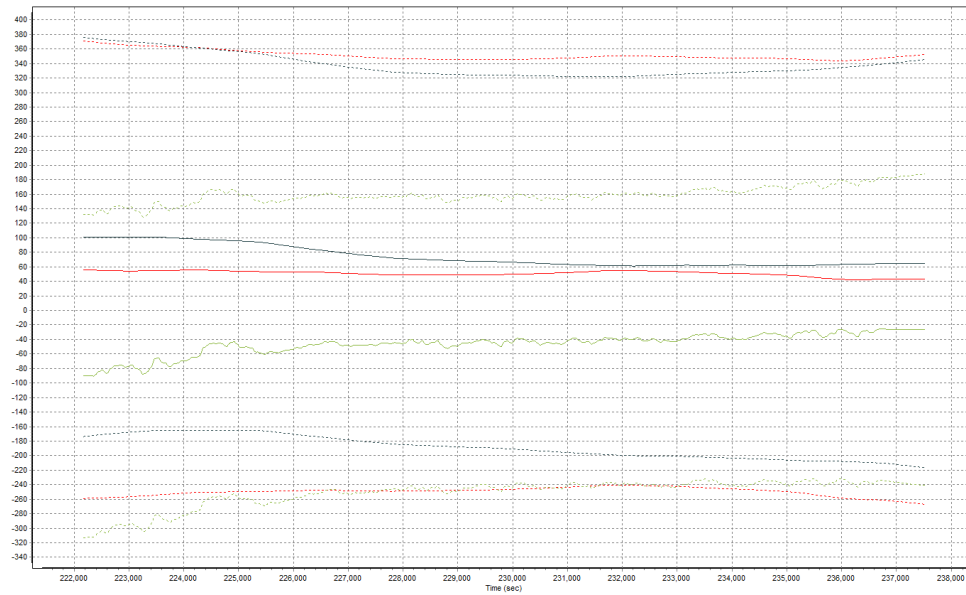
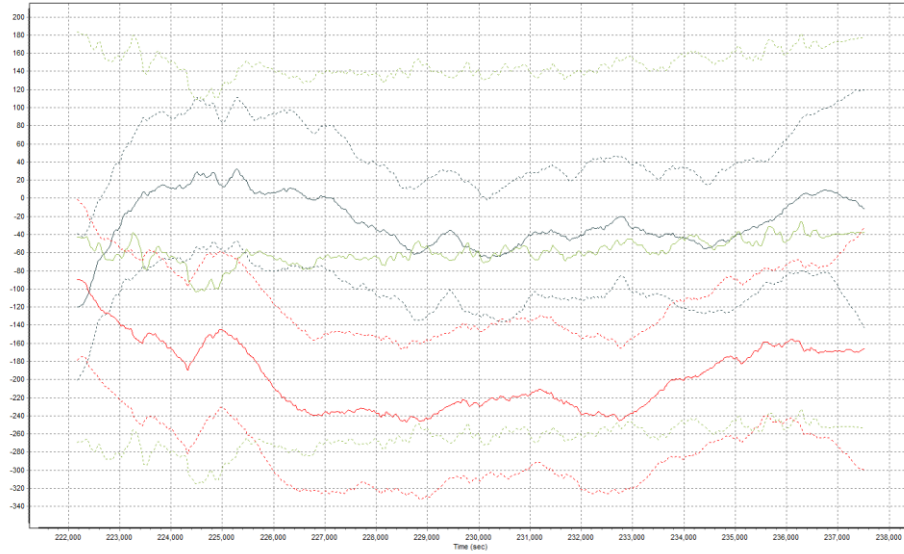
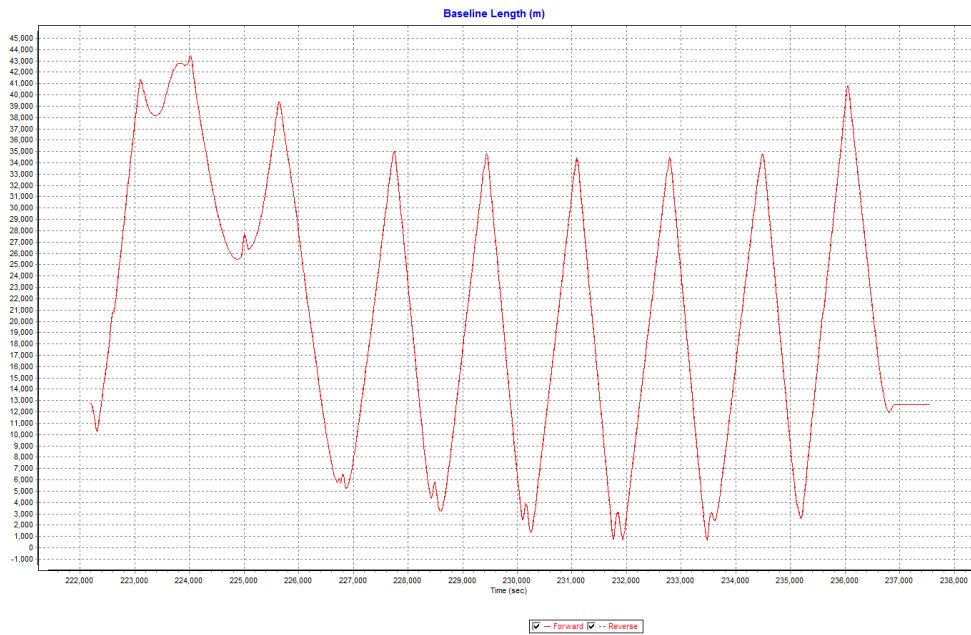
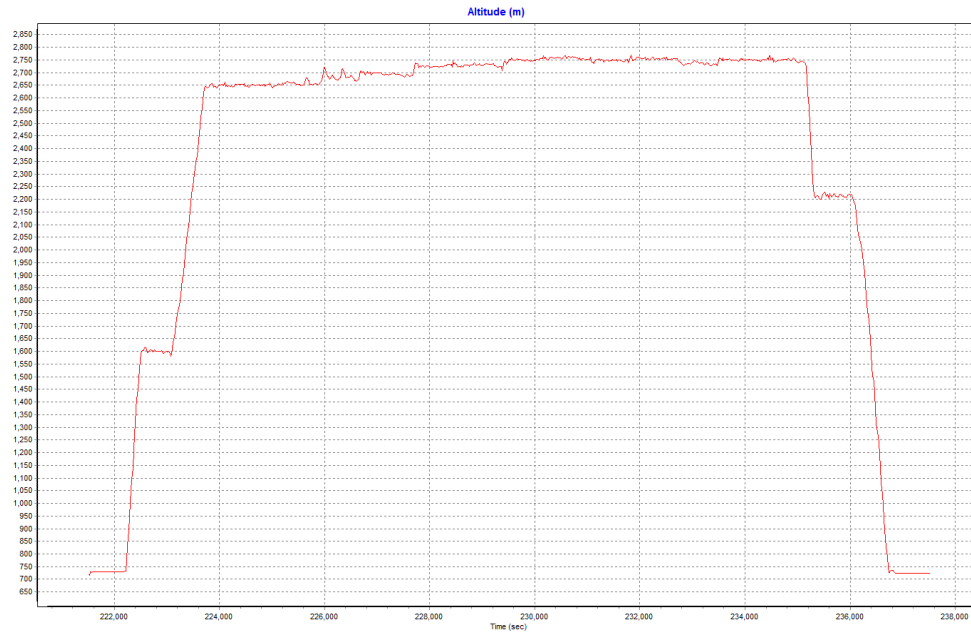


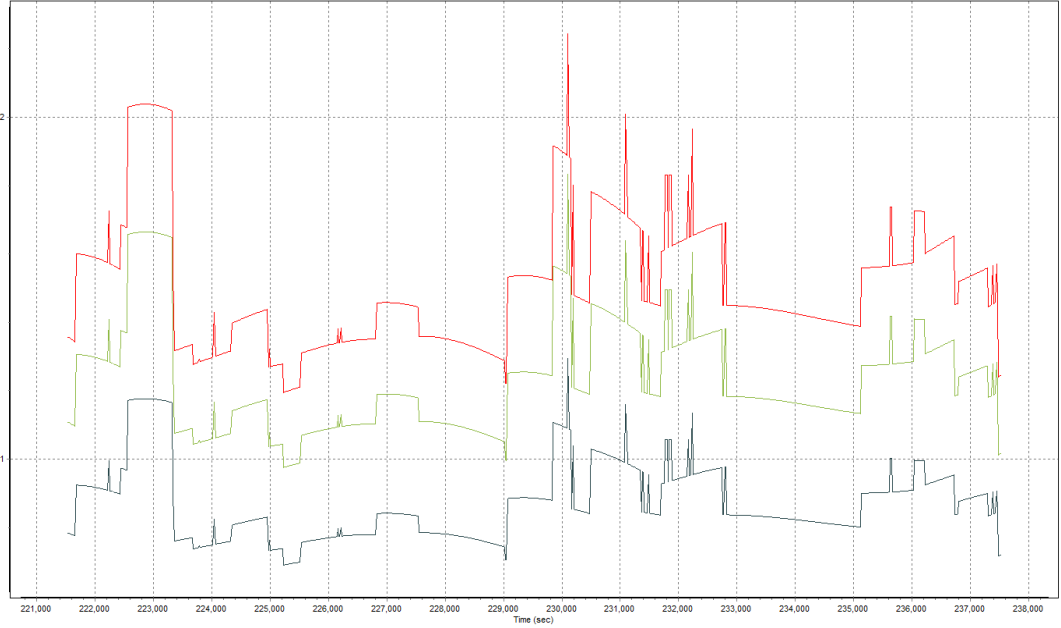
# Appendix E: GNSS and IMU processing reports for each mission

## CAU16327A



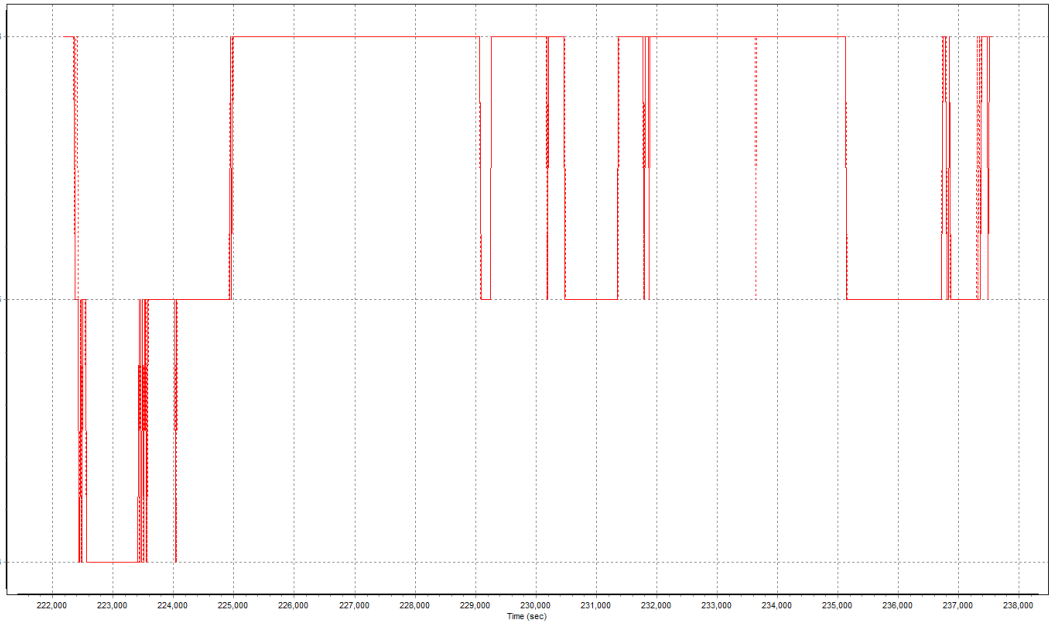


UOP



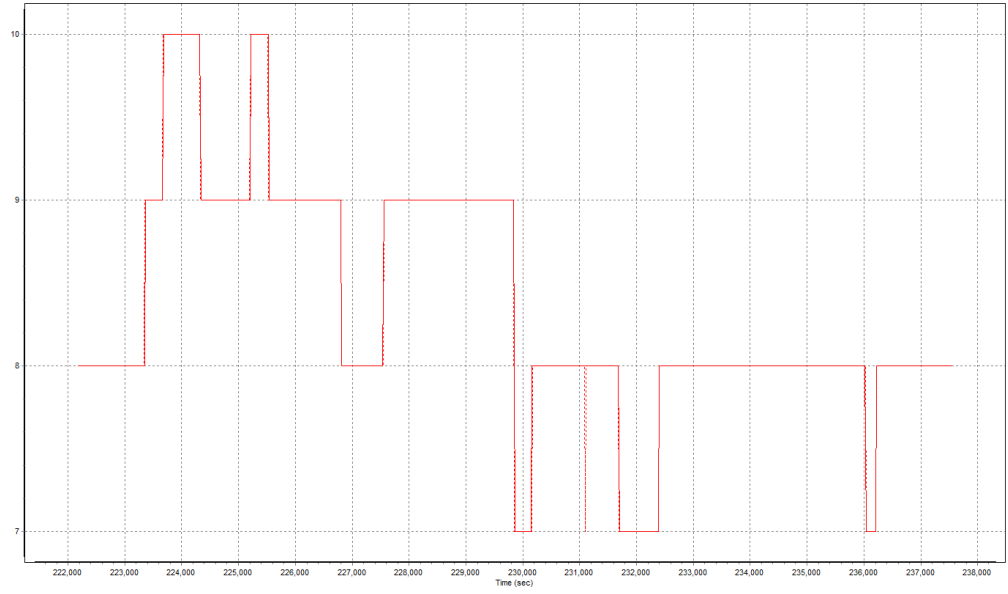
— PDOP — HDOP — VDOP

Number of GLONASS Satellites

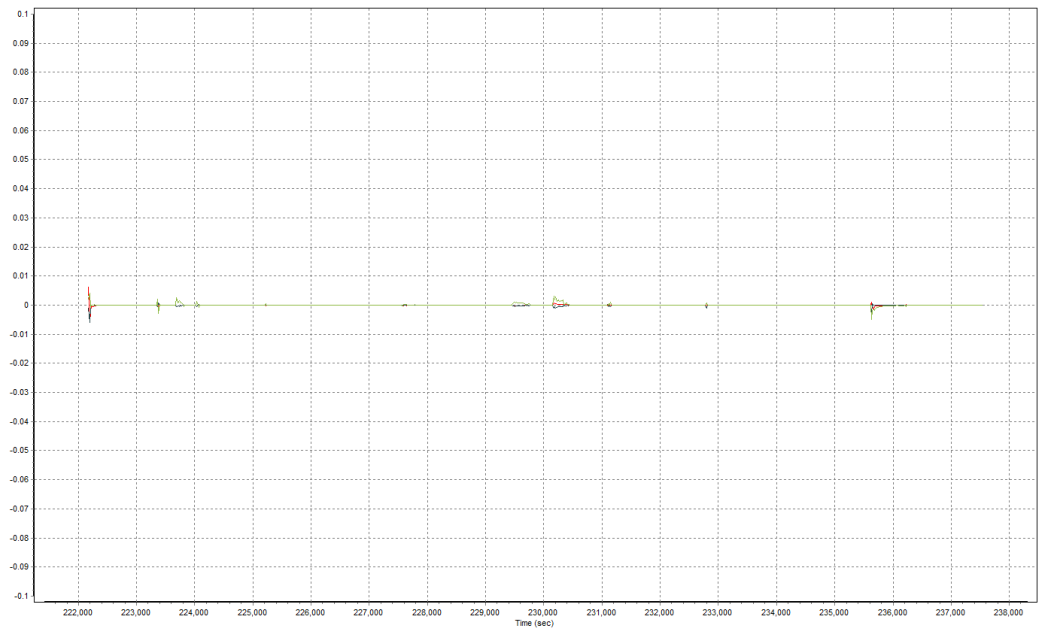


Forward  Reverse

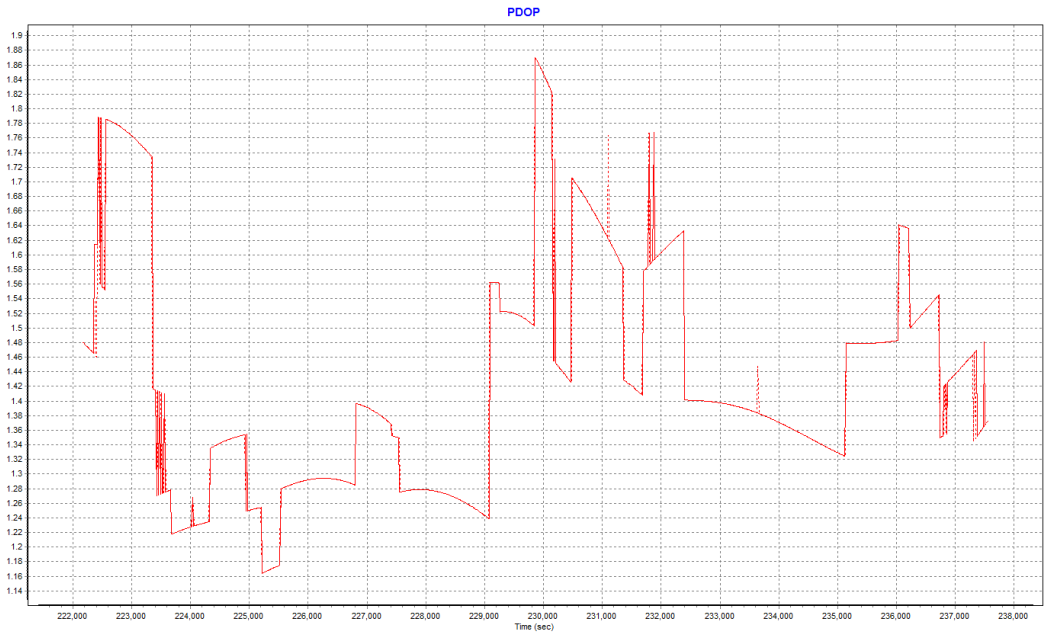
Number of GPS Satellites



Forward  Reverse



North (m) East (m) Down (m) DR mode

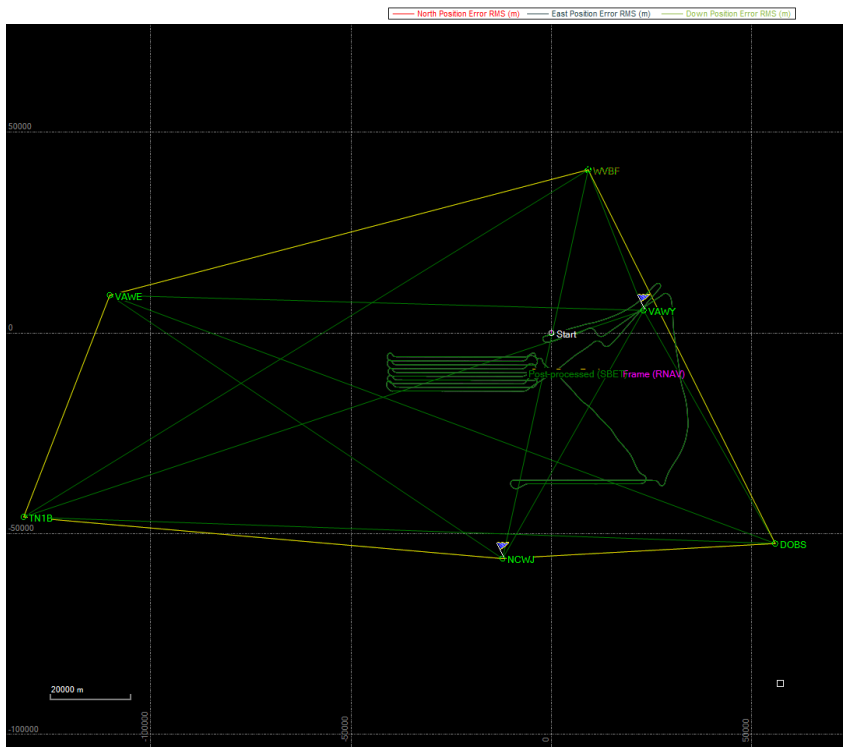
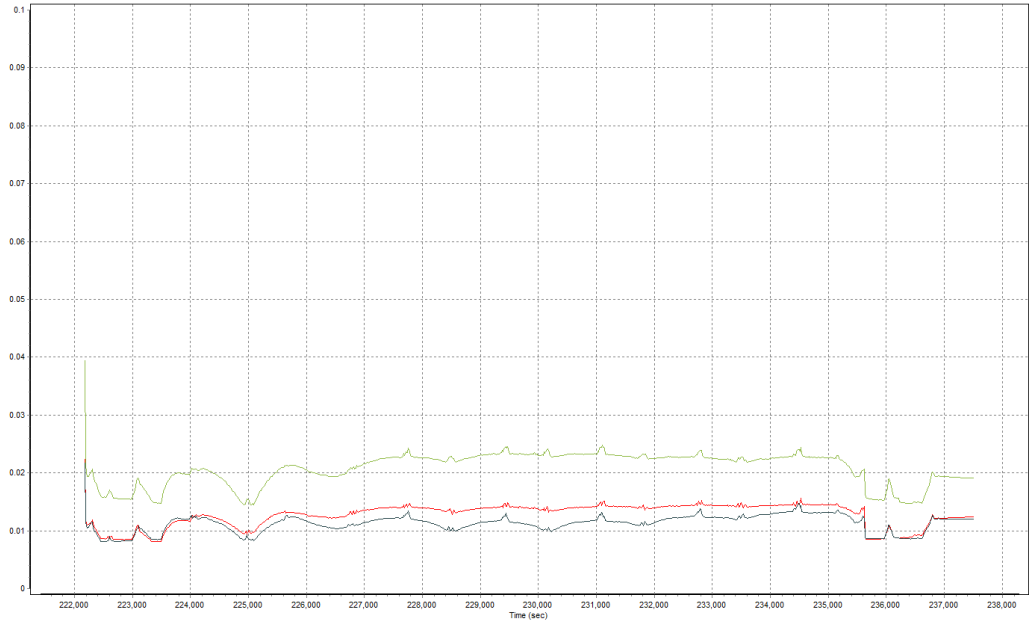


Forward  Reverse

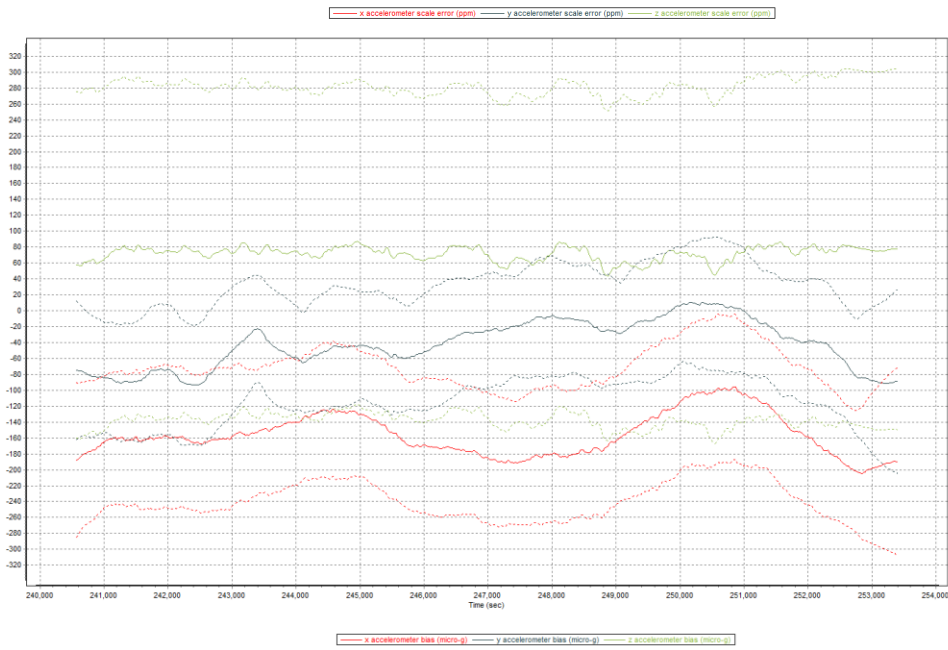
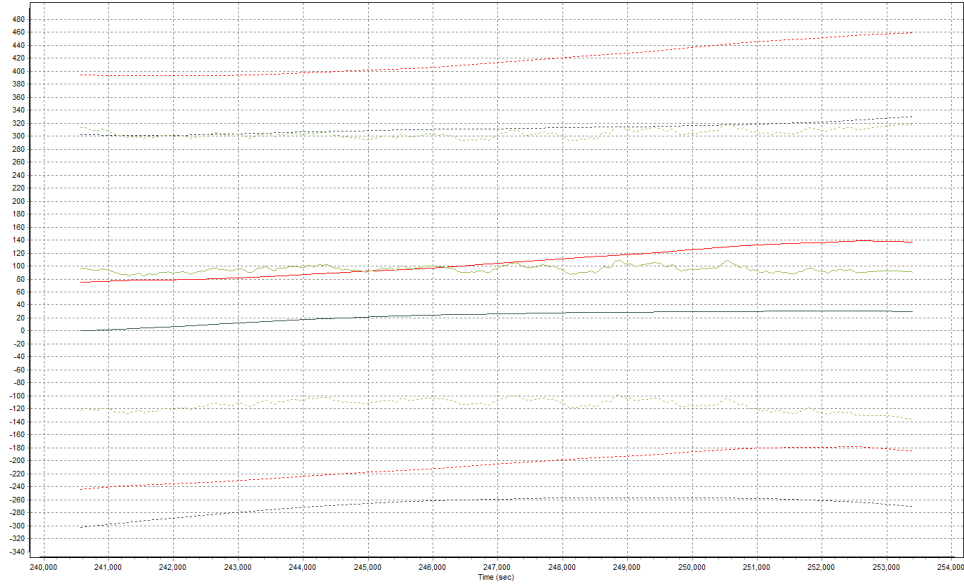


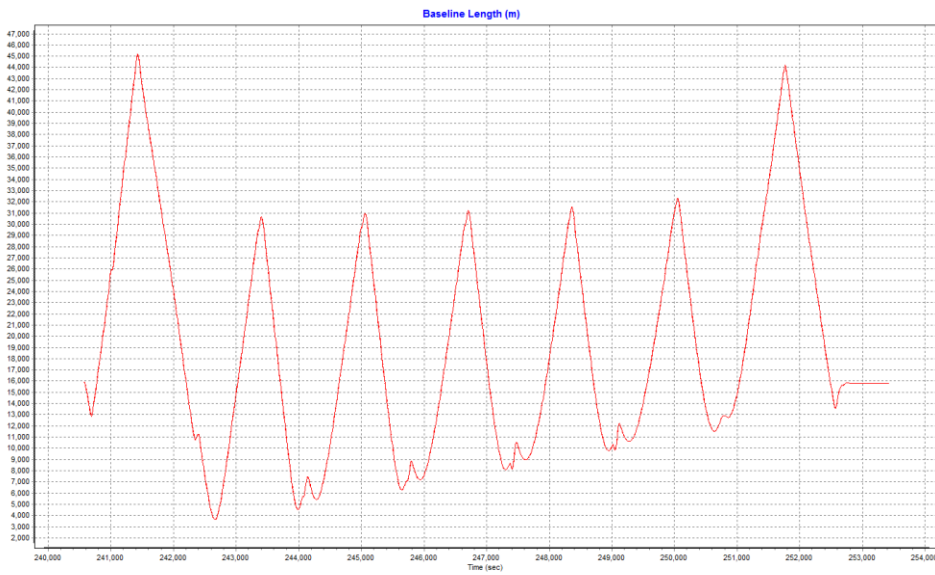
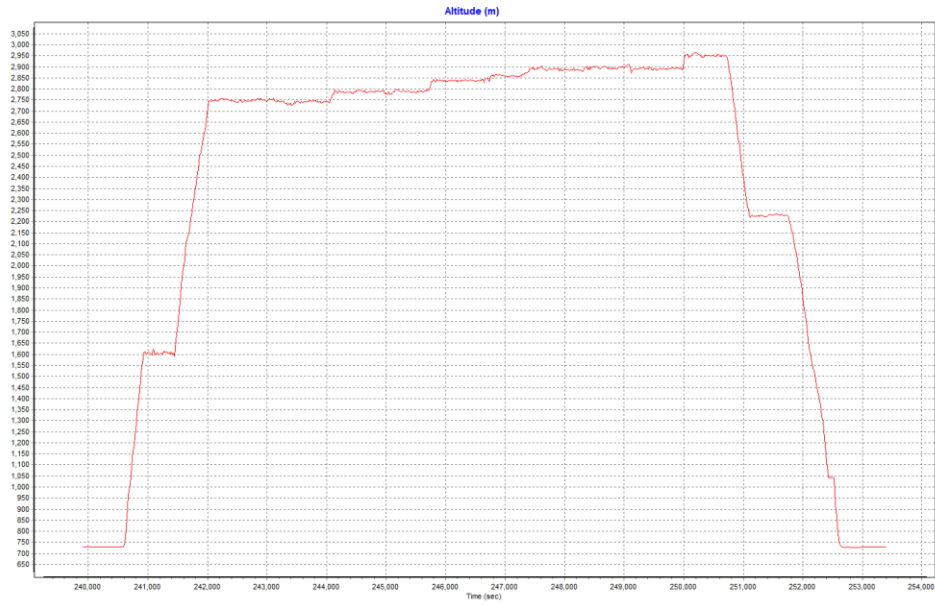
Forward  Reverse

0 = Fixed NL, 1 = Fixed VL, 2 = Float, 3 = DGNS, 4 = RTCM, 5 = IAPPP, 6 = C/A, 7 = GNSS Nav, 8 = DR



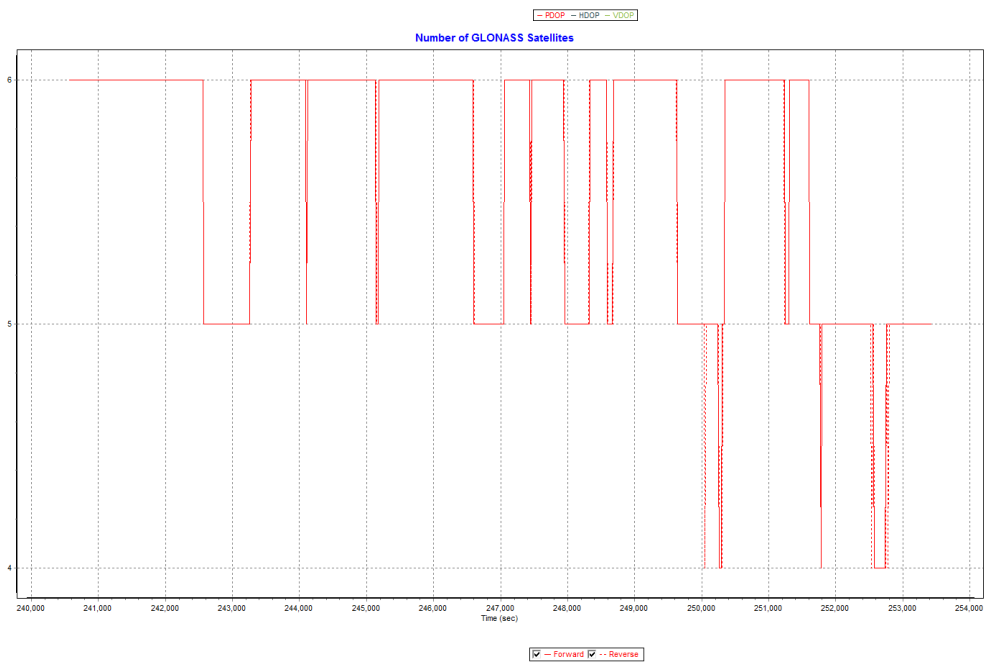
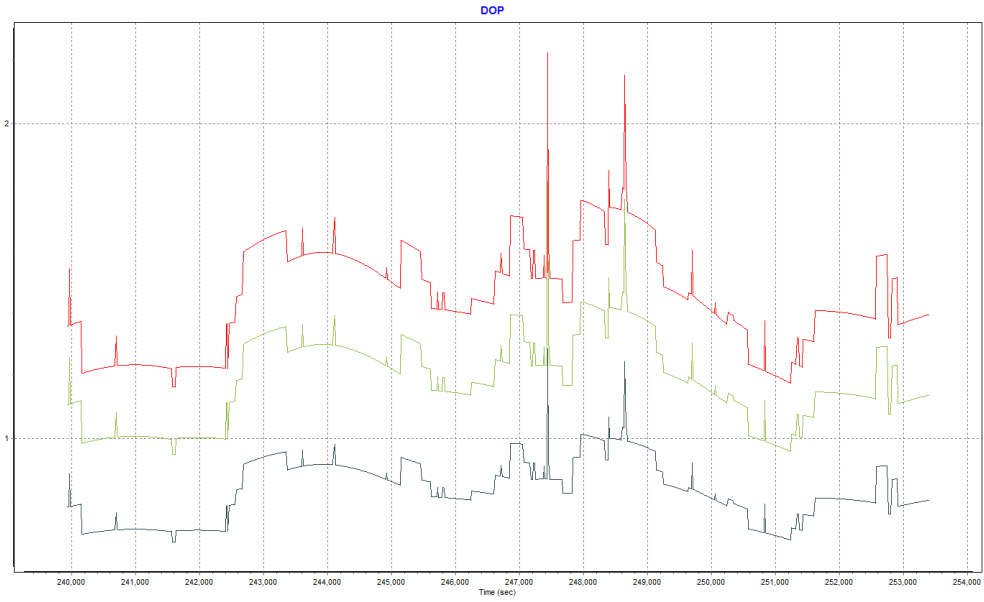
# CAU16327B



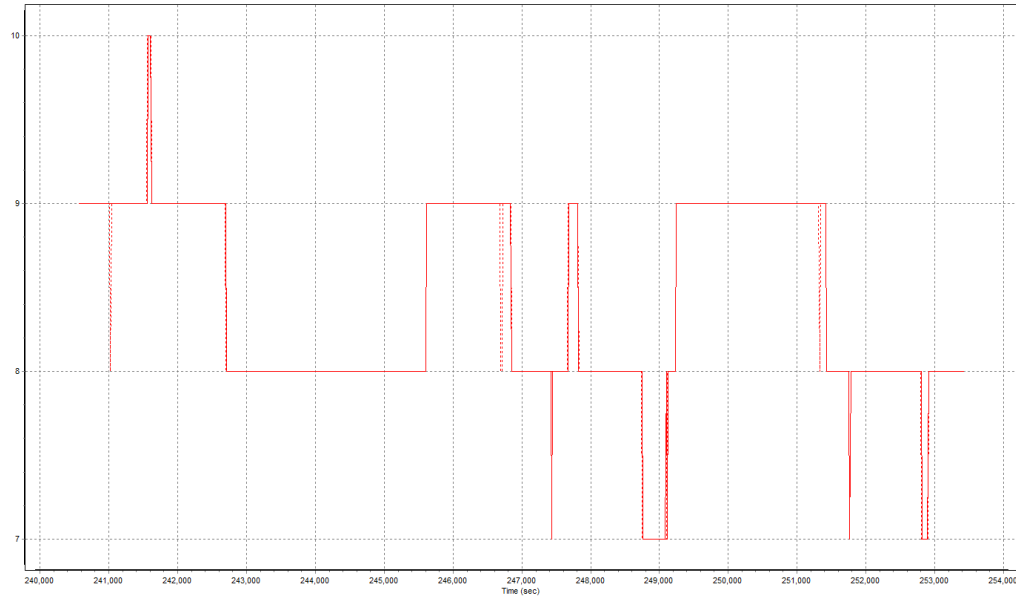


Forward  Reverse

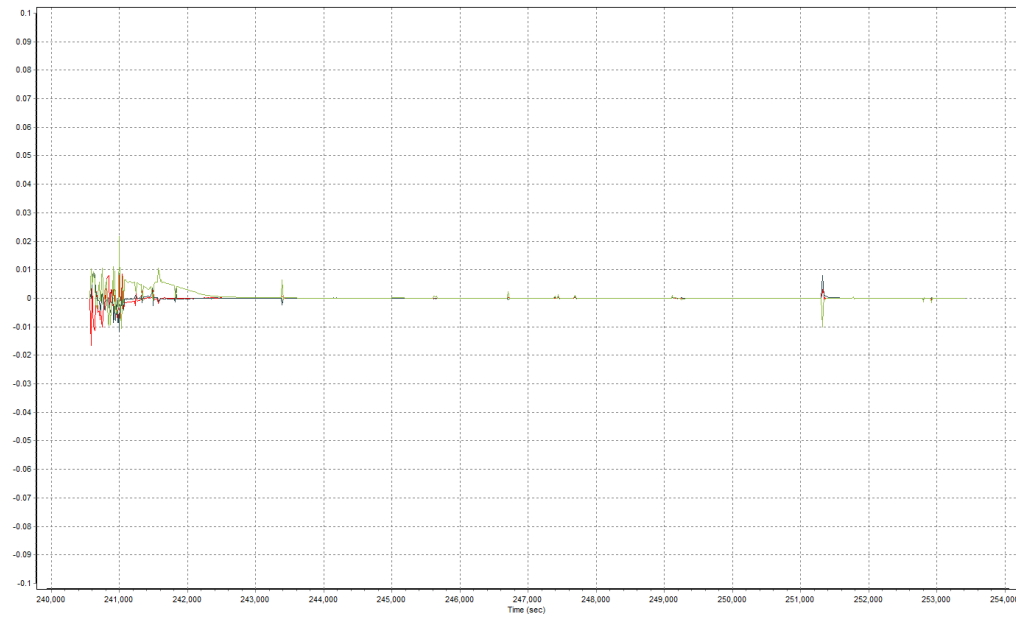




Number of GPS Satellites

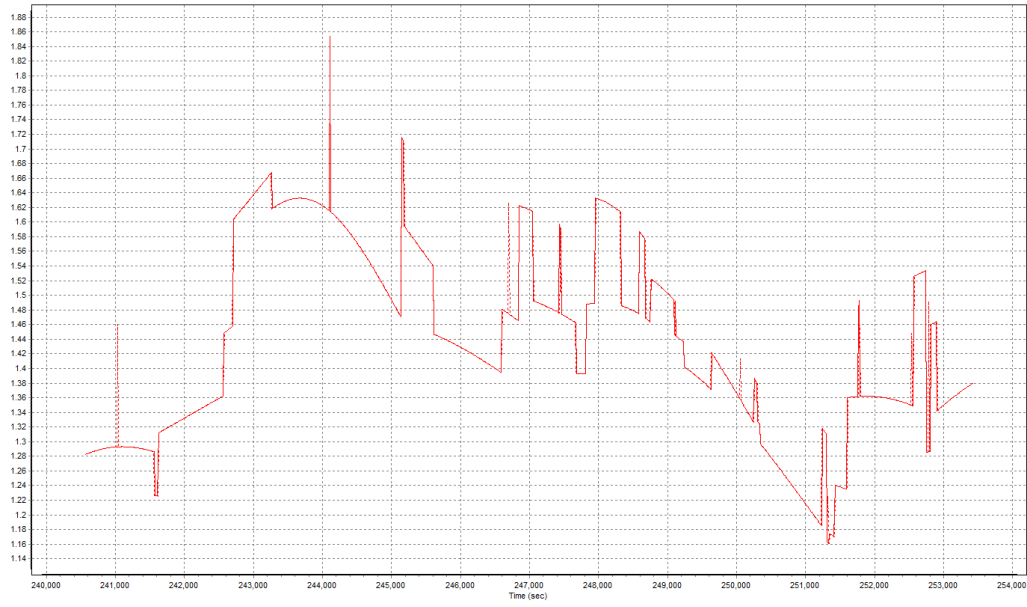


Forward  Reverse



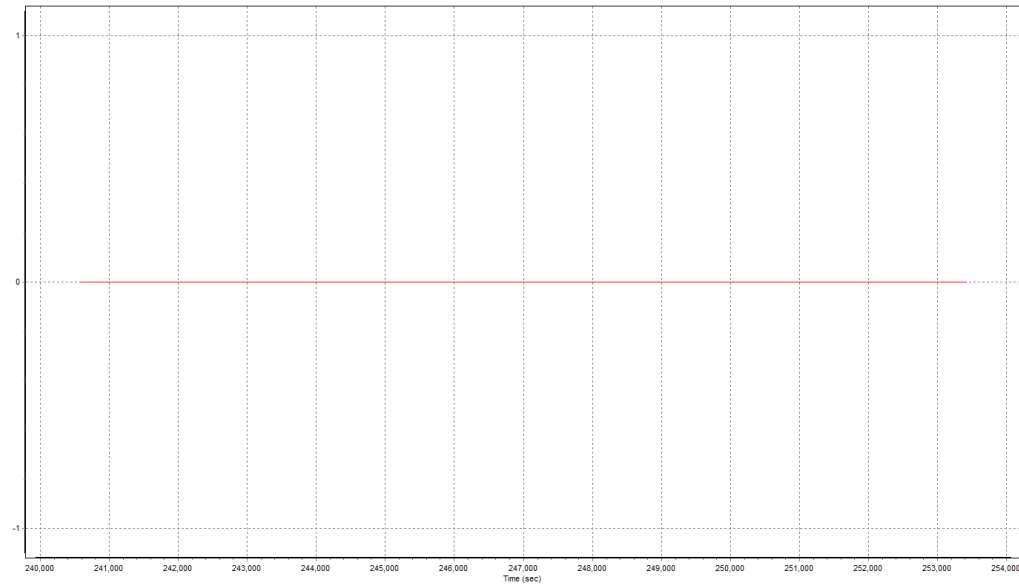
North (m)  East (m)  Down (m)  DR mode

PDOP



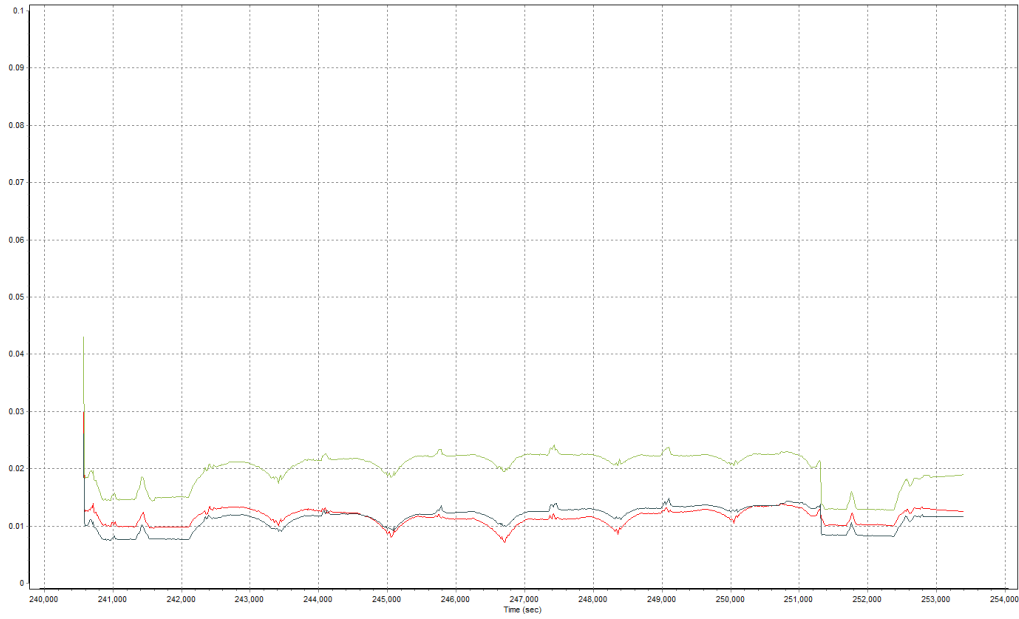
Forward  Reverse

Processing mode

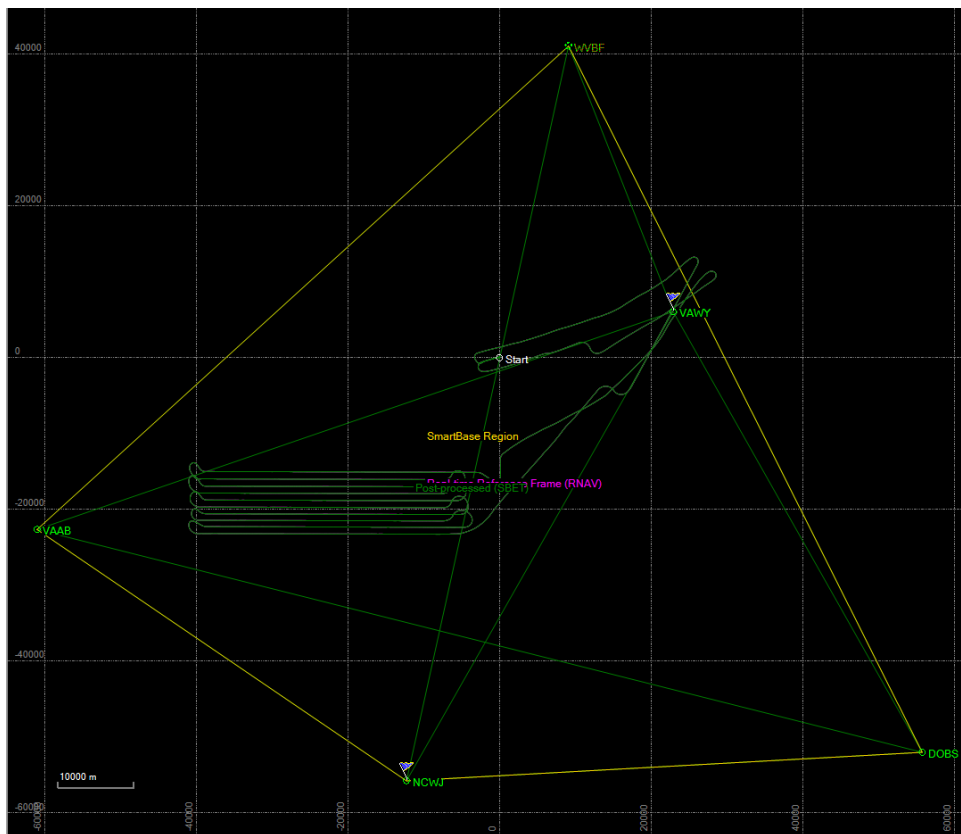


Forward  Reverse

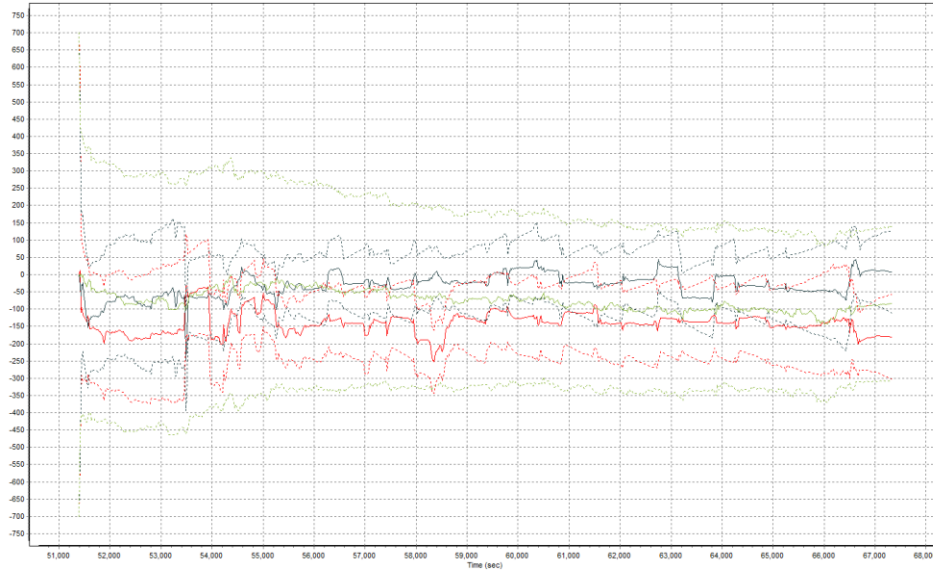
0 = Fixed NL, 1 = Fixed VL, 2 = Float, 3 = DGSS, 4 = RTCM, 5 = IARPP, 6 = CIA, 7 = GNSS Nav, 8 = DR



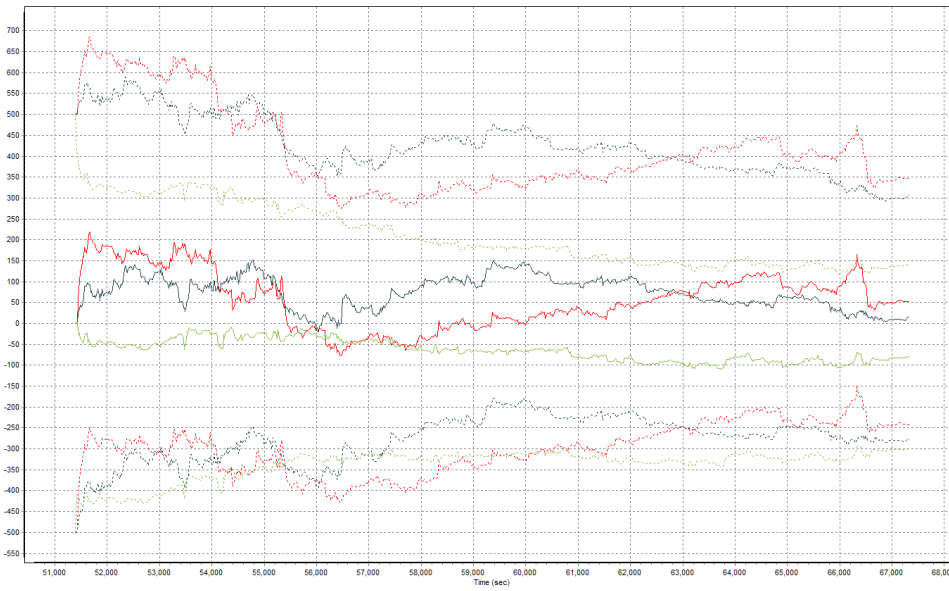
— North Position Error RMS (m) — East Position Error RMS (m) — Down Position Error RMS (m)



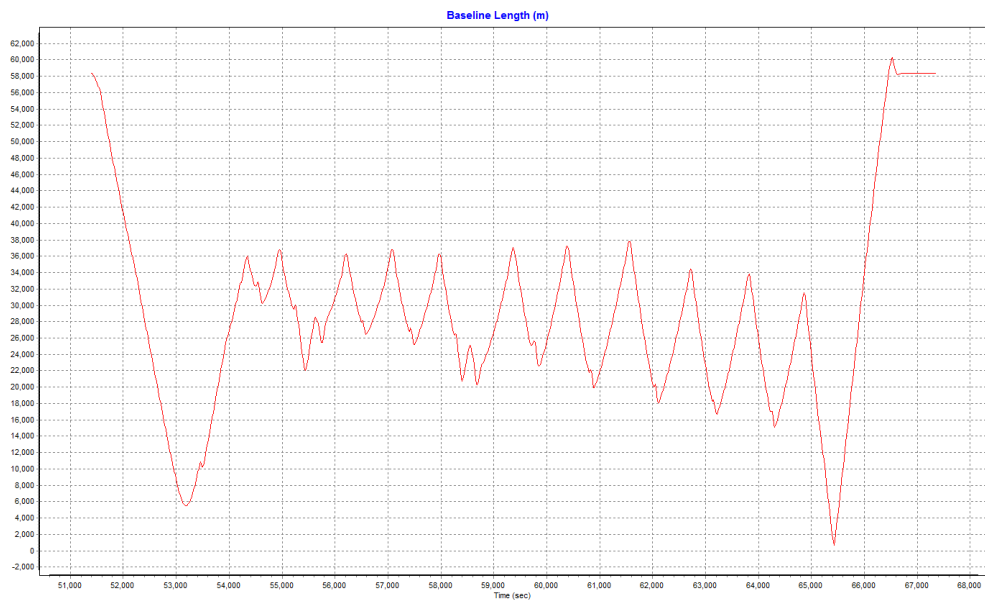
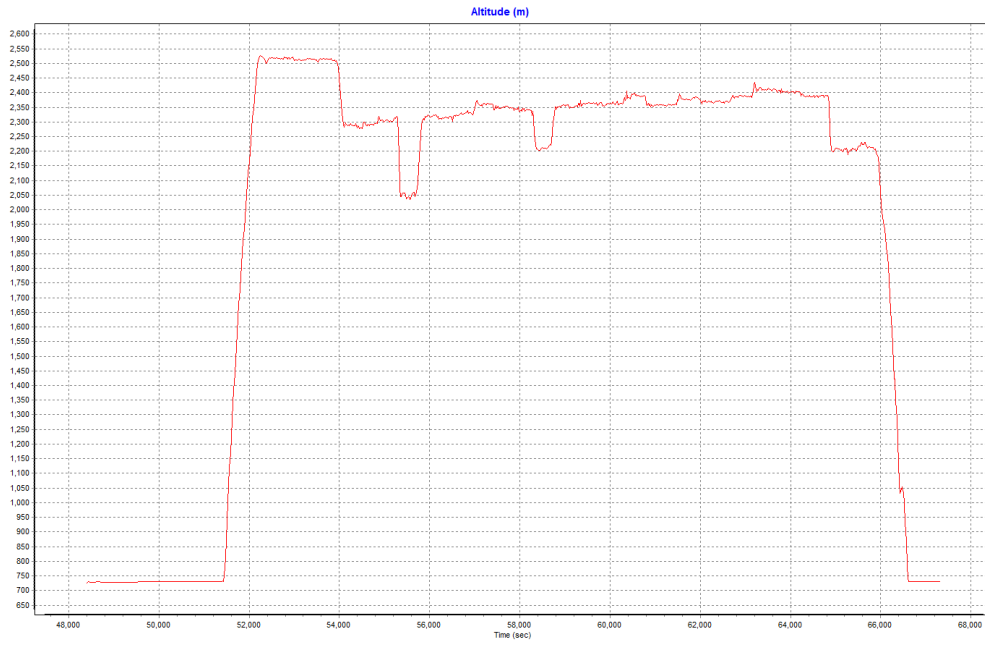
# CAU16332A



x accelerometer bias (micro-g) y accelerometer bias (micro-g) z accelerometer bias (micro-g)

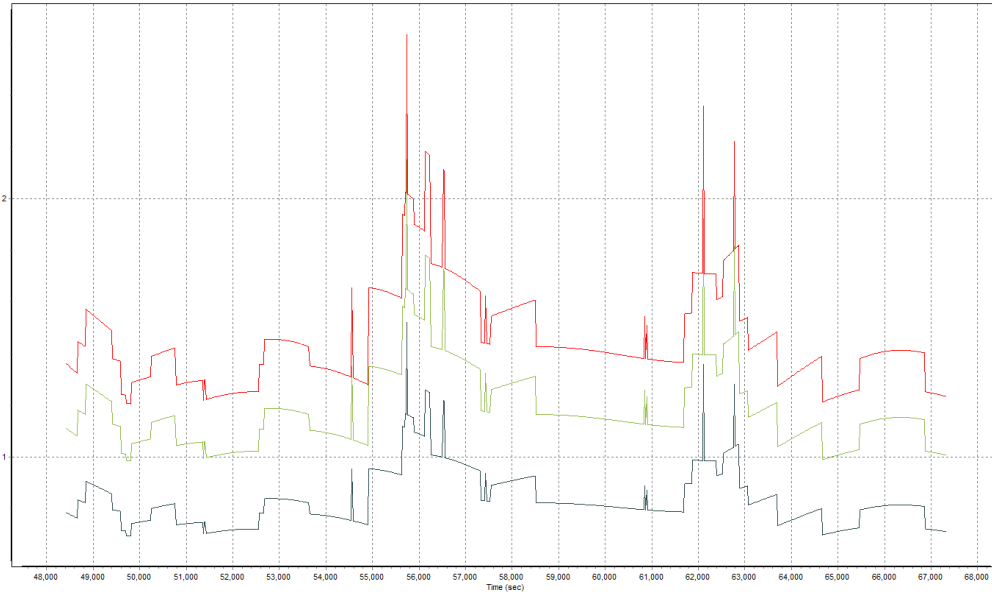


x accelerometer scale error (ppm) y accelerometer scale error (ppm) z accelerometer scale error (ppm)

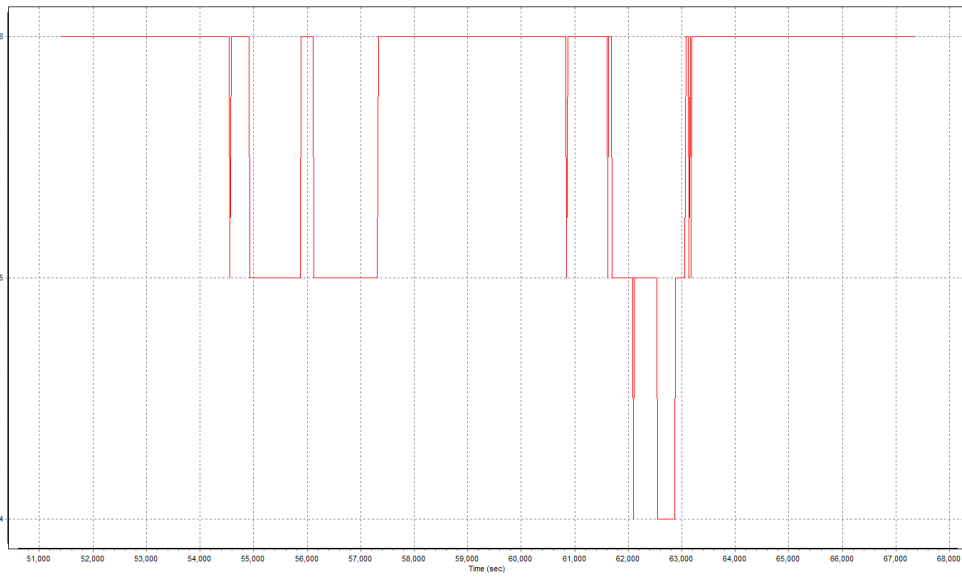


Forward  Reverse

DOP

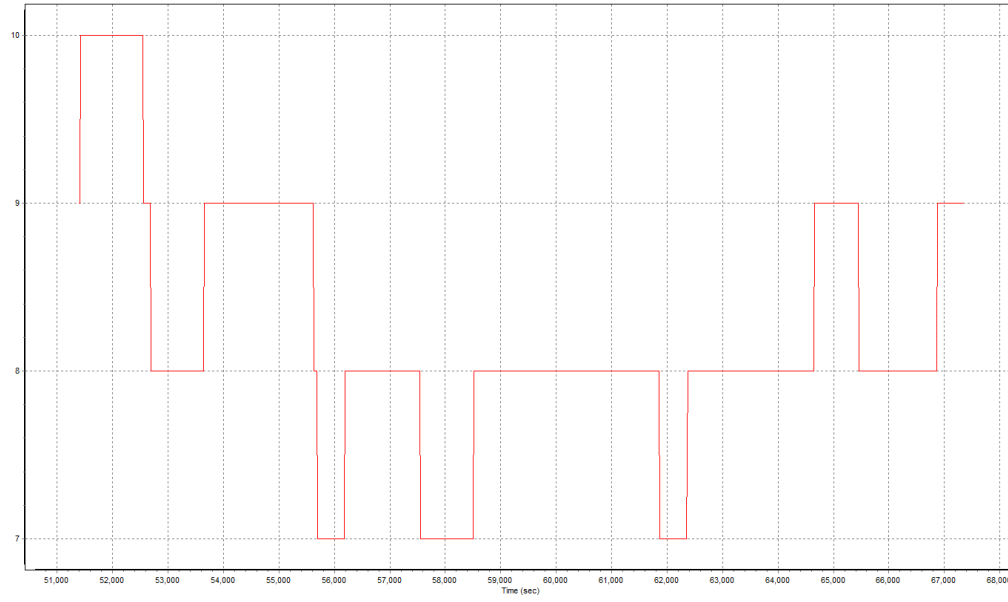


Number of GLONASS Satellites



Forward Reverse

Number of GPS Satellites



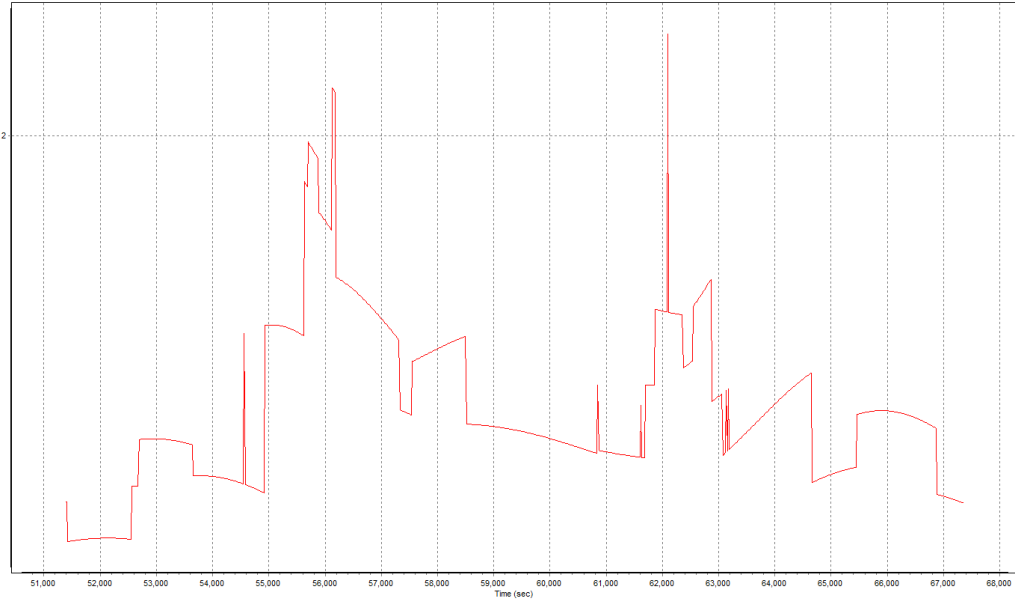
Forward  Reverse



North (m) East (m) Down (m) DR mode

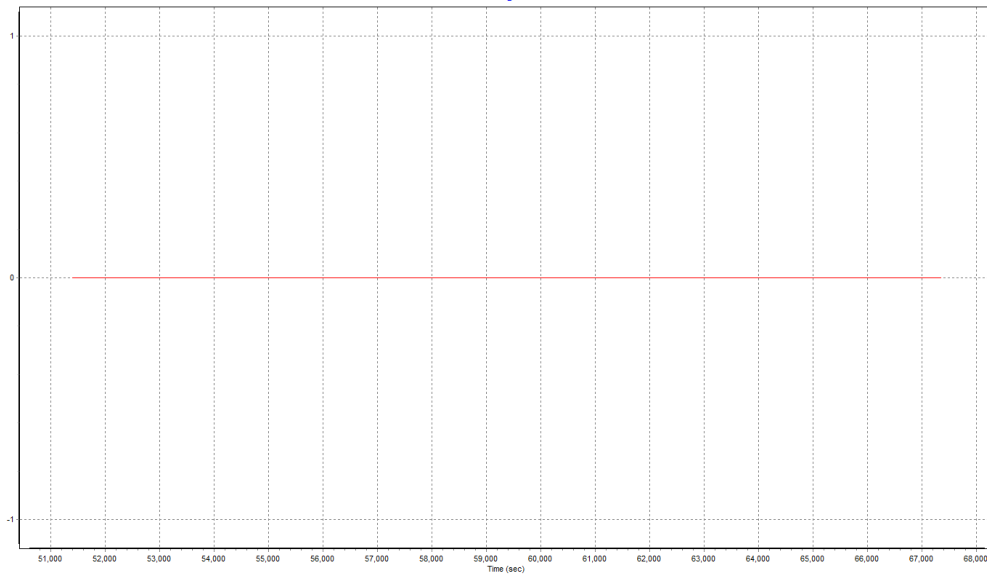


PDOP



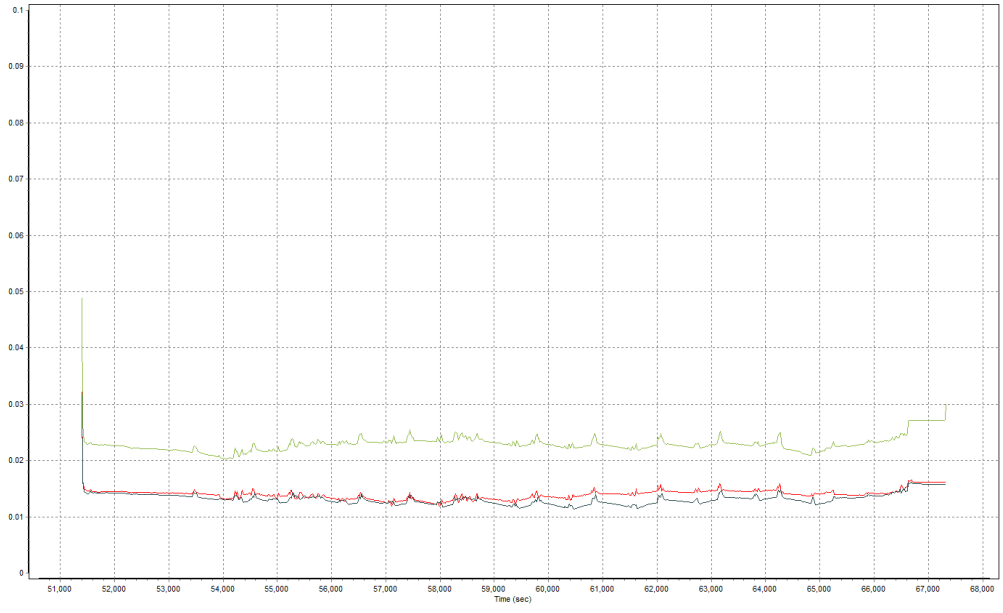
Forward  Reverse

Processing mode

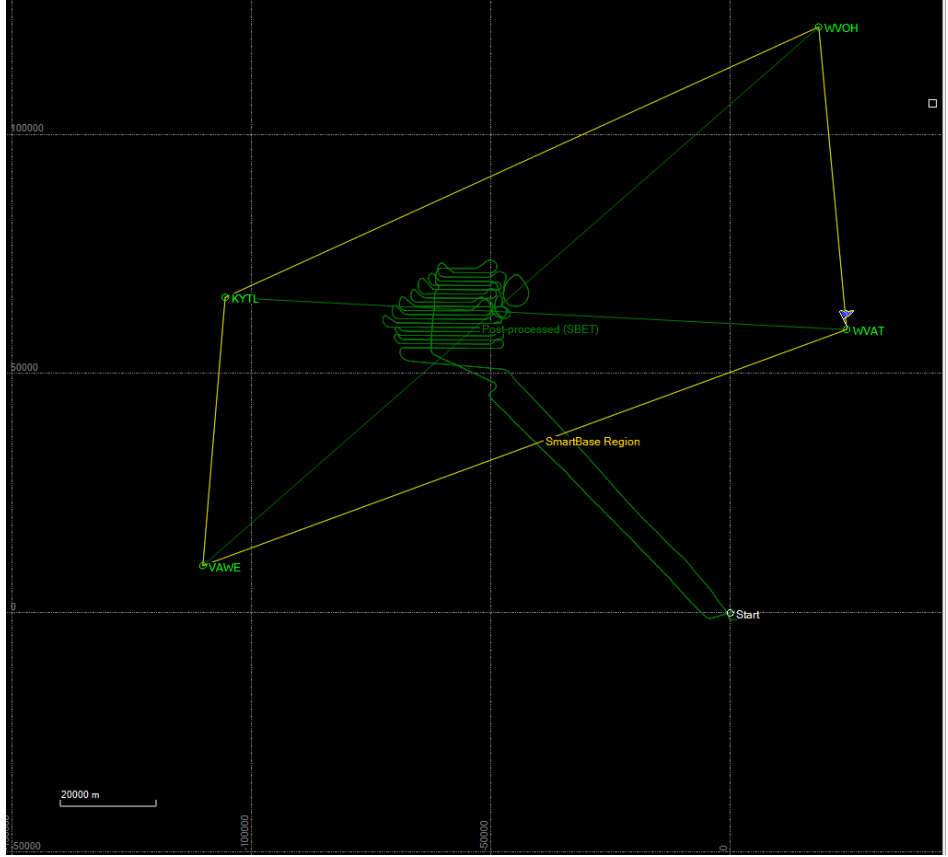


Forward  Reverse

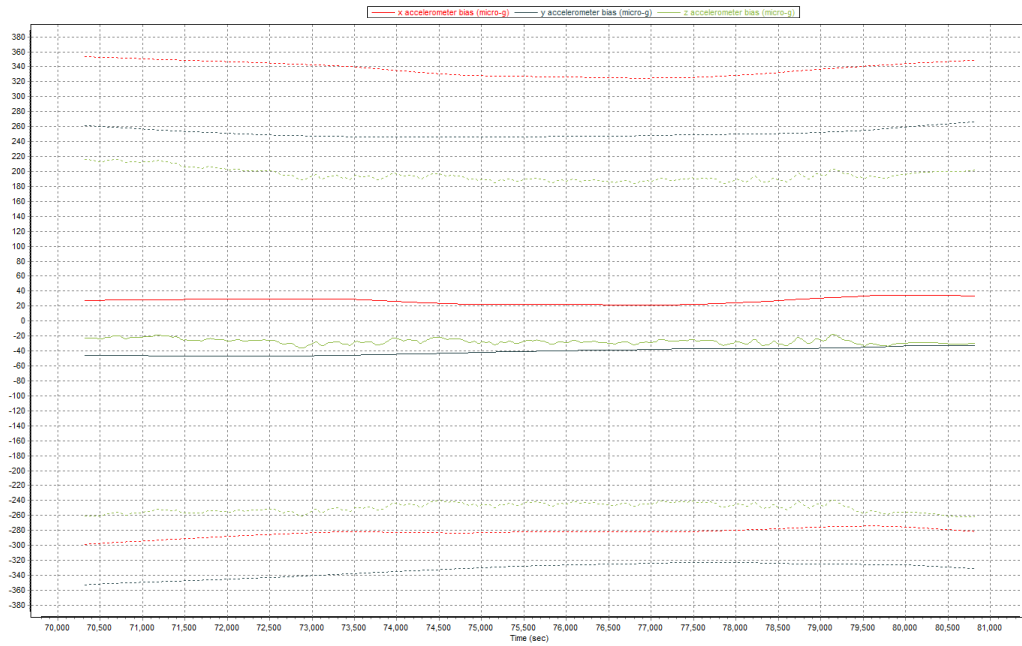
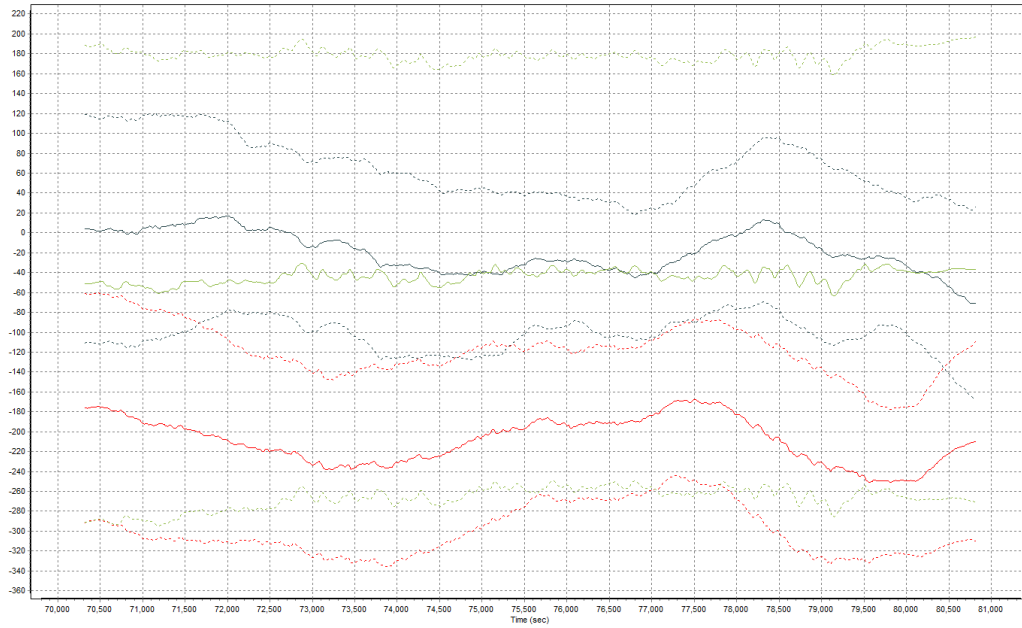
0 = Fixed NL, 1 = Fixed WL, 2 = Fixat, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = GA, 7 = GNSS Nav, 8 = DR

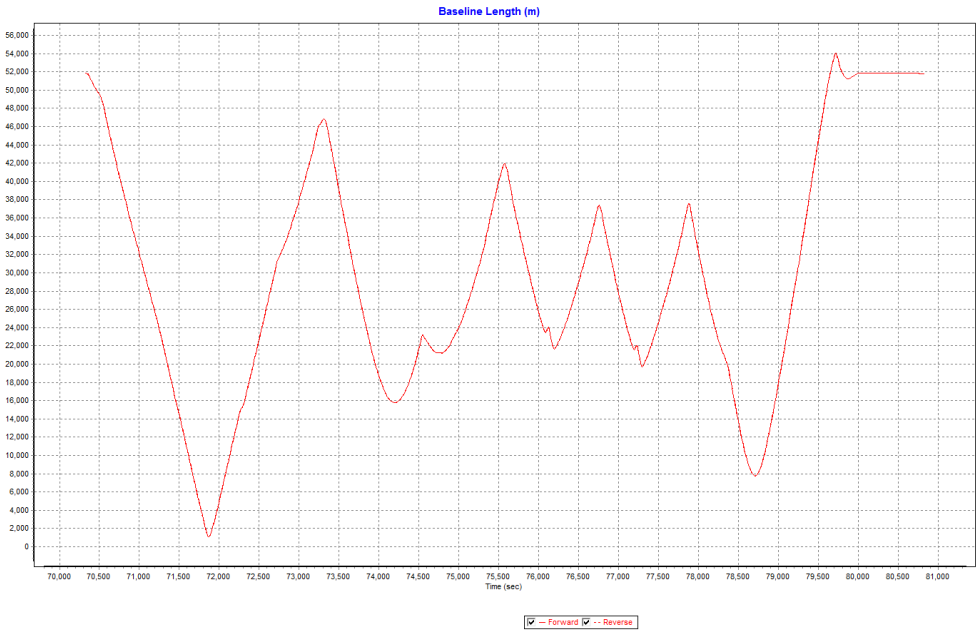
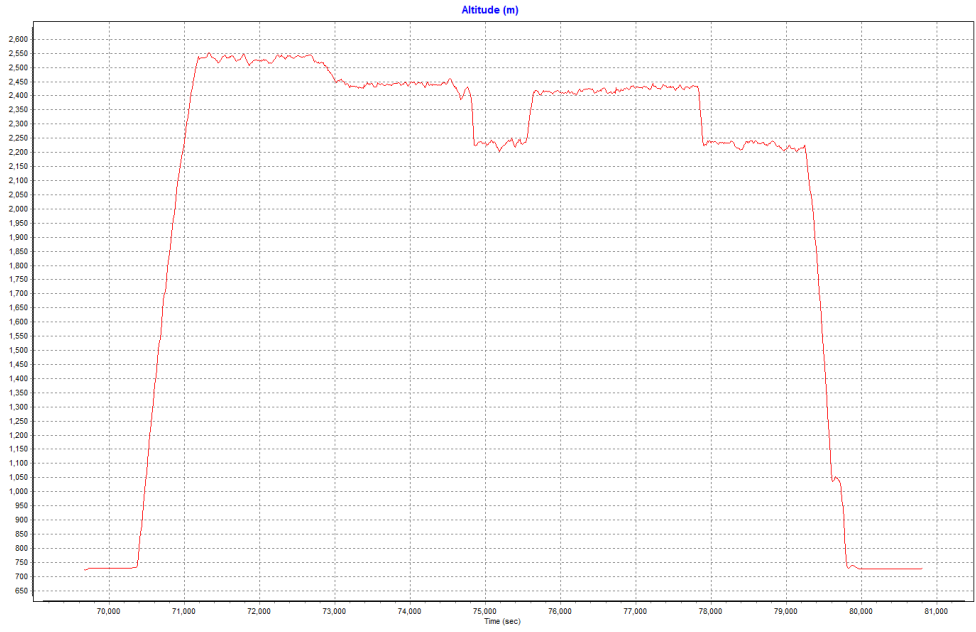


— North Position Error RMS (m) — East Position Error RMS (m) — Down Position Error RMS (m)

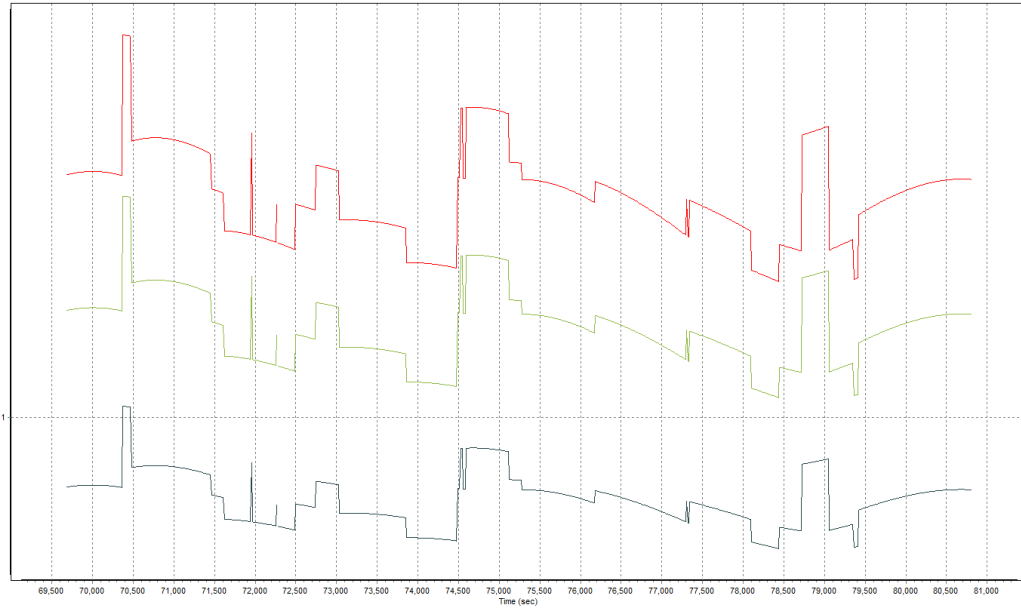


# CAU16332B



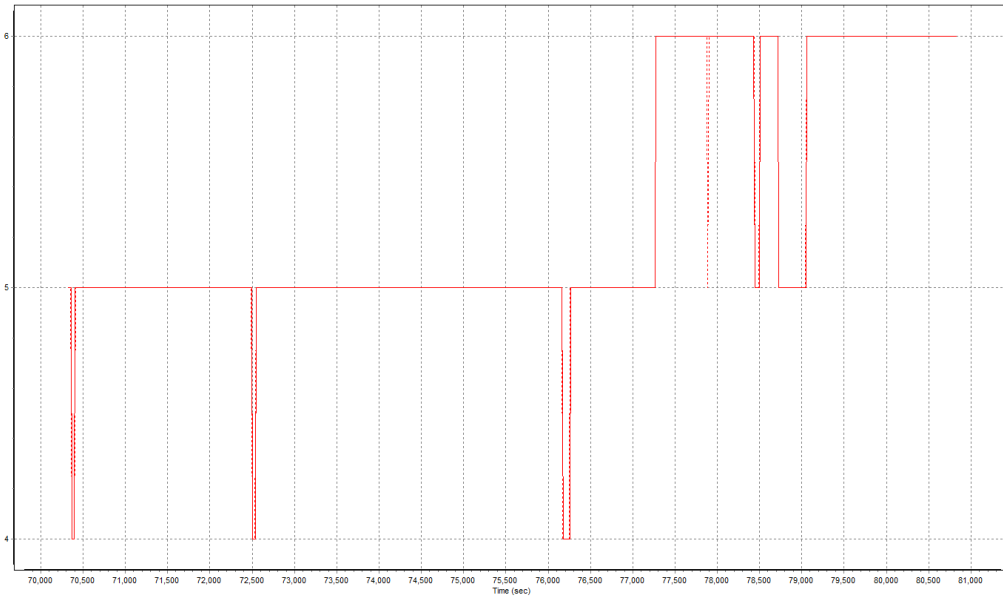


DOP



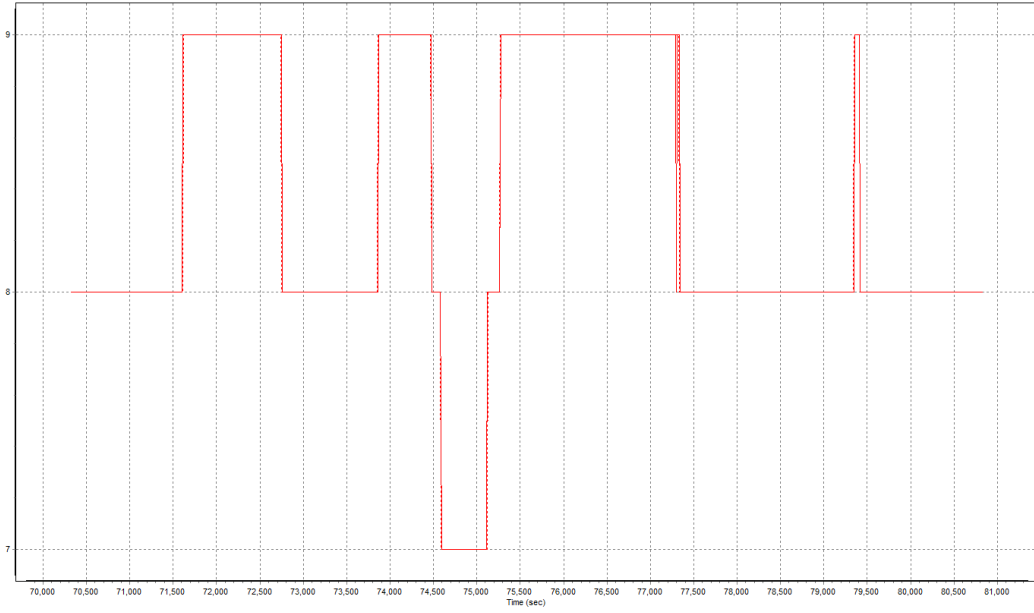
— PDOP — HDOP — VDOP

Number of GLONASS Satellites

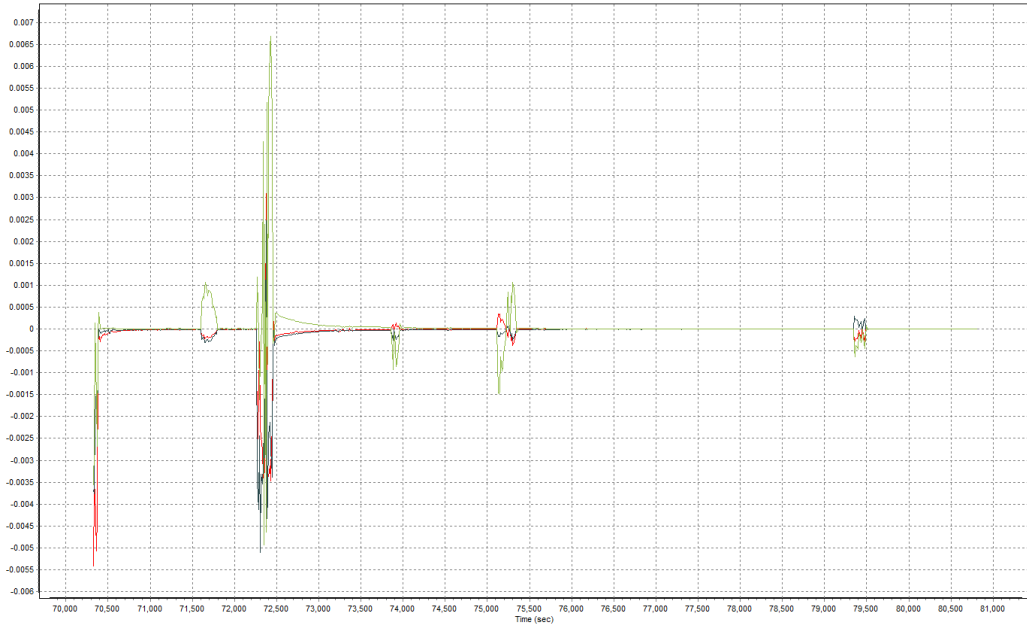


Forward  Reverse

Number of GPS Satellites



Forward  Reverse



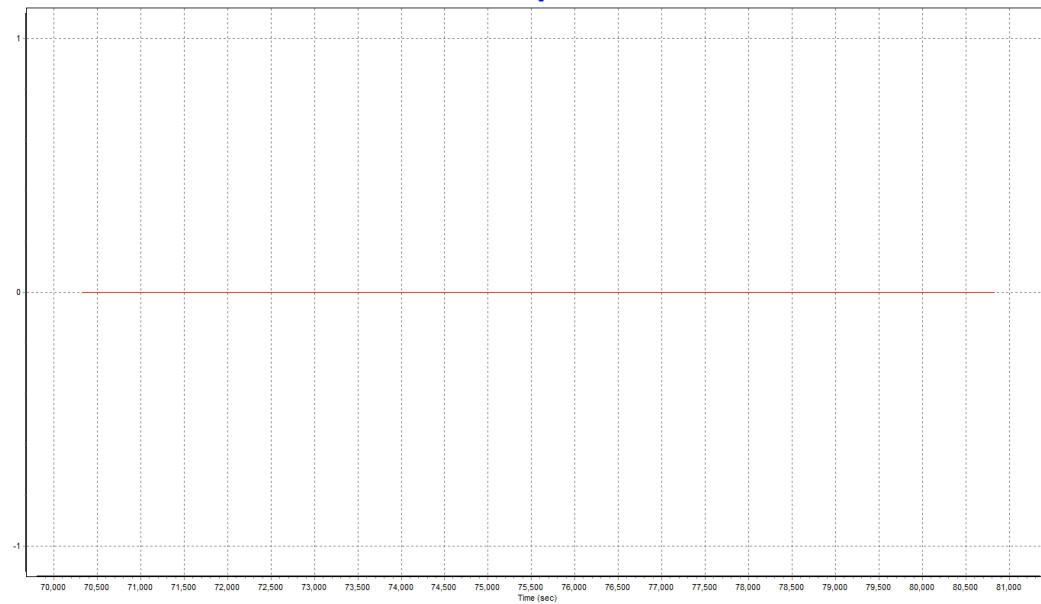
North (m)  East (m)  Down (m)  DR mode

PDOP



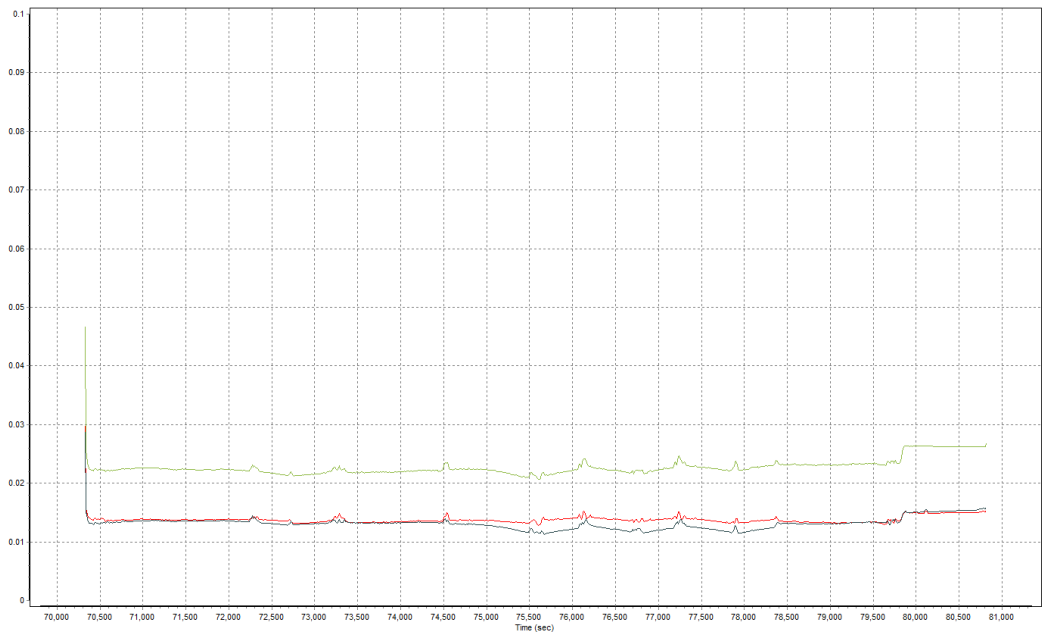
Forward  Reverse

Processing mode

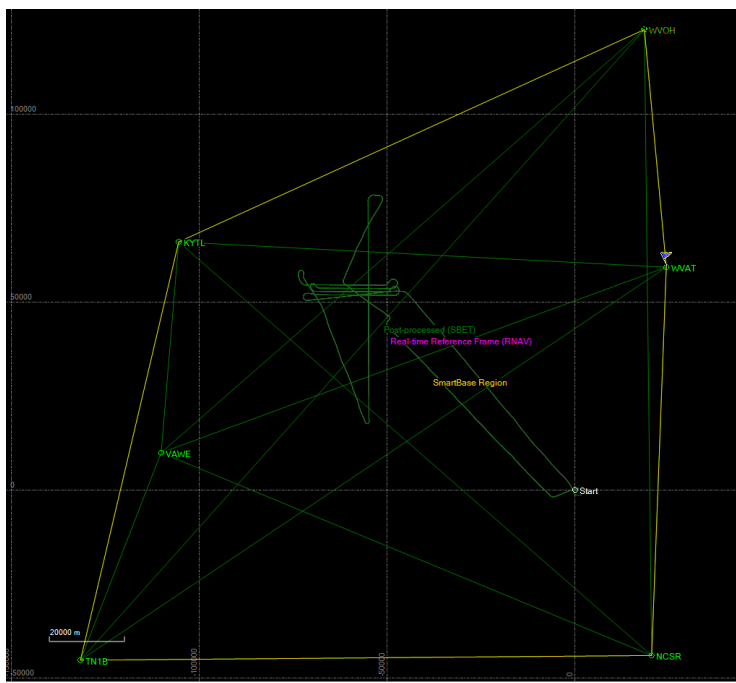


Forward  Reverse

0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNS, 4 = RTCM, 5 = IAPPP, 6 = CIA, 7 = GNSS Nav, 8 = DR

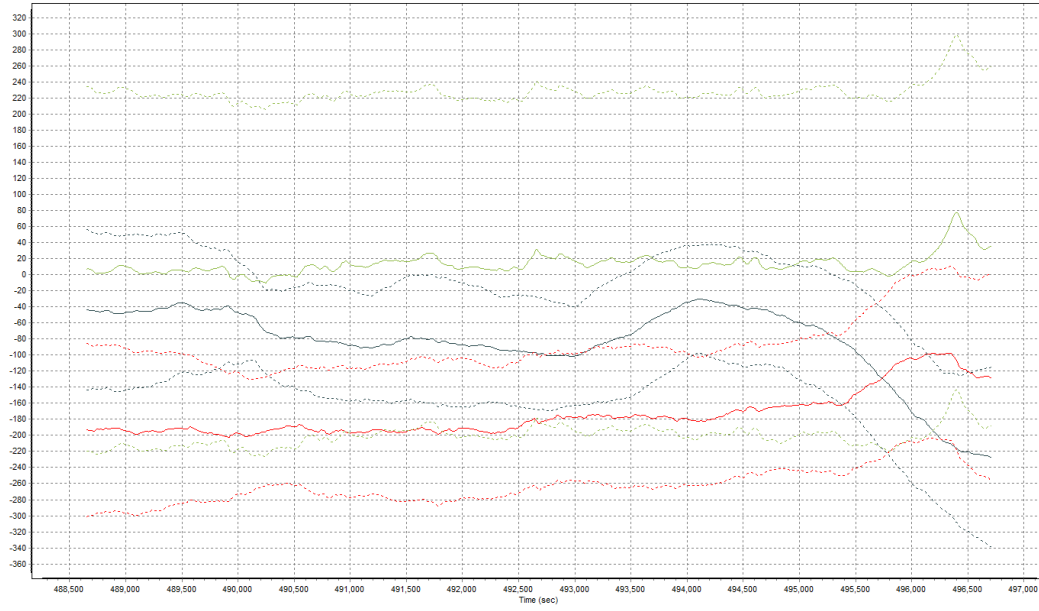


— North Position Error RMS (m) — East Position Error RMS (m) — Down Position Error RMS (m)

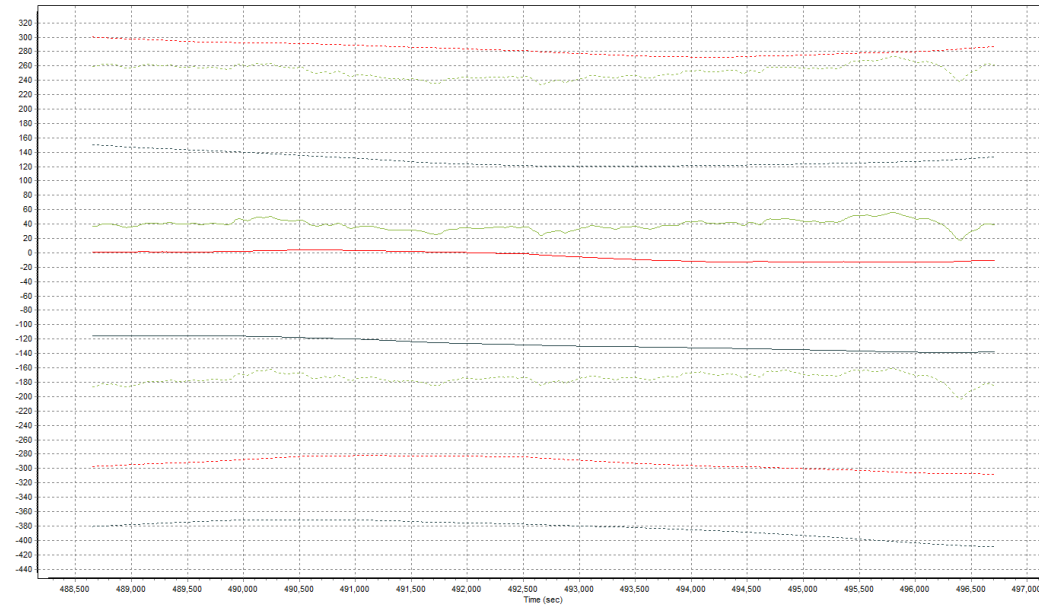




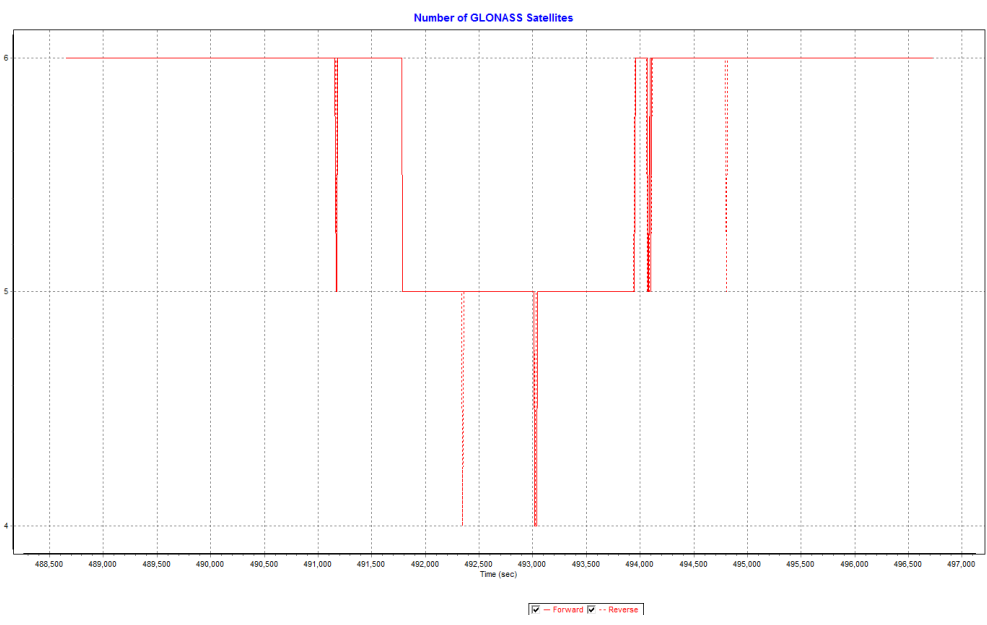
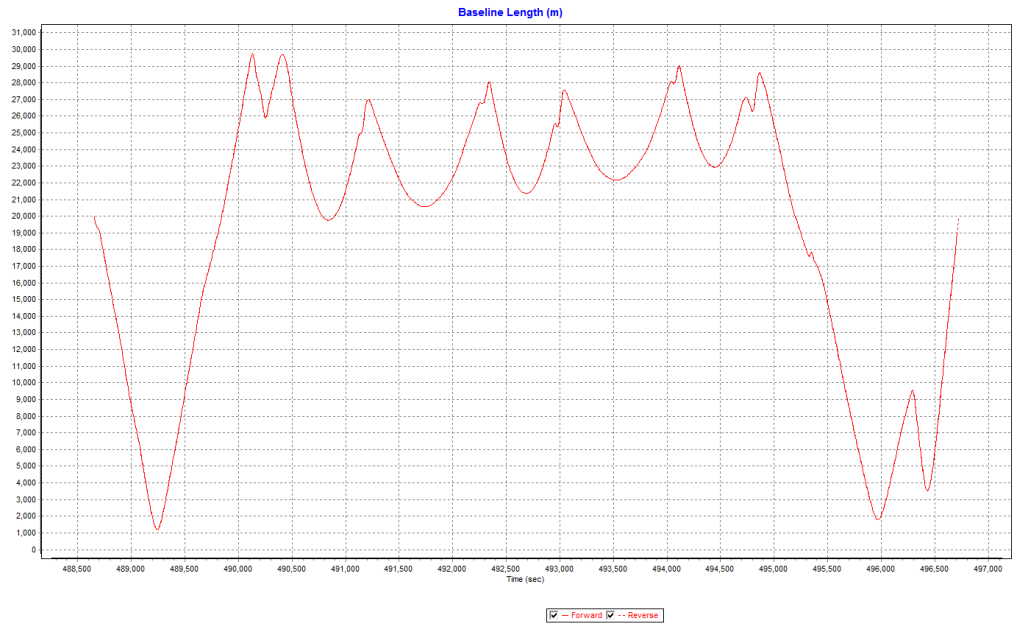
# CAU16337A



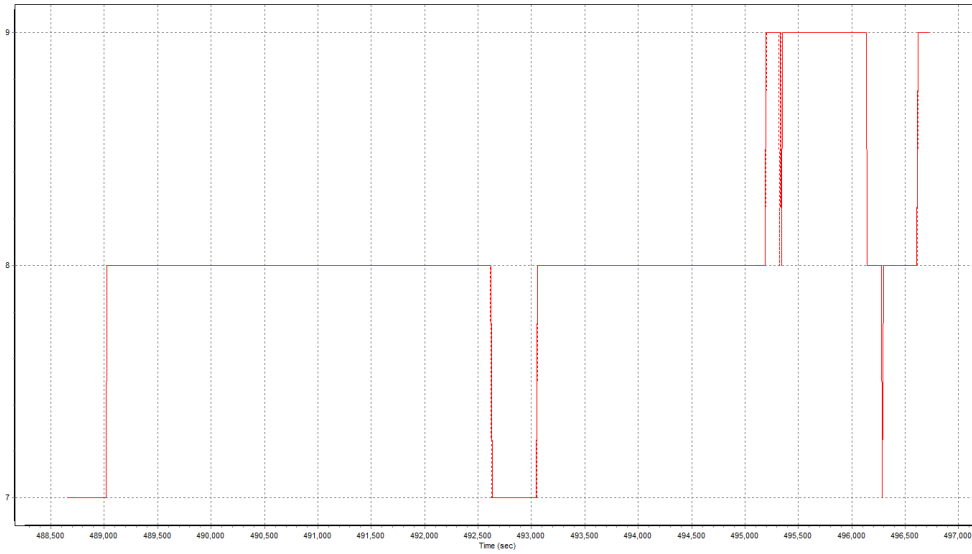
x accelerometer bias (micro-g) y accelerometer bias (micro-g) z accelerometer bias (micro-g)



x accelerometer scale error (ppm) y accelerometer scale error (ppm) z accelerometer scale error (ppm)



Number of GPS Satellites

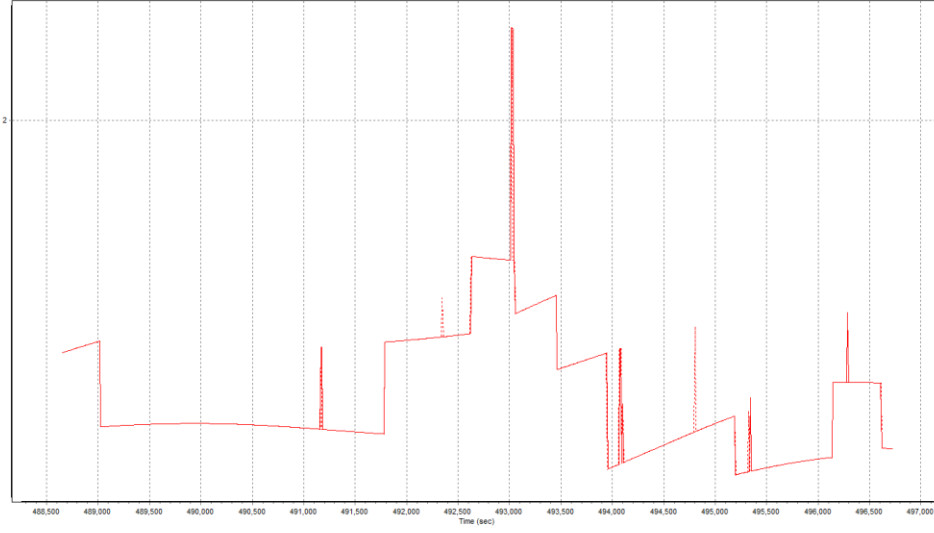


Forward  Reverse



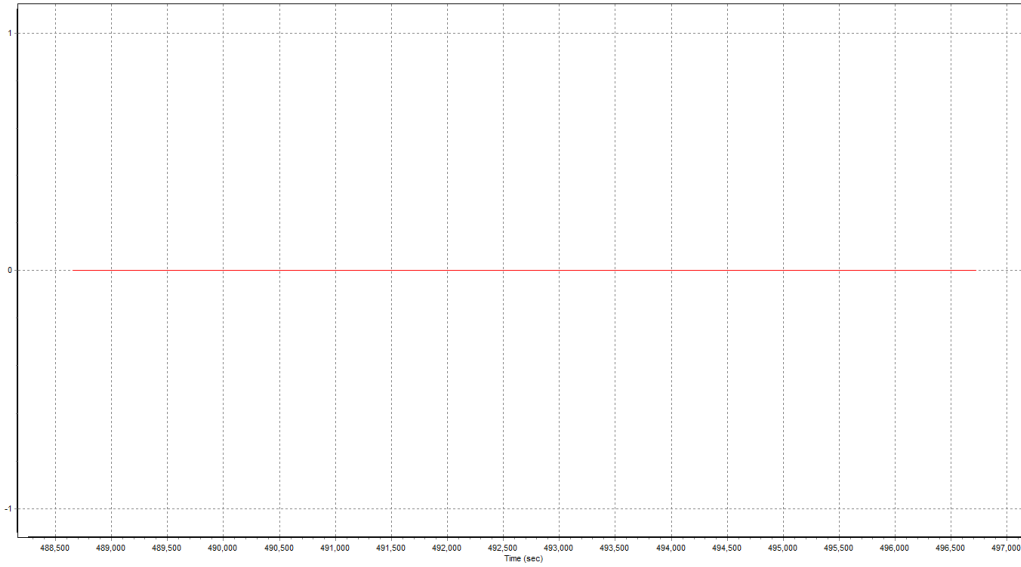
North (m)  East (m)  Down (m)  DR mode

PDOP



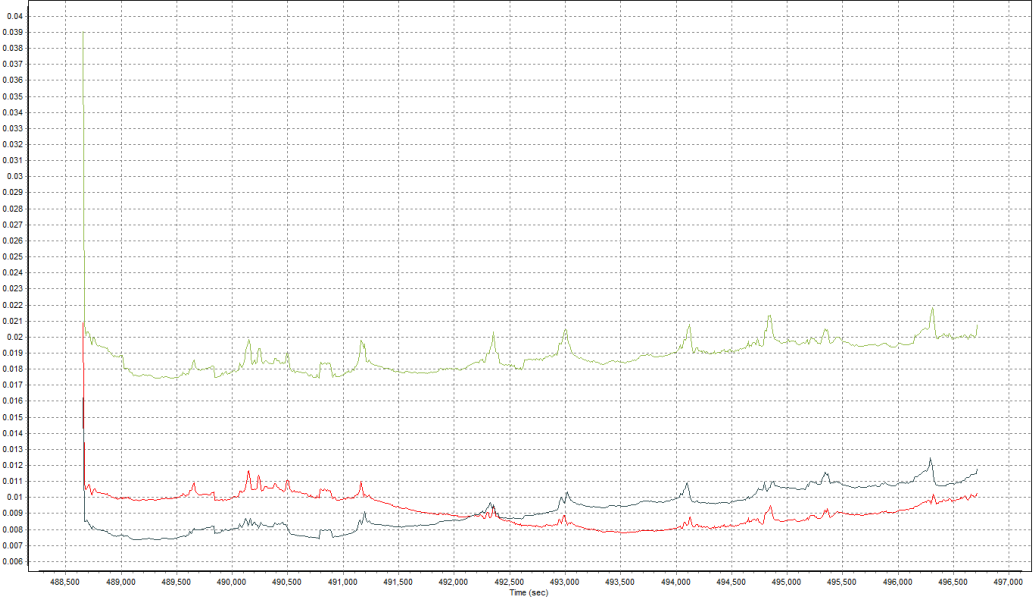
Forward  Reverse

Processing mode

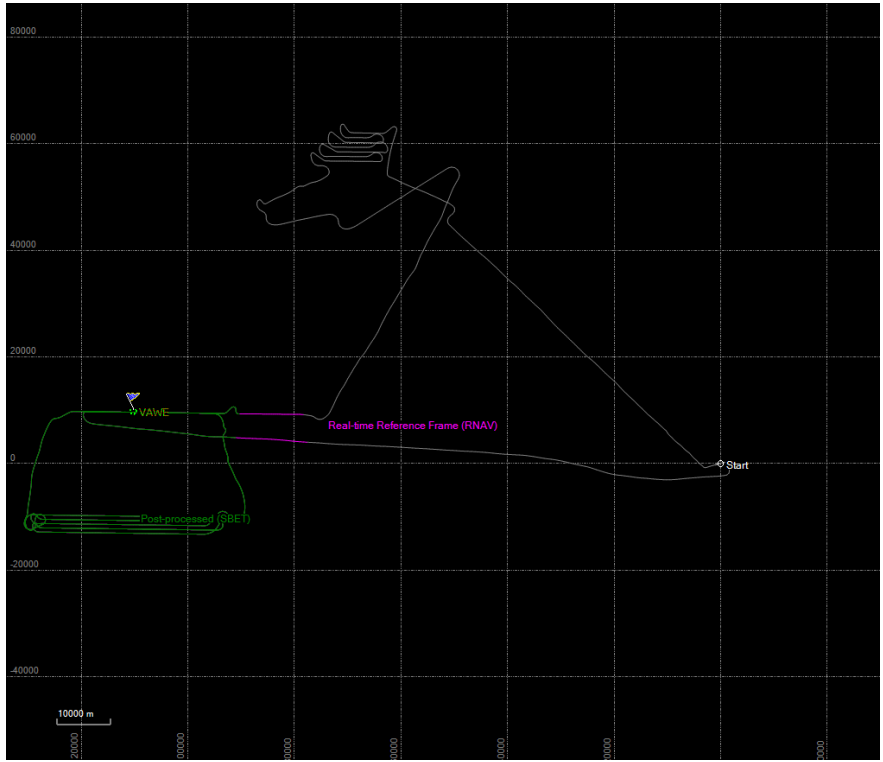


Forward  Reverse

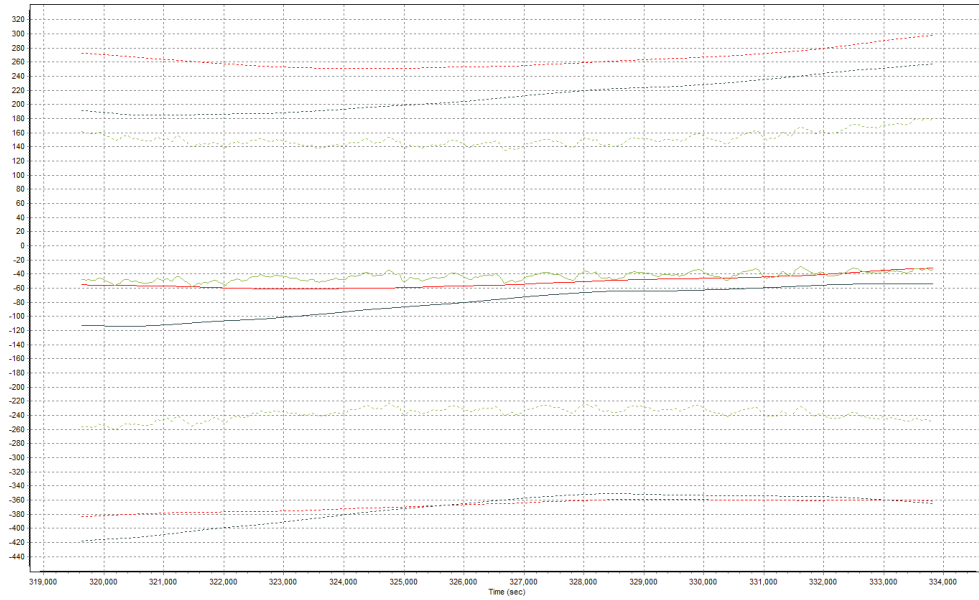
0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IARPP, 6 = CIA, 7 = GNSS Nav, 8 = DR



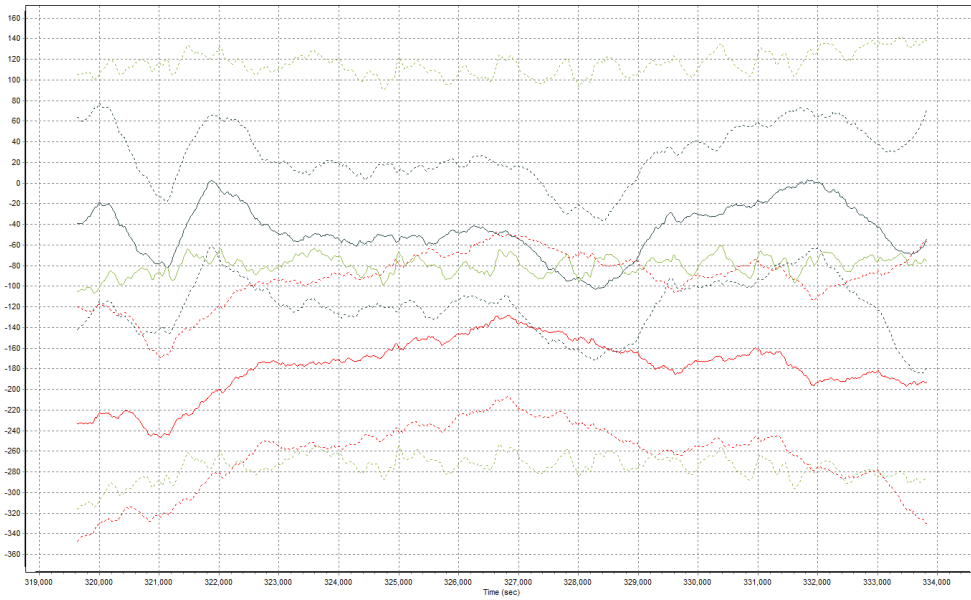
— North Position Error RMS (m) — East Position Error RMS (m) — Down Position Error RMS (m)



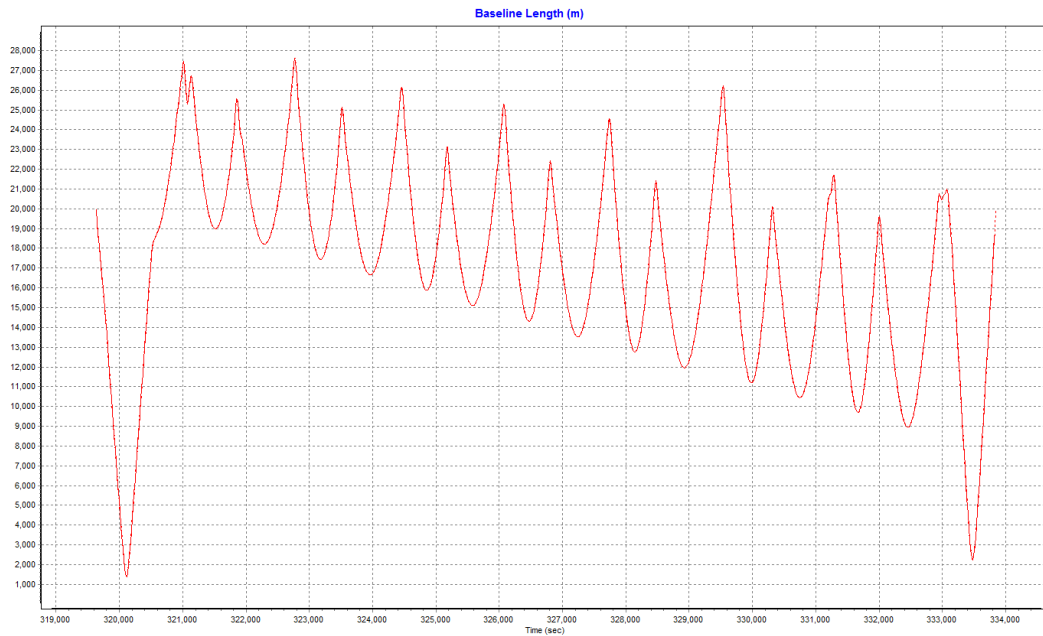
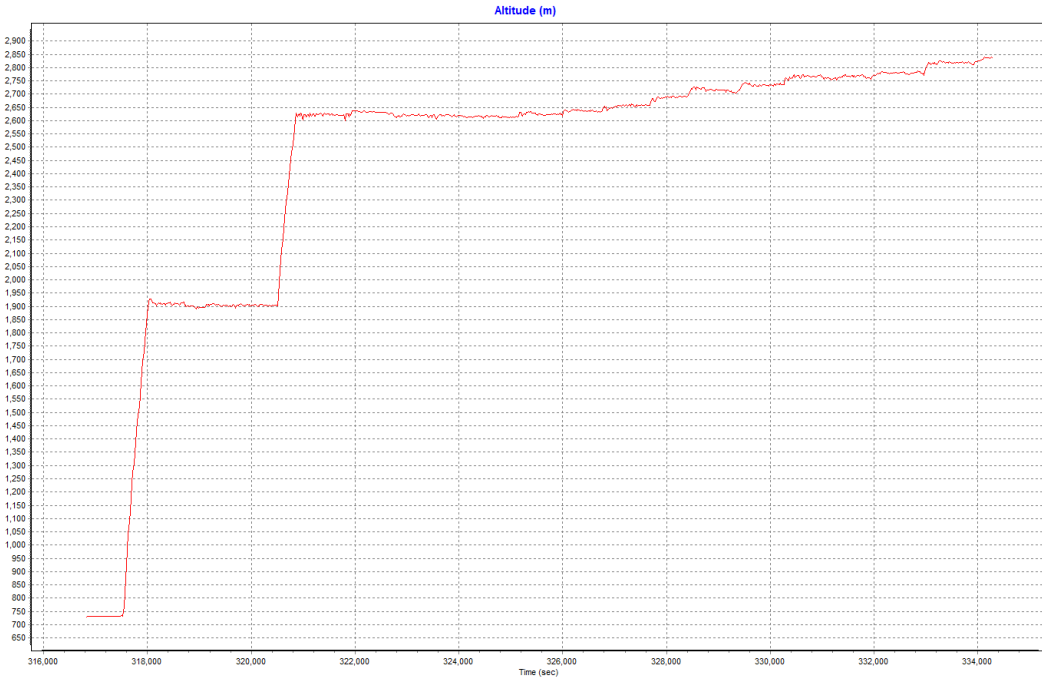
# CAU16342A



x accelerometer scale error (ppm) y accelerometer scale error (ppm) z accelerometer scale error (ppm)

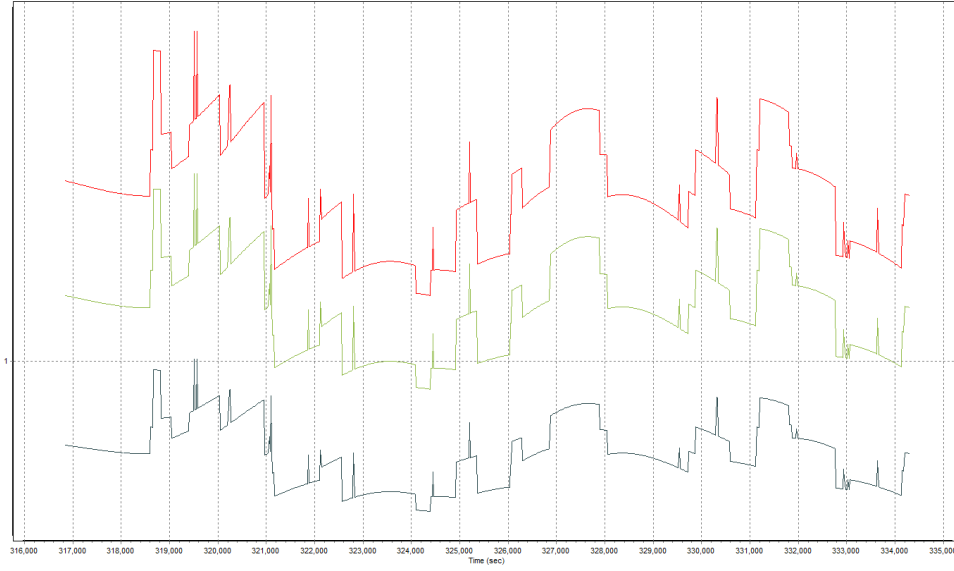


x accelerometer bias (micro-g) y accelerometer bias (micro-g) z accelerometer bias (micro-g)

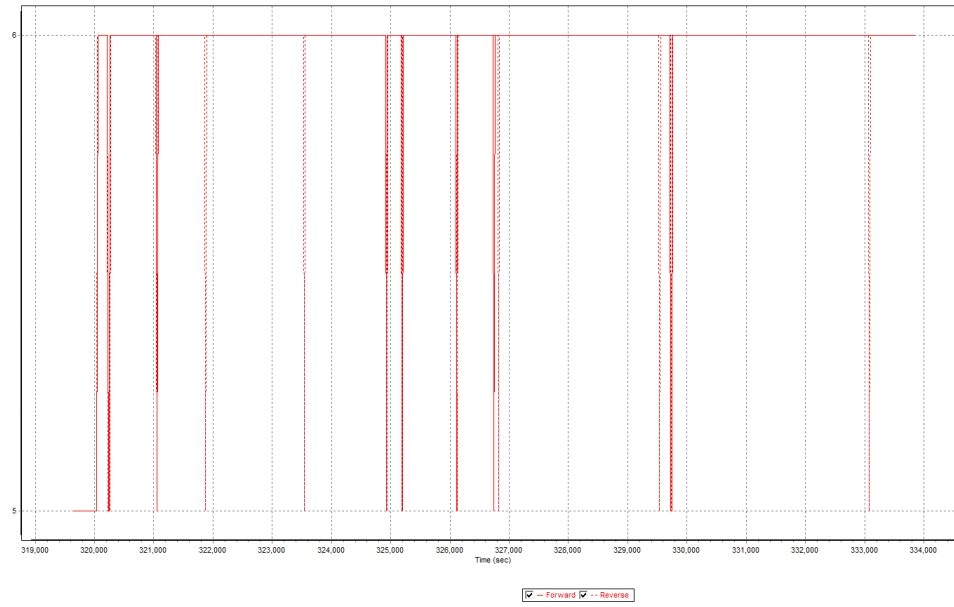


Forward  Reverse

DOP

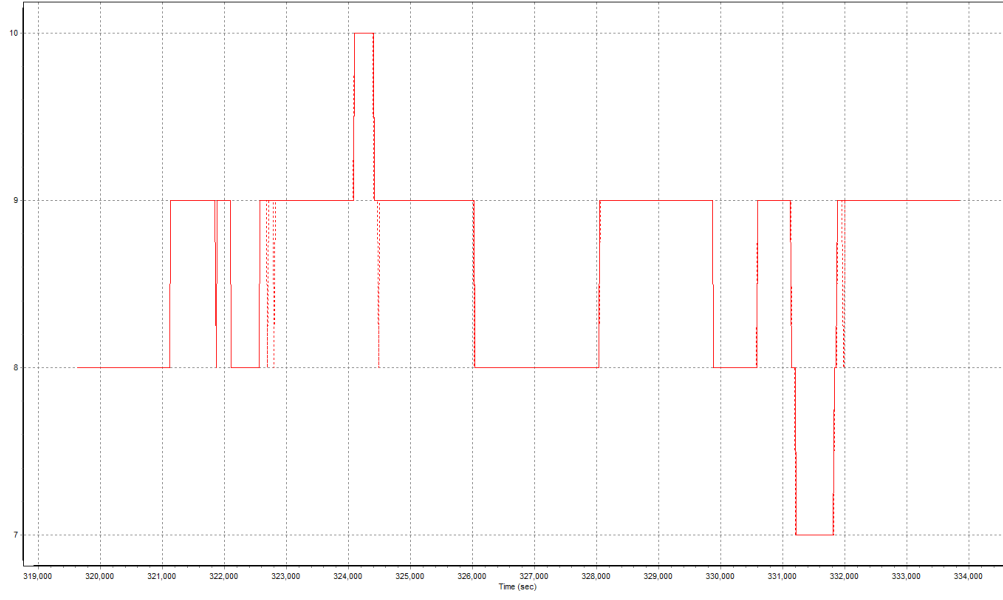


Number of GLONASS Satellites

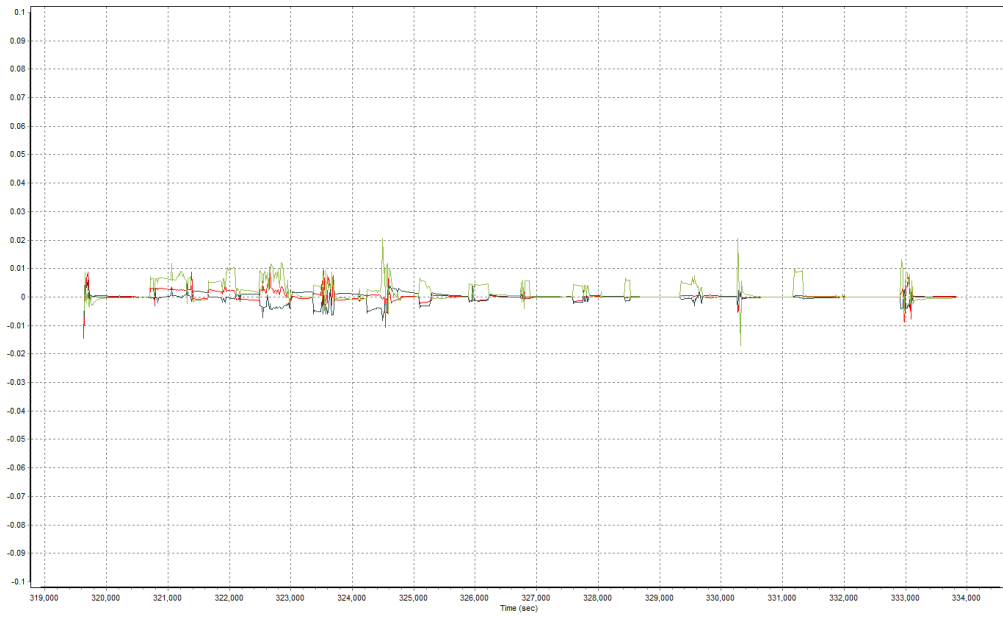




Number of GPS Satellites

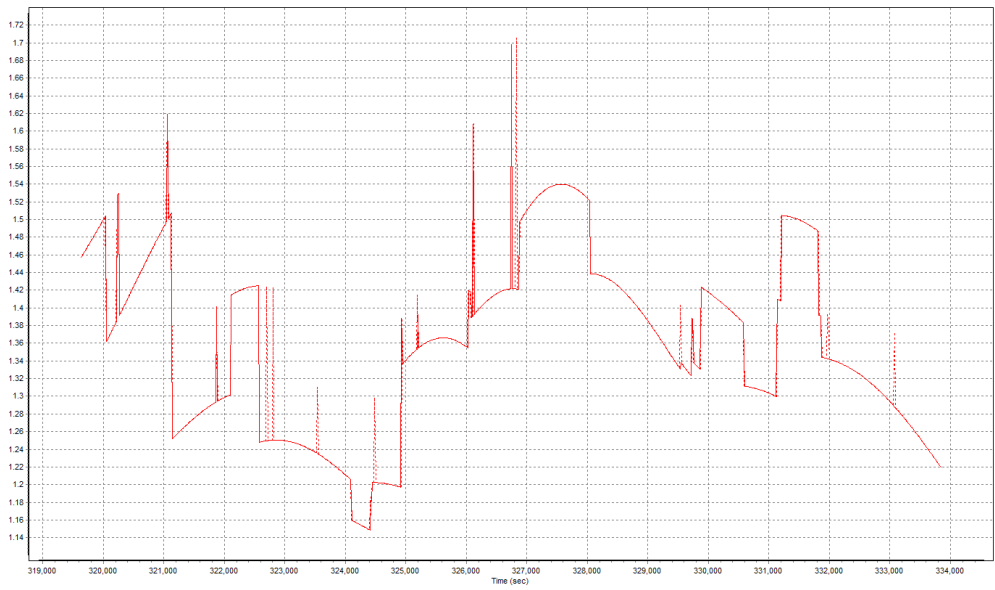


Forward  Reverse



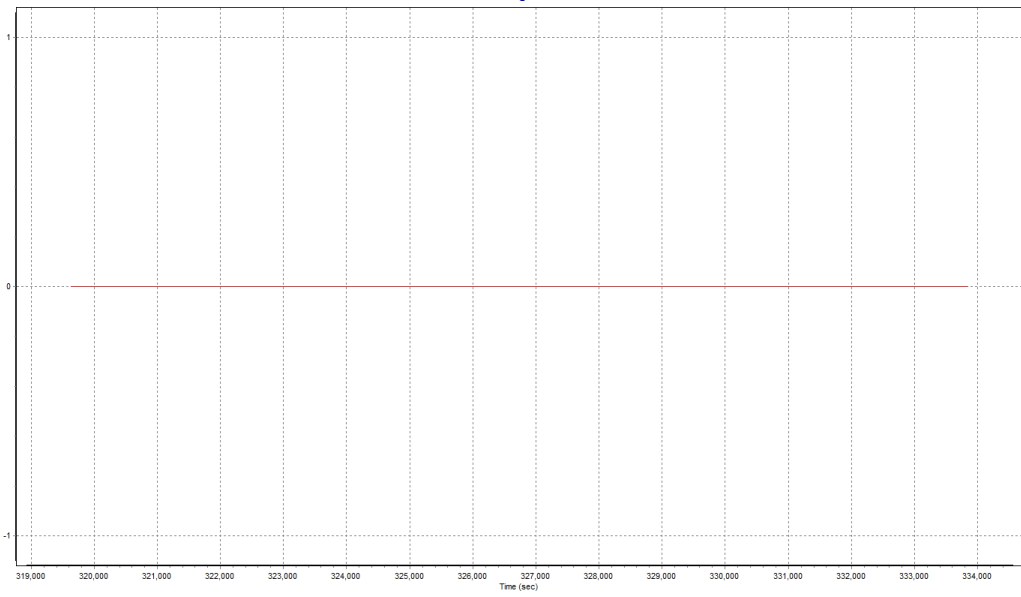
— North (m) — East (m) — Down (m) — DR mode

PDOP



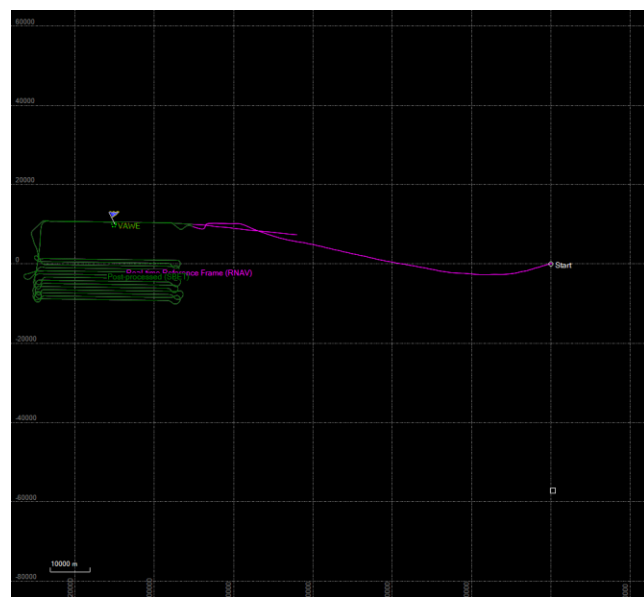
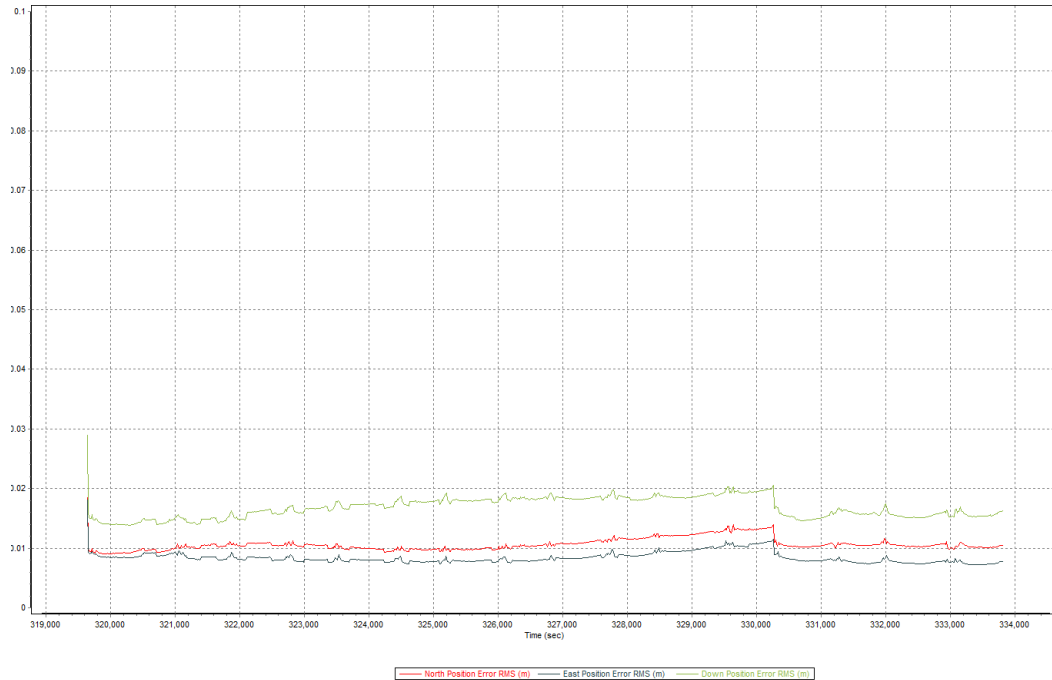
Forward  Reverse

Processing mode

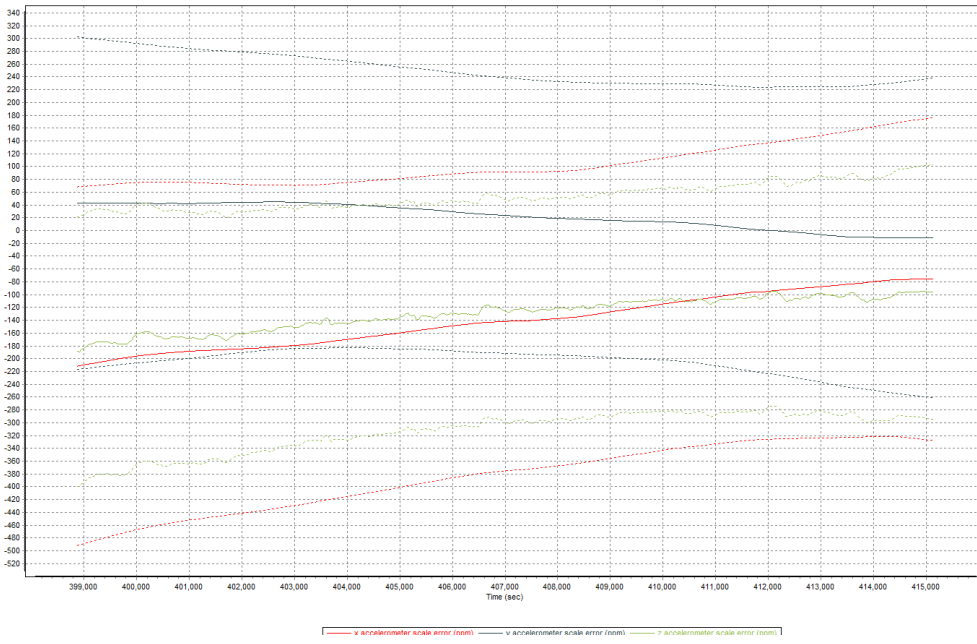
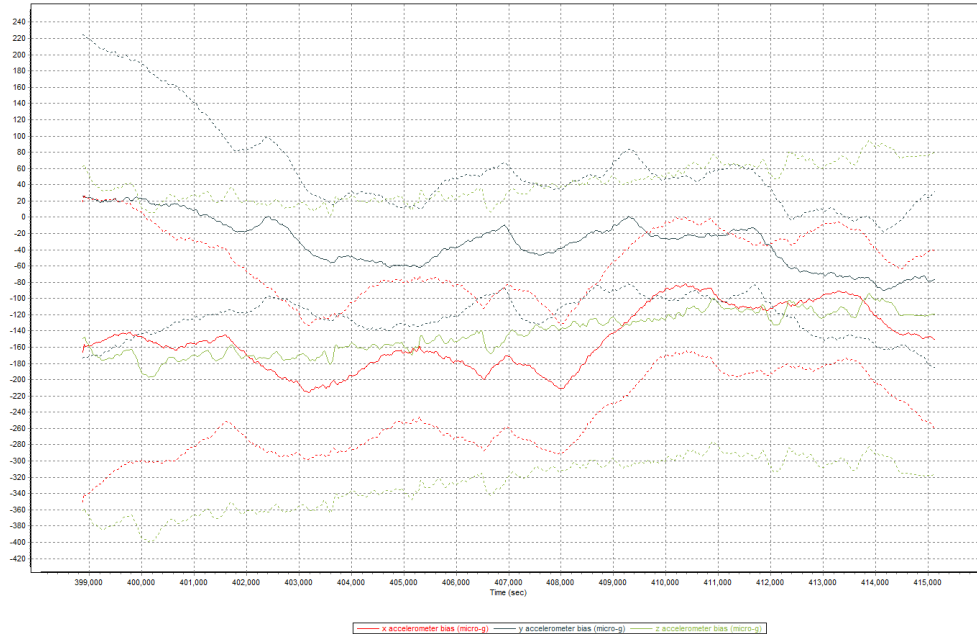


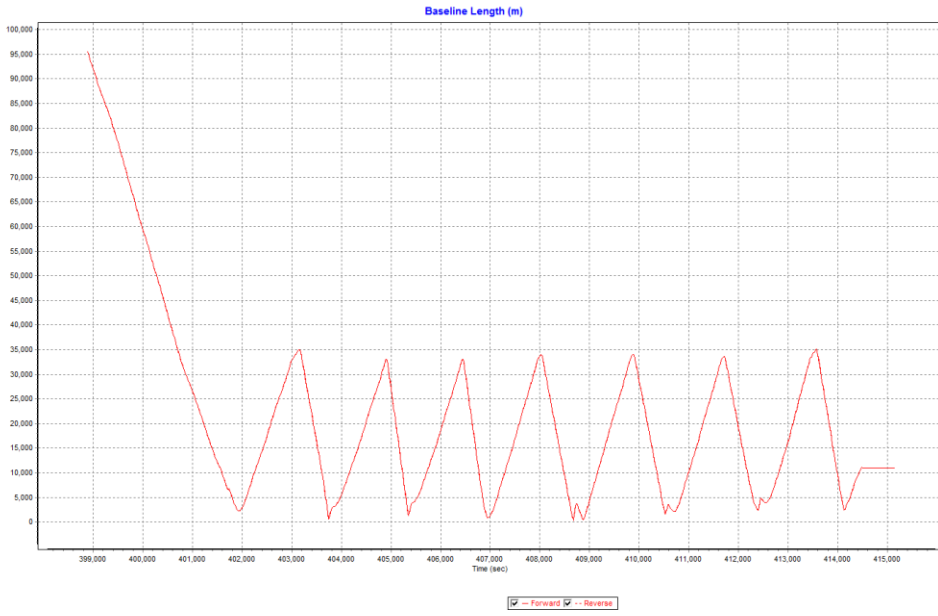
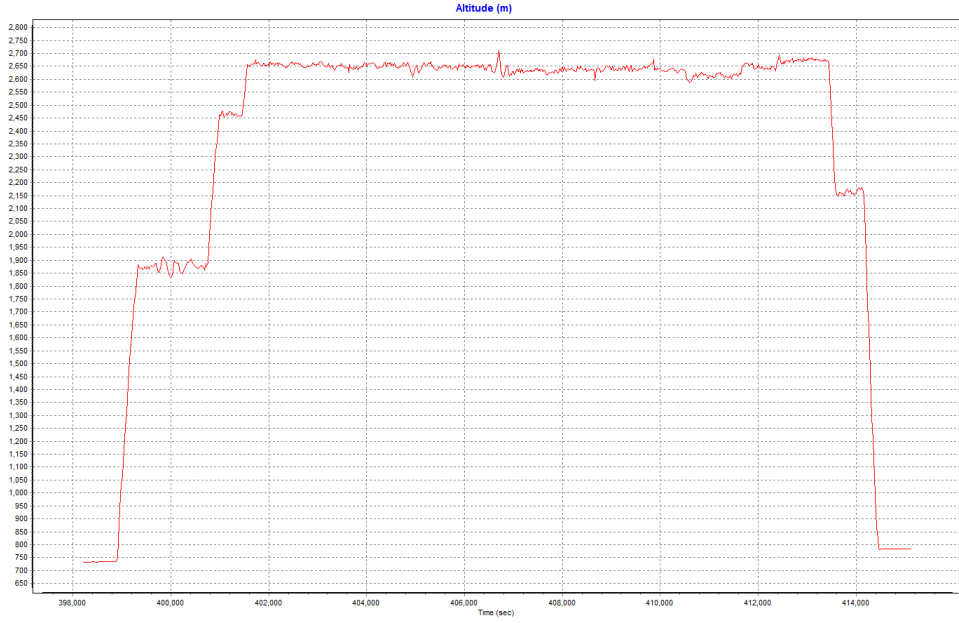
Forward  Reverse

0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = C/A, 7 = GNSS Nav, 8 = DR

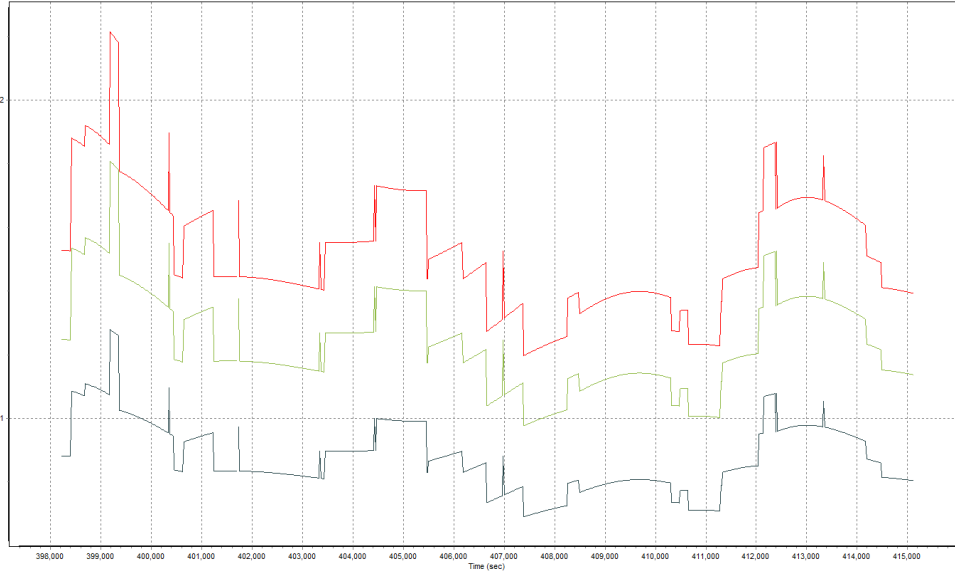


# CAU16343A



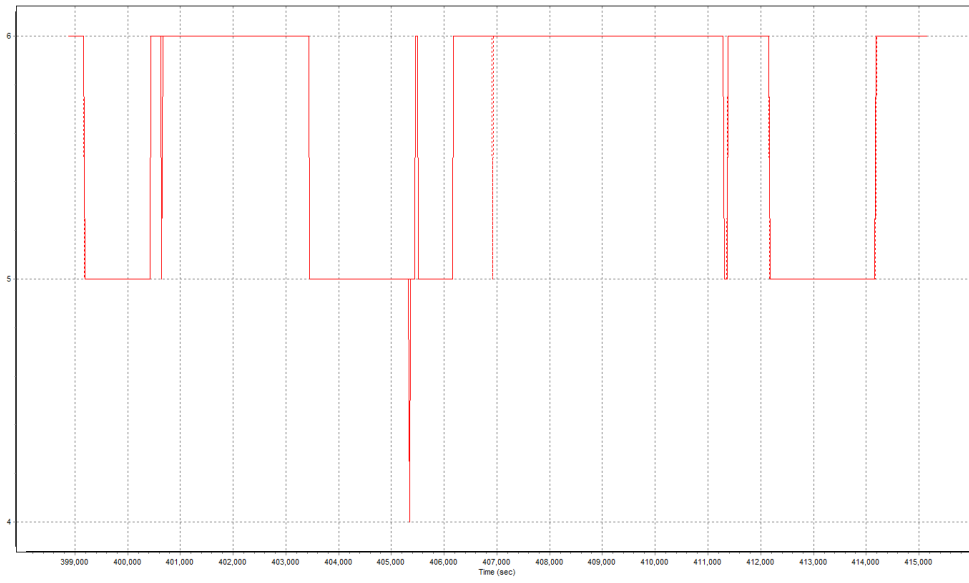


DOP



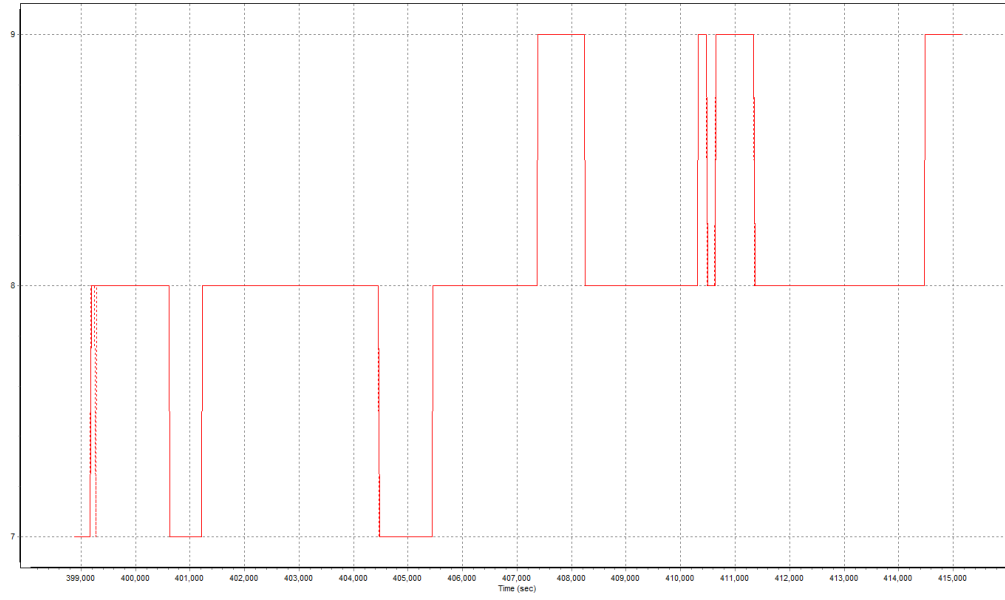
ROP HDOP VDOP

Number of GLONASS Satellites

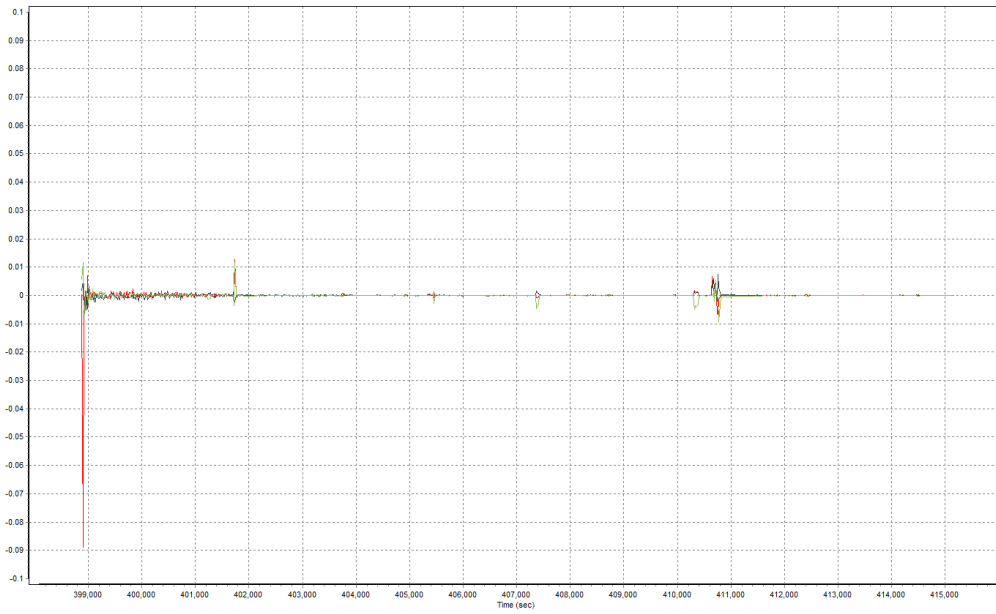


Forward Reverse

Number of GPS Satellites

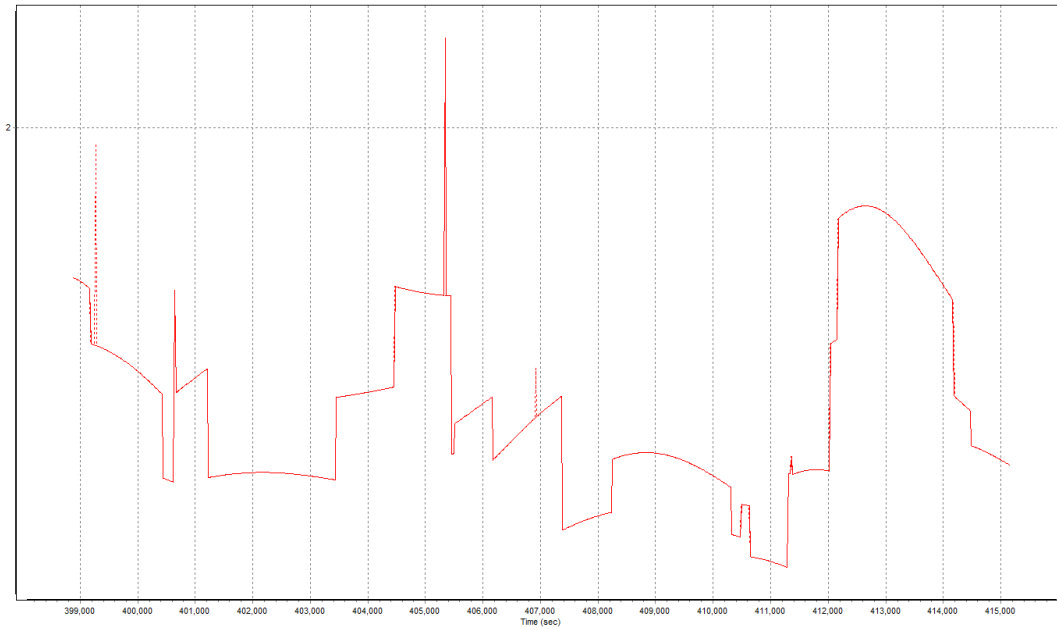


Forward  Reverse



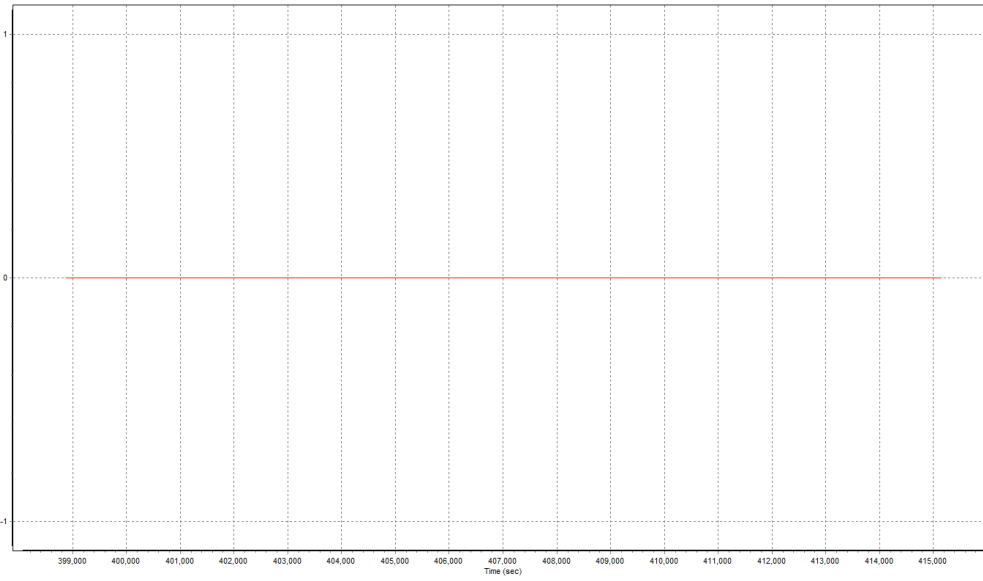
North (m)  East (m)  Down (m)  DR mode

PDOP



Forward  Reverse

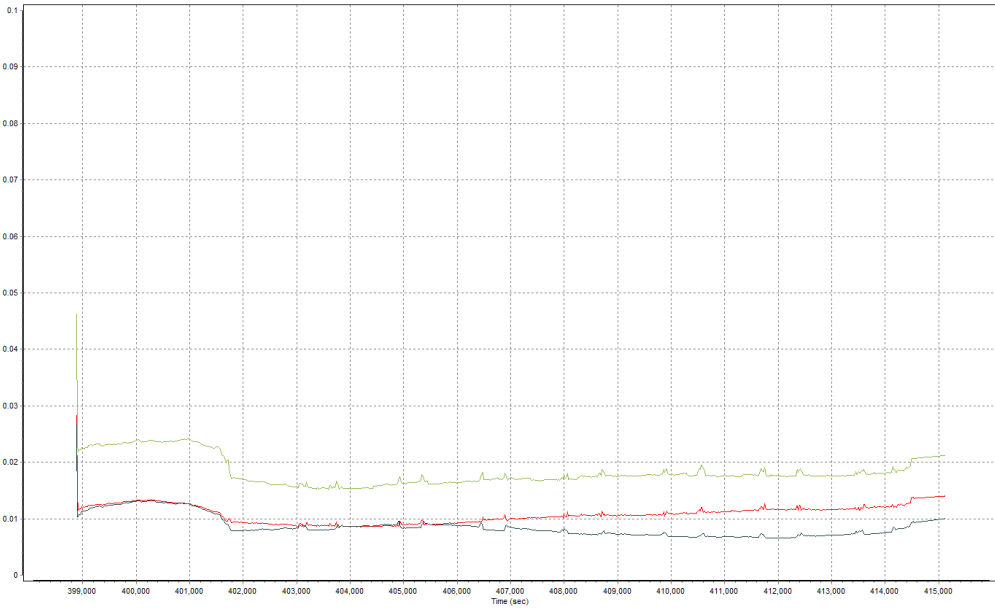
Processing mode



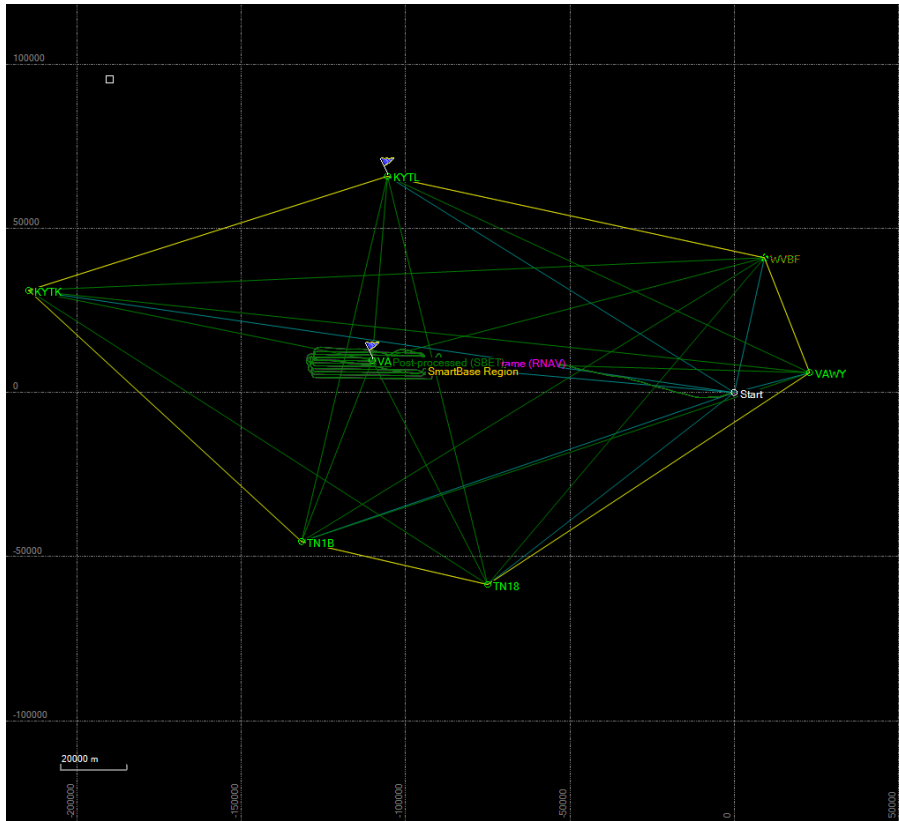
Forward  Reverse

0 = Fixed N, 1 = Fixed W, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = CIA, 7 = QNSS Nav, 8 = DR

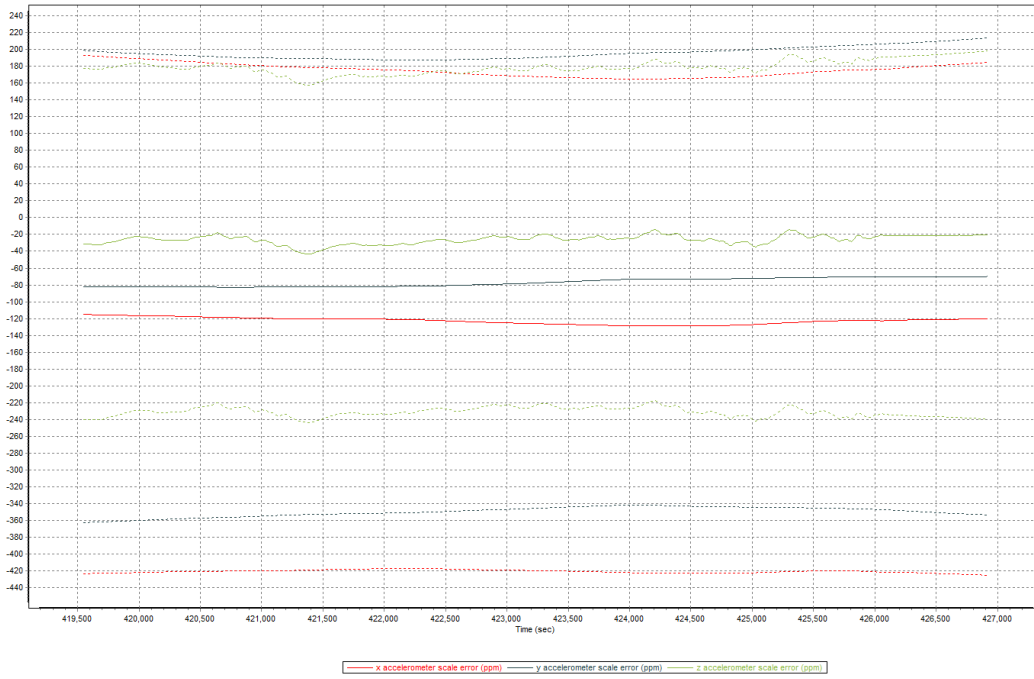
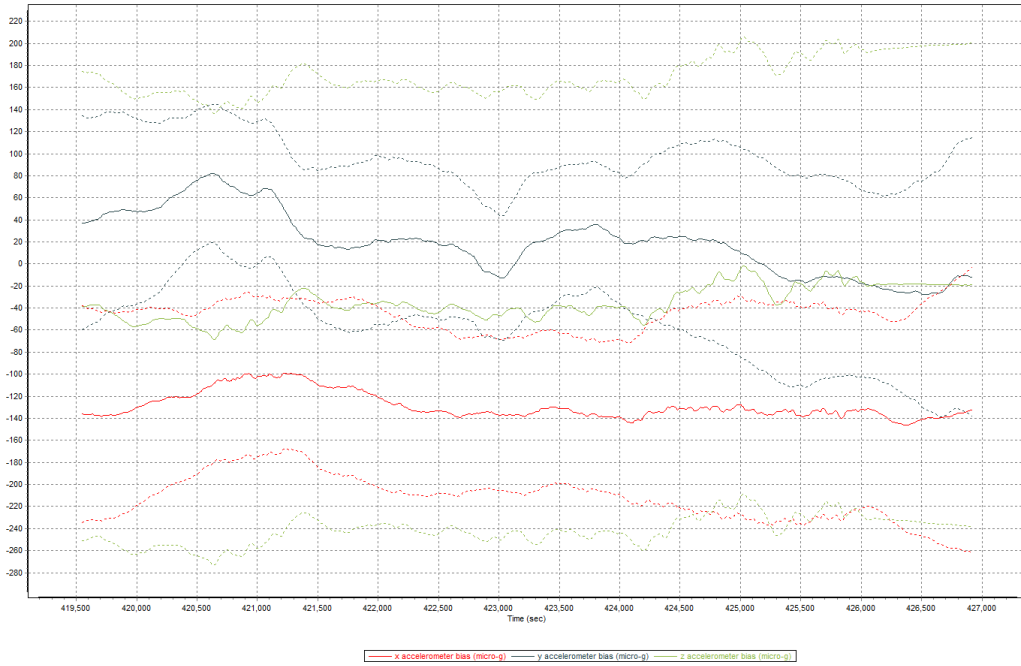


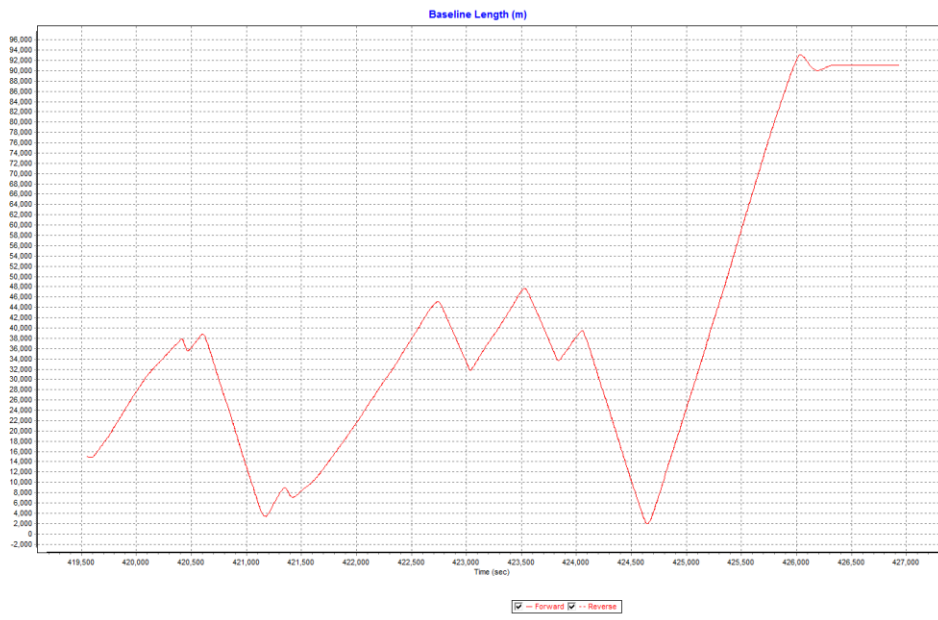
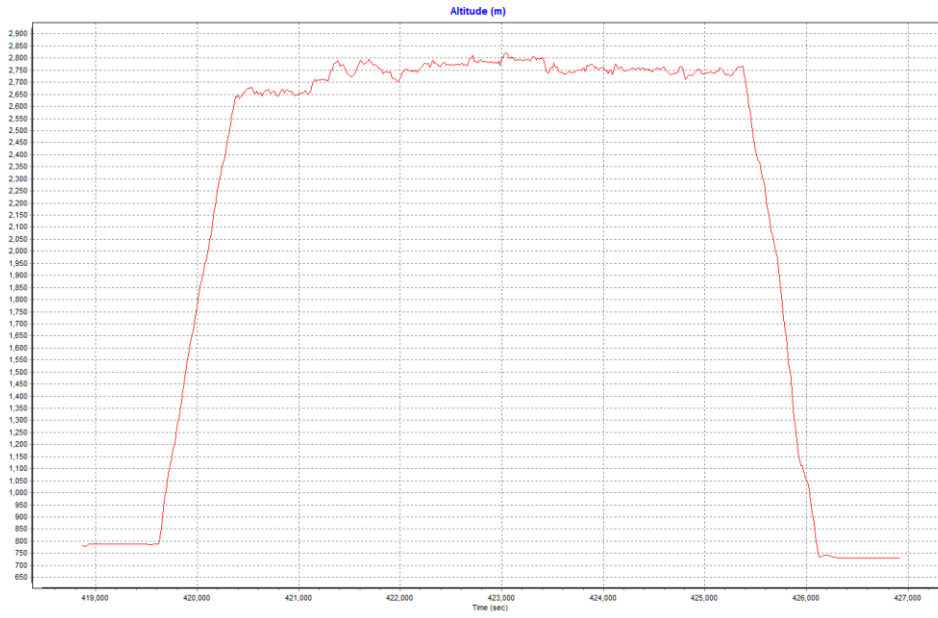


— North Position Error RMS (m) — East Position Error RMS (m) — Down Position Error RMS (m)

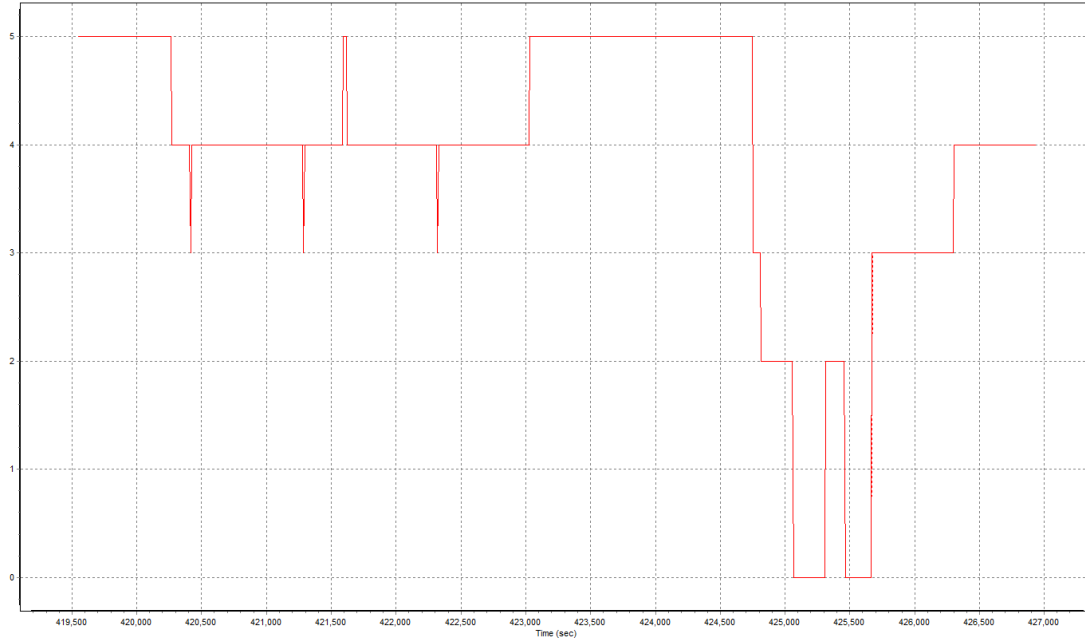


# CAU16343B



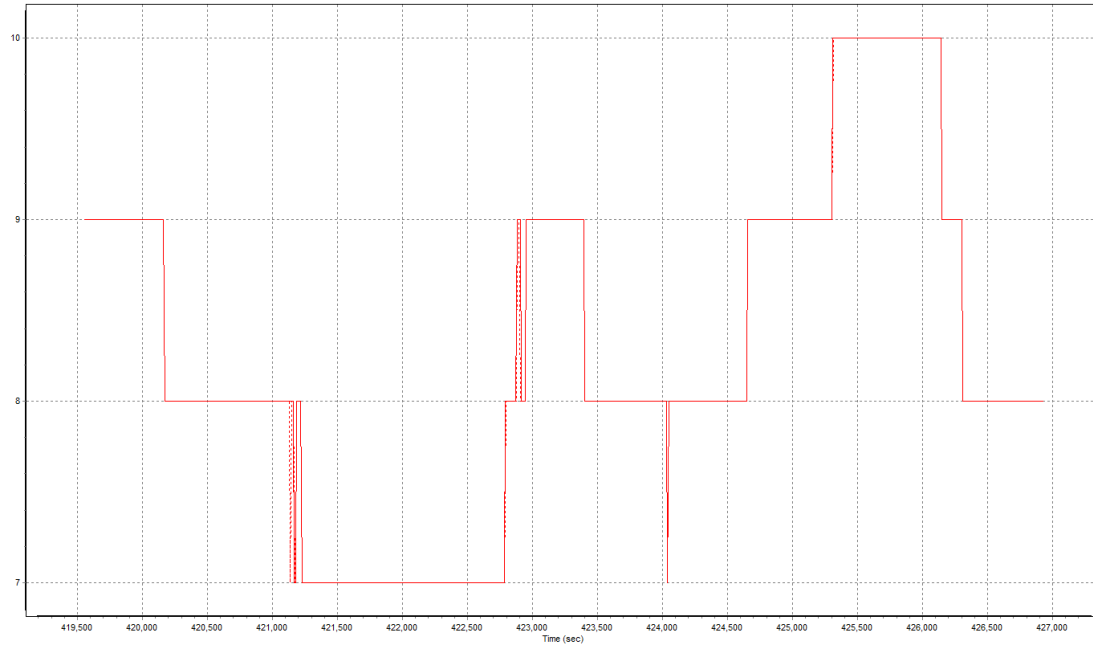


Number of GLONASS Satellites

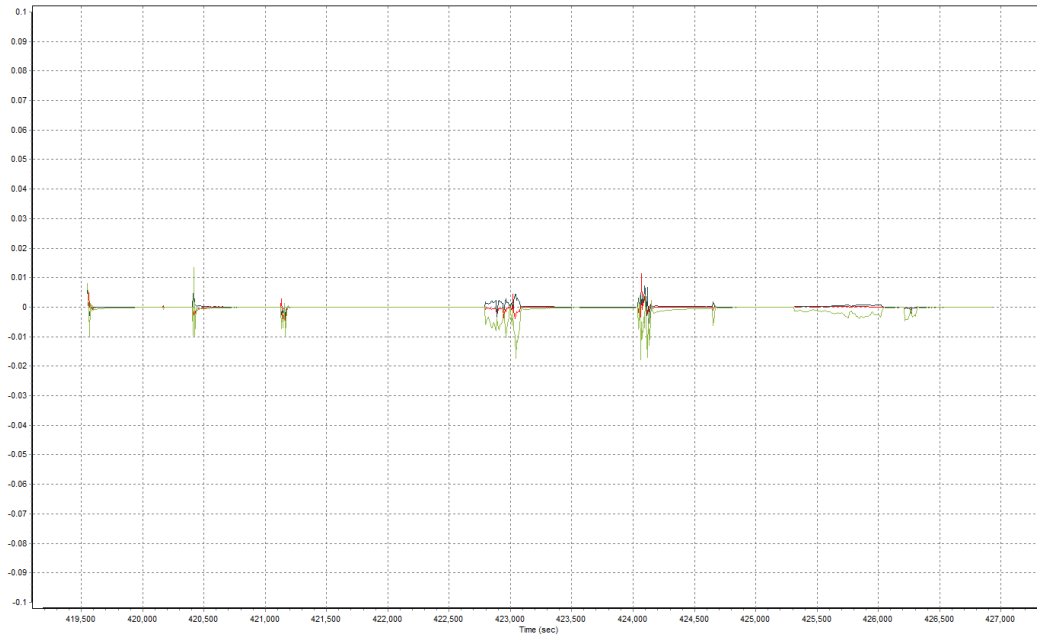


- Forward  - Reverse

Number of GPS Satellites

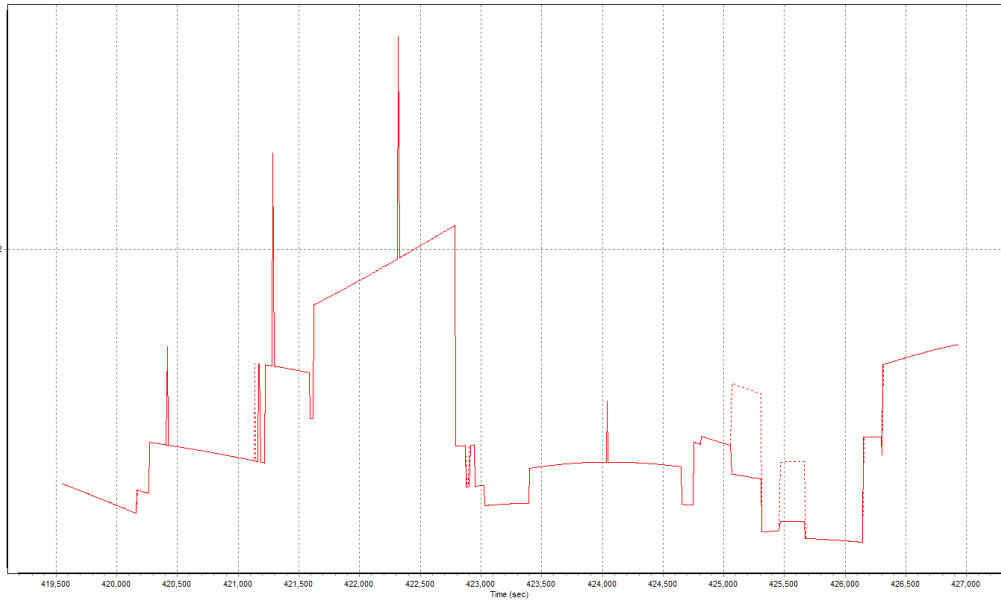


- Forward  - Reverse



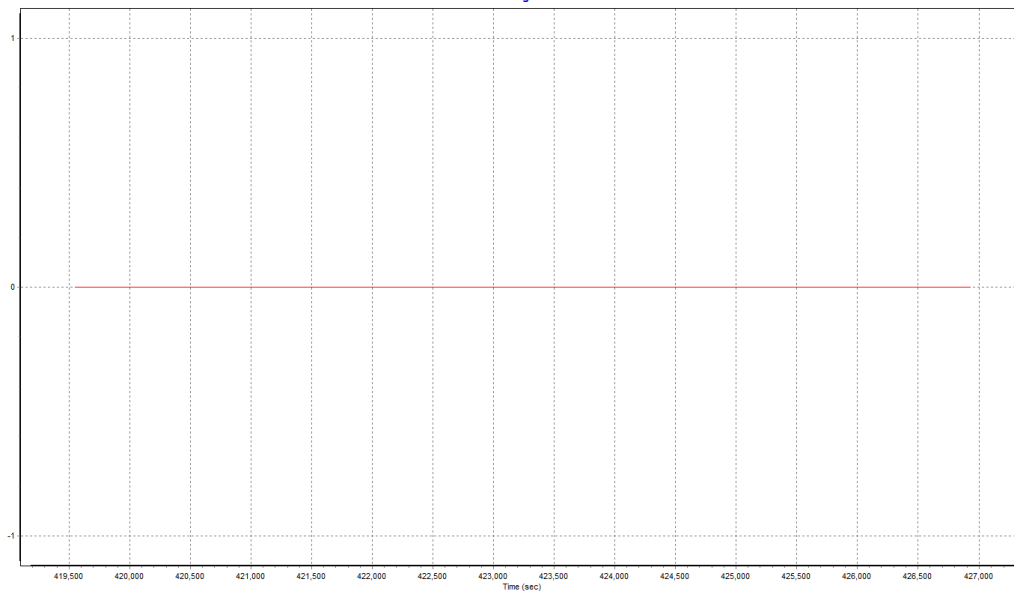
North (m)  East (m)  Down (m)  DR mode

**PDOP**



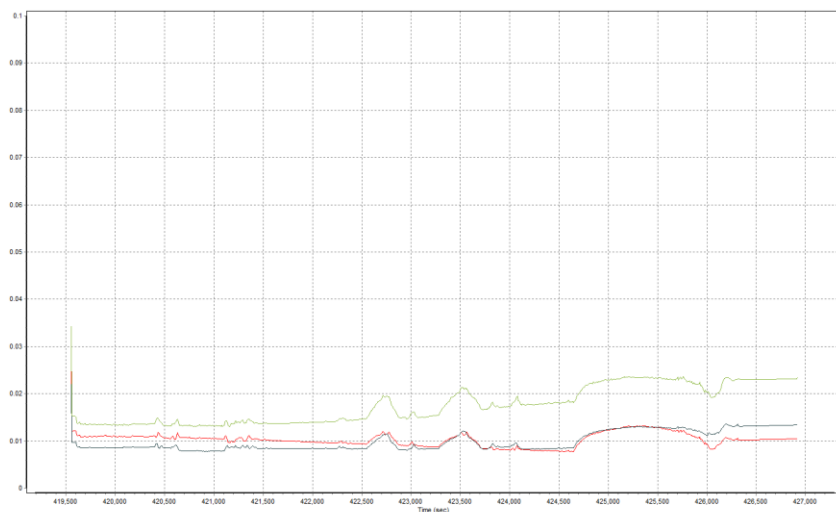
Forward  Reverse

Processing mode

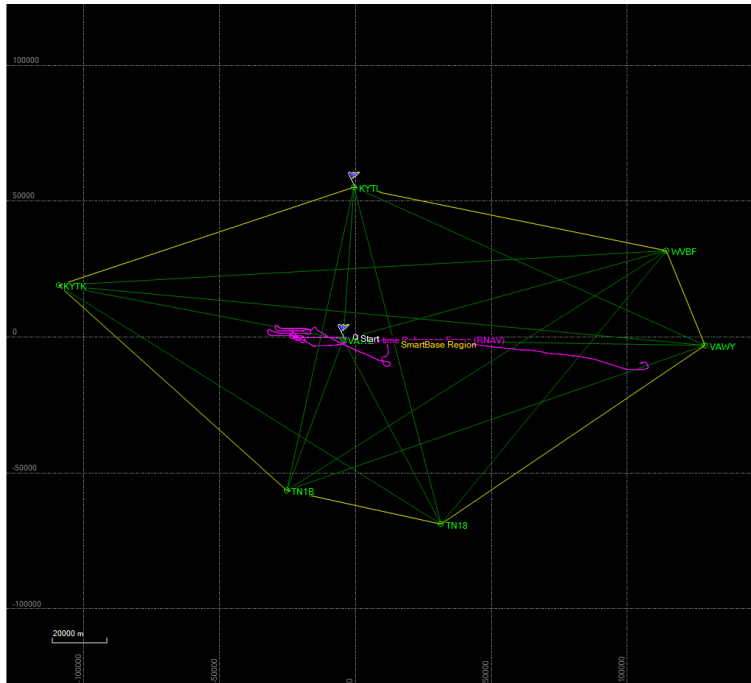


Forward  Reverse

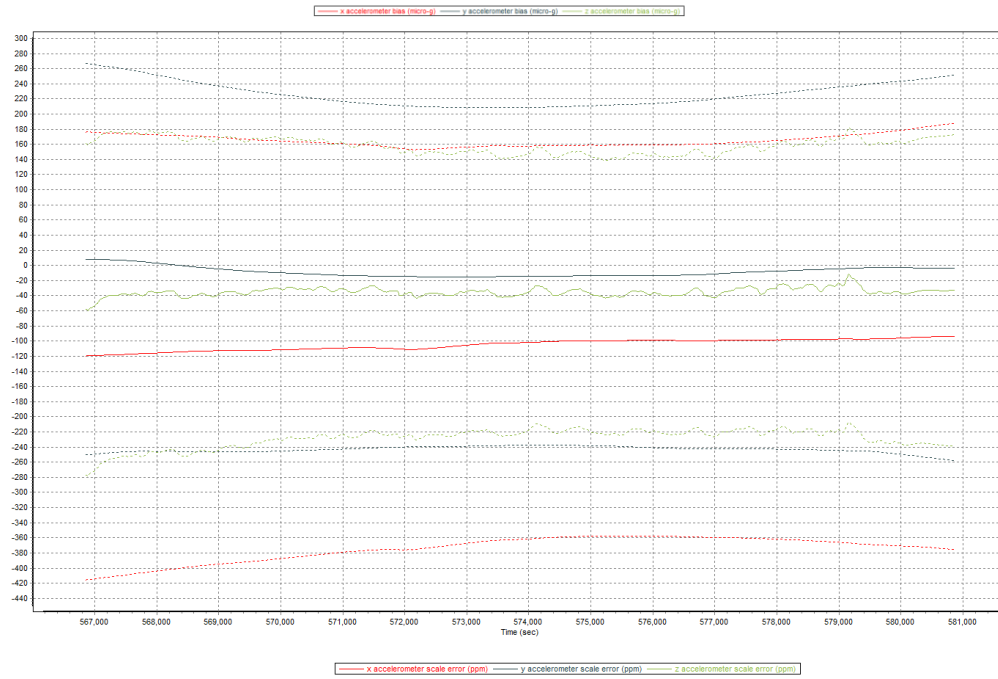
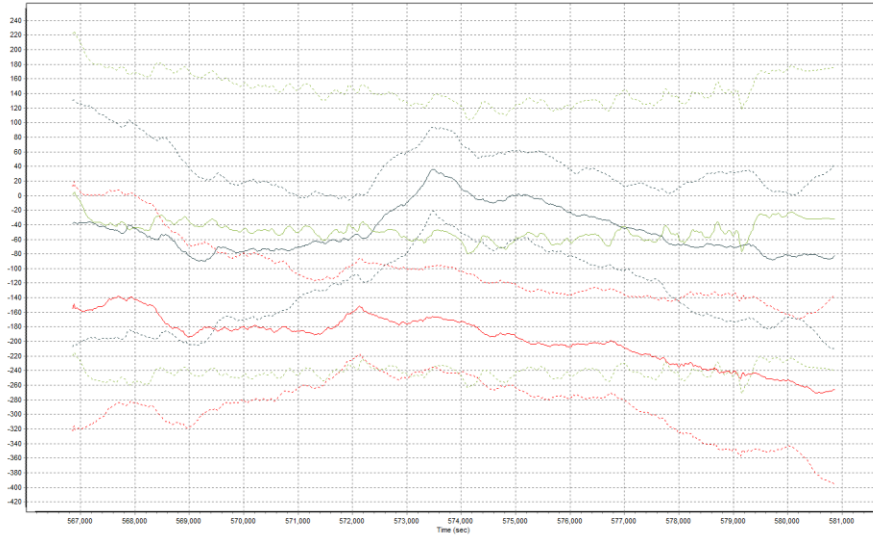
0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNS, 4 = RTCM, 5 = IAPPP, 6 = CIA, 7 = GNSS Nav, 8 = DR



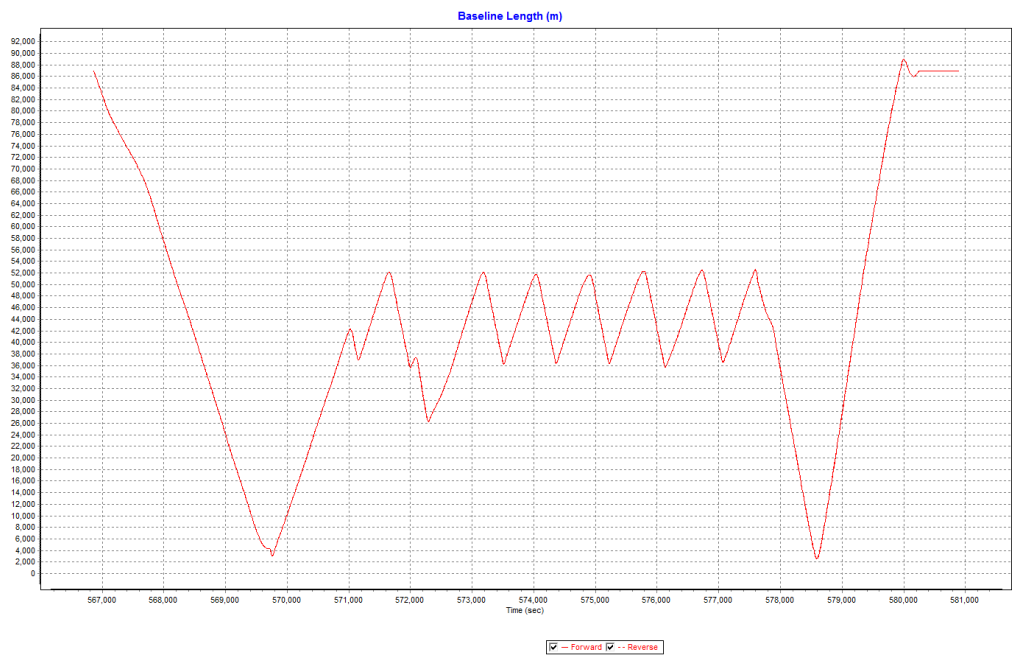
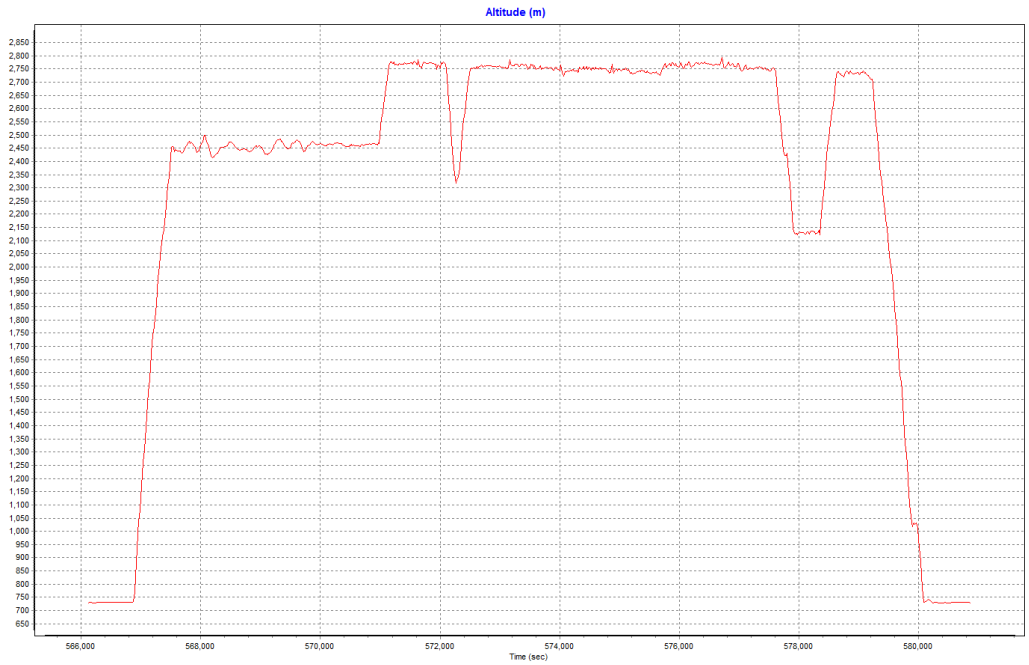
North Position Error RMS (m) East Position Error RMS (m) South Position Error RMS (m)



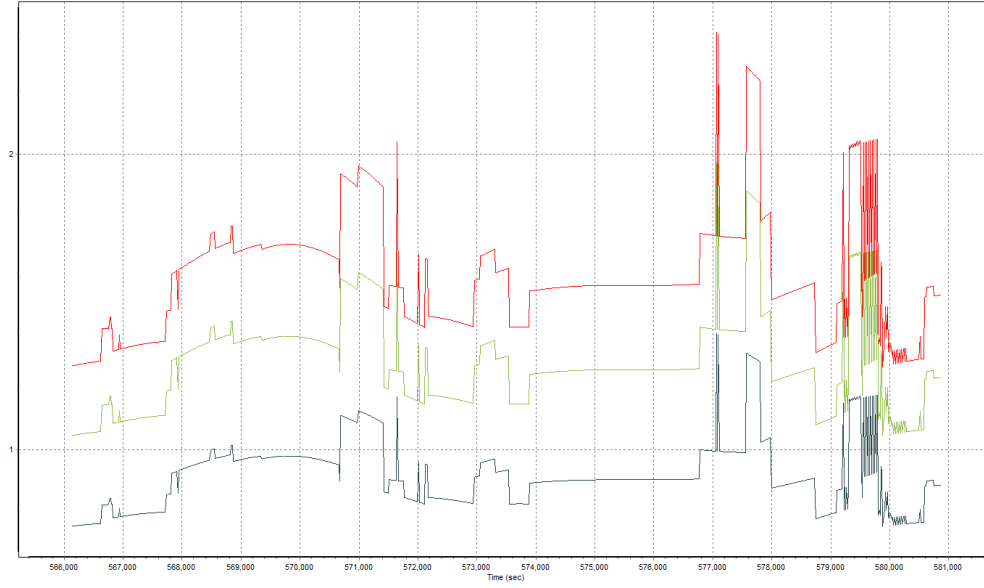
# CAU16345A





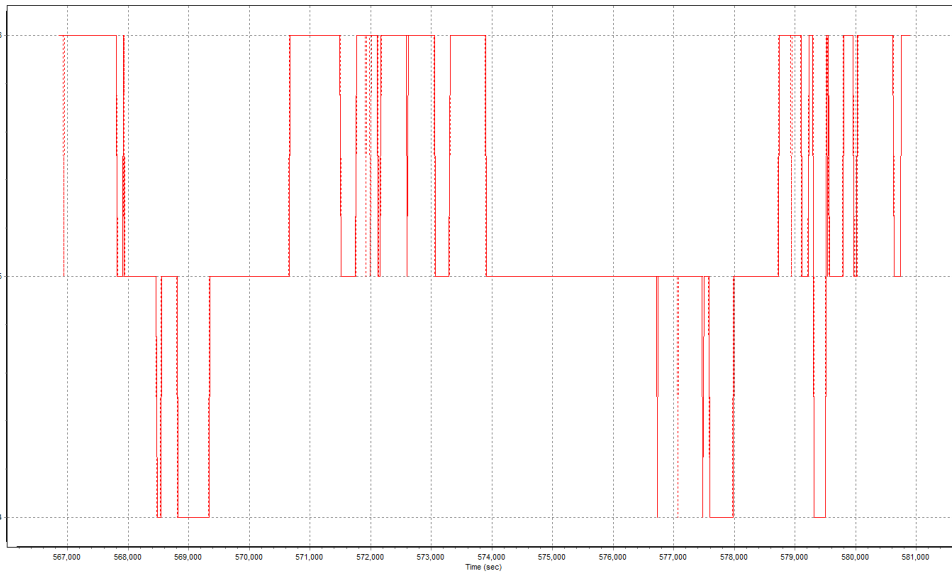


DOP



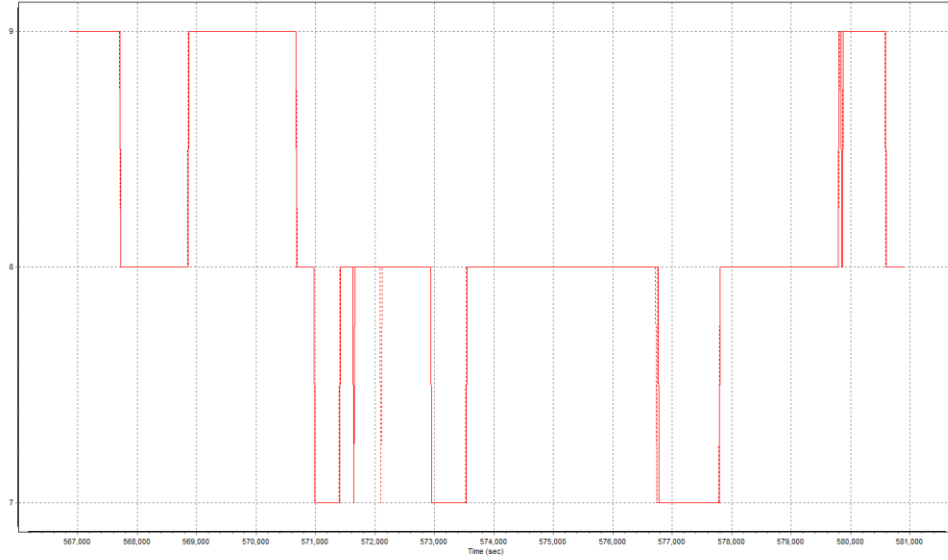
— PDOP — HDOP — VDOP

Number of GLONASS Satellites

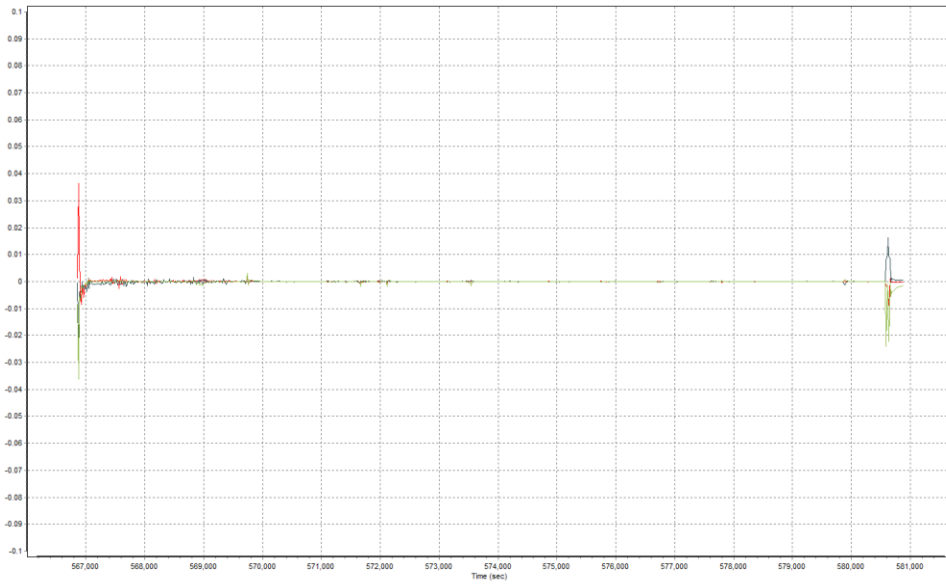


Forward  Reverse

Number of GPS Satellites



Forward  Reverse



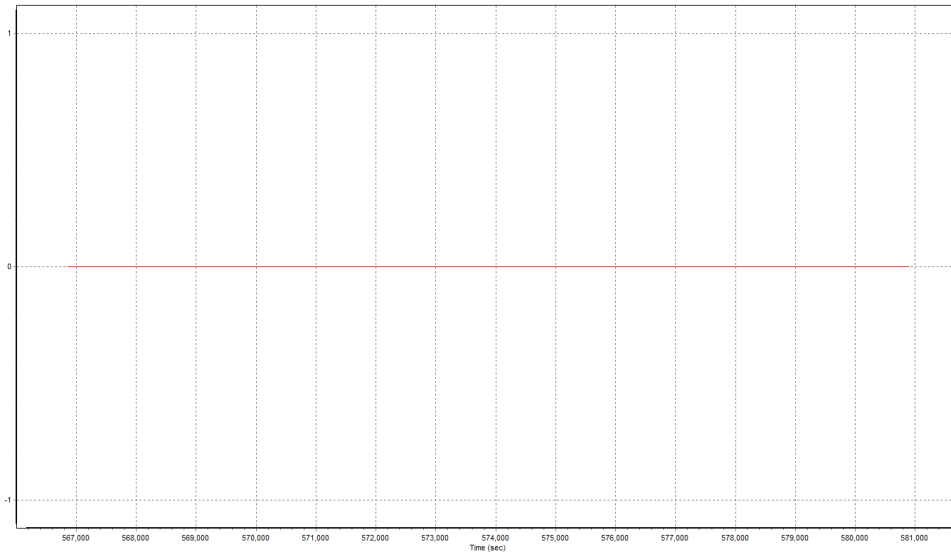
North (m)  East (m)  Down (m)  DR mode

PDOP



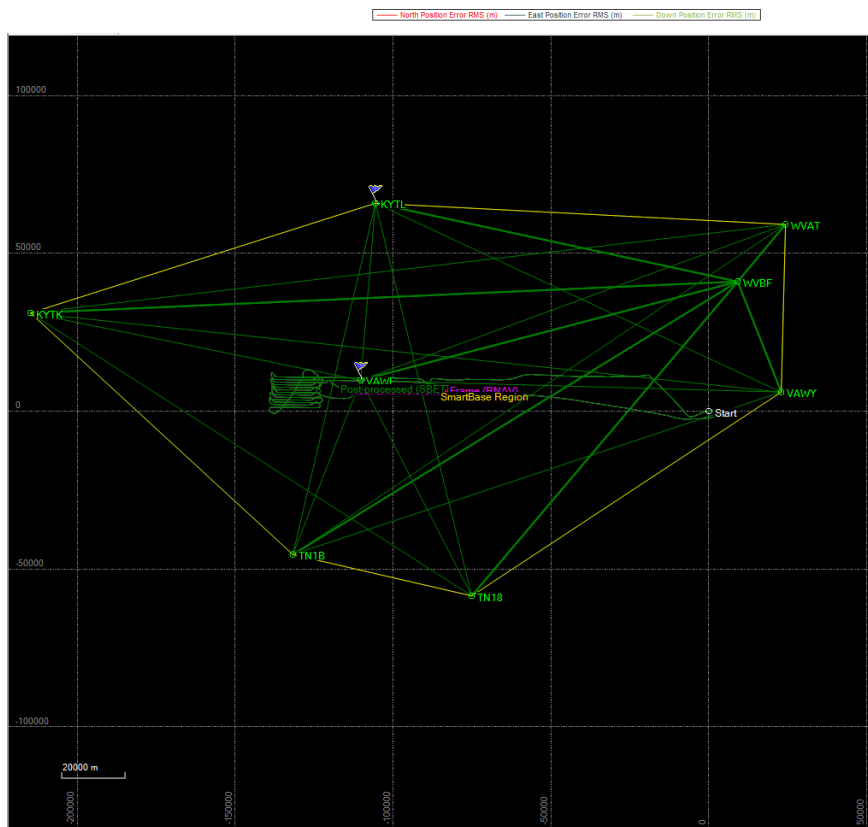
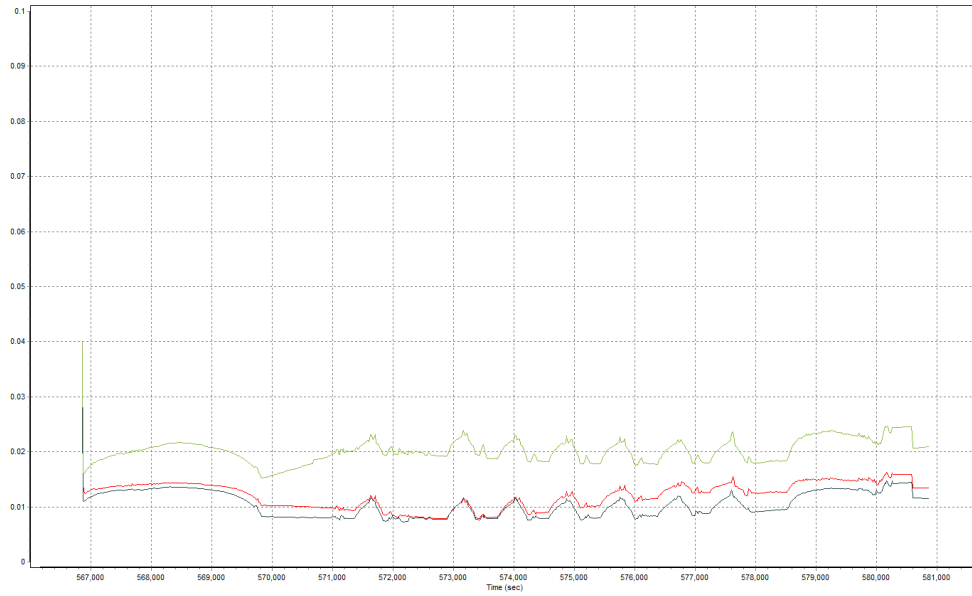
Forward  Reverse

Processing mode

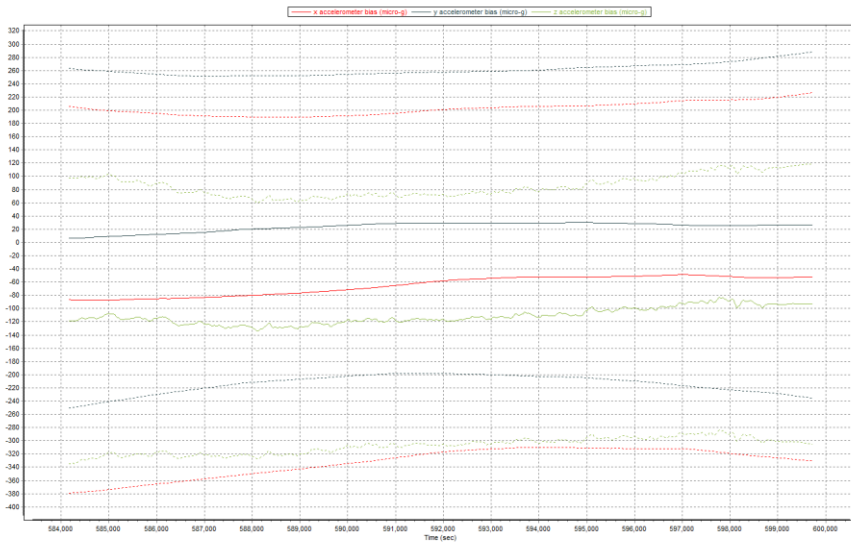
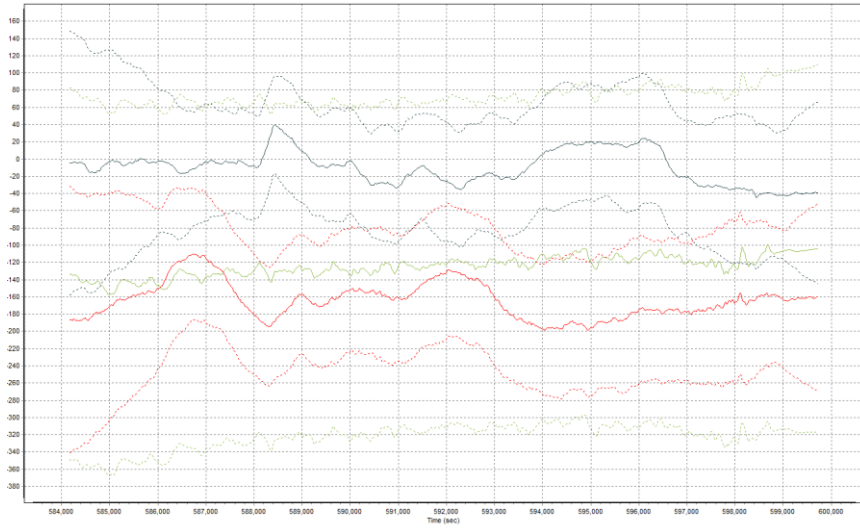


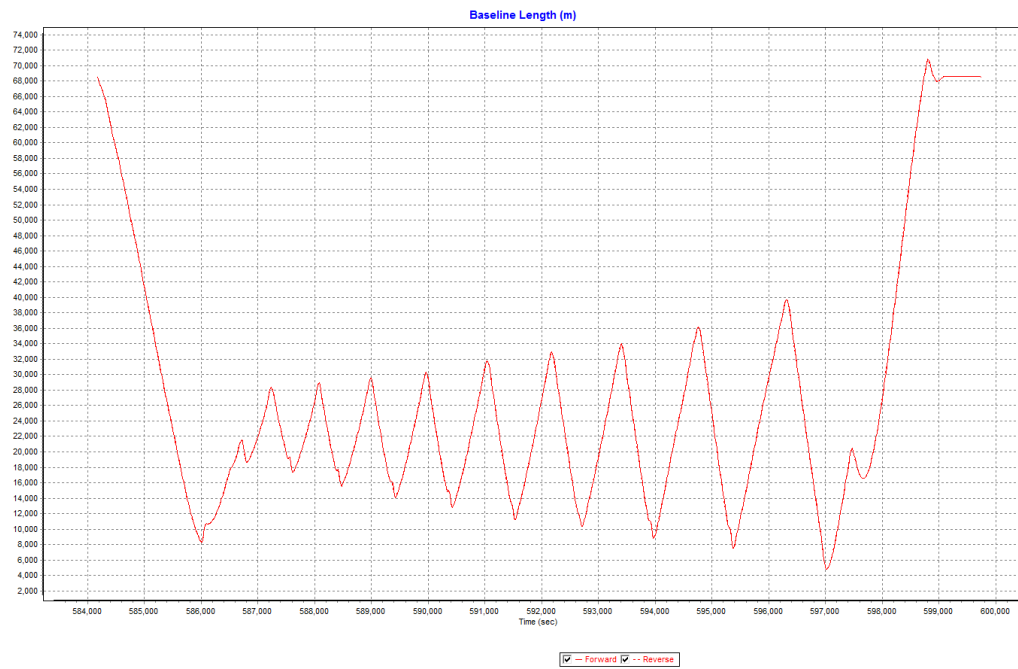
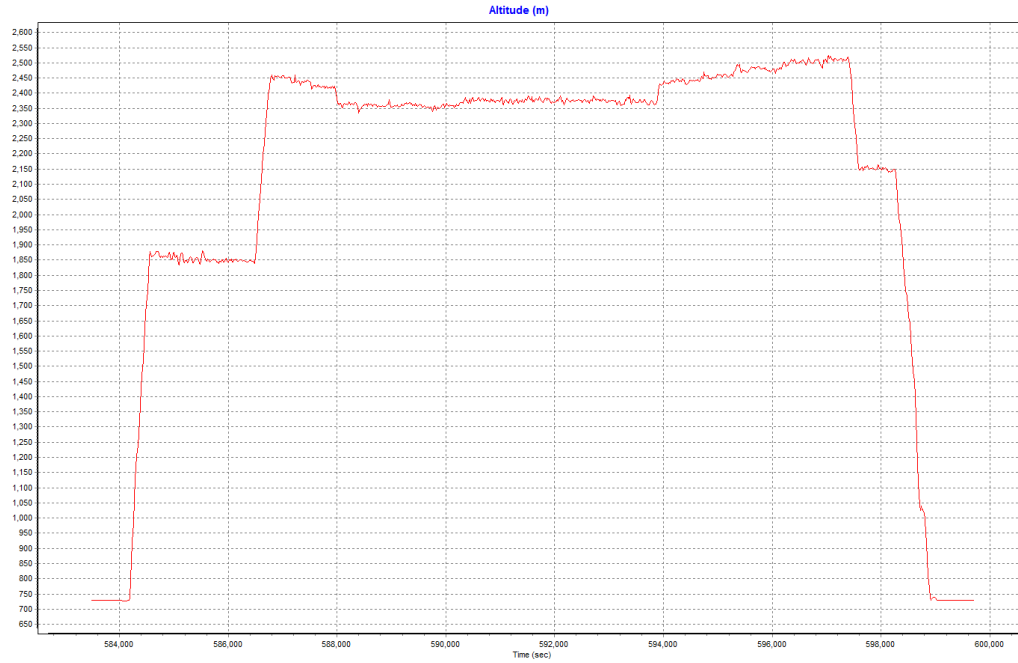
Forward  Reverse

0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = CIA, 7 = GNSS Nav, 8 = DR

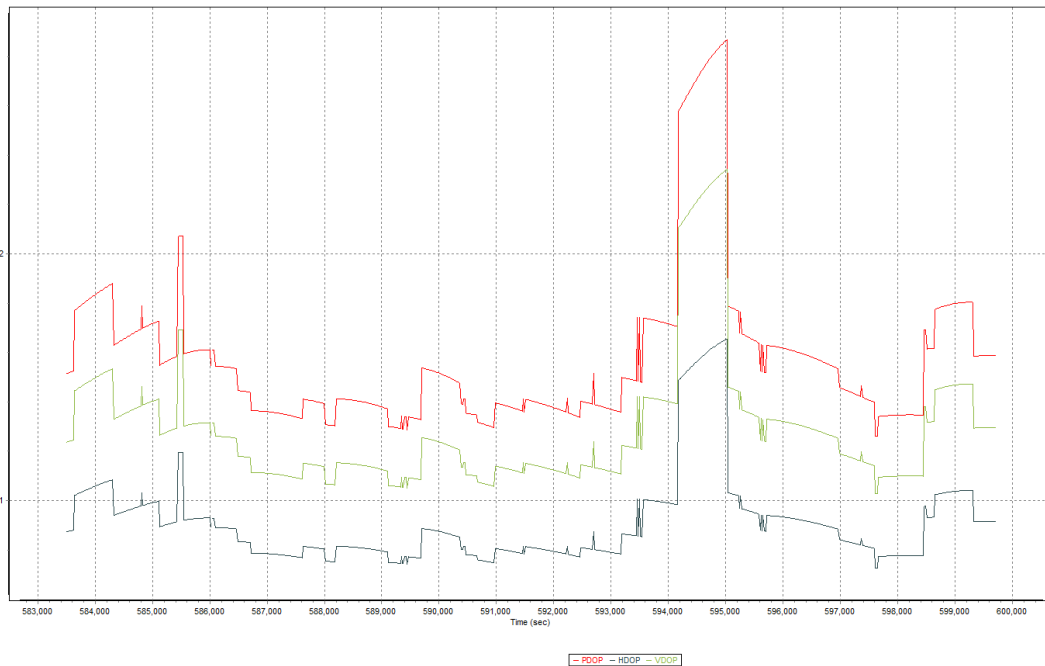


# CAU16345B

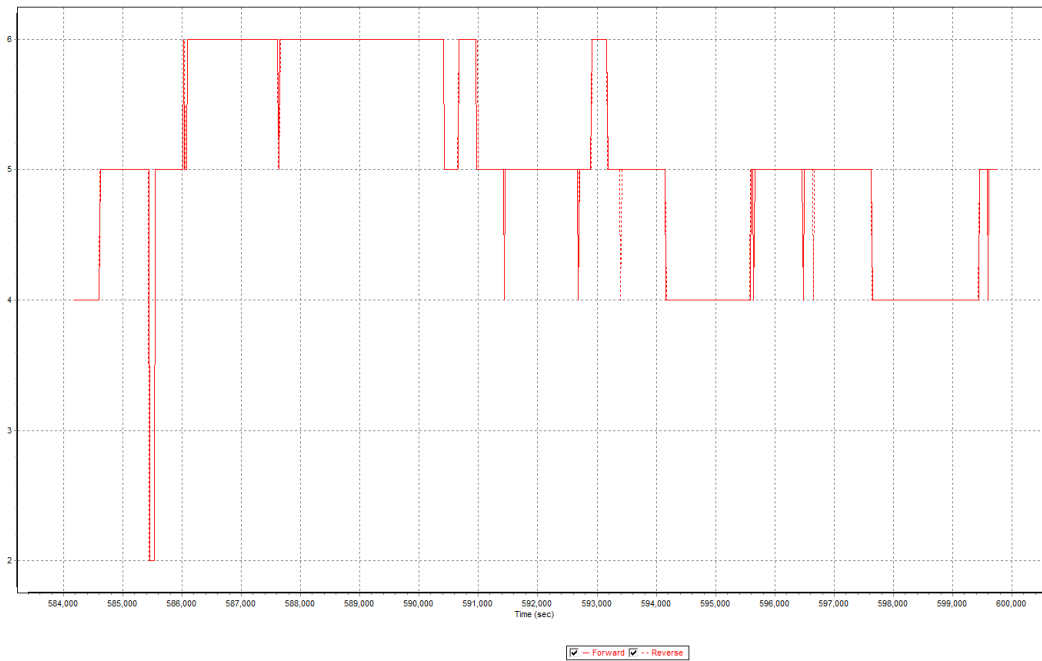




DOP

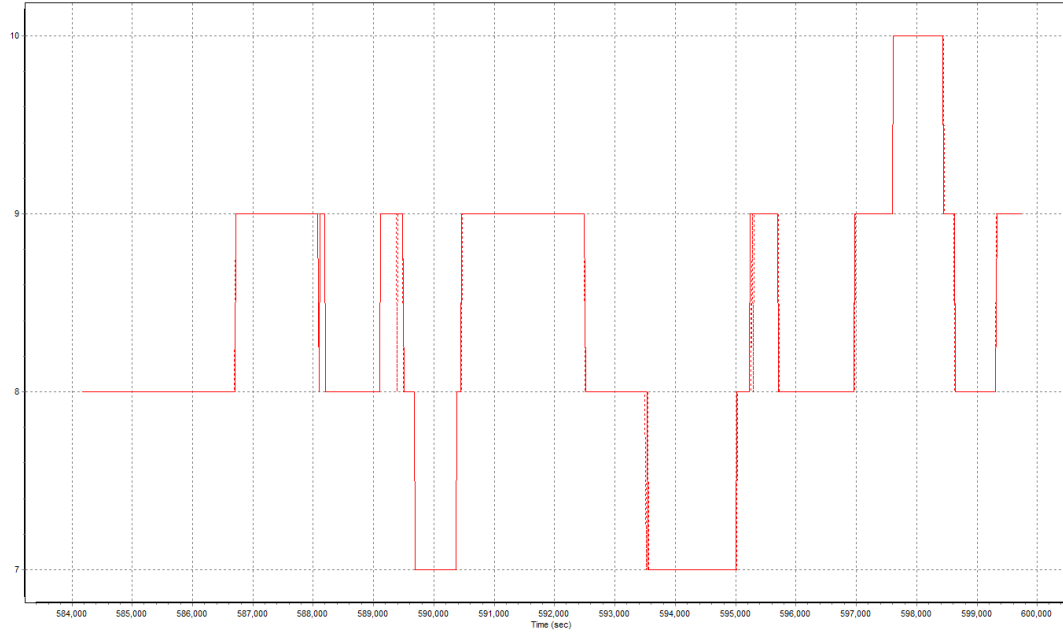


Number of GLONASS Satellites

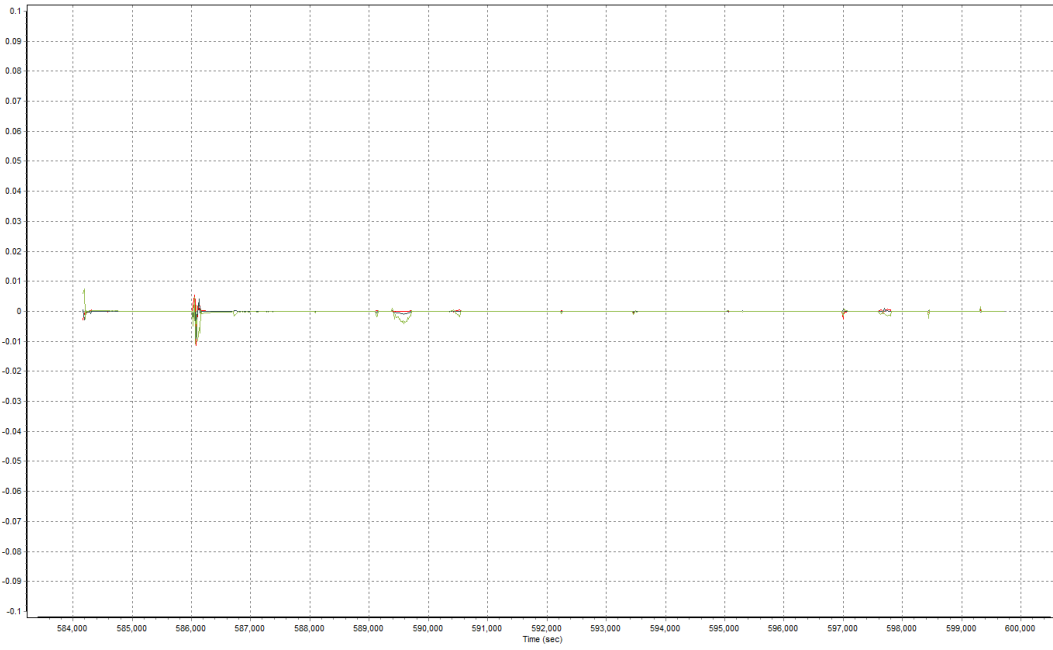




Number of GPS Satellites

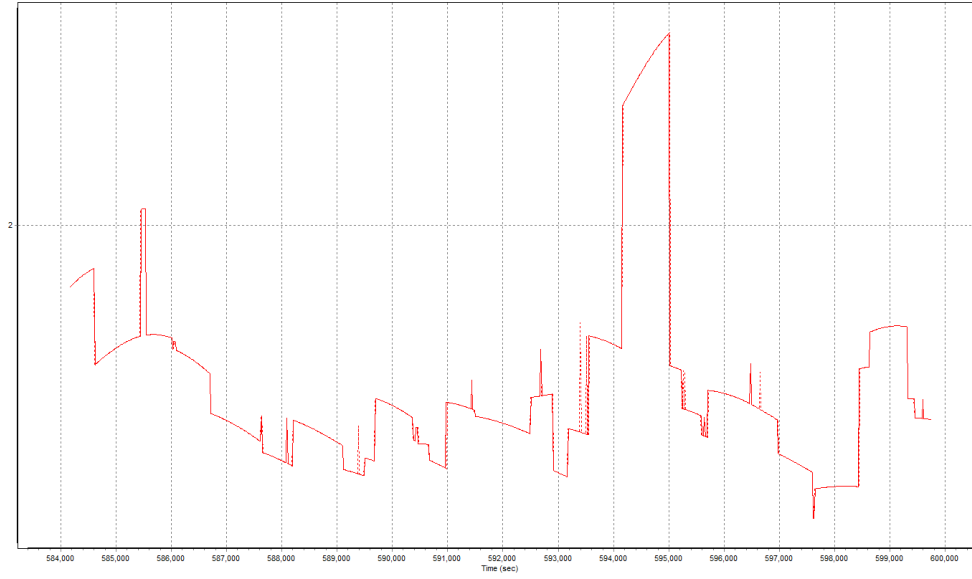


Forward  Reverse



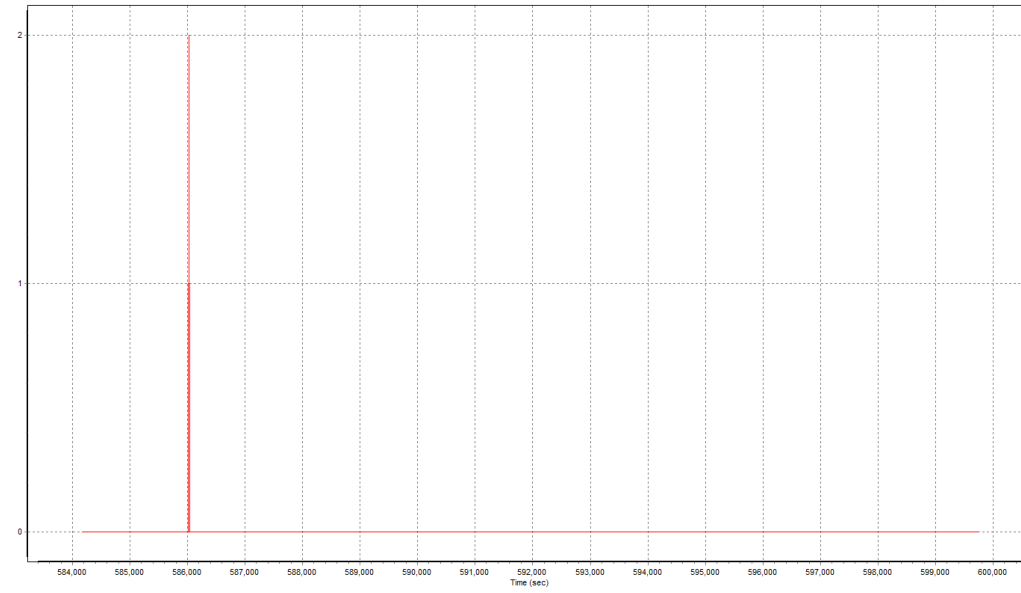
— North (m) — East (m) — Down (m) — DR mode

PDOP



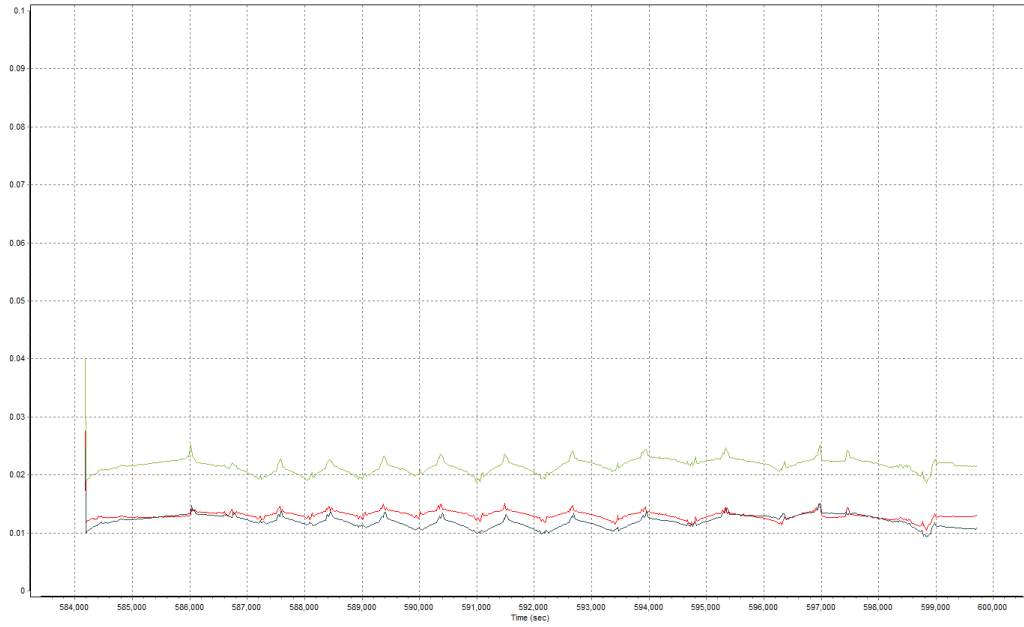
Forward  Reverse

Processing mode

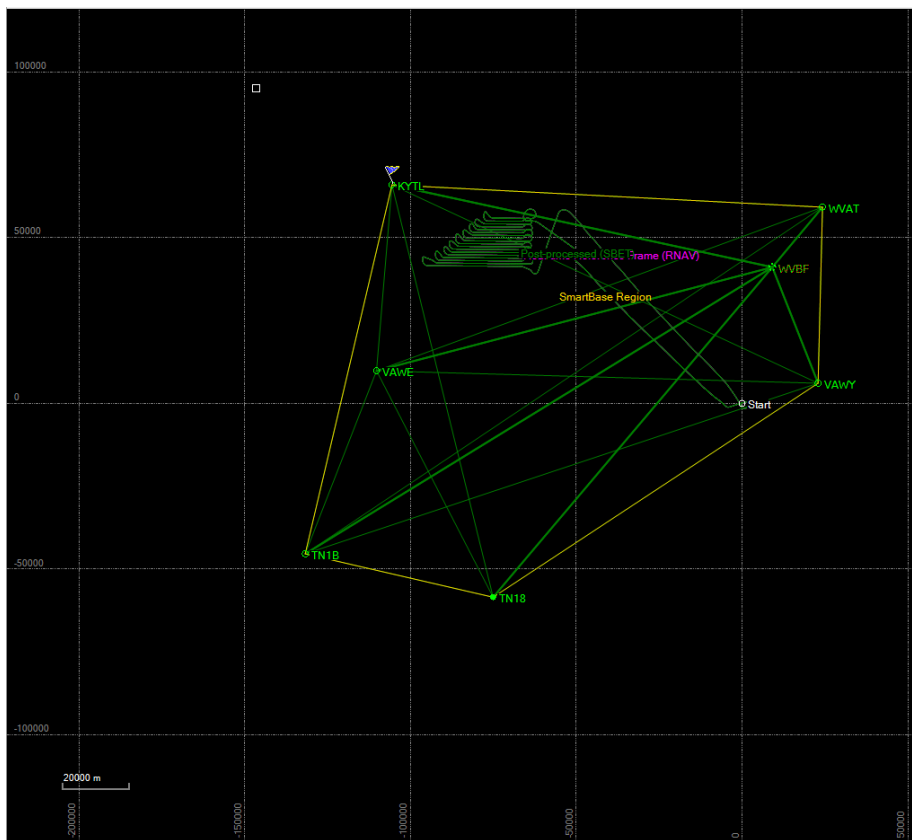


Forward  Reverse

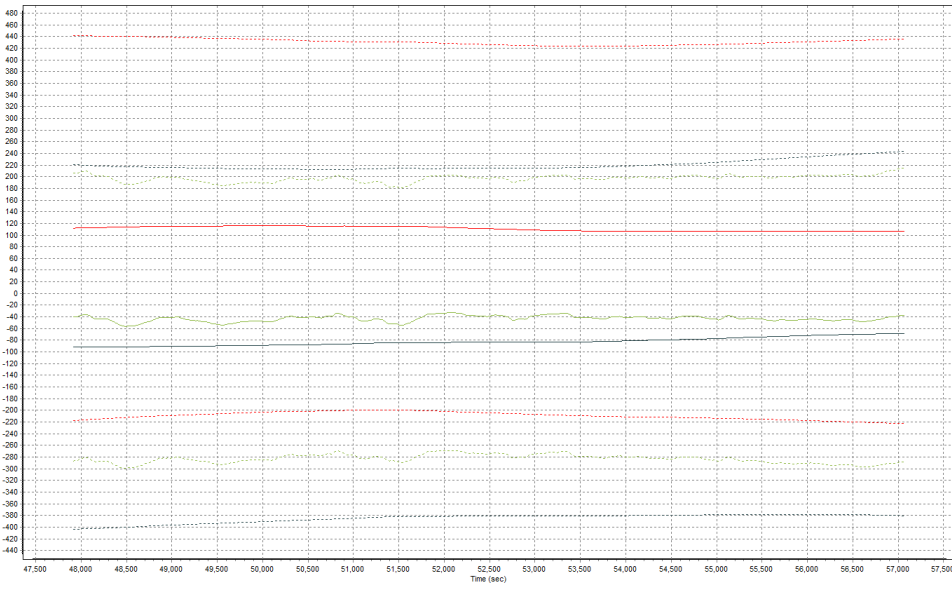
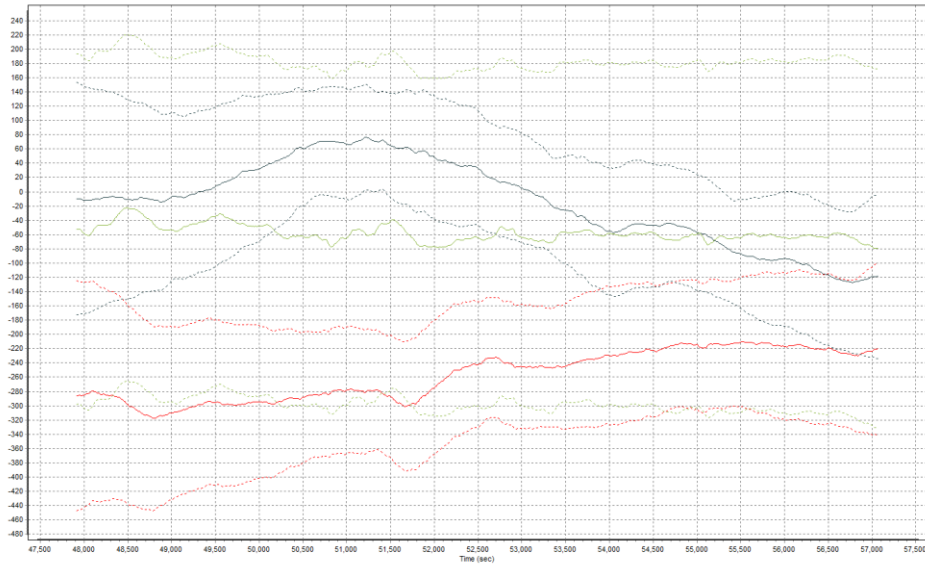
0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = WPP, 6 = CIA, 7 = GNSS Nav, 8 = DR

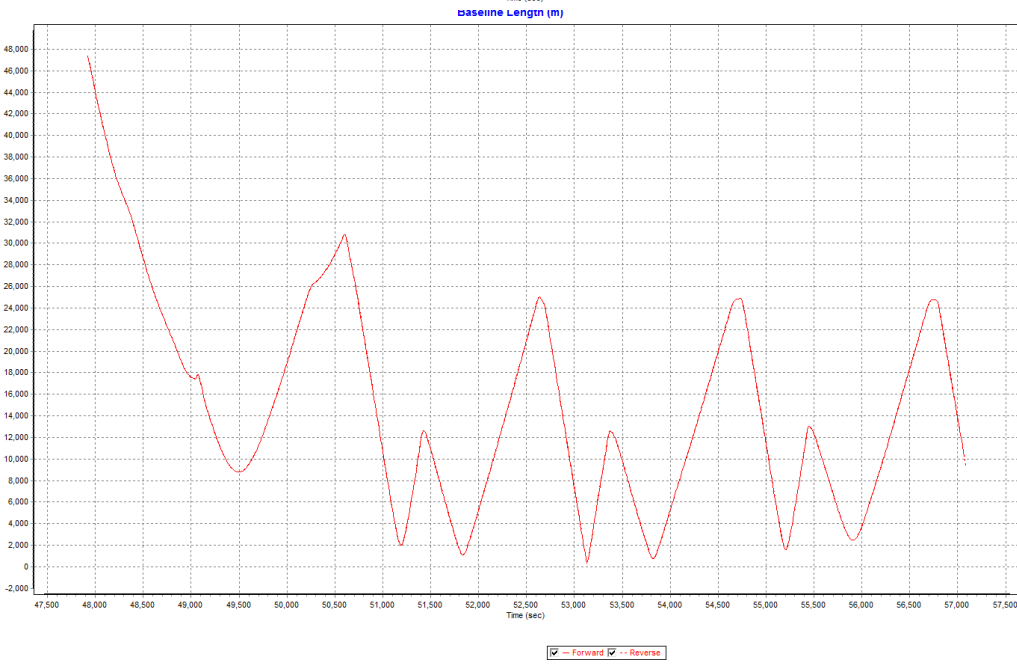
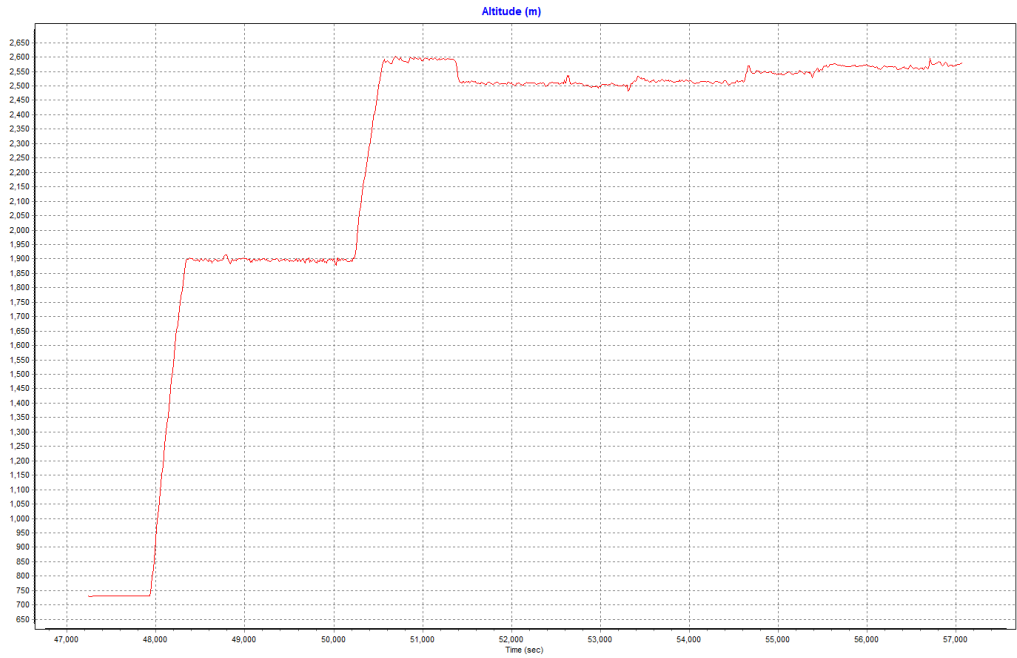


— North Position Error RMS (m) — East Position Error RMS (m) — Down Position Error RMS (m)

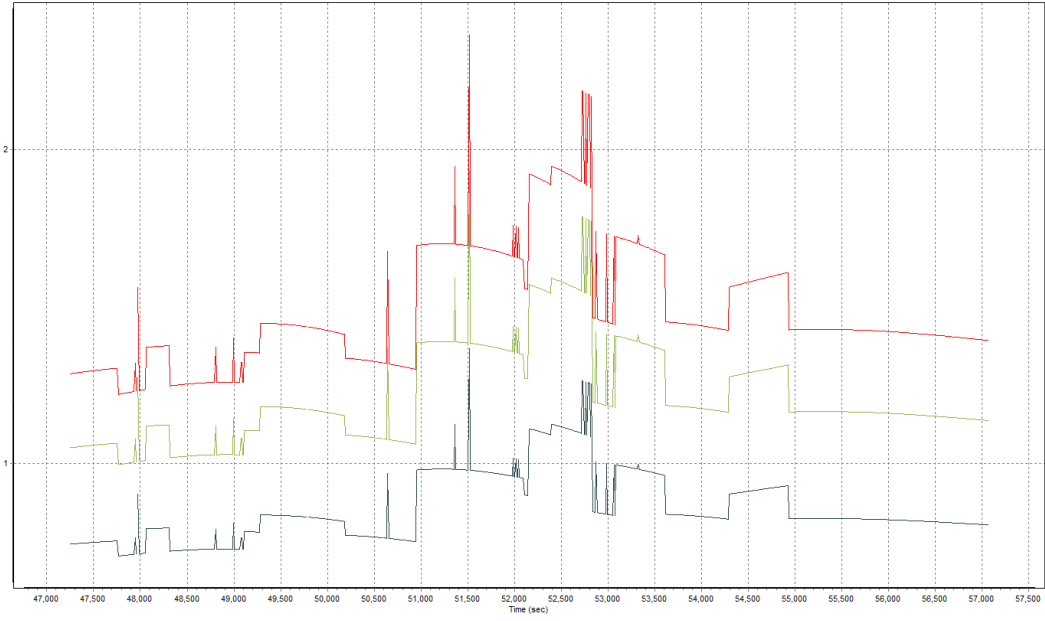


# CAU16346A



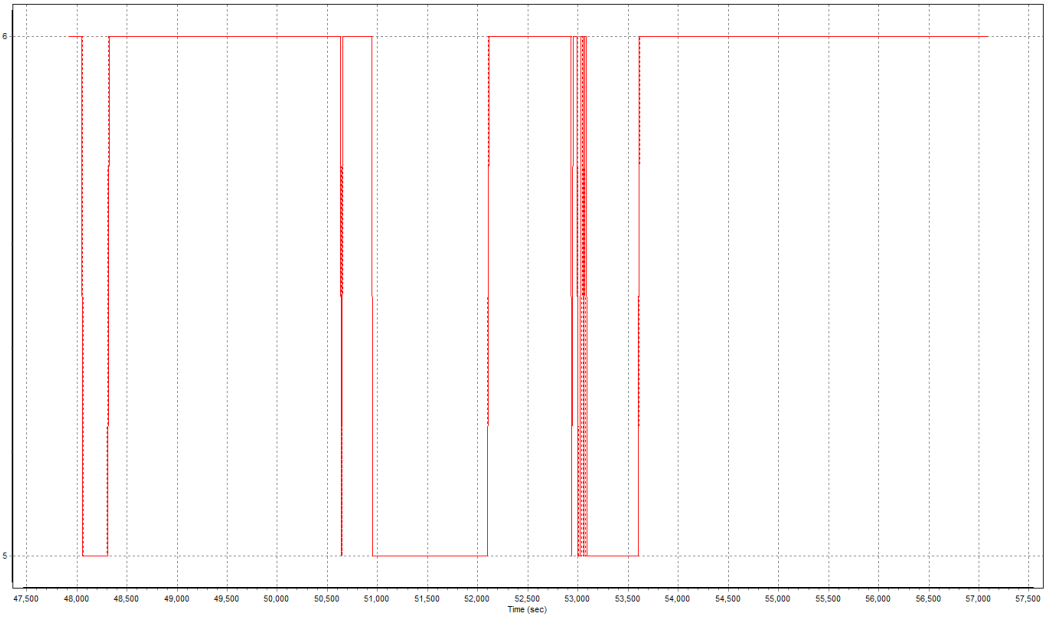


DOP



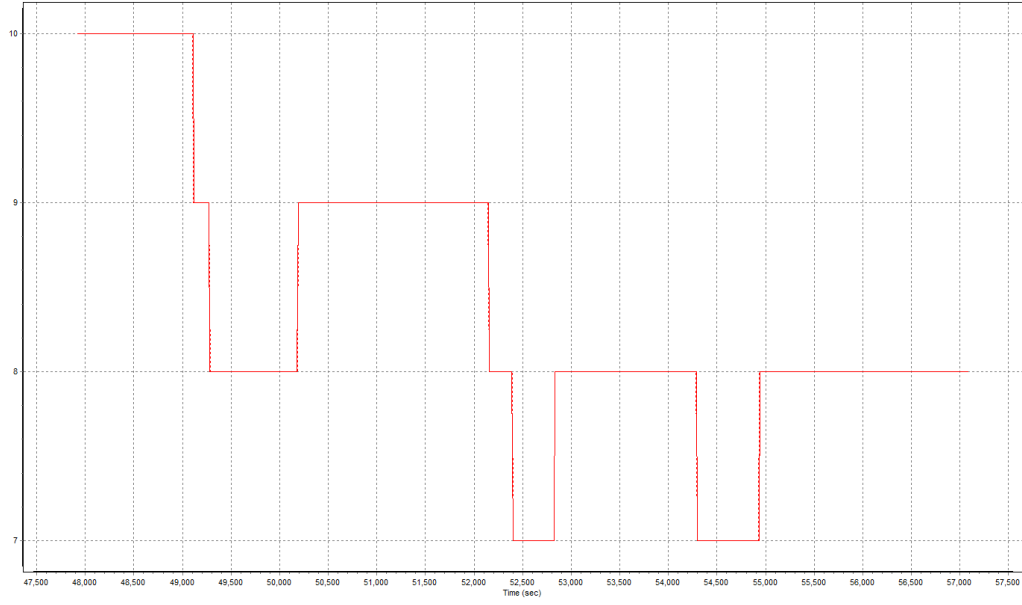
PDOP HDOP VDOP

Number of GLONASS Satellites

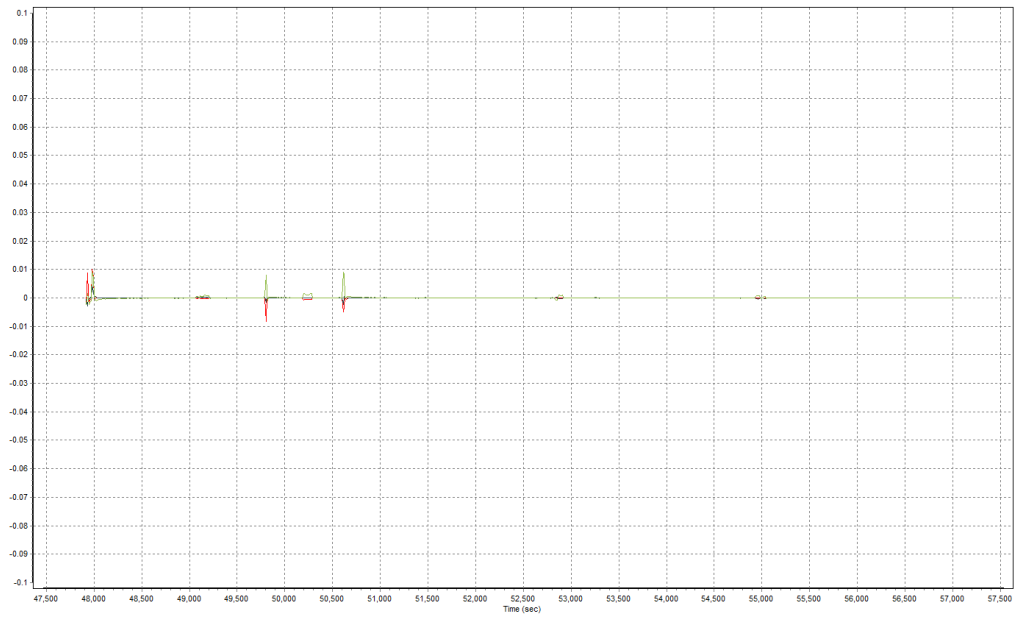


Forward Reverse

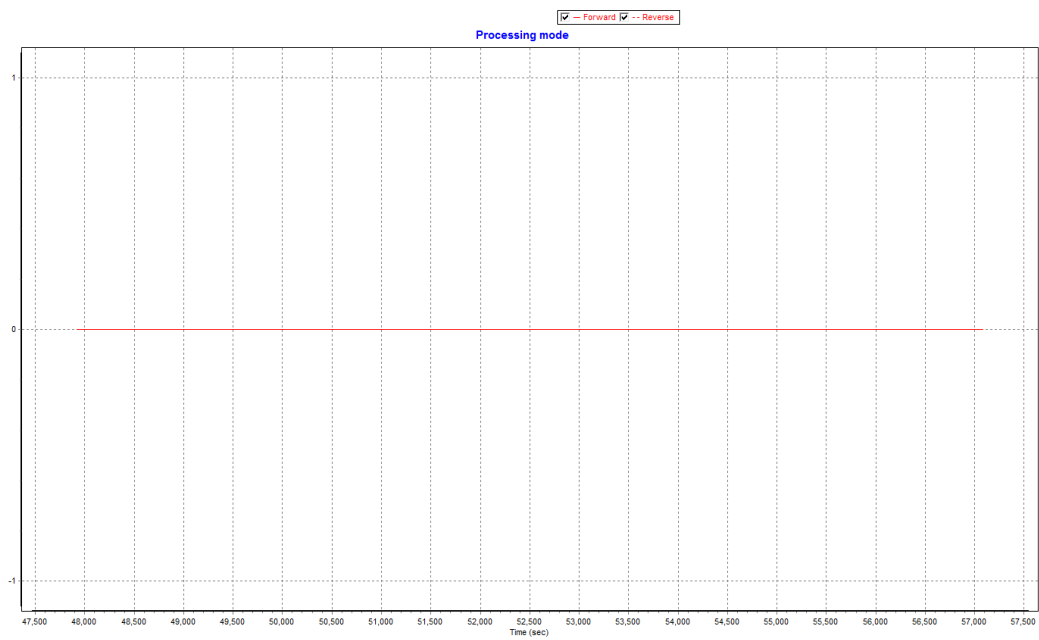
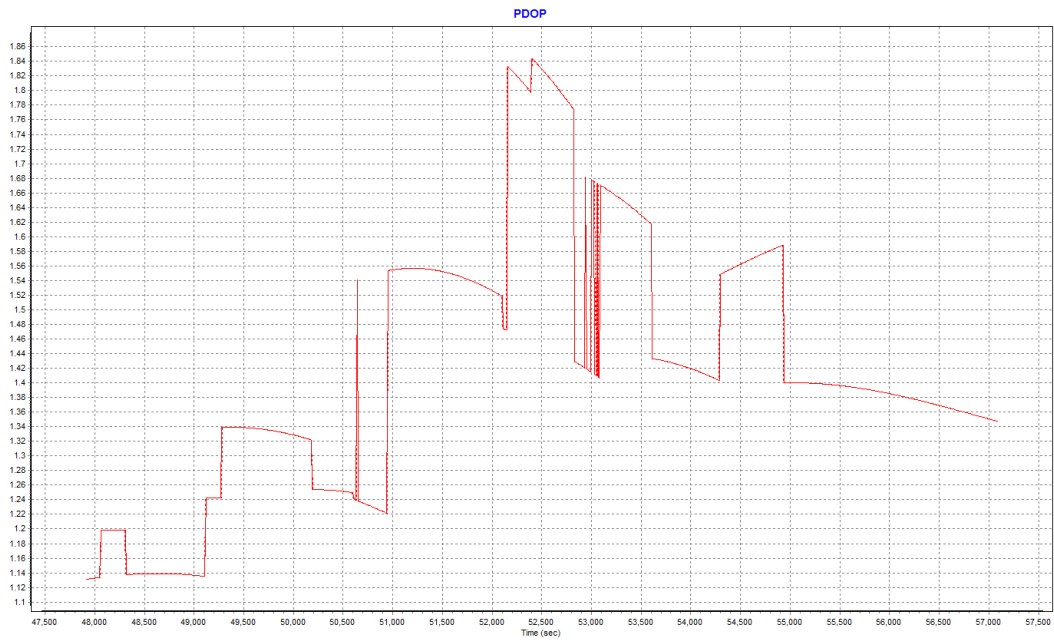
Number of GPS Satellites



Forward  Reverse



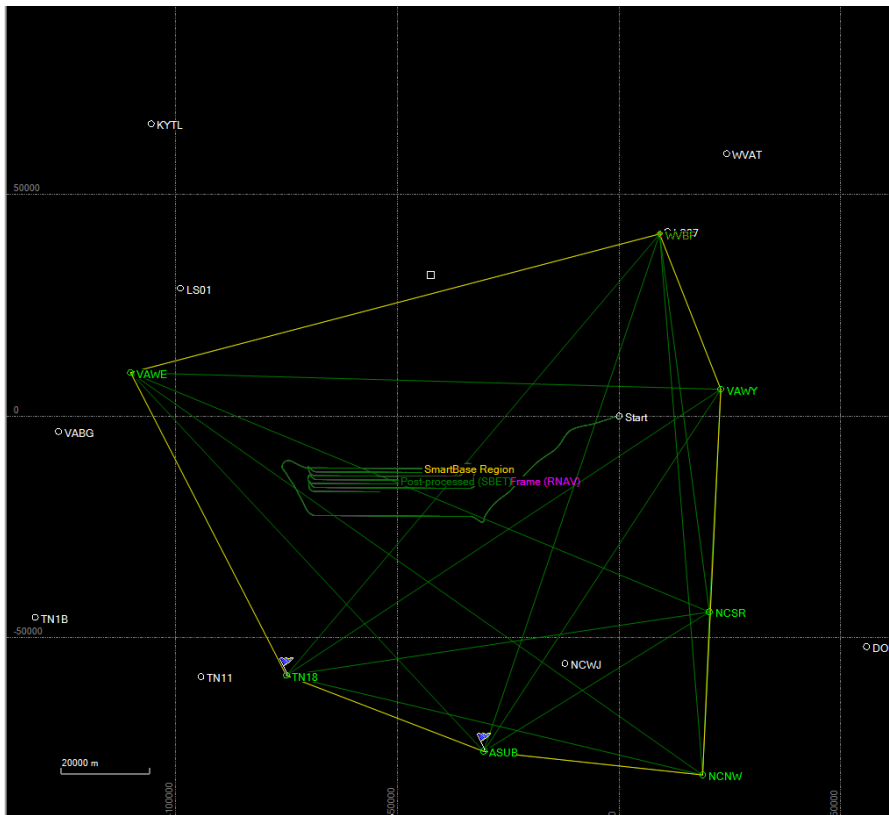
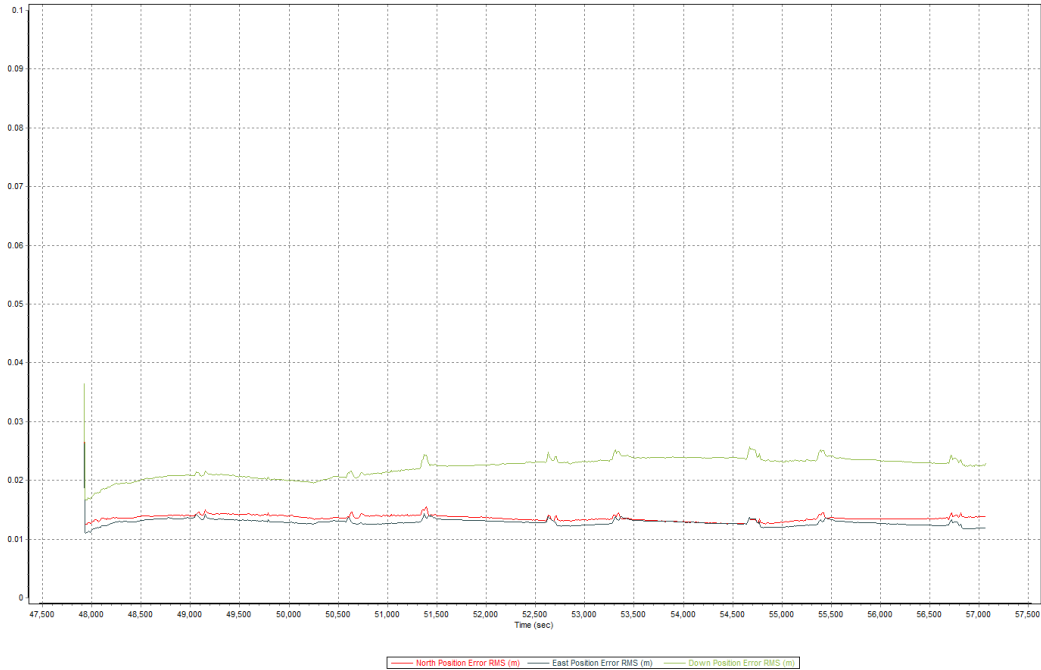
North (m)  East (m)  Down (m)  DR mode



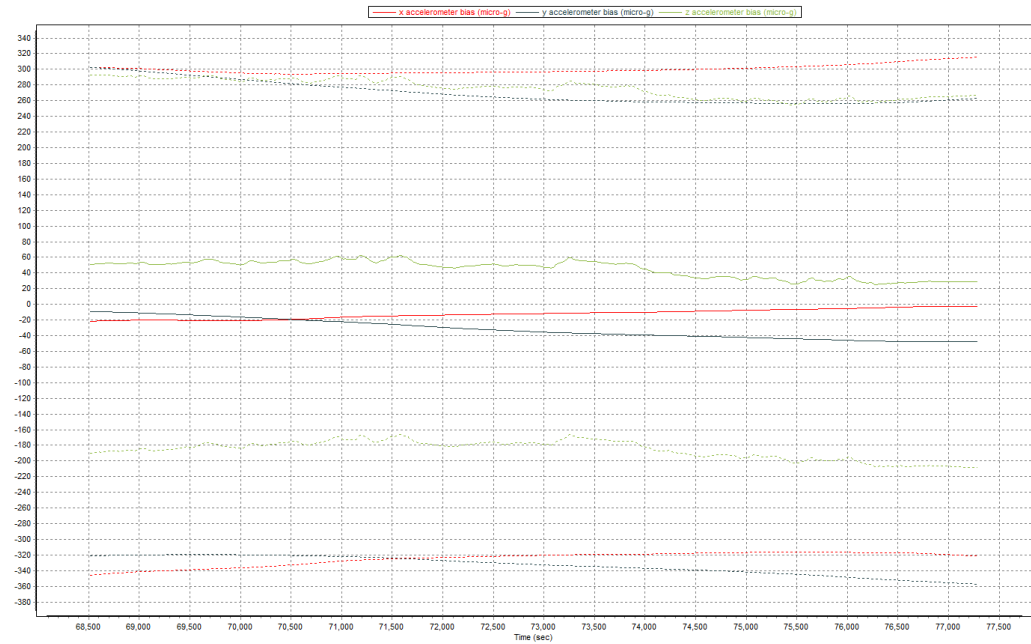
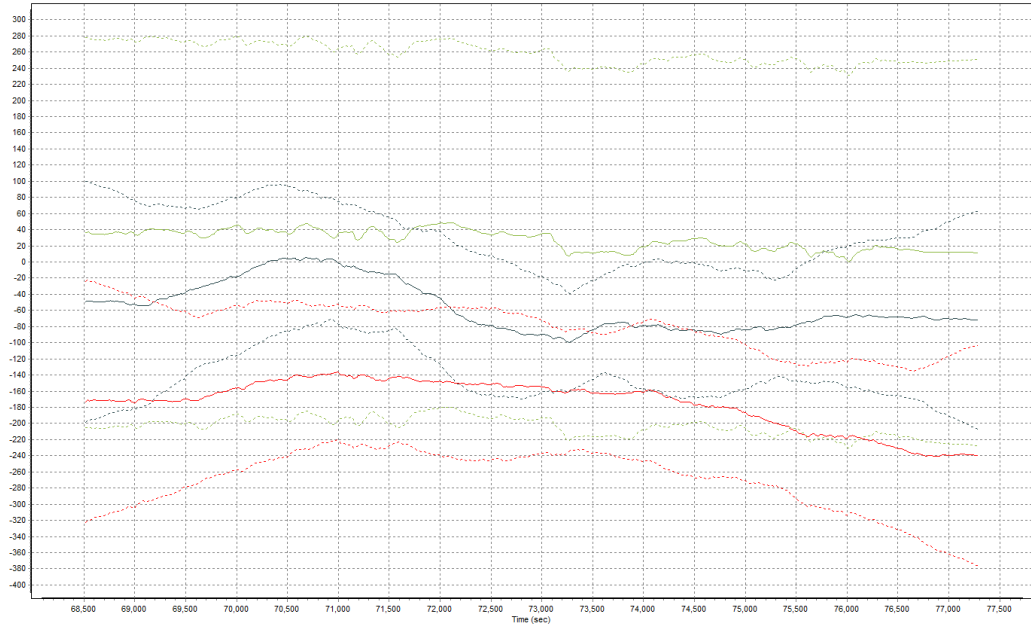
0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IA PPP, 6 = CIA, 7 = GNSS Nav, 8 = DR

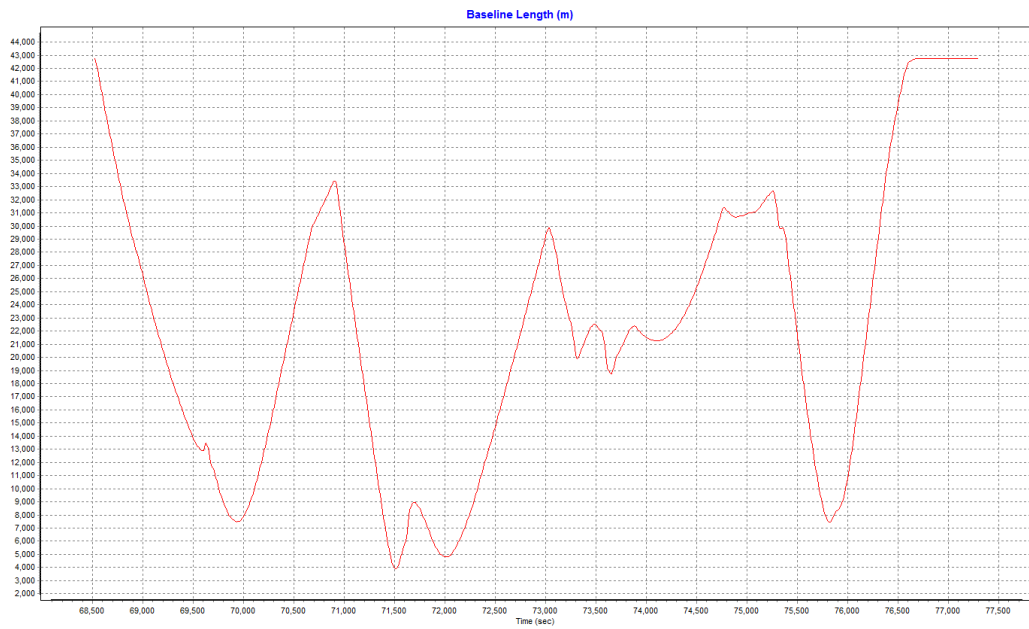
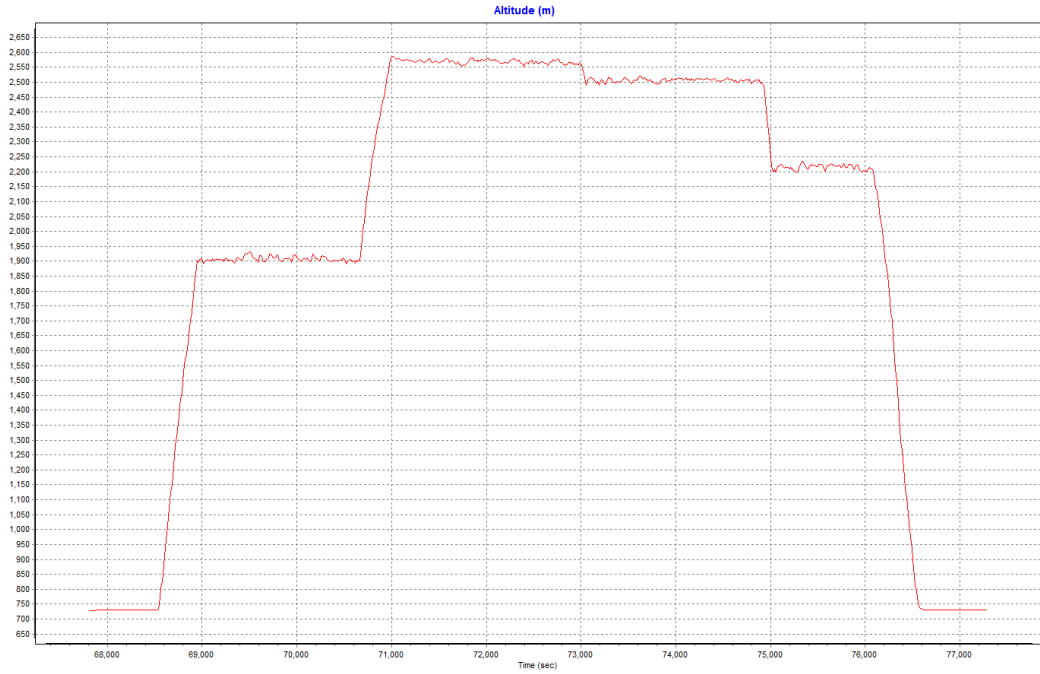
Forward  Reverse





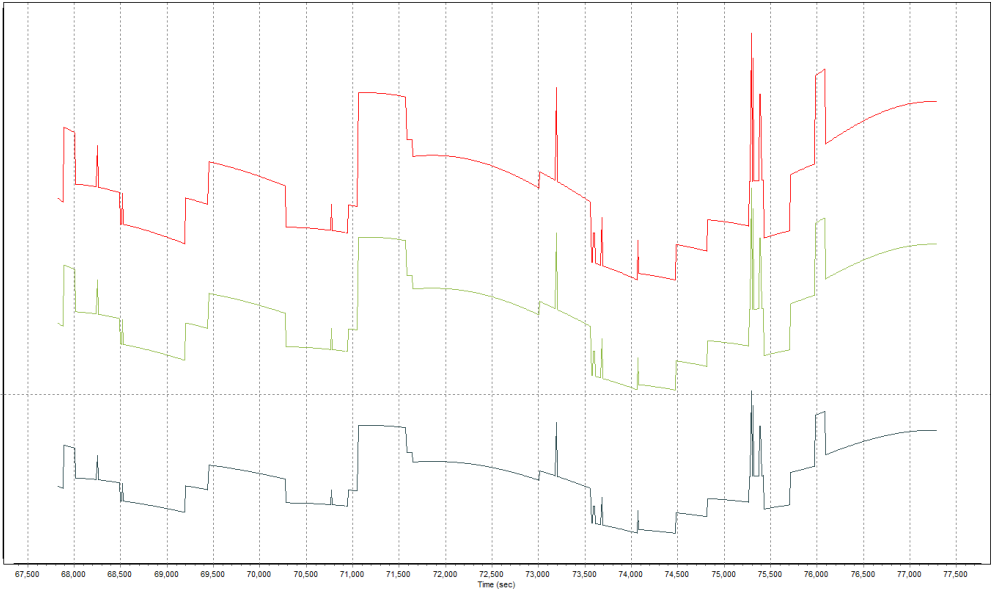
# CAU16346B





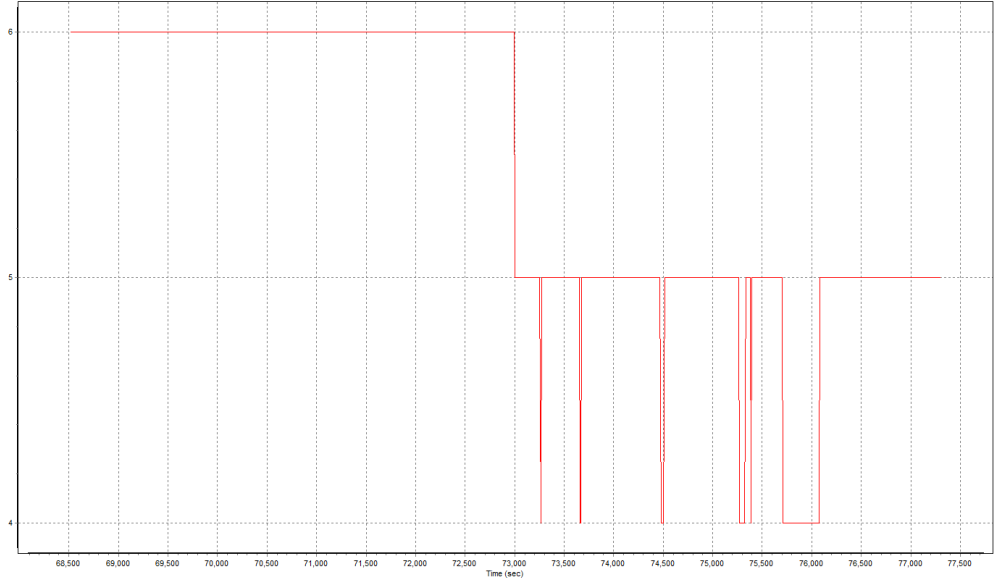
Forward  Reverse

DOP



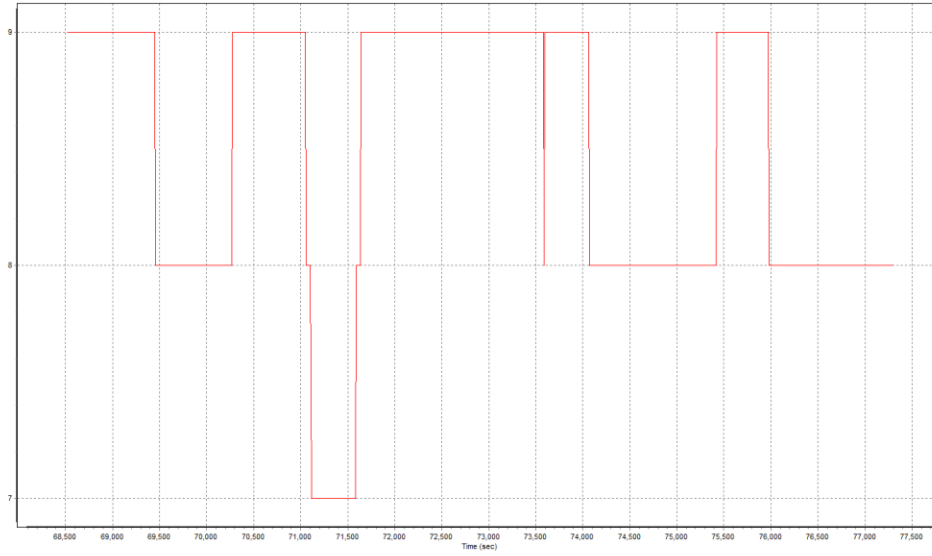
— PDOP — GDOP — VDOP

Number of GLONASS Satellites

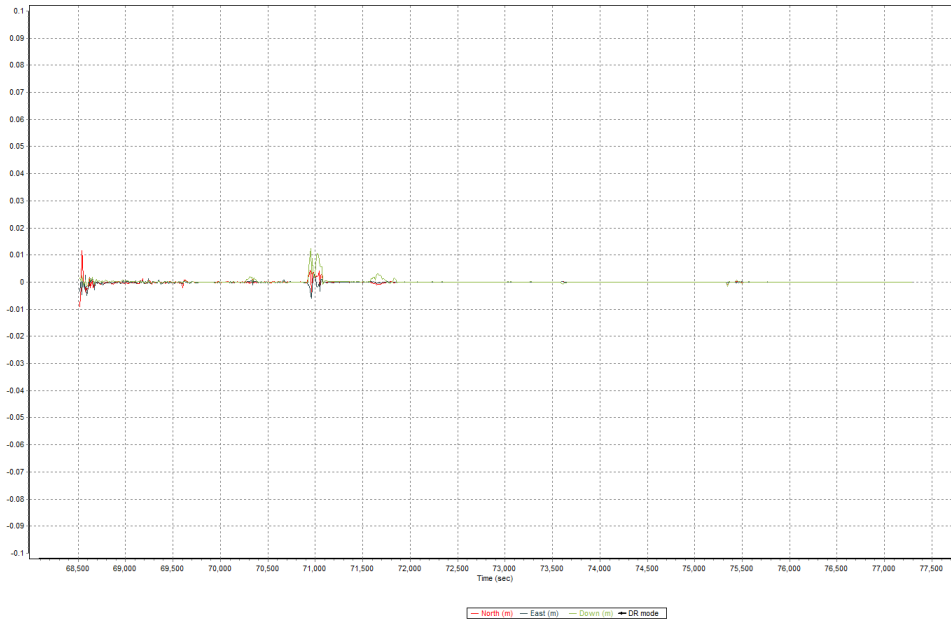


Forward  Reverse

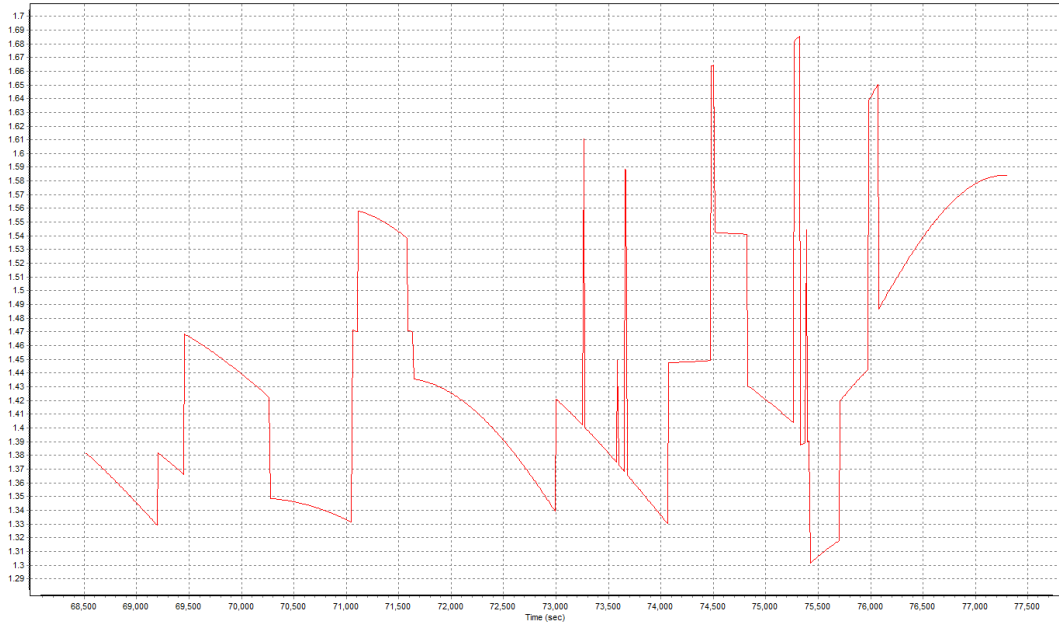
Number of GPS Satellites



Forward  Reverse

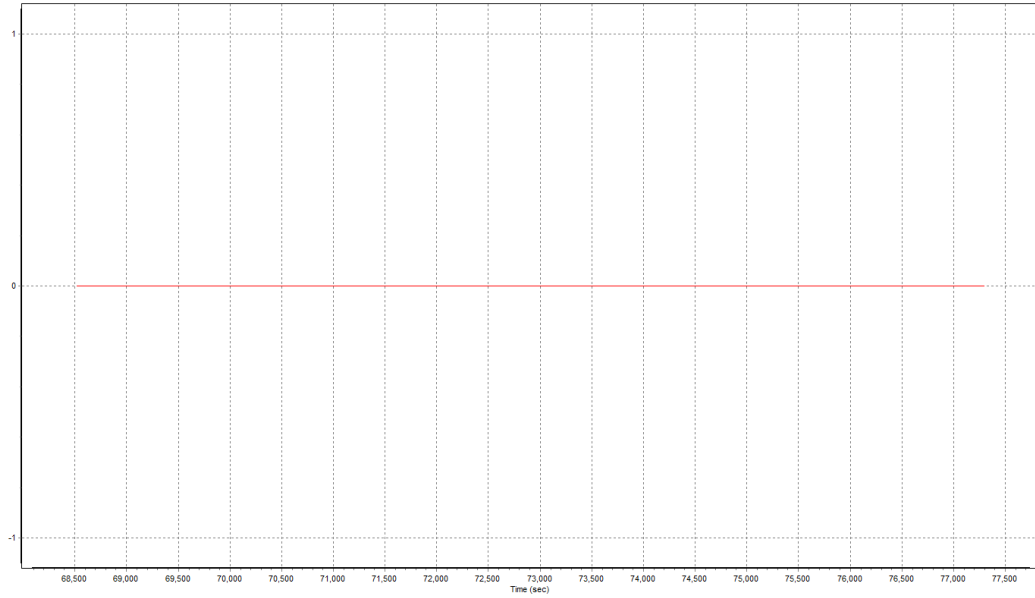


PDOP



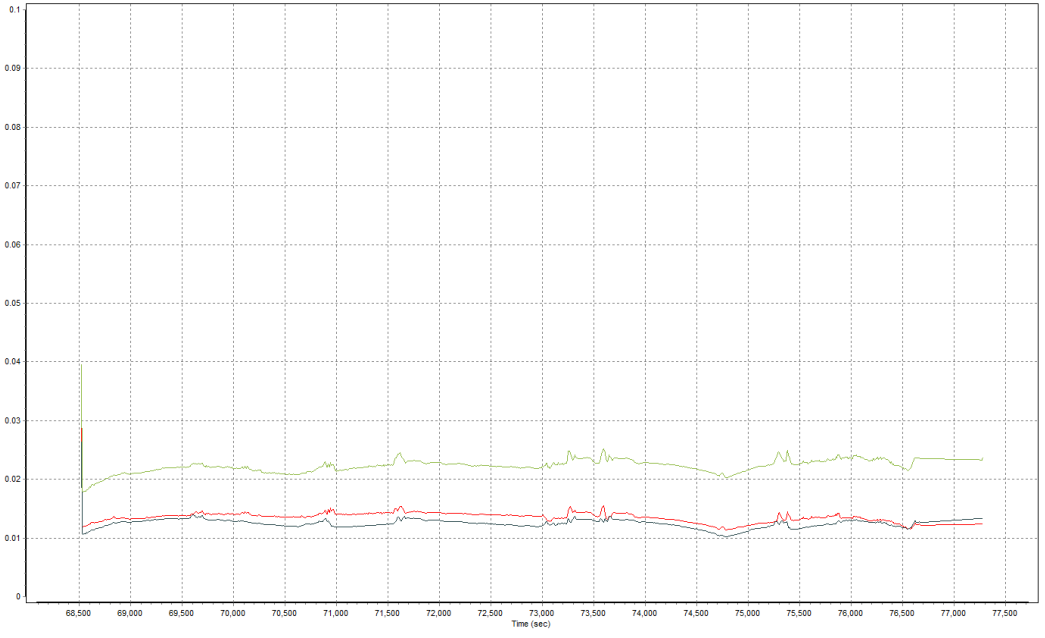
Forward  Reverse

Processing mode

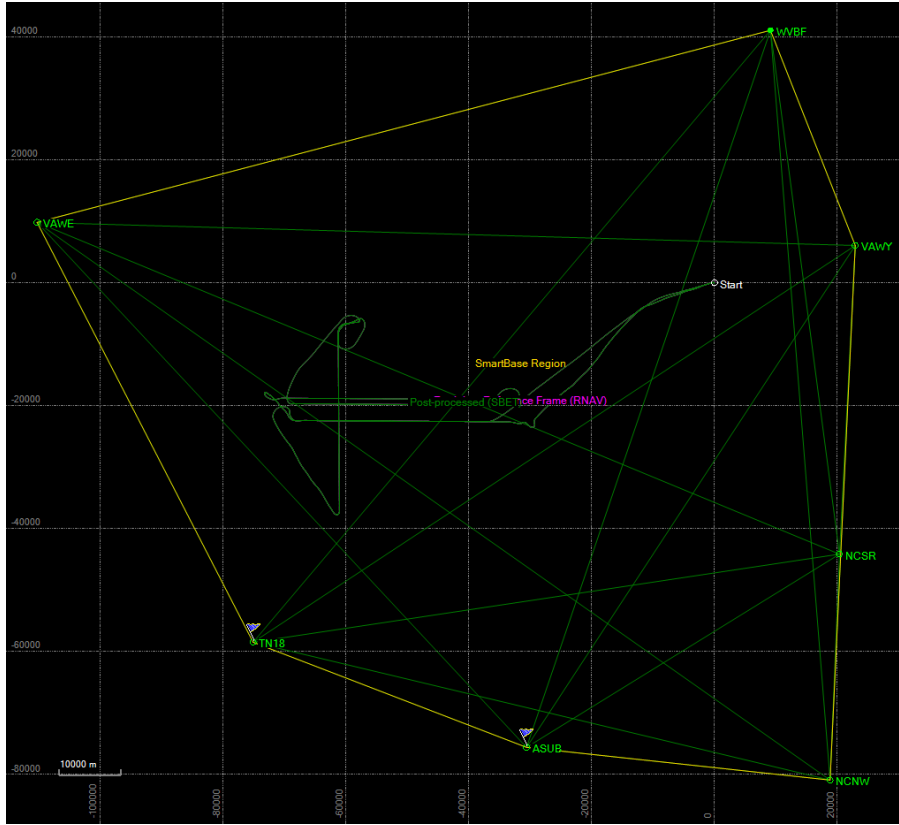


Forward  Reverse

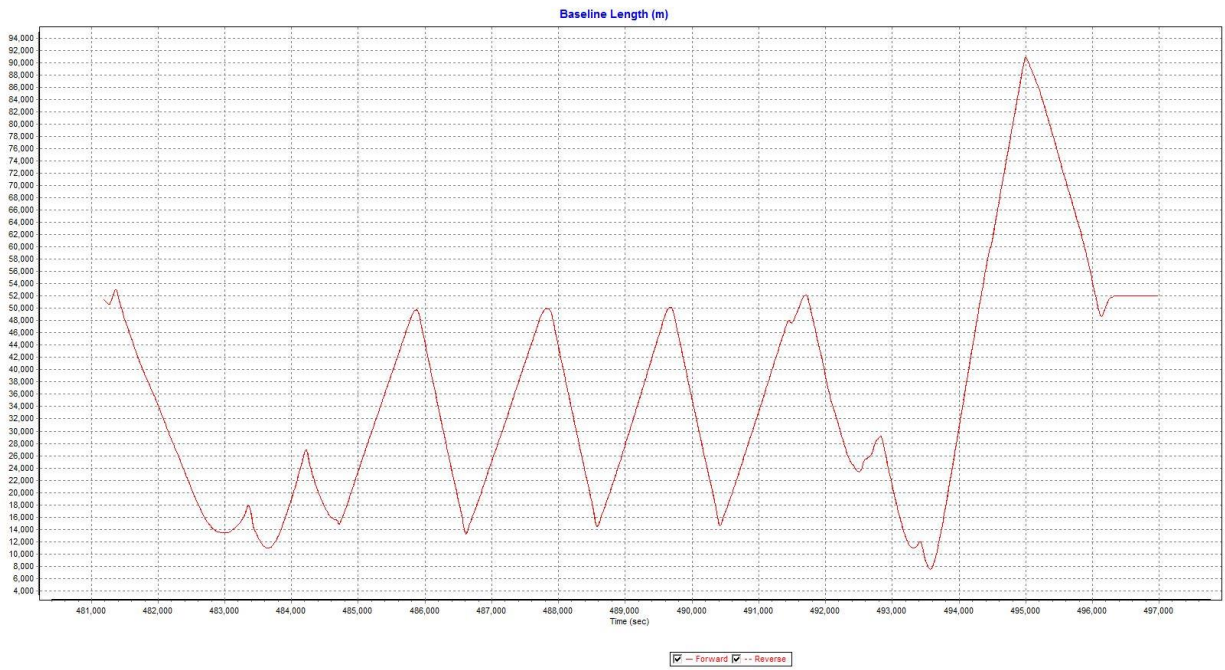
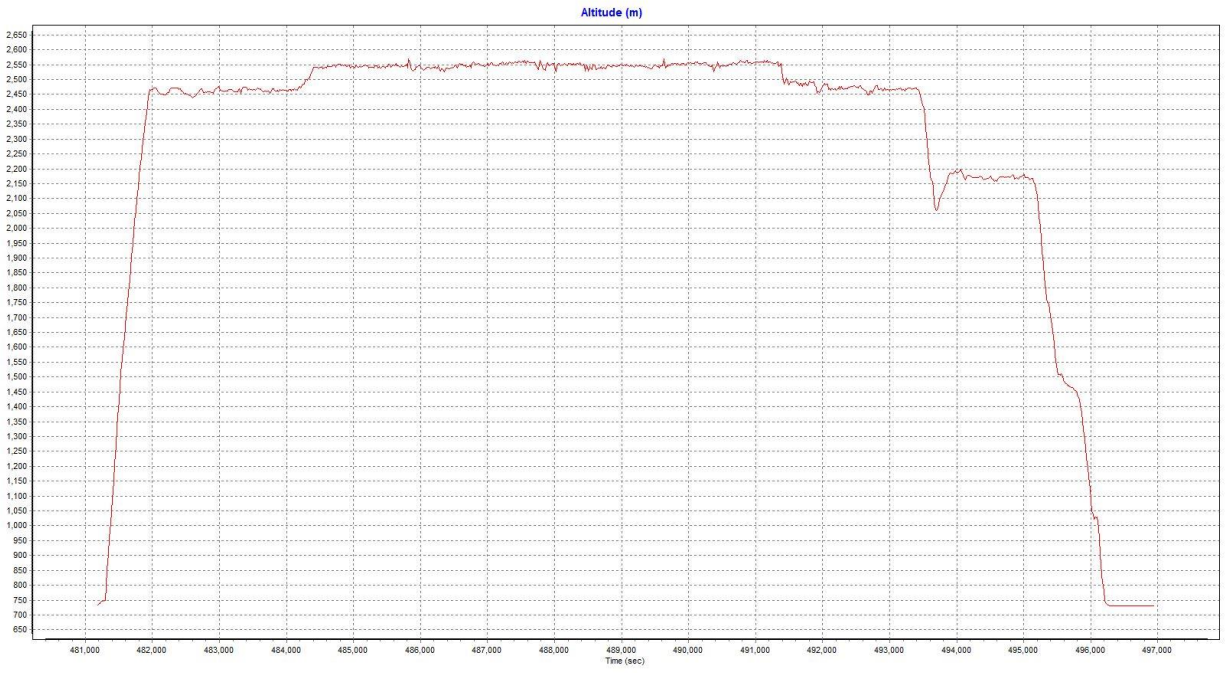
0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = CIA, 7 = GNSS Nav, 8 = DR



— North Position Error RMS (m) — East Position Error RMS (m) — Down Position Error RMS (m)

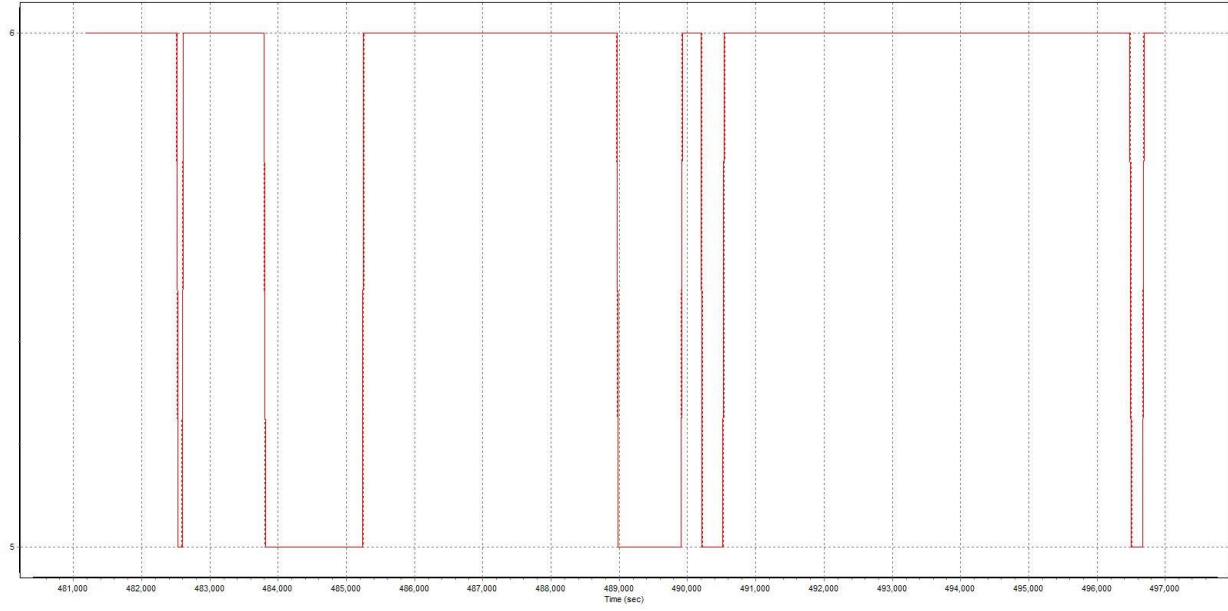


# CAU16351A



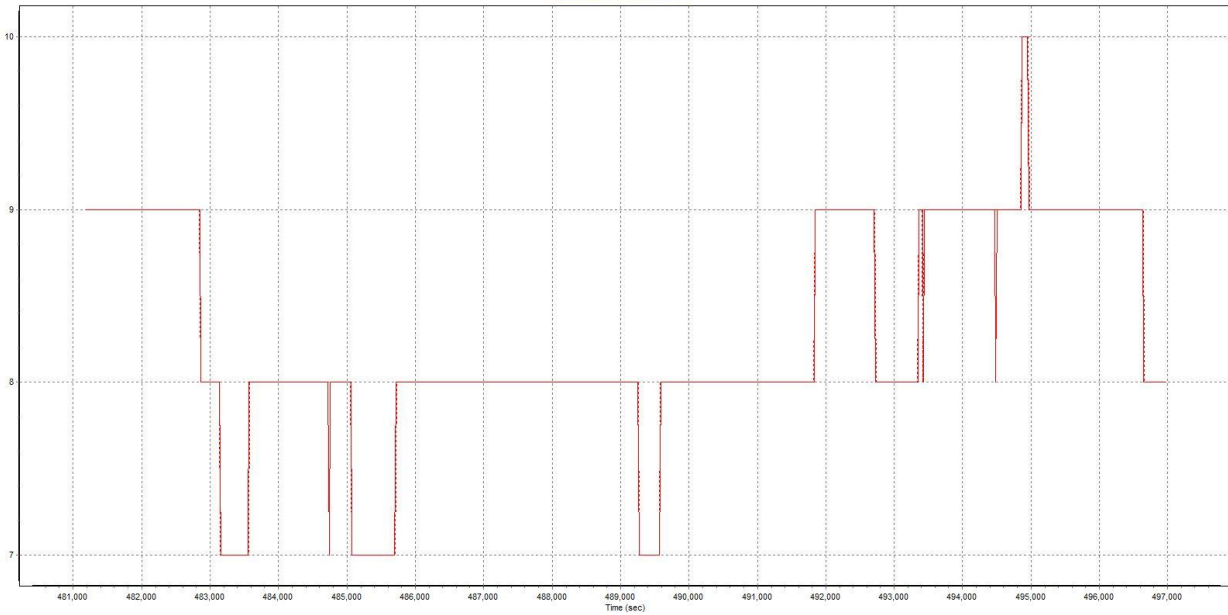


Number of GLONASS Satellites



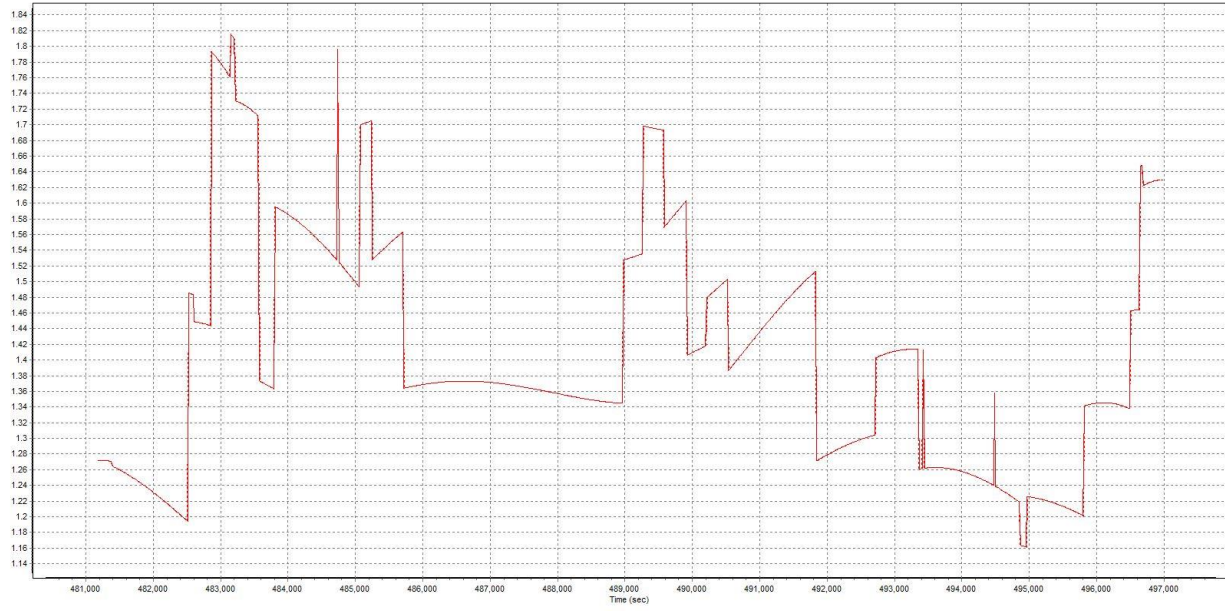
Forward  Reverse

Number of GPS Satellites



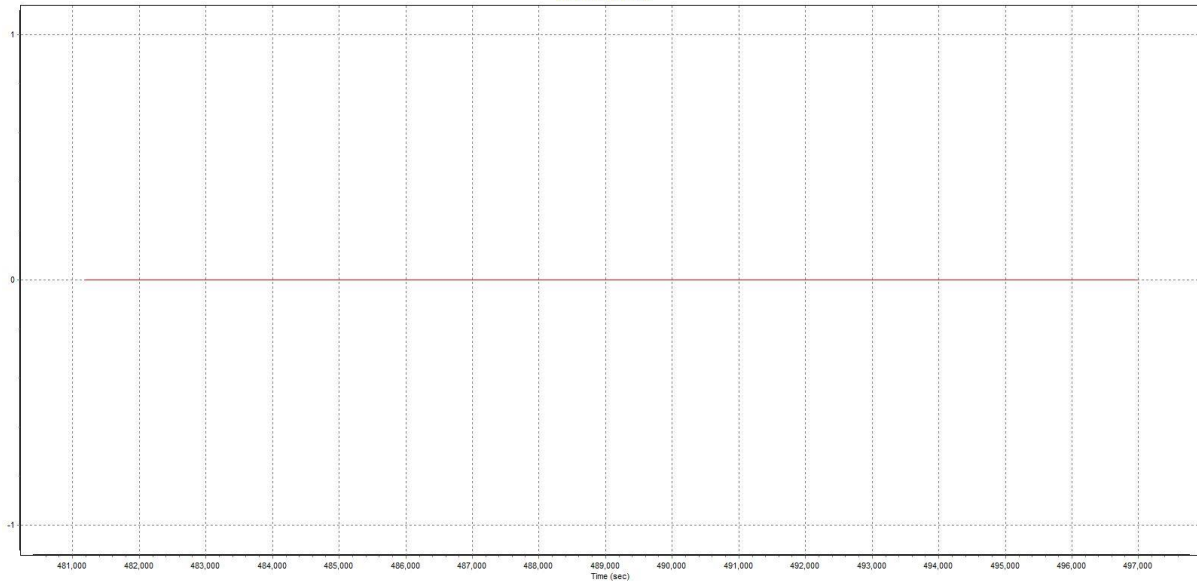
Forward  Reverse

PDOP



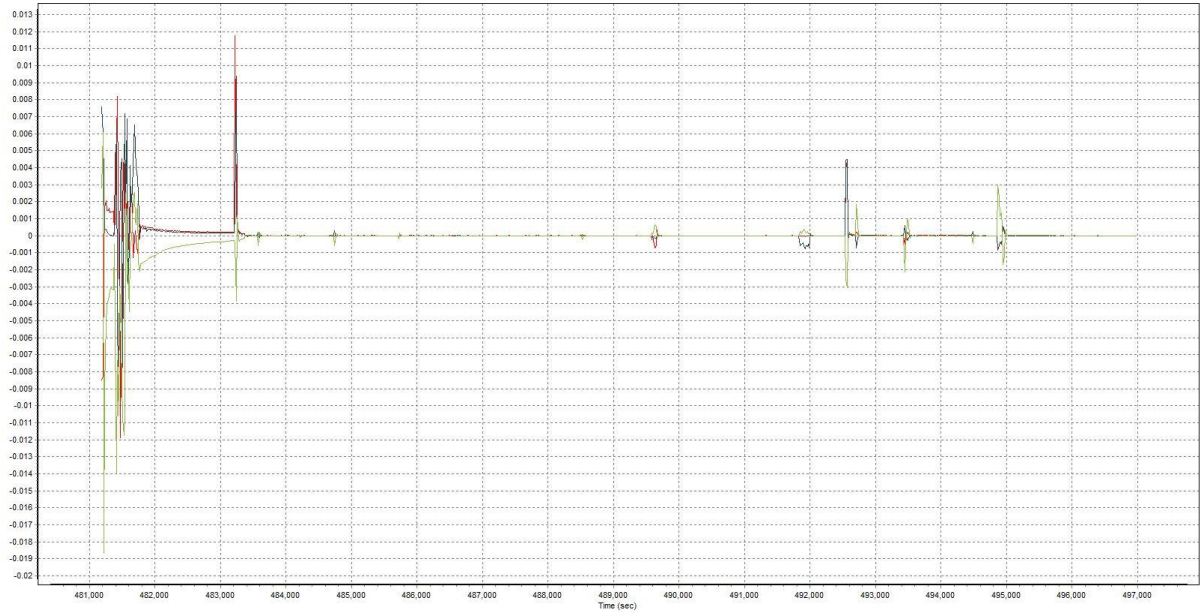
Forward  Reverse

Processing mode

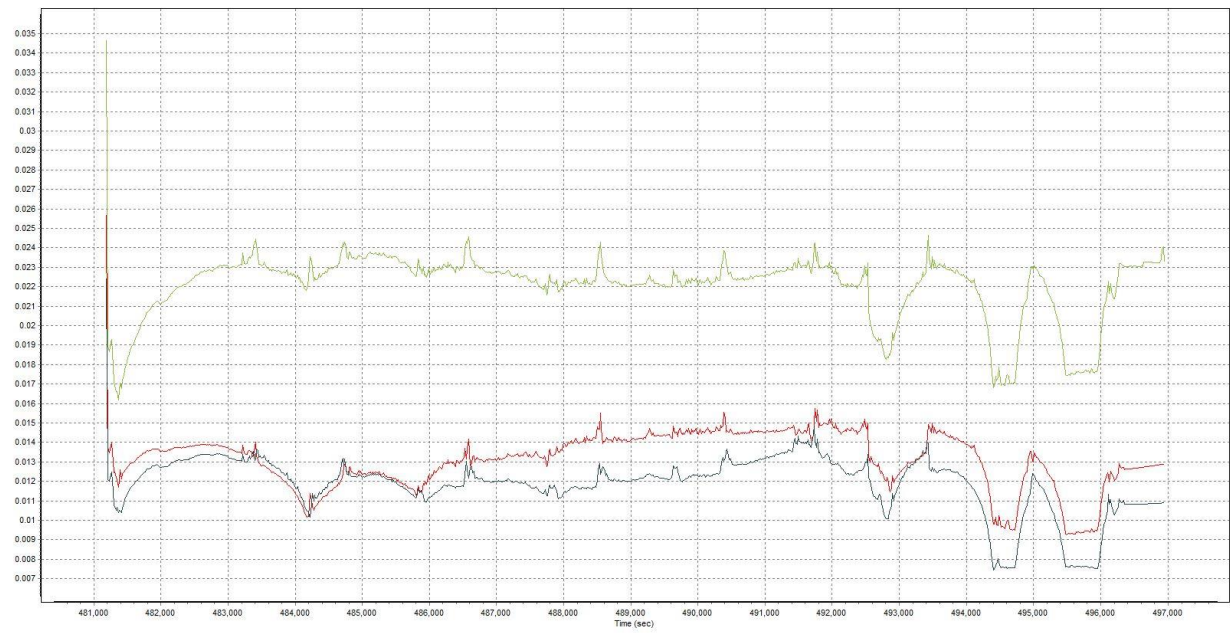


Forward  Reverse

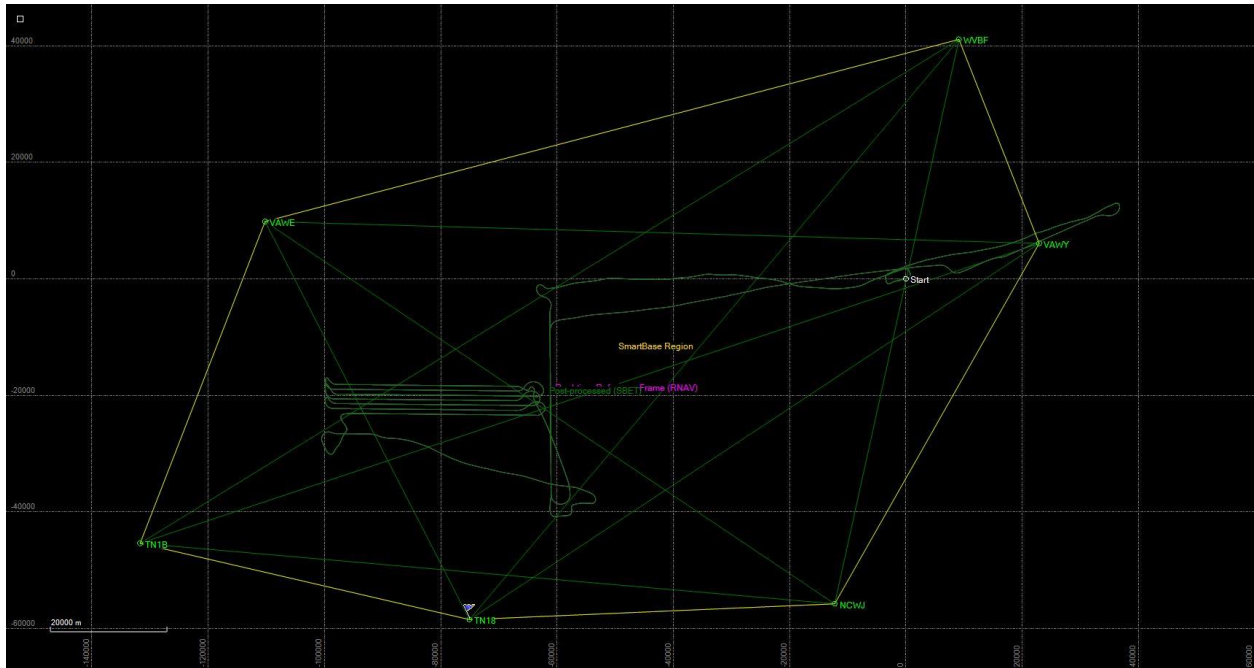
0 = Fixed NLL, 1 = Fixed WL, 2 = Float, 3 = DGNS, 4 = RTCM, 5 = IAPPP, 6 = C/A, 7 = GNSS Nav, 8 = DR

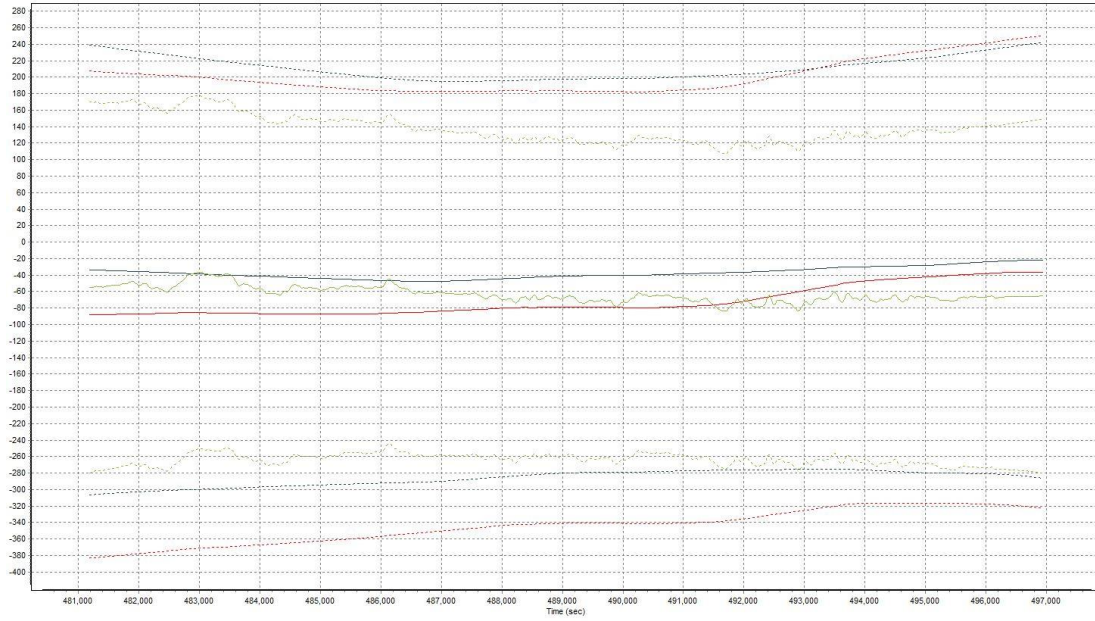


— North (m) — East (m) — Down (m) — DR mode

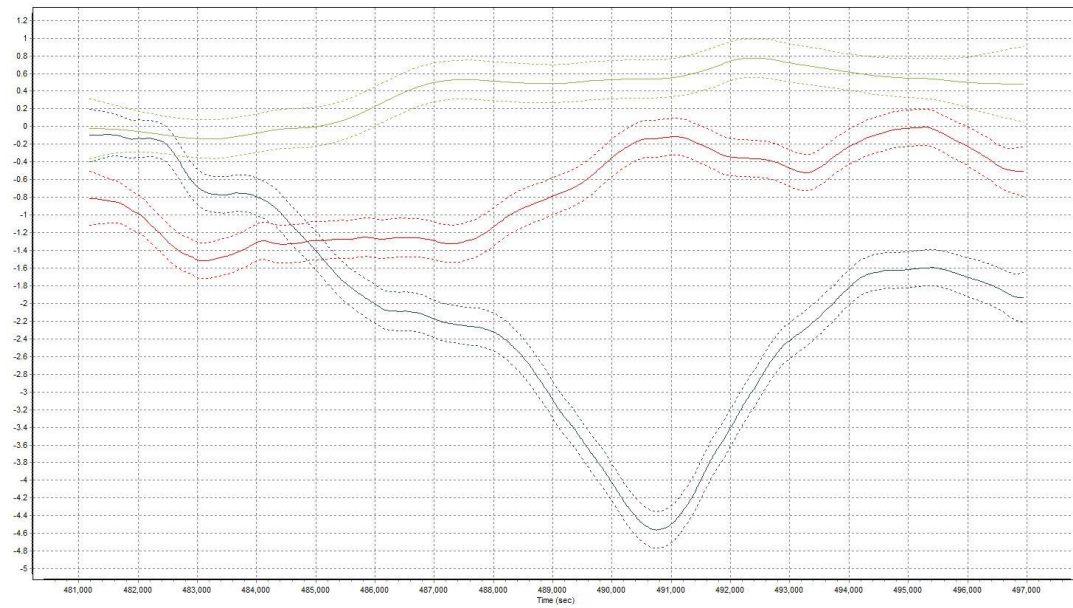


— North Position Error RMS (m) — East Position Error RMS (m) — Down Position Error RMS (m)

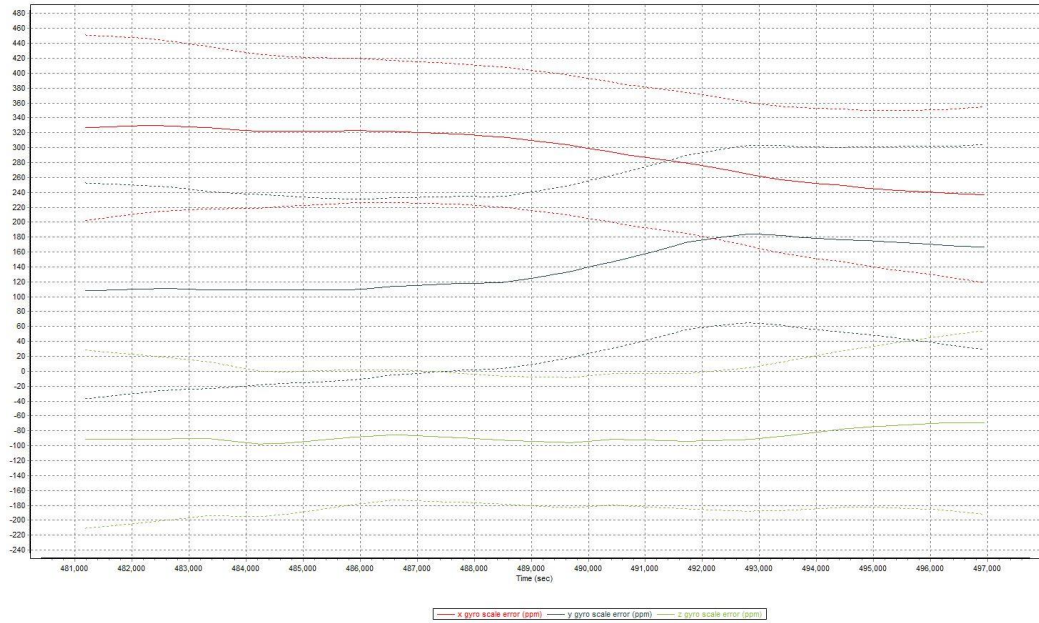




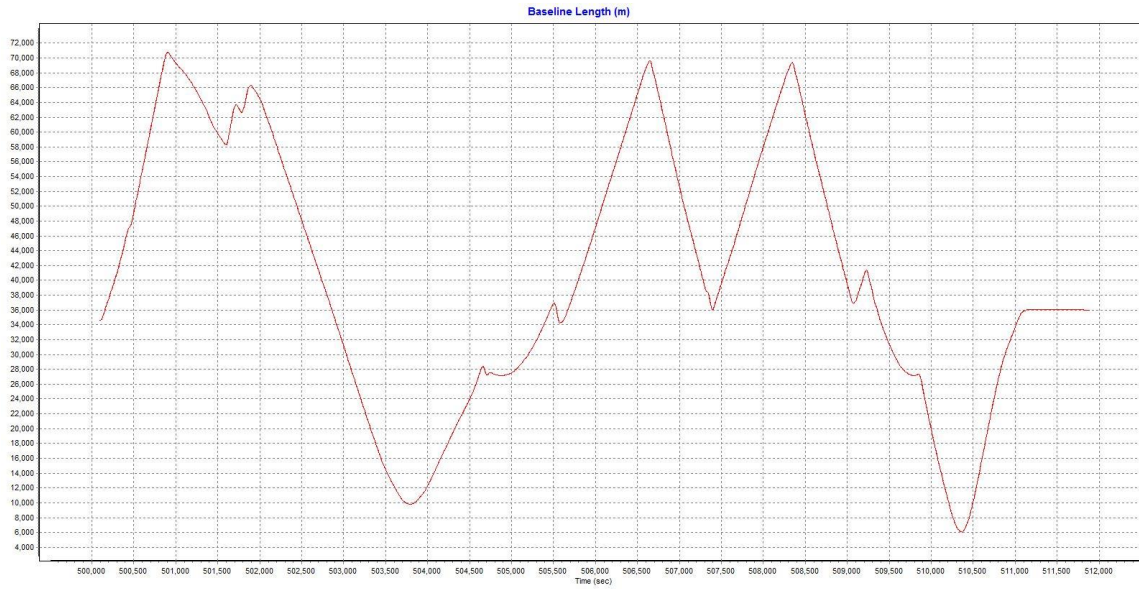
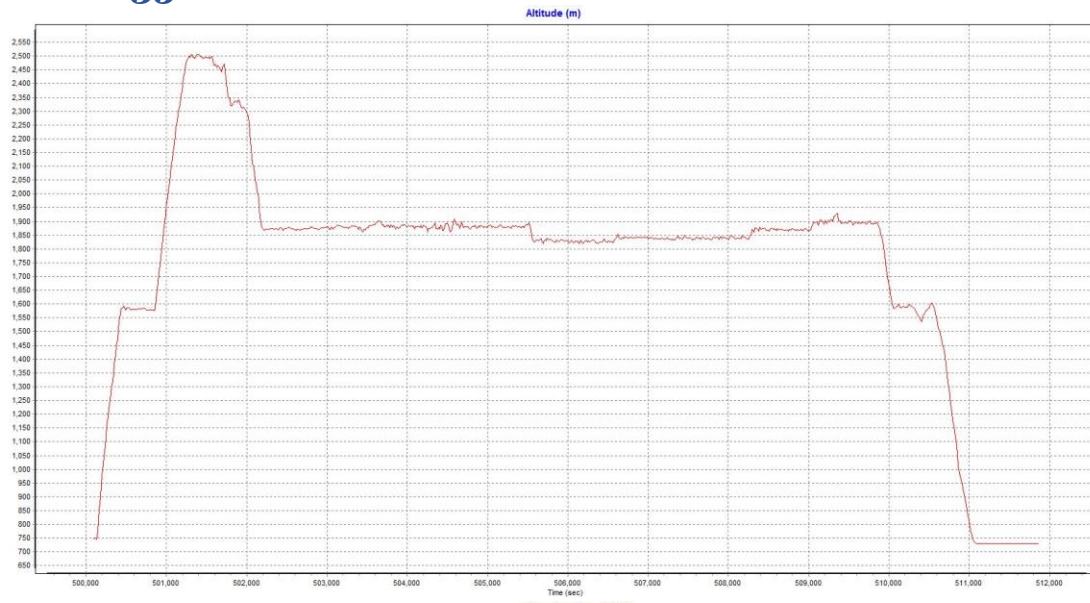
— x accelerometer scale error (ppm) — y accelerometer scale error (ppm) — z accelerometer scale error (ppm)



— x gyro bias (deg/hr) — y gyro bias (deg/hr) — z gyro bias (deg/hr)

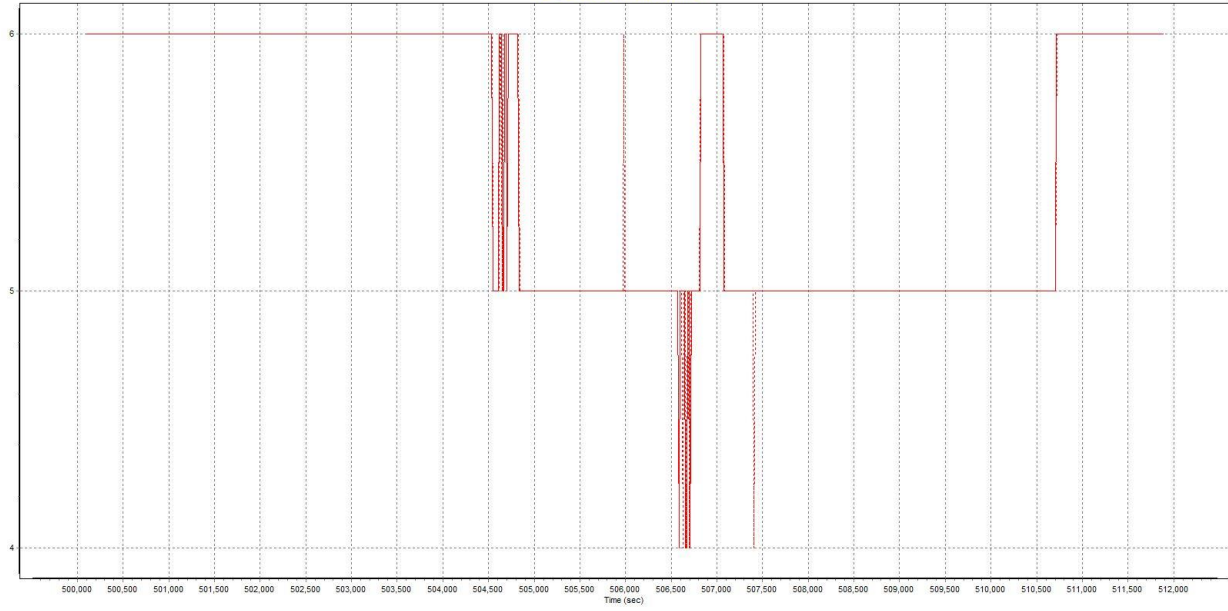


# CAU16351B



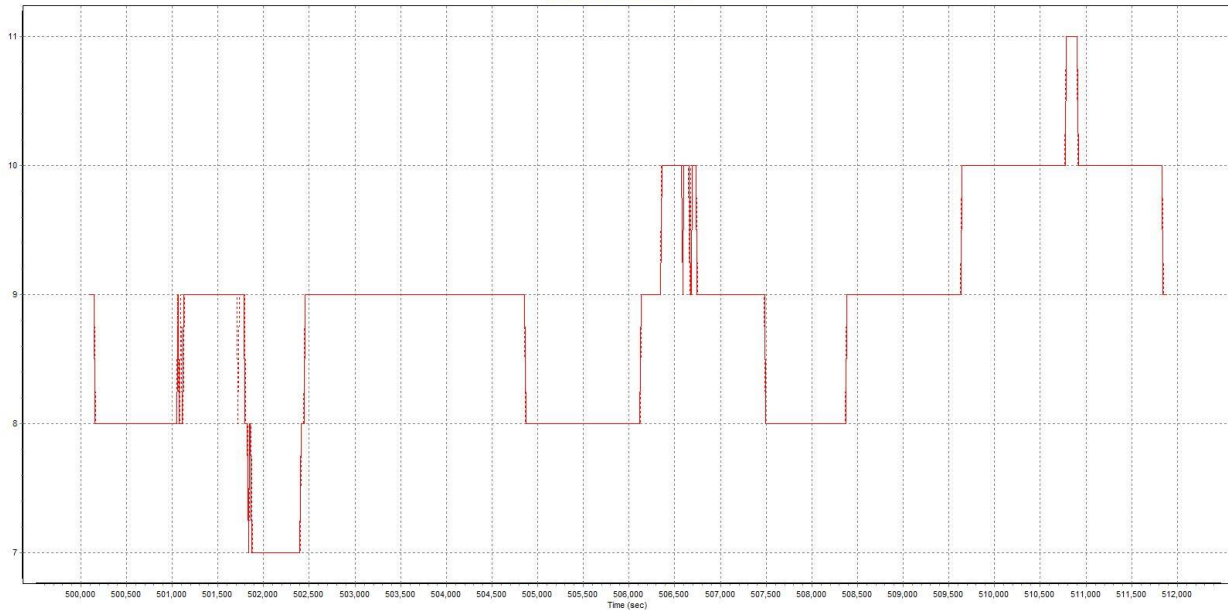
Forward  Reverse

Number of GLONASS Satellites



Forward  Reverse

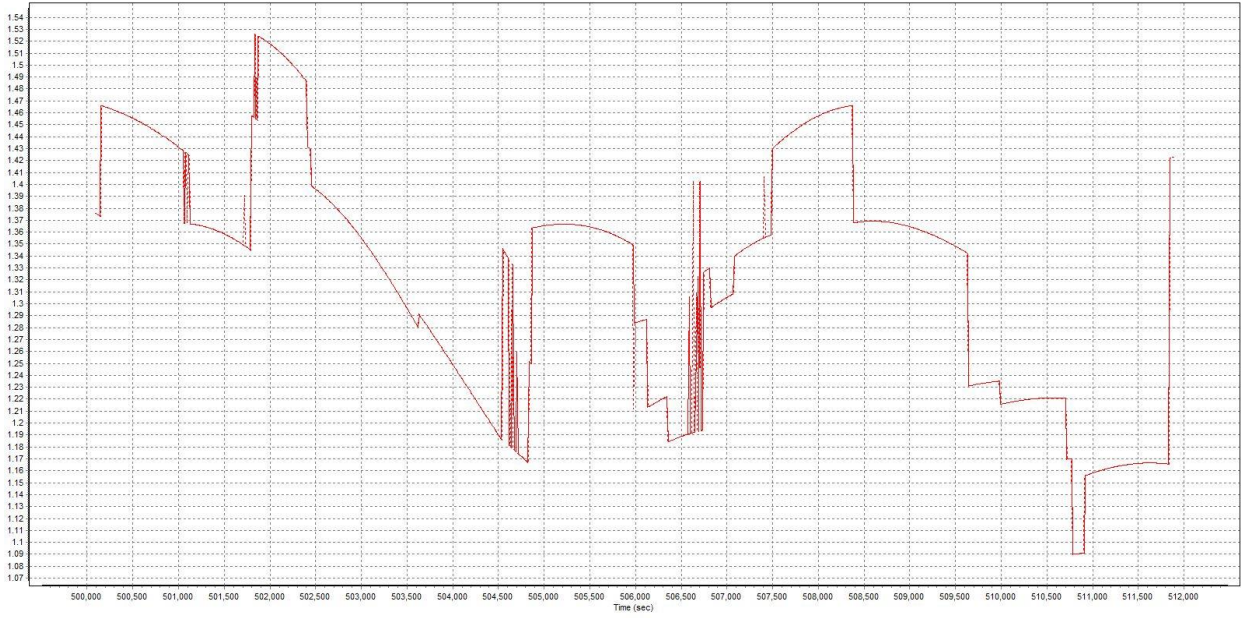
Number of GPS Satellites



Forward  Reverse

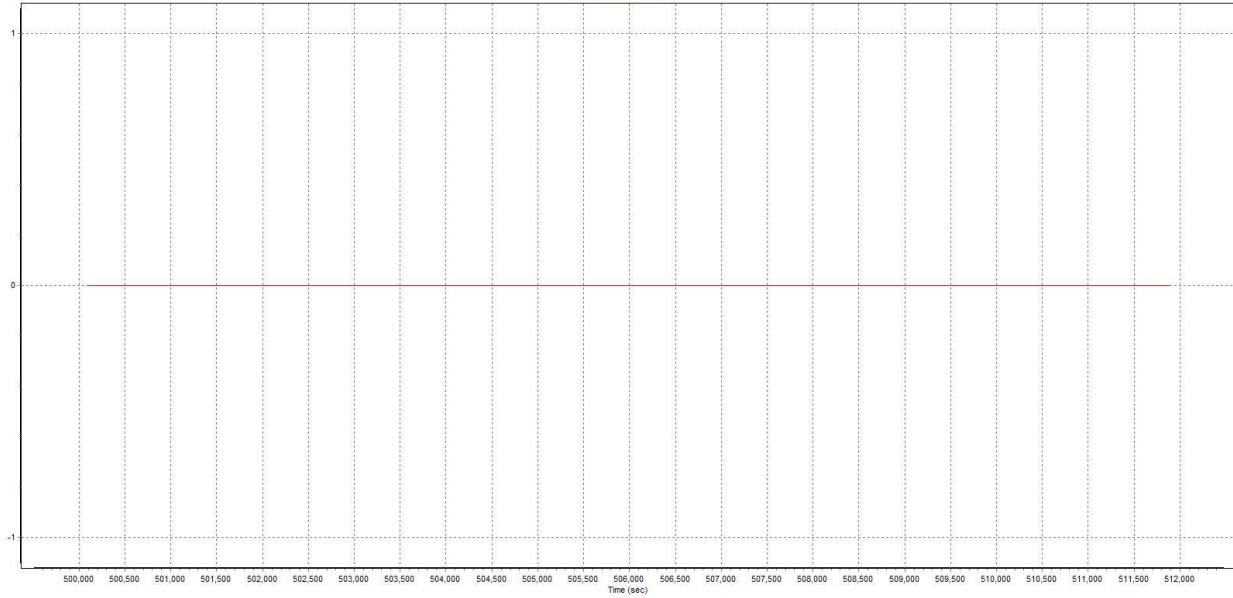


PDOP



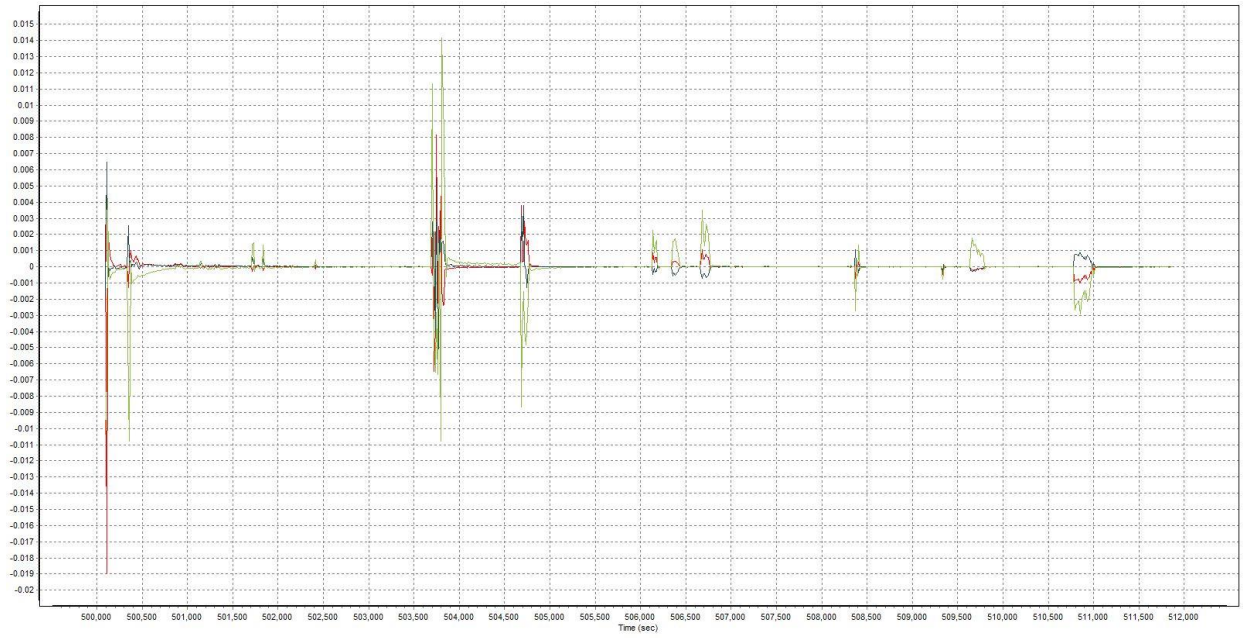
Forward  Reverse

Processing mode

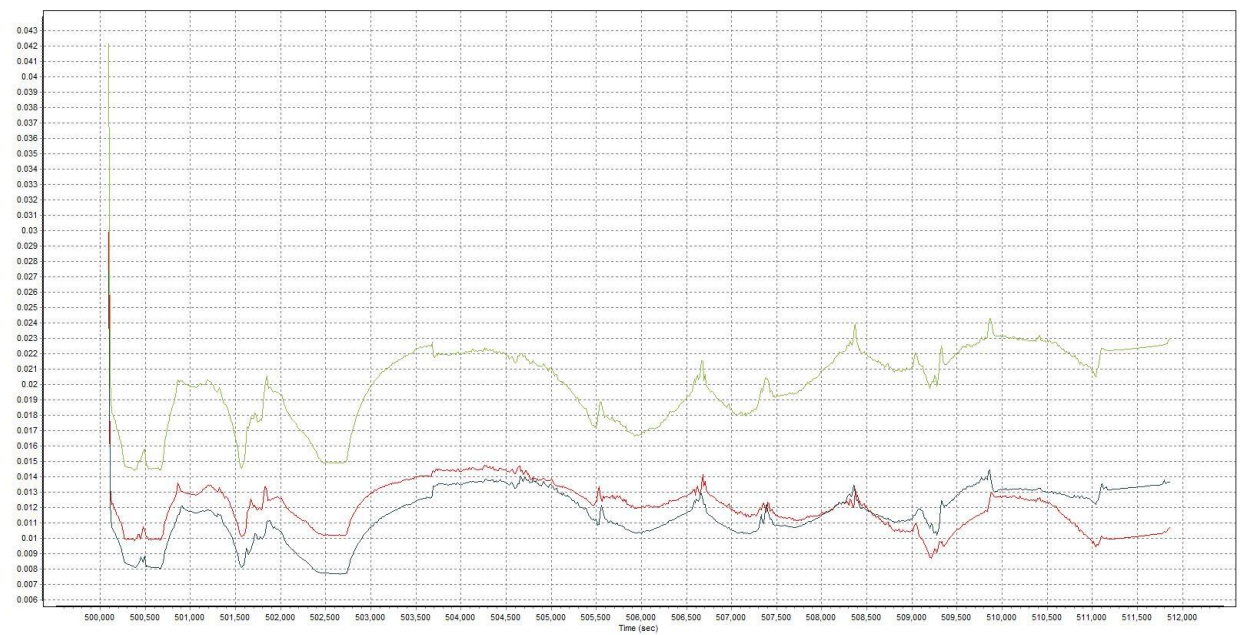


Forward  Reverse

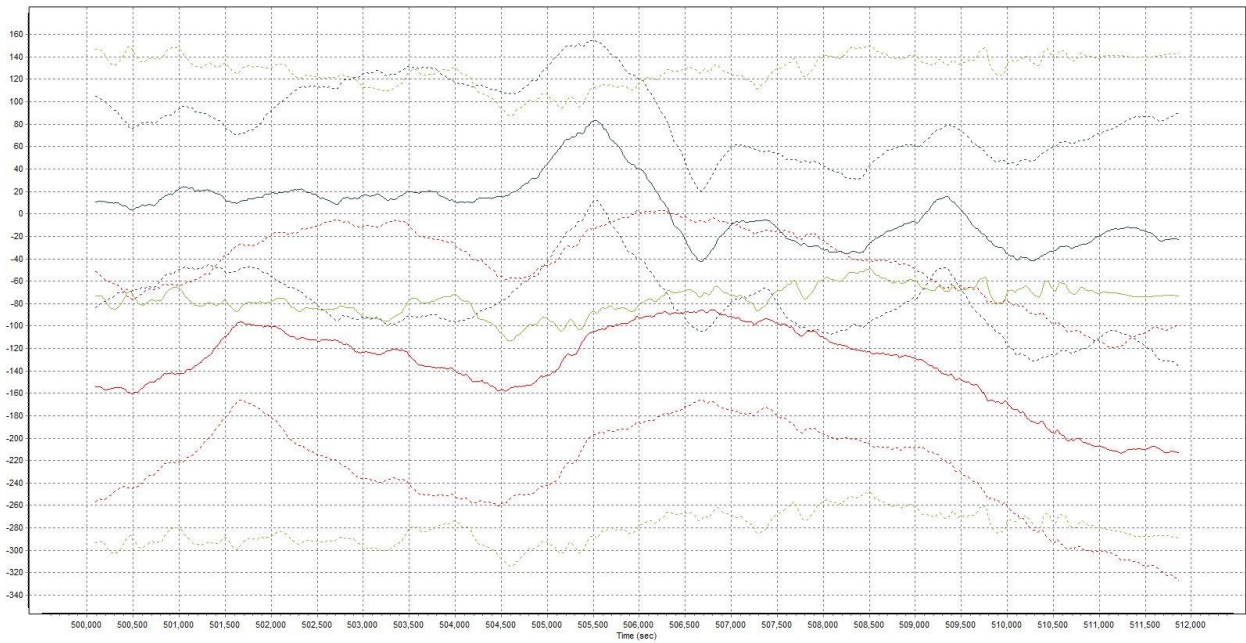
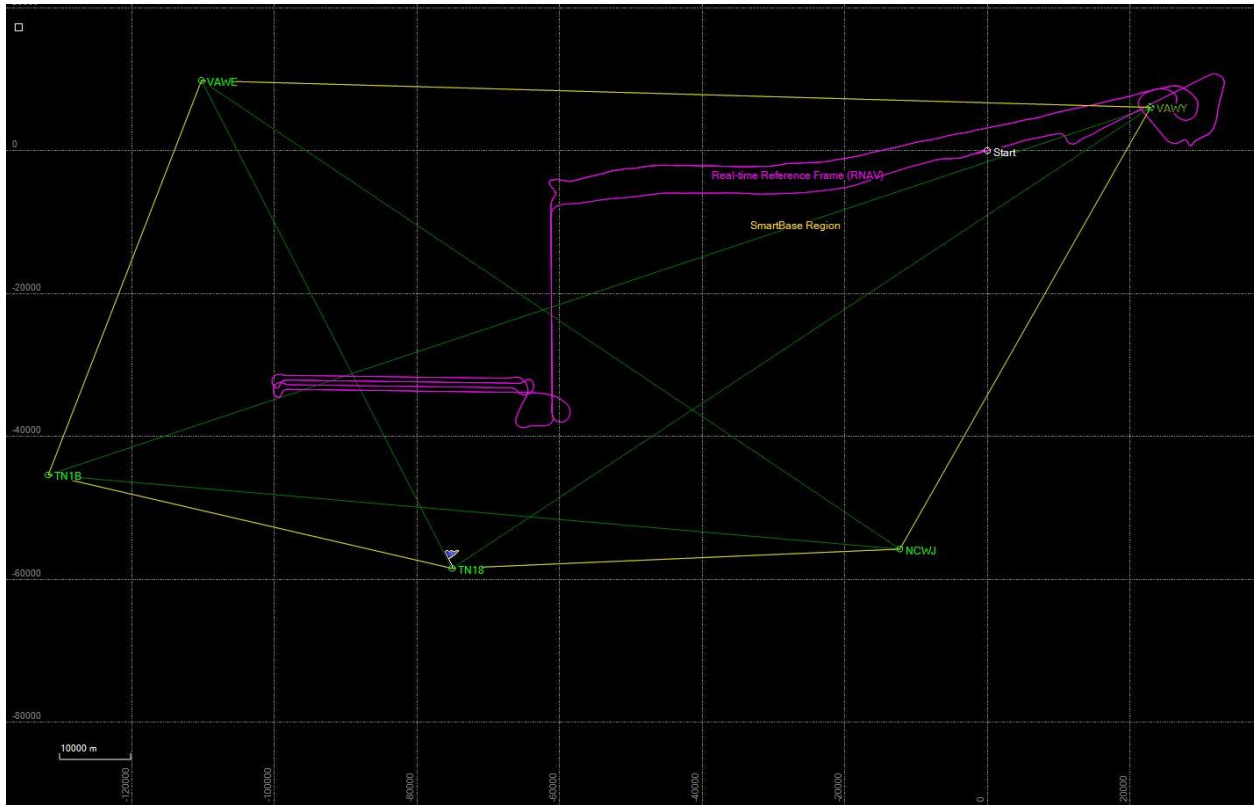
0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = CIA, 7 = GNSS Nav, 8 = DR



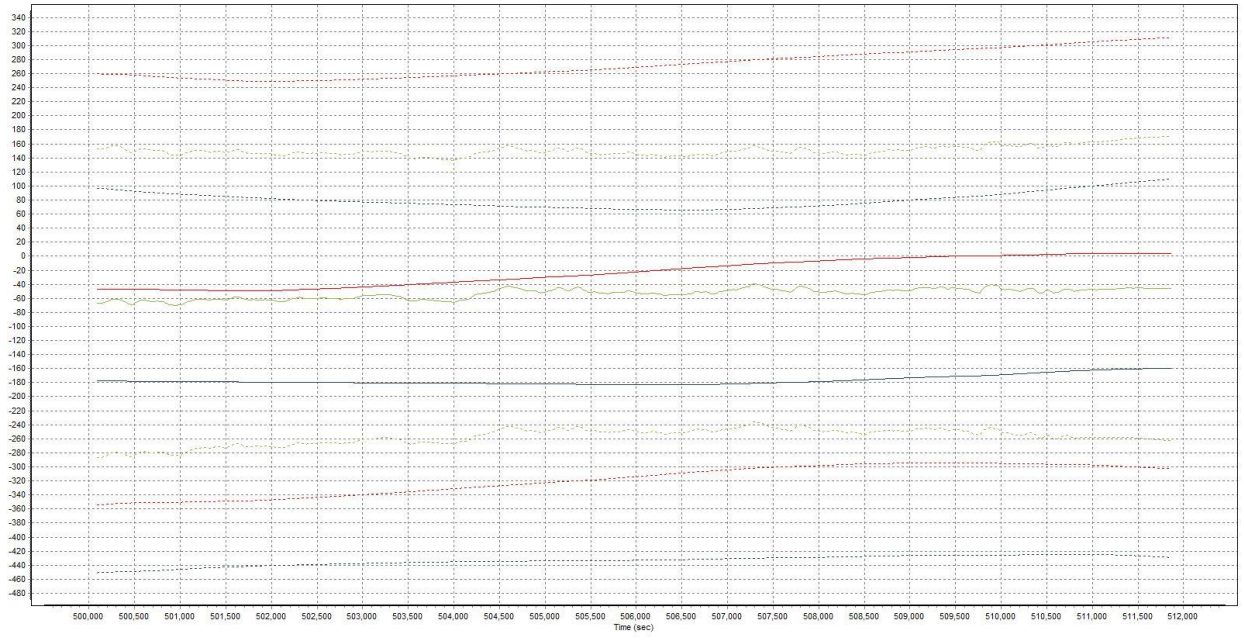
— North (m) — East (m) — Down (m) — DR mode



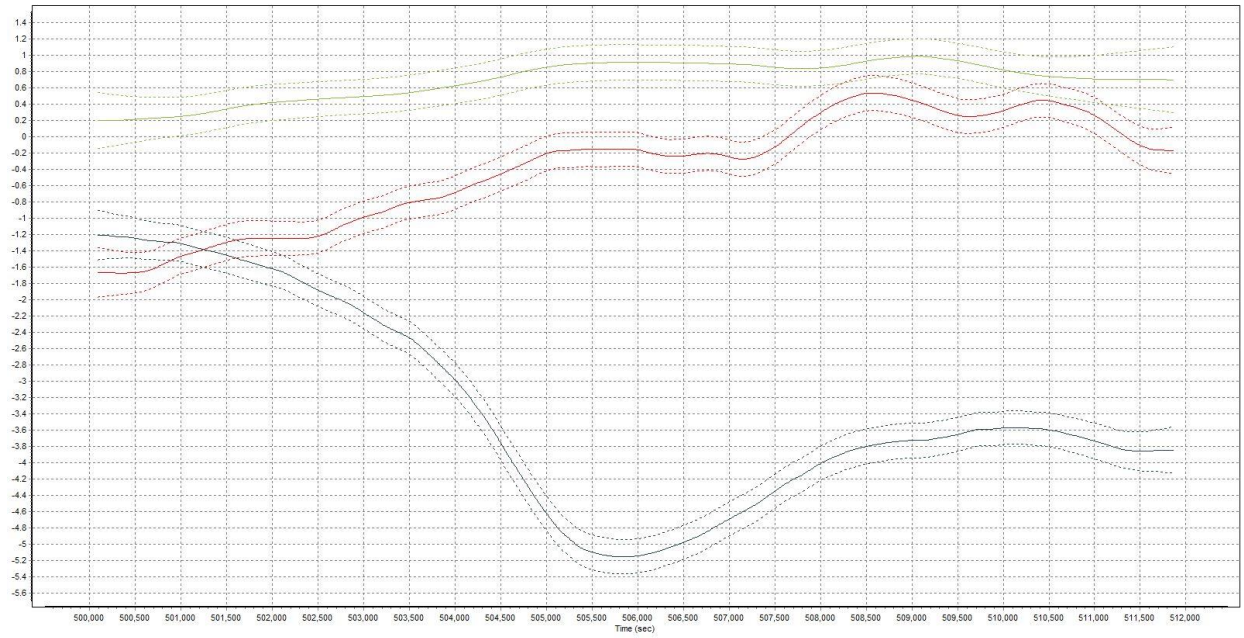
— North Position Error RMS (m) — East Position Error RMS (m) — Down Position Error RMS (m)



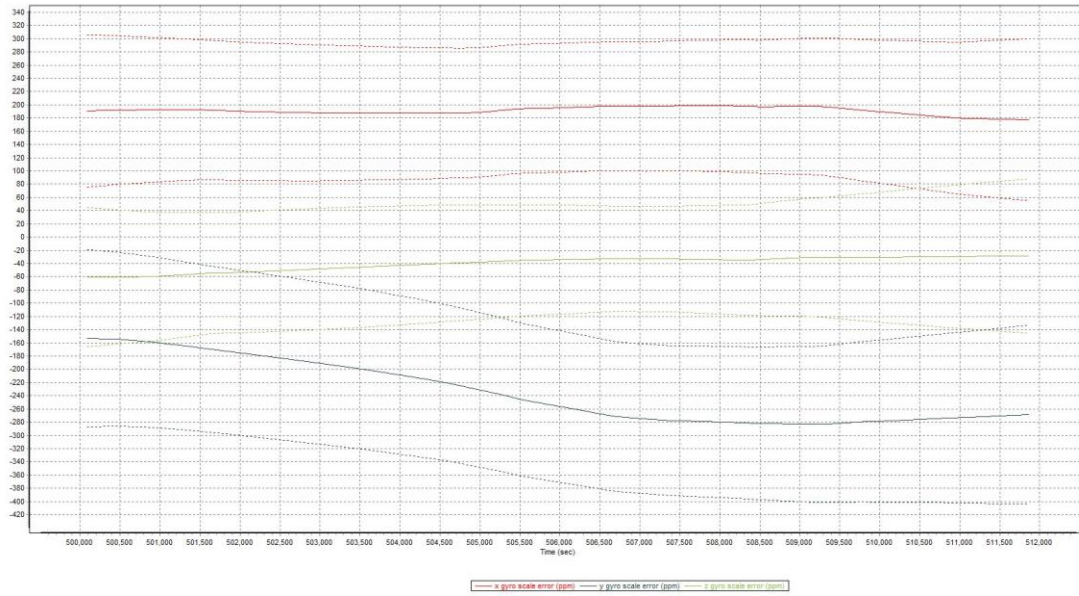
— x accelerometer bias (micro-g) — y accelerometer bias (micro-g) — z accelerometer bias (micro-g)



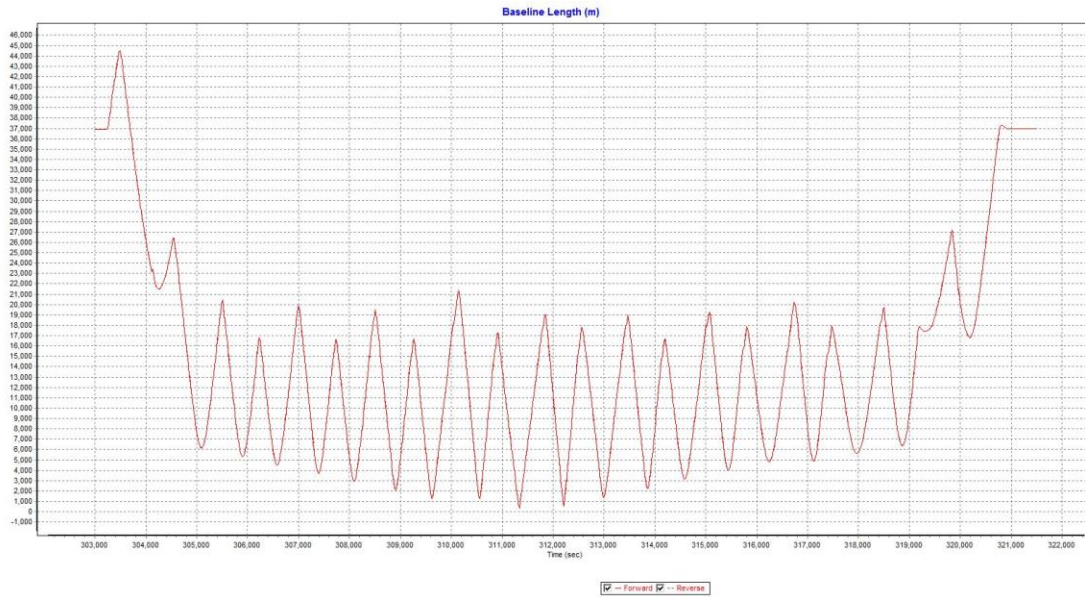
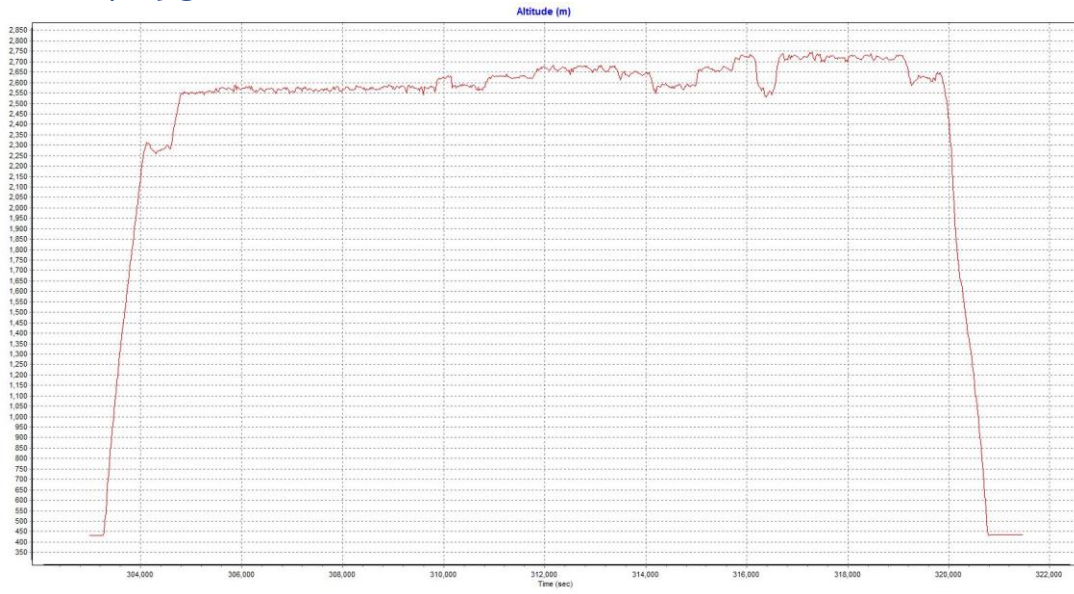
— x accelerometer scale error (ppm) — y accelerometer scale error (ppm) — z accelerometer scale error (ppm)



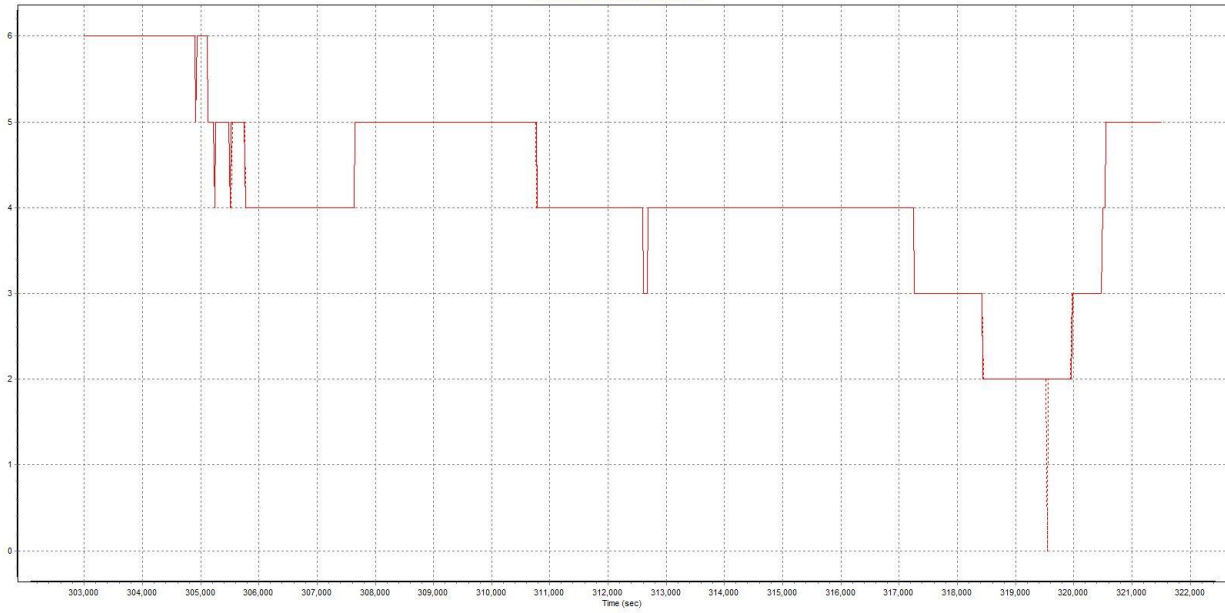
— x gyro bias (deg/hr) — y gyro bias (deg/hr) — z gyro bias (deg/hr)



# CAU17095A

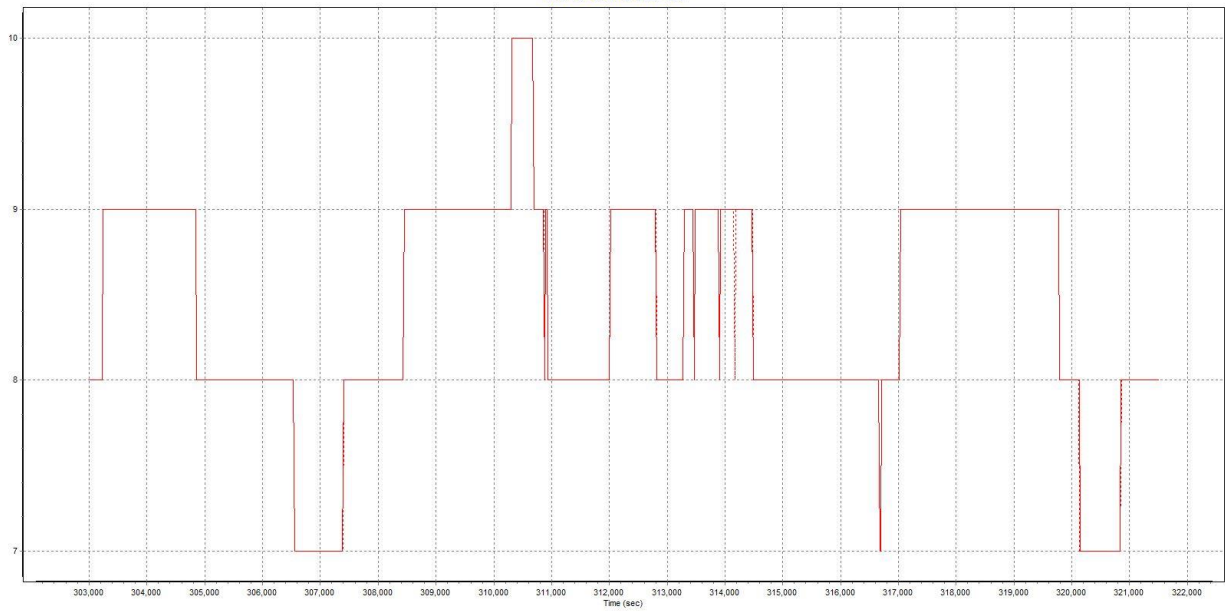


Number of GLONASS Satellites



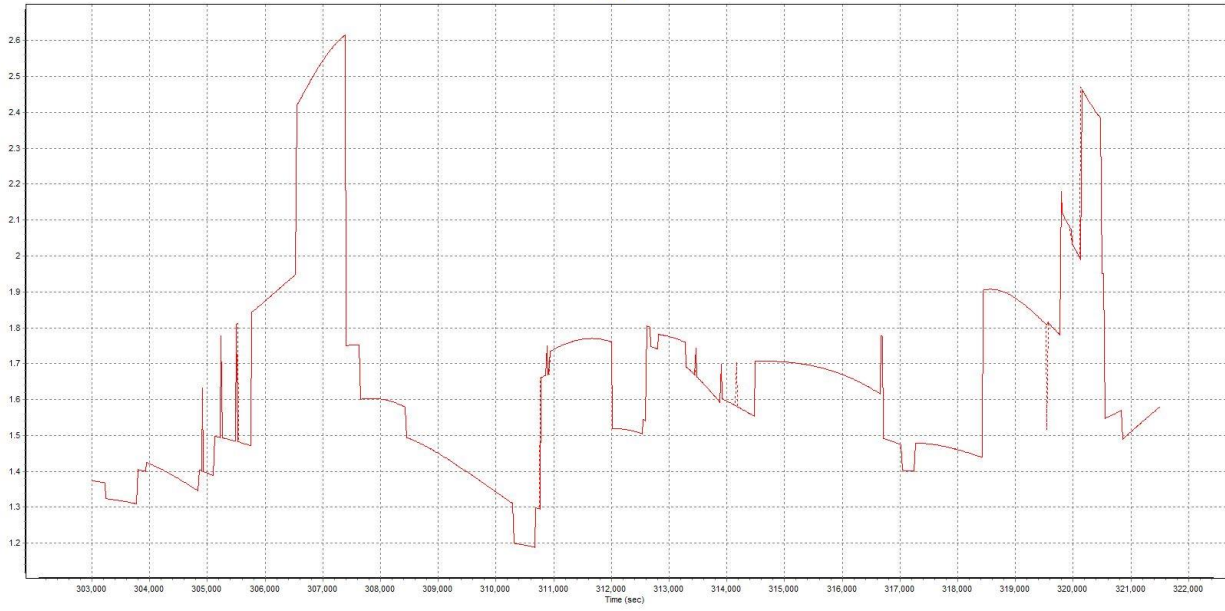
Forward  Reverse

Number of GPS Satellites



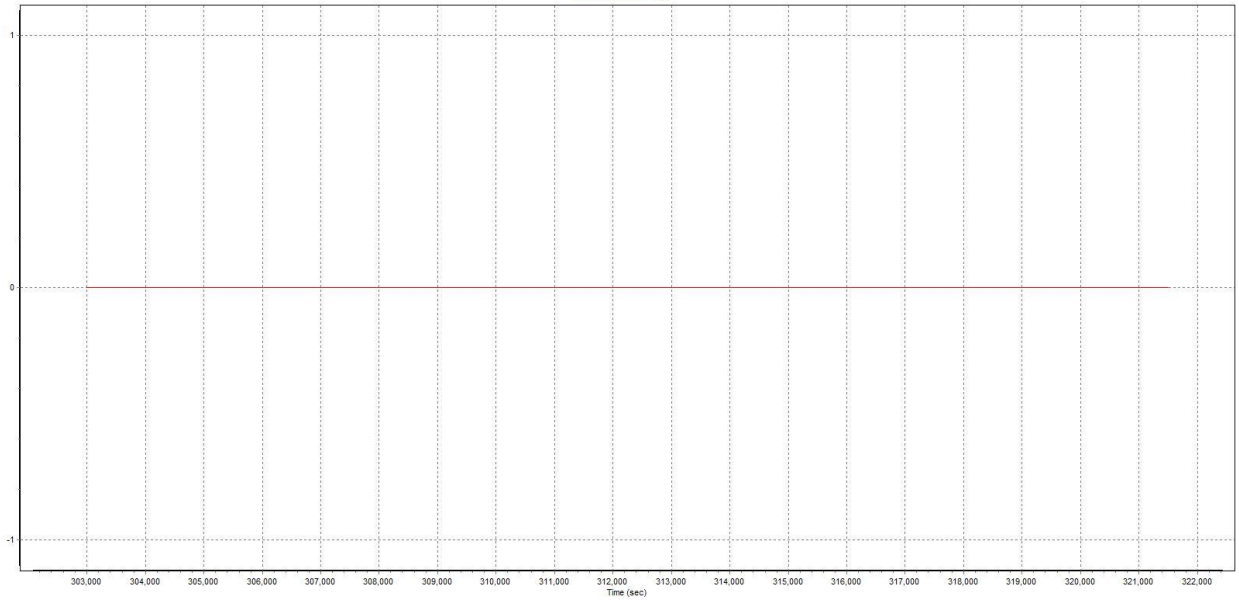
Forward  Reverse

PDOP



Forward  Reverse

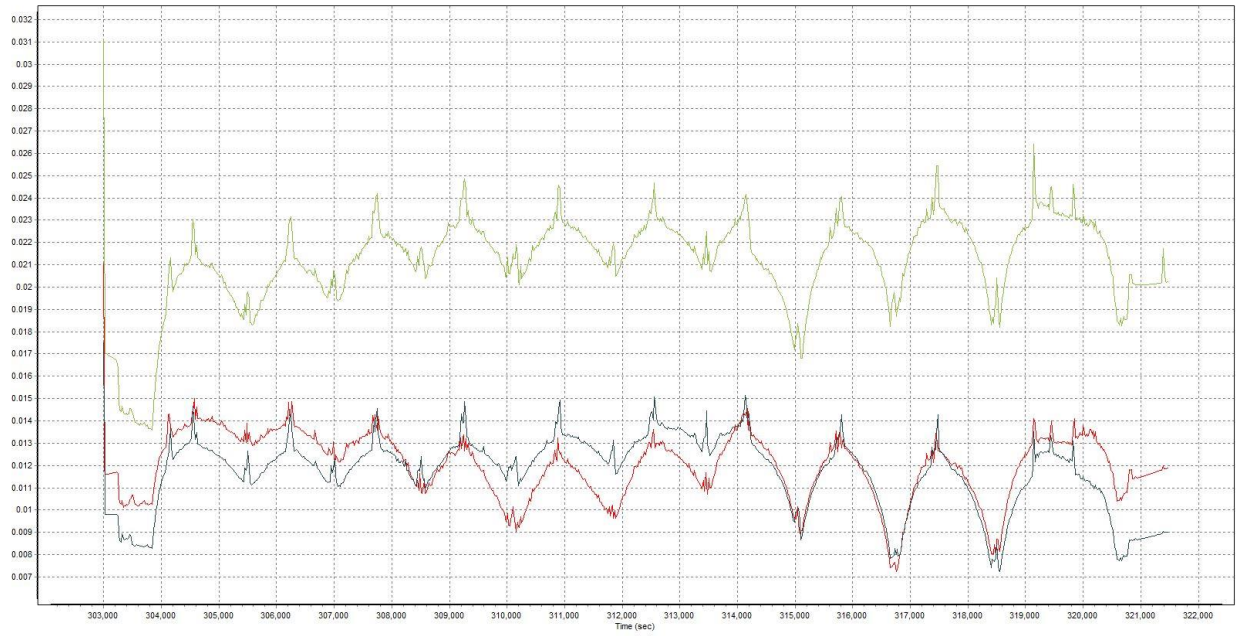
Processing mode



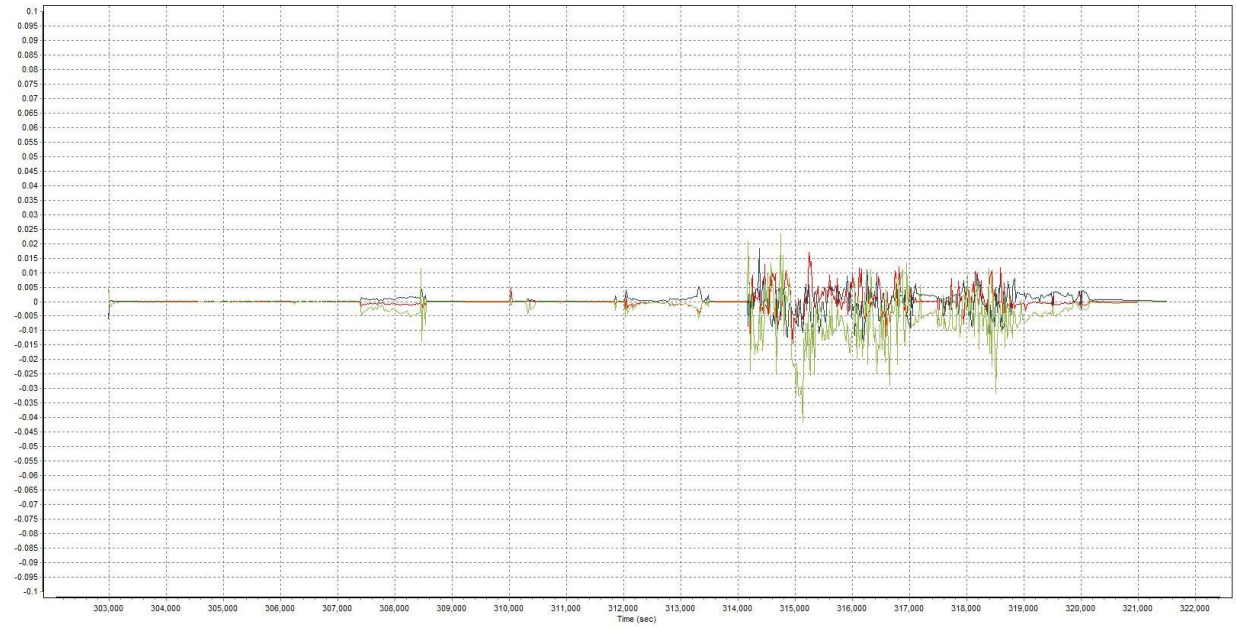
Forward  Reverse

0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNS, 4 = RTCM, 5 = IAPPP, 6 = CIA, 7 = GNSS Nav, 8 = DR

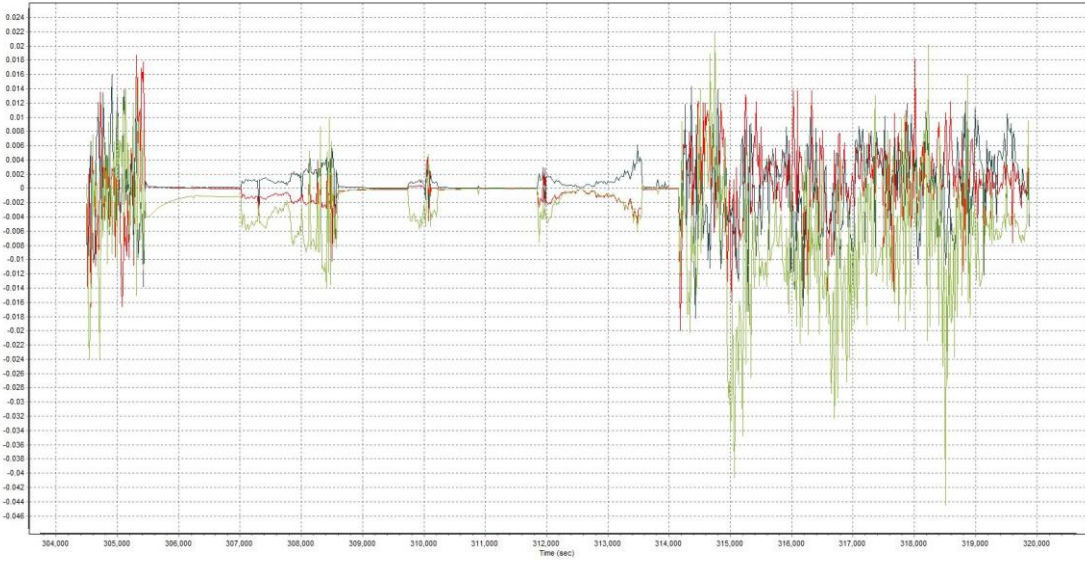




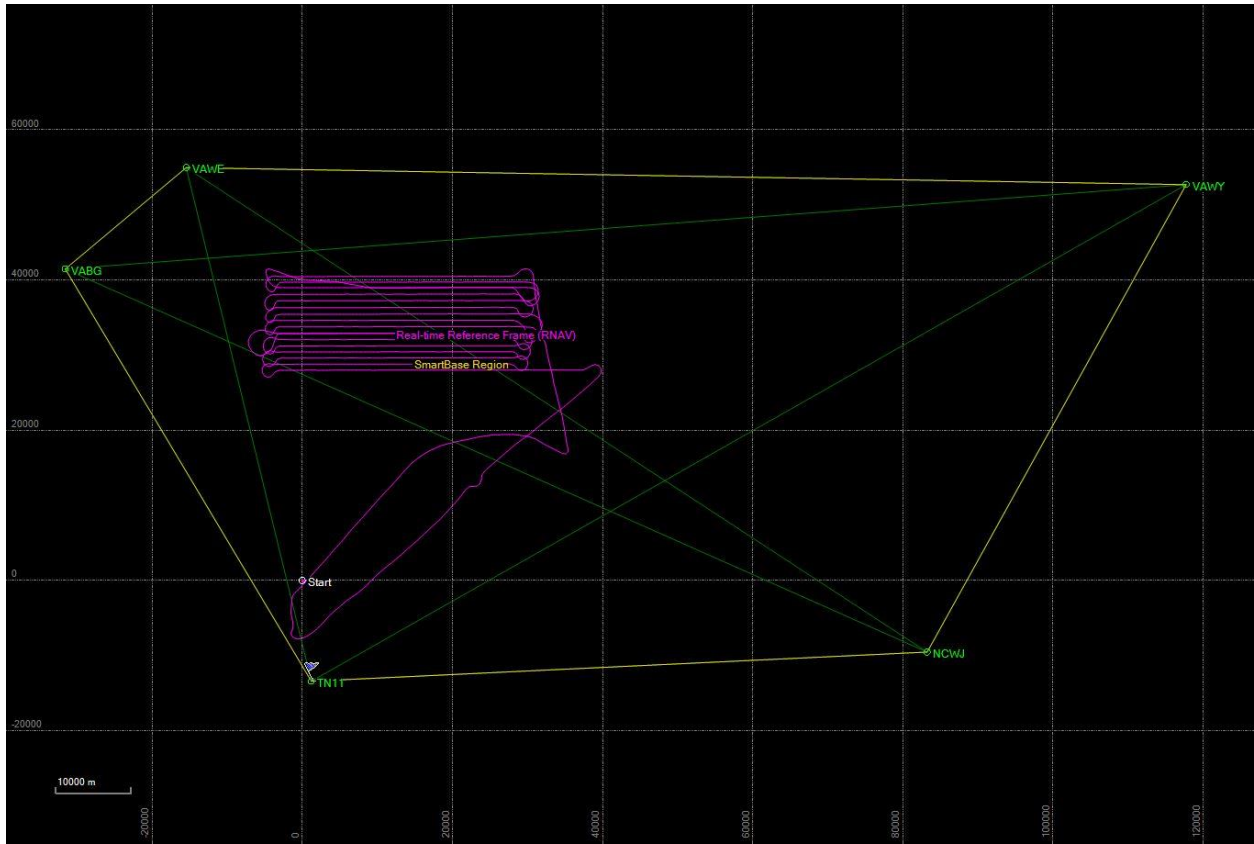
— North Position Error RMS (m) — East Position Error RMS (m) — Down Position Error RMS (m)

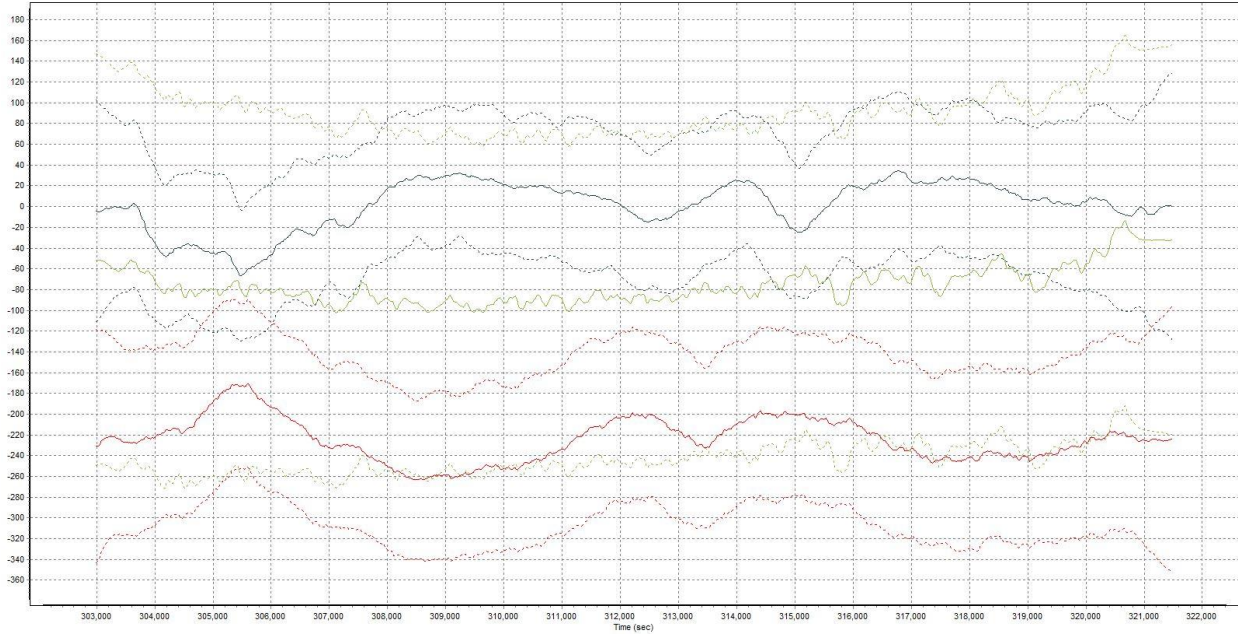


— North (m) — East (m) — Down (m) — DR node

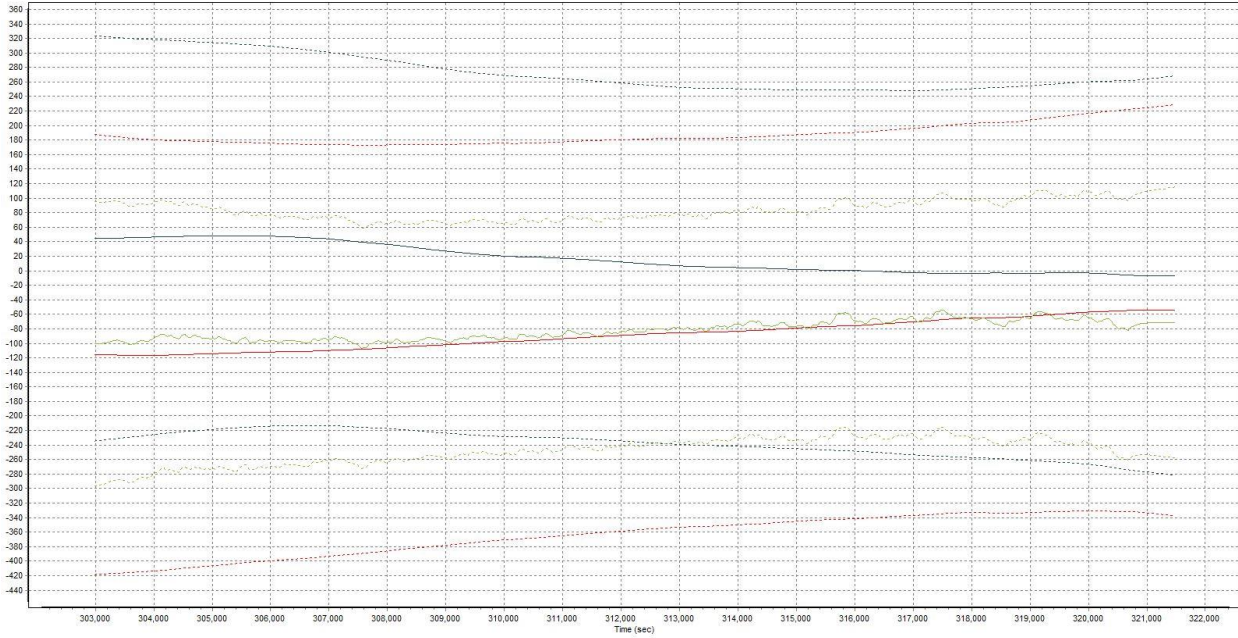


North (m) East (m) Down (m) DR mode

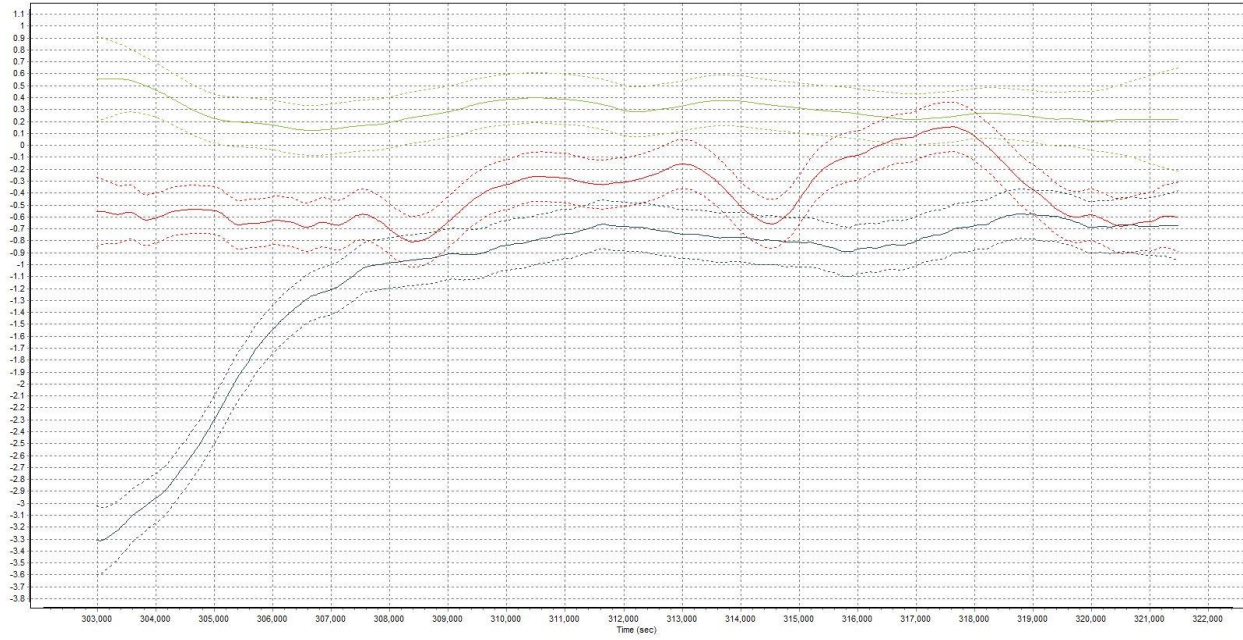




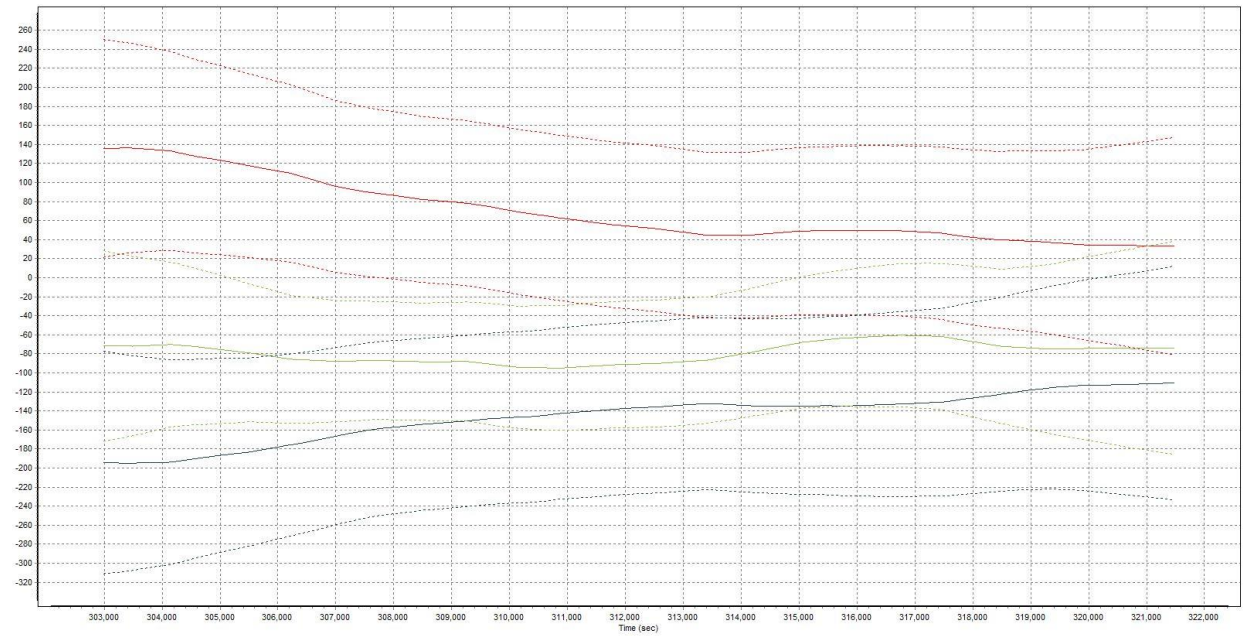
x accelerometer bias (micro-g) y accelerometer bias (micro-g) z accelerometer bias (micro-g)



x accelerometer scale error (ppm) y accelerometer scale error (ppm) z accelerometer scale error (ppm)

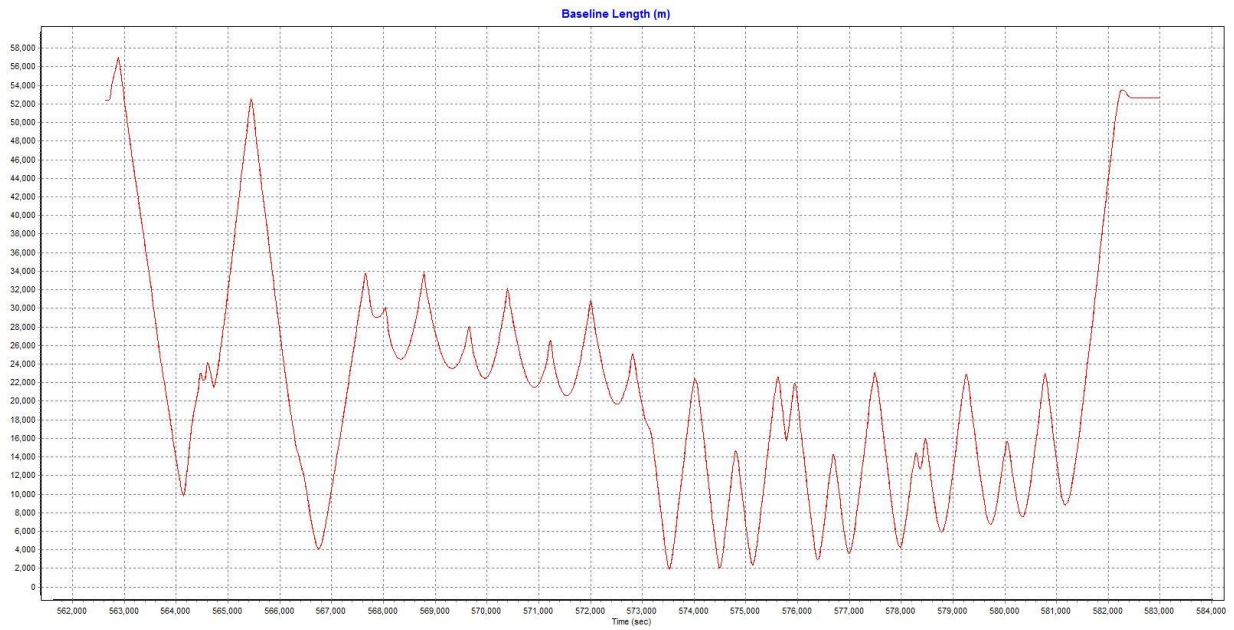


x gyro bias (deg/hr) y gyro bias (deg/hr) z gyro bias (deg/hr)

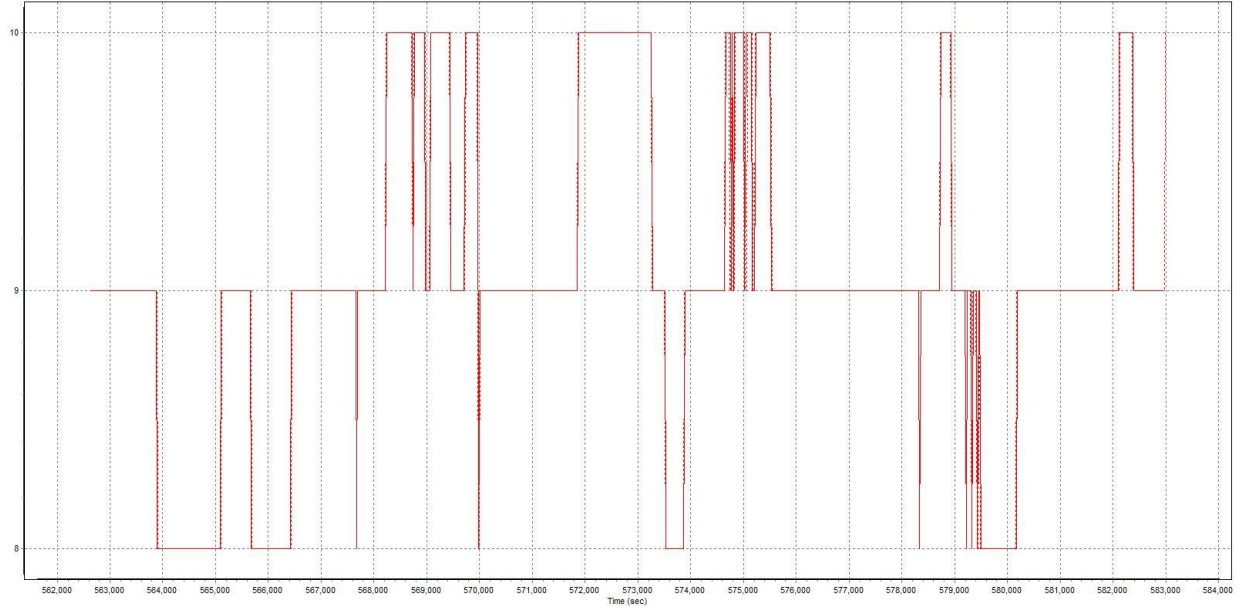


x gyro scale error (ppm) y gyro scale error (ppm) z gyro scale error (ppm)

# CAU17098A

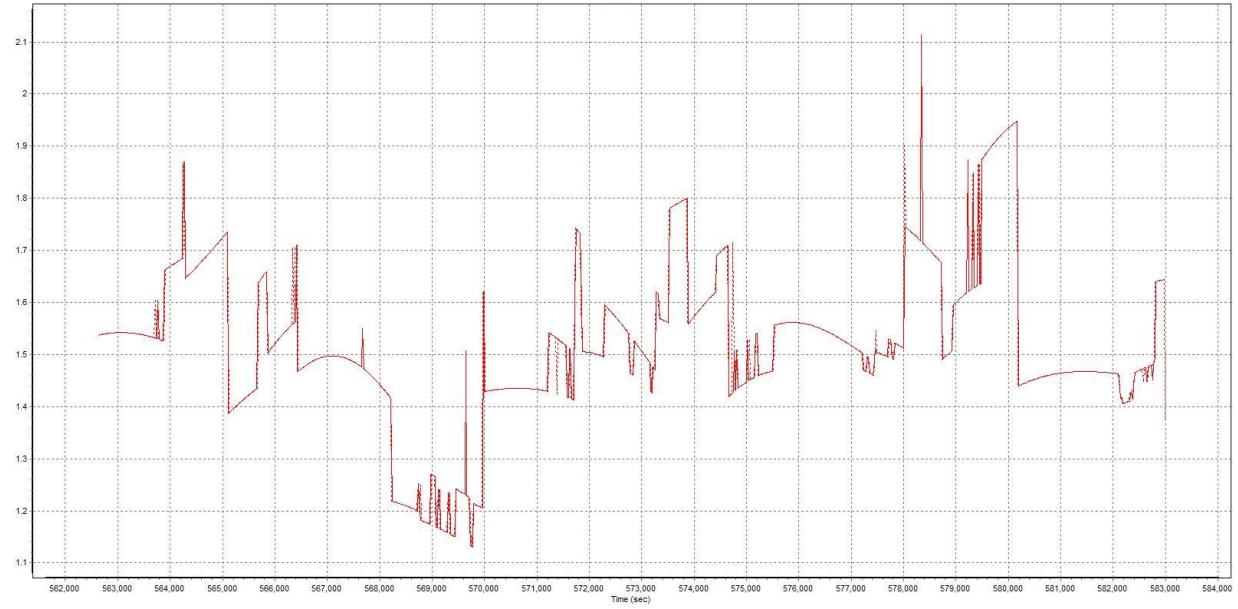


Number of GPS Satellites



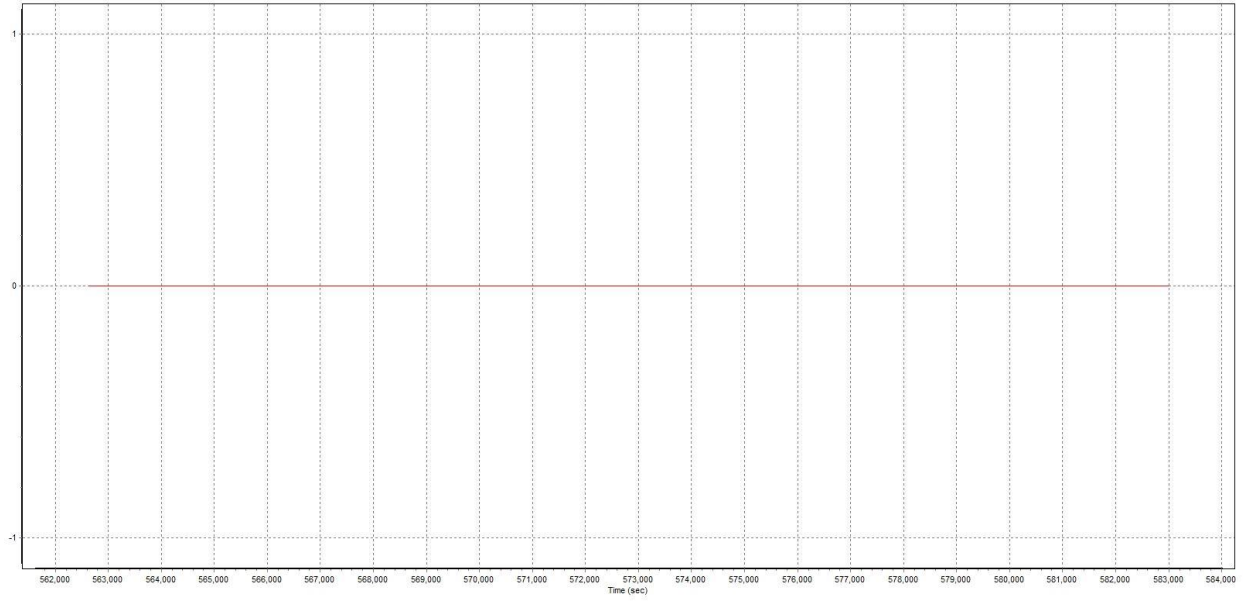
Forward  Reverse

PDOP



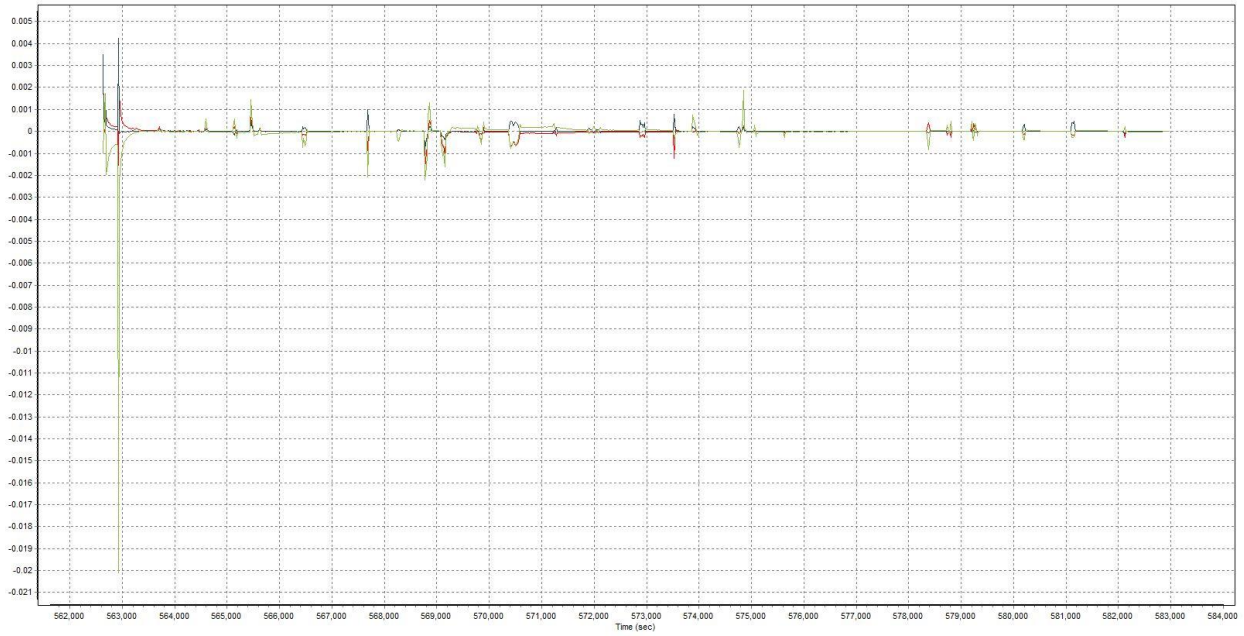
Forward  Reverse

Processing mode

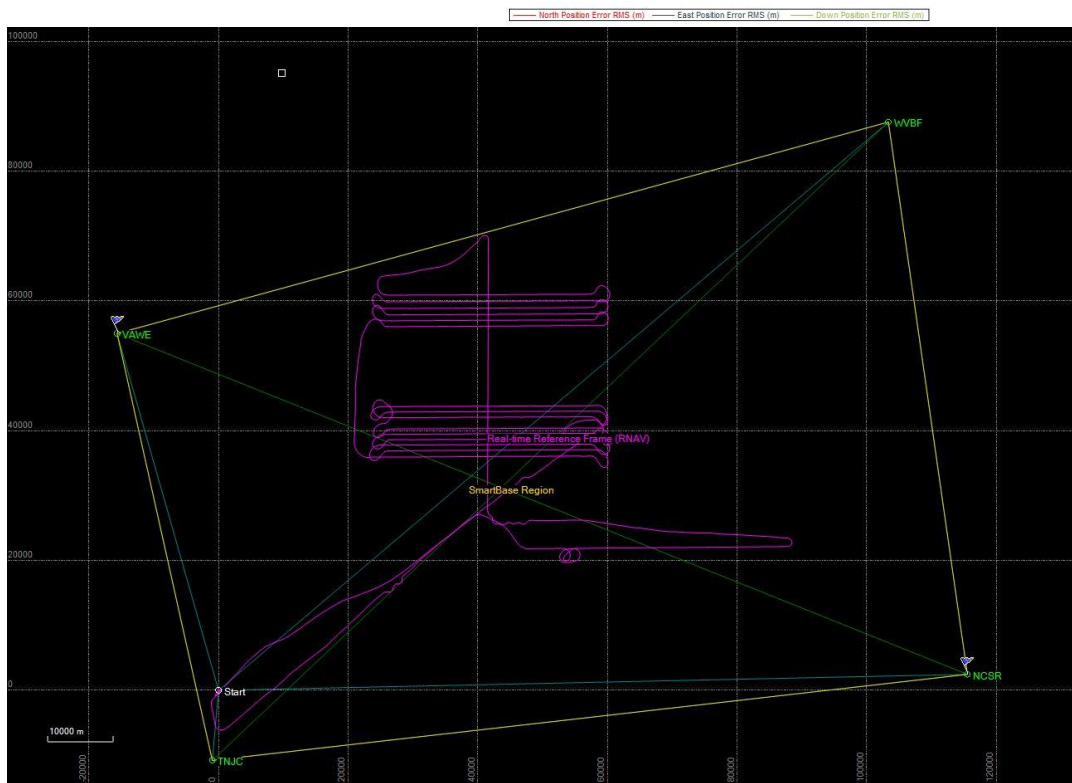
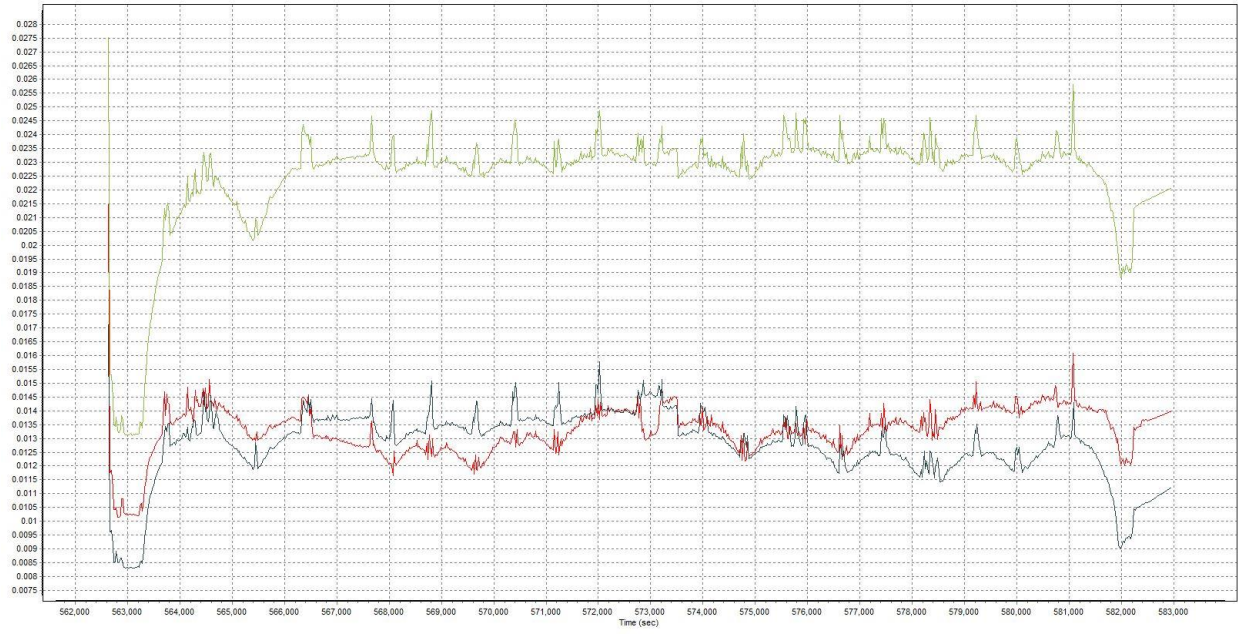


Forward  Reverse

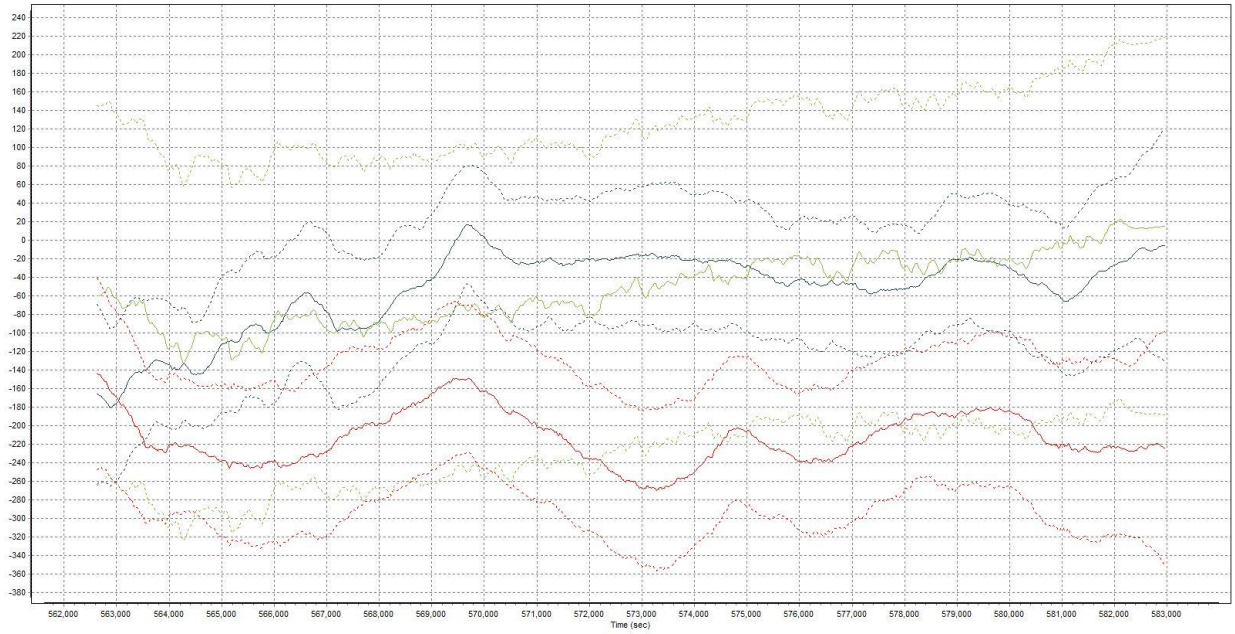
0 = Fixed NL, 1 = Fixed Wt, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = CIA, 7 = GNSS Nav, 8 = DR



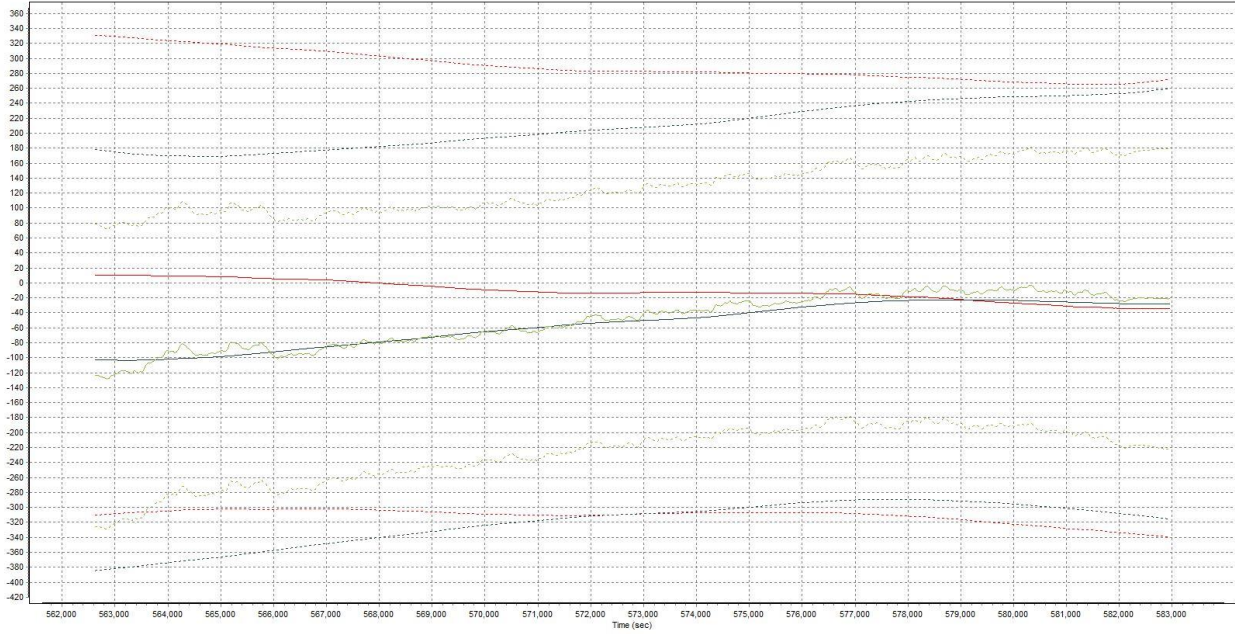
— North (m) — East (m) — Down (m) → DR mode



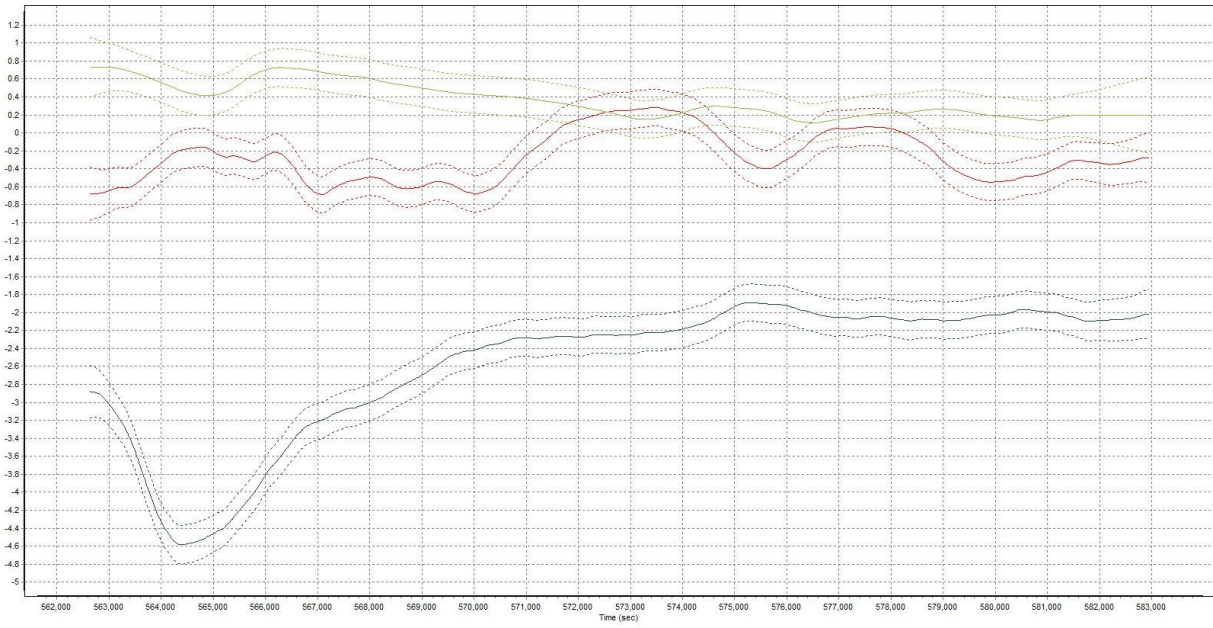




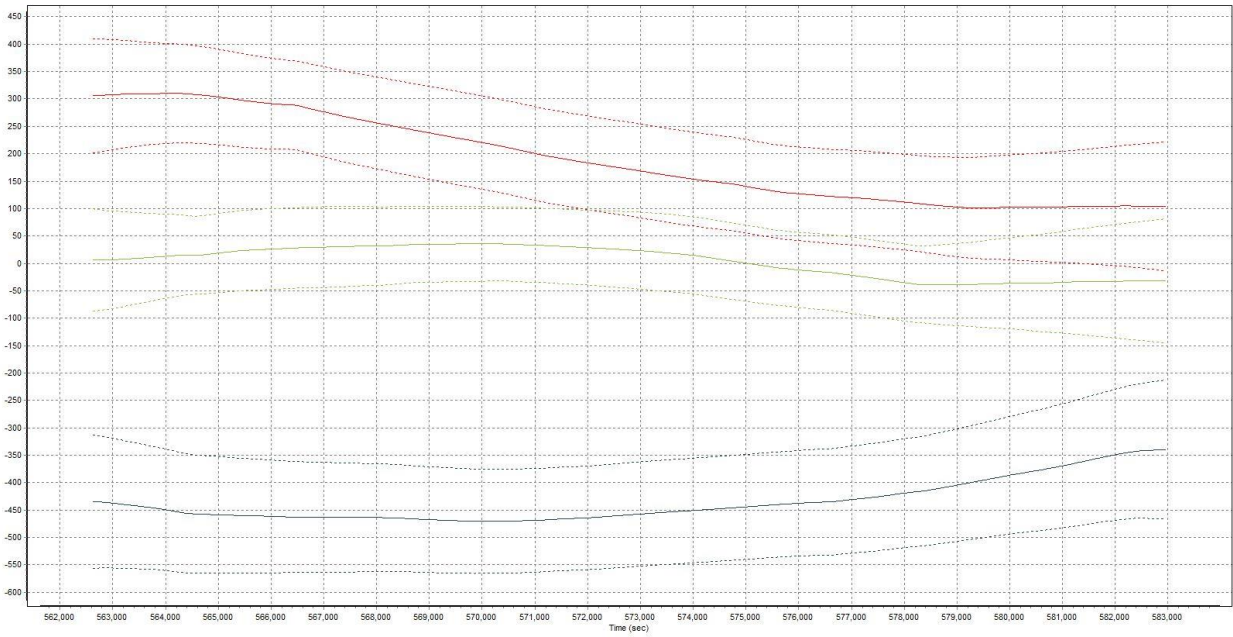
x accelerometer bias (micro-g) y accelerometer bias (micro-g) z accelerometer bias (micro-g)



x accelerometer scale error (ppm) y accelerometer scale error (ppm) z accelerometer scale error (ppm)



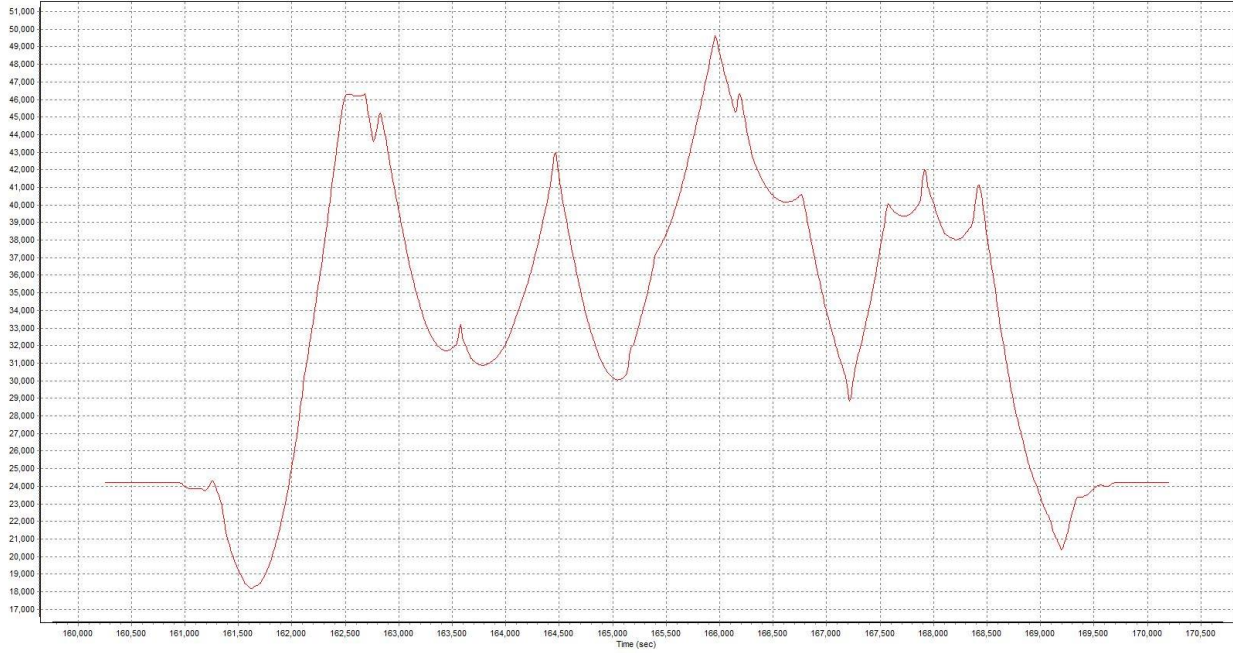
x gyro bias (deg/hr) y gyro bias (deg/hr) z gyro bias (deg/hr)



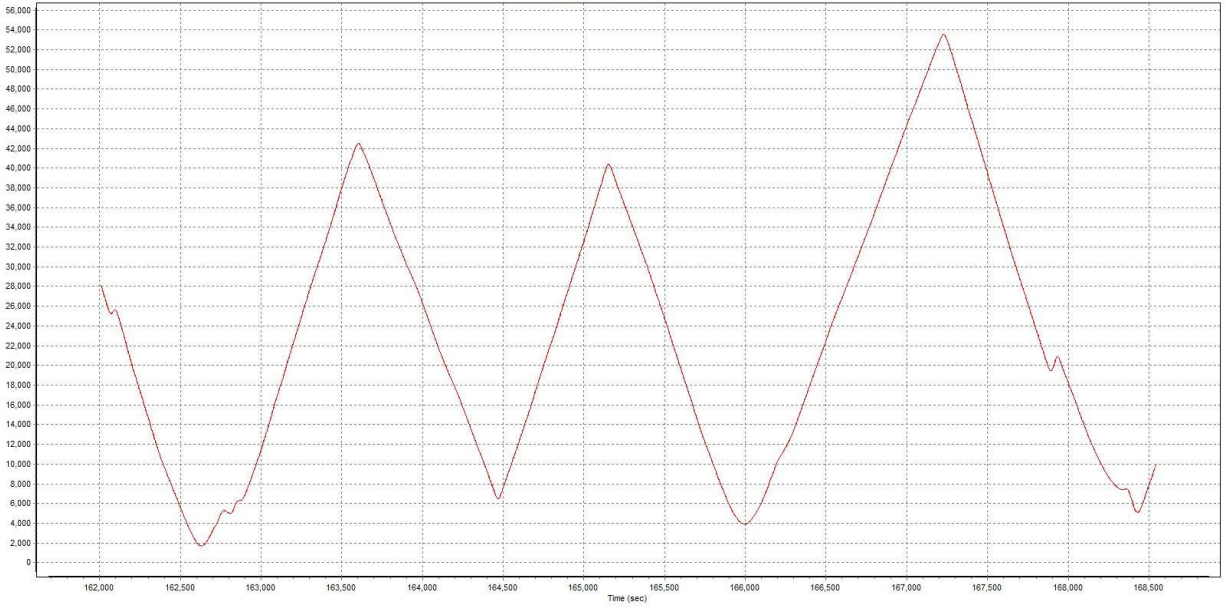
x gyro scale error (ppm) y gyro scale error (ppm) z gyro scale error (ppm)

**CAU17100B**

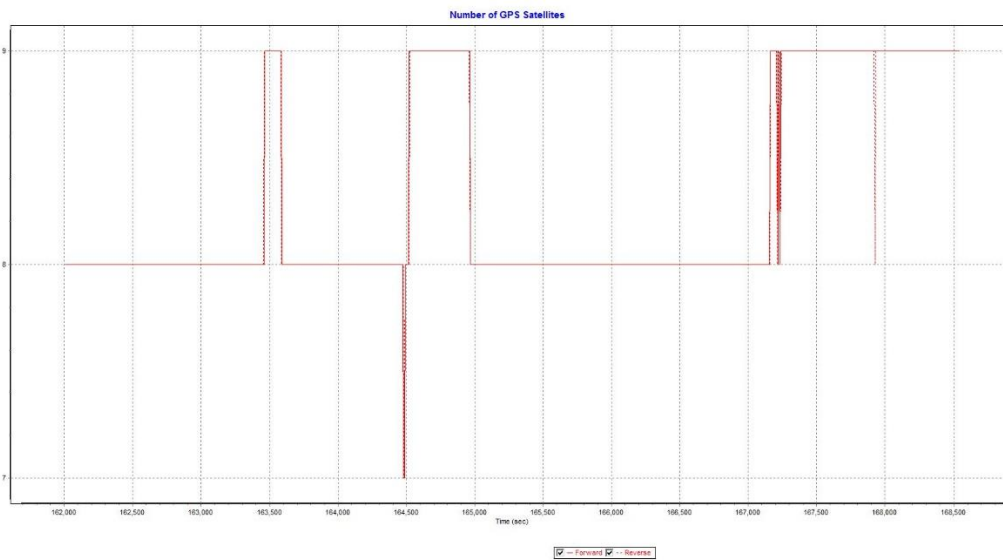
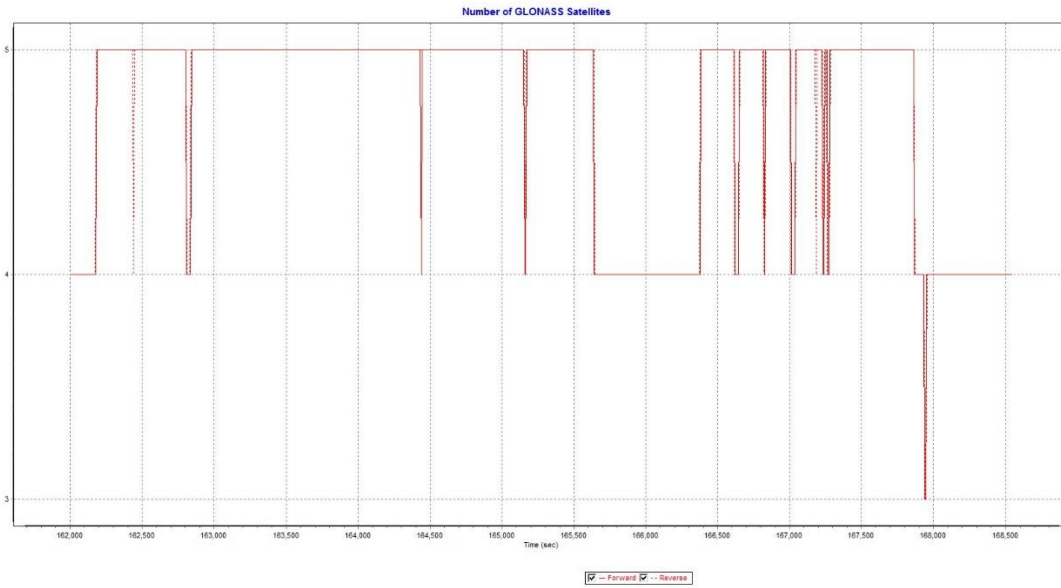
3D Distance to Closest GPS Station (m)



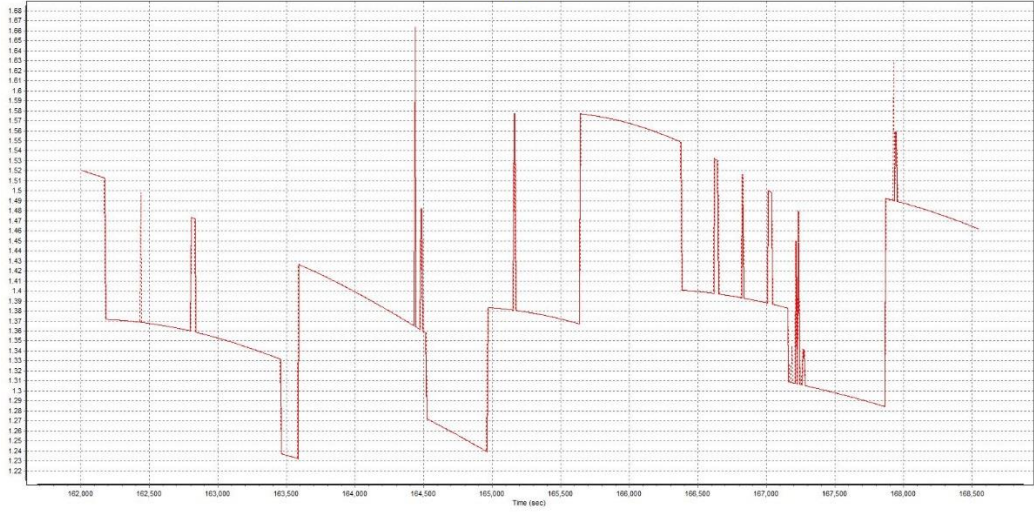
Baseline Length (m)



Forward  Reverse

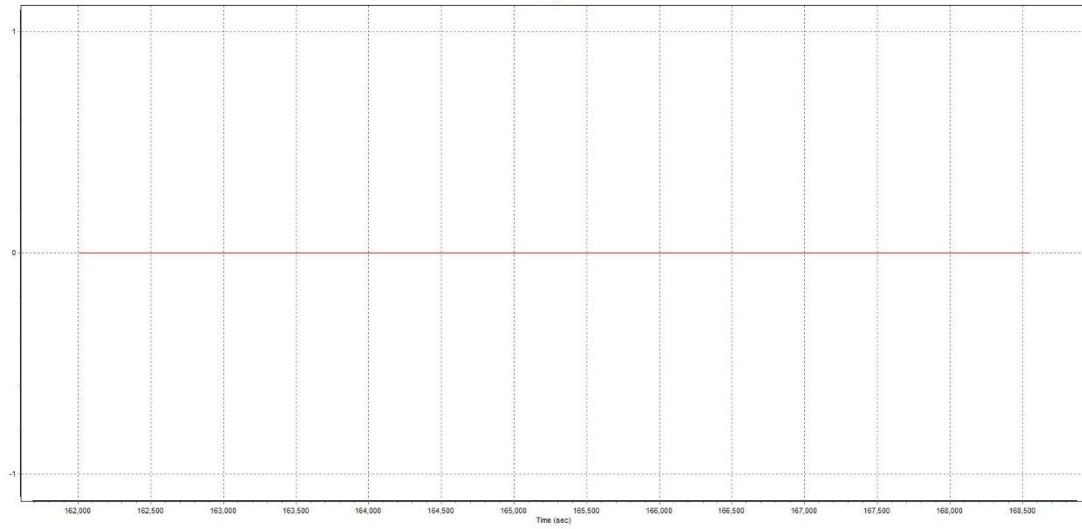


PDOP



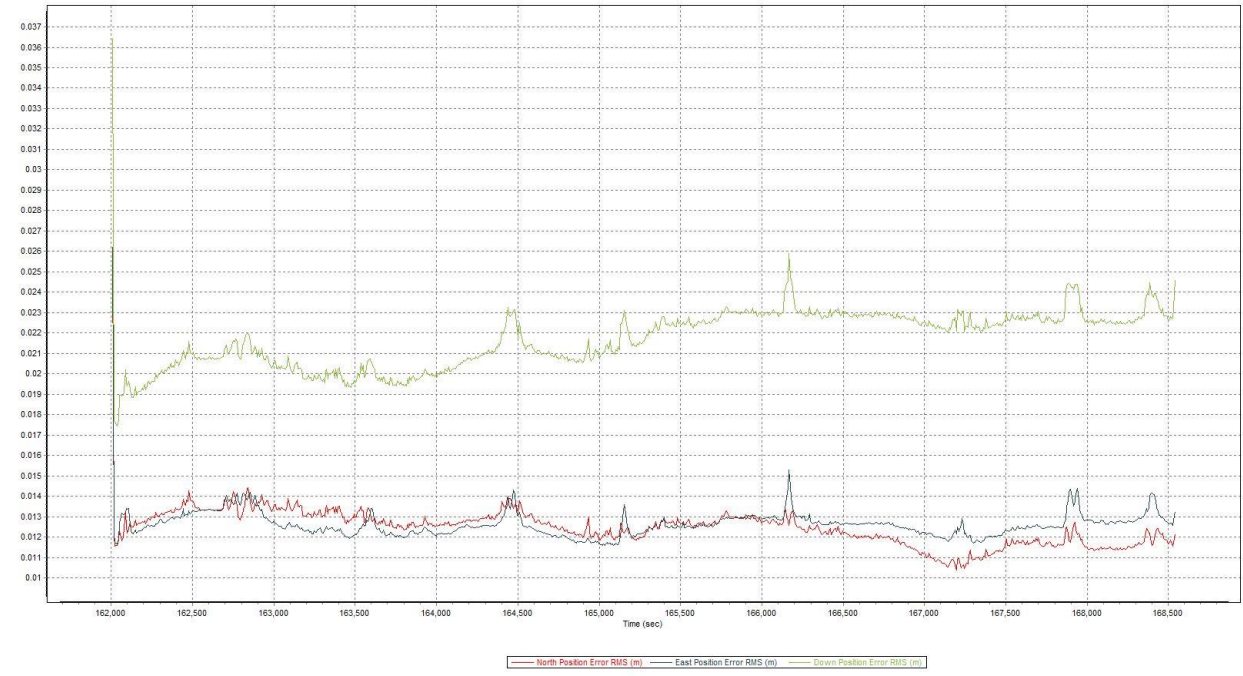
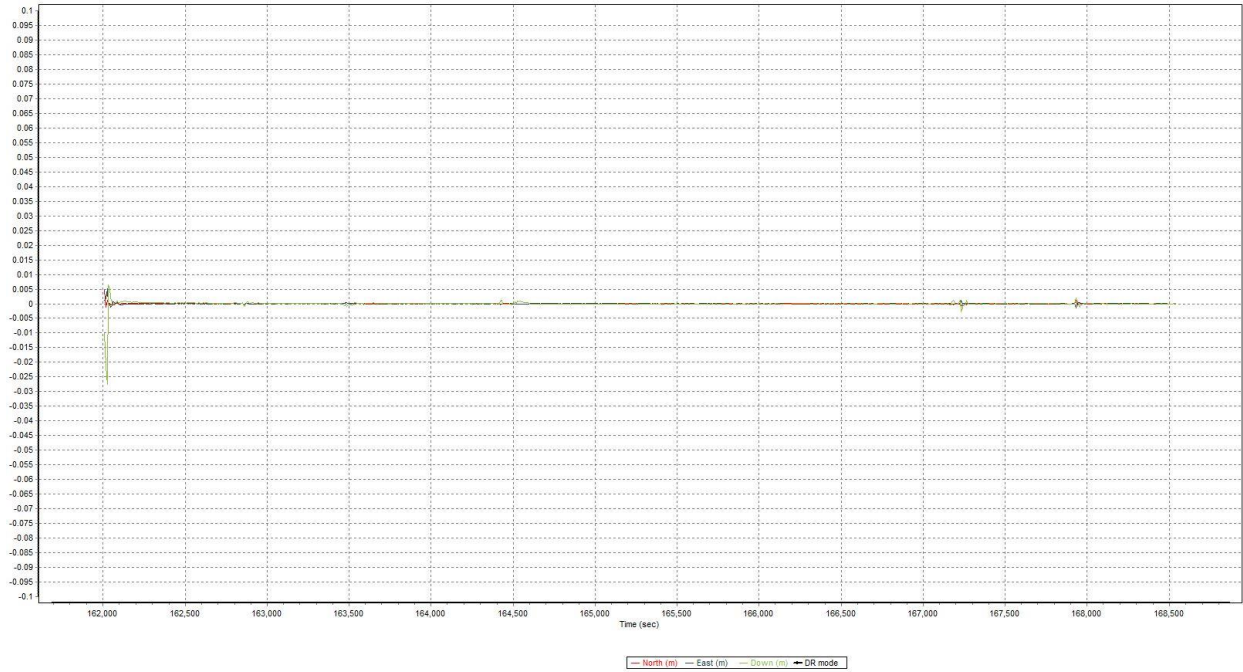
Forward  Reverse

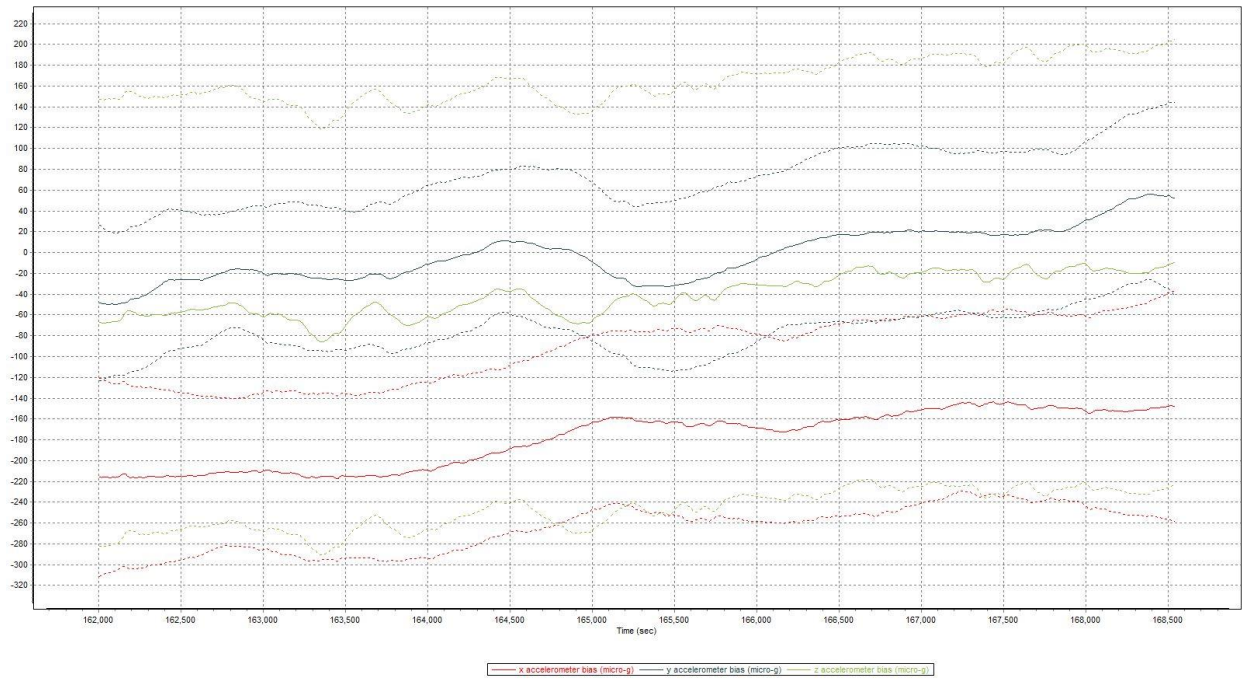
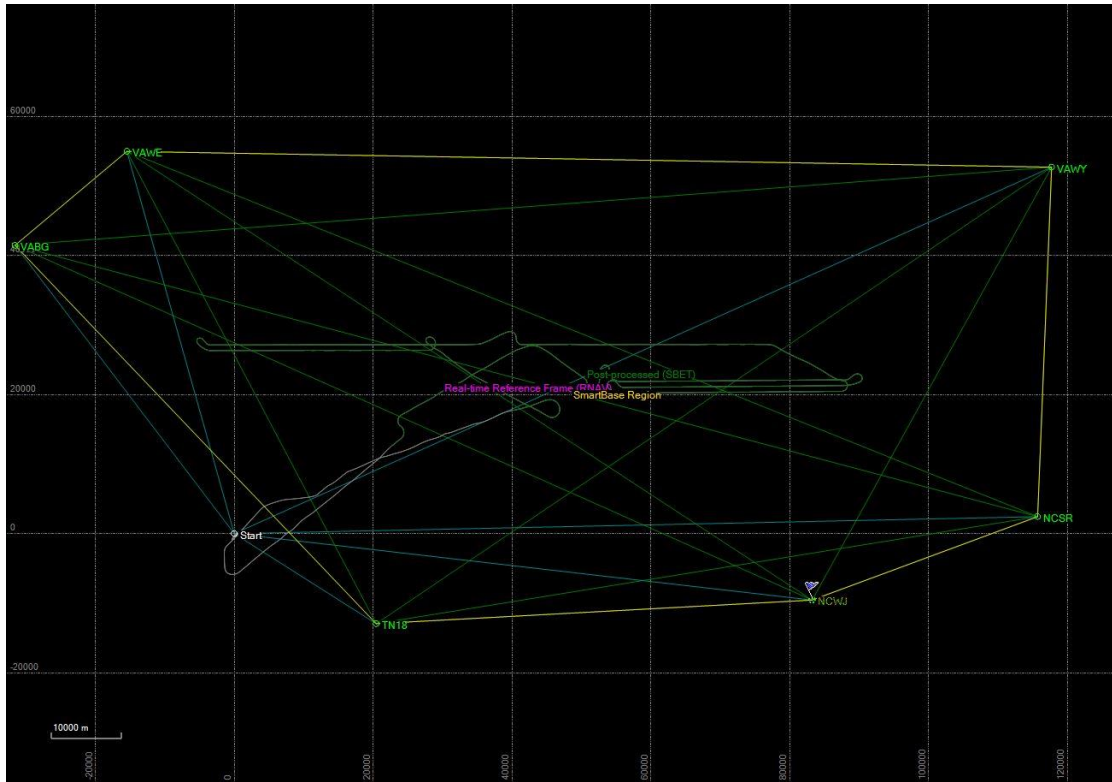
Processing mode

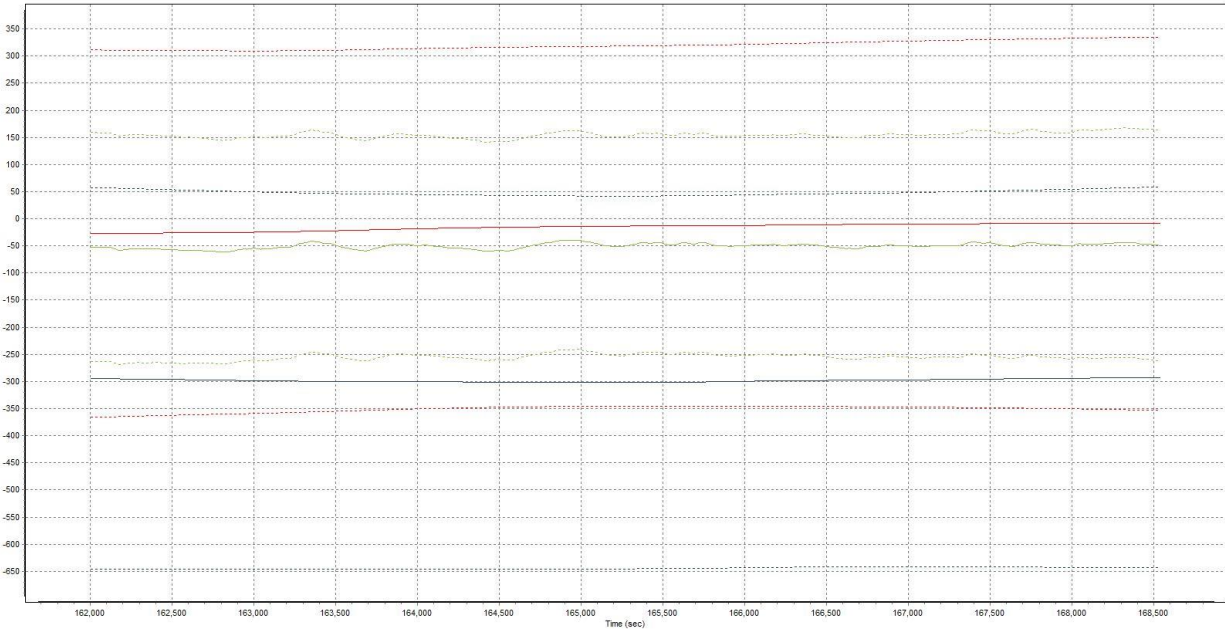


Forward  Reverse

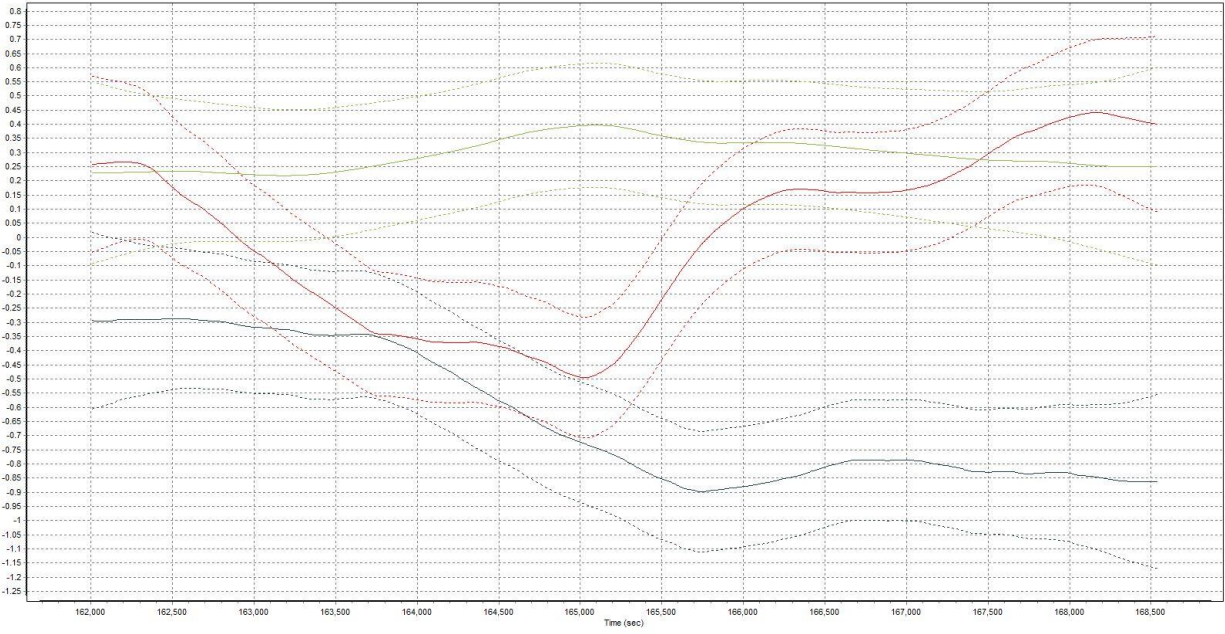
0 = Fixed NL, 1 = Fixed VL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = iAPPP, 6 = CIA, 7 = GNSS Nav, 8 = DR





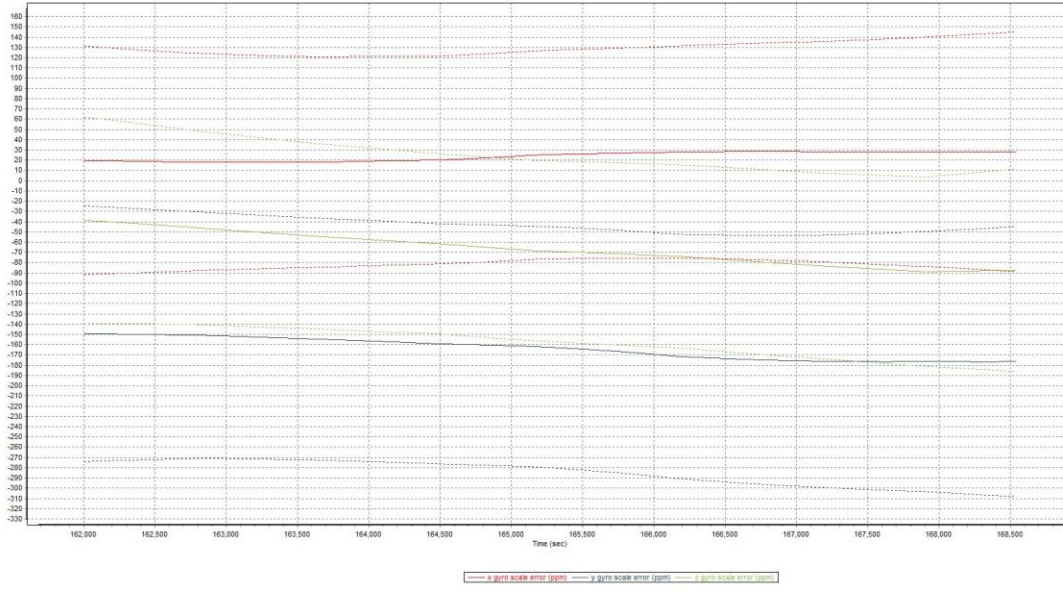


— x accelerometer scale error (ppm) — y accelerometer scale error (ppm) — z accelerometer scale error (ppm)

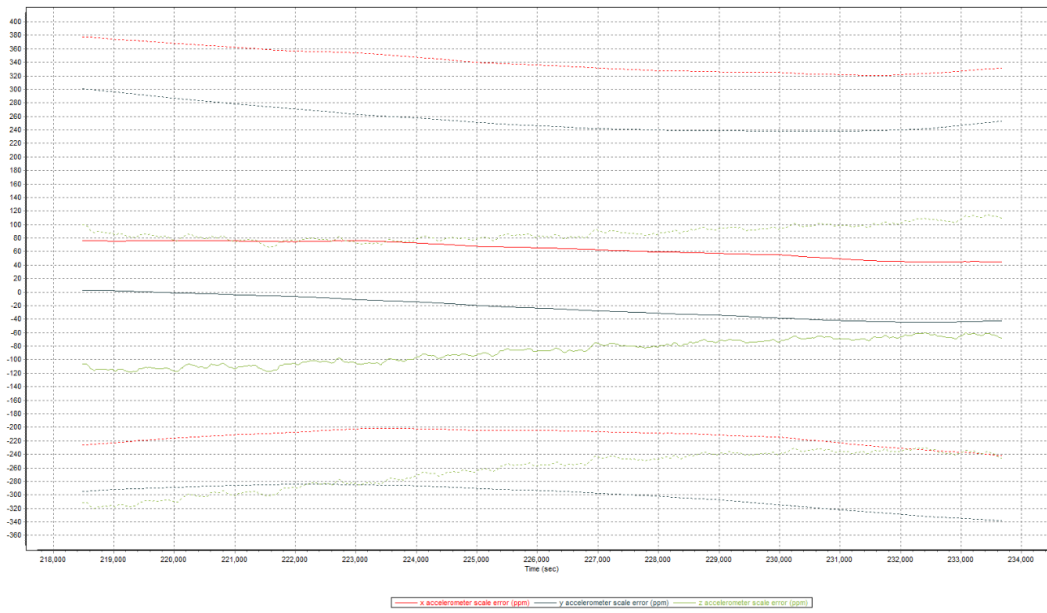
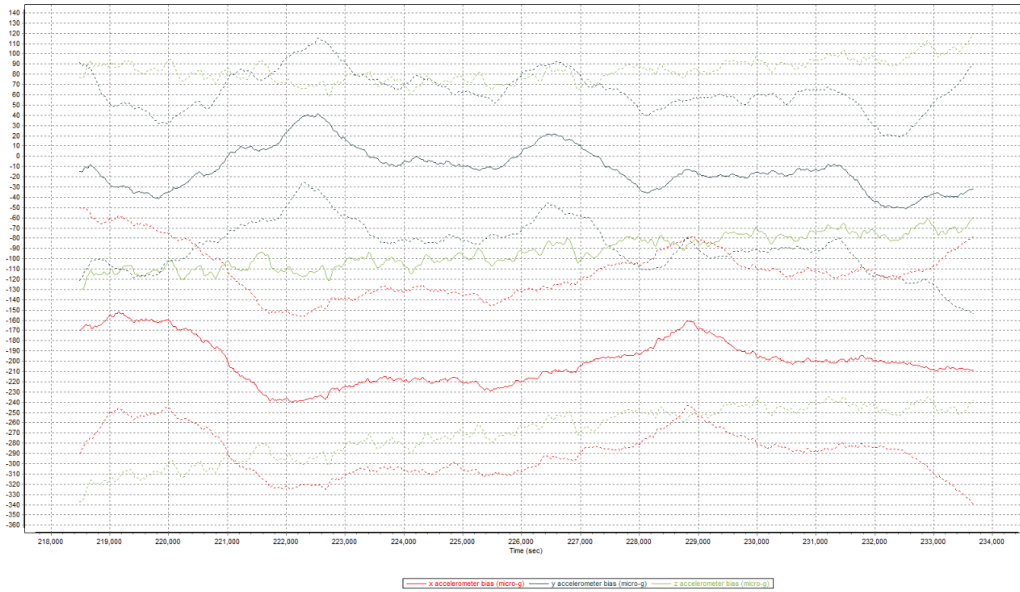


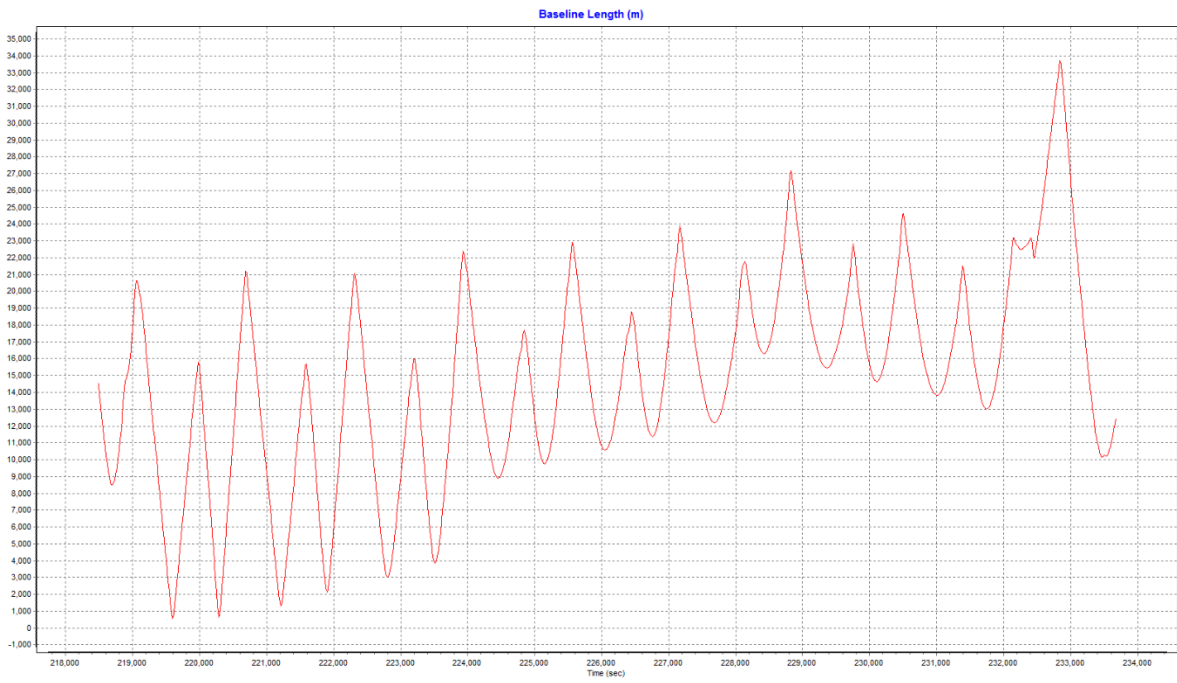
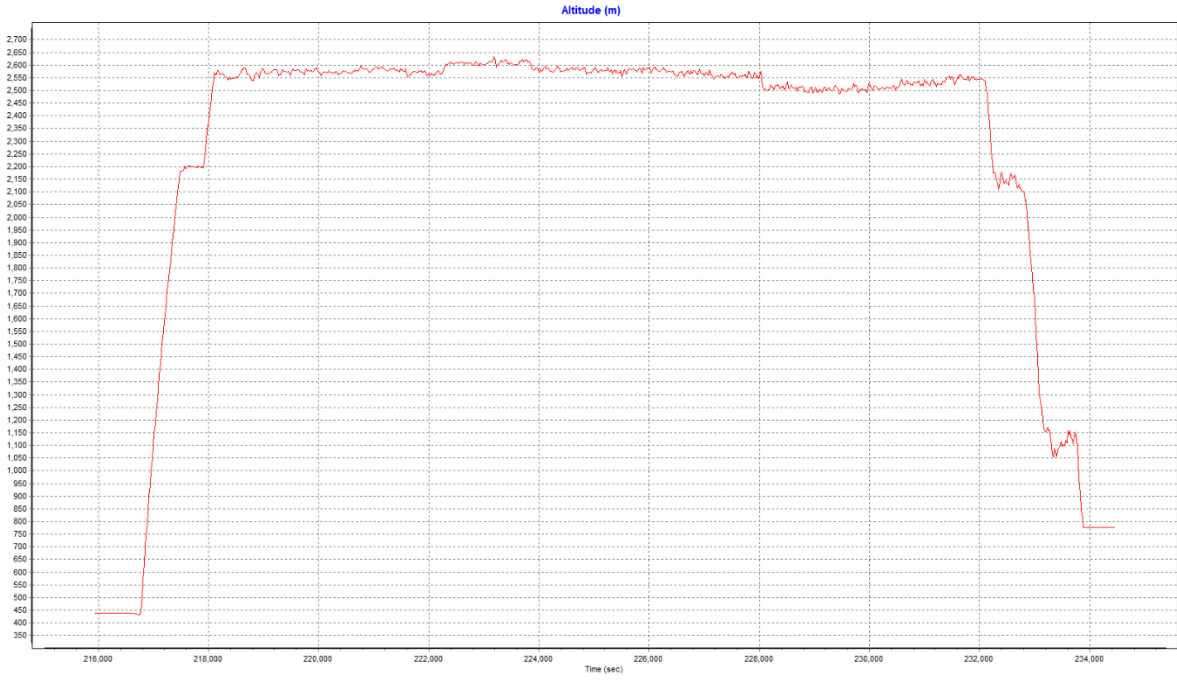
— x gyro bias (deg/hr) — y gyro bias (deg/hr) — z gyro bias (deg/hr)

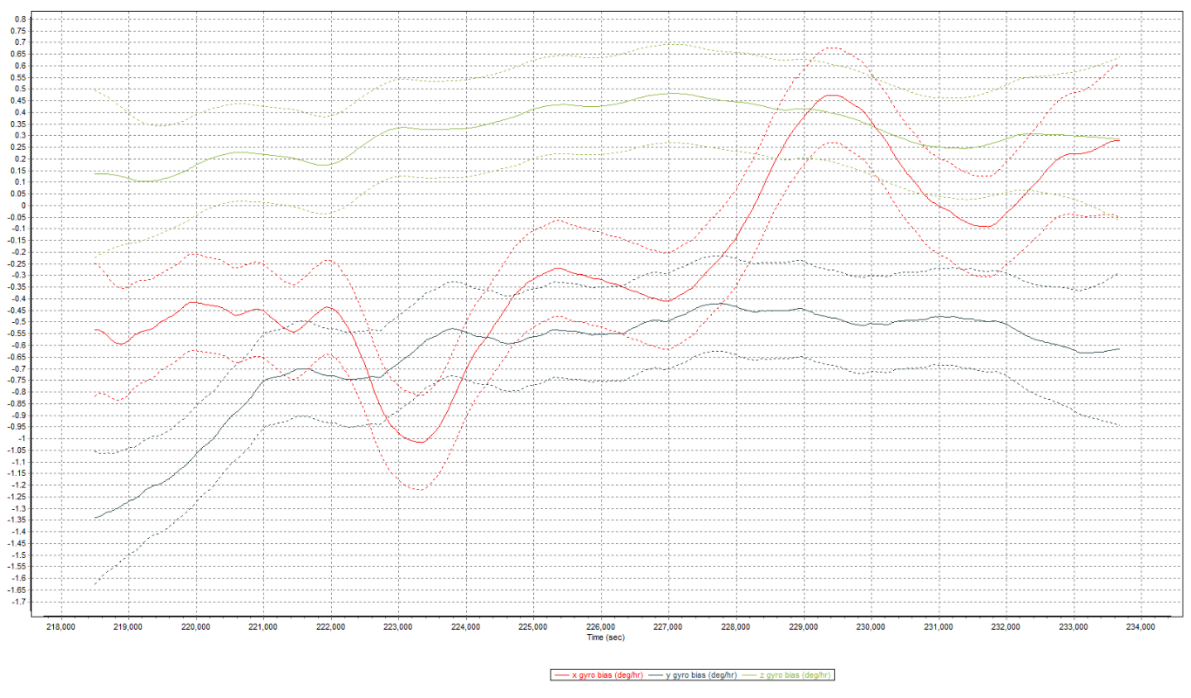
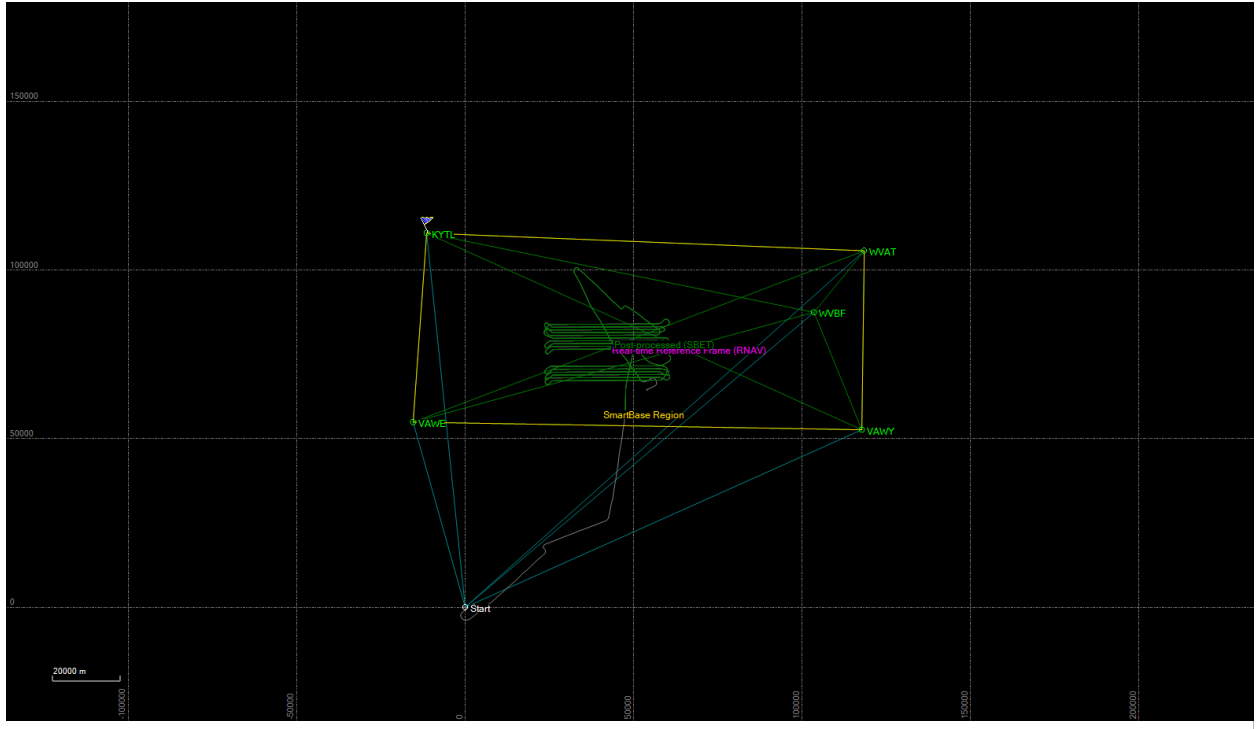


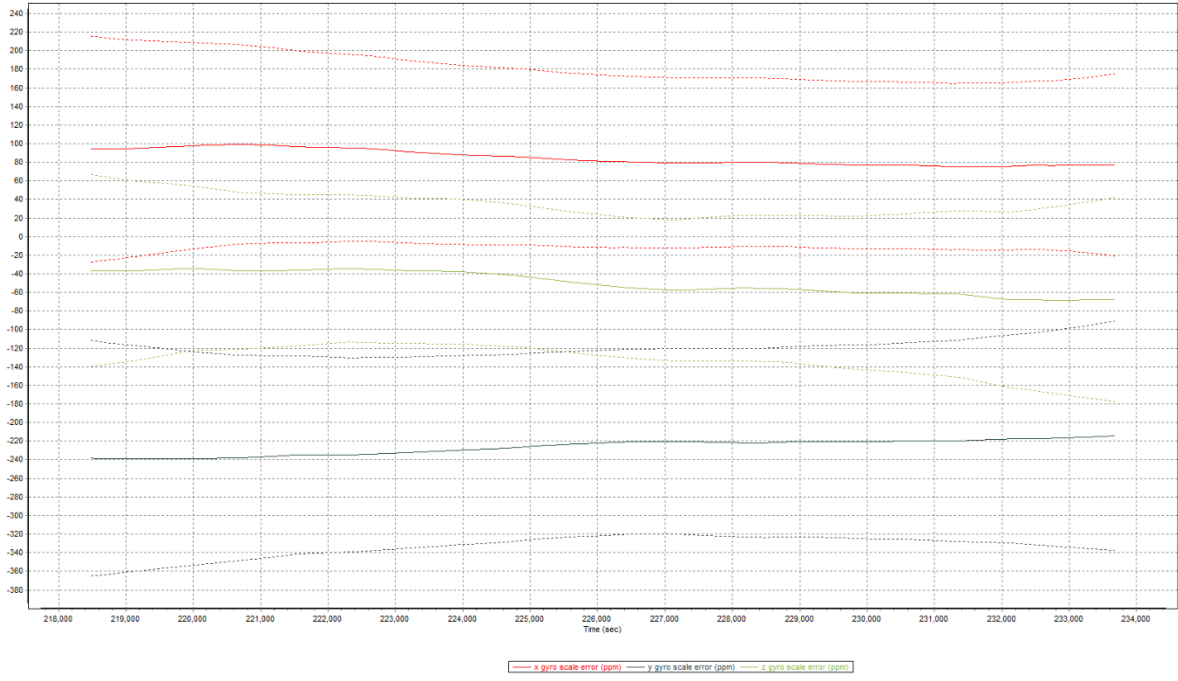


# CAU17101A

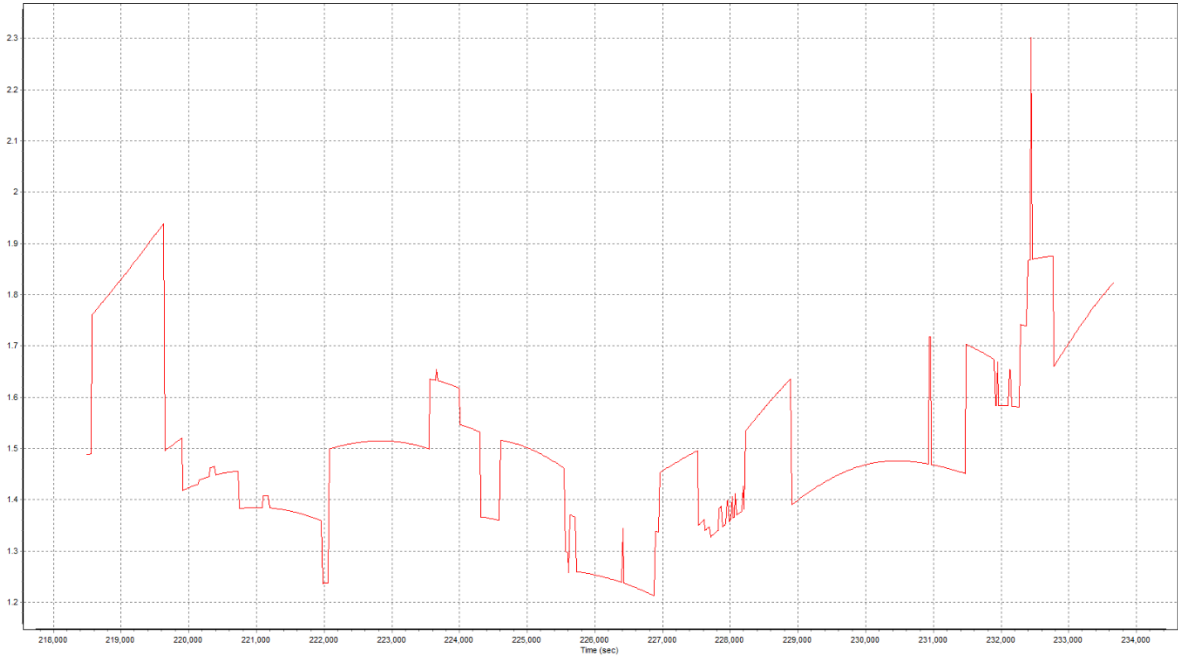


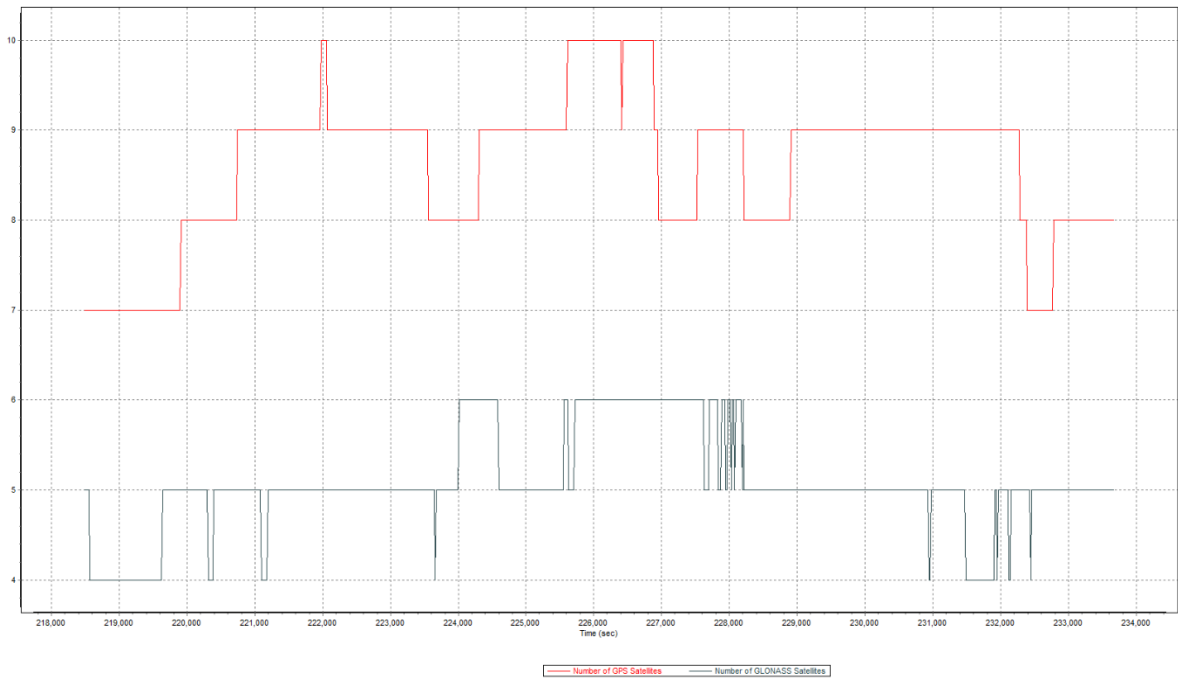
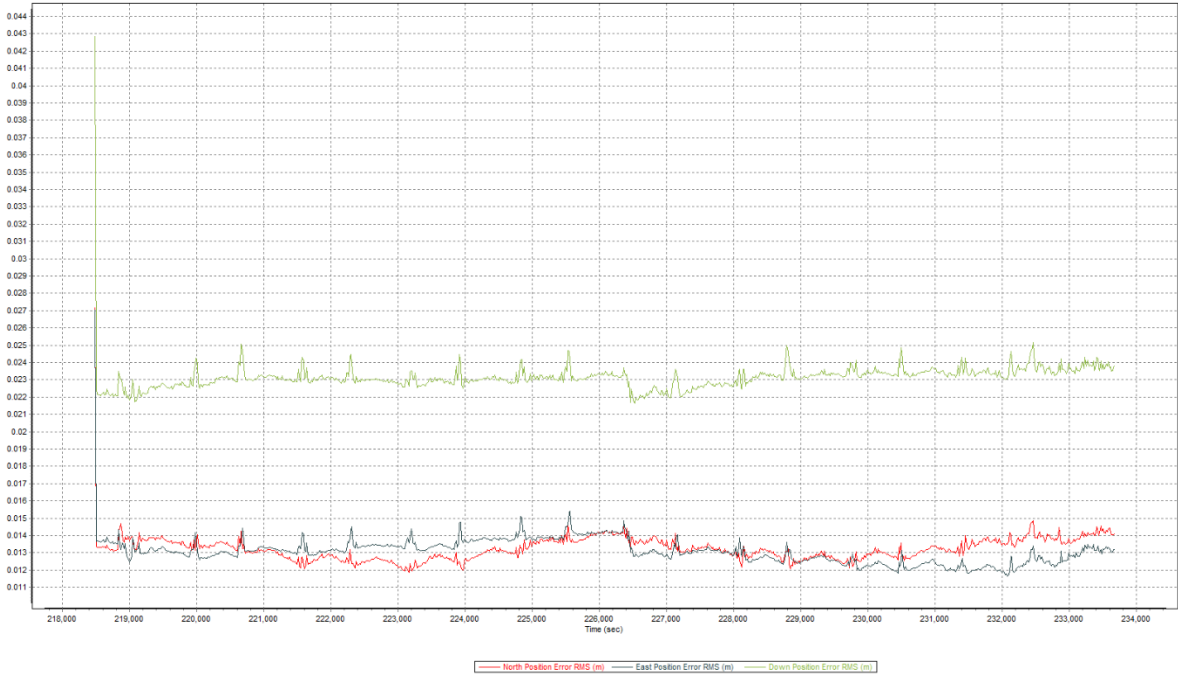






PDOP

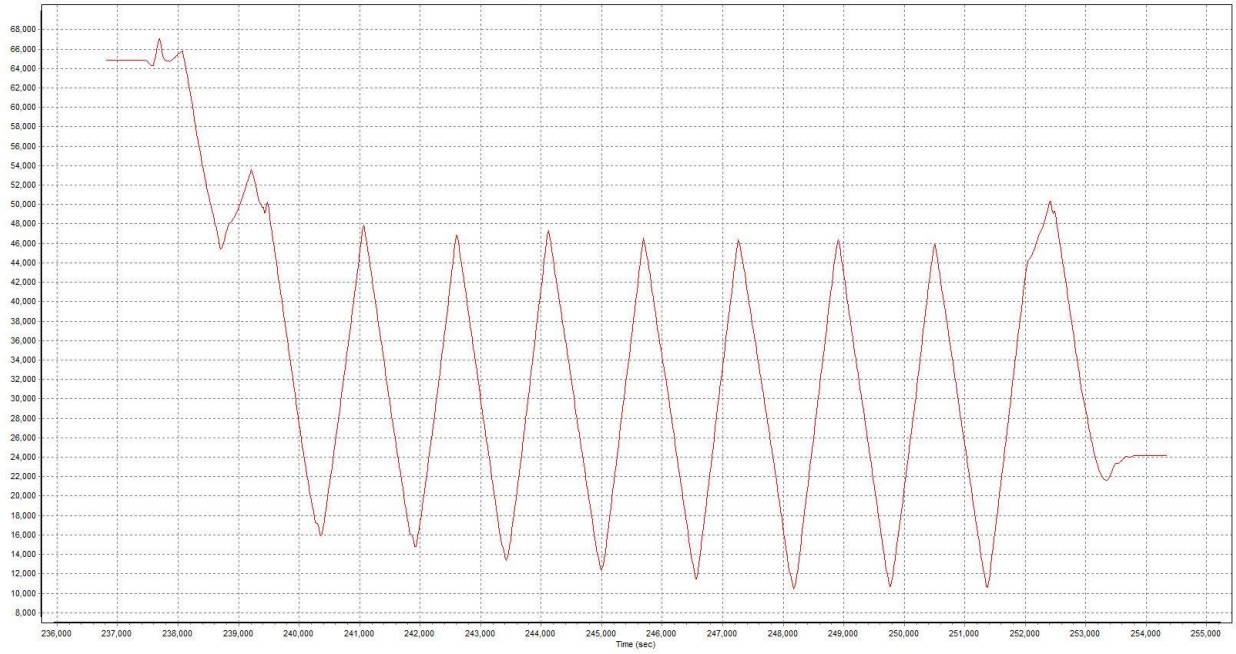




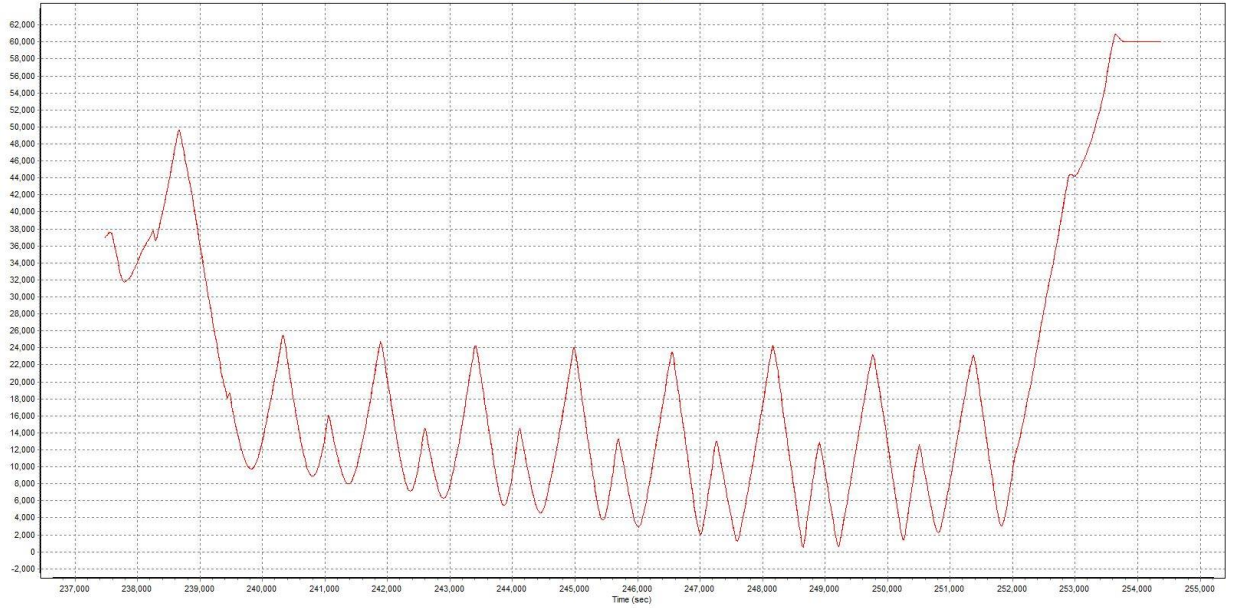


# CAU17101B

3D Distance to Closest GPS Station (m)



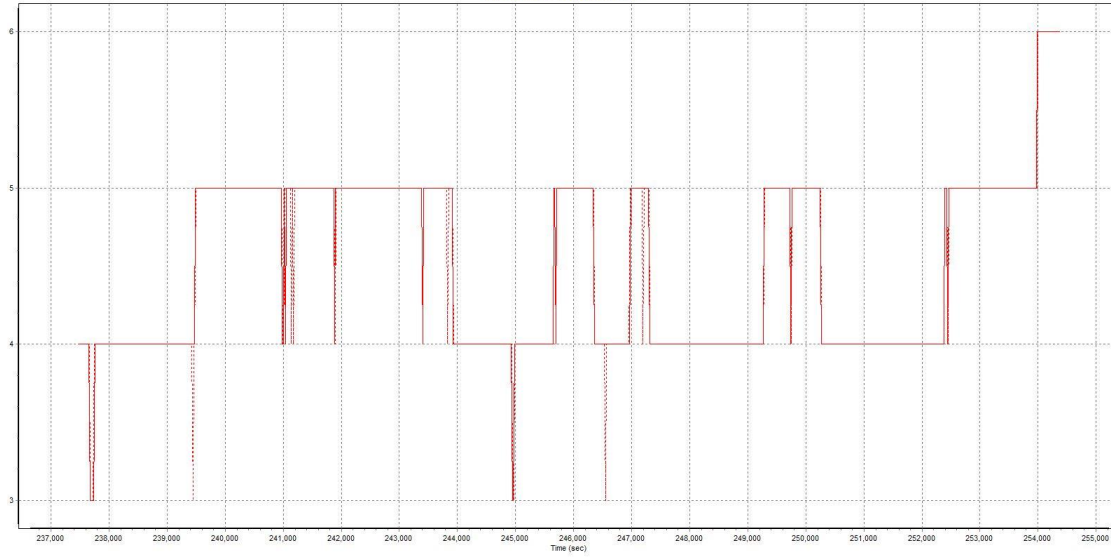
Baseline Length (m)



Forward  Reverse

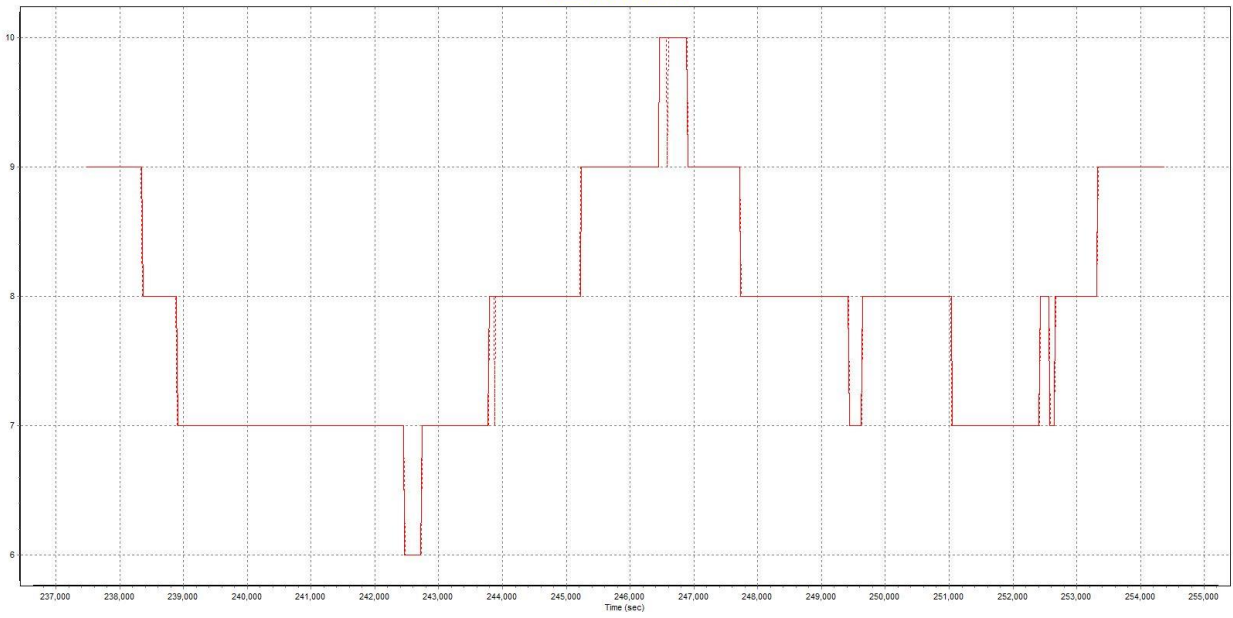


Number of GLONASS Satellites



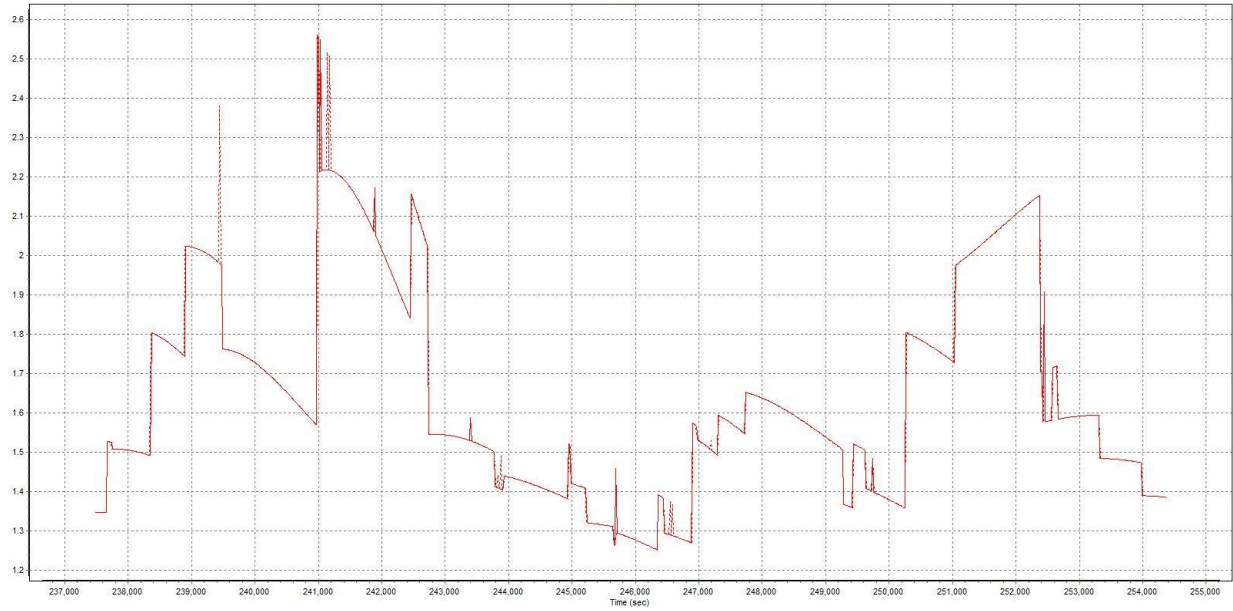
Forward  Reverse

Number of GPS Satellites



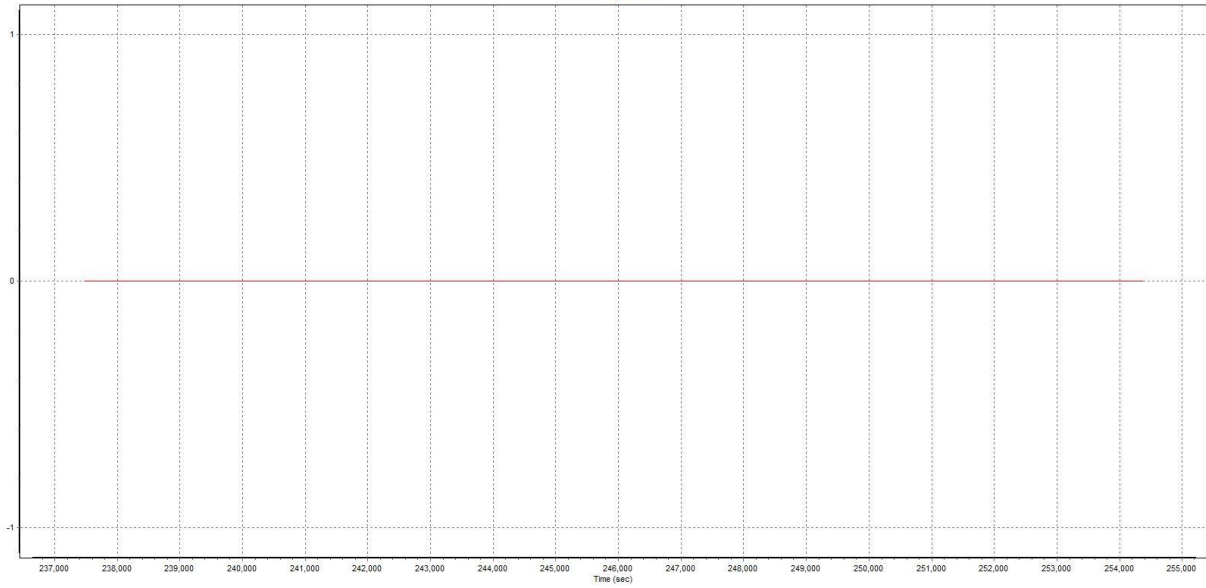
Forward  Reverse

PDOP



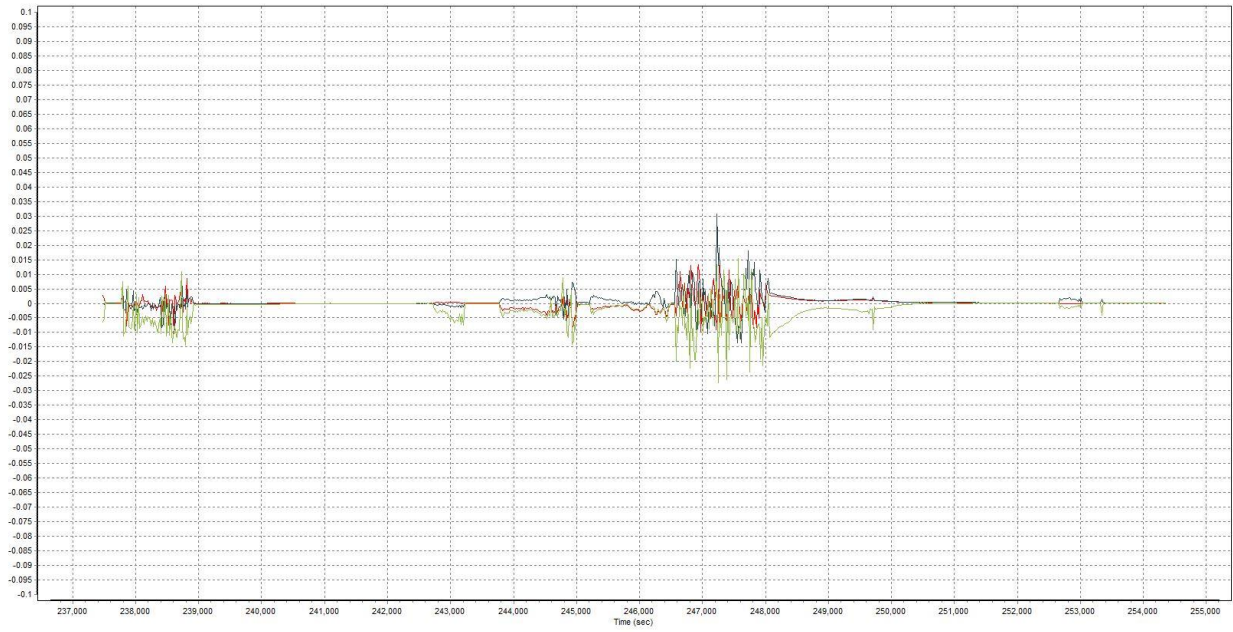
Forward  Reverse

Processing mode

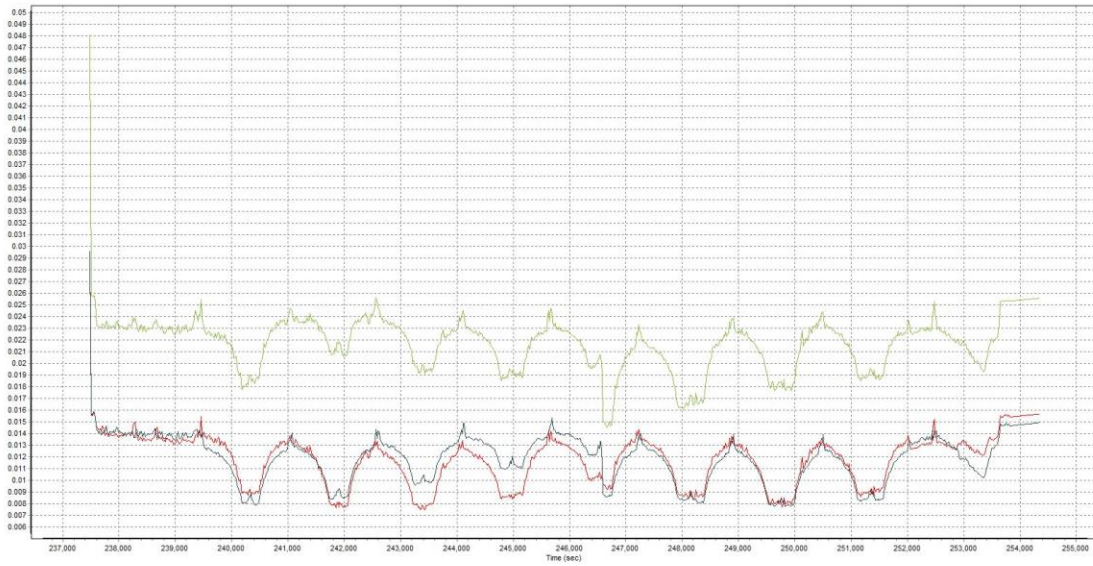


Forward  Reverse

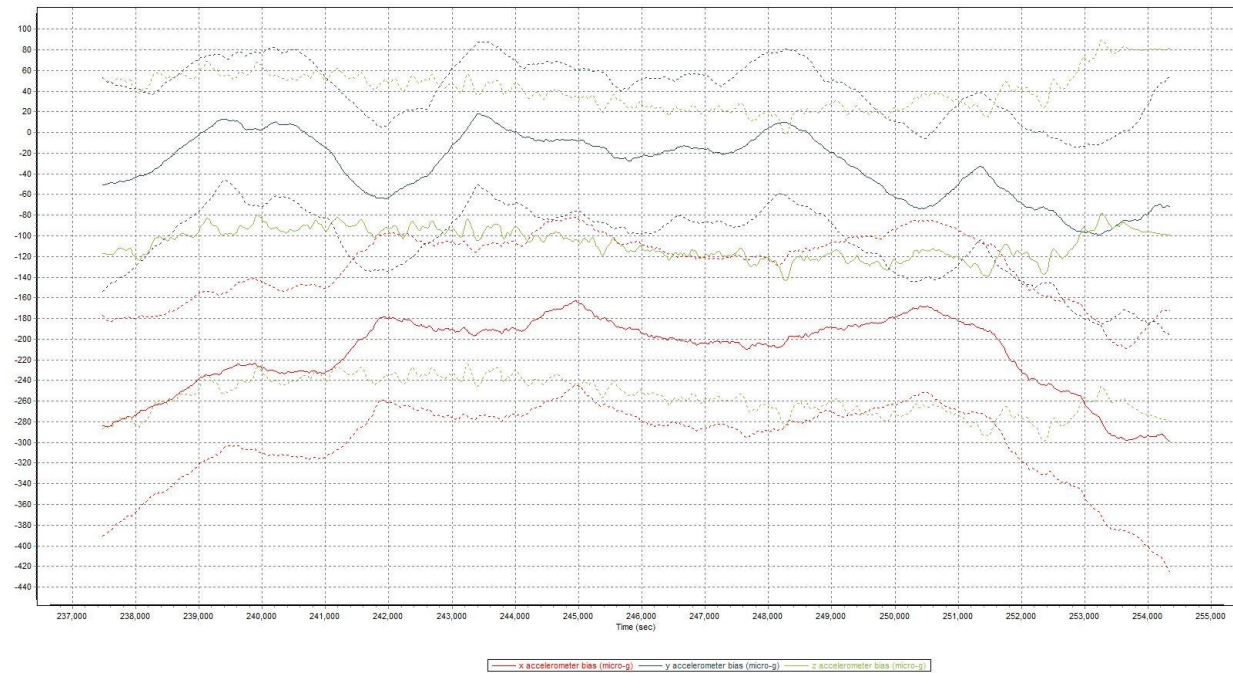
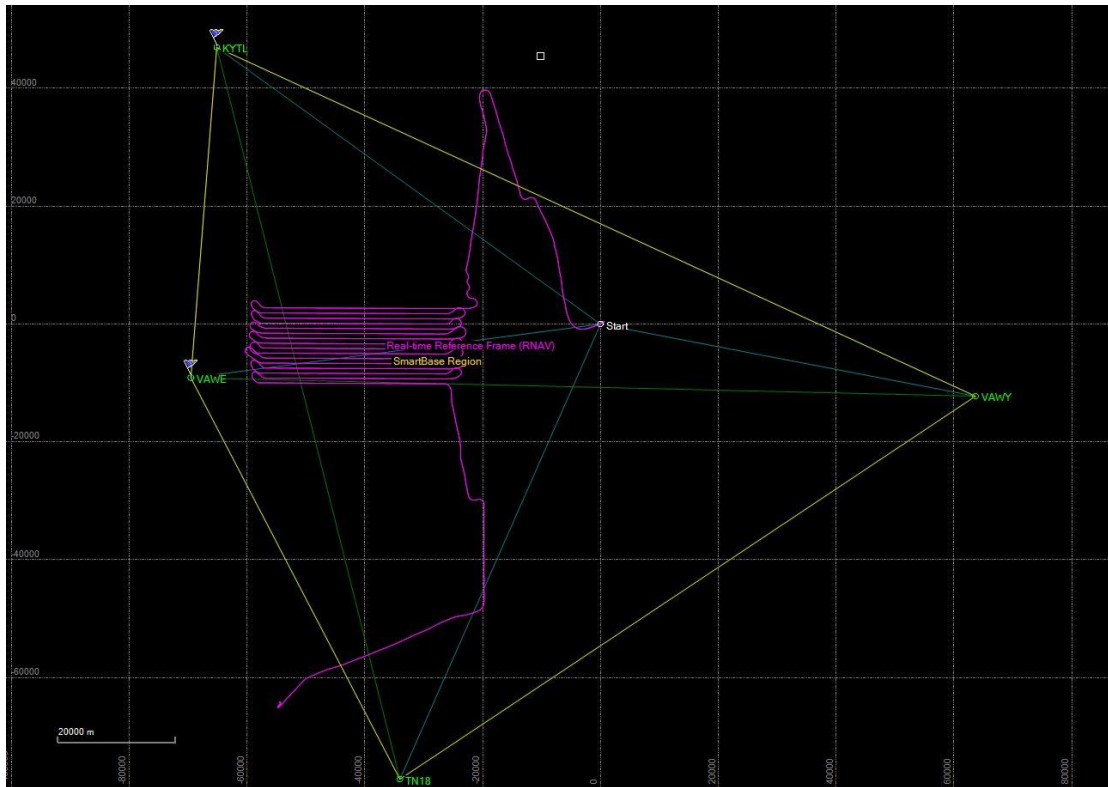
0 = Fixed NL, 1 = Fixed VL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = uAPPP, 6 = CIA, 7 = GNSS Nav, 8 = DR

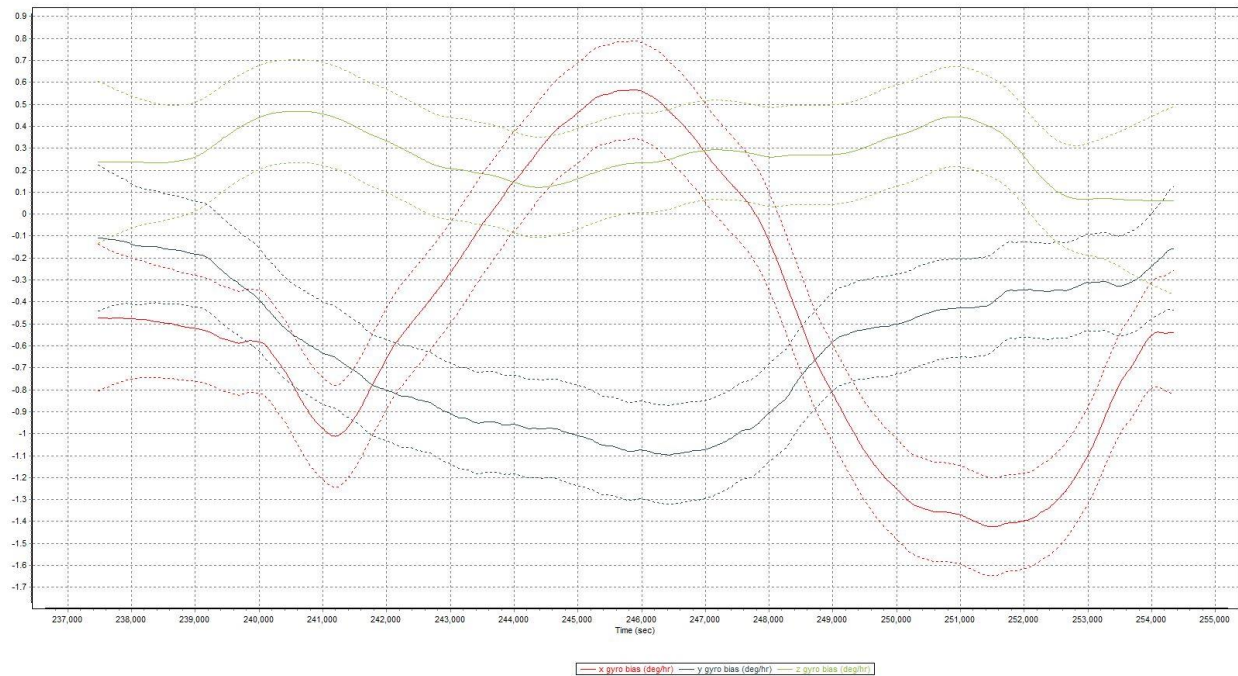
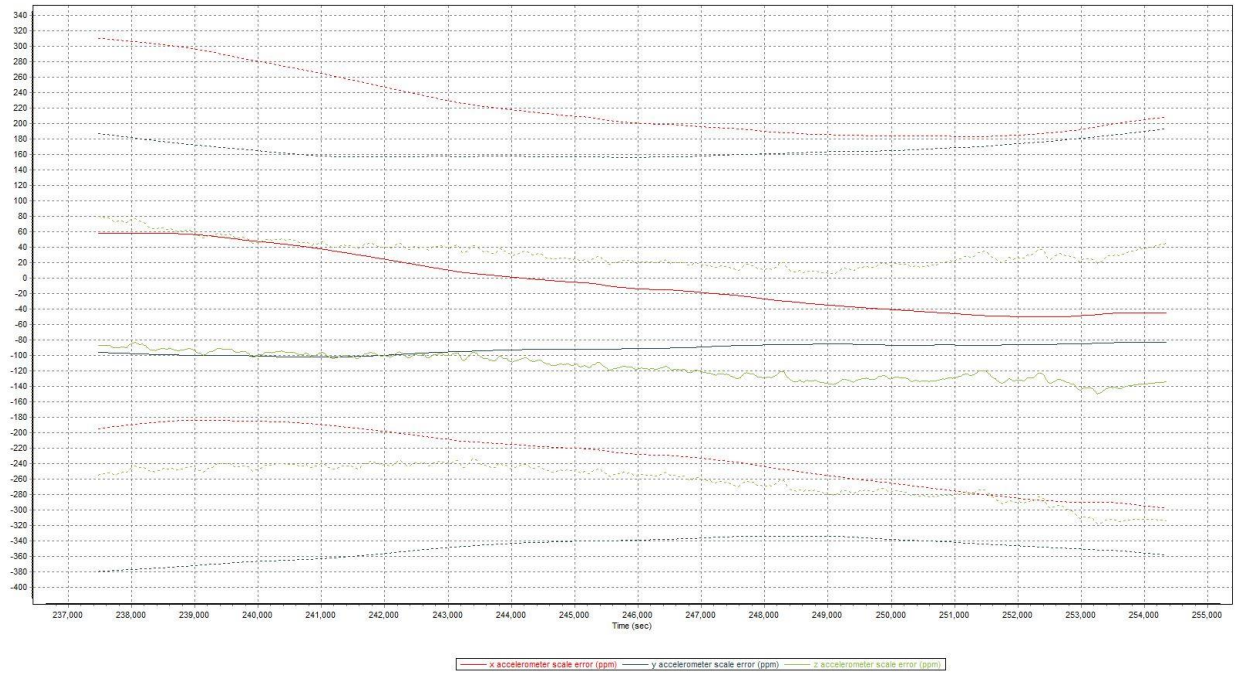


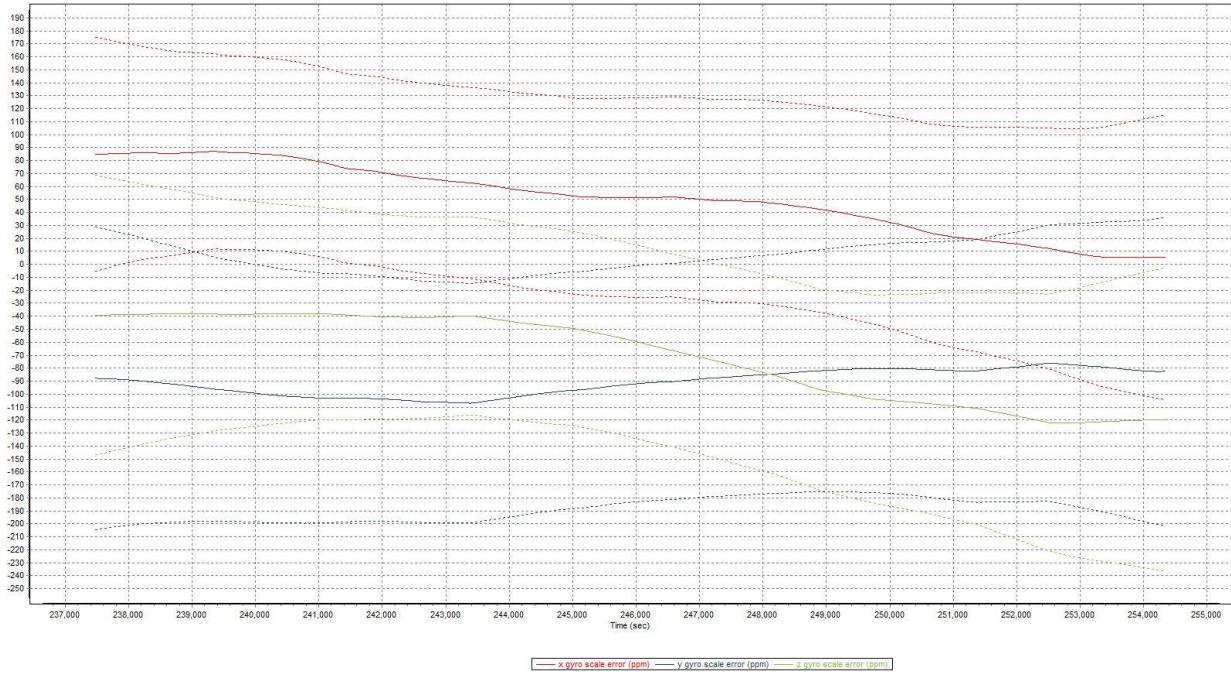
— North (m) — East (m) — Down (m) → DR mode



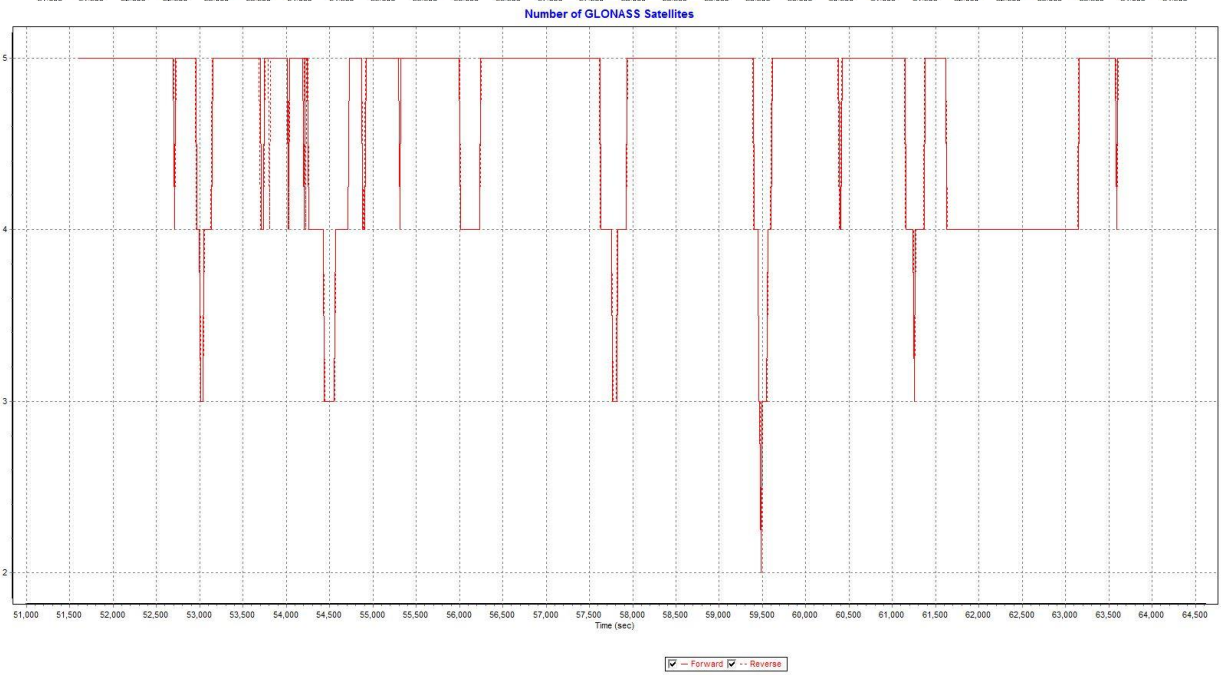
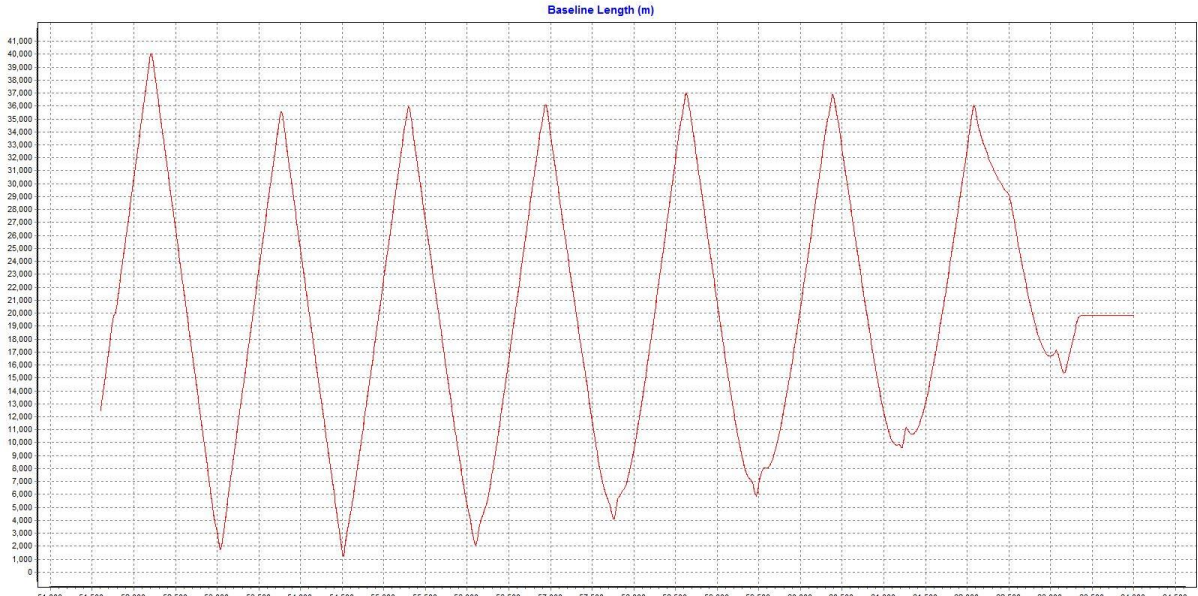
— North Position Error RMS (m) — East Position Error RMS (m) — Down Position Error RMS (m)



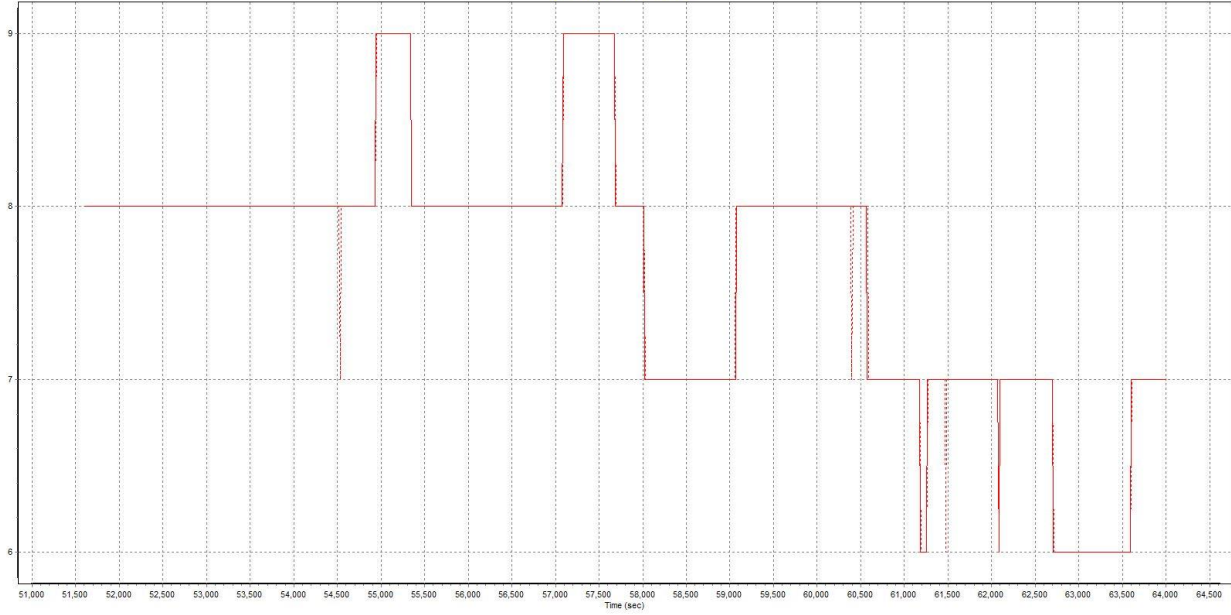




UNB16311A

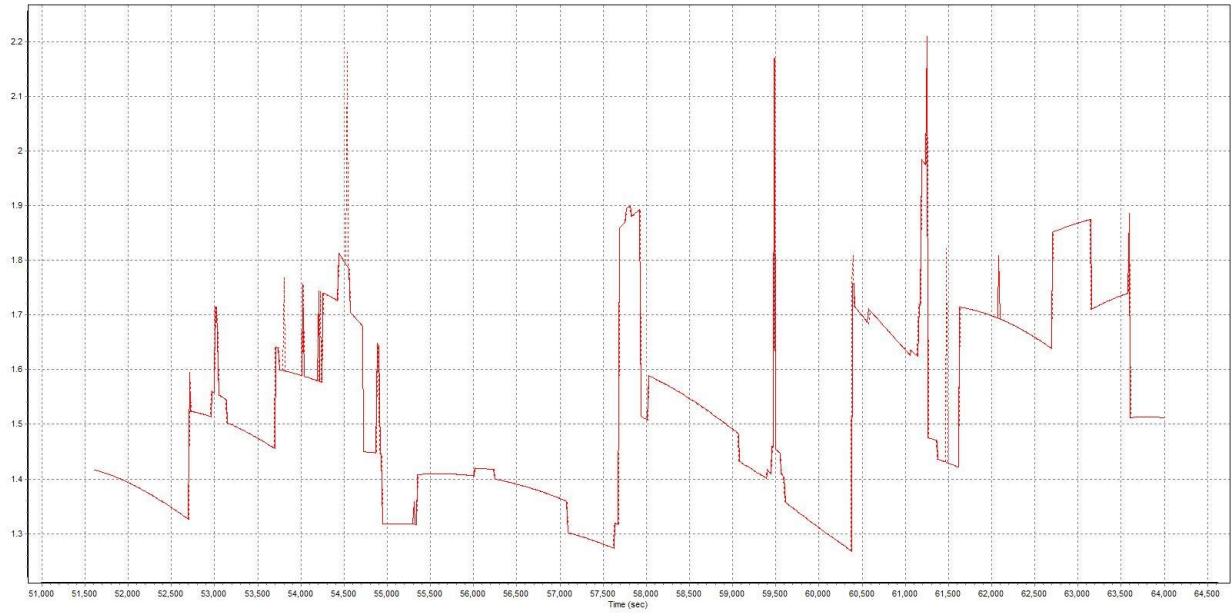


Number of GPS Satellites



Forward  Reverse

PDOP



Forward  Reverse

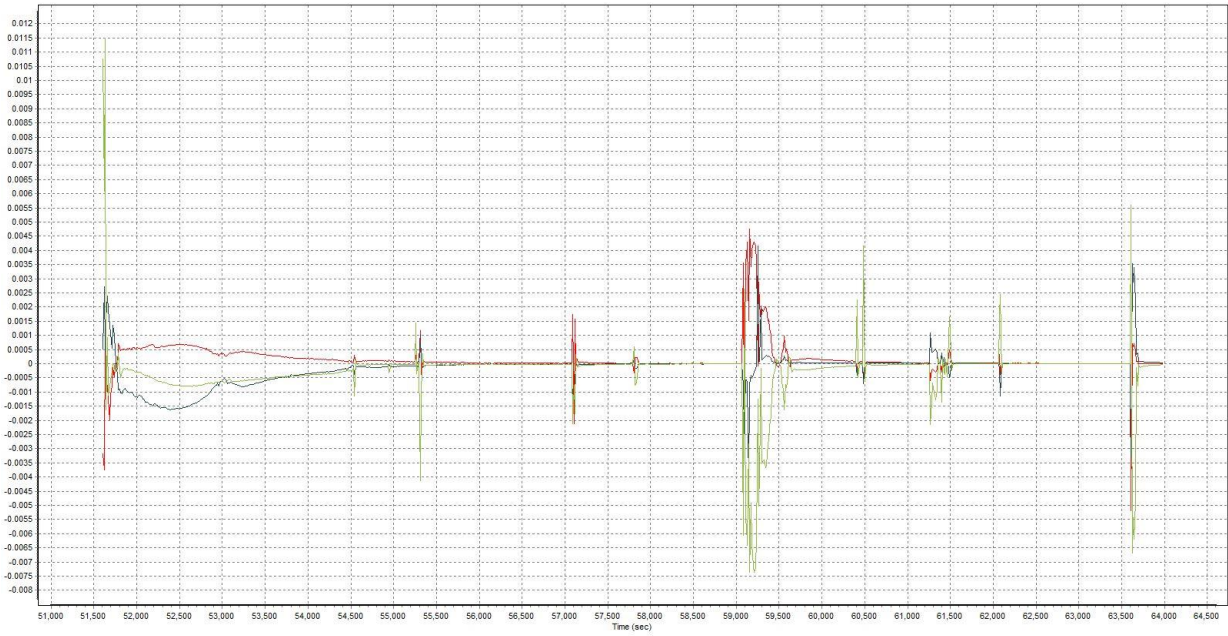


Processing mode

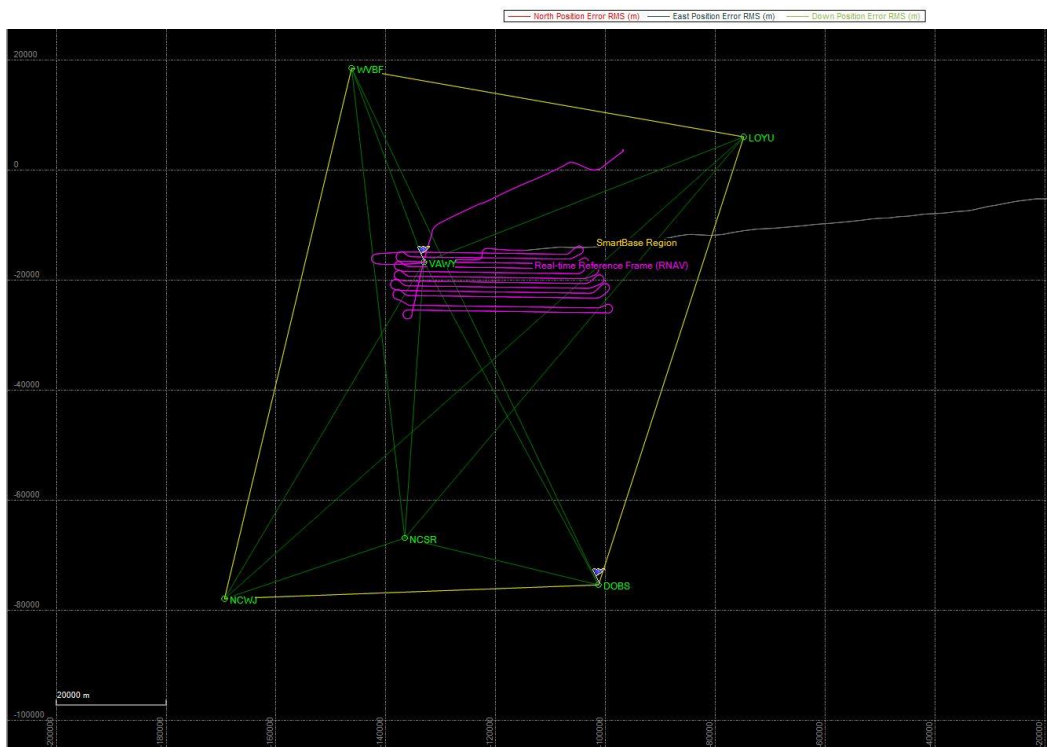
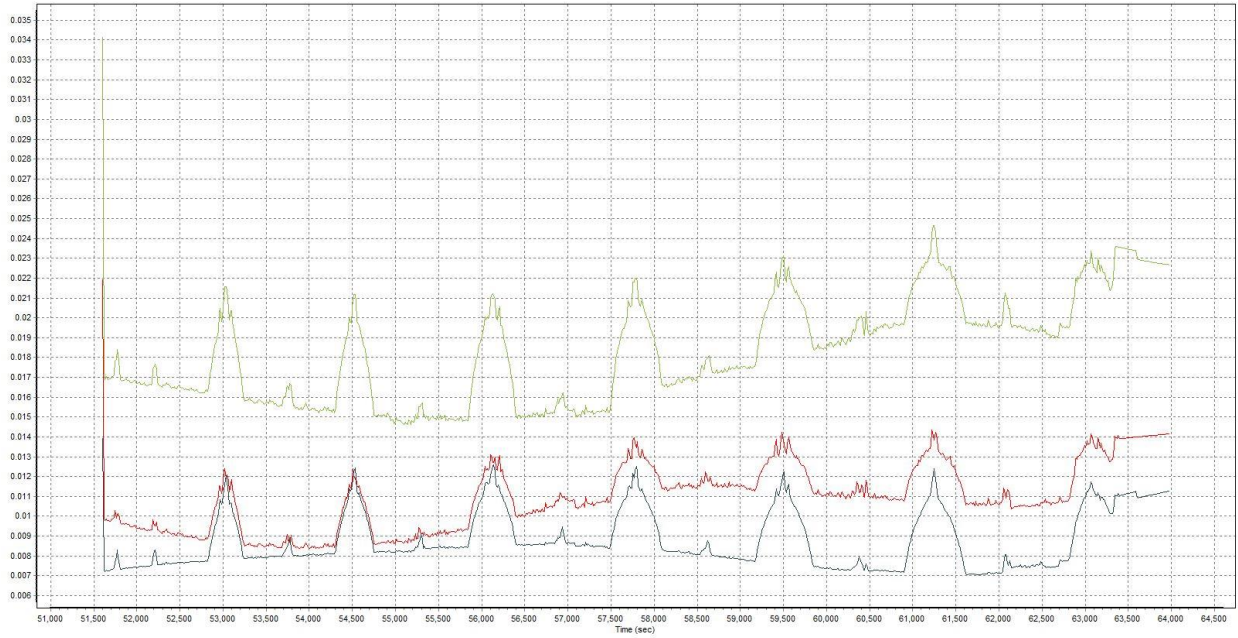


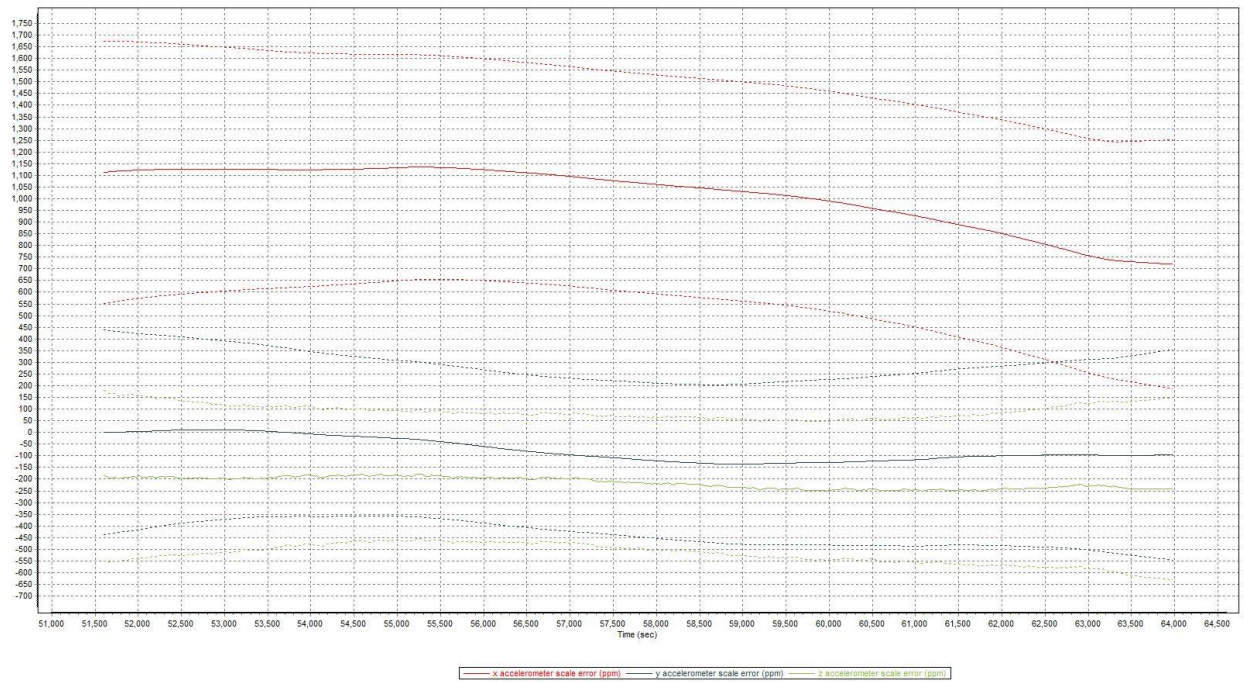
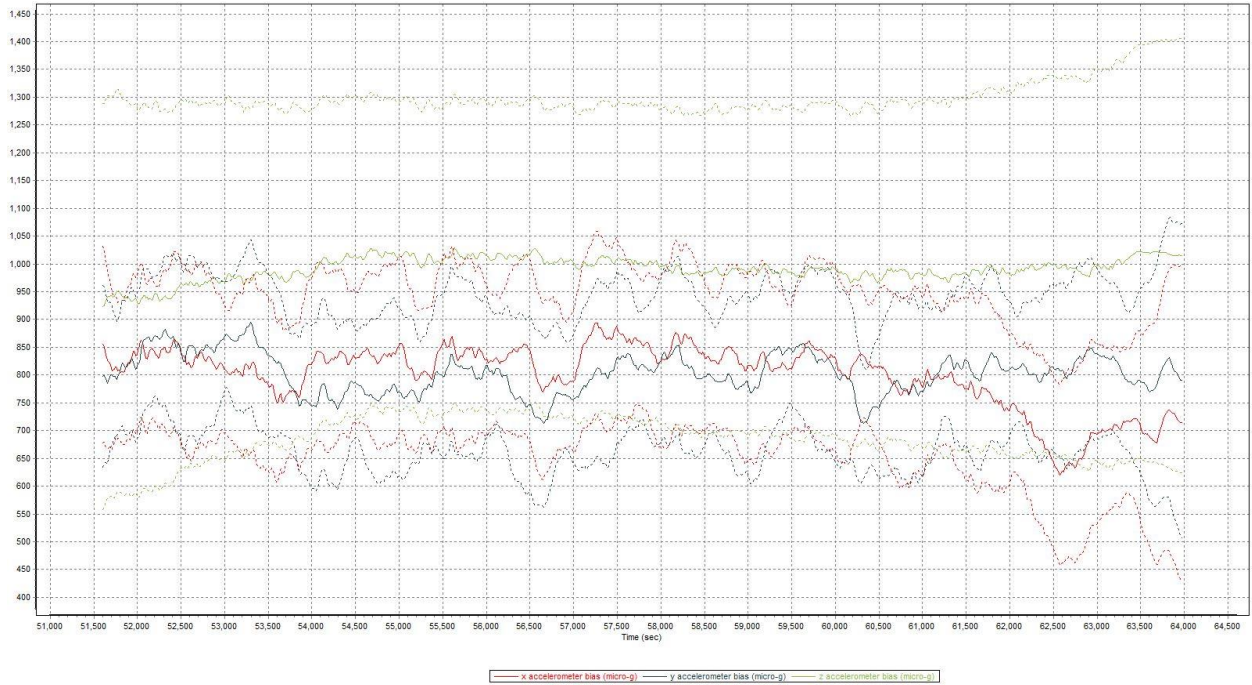
Forward  Reverse

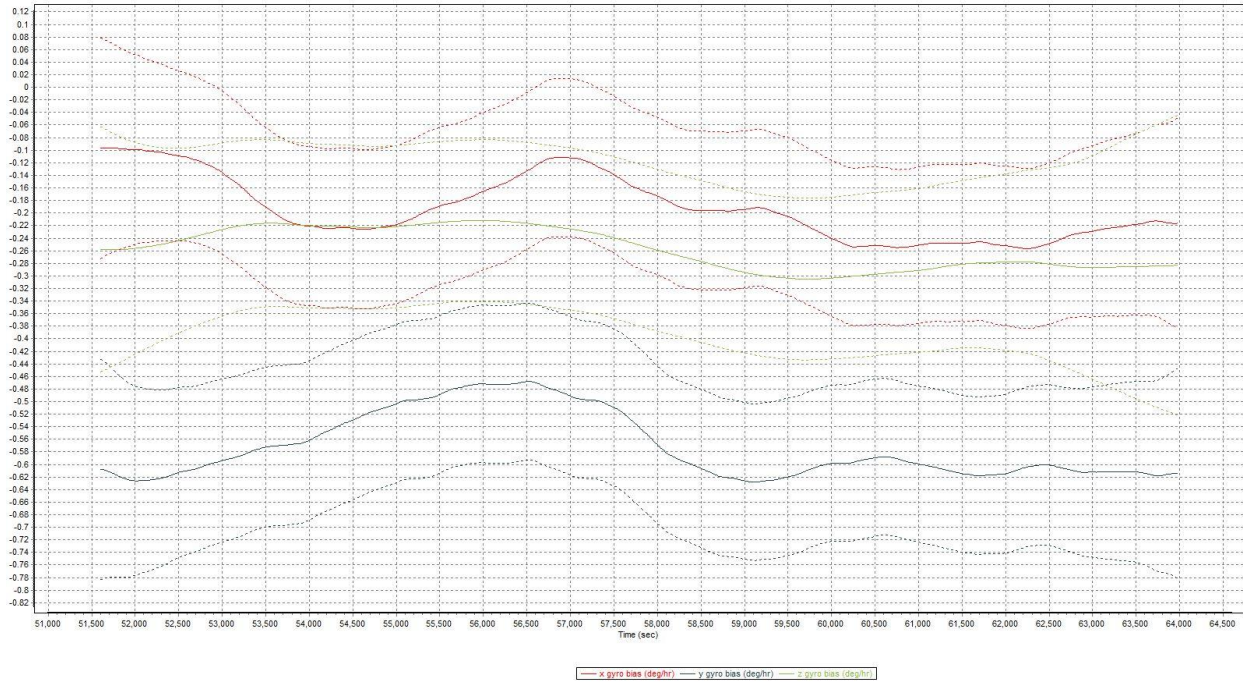
0 = Fixed NL, 1 = Fixed VL, 2 = Float, 3 = DGSS, 4 = RTCM, 5 = IAPPP, 6 = CIA, 7 = GNSS Nav, 8 = DR



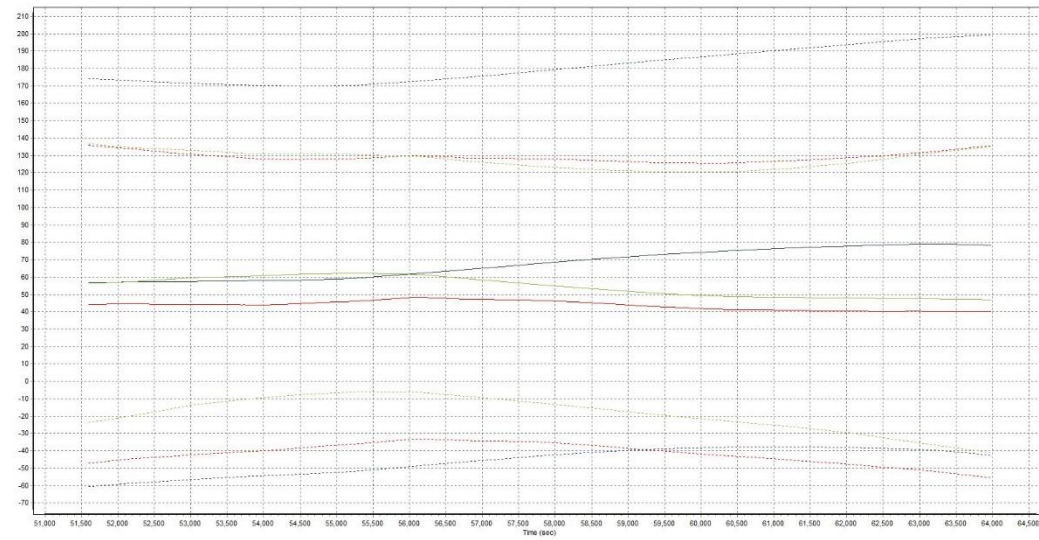
North (m) East (m) Down (m) ← DR mode





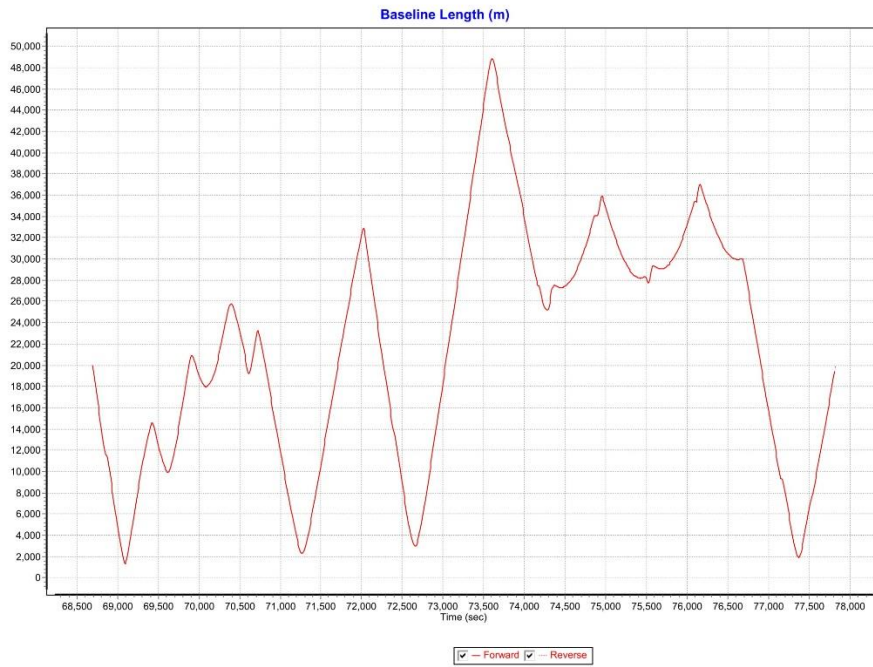
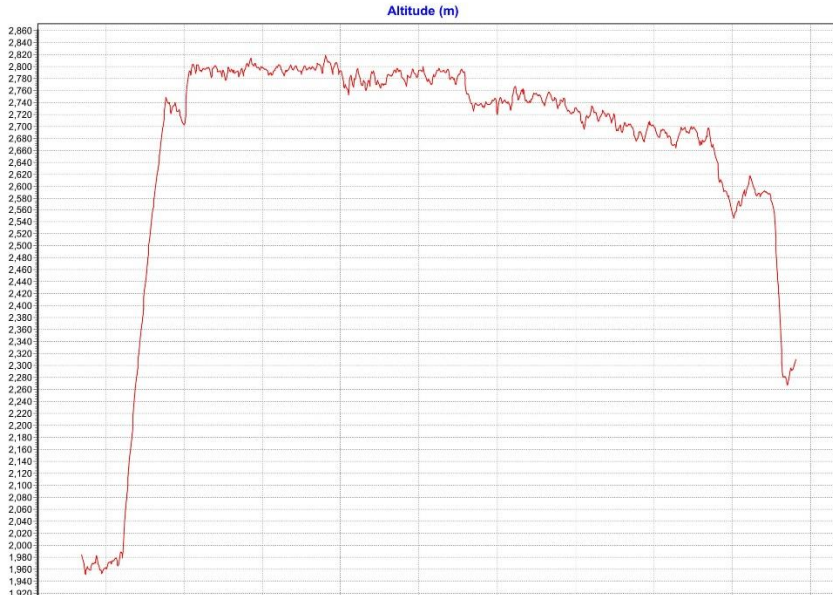


x gyro bias (deg/hr) y gyro bias (deg/hr) z gyro bias (deg/hr)

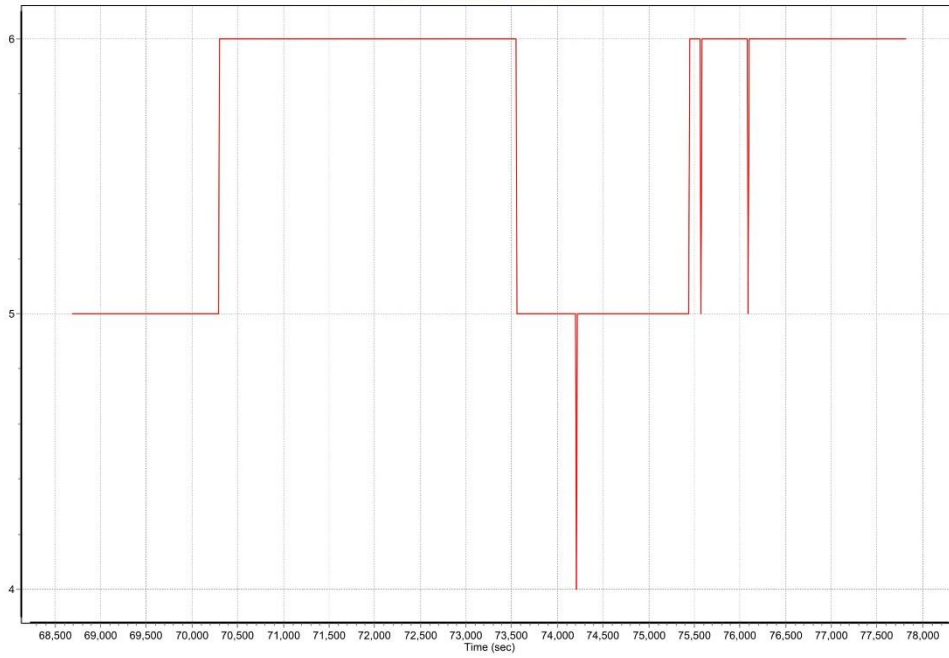


x gyro scale error (ppm) y gyro scale error (ppm) z gyro scale error (ppm)

**UNB16311B**

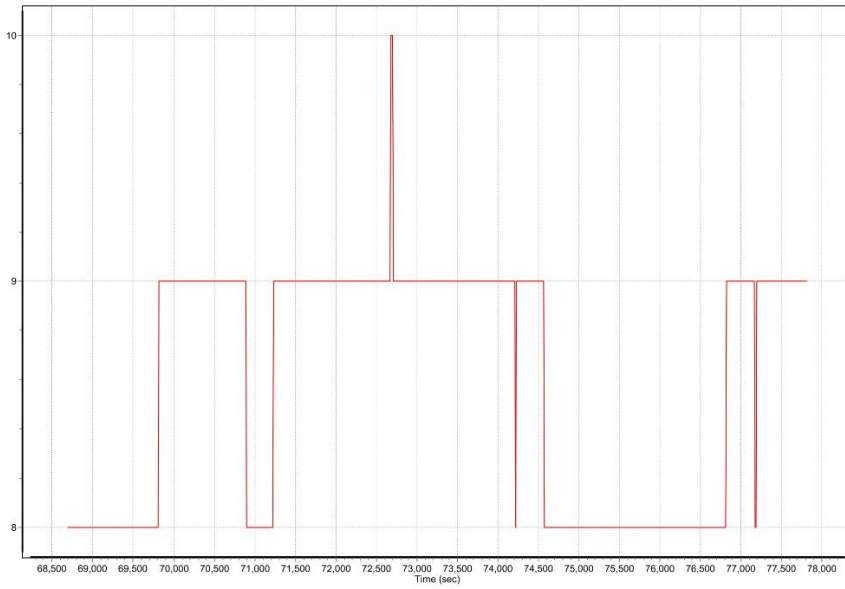


Number of GLONASS Satellites



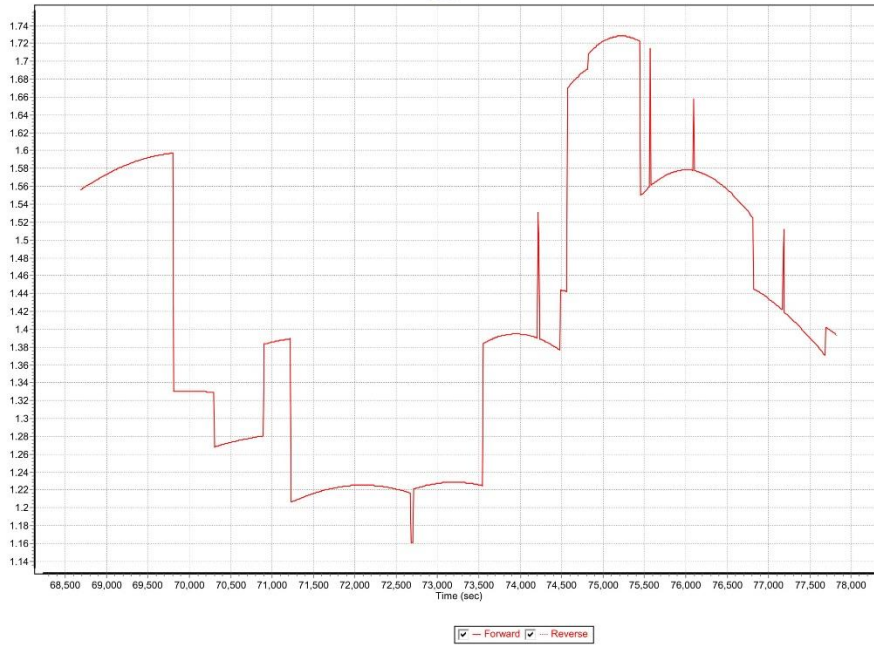
Forward  Reverse

Number of GPS Satellites

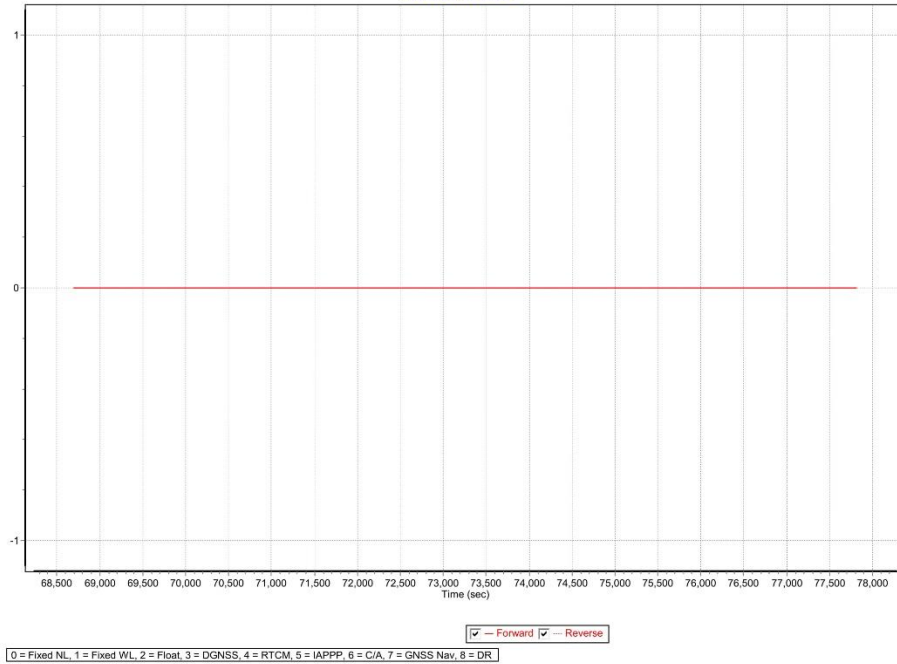


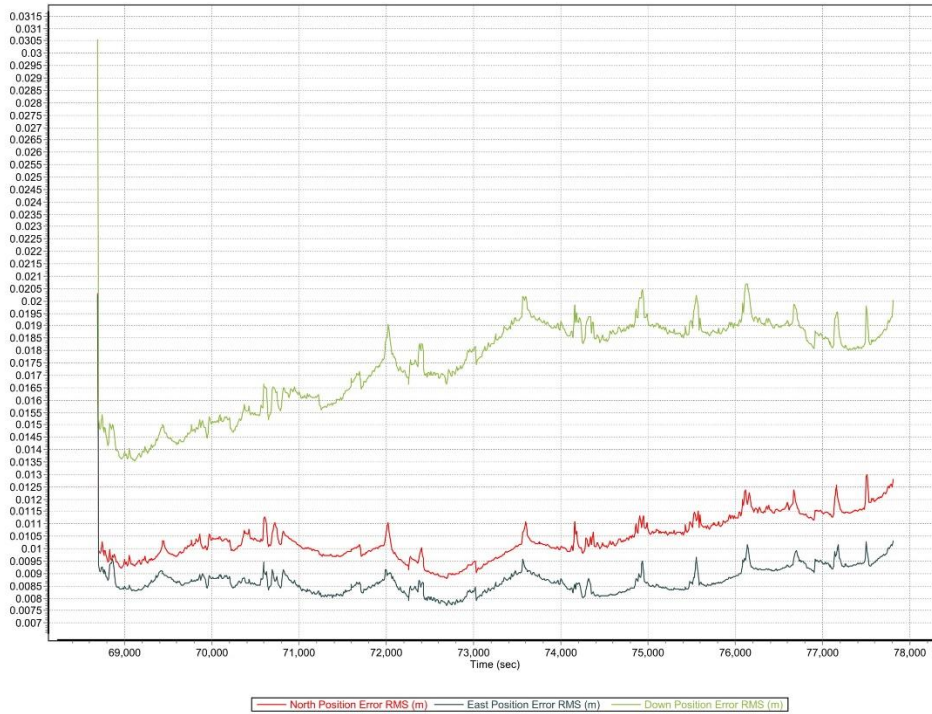
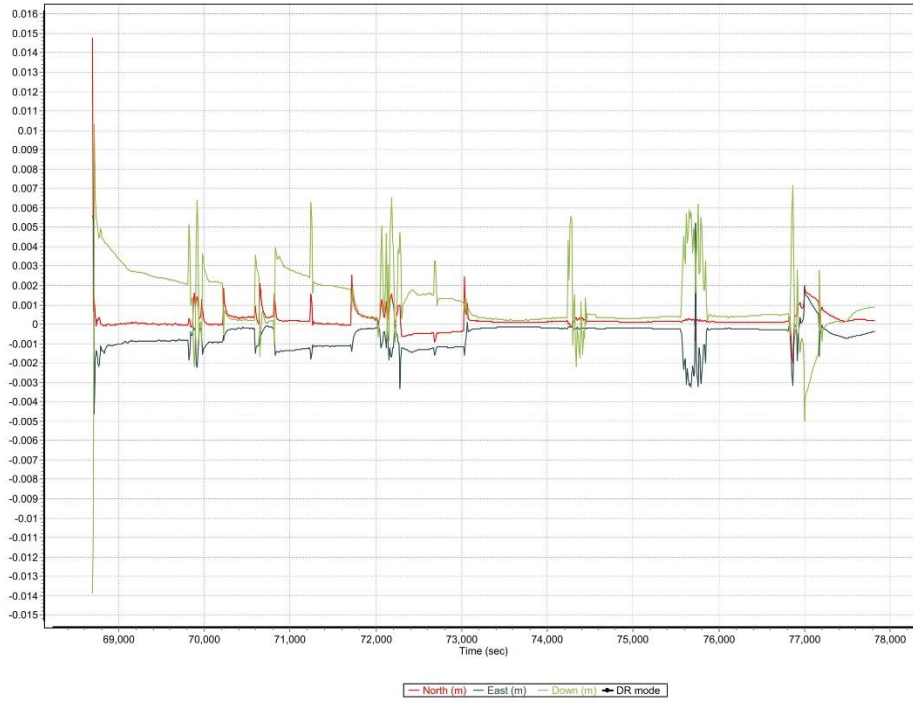
Forward  Reverse

### PDOP

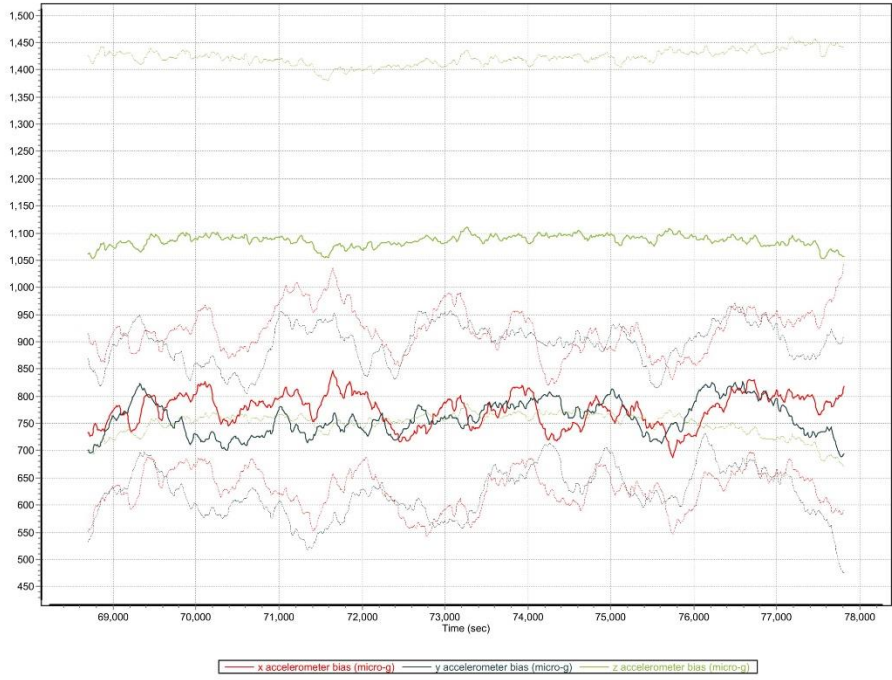


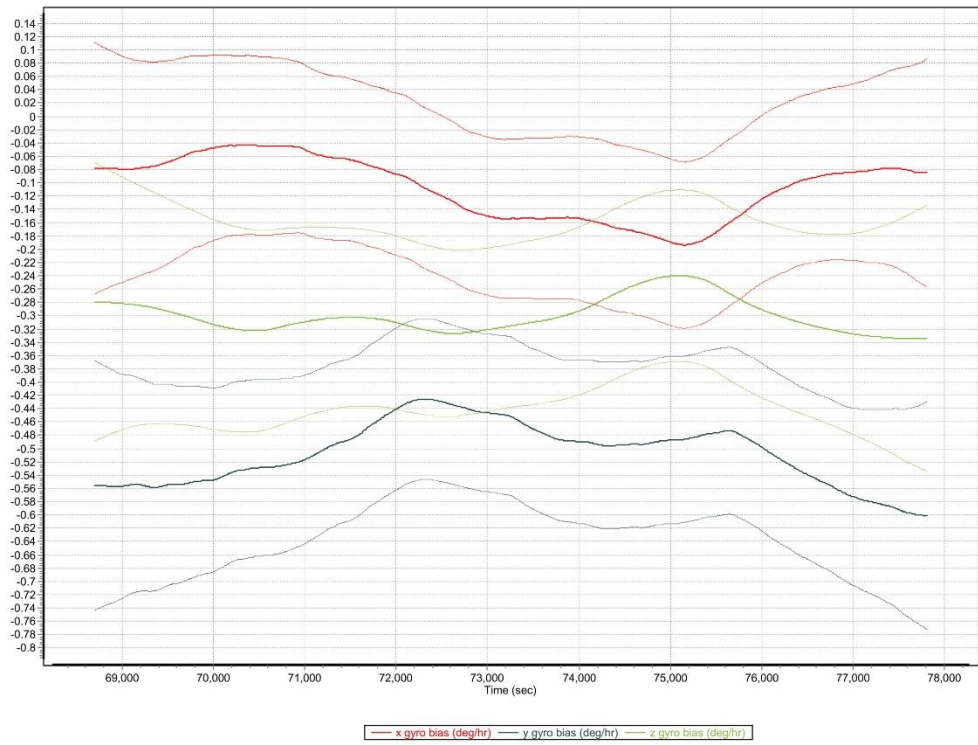
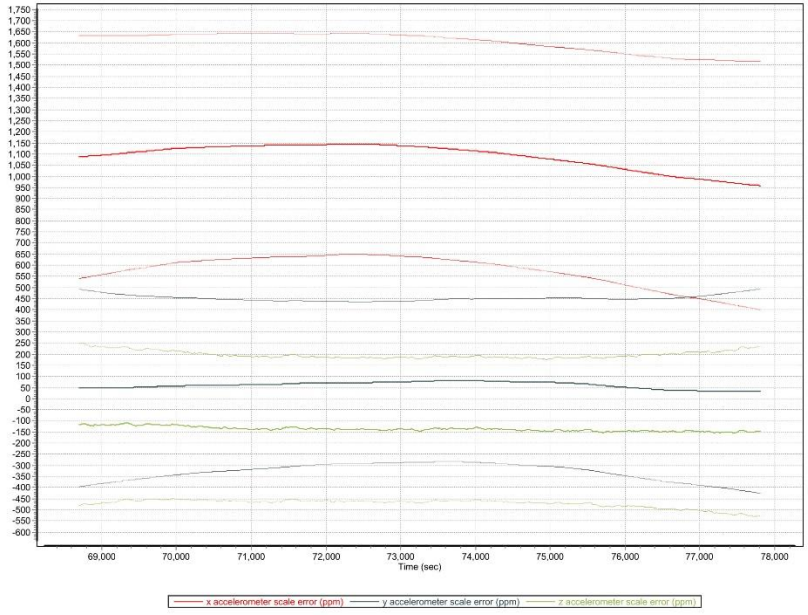
### Processing mode

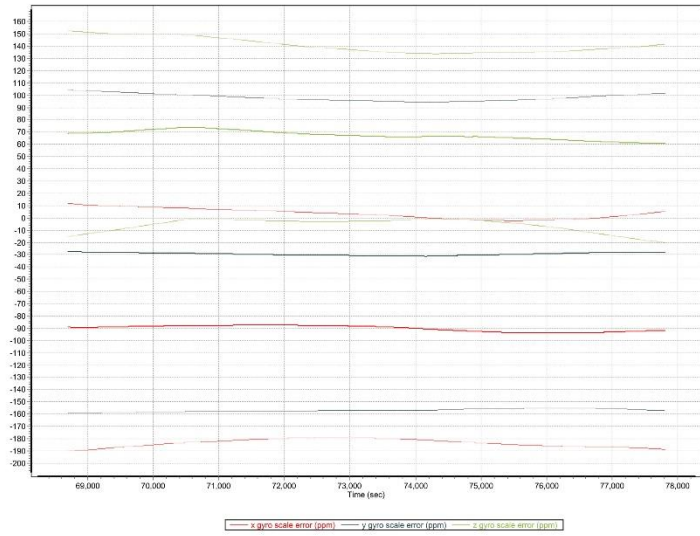




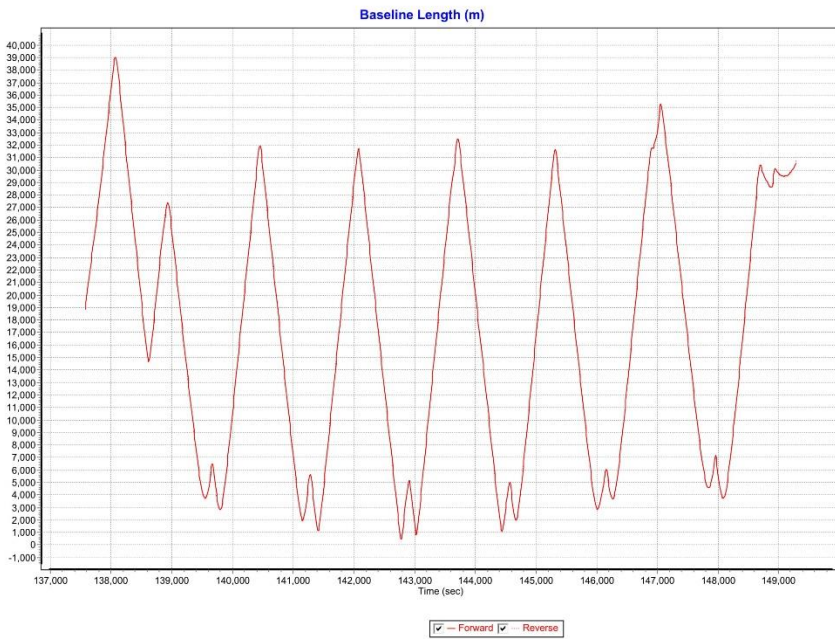
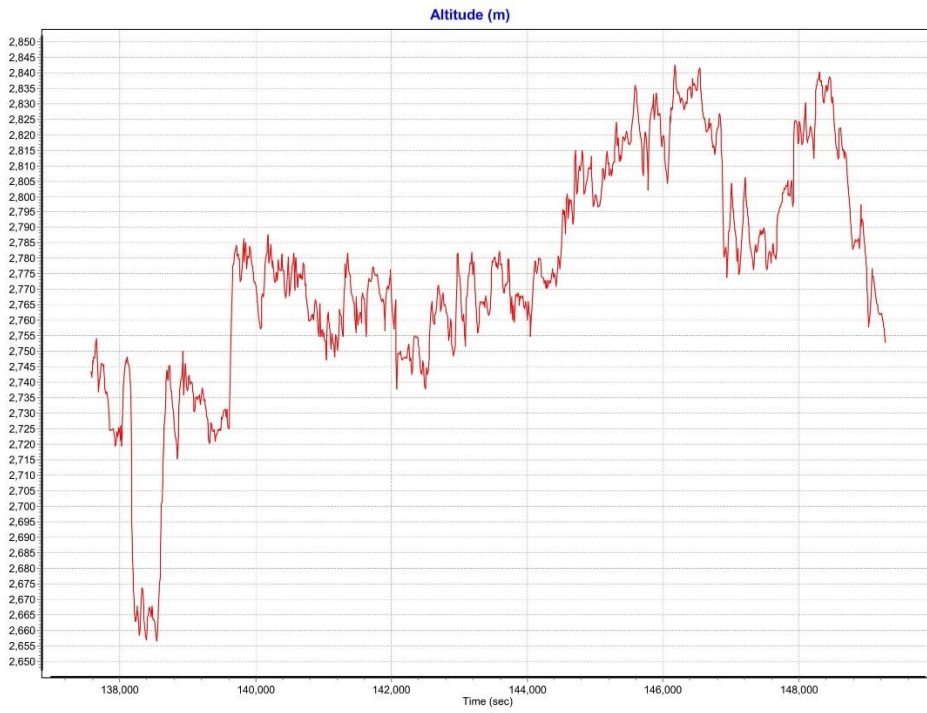


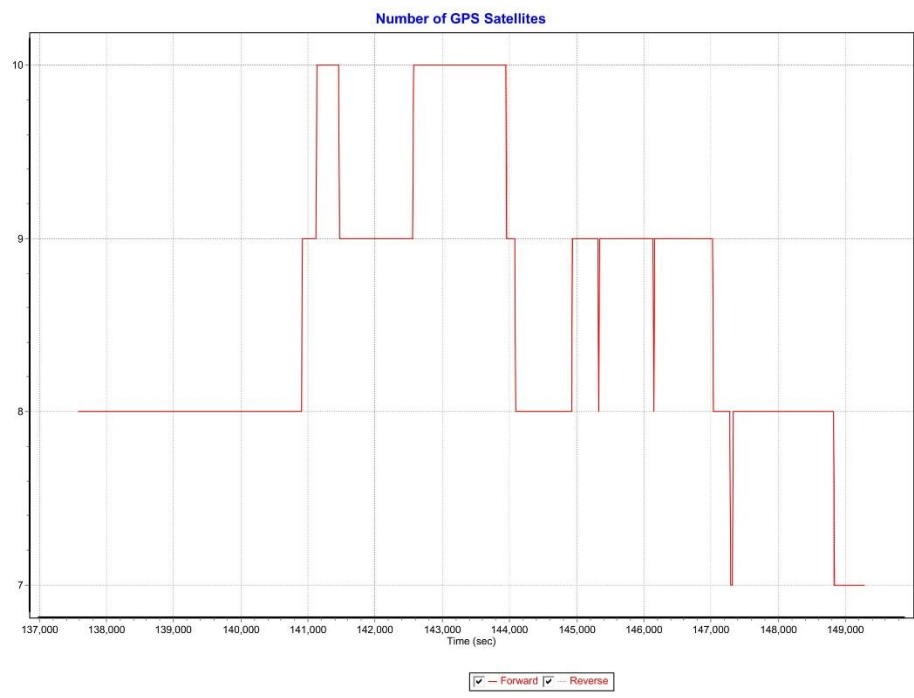
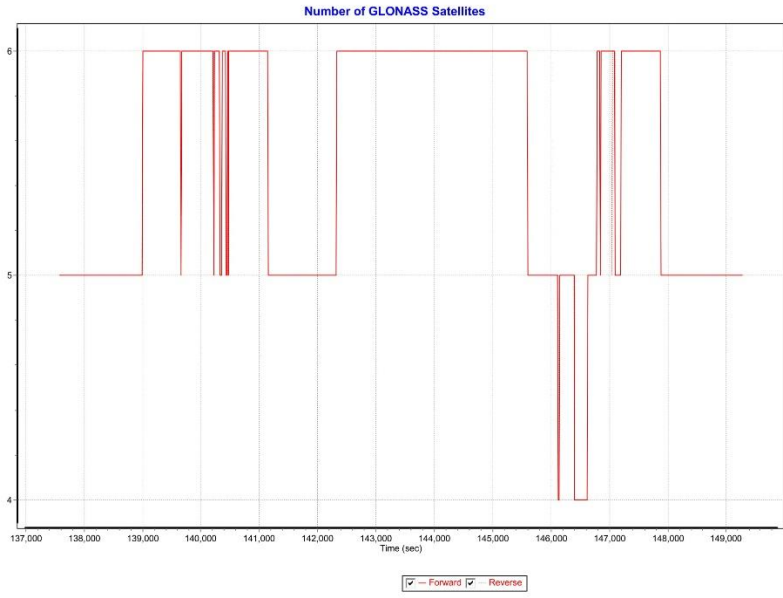




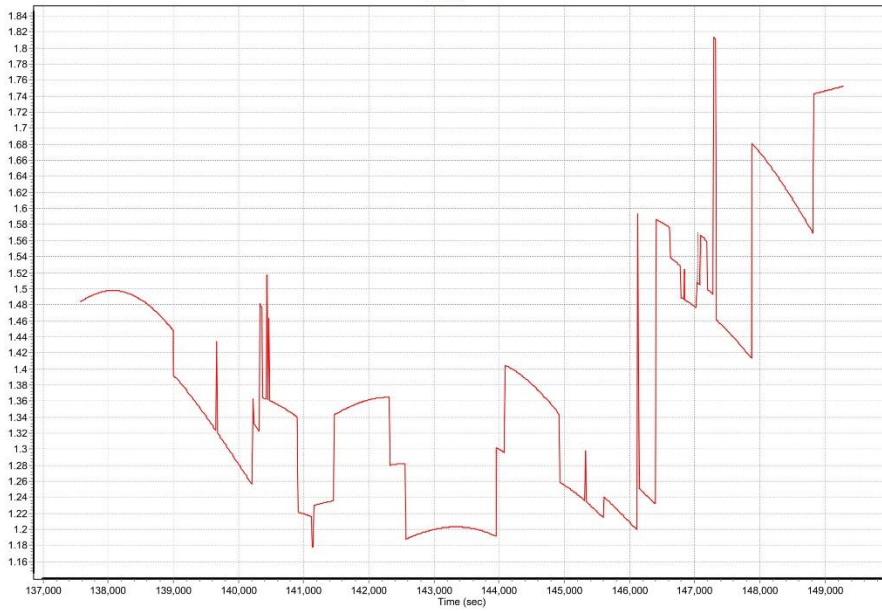


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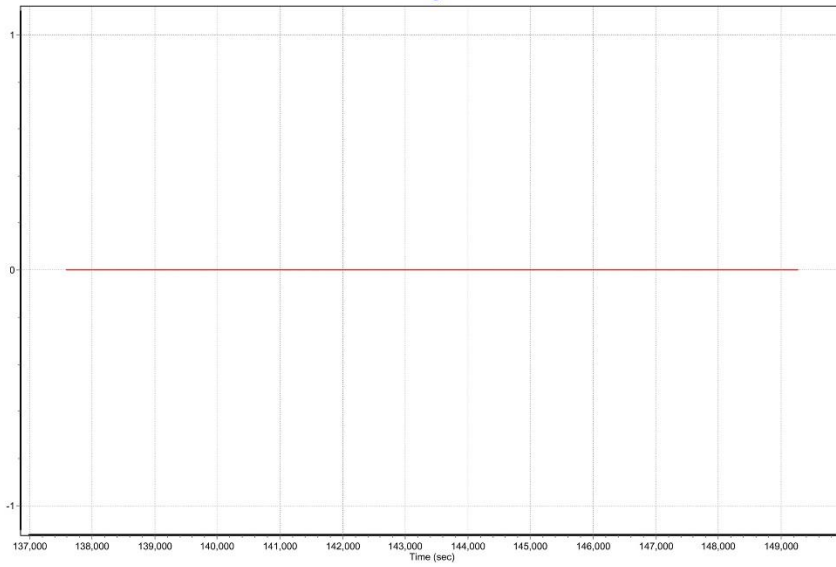


### PDOP



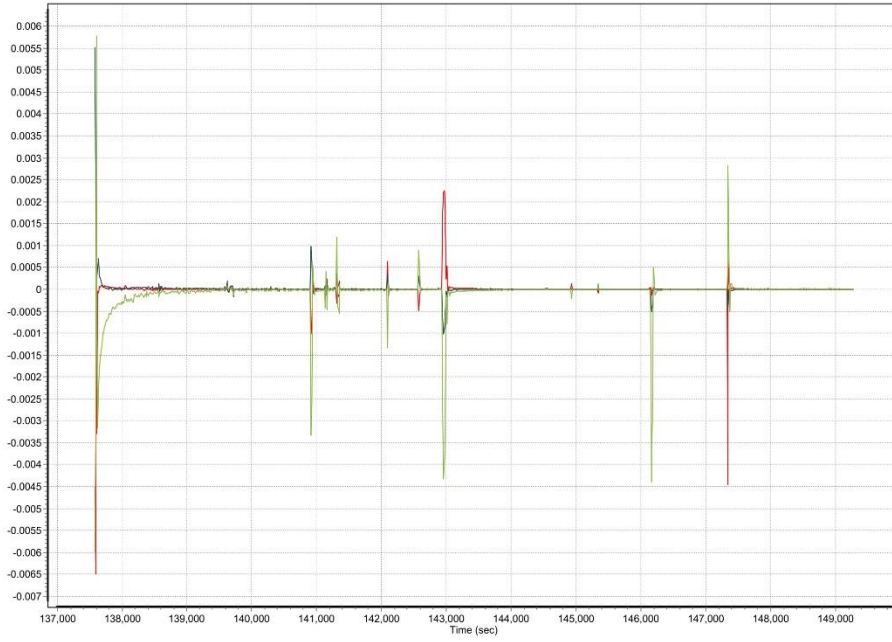
Forward  Reverse

### Processing mode

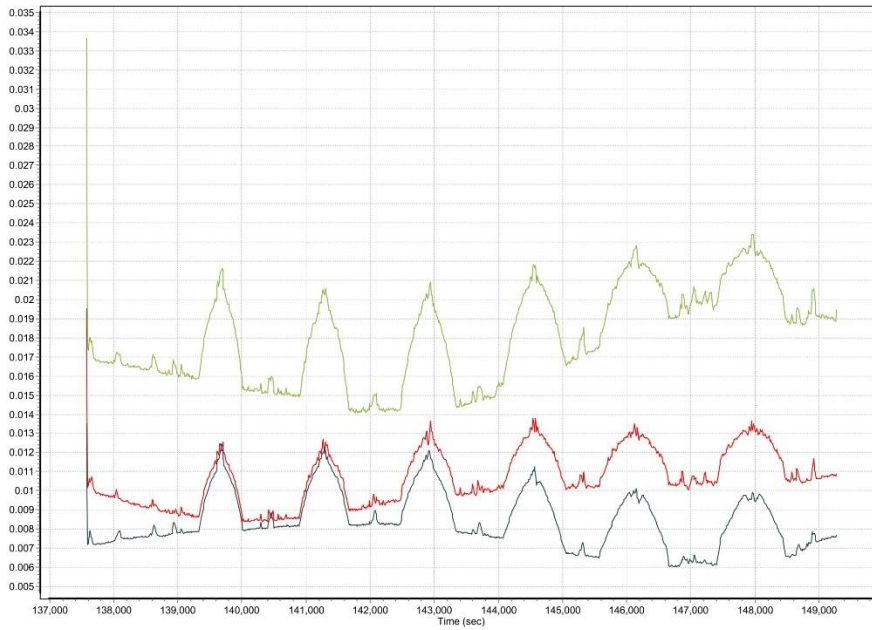


Forward  Reverse

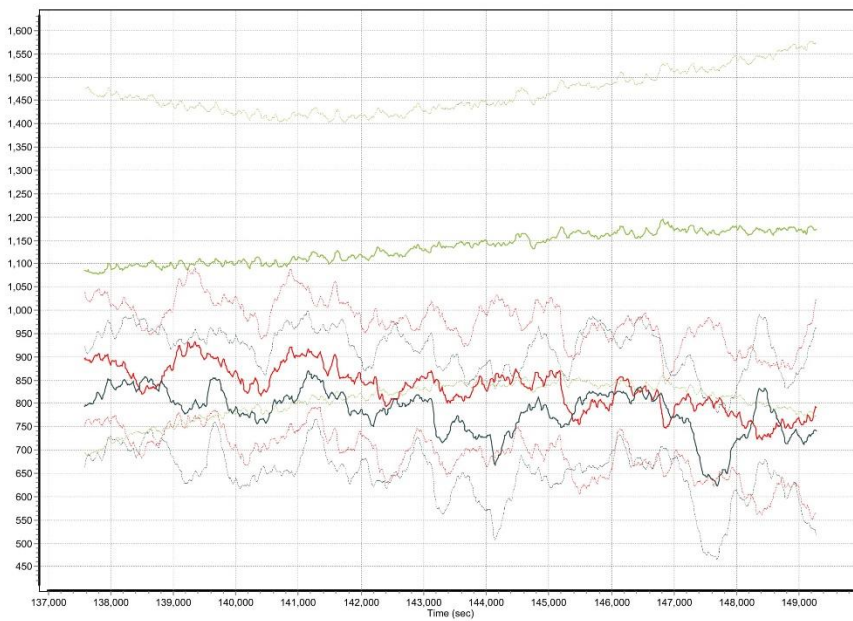
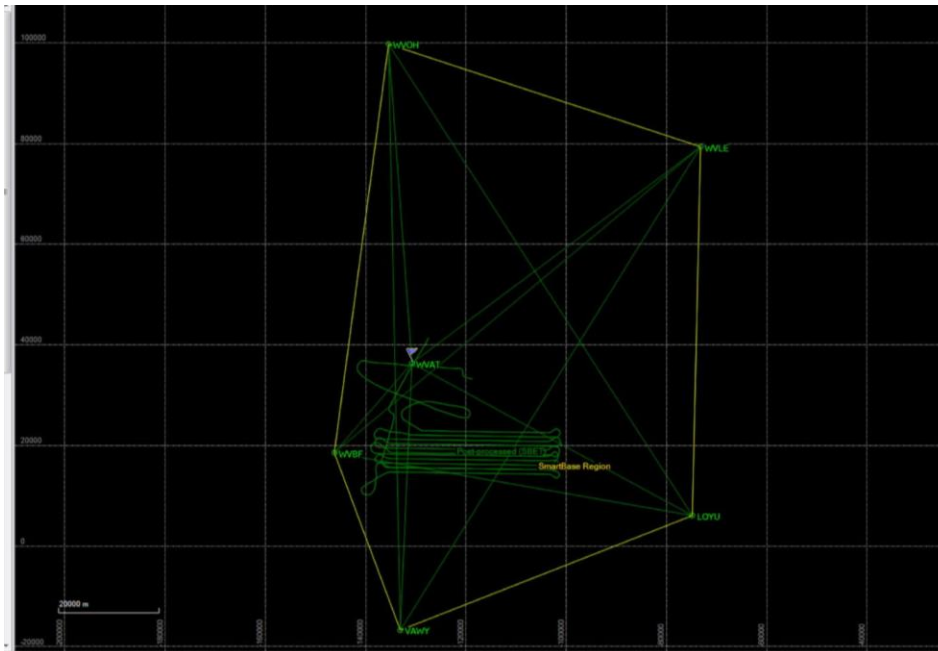
0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = CIA, 7 = GNSS Nav, 8 = DR



— North (m) — East (m) — Down (m) — DR mode

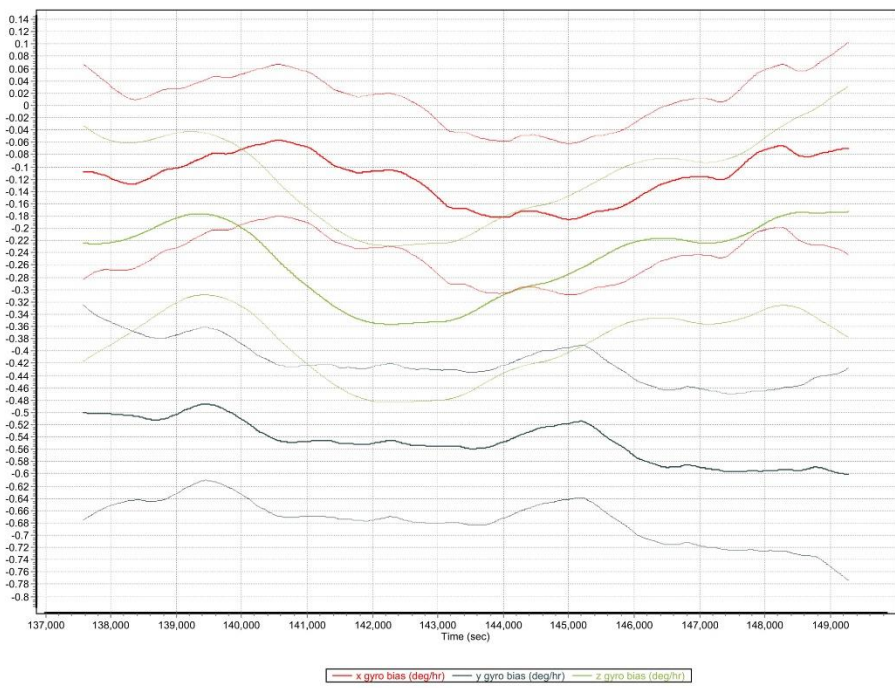
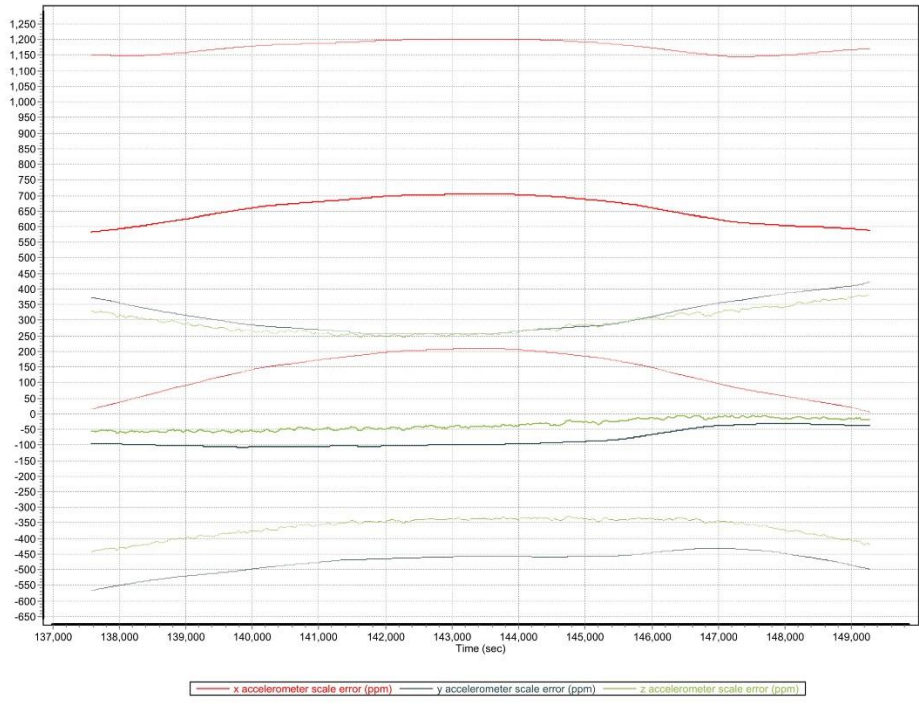


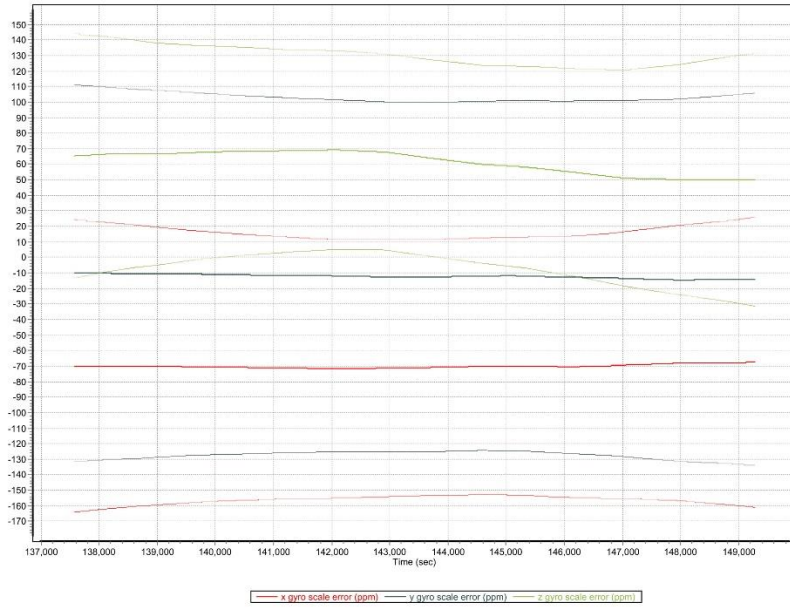
— North Position Error RMS (m) — East Position Error RMS (m) — Down Position Error RMS (m)



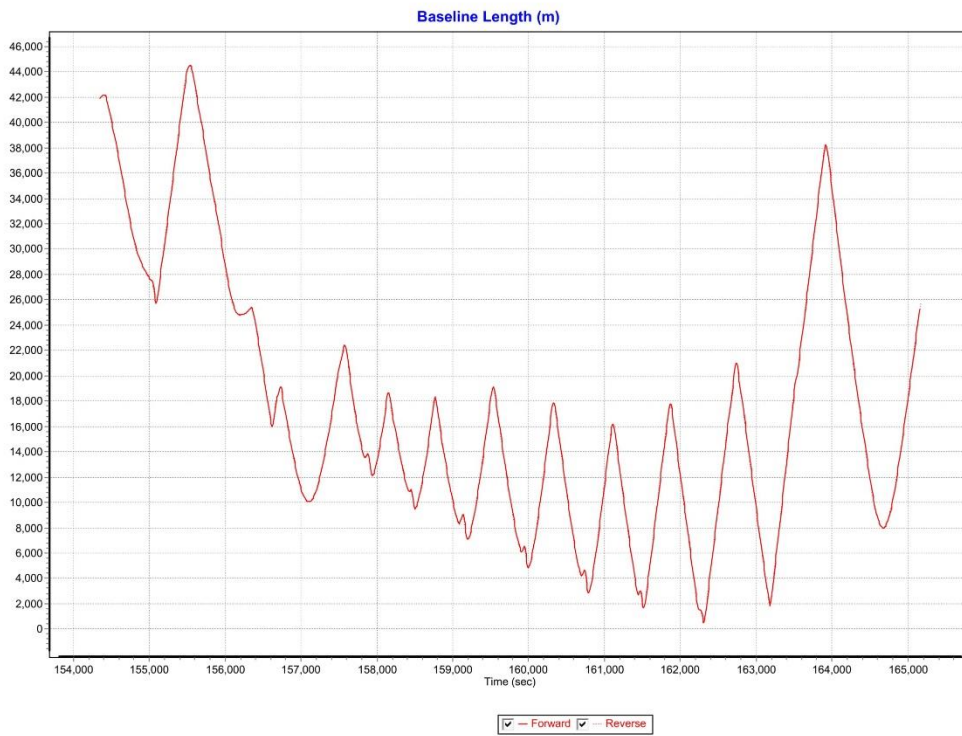
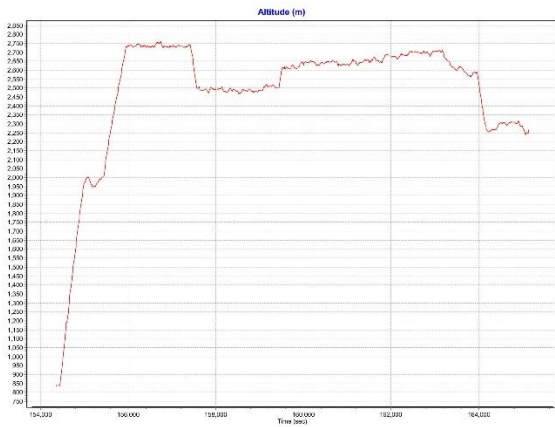
x accelerometer bias (micro-g) y accelerometer bias (micro-g) z accelerometer bias (micro-g)

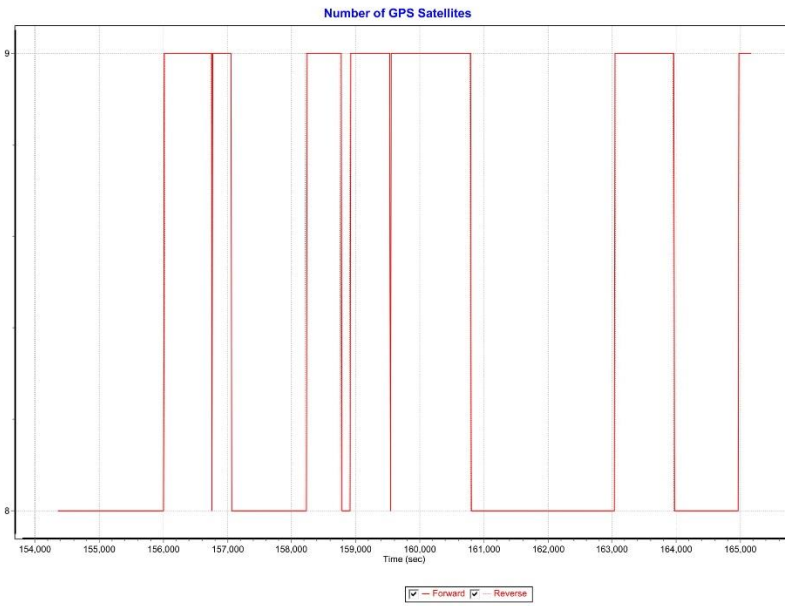
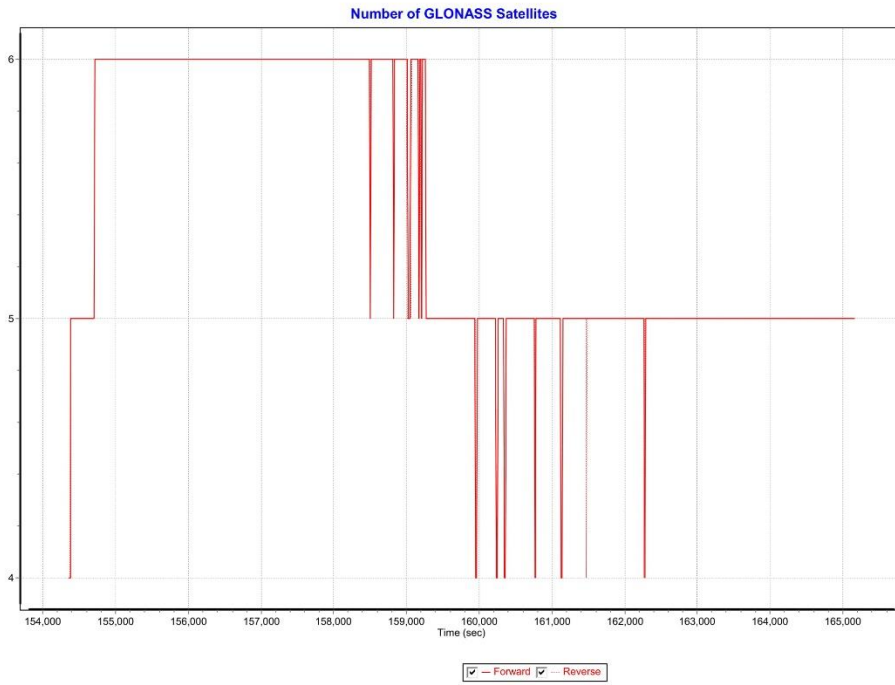




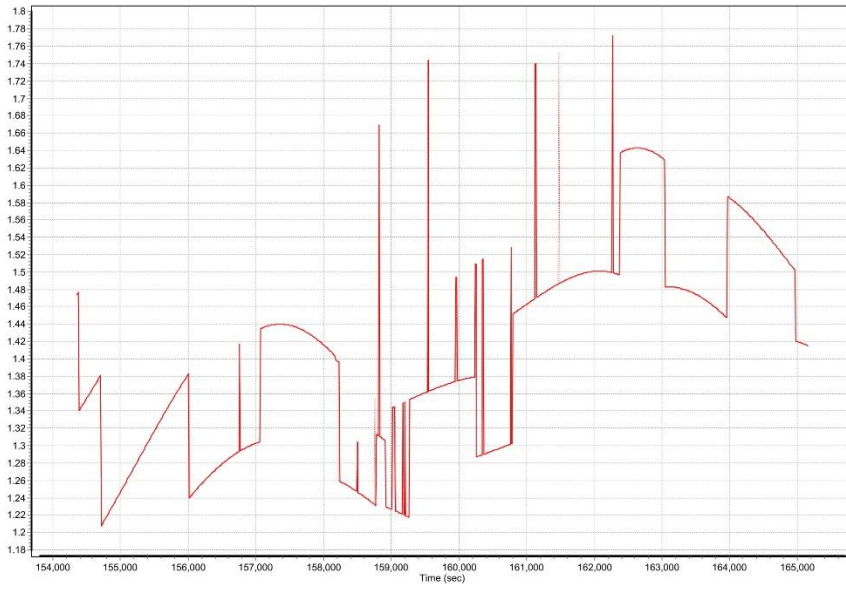


# UNB16312B

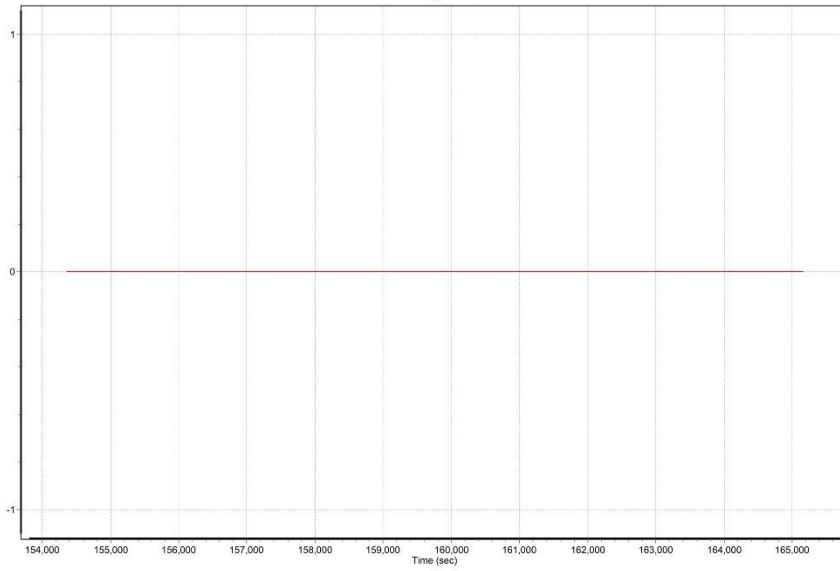




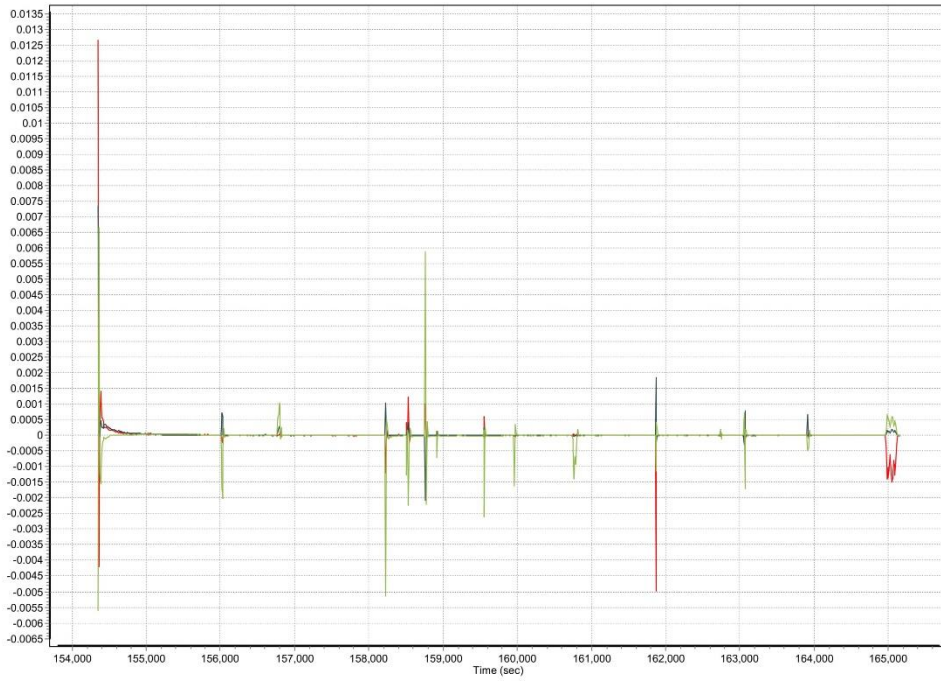
PDOP



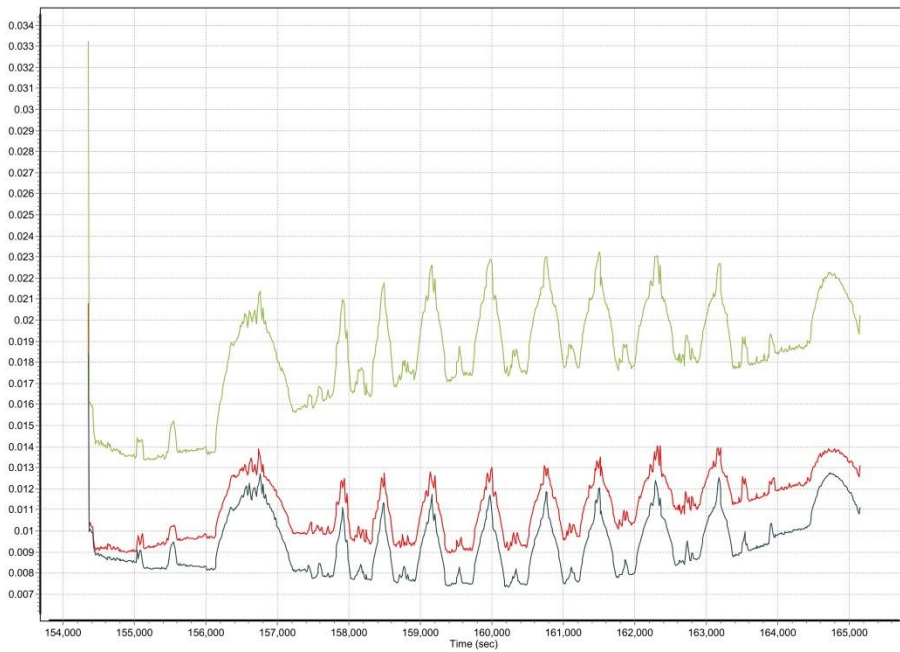
Processing mode



0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = C/A, 7 = GNSS Nav, 8 = DR

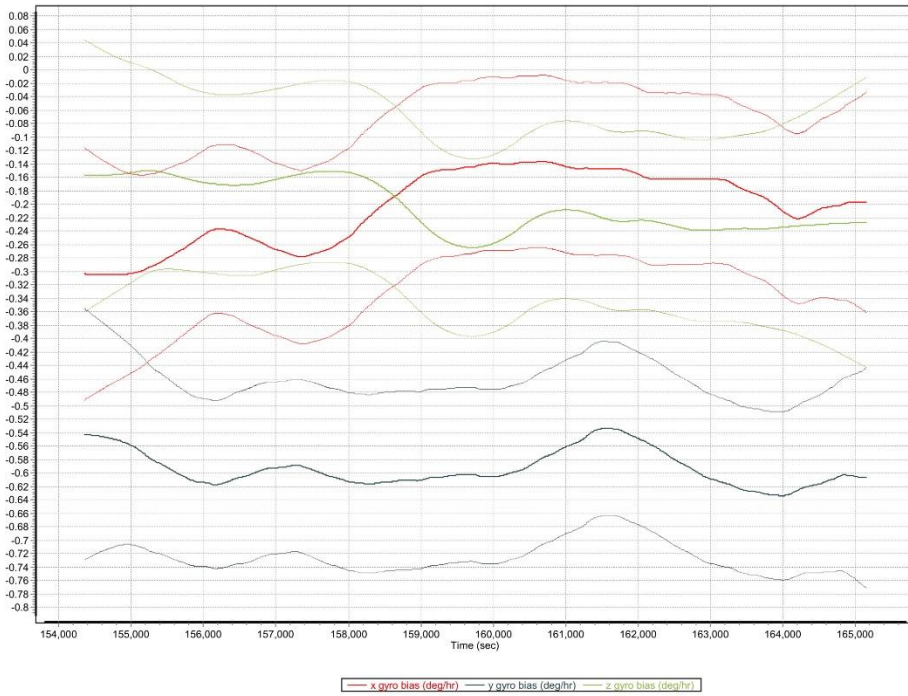
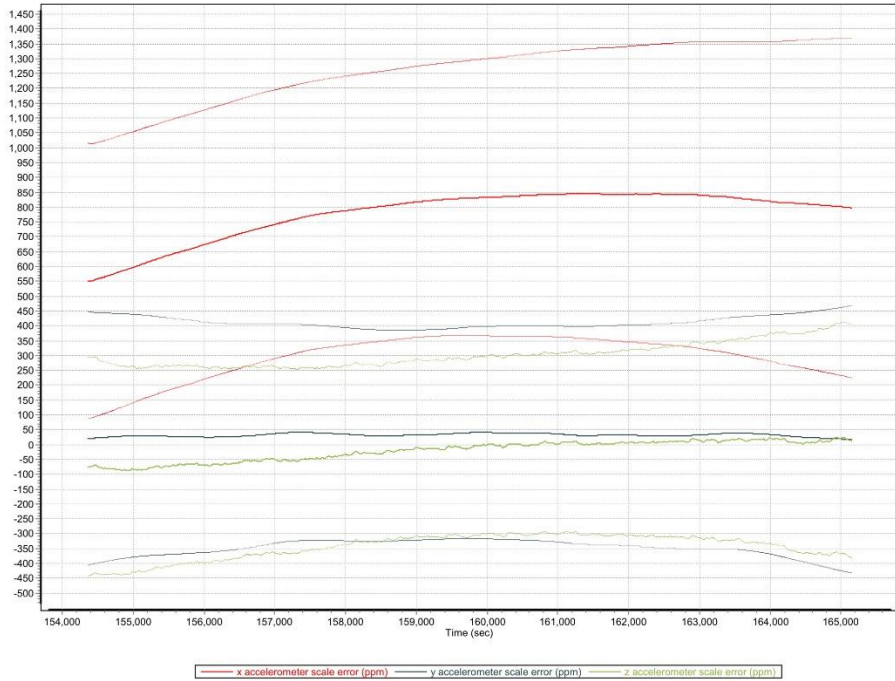


— North (m) — East (m) — Down (m) → DR mode

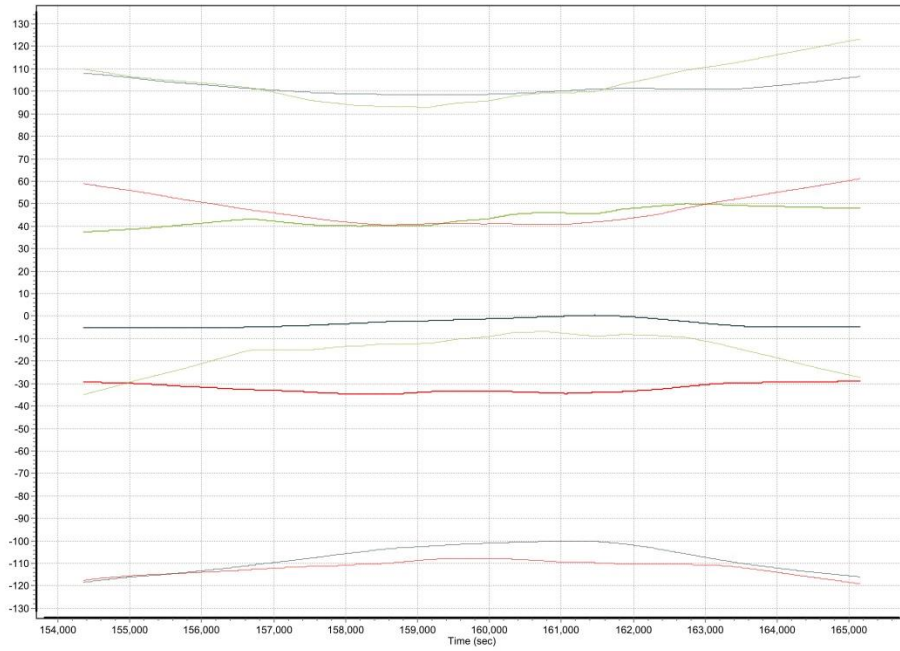


— North Position Error RMS (m) — East Position Error RMS (m) — Down Position Error RMS (m)



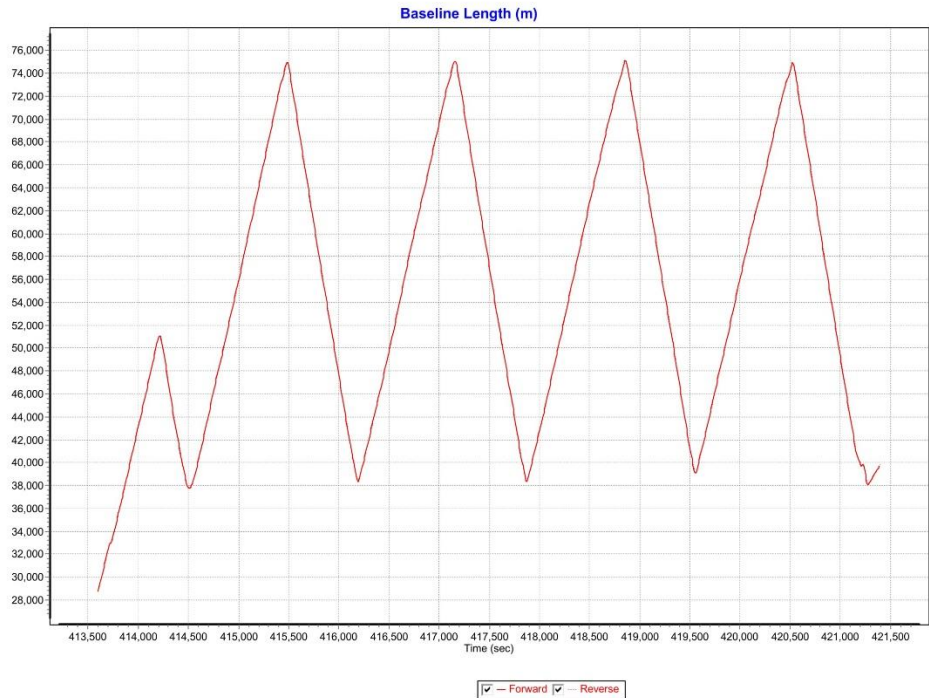
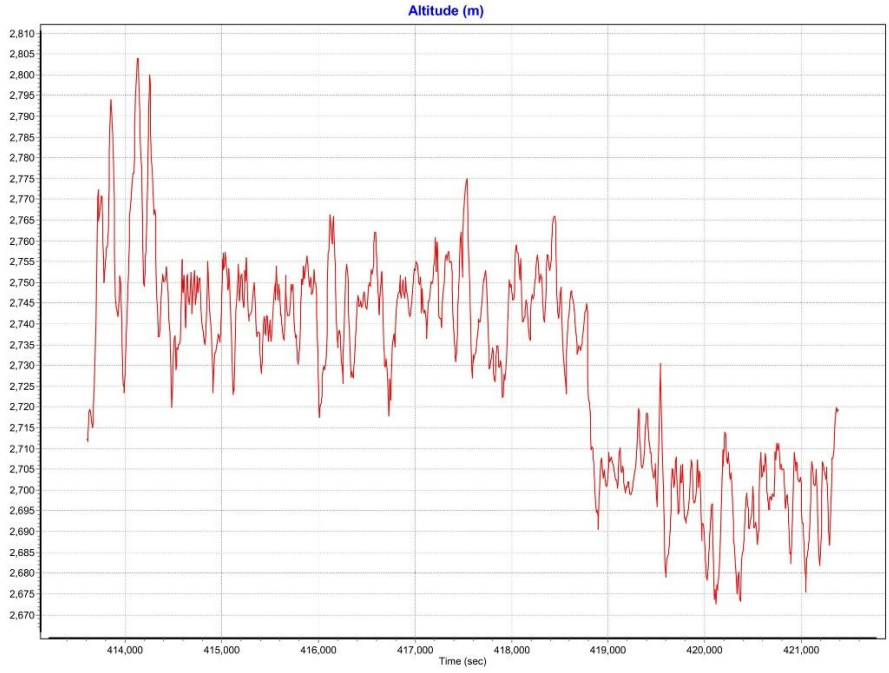




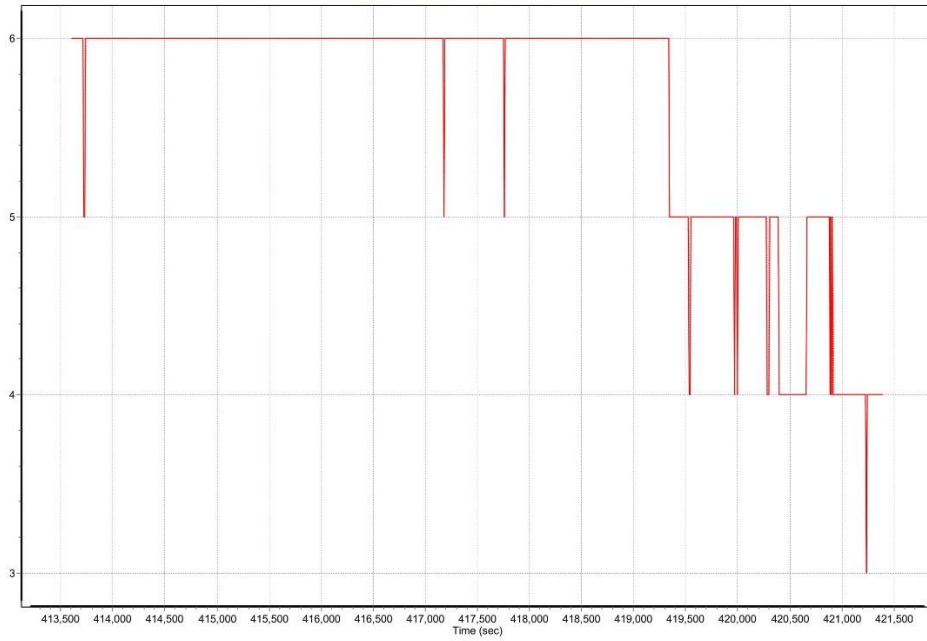


x gyro scale error (ppm) y gyro scale error (ppm) z gyro scale error (ppm)

# UNB16315A

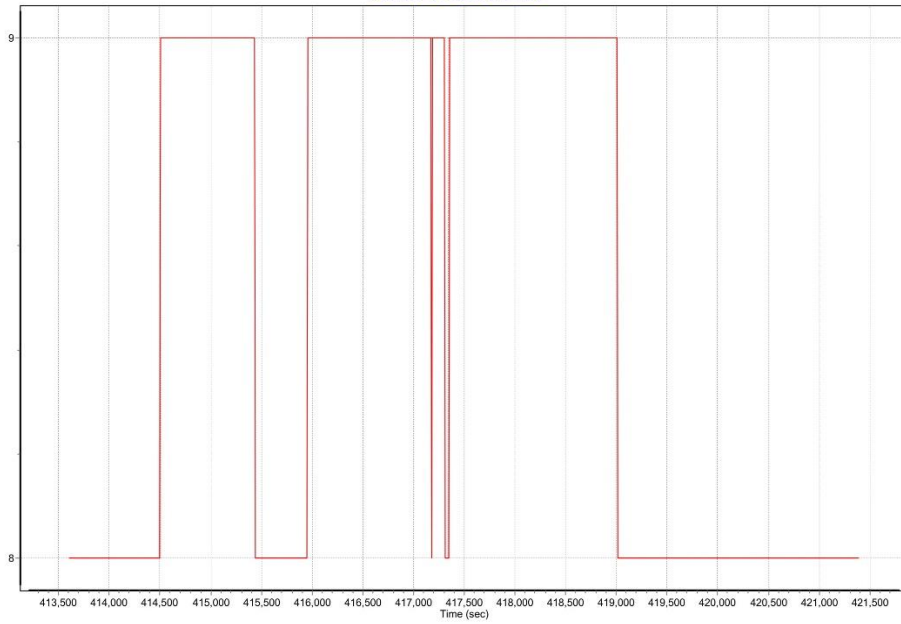


Number of GLONASS Satellites



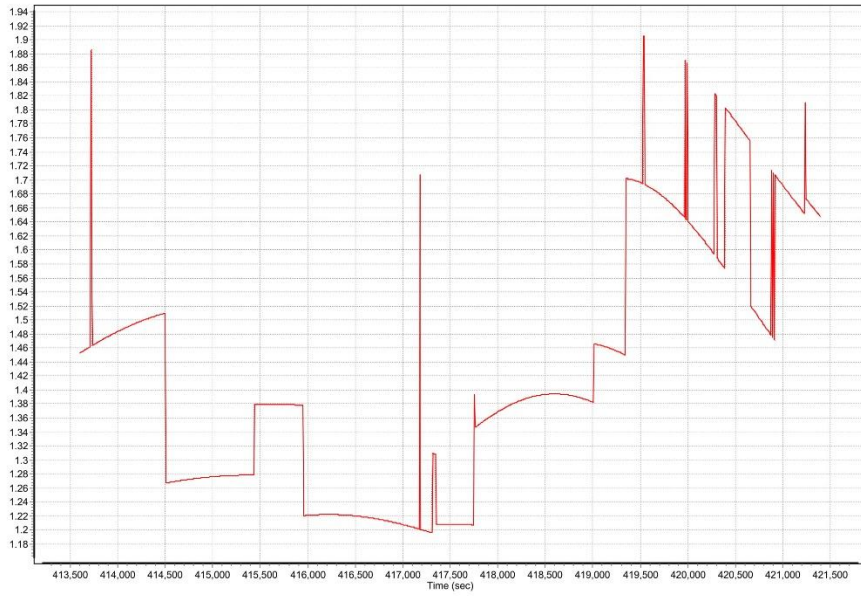
Forward  Reverse

Number of GPS Satellites



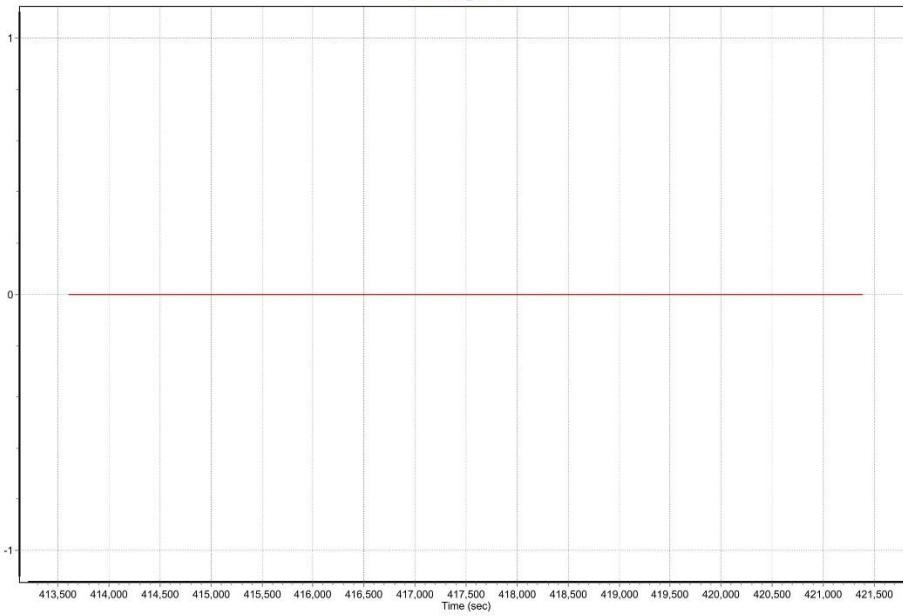
Forward  Reverse

PDOP



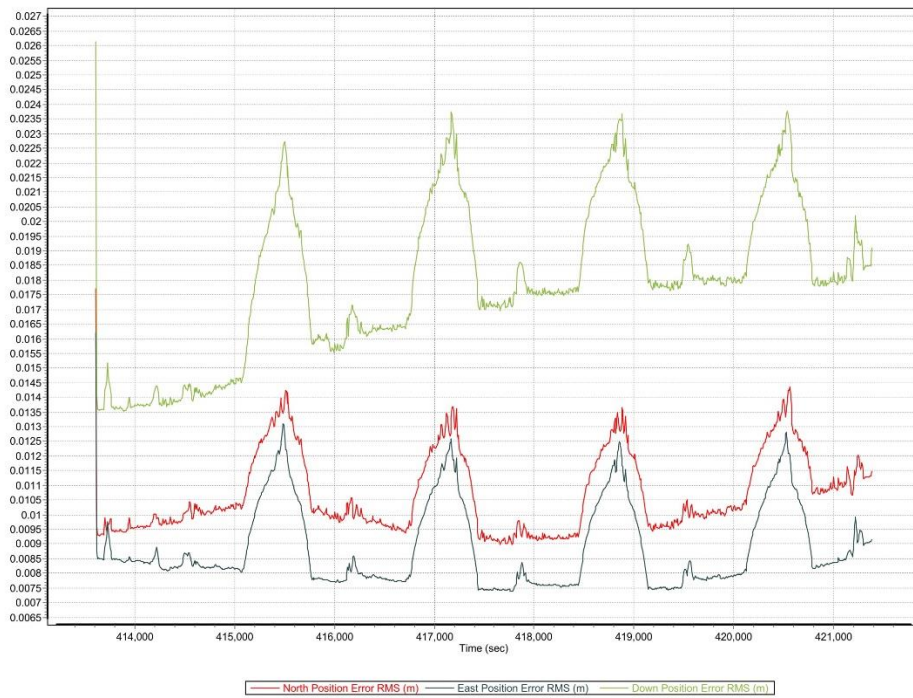
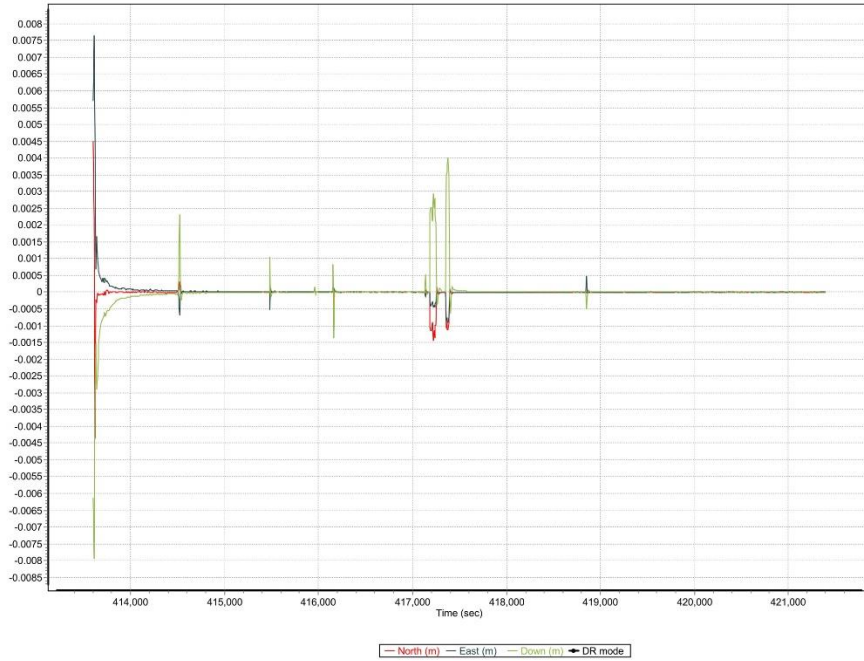
Forward  Reverse

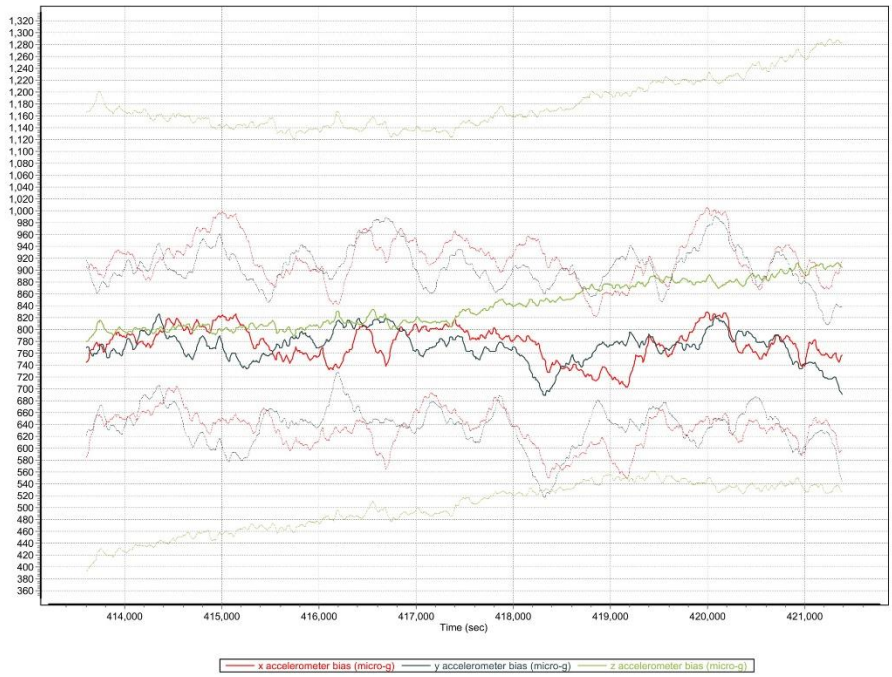
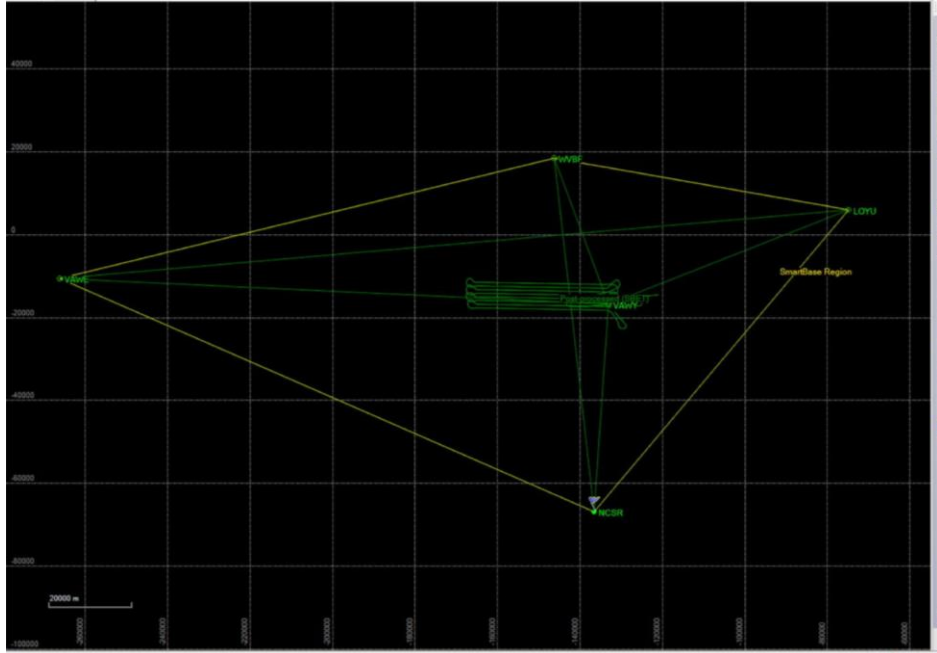
Processing mode

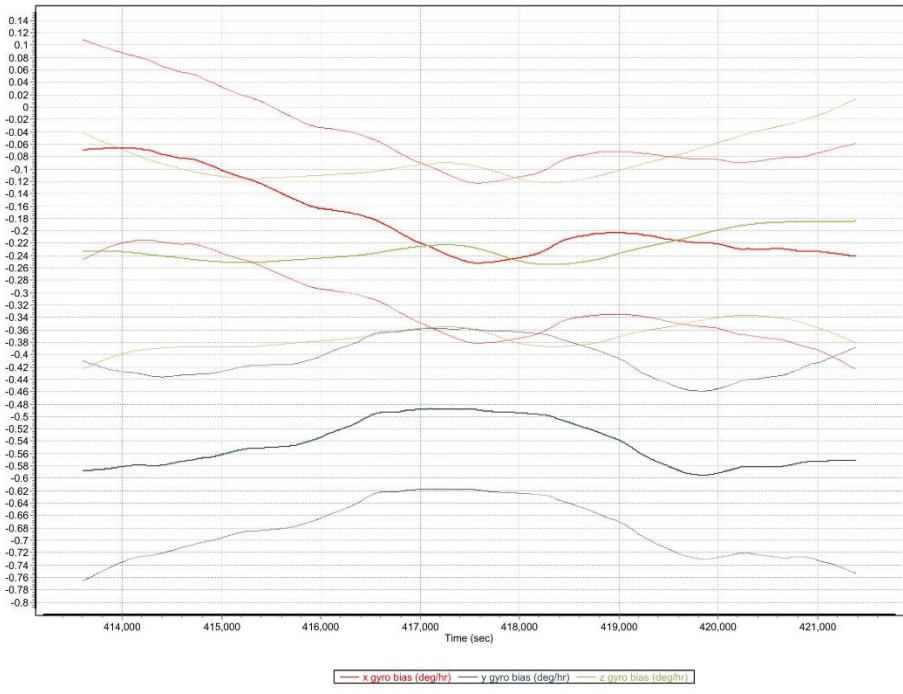
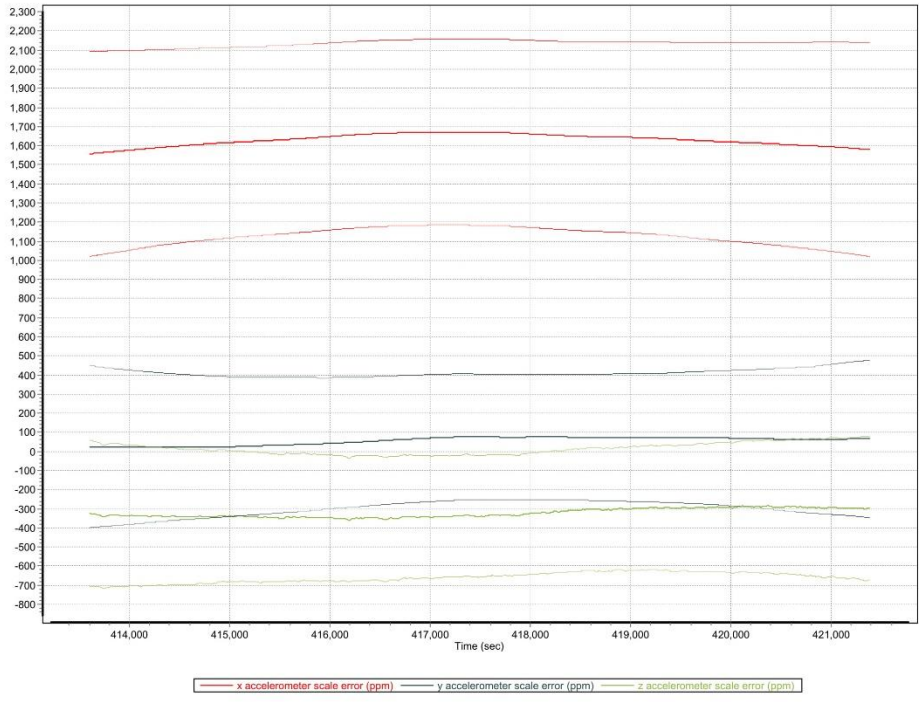


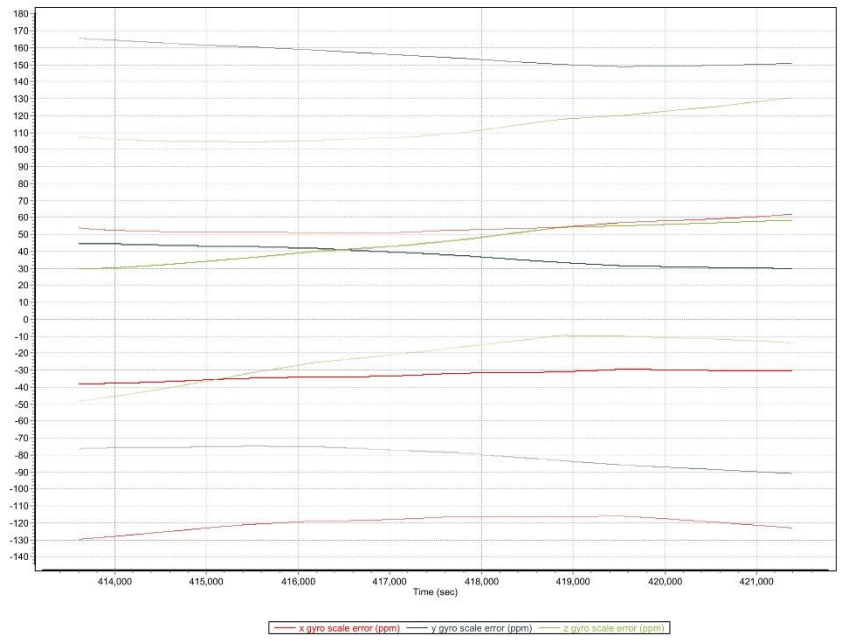
Forward  Reverse

0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = C/A, 7 = GNSS Nav, 8 = DR



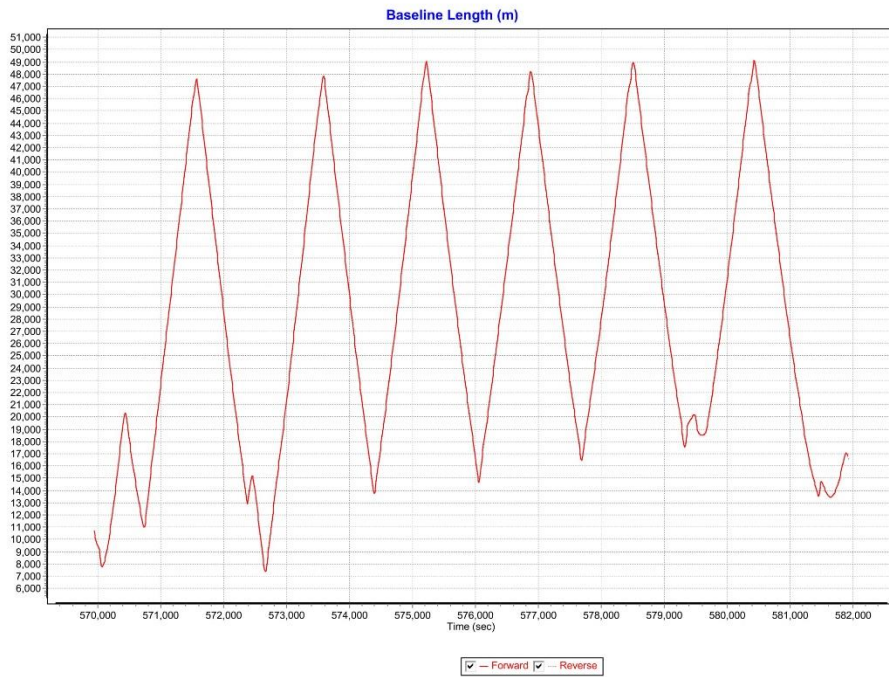
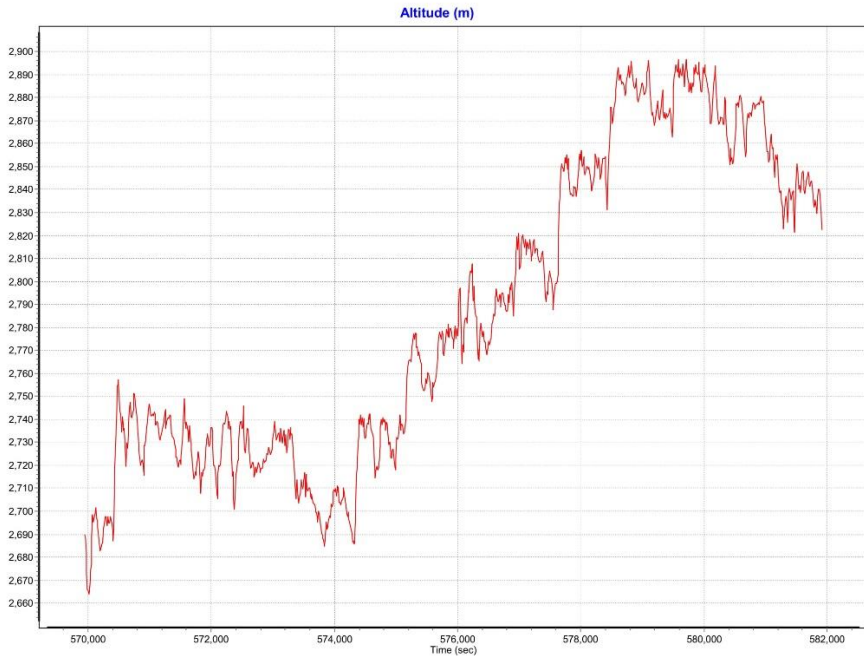




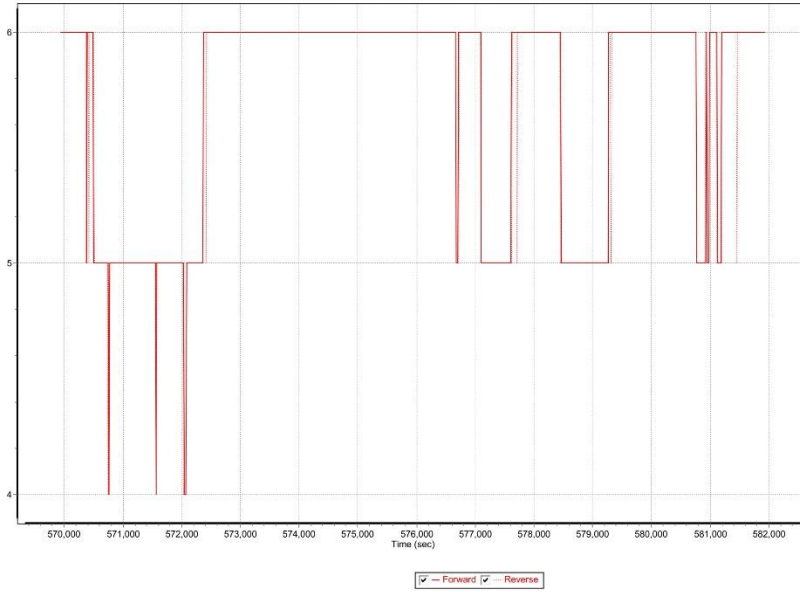




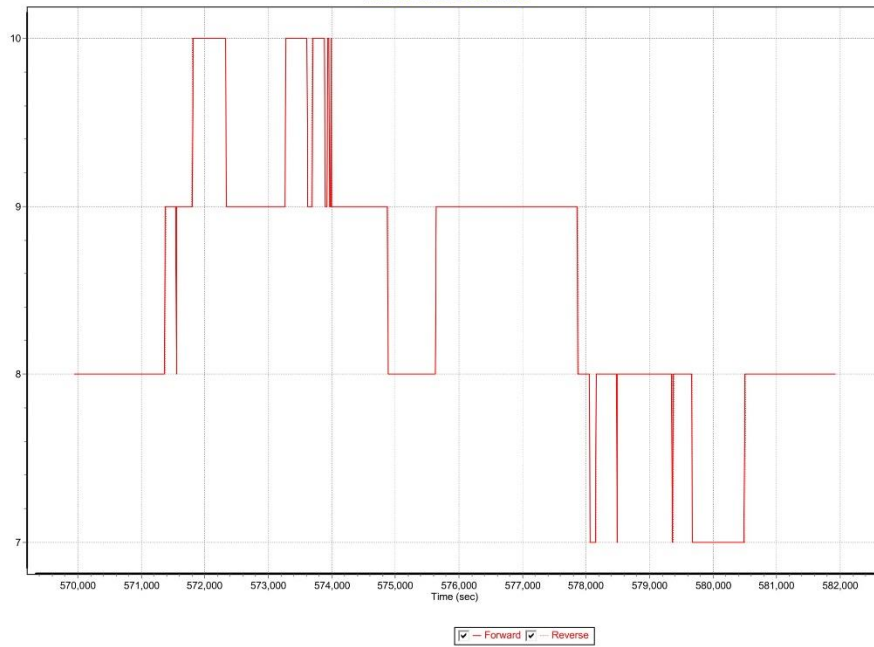
# UNB16317A

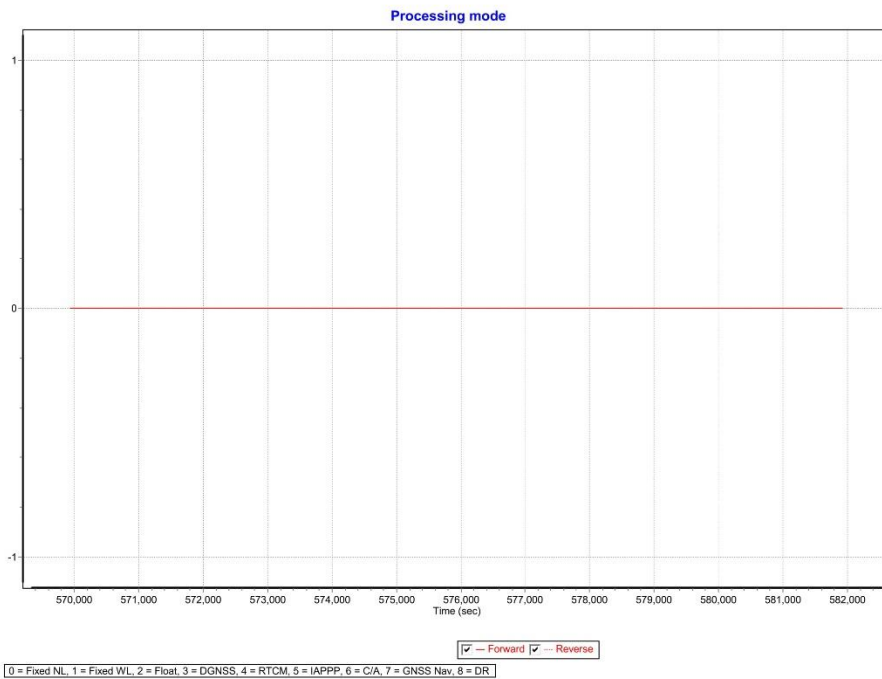
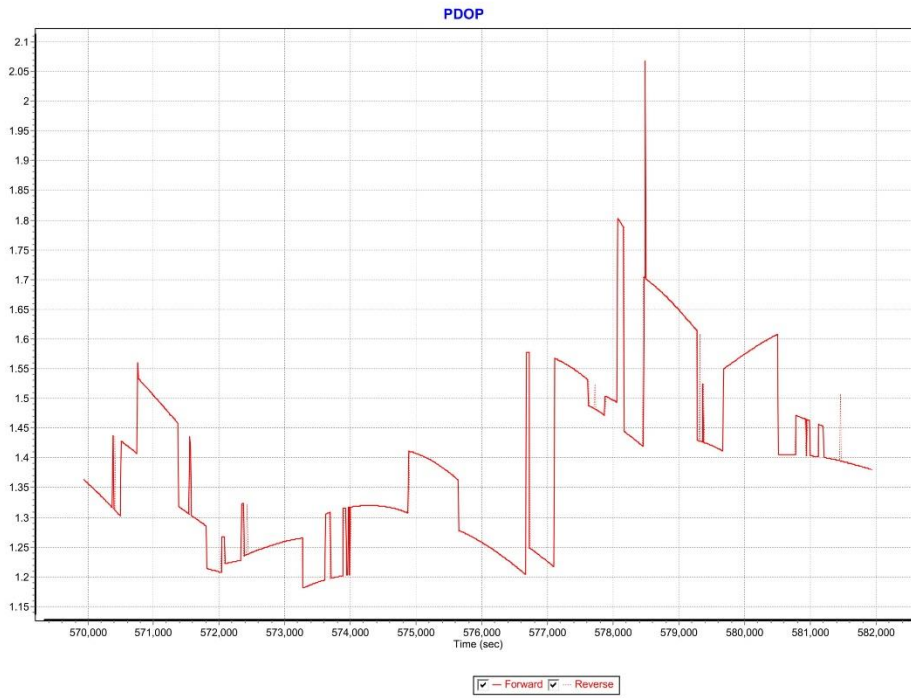


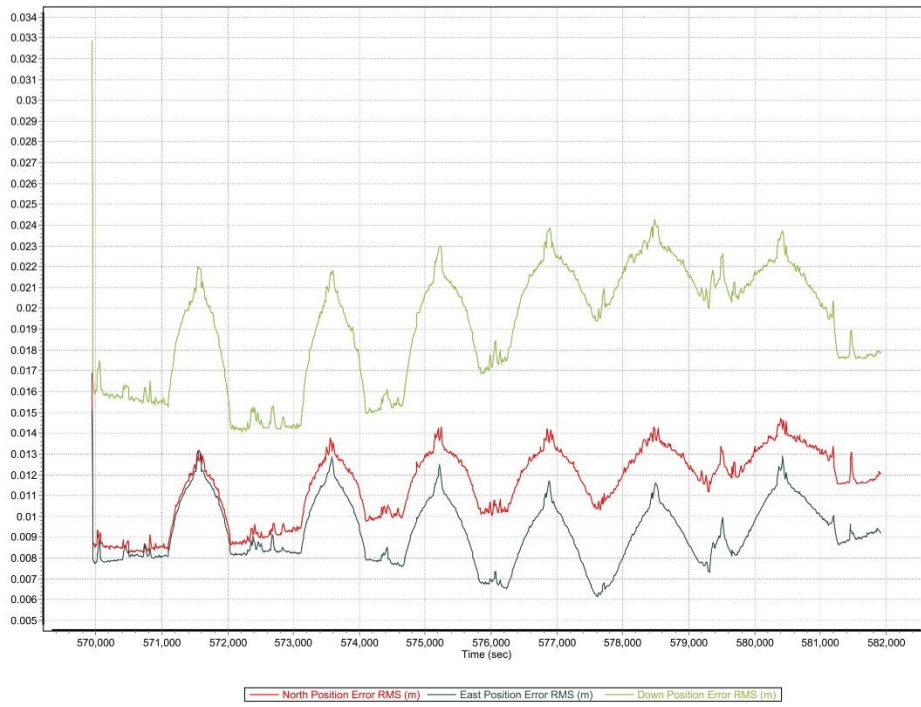
Number of GLONASS Satellites

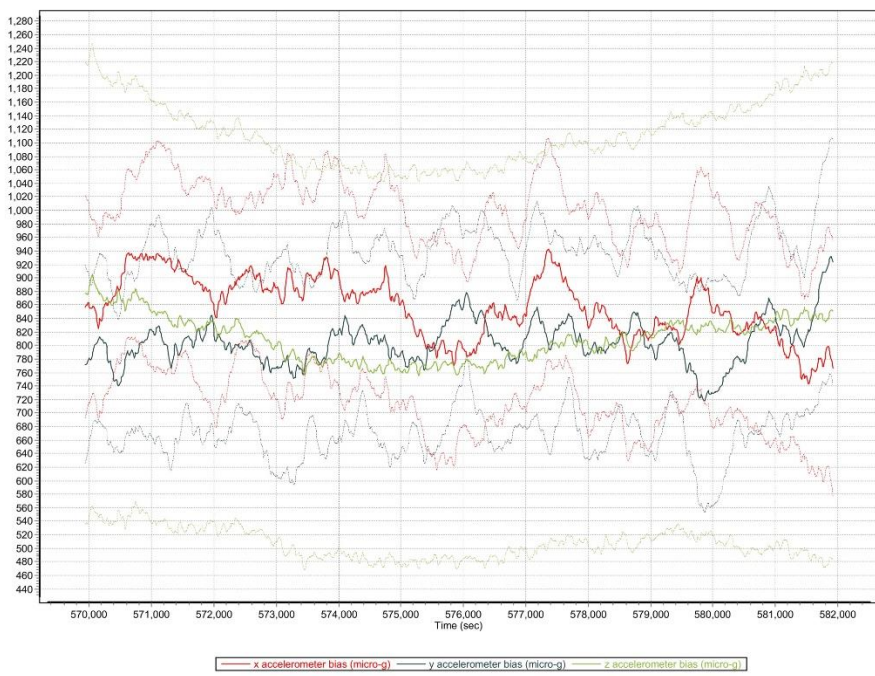
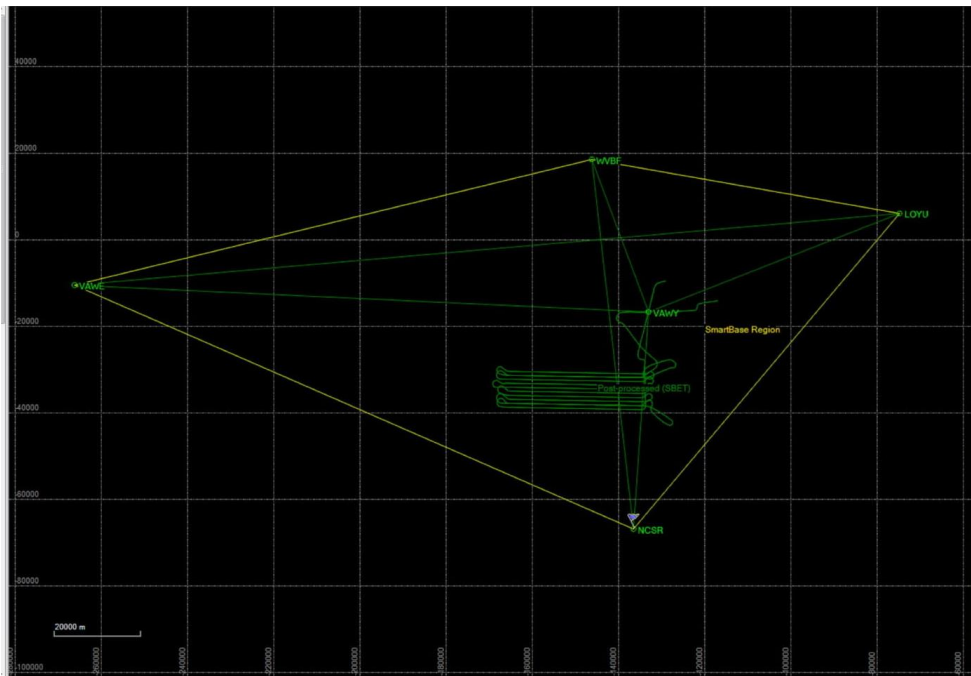


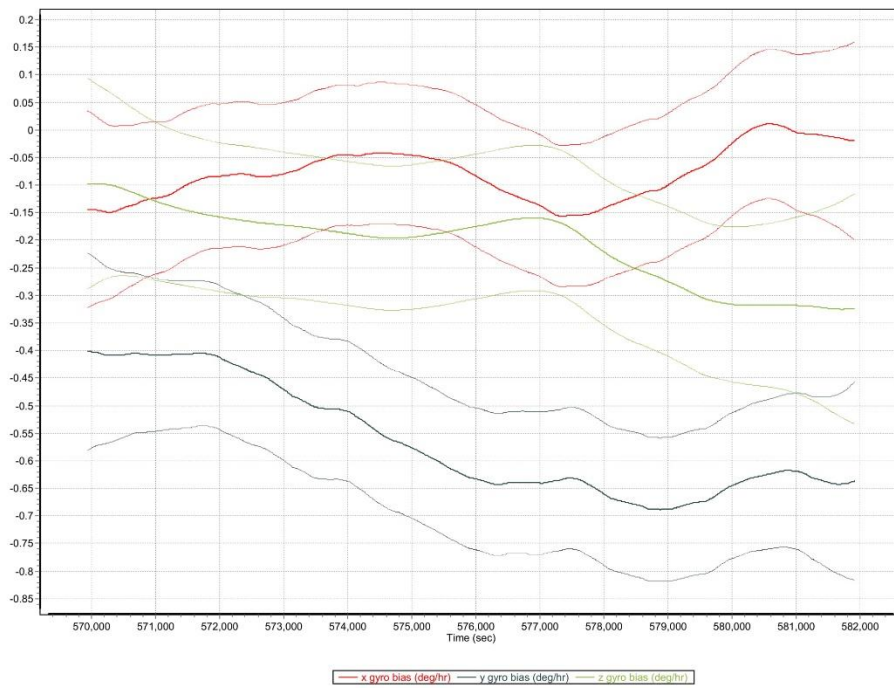
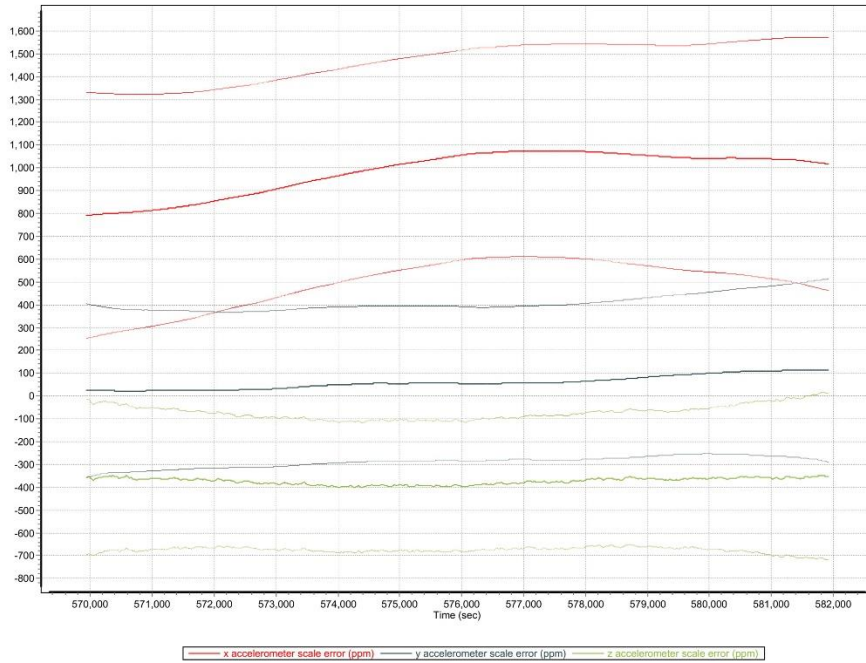
Number of GPS Satellites

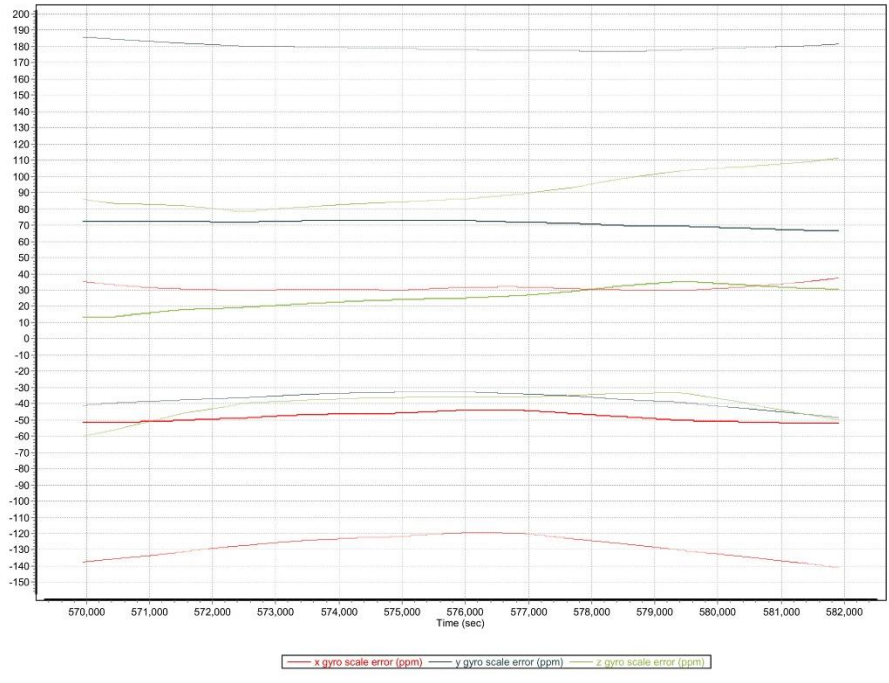




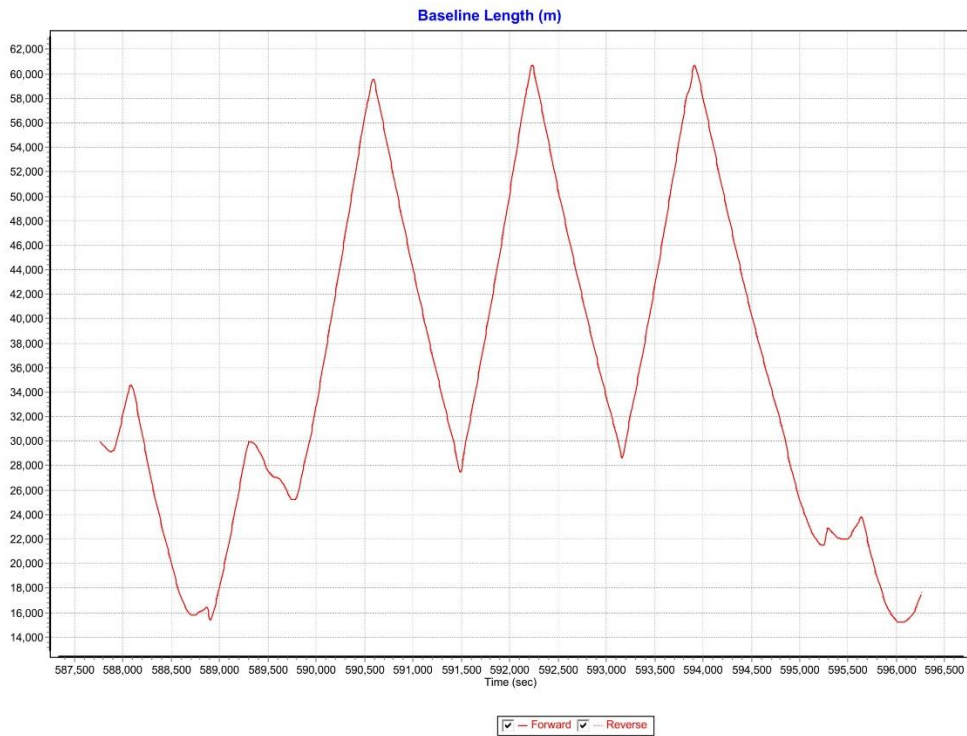
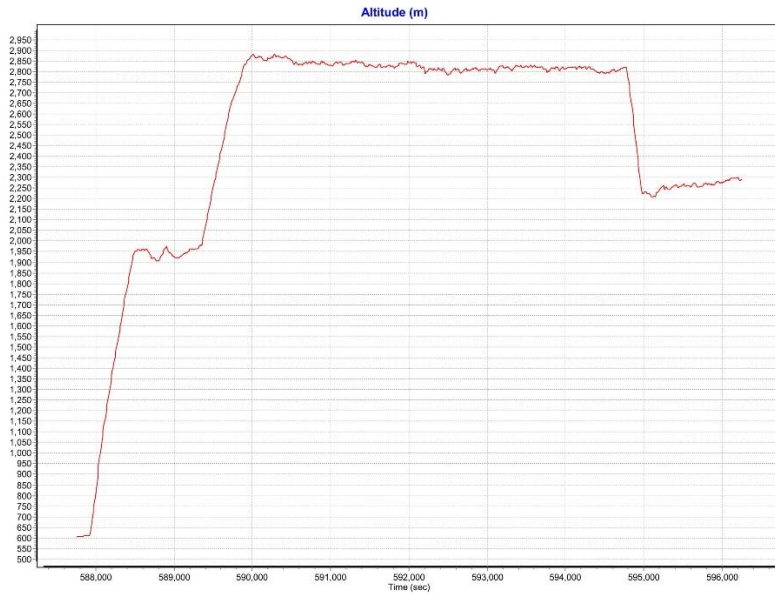






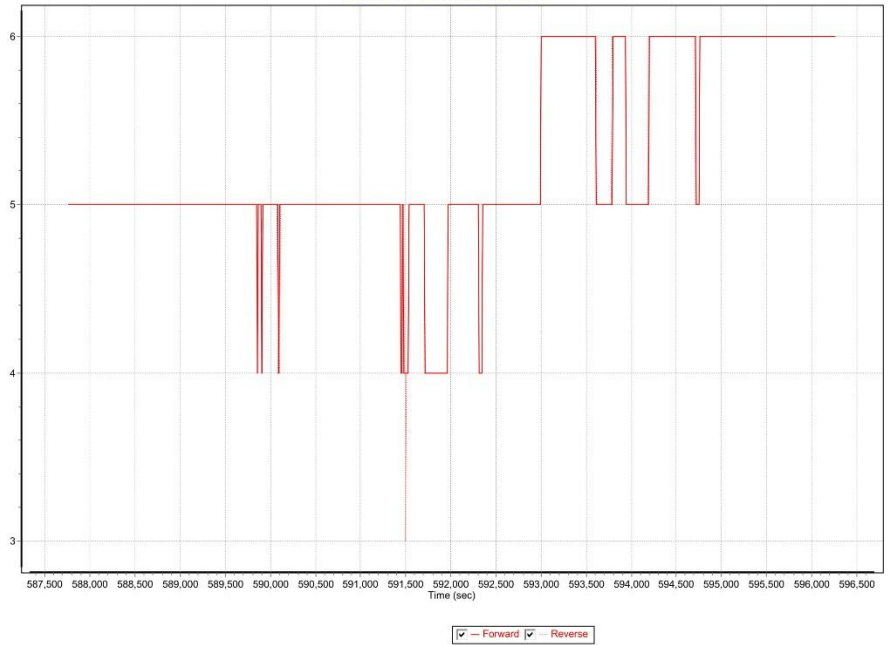


# UNB16317B

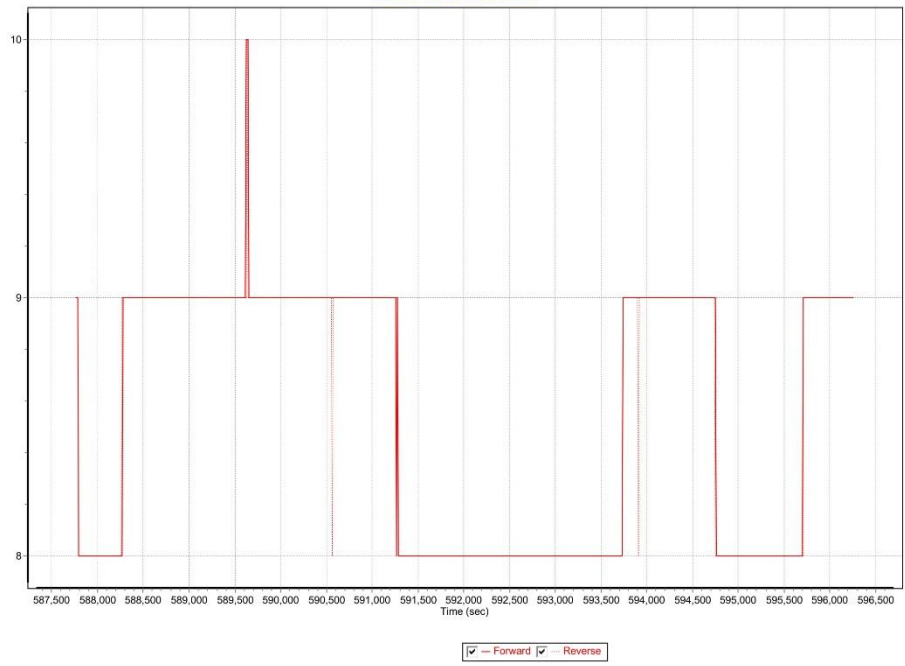




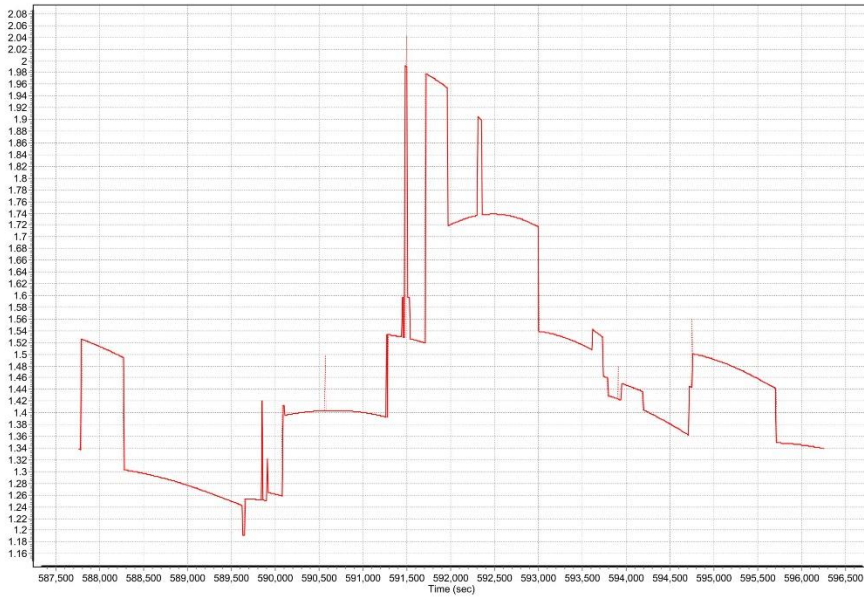
Number of GLONASS Satellites



Number of GPS Satellites

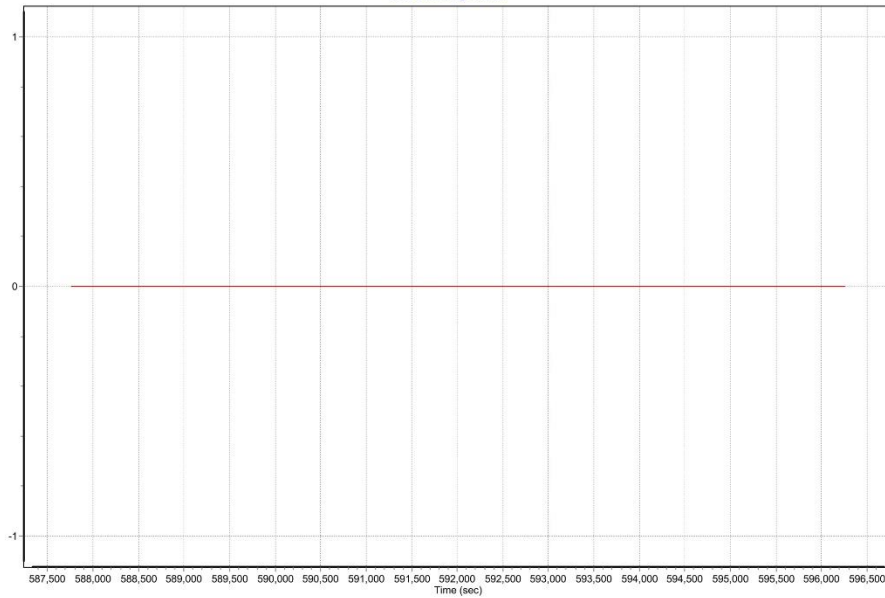


### PDOP



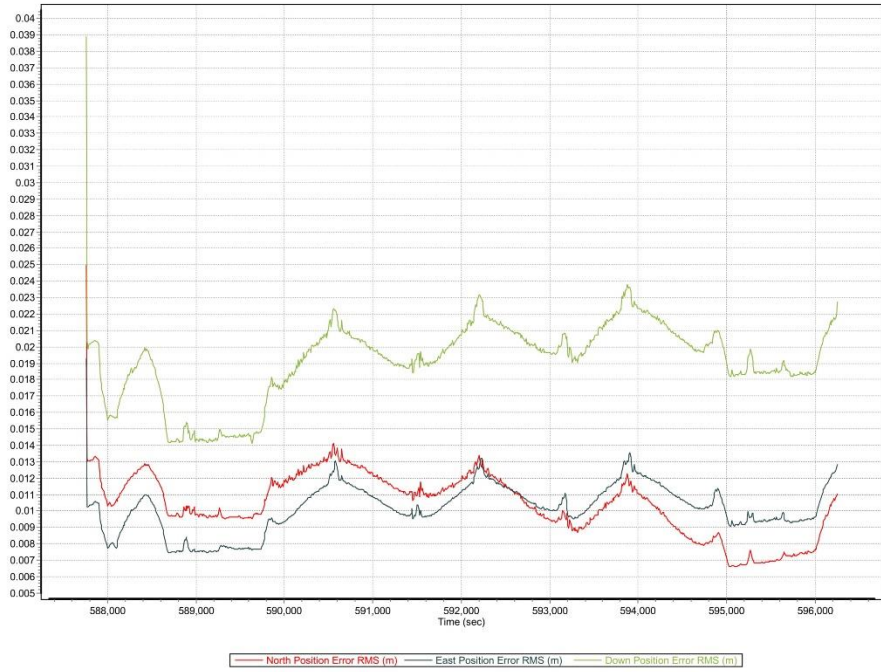
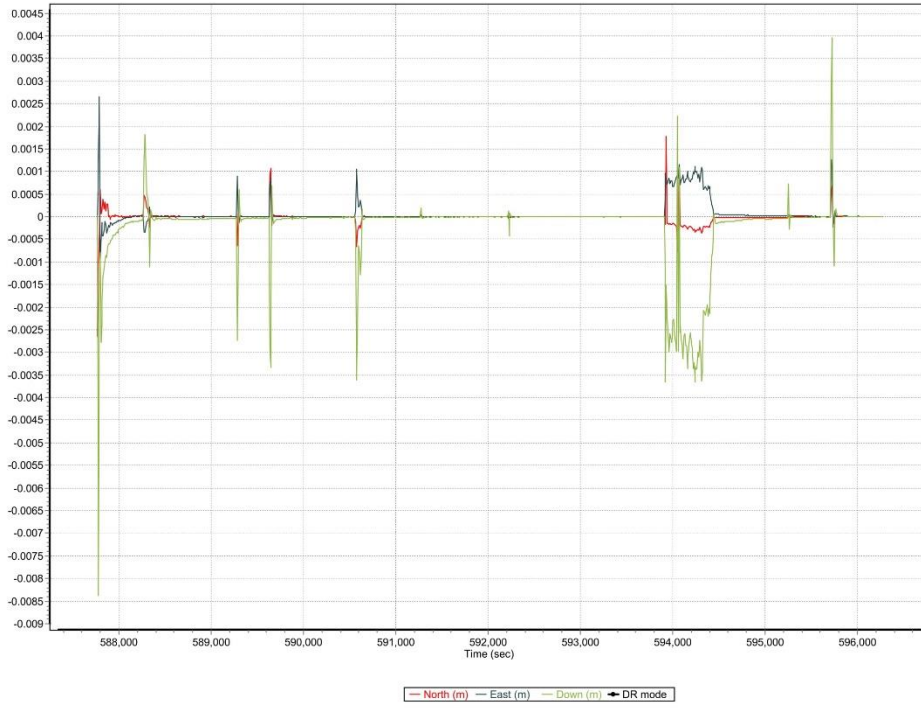
Forward  Reverse

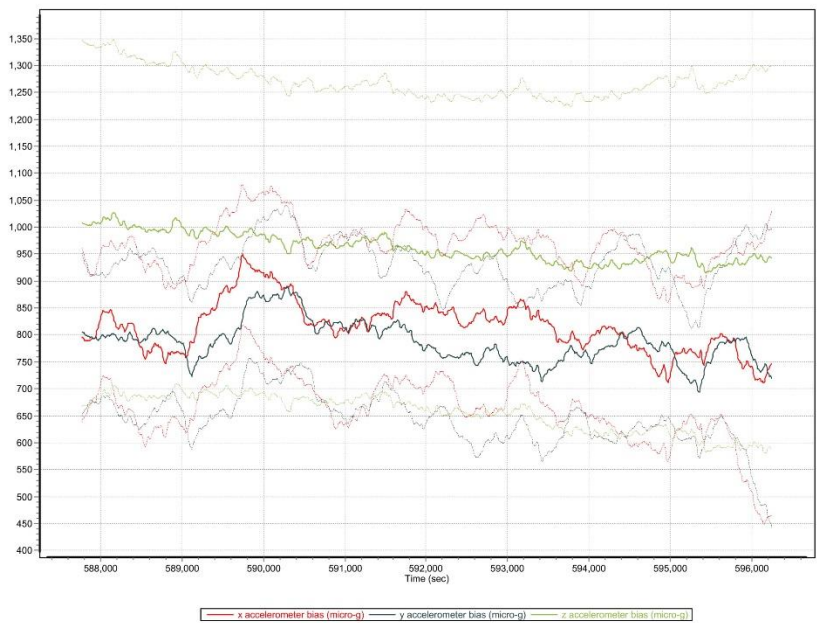
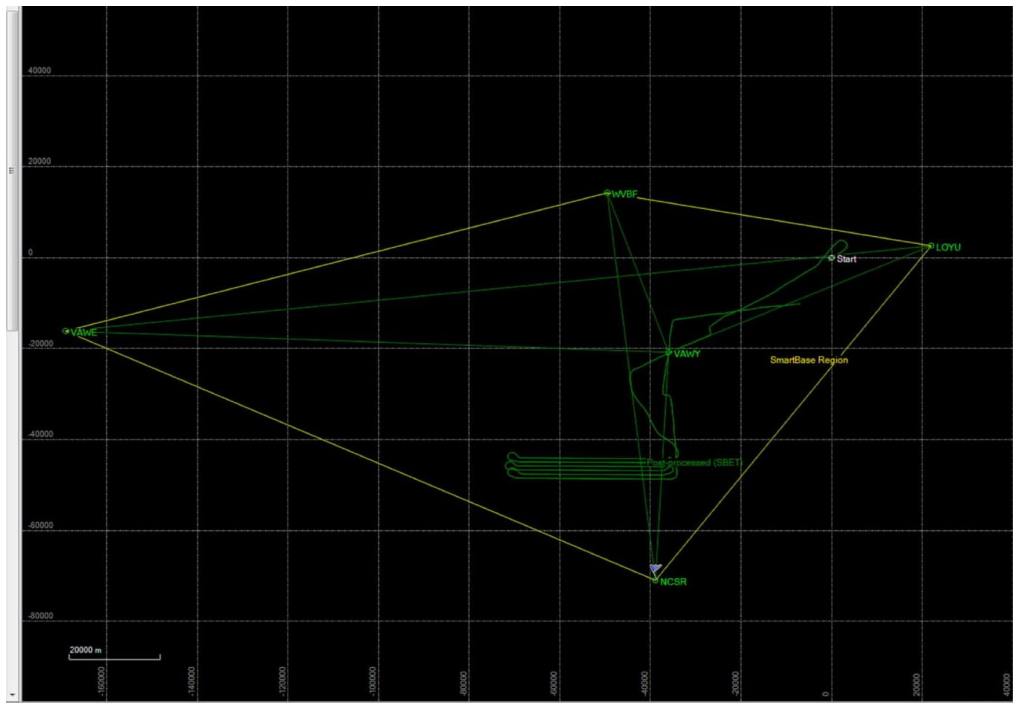
### Processing mode

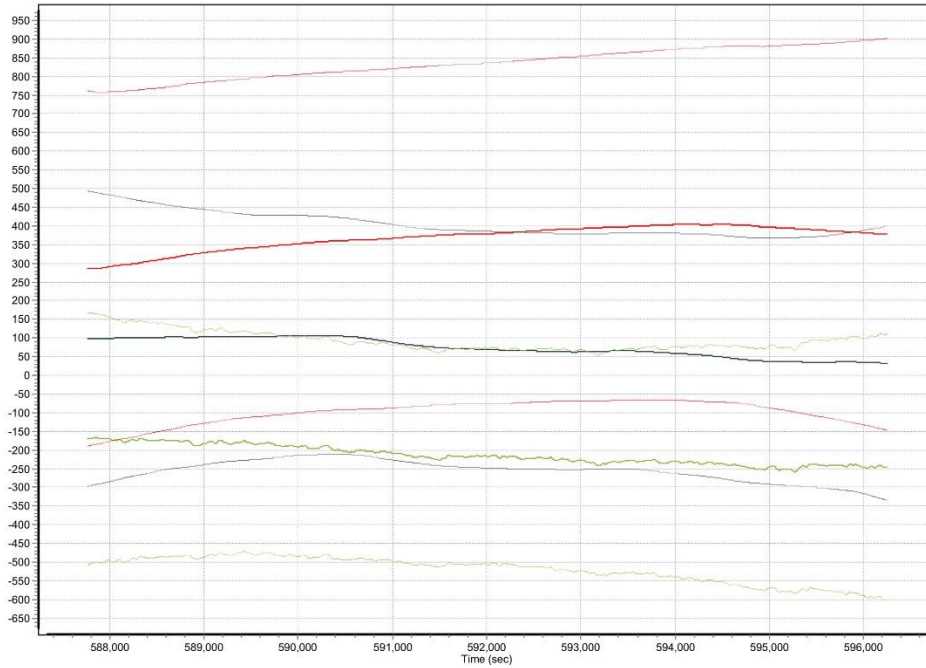


Forward  Reverse

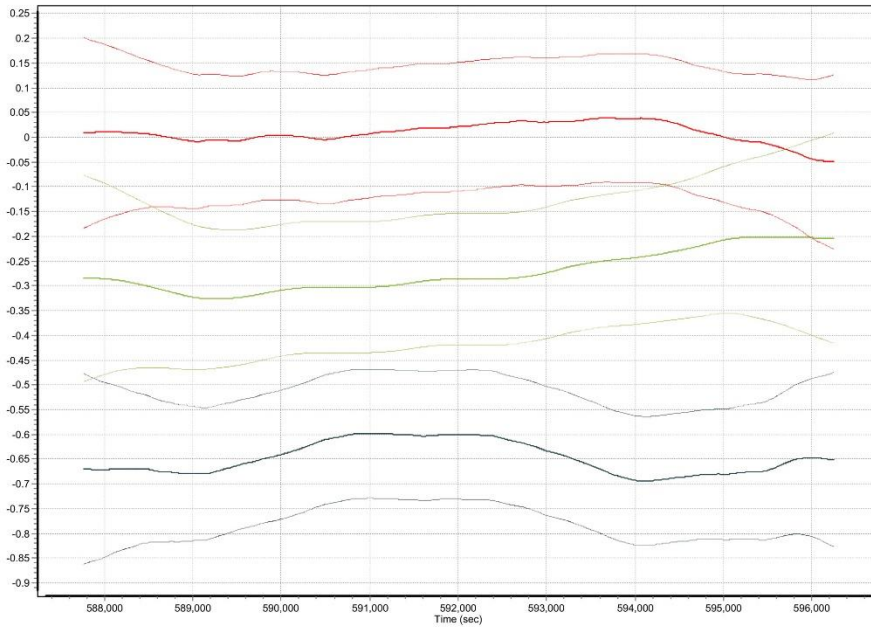
0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNS, 4 = RTCM, 5 = IAPPP, 6 = C/A, 7 = GNSS Nav, 8 = DR



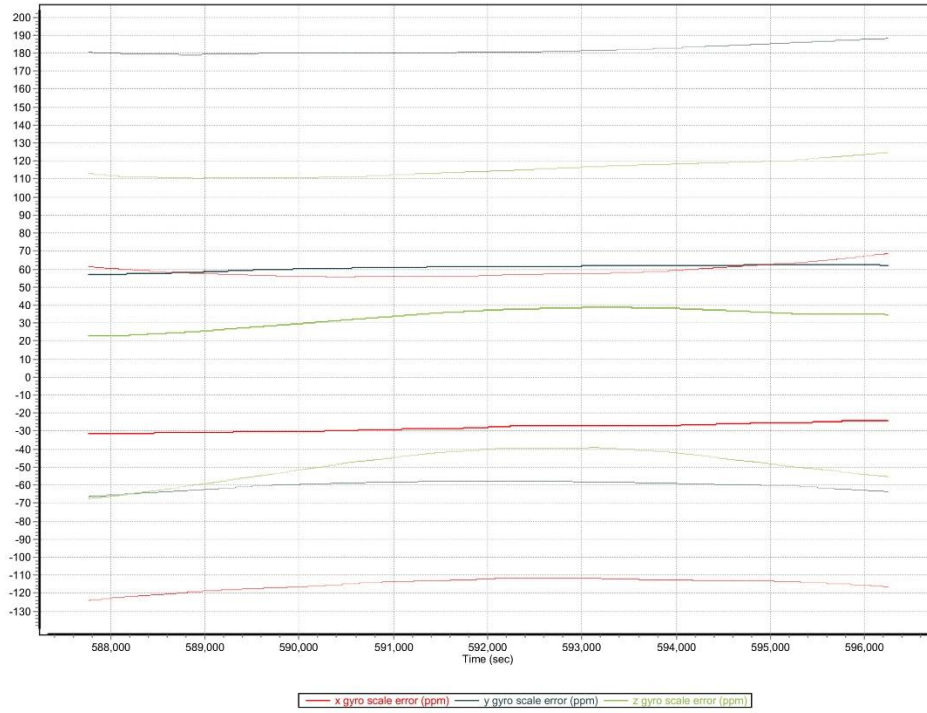




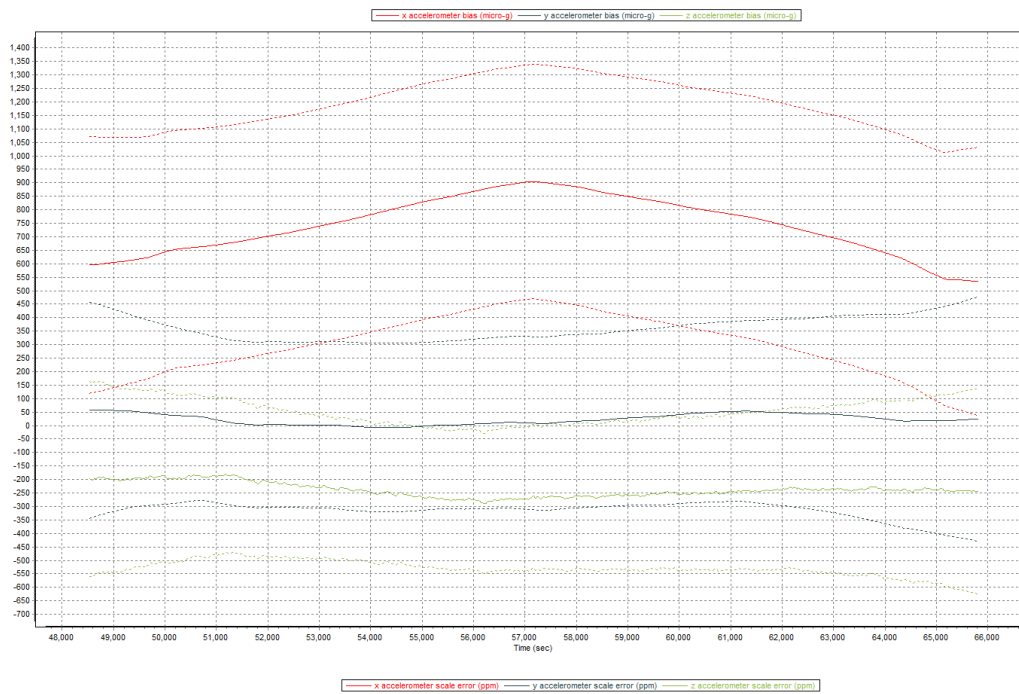
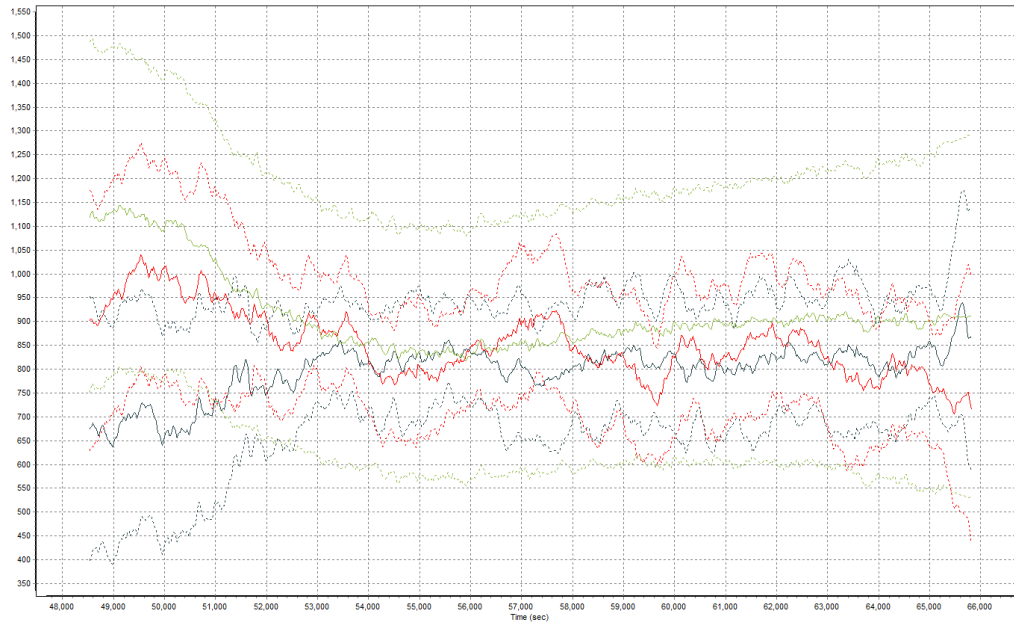
— x accelerometer scale error (ppm) — y accelerometer scale error (ppm) — z accelerometer scale error (ppm)

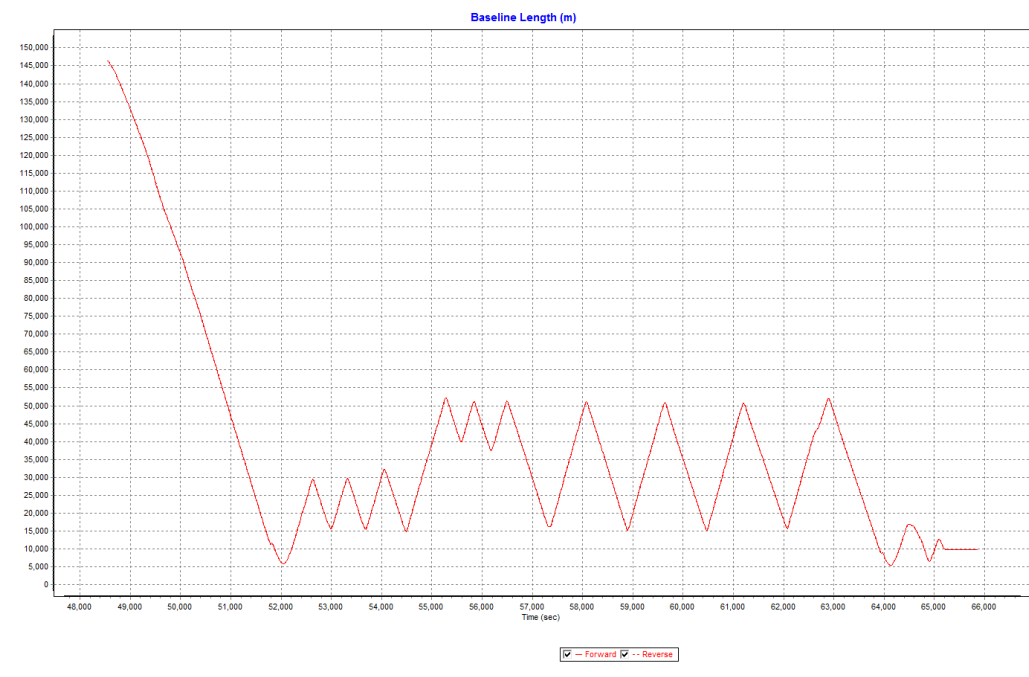


— x gyro bias (deg/hr) — y gyro bias (deg/hr) — z gyro bias (deg/hr)



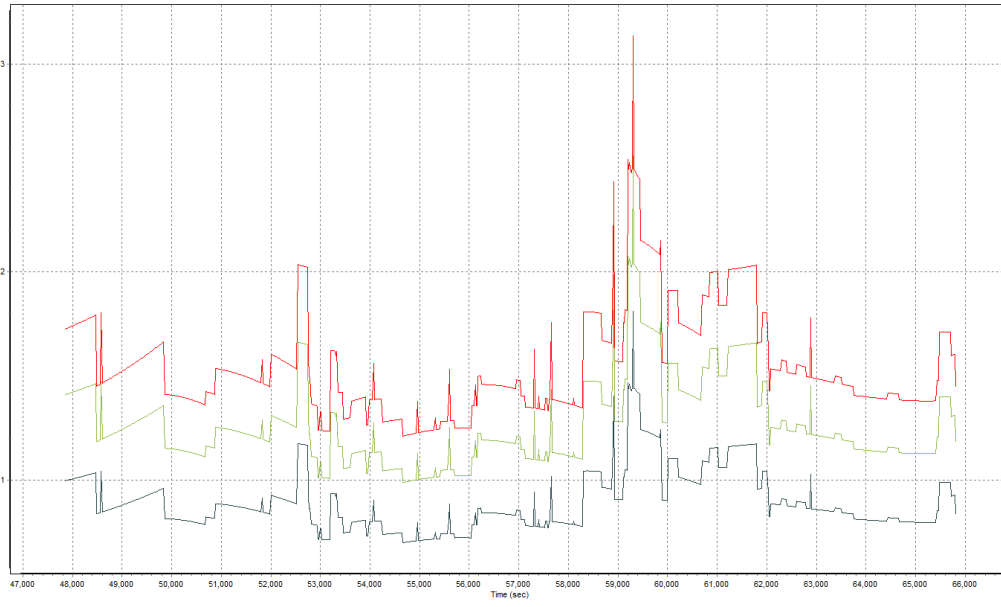
# UNB16318A





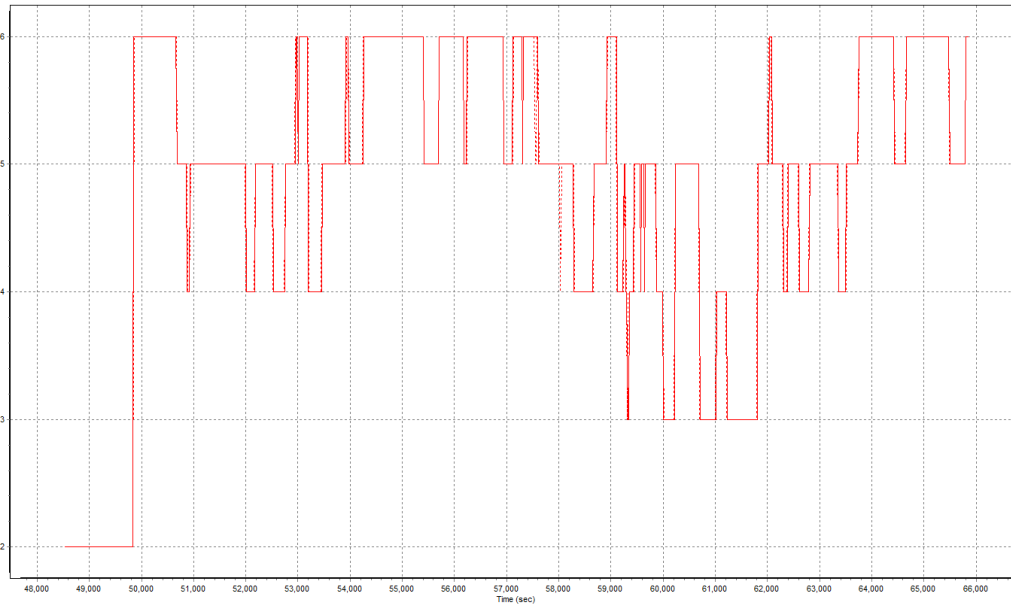


DOP



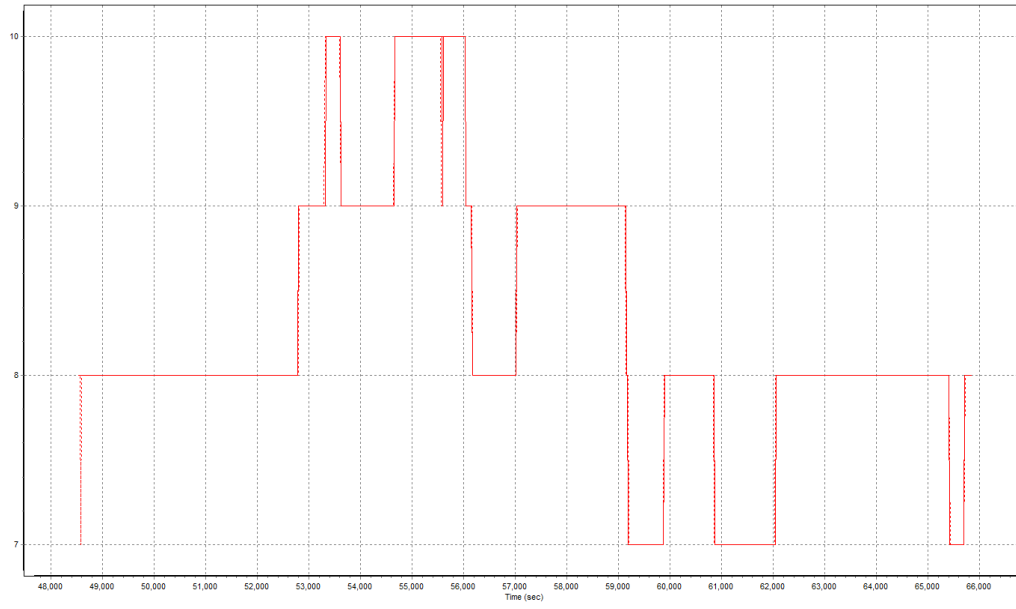
— PDOP — HDOP — VDOP

Number of GLONASS Satellites

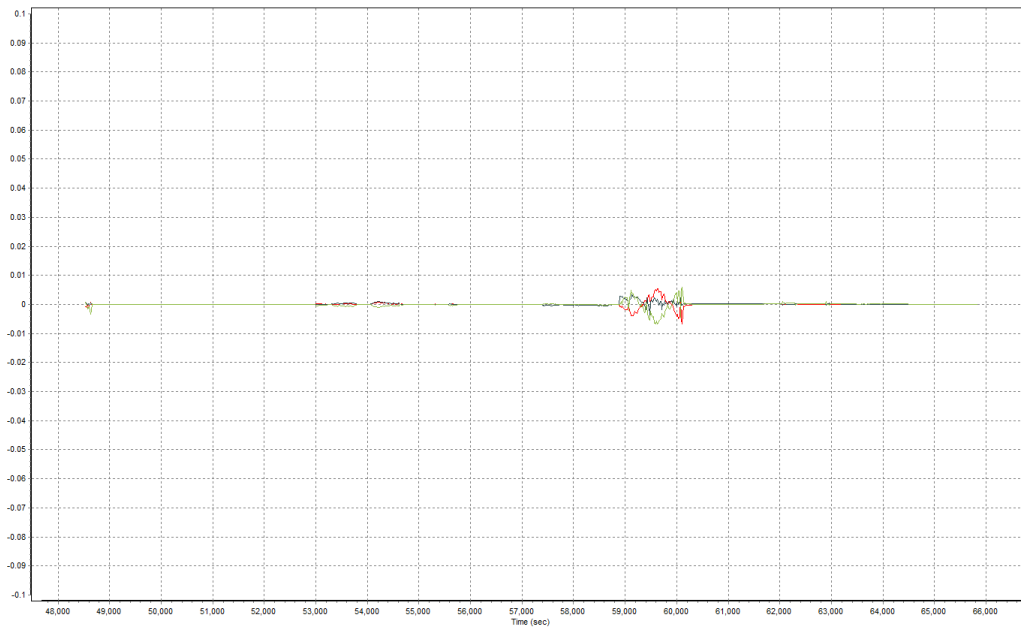


— Forward - - Reverse

Number of GPS Satellites

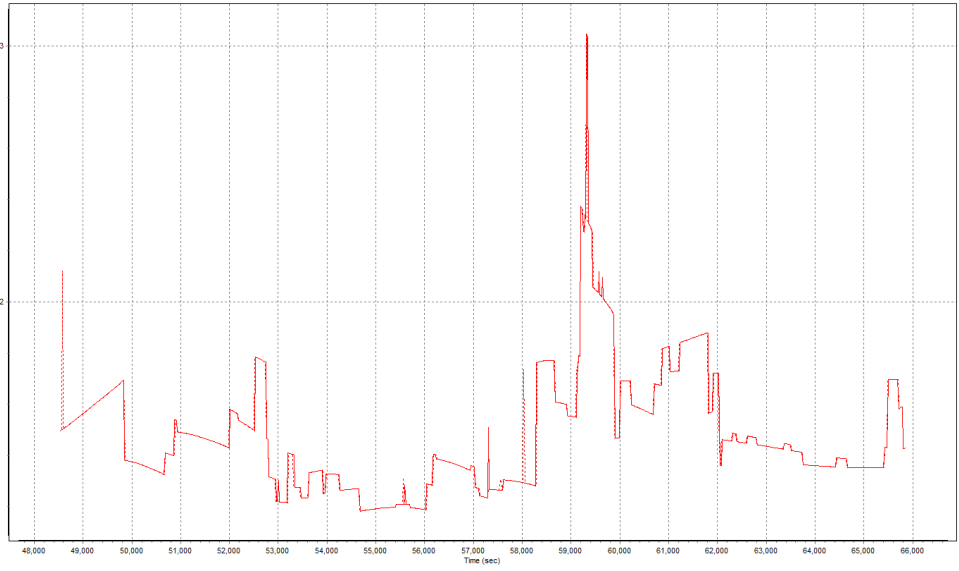


Forward  Reverse



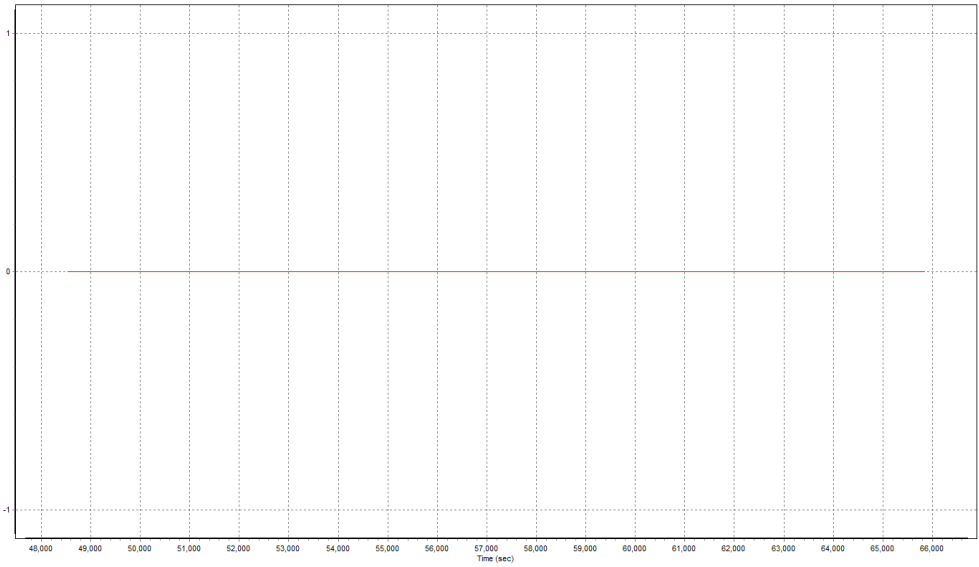
North (m)  East (m)  Down (m)  DR mode

PDOP



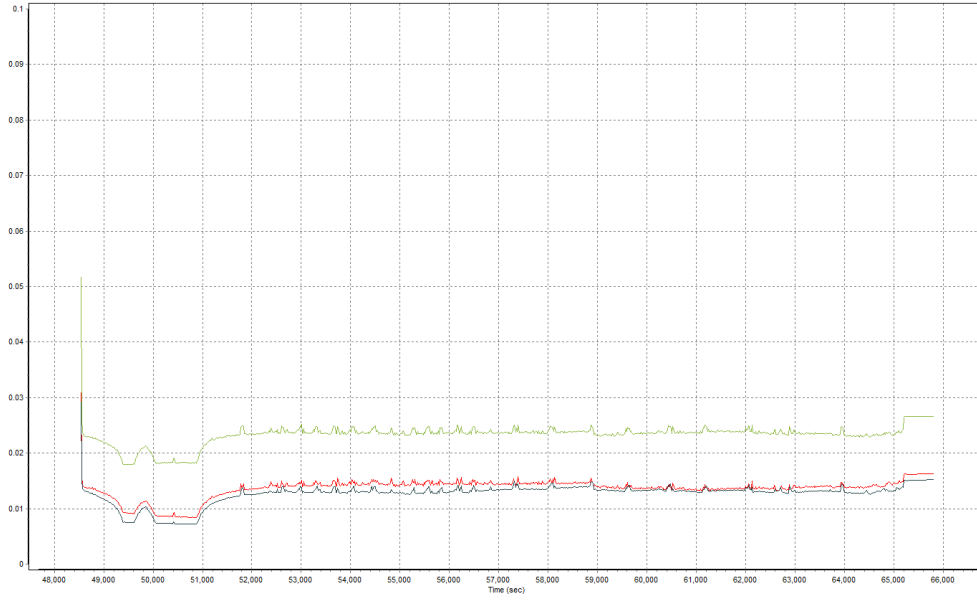
Forward  Reverse

Processing mode

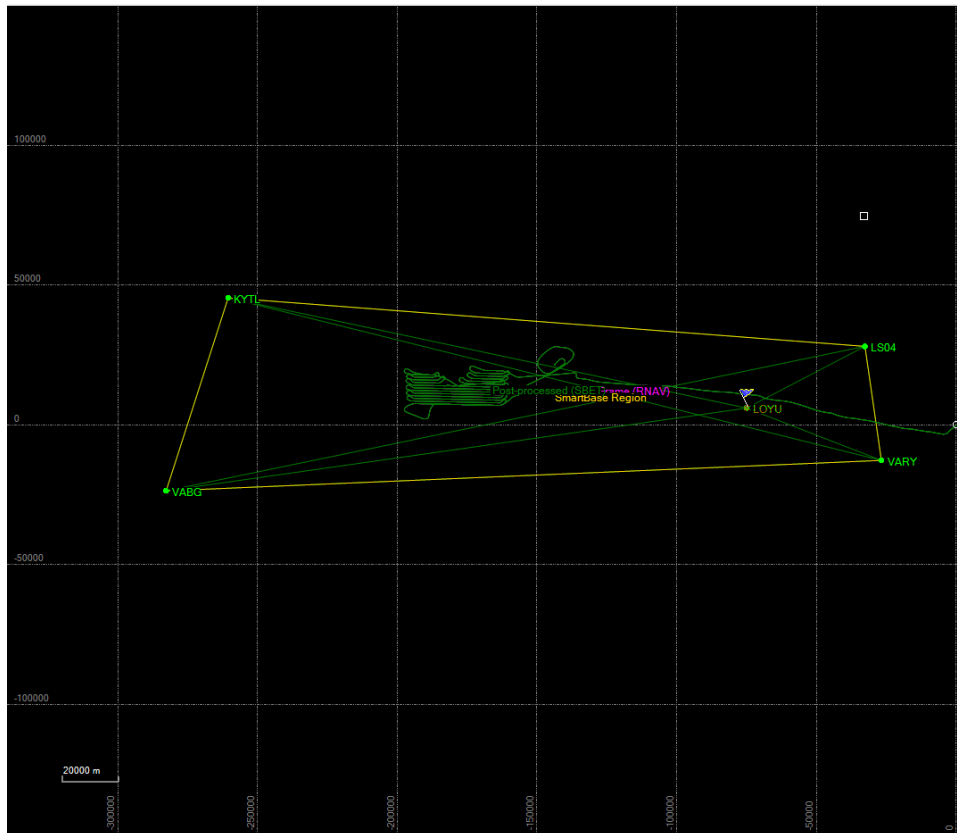


Forward  Reverse

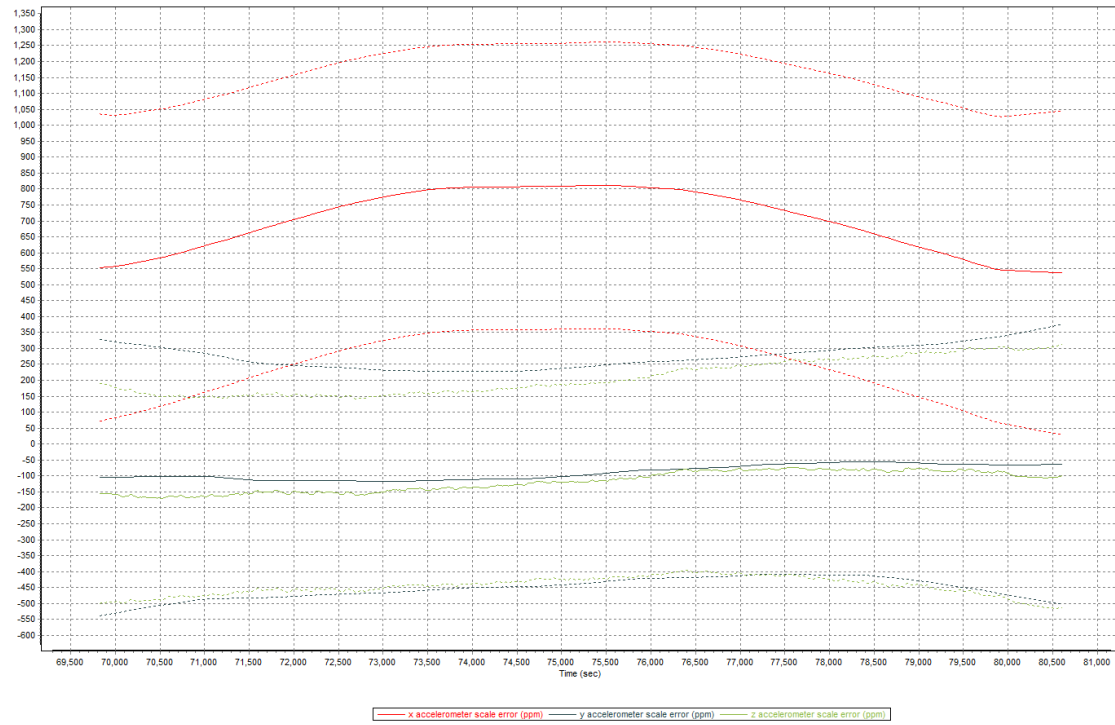
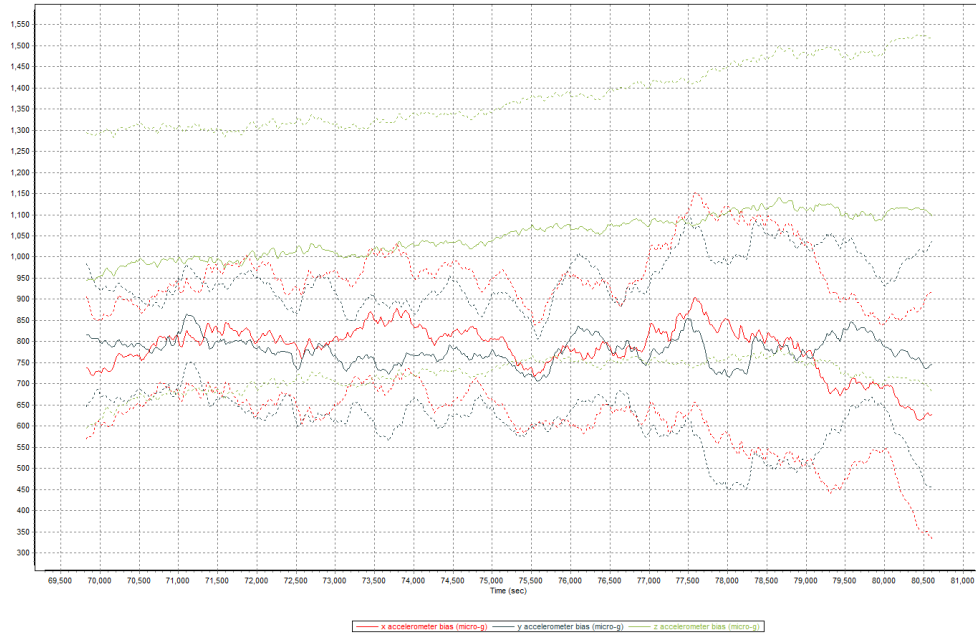
0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGSS, 4 = RTCM, 5 = IARPP, 6 = CIA, 7 = GNSS Nav, 8 = DR

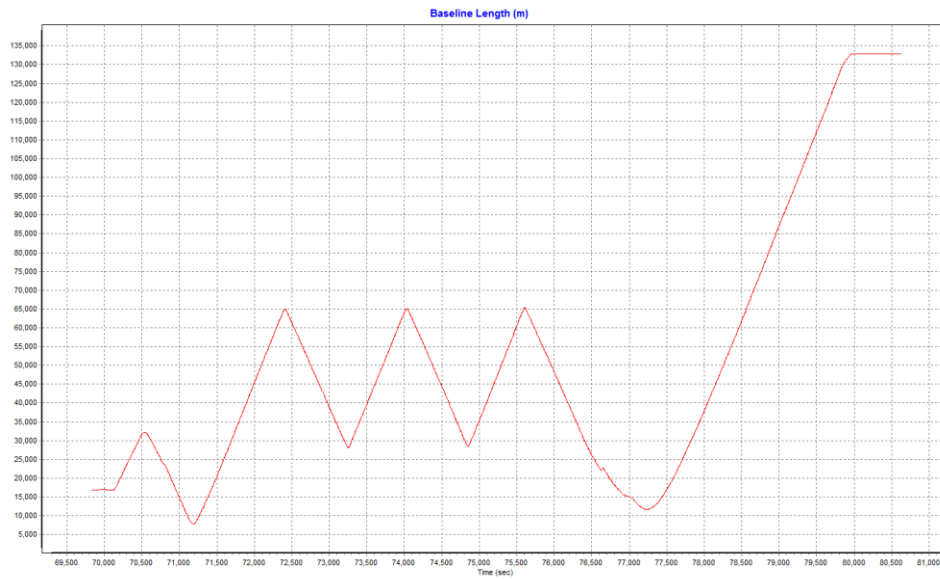
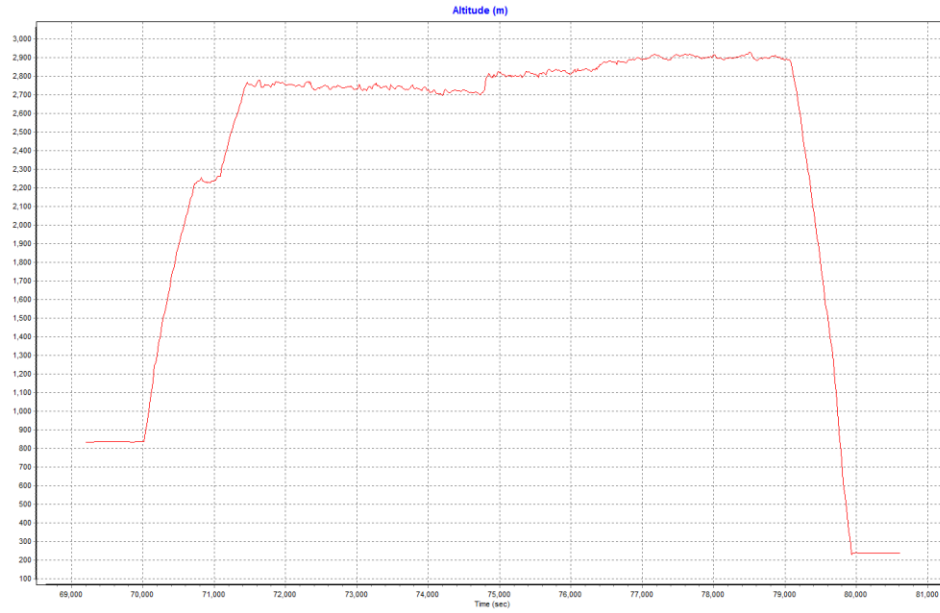


North Position Error RMS (m) East Position Error RMS (m) Down Position Error RMS (m)

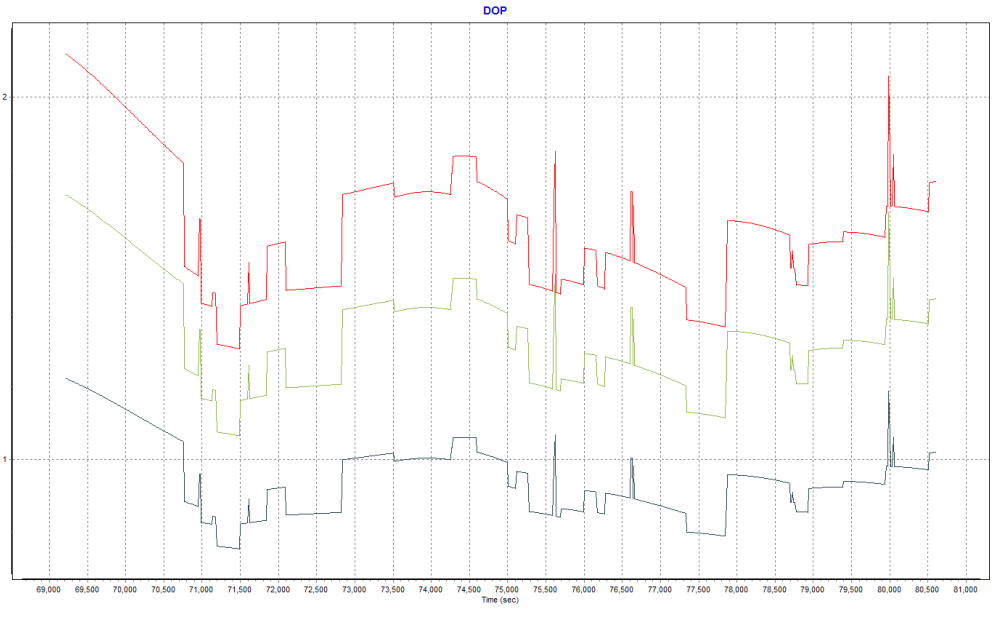


# UNB16318B

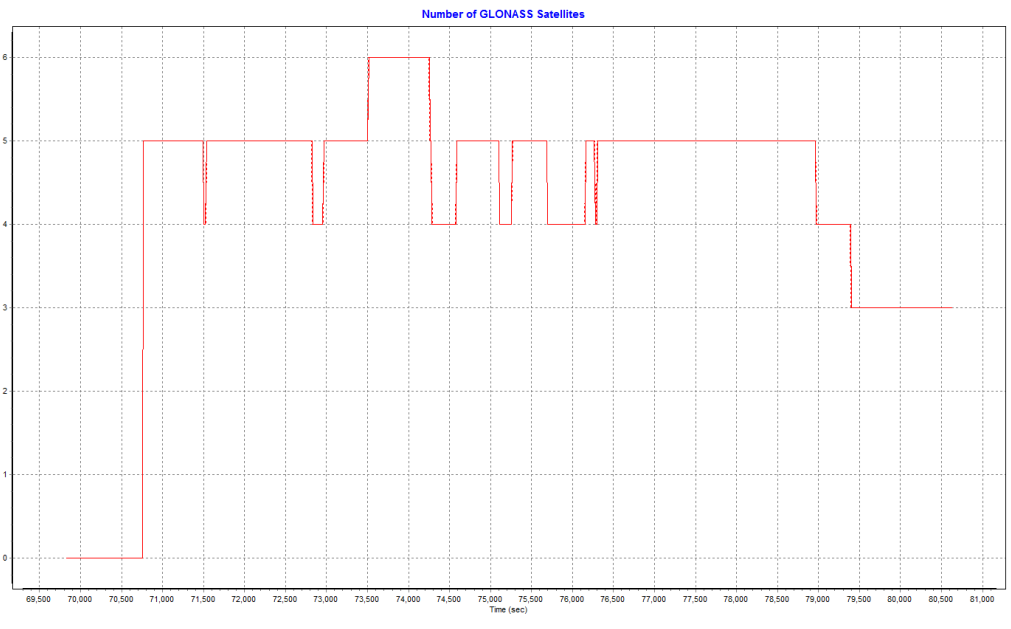




Forward  Reverse

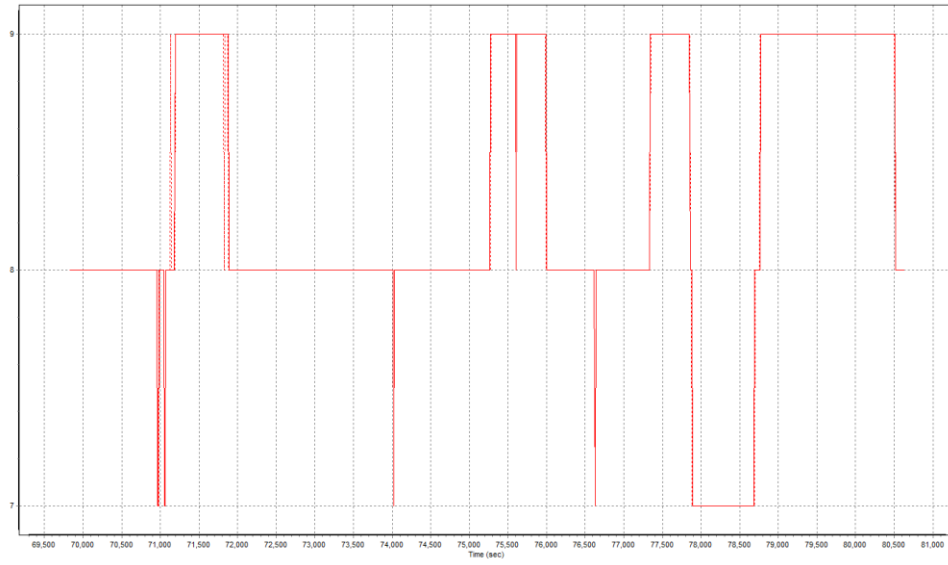


— PDOP — HDOP — VDOP

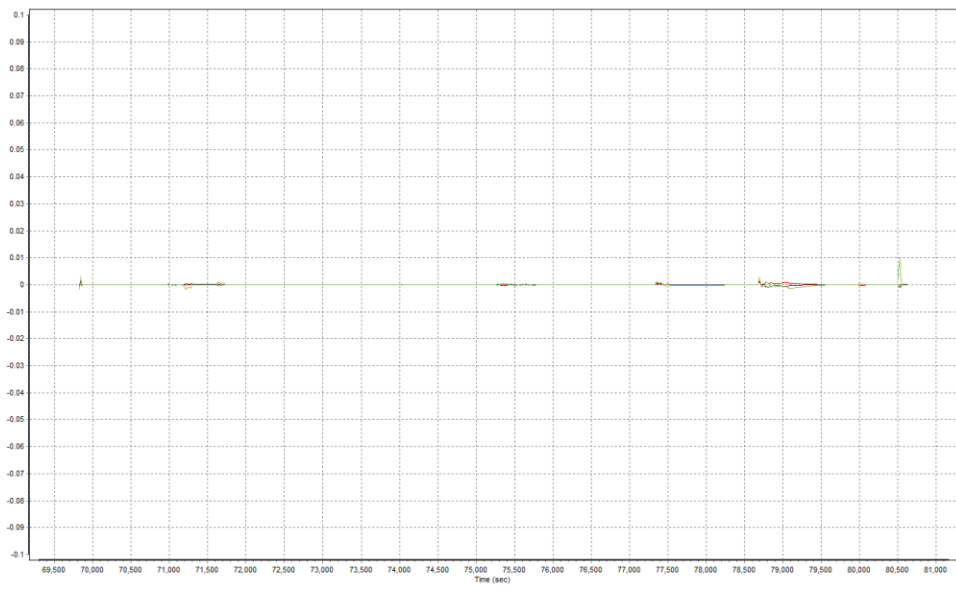


Forward  Reverse

Number of GPS Satellites



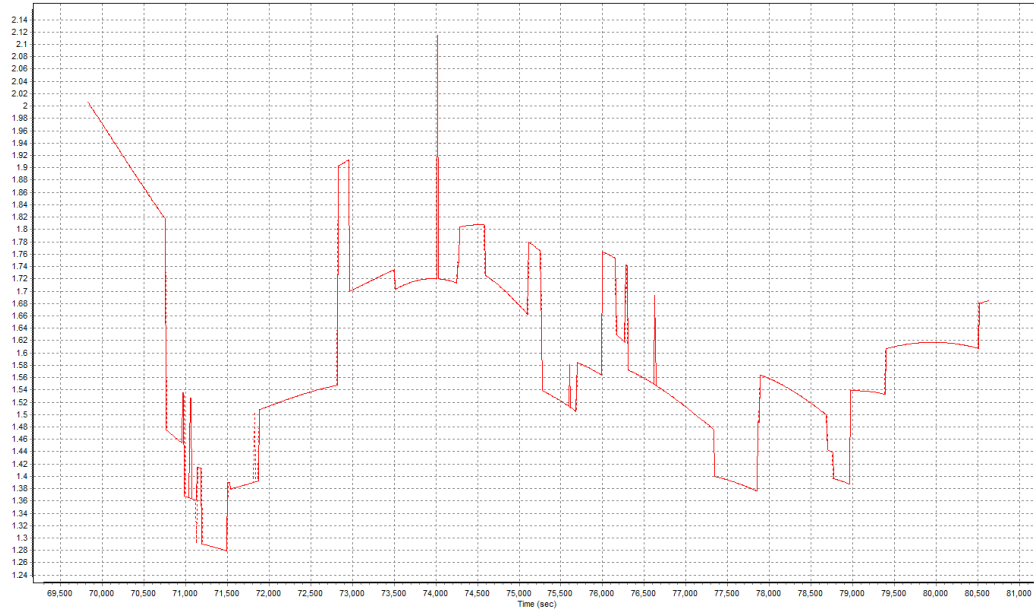
Forward  Reverse



North (m) East (m) Down (m) DR mode

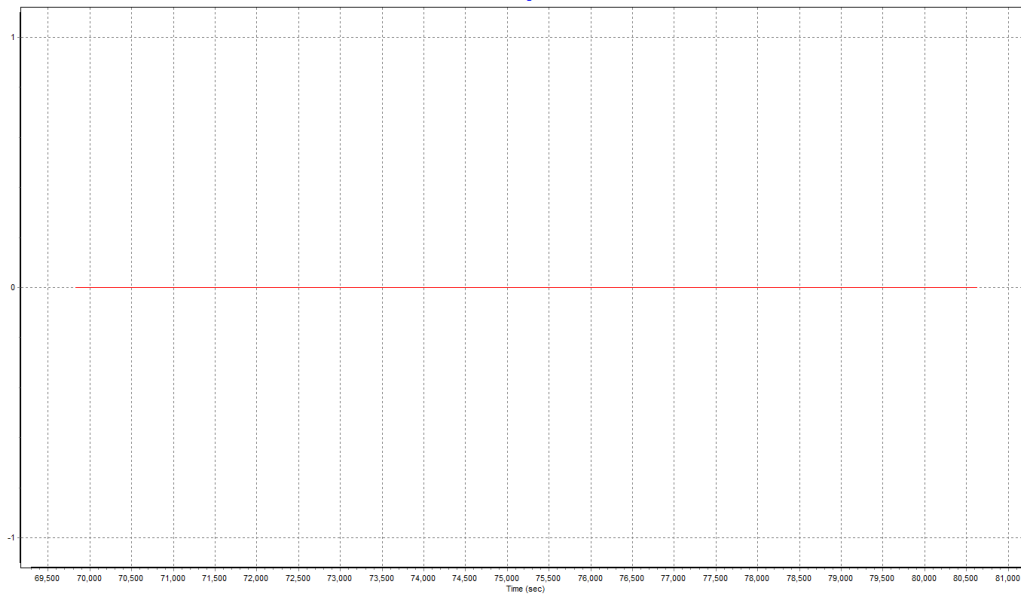


PDOP



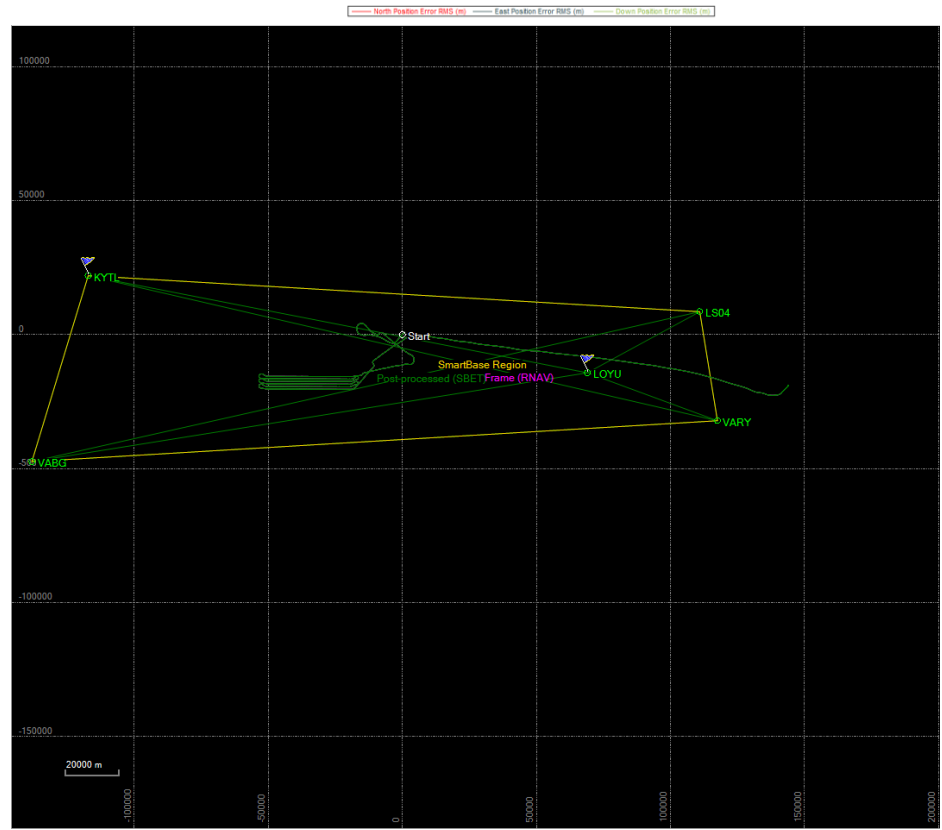
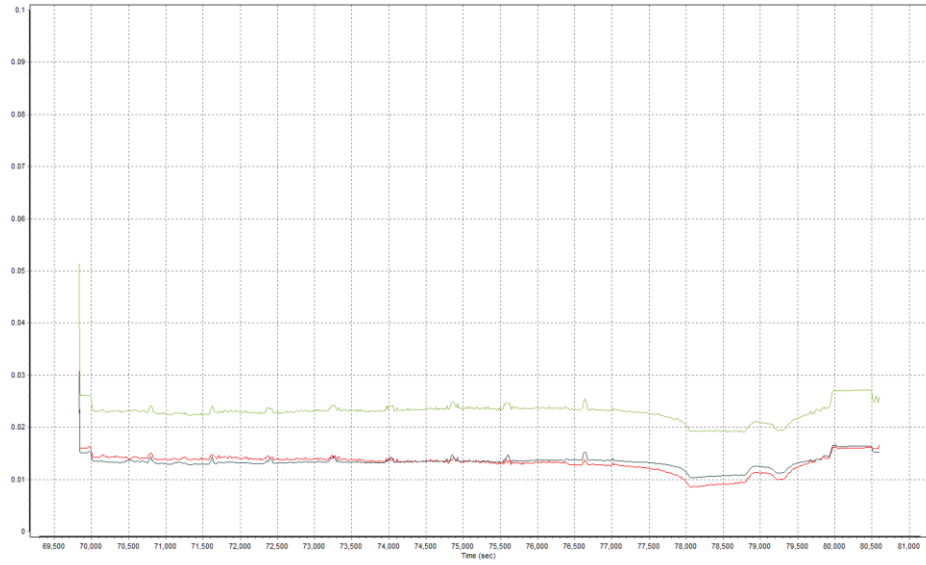
Forward  Reverse

Processing mode

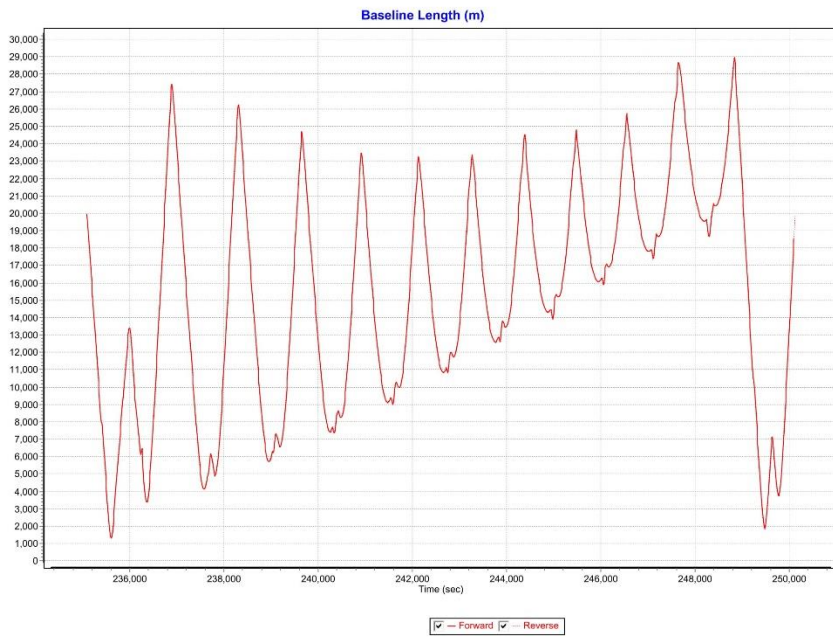
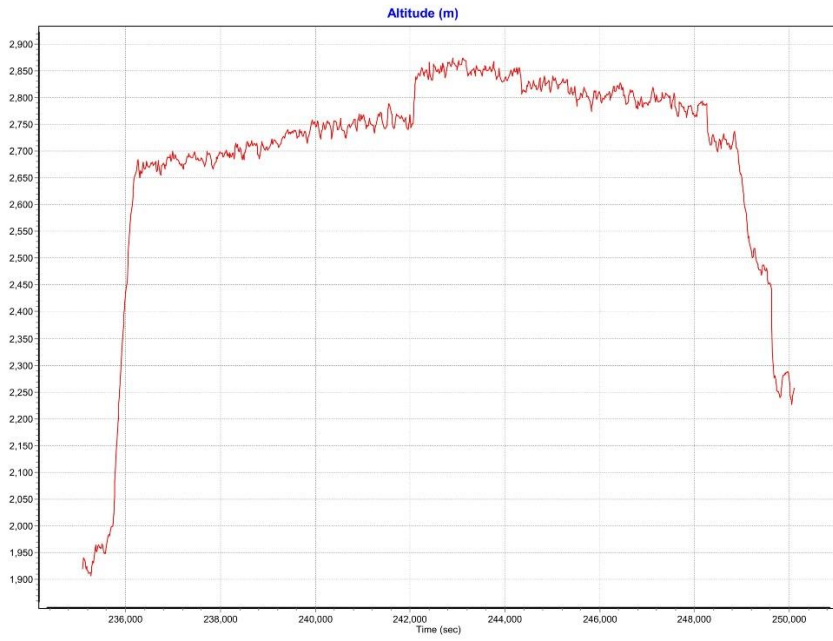


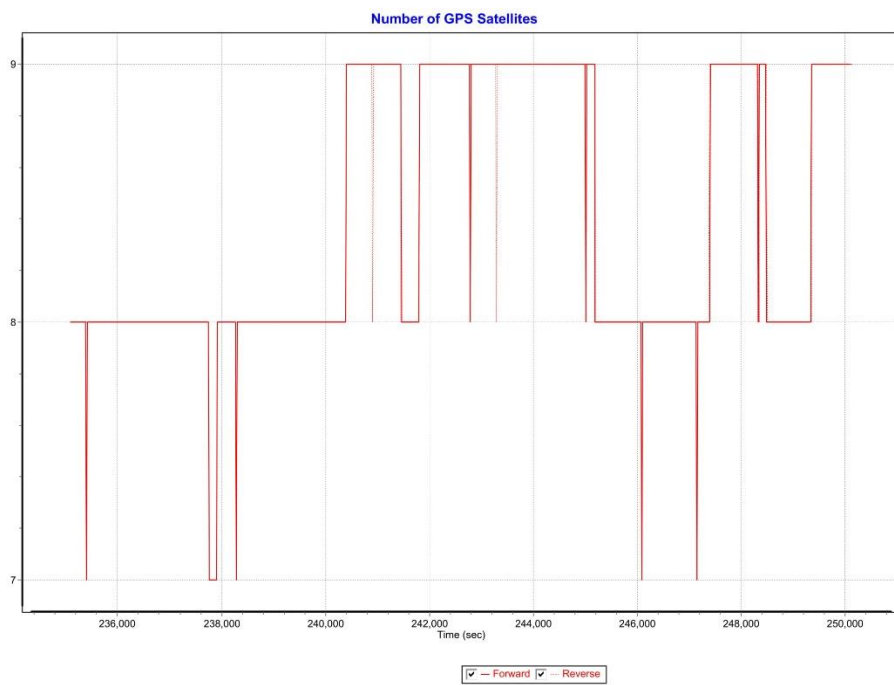
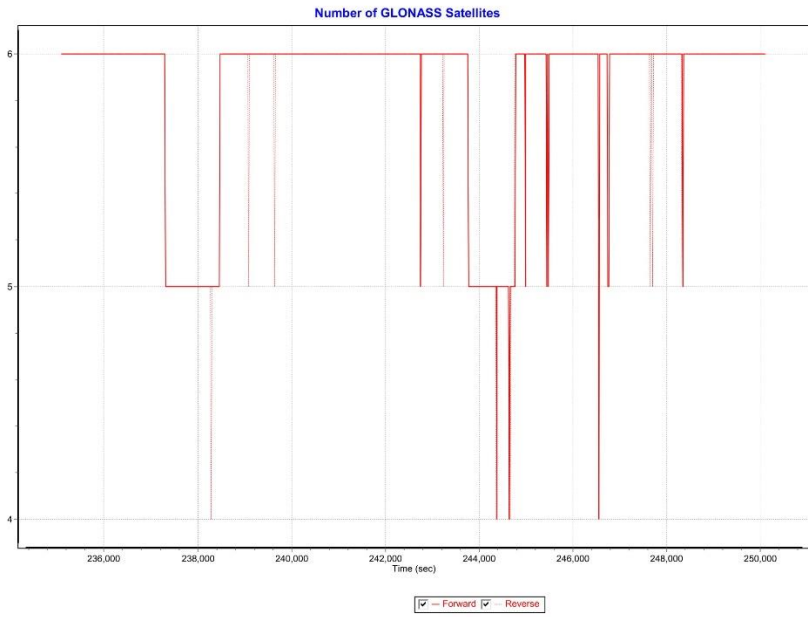
Forward  Reverse

0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGSS, 4 = RTCM, 5 = IARPP, 6 = CIA, 7 = GNSS Nav, 8 = DR

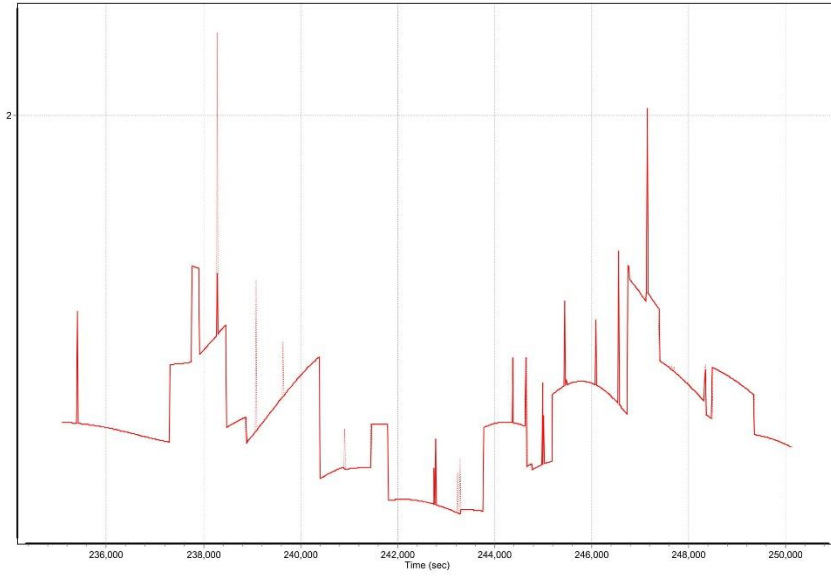


# UNB16320A



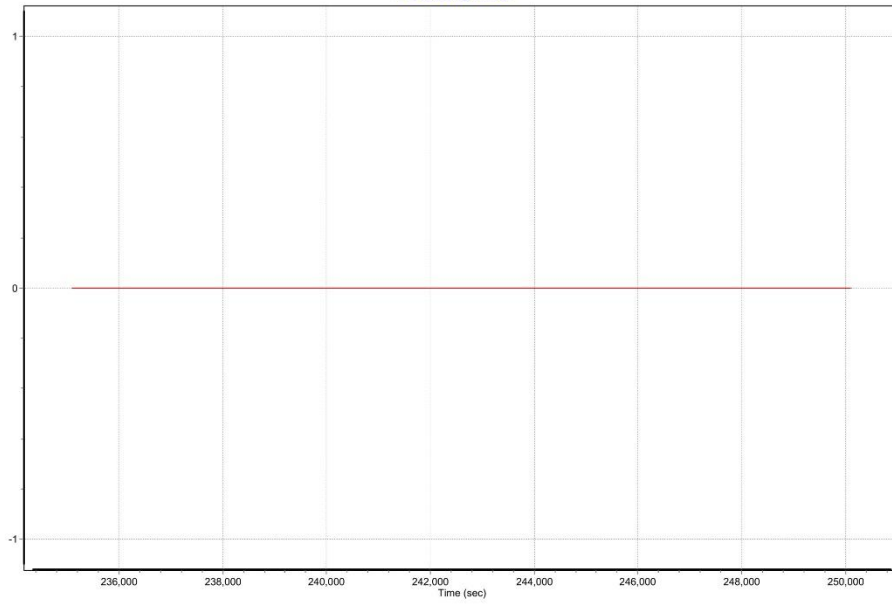


PDOP



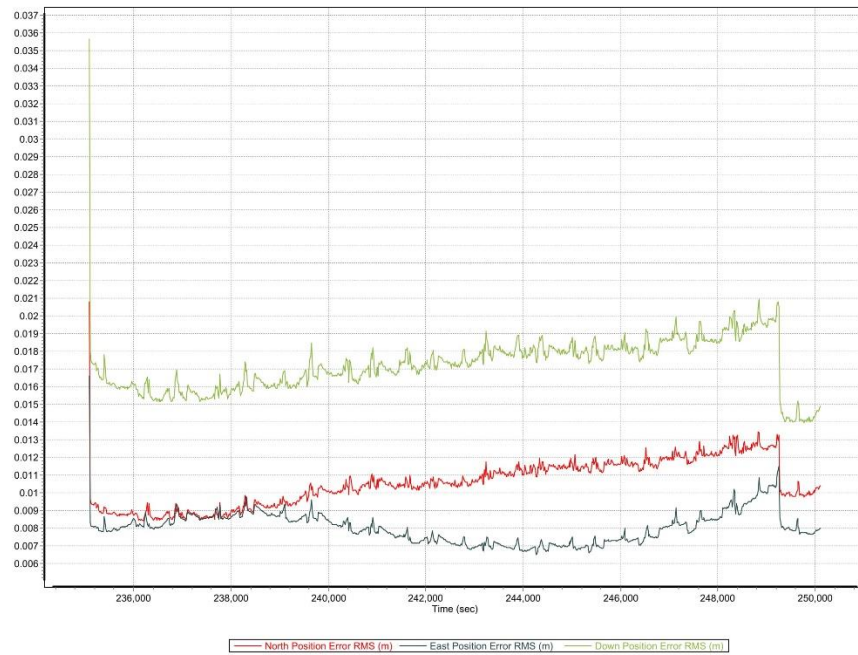
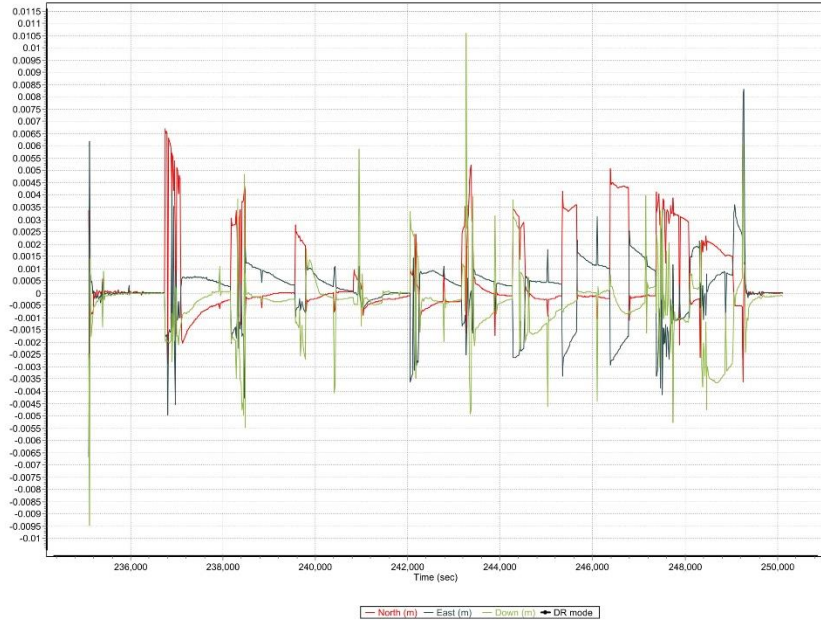
Forward  Reverse

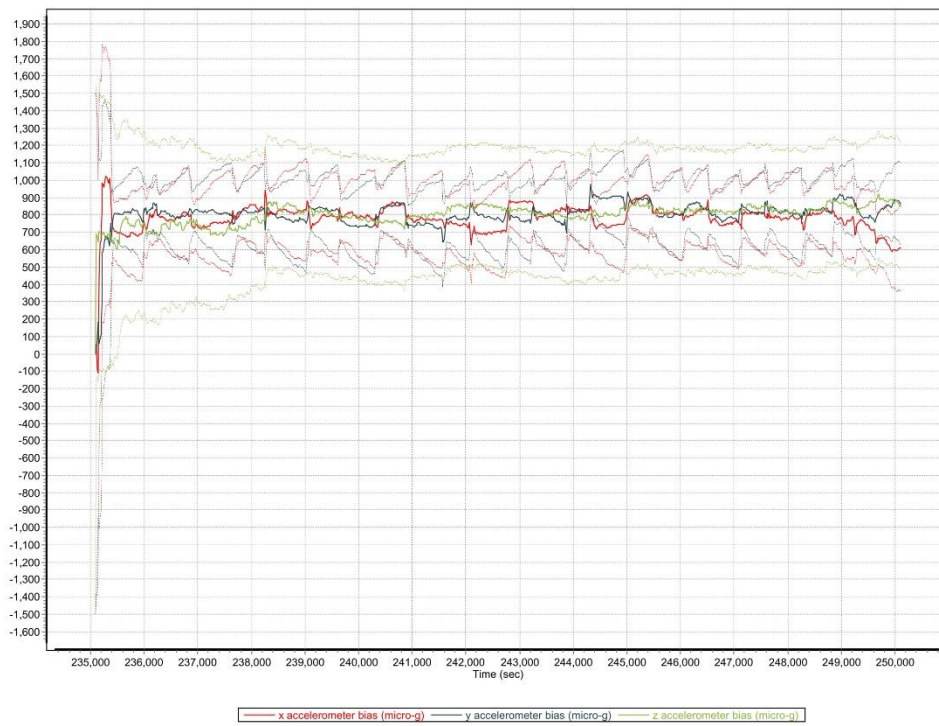
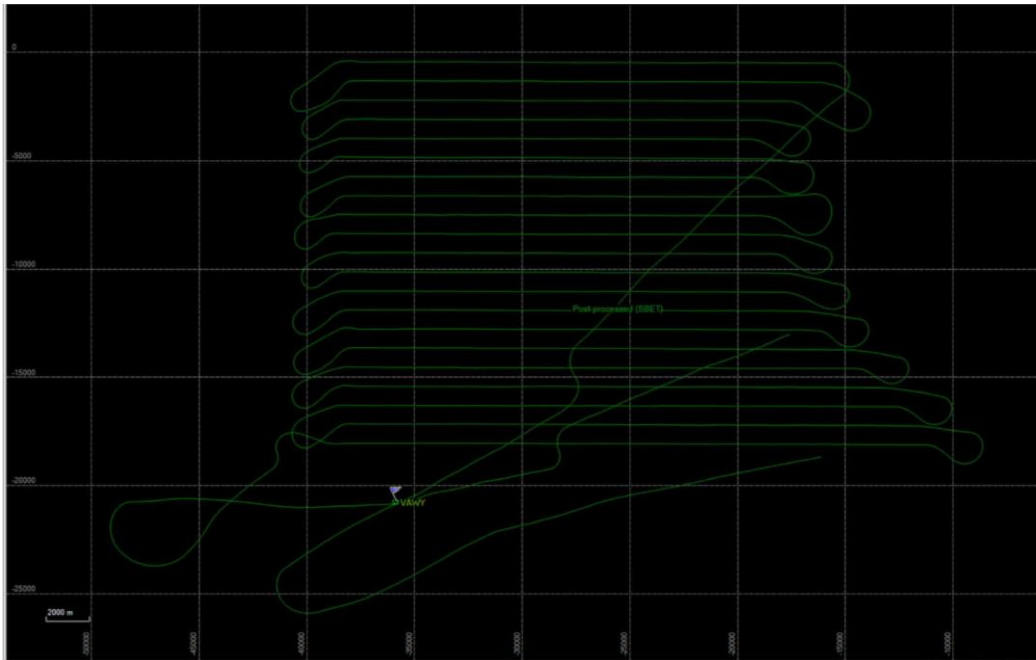
Processing mode

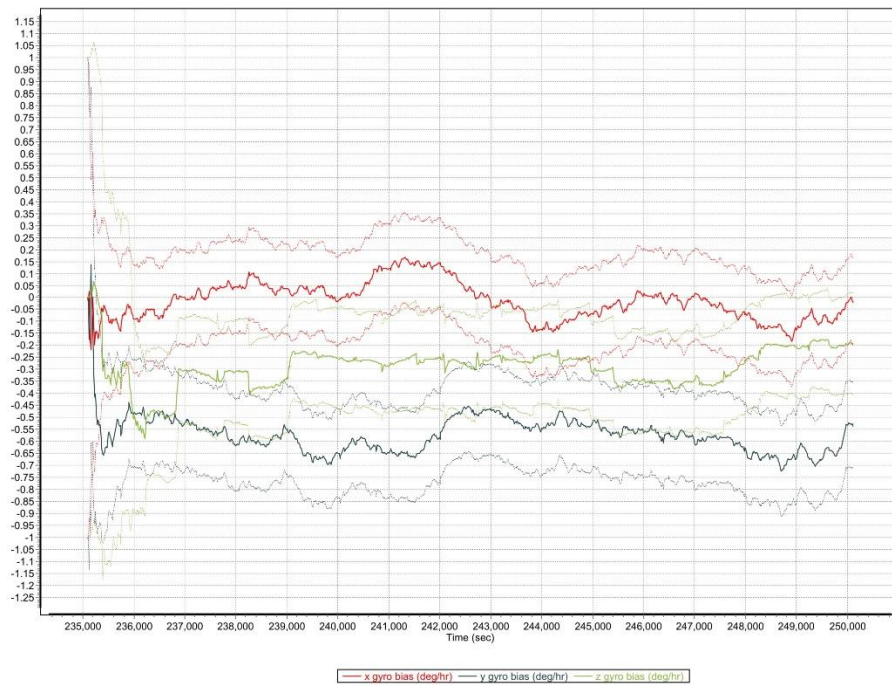
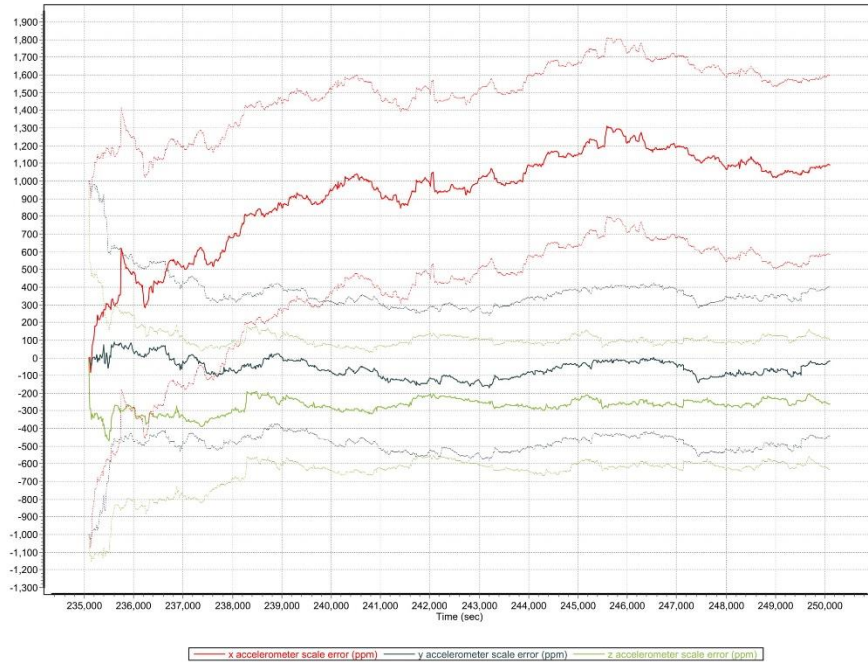


Forward  Reverse

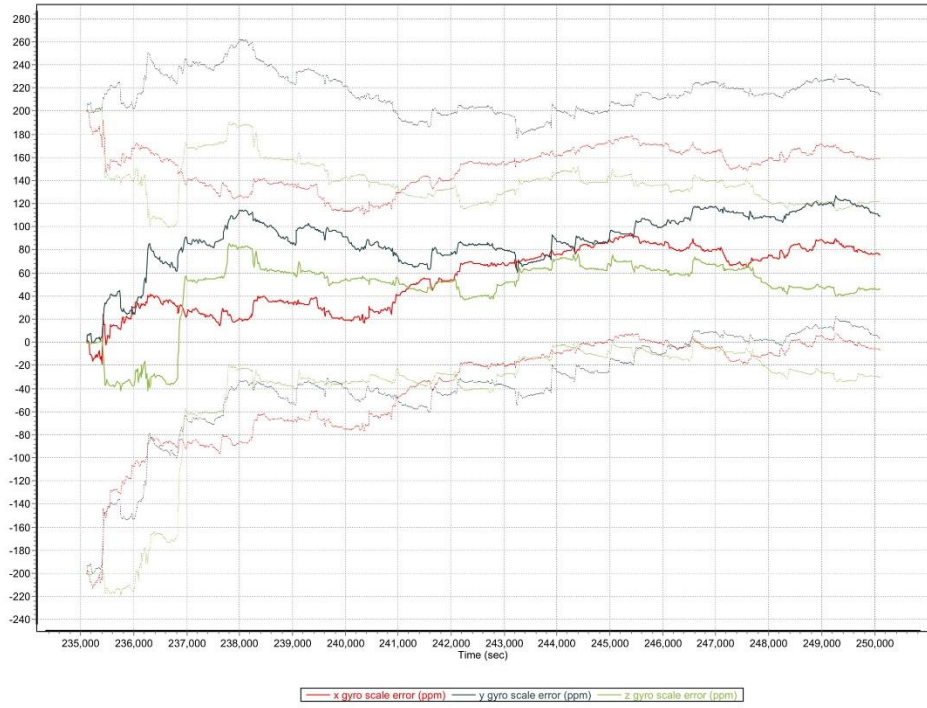
0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = CA, 7 = GNSS Nav, 8 = DR



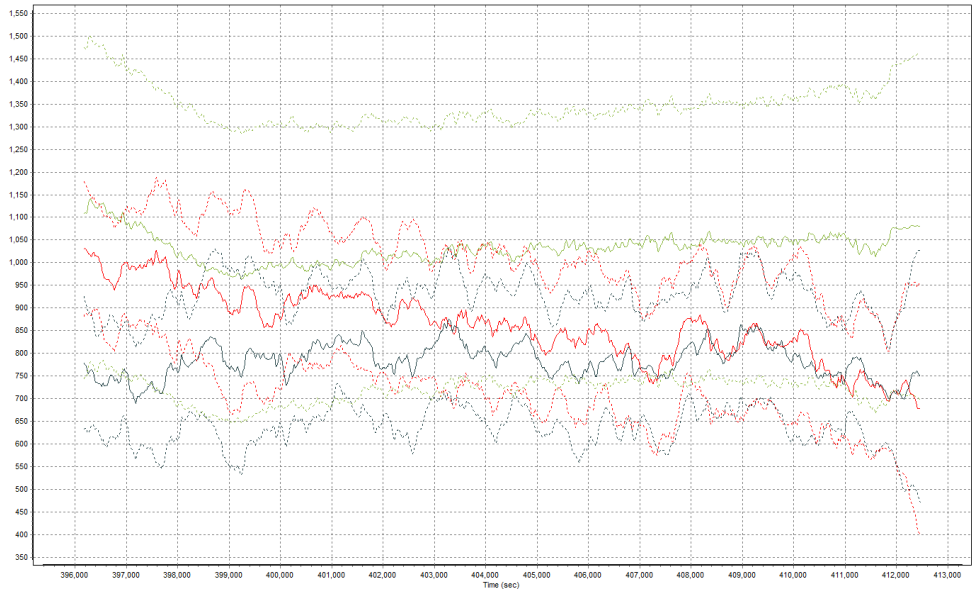




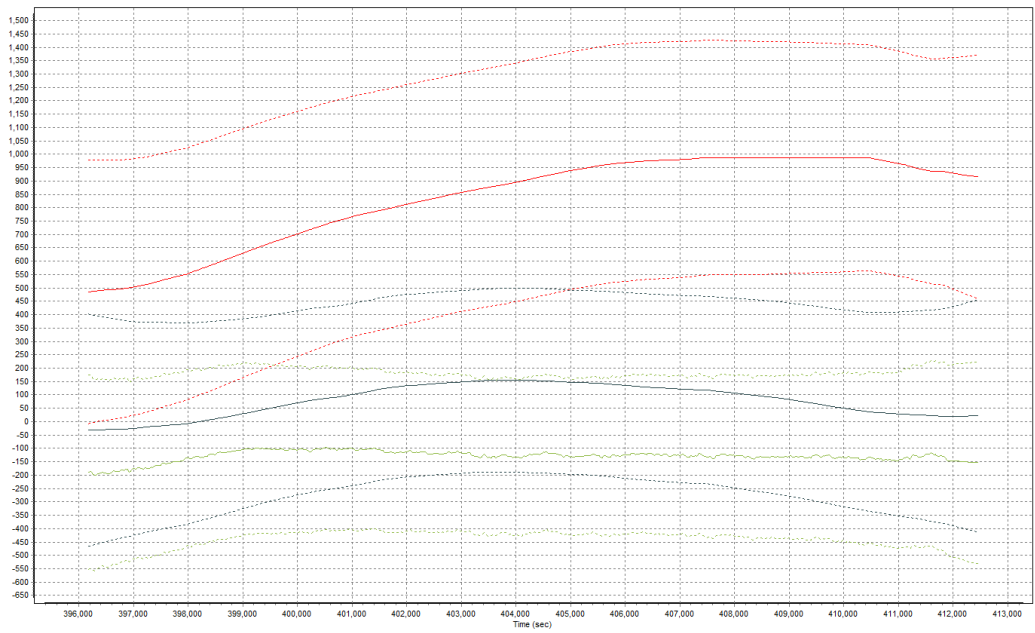




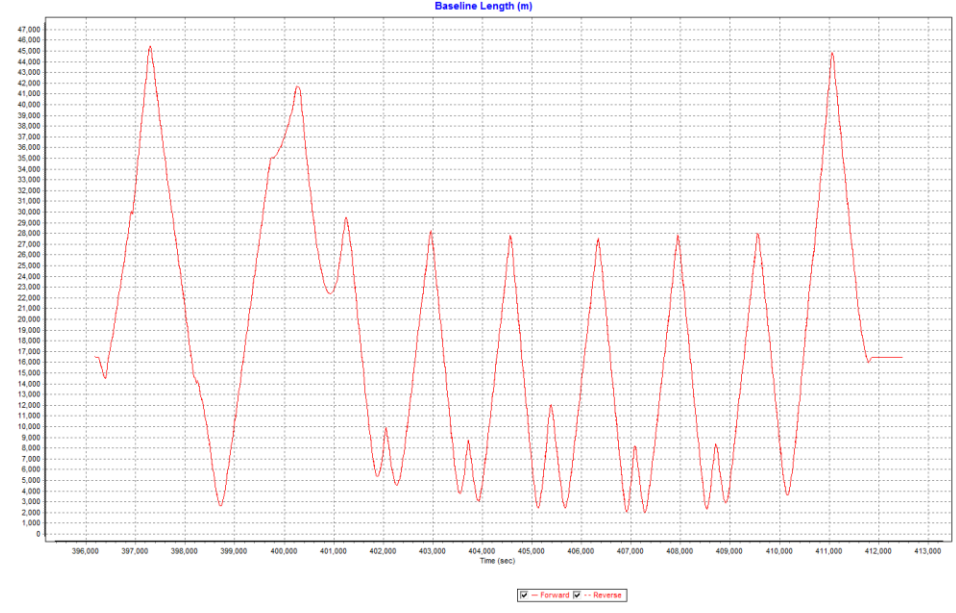
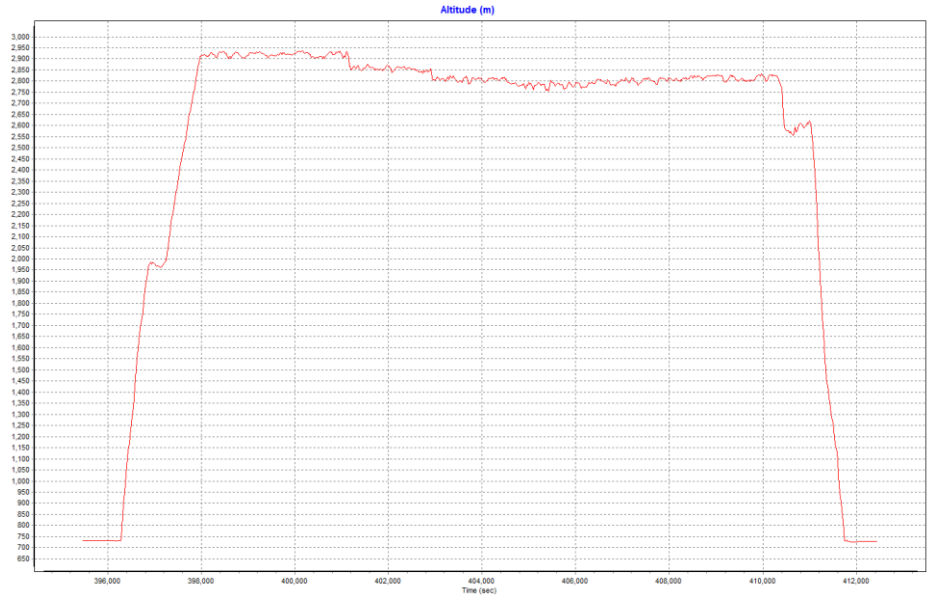
# UNB16322A

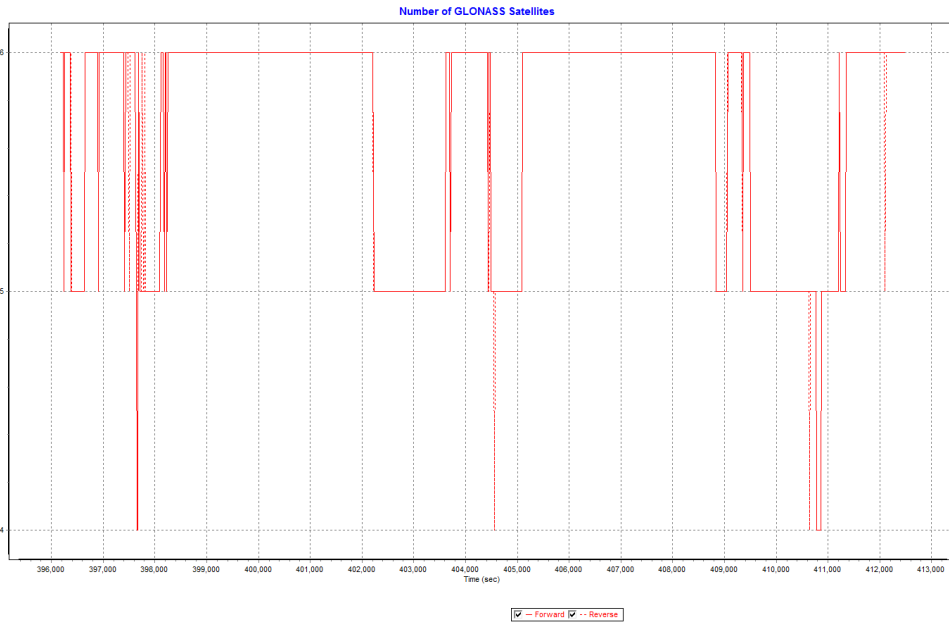
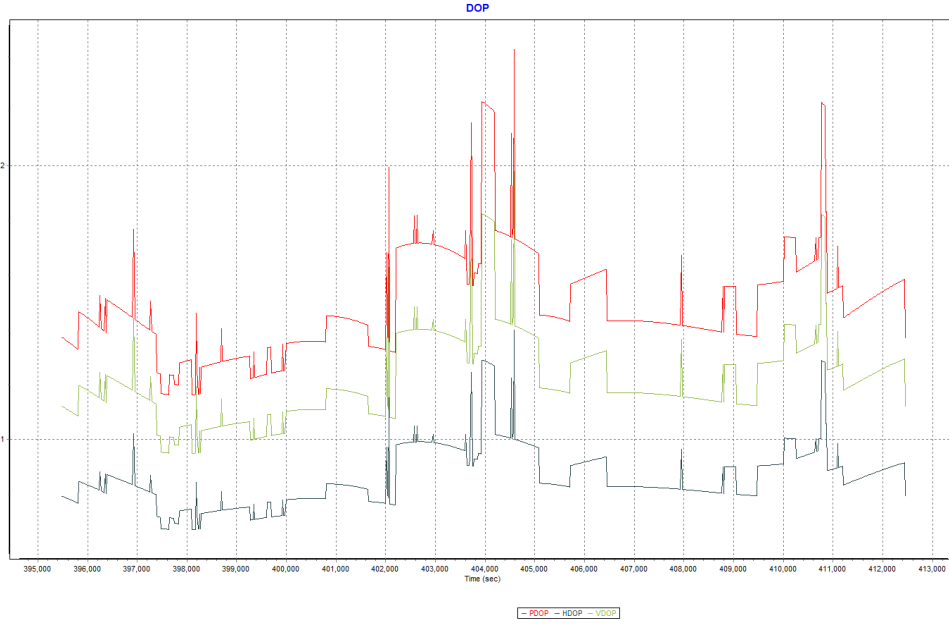


— x accelerometer bias (micro-g) — y accelerometer bias (micro-g) — z accelerometer bias (micro-g)

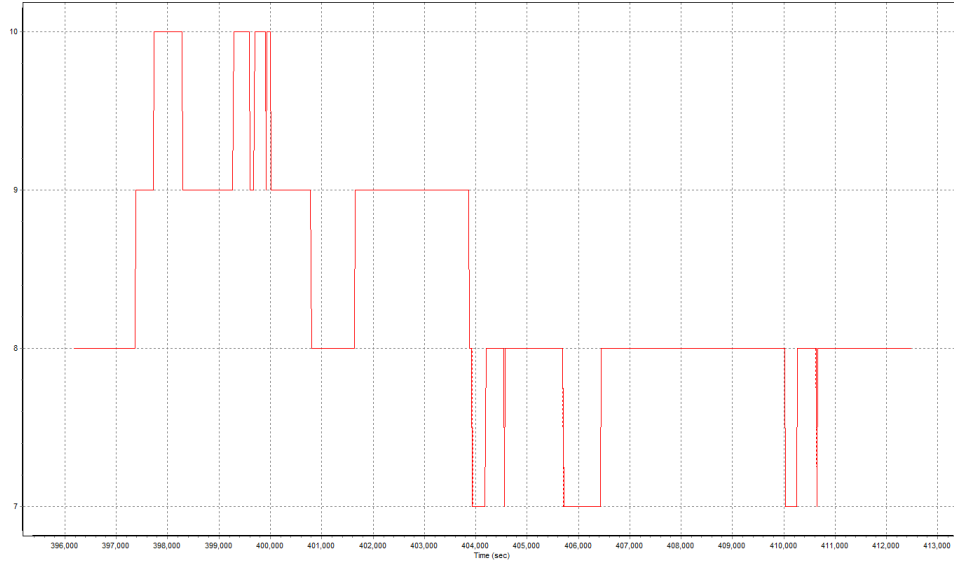


— x accelerometer scale error (ppm) — y accelerometer scale error (ppm) — z accelerometer scale error (ppm)

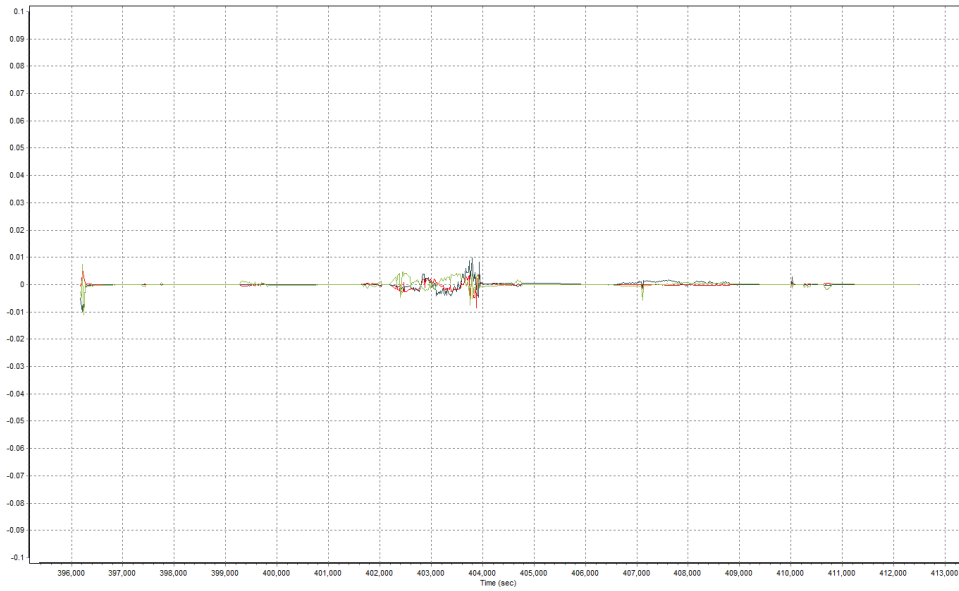




Number of GPS Satellites

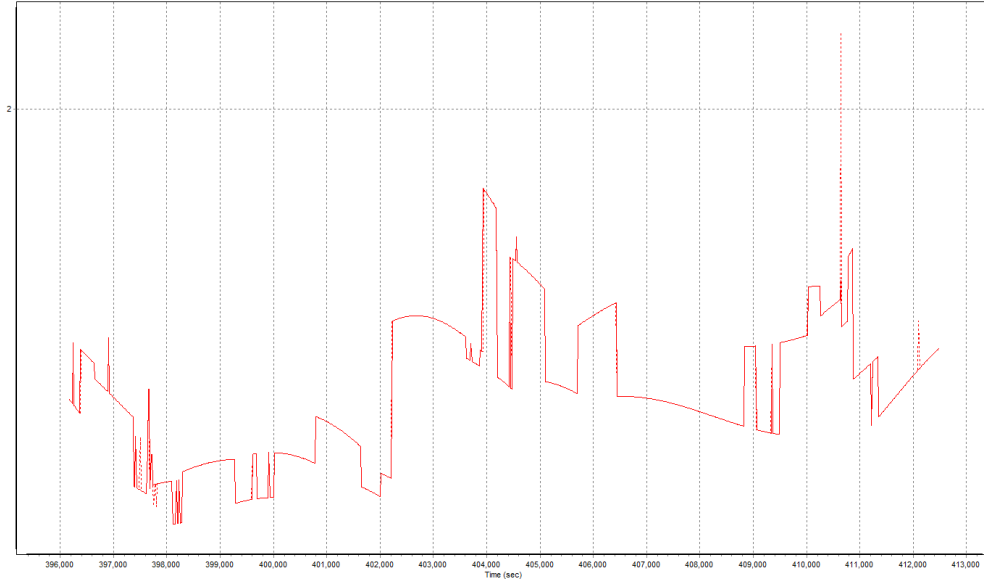


Forward  Reverse

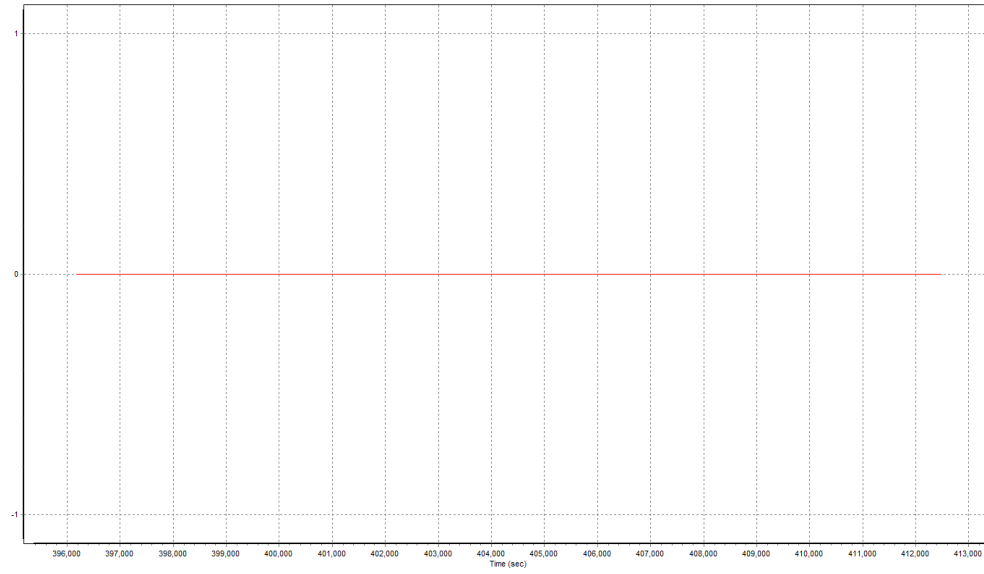


North (m) East (m) Down (m) DR mode

PDOP

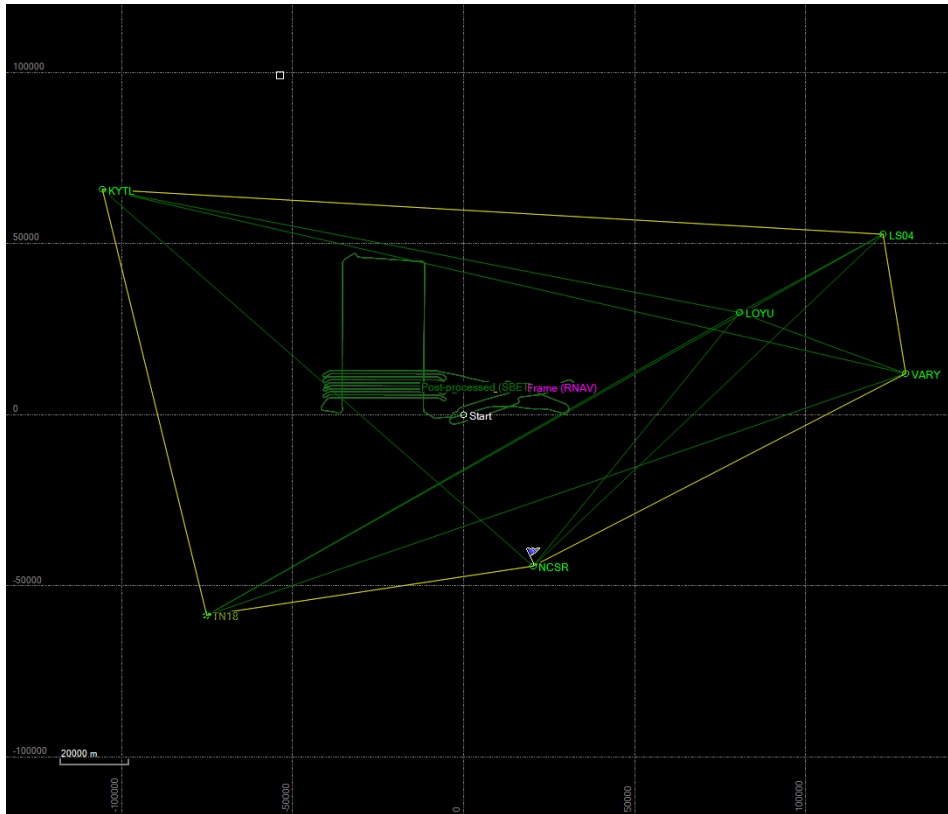
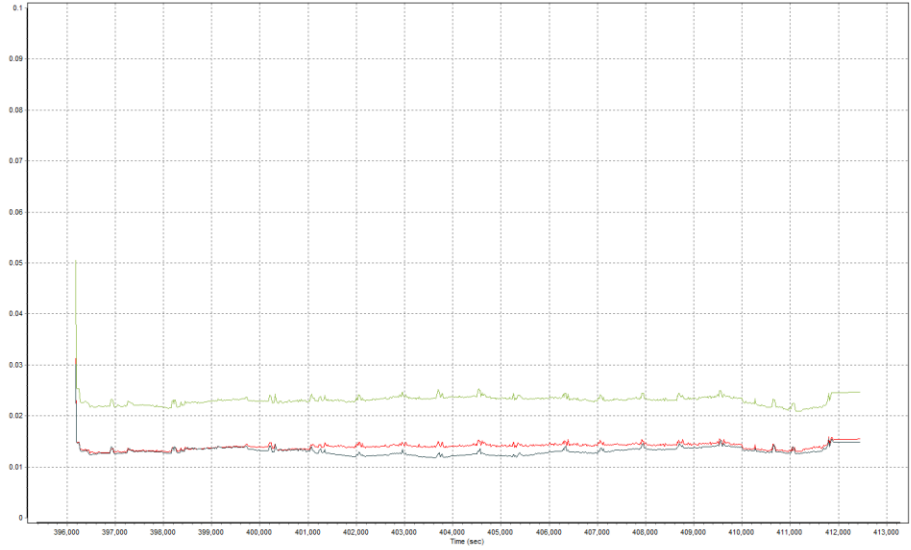


Processing mode

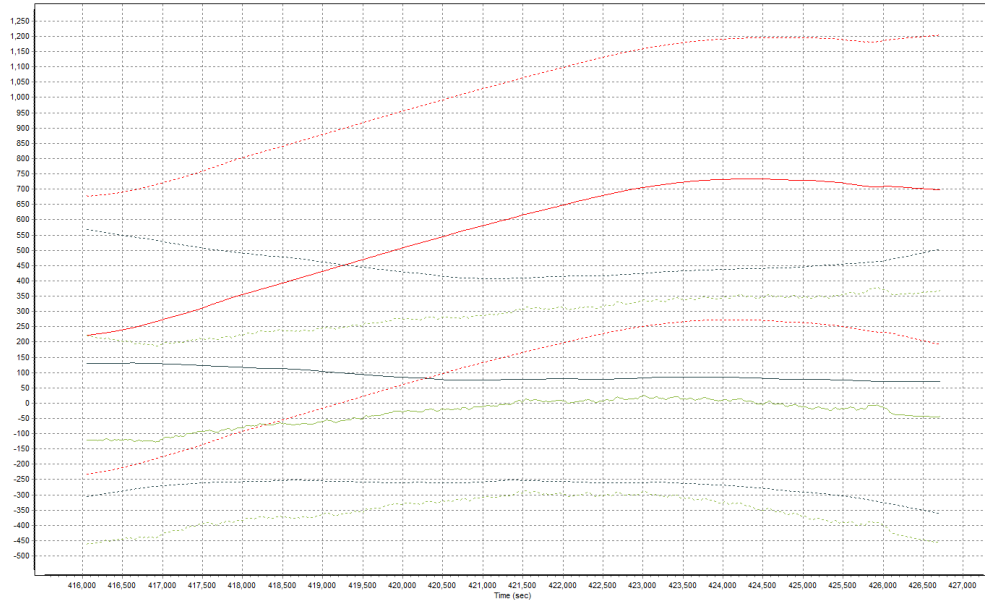


0 = Fixed N, 1 = Fixed W, 2 = Float 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = CIA, 7 = GNSS Nav, 8 = GR

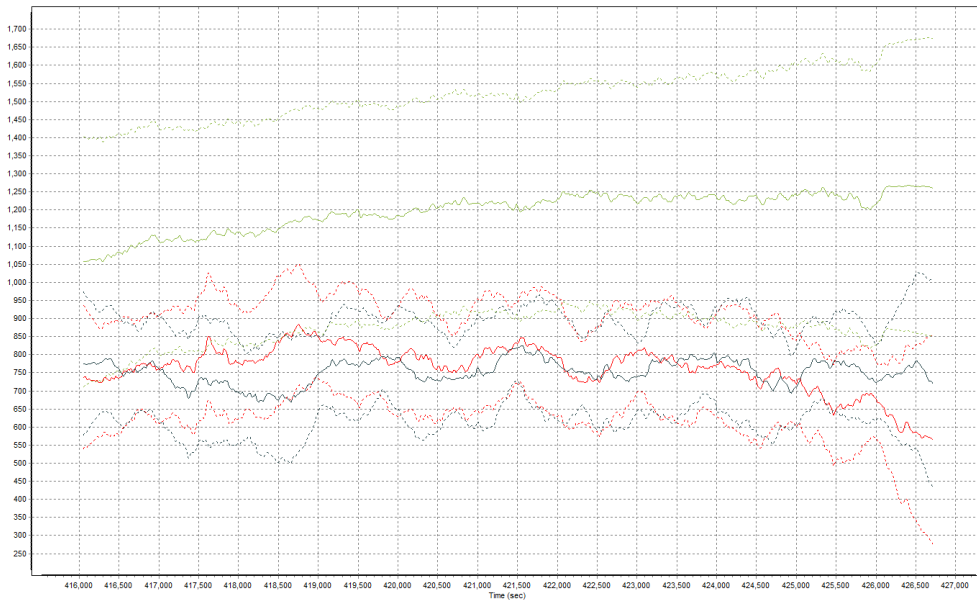
Forward  Reverse



# UNB16322B

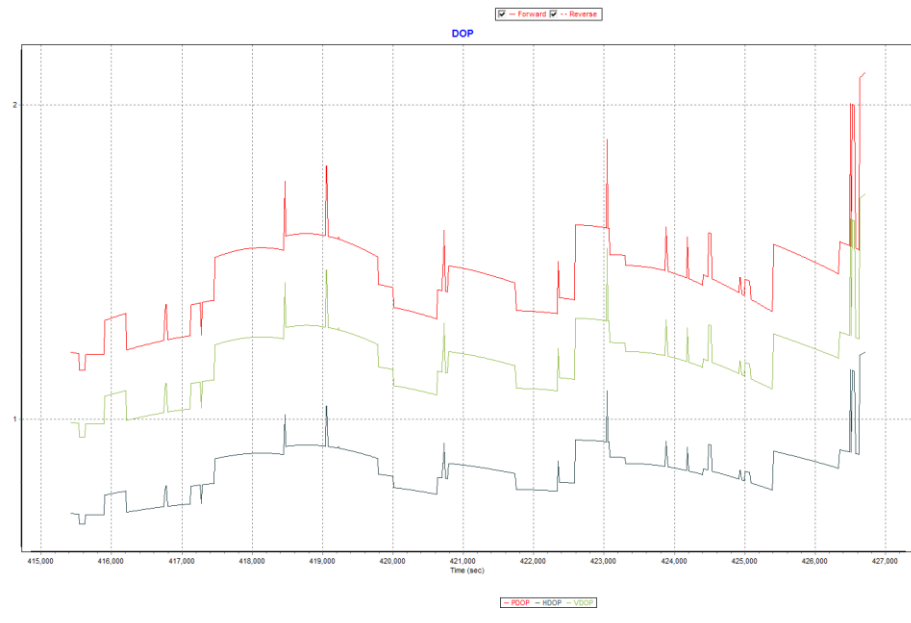
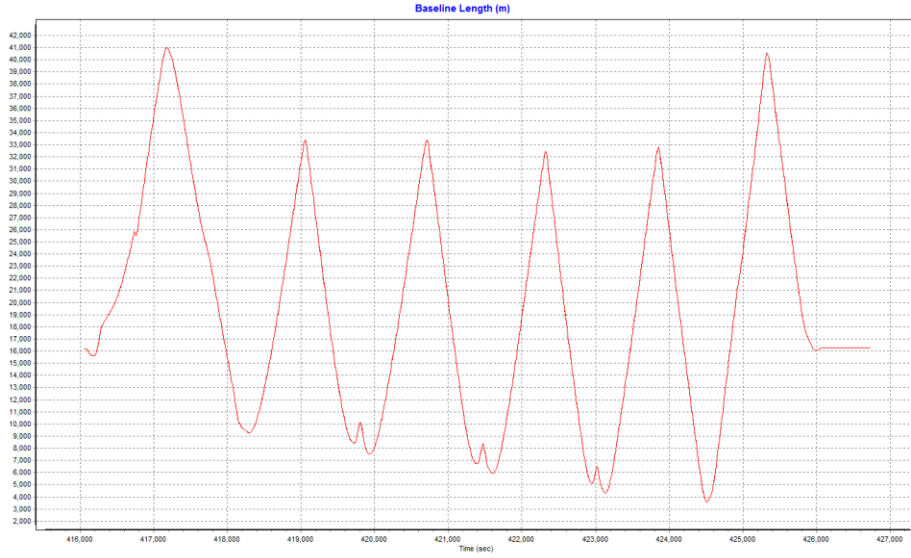


x accelerometer scale error (ppm)    y accelerometer scale error (ppm)    z accelerometer scale error (ppm)

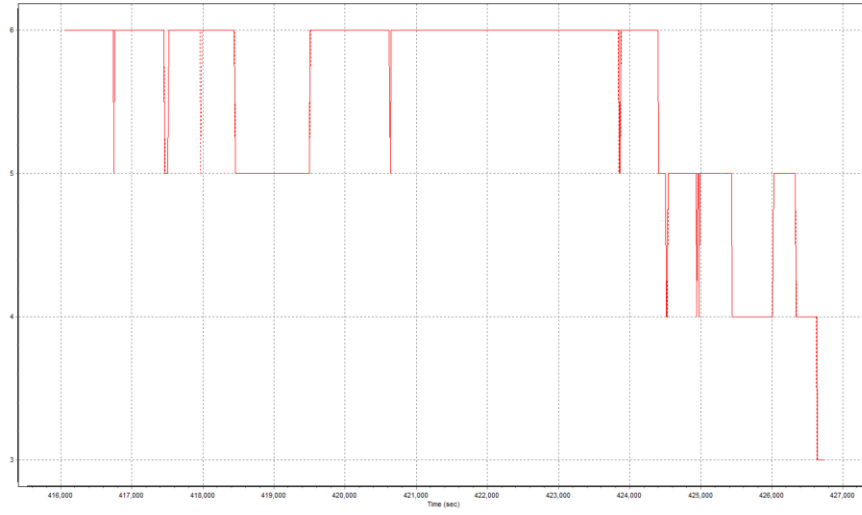


x accelerometer bias (micro-g)    y accelerometer bias (micro-g)    z accelerometer bias (micro-g)

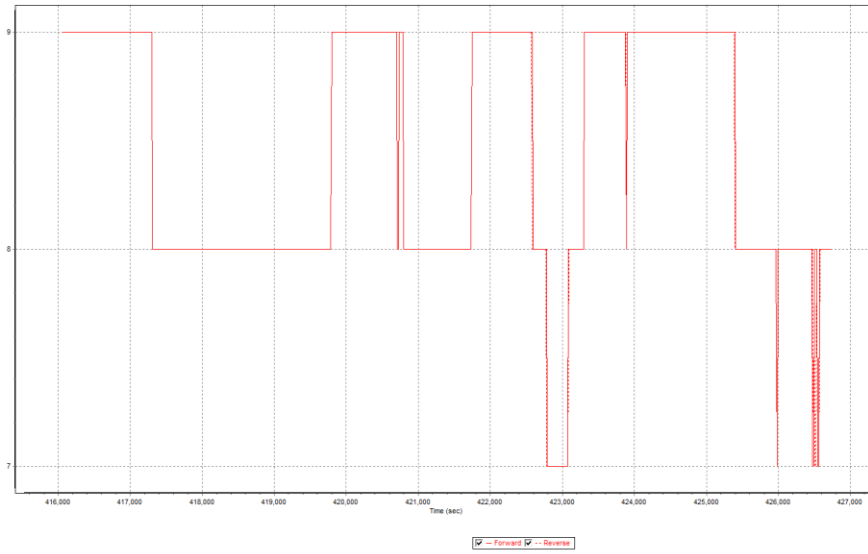


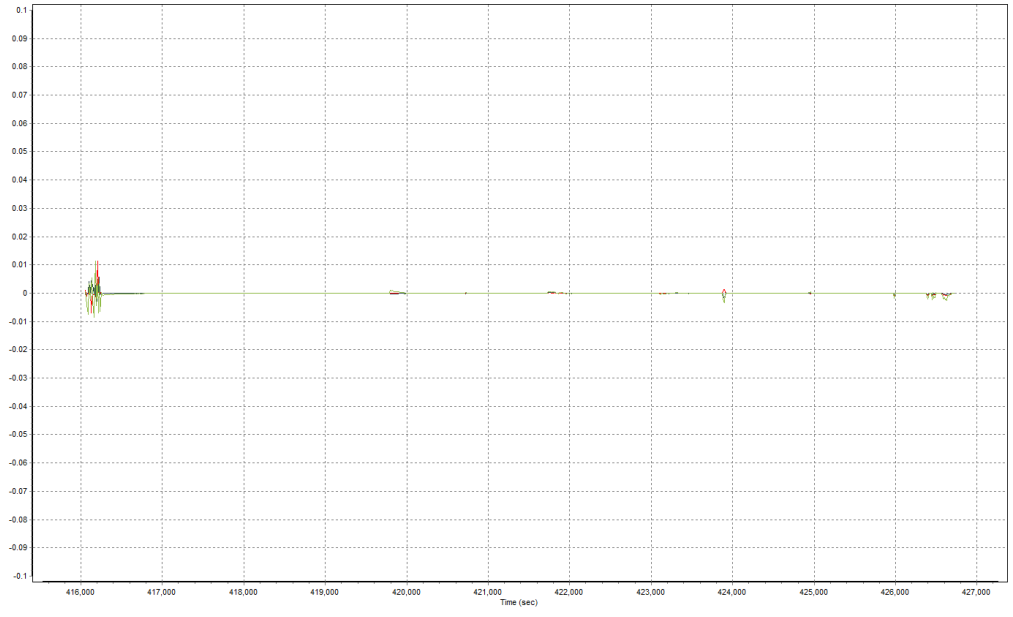


Number of GLONASS Satellites

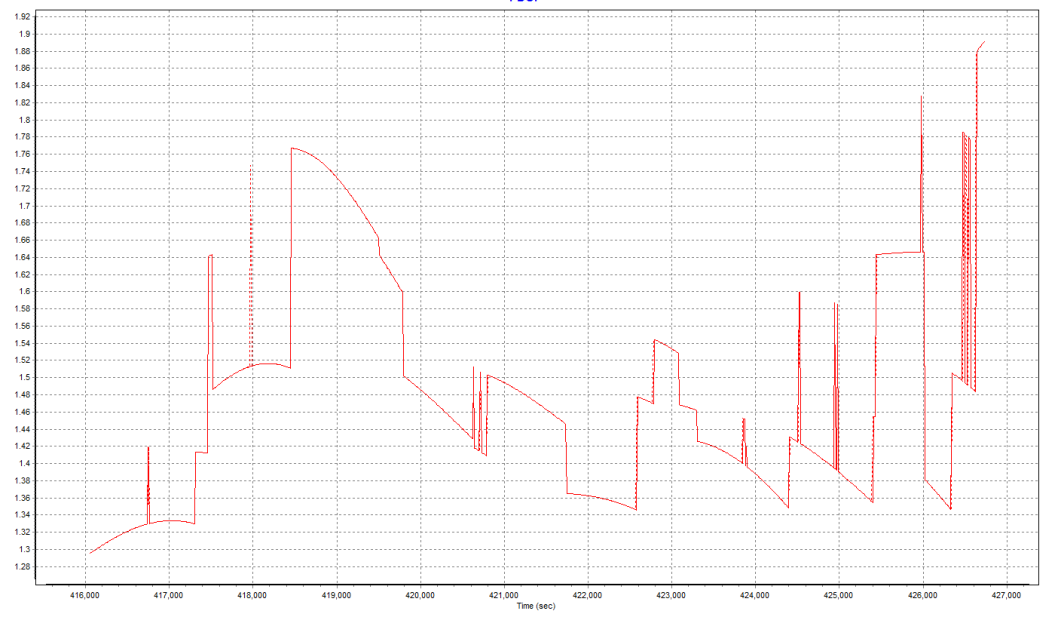


Number of GPS Satellites



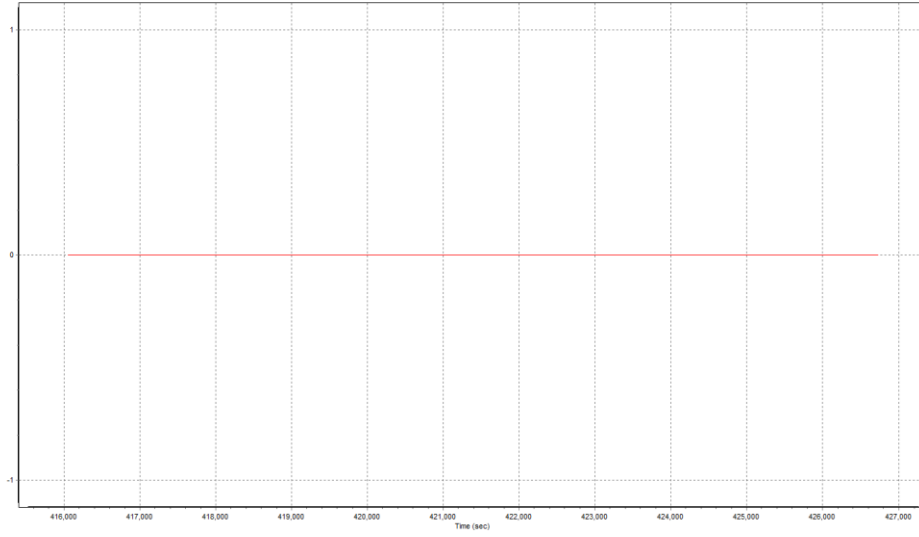


North (m)  
  East (m)  
  Down (m)  
  DR mode  
**PDOP**



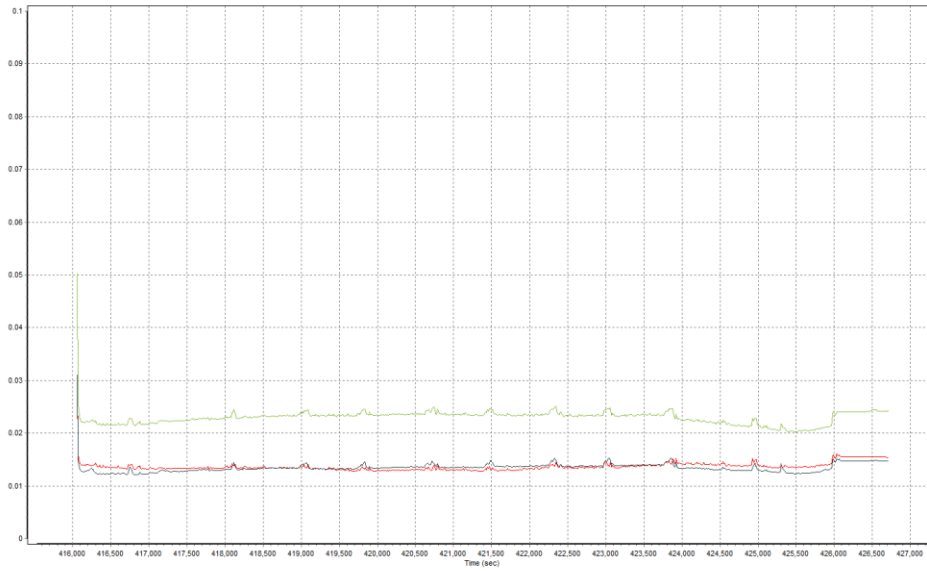
Forward  
  Reverse

Processing mode

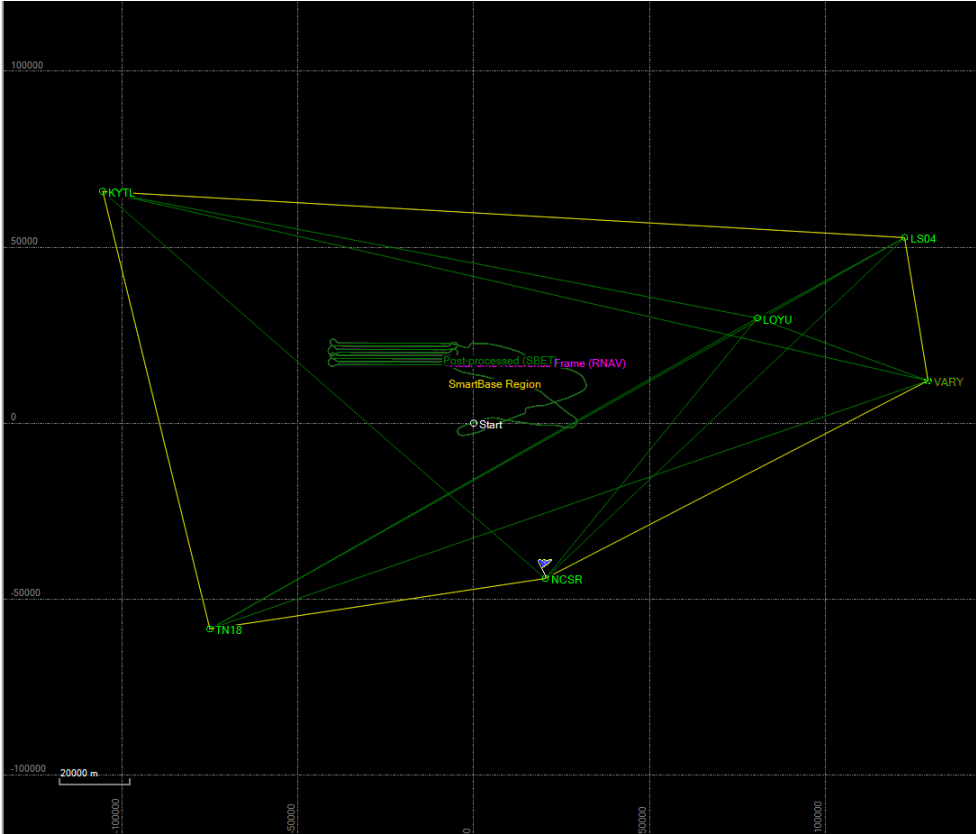


0 = Fixed NL, 1 = Fixed VL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = uAPPP, 6 = C/A, 7 = GNSS Nav, 8 = DR

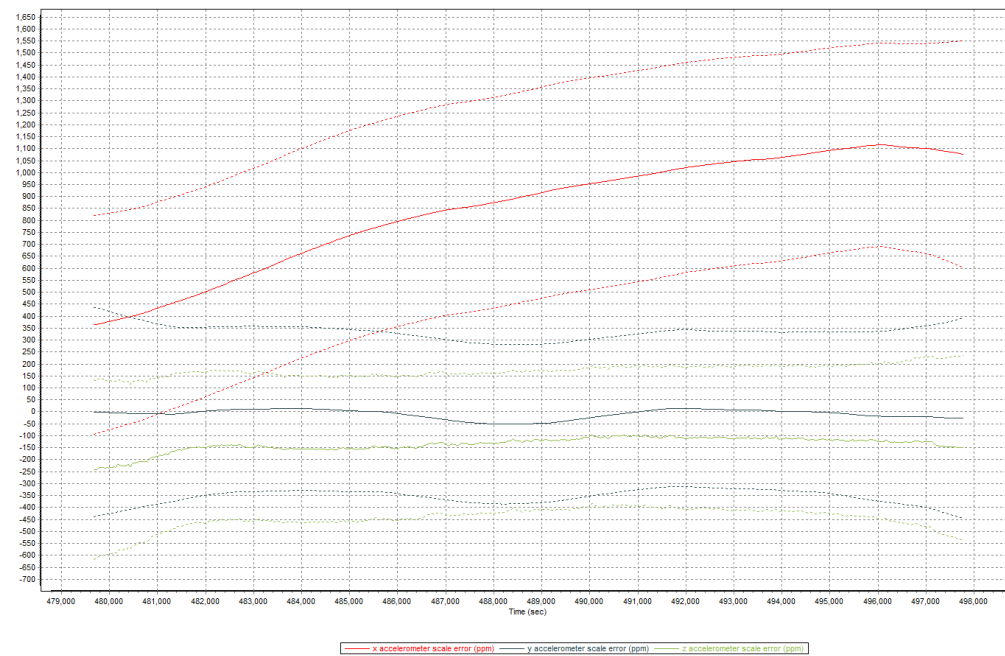
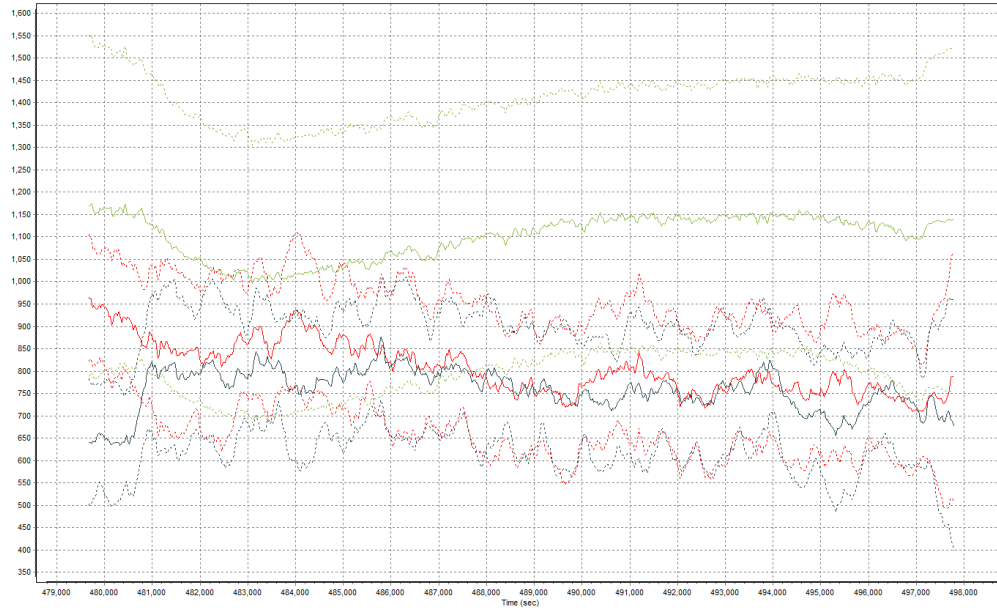
Forward  Reverse



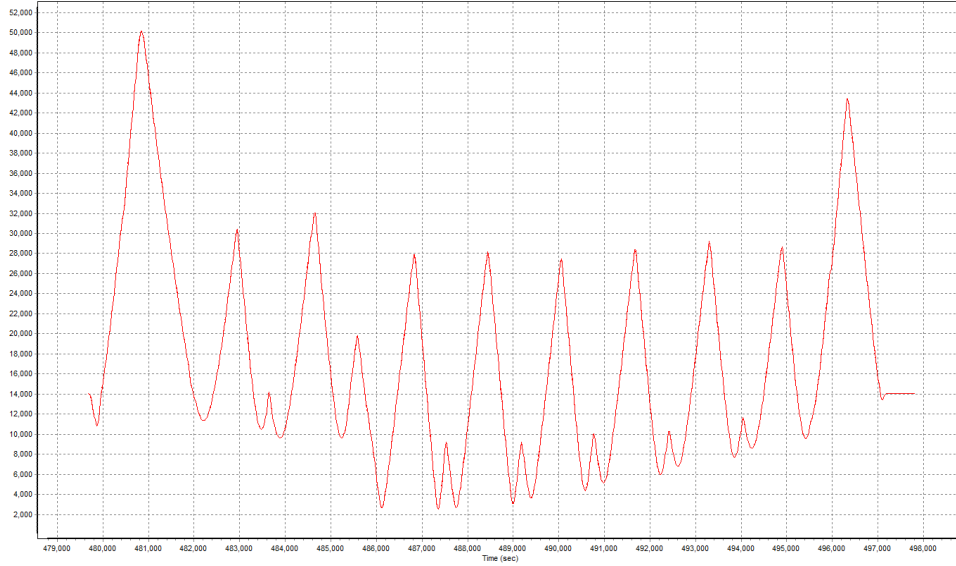
— North Position Error RMS (m) — East Position Error RMS (m) — Down Position Error RMS (m)



**UB16323A**

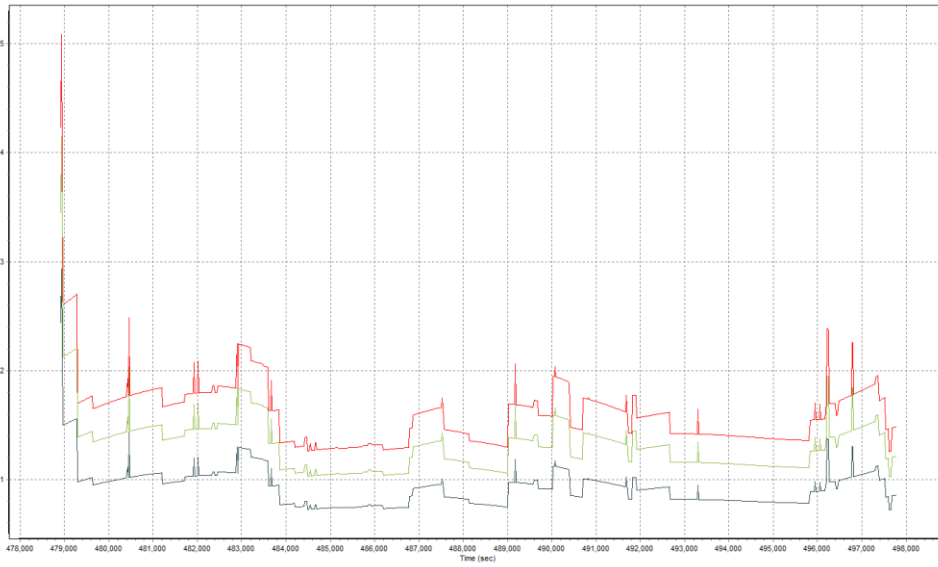


Baseline Length (m)



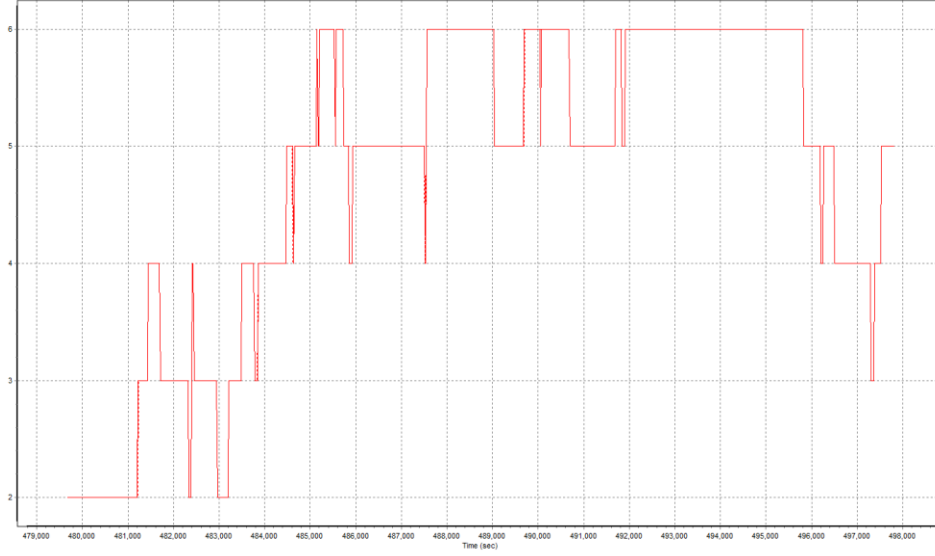
Forward  Reverse

DOP



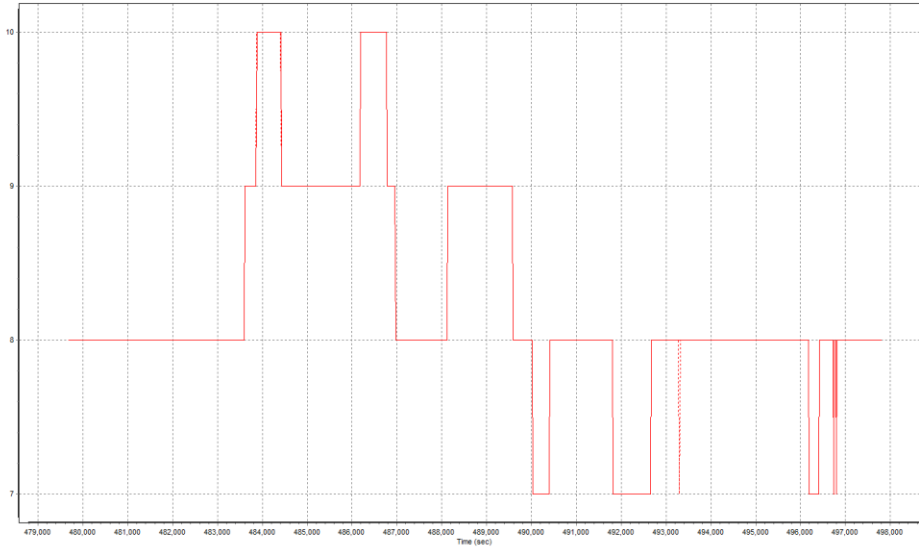
PDOP  HDOP  VDOP

Number of GLONASS Satellites



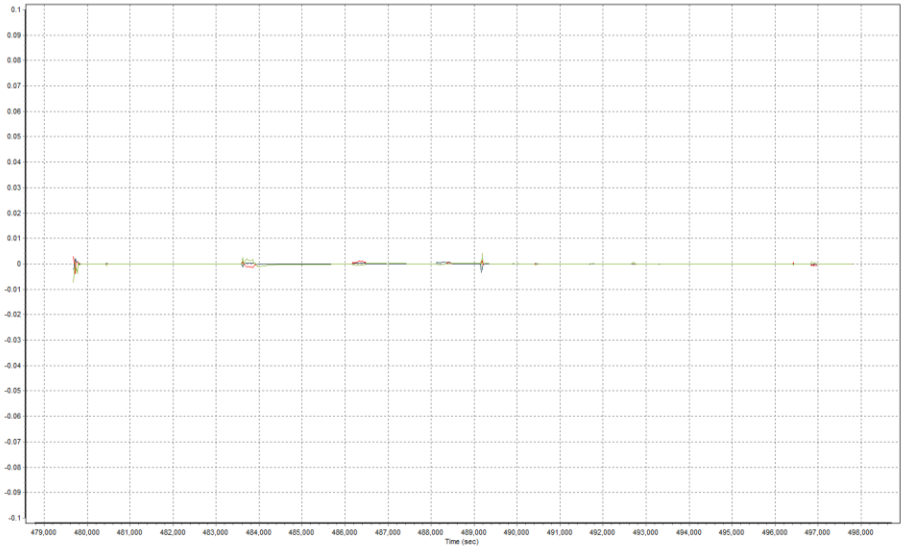
Forward  Reverse

Number of GPS Satellites



Forward  Reverse





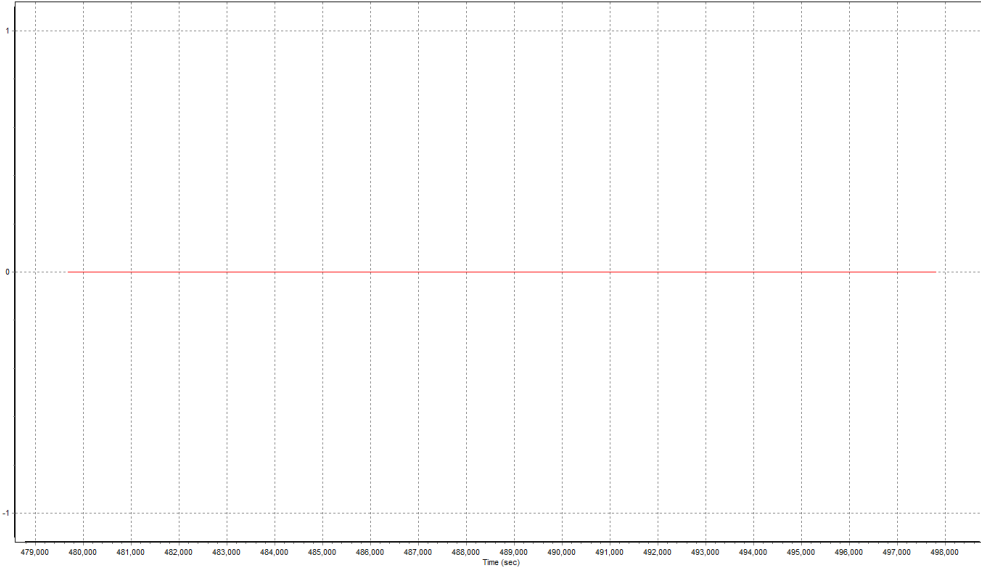
North (m) East (m) Down (m) DR mode

PDOP



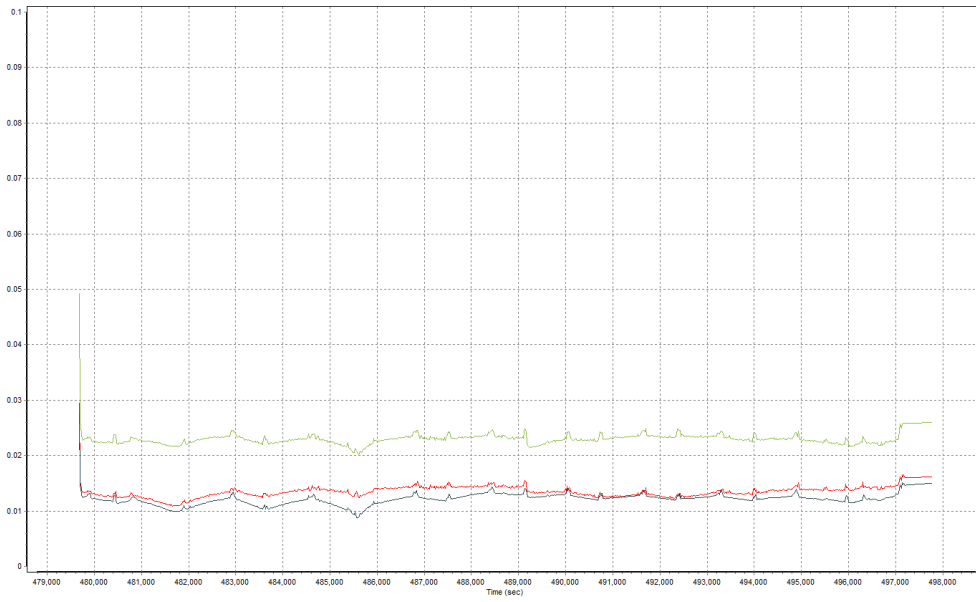
Forward Reverse

Processing mode

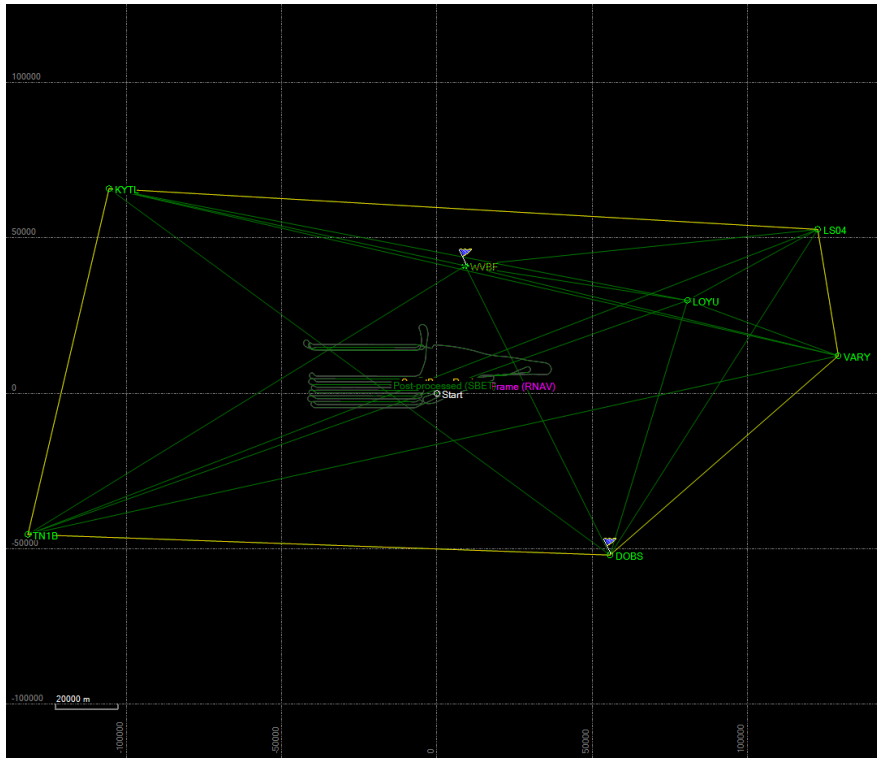


0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGSS, 4 = RTCM, 5 = IAPPP, 6 = CIA, 7 = GNSS Nav, 8 = DR

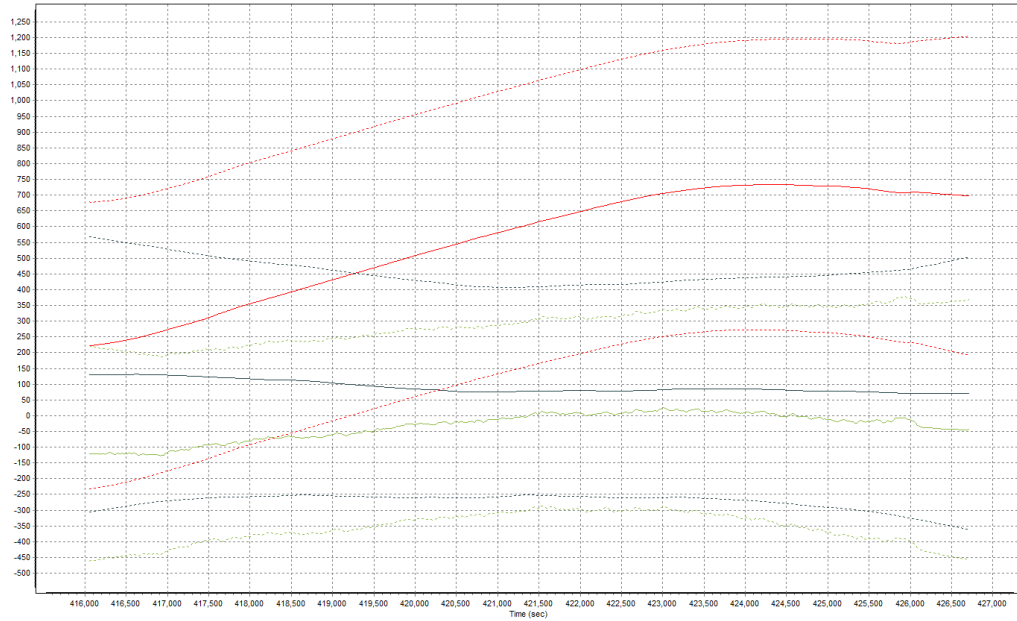
Forward  Reverse



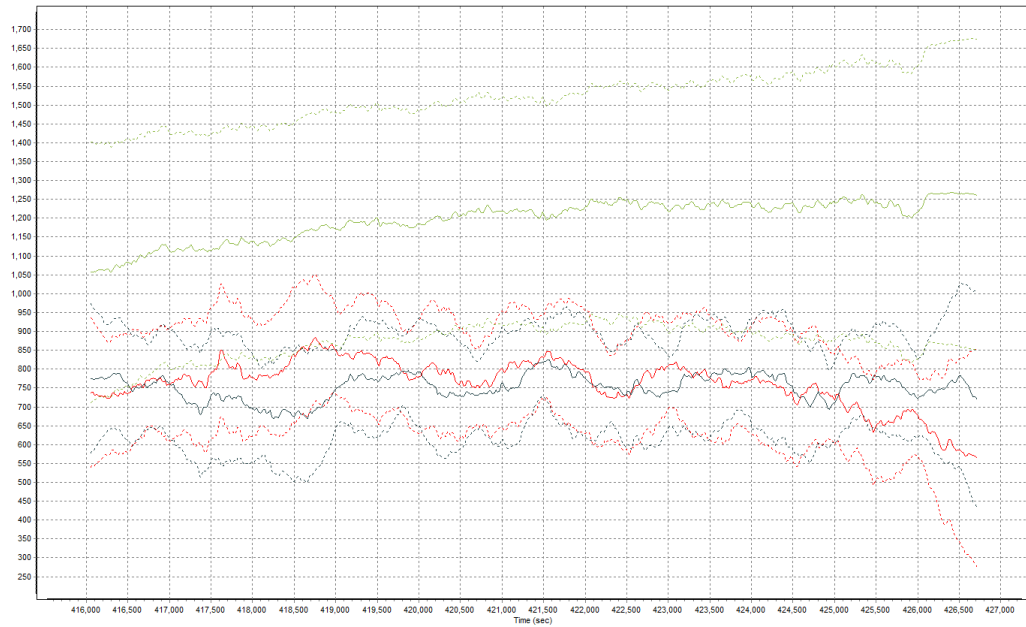
North Position Error RMS (m) East Position Error RMS (m) Down Position Error RMS (m)



# UNB16323B

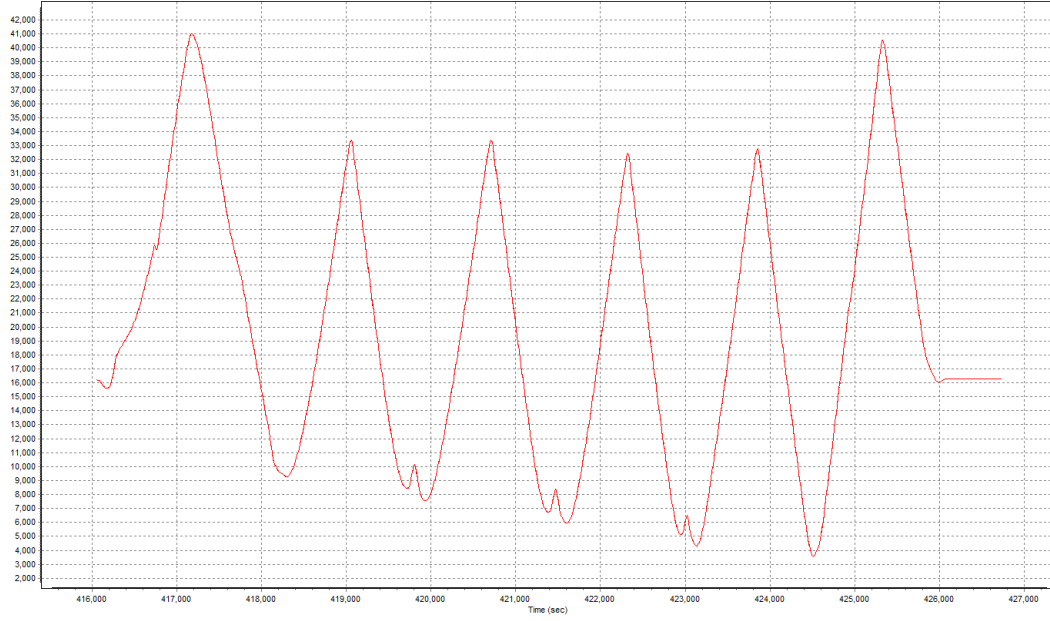


— x accelerometer scale error (ppm) — y accelerometer scale error (ppm) — z accelerometer scale error (ppm)



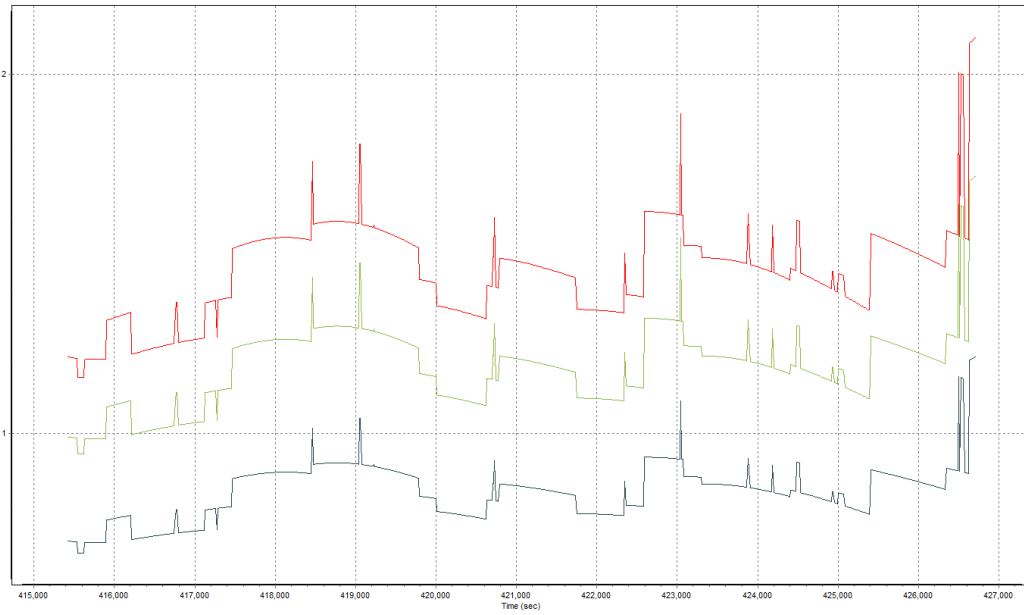
— x accelerometer bias (micro-g) — y accelerometer bias (micro-g) — z accelerometer bias (micro-g)

Baseline Length (m)



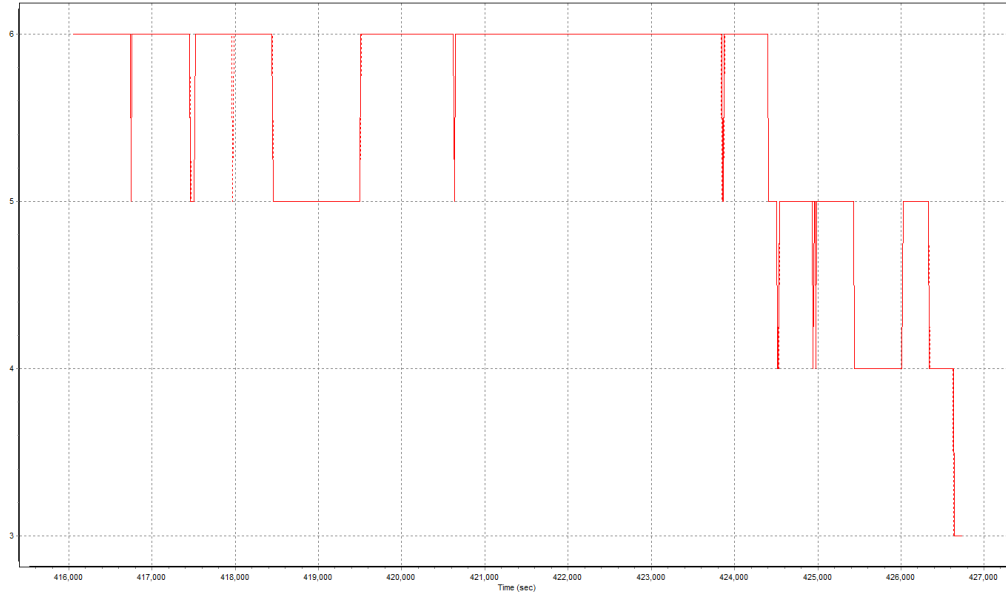
Forward  Reverse

DOP



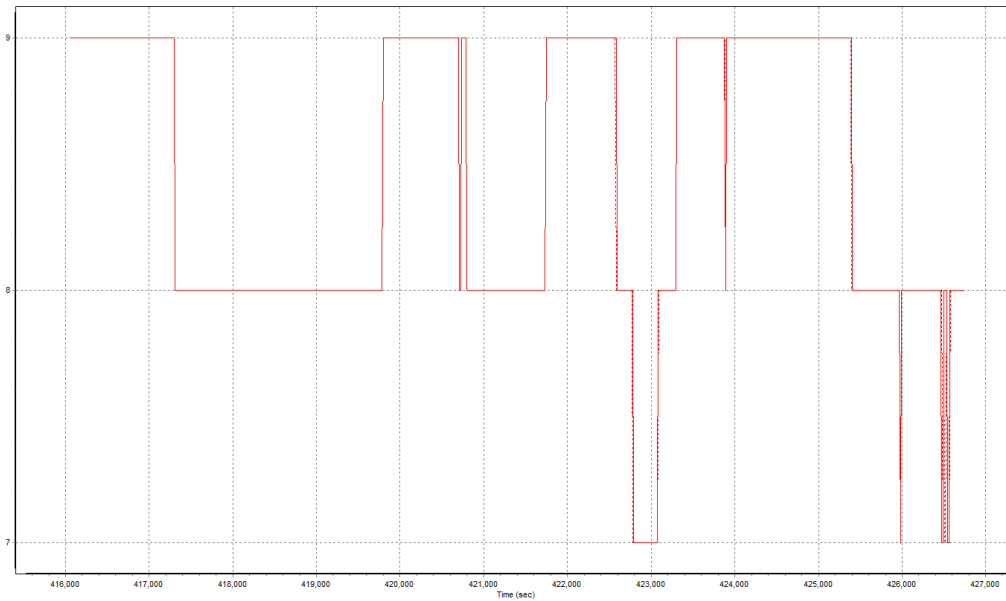
PDOP  HDOP  VDOP

Number of GLONASS Satellites

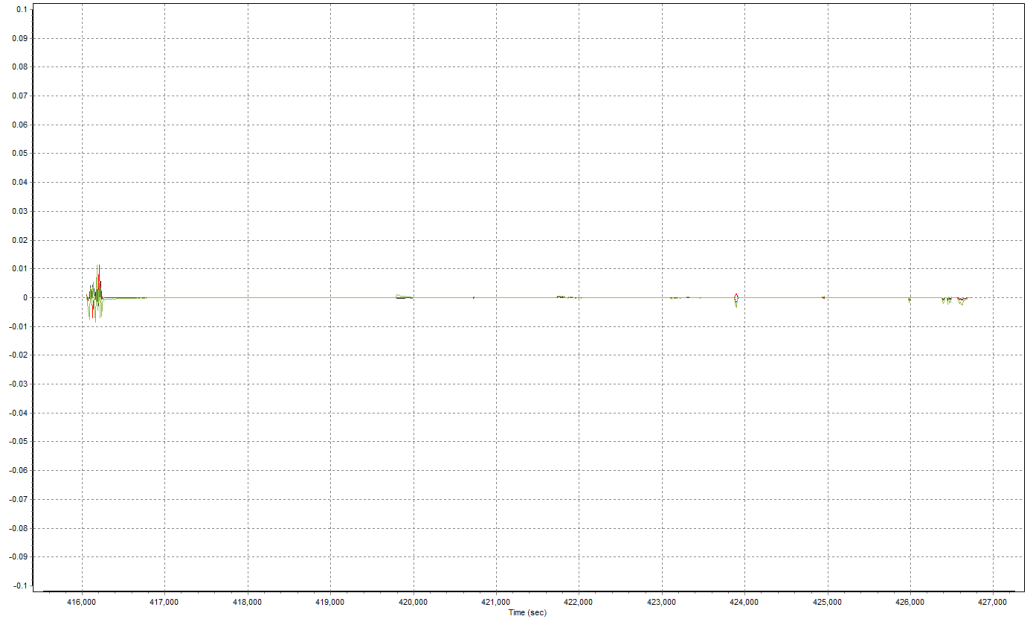


Forward  Reverse

Number of GPS Satellites



Forward  Reverse

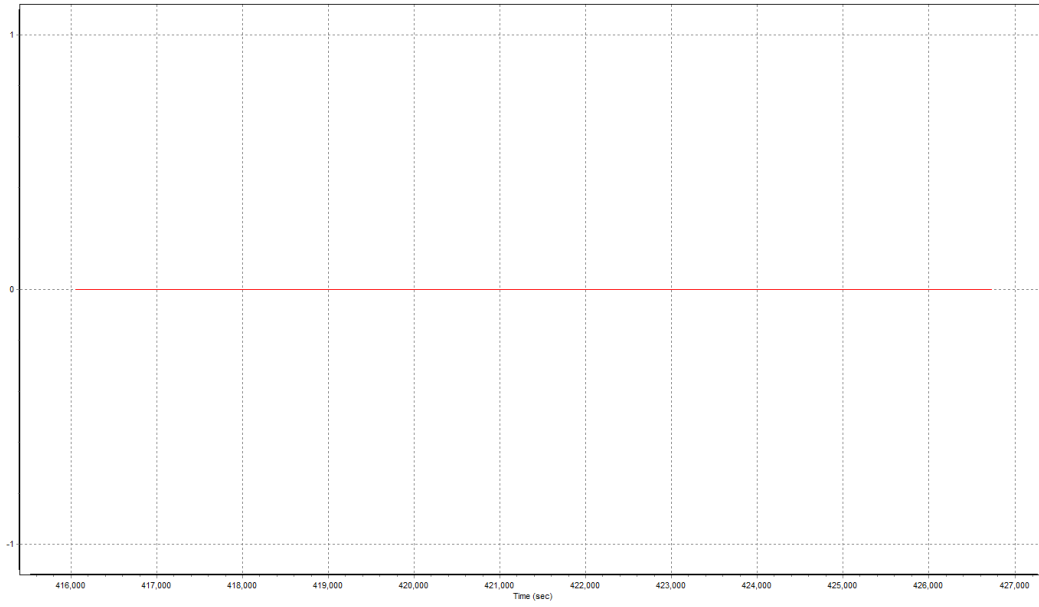


North (m)
  East (m)
  Down (m)
  DR mode



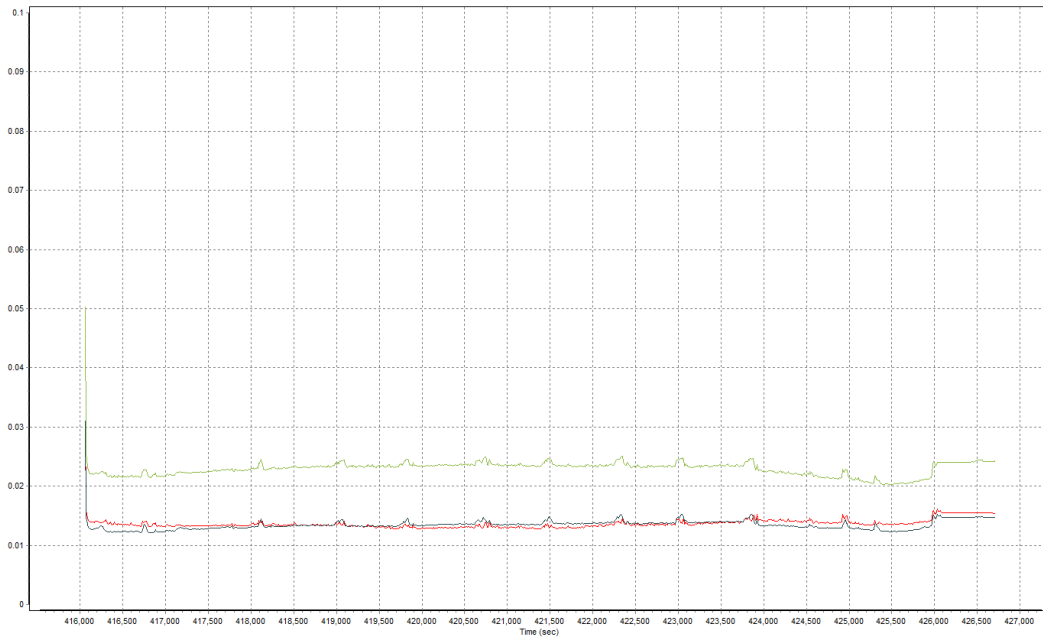
Forward
  Reverse

Processing mode



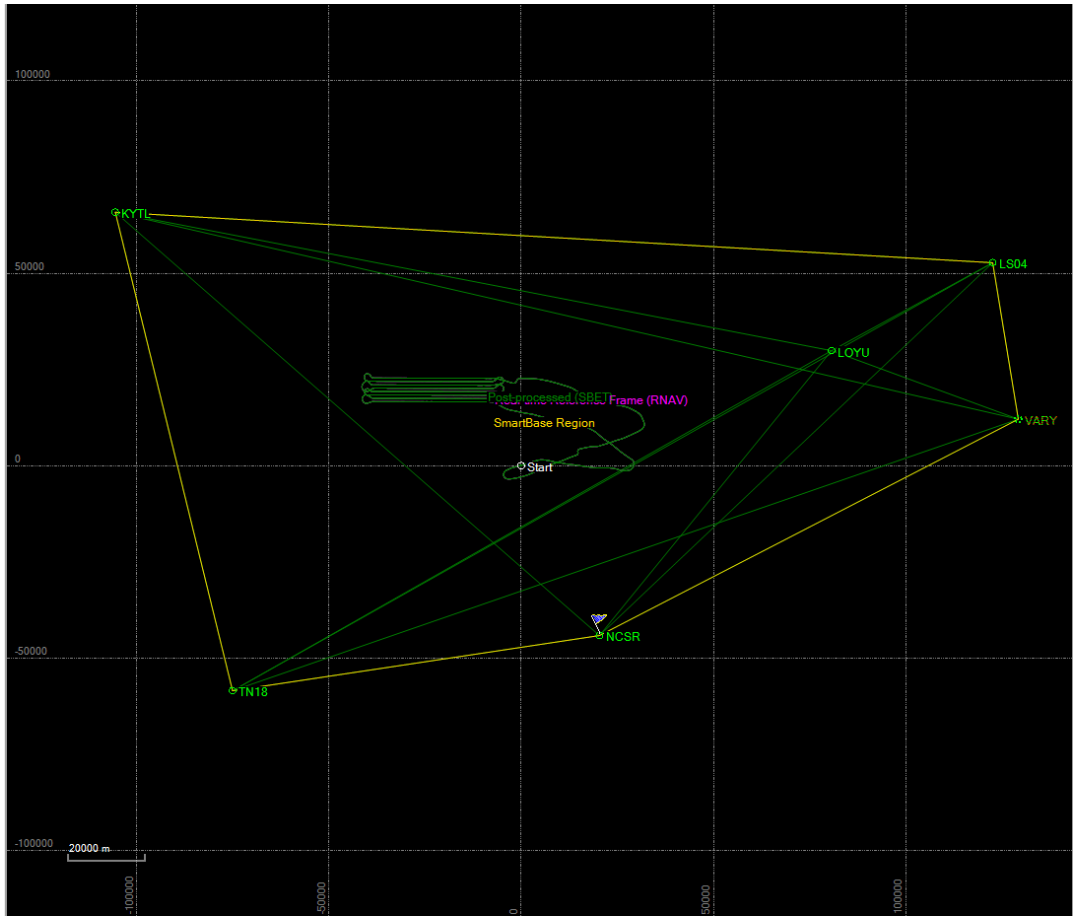
Forward  Reverse

0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = iARPP, 6 = CIA, 7 = GNSS Nav, 8 = DR

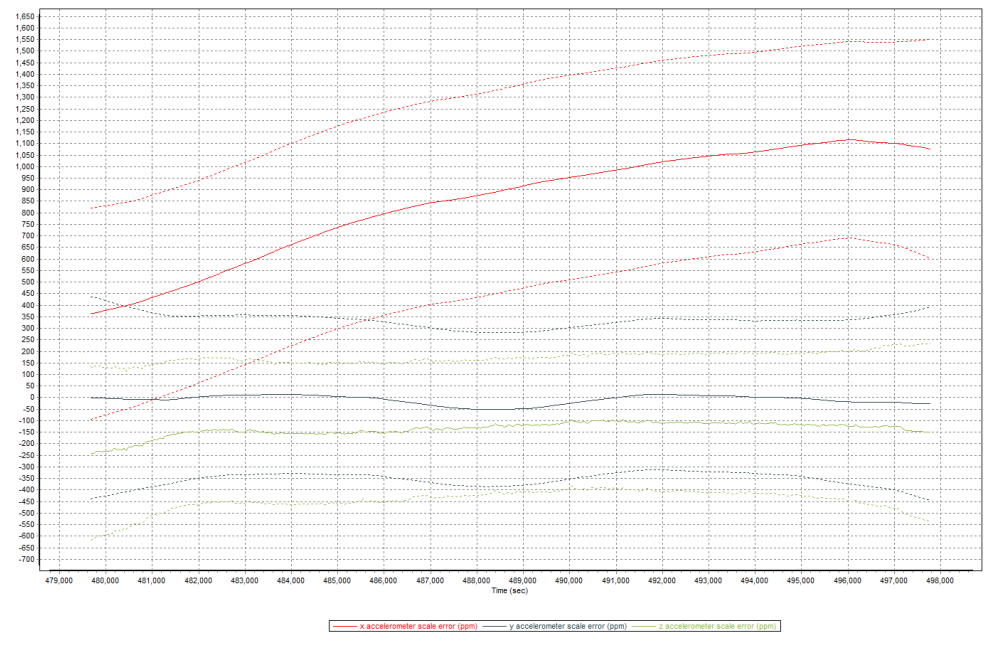
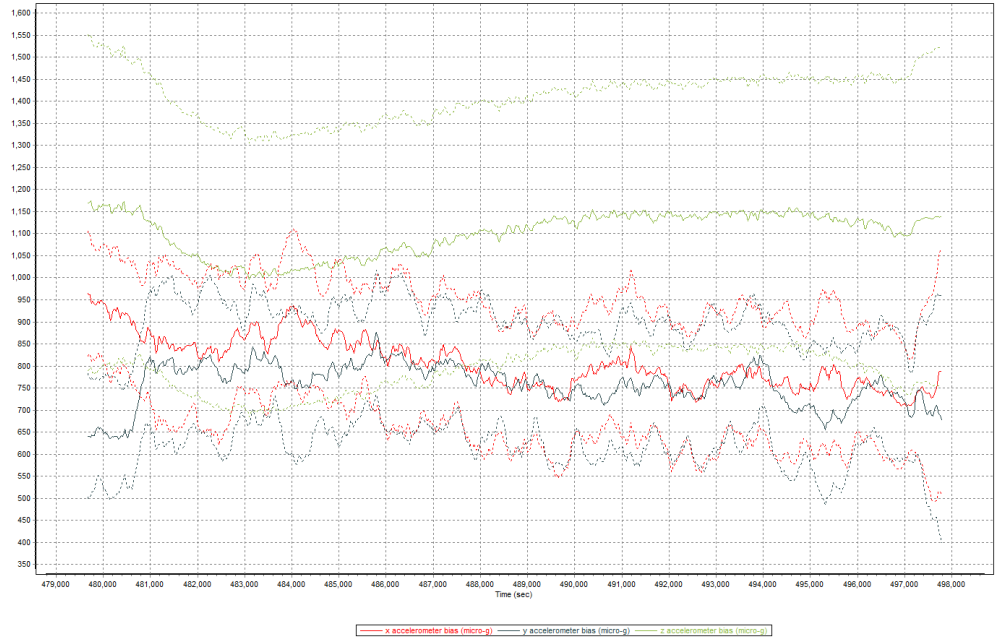


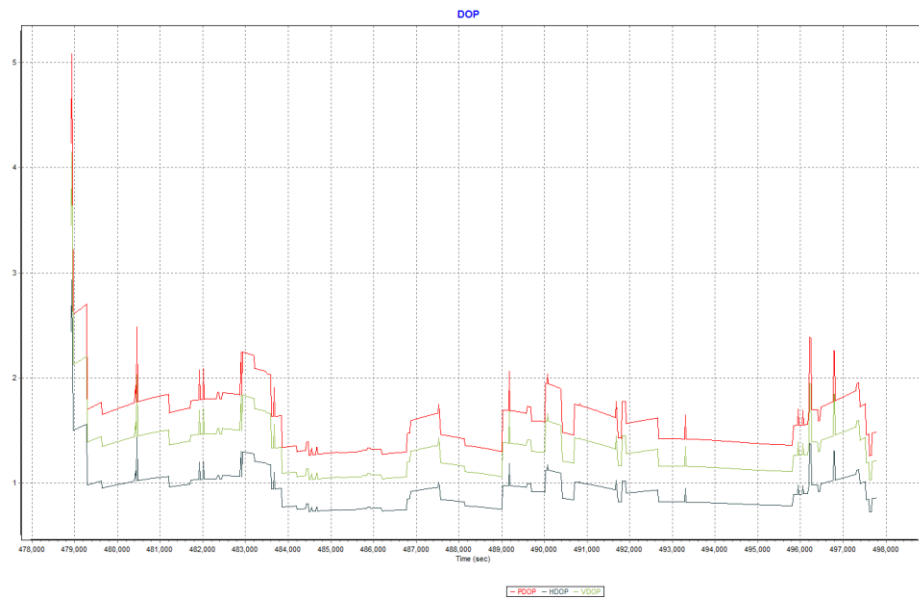
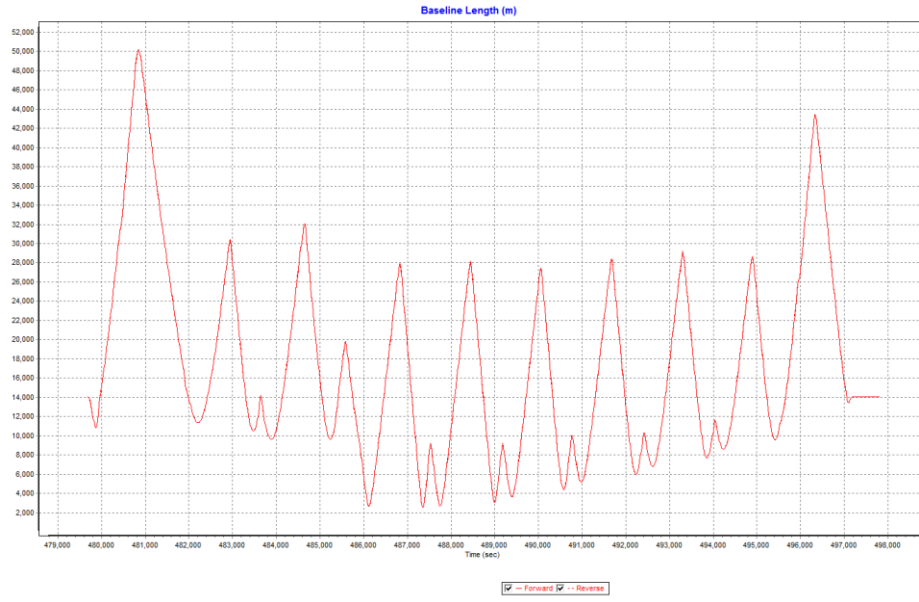
— North Position Error RMS (m) — East Position Error RMS (m) — Down Position Error RMS (m)

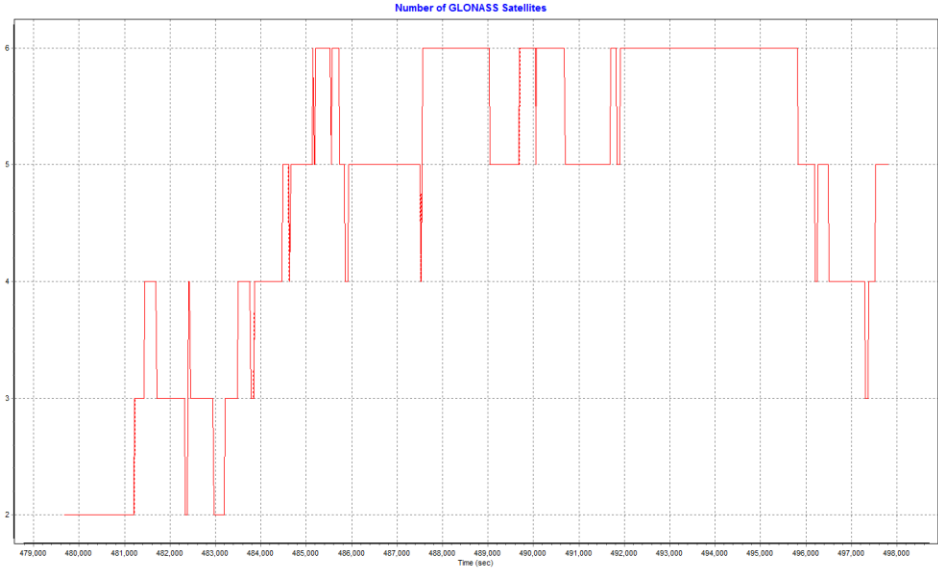




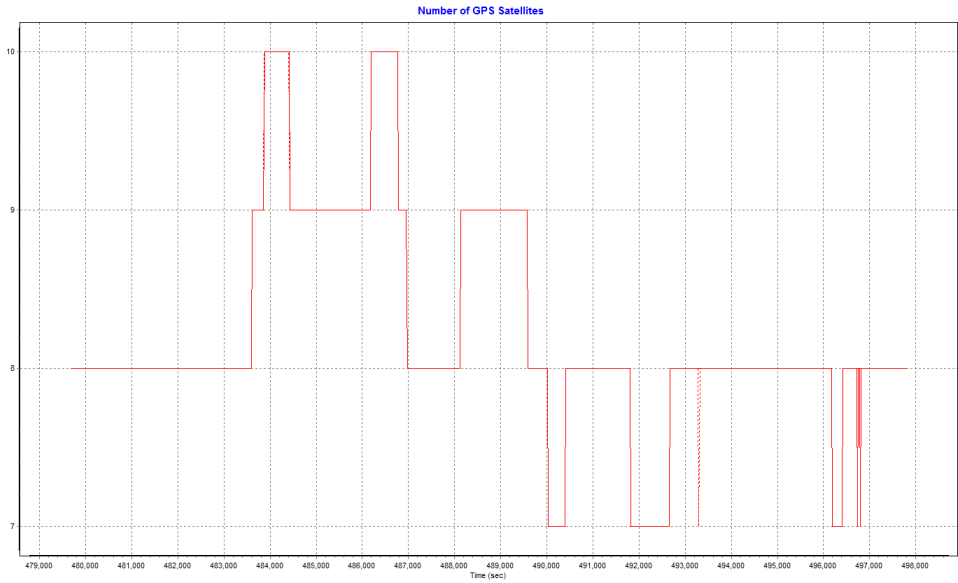
UNB16323A



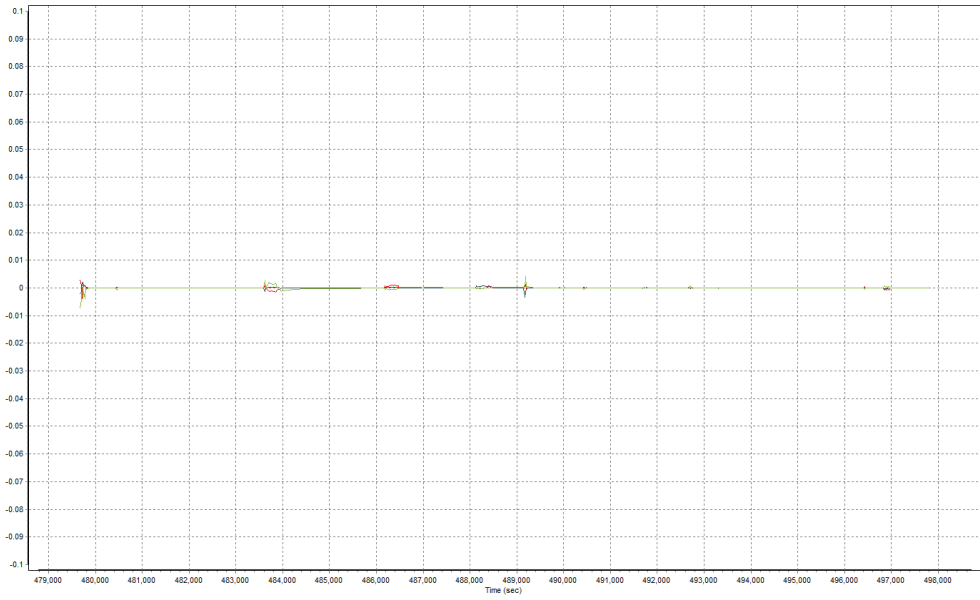




Forward  Reverse

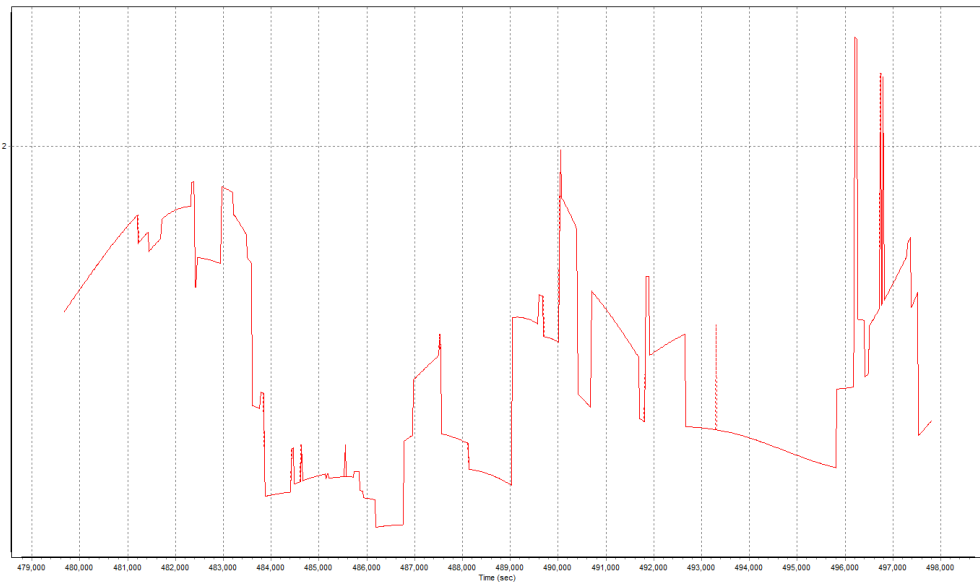


Forward  Reverse



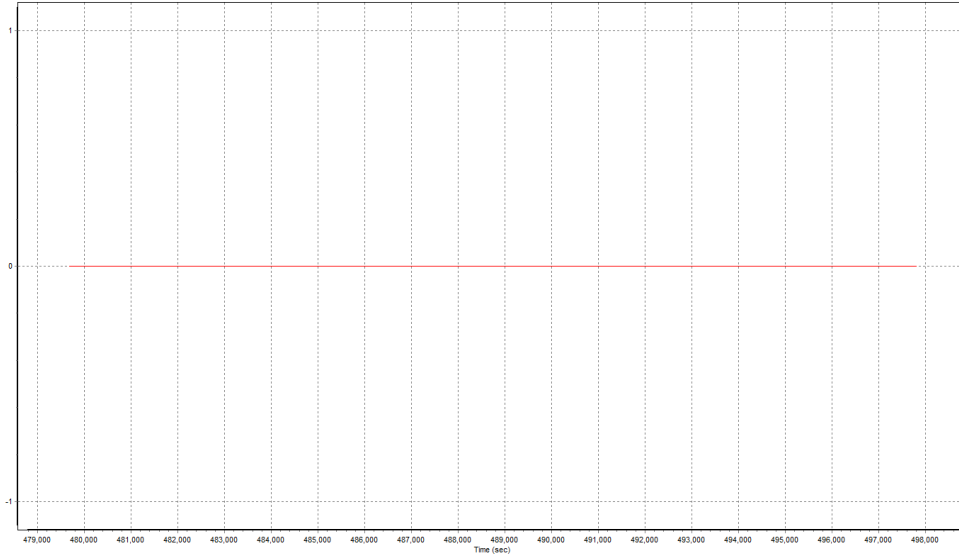
— North (m) — East (m) — Down (m) — DR mode

PDOF



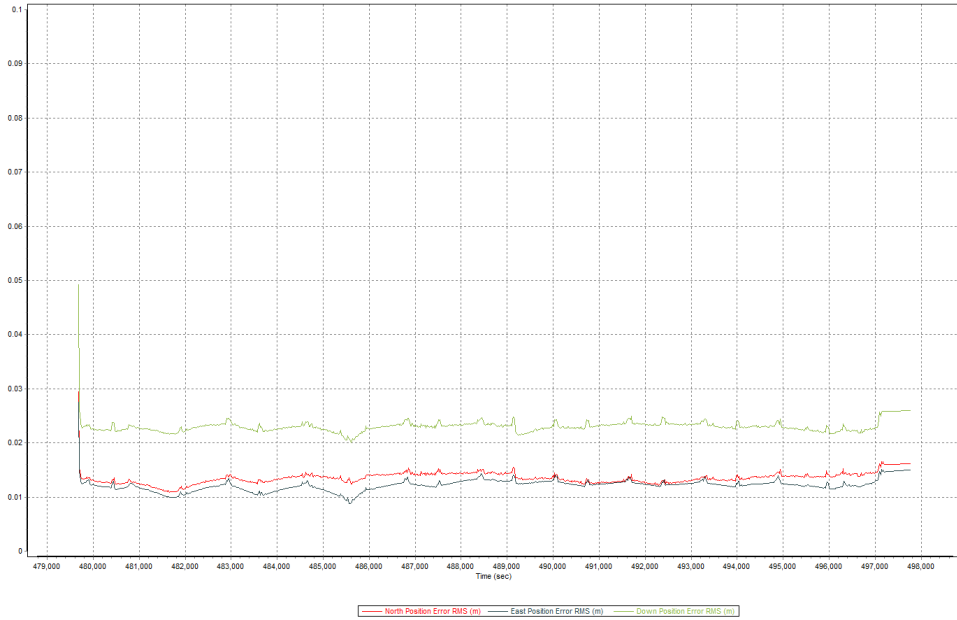
Forward  Reverse

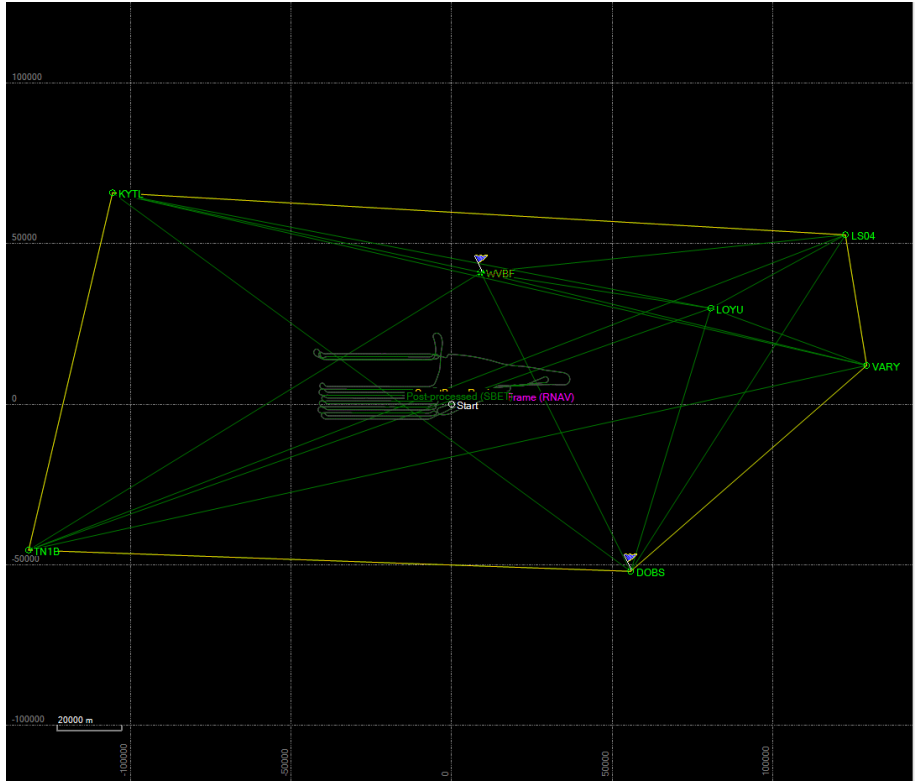
Processing mode



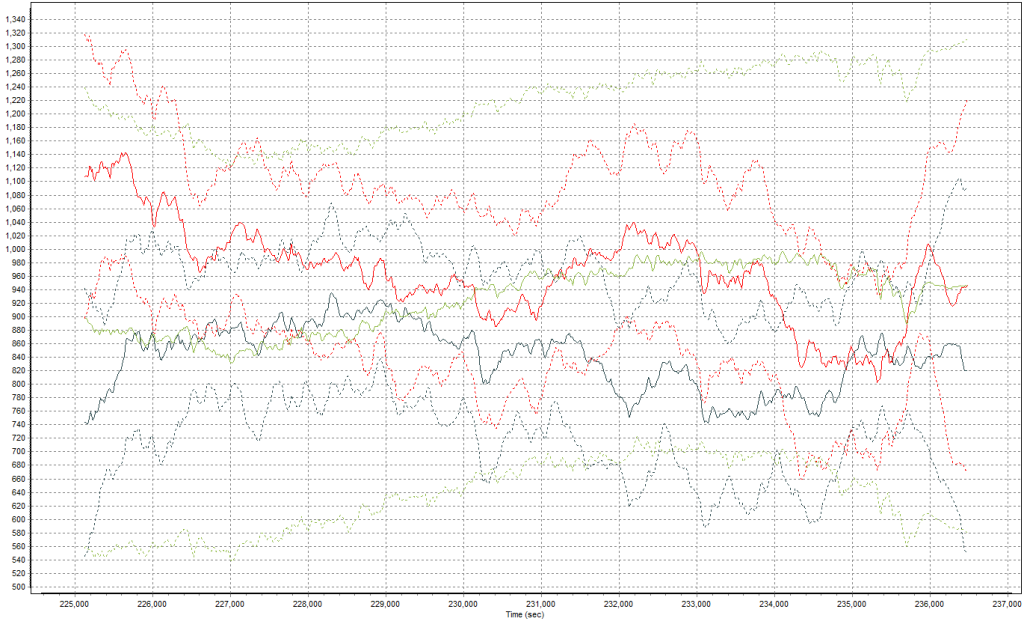
Forward  Reverse

0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNS, 4 = RTCM, 5 = IAPPP, 6 = CIA, 7 = GNSS Nav, 8 = DR

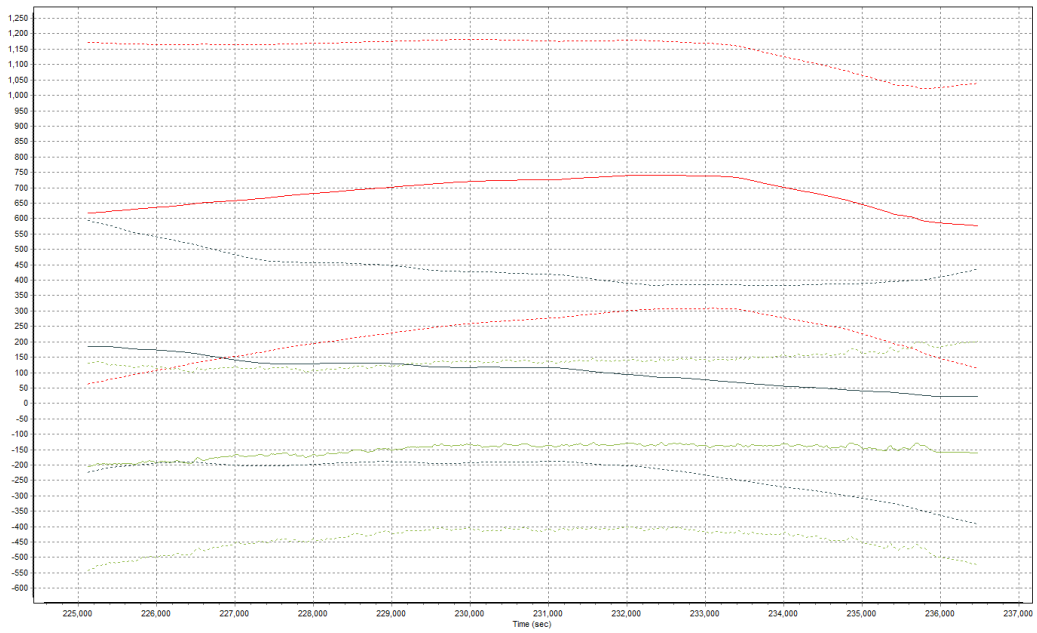




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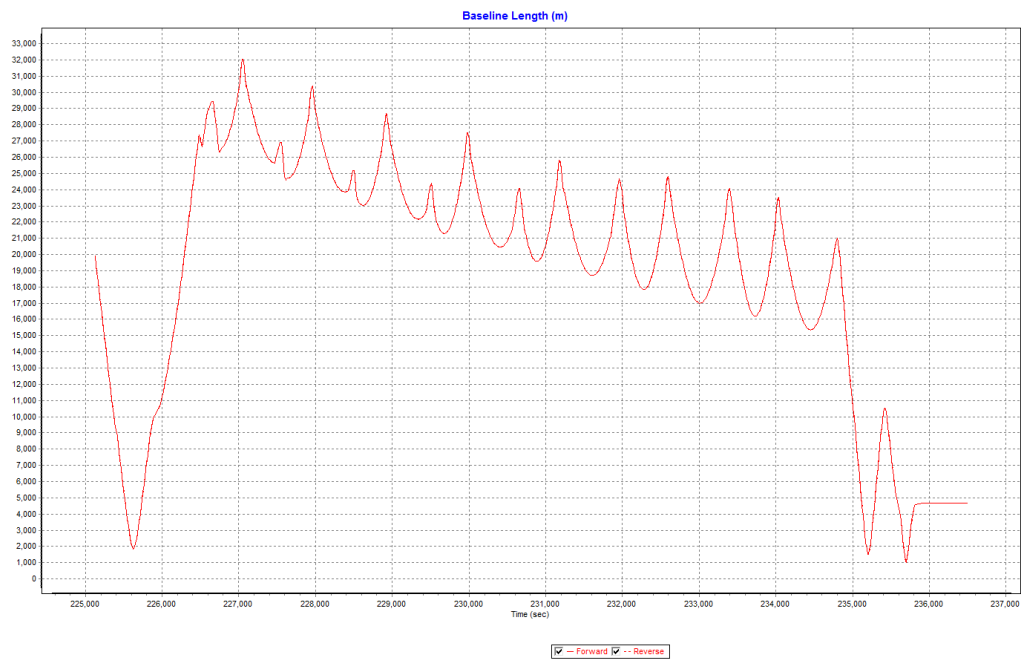
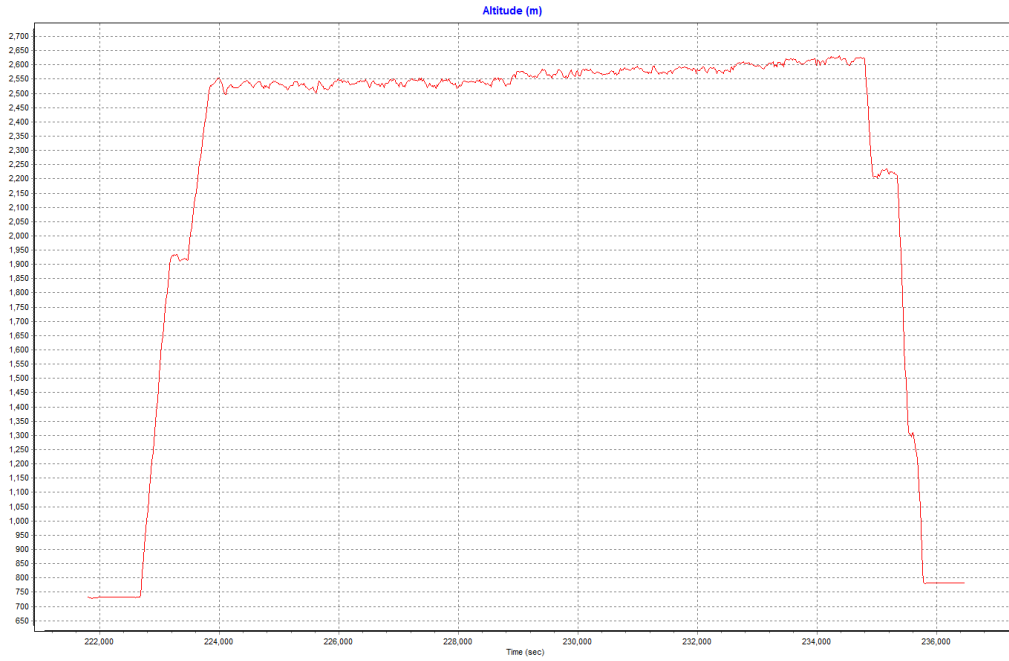


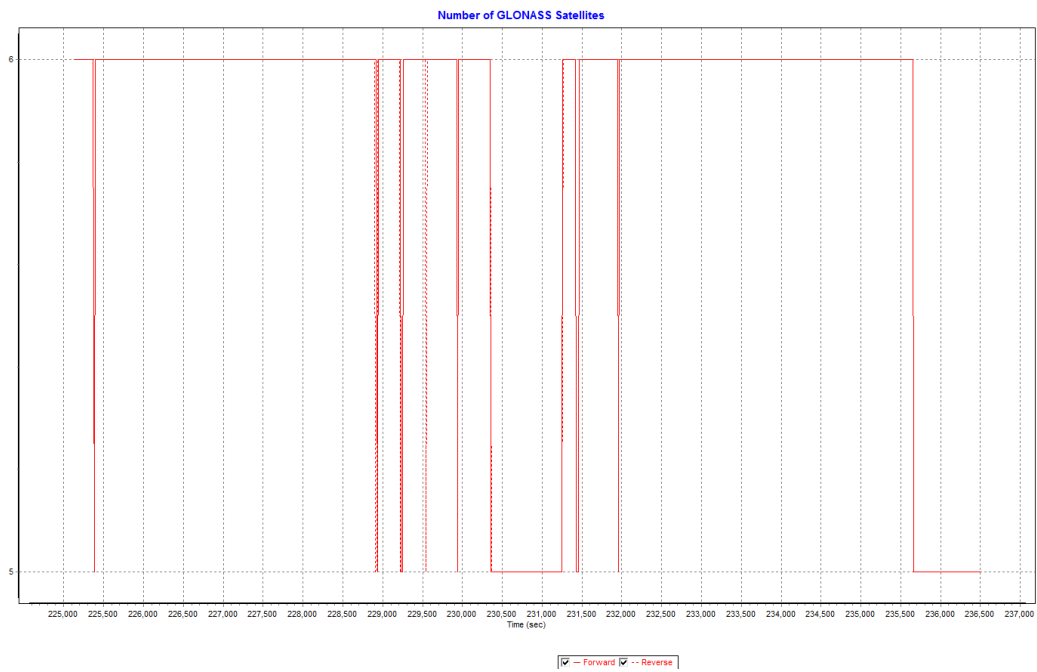
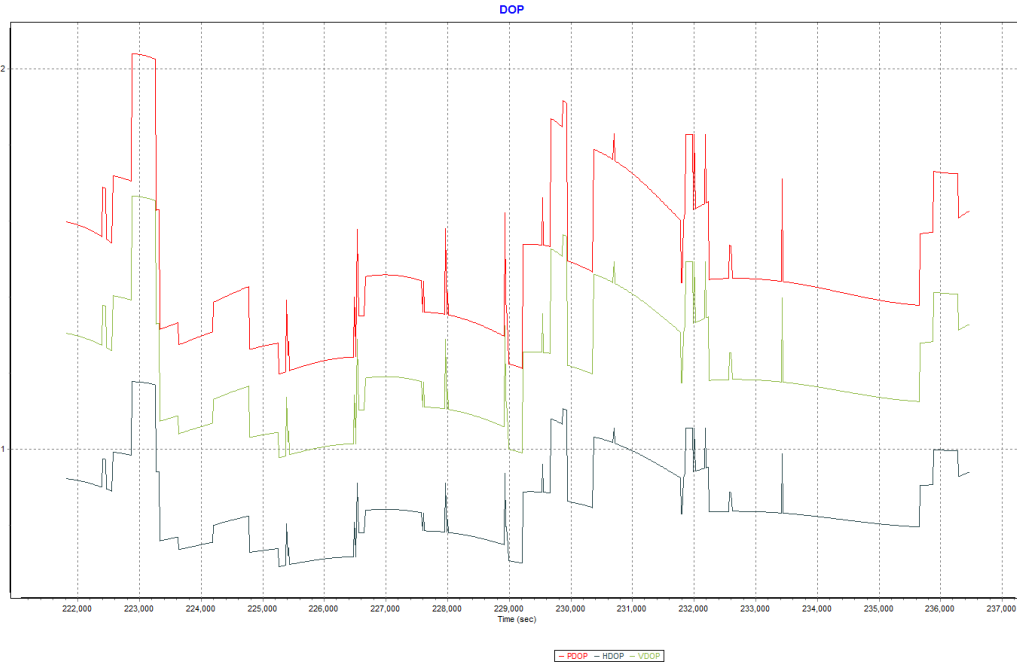
— x accelerometer bias (micro-g) — y accelerometer bias (micro-g) — z accelerometer bias (micro-g)



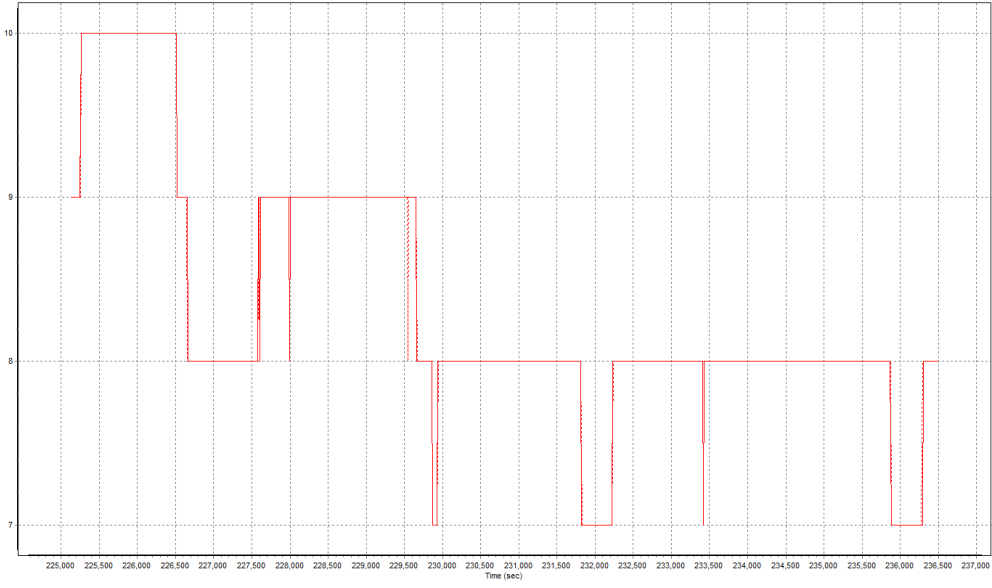
— x accelerometer scale error (ppm) — y accelerometer scale error (ppm) — z accelerometer scale error (ppm)



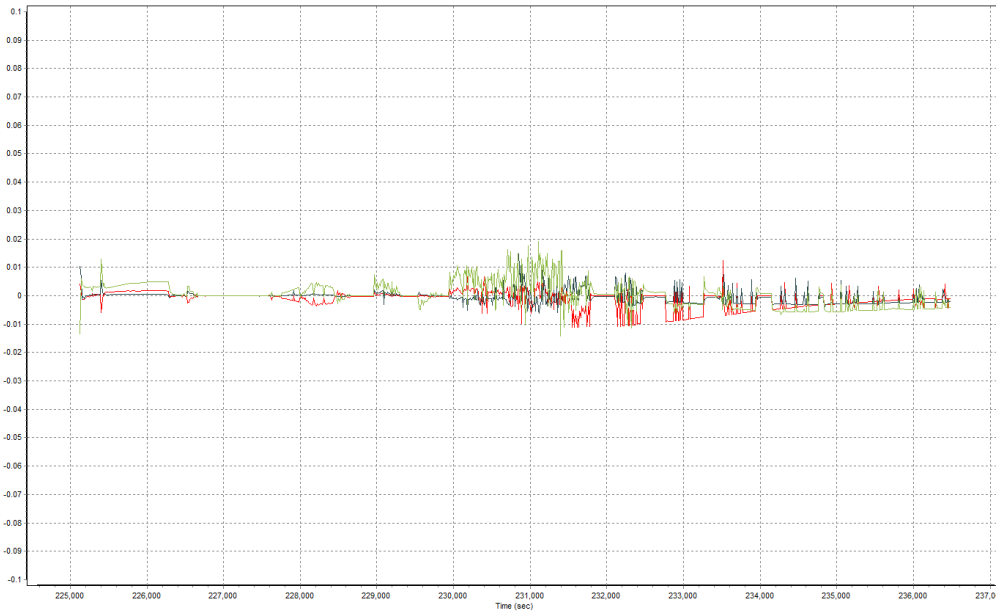




Number of GPS Satellites

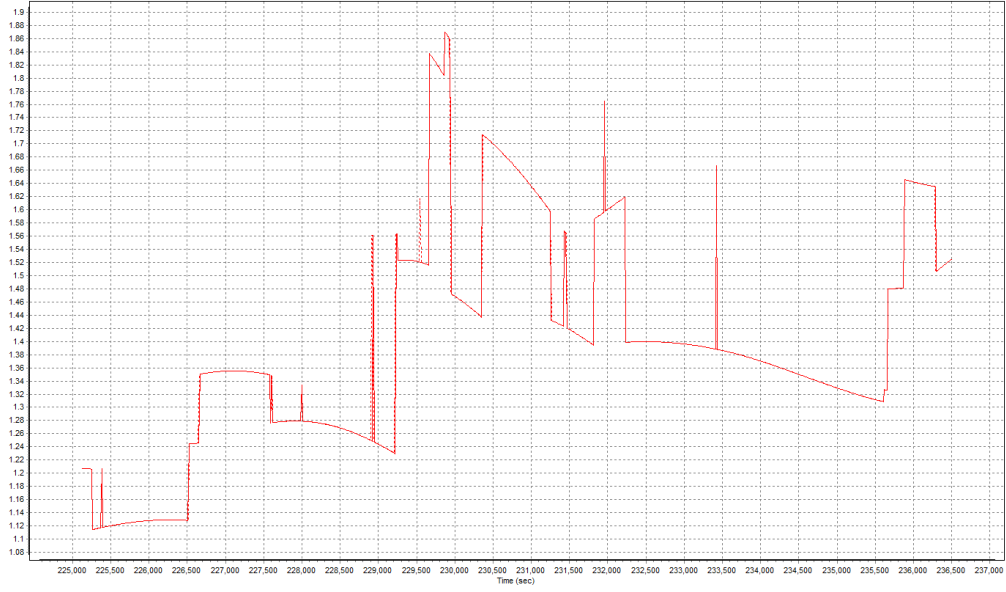


Forward  Reverse



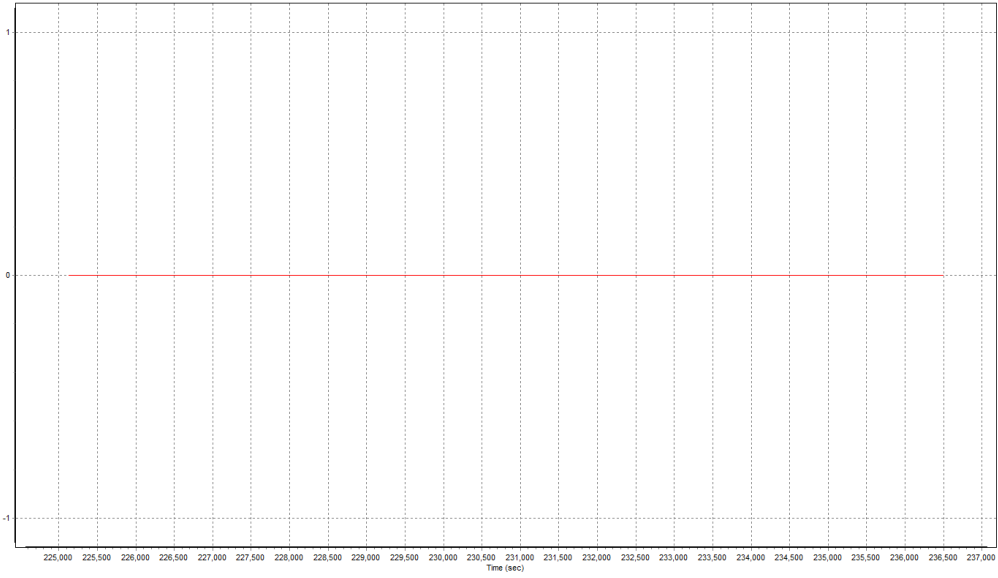
North (m)  East (m)  Down (m)  DR mode

PDOP



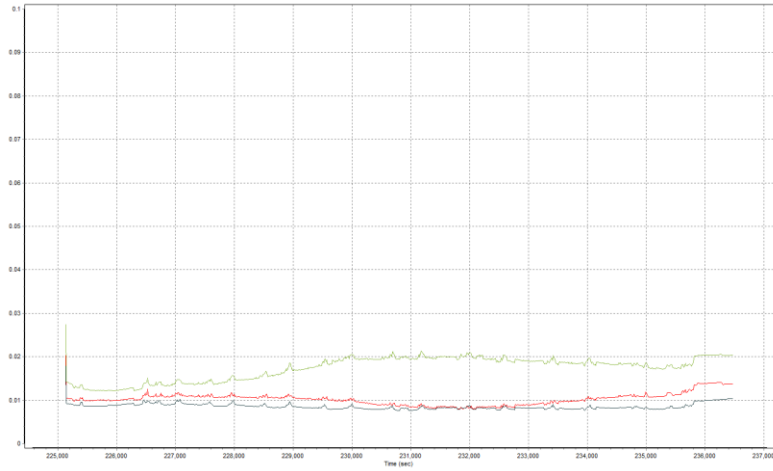
Forward  Reverse

Processing mode

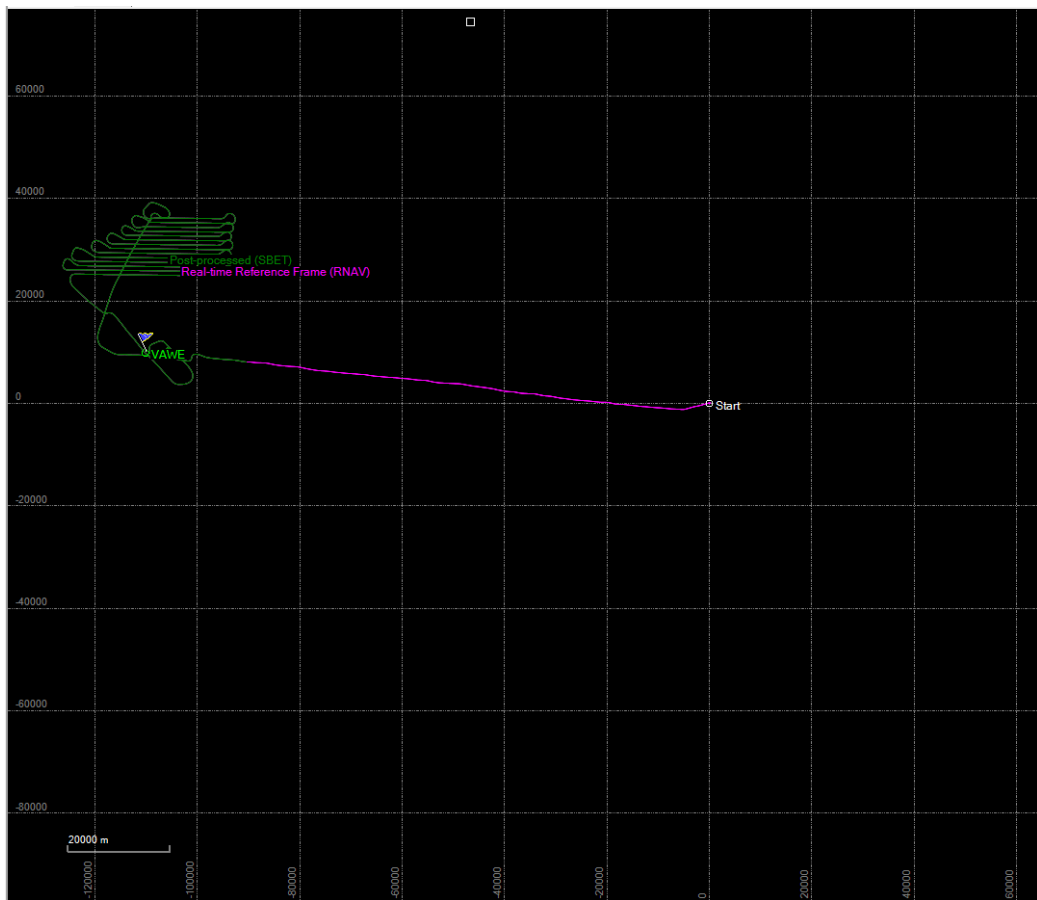


Forward  Reverse

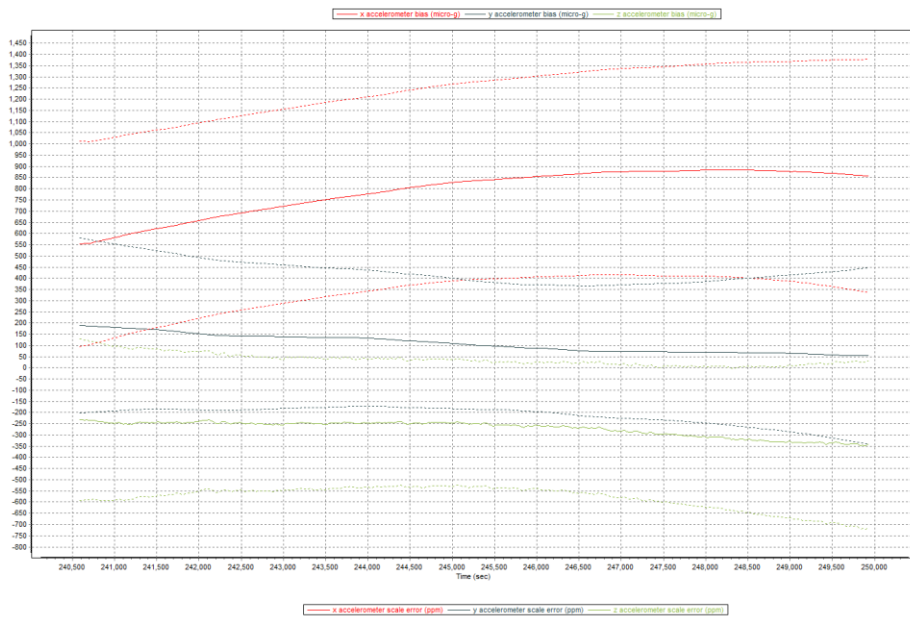
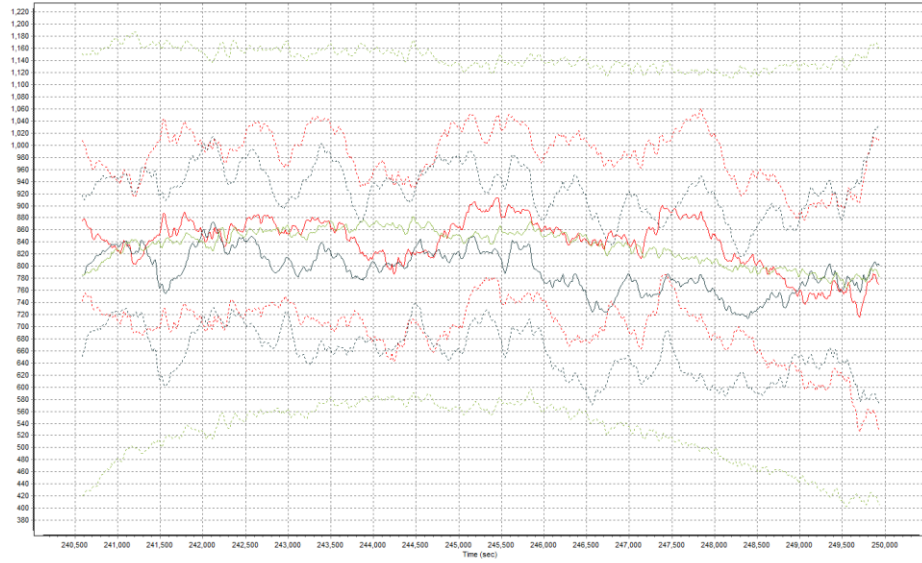
0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGSS, 4 = RTCM, 5 = IAPPP, 6 = CIA, 7 = GNSS Nav, 8 = DR



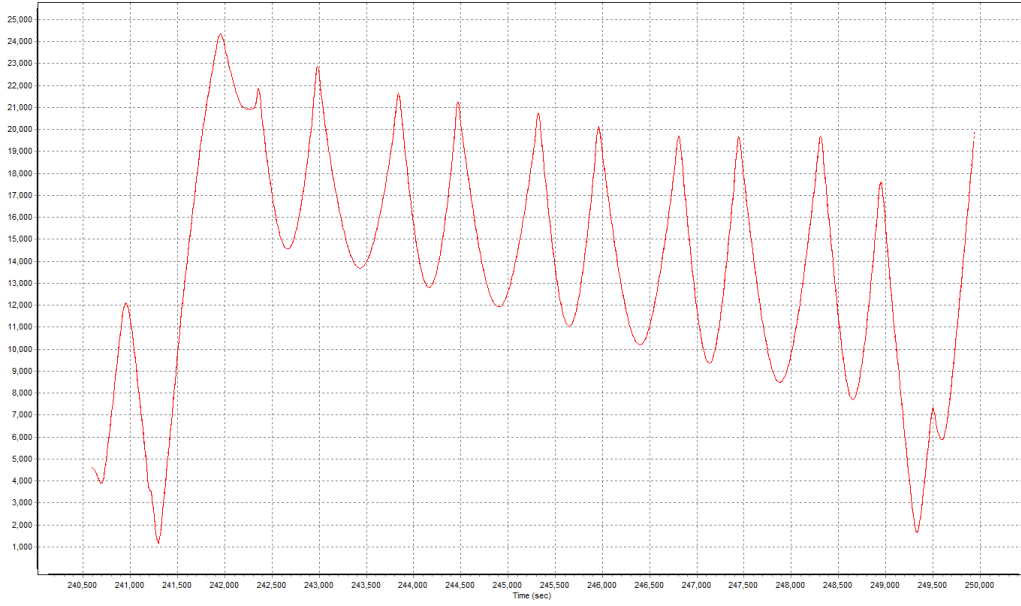
North Position Error RMS (m) East Position Error RMS (m) Down Position Error RMS (m)



UNB16327B

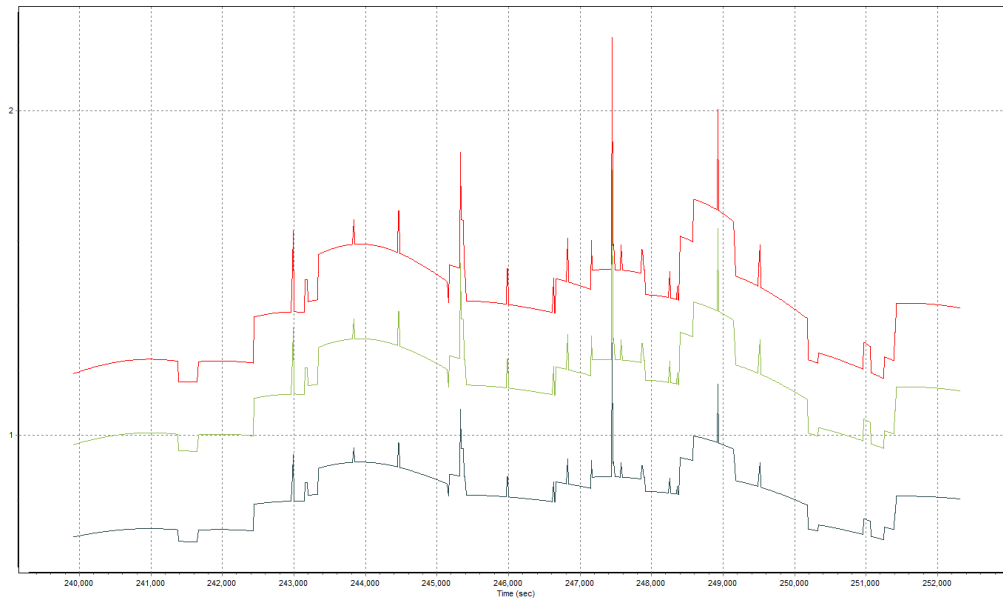


Baseline Length (m)



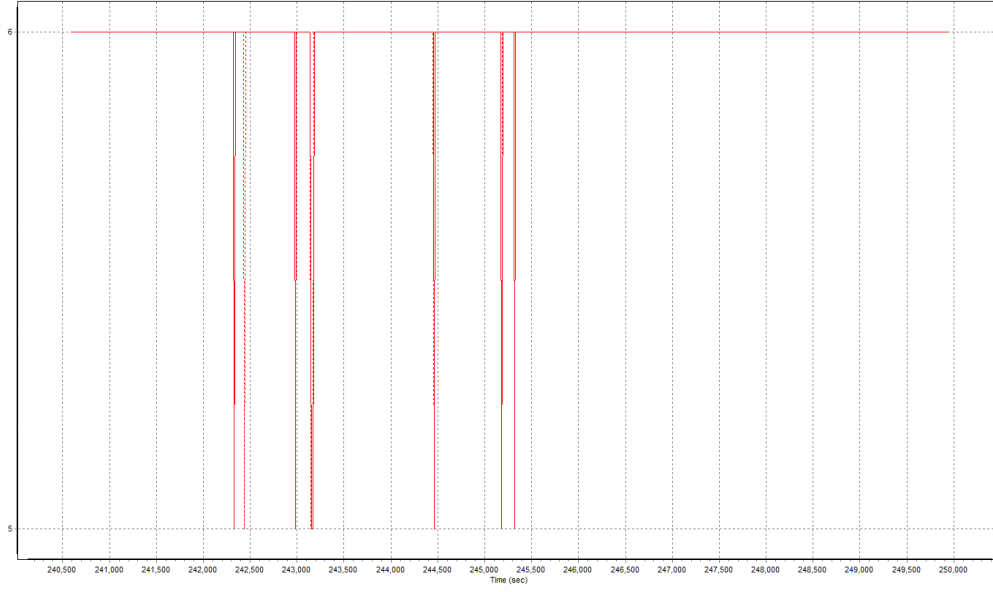
Forward  Reverse

DOP



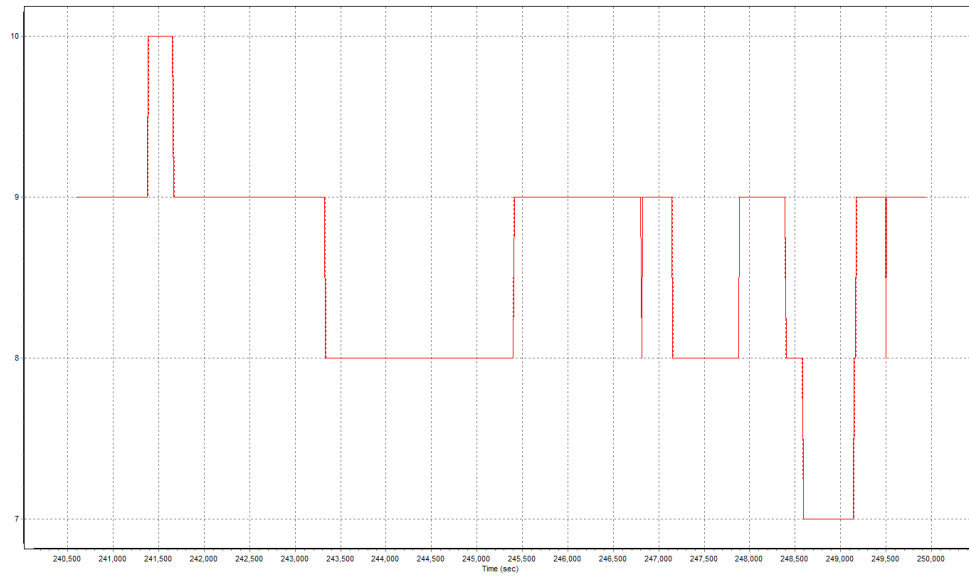
RDOP  HDOP  VDOP

Number of GLONASS Satellites



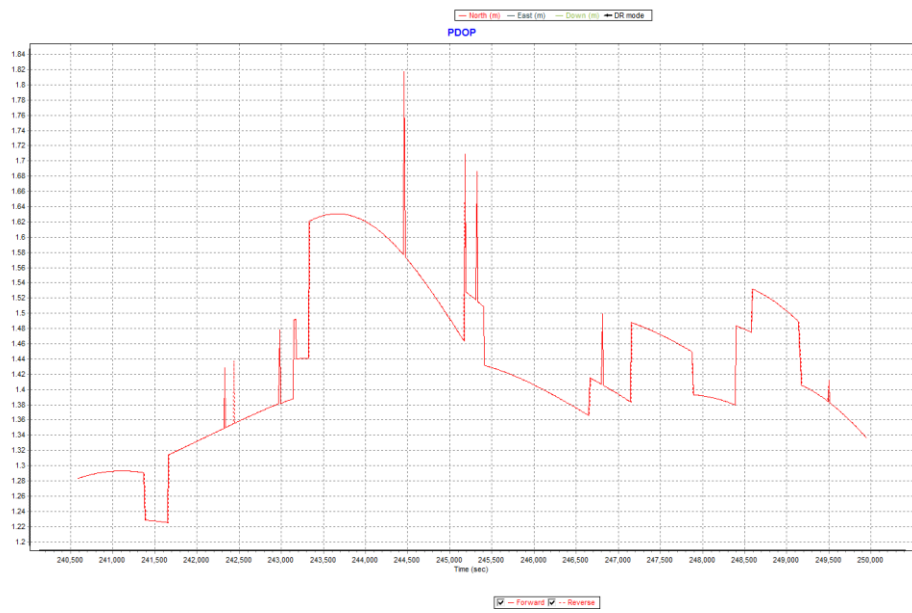
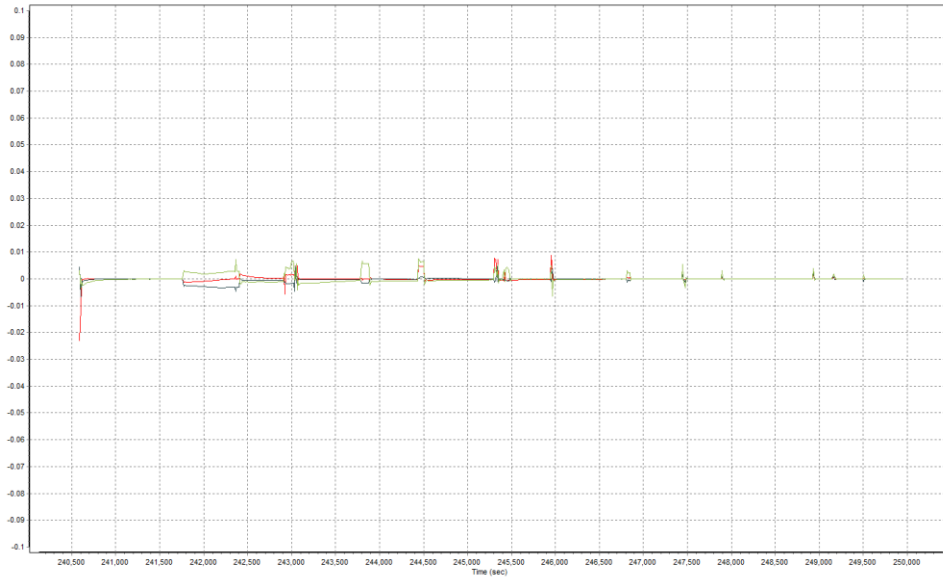
Forward  Reverse

Number of GPS Satellites

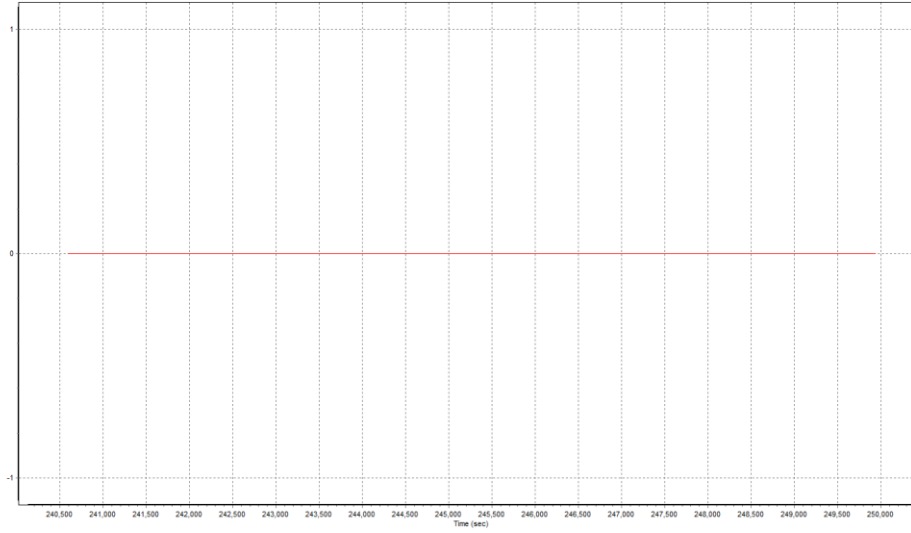


Forward  Reverse



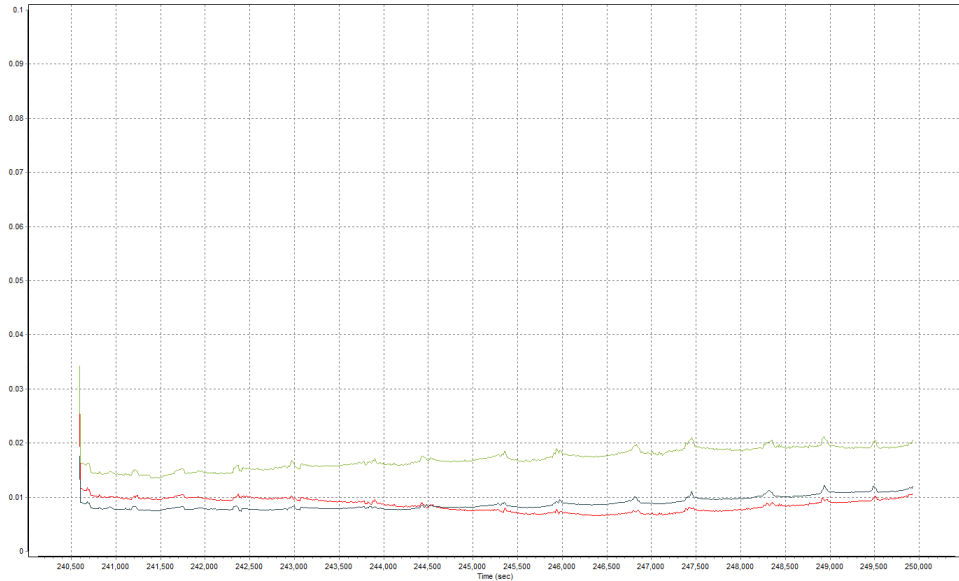


Processing mode

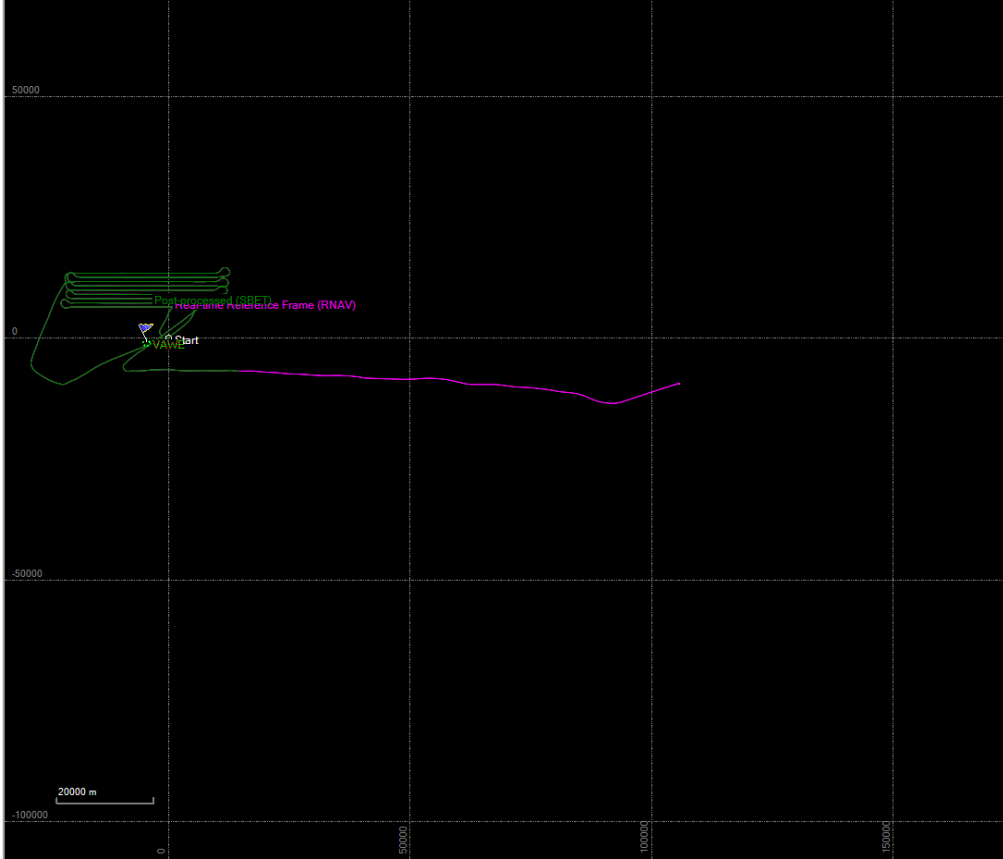


0 = Fixed NL, 1 = Fixed VL, 2 = Float, 3 = GNSS, 4 = RTCM, 5 = IAPPP, 6 = CIA, 7 = GNSS Nav, 8 = DR

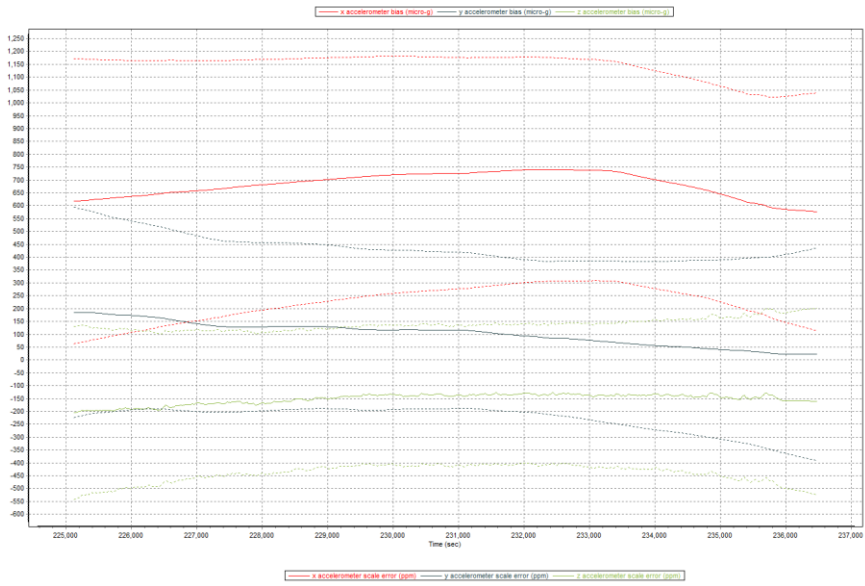
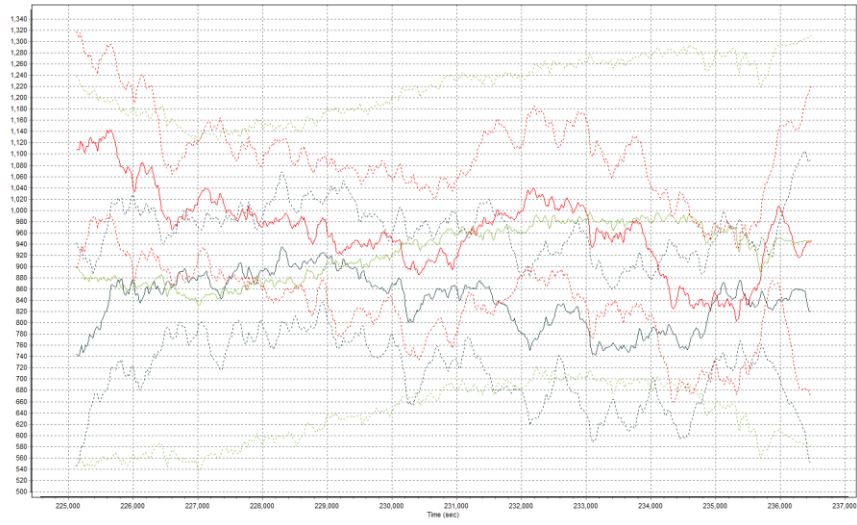
Forward  Reverse

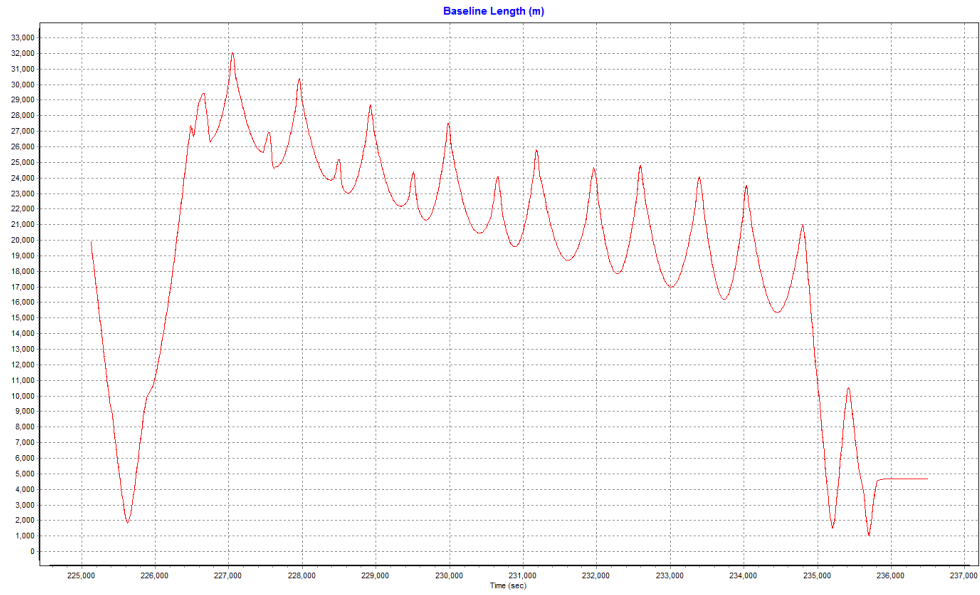
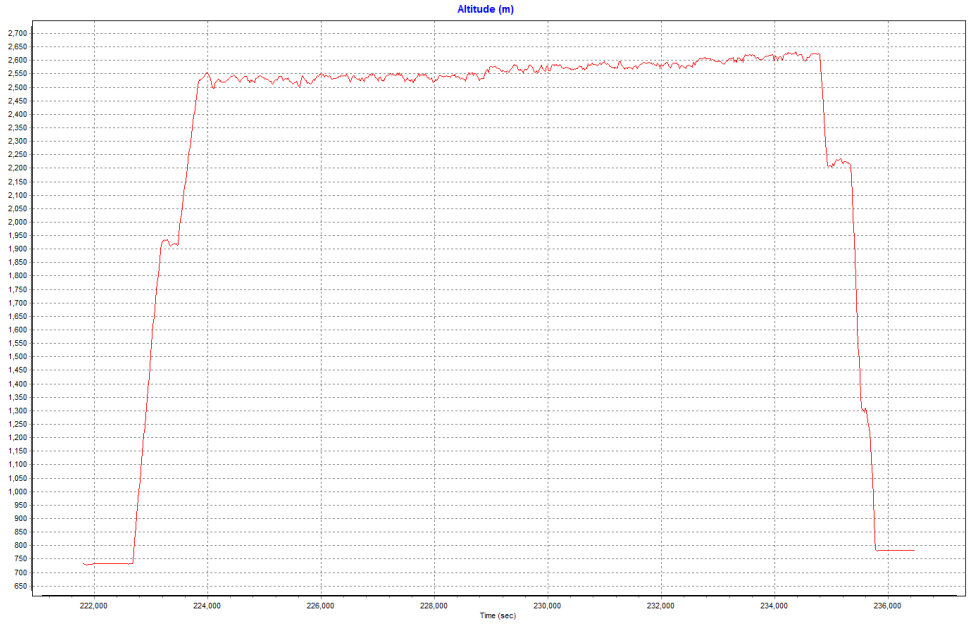


— North Position Error RMS (m) — East Position Error RMS (m) — Down Position Error RMS (m)

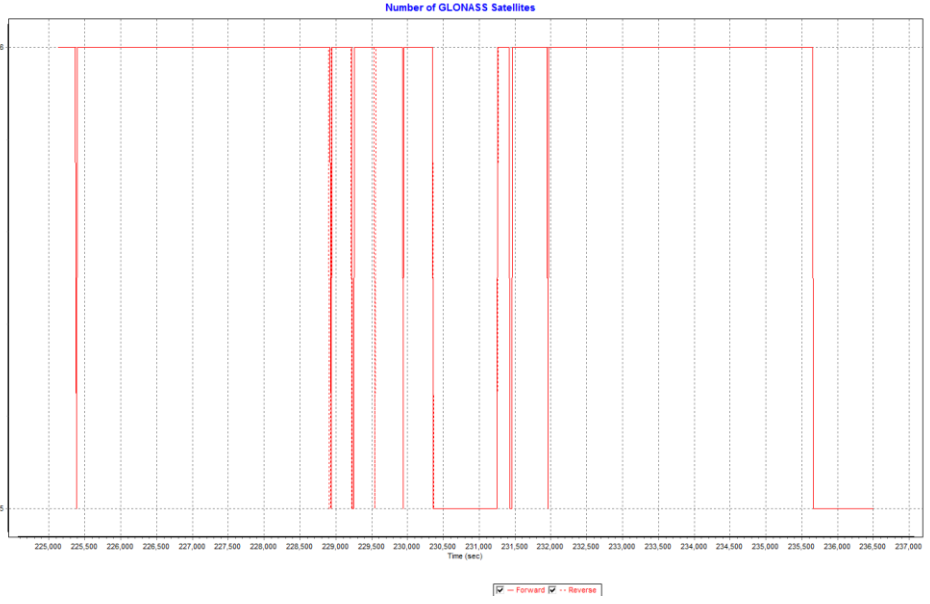
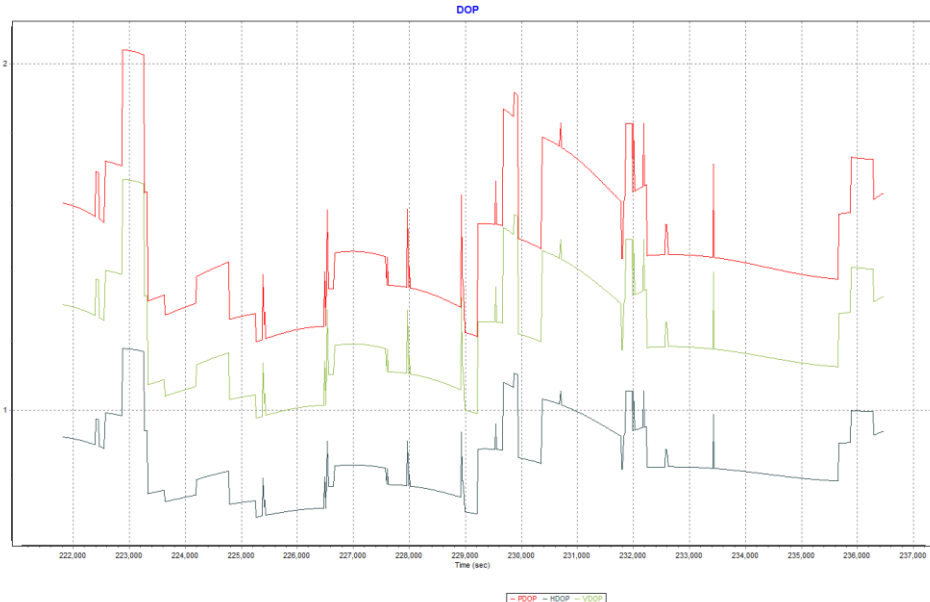


# UNB16327A

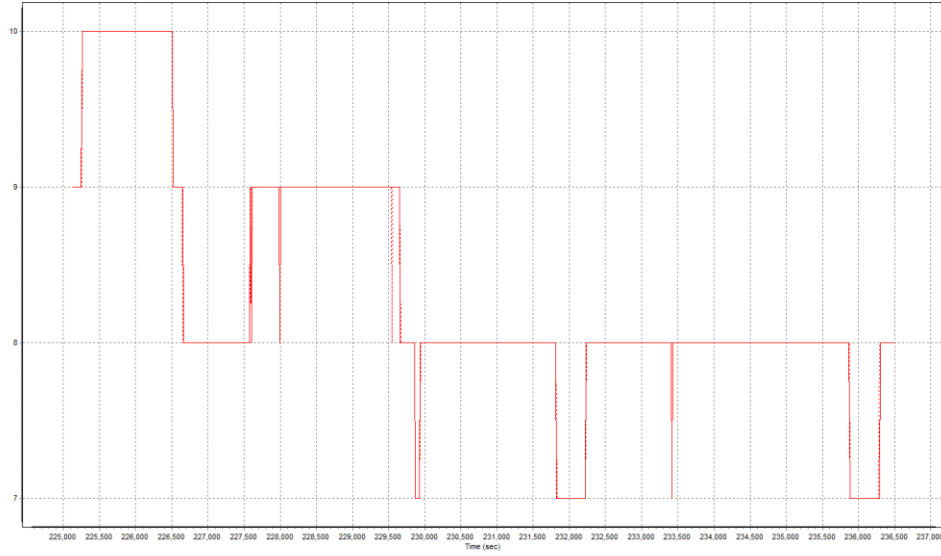




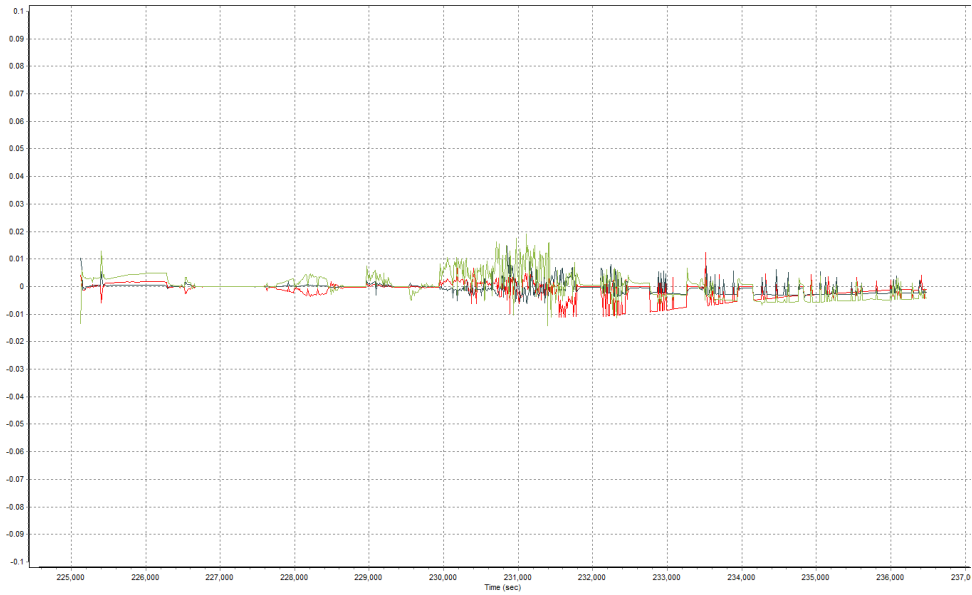
Forward  Reverse



Number of GPS Satellites

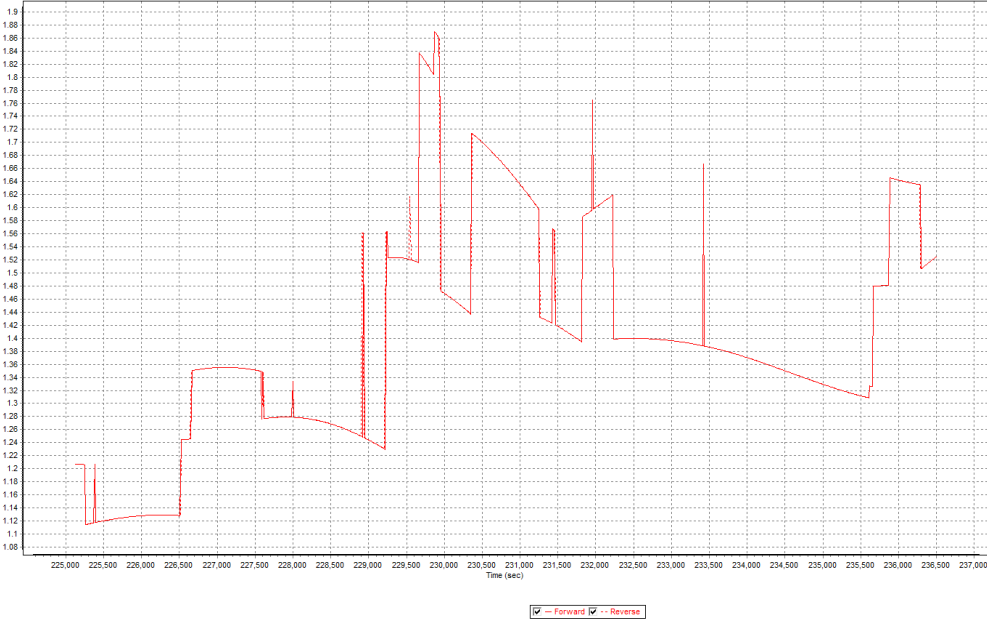


☑ Forward ☑ Reverse

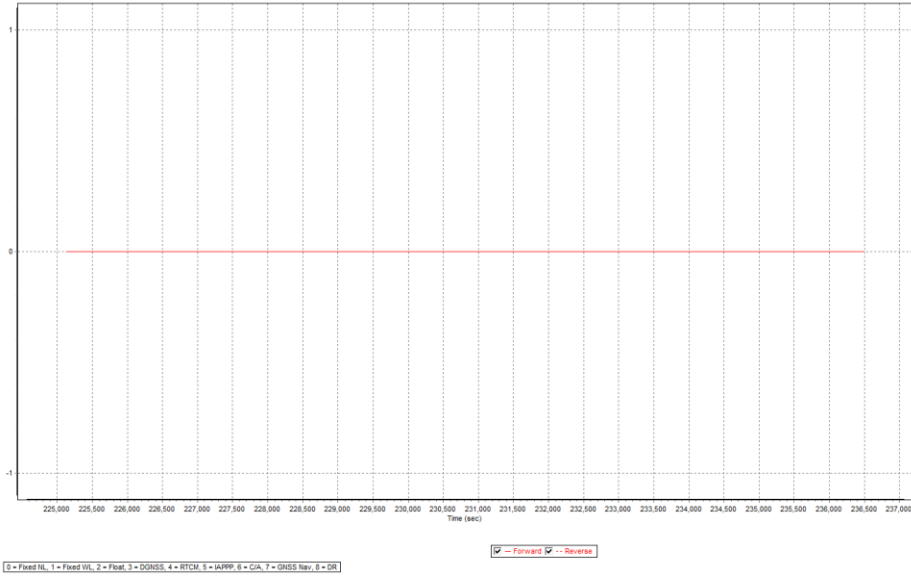


— North (m) — East (m) — Down (m) — DR mode

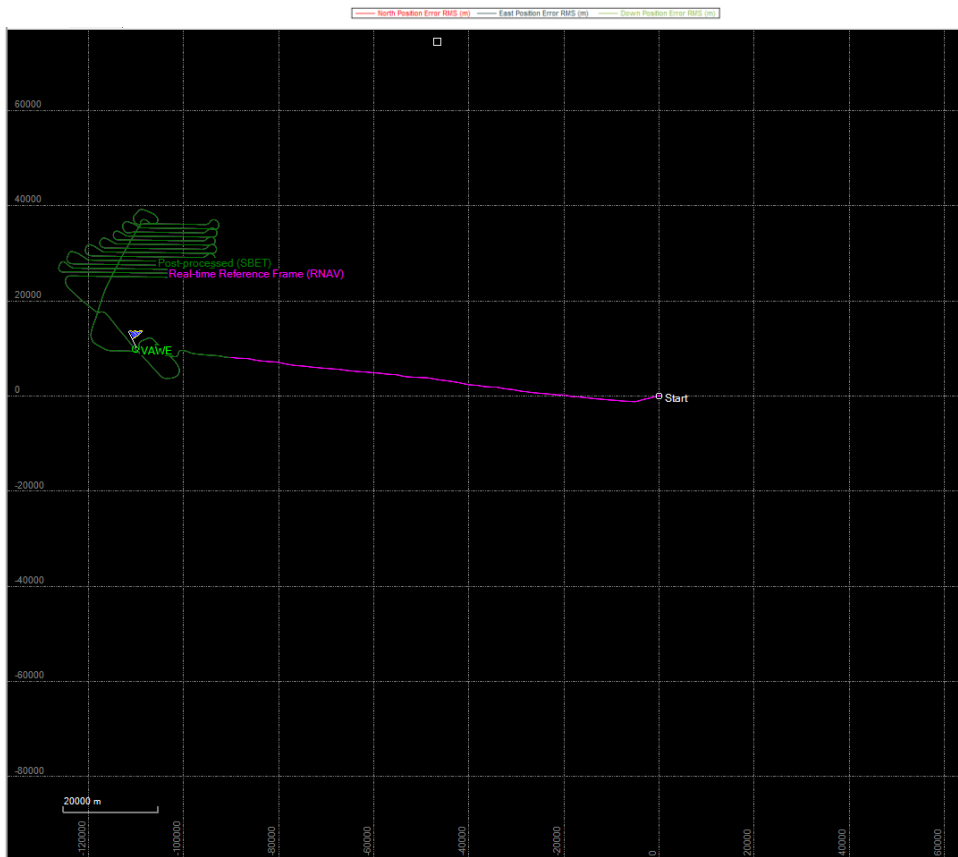
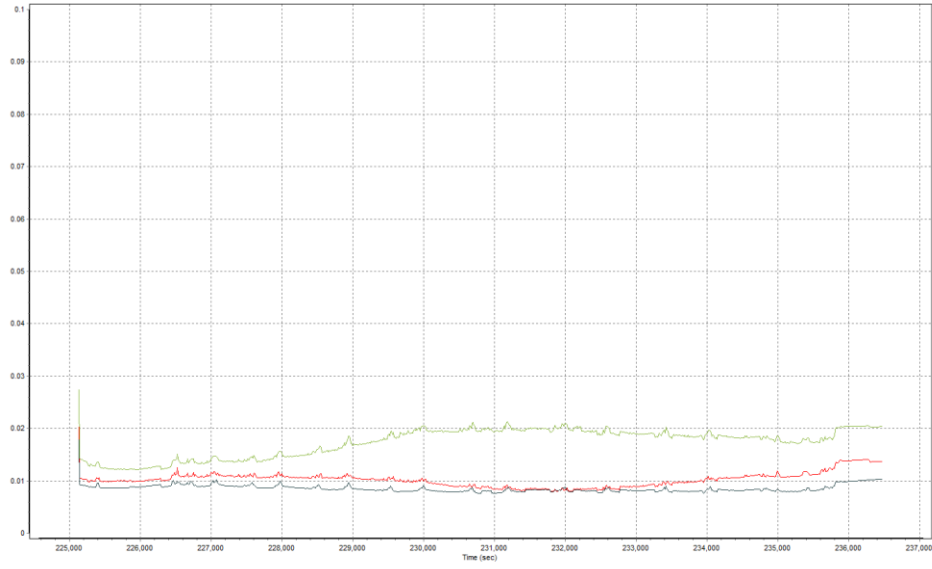
PDOP



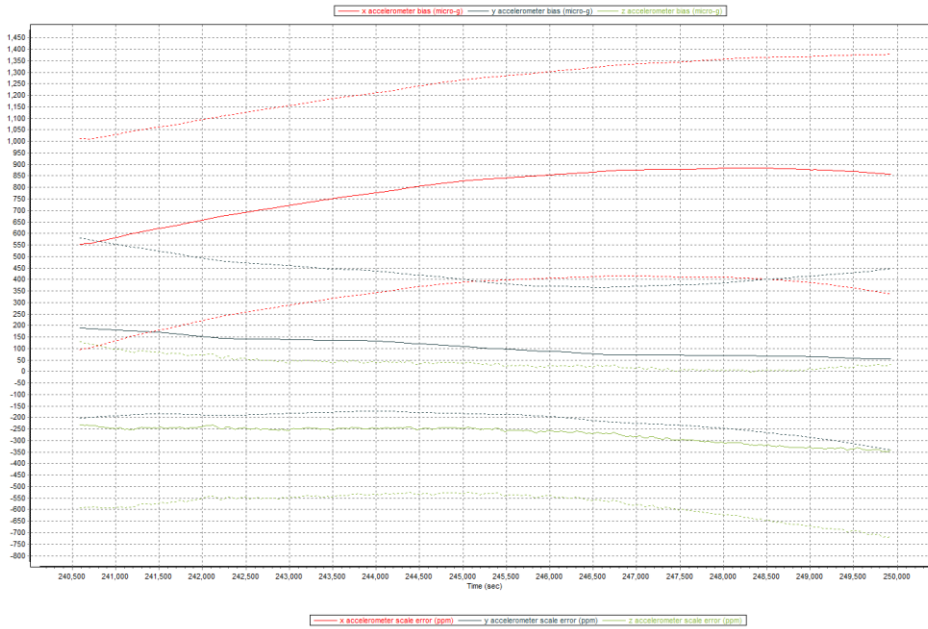
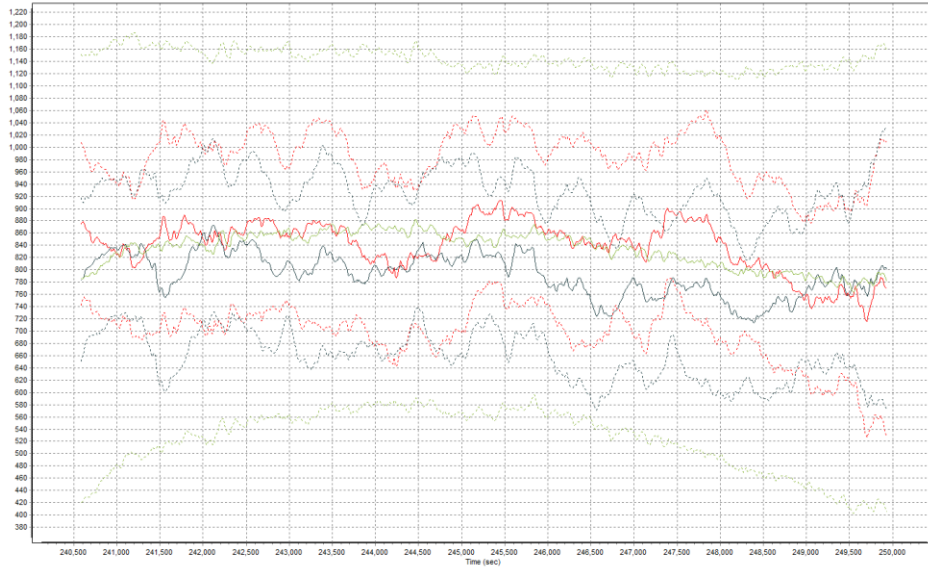
Processing mode

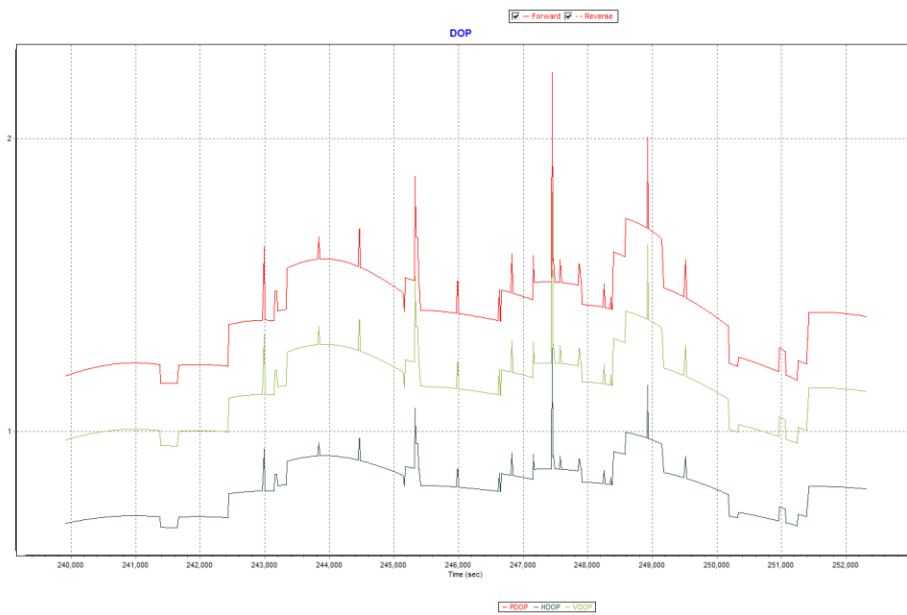
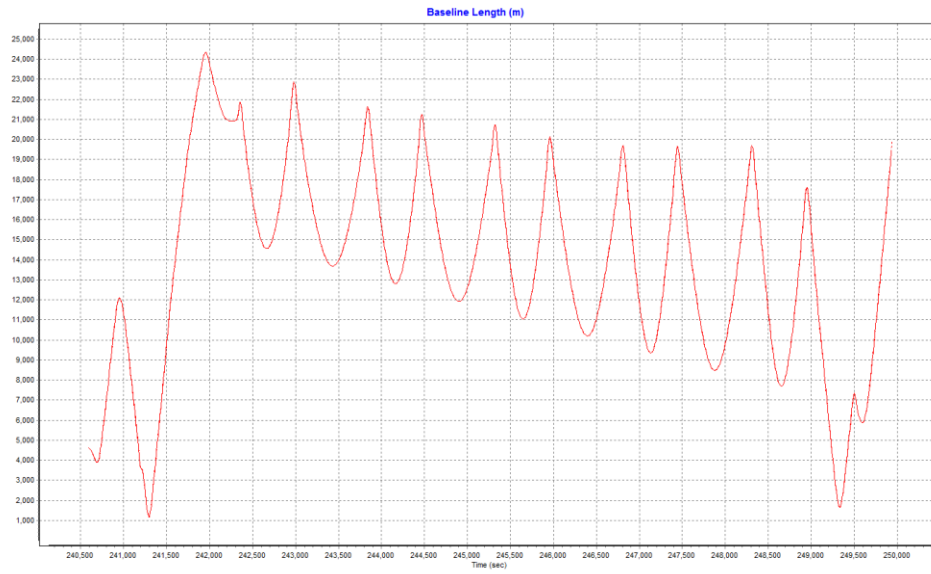




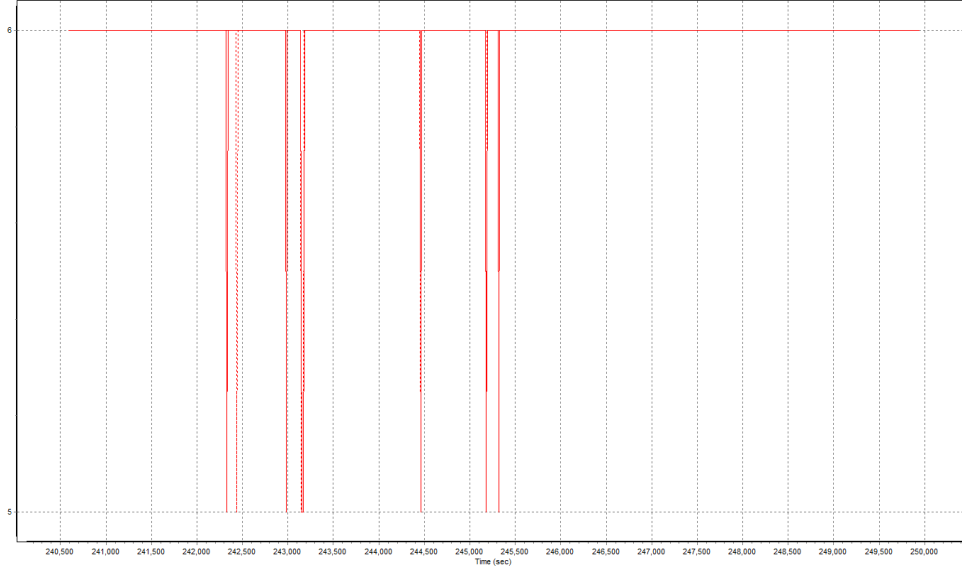


# UNB16327B



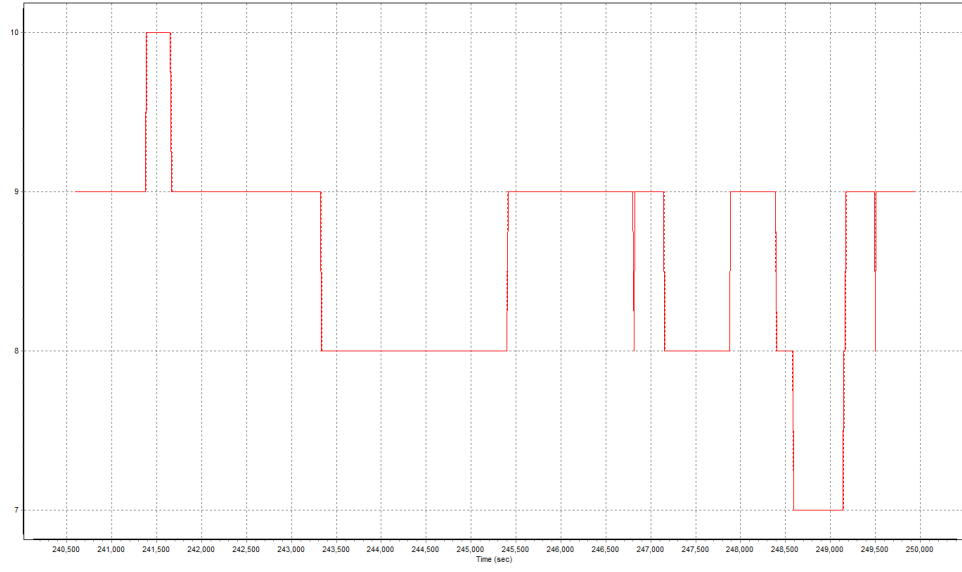


Number of GLONASS Satellites

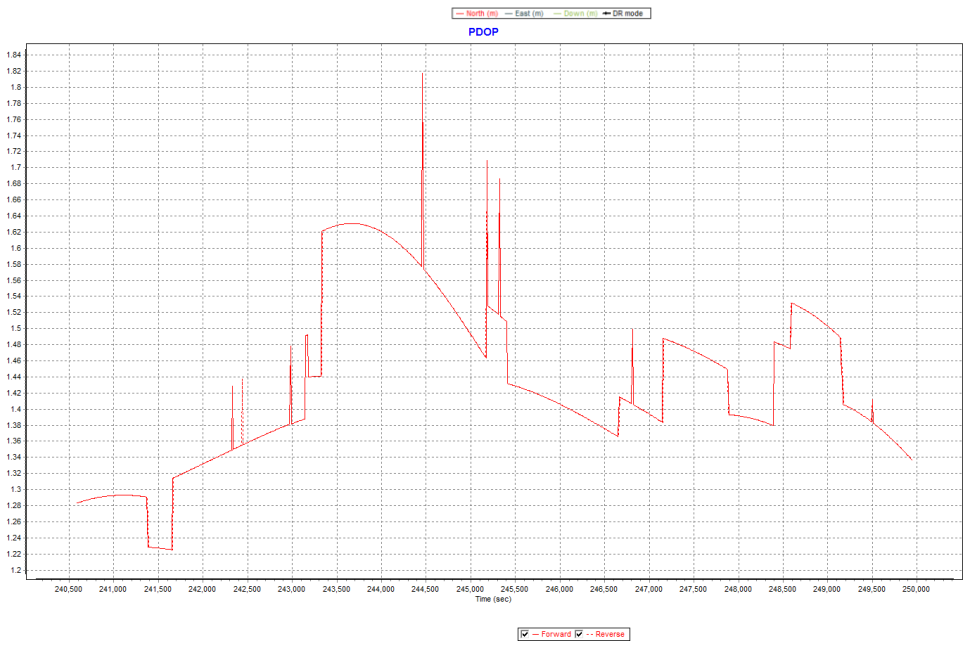
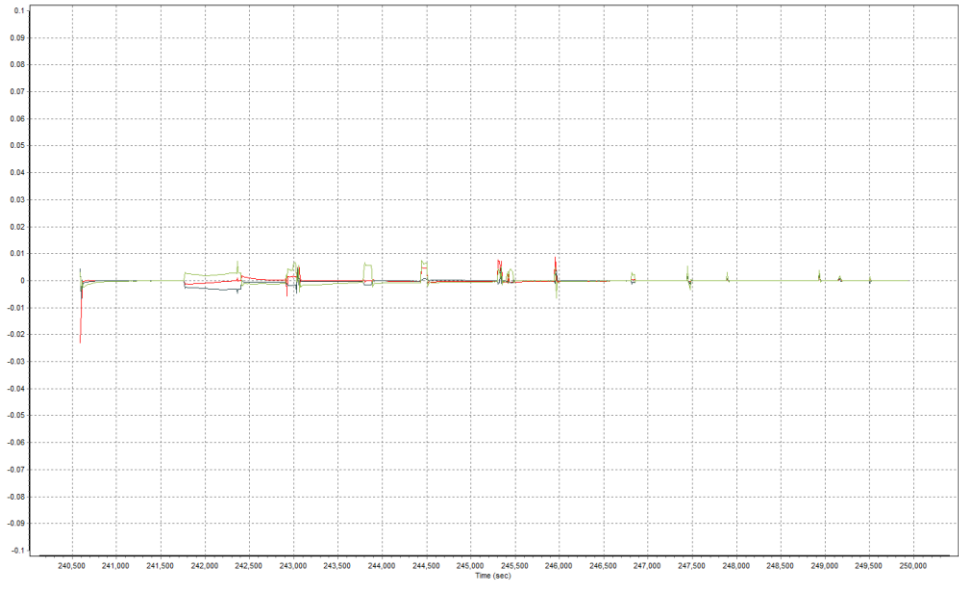


Forward  Reverse

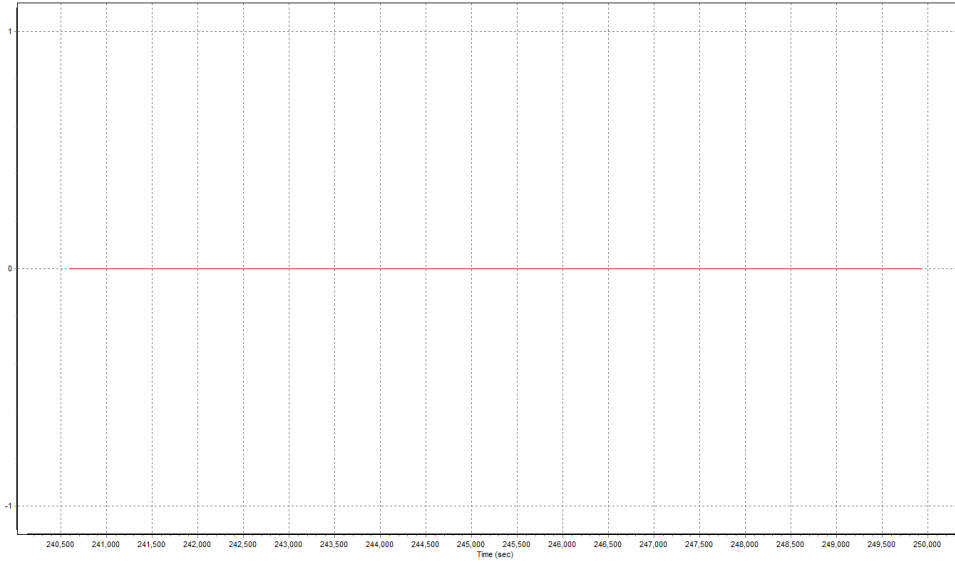
Number of GPS Satellites



Forward  Reverse

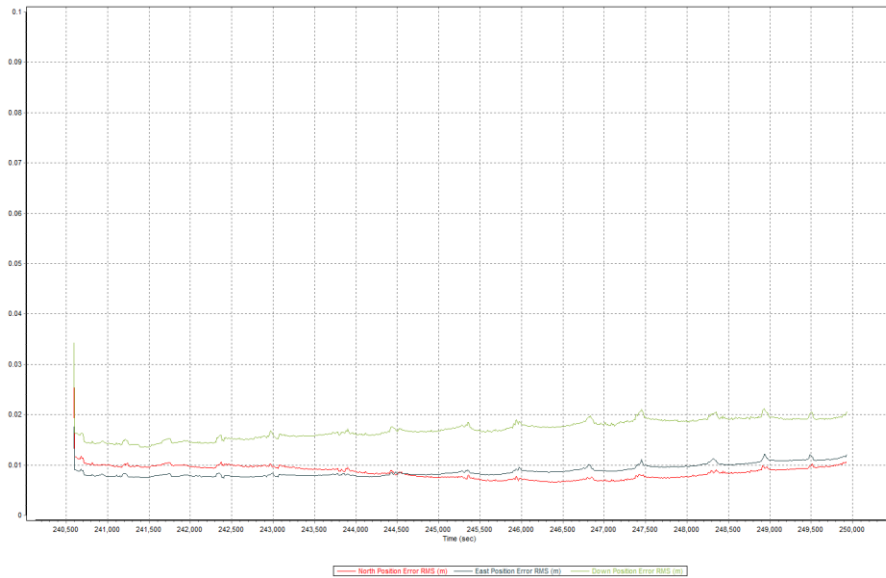


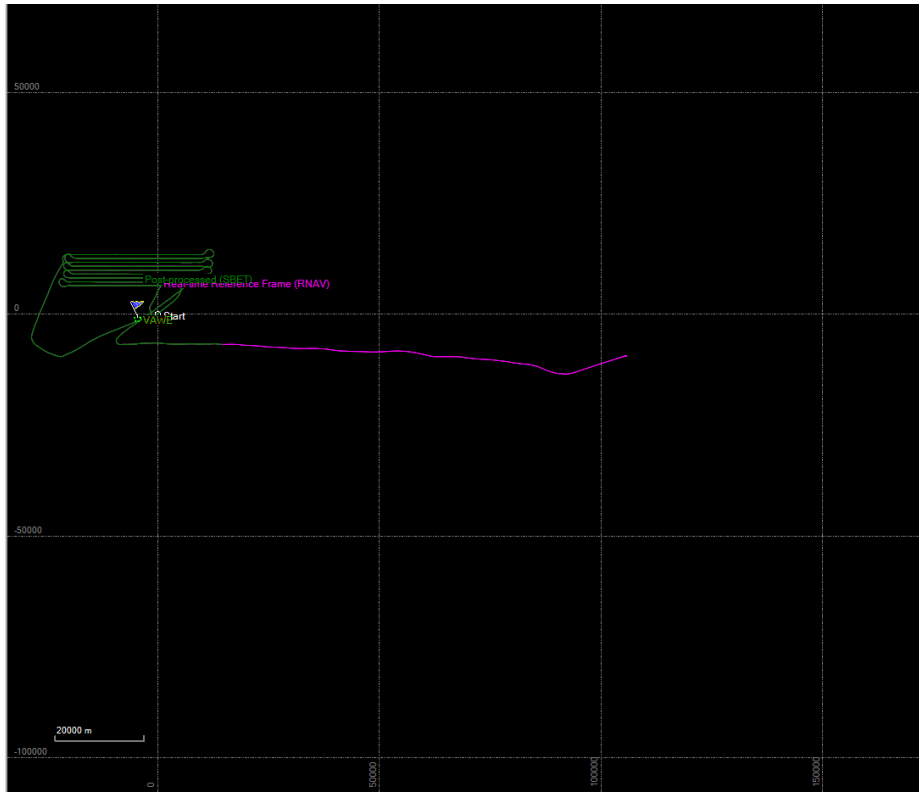
Processing mode



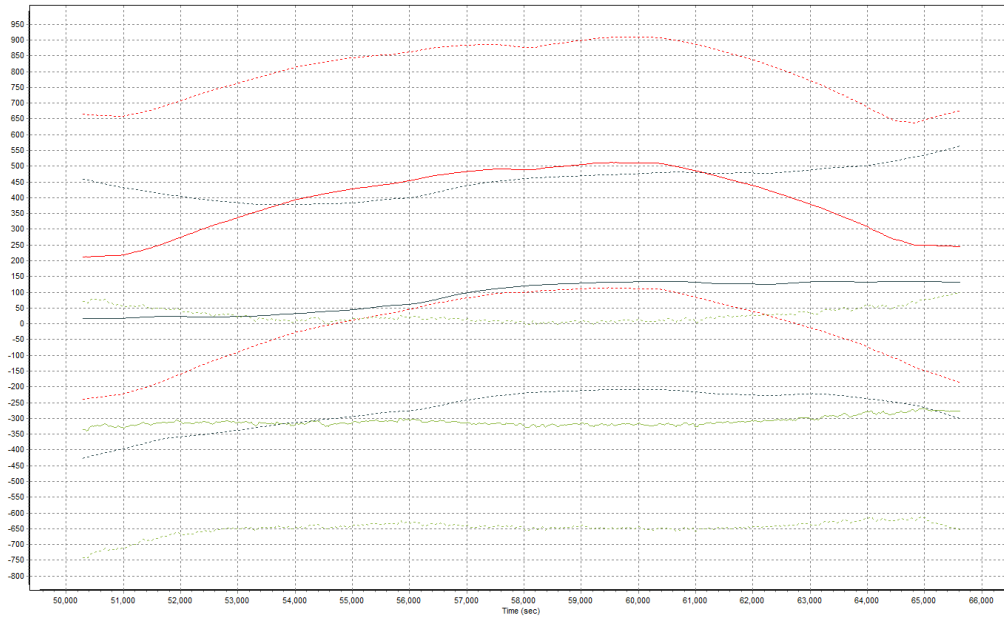
0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = CIA, 7 = GNSS Nav, 8 = OR

Forward  Reverse

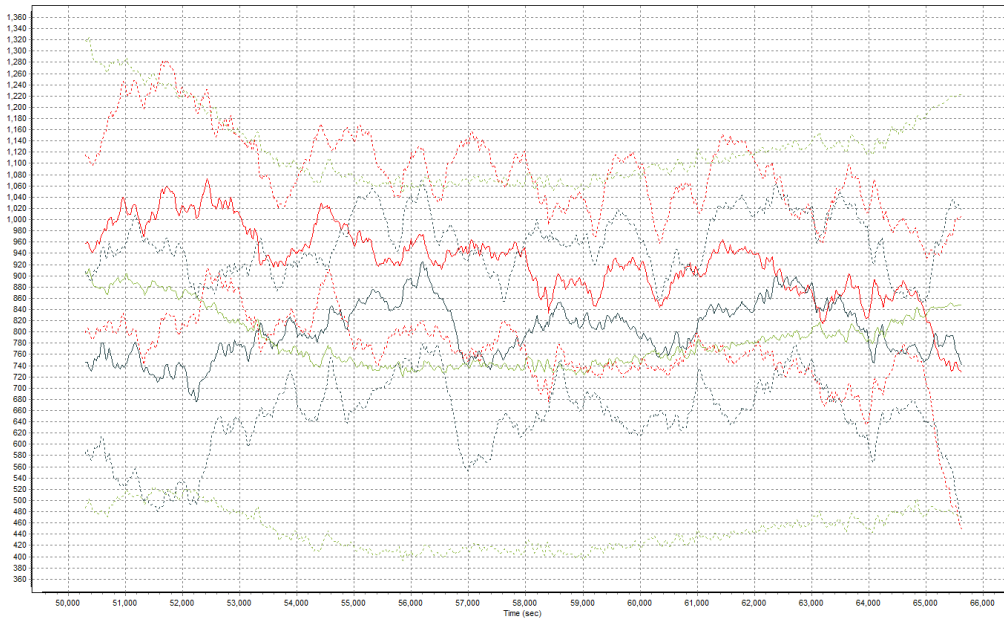




# UNB16332A

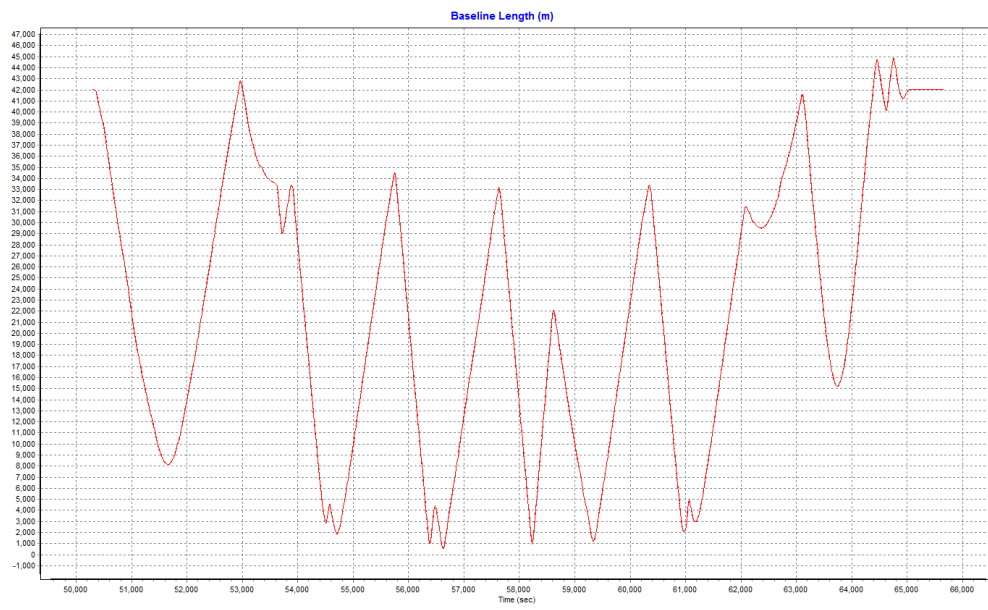
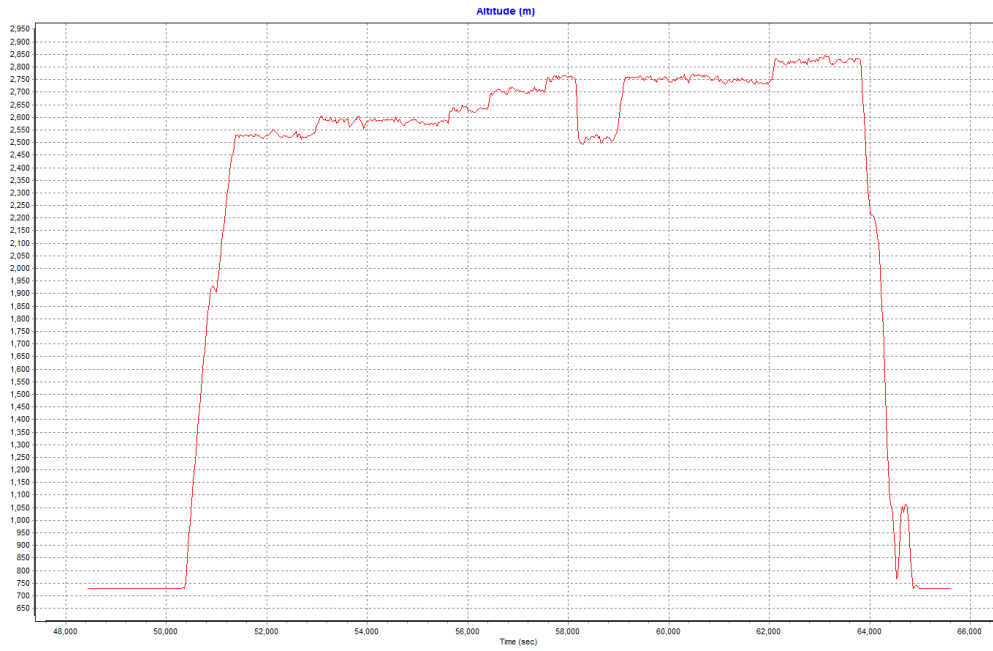


x accelerometer scale error (ppm)    y accelerometer scale error (ppm)    z accelerometer scale error (ppm)

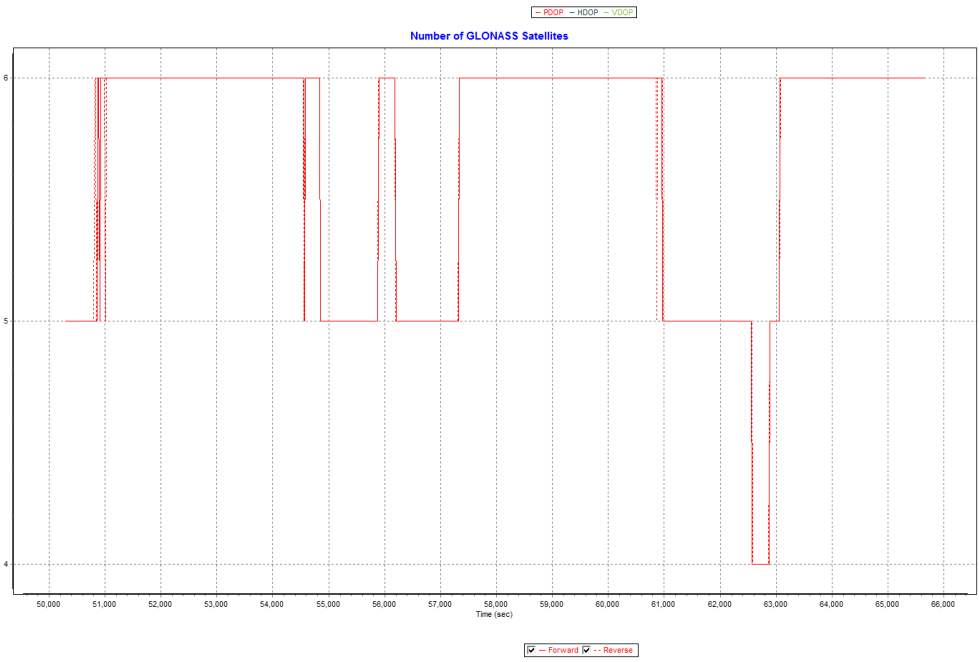
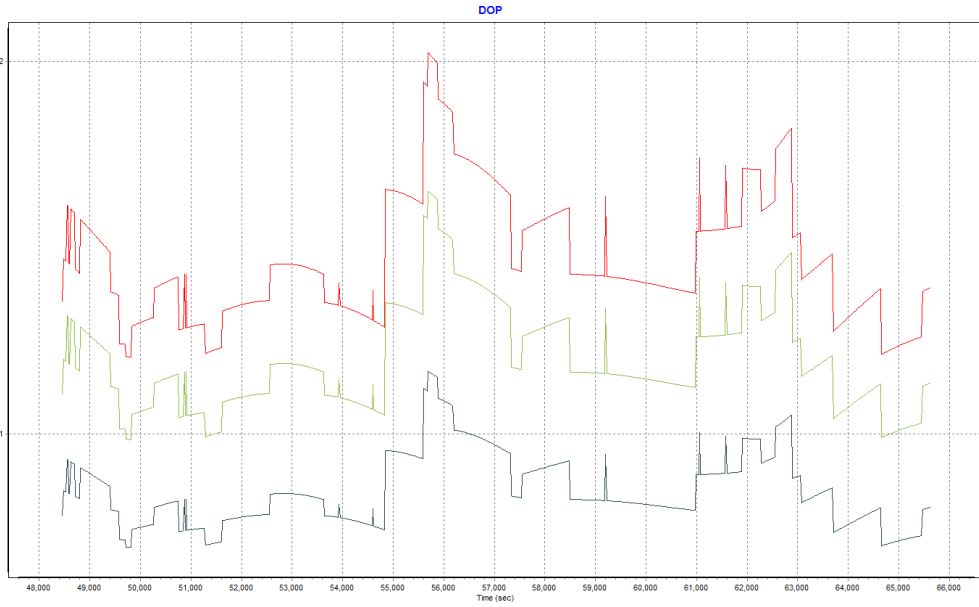


x accelerometer bias (micro-g)    y accelerometer bias (micro-g)    z accelerometer bias (micro-g)

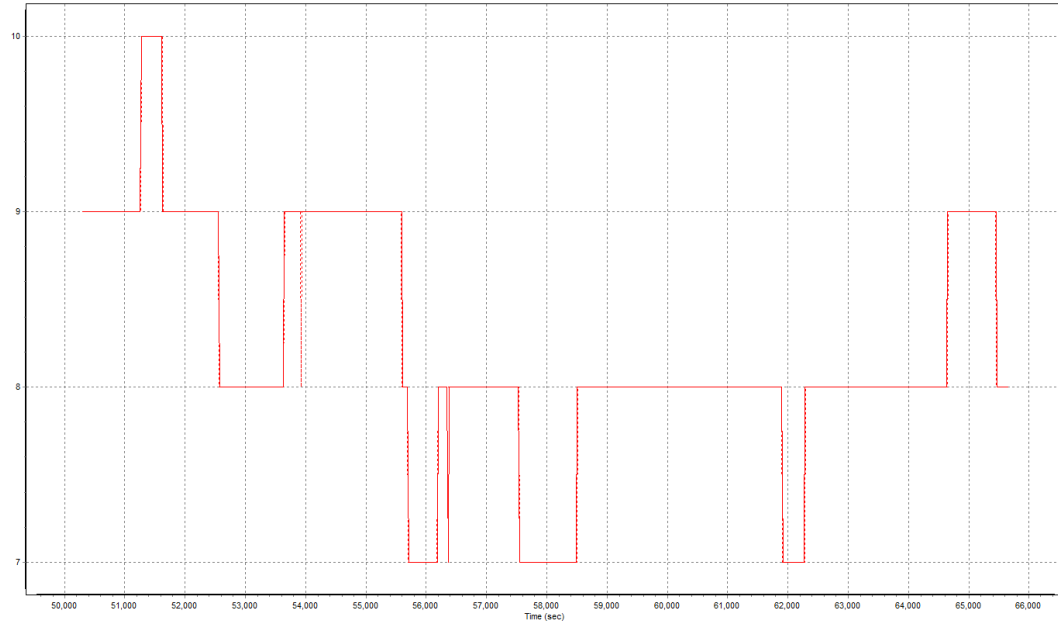




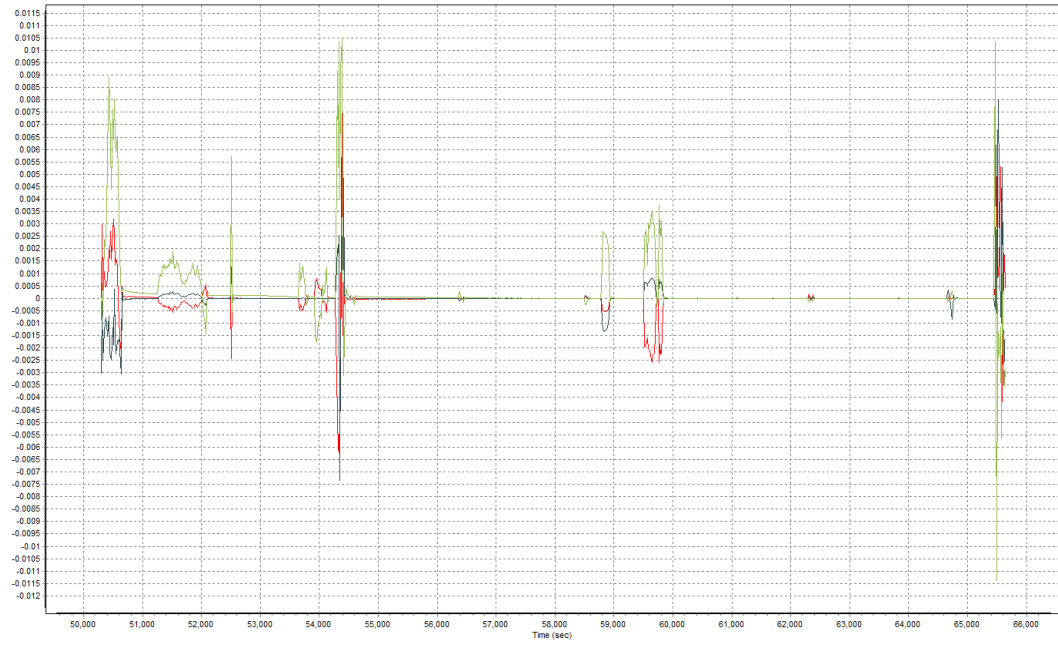
Forward  Reverse



Number of GPS Satellites

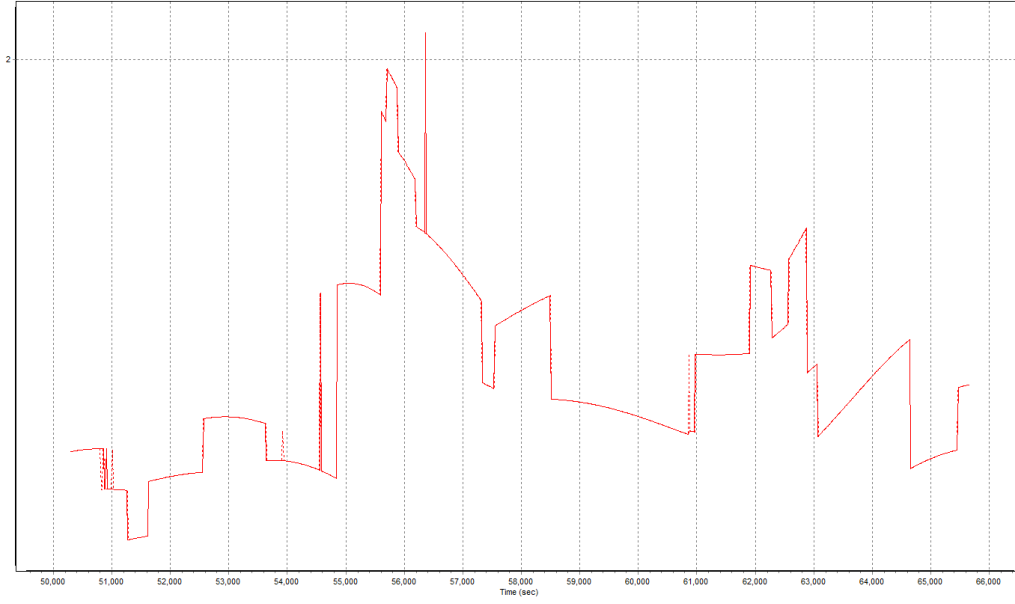


Forward Reverse



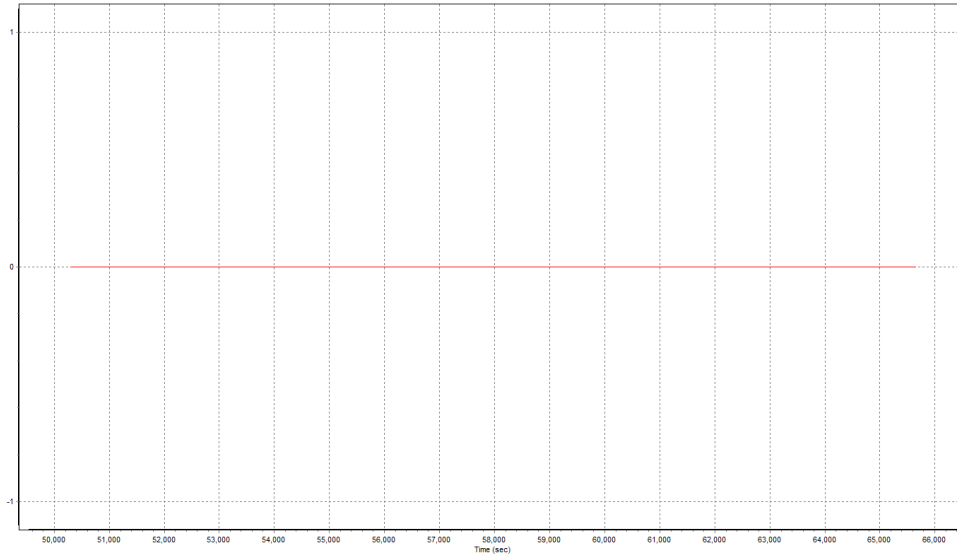
North (m) East (m) Down (m) DR mode

PDOP



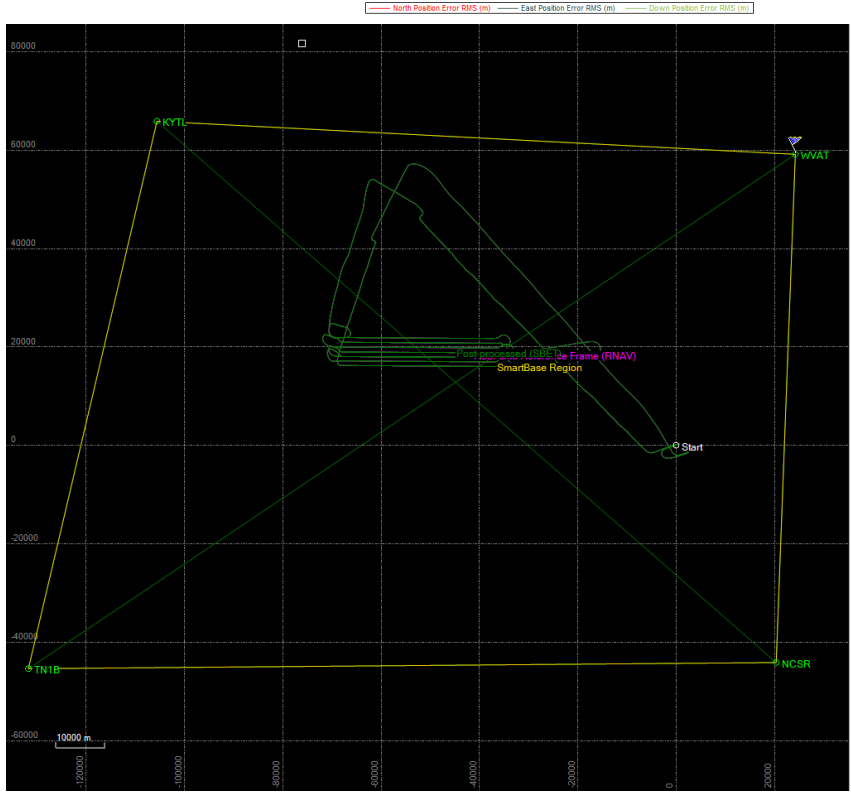
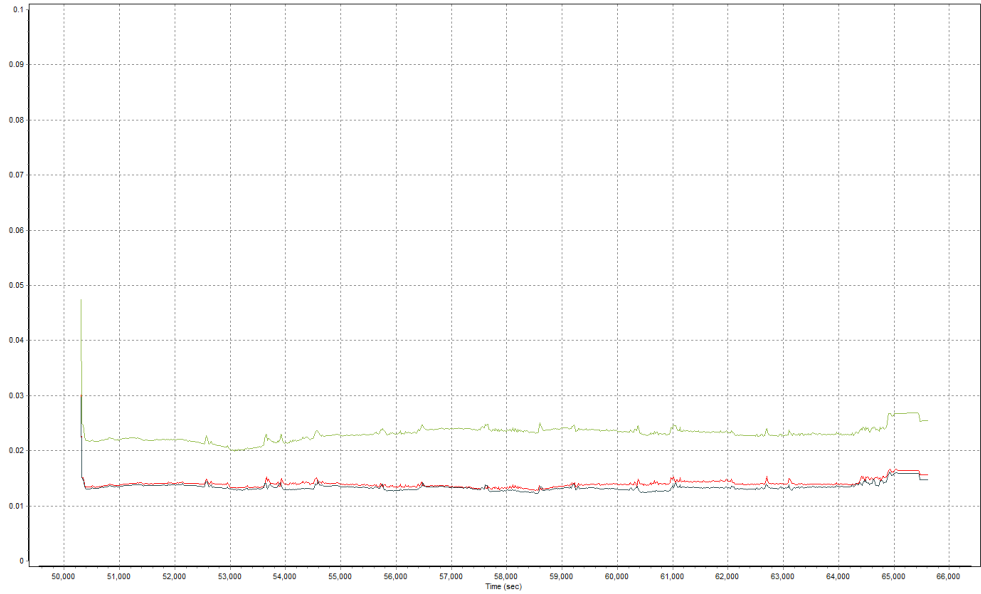
Forward  Reverse

Processing mode

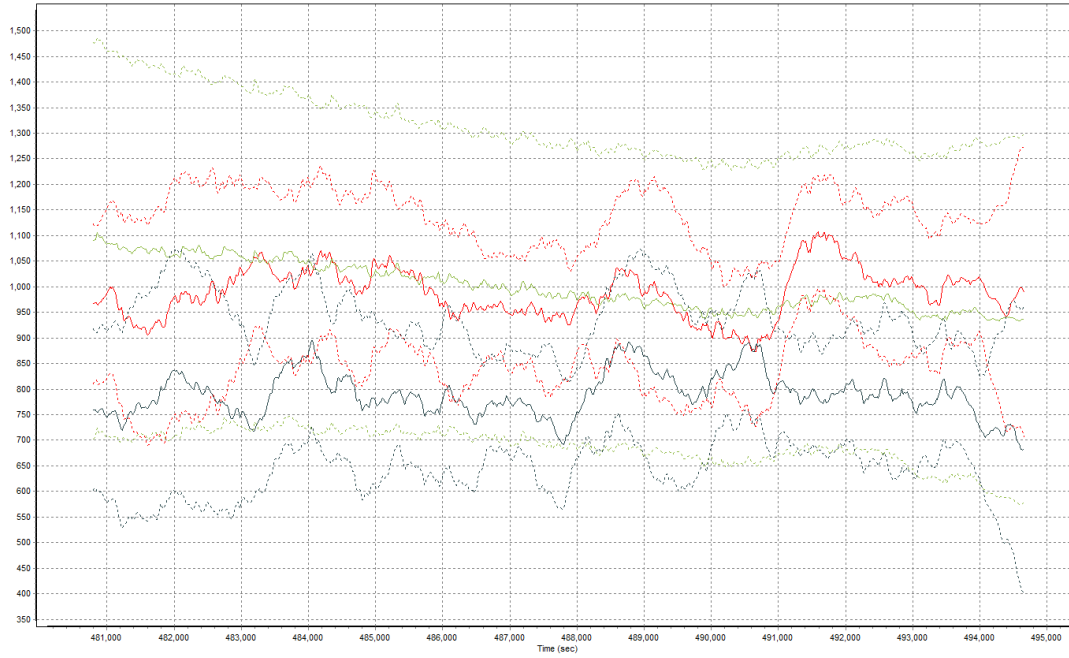


Forward  Reverse

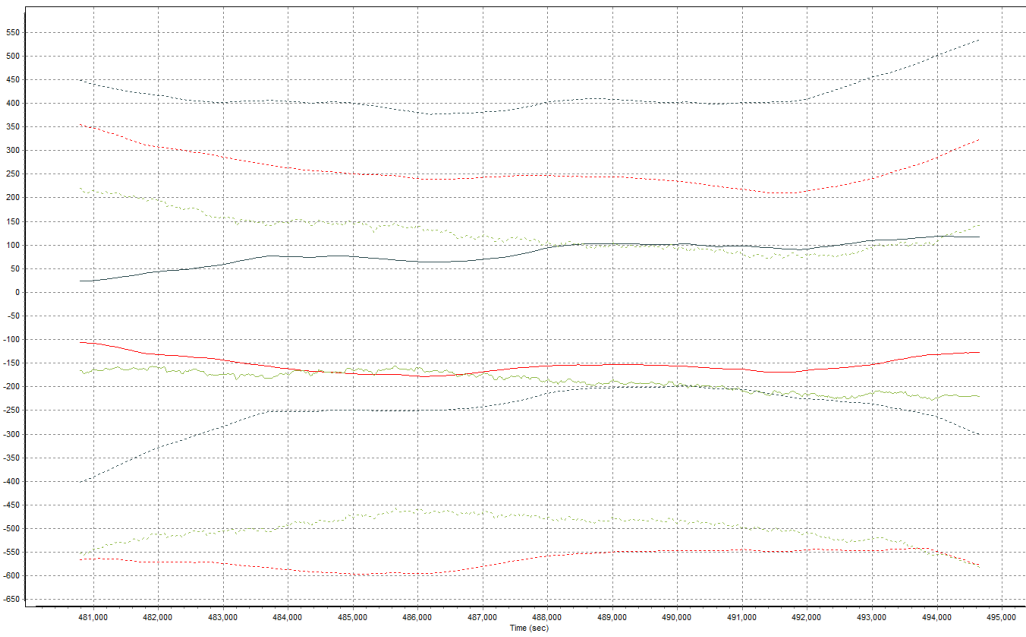
0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = iAPPP, 6 = CIA, 7 = GNSS Nav, 8 = DR



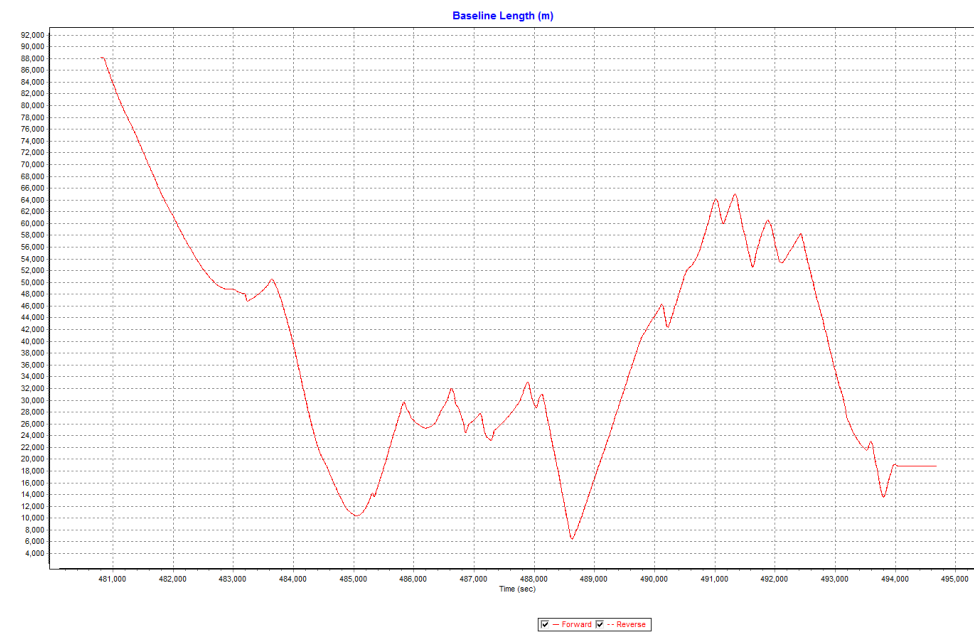
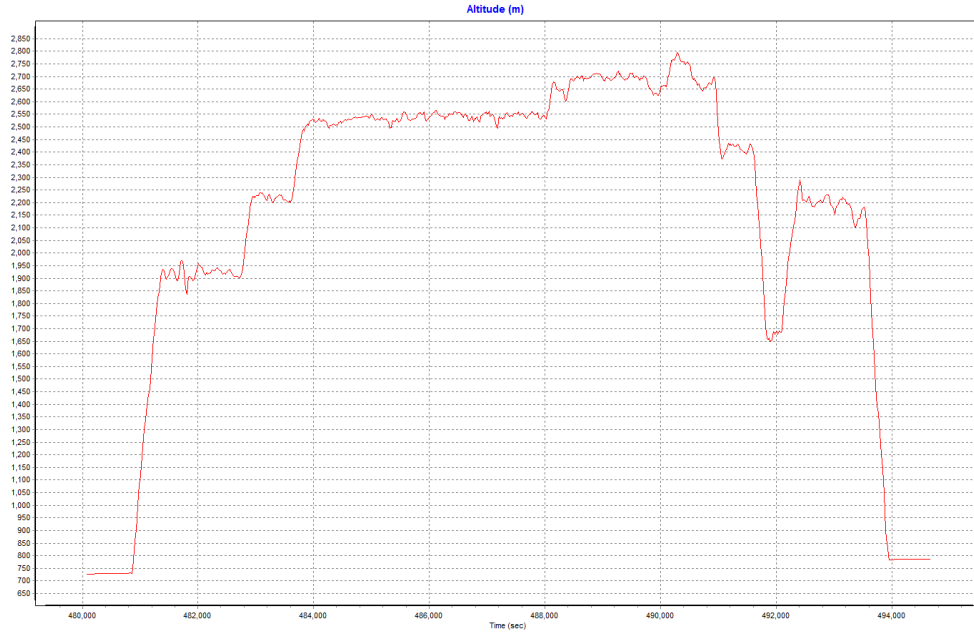
# UNB16337A



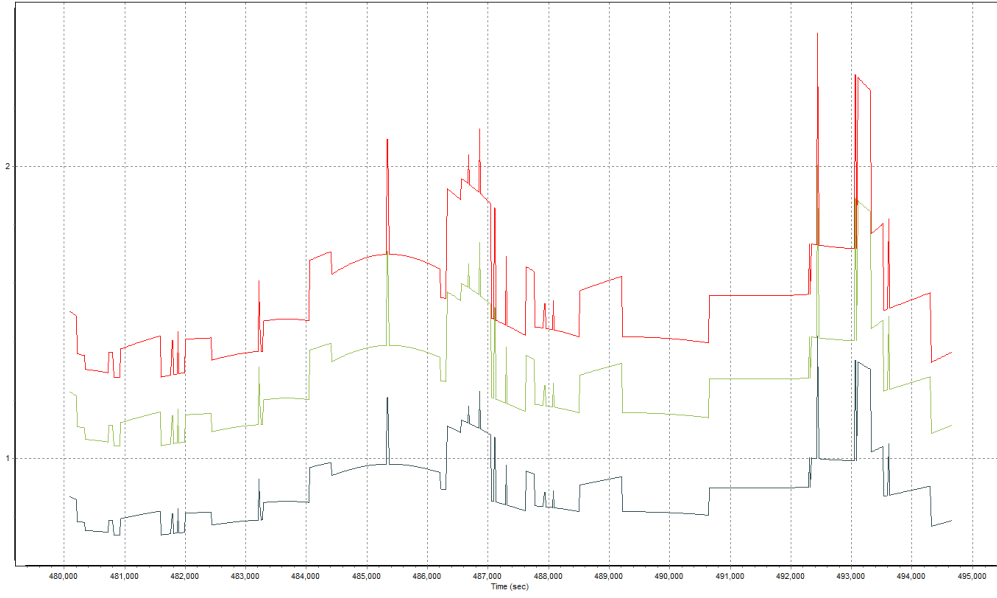
x accelerometer bias (micro-g) y accelerometer bias (micro-g) z accelerometer bias (micro-g)



x accelerometer scale error (ppm) y accelerometer scale error (ppm) z accelerometer scale error (ppm)

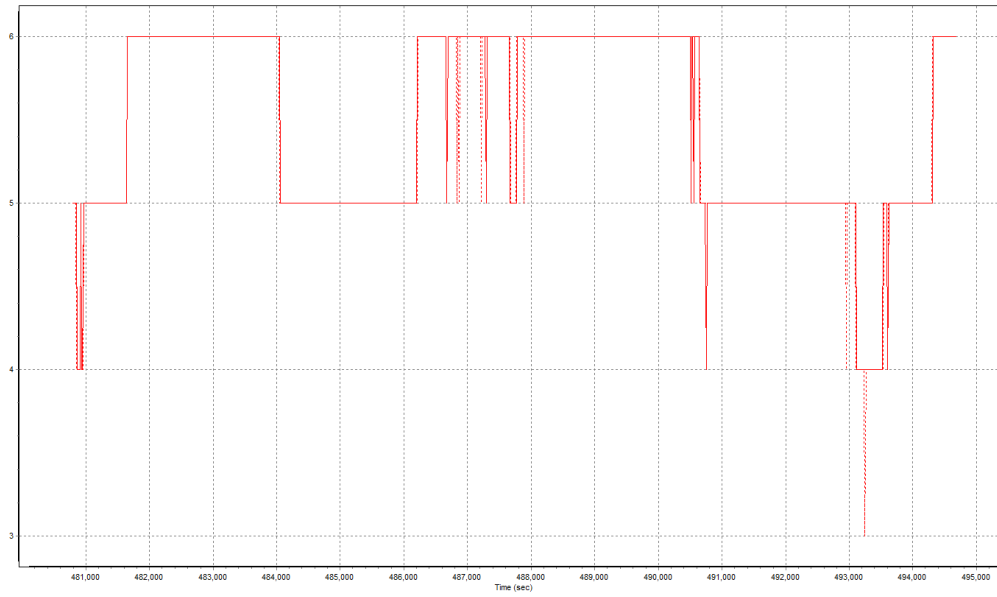


DOP



PDOP HDOP VDOP

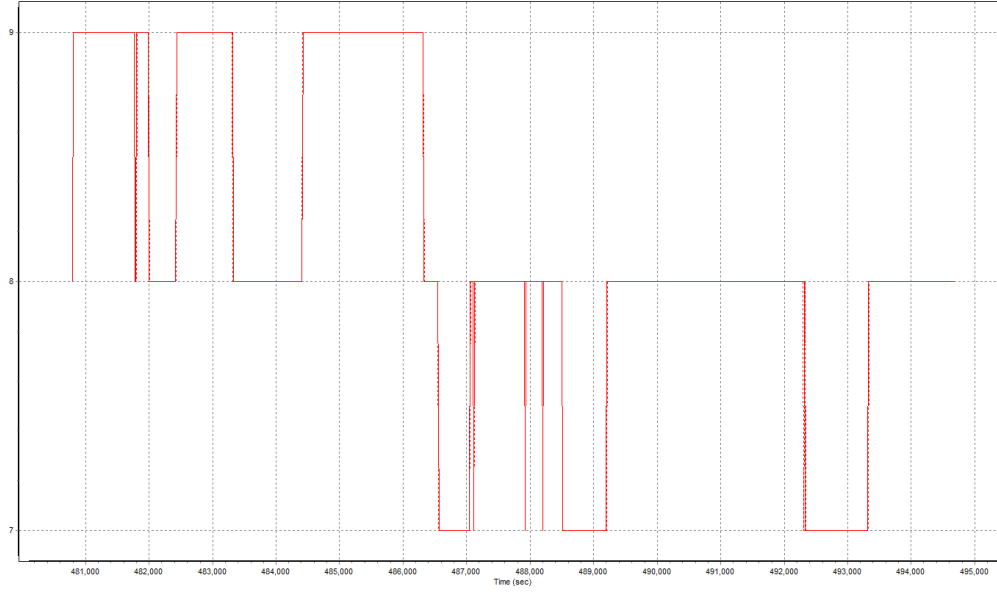
Number of GLONASS Satellites



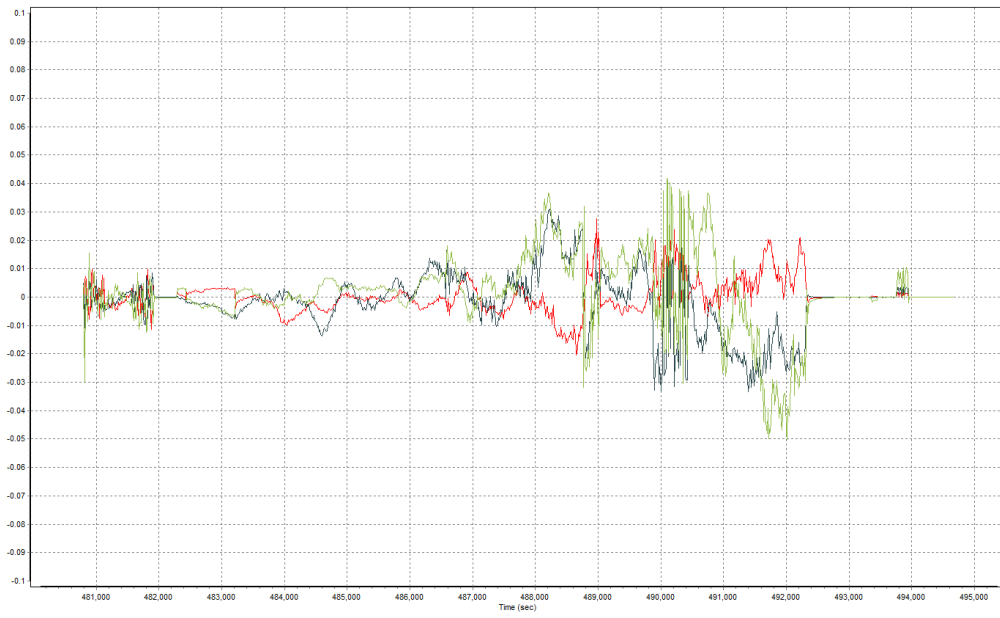
Forward Reverse



Number of GPS Satellites

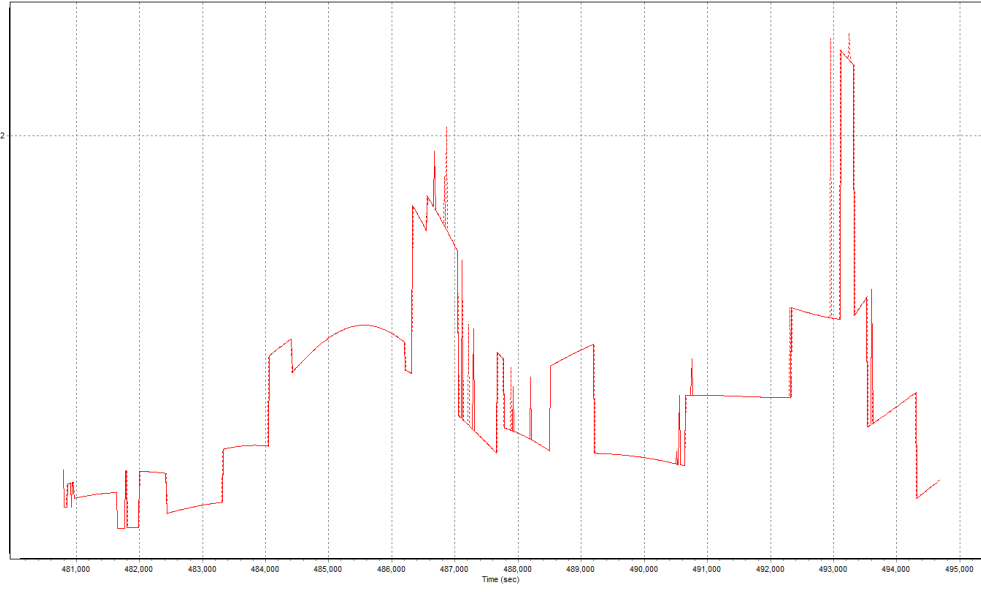


Forward  Reverse



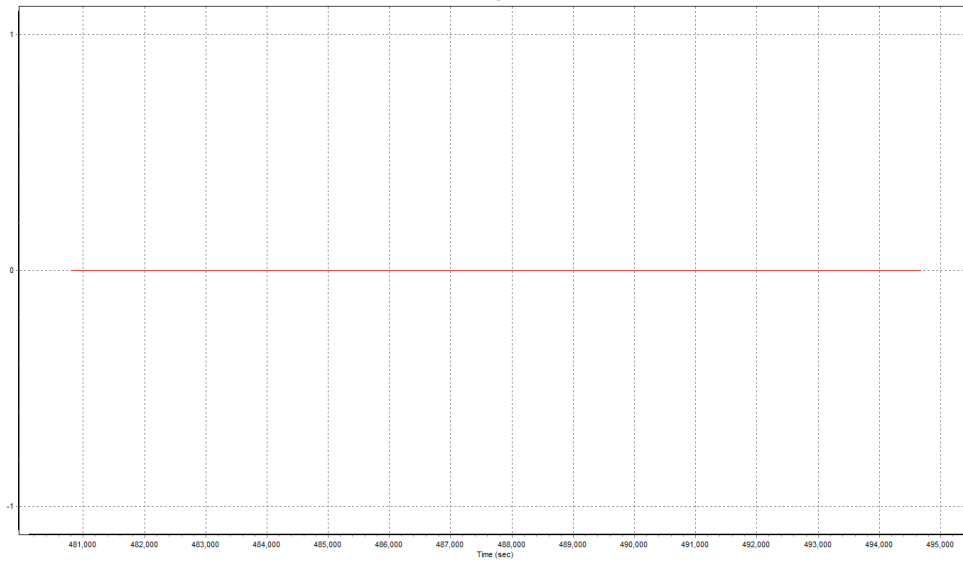
North (m) East (m) Down (m) DR mode

PDOP



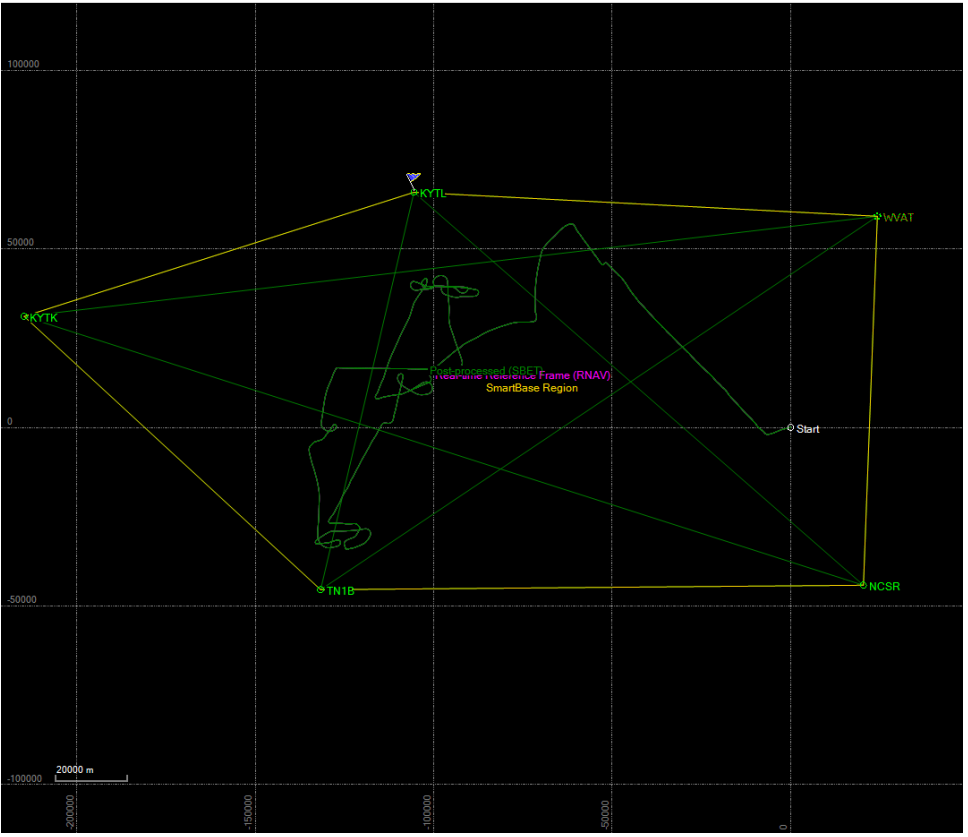
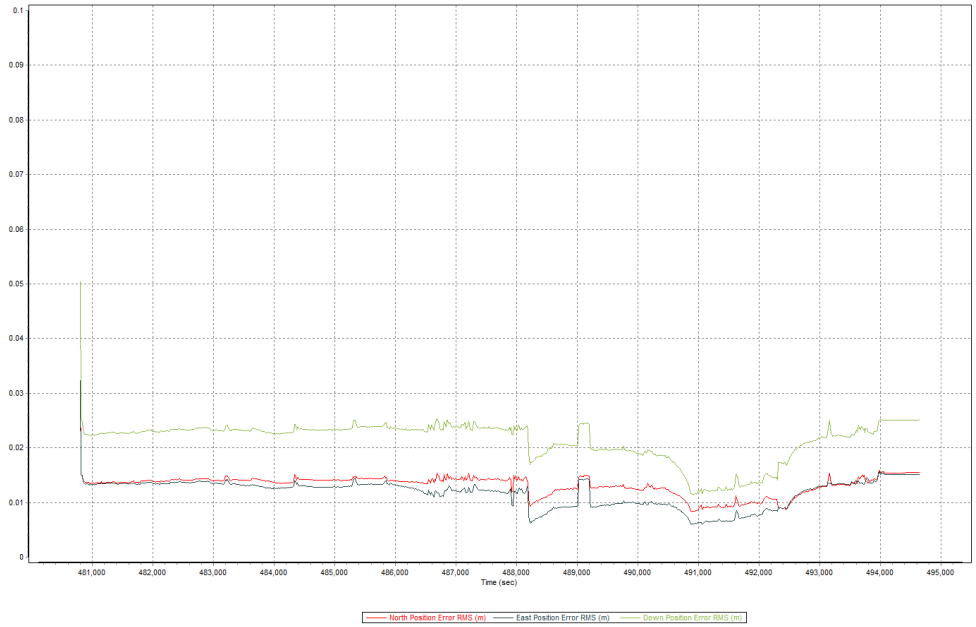
Forward  Reverse

Processing mode

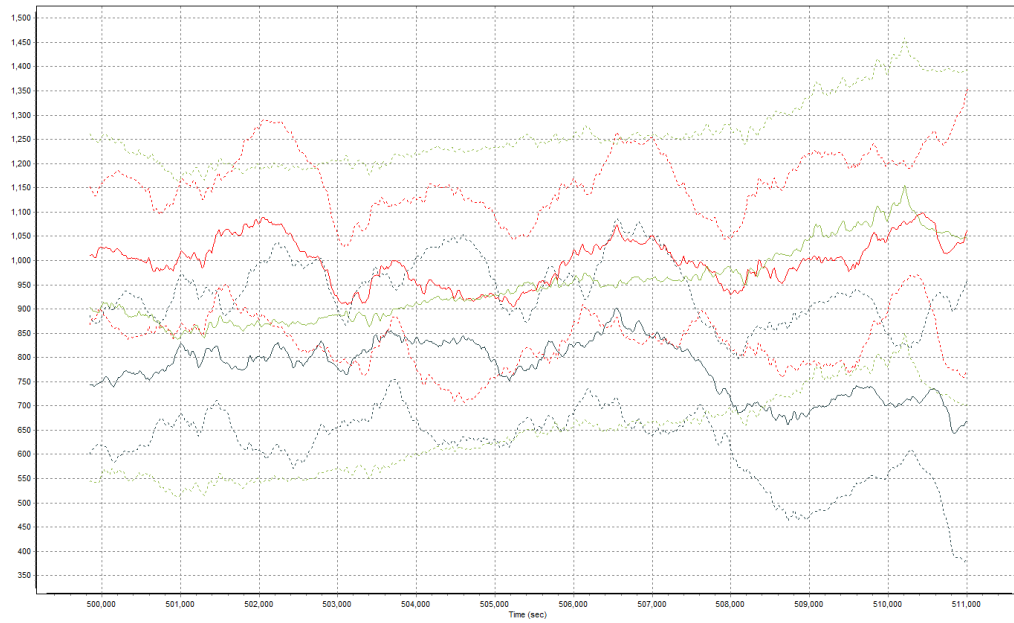


Forward  Reverse

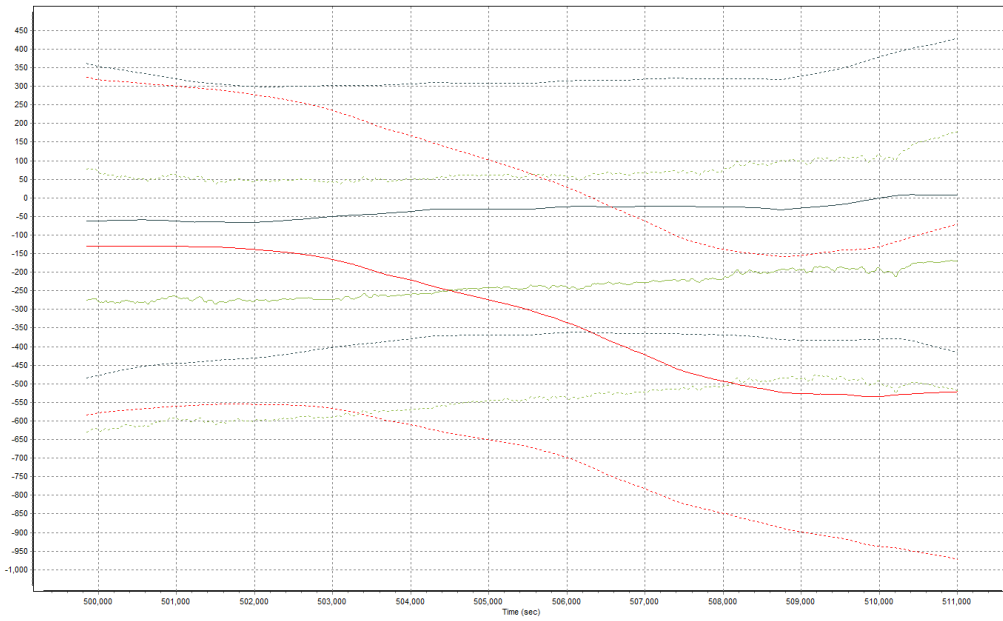
0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = iAPPP, 6 = CIA, 7 = GNSS Nav, 8 = DR



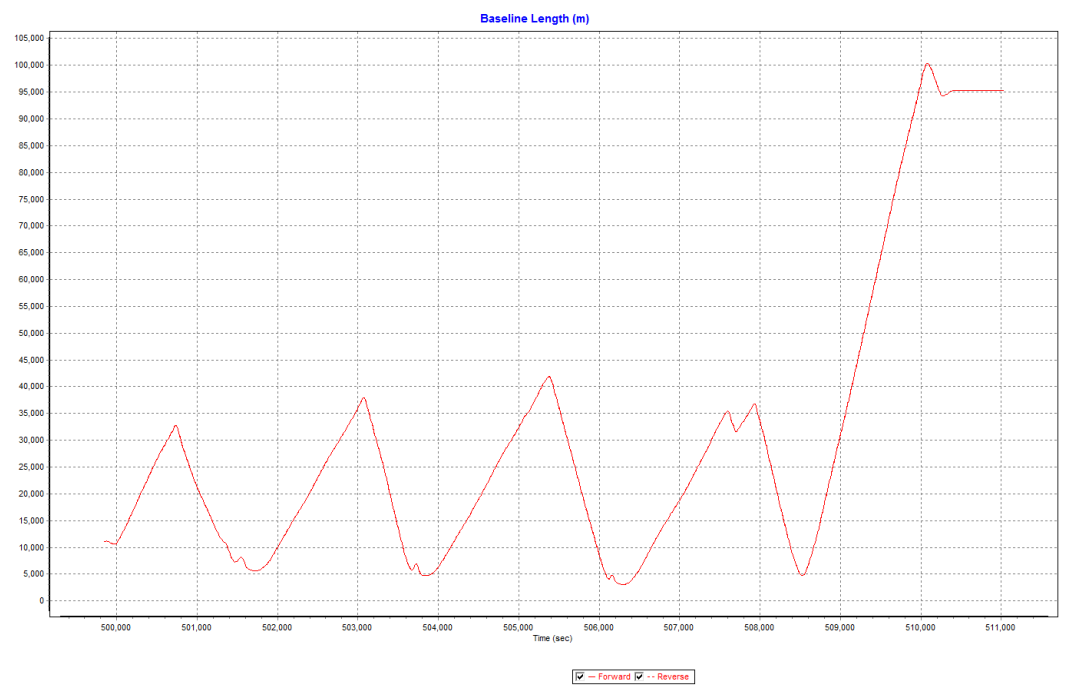
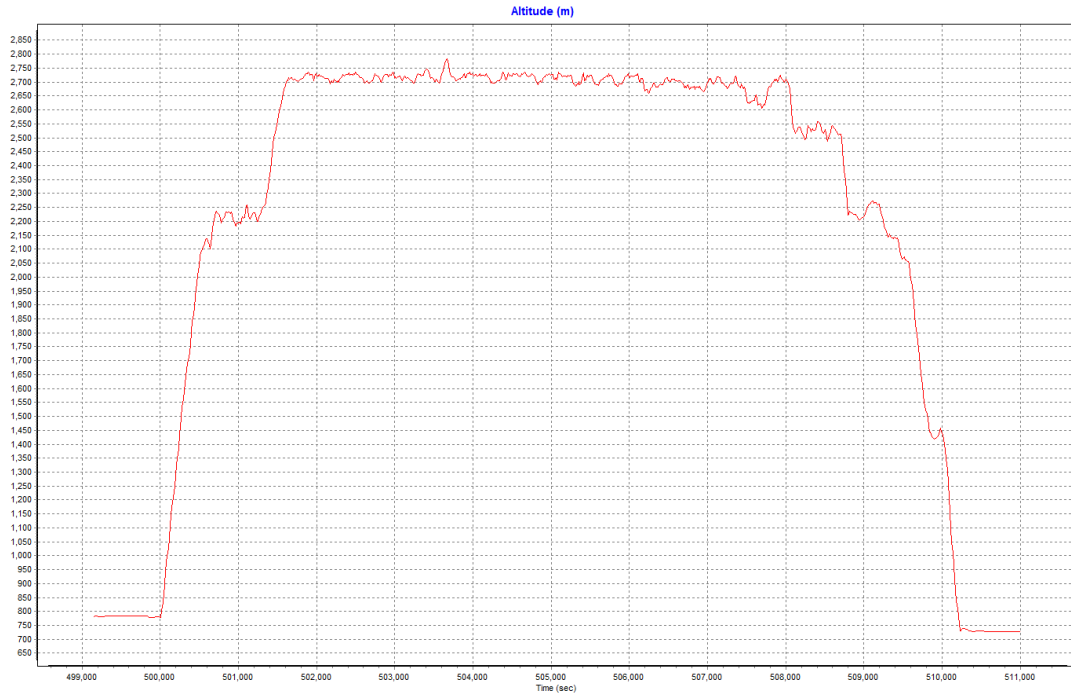
# UNB16337B



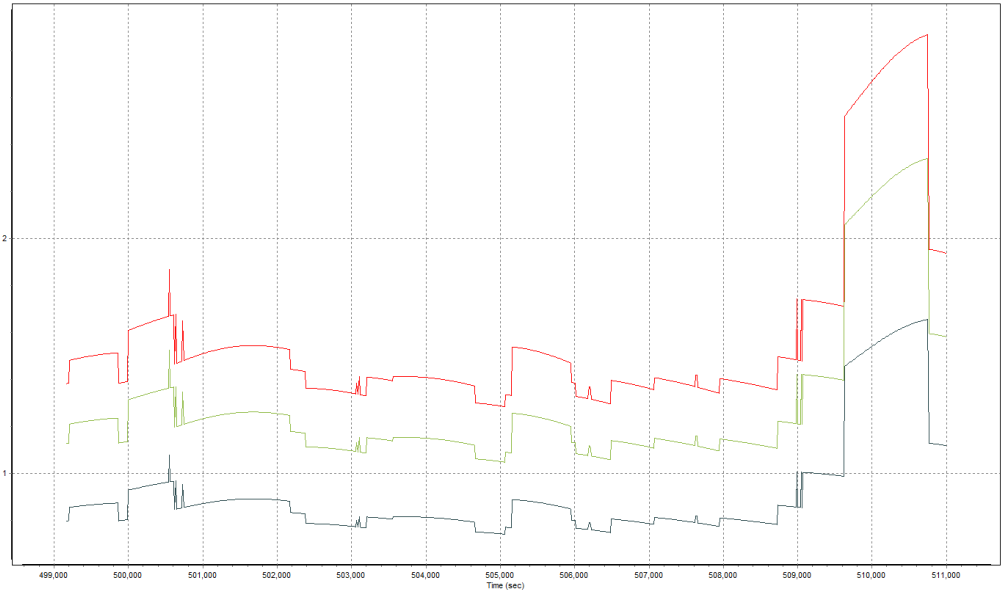
x accelerometer bias (micro-g) y accelerometer bias (micro-g) z accelerometer bias (micro-g)



x accelerometer scale error (ppm) y accelerometer scale error (ppm) z accelerometer scale error (ppm)

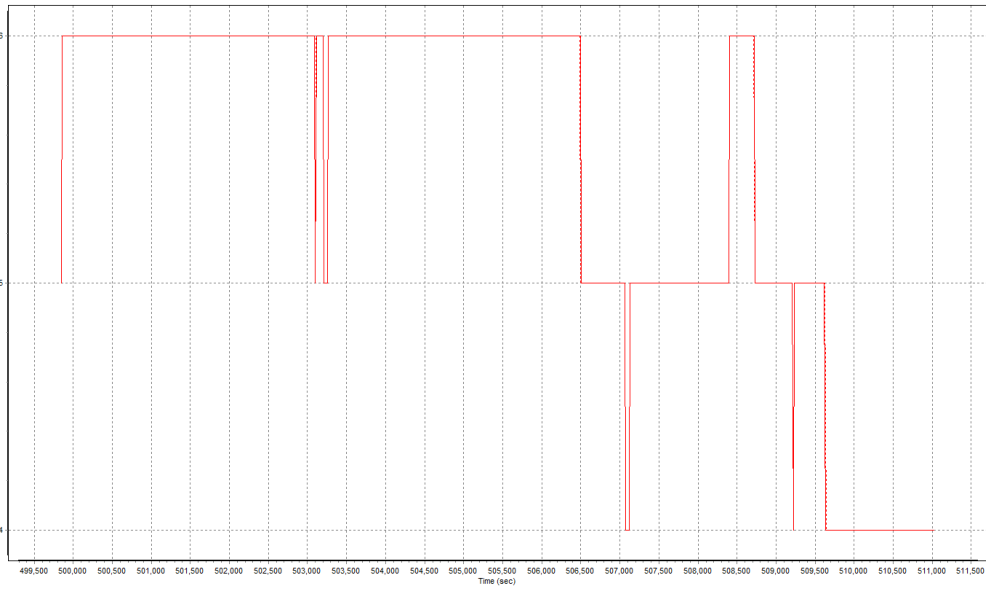


DOP



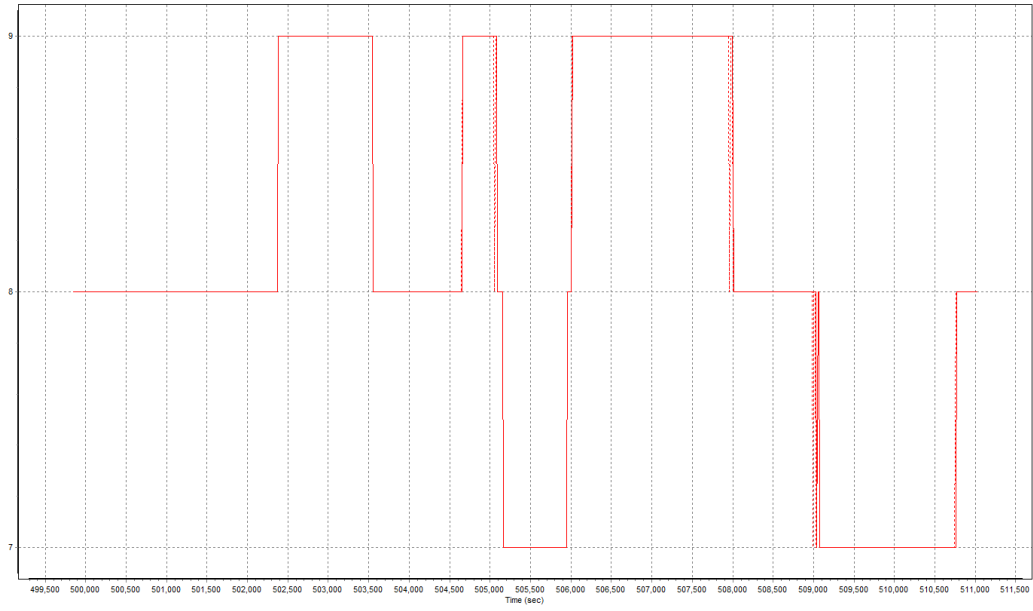
— DOP — HDOP — VDOP

Number of GLONASS Satellites

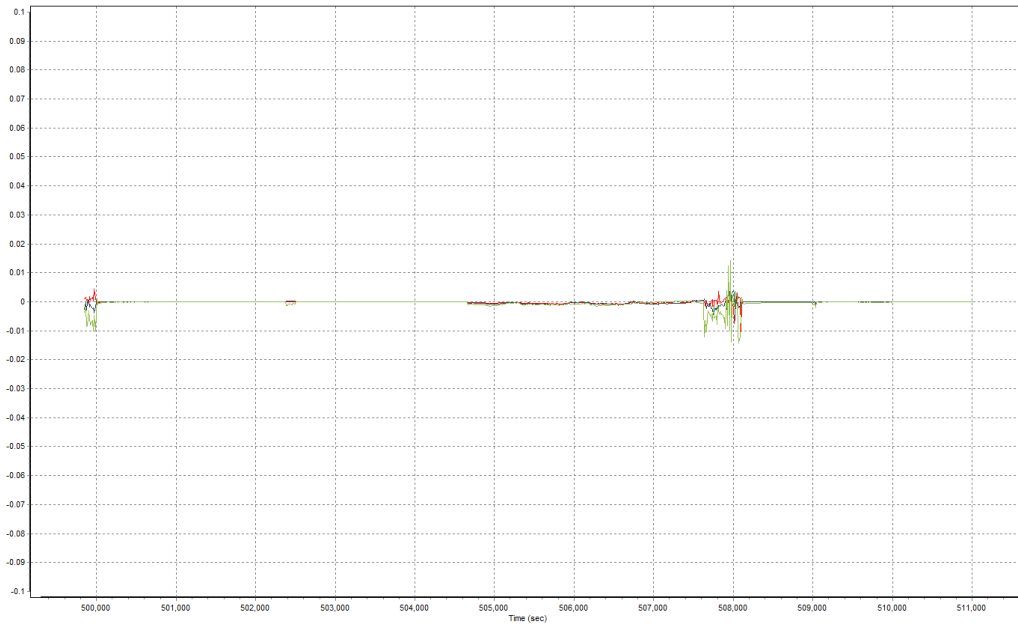


Forward  Reverse

Number of GPS Satellites

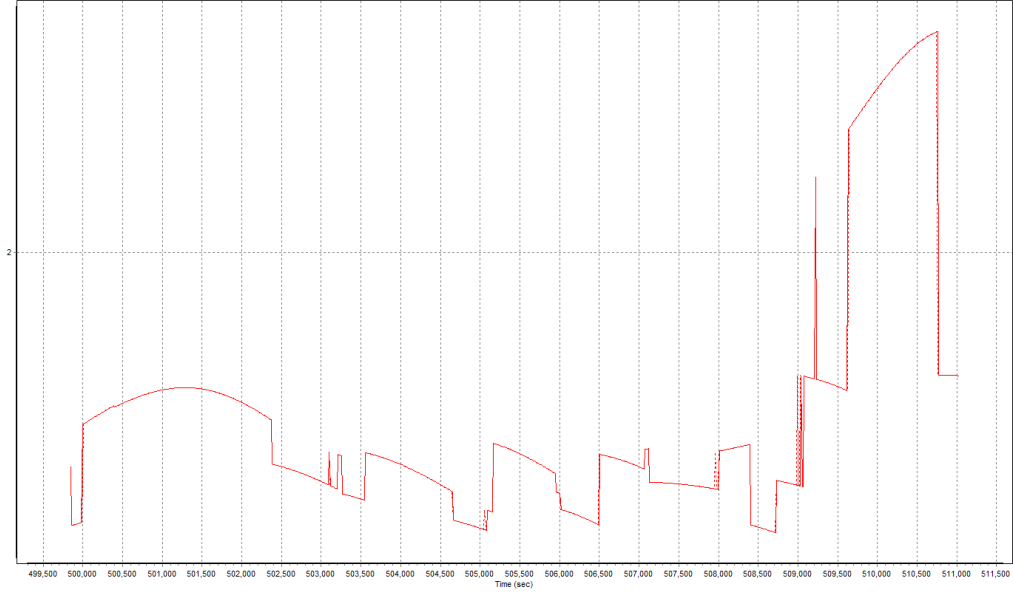


Forward  Reverse



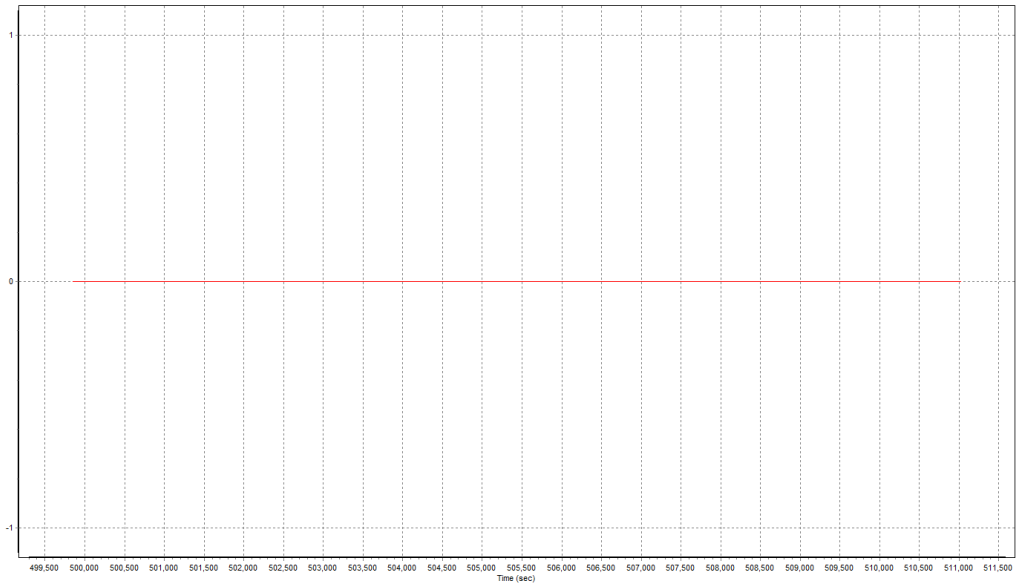
North (m)  East (m)  Down (m)  DR mode

PDOP



Forward  Reverse

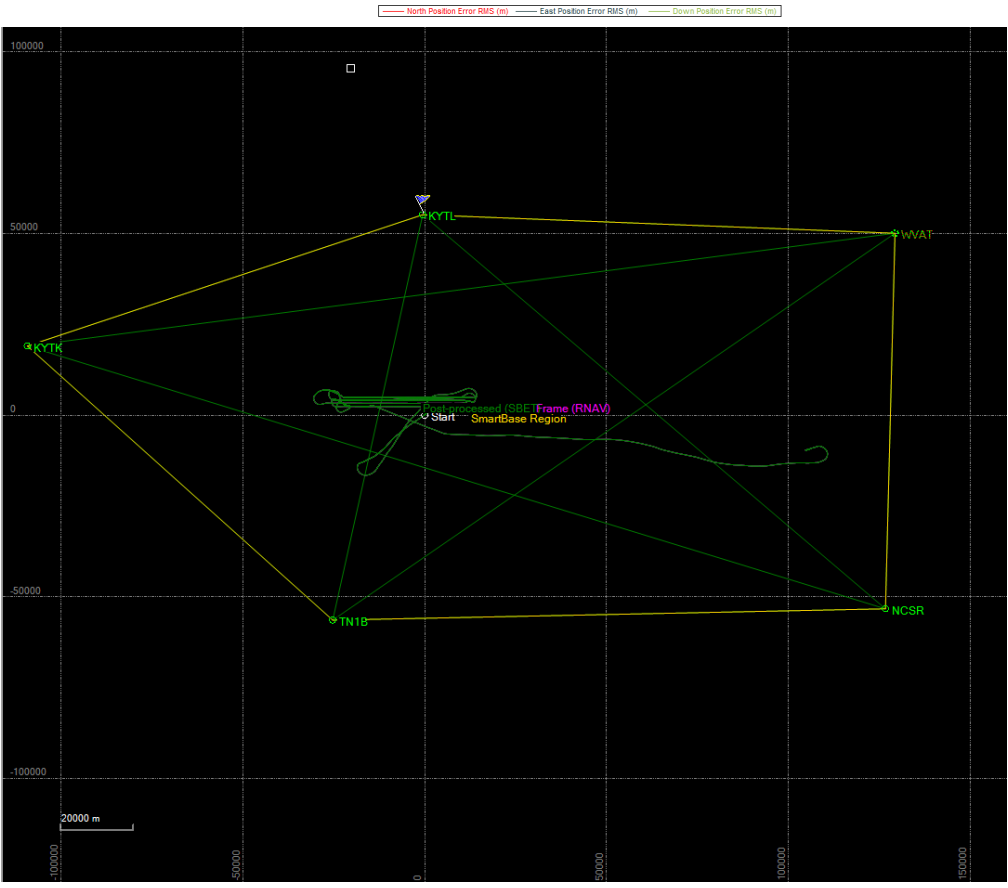
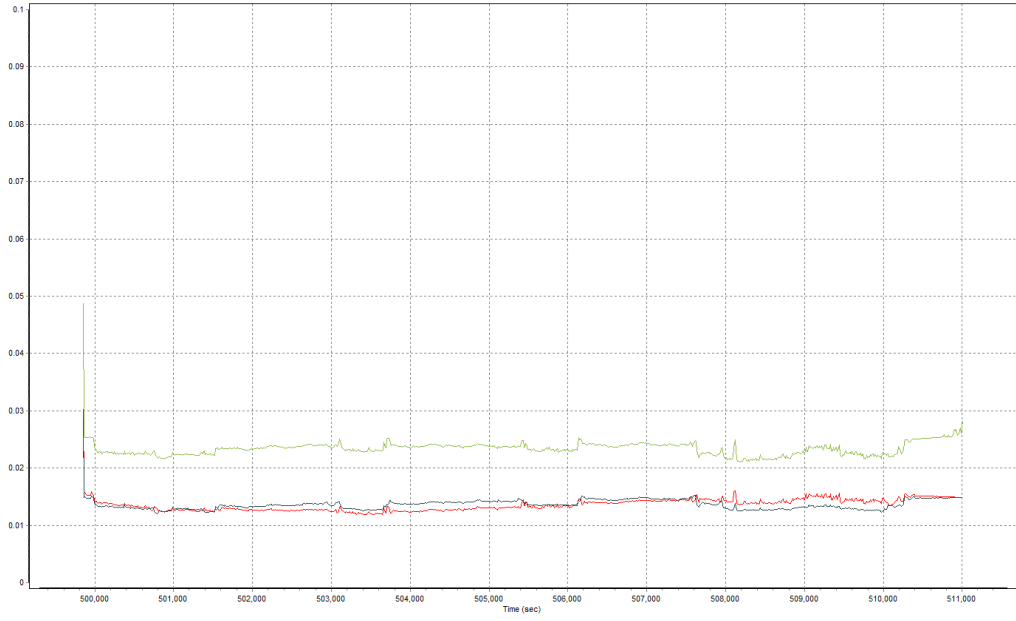
Processing mode



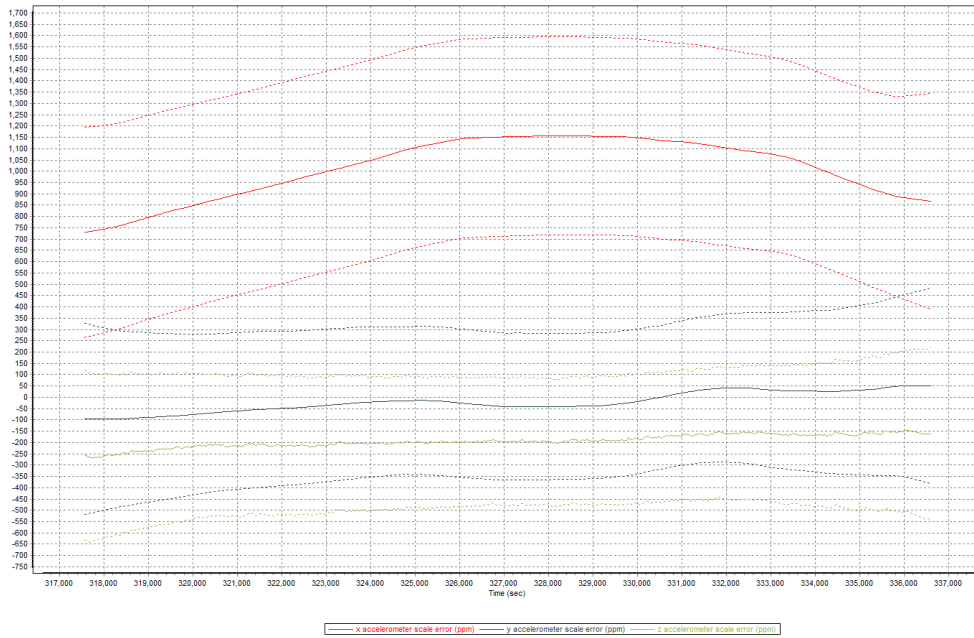
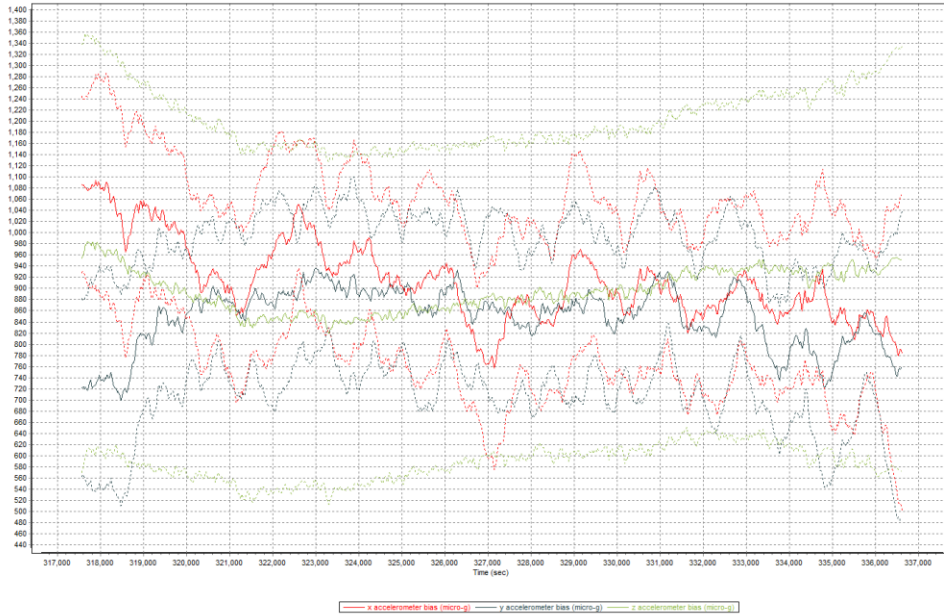
Forward  Reverse

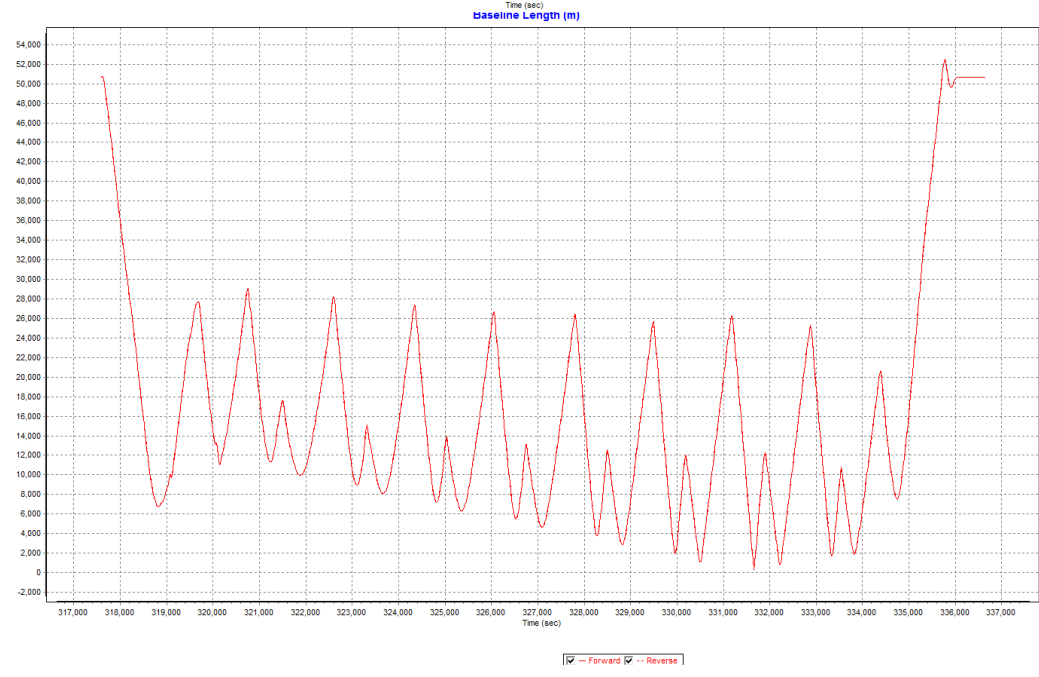
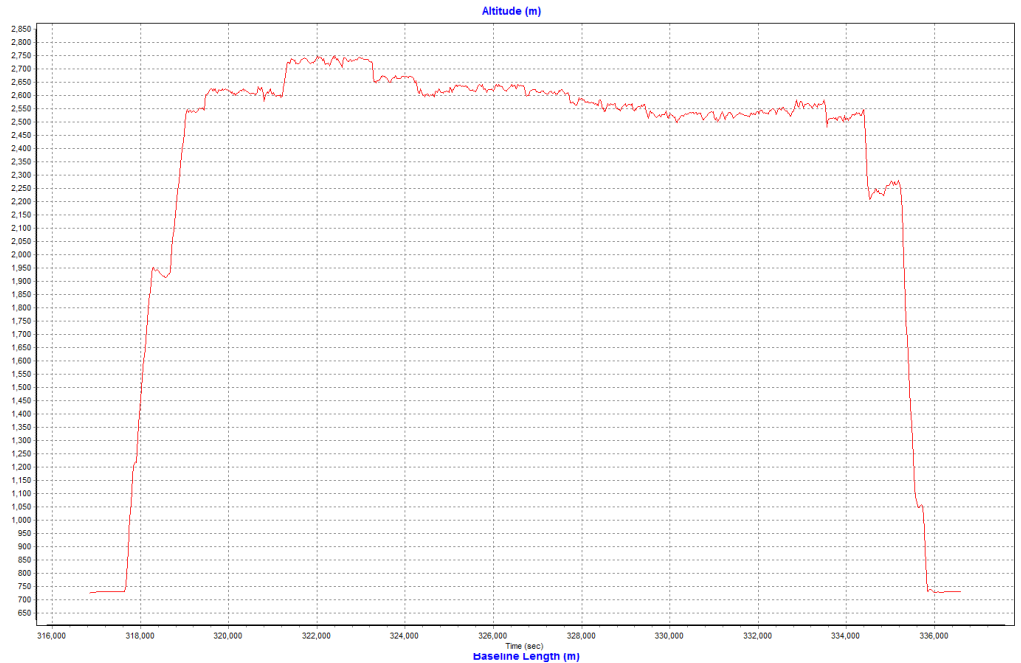
0 = Fixed NL, 1 = Fixed VL, 2 = Float, 3 = DGNS, 4 = RTCM, 5 = iAPPP, 6 = CIA, 7 = GNSS Nav, 8 = DR

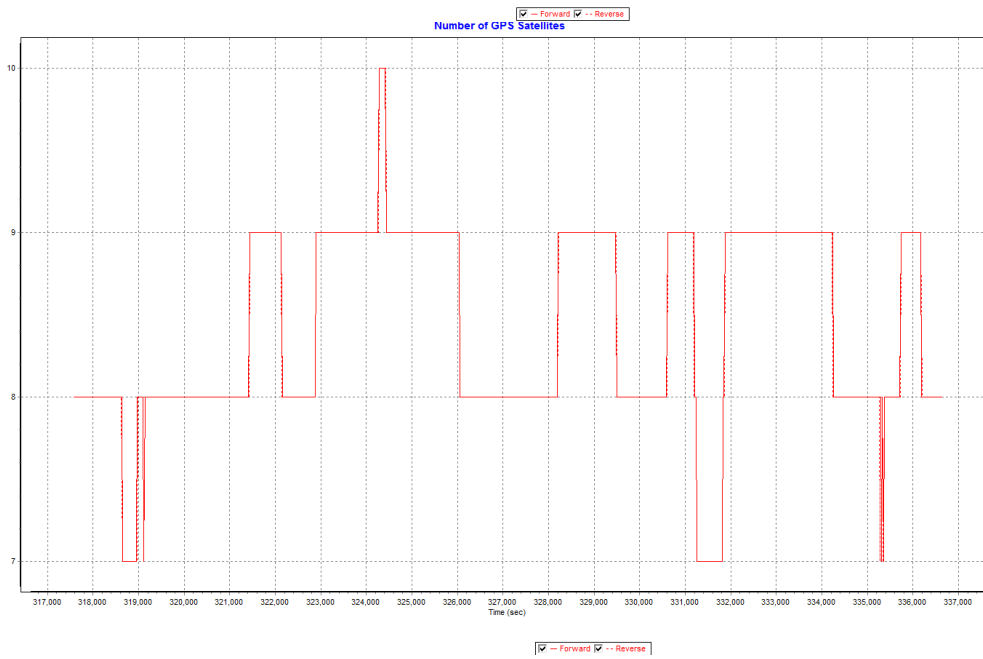


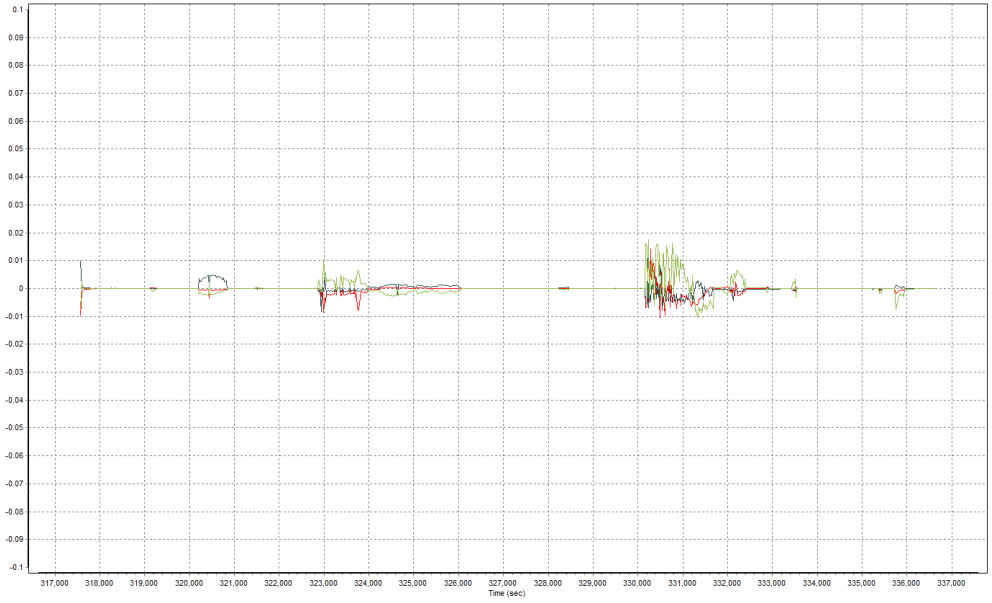


# UNB16342A



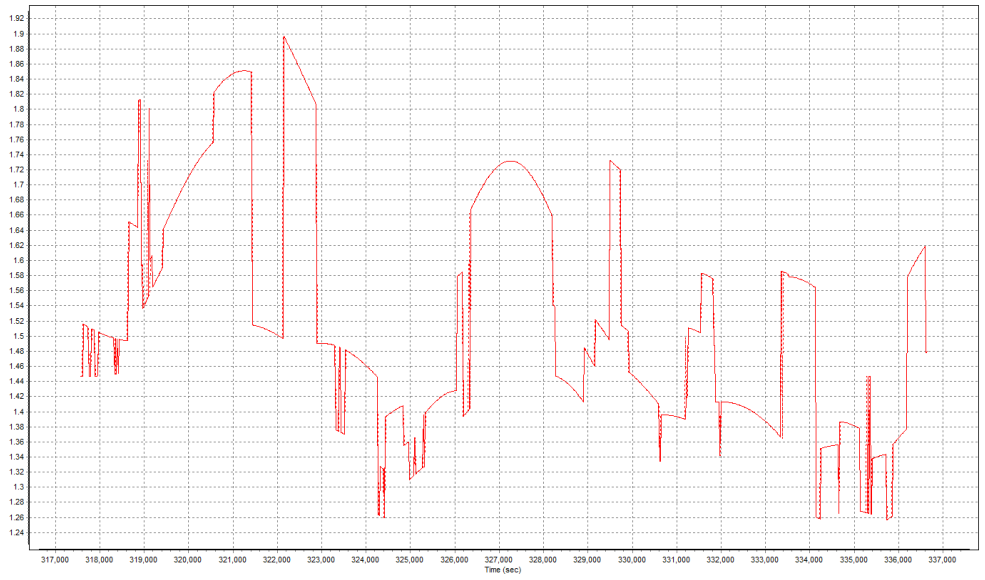






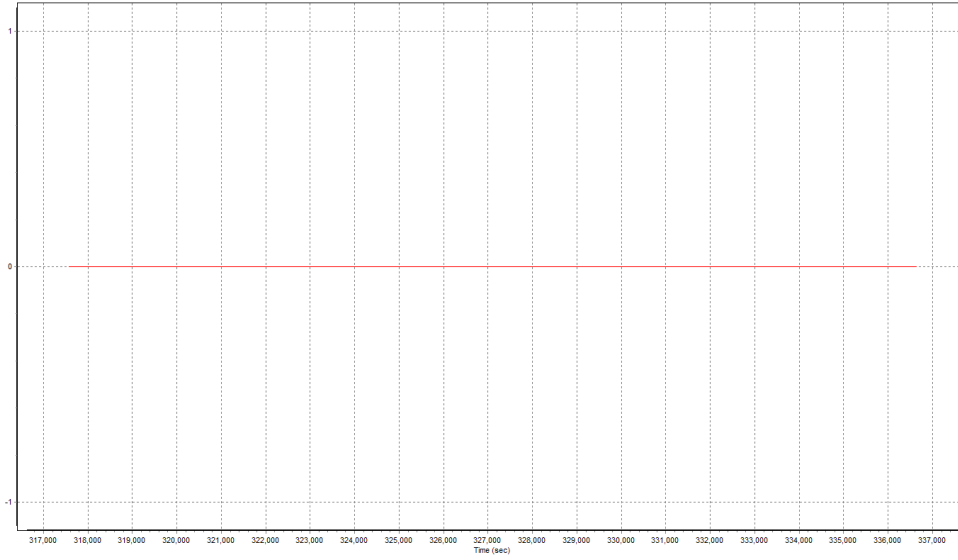
— North (m) — East (m) — Down (m) — DR mode

**PDOP**



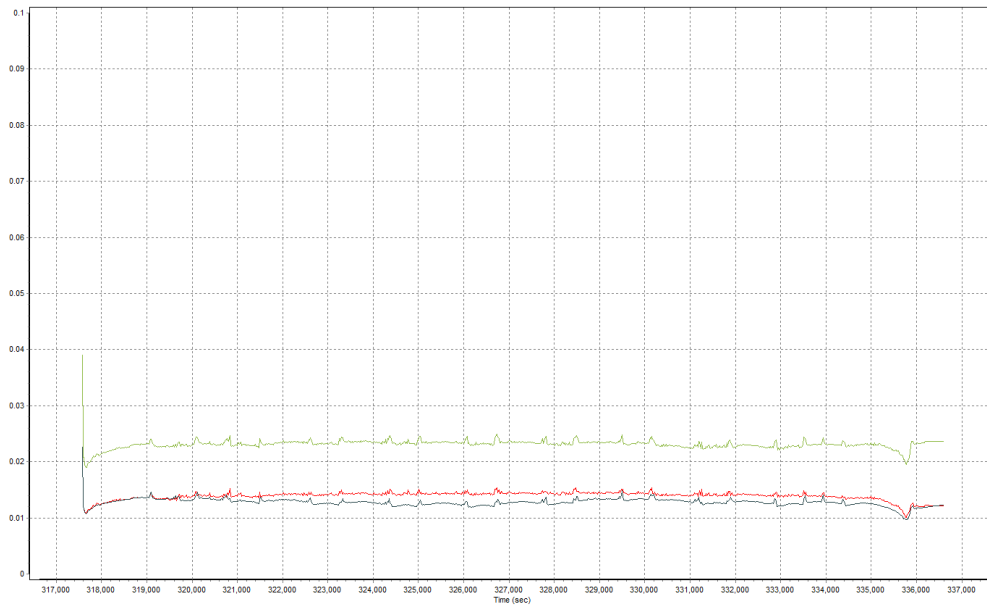
Forward  Reverse

Processing mode



Forward  Reverse

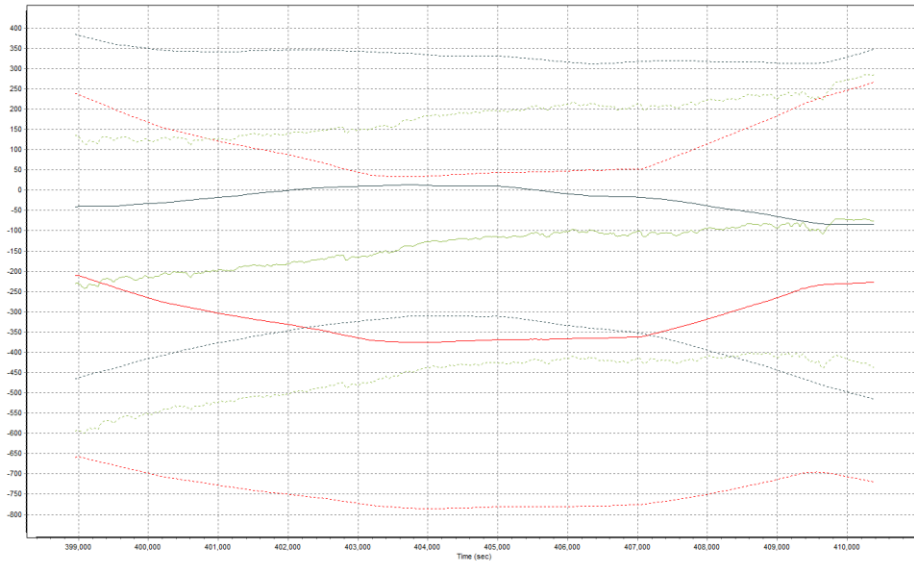
0 = Fixed Nt, 1 = Fixed Wt, 2 = Fixed, 3 = DGNS, 4 = RTCM, 5 = UPPP, 6 = CIA, 7 = GNSS Nav, 8 = DR



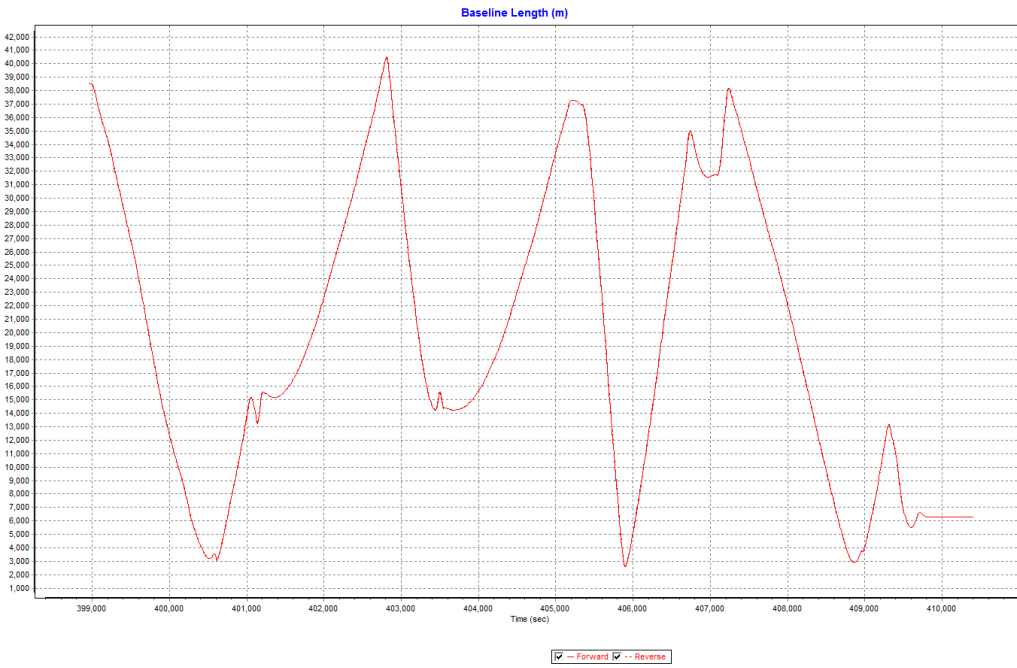
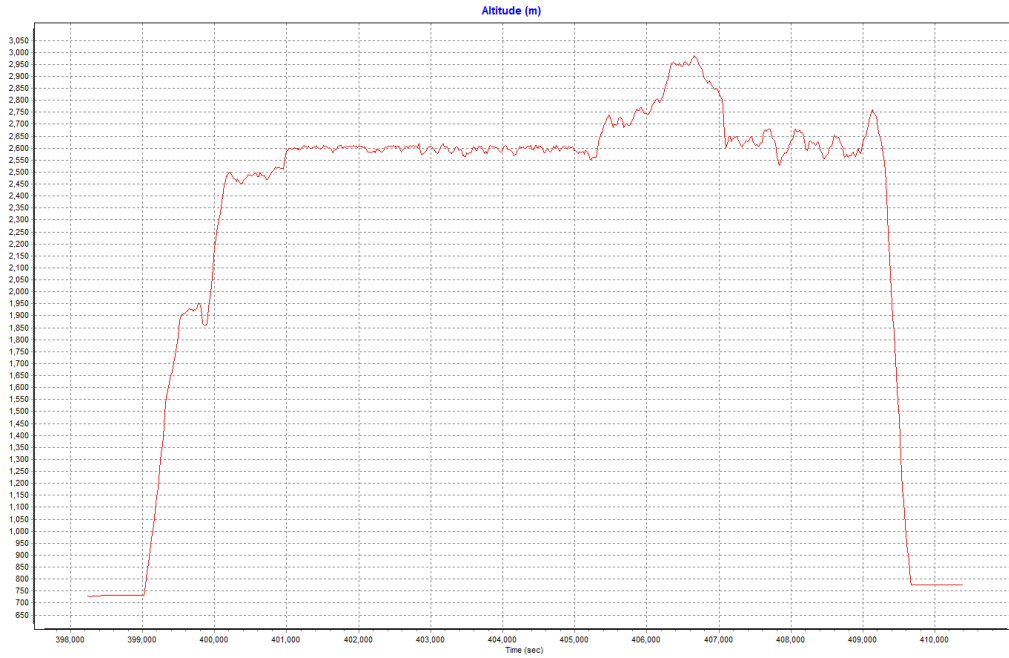
— North Position Error RMS (m) — East Position Error RMS (m) — Down Position Error RMS (m)



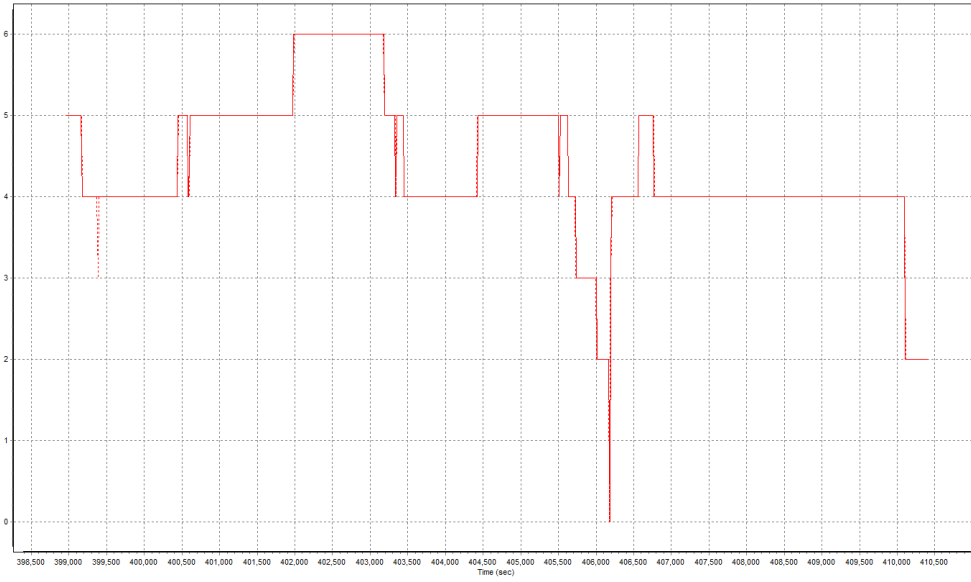
# UNB16343A





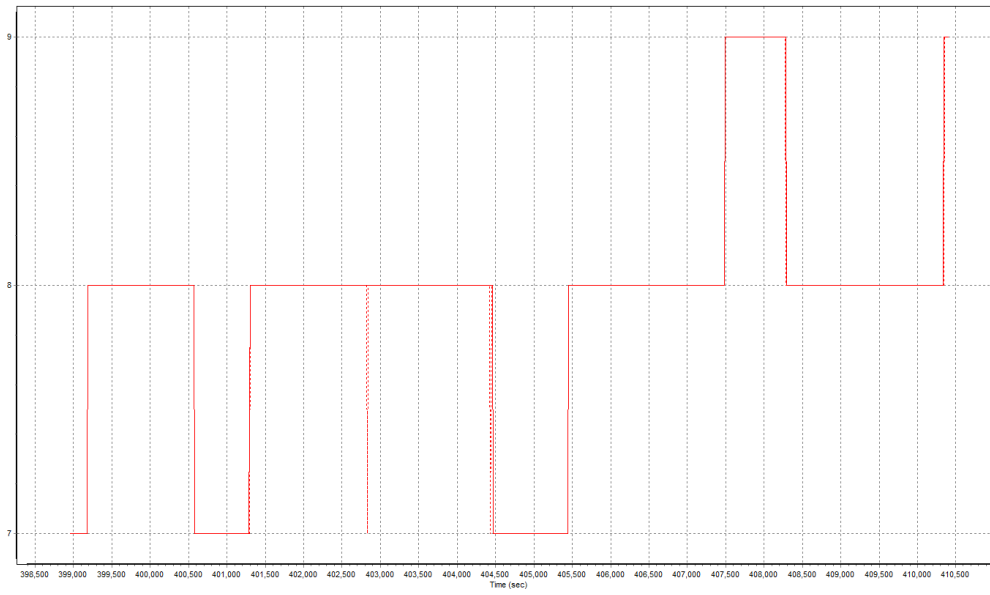


Number of GLONASS Satellites

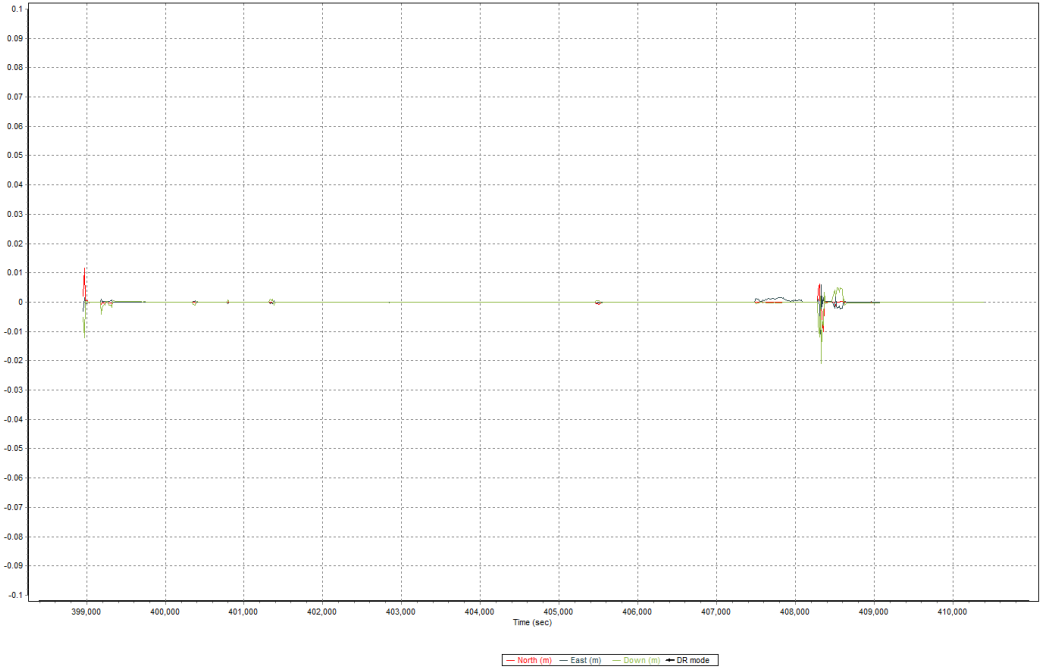


Forward  Reverse

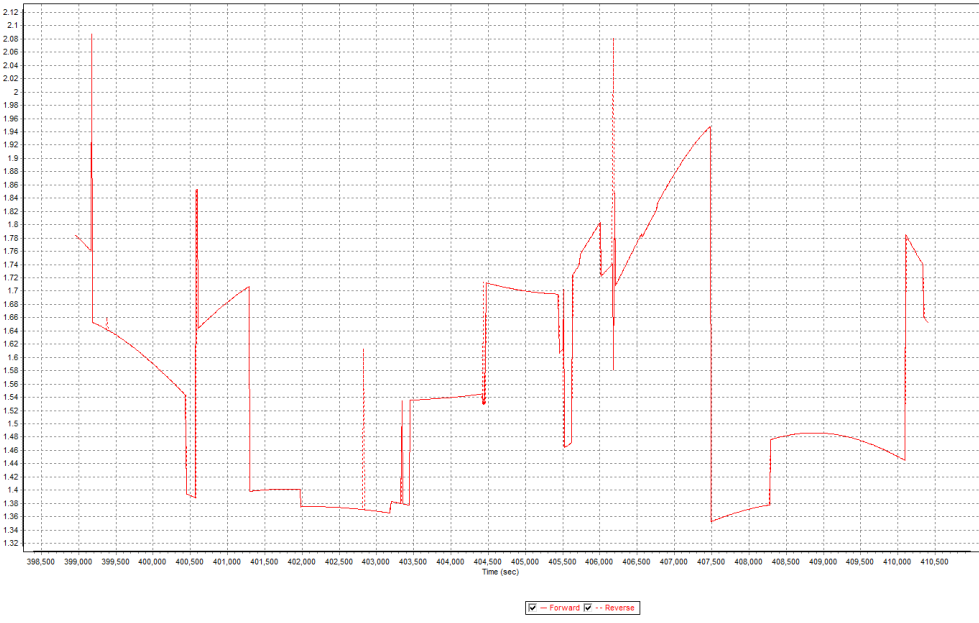
Number of GPS Satellites



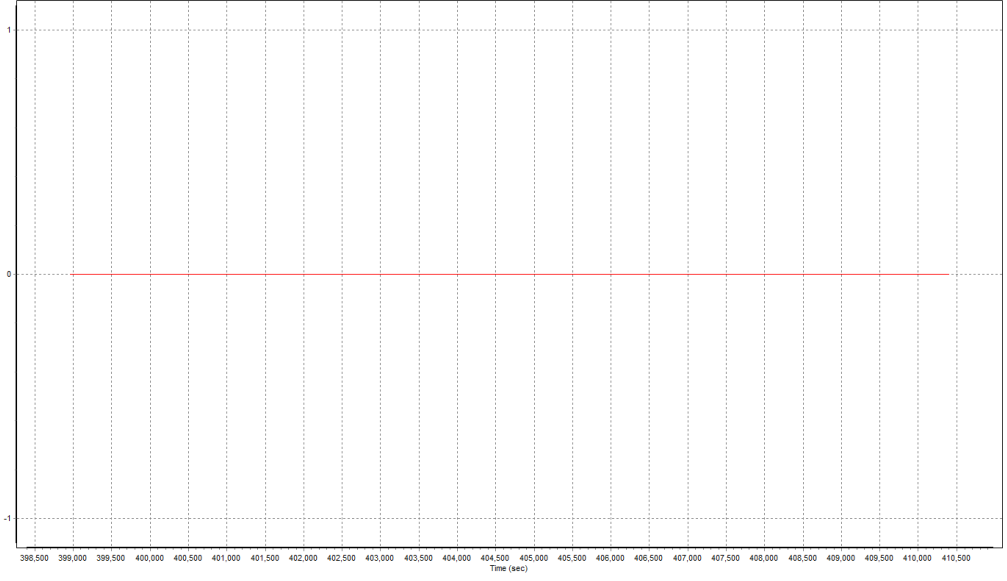
Forward  Reverse



PDOP

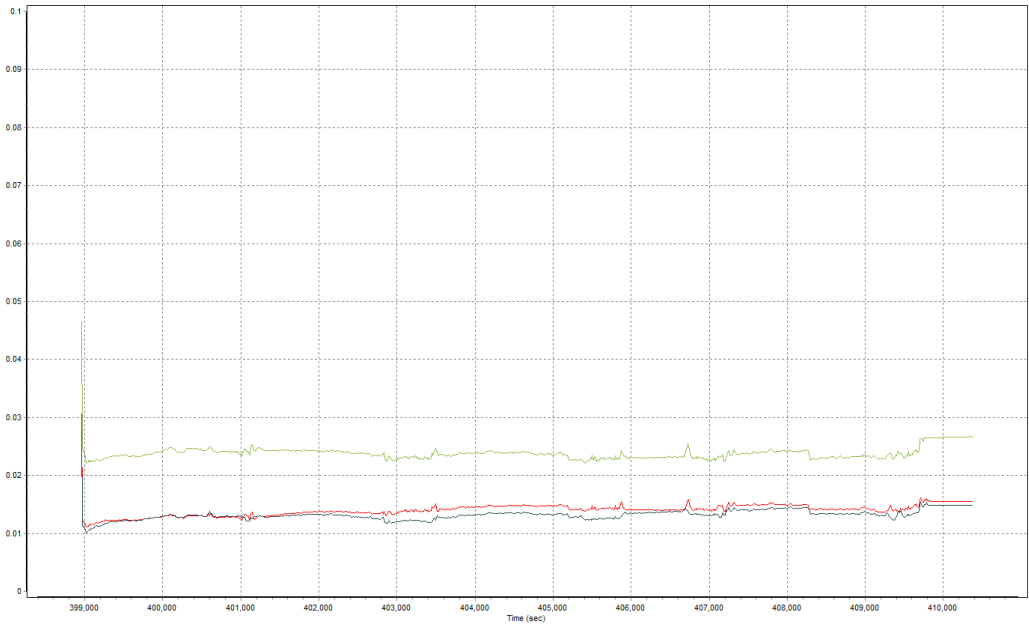


Processing mode

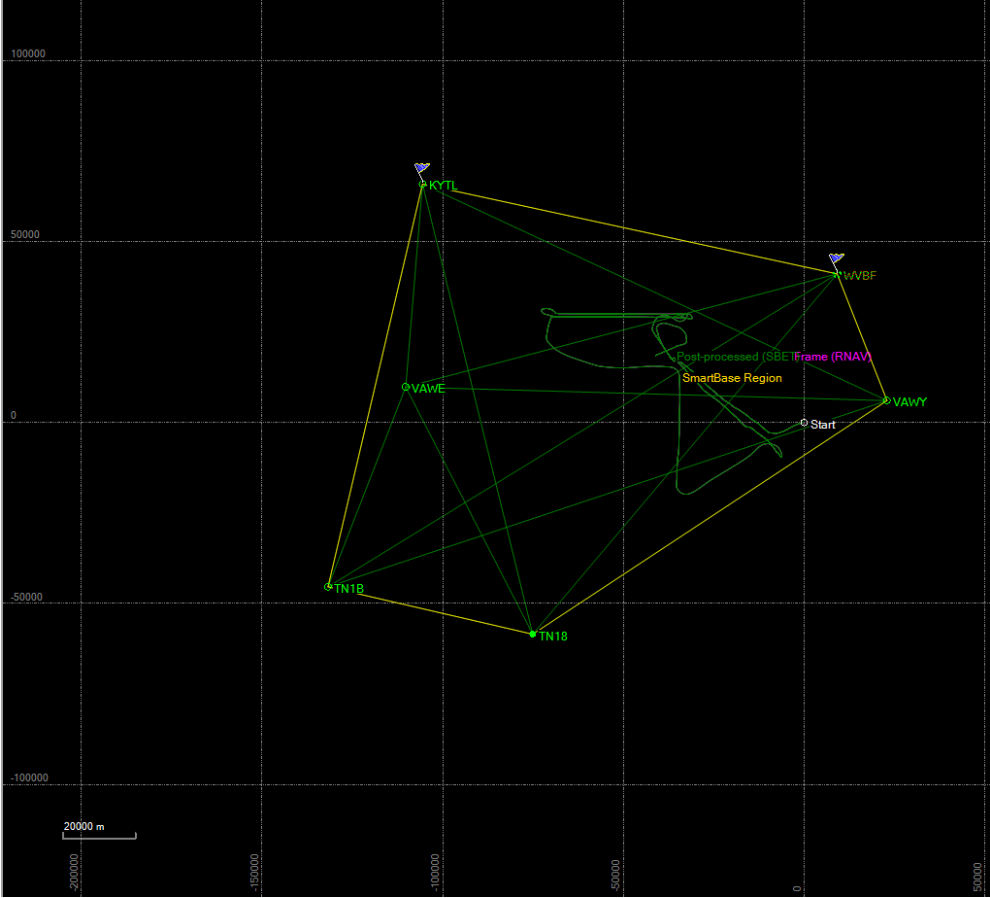


Forward  Reverse

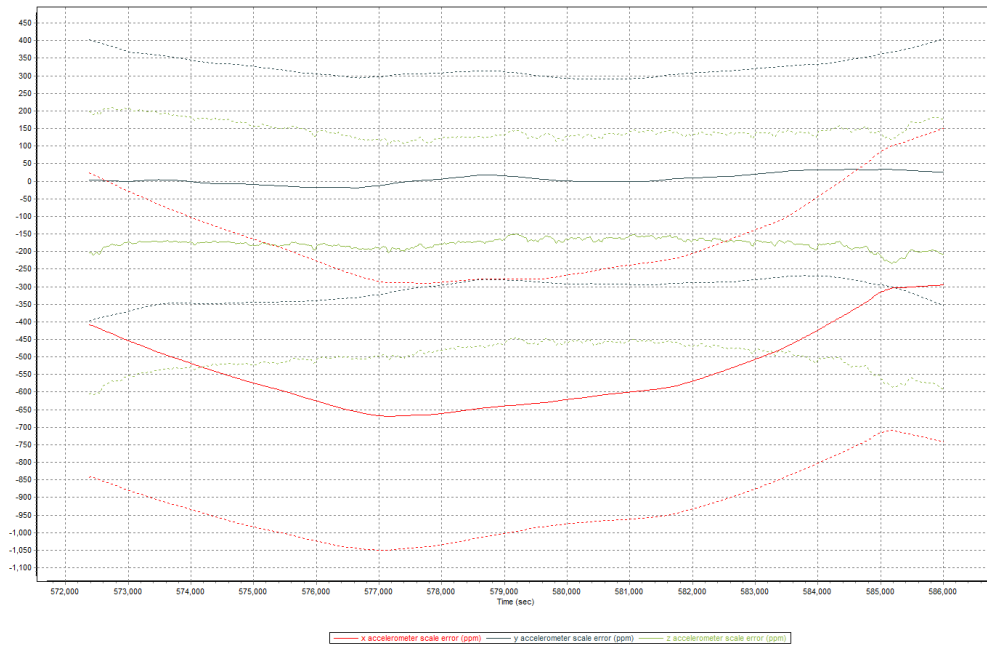
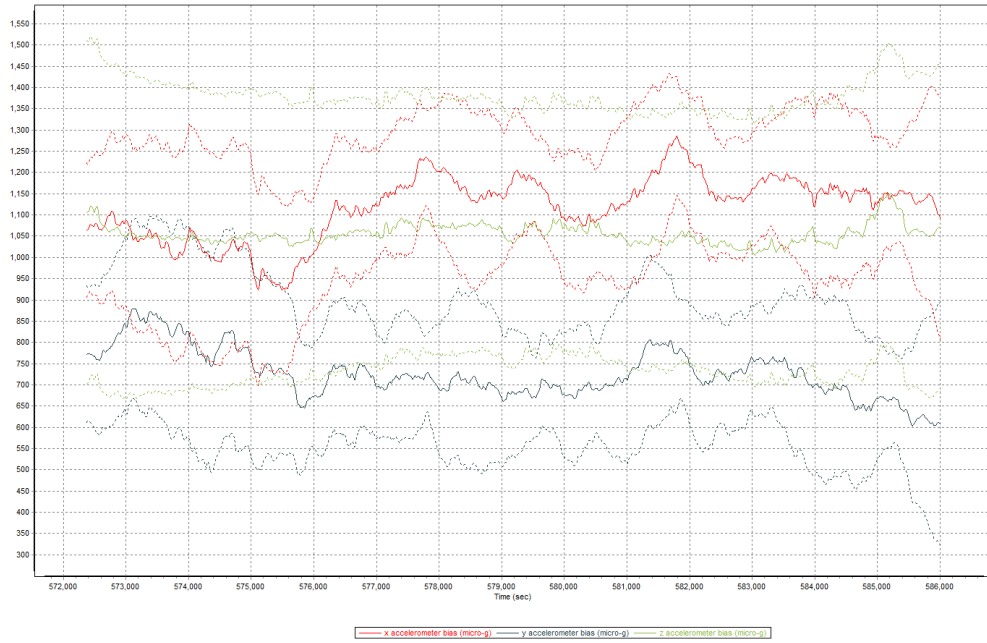
0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = CIA, 7 = GNSS Nav, 8 = DR

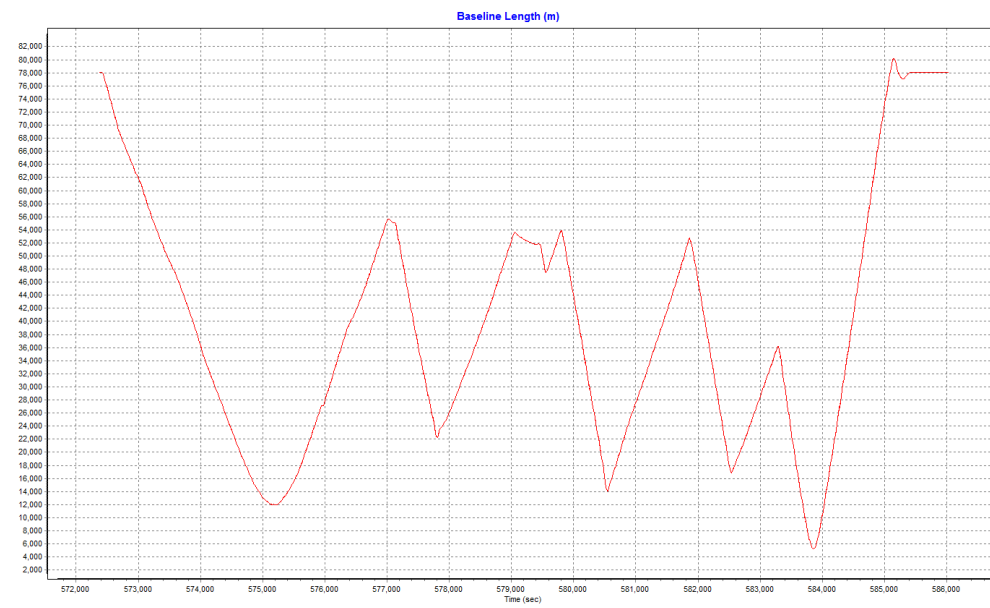
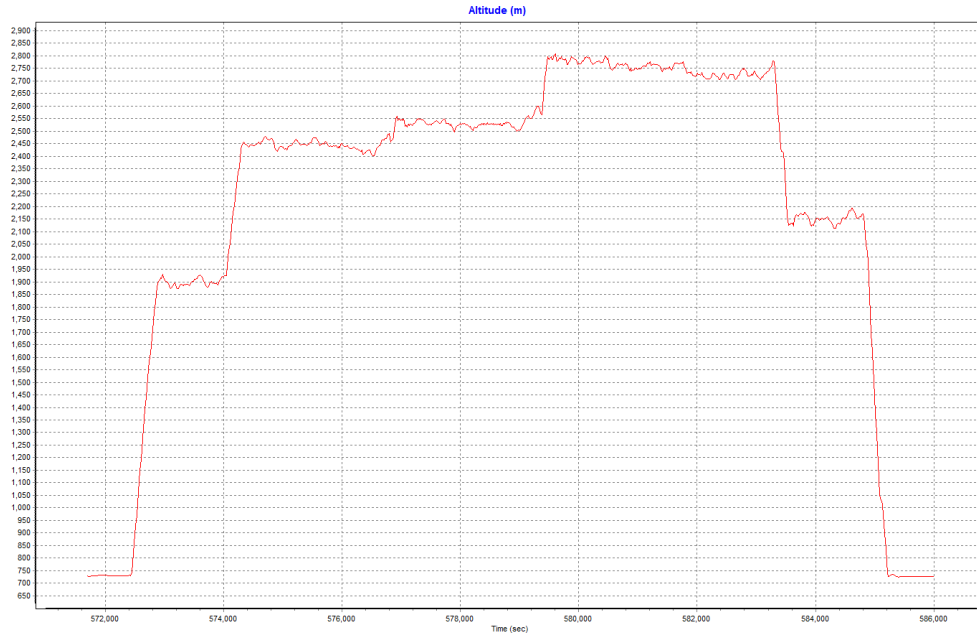


— North Position Error RMS (m) — East Position Error RMS (m) — Down Position Error RMS (m)



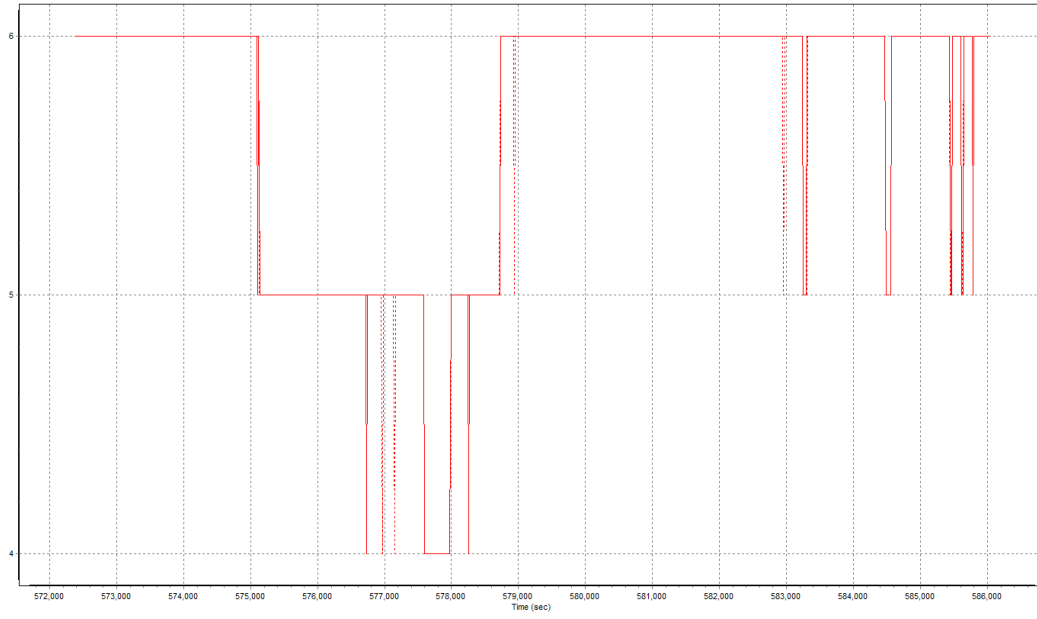
# UNB16345A





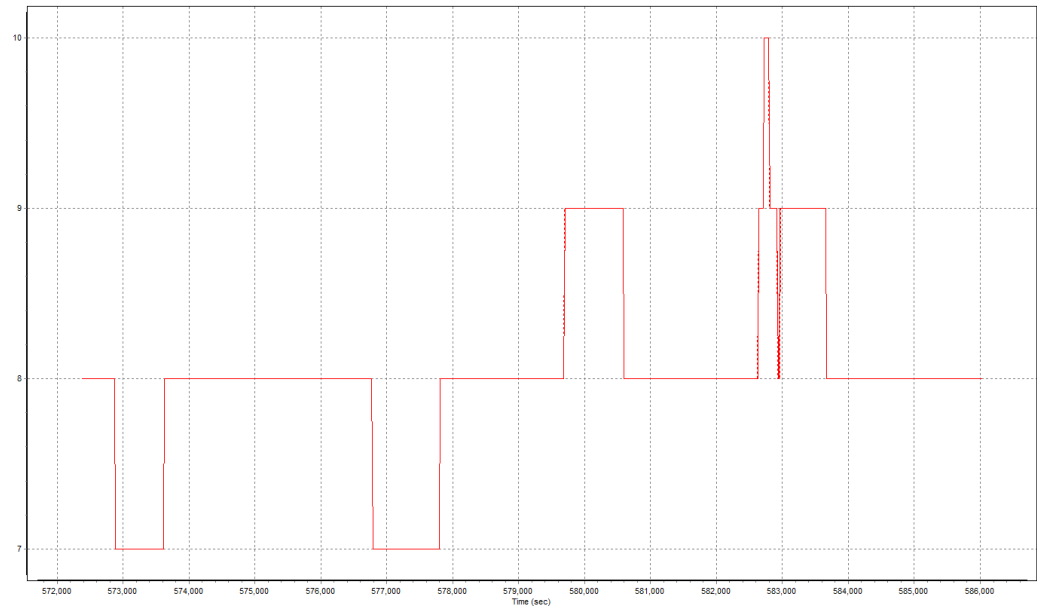
Forward  Reverse

Number of GLONASS Satellites



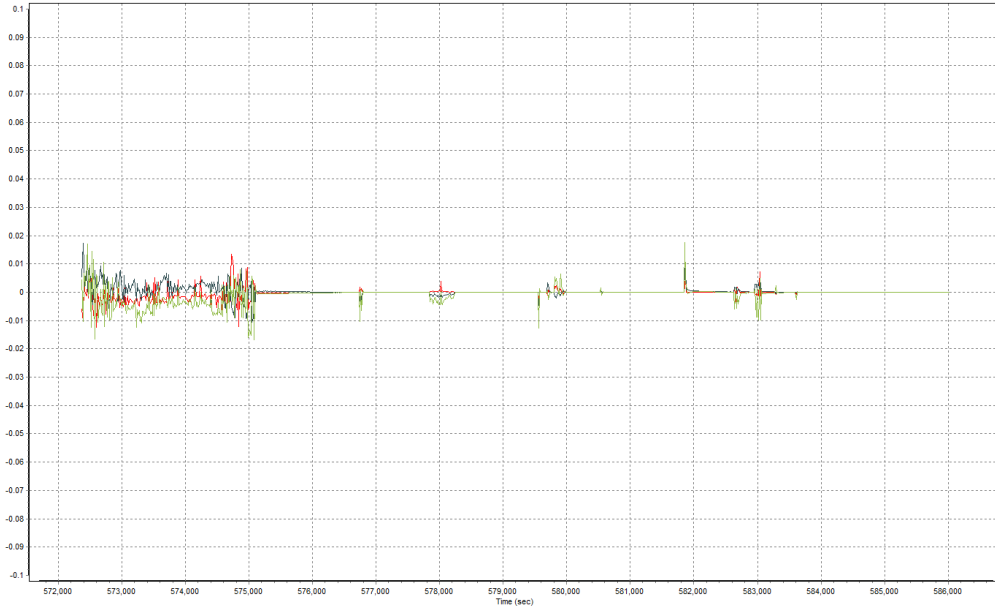
Forward  Reverse

Number of GPS Satellites

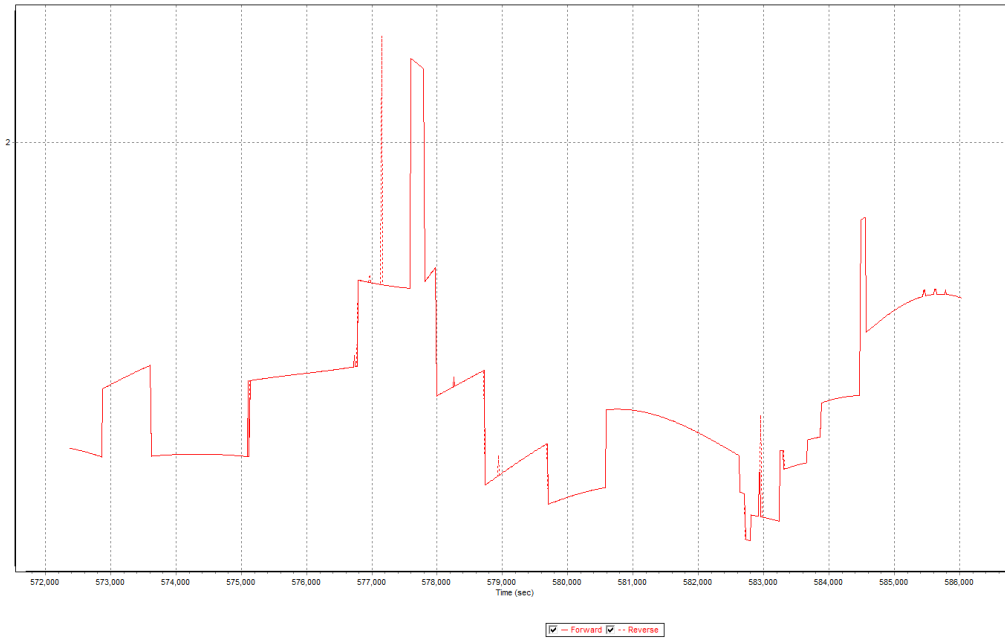


Forward  Reverse

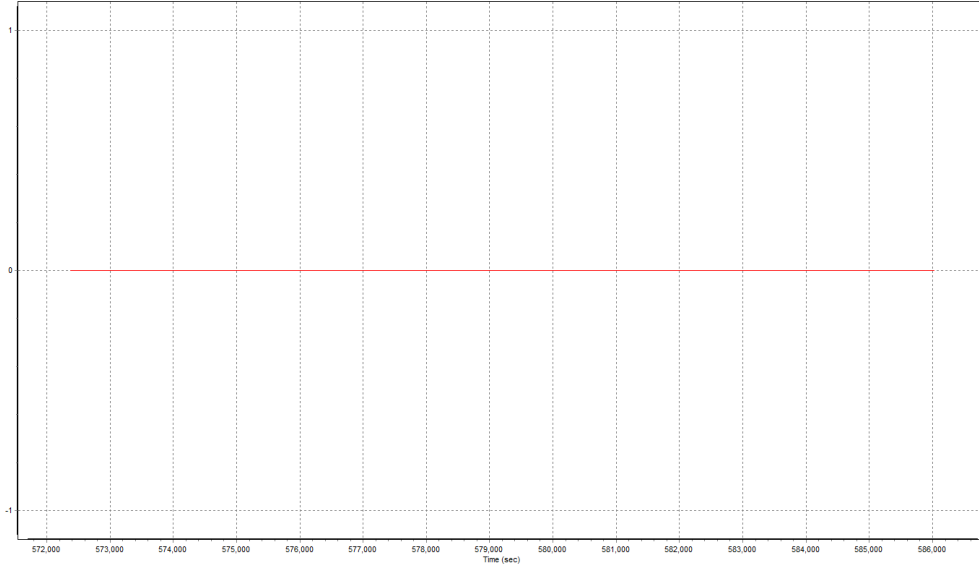




PDOP

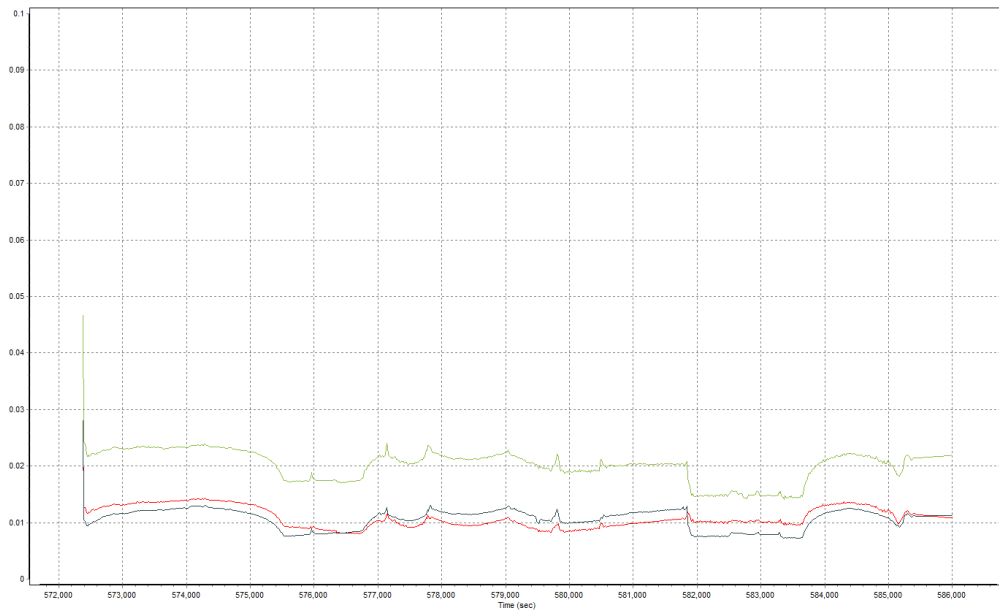


Processing mode

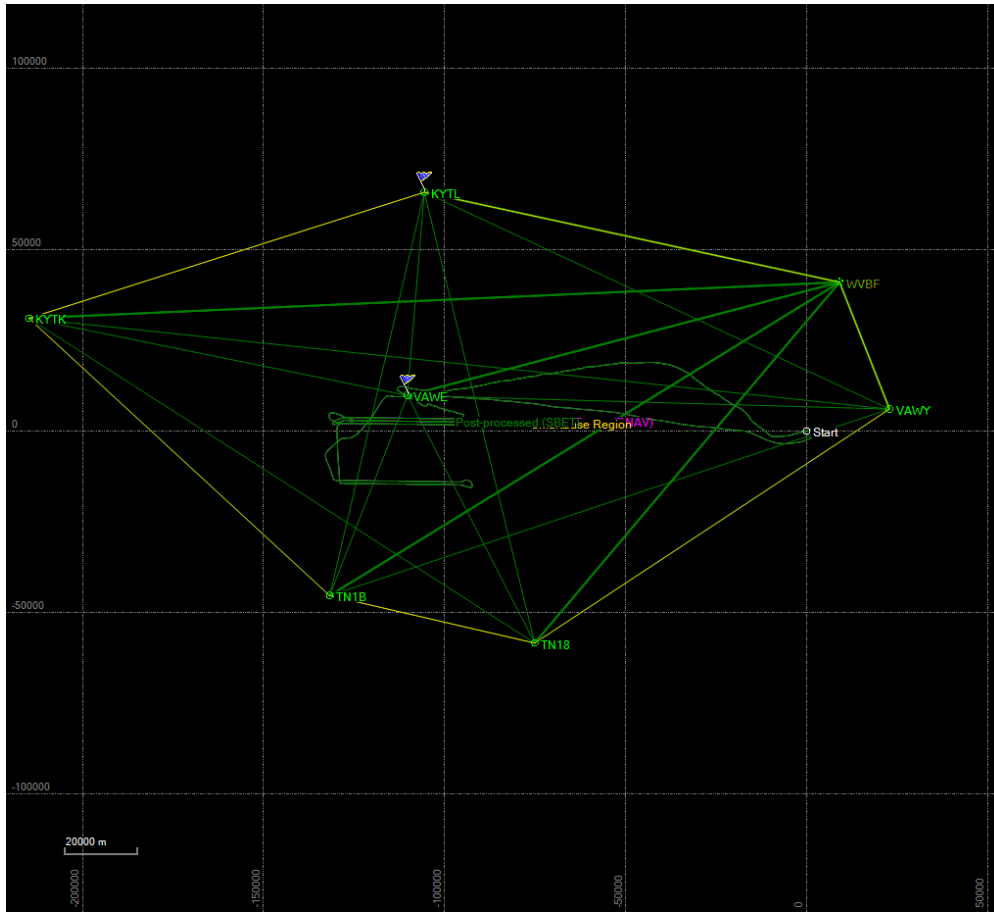


0 = Fixed NL, 1 = Fixed VL, 2 = Fixed, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = CIA, 7 = GNSS Nav, 8 = DR

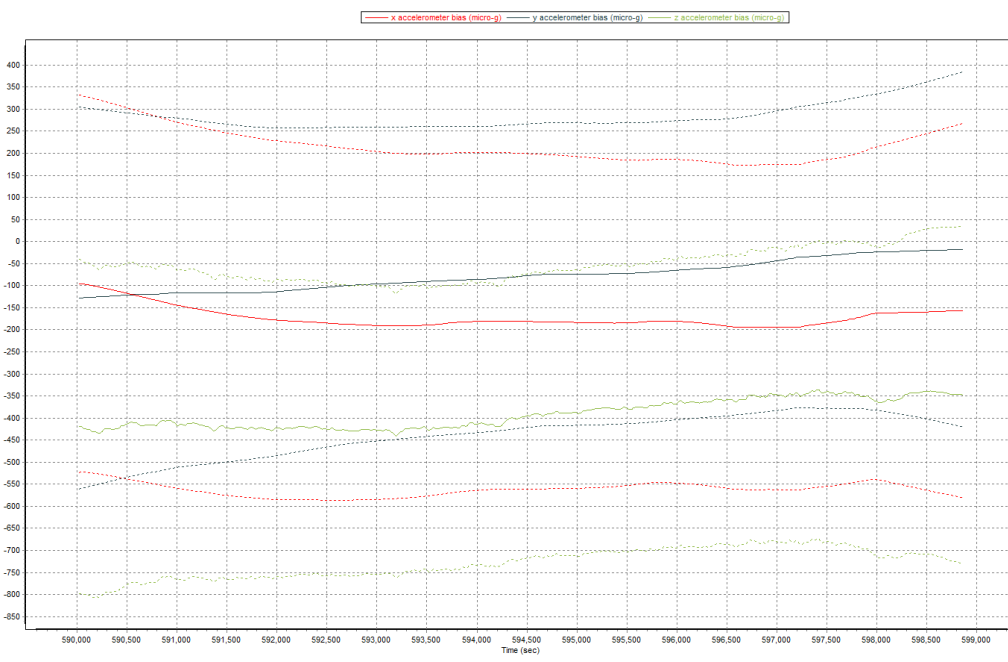
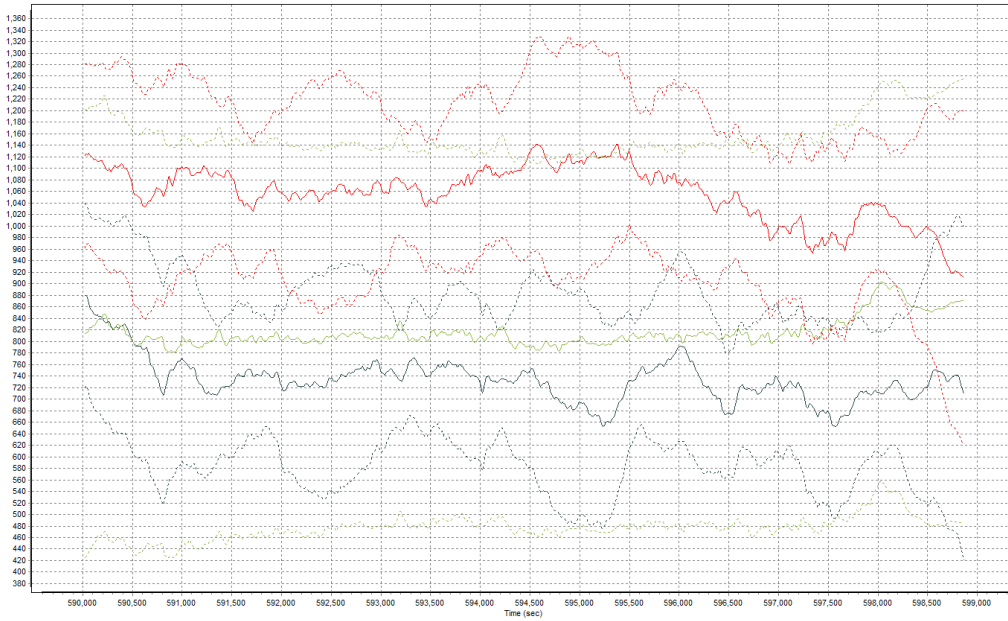
Forward  Reverse

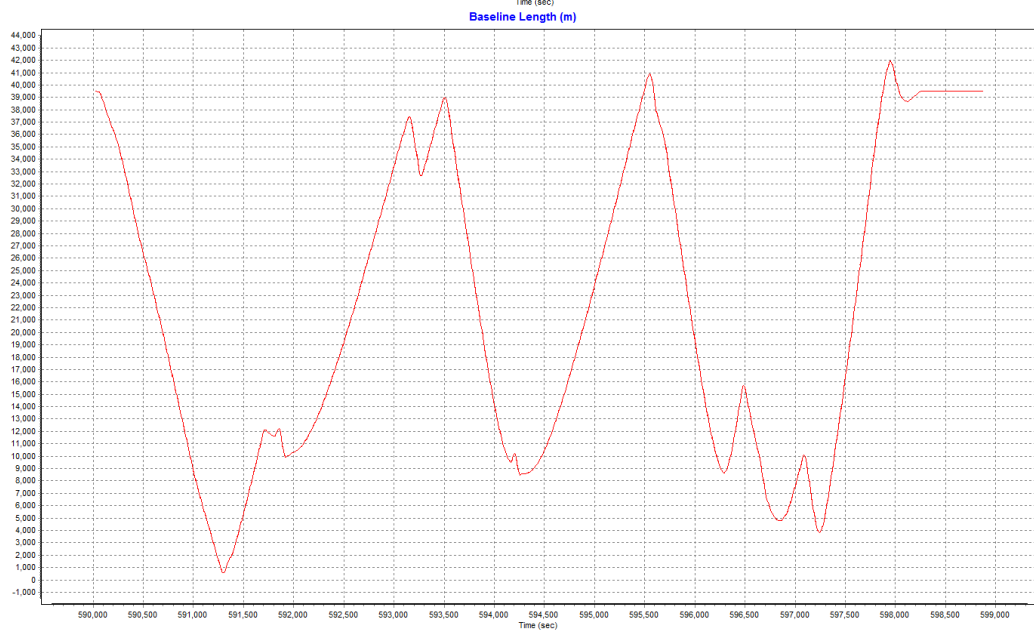
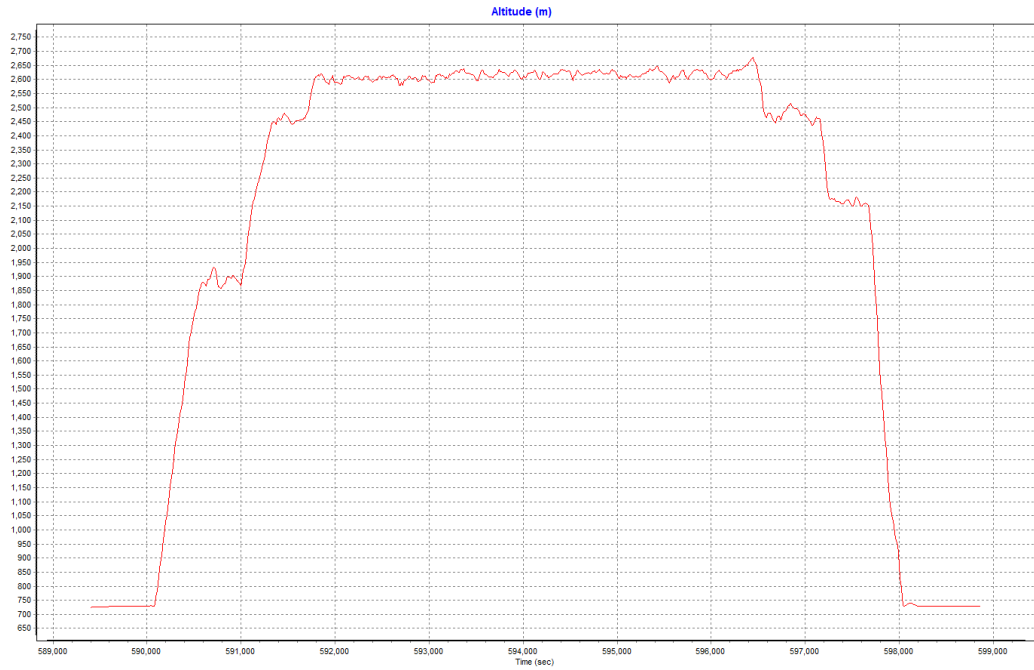


North Position Error RMS (m) East Position Error RMS (m) Down Position Error RMS (m)



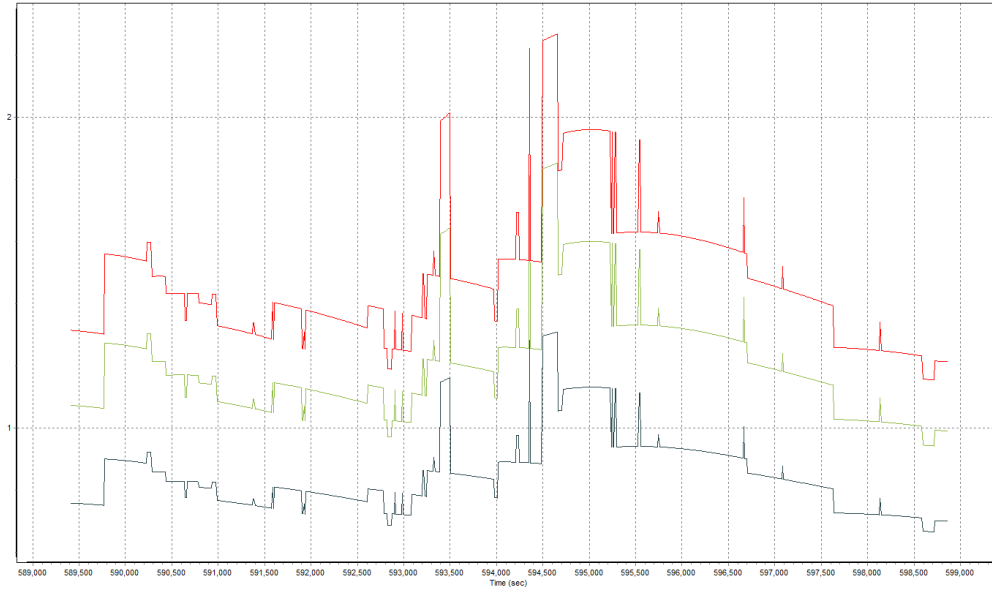
# UNB16345B





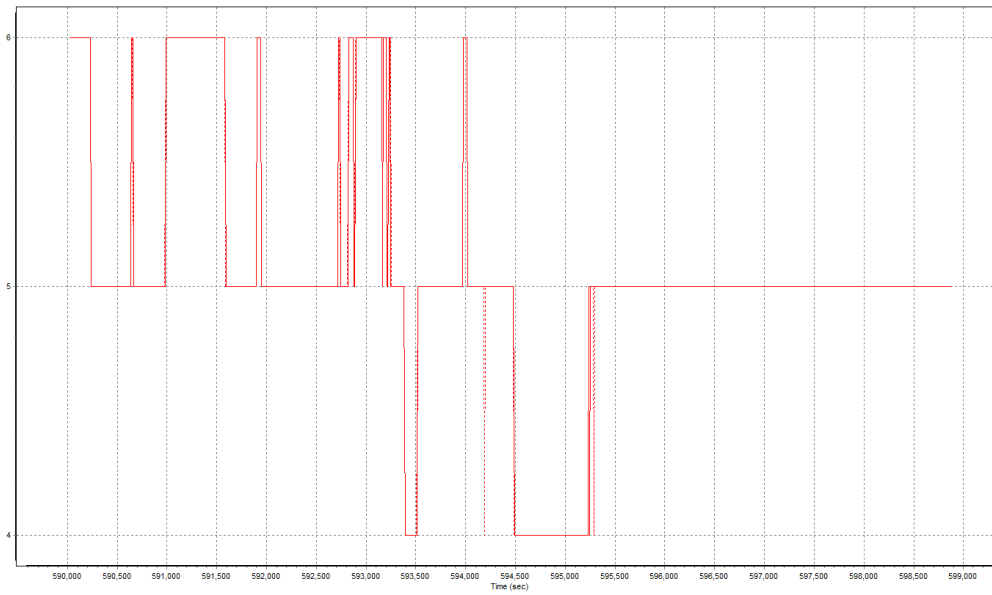
Forward  Reverse

DOP



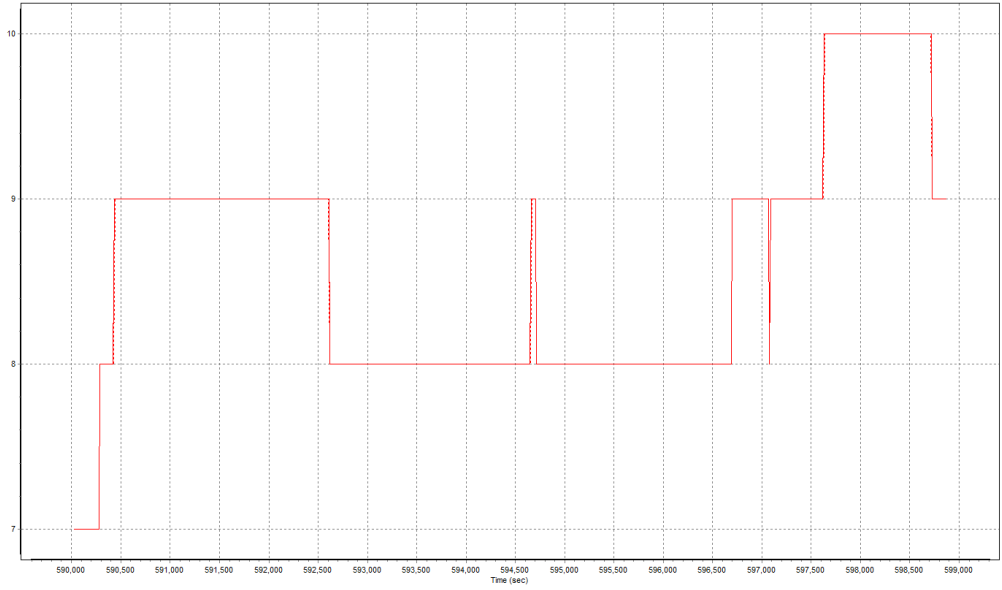
— PDOP — HDOP — VDOP

Number of GLONASS Satellites

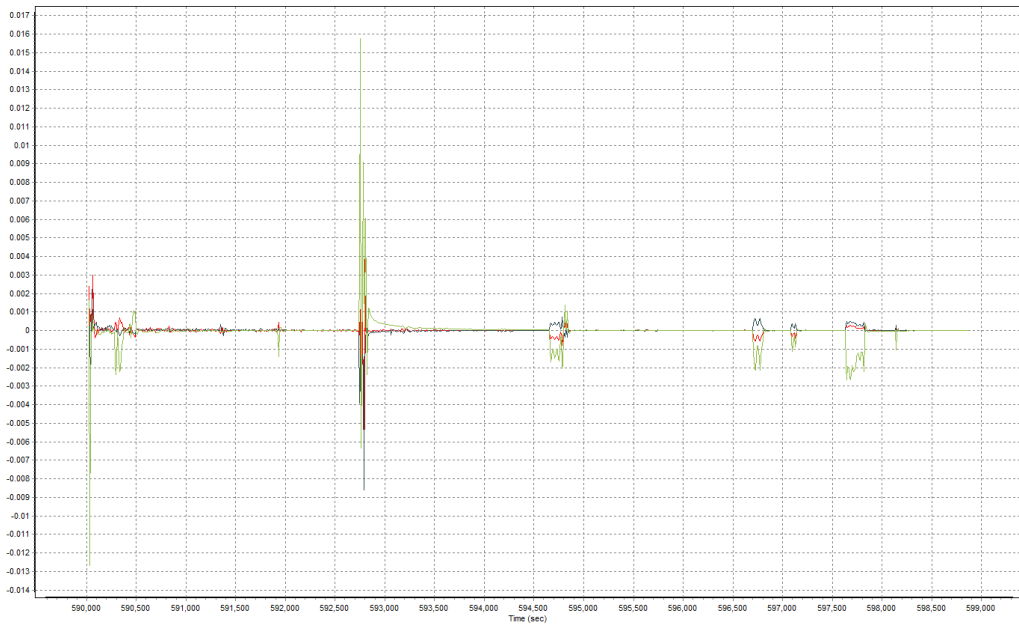


Forward  Reverse

Number of GPS Satellites



Forward  Reverse



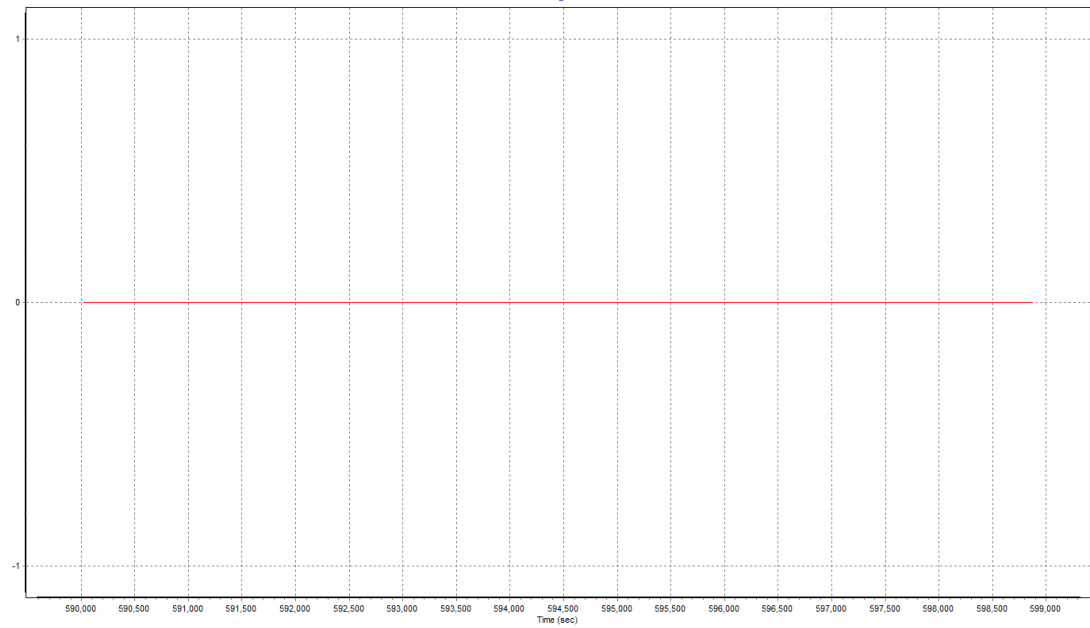
North (m)  East (m)  Down (m)  DR mode

PDOP



Forward  Reverse

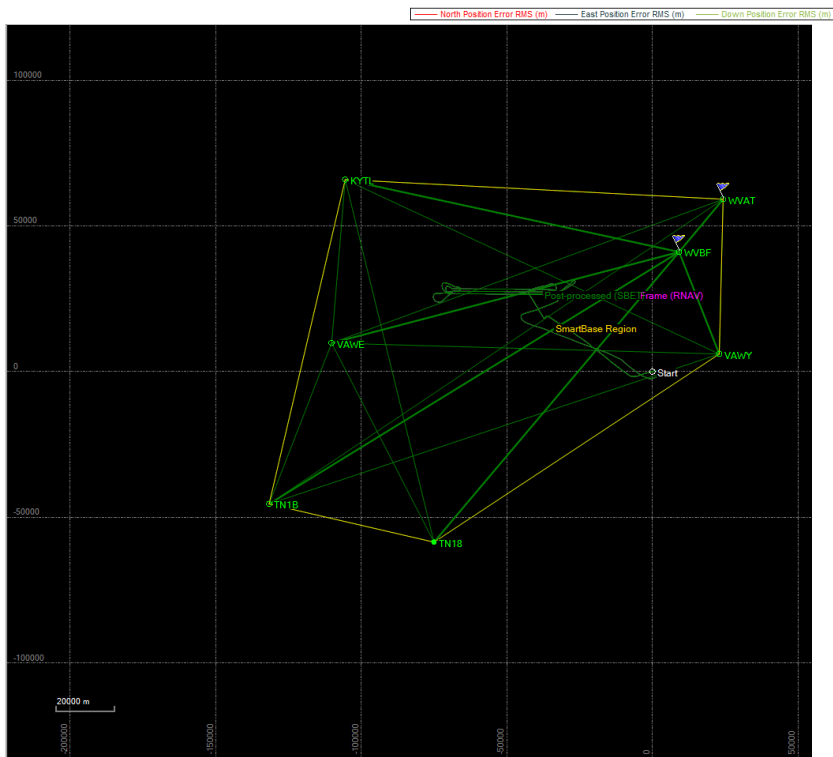
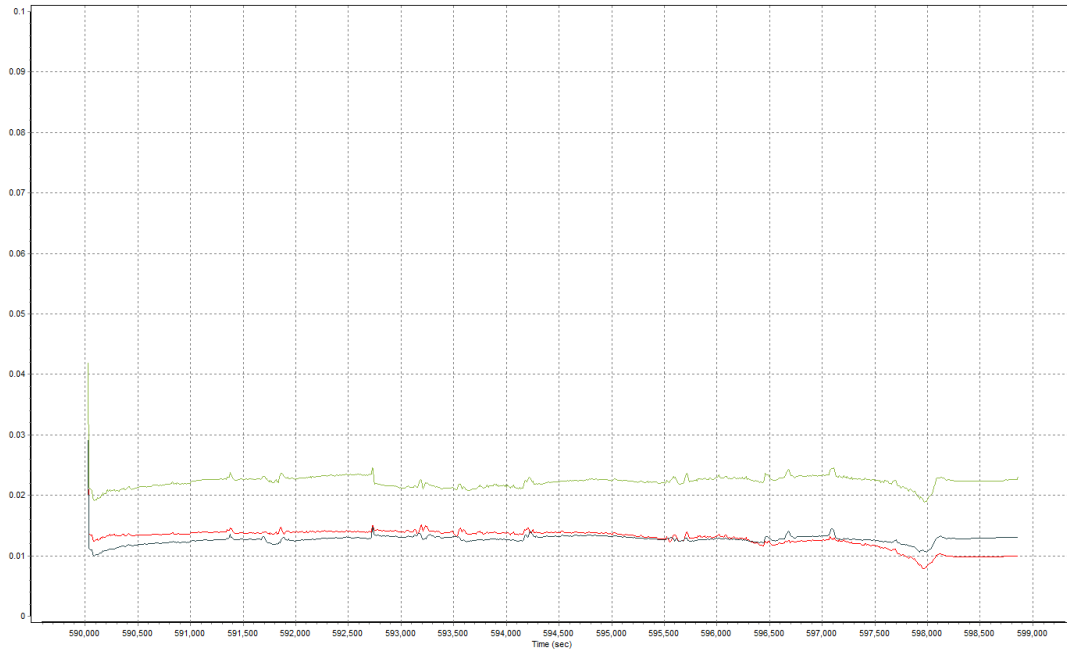
Processing mode



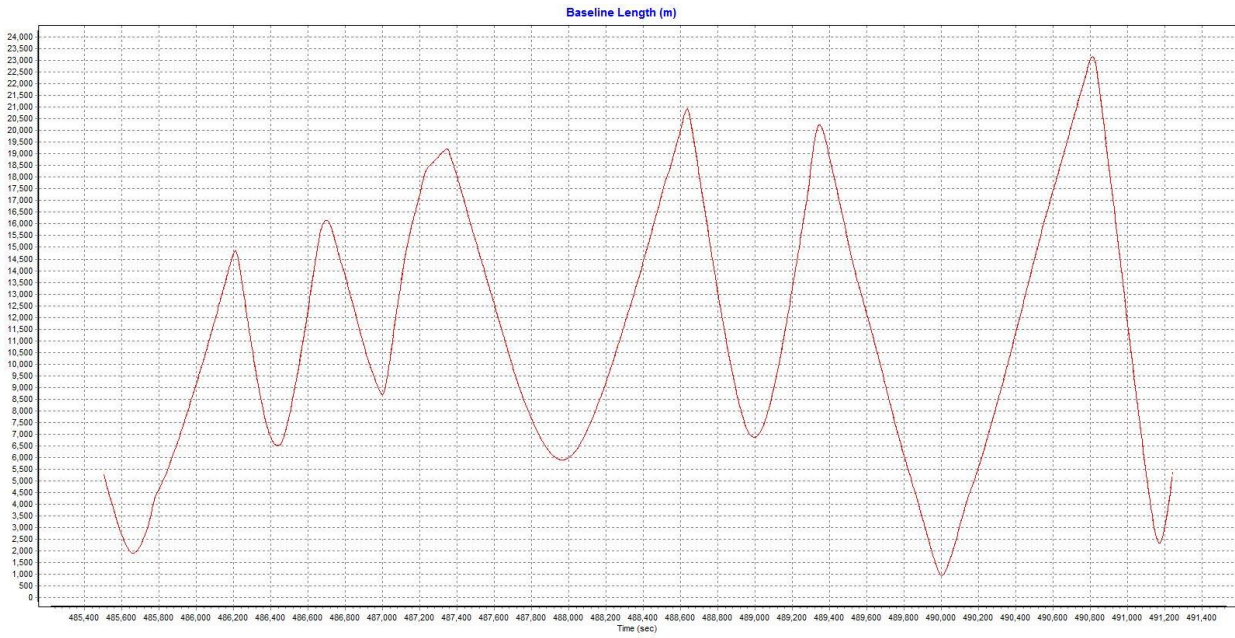
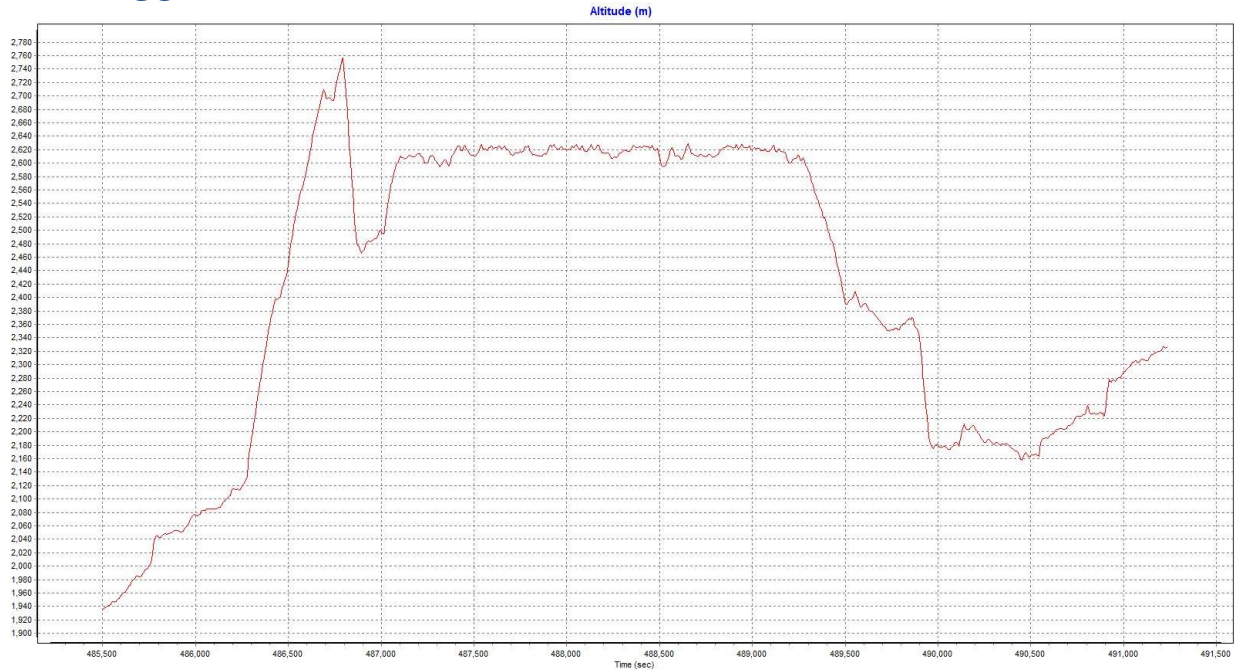
Forward  Reverse

0 = Fixed ILL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = CIA, 7 = GNSS Nav, 8 = DR



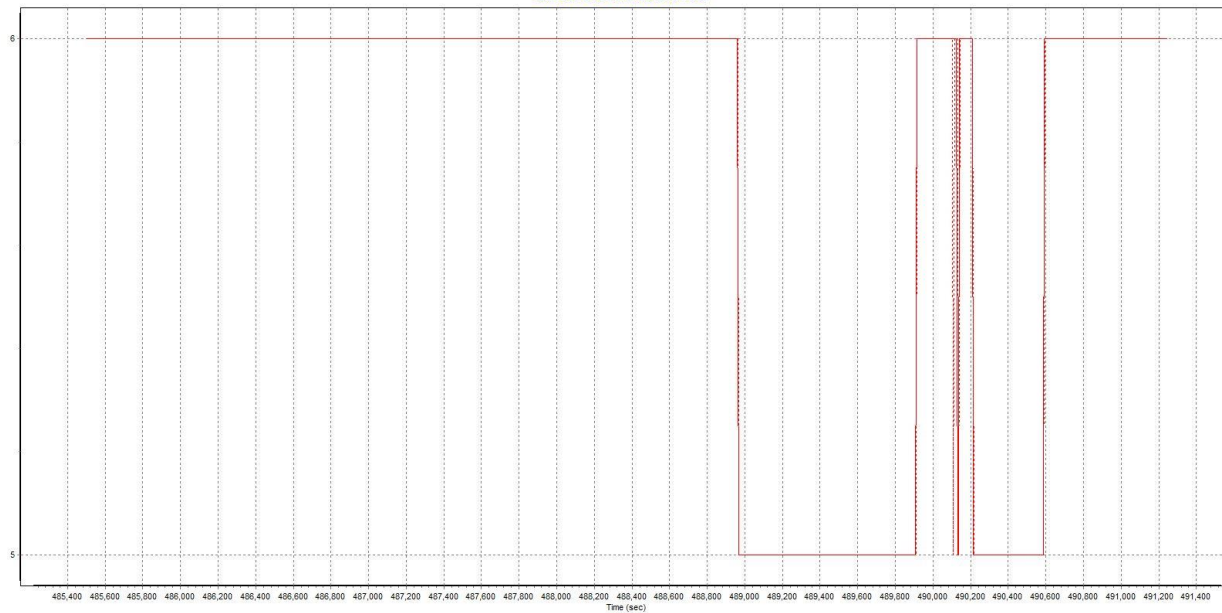


# UNB16351A



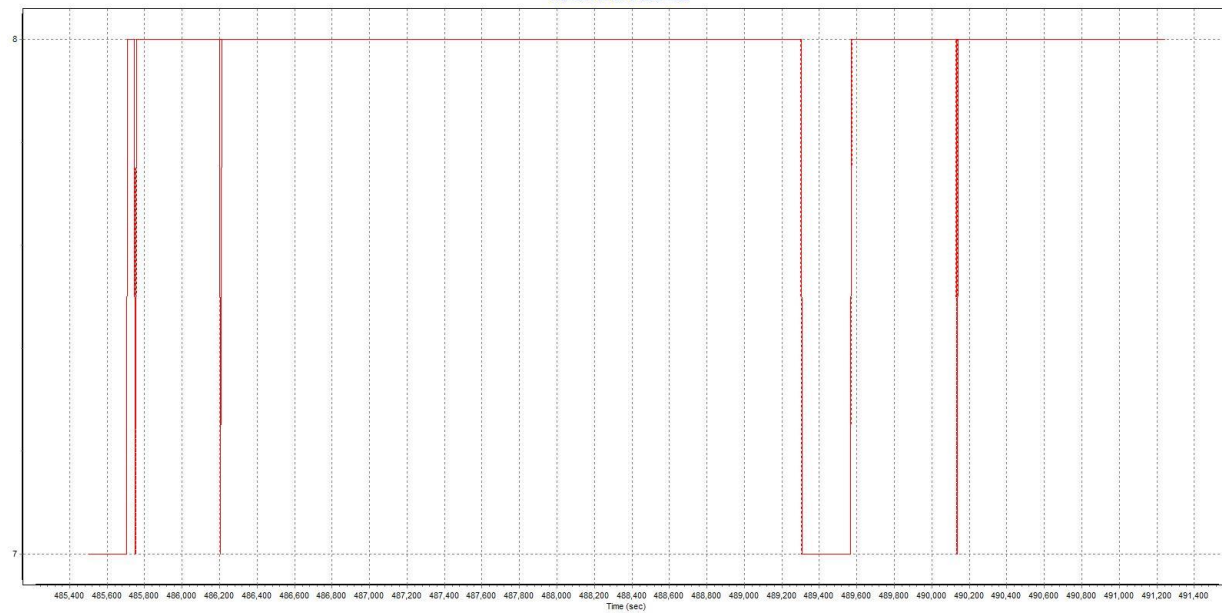
Forward  Reverse

Number of GLONASS Satellites



Forward  Reverse

Number of GPS Satellites



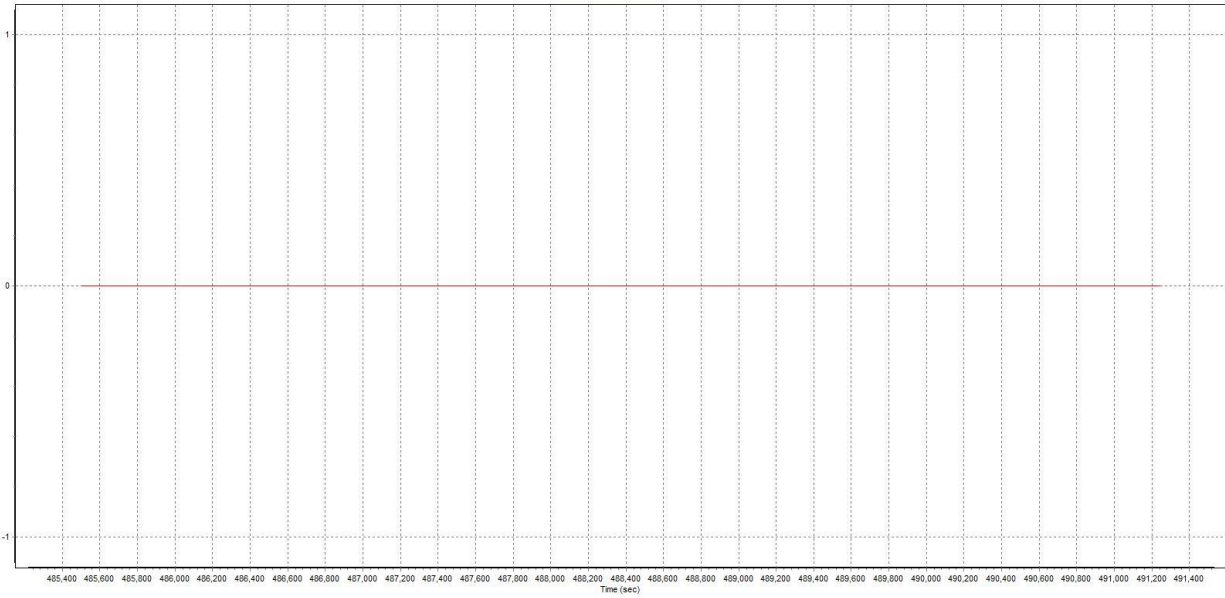
Forward  Reverse

PDOP



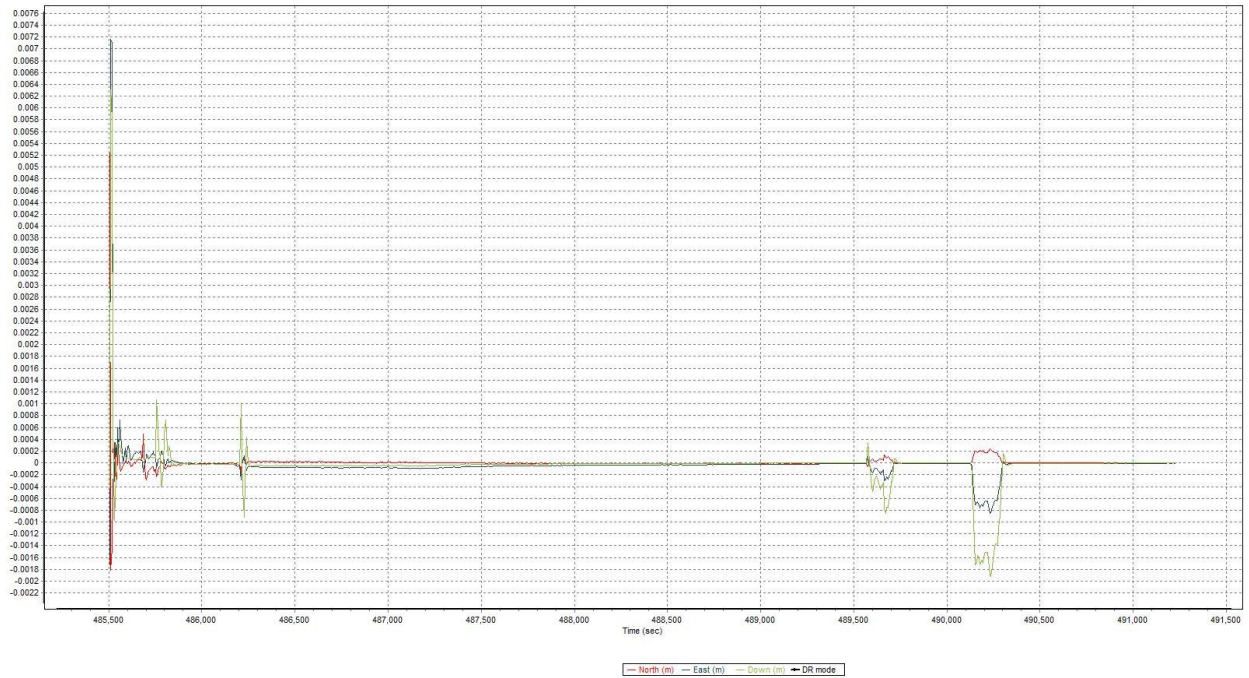
Forward  Reverse

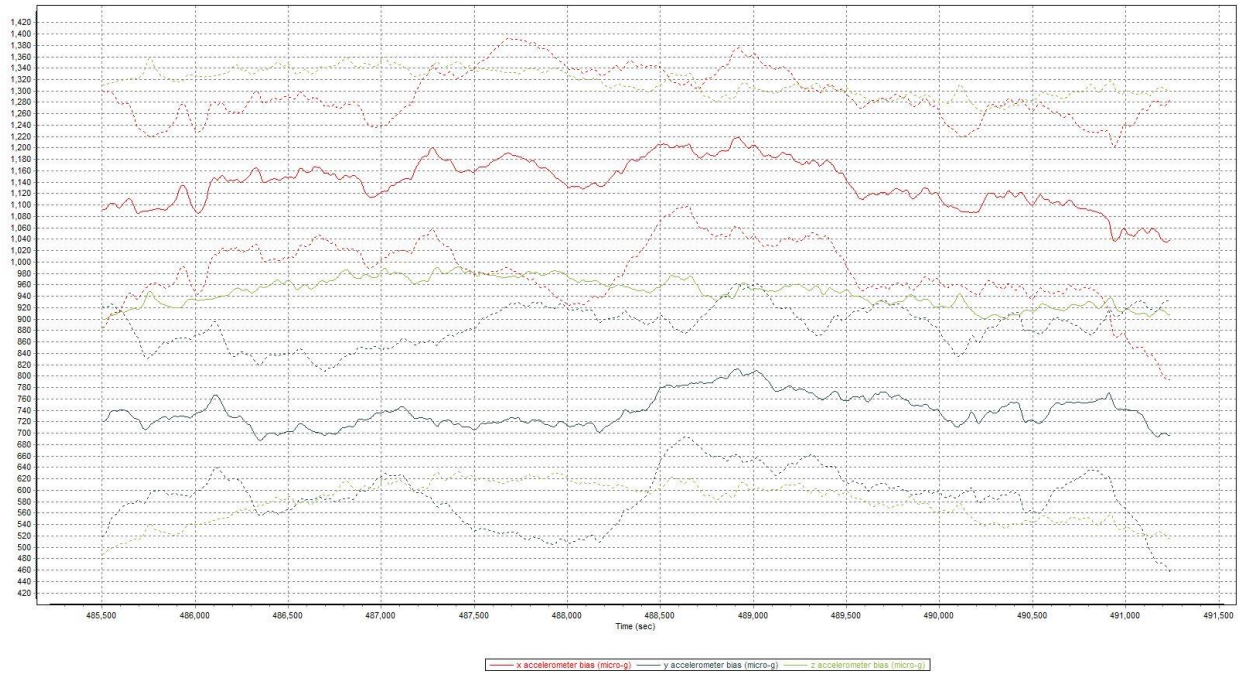
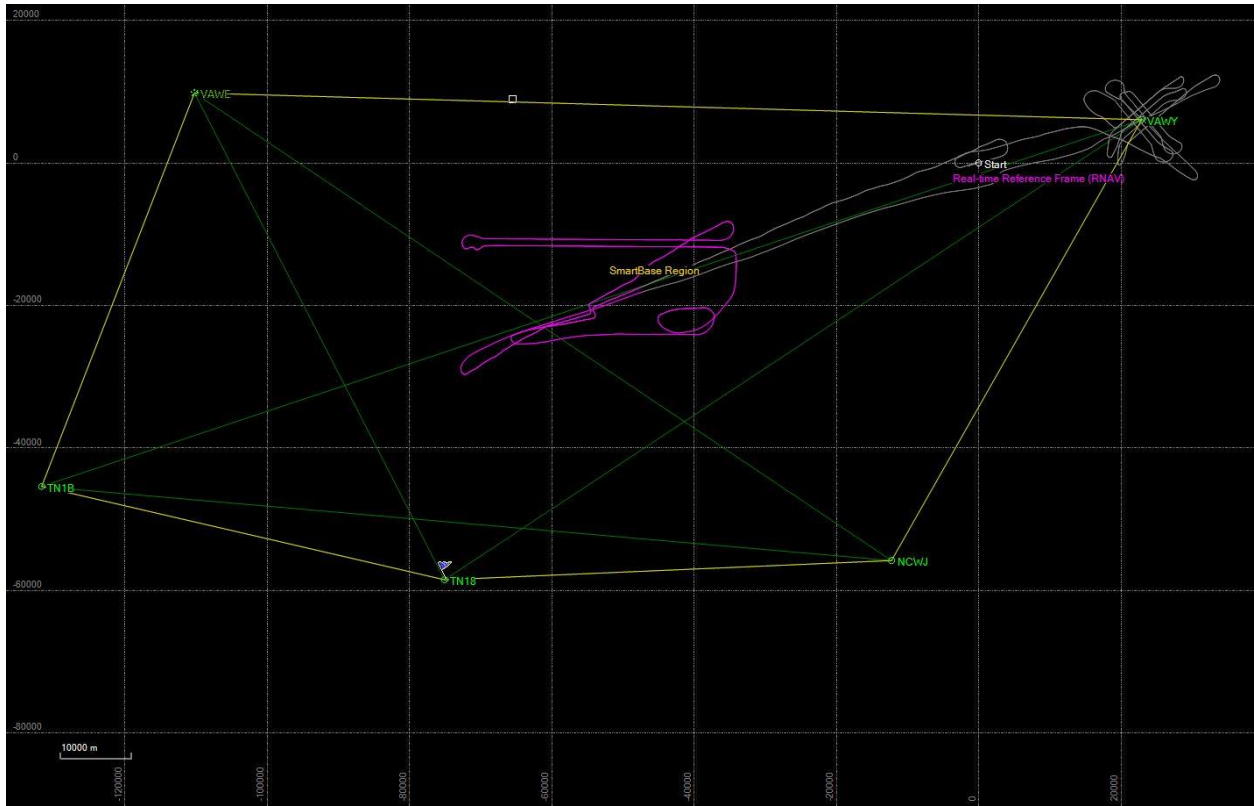
Processing mode

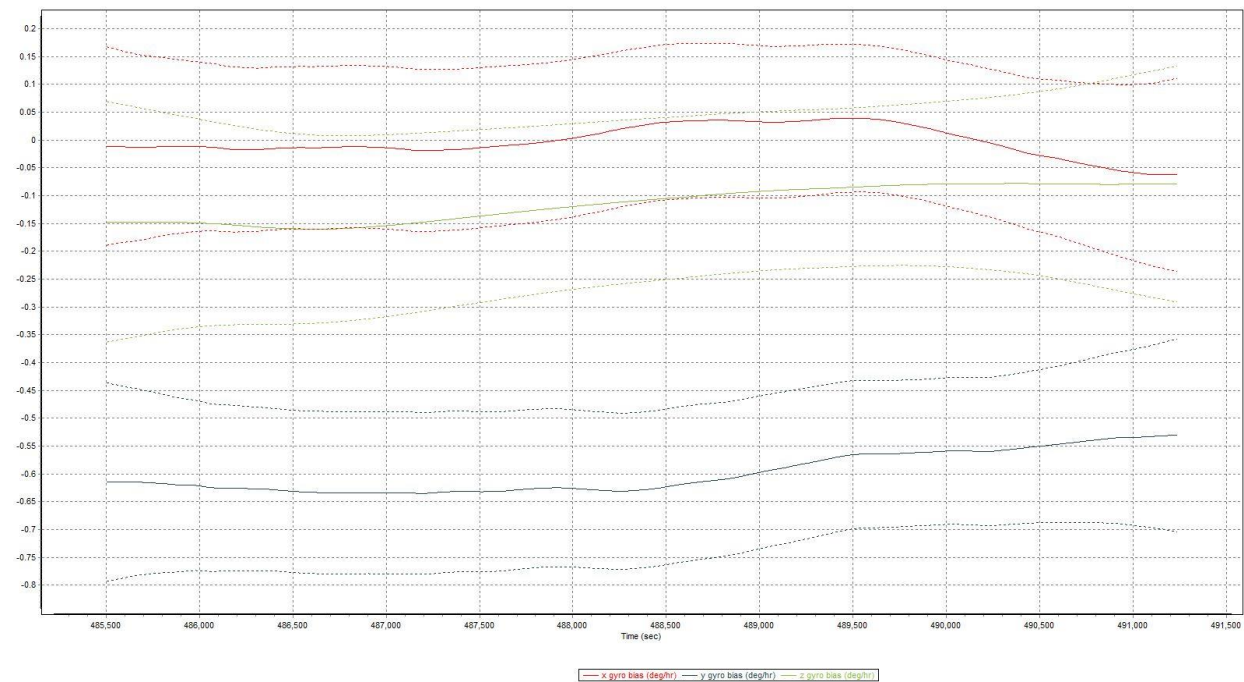
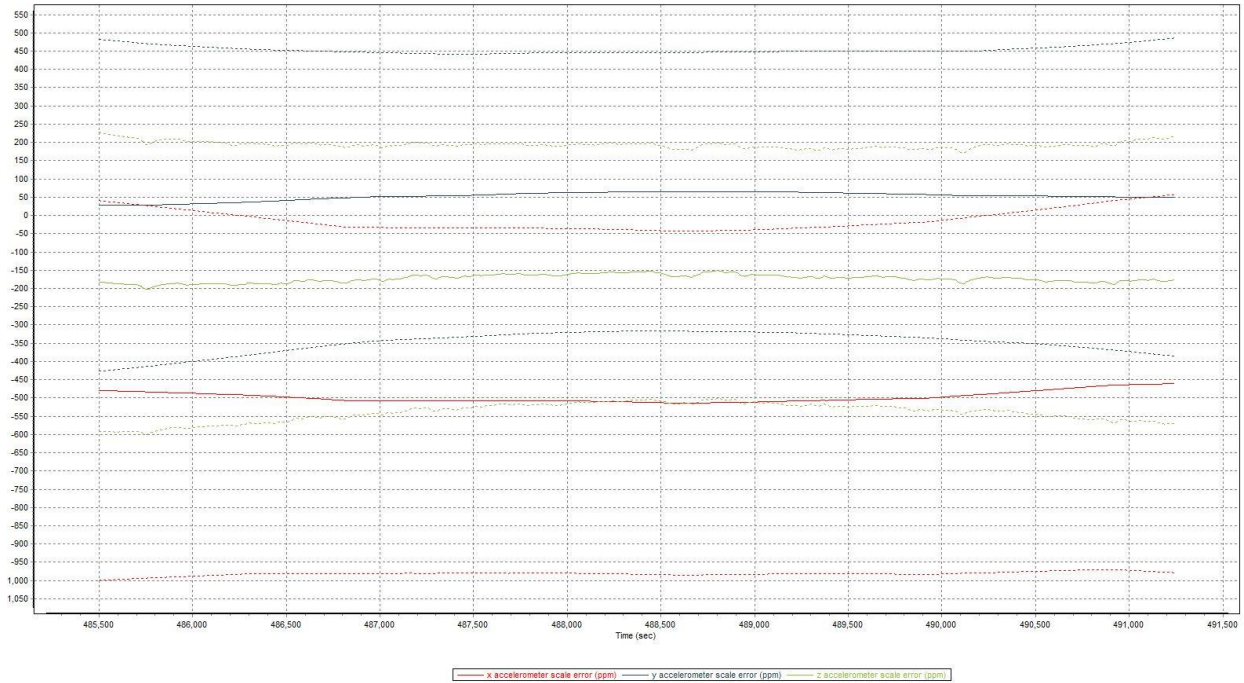


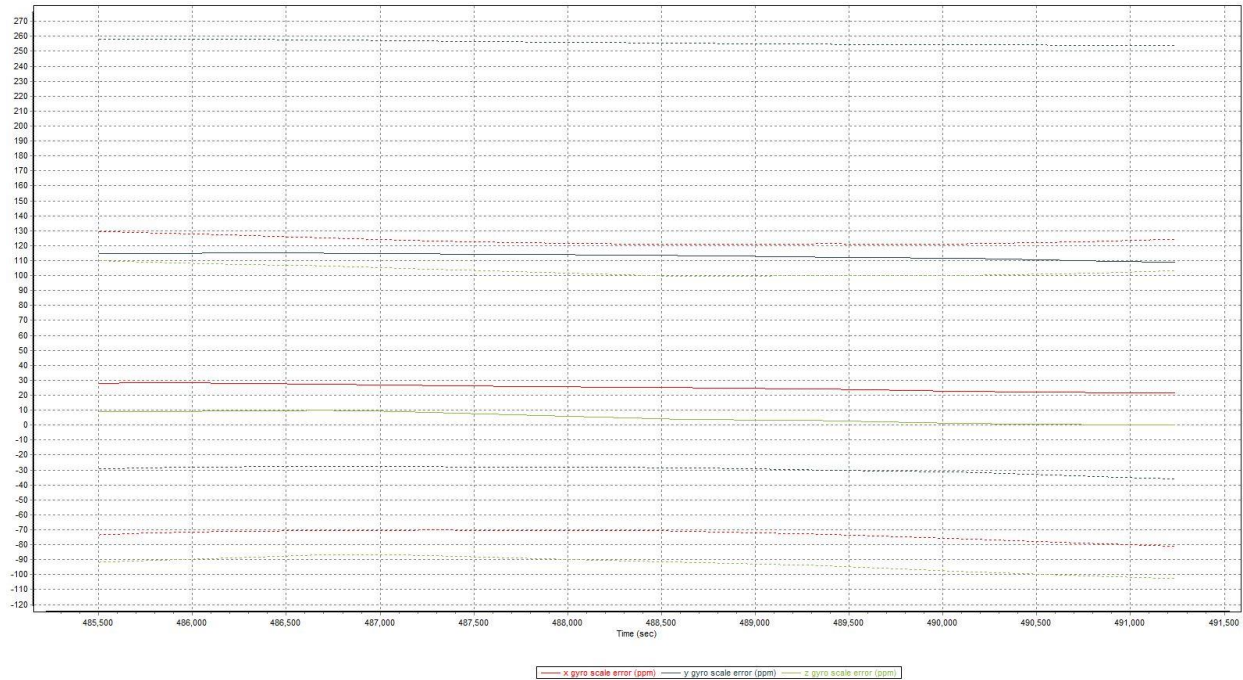
Forward  Reverse

0 = Fixed NL, 1 = Fixed VL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = CIA, 7 = GNSS Nav, 8 = DR



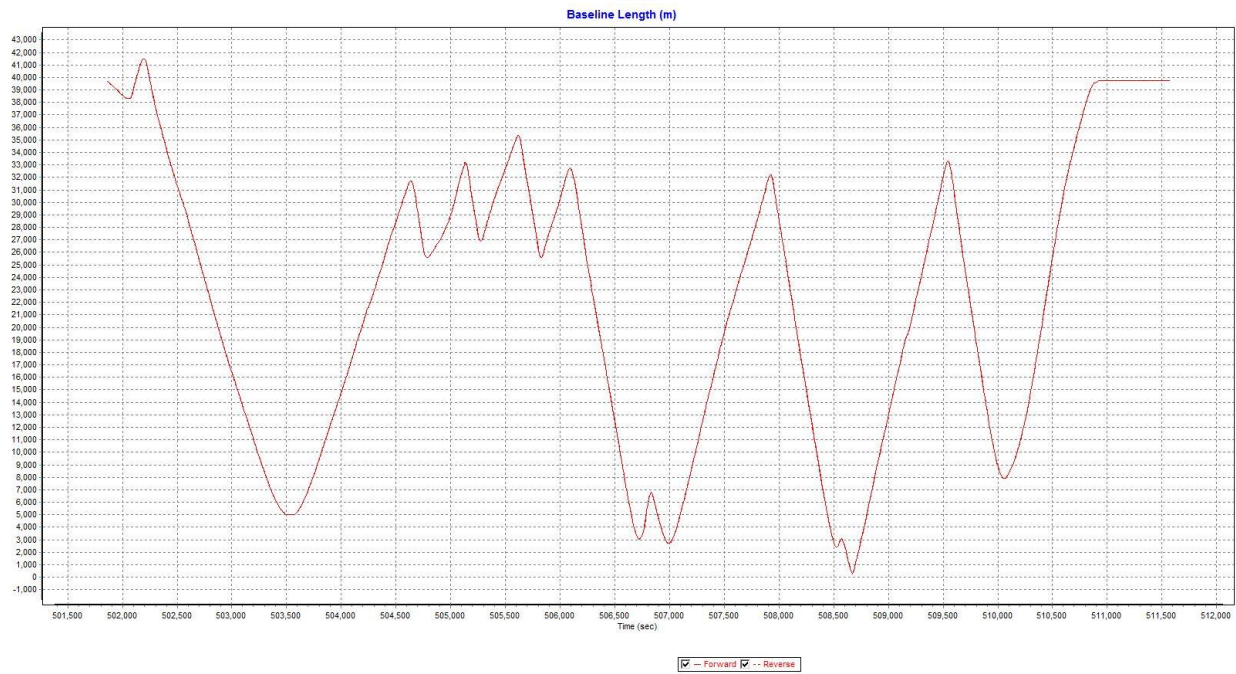
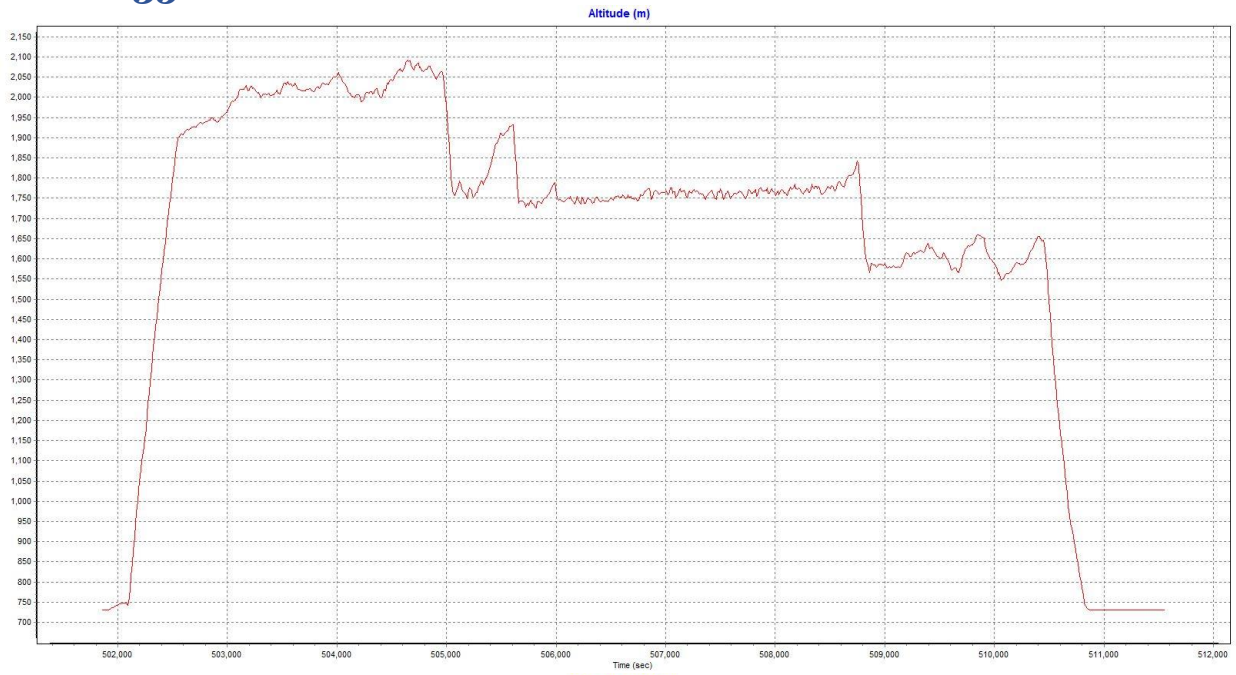




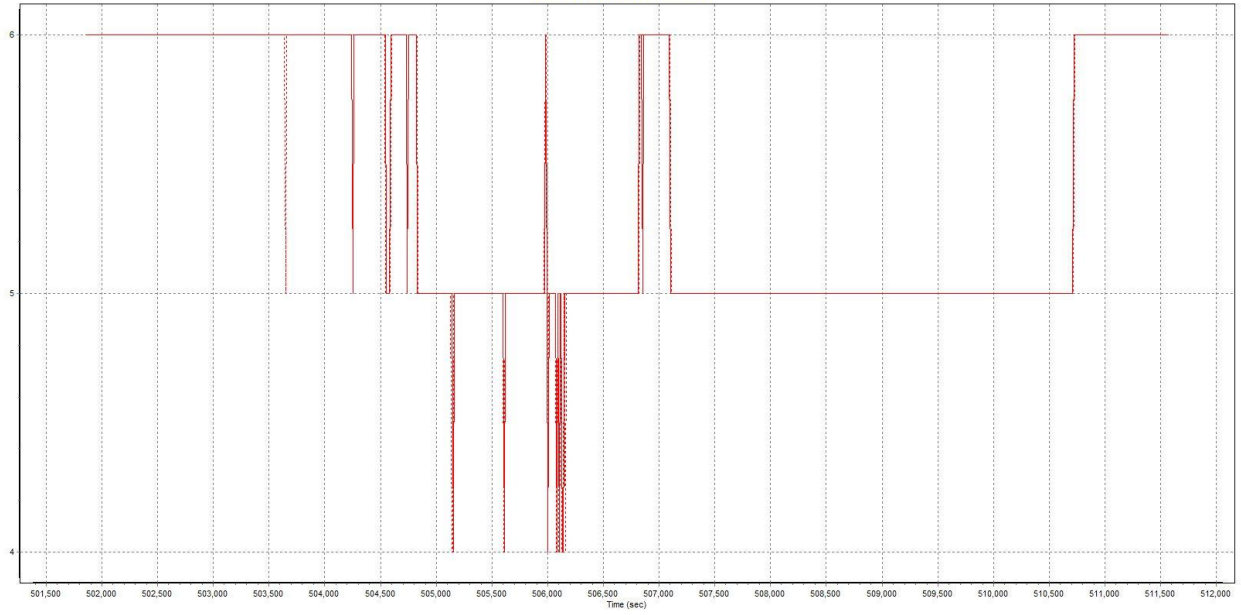




# UNB16351B

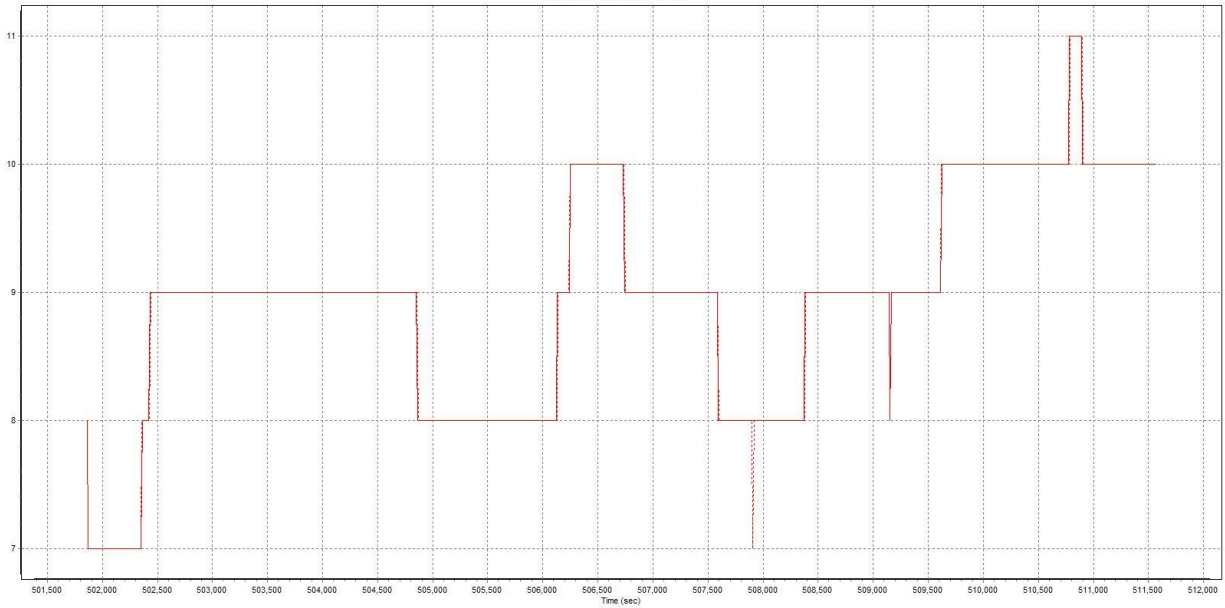


Number of GLONASS Satellites



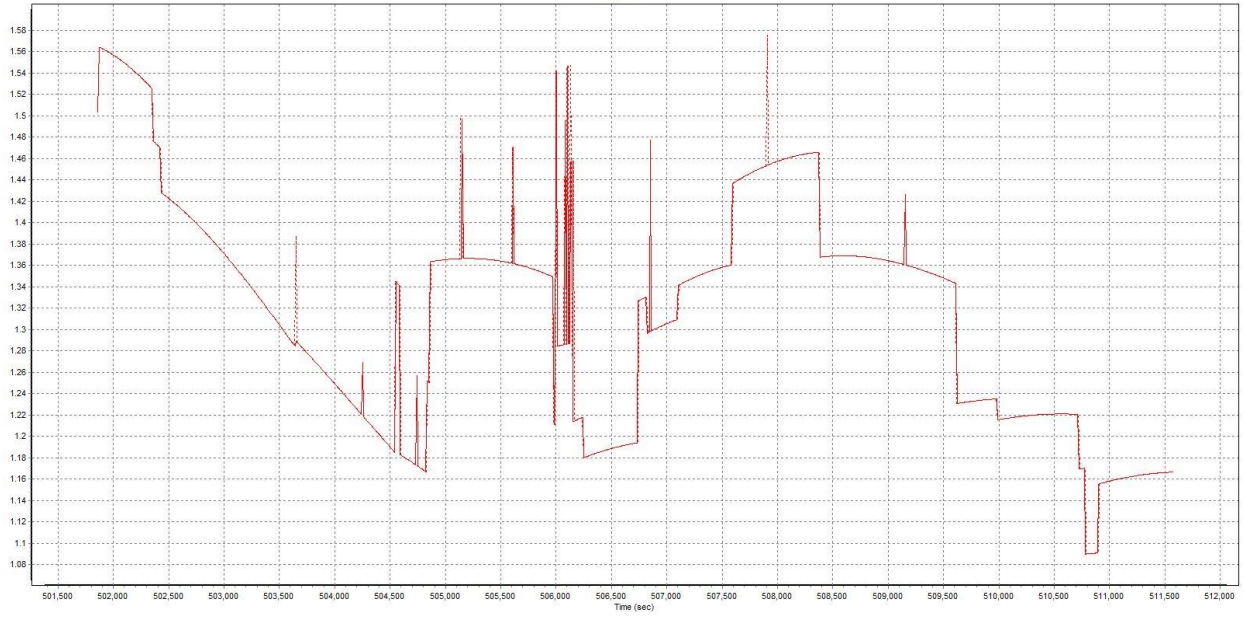
Forward  Reverse

Number of GPS Satellites



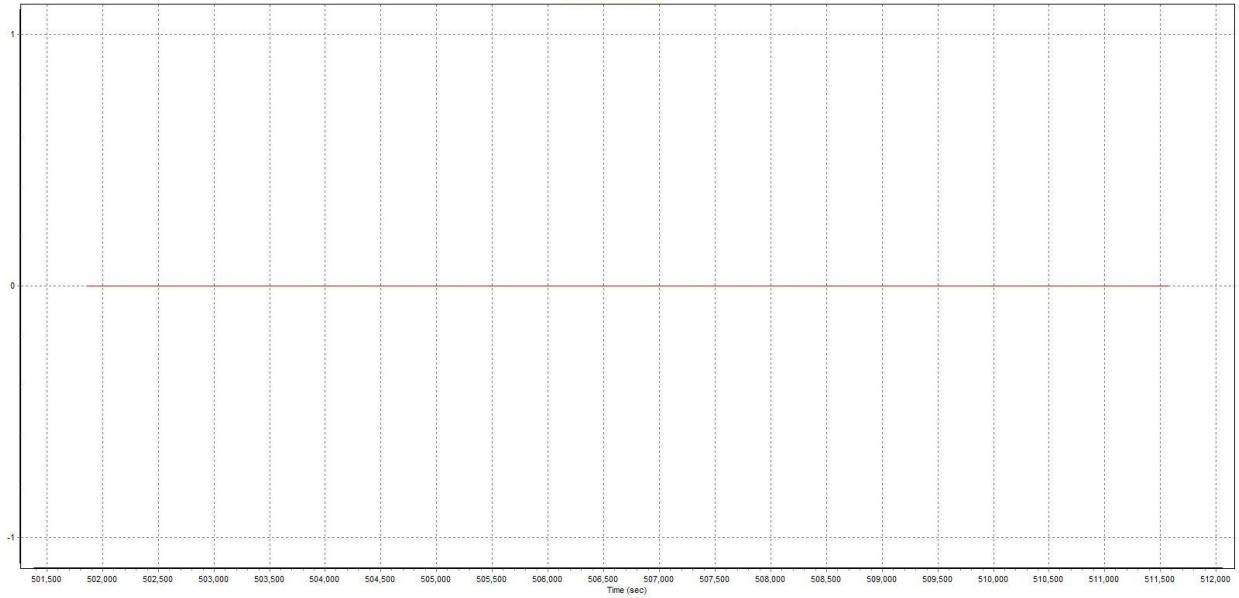
Forward  Reverse

PDOP



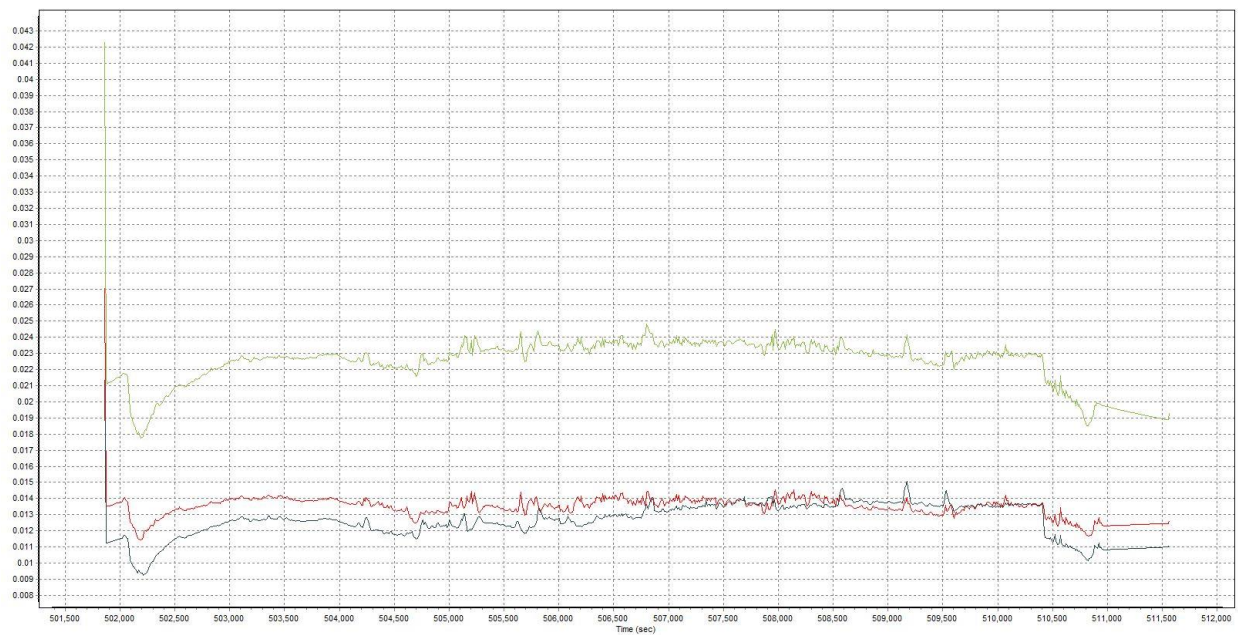
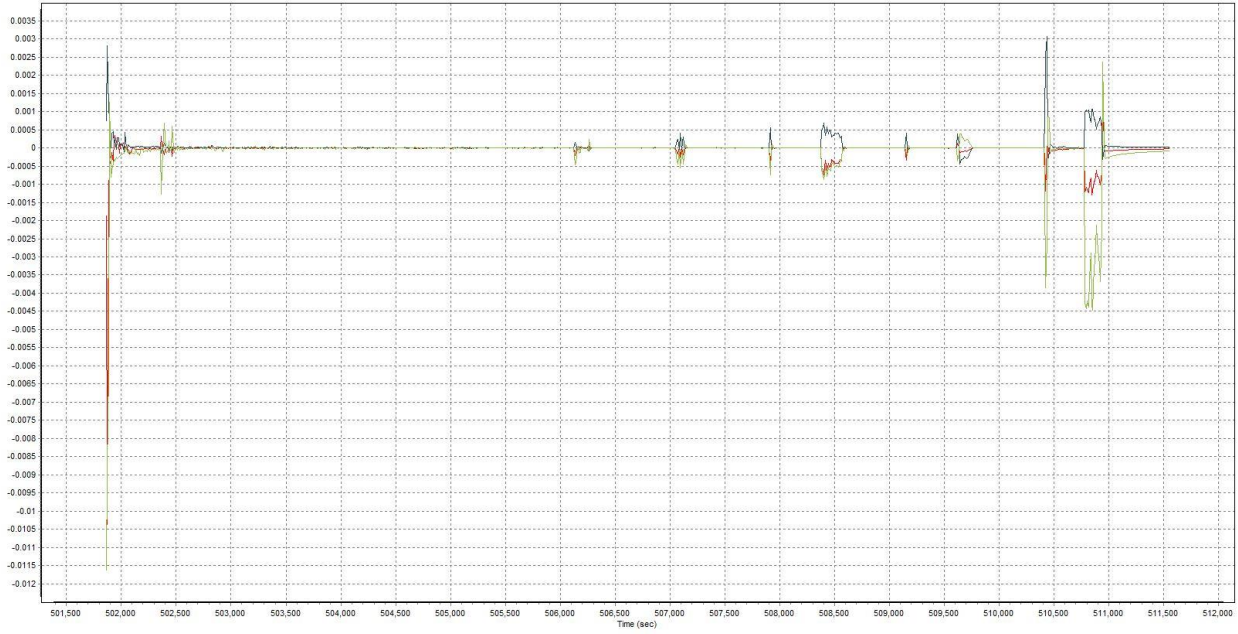
Forward  Reverse

Processing mode

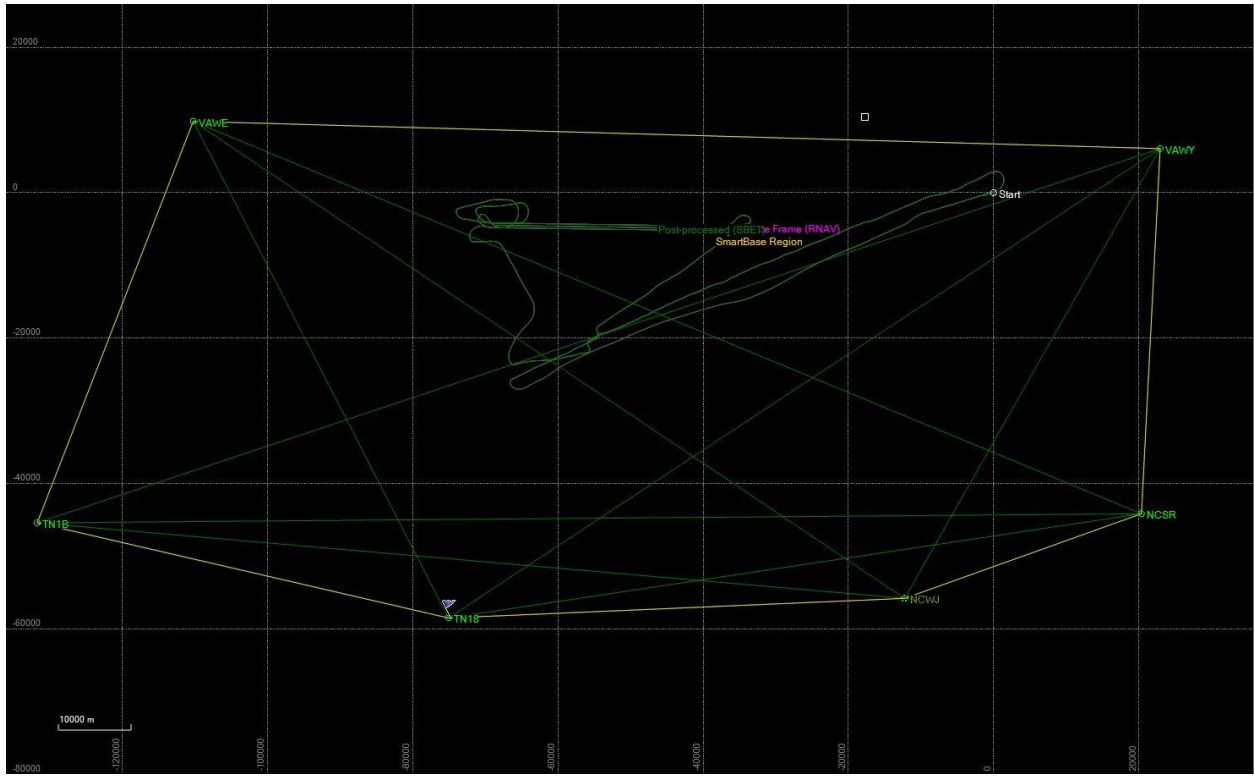


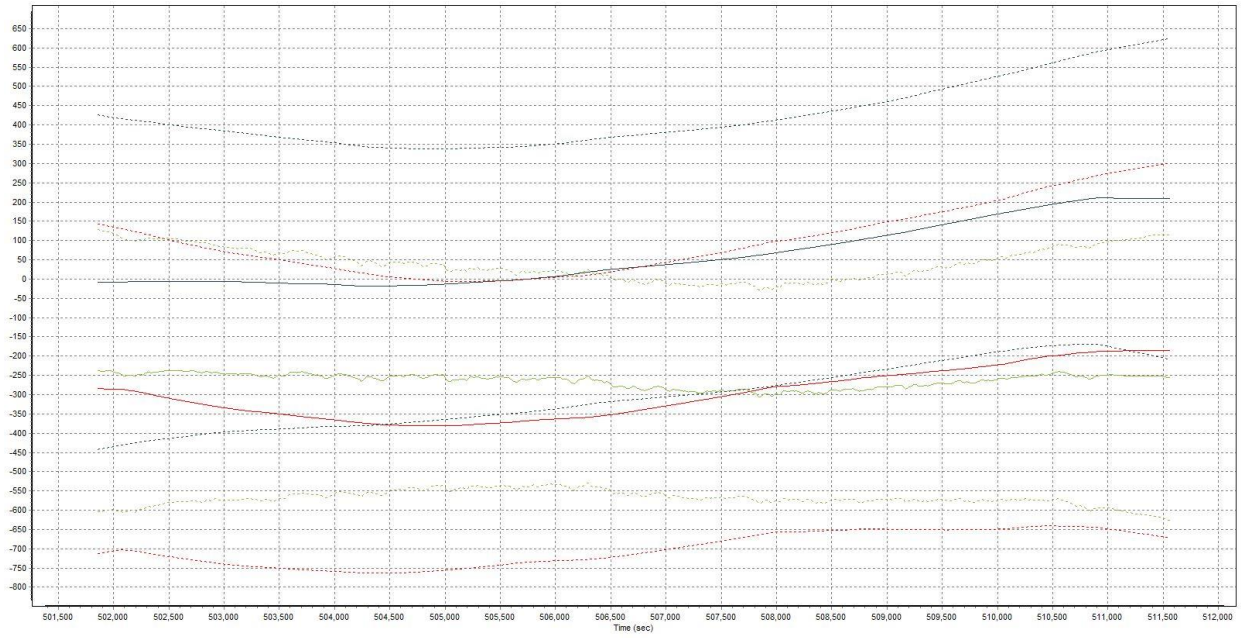
Forward  Reverse

0 = Fixed NL, 1 = Fixed VL, 2 = Float, 3 = DGSS, 4 = RTCM, 5 = IAPPP, 6 = CIA, 7 = GNSS Nav, 8 = DR

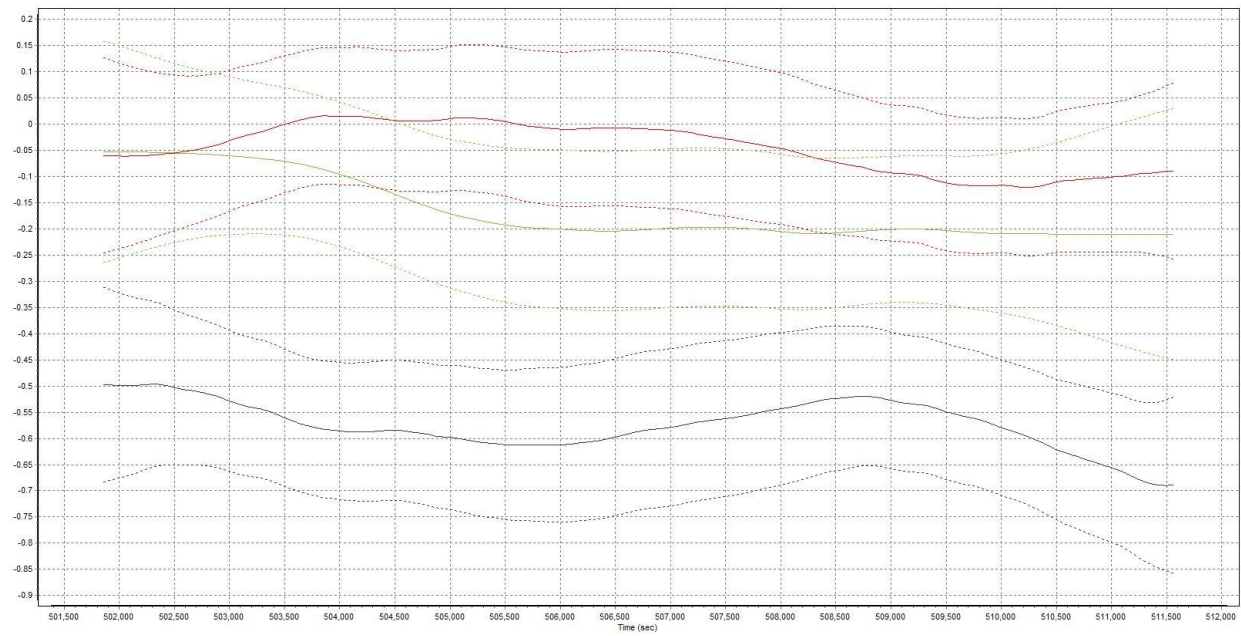


— North Position Error RMS (m) — East Position Error RMS (m) — Down Position Error RMS (m)

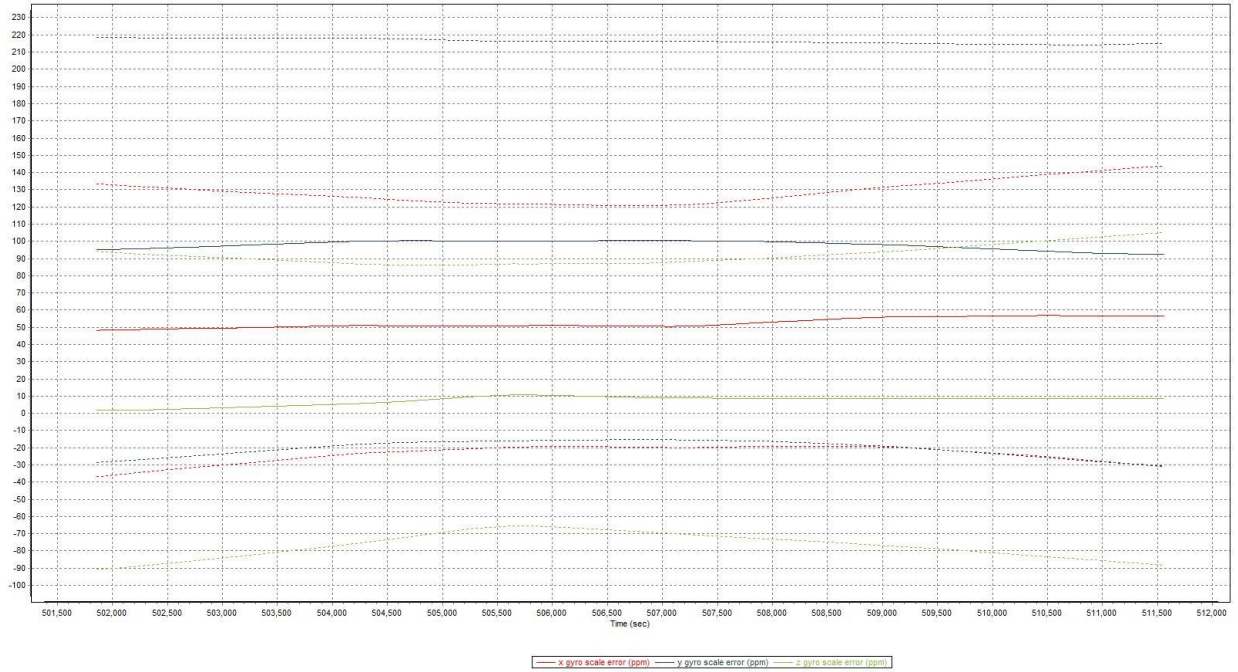




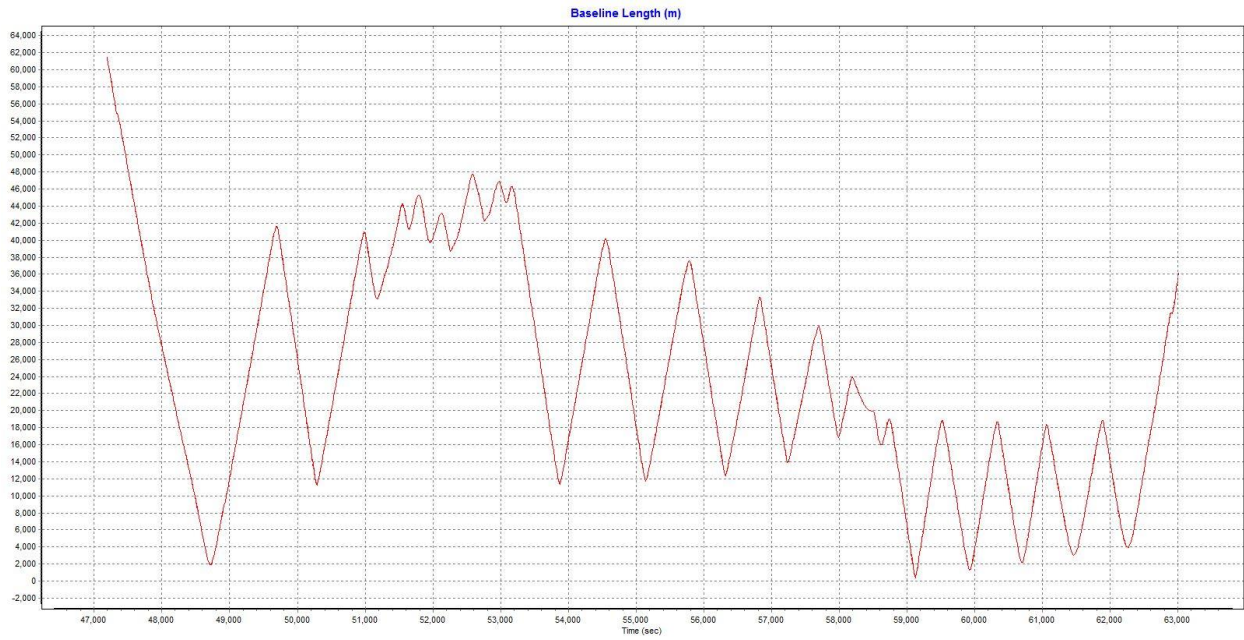
— x accelerometer scale error (ppm) — y accelerometer scale error (ppm) — z accelerometer scale error (ppm)



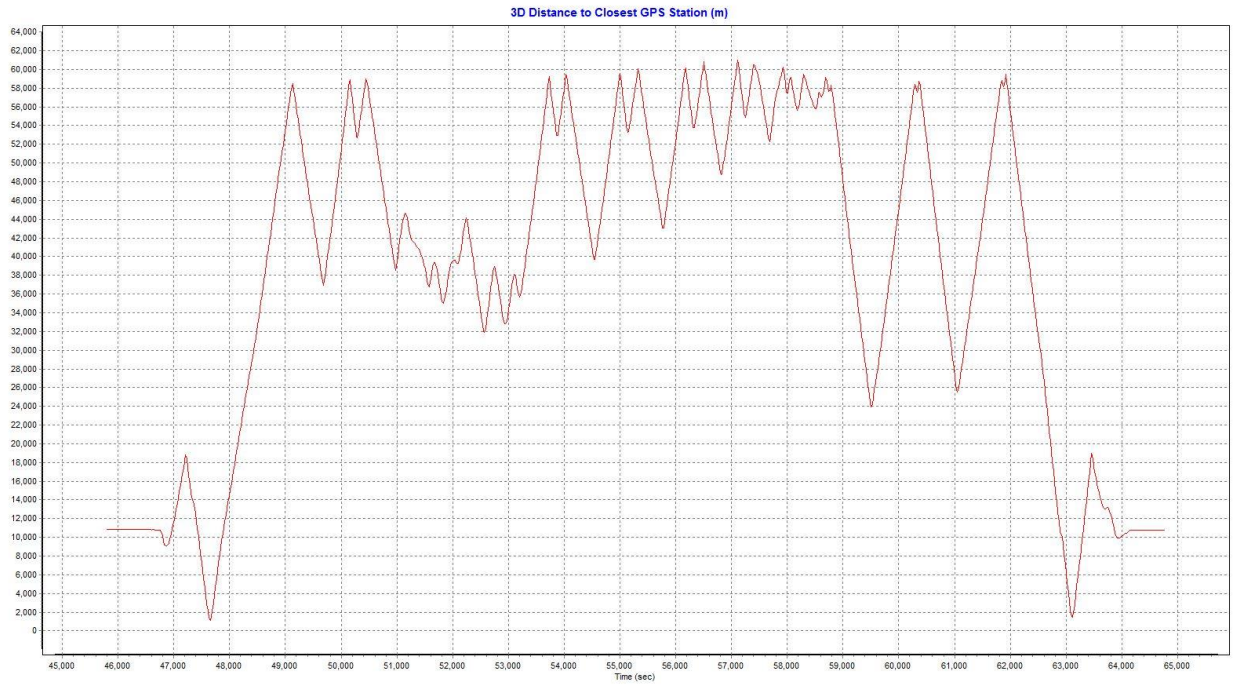
— x gyro bias (deg/hr) — y gyro bias (deg/hr) — z gyro bias (deg/hr)



# UNB17092A

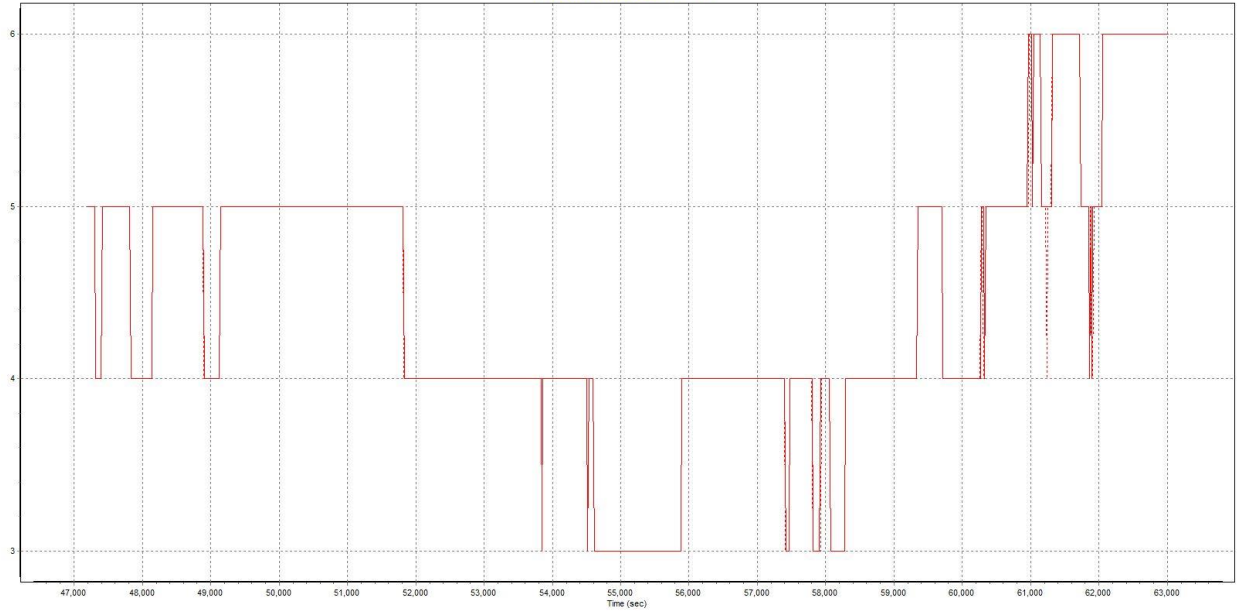


Forward  Reverse



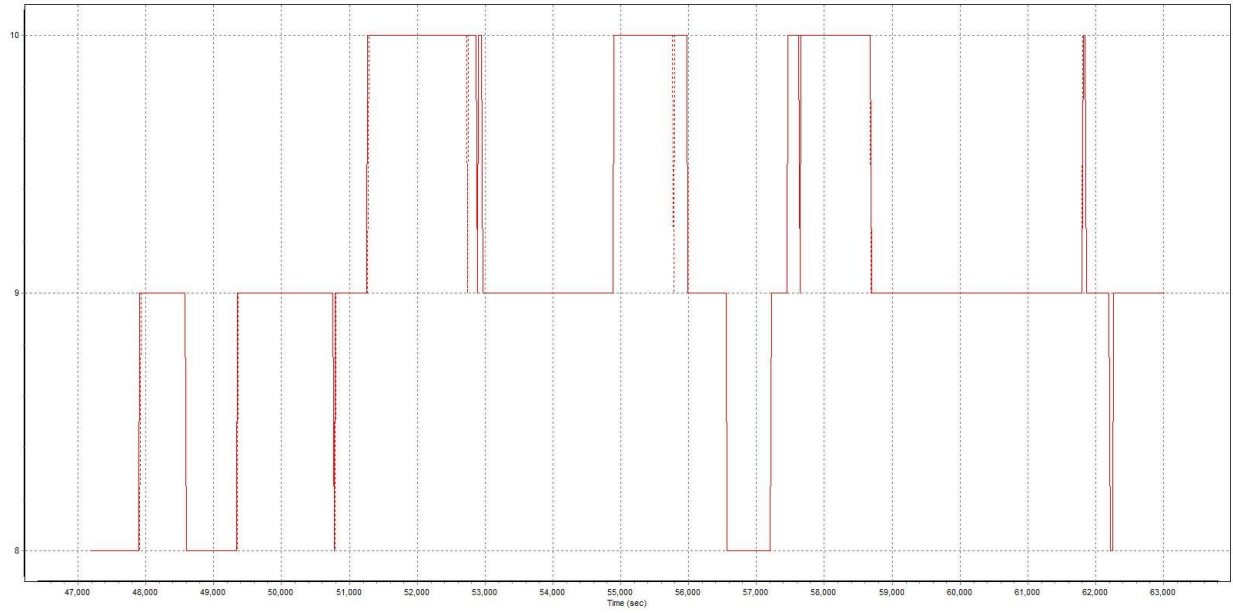


Number of GLONASS Satellites



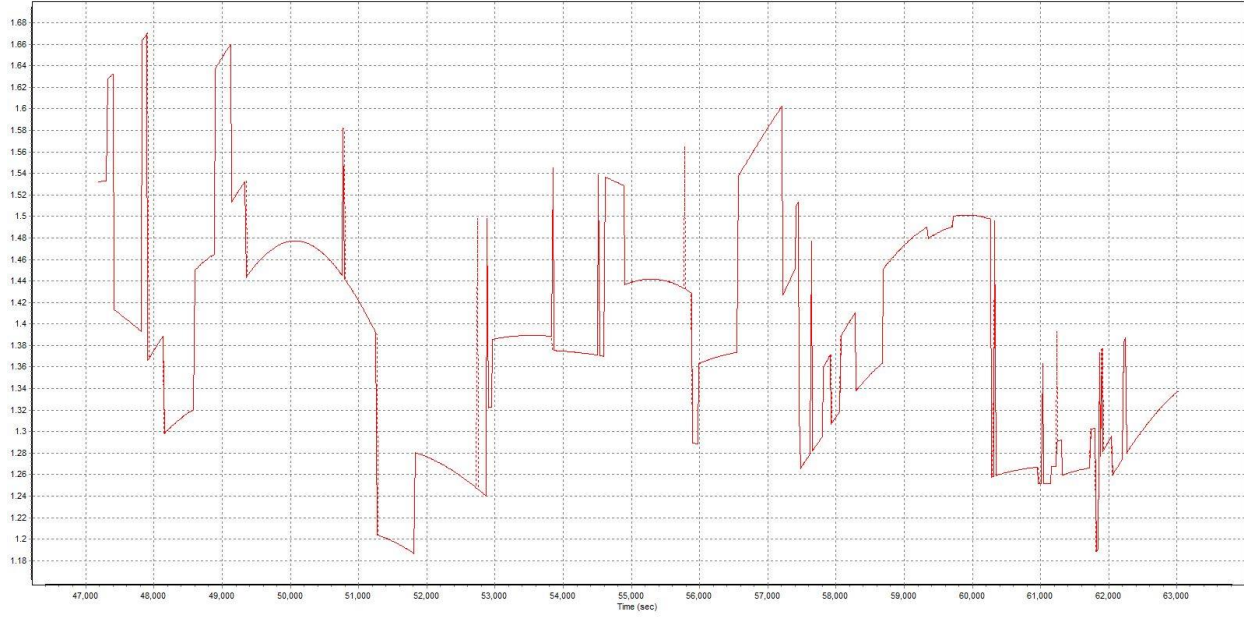
Forward  Reverse

Number of GPS Satellites



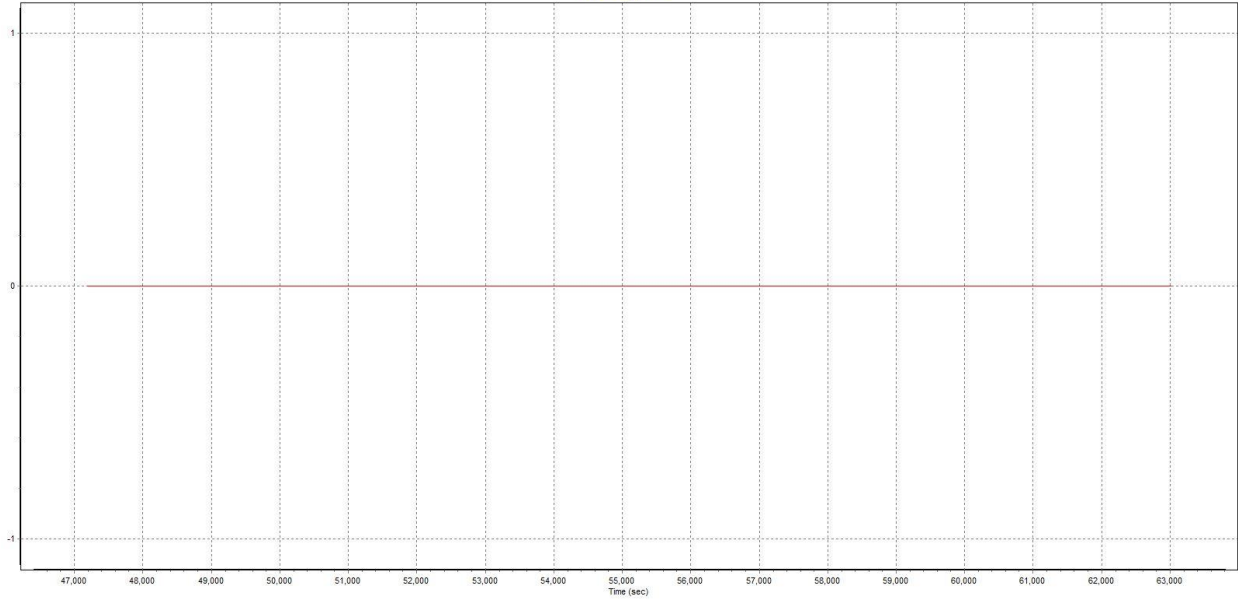
Forward  Reverse

PDOP



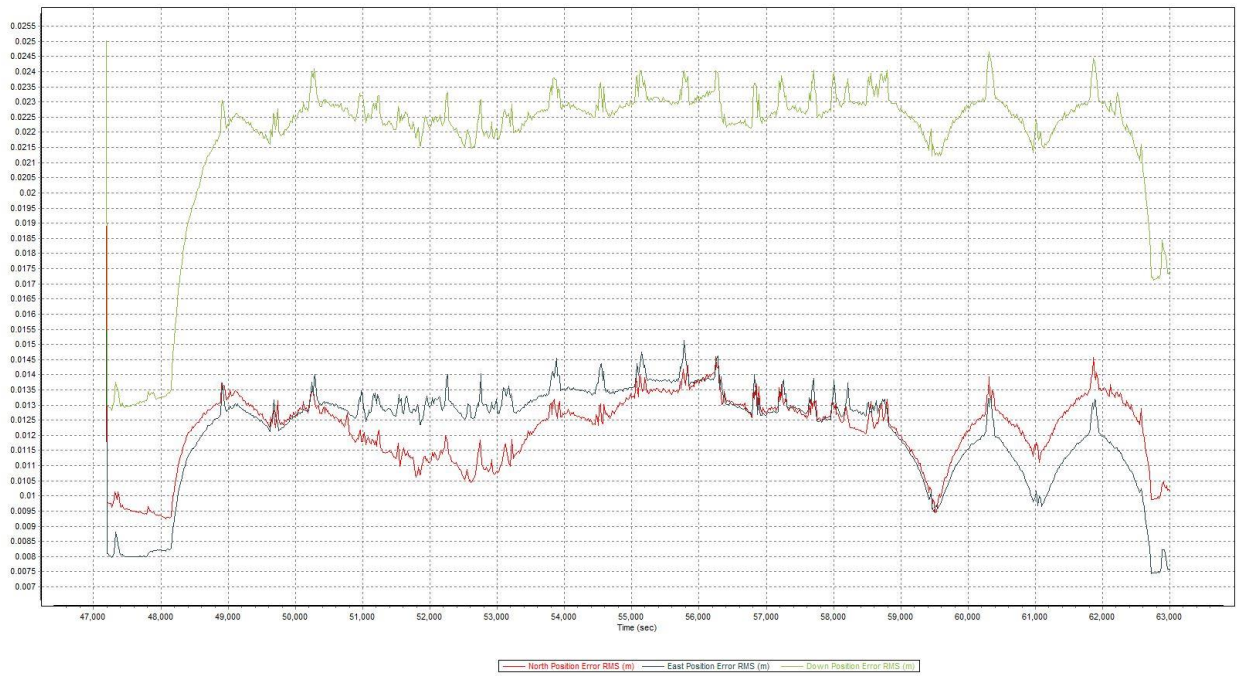
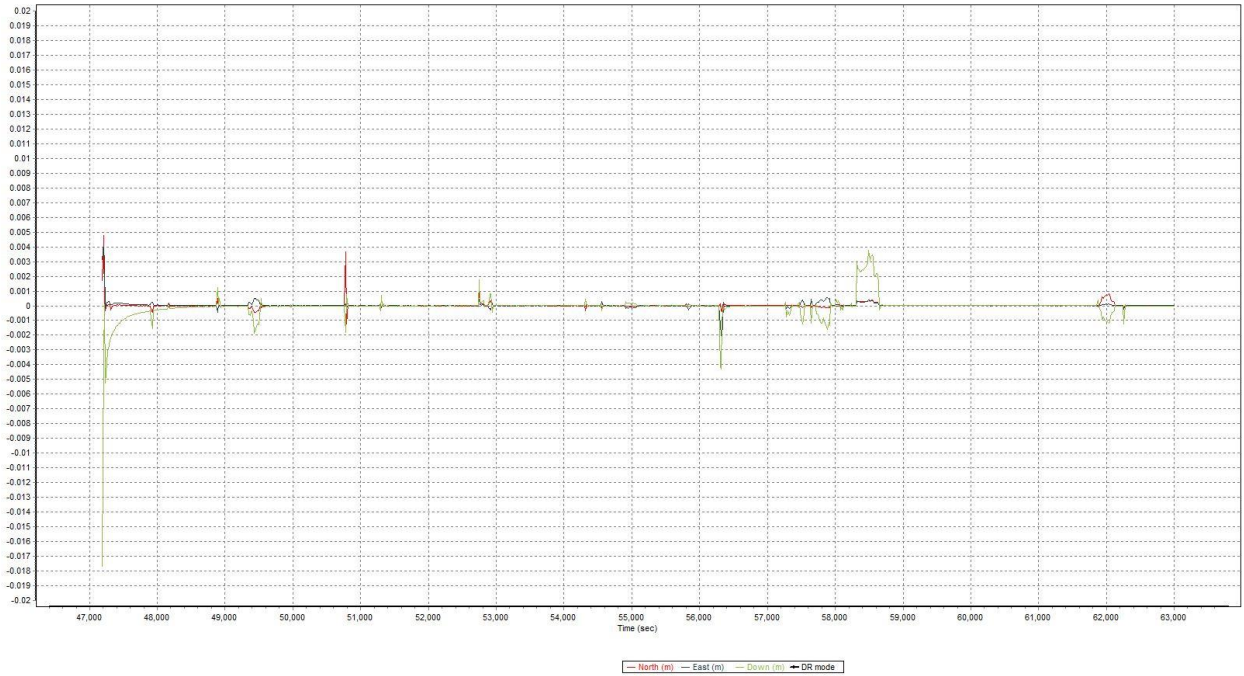
Forward  Reverse

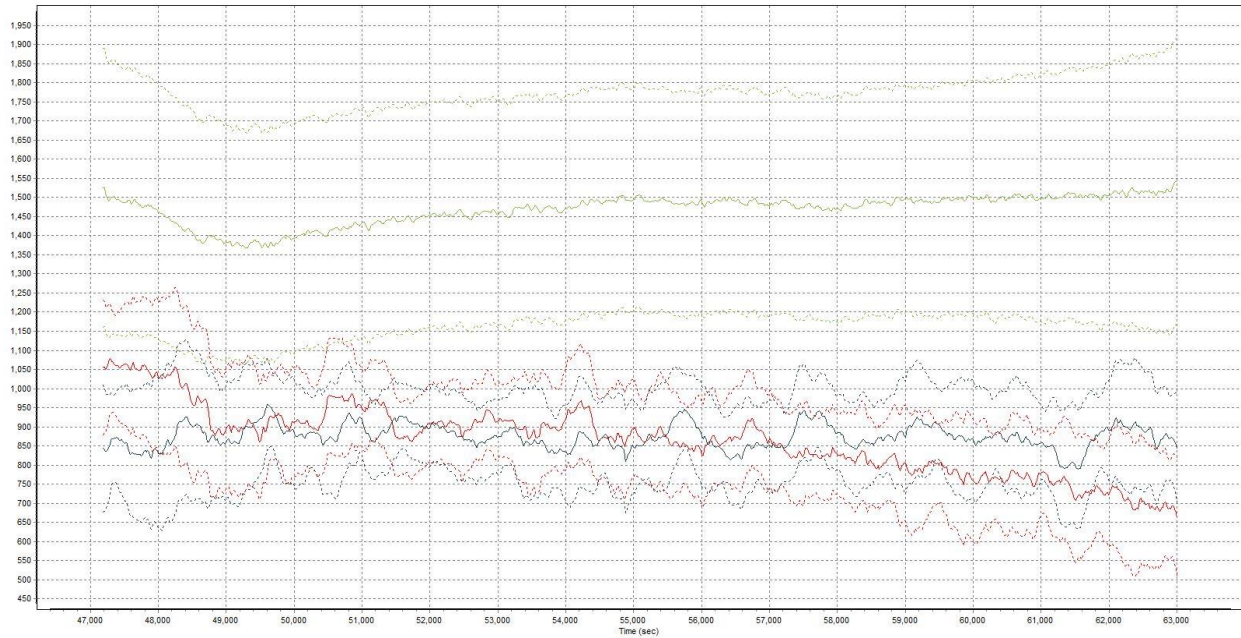
Processing mode



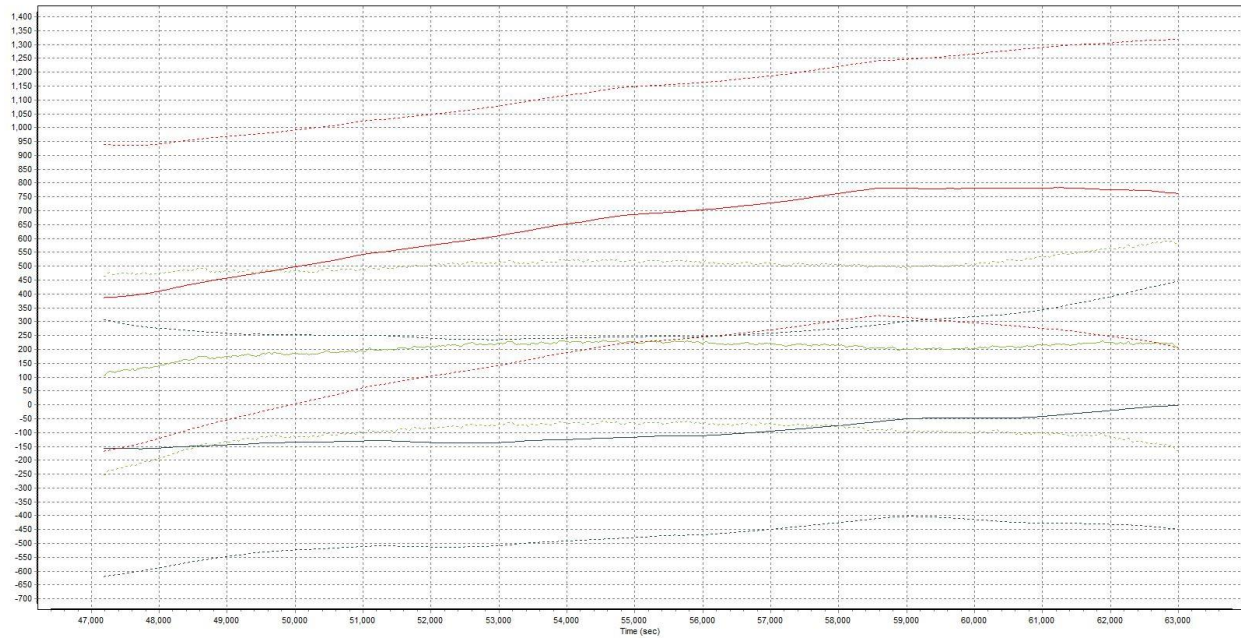
Forward  Reverse

0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = CIA, 7 = GNSS Nav, 8 = DR



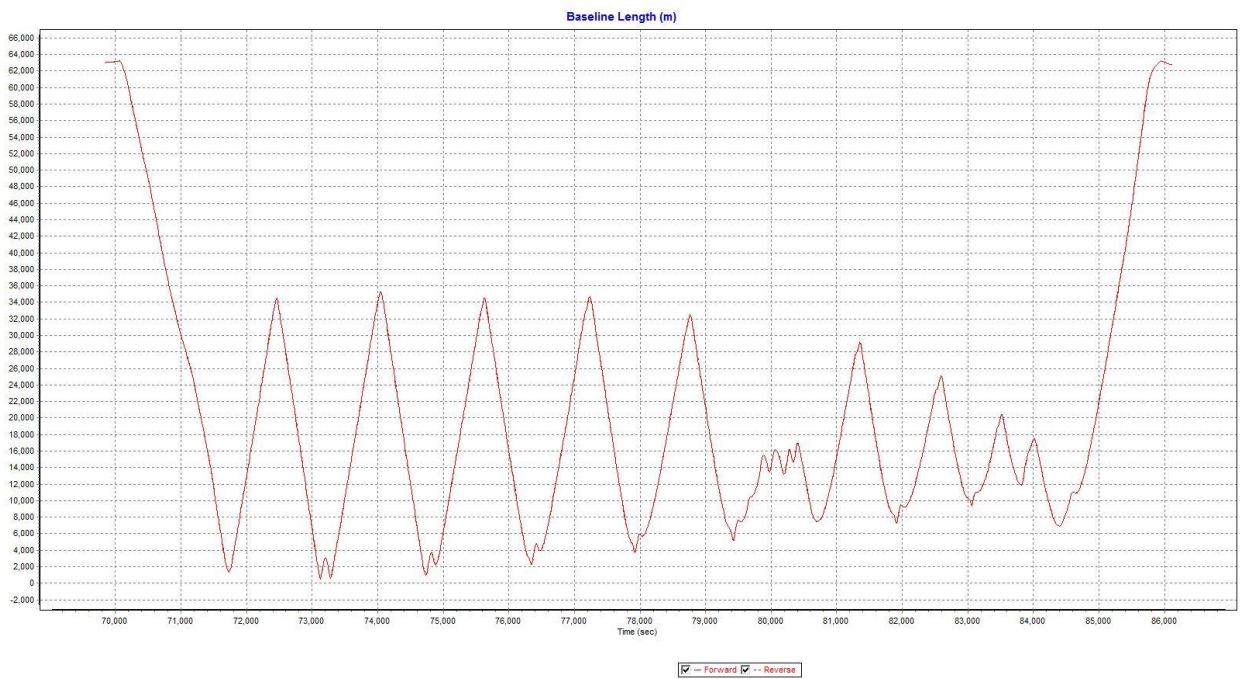
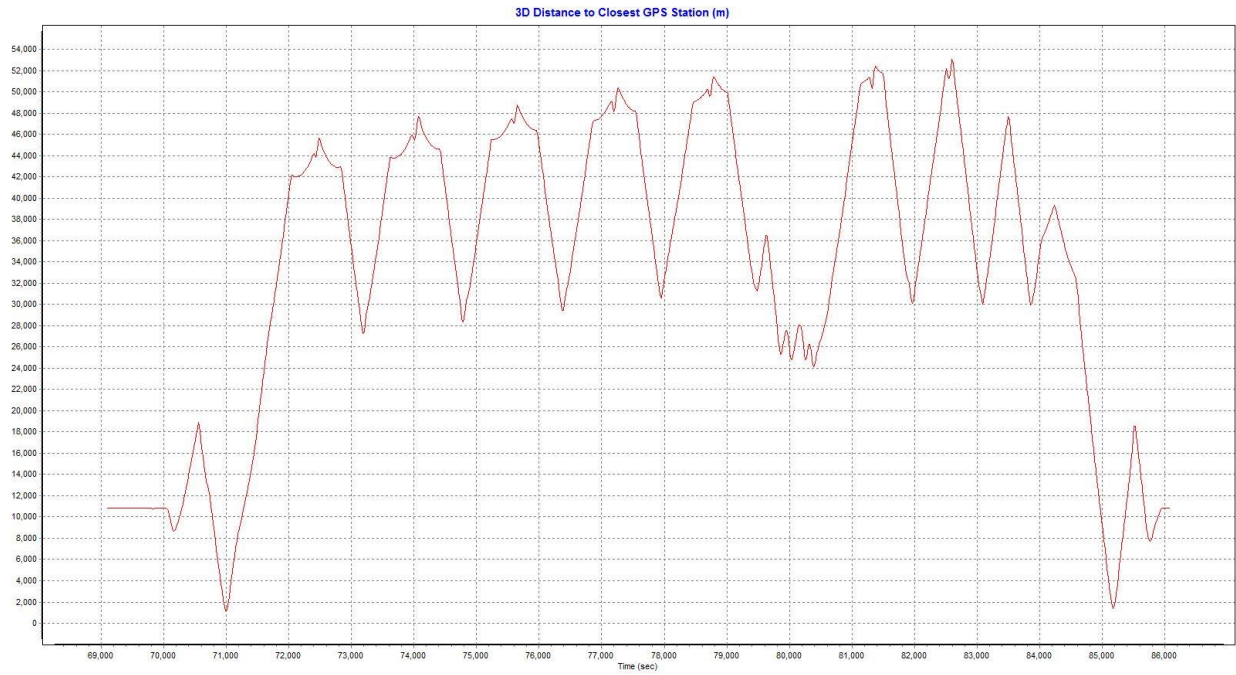


x accelerometer bias (micro-g) y accelerometer bias (micro-g) z accelerometer bias (micro-g)

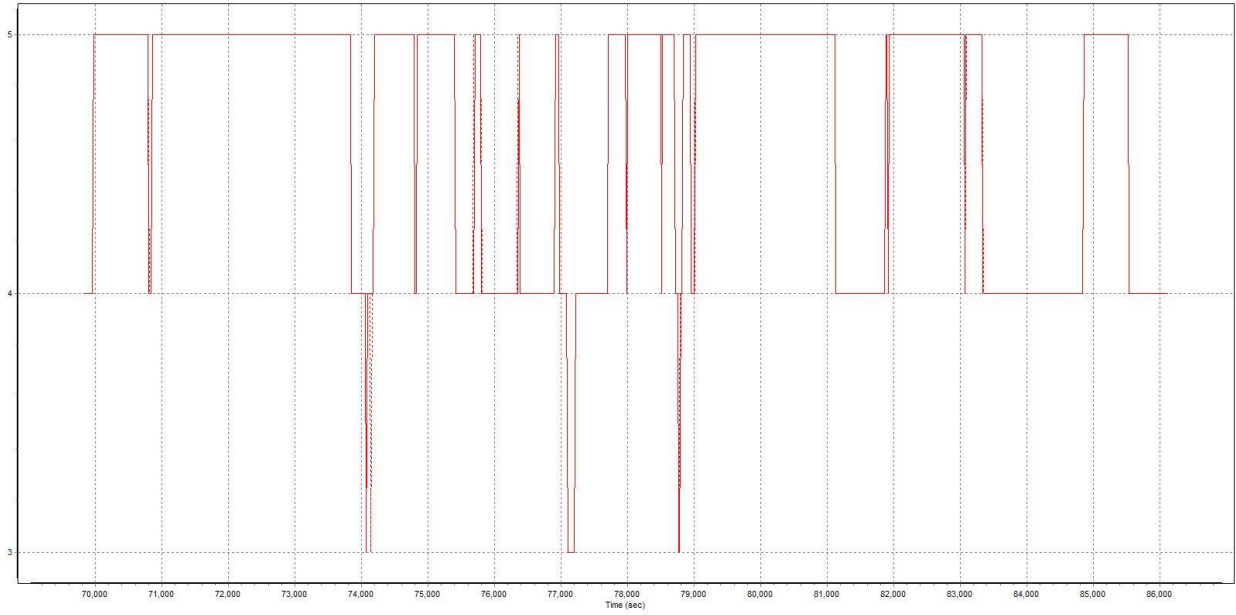


x accelerometer scale error (ppm) y accelerometer scale error (ppm) z accelerometer scale error (ppm)

# UNB17092B

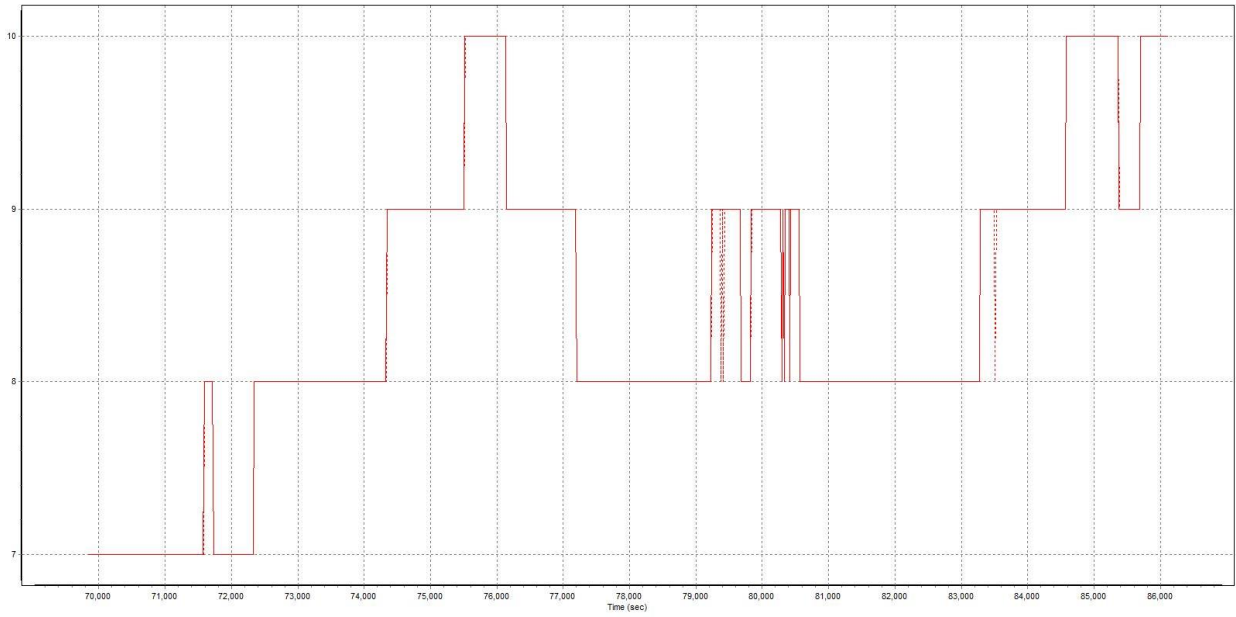


Number of GLONASS Satellites



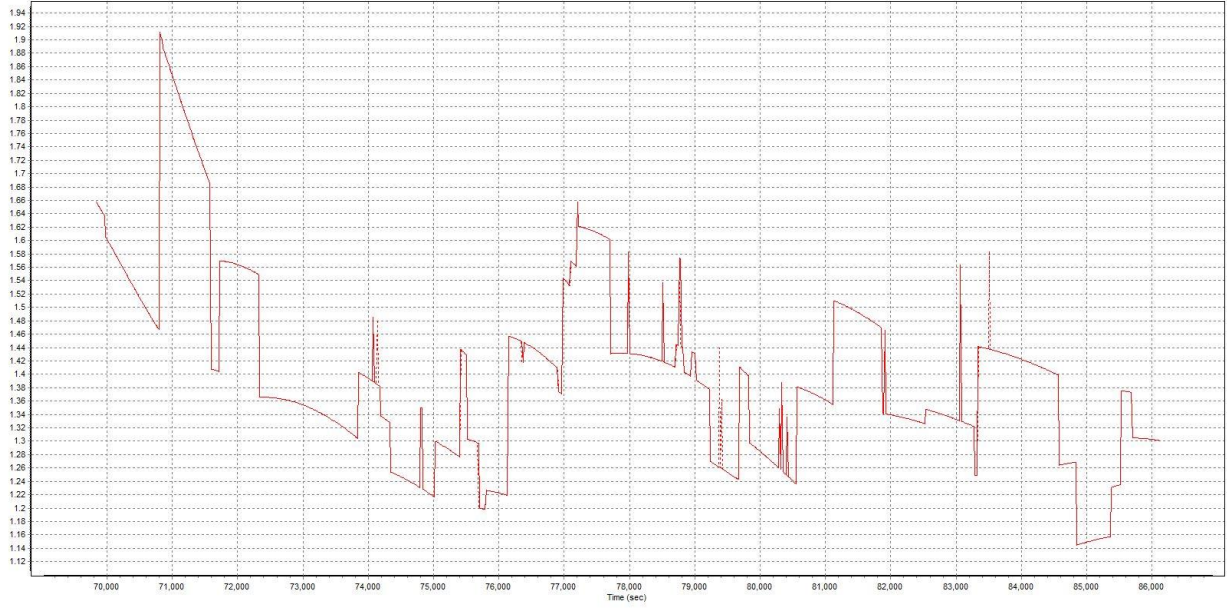
Forward  Reverse

Number of GPS Satellites



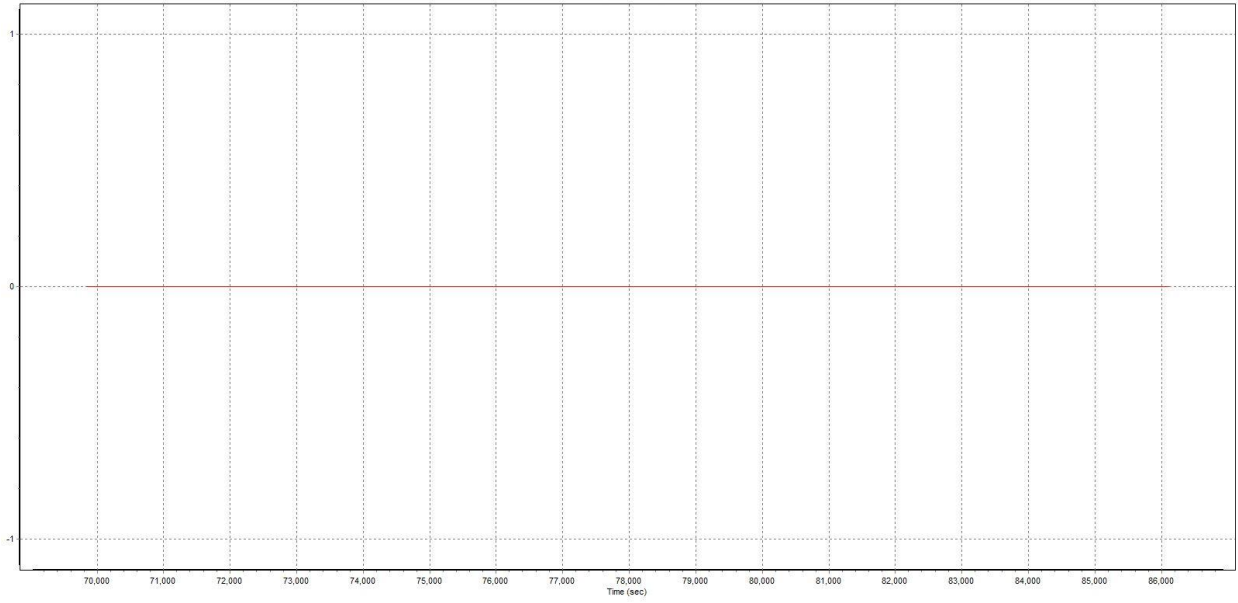
Forward  Reverse

PDOP



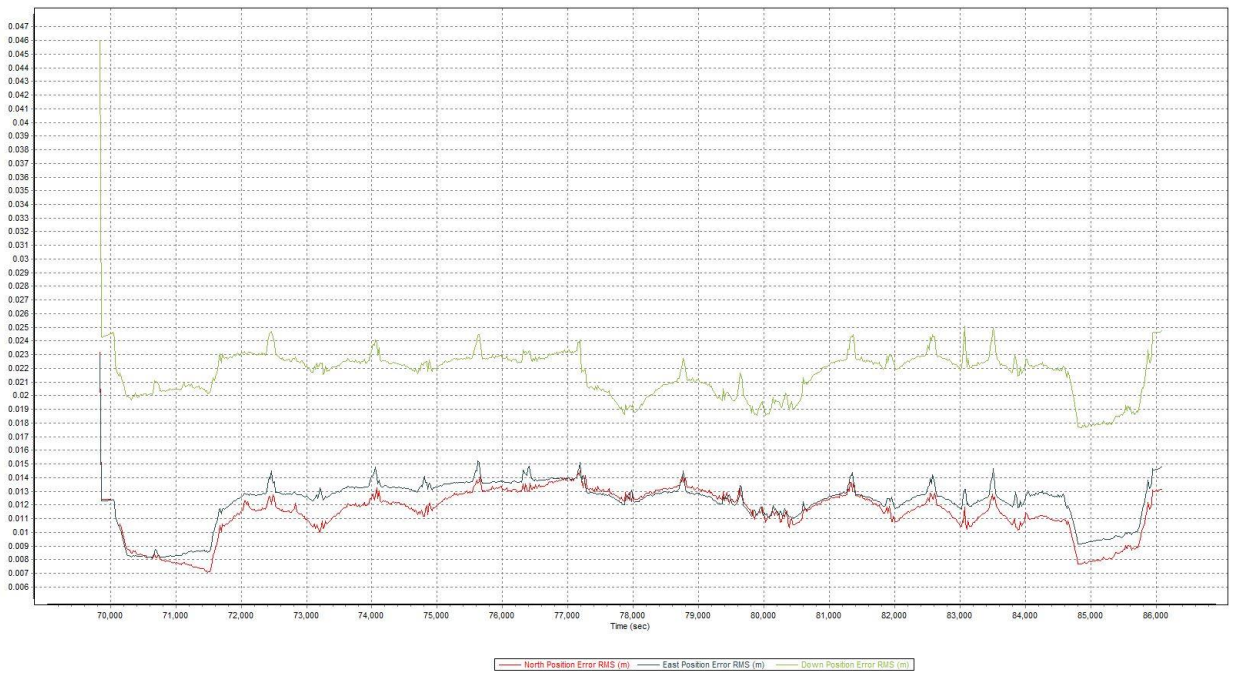
Forward  Reverse

Processing mode

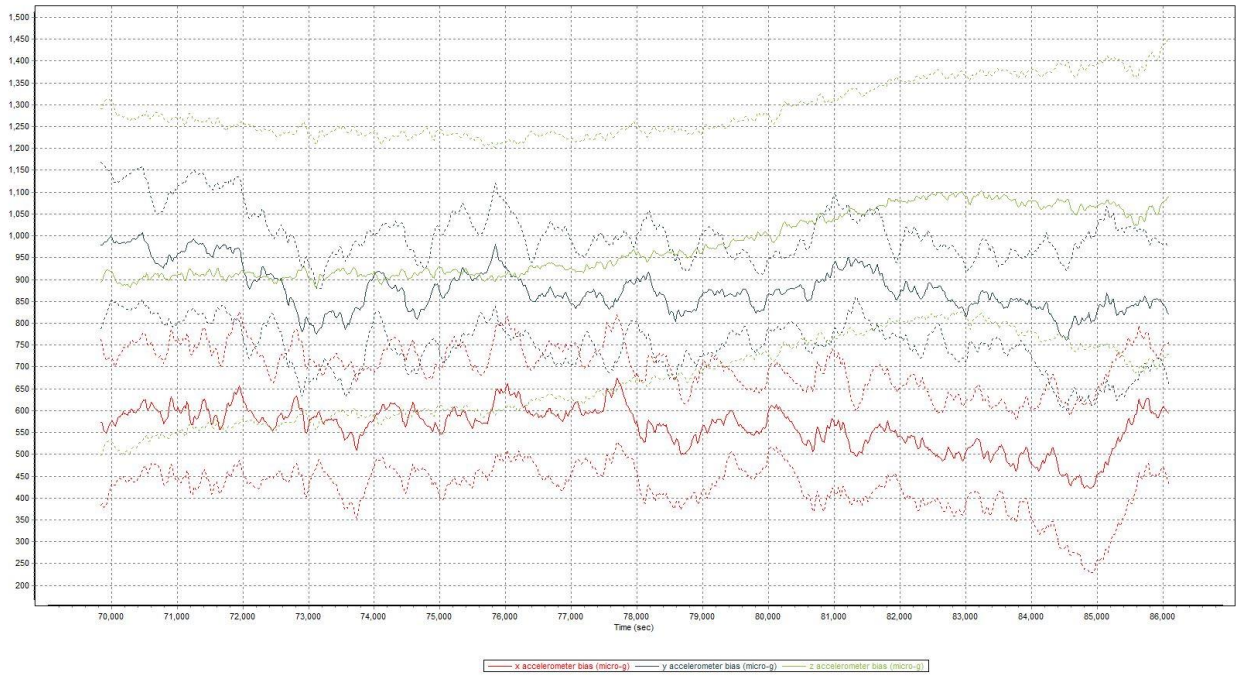
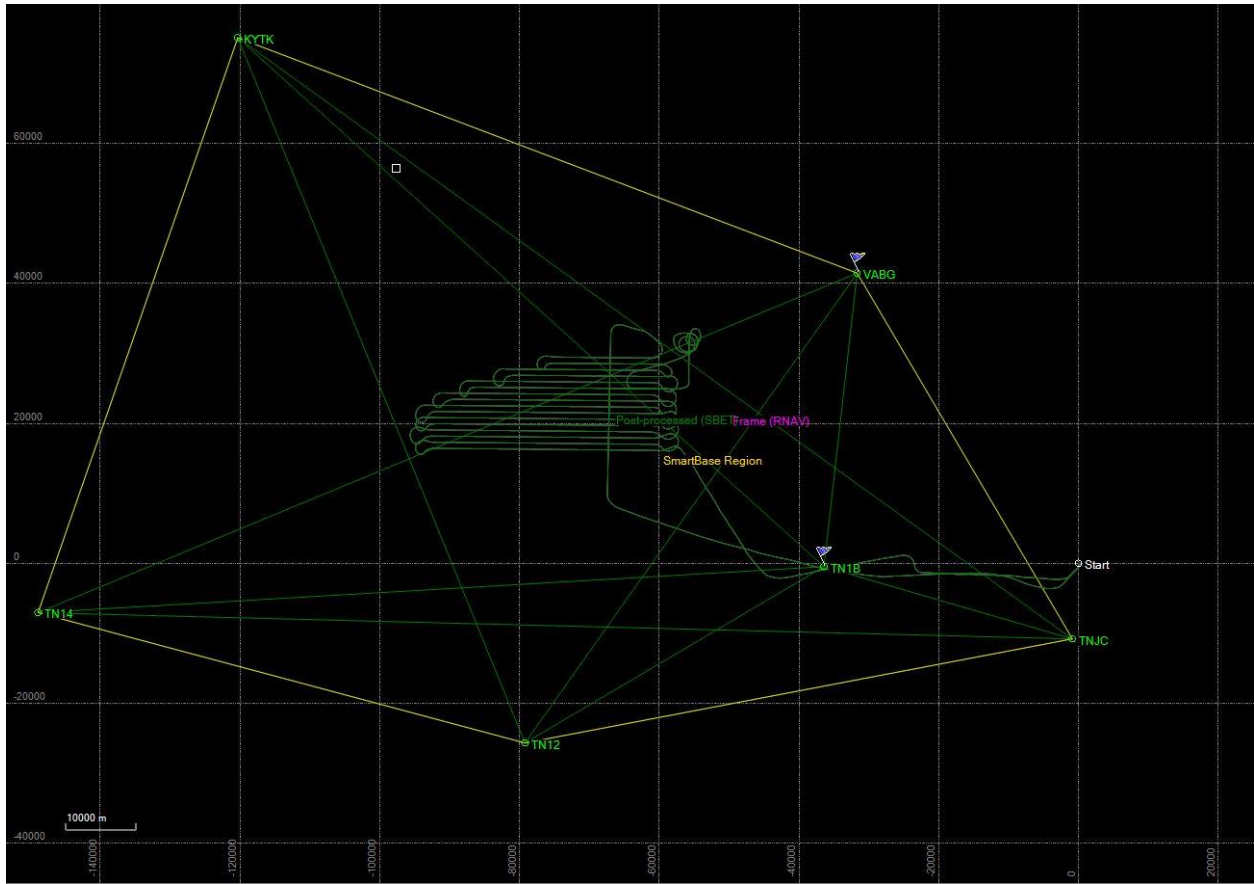


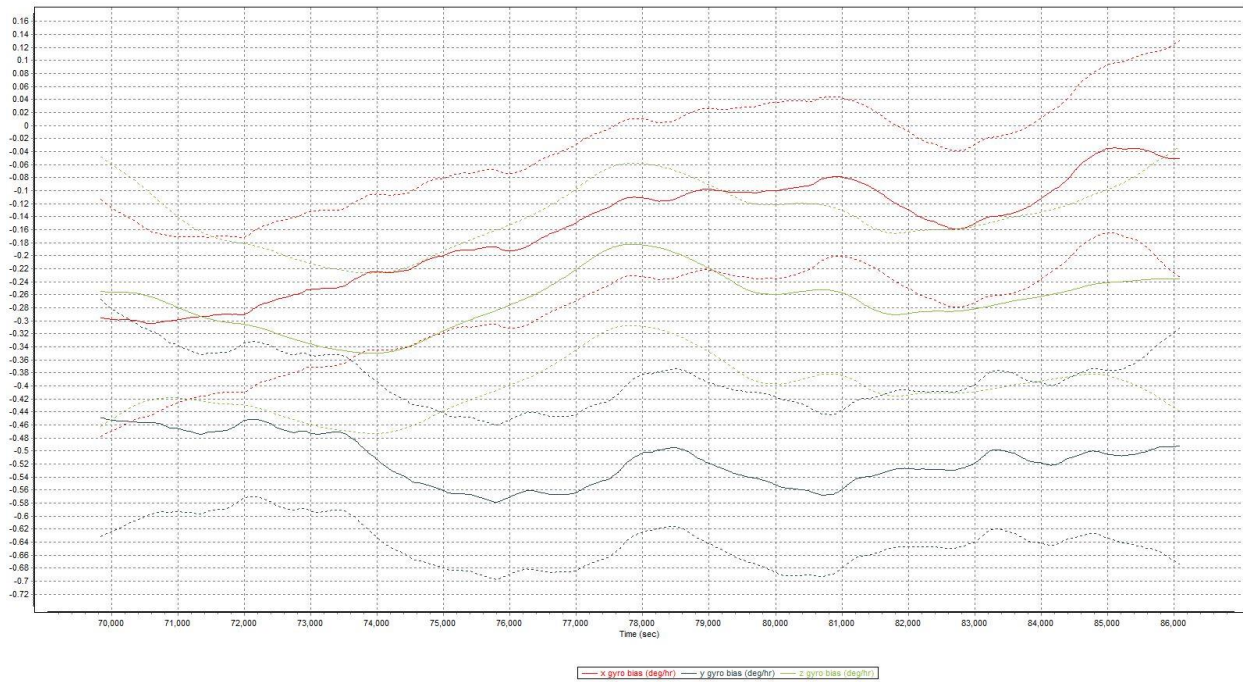
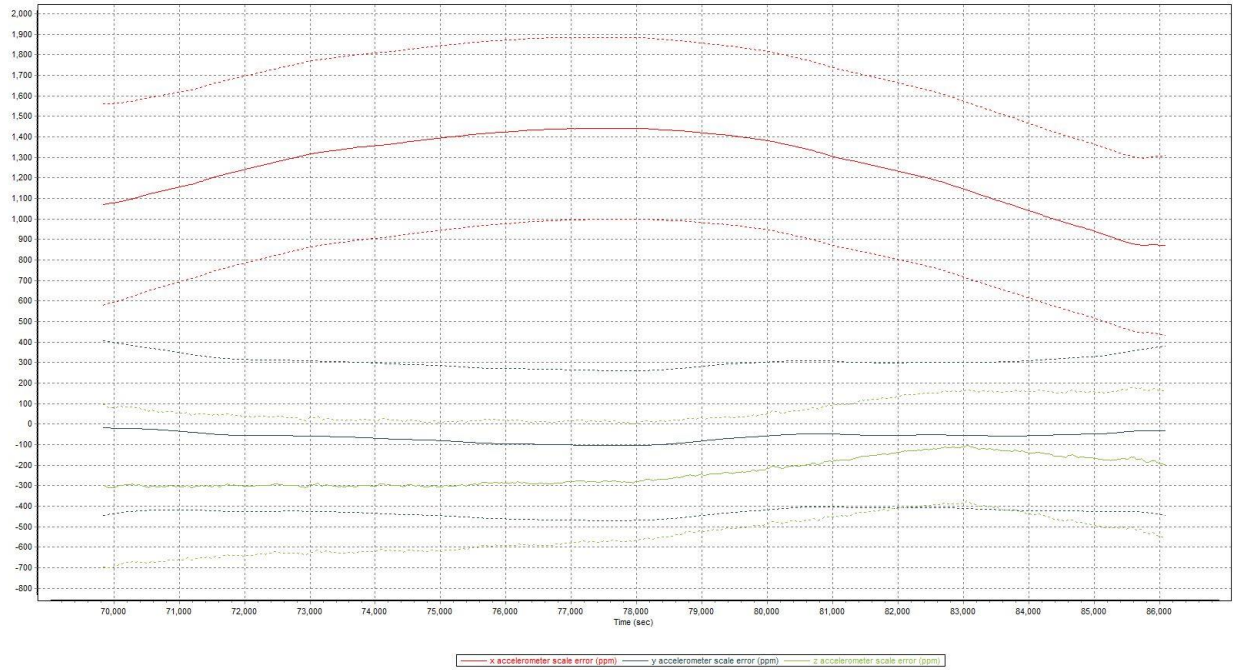
Forward  Reverse

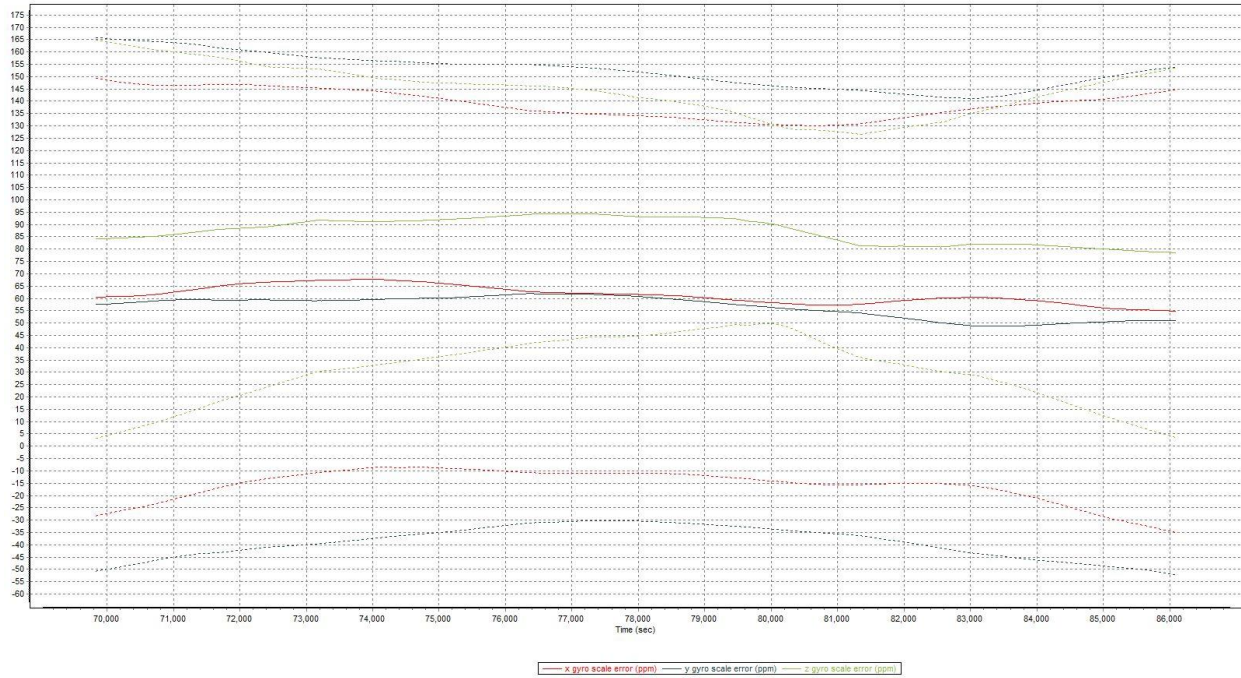
0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = CIA, 7 = GNSS Nav, 8 = DR





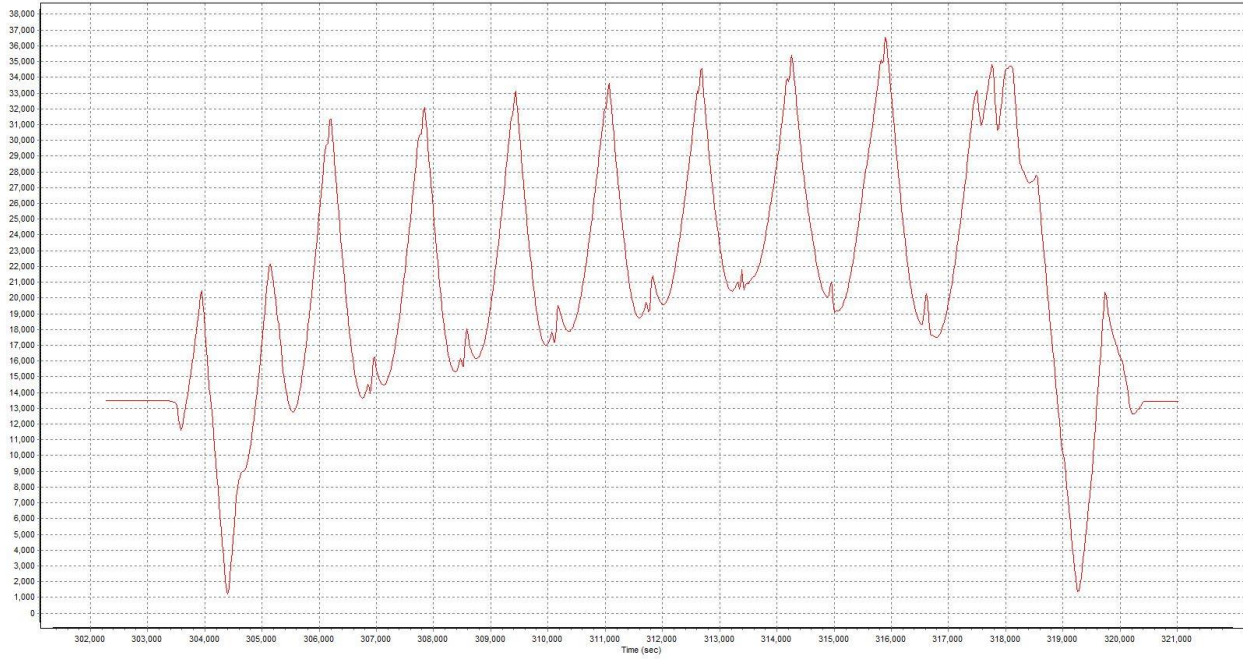




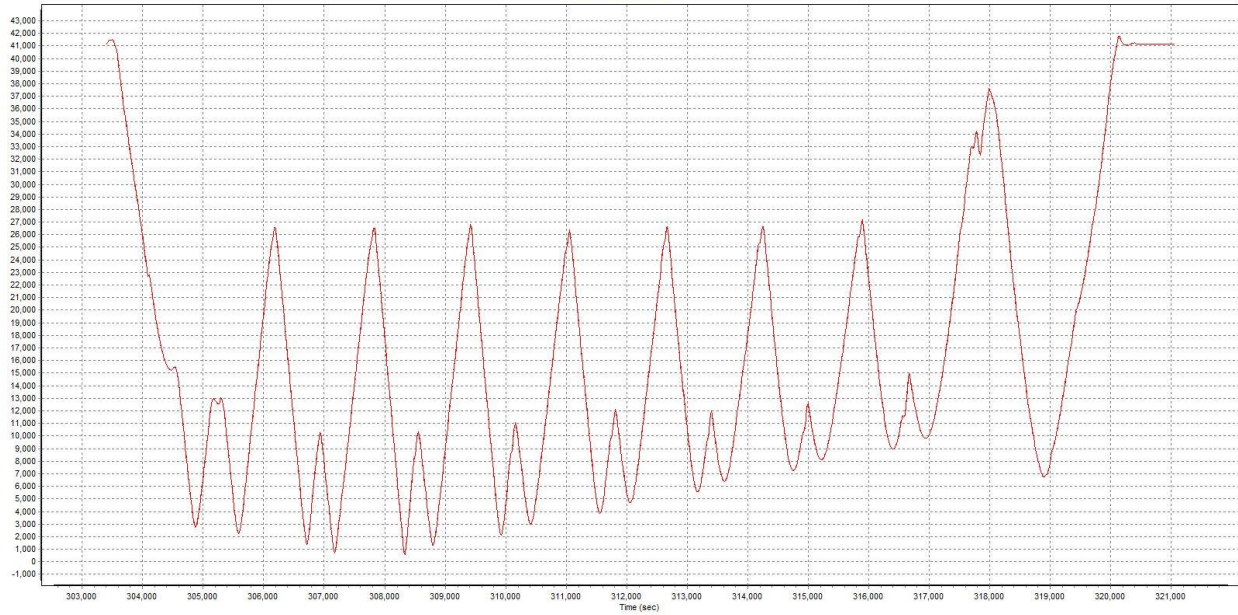


# UNB17095A

3D Distance to Closest GPS Station (m)

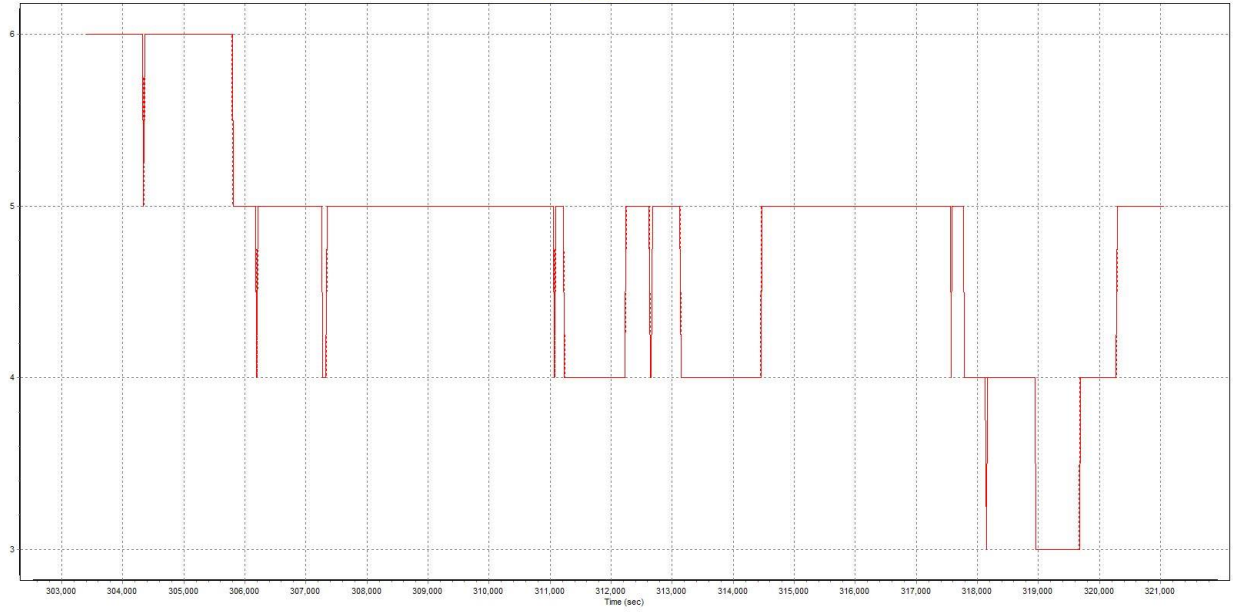


Baseline Length (m)



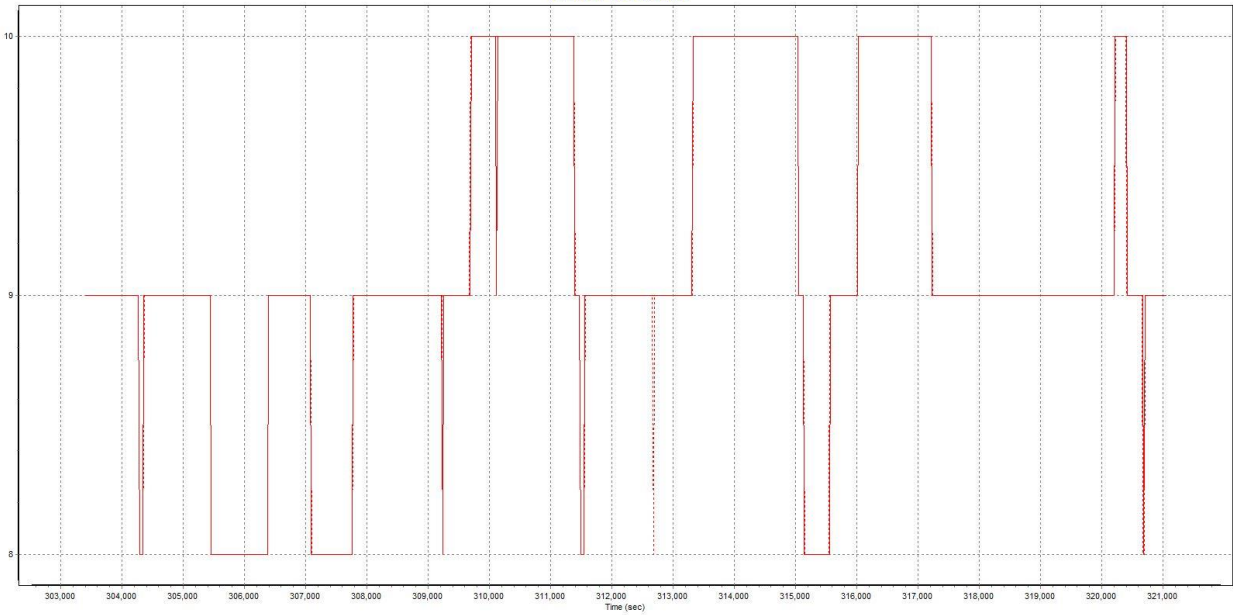
Forward  Reverse

Number of GLONASS Satellites



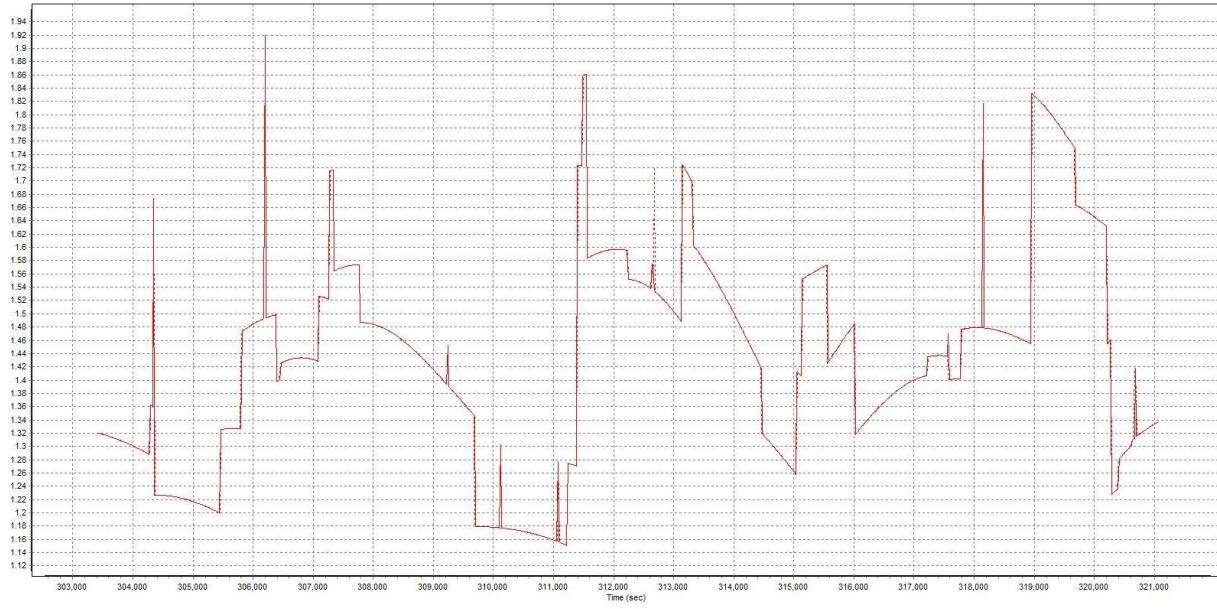
Forward  Reverse

Number of GPS Satellites



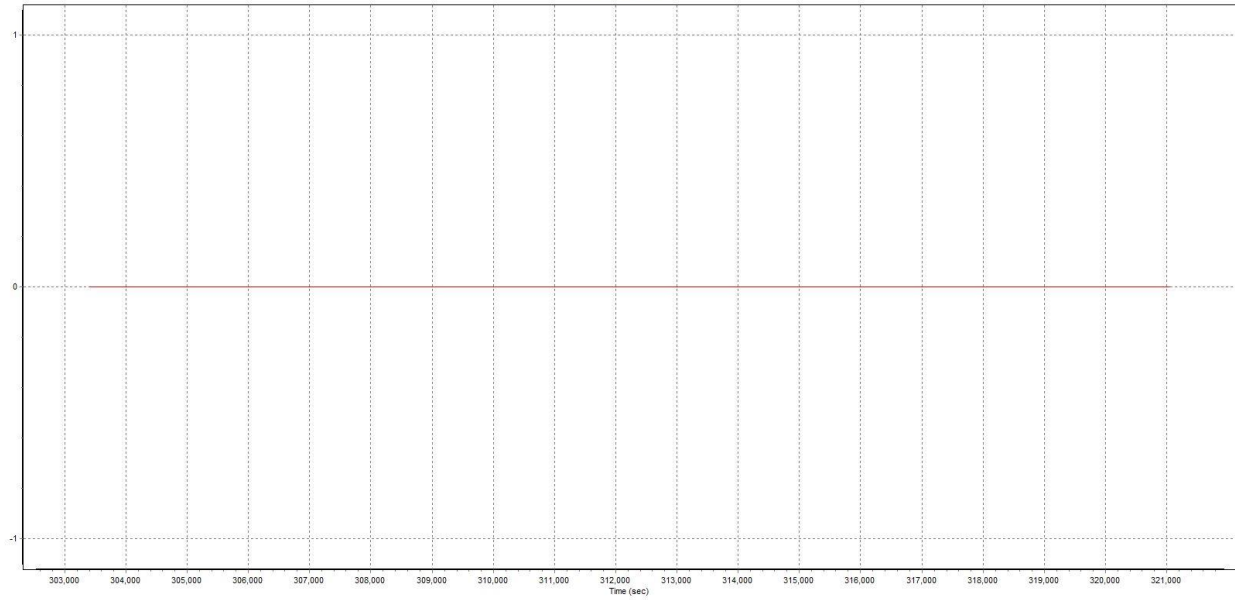
Forward  Reverse

PDOP



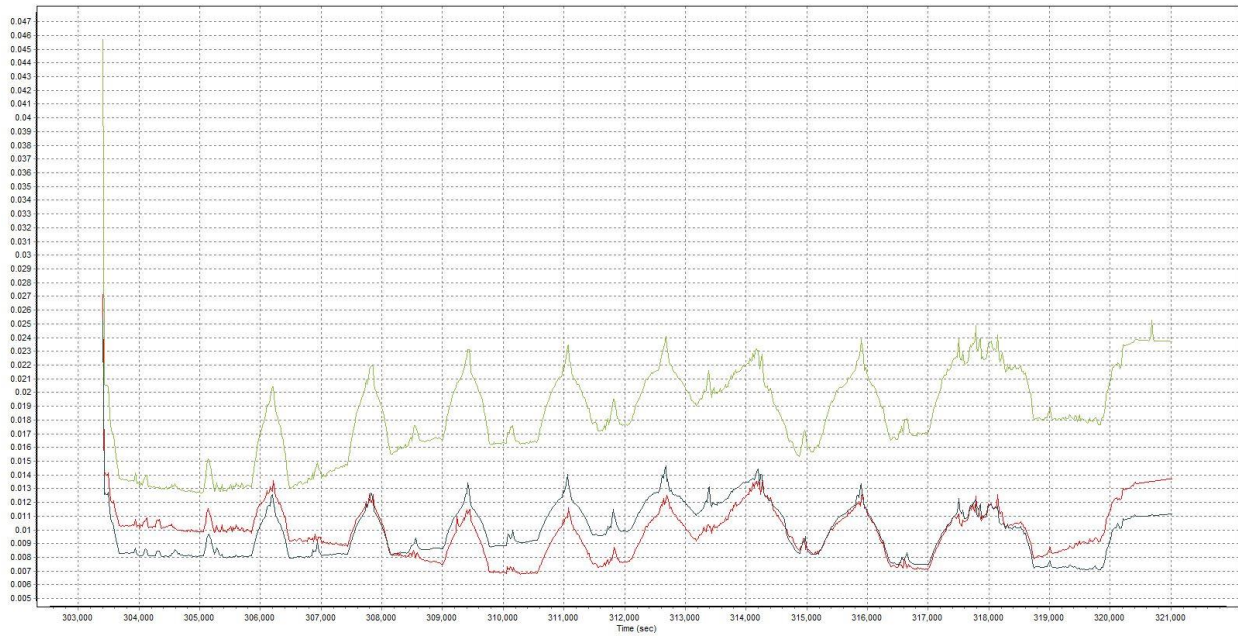
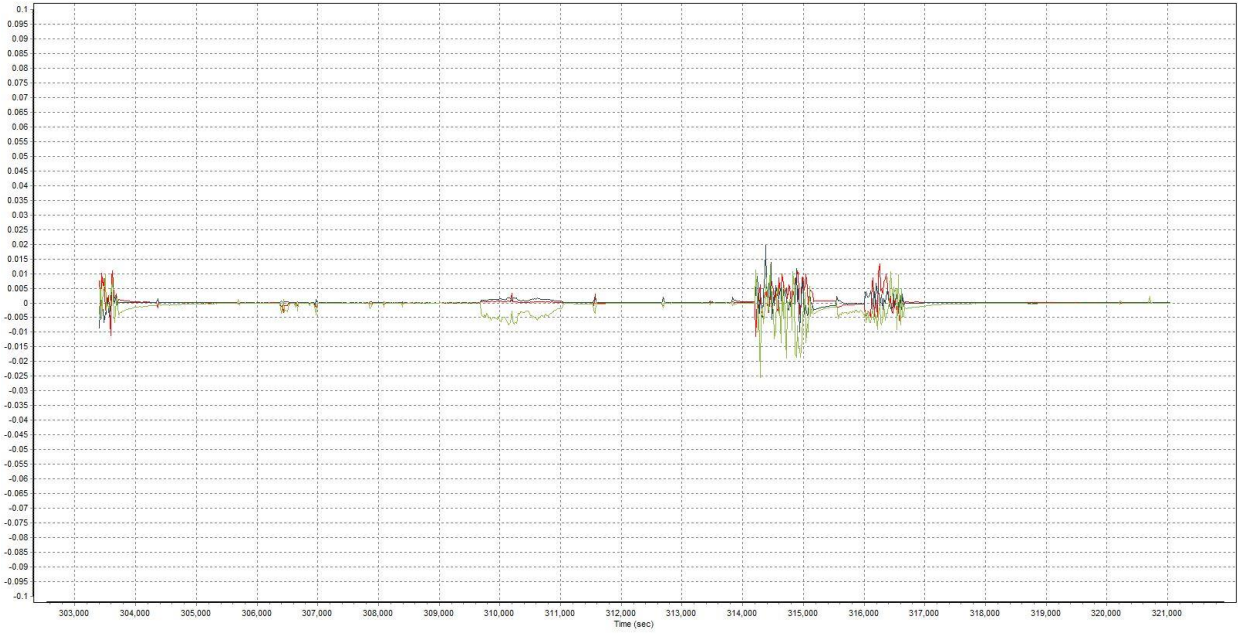
Forward  Reverse

Processing mode

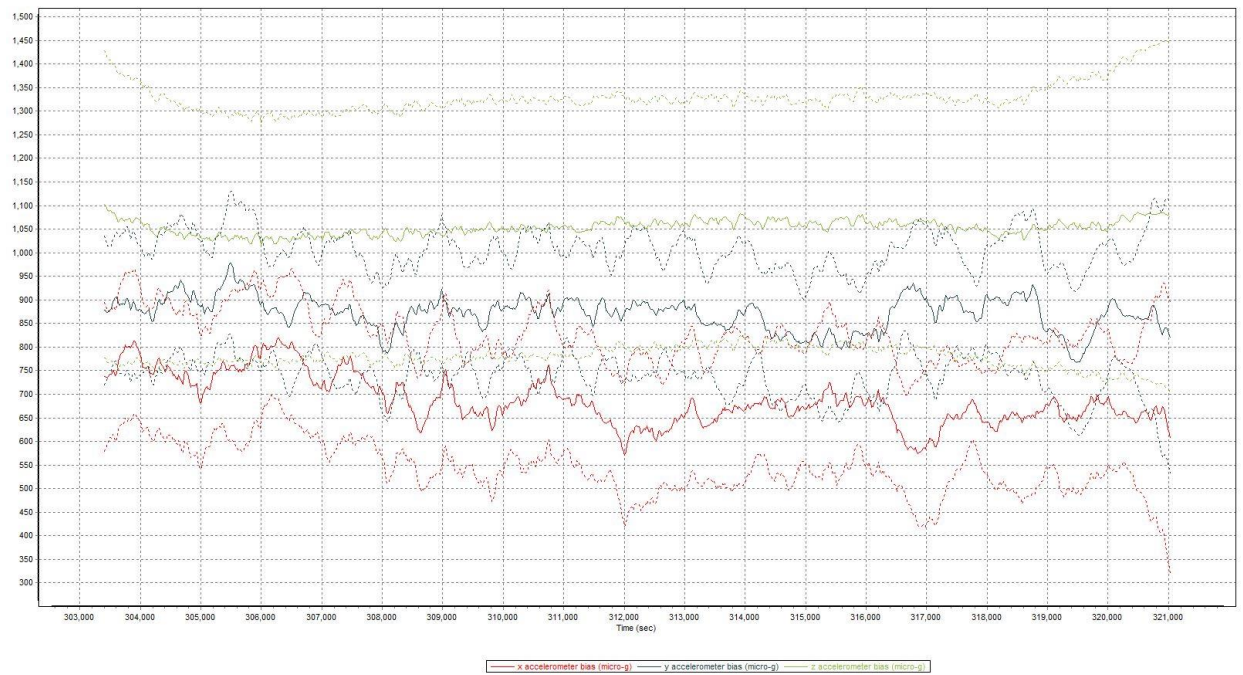
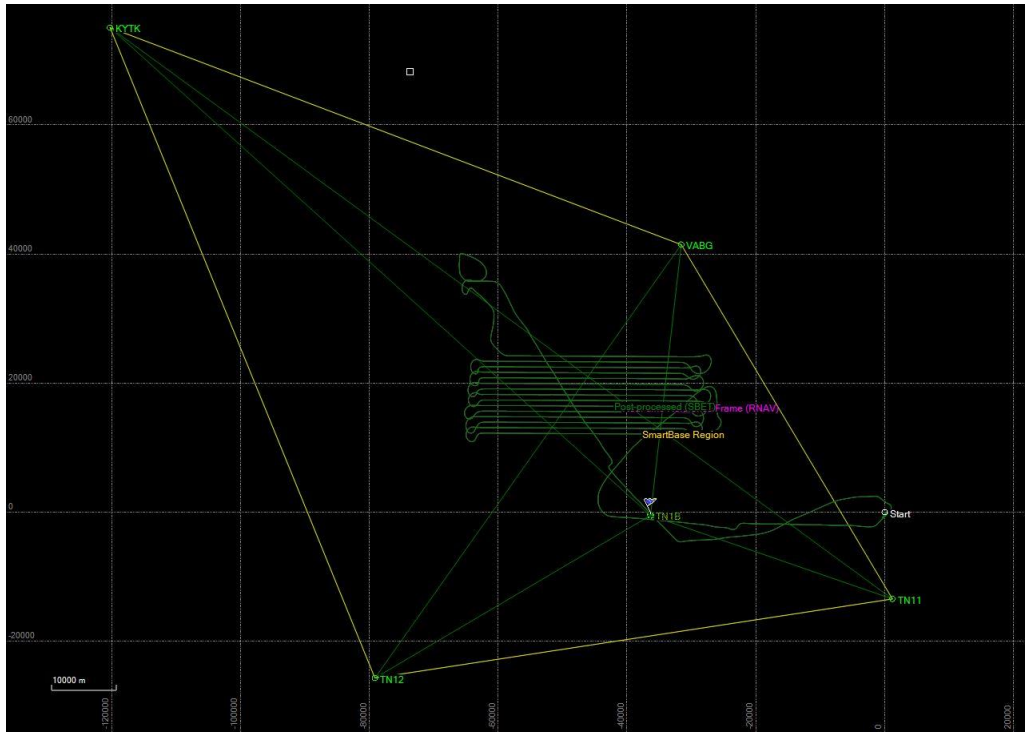


Forward  Reverse

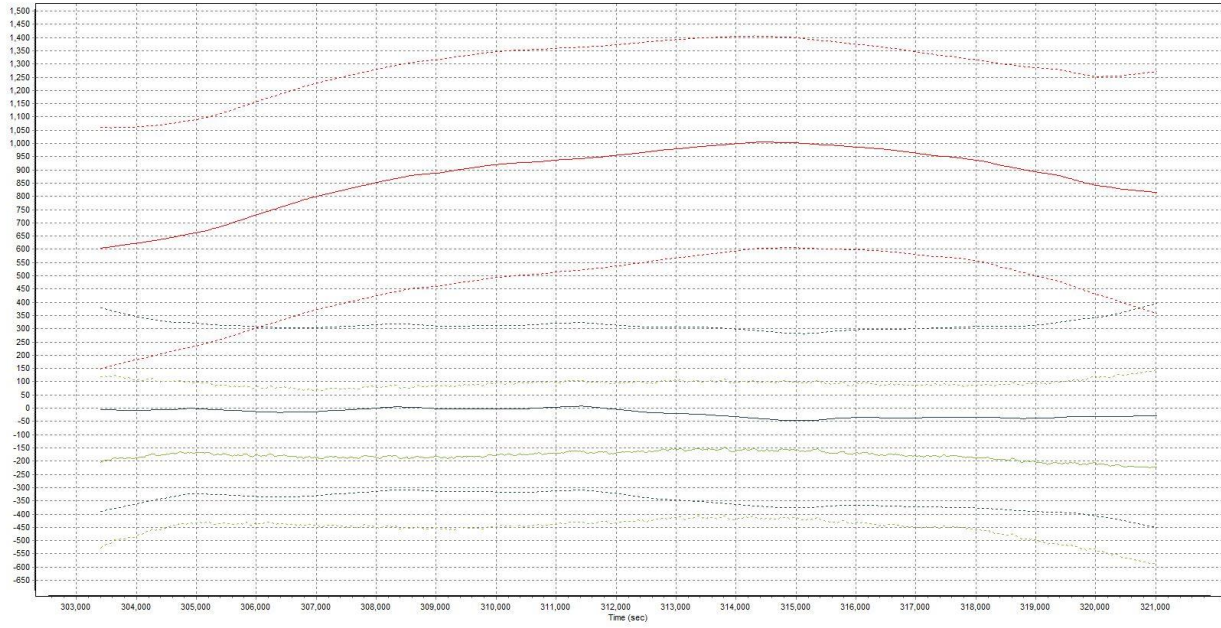
0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = CIA, 7 = GNSS Nav, 8 = DR



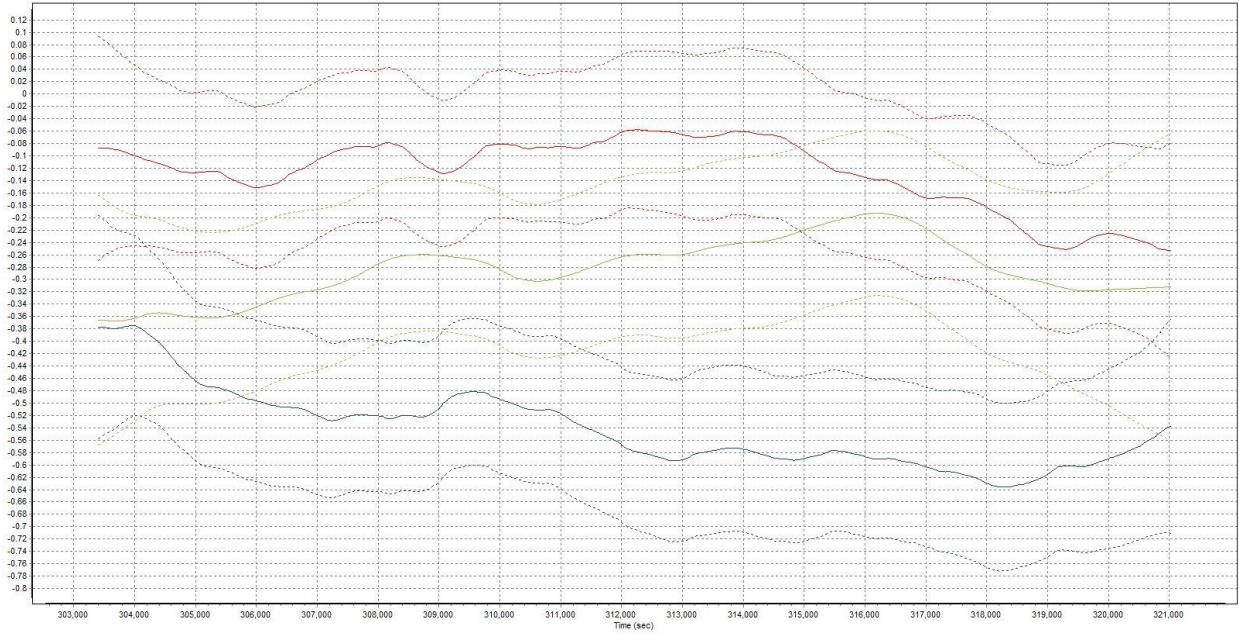
North Position Error RMS (m) East Position Error RMS (m) Down Position Error RMS (m)



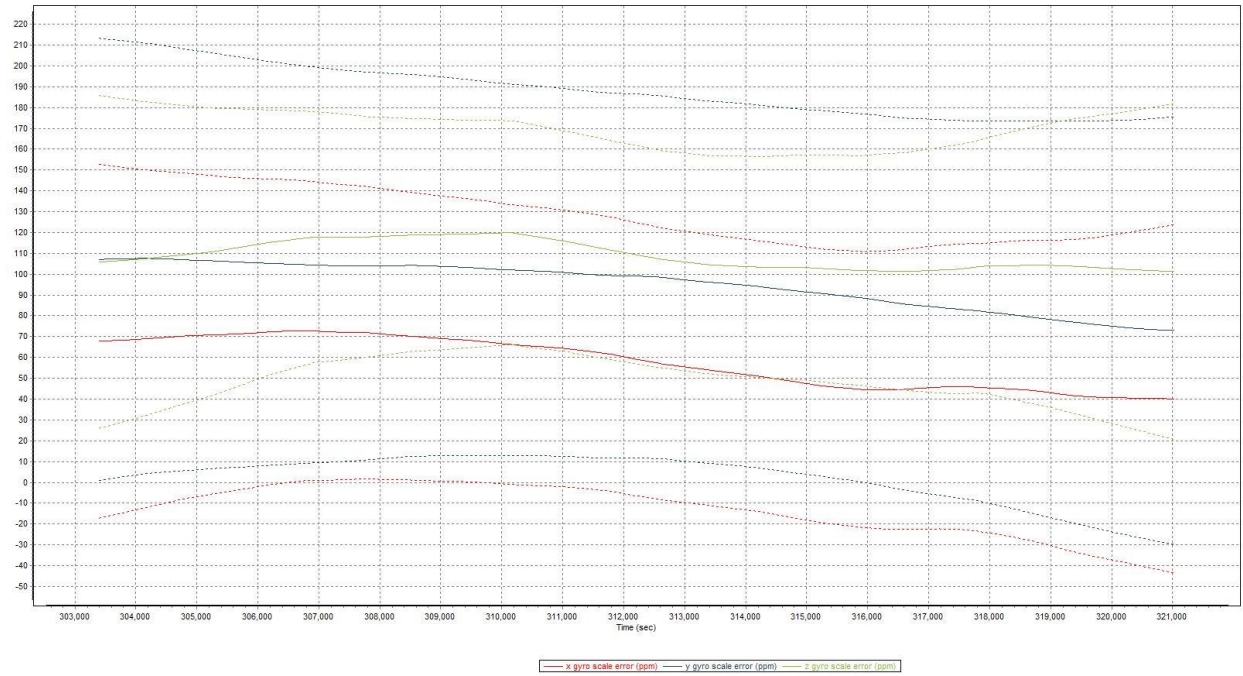




x accelerometer scale error (ppm)    y accelerometer scale error (ppm)    z accelerometer scale error (ppm)

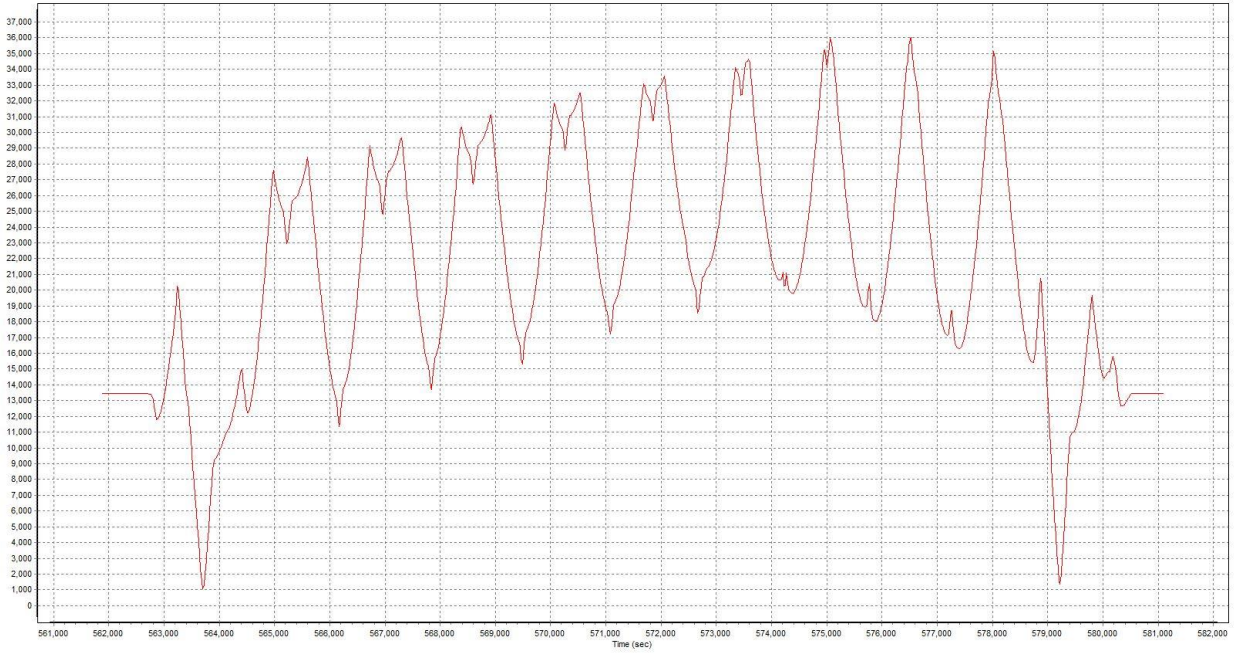


x gyro bias (deg/hr)    y gyro bias (deg/hr)    z gyro bias (deg/hr)

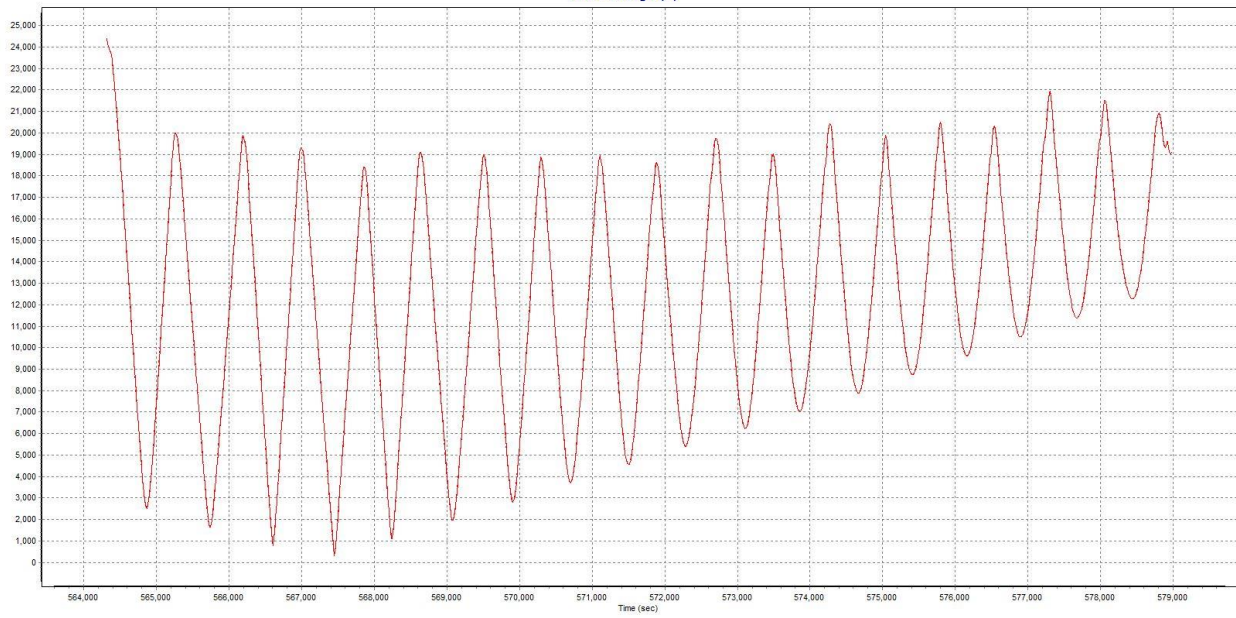


# UNB17098A

3D Distance to Closest GPS Station (m)

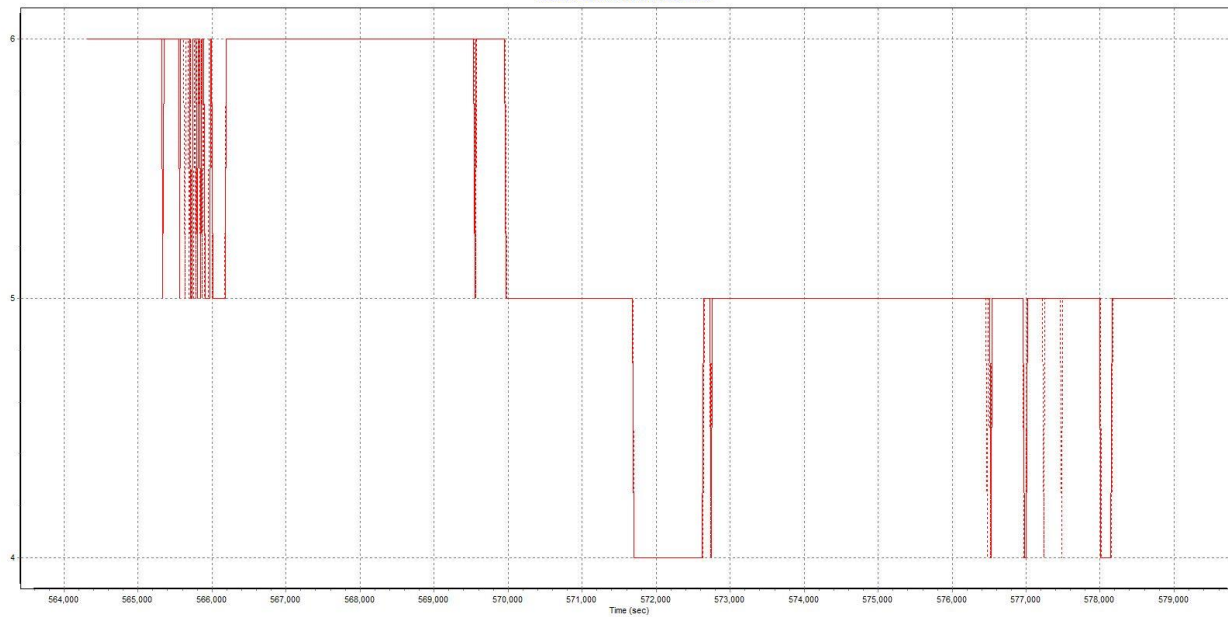


Baseline Length (m)



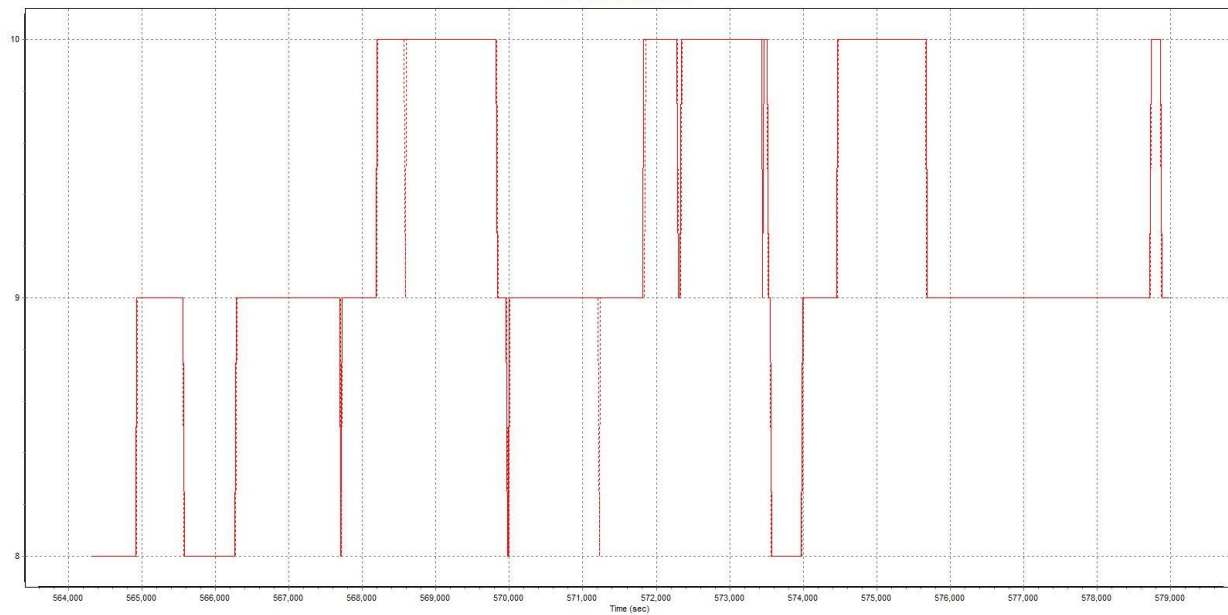
- Forward  - Reverse

Number of GLONASS Satellites



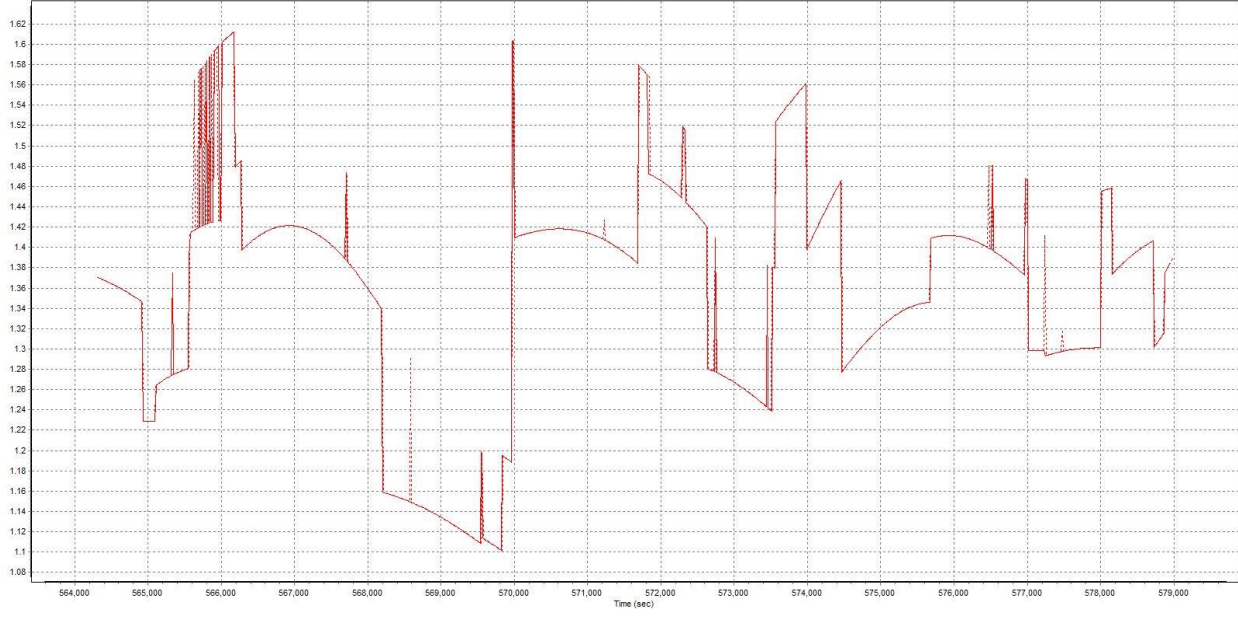
Forward  Reverse

Number of GPS Satellites



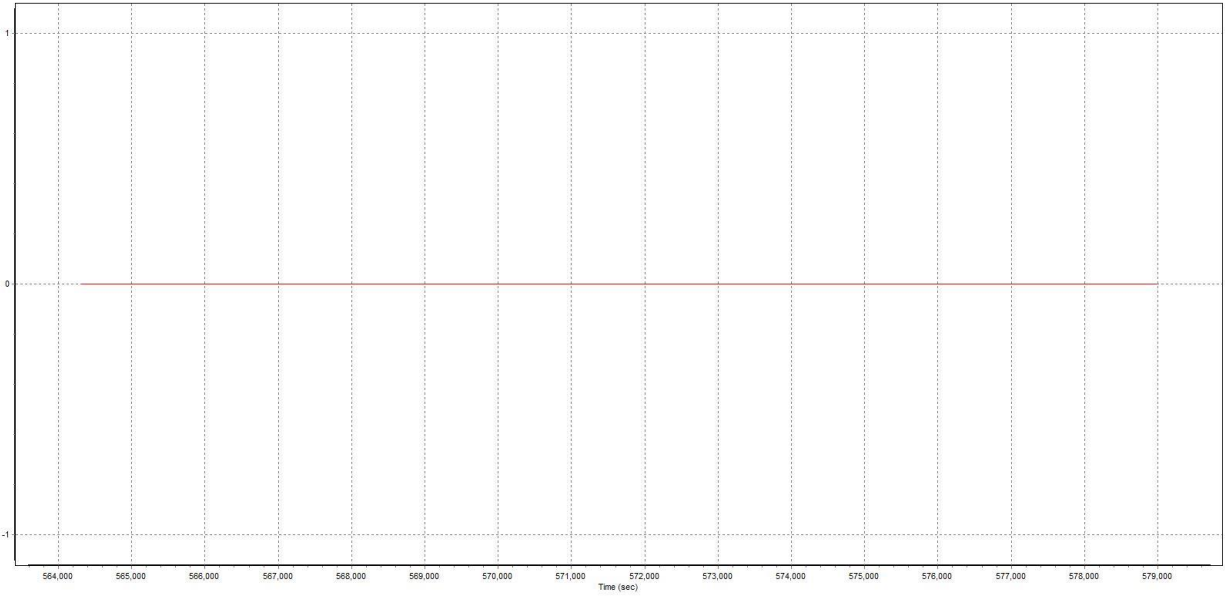
Forward  Reverse

PDOP



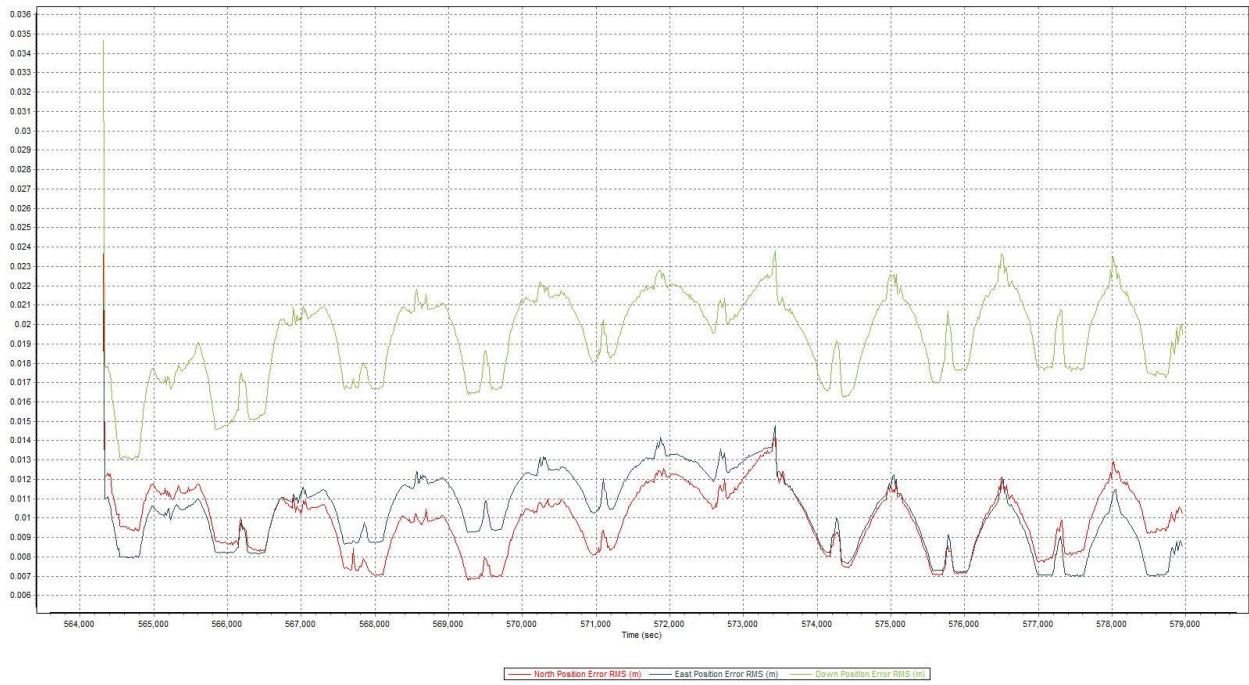
Forward  Reverse

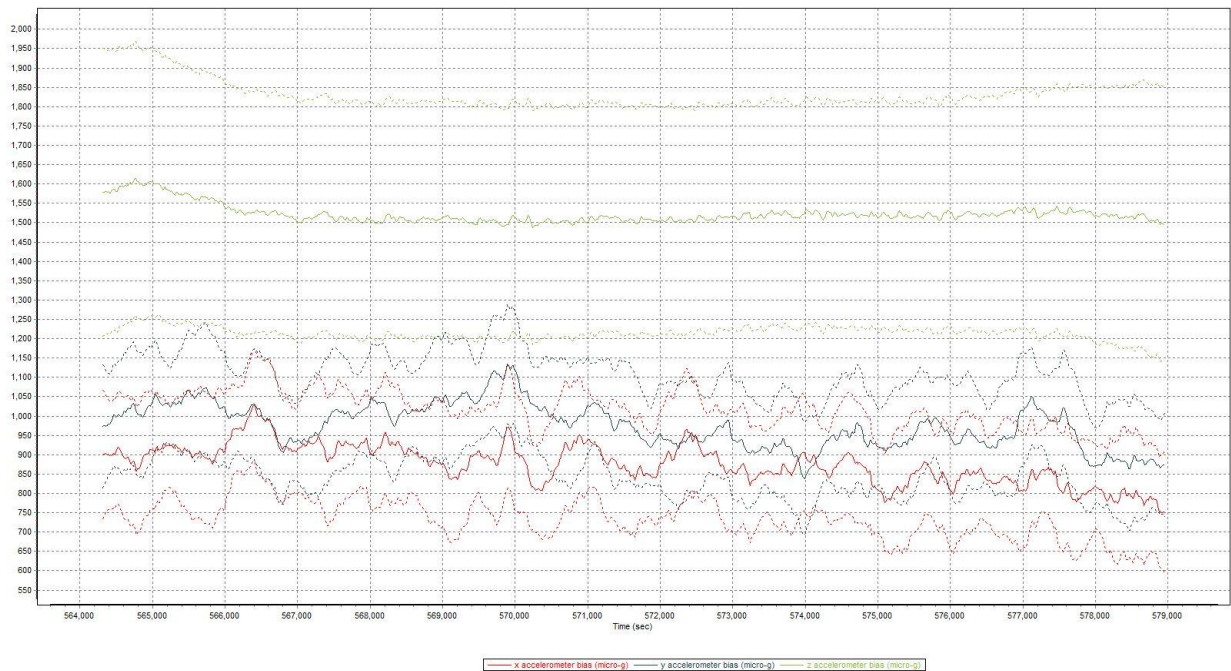
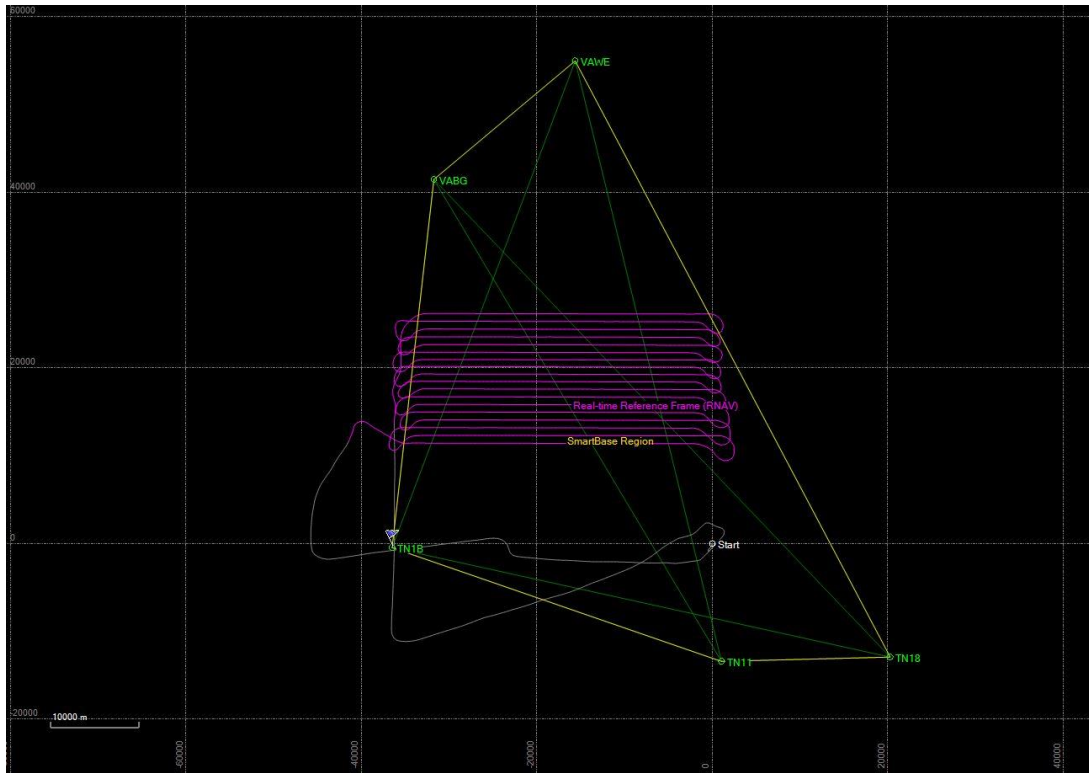
Processing mode

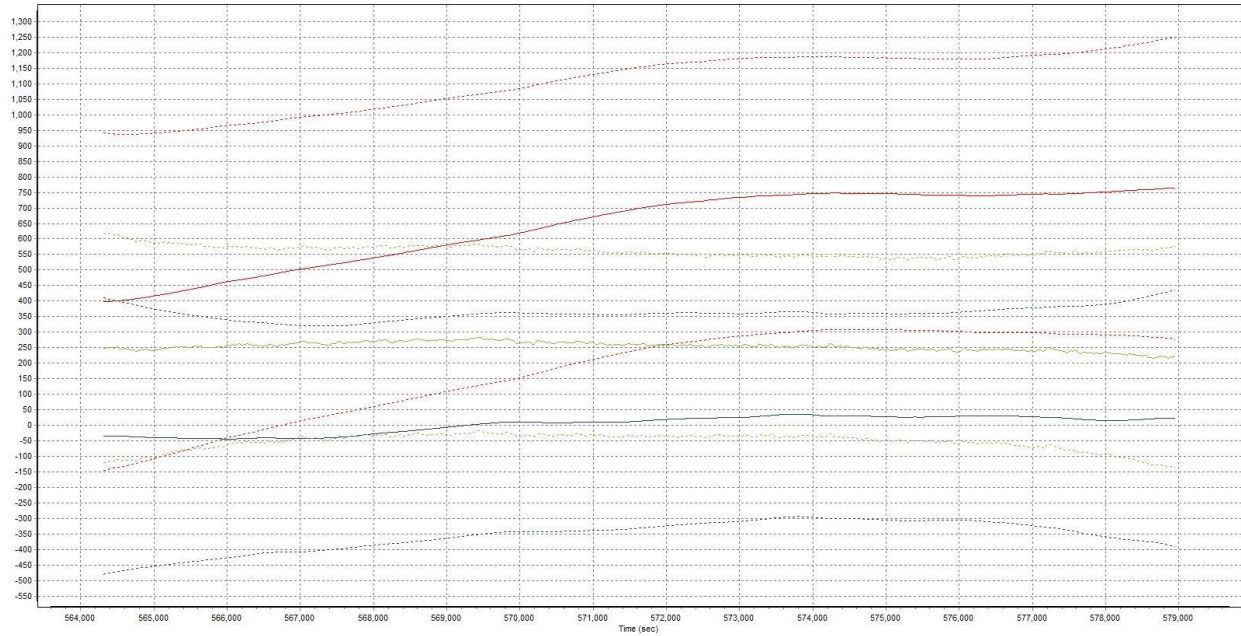


Forward  Reverse

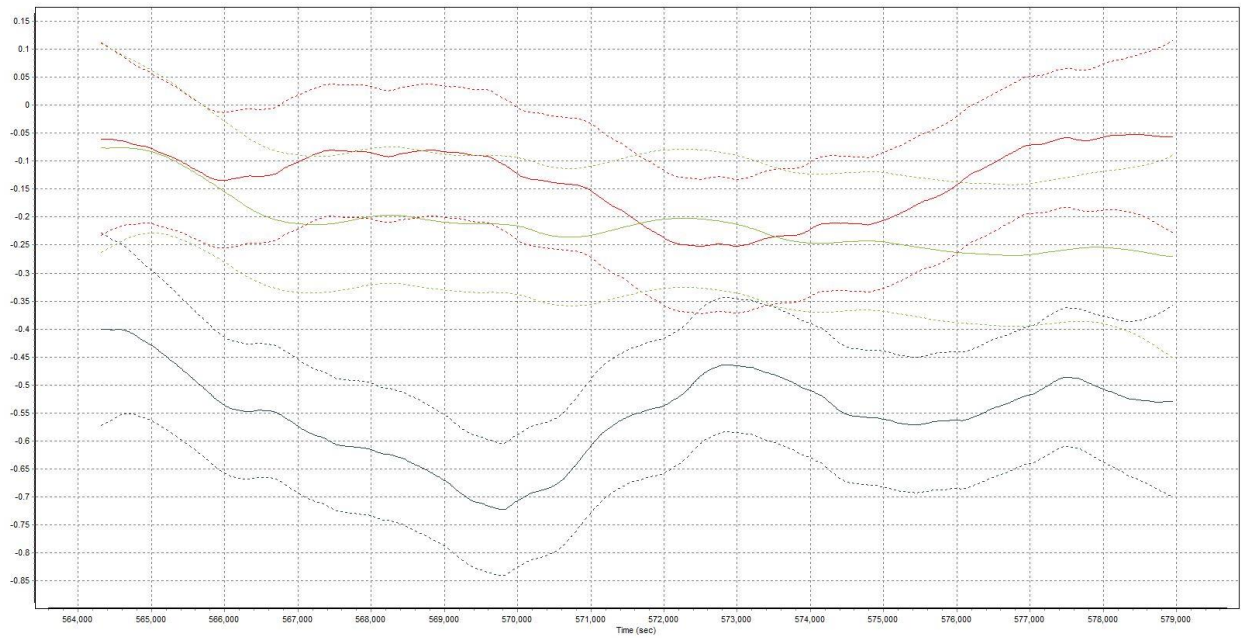
0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNS, 4 = RTCM, 5 = IAPPP, 6 = CIA, 7 = GNSS Nav, 8 = DR





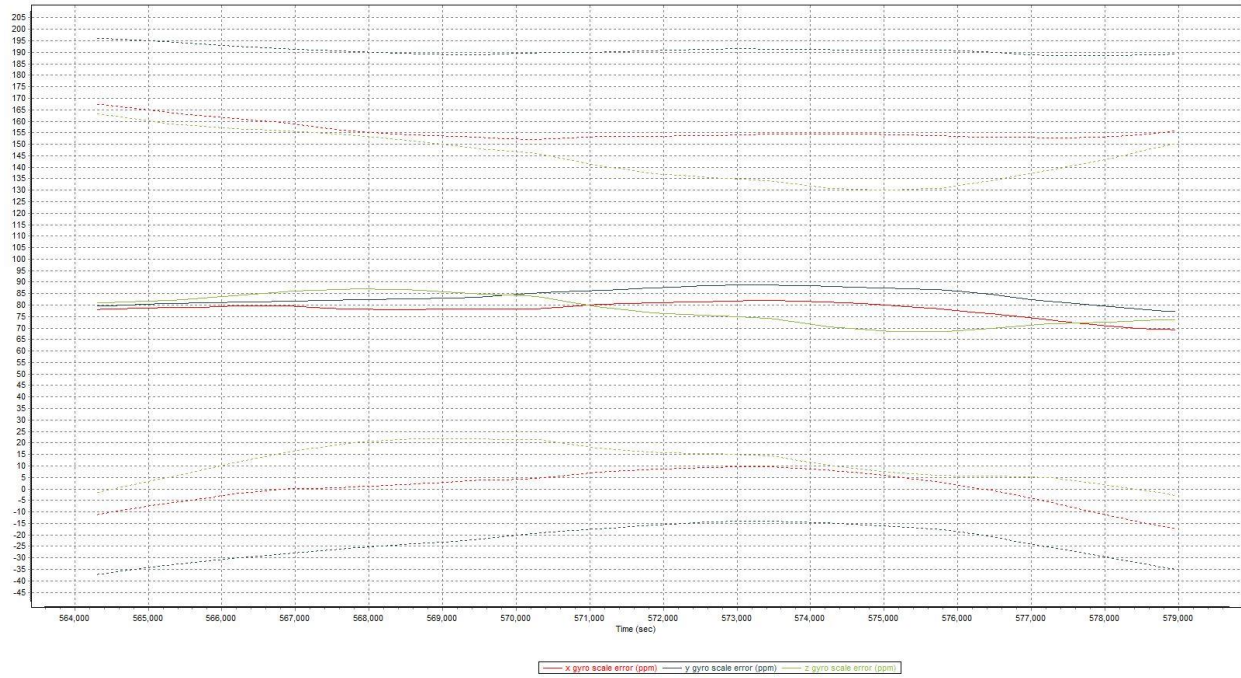


x accelerometer scale error (ppm) y accelerometer scale error (ppm) z accelerometer scale error (ppm)



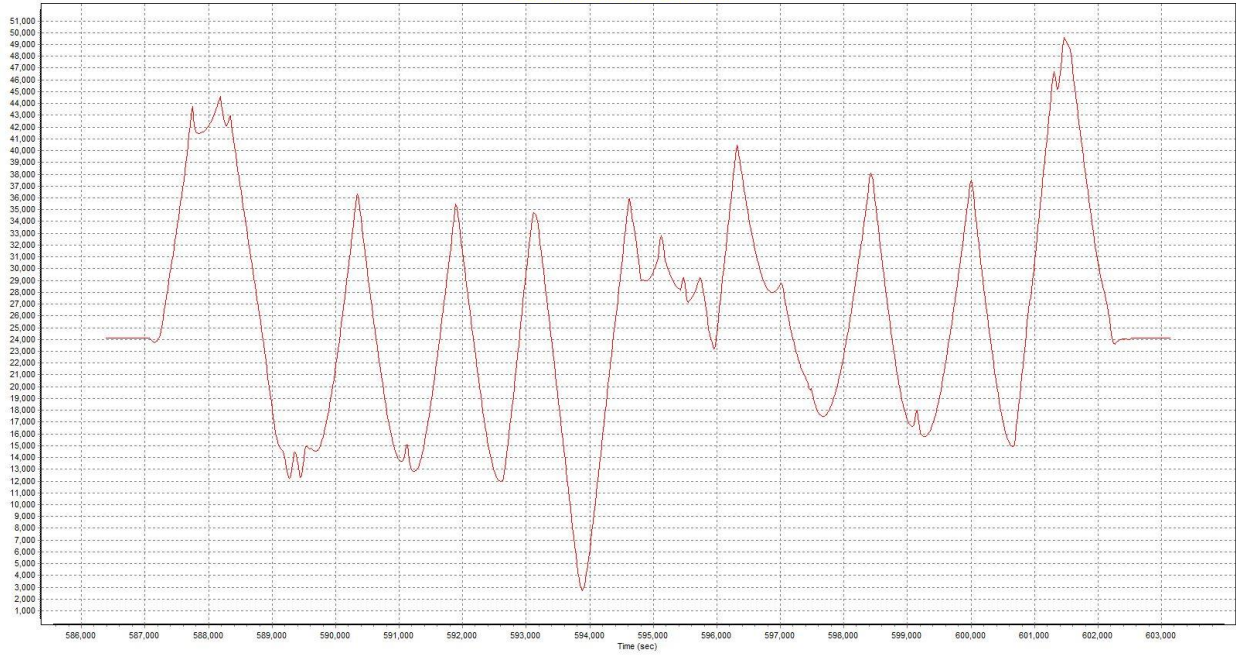
x gyro bias (deg/hr) y gyro bias (deg/hr) z gyro bias (deg/hr)



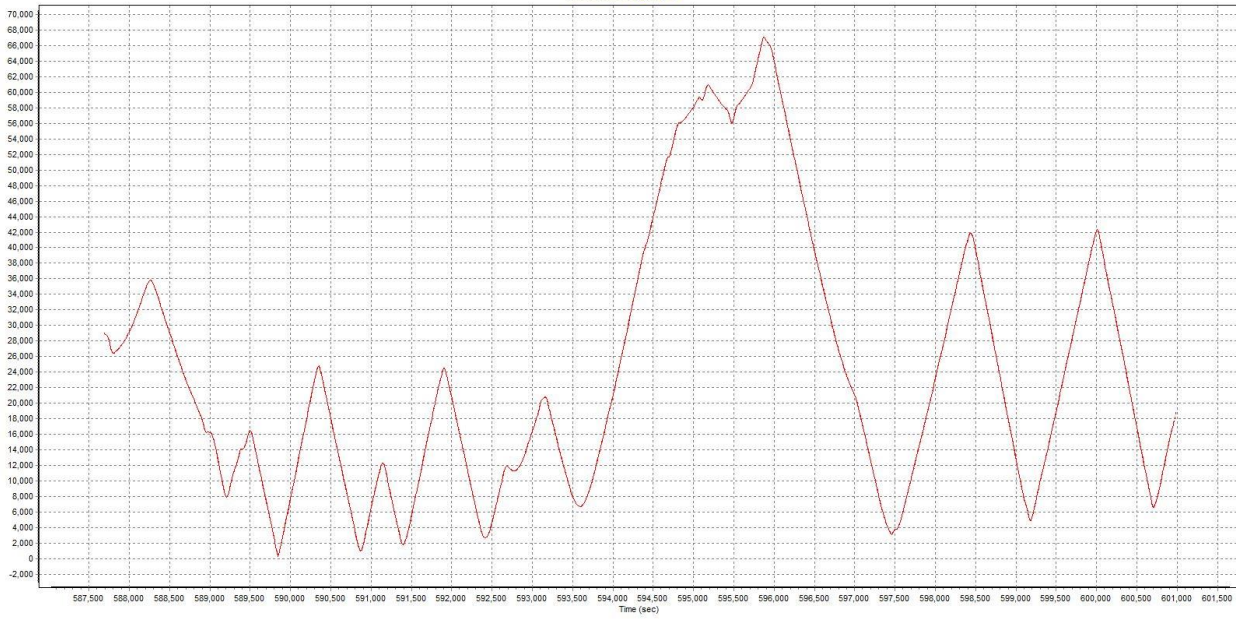


# UNB17098B

3D Distance to Closest GPS Station (m)

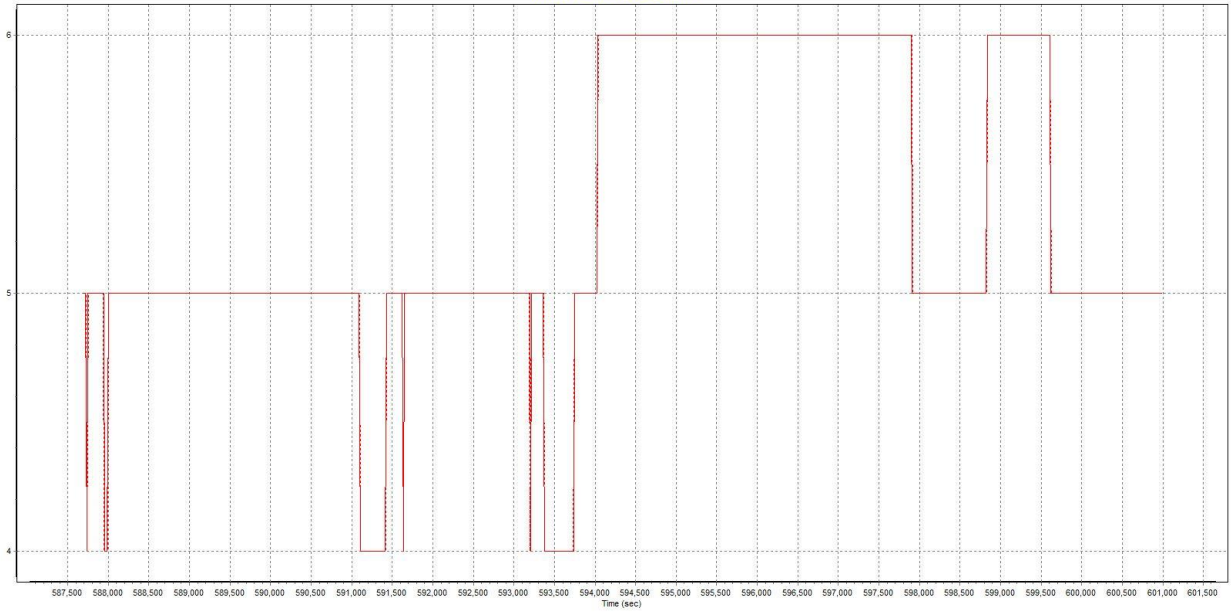


Baseline Length (m)



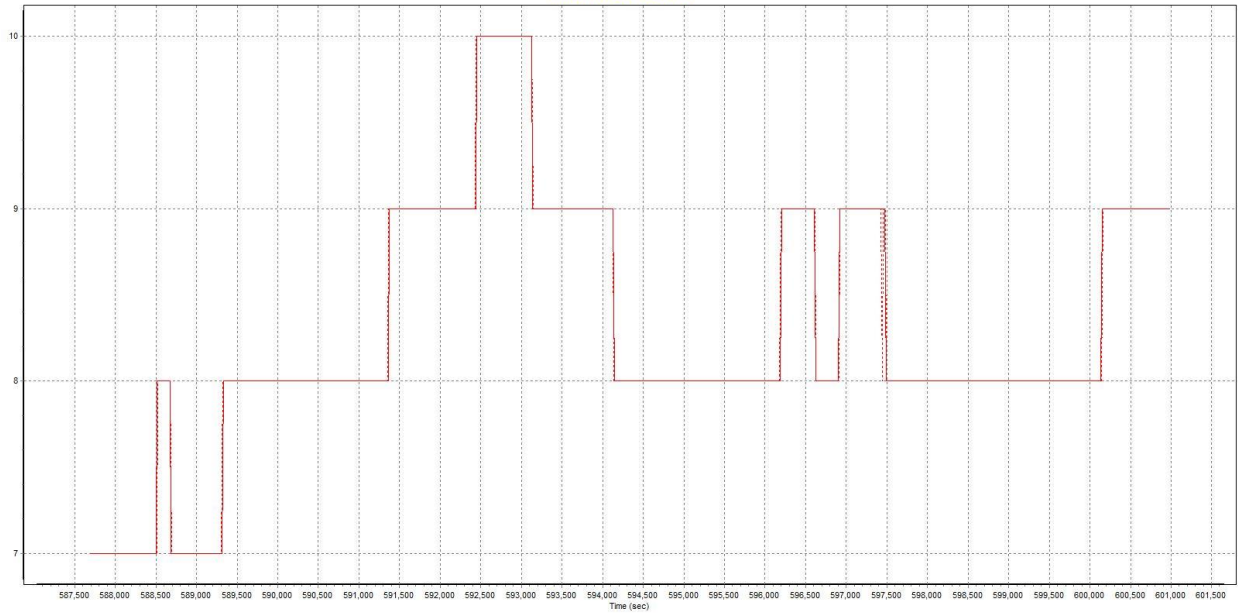
Forward  Reverse

Number of GLONASS Satellites



Forward  Reverse

Number of GPS Satellites



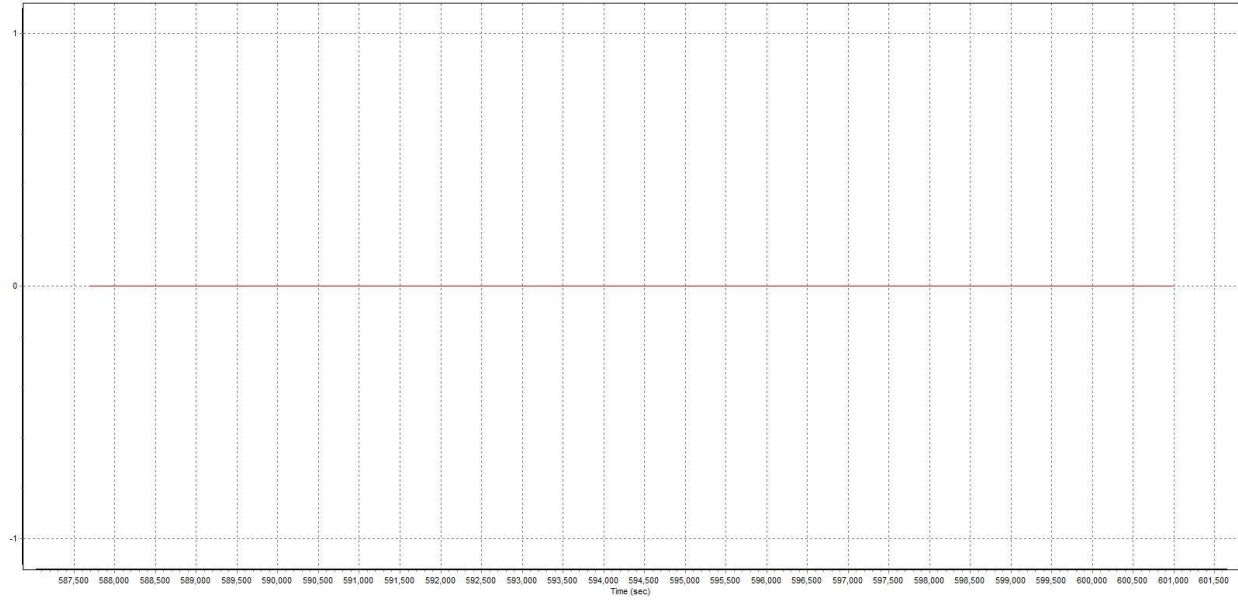
Forward  Reverse

PDOP



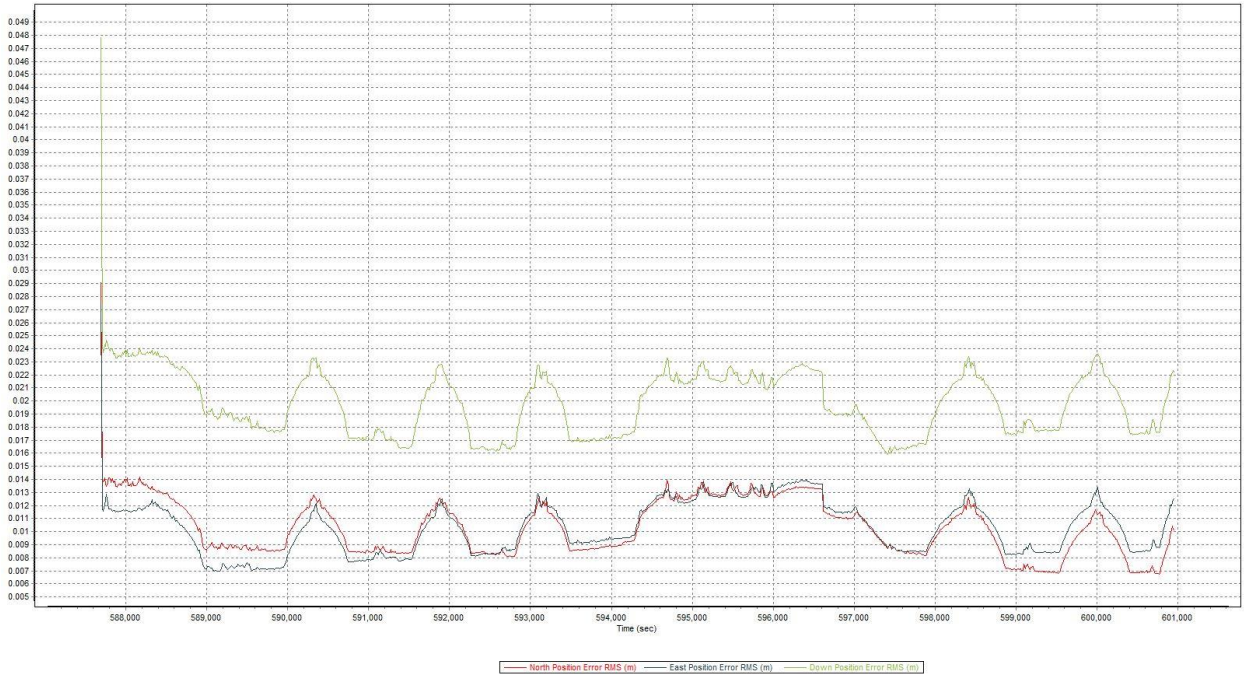
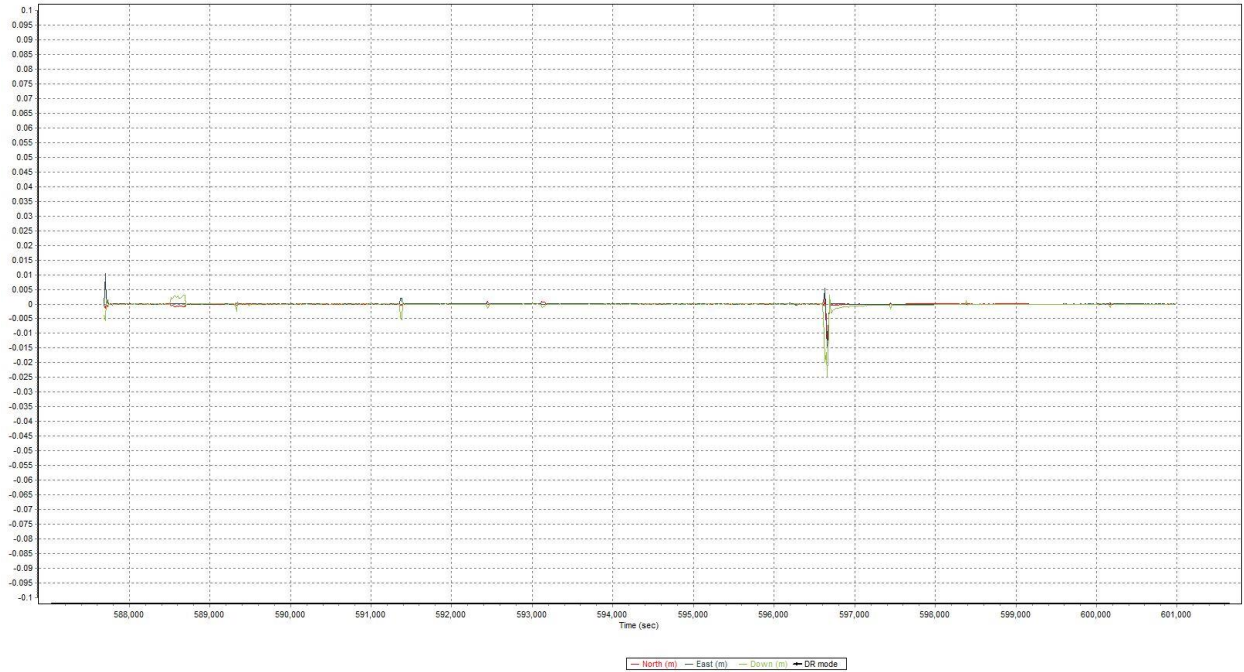
Forward  Reverse

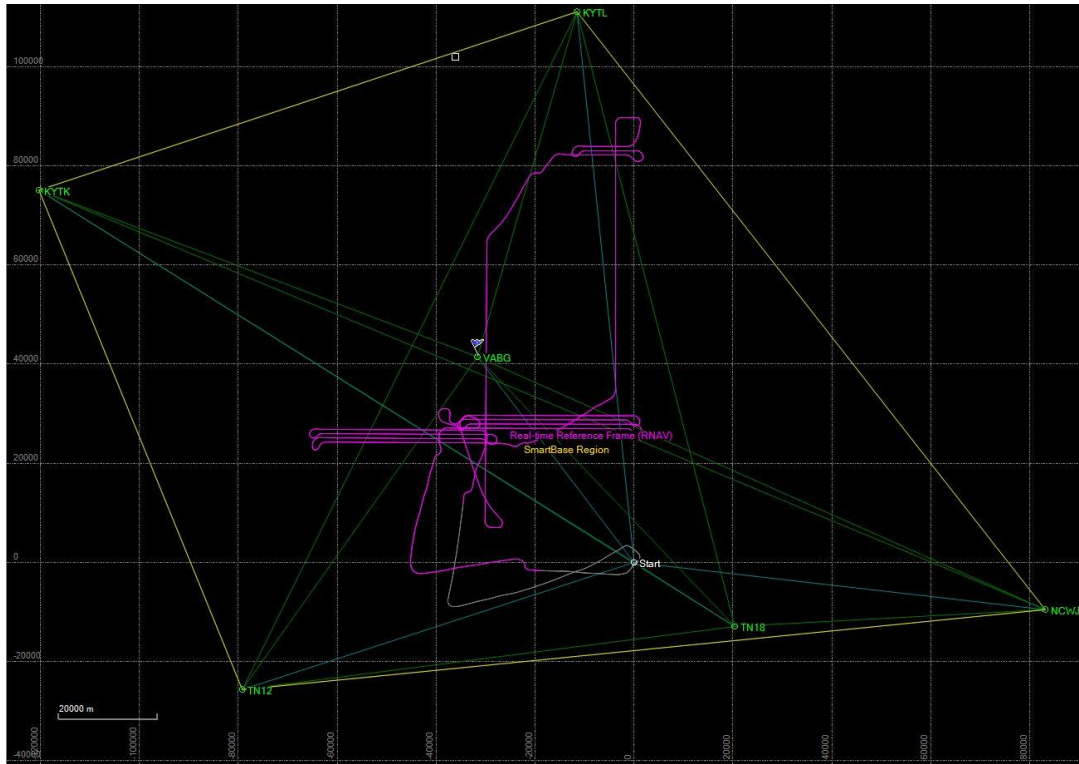
Processing mode

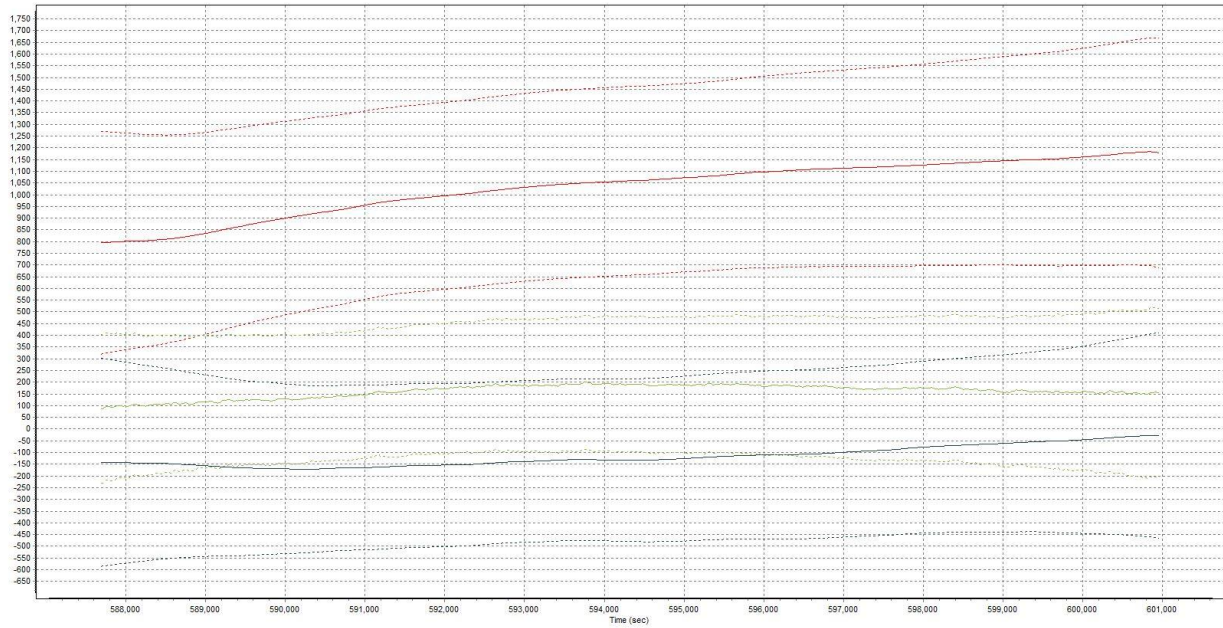


Forward  Reverse

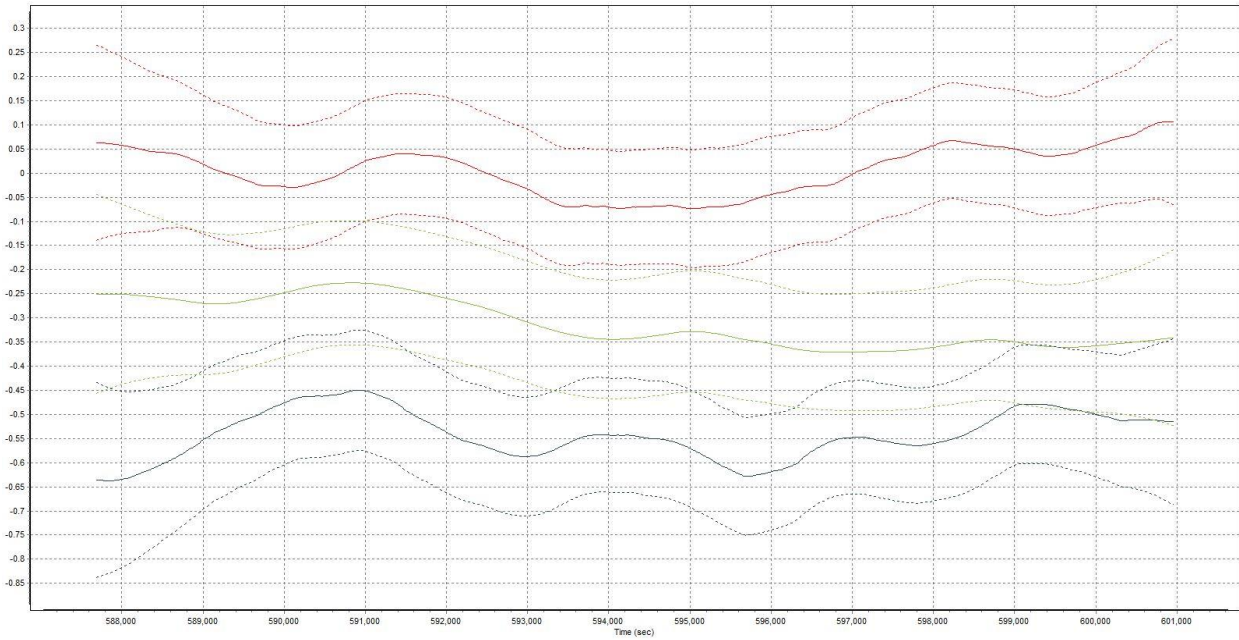
0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IARPP, 6 = CIA, 7 = GNSS Nav, 8 = DR



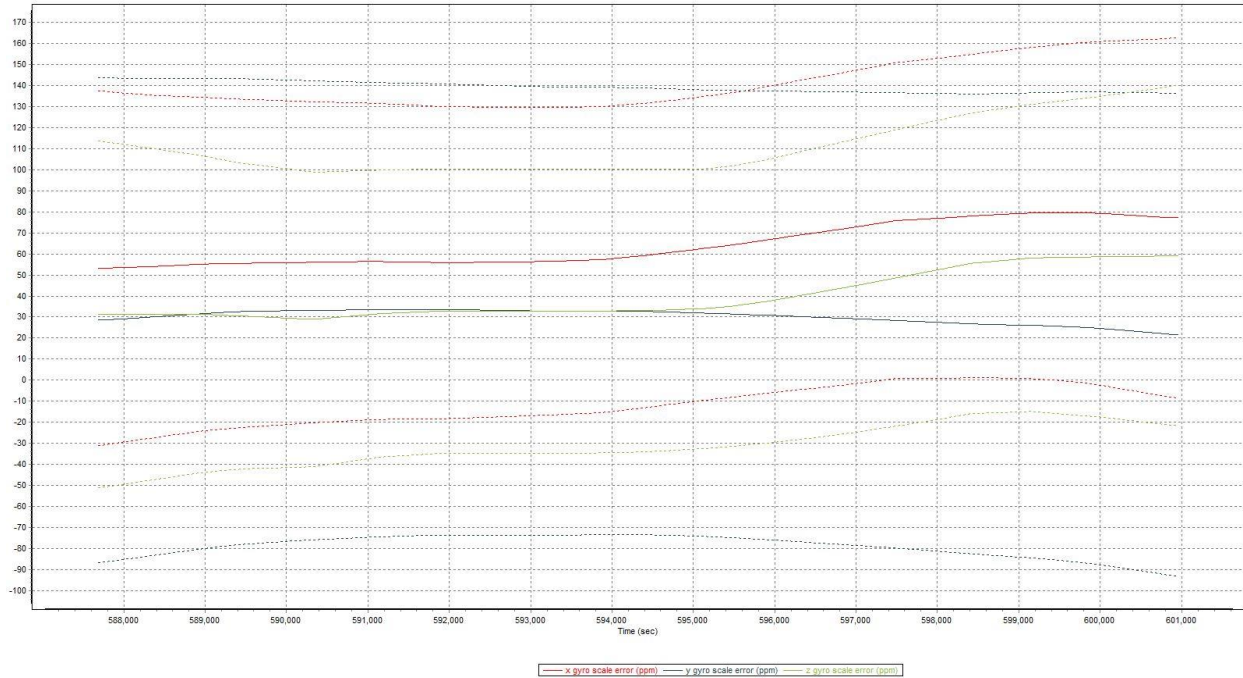




x accelerometer scale error (ppm) y accelerometer scale error (ppm) z accelerometer scale error (ppm)



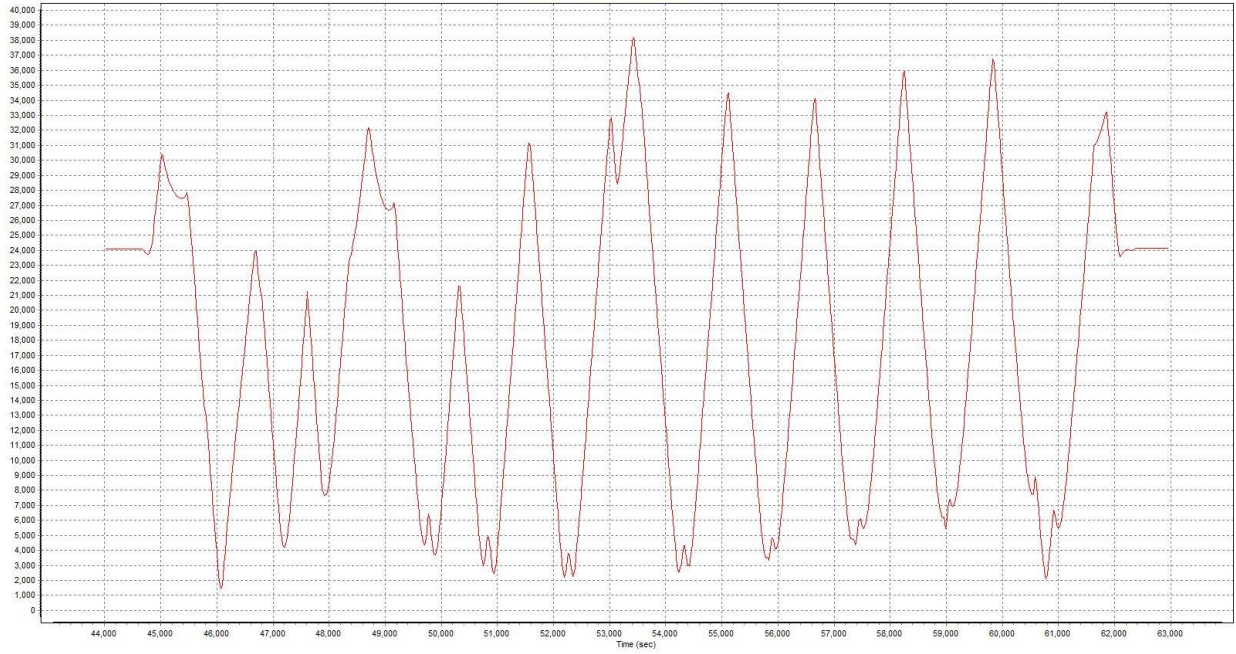
x gyro bias (deg/hr) y gyro bias (deg/hr) z gyro bias (deg/hr)



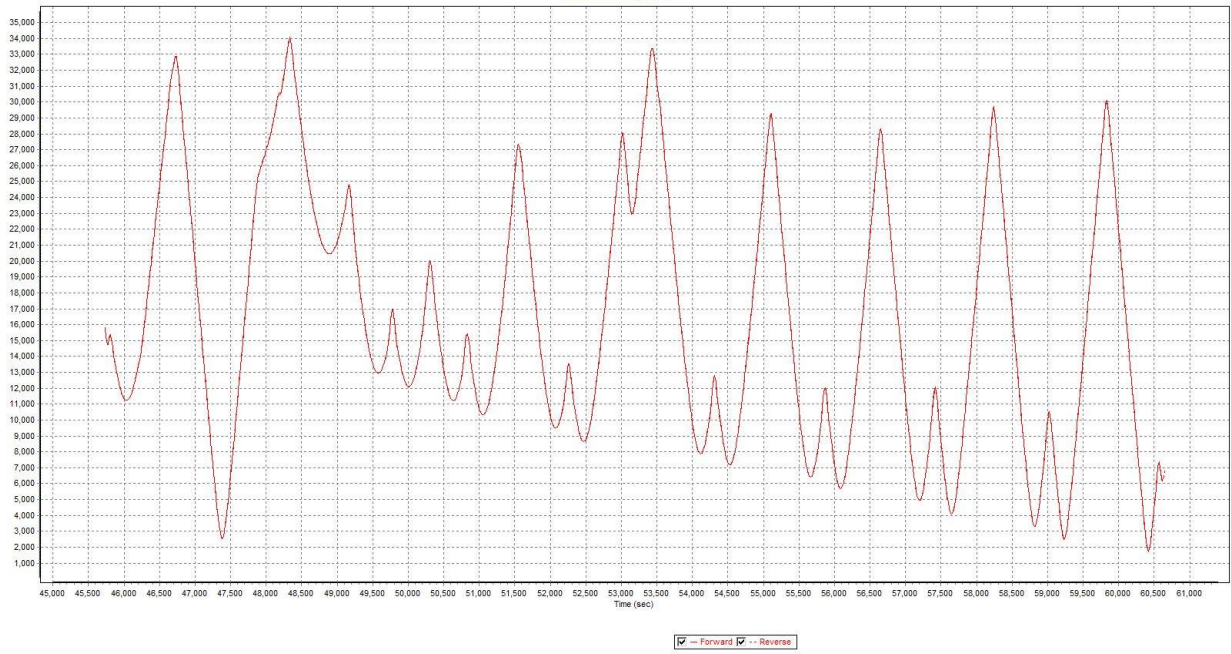


# UNB17099B

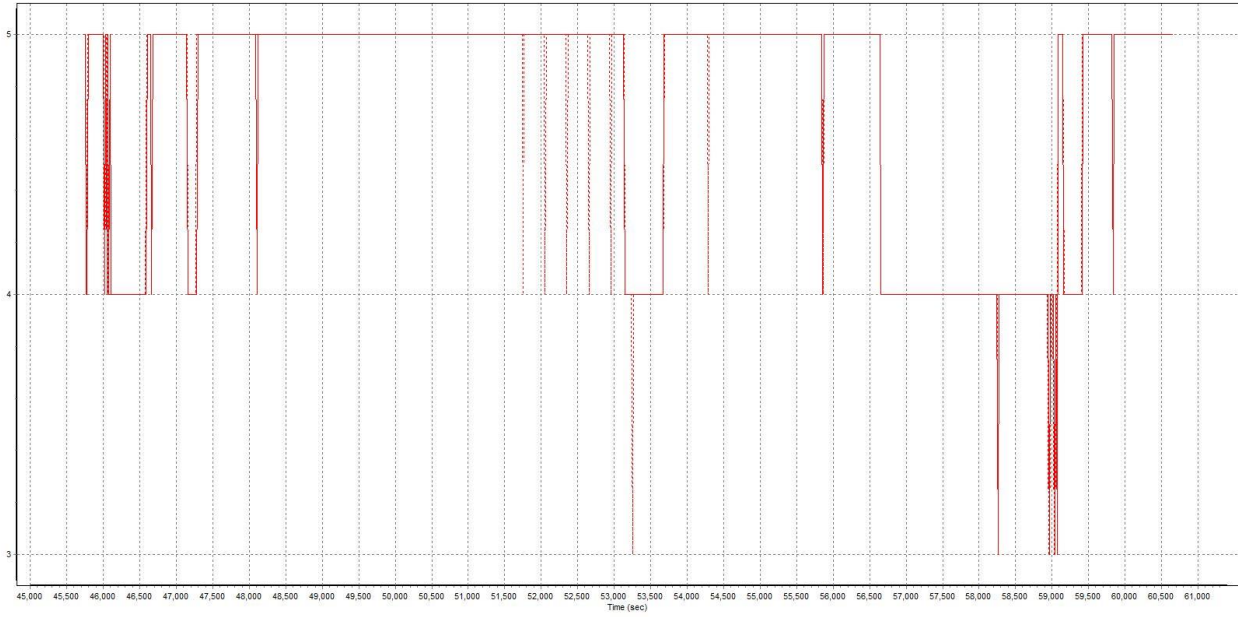
3D Distance to Closest GPS Station (m)



Baseline Length (m)

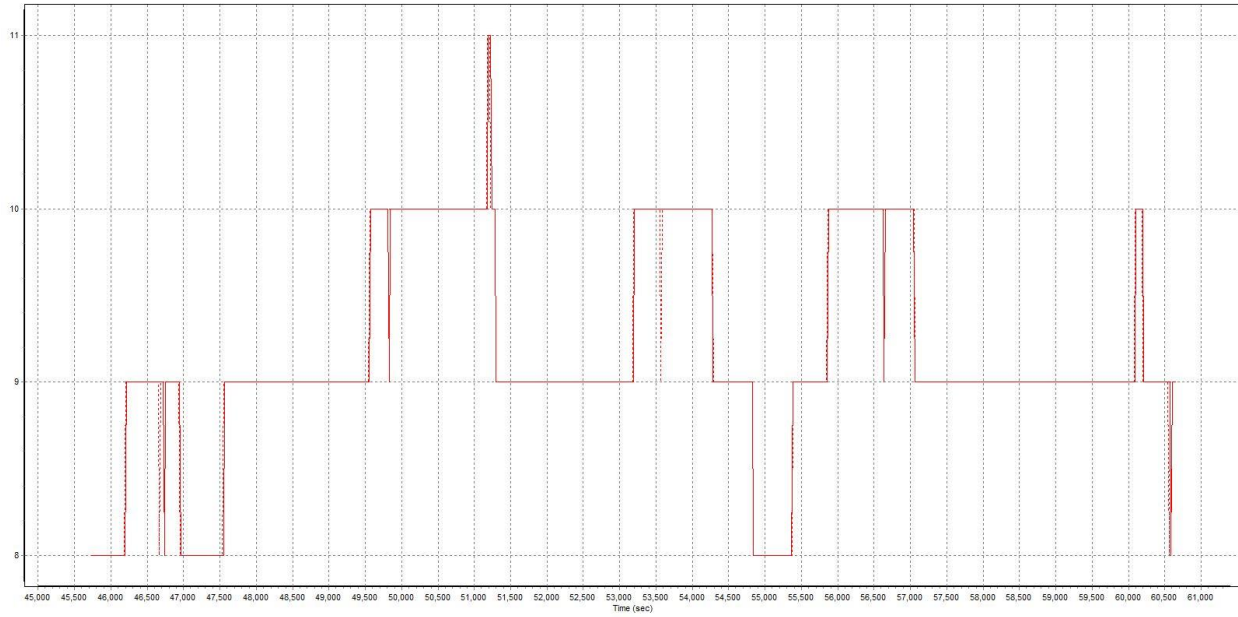


Number of GLONASS Satellites



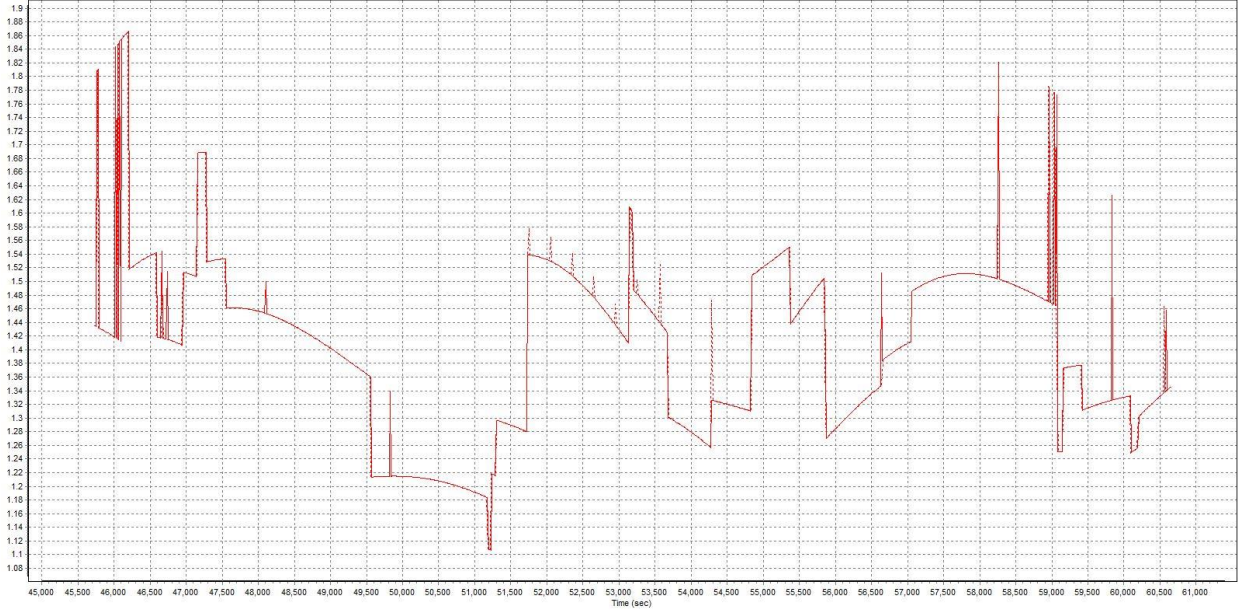
Forward  Reverse

Number of GPS Satellites



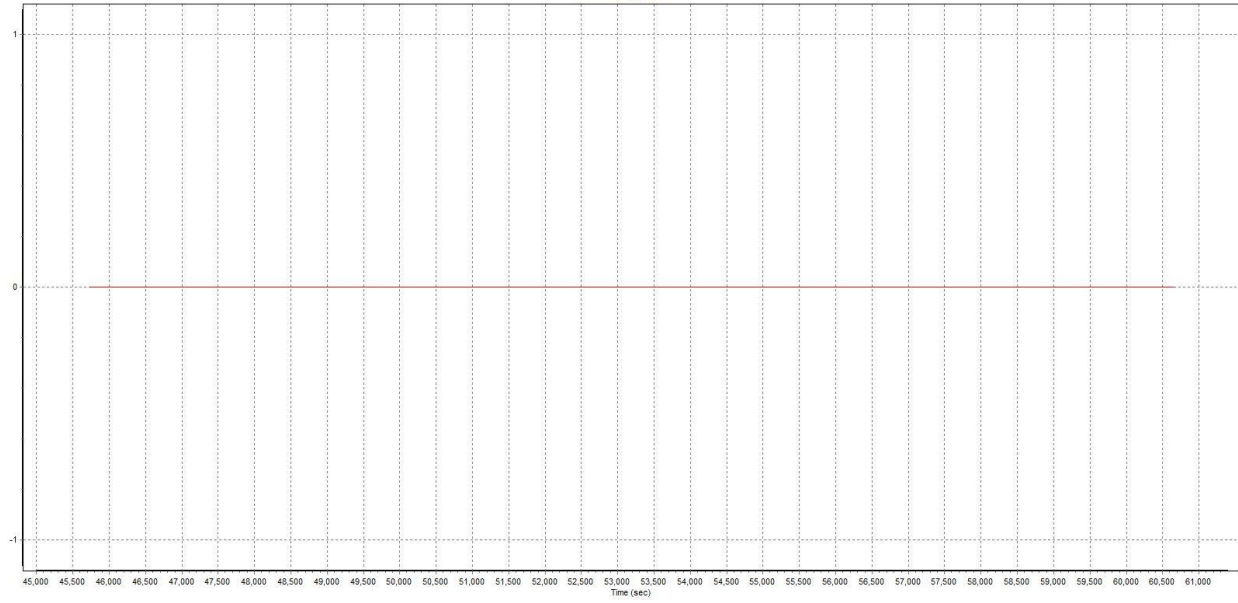
Forward  Reverse

PDOP



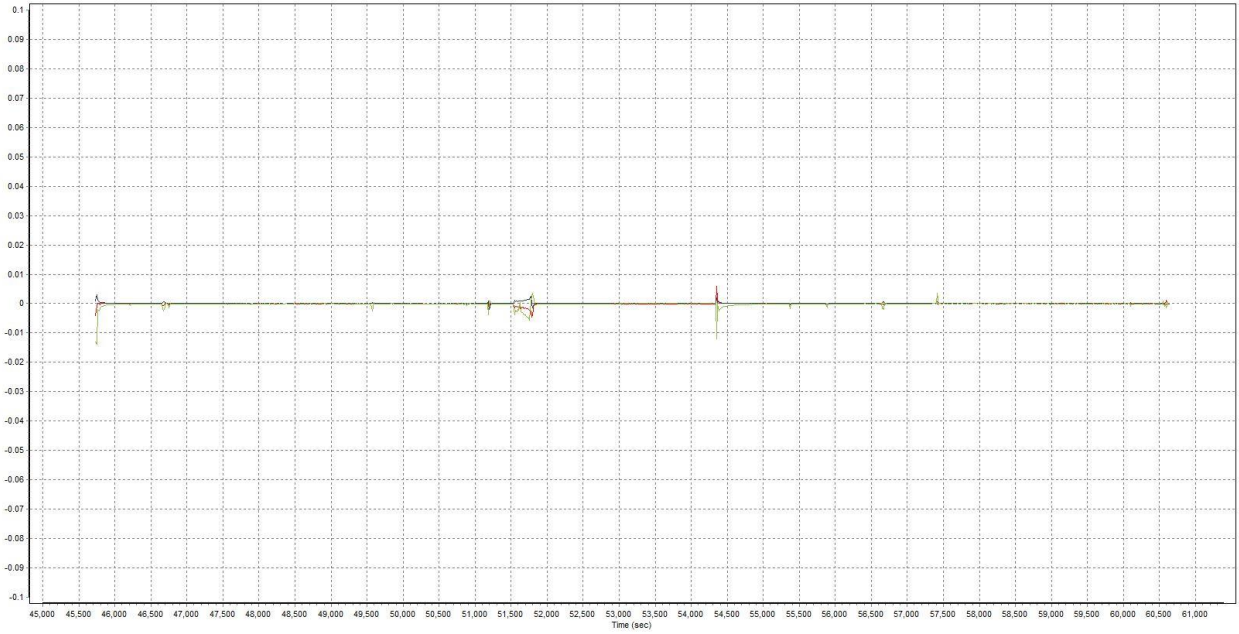
Forward  Reverse

Processing mode

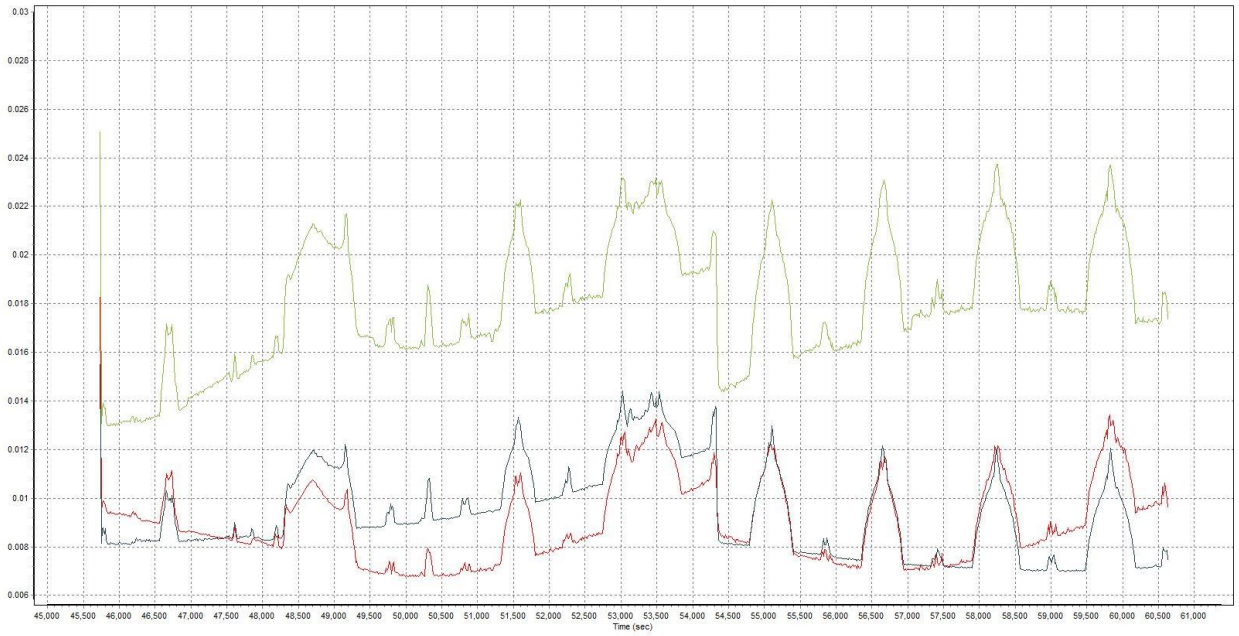


Forward  Reverse

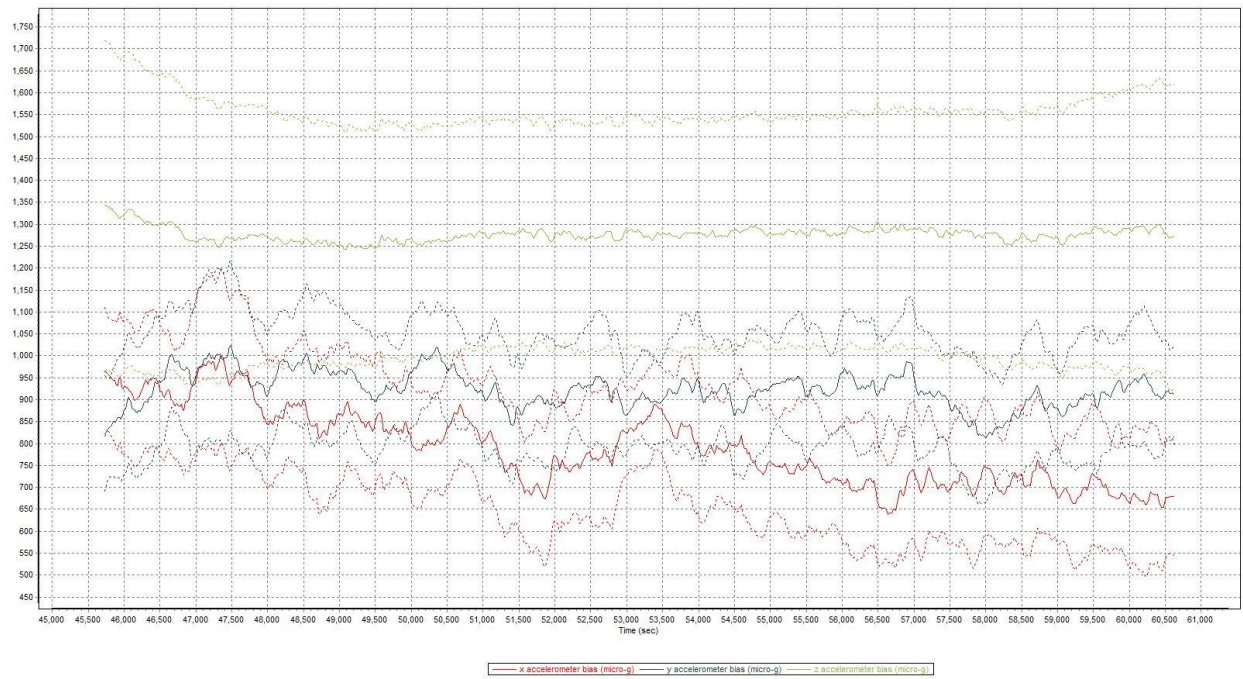
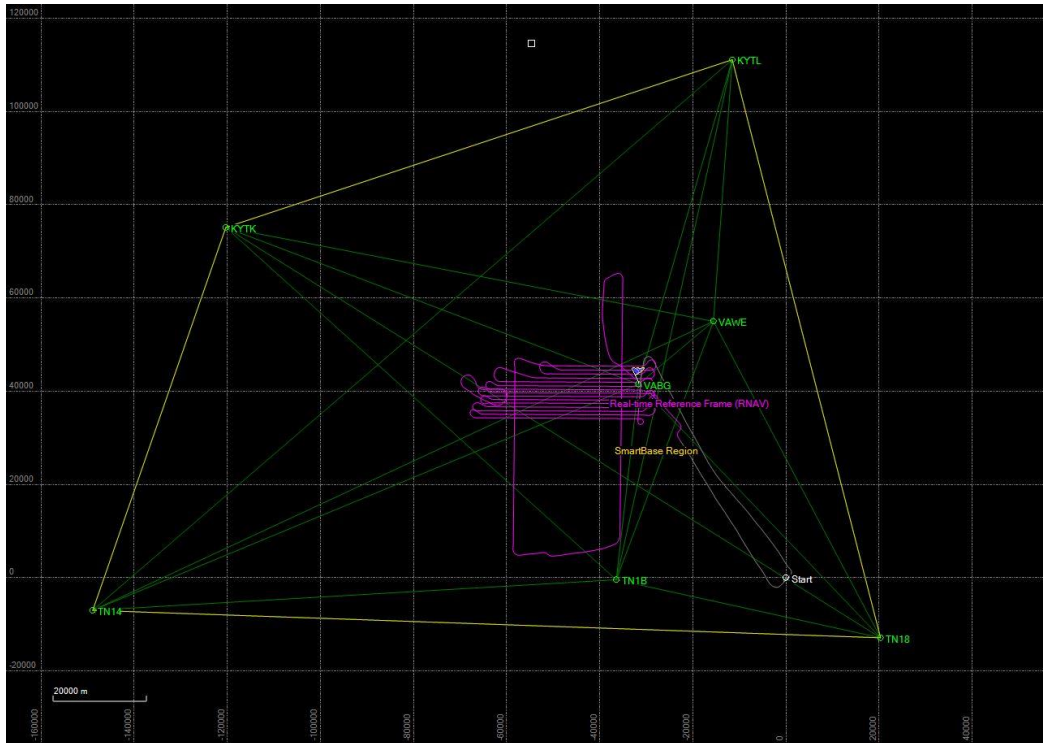
0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPR, 6 = CIA, 7 = GNSS Nav, 8 = DR

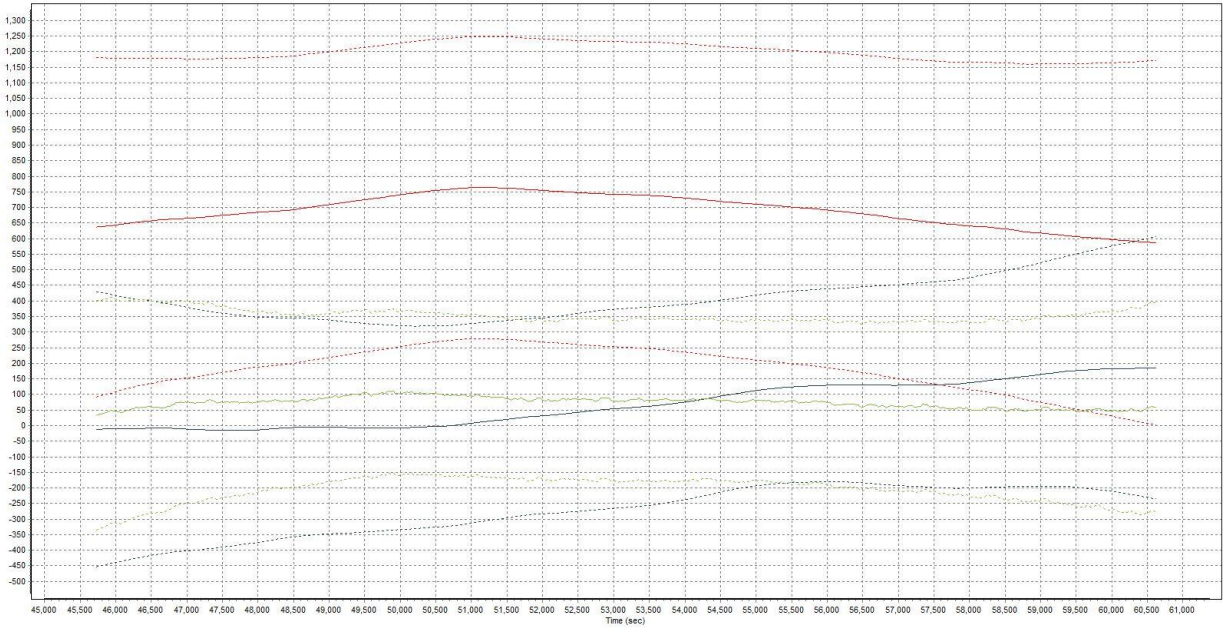


— North (m) — East (m) — Down (m) → DR mode

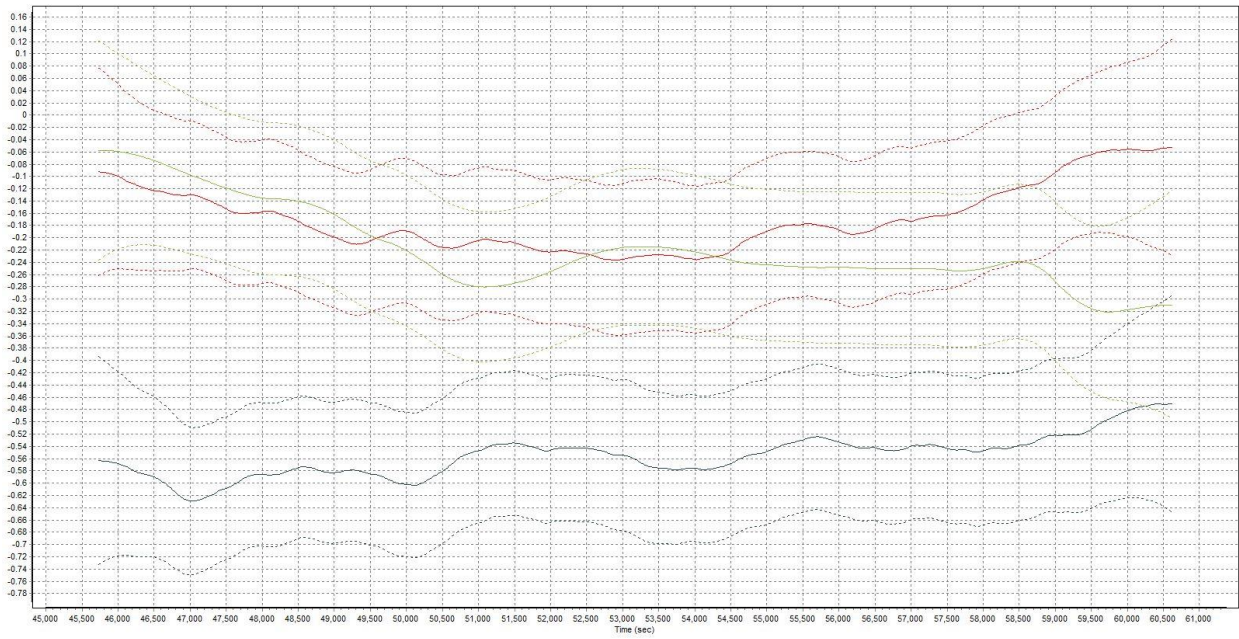


— North Position Error RMS (m) — East Position Error RMS (m) — Down Position Error RMS (m)

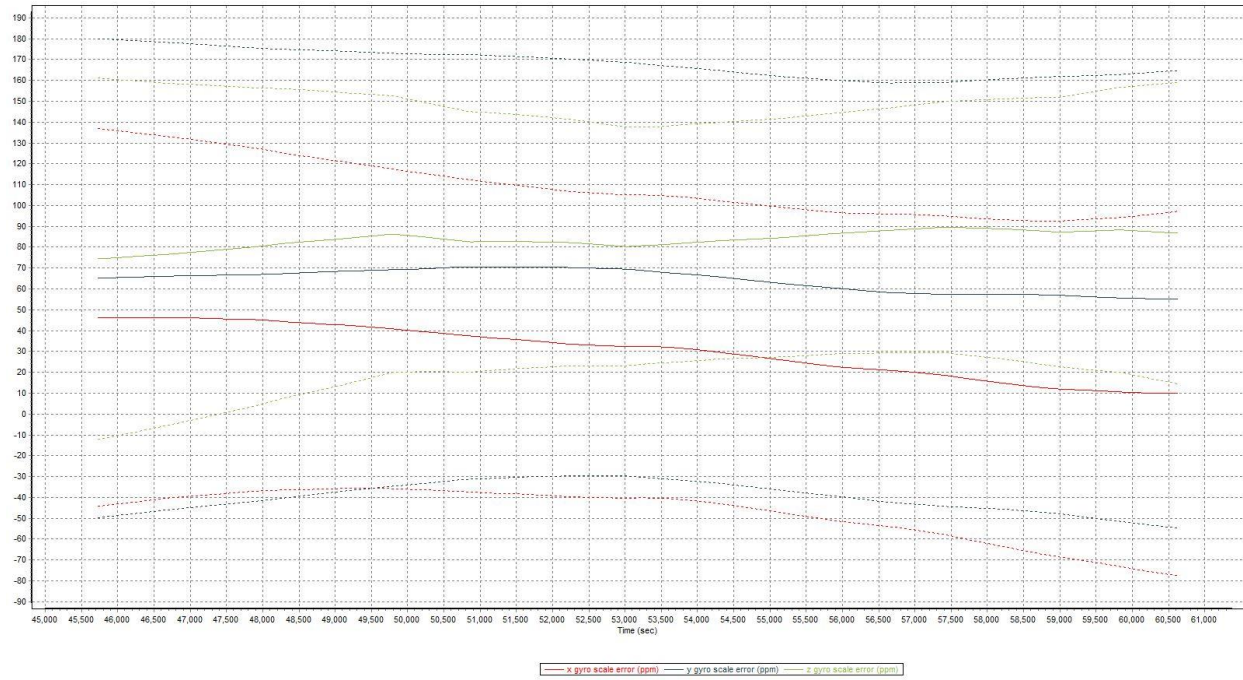




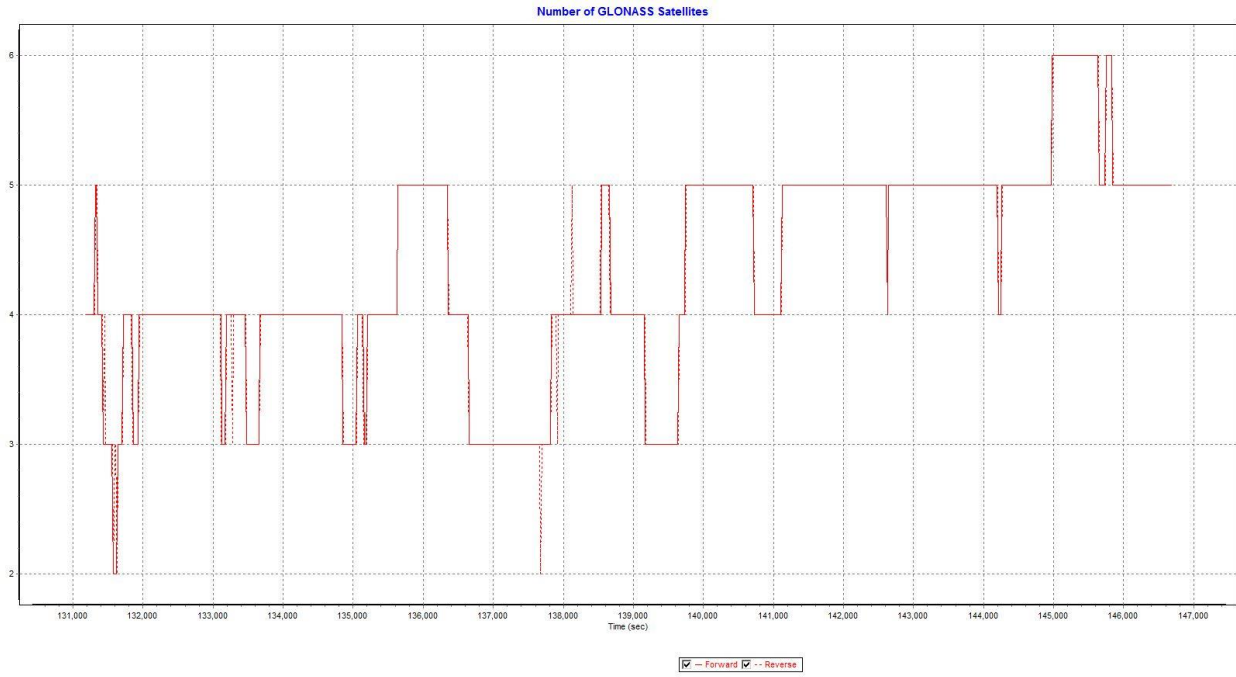
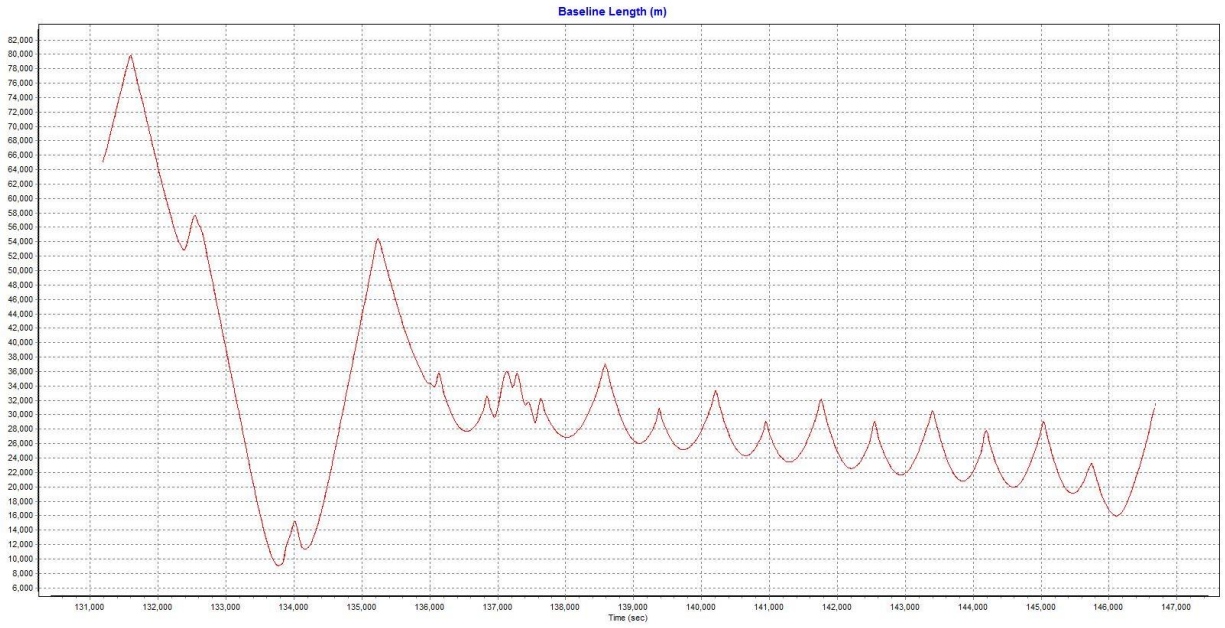
x accelerometer scale error (ppm) y accelerometer scale error (ppm) z accelerometer scale error (ppm)



x gyro bias (deg/hr) y gyro bias (deg/hr) z gyro bias (deg/hr)

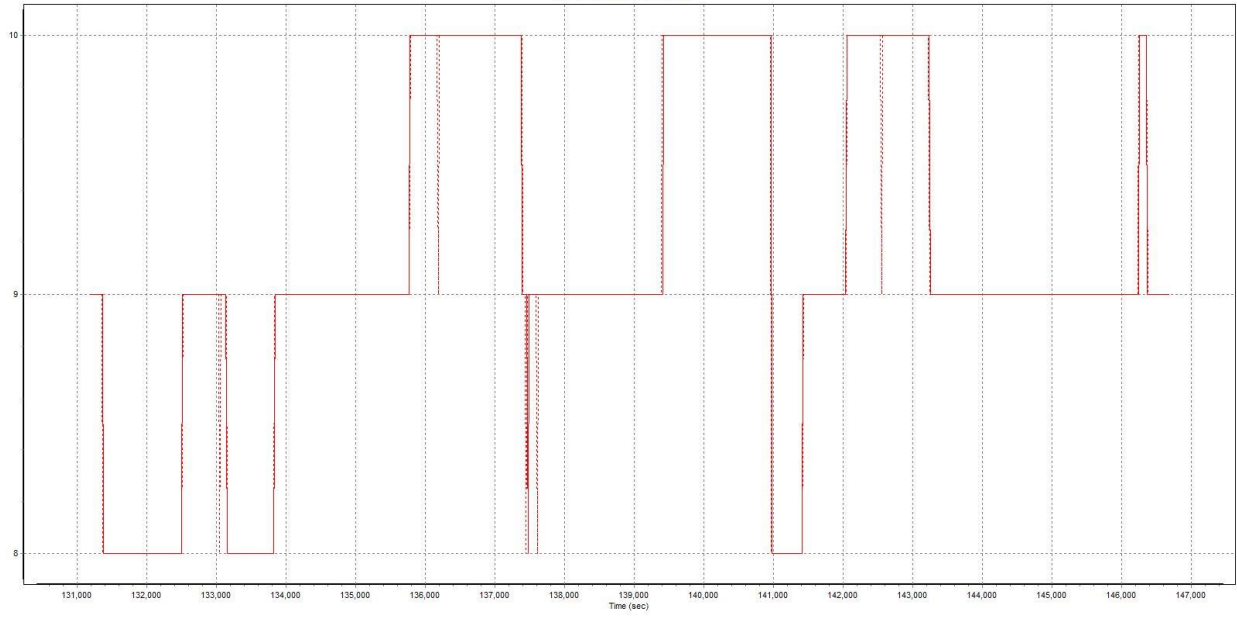


# UNB17100A



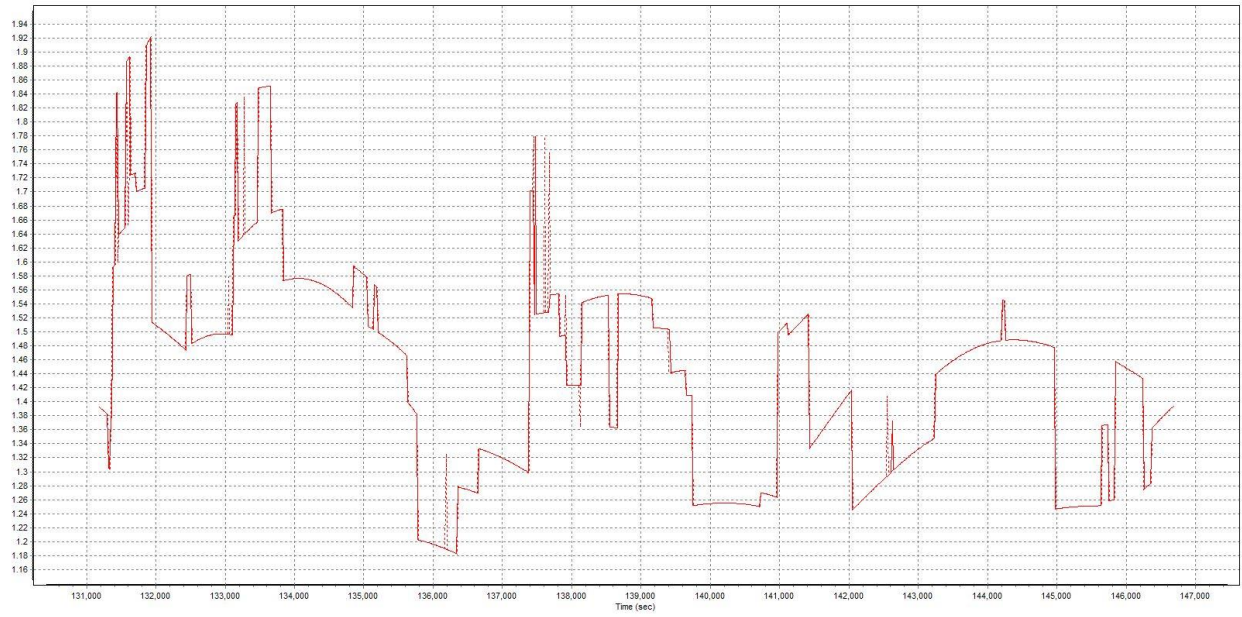


Number of GPS Satellites



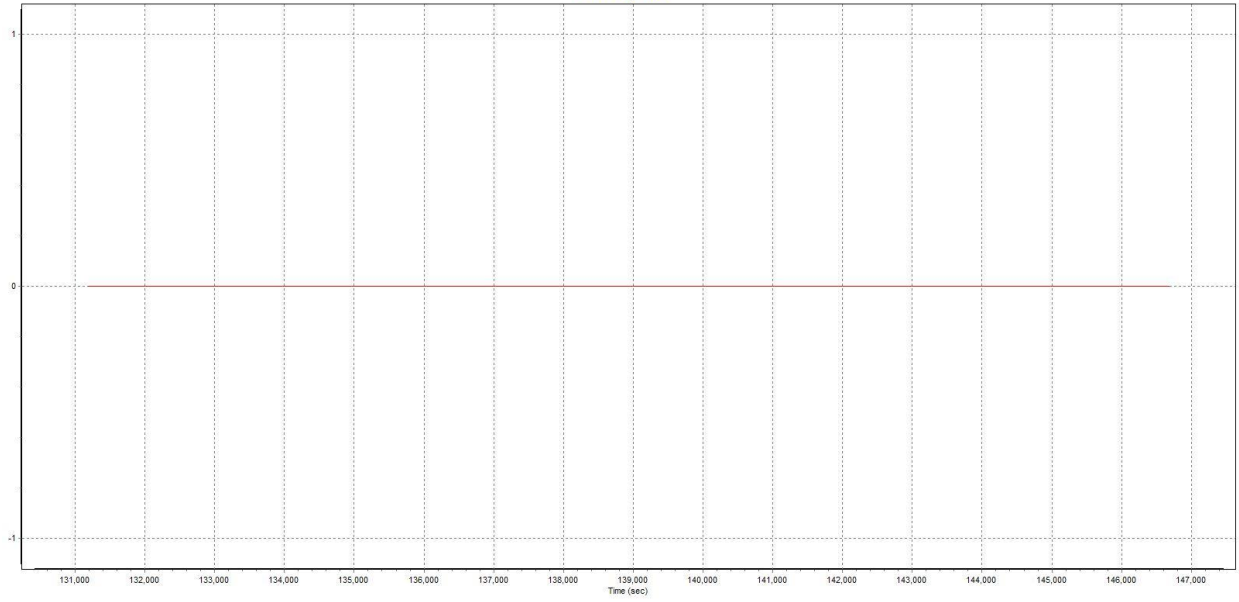
Forward  Reverse

PDOP



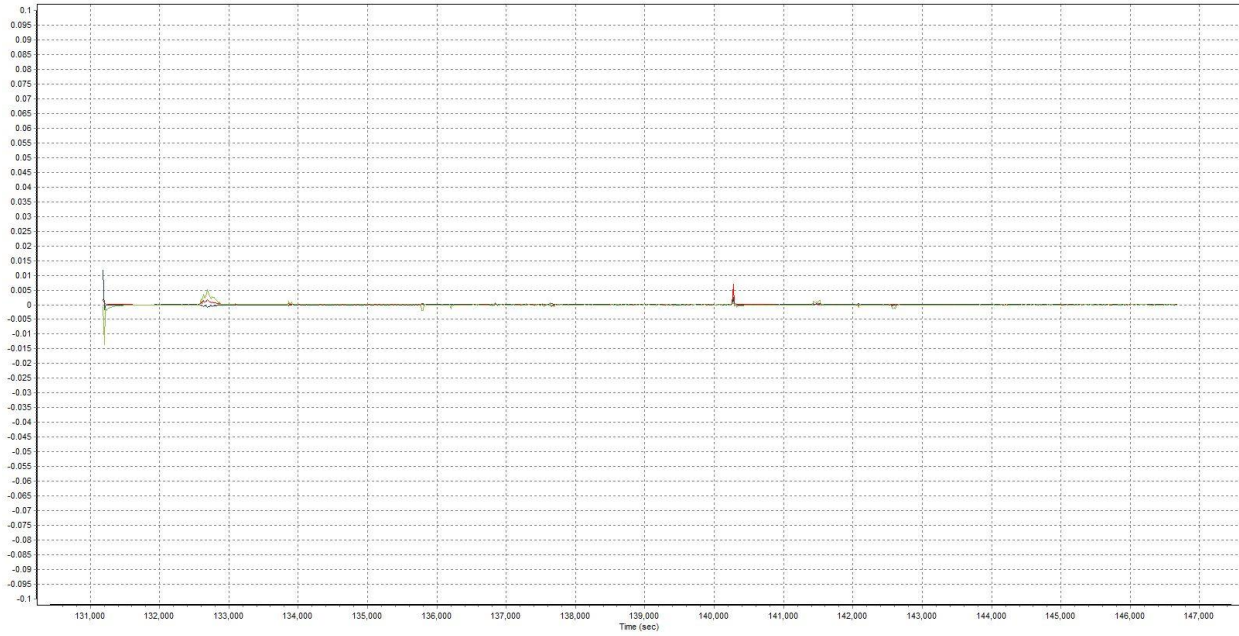
Forward  Reverse

Processing mode

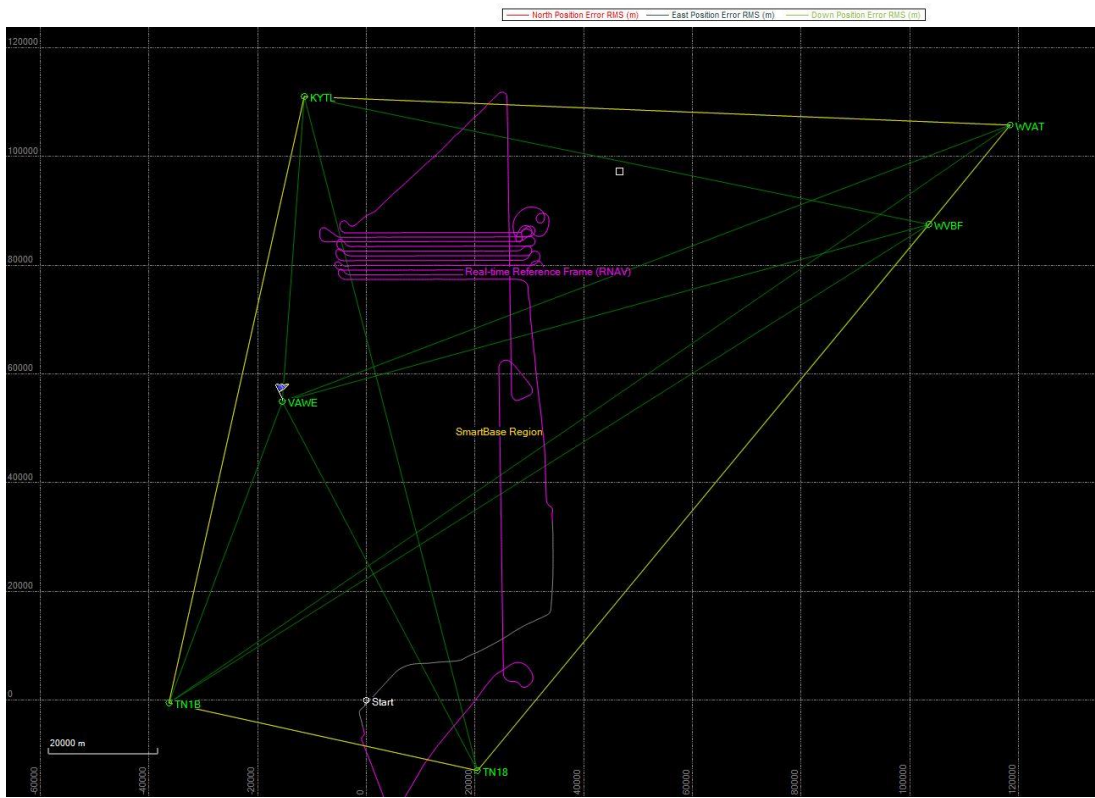
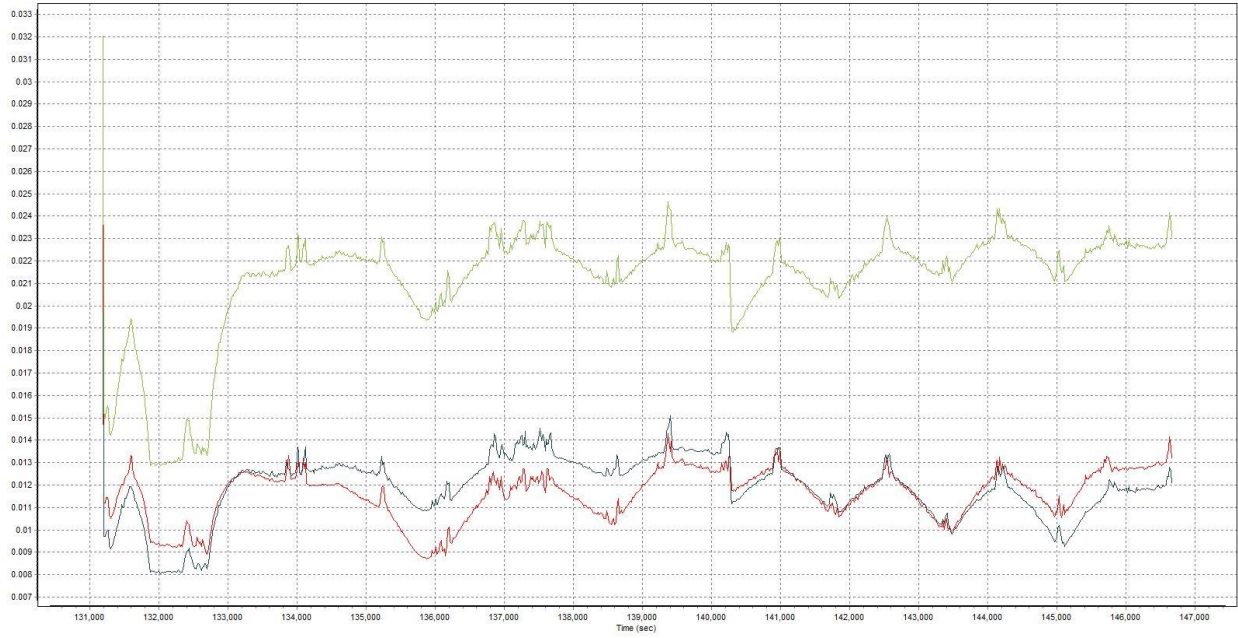


0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = CIA, 7 = GNSS Nav, 8 = DR

Forward  Reverse

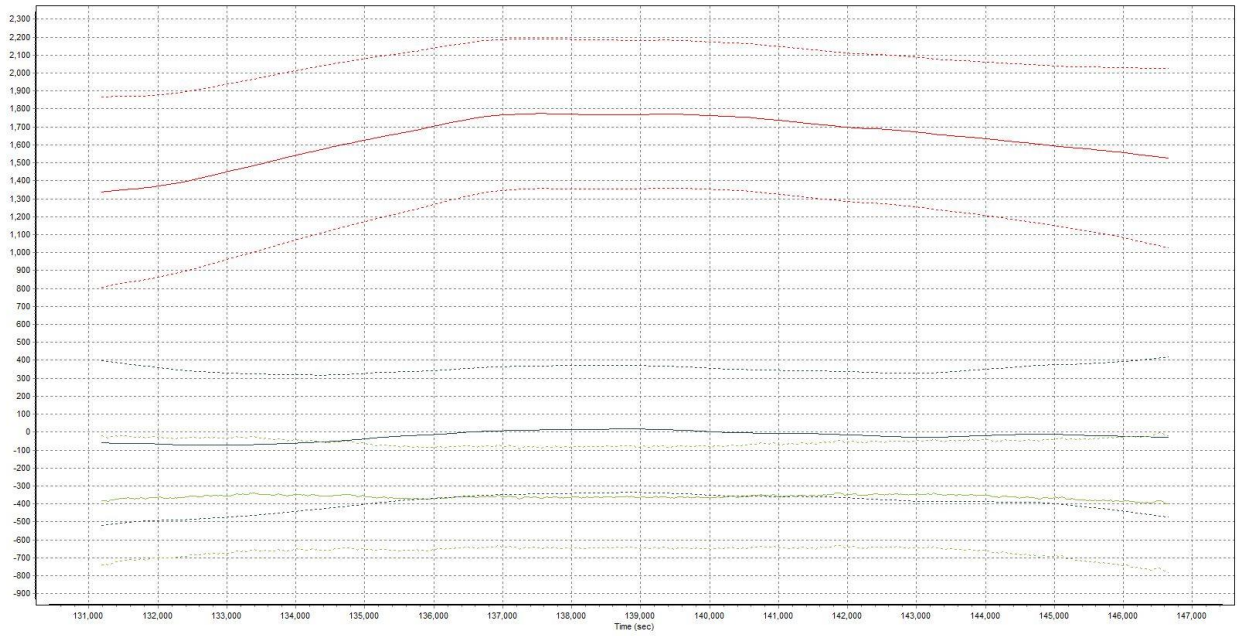


— North (m) — East (m) — Down (m) — DR mode

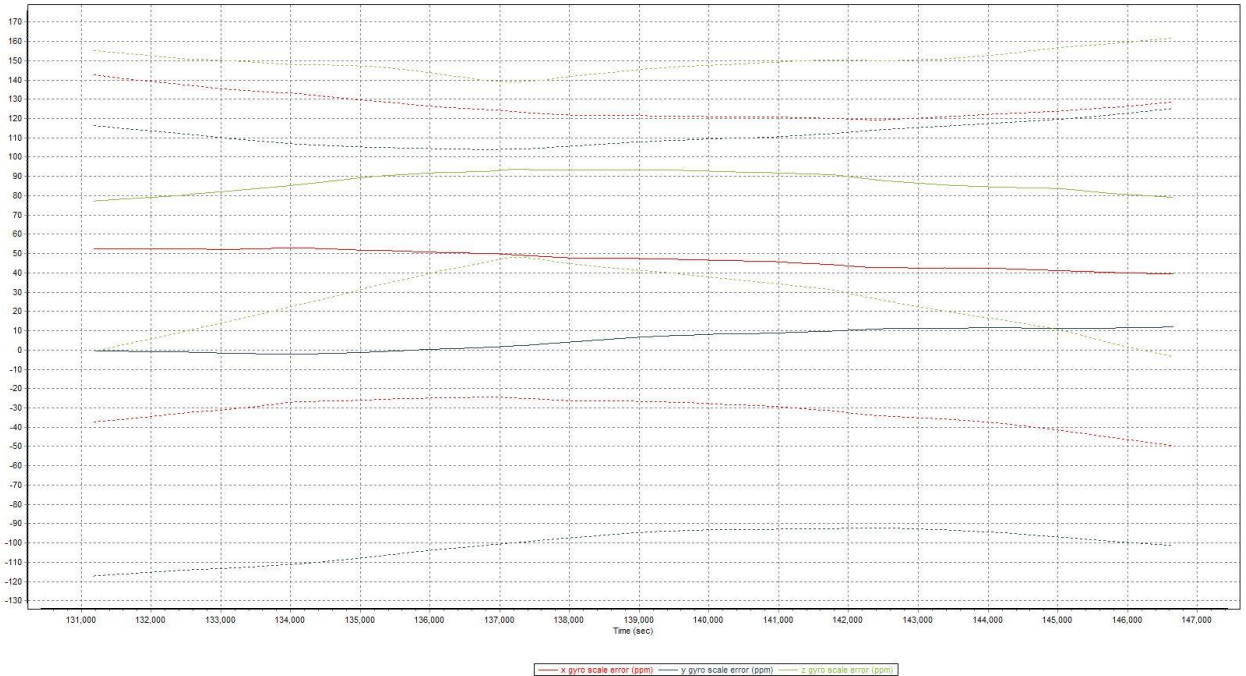
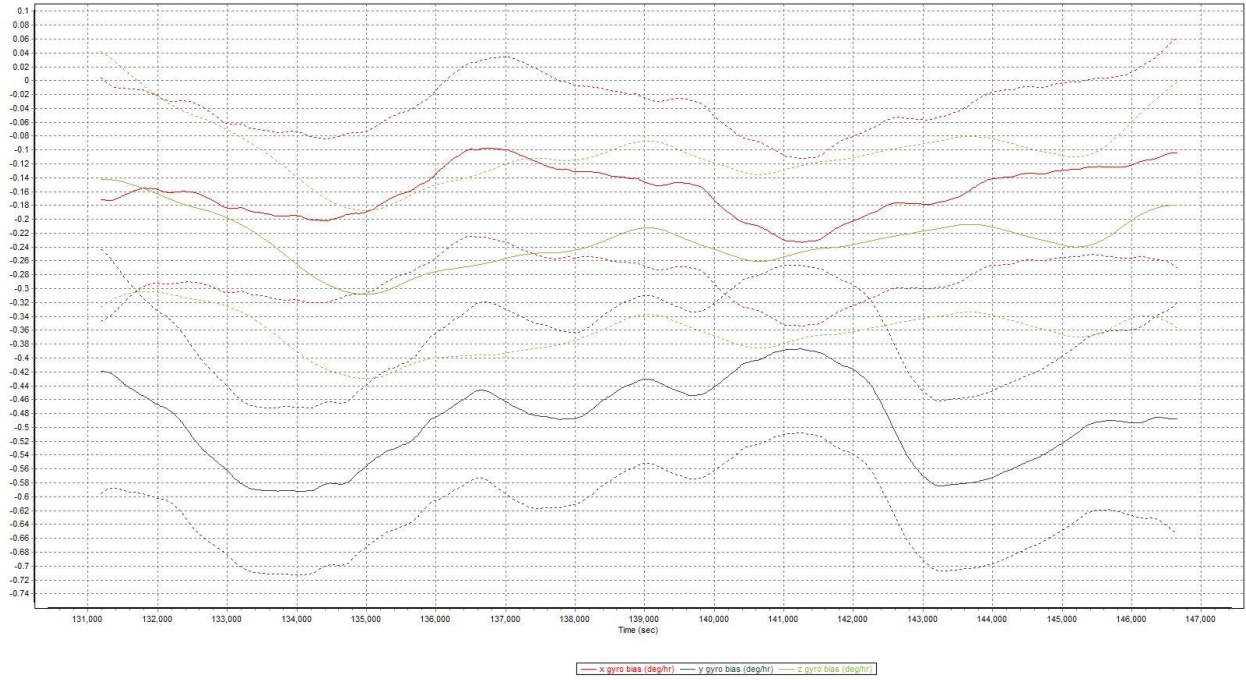




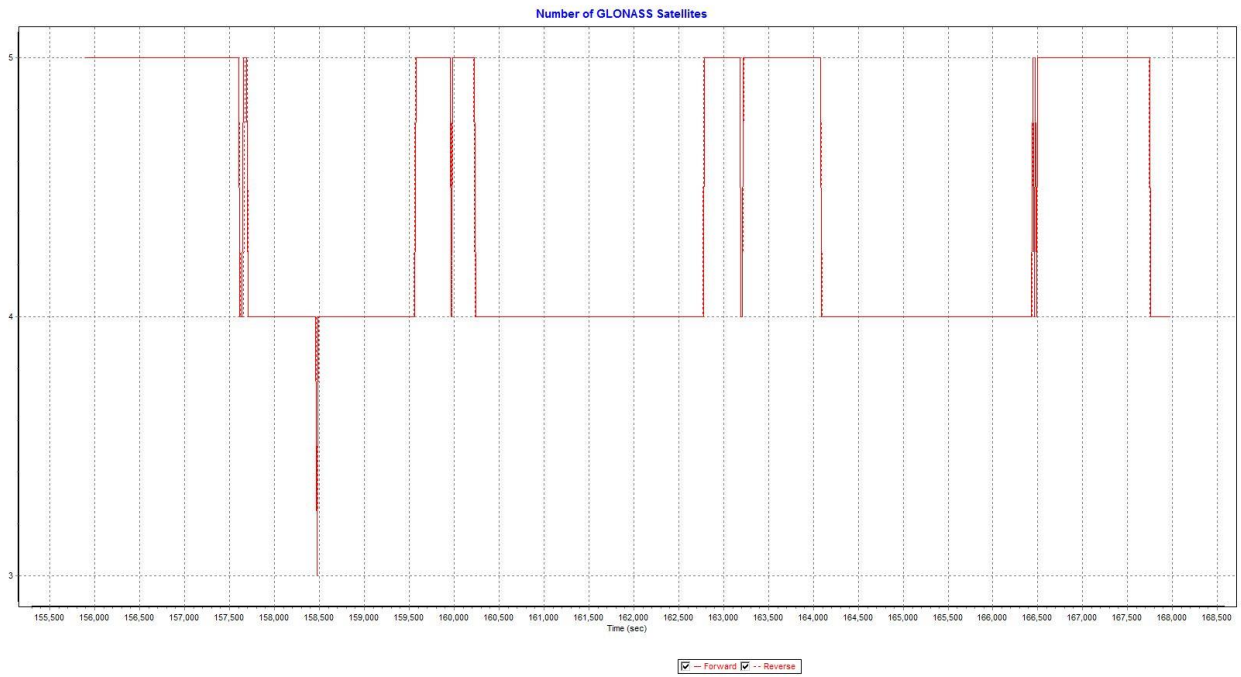
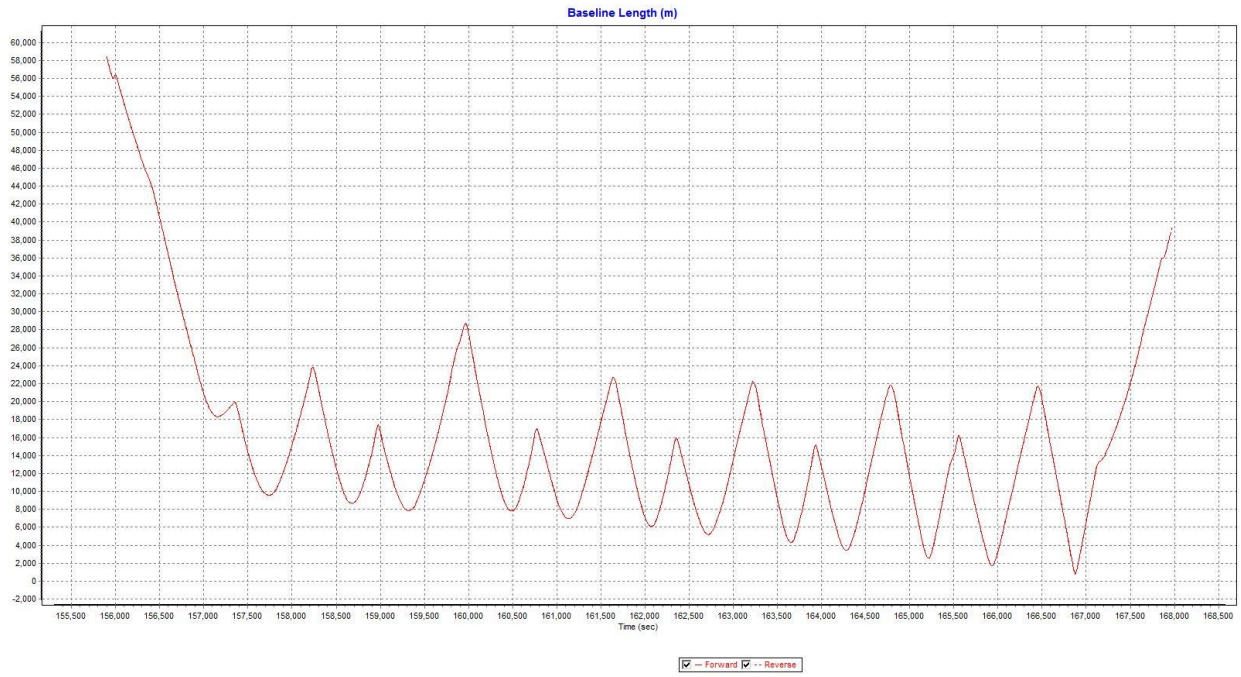
— x accelerometer bias (micro-g) — y accelerometer bias (micro-g) — z accelerometer bias (micro-g)



— x accelerometer scale error (ppm) — y accelerometer scale error (ppm) — z accelerometer scale error (ppm)

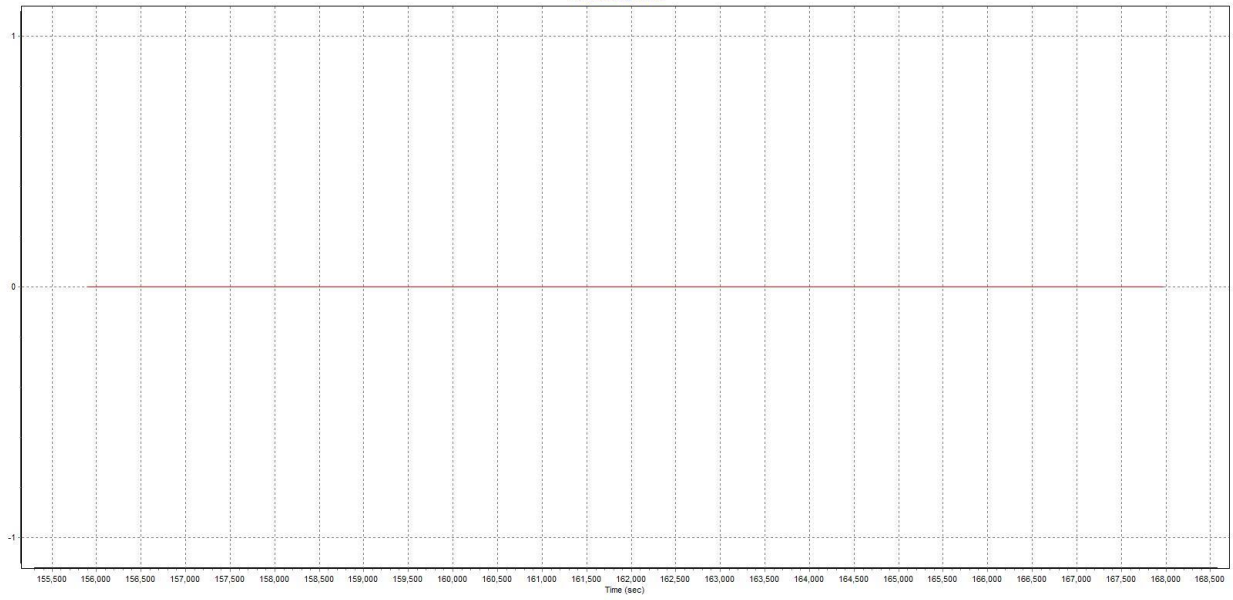


# UNB17100B



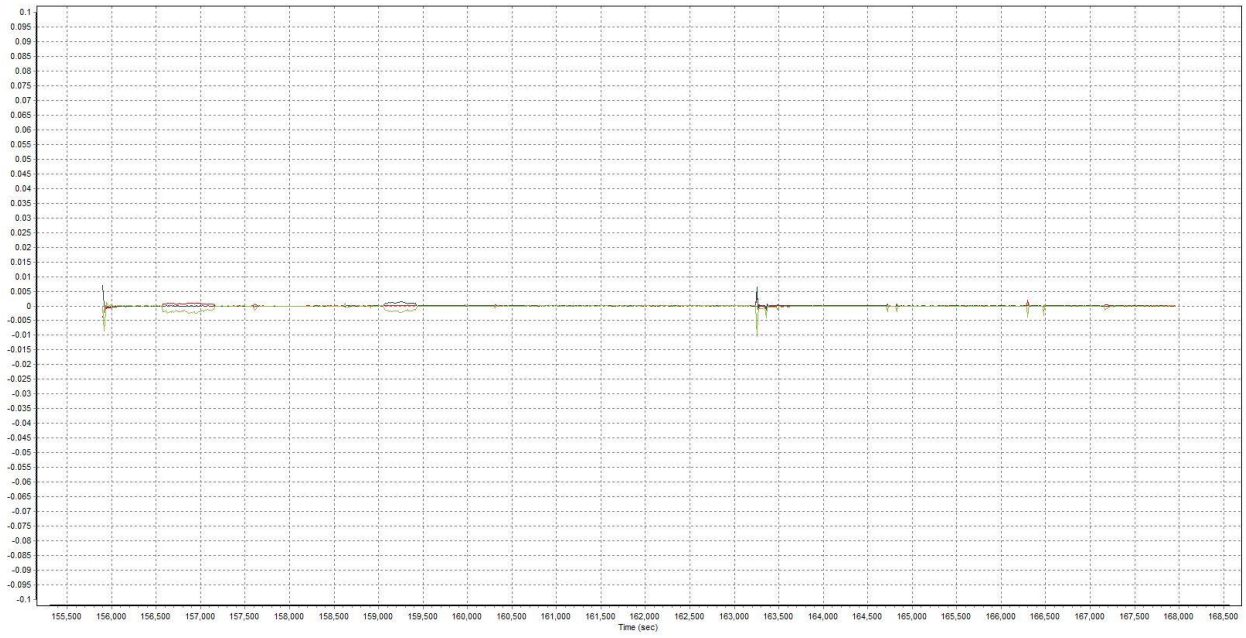


Processing mode



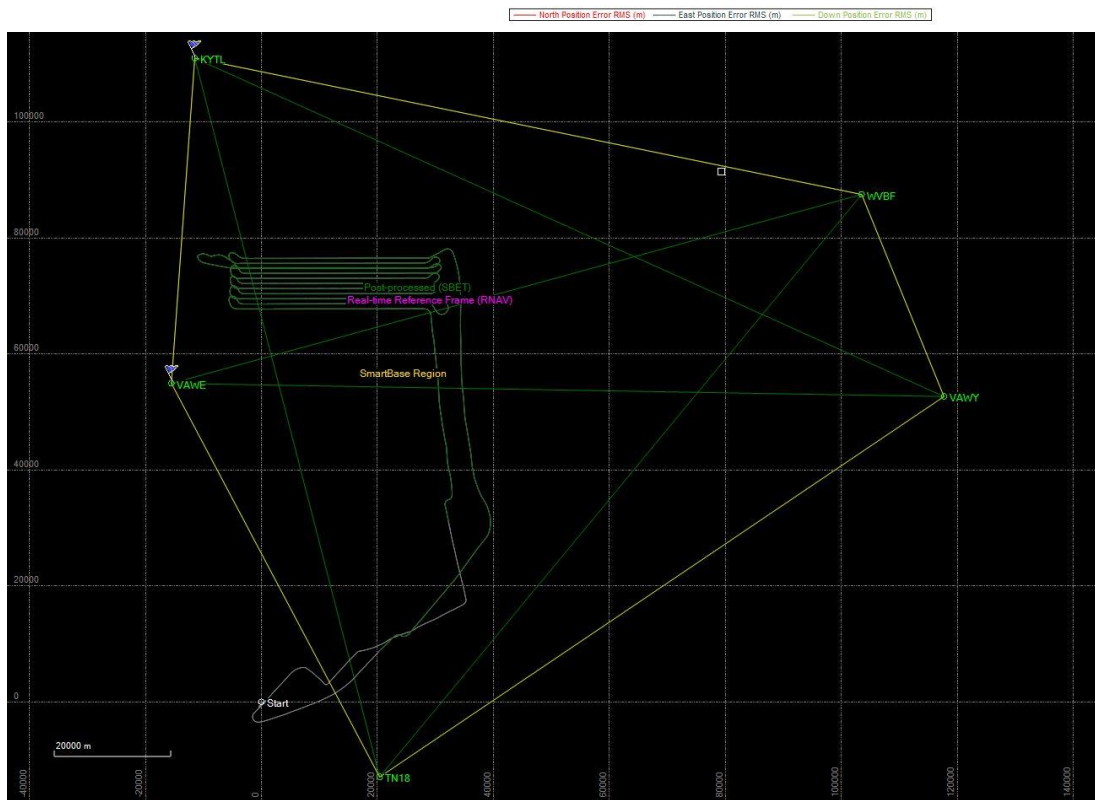
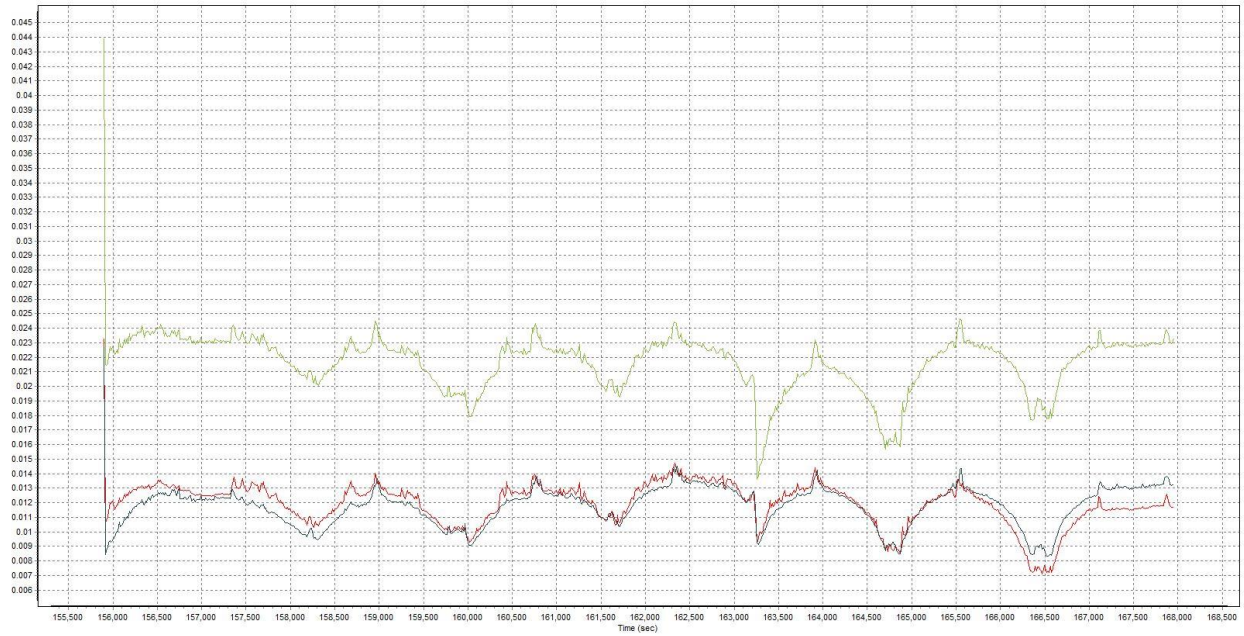
Forward  Reverse

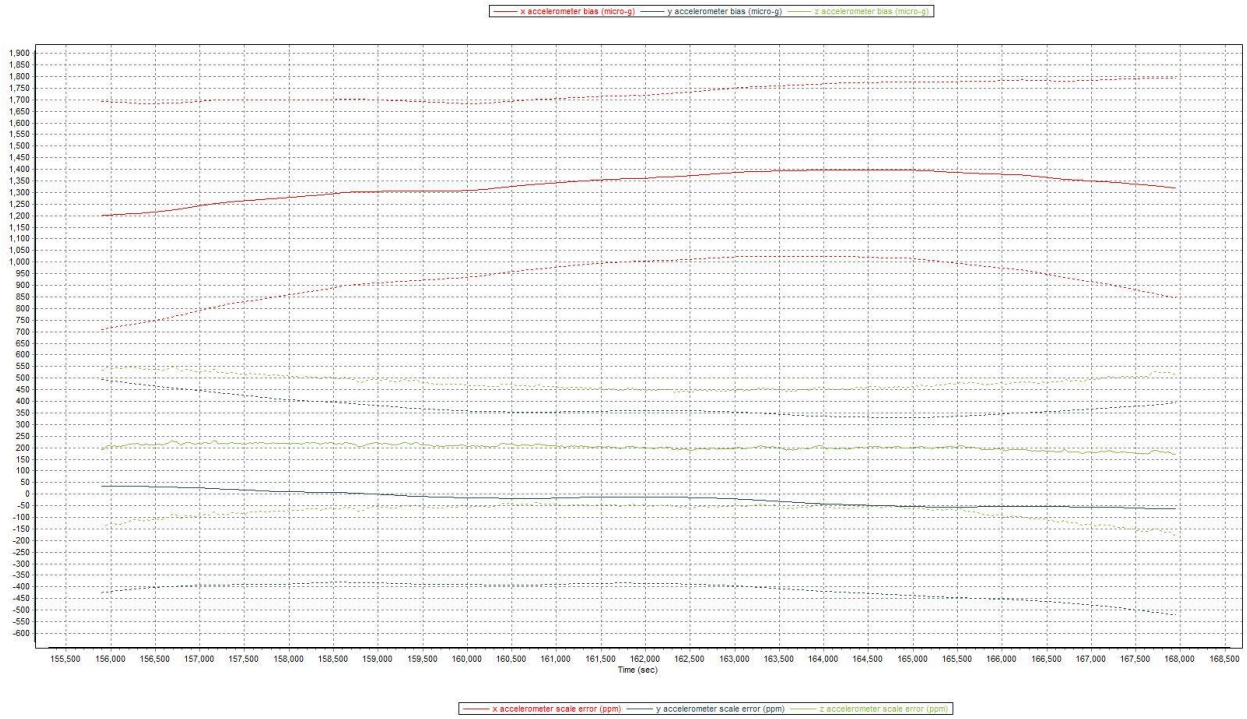
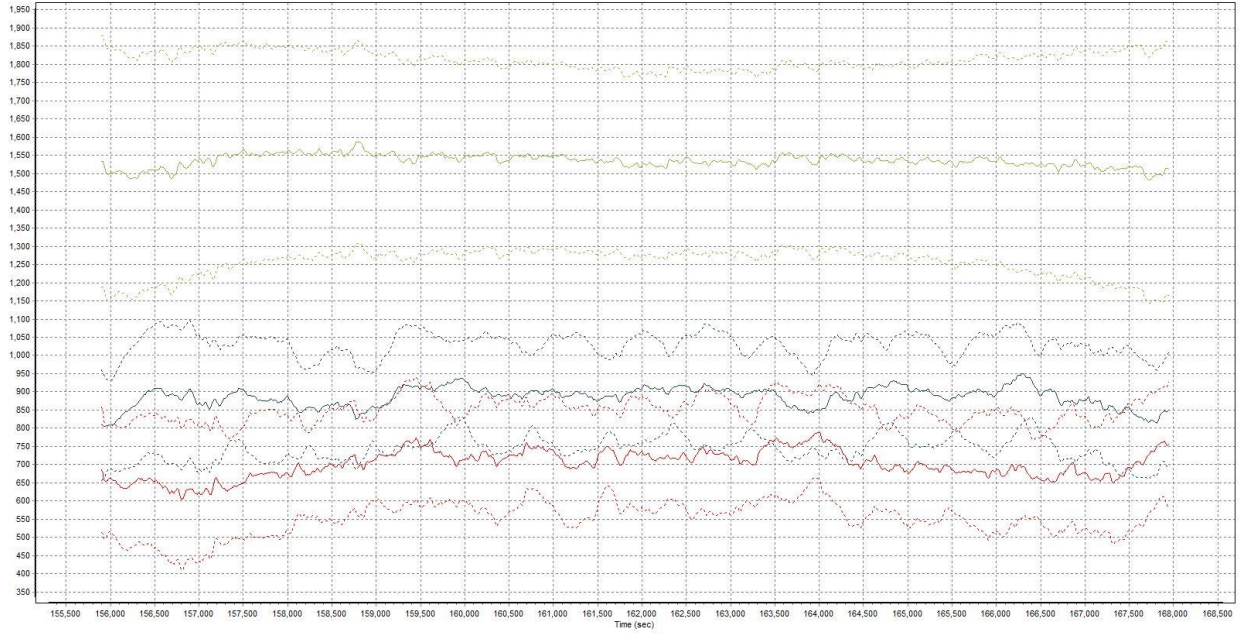
0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = CIA, 7 = GNSS Nav, 8 = DR

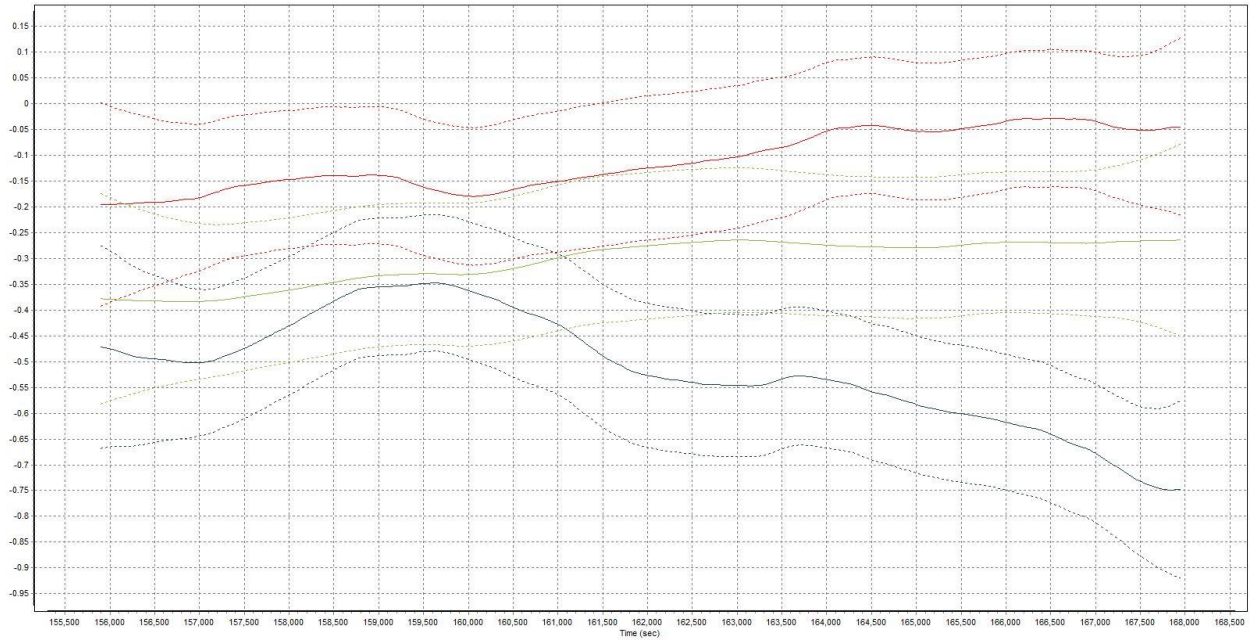


North (m) East (m) Down (m) DR mode

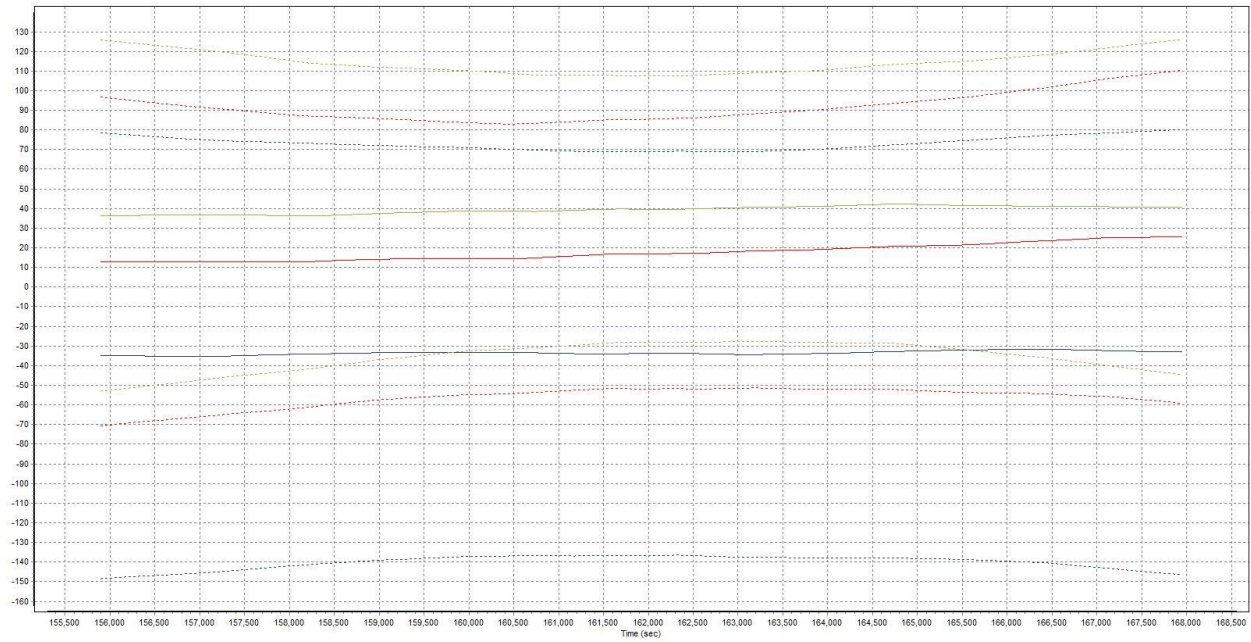








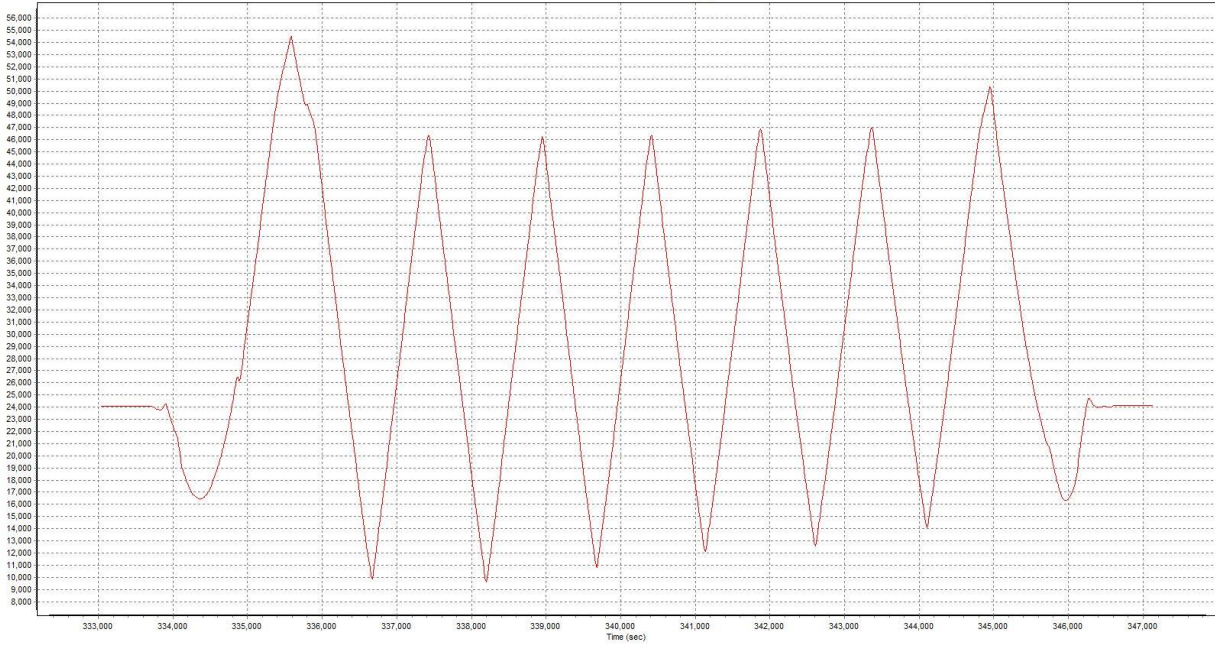
x gyro bias (deg/hr) y gyro bias (deg/hr) z gyro bias (deg/hr)



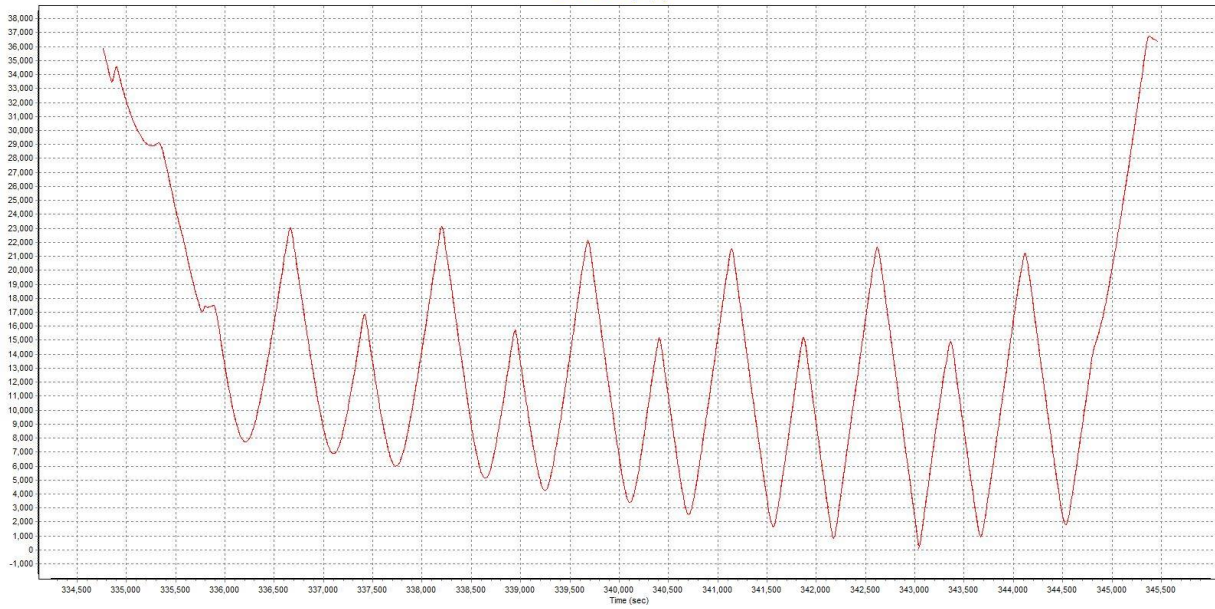
x gyro scale error (ppm) y gyro scale error (ppm) z gyro scale error (ppm)

# UNB17102A

3D Distance to Closest GPS Station (m)

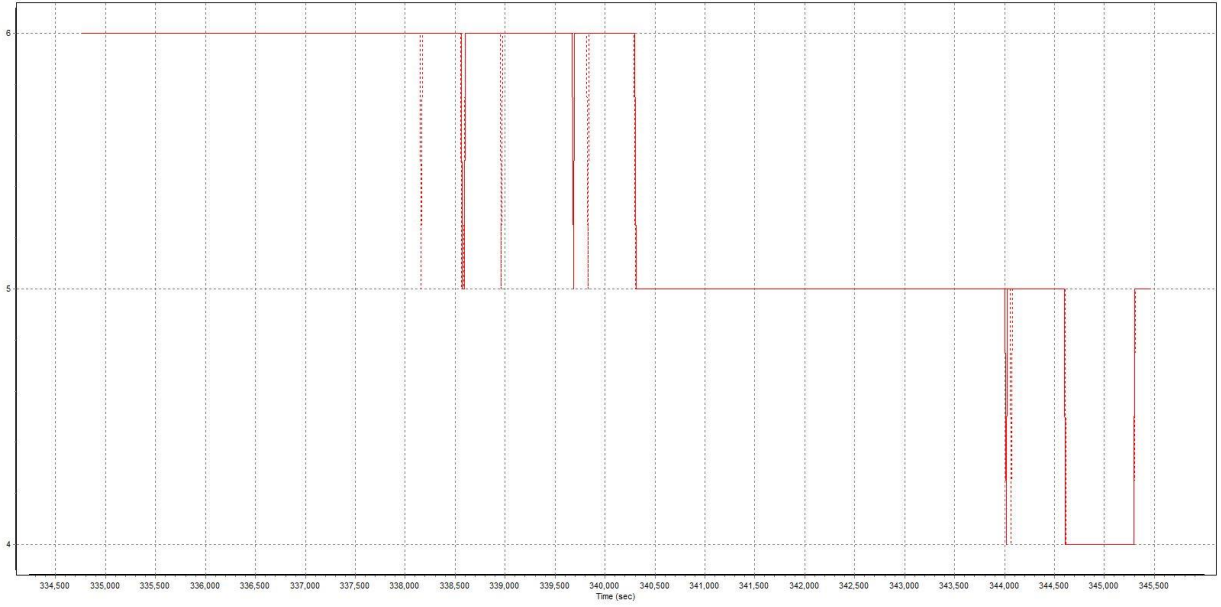


Baseline Length (m)



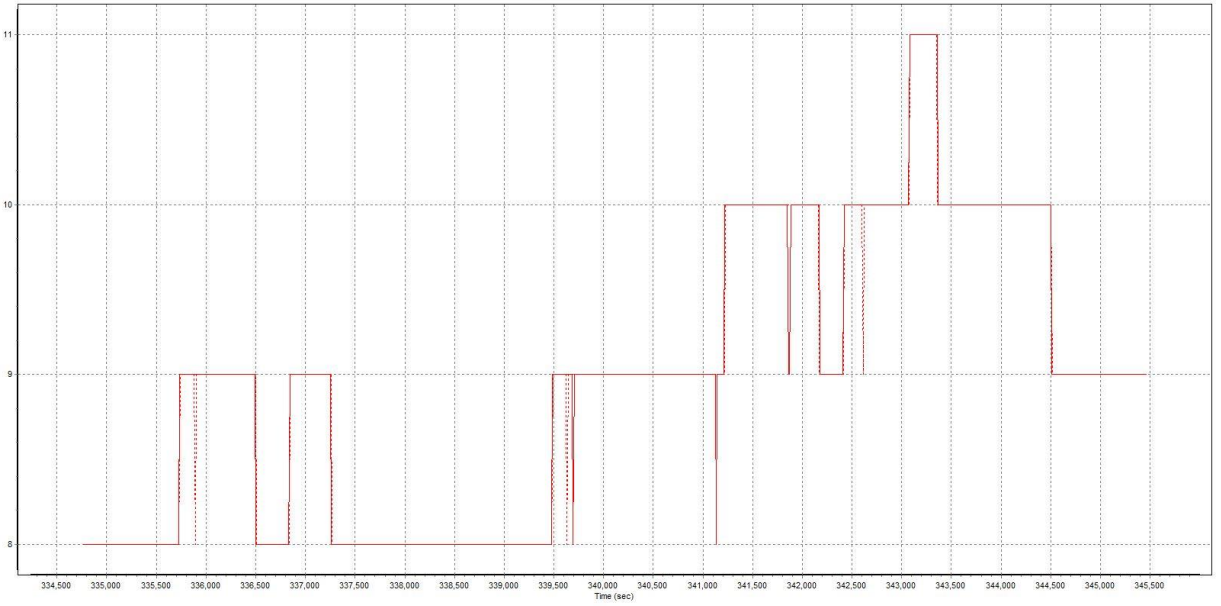
Forward  Reverse

Number of GLONASS Satellites



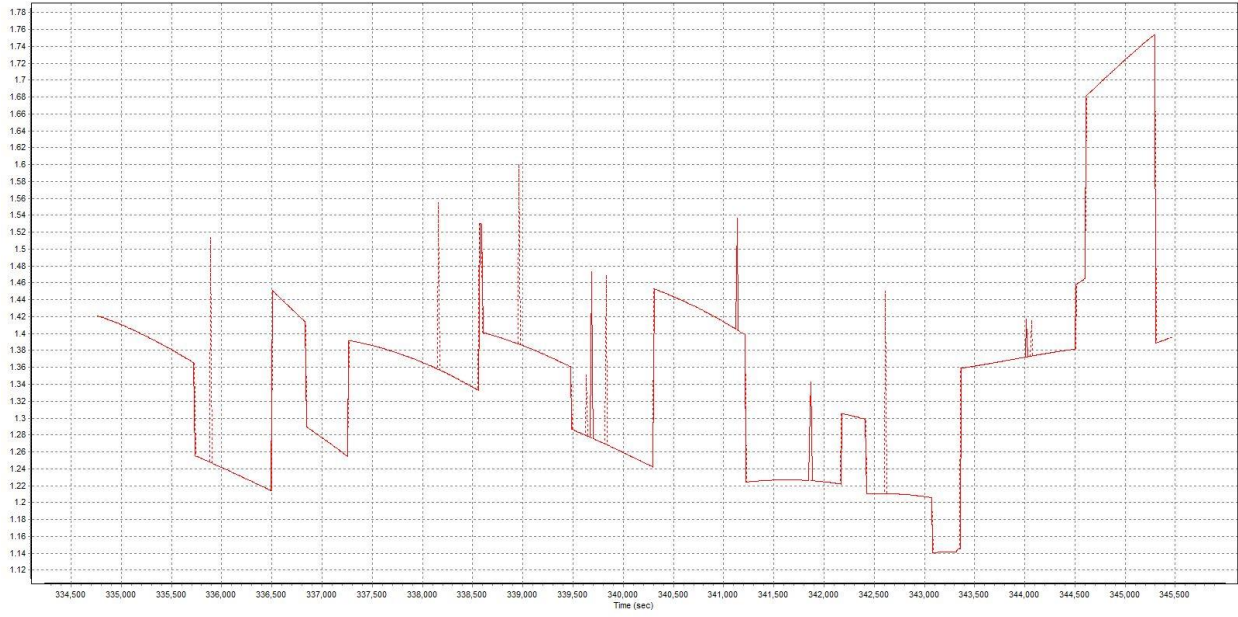
Forward  Reverse

Number of GPS Satellites



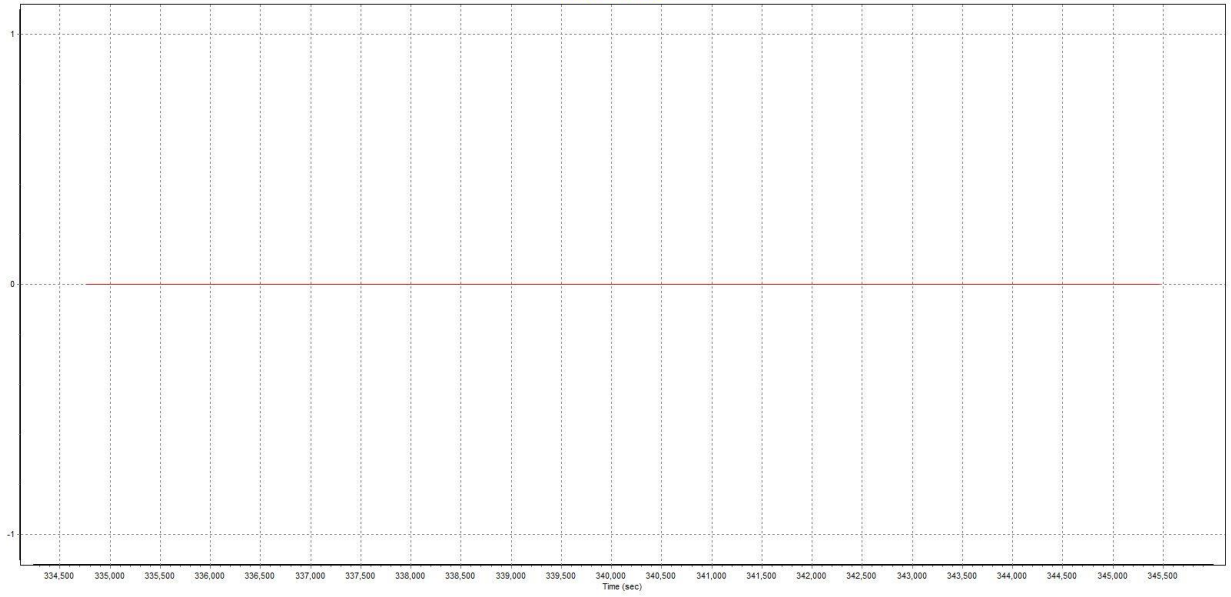
Forward  Reverse

PDOP



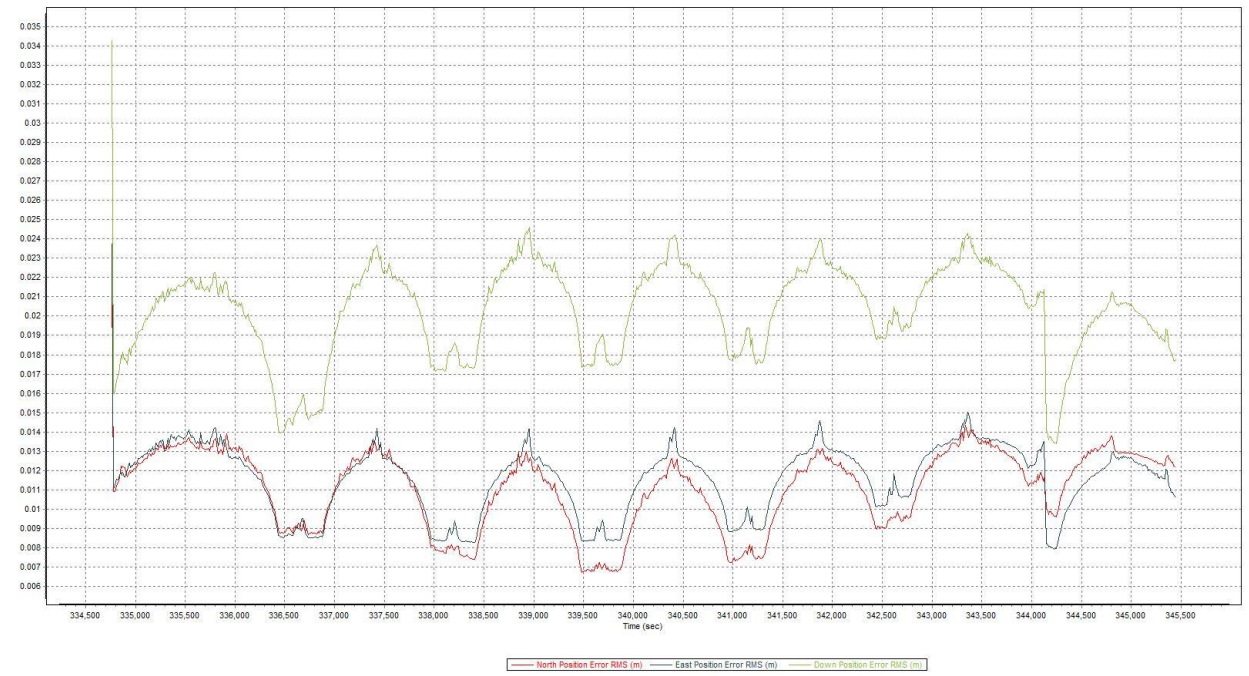
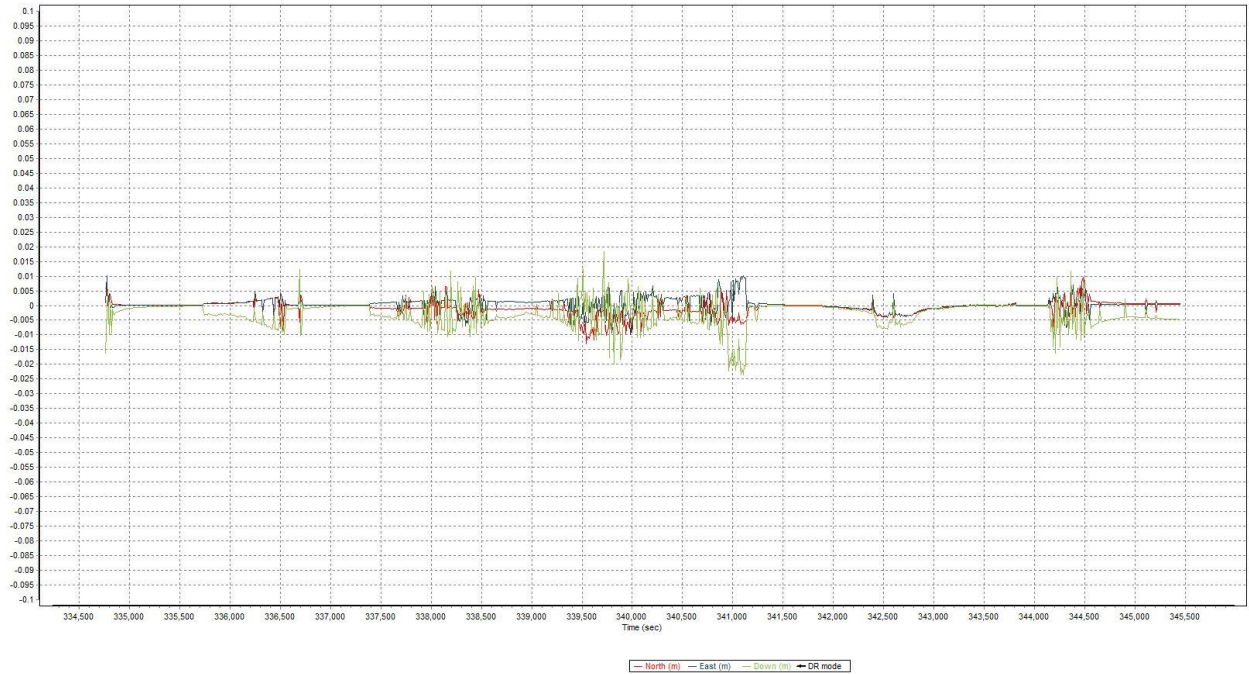
Forward  Reverse

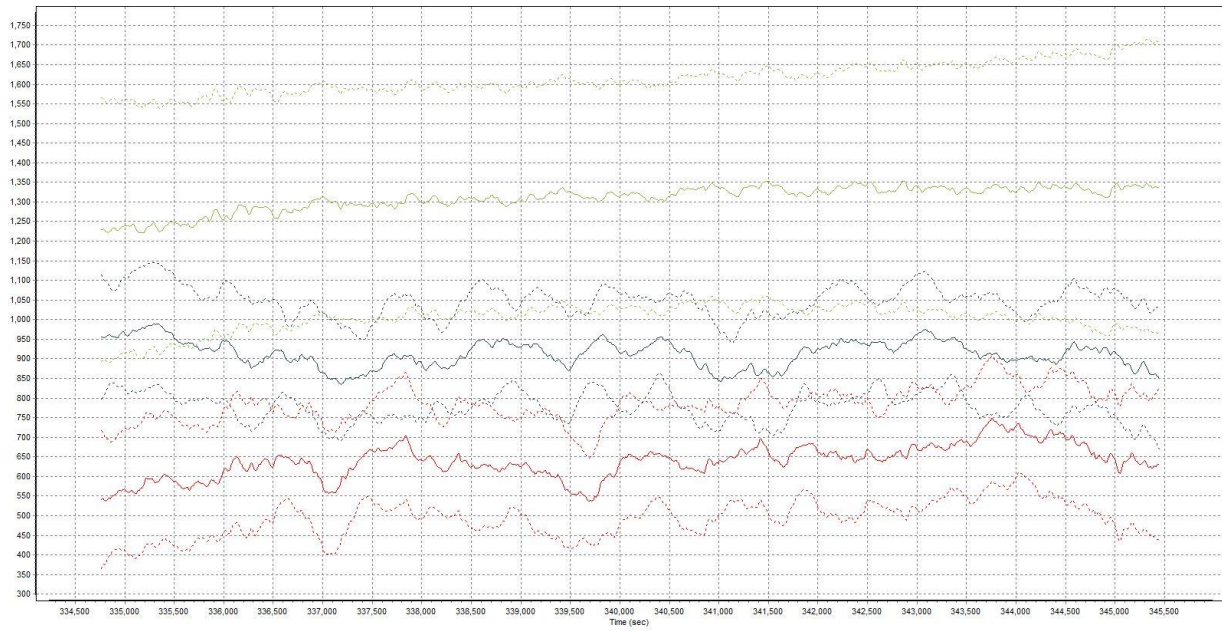
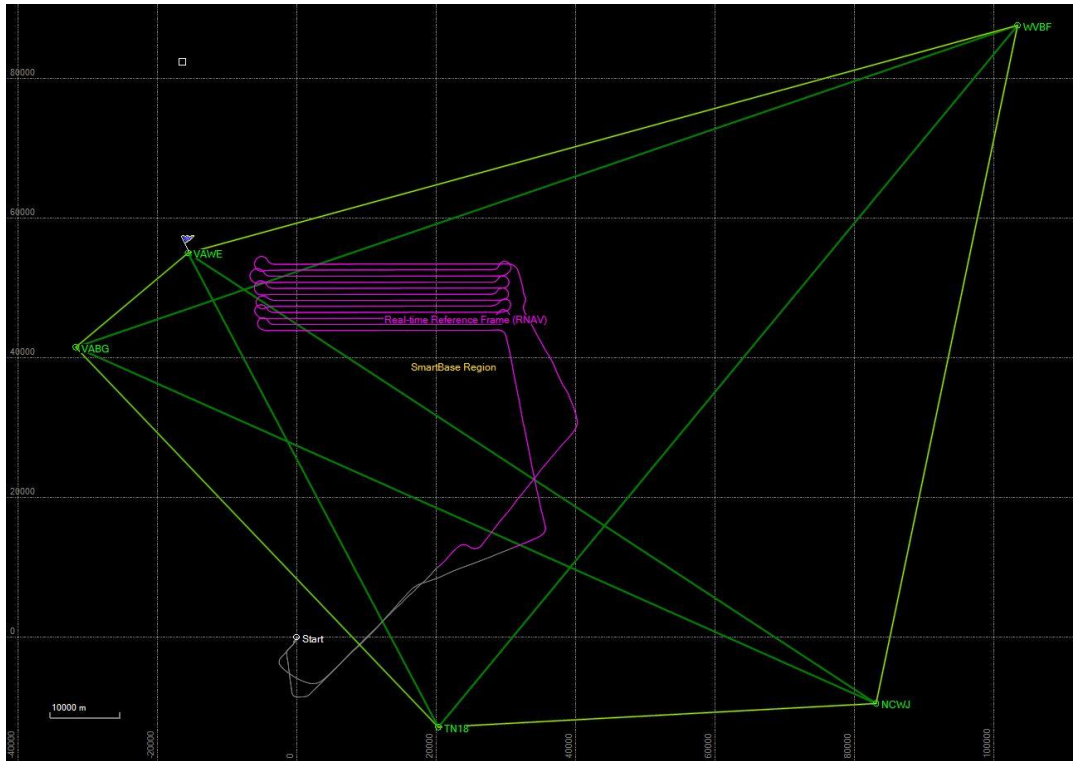
Processing mode



Forward  Reverse

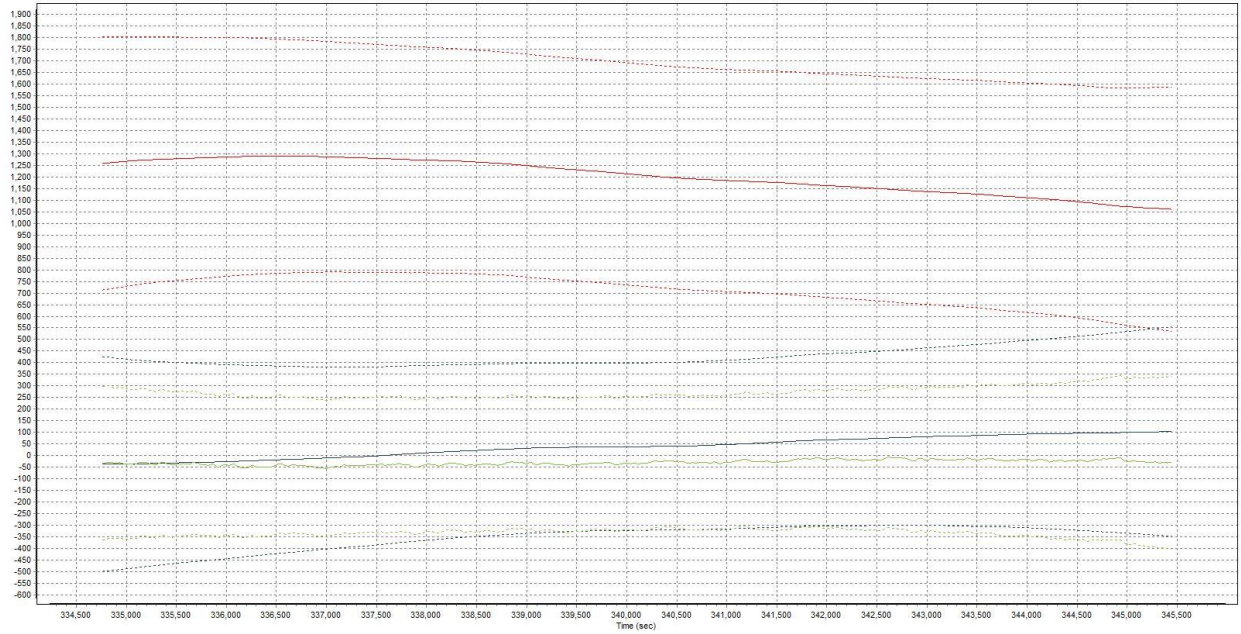
0 = Fixed NL, 1 = Fixed WL, 2 = Float, 3 = DGNSS, 4 = RTCM, 5 = IAPPP, 6 = CIA, 7 = GNSS Nav, 8 = DR



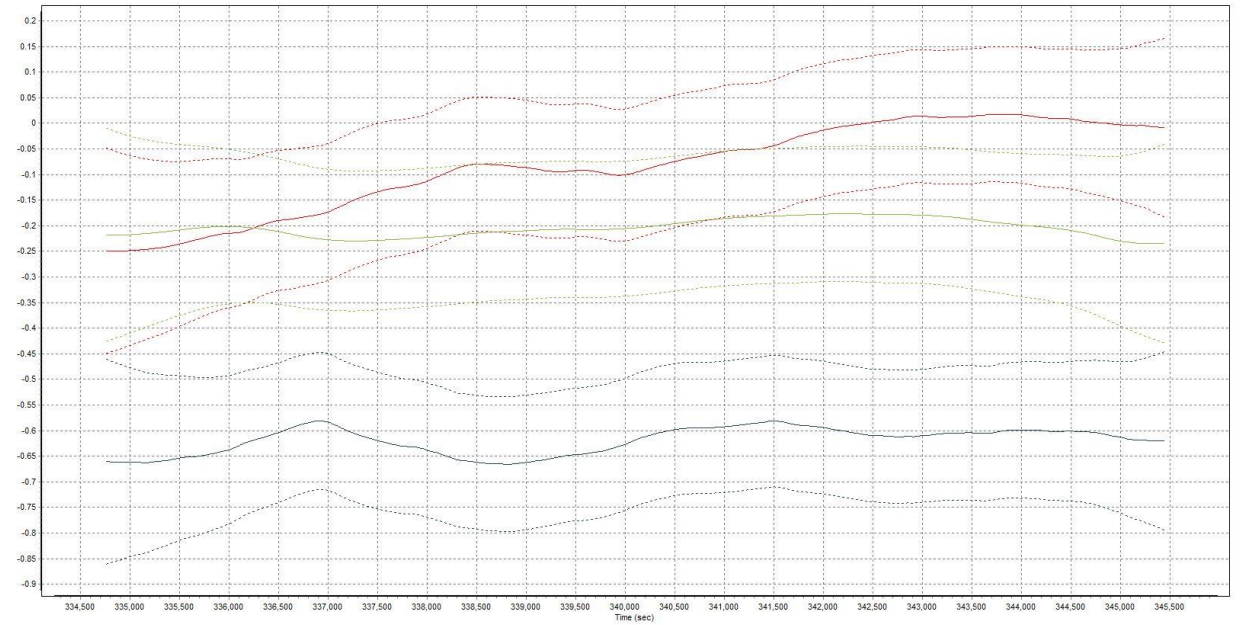


— x accelerometer bias (micro-g) — y accelerometer bias (micro-g) — z accelerometer bias (micro-g)

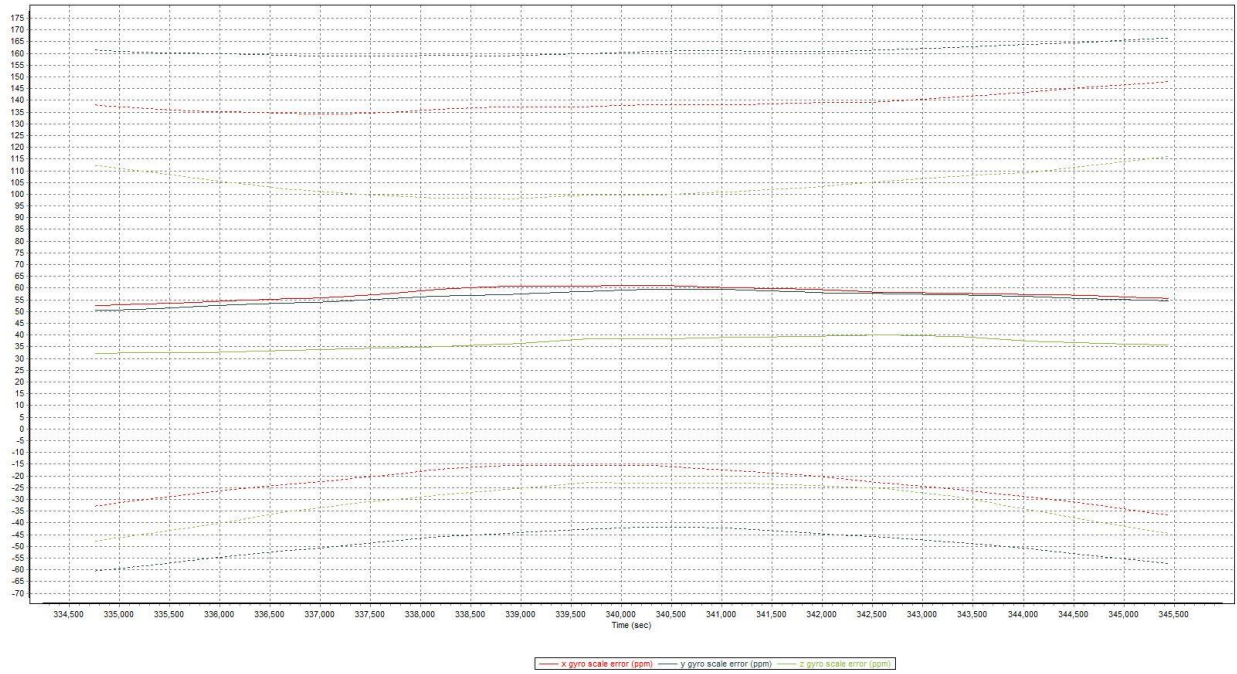




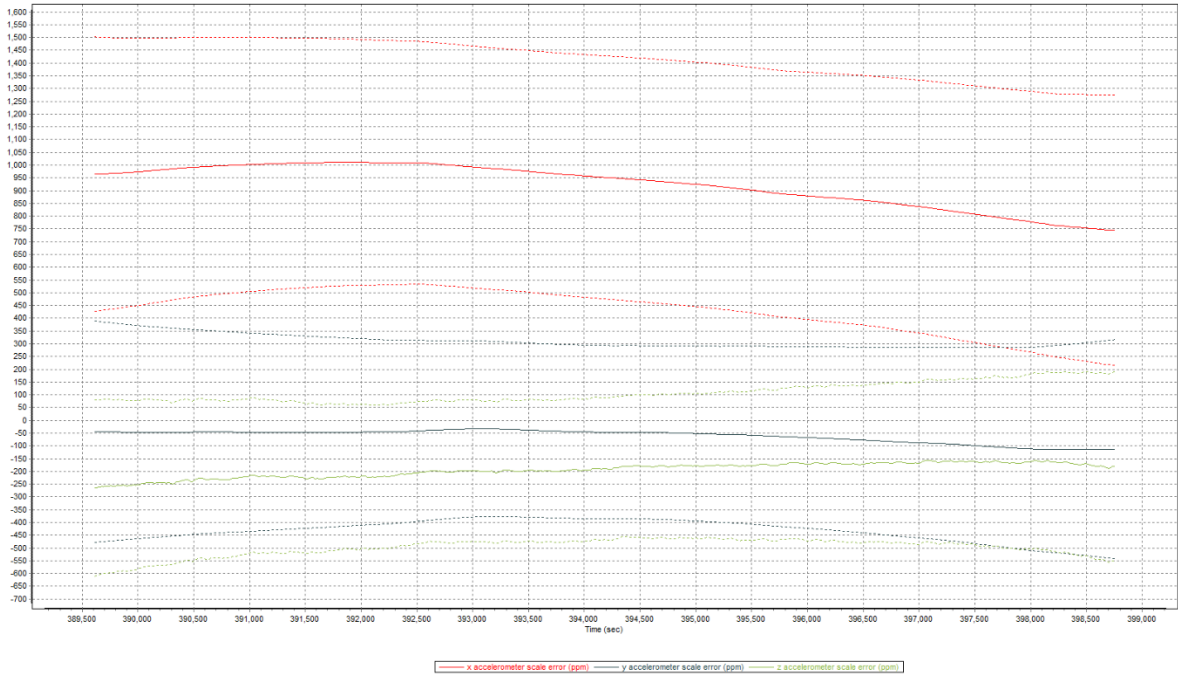
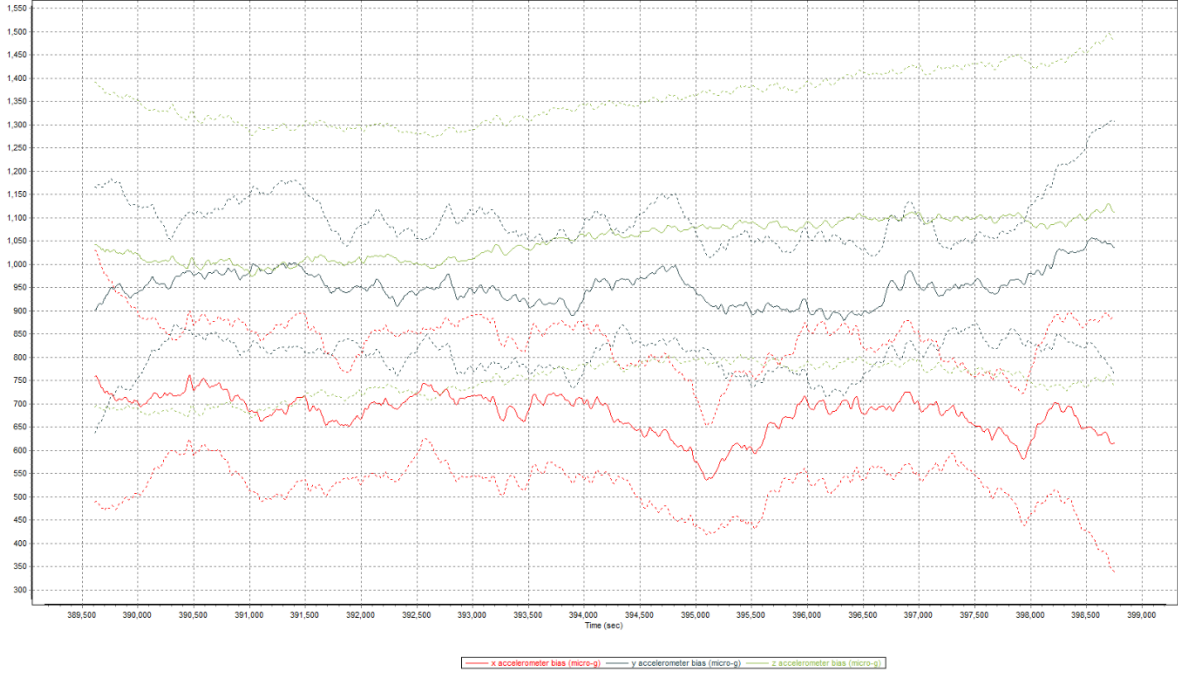
x accelerometer scale error (ppm) y accelerometer scale error (ppm) z accelerometer scale error (ppm)

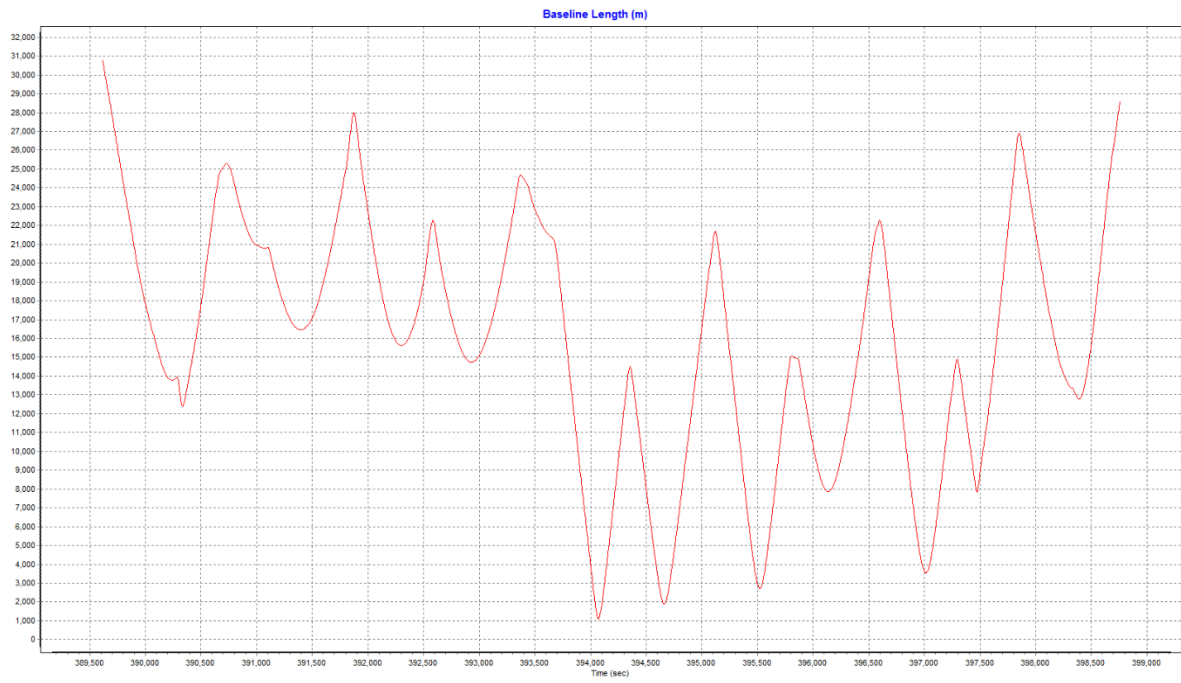
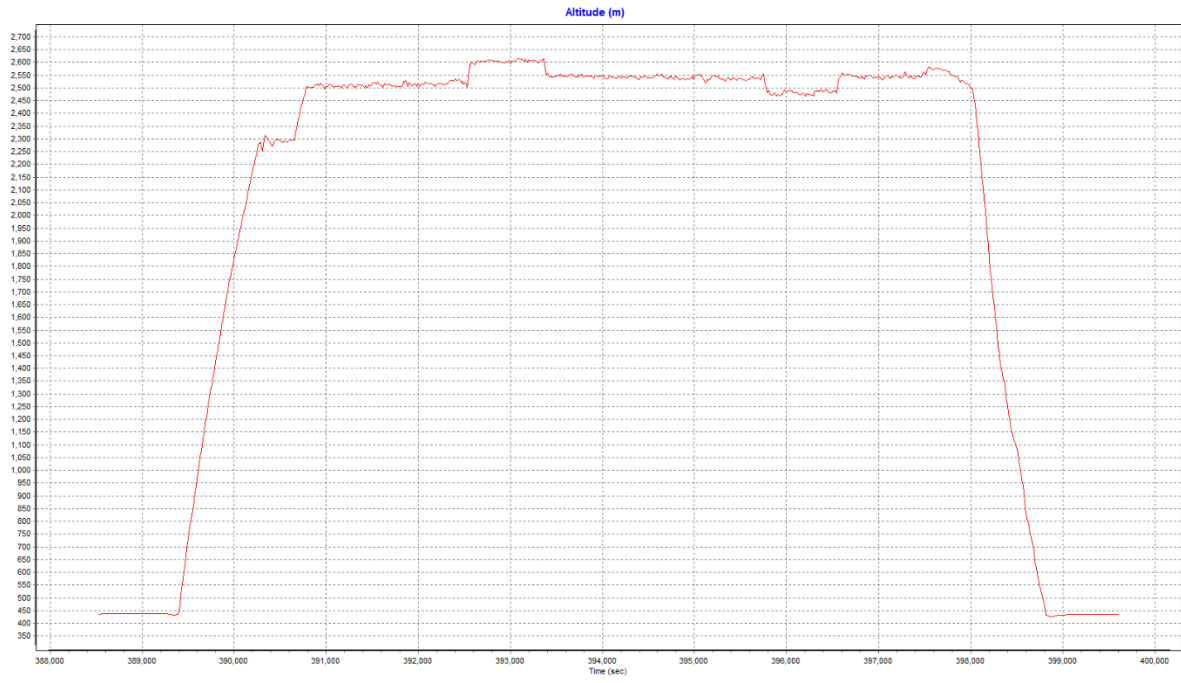


x gyro bias (deg/hr) y gyro bias (deg/hr) z gyro bias (deg/hr)

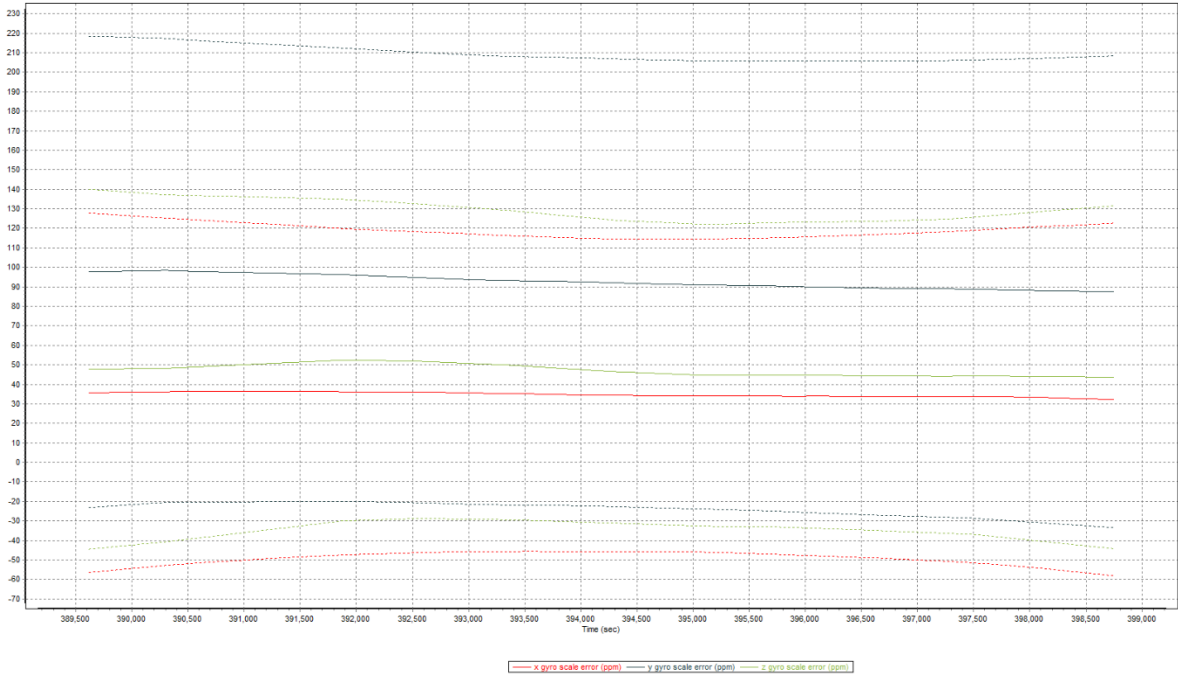


# UNB17103A

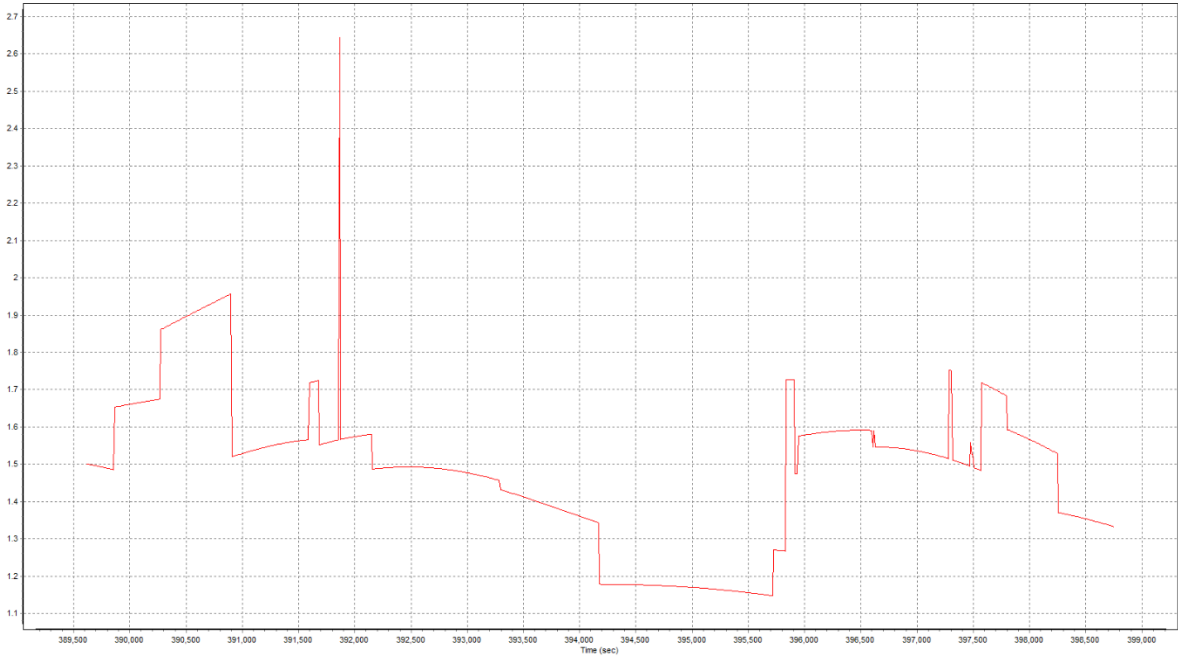


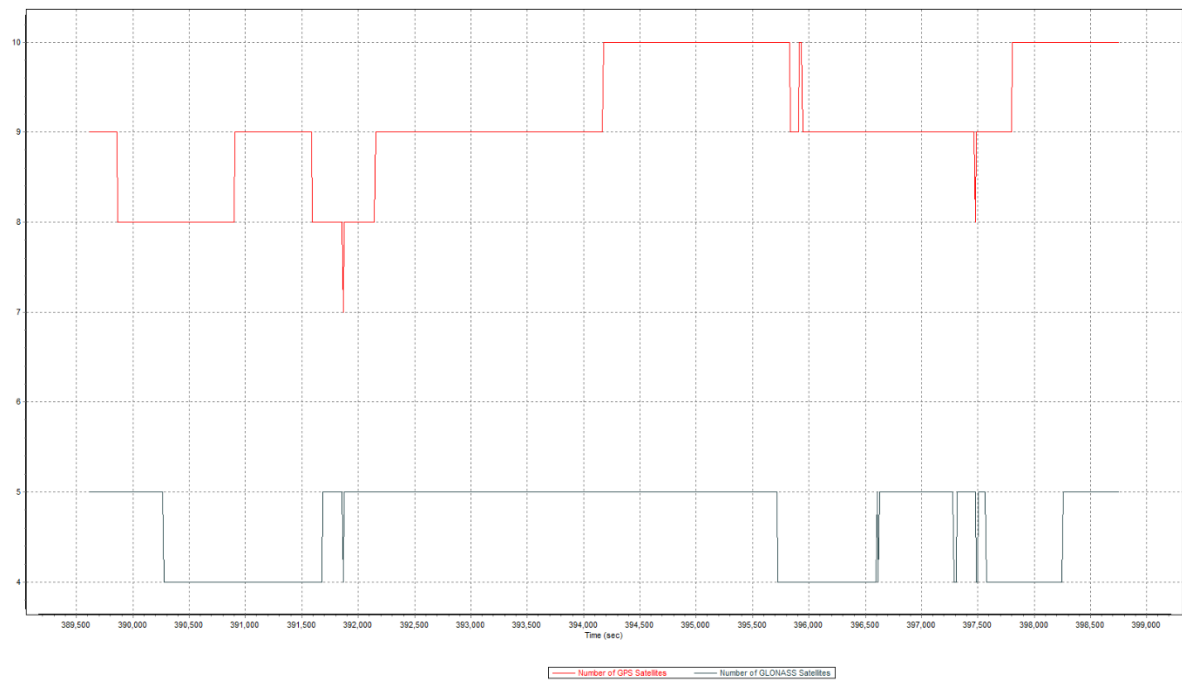
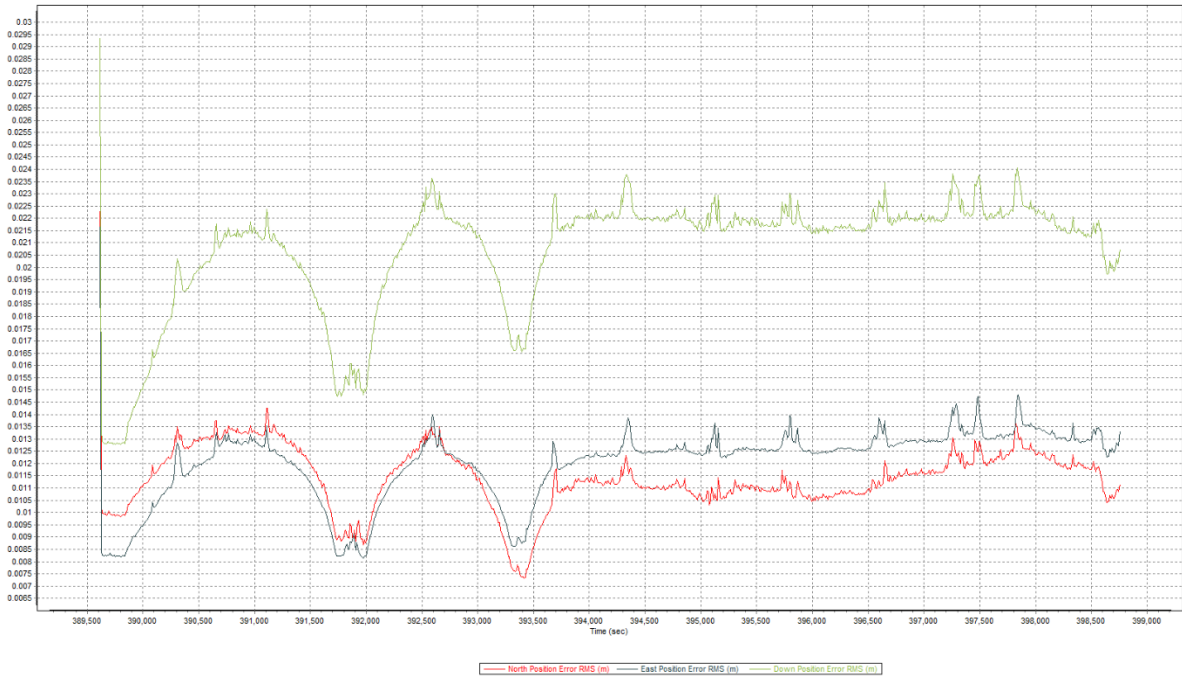


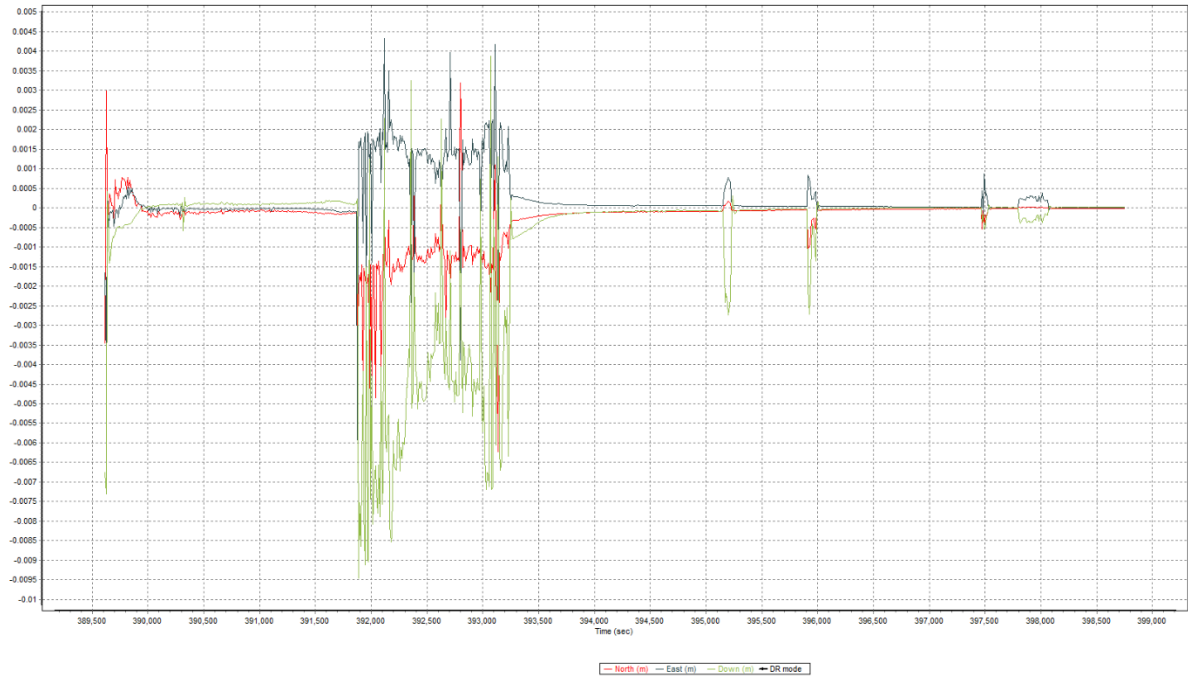




PDOP

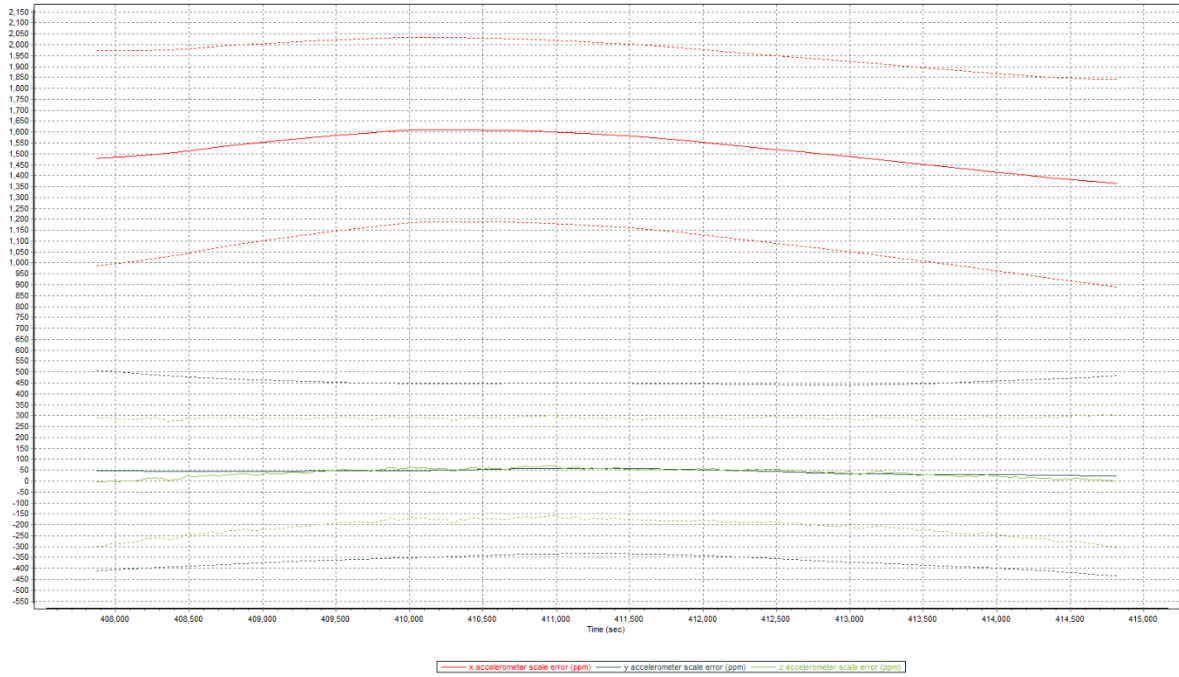
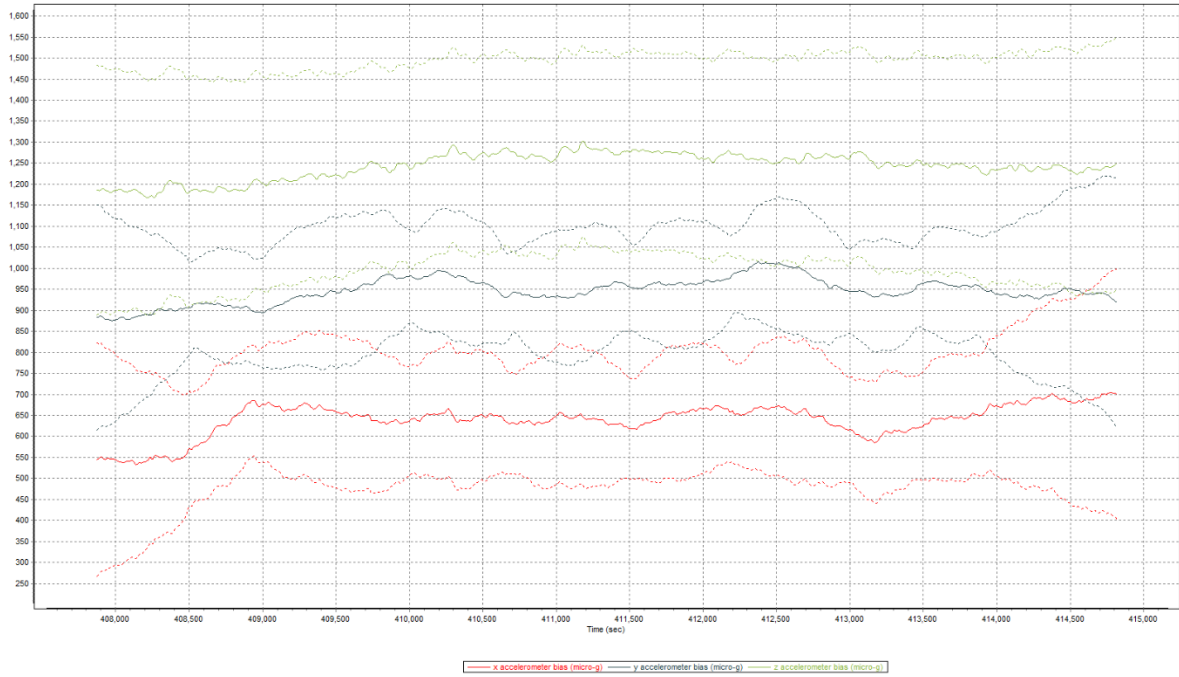


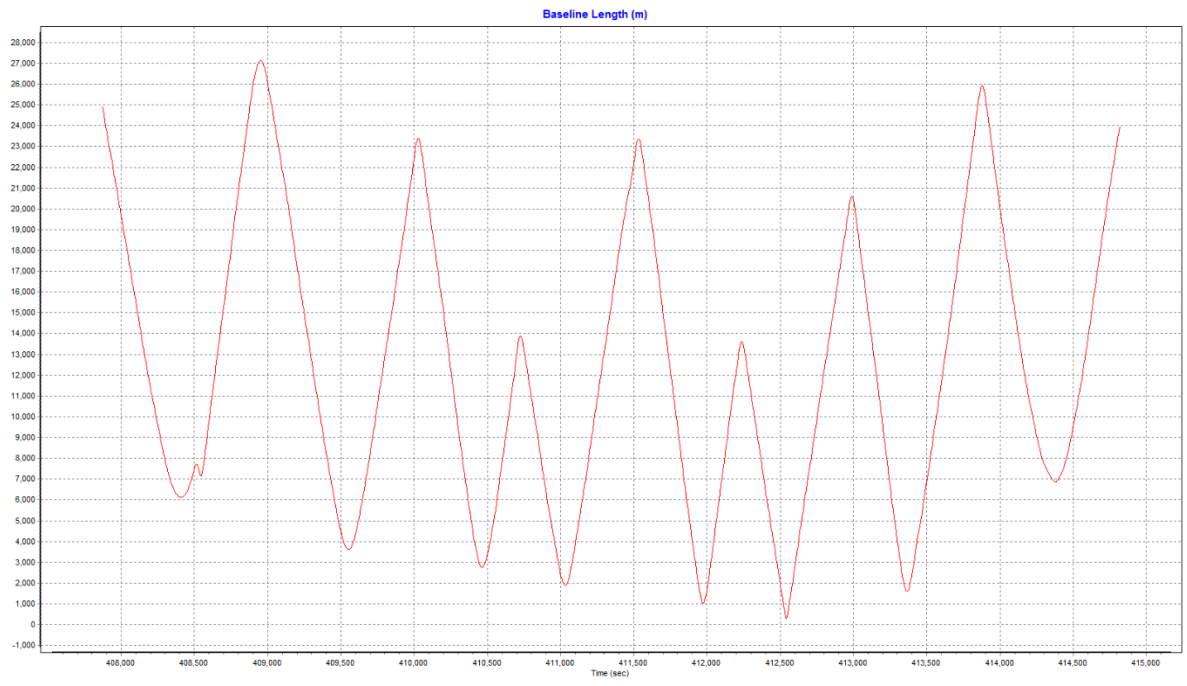


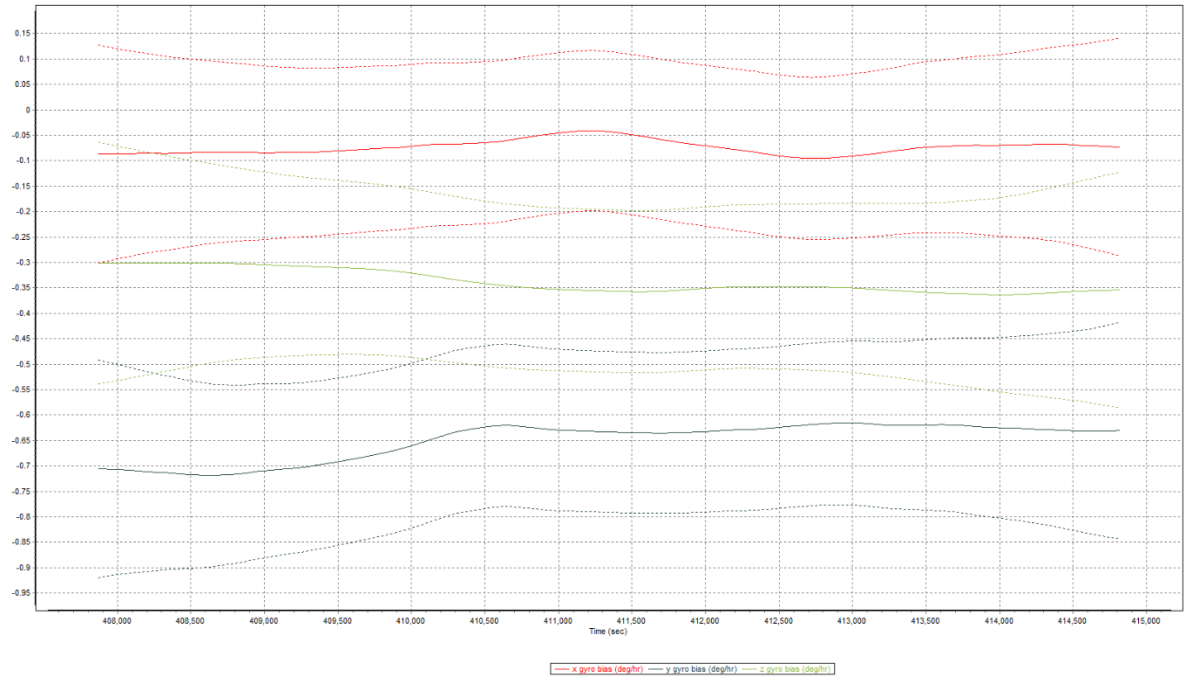
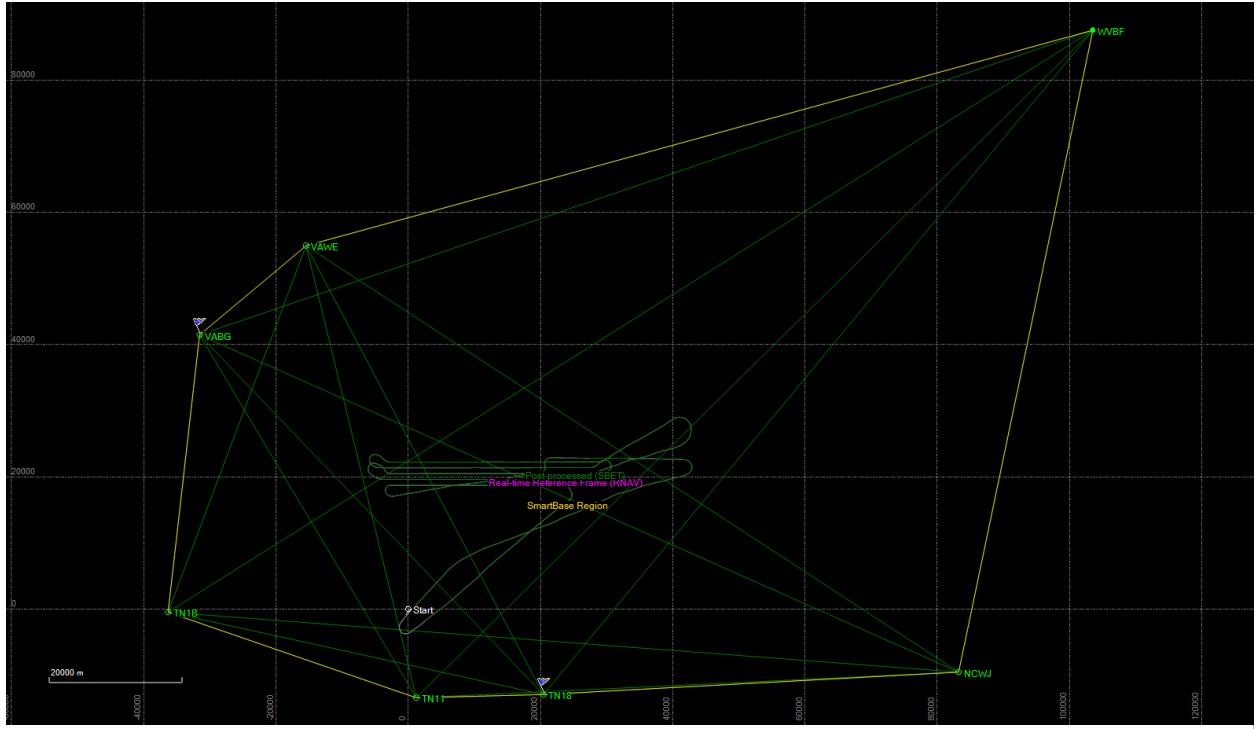


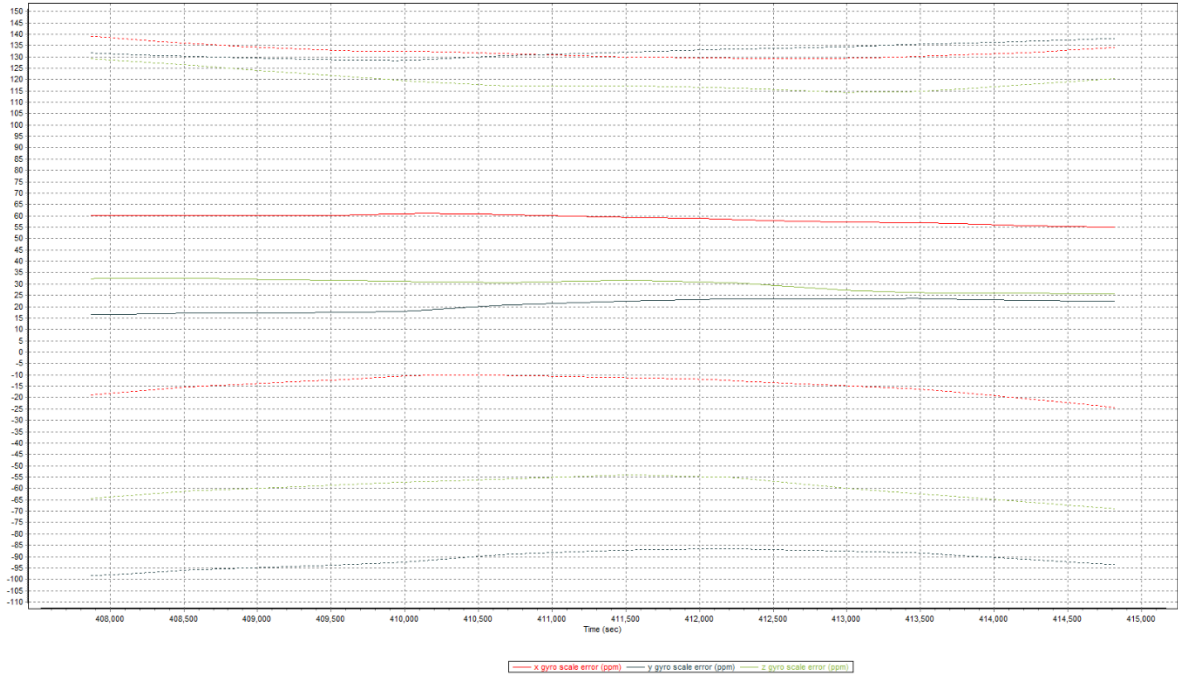


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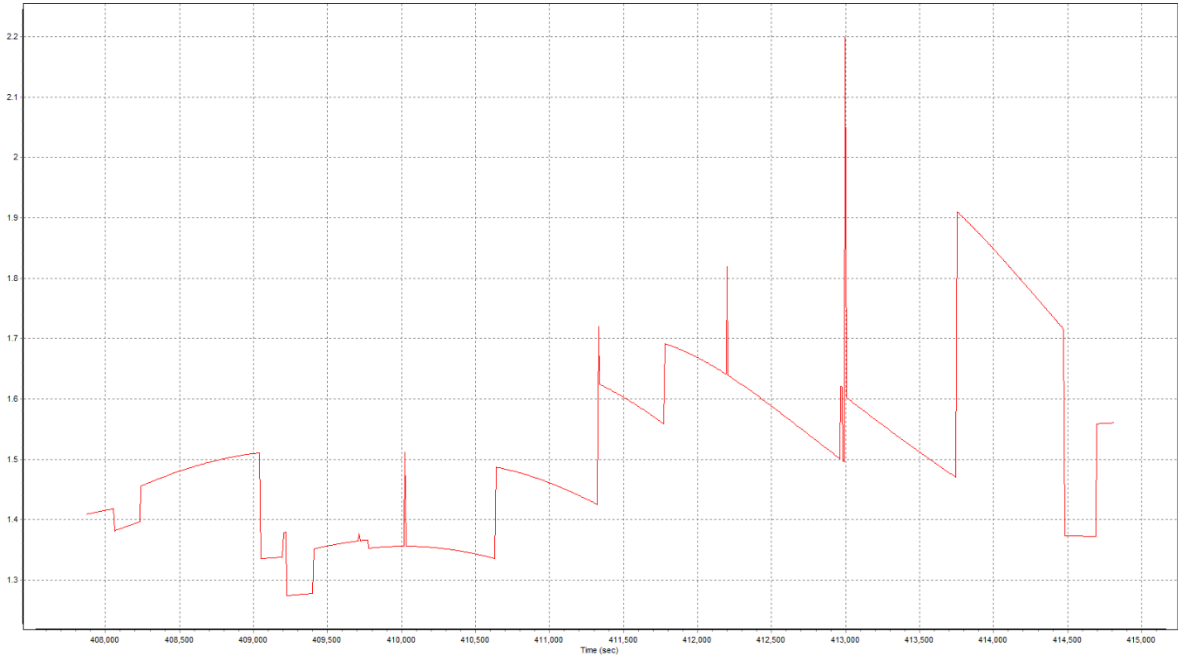


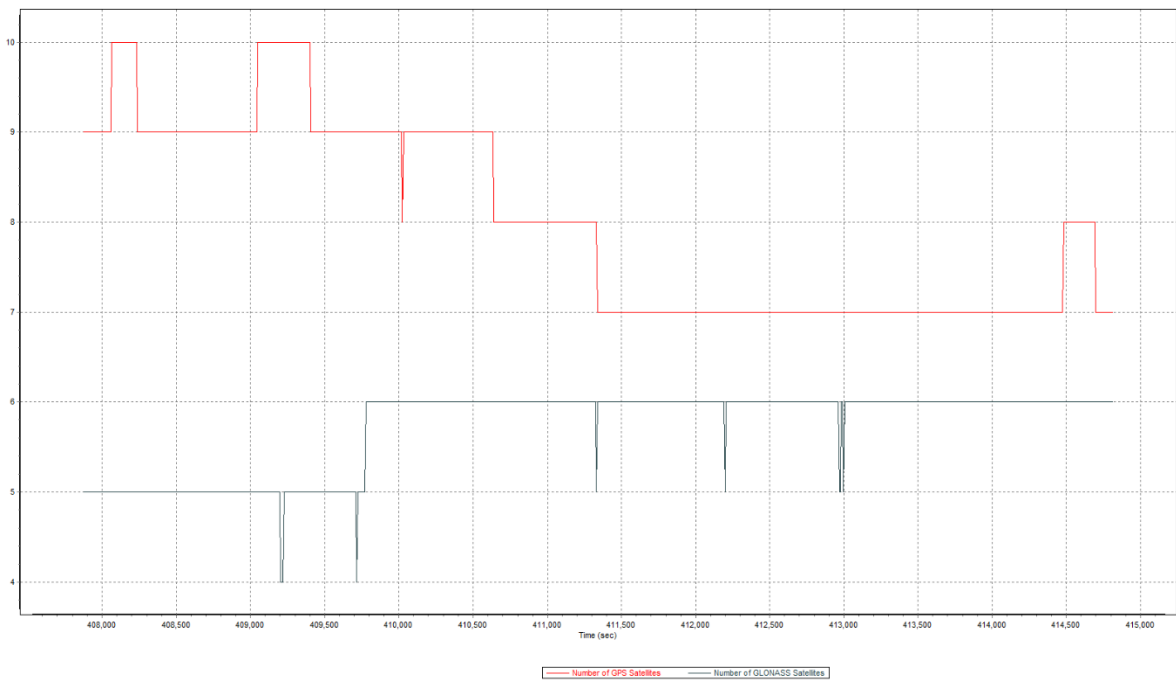
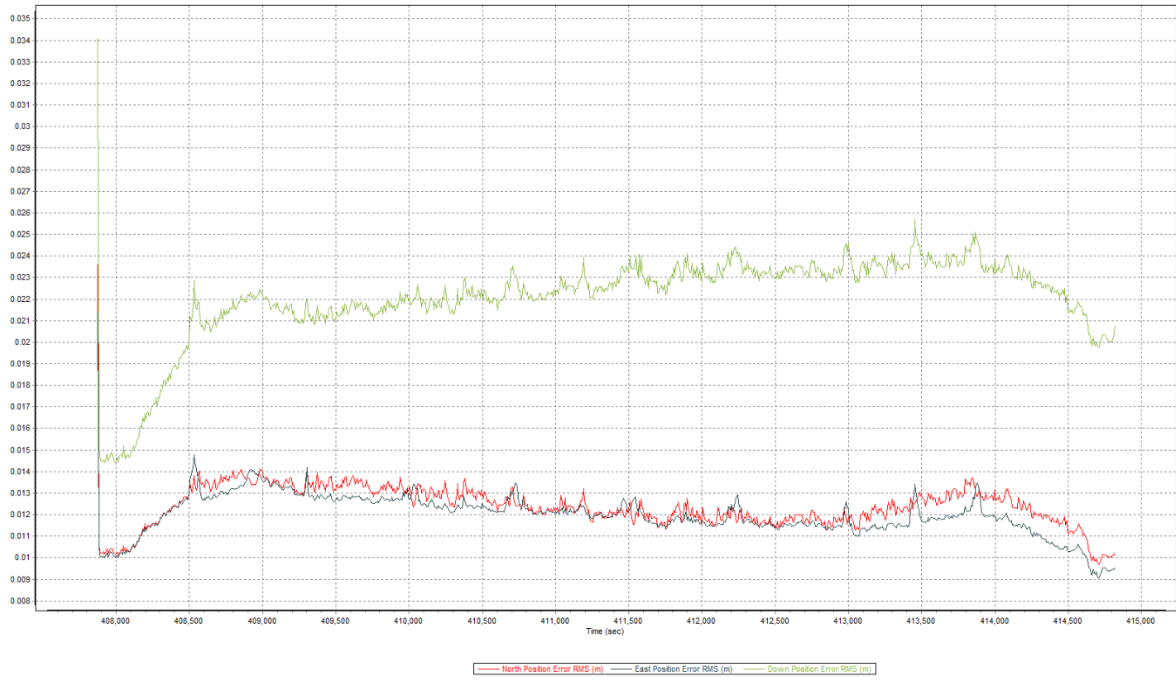


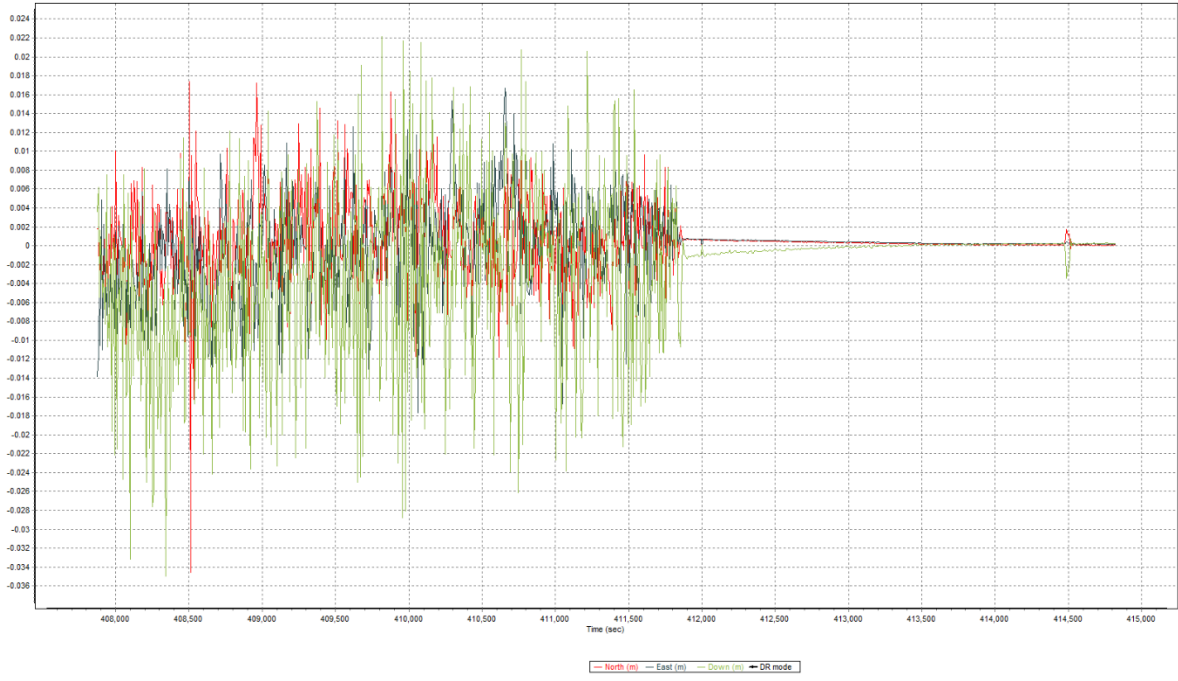




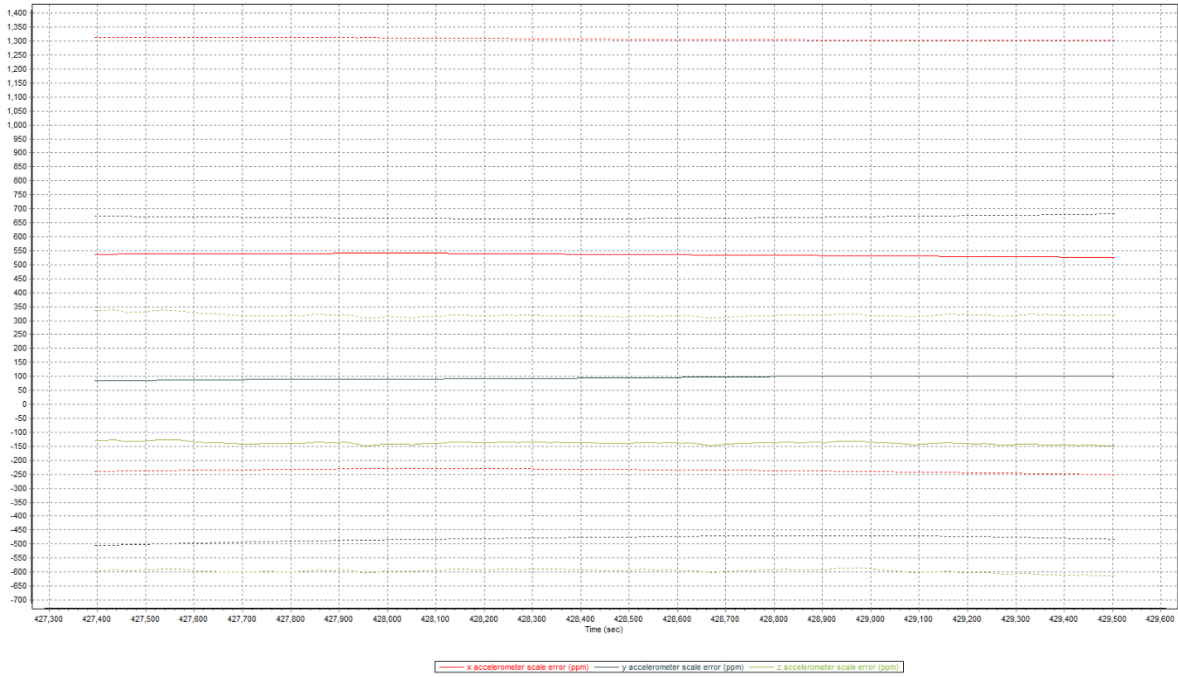
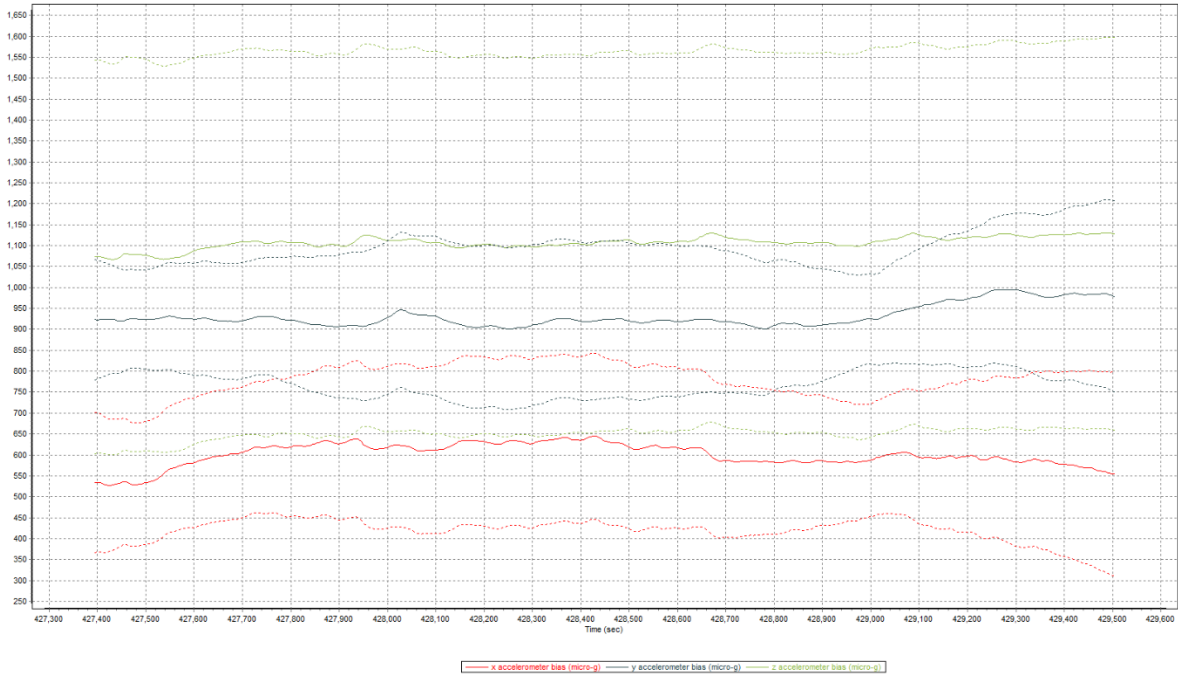
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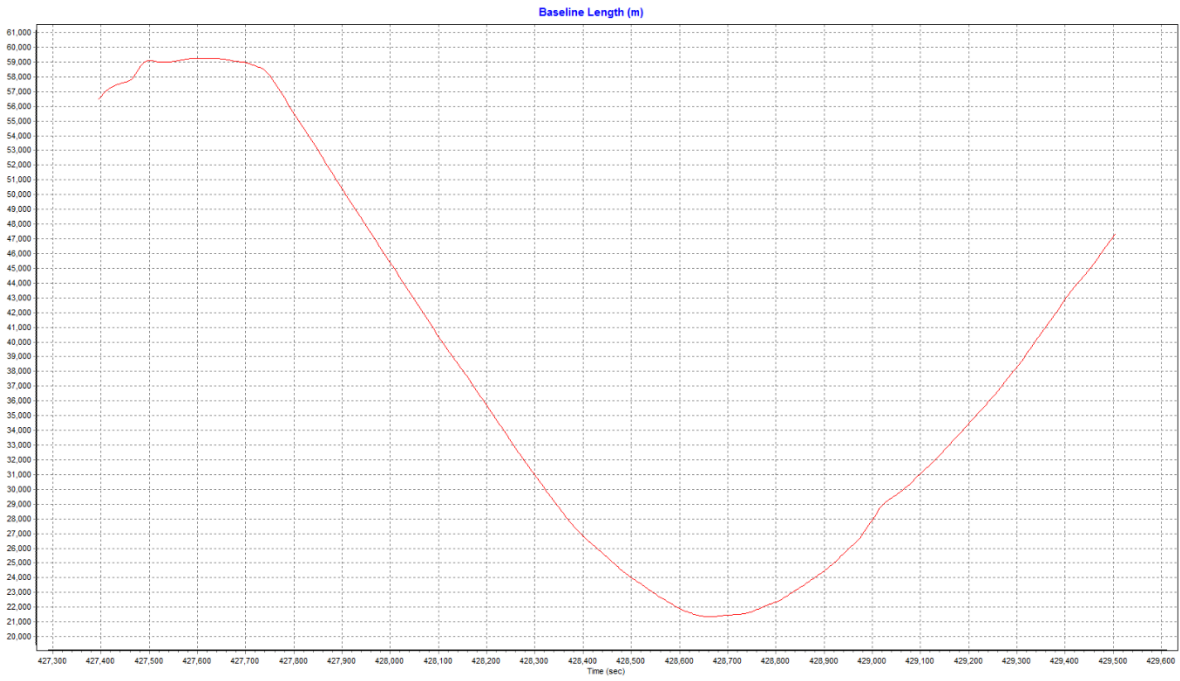
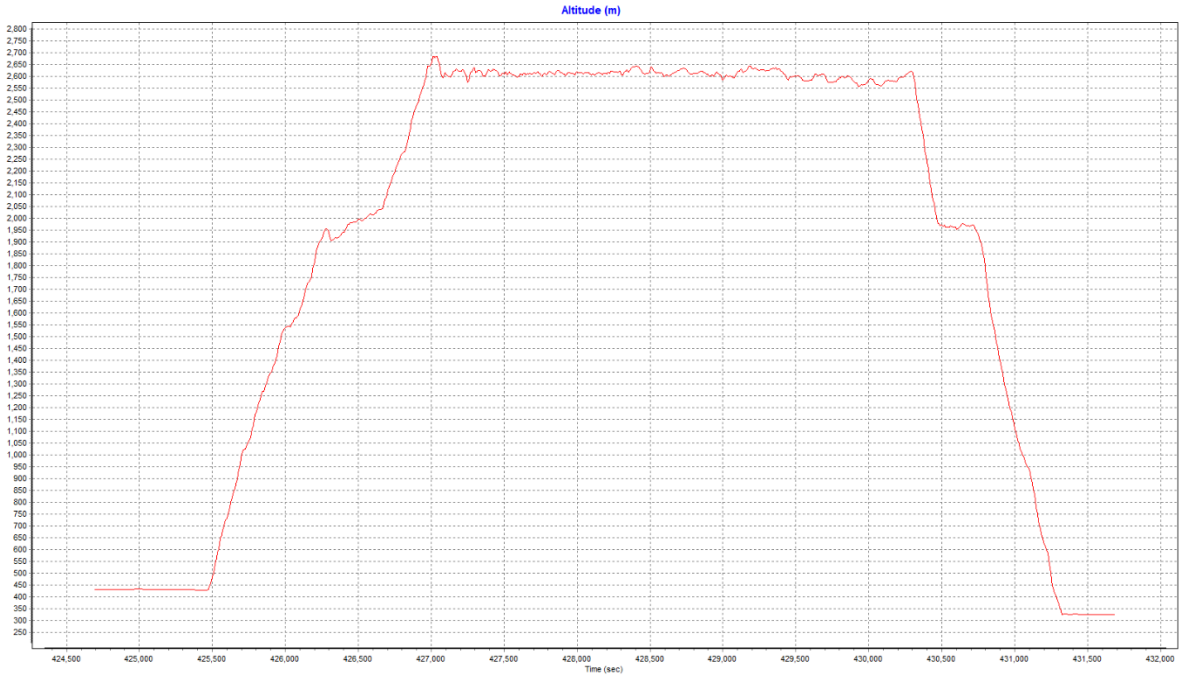




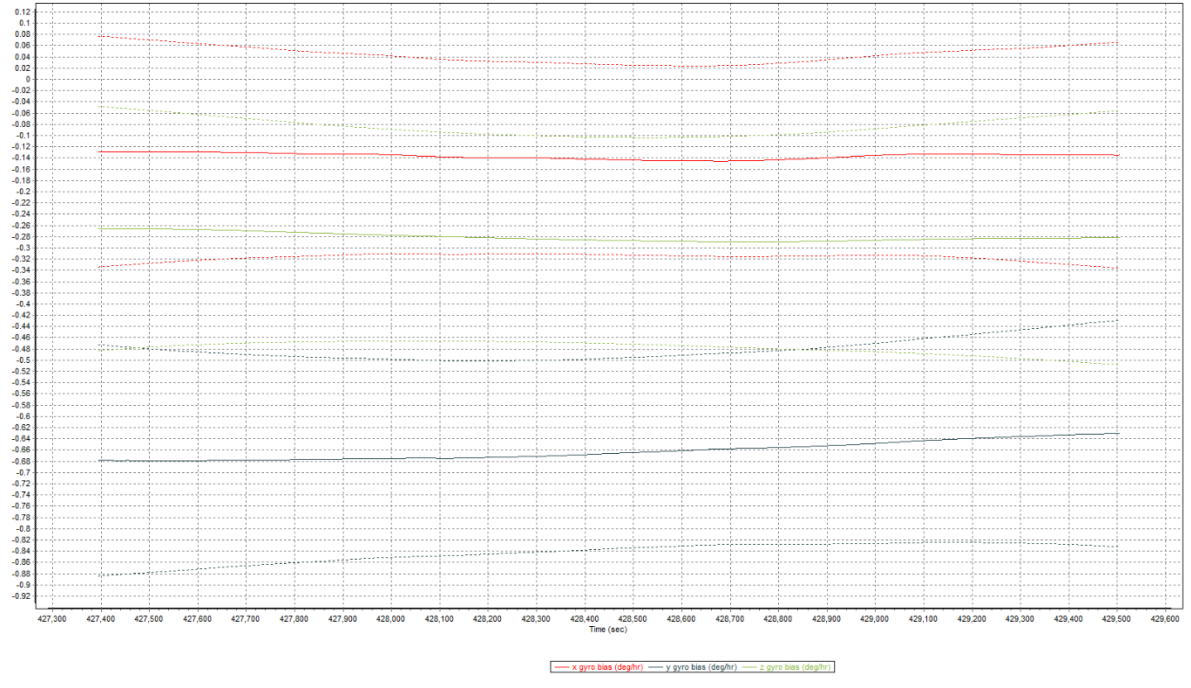
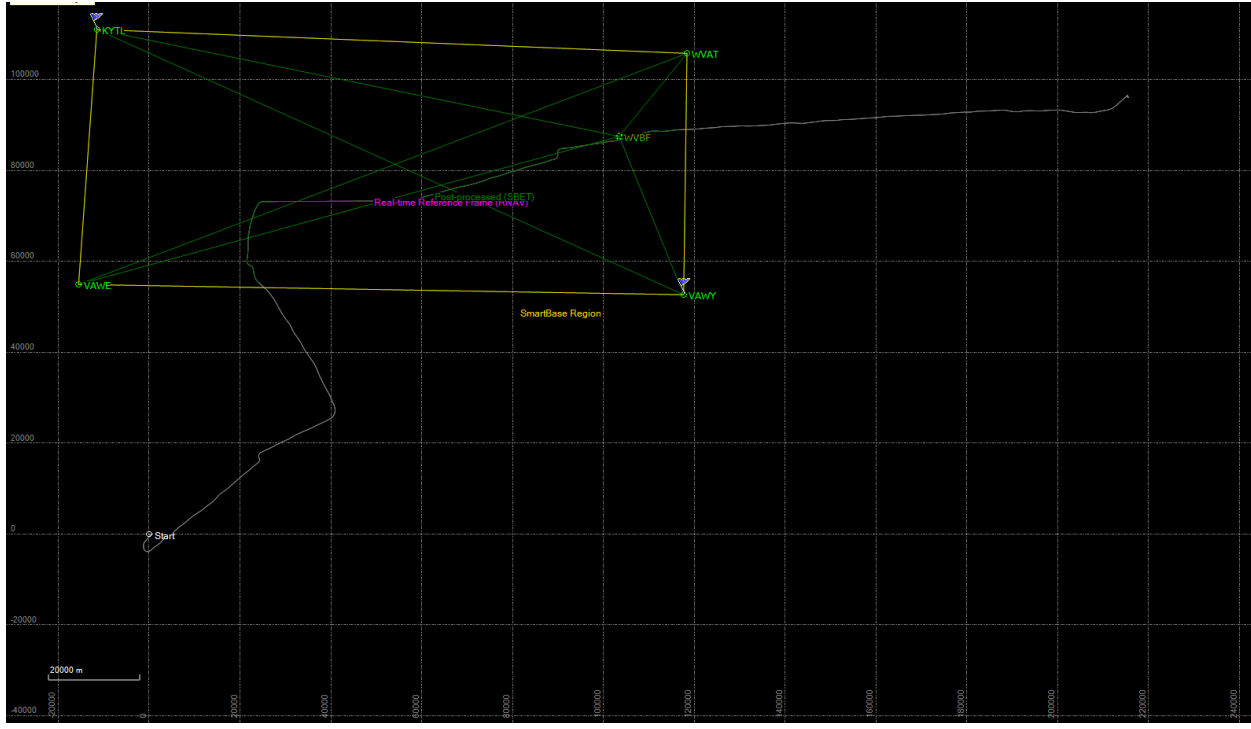


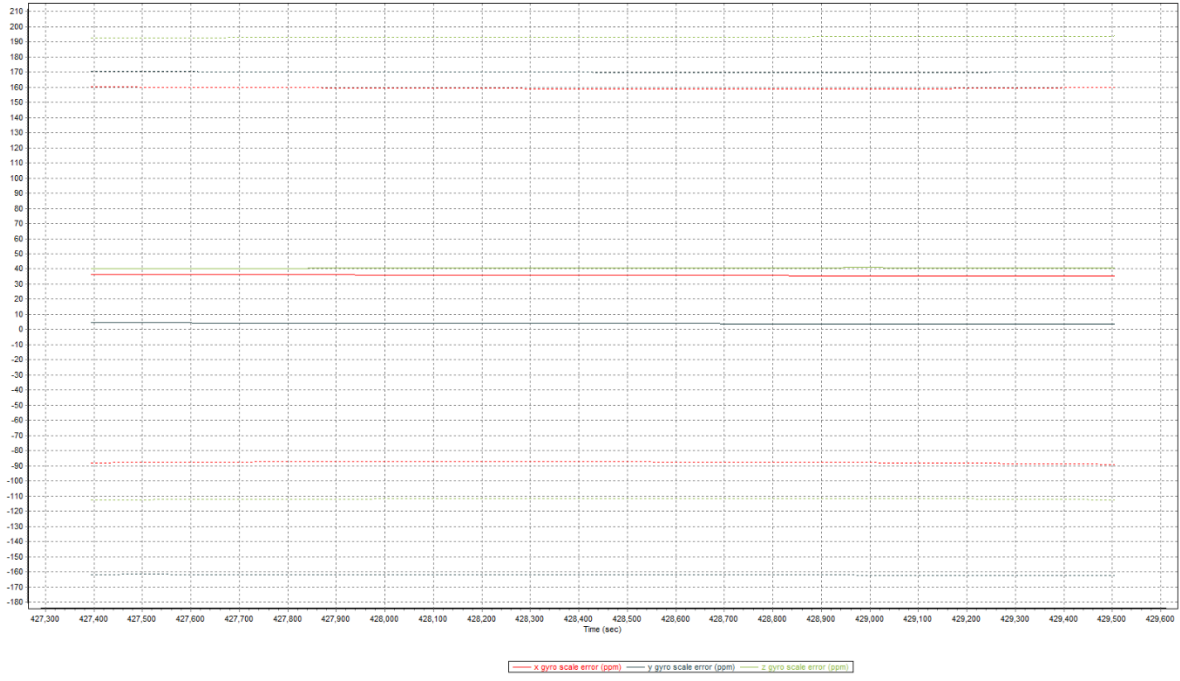
# UNB17103C











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