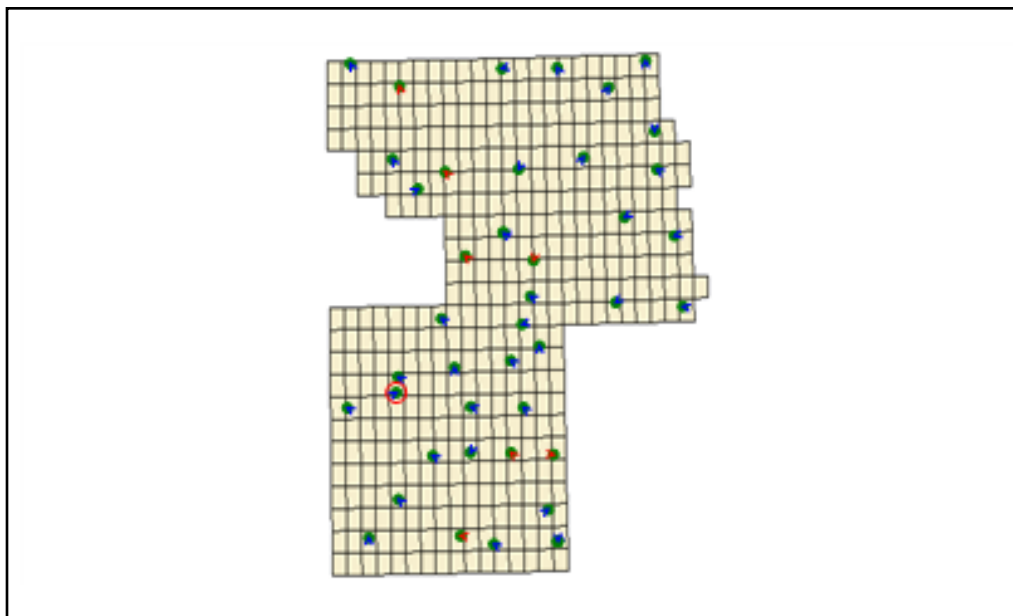
Metadata Information

Index File Name: Blk3_4_UTM14_AA.shp
of Polygons: 429
of Matching Images: 429
Polygon ID: Name
Units: Meters
Image Folder Path: I:\2800105\product_tiles\Client_NW_UTM14_hr4\Delivery\2018-11-26_101001
Threshold: CE90: 0.385
Scaling Used: 1:650

Tiled-Image Area

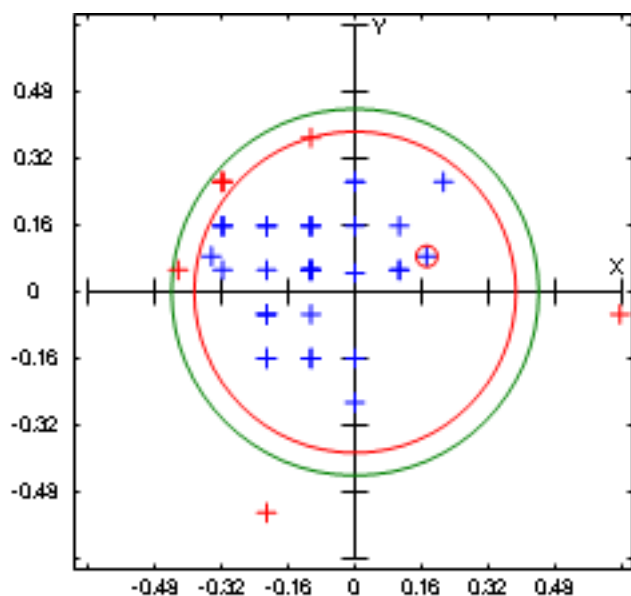


Vector Offset



Scaling Factor: 200

Circular Error



Error Statistics

Min ΔX :	-0.423	CE 95:	0.44
Min ΔY :	-0.529	Skew ΔX :	1.557
Max ΔX :	0.635	Skew ΔY :	-1.059
Max ΔY :	0.37	Horiz. Bias:	0.132
Mean ΔX :	-0.117	SRMSE H:	0.027
Mean ΔY :	0.06	CI:	0.054
RmseX:	0.221		
RmseY:	0.178		
RmseH:	0.284		
NSSDA:	0.491		
No. Obs.:	43		
SX:	0.189		
SY:	0.17		
SH:	0.18		
CE 90:	0.385		

Coordinates and Offsets of Analyzed Locations

	ID	Survey X	Survey Y	Photo X	Photo Y	ΔX	ΔY
1)	<input checked="" type="checkbox"/> CAL3005						
		667416.8	4561114.577	667416.589	4561114.048	-0.212	-0.529
2)	<input checked="" type="checkbox"/> CAL3008						
		656594.84	4569821.799	656594.494	4569821.885	-0.344	0.086
3)	<input checked="" type="checkbox"/> CAL3008_alt						
		656664.51	4569600.391	656664.293	4569600.55	-0.212	0.159
4)	<input checked="" type="checkbox"/> CAL3029						
		666340.05	4549967.753	666339.733	4549967.912	-0.318	0.159
5)	<input checked="" type="checkbox"/> CAL3111						
		642965.79	4562472.168	642965.468	4562472.433	-0.318	0.265
6)	<input checked="" type="checkbox"/> CAL3002						
		662080.93	4589443.538	662080.826	4589443.379	-0.106	-0.159
7)	<input checked="" type="checkbox"/> CAL3022						
		656077.24	4620664.619	656077.028	4620664.566	-0.212	-0.053
8)	<input checked="" type="checkbox"/> CAL3004						
		685381.92	4593165.005	685382.135	4593165.27	0.212	0.265
9)	<input checked="" type="checkbox"/> CAL3009						
		675961.59	4620917.03	675961.483	4620917.189	-0.106	0.159
10)	<input checked="" type="checkbox"/> CAL3012						
		707732.24	4623144.461	707732.237	4623144.507	0	0.046

	ID						
		Survey X	Survey Y	Photo X	Photo Y	ΔX	ΔY
11)	<input checked="" type="checkbox"/> CAL3015						
		711868.624	4589352.769	711868.518	4589352.822	-0.106	0.053
12)	<input checked="" type="checkbox"/> CAL3019						
		694412.965	4614849.195	694413.071	4614849.354	0.106	0.159
13)	<input checked="" type="checkbox"/> CAL3027						
		711004.609	4601199.272	711004.609	4601199.007	0	-0.265
14)	<input checked="" type="checkbox"/> CAL3036						
		618909.943	4486894.638	618909.731	4486894.797	-0.212	0.159
15)	<input checked="" type="checkbox"/> CAL3038						
		631286.863	4500427.906	631286.545	4500428.065	-0.318	0.159
16)	<input checked="" type="checkbox"/> CAL3043						
		608299.548	4474970.732	608299.548	4474970.997	0	0.265
17)	<input checked="" type="checkbox"/> CAL3003						
		619281.234	4615177.049	619281.128	4615177.419	-0.106	0.37
18)	<input checked="" type="checkbox"/> CAL3017						
		625892.02	4583313.994	625892.126	4583314.047	0.106	0.053
19)	<input checked="" type="checkbox"/> CAL3020						
		616766.884	4592552.447	616766.778	4592552.606	-0.106	0.159
20)	<input checked="" type="checkbox"/> CAL3026						
		601557.018	4622203.87	601556.912	4622204.029	-0.106	0.159

	ID						
		Survey X	Survey Y	Photo X	Photo Y	ΔX	ΔY
21)	<input checked="" type="checkbox"/> CAL3028						
		635731.749	4588623.154	635731.431	4588623.419	-0.318	0.265
22)	<input checked="" type="checkbox"/> CAL3030						
		659407.143	4501386.554	659406.825	4501386.819	-0.318	0.265
23)	<input checked="" type="checkbox"/> CAL3031						
		672737.85	4483712.205	672737.956	4483712.258	0.106	0.053
24)	<input checked="" type="checkbox"/> CAL3040						
		653205.702	4473009.202	653205.596	4473009.255	-0.106	0.053
25)	<input checked="" type="checkbox"/> CAL3042						
		676070.544	4473810.558	676070.332	4473810.399	-0.212	-0.159
26)	<input checked="" type="checkbox"/> CAL3042_alt						
		676277.753	4473841.213	676277.753	4473841.054	0	-0.159
27)	<input checked="" type="checkbox"/> CAL3046						
		674675.309	4500835.445	674675.944	4500835.392	0.635	-0.053
28)	<input checked="" type="checkbox"/> CAL3048						
		644755.545	4501424.085	644755.439	4501423.926	-0.106	-0.159
29)	<input checked="" type="checkbox"/> CAL3049						
		641266.292	4475585.445	641265.869	4475585.498	-0.423	0.053
30)	<input checked="" type="checkbox"/> CAL3006						
		718101.445	4568714.486	718101.233	4568714.433	-0.212	-0.053

	ID						
		Survey X	Survey Y	Photo X	Photo Y	ΔX	ΔY
31)	<input checked="" type="checkbox"/>	CAL3010					
		697061.77	4548048.91	697061.558	4548048.751	-0.212	-0.159
32)	<input checked="" type="checkbox"/>	CAL3013					
		700221.22	4574515.918	700221.114	4574515.865	-0.106	-0.053
33)	<input checked="" type="checkbox"/>	CAL3108					
		721186.751	4546793.916	721186.433	4546793.969	-0.318	0.053
34)	<input checked="" type="checkbox"/>	CAL3001					
		663378.608	4541263.909	663378.396	4541263.856	-0.212	-0.053
35)	<input checked="" type="checkbox"/>	CAL3032					
		663876.835	4515409.457	663876.623	4515409.616	-0.212	0.159
36)	<input checked="" type="checkbox"/>	CAL3033					
		669593.297	4534555.984	669593.297	4534556.143	0	0.159
37)	<input checked="" type="checkbox"/>	CAL3035					
		644937.607	4515595.32	644937.395	4515595.373	-0.212	0.053
38)	<input checked="" type="checkbox"/>	CAL3039					
		639062.755	4527803.941	639062.755	4527804.206	0	0.265
39)	<input checked="" type="checkbox"/>	CAL3045					
		659294.224	4529996.02	659294.118	4529996.073	-0.106	0.053
40)	<input checked="" type="checkbox"/>	CAL3037					
		618781.515	4524927.766	618781.409	4524927.819	-0.106	0.053

		ID					
		Survey X	Survey Y	Photo X	Photo Y	ΔX	ΔY
41)	<input checked="" type="checkbox"/> CAL3041						
		634339.585	4542991.279	634339.267	4542991.438	-0.318	0.159
42)	<input checked="" type="checkbox"/> CAL3050						
		600553.467	4515315.223	600553.361	4515315.276	-0.106	0.053
43)	<input checked="" type="checkbox"/> CAL_extra_york						
		618095.128	4520039.281	618095.3	4520039.367	0.172	0.086

Point CAL3005:

X1: 667416.801 Y1: 4561114.577 X2: 667416.589 Y2: 4561114.048 Delta X: -0.212 Delta Y: -0.529



Point CAL3008:

X1: 656594.838 Y1: 4569821.799 X2: 656594.494 Y2: 4569821.885 Delta X: -0.344 Delta Y: 0.086



Point CAL3008_alt:

X1: 656664.505 Y1: 4569600.391 X2: 656664.293 Y2: 4569600.55 Delta X: -0.212 Delta Y: 0.159



Point CAL3029:

X1: 666340.051 Y1: 4549967.753 X2: 666339.733 Y2: 4549967.912 Delta X: -0.318 Delta Y: 0.159



Point CAL3111:

X1: 642965.786 Y1: 4562472.168 X2: 642965.468 Y2: 4562472.433 Delta X: -0.318 Delta Y: 0.265



Point CAL3002:

X1: 662080.932 Y1: 4589443.538 X2: 662080.826 Y2: 4589443.379 Delta X: -0.106 Delta Y: -0.159



Point CAL3022:

X1: 656077.24 Y1: 4620664.619 X2: 656077.028 Y2: 4620664.566 Delta X: -0.212 Delta Y: -0.053



Point CAL3004:

X1: 685381.923 Y1: 4593165.005 X2: 685382.135 Y2: 4593165.27 Delta X: 0.212 Delta Y: 0.265



Point CAL3009:

X1: 675961.589 Y1: 4620917.03 X2: 675961.483 Y2: 4620917.189 Delta X: -0.106 Delta Y: 0.159



Point CAL3012:

X1: 707732.237 Y1: 4623144.461 X2: 707732.237 Y2: 4623144.507 Delta X: 0 Delta Y: 0.046



Point CAL3015:

X1: 711868.624 Y1: 4589352.769 X2: 711868.518 Y2: 4589352.822 Delta X: -0.106 Delta Y: 0.053



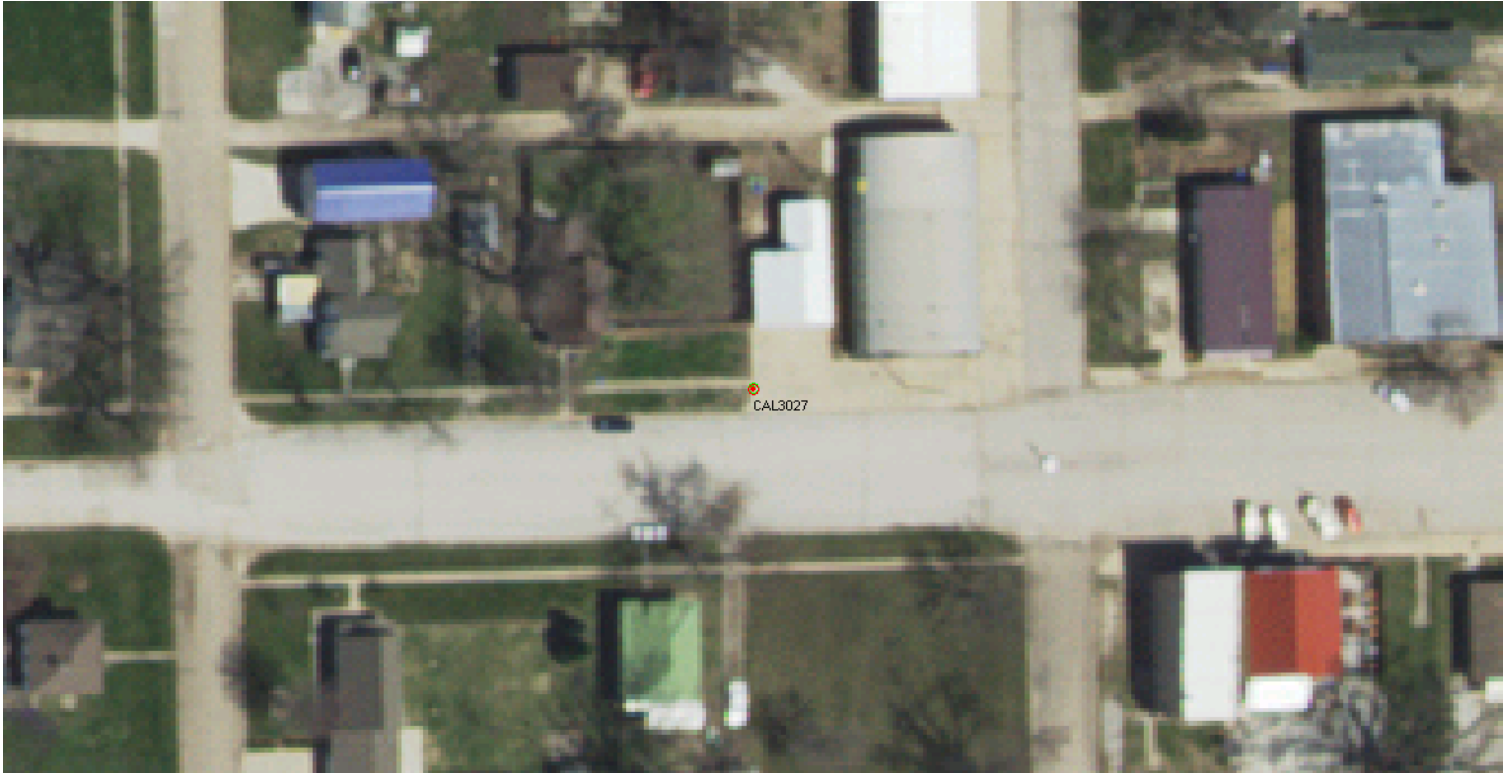
Point CAL3019:

X1: 694412.965 Y1: 4614849.195 X2: 694413.071 Y2: 4614849.354 Delta X: 0.106 Delta Y: 0.159



Point CAL3027:

X1: 711004.609 Y1: 4601199.272 X2: 711004.609 Y2: 4601199.007 Delta X: 0 Delta Y: -0.265



Point CAL3036:

X1: 618909.943 Y1: 4486894.638 X2: 618909.731 Y2: 4486894.797 Delta X: -0.212 Delta Y: 0.159



Point CAL3038:

X1: 631286.863 Y1: 4500427.906 X2: 631286.545 Y2: 4500428.065 Delta X: -0.318 Delta Y: 0.159



Point CAL3043:

X1: 608299.548 Y1: 4474970.732 X2: 608299.548 Y2: 4474970.997 Delta X: 0 Delta Y: 0.265



Point CAL3003:

X1: 619281.234 Y1: 4615177.049 X2: 619281.128 Y2: 4615177.419 Delta X: -0.106 Delta Y: 0.37



Point CAL3017:

X1: 625892.02 Y1: 4583313.994 X2: 625892.126 Y2: 4583314.047 Delta X: 0.106 Delta Y: 0.053



Point CAL3020:

X1: 616766.884 Y1: 4592552.447 X2: 616766.778 Y2: 4592552.606 Delta X: -0.106 Delta Y: 0.159



Point CAL3026:

X1: 601557.018 Y1: 4622203.87 X2: 601556.912 Y2: 4622204.029 Delta X: -0.106 Delta Y: 0.159



Point CAL3028:

X1: 635731.749 Y1: 4588623.154 X2: 635731.431 Y2: 4588623.419 Delta X: -0.318 Delta Y: 0.265



Point CAL3030:

X1: 659407.143 Y1: 4501386.554 X2: 659406.825 Y2: 4501386.819 Delta X: -0.318 Delta Y: 0.265



Point CAL3031:

X1: 672737.85 Y1: 4483712.205 X2: 672737.956 Y2: 4483712.258 Delta X: 0.106 Delta Y: 0.053



Point CAL3040:

X1: 653205.702 Y1: 4473009.202 X2: 653205.596 Y2: 4473009.255 Delta X: -0.106 Delta Y: 0.053



Point CAL3042:

X1: 676070.544 Y1: 4473810.558 X2: 676070.332 Y2: 4473810.399 Delta X: -0.212 Delta Y: -0.159



Point CAL3042_alt:

X1: 676277.753 Y1: 4473841.213 X2: 676277.753 Y2: 4473841.054 Delta X: 0 Delta Y: -0.159



Point CAL3046:

X1: 674675.309 Y1: 4500835.445 X2: 674675.944 Y2: 4500835.392 Delta X: 0.635 Delta Y: -0.053



Point CAL3048:

X1: 644755.545 Y1: 4501424.085 X2: 644755.439 Y2: 4501423.926 Delta X: -0.106 Delta Y: -0.159



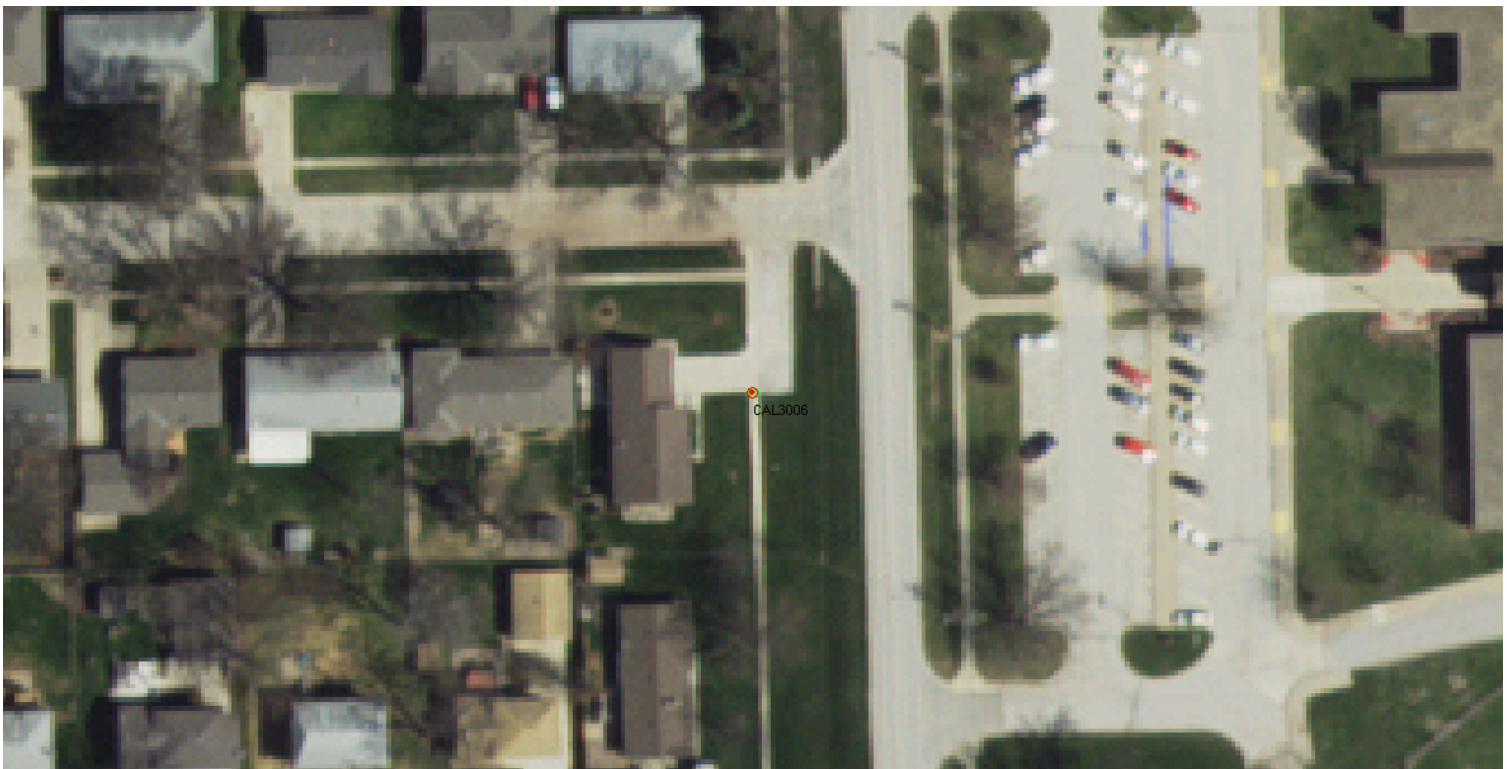
Point CAL3049:

X1: 641266.292 Y1: 4475585.445 X2: 641265.869 Y2: 4475585.498 Delta X: -0.423 Delta Y: 0.053



Point CAL3006:

X1: 718101.445 Y1: 4568714.486 X2: 718101.233 Y2: 4568714.433 Delta X: -0.212 Delta Y: -0.053



Point CAL3010:

X1: 697061.77 Y1: 4548048.91 X2: 697061.558 Y2: 4548048.751 Delta X: -0.212 Delta Y: -0.159



Point CAL3013:

X1: 700221.22 Y1: 4574515.918 X2: 700221.114 Y2: 4574515.865 Delta X: -0.106 Delta Y: -0.053



Point CAL3108:

X1: 721186.751 Y1: 4546793.916 X2: 721186.433 Y2: 4546793.969 Delta X: -0.318 Delta Y: 0.053



Point CAL3001:

X1: 663378.608 Y1: 4541263.909 X2: 663378.396 Y2: 4541263.856 Delta X: -0.212 Delta Y: -0.053



Point CAL3032:

X1: 663876.835 Y1: 4515409.457 X2: 663876.623 Y2: 4515409.616 Delta X: -0.212 Delta Y: 0.159



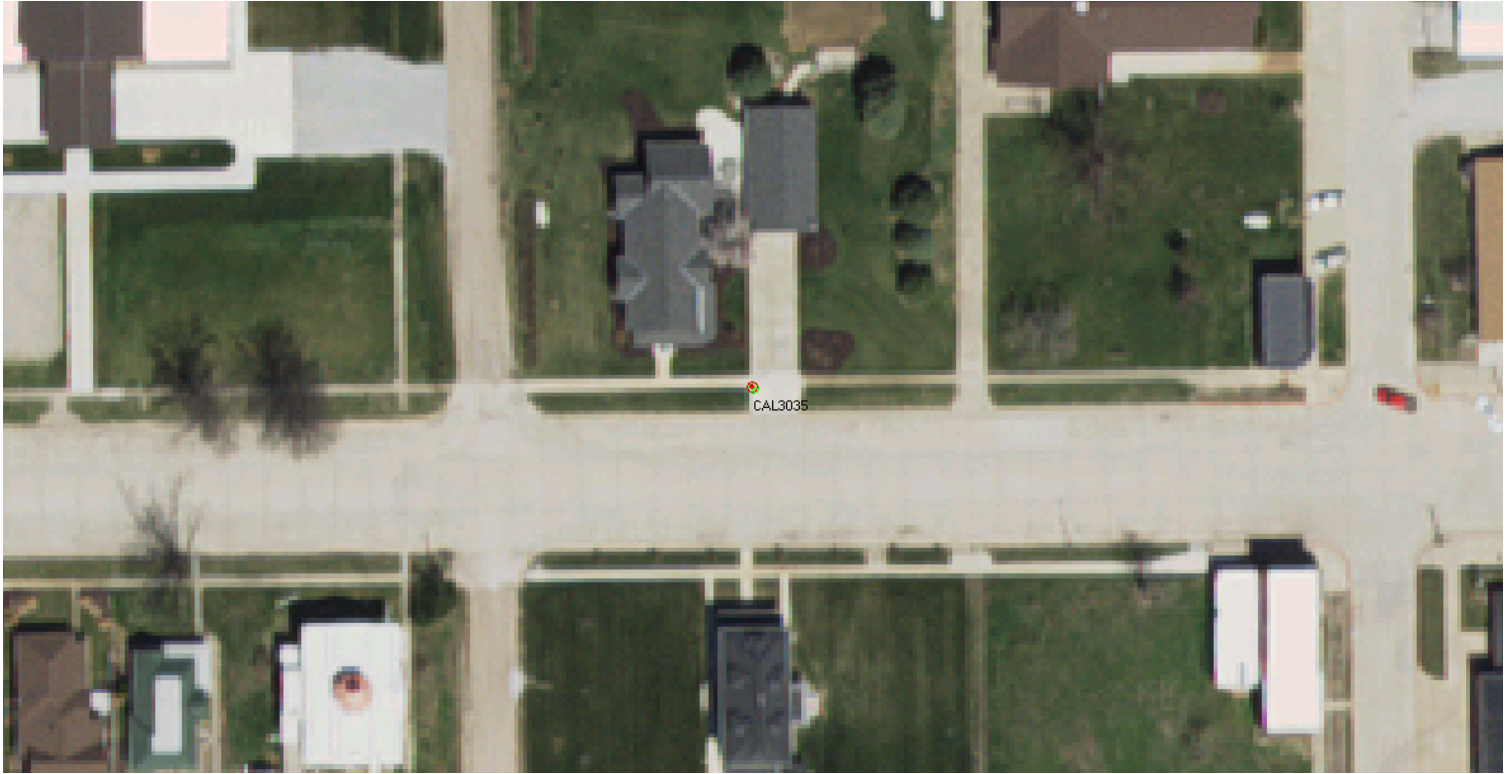
Point CAL3033:

X1: 669593.297 Y1: 4534555.984 X2: 669593.297 Y2: 4534556.143 Delta X: 0 Delta Y: 0.159



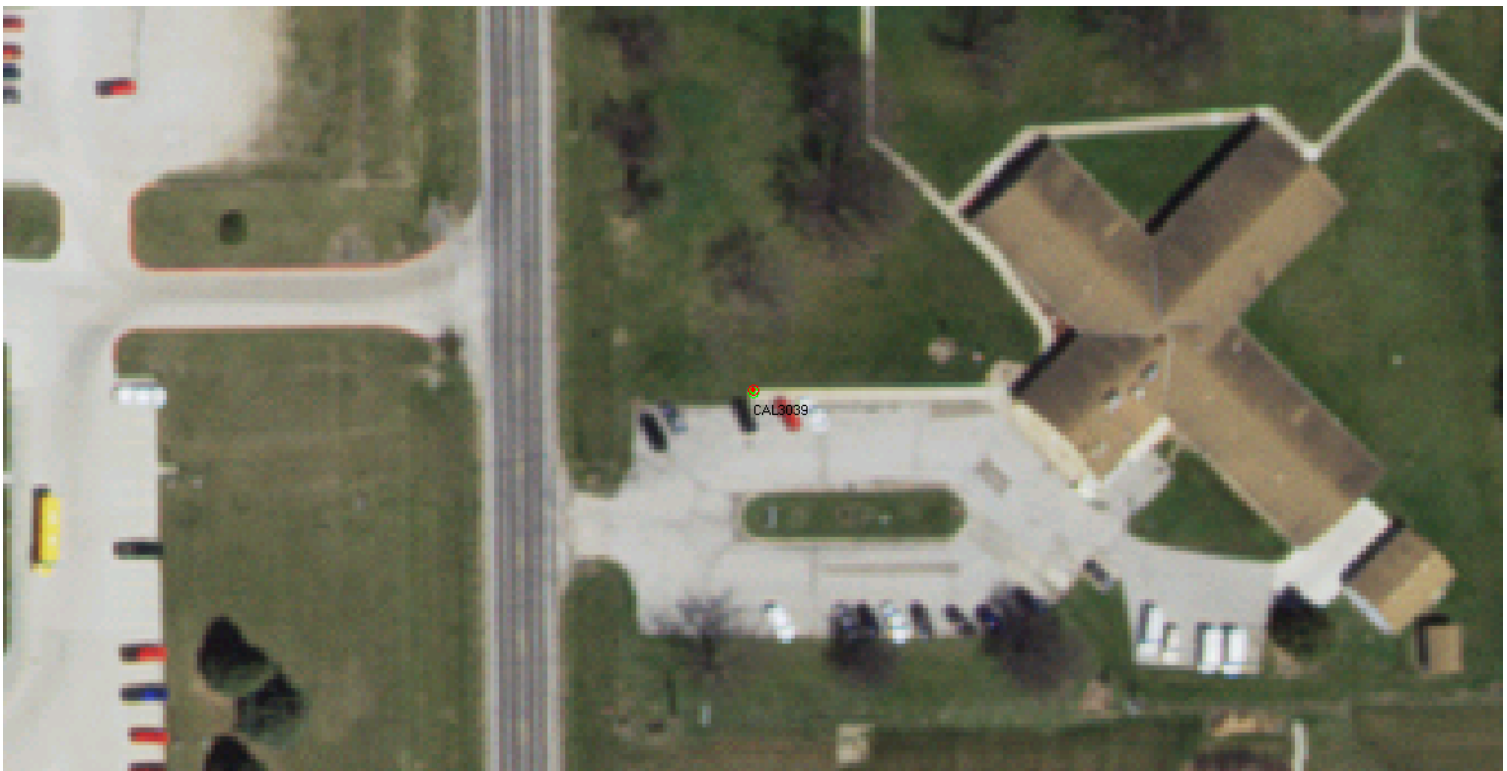
Point CAL3035:

X1: 644937.607 Y1: 4515595.32 X2: 644937.395 Y2: 4515595.373 Delta X: -0.212 Delta Y: 0.053



Point CAL3039:

X1: 639062.755 Y1: 4527803.941 X2: 639062.755 Y2: 4527804.206 Delta X: 0 Delta Y: 0.265



Point CAL3045:

X1: 659294.224 Y1: 4529996.02 X2: 659294.118 Y2: 4529996.073 Delta X: -0.106 Delta Y: 0.053



Point CAL3037:

X1: 618781.515 Y1: 4524927.766 X2: 618781.409 Y2: 4524927.819 Delta X: -0.106 Delta Y: 0.053



Point CAL3041:

X1: 634339.585 Y1: 4542991.279 X2: 634339.267 Y2: 4542991.438 Delta X: -0.318 Delta Y: 0.159



Point CAL3050:

X1: 600553.467 Y1: 4515315.223 X2: 600553.361 Y2: 4515315.276 Delta X: -0.106 Delta Y: 0.053



Point CAL_extra_york:

X1: 618095.128 Y1: 4520039.281 X2: 618095.3 Y2: 4520039.367 Delta X: 0.172 Delta Y: 0.086



Coordinates and Offsets of Unanalyzed Locations

	ID			
		Survey X	Survey Y	Reason For Exclusion
1)	<input type="checkbox"/> CAL3007			
		674516.863	4607206.849	Ambiguous Location
2)	<input type="checkbox"/> CAL3021			
		649077.179	4595420.032	Ambiguous Location
3)	<input type="checkbox"/> CAL_COLFAX_EXTRA			
		661773.175	4605319.462	Ambiguous Location
4)	<input type="checkbox"/> CAL_DODGE_EXTRA			
		691568.236	4601962.038	Ambiguous Location
5)	<input type="checkbox"/> CAL3034			
		606065.813	4486732.136	Ambiguous Location
6)	<input type="checkbox"/> CAL3047			
		602684.937	4498013.685	Ambiguous Location
7)	<input type="checkbox"/> CAL3051			
		620768.091	4469251.703	Ambiguous Location
8)	<input type="checkbox"/> CAL3011			
		640599.128	4616203.153	Ambiguous Location
9)	<input type="checkbox"/> CAL3024			
		608607.956	4605992.393	Ambiguous Location
10)	<input type="checkbox"/> CAL_extra_platte			
		627728.172	4620847.869	Ambiguous Location

Coordinates and Offsets of Unanalyzed Locations

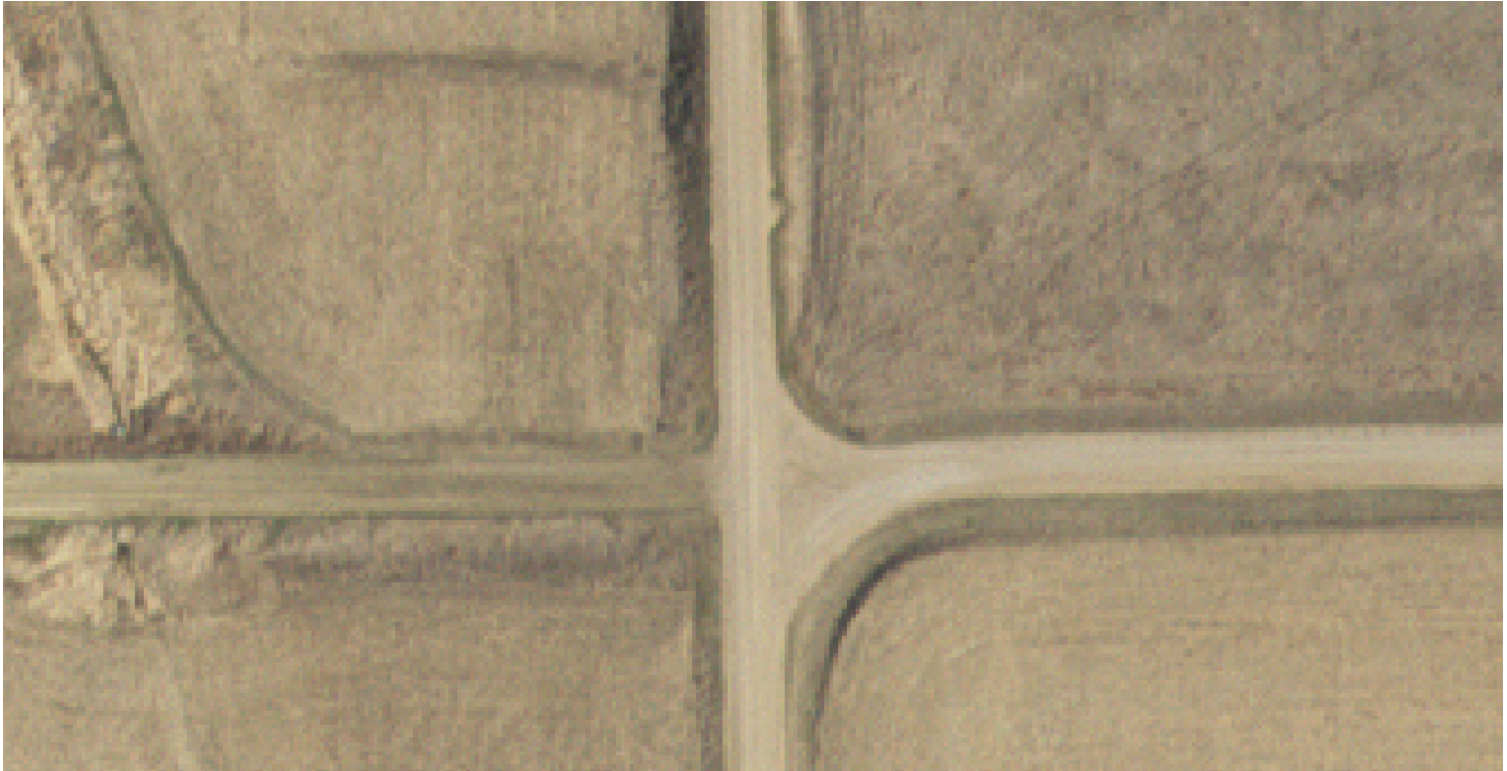
	ID		
		Survey X	Survey Y
			Reason For Exclusion
11)	<input type="checkbox"/> CAL3049_alt	709818.31	
			4548392.541
			Ambiguous Location
12)	<input type="checkbox"/> CAL3014	716114.571	
			4555022.368
			Ambiguous Location
13)	<input type="checkbox"/> CAL3016	686063.094	
			4583287.547
			Ambiguous Location
14)	<input type="checkbox"/> CAL3023	685121.847	
			4559104.39
			Ambiguous Location
15)	<input type="checkbox"/> CAL3025	698593.744	
			4561103.559
			Ambiguous Location
16)	<input type="checkbox"/> CAL_EXTRA_SAV	638734.138	
			4545279.45
			Ambiguous Location
17)	<input type="checkbox"/> CAL3018	650794.425	
			4545481.826
			Ambiguous Location
18)	<input type="checkbox"/> CAL3109	673978.234	
			4545941.814
			Ambiguous Location
19)	<input type="checkbox"/> CAL3110	674268.027	
			4534671.783
			Ambiguous Location
20)	<input type="checkbox"/> CAL_extra_sew	606704.677	
			4539866.952
			Ambiguous Location

Coordinates and Offsets of Unanalyzed Locations

	ID			
		Survey X	Survey Y	Reason For Exclusion
21)	<input type="checkbox"/> CAL3044			
		606704.677	4539866.952	Ambiguous Location

Point CAL3007:

X1: 674516.863 Y1: 4607206.849 Reason For Exclusion: Ambiguous Location



Point CAL3021:

X1: 649077.179 Y1: 4595420.032 Reason For Exclusion: Ambiguous Location



Point CAL_COLFAX_EXTRA:

X1: 661773.175 Y1: 4605319.462 Reason For Exclusion: Ambiguous Location



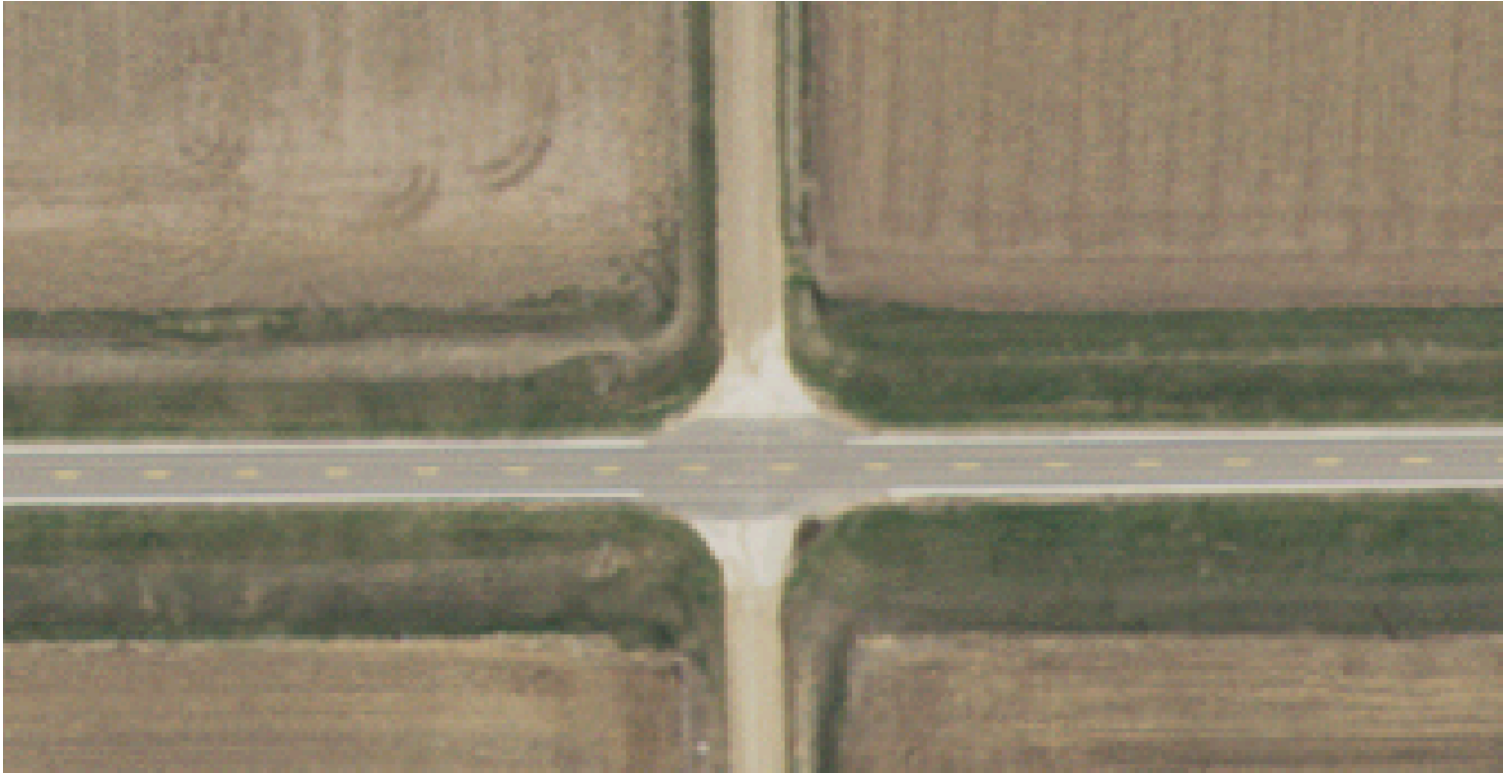
Point CAL_DODGE_EXTRA:

X1: 691568.236 Y1: 4601962.038 Reason For Exclusion: Ambiguous Location



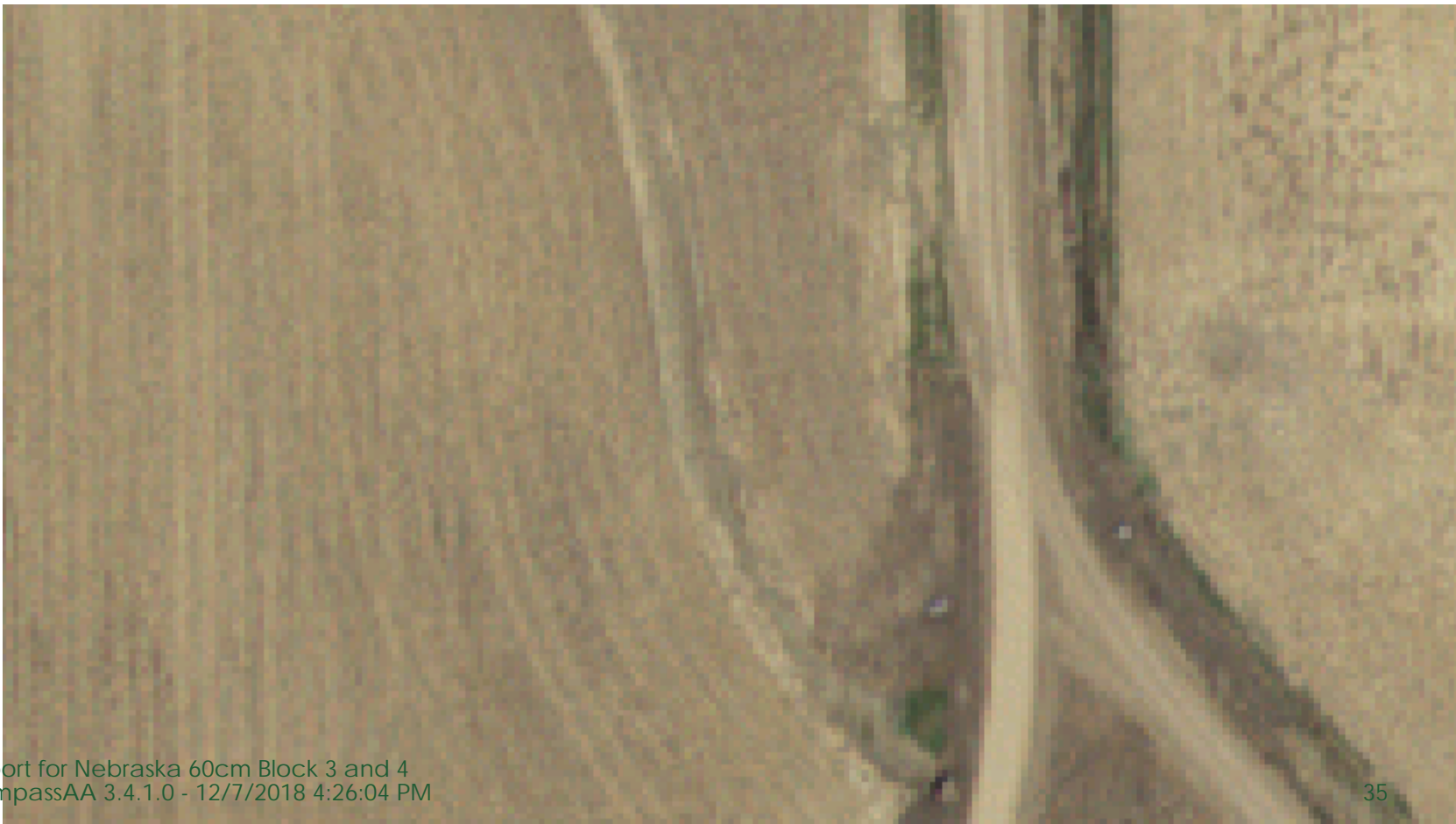
Point CAL3034:

X1: 606065.813 Y1: 4486732.136 Reason For Exclusion: Ambiguous Location



Point CAL3047:

X1: 602684.937 Y1: 4498013.685 Reason For Exclusion: Ambiguous Location



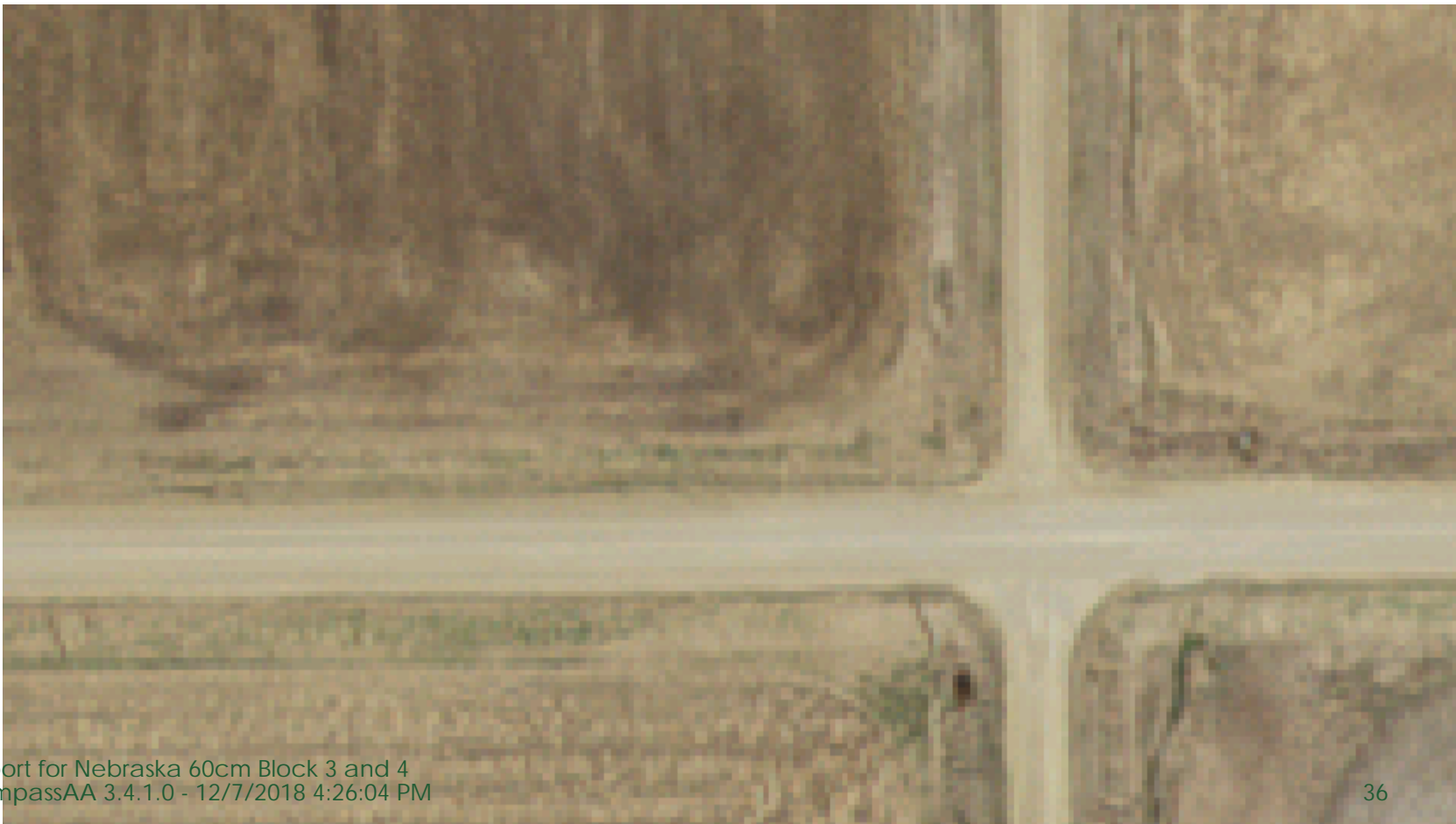
Point CAL3051:

X1: 620768.091 Y1: 4469251.703 Reason For Exclusion: Ambiguous Location



Point CAL3011:

X1: 640599.128 Y1: 4616203.153 Reason For Exclusion: Ambiguous Location



Point CAL3024:

X1: 608607.956 Y1: 4605992.393 Reason For Exclusion: Ambiguous Location



Point CAL_extra_platte:

X1: 627728.172 Y1: 4620847.869 Reason For Exclusion: Ambiguous Location



Point CAL3049_alt:

X1: 641158.85 Y1: 4475545.866 Reason For Exclusion: Ambiguous Location



Point CAL3014:

X1: 709818.31 Y1: 4548392.541 Reason For Exclusion: Ambiguous Location



Point CAL3016:

X1: 716114.571 Y1: 4555022.368 Reason For Exclusion: Ambiguous Location



Point CAL3023:

X1: 686063.094 Y1: 4583287.547 Reason For Exclusion: Ambiguous Location



Point CAL3025:

X1: 685121.847 Y1: 4559104.39 Reason For Exclusion: Ambiguous Location



Point CAL_EXTRA_SAU:

X1: 698593.744 Y1: 4561103.559 Reason For Exclusion: Ambiguous Location



Point CAL3018:

X1: 638734.138 Y1: 4545279.45 Reason For Exclusion: Ambiguous Location



Point CAL3109:

X1: 650794.425 Y1: 4545481.826 Reason For Exclusion: Ambiguous Location



Point CAL3110:

X1: 673978.234 Y1: 4545941.814 Reason For Exclusion: Ambiguous Location



Point CAL_extra_sew:

X1: 674268.027 Y1: 4534671.783 Reason For Exclusion: Ambiguous Location



Point CAL3044:

X1: 606704.677 Y1: 4539866.952 Reason For Exclusion: Ambiguous Location



Appendix 3

Following is a more detailed Survey Report



Geodetic Survey Report

CDI Project: 5420 Nebraska II

CDI POC: Philipp Hummel
phummel@compassdatainc.com

Location of Survey: Nebraska

Date of Survey: February 2018

Customer: Merrick

POC: Doug Jacoby

MERRICK Project Name: NE_NRCS_OrthoLidar_2017_D18

MERRICK Task Order Number: GPSC3 TO 014G0218F0028

MERRICK Subcontract Number: 65213751-A

Other Documents: CompassData-Nebraska II-SAPS_CDI Executed.pdf

Survey Report prepared by Philipp Hummel, PLS, CFedS, CP
phummel@compassdatainc.com

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Datum Requirements

Contractual requirements for the survey by the client:

Projection: Universal Transverse Mercator (UTM), Zones 13N, 14N, and 15N (where appropriate), Meters.

Horizontal Datum: North American Datum of 1983 (NAD 83), National Adjustment of 2011 (NA2011)

Vertical Datum: North American Vertical Datum of 1988 (NAVD 88); using the latest NGS-approved geoid (i.e., GEOID12B) for converting ellipsoid heights to orthometric elevations

Surveying Methods

The combination of static Global Navigation Satellite System (GNSS) observations, and Virtual Reference Station (VRS) GNSS observations resulted in the highest accuracy of the coordinates. The CompassData standard field procedures for VRS observations require a minimum of two 90 second collects at each point. Between the two observations the GNSS unit was rotated by 180 degrees and re-setup (to neutralize any potential tilt bias). All survey observations by CompassData were taken with Trimble GNSS units (R10 and R8). When no Trimble VRS Now and cell service was available, static GNSS observations were collected for a minimum of 45 minutes. Figure 1 below shows the coverage map of the Trimble VRS Now network. The Trimble VRS Network is also known as a Realtime Kinematic Network (RTN).

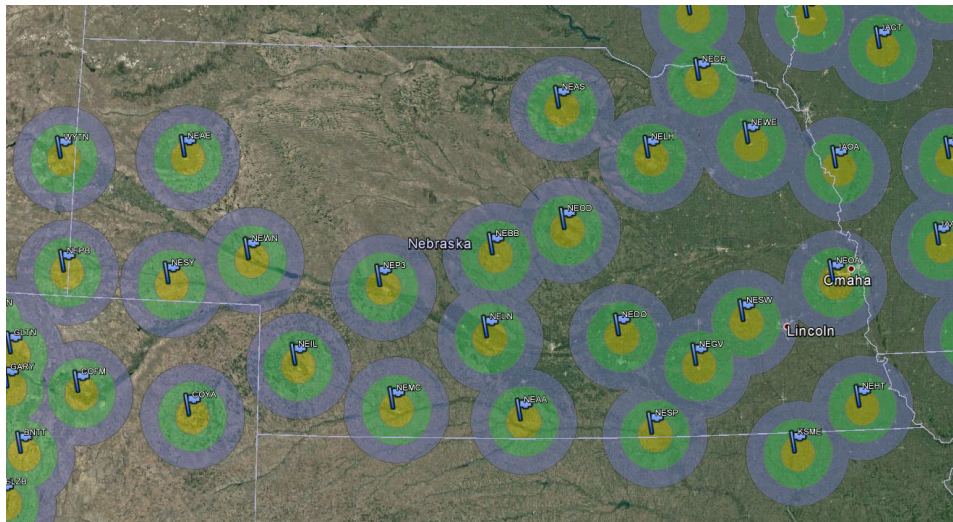


Figure 1: Trimble VRS Now Network

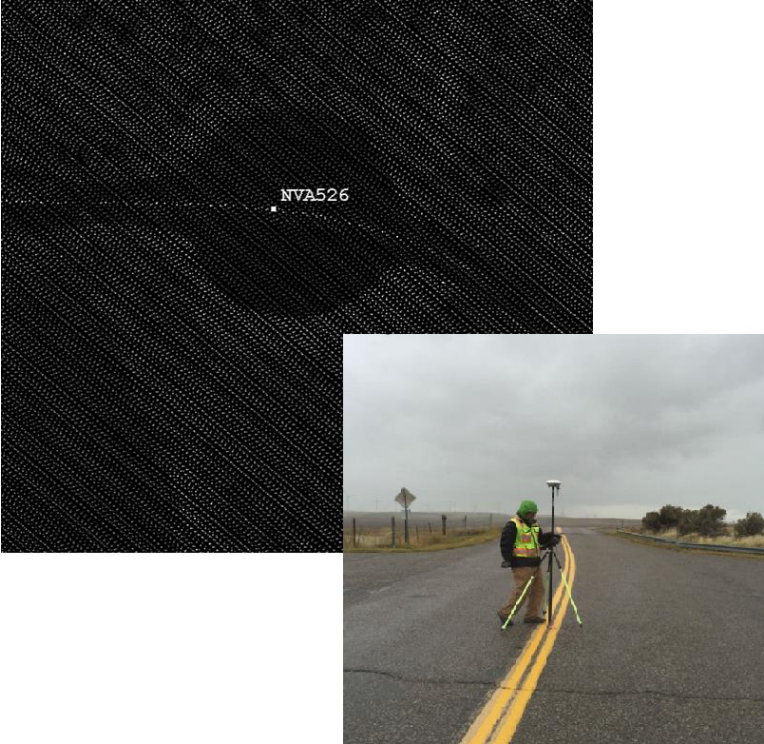
For the final coordinate values, a constrained network to continuously operating reference stations (CORS) was established. CORS stations are operated by the National Geodetic Survey (NGS). The constrained network anchors the VRS observations and static GNSS observations together. See Figure 2 below.

Calibration, NVA and VVA Points

For the most part, CompassData field crews surveyed the suggested locations as planned per the client provided GoogleEarth files. Some locations were moved up to 1-2 km from the original locations due to landowner concerns and highway safety issues. Calibration and NVA (Non-vegetated vertical assessment) points were planned to fall on flat hard surfaces types: asphalt, concrete, gravel, and dirt roads. Due to the rural landscape of the Nebraska II, most points are on gravel and dirt-roads. The vegetated vertical assessment points (VVAs) fell on different types of grasses that are common to the Nebraska II prairie. The different grasses will probably have similar LiDAR signal returns if measured before summer; slight differences can still be expected at some of the locations due to taller and denser grass. Five photos provided for each VVA point show the density and height of the grass. Some of the areas had been recently flattened by snow and wind.

Horizontal Accuracy Intensity-Identifiable Features

CompassData field crews surveyed 62 intensity-identifiable features as NVA or calibration points. The intensity-identifiable features were surveyed when it was feasible, meaning when road markings on asphalt were available and accessible to survey without having to place a GNSS unit into traffic for an extended time.



Post-Processing Procedure

The Nebraska II project area covers about a large portion of Nebraska and is subdivided in 3 separate areas. Post-processing of GNSS data of such large areas is spilt into smaller areas for two reasons: The geometric distortions that potentially come with very large networks are kept at a minimum, and the organization of the work can be handled easier. With client approval, the Nebraska II project was split into the 20 counties covered by the project. For each county, the data was post processed with the following procedure.

The static data collected in the field was combined into a network adjustment with any VRS GNSS observations and the static GNSS from the closest CORS stations. Coordinates for the static points were established by a constrained network adjustment (Method of the Least Squares) and checked against Online Positioning User Service (OPUS) solutions. Such static observations were also conducted on VRS observations for quality control.

All points meet accuracy requirements of 6.5 cm for calibration and NVA points and 9.8 cm for VVA points with a 95% confidence (CE95).

Distribution of Surveyed Points

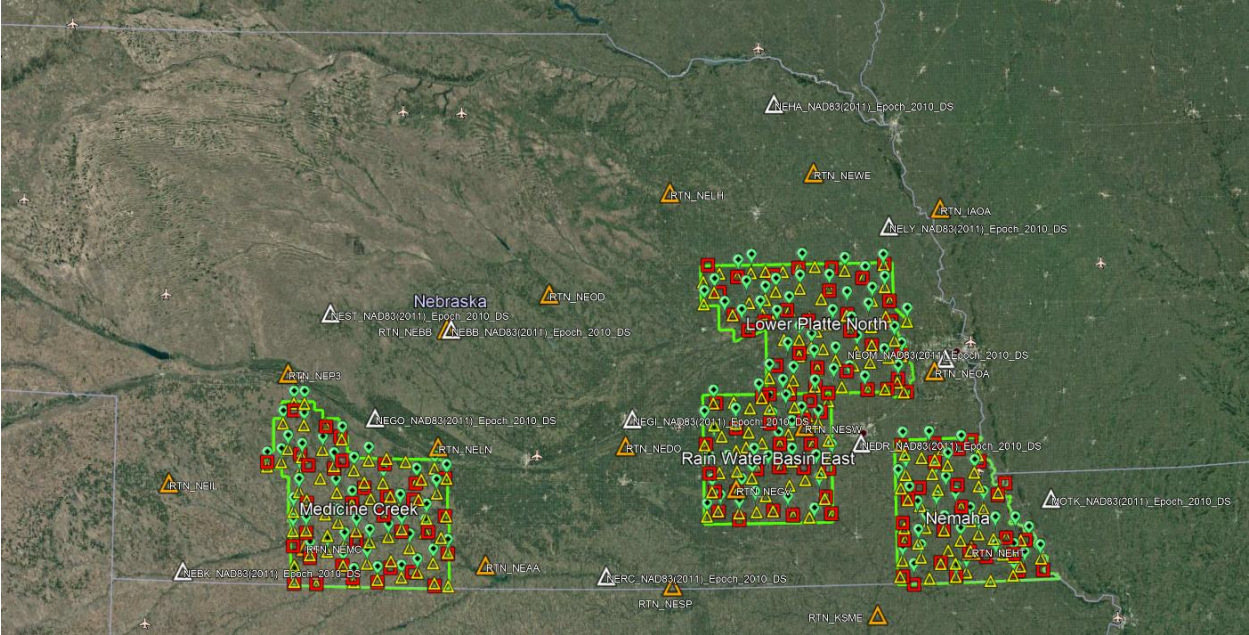


Figure 2: Distribution of Calibration Points (Red), NVA Points (Yellow), and VVA Points (Green) and CORS Stations by the NGS (White) and Trimble VRS Now Stations (Orange)

Incorporated CORS stations from the NGS and Trimble VRS Now

As described above, all the different network adjustments per county are based on the same GNSS base stations provided by the NGS and Trimble VRS Now. The NGS stations have the published NAD83 (2011) coordinates that were used as fixed constrains to reproduce the official NAD83 (2011) geodetic datum. While the Trimble VRS Now stations are operated, and used by various professionals, these are not on the same geodetic network order of the NGS authoritative data.

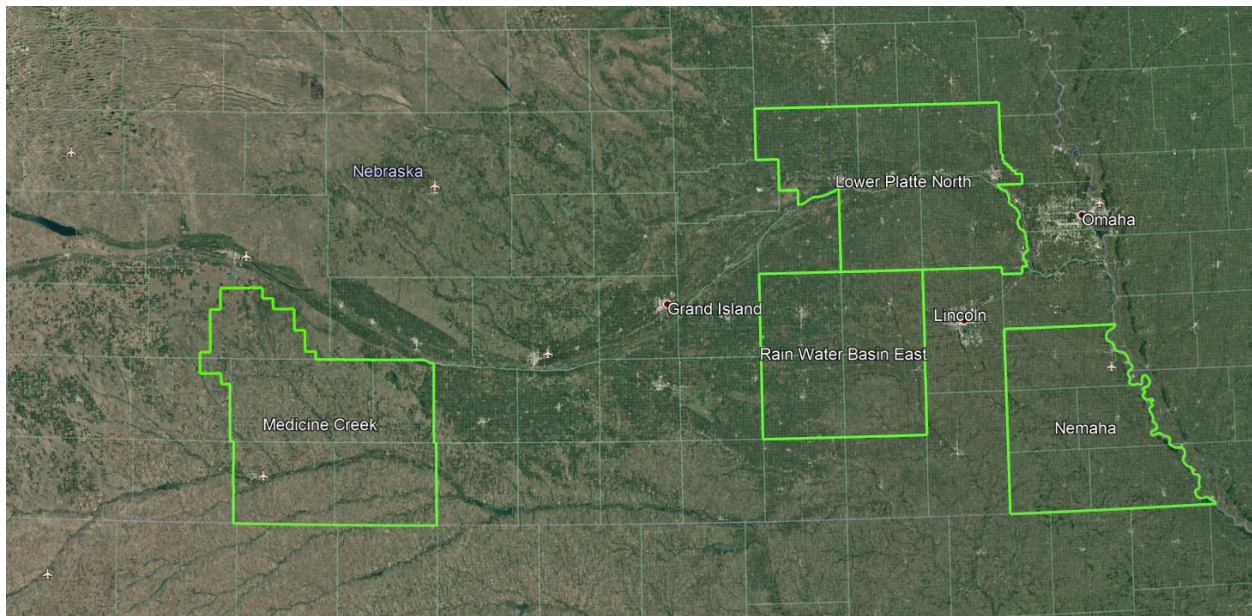
The geodetic datum was further confirmed with physical NGS monuments. Published coordinates by the NGS and OPUS solutions were taken in account to confirm accuracy of equipment and the NAD83(2011) datum.

Base Stations	Latitude	Longitude	HAE	NAVD88
IADN_NAD83(2011)_Epoch_2010_DS	41.99737861	-95.37570247	351.173	380.427
KSU1_NAD83(2011)_Epoch_2010_DS	39.10074370	-96.60947044	326.626	356.573
MOSV_NAD83(2011)_Epoch_2010_DS	39.95420768	-94.84758805	320.921	352.668
MOTK_NAD83(2011)_Epoch_2010_DS	40.43725836	-95.35121019	252.967	283.631
NEAL_NAD83(2011)_Epoch_2010_DS	41.67508023	-97.98057042	511.322	535.788
NEAP_NAD83(2011)_Epoch_2010_DS	40.30585513	-99.90537033	647.252	671.927
NEBB_NAD83(2011)_Epoch_2010_DS	41.40230124	-99.62597833	737.868	760.589
NEBK_NAD83(2011)_Epoch_2010_DS	40.06140632	-101.53103525	912.765	936.007
NEDR_NAD83(2011)_Epoch_2010_DS	40.77258105	-96.70031784	349.329	375.304
NEFR_NAD83(2011)_Epoch_2010_DS	40.14815400	-97.17067345	413.536	440.594
NEGI_NAD83(2011)_Epoch_2010_DS	40.92225342	-98.32815271	542.597	567.688
NEGO_NAD83(2011)_Epoch_2010_DS	40.92006473	-100.16589717	763.415	786.527
NELY_NAD83(2011)_Epoch_2010_DS	41.93825475	-96.45930250	399.147	425.053
NEMC_NAD83(2011)_Epoch_2010_DS	40.19940227	-100.57816530	740.680	764.713
NEOM_NAD83(2011)_Epoch_2010_DS	41.21556233	-96.08039169	351.506	378.703
RTN_KSME (Trimble VRS Now)	39.84114023	-96.60904227	374.580	402.670
RTN_NEAA (Trimble VRS Now)	40.13243889	-99.37050533	612.381	637.593
RTN_NEGV (Trimble VRS Now)	40.54019464	-97.59491297	473.879	500.555
RTN_NEHT (Trimble VRS Now)	40.17365704	-95.93323735	295.277	324.801
RTN_NELH (Trimble VRS Now)*	42.13799508	-98.04607500	516.535	541.179
RTN_NELN (Trimble VRS Now)	40.76824037	-99.71205248	708.802	732.678
RTN_NEMC (Trimble VRS Now)	40.21562091	-100.64948606	792.842	792.842
RTN_NEOA (Trimble VRS Now)	41.15075323	-96.16077923	337.973	364.812
RTN_NEP3 (Trimble VRS Now)	41.15071658	-100.79944327	845.943	868.070
RTN_NESW (Trimble VRS Now)	40.86854026	-97.10255165	437.918	464.836

RTN_NEWE (Trimble VRS Now)	42.23424649	-96.99916201	421.039	445.955
RTN_IAOA (Trimble VRS Now)**	42.02647890	-96.08125941	298.973	326.202

Note above *: The Trimble VRS Now base station NELN in Lexington was changed since the Sandhill survey.
Note above **: The Trimble VRS Now network operates in Onawa, IO, a base station IAOA that was introduced later to the processing of Dodge County (northeast corner of AOIs). The coordinate was established in the Dodge county network adjustment.

AOI and Regions of Nebraska II Project



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